Does indirectness of signal production reduce the explosion-supporting potential in chemotaxis-haptotaxis systems? Global classical solvability in a class of models for cancer invasion (and more)

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Abstract
We propose and study a class of parabolic-ODE models involving chemotaxis and haptotaxis of a species following signals indirectly produced by another, non-motile one. The setting is motivated by cancer invasion mediated by interactions with the tumor microenvironment, but has much wider applicability, being able to comprise descriptions of biologically quite different problems. As a main mathematical feature constituting a core difference to both classical Keller-Segel chemotaxis systems and Chaplain-Lolas type chemotaxis-haptotaxis systems, the considered model accounts for certain types of indirect signal production mechanisms.

The main results assert unique global classical solvability under suitably mild assumptions on the system parameter functions in associated spatially two-dimensional initial-boundary value problems. In particular, this rigorously confirms that at least in two-dimensional settings, the considered indirectness in signal production induces a significant blow-up suppressing tendency also in taxis systems substantially more general than some particular examples for which corresponding effects have recently been observed.

Key words: chemotaxis; haptotaxis; indirect signal production; global existence
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1 Introduction

We study here a general class of parabolic-parabolic-ODE-ODE systems (see (1.3) below) containing the following model of cancer invasion with chemotaxis and haptotaxis:

\[
\begin{align*}
    u_t &= \Delta u - \chi \nabla \cdot (u \nabla h) - \xi \nabla \cdot (u \nabla v) + \mu u(1 - u - v - w), \\
    h_t &= \Delta h - h + \alpha w, \\
    v_t &= -hv + \eta v(1 - u - v) + \beta \frac{w}{1+w}, \\
    w_t &= u,
\end{align*}
\]

supplemented with adequate initial conditions and no-flux boundary conditions. The model variables are: \( u \): density of tumor cells, \( h \): concentration of matrix metalloproteinases (MMP), \( v \): density of tissue fibers (extracellular matrix, ECM), \( w \): density of cancer associated fibroblasts (CAFs). The chemotactic bias of the cells is in the direction of the MMP gradient, while haptotaxis means as usual following the gradient of tissue density. In most of the previous chemotaxis and chemotaxis-haptotaxis models the chemoattractant is directly produced by the population performing diffusion and taxis, thereby involving (38) or not (31, 43, 45) the ECM in this production. In our present model the chemoattractant is generated in an indirect way, by the CAFs, which are activated by the tumor cells.

In [5] was introduced a complex model for the evolution of a population of tumor cells interacting with two chemoattractants and also performing haptotaxis. One of the chemoattractants therein is directly produced by the cells, while the other’s production is mediated by another substance, the latter being in turn produced by the cells under the influence of the first chemoattractant. All model variables (except tissue) are diffusing in a linear way; in particular, the producers of all chemoattractants are diffusive. This is not the case in our model (1.1); moreover, both signals are completely \( h \) or partially \( (v) \) obtained from the non-diffusing, indirect producer \( w \).

Model (1.1) is motivated by the problem of investigating CAF-mediated cancer invasion into the surrounding tissue. CAFs are major components of the neoplasm microenvironment. They secrete a variety of extracellular matrix components and are involved in the formation of the desmoplastic stroma characterizing many advanced carcinomas (15). For a long time the general belief was that tumor development, invasion, and metastasis occur as a result of cancer progression. Recent studies revealed, however, that CAFs contribute instead of tumor cells to these processes, via expression of various growth factors, cytokines, chemokines, and degradation of ECM (7, 15, 31, 36), but also by restructuring the latter to facilitate migration (22). Fibronectin (Fn) assembled by CAFs mediates cell association and directional migration. Compared with normal fibroblasts, CAFs produce an Fn-rich ECM with anisotropic fiber orientation, along which the tumor cells preferentially migrate (10). The origin of CAFs is not completely elucidated; we refer e.g. to [6, 20] for a couple of reviews. There is evidence that they can arise among others from carcinoma cells through epithelial-mesenchymal transition (EMT) (23), thus allowing the cancer cells to adopt a mesenchymal phenotype associated to enhanced migratory capacity and invasiveness (9, 39). It has also been shown (cf. e.g. 29) that cancer cells can reprogram resident tissue fibroblasts to become CAFs through the actions of miRNAs. MMPs are primarily derived from CAFs in various types of tumor (23, 26, 29). In particular, it has been shown e.g., that MMP-9, an endoproteinase involved in ECM degradation and implicated as a prerequisite of metastasis, has very limited or no expression in various cancer cell lines. Instead, MMP-9 is well-known to be secreted from cancer stromal fibroblasts and endothelial cells (39).
further information about CAFs and their MMP production we refer, e.g., to the review [26]. The main features of CAF-mediated tumor invasion mentioned above are captured in our model (1.1) below.

Closely related from a mathematical viewpoint is the chemotaxis-haptotaxis model

\[
\begin{align*}
    u_t &= D_u \Delta u + \chi \nabla \cdot (u \nabla h) - \xi \nabla \cdot (u \nabla v) - k_1 u + k_2 \frac{hw}{1+hw}, \\
    h_t &= D_h \Delta h + k_3 w - k_4 h, \\
    v_t &= -k_5 (h + u + w)v + k_6 v(1 - v)^2, \\
    w_t &= k_7 u - k_8 hw + k_9 w(1 - u - v - w)^2,
\end{align*}
\]

which describes the evolution of two cancer cell subpopulations either proliferating \( (w) \) or migrating \( (u) \), with the corresponding transitions between the two phenotypes, and in interaction with tissue \( (v) \) and acidity \( (h) \). The latter is mainly produced by the highly glycolytic proliferating tumor cells – hence indirect signal production. The proliferation/migration (also known as go-or-grow) dichotomy asserting that moving cells defer their proliferation seems to be a relevant feature for some types of cancer ([13],[21],[49]) and can lead to interesting mathematical problems and qualitative behavior of the corresponding heterogeneous tumor ([37],[51]). The migrating cells in (1.2) perform haptotaxis and pH-taxis: they move towards increasing ECM gradient and away from acidic (thus hypoxic) areas. The conversion from proliferating to migrating cells depends on the concentration \( h \) of protons in the peritumoral region and infers limitations, as only a rather small part of the tumor becomes motile -usually cells situated at the tumor margins. Moreover, the protons are buffered by the environment (e.g., uptake by vasculature), contribute to tissue degradation, and restrict tumor proliferation. Supplementary to hypoxia the tissue can be degraded by chemical or biological agents directly or indirectly produced or activated by the tumor cells, see e.g. [27] and [28]. The ECM remodeling also involves limited, logistic-like growth. The latter is also used in (1.2) to describe tumor cell proliferation. We note here that taking squares of the positive parts of the proliferation terms is motivated by the mainly technical need of satisfying the regularity assumptions in Theorem 1.1 and could perhaps be relaxed; in fact, the difference between functions of this type just involving the positive parts and those taking their squares is rather small. System (1.2) fits in the theoretical framework proposed and analyzed below.

Thus the general model class to be introduced and studied here includes descriptions of biologically quite different problems, as exemplified above. It therefore provides a comprehensive mathematical structure for several issues related to cancer cell migration under the influence of chemo- and haptotactic effects, including some variants of the often addressed Chaplain-Lolas model from [5]. Other problems characterizing tactic cell migration, e.g. in wound healing and/or angiogenesis or interacting microbial populations in biofilm formation and persistence, can potentially be cast into this mathematical framework. Models describing the dynamics of a species performing chemotaxis towards the gradient of a signal produced by another, non-tactic species (see e.g. [19] and [47]) form a subclass of this setting.

**Approaching a mathematical core feature:** indirectness of chemoattractant production.

From a purely mathematical perspective, a common feature distinguishing both (1.2) and (1.1) from classical chemotaxis or chemotaxis-haptotaxis systems of Keller-Segel or Chaplain-Lolas type consists in the circumstance that the respective mechanisms of chemoattractant production are indirect in
the sense that the corresponding signal is not produced directly by individuals of the cell population, but rather through a third agent. Possible implications on the system dynamics, however, have apparently been detected only in some quite particular examples of chemotaxis-only models: Indeed, the only findings in this direction we are aware of concentrate on associated derivates of the classical Keller-Segel system, for which substantial blow-up preventing effects of such indirect signal production mechanisms have recently been revealed. More precisely, in sharp contrast to what is known for standard Keller-Segel systems ([17], [2]), regardless of the size of the initial data some corresponding spatially two-dimensional initial-boundary value problems always possess globally defined classical solutions ([47], [25]).

Complementary to its biological motivation, the main mathematical purpose of the present work is to rigorously confirm that such relaxing effects of indirect chemoattractant production are actually not restricted to cases of chemotaxis-only systems, but rather seem to form a much more general and robust feature of chemotactic interaction also in significantly more contexts involving haptotactic migration mechanisms with all their potentially regularity-limiting properties due to lack of haptotactant diffusion.

