Shell–mediated tunnelling between (anti–)de Sitter vacua

Stefano Ansoldi
Center for Theoretical Physics - Laboratory for Nuclear Science and Department of Physics, Massachusetts Institute of Technology and International Center for Relativistic Astrophysics (ICRA) - Pescara - ITALY

Lorenzo Sindoni
International School for Advanced Studies, SISSA/ISAS via Beirut, 2-4 — I-34014 Miramare, Trieste (TS), ITALY and INFN, Sezione di Trieste

We give an extensive study of the tunnelling between arbitrary (anti-)de Sitter spacetimes separated by an infinitesimally thin relativistic shell in arbitrary spacetime dimensions. In particular, we find analytically an exact expression for the tunnelling amplitude. The detailed spacetime structures that can arise are discussed, together with an effective regularization scheme for before tunnelling configurations.

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I. INTRODUCTION

The study of vacuum decay initiated more than 30 years ago with the work of Callan and Coleman \[1, 2\]; in the following years the interest in the subject increased and the possible interplay of true vacuum bubbles with gravitation was also studied \[3, 4\], together with bubbles collisions and their importance in the early universe \[5, 6\]. At the same time, and as opposed with the true vacuum bubbles of Coleman et al., false vacuum bubbles were also considered. In connection with gravity, the behavior of regions of false vacuum, first studied by Sato et al. \[7, 8, 9, 10, 11, 12\], was for example analyzed in \[13, 14\]. For additional papers analyzing it in the context of inflation, we refer the reader to \[21, 22, 23\]; interesting links with more phenomenologically oriented approaches can also be drawn, as witnessed, for instance, by the recent \[24\].

In these last works, a minisuperspace approximation was adopted to quantize the system. In more detail, since general relativistic shells\(^1\) can be used as a convenient model and since in spherical symmetry the system only has one degree of freedom, standard semiclassical methods might be suitable to analyze the decay process (see \[25\] for an early, in principle, discussion of this point). In connection with cosmology, spaces equipped with a cosmological constant (i.e. de Sitter space and generalizations) have been naturally considered. In this context it also worth to remark the important role that they play in connection with the problem of gravitational entropy, causal structure and the presence of horizons (see, for instance \[26, 27, 28, 29, 30\] as well as the suggestive \[31\]).

Notwithstanding many interesting results, after 30 years, and with different flavors, the problem of the stability of (the de Sitter) vacuum in connection with the dynamics of false vacuum bubbles, is still a debated one \[15, 32, 33\].

The still open issues are highly non-trivial and go back to the, also long lasting, problem of formulating a consistent framework for a quantum theory of gravity \[34, 35, 36, 37, 38, 39, 40\], but we will not take explicitly this point of view here. We will instead analyze a specific situation, described below, in which the nucleation rate can be computed exactly in arbitrary spacetime dimensions. We will, then, explicitly compute in closed form the nucleation rate in the semiclassical approximation, compare it with existing results, and discuss in detail the associated spacetime structures: an analysis of how quantum effects may be relevant in the context of tunnelling from nothing configurations \[41\] will also be given. These results, extend some results present in the literature (for instance \[42, 43, 44\]) and can also provide a useful limiting case of more general situations, for instance those discussed in \[33\]. At the same time, to consider spacetimes of higher dimensionality and negative cosmological constant is especially important in view of recent results in the context of the AdS/CFT correspondence \[45\] and of the braneworld cosmological scenario \[46, 47\] (see also \[48\] and references therein for a study in the context of noncommutative branes).

Apart from the papers already cited above, the instanton approach has also been discussed by other authors (see for instance \[49, 50, 51\]) and although it will not be directly related to the present paper, we cannot avoid mentioning the suggestive relationship between the decay of the cosmological constant, membranes generated by higher rank gauge potentials and black holes.

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\(^1\) Electronic address: ansoldi@trieste.infn.it
URL: http://www-dft.ts.infn.it/~ansoldi
\(^2\) (Mailing address) Dipartimento di Matematica e Informatica - Università degli Studi di Udine, via delle Scienze 206, I-33100 Udine (UD), Italy; INFN, Sezione di Trieste, Trieste, Italy

\(^{1}\) In this paper we will use interchangeably the terms shell, bubble and brane, which in different epochs have appeared in the literature to designate the system under consideration.
which have appeared in many papers in the literature.

The structure of the paper is the following: in section [I] we recall the formalism by which a general relativistic thin spherical brane/shell can be described; this also gives us the opportunity to fix conventions and notations and briefly describe the canonical approach to its semiclassical quantization (subsection [II C]), a convenient dimensionless formalism is also introduced (subsection [II D]). We then directly come (section [III]) to the main result of this paper, which is the calculation of the tunnelling rate between the classical configurations of the system, in arbitrary spacetime dimensions; the results for the cases of 3, 4 and 5 spacetime dimensions are explicitly presented with dedicated plots of the values of the action as a function of the two dimensionless parameters of the model (subsection [III C]). The exact results for the tunnelling amplitude/probability calculated in section [III] correspond to specific transitions which take place in spacetime and that will be discussed later on, in a dedicated appendix. We discuss, instead, in the main text (section [IV]) a proposal to regularize some spacetime configurations which appear to be singular, relating this issue to the description of the brane energy-matter content. In the concluding section [V] the results of the paper are summarized; two appendices follow with the detailed description of the parameter space of the system (appendix [A]) and of all the Penrose diagrams associated with different values of the parameters of the problem (appendix [B]): they are crucial to fully grasp the physical system under consideration.

II. SHELL IN N + 1 DIMENSIONS

In this section we are going to briefly review some results about the dynamics of co-dimension one branes in an (N + 1)-dimensional spacetime, where, under the words co-dimension one brane, we understand an N-dimensional hypersurface Σ separating the (N + 1)-dimensional manifold in two domains, M− and M+, having Σ as a common part of their boundary: in brief ∂M− ∩ ∂M+ = Σ. In what follows we are going to use the clear notation of [68]; the formulation developed there can be readily extended to higher dimensions, just by letting the indices run on an extended set of values. We will thus quickly report this paraphrase with the purpose of recalling some notations and conventions. In particular let us choose two arbitrary systems of N+1 independent vector fields E±(a) in M±, respectively, with dual forms Ω±(a). Denoting with g(±) the four dimensional metric tensors in the two manifolds we can write²,

\[ g(±) = g(±)a_Ω^{(a)}ab Ω^{(b)} \]

in our notation Latin indices a, b (as well as all other Latin indices) will vary in the set \{0, 1, 2, . . . , N\}.

Let us first concentrate our attention on Σ: it is also a manifold, as M±, and we will denote by e(µ) an N-dimensional system of (commuting) independent vector fields on Σ, with dual system ω(µ); the indices µ and ν (as well as all other Greek indices) will vary in the set \{0, 1, . . . , N − 1\}. Because of the physical interpretation we will be interested in the case in which Σ is embedded as a timelike surface in M±. Since Σ is timelike the normal to Σ in M± is a spacelike vector n, which we choose normalized so that \langle n, n \rangle = 1. Moreover, our convention is that the normal points from the “−” side. More generally, the normal points from the “±” domain of spacetime.

The components of n (an unambiguously defined non-null vector) will be different, in general, when measured by an observer in M− or by one in M+, according to the following definition:

\[ n_± = \langle n, E(a) \rangle \pm = \langle n, E±(a) \rangle \]

In terms of n the extrinsic curvature of the surface Σ can be expressed as³

\[ K_{µν} = \langle n, \nabla e(µ) e(ν) \rangle \]

and, in general, it is different on the − and + side. Moreover, by the Gauss-Codazzi formalism, the geometry of spacetime around Σ can be described in terms of the intrinsic geometry of the hypersurface and of its extrinsic curvature. In the spirit of this formalism, let us denote by h the intrinsic metric of the hypersurface Σ, i.e.

\[ h = h_{µν} ω(µ) \otimes ω(ν) \]

When we will work with quantities defined in the bulk we will need to distinguish the ones defined in M+ from the ones defined in M−, and to this end we will use, as we did above, “±” superscripts or subscripts. In many cases we will also be interested in the jump of these quantities across Σ: for instance, if we consider the extrinsic curvature, we may need the to consider the difference \[ K^+_{µν} - K^-_{µν} \]; following [63, 64] we are going to rewrite this difference as \[ [K_{µν}] \]. Throughout this paper this will be the only meaning that we will give to the square brackets, i.e.

\[ [A] \equiv A^+ - A^- \]

To avoid confusion no other use of the square brackets will be done.

