SLIME MOULD ALGORITHM FOR PRACTICAL OPTIMAL POWER FLOW SOLUTIONS INCORPORATING STOCHASTIC WIND POWER AND STATIC VAR COMPENSATOR DEVICE

Purpose. This paper proposes the application procedure of a new metaheuristic technique in a practical electrical power system to solve optimal power flow problems, this technique namely the slime mould algorithm (SMA) which is inspired by the swarming behavior and morphology of slime mould in nature. This study aims to test and verify the effectiveness of the proposed algorithm to get good solutions for optimal power flow problems by incorporating stochastic wind power generation and static VAR compensators devices. In this context, different cases are considered in order to minimize the total generation cost, reduction of active power losses as well as improving voltage profile. Methodology. The objective function of our problem is considered to be the minimum the total costs of conventional power generation and stochastic wind power generation with satisfying the power system constraints. The stochastic wind power function considers the penalty cost due to the underestimation and the reserve cost due to the overestimation of available wind power. In this work, the function of Weibull probability density is used to model and characterize the distributions of wind speed. Practical value. The proposed algorithm was examined on the IEEE-30 bus system and a large Algerian electrical test system with 114 buses. In the cases with the objective is to minimize the conventional power generation, the achieved results in both of the testing power systems showed that the slime mould algorithm performs better than other existing optimization techniques. Additionally, the achieved results with incorporating the wind power and static VAR compensator devices illustrate the effectiveness and performances of the proposed algorithm compared to the ant lion optimizer algorithm in terms of convergence to the global optimal solution. References 38, tables 6, figures 9.

Key words: optimal power flow, slime mould algorithm, stochastic wind power generation, static VAR compensators.

Introduction. In the last decade, energy consumption has been increased significantly especially in developing countries. Renewable energy can be known as green energy or clean energy is one of the best in developing thanks to the technological advances made in the field of wind generators to reduce the cost of system installations. In addition, the application of flexible AC transmission systems (FACTS) controllers such as static VAR compensators (SVC) devices that considered one of the most desirable sources in recent years that keeps developing thanks to the technological advances made in the field of wind generators to reduce the cost of system installations. The OPF for the system that includes RESs such as wind power generators is the subject of ongoing research models nowadays. It is necessary to confront the stochastic nature of this source for analysis of the planning and operation of modern power systems, in order to obtain much more precise.
results [2]. In general, the problem with wind power is the stochastic nature of wind speed. Therefore the model which considers the probability of the available wind power can represent the cost of overestimating and underestimating this power at a certain period.

Recently, OPF with stochastic wind power has extensively been studied by more researchers. In [3] authors proposed a Gbest-guided artificial bee colony algorithm (GABC) to solve the OPF problem in the IEEE 30 bus system incorporating stochastic wind power. In attempting the same problem in [4] author proposed a modified moth swarm algorithm (MMSA) to solve the OPF problem incorporating stochastic wind power. In this work, three different objective functions are considered, which are the minimize the total operating cost, reduce the transmission power loss, and improve the voltage profile enhancement. In another study [5] authors applied the success history-based adaptation technique of differential evolution algorithm to solve the OPF problem comprises of stochastic wind-solar power with conventional thermal generators under various cases. The OPF incorporation with wind power and static synchronous compensator STATCOM was studied in [6] by using a modified bacteria foraging algorithm (MBFA). The results obtained proved that MBFA efficiency and better than the ACO algorithm for solving OPF problems in power systems. Bird Swarm Algorithm (BSA) for solving an OPF problem with incorporating stochastic wind and solar PV power in the power system is studied in [7]. The proposed approach applied in the modified IEEE 30-bus system with objective function is to minimize the total energy generation cost, which is the cost of thermal-wind-solar. In [8] authors applied a modified hybrid PSOGSA with a chaotic maps approach to improve OPF results by incorporating stochastic wind power and two controllers in the FACTS family such as TCSCs and TCPs. The proposed method is applied in the power systems to minimize the thermal generators' fuel cost and the wind power generating cost.

Several metaheuristic optimization algorithms were developed and applied for the OPF solution. Some of them are: salp swarm optimizer [9], moth swarm algorithm [10], differential evolution [11], glowworm swarm optimization [12], differential search algorithm [12], moth-flame optimizer [14], stard krill herd algorithm [15], artificial bee colony algorithm [16], symbiotic organisms search algorithm [17], improved colliding bodies optimization algorithm [18], firefly algorithm [19], black-hole-based optimization approach [20], the league championship algorithm [21, 22], multi-verse optimizer [23], harmony search algorithm [24], earthworm optimization algorithm [25]. Among several numbers of the available metaheuristic algorithm, a new flexible and efficient stochastic optimization algorithm has been proposed to solve our problem and satisfy our imposed conditions, this technique namely a slime mould algorithm (SMA). SMA is based upon the oscillation mode in nature and simulates the swarming behavior and morphology of slime mould in foraging.

In this paper, a new flexible and efficient stochastic optimization algorithm called slime mould algorithm (SMA) has been proposed with the aim is solving the OPF problem in power systems incorporating stochastic wind power and SVC devices.

