DYNAMICS ON FREE-BY-CYCLIC GROUPS

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Abstract. Given a free-by-cyclic group $G = F_N \rtimes \varphi \mathbb{Z}$ determined by any outer automorphism $\varphi \in \text{Out}(F_N)$ which is represented by an expanding irreducible train-track map $f$, with $u_0: G \to \mathbb{Z}$ the homomorphism having $\ker(u_0) = F_N$, we construct a $K(G, 1)$ 2–complex $X$ called the \textit{folded mapping torus} of $f$, and equip it with a semiflow. We show that $X$ enjoys many similar properties to those proven by Thurston and Fried for the mapping torus of a pseudo-Anosov homeomorphism. In particular, we construct an open, convex cone $A \subset H^1(X; \mathbb{R}) = \text{Hom}(G; \mathbb{R})$ containing $u_0$, a homology class $\epsilon \in H_1(X; \mathbb{R})$, and a continuous, convex, homogeneous of degree $-1$ function $H: A \to \mathbb{R}$ with the following properties. Given any primitive integral class $u \in A$ there is a graph $\Theta_u \subset X$ such that: (1) the inclusion $\Theta_u \to X$ is $\pi_1$–injective and $\pi_1(\Theta_u) = \ker(u)$, (2) $u(\epsilon) = \chi(\Theta_u)$, (3) $\Theta_u \subset X$ is a section of the semiflow and the first return map to $\Theta_u$ is an expanding irreducible train track map representing $\varphi_u \in \text{Out}(\ker(u))$ such that $G = \ker(u) \rtimes_{\varphi_u} \mathbb{Z}$, (4) the logarithm of the stretch factor of $\varphi_u$ is precisely $\delta(u)$, (5) if $\varphi$ was further assumed to be hyperbolic and fully irreducible then for every primitive integral $u \in A$ the automorphism $\varphi_u$ of $\ker(u)$ is also hyperbolic and fully irreducible. In addition, we describe connections with the work of Button, Dunfield, and McMullen on the Alexander norm, work of Algom-Kfir and Rafi on stretch factors, as well as work of Gautero and Wang on sections of semiflows.

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1. INTRODUCTION

Given a group $K$ and $\varphi \in \text{Out}(K)$ represented by the automorphism $\Phi: K \to K$, we denote the \textit{mapping torus group} of $\varphi$ as the semidirect product

$$G = G_\varphi = K \rtimes \varphi \mathbb{Z} = \{w, t \mid t^{-1}wt = \Phi(w) \text{ for all } w \in K\}.$$
The group $G$ and the associated homomorphism $u_0: G \to \mathbb{Z}$ given by $u_0(t^n w) = n$ depend only on $\varphi$, and not on $\Phi$. Conversely, given a primitive integral $u \in \text{Hom}(G, \mathbb{R}) = H^1(G; \mathbb{R})$ (a homomorphism with $u(G) = \mathbb{Z}$), there is an associated splitting $G = \ker(u) \times \varphi_u \mathbb{Z}$ with $\varphi_u \in \text{Out}(\ker(u))$ defining the splitting and with associated homomorphism $u$. Namely, if $t_u \in G$ is such that $u(t_u) = 1 \in \mathbb{Z}$, then $\varphi_u \in \text{Out}(\ker(u))$ is the outer automorphism class of the automorphism $\Phi_u$ of $\ker(u)$ defined as $\Phi_u(g) = t_u^{-1} g t_u$, where $g \in \ker(u)$. Of particular interest is the case when $\ker(u)$ is finitely generated. According to a result of Neumann [Neu], as well as more general results of Bieri–Neumann–Strebel [BNS] and Levitt [Lev], for finitely generated $G$ there exists an open cone $\mathcal{E}_G \subseteq H^1(G; \mathbb{R})$ (a subset invariant by positive scalar multiplication), which we call the f.g. cone of $G$, such that a primitive integral element $u \in H^1(G; \mathbb{R})$ has finitely generated kernel if and only if $u \in \mathcal{E}_G$.

When $G = \pi_1(M)$ is a closed oriented 3–manifold, Stallings [Sta1] proved that every primitive integral element $u \in \mathcal{E}_G$ is induced by a fibration $M \to S^1$. The fiber $S_u \subset M$ is then a surface with $\pi_1(S_u) = \ker(u)$, and $\varphi_u$ is induced by a homeomorphism $F_u: S_u \to S_u$ called the monodromy for $u$. Suppose that for some $u_0 \in \mathcal{E}_G$, the monodromy $F_{u_0}$ is pseudo-Anosov and let $\mathcal{E}_0 \subset \mathcal{E}_G$ denote the component containing $u_0$. Through a detailed analysis of $M$, Thurston [Thu, FLP] and Fried [Fri2, Fri1] proved that the monodromies for all primitive integral elements in $\mathcal{E}_0$ are intimately related to one another in important topological, geometric and dynamical ways. For example, the assignments $u \mapsto \chi(S_u)$ and $u \mapsto h(F_u)$ for primitive integral $u \in \mathcal{E}_0$, where $h(F_u)$ denotes the topological entropy of $F_u$, both extend to convex functions on all of $\mathcal{E}_0$.

In this paper, we provide a model for, and a similar analysis of, the situation where the 3–manifold group is replaced by a free-by-cyclic group, $G = F_N \rtimes_\varphi \mathbb{Z}$, where $F_N$ is a free group of rank 2, $N < \infty$, and $\varphi \in \text{Out}(F_N)$. Free-by-cyclic groups share many features with fundamental groups of compact 3–manifolds fibering over the circle (for example, see [AKR, FH, KL]), although the behavior in the free-by-cyclic case is generally more varied and more complicated.

Let $\varphi \in \text{Out}(F_N)$ be an arbitrary element and let $f: \Gamma \to \Gamma$ be a graph-map which is a representative of $\varphi$ satisfying some additional mild technical assumptions (a representative $f$ satisfying these assumptions can be easily constructed for any $\varphi \in \text{Out}(F_N)$, and these assumptions automatically hold if $f$ is an expanding irreducible train-track map). Let $G = G_\varphi$ be the mapping torus group of $\varphi$ and let $u_0 \in H^1(G_\varphi; \mathbb{R})$ be the associated homomorphism. Under these assumptions we construct $(X, \psi, \epsilon, A)$ where

- $X$ is a $K(G, 1)$ polyhedral 2–complex,
- $\psi$ is a semiflow on $X$—that is, an action of the additive semigroup $\mathbb{R}_+$,
- $\epsilon \in Z_1(X; \mathbb{R})$ is a cellular cocycle,
- $A = A_X \subset H^1(G; \mathbb{R})$ is an open, convex cone containing $u_0$.

With these notations, our main results can be summarized as follows.

**Theorem A.** Let $N \geq 2$, let $\varphi \in \text{Out}(F_N)$ be an arbitrary element represented by a “nice” graph-map $f: \Gamma \to \Gamma$ as above, and let $G = F_N \rtimes_\varphi \mathbb{Z}$. Then there exists $(X, \psi, \epsilon, A)$ as above such that for any primitive integral $u \in A$, there exists a compact connected topological graph $\Theta_u \subset X$ with the following properties:

1. The inclusion $\Theta_u \subset X$ is $\pi_1$-injective and, with the identification $\pi_1(X) = G$ we have $\pi_1(\Theta_u) = \ker(u)$,
2. $u(\epsilon) = \chi(\Theta_u) = 1 - \text{rk}(\ker(u))$,
3. $\Theta_u$ is a section of the semiflow $\psi$ and the first return map $f_u: \Theta_u \to \Theta_u$ represents $\varphi_u \in \text{Out}(\ker(u)) = \text{Out}(\pi_1(\Theta_u))$.

If we further assume that $f: \Gamma \to \Gamma$ is an expanding irreducible train-track map then there exists a continuous, convex, homogeneous of degree $-1$ function $S: A \to (0, \infty)$ such that for every primitive integral $u \in A$ we have:
4. \( f_u : \Theta_u \to \Theta_u \) is an expanding irreducible train-track map,

5. \( \delta(u) = \log(\lambda(\varphi_u)) = h(f_u) \) where \( \lambda(\varphi_u) > 1 \) is the “growth rate” or “stretch factor” of \( \varphi_u \) and \( h(f_u) \) is the topological entropy of \( f_u \).

6. If in addition we assume that \( \varphi \in \text{Out}(F_N) \) is hyperbolic and fully irreducible then for every primitive integral \( u \in A \) the automorphism \( \varphi_u \) of \( \ker(u) \) is hyperbolic and fully irreducible.

In the remainder of the introduction, we will discuss in more detail some generalizations and refinements of the various parts of this theorem (see §§1.1–1.3), elaborating on the similarities and differences with the 3–manifold setting. Next we will describe in §1.4 an application and the connection to work of Algom-Kfir and Rafi [AKR]. In §1.5 we compare our construction with related constructions of Gautero [Gau1] and Wang [Wan]. Finally, in §1.6 we briefly explain the relation between the class \( \epsilon \) and the work of McMullen [McM2], Dunfield [Dun], and Button [But] on the Alexander norm, further strengthening the analogy with the 3–manifold setting.

Theorem A will follow from Theorems B, C, and D below, which provide more detailed results.

1.1. Fibrations, semiflows and an Euler-like class. In what follows, we assume that \( M \) is a closed, oriented, aspherical 3–manifold and write \( G_M = \pi_1(M) \). We also assume that \( M \) fibers over the circle \( \nu_0 : M \to S^1 \) with fiber \( S \) and monodromy \( F : S \to S \), so that \( M = S \times [0,1]/(x,1) \sim (F(x),1) \). Write \( u_0 \in H^1(M;\mathbb{R}) \) to denote the induced primitive integral element \( u_0 = (\eta_0)_* : G_M \to \mathbb{Z} \).

We sketch here a geometric proof of the existence of the open set \( \mathcal{S} \), essentially due to Tischler [Tis], that motivates our construction. The starting point of the analysis is the following two observations. Firstly, there is a natural suspension flow on \( M \) determined by the local flow on \( S \times [0,1] \), given by \( (x,t) \mapsto (x,t+s) \) for \( x \in S \) and \( s \leq 1-t \). Secondly, via the de Rham isomorphism \( H^1(M;\mathbb{R}) \cong H^1_{dR}(M;\mathbb{R}) \), one can represent \( u_0 \) by the closed, nowhere vanishing 1–form \( \nu_0 \), where \( vol_{S^1} \) is the unit volume form on \( S^1 \). Any class \( u \in H^1(M;\mathbb{R}) \) projectively close to \( u_0 \) (that is, close up to scaling by positive real number), is also represented by a closed nowhere vanishing 1–form \( \nu \) projectively close to \( \nu_0 \).

This 1–form \( \nu \) provides a crucial tool for studying properties of \( u \): if \( u \) is a primitive integral class represented by such a \( \nu \), then integrating \( \nu \) defines a fibration \( \eta_\nu : M \to \mathbb{R}/\mathbb{Z} = \mathbb{S}^1 \) so that \( \nu = \eta_\nu^*(vol_{S^1}) \) and \( u = (\eta_\nu)_* : G_M \to \mathbb{Z} \). Thus every primitive integral \( u \in H^1(M;\mathbb{R}) \) projectively close to \( u_0 \) is also induced by a fibration over \( \mathbb{S}^1 \), and hence has finitely generated kernel equal to the fundamental group \( \pi_1(S_\nu) \) of the fiber \( S_\nu \). Furthermore, the fiber \( S_\nu \) is a section of the suspension flow on \( M \), and the first return map to \( S_\nu \) is precisely the monodromy \( F_\nu \) of the fibration. The Euler characteristic \( \chi(S_\nu) \) of any fiber \( S_\nu \) may then be calculated by pairing the homology class of \( S_\nu \) with the Euler class of the 2–plane bundle \( \ker(\nu) \)—equivalently, one may pair \( u \), the Poincaré dual of \( S_\nu \), with the Poincaré dual \( e_\nu \) of this Euler class. On the other hand, for any \( \nu \) projectively close to \( \nu_0 \), \( \ker(\nu) \) and \( \ker(\nu_0) \) are homotopic 2–plane subbundles of \( TM \) and so have equivalent Euler classes. Therefore, there is a single class \( \epsilon = e_{\nu_0} \) such that \( \chi(S_\nu) = u(\epsilon) \) for all \( u \) projectively close to \( u_0 \); see [Thu].

Now consider a free-by-cyclic group \( G = G_\varphi = F_N \rtimes \varphi \mathbb{Z} \) defined by \( \varphi \in \text{Out}(F_N) \) with \( 2 \leq N < \infty \) and associated primitive integral \( u_0 : G \to \mathbb{Z} \) with \( \ker(u_0) = F_N \). We would like to obtain a similar geometric understanding of those \( u \in H^1(G;\mathbb{R}) \) which are projectively near to \( u_0 \). Taking a topological representative \( f : \Gamma \to \Gamma \) of \( \varphi \) (that is, a graph \( \Gamma \) together with a topological graph map \( f \) and an isomorphism \( m : F_N \to \pi_1(\Gamma) \) for which \( m^{-1}f_*m \) represents \( \varphi \in \text{Out}(F_N) \); see §2.7), one may build the corresponding mapping torus \( Z_f = \Gamma \times [0,1]/(x,1) \sim (f(x),0) \). Analogous to the 3–manifold above, \( Z_f \) has fundamental group isomorphic to \( G \) and admits a map to the circle \( Z_f \to \mathbb{S}^1 \) inducing \( u_0 : G \to \mathbb{Z} \). However, it is unclear how to “perturb” this
map to the circle to obtain useful information about primitive integral elements \( u \in H^1(G; \mathbb{R}) \) which are near \( u_0 \), up to scaling.

To circumvent this problem, for any \( \varphi \in \text{Out}(F_N) \), given a “sufficiently nice” topological representative \( f: \Gamma \to \Gamma \) of \( \varphi \) (which always exist and are easy to find), we introduce a new \( 2 \)-complex, the *folded mapping torus* \( X_f \) for \( \varphi \). The complex \( X_f \) is obtained as a quotient of the full mapping torus \( Z_f \) of \( f \) by following the “folding line” from \( \Gamma \) to \( \Gamma \varphi \) in the Culler-Vogtmann outer space. See \( \S 2 \) and \( \S 4 \) for background, Convention 6.1 for the necessary assumptions on \( f \) and \( \S 6 \) for the construction of \( X_f \). In particular, the assumptions on \( f \) required to construct \( X_f \) will always be satisfied when \( f: \Gamma \to \Gamma \) is a train track representative of \( \varphi \).

The local flow on \( \Gamma \times [0, 1] \) given by \((x, t) \mapsto (x, t + s)\) descends to a semiflow \( \psi \) on \( X_f \) (see Proposition 6.8). Moreover, \( X_f \) is a \( K(G, 1) \)-space (see Corollary 6.13), and the homomorphism \( u_0: G \to \mathbb{Z} \) is induced by a map \( \eta_0: X_f \to \mathbb{S}^1 \).

Although \( X_f \) is not a manifold, and so there is no notion of smooth 1–forms on \( X_f \), the combinatorial structure of \( X_f \) nevertheless provides a way to perturb the maps \( \eta_0 \) and \( u_0 \). In \( \S 6.4 \), we construct a *trapezoid cell structure* on \( X_f \) (with a choice of orientation for the 1–cells) so that the restriction of \( \eta_0 \) to every semiflow line and every 1–cell is an orientation preserving local homeomorphism. We then define the positive cone of \( X_f \) to be the subset \( A = A_{X_f} \subset H^1(X_f; \mathbb{R}) \) of cohomology classes represented by cellular 1–cocycles that are positive on every positively oriented 1–cell. Moreover, this cell structure allows for the definition of a cellular 1–chain \( \epsilon \) on \( X_f \) that serves as a “combinatorial” analogue of the Poincaré dual of the Euler class of the 2–plane subbundle \( \ker(\nu_0) \) of \( TM \) considered above; see Remark 7.10 for more on this analogy. We summarize these basic properties of \( X_f \) in the following.

**Proposition 1.1.** Let \( \varphi \in \text{Out}(F_N) \) (where \( N \geq 2 \)) be arbitrary, let \( X_f \) be a folded mapping torus for \( \varphi \), with the trapezoid cell structure, and let \( \psi \) be the associated semiflow. Let \( u_0 \in H^1(G; \mathbb{R}) \) be the associated homomorphism for the splitting \( G_\varphi = F_N \rtimes \varphi \mathbb{Z} \). Then:

a) The 2–complex \( X_f \) is a \( K(G_\varphi, 1) \)–space.

b) The set \( A_{X_f} \subset H^1(X_f; \mathbb{R}) \) is an open convex cone containing \( u_0 \).

c) The singular 1–chain \( \epsilon \) is a 1–cycle and thus defines an element also denoted \( \epsilon \in H_1(X_f; \mathbb{R}) \), which we call the \( E_0 \)–class of \( X_f \).

Working in the framework of \( X_f \), we obtain the following results that precisely mirror the phenomenon described above for the 3–manifold \( M \).

**Theorem B.** Let \( \varphi \in \text{Out}(F_N) \) (where \( N \geq 2 \)), \( X_f \) a folded mapping torus for \( \varphi \) with the associated semiflow \( \psi \), positive cone \( A_{X_f} \subset H^1(X_f; \mathbb{R}) \), and \( E_0 \)–class \( \epsilon \in H_1(X_f; \mathbb{R}) \). Given a positive cellular 1–cocycle \( z \in Z^1(X_f; \mathbb{R}) \) representing a primitive integral element \( u \in A_{X_f} \subset H^1(X_f; \mathbb{R}) = H^1(G_\varphi; \mathbb{R}) \), there exists a map \( \eta_z: X_f \to \mathbb{S}^1 \) and a fiber \( \Theta_z = \eta_z^{-1}(x_0) \) for some \( x_0 \in \mathbb{S}^1 \) so that

1. \( \Theta_z \) is a finite connected topological graph such that the inclusion \( \Theta_z \subset X_f \) is \( \pi_1 \)–injective and such that \( \pi_1(\Theta_z) = \ker(u) \leq \pi_1(X_f) = G_\varphi \).

2. \( u(\epsilon) = \chi(\Theta_z) = 1 - \text{rk}(\ker(u)) \).

3. \( \Theta_z \) is a section of \( \psi \).

4. the first return map \( f_z: \Theta_z \to \Theta_z \) of \( \psi \) is a homotopy equivalence and \((f_z)_* \) represents \( \varphi_u \in \text{Out}(\ker(u)) \).

See \( \S 1.5 \) and \( \S 1.6 \) for discussion of related constructions and results.

1.2. Train tracks and semiflows. Returning to the 3–manifold \( M \), we now assume that some primitive integral class \( u_0 \in \mathcal{C}_G \) is induced by a fibration \( \eta_0: M \to \mathbb{S}^1 \) with monodromy \( F: S \to S \) that is pseudo-Anosov. According to Thurston’s hyperbolization theorem, \( M \) is a hyperbolic manifold. Recall that the monodromies \( F_\nu: S_\nu \to S_\nu \) for \( \nu \) near \( \nu_0 \), the 1–form representing \( u_0 \), are
the first return maps of the suspension flow of $F$. In fact, this statement is true for all $\nu$ representing $u$ in the same component of $\mathcal{C}_G$ as $u_0$. Another application of hyperbolization implies that any such $F_\nu: S_\nu \to S_\nu$ is isotopic to a pseudo-Anosov homeomorphism. Fried [FLP, Exposé 14] proved that the isotopy is not needed. Indeed, he proved that the first return map $F_\nu$ is already a pseudo-Anosov homeomorphism as soon as $F$ is, without appealing to the hyperbolic structure.

For $\varphi \in \text{Out}(F_N)$ there are two natural analogues of being represented by a pseudo-Anosov. The first such analogue is geometric in nature: an element $\varphi \in \text{Out}(F_N)$ is called hyperbolic if the group $G = F_N \rtimes_{\varphi} \mathbb{Z}$ is word-hyperbolic. Appealing to the work of Bestvina–Feighn [BF1], Brinkmann [Bri] proved that $\varphi \in \text{Out}(F_N)$ is hyperbolic if and only if $\varphi$ is a toroidal, that is, $\varphi$ has no periodic conjugacy classes of nontrivial elements of $F_N$. A much more important free group analogue of being represented by a pseudo-Anosov is dynamic in nature: an element $\varphi \in \text{Out}(F_N)$ is said to be fully irreducible or an iwip (for “irreducible with irreducible powers”) if no positive power of $\varphi$ preserves the conjugacy class of a proper free factor of $F_N$. The notions of hyperbolic and fully irreducible are independent, with neither one implying the other. In particular, there are many hyperbolic automorphisms that are not fully irreducible. The closest counterpart of being represented by a pseudo-Anosov homeomorphism in the free group setting is an element of $\text{Out}(F_N)$ that is both hyperbolic and fully irreducible. This behavior is known to be generic (e.g. see [Riv1, Riv2, CM]). If $\varphi \in \text{Out}(F_N)$ is hyperbolic then $N \geq 3$ since for $F_2 = F(a, b)$ every $\varphi \in \text{Out}(F(a, b))$ preserves the conjugacy class of some positive power of $[a, b]$.

We now suppose that $\varphi \in \text{Out}(F_N)$ can be represented by an expanding irreducible train-track map $f: \Gamma \to \Gamma$ (see Definitions 2.3 and 2.9); this key notion of a train-track map was introduced by Bestvina and Handel in [BH] and is an $\text{Out}(F_N)$ analogue of a pseudo-Anosov representative. According to a result of [BF1], such an $f$ exists for any fully irreducible $\varphi$, and more generally for any irreducible $\varphi$ of infinite order. Our next result proves that, if we construct the folded mapping torus $X_f$ using $f$, then for any primitive integral $u \in A$ represented by a positive cocycle $z$, the first return map $f_z: \Theta_z \to \Theta_z$ from Theorem B is also an expanding irreducible train-track representative of $\varphi_u \in \text{Out}(\ker(u))$.

If $\varphi$ is additionally assumed to be fully irreducible and hyperbolic, then in view of the hyperbolicity of $G \cong G_\varphi$, it follows that the monodromy $\varphi_u$ of any other primitive integral $u \in \mathcal{C}_G$ is necessarily hyperbolic as well. However, it is not at all clear whether $\varphi_u$ must also be fully irreducible. In general, proving full irreducibility for free group automorphisms is a fairly hard task, see for example, [CP]. Nevertheless, by using the structure of the folded mapping torus $X_f$, we prove that for any primitive integral $u \in A$, the monodromy $\varphi_u \in \text{Out}(\ker(u))$ is indeed fully irreducible:

**Theorem C.** Let $\varphi \in \text{Out}(F_N)$ (where $N \geq 2$) be an outer automorphism represented by an expanding irreducible train-track map $f: \Gamma \to \Gamma$, let $X_f$ be the folded mapping torus, and $\psi$ the associated semiflow. Let $u \in A_{X_f} \subset H^1(G_\varphi; \mathbb{R}) = H^1(X_f; \mathbb{R})$ be a primitive integral element which is represented by a positive 1-cocycle $z \in Z^1(X_f; \mathbb{R})$, and let $\Theta_z \subset X_f$ be the topological graph from Theorem B so that the first return map $f_z: \Theta_z \to \Theta_z$ is a homotopy equivalence representing $\varphi_u$. Then:

1. The map $f_z: \Theta_z \to \Theta_z$ is a topological graph-map (in the sense of Definition 2.1 below).
2. There exists a linear graph structure (in the sense of Subsection 2.2) on $\Theta_z$ with respect to which $f_z$ is an expanding irreducible train-track map.
3. If we additionally assume that $\varphi$ is hyperbolic and fully irreducible, then $\varphi_u \in \text{Out}(\ker(u))$ is also hyperbolic and fully irreducible.
We emphasize that, if in item (3) above \( \varphi \) is only assumed to be fully irreducible (and not hyperbolic), then \( \varphi_u \) need not be fully irreducible; see Remark 9.11.

We assume that a train track map is piecewise linear on every edge, with respect to some linear structure on the graph; see §§2.4–2.5 for precise statements. While this property is part of the assumption on \( f \), it becomes part of the conclusion for \( f_z \) for any positive cocycle \( z \). The graph \( \Theta_z \) does not come equipped with any natural linear structure, and thus part of the proof of Theorem C includes the construction of a natural linear structure. This structure is deduced as a consequence of a general dynamical result (which appears to be of independent interest), Theorem 3.2, about topological graph maps that are “sufficiently mixing” (a notion we call \textit{expanding on all scales}).

To prove that \( \varphi_u \) is fully irreducible, under the assumption that \( \varphi \) is hyperbolic and fully irreducible, we utilize a criterion of full irreducibility for hyperbolic automorphisms obtained by Kapovich in [Kap]; see also Pfaff [Pfa]. That criterion says that if \( f' : \Gamma' \to \Gamma' \) is a train-track map representative of a hyperbolic automorphism \( \varphi' \) then \( \varphi' \) is fully irreducible if and only if some power \( A(f')^m \) of the transition matrix \( A(f') \) is strictly positive and the Whitehead graphs of all vertices of \( \Gamma' \) are connected. We first obtain a general result strengthening this criterion (see Corollary 5.4 below) and show that the condition \( A(f')^m > 0 \) can be replaced by just requiring the transition matrix \( A(f') \) to be irreducible. We then verify that \( f_z : \Theta_z \to \Theta_z \) is a train-track map with an irreducible transition matrix and with connected Whitehead graphs by exploiting the properties of \( f \) and of the semiflow \( \psi \). This allows us to conclude that \( \varphi_u \) is fully irreducible. As another useful application of Corollary 5.4, we show in Corollary 5.6 that for hyperbolic elements in \( \text{Out}(F_N) \) being fully irreducible is equivalent to being fully irreducible.

1.3. \textbf{Entropy and stretch factors.} For a pseudo-Anosov homeomorphism \( F : S \to S \), the \textit{stretch factor} or \textit{dilatation} \( \lambda(F) \) records the asymptotic growth rate for lengths of curves under iteration. That is,

\[
\log(\lambda(F)) = \lim_{n \to \infty} \frac{\log(\ell(F^n(\gamma)))}{n}
\]

where \( \ell \) is the length of the geodesic representative in any fixed metric on \( S \) and \( \gamma \) is any homotopically nontrivial curve on \( S \). From the work of Fathi and Shub [FLP, Exposé 10], \( \log(\lambda(F)) \) is the topological entropy \( h(F) \) of \( F \). Returning to the 3–manifold \( M \), we continue to assume that some (hence every) monodromy \( F : S \to S \) for a primitive integral \( u_0 \in H^1(M; \mathbb{R}) \) is pseudo-Anosov we let \( \mathcal{C}_0 \subset \mathcal{C}_G \) denote the component containing \( u_0 \). Fried [Fri1] proved that the function which assigns to every \( u \in \mathcal{C}_0 \) the topological entropy \( h(F_u) \) of the monodromy \( F_u : S_u \to S_u \), extends to a continuous, homogeneous of degree \(-1\) function

\[
\mathfrak{h} : \mathcal{C}_0 \to \mathbb{R}
\]

for which the reciprocal \( 1/\mathfrak{h} \) is concave. See [LO, Oer2, McM1] for other proofs and extensions of this result.

Any \( \varphi \in \text{Out}(F_N) \) also has a \textit{stretch factor} \( \lambda(\varphi) \geq 1 \) defined as

\[
\log \lambda(\varphi) = \sup_{w \in F_N} \lim_{n \to \infty} \frac{\log ||\varphi^n(w)||_A}{n},
\]

where \( ||w||_A \) denotes the cyclically reduced length of \( w \) with respect to some fixed free basis \( A \) of \( F_N \). It is known that the above definition does not depend on the choice of \( A \) and that the sup in the above formula is actually a max.

An element \( \varphi \in \text{Out}(F_N) \) is called \textit{exponentially growing} if \( \lambda(\varphi) > 1 \). It is known that every fully irreducible \( \varphi \) is exponentially growing. More generally, if \( \varphi \in \text{Out}(F_N) \) admits an expanding irreducible train-track representative \( f : \Gamma \to \Gamma \), then \( \varphi \) is exponentially growing and \( \lambda(\varphi) = \lambda(f) \).
where $\lambda(f)$ is the Perron-Frobenius eigenvalue of the transition matrix $A(f)$ of $f$ (see § 2.4); in particular $\lambda(f)$ depends only on $\varphi$ and not on $f$ here. Moreover, in this case the topological entropy $h(f)$ of $f$ is equal to $\log(\lambda(f))$, (see Proposition 2.8 below for a more general version of this statement). This discussion applies, for example, to all fully irreducible automorphisms and, more generally, to all irreducible elements of $\text{Out}(F_N)$ of infinite order.

The final part of Theorem A provides the analogue of Fried’s result on entropy.

**Theorem D.** Let $\varphi \in \text{Out}(F_N)$ (where $N \geq 2$) be an element represented by an expanding irreducible train track map $f: \Gamma \to \Gamma$. Let $X_\psi$ be the folded mapping torus, $\psi$ the associated semiflow, and $A_{X_\psi} \subset H^1(X_\psi; \mathbb{R})$ the positive cone of $X_\psi$. Then there exists a continuous, homogeneous of degree $-1$ function

$$\mathcal{H}: A_{X_\psi} \to \mathbb{R}$$

such that for every primitive integral $u \in A_{X_\psi}$ represented by a positive cocycle $z \in Z^1(X_\psi; \mathbb{R})$, the first return map $f_z: \Theta_z \to \Theta_z$ satisfies

$$\log(\lambda(\varphi_u)) = h(f_z) = \mathcal{H}(u).$$

Moreover, $1/\mathcal{H}$ is concave, and hence $\mathcal{H}$ is convex.

The proof of Theorem D closely follows the argument of Fried from the 3–manifold case, with some important modifications. The rough idea of the proof is as follows. The logarithm of the stretch factor $\log(\lambda(\varphi_u))$ is equal to the topological entropy $h(f_z)$ of the first return map $f_z: \Theta_z \to \Theta_z$ of $\psi$. According to the variational principle, $h(f_z) = \sup_{\nu} h(\nu_f(f_z))$ where $\nu$ runs over all $f_z$–invariant Borel probability measures on $\Theta_z$ and where $h(\nu_f(f_z))$ is the Kolmogorov-Sinai entropy with respect to $\nu$. There is a natural bijection between $\psi$–invariant finite measures on $X_\psi$ and $f_z$–invariant finite measures on $\Theta_z$, which we write as $\mu \mapsto \bar{\mu}_0$ (with $\bar{\mu}$ representing the normalized probability measure). Then, according to a general result of Abramov, for any $\psi$–invariant probability measure $\mu$, $h(\bar{\mu}_0(f_z)) = h(\mu(\psi))/\bar{\mu}_0(\Theta_z)$ where $h(\mu(\psi))$ is a entropy of the flow with respect to $\mu$ (which depends on $\mu$, but not on the class $u \in A$ represented by the cocycle $z = z_0$). Then one gets

$$\frac{1}{h(f_z)} = \inf_{\mu} \frac{\bar{\mu}_0(\Theta_z)}{h(\mu(\psi))}. \quad \text{A key step in Fried’s argument is to then show that}$$

for any $\mu$ the function $u \mapsto \bar{\mu}_0(\Theta_z_u)$ extends to a linear continuous function $\mu_u: A \to \mathbb{R}$. The function $W: u \mapsto \inf_{\mu} \mu_u(u)/h(\mu(\psi))$ is now given as the infimum of a family of linear continuous functions. Therefore $W$ is concave on $A$ and hence $W$ is continuous. For every primitive integral $u \in A$ we have $W(u) = \inf_{\mu} \frac{\bar{\mu}_0(\Theta_z_u)}{h(\mu(\psi))}$, and the conclusion of Theorem D follows. There are several difficulties with carrying out this line of argument that we need to overcome. First, Fried’s and Abramov’s results are for flows, while $\psi$ is only a semiflow. Thus we need to immediately pass, via the “natural extension” construction in dynamics, from a semiflow $\psi$ on $X_\psi$ to a related flow $\psi'$ on another space $X'$. We then need to make sure that the above argument gets correctly translated to this new setting. Another difficulty is that the geometric “surgery” argument Fried uses to prove linearity of $\mu_u$ does not work well for $X'$. Thus we deploy a homological argument for that purpose instead of attempting to mimic the argument of Fried.

1.4. Connections to small dilatation free group automorphisms. As a corollary of Theorem D, we see that the function $u \mapsto \log(\lambda(\varphi_u))\chi(\ker(u))$ defined on primitive integral classes $u$ extends to a continuous function which is constant on rays. Thus from any $G = G_x$ with $b_1(G) \geq 2$ and $\varphi$ represented by an expanding irreducible train track map, one obtains sequences $\{\varphi_k: F_{N_k} \to F_{N_k}\}_{k=1}^\infty$ of automorphisms $\varphi_k$ represented by expanding irreducible train track maps for which $N_k \to \infty$ and $N_k \log(\lambda(\varphi_k))$ is uniformly bounded above and below by positive constants. Moreover, by Theorem C (3), if $\varphi$ is fully irreducible and hyperbolic so are all $\varphi_k$; see Corollary 10.7. This corollary mirrors a construction of pseudo-Anosov homeomorphisms with the analogous property using 3–manifolds as described by McMullen [McM1, Section 10]. Corollary
10.7 also complements the work of Algom-Kfir and Rafi [AKR] who showed that any sequence \( \{ \varphi_k : \mathbb{F}_{N_k} \to \mathbb{F}_{N_k} \}_{k=1}^{\infty} \) for which \( N_k \log(\lambda(\varphi_k)) \) is bounded must come from this construction (up to a certain surgery procedure). This was in turn a free-by-cyclic analogue of a result of Farb–Leininger–Margalit [FLM] (see also [Ago]) complementing McMullen’s construction. So in some sense, Corollary 10.7 brings this picture full circle.

1.5. Related results and constructions. As mentioned at the start of the introduction, it already follows from general facts about the BNS-invariant and related constructions (see, for example, [BNS, Lev]) that under the assumptions of Theorem B there exists some open cone \( \mathcal{A}' \subseteq H^1(\Gamma \varphi) \) containing \( u_0 \), such that every primitive integral \( u \in \mathcal{A}' \) has finitely generated kernel \( \ker(u) \). Additional general cohomological dimension considerations then also imply that \( \ker(u) \) is a free group, so that \( u \) determines another splitting of \( G_\varphi \) as a (f.g. free)-by-(infinite cyclic) group. We do not use these general facts in the proof of Theorem B and instead directly establish for every primitive integral \( u \in \mathcal{A} \) that \( \ker(\varphi(u)) \) is a free group of finite rank.

The folded mapping torus \( X_f \) and the semiflow \( \psi \) are similar to Gautero’s construction of a “dynamical 2–complex” [Gau1, Gau2, Gau3, Gau4] (see also the discussion in [Gau1, Section 5] for connections to other related notions) and the unpublished construction of Z. Wang [Wan] of a “decomposed mapping torus” and various “folded complexes”. Our folded mapping torus \( X_f \) turns out the be homeomorphic to the complex constructed by Brinkmann–Schleimer in [BS], which treats only the case when the automorphism is induced by a homeomorphism of a surface with one boundary component. However, [BS] does not construct a semi-flow on the complex, but rather uses it to construct an ideal triangulation of the mapping torus of the homeomorphism.