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² In a few equations below, we will use the notation \langle −, − \rangle to denote the scalar product. We also anticipate the notation \nabla Y X for the covariant derivative of the vector field X in the direction of the vector field Y.

³ We stress the normalization condition on n.
A. Junction conditions

The brane $\Sigma$ can be more than just a mathematical surface, *i.e.* we can (and, in most of the cases, we want to) equip it with a matter-energy content: it is then an infinitesimally\(^4\) thin distribution of matter-energy. Thanks to the above mentioned Gauss-Codazzi formalism, we can rewrite Einstein equations to make explicit the contribution from the localized matter. Then, the dynamics of $\Sigma$ as a surface separating $\mathcal{M}_+$ from $\mathcal{M}_-$ is obtained solving the following system of equations,

$$K^+_{\alpha\beta} - K^-_{\alpha\beta} \equiv [K_{\alpha\beta}] = 8\pi G_{N+1} (S_{\alpha\beta} - h_{\alpha\beta} S/2) ; \quad (1)$$

these are Israel’s junction conditions [63, 64] which relate the “jump” in the extrinsic curvature $[K_{\mu\nu}]$, *i.e.* the “jump” in the way the surface is embedded in each geometry, to the stress-energy tensor $S_{\mu\nu}$ of the matter contained on $\Sigma$. The tensor $S$ must also satisfy a conservation equation,

$$((N)\nabla, S)_{\mu} = \left[T(n, e_{(\mu)})\right],$$

where $T$ is the stress energy tensor describing the content of the complete spacetime manifold. Once we have specified the matter content of the bulk (and hence the geometry according to Einstein equations) the description of the dynamics of the system is obtained by solving the system of equations [11]: we refer the reader to [63] and [64] for additional material and related considerations.

B. Spherical symmetry

The set-up that is of interest for us is a simplified one, in which all the system is spherically symmetric and the surface stress-energy tensor is that of the, so called, tension model, with

$$S = -\kappa h,$$

where $\kappa > 0$ is a constant called the tension of the brane. In what follows, it will be convenient to also define

$$\tilde{\kappa} = 4\pi(N - 2)G_{N+1}\kappa.$$

Thanks to the spherical symmetry, the system of equations [11] can then be reduced to a single equation [67],

$$R \left( \epsilon_- \sqrt{\tilde{R}^2 + f_-(R)} - \epsilon_+ \sqrt{\tilde{R}^2 + f_+(R)} \right) = \tilde{\kappa} \tilde{R}^2 ; \quad (2)$$

in the above, $f_\pm(r_\pm)$ are the metric functions of the static line element adapted to the spherical symmetry, *i.e.* taking the four dimensional case as a convenient example, we choose in both $\mathcal{M}_\pm$ the coordinate system $x^a_\pm = (t_\pm, \theta_\pm, \phi_\pm, r_\pm)$ corresponding to the basis vectors $e_{t_\pm}$, $e_{\theta_\pm}$, $e_{\phi_\pm}$ and $e_{r_\pm}$, such that the metric is reduced to the form $g(\pm)_{ab} = \text{diag}(-f_\pm(r_\pm), r_\pm^2, r_\pm^2 \sin^2 \theta_\pm, 1/f_\pm(r_\pm))$. Generalizations to spacetimes with higher dimensionality are just more cumbersome to write but trivial in their substance. In these coordinate systems, we denote the radius of the brane by $R(\tau)$, where $\tau$ is the proper time of an observer comoving with the brane and an over-dot denotes the derivative with respect to $\tau$. Moreover, as anticipated in the introduction, we consider that this $N$-dimensional brane separates two $(N + 1)$-dimensional spacetimes of the de Sitter/anti-de Sitter type, in general with different cosmological constants $\Lambda_{\pm}$. We thus have

$$f_\pm(r_\pm) = 1 - \frac{2\Lambda_{\pm}}{N(N - 1)} r_\pm^2.$$

Finally $\epsilon_\pm$ are signs, defined as

$$\epsilon_\pm(R) = \text{sign}((n, e_{r_\pm}))/_{r_\pm=R}$$

and are crucial quantities to obtain the Penrose diagrams associated with the considered brane configuration.

C. The effective action/the momentum

Before proceeding with the analysis of the physical system that we introduced in the previous subsection, we believe it is useful to recall some important points about the structure of the junction conditions in spherical symmetry. For a generic junction between spherically symmetric spacetimes across a (spherical) brane carrying matter described by a given, but otherwise arbitrary, equation of state, it would prove very useful to extract an effective action for the dynamics of the brane starting directly from the Einstein-Hilbert action and from a suitable action for the matter fields and the brane [67]. This is the content of a consistent literature on the subject [68, 69, 70, 71, 72, 73, 74, 75, 76, 77, 78] among which we would like to single out the more general, and recent, [77]: the problem is not trivial at all, because of the same subtleties that appear, for instance, in the Hamiltonian formulation of General Relativity. Among the various possible approaches we will closely follow the quantization procedure originally proposed by Farhi, Guth and Guven [16], which has, lately, been followed also in [67] and [78]. For the Lagrangian approach to the classical dynamics we will instead follow the clear and more general exposition of [77]. We summarize here the relevant elements of these approaches referring the reader to the literature for additional details. In particular, the effective action for the shell can be obtained starting from the Einstein-Hilbert action with the Gibbons-Hawking

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\(^4\) Strictly speaking $\Sigma$ is a source defined in a distributional way: for additional material on this point, the reader is referred, for instance, to [63].
boundary terms \[16, 77, 79\]. Using the Gauss-Codazzi formalism \[80\], it is readily seen that the Einstein-Hilbert action for a spherical co-dimension one brane (which in our case will separate two domains of (anti--)de Sitter spacetime) can be decomposed in non-dynamical bulk contributions (indeed, we consider the geometry of the bulk spacetimes \(\mathcal{M}_\pm\) fixed) and a dynamical boundary contribution described in terms of the extrinsic curvature of the brane \(\Sigma\). It is enlightening (and, perhaps, necessary) not to use all the freedom in fixing the coordinate systems. As an exemplification we do not use the freedom given by the reparametrization invariance with respect to the proper time of the brane and we, thus, introduce a lapse function \(\mathcal{N}(s)\), so that the brane induced metric can be written as \(h_{\mu\nu}^{(N)} = \text{diag}( -\mathcal{N}(s)^2, R^2(s), \ldots)\) in the coordinates \((s, R, \ldots)\) (the “…” stand for the trivial spherically symmetric part). Then, following \[67, 77\], the effective action for the degrees of freedom associated with the radial and time coordinates takes the form

\[
S_{\text{eff}} \propto \int \left\{ R^{N-2} \left[ \epsilon \sqrt{R^2 + \mathcal{N}^2 f(R)} - \mathcal{N} \arctanh \left( \frac{\mathcal{N}}{\epsilon \sqrt{R^2 + N^2 f(R)}} \right) \right] - \kappa \mathcal{N} R^{N-1} \right\} d\tau. \tag{3}
\]

Thus, the effective Lagrangian of the system is given by

\[
\mathcal{L} = P^{(N)} \dot{R} - \mathcal{H},
\]

where, following \[67\], we have defined the effective Hamiltonian as

\[
\mathcal{H} = -R^{N-2} \left[ \epsilon \sqrt{R^2 + \mathcal{N}^2 f(R)} \right] + \kappa \mathcal{N} R^{N-1}
\]

and the effective momentum as

\[
P^{(N)}(R, \dot{R}) = -R^{N-2} \left[ \arctanh \left( \frac{\mathcal{N}}{\epsilon \sqrt{R^2 + N^2 f(R)}} \right) \right] \tag{4}
\]

Then, the equations of motion for the \(R\) and \(\mathcal{N}\) degrees of freedom are

\[
\frac{d\mathcal{H}}{d\tau} = \frac{\mathcal{N}}{N} \mathcal{H} \quad \text{and} \quad \mathcal{H}(R, \dot{R}, \mathcal{N}) = 0;
\]

the second equation is a first integral of the former one, and is the \textit{Hamiltonian constraint}. We see that it encodes all the information about the dynamics of the system, being identical to the only remaining junction condition. The first equation is the second order equation of motion of the system, given by the total derivative with respect to the proper time of the Hamiltonian constraint. In what follows, we will be mostly interested in the expression of the momentum evaluated on a solution of the equation of motion. In order to build a canonical structure (as it is done, for example, in \[40\]) we first have to prove the existence of a well defined symplectic structure on the phase space of the Lagrangian system; in particular the Legendre transform has to be invertible, which in our case means nothing but the invertibility of the conjugate momentum as a function of the velocity \[81\]. As appreciated already in \[16\], for generic co-dimension one branes this cannot be proved to be always satisfied\(^5\). However, for the system under consideration the canonical structure always exists and \(P^{(N)}\) can rigorously be considered the canonical momentum conjugate to the coordinate \(R\); thus, in the specific case of interest here, the canonical construction of the corresponding quantum theory is a well posed problem. To prove this statement, let us consider

\[
\frac{\partial P^{(N)}}{\partial R} = -R^{N-2} \left[ \frac{1}{\epsilon \sqrt{R^2 + N^2 f(R)}} \right].
\]

This quantity can be zero if and only if two conditions are simultaneously satisfied:

1. \(\epsilon_+ = \epsilon_-\);

\(^5\) In these cases the quantum theory cannot be built with the canonical formalism. Alternative formulations using the path integral approach have been considered in the seminal work of Farhi, Guth and Guven \[16\].
2. there is a point $R$ in the configuration space such that $f_+(R) = f_-(R)$.

