Current fluctuations in periodically driven systems

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Abstract. Small nonequilibrium systems driven by an external periodic protocol can be described by Markov processes with time-periodic transition rates. In general, current fluctuations in such small systems are large and may play a crucial role. We develop a theoretical formalism to evaluate the rate of such large deviations in periodically driven systems. We show that the scaled cumulant generating function that characterizes current fluctuations is given by a maximal Floquet exponent. Comparing deterministic protocols with stochastic protocols, we show that, with respect to large deviations, systems driven by a stochastic protocol with an infinitely large number of jumps are equivalent to systems driven by deterministic protocols. Our results are illustrated with three case studies: a two-state model for a heat engine, a three-state model for a molecular pump, and a biased random walk with a time-periodic affinity.

Keywords: large deviations in non-equilibrium systems, fluctuation phenomena, stationary states

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1. Introduction

Periodic external control is used to operate a wide variety of thermodynamic machines that includes traditional idealized engines. Modern experimental examples of such machines are molecular pumps [1] and micro-sized heat engines [2]. For these small systems, thermodynamic currents, such as the work exerted on a molecular pump or the heat flow in a heat engine, display thermal fluctuations that can be relatively large. For instance, the prominent fluctuation theorem is a symmetry related to these fluctuations.

Stochastic thermodynamics [3] is an emerging field that applies to small systems with large fluctuations. Within this theory, periodically driven systems are modeled as Markov processes with time-dependent transition rates that are periodic. Such modeling has been used in several works that include: models for stochastic resonance [4], linear response theory for periodically driven systems [5–11], theoretical studies for small heat engines far from equilibrium [12–15], necessary conditions for the generation of a current in a molecular pump [16–20], a mapping relating periodically driven systems with systems driven by a fixed thermodynamic affinity [21, 22], and 2.5 large deviations for Markov process with time-periodic generators [23, 24]. However, a generic formalism to evaluate the rate of large deviations of single currents is still not available.
Periodically driven systems reach a limiting periodic state that can be contrasted with nonequilibrium stationary states, which are described by Markov processes with constant transition rates. Physically, this second case corresponds to a system driven by a fixed thermodynamic affinity. For nonequilibrium stationary states, a generic formalism to quantify large deviations of currents is available: the so-called scaled cumulant generating function (SCGF) is determined by the maximum eigenvalue of a tilted generator \[25, 26\]. This formalism can be used to calculate the SCGF of systems subjected to a potential that is periodic in space \[27\], which is not the case for a time-periodic potential.

In this paper, we develop a formalism to determine large deviations in periodically driven systems. We show that a fundamental (or monodromy) matrix from Floquet theory \[28–31\], which is related to a time-dependent tilted generator, quantifies current fluctuations. Specifically, we show that this fundamental matrix is a Perron–Frobenius matrix and that its maximal eigenvalue gives the SCGF.

Deterministic protocols are commonly used in the study of periodically driven systems. Nevertheless, such systems can also be driven by a cyclic stochastic protocol that mimics the periodicity of a deterministic protocol \[11, 32–34\]. In this case, the system and protocol together form a bipartite Markov process with time-independent transition rates. For stochastic protocols, current fluctuations can then be analyzed within the stationary state of this bipartite Markov process. We prove the equivalence of current fluctuations between systems driven by a deterministic protocol and systems driven by a stochastic protocol with an infinitely large number of jumps. Therefore, we show that a periodic protocol can be seen as a particular limit of a stochastic protocol.

Illustrations of our results are performed with three models. An exactly solvable model for a heat engine, a model for molecular pump that we use to compare theory with numerical simulations, and one model for a biased random walk with a time-periodic affinity that has a particularly simple expression for the SCGF.

The paper is organized in the following way. In section 2, we define fluctuating currents in Markov processes with time-periodic transition rates. The formalism for the calculation of the SCGF is developed in section 3. In section 4, we analyze three case studies. Section 5 contains the results for a stochastic protocol. We conclude in section 6. In appendix A, we discuss fluctuating currents such as work, which can be written in a form that is apparently different from the generic currents we consider in the main text. We extend our results to diffusion processes in appendix B. An exact calculation of the SCGF for systems with two states and a piecewise constant protocol is presented in appendix C.

2. General setup and mathematical definitions

We consider a Markov process with a finite number of states \(\Omega\). The time-dependent transition rate from state \(i\) to state \(j\) at time \(t\) is denoted by \(w_{ij}(t)\). These transition rates are time-periodic with a period \(\tau\), i.e.

\[
    w_{ij}(t + \tau) = w_{ij}(t).
\]
In the theoretical framework of stochastic thermodynamics, which we use in our illustrative examples, the transition rates fulfill the restriction that if $w_{ij}(t) \neq 0$ then $w_{ji}(t) \neq 0$. However, our mathematical results (in sections 3 and 5) do not rely on this assumption. A physical interpretation for these transition rates based on the generalized detailed balance relation from stochastic thermodynamics can be found in [8, 10, 11].

