NUMERICAL RESEARCH OF THE BARENBLATT – ZHELTOV – KOCHINA STOCHASTIC MODEL

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At present, investigations of Sobolev-type models are actively developing. In the solution of applied problems the results allowing to get their numerical solutions are very significant. In the article the algorithm for numerical solving of the initial boundary value problem is developed. The problem describes the pressure distribution of the homogeneous fluid in the horizontal layer in the circle. The layer is opened by a vertical well of a small radius. In our research we suppose that random disturbing loads have an influence on the fluid. The problem was solved under two assumptions. Firstly, we suppose that an unstable fluid flow is axially symmetric, and secondly, that in initial moment the pressure in the layer is constant. After the process of the discretization we modify the original model to the Cauchy problem for the system of ordinary differential equations. For the numerical solution we use algorithms based on explicit one-step formulas of the Runge – Kutta type with the seventh-order accuracy and with the selection of the integration step. We also use the scheme of the eighth-order accuracy to evaluate the calculation accuracy on each steps of time. According to the results of this control, we choose the time-step. A lot of numerical experiments have shown high numerical efficiency of the algorithm that we use to solve the investigated initial-boundary problem.

Keywords: stochastic Sobolev type equation; numerical solution; Barenblatt – Zheltov – Kochina model; Cauchy problem.

Introduction. Let $G \subset \mathbb{R}^d$ be a bounded domain with a boundary $\partial G$ of class $C^\infty$. Consider in the cylinder $G \times \mathbb{R}_+$ the Barenblatt – Zheltov – Kochina equation \[ (\lambda - \Delta)u_t = \alpha \Delta u + f, \]
with the Dirichlet condition
\[ u(x, t) = 0, \ (x, t) \in \partial G \times \mathbb{R}_+. \]

Model (1), (2) simulates the pressure dynamics of the fluid filtered in fractured porous medium with random external influences $f$ [2], processes of moisture transfer in a ground [3] and processes of the solid-to-fluid thermal conductivity in the environment with two temperatures [4]. In equation (1) $\alpha$ and $\lambda$ are real parameters, that characterize the environment; the parameter $\alpha \in \mathbb{R}_+$, and the parameter $\lambda$ can also take the negative values [5]; the additive component $f$ presents the random external load [2]. Our goal is to find the random process $u = u(x, t)$ that satisfies (1), (2) with initial Cauchy condition
\[ u(x, 0) = u_0(x). \]
It must be noted that the problem (1), (2) in corresponding Hilbert spaces can be reduced to the linear stochastic Sobolev type equation

\[ Ldu = Muddt + NdW. \]

You can find more historical aspects of the stochastic equations theory (including the stochastic Sobolev type equations research), for example, in [6].

1. **Homogeneous Fluid Filtration.** Consider the algorithm of construction of numerical solution to (1), (2). As an example we consider unstable filtration of the homogeneous fluid in the horizontal layer. The layer is opened by a vertical well of a small radius. At the initial moment pressure of fluid in the layer is constant and is equal to \( p_0 \). Assume that a random load begins to influence the fluid. Let the domain \( G \subset \mathbb{R}^2 \) be presented by disk with the radius \( r_0 \) and center on the axis of the well. Introduce a polar system of coordinates and assume that the fluid flow is axially symmetric. In this case we can find the fluid pressure in a fissure if we solve the initial-boundary value problem [1]

\[
(\lambda - \Delta_r)p_t = \alpha \Delta_r p + A \sin(\omega t),
\]

\[
|p(0, t)| < +\infty, \quad p(r_0, t) = 0, \quad p(r, 0) = p_0,
\]

where \( \Delta_r = \frac{\partial^2}{\partial r^2} + \frac{1}{r} \frac{\partial}{\partial r}, \ A \in \mathbb{R}, \ \lambda = 1/\eta, \ \eta \) is a specific characteristics of the fractured ground, \( \alpha = \chi/\eta, \ \chi \) is the piezoconductivity coefficient of the fractured ground.

