DEFORMATIONS OF POLYNOMIALS, BOUNDARY SINGULARITIES AND MONODROMY

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Dedicated to Vladimir Igorevich Arnol’d on the occasion of his 65th anniversary

Abstract. We study the topology of polynomial functions by deforming them generically. We explain how the non-conservation of the total “quantity” of singularity in the neighbourhood of infinity is related to the variation of topology in certain families of boundary singularities along the hyperplane at infinity.

1. Introduction

One of the fundamental tools for studying singularities is deformation. In case of function germs with isolated singularity, classification and deformation results have been found through the pioneering work of V.I. Arnol’d in the early 1970s, one of the most spectacular being the list of simple singularities, their possible deformations and their amazing connections to other branches of mathematics [Ar1]. More recently, in the 1990s, the study of the behaviour of polynomial functions at infinity lead to a new branch: singularities at infinity of polynomials. In his 1998 paper [Ar2], Arnol’d gave a list of simple germs of fractions and polynomials at infinity, together with their specializations diagrams. One of the questions which may arise, placed in the global setting of polynomial functions, is the following: how does the topology of the polynomial change when deforming it?

Since Broughton’s fundamental paper [Bro] there has been an enormous interest in studying the variation of topology of the fibers of a given polynomial, partly due to the relation to the Jacobian Conjecture. In our paper, we study a polynomial by embedding it into a family. This gives a new viewpoint and non-trivial results occur even in cases where the topology at infinity of the original polynomial is constant (see §9).

It is well-known that an isolated singular point of a holomorphic function can be deformed into finitely many singularities and that the sum of their Milnor numbers equals the original one. A generic deformation is a Morsification and it can be used to define vanishing cycles, see e.g. the Appendix of Brieskorn’s paper [Bri].

Unlike the case of germs, deformations of polynomials do not conserve neither the total Milnor number, nor the number of vanishing cycles. While focusing on the behaviour at infinity, there is a way to define generic deformations of \( f_0 \), within the class of degree \( d \)

2000 Mathematics Subject Classification. 32S30, 14D05, 32S40, 58K60, 14B07, 58K10, 55R55.

Key words and phrases. deformations of polynomials, singularities at infinity, monodromy, boundary singularities.
polynomials, by asking that, for all \( s \neq 0 \), the total Milnor number \( \mu(s) \) of \( f_s \) is exactly equal to \( (d - 1)^n \). Such polynomials \( f_s \), which we call \textit{general-at-infinity}, have also the maximum number of vanishing cycles (Proposition 3.7, Corollary 3.8).

Our study is placed in the framework of polynomials with isolated singularities, including singularities at infinity, in some appropriate sense. We show that in this class, the number of vanishing cycles is upper semi-continuous (Proposition 5.1), which is just opposite as in the case of germs.

The loss of vanishing cycles is actually due to the loss of some of the singular points of \( f_s \), as \( s \to 0 \). This can happen in two ways: the corresponding critical value in \( \mathbb{C} \) of such a singularity tends either to a finite limit or to infinity. This phenomenon produces singularities at infinity for \( f_0 \), which are quantified by the total Milnor-Lê number \( \lambda \). In other words, loss of \( \mu \) yields gain of \( \lambda \): Theorem 5.4 shows how the \( \mu \rightleftharpoons \lambda \) exchange takes place whenever singularities tend to some point at infinity of a compactified fiber. In this way one can detect jumps in the topology by studying the behaviour of the affine critical points in the deformation.

Our approach is based on the interplay between the affine singularities of the polynomial and the singularities of its compactified fibers on the hyperplane at infinity \( H^\infty \). Actually there are finitely many one-parameter families of \textit{boundary singularities} attached to the compactifies fibers of a polynomial function and their restrictions to the hyperplane at infinity. Arnol’d has already remarked in \cite{Ar2} that there is a close relation between the classification of meromorphic germs of type \( H/Z^d \) and the one of germs of boundary singularities \cite{Ar1}.

In a one-parameter deformation \( f_s \) of \( f_0 \) there is a well-defined monodromy of a general fiber of \( f_s \) (where \( s \) is close enough to 0) over a small circle \( \partial \bar{D} \times \{t\} \) centered at \( (0, t) \in \mathbb{C} \times \mathbb{C} \). We call it the \textit{s-monodromy}. Depending on the position of \( t \) with respect to the affine discriminant \( \Delta_P \) (Definition 4.1), there are 3 types of \( s \)-monodromy, which we call \textit{generic}, \textit{atypical}, respectively \textit{at infinity}. We compare these global monodromies to the monodromies of the germs of boundary singularities of \( f_0 \). On the other hand we decompose the generic \( s \)-monodromy according to the types of branches of \( \Delta_P \). We find in \S\S 7 several formulas for the zeta-function of the monodromy.

There is a whole section of examples on the \( \mu \rightleftharpoons \lambda \) exchange and the \( s \)-monodromy. Finally, we explain to what extent our study of a global situation (deformations of polynomials) relates to Arnol’d’s classification of simple germs of meromorphic functions of type \( H/Z^d \).

Acknowledgements. This research originated in a discussion with Vladimir Igorevich Arnol’d in 1999 in Lille, on how vanishing cycles may appear in the list of simple meromorphic germs (see \S\ 9). Part of it was done as a 2002 RiP program at Oberwolfach, with support from the Volkswagen-Stiftung. The authors benefited from the excellent working conditions offered by the Mathematisches Forschungsinstitut Oberwolfach.
2. Invariants associated to a polynomial functions

For any polynomial function \( f : \mathbb{C}^n \to \mathbb{C} \), there exists a minimal finite set \( B_f \subset \mathbb{C} \), called the set of atypical values, such that the restriction \( f : \mathbb{C}^n \setminus f^{-1}(B_f) \to \mathbb{C} \setminus B_f \) is a locally trivial fibration. If \( f \) has isolated singularities at infinity, in the sense of [ST1], then its general fiber \( G \) is homotopy equivalent to a bouquet of spheres \( \vee_{\gamma} S^{n-1} \), cf. loc. cit.

In this case, the vanishing cycles are quantified by two well-defined, non-negative integers [ST1]:

\[
\begin{align*}
\mu &= \text{the total Milnor number of the affine singularities,} \\
\lambda &= \text{the total Milnor-Lê number at infinity}
\end{align*}
\]

and one has:

\[
(2.1) \quad b_{n-1}(G) = \mu + \lambda.
\]

In this paper we consider deformations of polynomials within the following class:

**Definition 2.1.** We say that \( f \) has fiberwise isolated singularities at infinity (for short, \( f \) is a FISI polynomial) if the projective closure of any fiber of \( f \) and its slice by the hyperplane at infinity \( H^\infty \) have at most isolated singularities.

This class is large enough to include all reduced polynomial functions in 2 variables. It is a subclass of polynomials having isolated singularities at infinity, in the sense of [ST1]. So the numbers \( \mu \) and \( \lambda \) are well-defined. The singularities at infinity of a FISI polynomial are detected as follows.

Let \( \mathcal{X} = \{(x; x_0), t) \in \mathbb{P}^{n-1} \times \mathbb{C} \mid \tilde{f} - tx_0^d = 0\} \) and let \( \tau : \mathcal{X} \to \mathbb{C} \) be the projection to the \( t \)-coordinate, where \( d = \deg f \) and \( \tilde{f} \) is the degree \( d \) homogenisation of \( f \) with the variable \( x_0 \). Then the singular locus of \( \mathcal{X} \) consists of the lines \( \{p_i\} \times \mathbb{C} \), where \( p_i \) is a singular point of \( \mathcal{X}_t := \tau^{-1}(t) \), situated on the part at infinity \( \mathcal{X}_t^\infty := \tau^{-1}(t) \cap H^\infty \) (and not depending on \( t \)).

Let now \( (p_i, t) \in \mathbb{P}^{n-1} \times \mathbb{C} \) be a singular point of \( \mathcal{X}_t^\infty \). This may be a singular point of \( \mathcal{X}_t \), or a point where \( \mathcal{X}_t \) is non-singular but tangent to \( H^\infty \) at \( p_i \). Let then denote by:

\[
\begin{align*}
\mu_{p_i}(t) := \mu(\mathcal{X}_t, p_i), & \quad \mu_{p_i}^\infty(t) := \mu(\mathcal{X}_t^\infty, p_i),
\end{align*}
\]

the Milnor numbers of the respective hypersurface germs at \( p_i \). Note that \( \mu_{p_i}^\infty(t) \) is independent of \( t \), therefore we shall use the notation \( \mu_{p_i}^\infty \). In contrast, \( \mu_{p_i}(t) \) may jump at a finite number of values of \( t \). Let then denote by \( \mu_{p_i, \text{gen}} \) the value of \( \mu_{p_i}(t) \) for generic \( t \). The jump of \( \mu_{p_i} \) at \( t \) is measured by the local Milnor-Lê number, cf. [Pa], [ST1]:

\[
(2.2) \quad \lambda_{p_i, t} = \mu_{p_i}(t) - \mu_{p_i, \text{gen}}.
\]