The associated master equation reads

$$\frac{d}{dt} P(i, t) = \sum_j \left[ P(j, t) w_{ji}(t) - P(i, t) w_{ij}(t) \right],$$

where $P(i, t)$ is the probability to be in state $i$ at time $t$. This equation can be written in the vectorial form

$$\frac{d}{dt} |P_t\rangle = L_t |P_t\rangle,$$

where $|P_t\rangle$ is a vector with components $P(i, t)$ and $L_t$ is the stochastic matrix defined as

$$[L_t]_{ji} \equiv (1 - \delta_{ij}) w_{ij}(t) - \delta_{ij} \sum_k w_{ik}(t).$$

A stochastic trajectory from time 0 to time $T = n\tau$ is a sequence of jumps and waiting times, which is denoted by $A_{n\tau}^T$. If a jump takes place at time $t$, the state before the jump is denoted $a_i^-$ and the state after the jump is denoted $a_i^+$. A fluctuating current is a functional of the stochastic trajectory defined as

$$X[A_{0\tau}^T] \equiv \sum_{0 \leq t \leq T} \theta_{a_i^-, a_i^+}(t).$$

For a current, the increments $\theta_{i,j}(t)$ are anti-symmetric, i.e.

$$\theta_{i,j}(t) = -\theta_{j,i}(t).$$

Fluctuations of this current in the long time limit are characterized by the SCGF

$$\lambda(z) \equiv \lim_{T \to \infty} \frac{1}{T} \ln \langle e^{zX} \rangle = \frac{1}{\tau} \lim_{n \to \infty} \frac{1}{n} \ln \langle e^{zX} \rangle,$$

where the brackets mean an average over stochastic trajectories. The average current $J$ and diffusion coefficient $D$ are given by

$$J \equiv \lim_{T \to \infty} \frac{1}{T} \langle X \rangle = \lambda'(0)$$

and

$$D \equiv \lim_{T \to \infty} \frac{1}{T} \left( \langle X^2 \rangle - \langle X \rangle^2 \right) = \lambda''(0),$$

respectively. Similarly, higher order moments associated with $X$ can be obtained by taking higher order derivatives of $\lambda(z)$ at $z = 0$.

In the long time limit, the system reaches an invariant limiting periodic distribution $P_i^{inv}(t) = P_i^{inv}(t + \tau)$. The average current can be written in terms of this distribution as
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\[ J = \frac{1}{\tau} \int_0^\tau \sum_{i<j} \theta_{ij}(t) [P^\text{inv}_i(t) w_{ij}(t) - P^\text{inv}_j(t) w_{ji}(t)] \, dt, \]  

(10)

where \( \sum_{i<j} \) means a sum over all links with non-zero transition rates in the network of states.

An important observable in stochastic thermodynamics is the work done on the system due to the periodic variation of energy of the system. This fluctuating current is typically written as an integral of a state function over the time interval \( T \). However, as we show in appendix A, observables such as work can also be written in the form given by equation (5).

3. Floquet theory for the SCGF

3.1. General theory

The joint probability that the current is \( X \) and the system is in state \( i \) at time \( t \) is written as \( P(i, X, t) \), whereas the vector \( |P_t(X)\rangle \) has components \( P(i, X, t) \). The Laplace transform of \( |P_t(X)\rangle \) is given by

\[ |\tilde{P}_t(z)\rangle \equiv \sum_X e^{Xz} |P_t(X)\rangle. \]  

(11)

The average \( \langle e^{zX} \rangle \) in equation (7) is related to this Laplace transform in the following way,

\[ \langle e^{zX} \rangle = \sum_{i=1}^{\Omega} \tilde{P}(i, z, T). \]  

(12)

From the master equation (2) and the tilted generator

\[ [\mathcal{L}_t(z)]_{ji} \equiv (1 - \delta_{ij}) w_{ij}(t) e^{z\theta_{ij} t} - \delta_{ij} \sum_k w_{ik}(t), \]  

(13)

we obtain

\[ \frac{d}{dt} |\tilde{P}_t(z)\rangle = \mathcal{L}_t(z) |\tilde{P}_t(z)\rangle. \]  

(14)

Using the periodicity of \( \mathcal{L}_t(z) \), the formal solution of this equation at time \( T = n\tau \) is

\[ |\tilde{P}_T(z)\rangle = \hat{\exp} \left( \int_0^T \mathcal{L}_t(z) \, dt \right) |\tilde{P}_0(z)\rangle = \left[ \hat{\exp} \left( \int_0^T \mathcal{L}_t(z) \, dt \right) \right]^n |\tilde{P}_0(z)\rangle \equiv \mathcal{M}(z)^n |\tilde{P}_0(z)\rangle, \]  

(15)

where \( |\tilde{P}_0(z)\rangle \) is the initial condition and \( \hat{\exp} \) represents a time-reversed ordered exponential. This ordered exponential can be defined as the solution of the differential equation

\[ \frac{d}{dt} \hat{\exp} \left( \int_0^t \mathcal{L}_t'(z) \, dt' \right) = \mathcal{L}_t(z) \hat{\exp} \left( \int_0^t \mathcal{L}_t'(z) \, dt' \right). \]  

(16)
where the initial condition is the identity matrix.

The matrix
\[ \mathcal{M}(z) \equiv \exp\left( \int_0^\tau L_{t'}(z) dt' \right) \]  
(17)
is a central object that is known as the fundamental matrix in Floquet theory [31]. The eigenvalues of this matrix are denoted by \( \rho_k(z) \), the right eigenvectors by \( |r_k(z)\rangle \), and the left eigenvectors by \( \langle l_k(z)| \). The fundamental matrix can then be written as
\[ \mathcal{M}(z) = \sum_{k=1}^\Omega \rho_k(z) |r_k(z)\rangle \langle l_k(z)|. \]  
(18)

From equation (15), by setting \( T = \tau \), imposing the initial condition \( a_0 = i \), and restricting to trajectories that finish at state \( a_T = j \), we obtain
\[ \langle e^{zX} \delta_{a_T,j} | a_0 = i \rangle = [\mathcal{M}(z)]_{ji}. \]  
(19)

This equation shows that all elements of the fundamental matrix \( \mathcal{M}(z) \) are positive. Hence, from the Perron–Frobenius theorem, the matrix \( \mathcal{M}(z) \) has a maximal real eigenvalue defined as \( \rho_1(z) \). This fact together with the definition of the SCGF in equations (7), (12), (15) and (18) lead to the main result
\[ \lambda(z) \simeq \frac{1}{\tau} \ln \rho_1(z), \]  
(20)
where the symbol \( \simeq \) means asymptotic equality in the limit \( n \to \infty \) and \( \tau^{-1} \ln \rho_1(z) \) is the maximal Floquet exponent. The SCGF \( \lambda(z) \) can be evaluated by first solving equation (16) and then calculating the maximal eigenvalue of \( \mathcal{M}(z) \). For \( z = 0 \) the matrix elements in equation (19) are transition probabilities, therefore, the maximum eigenvalue of the matrix is \( \rho_1(0) = 1 \), which implies \( \lambda(0) = 0 \). It is worth noting that equation (20) is not restricted to currents. This result is also valid for any functional of the stochastic trajectory with the form given in equation (5) that has increments that do not fulfill the anti-symmetry in equation (6). We point out that the SCGF has been obtained as a maximum Floquet exponent for specific two-state models in [11, 35].