**Modeling of SVC.** The static VAR compensator (SVC) device is an important member of the FACTS controllers’ family. The importance of SVC is to maintain the bus voltage magnitude at the desired level by providing or absorbing reactive energy. In the power system, SVC is modeled by shunt variable admittance. SVC’s admittance only has its imaginary part since the system, SVC is modeled by shunt variable admittance. Providing or absorbing reactive energy. In the power system, SVC is installed in the power system as a PV bus to regulate the voltage magnitude by injecting reactive power to a bus where it is connected. The current is reactive power absorbed or injected by the SVC device is calculated as follow:

\[
I_{SVC} = j b_{SVC} V_k; \tag{1}
\]

The \( b_{SVC} \) susceptance can be capacitive or inductive to provide or absorb reactive power, respectively. In this study, SVC is installed in the power system as a PV bus with the objective is to regulate the voltage magnitude \( V_k \) by injecting reactive power to a bus where it is connected. The current is reactive power absorbed or injected by the SVC device is calculated as follow:

\[
I_{SVC} = j b_{SVC} V_k; \tag{2}
\]

\[
Q_{SVC} = -V_k^2 b_{SVC}. \tag{3}
\]

**Optimal power flow problem formulation.** The optimal power flow problem solution aims to give the optimum value of the objective function by adjusting the settings of control variables. Generally, the mathematical expression of the optimization problem with satisfying various equality and inequality constraints may be represented as follows:

\[
\min F(x, u); \tag{4}
\]

Subjected to \( g(x, u) = 0 \); \tag{5}

\[
h(x, u) \leq 0; \tag{6}
\]

where \( F(x, u) \) denotes the objective function that to be optimized, \( x \) and \( u \) represents the vectors of the state variables (dependent variables) and control variables (independent variables), respectively.

**Control variables.** In the OPF the control variables should be adjusted to satisfy the load flow equations. The set of control variables can be represented by vector \( u \) as follows:

\[
\begin{bmatrix} P_G, \cdots, P_{NG}, P_{WS}, \cdots, P_{WS}, V_{G1}, \cdots, V_{GNG}, \\ Q_{C1}, \cdots, Q_{CNG}, T_1, \cdots, T_{NT}, SVC, SVC_{NSVC} \end{bmatrix}, \tag{7}
\]

Where \( P_G \) is the thermal generator active power; \( P_{WS} \) is the wind active power; \( V_G \) is the generator voltage; \( Q_{C} \) is the reactive power injected by the shunts compensator; \( T \) is the tap setting of transformers; SVC is the static VAR compensator; \( NC \) is the number of generators; \( NW \) is the number of wind farms; \( NC \) is the number of shunts compensators units; \( NT \) is the number of regulating transformers; \( NSVC \) is the number of SVC devices.

**State variables.** The set of variables which describe the electrical power state can be represented by vector \( x \) as follows:

\[
x = \left[ P_{Slack}, Q_{G1}, \cdots, Q_{CNG}, Q_{WS}, \cdots, Q_{WS}, V_{L1}, \cdots, V_{LNT}, S_I, \cdots, S_I \right] \tag{8}
\]

Where \( P_{Slack} \) is the active power generation at the slack bus; \( Q_G \) is the reactive power outputs of the generators; \( Q_{WS} \) is the reactive power outputs of the wind farms; \( V_L \) is the voltage magnitude at load bus; \( S_I \) is the apparent power flow; \( NC \) is the total number of generators buses;
Equality constraints. The equality constraints represent in the power system the load flow equations of the balanced powers and reflect the physics of the power system the load flow equations of the power system. The equality constraints can be represented as follows:

\[ P_{Gi} + P_{WSi} - P_{di} = V_i \sum_{j=1}^{N} V_j \left( g_{ij} \cos \delta_{ij} + z_{ij} \sin \delta_{ij} \right), \quad (9) \]

\[ Q_{Gi} + Q_{WSi} - Q_{di} = V_i \sum_{j=1}^{N} V_j \left( g_{ij} \sin \delta_{ij} + z_{ij} \cos \delta_{ij} \right), \quad (10) \]

Inequality constraints. The inequality constraints reflect the limiting of the power system operation. These inequality constraints can be represented as follows:

\[ P_{\min}^{\text{min}} \leq P_{Gi} \leq P_{\max}^{\text{max}}, \quad P_{\min}^{\text{min}} \leq P_{WSj} \leq P_{\max}^{\text{max}}, \quad Q_{\min}^{\text{min}} \leq Q_{Gi} \leq Q_{\max}^{\text{max}}, \quad Q_{\min}^{\text{min}} \leq Q_{WSj} \leq Q_{\max}^{\text{max}}, \quad V_{\min}^{\min} \leq V_{Gi} \leq V_{\max}^{\max}, \quad T_{\min}^{\min} \leq T_{NTj} \leq T_{\max}^{\max}, \quad Q_{\min}^{\text{SVC}} \leq Q_{\text{SVCj}} \leq Q_{\max}^{\text{max}}, \quad (11) \]

Objective function. In this study, the objective function is to minimize the total generation cost (TGC) subject to operating constraints. The objective function is formulated as:

\[ F_{\text{tot}} = \sum_{i=1}^{N} F_i(P_i) + \sum_{i=1}^{\text{NW}} C_{\text{wr}}(P_{\text{wr}}) + \sum_{i=1}^{\text{NW}} C_{\text{p,wr}}(P_{\text{wravl}} - P_{\text{wr}}) + \sum_{i=1}^{\text{NW}} C_{\text{r,wr}}(P_{\text{wr}} - P_{\text{wravl}}). \quad (12) \]

In the expression of the objective function formulated in the (12), the first term denotes thermal power generation cost, second, third and last term of the objective function shows the costs of wind power, respectively. Details of all terms are explained below.