We say that \( (p_i, t) \) is a singularity at infinity of \( f \) if and only if \( \lambda_{p_i, t} > 0 \). Then the set of atypical values \( B_f \) consists of the values \( t \in \mathbb{C} \) such that either \( t \) is a critical value of \( \tilde{f} \) or \( (p_i, t) \) is a singularity at infinity of \( f \) for some \( p_i \in H^\infty \). The total Milnor-Lê number of
\( f \) is the sum of the local ones:

\[
\lambda = \sum_{t \in \mathcal{B}} \sum_i \lambda_{p_i,t} = \sum_{t \in \mathcal{B}} \sum_i (\mu_{p_i}(t) - \mu_{p_i,\text{gen}}).
\] (2.3)

Let us compute the \((n-1)\)-th betti number of the fibers \( F_t = f^{-1}(t) \), using information on the singularities of their compactifications \( X_t \) and of their restrictions to the hyperplane at infinity \( X_t^\infty \). Recall that the Euler characteristic of the general fiber of a generic polynomial of degree \( d \) is \( \chi(n, d) = 1 + (-1)^{n-1}(d-1)^n \). Comparing it to the Euler characteristic of \( F_t \), one obtains the following formula, see e.g. [Di]:

\[
\chi(n, d) - \chi(F_t) = (-1)^{n-1} \sum_i (\mu_{p_i}(t) + \mu_{p_i}^\infty).
\]

This is valid for all \( t \), as long as \( F_t \) is non-singular. When \( F_t \) contains affine critical points, then the formula has to be corrected by adding to the right hand side the local Milnor numbers of these singularities. When \( F_t \) is the general fiber \( G \), we obtain:

\[
b_{n-1}(G) = (d-1)^n - \sum_i (\mu_{p_i,\text{gen}} + \mu_{p_i}^\infty).
\] (2.4)

We have now two different formulas, (2.1) and (2.4), both computing the number of vanishing cycles for a \( \mathcal{F} \) ISI polynomial.

3. DEFORMATIONS OF \( \mathcal{F} \) ISI POLYNOMIALS

In the following we consider a constant degree deformation of a polynomial \( f_0 \), i.e. a family \( P : \mathbb{C}^n \times \mathbb{C}^k \to \mathbb{C} \) of polynomial functions \( P(x, s) = f_s(x) \) such that \( \deg f_s = d \) for all values of the parameter \( s \) in a small neighbourhood of 0 \( \in \mathbb{C}^k \). We assume that \( P \) is holomorphic or polynomial in the parameters \( s \) and polynomial in the variables \( x \).

In this section we work with one-parameter deformations, i.e. \( k = 1 \). The following sets play an important role in our study:

\[
W_s := \{ [x] \in \mathbb{P}^{n-1} \mid \frac{\partial P_d}{\partial x}(x, s) = 0 \},
\] (3.1)

\[
\Sigma_s := \{ [x] \in \mathbb{P}^{n-1} \mid P_d-1(x, s) = 0 \} \cap W_s,
\]

where \( P_q \) stays for the degree \( q \) homogeneous part of \( P \) in variables \( x \in \mathbb{C}^n \).

That \( f_0 \) is a \( \mathcal{F} \) ISI polynomial is equivalent to: \( \dim W_0 \leq 0 \) and \( \dim \operatorname{Sing} f_0 \leq 0 \). Remark that the second condition is not a consequence of the first one (example: \( f_0 = x^2 \), as polynomial of 2 variables).

**Definition 3.1.** We say that \( P \) is a \( \mathcal{F} \) ISI deformation of \( f_0 \) if \( P \) has the property that \( \dim W_0 \leq 0 \) and that \( \dim \operatorname{Sing} f_s \leq 0 \) for all \( s \) in a small neighbourhood of 0.

Our definition of \( \mathcal{F} \) ISI deformation contains the condition that \( f_0 \) is \( \mathcal{F} \) ISI and it implies that \( f_s \) is \( \mathcal{F} \) ISI for any \( s \) in some small neighbourhood of 0.
Example 3.2. A constant degree deformation such that, for all $s$, $f_s$ is a polynomial in 2 variables with isolated singularities in the affine, is a $F\text{ISI}$ deformation.

We attach to the family $P$ the following hypersurface:

$$Y = \{([x : x_0], s, t) \in \mathbb{P}^n \times \mathbb{C} \times \mathbb{C} \mid \tilde{P}(x, x_0, s) - tx^d = 0\},$$

where $\tilde{P}$ denotes the homogenised of $P$ by the variable $x_0$, considering $s$ as parameter varying in a small neighbourhood of $0 \in \mathbb{C}$. Let $\tau : Y \to \mathbb{C}$ be the projection to the $t$-coordinate. This extends the map $P$ to a proper one in the sense that $\mathbb{C}^n \times \mathbb{C}$ is embedded into $Y$ and that $\tau_{\mid \mathbb{C}^n \times \mathbb{C}} = P$. Let $\sigma : Y \to \mathbb{C}$ denote the projection to the $s$-coordinates. We shall use the notations $Y_{s,\mathbb{C}} := Y \cap \sigma^{-1}(s)$, $Y_{\mathbb{C},t} := Y \cap \tau^{-1}(t)$ and $Y_{s,t} := Y_{s,\mathbb{C}} \cap \tau^{-1}(t) = Y_{\mathbb{C},t} \cap \sigma^{-1}(s)$. Note that $Y_{s,t}$ is the closure in $\mathbb{P}^n$ of the affine hypersurface $f_s^{-1}(t) \subset \mathbb{C}^n$. Let $Y^\infty := Y \cap \{x_0 = 0\} = \{P_d(x, s) = 0\} \times \mathbb{C}$ be the hyperplane at infinity of $Y$.

The singular locus of $Y$, namely:

$$\text{Sing } Y = \{x_0 = 0, \frac{\partial P_d}{\partial x}(x, s) = 0, P_{d-1}(x, s) = 0, \frac{\partial P_d}{\partial s}(x, s) = 0\} \times \mathbb{C}$$

is a subset of $Y^\infty$ and is a product-space by the $t$-coordinate. It depends only on the degrees $d$ and $d-1$ parts of $P$ with respect to the variables $x$.

For a fixed $s$ in a small neighbourhood of $0 \in \mathbb{C}$, the singular locus of $Y_{s,\mathbb{C}}$ is the analytic set:

$$\text{Sing } Y_{s,\mathbb{C}} = \Sigma_s \times \mathbb{C} \subset Y_{s,\mathbb{C}} \cap Y^\infty.$$ 

It is the union, over all $t \in \mathbb{C}$, of the singularities of the fibers $Y_{s,t}$ situated on the part at infinity $Y_{s,t}^\infty := Y_{s,t} \cap H^\infty$. Besides these singularities, there might be points $(p, s, t) \in Y^\infty$ where the fiber $Y_{s,t}$ is not singular but it is tangent to the hyperplane at infinity $H^\infty$. Those are exactly the points such that $p \in W_s \setminus \Sigma_s$. Notice that $W_s$ is the singular locus of $Y_{s,t}^\infty$ (and does not depend on $t$). Let us set the following notations, which we shall frequently use:

$$\phi(x) := \frac{\partial P}{\partial s}(x, 0), \quad \phi_d := \text{ degree } d \text{ part of } \phi.$$

Proposition 3.3. Let $P$ be any deformation of a $F\text{ISI}$ polynomial $f_0$. Then:

(a) $Y$ is non-singular if and only if $\Sigma_0 \cap \{\phi_d = 0\} = \emptyset$. In this case the critical set of the map $\sigma : Y \to \mathbb{C}$ is $\Sigma_0 \times \mathbb{C} \subset Y_{0,\mathbb{C}}$.

(b) $Y^\infty$ is non-singular if and only if $W_0 \cap \{\phi_d = 0\} = \emptyset$. In this case the critical set of the map $\sigma_1 : Y^\infty \to \mathbb{C}$ is $W_0 \times \mathbb{C} \subset Y_{0,\mathbb{C}}^\infty$.

Proof. (a) We have that $(\Sigma_0 \cap \{\phi_d = 0\}) \times \mathbb{C} = \text{Sing } Y \cap \{\sigma = 0\}$. Since Sing $Y$ is a germ of an analytic set at $Y_{0,\mathbb{C}}$, it follows that Sing $Y$ is empty if and only if $(\text{Sing } Y) \cap \{\sigma = 0\}$ is empty. The critical locus of $\sigma : Y \to \mathbb{C}$ is a germ at $Y_{0,\mathbb{C}}$ and therefore it is Sing $Y_{0,\mathbb{C}} = \Sigma_0 \times \mathbb{C}$. The proof of (b) is similar.
Corollary 3.4. Let $f_0$ be a $\mathcal{F}$ISI polynomial and let $P$ be a deformation such that $W_0 \cap \{\phi_d = 0\}$ is empty. Then $Y_{s,t}$ and $Y_{s,t}^\infty$ are non-singular, for all $t \in \mathbb{C}$ and all $s \neq 0$ close to $0$.

Proof. From Proposition 3.3, it follows that $W_s = \emptyset$, for $s \neq 0$. By (3.3), we get that $\text{Sing } Y_{s,C}$ is empty and so is $\text{Sing } Y_{s,t}^\infty$. Since both spaces are products by the $t$-coordinate, we get our claim.