This will subsequently be examined in the framework of the problem

\[
\begin{align*}
  u_t &= D_u \Delta u - \chi \nabla \cdot (u \nabla h) - \xi \nabla \cdot (u \nabla v) + f(u, v, w, h), & x \in \Omega, \ t > 0, \\
  h_t &= D_h \Delta h + g(u, v, w, h), & x \in \Omega, \ t > 0, \\
  v_t &= -\alpha u w + v \phi(u, v, w, h) + \Phi(w), & x \in \Omega, \ t > 0, \\
  w_t &= \beta u + w \psi(u, v, w, h), & x \in \Omega, \ t > 0, \\
  D_u \frac{\partial u}{\partial \nu} - \xi u \frac{\partial v}{\partial \nu} &= \frac{\partial h}{\partial \nu}, & x \in \partial \Omega, \ t > 0, \\
  u(x, 0) = u_0(x), \ h(x, 0) = h_0(x), \ v(x, 0) = v_0(x), \ w(x, 0) = w_0(x), & x \in \Omega,
\end{align*}
\]

(1.3)
in a bounded domain \( \Omega \subset \mathbb{R}^2 \) with smooth boundary, where the parameters \( \chi, \xi, D_u, D_h, \alpha \) and \( \beta \) are assumed to be positive, and where for simplicity we suppose throughout this paper that with some \( \vartheta \in (0, 1) \),

\[
\begin{align*}
  u_0 &\in C^{2+\vartheta}(\bar{\Omega}) \quad \text{is nonnegative with } u_0 \neq 0, \\
  h_0 &\in C^{2+\vartheta}(\bar{\Omega}) \quad \text{is nonnegative}, \\
  v_0 &\in C^{2+\vartheta}(\bar{\Omega}) \quad \text{is positive in } \bar{\Omega} \text{ with } \frac{\partial v_0}{\partial \nu} = 0 \text{ on } \partial \Omega, \text{ and that} \\
  w_0 &\in C^{2+\vartheta}(\bar{\Omega}) \quad \text{is positive in } \bar{\Omega}.
\end{align*}
\]

(1.4)

As for the parameter functions in (1.3), in order to create a setup sufficiently general so as to include both (1.2) and (1.1), we shall require that

\[
\quad f, g, \phi \text{ and } \psi \quad \text{belong to } \quad C^1([0, \infty)^4) \quad \text{and} \quad \Phi \in C^1([0, \infty)),
\]

(1.5)

and are such that

\[
\begin{align*}
  f_0(u) &\leq f(u, v, w, h) \leq C_f(v) \cdot (u + w + 1) \quad \text{for all } (u, v, w, h) \in [0, \infty)^4 \\
  \text{with some } f_0 &\in C^1([0, \infty)) \text{ such that } f_0(0) \geq 0, \text{ and some nondecreasing } C_f : [0, \infty) \rightarrow (0, \infty)
\end{align*}
\]

(1.6)
and
\[
\left\{\begin{array}{ll}
|g(u, v, w, h)| \leq C_g(v) \cdot (w + h + 1) & \text{for all } (u, v, w, h) \in [0, \infty)^4 \\
\text{with some nondecreasing } C_g : [0, \infty) \to (0, \infty) & \text{and}
\end{array}\right.
\]
and
\[
g(0, v, w, 0) \geq 0 & \text{for all } (v, w) \in [0, \infty)^2,
\]
that
\[
\left\{\begin{array}{ll}
\phi(u, v, w, h) \leq -c_\phi \cdot w + C_\phi & \text{for all } (u, v, w, h) \in [0, \infty)^4, \\
\phi_u(u, v, w, h) \leq \frac{C_\phi}{\sqrt{w^4 + 1}} & \text{for all } (u, v, w, h) \in [0, \infty)^4, \\
\phi_v(u, v, w, h) \leq \frac{C_\phi}{\sqrt{v^4 + 1}} + C_\phi & \text{for all } (u, v, w, h) \in [0, \infty)^4, \\
\phi_w(u, v, w, h) \leq \frac{C_\phi}{\sqrt{w^4 + 1}} + C_\phi & \text{for all } (u, v, w, h) \in [0, \infty)^4 \\
\phi_h(u, v, w, h) \leq \frac{C_\phi}{\sqrt{h^4 + 1}} + C_\phi & \text{for all } (u, v, w, h) \in [0, \infty)^4 \\
\text{with some positive constants } c_\phi & \text{and } C_\phi,
\end{array}\right.
\]
and that
\[
\left\{\begin{array}{ll}
0 \leq \Phi(w) \leq C\Phi & \text{for all } w \geq 0 \\
w\Phi'(w)^2 \leq C\Phi \Phi(w) & \text{for all } w \geq 0,
\end{array}\right.
\]
and finally
\[
\left\{\begin{array}{ll}
\psi(u, v, w, h) \leq C_\psi(v) & \text{for all } (u, v, w, h) \in [0, \infty)^4, \\
\psi_u(u, v, w, h) \leq \frac{C_\psi(v)}{\sqrt{w^4 + 1}} & \text{for all } (u, v, w, h) \in [0, \infty)^4, \\
\psi_v(u, v, w, h) \leq \frac{C_\psi(v)}{\sqrt{v^4 + 1}} & \text{for all } (u, v, w, h) \in [0, \infty)^4, \\
\psi_w(u, v, w, h) \leq \frac{C_\psi(v)}{\sqrt{w^4 + 1}} & \text{for all } (u, v, w, h) \in [0, \infty)^4 \\
\psi_h(u, v, w, h) \leq \frac{C_\psi(v)}{\sqrt{h^4 + 1}} & \text{for all } (u, v, w, h) \in [0, \infty)^4 \\
\text{with some nondecreasing } C_\psi : [0, \infty) \to (0, \infty) & \text{and some } \gamma \in (0, 1/2).\]
\]
As can readily be verified, indeed both models [12] and [11] then become special cases of the PDE system in [13] whenever the parameters $D_u, D_h, \chi, \xi, k_4$ and $k_6$ therein are positive, whereas $k_i$ for $i \in \{1, 2, 3, 5, 7, 8\}$ and $\eta$ and, in particular, $\mu$ is merely required to be nonnegative.

Our main results in this context then read as follows.

**Theorem 1.1** Let $\Omega \subset \mathbb{R}^2$ be a bounded domain with smooth boundary, assume that $\chi, \xi, \alpha, \beta, D_u$ and $D_h$ are positive, and suppose that $f, g, \phi, \Phi$ and $\psi$ satisfy (1.5), (1.6), (1.7), (1.8), (1.9) and (1.10). Then for any choice of $(u_0, h_0, v_0, w_0)$ fulfilling (1.4) with some $\vartheta \in (0, 1)$, the problem (1.3) possesses a uniquely determined globally defined classical solution $(u, h, v, w) \in (C^{2,1}(\Omega \times [0, \infty))^4$ for which $u, h, v$ and $w$ are nonnegative.

In particular, Theorem 1.1 asserts that indeed no finite-time blow-up occurs in [13] under the above assumptions, and that in this regard the solution behavior in [13] quite drastically differs from that in the corresponding variants of [12] and [11] in which the second equation is replaced with e.g. $h_t = D_h \Delta h + u$, and in which already in the semi-trivial case when $v \equiv 0$, known results on the actually resulting two-component Keller-Segel system for $(u, h)$ assert finite-time blow-up for some solutions ([16]).
In line with this, all known results even on global existence, but also on qualitative properties, in the original Chaplain-Lolas model \((5)\)

\[
\begin{cases}
  u_t = \Delta u - \chi \nabla \cdot (u \nabla h) - \xi \nabla \cdot (u \nabla v) + \mu u (1 - u - v), \\
  h_t = \Delta h - h + u, \\
  v_t = -hv + \eta v(1 - u - v),
\end{cases}
\tag{1.11}
\]

seem to strongly rely on the assumption that \(\mu\) be positive, thus guaranteeing the presence of a logistic-type quadratic growth restriction on the cell density \((4), (32), (31), (40), (41), (46), (48)\). Our results show that in the context of the variant \((1.1)\) of \((1.11)\) involving indirect chemotactic production, no such additional dampening is necessary: Indeed, even when tissue remodeling is included by supposing that \(\eta > 0\) in \((1.1)\), Theorem 1.1 asserts global classical solvability in \((1.1)\) for actually any nonnegative value of \(\mu\).

The paper is structured as follows: After stating a result on local existence and extensibility as well as some preliminary estimates in Section 2, in Section 3 we shall construct a quasi-energy functional for \((1.3)\) and draw some immediate conclusions concerning regularity of solutions. The accordingly obtained estimates are used as a starting point for a Moser-type iterative argument yielding \(L^\infty\) bounds for the key solution component \(u\) in Section 4, and hence paving an essential part of the way toward our proof of Theorem 1.1 in Section 5. Finally, in Section 6 we illustrate the theoretical findings by numerical simulations of \((1.1)\) and the corresponding model with direct signal production and provide some comments about the obtained results.

### 2 Local existence and basic estimates

Following several precedents in the literature \((11), (12), (31)\), in order to establish a preliminary result on local existence, but also to prepare our subsequent estimation procedure, we note that on substituting

\[
z := ue^{-\lambda v} \quad \text{with} \quad \lambda := \frac{\xi}{\Delta u} > 0,
\tag{2.1}
\]

the problem \((1.3)\) is equivalently transformed to

\[
\begin{cases}
  z_t = D_u e^{-\lambda v} \nabla \cdot (e^{\lambda v} \nabla z) - \chi e^{-\lambda v} \nabla \cdot (ze^{\lambda v} \nabla h) + e^{-\lambda v} f(ze^{\lambda v}, v, w, h), & x \in \Omega, \ t > 0, \\
  h_t = D_h \Delta h + g(ze^{\lambda v}, v, w, h), & x \in \Omega, \ t > 0, \\
  v_t = -\alpha ve^{\lambda v} z + v\phi(ze^{\lambda v}, v, w, h) + \Phi(w), & x \in \Omega, \ t > 0, \\
  w_t = \beta e^{\lambda v} z + w\psi(ze^{\lambda v}, v, w, h), & x \in \Omega, \ t > 0, \\
  \frac{\partial z}{\partial \nu} = \frac{\partial h}{\partial \nu} = 0, & x \in \partial \Omega, \ t > 0, \\
  z(x, 0) = u_0(x)e^{\lambda v_0(x)}, h(x, 0) = h_0(x), v(x, 0) = v_0(x), w(x, 0) = w_0(x), & x \in \Omega.
\end{cases}
\tag{2.2}
\]

In this formulation, with respect to the construction of local-in-time solutions the problem \((1.3)\) indeed becomes accessible to appropriate fixed point frameworks; by straightforward and minor adaptations of the corresponding arguments detailed e.g. in \((31)\), it is thereby possible to establish the following basic statement on unique solvability and extensibility.
Lemma 2.1 Let $\chi, \xi, \alpha, \beta, D_u$ and $D_h$ be positive, let $f, g, \phi, \Phi$ and $\psi$ comply with \((1.5), (1.6), (1.7), (1.8), (1.9)\) and \((1.10)\), and suppose that \((u_0, h_0, v_0, w_0)\) satisfies \((1.4)\) with some $\vartheta \in (0, 1)$. Then there exist $T_{\text{max}} \in (0, \infty]$ and a uniquely determined classical solution $(z, h, v, w) \in (C^2(\bar{\Omega} \times [0, \infty)))^4$ of \((2.2)\) such that

either $T_{\text{max}} = \infty$, or $\limsup_{t \to T_{\text{max}}} \{ \|z(\cdot, t)\|_{L^\infty(\Omega)} + \|v(\cdot, t)\|_{W^{1,5}(\Omega)} \} = \infty$. \tag{2.3}

Moreover, we have $z > 0, h \geq 0, v > 0$ and $w > 0$ in $\bar{\Omega} \times (0, T_{\text{max}})$.