For our particular choice of branes in (anti-)de Sitter spacetime, we see that in order for the second condition to hold we must have $\Lambda_- = \Lambda_+$; but this implies $\epsilon_+ = -1$, $\epsilon_- = +1$ so that the first condition then fails. Thus, for the class of junctions that we are considering one can always build a canonical structure.

### D. Dimensionless formalism

Following, for instance, [82], it is possible to determine the classical dynamics of the system by studying an equivalent one dimensional problem for the radial degree of freedom $R$, taking also into account the values of the signs $\epsilon_\pm(R)$.

Before proceeding we will set up a different system of dimensionless quantities, in order to remove the arbitrariness in the definition of the normalization of the cosmological constants and of the bubble’s tension. If we define the quantities

\[
x = \kappa R, \\
\bar{\tau} = \kappa \tau, \\
\lambda_\pm = \frac{2\Lambda_\pm}{\kappa^2 N(N-1)},
\]

\[
\alpha = \lambda_- + \lambda_+, \\
\beta = \lambda_- - \lambda_+,
\]

equation (2) then becomes

\[
- \left[\epsilon \sqrt{\dot{x}^2 + 1 - \lambda x^2}\right] x = x^2. \tag{5}
\]

For completeness we also report the dimensionless form of the effective momentum [1] when we impose the gauge choice $N \equiv 1$:

\[
P(x, \dot{x}) = -x^{N-2} \left[ \epsilon \arctanh \left( \frac{\dot{x}}{\sqrt{\dot{x}^2 + f(x)}} \right) \right]. \tag{6}
\]

This quantity will be central in what follows, but for the moment we keep our attention on equation (5). Despite its unusual look, it is easily proved that it is equivalent to a system of equations, which, in the notation that we are using, takes the form

\[
\begin{cases}
\dot{x}^2 + \bar{V}(x) = 0 \\
\epsilon_{\pm}(x) = -\text{sgn}(\beta \pm 1)
\end{cases} \tag{7}
\]

where the potential $\bar{V}(x)$ has a simple parabolic form

\[
\bar{V}(x) = 1 - \frac{x^2}{x_0^2} \tag{8}
\]

and $x_0$, the turning point, is given by

\[
x_0^2 = \frac{4}{1 + 2\alpha + \beta^2}, \tag{9}
\]

when the right-hand side is positive; otherwise there are no nontrivial classical solutions. All the solutions of the problem can be easily classified in according to the values of $\alpha$ and $\beta$: we refer the reader to appendix [A] for details.

The form of equation (5) for a brane separating two (anti-)de Sitter spacetimes, which, in turn, is responsible for the simple quadratic form of the potential (8), allows exact solution of this particular case. It is, in fact, not difficult to see that (5) has:

1. the trivial solution $x(\bar{\tau}) \equiv 0$, which always exists;
2. the solution

\[
x(\bar{\tau}) = x_0 \cosh \left( \frac{\bar{\tau} - \bar{\tau}(0)}{x_0} \right), \tag{10}
\]

which satisfies the initial condition $x(\bar{\tau}(0)) = x_0$; this solution is known as the bounce solution and exists only if the condition

\[1 + 2\alpha + \beta^2 > 0\]

is satisfied.

We also, incidentally, note that

\[
\beta = \pm 1 \iff \frac{1}{x_0^2} = \lambda_+
\]

i.e. when $|\beta| = 1$ the turning point radius coincides with one of the two cosmological horizons, if they exist. We also anticipate that a more careful analysis of the trivial solution $x(\bar{\tau}) \equiv 0$ will be required, since, although it is given to us by the mathematics of the problem, we are mostly interested in its physical role, especially when we will turn on (semiclassical) quantum effects (see section [IV]).

### III. Tunnelling

Using the notation introduced in the last section we can now describe how the semiclassical regime of the
brane dynamics looks like. In particular we can consider the tunnelling between the zero-radius solution towards the bouncing solution (10), and vice versa.

For example in one direction the semiclassical picture is as follows: we have a brane, of very small radius; of course, when it is very small, the quantum properties of its matter content will be non-negligible (we will further discuss this issue later on in section IV) and their interplay with gravity will be non-trivial; although we do not know the full quantum gravity description of the system, we will consider that, thanks to quantum effects, the brane will have a certain probability to tunnel under the potential barrier given by the effective potential $\mathcal{S}$ into the bounce solution. When emerging after the tunnelling quantum effects will likely become less and less important as compared with gravitational ones (and as far as the interaction with the bulk spacetime is concerned), so that the evolution of the brane will closely resemble that of the classical junction. This is not the case in the first stage of the evolution, involving the tunnelling process, and we will try to understand, at least at an effective level, the “responsibilities” of both the quantum and gravitational realms in this process. In particular, quantum effects will be considered in a modification at small scales of the stress-energy tensor (see section IV). Gravitational effects, at small scales, are also present, and described by the geometric character of Israel junction conditions. We think that our description might be able to take into account both these effects, at least within the limits represented by the semiclassical approximation. In this sense, although our treatment will be effective, it will give us the possibility to consistently solve the ambiguity arising at the mathematical level and represented by the $x(\vec{r}) \equiv 0$ solution. We will suggest that, at the semiclas- sical level, a more detailed treatment of both, the quantum and gravitational aspects, is unlikely to be necessary.

A. Tunnelling trajectories

For the system under consideration, tunnelling trajectory can be described by constructing the instanton in the Euclidean sector. The construction of the instanton in the general case is still an unsolved problem: we will follow the approach of [16]; moreover, the problems left open in [16] do not affect the present case. In fact it is easy to see that in our case the instanton describing the tunnelling can always be constructed without the necessity to introduce the pseudo-manifold that in [16] was necessary to deal with multiple covering of points in the Euclidean sector. Moreover the different descriptions of the tunnelling process that were obtained in [16] using the canonical or the path-integral approaches in our case also coincide, because they are consequences of properties of the dynamical variables during the tunnelling trajectory which are not present in the system that we are considering (please, see [54, 55, 56] for a more detailed description of these issues).

In this way we know that the tunnelling can be described directly at the effective level, where, the relevant aspects of the Euclidean junction can be determined by the Wick rotated classical effective system. We thus define $\tau_e = -i\bar{\tau}$; then, denoting with a prime the derivative with respect to $\bar{\tau}_e$, we have that the Euclidean system is obtained with the formal substitutions $\dot{x} \rightarrow ix'$ for the “velocity” and

$$\bar{P} \rightarrow i\bar{P}_e$$

for the momentum (it is not difficult to prove that the above substitution rules are rigorous results and that they can be obtained performing an Euclidean junction, as done, for instance, in [16]). In particular

$$\bar{P}_e(x, x') = -x^{N-2}\left[\arctan\left(\frac{x'}{\epsilon \sqrt{f(x) - (x')^2}}\right)\right].$$

(11)

In this way, the tunnelling process can be modelled using the effective tunnelling trajectory, which solves the Euclidean equation:

$$-(x')^2 + 1 - (x/x_0)^2 = 0.$$  

(12)

The analytic expression of the tunnelling trajectory of a brane expanding from zero radius at Euclidean time $\bar{\tau}_e = 0$ to the bouncing solution is:

$$x(\bar{\tau}_e) = x_0 \sin(\bar{\tau}_e/x_0).$$

The opposite process is then described by

$$x(\bar{\tau}_e) = x_0 \cos(\bar{\tau}_e/x_0),$$

if we assume that at Euclidean time $\bar{\tau}_e = 0$ the brane starts contracting from $x_0$. These two processes occur with certain probabilities, whose amplitudes $A$ can be expressed in the usual semiclassical approximation as

$$A(0 \rightarrow x_0) \propto \exp(-I_e(x)),$$

where $I_e(x)$ is the Euclidean and can be obtained as the integral of the Euclidean momentum evaluated on a solution of the Euclidean equation of motion (12). If, for simplicity, we define

$$I_e[x] = \frac{\Omega_{N-1}}{16\pi G_{N+1}} \frac{1}{k^{N-1}} \bar{I}_e[x],$$

where $\Omega_{N-1}$ is the volume of $S^{N-1}$, then $\bar{I}_e[x]$ can be obtained as

$$\bar{I}_e[x] = \int_0^{x_0} \bar{P}_e(x) dx.$$  

(13)

We stress again that $\bar{P}_e(x)$ is the Euclidean momentum evaluated on a solution of the Euclidean equation of motion and can be obtained by substituting $x' = \sqrt{V(x)}$ in (11). We thus have

$$\bar{P}_e(x) = -x^{N-2}\left[\arctan\left(\frac{2\sqrt{V(x)}}{(\beta + \omega)x}\right)\right].$$
where, to make writing more compact\(^8\), we have introduced the quantities \(\omega_\pm\) defined as \(\omega_\pm = \pm 1\).