Fuel cost of the conventional generator. The cost function of the thermal generators as follows:

\[ F_i(P_i) = \left( \sum_{i=1}^{i=1} a_i + b_i P_{Gi} + c_i P_{Gi}^2 \right), \quad (13) \]

where \( P_{Gi} \) is the active power generated from the available thermal generators; \( a_i, b_i \) and \( c_i \) are the cost coefficients of \( i \)-th generator.

The direct cost function for wind power. The grid operators pay the cost of purchasing wind power from a wind power producer based on the power purchase agreement. This cost is termed as the direct cost and is defined as follows [5]:

\[ C_{\text{wr}}(P_{\text{wr}}) = d_r P_{\text{wr}}, \quad (14) \]

where \( d_r \) is the direct cost coefficient for the \( j \)-th wind generator and \( P_{\text{wr}} \) is the scheduled power output.

Cost function due to the underestimation. The underestimation situation is due when the actual wind power is higher than the estimated value. So, the utility operator needs to pay a penalty cost for not using the surplus amount of available wind power [4, 5]. The penalty cost functions due to the underestimation of available wind power represented by (15), it can be given as [26]:

\[ C_{\text{p,wr}}(P_{\text{wravl}} - P_{\text{wr}}) = k_p (P_{\text{wravl}} - P_{\text{wr}}) = k_p (0 - P_{\text{wr}}) \cdot f_w(P_w), \quad (15) \]

where \( C_{\text{p,wr}} \) is the cost associated with wind power shortage (underestimation); \( P_{\text{wr}} \) is the actual available power output; \( k_p \) is the penalty cost coefficient due to underestimation and \( f_w(P_w) \) represents the probability density function (PDF).

Cost function due to the overestimation. On contrary to the underestimation situation, the overestimation situation is due when the actual wind power is less than the estimated value. So, a spinning reserve is needed for grid operators [5]. The penalty cost function due to the overestimation of available wind power represented by (16) as follows [27]:

\[ C_{\text{r,wr}}(P_{\text{wr}} - P_{\text{wravl}}) = k_r (P_{\text{wr}} - P_{\text{wravl}}) = k_r (P_{\text{wr}} - 0) \cdot f_w(P_w), \quad (16) \]

where \( C_{\text{r,wr}} \) the cost associated with wind power surplus (overestimation) and \( k_r \) is the reserve cost coefficient due to overestimation.

Wind power model. The distribution function was used in this work to model and characterize the distributions of wind speed known as Weibull probability density function (PDF) [28], and can be represented as:

\[ f_w(V) = k \frac{V^\lambda \exp \left(-\frac{V}{c}\right)}{c^{\lambda+1}}, \quad (17) \]

where \( V \) is the wind speed; \( k \) and \( c \) respectively the shape factor and scale factor (m/s).

The probability density function for the continuous portion of wind energy conversion systems (WECS) power output random variable becomes as follows:

\[ f_w(P_w) = \frac{k \cdot l \cdot v_{\text{cut-in}}}{c} \left( \frac{1 + \rho^2}{c} \right) \exp \left(-\frac{\left(1 + \rho^2\right) v_{\text{cut-in}}}{c} \right) \times \exp \left(-\frac{\left(1 + \rho^2\right) v_{\text{cut-off}}}{c} \right), \quad (18) \]

where \( l = \frac{v_{\text{rated}} - v_{\text{cut-in}}}{v_{\text{cut-off}}} \) is the ration of linear range wind speed to cut-in wind speed; \( v_{\text{cut-in}} \) is the wind speed at which wind turbine starts to generate power; \( v_{\text{cut-off}} \) is the wind speed at which the wind turbine is disconnected; \( v_{\text{rated}} \) is the wind speed at which the mechanical power output will be the rated power; \( \rho = P_w / P_r \) is the ratio of wind power output to rated wind power.
The probability for the discrete portion of the WECS power output is expressed by (19) and (20), respectively as follows [5, 29]:

\[
f_w(P_w) = \begin{cases} 
0 & \text{if } P_w = 0 \\
1 - \exp\left(-\left(\frac{v_{\text{cut-in}}}{c}\right)^k\right) - \exp\left(-\left(\frac{v_{\text{cut-off}}}{c}\right)^k\right) & \text{otherwise}
\end{cases}
\]

(19)

\[
f_w(P_w) = \exp\left(-\left(\frac{v_{\text{rated}}}{c}\right)^k\right),
\]

(20)

**Slime mould algorithm.** A slime mould algorithm (SMA) is a new stochastic optimizer technique nature-inspired proposed in 2020 in [30]. This technique based on the oscillation mode of slime mould in nature and simulates the swarming behavior and morphology of slime mould in foraging. The SMA algorithm features a special mathematical model that uses the adaptive weight to simulate the combination of positive and negative feedback from the bio-oscillator-based propagation wave that was inspired by slime mould to form the optimal pathway to connect food. Some of the most interesting characters in the slime mould are the unique pattern based on the various food sources to create a venous network connecting them at the same time. This scheme gives the high capability of escaping from local optima solutions. The algorithm is aroused by slime mold diffusion and foraging behavior. In SMA, slime mould can approach food, depending on the smell in the air. The slime mold morphology varies, with three different forms of contraction. The following section will explain in detail the mathematical model for simulating the behavior of slime mould during the foraging [30].