Without any further explicit mentioning, throughout the sequel we shall suppose that the assumptions of Lemma 2.1 are satisfied, and that $(z, v, w, h)$ and $T_{\text{max}} \in (0, \infty]$ are as provided by the latter. Moreover, we shall tacitly switch between these variables and the quadruple $(u, v, w, h)$ solving \((1.3)\) classically in $\Omega \times (0, T_{\text{max}})$, as thereby defined through \((2.1)\).

A first boundedness property of this solution is immediate.

Lemma 2.2 The solution of \((1.3)\) satisfies

$v(x, t) \leq \left\{ \|v_0\|_{L^\infty(\Omega)} + \frac{C\phi}{C\Phi} \right\} \cdot e^{C\phi t}$ for all $x \in \Omega$ and $t \in (0, T_{\text{max}})$.

\tag{2.4}

Proof. As from \((1.3), (1.8)\) and \((1.9)\) we know that

$v_t \leq C\phi v + C\Phi$ in $\Omega \times (0, T_{\text{max}}),$

by means of a simple comparison argument we conclude that

$$
\|v(\cdot, t)\|_{L^\infty(\Omega)} \leq \|v_0\|_{L^\infty(\Omega)} e^{C\phi t} + C\Phi \int_0^t e^{C\phi(t-s)} ds \text{ for all } t \in (0, T_{\text{max}}).
$$

Herein estimating $\int_0^t e^{C\phi(t-s)} ds \leq \frac{1}{C\phi} e^{C\phi t}$ for $t \geq 0$, from this we readily obtain \((2.4)\). \qed

Next, thanks to \((1.6)\) and \((1.7)\) the first and fourth solution components in \((1.3)\) can at least controlled with respect to their norm in $L^1(\Omega)$ in a fairly simple manner.

Lemma 2.3 Let $T > 0$. Then there exists $C(T) > 0$ such that

$$
\int_{\Omega} u(\cdot, t) \leq C(T) \quad \text{and} \quad \int_{\Omega} w(\cdot, t) \leq C(T) \quad \text{for all } t \in (0, \hat{T}) \tag{2.5}
$$

as well as

$$
\int_{\Omega} h(\cdot, t) \leq C(T) \quad \text{for all } t \in (0, \hat{T}), \tag{2.6}
$$

where $\hat{T} := \min \{T, T_{\text{max}}\}$. 7
Proof. Using that \( v \leq c_1(T) := \|v_0\|_{L^\infty(\Omega)} + \frac{c_\phi}{c_\phi} \cdot e^{C_\phi T} \) in \( \Omega \times (0, \hat{T}) \) due to Lemma 2.2, after spatial integration in the first and the fourth equation in (1.3) and adding the respective results we may rely on (1.6) and (1.10) in estimating

\[
\frac{d}{dt} \left\{ \int_\Omega u + \int_\Omega w \right\} = \int_\Omega f(u, v, w, h) + \int_\Omega u + \int_\Omega w \psi(u, v, w, h)
\leq C_f(c_1(T)) \cdot \left\{ \int_\Omega u + \int_\Omega w + |\Omega| \right\} + \beta \int_\Omega u + C_\psi(c_1(T)) \int_\Omega w
\leq \left\{ C_f(c_1(T)) + \beta + C_\psi(c_1(T)) \right\} \cdot \left\{ \int_\Omega u + \int_\Omega w + |\Omega|C_f(c_1(T)) \right\}
\]

for \( t \in (0, \hat{T}) \). A time integration of this linear ODI for \( \int_\Omega u + \int_\Omega w \) directly yields (2.5). Similarly, (1.7) implies that

\[
\frac{d}{dt} \int_\Omega h = \int_\Omega g(u, v, w, h) \leq C_g(c_1(T)) \cdot \left\{ \int_\Omega w + \int_\Omega h + |\Omega| \right\}
\]

for all \( t \in (0, \hat{T}) \), so that (2.6) becomes a consequence of (2.5).

□

3 A quasi-energy inequality

The purpose of this section consists in the construction of a Lyapunov-like functional which through a corresponding energy-dissipation inequality will provide some fundamental regularity information that will form the starting point of a series of \textit{a priori} estimates which in the presently considered spatially two-dimensional setting will finally allow for the conclusion that \( (u, v, w, h) \) is actually global in time.

As our first step in this direction, let us perform a standard testing procedure by which the crucial haptotactic contribution to the first equation in (1.3) is reduced to an \( L^2 \) inner product of gradients:

Lemma 3.1 Let \( \eta > 0 \). Then

\[
\frac{d}{dt} \int_\Omega u \ln u + D_u \int_\Omega \frac{\nabla u^2}{u} \leq \xi \int_\Omega \nabla u \cdot \nabla v + \frac{\chi^2}{2\eta} \int_\Omega |\Delta h|^2 + \eta \int_\Omega u^2 + C_f(\|v\|_{L^\infty(\Omega)}) \cdot \int_\Omega u \ln u + C_f(\|v\|_{L^\infty(\Omega)}) \cdot \int_\Omega w + \frac{C^2_f(\|v\|_{L^\infty(\Omega)})}{2\eta} \cdot \int_\Omega w + C_f(\|v\|_{L^\infty(\Omega)}) \cdot \int_\Omega h + |\Omega|C_f(\|v\|_{L^\infty(\Omega)}) + |\Omega| \cdot \|f_0 \cdot \ln \|_{L^\infty((0,1))}
\]

for all \( t \in (0, T_{max}) \).

Proof. In the identity

\[
\frac{d}{dt} \int_\Omega u \ln u + D_u \int_\Omega \frac{\nabla u^2}{u} = \chi \int_\Omega \nabla u \cdot \nabla h + \xi \int_\Omega \nabla u \cdot \nabla v + \int_\Omega f(u, v, w, h) \ln u + \int_\Omega f(u, v, w, h)
\]
valid for all \( t \in (0, T_{\text{max}}) \) due to (1.3), we use Young’s inequality to estimate

\[
\chi \int_{\Omega} \nabla u \cdot \nabla h = -\chi \int_{\Omega} u \Delta h \leq \frac{\eta}{2} \int_{\Omega} u^2 + \frac{\chi^2}{2\eta} \int_{\Omega} |\Delta h|^2 \quad \text{for all } t \in (0, T_{\text{max}}).
\] (3.3)

Moreover, by means of (1.6) we see that for all \( t \in (0, T_{\text{max}}) \),

\[
\int_{\Omega} f(u, v, w, h) \leq C_f(\|v\|_{L^\infty(\Omega)}) \cdot \left\{ \int_{\Omega} u + \int_{\Omega} w + |\Omega| \right\}
\]

and

\[
\int_{\Omega} f(u, v, w, h) \ln u \leq C_f(\|v\|_{L^\infty(\Omega)}) \cdot \int_{\{u \geq 1\}} (u + w + 1) \cdot \ln u + \int_{\{u < 1\}} f_0(u) \cdot \ln u
\]

\[
\leq C_f(\|v\|_{L^\infty(\Omega)}) \cdot \left\{ \int_{\Omega} u \ln u + \int_{\Omega} u w + \int_{\Omega} u \right\} + |\Omega| \cdot \|f_0 \cdot \ln \|_{L^\infty((0, 1))}
\]

\[
\leq C_f(\|v\|_{L^\infty(\Omega)}) \cdot \left\{ \int_{\Omega} u \ln u + \int_{\Omega} u \right\} + \frac{\eta}{2} \int_{\Omega} u^2 + \frac{C^2_f(\|v\|_{L^\infty(\Omega)})}{2\eta} \int_{\Omega} w^2
\]

\[+ |\Omega| \cdot \|f_0 \cdot \ln \|_{L^\infty((0, 1))},
\] because \( \ln y \leq y \) for all \( y \geq 1 \). In conjunction with (3.2)-(3.4), this establishes (3.1).

Now in order to achieve a precise cancelation of the integral in (3.1) stemming from haptotactic cross-diffusion, inspired by several precedent works on similar types of interaction (see e.g. [8], [45] and [38]), we track the evolution of the Dirichlet integral associated with \( \sqrt{v} \).