Since we shall use this several times, we should emphasize that in case $W_0 \cap \{\phi_d = 0\}$ is empty, the spaces $Y$ and $Y^\infty$ are non-singular. This is in contrast to the compactifying spaces $Y_0, C$, resp. $Y_0^\infty, C$, of the original polynomial $f_0$, which spaces have non-isolated singularities as soon as $\Sigma_0 \neq \emptyset$, resp. $W_0 \neq \emptyset$. For instance, in $Y$ we have smoothings $Y_{s,t}$ of $Y_{0,t}$, for all $t$, for $s \neq 0$.

Example 3.5. Yomdin deformations of $f_0$ are of the form:

$$P = f_0 - sx_1^d,$$

where $x_1$ denotes a coordinate. Sufficiently general Yomdin deformations, i.e. such that $\Sigma_0 \cap \{x_1 = 0\} = \emptyset$, are $\mathcal{F}$ISI deformations. We can use the chart $x_1 = 1$ to obtain a description of $Y$ as graph of a function:

$$s = (f_0)_d(1, x_2, \ldots, x_n) + x_0(f_0)_d - tx_0^d,$$

where $(f_0)_d$ denotes $(f_0)_{d-1} + x_0(f_0)_{d-2} + \cdots$.

3.1. Generic deformations.

Definition 3.6. A polynomial $f : \mathbb{C}^n \to \mathbb{C}$ such that, for any $t \in \mathbb{C}$, the compactified fiber $f^{-1}(t) \subset \mathbb{P}^n$ is transversal to the hyperplane at infinity $H^\infty = \mathbb{P}^n \setminus \mathbb{C}^n$, will be called general-at-infinity (abbreviated GI). We say that a 1-parameter deformation $P : \mathbb{C}^n \times \mathbb{C} \to \mathbb{C}$ is GI if the polynomial $f_s$ is GI, for any $s \neq 0$ within a small neighbourhood of 0.

We have the following property.

Proposition 3.7. The general fiber $G$ of a general-at-infinity polynomial $f$ is homotopy equivalent to a bouquet of $(n - 1)$-spheres and the number of spheres is $\mu = b_{n-1}(G) = (d - 1)^n$.

Proof. Since $f$ is GI, all its fibers are transversal to the hyperplane at infinity. This implies that $f$ has only isolated singularities in the affine and that the Milnor numbers $\mu_{p_i}(t)$ and $\mu_{p_i}^\infty$ are all zero, for all $t$. Then formula (2.4) shows that $b_{n-1}(G) = (d - 1)^n$. Further, since our $f$ is a $\mathcal{F}$ISI polynomial, it is in particular a polynomial with at most isolated singularities at infinity, in the sense of [ST1], and therefore its general fiber is a bouquet of $(n - 1)$-spheres, by [ST1, Theorem 3.1].

Corollary 3.8. A $\mathcal{F}$ISI polynomial $f : \mathbb{C}^n \to \mathbb{C}$ is general-at-infinity if and only if $b_{n-1}(G) = (d - 1)^n$. 
Proof. In one direction, this follows from Proposition 3.7. The reciprocal is a direct
corollary of the formula (2.4) for $b_{n-1}(G)$ in terms of $\mu_{p_i}$ and $\mu_{p_i}^\infty$.

A GI polynomial may have different configurations of isolated singularities in the affine,
provided that their total Milnor number is precisely $(d-1)^n$. A large class of GI deforma-
tions is given by the following result.

Corollary 3.9. Let $P$ be a deformation of a FISI polynomial $f_0$ such that $W_0 \cap \{\phi_d = 0\} = \emptyset$. Then $P$ is general-at-infinity.

Proof. By definition, $P$ is GI if and only if $Y_{s,t}$ and $Y_{\infty,s,t}$ are non-singular, for all $t \in \mathbb{C}$ and all $s \neq 0$ close to 0. Then our claim follows from Corollary 3.4.

4. THE AFFINE CRITICAL LOCUS

In case of several parameters, we have of course more room for constructing generic
deformations. For instance, let $P : \mathbb{C}^n \times \mathbb{C}^n \to \mathbb{C}$ be a deformation of $f$ such that $P_d = f_d + s_1 x_1^d + \cdots + s_n x_n^d$. Then $Y$ is nonsingular and $Y_{C,t}$ is nonsingular too, for any $t$.

Let us now focus on the critical locus of the deformation.

Definition 4.1. Let $\Psi := (\sigma, \tau) : Y \setminus Y_\infty \to \mathbb{C}^k \times \mathbb{C}$ be the map induced by the couple
of projections. We define the affine critical locus $\Gamma_P$ to be the closure in $\mathbb{P}^n \times \mathbb{C}^k \times \mathbb{P}$ of the set of points where $\Psi$ is not a submersion. Let us call affine discriminant and denote by $\Delta_P$ the closure in $\mathbb{C}^k \times \mathbb{P}$ of the image $\Psi(\Gamma_P \cap (\mathbb{C}^n \times \mathbb{C}^k \times \mathbb{C}))$ of the affine part of $\Gamma_P$.

Since we are only interested in the germ of $\Gamma_P$ at $\mathbb{P}^n \times \{0\} \times \mathbb{P}$, respectively in the germ of $\Delta_P$ at $\{0\} \times \mathbb{P}$, we shall tacitly use the same notations for the germs.

It follows from the definition that $\Gamma_P$ is a closed analytic set and its affine part $\Gamma_P \cap (\mathbb{C}^n \times \mathbb{C}^k \times \mathbb{C})$ is just the union, over $s \in \mathbb{C}^k$, of the affine critical loci of the polynomials $f_s$. Note that, if $\dim \text{Sing} f_s \leq 0$ for any $s$, then $\dim \Gamma_P \leq k$.

4.1. Affine critical locus of FISI deformations. Let now assume that $P$ is a one-
parameter FISI deformation. It follows that, if $\Gamma_P$ is not empty, then it is a curve.

An irreducible component $\Gamma_i$ of the germ $\Gamma_P$ can be of one of the following three types:

- Type I: $\Gamma_i \cap \{\sigma = 0\} \subset \mathbb{C}^n \times \{0\} \times \mathbb{C}$. Then $\Gamma_i$ is not in the neighbourhood of infinity.
- Type II: $\Gamma_i \cap \{\sigma = 0\} \subset Y_\infty$, a point having finite $t$-coordinate.
- Type III: $\Gamma_i \cap \{\sigma = 0\}$ is a point having infinite $t$-coordinate.

Let us decompose $\Gamma_P = \Gamma_I \cup \Gamma_{II} \cup \Gamma_{III}$ according to these types. If the total Milnor number $\mu(s)$ is not constant in the deformation $P$, then necessarily $\Gamma_{II} \cup \Gamma_{III} \neq \emptyset$. The points where $\Gamma_{II}$ intersects the hyperplane at infinity are shown to play an important role. The similar question for $\Gamma_{III}$ requires the completion with $t = \infty$.

Lemma 4.2. Let $P$ be a one-parameter FISI deformation. Then $\Gamma_{II} \cap \{x_0 = 0\} \subset \Sigma_0 \times \{0\} \times \mathbb{C}$ and $\Gamma_{III} \cap \{x_0 = 0\} \subset W_0 \times \{0\} \times \{\infty\}$.
Proof. From the definition of $\Gamma_P$ it follows that $\Gamma_P \cap \{\sigma = s\} \subset \mathbb{C}^n \times \mathbb{C}$, for any $s \neq 0$. Therefore $\Gamma_P \cap \{x_0 = 0\} \subset H^\infty \times \{0\} \times \mathbb{C}$. The curve $\Gamma_P \cap \mathbb{Y}$ is included into the critical set of the map $\Psi = (\sigma, \tau): \mathbb{Y} \to \mathbb{C} \times \mathbb{P}$. Slicing this with $\{x_0 = 0\}$ and $\{\sigma = 0\}$ gives \(\{\frac{\partial P}{\partial x}(x, 0) = 0, P_{d-1}(x, 0) = 0\}\times \mathbb{C}\).

For $\Gamma_{III}$, we homogenise the equations of $\Gamma_P \cap (\mathbb{C}^n \times \mathbb{C} \times \mathbb{C})$, which are $\{\frac{\partial P}{\partial x}(x, s) = 0, P(x, s) = t\}$, and get an algebraic set into $\mathbb{P}^n \times \mathbb{C} \times \mathbb{P}^1$, which we slice by $t = \infty \in \mathbb{P}^1$ and by $\{\sigma = 0\}$. This gives the set $\{\frac{\partial f}{\partial x}(x) = 0\} \subset H^\infty$.

For general-at-infinity deformations we can prove more precise results, as follows (see also Theorem 5.4).

**Proposition 4.3.** Let $P$ be a general-at-infinity deformation of a $\mathcal{F}$ISI $f_0$. If for some $t \in \mathbb{C}$, $\mathbb{Y}_{0,t}$ is non-singular but tangent to $H^\infty$ then $\Gamma_{III} \neq \emptyset$.

