Thinking outside the box: fluctuations and finite size effects

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Abstract

The isothermal compressibility of an interacting or non-interacting system may be extracted from the fluctuations of the number of particles in a well-chosen control volume. Finite size effects are prevalent and should be accounted for to obtain a meaningful, thermodynamic compressibility. In the traditional computational setup, where a given simulation box is replicated with periodic boundary conditions, we study particle number fluctuations outside the box (i.e. when the control volume exceeds the box itself), which bear relevant thermodynamic information. We also investigate the related problem of extracting the compressibility from the structure factor in the small wave-vector limit ($k \to 0$). The calculation should be restricted to the discrete set of wave-vectors $k$ that are compatible with the periodicity of the system, and we assess the consequences of considering other $k$ values, a widespread error among beginners.

Keywords: statistical mechanics, fluctuations, computational physics

(Some figures may appear in colour only in the online journal)

1. Context and motivation

In 1914, Ornstein and Zernike\textsuperscript{[1]} showed that in an equilibrium system at temperature $T$ and density $\rho$,

\[
\frac{\chi_\infty}{\chi^\eta} = 1 + \rho \int_D \left[ g(r) - 1 \right] \, dr.
\]

This emblematic achievement of statistical mechanics—also known as the compressibility equation—connects the fluctuations of the number of particles $N_D$ in a domain $D$ of a given infinite system to the macroscopic isothermal compressibility $\chi_\infty$ and to local structure through the pair correlation function $g(r)$,\textsuperscript{[2, 3]} which encodes the local structure; see appendix A.
Here, $\chi^g_\infty = (\rho k_B T)^{-1}$ is the ideal gas compressibility while $k_B$ is the Boltzmann constant. Equation (1) shows that at a critical point where $\chi_\infty \to \infty$, the amplitude of fluctuations also diverges and a long-range order sets in. Away from the critical point or the phase coexistence regime, equation (1) provides an operational way to compute the compressibility in a numerical simulation, but particular attention should be paid to finite size effects—see [4] for a review and references therein. Indeed, the bulk compressibility follows from equation (1) under grand canonical conditions, that is, when $D$ is a sub-part of an otherwise infinite (or large enough) system, such that in addition $D$ is bigger than the relevant microscopic length (particle size, correlation length etc). In practice, however, some simulation techniques like molecular dynamics operate under microcanonical conditions: fixed available volume, total number of particles $N$ and energy, with periodic boundary conditions to emulate bulk properties. Making use of the left-hand-side equality of (1) to infer $\chi_\infty$, one may be tempted to use large volumes $D$, in which case important finite size effects should be accounted for [3, 5]. They are the central issue under scrutiny here.

The question is the following: considering that in general the left-hand side of equation (1) defines a finite sized compressibility $\chi_L(D)$ from the fluctuations of the number of particles in a volume $D$, itself enclosed in a cubic simulation box of size $L$, i.e.

$$\frac{\chi_L(D)}{\chi^g_\infty} = \frac{\langle N_D^2 \rangle - \langle N_D \rangle^2}{\langle N_D \rangle},$$

what is the connection between $\chi_L(D)$ and the thermodynamic compressibility $\chi_\infty$? According to (1), both quantities should coincide when $L$ becomes very large, in which case $\chi_L(D)$ no longer depend on $D$, provided $D$ it is not too small and does not interfere with microscopic lengths. How does $\chi_L(D)$ depend on $D$, when the latter volume is not negligible compared to the one available? We will address below this question in the presence of periodic boundary conditions. It has already been answered in the literature when $D$ is a sub-volume of the simulation box (see [6] for a pedagogical account), but not in the ‘reverse’ perspective, with the simulation box as a sub-part of $D$ (i.e. $L^d < A(D)$ where $d$ is space dimension and $A(D)$ is the volume of domain $D$). The present study of fluctuations ‘outside the box’ is, to the best of our knowledge, original. It offers the possibility to infer thermodynamic information from a measure that is endowed with strong explicit finite size effects, and can be used as a teaching material for an advanced undergraduate course in statistical physics or computational techniques. The discussion is entirely based on elementary considerations: basic probability concepts like the law of total variance, and tools like correlation functions in direct or reciprocal space. Interesting relations can be derived that are usually not found in textbooks.

The paper is organized as follows. Before addressing in detail fluctuations ‘outside the box’, it is informative to decipher explicit size effects ‘inside the box’, which can be achieved from appropriate applications of (1). This is worked out in section 2, where known results are recovered, but from an original angle. We then turn our attention outside the box in section 3, which requires more subtle arguments, due to periodicity effects which create correlations between the particles inside the box, and their images outside. Sections 2 and 3 both are real space studies, and for completeness, we investigate the structure factor $S_L(k)$, which can be viewed as a scale dependent compressibility living in Fourier space. It is well known that $S_L(k)$ yields at small $k = |k|$ the thermodynamic compressibility, provided it is computed on the discrete set of ‘allowed’ Fourier modes compatible with the periodic boundaries. As an echo to the out-of-the-box viewpoint in real space, we analyse in section 4 the consequences of computing $S_L(k)$ for $k < 2\pi/L$, namely for wavelengths that exceed the box size, and more generally for $k$ values that are not within the allowed set [3]. While such a procedure clearly is erroneous, it is instructive to discuss the consequences of such a mistake that is made by
many beginners, and is sometimes found in the literature. The more technical aspects of the
discussion are relegated to appendices. Our conclusions are finally drawn in section 5.

2. Finite size effects within the box

We begin our discussion by emphasizing that in equation (1), the left-hand-side equality
\[
\frac{\chi_\infty}{\chi_{ig}} = \frac{\langle N_D^2 \rangle - \langle N_D \rangle^2}{\langle N_D \rangle^2} \tag{3}
\]
holds not only when \(D\) is large, but also under the proviso that this latter volume is negligible
compared to the whole available space. In that case, \(\chi_\infty(D) = \chi_\infty\). In practice, of course, one
has to work with a finite system, taken to be a cubic box of length \(L\), so that the condition for
the validity of (3) reads \(\sigma^d \ll A(D) \ll L^d\), with \(\sigma\) some microscopic length. This emulates a
grand canonical environment. It is thus important to know how \(\chi_\infty(D)\), defined in (2), depends
both on \(D\) and \(L\). We will see that this dependence is universal. Before going into the details of
the measurement of finite size effects, we present here the model used throughout this paper
as a test-bench and prototypical interacting fluid.