**Lemma 3.2** The solution of (1.3) has the property that

\[
\frac{d}{dt} \int_{\Omega} \frac{\nabla v^2}{v} + \frac{c_\phi}{2} \int_{\Omega} \frac{w}{v} |\nabla v|^2
\]

\[
\leq -2\alpha \int_{\Omega} \nabla u \cdot \nabla v + \frac{\alpha D_u}{2\xi} \int_{\Omega} \frac{|\nabla u|^2}{u}
\]

\[+ \left\{ 2C_\phi \cdot (2\|v\|_{L^\infty(\Omega)} + 1) + \frac{2\xi C^2_\phi}{\alpha D_u} \right\} \cdot \int_{\Omega} \frac{|\nabla v|^2}{v}
\]

\[+ \left\{ 4C^2_\phi \cdot (\|v\|_{L^\infty(\Omega)} + 1) \right\} \cdot \int_{\Omega} \frac{|\nabla w|^2}{w}
\]

\[+ 2C_\phi \cdot (\|v\|_{L^\infty(\Omega)} + 1) \cdot \int_{\Omega} |\nabla h|^2 \quad \text{for all } t \in (0, T_{\text{max}}).
\] (3.5)
Proof. According to the third equation in (1.3), we have
\[
\frac{d}{dt} \int_{\Omega} \frac{|\nabla v|^2}{v} = 2 \int_{\Omega} \frac{\nabla v \cdot \nabla}{v} \left\{ - \alpha uv + v\phi(u, v, w, h) + \Phi(w) \right\} - \int_{\Omega} \frac{|\nabla v|^2}{v^2} \cdot \left\{ - \alpha uv + v\phi(u, v, w, h) + \Phi(w) \right\}
\]
\[
= -2\alpha \int_{\Omega} \nabla u \cdot \nabla v - \alpha \int_{\Omega} \frac{u}{v} |\nabla v|^2 + \int_{\Omega} \frac{\Phi(u, v, w, h)}{v} |\nabla v|^2
\]
\[
+ 2 \int_{\Omega} \phi_u(u, v, w, h) \nabla u \cdot \nabla v + 2 \int_{\Omega} \phi_v(u, v, w, h) |\nabla v|^2
\]
\[
+ 2 \int_{\Omega} \phi_w(u, v, w, h) \nabla v \cdot \nabla w + 2 \int_{\Omega} \phi_h(u, v, w, h) \nabla v \cdot \nabla h
\]
\[
- \int_{\Omega} \frac{\Phi'(w)}{v^2} |\nabla v|^2 + 2 \int_{\Omega} \frac{\Phi'(w)}{v} \nabla v \cdot \nabla w \quad \text{for all } t \in (0, T_{\text{max}}).
\]
(3.6)

Here from (1.8) we know that
\[
\int_{\Omega} \frac{\phi(u, v, w, h)}{v} |\nabla v|^2 \leq -c_\phi \cdot \int_{\Omega} \frac{w}{v} |\nabla v|^2 + C_\phi \cdot \int_{\Omega} \frac{|\nabla v|^2}{v} \quad \text{for all } t \in (0, T_{\text{max}}),
\]
(3.8)

and that due to Young’s inequality, for all \( t \in (0, T_{\text{max}}) \) we have
\[
2 \int_{\Omega} \phi_u(u, v, w, h) \nabla u \cdot \nabla v \leq \frac{\alpha D_u}{2\xi} \int_{\Omega} \frac{|\nabla u|^2}{u} + \frac{2\xi}{\alpha D_u} \int_{\Omega} u \phi_u^2(u, v, w, h) |\nabla v|^2
\]
\[
\leq \frac{\alpha D_u}{2\xi} \int_{\Omega} \frac{|\nabla u|^2}{u} + \frac{2\xi C_\phi^2}{\alpha D_u} \int_{\Omega} \frac{|\nabla v|^2}{v}
\]
(3.9)

and
\[
2 \int_{\Omega} \phi_v(u, v, w, h) |\nabla v|^2 \leq 2C_\phi \int_{\Omega} \frac{|\nabla v|^2}{v} + 2C_\phi \int_{\Omega} |\nabla v|^2
\]
\[
\leq 2C_\phi \int_{\Omega} \frac{|\nabla v|^2}{v} + 2C_\phi \cdot \|v\|_{L^\infty(\Omega)} \int_{\Omega} \frac{|\nabla v|^2}{v}
\]
(3.10)

as well as
\[
2 \int_{\Omega} \phi_w(u, v, w, h) \nabla v \cdot \nabla w \leq \frac{c_\phi}{2} \int_{\Omega} \frac{w}{v} |\nabla v|^2 + \frac{2}{c_\phi} \int_{\Omega} \frac{v \phi_w^2(u, v, w, h)}{w} |\nabla w|^2
\]
\[
\leq \frac{c_\phi}{2} \int_{\Omega} \frac{w}{v} |\nabla v|^2 + \frac{4C_\phi^2}{c_\phi} \int_{\Omega} \frac{|\nabla w|^2}{w} + \frac{4C_\phi^2}{c_\phi} \int_{\Omega} \frac{v}{w} |\nabla w|^2
\]
\[
\leq \frac{c_\phi}{2} \int_{\Omega} \frac{w}{v} |\nabla v|^2 + \frac{4C_\phi^2 \cdot (\|v\|_{L^\infty(\Omega)} + 1)}{c_\phi} \int_{\Omega} \frac{|\nabla w|^2}{w}
\]
(3.11)
and
\[
2 \int_\Omega \phi_h(u, v, w, h) \nabla v \cdot \nabla h \leq C_\phi \int_\Omega \frac{\|\nabla v\|^2}{v} + \frac{1}{C_\phi} \int_\Omega v \phi_h^2(u, v, w, h) |\nabla h|^2
\]
\[
\leq C_\phi \int_\Omega \frac{\|\nabla v\|^2}{v} + 2C_\phi \int_\Omega |\nabla h|^2 + 2C_\phi \int_\Omega v |\nabla h|^2
\]
\[
\leq C_\phi \int_\Omega \frac{\|\nabla v\|^2}{v} + 2C_\phi \cdot (\|v\|_{L^\infty(\Omega)} + 1) \cdot \int_\Omega |\nabla h|^2. \quad (3.12)
\]

Moreover, combining Young’s inequality with (1.9) we can estimate
\[- \int_\Omega \Phi'(|w|) v^2 |\nabla v|^2 + 2 \int_\Omega \Phi'(w) v \nabla v \cdot \nabla w \leq \int_\Omega \Phi''(w) |\nabla w|^2
\]
\[
\leq C_\Phi \int_\Omega |\nabla w|^2 \quad \text{for all } t \in (0, T_{\text{max}}). \quad (3.13)
\]

As the second summand on the right of (3.6) is nonpositive, collecting (3.8)-(3.13) we thus infer (3.5) from (3.6).

Next, several expressions on the right-hand sides of (3.1) and (3.5) need to be controlled in modulus. Here the second integral on the right of (3.1) can in fact be absorbed by the dissipation rate appearing in the following inequality gained by means of a standard procedure.

**Lemma 3.3** For all \( t \in (0, T_{\text{max}}) \),
\[
\frac{d}{dt} \int_\Omega |\nabla h|^2 + D_h \int_\Omega |\Delta h|^2 \leq \frac{3C^2_g(\|v\|_{L^\infty(\Omega)})}{D_h} \cdot \left\{ \int_\Omega w^2 + \int_\Omega h^2 + |\Omega| \right\}. \quad (3.14)
\]

**Proof.** On testing the second equation in (1.3) by \( \Delta h \) and using Young’s inequality in a standard manner, we obtain
\[
\frac{1}{2} \frac{d}{dt} \int_\Omega |\nabla h|^2 + D_h \int_\Omega |\Delta h|^2 = - \int_\Omega g(u, v, w, h) \Delta h
\]
\[
\leq \frac{D_h}{2} \int_\Omega |\Delta h|^2 + \frac{1}{2D_h} \int_\Omega g^2(u, v, w, h) \quad \text{for all } t \in (0, T_{\text{max}}),
\]
which implies (3.14) due to the fact that by (1.7) and again Young’s inequality,
\[
g^2(u, v, w, h) \leq C^2_g(\|v\|_{L^\infty(\Omega)}) \cdot (w + h + 1)^2 \leq 3C^2_g(\|v\|_{L^\infty(\Omega)}) \cdot (w^2 + h^2 + 1)
\]
in \( \Omega \times (0, T_{\text{max}}). \)

The second last summand in (3.5), referring to the component \( w \) with evolution governed by an ODE only, apparently cannot be expected to be absorbed by some suitable dissipation rate. The following lemma indicates that at least some exponential control thereof will eventually be possible.
Lemma 3.4 We have
\[
\frac{d}{dt} \int_\Omega \frac{\nabla w}{w} \leq (\beta + 1) \int_\Omega \frac{\nabla u}{u} + \int_\Omega \frac{w}{v} \nabla v^2 + \left\{ 3C_\psi(\|v\|_{L^\infty(\Omega)}) + C_\psi(\|v\|_{L^\infty(\Omega)}) + \|v\|_{L^\infty(\Omega)}C_\psi^2(\|v\|_{L^\infty(\Omega)}) + 1 \right\} \int_\Omega \frac{\nabla w}{w}
\]
\[
+ \int_\Omega \frac{w^2 + C_\psi^{\frac{4}{1+2\gamma}}(\|v\|_{L^\infty(\Omega)}) \cdot \int_\Omega |\nabla h|^{\frac{4}{1+2\gamma}}}{w} \quad \text{for all } t \in (0, T_{\text{max}}).
\]
(3.15)

Proof. Using the fourth equation in (1.3), we compute
\[
\frac{d}{dt} \int_\Omega \frac{\nabla w}{w} = 2 \int_\Omega \frac{\nabla w}{w} \cdot \nabla \left\{ \beta u + w \psi(u, v, w, h) \right\} - \int_\Omega \frac{\nabla w}{w^2} \cdot \left\{ \beta u + w \psi(u, v, w, h) \right\}
\]
\[
= 2\beta \int_\Omega \frac{1}{w} \nabla u \cdot \nabla w + \int_\Omega \frac{\psi(u, v, w, h)}{w} \nabla w^2 - \beta \int_\Omega \frac{u}{w^2} |\nabla w|^2
\]
\[
+ 2 \int_\Omega \psi_u(u, v, w, h) \nabla u \cdot \nabla w + 2 \int_\Omega \psi_v(u, v, w, h) \nabla v \cdot \nabla w
\]
\[
+ 2 \int_\Omega \psi_w(u, v, w, h) |\nabla w|^2 + 2 \int_\Omega \psi_h(u, v, w, h) \nabla w \cdot \nabla h \quad \text{for all } t \in (0, T_{\text{max}})
\]
(3.16)

where by Young’s inequality,
\[
2\beta \int_\Omega \frac{1}{w} \nabla u \cdot \nabla w - \beta \int_\Omega \frac{u}{w^2} |\nabla w|^2 \leq \beta \int_\Omega \frac{\nabla u^2}{u} \quad \text{for all } t \in (0, T_{\text{max}}),
\]
(3.17)

and where by (1.10),
\[
\int_\Omega \frac{\psi(u, v, w, h)}{w} |\nabla w|^2 \leq C_\psi(\|v\|_{L^\infty(\Omega)}) \cdot \int_\Omega \frac{|\nabla w|^2}{w} \quad \text{for all } t \in (0, T_{\text{max}}).
\]
(3.18)