This relation between SCGF and maximal Floquet exponent is also valid for diffusion processes, as shown in appendix B. For piecewise protocols, transition rates \( w_{ij}(t) \) are piecewise. If the external protocol is piecewise constant, with the period divided into \( L \) pieces and \( \tau = \tau_0 + \tau_1 + \ldots + \tau_{L-1} \), the matrix \( \mathcal{M}(z) \) defined in equation (16) takes the form
\[ \mathcal{M}(z) = \exp(\tilde{L}_{L-1}(z)\tau_{L-1}) \ldots \exp(\tilde{L}_1(z)\tau_1) \exp(\tilde{L}_0(z)\tau_0), \]  
(21)
where \( \tilde{L}_k(z) \) is the constant modified generator during the interval \( \tau_k \). In this last equation, it is assumed that the increments of the current are also piecewise constant. The SCGF can then be obtained from the maximal eigenvalue of this matrix. For a piecewise protocol that is not constant, the expression of \( \mathcal{M}(z) \) becomes a product of ordered exponentials.
### 3.2. Expressions for average current and diffusion coefficient

The average current $J$, diffusion coefficient $D$, and higher order cumulants can be obtained without explicit evaluation of the maximum eigenvalue associated with $\mathcal{M}(z)$ in the following way. A similar method for non-equilibrium stationary states has been introduced by Koza [26] (see also [36, 37]). The characteristic polynomial associated with $\mathcal{M}(z)$ is written as

$$
\det (xI - \mathcal{M}(z)) = \sum_{m=0}^{\Omega} c_m(z)x^m,
$$

where $I$ is the identity matrix. The maximum eigenvalue $\rho_1(z)$ is a root of this polynomial, which leads to the equation

$$
\sum_{m=0}^{\Omega} c_m(z) [\rho_1(z)]^m = 0.
$$

Taking a derivative with respect to $z$ and setting $z = 0$ we obtain

$$
J = \frac{1}{\tau} \frac{\rho_1'(0)}{\rho_1(0)} = -\frac{1}{\tau} \frac{\sum_{m=0}^{\Omega} c'_m(0)}{\sum_{m=0}^{\Omega} mc_m(0)},
$$

where we used equation (8) and $\rho_1(0) = 1$. Taking a second derivative with respect to $z$ of equation (23) and setting $z = 0$ we obtain

$$
D = \frac{1}{\tau} \left\{ \rho''_1(0) - [\rho'_1(0)]^2 \right\} = -\frac{1}{\tau} \frac{\sum_{m=0}^{\Omega} c''_m(0) + 2\rho'_1(0)\sum_{m=0}^{\Omega} mc'_m(0) + [\rho'_1(0)]^2 \sum_{m=0}^{\Omega} m^2 c_m(0)}{\sum_{m=0}^{\Omega} mc_m(0)},
$$

where we used equation (9) and $\rho_1(0) = 1$. Using these expressions, $J$ and $D$ can be evaluated directly from the coefficients of the characteristic polynomial associated with $\mathcal{M}(z)$. Taking higher order derivatives leads to similar expressions for higher order cumulants.

### 4. Case studies

#### 4.1. Heat engine

We introduce an exactly solvable two-state model for a heat engine with a piecewise protocol, which is illustrated in figure 1(a). This model is similar to a model for a heat engine with a stochastic protocol analyzed in [11]. One of the states has energy 0 and the other state has a higher energy that depends on time. The protocol is divided in four steps. First, the energy changes from $E$ to $E + \Delta E$ at a cold temperature $\beta_c^{-1}$. Second, the temperature changes from $\beta_c^{-1}$ to the hot temperature $\beta_h^{-1}$. Third, the energy changes back from $E + \Delta E$ to $E$. Fourth, the temperature changes back from $\beta_h^{-1}$ to $\beta_c^{-1}$. The inverse temperature takes the form

$$
\beta(z) = \begin{cases} 
\beta_c^{-1}, & \text{if } z < 0, \\
\beta_h^{-1}, & \text{if } 0 < z < 1, \\
\beta_c^{-1}, & \text{if } z > 1.
\end{cases}
$$
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\[ \beta^k = \beta_c[1 - F_q h^k], \]  

(26)

where \( F_q \equiv (\beta_c - \beta_h)/\beta_c \geq 0, h^0 = h^1 = 0 \) and \( h^2 = h^3 = 1 \). Physically, \( F_q \) is the thermodynamic affinity associated with the heat current [11] and the temperature depends on time through the parameter \( h^k \). The energy of the state with higher energy is given by

\[ E^k = E + \Delta E f^k, \]  

(27)

where \( f^0 = f^3 = 0, f^1 = f^2 = 1 \). The parameter \( f^k \) gives the time-dependence of the energy and \( \Delta E \) is the amplitude of the time-dependent part of the energy.