Note that in the Euclidean case we have some freedom in appropriately choosing one of the possible branches of the inverse tangent function. Different choices will affect, in general, the result that we obtain for the action. As in \([16]\) we observe that non-careful choices will make the action a discontinuous function of the parameters; this can be seen without difficulties. Preliminarily, let us anticipate that with the symbol “arctan”, we will indicate the branch of the inverse tangent function with range \([-\pi/2, \pi/2]\). Let us then consider \(\beta \neq \omega\) and let us integrate by parts the integral \([13]\). We obtain

\[
\tilde{I}_e[x] = - \left[ x^{N-1} \frac{2\sqrt{V(x)}}{(\beta + \omega)x} \right]_0^{x_0} + \int_0^{x_0} x^{N-1} \frac{d}{x} \left( \arctan \frac{2\sqrt{V(x)}}{(\beta + \omega)x} \right).
\]

Let us now consider the first term above. Clearly, if we chose the branch of the arctan function to be the one with range in \([-\pi/2, \pi/2]\), then we have

\[
\lim_{\beta \to -\omega^-} \left[ x^{N-1} \frac{2\sqrt{V(x)}}{(\beta + \omega)x} \right]_0^{x_0} = -\frac{\omega \pi x_0^{N-1}}{2(N-1)}
\]

but

\[
\lim_{\beta \to -\omega^+} \left[ x^{N-1} \frac{2\sqrt{V(x)}}{(\beta + \omega)x} \right]_0^{x_0} = +\frac{\omega \pi x_0^{N-1}}{2(N-1)},
\]

so that the action develops a discontinuity at \(\beta = -\omega\). This discontinuity can be eliminated if we choose different branches of the inverse tangent functions (please remember that in the expression that we are considering we are using a compact notation to indicate the difference of two inverse tangent functions); in particular the two discontinuities at \(\beta = \pm 1\) can be eliminated by choosing:

1. the branch with range \([-\pi, 0]\) for the arctan function containing quantities of the “\(+\)” spacetime;

2. the branch with range \([-\pi, 0]\) for the arctan function containing quantities of the “\(−\)” spacetime.

Since in our notation “arctan” has range \([-\pi/2, \pi/2]\), this means that in the equations above must be rewritten with the substitutions (\(\Theta\) is the step function)

\[
\arctan(“+”) \rightarrow \arctan(“+”) - \pi \Theta(\beta + 1)
\]

and

\[
\arctan(“−”) \rightarrow \arctan(“−”) - \pi \Theta(\beta - 1);
\]

for the jump of the quantity which appears inside the expression of the Euclidean momentum, this implies the following substitution:

\[
[\arctan] \rightarrow [\arctan] - \pi \Theta(1 - \beta^2).
\]

In this way the action integral is continuous also at the points \(\beta = -\omega\) and is given by the integral

\[
\tilde{I}_e[x] = - \int_0^{x_0} dx x^{N-2} \times \left[ \arctan \frac{2\sqrt{V(x)}}{(\beta + \omega)x} - \pi \Theta(1 - \beta^2) \right]. (14)
\]

After these preliminary considerations, we can proceed to evaluate the tunnelling amplitude in the WKB approximation; as we anticipated and as we will see, in arbitrary spacetime dimensions this result can be expressed analytically in terms of known functions.

**B. General result for the tunnelling amplitude**

To calculate the first contribution to the integral \([14]\) we proceed as follows. As a preliminary step, we observe that it can be written as a difference of two integrals with the same general structure. Let us then consider the two integrals containing the inverse tangent functions: small differences, which do not substantially affect the calculation, can be taken into account by properly using the \(\omega\)’s introduced above, as we already did in the expressions for the momentum. This said, we can perform\(^9\) an integration by parts in \([14]\). The terms evaluated at the limits of integration, which appear in this process, do vanish and by changing the integration variable from \(x\) to \(\zeta = (x/x_0)^2\) (which also transforms the integration domain into the unit interval \((0, 1)\)) we obtain the following expression,

\[
\tilde{I}_e[x] = - \frac{x_0^N}{4(N-1)} \times \left[ \arctan \frac{2\sqrt{V(x)}}{(\beta + \omega)x} - \pi \Theta(1 - \beta^2) \right] + \pi x_0^{N-1} \frac{1}{N-1} \Theta(1 - \beta^2), (15)
\]

\(^8\) In view of the definition of the \(\omega\)’s, and of the meaning of the square brackets, the equation above is a shorthand for \(\tilde{I}_e(x) = -x^{N-2} \left( \epsilon_+ \arctan \frac{2\sqrt{V(x)}}{(\beta + 1)x} - \epsilon_- \arctan \frac{2\sqrt{V(x)}}{(\beta - 1)x} \right)\).

\(^9\) Strictly speaking this can be done only when \(\beta \neq -\omega\). The cases in which \(\beta = -\omega\) are trivial and can be dealt separately; or, more simply, since we already know from the discussion in the previous subsection that the action is continuous, we can just extend it to \(\beta = -\omega\) by continuity.
where
\[ z_\omega = \left(1 - x_0 (\beta + \omega \omega) / 2 \right) \left(1 + x_0 (\beta + \omega \omega) / 2 \right). \] (16)

When \( z_\omega < 1 \) one of the above integrals diverges since there is a pole of the integrand on the domain of integration. On the other hand, it is easy to see that the condition \( z_\omega < 1 \) implies
\[
\frac{x_0^2}{4} (\beta + \omega)^2 < 0
\]
and cannot be realized for any choice of the parameters if a tunnelling trajectory has to exist. The value \( z_\omega = 1 \) can instead be obtained if \( \beta = -\omega \) and we know that the action can be extended by continuity to these values, although the above procedure to calculate the integral is not valid. Thus, under the conditions \( \beta \neq -\omega \), we have that \( z_\omega > 1 \) is satisfied and equation (15) gives
\[
\tilde{I}_c[x] = -\frac{x_0^N}{4(N-1)} \frac{\Gamma(N/2)\Gamma(1/2)}{\Gamma((N+1)/2)} \times
\[
\times \left[ (\beta + \omega) F_1 \left[ 1, \frac{N}{2}, \frac{N+1}{2}, z_\omega \right] \right] + \pi x_0 (\beta+\omega)^2 \Theta(1-\beta^2),
\] (17)
where \( \Gamma \) is the Euler’s gamma function, \( F_1 \) the hypergeometric function. Note that \( x_0 \) depends on \( \alpha, \beta \) and so the first factor of the formula, depending on the number of spacetime dimensions, cannot be ignored even for a qualitative description of the tunnelling amplitude.

C. Some cases of interest

It is useful to specialize the result (17) to particular situations. We are going to do this by considering the cases in which spacetime is three, four and five dimensional. Below we are going to explicitly discuss these three cases. A comparative presentation of the results can be found in the contour plots of figure 1.

