Estimation with Aggregate Shocks

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Abstract

Aggregate shocks affect most households’ and firms’ decisions. Using three stylized models we show that inference based on cross-sectional data alone generally fails to correctly account for decision making of rational agents facing aggregate uncertainty. We propose an econometric framework that overcomes these problems by explicitly parameterizing the agents’ inference problem relative to aggregate shocks. Our framework and examples illustrate that the cross-sectional and time-series aspects of the model are often interdependent. Therefore, estimation of model parameters in the presence of aggregate shocks requires the combined use of cross-sectional and time series data. We provide easy-to-use formulas for test statistics and confidence intervals that account for the interaction between the cross-sectional and time-series variation. Lastly, we perform Monte Carlo simulations that highlight the properties of the proposed method and the risks of not properly accounting for the presence of aggregate shocks.

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1 Introduction

An extensive body of economic research suggests that aggregate shocks have important effects on households’ and firms’ decisions. Consider for instance the oil shock that hit developed countries in 1973. A large literature has provided evidence that this aggregate shock triggered a recession in the United States, where the demand and supply of non-durable and durable goods declined, inflation grew, the unemployment rate increased, and real wages dropped.

The profession has generally adopted one of the following three strategies to deal with aggregate shocks. The most common strategy is to assume that aggregate shocks have no effect on households’ and firms’ decisions, and hence that aggregate shocks can be ignored. Almost all papers estimating discrete choice dynamic models or dynamic games are based on this premise. Examples include Keane and Wolpin (1997), Bajari, Bankard, and Levin (2007), and Eckstein and Lifshitz (2011). The second approach is to add time dummies to the model in an attempt to capture the effect of aggregate shocks on the estimation of the parameters of interest, as was done for instance in Runkle (1991) and Shea (1995). The last strategy is to fully specify how aggregate shocks affect individual decisions jointly with the rest of the structure of the economic problem. We are aware of only one paper that uses this strategy, Lee and Wolpin (2010).

The previous discussion reveals that there is no generally agreed upon econometric framework for estimation and statistical inference in models where aggregate shocks have an effect on individual decisions. This paper makes two main contributions related to this deficiency. We first provide a general econometric framework that can be used to evaluate the effect of aggregate shocks on estimation and statistical inference and apply it to three examples. The examples reveal which issues may arise if aggregate shocks are a feature of the data, but the researcher does not properly account for them. The examples also provide important insights on which econometric method can be employed in the estimation of model parameters when aggregate shocks are present. Using those insights, we propose a method based on a combination of cross-sectional variables and a long time-series of aggregate variables. There are no available formulas that can be used for statistical inference when those two data sources are combined. The second contribution of this paper is to provide simple-to-use formulas for test statistics and confidence intervals that can be employed when our proposed method is used.
We proceed in four steps. In Section 2, we introduce the generic identification problem by examining a general class of models with the following two features. First, each model in this class is composed of two submodels. The first submodel includes all the cross-sectional features, whereas the second submodel is composed of all the time-series aspects. As a consequence, the parameters of the model can also be divided into two groups: the parameters that characterize the cross-sectional submodel and the parameters that enter the time-series submodel. The second feature is that the two submodels are linked by a vector of aggregates shocks and by the parameters that govern their dynamics. Individual decision making thus depends on aggregate shocks.

Given the interplay between the two submodels, aggregate shocks have complicated effects on the estimation of the parameters of interest. To better understand those effects, in the second step, we present three examples of the general framework that illustrate the complexities generated by the existence of the aggregate shocks.

In Section 3, we consider as a first example a simple model of portfolio choice with aggregate shocks. The simplicity of the model enables us to clearly illustrate the effect of aggregates shocks on the estimation of model parameters and on their asymptotic distribution. Using the example, we first show that, if the econometrician does not account for uncertainty generated by aggregate shocks, the estimates of model parameters are biased and inconsistent. Our results also illustrate that the inclusion of time dummies generally does not correctly account for the existence of aggregate shocks. We then provide some insight on the sign of the bias. When aggregate uncertainty is ignored, agents in the estimated model appear more risk averse than they are. This is a way for the misspecified model to account for the uncertainty in the data that is not properly modeled. As a consequence, the main parameter in the portfolio model, the coefficient of risk aversion, is biased upward. Lastly, we show that a method based on a combination of cross-sectional and time-series variables produces unbiased and consistent estimates of the model parameters.

In Section 4, as a second example, we study the estimation of firms’ production functions when aggregate shocks affect firms’ decisions. This example shows that there are exceptional

\footnote{In the Euler equation context, Chamberlain (1984) considers a special example characterized by a nonstationary aggregate environment and time-varying nonstochastic preference shocks. Under this special environment, he shows that, when aggregate shocks are present but disregarded, the estimated parameters can be inconsistent even when time dummies are included. In this paper, we show that the presence of aggregate shocks produces inconsistent estimates if those shocks are ignores, even when time dummies are employed, in very general and realistic contexts and not only in the very special case adopted by Chamberlain (1984).}
cases where model parameters can be consistently estimated using only repeated cross-sections if time dummies are skillfully used rather than simply added as time intercepts. Specifically, our analysis indicates that the method proposed by Olley and Pakes (1996) fails to produce consistent estimates if aggregate shocks are present. It also indicates that the production functions can be consistently estimated if their method is modified with the proper inclusion of time dummies. The results of Section 4 are of independent interest since aggregate shocks have significant effects in most markets and the estimation of firms’ production functions is an important topic in industrial organization, see for instance Levinsohn and Petrin (2003) and Ackerberg, Caves, and Frazer (2015).

In Section 5 we present as our last example a general equilibrium model of education and labor supply decisions. The portfolio example has the quality of being simple. But, because of its simplicity, it generates a one-directional relationship between the time-series and cross-sectional submodels: the parameters of the cross-sectional model can be consistently estimated only if the parameters of the time-series model are known, but the time-series parameters can be consistently estimated without knowledge of cross-sectional parameters. However, this is not generally the case. In many situations, the link between the two submodels is bi-directional. The advantage of the general-equilibrium example is that it produces a bi-directional relationship we can use to illustrate the complexity of the effect of aggregate shocks on the estimation of the model parameters and on their asymptotic distribution. The general equilibrium example also illustrates how our method based on cross-sectional and time-series variables can be used to generate consistent estimates when the link between the two sub-models is bi-directional.

The examples make clear that in general consistent estimation of parameters in models with aggregate shocks is not feasible with only cross-sectional or time series data. They also clarify that a method based on the combination of cross-sectional variables and a long time-series of aggregate variables generates consistent estimates. Since there is no existing formula for the computation of the standard errors when those two data sources are combined, as the third step, in Section 6 we provide easy-to-use algorithms that can be employed to obtain test statistics and confidence intervals for parameters estimated using the proposed method. The underlying asymptotic theory, which is presented in the companion paper Hahn, Kuersteiner, and Mazzocco (2016), is highly technical due to the complicated interactions that exists between the two submodels. It is therefore
surprising that the formulas necessary to perform inference take simple forms that are easy to adopt. We conclude the section by illustrating, using the portfolio choice model and the general equilibrium model, how the formulas can be computed in specific cases.

Finally, to evaluate our econometric framework, we perform a Monte Carlo experiment for the general equilibrium model. The Monte Carlo results indicate that our method performs well when the length of the time-series is sufficiently large. In that case, the parameter estimates are statistically close to the true values and the coverage probabilities are statistically close to the nominal levels. To document biases that may arise from ignoring aggregate shocks and using only cross-sectional variation, we also estimate the model’s parameters under the incorrect assumption that the economy is not affected by aggregate shocks. Our results show that this form of misspecification can generate extremely large biases for the parameters that require both cross-sectional and longitudinal variation to be consistently estimated. For instance, we find that a parameter that is of considerable interest to economists, the coefficient of risk aversion, is between five and six times larger than the true value if aggregate shocks are ignored. This result is consistent with the intuition provided by the portfolio choice model. If aggregate shocks are ignored by the econometrician, agents in the model are estimated to be more risk averse than they are to account for the high degree of uncertainty present in the data.

In addition to the econometric literature that deals with inferential issues, our paper also contributes to a growing literature whose objective is the estimation of general equilibrium models. Some examples of papers in this literature are Heckman and Seldacek (1985), Heckman, Lochner, and Taber (1998), Lee (2005), Lee and Wolpin (2006), Gemici and Wiswall (2011), Gillingham, Iskhakov, Munk-Nielsen, Rust, and Schjerning (2015). Aggregate shocks are a natural feature of general equilibrium models. Without them those models have the unpleasant implication that all aggregate variables can be fully explained by observables and, hence, that errors have no effects on those variables. Our general econometric framework makes this point clear by highlighting the impact of aggregate shocks on parameter estimation and the variation required in the data to estimate those models. More importantly, our results provide easy-to-use formulas that can be employed to perform statistical inference in a general equilibrium context.

A separate discussion is required for the paper by Lee and Wolpin (2006). That paper is the only one that estimates a model that fully specifies how aggregate shocks affect individual
decisions. Using that approach, the authors can obtain consistent estimates of the parameters of interest. Their paper is primarily focused on the estimation of a specific empirical model. They do not address the broader question of which statistical assumptions and what type of data requirements are needed more generally to obtain consistent estimators when aggregate shocks are present, which is the focus of this paper. Moreover, as we argue later on, in Lee and Wolpin’s (2010) paper there are issues with statistical inference and efficiency.

2 The General Identification Problem

This section introduces the identification problem generated by the existence of aggregate shocks in general terms. We consider a class of models with three main features. First, the model can be divided into two parts. The first part encompasses all the aspects of the model that can be analyzed using cross-sectional variables and will be denoted with the term cross-sectional submodel. The second part includes aspects whose examination requires time-series variables and will be denoted with the term time-series submodel. Second, the two submodels are linked by the presence of a vector of aggregate shocks $\nu_t$ and by the parameters that govern their dynamics. The vector of aggregate shocks may not be observed. If that is the case, it is treated as a set of parameters to be estimated. Lastly, the parameters of the model can be consistently estimated only if a combination of cross-sectional and time-series data are available, which is the case for many interesting models with aggregate shocks.

We now formally introduce the general model. It consists of two distinct vectors of variables $y_{i,t}$ and $z_s$. The first vector $y_{i,t}$ includes all the variables that characterize the cross-sectional submodel, where $i$ describes an individual decision-maker, a household or a firm, and $t$ a time period in the cross-section. The second vector $z_s$ is composed of all the variables associated with the time-series model. Accordingly, the parameters of the general model can be divided into two sets, $\beta$ and $\rho$. The first set of parameters $\beta$ characterizes the cross-sectional submodel, in the sense that, if the second set $\rho$ was known, $\beta$ and $\nu_t$ can be consistently estimated using exclusively variation in the cross-sectional variables $y_{i,t}$. Similarly, the vector $\rho$ characterizes the time-series

\footnote{Even if the time subscript $t$ is not necessary in this subsection, we keep it here for notational consistency because later we consider the case where longitudinal data are collected.}
submodel meaning that, if $\beta$ were known, those parameters can be consistently estimated using exclusively the time series variables $z_s$. There are two functions that relate the cross-sectional and time-series variables to the parameters. The function $f(y_{i,t} | \beta, \nu_t, \rho)$ restricts the behavior of the cross-sectional variables conditional on a particular value of the parameters. Analogously, the function $g(z_s | \beta, \rho)$ describes the behavior of the time-series variables for a given value of the parameters. An example is a situation in which (i) the variables $y_{i,t}$ for $i = 1, \ldots, n$ are i.i.d. given the aggregate shock $\nu_t$, (ii) the variables $z_s$ correspond to $(\nu_s, \nu_{s-1})$, (iii) the cross-sectional function $f(y_{i,t} | \beta, \nu_t, \rho)$ denotes the log likelihood of $y_{i,t}$ given the aggregate shock $\nu_t$, and (iv) the time-series function $g(z_s | \beta, \rho) = g(\nu_s | \nu_{s-1}, \rho)$ is the log of the conditional probability density function of the aggregate shock $\nu_s$ given $\nu_{s-1}$. In this special case the time-series function $g$ does not depend on the cross-sectional parameters $\beta$.

We assume that our cross-sectional data consist of $\{y_{i,t}, i = 1, \ldots, n\}$, and our time series data consist of $\{z_s, s = \tau_0 + 1, \ldots, \tau_0 + \tau\}$. For simplicity, we assume that $\tau_0 = 0$ in this section.

The parameters of the general model can be estimated by maximizing a well-specified objective function. Since in our case the general framework is composed of two submodels, a natural approach is to estimate the parameters of interest by maximizing two separate objective functions, one for the cross-sectional model and one for the time-series model. We denote these criterion functions by $F_n(\beta, \nu_t, \rho)$ and $G_\tau(\beta, \rho)$. In the case of maximum likelihood these functions are simply $F_n(\beta, \nu_t, \rho) = \frac{1}{n} \sum_{i=1}^{n} f(y_{i,t} | \beta, \nu_t, \rho)$ and $G_\tau(\beta, \rho) = \frac{1}{\tau} \sum_{s=1}^{\tau} g(z_s | \beta, \rho)$. Another scenario where separate criterion functions arise naturally is when $f$ and $g$ represent moment conditions. The use of two separate objective functions is helpful in our context because it enables us to discuss which issues arise if only cross-sectional variables or only time-series variables are used in the estimation. Moreover, considering the two components separately adds flexibility since data are not required for all variables in the same period.

In this paper, we consider the class of models for which identification of the parameters requires the joint use of cross-sectional and time-series data. Specifically, for any fixed and feasible value of $\rho$ the maximum of the objective function $F$ over the parameters $\beta$ and the aggregate shocks $\nu$ remains unchanged and independent of the value of $\rho$. The parameter $\rho$ can therefore not be identified using only cross-sectional variation. Similarly, the objective function $G$ of the time-series model evaluated at the time-series parameters and aggregate shocks takes the same value for any
feasible set of cross-sectional parameters. Consequently, the parameters $\beta$ cannot be identified using only time-series variation. In our class of models, however, all the parameters of interest can be consistently estimated if cross-sectional data are combined with time-series data.

In the next three sections, we use three examples to illustrate the effects of aggregate shocks on the estimation of model parameters and the method we propose to address the issues generated by the presence of those shocks.

3 Example 1: Portfolio Choice

We start with a simple portfolio choice example that clearly illustrates the perils of ignoring aggregate shocks. Using this example, we make the following points. First, the presence of aggregate shocks generally produces estimates that are biased and inconsistent unless the econometrician properly accounts for the uncertainty generated by the aggregate shocks. Second, the use of time dummies generally does not solve the problems generated by the existence of aggregate shocks. Third, if the researcher does not account for the aggregate shocks, the parameter estimates will adjust to make the model consistent with the aggregate uncertainty that is present in the data but not modeled, hence the bias. For instance, in a model with risk averse agents such as our portfolio example, ignoring the aggregate shocks produces estimates of the risk aversion parameter that are upward biased.

Consider an economy that, in each period $t$, is populated by $n$ households. These households are born at the beginning of period $t$, live for one period, and are replaced in the next period by $n$ new families. The households living in consecutive periods do not overlap and, hence, make independent decisions. Each household is endowed with deterministic income and has preferences over a non-durable consumption good $c_{i,t}$. The preferences can be represented by Constant Absolute Risk Aversion (CARA) utility functions which take the following form: $U(c_{i,t}) = -e^{-\delta c_{i,t}}$. For simplicity, we normalize income to be equal to 1.

During the period in which households are alive, they can invest a share of their income in a

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3Our models assume rational expectations. We do not consider examples that incorporate model uncertainty, i.e., the possibility that agents need to learn or estimate model parameters when making decisions. We restrict our attention to rational expectation models because there is only a limited number of papers that consider self-confirming equilibria or robust control. See Cho, Sargent, and Williams (2002) or Hansen, Sargent, and Tallarini (1999). This is, however, an important topic that we leave for future research.
risky asset with return $u_{i,t}$. The remaining share is automatically invested in a risk-free asset with a return $r$ that does not change over time. At the end of the period, the return on the investment is realized and households consume the quantity of the non-durable good they can purchase with their realized income. The return on the risky asset depends on aggregate shocks. Specifically, it takes the following form: $u_{i,t} = \nu_t + \epsilon_{i,t}$, where $\nu_t$ is the aggregate shock and $\epsilon_{i,t}$ is an i.i.d. idiosyncratic shock. The idiosyncratic shock, and hence the heterogeneity in the return on the risky asset, can be interpreted as differences across households in transaction costs, in information on the profitability of different stocks, or in marginal tax rates. We assume that $\nu_t \sim N(\mu, \sigma_\nu^2)$, $\epsilon_{i,t} \sim N(0, \sigma_\epsilon^2)$, and hence that $u_{i,t} \sim N(\mu, \sigma^2)$, where $\sigma^2 = \sigma_\nu^2 + \sigma_\epsilon^2$.

Household $i$ living in period $t$ chooses the fraction of income to be allocated to the risk-free asset $\alpha_{i,t}$ by maximizing its life-time expected utility:

$$
\max_{\alpha_{i,t}} E \left[-e^{-\delta c_{i,t}}\right]
$$

s.t. $c_{i,t} = \alpha_{i,t} (1 + r) + (1 - \alpha_{i,t}) (1 + u_{i,t}),$

where the expectation is taken with respect to the return on the risky asset. It can be shown\(^4\) that the household’s optimal choice of $\alpha_{i,t}$ is given by

$$
\alpha_{i,t}^* = \alpha = \frac{\delta \sigma^2 + r - \mu}{\delta \sigma^2}.
$$

We will assume that the econometrician is mainly interested in estimating the risk aversion parameter $\delta$.

We now consider an estimator that takes the form of a population analog of (2), and study the impact of aggregate shocks on the estimator’s consistency when an econometrician works only with cross-sectional data. Our analysis reveals that such an estimator is inconsistent because cross-sectional data do not contain information about aggregate uncertainty. It also makes explicit the dependence of the estimator on the probability distribution of the aggregate shock and thus points to the following method for consistently estimating $\delta$. First, using time series variation, the parameters pertaining to aggregate uncertainty are consistently estimated. Second, those

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\(^4\)This is shown in the Appendix, which is available upon request.
estimates are plugged into the cross-sectional model to estimate the remaining parameters.

Without loss of generality, we assume that the cross-sectional data are observed in period \( t = 1 \). Econometricians observe data on the return of the risky asset \( u_{i,t} \) and on the return of the risk-free asset \( r \). We assume that they also observe a noisy measure of the share of resources invested in the risk-free asset \( \alpha_{i,t} = \alpha + e_{i,t} \), where \( e_{i,t} \) is a measurement error with zero mean and variance \( \sigma^2_e \). The vector of cross-sectional variables \( y_i \) is therefore composed of \( u_{i1} \) and \( \alpha_{i1} \) and the vector of cross-sectional parameters \( \beta \) is composed of \( \delta \), \( \sigma^2_\epsilon \), and \( \sigma^2_e \). The vector of time-series variables includes only the aggregate shock, i.e. \( z_t = \nu_t \), and the vector of time-series variables parameters is composed of \( \mu \) and \( \sigma^2_\nu \). Since, \( \nu_t \) corresponds to the aggregate return of the risky asset, we assume that \( \nu_t \) is observed.

Consider an econometrician who ignores the existence of the aggregate shocks, by assuming that the aggregate return is fixed at \( \mu \) for all \( t \), and uses only cross-sectional variation. Recall that \( \mu = E[u_{i1}] \), \( \sigma^2 = \text{Var}(u_{i1}) \), and \( \alpha = E[\alpha_{i1}] \). That econometrician will therefore estimate those parameters using the following method-of-moments estimators:

\[
\hat{\mu} = \frac{1}{n} \sum_{i=1}^{n} u_{i1} = \bar{u}, \quad \hat{\sigma}^2 = \frac{1}{n} \sum_{i=1}^{n} (u_{i1} - \bar{u})^2, \quad \text{and} \quad \hat{\alpha} = \frac{1}{n} \sum_{i=1}^{n} \alpha_{i1}.
\]

Econometricians can then use equation (2) to write the risk aversion parameter as \( \delta = (\mu - r) / (\sigma^2 (1 - \alpha)) \) and estimate it with the sample analog \( \hat{\delta} = (\hat{\mu} - r) / (\hat{\sigma}^2 (1 - \hat{\alpha})) \).