Gautero builds a 2–complex from a topological representative \( \varphi : \Gamma \to \Gamma \), where \( \Gamma \) is a trivalent graph, and a path in outer space from \( \Gamma \) to \( \Gamma \varphi \) using Whitehead moves (see also the variation in [Gau4] using Stallings’ folds instead of Whitehead moves, which is a modification of his original construction and is more closely related to the one here). Wang [Wan] on the other hand constructs from a sequence of Stallings folds from \( \Gamma \) to \( \Gamma \varphi \) first an iterated mapping cylinder which he calls a decomposed mapping torus. This space is homotopy equivalent to the mapping torus and also admits a semiflow. Then for each cohomology class \( u \in H^1(\Gamma \varphi) ; \mathbb{R} \) satisfying certain conditions he builds what he calls a folded complex \( Y_{f,u} \) which is a quotient of his decomposed mapping torus.

In both of these constructions, the main goal is that of finding cross sections in analogy with Fried’s work [Fri2]. In particular, these constructions are likely sufficient for proving analogues of Theorem B. However, it is unclear how to attack the remainder of Theorem A and Theorems C and D, with these constructions. It is worth noting that in Wang’s construction, he uses sections of the folded complexes to find sections of the original mapping torus (though the latter will likely not satisfy Theorem B). In any event, we try to mention the relevant connections to Gautero’s and Wang’s construction wherever possible throughout the paper.

1.6. Alexander norm. In the 3–manifold setting, the Thurston norm is a seminorm
\[
\nu_T : H^1(M; \mathbb{R}) = H^1(G_M; \mathbb{R}) \to \mathbb{R}
\]
defined by Thurston [Thu] taking integral values on primitive integral points (see also [Gab, Mos1, Mos2, Oer1, LO, Sch]). He then observed that the unit ball \( B_T \) is a polyhedron. The norm of a primitive integral class is a measure of the complexity of the class, and for any class \( u \) represented by a fibration \( M \to S^1 \), the norm is precisely \( \nu_T(u) = -u(e) \), where \( e \) is again the Poincarné dual of the associated Euler class. In fact, in this setting \( C_{G_M} \) is a union of cones on the interiors of certain top dimensional faces of the polyhedron \( B_T \). In [McM2], McMullen constructed a related Alexander norm \( \nu_A \) on \( H^1(G; \mathbb{R}) \) for any finitely presented group \( G \), which again has a polyhedral unit ball \( B_A \) (and so as with the Thurston norm, \( \nu_A \) is linear on cones on faces). In the case
of the 3–manifold group $G_M$ the Thurston and Alexander norms actually agree on $\mathcal{E}_G$ when $\dim(H^1(M;\mathbb{R})) > 1$; however Dunfield [Dun] proved that in general they do not agree on all of $H^1(G_M;\mathbb{R})$.

In the case of our free-by-cyclic group $G_\omega$, since $G_\omega$ has a deficiency 1 presentation, the results of McMullen [McM2, Theorem 4.1] and Button [But, Theorem 3.1] together imply that when $\dim(H^1(G_\omega;\mathbb{R})) > 1$, the Alexander norm calculates $n_A(u) = b_1(\ker(u)) - 1$ for any primitive integral $u \in \mathcal{E}_{G_\omega}$, where $b_1(\ker(u)) = \dim(H^1(\ker(u);\mathbb{R}))$. General cohomological considerations (e.g. see Theorem 2.6 and Remark 2.7 in [GMSW]) additionally imply that $\ker(u)$ is free for any primitive integral $u \in H^1(G_\omega;\mathbb{R})$ with $\ker(u)$ finitely generated; thus we have $b_1(\ker(u)) = \text{rk}(\ker(u))$ in this case. Moreover, Dunfield’s work [Dun] implies that any primitive integral $u \in \mathcal{E}_{G_\omega}$ must lie over the interior of a top dimensional face of $B_A$; therefore $n_A$ restricts to a linear function on an open cone neighborhood of any such $u$. Putting these results together, it follows that for every primitive integral $u_0 \in \mathcal{E}_{G_\omega}$, the assignment $u \mapsto 1 - \text{rk}(\ker(u))$ for primitive integral $u$ extends to a linear function $u \mapsto -n_A(u)$ on some open cone containing $u_0$ (namely the intersection of $\mathcal{E}_{G_\omega}$ with the cone on a top dimensional face of $B_A$). Thus Theorem B(2) gives a realization of this linear function as the geometrically defined $E_0$–class $\epsilon \in H^1(G_\omega;\mathbb{R})$. Moreover, it shows that pairing any element of $A_X$ with the $E_0$–class gives precisely the (negative of the) Alexander norm and thus strengthens the analogy with McMullen’s result for 3–manifolds.

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2. Background

2.1. Graphs. A **topological graph** $\Gamma$ is a locally finite 1-dimensional cell complex (where locally finite means that every 0-cell is incident to only finite many 1-cells). The 0-cells of $\Gamma$ are called **vertices** and the set of all vertices of $\Gamma$ is denoted by $V\Gamma$. Open 1-cells of $\Gamma$ are called **topological edges** of $\Gamma$ and the set of these is denoted $E_{\text{top}}\Gamma$. Every topological edge of $\Gamma$ is homeomorphic to an open interval and thus admits exactly two orientations. An **oriented edge** $e$ of $\Gamma$ is a topological edge together with a choice of an orientation on it. We denote the set of all oriented edges of $\Gamma$ by $ET\Gamma$. If $e$ is an oriented edge of $\Gamma$, then $e^{-1}$ denotes the same topological edge with the opposite orientation. Thus $^{-1}: ET\Gamma \to ET\Gamma$ is a fixed-point-free involution. For an oriented edge $e \in ET\Gamma$ the attaching maps for the underlying 1-cell canonically define the **initial vertex** $o(e) \in V\Gamma$ and the **terminal vertex** $t(e) \in V\Gamma$. By construction, for any $e \in ET\Gamma$ we have $o(e^{-1}) = t(e)$ and $t(e^{-1}) = o(e)$. For $e \in ET\Gamma$ we denote by $\overline{e}$ the closure of $e$ in $\Gamma$.

An **orientation** on a graph $\Gamma$ is a partition $ET\Gamma = E_+\Gamma \sqcup E_-\Gamma$ such that for every $e \in ET\Gamma$ we have $e \in E_+\Gamma$ if and only if $e^{-1} \in E_-\Gamma(\Gamma)$.

Given a topological graph $\Gamma$ and $v \in V\Gamma$ the **link** $\text{Lk}_\Gamma(v)$ consists of all $e \in ET\Gamma$ with $o(e) = v$. A **turn** in $\Gamma$ is an unordered pair $e,e'$ of (not necessarily distinct) elements of $\text{Lk}_\Gamma(v)$. A turn $e,e'$ is **degenerate** if $e = e'$ and **nondegenerate** otherwise. We denote the set of all turns in $\Gamma$ by $\text{Turns}(\Gamma)$.

Given a finite set of points in a topological graph $\Gamma$, one can naturally construct a topological graph $\Gamma'$ as the **subdivision**, in which the vertex set contains the original vertex set, together with the finite set of points.

2.2. Linear and metric structures. Given a topological graph $\Gamma$, a **linear atlas of charts** for $\Gamma$ is a set

$$\Lambda = \{(e_\alpha, j_\alpha, [a_\alpha, b_\alpha])\}_{\alpha \in J}$$
where \( J \) is some index set, \( e_\alpha \in ET \) for every \( \alpha \), and \( j_\alpha: [a_\alpha, b_\alpha] \rightarrow \Gamma \) is a characteristic map: a continuous function for which the restriction to \( \{a_\alpha, b_\alpha\} \) is an orientation preserving homeomorphism onto the interior of \( e_\alpha \) (in particular, \( j_\alpha(a_\alpha) = o(e_\alpha) \) and \( j_\alpha(b_\alpha) = t(e_\alpha) \)). We further assume that (1) for every \( e \in ET \), there exists at least one \( \alpha \in J \) so that \( e = e_\alpha \); (2) for any \( \alpha, \beta \in J \) such that \( e_\alpha = e_\beta \) then the restriction \( j_\alpha^{-1}j_\beta: (a_\beta, b_\beta) \rightarrow (a_\alpha, b_\alpha) \) is the unique orientation preserving affine map; and (3) for every \( \alpha \) there exists \( \alpha' \) so that \( e_{\alpha'} = e_\alpha^{-1} \) and \( j_{\alpha'} = j_\alpha \circ \sigma \), where \( \sigma: [a_\alpha, b_\alpha] \rightarrow [a_{\alpha'}, b_{\alpha'}] \) is the unique affine, orientation reversing involution. A linear structure on a topological graph \( \Gamma \) is a linear atlas \( \Lambda = \{(e_\alpha, j_\alpha, [a_\alpha, b_\alpha])\}_{\alpha \in J} \) which is maximal with respect to inclusion.

A metric atlas on a topological graph \( \Gamma \) is a linear atlas \( L = \{(e_\alpha, j_\alpha, [a_\alpha, b_\alpha])\}_{\alpha \in J} \) on \( \Gamma \) such that whenever \( \alpha, \beta \in J \) satisfy \( e_\alpha = e_\beta \) or \( e_\alpha = e_\beta^{-1} \), then \( |b_\alpha - a_\alpha| = |b_\beta - a_\beta| \). Note that this implies that whenever \( e_\alpha = e_\beta \) then the restriction \( j_\alpha^{-1}j_\beta: (a_\beta, b_\beta) \rightarrow (a_\alpha, b_\alpha) \) is the unique orientation preserving isometry and whenever \( e_\alpha = e_\beta^{-1} \) then the restriction \( j_\alpha^{-1}j_\beta: (a_\beta, b_\beta) \rightarrow (a_\alpha, b_\alpha) \) is the unique orientation reversing isometry. A metric structure on a topological graph \( \Gamma \) is a metric atlas \( L \) on \( \Gamma \) which is maximal with respect to inclusion.

A linear or metric structure on \( \Gamma \) uniquely determines one on any subdivision of \( \Gamma \). Furthermore, linear and metric structures naturally lift under covering maps.

Given a metric structure \( L = \{(e_\alpha, j_\alpha, [a_\alpha, b_\alpha])\}_{\alpha \in J} \) on a graph \( \Gamma \), we can define \( L(e_\alpha) = b_\alpha - a_\alpha > 0 \) to be the \( L \)-length of \( e_\alpha \). From the definition of metric structure, this uniquely defines a function we also denote \( L: ET \rightarrow \mathbb{R}_+ \) satisfying \( L(e) = L(e_1^{-1}) \), for every \( e \in ET \). Any such function on \( ET \) is called a length function for \( \Gamma \). The volume of \((\Gamma, L)\) is then defined to be the (possibly infinite) quantity \( \text{vol}(\Gamma) := \frac{1}{2} \sum_{e \in ET} L(e) \). Since \( \Gamma \) is locally finite, there is a unique geodesic metric \( d_L \) on each component of \( \Gamma \) defining the original weak topology on the 1–complex \( \Gamma \) for which the characteristic maps of that metric structure are all local isometries. Conversely, given a geodesic metric \( d \) on the components of \( \Gamma \), there is a canonical metric structure \( L \) so that \( d = d_L \).

Any metric structure \( L \) on \( \Gamma \) extends to a canonical linear structure \( \Lambda \), meaning that \( L \subset \Lambda \). Also, given a linear structure \( \Lambda \) on \( \Gamma \) and any length function \( L: ET \rightarrow \mathbb{R}_+ \), there exists a unique metric structure \( L \subset \Lambda \) for which \( L(e) = L(e_\alpha) \) for all \( e \in ET \). That is, when a linear structure \( \Lambda \) on \( \Gamma \) is fixed, we can uniquely specify a metric structure \( L \subset \Lambda \) on \( \Gamma \) by simply specifying the lengths of edges.

A graph or linear graph is a topological graph \( \Gamma \) together with a linear structure \( \Lambda \) on it. A metric graph is similarly defined as a topological graph \( \Gamma \) together with a metric structure \( L \). Via the canonical linear structure determined by a metric structure, any metric graph is also naturally a linear graph.

2.3. Paths. If \( \Gamma \) is a topological graph, for \( n \geq 1 \) a combinatorial edge-path of simplicial length \( n \) in \( \Gamma \) is a sequence \( \gamma = e_1 e_2 \ldots e_n \) of oriented edges of \( \Gamma \) such that for \( i = 1, \ldots, n - 1 \) we have \( t(e_i) = o(e_{i+1}) \). We denote \( |\gamma| = n \) and put \( o(\gamma) := o(e_1) \) and \( t(\gamma) := t(e_n) \). Also, for a vertex \( v \) of \( \Gamma \) we view \( \gamma = v \) as a combinatorial edge-path of simplicial length \( |\gamma| = 0 \) with \( o(\gamma) = t(\gamma) = v \). For a combinatorial edge-path \( \gamma = e_1 \ldots e_n \) we denote \( \gamma^{-1} = e_n^{-1} \ldots e_1^{-1} \), so that \( \gamma^{-1} \) is a combinatorial edge-path from \( t(\gamma) \) to \( o(\gamma) \) with \( |\gamma| = |\gamma^{-1}| = n \). For \( \gamma = v \) (where \( v \in \Gamma \) we put \( \gamma^{-1} = \gamma = v \).

If \( \gamma = e_1 \ldots e_n \) is a combinatorial edge path and \( t \) is a turn, we say that this turn is contained in \( \gamma \) if there exists \( 2 \leq i \leq n \) such that \( t = \{e_{i-1}, e_i\} \) or \( t = \{e_i, e_{i+1}\} \).

A topological edge-path of simplicial length \( n \) is a continuous map \( g: [a, b] \rightarrow \Gamma \) such that there exists a combinatorial edge-path \( \gamma_g = e_1 \ldots e_n \) in \( \Gamma \) and a subdivision \( a = c_0 < c_1 < \cdots < c_n = b \) such that for each \( i = 1, \ldots, n \) we have \( g(c_{i-1}) = o(e_i), g(c_i) = t(e_i) \), and the restriction \( g|_{[c_{i-1}, c_i]} \)
is an orientation preserving homeomorphism onto \(e_1\). We say that \(\gamma_g\) is the combinatorial edge-path associated to \(g\). Writing \(o(g) := o(e_1)\) and \(t(g) := t(e_n)\), then \(g\) is a path in \(\Gamma\) from \(o(g)\) to \(t(g)\). For any vertex \(v\) of \(\Gamma\) and \([a, b] \subset \mathbb{R}\), we also regard the constant map \(g: [a, b] \rightarrow \Gamma\) given by \(g(s) = v\) for all \(s \in [a, b]\) as a topological edge-path of simplicial length 0 with \(o(g) = t(g) = v\).

If \(\Gamma\) is a linear graph, then a topological edge-path \(g: [a, b] \rightarrow \Gamma\) is a PL edge-path if in addition it satisfies the following condition. For every edge \(e_i\) of \(\Gamma\) and any chart \((e_\alpha, j_\alpha, [a_\alpha, b_\alpha])\) from the linear atlas with \(e_\alpha = e_i\), the restriction of \(g\) to \([c_{i-1}, c_i]\) is equal to \(j_\alpha \circ \tau_{\alpha,i}\) where \(\tau_{\alpha,i}\) is the unique orientation-preserving affine homeomorphism from \([c_{i-1}, c_i]\) to \([a_\alpha, b_\alpha]\).

By dropping the requirement that \(g(a)\) and \(g(b)\) be vertices of \(\Gamma\), the above definition is straightforwardly modified to get the notion of a PL path in \(\Gamma\).

If we have a combinatorial path \(\gamma\) with \(|\gamma| = n\) in a topological (respectively, linear) graph \(\Gamma\), there always exists a topological (respectively, PL) edge-path \(g: [a, b] \rightarrow \Gamma\) with \(\gamma_g = \gamma\). Therefore we will often suppress the distinction between combinatorial, topological, and PL edge-paths and just call them edge-paths, unless we wish to emphasize the distinction. We call edge-paths of positive simplicial length nondegenerate and edge-paths of simplicial length 0 degenerate.

A combinatorial edge-path \(\gamma\) in \(\Gamma\) is tight or reduced if \(\gamma\) does not contain a subpath of the form \(ee^{-1}\) where \(e \in E\Gamma\) (that is, if \(\gamma\) contains no degenerate turns). A topological or PL edge-path is tight or reduced if the associated combinatorial edge-path is so. More generally, a PL path \(g: [a, b] \rightarrow \Gamma\) is tight if \(g\) is locally injective.

If \((\Gamma, \mathcal{L})\) is a metric graph, then the \(d_{\mathcal{L}}\)-length of a PL-path \(g\) in \((\Gamma, \mathcal{L})\) is denoted by \(|g|_{\mathcal{L}}\). Similarly, the length of a combinatorial edge-path \(\gamma = e_1 \ldots e_n\) will be denoted by \(|\gamma|_{\mathcal{L}} = \sum_{i=1}^{n} \mathcal{L}(e_i)\).

2.4. Graph maps.

**Definition 2.1** (Graph-map). If \(\Gamma\) and \(\Delta\) are topological graphs, a topological graph-map \(f: \Gamma \rightarrow \Delta\) is a continuous function such that \(f(V\Gamma) \subseteq V\Delta\) and such that for every \(e \in E\Gamma\) \(f|_e\) is a topological-edge-path (possibly degenerate) from \(f(o(e))\) to \(f(t(e))\) in \(\Delta\). More precisely, this means that for any characteristic map \(j: [a, b] \rightarrow e\), the composition \(f \circ j: [a, b] \rightarrow \Delta\) is a topological edge-path. In this situation we will often denote the combinatorial edge-path in \(\Delta\) associated to \(f \circ j\) by \(f(e)\). If \(\Gamma\) and \(\Delta\) are linear graphs and in addition we assume that for every \(e \in E\Gamma\), \(f|_e\) is a PL edge-path from \(f(o(e))\) to \(f(t(e))\), then we call \(f\) a linear graph-map or just a graph map.

**Example 2.2** (Running example). Here we introduce an example that we will develop throughout the paper as a means of illustrating key ideas. Let \(\Gamma\) denote the graph in Figure 1. This graph has four edges, oriented as shown and labeled \(\{a, b, c, d\} = E_4\Gamma\). We consider a graph-map \(f: \Gamma \rightarrow \Gamma\) under which the edges of \(\Gamma\) map to the combinatorial edge paths \(f(a) = d, f(b) = a, f(c) = b^{-1}a,\) and \(f(d) = ba^{-1}db^{-1}ac\).

![Figure 1](image-url)  
**Figure 1.** An example graph-map. Left: Original graph \(\Gamma\). Right: Subdivided graph \(\Delta\) with labels. Our example \(f: \Gamma \rightarrow \Gamma\) is the is the composition of the “identity” \(i: \Gamma \rightarrow \Delta\) with the map \(f': \Delta \rightarrow \Gamma\) that sends edges to edges preserving labels and orientations.
To describe this example precisely, give $\Gamma$ a linear structure and let $\Delta$ be the graph obtained by subdividing $\Gamma$ as pictured on the right of Figure 1. The identity then gives a graph-map $\iota : \Gamma \to \Delta$. Labeling the edges of $\Delta$ as indicated, there is a unique linear graph-map $f' : \Delta \to \Gamma$ for which each edge of $\Delta$ maps by an affine map to the edge of the same label in $\Gamma$. Our example is defined to be the graph-map

$$f := f' \circ \iota : \Gamma \to \Gamma.$$ 

**Definition 2.3** (Regular and expanding maps). A topological graph-map $f : \Gamma \to \Delta$ is **regular** if for any $e \in ET$ the combinatorial edge-path $f(e)$ is non-degenerate and tight (thus $|f(e)| > 0$). We say that a topological graph map $f : \Gamma \to \Gamma$ is **expanding** if for every edge $e \in ET$ we have $|f^n(e)| \to \infty$ as $n \to \infty$.

Let $f : \Gamma \to \Delta$ be a regular topological graph-map and let $v \in VT$. Define an equivalence relation $\sim_{f,v}$ on $Lk_v(v)$ by saying that for $e, e' \in Lk_f(v)$ we have $e \sim_{f,v} e'$ whenever the combinatorial edge-paths $f(e)$ and $f(e')$ start with the same (oriented) edge of $\Delta$. An equivalence class with respect to $\sim_{f,v}$ is called a **gate** at $v$ corresponding to $f$.

**Definition 2.4** (Tame maps). A topological graph-map $f : \Gamma \to \Delta$ is **tame** if $f$ is regular and if for every vertex $v \in VT$ there are at least two gates of $f$ at $v$. Note that if $f : \Gamma \to \Delta$ is tame then every vertex of $\Gamma$ has valence $\geq 2$.

**Definition 2.5** (Taken turns and Whitehead graphs). Let $f : \Gamma \to \Gamma$ be a regular graph-map. A turn $e_1, e_2$ in $\Gamma$ is **taken** by $f$ if there exist $e \in ET$ and $n \geq 1$ such that $e_1^{-1}e_2$ is a subpath of $f^n(e)$ (that is, if the turn $e_1, e_2$ is contained in $f^n(e)$). For any vertex $v \in VT$ we define the **Whitehead graph** of $v$, denoted $Wh_f(f,v)$ or just $Wh(f,v)$ if $\Gamma$ is fixed, as follows. The graph $Wh(f,v)$ is a simple graph whose vertex set is $Lk_f(v)$. Thus the vertices of $Wh_f(f,v)$ are exactly all those $e \in ET$ such that $o(e) = v$. Two distinct elements $e_1, e_2 \in Lk_f(v)$ are adjacent as vertices in $Wh(f,v)$ whenever the turn $e_1, e_2$ is taken by $f$. (Note that since $e_1 \neq e_2$, the turn $e_1, e_2$ is nondegenerate.)

**Remark 2.6.** For a regular graph-map $f : \Gamma \to \Gamma$ denote by $Turn_{\infty}(f)$ the set of all turns contained in the paths $\{f^k(e) : e \in ET, 1 \leq k \leq n\}$. Then $Turn_{\infty}(f) \subseteq Turn_{\infty+1}(f)$ for all $n \geq 1$. Put $Turn_{\infty}(f) := \cup_{n \geq 1} Turn_n(f)$. By definition, for a vertex $v \in \Gamma$ the Whitehead graph $Wh(f,v)$ records all the nondegenerate turns at $v$ that belong to $Turn_{\infty}(f)$.

Let $\Gamma$ be a finite topological graph with at least one edge and let $f : \Gamma \to \Gamma$ be a topological graph-map. Choose an orientation on $\Gamma$ and let $e_1, \ldots, e_k$ be an ordering of $E_\Gamma$. The **transition matrix** $A(f) = (a_{ij})_{i,j=1}^k$ is a $k \times k$ matrix where for $1 \leq i, j \leq k$ the entry $a_{ij}$ is the total number of occurrences of $e_j^{-1}$ in the path $f(e_i)$ (note that this definition gives the transpose of that used for the transition matrix in [BH]). Thus for every $n \geq 1$ we have $A(f^n) = A(f)^n$. Define $\lambda(f)$ to be the spectral radius of the transition matrix $A(f)$.

We say that $A(f)$ is **positive**, denoted $A(f) > 0$, if $a_{ij} > 0$ for all $1 \leq i, j \leq k$. We say that $A = A(f)$ is **irreducible** if for every $1 \leq i, j \leq k$ there exists $t = t(i,j) \geq 1$ such that $(A^t)_{ij} > 0$. Thus if $A(f) > 0$ then $A(f)$ is irreducible. Note that if $A(f)$ is irreducible then $\lambda(f)$ is exactly the Perron-Frobenius eigenvalue of $A(f)$. Furthermore, when $A(f)$ is irreducible, the property $\lambda(f) > 1$ is equivalent to $f$ being expanding, which is also equivalent to $A(f)$ not being a permutation matrix.

**Example 2.7.** Consider again our running example graph-map $f : \Gamma \to \Gamma$ defined in Example 2.2. The four combinatorial edge paths $f(a) = d$, $f(b) = a$, $f(c) = b^{-1}a$ and $f(d) = ba^{-1}db^{-1}ac$ are all reduced; therefore $f$ is a regular graph-map. Hence we also see that the gates at the left and right vertices of $\Gamma$ are

$$\{a\}, \{b\}, \{d\}, \quad \text{and} \quad \{a^{-1}\}, \{b^{-1}\}, \{c\}, \{d^{-1}\},$$
respectively; thus $f$ is tame. One may also calculate by hand the Whitehead graphs of $f$ for the vertices of $\Gamma$, which we have illustrated in Figure 2. Namely, in the notations of Remark 2.6, Figure 2 shows all the nondegenerate turns that belong to $\text{Turns}_3(f)$ is this example. A direct check shows that $\text{Turns}_3(f) = \text{Turns}_4(f)$ here and hence $\text{Turns}_\infty(f) = \text{Turns}_3(f)$. Therefore the graphs shown in Figure 2 are exactly the Whitehead graphs of the two vertices of $\Gamma$. Note that both these Whitehead graphs are connected.

Finally, the transition matrix, Perron–Frobenius eigenvalue and corresponding unit eigenvector for this example are

$$A(f) = \begin{pmatrix} 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 \\ 2 & 2 & 1 & 1 \end{pmatrix}, \quad \lambda \approx 2.4142, \quad v \approx \begin{pmatrix} 2265 \\ 0.939 \\ 1.327 \\ 0.5469 \end{pmatrix}.$$ 

The characteristic polynomial of $A(f)$ is $x^4 - x^3 - 2x^2 - 3x - 1$. It is easy to check that $A(f)^3$ is positive, so $A(f)$ is irreducible. Since $\lambda(f) > 1$, we also see that $f$ is expanding.

The following statement about computing topological entropy of topological graph-maps appears to be a known “folklore” fact for the setting of linear graph-maps with an irreducible transition matrix, although we were unable to find an explicit reference for it in the literature. In that context, this fact is a straightforward corollary of Theorem 7.1 in the paper [Bow] of Bowen (using the “canonical eigenmetric” on the graph, constructed as in §3 below) which allows one to compute the topological entropy by counting $n$-periodic points of $\Gamma$ as $n \to \infty$. The version we provide below is more general and applies to topological graph-maps that may be the identity maps on some small non-degenerate subintervals of some edges (thus $f$ could have continuumly many fixed points, in which cases Bowen’s result is not applicable) and also which do not necessarily have irreducible transition matrix (so that a “uniformly expanding” metric on the graph required by Bowen’s theorem is not necessarily available even in the linear-graph context).

Proposition 2.8. Let $\Gamma$ be a finite connected topological graph with at least one edge and let $f: \Gamma \to \Gamma$ be regular topological graph-map. Let $h(f)$ be the topological entropy of $f$.

Then $h(f) = \log \lambda(f)$ (recall that $\lambda(f)$ is the spectral radius of $A(f)$).

Proof. This statement follows, for example, by a direct application of Lemma 3.2 of [AMM]. In the notations of [AMM], for any $x \in \Gamma$ the set $f^{-1}(x)$ is finite and we have $K_f(x) = \{x\}$. With $A = VT$, the triple $(\Gamma, A, f)$ satisfies the condition from [AMM] of being a “monotone representative of an action”. In the notations of [AMM], the partition $A^f_\bullet$ of $\Gamma$ consists of all the vertices and open 1-cells of $\Gamma$ and the partition $A^n_f$ of $\Gamma$ consists of all the $f^n$-preimages of vertices and of all the connected components of the $f^n$-preimages of open 1-cells. Thus, up to an additive
constant independent of \(n\), the cardinality \(\#(A^n)\) of the partition \(A^n\) is equal to \(\sum_{e \in E, \Gamma} |f^n(e)|\) (where \(E, \Gamma\) comes from any choice an orientation on \(\Gamma\)). In other words, \(\#(A^n)\) is equal, up to a finite additive error independent of \(n\), to the sum of all the entries of the matrix \((A(f))^n\).

By Lemma 3.2 of [AMM] we have

\[
(*) \quad h(f) = \lim_{n \to \infty} \frac{1}{n} \log \#(A^n) = \log \lambda(f),
\]

where \(\lambda(f)\) is the Perron-Frobenius eigenvalue of \(A(f)\) and \(\lambda(f) > 1\). If \(\lambda(f) = 1\) then the sum of all the entries of \((A(f))^n\) grows polynomially in \(n\) and equation (*) yields \(h(f) = 0\). Thus we have \(h(f) = 0 = \log 1 = \log \lambda(f)\), as required.

If \(\lambda > 1\), then there is a constant \(c \geq 1\) independent of \(n\) such that for every \(n \geq 1\) we have \(\frac{1}{n} \lambda(f)^n \leq \#(A^n) \leq c \lambda(f)^n\). Then by (*) we again have \(h(f) = \log \lambda(f)\), as required. \(\square\)

2.5. Train-tracks. To obtain sufficient information to prove Theorems C and D we will make heavy use of a certain class of graph-maps introduced in [BH] that have additional structure. This extra structure ensures that the map and all of its powers are combinatorially efficient.

**Definition 2.9** (Train-track map). Let \(\Gamma\) be a finite connected (linear) graph with at least one edge and without valence-1 vertices. A (linear) graph-map \(f: \Gamma \to \Gamma\) is a train-track map if:

1. The map \(f\) is a homotopy equivalence (and hence \(f\) is surjective).
2. For every edge \(e \in E\) and every \(n \geq 1\) the map \(f^n|_e\) is an immersion; that is, the edge-path \(f^n(e)\) is tight and non-degenerate. (Note that this implies that for every \(n \geq 1\) the map \(f^n: \Gamma \to \Gamma\) is regular.)
3. If \(v\) is a vertex of valence 2 in \(\Gamma\) then for every \(n \geq 1\) the map \(f^n\) is an immersion near \(v\); that is, for every \(n \geq 1\) there exists an open neighborhood \(J\) of \(v\) in \(\Gamma\) such that \(f^n|_J\) is injective.

Note that if \(f\) is a train-track map then any turn taken by \(f\) is automatically non-degenerate.

An irreducible train track map is a train-track map \(f: \Gamma \to \Gamma\) such that the transition matrix \(A(f)\) is irreducible. In this case, the Perron-Frobenius theory tells us that \(\lambda(f) \geq 1\) is an irreducible train track map is a train-track map \(f: \Gamma \to \Gamma\) such that the transition matrix \(A(f)\) is irreducible. In this case, the Perron-Frobenius theory tells us that \(\lambda(f) \geq 1\) is an eigenvalue of \(A(f)\), that there exists a unique (up to a scalar multiple) left eigenvector \(v\) for \(A(f)\) with \(A(f)v = \lambda(f)v\), and that all the coordinates of \(v\) are positive. We normalize \(v\) so that the sum of its coordinates is equal to 1. The coordinates of \(v\) then define a length function \(E \to \mathbb{R}_+\) which together with the linear structure induces a metric structure \(L\) on \(\Gamma\) so that \(\text{vol}_L(\Gamma) = 1\) and such that for every \(e \in E\) we have \(f(e)|_L = \lambda(f)L(e) = \lambda(f)\|e\|_L\). We call this \(L\) the train-track metric structure on \(\Gamma\) and the geodesic metric \(d_L\) the train track metric on \(\Gamma\).

The following lemma implies that condition (3) in Definition 2.9 is often automatically satisfied.

**Lemma 2.10.** Let \(\Gamma\) be a finite connected topological graph with at least one edge and let \(f: \Gamma \to \Gamma\) be an expanding topological graph-map with an irreducible transition matrix \(A(f)\) and such that for every edge \(e \in E\) and every \(n \geq 1\) the map \(f^n|_e\) is an immersion. Then:

1. For every edge \(e \in E\) there exists an edge \(e' \in E\) with \(o(e) = o(e')\) such that the turn \(e, e'\) is taken by \(f\).
2. The map \(f^n\) is tame, there is at least one turn taken at every vertex of \(\Gamma\) and the graph \(\Gamma\) has no degree-1 vertices. Moreover, if \(v\) is a vertex of valence 2 in \(\Gamma\) then for every \(n \geq 1\) the map \(f^n\) is an immersion near \(v\).

**Proof.** Let \(e \in E\) be an arbitrary edge. Since \(f\) is expanding, there exists \(m \geq 1\) such that \(|f^m(e)| \geq 3\). Thus \(f^m(e) = \alpha e_0 \beta\) where \(e_0 \in E\) and where \(\alpha, \beta\) are reduced edge-paths with \(\|\alpha\|, \|\beta\| > 0\). Since the matrix \(A(f)\) is irreducible, there exists \(k \geq 1\) such that the path \(f^k(e_0)\) passes through \(e\) or \(e^{-1}\). Hence the path \(f^{k+m}(e) = f^k(\alpha)f^k(e_0)f^k(\beta)\) contains \(e\) or \(e^{-1}\) as an interior edge, that is, an edge that is neither initial nor terminal in \(f^{n+k}(e)\). Therefore there
exists an edge \( e' \) with \( o(e') = o(e) \) such that the turn \( e, e' \) occurs in \( f^{n+k}(e) \), so that the turn \( e, e' \) is taken by \( f \). Thus part (1) of the lemma is verified. Part (2) is a direct corollary of part (1) in view of the assumptions on \( f \).

\[ \square \]

**Remark 2.11.** Note that if \( f : \Gamma \rightarrow \Gamma \) is an irreducible train-track map and \( d_{\mathcal{L}} \) is the train-track metric on \( \Gamma \), it is not necessarily true that the map \( f \) is locally a \( \lambda(f) \)-homothety on every edge of \( \Gamma \). The reason is that \( \Gamma \) comes equipped with a linear structure \( \Lambda \) such that for each \( e \in E\Gamma \), there exists a unique chart map \( j_e : \mathbb{R} \rightarrow \Gamma \) in \( \Lambda \) mapping \( (0, \mathcal{L}(e)) \) homeomorphically to \( e \).

If \( f(e) = e_1 \cdots e_m \), then there is a unique subdivision \( 0 = t_0 < t_1 < \cdots < t_m = \mathcal{L}(e) \) such that \( f \circ j_e \) maps \((t_{i-1}, t_i)\) homeomorphically to \( e_i \). Note that the relative lengths of the subintervals \((t_{i-1}, t_i)\) are specified by the linear structure. In general, there is no reason to assume that we will have \( \mathcal{L}(f(e)) = \lambda(f) \mathcal{L}(e) \). Therefore, even though \( \mathcal{L}(f(e)) = \lambda(f) \mathcal{L}(e) \), the map \( f \) may stretch the metric \( d_{\mathcal{L}} \) on the subsegments \( j_e([t_{i-1}, t_i]) \) of \( e \) by different amounts, depending on \( i \) and not necessarily equal to \( \lambda(f) \).

However, in §3 we will see that this problem can be fixed by changing the linear structure on \( \Gamma \) in a way that \( f \) remains a linear graph-map and, with respect to the corresponding train track metric, \( f \) is locally a \( \lambda(f) \)-homothety on edges.

If \( f : \Gamma \rightarrow \Gamma \) is a regular topological graph-map, we have a natural derivative map \( D_f : E\Gamma \rightarrow E\Gamma \), where for \( e \in E\Gamma \) we define \( D_f(e) \) to be the initial edge of the edge-path \( f(e) \). The map \( D_f \) naturally extends to \( D_f : \text{Turns}(\Gamma) \rightarrow \text{Turns}(\Gamma) \) by setting \( D_f(e, e') := \{ D_f(e), D_f(e') \} \), where \( e, e' \) is a turn in \( \Gamma \). A turn \( t \in \text{Turns}(\Gamma) \) is then called legal for \( f \) if \( (D_f)^n(t) \) is non-degenerate for every \( n \geq 0 \).