We start then with the three dimensional case, which is lower-dimensional gravity; in three spacetime dimensions it seems more clear how to build a quantum theory out of the classical junction conditions [40]. Moreover three dimensional gravity is an interesting system by itself, it allows an easier visualization of some results and can be used for interesting specific toy models. Anyway, in this case we have \( N = 2 \) and we can express \( F_1 \left[ 1, 1; 3/2; x \right] \) in terms of elementary functions as
\[
F_1 \left[ 1, 1; 3/2; y \right] = \frac{\arcsin(\sqrt{y})}{\sqrt{1-y^2}}. \] (18)

Correspondingly the action becomes
\[
\tilde{I}_c = -\frac{x_0^4}{12} \frac{\Gamma(1/2)}{\Gamma(5/2)} \times
\[
\times \left[ (\beta + \omega) \frac{\arcsin(\sqrt{z_\omega})}{\sqrt{1-z_\omega^2}} - \frac{1}{z_\omega^3} \right] \] + \pi x_0 (\beta+\omega)^2 \Theta(1-\beta^2),
\] (19)

The corresponding probability is plotted as a function of \( \beta \) in figure 2 for some non-negative values of \( \alpha \) and in figure 3 for some negative values of \( \alpha \).

Not many comments are necessary, of course, for the four dimensional case, the original arena on which this calculation was performed. Again we can take advantage of a simple expression for the corresponding hypergeometric function
\[
F_1 \left[ 1, 3/2; 2; y \right] = \frac{2}{y\sqrt{1-y}} - \frac{2}{y}, \] (20)

which brings the final result in the form
\[
\tilde{I}_c = -\frac{x_0^2}{4} \times \left[ \text{sgn}(\beta + \omega) \frac{1-(z_\omega)^{1/2}}{z_\omega} - \Theta(1-\beta^2) \right]. \] (21)

The plots of the probability as a function of \( \beta \) can be found in figure 4 for some non-negative values of \( \alpha \) and in figure 5 for some negative values of \( \alpha \). This result is the same as the one obtained in [86] and it also reduces to the one calculated in [3]: it, thus, represents a useful consistency check.

Finally, the five dimensional case is interesting in the context of the Randall-Sundrum scenario. In this case, using
\[
F_1 \left[ 1, 2; 5/2; y \right] = \frac{3}{2y} \left( \frac{\arcsin(\sqrt{y})}{\sqrt{1-y^2}} - 1 \right), \] (22)

the result for the action integral can be put in the following form:
\[
\tilde{I}_c = -\frac{x_0^4}{12} \frac{\Gamma(2/2)}{\Gamma(5/2)} \times \left[ (\beta + \omega) \left( \frac{\arcsin(\sqrt{z_\omega})}{\sqrt{1-z_\omega^2}} - \frac{1}{z_\omega^3} \right) \right] + \pi x_0 (\beta+\omega)^2 \Theta(1-\beta^2),
\] (23)

Again we present two plots of the corresponding probability as a function of \( \beta \); figure 6 shows the behavior for some non-negative values of \( \alpha \), whereas plots for some negative values of \( \alpha \) can be found in figure 7.

IV. DISCUSSION

Up to this point we have discussed the physics of the system rather quickly, focusing mainly on the mathematics necessary to describe the classical and the semiclassical phases. There is still a point which deserves a
detailed discussion, since it involves non-trivial aspects of
the dynamics of the brane. Indeed, the physical process
we have considered is the tunnelling of spacetime, from
a classical situation representing a spacetime containing
a small brane to another classical configuration describ-
ing a bouncing brane. In our picture, the pre-tunnelling
state is represented by the \( x = 0 \) solution of the junction
condition. Although this case might appear rather simple
at first sight and one could be tempted to just state that
the initial state is, for example, the full \( \mathcal{M}_+ \) spacetime
(a point of view which has been taken for example in \cite{67}),
much more care has to be taken. The main reason is that
when \( x = 0 \), the brane's world-volume degenerates to a
curve. Thus, the formalism that we used to describe the
brane breaks down and the analysis that we have made
cannot be considered as rigorous as it is in the case of the
bouncing solutions. As a manifestation of this fundamen-
tal problem, we observe that the equations determining
the \( \epsilon_+ \) signs do not hold for the particular solution \( x = 0 \).
In particular, for this solution the junction condition as
written in \cite{5} does not provide any mean to solve this
problem.

A way out of this situation appears when we reflect on
the fact that this process, although described semiclassical-
ly, is quantum in its true nature. Thus an approxima-
tion of the system which considers it completely classical
before the tunnelling, i.e. in the degenerate configuration,
might be too rough and might require a more careful
consideration. During the tunnelling trajectory, and even
more for the \( x = 0 \) classical solution, quantum effects are
supposed to be, if not dominant, at least relevant enough
to modify the classical picture of the junction.

We will propose here an attempt to address the prob-
lem. Our proposal should be considered a first step fur-
ther, but far from a first principle solution of the com-
plex quantum problem; it just aims to show that the
mathematical and physical aspects of the problem stated
above can be dealt with by giving an effective formulation
for the phenomena that might arise at small scales. At
the same time, although we will just build an effective
model, we will not be very demanding about its main
properties: in this way, hopefully, the model, although
effective, could mimic well enough effects produced by
quantum gravity whatever will be their, still undiscover-
ered, true nature.

In this respect, we would also like to point out the fol-
lowing: i) the main effect of our proposal is to slightly
perturb the effective potential \cite{5} in the tunnelling re-
gion; then, we will ii) show that the perturbed problem
is free from ambiguities and iii) use for the unperturbed
case the results obtained in the perturbed one, when the
perturbation becomes smaller and smaller. To have a
definite model, we will regard the small scale behavior
of the matter composing the brane/shell as the physical
origin for the perturbations (see below). On the other
hand, the consequence of these perturbations in the ef-
fective formulation is completely generic: it is, in fact,
possible to show that other physical motivations, as for
instance the quantum properties of spacetime at small
scales, could be reflected in a similar way in the effective

FIG. 1: Contour plots of the values of the tunnelling probability in 3 (case a), 4 (case b) and 5 (case c) spacetime dimensions in
the \( \beta - \alpha \) plane. The area inside the crosshatched parabola in the bottom of each picture is the region in parameter space where
tunnelling cannot occur since no bounce solutions exists (no tunnel zone). A better understanding of what happens close to
the limiting parabola can be understood from the following figures \cite{5} and \cite{7}. Next to next contours indicate a jump of the
probability of 0.1, with the lightest gray tone indicating the range (0.9, 1.0) and the darkest the range (0.0, 0.1). The same
color indicates the same range of values of the probability in all the three sub-diagrams.
FIG. 2: Plots of the values of the tunnelling probability in a spacetime of dimension 3, as a function of $\beta$ for fixed non-negative values of $\alpha$ as listed above. The detailed behavior for $\alpha = 0$ around $\beta = 0$, is also shown (to better see that the probability is small but non-zero).

formulation. For these reasons, we can regard our conclusions model independent to a high degree, at least within the context defined by the semiclassical approximation.

To introduce our model we can naturally think the brane as sourced by some matter fields whose nature is, ultimately, quantum. We thus argue that, although at large scales the approximation for the brane stress-energy tensor that we made in subsection II B might be rough but still appropriate, at small scales it will instead break down due to quantum effects. We will model these additional quantum effects by adding a term to the brane stress-energy tensor as follows:

$$S \rightarrow S + S_q,$$

where the “quantum” contribution $S_q$ will be parametrized as

$$S_q = \rho_q \mathbf{u} \otimes \mathbf{u} + \sigma_q \mathbf{h}.$$  \hspace{1cm} (25)

The conservation equation for $S_q$ under the assumption of spherical symmetry gives (we are going to use, from now on, the dimensionless versions of the parameters $\rho_q$ and $\sigma_q$, which following the notation above, are called $\bar{\rho}_q$ and $\bar{\sigma}_q$)

$$\frac{d\bar{\rho}_q}{dx} + N \frac{\bar{\rho}_q}{x} = \frac{d\bar{\sigma}_q}{dx}. \hspace{1cm} (26)$$

We will choose preliminarily

$$\bar{\rho}_q(x) = ax^q$$  \hspace{1cm} (27)

so that

$$\bar{\sigma}_q(x) = a \frac{q + N}{q} x^q.$$  \hspace{1cm} (28)

In this case the junction condition becomes\(^{10}\)

$$- \left[ \epsilon(q) \sqrt{x^2 + 1 - \lambda x^2} \right] x = x^2 \mu(x), \hspace{1cm} (29)$$

\(^{10}\) We remember that we are following the convention in which square brackets indicate the jump of the enclosed quantity, i.e. the difference of it when evaluated in the ‘+’ and ‘−’ domains. We are now using the suffix ‘...q’ or ‘...($q$)’ to indicate quantities when the energy momentum tensor is modified, as described in the text, to take into account quantum effects; thus the two signs will now be $\epsilon(q)_{\pm}$. 


and, for short, $\bar{\alpha} = a(q + N)/q$. Now we are going to slightly restrict the parameters $\bar{a}$ and $q$ to make these general settings appropriate for our model. In particular, the modification to the stress energy tensor, described by $\bar{\alpha}$ and $\alpha$ was introduced to model the quantum effects at small scales; thus it should be negligible at large scales and this can be achieved if $q + 1 < 0$, i.e. $q < -1$.