We have considered \(N\) particles moving in a two-dimensional box of length \(L\) with periodic
boundary conditions. The highly repulsive interaction potential \(U\) is pair-wise additive and
takes the form:
\[
U(r_i, r_j) \propto \left(\frac{\sigma}{|r_i - r_j|}\right)^{64}. \tag{4}
\]
With such an interaction, the phenomenology is very close to the hard disks case, with an
effective diameter \(\sigma_{\text{eff}} \simeq \sigma\) (for instance, the bulk compressibility is well estimated by the
Henderson’s equation for hard disks [7]). Therefore, we introduce the reduced effective density,
defined as
\[
\rho^* = \frac{N}{L^2} \sigma^2, \tag{5}
\]
which measures the relevance of interaction among the particles. The ideal gas is retrieved in the
limit \(\rho^* \to 0\). The system has been studied via molecular dynamics simulations at fixed energy,
namely in the ensemble NVE. In short, the equations of motion are numerically integrated via
the velocity Verlet algorithm with periodic boundary conditions, assuring homogeneity [3, 5,
8]. In order to study finite size effects, we have then measured the number of particles variance
and the mean in a square domain \(D\) of size \(l\).

On the left-hand side of figure 1, we see that \(\chi_\infty(D)\) indeed goes to a plateau for \(l \gg \sigma\),
giving the thermodynamic compressibility of the system. This is true, however, provided
\(l \ll L\), and when \(l/L\) is no longer small, \(\chi_\infty(l)\) decreases strongly—see the right-hand side of
figure 1. In the limiting case where \(l = L\), the number of particles in the control volume no
longer fluctuates since it takes the known value \(N\). Hence \(\chi_\infty(L) = 0\), as can be seen in the
figure. More specifically, it has been shown that [6]
\[
\frac{\chi_\infty(l)}{\chi_{ig}} = \chi_\infty \left(1 - \frac{l^2}{L^2}\right), \tag{6}
\]
under the proviso that \(l \gg \sigma\), i.e. that one should not probe microscopic control volumes. In
the present geometry, this relation is well obeyed—see figure 2. More generally, when \(D\) is
arbitrary and of volume \(A(D)\), the parenthesis reads \((1 - A(D)/L^d)\) in arbitrary dimension \(d\).
It therefore appears that the finite size effects, embedded in the term in parenthesis, factorize
from those due to interactions (given by \(\chi_\infty/\chi_{ig}\)). We offer below a derivation in two steps of
equation (6) that differs from existing ones, first when \(l\) is close to \(L\), where the factorization
Figure 1. Molecular dynamics results for a cubic control volume \( \mathcal{D} \) of linear extension \( l \), in a simulation box of size \( L \). Left: the behaviour for small \( l \) of the reduced variance defined in (2). Right: the same quantity for different numbers of particles. In both figures, the reduced density (\( \rho^* \equiv \rho \sigma^2 \) where \( \sigma \) is particle size) is fixed to \( \rho^* = 0.26 \), and the horizontal dashed line shows \( \chi_\infty / \chi^*_{ig} \). For each value of \( N \), the vertical arrow shows \( L/\sigma \equiv (N/\rho^*)^{1/2} \).

Figure 2. Behaviour of the reduced variance defined in (2), which can arguably be viewed as a finite size compressibility, for the case \( l < L \) and different effective densities. As above, \( L \) is the simulation box size and \( l \) is the size of the control volume \( \mathcal{D} \), inside which the number of particle \( N_D \) fluctuates. When \( l = L \), \( N_D = N \), the known number of particles in the simulation box, and thus does not fluctuate (\( \chi_\infty (l) = 0 \)). The solid line is the prediction given by equation (6). The horizontal dashed curves on the left-hand side show the ratio \( \chi_\infty / \chi^*_{ig} \) of the bulk compressibility over its ideal gas counterpart.

The property is immediately apparent, and then without restrictions but for \( l \gg \sigma \). The situation where \( l > L \) is the subject of section 3. It is worth stressing that in the ideal gas case, the relation \( \chi^*_{ig} (l) / \chi^*_{ig} = (1 - l^2 / L^2) \) follows from elementary considerations—see appendix B, which repeats the main arguments used in [6].

At this point, one may wonder about the possible finite size effects that may affect the right-hand side of equation (1). This equality does not assume \( l \ll L \), but it requires a large
enough domain $D$ ($l \gg \sigma$). Interestingly, it may be extended to hold for arbitrary $D$: in general, we have

$$\frac{\langle N_D^2 \rangle - \langle N_D \rangle^2}{\langle N_D \rangle} = 1 + \rho \int_{\tilde{D}} w_D(r) [g_N(r) - 1] \, dr,$$

the derivation of which can be found in appendix C. As compared to (1), note the weighting factor $w_D$ and the integration over a different domain $\tilde{D}$. When the volume $D$ is large enough, the right-hand side equality of (1) holds, as explained in appendix C.

By means of equation (7), it is possible to explain the behaviour of the finite size compressibility $\chi_L(D)$ for short length scales. Indeed, we come back to figure 1 and focus on the microscopic range where $l$ is comparable to the particle size $\sigma$, and where $\chi_{\infty} / \chi^0_{\infty}$ raises to unity. First, this can be readily understood from the limiting case where $l$ is quite a bit smaller than $\sigma$, so that there is at most one particle in $D$, with a small probability $p \ll 1$, or none with probability $1 - p$. Hence $N_D$ becomes here a Bernoulli variable ($N_D = 0$ or 1), so that the variance $\langle N_D^2 \rangle - \langle N_D \rangle^2 = p - p^2 \simeq p$, which thus equals $\langle N_D \rangle$. The left-hand term of equation (7) is accordingly unity and so is the right-hand side, where the integral is small compared to 1. When the volume of $D$ increases, this integral contributes negatively since $g(r) \simeq 0$ for $r < \sigma$, as a consequence of hard core repulsion. This explains the initial decay observed for small sizes in figures 1, which can be further rationalized since having a vanishing $g$ for small inter-particle distances implies, from (7), that

$$\frac{\chi_L(l)}{\chi^0_{\infty}} \simeq 1 - \rho l^2 = 1 - \rho^* \left( \frac{l}{\sigma} \right)^2 \quad \text{for} \quad l < \sigma,$$

where use has been made of $\int_{\tilde{D}} w_D(r) \, dr = A(D)$. As can be seen in figure 3, which also displays a typical $g(r)$, this relation is well obeyed.