The time-intervals of the period are set to \( \tau_0 = \tau_2 = \tau/2 \) and \( \tau_1 = \tau_3 = \tau' \rightarrow 0 \), i.e. the energy changes happens after a time interval \( \tau/2 \) and the temperature changes are instantaneous. Hence, the number of pieces of the protocol is reduced from four to two. The transition rates for this model, which fulfill the generalized detailed balance relation [3], are set to

\[ w^0_+ = we^{-\beta_c E/2} \quad \text{and} \quad w^0_- = we^{\beta_c E/2}, \]  

(28)

for the first part of the period;

\[ w^1_+ = we^{-\beta_h (E+\Delta E)/2} \quad \text{and} \quad w^1_- = we^{\beta_h (E+\Delta E)/2}, \]  

(29)

for the second part of the period. The subscript + indicates a transition rate from the state with energy zero to the state with energy \( E^k \), whereas the subscript − indicates the reversed transition rate. The superscript 0 indicates the first half of the period and the superscript 1 indicates the second half of the period.

The basic physics of the model is that part of the heat taken from the hot reservoir is transformed into extracted work, as explained in [11]. Two currents of interest are

\[ \lambda_q(z) = \lambda_e(-\beta_c (E + \Delta E) z). \]  

Figure 1. Model and results for a heat engine. (a) Illustration of the model. The energy levels in blue (red) are associated with the cold (hot) temperature \( \beta^k \) (\( \beta_h^k \)). (b) SCGF associated with the heat current \( \lambda_q(z) \) and the work current \( \lambda_e(z) \). Parameters are set to \( \Delta E = E = \beta_c = \tau = k = 1 \) and \( \beta_h = 1/10 \), which gives \( \beta_h (E + \Delta E) = 2 \). The heat and work currents are not independent in this model with their SCGF following the relation \( \lambda_q(z) = \lambda_e(-\beta_c (E + \Delta E) z). \)
the heat current $X_q$ and the work current $X_e$. The piecewise version of the modified generator for a generic current reads

$$\tilde{\mathcal{L}}_k(z) = \begin{pmatrix} -w^k_+ & w^k e^{-z\theta^k} \\ w^k e^{z\theta^k} & -w^k_- \end{pmatrix},$$

(30)

where $k = 0$ for the first half of the period and $k = 1$ for the second half of the period. The increments for the heat current $X_q$ are defined as $\theta^0_q \equiv 0$ and $\theta^1_q \equiv \beta_c(E + \Delta E)$. The increments for the work current $X_e$ are defined as $\theta^0_e \equiv 0$ and $\theta^1_e \equiv -1$. Hence, we obtain the relation $X_q = -\beta_c(E + \Delta E)X_e$, which with equation (7) leads to $\lambda_q(z) = \lambda_e(-\beta_c(E + \Delta E)z)$ for the SCGF. In other words, for this simple model there is tight coupling between the work and heat currents, as shown in figure 1(b).

The exact calculation of the SCGF for a generic piecewise two-state model is presented in appendix C. For the present model, the SCGF associated with $X_q$ is

$$\lambda_q(z) = \frac{1}{r} \ln \left[ f(z) + \sqrt{\left[ f(z) \right]^2 - 4e^{-(w^0 + w^1)/2}} \right]$$

(31)

where

$$f(z) \equiv 4e^{-r(w^0 + w^1)/4} \sinh(w^0 r/4) \sinh(w^1 r/4) [q^0_+ q^0_- e^{z\beta_c(E + \Delta E)} + q^1_+ q^1_- e^{-z\beta_c(E + \Delta E)}]$$

$$+ (e^{-r(w^0 + w^1)/2} q^0_+ + q^0_-)(e^{-r(w^1 + w^0)/2} q^1_+ + q^1_-) + (q^0_+ e^{-r w^0/2} q^1_+ + q^1_- e^{-r w^1/2})$$

(32)

$w^0 \equiv 2w \cosh(\beta_c E/2), \ w^1 \equiv 2w \cosh(\beta_h(E + \Delta E)/2), \ q^0_+ \equiv w^0_+/w^0, \ and \ q^1_+ \equiv w^1_+/w^1.$

The SCGF plotted in figure 1(b) is a concave function of $z$, which is a generic property of a SCGF, and it becomes linear in $z$ for large $z$, which is a peculiarity of two-state models.

### 4.2. Molecular pump

We now analyze a three-state model for a molecular pump with states $i = 1, 2, 3$, which is similar to a model analyzed in [16]. The key phenomena that happens in such pumps, is that even though there are no fixed thermodynamic affinities, a suitable time-periodic variation of energies $E_i(t)$ and energy barriers $B_i(t)$ can lead to net rotation in the three state system. Periodically driven molecular pumps can be realized experimentally with interlocked molecular rings [1]. The transition rates are set to

$$w_{i,i+1} = w e^{E_i(t) - B_{i+1}(t)} \quad and \quad w_{i+1,i} = w e^{E_{i+1}(t) - B_{i+1}(t)},$$

(33)

where for $i = 3$ we have $i + 1 = 1$ and the inverse temperature is $\beta = 1$. The energies are given by

$$E_i(t) = -1 + \cos[2\pi(t + (i - 1)/3)/\tau],$$

(34)

and the energy barriers are given by

$$B_i(t) = \cos[2\pi(t + (i - 1)/3)/\tau].$$

(35)

The increment of the fluctuating current of interest is such that it increases by one if there is a transition in the clockwise direction ($1 \rightarrow 2, \ 2 \rightarrow 3, \ and \ 3 \rightarrow 1$) and it
decreases by one if there is a transition in the counter clockwise direction. The time-dependent modified generator for this current reads
\[
\mathbf{L}_t(z) = \begin{pmatrix}
-w_{12}(t) - w_{13}(t) & w_{21}(t)e^{-z} & w_{31}(t)e^{z} \\
-w_{12}(t)e^{z} & -w_{21}(t) - w_{23}(t) & w_{32}(t)e^{-z} \\
w_{13}(t)e^{-z} & w_{23}(t)e^{z} & -w_{31}(t) - w_{32}(t)
\end{pmatrix}.
\]

We calculated the average current \(J\) and diffusion coefficient \(D\) using equations (24) and (25), respectively. The fundamental matrix \(\mathcal{M}(z)\) was evaluated with numerical solution of equation (16). In figure 2 we show that both quantities show perfect agreement with results obtained from Monte Carlo simulations. Note that the sign of the current depends on the rate constant \(w\) that determines the speed of the transitions in relation to the period \(\tau\): for large enough \(w\) the current becomes negative. We have used a discrete-time algorithm for our simulations with a sufficiently small time-step, a continuous-time algorithm for time-dependent transition rates can be found in [38].