Then we need to modify (4) to the system of ordinary differential equations. So we make a discretization of the domain \( G \). We work on a segment \([0, r_0]\) with the equally spaced grid \( r_j = (j - 1)h_r, \ j = 1, J, \ h_r = r_0/(J - 1), \ J \) is the number of discretization points. It is known that the construction of difference approximation for the \( p \)-th order derivatives in the \( j \)-th discretization point is based on the formula

\[
\left( \frac{\partial^p u}{\partial r^p} \right)_j = \frac{1}{h_r^p} \sum_{i=j-j_h}^{j+j_h} a_{pji} u_i + O\left(h_r^{n_u-p}\right),
\]

where \( j_i(j_p) \) is the amount of points to the left (right) from the \( j \)-th point in which the derivative is calculated, \( i \) is numbers of points that we use in the approximation of the derivative \( n_u = j_i + j_p + 1 \) is the amount of points that we use in the derivative approximation, \( n_u \leq J \). After we use the expansion of a function \( p(r, t) \) in a Taylor series in the point \( r_j \), we can simply receive a system of linear equations to find coefficients \( a_{pji} \). We have already made a special program in Maple Math Software to calculate \( a_{pji} \) for \( p \in \mathbb{N} \)-order derivative and for \( j, i = 1, J \). This program gives an opportunity to use (5) with difference approximation errors \( O\left(h_r^{n_u-p}\right) \) during the process of numerical simulations.

After we have done the discretization of initial-boundary conditions (4) we obtain a Cauchy problem for the system of ordinary differential equations for the function \( u_j(t) \). The system we will write in the matrix form

\[
M \frac{dU(t)}{dt} = PU(t) + W,
\]

\[
U(0) = U_0.
\]
Where \( M = \begin{pmatrix}
    1 & 0 & 0 & \ldots & 0 \\
    b_{2,1} & \lambda - b_{2,2} & b_{2,3} & \ldots & b_{2,j} \\
    \ldots & \ldots & \ldots & \ldots & \ldots \\
    b_{j-1,1} & b_{j-1,2} & b_{j-1,3} & \ldots & \lambda - b_{j-1,j} \\
    0 & 0 & 0 & \ldots & 1
\end{pmatrix} \), \( U(t) = \begin{pmatrix}
    u_1(t) \\
    u_2(t) \\
    \vdots \\
    u_{J-1}(t) \\
    u_J(t)
\end{pmatrix} \),

\[
U_0 = \begin{pmatrix}
    u_{0,1} \\
    u_{0,2} \\
    \vdots \\
    u_{0,J-1} \\
    u_{0,J}
\end{pmatrix}, \quad P = \begin{pmatrix}
    1 & 0 & 0 & \ldots & 0 \\
    b_{2,1} & b_{2,2} & b_{2,3} & \ldots & b_{2,j} \\
    \ldots & \ldots & \ldots & \ldots & \ldots \\
    b_{j-1,1} & b_{j-1,2} & b_{j-1,3} & \ldots & b_{j-1,j} \\
    0 & 0 & 0 & \ldots & 1
\end{pmatrix}, \quad W = \begin{pmatrix}
    0 \\
    A \sin(\omega t) \\
    \vdots \\
    A \sin(\omega t) \\
    0
\end{pmatrix},
\]

\( u_j \) is values of pressure in the \( j \)-th point of digitalization. If we don’t use the point in derivative approximation, then \( b_{ji} = 0 \), otherwise \( b_{ji} = \frac{a_{2ji}}{h_r^2} + \frac{a_{1ji}}{r_j} \), where the first index \( j \) indicates the number of the point in which we make the derivative approximation and the second index \( i \) indicates the number of point, that takes part in the derivative approximation.

It’s easy to show that the determinant of the matrix \( P \) is not equal to 0. In rare cases when we set \( \lambda \) it may be that the determinant of the matrix \( M \) equals to 0. In this case we need to change the amount of points that take part in derivatives approximation. It will change the value of the determinant of the matrix \( P \) and consequently change the value of the determinant of matrix \( M \). Therefore, we assume that \( \det(M) \neq 0 \).

After the inversion of the matrix \( M \) from equation (6), we obtain a Cauchy problem for the first-order differential equations in the matrix form

\[
\frac{dU(t)}{dt} = F(t, U(t)), \quad 0 < t \leq t_0,
\]

\[
U(0) = U_0,
\]

where \( F(t, U(t)) = M^{-1}(PU(t) + W) \).

For the numerical solution of (7) we use algorithms that are based on explicit one-step formulas of the Runge – Kutta type with the seventh order accuracy [7]:

\[
U_{n+1} = U_n + \sum_{i=1}^{13} p_{n,i} k_i,
\]

\[
k_i = hF\left(t_n + \alpha_i h_t, \psi_n + \sum_{j=1}^{13} \beta_{i,j} k_j, A_n + \sum_{j=1}^{13} \beta_{i,j} k_j\right),
\]