**Approach food.** The following formulas for imitating the contraction mode is proposed to model the behavior of slime mould to approaching food according to the odor in the air as follow:

\[
X(t+1) = \begin{cases} 
X_B(t) + \frac{v_{b}}{v_{c}} \left( W \cdot X_A(t) - X_B(t) \right) & r < p; \\
X_B(t) + lb & \text{otherwise}
\end{cases}
\]

(21)

where \(X\) denotes the slime mould location; \(X_b\) is the individual emplacement with the highest odor concentration currently found; \(X_a\) and \(X_b\) are indicated two randomly selected individuals from the swarm; \(v_b\) is a parameter distributed in the range of \([-a, a]\); \(v_c\) decreases linearly from 1 to 0; \(t\) shows the current iteration; \(W\) represents the slime mould weight and given below by (24); \(p\) is the parameter given as follows:

\[
p = \tan^{-1}\left(\frac{S(i) - DF}{1}\right),\]

(22)

where \(S(i)\) shows the fitness of \(X\); \(i = 1, 2, ..., n\); \(DF\) is the optimum fitness obtained in all iterations.

The parameter of \(a\) is given as follows:

\[
a = \arctan \left( -\frac{t}{\max_t} + 1 \right) .\]

(23)

The expression of \(W\) define the location of slime mould and is given as follows:

\[
W(\text{SmellIndex}(i)) = \begin{cases} 
1 + r \cdot \log \left( \frac{bF - \bar{S}(i) + 1}{bF - wF} \right) & \text{condition} \\
1 - r \cdot \log \left( \frac{bF - \bar{S}(i) + 1}{bF - wF} \right) & \text{others}
\end{cases},
\]

(24)

where \(\text{condition}\) denotes that \(S(i)\) is ranked first half of the population; \(r\) represents the random value distributed in the range of \([0, 1]\); \(bF\) and \(wF\) are represented the optimal and worst fitness value obtained in the current iterative process, respectively; \(\text{SmellIndex}\) represents the sequence of fitness values sorted as:

\[
\text{SmellIndex} = \text{Sort}(S).
\]

(25)

**Wrap food.** This portion mathematically simulates the contraction mode in the slime mould venous tissue structure while searching. In the context, the higher the food concentration reached by the vein, the stronger the bio-oscillator-generated wave, the quicker the cytoplasm flows and the thicker the vein. The following mathematical formula represents updating the emplacement of slime mould:

\[
\bar{X} = \begin{cases} 
\frac{\text{rand} \cdot (ab - lb) + lb}{\text{rand} < z} & r < p; \\
\frac{v_{c} \cdot X(t)}{r \geq p}
\end{cases}
\]

(26)

where \(lb\) and \(ub\) denote the lower and upper limits of the search range, respectively; \(\text{rand}\) denotes the random value distributed in the range of \([0, 1]\).

**Grabble food.** Slime mould is primarily dependent on the propagation wave to change the cytoplasmic flow in the veins, so they appear to be in a better concentration of food. Slime mould can approach food faster when the concentration and quality of food are high, while if the food concentration is lower, approach it more slowly, thus increasing the efficiency of slime mould in selecting the optimum source of food.

In the SMA process, the value of the parameter \(v_{b}\) oscillates randomly in the interval between \([-a, a]\) and progressively approaches zero as the iterations increase. The value of \(v_{c}\) oscillates randomly in the interval between \([-1, 1]\) and finally tends to be zero.

The pseudo-code of the SMA to solve the OPF problem is shown in Algorithm 1.

**Algorithm 1 Pseudo-code SMA algorithm**

- Read the system data (bus data, line data, and generator data);
- Initialize the parameters of search agents, size of the population, the maximum number of iterations, the number and position of the control variables;
- Initialize the position of the slime mould \(X_i\) using (21);
- While \(\text{iteration} \leq \text{Max. iteration}\),
- Calculate the fitness of all slime mould using (26);
- Update the best fitness, \(X_g\);
- Calculate the \(W\) by using (24);
- For each search space
  - Update the parameters of SMA which are: \(p\), \(v_{b}\) and \(v_{c}\);
  - Update the best positions of the slime mould;
  - Calculate the best value of the objective function (12);
- End For
- \(\text{iter} = \text{iter} + 1\);
- End while
- Return best Fitness found so far, \(X_g\).
Simulations and results. To demonstrate the performance and efficiency of the SMA algorithm to solve the OPF problem by incorporating stochastic wind power and FACTS devices such as SVC, the present work aims to apply the SMA on IEEE 30-bus and Algerian 114-bus systems with different test cases study. In this context, the minimization of total fuel cost and wind power cost is considered as objective functions. The description of all these test cases can be found in the following section. All the simulations are carried out by using MATLAB 2009b and computed with specification Intel® Core™ i5 CPU@1.80 GHz with 8 GB of RAM. For establishing the robustness of the SMA algorithm, 30 independent trial runs are performed for all the test cases. In this work, the population size is 40 and the number of iterations maximal is 500.