4.3. Biased random walk with time-periodic affinity

In this section, we consider a biased random walk on a ring with \(\Omega\) states driven by a time-periodic affinity
\[
F(t) \equiv F \cos(2\pi t/\tau).
\]
The transition rate for a jump in the clockwise direction is given by
\[
w_+(t) = w \exp[\psi F(t)/\Omega],
\]
whereas the transition rate for a jump in the anti-clockwise direction is
\[
w_-(t) = w \exp[(\psi - 1) F(t)/\Omega],
\]
where \(0 \leq \psi \leq 1\). The parameter \(\psi\) determines how \(F(t)\) influences forward and backward rates. We consider the current in the ring, which increases by one if a
jump in the clockwise direction takes place and decreases by one if a jump in the
anti-clockwise direction takes place. For example, for $\Omega = 3$ the modified generator $\mathcal{L}(z)$ takes the form in equation (36) with $w_{12}(t) = w_{23}(t) = w_{31}(t) = w_{+}(t)$ and $w_{21}(t) = w_{32}(t) = w_{-}(t)$.

This model has the peculiar property that the uniform vector $\langle 1 \rangle$ is a left eigenvector of $\mathcal{L}(z)$, for all $t$ and $z$, with eigenvalue

$$\lambda(z) = -w_-(t) - w_+(t) + w_-(t)e^{-z} + w_+(t)e^z. \tag{40}$$

Hence, from the Dyson series of the ordered exponential and equation (17) for $\mathcal{M}(z)$, we obtain

$$\langle 1 | \mathcal{M}(z) = \langle 1 | \exp \left( \int_0^\tau \lambda_t(z) dt \right). \tag{41}$$

Since $\langle 1 \rangle$ is a positive vector, from the Perron–Frobenius theorem, it must be the eigenvector associated with the maximum eigenvalue of $\mathcal{M}(z)$, which leads to $\rho_1(z) = \exp \left( \int_0^\tau \lambda_t(z) dt \right)$. Using equation (20), we then obtain

$$\lambda(z) = \tau^{-1} \int_0^\tau \lambda_t(z) dt. \tag{42}$$

Explicit evaluation of the above integral leads to

$$\lambda(z) = w(1 - e^{-z})[e^z I_0(\psi F_0/\Omega) - I_0(F_0(-1 + \psi)/\Omega)], \tag{43}$$

where $I_0(x)$ is a modified Bessel function of the first kind. Interestingly, the average current in this model is given by

$$J = \lambda'(0) = w[I_0(\psi F/\Omega) - I_0(F(-1 + \psi)/\Omega)]. \tag{44}$$

Even though the thermodynamic affinity integrated over a period is zero, the average current can be non-zero: $J$ is positive for $\psi > 1/2$ and negative for $\psi < 1/2$.

The expression in equation (42) for $\lambda(z)$ in terms of an integral of the maximum eigenvalue associated with $\mathcal{L}(z)$ is valid not only for the above model but for any current related to a modified generator that fulfils the property

$$\langle 1 | \mathcal{L}(z) = \langle 1 | \lambda_t(z), \tag{45}$$

for all $z$ and $t$. Furthermore, from equation (42), if the property (45) is satisfied, the SCGF can be written as

$$\lambda(z) = \tau^{-1} \sum_{ij} \int_0^\tau P^\text{inv}_i(t) [\mathcal{L}(z)]_{ji} dt, \tag{46}$$

where this equation is valid not only for $P^\text{inv}_i(t)$ but for an arbitrary probability distribution. Expression (46) for the evaluation of the SCGF has been proposed in [22] as a general expression for the SCGF. While it is correct for this peculiar case, in general, equation (46) does not provide the correct SCGF. In figure 3, we show that the right hand side of equation (46) is different from the SCGF for the model for a molecular pump from section 4.2.
5. Stochastic protocol

Hitherto we have restricted ourselves to the case of a deterministic protocol. In this section, we consider a system driven by a stochastic protocol, which is cyclic and, therefore, mimics periodicity. We show that a stochastic protocol with a infinitely large number of jumps is equivalent to a deterministic protocol with respect to the large deviations of fluctuating currents.

For a stochastic protocol, the mathematical model is a bipartite Markov process with time-independent transition rates \([11, 33]\). The bipartite Markov process has \(\Omega \times N\) states, where \(N\) is the number of jumps of the external protocol. A state of the bipartite Markov process \((i, n)\) is determined by the variable \(i\) that identifies the state of the system and the variable \(n = 0, 1, \ldots, N - 1\) that identifies the state of the external protocol. The transition rates for a change in the state of the system are defined as

\[
    w_{ij}^n \equiv w_{ij}(t = n\tau/N),
\]

where \(w_{ij}(t)\) is the transition rate of a corresponding Markov process with time-dependent transition rates that describes a deterministic protocol.

Since the external protocol is stochastic, there is a transition rate associated with changes of the state of the protocol from \(n\) to \(n + 1\). The reversed transition rate is zero. From the periodicity of the protocol, for \(n = N - 1\) the protocol transitions back to \(n = 0\). The transition rate for a change in the protocol is set to \(N/\tau\), hence, the average time for the protocol to complete a cycle is \(\tau\).