In the presence of the aggregate shocks \( \nu_t \), however, the method-of-moments estimators take the following form:

\[
\hat{\mu} = \frac{1}{n} \sum_{i=1}^{n} u_{i1} = \nu_1 + \frac{1}{n} \sum_{i=1}^{n} \epsilon_{i1} = \nu_1 + o_p(1),
\]

\[
\hat{\sigma}^2 = \frac{1}{n} \sum_{i=1}^{n} (u_{i1} - \bar{u})^2 = \frac{1}{n} \sum_{i=1}^{n} (\epsilon_{i1} - \bar{\epsilon})^2 = \sigma^2_\epsilon + o_p(1),
\]

\[
\hat{\alpha} = \alpha + \frac{1}{n} \sum_{i=1}^{n} e_{i1} = \alpha + o_p(1),
\]

\[\text{Our model is a stylized version of many models considered in a large literature interested in estimating the parameter } \delta \text{ using cross-sectional variation. Estimators are often based on moment conditions derived from first order conditions (FOC) related to optimal investment and consumption decisions. Such estimators have similar problems, which we discuss in Appendix A.2. The appendix is available upon request.}\]
which implies that \( \delta \) will be estimated to be

\[
\hat{\delta} = \frac{\nu_1 + o_p(1) - r}{(\sigma^2_\epsilon + o_p(1)) (1 - \alpha + o_p(1))} = \frac{\nu_1 - r}{\sigma^2_\epsilon (1 - \alpha)} + o_p(1).
\]

(3)

Using Equation (3), we can study the properties of estimator \( \hat{\delta} \). Without aggregate shocks, we would have \( \nu_1 = \mu \), \( \sigma^2_\nu = 0 \), \( \sigma^2 = \sigma^2 \) and, therefore, \( \hat{\delta} \) would converge to \( \delta \), a nonstochastic constant, as \( n \) grows to infinity. It is therefore a consistent estimator of the risk aversion parameter. However, in the presence of the aggregate shock, the proposed estimator has different properties.

We consider first the case in which econometricians condition on the realization of the aggregate shock \( \nu \) or, equivalently, assumes that the realization of the aggregate shock is known. In this case, the estimator \( \hat{\delta} \) is inconsistent with probability 1, since it converges to \( \frac{\nu_1 - r}{\sigma^2_\epsilon (1 - \alpha)} \) and not to the true value \( \frac{\mu - r}{\sigma^2_\epsilon (1 - \alpha)} \).

As discussed in the introduction, a common practice to account for the effect of aggregate shocks is to include time dummies in the model. The portfolio example clarifies that the addition of time dummies does not solve the problem generated by the presence of aggregate shocks. The inclusion of time dummies is equivalent to the assumption that the realization of the aggregate shock is known or that econometricians condition on the realization of \( \nu \). But the previous result indicates that, using exclusively cross-sectional data, the estimator \( \hat{\delta} \) is biased even if the realizations of the aggregate shocks are known. To provide the intuition behind this result, note that, if aggregate shocks affect individual behavior, the decisions recorded in the data account for the uncertainty generated by the variation in \( \nu \). Even if econometricians assume that the realizations of the aggregate shocks are known, the only way the portfolio model can rationalize the degree of uncertainty displayed by the data is by making the agents more risk averse than they actually are. Hence, the bias and inconsistency described above.

We now consider the case in which econometricians do not condition on the realization of the aggregate shock. As \( n \) grows to infinity, \( \hat{\delta} \) converges to a random variable with a mean that is different from the true value of the risk aversion parameter. The estimator will therefore be biased and inconsistent. To see this, remember that \( \nu_1 \sim N(\mu, \sigma^2_\nu) \). As a consequence, the unconditional
asymptotic distribution of \( \hat{\delta} \) takes the following form:

\[
\hat{\delta} \to N \left( \frac{\mu - r}{\sigma^2 (1 - \alpha)}, \left( \frac{1}{\sigma^2 (1 - \alpha)} \right)^2 \sigma^2_\nu \right) = N \left( \delta + \delta \frac{\sigma^2_\nu}{\sigma^2_\epsilon}, \left( \sigma^2_\nu (\alpha - 1) \right)^2 \right),
\]

which is centered at \( \delta + \delta \frac{\sigma^2_\nu}{\sigma^2_\epsilon} \) and not at \( \delta \), hence the “bias”. The intuition behind the bias is the same as for the case in which the realization of the aggregate shock is known. But when econometricians do not condition on \( \nu \), it is straightforward to sign the bias. The bias is equal to \( \delta \frac{\sigma^2_\nu}{\sigma^2_\epsilon} \) and always positive, which is consistent with the intuition described above according to which ignoring aggregate shocks generates estimates of the risk aversion parameter that are too high. The formula of the bias also enables one to reach the intuitive conclusion that its size increases when the magnitude of the aggregate uncertainty (\( \sigma^2_\nu \)) is large relative to the magnitude of the micro-level uncertainty (\( \sigma^2_\epsilon \)).

We are not the first to consider a case in which the estimator converges to a random variable. Andrews (2005) and more recently Kuersteiner and Prucha (2013) discuss similar scenarios. Our example is remarkable because the nature of the asymptotic randomness is such that the estimator is not even asymptotically unbiased. This is not the case in Andrews (2005) or Kuersteiner and Prucha (2013), where in spite of the asymptotic randomness the estimator is unbiased.

As mentioned above, there is a simple statistical explanation for our result: cross-sectional variation is not sufficient for the consistent estimation of the risk aversion parameter if aggregate shocks affect individual decisions. To make this point transparent, observe that, conditional on the aggregate shock, the assumptions of this section imply that the cross-sectional variable \( y_i = (u_{i1}, \alpha_{i1}) \) have the following distribution

\[
y_i | \nu_1 \sim N \left( \begin{bmatrix} \nu_1 \\ \delta (\sigma^2_\nu + \sigma^2_\epsilon) + r - \mu \end{bmatrix}, \begin{bmatrix} \sigma^2_\nu & 0 \\ 0 & \sigma^2_\epsilon \end{bmatrix} \right),
\]  

\( y_i | \nu_1 \sim N \left( \begin{bmatrix} \nu_1 \\ \delta (\sigma^2_\nu + \sigma^2_\epsilon) + r - \mu \end{bmatrix}, \begin{bmatrix} \sigma^2_\nu & 0 \\ 0 & \sigma^2_\epsilon \end{bmatrix} \right),
\]

12

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6When the realization of \( \nu \) is assumed to be known, one can only sign the expected bias, where the expectation is taken over the realization of the aggregate shock, since the bias depends on the actual realization of the shock. The expected bias is always positive and increasing in \( \sigma^2_\nu \) as our intuition indicates.

7Kuersteiner and Prucha (2013) also consider cases where the estimator is random and inconsistent. However, in their case this happens for different reasons: the endogeneity of the factors. The inconsistency considered here occurs even when the factors are strictly exogenous.
Using (4), it is straightforward to see that any arbitrary choice of the time-series parameters \( \rho = (\mu, \sigma^2_\nu) \) maximize the cross-sectional likelihood, as long as one chooses \( \delta \) that satisfies the following equation:

\[
\frac{\delta (\sigma^2_\nu + \sigma^2_\epsilon) + r - \mu}{\delta (\sigma^2_\nu + \sigma^2_\epsilon)} = \alpha.
\]

Consequently, the cross-sectional parameters \( \mu \) and \( \sigma^2_\nu \) cannot be consistently estimated by maximizing the cross-sectional likelihood and, hence, \( \delta \) cannot be consistently estimated using only cross-sectional data.

We can now describe the method we propose in this paper as a general solution to the issues introduced by the presence of aggregate shocks. The method, which generates unbiased estimates of the model parameters, relies on the combined use of cross-sectional and time-series variables. Specifically, under the assumption that the realizations of the aggregate shocks are observed, the researcher can consistently estimate the parameters that characterize the distribution of those shocks \( \mu \) and \( \sigma^2_\nu \) using a time-series of aggregate data \( \{z_t\} \). The risk aversion parameter \( \delta \) and the remaining two parameters \( \sigma^2_\epsilon \) and \( \sigma^2_e \) can then be consistently estimated using cross-sectional variables, by replacing the consistent estimators of \( \mu \) and \( \sigma^2_\nu \) in the correctly specified cross-section likelihood derived in equation (4).

The example presented in this section is a simplified version of the general class of models introduced in Section 2. The variables and parameters of the time-series submodel affect the cross-sectional submodel, but the cross-sectional variables and parameters have no impact on the time-series submodel. As a consequence, the time-series parameters can be consistently estimated without knowing the cross-sectional parameters. The recursive feature of the example is due to the exogenously specified price process and the partial equilibrium nature of the model. In more complicated situations, such as general equilibrium models, where aggregate shocks are a natural feature, the relationship between the two submodels is generally bi-directional. But before considering an example of the general case, we study a situation in which the effect of aggregate shocks can be accounted for with the proper use of time dummies.

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8The assumption that the realizations of aggregate shocks are observed is made to simplify the discussion and can be easily relaxed. In Section 5 we apply the proposed estimation method to a general equilibrium example in which the realizations of the aggregate shocks are not observed.
4 Example 2: Estimation of Production Functions

In the previous section, we presented an example that illustrates the complicated nature of identification in the presence of aggregate shocks. The example highlights that generally there is no simple method for estimating the class of models considered in this paper. Estimation requires a careful examination of the interplay between the cross-sectional and time-series submodels. In this section, we consider an example showing that there are exceptions to this general rule. In the case we analyze, the researcher is interested in only a subset of the parameters, and its identification can be achieved using only cross-sectional data even if aggregate shocks affect individual decisions, provided that time dummies are skillfully employed. We will show that the naive practice of introducing additive time dummies is not sufficient to deal with the effects generated by aggregate shocks. But the solution is simpler than the general approach we adopted to identify the parameters of the portfolio model.

The example we consider here is a simplified version of the problem studied by Olley and Pakes (1996) and deals with an important topic in industrial organization: the estimation of firms’ production functions. A profit-maximizing firm $j$ produces a product $Y_{j,t}$ in period $t$, employing a production function that depends on the logarithm of labor $l_{j,t}$, the logarithm of capital $k_{j,t}$, and a productivity shock $\omega_{j,t}$. By denoting the logarithm of $Y_{j,t}$ by $y_{j,t}$, the production function takes the following form:

$$ y_{j,t} = \beta_0 + \beta_l l_{j,t} + \beta_k k_{j,t} + \omega_{j,t} + \eta_{j,t}, $$

(5)

where $\eta_{j,t}$ is a measurement error. The firm chooses the amount of labor to use in production and the new investment in capital $i_{j,t}$ by maximizing a dynamic profit function subject to the constraints that in each period capital accumulates according to the following equation:

$$ k_{j,t+1} = (1 - \delta) k_{j,t} + i_{j,t}, $$

where $\delta$ is the rate at which capital depreciates. In the model proposed by Olley and Pakes (1996), firms are heterogeneous in their age and can choose to exit the market. In this section, we will abstract from age heterogeneity and exit decisions because they make the model more

---

9For details of the profit function, see Olley and Pakes (1996).
complicated without adding more insight on the effect of aggregate shocks on the estimation of production functions.

A crucial feature of the model proposed by Olley and Pakes (1996) and of our example is that the optimal investment decision in period $t$ is a function of the current stock of capital and of the productivity shock, i.e.

$$i_{j,t} = i_t(\omega_{j,t}, k_{j,t}).$$  \hspace{1cm} (6)

Olley and Pakes (1996) do not allow for aggregate shocks, but in this example we consider a situation in which the productivity shock at $t$ is the sum of an aggregate shock $\nu_t$ drawn from a distribution $F(\nu|\rho)$ and of an i.i.d. idiosyncratic shock $\varepsilon_{j,t}$, i.e.

$$\omega_{j,t} = \nu_t + \varepsilon_{j,t}.$$ \hspace{1cm} (7)

One example of aggregate shock affecting the productivity of a firm is the arrival of technological innovations in the economy. We will assume that the firm observes the realization of the aggregate shock and, separately, of the i.i.d. shock.

We first review the estimation method proposed by Olley and Pakes (1996) for the production function (5) when aggregate shocks are not present. We then discuss how that method has to be modified with the appropriate use of time dummies if aggregate shocks affect firms’ decisions.

The main problem in the estimation of the production function (5) is that the productivity shock is correlated with labor and capital, but not observed by the econometrician. To deal with that issue, Olley and Pakes (1996) use the result that the investment decision (6) is strictly increasing in the productivity shock for every value of capital to invert the corresponding function, solve for the productivity shock, and obtain

$$\omega_{j,t} = h_t(i_{j,t}, k_{j,t}).$$ \hspace{1cm} (8)

One can then replace the productivity shock in the production function using equation (8) to obtain

$$y_{j,t} = \beta_l l_{j,t} + \phi_t(i_{j,t}, k_{j,t}) + \eta_{j,t},$$ \hspace{1cm} (9)
where
\[ \phi_t(i_{j,t}, k_{j,t}) = \beta_0 + \beta_k k_{j,t} + h_t(i_{j,t}, k_{j,t}). \] (10)

The parameter \( \beta_l \) and the function \( \phi_t \) can then be estimated by regressing, period by period, \( y_{j,t} \) on \( l_{j,t} \) and a flexible polynomial (i.e., a nonparametric approximation) in \( i_{j,t} \) and \( k_{j,t} \) or, similarly, by interacting time dummies with the polynomial in \( i_{j,t} \) and \( k_{j,t} \). The parameter \( \beta_l \) is therefore identified by
\[ \beta_l = \frac{E[(l_{j,t} - E[l_{j,t}|i_{j,t}, k_{j,t}]) (y_{j,t} - E[y_{j,t}|i_{j,t}, k_{j,t}])]}{E[(l_{j,t} - E[l_{j,t}|i_{j,t}, k_{j,t}])^2]}. \] (11)

To identify the parameter on the logarithm of capital \( \beta_k \) observe that the production function (5) implies the following:
\[ E[y_{i,t+1} - \beta_l l_{j,t+1} | k_{j,t+1}] = \beta_0 + \beta_k k_{j,t+1} + E[\omega_{j,t+1} | \omega_{j,t}] = \beta_0 + \beta_k k_{j,t+1} + g(\omega_{j,t}), \] (12)
where the first equality follows from \( k_{j,t+1} \) being determined conditional on \( \omega_{j,t} \). Note that, in the absence of aggregate shocks, the function \( g(\cdot) \) is independent of time. The shock \( \omega_{j,t} = h_t(i_{j,t}, k_{j,t}) \) is not observed, but using equations (8) and (10), it can be written in the following form:
\[ \omega_{j,t} = \phi_t(i_{j,t}, k_{j,t}) - \beta_0 - \beta_k k_{j,t}, \] (13)
where \( \phi_t \) is known from the first-step estimation. Substituting for \( \omega_{j,t} \) into the function \( g(\cdot) \) in equation (12) and letting \( \xi_{j,t+1} = \omega_{j,t+1} - E[\omega_{j,t+1} | \omega_{j,t}] \), equation (12) can be written as follows:
\[ y_{i,t+1} - \beta_l l_{j,t+1} = \beta_k k_{j,t+1} + g(\phi_t - \beta_k k_{j,t}) + \xi_{j,t+1} + \eta_{j,t}. \] (14)
where \( \beta_0 \) has been included in the function \( g(\cdot) \). The parameter \( \beta_k \) can then be estimated by using the estimates of \( \beta_l \) and \( \phi_t \) obtained in the first step and by minimizing the sum of squared residuals in the previous equation, employing a kernel or a series estimator for the function \( g \).

We now consider the case in which aggregate shocks affect the firm’s decisions and analyze how

---

10Given our simplifying assumptions that there are no exit decisions and age heterogeneity, without aggregate shocks, the function \( \phi \) is independent of time. We use the more general notation that allows for time dependence to highlight where the estimation approach developed in Olley and Pakes (1996) fails when aggregate shocks are present.
the model parameters can be identified using only cross-sectional variation. The introduction of aggregate shocks changes the estimation method in two main ways. First, the investment decision is affected by the aggregate shock and takes the following form:

\[ i_{j,t} = i_t(\nu_t, \varepsilon_{j,t}, k_{j,t}). \]

where \( \nu_t \) and \( \varepsilon_{j,t} \) enter as independent arguments because the firm observes them separately. Second, all expectations are conditional on the realization of the aggregate shock since in the cross-section there is no variation in that shock and only its realization is relevant.

If the investment function is strictly increasing in the productivity shock \( \omega_{j,t} \) for all capital levels, it is also strictly increasing in \( \nu_t \) and \( \varepsilon_{j,t} \) for all \( k_{j,t} \), because \( \omega_{j,t} = \nu_t + \varepsilon_{j,t} \). Using this result, we can invert \( i_t(\cdot) \) to derive \( \varepsilon_{j,t} \) as a function of the aggregate shock, investment, and the stock of capital, i.e.

\[ \varepsilon_{j,t} = h_t(\nu_t, i_{j,t}, k_{j,t}). \]

The production function can therefore be rewritten in the following form:

\[
y_{j,t} = \beta_0 + \beta_l l_{j,t} + \beta_k k_{j,t} + \nu_t + \varepsilon_{j,t} + \eta_{j,t} \\
= \beta_l l_{j,t} + [\beta_0 + \beta_k k_{j,t} + \nu_t + h_t(\nu_t, i_{j,t}, k_{j,t})] + \eta_{j,t} \\
= \beta_l l_{j,t} + \phi_t(\nu_t, i_{j,t}, k_{j,t}) + \eta_{j,t} \\
= \beta_l l_{j,t} + \phi_t(i_{j,t}, k_{j,t}) + \eta_{j,t}.
\]

where we have included the aggregate shock in the function \( \phi_t \). Analogously to the case of no aggregate shocks, \( \beta_l \) can be consistently estimated by regressing period by period \( y_{j,t} \) on \( l_{j,t} \) and a polynomial in \( i_{j,t} \) and \( k_{j,t} \) or, similarly, by interacting the polynomial with time dummies.

Note that the estimation of \( \beta_l \) is not affected by the uncertainty generated by the aggregate shocks since that uncertainty is captured by the time subscript in the function \( \phi_t \) and the method developed by Olley and Pakes (1996) already requires the estimation of a different function \( \phi \) for
each period. The parameter $\beta_l$ is therefore identified by

$$
\beta_l = \frac{E[(l_{j,t} - E[l_{j,t} | i_{j,t}, k_{j,t}, \nu_t]) (y_{j,t} - E[y_{j,t} | i_{j,t}, k_{j,t}, \nu_t])]}{E[(l_{j,t} - E[l_{j,t} | i_{j,t}, k_{j,t}, \nu_t])^2]}.
$$

(16)

Observe that the expectation operator in the previous equation is in principle defined with respect to a probability distribution function that includes the randomness of the aggregate shock $\nu_t$. But, when one uses cross-sectional variation, $\nu_t$ is fixed at its realized value. As a consequence, the distribution is only affected by the randomness of $\varepsilon_{j,t}$.

For the estimation of $\beta_k$, note that, under the assumption that the $\nu_t$'s are independent of the $\varepsilon_{j,t}$'s,

$$
E[y_{i,t+1} - \beta_l l_{j,t+1} | k_{j,t+1}, i_{j,t}, k_{j,t}, \nu_{t+1}, \nu_t, \varepsilon_{j,t}]
$$

(17)

$$
= \beta_0 + \beta_k k_{j,t+1} + E[\nu_{t+1} + \varepsilon_{j,t+1} | k_{j,t}, \nu_{t+1}, \nu_t, \varepsilon_{j,t}]
$$

$$
= \beta_0 + \beta_k k_{j,t+1} + \nu_{t+1} + E[\varepsilon_{j,t+1} | \varepsilon_{j,t}]
$$

$$
= \beta_0 + \beta_k k_{j,t+1} + \nu_{t+1} + g(\varepsilon_{j,t})
$$

where the first equality follows from $k_{j,t+1}$ being known if $i_{j,t}, k_{j,t}, \nu_t$, and $\varepsilon_{j,t}$ are known.

The only variable of equation (17) that is not observed is $\varepsilon_{j,t}$. But remember that

$$
\varepsilon_{j,t} = h_t(\nu_t, i_{j,t}, k_{j,t}) = \phi_t(\nu_t, i_{j,t}, k_{j,t}) - \beta_0 - \beta_k k_{j,t} - \nu_t.
$$

We can therefore use the above expression to substitute for $\varepsilon_{j,t}$ in equation (17) and obtain

$$
E[y_{i,t+1} - \beta_l l_{j,t+1} | k_{j,t+1}, i_{j,t}, k_{j,t}, \nu_{t+1}, \nu_t]
$$

$$
= \beta_0 + \beta_k k_{j,t+1} + \nu_{t+1} + g_t(\phi_t(\nu_t, i_{j,t}, k_{j,t}) - \beta_0 - \beta_k k_{j,t} - \nu_t)
$$

$$
= \beta_k k_{j,t+1} + g_{t,t+1}(\phi_t - \beta_k k_{j,t}),
$$

where in the last equality $\beta_0$, $\nu_t$, and $\nu_{t+1}$ have been included in the function $g_{t,t+1}(\cdot)$. Hence, if one defines $\xi_{j,t+1} = \varepsilon_{j,t+1} - E[\varepsilon_{j,t+1} | \nu_t, \varepsilon_{j,t}]$, the previous equation can be written in the following
The inclusion of the aggregate shocks in the function \( g(\cdot) \) implies that that function varies with time when aggregate shocks are present. This is in contrast with the case considered in Olley and Pakes (1996) where aggregate shocks are ignored and, hence, the function \( g(\cdot) \) is independent of time.

