Does robotic-assisted unicompartmental knee arthroplasty have lower complication and revision rates than the conventional procedure? A systematic review and meta-analysis

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ABSTRACT

Objective We conducted this systematic review and meta-analysis of studies on patients who underwent unicompartmental knee arthroplasty (UKA) to compare the complication rates, revision rates and non-implant-specific complications between robotic-assisted and conventional UKA.

Design Systematic review and meta-analysis.

Data sources The PubMed, Embase, Web of Science and Cochrane databases were searched up to 30 June 2020.

Eligibility criteria Case–control studies comparing robotic-assisted and conventional UKA.

Data extraction and synthesis Data from all eligible articles were independently extracted by two authors. We analysed the differences in outcomes between robotic-assisted and conventional UKA by calculating the corresponding 95% CIs and pooled relative risks (RRs). Heterogeneity was assessed using the χ² and I² tests. All analyses were performed using the ‘metafor’ package of R V3.6.2 software.

Results A total of 16 studies involving 50 024 patients were included in the final meta-analysis. We found that robotic-assisted UKA had fewer complications (RR: 0.52, 95% CI: 0.28 to 0.96, p=0.036) and lower revision rates (RR: 0.42, 95% CI: 0.20 to 0.86, p=0.017) than conventional UKA. We observed no significant differences in non-implant-specific complications between the two surgical techniques (RR: 0.80, 95% CI: 0.61 to 1.04, p=0.96). No publication bias was found in this meta-analysis.

Conclusions This study provides evidence that robotic-assisted UKA is safer and is associated with lower revision rates than conventional UKA; however, owing to important limitations, the results lack reliability, and more studies are required.

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INTRODUCTION

Unicompartmental knee arthroplasty (UKA) is often performed for treating isolated compartmental knee osteoarthritis owing to its minimally invasive nature and less bone resection required during surgery.

However, higher rates of revision surgery (10%–20%) have been reported in patients undergoing UKA than in those undergoing total knee arthroplasty.1 There could be multiple reasons for the higher failure rate, including poor patient selection and component design, whereas some authors have identified malpositioning as the cause.2 The use of robotic systems, which offer promising short-term radiological outcomes of implants and precision in bone cuts, during UKA has considerably increased. Currently, approximately 15%–20% of UKA surgeries are being performed with the assistance of robotic systems, with improved clinical efficacy.3 Most experts believe that robotic-assisted UKA provides significantly better component angle alignment accuracy and functional outcomes, as well as higher patient satisfaction, than conventional UKA. However, there are considerable variations in the complication rates than the conventional procedure. A systematic review and meta-analysis. BMJ Open 2021;11:e044778. doi:10.1136/bmjopen-2020-044778
and revision rates reported in previous studies, which make it difficult to estimate the safety outcomes of the two surgical techniques.4,5

Previous meta-analyses have compared the effects and safety of robotic-assisted and conventional UKA. In a meta-analysis by Fu et al, it was reported that robotic-assisted UKA showed no decrease in the rate of adverse events compared with conventional UKA. However, few articles (only seven studies) were included in the meta-analysis, and the difference in the revision rates between the two techniques was not reported.6 Another meta-analysis by Zhang et al contradicted the conclusion about adverse events by Fu et al, reporting instead that robotic-assisted UKA could significantly reduce the rate of complications; however, the results were also subject to limitations in sample size and follow-up duration, which might influence the assessment of the difference in outcomes between robotic-assisted and conventional UKA.4 Another recent meta-analysis did not reach a definitive conclusion about complications.5 Therefore, we conducted this systematic review and meta-analysis of studies on patients who underwent UKA to compare the complication rates, revision rates and non-implant-specific complications between robotic-assisted and conventional UKA. We hypothesised that there would be no obvious differences in complication and revision rates between the two techniques.

METHODS

Search strategy
We searched the PubMed, Web of Science, Embase and Cochrane databases using combinations of the following keywords: ‘unicompartmental knee arthroplasty’, ‘UKA’, ‘conventional UKA’, ‘traditional UKA’, ‘manual UKA’, ‘robotic-assisted UKA’, ‘non-robotically assisted UKA’, ‘complications’, ‘adverse events’ and ‘revision’ (last updated on 30 June 2020). The references of the identified reports were also retrieved and reviewed to find other related studies. All studies were carefully and repeatedly evaluated. The study period, treatment information, hospital and any additional inclusion criteria were used to identify duplicate or overlapping data.