Where \( h_t \) is a integration step in Runge – Kutta method,

\[
\alpha_1 = 0, \quad \alpha_2 = \frac{2}{27}, \quad \alpha_3 = \frac{1}{9}, \quad \alpha_4 = \frac{1}{6}, \quad \alpha_5 = \frac{5}{12}, \quad \alpha_6 = \frac{1}{2}, \quad \alpha_7 = \frac{5}{6},
\]

\[
\alpha_8 = \frac{1}{6}, \quad \alpha_9 = \frac{2}{3}, \quad \alpha_{10} = \frac{1}{3}, \quad \alpha_{11} = 1, \quad \alpha_{12} = 0, \quad \alpha_{13} = 1,
\]

\[
\beta_{2,1} = \frac{2}{27}, \quad \beta_{3,1} = \frac{1}{36}, \quad \beta_{3,2} = \frac{1}{12}, \quad \beta_{4,1} = \frac{1}{24}, \quad \beta_{4,2} = 0, \quad \beta_{4,3} = \frac{1}{8},
\]

\[
\beta_{5,1} = \frac{5}{12}, \quad \beta_{5,2} = 0, \quad \beta_{5,3} = -\frac{25}{16}, \quad \beta_{5,4} = \frac{25}{16}, \quad \beta_{6,1} = \frac{1}{20}, \quad \beta_{6,2} = \beta_{6,3} = 0,
\]
\[
\begin{align*}
\beta_{6,4} &= \frac{1}{4}, \quad \beta_{6,5} = \frac{1}{5}, \quad \beta_{7,1} = \frac{-25}{108}, \quad \beta_{7,2} = \beta_{7,3} = 0, \quad \beta_{7,4} = \frac{125}{108}, \quad \beta_{7,5} = \frac{-65}{27}, \\
\beta_{7,6} &= \frac{125}{54}, \quad \beta_{8,1} = \frac{31}{300}, \quad \beta_{8,2} = \beta_{8,3} = \beta_{8,4} = 0, \quad \beta_{8,5} = \frac{61}{225}, \quad \beta_{8,6} = \frac{-2}{9}, \\
\beta_{8,7} &= \frac{13}{900}, \quad \beta_{9,1} = 2, \quad \beta_{9,2} = \beta_{9,3} = 0, \quad \beta_{9,4} = \frac{23}{108}, \quad \beta_{9,5} = \frac{704}{45}, \quad \beta_{9,6} = \frac{-107}{9}, \\
\beta_{9,7} &= \frac{67}{90}, \quad \beta_{9,8} = 3, \quad \beta_{10,1} = \frac{-91}{108}, \quad \beta_{10,2} = \beta_{10,3} = 0, \quad \beta_{10,4} = \frac{23}{108}, \\
\beta_{10,5} &= \frac{-976}{135}, \quad \beta_{10,6} = \frac{311}{54}, \quad \beta_{10,7} = \frac{-19}{60}, \quad \beta_{10,8} = \frac{17}{6}, \quad \beta_{10,9} = \frac{-1}{12}, \\
\beta_{11,1} &= \frac{2383}{4100}, \quad \beta_{11,2} = \beta_{11,3} = 0, \quad \beta_{11,4} = \frac{-341}{164}, \quad \beta_{11,5} = \frac{4496}{1025}, \quad \beta_{11,6} = \frac{-301}{82}, \\
\beta_{11,7} &= \frac{2133}{4100}, \quad \beta_{11,8} = \frac{45}{82}, \quad \beta_{11,9} = \frac{45}{164}, \quad \beta_{11,10} = \frac{-18}{41}, \\
\beta_{12,1} &= \frac{3}{205}, \quad \beta_{12,2} = \beta_{12,3} = \beta_{12,4} = \beta_{11,5} = 0, \quad \beta_{12,6} = \frac{-6}{41}, \quad \beta_{12,7} = \frac{-3}{205}, \\
\beta_{12,8} &= \frac{-3}{41}, \quad \beta_{12,9} = \frac{3}{41}, \quad \beta_{12,10} = \frac{6}{41}, \quad \beta_{12,11} = 0, \quad \beta_{13,1} = \frac{-1777}{4100}, \\
\beta_{13,2} &= \beta_{13,3} = 0, \quad \beta_{13,4} = \frac{-341}{164}, \quad \beta_{13,5} = \frac{4496}{1025}, \quad \beta_{13,6} = \frac{-289}{82}, \\
\beta_{13,7} &= \frac{-2193}{4100}, \quad \beta_{13,8} = \frac{51}{82}, \quad \beta_{13,9} = \frac{33}{164}, \quad \beta_{13,10} = \frac{12}{41}, \quad \beta_{13,11} = 0, \quad \beta_{13,12} = 1, \\
p_{7,1} &= \frac{41}{840}, \quad p_{7,2} = p_{7,3} = p_{7,4} = p_{7,5} = 0, \quad p_{7,6} = \frac{34}{105}, \quad p_{7,7} = p_{7,8} = \frac{9}{35}, \\
p_{7,9} = p_{7,10} = \frac{9}{280}, \quad p_{7,11} = \frac{41}{840}, \quad p_{7,12} = p_{7,13} = 0.
\end{align*}
\]