We can now compute the modified effective potential $\bar{V}'_q$. The potential turns out to be

$$\bar{V}'_q(x) = -\frac{x^2}{4} \left( \beta^2 + 2\alpha(1 + \bar{a}x^q)^2 + (1 + \bar{a}x^q)^4 \right)$$

$$\lim_{x \to 0^-} \bar{V}'_q(x) = -\frac{\bar{a}^2}{4x^{-2q-2}}$$

This implies that the $\bar{V}'_q(x)$ allows not only the bounce brane junction, as $\bar{V}(x)$ does, but also bounded solutions. Thus the addition of the $S_q$ term to the stress energy tensor, which in our picture is supposed to take into account quantum effects at small scales, in fact does his job by trading the $x \equiv 0$ solution for a bounded one of finite (i.e. non-vanishing) size. Moreover this solution exists under very general assumptions about the form of $S_q$, so that we do not have to commit ourselves too much about the underlying quantum gravity physics of which $S_q$ is roughly supposed to take into account some effective semiclassical description. Looking, now at equation (33) we also see that for small $\bar{a}$, apart from the evident qualitative difference at small scales, the potential resembles closely the non-perturbed one (and this happens, in particular, along the tunnelling trajectory). Thus it will be a sufficiently good approximation to evaluate the tunnelling probability in the, analytically much simpler, unperturbed case.

At this point, our picture of the spacetime transition will be as follows. We will take as final configurations of the tunnelling process the junctions obtained without considering the correction, which in our setup is strongly suppressed at large distances; then, the initial state, which is the $x \equiv 0$ solutions, will be “regularized” by considering the junction as the limiting case of the bounded perturbed junction when $\bar{a} \to 0$. In particular, the sign ambiguity, which affects the $x \equiv 0$ solution, will be solved by choosing the signs of the bounded trajectory

FIG. 3: Plots of the values of the tunnelling probability in a spacetime of dimension 3, as a function of $\beta$ for fixed negative values of $\alpha$ as listed above. For $\alpha < -1/2$, not all values of $\beta$ are allowed. We have put the mark on each curve in correspondence of the minimum value of $\beta$ for which (at the given value of $\alpha$) the tunnelling process can exist. For smaller values, the infinitely expanding solution, in fact, is not present.

with

$$\mu(x) = 1 + \bar{\alpha}x^q$$  \hspace{1cm} (30)
of the perturbed model. These signs can be obtained in closed form considering the $x \to 0$ limit of the junction condition, which is dominated by the correction. Therefore

$$\epsilon_\pm = \mp 1 \quad (34)$$

Using this prescription, then, one can build the spacetime diagrams representing the tunnelling process. We refer the reader to appendices for a complete discussion of the parameter space (appendix [A]) and of the global spacetime diagrams representing the various physical situations (appendix [B]).

To conclude the discussion, we would like to remark that, despite the fact that the regularization procedure we have described changes dramatically the situation in the region near $x = 0$ of the configuration space of the brane, the effect on the calculation we have performed is not significant. This is due to the fact that in the tunnelling region, the potential is substantially modified only in a narrow region close to the turning point corresponding to the maximum radius of the bounded solution of the modified classical junction condition. In the tunnelling region, the perturbation to the potential is finite, and by sending $\bar{a} \to 0$ the tunnelling amplitude of the modified problem is approximated arbitrarily well by our calculation in section [III]. Of course, in the real physical problem we expect that quantum effects would prevent the brane from shrinking to zero radius: thus the mathematical limit $\bar{a} \to 0$ should be read as a more physically sound limit in which $\bar{a}$ tends to a small but finite value related to the ultimate physical nature of the brane itself (which is presently only partially understood). As a consequence, the analytical result that we have obtained (which relies on a WKB approximated description of the quantum process) can also be consider an approximation of the full quantum result at the lowest power in the ratio between the maximum radius of the bounded solution of the modified classical junction equations and $x_0$.

V. CONCLUSIONS

In this paper we have calculated analytically the tunnelling amplitude for a domain of spacetime of de Sitter/anti–de Sitter type in a background which, again, is de Sitter/anti–de Sitter. The analytical result holds in arbitrary spacetime dimensions greater than three, and generalizes already existing four dimensional calcu-
lutions. It is not difficult to see that this result reduces, for appropriate values of the parameters, to the result found by Coleman and de Luccia \cite{8} for the false vacuum to true vacuum transition in four spacetime dimensions. Also the results by Parke \cite{86}, again in the four dimensional case, are correctly reproduced.

We have, also, discussed extensively, in the text and in appendix \textit{B} the spacetime structures that can arise for all possible values of the parameters characterizing the model. Some of these spacetime structures, already discussed in the literature, are known as \textit{tunnelling from nothing} configurations. We have also exposed a possible issue of the shell formalism in the description of the pre-tunnelling state and proposed a solution which relies on the above mentioned \textit{tunnelling from nothing} configurations; in this way we have been able to make what we consider to be a consistent choice for the \textit{before tunnelling} configurations. This proposal, which is implemented by considering a modification to the stress-energy tensor for the matter on the shell at small states, is motivated by the observation that if quantum effects are non-negligible on scales at which the tunnelling process occurs, they should also be non-negligible at smaller scales, where the \textit{before tunnelling} configurations live. By modelling the influence of these quantum effects with a quite generic modification to the form of the stress-energy tensor at small scales, we have proposed an unambiguous rule to fix the initial configuration. This approach to the problem, seems to us consistent with the level at which we are modelling quantum effects for this gravitational system, which is the \textit{semiclassical approximation} for an \textit{infinitesimally thin} distribution of matter and energy. At the same time, it has already been shown that, if we add a more refined matter content on the shell (as for instance a collection of gauge fields), modifications similar to the one that we have considered in this paper naturally appear \cite{87}. Moreover, we note that it gives a very consistent picture of the tunnelling process, since all the possible types of tunnelling result in a \textit{sudden expansion} of a very small region of spacetime from a small size (where quantum effects are certainly non negligible) to a much bigger size, with radius of the order of $x_0$. This shows that the regularized tunnelling always models what in the literature has been called tunnelling \textit{“from nothing”}. In our case the “nothing” is exactly the quantum state of the spacetime junction that we model, in an effective way, using (29). It thus seems that some tunnelling configurations present in the literature and of more difficult interpretation \cite{67} might be ruled out by the quantum properties of matter and/or of spacetime at small scales. In fact, it is suggestive to reflect about the fact that, even in our very simplified and purely effective treatment of quantum effects before and during the tunnelling, all tunnelling processes start exactly \textit{“from nothing”} (as interpreted above), i.e. from a configuration which is consistent with the quantum properties of the following tunnelling process.

To conclude, we would like to explicitly distinguish between the analytical result for the tunnelling probability and the proposal to interpret the \textit{pre-tunnelling}
configurations. Indeed the analytical result is a natural generalization of already existing calculations and it incorporates them as special cases. Its validity is completely independent from our interpretation of the before tunnelling configurations and it can represent a useful limit case to check the results of more elaborated models: for instance, a de Sitter–Schwarzschild shell configuration should reproduce, in the limit of vanishing Schwarzschild mass, our result for a tunnelling between a de Sitter space of assigned cosmological constant and a de Sitter space with vanishing cosmological constant, i.e. Minkowski space.