Apart from that, combining (1.10) with Young’s inequality we see that
\[
2 \int_\Omega \psi(u, v, w, h) \nabla u \cdot \nabla w \leq \int_\Omega \frac{\nabla u^2}{u} + \int_\Omega \psi_u^2(u, v, w, h)|\nabla w|^2
\]
\[
\leq \int_\Omega \frac{\nabla u^2}{u} + C_\psi^2(\|v\|_{L^\infty(\Omega)}) \cdot \int_\Omega \frac{|\nabla w|^2}{w}
\]
(3.19)

and
\[
2 \int_\Omega \psi(v, u, v, w, h) \nabla v \cdot \nabla w \leq \int_\Omega \frac{w}{v} |\nabla v|^2 + \int_\Omega \frac{v}{w} \psi_v^2(u, v, w, h)|\nabla w|^2
\]
\[
\leq \int_\Omega \frac{w}{v} |\nabla v|^2 + \|v\|_{L^\infty(\Omega)}C_\psi^2(\|v\|_{L^\infty(\Omega)}) \cdot \int_\Omega \frac{|\nabla w|^2}{w}
\]
(3.20)

as well as
\[
2 \int_\Omega \psi_w(u, v, w, h) |\nabla w|^2 \leq 2C_\psi(\|v\|_{L^\infty(\Omega)}) \cdot \int_\Omega \frac{|\nabla w|^2}{w}
\]
(3.21)
and
\[
2 \int_{\Omega} \psi_h(u,v,w,h) \nabla w \cdot \nabla h \leq \int_{\Omega} \frac{|\nabla w|^2}{w} + \int_{\Omega} w \psi^2_h(u,v,w,h)|\nabla h|^2
\leq \int_{\Omega} \frac{|\nabla w|^2}{w} + C^2_{\psi}(\|v\|_{L^\infty(\Omega)}) \cdot \int_{\Omega} w^{1-2\gamma}|\nabla h|^2
\leq \int_{\Omega} \frac{|\nabla w|^2}{w} + \int_{\Omega} w^2 + C^{1+\gamma}_{\psi}(\|v\|_{L^\infty(\Omega)}) \cdot \int_{\Omega} |\nabla h|^{\frac{4}{1+2\gamma}} \tag{3.22}
\]
for all \( t \in (0, T_{max}) \). Inserting (3.17)-(3.22) into (3.16) directly yields (3.15). \( \square \)

A final minor ingredient to our quasi-energy inequality is addressed in the following.

**Lemma 3.5** If \( \eta > 0 \), then
\[
\frac{d}{dt} \int_{\Omega} w^2 \leq \eta \int_{\Omega} u^2 + \left\{ \frac{\beta^2}{2\eta} + 2C_{\psi}(\|v\|_{L^\infty(\Omega)}) \right\} \cdot \int_{\Omega} w^2 \quad \text{for all } t \in (0, T_{max}). \tag{3.23}
\]

**Proof.** As
\[
\frac{1}{2} \frac{d}{dt} \int_{\Omega} w^2 = \beta \int_{\Omega} uw + \int_{\Omega} w^2 \psi(u,v,w,h) \quad \text{for all } t \in (0, T_{max})
\]
by (1.3), this follows by observing that
\[
\beta \int_{\Omega} uw \leq \frac{\eta}{2} \int_{\Omega} u^2 + \frac{\beta^2}{2\eta} \int_{\Omega} w^2 \quad \text{for all } t \in (0, T_{max})
\]
due to Young’s inequality, and that
\[
\int_{\Omega} w^2 \psi(u,v,w,h) \leq C_{\psi}(\|v\|_{L^\infty(\Omega)}) \cdot \int_{\Omega} w^2 \quad \text{for all } t \in (0, T_{max})
\]
according to (1.10). \( \square \)

As a last preparation, let us make use of appropriate parabolic regularization features to estimate terms of the form appearing in the last integral from (3.15).

**Lemma 3.6** Let \( q \in [1, 4) \). Then there exists \( \theta = \theta(q) \in (0, 1) \) with the property that for all \( T > 0 \) one can find \( C(q,T) > 0 \) such that
\[
\int_{\Omega} |\nabla h|^q \leq C(q,T) \cdot \left\{ \int_{\Omega} |\Delta h|^2 \right\}^\theta \quad \text{for all } t \in (0, \hat{T}), \tag{3.24}
\]
where again \( \hat{T} := \min\{T, T_{max}\} \).

**Proof.** We first note that according to (1.7), Lemma 2.2 and Lemma 2.3 we can fix positive constants \( c_1(T), c_2(T) \) and \( c_3(T) \) such that
\[
|g(u,v,w,h)| \leq c_1(T) \cdot (w + h + 1) \quad \text{in } \Omega \times (0, \hat{T}), \tag{3.25}
\]
and that
\[
\int_{\Omega} w \leq c_2(T) \quad \text{and} \quad \int_{\Omega} h \leq c_3(T) \quad \text{for all } t \in (0, T_{\text{max}}),
\] (3.26)
and observe that since \( q < 4 \) it is possible to choose \( r \equiv r(q) \in (1, 2) \) suitably close to 2 satisfying \( r > q - 2 \). In the Duhamel representation
\[
\nabla h(\cdot, t) = \nabla e^{t \Delta} h_0 + \int_{0}^{t} \nabla e^{(t-s) \Delta} g(u(\cdot, s), h(\cdot, s), v(\cdot, s), w(\cdot, s)) ds, \quad t \in (0, T_{\text{max}}),
\]
we may then use standard \( L^p-L^q \) estimates for the Neumann heat semigroup \( (e^{\sigma \Delta})_{\sigma \geq 0} \) (Lemma 1.3]) to find \( c_4(T) > 0 \) such that for all \( t \in (0, \hat{T}) \),
\[
\|\nabla h(\cdot, t)\|_{L^r(\Omega)} \leq c_4(T) \|h_0\|_{W^{1,\infty}(\Omega)} + c_4(T) \int_{0}^{t} (t-s)^{-\frac{3}{2} + \frac{1}{r}} \|g(u(\cdot, s), h(\cdot, s), v(\cdot, s), w(\cdot, s))\|_{L^1(\Omega)} ds.
\]
As (3.25) and (3.26) warrant that
\[
\|g(u(\cdot, s), h(\cdot, s), v(\cdot, s), w(\cdot, s))\|_{L^1(\Omega)} \leq c_5(T) := c_1(T) \cdot \left( c_2(T) + c_3(T) + |\Omega| \right)
\]
for all \( s \in (0, \hat{T}) \), this readily entails that
\[
\|\nabla h(\cdot, t)\|_{L^r(\Omega)} \leq c_6(T) := c_4(T) \|h_0\|_{W^{1,\infty}(\Omega)} + \frac{c_4(T)c_5(T) \cdot T^{\frac{1}{r} - \frac{3}{2}}}{\frac{1}{r} - \frac{3}{2}} \quad \text{for all } t \in (0, \hat{T})
\] (3.27)
with \( c_6(T) \) being finite due to our restriction \( r < 2 \). Now since a combination of the Gagliardo-Nirenberg inequality with elliptic regularity theory yields \( c_7 > 0 \) such that
\[
\|\nabla h(\cdot, t)\|_{L^q(\Omega)} \leq c_7 \|\Delta h(\cdot, t)\|^{\frac{q-r}{r}}_{L^r(\Omega)} \|\nabla h(\cdot, t)\|_{L^r(\Omega)} \quad \text{for all } t \in (0, T_{\text{max}}),
\]
from (3.27) we immediately obtain (3.24) with \( \theta \equiv \theta(q) := \frac{q-r}{2} \) fulfilling \( \theta \in (0, 1) \) according to the inequality \( r > q - 2 \).

We can now proceed to our detection of an energy-like structure in (1.3), as expressed in the following lemma.