2.1. Factorization properties and fluctuations in a large sub-region

We know that $\chi_L(L) = 0$, and we give here a simple argument that explains how $\chi_L(l)$ approaches 0 when $l$ approaches $L$, following the form given in equation (6). The space
dimension $d$ is here unspecified. We consider again a square sub-domain $\mathcal{D}$ (size $l$) of the confining box (size $L$). When $l$ is close to $L$ (with $l < L$), the idea is to consider the complementary domain of $\mathcal{D}$, noted $\overline{\mathcal{D}}$, such that the volumes obey $A(\mathcal{D}) + A(\overline{\mathcal{D}}) = L^d$. We assume that $\overline{\mathcal{D}}$, although much smaller than $\mathcal{D}$, is large enough compared to the microscopic scale $\sigma$. Under these circumstances, $\mathcal{D}$ plays for $\overline{\mathcal{D}}$ the role of a reservoir of particles, and $\overline{\mathcal{D}}$ is ruled by the grand canonical laws. In particular, the number of molecules in $\overline{\mathcal{D}}, N_{\overline{\mathcal{D}}}$, obeys

$$\frac{\chi_i}{\chi_i^0} = \frac{\langle N_{\overline{\mathcal{D}}}^2 \rangle - \langle N_{\overline{\mathcal{D}}} \rangle^2}{\langle N_{\overline{\mathcal{D}}} \rangle^2}.$$

(9)

We then note that $N_{\mathcal{D}} + N_{\overline{\mathcal{D}}} = N$ is a non-fluctuating quantity. Hence, $N_{\mathcal{D}}$ and $N_{\overline{\mathcal{D}}}$ have the same variance, a quantity that will be denoted by $V$:

$$V(N_{\mathcal{D}}) = V(N_{\overline{\mathcal{D}}}) \implies \langle N_{\overline{\mathcal{D}}}^2 \rangle - \langle N_{\overline{\mathcal{D}}} \rangle^2 = \langle N_{\mathcal{D}}^2 \rangle - \langle N_{\mathcal{D}} \rangle^2.$$

(10)

On the other hand, we have from homogeneity

$$\langle N_{\mathcal{D}} \rangle = \frac{A(\mathcal{D})}{L^d} N$$

and

$$\langle N_{\overline{\mathcal{D}}} \rangle = \left(1 - \frac{A(\mathcal{D})}{L^d}\right) N.$$

(11)

Gathering results, we reach the desired expression for $\chi_i(l)$

$$\frac{\chi_i(l)}{\chi_i^0} = \frac{\langle N_{\overline{\mathcal{D}}}^2 \rangle - \langle N_{\overline{\mathcal{D}}} \rangle^2}{\langle N_{\overline{\mathcal{D}}} \rangle^2} = \frac{\chi_i}{\chi_i^0} \frac{L^d - A(\mathcal{D})}{A(\mathcal{D})} \simeq \frac{\chi_i}{\chi_i^0} \left(1 - \frac{A(\mathcal{D})}{L^d}\right) \equiv \frac{\chi_i}{\chi_i^0} \left(1 - \frac{l^d}{L^d}\right),$$

(12)

where use was made of the condition $A(\mathcal{D}) \simeq L^d$. As expected, $\chi_i(L) = 0$. We have thus justified that finite size effects arise in $\chi_i(l)$ through a purely geometric factor, $(1 - A(\mathcal{D})/L^d)$, a result that so far holds under the requirement that $\mathcal{D}$ almost fills the available volume $L^d$. As shown in figure 2, it is possible to extend the validity of that expression in a large range of $\mathcal{D}$ volumes, provided $A(\mathcal{D}) \gg \sigma^d$, in order to wash out microscopic details. This is the purpose of the next section.

2.2. Factorization property and pair correlation function

The line of reasoning goes here through the particle correlation function $g_N(r)$ defined in appendix A. We remind readers that $\rho g_N(r)$ is the density of molecules at point $r$, given that one molecule is at the origin. Its expression is slightly different in a finite box with $N$ molecules, and in a truly infinite system at the same density, where it is denoted by $g(r)$. In order to get a flavour of the leading order difference between $g_N(r)$ and $g(r)$, we go back to the ideal gas case, for which all the $g$s have to be uniform, since there is no length scale in the model. By definition, $\rho \int \rho g_N(r)$ counts the number of neighbours around a given tagged molecule, which is therefore $N - 1$. This means that $g_N(r) = 1 - 1/N$, which in turn implies that $g(r) = 1$ [3].

Instructed by the ideal gas limiting case where $g_N(r) = g(r) - 1/N$, we go back to interacting systems and assume that the first finite $N$ correction to $g(r)$ reads

$$g_N(r) = g(r) + \delta g$$

(13)

where $\delta g$ does not depend on $r$, and is likely to scale like $1/N$. We then use equation (7) for a non-microscopic domain $\mathcal{D}$, in which case

$$\frac{\chi_i(l)}{\chi_i^0} = \frac{\langle N_{\overline{\mathcal{D}}}^2 \rangle - \langle N_{\overline{\mathcal{D}}} \rangle^2}{\langle N_{\overline{\mathcal{D}}} \rangle} = 1 + \rho \int_D \left[g_N(r) - 1\right] dr.$$

(14)
From equation (13) we have
\[ \chi_L(l) = 1 + \rho \int_D (g(r) - 1) \, \text{d}r + \rho \int_D \delta_g \, \text{d}r = \chi_\infty + \rho A(D) \delta_g, \] (15)

where equation (1) has been used.

Next, a necessary requirement is that \( \chi_L(L) = 0 \), which imposes that
\[ \rho \delta g L^d = -\frac{\chi_\infty \chi_\infty}{N}. \] (16)

We obtain here a non-trivial result, which generalizes to interacting systems the ideal gas relation (see also [9] for a more general discussion):
\[ g_N(r) = g(r) - \frac{\chi_\infty}{N \chi_\infty}. \] (17)

Inserting equation (16) into equation (15), one obtains
\[ \frac{\chi_L(D)}{\chi_\infty} = \frac{\chi_\infty}{\chi_\infty} \left( 1 - A(D) \frac{L^d}{L^d} \right), \] (18)

which is exactly equation (6). We point out that there is also another term of order \( O(1/N) \) in equation (17). However, it depends on \( \rho \) and contributes to the compressibility only with a sub-leading term in system size, leaving the result in equation (18) unaffected since the domain \( D \) is here taken to be large (see [10] for a detailed discussion). We thus see that the ideal gas finite size correction (B.3) also applies to interacting fluids. It is also worth stressing that we did not assume, at any stage, that the interaction potential was pair-wise additive (except in the simulated model used for illustrative purposes).

The goal in the subsequent analysis is to decipher the fluctuation behaviour of the number of molecules \( N_D \), through \( \chi_L(l) \), when the control volume is larger than the confining box \( (l > L, \text{ with periodic boundary conditions}) \). Clearly, equation (18) no longer holds ‘outside the box’, where \( A(D) > L^d \), since it would predict a negative variance for \( N_D \).