Inclusion and exclusion criteria
Studies that met the following criteria were considered eligible for inclusion in this study: (1) original studies about UKA, (2) studies that compared robotic-assisted and conventional UKA, (3) studies that provided controls and effective data (including randomised controlled trials (RCTs), prospective cohort trials, case–control studies and retrospective comparative studies) and (4) studies published in English. The exclusion criteria were as follows: (1) studies published as talks, reviews, digests, letters, commentaries or case reports; (2) model-based or cadaver studies; (3) duplicate or overlapping studies; and (4) not case–control studies.

Data extraction and quality assessment
The data from all eligible articles were independently extracted by two authors, who discussed any disagreements to reach a consensus. The data retrieved from each study included the first author’s name, year of publication, country, methods, number of patients, follow-up duration, complications, revision rate and non-implant-specific complications. Three experienced reviewers used the modified Newcastle-Ottawa quality assessment scale to evaluate the quality of the selected studies. A score of 9 was assigned to studies of superior quality, between 6 and 8 to high-quality studies, between 3 and 5 to moderate-quality studies and <3 to low-quality studies.7

Statistical analysis
We analysed the differences in outcomes between robotic-assisted and conventional UKA by calculating the corresponding 95% CIs and pooled relative risks (RRs). Heterogeneity was assessed using the $\chi^2$ and I $^2$ tests. Fixed-effect models were employed when there was no significant heterogeneity ($I^2 \leq 50\%$, $p>0.10$); otherwise, a random-effects model was used to obtain the pooled effects among the included studies. Galbraith plots were used to detect potential sources of heterogeneity.8 Normal quantile–quantile (Q–Q) plots were used to check for deviation of data from the CI. Outlier and influence analyses were performed by inspecting the plots for externally standardised residues, DFFITS values, Cook’s distances, covariance ratios, estimates of $\tau^2$, test statistics for residual heterogeneity when each study was excluded in turn, hat values, and weights for each study included in the analysis.9 Publication bias was assessed by inspecting a contour-enhanced funnel plot, with contours at 90%, 95% and 99% CIs. All analyses were performed using the ‘metafor’ package of R V.3.6.2 software.10 A two-tailed $p$ value of $<0.05$ was considered statistically significant.

Patient and public involvement
There was no patient and public involvement in this systematic review.

RESULTS

Study characteristics
We initially identified 374 studies through the search of the PubMed, Embase, Web of Science and Cochrane databases. Of these, 322 studies did not meet the inclusion criteria and were excluded after reviewing the titles and abstracts. Of the 52 remaining studies that were subjected to a full-text review, 28 were excluded because they were not comparative studies. In addition, eight full-text articles were excluded for the following reasons: (1) data were incomparable or incomplete and (2) data about complications were not available. Finally, 16 studies involving 50 024 patients were included in the final meta-analysis. The flow diagram of study selection is presented in figure 1. Table 1 summarises the main characteristics of the 16 included studies. The quality assessment of the
Complications that lead to failure of UKA include bearing dislocation, aseptic loosening, polyethylene wear, periprosthetic fracture, progression of arthritis to the contralateral compartment, infection, bone-implant impingement, retained cement debris in the joint, knee ankylosis, wound complications, deep haematoma, infection, thrombosis, persistent pain and pin-site infection and fracture in our meta-analysis. The \( \chi^2 \) and I\(^2\) test results indicated no statistical heterogeneity among the included studies (p=0.49, I\(^2\)=0.00%) and Galbraith plots (figure 4A) and Q–Q plots (figure 4B) also showed no statistical heterogeneity. We observed no significant differences in non-implant-specific complications between the two groups in comparisons using a fixed-effects model (RR: 0.80, 95% CI: 0.61 to 1.04, p=0.96; figure 4C).
Table 1  Main characteristics of all articles included in the meta-analysis