The stationary distribution of state \((i, n)\) is denoted \(P^n_i\), where the dependence on the total number of jumps \(N\) is not shown for a compact notation. The conditional probability of state \(i\) given that the protocol is in state \(n\) is \(P(i|n) = P^n_i/P^n\), where \(P^n = \sum_i P^n_i = 1/N\) is the stationary probability that the protocol is at state \(n\). As shown in [33], in the limit of \(N \to \infty\), the stationary distribution of the bipartite Markov

\[\tfrac{\textit{SCGF}}{\text{Eq. (46)}}\]

Figure 3. Comparison between SCGF obtained with the formalism from section 3 and the right hand side of equation (46). These results were obtained for the model from section 4.2 with \(\tau = 1\) and \(w = 5\).
process is equivalent to the invariant periodic distribution of the corresponding Markov process with time-periodic transition rates, i.e. $P(i|n) \to P^{\text{inv}}_i(t)$, where $\tau n/N \to t$.

A stochastic trajectory of the bipartite process, from time 0 to time $T'$, is denoted by $(A, \Xi)_0^{T'}$, where $A$ represents the state of the system and $\Xi$ represents the state of the protocol. A generic current, analogous to the current in equation 13, can be obtained from the tilted generator $\mathcal{L}(z)$ [33], which is a matrix with dimension $N \times \Omega$ given by

$$
\mathcal{L}(z) = \begin{pmatrix}
I_N & I_N/T & \cdots & I_N/T \\
I_N/T & L(x)_0(z) - I_N/T & \cdots & 0 \\
0 & I_N/T & L(x)_2(z) - I_N/T & \cdots \\
\vdots & \vdots & \vdots & \vdots \\
0 & 0 & 0 & \cdots & L_{\text{inv}}^{N} (z) - I_N/T \\
\end{pmatrix},
$$

where $I$ is the identity matrix with dimension $\Omega$ and $L_{\text{inv}}$ is equivalent to the tilted generator from equation (13) with $\theta_{ij}^0$ instead of $\theta_{ij}(t)$.

The maximal eigenvalue associated with (49) is written as $\Lambda_N(z)$. We now show that $\lim_{N \to \infty} \Lambda_N(z) = \lambda(z)$. The right eigenvector associated with $\Lambda_N(z)$ is written as $\bar{v}_N(z)$. From the equation $\mathcal{L}(z)\bar{v}_N(z) = \Lambda_N(z)\bar{v}_N(z)$ and equation (49) we obtain

$$
\frac{N}{\tau} \left[ v^n_i(z) - v^{i-1}_n(z) \right] = \sum_j \left[ \mathcal{L}_{\text{inv}}(z) \right]_{ij} v^n_j(z) - \Lambda_N(z) v^n_i(z),
$$

where $v^n_i(z)$ are the components of $\bar{v}_N(z)$. We omit the dependence of these components on $N$ for a compact notation. This equation can be written in the form

$$
\frac{N}{\tau} \left( |v(z)|_n - |v(z)|_{n-1} \right) = \mathcal{L}_{\text{inv}}(z) |v(z)|_n - \Lambda_N(z) |v(z)|_n,
$$

where $|v(z)|_n$ is vector with dimension $\Omega$ and components $v^n_i(z)$. In the limit $N \to \infty$, we set $n \tau/N \to t'$ and $|v(z)|_n \to |\bar{v}(z)|_{t'}$. Since for $n = N-1$ the stochastic protocol jumps back to $n = 0$, by construction $|\bar{v}(z)|_{t'} = |\bar{v}(z)|_{t'+\tau}$. For $N \to \infty$, the vectorial form of equation (51) then becomes

$$
\frac{d}{dt'} |\bar{v}(z)|_{t'} = \left[ \mathcal{L}_{t'}(z) - \lim_{N \to \infty} \Lambda_N(z) \right] |\bar{v}(z)|_{t'}.
$$

The formal solution of this equation reads

$$
|\bar{v}(z)|_{t'} = \exp \left( - t' \lim_{N \to \infty} \Lambda_N(z) \right) \hat{\exp} \left( \int_0^{t'} \mathcal{L}_u(z) du \right) |\bar{v}(z)|_0.
$$

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Using the periodicity of the eigenvector, i.e. $|\overline{v}(z)\rangle_\tau = |\overline{v}(z)\rangle_0$ and setting $t' = \tau$, we obtain

$$\mathcal{M}(z)|\overline{v}(z)\rangle_\tau = \exp\left(\tau \lim_{N \to \infty} \Lambda_N(z)\right) |\overline{v}(z)\rangle_\tau,$$

(54)

where $\mathcal{M}(z)$ is the fundamental matrix defined in equation (15). Since by construction $|\overline{v}(z)\rangle_\tau$ is positive, from the Perron–Frobenius theorem $\exp(\tau \lim_{N \to \infty} \Lambda_N(z))$ is the maximal eigenvalue associated with $\mathcal{M}(z)$, i.e.

$$\lambda(z) = \lim_{N \to \infty} \Lambda_N(z).$$

(55)

In figure 4 we provide two numerical illustrations, one with the model from section 4.2 and the other with the model section 4.3, of the convergence of the SCGF for a stochastic protocol with increasing $N$ towards the SCGF for a deterministic protocol. There is no generic inequality between $\Lambda_N(z)$ and $\Lambda(z)$.

6. Discussion

For systems driven by an external periodic protocol, which are well described by Markov processes with time-periodic transition rates, large fluctuations of a thermodynamic current can now be determined with the formalism developed in section 3. In particular, the SCGF can be evaluated by calculating the maximum Floquet exponent associated with the fundamental matrix $\mathcal{M}(z)$. Cumulants such as the average current $J$ and the diffusion coefficient $D$ can also be directly evaluated from this matrix, which provides a numerical method that can be more efficient than Monte Carlo simulations for small systems. Mathematically, beyond fluctuating currents, our formalism also applies to generic observables that count the number of jumps with increments that do not have to be anti-symmetric.