IEEE 30-bus test system. The first test is dedicated to the standard IEEE 30-bus power system in order to verify the performance and efficiency of the SMA for the small scale power system. This system includes 6 generators unit, 41 transmission lines, 4 transformers located at lines 6-9, 4-12, 9-12, and 27-28. Nine reactive compensators are located at buses 10, 12, 15, 17, 20, 21, 23, 24, and 29. The total load is (2.834 +j0.735) p.u.

The upper limit and lower limit variables are shown in Table 1. In this section, two different parts are considered, the first part is solving the OPF problem under normal conditions and the second part is solving the OPF problem under the contingency state.

OPF solution under normal condition. In this part, the SMA is applied to solve the OPF problem under the normal condition with active power loading is 283.4 MW. Three different cases are examined via SMA as follows.

Case 1: Minimization of total fuel cost. The objective function used in the first case under normal condition is to minimize the total fuel cost according to the optimal power distribution of the production units and is described by (13). Table 3 tabulates the results obtained by the SMA algorithm for Case 1. It can be seen that the optimal settings of control variables are all within their acceptable limits. Furthermore, we can also see that the fuel cost obtained by SMA is 798.9709 $/h, this value is lower and better compared to those obtained by MSA, GSO, MFO, BHBO, ALO, MSCA which are mentioned in Table 1.

| Method                          | Fuel cost ($/h) |
|--------------------------------|-----------------|
| Slime mould algorithm          | 798.9709        |
| Moth swarm algorithm [10]      | 800.5099        |
| Glowworm Swarm Optimization [12]| 799.06          |
| Moth-Flame Optimizer [14]      | 799.072         |
| Black-hole-based optimization [20]| 799.921        |
| Ant lion optimizer [31]        | 799.0133        |
| Modified Sine-Cosine algorithm [32]| 799.31        |

Table 1

The convergence characteristics of the proposed method and the ALO algorithm are shown in Fig. 1. It can be seen that the SMA algorithm outperforms the ALO algorithm in terms of convergence rate towards the global optimum solution. So, the results achieved showed the SMA superior and robust compared to the ALO algorithm in order to get the best solution to solve the OPF problem.

Case 2: Minimization of total fuel cost and wind power cost. In this test case, SMA is applied to solve the OPF problem by incorporating stochastic wind power. Thus, the objective function is minimizing the total generation cost that includes fuel cost and wind power cost. The cumulative cost, described by (13). In this case, the standard IEEE 30-bus system is considered by including two wind farms located at bus numbers 10 and 24. Moreover, the two wind farms (WFs) consist of 30 units of wind turbine generation (WTG) with a nominal power rating of each WTG is 2 MW. Thus, each WF having a total capacity of 30 MW.

Table 2 details the specification of wind turbine characteristics used in all optimization cases in this study concern with incorporating wind power for the IEEE 30-bus system [33].

| Parameters          | Value |
|---------------------|-------|
| $k$                 | 2     |
| $c$                 | 3     |
| $d_r$               | 1.3   |
| $P_{wr}$            | 2000 kW |
| $v_{cut-in}$        | 4 m/s |
| $v_{cut-out}$       | 12 m/s |
| $v_{cut-off}$       | 25 m/s |
| $K_{p,j}$ (penalty factor) | 1 $/MWh |
| $K_{r,j}$ (reserve factor) | 4 $/MWh |

Table 2

Table 3 presents for case 2 the results obtained by SMA to minimize the total generation costs, which are the total fuel and wind costs. The sizing of the two wind farms can be referred to in the same table. For this case, SMA exhibit bus 10 and 24 as the optimal locations of the wind farm. At active power loading of 283.4 MW, It can be seen that the TGC produced by SMA is reduced from 798.9709 $/h to 725.7113 $/h. Moreover, the active power losses have also increased from 8.5752 MW to 6.2413 MW which is lowered by 27.21 %. Thus, SMA provides the best values to minimize the TGC and reduce the active power losses in the IEEE 30-bus test system by incorporating wind power compared to the case without the implementation of wind farms. In general, the implementation of wind farm installation to the system has significantly reduced the values of the total generation cost and the active power losses.