**Remark 2.12.** Consider a finite graph \( \Gamma \) without valence-1 vertices and a homotopy equivalence regular (linear) graph-map \( f : \Gamma \rightarrow \Gamma \). In this situation it is easy to see that \( f \) is a train-track map if and only if the unique non-degenerate turn at each valence-2 vertex is legal and every turn contained in an edge-path of the form \( f(e) \) for \( e \in E\Gamma \) is legal. Moreover, it is easy to check whether a given turn is legal because the set \( \text{Turns}(\Gamma) \) is finite. Therefore, it is straightforward and algorithmic to determine whether the given map \( f \) is a train track-map.

**Example 2.13.** The graph-map \( f \) introduced in Example 2.2 is actually a train-track map. This fact can be easily checked by hand using the algorithm explained in Remark 2.12 above, and we have also verified that \( f \) is a train-track map using Peter Brinkmann’s software package xtrain\(^1\).

### 2.6. Outer automorphisms.

For an integer \( N \geq 2 \) let \( F_N = F(x_1, \ldots, x_N) \) be the free group of rank \( N \). Recall that \( \text{Out}(F_N) \) is the group of all automorphisms of \( F_N \) modulo the subgroup of inner automorphisms

An element \( \varphi \in \text{Out}(F_N) \) is said to be reducible if there exists a free product decomposition \( F_N = A_1 \ast \cdots \ast A_k \ast C \) with \( k \geq 1 \) and each \( A_i \neq \{1\} \) (and where it is possible that \( C = \{1\} \)) such that \( \varphi \) permutes the conjugacy classes \([A_1], \ldots, [A_k] \).

An element \( \varphi \in \text{Out}(F_N) \) is irreducible if it is not reducible. Moreover, \( \varphi \in \text{Out}(F_N) \) is said to be fully irreducible or iwip (for “irreducible with irreducible powers”) if \( \varphi^n \) is irreducible for every \( n \geq 1 \). Thus \( \varphi \) is fully irreducible if and only if there do not exist \( n \geq 1 \) and a proper free factor \( A \) of \( F_N \) such that \( \varphi^n([A]) = [A] \). We say, \( \Phi \in \text{Out}(F_N) \) is said to be irreducible (respectively, fully irreducible) if the outer automorphism class \( \varphi \in \text{Out}(F_N) \) of \( \Phi \) is irreducible (respectively, fully irreducible).

Finally, \( \varphi \in \text{Out}(F_N) \) (or an element of \( \text{Aut}(F_N) \) representing \( \varphi \)) is called atoroidal or hyperbolic if there do not exist \( n \geq 1 \) and \( w \in F_N \) such that \( \varphi^n \) preserves the conjugacy class \([w] \) of \( w \) in \( F_N \). A result of Brinkmann [Bri] (utilizing the Bestvina–Feighn Combination

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\(^1\)Available at http://gitorious.org/xtrain
Theorem [BF1]) says that \( \varphi \in \text{Aut}(F_N) \) is hyperbolic if and only if the mapping torus group \( G_\varphi = F_N \times_{\varphi} \mathbb{Z} \) of \( \varphi \) is word-hyperbolic.

2.7. Topological representatives. Given a finite connected graph \( \Gamma \) and a homotopy equivalence topological graph-map \( f: \Gamma \to \Gamma \), let \( v \in V\Gamma \) be a vertex and let \( \beta \) be an edge-path from \( v \) to \( f(v) \). We denote by \( f_*: \pi_1(\Gamma, v) \to \pi_1(\Gamma, v) \) the map given by \( f_*([\gamma]) = [\beta(f \circ \gamma) \beta^{-1}] \), where \( \gamma \) is an edge-path from \( v \) to \( v \) in \( \Gamma \).

**Definition 2.14** (Topological representative). Let \( \varphi \in \text{Out}(F_N) \), where \( N \geq 2 \). A topological representative of \( \varphi \) is a pair \((m,f)\) where \( f: \Gamma \to \Gamma \) is a homotopy equivalence topological graph-map of a finite connected topological graph \( \Gamma \) to itself, and where \( m: F_N \to \pi_1(\Gamma, v) \) is an isomorphism such that \( m^{-1} \circ f_* \circ m: F_N \to F_N \) is an automorphism of \( F_N \) whose outer automorphism class is \( \varphi \). The isomorphism \( m \) is called a marking. By convention, we will usually omit the explicit mention of marking and just say that \( f: \Gamma \to \Gamma \) is a topological representative of \( \varphi \).

If \( P \) is a type of topological graph-map (such as “regular” or “linear”), we say that a topological representative \( f: \Gamma \to \Gamma \) is \( P \) if the topological graph-map \( f \) of type \( P \). Alternately we may say that \( f: \Gamma \to \Gamma \) is a \( P \) representative of \( \varphi \). Thus we may discuss regular representatives, tame representatives, irreducible train-track representatives, and so on. We emphasize that if \( f \) is a train-track representative of \( \varphi \), then this automatically implies that \( f \) is a regular topological representative of \( \varphi \) and that \( f^n: \Gamma \to \Gamma \) is a train-track representative of \( \varphi^n \) for all \( n \geq 1 \).

Given any \( \varphi \in \text{Out}(F_N) \), one can easily construct a regular topological representative for \( \varphi \) with \( \Gamma \) being a wedge of circles. Constructing representatives with more structure is in general harder and may depend on the outer automorphism \( \varphi \). An important general result of Bestvina and Handel [BH] says that for every irreducible \( \varphi \in \text{Out}(F_N) \) (where \( N \geq 2 \)) there exists an irreducible train-track topological representative of \( \varphi \). The converse is, in general, not true: it is possible for an irreducible train-track map to be a topological representative of a reducible \( \varphi \in \text{Out}(F_N) \). However, if \( \varphi \in \text{Out}(F_N) \) is fully irreducible then every train-track representative of \( \varphi \) has irreducible transition matrix and thus is an irreducible train-track map. We discuss the relationship between fully irreducible hyperbolic outer automorphisms and the properties of their train-track representatives in greater detail in §5 below.

**Example 2.15.** We now return to the graph map \( f: \Gamma \to \Gamma \) introduced in Example 2.2. We have \( \pi_1(\Gamma) \cong F_3 \) and it is not hard to check directly that \( f \) is a homotopy equivalence; thus \( f \) is a topological representative of an element \( \varphi \in \text{Out}(F_3) \). Specifically, use \( v_0 = o(c) \) as a base-vertex in \( \Gamma \) and put \( x_1 = b^{-1}a, x_2 = a^{-1}d \) and \( x_3 = c \). Then \( \{x_1, x_2, x_3\} \) is a free basis of \( \pi_1(\Gamma, v_0) \), which gives us an identification (i.e., marking) \( F(x_1, x_2, x_3) = \pi_1(\Gamma, v_0) \). The automorphism \( \varphi \) is then given by \( \varphi(x_1) = x_2, \varphi(x_2) = x_2^{-1}x_1x_2x_3, \varphi(x_3) = x_1 \). We have moreover verified, with the help of Derek Holt the computational software package kbmag\(^2\), that the group \( G_\varphi \) is word-hyperbolic and therefore the automorphism \( \varphi \) is hyperbolic. In Example 5.5 we will see that \( \varphi \) is also fully irreducible.

3. Expansion and promotion of topological graph-maps

Given a topological graph-map \( f: \Gamma \to \Gamma \), we say that \( f \) is expanding on all scales if for every \( x \in \Gamma \), every neighborhood \( U \) of \( x \), and every edge \( e \) of \( \Gamma \), there exists a positive integer \( m \) and an open interval \( W \subset U \) so that \( f^m \) maps \( W \) homeomorphically onto \( e \). Observe that as an immediate consequence, \( f(e) \) is always a nondegenerate combinatorial edge-path (it cannot be constant on any open set).

Let us first observe that for graph maps, expanding on all scales is a rather mild condition that can be deduced from the combinatorial data.

\(^2\)Available at http://www.gap-system.org/Packages/kbmag.html
Lemma 3.1. Let \( f : \Gamma \to \Gamma \) be a graph map of a finite (linear) graph \( \Gamma \). Suppose that \( f \) is expanding and that \( A(f) \) is irreducible. Then \( f \) is expanding on all scales.

Proof. The graph \( \Gamma \) comes equipped with a linear structure \( \Lambda \). For each edge \( e \) and any chart \((e_\alpha, j_\alpha, [a_\alpha, b_\alpha])\) with \( e_\alpha = e \), the composition \( f \circ j_\alpha : [a_\alpha, b_\alpha] \to \Gamma \) is a PL edge-path. Thus if \( e_1 \ldots e_n \) is the combinatorial edge-path \( f(e) \) then there is a partition \( a_\alpha = c_0 < c_1 \ldots < c_n = b_\alpha \) of \([a_\alpha, b_\alpha]\) so that \( f \circ j_\alpha \) is a homeomorphism of \((c_{i-1}, c_i)\) onto \( e_i \) for each \( i = 1, \ldots, n \). We then define the subdivision ratios of the edge \( e \) to be the numbers \( \rho_i = \frac{c_{i+1} - c_i}{c_i - c_{i-1}} \) for \( i = 1, \ldots, n \). These numbers all satisfy \( 0 < \rho_i < 1 \) unless \( n = 1 \). Notice that since the transition functions between charts are affine, these numbers do not depend on the choice of the chart \( j_\alpha : [a_\alpha, b_\alpha] \to \Gamma \). Since \( \Gamma \) has finitely many edges, there are only finitely many subdivision ratios, and we let \( \rho \) denote the maximal ratio that is strictly less than 1.

For an edge \( e_0 \in \mathcal{E} \) of \( \Gamma \) we will now analyze what happens to \( e_0 \) under iteration by \( f \). By the maximality condition for linear structures, \( \Lambda \) contains a chart of the form \((e_0, j_0, [0, 1])\). For \( k \geq 0 \) the set \( f^{-k}(\mathcal{E}) \) partitions \([0, 1]\) into subintervals, each of which is mapped homeomorphically onto an edge of \( \Gamma \) by \( f^k \). Let \( S_k \) denote the set of intervals in this subdivision. Suppose that an interval \( I \in S_k \) is mapped homeomorphically onto \( e \in \mathcal{E} \) by \( f^k \). Then \( I \) becomes further subdivided in \( S_{k+1} \) into subintervals of lengths \( \text{len}(I)\rho_j^1, \ldots, \text{len}(I)\rho_j^{|f(e)|} \). In particular, if \( |f(e)| \geq 2 \), then each of these subintervals has length at most \( \text{len}(I)\rho \).

Let \( l_k \) denote the maximal length of any subinterval in \( S_k \). Notice that, since intervals are only ever subdivided (i.e., \( f^{-k}(\mathcal{E}) \subset f^{-k-1}(\mathcal{E}) \)), \( l_k \) is nonincreasing. We claim that \( l_k \) in fact tends to 0 as \( k \to \infty \). Indeed, since \( f \) is expanding, there exits \( M \geq 1 \) so that \( |f^M(e)| \geq 2 \) for every \( e \in \mathcal{E} \) (notice that \( |f^n(e)| \) is nondecreasing function of \( n \)). It follows that every interval in \( S_k \) becomes subdivided in \( S_{k+M} \). Therefore \( l_{k+M} \leq l_k\rho \) for all \( k \geq 0 \) and we conclude \( l_k \to 0 \).

We now prove that \( f \) is expanding on all scales. Given \( x \in \Gamma \) and a neighborhood \( U \) of \( x \), we may find an open interval \( U' \subset U \) that is contained in some edge \( e_0 \) of \( \Gamma \). The above discussion shows that for some sufficiently large \( k \), \( U' \) contains an interval \( W' \subset U' \) that is mapped homeomorphically over some edge \( e_1 \). Let \( e \in \mathcal{E} \) be any edge. Since \( A(f) \) is irreducible, there exists a power \( n \) so that the combinatorial edge-path \( f^n(e_1) \) crosses \( e \) or \( e^{-1} \). Therefore, there is a further subinterval \( W' \subset W' \) so that \( f^{k+n}(W) \) is mapped homeomorphically onto \( e \). \( \square \)

While a topological graph map is always homotopic to a graph map with respect to a linear structure, the next theorem says that when the map is expanding on all scales it is possible to achieve this property without adjusting the map by a homotopy.

Recall that if \( \Gamma \) is a topological graph and \( e \in \mathcal{E} \) then \( \overline{\pi} \) denotes the closure of \( e \) in \( \Gamma \).

Theorem 3.2. Suppose \( f : \Gamma \to \Gamma \) is a topological graph-map that is expanding on all scales and such that for every \( e \in \mathcal{E} \) the combinatorial edge-path \( f(e) \) is tight (i.e. that \( f \) is locally injective on \( e \)). Choose an orientation on \( \Gamma \) and an ordering \( E_+ \Gamma = \{e_1, \ldots, e_n\} \).

Then the topological graph-map \( f \) is expanding, the matrix \( A(f) \) is irreducible with the Perron-Frobenius eigenvalue \( \lambda = \lambda(f) > 1 \), and there exists a volume-1 metric structure \( \mathcal{L} \) on \( \Gamma \) with the following properties:

(1) The restriction of \( f \) to any edge is a local \( \lambda \)-homothety with respect to \( d_\mathcal{L} \). This means that for any \( p \in e \) there exists a neighborhood \( U \) of \( p \) in \( e \) such that for all \( x, y \in U \) we have \( d_\mathcal{L}(f(x), f(y)) = \lambda d_\mathcal{L}(x, y) \), and there exist a non-degenerate initial segment \( J_+ \) of \( \overline{\pi} \) and a non-degenerate terminal segment \( J_- \) of \( \overline{\pi} \) such that for any \( x, y \in J_+ \) and any \( x, y \in J_- \) we have \( d_\mathcal{L}(f(x), f(y)) = \lambda d_\mathcal{L}(x, y) \).

(2) For every \( i = 1, \ldots, n \) the \( d_\mathcal{L} \)-length of \( e_i \) is equal to \( v_i \) where \( v = (v_1, \ldots, v_n)^T \) is the left Perron-Frobenius eigenvector (i.e. for the left action of \( A(f) \) on column vectors) with \( \sum_{i=1}^n v_i = 1 \).
We assume for simplicity that $\Gamma$ has no loop-edges. It will be clear from the proof how to adjust the argument to cover the case where some loop-edges are present.

The assumptions on $f$ imply that $A(f)$ is irreducible. Indeed, given any two edges $e_i, e_j \in E_+\Gamma$, the edge $e_j$ is a neighborhood of any point $x \in e_j$, and as such there exists $m$ and an open interval $W$ in $e_j$ so that $f^m$ maps $W$ homeomorphically onto $e_i$. Therefore, there is at least one occurrence of $e_i$ or $e_i^{-1}$ in $f^m(e_j)$, and hence $(A(f^m))_{ij} \neq 0$.

Clearly, $A(f)$ is not a permutation matrix and thus the topological graph-map $f$ is expanding.

Now let $\Gamma_0 = \Gamma$ and for $k \geq 1$ define $\Gamma_k$ to be the graph obtained by subdividing $\Gamma_{k-1}$ along $f^{-1}(V\Gamma_{k-1})$. By construction $V\Gamma_{k-1} \subset V\Gamma_k$ for all $k \geq 0$. Furthermore, since $f(V\Gamma) \subset V\Gamma$, it follows that $V\Gamma_k = (f^k)^{-1}(V\Gamma)$. Given any edge $e_{k,0} \in E\Gamma_k$ for any $k \geq 0$, the subdivision makes $e_{k,0}$ into a combinatorial edge-path $\gamma_{e_{k,0}} = e_{k+1,1}e_{k+1,2} \cdots e_{k+1,r}$ in $\Gamma_{k+1}$. Also, for every $k \geq 1$, we have $f(e_{k,0})$ is an edge $e_{k-1,0} \in E\Gamma_{k-1}$.

**Claim 3.3.** The set

$$V = \bigcup_{k=0}^{\infty} V\Gamma_k$$

is dense in $\Gamma$.

**Proof of claim.** Given any $x \in \Gamma$ and any neighborhood $U$, we need only prove that $V\Gamma_k \cap U \neq \emptyset$ for $k$ sufficiently large. Let $e$ be any edge of $\Gamma$ and let $m$ and $W \subset U$ be as in the definition of $f$ being expanding on all scales. Without loss of generality, we can assume that $W \subset U$ (by replacing $U$ with a strictly smaller neighborhood before finding $m$ and $W$). Then $f^m(W) = \overline{\ell}$, and hence $(f^m)^{-1}(o(e) \cup t(e)) \subset U$. Therefore $(f^m)^{-1}(V\Gamma) = V\Gamma_m$ nontrivially intersects $U$, and we set $k = m$. $\square$

**Claim 3.4.** There exists a sequence of length functions $\{L_k : E\Gamma_k \to \mathbb{R}_+\}_{k=0}^{\infty}$ with the following two properties.

1. For every edge $e_{k,0} \in E\Gamma_k$, with $k \geq 0$, if $\gamma_{e_{k,0}} = e_{k+1,1}e_{k+1,2} \cdots e_{k+1,r}$ is the combinatorial edge-path representing $e_{k,0}$ in $E\Gamma_{k+1}$, then

   $$L_k(e_{k,0}) = \sum_{\ell=1}^{r} L_{k+1}(e_{k+1,\ell}).$$

2. For every edge $e_{k,0} \in E\Gamma_k$, with $k \geq 1$, if we write $f(e_{k,0}) = e_{k-1,0}$, then

   $$\lambda L_k(e_{k,0}) = L_{k-1}(e_{k-1,0}).$$

**Proof of Claim.** To construct this sequence of length functions, we define $L_0$ first to be given by $L(e_i) = L(e_i^{-1}) = v_i$, where $\mathbf{v} = (v_1, \ldots, v_n)$ is the Perron-Frobenius eigenvector for $\lambda$. Then for $k \geq 1$ define $L_k$ in terms of $L_{k-1}$ inductively by the second condition. Equivalently, we note that for every $k \geq 1$ and every edge $e_{k,0} \in E\Gamma_k$, we have $f^k$ maps $e_{k,0}$ homeomorphically onto some edge $e_i \in E\Gamma$ and so its $L_k$-length is $\lambda^{-k}v_i$.

It remains to verify that the first property holds. Fix $e_{k,0}$ and we let $i$ be as above so that $f^k$ maps $e_{k,0}$ homeomorphically onto $e_i$. The next iteration of $f$ maps $e_i$ over each edge $e_j$ exactly $a_{ij}$ times and we have

$$\lambda v_i = \sum_{i=1}^{n} a_{ij}v_j.$$  \hspace{1cm} (3.1)

On the other hand, writing

$$e_{k,0} = e_{k+1,1}e_{k+1,2} \cdots e_{k+1,r}$$
and letting \( j(\ell) \) be such that \( f^{k+1} \) maps \( e_{k+1, \ell} \) homeomorphically onto \( e_{j(\ell)} \), it follows that
\[
f(e_{i}) = e_{j(1)}e_{j(2)} \cdots e_{j(r)},
\]
and so comparing with (3.1) we have
\[
\lambda v_{i} = \sum_{\ell=1}^{r} v_{j(\ell)}.
\]
The \( L_{k+1} \)-length of \( e_{k+1, \ell} \) is \( \lambda^{-(k+1)}v_{j(\ell)} \) and therefore we have
\[
L_{k}(e_{k,0}) = \lambda^{-k}v_{i} = \lambda^{-k} \left( \lambda^{-1} \sum_{\ell=1}^{r} v_{j(\ell)} \right) = \lambda^{-(k+1)} \sum_{\ell=1}^{r} v_{j(\ell)} = \sum_{\ell=1}^{r} L_{k+1}(e_{k+1, \ell}).
\]

We now prove that there exists a metric structure with the required properties. As a consequence of the second condition, we note that the \( L_{k} \)-length of any edge of \( E\Gamma_{k} \) is at most \( \lambda^{-k} \) times the maximum \( L_{0} \)-length of the edges in \( E\Gamma_{0} = E\Gamma \). In particular, the maximum \( L_{k} \)-length of any edge in \( E\Gamma_{k} \) tends to zero as \( k \to \infty \).

Now suppose that \( e \in E\Gamma \) and that \( x, y \in V \cap \pi \) are any two points. We define a “distance in \( e \)" \( d_{V,e}(x, y) \) between \( x \) and \( y \) to be the sum of the \( L_{k} \)-length of the edges between \( x \) and \( y \) inside \( e \), provided \( x, y \in VT_{k} \) (which is valid for all sufficiently large \( k \), depending on \( x \) and \( y \)). By the first condition, this definition of \( d_{V,e}(x, y) \) is independent of \( k \) and hence we get a metric \( d_{V,e} \) on \( V \cap \pi \). Moreover, by construction, with respect to the ordering on \( V \cap \pi \) induced by the orientation on \( e \), if \( x < y < z \) are three points in \( V \cap \pi \), then
\[
d_{V,e}(x, z) = d_{V,e}(x, y) + d_{V,e}(y, z).
\]
Because the \( L_{k} \)-length of edges in \( E\Gamma_{k} \) tend to zero and because \( V \cap e \) is dense in \( \pi \), we can extend \( d_{V,e} \) to a geodesic metric \( d_{e} \) on \( \pi \) (inducing the given topology): for an arbitrary pair of points \( x', y' \) in \( \pi \), we can approximate \( d_{e}(x', y') \) from above (respectively, below) by \( d_{V,e} \)-distances between points in \( V \) limiting to \( x', y' \) from outside (respectively, inside) the arc between \( x' \) and \( y' \). For \( x, y \in V \cap \pi \) we will have \( d_{e}(x, y) = d_{V,e}(x, y) \).

The collection of metrics \( d_{e} \) on edges of \( \Gamma \) determines a geodesic metric \( d \) on \( \Gamma \) consistent with the original topology on \( \Gamma \). By construction of \( d_{e} \) and using local injectivity of \( f \) on edges, it follows that for any edge \( e \in E\Gamma \) and any sufficiently close points \( x, y \in V \) we have \( d(f(x), f(y)) = \lambda d(x, y) \). Since \( V \) is dense in \( e \), it follows that \( f \) is locally a \( \lambda \)-homothety on edges with respect to \( d \), as required. This completes the proof.

\[\square\]

\textbf{Remark 3.5.} This proof follows closely the strategy for constructing the stable foliation for a pseudo-Anosov in [FLP, Exposé 9.5].

\textbf{Lemma 3.1} and \textbf{Theorem 3.2} immediately imply:

\textbf{Corollary 3.6.} Let \( \Gamma \) be a finite connected (linear) graph and let \( f : \Gamma \to \Gamma \) be a regular graph-map such that \( f \) is expanding and such that \( A(f) \) is irreducible.

Then there exists another linear structure \( \Lambda \) on the underlying topological graph of \( \Gamma \), and a volume-1 metric structure \( \mathcal{L} \) on \( \Gamma \) compatible with \( \Lambda \) such that with respect to \( \Lambda \) the map \( f : \Gamma \to \Gamma \) is still a linear graph-map and such that the restriction of \( f \) to any edge is affine with constant derivative \( \lambda = \lambda(f) \) with respect to \( \mathcal{L} \). (Thus locally on every edge, \( f \) is a \( \lambda(f) \)-homothety with respect to \( d_{\mathcal{L}} \)).
Definition 3.7 (Canonical eigenmetric). Given \( f : \Gamma \to \Gamma \) as in Corollary 3.6 and let \( \Lambda, \mathcal{L} \) and \( d_{\mathcal{L}} \) be provided by Corollary 3.6. We call the linear structure \( \Lambda \) the canonical linear structure corresponding to \( f \) and call \( \mathcal{L} \) the canonical metric structure corresponding to \( f \). We also call the metric \( d_{\mathcal{L}} \) on the topological graph \( \Gamma \) the canonical eigenmetric corresponding to \( f \).

Note that if \( \Gamma \) is a finite (linear) graph and \( f : \Gamma \to \Gamma \) is an expanding irreducible train-track map and if \( \Lambda \) is the canonical linear structure on \( \Gamma \) and \( d_{\mathcal{L}} \) is the canonical eigenmetric then \( d_{\mathcal{L}} \) is exactly the train-track metric on \( \Gamma \) corresponding to \( f \) and \( \Lambda \) (in the sense defined in Subsection 2.5).

4. Folding paths

We will need a metric version of Stallings’ folding line adapted to our setting (see [Sta2, KM] for the classic version of Stallings folds).

Our version of the folding line is more elementary and less canonical than what Francaviglia and Martino call “fast folding line” (see Definition 5.6 in [FM]) and what Bestvina and Feign call “folding all illegal turns at speed 1” (see the definition immediately prior to Proposition 2.2 in [BF2]). While we could have used the “fast folding line” when defining the “folded mapping torus” \( X_f \) in \( \S 6 \) below, the more basic Stallings folds construction is sufficient for our purposes and simpler to analyze.

Convention 4.1. In this subsection let \( \varphi \in \text{Out}(F_N) \), let \( \Gamma \) be a finite connected linear graph and let \( f : \Gamma \to \Gamma \) be a linear graph-map which is a tame topological representative of \( \varphi \). Let \( \mathcal{L} \) be a metric structure on \( \Gamma \) compatible with the given linear graph structure on \( \Gamma \).

Thus for every \( e \in E \Gamma \) \( f(e) \) is a tight nondegenerate edge-path in \( \Gamma \). Also, the tameness assumption implies that every vertex of \( \Gamma \) has valence \( \geq 2 \).

Remark 4.2. Given any \( \varphi \in \text{Out}(F_N) \) it is easy to construct a tame topological representative of \( \varphi \). This can be done, for example, via replacing an arbitrary regular topological representative \( \varphi' : \Gamma \to \Gamma \) of \( \varphi \) by an “optimal” map \( f : \Gamma \to \Gamma \) that is freely homotopic to \( f \), as explained in [FM]. Alternatively, given \( \varphi \in \text{Out}(F_N) \), one can always find, via an explicit combinatorial construction, a tame representative \( f : \Gamma \to \Gamma \) of \( \varphi \) with \( \Gamma \) being a wedge of \( N \) circles, as explained in [KR]. Also, as follows from Corollary 5.4 below, if \( \varphi \in \text{Out}(F_N) \) is a hyperbolic iwip then any train-track representative of \( \varphi \) is tame (since the Whitehead graphs of all vertices are connected). More generally, Lemma 2.10 implies that if \( f : \Gamma \to \Gamma \) is an expanding irreducible train-track map, then \( f \) is tame.

Now we form a new labeled metric graph \( \Delta \) as follows. We have \( \Delta = \Gamma \) as a set and as a topological space. The vertex set of \( \Delta \) is \( V \Delta := f^{-1}(V \Gamma) \cup V \Gamma \) and the 1-cells of \( \Delta \) are the connected components of \( \Delta - V \Delta \). Thus, combinatorially, \( \Delta \) is obtained from \( \Gamma \) by subdividing each edge \( e \) of \( \Gamma \) into \( |f(e)| \) edges. The graph \( \Delta \) inherits a natural linear graph structure from \( \Gamma \) and we still have the graph-map \( f : \Delta \to \Gamma \) which is now an affine homeomorphism on every open 1-cell. We endow \( \Delta \) with a metric structure \( \mathcal{L}_0 \) by setting \( \mathcal{L}_0(e) := \mathcal{L}(f(e)) \) for every \( e \in E \Delta \). For every edge \( e \in E \Delta \) and every vertex \( v \in V \Delta \) we think of \( f(e) \in E \Gamma \) as the label of \( e \) and of \( f(v) \in V \Gamma \) as the label of \( v \). This labeling satisfies the property that \( f(e^{-1}) = (f(e))^{-1} \) and that \( o(f(e)) = o(f(o(e))) \), \( t(f(e)) = f(t(e)) \) for all \( e \in E \Delta \). In general, we call a (linear) graph \( \Psi \) with a labeling \( \tau : V \Psi \to V \Gamma \), \( \tau : E \Psi \to E \Gamma \) of vertices and edges, satisfying these properties, a \( \Gamma \)-graph.

Any \( \Gamma \)-graph \( \Psi \) comes equipped with a canonical graph-map \( \tau : \Psi \to \Gamma \), given by the labeling, which is an affine homeomorphism on open edges. Since \( \tau : \Psi \to \Gamma \) sends an edge to an edge, \( \tau \) is a regular graph-map. A \( \Gamma \)-graph \( \Psi \) is folded if whenever \( e, e' \in E \Psi \) are such that \( o(e) = o(e') \) and \( \tau(e) = \tau(e') \) then \( e = e' \). It is easy to see that for a \( \Gamma \)-graph \( \Psi \) the map \( \tau : \Psi \to \Gamma \) is locally injective if and only if \( \Psi \) is folded. If a \( \Gamma \)-graph \( \Psi \) is not folded and \( e \neq e' \) are elements of \( E \Psi \)
such that \( o(e) = o(e') \) and \( \tau(e) = \tau(e') \), then identifying \( e \) and \( e' \) into a single edge with label \( \tau(e) = \tau(e') \) produces a new \( \Gamma \)-graph \( \Psi' \). We say that \( \Psi' \) is obtained from \( \Psi \) by a combinatorial Stallings fold.

We say that a \( \Gamma \)-graph \( \Psi \) is tame if the label-ling graph-map \( \tau : \Psi \to \Gamma \) is tame. Note that for a \( \Gamma \)-graph \( \Psi \) and a vertex \( v \) of \( \Psi \), the number of gates at \( v \) with respect to the labeling graph-map \( \tau \) is equal to the number of distinct labels of edges of \( \Psi \) with origin \( v \). Thus a \( \Gamma \)-graph \( \Psi \) is tame if and only if for every vertex \( v \) of \( \Psi \) there exist some two edges \( e, e' \in E\Psi \) with \( o(e) = o(e') = v \) and \( \tau(e) \neq \tau(e') \). Hence if \( \Psi \) is a tame \( \Gamma \)-graph and \( \Psi' \) is obtained from \( \Psi \) by a combinatorial Stallings fold then \( \Psi' \) is again tame.

We now return to the construction of a folding path. We can obtain \( \Gamma \) from \( \Delta \) by a finite sequence of combinatorial Stallings folds

(4.1)

\[
\Delta = \Delta_0, \Delta_1, \ldots, \Delta_m = \Gamma
\]

where \( m = \#E_{\text{top}} \Delta - \#E_{\text{top}} \Gamma \) and where each \( \Gamma \)-graph \( \Delta_{i+1} \) is obtained from \( \Delta_i \) by a single combinatorial Stallings fold identifying the edges \( e_i, e'_i \) of \( \Delta_i \). Each \( \Delta_i \) comes equipped with a natural metric structure \( \mathcal{L}'_i \) obtained by pulling back the metric \( \mathcal{L} \) from \( \Gamma \) via the labeling map: for every \( e \in E\Delta \), we have \( \mathcal{L}'_i(e) := \mathcal{L}(\tau(e)) \).

Note that since by assumption, the map \( f : \Gamma \to \Gamma \) is tame and hence the \( \Gamma \)-graph \( \Delta = \Delta_0 \) is tame. Since Stallings folds preserve tameness, it follows that each \( \Delta_i \) is tame. In particular, this means that every vertex of \( \Delta_i \) has valence \( \geq 2 \).

We now define a family of metric graphs \( \kappa^s = (\Gamma^s, \mathcal{L}^s) \), where \( 0 \leq s \leq L \), as follows. We have \( 0 = s_0 < s_1 < \cdots < s_m = L \) with \( \Gamma^{s_i} = \Delta_i \) and \( \mathcal{L}^{s_i} = \mathcal{L}'_i \) (so that \( \Gamma^0 = \Delta, \mathcal{L}^0 = \mathcal{L}_0, \Gamma^L = \Gamma \) and \( \mathcal{L}^L = \mathcal{L} \)) and \( s_{i+1} - s_i = \mathcal{L}'_i(e_i) \). Now for arbitrary \( s \in [s_i, s_{i+1}] \) let \( \Gamma^s \) be obtained from \( (\Delta_i, \mathcal{L}'_i) \) by identifying initial segments of \( e_i \) and \( e'_i \) of \( \mathcal{L}'_i \)-length \( s - s_i \). Then \( \Gamma^s \) inherits from \( (\Delta_i, \mathcal{L}'_i) \) a natural linear graph structure and natural metric structure \( \mathcal{L}^s \).

Remark 4.3. We have noted above that each \( \Delta_i \) is tame and thus has no valence-1 vertices. Therefore for every \( 0 \leq s \leq L \) the graph \( \Gamma^s \) has no valence-1 vertices either, since the new vertices that appear in the middle of performing a single Stallings fold have valence-3.

Each \( \kappa^s = (\Gamma^s, \mathcal{L}^s) \) comes equipped with natural homotopy equivalence graph-maps \( h^s : (\Gamma_0, \mathcal{L}_0) \to (\Gamma^s, \mathcal{L}^s) \) and \( g^s : (\Gamma^s, \mathcal{L}^s) \to (\Gamma, \mathcal{L}) \) which are locally isometric on edges and such that \( f = g^s \circ h^s \).

Moreover, for any \( 0 \leq s \leq s' \leq L \) there is a canonical homotopy equivalence map \( r^{s',s} : (\Gamma^s, \mathcal{L}^s) \to (\Gamma^{s'}, \mathcal{L}^{s'}) \) which is locally isometric on edges and such that \( h^{s'} = r^{s',s} \circ h^s \) and such that for any \( 0 \leq s \leq s' \leq L \) we have \( r^{s',s} = r^{s',s'} \circ r^{s,s'} \).

Finally, we reparameterize the path \( \kappa^s \) from having domain \([0, L]\) to having domain \([0, 1]\) by setting \( \kappa_t := (\Gamma_t, \mathcal{L}_t) \) where \( \Gamma_t = \Gamma^{ttL}, \mathcal{L}_t = \mathcal{L}^{ttL} \) for \( t \in [0, 1] \). Thus \( \Delta = \Gamma^0 = \Gamma_0 = \Gamma_1 = \Gamma^L = \Gamma \), and \( \mathcal{L}_1 = \mathcal{L}^L = \mathcal{L} \). Here the equality \( \Gamma_0 = \Gamma_1 \) is understood to be up to a finite subdivision (since \( \Gamma_0 = \Delta \) is a subdivision of \( \Gamma_1 = \Gamma \)).

We also define \( h_t = h^{ttL}, g_t = g^{ttL} \) and \( r_{t',t} = r^{ttL}(t' \cdot tL) \) for \( 0 \leq t \leq t' \leq 1 \).

Note that \( h_1 = g_0 = f : \Gamma \to \Gamma, h_t = r_{0,t}, g_t = r_{1,t}, \) and that \( f = g_t \circ h_t \) for any \( t \in [0, 1] \). We refer to the family \( \kappa_t, t \in [0, 1] \), together with the maps \( h_t, g_t, r_{t',t} \) defined above, as the topological folding line corresponding to the topological representative \( f : \Gamma \to \Gamma \) of \( \varphi \) and a metric structure \( \mathcal{L} \) on \( \Gamma \). We write \( \{ \Gamma_t, h_t, g_t, r_{t',t} \} \) for \( 0 \leq t \leq 1 \) to denote the topological folding line.