Given equation (18), if one attempts to estimate \( \beta_k \) using equation (14), repeated cross-sections and the method developed for the case with no aggregate shocks, the estimated coefficient will generally be biased because the econometrician does not account for the aggregate shocks and their correlation with the firm’s choice of capital. There is, however, a small variation of the method proposed earlier that produces unbiased estimates of \( \beta_k \), as long as \( \varepsilon_{j,t} \) is independent of \( \eta_{j,t} \). The econometrician should regress period by period \( y_{j,t} \) on \( l_{j,t} \) and a nonparametric function of \( i_{j,t} \) and \( k_{j,t} \) or, in practice, on a flexible polynomial of \( i_{j,t} \) and \( k_{j,t} \) interacted with time dummies. It is this atypical use of time dummies that enables the econometrician to account for the effect of aggregate shocks on firms’ decisions.

We conclude by drawing attention to two features of the production function example that make it possible to use time dummies to deal with the effect of the aggregate shocks. To do that, it is useful to cast the example in terms of the cross-sectional and time-series submodels. The cross-sectional submodel includes the variables \( y_j, l_j, k_j, \) and \( i_j \), the parameters \( \beta_0, \beta_l, \) and \( \beta_k \), and the non-parametric functions \( \phi_t \) and \( g_{t,t+1} \). The time-series submodel includes the aggregate shocks \( \nu_t \) and the parameters \( \rho \) that define their distribution function. The decomposition in the two submodels highlights two features of the example. First, the time-series submodel affects the cross-sectional counterpart only through the functions \( \phi_t \) and \( g_{t,t+1} \). Second, to consistently estimate the production function parameters \( \beta_l \) and \( \beta_k \), the functions \( \phi_t \) and \( g_{t,t+1} \) must be known to control for the correlation between labor and capital on one side and the productivity shocks on the other. But it is irrelevant how the aggregate shocks and the corresponding parameters enter those functions. These two features imply that, if the econometrician is only interested in estimating the production function parameters \( \beta_l \) and \( \beta_k \), he can achieve this by simply estimating the cross-sectional submodel. This is possible as long as the functions \( \phi_t \) and \( g_{t,t+1} \) are allowed to
vary in a non-parametric way over time to deal with the existence of the aggregate shocks. The
cleaver use of time-dummies, therefore, solves all the issues raised by their presence. However,
if the econometrician is interested in estimating the entire model, which includes the parameters
that describe the distribution of the aggregate shocks, he has to rely on the general approach
based on the combination of cross-sectional and time-series variables.

5 Example 3: A General Equilibrium Model

In this section, we consider as a third example a general equilibrium model of education and
labor supply decisions in which aggregate shocks influence individual choices. This example pro-
vides additional insights into the effects of aggregate shocks on the estimation of model parameters.
Differently from the portfolio and production function examples, it considers a case in which the re-
relationship between the cross-sectional and time-series models is bi-directional: the cross-sectional
parameters cannot be identified from cross-sectional data without knowledge of the time-series
parameters and the time-series parameters cannot be identified from time series data without
knowing the cross-sectional parameters. In addition, it confirms the results obtained in the port-
folio example. Disregarding the uncertainty generated by the aggregate shocks can produce large
biases in parameters that are important for economists and policy makers. We show theoretically
that ignoring the presence of aggregate shocks generally produces estimates of the risk aversion
parameter that are severely biased. Monte Carlo simulations confirm biases in that parameter as
large as five, six times the size of the true parameter.

In principle, we could have used as a general example a model proposed in the general equilib-
rium literature such as the model developed in Lee and Wolpin (2006). We decided against this
alternative because in those models the effect of the aggregate shocks on the estimation of the
model parameters and the relationship between the cross-sectional and time-series submodels are
complicated and therefore difficult to describe. Instead, we decided to develop a model that is
sufficiently general to generate an interesting relationship between the shocks and the estimation
of the parameters of interest and between the two submodels, but at the same time sufficiently
stylized for these relationships to be easy to describe and understand.

In the model we develop, aggregate shocks affect the education decisions of young individuals
and their subsequent labor supply decisions when of working-age. Specifically, we consider an economy in which in each period \( t \in T \) a young and a working-age generation overlap. Each generation is composed of a continuum of individuals with measure \( N_t \). Each individual is endowed with preferences over a non-durable consumption good and leisure. The preferences of individual \( i \) are represented by a Cobb-Douglas utility function \( U_i(c, l) = (c^\sigma l^{1-\sigma})^{1-\gamma_i}/(1 - \gamma_i) \), where the risk aversion parameter \( \gamma_i \) is a function of the observable variables \( x_{i,t} \), the unobservable variables \( \xi_{i,t} \), and a vector of parameters \( \mu \), i.e. \( \gamma_i = \gamma(x_{i,t}, \xi_{i,t} | \mu) \). Future utilities are discounted using a discount factor \( \delta \).

Both young and working-age individuals are endowed with a number of hours \( T \) that can be allocated to leisure or to a productive activity. Young individuals are also endowed with an exogenous income \( y_{i,t} \). In each period, the economy is hit by an aggregate shock \( \nu_t \) whose conditional probability \( P(\nu_{t+1} | \nu_t) \) is determined by \( \log \nu_{t+1} = \rho \log \nu_t + \eta_t \). We assume that \( \eta_t \) is normally distributed with mean 0 and variance \( \omega^2 \). The aggregate shock affects the labor market in a way that will be established later on.

In each \( t \), young individuals choose the type of education to acquire. They can choose either a flexible type of education \( F \) or a rigid type of education \( R \). Working-age individuals with flexible education are affected less by adverse aggregate shocks, but they have lower expected wages. The two types of education have identical cost \( C_e < y_{i,t} \) and need the same amount of time to acquire \( T_e < T \). Since young individuals have typically limited financial wealth, we assume that there is no saving decision when young and that any transfer from parents or relatives is included in non-labor income \( y_{i,t} \). We also abstract from student loans and assume that all young individuals can afford to buy one of the two types of education. As a consequence, a young individual will consume the part of income \( y_{i,t} \) that is not spent on education.

At each \( t \), working-age individuals draw a wage offer \( w_{i,t}^F \) if they have chosen the flexible education when young and a wage offer \( w_{i,t}^R \) otherwise. They also draw a productivity shock \( \varepsilon_{i,t}^S \), for \( S = F, R \), which determines how productive their hours of work are in case they choose to supply labor. We assume that the productivity shock is unknown to the individuals when young. Given the wage offer and the productivity shock, working-age individuals choose how much to

\[11\]In the rest of the Section we use interchangeably the word 'measure' and the more intuitive but less precise word 'number' to refer to \( N_t \) or similar objects.
work $h_{i,t}$ and how much to consume. If a working-age individual decides to supply $h_{i,t}$ hours of work, the effective amount of labor hours supplied is given by $\exp(\varepsilon_{i,t}^F) h_{i,t}$ for the flexible type of education $F$ and by $\exp(\varepsilon_{i,t}^R) h_{i,t}$ for the rigid type of education $R$. We assume that $\varepsilon_{i,t}^S$ is normally distributed with mean $\mu_{\varepsilon_{i,t}^S}$ and variance $\sigma_{\varepsilon_{i,t}^S}^2$, for $S = F, R$, and that $\sigma_{\varepsilon_{i,t}^F}^2 < \sigma_{\varepsilon_{i,t}^R}^2$. To simplify the analysis we normalize $E[\exp(\varepsilon_{i,t}^S)] = 1$, for $S = F, R$.

The economy is populated by two types of firms to whom the working-age individuals supply labor. The first type of firm employs only workers with education $F$, whereas the second type of firm employs only workers with education $R$. Both use the same type of capital $K$, which is assumed to be fixed over periods. The labor demand functions of the two types of firms are assumed to take the following form:

$$\log H_{t}^{D,F} = \alpha_0 + \alpha_1 \log w_t^F,$$

and

$$\log H_{t}^{D,R} = \alpha_0 + \alpha_1 \log w_t^R + \log \nu_t,$$

where $H^{D,S}$ is the total demand for effective labor, with $S = F, R$, $\alpha_0 > 0$, and $\alpha_1 < 0$. We assume that the two labor demands have identical slopes for simplicity. These two labor demand functions enable us to account for the common insight that workers with more flexible education are affected less by aggregate shocks such as business cycle shocks. The wage for each education group is determined by the equilibrium in the corresponding labor market. It will therefore generally depend on the aggregate shock.

We conclude the description of the model by pointing out that there is only one source of uncertainty in the economy, the aggregate shock, and two sources of heterogeneity across individuals, the risk aversion parameter and the productivity shock.

The problem solved in period $t$ by individual $i$ of the young generation is to choose consumption,
leisure, and the type of education that satisfy:

$$\max_{c_{i,t}, l_{i,t}, c_{i,t+1}, l_{i,t+1}, S} \frac{(c_{i,t+1} \sigma l_{i,t+1})^{1-\gamma_i}}{1-\gamma_i} + \delta \int \frac{(c_{i,t+1} \sigma l_{i,t+1})^{1-\gamma_i}}{1-\gamma_i} dP(\nu_{t+1} | \nu_t)$$  \hspace{1cm} (19)

s.t.  

$$c_{i,t} = y_{i,t} - C_e \quad \text{and} \quad l_{i,t} = T - T_e$$

$$c_{i,t+1} = w_{i,t+1}^S (\nu_{t+1}) \exp (\varepsilon_{i,t+1}^S) (T - l_{i,t+1}) \quad \text{for every } \nu_{t+1}.$$  

Here, $w_{i,t+1}^S (\nu_{t+1})$ denotes the wage rate of individual $i$ in the second period, which depends on the realization of the aggregate shock $\nu_{t+1}$ and the education choice $S = F, R$. The wage rate is per unit of the effective amount of labor hours supplied and is determined in equilibrium.

The problem solved by a working-age individual takes a simpler form. Conditional on the realization of the aggregate shock $\nu_t$ and on the type of education $S$ chosen when young, individual $i$ of the working-age generation chooses consumption and leisure that solve the following problem:

$$\max_{c_{i,t}, l_{i,t}} \frac{(c_{i,t} \sigma l_{i,t})^{1-\gamma_i}}{1-\gamma_i}$$  \hspace{1cm} (20)

s.t.  

$$c_{i,t} = w_{i,t}^S (\nu_t) \exp (\varepsilon_{i,t}^S) (T - l_{i,t}).$$  

We now solve the model starting from the problem of a working-age individual. Using the first order conditions of problem (20) the optimal choice of consumption, leisure, and hence labor supply for a working-age individual takes the following form:

$$c_{i,t}^* = \sigma w_t (\nu_t, S) \exp (\varepsilon_{i,t}^S) T,$$  \hspace{1cm} (21)

$$l_{i,t}^* = (1 - \sigma) T,$$  \hspace{1cm} (22)

$$h_{i,t}^* = T - l_{i,t} (\nu_{i,t}) = \sigma T.$$  

The supply of effective labor is therefore equal to $\sigma \exp (\varepsilon_{i,t}^S) T$. Given the optimal choice of consumption and leisure, conditional on the aggregate shock, the value function of a working-age individual with education $S$ can be written as follows:

$$V_{i,t} (S, \nu_t, \varepsilon_{i,t}) = \frac{[(\sigma w_{i,t}^S (\nu_t) \exp (\varepsilon_{i,t}^S) T)^\sigma ((1 - \sigma) T)^{1-\sigma}]^{1-\gamma_i}}{1-\gamma_i}, \quad S = F, R.$$  

23
Given the value functions of a working-age individual, we can now characterize the education choice of a young individual. This individual will choose education $F$ if the expectation taken over the next period aggregate shocks of the corresponding value function is greater than the analogous expectation for education $R$:

$$E[V_{i,t} (F, \nu_{t+1}, \varepsilon_{i,t+1}) | \nu_t] \geq E[V_{i,t} (R, \nu_{t+1}, \varepsilon_{i,t+1}) | \nu_t].$$

(23)

To simplify the discussion, we assume that $\varepsilon_{i,t+1}$ is independent of $\gamma_i$, thereby eliminating sample selection issues in the wage equations.

Before we can determine which variables and parameters affect the education choice, we have to derive the equilibrium in the labor market. It can be shown that the labor market equilibrium is characterized by the following two wage equations:

$$\log w_{i,t}^F = \log n_t^F + \log \sigma + \log T - \alpha_0 \frac{\alpha_1}{\varepsilon_{i,t}^F},$$

(24)

$$\log w_{i,t}^R = \log n_t^R + \log \sigma + \log T - \alpha_0 - \log \nu_t \frac{\alpha_1}{\varepsilon_{i,t}^R},$$

(25)

where $w_{i,t}^F$ and $w_{i,t}^R$ are the individual wages observed in sectors $F$ and $R$ and $n_t^F$ and $n_t^R$ are the measures of individuals that choose education $F$ and $R$. We can now replace the equilibrium wages inside inequality (23) and analyze the education decision of a young individual. It can be shown that a young individual chooses the flexible type of education at time $t$ if the following inequality is satisfied:

$$\gamma_i \geq 1 - \frac{\log \left( \frac{n_{t+1}^F}{n_{t+1}^R} \right) + \frac{\sigma^2_R - \sigma^2_F}{2} + \rho \log \nu_t}{\sigma \left( \sigma^2_R - \sigma^2_F + \omega^2 \right) \frac{2\alpha_1}{2\alpha_1}}.$$

(26)

This inequality provides some insight into the educational choice of young individuals. Since $\alpha_1 < 0$, they are more likely to choose the flexible education which insures them against aggregate shocks if the variance of the aggregate shock is larger, if they are more risk averse, if the aggregate shock at the time of the decision is lower as long as $\rho > 0$, and if the elasticity of the wage for the rigid education with respect to the aggregate shock is larger (the absolute value of $\alpha_1$ is lower).

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12 See Appendix B.2, which is available upon request.

13 Details are given in the Appendix, which is available upon request.
Similarly to the first two examples, we can classify some of the variables and some of the parameters as belonging to the cross-sectional submodel and the remaining to the time-series submodel. The cross-sectional variables include consumption $c_{i,t}$, leisure $l_{i,t}$, individual wages $w_{i,t}^F$ and $w_{i,t}^R$, the variable determining the educational choice $D_{i,t}$, the amount of time $\mathcal{T}$ an individual can divide between leisure and productive activities, and the variables that enter the risk aversion parameter $x_{i,t}$. The time-series variables are composed of the aggregate shock $\nu_t$, the numbers of young individuals choosing the two types of education $n^F$ and $n^R$, and the aggregate equilibrium wages in the two sectors $w_t^F = E[w_{it}^F]$ and $w_t^R = E[w_{it}^R]$.\(^\text{14}\) We want to stress the difference between individual wages and aggregate wages. Individual wages are typically observed in panel data or repeated cross-sections whose time dimension is generally short, whereas aggregate wages are available in longer time-series of aggregate data. The cross-sectional parameters consist of the relative taste for consumption $\sigma$, the variances $\sigma^2_F$ and $\sigma^2_R$ of the individual productivity shocks, the parameters defining the risk aversion $\mu$, and the parameters of the wage equations $\alpha_0$ and $\alpha_1$, whereas the time-series parameters include the two parameters governing the evolution of the aggregate shock $\varrho$ and $\omega^2$, and the discount factor $\delta$. The discount factor is notoriously difficult to estimate. For this reason, in the rest of the section we will assume it is known.

We now employ the method proposed in this paper, which exploits a combination of a long time-series of aggregate data and cross-sectional data, in the estimation of the model parameters. We will highlight which parameters require cross-sectional variables to be identified, which parameters require time-series variables, and which parameters embody the bi-directional relationship between the cross-sectional and time-series submodels.

We assume that the econometrician has access to two repeated cross-sections of data for periods $t = 1$ and $t = 2$, which include i.i.d. observations on educational choices $D_{i,t}$, wages $w_{i,t}^S$ with $S = F, R$, consumption $c_{i,t}^*$, and leisure $l_{i,t}^*$. The econometrician has also access to a time-series of aggregate data that spans $t = 1, \ldots, \tau$. It consists of the measures of people choosing the flexible and rigid educations $n_t^F$ and $n_t^R$, and their corresponding aggregate wages $w_t^F$ and $w_t^R$. For simplicity, we assume that the two cross-sections consist of the same number of individuals $n$, and that the first $\bar{n}_1$ and $\bar{n}_2$ individuals in the two cross sections chose $S = F$.

\(^{14}\)The expectation operator $E$ corresponds to the expectation taken over the distribution of cross-sectional variables.
The parameters \( \alpha_1, \sigma, \sigma^2_F \), and \( \sigma^2_R \) can be estimated using only the two cross-sections. Specifically, \( \alpha_1 \) can be consistently estimated using the wage equation for the flexible education (24) for the periods 1 and 2 as the \( \hat{\alpha}_1 \) which solves
\[
\frac{1}{n_1} \sum_{i=1}^{n_1} \log w_{1,i}^F - \frac{1}{n_2} \sum_{i=1}^{n_2} \log w_{1,2}^F = \frac{1}{\hat{\alpha}_1} (\log n_1^F - \log n_2^F).
\] (27)
Observe that this can be done because the productivity shock \( \varepsilon_t \) and the risk aversion parameter \( \gamma_i \) are assumed to be independent of each other, which implies that there is no sample selectivity problem. The parameter \( \sigma \) can be consistently estimated employing the consumption and leisure choices of the working-age individuals (21) and (22) for period 1 as \( \hat{\sigma} \) that solves
\[
\frac{1}{n_1} \sum_{i=1}^{n_1} \frac{c_{1,i}}{l_{1,i}^*} = w_1^F \frac{\hat{\sigma}}{1 - \hat{\sigma}}.
\] (28)
The variances of the productivity shocks for the two sectors \( \sigma^2_F \) and \( \sigma^2_R \) can be estimated using the wage equations for sectors \( F \) and \( R \) (24) and (25) as the sample variances of \( \log w_{1,t}^F \) and \( \log w_{1,t}^R \).

The aggregate shocks and the parameters governing their evolution \( \varrho \) and \( \omega^2 \) can then be estimated using the time-series of aggregate data. Specifically, with \( \alpha_1 \) consistently estimated, the aggregate shock in period \( t \) can be consistently estimated for \( t = 1, \ldots, \tau \) using the following equation:
\[
\log \nu_t = \hat{\alpha}_1 (\log w_t^F - \log w_t^R) - (\log n_t^F - \log n_t^R),
\] (29)
which was derived by computing the difference between the equations defining the equilibrium wages in sectors \( R \) and \( S \) and solving for \( \log \nu_t \).\(^{15}\) Observe that \( \nu_t \) can only be estimated because \( \alpha_1 \) was previously estimated using the cross-sections. The parameters \( \varrho \) and \( \omega^2 \) can then be consistently estimated by the time-series regression of the equation that characterizes the evolution of the aggregate shocks:
\[
\log \nu_{t+1} = \varrho \log \nu_t + \eta_t.
\] (30)

The only parameters left to estimate are the parameters \( \mu \) defining the individual risk aversion \( \gamma_i \). They are the most interesting parameters of the model because they incorporate the bi-
directional relationship between the cross-sectional and time-series submodels, as the following
discussion reveals. Specifically, if the distribution of $\gamma_i$ is parametrically specified, the parameters
$\mu$ can be consistently estimated by MLE using cross-sectional variation on the educational choices
and the inequality that characterizes those choices \[26]. In the Monte Carlo exercise in Section 7, we assume that $\log \gamma_i \sim N(\mu, 1)$. Under this assumption, the distribution of risk aversion in the
population is characterized by only one parameter, its mean $\mu$. It can be shown that in this case
the probability that an individual chooses education $F$ takes the following form:\[16\]

$$1 - \Phi(\log (1 - \Theta_t) - \mu).$$

where

$$\Theta_t \equiv \frac{\log \left( \frac{n_F^t}{n_R^t} \right) + \frac{\sigma^2_R - \sigma^2_F}{2} + \rho \log \nu_t}{\sigma(\sigma^2_R - \sigma^2_F + \omega^2)}.$$

We can therefore estimate the mean of the distribution of risk aversion $\mu$ using a Probit maximum
likelihood estimator, provided that $\nu_t$, $\rho$, $\omega^2$, $\sigma^2_F$, $\sigma^2_R$, $\sigma$, and $\alpha_1$ and are known.\[17\] The cross-
sectional parameter $\mu$ can therefore be estimated only if the time-series parameters $\nu_t$, $\rho$, and $\omega^2$
have been previously estimated. But their estimation requires the prior estimation of the cross-
sectional parameter $\alpha_1$. Hence, the bi-directional relationship between the cross-sectional and
time-series submodels.