**Lemma 3.7** Let \( T > 0 \). Then there exist \( a = a(T) > 0, b > 0 \) and \( C = C(T) > 0 \) such that for
\[
\mathcal{F}(t) := \int_{\Omega} u(\cdot, t) \ln u(\cdot, t) + a \int_{\Omega} \nabla h(\cdot, t)^2 + \frac{\xi}{2} \int_{\Omega} \frac{\nabla v(\cdot, t)^2}{v(\cdot, t)} + b \int_{\Omega} \frac{\nabla w(\cdot, t)^2}{w(\cdot, t)} + \int_{\Omega} w^2(\cdot, t), \quad t \in [0, \hat{T}),
\] (3.28)
and
\[
\mathcal{D}(t) := \int_{\Omega} \frac{\nabla u(\cdot, t)^2}{u(\cdot, t)} + \int_{\Omega} \nabla h(\cdot, t)^2, \quad t \in (0, \hat{T}),
\] (3.29)
we have
\[
\frac{d}{dt} \mathcal{F}(t) + \frac{1}{C(T)} \cdot \mathcal{D}(t) \leq C(T) \cdot \mathcal{F}(t) + C(T) \quad \text{for all } t \in (0, \hat{T}),
\] (3.30)
where \( \hat{T} := \min\{T, T_{\text{max}}\} \).
Proof. Thanks to Lemma 2.3 and Lemma 2.2, we can fix positive constants $c_1(T), c_2(T)$ and $c_3(T)$ such that

$$\int_{\Omega} u \leq c_1(T) \quad \text{and} \quad \int_{\Omega} w \leq c_2(T) \quad \text{for all } t \in (0, \hat{T})$$

(3.31)
as well as

$$\|v(\cdot, t)\|_{L^\infty(\Omega)} \leq c_3(T) \quad \text{for all } t \in (0, \hat{T}).$$

(3.32)

Then in accordance with the Gagliardo-Nirenberg inequality, choosing $c_4 > 0$ such that

$$\int_{\Omega} \varphi^4 \leq c_4 \cdot \left\{ \int_{\Omega} |\nabla \varphi|^2 \right\} \cdot \left\{ \int_{\Omega} \varphi^2 \right\} + c_4 \cdot \left\{ \int_{\Omega} \varphi^2 \right\}^2 \quad \text{for all } \varphi \in W^{1,2}(\Omega),$$

(3.33)

we define

$$\eta \equiv \eta(T) := \frac{D_u}{2c_1(T)c_4}$$

(3.34)

and take $a \equiv a(T) > 0$ large enough fulfilling

$$\frac{x^2}{2\eta} \leq \frac{aDh}{4}. $$

(3.35)

Finally picking $b > 0$ small such that both

$$b(\beta + 1) \leq \frac{D_u}{4}$$

(3.36)

and

$$b \leq \frac{\xi c_2}{4\alpha}$$

(3.37)

hold, we let $\mathcal{F}$ and $\mathcal{D}$ be as determined through (3.28) and (3.29) and claim that then (3.30) is valid with some suitably large $C(T) > 0$. To this end, we first take an appropriate linear combination of the inequalities provided by Lemma 3.1, Lemma 3.3, Lemma 3.2, Lemma 3.4 and Lemma 3.5 which when applied to our particular value of $\eta$ namely show that

$$\frac{d}{dt} \mathcal{F}(t) \leq \left\{- D_u \int_{\Omega} \frac{|\nabla u|^2}{u} + \xi \int_{\Omega} \nabla u \cdot \nabla v + \frac{\chi^2}{2\eta} \int_{\Omega} |\Delta h|^2 + \eta \int_{\Omega} u^2 + C_f(c_3(T)) \cdot \int_{\Omega} u \ln u + 2C_f(c_3(T)) \cdot c_1(T) \right. $$

$$+ \left. \frac{C^2_2(c_3(T))}{2\eta} \cdot \int_{\Omega} w^2 + C_f(c_3(T)) \cdot c_1(T) + |\Omega| \cdot C_f(c_3(T)) + |\Omega| \cdot \|f_0 \cdot \ln\|_{L^\infty((0,1))} \right\}$$

(3.38)
\[ + \left\{ - aD_h \int_\Omega |\Delta h|^2 + \frac{3aC_g^2(c_3(T))}{D_h} \cdot \int_\Omega u^2 + \frac{3aC_g^2(c_3(T))}{D_h} \cdot \int_\Omega h^2 + \frac{3a|\Omega|C_g^2(c_3(T))}{D_h} \right\} \\
+ \left\{ - \frac{\xi c_\phi}{4\alpha} \int_\Omega \frac{\nabla^2 v}{v} \cdot |\nabla v|^2 - \xi \int_\Omega \nabla u \cdot \nabla v \\
+ \frac{D_u}{4} \int_\Omega |\nabla u|^2 + \frac{\xi}{2\alpha} \cdot \left\{ 2C_\phi \cdot (2c_3(T) + 1) + \frac{2\xi C_\phi^2}{aD_u} \right\} \cdot \int_\Omega |\nabla v|^2 \\
+ \frac{\xi}{2\alpha} \cdot \left\{ \frac{4C_\phi^2(c_3(T) + 1) + C_\Phi}{c_\phi} \right\} \int_\Omega \frac{|\nabla w|^2}{w} + \frac{\xi C_\phi \cdot (c_3(T) + 1)}{\alpha} \int_\Omega |\nabla h|^2 \right\} \\
+ \left\{ b(\beta + 1) \int_\Omega \frac{|\nabla u|^2}{u} + b \int_\Omega \frac{w}{v} |\nabla v|^2 \\
+ b \cdot \left\{ \frac{3C_\phi(c_3(T)) + C_\phi^2(c_3(T)) + c_3(T)C_\phi^2(c_3(T)) + 1}{\eta} \right\} \cdot \int_\Omega |\nabla w|^2 \\
+ \frac{b}{\eta} \cdot \int_\Omega u^2 + \frac{\beta^2}{\eta} + 2C_\psi(c_3(T)) \right\} \cdot \int_\Omega u^2 \right\} \\
= \left\{ - \frac{3D_u}{4} + b(\beta + 1) \right\} \cdot \int_\Omega \frac{|\nabla u|^2}{u} + 2\eta \int_\Omega u^2 \\
+ \left\{ -(aD_h + \frac{\chi^2}{2\eta}) \right\} \cdot \int_\Omega |\Delta h|^2 + c_5(T) \int_\Omega |\nabla h|^\frac{4}{1+2\gamma} \\
+ \left\{ - \frac{\xi c_\phi}{4\alpha} + b \right\} \cdot \int_\Omega \frac{w}{v} |\nabla v|^2 \\
+ c_6(T) \int_\Omega u \ln u + c_7(T) \int_\Omega \frac{|\nabla v|^2}{v} + c_8(T) \int_\Omega \frac{|\nabla w|^2}{w} + c_9(T) \int_\Omega u^2 \\
+ c_{10}(T) \int_\Omega |\nabla h|^2 + c_{11}(T) \int_\Omega h^2 + c_{12}(T) \right\} \text{ for all } t \in (0, \hat{T}) \quad (3.38) \]

with obvious definitions of \(c_i(T)\) for \(i \in \{5, \ldots, 12\}\), where we have made use of a favorable cancellation in some contributions stemming from the haptotactic interaction.

Now employing (3.33) we see that due to (3.31) and (3.34) we have

\[
2\eta \int_\Omega u^2 \leq \frac{c_4\eta}{2} \cdot \left\{ \int_\Omega \frac{|\nabla u|^2}{u} \right\} \cdot \left\{ \int_\Omega u \right\} + 2c_4 \eta \cdot \left\{ \int_\Omega u \right\}^2 \\
\leq \frac{c_1(T)c_4 \eta}{2} \int_\Omega \frac{|\nabla u|^2}{u} + 2c_1^2(T)c_4 \eta \\
= \frac{D_u}{4} \int_\Omega \frac{|\nabla u|^2}{u} + 2c_1^2(T)c_4 \eta \quad \text{for all } t \in (0, \hat{T}), \quad (3.39)
\]

whereas Lemma 3.6 says that as \(\frac{4}{1+2\gamma} < 4\), there exist \(\theta \in (0, 1)\) and \(c_{13}(T) > 0\) such that

\[
c_5(T) \int_\Omega |\nabla h|^\frac{4}{1+2\gamma} \leq c_{13}(T) \cdot \left\{ \int_\Omega |\Delta h|^2 \right\}^\theta \quad \text{for all } t \in (0, \hat{T}),
\]

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whence by Young’s inequality,

\[ c_5(T) \int_\Omega |\nabla h|^\frac{4}{1+2\gamma} \leq \frac{aD_h}{4} \int_\Omega |\Delta h|^2 + c_{14}(T) \quad \text{for all } t \in (0, \hat{T}) \]  

(3.40)

with some \( c_{14}(T) > 0 \). Since moreover the Poincaré inequality provides \( c_{15}(T) > 0 \) satisfying

\[ c_{11}(T) \int_\Omega h^2 \leq c_{15}(T) \int_\Omega |\nabla h|^2 + c_{15}(T) \quad \text{for all } t \in (0, \hat{T}), \]

thanks to the restrictions in (3.35), (3.36) and (3.37) we conclude from (3.38), (3.39) and (3.40) that there exists \( c_{16}(T) > c_6(T) \) such that

\[
\begin{align*}
\frac{d}{dt} F(t) &\leq -\frac{D_u}{4} \int_\Omega \frac{\nabla u}{u} - \frac{aD_h}{2} \int_\Omega |\Delta h|^2 \\
& \quad + c_6(T) \int_\Omega u \ln u + c_{16}(T) \cdot \left\{ a \int_\Omega |\nabla h|^2 + \frac{\xi}{2\alpha} \int_\Omega \frac{|\nabla v|^2}{v} + b \int_\Omega \frac{|\nabla w|^2}{w} + \int_\Omega w^2 \right\} + c_{16}(T)
\end{align*}
\]

for all \( t \in (0, \hat{T}) \). Using that \( y \ln y \geq -\frac{1}{e} \) for all \( y > 0 \) and thus \( \int_\Omega u \ln u \geq -\frac{\|\Omega\|}{e} \) for all \( t \in (0, T_{max}) \), from this we finally obtain that for all \( t \in (0, \hat{T}) \),

\[
\frac{d}{dt} F(t) + \min \left\{ \frac{D_u}{4}, \frac{aD_h}{2} \right\} \cdot D(t) \leq c_{16}(T) \cdot F(t) - \left( c_{16}(T) - c_6(T) \right) \cdot \int_\Omega u \ln u + c_{16}(T) \\
\leq c_{16}(T) \cdot F(t) + \frac{\|\Omega\| \cdot (c_{16}(T) - c_6(T))}{e} + c_{16}(T),
\]

as intended. \( \square \)

Upon integration, the latter implies several \textit{a priori} estimates, significantly going beyond those from Lemma 2.2 and Lemma 2.3, among which we explicitly state only those three inequalities that will be referred to later on.