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We have calculated analytically the SCGF in two models: a heat engine with piecewise constant protocol and a biased random walk with a time-periodic affinity. Furthermore, we have verified our theoretical results by showing agreement between results obtained from numerical evaluation of the maximal Floquet exponent and results obtained from Monte Carlo simulations for a model for a molecular pump.

The SCGF associated with a stochastic protocol with an infinitely large number of jumps is equivalent to the SCGF associated with a deterministic protocol, as proved in section 5. This proof provides a rigorous basis to the idea that periodically driven systems can be analyzed with the use of stochastic protocols, i.e. if a result about current fluctuations is valid for stochastic protocols than it should be valid for deterministic protocols, which can be obtained as a particular limit of a stochastic protocol. The advantage of working with stochastic protocols is that the system and protocol together form a bipartite Markov process with constant transition rates that reach a nonequilibrium stationary state, which are quite well known.

### Appendix A. Work and related currents

A fluctuating current of interest in stochastic thermodynamics is the work done on the system due to the time variation of the energy levels. For jump processes, such current can be written in the form

$$X'[A_T^0] = \int_0^T f_a(t) dt,$$

(A.1)

where $f_a(t) = \partial_t g_i(t)$ and $g_i(t)$ is periodic with period $\tau$. For the case of work $g_i(t)$ is the free energy of state $i$.

The empirical density $\rho_i(t)$ and the empirical flow $C_{ij}(t)$ are the number of periods for which the trajectory is in state $i$ at time $t \in [0, \tau]$ and the number of transitions from $i$ to $j$ at time $t$, respectively. They are functionals of the stochastic trajectory from time 0 to time $T = n \tau$ that are defined as

$$\rho_i(t) = \frac{1}{n} \sum_{k=0}^n \delta_n(k\tau + t),$$

(A.2)

and

$$C_{ij}(t) = \frac{1}{n} \sum_{k=0}^n \delta_n(k\tau + t) - \delta_n(k\tau + t) \delta_n(k\tau + t) + j.$$

(A.3)

As shown in [24], in the large deviation regime, they fulfill the constraint

$$\frac{d}{dt} \rho(i, t) = \sum_j [C_{ji}(t) - C_{ij}(t)],$$

(A.4)

for every single stochastic trajectory. Moreover, both $C_{ij}(t)$ and $\rho_i(t)$ are periodic with period $\tau$.

Using the empirical density in equation (A.2) we can rewrite equation (A.1) as
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$$X'\left[ A_0^T \right] = n \sum_i \int_0^\tau \partial_t g_i(t) \rho_i(t) dt,$$

(A.5)

where we used $f_i(t) = \partial_t g_i(t)$. From the constraint in equation (A.4) and the definition of the empirical flow in equation (A.3), we obtain

$$X'\left[ A_0^T \right] = \sum_{0 \leq t \leq n\tau} \left( f_i(a_i^+) - f_i(a_i^-) \right),$$

(A.6)

which is a current of the form given in equation (5). Hence, the current in equation (A.1) can be written as in equation (5) if $f_i(t) = \partial_t g_i(t)$. This relation also holds for a stochastic protocol [11]. In general, if $f(t)$ is not a derivative of a periodic function, this relation may not hold. Whereas extending the results from section 3 to such a case should be straightforward, as we have done for diffusion processes in appendix B, proving the equivalence with stochastic protocols for this more general current remains an open challenge.

**Appendix B. Diffusion processes**

We consider a $d$-dimensional diffusion process $Y_t$ that follows the Fokker–Planck equation

$$\partial_t \mu_t(y) = \mathcal{L}_t \left[ \mu_t \right](y)$$

(B.1)

where $\mu_t(y)$ is the probability density at time $t$ and the adjoint of the generator is given by

$$\mathcal{L}_t^\dagger = \hat{F}_t \nabla + \nabla \frac{D_t}{2} \nabla$$

(B.2)

where $\hat{F}_t$ is a time-periodic the drift vector, $D_t$ is a time-periodic diffusion matrix, $\tau$ is the period, and $\nabla$ is the nabla operator. This generator is then time-periodic. Hence, the invariant probability density related to the long time limit has the property

$$\mu_{inv}^t(y) = \mu_{inv}^t + \tau \int_0^\tau f_t(y) \rho_{inv}^\tau(y)dy + \int J_{\rho_{inv},t}^\tau(y)g_t(y)dy,$$

(B.3)

where we use $\circ$ for the Stratonovich convention, $f_t = f_{t+\tau}$ is a scalar function, and $g_t = g_{t+\tau}$ is a vector field. The Fokker–Planck current associated with $\rho_{inv}^t$ is a vector

$$J_{\rho_{inv},t}(y) = \hat{F}_t(y)\rho_{inv}^t(y) - \frac{1}{2} D_t(y) \left( \nabla \rho_{inv}^t(y) \right).$$

(B.4)

The typical behavior of $X \left[ Y_0^{n\tau} \right]$ is given by

$$\lim_{n \to \infty} \frac{X \left[ Y_0^{n\tau} \right]}{n\tau} = \frac{1}{\tau} \int_0^\tau dt \left( \int \rho_{inv}^t(y) f_t(y)dy + \int J_{\rho_{inv},t}(y)g_t(y)dy \right).$$

(B.5)

The SCGF is defined as
\[
\lambda(z) \equiv \lim_{n \to \infty} \frac{1}{nT} \ln \langle \exp [zX_{nT}] \rangle.
\]  
(B.6)