To evaluate the effect of ignoring aggregate shocks when estimating the parameters of the
general equilibrium model, we now consider the case of an econometrician who is unaware of the
presence of aggregate shocks and, hence, only uses cross-sectional variation for the identification
and estimation of the parameters of interest. The misspecification only changes the inequality
that characterizes the education choice \[26\], which in this case takes the following form:\[18\]

$$\gamma_i \geq 1 - \frac{\log \left( \frac{n_F^{t+1}}{n_R^{t+1}} \right) + \frac{\sigma^2_R - \sigma^2_F}{2} + \log \nu_{t+1}}{\sigma(\sigma^2_R - \sigma^2_F)}.$$

\[31\]

\[16\] For details see the Appendix, which is available upon request.
\[17\] It is straightforward to relax the distributional assumption on $\gamma_i$ and consider the more general case where the
risk aversion parameter $\gamma_i$ is a function of the observable variables $x_{i,t}$, the unobservable variables $\xi_{i,t}$, and a vector
of parameters $\mu$, i.e. $\gamma_i = \gamma(x_{i,t}, \xi_{i,t} | \mu)$.
\[18\] For details see the Appendix which is available upon request.
As a consequence, under the misspecification and the assumption that \( \log \gamma_i \sim N(\mu, 1) \), the probability that an individual chooses education \( F \) becomes

\[
1 - \Phi(\log (1 - \Theta^*_t) - \mu),
\]

where

\[
\Theta^*_t \equiv \frac{\log \left( \frac{n^F_{t+1}}{n^R_{t+1}} \right) + \frac{\sigma^2_R - \sigma^2_F}{2} + \log \nu_{t+1}}{\sigma(\sigma^2_R - \sigma^2_F)^{2\alpha_1}}.
\]

Since this form of misspecification only changes the probability of choosing education \( F \), only estimation of the parameter \( \mu \) is affected. To understand its effect, we derive the estimation bias in closed form. In the misspecified model, the probability that someone selects education \( F \) can be written as follows:

\[
1 - \Phi(\log (1 - \Theta^*_t) - \mu) = 1 - \Phi(\log (1 - \Theta_t) - (\mu - \log (1 - \Theta^*_t) + \log (1 - \Theta_t))).
\]

Let \( \hat{\mu} \) be the maximum likelihood estimator of the correctly specified model. Then, the previous equation implies that the maximum likelihood estimator \( \hat{\mu}_{\text{mis}} \) of the misspecified model satisfies the following equation:

\[
\hat{\mu}_{\text{mis}} = \hat{\mu} + \log (1 - \Theta^*_t) - \log (1 - \Theta_t).
\]

The misspecification bias has therefore the following analytic form:

\[
\log (1 - \Theta^*_t) - \log (1 - \Theta_t) = \log \left( 1 - \frac{\log \left( \frac{n^F_{t+1}}{n^R_{t+1}} \right) + \frac{\sigma^2_R - \sigma^2_F}{2} + \log \nu_{t+1}}{\sigma(\sigma^2_R - \sigma^2_F)^{2\alpha_1}} \right) - \log \left( 1 - \frac{\log \left( \frac{n^F_{t+1}}{n^R_{t+1}} \right) + \frac{\sigma^2_R - \sigma^2_F}{2} + \varrho \log \nu_t}{\sigma(\sigma^2_R - \sigma^2_F + \omega^2)^{2\alpha_1}} \right).
\]

It shows that the magnitude of the bias depends on the size of the the variance of the aggregate shocks \( \omega^2 \) and on the difference between the expected aggregate shock in period \( t + 1 \), \( \varrho \log \nu_t \), and its realization, \( \log \nu_{t+1} \). Later in the paper, we will use particular values for the model parameters to provide evidence on the magnitude of the bias. Intuitively, ignoring the uncertainty generated by the aggregate shocks should have the same effect as in the portfolio example of biasing upward.
the estimated risk aversion parameter. Not accounting for the aggregate shocks is equivalent to assuming that the agents face less uncertainty than they actually experience when making the education decisions. Since the individuals’ decisions are based on the actual uncertainty, the only way the model can explain those choices is by making people more risk averse. In the general equilibrium model, this insight is not as straightforward to see as in the portfolio example, since the bias depends also on the difference between the current and next period aggregate shocks. For this reason we perform a Monte Carlo exercise whose results are reported in Section[7]. They confirm the intuition regarding the sign of the bias and show that its size can be extremely large. These insights are not specific to the uncertainty generated by the aggregate shocks. They apply equally to individual-specific shocks. If the econometrician disregards the variation generated by those shocks, risk aversion will generally be estimated to be larger than it actually is.

There is an alternative approach that can be used to estimate model parameters when aggregate shocks affect behavior. The econometrician can use a single panel data set in which the time-series dimension of the panel is sufficiently long, instead of the repeated cross-sections combined with the time-series of aggregate data. The general equilibrium model of this section is too complicated to illustrate the limitations of the alternative panel-data approach. Using a stylized linear panel model, however, one can show that, when the alternative approach is used, the effective sample size of the data is not \( n \times T \) but \( T \), with the cross-section generally playing a minor role[19]. The reason is that the asymptotic theory for the alternative “long panel” approach requires, analogously to the time-series analysis, the time dimension \( T \) to go to infinity. A large cross-section \( n \) does not compensate for the lack of a long time-series in the panel. This is in contrast to the textbook panel analysis, which indicates that the effective sample size is \( n \times T \). Since in practice almost all panel data sets have limited time-series dimensions, using the alternative panel approach would therefore lead to imprecise estimates relative to our proposed method.

It is also important to point out that the practice of computing standard errors under the assumption that the time-series parameters are known does not solve the large-\( T \) problem illustrated by our panel example. Under that assumption, the standard errors for the cross-sectional parameters are incorrect and too small because they do not account for the noise introduced by the estimation of the time series parameters. Lee and Wolpin (2006) use such a procedure (see

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[19] A detailed exposition of the model and derivation are in Appendix [C] which is available upon request.
also their footnote 37). Their standard errors therefore underestimate the true standard errors.

The econometric method proposed in this paper for the estimation of models with aggregate shocks requires the combined use of cross-sectional data with long time-series of aggregate data. There are no formulas available for the computation of standard errors and confidence intervals that account for jointly estimated time series and cross-sectional coefficients based on those combined data sources. In the next section, we provide such formulas. They are based on a new and complex asymptotic theory that we develop in the companion paper Hahn, Kuersteiner, and Mazzocco (2016). Surprisingly, in spite of the complexity of the theory, the formulas are straightforward and easy to use.

6 Standard Errors

The asymptotic theory underlying estimators obtained from the combination of the two data sources considered in this paper is complex. It is based on a new central limit theorem that requires a novel martingale representation. Given its complexity, the theory is presented in a separate paper (Hahn, Kuersteiner and Mazzocco (2016)). However, the mechanical implementation of test statistics and confidence intervals is surprisingly straightforward. In this Section, we first provide a step-by-step description of how those statistics can be calculated. We then explain how they can be employed in concrete cases using as examples the portfolio choice and the general equilibrium models analyzed in the previous sections.

The computation starts with the explicit characterization of the “moments” that identify the cross-sectional parameters $\beta$ and the time-series parameters $\rho$. In the most general case, the aggregate shocks are unknown and must be estimated jointly with the other model parameters using cross-sectional data, as illustrated in the general equilibrium example. The shocks can therefore be treated as cross-sectional parameters. This is accounted for by introducing a new vector of parameters $\theta$ which is composed of the original cross-sectional parameters and the aggregate shocks, i.e. $\theta = (\beta, \nu_1, ..., \nu_T)$. We then denote with $f_{\theta,i}(\theta, \rho)$ the $i$-th moment used in the identification of the parameters in $\theta$ and with $g_{\rho,t}(\beta, \rho)$ the $t$-th moment used in the identification of the time-series parameters. Our proposed estimator based on a combination of cross-sectional data and a long

\footnote{Donghoon Lee kindly confirmed this in private communication.}
time-series of aggregate data can then be written as the solution \((\hat{\theta}, \hat{\rho})\) to the following system of equations:

\[
\sum_{i=1}^{n} f_{\theta,i} \left( \hat{\theta}, \hat{\rho} \right) = 0, \quad (33)
\]

\[
\sum_{t=\tau_0 + 1}^{\tau_0 + \tau} g_{\rho,t} \left( \hat{\beta}, \hat{\rho} \right) = 0. \quad (34)
\]

Using those equations, the standard errors for \(\hat{\theta}\) and \(\hat{\rho}\) can be calculated using the following five steps.

1. Let \(\phi = (\theta', \rho')'\) be the vector of parameters.

2. Let

\[
A = \begin{bmatrix} \hat{A}_{f,\theta} & \hat{A}_{f,\rho} \\ \hat{A}_{g,\theta} & \hat{A}_{g,\rho} \end{bmatrix},
\]

be the matrix of first order derivatives of the moments with respect to the parameters, with

\[
\hat{A}_{f,\theta} = \frac{1}{n} \sum_{i=1}^{n} \frac{\partial f_{\theta,i}}{\partial \theta'}, \quad \hat{A}_{f,\rho} = \frac{1}{n} \sum_{i=1}^{n} \frac{\partial f_{\theta,i}}{\partial \rho'}, \\
\hat{A}_{g,\theta} = \frac{1}{\tau} \sum_{t=\tau_0 + 1}^{\tau_0 + \tau} \frac{\partial g_{\rho,t}}{\partial \theta'}, \quad \hat{A}_{g,\rho} = \frac{1}{\tau} \sum_{t=\tau_0 + 1}^{\tau_0 + \tau} \frac{\partial g_{\rho,t}}{\partial \rho'}.
\]

3. Let

\[
\hat{\Omega}_f = \frac{1}{n} \sum_{i=1}^{n} f_{\theta,i} \left( \hat{\theta}, \hat{\rho} \right) f_{\theta,i} \left( \hat{\theta}, \hat{\rho} \right)',
\]

and

\[
\hat{\Omega}_g = \frac{1}{n} \sum_{i=1}^{n} g_{\rho,t} \left( \hat{\theta}, \hat{\rho} \right) g_{\rho,t} \left( \hat{\theta}, \hat{\rho} \right)'.
\]

4. Let

\[
W = \begin{bmatrix} \frac{1}{n} \hat{\Omega}_f & 0 \\ 0 & \frac{1}{\tau} \hat{\Omega}_g \end{bmatrix}
\]
5. Calculate

\[ V = A^{-1}W (A')^{-1} \]

and use the square roots of the diagonal elements as the standard errors of the estimator. For instance, if one is interested in the 95% confidence interval of the first component of \( \phi \), it can be written as \( \hat{\phi}_1 \pm 1.96 \sqrt{V_{1,1}} \).

The theoretical results in our companion paper as well as more detailed calculations in the appendix reveal a few important points. The matrix \( V \) in general is a function of aggregate shocks realized during the observation periods of the cross-sectional sample. This randomness affects the standard errors for both the cross-sectional and time series parameters. As a result, caution needs to be exercised when comparing standard errors across different observation periods or samples. On the other hand, pivotal statistics such as t-ratios or confidence intervals have standard distributional properties and can be compared across different samples. A similar word of caution applies to sample descriptive statistics such as simple sample averages obtained from short panels. These averages in general are functions of realized values of aggregate shocks even when the cross-sectional sample size is large. As a result, descriptive statistics are expected to change in response to changes of the aggregate shock. Comparison of these descriptive measures across different time periods or data sets thus needs to be done with caution. The deep structural parameters estimated in this paper, however, are typically thought to be fixed. As long as these parameters are estimated consistently, their point estimators are not affected by variation from aggregate shocks in large enough samples.

In Appendix D which is available upon request, we show for the interested reader how the standard error formulas can be derived for the portfolio example of Section 3 and the general equilibrium model of Section 5. The application of the formulas to the two examples highlights two features that determine the properties of the asymptotic distribution of the proposed estimator. In the simple portfolio example, there is a one-directional relationship between the cross-sectional and time-series submodels. As a consequence, the cross-sectional parameters can be estimated without knowledge of the time-series parameters. In addition, agents form expectations for the main variable, end-of-period wealth, that do not depend on the current realization of the aggregate shock. These two features imply that the asymptotic distribution has a simple form that is
independent of the aggregate shocks. If one of these two conditions is not satisfied, as mentioned above, the limiting distribution has a more complicated form that depends on aggregate shocks. The more complex general equilibrium example illustrates this point. In that case, the relationship between the two sub-models is bidirectional, implying that there is no recursive structure that can be used to first estimate the cross-sectional parameters without knowledge of their time-series counterparts. As a consequence, the asymptotic distribution depends on the aggregate variables needed for the estimation of the cross-sectional parameters. Moreover, agents use the current realization of the aggregate shock to form expectations about future events. Since these expectations are used in their decision making process, the aggregate shocks affect the limiting distribution of the estimator by entering the variance-covariance matrix.

7 Monte Carlo Results

In this section we report two sets of results. We first present Monte Carlo results for the general equilibrium model with the objective of illustrating how the estimation and inference approach introduced in this paper can be applied in practice, and with the additional objective of documenting the ability of our standard error formulas to produce the correct coverage probabilities for the parameters of interest. We then provide evidence on the magnitude of the bias that can be generated if the econometrician ignores aggregate shocks.

To perform the Monte Carlo simulations and determine the size of the bias, we have to set the 7 parameters of the general equilibrium model at particular values. The most consequential parameter value is the one assigned to the variance of the aggregate shocks $\omega^2$ since, as shown in Section 5, it determines the magnitude of the bias if the econometrician ignores the aggregate shocks. We chose the size of $\omega^2$ using the estimated variance of the aggregate shocks used by Kydland and Prescott (1982). They use an estimated variance for the quarterly U.S. cyclical output that is equal to 0.000165. Differently from Kydland and Prescott (1982), in our model capital is assumed to be fixed. As a consequence, the variation in aggregate shocks affects exclusively labor demand. To account for this feature of our model, we divided the variance estimated in Kydland and Prescott (1982) by the square of the labor share in the economy. Since in the U.S. the

\[21\text{The derivation of the short-run labor demand function for a Cobb-Douglas production function shows that this}\]
labor share is approximately 1/3, we divide 0.000165 by 1/9 to obtain 0.00149. In addition, in our model only one of the two sectors is affected by the aggregate shocks. To make the estimated variance consistent with our model, we have therefore to multiply it by the square of 2 (the two sectors). With this additional adjustment, we have a quarterly variance for the aggregate shock of 0.006. Our model has only two periods, one in which people engage in education and one in which those individuals work. We assume that each period is composed of 20 years and we multiply the quarterly variance of 0.006 by 4 quarters and 20 years, obtaining the aggregate variance we use in the simulations, 0.48.

The values assigned to the variances of the productivity shocks $\sigma_F^2$ and $\sigma_R^2$ are also important for the outcome of the Monte Carlo exercise, since they determine the size of the individual-level uncertainty relative to the size of the aggregate uncertainty. We chose those variances using the estimated variance of the productivity shocks reported in Macurdy (1982). Macurdy (1982) estimates a variance for the residuals of yearly wages in the U.S. that is between 0.062 and 0.054. To derive our measures of the micro variances, we multiply the upper bound of the yearly variance estimated by Macurdy by 20 years (one of our periods), obtaining 1.2. Lastly, in our model the micro shocks in sector $F$ have a smaller variance than the shocks in sector $R$. To account for this, we set $\sigma_F^2 = 1$ and $\sigma_R^2 = 1.4$. The mean variance of the micro shocks is therefore 1.2, which corresponds to the estimate obtained using the results in Macurdy (1982).

The remaining parameters are set equal to the following values. The mean of the log of the risk aversion parameter $\mu$ is set equal to 0.2, which corresponds to a mean risk aversion parameter of approximately 2. The parameter measuring the persistence of the aggregate shock $\rho$ is initially set equal to 0.75. We then evaluate how the results change when it is first increased to 0.9 and then reduced to 0.5. The constant $\alpha_0$ and slope $\alpha_1$ of the labor demand functions are chosen to be equal to 7 and -1, respectively. The parameter characterizing the preferences for consumption $\sigma$ is set equal to 0.6.

In the Monte Carlo exercise we consider 9 different specifications depending on the size of the cross-section sample and length of the time-series sample. Specifically, we simulate the model and estimate the parameters using the following sample sizes for the cross-section: 2,500, 5,000, and
10,000 individuals; and the following lengths for the time-series: 25, 50, and 100 periods. In all cases we generate 5000 simulated data sets for the general equilibrium model. The Monte Carlo results obtained using the method proposed in this paper are presented in Table 1. The bias generated by ignoring the aggregate shocks is reported in Table 2. We only report results for the parameters \( \mu, \rho, \) and \( \omega^2 \). All the other parameters are estimated using the same estimators in the correct and misspecified model. The estimates are therefore identical in the two models. Moreover, they are estimated precisely and without significant bias in all Monte Carlo specifications.

We start by discussing the performance of the proposed approach. In the second column of Table 1 we report the selected parameter estimates and in the third column the coverage probability for those parameters of a confidence interval with 90% nominal coverage probability.

Table 1 documents that the accuracy of the estimates increases with the length of the time-series. When the length of the time-series increases from 25 to 100 the estimated persistence parameter \( \rho \) goes from 0.700, 0.050 lower than the true parameter, to about 0.735, just 0.015 lower than the true parameter. The size of the cross-section has no effect on the estimated value of \( \rho \). A similar pattern characterizes the estimates of the variance of the aggregate shocks, except that in this case the size of the cross-section has a small effect on the estimation results. For a cross-section of 10,000 individuals, an increase from 25 to 100 periods produces a decline in the estimated \( \omega^2 \) from 0.504, 0.024 higher than the true parameter, to 0.486, just 0.06 above the true value. Similar trends characterize the estimates of \( \omega^2 \) for cross-sections of 2,500 and 5,000, except that the accuracy of the estimates improves slightly with larger cross-sections.

In the estimation of the risk aversion parameter \( \mu \), we replace the other parameters that enter the educational decision (26) with their estimated values. The small biases in the estimation of \( \rho \)

\[ \Theta_t = \log \left( \frac{n p_{t+1}}{n_{t+1}} \right) + \frac{\sigma_f - \sigma^2}{2} + \rho \log \nu_t \]

In the model, \( \Theta_t \) is always smaller than 1 and, hence, \( \log(1 - \Theta_t) \) is always well defined. In the estimation of \( \mu \), however, the true parameters included in \( \Theta_t \) are replaced with their estimated values. In some of the Monte Carlo repetitions, the randomness of the estimated parameters generates values of \( \Theta_t \) that are greater than 1, which implies that \( \log(1 - \Theta_t) \) is not well defined. A similar problem arises when we estimate the misspecified model. The results reported in this Section are obtained by dropping all simulations for which \( \Theta_t \geq 1 \). In Appendix F we report the results obtained by using all the Monte Carlo runs and by setting \( \Theta = 0.99 \) in all cases in which \( \Theta \geq 1 \).
and $\omega^2$ will therefore affect the estimation of $\mu$, and generate patterns that are similar to the ones observed for $\rho$ and $\omega^2$ when we increase the length of the time-series and the size of the cross-section. For instance, with a cross-section of 10,000 individuals, when we increase the time-series from 25 to 100 periods the estimated $\mu$ increases from 0.166, 0.036 below the true parameter, to 0.188, just 0.012 below the true value. To confirm that the small bias in the estimation of $\mu$ is generated by the small biases that characterize the other parameters, we have also estimated $\mu$ using the educational decision and the true value of the other parameters. We will refer to this estimator as the infeasible estimator. The estimated values obtained using this estimator, which by construction varies only with the length of the time series, are reported in Table 1. They are always identical to the true parameter, which confirms that the small bias in the estimation of $\mu$ is generated by the small bias introduced by the other parameters. These results indicate that it is important to use a long time-series when estimating a model with aggregates shocks to reduce the noise introduced by the estimation of the other parameters. A long time-series of aggregate variables should therefore be preferred to a panel of data, since available panels have a short time dimension.

We now describe the estimation of the risk aversion parameter using only cross-sectional data. As discussed in Section 5, the parameter $\mu$ requires both cross-section and time-series variation to be consistently estimated. If the econometrician uses only cross-sectional data, the estimated $\mu$ will be biased. In Table 2 we report the estimated $\mu$ and the corresponding bias only for the three time-series, since the results are nearly identical across cross-sections. The numbers indicate that the bias is positive, extremely large, and similar for all time-series. In all cases, $\mu$ is estimated to be about six times the true parameter and the bias to be about five times the true value. A bias of this magnitude can have significant consequences if the estimated parameter is used to answer policy questions, with answers that can be considerably different from the ones that should be obtained.