**Lemma 3.8** For all \( T > 0 \) there exists \( C(T) > 0 \) such that again writing \( \hat{T} := \min\{T, T_{max}\} \) we have

\[ \int_\Omega u(\cdot, t) \ln u(\cdot, t) \leq C(T) \quad \text{for all } t \in (0, \hat{T}) \]  

(3.41)

and

\[ \int_\Omega |\nabla h(\cdot, t)|^2 \leq C(T) \quad \text{for all } t \in (0, \hat{T}) \]  

(3.42)

as well as

\[ \int_0^{\hat{T}} \int_\Omega |\Delta h|^2 \leq C(T). \]  

(3.43)

**Proof.**  Upon integrating (3.30) in time, we can find \( c_1(T) > 0 \) such that with \( F \) and \( D \) taken from (3.28) and (3.29) we have

\[ F(t) \leq c_1(T) \quad \text{for all } t \in (0, \hat{T}) \quad \text{and} \quad \int_0^{\hat{T}} D(t) dt \leq c_1(T). \]
Once more using that $y \ln y \geq -\frac{1}{e}$ for $y > 0$, from this we readily obtain the claimed inequalities as particular consequences.

As an immediate consequence, let us add the following observation about regularity of $h$.

**Corollary 3.9** Let $p \geq 1$ and $T > 0$. Then there exists $C(p,T) > 0$ such that with $\widehat{T} := \min\{T,T_{\text{max}}\}$,

$$\int_{\Omega} h^p(\cdot, t) \leq C(p,T) \quad \text{for all } t \in (0, \widehat{T}).$$

(3.44)

**Proof.** As $W^{1,2}(\Omega) \hookrightarrow L^p(\Omega)$, combining (2.6) with (3.42) immediately yields (3.44).

□

4 \hspace{1cm} L^\infty \text{ bounds for } u

In this section we intend to make use of the information from Lemma 3.8 in order to finally achieve an a priori bound for the quantity $z$ from (2.1), and hence for $u$, with respect to the norm in $L^\infty(\Omega)$. Here a key role will be played by the following implication of the estimate (3.41) on a Gagliardo-Nirenberg-type interpolation, as expressed in the following.

**Lemma 4.1** Let $p > 1$ and $T > 0$. Then for all $\eta > 0$ one can find $C(\eta,p,T) > 0$ such that

$$\int_{\Omega} z^{p+1} \leq \eta \int_{\Omega} z^{p-2} |\nabla z|^2 + C(\eta,p,T) \quad \text{for all } t \in (0, \widehat{T})$$

(4.1)

with $\widehat{T} := \min\{T,T_{\text{max}}\}$.

**Proof.** This follows in a standard manner from the boundedness property of $z$ in $L \log L(\Omega)$ as implied by Lemma 3.8 and Lemma 2.2 by means of a refined interpolation inequality of Gagliardo-Nirenberg type, the latter going back to [3] and extended to a version applicable to the present setting in [45, Lemma A.5] (for details, see e.g. [45, p.800]).

□

In order to make appropriate use of this, let us perform another well-established testing procedure to (2.2), a basic outcome of which is the following.

**Lemma 4.2** Let $T > 0$. Then there exists $C(T) > 0$ such that for all $p \geq 2$ and all $t \in (0, \widehat{T})$ with $\widehat{T} := \min\{T,T_{\text{max}}\}$,

$$\frac{d}{dt} \int_{\Omega} e^{\lambda v} z^p + \frac{p(p-1)D u}{2} \int_{\Omega} z^{p-2} |\nabla z|^2 \leq C(T) \cdot p \cdot \left\{ \int_{\Omega} z^p + \int_{\Omega} w^p + 1 \right\}$$

$$+ C(T) \cdot p^2 \cdot \int_{\Omega} z^p |\nabla h|^2.$$  (4.2)
Proof. By means of (2.2), we obtain
\[
\frac{d}{dt} \int_\Omega e^{\lambda u} z^p = p \int_\Omega e^{\lambda u} z^{p-1} \cdot \left\{ D_u e^{\lambda u} \nabla \cdot (e^{\lambda u} \nabla z) - \chi e^{\lambda u} \nabla \cdot (z e^{\lambda u} \nabla h) + e^{-\lambda u} f(z e^{\lambda u}, h, v, w) \right\} + \lambda \int_\Omega e^{\lambda u} z^p \cdot \left\{ - \alpha v e^{\lambda u} z + v \phi(z e^{\lambda u}, h, v, w) + \Phi(w) \right\}
\]
\[= -p(p-1)D_u \int_\Omega e^{\lambda u} z^{p-2} |\nabla z|^2 + p(p-1)\chi \int_\Omega e^{\lambda u} z^{p-1} \nabla z \cdot \nabla h + p \int_\Omega z^{p-1} f(z e^{\lambda u}, h, v, w) - \alpha \int_\Omega v e^{2\lambda u} z^{p-1} + \lambda \int_\Omega v e^{\lambda u} z^p \phi(z e^{\lambda u}, h, v, w) + \lambda \int_\Omega v e^{\lambda u} z^p \Phi(w) \]  
(4.3)
for all \(t \in (0, T_{\text{max}})\), where by Young’s inequality,
\[
p(p-1)\chi \int_\Omega e^{\lambda u} z^{p-1} \nabla z \cdot \nabla h \leq \frac{p(p-1)D_u}{2} \int_\Omega e^{\lambda u} z^{p-2} |\nabla z|^2 + \frac{p(p-1)\chi^2}{2D_u} \int_\Omega e^{\lambda u} z^p |\nabla h|^2 \leq \frac{p(p-1)D_u}{2} \int_\Omega e^{\lambda u} z^{p-2} |\nabla z|^2 + \frac{p^2\chi^2}{2D_u} e^{\lambda c_1(T)} \int_\Omega z^p |\nabla h|^2 \]  
(4.4)
for all \(t \in (0, \hat{T})\), with \(c_1(T) := \|v\|_{L^\infty(\Omega \times (0, \hat{T}))}\) being finite according to Lemma 2.2. Furthermore, (4.6) and Young’s inequality warrant that for all \(t \in (0, \hat{T})\),
\[
p \int_\Omega z^{p-1} f(z e^{\lambda u}, h, v, w) \leq PC_f(c_1(T)) \cdot \left\{ \int_\Omega e^{\lambda u} z^p + \int_\Omega z^{p-1} w + \int_\Omega z^{p-1} \right\} \leq PC_f(c_1(T)) \cdot \left\{ e^{\lambda c_1(T)} \int_\Omega z^p + \int_\Omega z^p + \int_\Omega z^p + |\Omega| \right\}, \]
(4.5)
while from (1.8) and (1.9) we know that
\[
\lambda \int_\Omega v e^{\lambda u} \phi(z e^{\lambda u}, h, v, w) \leq \lambda c_1(T) e^{\lambda c_1(T)} \quad \text{for all } t \in (0, \hat{T}) \]
(4.6)
and that
\[
\lambda \int_\Omega e^{\lambda u} z^p \Phi(w) \leq \lambda e^{\lambda c_1(T)} \cdot C_\Phi \int_\Omega z^p \quad \text{for all } t \in (0, \hat{T}). \]
(4.7)
As clearly \(e^{\lambda u} \geq 1\), by nonnegativity of \(\alpha\) we therefore infer (4.2) from (4.3) when combined with (4.4), (4.5), (4.6) and (4.7). \(\square\)

Here a suitable control of the crucial rightmost summand in (4.2) will rely, besides on Lemma 1.1, also on the following statement which can be viewed as partially generalizing Lemma 3.5.

Lemma 4.3 Let \(p \geq 1\) and \(T > 0\). Then writing \(\hat{T} := \min\{T, T_{\text{max}}\}\) and \(\tau := \frac{1}{2} \hat{T}\), with some \(C(p, T) > 0\) we have
\[
\int_\Omega w^p(\cdot, t) \leq C(p, T) \int_\tau^t \int_\Omega z^p + C(p, T) \quad \text{for all } t \in (\tau, \hat{T}). \]
(4.8)
Proof. Choosing \( c_1(T) > 0 \) large enough fulfilling \( v \leq c_1(T) \) in \( \Omega \times (0, \hat{T}) \) according to Lemma 2.2 equation (1.3), and due to Young’s inequality and (1.10) we can estimate

\[
\frac{d}{dt} \int_{\Omega} w^p = p \beta \int_{\Omega} \lambda \nu \, w^{p-1} \, z + p \int_{\Omega} w^p \psi(e^{\lambda \nu \, v}, h, v, w) \\
\leq p \beta e^{\lambda c_1(T)} \int_{\Omega} w^{p-1} \, z + p C \psi(c_1(T)) \cdot \int_{\Omega} w^p \\
\leq p \beta e^{\lambda c_1(T)} \cdot \{ \int_{\Omega} w^p + \int_{\Omega} z^p \} + p C \psi(c_1(T)) \cdot \int_{\Omega} w^p \quad \text{for all } t \in (0, \hat{T}),
\]

so that with some \( c_2(p, T) > 0 \) we have

\[
\frac{d}{dt} \int_{\Omega} w^p \leq c_2(p, T) \int_{\Omega} w^p + c_2(T) \int_{\Omega} z^p \quad \text{for all } t \in (0, \hat{T}).
\]

An integration thereof shows that

\[
\int_{\Omega} w^p(\cdot, t) \leq e^{c_2(p, T)(t-\tau)} \cdot \int_{\Omega} w^p(\cdot, \tau) + c_2(T) \int_{\tau}^t e^{c_2(p, T)(t-s)} \cdot \int_{\Omega} z^p(\cdot, s)ds \\
\leq e^{c_2(p, T)T} \cdot \int_{\Omega} w^p(\cdot, \tau) + c_2(T) e^{c_2(p, T)T} \cdot \int_{\tau}^t \int_{\Omega} z^p \quad \text{for all } t \in (\tau, \hat{T})
\]

and hence implies (4.8). □

We can thereby use Lemma 4.2 along with Lemma 4.1 to derive the following \( L^p \) estimate for \( z \), at this stage yet involving bounds possibly depending on the finite number \( p \geq 2 \).