**Proof.** Our hypothesis on $\mathbb{Y}_{0,t}$ is equivalent to $\Sigma_0 = \emptyset$ and $W_0 \neq \emptyset$. Since $\Gamma_P \cap \mathbb{Y}_{0,t} \subset \Sigma_0 \times \mathbb{C}$, it follows that there are no type II components of $\Gamma_P$. Moreover, $\Sigma_0 = \emptyset$ implies that $\lambda(0) = 0$. Since $W_0 \neq \emptyset$, the total Milnor number $\mu(0)$ is strictly less than $\mu(s)$, for $s \neq 0$, by (2.4) and (5.1). This can only be due to the fact that affine critical values of $f_s$ tend to infinity, as $s \to 0$. This means that branches of type III do exist.

**Proposition 4.4.** Let $P$ be a one-parametre $\mathcal{F}$ISI deformation and assume that the total space $\mathbb{Y}$ is non-singular. If for some $t \in \mathbb{C}$, $\mathbb{Y}_{0,t}$ has singularities on $H^\infty$ then all branches of $\Delta_P$ of type II are tangent to the $\{\sigma = 0\}$-axis.

**Proof.** Our condition on $\mathbb{Y}_{0,t}$ is equivalent to $\Sigma_0 \neq \emptyset$ and is a necessary condition for the existence of type II branches of $\Gamma_P$, see Lemma 4.2. Let $v = (p, t_0) \in \Gamma_P \cap \mathbb{Y}^\infty$. Denote by $\Gamma_{P,v}$ the germ of $\Gamma_P$ at $v$. We may assume that $\Gamma_{P,v}$ is an irreducible germ, if not, then we take an irreducible component of it. Take a parametrization of $\Gamma_{P,v}$, $\gamma(\epsilon)$, with $\gamma(0) = v$. One should prove that the fraction $\sigma(\gamma(\epsilon))/\tau(\gamma(\epsilon))$ tends to 0 as $\epsilon \to 0$. This is indeed so since $\tau$ is a linear function germ of the non-singular space $\mathbb{Y}$ and $\sigma$ has a singularity at $v$, hence it is in the square of the maximal ideal of holomorphic germ at $v$. Then our claim follows by Lé’s result [Lé2, Proposition 1.2].

5. Changes of topology within deformations

We study the change of topology within the class of $\mathcal{F}$ISI polynomials. Let $P$ be a $\mathcal{F}$ISI deformation of a polynomial $f = f_0$ of degree $d$. We recall the notations in §2 and adapt them to our family $f_s$, as follows: $G_s$ is the general fiber of $f_s$, $F_{s,t} := f_s^{-1}(t)$, $\mu(s)$ is the total Milnor number and $\lambda(s)$ is the total Milnor-Lé number at infinity of $f_s$. Note that if $f_s$ is GI then $\lambda(s) = 0$ and $\chi(F_{s,t}) = \chi(n, d)$ if $t \notin B_{f_s}$. We first have the following semi-continuity result:

**Proposition 5.1.** Let $P$ be a $\mathcal{F}$ISI deformation of $f_0$. Then the number of vanishing cycles $\gamma(s) := \mu(s) + \lambda(s)$ is upper semi-continuous, i.e.

$$\mu(s) + \lambda(s) \geq \mu(0) + \lambda(0).$$
Proof. When examining the formula (2.4) applied to \( f_s \), namely:
\[
\gamma(s) = b_{n-1}(G_s) = (d - 1)^n - \sum_{p_i \in W_s} (\mu_{p_i, \text{gen}}(s) + \mu_{p_i}^\infty(s)),
\]
we see that \( \mu_{p_i, \text{gen}}(s) \) and \( \mu_{p_i}^\infty(s) \) are lower semi-continuous since local Milnor numbers of hypersurface singularities.

From (5.1) and the semi-continuity of its \( \mu \)-ingredients, we also get:

**Corollary 5.2.** If \( P \) is a \( \gamma(s) \)-constant deformation, then both \( \mu_{p_i, \text{gen}}(s) \) and \( \mu_{p_i}^\infty(s) \) are constant for small \( |s| \).

Let us denote by \( \mu_I(s), \mu_{II}(s), \mu_{III}(s) \) the sum of the Milnor numbers of the singularities of \( f_s \) at the affine points of \( \Gamma_I, \Gamma_{II}, \Gamma_{III} \) respectively. We have \( \mu(s) = \mu_I(s) + \mu_{II}(s) + \mu_{III}(s) \) and, if the deformation is general-at-infinity, then we know that \( \mu(s) = (d - 1)^n \).

**Lemma 5.3.** If \( P \) is a general-at-infinity deformation then
\[
\mu_{II}(s) + \mu_{III}(s) = \lambda(0) + \sum_{p_i \in W_0} \beta_{p_i}(0),
\]
where \( \beta_{p_i}(s) := \mu_{p_i, \text{gen}}(s) + \mu_{p_i}^\infty(s) \).

Proof. Since \( f_s \) is GI for \( s \neq 0 \), we have \( \lambda(s) = 0 \) and \( W_s = \emptyset \), hence \( \beta_{p_i}(s) = 0 \). From the formula (2.1) for \( f_0 \) and \( f_s \), we get \( b_{n-1}(G_s) - b_{n-1}(G_0) = \mu_{II}(s) + \mu_{III}(s) - \lambda(0) \), whereas from (2.4), see also (5.1), we get \( b_{n-1}(G_s) - b_{n-1}(G_0) = \Delta \beta := \sum_{p_i \in W_0} \beta_{p_i}(0) \).

Related to the semi-continuity result Proposition 5.1, a question which arises next would be: what is the behaviour of \( \mu(s) \) and of \( \lambda(s) \) when \( s \to \infty \)? It is clear that the total Milnor number \( \mu(s) \) cannot increase. It can either be constant (e.g. in homogeneous deformations of polynomials) or decrease, like in Example 8.1. In case \( \mu(s) \) decreases, as \( s \to 0 \), we say that there is loss of \( \mu \) at infinity; this happens if and only if \( \Gamma_{II} \cup \Gamma_{III} \neq 0 \).

In contrast, \( \lambda(s) \) may either increase or decrease (or be constant). Examples where it increases may be found in Siersma-Smeltink paper [SS], see also Example 8.3. Examples of \( \lambda \)-constant deformations are all those with \( \lambda(s) = 0 \). Example 8.4 (of a non-FISI deformation) shows that \( \lambda(s) \) may decrease. An important fact is that we can now detect \( \lambda \) by \( \Gamma_P \).

**Theorem 5.4.** Let \( P \) be a one-parameter \( F_{\text{ISI}} \) deformation of a polynomial \( f_0 \) such that the total space \( \mathbb{Y} \) is non-singular. Let \( p \in \Sigma_0 \). Then \( (p, 0, t_0) \in \Gamma_P \) if and only if \( \lambda_{p,t_0}(0) \neq 0 \) and in this case we have:
\[
\lambda_{p,t_0}(0) < \sum_{(a,s,t) \in \Gamma_P \cap \mathbb{Y}_{s,t}} \mu(\mathbb{Y}_{s,t}, a),
\]
where \( s \in D^* \) is fixed, close enough to 0, and the sum is taken over the singular points of \( f_s \) which tend to \( (p, 0, t_0) \) as \( s \to 0 \).
Proof. Consider the germ of \( Y \) at \((p, 0, t_0)\) and the restriction map \( \Psi = (\sigma, \tau) : (Y, (p, 0, t_0)) \rightarrow \mathbb{C}^2 \). The condition \((p, 0, t_0) \in \Gamma_P\) implies that \( \Sigma_0 \neq \emptyset \), which implies that \( \sigma : Y \rightarrow \mathbb{C} \) has non-isolated singularities at \((p, 0, t_0)\). Nevertheless \( \tau \) is a linear function on \( Y \) and has isolated singularities on \( Y_{0,0} \), \( \mathbb{C} \). Then the Milnor fiber of \( \tau \) is contractible. After [Lê1], we may take a small ball \( B \) in \( Y \) at \((p, 0, t_0)\) and a 2-disk \( D \times D' \) in \( \mathbb{C}^2 \) at \((0, t_0)\), such that \( \Psi \) induces a locally trivial fibration \( \Psi : (B \cap Y) \setminus (\Gamma_P \cup \{\sigma = 0\}) \rightarrow (D \times D') \setminus \Delta_P \). Let \( Y_{U,V} := B \cap Y_{U,V} \), for \( U \subset D \) and \( V \subset D' \). Since \( \tau \) is a linear function, we have that \( Y_{D,t} \) is contractible, for any \( t \in D' \). Taking into account the singularities of the fibers of the projection \( \sigma : Y_{D,t} \rightarrow D \) and using Lê’s attaching results [Lê2], we deduce the following homotopy equivalences:

\[
Y_{D,t} \xrightarrow{ht} Y_{s,t} \cup \mu_p(t_0) \text{ cells of dimension } n - 1, \\
Y_{D,t} \xrightarrow{ht} Y_{s,t} \bigcup \{\mu_p(t) \text{ cells of dimension } n - 1\} \bigcup \{\alpha \text{ cells of dimension } n - 1\},
\]

where

\[
\mu_p(t) := \mu(Y_{0,t}, p), \quad \mu_p(t_0) := \mu(Y_{0,t_0}, p), \\
\alpha := \sum_{(a,s,t) \in \Gamma_P \cap Y_{D,t}} \mu(Y_{s,t}, a).
\]

**Figure 1. Attaching cells**

Since \( Y_{s,t_0} \xrightarrow{ht} Y_{s,t} \) we have the equality \( \mu_p(t_0) = \mu_p(t) + \alpha \) and therefore \( \alpha = \mu_p(t_0) - \mu_p(t) = \lambda_{p,t_0}(0) \), by (2.2). Since \( \Gamma_P \) consists of trajectories of affine singular points, \( \alpha \) is an intersection number, namely:

\[
\alpha = \text{int}_{(p,t_0)}(\Gamma_P, \{\tau = t_0\}) = \text{int}_{(0,t_0)}(\Delta_P, \{\tau = t_0\}),
\]

where in the first intersection number, each point is counted with multiplicity equal to the Milnor number of the singularity of the fiber of \( \Psi \) at that point. The second intersection number involves in addition the multiplication by the degree of the covering \( \Gamma \xrightarrow{\Phi} \Delta \), for
each irreducible component of $\Gamma$ and of $\Delta$. This shows that $\alpha > 0$, which is our first claim. Let us emphasize that $\lambda_{p,t_0}(0)$ was identified with the intersection number between $\Gamma_{II}$ and the hyperplane $\{\tau = t_0\}$.