3. Fluctuations outside the box

If one consider domains larger than the simulation box, due account must be taken of the presence of the images in the replicated boxes of a given particle from the simulation box, in order to have a proper calculation of the fluctuations. For the sake of simplicity, we discuss again the two dimensional case with a square region \( D \). We postpone the discussion on the relevance of the dimensionality to the end of the section. Let us consider the representation in figure 4 (left), where \( D \) is of length \( l \) such that \( L < l < 2L \). The number \( N_1 \) of particles contained in this control volume can be so decomposed:
\[ N_1 = N_0 + 4N_1 + 2N_2, \] (19)

where \( N_1 \) and \( N_2 \) are respectively the number of particles contained in the regions \( D_1 \) and \( D_2 \) shown in figure 4 (right), and \( N_0 \) is the number in the central white area \( D_0 \). Since the number of particles in the system is fixed, these quantities obey the following constraint:
\[ N = N_0 + N_1 + N_2, \] (20)

which is therefore non-fluctuating. Equation (20) can be used to simplify equation (19) since the confining box is entirely contained in the region of length \( l \) and does not contribute to the
fluctuations. Then, the total number of particles inside $\mathcal{D}$, from equation (19), can be rewritten as $N_i = N + N_{fl}$ where

$$N_{fl} = 3N_1 + N_2,$$

and both quantities have the same variance: $V(N_{fl}) = V(N_i)$.

From this example one learns that, in order to describe the number fluctuations for every length $l$, an important quantity is the number of cells (the original one and the replicated ones) which are included in the domain of interest. Therefore, the relevant parameters are

$$\kappa = \left\lfloor \frac{l}{L} \right\rfloor \quad \text{and} \quad x = \frac{l - \kappa L}{2},$$

where $\lfloor \ldots \rfloor$ is the ‘integer part’ function\(^3\). Note that $x < L/2$, by definition. The relation (21) can be easily generalized to any value of $l$, also larger than $2L$, yielding:

$$N_{fl} = (2\kappa + 1)N_1 + \kappa N_2.$$  \hspace{1cm} (22)

In conclusion, it appears from equation (23) that, due to periodicity, the particle fluctuations ‘outside’ the box can be recast as a sum of contributions ‘inside’ the confining box. We can therefore resort to the considerations of appendix D, which rely on the so-called law of total variance. It is shown there that

$$V(\alpha N_1 + \beta N_2) = \frac{(\alpha p_1 + \beta p_2)^2}{p_1 + p_2} V(N_1 + N_2) + (\alpha - \beta)^2 E[V(N_1|N_1 + N_2)] + E[V(N_1|N_1 + N_2)]/E[N_1 + N_2],$$

where in the last term $V(N_1|N_1 + N_2) = V(N_2|N_1 + N_2)$ is the variance of $N_1$, given that $N_1 + N_2$ has a prescribed fixed value. Once this variance is known for fixed $N_1 + N_2$, it should subsequently be averaged over the probability distribution of $N_1 + N_2$, to provide the mean

\(^3\lfloor x \rfloor = n$ where $n$ is the largest integer that satisfies the inequality $n \leq x$.\)
\[ E[V(N_1|N_1 + N_2)] \] sought for, appearing on the right-hand side of (24). The key point next is that we can apply the compressibility relation (6) twice, to get first \( V(N_1 + N_2) \) and then \( V(N_1|N_1 + N_2) \). In the present geometry,

\[
p_1 = \frac{\mathcal{A}(D_1)}{L^2} = \frac{4x^2}{L^2}, \quad p_2 = \frac{\mathcal{A}(D_2)}{L^2} = \frac{4x(L - 2x)}{L^2},
\]

but for the time being, we do not need to specify these values. To get \( V(N_1 + N_2) \), we consider the region \( D_1 \cup D_2 \), which is a sub-domain of the confining box having \( N \) particles, so that

\[
V(N_1 + N_2) = \frac{x}{x_\infty} (N_1 + N_2) \left( 1 - \frac{\mathcal{A}(D_1) + \mathcal{A}(D_2)}{L^2} \right)
\]

\[
= \frac{x}{x_\infty} N(p_1 + p_2)(1 - p_1 - p_2).
\]

Likewise \( V(N_1|N_1 + N_2) \) is the variance of the number of particles in \( \mathcal{A}(D_1) \), given that there are exactly \( N_1 + N_2 \) particles in \( D_1 \cup D_2 \). Thus

\[
V(N_1|N_1 + N_2) = \frac{x}{x_\infty} E(N_1|N_1 + N_2) \left( 1 - \frac{\mathcal{A}(D_1)}{\mathcal{A}(D_1) + \mathcal{A}(D_2)} \right)
\]

\[
= \frac{x}{x_\infty} N_1 \left( 1 - \frac{p_1}{p_1 + p_2} \right)
\]

and we finally need \( E(N_1 + N_2) = \langle N_1 + N_2 \rangle = N(p_1 + p_2) \) to reach

\[
E[V(N_1|N_1 + N_2)] = \frac{x}{x_\infty} Np_1 \left( 1 - \frac{p_1}{p_1 + p_2} \right).
\]

Going back to equation (24), this yields

\[
V(N_i) = \frac{x}{x_\infty} N(p_1 + p_2) \left[ \frac{\alpha p_1 + \beta p_2}{p_1 + p_2} \right]^2 \left( 1 - p_1 - p_2 \right) + \left( \alpha - \beta \right)^2 \left( \frac{p_1 p_2}{(p_1 + p_2)^2} \right).
\]

This expression is general. We now specify it for the probabilities given in equation (25), obtaining

\[
V(N_{fl}) = \frac{x}{x_\infty} N \frac{4x(L - 2x)(\kappa L^2 + 4\kappa Lx + x(L + 2x))}{L^4}.
\]

Moreover, from equations (22), the mean number of particles in a box of length \( l \) can be rewritten as:

\[
E(N_i) = \langle N_i \rangle = \frac{N}{L^2} (\kappa L + 2x)^2.
\]

The final formula of the compressibility is then given by

\[
\chi_c(l) = \frac{x}{x_\infty} \frac{4x(L - 2x)(\kappa L^2 + 4\kappa Lx + x(L + 2x))}{L^2 (\kappa L + 2x)^2},
\]

which is remarkably well obeyed by simulation data—see figure 5. Let us note that in the case \( l < L \), where \( \kappa = 0 \) and \( x \equiv l \), equation (18) is recovered. In the literature, a distinction is made between explicit (due to ensemble averages) and implicit (due to periodic boundary conditions) finite size effects. It is then noteworthy that both effects are at work in equation (32)[11]. We stress again that we are describing here the most general and model independent contribution and we are neglecting the effects due to the microscopic region, namely when \( x \) (or \( L - x \)) is of the order of the correlation length (around \( \sigma \) in our case). At this scale, periodic boundary conditions can give rise to other implicit corrections that can be relevant in denser regimes [12, 13].
The behaviour of $\chi_L(l)$ for $l > L$ is oscillatory, since $\chi_L(l^\star) = 0$ for each $l^\star$ that is commensurate with the length of the box, namely for $l^\star = L, 2L, 3L, \ldots$. Then, for each interval $\kappa L \leq l \leq (\kappa + 1)L$, $\chi_L$ reaches a maximum at an $x$ value slightly lower than $x = L/4$, which tends asymptotically to $L/4$ for large $\kappa$. Indeed, for large $l$, namely large $\kappa$, one has that:

$$\chi^{(d=2)}_L(l) \simeq \frac{4x(L - 2x)}{L^2},$$

where the superscript keeps track of the dimensionality of the system. Equation (33) has the interesting property of being independent of $\kappa$, resulting asymptotically in a periodic function.