This folding line also depends on the choice of a sequence of combinatorial Stallings folds (4.1) taking \( \Delta \) to \( \Gamma \), but this dependence will not affect the proofs of our main results. Also, the proofs of the results in this paper would go through if we always used the simplicial metric (where every edge has length 1) on \( \Gamma \) when defining the topological folding line. However, for intuition and visualization purposes it is sometimes useful to think about different edges having different length and to allow \( \mathcal{L} \) to be an arbitrary metric structure on \( \Gamma \).
Remark 4.4. Technically, in the standard Outer space terminology, the “folding path” $\kappa_t$ is a family of “marked metric graphs” which connects the “marked metric graph” $(m, \Gamma_0, L_0)$ (where $m : F_N \to \pi_1(\Gamma_0)$ is the marking given by the fact that $f$ is a topological representative of $\varphi$ and that $\Gamma_0$ is a subdivision of $\Gamma$) to the “marked metric graph” $(f_* \circ m, \Gamma, L)$. However, the markings on the graphs $\Gamma_t$ are not important for the specific applications used in this paper and therefore we did not record them when defining $\kappa_t$.

For the purposes of constructing the “folded mapping torus” of $f$ in §6 below, we will mainly forget about the metric structures $L_t$ on the graphs $\Gamma_t$ and only look at the underlying 1-complexes $\Gamma_t$ and the topological maps $h_t, g_t$ provided by the above construction. The metric structures $L_t$ on $\Gamma_t$ will occasionally be useful, and, in particular, they will make it simpler to describe the cell structure on the “folded mapping torus” of $f$.

Convention 4.5. If $f : \Gamma \to \Gamma$ is an expanding irreducible train-track representative of some $\varphi \in \text{Out}(F_N)$, we will always use the canonical linear structure $\Lambda$, the canonical metric structure $L$ and the canonical eigenmetric $d_L$ on $\Gamma$ (as in Definition 3.7), when constructing the topological folding line $\Gamma_t$. In particular, $L_0 = \lambda(f) L$.

Example 4.6. Let $f : \Gamma \to \Gamma$ be the graph-map from Example 2.2. Figure 3 illustrates the first two combinatorial Stallings folds in the folding sequence taking the $\Gamma$-graph $\Delta$ to $\Gamma$ for the graph map $f : \Gamma \to \Gamma$.

![Figure 3](image-url)

**Figure 3.** Two combinatorial Stallings folds used to construct a topological folding line.

5. **Clean train-tracks and full irreducibility**

In this section we obtain a strengthened and easier to use version of a criterion of full irreducibility for hyperbolic automorphisms from [Kap].

Recall that according to our definitions, for a train-track map $f : \Gamma \to \Gamma$ we allow the graph $\Gamma$ to have valence-2 vertices but no valence-1 vertices. However we do require that for any vertex $v$ of valence 2 and any $n \geq 1$ the map $f^n$ be locally injective on some small neighborhood of $v$ in $\Gamma$. This condition is automatically satisfied if we only require $f^n$ to be an immersion on all edges...
for all $n$ and also require the Whitehead graphs of all valence-$2$ vertices to be connected. Recall that a train-track map $f : \Gamma \to \Gamma$ is expanding if for every edge $e$ of $\Gamma$ the simplicial length $|f^n(e)|$ tends to $\infty$ as $n \to \infty$.

We need the notion of a “clean train-track”, introduced in [Kap]:

**Definition 5.1 (Clean train-track).** Let $f : \Gamma \to \Gamma$ be a train-track map.

We say that a train-track $f$ is clean if $f$ is expanding, if the Whitehead graph $Wh(f,v)$ is connected for each vertex $v \in V_\Gamma$, and if there exists $m > 0$ such that $A(f^m) > 0$. (This implies that $A(f^n) = A(f)^n$ is irreducible for all $n \geq 1$ and that $A(f^n) > 0$ for all $n \geq m$.) We say that $f$ is weakly clean if $f$ is expanding, if the Whitehead graph $Wh(f,v)$ is connected for each vertex $v \in V_\Gamma$ and if $A(f)$ is irreducible.

It is obvious that a clean train-track is weakly clean. Here we will show that the converse is also true and that any weakly clean train-track map is clean. It is proved in [Kap] that for a hyperbolic $\varphi \in \text{Out}(F_N)$ the element $\varphi$ is an iwip if and only if some (equivalently, any) train-track representative of $\varphi$ is clean. Thus establishing equivalence between clean and weakly clean conditions will imply that in this criterion one can replace being clean by being weakly clean.

**Remark 5.2.** Note that if $\Delta$ is a finite connected subgraph of a graph $\Gamma$ then the inclusion $\iota : \Delta \to \Gamma$ induces an injective homomorphism $\iota_* : H_1(\Delta; \mathcal{R}) \to H_1(\Gamma; \mathcal{R})$. For this reason if, in this situation, $f : \Gamma \to \Gamma$ is a graph-map which is homotopy equivalence, and $\Delta_1 = f(\Delta)$ then $b_1(\Delta) \leq b_1(\Delta_1)$.

**Proposition 5.3.** Let $f : \Gamma \to \Gamma$ be a weakly clean train-track. Then $f$ is clean.

**Proof.** Since $f$ is expanding and $\Gamma$ is finite, for every oriented edge $e$ of $\Gamma$ there exists $n > 0$ and an oriented edge $e'$ such that the path $f^n(e)$ contains at least three occurrences of the edge $e'$ (with positive orientation). From irreducibility of $A(f)$ it follows that there exists $j > 0$ such that $f^j(e')$ contains either $e$ or $e^{-1}$. Then $f^{n+j}(e)$ contains at least 3 occurrences of $e$ or at least 3 occurrences of $e^{-1}$. Hence $f^{2(n+j)}(e)$ contains at least 3 occurrences of $e$. Put $k(e) := 2(n+j)$ and then put $m$ to be the product of $k(e)$ taken over all oriented edges $e$ of $\Gamma$. Then for any oriented edge $e$ the path $f^m(e)$ contains at least three positive occurrences of $e$ and the same is true for $f^{mq}(e)$ for any integer $q \geq 1$.

Now let $e$ be an oriented edge of $\Gamma$ and for $n \geq 1$ put $\Delta_0 = \{e\}$ and let $\Delta_n$ be the subgraph of $\Gamma$ given by the union of all the edges in the path $f^{mn}(e)$. Then, by construction, $\Delta_n \subseteq \Delta_{n+1}$ for all $n \geq 0$ and we put $\Delta(e) := \bigcup_{n \geq 0} \Delta_n$. Since $\Gamma$ is finite, and the graphs $\Delta_n$ are connected, $\Delta(e)$ is a finite connected subgraph of $\Gamma$ containing $e$ and such that $\Delta(e) = \Delta(e^{-1})$. Also, by construction, we have $f^m(\Delta(e)) = \Delta(e)$.

**Claim 1.** For any edge $e$ of $\Gamma$ and any $j > 0$ the graphs $\Delta(e)$ and $f^j(\Delta(e))$ are homotopy equivalent. Since $f : \Gamma \to \Gamma$ is a homotopy equivalence, Remark 5.2 implies that $b_1(\Delta(e)) \leq b_1(\Delta')$ where $\Delta' = f^j(\Gamma(e))$. We can find $k \geq 1$ such that $j \leq mk$. Then $f^{mk-j}(\Delta') = f^{mk}(\Delta(e)) = \Delta(e)$ and hence, again by Remark 5.2, we have $b_1(\Delta') \leq b_1(\Delta(e))$. Hence $b_1(\Delta') = b_1(\Delta(e))$, as required, and Claim 1 is established.

**Claim 2.** For any two edges $e, e'$ of $\Gamma$ we have $b_1(\Delta(e)) = b_1(\Delta(e'))$ (and hence the graphs $\Delta(e)$ and $\Delta(e')$ are homotopy equivalent).

Indeed, let $e, e'$ be arbitrary oriented edges. By irreducibility of $A(f)$ there exists $j > 0$ such that $f^j(e)$ contains $e'$ or $(e')^{-1}$. Then for any $k \geq 0$ $f^{mk}(f^j(\Delta(e))) = f^{j+mk}(\Delta(e)) = f^j(f^{mk}(\Delta(e))) = f^j(\Delta(e))$. Hence $f^{mk}(e')$ is contained in $f^j(\Delta(e))$ for every $k \geq 1$ and therefore, by definition, $\Delta(e') \subseteq f^j(\Delta(e))$. Hence $b_1(\Delta(e')) \leq b_1(f^j(\Delta(e))) = b_1(\Delta(e))$. A symmetric argument shows that $b_1(\Delta(e)) \leq b_1(\Delta(e'))$ and hence $b_1(\Delta(e)) = b_1(\Delta(e'))$. Thus Claim 2 is verified.

**Claim 3.** For any edge $e$ of $\Gamma$ we have $\Delta(e) = \Gamma$. 


Indeed, suppose not, and let $e$ be such that $\Delta(e) \neq \Gamma$. Then there exists a vertex $v$ of $\Delta(e)$ such that $v$ is incident to an edge of $\Delta(e)$ and to an edge of $\Gamma - \Delta(e)$.

Since the Whitehead graph $\text{Wh}_f(v) = (\mathcal{F}, \mathcal{V})$ is connected, there exist oriented edges $e_1$ and $e_2$ with origin $v$ such that $e_1 \subseteq \Delta(e)$, $e_2 \not\subseteq \Delta(e)$ and such that the turn $e_1, e_2$ is taken by $f$. Hence there exists an edge $e_3$ and $i > 0$ such that $e_3^{-1} e_2$ is a subpath of $f(i)$. Since $f: \Gamma \to \Gamma$ is surjective, there exist $k \geq 1$ and an edge $e_4$ such that $km > i$ and such that $f^{km-i}(e_4)$ contains $e_3$. Hence $f^m(e_4)$ contains $e_3^{-1} e_2$ as a subpath. Therefore, by definition, we have $e_1 \subseteq \Delta(e_4)$ and $e_2 \subseteq \Delta(e_4)$ and hence $\Delta(e_1) \subseteq \Delta(e_4)$ and $\Delta(e_2) \subseteq \Delta(e_4)$.

Also, since $f^m(\Delta(e)) = \Delta(e)$ and since $e_1$ is an edge of $\Delta(e)$, we have $\Delta(e_1) \subseteq \Delta(e)$. In particular, $e_2$ is not contained in $\Delta(e_1)$.

Let $v'$ be the terminal vertex of $e_2$. Then $v' \not\in \Delta(e_1)$ since otherwise $\Xi := e_2 \cup \Delta(e_1)$ has the first Betti number bigger than that of $\Delta(e_1)$ which is impossible since $\Xi \subseteq \Delta(e_2)$ and $b_1(\Delta(e_1)) = b_1(\Delta(e_4))$ by Claim 2.

By the choice of $m$ the path $f^m(e_2)$ contains at least 3 positive occurrences of $e_2$. Hence there exists a fixed point $x$ of $f^m$ in the interior of $e_2$ coming from a positive occurrence of $e_2$ in $f^m(e_2)$ which is neither initial nor terminal edge of $f^m(e_2)$. Thus $f^m$ preserves the orientation in a small neighborhood of $x$. Let $\beta = \min \{x, v'\}$ be the segment of $e_2$ from $x$ to $v'$. Then $f^m([x, v']) = [x, v'] \cup \beta$ where $\beta$ is a tight combinatorial edge-path of positive simplicial length with initial vertex $v'$. Thus for all $n \geq 0$ the path $f^{mn}([x, v']) = [x, v'] \cup \beta_n$ is a proper initial segment of the path $f^{m(n+1)}([x, v']) = [x, v'] \cup \beta_{n+1}$, where $\beta_n$ is a tight combinatorial edge-path starting at $v'$ with $|\beta_n| \to \infty$ as $n \to \infty$. Let $\rho$ be the path in $\Gamma$ obtained by taking the “union” of all $f^{mn}([x, v'])$, that is, $\rho$ is the path starting at $x$ such that for all $n \geq 0$ $f^{mn}(\{x, v'\})$ is an initial segment of $\rho$. This $\rho$ is sometimes called a “combinatorial eigenray” of $f$. By construction we have $\rho \subseteq \Delta(e)$.

The path $\rho$ has the form $\rho = [x, v'] \rho'$ where $\rho'$ is a semi-infinite edge-path in $\Gamma$ starting at $v'$.

Then either $\rho'$ has a nonempty intersection with $\Delta(e_1)$ (in which case we look at the first time when $\rho'$ hits the graph $\Delta(e_1)$), or, if $\rho'$ and $\Delta(e_1)$ are disjoint, then there is an oriented edge that occurs in $\rho'$ at least twice and hence $\rho'$ contains a nontrivial immersed loop. In both cases we see that $\Xi_1 = \Delta(e_1) \cup e_2 \cup \rho'$ has $b_1(\Xi_1) > b_1(\Delta(e_1))$. However, $\Xi_1 \subseteq \Delta(e_4)$ and hence $b_1(\Delta(e_4)) > b_1(\Delta(e_1))$, which contradicts Claim 2.

Thus Claim 3 is established and we know that $\Delta(e) = \Gamma$ for every edge $e$ of $\Gamma$. By definition of $\Delta(e)$ it follows that for every edge $e$ of $\Gamma$ there exists $n_e \geq 1$ such that $f^{n_e}(e)$ passes through every topological edge of $\Gamma$. Since $f: \Gamma \to \Gamma$ is surjective, it follows that for every $i \geq n_e m$ the path $f^i(e)$ also passes through every topological edge of $\Gamma$. Now put $M$ to be the maximum of $n_e m$ taken over all edges $e$ of $\Gamma$. Then for any two oriented edges $e, e'$ of $\Gamma$ the path $f^M(e)$ contains an occurrence of $e'$ or $(e')^{-1}$. This means that $A(f^M) > 0$, as required.

Note that if $\varphi \in \text{Out}(F_N)$ is hyperbolic (i.e. atoroidal) and $f: \Gamma \to \Gamma$ is a train-track representative of $\varphi$ with irreducible $A(f)$ then $f$ is expanding (since otherwise $A(f)$ is a permutation matrix and $\varphi$ has finite order, which contradicts the hyperbolicity assumption about $\varphi$). Combining Proposition 5.3 with Proposition 4.4 of [Kap] we immediately obtain:

**Corollary 5.4.** Let $N \geq 3$ and let $\varphi \in \text{Out}(F_N)$ be a hyperbolic element. Then the following conditions are equivalent:

1. The automorphism $\varphi$ is fully irreducible.
2. If $f: \Gamma \to \Gamma$ is a train-track representative of $\varphi$ then $f$ is clean.
3. There exists a clean train-track representative of $\varphi$.
4. There exists a weakly clean train-track representative of $\varphi$.

**Example 5.5.** We have already seen that $f: \Gamma \to \Gamma$ in Example 2.2 is an expanding irreducible train-track map representing an automorphism $\varphi \in \text{Out}(F_3)$. We also already know that $\varphi$ is
hyperbolic – this fact was verified (see Example 2.15) by checking that the group \( G_\varphi \) is word-

hyperbolic. We have already verified in Example 2.7 that the Whitehead graphs of both vertices

of \( \Gamma \) with respect to \( f \) are connected. Thus \( f \) is a weakly clean train track. Therefore, by

Corollary 5.4, \( \varphi \) is fully irreducible.

Another useful corollary of Proposition 5.3 is that for hyperbolic elements of \( \text{Out}(F_N) \) the

notions of being irreducible and fully irreducible coincide:

**Corollary 5.6.** Let \( N \geq 3 \) and let \( \varphi \in \text{Out}(F_N) \) be a hyperbolic element.

Then \( \varphi \) is irreducible if and only if \( \varphi \) is fully irreducible.

**Proof.** Obviously, if \( \varphi \) is fully irreducible then \( \varphi \) is irreducible. Thus let \( \varphi \in \text{Out}(F_N) \) be hyperbolic

and irreducible. Assume that \( \varphi \) is not fully irreducible. Since \( \varphi \) is irreducible, by a result of

Bestvina–Handel [BH], there exists a train-track representative \( f: \Gamma \rightarrow \Gamma \) of \( \varphi \) with an irreducible

transition matrix \( A(f) \). Since \( \varphi \) is hyperbolic and thus has infinite order in \( \text{Out}(F_N) \), we know that

\( A(f) \) is not a permutation matrix. Hence \( \lambda(f) > 1 \), so that \( f \) is expanding. By assumption

\( f \) is not fully irreducible and therefore, by Corollary 5.4 above, the train-track \( f \) is not weakly

clean. This means that for some vertex \( v \) of \( \Gamma \) the Whitehead graph \( \text{Wh}(f,v) \) is not connected.

Proposition 4.1 of [Kap] (which first appears, in implicit form, in the proof of Proposition 4.5 in

[BH]) now implies that \( \varphi \) is reducible, contrary to our assumption that \( \varphi \) is irreducible. Thus \( \varphi \)

is fully irreducible, as required. \( \square \)

Note that the conclusion of Corollary 5.6 fails without the assumption that \( \varphi \) is hyperbolic, as

already observed by Bestvina and Handel in [BH]. For example, let \( S \) be a compact connected

hyperbolic surface with \( m \geq 3 \) boundary components, let \( F_N = \pi_1(S) \) and let \( \varphi \in \text{Out}(F_N) \) be

induced by a pseudo-Anosov homeomorphism \( g \) of \( S \). The boundary components of \( S \) represent

primitive elements of \( F_N \) and therefore such \( \varphi \) is not fully irreducible. However, if \( g \) transitivity

permutes the boundary components of \( S \), then \( \varphi \) is irreducible.

**6. The folded mapping torus and semiflows.**

**Convention 6.1.** Let \( \varphi \in \text{Out}(F_N) \) and set \( G = G_\varphi \). Fix a regular, tame topological representa-

tive \( f: \Gamma \rightarrow \Gamma \) for \( \varphi \), a metric structure \( \mathcal{L} \) and a topological folding line \( \{ \Gamma_1, h_t, g_t, r_{t,t'}, i \}_{0 \leq t \leq t' \leq 1} \).

In this section, given the above data, we describe a cell complex we call the **folded mapping torus** of \( f \), denoted \( X_f \), which is a particular \( K(G,1) \) built from the data of the folding line. We also construct a semiflow on \( X_f \) that encodes the folding line, and prove a few basic properties of \( X_f \). We end by describing the cell structure in a little more detail and defining the \( E_0 \)-class \( \epsilon \in H_1(X_f;\mathbb{Z}) \) to be used in Theorem B.

**Remark 6.2.** The construction of another \( K(G,1) \) 2–complex from \( \varphi \in \text{Out}(F_N) \) —Gautero’s

“dynamical 2–complex”—and a semiflow is carried out by Gautero in [Gau1, Proposition 3.9, Proposition 4.3] using a sequence of Whitehead moves in place of the folding path; see also the modification in [Gau4]. Similarly, Wang’s construction [Wan] of the decomposed mapping torus is similar to our construction via “building blocks” described below.

**6.1. The folded mapping torus.** Recall that the combinatorial Stallings folds

\[ \Delta = \Delta_0, \Delta_1, \ldots, \Delta_m = \Gamma \]

occur along the folding line at certain times which we denote

\[ 0 = t_0 < t_1 < \ldots < t_m = 1. \]

That is, \( t_i \) is the unique time when \( \Gamma_{t_i} = \Delta_i \). Write \( e_i, e'_i \in E\Delta_i = ET_{t_i} \) for the edges folded together by

\[ r_{t_{i+1}, t_i}: \Gamma_{t_i} \rightarrow \Gamma_{t_{i+1}}. \]
Finally, set $\ell_i = \mathcal{L}_i(e_i) = \mathcal{L}_i(e_i') = \mathcal{L}(g_i(e_i))$. With the notation as in §4 we see that

$$\frac{t_{i+1} - t_i}{\ell_i} = \frac{s_{i+1} - s_i}{\ell_i} = \frac{1}{L} = \frac{1}{L}.$$ 

is constant $1/L$. It follows that $r_{t,t_i}$ identifies the initial segments of $e_i$ and $e_i'$ of length $(t - t_i)L$, and is injective on the remainder of each.

We build our $K(G,1)$ out of $m$ “building blocks”, one for each $\Gamma_{t_i}$, for $0 \leq i \leq m - 1$, constructed as follows. Start with the product

$$\Gamma_{t_i} \times [t_i, t_{i+1}]$$

equipped with the product cell structure. The metric structure $\mathcal{L}_i$ and Euclidean metric on $[t_i, t_{i+1}]$ allow us to view $\Gamma_{t_i} \times [t_i, t_{i+1}]$ as a geodesic metric space for which each cell is the image of a Euclidean rectangle by a locally isometric immersion (injective on the interiors). These are characteristic maps for the 2–cells. For the 2–cells determined by $e_i \times (t_i, t_{i+1})$ and $e_i' \times (t_i, t_{i+1})$ we let $R_i = [0, \ell_i] \times [t_i, t_{i+1}]$ and write these as

$$\rho_i : R_i \rightarrow \bar{e}_i \times [t_i, t_{i+1}],$$
$$\rho_i' : R_i \rightarrow \bar{e}_i' \times [t_i, t_{i+1}].$$

We assume that these are parameterized so that

$$\rho_i(0, t_i) = o(e_i), \rho_i'(0, t_i) = o(e_i'), \rho_i(\ell_i, t_i) = t(e_i), \rho_i'(\ell_i, t_i) = t(e_i').$$

A technical note: One of the edges $e_i$ or $e_i'$ may actually be a loop, so that one of $\rho_i$ or $\rho_i'$ may fail to be injective. However, $e_i$ and $e_i'$ cannot both be loops since folding together two loop edges changes the homotopy type of a graph. We assume (by interchanging $e_i$ and $e_i'$ if necessary) that $e_i$ is not a loop, and hence $\rho_i$ is actually injective.

**Definition 6.3** (Building blocks). The $i^{th}$ building block $X_i'$ is the quotient

$$\Pi_i : \Gamma_{t_i} \times [t_i, t_{i+1}] \rightarrow X_i' = \Gamma_{t_i} \times [t_i, t_{i+1}]/\sim$$

where $\sim$ is the equivalence relation generated by

$$\rho_i(s, t) \sim \rho_i'(s, t)$$

for all $0 \leq s \leq \ell_i$ and $t_i + s/L \leq t \leq t_{i+1}$.

Each building block $X_i'$ admits a natural metric and cell structure. To describe these structures, subdivide the rectangle $R_i$ into two Euclidean triangles

$$B_i = \{(s,t) \mid 0 \leq s \leq \ell_i, t_i + s/L \leq t \leq t_{i+1}\},$$
$$B_i' = \{(s,t) \mid 0 \leq s \leq \ell_i, t_i \leq t \leq t_i + s/L\}.$$

This procedure determines, via $\rho_i$ and $\rho_i'$, a subdivision of $\Gamma_{t_i} \times [t_i, t_{i+1}]$ dividing each of the rectangular 2–cells $\rho_i(R_i)$ and $\rho_i'(R_i)$ into two Euclidean triangles. The quotient $X_i'$ is obtained by identifying $\rho_i(B_i)$ to $\rho_i'(B_i)$ by the isometry $\rho_i \circ \rho_i'^{-1}$. The subdivided cell structure on $\Gamma_{t_i} \times [t_i, t_{i+1}]$ descends to a cell structure on $X_i'$. We give $X_i'$ the unique path metric making $\Pi_i$ into a local isometry when restricted to each cell. As such $\Pi_i$ is a path isometry. See Figure 4 for the local picture of $X_i'$ near the triangles.

Since $\sim$ only identifies points with the same second coordinate, the projection $\Gamma_{t_i} \times [t_i, t_{i+1}] \rightarrow [t_i, t_{i+1}]$ descends to a continuous surjection $\pi_i : X_i' \rightarrow [t_i, t_{i+1}]$. We write $X_i'(t) = \pi_i^{-1}(t) = \Pi_i(\Gamma_{t_i} \times \{ t \})$ for every $t_i \leq t \leq t_{i+1}$. 

Lemma 6.4. For every $t \in [t_i, t_{i+1}]$ there is an isometry
\[ \xi_i^t : X_i'(t) \to \Gamma_t \]
so that for all $x \in \Gamma_t$,
\[ \xi_i^t \circ \Pi_i(x, t) = r_{t, t_i}(x). \]

Proof. The first observation is that the restriction of $\Pi_i$ defines a homeomorphism (in fact, a path isometry)
\[ \Pi_i : \Gamma_t \times [t_i, t_{i+1}] \setminus (\rho_i(R_i) \cup \rho'_i(R_i)) \to X_i' \setminus \Pi(\rho_i(R_i) \cup \rho'_i(R_i)). \]
This fact holds because all the identifications from $\sim$ occur only on $(\rho_i(R_i) \cup \rho'_i(R_i))$. On the other hand, we note that the restriction of $\Pi_i$ to $\rho_i(R_i)$ is a bijection, while the restriction of $\Pi_i$ to $\rho'_i(R_i)$ is either a bijection or identifies exactly two distinct points. The latter case occurs when $e'_i$ is a loop (recall that $e_i$ is not a loop), in which case $\Pi_i$ identifies $\rho_i(0, t_{i+1})$ and $\rho_i(\ell_i, t_{i+1})$. See Figure 5.

Figure 5. Two possibilities for $\Pi_i$ near $\rho_i(R_i) \cup \rho'_i(R_i)$ depending on whether $e'_i$ is a loop (right) or not a loop (left).

From these facts and the definition of $\sim$, it follows that $\rho_i(s, t) \sim \rho'_i(s', t')$ if and only if
1. $(s, t) = (s', t') \in B_i$, or
2. $e'_i$ is a loop and $(s, t) = (0, t)$, $(s', t') = (\ell_i, t)$, and $t_i \leq t = t' \leq t_{i+1}$, or
3. $e'_i$ is a loop and $(s, t) = (\ell_i, t_{i+1})$ and $(s', t') = (0, t_{i+1}).$
Again, see Figure 5.

Now let \( \zeta_t : \Gamma_t \to X'_t(t) \) be the map given by \( \zeta_t(x) = \Pi_t(x,t) \). Since \( \Pi_t \) is a path isometry, so is \( \zeta_t \). From the above, we see that the restriction of \( \zeta_t \) to \( \Gamma \setminus (e_i \cup e'_i) \) is a path isometry (in particular, a homeomorphism) onto its image \( X_1(t) \setminus \zeta_t(e_i \cup e'_i) \).

Let \( j, j' : [0, \ell] \to \Gamma_t \) be characteristic maps for \( e_i \) and \( e'_i \), respectively, from the metric atlas \( \mathcal{L}_i \). Observe that \( \rho_i(s, t) = (j(s), t) \) and \( \rho'_i(s, t) = (j'(s), t) \) for all \( 0 \leq s \leq \ell_i \) and \( t_i \leq t \leq t_i \). Suppose that \( e'_i \) is not a loop. Then from the description of \( \zeta_t \) above, we see that two distinct points of \( e_i \cup e'_i \) are identified if and only if they have the form \( j(s), j'(s) \) and \( (s, t), (s, t) \) in \( \mathcal{L}_i \), or equivalently \( t_i + s/L \leq t < t_{i+1} \). Thus, \( \zeta_t \) is a path isometry on each of \( e_i \) and \( e'_i \), respectively, and (isometrically) identifies the initial segments \( j([s_i, s]) \) and \( j'([s_i, s]) \) of length \( s = s_i = L(t - t_i) \), and is injective on the remainder of \( e_i \cup e'_i \). This is precisely the property defining \( r_{t, t_i : \Gamma_t \to \Gamma_t} \) (see above), and hence we have an isometry \( \xi_t : X_i(t) \to \Gamma_t \) so that \( r_{t, t_i} = \xi_t \circ \zeta_t \). When \( e'_i \) is a loop, the same argument is valid, as long as \( t_i \leq t < t_{i+1} \). When \( t = t_{i+1} \), we are identifying the entire edge \( e_i \) to the entire edge \( e_{i+1} \) by a path isometry and again we see that \( r_{t_{i+1}, t_i} = \xi_t \circ \zeta_t \), completing the proof. \( \square \)

From this lemma it follows that for every \( 0 \leq i \leq m - 1 \), the map \( \xi^{i+1,i} : X'_i(t_{i+1}) \to X'_i(t_{i+1}) \) given by

\[
\xi^{i+1,i} = (\xi^{i+1}_{i+1})^{-1} \circ \xi^{i}_{i+1}
\]

is an isometry. Let \( X' \) denote the quotient obtained by “stacking the building blocks up”

\[
X' = \left( \bigcup_{i=0}^{m-1} X'_i \right) / \sim
\]

where \( x \sim \xi^{i+1,i}(x) \) for all \( i = 0, \ldots, m - 1 \) and for all \( x \in X_i(t_{i+1}) \). The cell structure on the union of the \( X'_i \) descends to a cell structure on \( X' \) and since the gluings are by the isometries \( \xi^{i+1,i} \), there is a unique path metric on \( X' \) so that the quotient map is a path isometry on every cell.

The projections \( \pi_i : X'_i \to [t_i, t_{i+1}] \) descend to a projection \( \pi : X' \to [0, 1] \). Denote the fibers of \( \pi \) by \( X'(t) = \pi^{-1}(t) \). The isometries \( \xi_t \) of Lemma 6.4 descend to isometries \( \xi_t : X'(t) \to \Gamma_t \).

For all \( 0 \leq t \leq t' \leq 1 \) we then define \( r'_{t,t'} : X'(t) \to X'(t') \) by

\[
r'_{t,t'} = \xi_{t'}^{-1} \circ r_{t',t} \circ \xi_t.
\]

In particular, observe that

\[
r'_{t,0} = \xi_{t}^{-1} \circ h_t \circ \xi_0, \quad r'_{1,t} = \xi_{1}^{-1} \circ g_t \circ \xi_t
\]

so that for all intents and purposes, the space \( X' \) and the maps \( \{ r'_{t,t'} \} \) encode all information about the folding line \( \{ \Gamma_t, h_t, g_t, r_{t,t'} \} \). Using the identification \( \Gamma_0 = \Gamma = \Gamma_1 \), we also have

\[
r'_{1,0} = \xi_{1}^{-1} \circ f \circ \xi_0.
\]

Next we define a map

\[
\Pi' : \Gamma \times [0, 1] \to X'
\]

by

\[
\Pi'(x, t) = r'_{t,0} \circ \xi_0^{-1}(x).
\]
again using the identification $\Gamma_0 = \Gamma$. This maps $\Gamma \times \{t\}$ to $X'(t)$ and is essentially the folding map $h_t$:
\[
\Pi'(x, t) = \xi_t^{-1} \circ h_t(x).
\]
To see that this map is continuous, note that on $\Gamma \times [t_i, t_{i+1}]$, the restriction of $\Pi'$ is the composition of the continuous map $(x, t) \mapsto \Pi_t(r_{t_i,0}(x), t)$ with the quotient map to $X'$.

**Definition 6.5** (Folded mapping torus). The folded mapping torus $X = X_f$ is the quotient
\[
X' \to X_f
\]
obtained by gluing $X'(1)$ to $X'(0)$ by the homeomorphism $\xi_0^{-1} \circ \xi_1$. Here we are identifying $\Gamma_0 = \Gamma = \Gamma_1$ in order to make sense of the composition $\xi_0^{-1} \circ \xi_1$.

Next we relate $X_f$ to the mapping torus of $f$, which is the space $Z_f = \Gamma \times [0, 1]/\sim$ where $(x, 1) \sim (f(x), 0)$.

**Proposition 6.6.** The map $\Pi'$ descends to a continuous map
\[
\Pi : Z_f \to X_f.
\]

**Proof.** Since $\Pi'$ is continuous and all spaces are given the quotient topology, continuity will come for free once we know that $\Pi'$ descends to a map. To establish this conclusion, let $x \in \Gamma$. We need to prove that $\Pi(x, 1)$ and $\Pi(f(x), 0)$ are identified in $X_f$, that is, that they differ by $\xi_0^{-1} \circ \xi_1$. Verifying this fact is a matter of unravelling the definitions.
\[
\Pi'(f(x), 0) = r'_{0,0} \circ \xi_0^{-1}(f(x)) = \xi_0^{-1}(f(x)) = \xi_0^{-1} \circ \xi_1 \circ \xi_0^{-1} \circ f \circ \xi_0 \circ \xi_0^{-1}(x) = \xi_0^{-1} \circ \xi_1 \circ r'_{1,0} \circ \xi_0^{-1}(x) = \xi_0^{-1} \circ \xi_1(\Pi'(x, 1)).
\]

In the next section we prove that in fact $\Pi$ is a homotopy equivalence. It is not too difficult to prove this result directly, but a simple proof presents itself as a consequence of the construction of the semiflow below.

Before proceeding, we note that the gluing map $\xi_0^{-1} \circ \xi_1$ is not an isometry, so $X$ does not come equipped with a canonical metric (even though $X'$ does). However, the map is a homeomorphism, and we can produce a cell structure on $X$ from that on $X'$. This cell structure is obtained by subdividing $X'(1)$ (which is a subcomplex of $X'$) so that the gluing map $\xi_0^{-1} \circ \xi_1$. The map $\xi_0^{-1} \circ \xi_1$ is essentially the identification $\Gamma_1 = \Gamma = \Gamma_0$, and so this subdivision agrees with the one used to define the folding path in the first place. In §6.4 we will describe another cell structure on $X$ to better suit our needs.

The projection $\pi : X'(t) \to [0, 1]$ descends to a map
\[
\eta_0 : X \to S^1 = \mathbb{R}/\mathbb{Z}.
\]
For every $t \in \mathbb{R}/\mathbb{Z}$, the fiber $\eta_0^{-1}(t)$ is homeomorphic to $X'(t) \cong \Gamma_t$ (where we take a representative $t \in [0, 1]$ for the point of $S^1$). To simplify the notation, we use this homeomorphism to identify $\eta_0^{-1}(t) = \Gamma_t$ for the remainder of the paper. Consequently, the restriction of $\Pi$ to $\Gamma \times \{0\}$ is the identity on $\Gamma = \Gamma_0$. For $0 \leq t \leq t' < 1$, $r'_{t,t'} : X'(t) \to X'(t')$ descends to the folding map $r'_{t,t} : \Gamma_t \to \Gamma_{t'}$ with this identification. Furthermore, for every $0 \leq t < 1$, the restriction of $\Pi$ to the slices $\Gamma \times \{t\} \to \Gamma_t$ is the folding map
\[
\Pi(x, t) = h_t(x).
\]
Example 6.7. Returning to our running example \( f : \Gamma \to \Gamma \), Figure 6 shows the folded mapping torus \( X_f \) in this case. We have represented it as four large rectangles with a subdivided cell structure, and with identifications as indicated. See the caption of the figure for detailed description of the identifications.

