The exact solution of the mean geodesic distance for Vicsek fractals

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Abstract

Vicsek fractals are one of the most interesting classes of fractals and the study of their structural properties is important. In this paper, the exact formula for the mean geodesic distance of Vicsek fractals is found. The quantity is computed precisely through the recurrence relations derived from the self-similar structure of the fractals considered. The obtained exact solution exhibits that the mean geodesic distance approximately increases as a power-law function of the number of nodes, with the exponent equal to the reciprocal of the fractal dimension. The closed-form solution is confirmed by extensive numerical calculations.

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(Some figures in this article are in colour only in the electronic version)
A central issue in the study of complex systems is to understand how their dynamical behaviors are influenced by underlying geometrical and topological properties [18, 19]. Among many fundamental structural characteristics [20], mean geodesic distance is an important topological feature of complex systems that is often described by graphs (or networks) where nodes (vertices) represent the component units of systems and links (edges) stand for the interactions between them [21, 22]. Mean geodesic distance is defined as the mean length of the shortest paths between all pairs of nodes. It has been well established that mean geodesic distance directly relates to many aspects of real systems, such as signal integrity in communication networks, the propagation of beliefs in social networks or of technology in industrial networks. Recent studies indicated that a number of other dynamical processes are also relevant to mean geodesic distance, including disease spreading [23], random walks [24], navigation [25], to name but a few. Thus far great efforts have been made to valuate and understand the mean geodesic distance of different systems [26–31].

Despite the importance of this structural property, to the best of our knowledge, the rigorous computation for the mean geodesic distance of Vicsek fractals has not been addressed. To fill this gap, in this present paper we investigate this interesting quantity analytically. We derive an exact formula for the mean geodesic distance characterizing the Vicsek fractals. The analytic method is on the basis of an algebraic iterative procedure obtained from the self-similar structure of Vicsek fractals. Our research opens the way to theoretically studying the mean geodesic distance of regular fractals and deterministic networks [33–35].

The classical Vicsek fractals are constructed iteratively [12, 15]. We denote by $V_{f,t}$ ($t \geq 0, f \geq 2$) the Vicsek fractals after $t$ generations. The construction starts from ($t = 0$) a star-like cluster consist of $f + 1$ nodes arranged in a crosswise pattern, where $f$ peripheral nodes are connected to a central node. This corresponds to $V_{f,0}$. For $t \geq 1$, $V_{f,t}$ is obtained from $V_{f,t-1}$. To obtain $V_{f,1}$, we generate $f$ replicas of $V_{f,0}$ and arrange them around the periphery of the original $V_{f,0}$, then we connect the central structure by $f$ additional links to the corner copy structures. These replication and connection steps are repeated $t$ times, with the required Vicsek fractals obtained in the limit $t \to \infty$, whose fractal dimension is $\frac{\ln(f+1)}{\ln 3}$. In figure 1, we schematically show the structure of $V_{4,2}$. According to the construction algorithm, at each time step the number of nodes in the systems increase by a factor of $f + 1$, thus, we can easily know that the total number of nodes (network order) of $V_{f,t}$ is $N_t = (f + 1)^{t+1}$.
After introducing the Vicsek fractals, we now analytically investigate the mean geodesic distance between all the node pairs in the fractals by using a method similar to but different from that proposed in [9]. We represent all the shortest path lengths of $V_{f,t}$ as a matrix in which the entry $d_{ij}$ is the geodesic distance from node $i$ to node $j$, where geodesic distance is the path connecting two nodes with minimum length. The maximum value $D_t$ of $d_{ij}$ is called the diameter of $V_{f,t}$. A measure of the typical separation between two nodes in $V_{f,t}$ is given by the mean geodesic distance $L_t$ defined as the mean of geodesic lengths over all couples of nodes

$$L_t = \frac{S_t}{N_t(N_t - 1)/2},$$

where

$$S_t = \frac{1}{2} \sum_{i \in V_{f,t}, j \in V_{f,t}, i \neq j} d_{ij}$$

denotes the sum of the geodesic distances between two nodes over all pairs.