Finally, the arguments presented in this section can be adapted to different dimensions, and it turns out that the asymptotic behaviour (33) is strongly connected to the dimensionality of the system. We shall not repeat the full calculation, but we deduce instead the behaviour for large $l$ from a simple scaling approach. When $x \simeq L/4$, the fluctuation of $N_{fl}$ stems from a surface contribution, and each different cell at the boundary of the domain under consideration behaves independently from the other ones. The variances can therefore be added, resulting in

$$V(N_{fl}) \propto \kappa^{2(d-1)}N \quad \text{while} \quad E(N_{t}) \propto \kappa^dN.$$ (34)

Equation (34) explains the peaks observed in figure 6, since:

$$\chi^{(d)}_L \propto \kappa^{d-2} \quad \text{for} \quad \kappa \gg 1 \ \text{and} \ x \simeq \frac{L}{4},$$

with therefore a growing amplitude for large $l$ in three dimensions, and conversely a decrease in one dimension.

**4. The structure factor**

4.1. Definition and low $k$ behaviour

Having analysed real space probes for density fluctuations and correlations in sections 2 and 3, we now turn to a related and complementary study in Fourier space. A convenient measure
of density–density correlations, used in experiments, theory and simulations alike, is given by the structure factor, defined as

$$ S(k) = \frac{1}{N} \langle \hat{\rho}(k) \hat{\rho}(-k) \rangle, \quad (36) $$

where the microscopic density $\hat{\rho}$ and its Fourier transform are introduced:

$$ \hat{\rho}(r) = \sum_{j=1}^{N} \delta(r - r_j) \quad \Rightarrow \quad \hat{\rho}(k) = \int dr \hat{\rho}(r) e^{-ik \cdot r} = \sum_{j=1}^{N} e^{-ik \cdot r_j}. \quad (37) $$

From equation (36), it follows that

$$ S_L(k) = \frac{1}{N} \sum_{i=1}^{N} \sum_{j=1}^{N} \langle \exp[-ik \cdot (r_i - r_j)] \rangle = 1 + \frac{1}{N} \sum_{i \neq j} \langle \exp[-ik \cdot (r_i - r_j)] \rangle, $$

where the system size $L$ appears explicitly as a subscript. For indiscernible particles, there are $N(N-1)$ possible couples $(i,j)$ involved in the summation above, and thus

$$ S_L(k) = 1 + (N-1) \langle \exp[-ik \cdot r_{12}] \rangle. \quad (38) $$

The equilibrium average $\langle \ldots \rangle$, which pertains to a homogeneous system, can be expressed in terms of $g_N(r)$, but some attention should be paid to normalization. Remembering that $\rho \int g_N(r) dr = N - 1$ where the integral runs over the total available volume $L^d$ and $\rho = N/L^d$, a simple requirement to set normalization right is to enforce that (1) be unity, so that

$$ S_L(k) = 1 + \frac{N}{L^d} \int dr w_L(r) g_N(r) e^{-ik \cdot r}. \quad (39) $$

where the weight function $w_L(r)$ is a consequence of changing to the new variable $r \equiv r_1 - r_2$. It already appeared in equation (7) and is defined in equation (C.8) of the appendix C. The term $w_L(r)$ is quasi-systematically overlooked in the literature, which assumes that $L$ is big enough, as we now assume. In that case, we do not need to specify the volume of integration in (39),
which avoids the subtleties discussed in appendix E. In the thermodynamic limit \( L \to \infty \), \( N \to \infty \), \( N/L^d = \rho \) (\( \rho \) constant), one has

\[
\lim_{L \to \infty} S_L(k) = S_\infty(k) = 1 + \rho \int_{\mathbb{R}^d} \mathcal{d}r g(r) e^{-ik \cdot r},
\]

which can be rewritten as:

\[
S_\infty(k) = 1 + (2\pi)^d \rho \delta(k) + \rho \int_{\mathbb{R}^d} \mathcal{d}r [g(r) - 1] e^{-ik \cdot r}.
\]

The quantity in the integral is quickly vanishing as \( r = |r| \) becomes large, a property that stems from the usually fast approach to unity of \( g(r) \). Invoking (1), and taking the limit \( k \to 0^+ \) which discards the value \( k = 0 \) to avoid the above diverging term in \( \delta(k) \) [3], we have

\[
\lim_{k \to 0^+} S_\infty(k) = \frac{k_\infty}{\chi_\infty},
\]

In practice, say in a simulation, what is accessible is the finite size \( S_L(k) \) and not \( S_\infty(k) \), which in turns allows for the estimation of the bulk compressibility through equation (42), up to finite size effects. Indeed, the periodic boundaries imply that the density of particles, for any microscopic configuration, is a periodic function. This imposes a severe restriction on the admissible values of \( k \), since they must be commensurate with the periodicity of the system:

\[
k = \frac{2\pi}{L} (n_x, n_y)
\]

in two dimensions where \( n_x \) and \( n_y \) are any two integers. Hence, \( k_{\text{min}} = 2\pi / L \) is the smallest modulus of the allowed non-vanishing vectors. As a precursor of the diverging \( \delta \) term in (41), we note that for the finite size structure factor, \( S_L(0) = N \), and that therefore, the thermodynamic limit of \( S_L(k) \) is singular at \( k = 0 \). In practice, \( k = 0 \) should be left aside, and an operational way to compute the compressibility is to consider the large \( L \) limit of \( S_L(2\pi / L) \). Our goal is not to discuss what finite size corrections ensue (see e.g. [14, 15]), but to investigate what happens when one mistakenly computes \( S_L(k) \) for \( k \) values that are not within the allowed discrete set (43). To this end, it is appropriate to revisit the ideal gas limit, where all quantities are easily derived. As happened for the density fluctuations in previous sections, several key features thereby obtained do apply to interacting systems as well, as we shall see below.