![Figure 6. The folded mapping torus \( X_f \) for the example \( f : \Gamma \to \Gamma \). The identifications on the sides of the large rectangles are indicated by thick and medium-thick lines, and these are by isometries. This identification gives the product \( \Gamma \times [0,1] \). The tops of the rectangles are identified to the bottoms as indicated by the labeled arrows, and these are by dilations by \( \lambda \approx 2.4142 \). The result of these identifications (together with the side identifications) gives the mapping torus \( Z_f \). Finally, the 2–cells are identified as indicated by the shading and the patterns of 2–cells (white cells are not identified to any others) to produce \( X_f \). We have also indicated which 1–cells in the interiors of the rectangles are identified with those coming from the boundaries of the rectangles via thick and medium-thick lines. We note that performing the side identifications and the 2–cell identifications only (which can be done by isometries) gives the complex \( X' \).](image)

6.2. The semiflow and homotopy type of \( X_f \). The local flow \( \hat{\psi}' \) on \( \Gamma \times [0,1] \) given by \( \hat{\psi}'(x,t) = (x,t+s) \) extends to a semiflow (i.e. an action of the semigroup of nonnegative reals \( \mathbb{R}_+ \)) on \( Z_f \). To describe this semiflow, we require that when a point \((x,t)\) reaches \((x,1)\) in \( \Gamma \times \{1\} \) it is sent to the identified point \((f(x),0)\) in \( \Gamma \times \{0\} \). We denote this semiflow by \( \hat{\psi}_s \). To describe \( \hat{\psi}_s \) explicitly, we use the bijection \( F : \Gamma \times [0,1] \to Z_f \), and then \( \hat{\psi} \) is given by

\[
\hat{\psi}_s(F(x,t)) = F(f^{\lfloor s+t \rfloor}(x), s + t - \lfloor s + t \rfloor).
\]

Proposition 6.8. There is a semiflow \( \psi \) on \( X_f \) such that for all \( s \in \mathbb{R}_+ \), we have

\[
\Pi \circ \hat{\psi}_s = \psi_s \circ \Pi.
\]

Moreover, for \( 0 \leq t \leq t' < 1 \) we have

\[
\psi_{t'-t}|_{r_t} = r_{t'.t} : \Gamma_t \to \Gamma_{t'}.
\]

Proof. For every \( x \in \Gamma \), \( 0 \leq t \leq 1 \), and \( 0 \leq s \leq 1 - t \), we define

\[
\psi_s(x,t) = r'_{t+s,t} \circ \Pi'(x,t).
\]
Finally, applying the second statement of Proposition 6.8, we see that \( \psi \) proves that \( \Pi \) for all \( x \in \Gamma \), \( 0 \leq t \leq 1 \) and \( 0 \leq s, s' \leq 1 \) with \( s + s' \leq 1 - t \) we have
\[
\psi_s' \circ \psi_s'(\Pi'(x,t)) = \psi_s'(r_{t+s,t}^l(\Pi'(x,t))) = r_{t+s+s',t+s,0}^l(\Pi'(x,t))
\]
\[
\psi_s' = r_{t+s,s',t}(\Pi'(x,t)) = \psi_{s+s'}'(\Pi'(x,t)).
\]

As in the case of \( Z_f \), we obtain a semiflow \( \psi \) on \( X_f \) from \( \psi' \) on \( X' \) by requiring that when a point reaches \( X'(1) \) it is sent to \( X'(0) \) by \( \xi_0^{-1} \). So to see that \( \Pi \circ \hat{\psi} = \psi \circ \Pi \), it suffices to prove that \( \Pi' \) semiconjugates the local flow on \( \Gamma \times \{0,1\} \) to the local semiflow on \( X' \). That is, we need to prove that for all \( x \in \Gamma \), \( 0 \leq t \leq 1 \) and \( 0 \leq s \leq 1 - t \), we have
\[
\Pi'(x,t + s) = \psi_s'(\Pi'(x,t)).
\]
Verifying this conclusion is a matter of definitions:
\[
\Pi'(x,t + s) = r_{t+s,0}^l \circ \xi_0^{-1}(x) = r_{t+s,t}^l \circ r_{t,0}^l \circ \xi_0^{-1}(x) = \psi_s'(\Pi'(x,t)).
\]
This proves the first part of the proposition.

To prove the second statement, we observe that just from the definition of the local semiflow \( \psi' \) on \( X' \), we have
\[
\psi_{t' - t}|_{X'(t)} = r_{t',t}: X'(t) \to X'(t')
\]
for all \( 0 \leq t \leq t' < 1 \). Projecting to \( X_f \), this becomes
\[
\psi_{t' - t}|_{\Gamma} = r_{t',t}: \Gamma \to \Gamma_v
\]
as required. \( \square \)

**Definition 6.9.** We call \( \psi \) from Proposition 6.8 the suspension semiflow on \( X_f \).

If \( s \in \mathbb{R} \), we write \( \Gamma_s \) to denote \( \Gamma_{s-[s]} \). It is most useful to describe the semiflow in terms of its effect on the fibers \( \Gamma_t \). For small \( s \), one simply folds \( \Gamma_t \). If \( s \) is large, then one folds until we reach \( \Gamma_1 = \Gamma_0 \), then we apply a power of \( f \), and then finish off by folding. A precise statement is the following straight forward application of the proposition.

**Corollary 6.10.** For every \( 0 \leq t < 1 \) and \( s \in \mathbb{R}_+ \), we have
\[
\psi_s|_{\Gamma_t} = r_{b,0} \circ f^k \circ r_{t+a,t}: \Gamma_t \to \Gamma_{t+s}
\]
where \( a = \min\{[t] - t, t + s\} \), \( k = \max\{0, [t + s - a]\} \), \( b = s - (k + a) \). In particular, for all \( s \in \mathbb{R}_+ \) we have
\[
\psi_s|_{\Gamma_0} = r_{s-[s],0} \circ f^{[s]}: \Gamma_0 \to \Gamma_s
\]

**Proof.** One easily checks that \( s = a + b + k \), \( k \in \mathbb{Z} \) and \( 0 \leq a, b < 1 \), and we write
\[
\psi_s = \psi_b \circ \psi_k \circ \psi_a.
\]
To prove the corollary, we need verify that each of the maps on the right is as stated in the corollary. If \( s = a \), then \( b = k = 0 \) and the statement is exactly the second part of Proposition 6.8. Otherwise, \( t + a = 1 \) (or \( t = a = 0 \)), so that \( r_{t+a,t}(\Gamma_t) = \Gamma_t \). Observe that the restriction of \( \Pi \) to \( \Gamma \times \{0\} \) is the identity \( \Gamma = \Gamma_0 \), and so Proposition 6.8 implies
\[
\psi_k|_{\Gamma_0} = \Pi|_{\Gamma \times \{0\}} \circ f^k \circ \Pi|_{\Gamma \times \{0\}}^{-1} = f^k.
\]
Finally, applying the second statement of Proposition 6.8, we see that \( \psi_b|_{\Gamma_0} = r_{b,0} \).
\( \square \)

As a simple application of the semiflow \( \psi \) we have the following.

**Proposition 6.11.** The map \( \Pi: Z_f \to X_f \) is a homotopy equivalence.
Proof. The map $\Pi$ restricted to $\Gamma \times \{t\}$ is the folding map $h_t$. Construct a map $F: X_f \to Z_f$ by applying $g_t$ to $\Gamma_t$ for every $t$. The composition $F \circ \Pi: Z_f \to Z_f$ is the time 1 map $\psi_1$, while the composition in the other order $\Pi \circ F: X_f \to X_f$ is $\psi_1$. Since $\psi_1$ and $\psi_1$ are homotopic to $\psi_0 = \text{id}_{Z_f}$ and $\psi_0 = \text{id}_{X_f}$, respectively, (the semiflow defines the homotopy), we see that $\Pi$ is a homotopy equivalence. \qed

Recall that $G = G_\varphi = \langle F_N, t \mid t^{-1}wt = \Phi(w), w \in F_N \rangle$, where $\Phi \in \text{Aut}(F_N)$ is a representative of the outer automorphism class $\phi$. The projection $\Gamma \times [0,1] \to [0,1]$ descends to a surjection $\eta'_0: Z_f \to S^1 = \mathbb{R}/\mathbb{Z}$. An application of van Kampen’s Theorem implies that the isomorphism $F_N \to \pi_1(\Gamma)$ from the marking extends to an isomorphism $\Psi: G \to \pi_1(Z_f)$ for which $(\eta'_0)_*(\Psi(t)) = 1 \in \mathbb{Z} = \pi_1(S^1)$. Thus, $u_0: G \to \mathbb{Z}$ defined by $u_0(t^n w) = n$ for all $w \in F_N$ satisfies $u_0 = (\eta'_0)_* \circ \Psi$.

**Convention 6.12.** For the remainder of this paper, we use the isomorphism $\Pi_* \circ \Psi: G \to \pi_1(X_f)$ to identify $G$ with $\pi_1(X_f)$. With this convention, and the fact that $\eta'_0 = \eta_0 \circ \Pi$ we see that $(\eta_0)_* = u_0$.

Since $Z_f$ is a $K(G,1)$ for $G = G_\varphi$ (see e.g. [Hat, Theorem 1.B 11]), as a consequence of Proposition 6.11 we have

**Corollary 6.13.** The folded mapping torus $X_f$ is a $K(G,1)$ space.

6.3. Horizontal, vertical, and edge degree.

**Definition 6.14.** We intuitively define the *degree* $d(e)$ of a 1–cell $e$ to be the number of 2–cells attached to $e$, counted with multiplicity. More precisely, we note that the attaching maps for the 2–cells are locally injective, and for every 1–cell $e$, we pick a point $x \in e$, and $d(e)$ is the total number of points in the preimage, over all attaching maps (local injectivity makes this definition independent of $x$). Equivalently, $d(e)$ is the minimum number of components of $U - e$, over all arbitrarily small neighborhoods $U$ of $x$. For example, any point in an edge of degree 2 has a neighborhood homeomorphic to $\mathbb{R}^2$.

**Definition 6.15.** The *horizontal foliation* of $X_f$ is the decomposition of $X_f$ into fibers $\Gamma_t$, for $t \in S^1$. We refer to any subset of a single fiber $\Gamma_t$ as being horizontal. We refer to any arc of a flow line as a *vertical* arc. More generally, any set of points that all flow forward to a common point will be called vertical.

The complement of the closure of the 1–cells of degree different than 2 is a topological surface. We note that the restriction of the horizontal foliation to this surface is a foliation in the traditional sense. Likewise, the restriction of the semiflow to this surface is a local flow.

The 1–cells fall into three types: vertical, horizontal and skew.

**Definition 6.16.** The *vertical* 1–cells are 1–cells contained in semiflow lines, while the *horizontal* 1–cells are contained in fibers of $\eta_0$. The skew 1–cells are the $m$ remaining 1–cells which occur as the (nonhorizontal/nonvertical) side of some triangle.

Note that the horizontal 1–cells all have degree 2 and the skew 1–cells all have degree 3. On the other hand, the vertical 1–cells have more general degrees.

**Lemma 6.17.** If $e$ is a vertical or skew 1–cell and $v \in V \Gamma_t$ is the vertex defined by $v = \Gamma_t \cap e$, then $d(e) = \text{val}(v)$, where $\text{val}(v)$ is the valence of $v$ in $\Gamma_t$. In particular, $d(e) \geq 2$ for every vertical 1–cell.
Proof. First suppose \( e \) is a vertical 1–cell, and observe that \( t \not\in \{ t_0, \ldots, t_m \} \) because \( \epsilon = \Pi(v_0 \times (t_i, t_{i+1})) \) for some vertex \( v_0 \in V \Gamma_t \) for some \( i \), and \( v = \Gamma_t \cap e \neq \emptyset \). The fact that \( d(e) = \text{val}(v) \) follows from the fact that one has a basis of neighborhoods of \( v \) in \( X \) of the form \( U = W \times (t - \epsilon, t + \epsilon) \) for small \( \epsilon > 0 \) and \( W \) a neighborhood of \( v \) in \( \Gamma_t \). The minimal number of components of \( W - v \) is equal to the minimal number of components of \( U - e \) over all sufficiently small neighborhoods \( W \) of \( v \) in \( \Gamma_t \), and this is equal to \( \text{val}(v) \), so \( d(e) \leq \text{val}(v) \). Any sufficiently small neighborhood about \( v \) in \( X \) is contained in some basis open set \( U \), and from here one easily deduces \( d(e) = \text{val}(v) \).

Since the intersection of a skew 1–cell \( e \) with \( \Gamma_t \) corresponds to the “new” vertex of a fold, and this vertex always has \( \text{val}(v) = 3 \) (and as we’ve already noted, \( d(e) = 3 \)), the first statement for \( e \) follows.

For the second statement, we note that our folding lines never produce graphs with valence 1 vertices, by Remark 4.3. \( \square \)

6.4. The trapezoid structure. To carry out the constructions in §8.7, it is desirable to modify the cell structure so that there are no horizontal 1–cells while maintaining a simple structure for the 2–cells. Simply erasing the horizontal 1–cells is insufficient, since the complement of the (closure of the) vertical and skew 1–cells need not be a union of disks (although it is a surface). We therefore proceed as follows.

For every edge \( e \) of \( \Gamma_0 \subset X_f \), we consider the image under the semiflow for time up to 1:

\[
R_e = \bigcup_{0 \leq s \leq 1} \psi_s(\bar{e}).
\]

We call this set the strip above \( e \). The complex \( X \) is a union of the strips above edges \( e \) of \( \Gamma_0 \).

Some strips contain a skew edge and others do not. The example in Figure 6 has 10 strips, 9 of which contain a skew edge, and one does not.

For each strip that does not contain a skew 1–cell, we subdivide the first rectangle \( \bar{e} \times [0, t_1] \) into two triangles by adding one of the diagonals (it does not matter which diagonal we add). The added diagonal becomes a 1–cell which we also call a skew 1–cell. The new skew 1–cells are distinguished from the previous ones by their degree: the new skew 1–cells all have degree 2, while the old ones have degree 3.

For any skew 1–cell \( e \), consider the set of points \( T_e \subset X - e \) that flow into \( e \) before meeting any other skew 1–cell. That is \( y \in T_e \) if and only if there exists \( r > 0 \) so that \( \psi_r(y) \in e \), and for all \( 0 \leq s < r \), \( \psi_s(y) \) is not contained in any skew 1–cell. We now describe \( T_e \) in more detail.

Suppose first that \( d(e) = 2 \). Below \( e \) is a unique triangle 2–cell, and call it \( U_1 \). The triangle \( U_1 \) lies below \( e \) and above a horizontal 1–cell \( \delta_1 \). The 1–cell \( \delta_1 \) is contained in the top arc of a 2–cell \( \sigma_2 \) (it may be a proper subarc of the top of this 2–cell only if \( \delta_1 \subset \Gamma_0 = \Gamma_1 \)). Let \( U_2 \) denote the subset of \( \sigma_2 \) directly below \( \delta_1 \) (that is, the subset of this 2–cell that flows into \( \delta_1 \)). If \( \sigma_2 \) is a triangle, then the bottom of \( U_2 \) is an arc of a skew 1–cell, and hence \( T_e = U_1 \cup \delta_1 \cup U_2 \). If \( \sigma_2 \) is a rectangle, then \( U_2 \) lies above an arc \( \delta_2 \) of a horizontal 1–cell \( e_2 \), and \( \delta_2 \) is a subarc of a 2–cell \( \sigma_3 \). Let \( U_3 \) denote the subset of \( \sigma_3 \) below \( \delta_2 \). If \( \sigma_3 \) is a triangle 2–cell, then

\[
T_e = U_1 \cup \delta_1 \cup U_2 \cup \delta_2 \cup U_3.
\]

Otherwise, \( \sigma_3 \) is a rectangle, and we repeat again. In this way, we eventually write \( T_e \) as

\[
T_e = U_1 \cup \delta_1 \cup U_2 \cup \delta_2 \cup \ldots \cup \delta_k \cup U_k
\]

for some \( k \geq 1 \). See Figure 7. This procedure terminates because every strip contains a skew 1–cell, hence a triangle (which explains why the new skew 1–cells were added).
If \( d(e) = 3 \), then below \( e \) there are exactly two triangle 2–cells. The above description can be carried out for each of the two triangles thus producing two trapezoids \( T_e = T'_e \sqcup T''_e \), each of which can be described as

\[
U_1 \cup \delta_1 \cup U_2 \cup \delta_2 \cup \ldots \cup \delta_k \cup U_k
\]

for some \( k \geq 1 \).

**Definition 6.18.** A trapezoid for \( X \) is a disk \( T_e \) when \( d(e) = 2 \) or one of \( T'_e \) or \( T''_e \) when \( d(e) = 3 \).

![Two possible trapezoids.](image)

**Figure 7.** Two possible trapezoids.

Let \( \mathcal{T} \) denote the set of all trapezoids. The closure of any \( T \in \mathcal{T} \) is a union

\[
\bar{T} = T \cup e_+(T) \cup e_-(T) \cup \ell_+(T) \cup \ell_-(T)
\]

where \( e_+(T) = \bar{e} \) and \( e \) is the initial skew 1–cell defining the trapezoid, \( e_-(T) \) is the arc of a skew 1–cell below \( T \), and \( \ell_\pm(T) \) are the arcs of flow lines bounding \( T \) on either side (one of which may degenerate to a single point). Although \( T \) is an open disk, \( \bar{T} \) need not be a closed disk (for example, it can happen that \( e_-(T) \subset e_+(T) \); see Figure 8).

Because every flow line eventually intersects some skew 1–cell (again because of the addition of the new skew 1–cells), it follows that \( X \) is the union

\[
X = \bigcup_{T \in \mathcal{T}} \bar{T}.
\]

Since \( T \cap T' = \emptyset \) for all \( T \neq T' \in \mathcal{T} \) (since the first skew 1–cell a point meets under \( \psi \) is unique), we can define a new cell structure for which \( \mathcal{T} \) is the set of 2–cells.

**Definition 6.19** (Trapezoid cell structure). The trapezoid cell structure is the cell structure for which \( \mathcal{T} \) is the set of 2–cells, and the vertices are precisely the union of the (three or) four corners of \( \bar{T} \) over all \( T \in \mathcal{T} \). We give the 1–skeleton \( X^{(1)}_f \) a metric structure so that the restriction of \( \eta_0 \) to each edge is a local isometry to \( S^1 \), and an orientation by insisting that these maps be orientation preserving.

**Convention 6.20.** In all of what follows, we will assume that the cell structure on \( X \) is the trapezoid cell structure, unless otherwise stated. We refer to the original cell structure (with the added diagonals) as the old cell structure. We also refer to the 1–cells of trapezoid cell structure as either vertical or skew.

**Remark 6.21.** We note that every skew 1–cell for the trapezoid cell structure is contained in a skew 1–cell of the old cell structure, but that this is not true for the vertical 1–cells. However, any vertical 1–cell of the trapezoid structure eventually flows into a vertical 1–cell of the old cell structure. Since the union of the vertical 1–cells of the old structure is invariant under \( \psi \) (because \( f(V\Gamma) \subset V\Gamma \)), so is the union of the vertical 1–cells of the trapezoid structure.
Example 6.22. The trapezoid cell structure for our running example $f: \Gamma \to \Gamma$ is shown in Figure 8. There are fourteen 0–cells, twenty-seven 1–cells and thirteen 2–cells.

![Figure 8: The trapezoid cell structure for the folded mapping torus $X_f$ for the example $f: \Gamma \to \Gamma$.](image)

6.5. The semiflow on trapezoids. As described above, each trapezoid is built from a union of subrectangles of rectangles, two subtriangles of triangles, and the horizontal arcs in between:

$$T = U_1 \cup \delta_1 \cup U_2 \cup \delta_2 \ldots \cup \delta_k \cup U_k.$$ 

As $T$ is a disk, $\psi$ actually restricts to a local flow on $T$. This local flow has a very simple description, see Figure 9.

Proposition 6.23. For every trapezoid $T \in \mathcal{T}$ there are real numbers $m_1, m_2, t_0 \in \mathbb{R}$ defining a (possibly degenerate) Euclidean trapezoid

$$\hat{T} = \{(r, t) \in \mathbb{R}^2 | 0 \leq r \leq 1, m_1 r \leq t \leq m_2 r + t_0\}$$

and a continuous map

$$\sigma_T: \hat{T} \to \hat{T}$$

such that $\sigma_T$ sends horizontal lines to horizontal arcs, and for all $(r, t) \in \hat{T}$ and $0 \leq s \leq m_2 r + t_0 - t$ we have

$$\sigma_T(r, t + s) = \psi_s(\sigma_T(r, t)).$$

Moreover, $\sigma_T$ restricted to the interior of $\hat{T}$ is a homeomorphism onto $T$.

Proof. By Proposition 6.8, we see that the map $\hat{\Pi}: \Gamma \times [0, 1] \to X$ obtained by composing $\Pi': \Gamma \times [0, 1] \to X$ with the projection $X' \to X$ satisfies

$$(x, t + s) \mapsto \psi_s(\hat{\Pi}(x, t)).$$

Since $T$ is a union of images of product rectangles and triangles in $\Gamma \times [0, 1]$ under $\hat{\Pi}$, it is straightforward to piece together the local flows $(x, t) \mapsto (x, t + s)$ on these and construct the required $\hat{T}$ and map $\sigma_T$. □

Convention 6.24. We use the maps $\sigma_T$ from Proposition 6.23 to give the interior of every trapezoid $T$ a smooth structure. Note that the local flow $\psi|_T$ on any trapezoid $T$ is thus smooth, as is $\eta_0|_T$. 
7. LOCAL MODELS FOR THE SEMIFLOW

The simplest behavior of $\psi$ is in the interior of a trapezoid where Proposition 6.23 gives a completely transparent picture of what $\psi$ looks like, namely it is a local flow on a trapezoid by translation in the direction of the parallel sides. Our next goal is to complete this description by giving “local models” for the semiflow near any point of the 1–skeleton of $X_f$.

Remark 7.1. The discussion in this section should be compared with [Gau1, Section 2.3]. In [Wan], similar issues are addressed using work of Bestvina and Brady [BB].

Definition 7.2 (Local model). A local model for $\psi$ is a subset of $X_f$ of the form

$$\mathcal{M}(K,s_0) = \bigcup_{0 \leq s \leq s_0} \psi_s(K)$$

where $s_0 > 0$ and $K$ is a closed contractible neighborhood of a point of $\Gamma_t$, for some $t$. We call $K$ the bottom of $\mathcal{M}$ and $\psi_{s_0}(K)$ the top and we call $\mathcal{M}$ minus the top and bottom the flow-interior of $\mathcal{M}$.

About every point of $X_f$ we will construct a local model $\mathcal{M} = \mathcal{M}(K,s_0)$ and study the maps

$$\psi_s: \psi_t(K) \to \psi_{t+s}(K)$$

induced by the flow on the horizontal pieces $\psi_t(K)$ and $\psi_{t+s}(K)$, for $0 \leq t < t+s \leq s_0$. As these maps will enjoy several useful properties, it is convenient to introduce the following terminology.

Definition 7.3 (Control rel boundary). Given two finite graphs $Q_0$ and $Q_1$, let $\partial Q_0$ and $\partial Q_1$ denote the set of valence 1 vertices. We will say that a continuous map $\Upsilon: Q_0 \to Q_1$ is controlled rel boundary if the following holds:

1. For every $x \in Q_1$, $\Upsilon^{-1}(x)$ is finite;
2. $\Upsilon(\partial Q_0) = \partial Q_1$ and $\Upsilon^{-1}(\partial Q_1) = \partial Q_0$; and
3. $\Upsilon: (Q_0, \partial Q_0) \to (Q_1, \partial Q_1)$ is a relative homotopy equivalence. That is, there exists a continuous map $\Upsilon_0: (Q_1, \partial Q_1) \to (Q_0, \partial Q_0)$ so that

$$\Upsilon_0 \circ \Upsilon: Q_0 \to Q_0$$

and $\Upsilon \circ \Upsilon_0: Q_1 \to Q_1$ are homotopic rel $\partial Q_0$ and $\partial Q_1$, respectively, to the identity.

Note that $\Upsilon$ must restrict to a bijection from $\partial Q_0$ to $\partial Q_1$, and that $\Upsilon_0|_{\partial Q_1} = (\Upsilon|_{\partial Q_0})^{-1}$. 
This notion gives rise to a useful local definition for a map between graphs (cf. [Gau1, Definition 2.11]).

**Definition 7.4** (local control). If $Q_0$ and $Q_1$ are graphs, then a map $\Upsilon: Q_0 \to Q_1$ is *locally controlled* if there exists subdivisions $Q'_0$ of $Q_0$ and $Q'_1$ of $Q_1$ with the following properties.

1. $Q'_0$ and $Q'_1$ are each a finite union of subgraphs: $Q'_0 = Q'_0^0 \cup \ldots \cup Q'_0^r$, $Q'_1 = Q'_1^0 \cup \ldots \cup Q'_1^s$.
2. For each $i = 0, 1$ and every $j, j'$, $Q'_i \cap Q'_j \subset Q'_i \cup \partial Q'_j$; and
3. For each $j = 1, \ldots, r$, $\Upsilon(Q'_0^j) = Q'_1^j$ and the restriction $\Upsilon|_{Q'_0^j}: Q'_0^j \to Q'_1^j$ is controlled rel boundary.

**Proposition 7.5.** If $Q_0, Q_1$ are finite graphs and $\Upsilon: Q_0 \to Q_1$ is locally controlled, then $\Upsilon$ is a homotopy equivalence and for every $x \in Q_1$, $\Upsilon^{-1}(x)$ is finite.

**Proof.** Since $\Upsilon|_{Q'_0}$ is locally controlled rel boundary for all $j$, it follows that

$$\Upsilon \left( \bigcup_{j=1}^{r} \partial Q'_0^j \right) = \bigcup_{j=1}^{r} \partial Q'_1^j$$

and the restriction of $\Upsilon$ to $\cup \partial Q'_0^j$ is a bijection onto $\cup \partial Q'_1^j$. By definition of controlled rel boundary, there exist $r$ continuous maps

$$\Upsilon'_0: Q'_0^j \to Q'_0^j$$

such that $\Upsilon'_0 \circ \Upsilon|_{Q'_0^j}: Q'_0^j \to Q'_0^j$ and $\Upsilon|_{Q'_0^j} \circ \Upsilon'_0: Q'_1^j \to Q'_1^j$ are homotopic relative to $\partial Q'_0^j$ and $\partial Q'_1^j$, respectively, to the identity. Since

$$\Upsilon'_0|_{\partial Q'_0^j} = (\Upsilon|_{\partial Q'_0^j})^{-1}$$

it follows that $\Upsilon'_0$ and $\Upsilon'_1$ agree on $Q'_1 \cap Q'_1'$ for all $j, j'$. Therefore, the $\Upsilon'_0$ are the restrictions of a continuous map

$$\Upsilon_0: Q_1 \to Q_0.$$

The various homotopies to the identities glue together to define homotopies of $\Upsilon_0 \circ \Upsilon: Q_0 \to Q_0$ and $\Upsilon \circ \Upsilon_0: Q_1 \to Q_1$ to the respective identities. Thus, $\Upsilon$ is a homotopy equivalence.

For any $x \in Q_1$, we have $x \in Q'_1$ for some $j$ and hence $\Upsilon^{-1}(x) = \Upsilon|_{Q'_0}^{-1}(x)$ is finite. 

**Proposition 7.6.** For every open set $U \subset X_f$ and every point $x \in U$, there exists a local model neighborhood $\mathcal{M}(K, s_0) \subset U$ containing $x$ in its interior such that

$$\psi_s: \psi_t(K) \to \psi_{t+s}(K)$$

is controlled rel boundary for all $0 \leq s, t \leq s + t \leq s_0$.

**Proof.** Recall that $0 = t_0 < \cdots < t_m = 1$ denote the times at which the Stallings folds $\Delta_i = \Gamma_{t_i}$ occur during the folding process. Let $t' \in [0, 1)$ be such that $x \in \Gamma_{t'}$ and $t' \in [t_{j-1}, t_j)$ for some $j = 1, \ldots, m$. Similarly choose $t'' \in (0, 1]$ so that $x \in \Gamma_{t''}$ and $t'' \in (t_{j-1}, t_j]$ for some $i = 1, \ldots, m$. Thus $t' = t''$ unless $x \in \Gamma_0 = \Gamma_1$, in which case we have $t' = 0$ and $t'' = 1$. The proposition essentially follows from the fact that for small $s > 0$ the maps $\psi_s: \Gamma_{t'} \to \Gamma_{t'+s}$ and $\psi_s: \Gamma_{t''-s} \to \Gamma_{t''}$ are just the folding maps $r_{t'+s, t'}$ and $r_{t''-s, t''}$, respectively.

Note that while $\Gamma_{t'} = \Gamma_{t''}$ as sets and topological spaces, the graph structure on $\Gamma_{t'}$ may be a combinatorial subdivision of that in $\Gamma_{t''}$ (when $t' = 0$ and $t'' = 1$). In any case, we may choose a closed contractible neighborhood $K$ of $x$ in $\Gamma_{t'} = \Gamma_{t''}$ so that $\partial K$ is disjoint from $\partial \Gamma_{t'}$ and $\partial \Gamma_{t''}$. We let $D > 0$ be any number less than the minimal distance from $\partial K$ to $\partial \Gamma_{t'} \cup \partial \Gamma_{t''}$ in either of the metrics on $\Gamma_{t'}$ and $\Gamma_{t''}$. 


Next, let $\zeta$ denote the speed of folding. That is, for all $t_{k-1} \leq s < s' \leq t_k$, the map $r_{s',s}$ identifies the length $\zeta(s' - s)$ initial segments of two edges $e_1, e_2 \in \Gamma_s$ (thus $\zeta = 1/L$ from §4). Fix any $0 < \delta < \min \{ \rho, |t_j - t'|, |t'' - t_{k-1}| \}$.

We claim that if $K_s = r_{s,t}(K)$, then for all $t' \leq s \leq s' \leq t + \delta$, $r_{s',s}|K_s$ is controlled rel boundary. Indeed, the vertex $v = o(e_1) = o(e_2)$ of $\Gamma_{t'}$ that is being folded by $r_{s',t'}$ moves at speed $\zeta$, and so $r_{s',t'} = r_{s',s} \circ r_{s,t}$ only fails to be a homeomorphism on the $\zeta(s' - t') < D$ neighborhood of $v$, which is contained in the complement of $\partial K$. Thus if $v \notin K$, $r_{s',v}|K_s$, hence also $r_{s',s}|K_s$, is a homeomorphism. Otherwise $r_{s',s}|K_s$ simply identifies initial segments of length $\zeta(s' - s)$ of a pair of edges, and hence is nevertheless controlled rel boundary.

By similar reasoning, if $t'' - \delta \leq s \leq s' \leq t''$ and if we write $K_s$ to denote $(r_{t''-t'})^{-1}(K) \subset \Gamma_s$, we again find that $r_{s',s}|K_s : K_s \to K_{s'}$ is controlled rel boundary. Therefore, by choosing $s_0 = 2\delta$ and $K = K_{t''-t}$, we see that $M(K',s_0)$ is a local model satisfying the conclusion of the proposition. \hfill \Box

7.1. Examples of local models. Local models will play an important role in the sequel. In an effort to familiarize the reader with these tools, and to clarify the proof of 7.6, in this subsection we will describe and illustrate some specific types of local models. In all figures throughout this subsection, we have indicated 1–cells of $X_f$ with thick lines. A single arrow indicates a vertical 1–cell and double arrow indicates a skew 1–cell.

The simplest type of local models are homeomorphic to surfaces, in which case $K \cong [-1,1]$ and $K \times [0,s_0] \cong M(K,s_0)$ via a homeomorphism $(r,t) \mapsto \psi_t(r)$. We call these surface local models. These exist for any point in the interior of a trapezoid (for example, by proposition 6.23), but they also exist near 1–cells with degree 2, and 0–cells for which all adjacent 1–cells are degree 2. In this case, note that the semiflow restricts to a local flow, and the maps

$$\psi_s : \psi_t(K) \to \psi_{t+s}(K)$$

are all homeomorphisms (in particular, they are controlled rel boundary).

However, local models near the 1–cells $e$ with $d(e) > 2$ are necessarily more complicated. It is thus useful to distinguish these, and we do so with the following

Definition 7.7. Let $E_0$ denote the set of 1–cells $e$ with $d(e) > 2$. Let $E_0 \subset X_f^{(1)}$ denote the subgraph of the 1–skeleton with edge set $E_0$ and vertex set $\{ o(e), t(e) \mid e \in E_0 \}$. We give $E_0$ the restricted metric structure and orientation from that of $X_f^{(1)}$; see Definition 6.19.

Let us next consider the local model about a point $x$ in a 1–cell $e$ with $d(e) > 2$. When $e$ is a vertical 1–cell there is a local model for which the semiflow restricts to a local flow. Indeed, if $x = \Gamma_t \cap e$, then for nearby $t' < t < t''$ with $t'' - t'$ sufficiently small, we will have that $\Gamma_{t'} \cap e$ is a vertex of $\Gamma_s$ of degree $d(e)$ for all $s \in [t',t'']$. Subdividing each edge of $\Gamma_{t'}$ adjacent to $x' = \Gamma_{t'} \cap e$ by adding a point very close to $x'$, and letting $K$ be the star of $x'$, we see that the flow defines a homeomorphism $K \times [t',t''] \to M(K,t'' - t')$ via $(y,s) \mapsto \psi_{s-t'}(y)$. See Figure 10.

When $e$ is a skew 1–cell with $d(e) = 3$ there is a local model neighborhood as shown at the right of Figure 10. Observe that any such $x$ is contained in $X_f(t)$ for some $t_i < t < t_{i+1}$ and some building block $X_f^i$. In particular, the local models are obtained from the explicit construction of the building blocks; see Definition 6.3. Here we note that the maps $\psi_s : \psi_t(K) \to \psi_{t+s}(K)$ are not homeomorphisms, although they are controlled rel boundary.

Finally we consider local models near 0–cells, for which there is a variety of possible behavior. To simplify the discussion, let us assume $v$ is a 0–cell that does not lie in the interior of an old skew 1–cell and does not have a local model homeomorphic to a surface. For such a point, we will actually illustrate two local models, one above $v$ and one below $v$. By combining these, one obtains what we call a stacked local model.
Under our assumptions, $v$ is a 0–cell of the old cell structure, and is thus a vertex of valence at least 3 in $\Gamma_{t_i}$ for some $t_i$ with $i = 0, \ldots, m - 1$ (if $v$ had valence 2, it would have a surface local model neighborhood). We construct a local model above $v$ by subdividing each edge of $\Gamma_{t_i}$ adjacent to $v$ and taking $K$ to be the closed star of $v$. Taking $s_0 \in (0, t_{i+1} - t_i)$, we obtain a local model $M(K, s_0)$ for $v$ that is in fact contained in the image of the building block $X'_f$.

There are essentially two possibilities for $M(K, s_0)$. If $v = o(e) = o(e')$ for two distinct edges $e, e'$ which are folded together in $\Gamma_{t_{i+1}}$, then this folding produces a skew 1–cell $e_1$ with $o(e_1) = v$ and $d(e_1) = 3$, and a vertical 1–cell $e_2$ with $d(e_2) = v$ with $d(e_2) = \text{val}(v) - 1$, where $\text{val}(v)$ is the valence of $v$ in $\Gamma_{t_i}$. We have illustrated $M(K, s_0)$ in Figure 11 (b) (for $\text{val}(v) = 5$) and (c) (for $\text{val}(v) = 3$). If $v$ is not the initial vertex of a pair of edges folded together in $\Gamma_{t_{i+1}}$, then (for $s_0$ sufficiently small), $M(K, s_0)$ is a product. See Figure 11 (a) (for $\text{val}(v) = 5$).