In Tables 3 and 4 we also report the effect of changing the persistence of the aggregate shock by increasing $\rho$ from 0.75 to 0.9 and by reducing it from 0.75 to 0.5 for the the specification with 10,000 people and 100 periods. The effect is small. When we use our proposed method the estimated coefficients are close to the true values. But if one ignores the aggregate shocks the bias is large and positive.
Our Monte Carlo results indicate that ignoring aggregate shocks that affect the data can have large effects on the estimation of important parameters, such as the coefficient of risk aversion, and on the policy evaluations which are based on them. Our results also indicate that the estimation method we propose performs well. Given that it is relatively straightforward to use, it is an easy solution for dealing with the presence of aggregate shocks.

8 Summary

Using a general econometric framework and three examples we shown that generally, when aggregate shocks are present, model parameters cannot be identified using cross-sectional variation alone. Identification of those parameters requires the combination of cross-sectional and time-series data. When those two data sources are jointly used, there are no available formulas for the computation of test statistics and confidence intervals. We provide new easy-to-use formulas that account for the interaction between those data sources. Our results are expected to be helpful for the econometric analysis of rational expectations models involving individual decision making as well as general equilibrium models.

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Table 1: Monte Carlo Results, Parameter Estimates For Correct Model

| True Parameter                                      | Estimate | Cov. Prob. |
|-----------------------------------------------------|----------|------------|
| **Cross-sectional Sample Size: 2,500, Time-series Sample Size: 25** |          |            |
| Log Risk Aversion Mean: $\mu = 0.2$                 | 0.157    | 0.902      |
| Aggregate Shock Persistence: $\rho = 0.75$          | 0.700    | 0.875      |
| Variance of Aggregate Shock: $\sigma^2 = 0.48$      | 0.514    | 0.840      |
| **Cross-sectional Sample Size: 2,500, Time-series Sample Size: 50** |          |            |
| Log Risk Aversion Mean: $\mu = 0.2$                 | 0.173    | 0.922      |
| Aggregate Shock Persistence: $\rho = 0.75$          | 0.722    | 0.892      |
| Variance of Aggregate Shock: $\sigma^2 = 0.48$      | 0.502    | 0.867      |
| **Cross-sectional Sample Size: 2,500, Time-series Sample Size: 100** |          |            |
| Log Risk Aversion Mean: $\mu = 0.2$                 | 0.177    | 0.929      |
| Aggregate Shock Persistence: $\rho = 0.75$          | 0.735    | 0.888      |
| Variance of Aggregate Shock: $\sigma^2 = 0.48$      | 0.495    | 0.888      |
| Infeasible estimator of Log Risk Aversion Mean, Cross-section of 2,500: 0.1997 | | |
| **Cross-sectional Sample Size: 5,000, Time-series Sample Size: 25** |          |            |
| Log Risk Aversion Mean: $\mu = 0.2$                 | 0.158    | 0.900      |
| Aggregate Shock Persistence: $\rho = 0.75$          | 0.700    | 0.871      |
| Variance of Aggregate Shock: $\sigma^2 = 0.48$      | 0.508    | 0.838      |
| **Cross-sectional Sample Size: 5,000, Time-series Sample Size: 50** |          |            |
| Log Risk Aversion Mean: $\mu = 0.2$                 | 0.180    | 0.918      |
| Aggregate Shock Persistence: $\rho = 0.75$          | 0.722    | 0.887      |
| Variance of Aggregate Shock: $\sigma^2 = 0.48$      | 0.495    | 0.868      |
| **Cross-sectional Sample Size: 5,000, Time-series Sample Size: 100** |          |            |
| Log Risk Aversion Mean: $\mu = 0.2$                 | 0.178    | 0.932      |
| Aggregate Shock Persistence: $\rho = 0.75$          | 0.736    | 0.888      |
| Variance of Aggregate Shock: $\sigma^2 = 0.48$      | 0.489    | 0.888      |
| Infeasible estimator of Log Risk Aversion Mean, Cross-section of 5,000: 0.1998 | | |
| **Cross-sectional Sample Size: 10,000, Time-series Sample Size: 25** |          |            |
| Log Risk Aversion Mean: $\mu = 0.2$                 | 0.166    | 0.896      |
| Aggregate Shock Persistence: $\rho = 0.75$          | 0.700    | 0.870      |
| Variance of Aggregate Shock: $\sigma^2 = 0.48$      | 0.504    | 0.835      |
| **Cross-sectional Sample Size: 10,000, Time-series Sample Size: 50** |          |            |
| Log Risk Aversion Mean: $\mu = 0.2$                 | 0.183    | 0.914      |
| Aggregate Shock Persistence: $\rho = 0.75$          | 0.722    | 0.883      |
| Variance of Aggregate Shock: $\sigma^2 = 0.48$      | 0.492    | 0.859      |
| **Cross-sectional Sample Size: 10,000, Time-series Sample Size: 100** |          |            |
| Log Risk Aversion Mean: $\mu = 0.2$                 | 0.188    | 0.923      |
| Aggregate Shock Persistence: $\rho = 0.75$          | 0.736    | 0.882      |
| Variance of Aggregate Shock: $\sigma^2 = 0.48$      | 0.486    | 0.887      |
| Infeasible estimator of Log Risk Aversion Mean, Cross-section of 10,000: 0.200 | | |

Notes: This Table reports the Monte Carlo results for the correct model obtained using our proposed estimation method. They are derived by simulating the general equilibrium model 5000 times. The second column reports the average estimated parameter, where the average is computed over the 5000 simulations. Column 3 reports the coverage probability of a confidence interval with 90% nominal coverage probability.
Table 2: Monte Carlo Results, Risk Aversion Estimates For Misspecified Model

| True Parameter | Estimate | Bias  |
|----------------|----------|-------|
| **Cross-sectional Sample Size: 2,500** |          |       |
| Log Risk Aversion Mean: $\mu = 0.2$ | 1.163    | 0.963 |
| **Cross-sectional Sample Size: 5,000** |          |       |
| Log Risk Aversion Mean: $\mu = 0.2$ | 1.173    | 0.973 |
| **Cross-sectional Sample Size: 10,000** |          |       |
| Log Risk Aversion Mean: $\mu = 0.2$ | 1.179    | 0.979 |

Notes: This Table reports the Monte Carlo results for the misspecified model obtained using only cross-sectional variation. They are derived by simulating the general equilibrium model 5000 times. The second column reports the average estimated parameter, where the average is computed over the 5000 simulations. Column 3 reports the estimation bias, which is computed as the difference between the estimated and true parameter.

Table 3: Monte Carlo Results, Parameter Estimates For Correct Model, Different $\rho$’s

| True Parameter | Estimate | Cov. Prob. |
|----------------|----------|------------|
| **Cross-sectional Sample Size: 10,000, Time-series Sample Size: 100** |          |            |
| Log Risk Aversion Mean: $\mu = 0.2$ | 0.212    | 0.920      |
| Aggregate Shock Persistence: $\rho = 0.9$ | 0.883    | 0.890      |
| Variance of Aggregate Shock: $\omega^2 = 0.48$ | 0.490    | 0.890      |
| **Cross-sectional Sample Size: 10,000, Time-series Sample Size: 100** |          |            |
| Log Risk Aversion Mean: $\mu = 0.2$ | 0.179    | 0.930      |
| Aggregate Shock Persistence: $\rho = 0.5$ | 0.490    | 0.885      |
| Variance of Aggregate Shock: $\omega^2 = 0.48$ | 0.488    | 0.889      |

See notes at Table 1.
Table 4: Monte Carlo Results, Risk Aversion Estimates For Misspecified Model, Different \( \rho \)'s

| True Parameter | Estimate | Bias |
|----------------|----------|------|
| **Cross-sectional Sample Size: 10,000, \( \rho = 0.9 \)** | | |
| Log Risk Aversion Mean: \( \mu = 0.2 \) | 1.203 | 1.003 |
| **Cross-sectional Sample Size: 10,000, \( \rho = 0.5 \)** | | |
| Log Risk Aversion Mean: \( \mu = 0.2 \) | 1.163 | 0.963 |

See notes at Table 2.

Appendix – Available Upon Request

A Discussion for Section 3

A.1 Proof of (2)

The maximization problem is equivalent to

\[
\max_{\alpha} -e^{-\delta(\alpha+r)+(1-\alpha)} E\left[e^{-\delta(1-\alpha)u_{i,t}}\right].
\]

Since \(-\delta (1 - \alpha) u_{i,t} \sim N(-\delta (1 - \alpha) \mu, \delta^2 (1 - \alpha)^2 \sigma^2)\), we have

\[
E\left[e^{-\delta(1-\alpha)u_{i,t}}\right] = e^{-\delta(1-\alpha)\mu+\frac{\delta^2(1-\alpha)^2}{2}\sigma^2},
\]

and the maximization problem can be rewritten as follows:

\[
\max_{\alpha} -e^{-\delta\left(\alpha(1+r)+(1-\alpha)(1+\mu)-\frac{\delta(1-\alpha)^2\sigma^2}{2}\right)}.
\]

Taking the first order condition, we have,

\[
0 = -\delta \left(r - \mu + \sigma^2 \delta - \alpha \sigma^2 \delta\right)
\]

from which we obtain the solution

\[
\alpha = \frac{1}{\sigma^2 \delta}\left(r - \mu + \sigma^2 \delta\right).
\]
A.2 Euler Equation and Cross Section

Our model in Section 3 is a stylized version of many models considered in a large literature interested in estimating the parameter $\delta$ using cross-sectional variation. Estimators are often based on moment conditions derived from first order conditions (FOC) related to optimal investment and consumption decisions. We illustrate the problems facing such estimators.

Assume a researcher has a cross-section of observations for individual consumption and returns $c_{i,t}$ and $u_{i,t}$. The population FOC of our model takes the simple form $E[e^{-\delta c_{i,t}}(r-u_{i,t})] = 0$. A just-identified moment based estimator for $\delta$ solves the sample analog $n^{-1}\sum_{i=1}^{n} e^{-\hat{\delta} c_{i,t}} (r-u_{i,t}) = 0$. It turns out that the probability limit of $\hat{\delta}$ is equal to $(\nu_t - r)/((1-\alpha)\sigma^2_t)$, i.e., $\hat{\delta}$ is inconsistent.

We now compare the population FOC a rational agent uses to form their optimal portfolio with the empirical FOC an econometrician using cross-sectional data observes:

$$n^{-1}\sum_{i=1}^{n} e^{-\delta c_{i,t}} (r-u_{i,t}) = 0.$$  

Noting that $u_{i,t} = \nu_t + \epsilon_{i,t}$ and substituting into the budget constraint

$$c_{i,t} = 1 + \alpha r + (1-\alpha) u_{i,t} = 1 + \alpha r + (1-\alpha) \nu_t + (1-\alpha) \epsilon_{i,t}$$

we have

$$n^{-1}\sum_{i=1}^{n} e^{-\delta c_{i,t}} (r-u_{i,t}) = n^{-1}\sum_{i=1}^{n} e^{-\delta (1+\alpha r+(1-\alpha)\nu_t)-\delta(1-\alpha)\epsilon_{i,t}} (r-\nu_t-\epsilon_{i,t})$$

$$= e^{-\delta (1+\alpha r+(1-\alpha)\nu_t)} (r-\nu_t) n^{-1}\sum_{i=1}^{n} e^{-\delta(1-\alpha)\epsilon_{i,t}} - n^{-1}\sum_{i=1}^{n} e^{-\delta(1-\alpha)\epsilon_{i,t}} \epsilon_{i,t}.$$  \hspace{1cm} (35)

Under suitable regularity conditions including independence of $\epsilon_{i,t}$ in the cross-section it follows that

$$n^{-1}\sum_{i=1}^{n} e^{-\delta(1-\alpha)\epsilon_{i,t}} = E[e^{-\delta(1-\alpha)\epsilon_{i,t}}] + o_p(1) = e^{\frac{\delta^2(1-\alpha)^2\sigma^2}{2}} + o_p(1) \hspace{1cm} (36)$$

\hspace{1cm} \text{We assume $\delta \neq 0$ and rescale the equation by $-\delta^{-1}$.}
and
\[ n^{-1} \sum_{i=1}^{n} e^{-\delta(1-\alpha)e_{i,t}e_{i,t}} = E\left[e^{-\delta(1-\alpha)e_{i,t}e_{i,t}}\right] + o_p(1) = -\delta (1 - \alpha) \sigma_e^2 e^{\frac{\delta^2(1-\alpha)^2\sigma_e^2}{2}} + o_p(1). \tag{37} \]

Taking limits as \( n \to \infty \) in (35) and substituting (36) and (37) then shows that the method of moments estimator based on the empirical FOC asymptotically solves
\[ \left( (r - \nu_t) + \delta (1 - \alpha) \sigma_e^2 \right) e^{\frac{\delta^2(1-\alpha)^2\sigma_e^2}{2}} = 0. \tag{38} \]

Solving for \( \delta \) we obtain
\[ \text{plim } \hat{\delta} = \frac{\nu_t - r}{(1 - \alpha) \sigma_e^2}. \]

This estimate is inconsistent because the cross-sectional data set lacks cross sectional ergodicity, or in other words does not contain the same information about aggregate risk as is used by rational agents. Therefore, the empirical version of the FOC is unable to properly account for aggregate risk and return characterizing the risky asset. The estimator based on the FOC takes the form of an implicit solution to an empirical moment equation, which obscures the effects of cross-sectional non-ergodicity. A more illuminative approach uses our modelling strategy in Section 2.

On the other hand, it is easily shown using properties of the Gaussian moment generating function that the population FOC is proportional to
\[ E\left[e^{-\delta(1-\alpha)u_{i,t} (r - u_{i,t})}\right] = (r - \mu + \delta (1 - \alpha) \sigma_e^2) e^{-\delta(1-\alpha)\mu + \frac{\delta^2(1-\alpha)^2\sigma_e^2}{2}} = 0. \tag{39} \]

The main difference between (36) and (37) lies in the fact that \( \sigma_v^2 \) is estimated to be 0 in the sample and that \( \nu_t \neq \mu \) in general. Note that (39) implies that consistency may be achieved with a large number of repeated cross sections, or a panel data set with a long time series dimension. However, this raises other issues discussed in Section C.
B Details of Section 5

B.1 Proof of (26)

In the proof we will drop the \( i \) subscripts for notational purposes. The individual will choose education \( F \) if

\[
E \left[ V_{t+1} \left( F, \nu_{t+1}, \varepsilon_{t+1}^F \right) \right] \geq E \left[ V_{t+1} \left( R, \nu_{t+1}, \varepsilon_{t+1}^R \right) \right].
\]

Using (49) and (50) later in Section B.2, we write

\[
V_{t+1} \left( F, \nu_{t+1}, \varepsilon_{t+1}^F \right) = \left( \left( \frac{n_{t+1}^F \sigma T}{e^{\alpha_0}} \right)^{1/\alpha_1} \sigma T \right)^\sigma \frac{1}{(1-\sigma) T^{1-\sigma}}^{1-\gamma} \exp \left( \sigma \frac{(1/\alpha_1)(1-\gamma)}{\varepsilon_{t+1}^F} \right),
\]

and

\[
V_{t+1} \left( R, \nu_{t+1}, \varepsilon_{t+1}^R \right) = \left( \left( \frac{n_{t+1}^R \sigma T}{e^{\alpha_0}} \right)^{1/\alpha_1} \sigma T \right)^\sigma \frac{1}{(1-\sigma) T^{1-\sigma}}^{1-\gamma} \exp \left( \sigma \frac{(1/\alpha_1)(1-\gamma)}{\varepsilon_{t+1}^R} \right) \times \left( \nu_{t+1}^{-(1/\alpha_1)(1-\gamma)} \right).
\]

It follows that education \( F \) is chosen if and only if

\[
\left( n_{t+1}^F \right)^{\sigma(1-\gamma)/\alpha_1} \geq \left( n_{t+1}^R \right)^{\sigma(1-\gamma)/\alpha_1} \times E \left[ \exp \left( \sigma \frac{(1/\alpha_1)(1-\gamma)}{\varepsilon_{t+1}^R} \right) \right] \times \frac{E \left[ \exp \left( \sigma \frac{(1/\alpha_1)(1-\gamma)}{\varepsilon_{t+1}^F} \right) \right]}{E \left[ \exp \left( \sigma \frac{(1/\alpha_1)(1-\gamma)}{\varepsilon_{t+1}^R} \right) \right]}. \tag{40}
\]

Recall that \( E \left[ \exp \left( \varepsilon^S_t \right) \right] = 1 \) for \( S = F, R \). It follows that \( \varepsilon_{t+1}^F \sim N \left( -\frac{\sigma_F^2}{2}, \sigma_F^2 \right) \), and \( \varepsilon_{t+1}^R \sim N \left( -\frac{\sigma_R^2}{2}, \sigma_R^2 \right) \), and as a consequence,

\[
E \left[ \exp \left( \frac{\sigma}{\alpha_1} \varepsilon_{t+1}^F \right) \right] = \exp \left( -\frac{\sigma}{2} \frac{(1/\alpha_1)(1-\gamma)}{2} \sigma_F^2 + \frac{(\sigma(1/\alpha_1)(1-\gamma))^2}{2} \sigma_F^2 \right), \tag{41}
\]

\[
E \left[ \exp \left( \frac{\sigma}{\alpha_1} \varepsilon_{t+1}^R \right) \right] = \exp \left( -\frac{\sigma}{2} \frac{(1/\alpha_1)(1-\gamma)}{2} \sigma_R^2 + \frac{(\sigma(1/\alpha_1)(1-\gamma))^2}{2} \sigma_R^2 \right). \tag{42}
\]
Also, because \( \log \nu_{t+1} = \rho \log \nu_t + \eta_t \), or \( \nu_{t+1} = \nu_t^\rho \exp(\eta_t) \), we can write

\[
E_t \left[ \nu_{t+1}^{-\sigma(1-\gamma)(1/\alpha_1)} \right] = E_\eta \left[ \left( \nu_t^\rho \exp(\eta_t) \right)^{-\sigma(1-\gamma)(1/\alpha_1)} \right] = \nu_t^{-\rho\sigma(1-\gamma)(1/\alpha_1)} E \left[ \exp \left( -\sigma \left( \frac{1}{\alpha_1} \right) \eta_t \right) \right].
\]

where \( E_\eta [\cdot] \) denotes the integral with respect to \( \eta_t \) alone. The assumption that \( \eta_t \sim N(0, \omega^2) \) allows us to write

\[
E \left[ \exp \left( -\sigma \left( \frac{1}{\alpha_1} \right) \eta_t \right) \right] = \exp \left( \frac{(\sigma \left( \frac{1}{\alpha_1} \right))^2}{2} \omega^2 \right)
\]

recognizing that the expectation on the left is nothing but the moment generating function of \( N(0, \omega^2) \) evaluated at \( -\sigma \left( \frac{1}{\alpha_1} \right) \). Therefore, we have

\[
E_t \left[ \nu_{t+1}^{-\sigma(1-\gamma)(1/\alpha_1)} \right] = \nu_t^{-\rho\sigma(1-\gamma)(1/\alpha_1)} \exp \left( \frac{(\sigma \left( \frac{1}{\alpha_1} \right))^2}{2} \omega^2 \right) \tag{43}
\]

Combining (41), (42), and (43), we obtain

\[
E \left[ \exp \left( \sigma \left( \frac{1}{\alpha_1} \right) (1-\gamma) \varepsilon_{t+1}^R \right) \right] E_t \left[ \nu_{t+1}^{-\sigma(1/\alpha_1)(1-\gamma)} \right] \frac{E \left[ \exp \left( \sigma \left( \frac{1}{\alpha_1} \right) (1-\gamma) \varepsilon_{t+1}^F \right) \right]}{E \left[ \exp \left( \sigma \left( \frac{1}{\alpha_1} \right) (1-\gamma) \varepsilon_{t+1}^R \right) \right]}
\]

\[
= \nu_t^{-\rho\sigma(1-\gamma)(1/\alpha_1)} \exp \left( \frac{(\sigma \left( \frac{1}{\alpha_1} \right))^2}{2} \frac{\sigma_R^2 - \sigma_F^2 + \omega^2}{\sigma_R^2 - \sigma_F^2} \right) \times \exp \left( -\frac{\sigma \left( \frac{1}{\alpha_1} \right) (1-\gamma) (\sigma_R^2 - \sigma_F^2)}{2} \right)
\]

As a consequence, (40) is equivalent to

\[
(n_{t+1}^F)^{\sigma(1-\gamma)/\alpha_1} \geq (n_{t+1}^R)^{\sigma(1-\gamma)/\alpha_1} \frac{\nu_t^{-\rho\sigma(1-\gamma)(1/\alpha_1)} \exp \left( \frac{(\sigma \left( \frac{1}{\alpha_1} \right))^2}{2} \frac{\sigma_R^2 - \sigma_F^2 + \omega^2}{\sigma_R^2 - \sigma_F^2} \right)}{\exp \left( -\frac{\sigma \left( \frac{1}{\alpha_1} \right) (1-\gamma) (\sigma_R^2 - \sigma_F^2)}{2} \right)} \tag{44}
\]
when $1 - \gamma > 0$, and to

\[
(n_{t+1}^F)^{\sigma(1-\gamma)/\alpha_1} \leq (n_{t+1}^R)^{\sigma(1-\gamma)/\alpha_1} \nu_t^{-\rho \sigma(1-\gamma)(1/\alpha_1)} \exp \left( \frac{(\sigma - \rho \sigma(1-\gamma))(1/\alpha_1)^2}{\sigma^2_R - \sigma^2_F + \omega^2} \right) \times \exp \left( -\frac{\sigma(1/\alpha_1)(1-\gamma)(\sigma^2_R - \sigma^2_F)}{2} \right)
\]

(45)

when $1 - \gamma < 0$.