Fig. 1. Convergence characteristics of the SMA & ALO: Case 1
Table 3

| Control Variables | Limits | Active power loading 283.4 MW | Active power loading 410.93 MW |
|-------------------|--------|-----------------------------|-------------------------------|
|                   | Min    | Max    | Case 1 | Case 2 | Case 3 | Case 4 | Case 5 | Case 6 |
| $P_{G1}$ (MW)     | 50     | 200    | 177.5784 | 139.3865 | 139.6782 | 199.9977 | 195.2207 | 195.2576 |
| $P_{G2}$ (MW)     | 20     | 80     | 48.6770  | 39.6216  | 39.4803  | 78.8218  | 57.6992  | 57.8394  |
| $P_{G3}$ (MW)     | 15     | 50     | 21.6682  | 18.6332  | 18.5144  | 42.4211  | 32.9495  | 32.7988  |
| $P_{G4}$ (MW)     | 10     | 35     | 21.2316  | 10.0000  | 10.0292  | 34.9915  | 34.9999  | 34.9896  |
| $P_{G11}$ (MW)    | 10     | 30     | 12.0890  | 10.0000  | 10.0025  | 29.9997  | 21.9266  | 23.1781  |
| $P_{G13}$ (MW)    | 12     | 40     | 12.0000  | 12.0000  | 12.0042  | 38.2946  | 20.3897  | 19.1394  |
| $P_{WS1}$ (MW)    | 0      | 40     | –      | 30.0000  | –      | 30.0000  | 30.0000  | 30.0000  |
| $P_{WS2}$ (MW)    | 0      | 40     | –      | 30.0000  | 30.0000 | –      | 30.0000  | 30.0000  |
| $V_{G1}$ (p.u)    | 0.95   | 1.1    | 1.0879  | 1.0894  | 1.0873  | 1.0843  | 1.0804  | 1.0818  |
| $V_{G2}$ (p.u)    | 0.9    | 1.1    | 1.0618  | 1.0644  | 1.0597  | 1.0286  | 1.0264  | 1.0263  |
| $V_{G3}$ (p.u)    | 0.9    | 1.1    | 1.0771  | 1.0760  | 1.0719  | 1.0616  | 1.0699  | 1.0694  |
| $V_{G11}$ (p.u)   | 0.9    | 1.1    | 1.0903  | 1.0987  | 1.0987  | 1.0111  | 1.0991  | 1.0993  |
| $V_{G12}$ (p.u)   | 0.9    | 1.1    | 1.0183  | 1.0150  | 1.0150  | 1.0511  | 1.0975  | 1.0974  |
| $T_{G1}$ (p.u)    | 0.9    | 1.1    | 1.0259  | 1.0988  | 1.0988  | 1.0189  | 1.0896  | 1.1000  |
| $T_{G2}$ (p.u)    | 0.9    | 1.1    | 0.9010  | 1.0887  | 1.0887  | 1.0211  | 1.0991  | 1.0993  |
| $T_{G3}$ (p.u)    | 0.9    | 1.1    | 0.9803  | 1.0786  | 1.0786  | 1.0511  | 1.0975  | 1.0974  |
| $T_{G15}$ (p.u)   | 0.9    | 1.1    | 0.9586  | 1.0429  | 1.0429  | 0.9609  | 1.0272  | 1.0455  |
| $Q_{G1}$ (Mvar)   | 0      | 5      | 4.3806  | 0.0139  | 4.3806  | 4.8813  | 4.1783  | 3.8868  |
| $Q_{G2}$ (Mvar)   | 0      | 5      | 4.7970  | 2.8581  | 4.7970  | 4.8901  | 0.8560  | 0.8560  |
| $Q_{G3}$ (Mvar)   | 0      | 5      | 4.8272  | 0      | 4.7098  | 3.1109  | 3.1556  | 1.6088  |
| $Q_{G4}$ (Mvar)   | 0      | 5      | 4.9942  | 2.7221  | 4.9942  | 4.9727  | 4.9617  | 5.0000  |
| $Q_{G5}$ (Mvar)   | 0      | 5      | 2.5651  | 2.7844  | 2.5651  | 2.3311  | 1.5544  | 4.1684  |
| $Q_{G6}$ (Mvar)   | 0      | 5      | 2.8396  | 5.0000  | 2.8396  | 4.9357  | 0.0066  | 4.9944  |
| $Q_{G7}$ (Mvar)   | 0      | 5      | 3.4609  | 4.8785  | 3.4609  | 2.9808  | 2.7736  | 4.7325  |
| $Q_{G8}$ (Mvar)   | 0      | 5      | 4.9957  | 0.2167  | 4.9957  | 4.6307  | 1.3769  | 0.0423  |
| $Q_{G9}$ (Mvar)   | 0      | 5      | 1.1562  | 0.9389  | 1.1562  | 0.4900  | 1.2900  | 4.8493  |
| $Q_{G10}$ (Mvar)  | 0      | 5      | –      | –      | –      | 3.9403  | 4.7442  | 5.8394  |
| $Q_{G11}$ (Mvar)  | 0      | 5      | –      | –      | –      | 3.7354  | 0.8719  | 10.3240  |
| $Q_{G12}$ (Mvar)  | –25    | 25     | –      | –      | –      | 5.6479  | –      | 6.6716  |
| Total generation cost ($/h) | 798.9709 | 725.7113 | 725.8855 | 1339.4776 | 1198.1826 | 1198.2092 |
| Power losses (MW) | 8.5752 | 6.2413 | 6.3087 | 13.5964 | 12.2555 | 12.2729 |
| Voltage deviation (p.u) | 1.4494 | 0.6285 | 0.5195 | 1.4631 | 1.3915 | 1.3928 |
| Reserved real power | – | 53.5074 | 53.5074 | 53.5074 | – | 53.5074 | 53.5074 |

The convergence curves of the SMA and ALO for case 2 are shown in Fig. 2, which allows us to note, in the first place, that the SMA converges towards the global optimum value at iteration 120 compared to the ALO, that the convergence towards the optimal solution is reached at iteration 270.