A local model below $v$ is described similarly. If $v \in \Gamma_0$, then $v \in \Gamma_1$ as well, so we may assume that $v \in \Gamma_{t_i}$ with $i = 1, \ldots, m$ is a vertex with $\text{val}(v) \geq 3$. We again take the star $K'$ of $v$ in $\Gamma_{t_i}$ (after subdividing), and set $K = (\psi_{s_0})^{-1}(K')$ for a small $s_0 \in (0, t_i - t_{i-1})$. Then

$$M(K, s_0) = \{(\psi_s)^{-1}(K') \mid 0 \leq s \leq s_0\}$$

is a local model below $v$. Again there are essentially two possibilities, which are illustrated in Figure 11 (d)–(f) (for $\text{val}(v) = 5$ or 3). Note that in all cases, the local models have the property that the flow maps $\psi_s : \psi_t(K) \to \psi_{t+s}(K)$ are controlled rel boundary.

### 7.2. The $E_0$–class.

Recall that the 1–skeleton $X_f^{(1)}$ is oriented; see Definition 6.19. Define a cellular 1–chain $\epsilon \in C_1(X_f; \mathbb{R})$ by

$$\epsilon = \frac{1}{2} \sum e [2 - d(e)] e,$$

where the sum is over all 1–cells $e$ in $X_f^{(1)}$, although the coefficients are nonzero only on edges $e \in E_0$. As an application of the local models, we prove:

**Proposition 7.8.** The chain $\epsilon$ is a cycle $\epsilon \in Z_1(X_f; \mathbb{R})$.

**Proof.** Fix a 0–cell $v \in V \mathcal{E}_0$. We need to show that the value of $\partial \epsilon$ on $v$ is zero. To prove this fact, choose a local model neighborhood $M(K, s_0)$ around $v$, so that $v \in \psi_{s'_0}(K)$ for some $0 < s'_0 < s_0$. Note that because $v \in V \mathcal{E}_0$, this is not a surface local model, and hence it is a stacked local...
model which we write as \( \mathcal{M} = \mathcal{M}^+ \cup \mathcal{M}^- \) for local models \( \mathcal{M}^- \) and \( \mathcal{M}^+ \) below and above \( v \), respectively.

Now let \( e_1^-, \ldots, e_r^- \) (respectively, \( e_1^+, \ldots, e_r^+ \)) denote 1–cells in \( E_0 \) with \( t(e_j^-) = v \) (respectively, \( o(e_j^+) = v \)). Every \( e_j^\pm \) nontrivially intersects the local model \( \mathcal{M}^\pm \), as shown in Figure 11. If we let \( v_j^- = e_j^- \cap K = \psi_0(K) \) and \( v_j^+ = e_j^+ \cap \psi_{s_0}(K) \) then for all \( j \) we clearly have

\[
\text{val}(v_j^+) = d(e_j^+) \]

where \( \text{val}(v_j^-) \) denotes the valence of \( v_j^- \) in \( K \), and \( \text{val}(v_j^+) \) denotes the valence of \( v_j^+ \) in \( \psi_{s_0}(K) \). Moreover, by inspecting the local models, we can see that

\[
\sum_{j=1}^r 2 - \text{val}(v_j^-) = 2 - \text{val}(v) = \sum_{j=1}^{r'} 2 - \text{val}(v_j^+) \]
where \( \text{val}(v) \) denotes the valence of \( v \) in \( \psi_s(K) \). Combining these two equations we obtain

\[
\sum_{j=1}^{r} 2 - d(e_j^-) = 2 - \text{val}(v) = \sum_{j=1}^{r'} 2 - d(e_j^+).
\]

Finally, we observe that the coefficient of \( v \) in \( \partial e \) is equal to one half of the difference of the two sums here, and hence is zero. This completes the proof of the proposition. \( \square \)

**Definition 7.9.** We refer to the homology class of \( e \) as the \( E_0 \)-class. As an abuse of notation, we also denote the homology class by \( e \in H_1(X_f; \mathbb{R}) \).

**Remark 7.10.** We now explain the strong geometric analogy between our construction of the \( E_0 \)-class and the Poincaré dual of the Euler class in the 3-manifold setting.

Suppose that \( \eta_0 : M \to S^1 \) is a closed, oriented 3–manifold that fibers over \( S^1 \) inducing some primitive integral element \( (\eta_0)_* = u_0 \) with pseudo-Anosov monodromy \( F : S \to S \). Let \( T\mathcal{F} \to M \) denote the tangent plane bundle of the foliation \( \mathcal{F} \) by fibers (which is also the kernel of the 1–form \( \eta_0^d(\text{vol}_{S^1}) \)). Taking any section \( \sigma : M \to T\mathcal{F} \) transverse to the zero section \( Z \subset T\mathcal{F} \), the Poincaré dual \( e \) of the Euler class of \( T\mathcal{F} \) is represented by the oriented 1–submanifold \( \sigma^{-1}(Z) \); see [BT, §12].

Now suppose that the stable foliation \( \mathcal{F} \) is orientable, all singularities are 4–prong, and that the orientation is preserved by \( F \). Suspending \( \mathcal{F} \) defines a 2–dimensional singular foliation that intersects each fiber in the stable foliation for the first return map to that fiber. Because \( \mathcal{F} \) is orientable (and the orientation is preserved by \( F \)), we can choose a section \( \sigma \) of \( T\mathcal{F} \) that is also tangent to \( \mathcal{F} \) at every nonsingular point, and is zero precisely at the singular points. Moreover, since the singularities are 4–prong (i.e. index \(-1\)), this can be done so that \( \sigma \) is transverse to \( Z \). Therefore, \( e \) is represented by the suspension of the singular points of \( \mathcal{F} \).

This conclusion actually holds without any assumption on orientability of \( \mathcal{F} \) or on the number of prongs at the singularity, with the appropriate modifications. Namely, if \( \gamma_1, \ldots, \gamma_n \) are all the closed orbits of singular points under the suspension flow, and if the number of prongs of a singular point \( p_i \) contained in \( \gamma_i \) is denoted \( d(\gamma_i) \), then \( e \) is represented by the oriented 1–manifold

\[
\frac{1}{2} \sum_{i=1}^{n} [2 - d(\gamma_i)]\gamma_i.
\]

Here, \( \frac{1}{2}(2 - d(\gamma_i)) \) is just the index of the singularity (see e.g. [FLP, Exposé 5]). The \( E_0 \)-class is the obvious analogue in which the closed orbits are replaced by the 1–cells of the cell structure, and the number of prongs is replaced by degree (as the notation suggests).

### 8. Cocycles, Fibrations, and the \( E_0 \)-class

Here we begin a more detailed analysis of the map \( \eta_0 : X_f \to S^1 \). As described in §6.2 \( \eta_0 \) induces the integral element \( u_0 = (\eta_0)_* \in H^1(X_f; \mathbb{R}) \cong H^1(G; \mathbb{R}) \cong \text{Hom}(G, \mathbb{R}) \); see Proposition 6.11 and Convention 6.12. In this section we explain how to construct the neighborhood \( \mathcal{A} \subset H^1(X_f; \mathbb{R}) \) for which the integral elements in this neighborhood are similarly induced by maps \( \eta : X_f \to S^1 \). We also begin to explain how much of the structure of \( \eta_0 \) is also present in \( \eta \). We complete this section with the proof of Theorem B.

#### 8.1. Cellular cocycle representatives

The first task is to provide an explicit cellular cocycle \( z_0 \in Z^1(X_f; \mathbb{Z}) \) representing \( u_0 \). This is done as follows. Recall that unless otherwise stated, the cell structure is always the trapezoid cell structure.
The restriction of \( \eta_0 \) to any cell \( \sigma \subset X_f \) can be lifted to the universal cover:

\[
\begin{array}{c}
\tilde{\eta}_0|_{\sigma} \\
\sigma
\end{array} \quad \xrightarrow{\eta_0|_{\sigma}} \quad S^1
\]

Moreover, this lift is unique up to composing with a covering transformation \( x \mapsto x + n, \ n \in \mathbb{Z} \).

For any 1–cell \( e \) the difference in the values at the end points of the lift \( \tilde{\eta}_0|_e \) is independent of the lift, and we denote this difference by \( z_0(e) \). This assignment defines a cellular cochain \( z_0 \in C^1(X_f; \mathbb{R}) \).

**Lemma 8.1.** The cochain \( z_0 \) is a cocycle representing the class \( u_0 \).

**Proof.** For any based loop \( \gamma: [0, 1] \to X_f \) constructed as a concatenation of oriented 1–cells \( e_1^{\delta_1} e_2^{\delta_2} \cdots e_k^{\delta_k} \), where \( \delta_j \in \{\pm 1\} \), we obtain lifts \( \tilde{\eta}_0|_{\gamma} \) to \( \mathbb{R} \) by restricting a lift \( \tilde{\eta}_0 \circ \gamma: [0, 1] \to \mathbb{R} \) of \( \eta_0 \circ \gamma \). Then

\[
\begin{align*}
\quad \quad \quad \quad u_0(\gamma) &= (\eta_0)_*(\gamma) = \tilde{\eta}_0 \circ \gamma(1) - \tilde{\eta}_0 \circ \gamma(0) \\
&= \sum_{j=1}^k \delta_j z_0(e_j) = z_0(\sum_{j=1}^k \delta_j e_j) \\
&= z_0(\gamma).
\end{align*}
\]

In particular, the value of \( z_0 \) around the boundary of any 2–cell is the value of \( u_0 \) around the cell which is zero. Thus \( z_0 \) is a cocycle, and it agrees with \( u_0 \) on every loop. \( \square \)

### 8.2. Positive cocycles.

**Definition 8.2.** Call a cocycle \( z \in Z^1(X_f; \mathbb{R}) \) positive if

\[
z(e) > 0
\]

for every 1–cell \( e \).

**Remark 8.3.** This definition is analogous to the notion of positivity in Gautero’s dynamical 2–complex (see [Gau1, Definition 2.1]), and will serve a similar purpose. See also Wang [Wan].

Since the restriction of \( \eta_0 \) to any 1–cell \( e \) is an orientation preserving diffeomorphism, the discussion in the previous section together with Lemma 8.1 shows that \( z_0 \) is a positive cocycle.

**Proposition 8.4.** The set of cohomology classes represented by positive 1–cocycles is an open, convex cone \( \mathcal{A} \subset H^1(X_f; \mathbb{R}) \).

**Proof.** Choose a basis for \( H^1(X_f; \mathbb{R}) \) represented by cocycles \( \zeta_1, \ldots, \zeta_b \). Suppose \( z \) is positive, so that \( z(e) > 0 \) for every \( e \in E_0 \). Then one can find \( s > 0 \) so that for all \( s_1, \ldots, s_b \) with \( |s_j| < s \) for every \( j \), we also have

\[
z(e) + \sum_{j=1}^b s_j \zeta_j(e) > 0
\]

for every 1–cell \( e \). The set

\[
\{[t(z + s_j \zeta_j)] \in H^1(X_f; \mathbb{R}) \mid |s_j| < s, \ t > 0\}
\]

is a neighborhood of \([z] \in H^1(X_f; \mathbb{R})\), consisting entirely of cohomology classes represented by positive cocycles. Therefore, \( \mathcal{A} \) is open.
Suppose $z_1, z_2$ are positive and $s, t > 0$. For any 1–cell $e$, we have $z_1(e) > 0$ and $z_2(e) > 0$ and thus

$$(tz_1 + sz_2)(e) = tz_1(e) + sz_2(e) > 0.$$ 

Therefore, $A$ is a convex cone.

**Definition 8.5 (Positive cone).** We denote by $A_{X_f}$ the set of all $u \in H^1(G_u; \mathbb{R}) = H^1(X_f; \mathbb{R})$ such that $u$ can be represented by a positive 1–cocycle. We call $A_{X_f}$ the **positive cone** corresponding to $X_f$.

### 8.3. Trapezoidal subdivisions.

For each positive 1–cocyce $z$ representing an integral class in $u \in A$, we seek to construct a ‘perturbed’ fibration $\eta_z: X_f \to S^1$ that, among other things, induces the homomorphism $u: G \to \mathbb{Z}$ on the level of fundamental group. To aid in the construction of $\eta_z$, which will be carried out in §8.7, it will be helpful to use a subdivided cell structure on $X_f$ that is tailored to the cocycle $z$. Here we describe the type of cell structures that we will use.

For a trapezoidal 2–cell $T$ of $X_f$, recall that $\ell_-(T), \ell_+(T), e_-(T),$ and $e_+(T)$ denote the left, right, bottom and top arcs of $T$, respectively. As each of these arcs is in fact a union of 1–cells of $X_f$, we may regard them as cellular 1–chains in $X_f$. The trapezoid $T$ induces a $T$–orientation on these arcs as follows: By definition, $\ell_+(T)$ and $e_-(T)$ are given the positive orientation (as specified in Definition 6.19) so that the 1–cells comprising $\ell_+(T)$ and $e_-(T)$ must appear with positive coefficient in those 1–chains. The two sides $\ell_\pm(T)$ of $T$ are then distinguished by the convention that $e_-(T)$ is oriented from $\ell_-(T)$ to $\ell_+(T)$. Lastly the $T$–orientation on the top arc $e_+(T)$ is defined so that it is also oriented from $\ell_-(T)$ to $\ell_+(T)$. Alternatively, using $\psi$ to flow the bottom to the top defines a map $h_T: e_-(T) \to e_+(T)$ which is a homeomorphism on the interior of $e_-(T)$; the $T$–orientation on $e_+(T)$ is defined such that $h_T$ is orientation preserving.

As the $T$–orientation on $e_+(T)$ may not agree with the positive orientation on $X_f^{(1)}$, we see that the 1–cells comprising the 1–chain $e_+(T)$ may appear with positive or negative coefficient in this 1–chain. Define the **sign of $T$** to be $\zeta(T) \in \{\pm 1\}$ such that $\zeta(T)e_+(T)$ has positive coefficients. With these definitions, the boundary of $T$ is the cellular 1–chain

$$\partial T = e_-(T) + \ell_+(T) - e_+(T) - \ell_-(T).$$

We furthermore recall that the cell structure on $X_f$ is constructed so that every 1–cell is either vertical or skew. The sides $\ell_\pm(T)$ of each trapezoid $T$ consist of vertical 1–cells, and the top $e_+(T)$ consists of (possibly several) skew 1–cells. On the other hand, the bottom $e_-(T)$ of each trapezoid consists of a single skew 1–cell. Conversely, every skew 1–cell of $X_f$ is equal to $e_-(T)$ for a unique trapezoid $T$. The subdivisions of $X_f$ that we construct below will again be **trapezoidal cell structures**, meaning that they have exactly this structure. Furthermore, each 2–cell $T$ of the subdivision will be a trapezoid that is contained in a unique 2–cell $T'$ of $X_f$. In fact $T$ will be a subtrapezoid of $T'$ having top and bottom arcs, again denoted $e_\pm(T)$, that are subarcs of $e_\pm(T')$ and with side arcs, again denoted $\ell_\pm(T)$, being arcs of flowlines running all the way from the bottom to the top of $T'$. Such a subdivision will be called a **trapezoidal subdivision**. As with $X_f$, the 1–cells are all skew or vertical and hence inherit orientations making the restriction of the fibration $\eta_0$ to each 1–cell orientation preserving. We use the same conventions for the $T$–orientation on the sides of a trapezoid $T$ of the subdivision and define the sign $\zeta(T)$ just as for trapezoids of $X_f$. With these definitions we have $\zeta(T) = \zeta(T')$, where $T'$ is the unique 2–cell of $X_f$ containing $T$.

### 8.4. The subdivision procedure.

Consider a trapezoidal subdivision $Y$ of $X_f$. Suppose that $Y$ contains a trapezoid $T_0$ whose top arc $e_+(T_0)$ consists of a single skew 1–cell. This 1–cell is then necessarily the bottom of another trapezoid $T_1$ which may again have a single 1–cell along its top arc $e_+(T_1)$. Continuing in this manner we may be able to find a sequence of
Lemma 8.6. Every invariant band $B$ of a trapezoidal subdivision $Y$ of $X_f$ contains a closed orbit $O$ of $\psi$ in its interior that intersects each trapezoid of the band in a single vertical arc.

Proof. Let us write the invariant band as $B = T_0 \cup \cdots \cup T_k$, where $T_k = T_0$. Since $B$ is invariant under $\psi$ and every flowline of $X_f$ intersects the graph $\Gamma \subset X_f$ infinitely often, it must be the case that some trapezoid of $B$, say $T_0$, intersects $\Gamma$ nontrivially. Moreover, since $T_0$ is a subtrapezoid of a unique trapezoidal subdivision $T''$ of $X_f$ and since $\Gamma$ is by construction disjoint from the interior of $T''(T')$ and can intersect $T'$ in at most one connected component (see §6.4), we see that $\Gamma \cap T_0$ must consist of a single arc $c$ running from $\ell_-(T_0)$ to $\ell_+(T_0)$. As the intersection of $\Gamma$ with any trapezoid of $X_f$ is either empty or contained in a single edge of $\Gamma$, we furthermore see that $c \subset \Gamma$ is a subarc of a single edge $e$ of $\Gamma$.

Let $f': c \to c$ denote the first return map of the restricted flow $\psi|_B$ to $c \subset B$. Since the first return map of $\psi$ to $\Gamma$ is the original map $f$, it follows that $f' = f^m|_c$ for some $m \geq 1$. Using the linear structure on $\Gamma$ to identify $c$ with a closed interval $[0, 1]$, we now see that $f'$ is an affine homeomorphism from $c$ to itself. Therefore, $f'$ necessarily has a fixed point $x$ in the interior of $c$. Taking the flowline through $x$ then gives a closed orbit of $\psi$ contained in the interior of $B$ that intersects each trapezoid $T_i$ in a single vertical arc. \qed

Remark 8.7. When $f: \Gamma \to \Gamma$ is an expanding irreducible train track map, Lemma 3.1 shows that $f$ is expanding on all scales and so there cannot exist a subarc $c \subset \Gamma$ of an edge of $\Gamma$ and a power $m \geq 1$ for which $f^m|_c$ is a homeomorphism. Therefore the proof of Lemma 8.6 implies that a trapezoidal subdivision of $X_f$ cannot contain any invariant bands when $f: \Gamma \to \Gamma$ is an expanding irreducible train track map.

We now define the subdivision procedure that will be used in §8.7 below.

Definition 8.8 (Standard subdivision). Let $Y$ be a trapezoidal subdivision of $X_f$. The standard subdivision $\hat{Y}$ of $Y$ is constructed as follows. Firstly, for each invariant band $B = T_0 \cup \cdots \cup T_k$ (with $T_k = T_0$) of $Y$, Lemma 8.6 provides a closed orbit $O$ of $\psi$ in the interior of $B$. The top and bottom arcs of each trapezoid $T_i$ consist of single skew 1–cells of $Y$, and the maps $h_{T_i}: e_-(T_i) \to e_+(T_i)$ give us homeomorphisms $e_-(T_i) \to e_-(T_{i+1})$ between these 1–cells. We subdivide each of these 1–cell into two 1–cells by adding a vertex at the point $v_i = O \cap e_-(T_i)$ for $0 \leq i < k$. We furthermore subdivide each trapezoid $T_i$ of $B$ into two trapezoids by adding a vertical 1–cell $\beta_i = O \cap T_i$ from $v_i$ to $v_{i+1}$ (notice that these 1–cells are by construction arcs of flowlines). Let $Y^*$ denote the auxiliary trapezoidal subdivision of $Y$ obtained by performing this procedure to each invariant band of $Y$. In light of Remark 8.7, we see that this has no effect (that is $Y^* = Y$) in the case that $f: \Gamma \to \Gamma$ is an expanding irreducible train track map.

We now further subdivide $Y^*$ as follows. First, the vertical 1–cells are not subdivided. Each skew 1–cell of $Y^*$ is $e_-(T)$ for some trapezoid $T$ of $Y^*$, and we may write the top arc of $T$ as a concatenation of skew 1–cells of $Y^*$. Let $v_0, v_1, \ldots, v_k$ be the vertices of $e_+(T)$, traversed in that order along $e_+(T)$ (with the $T$–orientation), so that $v_0$ is the top endpoint of $\ell_-(T)$ and $v_k$ is the top endpoint of $\ell_+(T)$. We let $u_i = h_T^{-1}(v_i)$, where $h_T: e_-(T) \to e_+(T)$ is the map defined by $\psi$, and we subdivide $e_-(T)$ at the points $u_1, \ldots, u_k$ yielding new 1–cells $\alpha_i = (u_{i-1}, u_i)$ for $1 \leq i \leq k$ (so if $k = 1$, $e_-(T)$ is not subdivided). Lastly, we subdivide the trapezoid $T$ of $Y^*$ into
Definition 8.10 (Skew ratio). Let $Y$ be a trapezoidal subdivision of $X_f$, and let $z \in Z^1(Y; \mathbb{R})$ be a positive cocycle on $Y$. For a trapezoid $T$ of $Y$ whose top arc is a 1–cell $e_+(T) = \zeta(T)(\sigma_1 + \cdots + \sigma_k)$ we define the skew ratios of $T$ to be the numbers

$$0 < \rho(T) = \frac{z(\sigma_i)}{\zeta(T)z(e_+(T))} \leq 1,$$

where the maximum is over all trapezoids $T$ of $Y$. To emphasize the dependence on the cocycle $z$, these quantities will sometimes be notated more elaborately as $\rho_i(T, z)$, $\rho(T, z)$, and $\rho(Y, z)$.

Definition 8.11 (Standard refinement). Let $z \in Z^1(Y; \mathbb{R})$ be a positive cocycle on a trapezoidal subdivision $Y$ of $X_f$. The standard refinement of $z$ is the positive cocycle $\hat{z} \in Z^1(\hat{Y}; \mathbb{R})$ defined as follows: First consider a trapezoid $T$ contained in an invariant band of $Y$. Then in the auxiliary subdivision $Y^*$, the bottom arc $e_-(T)$ is subdivided into two skew 1–cells $\sigma_1, \sigma_2$ and the trapezoid $T$ is subdivided into two trapezoids by the addition of a new vertical 1–cell $\beta$. Correspondingly, we define an auxiliary refinement $z^* \in Z^1(Y^*; \mathbb{R})$ of $z$ by declaring

$$z^*(\sigma_1) = z^*(\sigma_2) = \frac{z(e_-(T))}{2} \quad \text{and} \quad z^*(\beta) = \frac{z(e_-(T)) + z(e_+(T))}{2} \quad (8.3)$$
for the new 1–cells arising in any such trapezoid and leaving \( z \) unchanged on the remaining 1–cells of \( Y \). It is straightforward to check that \( z^* \) then defines a positive refinement of \( z \).

Next consider any trapezoid \( T \) of \( Y^* \) with top arc a 1–chain \( e_+(T) = \zeta(T)(\sigma_1 + \cdots + \sigma_k) \) in \( Y^* \). As in Definition 8.8 we let \( \alpha_1, \ldots, \alpha_k \) be the new skew 1–cells for the subdivision of \( e_-(T) \) in \( \hat{Y} \), and \( \beta_1, \ldots, \beta_{k-1} \) the new vertical 1–cells of \( \hat{Y} \) inside \( T \). These are indexed so that \( \beta_i \) connects the terminal vertex of \( h_T(\alpha_i) = \zeta(T)\sigma_i \) to the terminal vertex of \( \alpha_i \). We then construct the refinement \( \hat{z} \) of \( z^* \) by leaving the value unchanged on the vertical 1–cells of \( \ell_\pm(T) \) (which are again vertical 1–cells of \( \hat{Y} \)), and for each \( 1 \leq i \leq k \) declaring

\[
\hat{z}(\alpha_i) = \rho_i(T) z^*(e_-(T))
\]

and

\[
\hat{z}(\beta_i) = z^*(\ell_+(T))(\rho_1(T) + \cdots + \rho_i(T)) + z^*(\ell_-(T))(\rho_{i+1}(T) + \cdots + \rho_k(T)).
\]

It is straightforward to see that this procedure defines a positive cocycle that refines \( z^* \) and thus also \( z \). See Figure 12 for an illustration of this refinement procedure.

Figure 12. A local picture of the subdivision and cocycle refinement procedure for a trapezoid \( T \) when \( e_+(T) \) consists of more than one skew 1–cell. The numbers along the 1–cells on the left represent the values of some positive cocycle \( z \) and the numbers along the 1–cells on the right represent the values of the refinement \( \hat{z} \). In this example, we have assumed for simplicity that the trapezoids above \( T \) are not subdivided. In general the values along the top will also be “distributed” among the 1–cells in the respective subdivisions.

Notice that skew ratios are essentially preserved under the standard refinement procedure:

**Lemma 8.12.** Let \( z \in Z^1(Y; \mathbb{R}) \) be a positive cocycle on a trapezoidal subdivision \( Y \) of \( X_f \). Then for the standard subdivision \( \hat{Y} \) and corresponding refinement \( \hat{z} \in Z^1(\hat{Y}; \mathbb{R}) \) we have

\[
\rho(\hat{Y}, \hat{z}) \leq \max\{\rho(Y, z), 1/2\}.
\]

**Proof.** First consider a trapezoid \( T^* \) of \( Y^* \). If \( T^* \) is a new trapezoid that was created while constructing the subdivision \( Y^* \), then its top arc \( e_+(T^*) \) necessarily consists of a single skew 1–cell of \( Y^* \) and so we have have \( \rho(T^*, z^*) = 0 \) in this case. Otherwise \( T^* = T_0 \) for some trapezoid \( T_0 \) of \( Y \) and we have \( \rho(T^*, z^*) = \rho(T_0, z) \) except in the case that the 1–chain \( e_+(T_0) = \zeta(T_0)(\sigma_1 + \cdots + \sigma_k) \)...
in $Y$ contains a $1$–cell $\sigma_1$ that becomes subdivided into two $1$–cells $\sigma_1'$ and $\sigma_1''$ in $Y^*$. In that case by (8.3) and Definition 8.10 we have
\[
z^*(\sigma_1') = z^*(\sigma_1'') = \frac{z(\sigma_1)}{2} = \frac{1}{2} \rho_1(T_0, z) \zeta(T_0) z(e_+(T_0)) = \frac{1}{2} \rho_1(T_0, z) \zeta(T^*) z(e_+(T^*)).
\]
If $k = 1$, so that $\rho_1(T_0, z) = 1$, then $\rho(T^*, z^*) = 1/2$, and otherwise it follows that $\rho(T^*, z^*) \leq \rho(T_0, z)$. Whence we have $\rho(T^*, z^*) \leq \max(\rho(Y, z), 1/2)$ for every trapezoid $T^*$ of $Y^*$.

Next suppose that $T$ is a trapezoid of $\tilde{Y}$ and that we have $e_+(T) = \zeta(T)(\alpha_1 + \cdots + \alpha_k)$ with $k \geq 2$. Notice that, by construction, the top arc $e_+(T)$ of $T$ consists of a single $1$–cell $\alpha$ of $Y^*$. Let $T^*$ be the trapezoid of $Y^*$ with $e_-(T^*) = \alpha$. Since the $1$–cell $\alpha$ evidently becomes subdivided in $\tilde{Y}$, by definition of the standard subdivision we must have $e_+(T^*) = \zeta(T^*)(\sigma_1 + \cdots + \sigma_k)$, as a $1$–chain in $Y^*$, where $h_{T^*}$ sends $\alpha_i$ to $\sigma_i$. From (8.4) we have
\[
\zeta(\alpha) = \rho(T^*, z^*) = \rho_1(T^*, z^*) = x(T^*) z(e_-(T^*)�(T_0, z)).
\]
By the refinement property, we also have $z^*(e_-(T^*)) = \zeta(\alpha) = \zeta(T) \zeta(e_+(T))$. Therefore
\[
\rho_1(T, \tilde{z}) = \frac{\zeta(\alpha)}{\zeta(T) \tilde{z}(e_+(T))} = \rho(T^*, z^*) \leq \rho(T^*, z^*) \leq \max(\rho(Y, z), 1/2)
\]
as required. \hfill \Box

Lemma 8.12, Lemma 8.9 and the definition of standard refinement now give the following:

**Lemma 8.13.** Let $Y_0$ be a trapezoidal subdivision of $X_f$ and $z_0 \in Z^1(Y_0; \mathbb{R})$ a positive cocycle. Consider the sequence of standard subdivisions $Y_0, Y_1, \ldots$ with corresponding cocycle refinements defined recursively by $Y_{n+1} = \tilde{Y}_n$ and $z_{n+1} = \tilde{z}_n$. Then the numbers
\[
S_n = \max\{z_n(\sigma) \mid \sigma \text{ is a skew } 1\text{–cell of } Y_n\}
\]
tend to zero as $n \to \infty$.

**Proof.** Let $\delta = \max(\rho(Y_0, z_0), 1/2) < 1$. Applying Lemma 8.12 inductively, we see that $\rho(T, z_n) \leq \delta$ for all trapezoids $T$ of $Y_n$ and for all $n \geq 0$. According to (8.3) and (8.4), whenever a skew $1$–cell $\sigma = e_-(T)$ of $Y_n$ becomes subdivided in $Y_{n+1}$, each resulting subcell $\sigma' \subsetneq \sigma$ satisfies
\[
z_{n+1}(\sigma') \leq \max(\rho(T), 1/2) z_n(e_-(T)) \leq \delta z_n(\sigma).
\]
By Lemma 8.9, for each $n$ there exists $m > n$ so that every $1$–cell of $Y_n$ has become subdivided in $Y_m$. The above inequality then implies $S_m \leq \delta S_n$ and the result follows. \hfill \Box

8.6. **An unconstrained refinement.** Our construction of the perturbed fibration $\eta_z : X_f \to \mathbb{S}^1$ associated to a primitive integral element $[z] \in \mathcal{A}$ will rely on finding a subdivision of $X_f$ and a positive refinement of $z$ in which every trapezoid enjoys the following property.

**Definition 8.14** (Unconstrained trapezoids). Let $Y$ be a trapezoidal subdivision of $X_f$ and let $z \in Z^1(Y; \mathbb{R})$ be a 1–cocycle. A trapezoid $T$ of $Y$ is said to be unconstrained by $z$ if
\[
\max\{0, z(e_-(T))\} \leq \min\{z(\ell_-(T)), z(\ell_+(T)) + z(e_+(T))\}.
\]
We note that when $z$ is positive, the above definition reduces to $z(e_-(T)) \leq z(\ell_-(T))$ since the cocycle condition $z(\partial T) = 0$ (see (8.2)) immediately yields
\[
0 < z(e_-(T)) = z(e_-(T)) + z(\ell_+(T)) = z(e_+(T)) + z(\ell_-(T)).
\]
Therefore, in this case a trapezoid is automatically unconstrained whenever $z(e_+(T)) < 0$. In particular, we see that trapezoids with $\zeta(T) = -1$ are unconstrained by every positive 1–cocycle.

We now employ the constructions from §3.8.3–8.5 to find such a refinement. For the proof, we recall that $X_f$ may contain some trapezoids $T$ for which one of the sides $\ell_\pm(T)$ degenerates to a single point (see Figure 7). Such trapezoids are said to be *degenerate*. 


Proposition 8.15. Let $Y_0$ denote the trapezoidal cell structure $X_f$ and let $z_0 = z \in Z^1(X_f; \mathbb{R})$ be a positive cocycle. Consider the sequence $Y_0, Y_1, \ldots$ of standard subdivisions defined recursively by $Y_{n+1} = \hat{Y}_n$ with corresponding cocycle refinements $z_{n+1} = \hat{z}_n$. Then there exist some $n \geq 0$ so that every trapezoid $T$ of $Y_n$ is unconstrained by $z_n \in Z^1(Y_n; \mathbb{R})$.

Proof. Let $D$ denote the set of degenerate trapezoids of $X_f$. Any $T' \in D$ has $\zeta(T') = -1$, and furthermore any trapezoid $T$ of a subdivision $Y_n$ which is contained in some $T' \in D$ also has $\zeta(T) = -1$. Therefore, any such $T$ is unconstrained by $z_n$ as the calculation following Definition 8.14 demonstrates. So we need only consider trapezoids $T$ not contained in any trapezoid in $D$.

Let $M > 0$ be the minimum of $z(\beta)$ over all vertical 1–cells of $X_f$. We claim that for $n \geq 0$ every vertical 1–cell $\beta$ of $Y_n$ that is not contained in the interior of some $T' \in D$ also has $z_n(\beta) \geq M$. This is true for $n = 0$ by definition of $M$; arguing by induction we assume it is true for some $n \geq 0$ and prove it for $n + 1$. The condition holds for all vertical 1–cells of $Y_{n+1}$ that are also vertical 1–cells of $Y_n$ by induction hypothesis. Thus it suffices to consider a new vertical 1–cell of $Y_{n+1}$ that is not contained in any trapezoid in $D$ and is not a 1–cell of $Y_n$. By construction, such a 1–cell can only arise as a vertical arc $\beta_i$ connecting $e_-(T)$ to $e_+(T)$ for some trapezoid $T$ of $Y_n$ that is not contained in any $T' \in D$. We then have $z_n(\ell_+(T)) \geq M$ since the 1–cells comprising these chains are not contained in the interior of any $T' \in D$. As $p_1(T) + \cdots + p_k(T) = 1$, equations (8.3) and (8.5) show that $z_{n+1}(\beta_i)$ is a convex combination of $z_n(\ell_+(T)) \geq M$ and $z_n(\ell_-(T)) \geq M$, and hence $z_{n+1}(\beta_i) \geq M$, as required.

By Lemma 8.13 we may now choose $n$ so that every skew 1–cell $\sigma$ of $Y_n$ satisfies $z_n(\sigma) < M$. For any trapezoid $T$ of $Y_n$ that is not contained in a trapezoid of $D$, we then have $z_n(\ell_+(T)) \geq M$ by the preceding paragraph. Therefore

$$z_n(e_-(T)) < M \leq z_n(\ell_-(T)),$$

showing that $T$ is unconstrained by $z_n$ and completing the proof.

8.7. Perturbed fibrations. We now utilize the trapezoidal subdivisions and cocycle refinements developed in §§8.3–8.6 to construct perturbed fibrations $\eta_z: X_f \to S^1$ for positive 1–cocycles representing primitive integral classes in $\mathcal{A}$. The proof will also utilize the local model neighborhoods introduced in §7. For any local model $\mathcal{M} \subset X_f$, we denote a lift to the universal covering $\pi: \mathbb{R} \to S^1$ of the restriction of $\eta_0$ to $\mathcal{M}$ by

$$\eta_{\mathcal{M}}: \mathcal{M} \to \mathbb{R}$$

and write $I_{\mathcal{M}} = \eta_{\mathcal{M}}(\mathcal{M})$.

Lemma 8.16. Let $z \in Z^1(X_f; \mathbb{R})$ be a positive cocycle representing an integral class $u \in \mathcal{A}$. Then there exists a map $\eta_z: X_f \to S^1$ and a finite covering $\mathcal{M}$ of $X_f(1)$ by local model neighborhoods with the following properties.

1. $(\eta_z)_* = u: \pi_1(X_f) \to \pi_1(S^1) = \mathbb{Z}$ in $H^1(X_f; \mathbb{R})$.

2. For each local model $\mathcal{M} \subset \mathcal{M}$, there is an orientation preserving injective local diffeomorphism $h_{\mathcal{M}}: I_{\mathcal{M}} \to \mathbb{R}$ so that the restriction $\eta_z|_{\mathcal{M}}$ satisfies

$$\eta_z|_{\mathcal{M}} = \pi \circ h_{\mathcal{M}} \circ \eta_{\mathcal{M}}.$$

3. The restriction of $\eta_z$ to any semiflow line is a local diffeomorphism and the restriction to the interior of each trapezoid is a submersion.