Consider first the case $1 - \gamma > 0$. Taking logs of (44), we obtain

\[
\frac{\sigma(1-\gamma)}{\alpha_1} \log n^F_{t+1} - \frac{\sigma(1-\gamma)}{\alpha_1} \log n^R_{t+1} - \rho \frac{\sigma(1-\gamma)}{\alpha_1} \log \nu_t + \frac{(\sigma(1-\gamma))^2}{2\alpha_1^2} (\sigma^2_R - \sigma^2_F + \omega^2) - \frac{\sigma(1/\alpha_1)(1-\gamma)(\sigma^2_R - \sigma^2_F)}{2}.
\]

Dividing by $\sigma$ and multiplying by $\alpha_1 < 0$, we conclude that the decision is equivalent to

\[
\frac{(1-\gamma)^2 (\sigma^2_R - \sigma^2_F + \omega^2)}{2\alpha_1^2} \leq \frac{(\sigma(1-\gamma))^2 (\sigma^2_R - \sigma^2_F)}{2\alpha_1^2}.
\]

Dividing by $\sigma (1-\gamma) (\sigma^2_R - \sigma^2_F + \omega^2) > 0$, we obtain

\[
\frac{\log n^F_{t+1} + \frac{\sigma^2_R - \sigma^2_F}{2} + \rho \log \nu_t}{\sigma^2_R - \sigma^2_F + \omega^2} \leq \frac{1-\gamma}{2\alpha_1}.
\]

Multiplying by $2\alpha_1 < 0$, we obtain

\[
\frac{\log n^F_{t+1} + \frac{\sigma^2_R - \sigma^2_F}{2} + \rho \log \nu_t}{\sigma^2_R - \sigma^2_F + \omega^2} \geq 1 - \gamma.
\]

or

\[
\gamma \geq 1 - \frac{\log \left( \frac{n^F_{t+1}}{n^R_{t+1}} \right) + \frac{\sigma^2_R - \sigma^2_F}{2} + \rho \log \nu_t}{\sigma^2_R - \sigma^2_F + \omega^2}
\]

which proves inequality (26) for the $1 - \gamma > 0$ case.
Consider now the case $1 - \gamma < 0$. Taking logs of (45), we obtain

$$\frac{\sigma (1 - \gamma)}{\alpha_1} \log n_{t+1}^F \leq \frac{\sigma (1 - \gamma)}{\alpha_1} \log n_{t+1}^R - \rho \frac{\sigma (1 - \gamma)}{\alpha_1} \log \nu_t$$

$$+ \frac{(\sigma (1 - \gamma))^2}{2\alpha_1^2} (\sigma_R^2 - \sigma_F^2 + \omega^2) - \frac{\sigma (1/\alpha_1) (1 - \gamma) (\sigma_R^2 - \sigma_F^2)}{2}$$

Dividing by $\sigma$ and multiplying by $\alpha_1 < 0$, we conclude that the decision is equivalent to

$$(1 - \gamma) \left( \log \frac{n_{t+1}^F}{n_{t+1}^R} + \frac{\sigma_R^2 - \sigma_F^2}{2} + \rho \log \nu_t \right) \geq \frac{\sigma (1 - \gamma)^2 (\sigma_R^2 - \sigma_F^2 + \omega^2)}{2\alpha_1}$$

Dividing by $\sigma (1 - \gamma) (\sigma_R^2 - \sigma_F^2 + \omega^2) < 0$, we obtain

$$\frac{\log \frac{n_{t+1}^F}{n_{t+1}^R} + \frac{\sigma_R^2 - \sigma_F^2}{2} + \rho \log \nu_t}{\sigma (\sigma_R^2 - \sigma_F^2 + \omega^2)} \leq \frac{(1 - \gamma)}{2\alpha_1}$$

Multiplying by $2\alpha_1 < 0$, we obtain

$$\frac{\log \frac{n_{t+1}^F}{n_{t+1}^R} + \frac{\sigma_R^2 - \sigma_F^2}{2} + \rho \log \nu_t}{\sigma (\sigma_R^2 - \sigma_F^2 + \omega^2)} \geq 1 - \frac{(1 - \gamma)}{2\alpha_1}$$

or

$$\gamma \geq 1 - \frac{\log \frac{n_{t+1}^F}{n_{t+1}^R} + \frac{\sigma_R^2 - \sigma_F^2}{2} + \rho \log \nu_t}{\sigma (\sigma_R^2 - \sigma_F^2 + \omega^2) \frac{2\alpha_1}}$$

which proves inequality (26) for the $1 - \gamma < 0$ case as well.

**B.2 Proof of (24) and (25)**

Note that individual heterogeneity is completely summarized by the vector $\chi_t \equiv (\varepsilon_t^F, \varepsilon_t^R, \gamma)$. This means that the labor supply for each type $\chi$ of workers can be written $h_t^F(\chi)$ and $h_t^R(\chi)$. We assume that the measure of individuals such that $(\varepsilon_t^F, \varepsilon_t^R, \gamma) \in A$ for some $A \subset \mathbb{R}^3$ is given by $N_t \int_A G(d\chi)$, where $G$ is a joint CDF. For simplicity, we assume that $G$ is such that the first and second components are independent of each other. Recall that we also assume that $\int \exp (\varepsilon_t) G(d\chi) = 1$. 7
We can rewrite (23) as follows:

\[
E \left[ \frac{\left( \sigma w_{t+1}^F \left( \nu_{t+1} \right) \exp \left( \varepsilon_{t+1}^F \right) \right)^\sigma (1 - \sigma) T^{1-\sigma}}{1 - \gamma} \right] \nu_t \right] \geq E \left[ \frac{\left( \sigma w_{t+1}^R \left( \nu_{t+1} \right) \exp \left( \varepsilon_{t+1}^R \right) \right)^\sigma (1 - \sigma) T^{1-\sigma}}{1 - \gamma} \right] \nu_t \right].
\]

As a consequence, education \( F \) is chosen if

\[
\psi (\gamma, \nu_t) \equiv E \left[ \frac{\left( \sigma w_{t+1}^F \left( \nu_{t+1} \right) \exp \left( \varepsilon_{t+1}^F \right) \right)^\sigma (1 - \gamma)}{1 - \gamma} \right] \nu_t ] - E \left[ \frac{\left( \sigma w_{t+1}^R \left( \nu_{t+1} \right) \exp \left( \varepsilon_{t+1}^R \right) \right)^\sigma (1 - \gamma)}{1 - \gamma} \right] \nu_t \right] \geq 0
\]

Specifically, an individual chooses \( F \) if \( \psi (\gamma, \nu_t) > 0 \). We can now introduce the equilibrium condition for education \( F \). It takes the following form:

\[
H_{t+1}^{D,F} = N_{t+1} \int_{E=F} h_{t+1}^F (\chi) G \left( d\chi \right) = N_{t+1} \sigma T \int_{\psi(\gamma,\nu_t) \geq 0} \exp \left( \varepsilon_{t+1}^F \right) G \left( d\chi \right)
\]

\[
H_{t+1}^{D,R} = N_{t+1} \int_{E=R} h_{t+1}^R (\chi) G \left( d\chi \right) = N_{t+1} \sigma T \int_{\psi(\gamma,\nu_t) < 0} \exp \left( \varepsilon_{t+1}^R \right) G \left( d\chi \right)
\]

Using independence between \( \gamma \) and \( \varepsilon \) as well as \( \int \exp \left( \varepsilon_{t+1}^F \right) G \left( d\chi \right) = 1 \), we can write

\[
\int_{\psi(\gamma,\nu_t) \geq 0} \exp \left( \varepsilon_{t+1}^F \right) G \left( d\chi \right) = \left( \int_{\psi(\gamma,\nu_t) \geq 0} G \left( d\chi \right) \right) \left( \int \exp \left( \varepsilon_{t+1}^F \right) G \left( d\chi \right) \right)
\]

\[
= \int_{\psi(\gamma,\nu_t) \geq 0} G \left( d\chi \right)
\]

\[
= \text{Fraction of workers in Sector } F
\]

so we can write \( H_{t+1}^{D,F} = n_t^F \sigma T \), where \( n_t^F \) is the measure of individuals that chose education \( F \).

Taking logs, we have:

\[
\log H_{t+1}^{D,F} = \log n_t^F + \log \sigma + \log T,
\]

Substituting for \( H_{t+1}^{D,F} \), we obtain the following equilibrium condition:

\[
\alpha_0 + \alpha_1 \log w_{t+1}^F = \log n_t^F + \log \sigma + \log T,
\]

8
Solving for $\log w^F_t$, we have the log equilibrium wage:

\[
(z^F_t \equiv) \quad \log w^F_t = \frac{\log n^F_t + \log \sigma + \log T - \alpha_0}{\alpha_1}.
\] (49)

This wage is for the unit of effective labor. Because the worker $i$ provides $\sigma \exp(\varepsilon_t) T$ of effective labor, his recorded earning is $\sigma \exp(\varepsilon_t) T \exp \left( \frac{\log n^F_t + \log \sigma + \log T - \alpha_0}{\alpha_1} \right)$. Because the individual works for $\sigma T$ hours, his wage for the labor is $\exp(\varepsilon_t) \exp \left( \frac{\log n^F_t + \log \sigma + \log T - \alpha_0}{\alpha_1} \right)$; we will assume that the cross section “error” consist of $n$ i.i.d. copies of $\varepsilon_t$, i.e., the observed log equilibrium individual wage follows:

\[
\log w^F_{it} = \frac{\log n^F_t + \log \sigma + \log T - \alpha_0}{\alpha_1} + \varepsilon^F_{it}.
\]

Because of the normalization $E \left[ \exp \left( \varepsilon^R_{it} \right) \right] = 1$, the second equality in (48) also applies to the $R$ sector, and as a consequence, the equilibrium condition for education $R$ has the following form:

\[
H^{D,R}_t = n^R_t \sigma T,
\]

where $n^R_t$ is the measure of individuals that chose education $R$. Substituting for $H^{D,R}_t$ and solving for $\log w^R_t$, we obtain the following equilibrium wage for $R$:

\[
(z^R_t \equiv) \quad \log w^R_t = \frac{\log n^R_t + \log \sigma + \log T - \alpha_0 - \log \nu_t}{\alpha_1}.
\] (50)

By the same reasoning, the observed log equilibrium wage would look like

\[
\log w^R_{it} = \frac{\log n^R_t + \log \sigma + \log T - \alpha_0 - \log \nu_t}{\alpha_1} + \varepsilon^R_{it}.
\]

C Long Panels?

Our proposal requires access to two data sets, a cross-section (or short panel) and a long time series of aggregate variables. One may wonder whether we may obtain an estimator with similar properties by exploiting panel data sets in which the time series dimension of the panel data is
large enough.

One obvious advantage of combining two sources of data is that time series data may contain variables that are unavailable in typical panel data sets. For example the inflation rate potentially provides more information about aggregate shocks than is available in panel data. We argue with a toy model that even without access to such variables, the estimator based on the two data sets is expected to be more precise, which suggests that the advantage of data combination goes beyond availability of more observable variables.

Consider the alternative method based on one long panel data set, in which both \( n \) and \( T \) go to infinity. Since the number of aggregate shocks \( \nu_t \) increases as the time-series dimension \( T \) grows, we expect that the long panel analysis can be executed with tedious yet straightforward arguments by modifying ideas in Hahn and Kuersteiner (2002), Hahn and Newey (2004) and Gagliardini and Gourieroux (2011), among others.

We will now illustrate a potential problem with the long panel approach with a simple artificial example. Suppose that the econometrician is interested in the estimation of a parameter \( \gamma \) that characterizes the following system of linear equations:

\[
q_{i,t} = x_{i,t}\frac{\gamma}{\omega} + \nu_t + \varepsilon_{i,t}\quad i = 1, \ldots, n; \quad t = 1, \ldots, T,
\]

\[
\nu_t = \omega \nu_{t-1} + u_t.
\]

The variables \( q_{i,t} \) and \( x_{i,t} \) are observed and it is assumed that \( x_{i,t} \) is strictly exogenous in the sense that it is independent of the error term \( \varepsilon_{i,t} \), including all leads and lags. For simplicity, we also assume that \( u_t \) and \( \varepsilon_{i,t} \) are normally distributed with zero mean and that \( \varepsilon_{i,t} \) is i.i.d. across both \( i \) and \( t \). We will denote by \( \delta \) the ratio \( \gamma/\omega \).

In order to estimate \( \gamma \) based on the panel data \( \{(q_{i,t}, x_{i,t}) : i = 1, \ldots, n; \quad t = 1, \ldots, T\} \), we can adopt a simple two-step estimator of \( \gamma \). In a first step, the parameter \( \delta \) and the aggregate shocks \( \nu_t \) are estimated using an Ordinary Least Square (OLS) regression of \( q_{i,t} \) on \( x_{i,t} \) and time dummies. In the second step, the time-series parameter \( \omega \) is estimated by regressing \( \hat{\nu}_t \) on \( \hat{\nu}_{t-1} \), where \( \hat{\nu}_t \), \( t = 1, \ldots, T \), are the aggregate shocks estimated in the first step using the time dummies. An estimator of \( \gamma \) can then be obtained as \( \hat{\gamma} = \hat{\delta} \hat{\omega} \).

The following remarks are useful to understand the properties of the estimator \( \hat{\gamma} = \hat{\delta} \hat{\omega} \). First,
even if \( \nu_t \) were observed, for \( \hat{\omega} \) to be a consistent estimator of \( \omega \) we would need \( T \) to go to infinity, under which assumption we have \( \hat{\omega} = \omega + O_p\left(T^{-1/2}\right) \). This implies that it is theoretically necessary to assume that our data source is a “long” panel, i.e., \( T \to \infty \). Similarly, \( \hat{\nu}_t \) is a consistent estimator of \( \nu_t \) only if \( n \) goes to infinity. As a consequence, we have \( \hat{\nu}_t = \nu_t + O_p\left(n^{-1/2}\right) \). This implies that it is in general theoretically necessary to assume that \( n \to \infty \). Moreover, if \( n \) and \( T \) both go to infinity, \( \hat{\delta} \) is a consistent estimator of \( \delta \) and \( \hat{\delta} = \delta + O_p\left(n^{-1/2} T^{-1/2}\right) \). All this implies that

\[
\hat{\gamma} = \hat{\delta} \hat{\omega} = \left(\delta + O_p\left(\frac{1}{\sqrt{nT}}\right)\right) \left(\omega + O_p\left(\frac{1}{\sqrt{T}}\right)\right) = \delta \omega + O_p\left(\frac{1}{\sqrt{T}}\right) = \gamma + O_p\left(\frac{1}{\sqrt{T}}\right).
\]

The \( O_p\left(n^{-1/2} T^{-1/2}\right) \) estimation noise of \( \hat{\delta} \), which is dominated by the \( O_p\left(T^{-1/2}\right) \) error from estimating \( \hat{\omega} \), is the term that would arise if \( \omega \) were not estimated. The term reflects typical findings in long panel analysis (i.e., large \( n \), large \( T \)), where the standard errors are inversely proportional to the square root of the number \( n \times T \) of observations. The fact that the estimation error of \( \hat{\gamma} \) is dominated by the \( O_p\left(T^{-1/2}\right) \) term indicates that the number of observations is effectively equal to \( T \), i.e., the long panel should be treated as a time series problem for all practical purposes.

This conclusion has two interesting implications. First, the sampling noise due to cross-section variation should be ignored and the “standard” asymptotic variance formulae should generally be avoided in panel data analysis when aggregate shocks are present. We note that Lee and Wolpin’s (2006, 2010) standard errors use the standard formula that ignores the \( O_p\left(T^{-1/2}\right) \) term. Second, since in most cases the time-series dimension \( T \) of a panel data set is relatively small, despite the theoretical assumption that it grows to infinity, estimators based on panel data will generally be more imprecise than may be expected from the “large” number \( n \times T \) of observations.

\[\text{Footnote 25:} \text{For} \ \hat{\omega} \text{ to have the same distribution as if} \ \nu_t \text{ were observed, we need} \ n \text{ to go to infinity faster than} \ T \text{ or equivalently that} \ T = o\left(n\right). \text{See Heckman and Sedlacek (1985, p. 1088).} \]

\[\text{Footnote 26:} \text{This raises an interesting point. Suppose there is an aggregate time series data set available with which consistent estimation of} \ \gamma \text{ is feasible at the standard rate of convergence. Also suppose that the number of time series observations, say} \ \tau \text{, is a lot larger than} \ T. \text{In that case we conjecture that the panel data analysis is strictly dominated by the time series analysis from an efficiency point of view.}\]
Asymptotic Distribution and Standard Error Formulas for Examples

In this section, we discuss how the discussion in Section 6 applies to the general equilibrium model. We also present characterizations of the asymptotic distributions for the examples in Sections 3 and 5.

D.1 Standard Error Formula Applied to the General Equilibrium Model

Recall our assumption that the (repeated) cross-sectional data include \( n \) i.i.d. observations \((w_{i,t}, c^*_{i,t}, l^*_{i,t}, F_{i,t})\) for working individuals from two periods \( t = 1, 2 \). Here, \( F_{i,t} \) denotes a dummy variable that is equal to one if the agent chooses \( S = F \) in the previous period. Recall that we use

\[
\frac{1}{\bar{n}_1} \sum_{i=1}^{\bar{n}_1} \log w_{i,1}^F - \frac{1}{\bar{n}_2} \sum_{i=1}^{\bar{n}_2} \log w_{i,2}^F = \frac{1}{\hat{\alpha}_1} \left( \log n_1^F - \log n_2^F \right)
\]

\[
\frac{1}{\bar{n}_1} \sum_{i=1}^{\bar{n}_1} \frac{c^*_{i,1}}{l^*_{i,1}} = \frac{w_1^F}{1 - \hat{\sigma}}
\]

as well as

\[
\log \nu_t = \hat{\alpha}_1 \left( \log w_t^F - \log w_t^R \right) - \left( \log n_t^F - \log n_t^R \right)
\]

The parameters \( \rho \) and \( \omega^2 \) can then be consistently estimated by the time-series regression of the following equation:

\[
\log \nu_{t+1} = \rho \log \nu_t + \eta_t.
\]

In addition to these equations, we will use the cross section variances of \( \log w_{i,1}^F \) and \( \log w_{i,1}^R \) to estimate \( \sigma_F^2 \) and \( \sigma_R^2 \). We also have the log likelihood from a sample of \( n \) individuals (cross section) is

\[
\sum_{i=1}^{n} \{ F_{i,2} \log [1 - \Phi (\log (1 - \Theta) - \mu)] + (1 - F_{i,2}) \log [\Phi (\log (1 - \Theta) - \mu)] \}
\]
where $\Theta$ is constant across $i$ and given by

$$
\Theta \equiv \log \left( \frac{n_F}{n_R^2} \right) + \frac{\sigma_R^2 - \sigma_F^2}{2} + \rho \log \nu_1
$$

(53)

The moments employed in the estimation of $\alpha_1$ and $\sigma$ take the following form:

$$
\frac{1}{n_1} \sum_{i=1}^{n_1} \log w_{i,1}^F - \frac{1}{n_2} \sum_{i=1}^{n_2} \log w_{i,2}^F = \frac{1}{\hat{\alpha}_1} (\log n_1^F - \log n_2^F)
$$

$$
\frac{1}{n_1} \sum_{i=1}^{n_1} c_{i,1}^* l_{i,1}^* = w_1^F \frac{\hat{\sigma}}{1 - \hat{\sigma}}
$$

To simplify notation we introduce two redundant parameters $\delta_1$ and $\delta_2$

$$
\frac{1}{n_1} \sum_{i=1}^{n_1} \log w_{i,1}^F = \hat{\delta}_1, \quad \frac{1}{n_2} \sum_{i=1}^{n_2} \log w_{i,2}^F = \hat{\delta}_2
$$

and understand

$$
\hat{\alpha}_1 = \frac{\log n_1^F - \log n_2^F}{\hat{\delta}_1 - \hat{\delta}_2} \quad (54)
$$