### 4.2. From the ideal gas...

For non-interacting systems, there is no length scale present in the model, which results in a constant pair correlation function and a thermodynamic limit structure factor \( S_\infty(k) \) that cannot depend on \( k \). In equation (39), one can set \( g(r) = 1 - 1/N \) as alluded to in section 2.2, to cast the structure factor as a sum of two contributions:

\[
S_L(k) = S_\infty(k) + \delta S_w(k, L)
\]

where \( S_\infty(k) \equiv 1 \) is the thermodynamic limit value of the structure factor—indeed structureless—and \( \delta S_w(k, L) \) is given by

\[
\delta S_w(k, L) = (N - 1) \left( \frac{4 \sin \left( \frac{k_x}{2} \right) \sin \left( \frac{k_y}{2} \right)}{k_x k_y L^2} \right)^2.
\]

For the sake of the discussion, we restrict to two dimensions, without loss of generality. The term \( \delta S_w \) bears a subscript \( w \) to remind us that it contributes only when ‘wrong’ values of \( k \) are considered: as it should, \( \delta S_w(k) = 0 \) when \( k \) fulfills (43), so that the correct result of a unit
structure factor is recovered. In figure 7, the behaviour encoded in equation (44) is shown for different values of $L$. At arbitrary $k$ fixed and different from zero

\[
\lim_{L \to \infty} \delta S_w(k, L) = 0, \tag{46}
\]

since such a correction must disappear in the thermodynamical limit, where all the values of $k$ are allowed. Let us also note that at fixed $L$:

\[
\lim_{(k_x, k_y) \to 0} \delta S_w(k, L) = \delta S_w(0, L) = N - 1. \tag{47}
\]

This shows that the divergence of $S_L(0) = N$ in the thermodynamic limit is in some sense due to the non physical contribution $\delta S_w$. Working on the discrete allowed set (43), and taking the limit $k \to 0^+$, this divergence disappears, and the meaningful compressibility is obtained.

4.3. ...back to interacting systems

An interesting feature of relation (45) is that it survives to the ideal gas limitation. It is generically valid for a system of interacting particles

\[
S_L(k) \simeq S_\infty(k) + \delta S_w(k, L) \tag{48}
\]

up to terms $O(1/L)$, where $\delta S_w(k, L)$ is the same as in (45). The sub-leading terms—discarded here—have been already calculated in other studies [14]. We focus here on the presence of $\delta S_w$, stemming from the improper account of periodic boundaries, the consequences of which seem to have been overlooked in some previous studies. The derivation of (48) makes use of similar arguments as those invoked in section 2.2, and is reported in appendix E. Equation (48) is well obeyed in molecular dynamics simulations, as shown in figure 8.
The oscillations generated by $\delta S_{\text{w}}(k, L)$ when $S_{\text{w}}(k)$ is evaluated for the wrong $k$ values are unphysical. Such a mistake is frequently made by newcomers to the field, but can also be found in the literature, in different settings. An example is given by [16, 17], where two-dimensional harmonic crystals are studied. The authors work out analytically the structure factor for different sizes of a monolayer while working in a square finite box of length $L$. All phonons with a wavelength exceeding $L$ are excluded, so that the range $k < 2\pi/L$ is not accessible, but values larger than this lower cutoff are all considered as acceptable. This does not comply with the discrete rule (43). Once corrected for that problem, the computed finite $L$ structure factors (shown, e.g., in figures 2 and 3 of [16, 17]), no longer exhibit the spurious oscillations that are the exact counterpart of those illustrated in figures 7 or 8, and are in much better agreement with the large $L$ analytical predictions than reported.

5. Summary

We have presented a study of fluctuations and correlations in a finite size interacting fluid, where several relevant statistical physics results can be obtained. Our treatment implicitly addresses systems with short-range interactions, and excludes, for instance, Coulombic problems where specific sum rules do apply. Particular emphasis was put on a geometry where the confining volume is cubic, and replicated through periodic boundary conditions [3]. This is a common scheme to minimize surface effects in a numerical simulation and thereby emulate bulk phases. We have shown here how the periodicity of the system interferes with the fluctuations of the number of particles in a control volume that exceeds that of the confining box, through the
correlations that are induced between a given particle in the central box and its replicated images in neighbouring cells [3, 8]. In addition, several known results in the simpler case where the control volume is smaller than the simulation box have been rederived in section 2, but from an original perspective. In a second step, we addressed the dual problem of computing the static structure factor of the fluid, but for Fourier modes that do not comply with periodicity. Such a procedure, that is met at times, yields unphysical results, which have been examined. In the course of the argumentation, it appeared that the limiting case of non-interacting systems provided the germane effects under scrutiny and could be singled out (factorized) from those stemming from interactions.

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Appendix A. Definition of correlation functions

From the microscopic density, one defines the single-particle density field:

\[ \rho_N^{(1)}(r) = \left\langle \sum_{i=1}^{N} \delta(r - r_i) \right\rangle \]  

(A.1)

where the brackets denote the equilibrium average. In the same vein, we introduce the two-particle correlation function

\[ \rho_N^{(2)}(r, r') = \left\langle \sum_{i \neq i'}^{N} \delta(r - r_i)\delta(r' - r_{i'}) \right\rangle. \]

(A.2)

Interactions affect pair correlations, which are most conveniently encoded in the pair correlation function

\[ g_N(r, r') = \frac{\rho_N^{(2)}(r, r')}{\rho_N^{(1)}(r)\rho_N^{(1)}(r')} \].

(A.3)

This quantity, measurable from scattering experiments, plays a pivotal role in the study of simple liquids. In a homogeneous system like those considered in the present study, \( \rho_N^{(1)}(r) \) is independent of \( r \) and takes the value \( \rho \), while \( \rho_N^{(2)}(r, r') \) and \( g_N(r, r') \) only depend on the relative position \( r - r' \) [2, 3]. It will therefore be denoted \( g_N(r) \). By definition, \( \rho g_N(r) \) is the conditional density of particles at position \( r \), given that a particle sits at the origin. \( g_N(r) \) is a function of density and system size through the number of particles \( N \). In the thermodynamic limit (\( N \rightarrow \infty \)), it is simply denoted \( g(r) \). This is the quantity shown in the inset of figure 3, which has a typical shape for systems interacting through a steeply repulsive potential at short distances: for \( l < \sigma \), \( g(\sigma) \approx 0 \), since particles cannot overlap, while \( g \rightarrow 1 \) for large \( l \), since having a particle at a given point becomes immaterial for particles at distance \( l \) away.