4. For some $x_0 \in S^1$, $\eta_z^{-1}(x_0) \cap X_f(1)$ consists of a finite set of points which flow into periodic orbits of $\psi$. Moreover, if $f$ is an expanding irreducible train track map, then all points of $\eta_z^{-1}(x_0) \cap X_f(1)$ eventually flow into vertical 1–cells of $X_f$. 


Part (2) of the lemma basically says that in each local model $M$, the map $\eta_z$ factors through the restriction to $M$ of $\eta_0$ (but to make this correct, we need to use $\eta_M$ instead of the restriction of $\eta_0$ to $M$ exactly). As a consequence of (2), we see that the fibers of $\eta_z$ are horizontal in $M$.

**Proof.** The map $\eta_z: X_f \to S^1$ will be defined so that for any 1–cell $e$, if we lift the restriction to the universal cover $\bar{\eta}_z|_e: e \to \mathbb{R}$, then the difference in the values at the endpoints (which is independent of the lift) is exactly $z(e)$. A calculation as in Equation (8.1) shows that any such map will satisfy conclusion (1) of the lemma. The plan is to first construct a map on the 1–skeleton $\eta_z^1: X_f^{(1)} \to S^1$ satisfying this property, so that the restriction to each 1–cell $e$ is a local diffeomorphism onto its image, and so that (4) is satisfied. Assuming that every trapezoid of $X_f$ is unconstrained by $z$, we may then extend $\eta_z^1$ over the 2–cells so that (3) is satisfied. Finally, we modify $\eta_z^1$ in a neighborhood of $X_f^{(1)}$ and construct the covering $\tilde{M}$ so that (2) is satisfied.

By Proposition 8.15, after passing to a trapezoidal subdivision $Y$ of $X_f$ and a corresponding refinement $z'$ of $z$, we may assume that every trapezoid of $Y$ is unconstrained by $z'$. Suppose we can prove the lemma for the cell structure $Y$ and corresponding refinement $z'$. The first assertion of (4) will then follow from the fact that $X_f^{(1)} \subset Y^{(1)}$. Furthermore, in the case that $f$ is an expanding irreducible train track map, all vertical 1–cells of $Y$ eventually flow into the vertical 1–cells of $X_f$ (see Definition 8.8), so the second assertion of (4) will follow as well. Since any finite cover of the 1–skeleton of $Y$ also covers the 1–skeleton of $X_f$, part (2) will follow, and (3) will follow similarly by using local models near the new vertical 1–cells. Finally, (1) does not make reference to the cell structure and so will follow automatically. Thus it suffices to prove the lemma for $Y$ and $z'$; by an abuse of notation we therefore continue to refer to this subdivision and refined cocycle simply as $X = X_f$ and $z' = z$, respectively.

Choose a maximal tree $Q \subset X_f^{(1)}$ and fix some vertex $v_0 \in Q$ to serve as a basepoint. Define a map $\hat{\eta}_z: Q \to \mathbb{R}$ so that $\hat{\eta}_z(v_0) = 0$ and so that the restriction to every 1–cell $e$ in $Q$ is an injective local diffeomorphism and so that

$$\hat{\eta}_z(t(e)) - \hat{\eta}_z(o(e)) = z(e).$$

Because $z$ represents an integral cohomology class, we see that for any 1–cell $e \in E_0$ which is not in $Q$, although this equation can fail, we still have

$$\hat{\eta}_z(t(e)) - \hat{\eta}_z(o(e)) - z(e) \in \mathbb{Z}.$$

Therefore, composing $\hat{\eta}_z$ with $\pi$, we obtain a map $\eta_z^1: Q \to S^1$ which can we can extend to all of $X_f^{(1)}$ with the property that for any 1–cell $e$, any lift $\tilde{\eta}_z|_e: e \to \mathbb{R}$ is an injective local diffeomorphism and

$$\tilde{\eta}_z|_e(t(e)) - \tilde{\eta}_z|_e(o(e)) = z(e).$$

We next modify $\eta_z^1: X_f^{(1)} \to S^1$ by a homotopy rel $X_f^{(0)}$, maintaining the property that $\eta_z^1$ is a local diffeomorphism on each edge, so that on a neighborhood $U$ of $X_f^{(0)}$ our map $\eta_z^1$ factors through the restriction of $\eta_0$ to $U$. More precisely, we arrange that each connected component $U_0$ of $U$ contains a single vertex of $X_f^{(0)}$ and that for any lift $\tilde{\eta}_0: U_0 \to \mathbb{R}$ of the restriction of $\eta_0$ to $U_0$ there exists a local diffeomorphism $h: \mathbb{R} \to \mathbb{R}$ so that

$$\eta_z^1|_{U_0 \cap X_f^{(1)}} = \pi \circ h \circ \tilde{\eta}_0|_{U_0 \cap X_f^{(1)}}.$$

This modification ensures that two points of $U_0 \cap X_f^{(1)}$ are identified by $\eta_z^1$ if and only if they are also identified by $\eta_0$.

After shrinking $U$ if necessary, we may then choose a point $x_0 \in S^1 \setminus \eta_z^1(U)$. Note that when $f: \Gamma \to \Gamma$ is an expanding irreducible train track map, the set $\bigcup_{k \geq 1} f^{-k}(VT)$ is dense in $\Gamma$ (see the proof of Theorem 3.2). Therefore, the set of points in $X_f$ that eventually flow into vertical...
that we construct below will agree with \( \eta \) eventually flow into periodic orbits of \( \psi \) (see Remark 6.21). More generally, if \( P \subset \Gamma \) is the set of periodic points for \( f \), then \( \bigcup_{k \geq 1} f^{-k}(P) \) is also dense (as can be seen from the linear structure of \( f \)), and hence the set of points of \( X_f \) that eventually flow into periodic orbits is always dense. Therefore, we may modify \( \eta'_z : X_f^{(1)} \to S^1 \) by a homotopy rel \( U \supset X_f^{(0)} \) so that \( (\eta'_z)^{-1}(x_0) \) (which is a finite subset of \( X_f^{(1)} \setminus U \)) consists of points that eventually flow into periodic orbits of \( \psi \) (and that furthermore flow into vertical 1–cells of \( X_f \) in the case that \( f \) is an expanding irreducible train track map). The extension \( \tilde{\eta}_z : X_f \to S^1 \) of \( \eta'_z \) that we construct below will agree with \( \eta'_z \) on \( X_f^{(1)} \) and will therefore satisfy condition (4).

We then extend \( \eta'_z \) over the 2–cells of \( X_f \) as follows. Consider a trapezoid \( T \) of \( X_f \), and let \( v \in X_f^{(0)} \) denote the common initial vertex of \( e_-(T) \) and \( \ell_-(T) \) (recall that \( e_-(T) \) is oriented from \( \ell_-(T) \) to \( \ell_+(T) \)). Lifting \( \eta'_z|_{\partial T} \) to the universal cover gives us a map \( \tilde{\eta}'_z|_{\partial T} : \partial T \to \mathbb{R} \) which, after composing with a translation, we may assume sends \( v \) to 0. By construction, \( \tilde{\eta}'_z|_{\partial T} \) then maps \( e_-(T) \) and \( e_+(T) \) locally diffeomorphically onto the intervals
\[
[0, z(e_-(T))] \quad \text{and} \quad [z(\ell_-(T)), z(\ell_-(T)) + z(e_+(T))],
\]
respectively (in the case \( \zeta(T) = -1 \), note that the endpoints of this latter interval have been written out of order). Since \( T \) is unconstrained by \( z \), these intervals have disjoint interiors. Therefore the map \( \tilde{\eta}'_z|_{\partial T} \) does not identify any interior point of \( e_-(T) \) with any interior point of \( e_+(T) \). Rather, \( \tilde{\eta}'_z|_{\partial T} \) identifies each point of \( e_-(T) \) with a point of \( \ell_+(T) \), and each point of \( e_+(T) \) with a point of either \( \ell_+(T) \) (in the case \( \zeta(T) = 1 \)) or \( \ell_-(T) \) (in the case \( \zeta(T) = -1 \)). It follows that we may extend \( \pi \circ \tilde{\eta}'_z|_{\partial T} \) to a map \( \eta'_z : \hat{T} \to S^1 \) whose fibers are transverse to the flow. Explicitly, identifying \( \hat{T} \) with the Euclidean trapezoid \( \hat{T} \) via the map \( \sigma_T : \hat{T} \to T \) provided by Proposition 6.23, we extend \( \tilde{\eta}'_z|_{\partial T} \) over \( \hat{T} \) so that the fibers are straight (Euclidean) lines in \( \hat{T} \) and define \( \eta'_z \) on \( \hat{T} \) as \( \pi \circ \tilde{\eta}'_z|_{\hat{T}} \). The unconstrained condition then ensures that each fiber has nonvertical slope and is therefore transverse to the foliation of \( \hat{T} \) by (vertical) flowlines. Extending \( \eta'_z \) over every trapezoidal 2–cell of \( X_f \) in this manner, we obtain the map \( \eta'_z : X_f \to S^1 \).

Notice that the fibers of \( \eta'_z \) are by construction transverse to \( X_f^{(1)} \). We may therefore modify \( \eta'_z \) by a homotopy rel the 1–skeleton to obtain a map \( \eta_z : X_f \to S^1 \) whose fibers remain transverse to the flow and are furthermore horizontal in a neighborhood \( W \) of \( X_f^{(1)} \). This map satisfies conclusions (1) and (3) of the lemma.

Finally to prove part (2), we construct the cover \( \mathcal{M} \) of \( X_f^{(1)} \) by local models. For each 0–cell \( v \) of \( X_f \) we use Proposition 7.6 to find a local model neighborhood \( M_v \) of \( v \) contained in \( U \cap W \). The local models \( M_v \) and \( M_v' \) are then disjoint for distinct 0–cells (since each component of \( U \) contains a single 0–cell). We next cover each edge by finitely many 1–cell local models that are each contained in \( W \) and let \( \mathcal{M} \) denote the resulting cover. Since each \( M \in \mathcal{M} \) is contained in \( W \), we see that the fibers of \( \eta_z|_{\mathcal{M}} \) are necessarily horizontal. This implies that two points of \( \mathcal{M} \) are identified by a lift \( \tilde{\eta}_z|_{\mathcal{M}} \) if and only if they are also identified by \( \eta_z|_{\mathcal{M}} \). Therefore the maps \( \tilde{\eta}_z|_{\mathcal{M}} \) and \( \eta_z^{-1}|_{\mathcal{M}} \) may be composed to yield a well defined map
\[
h_{\mathcal{M}} = \tilde{\eta}_z|_{\mathcal{M}} \circ \eta_z^{-1}|_{\mathcal{M}} : I_{\mathcal{M}} \to \mathbb{R}.
\]
This map \( h_{\mathcal{M}} \) is a local diffeomorphism (as can be seen by restricting to a flowline in \( \mathcal{M} \)) and thus satisfies conclusion (2) of the lemma. \( \square \)

**Remark 8.17.** Alternatively, one could work with continuous 1–forms on \( X \) as described in [FGS]. We do not need any of the technical machinery developed in that setting here, and our situation requires other special considerations, so we decided to avoid adding another layer of terminology.
Definition 8.18 (Associated fibrations and the graph $\Theta_z$). Let $u \in H^1(X_f; \mathbb{R})$ be an integral class represented by a positive 1–cocycle $z \in Z^1(X_f; \mathbb{R})$. A map $\eta_z : X_f \to S^1$ satisfying the conclusions of Lemma 8.16 will be called an associated fibration for $z$. For any point $x \in S^1$, let $\Theta_{x,z} = \eta_z^{-1}(x)$ be the full preimage of $x$. By the second and third condition of Lemma 8.16, the fiber $\Theta_{x,z}$ is a finite topological graph with vertex set equal to the intersection with $X_f^{(1)}$. The associated graph $\Theta_z$ for this fibration is defined by choosing a point $x_0 \in S^1$ as in part (4) and letting $\Theta_z := \Theta_{x_0,z}$ as a topological space; as topological graph we equip $\Theta_z$ with the vertex set

$$V \Theta_z = \left( \bigcup_{s \geq 0} \psi_s(V \Theta_{x_0,z}) \right) \cap \Theta_{x_0,z}.$$ 

According to part (4), $V \Theta_{x_0,z}$ flows into periodic orbits of $\psi$, and hence $\Theta_z$ is indeed a finite subdivision of $\Theta_{x_0,z}$. Note that by construction, every edge of $\Theta_z$ is contained in a trapezoidal 2–cell of $X_f$ (since this is already true for $\Theta_{x_0,z}$).

Let $u, z, \eta_z$ and $\Theta_z$ be as in Definition 8.18 above. To understand the graph $\Theta_z$, we need to study some general properties of the graphs $\Theta_{x,z}$ (where $x \in S^1$ is arbitrary) and how they transform under $\psi$. By the third condition of Lemma 8.16, we can reparametrize the semiflow $\psi_s$ so that the composition $\mathbb{R}_+ \to S^1$ of any semiflow line with the projection to the circle has unit speed. We denote this reparametrization by $\psi_s^z$. With this reparametrization we have

$$\psi_s^z(\Theta_{x,z}) = \Theta_{x+s,z},$$

where $s \in \mathbb{R}$ and $x + s \in S^1 = \mathbb{R}/\mathbb{Z}$. By Lemma 8.16 (2), given a local model $\mathcal{M} = \mathcal{M}(K, s_0) \in \mathbb{M}$, there exists $s_0^z$ so that

$$\mathcal{M} = \bigcup_{0 \leq s \leq s_0^z} \psi_s^z(K).$$

Furthermore, there is a homeomorphism $h_{K,z} : [0, s_0] \to [0, s_0^z]$ so that

$$\psi_s(K) = \psi_{h_{K,z}(s)}(K).$$

Lemma 8.19. For any $x \in S^1$ there exists $x' \in S^1$ and $s_x > 0$ so that $x = x' + s_x/2$ and for all $0 \leq s \leq s' \leq s_x$, the map

$$\psi_{s-s'} : \Theta_{x+s,z} \to \Theta_{x'+s',z}$$

is a homotopy equivalence.

Proof. For any $x' \in S^1$ and $0 < s' < 1/2$ let

$$N(x', s') = \bigcup_{0 \leq s \leq s'} \psi_s^z(\Theta_{x',z}) = \eta_z^{-1}([x', x' + s']).$$

Now cover the intersections of $\Theta_{x,z}$ with $X_f^{(1)}$ by the flow-interiors of local models. By replacing the local models $\mathcal{M} \in \mathbb{M}$ by smaller local models if necessary, we can assume that $\Theta_{x,z}$ does not intersect the top or bottom of any $\mathcal{M}$ and that for all $\mathcal{M} \neq \mathcal{M}' \in \mathbb{M}$, we have

$$\Theta_{x,z} \cap \mathcal{M} \cap \mathcal{M}' = \emptyset.$$

Then we can choose $x'$ and $s_x < 1/2$ so that $x = x' + s_x/2$ and for any local model $\mathcal{M} = \mathcal{M}(K, s_0)$ there exist $0 < s_1^M < s_2^M < \ldots < s_r^M < s_0^z$ (with $r = r(\mathcal{M})$) so that

$$N(x', s_x) \cap \mathcal{M} = \bigcup_{j=1}^r \left( \bigcup_{0 \leq s \leq s_x} \psi_s^x(K) \right).$$
Furthermore, by choosing \( s_x \) sufficiently small we can also guarantee that
\[
N(x', s_x) \cap M \cap M' = \emptyset
\]
for all \( M \neq M' \in M \).

Now applying Proposition 7.6 (and reparametrizing) it follows that for all \( 0 \leq s \leq s' \leq s_x \) and all \( M \in M \), we have
\[
\psi_{s'-s}^z: \Theta_{x'+s,z} \cap M \to \Theta_{x'+s',z} \cap M
\]
is controlled rel boundary. Any component of the complement
\[
U \subset N(x', s_x) \setminus \bigcup_{M \in M} M
\]
is entirely contained in some trapezoid \( T \). In \( T \) the semiflow is a flow, and so the restriction
\[
\psi_{s'-s}^z: \Theta_{x'+s,z} \cap U \to \Theta_{x'+s',z} \cap U
\]
is a homeomorphism.

It follows that \( \psi_{s'-s}: \Theta_{x'+s,z} \to \Theta_{x'+s',z} \) is locally controlled, and so by Proposition 7.5 it is a homotopy equivalence.

Corollary 8.20. For any \( x \in S^1 \) and \( s \in \mathbb{R} \) we have that
\[
\psi_z^x: \Theta_{x,z} \to \Theta_{x+s,z}
\]
is a homotopy equivalence. In particular, the first return map
\[
f_z = \psi_z^1: \Theta_z \to \Theta_z
\]
is a homotopy equivalence. Furthermore, \( f_z(V \Theta_z) \subset V \Theta_z \).

Proof. We can realize \( \psi_z^x \) as the composition \( \psi_z^x = \psi_z^x \circ \ldots \circ \psi_z^x \), where the restriction \( \psi_z^x: \Theta_{x',z} \to \Theta_{x'+z',z} \) is a homotopy equivalence given by Lemma 8.19 for some \( x_1, \ldots, x_k \) with \( x_1 = x \). This proves the first (and hence also the second) statement. The last statement follows from the definition of \( V \Theta_z \) (see Definition 8.18 ) since \( f_z \) is the first return map of \( \psi \). \( \square \)

As a consequence we have the following Corollary (cf. [Gau1, Theorem 3.1] and [Wan, Lemma 4.1.3]).

Corollary 8.21. For any primitive integral element \( u \in \mathcal{A} \) represented by a positive 1–cocycle \( z \) with associated fibration \( \eta_z \), the fiber \( \Theta_z \) is connected and the induced map \( \pi_1(\Theta_z) \to \pi_1(X_f) = G \) is an isomorphism onto the kernel \( \ker(u) \) of \( u = (\eta_z)_*: G \to \mathbb{Z} \).

Proof. The flow \( \psi_z^x: \Theta_{x,z} \to \Theta_{x+s,z} \) is a homotopy equivalence for all \( x, s \), so the number of components \( n \) of \( \Theta_{x,z} \) is constant, independent of \( x \). Construct the quotient \( F: X \to X/\sim \), where \( \sim \) is the equivalence relation whose equivalence classes are precisely the connected components of \( \Theta_{x,z} \) for \( x \in S^1 \). There is a larger equivalence relation \( \sim' \) whose equivalence classes are the sets \( \Theta_{x,z} \) for \( x \in S^1 \), and this quotient \( X/\sim' \) is just \( S^1 \) itself. The quotient \( X \to S^1 \) factors as \( X \to X/\sim \to S^1 \), and the \( X/\sim \to S^1 \) is everywhere \( n \)-to-1. In fact, this map is an \( n \)-fold covering map, \( X/\sim = S^1 \to S^1 \). Therefore, the homomorphism \( u: G \to \mathbb{Z} \) factors through the induced map of this cover \( F_*: G \to \pi_1(X/\sim) \). But the induced map from \( X/\sim \to S^1 \to S^1 \) is multiplication by \( \pm n \), and hence \( u = \pm nF_* \). Since \( u \) is primitive, it follows that \( n = 1 \), so \( \Theta_{x,z} \) is connected for all \( x \).

For the second statement, apply van Kampen’s Theorem to calculate \( \pi_1(X_f) \) as a semi-direct product \( \pi_1(\Theta_x) \rtimes \mathbb{Z} \), and observe that the projection onto \( \mathbb{Z} \) is \( (\eta_z)_* \). \( \square \)
8.8. \( E_0 \)-class and the proof of Theorem B. In this section we will establish Theorem B from the Introduction. Recall that for any \( \varphi \in \text{Out}(F_N) \), where \( N \geq 2 \), given a tame linear graph-map \( f : \Gamma \to \Gamma \) which is a topological representative and given a metric structure \( \mathcal{L} \) on \( \Gamma \), compatible with the underlying linear structure on \( \Gamma \), and given some folding sequence as in (4.1), we have constructed the corresponding folded mapping torus \( X_f \) for \( \varphi \). As noted in Remark 4.2, for any \( \varphi \in \text{Out}(F_N) \) there exists a tame representative \( f \) as above.

Recall also that in Definition 7.7 we defined a subgraph \( E_0 \) of \( X_f^{(1)} \) and that in Definition 7.9 we defined the \( E_0 \)-class \( \epsilon \in H_1(X_f; \mathbb{R}) \).

We now prove:

**Theorem B.** Let \( \varphi \in \text{Out}(F_N) \) (where \( N \geq 2 \)), \( X_f \) be a folded mapping torus for \( \varphi \), with the associated semiflow \( \psi \), positive cellular \( \psi \)–class \( \epsilon \) \( \in H_1(X_f; \mathbb{R}) \). Given a positive cellular 1–cocycle \( z \in Z^1(X_f; \mathbb{R}) \) representing a primitive integral element \( u \in A_{X_f} \subset H^1(X_f; \mathbb{R}) = H^1(G_\varphi; \mathbb{R}) \), there exists a map \( \eta_z : X_f \to S^1 \) and a fiber \( \Theta_z = \eta_z^{-1}(x_0) \) for some \( x_0 \in S^1 \) so that

1. \( \Theta_z \) is a finite connected topological graph such that the inclusion \( \Theta_z \subset X_f \) is \( \pi_1 \)-injective and such that \( \pi_1(\Theta_z) = \ker(u) \leq \pi_1(X_f) = G_\varphi \).
2. \( u(e) = \chi(\Theta_z) = 1 - \text{rk}(\ker(u)) \).
3. \( \Theta_z \) is a section of \( \psi \).
4. the first return map \( f_z : \Theta_z \to \Theta_z \) of \( \psi \) is a homotopy equivalence and \( (f_z)_* \) represents \( \varphi u \in \text{Out}(\ker(u)) \).

**Proof.** The existence of \( \eta_z \) comes from Lemma 8.16, and property (1) is a consequence of Corollary 8.21. Property (3) is immediate and (4) follows from Corollary 8.20.

All that remains is to prove (2). Since \( \chi(\Theta_z) = 1 - \text{rk}(\ker(z)) \), to establish (2) it suffices to prove \( u(e) = \chi(\Theta_z) \).

Write \( e = \sum_{c \in E_0} c e \in Z_1(X_f; \mathbb{R}) \) where \( c e = (2 - d(e))/2 \). Let \( x \) be any point not in the \( \eta_z \)–image of the zero-skeleton \( X_f^{(0)} \). Since \( (\eta_z)_* = u \) and \( z \) is a cocycle that represents \( u \), we can calculate \( z(e) \) by pushing \( e \) forward by \( \eta_z \), and pairing this 1–cocycle on \( S^1 \) with the Poincaré dual of the fundamental class. This class is represented in deRham cohomology, \( H^1(S^1; \mathbb{R}) = H^1_{dR}(S^1; \mathbb{R}) \) by any 1–form \( \omega \) on \( S^1 \) with total volume 1. Pick such a 1–form \( \omega \) with support contained in an interval about \( x \) disjoint from \( \eta_z(X_f^{(0)}) \).

Next, recall that the restriction of \( \eta_z \) to any \( e \in E_0 \) is an orientation preserving local diffeomorphism. In particular, we can consider the restriction of \( \eta_z \) to \( e \) as a smooth, singular 1–cell in \( S^1 \) which we denote \( e_z \). By our choice of \( \omega \) and since \( \eta_z \) is orientation preserving on \( e \), we have

\[
\int_{e_z} \omega = \left| \eta_z^{-1}(x) \cap e \right|.
\]

Thus, from the previous paragraph we have

\[
z(e) = \sum_{c \in E_0} c \int_{e_z} \omega = \frac{1}{2} \sum_{c \in E_0} (2 - d(e)) \left| \eta_z^{-1}(x) \cap e \right|
\]

Now observe that \( \eta_z^{-1}(x) \cap E_0 \) is precisely the set of vertices of \( \Theta_{e,z} \) of valence greater than 2. Indeed, if \( y \in \eta_z^{-1}(x) \cap e \), then the valence \( \text{val}(y) \) in \( \Theta_{x,z} \) is precisely \( d(e) \). Therefore, from this fact and the previous equation we have

\[
z(e) = \frac{1}{2} \sum_{y \in \Theta_{x,z}} (2 - \text{val}(y)) = \chi(\Theta_{x,z}).
\]
By definition, $\Theta_z$ is a subdivision of $\Theta_{x_0,z}$ for some $x_0$ not in the image of $X_f^{(0)}$. Hence $z(\epsilon) = \chi(\Theta_{x_0,z}) = \chi(\Theta_z)$, as required. 

9. Train track maps and full irreducibility

Recall that if $\varphi \in \text{Out}(F_N)$ is represented by an expanding irreducible train-track map $f: \Gamma \to \Gamma$, then given any metric structure $L$ on $\Gamma$, compatible with the underlying linear structure of $\Gamma$, and given a folding sequence as in (4.1), we can construct the corresponding folded mapping torus $X_f$ for $\varphi$.

In this section we prove Theorem C from the Introduction:

**Theorem C.** Let $\varphi \in \text{Out}(F_N)$ (where $N \geq 2$) be an outer automorphism represented by an expanding irreducible train track map $f: \Gamma \to \Gamma$, let $X_f$ be the folded mapping torus, and $\psi$ the associated semiflow. Let $u \in \mathcal{A}_{X_f} \subset H^1(G_{\varphi}; \mathbb{R}) = H^1(X_f; \mathbb{R})$ be a primitive integral element which is represented by a positive 1-cocycle $z \in Z^1(X_f; \mathbb{R})$, and let $\Theta_z \subset X_f$ be the topological graph from Theorem B so that the first return map $f_z: \Theta_z \to \Theta_z$ is a homotopy equivalence representing $\varphi_u$. Then:

1. The map $f_z: \Theta_z \to \Theta_z$ is a topological graph-map (in the sense of Definition 2.1 below).
2. There exists a linear graph structure (in the sense of Subsection 2.2) on $\Theta_z$ with respect to which $f_z$ is an expanding irreducible train-track map.
3. If we additionally assume that $\varphi$ is hyperbolic and fully irreducible, then $\varphi_u \in \text{Out}(\ker(u))$ is also hyperbolic and fully irreducible.

**Convention 9.1.** For the remainder of the section, for the purposes of proving parts (1) and (2) of Theorem C, we assume that $f: \Gamma \to \Gamma$ is an expanding irreducible train track map representing $\varphi \in \text{Out}(F_N)$. Note that by Lemma 2.10 the map $f$ is tame. We equip $\Gamma$ with the canonical eigenmetric and the corresponding linear structure, following Convention 4.5, and then construct the corresponding folding line and the folded mapping torus $X_f$.

We do not assume $\varphi$ is hyperbolic and fully irreducible until specifically stated; see Convention 9.7.

The proof of Theorem C, will be given after establishing a sequence of lemmas. To begin, we choose a positive cocycle $z$ representing a primitive integral class $u \in \mathcal{A} = A_{X_f}$ and an associated fibration $\eta_z$ defining the finite connected topological graphs $\Theta_z$ and $\Theta_{x,z}$ for all $x \in S^1$—see Definition 8.18. Recall that the time 1 map $\psi_1^z$ of the reparametrized flow is the first return map for $\Theta_z$ and is denoted $f_z: \Theta_z \to \Theta_z$.

From Corollary 8.20, $f_z$ is a homotopy equivalence and $f_z(V\Theta_z) = V\Theta_z$.

By Corollary 8.21, the inclusion induces an isomorphism $\pi_1(\Theta_z) \cong \ker(u)$, which we use to identify $\ker(u) = \pi_1(\Theta_z)$. Then $f_z$ induces the monodromy $(f_z)_* = \varphi_u \in \text{Out}(\ker(u))$.

Thus $f_z$ satisfies all the requirements of being a topological representative of $\varphi_u$ (in the sense of Definition 2.14) except that we don’t know yet that $f_z$ is a topological graph-map. We will show that $f_z$ is a topological graph-map, and that, with respect to an appropriate linear structure on $\Theta_z$, the map $f_z$ is an expanding irreducible train track map. When $\varphi$ is fully irreducible, we will find that $f_z$ is moreover a weakly clean train track map. The fact that $\varphi_u$ is fully irreducible will then follow from Corollary 5.4.

We begin our analysis of $f_z$ with the following technical lemma.

**Lemma 9.2.** Suppose $\alpha: (-\delta, \delta) \to \sigma$ is an arc in the interior of a 2–cell $\sigma$ of $X_f$ transverse to flow $\psi_s$. Then the map

$$\Psi_\alpha: (-\delta, \delta) \times \mathbb{R}_{\geq 0} \to X_f$$

defined by $\Psi_\alpha(t, s) = \psi_s(\alpha(t))$ is locally injective.
Proof. The 2–cell $\sigma$ is a trapezoid whose bottom edge is an arc in a skew 1–cell of the old cell structure, which in turn lives in the strip $\{\psi_s(c_0) : 0 \leq s \leq 1\}$ over an edge $c_0$ of $\Gamma_0$. Since $\Gamma_0$ is a subdivision of $\Gamma$, we see that there is an edge $e \in ET$ so that $\alpha(-\delta,\delta)$ is contained in $\{\psi_s(e) : s \geq 0\}$. If we take a characteristic map $j : [0,1] \rightarrow X_f$ for $e$, it therefore suffices to show that

$$\Psi_j : (0,1) \times \mathbb{R}_{\geq 0} \rightarrow X_f$$

is locally injective. For this, observe that by composing with $\eta_0$, it follows that if $\Psi_j(s,t) = \Psi_j(s',t')$ then $t - t'$ is an integer. Given a point $(s_0,t_0)$, choose a neighborhood of the form $W = U \times (t_0 - \frac{1}{2},t_0 + \frac{1}{2})$. If $\Psi_j(s,t) = \Psi_j(s',t')$ for $(s,t), (s',t') \in W$, then $t = t'$.

To find $U$, we proceed as follows. Let $T > t_0 + \frac{1}{2}$ be an integer. Since $f$ is a train track map, there is a neighborhood $U$ of $s_0$ so that $f^T|_U$ is injective. Suppose $s,s' \in U$ and $|t - t_0| < \frac{1}{2}$ is such that $\Psi_j(s,t) = \Psi_j(s',t)$. Then $\psi_t(e(s)) = \psi_t(e(s'))$. Since $t < T$, we have $T - t > 0$ and the semiflow property implies

$$f^T(e(s)) = \psi_T(e(s)) = \psi_{T-t}(\psi_t(e(s)))$$

$$= \psi_{T-t}(\psi_t(e(s'))) = \psi_T(e(s')) = f^T(e(s')).$$

Therefore, $s = s'$ and $\Psi_j$ is injective on $W$. Since $(s_0,t_0)$ was arbitrary, $\Psi_j$ is locally injective. □

Now suppose $\psi^*_\alpha$ is the reparametrizations of the semiflow $\psi_\alpha$ coming from a positive perturbation $z$ of $z_0$. We can define a map $\Psi^*_\alpha(t,s) = \psi^*_\alpha(\alpha(t))$ as in the lemma. Because $\psi^*_\alpha$ is a reparametrization of $\psi_\alpha$, it follows that $\Psi^*_\alpha = \Psi_\alpha \circ H$ for some homeomorphism

$$H : (-\delta,\delta) \times \mathbb{R}_{\geq 0} \rightarrow (-\delta,\delta) \times \mathbb{R}_{\geq 0}$$

(determined by the reparameterization). Thus, the conclusion of the lemma remains true for $\Psi^*_\alpha$ in place of $\Psi_\alpha$. In particular, since edges of $\Theta_z$ are arcs in the interiors of 2–cells of $X_f$, this implies the following.

**Lemma 9.3.** For each $n \geq 1$ the map $f^n_{\alpha} : \Theta_z \rightarrow \Theta_z$ is locally injective on the interior of each edge of $\Theta_z$. Moreover, $f_z$ is a regular topological graph map.

Proof. The first statement follows immediately from the above discussion of the map $\Psi^*_\alpha$. To see the second statement, first recall that by Corollary 8.20, we have $f_{\alpha}(V\Theta_z) \subset V\Theta_z$. Let $e$ be an edge of $\Theta_z$ and let $j : [0,1] \rightarrow \Theta_z$ be such that $j(0) = o(e)$, $j(1) = t(e)$ and $j|_{[0,1]}$ is a homeomorphism onto $e$. To show that $f_z$ is a topological graph map, we must check that $f_z \circ j$ is a topological edge-path in $\Theta_z$. The regularity of $f_z$ will then follow immediately from local injectivity on edges.

The set $(f_z \circ j)^{-1}(V\Theta_z)$ of points that map to vertices of $\Theta_z$ is a closed, and hence compact, subset of $[0,1]$. Therefore, by the local injectivity of $f_z \circ j$ and finiteness of $V\Theta_z$, the set is finite and we may write its points as $0 = c_0 < \cdots < c_n = 1$. Now consider a subinterval $I = (c_{i-1},c_i)$. Since $(f_z \circ j)(I)$ is disjoint from $V\Theta_z$, this image must be contained in a single edge $e'$ of $\Theta_z$. Moreover, the Intermediate Value Theorem implies that $(f_z \circ j)|_I$ maps onto $e'$. Therefore, by the local injectivity, $(f_z \circ j)|_I$ is a homeomorphism onto $e'$, as required. □

We next desire to construct a linear structure on $\Theta_z$ and to establish the necessary combinatorial properties of $f_z$. To this end we introduce the following notation.

Each edge $e$ of $\Theta_z$ lives in trapezoid of $X_f$ whose bottom is an arc of a skew 1–cell of the old cell structure. Therefore, there exists an arc $\lambda_e$ contained in an edge of $\Gamma$ so that a reparametrization of the flow maps $\lambda_e$ homeomorphically onto $e$. More precisely, there exists a continuous function $\tau_e : \lambda_e \rightarrow \mathbb{R}_{\geq 0}$ so that the map $\rho_e : \lambda_e \rightarrow X_f$ defined by $\rho_e(y) = \psi_{\tau_e(y)}(y)$ sends $\lambda_e$ homeomorphically onto $e$. If we then choose an integer $m_e \geq \max\{\tau_e(\lambda_e)\}$ and define $s_e : e \rightarrow [0,m_e]$ by
We now show that all Whitehead graphs of irreducible train-track map, as required. Furthermore assume that the element $f \in \text{Out}(F_N)$ is hyperbolic and fully irreducible.

By Corollary 5.4 we now know that $f$ is a clean train track map. Thus the Whitehead graph $\text{Wh}(f,v)$ associated to each vertex $v$ of $\Gamma$ is connected and $A(f)^m$ is positive for some $m \geq 1$. We now show that all Whitehead graphs of $f : \Theta \to \Theta$ are connected as well.

Recall that $\Gamma_t = \eta_0^{-1}(t)$ denotes the horizontal fiber of $X_f$ at height $t \in [0, 1]$, and that $\Gamma_0 = \Gamma$. For any point $x \in \Gamma_t$, we define the corresponding $\z$-modified Whitehead graph $\text{Wh}^z(\Gamma_t, x)$ as
follows. If \( x \) lies in the interior of an edge of \( \Gamma_t \), then subdivide that edge at \( x \). The vertices of \( \text{Wh}^z(\Gamma_t, x) \) are as usual the set of “directions” at \( x \), that is the set of edges in the (subdivided) graph that originate at \( x \). Two such edges \( e_1, e_2 \) are adjacent in \( \text{Wh}^z(\Gamma_t, x) \) if there exists an edge \( e \) of \( \Theta_2 \) and a power \( n \geq 0 \) so that the edge-path \( \psi_t \circ f^n \circ \rho'_e(e) \) takes the corresponding turn \( e_1, e_2 \); in this case we call \( e_1, e_2 \) a \( z \)-taken turn.