Given that our asymptotics are based on $n \to \infty$, we need to express moments in terms of $n$:

$$
\sum_{i=1}^{n} F_{i,1} \left( \log w_{i,1}^F - \delta_1 \right) = 0,
$$

$$
\sum_{i=1}^{n} F_{i,2} \left( \log w_{i,2}^F - \delta_2 \right) = 0,
$$

$$
\sum_{i=1}^{n} F_{i,1} \left( \frac{c_{i,1}^* l_{i,1}^*}{l_{i,1}^*} - w_1^F \frac{\sigma}{1 - \sigma} \right) = 0.
$$

For the estimation of $\sigma_F^2 = \sigma_e^2$, we use the fact that the second moment is the sum of the variance and the square of the first moment and let

$$
\sum_{i=1}^{n} F_{i,1} \left( \left( \log w_{i,1}^F \right)^2 - (\sigma_F^2 + \delta_1^2) \right) = 0.
$$
Likewise, for the estimation of $\sigma^2_R$,

$$\sum_{i=1}^{n} (1 - F_{i,1}) (\log w_{i,1}^R - \delta_3) = 0,$$

$$\sum_{i=1}^{n} (1 - F_{i,1}) \left( (\log w_{i,1}^R)^2 - (\sigma^2_R + \delta_3^2) \right) = 0.$$ 

For the estimation of the parameters $\rho$ and $\omega^2$, the OLS estimator of $\hat{\rho}$ and the corresponding estimator for $\omega^2$ solve:

$$\frac{1}{\tau} \sum_{t=1}^{\tau} \log \nu_t \left( \log \nu_{t+1} - \hat{\rho} \log \nu_t \right) = 0$$

and

$$\frac{1}{\tau} \sum_{t=1}^{\tau} \left( \log \nu_{t+1} - \hat{\rho} \log \nu_t \right)^2 = \hat{\omega}^2.$$ 

Replacing for $\log \nu_{t+1}$ and $\log \nu_t$ using equation (51), as well as (54), we obtain the following two moment conditions:

$$\sum_{t=1}^{\tau} \left( \frac{\log n_t^F - \log n_t^R}{\delta_1 - \delta_2} (\log w_t^F - \log w_t^R) \right) \times \left( \frac{\log n_t^{F+1} - \log n_t^{R+1}}{\delta_1 - \delta_2} (\log w_{t+1}^F - \log w_{t+1}^R) \right) - \hat{\rho} \left( \frac{\log n_t^F - \log n_t^R}{\delta_1 - \delta_2} (\log w_t^F - \log w_t^R) \right)^2 = 0,$$

$$\sum_{t=1}^{\tau} \left( \frac{\log n_t^F - \log n_t^R}{\delta_1 - \delta_2} (\log w_t^{F+1} - \log w_t^{R+1}) \right) - \hat{\rho} \left( \frac{\log n_t^F - \log n_t^R}{\delta_1 - \delta_2} (\log w_t^F - \log w_t^R) \right)^2 - \omega^2 = 0.$$ 

For the rest of the parameters, we note that $F_{i,2}$ is chosen with probability $1 - \Phi (\log (1 - \Theta) - \mu)$ for

$$\Theta = \frac{\log (n_t^F/n_t^R) + \frac{\sigma^2_R - \sigma^2_F}{2} + \hat{\rho} \log \nu_t}{\sigma (\sigma^2_R - \sigma^2_F + \omega^2)}$$

so $\mu$ can be estimated by Probit MLE, where the FOC can be shown to be

$$0 = \sum_{i=1}^{n} \left\{ F_{i,2} - [1 - \Phi (\log (1 - \Theta) - \mu)] \right\}$$

14
where

\[
\Theta = \log \left( \frac{n_F^R}{n_R^2} \right) + \frac{\sigma_{\delta}^2 - \sigma_{\mu}^2}{2} + \varrho \log \nu_1
\]

\[
= \log \left( \frac{n_F^R}{n_R^2} \right) + \frac{\sigma_{\delta}^2 - \sigma_{\mu}^2}{2} + \varrho \left( \log n_1^F - \log n_1^R \right)
\]

Here, we used the fact that

\[
\log \nu_1 = \alpha_1 \left( \log w_1^F - \log w_1^R \right) - \left( \log n_1^F - \log n_1^R \right)
\]

\[
\alpha_1 = \frac{\log n_1^F - \log n_1^R}{\delta_1 - \delta_2}
\]

Based on the previous discussion, we can now present moments in the form of (33) and (34). In our case, \( \log \nu_1 \) is estimated with the aid of aggregate variables, so we have \( \beta = \theta = (\mu, \delta_1, \delta_2, \sigma, \delta_3, \sigma_F^2, \sigma_R^2)' \) and \( \rho = (\varrho, \omega^2)' \). We see that the cross sectional moments are

\[
\frac{1}{n} \sum_{i=1}^{n} F_{i,1} \left( \log w_{i,1}^F - \delta_1 \right) = 0,
\]

\[
\frac{1}{n} \sum_{i=1}^{n} F_{i,2} \left( \log w_{i,2}^F - \delta_2 \right) = 0,
\]

\[
\frac{1}{n} \sum_{i=1}^{n} F_{i,1} \left( \frac{c_{i,1}}{l_{i,1}^*} - w_{i,1}^F \frac{\sigma}{1 - \sigma} \right) = 0,
\]

\[
\frac{1}{n} \sum_{i=1}^{n} \{ F_{i,2} - \left[ 1 - \Phi (\log (1 - \Theta) - \mu) \right] \} = 0,
\]

and

\[
\sum_{i=1}^{n} F_{i,1} \left( \left( \log w_{i,1}^F \right)^2 - \left( \sigma_F^2 + \delta_1^2 \right) \right) = 0,
\]

\[
\sum_{i=1}^{n} (1 - F_{i,1}) \left( \log w_{i,1}^R - \delta_3 \right) = 0,
\]

\[
\sum_{i=1}^{n} (1 - F_{i,1}) \left( \left( \log w_{i,1}^R \right)^2 - \left( \sigma_R^2 + \delta_3^2 \right) \right) = 0,
\]
where
\[
\Theta = \log \left( \frac{n_F^{\delta_1} - n_F^{\delta_2}}{n_R^{\delta_1} - n_R^{\delta_2}} \right) + \varphi \left( \frac{\log n_F^{\delta_1} - \log n_R^{\delta_2}}{\delta_1 - \delta_2} \right) - \left( \log w_i^F - \log n_i^R \right) - \left( \log n_i^F - \log n_i^R \right) \right),
\]

and the time series moments are
\[
\frac{1}{\tau} \sum_{t=1}^{\tau} \log \nu_t \left( \log \nu_{t+1} - \varphi \log \nu_t \right) = 0,
\]
\[
\frac{1}{\tau} \sum_{t=1}^{\tau} \left( (\log \nu_{t+1} - \varphi \log \nu_t)^2 - \omega^2 \right) = 0,
\]

where
\[
\log \nu_t = \frac{\log n_1^F - \log n_2^F}{\delta_1 - \delta_2} \left( \log w_i^F - \log w_i^R \right) - \left( \log n_i^F - \log n_i^R \right) .
\]

Letting
\[
f_{\theta,i} (\theta, \rho) = \begin{bmatrix}
F_{i,1} \left( \log w_i^F - \delta_1 \right) \\
F_{i,1} \left( \frac{c_{i,1}^F}{w_{i,1}^F} - \log \frac{w_{i,1}^F}{1 - \varphi} \right) \\
F_{i,1} \left( \left( \log w_i^F \right)^2 - \left( \delta_1^2 \right) \right) \\
(1 - F_{i,1}) \left( \log w_i^R - \delta_3 \right) \\
(1 - F_{i,1}) \left( \left( \log w_i^F \right)^2 - \left( \delta_1^2 \right) \right) \end{bmatrix}, \tag{55}
\]

and
\[
g_{\rho,t} (\beta, \rho) = \begin{bmatrix}
\log \nu_t \left( \log \nu_{t+1} - \varphi \log \nu_t \right) \\
(\log \nu_{t+1} - \varphi \log \nu_t)^2 - \omega^2 \end{bmatrix}, \tag{56}
\]

we can compute
\[
\hat{\Omega}_f = \frac{1}{n} \sum_{i=1}^{n} f_{\theta,i} f'_{\theta,i}
\]

and
\[
\hat{\Omega}_g = \tau^{-1} \sum_{t=1}^{\tau} g_{\rho,t} g'_{\rho,t}
\]
and

\[ \hat{W} = \begin{bmatrix} \frac{1}{n} \hat{\Omega}_f & 0 \\ 0 & \frac{1}{\tau} \hat{\Omega}_g \end{bmatrix}. \] (57)

We are now ready to describe the five steps required in the computation of test statistics and confidence intervals for the general equilibrium model. As a first step, let \( \theta = \beta = (\mu, \delta_1, \delta_2, \sigma, \delta_3, \sigma_R^2, \sigma_D^2)' \) and \( \rho = (\rho, \omega^2)' \). Observe that the aggregate shock is not in the set of estimated parameters, since the general equilibrium model implies that \( \log \nu_i = \alpha_1 (\log w_{it}^f - \log w_{it}^R) - (\log n_{it}^f - \log n_{it}^R) \). In the second, third, and fourth steps compute the matrices \( A, \hat{\Omega}_f, \hat{\Omega}_g, \) and \( W \) using the vectors of moments \( f_{\theta,i} \) and \( g_{\rho,i} \) derived above. In the last step, calculate the variance matrix \( V = A^{-1} W (A')^{-1} \) and form related t-ratios and confidence intervals.

### D.2 Limiting Distributions

We first consider the portfolio choice problem in Section 3. In this example, the time series log likelihood is given by

\[ \tau^{-1} \sum_{s=1}^{\tau} \log (\phi (\nu_t / \sigma_{\nu}) / \sigma_{\nu}) \]

where \( \phi \) is the PDF of \( N(0,1) \). The likelihood is maximized that \( \hat{\nu} = \tau^{-1} \sum_{s=1}^{\tau} \nu_t \) and \( \hat{\sigma}_{\nu}^2 = \tau^{-1} \sum_{s=1}^{\tau} (\nu_t - \hat{\nu})^2 \). The cross-sectional likelihood is given by

\[ n^{-1} \sum_{i=1}^{n} \log (\phi ((u_{i1} - \nu_1) / \sigma_e) / \sigma_e) + n^{-1} \sum_{i=1}^{n} \log (\phi (\alpha_{i1} - \alpha) / \sigma_e) / \sigma_e) \]

where \( \alpha = (\delta (\sigma_e^2 + \sigma_v^2) + r - \mu) / \delta (\sigma_e^2 + \sigma_v^2) \). For given values of \( \mu, r, \) and \( \sigma_v^2 \) there is a one-to-one mapping between the parameters \( (\delta, \sigma_e^2, \sigma_v^2, \nu_1) \) and \( (\alpha, \sigma_e^2, \sigma_v^2, \nu_1) \). Maximizing the likelihood with respect to \( (\delta, \sigma_e^2, \sigma_v^2, \nu_1) \) is thus equivalent to maximizing the likelihood with respect to \( (\alpha, \sigma_e^2, \sigma_v^2, \nu_1) \) and then solving for \( (\delta, \sigma_e^2, \sigma_v^2, \nu_1) \). The maximizer for \( (\alpha, \sigma_e^2, \sigma_v^2, \nu_1) \) is the standard MLE of the normal distribution for mean and variance, \( \hat{\nu}_1 = n^{-1} \sum_{i=1}^{n} u_{i1}, \hat{\alpha} = n^{-1} \sum_{i=1}^{n} \alpha_{i1}, \hat{\sigma}_e^2 = n^{-1} \sum_{i=1}^{n} (u_{i1} - \hat{\nu}_1)^2 \) and \( \hat{\sigma}_e = n^{-1} \sum_{i=1}^{n} (\alpha_{i1} - \hat{\alpha})^2 \). The limiting distributions of these estimators are given by

\[ \tau^{1/2} \begin{pmatrix} \hat{\mu} - \mu \\ \hat{\sigma}_e^2 - \sigma_e^2 \end{pmatrix} \to_d N \left( 0, \begin{bmatrix} \sigma_v^2 & 0 \\ 0 & 2\sigma_v^2 \end{bmatrix} \right), \]

17
and

\[
\begin{pmatrix}
\hat{\alpha} - \alpha \\
\hat{\sigma}_e^2 - \sigma_e^2 \\
\hat{\nu}_1 - \nu_1
\end{pmatrix}
\overset{d}{\to} \mathcal{N}
\begin{pmatrix}
\sigma_e^2 & 0 & 0 & 0 \\
0 & 2\sigma_e^2 & 0 & 0 \\
0 & 0 & 2\sigma_e^2 & 0 \\
0 & 0 & 0 & \sigma_e^2
\end{pmatrix}
\]

From the results in Hahn, Kuersteiner, and Mazzocco (2016) the convergence of the two vectors is joint, with asymptotic independence between cross-section and time series parameters, and stable with respect to \( \nu_1 \). However, because of the particularly simple nature of the model the limiting distributions are conventional Gaussian limits with fixed variances. To obtain the limiting distribution of \( \hat{\delta} \) one now simply applies the delta method and the continuous mapping theorem. More specifically, we have

\[
\begin{array}{c}
\hat{\delta} = \frac{\hat{\mu} - r}{\sigma_e^2 + \sigma_\nu^2} (1 - \alpha) - \frac{\hat{\mu} - r}{\sigma_e^2 + \sigma_\nu^2} (1 - \alpha) \hat{n}^{1/2} (\hat{\alpha} - \alpha) - \frac{\hat{\mu} - r}{\sigma_e^2 + \sigma_\nu^2} (1 - \alpha) \hat{n}^{1/2} (\hat{\sigma}_e^2 - \sigma_e^2) \\
+ \frac{1}{\sigma_e^2 + \sigma_\nu^2} \sqrt{n} \hat{\tau}^{1/2} (\hat{\mu} - \mu) - \frac{\mu - r}{\sigma_e^2 + \sigma_\nu^2} (1 - \alpha) \sqrt{\frac{\tau}{n}} \hat{\tau}^{1/2} (\hat{\sigma}_\nu^2 - \sigma_\nu^2) + o_p (1)
\end{array}
\]

leading to a limiting distribution of \( \hat{\delta} \) given by

\[
n^{-1/2} \left( \hat{\delta} - \delta \right) \overset{d}{\to} \mathcal{N}
\begin{pmatrix}
2 (1 - \alpha)^2 (\mu - r)^2 (\sigma_e^2 + \kappa \sigma_\nu^2) + (\sigma_e^2 + \sigma_\nu^2)^2 ((\mu - r)^2 \sigma_e^2 + (1 - \alpha)^2 \kappa \sigma_\nu^2)
\end{pmatrix}
\]

where \( \kappa = \lim \frac{\nu_1}{\tau} \) and the variance formula uses the fact that the four components in (58) are asymptotically independent. The formula for the variance is indicative of the fact that first step estimation of the time series parameters can be ignored if \( \tau \) is much larger than \( n \), such that \( \kappa \) is close to zero. However, this is an unlikely scenario given that cross-sectional samples tend to be quite large.

We now consider the general equilibrium example. It is useful to analyze the form of the limiting distribution of a set of GMM estimators based on \( f \) and \( g \). Define the empirical moment functions as

\[
h_n (\theta, \rho) = n^{-1} \sum_{i=1}^{n} f_{\theta,i} (\theta, \rho), \quad k_\tau (\beta, \rho) = \tau^{-1} \sum_{t=0}^{n_0 + \tau} g_{\rho,t} (\beta, \rho).
\]

and the moment based criterion functions

\[
F_n (\theta, \rho) = -h_n (\theta, \rho) \Omega^{-1} h_n (\theta, \rho) \quad \text{and} \quad G_\tau (\beta, \rho) =
\]

18
The estimators then are defined as the solution \((\hat{\theta}, \hat{\rho})\) to

\[
\begin{align*}
\frac{\partial F_n(\hat{\theta}, \hat{\rho})}{\partial \theta} &= 0 \\
\frac{\partial G_\tau(\hat{\beta}, \hat{\rho})}{\partial \rho} &= 0.
\end{align*}
\]

Because the GMM estimators are exactly identified in our example these equations reduce to

\[
\begin{align*}
h_n(\hat{\theta}, \hat{\rho}) &= 0 \\
k_\tau(\hat{\beta}, \hat{\rho}) &= 0.
\end{align*}
\]

We focus on the just identified case and refer the reader to our companion paper Hahn, Kuersteiner and Mazzocco (2016) for a general treatment. The limiting distribution of \((\hat{\theta}, \hat{\rho})\) depends on the joint limiting distribution of \(h_n(\theta_0, \rho_0)\) and \(k_\tau(\beta_0, \rho_0)\).

Recall \(\log w_{it}^F = \alpha_1^{-1} (\log n_{t}^F + \log \sigma + \log T - \alpha_0) + \varepsilon_{it}^F\) such that

\[
\delta_1 = \alpha_1^{-1} (\log n_{t}^F + \log \sigma + \log T - \alpha_0) - \frac{\sigma_F^2}{2}.
\]

Similarly, let \(\delta_2 = \alpha_1^{-1} (\log n_{t}^F + \log \sigma + \log T - \alpha_0) - \frac{\sigma_F^2}{2}\),

\[
\delta_3 = \alpha_1^{-1} (\log n_{t}^R + \log \sigma + \log T - \alpha_0 - \log \nu_1) - \frac{\sigma_R^2}{2}
\]

and define \(p(\Theta) = \Phi (\log (1 - \Theta) - \mu)\). Let \(\mathcal{C}\) be the \(\sigma\)-field generated by \(\log n_{t}^R, \log n_{t}^F, \log n_{t}^F\) and \(\log \nu_1\) such that \(\Theta, w_{t}^F, \delta_1, \delta_2\) and \(\delta_3\) are measurable with respect to \(\mathcal{C}\). Based on the theory in our companion paper, the moment functions converge jointly and stably to independent mixed Gaussian limits

\[
n^{1/2} h_n(\theta_0, \rho_0) \xrightarrow{d} \Omega_j^{1/2} \xi_h \sim N (0, \Omega_j) \quad (\mathcal{C}\text{-stably})
\]
where $\xi_h \sim N(0, I)$ and is independent of any $C$-measurable random variable, 

\[ \Omega_{f,1} = \begin{bmatrix}
    p(\bar{\Theta}_1)\sigma^2_F & p(\bar{\Theta}_1)\frac{w_F^\prime \sigma}{1-\sigma}\sigma^2_F & 2\delta_1\sigma^2_F \\
    p(\bar{\Theta}_1)\frac{w_F^\prime \sigma}{1-\sigma}\sigma^2_F & p(\bar{\Theta}_1)\left(\frac{w_F^\prime \sigma}{1-\sigma}\right)^2 (e^{\sigma^2_F} - 1) & p(\bar{\Theta}_1)\frac{w_F^\prime \sigma}{1-\sigma}(2\delta_1 + 1)\sigma^2_F \\
    2\delta_1\sigma^2_F & p(\bar{\Theta}_1)\frac{w_F^\prime \sigma}{1-\sigma}(2\delta_1 + 1)\sigma^2_F & p(\bar{\Theta}_1)(2\sigma^4_F + 4\delta^2_1\sigma^2_F)
\end{bmatrix}, \]

\[ \Omega_{f,2} = \begin{bmatrix}
    (1 - p(\bar{\Theta}_1))\sigma^2_R & 2\delta_3\sigma^2_R \\
    2\delta_3\sigma^2_R & (1 - p(\bar{\Theta}_1))(2\sigma^4_R + 4\delta_3^2\sigma^2_R)
\end{bmatrix}, \]

\[ \Omega_{f,3} = \begin{bmatrix}
    p(\bar{\Theta}_1)\sigma^2_e & 0 \\
    0 & p(\bar{\Theta}_2)(1 - p(\bar{\Theta}_2))
\end{bmatrix}, \]

and

\[ \Omega_f = \begin{bmatrix}
    \Omega_{f,1} & 0 & 0 \\
    0 & \Omega_{f,2} & 0 \\
    0 & 0 & \Omega_{f,3}
\end{bmatrix}. \]

Here, we let

\[ \bar{\Theta}_t \equiv \log \left( \frac{n^x_t}{n^x_{t-1}} \right) + \frac{(\pi^2 - 1)\sigma^2_e}{2} + \rho \log \nu_{t-1} \]

for clarity. For the time series sample it is straight forward to see that under suitable regularity conditions

\[ \tau^{1/2}k_\tau(\beta_0, \rho_0) \rightarrow_d \Omega^{1/2}_g \xi_k \sim N(0, \Omega_g) \quad (C\text{-stably}) \]

where $\xi_k \sim N(0, I)$ and independent of any $C$-measurable random variable and

\[ \Omega_g = \begin{bmatrix}
    \omega^4_{1-\omega_0^2} & 0 \\
    0 & 2\omega^4
\end{bmatrix}. \]

The results in Hahn, Kuersteiner and Mazzocco (2016) imply that $\xi_h$ and $\xi_k$ are independent Gaussian random variables conditional on $C$. The explicit formulas make clear that in this model the limiting variance does depend on macro variables including common shocks and other observables. Since these variables remain random in the limit as $n$ and $\tau$ tend to infinity, the resulting limiting distribution is mixed Gaussian and the convergence to the limit is joint with the macro
variables or \( C \)-stable. The later is important because the influence matrix \( A \), as we show below, also depends on these same macro variables.