To prove the second part of the statement, let us first observe that the right-hand side of the claimed inequality is equal to the following intersection numbers, taken with appropriate multiplicities:

$$\text{int}_{(p,t_0)}(\Gamma_P, \{\sigma = 0\}) = \text{int}_{(0,t_0)}(\Delta_P, \{\sigma = 0\}).$$

By Proposition 4.4, $\Delta_P$ is tangent to $\{\sigma = 0\}$. This tangency implies that:

$$\text{int}_{(0,t_0)}(\Delta_P, \{\sigma = 0\}) > \text{int}_{(0,t_0)}(\Delta_P, \{\tau = t_0\}),$$

which gives the claimed inequality.

Corollary 5.5. In the conditions of Theorem 5.4, if $\deg f_0 > 2$ and the singularities of some fiber $Y_{0,t}$ at $H_\infty$ are of type $A_1$ only, then $\Gamma_{II} = \emptyset$.

Proof. Since $\deg f > 2$, the type $A_1$ of the singularities at $H_\infty$ of $Y_{0,t}$ is independent of $t$. Consequently, there is no jump of $\mu$ at infinity. It follows, by formulas (2.2) and (2.3), that $\lambda(0) = 0$. By Theorem 5.4, this means that there is no $\Gamma_{II}$. 

6. The $s$-monodromy and boundary singularities

Let $P$ denote a one-parameter, general-at-infinity deformation of a (non-GI) polynomial $f_0$ and define the topological bifurcation diagram in the $(s, t)$-target space of the map $\Psi = (\sigma, \tau) : Y \setminus Y_\infty \to \mathbb{C} \times \mathbb{C}$, as follows:

$$(6.1) \quad \text{Bif}_{s,t}^\top := \{(s, t) \mid \Psi \text{ is not a topologically trivial fibration at } (s, t)\} \subset \mathbb{C} \times \mathbb{C}.$$

Since $P$ is a GI deformation, $\text{Bif}_{s,t}^\top$ is the union of the $t$-axis $\{\sigma = 0\}$ and the affine discriminant $\Delta_P \cap (\mathbb{C} \times \mathbb{C})$.

Let $F_{A,B}$ denote the set $(\mathbb{C}^n \times \mathbb{C}) \cap \sigma^{-1}(A) \cap \tau^{-1}(B)$, for some subsets $A \subset \mathbb{C}$ and $B \subset \mathbb{C}$. Take a small disc $D$ centered at the origin in the $s$-coordinate space $\mathbb{C}$. The $s$-monodromy is the monodromy of the fibration over the circle $F_{0D,\mathbb{C}} \to \partial D$.

We study this monodromy action on the general fiber $F_{s,t}$, where $(s, t) \notin \text{Bif}_{s,t}^\top$, in relations to the singularities at infinity of $f_0$.

Let then $s \in \partial D$ and $h_{s,t}$ denote the $s$-monodromy over $\partial D$ acting on the homology $H_s(F_{s,t}, \mathbb{Z})$. For a fixed value of $t$, there are 3 types of $s$-monodromies, corresponding to the 3 types of loops (see Figure 2): “gen” – for a generic value of $t$, “aty” – for an atypical value of $t$, “inf” – for $t$ near infinity, in case of branch of type III.

In the first two cases we avoid intersections of $\partial D^* \times \{t\}$ with $\Delta_P$, in the third case we require intersections with branches of type III.

6.1. The generic case. Let $t \in \mathbb{C}$ and let $D$ be a small enough disc as above, centered at $0 \in \mathbb{C}$, such that the disc $\partial D^* \times \{t\}$ does not intersect $\Delta_P$. The fiber $F_{s,t}$ has a geometric $s$-monodromy over $\partial D$ which can be extended to a diffeomorphism of $F_{D,t}$ into itself, the
latter being isotopic to the identity. The induced algebraic monodromy is called generic $s$-monodromy and will be denoted by $h_{\text{gen}}$.

Since $f_0$ is $\mathcal{F}$ISI and the deformation $P$ is general-at-infinity, the fibers of the restriction to $D \times \{t\}$ of the map $\bar{\Psi} : Y \to \mathbb{C} \times \mathbb{C}$ have no singularities at $H^\infty$, except for the fiber $Y_{0,t}$. So let $p_i \in Y_{0,t}^\infty$ be such a singularity and let $B_i \subset Y$ be a Milnor ball at $p_i$. We assume that $D$ is small enough such that $(B_i, D)$ is Milnor data for any $i$. Then, by excision, we have the following direct sum decomposition of the relative homology:

$$H^*(F_{D,t}, F_{s,t}) = \bigoplus_i H^*(B_i \cap F_{D,t}, B_i \cap F_{s,t}).$$

Lemma 6.1. Let $P$ be a one-parameter $\mathcal{F}$ISI deformation of a polynomial $f_0$ such that $W_0 \cap \{\phi_d = 0\} = \emptyset$. Then, for $n \geq 2$:

(a) $H^*(F_{D,t}, F_{s,t})$ is concentrated in dimension $n$.
(b) $H_q(B_i \cap F_{s,t})$ is trivial if $q \neq 0, 1, n - 1$, it is $\mathbb{Z}$ if $q = 0$ and if $q = 1 \neq n - 1$, and it is isomorphic to $H_n(B_i \cap F_{D,t}, B_i \cap F_{s,t})$ if $q = n - 1 \neq 1$. If $n = 2$ then $H_1(B_i \cap F_{s,t}) \simeq \mathbb{Z} \oplus H_2(B_i \cap F_{D,t}, B_i \cap F_{s,t})$.

Proof. (a). Since the family of hypersurfaces $Y_{s,t}$, for $s \in D$ is a smoothing of the hypersurface with only isolated singularities $Y_{0,t}$, it follows from [Ti], using [HL], that the relative homology $H^*(B_i \cap F_{D,t}, B_i \cap F_{s,t})$ is concentrated in dimension $n$. Our claim then follows by the direct sum decomposition (6.1). Note that the point (a) only requires the $\mathcal{F}$ISI condition.

(b). By Proposition 3.3, our space $Y_{D,t}$ is nonsingular. Hence $B_i \cap Y_{D,t} \setminus Y_\infty$ is homeomorphic to a ball of dimension $n$ from which one takes out a coordinate hyperplane, so this space is homeomorphic to $\mathbb{C}^n \setminus \mathbb{C}^{n-1}$. Then (b) follows from the long exact sequence of the pair $(B_i \cap F_{D,t}, B_i \cap F_{s,t})$. \qed

Let $h_i$ denote the $s$-monodromy action on $H_{n-1}(B_i \cap F_{s,t})$. This can be interpreted as the Milnor monodromy of a boundary singularity. Indeed, the function $\tau$ on the ball $B_i \cap Y_{D,t}$ has an isolated singularity at $p_i \in Y_{0,t}^\infty$. Its restriction $\tau|_Y^{\infty}$ to the non-singular hyperplane $Y^{\infty}$ has also an isolated singularity at $p_i$. It was Arnol’d who founded the study of germs of boundary singularities and classified simple germs, see [AGV]. In his paper [Ar2], Arnol’d shows that the classification of meromorphic germs of type $H/Z^d$ is closely related to the classification of boundary singularities (see also §9).
To the pair of function germs \((\tau, \tau_{Y_s})\) at \(p_i\), one associates the pair of Milnor fibers \((B_i \cap Y_{s,t}, B_i \cap Y_{s,t}^\infty)\). In a subsequent work, A. Szpirglas [Sz] studied vanishing cycles of boundary singularities, from the point of view of a certain duality between the pair of Milnor fibers and their difference. After [Sz], there are two Lefschetz-dual short exact sequences, which in our case take the following form (in case \(n \geq 2\)):

\[
0 \rightarrow H_{n-1}(B_i \cap Y_{s,t}) \rightarrow H_{n-1}(B_i \cap Y_{s,t}, B_i \cap Y_{s,t}^\infty) \xrightarrow{\partial} \tilde{H}_{n-2}(B_i \cap Y_{s,t}^\infty) \rightarrow 0
\]

(6.3)

\[
0 \leftarrow H_{n-1}(B_i \cap Y_{s,t}) \leftarrow H_{n-1}(B_i \cap F_{s,t}) \xleftarrow{L} \tilde{H}_{n-2}(B_i \cap Y_{s,t}^\infty) \leftarrow 0,
\]

where \(L\) is the Leray “tube” map.