Using the Feynman–Kac formula and the Grinasov lemma it can be shown that [39]
\[
\langle e^{zX} \delta(Y_T - y')|Y_0 = y \rangle = \left[ \hat{\exp} \left( \int_0^{nT} dt \mathcal{L}_t(z) \right) \right] (y', y),
\]  
(B.7)

where the tilted generator \( \mathcal{L}_t(z) \) is the second order differential operator of the form
\[
\mathcal{L}_t(z) = zf_t + \hat{F}_t (\nabla + zg_t) + (\nabla + zg_t) \frac{D_t}{2} (\nabla + zg_t).
\]  
(B.8)

Equation (B.7) is analogous to equation (19) for jump processes. The fundamental operator is defined as
\[
\mathcal{M}(z) \equiv \hat{\exp} \left( \int_0^{\tau} dt \mathcal{L}_t(z) \right).
\]  
(B.9)

From equation (B.7), this operator is also a Perron–Frobenius operator. Similar to the case for jump processes, \( \mathcal{M}(z) \) can be expanded in the form given by equation (18). The real maximum eigenvalue of \( \mathcal{M}(z) \) is denoted \( \rho_1(z) \). Following the same procedure for a jump process one can define a Laplace transform of the probability of current, analogous to equation (11) (with an integral instead of a sum). The time evolution of this Laplace transform follows equation (14). Hence, the SCGF \( \lambda(z) \) can be expressed in terms of the maximum eigenvalue \( \rho_1(z) \) through the formula
\[
\lambda(z) = \frac{1}{\rho_1(z)} \left( \frac{1 - e^{-\tau w_k^+}}{e^{\theta w_k^+}} + \frac{1 - e^{-\tau w_k^-}}{e^{-\theta w_k^-}} \right).
\]  
(C.2)

where \( w_k = w_k^+ + w_k^- \). The fundamental matrix for a piecewise protocol in equation (21) is a product of the matrices in equation (C.2). Expressing the maximum eigenvalue of the two by two fundamental matrix in terms of its trace and determinant, and using the Abel–Jacobi–Liouville identity for the determinant.

Appendix C. Exact expressions for two-state model with piecewise constant protocol

We consider a generic two-state model with a piecewise constant protocol (see [35] for similar calculations for a protocol with two pieces). The transition rates during the interval \( \tau_k \) are denoted by \( w_k^+ \) and \( w_k^- \), where \( w_k^+ \) is the transition rate from state 1 to state 2. The increment of the current from state 1 to state 2 during the interval \( \tau_k \) is \( \theta_k \) and the increment for the reversed transition is \( -\theta_k \). The piecewise version of the modified generator reads
\[
\mathcal{L}_k(z) = \begin{pmatrix}
-w_k^+ & w_k^+ e^{-z \theta_k} \\
-w_k^- e^{z \theta_k} & w_k^-
\end{pmatrix}.
\]  
(C.1)

From this matrix, we obtain
\[
\exp \left( -\tau_k \mathcal{L}_n(z) \right) = \frac{1}{w_k^+} \begin{pmatrix}
e^{-\tau_k w_k^+} w_k^- + w_k^+ & e^{-z \theta_k} (1 - e^{-\tau_k w_k^-}) w_k^- \\
e^{\theta_k} (1 - e^{-\tau_k w_k^+}) w_k^+ & w_k^+ + e^{-\tau_k w_k^-} w_k^-
\end{pmatrix},
\]  
(C.2)
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\[
\det(\mathcal{M}(z)) = \exp\left(\int_0^\tau \text{Tr}(\mathcal{L}_t(z)) \, dt\right) = \prod_{n=0}^{N-1} e^{-\tau_k w_{nk}}, \quad (C.3)
\]

we obtain the following expression for the SCGF

\[
\lambda(z) = \frac{1}{\tau} \ln \left[ \frac{\text{Tr}(\mathcal{M}(z)) + \sqrt{[\text{Tr}(\mathcal{M}(z))]^2 - 4 \prod_{n=0}^{N-1} e^{-\tau_k w_{nk}}}}{2} \right]. \quad (C.4)
\]

Hence, we can calculate \(\lambda(z)\) from the trace of the fundamental matrix in equations (21) with (C.2). In particular, for \(N = 2\) the trace of the fundamental matrix is given by

\[
\text{Tr}(\mathcal{M}(z)) = 4e^{-(\tau_0 w^0 + \tau_1 w^1)/2} \sinh(w^0 \tau_1/2) \sinh(w^1 \tau_1/2) \left[ q^0_+ e^{\theta_1 - \theta_0} + q^0_- e^{(\theta_1 - \theta_0)} \right] + (e^{-\tau_0 w^0} q^0_+ + q^0_-) (e^{-\tau_1 w^1} q^1_+ + q^1_-) + (q^0_+ e^{-\tau_0 w^0} q^1_- + q^1_+ e^{-\tau_1 w^1}), \quad (C.5)
\]

where \(q^0_\pm \equiv w^0_\pm / w^0\) and \(q^1_\pm \equiv w^1_\pm / w^1\).

For the model for a heat engine in section 4.1 the protocol has \(N = 4\) pieces. Since the changes in temperature are instantaneous, this number is reduced to \(N = 2\), with \(\tau_0 = \tau_1 = \tau/2\). The transition rates for this model \(w^0_\pm = we^{-\beta_1 E/2}\), \(w^1_\pm = we^{-\beta_2 (E + \Delta E)/2}\), and \(w^0_\pm = we^{\beta_1 (E + \Delta E)/2}\), \(w^1_\pm = we^{\beta_2 (E + \Delta E)/2}\). For the current \(X_q\) the increments, are \(\theta^0_q = 0\) and \(\theta^1_q = \beta_2(E + \Delta E)\). For the current \(X_e\) the increments are \(\theta^0_e = 0\) and \(\theta^1_e = -1\).

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