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APPENDIX A: PARAMETER SPACE

In this appendix we will elaborate about the classification of the possible junctions between two (anti–)de Sitter spacetimes. After switching to the dimensionless formulation (see subsection II D), we remain with two parameters, i.e. \( \lambda_\pm \), or, which is the same, \( \alpha \) and \( \beta \). We will mostly use the latter quantities in the following analysis, since many relevant features of the solutions to Israel’s junction condition related to the causal structure of the full spacetime manifold \( \mathcal{M} \) are easily deducible from the comparison between the two cosmological constants. In particular, in figure 8 we give a classification of the possible solutions. The diagram shows the parameter space of the variables \( (\alpha, \beta) \) and \( (\lambda_+, \lambda_-) \). The classification of the solutions using \( \alpha \) and \( \beta \), looks nicely symmetric with respect to the axis \( \beta = 0 \), for which \( \lambda_+ = \lambda_- \); this is the primary reason why we will mostly use the \( (\alpha, \beta) \) parametrization in our discussion. The \( (\lambda_+, \lambda_-) \) axes can, anyway, be conveniently used to single out the de Sitter from the anti–de Sitter spacetime. In particular, we have defined four main groups of solutions:

**type A**) these are solutions in which both spacetimes joined across the brane are anti–de Sitter space-
times, i.e. we have an AdS\(_{-}\) - AdS\(_{+}\) junction; this part of the parameter space is bounded by the parabola \(\alpha = -(\beta^2 + 1)/2\) (equivalently \(x_0^{-1} = 0\)), whose inside is the black region where no solution exists;

**type B** these solutions describe a junction of one part of de Sitter spacetime in the \(\mathcal{M}_-\) manifold with a part of anti-de Sitter spacetime in the \(\mathcal{M}_+\) manifold, i.e. they are dS\(_{-}\) - AdS\(_{+}\) junctions, and play the role of counterparts of the below discussed type D solutions;

**type C** these are junctions in which both spacetimes have the de Sitter geometry, i.e. we have dS\(_{-}\) - dS\(_{+}\) junctions; in some cases, qualitatively different diagrams may arise depending on which cosmological constant is the bigger, i.e. depending on the sign of \(\beta\);

**type D** as anticipated above, this last type of solutions is similar to the type B, with the role of “−” and “+” interchanged; we thus have AdS\(_{-}\) - dS\(_{+}\) junctions.

The above information is not enough to completely characterize the classical spacetime obtained from the junction. In addition we need to know the behavior of the normal to the brane travelling in the spacetimes that we have determined from the diagram in figure [3]. According to our convention the normal to the brane has its tail-tip direction going from the “−” to the “+” parts of the full spacetime \(\mathcal{M}\); on the other hand in each of the two spacetimes \(\mathcal{M}_\pm\) the corresponding signs \(\epsilon_\pm\) determine if the normal to the brane points in the direction of increasing \((\epsilon = +1)\) or decreasing \((\epsilon = -1)\) radius. Using the results in (7) for \(\epsilon_\pm\) we can subdivide the parameter

FIG. 7: Plots of the values of the tunnelling probability in a spacetime of dimension 5, as a function of \(\beta\) for fixed negative values of \(\alpha\) as listed above. For \(\alpha < -1/2\), not all values of \(\beta\) are allowed. We have put the mark on each curve in correspondence of the minimum value of \(\beta\) for which (at the given value of \(\alpha\)) the tunnelling process can exist and, the zoomed diagram, helps resolving the superposition that arises between the curves obtained for \(\alpha = -0.50, -1.00, -1.50\).
The space of parameters is subdivided according to the different kinds of junctions, which can be between anti–de Sitter and anti–de Sitter spacetimes (type A), anti–de Sitter and de Sitter spacetimes (type B), de Sitter and anti–de Sitter spacetimes (type D) or de Sitter and de Sitter spacetimes (type C). The black part of the parameter space, identified by the condition \(1 + 2\alpha + \beta^2 < 0\), singles out the values of the parameters for which tunnelling is not possible since the infinitely expanding solution does not exist.

In principle we have to study 10 different cases, corresponding to as many different regions in the parameter space. These regions are obtained combining the classifications in figures 8 and 9 so that in each region there is a well defined type of junction with an unique choice for the signs. As we will see each of the pairs A1 and A3, B1 and D3, B2 and D2, C1 and C3 will correspond to a distinct processes in spacetime; this matches well with the analytical result, in which the action turns out to be an even function of \(\beta\), and gives only a total of 6 different possible processes.

In figure 9 we can see the parameter space can be subdivided in three other regions (strips) according to the values of the signs \(\epsilon\). In region 1 we have \(\epsilon = -1\), in region 2 we have \(\epsilon = +1\) and, finally, in region 3 we have \(\epsilon = +1\).

We thus have various combinations of the geometries of the two spacetimes \(\mathcal{M}_{\pm}\) according to the classification in figure 8 moreover we have to combine them choosing the part of spacetime on the correct side of the brane trajectory following the classification in figure 9. This gives a total of ten subcases, which are summarized in figure 10. The naming convention is the most natural, so that, for instance, the junction named B2 is a junction of type B, i.e. a \(dS(-) - AdS(+)\) junction, with the signs as in region 2, i.e. \(\epsilon - = +1\) and \(\epsilon + = -1\). All other names
follow the same convention and we thus obtain solutions of the following types $A_1$, $A_2$, $A_3$, $B_1$, $B_2$, $C_1$, $C_2$, $C_3$, $D_2$, $D_3$; their causal structure is detailed in the following appendix.

**APPENDIX B: PENROSE DIAGRAMS & TUNNELLING**

Here, following the classification given in the previous appendix, we show the corresponding Penrose diagrams for the classical solutions, and a pictorial representation of the corresponding tunnelling processes. For each case we give four diagrams:

1. the complete spacetime from which we have to "cut" the $M_-$ part of the bulk (with the trajectory of the bubble and the associated normal) in the top left diagram;
2. the complete spacetime from which we have to "cut" the $M_+$ part of the bulk (with the trajectory of the bubble and the associated normal) in the top right diagram;
3. the junction, *i.e.* the full manifold $M$ (again with the shell trajectory and the corresponding normal) in the bottom left diagram;
4. a pictorial representation of the creation of the brane *via* a tunnelling process, in the bottom right diagram; in this case we have used time translation invariance to set the "tunnelling time" at the coordinate time $t = 0$ so that the top half of the diagram represents the final state (*i.e.* the top half of the junction in the bottom left diagram) whereas the bottom half of the diagram is a representation (detailed below) of the pre-tunnelling configuration.

We would like to discuss preliminarily in more detail the way in which the pre-tunnelling configuration is constructed. We remember that we are considering non negligible quantum effects in the regime of the dynamics before the tunnelling. We will thus use for the signs the results coming from the modified junction (29), which are those in (34). This gives a spacetime structure consisting of two regions (which can be of the de Sitter or of the anti–de Sitter type depending on the values of $\alpha$ and $\beta$) both bounded by $r = 0$ and by the shell radius $r = R(\tau)$: this is the junction corresponding to the bounded solution of the modified potential (31), which is a brane starting from zero radius and expanding to a maximum radius (much smaller than any other length scale present in the problem) before recollapsing to $r = 0$. In the limit in which $\bar{a} \to 0$, as discussed in section IV, this maximum radius tends, in fact, to zero. Nevertheless, in our representation of the spacetime before the tunnelling we have kept an arbitrarily finite size for the maximum radius, to make the diagram more readable. At the same time, we have slightly “blurred” it to make pictorially explicit that we are not dealing with a purely classical configuration but with a somehow “heuristic” representation of a spacetime where quantum effects are highly non trivial and certainly non negligible. We would like, anyway, to stress again that these quantum configurations will be the initial state of tunnelling processes that correspond to what in the literature has also been called “tunnelling from nothing” (see for instance [67] and references therein).

We will now present in detail the various kinds of junctions.

1. **Type A**

As discussed in main text (and with reference to figure 10), this class of junctions consists of the matching of two anti–de Sitter spacetimes with different cosmological constants. There are three possibilities corresponding to type $A_1$, $A_2$ and $A_3$ junctions, which are shown, respectively, in figures 11, 12 and 13.

![Figure 11: Case A1: AdS/AdS, $\epsilon_\pm = -1$](image)

The junction of type $A_1$ (figure 11) has $\epsilon_\pm = -1$, so in both anti-de Sitter spacetimes the normal to the brane points in the direction of decreasing radii. For this junction (and for all the ones in the 1 sector), $\beta > 1$, so that $\lambda_-$ is always greater than $\lambda_+$. The classical junction is seen (by an observer travelling toward increasing values of the radius) as a transition from a more negative to a less negative value of the cosmological constant, when he/she crosses the brane. The global picture of the tunnelling process is then obtained according to the
prescription discussed in section [V]. The pre-tunnelling spacetime has been discussed above and now consists of two “small” parts of anti–de Sitter spacetime with different cosmological constant. The tunnelling process shows the transition between a compact spacetime composed by two anti-de Sitter regions to a spacetime similar to anti–de Sitter, except for the fact that at some radius the cosmological constant changes its value.

\[
\begin{align*}
\text{AdS}_-, \epsilon_- &= +1 & \text{AdS}_+, \epsilon_+ &= -1 \\
\text{AdS}_+, \epsilon_+ &= +1 & \text{AdS}_-, \epsilon_- &= +1
\end{align*}
\]

FIG. 12: Case A2: AdS/AdS, \( \epsilon_- = +1; \epsilon_+ = -1 \)

The junction of type A2, is instead a junction where effectively a tiny junction of two anti-de Sitter spacetimes is “inflated” (figure 12). In this case the signs are given by \( \epsilon_\pm = \mp 1 \). Thus the normal to the brane points in the direction of increasing radii in the anti–de Sitter spacetime with cosmological constant \( \lambda_- \), but it points in the direction of decreasing radii in the anti–de Sitter spacetime with cosmological constant \( \lambda_+ \). The net effect of the tunnelling process, which starts from the already discussed initial state, is thus to inflate the pre-tunnelling compact spacetime into a similar, but much larger, one (note that for graphical reasons the scales in the pre-tunnelling and post-tunnelling parts of the diagram are different; we remember that the maximum radius of the pre-tunnelling state will be much smaller than any other length scale in the problem). The various diagrams are in figure 12.