7. ZETA-FUNCTION OF THE S-MONODROMY

For a monodromy action \(h\) on a space \(M\) one defines the zeta-function on the \(\mathbb{Z}\)-homology \(H_*(M)\), as follows:

\[
\zeta_M(t) := \prod_{j \geq 0} [\det(I - t \cdot h | H_j(M))]^{(-1)^{j+1}}.
\]

With this sign convention, the degree of the zeta-function is equal to \(-\chi(M)\).

Let then \(\zeta_{gen}\) denote the zeta-function of the generic s-monodromy \(h_{gen}\) on \(H_*(F_{s,t})\). Let \(Z_i := B_i \cap F_{s,t}\) and let \(\zeta_{Z_i}\) denote its zeta-function. Remark that \(Z_i\) is the Milnor fiber of a transversal singularity to a non-isolated singularity, see §7.2.1 for explanations.

For \(n \geq 2\), by using (6.3), it follows that \(\zeta_{Z_i}(t)\) is equal to the product \(\zeta_{B_i \cap Y_{s,t}}(t) \cdot \zeta_{B_i \cap Y_{s,t}^\infty}(t)\) of the zeta-functions of the boundary singularity \((Y_{0,t}, Y_{0,t}^\infty)\) at the point \((p_i, 0, t)\).

**Proposition 7.1.**

\[
\zeta_{gen}(t) = (1 - t)^{-\chi(F_{0,t})} \cdot \prod_i [\zeta_{B_i \cap Y_{s,t}}(t) \cdot \zeta_{B_i \cap Y_{s,t}^\infty}^{-1}(t)].
\]

**Proof.** Note that the homology \(\tilde{H}_*(F_{s,t})\) is concentrated in dimension \(n - 1\). The exact sequence of the pair \((F_{D,t}, F_{s,t})\) yields the following exact sequence on which the s-monodromy acts (for \(n \geq 2\)):

\[
0 \rightarrow H_n(F_{D,t}) \rightarrow H_n(F_{D,t}, F_{s,t}) \rightarrow H_{n-1}(F_{s,t}) \rightarrow H_{n-1}(F_{D,t}) \rightarrow 0.
\]

By (6.2) and by Lemma 6.1, we get \(\prod_i \zeta_{Z_i}(t) = \zeta_{(F_{D,t}, F_{s,t})}^{-1}(t)\). As shown before, we also have \(\zeta_{Z_i} = \zeta_{B_i \cap Y_{s,t}} \cdot \zeta_{B_i \cap Y_{s,t}^\infty}^{-1}\). Then apply the zeta-function to above exact sequence. Since on \(H_*(F_{D,t})\) the s-monodromy is trivial, and since \(\chi(F_{D,t}) = \chi(F_{0,t})\), we get the claimed equality. □
7.1. The atypical case. This case works exactly as the generic case and we get a similar formula for \( \zeta_{aty} \), for a fixed value \( t_0 \):

\[
\zeta_{aty}(t) = (1 - t)^{-\chi(F_{0,t_0})} \cdot \prod_i \left[ \zeta_{B_i \cap Y_{s,t_0}}(t) \cdot \zeta_{B_i \cap Y_{s,t_0}^\infty}(t) \right].
\]

Note that \( F_{0,t_0} \) is now the atypical fiber and that the zeta-functions \( \zeta_{B_i \cap Y_{s,t_0}} \) and \( \zeta_{B_i \cap Y_{s,t_0}^\infty} \) are the ones of its corresponding boundary singularities.

7.2. The global \( s \)-monodromy of \((F_{s,C}, F_{s,t})\). The \( s \)-monodromy also acts on the homology exact sequence of the pair \((F_{s,C}, F_{s,t})\). Since \( F_{s,C} = \mathbb{C}^n \), the monodromy on it is trivial and we have the isomorphism:

\[
H_s(F_{s,C}, F_{s,t}) \xrightarrow{\sim} H_{s-1}(F_{s,t}),
\]

which is equivariant with respect to the \( s \)-monodromy action, concentrated in \( * = n \).

We may decompose the relative homology, by excision, into a direct sum of submodules, which correspond to the points where the discriminant \( \Delta_P \) intersects the \( t \)-axis and at \( t = \infty \). We take within \( \{s\} \times \mathbb{C} \) a disjoint union of disks \( \bigcup j T_j \) connected by simple, non-intersecting paths to some general point \((s, t)\), with the following property: each disk \( T_j \) contains all intersection points with \( \Delta_P \) that tend, as \( s \to 0 \), to a single point of \( \Delta_P \cap \{0\} \times \mathbb{C} \) or tend to the infinity point \( \{0\} \times \infty \) of the projective compactification \( \{0\} \times \mathbb{P}^1 \). Similarly as in [ST3], one may define a geometric monodromy on \( F_{s,C} \), such that it acts on \( F_{s,T_j} \), for any \( j \), and on every fiber \( F_{s,t} \) such that \( t \not\in \bigcup_{j \geq 0} T_j \). By convention, \( T_0 \) means the punctured disk centered at \( \{0\} \times \infty \); this corresponds of course to the intersections with \( \Delta_{III} \).

We get the following direct sum decomposition, compatible with the monodromy action in homology:

\[
(7.1) \quad H_n(F_{s,C}, F_{s,t}) \xrightarrow{\sim} \bigoplus_j H_n(F_{s,T_j}, F_{s,t}).
\]

In the source space we can further localise the vanishing homology to neighborhoods of the intersection points of \( \Gamma_P \) with \( Y_{0,C} \). The branches of \( \Delta_P \) that meet \( T_j \) can be projections of one or more branches of \( \Gamma_P \), of different types. We assume from now on that each \( T_j \) contains projections of a single type of branches, so that to each disk \( T_j \) one may assign a well-defined type I, II or III.

The direct sum (7.1) can be decomposed into 3 terms, according to the type of \( T_j \). Then the zeta-function splits accordingly too. We get:

**Proposition 7.2.** \( \zeta_{gen}(t) = (1 - t)^{-1+(-1)^n \mu(0)} \zeta_{I}^{-1}(t) \cdot \zeta_{II}^{-1}(t) \cdot \zeta_{III}^{-1}(t) \).

**Proof.** Comparing \( \zeta_{gen} \) with the zeta-function of \( h \) on \( H_n(F_{s,C}, F_{s,t}) \) gives \( \zeta_{gen}(t) = (1 - t)^{-1} \zeta_I^{-1}(t) \cdot \zeta_{II}^{-1}(t) \cdot \zeta_{III}^{-1}(t) \).

For \( \zeta_I \) we have the following formula:

\[
\zeta_I(t) = (1 - t)^{-\chi(F_{s,T_j}, F_{s,t})} = (1 - t)^{(-1)^{n+1} \mu(0)}.
\]
where $T_I$ denotes the union of type I disks and their corresponding paths. Indeed, for disks of type I, the $s$-monodromy on $H_n(F_{s,T_I})$ is the identity, and $\chi(F_{s,T_I},F_{s,t}) = (-1)^n\mu(0)$. \qed

7.2.1. $s$-monodromy related to $\Delta_{II}$. For some point $(p,0,t_0) \in \Gamma_{II} \cap \mathbb{Y}_{0,T}^{\infty}$, let us take a Milnor ball $B$ and recall the notation $Y_{s,T} := B \cap \mathbb{Y}_{s,T}$. This is the Milnor fiber of the germ at $(p,0,t_0)$ of the non-isolated line singularity $Y_{0,T}$ and $\zeta_{Y_{s,T}}$ will denote its monodromy. The reduced homology of $Y_{s,T}$ is concentrated in dimensions $n-2$ and $n-1$. Slicing $Y_{0,T}$ by $\mathbb{Y}_{C,t}$ at some point $(p,0,t)$, for $t$ close to $t_0$, defines the transversal singularity. Its Milnor fiber is $Z_t := B(p,0,t) \cap \mathbb{Y}_{s',t}$, where $B(p,0,t) \subset \mathbb{Y}$ is a small Milnor ball centered at $(p,0,t)$ and $s' \in \partial D_t$, for some disc $D_t$ of radius smaller than that of $B_t$, such that $(D_t \times \{t\}) \cap \Gamma_{I} = \emptyset$. The reduced homology $\tilde{H}_s(Z_t,\mathbb{Z})$ is concentrated in dimension $n-2$. We denote by $\zeta_{Z_t}$ the zeta-function of the Milnor monodromy of the transversal singularity.

With these notations, we get the following formula for type II components:

**Proposition 7.3.**

$$\zeta_{II}(t) = (1 - t)^{(-1)^n - 1}\lambda(0) \prod [\zeta_{Y_{s,T}}(t) \cdot \zeta_{Z_t}^{-1}(t)],$$

where the product is taken over all $T$’s of type II and, for each such $T$, over all points $\Gamma_{II} \cap \mathbb{Y}_{0,T}^{\infty}$.