We continue by exhibiting the procedure of the determination of the total distance and present the recurrence formula, which allows us to obtain $S_{t+1}$ of the $t+1$ generation from $S_t$ of the $t$ generation. By construction, the fractal $V_{f,t+1}$ is obtained by the juxtaposition of $f+1$ copies of $V_{f,t}$ that are consecutively labeled as $V_{f,t}^{(1)}$, $V_{f,t}^{(2)}$, ..., $V_{f,t}^{(f+1)}$, see figure 2. This obvious self-similar structure allows us to calculate $S_t$ analytically. It is easy to see that the total distance $S_{t+1}$ satisfies the recursion relation

$$S_{t+1} = (f + 1)S_t + \Theta_t,$$

where $\Theta_t$ is the sum over all shortest path length whose endpoints are not in the same $V_{f,t}$ branch. The solution of equation (3) is

$$S_t = (f + 1)^tS_0 + \sum_{m=0}^{t-1} [(f + 1)^{t-m-1}\Theta_m].$$

Thus, all that is left to obtain $S_t$ is to compute $\Theta_m$. 

Figure 2. A schematic illustration of the iterative construction for $V_{f,t+1}$, which is obtained by joining $f+1$ copies of $V_{f,t}$ denoted as $V_{f,t}^{(1)}$, $V_{f,t}^{(2)}$, ..., $V_{f,t}^{(f+1)}$, respectively.
The paths that contribute to $\Theta_t$ must all go through at least one of the $2^f$ edge nodes (such as $G, X, Y$ and $Z$ in figure 2) at which the different $V_{f,t}$ branches are connected. The analytical expression for $\Theta_t$, named the crossing path length [9], can be derived as below.

Denote $\Theta_t^{\alpha,\beta}$ as the sum of all shortest paths with endpoints in $V_{f,t}^{(\alpha)}$ and $V_{f,t}^{(\beta)}$. For convenience, we denote by $V_{f,t}^{(1)}$ the central branch of $V_{f,t+1}$. According to whether or not the two branches are adjacent, we sort the crossing path length $\Theta_t^{\alpha,\beta}$ into two classes: $\Theta_t^{|\phi|}$ ($\phi > 1$), $\Theta_t^{|\phi|}$ ($\phi > 1$, $\theta > 1$, and $\phi \neq \theta$). For any two crossing paths in the same class, they have identical length. Therefore, in the following computation of $\Theta_t$, we will only consider $\Theta_t^{1,2}$ and $\Theta_t^{2,3}$. The total sum $\Theta_t$ is then given by

$$\Theta_t = f \times \Theta_t^{1,2} + \frac{f(f-1)}{2} \times \Theta_t^{2,3}.$$  \hspace{1cm} (5)

To calculate the crossing path length $\Theta_t^{1,2}$ and $\Theta_t^{2,3}$, we give the following definition and notations. We define external nodes of $V_{f,t}$ as the nodes that will be linked to one of its copes at step $t+1$ to form $V_{f+1,t}$. Let $d_t$ denote the sum of length of the path from an external node of $V_{f,t}$ to all nodes in $V_{f,t}$, including the external node itself. We assume that the two branches $V_{f,t}^{(1)}$ and $V_{f,t}^{(2)}$ are connected at two nodes $X$ and $G$, which separately belong to $V_{f,t}^{(1)}$ and $V_{f,t}^{(2)}$, and that $V_{f,t}^{(1)}$ and $V_{f,t}^{(3)}$ are linked to each other at two nodes $Y$ and $Z$ that are in $V_{f,t}^{(1)}$ and $V_{f,t}^{(3)}$, respectively.