**Lemma 9.8.** The \( z \)-modified Whitehead graph \( \text{Wh}^z(\Gamma_t, x) \) is connected for all \( t \in [0, 1] \) and \( x \in \Gamma_t \).

**Proof.** We first claim that \( \text{Wh}^z(\Gamma_0, x) \) is connected for each \( x \in \Gamma_0 \). Indeed, for every edge \( e \) of \( \Theta_2 \) there exists an \( n \geq 1 \) so that the path \( f^n \circ \rho'_e(e) \) crosses every edge of \( \Gamma_0 = \Gamma \). This follows from the positivity of \( A(f)^n \) for large \( n \) together with the facts that \( f \) is expanding on all scales and \( \rho'_e(e) \) contains an open neighborhood in \( \Gamma \). This shows that \( \text{Wh}^z(\Gamma_0, x) \) is connected whenever \( x \) lies in the interior of an edge of \( \Gamma_0 \). On the other hand, when \( x \) is a vertex of \( \Gamma_0 \) it is easy to see that \( \text{Wh}^z(\Gamma_0, x) = \text{Wh}(f, x) \), which we already know is connected. Indeed, since \( f^n \circ \rho'_e(e) \) crosses every edge of \( \Gamma_0 \), whenever \( k \geq 1 \) and \( e \in E\Gamma_0 \) are such that \( f^k(e) \) takes a turn at \( x \), then \( f^{n+k} \circ \rho'_e(e) \) takes the same turn at \( x \).

Now let \( t > 0 \) and let \( x \) be any point of \( \Gamma_t \). Let \( P = (\psi_t)^{-1}(x) \subset \Gamma_0 \) be the preimage. Notice that \( \psi_t \) maps each \( z \)-taken turn at \( p \in P \) to a \( z \)-taken turn at \( x \); that is, \( \psi_t \) induces a map of \( z \)-modified Whitehead graphs \( \psi_t: \text{Wh}^z(\Gamma_0, p) \rightarrow \text{Wh}^z(\Gamma_t, x) \) for each \( p \in P \). Indeed, each edge \( e_1 \) originating at \( p \) is mapped to an edge \( \psi_t(e_1) \) originating at \( x \); and if \( e \in \Theta_2 \) is an edge such that \( f^n \circ \rho'_e(e) \) takes a turn \( e_1, e_2 \) at \( p \in P \), then \( \psi_t \circ f^n \circ \rho'_e(e) \) takes the turn \( f_t(e_1), f_t(e_2) \) at \( x \).

Let \( T \subset X_f \) denote the union of the flow lines \( \psi_{s,t}(p) \) for the points \( p \in P \) (i.e., \( T \) is the set \( \{ \psi_s(p) \mid s \in [0, t], p \in P \} \)). Then \( T \) is an oriented trivalent tree with \( |P| \) leaves on the bottom and one point \( x \) at the top. Each point \( y \in T \) lives in some \( \Gamma_s \) and has a corresponding \( z \)-modified Whitehead graph \( \text{Wh}^z(\Gamma_s, y) \). The fact that \( \text{Wh}^z(\Gamma_t, x) \) is connected will follow from the following claim.

**Claim:** \( \text{Wh}^z(\Gamma_s, w) \) is connected for each \( w \in T \).

We have already demonstrated this for the \( |P| \) points at the base of the tree. If \( w \in \Gamma_s \) lies in the interior of an edge of \( T \), and \( y \in \Gamma_r \), with \( r < s \), lies in the same edge, then the flow \( \psi_{s-r} \) induces a quotient map \( \text{Wh}^z(\Gamma_r, y) \rightarrow \text{Wh}^z(\Gamma_s, w) \) (the fact that \( y \) and \( w \) lie in the same edge of \( T \) implies that \( y \) does not get identified with any other points in the interval \( [r, s] \)). In particular, \( \text{Wh}^z(\Gamma_s, w) \) is connected provided \( \text{Wh}^z(\Gamma_r, y) \) is.

Now suppose that \( 2 \) upward-oriented edges \( b_1, b_2 \) of \( T \) meet at a point \( w \in \Gamma_s \). Restricting to a sufficiently small time interval \( [r, s] \), we may assume that there is a constant \( z \)-modified Whitehead graph \( G_1 \) along each \( b_i \). By induction on the combinatorial distance to \( P \) within \( T \) we may suppose that each \( G_1 \) is connected. Let \( e_1, e_2 \in E\Gamma_r \) denote the two edges of \( \Gamma_r \) whose initial segments are folded together by \( r_{s-r}: \Gamma_r \rightarrow \Gamma_s \). The closures of these edges necessarily contain the points \( y_1, y_2 \in \Gamma_r \cap T \) for which \( \psi_{s-r}(y_1) = \psi_{s-r}(y_2) = w \). The initial segment \( \alpha \) of \( e_i \) (oriented from \( y \) to \( o(e_i) \)) then corresponds to a vertex in \( G_i = \text{Wh}^z(\Gamma_r, y_i) \). Since \( \alpha_1 \) and \( \alpha_2 \) are folded together by \( \psi_{s-r} \), we see that the induced map \( \psi_{s-r} \) on \( z \)-modified Whitehead graphs identifies these two vertices. Therefore \( \text{Wh}^z(\Gamma_s, w) \) is the wedge of the connected graphs \( G_1 \) and \( G_1 \) and in particular is connected. \( \square \)

**Corollary 9.9.** The Whitehead graphs of all vertices of \( \Theta_2 \) with respect to \( f_z: \Theta_2 \rightarrow \Theta_2 \) are connected.

**Proof.** Recall that \( V\Theta_2 \) is defined to be the set of intersection points of \( \Theta_2 \) with \( X_f(1) \), together with some additional degree-2 vertices obtained by subdividing at points of intersection of the flow lines through this first set of points—see Definition 8.18.

Let \( v \) be a vertex of \( \Theta_2 \). Let us first suppose that \( v \) is not contained in a skew 1–cell of \( X_f \). One may then find a neighborhood \( U \subset X_f \) of \( v \) and a time \( t \) such that the flow \( \psi \) maps
Γ_t ∩ U homeomorphically onto Θ_z ∩ U. Let x be the point of Γ_t ∩ U that flows onto v. From the definition of z-modified Whitehead graphs, we see that the flow induces a graph isomorphism Wh^z(Γ_t, x) → Wh_θ_z(f_z, v). Therefore Wh_θ_z(f_z, v) is connected by Lemma 9.8.

Now suppose that v lies on a skew 1–cell. In this case we can find a neighborhood U ⊂ X_f of v so that U ∩ Θ_z is a tree with one vertex v and 3 edges, and a time t so that U ∩ Γ_t consists of 2 disjoint edges. Moreover, each component of U ∩ Γ_t contains a point x_t that flows onto v. By Lemma 9.8, we know that each graph Wh^z(Γ_t, x_t) is connected (in this case just a single edge with two vertices). The flow now induces a quotient map

\[ Wh^z(Γ_t, x_1) ∪ Wh^z(Γ_t, x_2) → Wh_θ_z(f_z, v) \]

that takes a vertex from each Wh^z(Γ_t, x_t) and identifies these to a single vertex in Wh_θ_z(f_z, v). Therefore Wh_θ_z(f_z, v) is the wedge of 2 line segments and is in particular connected. □

Corollary 9.10. The map f_z : Θ_z → Θ_z is a weakly clean train-track map.

Proof. We already know by Lemma 9.6, that f_z : Θ_z → Θ_z is an expanding train track map with an irreducible transition matrix A(f_z). Corollary 9.9 implies that the Whitehead graphs Wh_θ_z(f_z, v) are connected for all v ∈ V Θ_z. Thus f_z is a weakly clean train-track map. □

Proof of Theorem C. Suppose first that f : Γ → Γ is an expanding irreducible train-track map representing ϕ, without assuming that ϕ is hyperbolic and fully irreducible. Recall that u ∈ A is a primitive integral element, that z ∈ Z^1(X_f; R) is a positive 1–cocycle representing the cohomology class u and that f_z : Θ_z → Θ_z induces the monodromy (f_z)_* = ϕ_u ∈ Out(ker(u)) = Out(π_1(Θ_z)). Lemma 9.3 shows that f_z is a topological graph-map and thus f_z is a topological representative of the automorphism ϕ_u of ker(u) = π_1(Θ_z). Corollary 9.5 implies that there exists a linear structure Λ on Θ_z so that f_z : Θ_z → Θ_z is an expanding (linear) graph-map with A(f_z) irreducible. Lemma 9.3 also shows that f_z^n(e) is a tight edge-path for every edge e ∈ E Θ_z and every n ≥ 1, and Lemma 9.6 furthermore proves that f_z : Θ_z → Θ_z is an expanding irreducible train-track map representing ϕ_u. This verifies parts (1) and (2) of Theorem C.

Suppose now that ϕ is additionally assumed to be hyperbolic and fully irreducible, in which case G_ϕ is word-hyperbolic and f is a clean train-track representing ϕ. Since G_ϕ_u ≅ G_ϕ is word-hyperbolic, we also know that ϕ_u is a hyperbolic automorphism. By Corollary 9.10 we additionally have f_z is a weakly clean train track map. Hence ϕ_u is fully irreducible by Corollary 5.4. □

Remark 9.11. The full irreducibility conclusion for ϕ_u of part (3) in Theorem C does not necessarily hold under the weaker assumption in part (3) that ϕ only be fully irreducible (i.e. without the assumption that ϕ be hyperbolic). Recall that, as proved in [BH], a fully irreducible ϕ ∈ Out(F_N) is non-hyperbolic if and only if ϕ comes from a pseudo-Anosov homeomorphism f of an once-punctured connected surface S without boundary with F_N = π_1(S). In this case the mapping torus M_f of f is a hyperbolic 3–manifold fibering over the circle with fiber S and G_ϕ = π_1(M). If M admits a different fibration over S^1 with fiber Y, then M_f also decomposes as the mapping torus of a homeomorphism f’ of Y and this f’ is again pseudo-Anosov. However, in general, there is no reason to expect that the new fiber Y will have exactly one puncture, even for a fibration of M coming from a class u ∈ H^1(G_ϕ, R) which is projectively close to the class u_0 associated with the original fibration. If such Y has at least two punctures, then the element of Out(π_1(Y)) corresponding to f’ is not fully irreducible, since the punctures of Y are permuted by f’ and the peripheral curves around the punctures are primitive elements of π_1(Y).

10. Dynamics and entropy

In this section, we establish Theorem D from the Introduction:
Theorem D. Let $\varphi \in \text{Out}(F_N)$ (where $N \geq 2$) be an element represented by an expanding irreducible train track map $f: \Gamma \to \Gamma$. Let $X_f$ be the folded mapping torus, $\psi$ the associated semiflow, and $A_{X_f} \subset H^1(X_f; \mathbb{R})$ the positive cone of $X_f$. Then there exists a continuous, homogeneous of degree $-1$ function
\[ \mathcal{H}: A_{X_f} \to \mathbb{R} \]
such that for every primitive integral $u \in A_{X_f}$ represented by a positive cocycle $z \in Z^1(X_f; \mathbb{R})$, the first return map $f_z: \Theta \to \Theta_z$ satisfies
\[ \log(\lambda(\varphi_u)) = h(f_z) = \mathcal{H}(u). \]
Moreover, $1/\mathcal{H}$ is concave, and hence $\mathcal{H}$ is convex.

Our proof closely follows Fried’s proof of the analogous statement for mapping tori of pseudo-Anosov homeomorphisms (which applies in a more general setting); see [Fri1]. To carry out the arguments here, we work with the natural extension, as we now explain.

10.1. The natural extension of the first return map. Fix any integral class $u \in A$ represented by a positive cocycle $z$ and let $\eta_z: X = X_f \to S^1$ be an associated fibration. Recall that $\Theta_z$ is the preimage of a point under $\eta_z$ which we assume (as we may) is $0 \in S^1 = \mathbb{R}/\mathbb{Z}$, so that $\Theta_z = \eta_z^{-1}(0)$. Additionally, $f_z: \Theta \to \Theta_z$ denotes the first return map of $\psi$. The failure of $f_z: \Theta \to \Theta_z$ to be a homeomorphism can be rectified in a certain sense by the construction of the natural extension. This is the space
\[ \Theta_z' = \{ x = (\ldots, x_{-1}, x_0, x_1, \ldots) \mid x_i \in \Theta_z \text{ such that } x_i = f_z(x_{i-1}) \text{ for all } i \}, \]
equipped with the product topology, together with the shift map $f_z': \Theta_z' \to \Theta_z'$ defined by
\[ (f_z'(x))^i = x_{i+1} \]
for all $i \in \mathbb{Z}$. That is, the $i^{th}$ coordinate of $f_z'(x)$ is the $(i + 1)^{st}$ coordinate of $x$. There is a continuous surjective semi-conjugacy $\pi_z: \Theta_z' \to \Theta_z$ given by
\[ \pi_z(\ldots, x_{-1}, x_0, x_1, \ldots) = x_0. \]
That is, $\pi_z \circ f_z' = f_z \circ \pi_z$ ($\pi_z$ is a semi-conjugacy of $f_z'$ onto $f_z$). This fact is immediate from the definition of $\Theta_z'$ and $f_z'$. Since $\pi_z$ is surjective, the topological entropies satisfies the inequality
\[ h(f_z') \geq h(f_z). \]
However, the system $f_z': \Theta_z' \to \Theta_z'$ is the “smallest” homeomorphism which admits a semiconjugacy to $f_z: \Theta \to \Theta_z$, in the sense that any other homeomorphism which can be semiconjugated onto $f_z: \Theta \to \Theta_z$ factors through $\pi_z$ via a surjection to $\Theta_z'$. The key fact for us is that topological entropy is actually preserved in this case, see [Dow, Section 6.8]:

Lemma 10.1. The topological entropy of the extension satisfies
\[ h(f_z') = h(f_z). \]

10.2. A natural extension of the semiflow. We can make a similar construction for the semiflow $\psi_s: X \to X$. Say that a map $\gamma: \mathbb{R} \to X$ is a biinfinite flow line for $\psi$ if
\[ \psi_s(\gamma(t)) = \gamma(t + s) \]
for all $t \in \mathbb{R}$ and $s \geq 0$. Let $X'$ denote the space of all biinfinite flow lines, equipped with the topology of uniform convergence on compact sets:
\[ X' = \{ \gamma \mid \gamma \text{ is a biinfinite flow line } \}. \]
This comes equipped with a flow $\Psi$ defined by $(\Psi_s(\gamma))(t) = \gamma(t + s)$ for all $t, s \in \mathbb{R}$. There is a map $\Pi: X' \to X$ given by $\Pi(\gamma) = \gamma(0)$ which is a continuous surjection (since there is a biinfinite flow line through every point). Again from the definitions, we see that for all $s \geq 0$ we have

$$\psi_s \circ \Pi = \Pi \circ \psi_s$$

which is to say, $\Pi$ semiconjugates $\Psi$ to $\psi$. This is also clearly the minimal flow with this property.

By composing $\eta_z$ with $\Pi$ we obtain a map

$$\eta'_{z} = \eta_{z} \circ \Pi: X' \to S^1.$$  

We put $\Theta_{z}'' := (\eta'_{z})^{-1}(0)$ and denote the first return map of $\Psi$ to this section by $f''_{z}: \Theta_{z}'' \to \Theta_{z}''$. As the next lemma shows, $f''_{z}$ is nothing but the natural extension of $f_{z}: \Theta_{z} \to \Theta_{z}$ already constructed above.

**Lemma 10.2.** There is a homeomorphism $F: \Theta_{z}'' \to \Theta_{z}$ that conjugates $f''_{z}$ to $f'_{z}$.

**Proof.** First observe that $\gamma \in X'$ is in $\Theta_{z}''$ if and only if $\gamma(0) \in \Theta_{z}$. Such a biinfinite flow line $\gamma: \mathbb{R} \to X$ meets $\Theta_{z}$ at infinitely many points in both forward and backward time. More precisely, there is an increasing, biinfinite, proper sequence of times $\{t_{j}\}_{j \in \mathbb{Z}}$ with $t_{0} = 0$ so that

$$\gamma(t) \in \Theta_{z} \iff t = t_{j} \text{ for some } j.$$

Since $f_{z}$ is the first return map of $\psi$ to $\Theta_{z}$, it follows that $f_{z}(\gamma(t_{j})) = \gamma(t_{j+1})$ for all $j$. Therefore, for any $\gamma \in \Theta_{z}''$, we may define

$$F(\gamma) = (\ldots, \gamma(t_{-1}), \gamma(t_{0}), \gamma(t_{1}), \ldots)$$

(that is, the $i^{th}$ coordinate of $F(\gamma)$ is $\gamma(t_{j})$), which is an element of $\Theta_{z}'$.

To see that $F$ is injective, we claim that the sequence

$$(\ldots, \gamma(t_{-1}), \gamma(t_{0}), \gamma(t_{1}), \ldots)$$

determines $\gamma$. This is because, for any $t > s$, $\gamma(s)$ determines $\gamma(t)$ by the formula $\gamma(t) = \psi_{t-s}(\gamma(s))$. As $j \to -\infty$, $t_{j} \to -\infty$, and so for any $t \in \mathbb{R}$, $\gamma(t)$ is determined by some $\gamma(t_{j})$ with $t_{j} < t$. Therefore, $F$ is injective. Similarly, given any sequence $\bar{z} \in \Theta_{z}'$, we can use this reasoning to construct $\gamma \in \Theta_{z}''$ with $F(\gamma) = \bar{z}$.

Suppose now that $\gamma_{n} \to \gamma$ is a sequence of flow lines converging uniformly on compact sets with $\gamma(0), \gamma_{n}(0) \in \Theta_{z}$ for all $n$ and $\gamma_{n}(0) \to \gamma(0)$. Let $\{t_{j}\}_{j \in \mathbb{Z}}$ denote the sequence for $\gamma$ as above, and similarly, $\{t_{n,j}\}_{j \in \mathbb{Z}}$ the sequence for $\gamma_{n}$. The uniform convergence on compact sets implies that the points of intersection of $\gamma_{n}$ with $\Theta_{z}$ are converging uniformly on compact sets to the intersection points of $\gamma$ with $\Theta_{z}$, which is to say, $\gamma_{n}(t_{n,j}) \to \gamma(t_{j})$ for all $j$ as $n \to \infty$. Therefore $F$ is continuous. Because $X$ is compact, one can show that $X'$ is also compact, hence so is $\Theta_{z}'$.

Since $\Theta_{z}'$ is Hausdorff, the continuous map $F: \Theta_{z}'' \to \Theta_{z}'$ is a homeomorphism.

For any $\gamma \in \Theta_{z}''$ and any $j$, we have $f_{z}(\gamma(t_{j})) = \gamma(t_{j+1})$, and therefore $F$ conjugates $f_{z}''$ to the shift map $f_{z}'$.

Because of this lemma, we will ignore the distinction between $f''_{z}: \Theta_{z}'' \to \Theta_{z}''$ and $f'_{z}: \Theta_{z}' \to \Theta_{z}'$, and just refer to $\Theta_{z}'$ as the section of $\Psi$ and $f_{z}'_{z}: \Theta_{z}' \to \Theta_{z}'$ the first return map of $\Psi$.

### 10.3. The variational principal and Abramov’s Theorem

The topological entropy of $f'_{z}$ is approximated from below by metric entropies $h_{\nu}(f'_{z})$ for invariant probability measures $\nu$ on $\Theta_{z}'$, according to the variational principle; see [Dow, Section 6.8].

**Theorem 10.3.** For any integral class $u \in \mathcal{A}$ represented by a positive cocycle $z$ we have

$$h(f'_{z}) = \sup_{\nu} h_{\nu}(f'_{z})$$

where $\nu$ ranges over all $f'_{z}$–invariant Borel probability measures on $\Theta_{z}'$. 
The key to proving continuity (and the other properties) of the entropy is a result of Abramov which relates entropy of \( f'_{z} \) to that of the flow \( \Psi \). To make sense of this, we have to relate \( f'_{z} \)-invariant measures on \( \Theta'_{z} \) to \( \Psi \)-invariant measures on \( X' \). In fact, there is a bijection between these two spaces of measures defined as follows.

Given a \( \Psi \)-invariant probability measure \( \mu \) on \( X' \), we can construct a measure \( \bar{\mu}_0 \) on any section \( \Theta'_{z} \) by the formula
\[
\bar{\mu}_0(A) = \frac{1}{t} \mu(\{ \psi_{s}(x) \mid x \in A, 0 \leq s \leq t \})
\]
for any Borel measurable set \( A \subset \Theta'_{z} \). This may not be a probability measure, and indeed the total measure \( \bar{\mu}_0(\Theta'_{z}) \) is an important quantity. The \( f'_{z} \)-invariant probability measure on \( \Theta_{z} \) is the normalization
\[
\bar{\mu} = \frac{1}{\bar{\mu}_0(\Theta'_{z})} \bar{\mu}_0.
\]

There is a flow-equivariant local homeomorphism
\[
\Theta'_{z} \times \mathbb{R} \to X'
\]
given by \((x, s) \mapsto \Psi_{s}(x)\) (where the flow on the domain is just the obvious translation action on the second coordinate). The product measure \( \bar{\mu}_0 \times m \), where \( m \) is Lebesgue measure on \( \mathbb{R} \), is flow-invariant and pushes forward to a flow invariant measure. From the construction of \( \bar{\mu}_0 \), it follows that \( \mu \) is the push forward of \( \bar{\mu}_0 \times m \). As an abuse of notation, we will just write \( \mu = \bar{\mu}_0 \times m \). This can be used to describe the inverse construction.

Abramov’s Theorem relating the entropy of a flow to the first return map of a section (see [Abr, DGS]) takes the following form in our situation (see also [Fri1]).

**Theorem 10.4.** For any integral class \( u \in A \) represented by a positive cocycle \( z \) and any \( \Psi \)-invariant probability measure \( \mu \) on \( X' \), let \( \bar{\mu}_0 \) and \( \bar{\mu} \) be defined as above. Then
\[
\frac{h_{\bar{\mu}}(f_{z}')}{h_{\bar{\mu}_0}(\Theta'_{z})} = \frac{h_{\mu}(\Psi)}{h_{\mu}(\Psi)}.
\]

As an immediate corollary of these two results, we have the following useful expression for the reciprocal of the topological entropy.

**Corollary 10.5.** For any integral class \( u \in A \) represented by a positive cocycle \( z \), we have
\[
\frac{1}{h(f_{z}')} = \inf_{\mu} \frac{\bar{\mu}_0(\Theta'_{z})}{h_{\mu}(\Psi)}
\]
where the infimum is over all \( \Psi \)-invariant Borel probability measures \( \mu \) on \( X' \), and \( \bar{\mu}_0 \) is constructed from \( \mu \) as above.

10.4. The measure \( \bar{\mu}_0 \) and linearity. Given a \( \Psi \)-invariant probability measure \( \mu \) on \( X' \), we now have a function defined on the integral classes \( u \in A \) which we denote
\[
\mu_s(u) = \bar{\mu}_0(\Theta'_{z_u})
\]
where \( z_u \) is a positive cocycle representing \( u \). If \( z'_u \) is another positive cocycle representing \( u \) with fiber \( \Theta'_{z'_u} \), then we can flow \( \Theta'_{z_u} \) homeomorphically onto \( \Theta'_{z'_u} \), and hence \( \bar{\mu}_0(\Theta'_{z'_u}) = \bar{\mu}_0(\Theta'_{z_u}) \) is independent of the choice of \( z_u \) (and fibration \( \eta_{z_u} \)).

Our goal is now to prove the following.

**Lemma 10.6.** If \( \mu \) is a \( \Psi \)-invariant probability measure on \( X' \), then \( \mu_s \) is the restriction of a linear function (of the same name):
\[
\mu_s : H^1(X; \mathbb{R}) \to \mathbb{R}.
\]
Proof. Given an integral class \( u \in \mathcal{A} \) represented by a positive cocycle \( z = z_u \), we can reparametrize the flow as \( \Psi \), so that for the projection of the flow lines to \( S^1 = \mathbb{R}/\mathbb{Z} \) by \( \eta_z \) are local isometries. The bijections

\[
\{ \text{\( \Psi \)-inv’t measures on } X’ \} \leftrightarrow \{ \text{\( f_{\Psi} \)-inv’t measures on } \Theta’_{z} \} \\
\leftrightarrow \{ \text{\( \Psi^z \)-inv’t measures on } X’ \}
\]

will allow us to turn the \( \Psi \)-invariant measure \( \mu \) on \( X’ \) into a \( \Psi^z \)-invariant measure \( \mu^z \) on \( X’ \), given by

\[
\mu_z = m_z \times \mu
\]

where \( m_z \) is the Lebesgue measure on \( \mathbb{R} \), and the subscript \( z \) is only there to remind us that it is induced by the reparametrized flow \( \Psi^z \).

The measure \( \mu_z \) is not a probability measure. Indeed, the parametrization is chosen so that the map

\[
\Theta'_{z} \times [0, 1) \rightarrow X'
\]

given by

\[
(\bar{x}, s) \mapsto \Psi^z(\bar{x})
\]

is 1-1 and onto. It follows that

\[
\mu_z(X') = \hat{\mu}_0(\Theta'_{z}).
\]

What is important about this formula is that the left hand side does not involve the section \( \Theta'_{z} \). Moreover, we could have used a different section \( \Theta'_{u} \), and as long as we use the flow \( \Psi^z \), we would produce the same measure \( \mu_z \).

Now suppose that \( u, v \in \mathcal{A} \) are two integral classes represented by \( z \) and \( w \), respectively. A useful observation about the maps \( \eta_z \) and \( \eta_w \) is that because they are maps to the additive group \( S^1 = \mathbb{R}/\mathbb{Z} \), we can add them \( \eta_z + \eta_w \). A careful choice of \( \eta_z \) and \( \eta_w \) implies \( \eta_z + w = \eta_z + \eta_w \) is a fibration associated to \( z + w \) which determines the corresponding map

\[
\eta'_{z+w} = \eta'_z + \eta'_w : X' \rightarrow S^1.
\]

The measure \( \mu_z \) and \( \mu_w \) are defined by taking the product \( \hat{\mu}_0 \) with the Lebesgue measures \( m_z \) and \( m_w \), induced by the reparametrized flows \( \Psi^z \) and \( \Psi^w \), respectively. Since these flows are parametrized so that \( \eta'_z \) and \( \eta'_w \) restricted to flow lines are local isometries, it follows that \( \mu_{z+w} \) is defined by taking the product \( \hat{\mu}_0 \) with \( m_z + m_w \). Consequently, we have

\[
\mu_{z+w} = \mu_z + \mu_w.
\]

Hence

\[
\mu_s(u + v) = \mu_{z+w}(X') = \mu_z(X') + \mu_w(X') = \mu_s(u) + \mu_s(v)
\]

and \( \mu_s \) is linear on the integral points of \( \mathcal{A} \). It follows that \( \mu_s \) uniquely extends to a linear function on \( H^1(X; \mathbb{R}) \).

10.5. Completing the proof. Combining the previous facts, we give the

Proof of Theorem D. If \( u \in \mathcal{A} \) is a primitive integral element and \( z_u \) is a positive 1-cocycle, then, by Corollary 8.20 the map \( f_{z_u} : \Theta_{z_u} \rightarrow \Theta_{z_u} \) is a homotopy equivalence taking vertices to vertices. By Corollary 8.21 we also know that \( \Theta_{z_u} \) is connected and furthermore, it has no valence-1 vertices (see the proof of Theorem B). By Lemma 9.3 the map \( f_{z_u} : \Theta_{z_u} \rightarrow \Theta_{z_u} \) is a regular topological graph-map. Corollary 8.21 now implies that \( f_{z_u} \) is a regular topological representative of the monodromy \( \varphi_u \in \text{Out(ker}(u)) \). By Proposition 2.8 we have \( \lambda(f_{z_u}) = \log \lambda(f_{z_u}) \) where \( \lambda(f_{z_u}) \) is the spectral radius of the transition matrix \( A(f_{z_u}) \). We have also seen in the proof of Theorem C that for an appropriate choice of a linear structure on \( \Theta_{z_u} \) the map \( f_{z_u} : \Theta_{z_u} \rightarrow \Theta_{z_u} \) is an expanding irreducible train-track map representing \( \varphi_u \). Therefore \( \lambda(f_{z_u}) = \lambda(\varphi_u) \) is the growth.
rate of \( \varphi_u \) and thus \( h(f_{z_u}) = \log \lambda(f_{z_u}) = \log \lambda(\varphi_u) = h(\varphi_u) \), the algebraic entropy of \( \varphi_u \). Since \( \varphi_u \) is fully irreducible, we have \( h(f_{z_u}) = h(\varphi_u) > 0 \).

Define a function \( W : \mathcal{A} \to \mathbb{R} \) by

\[
W(u) := \inf_{\mu} \frac{\mu_u(z_u)}{h_u(\Psi)}
\]

where \( u \in \mathcal{A} \), where \( z_u \) is a positive cocycle representing \( u \), and the infimum is over all Borel \( \Psi \)-invariant probability measures \( \mu \) on \( X' \). By Lemma 10.1 we have \( W(u) = 1/h(f'_{z_u}) = 1/h(f_{z_u}) \) for any primitive integral class \( u \in \mathcal{A} \). The linearity of \( \mu_u \) implies that the function \( W \) is homogeneous of degree 1. By Corollary 10.5, we see that \( W \) is the infimum of a collection of linear functions, and is therefore concave and hence continuous. For any primitive integral \( u \in \mathcal{A} \) we have \( 0 < h(f_{z_u}) < \infty \) and hence \( 0 < W(u) = 1/h(f_{z_u}) < \infty \). Since the primitive integral classes are projectively dense in \( \mathcal{A} \), concavity and homogeneity of \( W \) imply that \( 0 < W(u) < \infty \) for all \( u \in \mathcal{A} \). Therefore setting \( \mathcal{H}(u) := 1/W(u) \) for all \( u \in \mathcal{A} \) gives us a continuous homogeneous of degree \(-1\) function \( \mathcal{H} : \mathcal{A} \to (0, \infty) \). By construction, for every primitive integral \( u \in \mathcal{A} \) we have \( \mathcal{H}(u) = \log \lambda(f_{z_u}) = \log \lambda(\varphi_u) = h(\varphi_u) \), as required. \( \square \)

As mentioned in the introduction, we have the following analogue from the 3–manifold setting of McMullen’s [McM1, Section 10] which complements the results of Algom-Kfir and Rafi [AKR].

**Corollary 10.7.** Let \( \varphi \in \text{Out}(F_N) \) (where \( N \geq 2 \)) be an element represented by an expanding irreducible train track map \( f : \Gamma \to \Gamma \), and let \( X_f, \mathcal{A}_{X_f} \), and \( \mathcal{H} \) be as in Theorem D. The function

\[
D : \mathcal{A} \to \mathbb{R}_+
\]

given by \( D(u) = \mathcal{H}(u)u(\epsilon) \) is continuous and constant on rays. In particular, for any compact subset \( K \subset \mathcal{A} \), \( D \) is bounded on the cone over \( K \),

\[
C_K = \{ c\tau \mid c \in \mathbb{R}_+, \tau \in K \}.
\]

Consequently, if \( \dim(H^1(G; \mathbb{R})) \geq 2 \), then \( G \cong F_{N_k} \rtimes \varphi_k \mathbb{Z} \) for some sequence of automorphisms \( \varphi_k \in \text{Out}(F_{N_k}) \), with \( N_k \to \infty \), represented by expanding irreducible train track maps, and there are constants \( 0 < c_1 < c_2 < \infty \) so that

\[
c_1 \leq N_k \log \lambda(\varphi_k) \leq c_2.
\]

If \( \varphi \) is fully irreducible and hyperbolic so are all \( \varphi_k \).

**Proof.** Continuity follows from linearity of \( u \mapsto u(\epsilon) \) and continuity of \( \mathcal{H} \). The fact that \( D \) is constant on rays comes from the canceling homogeneity degrees: \(+1\) for \( \epsilon \) and \(-1\) for \( \mathcal{H} \). The second statement follows from the fact that \( D(K) = D(C_K) \), and \( K \) is compact. The existence of \( \varphi_k \) and constants \( 0 < c_1 < c_2 < \infty \) follows from the first statement and Theorems B and C by taking any sequence \( \{ u_k \} \subset \mathcal{A} \) of primitive integral elements for which the corresponding rays \( \mathbb{R}_+u_k \) converge to a point in \( \mathcal{A} \). The last statement is a consequence of Theorem C, part (3). \( \square \)

**Remark 10.8.** It is possible to avoid the use of Theorem 3.2 in the proof of Theorem D and in the proof of all parts of Theorem C except for part (2).

Namely, suppose \( f : \Gamma \to \Gamma \) is a regular topological graph-map of a finite connected topological graph \( \Gamma \) with an irreducible transition matrix \( A(f) \). It is straightforward to find a metric structure \( \mathcal{L} \) on \( \Gamma \) and a regular linear graph map \( f' : (\Gamma, \mathcal{L}) \to (\Gamma, \mathcal{L}) \) such that \( f' \) is isotopic to \( f \) and has “the same combinatorics” as \( f \) and such that \( f' \) is a local \( \lambda(f) \)-homothety on edges with respect to \( d_\mathcal{L} \).

By “the same combinatorics” we mean that for any \( \epsilon \in ET \) and \( n \geq 1 \) we have \( f^n(\epsilon) = (f')^n(\epsilon) \) as combinatorial edge-paths. Thus \( A(f) = A(f') \), \( \lambda(f) = \lambda(f') \), and a turn in \( \Gamma \) is taken by \( f \) if and only if it is taken by \( f' \). Hence \( \text{Whr}(f, v) = \text{Whr}(f', v) \) for any \( v \in VT \). We have
$h(f) = h(f') = \log \lambda(f)$ by Proposition 2.8. Also, if $f^n$ is locally injective on edges for all $n \geq 1$ then $(f')^n$ is locally injective on edges for all $n \geq 1$; that is, $f'$ is a train-track map.

In the proof of Theorem C, we can first verify that $f^n_z : \Theta_z \rightarrow \Theta_z$ is locally injective on edges for all $n \geq 1$ and that $A(f_z)$ is irreducible with $\lambda(f_z) > 1$, and that all Whitehead graphs of all the vertices of $\Theta_z$ with respect to $f_z$ are connected. We can then pass to the modified isotopic linear graph-map $f'_z : \Theta_z \rightarrow \Theta_z$ constructed as above. Then it will follow that $f'_z$ is a (weakly) clean train-track map representing the same outer automorphism $\varphi_u$ of $\pi_1(\Theta_z) = \ker(u)$ as $f_z$. Hence $\varphi_u$ is fully irreducible by Corollary 5.4, yielding Theorem C. Moreover, since $h(f) = h(f') = \log \lambda(f) = h(\varphi_u)$, the proof of Theorem D would go through without appealing to Theorem 3.2 as well. We included the proof of Theorem 3.2 since it appears to be of independent interest and may be useful in the further analysis of the properties of the monodromies $\varphi_u$. Moreover, part (2) of Theorem C, which does require the use of Theorem 3.2, provides a stronger analogy with the motivating results of Fried for 3-manifolds.

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