The final type A diagram is the A3 one. This is very much as the A1 type, only that now \( \epsilon_\pm = +1 \); in both spacetime the normal to the shell trajectory points in the direction of increasing radii. Thus (apparently) the role of \( M_\pm \) is interchanged, as shown in figure 13 where the dark and light gray parts looks complementary to those in figure 11 on the other hand, now we have \( \beta < -1 \) so that \( \lambda_+ > \lambda_- \). The global spacetime structure in the bottom left corner of figure 13 implies that an observer crossing the brane in the direction of increasing values of the radius, perceives again a transition from a more negative to a less negative value of the cosmological constant. So this diagram describes exactly the same process described by type A1, as it is possible to see from the diagram in figure 13.

2. Type B

The type B solutions, B1 and B2, correspond to the junction of a part of a de Sitter spacetime, \( M_- \), with a part of anti–de Sitter spacetime, \( M_+ \). Although the pre-tunnelling picture does not change very much, the configurations before the tunnelling are now de Sitter–anti-de Sitter junctions.

Let us first discuss the case B1, shown in figure 14. In both spacetimes, the normal to the shell points in the direction of decreasing radii, since we have \( \epsilon_\pm = -1 \). The \( M_- \) part of spacetime corresponds to the region of de Sitter complementary to the region between \( r = 0 \) and the brane’s world-volume, whereas the anti–de Sitter part \( M_+ \) is the bounded region in the upper right picture of figure 14. Thus the spacetime \( M \) shows a transition from a negative to a positive value of the cosmological constant for an observer crossing the shell in the direction of increasing radius. The configuration before the tunnelling has been described above; the tunnelling pro-
in this case the signs which fix the orientation of the normals are $\epsilon_\pm = \mp 1$, the situation for $\mathcal{M}_+$ is as in the previous case, but the $\mathcal{M}_-$ part of spacetime changes because of the change in the sign of $\epsilon_+$. This gives for the junction the diagram in the bottom left part of figure 15. The configuration before and after the tunnelling is shown in the bottom right corner of figure 15. The situation is very similar to the one in the previous case.

### 3. Type C

Type C solutions are the “de Sitter counterpart” of type A solution. The main difference (not related to the spacetime structure) is that whereas for anti–de Sitter junctions the values of the cosmological constant are restricted (i.e. given two arbitrary values a junction might not exists) de Sitter junctions exist for all values of the cosmological constants $\lambda_\pm$ (this is clear from figure 10). Please, also remember that now the pre-tunnelling diagram will consist of a junction of two de Sitter spacetime with different cosmological constants and with all the other properties described above.

Let us start with case C1, shown in figure 16. For this junction, the signs are $\epsilon_\pm = -1$, so in both de Sitter spacetimes the normals to the brane point in the direction of decreasing radii. Moreover, since in this case $\beta > 1$, the cosmological constant in $\mathcal{M}_-$ will be bigger than the cosmological constant in $\mathcal{M}_+$, so that the cosmological horizon $H_-$ will be smaller than $H_+$. The diagram for the junction is shown in the bottom left part of figure 16. It is

We then come to the case B2, shown in figure 15. Since

FIG. 14: Case B1: dS/AdS, $\epsilon_- = \epsilon_+ = -1$

FIG. 15: Case B2: dS/AdS, $\epsilon_- = +1; \epsilon_+ = -1$

FIG. 16: Case C1: dS/dS, $\epsilon_- = \epsilon_+ = -1$
interesting to see some effects of the brane on the spacetime structure. There are observers that crossing the brane can move behind the cosmological horizon of $\mathcal{M}_-$ without going through $H_-$. They can also come out, by crossing the brane in the opposite direction. At the same time observers, by moving accurately and with proper timing, might end up behind the cosmological horizon of $\mathcal{M}_+$ without crossing any horizon but using the shell as a “gate”\textsuperscript{11}. As usual no additional considerations are required for the before tunnelling configuration. We note, instead, that the semiclassical transition has again the required for the before tunnelling configuration. We note, instead, that the semiclassical transition has again the effect of “inflating” a small quantum spacetime region, as clearly shown in figure 16.

The normals now point in both spacetimes toward the dark side, but now exactly the different cosmological constants is $\lambda_+ > \lambda_-$, so that $H_+ > H_-$. At this stage we might wonder if this junction is the same as C1 (mirroring what happens between the junctions of the A1 and A3 type). We will see that this is indeed the case. The normals now point in both spacetimes toward the direction of increasing radii (since $\epsilon_\pm = +1$). Thus the junction is as in the bottom left corner of figure 17. When we consider also the configuration before tunnelling, we see that the diagram in the bottom right part of figure 17 is the “switched color and reflected” version of the one in the bottom right part of figure 18. We remember now that the in the C1 case $\lambda_-$ in the light gray part was bigger than $\lambda_+$ in the dark side, but now exactly the opposite happens. Thus, despite the different coloring, case C3 represents the same physical situation of case C1. This observation makes interesting to complete the analysis for the remaining two cases, which is done in the following subsection.

\begin{figure}[h]
\centering
\includegraphics[width=\textwidth]{fig17.png}
\caption{Case C2: dS/dS, $\epsilon_- = +1; \epsilon_+ = -1$}
\end{figure}

\begin{figure}[h]
\centering
\includegraphics[width=\textwidth]{fig18.png}
\caption{Case C3: dS/dS, $\epsilon_- = \epsilon_+ = +1$}
\end{figure}

\textsuperscript{11} These considerations might be modified if we consider the influence of the observer on spacetime. To neglect this influence, as a first approximation, is fairly common in the literature to obtain some hints about the global spacetime structure.
4. Type D

To conclude the analysis of the global spacetime structure we have to analyze what happens for the last kind of junctions, those of type $D$. These are junctions between de Sitter and anti–de Sitter spacetimes, so that the pretunnelling configuration will also change accordingly, as we have discussed for the previous cases.

![FIG. 19: Case D2: AdS/dS, $\epsilon_- = +1; \epsilon_+ = -1$](image)

The case of the junction of type $D2$ is characterized by the following signs: $\epsilon_\pm = \mp 1$. This means that in the anti–de Sitter side the normal points in the direction of increasing radii, whereas in the de Sitter part, it points in the direction of decreasing radii. Thus the junction, shown in the bottom left corner of figure 19 is the mirror image of the B2 case. Again, the considerations in section IV determine the geometry before the tunnelling. This brings, in complete analogy with the B2 case, to the picture of the tunnelling process given in the bottom right part of figure 19; again, apart from the different colors, this case is the same as B2 also in connection with the semiclassical tunnelling process.

![FIG. 20: Case D3: AdS/dS, $\epsilon_- = \epsilon_+ = +1$](image)

We have thus only one case left, which is quickly dealt with, namely D3. It is now not difficult to anticipate that this process will turn out to be identical to B1, that appears in figure 14. Indeed the signs are now $\epsilon_\pm = +1$, so that in both spacetime the normals point in the direction of increasing radii. By the usual procedure we are thus led to the spacetime diagram shown in the bottom left part of figure 20. Part of this diagram will constitute the final state of the tunnelling process. The initial state is obtained as usual and the picture of the tunnelling process is as in the bottom right part of figure 20.

5. Comments

From the analysis developed so far we have seen that, although in principle we have ten different tunnelling processes, in fact process A1 is the same as A3, process B1 is the same as D3, process B2 is the same as A2 and process C1 is the same as C3. We are thus left with only six distinct processes. From “symmetry consideration”, it is natural to notice that $|\beta|$, not $\beta$ itself, is the relevant quantity (together with $\alpha$) to classify the possible tunnelling configurations. We will thus not be surprised if the tunnelling amplitude will be a function of $|\beta|$, or, which is the same, an even function of $\beta$. We would also like to note already here that all the tunnelling processes can be interpreted as a very large expansion of a small quantum region of spacetime.

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