Case 3: Minimization of fuel cost and wind power cost by considering the SVC device. In this case study, SMA is applied for solving the OPF problem by incorporating wind power and SVC devices. The optimal location of the SVC device for the IEEE 30-bus system found by SMA is bus N°30. The objective function used is to minimize the TGC as described by (13). From this case, it can be seen that the voltage deviation is reduced from 1.4494 p.u (case 1) and 0.6285 (case 2) to 0.5428 p.u. The voltage profile obtained by the SMA algorithm for cases 2 and 3 is shown in Fig. 3. It is seen that the effect of the SVC device to improve the profile voltage, especially in the busses far from generators units such as bus N°25 until bus N°30.

![Fig. 2. Convergence characteristics of the SMA & ALO: Case 2 OPF solution under the contingency state.](https://ssrn.com/abstract=3824227)
the contingency state, which is increased loading at 45%. Thus, the active power loading is 410.93 MW. Three different cases are considered for this part.

Figure 3. Profile Voltage magnitudes for case 2 and case 3

Case 4: Minimization of total fuel cost. In this case, the objective function is to optimize the total fuel cost in the IEEE 30-bus system with increased loading at 45% and is described by (16) addition to the penalty of line power. From the results given by the SMA algorithm for the case N°5, it can be seen that most generators work near their maximum limits, due to the increased load compared to the results given in case 1 without increased load. Moreover, we can also see that the fuel cost, active power losses, and voltage deviation are increased as presented in Table 3. The convergence characteristics of the SMA and ALO for case 4 are shown in Fig. 4.

Figure 4. Convergence characteristics of the SMA & ALO: Case 4

Case 5: Minimization of total fuel cost and wind power cost. The minimization of total fuel cost and wind power cost, in this case, is formulated as the objective function, which is described by (13). At higher active power loading of 410.90 MW, SMA provides 1198.1826 $/h for the TGC, this value better than a value obtained in a case without incorporating wind power. On the other hand, the implementation of wind farms has reduced the active power losses and the deviation voltage in the system.

The convergence characteristics of the SMA and ALO for case 5 are shown in Fig. 5. From this figure, it demonstrates that the SMA algorithm can converge to the global optimum at iteration 170, while ALO towards the optimal solution is reached at iteration 230.

Figure 5. Convergence characteristics of the SMA & ALO: Case 5

Algerian electrical network system. In order to verify the performance and efficiency of the ALO to solve nonlinear problems in larger-scale dimensions, OPF is performed on the Algerian electrical network system. This system includes 15 generators, 175 transmission lines, and 16 located from line 160 to line 175. The technical and economic parameters of generator units of the Algerian electrical network system are presented in [34].

Case 7: Minimization of total fuel cost. In this case, SMA is tested to identify the optimal fuel cost on the large-scale Algerian electrical network system with 114 buses. Table 4 presents the optimal settings of control variables reached by SMA with three different cases taking into consideration the vector of control variables contains the active powers generated and the generator voltages. The best value of fuel cost obtained by SMA for the vector of control variables contains the active powers generated is 18914.105 $/h and better than other methods as well as previously reported methods in Table 5.

The convergence characteristics of the proposed algorithm and ALO algorithm for case 7 are shown in Fig. 7. It can be seen that the SMA algorithm outperforms the ALO algorithm in terms of convergence rate towards the global optimum solution.

Table 4: The optimal settings of control variables reached by SMA for case 7

Algerian electrical network system. In order to verify the performance and efficiency of the ALO to solve nonlinear problems in larger-scale dimensions, OPF is performed on the Algerian electrical network system. This system includes 15 generators, 175 transmission lines, and 16 located from line 160 to line 175. The technical and economic parameters of generator units of the Algerian electrical network system are presented in [34].

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The convergence characteristics of the proposed algorithm and ALO algorithm for case 7 are shown in Fig. 7. It can be seen that the SMA algorithm outperforms the ALO algorithm in terms of convergence rate towards the global optimum solution.
Table 4

Best control variable settings obtained via SMA for ALG 114-bus system including WPG and SVC devices