| Order | Studies          | Year | Country | Design       | No. knees RA-UKA | Follow-up (month) | Complication | Revision | Robot systems          | Function scoring system             |
|-------|------------------|------|---------|--------------|------------------|-------------------|--------------|----------|-------------------------|-------------------------------------|
| 1     | Cobb et al\(^{25}\) | 2006 | UK      | RCT          | 19               | 4.5               | 1            | Null     | Acrobot system (Acrobot) | AKSS, WOMAC                       |
| 2     | Lonner and Moretti\(^{13}\) | 2010 | USA     | PCT          | 31               | 3                 | 1            | Null     | Tactile Guidance System (MAKO) | Null                                |
| 3     | Hansen et al\(^{14}\) | 2014 | USA     | Case-control | 30               | 24                | 7            | 0        | RIO System (MAKO)         | Recovery time first, ambulation     |
| 4     | MacCallum et al\(^{23}\) | 2016 | USA     | PCT          | 87               | 32.4              | 3            | 7        | RIO System (Stryker Mako) | Null                                |
| 5     | Blyth et al\(^{15}\) | 2017 | UK      | RCT          | 64               | 12                | 1            | Null     | Acrobot system (Acrobot) | AKSS                                |
| 6     | Gilmour et al\(^{20}\) | 2018 | UK      | RCT          | 58               | 24                | 0            | 2        | RIO System (MAKO)         | AKSS, OKS, FJS, pain VAS            |
| 7     | Kayani et al\(^{31}\) | 2018 | UK      | PCT          | 60               | 1                 | 2            | Null     | RIO System (MAKO)         | Null                                |
| 8     | Batailler et al\(^{22}\) | 2018 | France  | Case-control | 80               | 19.7              | 4            | 3        | Navio system (Smith and Nephew) | IKSS                                |
| 9     | Canetti et al\(^{33}\) | 2018 | France  | Retrospective cohort | 11               | 39.3              | 0            | 2        | Navio system (Smith and Nephew) | IKSS                                |
| 10    | Banger et al\(^{34}\) | 2019 | UK      | RCT          | 74               | 60                | 0            | 2        | RIO System (MAKO)         | AKSS, JFS, pain VAS, stiffness, VAS, OKS |
| 11    | Wong et al\(^{16}\) | 2019 | USA     | Retrospective cohort | 58               | 3                 | 7            | 7        | RIO System (MAKO)         | SF-12, WOMAC, KSFS                  |
| 12    | Cool et al\(^{19}\) | 2019 | USA     | Retrospective comparative study | 246              | 24                | 2            | 2        | Null                    | Null                                |
| 13    | Kayani et al\(^{35}\) | 2019 | UK      | PCT          | 73               | 3                 | 0            | 2        | RIO System (MAKO)         | Pain scores, opiate analgesia, straight leg raise, knee flexion |
| 14    | Vakharia et al\(^{17}\) | 2019 | USA     | Retrospective comparative study | 13 617           | 36                | 125          | 125     | Null                    | Null                                |
| 15    | Mergenthaler et al\(^{26}\) | 2020 | France  | Case-control | 200              | 24                | 19           | 8        | Navio system (Smith and Nephew) | KSS score                           |
| 16    | St Mart et al\(^{18}\) | 2020 | Australia | Retrospective comparative study | 2851             | 46                | 47           | 47      | Mako-assisted Restoris (MAKO) | Null                                |

PCT, prospective cohort trial; RA-UKA, robotic-assisted unicompartmental knee arthroplasty; RCT, randomised controlled trial.
and accuracy of UKA, possibly leading to fewer complications and lower revision rates.\textsuperscript{13} Many studies have evaluated the complications of robotic-assisted UKA; however, there are few studies on the complications of robotic-assisted UKA compared with those with conventional UKA. Researchers have reported conflicting results about the complication rates between robotic-assisted and conventional UKA. Hansen \textit{et al} and Blyth \textit{et al} did not find a significant difference in the rate of complications between the two techniques.\textsuperscript{14,15} Wong \textit{et al} found that the robotic-arm-assisted arthroplasty cohort had a higher early revision rate than the conventional group, whereas other studies reported that robotic-assisted UKA had fewer complications and lower revision rates than conventional UKA.\textsuperscript{16–18} It is important to assess the complications of this new technology before it can be widely used.\textsuperscript{19} Therefore, we conducted this systematic review and meta-analysis to compare the complication rates, revision rates and non-implant-specific complications between robotic-assisted and conventional UKA. The main finding of our meta-analysis was that robotic-assisted UKA has fewer complications and lower revision rates than conventional UKA; however, there were no significant differences in non-implant-specific complications. Thus, our study confirms that robotic-assisted UKA has fewer complications and lower revision rates than the conventional procedure.

Many studies have explored the relationship between the component position and its impact on implant survival and patient satisfaction.\textsuperscript{20,21} Some authors believe that a reduction in alignment errors of these components will ultimately affect implant function or survival.\textsuperscript{22} Some studies confirmed that the proportion of patients with tibial and femoral component implantation within 2° of the target position was significantly greater in the group

![Figure 2](A) Galbraith plot, (B) quantile–quantile (Q–Q) plot and (C) forest plot for the comparison of complications between robotic-assisted and conventional unicompartmental knee arthroplasty (UKA).

![Figure 3](A) Galbraith plot, (B) quantile–quantile (Q–Q) plot and (C) forest plot for the comparison of revision rate between robotic-assisted and conventional unicompartmental knee arthroplasty (UKA).
Figure 4  (A) Galbraith plot, (B) quantile–quantile (Q–Q) plot and (C) forest plot for the comparison of non-implant-specific complications between robotic-assisted and conventional unicompartmental knee arthroplasty (UKA).