**Proof.** Note first that $Y_{s,t} := B \cap \mathbb{Y}_{s,T}$ is the Milnor fiber of the germ at $(p,0,t_0)$ of the hypersurface $\mathbb{Y}_{0,t_0}$. Then, for some fixed $T$ we have:

$$\zeta(F_{s,t},F_{s,t}) = \zeta_{F_{s,t}} \cdot \zeta_{F_{s,t}}^{-1} = \zeta_{Y_{s,T}} \cdot \zeta_{Y_{s,T}}^{-1} \cdot \zeta_{Y_{s,t}} \cdot \zeta_{Y_{s,t}}^{-1} = \prod [\zeta_{Y_{s,T}} \cdot \zeta_{Y_{s,t}} \cdot \zeta_{Y_{s,t}}^{-1} \cdot \zeta_{Y_{s,t}}^{-1}] = \prod [\zeta_{Y_{s,T}} \cdot \zeta_{Y_{s,t}}^{-1}],$$

where the product is taken over all points $\Gamma_{II} \cap \mathbb{Y}_{0,T}^{\infty}$. The cancellation in the last equality is due to the product structure $Y_{s,t}^{\infty} = Y_{s,t}^{\infty} \times T$.

The zeta-function $\zeta_{Y_{s,t}}$ corresponds to the $s$-monodromy of the fiber $Y_{s,t}$ around the transversal singularity. This is not the Milnor monodromy of $Y_{s,t}$ since not all vanishing cycles of $Y_{s,t}$ vanish at the singularity $(p,0,t)$. In fact there is a geometric decomposition of the reduced homology into a direct sum $\tilde{H}_s(Y_{s,t},\mathbb{Z}) = M \oplus N$, where $M$ is the module of cycles vanishing at $(p,0,t)$ and $N$ denotes the module of cycles vanishing at the points of intersection $\Gamma_p \cap \mathbb{Y}_{t,C}$ which tend to $(p,0,t_0)$ as $t \to t_0$. Note that $b_{n-1}(M) = \mu_{p,\text{gen}}(0)$ and that $b_{n-1}(N) = \lambda_{p,t_0}(0)$, as shown in the proof of Theorem 5.4 (see also Figure 1).

Now we may apply a general Picard type theorem$^3$ which in our case says that the action of the $s$-monodromy on some cycle in $N$ is the identity, modulo $M$. At the level of zeta-functions, this yields a product decomposition:

$$\zeta_{Y_{s,t}}(t) = (1 - t)^{(-1)^n\lambda_{p,t_0}(0)} \cdot \zeta_{Z_t}(t).$$

$^1$Non-isolated line singularities and their monodromy have been studied by Dirk Siersma in several papers, see e.g. [Si1, Si2].

$^2$Remark that we used the notation $Z_t$ for the same object $Z_t$ in the beginning of §7.

$^3$A proof can be found in [ST2, Prop. 2.2].
Taking the product over all points $\Gamma_{II} \cap Y_{0,T}$ and over all $T$, yields the claimed formula. \hfill \Box

In terms of the corresponding Betti numbers, we can read the above proposition as follows:

\begin{equation}
\mu_{II} = \sum_{(p,t_0) \in \Gamma_{II} \cap Y_{0,T}} (b_n(Y_{0,T},(p,t_0)) - b_{n-1}(Y_{0,T},(p,t_0)) + \mu_{p,geo}(0)) + \lambda(0),
\end{equation}

where $b_n$ and $b_{n-1}$ are the Betti numbers of the Milnor fiber of the non-isolated line singularity $Y_{0,C}$ at the point $(p,0,t_0)$.

7.2.2. \textit{s-monodromy related to $\Delta_{III}$.} Since we can compute the zeta-function of the generic $s$-monodromy in two different ways, we are able to compute $\zeta_{III}$. Indeed, by comparing the formulas in Propositions 7.1 and 7.2, we get:

\begin{equation}
\zeta_{II}(t) \cdot \zeta_{III}(t) = (1-t)(-1)^{n-1}\mu_{p,geo}(0) \cdot \prod i \zeta_i^{-1}(t).
\end{equation}

In terms of Milnor numbers, this yields:

$$\mu_{II} + \mu_{III} = \lambda(0) + \sum \beta_i,$$

and so we find again the formula given by Lemma 5.3.

From (7.3) and Proposition 7.3, we may deduce a formula for $\zeta_{III}$.

8. Examples

We show by examples the various ways in which the $\mu \leftrightarrow \lambda$ exchange takes place during deformations $P$, in relation to the affine discriminant $\Delta_P$.

Example 8.1. Let $f = x^2y + x$, the Broughton example [Bro] of a polynomial with no affine singularities and one singularity at infinity: $\mu = 0$ and $\lambda = 1$. The $\lambda$ corresponds to a jump of the local type of $X_t$ at infinity from $A_2$ to $A_3$, see §2. Compare also to Remark 9.3.

Consider the deformation $f_s = x^2y + x + sy^3$. This is a GI deformation of a $FISI$ polynomial. The topological bifurcation set $\text{Bif}_{top}^P$ consists of the axis $\{\sigma = 0\}$ and the affine discriminant $\Delta_P$, which has equation $s = \alpha t^4$.

We have that $\Delta_P = \Delta_{II}$ and $\Delta_{II}$ is tangent to $\{\sigma = 0\}$. According to Theorem 5.4, this forces $\lambda(0) > 0$. For $s \neq 0$ we have: $\mu(s) = 4$ and $\lambda(s) = 0$, so, as $s \to 0$:

$$\mu + \lambda = 4 + 0 \to 0 + 1.$$

In order to show the intermediate steps in this process, we consider the deformation, see Siersma-Smeltink paper [SS]:

$$P(x,y;s_1,s_2,s_3) = x^2y + x + s_1y + s_2y^2 + s_3y^3.$$
Then the affine discriminant $\Delta_P$ has the following structure:
\[
\begin{align*}
& s_3 \neq 0 & \mu + \lambda &= 4 + 0 \\
& s_3 = 0, \ s_2 \neq 0 & \mu + \lambda &= 3 + 0 \\
& s_3 = s_2 = 0, \ s_1 \neq 0 & \mu + \lambda &= 2 + 0 \\
& s_3 = s_2 = s_1 = 0 & \mu + \lambda &= 0 + 1.
\end{align*}
\]

In particular, the deformation $f_s = x^2y + x + sy$ is shown in Figure 3, right side. Here $\Delta_P = \Delta_{II}$ has equation $s = ct^2$.

For the zeta-function of the $s$-monodromy in the above $y^3$-deformation, Proposition 7.1 gives the following formulas. Remark that the boundary singularity is of type $(A_2, A_1)$ at the point $[0 : 1] \in \mathbb{Y}^\infty_0$, for $t \neq 0$, and of type $(A_3, A_1)$ when $t = 0$.

\[
\zeta_{gen}(t) = \frac{1 - t^3}{1 - t} \cdot \frac{1 - t^2}{1 - t}, \quad \zeta_{aty}(t) = (1 - t)^{-1} \cdot \frac{1 - t^4}{1 - t} \cdot \frac{1 - t^2}{1 - t}.
\]

The formula for $\zeta_{II}$ in Proposition 7.3 needs knowledge on the non-isolated singularity of $\mathbb{Y}$ at the point $(0 : 1, 0, 0)$. According to de Jong’s list [dJ], this is of type $F_1A_2$ and therefore its Milnor fiber is homotopy equivalent to a 2-sphere and its monodromy on $H_2$ is $-id$. We get:

\[
\zeta_{II}(t) = (1 - t)^{-1} \cdot \frac{1 - t}{1 - t^4} \cdot \frac{1}{1 + t}.
\]

This fits with (7.3) since $\zeta_{III} = 1$ and the above result for $\zeta_{gen}$.

**Example 8.2.** Start with the polynomial $f = y^{k+1} + x^k$. By homogenising and localising in the chart $x = 1$, this corresponds to the fraction $A_k$ in Arnol’d’s list (Table 1), see §9 for details.

The hypersurface $\mathbb{X}_t$ is non-singular and $k$-fold tangent to the hyperplane at infinity $H^\infty$. Let us study the following Yomdin deformation (in particular, a GI deformation):

\[
f_s = y^{k+1} + x^k + sx^{k+1}.
\]

Then $\mathbb{Y}_{s,t}$ intersects transversely $H^\infty$ for all $t$ and all $s \neq 0$. Moreover, $\mathbb{Y}_{0,t}$ has no singularity at $H^\infty$ and is tangent to $H^\infty$ at the point $[1 : 0] \in H^\infty$. 

**Figure 3.** $y^2$-deformation and $y$-deformation of Broughton’s example
We get that $\Delta_I$ is the $s$-axis \{ $\tau = 0$ \}, $\Delta_{II} = \emptyset$ (and therefore $\lambda(0) = 0$) and that $\Delta_{III}$ has equation $s^k t = \alpha$ (see Figure 4). A slice $t = t_0$ will cut $\Gamma_{III}$ at $k$ points, each of which representing a singularity of some $Y_{s,t}$ of type $A_k$.

\[ \tau \]
\[ \Delta_{m} \]
\[ \Delta_{i} \]
\[ \sigma \]

**Figure 4. Yomdin deformation of $A_k$.**

Since at $H^\infty$ we have a boundary singularity of type $(A_0, A_k)$, the zeta-function of the generic $s$-monodromy is, after Proposition 7.1:

$\zeta_{gen}(t) = (1-t)^{-1-k+k^2} \cdot \frac{1-t^{k+1}}{1-t}$.