When we use explicit methods to solve the stiff problem we would like to note that the integration step is limited not only by calculation accuracy but also by the stability of the numerical method [8]. We can find the local error \( \delta_n \) of the method with the seventh order accuracy by using the next formula [7]

\[
\delta_n = \sum_{i=1}^{13} (p_{8,i} - p_{7,i})k_i,
\]

where coefficients \( p_{8,i} \) are equals

\[
p_{8,1} = p_{8,2} = p_{7,3} = p_{7,4} = p_{7,5} = 0, \quad p_{7,6} = \frac{34}{105}, \quad p_{7,7} = p_{8,8} = \frac{9}{35}, \quad p_{8,9} = p_{8,10} = \frac{9}{280}, \quad p_{8,11} = p_{8,12} = 0, \quad p_{8,13} = \frac{41}{840}.
\]

If you would like to evaluate the control of the calculation accuracy you can use the next inequality

\[
||\delta_n|| \leq \varepsilon.
\]
Here \( || \cdot || \) is a norm in \( R^J \), \( J \) is the dimension of the matrix column \( F(t,U(t)) \), \( \varepsilon \) is the necessary calculation accuracy. In our case \( \delta_n = O\left(h_t^s\right) \). Therefore integration step \( h^{ac} \) according to accuracy is calculated with the formula [8]

\[
h^{ac} = q h_t, \quad q = \sqrt{\frac{\varepsilon}{||\delta_n||}}.
\]

In the case \( q < 1 \) we need to repeat the calculation that we received at the step \( h_t \) and use the other step \( h^{ac} \). Otherwise we must repeat our calculations on the next interval of time.

2. Results of the Calculation Experiment. The algorithm for solving of problem (4) that was described in previous paragraph, was implemented in a special program in Maple Math Software. This program gives us an opportunity to conduct numerical experiments that find the values of the pressure in breaches under a specific condition. This condition describes random loads, that have difference influence on the seam consumption. We use the random number generator to choose the constant \( A \in R \) for function that determines random loads for the seam consumption. Estimates of experiments show that in equation (4) the parameter \( \eta \) for different earth materials take the value between very wide limits \( \eta = 10^{-4} \text{ m}^2 \div 10^8 \text{ m}^2 \), and the coefficient \( \chi = 0, 1 \text{ m}^2/\text{s} \div 1 \text{ m}^2/\text{s} \).

Fig 1. Dependence of pressure \( p = p(t_s,r) \) in a fissure at moments of time \( t_s = 1, 27s \), \( t_s = 2, 61s \), \( t_s = 4s \)

Fig 2. Dependence of pressure \( p = p(t,r) \) in fissure on \( t \) and \( r \)

Numerous calculations have shown that the developed algorithm of the solution allows to find the numerical solution of the problem with high computational efficiency.

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В настоящее время активно развиваются исследования математических моделей соболевского типа. В решении прикладных задач значимыми являются результаты, позволяющие получать их численное решение. В работе разработан алгоритм численного решения начально-краевой задачи описывающей распространение динамики однослойной жидкости в горизонтальном пласте, который всегда вертикальной скважиной малого размера. Предполагается, что на жидкость действуют возмущающие случайные нагрузки, а область исследования представляет собой круг с центром на оси скважин. Задача решалась в предположении, что неустойчивое течение жидкости осесимметричное, а в начальный момент времени конец в пласте постоянное. Продолжение дискретизации, исходная задача для дифференциального уравнения в частных производных, преобразована к задаче Коши для системы обыкновенных дифференциальных уравнений. Для численного решения задачи Коши использовались алгоритмы, основанные на языке обыкновенных формул типа Рунге — Куттс седьмого порядка точности с выбором шага интегрирования. Для оценки контроля точности вычислений на каждом временном шаге использовалась схема восьмого порядка точности. Исходя из результатов этого контура, выбирался временной шаг. Многочисленные вычислительные эксперименты показали высокую вычислительную эффективность алгоритма решения исследуемой начально-краевой задачи.

Ключевые слова: стохастическое уравнение соболевского типа; численное решение; модель Баренблатта — Желтов — Кочина; задача Коши.
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