| Control Variables | Case 7 | Case 8 | Case 9 | Control Variables | Case 7 | Case 8 | Case 3 |
|-------------------|--------|--------|--------|-------------------|--------|--------|--------|
| \( P_{G11} \) (MW) | 451.3078 | 444.8246 | 446.5335 | \( V_{G11} \) (p.u.) | 1.0997 | 1.1000 | 1.0999 |
| \( P_{G12} \) (MW) | 451.1405 | 444.3754 | 445.8411 | \( V_{G12} \) (p.u.) | 1.1000 | 1.1000 | 1.0993 |
| \( P_{G17} \) (MW) | 446.9078 | 439.3309 | 441.6877 | \( V_{G17} \) (p.u.) | 1.1000 | 1.1000 | 1.1000 |
| \( P_{G22} \) (MW) | 194.8571 | 189.3309 | 189.6877 | \( V_{G22} \) (p.u.) | 1.1000 | 1.1000 | 1.1000 |
| \( P_{G52} \) (MW) | 191.8038 | 186.3309 | 186.6877 | \( V_{G52} \) (p.u.) | 1.1000 | 1.1000 | 1.1000 |
| \( P_{G80} \) (MW) | 187.8661 | 182.3309 | 182.6877 | \( V_{G80} \) (p.u.) | 1.1000 | 1.1000 | 1.1000 |
| \( P_{G83} \) (MW) | 187.3028 | 181.8309 | 182.1877 | \( V_{G83} \) (p.u.) | 1.1000 | 1.1000 | 1.1000 |
| \( P_{G98} \) (MW) | 184.8078 | 179.3309 | 180.6877 | \( V_{G98} \) (p.u.) | 1.1000 | 1.1000 | 1.1000 |
| \( P_{G100} \) (MW) | 193.8078 | 188.3309 | 188.6877 | \( V_{G100} \) (p.u.) | 1.1000 | 1.1000 | 1.1000 |
| \( P_{G101} \) (MW) | 196.3078 | 190.8309 | 191.1877 | \( V_{G101} \) (p.u.) | 1.1000 | 1.1000 | 1.1000 |
| \( P_{G109} \) (MW) | 199.8078 | 194.3309 | 194.6877 | \( V_{G109} \) (p.u.) | 1.1000 | 1.1000 | 1.1000 |
| \( P_{G111} \) (MW) | 202.3078 | 196.8309 | 197.1877 | \( V_{G111} \) (p.u.) | 1.1000 | 1.1000 | 1.1000 |

Table 5

Comparison of solutions achieved using SMA and different methods for Case 7

| Method | Fuel cost ($/h) |
|--------|----------------|
| Slime mould algorithm | 18914.105 |
| Differential evolution [34] | 19203.340 |
| Grey wolf optimizer [35] | 19179.958 |
| Hybrid GA-DE-PS [36] | 19199.444 |
| M-objective ant lion algorithm [37] | 19355.859 |

Table 6

The characteristics of this wind turbine

| Parameters | Wind turbine 1 | Wind turbine 2 |
|------------|----------------|---------------|
| \( K_p \) (penalty factor) | 1.5 $/MWh | 1.5 $/MWh |
| \( K_r \) (reserve factor) | 3 $/MWh | 3 $/MWh |

Fig. 7. Convergence characteristics of the SMA & ALO: Case 7

Case 8: Minimization of total fuel cost and wind power cost. In this case, SMA is applied to solve the OPF problem on the large-scale power system by incorporating stochastic wind power. The Algerian power system ALG 114-bus is considered by including two wind generators located at buses 99 (Setif) and 107 (Djelfa). Moreover, the two wind farms (WF) consist of 40 units of wind turbine generation (WTG) are connected to the system at buses 10 and 24 with a nominal power rating of each WTG is 1.5 MW. Weibull settings for the sites that have been chosen are taken from [38]. The choice of the turbine has been set for General Electric GE 1,5-77 machines. The characteristics of this wind turbine are shown in Table 6.

Table 4 summarizes the best results reached by SMA to minimize total generation cost, reduce active power losses and improve the voltage profile by incorporating two wind farms. Based on the results achieved by the SMA in case 7 compared to case 8, the incorporation of wind farms into the system in the ALG 114 system gave more significant profit in TGC and reducing active power losses. The convergence characteristics of the SMA for case 8 are shown in Fig. 8. The convergence of the SMA is reached in the first 170 iterations, while the convergence of the ALO towards the optimal solution is reached at iteration 230.
**Case 9: Minimization of total fuel cost and wind power cost by considering the SVC device.** In order to illustrate the effectiveness of the SMA in presence of SVC devices on the power system, the ALG 114-bus is considered by including two SVC devices at busses N°68 (Sedjerara) and buss N°89 (Souk Ahras). These locations of SVC devices are considered the optimal placement in the Algerian 114-bus system found by the SMA algorithm. After the results of the simulation, the installation of the SVC improved considerably the total generation cost, the active power loss. Figure 9 represents the effect of SVC devices is significant in the Algerian 114-bus system to maintain the voltages within the acceptable limits.

**Conclusion.** This paper proposed a recent metaheuristic technique called a slime mould algorithm to solve the optimal power flow problem incorporating stochastic wind power and static VAR compensator devices. In this study, nine cases have been considered and examined via the proposed algorithm on the IEEE 30-bus system and practical Algerian power system ALG 114-bus. The objective function solved is a minimization of the total generation cost that includes fuel cost and wind power cost. Also, the nature of the wind output function used is based on the Weibull probability distribution function. For the case without considering wind power and static VAR compensator devices, it is worth mentioning that the proposed algorithm is capable of achieving and getting the best global optimal solution for both of the testing systems compared to the other methods in the literature mentioned in this paper. With considering wind power and SVC devices, the numerical results obtained show a better performance of the proposed algorithm to solve the optimal power flow problem compared to the ant lion optimizer algorithm. Additionally, incorporating the wind power and static VAR compensator device has a high influence on the power system through minimize the total generation cost, reduce the active power loss as well as improve the voltage profile. Thus, the results obtained prove the merits and efficiency of the proposed algorithm to solve the stochastic optimal power flow problem.

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