Appendix B. Ideal gas and binomial distribution

Let us consider an ensemble of \( N \) non-interacting particles in a \( d \)-dimensional box of length \( L \). where, by virtue of spatial homogeneity, the probability for finding a particle in a sub-region \( D \) is proportional to its volume \( A(D) \), namely:

\[ p_D = \frac{A(D)}{L^d}. \]

(B.1)
Moreover, the probability for having $N_D$ particles in $D$ is given by the binomial distribution (see e.g. [6]):

$$P_D(N_D) \equiv \binom{N}{N_D} p_D^{N_D} (1 - p_D)^{N-N_D},$$

(B.2)

with mean $E(N_D) = N p_D$ and variance $V(N_D) = N p_D (1 - p_D)$. It follows from the definition (2) that

$$\frac{\chi^g_{\infty}(D)}{\chi^g_{\infty}} = \frac{\langle N_D^2 \rangle - \langle N_D \rangle^2}{\langle N_D \rangle} = 1 - p_D = 1 - \frac{A(D)}{L^d}.$$  

(B.3)

This is the result quoted in the main text. In the limit where $A(D)/L^d \to 0$, which we can dub the grand canonical condition, the right-hand side of (B.3) goes to 1. A reformulation of that result is that for $p_D \to 0$, that is in the grand canonical ensemble, the binomial law goes to a Poisson distribution [18]

$$P_D(n) = \frac{\lambda^n e^{-\lambda}}{n!}$$  

(B.4)

where $\lambda = N p_D$ is the mean value. It is a property of Poissonian variables that the mean value and the variance are equal.

**Appendix C. Compressibility and finite size effects**

The quantities appearing in equation (1) can be used to define two different objects $\chi_L(D)$ and $\tilde{\chi}_g(D)$, according to:

$$\frac{\chi_L(D)}{\chi^g_{\infty}} = \frac{\langle N_D^2 \rangle - \langle N_D \rangle^2}{\langle N_D \rangle},$$

(C.1)

and

$$\frac{\tilde{\chi}_g(D)}{\chi^g_{\infty}} = 1 + \rho \int_D dr \left[ g(r) - 1 \right].$$

(C.2)

When $D$ is large in an even much larger (say infinite) system, $\tilde{\chi}_g(D)$ and $\chi_L(D)$ coincide with the bulk compressibility $\chi_{\infty}$. In general, however, these two quantities differ as we now illustrate.

In order to see the connection between equations (C.1) and (C.2), it is necessary to start from the definition of particle fluctuations via the density field (A.1), namely:

$$\langle (N_D - \langle N_D \rangle)^2 \rangle = \int_{D_1} dr_1 \int_{D_2} dr_2 \left[ \rho_N^{(1)}(r_1) - \rho \right] \left[ \rho_N^{(1)}(r_2) - \rho \right].$$

(C.3)

By using the definitions in equations (A.1–A.3), this expression can be rewritten in terms of the radial distribution function:

$$\langle N_D^2 \rangle - \langle N_D \rangle^2 = \rho^2 \int_{D^2} dr_1 dr_2 \left[ g_N(r_1 - r_2) - 1 \right] + \rho A(D).$$

(C.4)

To take advantage of the fact that $g_N$ only depends on its relative position in a homogeneous system, one usually changes variables from $\{r_1, r_2\}$ to $\{r = r_1 - r_2, r_2\}$, but attention should be paid to the domain of integration, which becomes distorted. An expedient way of proceeding is to consider the new domain $\tilde{D} \equiv \{r = r_1 - r_2 | r_1 \in D, r_2 \in D\}$, and insert the identity

$$1 = \int_{\tilde{D}} dr \delta(r - r_1 + r_2),$$

(C.5)
into equation (C.4). We stress that equation (C.5) is valid only if $r_1$ and $r_2$ belong to the set $\mathcal{D}$, which is our case; otherwise the left-hand term must be substituted with a Heaviside step function. We thus get

$$\frac{\langle N_D^2 \rangle - \langle N_D \rangle^2}{\langle N_D \rangle} = 1 + \rho \int_{\mathcal{D}} dr \ w_D(r) \ [g_N(r) - 1],$$

(C.6)

where

$$w_D(r) = \frac{\int_{\mathcal{D}} dr_1 dr_2 \delta(r - |r_1 - r_2|)}{\mathcal{A}(\mathcal{D})}$$

(C.7)

is a dimensionless weight function. This is exactly the expression we were looking for, connecting fluctuations to a proper integral of the radial distribution function for arbitrary domain $\mathcal{D}$, no matter how small. Remarkably, equation (C.6) yields the right-hand side of the ordinary formula (1) in two limiting cases only:

- when $\mathcal{A}(\mathcal{D})$ is small with particles having an hard-core like repulsion, since $g(r) \simeq 0$ and $\int_{\mathcal{D}} dr \ w_D(r) = \int_{\mathcal{D}} dr = \mathcal{A}(\mathcal{D})$.

- when $\mathcal{A}(\mathcal{D})$ is large, since $w_D(r) \to 1$ when $\mathcal{D} \to \mathbb{R}^d$, and the integral over $\mathcal{D}$ coincides with that one over the whole space, and with that over $\mathcal{D}$.

From the limits above, it appears that the maximum deviation between $\chi_L(\mathcal{D})$ and $\tilde{\chi}_g(\mathcal{D})$ appears in some intermediate regime, as confirmed in figure C1. For instance, in the case of the squared shape region described in the main article (length $l$ and dimension $d$), a straightforward calculation from (C.7) gives

$$w_I(r) = \prod_{i=1}^{d} \left(1 - \frac{|x_i|}{l}\right), \quad \text{where} \ r \equiv \{x_1, x_2, \ldots, x_d\}.$$  

(C.8)

In the inset of figure C1, one can observe that equation (C.6) is well obeyed.
Appendix D. A result on the fluctuations of correlated variables

Let us consider a box which contains exactly $N$ homogeneously distributed particles. We define two non-overlapping regions, $D_1$ and $D_2$, and we are interested in the statistics of the following quantity:

$$N_i = \alpha N_1 + \beta N_2,$$  

(D.1)

where $N_i$ is the number of particles contained in the region $D_i$. Equation (D.1) is the linear combination of two correlated random variables (for instance, when $N_1 = N$, $N_2$ necessarily vanishes). The calculation of the mean values, denoted again with the symbol $E$, simply follows from the homogeneity assumption

$$E(N_i) = \alpha E(N_1) + \beta E(N_2) = \alpha N p_1 + \beta N p_2$$

(D.2)

with $p_i \propto A(D_i)$, the volume of region $D_i$. When it comes to computing the variance $V(N_i)$, a result known as the law of total variance [19] becomes useful. It reads:

$$V(N_i) = V(E(N_i|N_3)) + E(V(N_i|N_3)),$$  

(D.3)

where $N_3$ is any arbitrary variable, used for conditioning. Loosely speaking, equation (D.3) states that the total variance is the mean of the conditioned variance plus the variance of the conditioned mean. More precisely, $E(N_i|N_3)$ (resp $V(N_i|N_3)$) signifies that, $N_3$ being fixed, one computes the corresponding mean value (respectively variance) of $N_i$. In the present situation, it is convenient to choose $N_3 = N_1 + N_2$, the number of particles in $D_3 = D_1 \cup D_2$. Then,

$$E(N_i|N_3) = \alpha E(N_1|N_3) + \beta E(N_2|N_3) = \alpha N_3 \frac{p_1}{p_1 + p_2} \beta N_3 \frac{p_2}{p_1 + p_2},$$