Figure 5  Contour-enhanced funnel plots of the included studies showing no evidence of publication bias in complications (A), revision rate (B) and non-implant-specific complications (C).
that underwent robotic-assisted UKA, resulting in better long-term clinical scores and a lower implant failure rate.\textsuperscript{20,23,24} Therefore, it could be inferred that the use of a robotic-assisted system in UKA can reduce implantation errors, leading to fewer complications and lower rates of revision surgery than conventional UKA. Although non-implant-specific complications are likely to be related to the procedure, fewer complications were considered to be directly related to the comparative study itself.\textsuperscript{25} Mergenthaler et al reported no complications related to the use of the robotic system.\textsuperscript{26} Pearle et al suggested that no further rigid fixation device is necessary, which reduces potential complications such as infection, iatrogenic fractures or soft tissue injury caused by the weight and movement of the robot.\textsuperscript{27} However, there were no significant differences in non-implant-specific complications between the two techniques in our meta-analysis. Therefore, there is no evidence that the use of robotic systems can add to the non-implant-specific complications of UKA.

Although robotic-assisted UKA is widely performed and is the current trend in orthopaedic surgery, it has some shortcomings. Robotic-assisted UKA was found to significantly prolong the duration of surgery compared with conventional UKA (online supplemental figure S1). Some studies have also documented that robotic-arm-assisted UKA has a higher cost.\textsuperscript{28,29} In addition, the device-related complications, such as pin-site fracture and infection, are non-negligible. We checked all articles included in the meta-analysis for a statement on funding or conflicts of interest related to the work. When such a statement was provided, we categorised the study as an industry-funded study or involving authors with financial conflicts of interest. We found that the included articles were more likely to be industry funded or written by authors with financial conflicts of interest (online supplemental figure S2). Therefore, this information should not be overlooked, and more large-scale, non-commercially supported studies evaluating the efficacy of the two treatments in this patient population are needed in the future.

This meta-analysis has several limitations. First, long-term revision rates depend on the duration of follow-up; however, all included studies had a short follow-up period (3–60 months). Hence, the data on revision rates are not reliable. Future studies with a longer follow-up duration, preferably 10 years, are necessary to assess complications and revision rates. Second, some studies were not RCTs and had a small sample size, which increase the possibility of publication bias. Therefore, our results should be further confirmed by large-scale RCTs. Third, the types of robotic-assisted UKA performed in each study were different, as shown in table 1. The different types of robotic systems used were the Acrobat, RIO or Mako-assisted Restoris and Navio systems. Rapid advances in robotic-assisted technology have led to improvements in UKA over the past 10 years. Implant position, soft tissue balance and radiographic component alignment

Figure 6 Outlier and influence analyses. The standardised residuals (rstudent), DFFITS (dffits), Cook’s distances (cook.d), covariance ratios (cov.r), estimates of τ² (tau2.del) and test statistics (QE.del) for the random-effects model that was used for the analysis of the complications are shown.
seem to have gradually improved with the development of robotic-assisted systems. Considering the evolution of this technology and its possible impact on outcomes, well-designed studies are necessary to advance the understanding of the impact of different robotic systems. Fourth, all included studies were limited to the English literature; therefore, some related studies published in other languages that might have met the inclusion criteria could have been missed. Fifth, most of the studies in our meta-analysis did not report pin-site and device-specific complications. Revision surgeries secondary to pin-site fracture were reported in some studies; however, the sample size was small. Therefore, we did not conduct a systematic analysis on these specific complications and revisions. Although we attempted to identify and retrieve all additional unpublished information, some missing data were inevitable. In addition, our results were not adjusted for other factors that could influence complications, such as patient age and weight, anterior cruciate ligament status, soft tissue balance and composition and thickness of the polyethylene component. Sixth, some of the included studies did not mention the reasons for loss to follow-up or lack details about revision surgery. However, these might have no effect on the analysis. Finally, when events such as complications and revisions occur over a non-fixed period, it is common to use HRs as the statistic of interest. As the ‘metafor’ package has no function for using HRs as the statistic of interest, we used RRs as the statistic of interest across all studies.

CONCLUSIONS

To summarise, this meta-analysis study indicates that robotic-assisted UKA is associated with fewer complications and lower rates of revision surgery than conventional UKA. No evidence suggests that the use of robotic systems might increase the rate of non-implant-specific complications of UKA.

Therefore, the study provides evidence that robotic-assisted UKA has fewer complications and lower revision rates than conventional UKA; however, owing to important limitations, the results lack reliability, and more studies are required.

Contributors YS conceived the study and wrote the manuscript. WZ analysed the data. WL generated data. XH and JH reviewed the manuscript.

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Competing interests None declared.

Patient consent for publication Not required.

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