Next compute the limits

\[
A_{f,\theta} = \text{plim} n^{-1} \sum_{i=1}^{n} \frac{\partial f_{\theta,i}(\theta_0, \rho_0)}{\partial \theta^i}, \quad A_{f,\rho} = \text{plim} n^{-1} \sum_{i=1}^{n} \frac{\partial f_{\theta,i}(\theta_0, \rho_0)}{\partial \rho^i},
\]

\[
A_{g,\theta} = \text{plim} \tau^{-1} \sum_{t=\tau_0+1}^{\tau_0+\tau} \frac{\partial g_{\rho,t}(\beta_0, \rho_0)}{\partial \theta^i}, \quad A_{g,\rho} = \text{plim} \tau^{-1} \sum_{t=\tau_0+1}^{\tau_0+\tau} \frac{\partial g_{\rho,t}(\beta_0, \rho_0)}{\partial \rho^i}.
\]

First, letting \( \dot{p}(\Theta) = \phi(\log (1 - \Theta) - \mu) \) where \( \phi \) is the PDF of \( N(0, 1) \),

\[
A_{f,\theta} = \begin{bmatrix}
0 & -p(\bar{\Theta}_1) & 0 & 0 & 0 & 0 \\
0 & 0 & 0 & -\frac{\nu_f}{(1-\nu_f)}p(\bar{\Theta}_1) & 0 & 0 \\
0 & -2\delta_1 p(\bar{\Theta}_1) & 0 & 0 & 0 & -p(\bar{\Theta}_1) \\
0 & 0 & 0 & 0 & - (1 - p(\bar{\Theta}_1)) & 0 \\
0 & 0 & 0 & 0 & 0 & - (1 - p(\bar{\Theta}_1)) \\
-\dot{p}(\bar{\Theta}_2) & -\frac{\dot{p}(\bar{\Theta}_2)}{1-\bar{\Theta}_2} & -\frac{\dot{p}(\bar{\Theta}_2)}{1-\bar{\Theta}_2} & -\frac{\dot{p}(\bar{\Theta}_2)}{1-\bar{\Theta}_2} & -\frac{\dot{p}(\bar{\Theta}_2)}{1-\bar{\Theta}_2} & -\frac{\dot{p}(\bar{\Theta}_2)}{1-\bar{\Theta}_2} \end{bmatrix},
\]

Next, consider the two cross-derivative terms where the first one is given by

\[
A_{f,\rho} = \begin{bmatrix}
0 & 0 \\
0 & 0 \\
0 & 0 \\
0 & 0 \\
0 & 0 \\
-\frac{\dot{p}(\bar{\Theta})}{1-\bar{\Theta}_2} & -\frac{\dot{p}(\bar{\Theta})}{1-\bar{\Theta}_2} \end{bmatrix}.
\]

Next note that

\[
\log \nu_t = \frac{\log n_1^F - \log n_2^F}{\delta_1 - \delta_2} (\log w_1^F - \log w_1^R) - (\log n_1^F - \log n_1^R)
\]

such that \( \partial \log \nu_t / \partial \theta \) is non-zero for elements \( \delta_1 \) and \( \delta_2 \). For \( \log \nu_t (\log \nu_{t+1} - \rho \log \nu_t) \) the deriva-
tive \( \frac{\partial \log \nu_t}{\partial \theta} \) has zero expectation because \( \log \nu_{t+1} - \nu_0 \log \nu_t = \eta_t \). For \( \log \nu_{t+1} - \nu_0 \log \nu_t \) we obtain partial derivatives equal to \( 2\eta_t \frac{\partial \log \nu_{t+1}}{\partial \theta} - \nu_0 \frac{\partial \log \nu_{t}}{\partial \theta} \). Since \( \eta_t \) is orthogonal to all data in \( \log \nu_t \) it follows that \( E[\eta_t (\frac{\partial \log \nu_{t+1}}{\partial \theta} - \nu_0 \frac{\partial \log \nu_{t}}{\partial \theta})] = 0 \). Under suitable regularity conditions it then follows that sample averages converge to these expectations, leading to

\[
A_{g,\theta} = \begin{bmatrix}
0 & \log \nu_t \left( \frac{\partial \log \nu_{t+1}}{\partial \theta} - \nu_0 \frac{\partial \log \nu_{t}}{\partial \theta} \right) & E \left[ \log \nu_t \left( \frac{\partial \log \nu_{t+1}}{\partial \theta} - \nu_0 \frac{\partial \log \nu_{t}}{\partial \theta} \right) \right] & 0 & 0 & 0 \\
0 & 2E \left[ \eta_t \frac{\partial \log \nu_{t+1}}{\partial \theta} \right] & 2E \left[ \eta_t \frac{\partial \log \nu_{t+1}}{\partial \theta} \right] & 0 & 0 & 0 \\
end{bmatrix}.
\]

Finally, straight forward calculations show that under suitable regularity conditions ensuring a law of large numbers for an autoregressive process the limits in \( A_{g,\rho} \) are given by

\[
A_{g,\rho} = \begin{bmatrix}
-\frac{\omega^2}{1-\gamma^2} & 0 \\
0 & -1 \\
end{bmatrix}.
\]

The limiting distribution of \( \hat{\theta} \) is a consequence of Hahn, Kuersteiner and Mazzocco (2016), Theorem 2 and Corollary 2. Using the notation developed here we have

\[
\sqrt{n} \left( \hat{\theta} - \theta_0 \right) \stackrel{d}{\rightarrow} -A^f,\theta \Omega \frac{1}{2} \xi_h - \sqrt{\kappa} A^g,\rho \Omega \frac{1}{2} \xi_k \ (C\text{-stably})
\]

where

\[
A^f,\theta = A_{f,\theta}^{-1} + A_{f,\theta}^{-1} A_{f,\rho} \left( A_{g,\rho} - A_{g,\theta} A_{f,\theta}^{-1} A_{f,\rho} \right)^{-1} A_{g,\theta} A_{f,\theta}^{-1}
\]

\[
A^g,\rho = -A_{f,\theta}^{-1} A_{f,\rho} \left( A_{g,\rho} - A_{g,\theta} A_{f,\theta}^{-1} A_{f,\rho} \right)^{-1} A_{g,\theta} A_{f,\theta}^{-1}
\]

The limiting distribution of \( \hat{\rho} \) is mixed Gaussian \( N(0, \Omega_{\rho}) \), with random weight matrix \( \Omega_{\rho} = A^f,\theta \Omega_f A^f,\theta + \kappa A^g,\rho \Omega_g A^g,\rho \) where we have shown how the elements of \( A \) and \( \Omega_f \) depend on macro variables and unobserved macro shocks. Similarly, the limiting distribution of \( \hat{\rho} \) is also mixed Gaussian and can be derived in a similar fashion.
E Proof of (31)

Suppose that our econometrician tries to estimate $\mu$ using only cross-section data sets misspecifies the model and assumes that the difference in the labor demand functions of the two types of firms is not due to the aggregate shock, but to different intercepts, i.e.,

$$
\log H_{t+1}^{D,F} = \alpha_0 + \alpha_1 \log w_{t+1}^F \\
\log H_{t+1}^{D,R} = \alpha_0' + \alpha_1 \log w_{t+1}^R
$$

with $\alpha_0 \neq \alpha_0'$. The equilibrium wages are then

$$
\log w_{t+1}^F = \frac{\log n_{t+1}^F + \log \sigma + \log T - \alpha_0}{\alpha_1}, \\
\log w_{t+1}^R = \frac{\log n_{t+1}^R + \log \sigma + \log T - \alpha_0'}{\alpha_1},
$$

with (59)

and as a consequence, equation (40) is changed to

$$
(\frac{n_{t+1}^F}{\sigma_{1-\gamma}/\alpha_1})^{\sigma_{1-\gamma}} E \left[ \exp \left( \sigma_1 (1/\alpha_1) (1 - \gamma) \varepsilon_{t+1}^F \right) \right] \\
\geq (\frac{n_{t+1}^R}{\sigma_{1-\gamma}/\alpha_1})^{\sigma_{1-\gamma}} E \left[ \exp \left( \sigma_1 (1/\alpha_1) (1 - \gamma) \varepsilon_{t+1}^R \right) \right].
$$

Note that

$$
E \left[ \exp \left( \sigma_1 (1/\alpha_1) (1 - \gamma) \varepsilon_{t+1}^F \right) \right] = \exp \left( -\frac{\sigma_1 (1/\alpha_1) (1 - \gamma)}{2} \sigma_{1-\gamma}^2 \right) \exp \left( \frac{\sigma_1 (1 - \gamma) (1/\alpha_1)^2}{2} \sigma_{1-\gamma}^2 \right),
$$

$$
E \left[ \exp \left( \sigma_1 (1/\alpha_1) (1 - \gamma) \varepsilon_{t+1}^R \right) \right] = \exp \left( -\frac{\sigma_1 (1/\alpha_1) (1 - \gamma)}{2} \sigma_{1-\gamma}^2 \right) \exp \left( \frac{\sigma_1 (1 - \gamma) (1/\alpha_1)^2}{2} \sigma_{1-\gamma}^2 \right),
$$

23
and

\[
\begin{align*}
\left[ \left( \frac{1}{e^{\tilde{\alpha}_0}} \right)^{1/\alpha_1} \right]^{1-\gamma} \exp \left( -\frac{\sigma (1/\alpha_1) (1-\gamma)}{2} \sigma_F^2 \right) &= \exp \left( -\sigma (1/\alpha_1) (1-\gamma) \tilde{\alpha}_0 \right), \\
\left[ \left( \frac{1}{e^{\alpha_0'}} \right)^{1/\alpha_1} \right]^{1-\gamma} \exp \left( -\frac{\sigma (1/\alpha_1) (1-\gamma)}{2} \sigma_R^2 \right) &= \exp \left( -\sigma (1/\alpha_1) (1-\gamma) \tilde{\alpha}_0' \right),
\end{align*}
\]

where

\[
\tilde{\alpha}_0 = \alpha_0 + \frac{1}{2} \sigma_F^2 = \alpha_0 - E \left[ \varepsilon_t^F \right], \quad \tilde{\alpha}_0' = \alpha_0' + \frac{1}{2} \sigma_R^2 = \alpha_0' - E \left[ \varepsilon_t^R \right].
\]

Therefore, the econometrician will conclude that \( F \) is chosen if

\[
\left( \frac{n_t^F}{n_t^R} \right)^{\sigma(1-\gamma)/\alpha_1} \exp \left( -\sigma (1/\alpha_1) (1-\gamma) \tilde{\alpha}_0 \right)
\geq \left( \frac{n_t^R}{n_t^R} \right)^{\sigma(1-\gamma)/\alpha_1} \exp \left( -\sigma (1/\alpha_1) (1-\gamma) \tilde{\alpha}_0' \right) \exp \left( \frac{(\sigma (1-\gamma) (1/\alpha_1))^2}{2} (\sigma_R^2 - \sigma_F^2) \right)
\]

when \( 1 - \gamma > 0 \), and to

\[
\left( \frac{n_t^F}{n_t^R} \right)^{\sigma(1-\gamma)/\alpha_1} \exp \left( -\sigma (1/\alpha_1) (1-\gamma) \tilde{\alpha}_0 \right)
\leq \left( \frac{n_t^R}{n_t^R} \right)^{\sigma(1-\gamma)/\alpha_1} \exp \left( -\sigma (1/\alpha_1) (1-\gamma) \tilde{\alpha}_0' \right) \exp \left( \frac{(\sigma (1-\gamma) (1/\alpha_1))^2}{2} (\sigma_R^2 - \sigma_F^2) \right)
\]

when \( 1 - \gamma < 0 \). This implies that \( F \) is chosen if

\[
\gamma \geq 1 - \frac{\log \left( \frac{n_t^F}{n_t^R} \right) + (\tilde{\alpha}_0' - \tilde{\alpha}_0)}{\frac{\sigma (\pi^2 - 1) \sigma^2}{2\alpha_1}}.
\] (60)

Note that

\[
\tilde{\alpha}_0' - \tilde{\alpha}_0 = \alpha_0' - \alpha_0 + \frac{1}{2} (\sigma_R^2 - \sigma_F^2).
\]

We now argue that \( \alpha_0' - \alpha_0 \) above should be understood to be equal to \( \log \nu_{t+1} \). Note that the econometrician can estimate \( \alpha_1 \) consistently using equation (27), which is based on cross-section variation. The econometrician can also estimate \( \alpha_0' - \alpha_0 \) consistently by \( \tilde{\alpha}_1 \left( \log u_{t+1}^F - \log u_{t+1}^R \right) - \left( \log n_{t+1}^F - \log n_{t+1}^R \right) \). Comparing with (29), we conclude that the econometrician’s estimator is
exactly equal to our earlier estimator of $\log \nu_{t+1}$. This is a natural consequence of the nature of the econometrician’s misspecification, who assumes that the difference in the equilibrium wages in (59) reflects the difference of intercepts of the labor demand functions. However, this assumption is incorrect and the difference of the intercepts is due to the aggregate shock, i.e, $\alpha'_0 = \alpha_0 + \log \nu_{t+1}$.

It follows that the econometrician’s conclusion (60) above can be equivalently written with $\alpha'_0 - \alpha_0$ replaced by $\log \nu_{t+1}$, which establishes (31).

### F Censored versus Truncated Results

As mentioned in the main text, to perform the Monte Carlo exercise we have to deal with a technical issue. The estimation of the risk aversion parameter $\mu$ in the general equilibrium model requires the computation of $\log (1 - \Theta)$ where

$$\Theta \equiv \frac{\log \left( \frac{n_F}{n_R} \right) + \frac{\sigma_F^2 - \sigma_R^2}{2} + \rho \log \nu_1}{\sigma \left( \sigma_F^2 - \sigma_R^2 + \omega^2 \right) / 2\alpha_1}$$

In the model, $\Theta$ is always smaller than 1 and, hence, $\log (1 - \Theta)$ is always well defined. In the estimation of $\mu$, however, the true parameters included in $\Theta$ are replaced with their estimated values. In some of the Monte Carlo repetitions, the randomness of the estimated parameters generates values of $\Theta$ that are greater than 1, which implies that $\log (1 - \Theta)$ is not well define. We deal with this issue by presenting two sets of results. A first set in which we only use Monte Carlo runs in which $\Theta < 1$. We will refer to these results as the “truncated” results. A second set in which we set $\Theta = 0.99$ if $\Theta > 1$ and report our findings using all the Monte Carlo runs. We will refer to the second set as the ”censored” set. With the results, we also report the number of simulations in which $\Theta > 1$. An examination of the probability of choosing education $F$ clarifies that the censored set tends to bias the estimates of $\mu$ downward: by setting $\Theta$ closer to 1, the MLE estimator of $\mu$ tends to minus infinity. The truncated set may therefore provide a more accurate description of the true bias. But the censored set is also informative because it documents the potential effect of replacing the true parameters of the model with their estimates in the estimation of parameters that are affected by both cross-sectional and time-series variation.
This issue is even more significant when the risk aversion parameter is estimated using the misspecified model. In that case, $\Theta$ can be greater than 1 for two different reasons. First, as in the general equilibrium model, the true parameters are replaced by their estimated counterparts. Second, $\Theta$ is misspecified and, hence, there is no reason to expect that it satisfies the theoretical restriction $\Theta < 1$. We therefore expect the downward bias for the misspecified model in the censored results and the number of cases in which $\Theta > 1$ to be larger than in the general equilibrium model.

Tables 5 and 6 compare the results obtained using the censored sample with the results obtained using the truncated sample. There are three patterns worth highlighting. First, when the censored sample is used, as expected, the average of the estimated risk aversion parameter obtained employing our proposed method is always lower. Second, with our proposed method the number of cases in which $\Theta > 1$ decreases with the length of the time-series, since the persistence and the variance of the aggregate shocks are estimated more precisely. This suggests that it is important to employ a long time-series of aggregate data to avoid situations in which the estimated parameters are incompatible with the structure of the model. Lastly, as expected, when we use the misspecified model, the number of cases in which $\Theta > 1$ is much larger and the misspecification bias goes from being positive to being negative.
### Table 5: Monte Carlo Results, Parameter Estimates For Correct Model

| True Parameter | Censored Results | Truncated Results |
|----------------|------------------|-------------------|
|                | Estimate | Cov. Prob. | Estimate | N. Cases |
| **Cross-sectional Sample Size: 2,500, Time-series Sample Size: 25** | | | |
| Log Risk Aversion Mean: $\mu = 0.2$ | 0.053 | 0.896 | 0.157 | 120/5000 |
| **Cross-sectional Sample Size: 2,500, Time-series Sample Size: 50** | | | |
| Log Risk Aversion Mean: $\mu = 0.2$ | 0.114 | 0.918 | 0.173 | 73/5000 |
| **Cross-sectional Sample Size: 2,500, Time-series Sample Size: 100** | | | |
| Log Risk Aversion Mean: $\mu = 0.2$ | 0.129 | 0.926 | 0.177 | 59/5000 |
| **Cross-sectional Sample Size: 5,000, Time-series Sample Size: 25** | | | |
| Log Risk Aversion Mean: $\mu = 0.2$ | 0.070 | 0.893 | 0.158 | 102/5000 |
| **Cross-sectional Sample Size: 5,000, Time-series Sample Size: 50** | | | |
| Log Risk Aversion Mean: $\mu = 0.2$ | 0.130 | 0.915 | 0.180 | 61/5000 |
| **Cross-sectional Sample Size: 5,000, Time-series Sample Size: 100** | | | |
| Log Risk Aversion Mean: $\mu = 0.2$ | 0.148 | 0.930 | 0.178 | 38/5000 |
| **Cross-sectional Sample Size: 10,000, Time-series Sample Size: 25** | | | |
| Log Risk Aversion Mean: $\mu = 0.2$ | 0.082 | 0.889 | 0.166 | 95/5000 |
| **Cross-sectional Sample Size: 10,000, Time-series Sample Size: 50** | | | |
| Log Risk Aversion Mean: $\mu = 0.2$ | 0.139 | 0.910 | 0.183 | 54/5000 |
| **Cross-sectional Sample Size: 10,000, Time-series Sample Size: 100** | | | |
| Log Risk Aversion Mean: $\mu = 0.2$ | 0.159 | 0.923 | 0.188 | 36/5000 |

Notes: This Table reports the Monte Carlo results for the correct model obtained using our proposed estimation method. They are derived by simulating the general equilibrium model 5000 times. The second column reports the average estimated parameter, where the average is computed over the 5000 simulations, when we use all the Monte Carlo runs and set $\Theta_t = 0.99$ in all cases in which $\Theta_t \geq 1$. Column 3 reports the corresponding coverage probability of a confidence interval with 90% nominal coverage probability. Column 4 reports the average estimated parameter when we drop all simulations for which $\Theta_t \geq 1$. Column 5 reports the number of case in which $\Theta_t \geq 1$.

### Table 6: Monte Carlo Results, Parameter Estimates For Misspecified Model

| True Parameter | Censored Results | Truncated Results |
|----------------|------------------|-------------------|
|                | Estimate | Bias | Estimate | N. Cases |
| **Cross-sectional Sample Size: 2,500** | | | |
| Log Risk Aversion Mean: $\mu = 0.2$ | -0.990 | -1.190 | 1.163 | 1170/1000 |
| **Cross-sectional Sample Size: 5,000** | | | |
| Log Risk Aversion Mean: $\mu = 0.2$ | -0.996 | -1.196 | 1.173 | 1180/5000 |
| **Cross-sectional Sample Size: 10,000** | | | |
| Log Risk Aversion Mean: $\mu = 0.2$ | -0.997 | -1.197 | 1.179 | 1185/5000 |

Notes: This Table reports the Monte Carlo results for the misspecified model obtained using only cross-sectional variation. They are derived by simulating the general equilibrium model 5000 times. The second column reports the average estimated parameter, where the average is computed over the 5000 simulations, when we use all the Monte Carlo runs and set $\Theta_t = 0.99$ in all cases in which $\Theta_t \geq 1$. Column 3 reports the corresponding coverage probability of a confidence interval with 90% nominal coverage probability. Column 4 reports the average estimated parameter when we drop all simulations for which $\Theta_t \geq 1$. Column 5 reports the number of case in which $\Theta_t \geq 1$. 

27