(D.4)

as follows from the homogeneity assumption. Indeed, when $N_3$ particles exactly lie in $D_3$, a fraction $\frac{A(D_3)}{A(D_1) + A(D_2)}$ of them lies in $D_i$ on average. For the (unconditioned) variance, we have

$$V(E(N_i|N_3)) = \left( \frac{\alpha p_1 + \beta p_2}{p_1 + p_2} \right)^2 V(N_3).$$

(D.5)

We turn to the second contribution in equation (D.3)

$$V(N_i|N_3) = V(\alpha N_1 + \beta (N_3 - N_1)|N_3)$$

$$= V((\alpha - \beta)N_1 + \beta N_3|N_3)$$

$$= V((\alpha - \beta)N_1|N_3),$$

(D.6)

since the variance is not affected by a shift of the variable. Thus

$$V(N_i|N_3) = (\alpha - \beta)^2 V(N_i|N_3).$$

(D.7)

Gathering results, one gets:

$$V(N_i) = \left( \frac{\alpha p_1 + \beta p_2}{p_1 + p_2} \right)^2 V(N_3) + (\alpha - \beta)^2 E(V(N_i|N_3))$$

(D.8)

Note when $\alpha = \beta = 1$, $N_i = N_1 + N_2 = N_3$ and we recover the tautological expression $V(N_i) = V(N_3)$.

Appendix E. Structure factor and finite size effects

In this section, we derive equation (48) for the structure factor, as considered in section 4. In this case, there are two different sources of finite size effects. Indeed, apart from the finite number of particles considered, the finite length of the box imposes a strong constraint on the allowed set of wave vectors. In order to derive the final result, both restrictions must be
taken into account. For simplicity, we study the two-dimensional case, but what follows can be easily generalized to other dimensions.

We consider two different boxes of lengths \( R \) and \( L \) with \( L < R \) and their finite size structure factors \( S_R(k) \) and \( S_L(k) \). The allowed values of \( k \) with respect to the box \( R \) belong to the set \( U_R = \{ \frac{2\pi}{R} n \} \), where \( n \) is any vector with integer coordinates—see (43). In the thermodynamical limit, the structure factor sought is recovered:

\[
\lim_{R \to +\infty} S_R(k) = S_\infty(k) \tag{E.1}
\]

and in the same limit \( U_R \to \mathbb{R}^2 \) while all of the values of \( k \) are allowed. By definition, the structure factor is connected to the pair distribution function. From equation (39), we have that:

\[
S_R(k) = 1 + \frac{N}{R^2} \int_{-R}^{R} dr \, w_R(r) g_{N,R}(r) \exp[-i k \cdot r] \tag{E.2}
\]

\[
= 1 + \frac{N}{R^2} \int_{-R}^{R} dr \, g_{N,R}(r) \exp[-i k \cdot r] + \mathcal{O}(R^{-1}) \tag{E.3}
\]

where attention should be paid to the fact that \( r = r_2 - r_1 \) denotes the relative position of the particles, so that if the available volume for each position \( r_1 \) and \( r_2 \) is a square, then \( \tilde{B}_R \) is a parallelogram. For this reason, the same weight function \( w_R(r) \), considered in appendix C, appears. However, this point is not crucial for what follows.

Let us now consider the region \( B_L \), square-shaped, of length \( L \), with \( L < R \). If, for some integer \( n \), one has that

\[
R = nL, \tag{E.4}
\]

then clearly the values allowed for \( B_L \) are a subset of \( U_R \), but this is not true in general. We next evaluate the following difference

\[
S_L(k) - S_R(k) = I_1 + I_2 + \mathcal{O}(R^{-1}) + \mathcal{O}(L^{-1}) \tag{E.5}
\]

where

\[
I_1 = \rho \int_{B_L} dr \, e^{-ik \cdot r} \left[ g_{N,L}(r) - g_{N,R}(r) \right] \tag{E.6}
\]

\[
I_2 = -\rho \int_{\tilde{B}_L - \tilde{B}_R} dr \, e^{-ik \cdot r} g_{N,R}(r). \tag{E.7}
\]

We stress that equation (E.5) is considered only for the values of \( k \) that belong to \( U_R \). The two terms are now analysed separately. The first one gives a \( 1/N \) contribution. In order to show that, we recall the expansion used in equation (13):

\[
g_{N,R}(r) = g(r) + \delta g_R \tag{E.8}
\]

where \( \delta g_R \sim \mathcal{O}(1/N) = \mathcal{O}(1/R^2) \), together with the corresponding equation for \( g_{N,L}(r) \). One has that

\[
I_1 = \rho \int_{B_L} dr \, e^{-ik \cdot r} [\delta g_L - \delta g_R]. \tag{E.9}
\]

Then in the thermodynamical limit

\[
\lim_{R \to +\infty} I_1 = \int_{B_L} dr \, \delta g_L e^{-ik \cdot r} \sim \mathcal{O}(L^{-2}). \tag{E.10}
\]
Regarding the second contribution, under the condition $R \gg L \gg 1$ and since the integrand runs for distances larger than $L$, we can assume $g_{\nu,L}(r) \simeq 1$, apart from a term $O(L^{-2})$, and then

$$I_2 \simeq -\rho \int_{\hat{B}_R - \hat{B}_L} \mathrm{d}r \, e^{-i\mathbf{k} \cdot \mathbf{r}} = \rho \int_{B_R} \mathrm{d}r \, e^{-i\mathbf{k} \cdot \mathbf{r}} = \delta S_w (\mathbf{k}, L), \tag{E.11}$$

since for the set $U_R$, the integral over $\hat{B}_R$ vanishes. As already defined in section 4, the last integral in equation (E.11) leads to the ideal gas correction that we rewrite here for completeness:

$$\delta S_w (\mathbf{k}, L) = \frac{(N-1)}{L^2} \left| \frac{4 \sin \left( \frac{\ell}{2} k_1 \right) \sin \left( \frac{\ell}{2} k_2 \right)}{k_1 k_2} \right|^2. \tag{E.12}$$

As appears from equation (E.12), $I_2$ contains the contribution of the wrong $k$: it vanishes as soon as $B_L$ is commensurate with $B_R$, since $U_L$ is contained in $U_R$. Inserting equations (E.10) and (E.11) into equation (E.5), in the thermodynamical limit where $R \to \infty$, one obtains the final result

$$S_L (k) = S_\infty (k) + \delta S_w (\mathbf{k}, L) + O \left( L^{-1} \right). \tag{E.13}$$

This is the expression, valid for all $k$, that is considered in section 4.3.

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