In order to determine $d_t$, we should compute the diameter $D_t$ of $V_{f,t}$ first. By construction, one can see that the diameter $D_t$ equals the path length between arbitrary pair of external nodes of $V_{f,t}$. Thus, we have the following recursive relation:

$$D_{t+1} = 3D_t + 2.$$  \hspace{1cm} (6)

Considering the initial condition $D_0 = 2$, equation (6) is solved inductively to obtain

$$D_t = 3^{t+1} - 1,$$  \hspace{1cm} (7)

which is independent of $f$.

We now calculate the quantity $d_{t+1}$. Let $K$ denote the external node of $V_{f,t+1}$, which is in the branch $V_{f,t}^{(2)}$. By definition, $d_{t+1}$ can be given by the sum

$$d_{t+1} = \sum_{j \in V_{f,t+1}} d_K_j = \sum_{u \in V_{f,t}^{(2)}} d_K_u + \sum_{v \in V_{f,t}^{(1)}} d_K_v + (f-1) \sum_{w \in V_{f,t}^{(3)}} d_K_w = d_t + \sum_{v \in V_{f,t}^{(1)}} d_K_v + (f-1) \sum_{w \in V_{f,t}^{(3)}} d_K_w.$$  \hspace{1cm} (8)

We denote the second and third terms in equation (8) by $g_t$ and $q_t$, respectively. Thus, $d_{t+1} = d_t + g_t + q_t$. The quantity $g_t$ is evaluated as follows:

$$g_t = \sum_{u \in V_{f,t}^{(1)}} (d_{K_G} + d_{G_X} + d_{X_v}) = d_t + N_t \times (D_t + 1),$$  \hspace{1cm} (9)

where $d_{KG} = D_t$ and $d_{GX} = 1$ were used. Analogously, $q_t = (f-1) \sum_{w \in V_{f,t}^{(3)}} (d_{KG} + d_{GX} + d_{XY} + d_{YZ} + d_{ZW}) = (f-1)[d_t + N_t \times 2(D_t + 1)].$  \hspace{1cm} (10)

With equations (9) and (10), equation (8) becomes

$$d_{t+1} = (f + 1) d_t + (2f - 1) \times N_t \times (D_t + 1).$$  \hspace{1cm} (11)

\[\text{J. Phys. A: Math. Theor. 41 (2008) 485102} \]
Using \( N_t = (f + 1)^t - 1 \) and \( g_0 = 2f + 1 \), equation (11) is resolved by induction
\[
d_t = \frac{1}{2}(2f - 1)(3^{r + 1} - 1) (1 + f)^t.
\] (12)

With above obtained results, we can determine the length of crossing paths \( \Theta_1^{1,2} \) and \( \Theta_2^{2,3} \), which can be expressed in terms of the previously explicitly determined quantities. By definition, \( \Theta_1^{1,2} \) is given by the sum
\[
\Theta_1^{1,2} = \sum_{i \in V_1, j \in V_2} d_{ij}
= \sum_{i \in V_1, j \in V_2} (d_{iX} + d_{XG} + d_{Gj})
= N_t \sum_{i \in V_1} d_{iX} + (N_t)^2 + N_t \sum_{j \in V_2} d_{Gj}
= 2N_t \sum_{i \in V_1} d_{iX} + (N_t)^2,
\] (13)

where we have used the equivalence relation \( \sum_{i \in V_1} d_{iX} = \sum_{j \in V_2} d_{Gj} \).