**Example 8.3.** ("Mixed example").

\[ f_s = xy^4 + x^2y^2 + y + sx^5. \]

We get:

\[
\begin{align*}
& s = 0 \quad \mu + \lambda = 5 + 2 \\
& s \neq 0 \quad \mu + \lambda = 16 + 0.
\end{align*}
\]

When $s = 0$, the value 2 of $\lambda(0)$ is got in connection to the jump $D_6 \to D_8$ at $t = 0$.

The topological bifurcation set $\text{Bif}^{top}_{p}$ consists of 3 branches: the axis $\sigma = 0$ (since $\gamma(0) \neq \gamma(s)$, $\Delta_I$, $\Delta_{II}$ and $\Delta_{III}$). For $\Delta_{II}$ we get the equation $s^2 = \alpha t^7$, and $\mu_{II} = 7$. For $\Delta_{III}$ we get the equation $s^6 t^4 = \beta$, and $\mu_{III} = 4$. The difference to the total $\gamma(s) = 16$ is of course $\mu_I = 5$, which corresponds to $\Delta_I$.

For the zeta-function of the $s$-monodromy, we apply Proposition 7.1, remarking that the boundary singularity at infinity is of type $(D_6, A_3)$, for generic $t$, and of type $(D_8, A_3)$ for $t = 0$. We therefore get:

$\zeta_{gen}(t) = (1-t)^6 \cdot \zeta_{D_6}(t) \cdot (1-t^4)$, \quad $\zeta_{aty}(t) = (1-t)^4 \cdot \zeta_{D_8}(t) \cdot (1-t^4)$,

where $\zeta_{D_6}$ and $\zeta_{D_8}$ are the local zeta-functions of the $D_6$ and $D_8$ hypersurface germs (Arnol’d’s classification [Ar1]), respectively.

**Example 8.4.** In certain deformations, the invariant $\lambda$ may decrease. The following example is not a $\mathcal{F}ISI$ deformation since the initial polynomial $f_0$ is not $\mathcal{F}ISI$ (however, $f_0$ is isomorphic to a linear form): $f_s = x + sx^2y + z^3$. We have: $\lambda(s) = 2$, $\mu(s) = 0$, for $s \neq 0$, and $\lambda(0) = 0$, $\mu(0) = 0$. 

9. On Arnol’d’s classification

In his paper [Ar2], V.I. Arnol’d studied germs of fractions \( P/Q \), where \( P \) and \( Q \) are polynomials, with respect to several equivalence relations such as the right-equivalence. The relation to polynomial functions is as follows. Starting with a polynomial \( f : \mathbb{C}^n \to \mathbb{C} \) of degree \( d \) in coordinates \( (x, y_2, \ldots, y_n) \), we can introduce new affine coordinates \( Y = \frac{2}{x}, Z = \frac{1}{x} \) in order to study points at infinity \( [x : y : 1] = [1 : Y : Z] \). For \( f = t \) one gets \( t = \frac{H(Y, Z)}{Z^d} \), where \( H(Y, Z) = \tilde{f}(1, Y, Z) \) and \( \tilde{f}(x, y, z) \) denotes the homogenised of \( f(x, y) \) with the new variable \( z \).

According to Arnol’d’s study, right-equivalence of fractions is very near to right-equivalence of boundary singularities. In the above example, the boundary singularity is the one of the germ \( H(Y, Z) \) with respect to the hyperplane \( Z = 0 \). After [Ar2], the list of simple fractions of type \( \frac{H(Y, Z)}{Z^d} \) is given in Table 1 (where the letter \( Q \) denotes a quadratic form in the rest of the \( Y \)-coordinates).

| type | function | boundary type | conditions |
|------|----------|--------------|------------|
| \( A_0 \) | \( \frac{Y}{Z^d} \) | \( (A_0, A_k) \) | \( k \geq 1, \ d > 1 \) |
| \( A_k \) | \( \frac{Y^{k+1} + Z + Q_2}{Z^d} \) | \( (A_0, A_k) \) | \( k \geq 1, \ d > 1 \) |
| \( B_k \) | \( \frac{Y^2 + Z^k + Q_2}{Z^d} \) | \( (A_{k-1}, A_1) \) | \( k \geq 2, \ d > k \) |
| \( C_k \) | \( \frac{Y^k + YZ + Q_2}{Z^d} \) | \( (A_1, A_{k-1}) \) | \( k \geq 3, \ d > 1 \) |
| \( D_k \) | \( \frac{Y^2Y_2 + Y_2^{k-1} + Z + Q_3}{Z^d} \) | \( (A_0, D_k) \) | \( k \geq 4, \ d > 1 \) |
| \( E_6 \) | \( \frac{Y_1^3 + Y_2^4 + Z + Q_3}{Z^d} \) | \( (A_0, E_6) \) | \( d > 1 \) |
| \( E_7 \) | \( \frac{Y_1^3 + Y_1Y_2^3 + Z + Q_3}{Z^d} \) | \( (A_0, E_7) \) | \( d > 1 \) |
| \( E_8 \) | \( \frac{Y_1^3 + Y_2^5 + Z + Q_3}{Z^d} \) | \( (A_0, E_8) \) | \( d > 1 \) |
| \( F_4 \) | \( \frac{Y^3 + Z^2 + Q_3}{Z^d} \) | \( (A_2, A_2) \) | \( d > 2 \) |

Table 1. Arnol’d’s list of fractions of type \( H/Z^d \)

All the simple germs in Arnol’d’s list have \( \lambda = 0 \), so they are topologically trivial at infinity. However, deforming these singularities yields an interesting behaviour. As we have shown before, we may consider for instance Yomdin deformations and their \( s \)-monodromy. Those are non-trivial.

Example 9.1. Let us treat the \( A_k \) singularity, where \( d = k + 1 \), namely \( f = y^{k+1} + x^k \). Consider the following unfolding and its corresponding localisation:

\[
P(x, y; s_1, \ldots, s_k) = y^{k+1} + x^k + s_1x^2y^{k-1} + s_2x^3y^{k-2} + \cdots s_kx^{k+1},
\]

\[
y^{k+1} + x_0 + s_1y^{k-1} + s_2y^{k-2} + \cdots s_k = t_0^{k+1}.
\]

In the parameter space \( \mathbb{C}^k \) there exists a natural stratification of the bifurcation set of \( P \) (see Corollary 3.8):

\[
\text{Bif}_P := \{ s \in \mathbb{C}^k \mid b_{n-1}(G_s) < (d - 1)^n \},
\]
corresponding to the number and multiplicity of the roots of the polynomial \( y^{k+1} + s_1 y^{k-1} + s_2 y^{k-2} + \cdots s_k \). Each stratum of Bif \( P \) yields a well-defined Betti number \( b_1(G_s) \) of the general fiber \( G_s \) of \( f_s \). The following 2-parameter deformation:

\[
f_s = y^{k+1} + x^k + s_1 x^{k+1} + s_2 x^k y
\]

yields a kind of Morsification, in the sense that, fixing \( s_2 \) close to 0, we get \( k \) values of \( s_1 \) for which \( f_s \) has simple tangencies at infinity. We send to Example 8.2 for more details on the 1-parameter Yomdin deformation \( f_s = y^{k+1} + x^k + s x^{k+1} \).

We end by two remarks.

**Remark 9.2.** There is an important difference between looking to global polynomial functions and looking to the germ at some point at infinity. For example, take the \( A_k \) fraction singularity from Arnol’d’s list (Table 1). By changing coordinates, one gets \( f = x^{d-k-1} y^{k+1} + x^{d-1} \), which can be viewed as a global polynomial function. When \( d > k - 1 \), this has a non-isolated singularity, which is of course not in the chart \( x = 1 \). However, one can get rid of non-isolated singularities by finding more suitable representatives in the same right-equivalence class. For instance, in case of \( A_1 \):

\[
\frac{Y^2 + Z}{Z^d} \sim \frac{Y^2 + Z + Y^3 Z}{Z^d},
\]

which corresponds, at the point \([1 : 0 : 0]\), to the equivalence:

\[
x^2 y^2 + x^3 \sim x^2 y^2 + x^3 + y^3.
\]

**Remark 9.3.** The polynomial \( f = y + xy^2 \) of degree 3, which is Broughton’s example (see Example 8.1), does not occur in Arnol’d’s list (Table 1). Indeed, in coordinates at infinity we see the following equivalence:

\[
\frac{Y^2 + Y Z^2}{Z^3} \sim \frac{Y^2 + Z^4}{Z^3},
\]

which is the \( B_4 \) fraction germ, but this is not simple, since here \( d < k \). Another way to see the non-simplicity of \( B_4 \) is as follows. There is no inner modulus in case of \( B_4 \) in degree 3, but this exists for \( B_3 : \frac{Y^2 + \alpha Z^3}{Z^3} \), since \( \alpha \) is indeed an inner modulus. That \( B_4 \) is not simple follows now from adjacency.

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