Proceeding similarly,
\[
\Theta_2^{2,3} = \sum_{i \in V_2, j \in V_3} d_{ij}
= \sum_{i \in V_2, j \in V_3} (d_{iG} + d_{GX} + d_{XY} + d_{YZ} + d_{Zj})
= 2N_t \sum_{i \in V_2} d_{iG} + (N_t)^2 + 2N_t \sum_{j \in V_3} d_{iG} + (N_t)^2 d_{XY}
= 2N_t \sum_{i \in V_2} d_{iG} + (N_t)^2 (D_t + 2).
\] (14)

Inserting equations (13) and (14) into equation (5), we have
\[
\Theta_t = (f^2 + f) N_t d_t + f^2 (N_t)^2 + \frac{f(f - 1)}{2} (N_t)^2 D_t.
\] (15)

Substituting equation (15) into equation (4) and using the initial value \( S_0 = f^2 \), we can obtain the exact expression for the total distance
\[
S_t = \frac{1}{6f + 4} (f + 1)^t f^2 (f + 1)^t (3^{r + 1} + 1)
+ 3(3^{r + 1} - 1) f^2 (f + 1)^t + 4((f + 1)^t - 1)
- 2 f (3^{r + 1} (f + 1)^t - 4(1 + f)^t + 1).
\] (16)

When \( f = 2 \), the Vicsek fractals are reduced to a one-dimensional linear chain. In this case, \( S_t \) expressed by equation (16) can be simplified as \( S_t = \frac{(3^{r + 1} - 1)(3^{r + 1} + 1)}{6} = \frac{N_t - 1}{N_t - 1} \), which recovers the previously obtained result for linear chain [32]. In addition, for other values of \( f \), we have also compared equation (16) with the results of direct numerical computation, both of which are consistent with each other, see table 1.
Figure 3. Mean geodesic distance \( L_t \) versus network order \( N_t \) on a log–log scale. The solid lines serve as guides to the eye.

Table 1. Sum of geodesic distance \( S_t \) for various \( f \) and \( t \). All \( S_t \) are obtained by both equation (16) and numerical simulations, which completely agree with each other.

| \( f \) | \( S_0 \) | \( S_1 \) | \( S_2 \) | \( S_3 \) |
|---|---|---|---|---|
| 2 | 4 | 120 | 3276 | 88 560 |
| 3 | 9 | 516 | 25 872 | 1258 560 |
| 4 | 16 | 1480 | 117 400 | 8962 000 |
| 5 | 25 | 3390 | 389 700 | 42 928 920 |
| 6 | 36 | 6720 | 1055 460 | 158 449 536 |

Then the analytic expression for the mean geodesic distance can be obtained as

\[
L_t = \frac{1}{(3f^2 + 5f + 2)[(f + 1)^t + 1]} \left[ f^2(f + 1)^t(3^t + 1) 
+ 3(3^t - 1)f^3(f + 1)^t + 4((f + 1)^t - 1) - 2f(3^t(f + 1)^t - 4(1 + f)^t + 1) \right]. \tag{17}
\]

In the infinite system size, i.e., \( t \to \infty \)

\[
L_t \sim 3^t = (N_t)^{\ln 3 \over \ln (f + 1)}, \tag{18}
\]

where the exponent \( \frac{\ln 3}{\ln (f + 1)} \) is equal to the reciprocal of the fractal dimension. Thus, in the large limit of \( t \), the mean geodesic distance \( L_t \) is proportional to the diameter \( D_t \), both of which increase algebraically with increasing size of the system. In contrast to many recently studied network models mimicking real-life systems in nature and society [21, 22], the Vicsek fractals are not small worlds despite of the fact that these fractals show similarity (fractality) observed in many real-world systems.

We have checked our analytic result against numerical calculations for different \( f \) and various \( t \). In all the cases we obtain a complete agreement between our theoretical formula and the results of numerical investigation, see figure 3.

To sum up, in complex systems the mean geodesic distance plays an important role. It has a profound impact on a variety of crucial fields, such as information processing, disease
or rumor transmission, network designing and optimization. In this paper, we have derived analytically the solution for the mean geodesic distance of Vicsek fractals which have been attracting much research interest. Our analytical technique could guide and shed light on related studies for deterministic fractals and network models by providing a paradigm for calculating the mean geodesic distance. Moreover, as a guide to and a test of approximate methods, we believe our vigorous solution can prompt the studies on random fractals.

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