Lemma 4.4 Let \( p \geq 2 \) and \( T > 0 \). Then there exists \( C(p, T) > 0 \) such that

\[
\int_{\Omega} z^p(\cdot, t) \leq C(p, T) \quad \text{for all } t \in (0, \hat{T}),
\]

where again \( \hat{T} := \min\{T, T_{\text{max}}\} \).

Proof. From Lemma 4.2 we obtain \( c_1(p) > 0 \) and \( c_2(p, T) > 0 \) such that

\[
\frac{d}{dt} \int_{\Omega} e^{\lambda \nu \, z^p} + c_1(p) \int_{\Omega} z^{p-2} |\nabla z|^2 \leq c_2(p, T) \int_{\Omega} e^{\lambda \nu \, z^p} + c_2(p, T) \cdot \left\{ \int_{\Omega} w^p + 1 \right\} + c_2(p, T) \int_{\Omega} z^p |\nabla h|^2 \quad \text{for all } t \in (0, \hat{T}),
\]

again because \( e^{\lambda \nu \, z} \geq 1 \). Here since Lemma 3.8 provides \( c_3(T) > 0 \) such that

\[
\int_{\Omega} |\nabla h|^2 \leq c_3(T) \quad \text{for all } t \in (0, \hat{T}),
\]
by means of Young’s inequality and the Gagliardo-Nirenberg inequality we infer that with some $c_4(p, T) > 0$ we have

$$c_2(p, T) \int_{\Omega} z^p |\nabla h|^2 \leq c_2(p, T) \int_{\Omega} z^{p+1} + c_2(p, T) \int_{\Omega} |\nabla h|^{2(p+2)}$$

$$\leq c_2(p, T) \int_{\Omega} z^{p+1} + c_4(p, T) \cdot \left\{ \int_{\Omega} |\Delta h|^{p+1} \right\} \cdot \left\{ \int_{\Omega} |\nabla h|^2 \right\}^{\frac{p+1}{2}}$$

$$\leq c_2(p, T) \int_{\Omega} z^{p+1} + (c_3(T))^{\frac{p+1}{2}} c_4(p, T) \int_{\Omega} |\Delta h|^{p+1} \quad \text{for all } t \in (0, \hat{T}).$$

Therefore, \((4.10)\) shows that there exists $c_5(p, T) > 0$ such that $y(t) := \int_{\Omega} e^{\lambda v(\cdot, t) z^p(\cdot, t)}, t \in [0, T_{\max})$, satisfies

$$y'(t) + c_1(p) \int_{\Omega} z^{p-2} |\nabla z|^2 \leq c_2(p, T) y(t) + c_5(p, T) \cdot \left\{ \int_{\Omega} z^{p+1} + \int_{\Omega} w^{p+1} + \int_{\Omega} |\Delta h|^{p+1} + 1 \right\}$$

for all $t \in (0, \hat{T})$ and thus, upon integration,

$$y(t) + c_1(p) \int_{\tau}^t \int_{\Omega} z^{p-2} |\nabla z|^2$$

$$\leq y(t) + c_1(p) \int_{\tau}^t e^{c_2(p, T)(t-s)} \cdot \int_{\Omega} z^{p-2} (\cdot, s) |\nabla z(\cdot, s)|^2 \, ds$$

$$\leq y(t) + c_1(p) e^{c_2(p, T)(t-\tau)}$$

$$+ c_5(p, T) \int_{\tau}^t e^{c_2(p, T)(t-s)} \cdot \left\{ \int_{\Omega} z^{p+1} (\cdot, s) + \int_{\Omega} w^{p+1} (\cdot, s) + \int_{\Omega} |\Delta h(\cdot, s)|^{p+1} + 1 \right\} \, ds$$

$$\leq y(t) e^{c_2(p, T) T}$$

$$+ c_5(p, T) e^{c_2(p, T) T} \cdot \left\{ \int_{\tau}^t \int_{\Omega} z^{p+1} + \int_{\tau}^t \int_{\Omega} w^{p+1} + \int_{\tau}^t \int_{\Omega} |\Delta h|^{p+1} + T \right\}$$

\((4.12)\)

for all $t \in (\tau, \hat{T})$, where again we have set $\tau := \frac{t}{2}$. As thus $\tau$ is positive, a well-known result on maximal Sobolev regularity in the parabolic subproblem of \((1.3)\) satisfied by $h$ \((1.4)\) becomes applicable so as to yield $c_6(p, T) > 0$ satisfying

$$\int_{\tau}^t \int_{\Omega} |\Delta h|^{p+1} \leq c_6(p, T) \int_{\tau}^t \int_{\Omega} |g(e^{\lambda v z, h, v, w})|^{p+1} + c_6(p, T)$$

$$\leq c_6(p, T) \cdot (p + 1) C_{\gamma}^{p+1} (\|v\|_{L^\infty(\Omega \times (0, \hat{T}))}) \cdot \int_{\tau}^t \int_{\Omega} (w^{p+1} + h^{p+1} + 1) + c_6(p, T)$$

for all $t \in (\tau, \hat{T})$ because of \((1.7)\). Since Corollary 3.9 and Lemma 4.3 provide $c_7(p, T) > 0$ and $c_8(p, T) > 0$ such that

$$\int_{\tau}^t \int_{\Omega} h^{p+1} \leq c_7(p, T) \quad \text{for all } t \in (\tau, \hat{T})$$

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and that
\[ \int_\tau^t \int_\Omega w^{p+1} \leq c_8(p, T) \cdot \left\{ \int_\tau^t \int_\Omega z^{p+1} + 1 \right\} \quad \text{for all } t \in (\tau, \hat{T}), \]
this means that with some \( c_9(p, T) > 0 \) we have
\[ \int_\tau^T \int_\Omega |\Delta h|^{p+1} \leq c_9(p, T) \cdot \left\{ \int_\tau^t \int_\Omega z^{p+1} + 1 \right\} \quad \text{for all } t \in (\tau, \hat{T}), \]
so that from (4.12) we infer the existence of \( c_{10}(p, T) > 0 \) satisfying
\[ y(t) + c_1(p) \int_\tau^t \int_\Omega z^{p-2} |\nabla z|^2 \leq c_{10}(p, T) \int_\tau^t \int_\Omega z^{p+1} + c_{10}(p, T) \quad \text{for all } t \in (\tau, \hat{T}). \quad (4.13) \]
We now employ Lemma 4.1 to see that with some \( c_{11}(p, T) > 0, \)
\[ c_{10}(p, T) \int_\tau^t \int_\Omega z^{p+1} \leq c_1(p) \int_\tau^t \int_\Omega z^{p-2} |\nabla z|^2 + c_{11}(p, T) \quad \text{for all } t \in (\tau, \hat{T}), \]
whence (4.13) ensures that
\[ y(t) \leq c_{10}(p, T) + c_{11}(p, T) \quad \text{for all } t \in (\tau, \hat{T}) \]
and that thus, clearly, (4.9) holds. \( \square \)

By adapting a well-established Moser-type iteration ([1], [44]) to the present context, however, one can readily turn the latter into estimates in \( L^\infty. \)

**Lemma 4.5** Given \( T > 0, \) one can find \( C(T) > 0 \) such that with \( \hat{T} := \min\{T, T_{max}\} \) we have
\[ \|z(\cdot, t)\|_{L^\infty(\Omega)} \leq C(T) \quad \text{for all } t \in (0, \hat{T}). \quad (4.14) \]

**Proof.** We first fix any \( p_\ast > 2 \) and then obtain upon combining Lemma 4.4 with Lemma 4.3, Lemma 2.2 (1.7) and Corollary 3.9 that
\[ \int_\tau^t \int_\Omega |g|^{p_\ast} \leq c_1(T) \quad \text{for all } t \in (\tau, \hat{T}) \]
with \( \tau := \frac{1}{2} \hat{T} \) and some \( c_1(T) > 0. \) As a consequence thereof, standard regularization features of the Neumann heat semigroup ([50, Lemma 1.3], [18, Lemma 4.1]) entail boundedness of \( \nabla h \) in \( \Omega \times (\tau, \hat{T}), \)
so that from Lemma 4.2 we infer the existence of \( c_2(T) > 0 \) and \( c_3(T) > 0 \) such that for \( p := 2^{k+1} \) and any nonnegative integer \( k, \)
\[ \frac{d}{dt} \int_\Omega e^{\lambda u} z^p + c_2(T) \int_\Omega |\nabla z|^2 \leq c_3(T) \cdot p^2 \cdot \left\{ \int_\Omega z^p + \int_\Omega w^p + 1 \right\} \quad \text{for all } t \in (\tau, \hat{T}). \]
On integrating and recalling Lemma 2.2 and Lemma 4.3 we see that with some $c_4(T) > 0$, for any such $p$ and arbitrary $t \in (\tau, \hat{T})$ we have

$$
\int_\Omega z^p(\cdot, t) + c_2(T) \int_\tau^t \int_\Omega |\nabla z^p|_2^2 \leq \int_\Omega e^{c_4(\cdot, t)} z^p(\cdot, t) + c_2(T) \int_\tau^t \int_\Omega |\nabla z^p|_2^2
\leq \int_\Omega e^{c_4(\cdot, \tau)} z^p(\cdot, \tau) + c_3(T) \cdot p^2 \cdot \int_\tau^t \int_\Omega z^p \leq c_4(T) \int_\Omega z^p(\cdot, \tau) + c_4(T) \cdot p^2 \cdot \int_\tau^t \int_\Omega z^p + c_3(T) \cdot p^2. \quad (4.15)
$$

The remaining part now follows a well-established reasoning: According to the Gagliardo-Nirenberg inequality and Young’s inequality, we can find $c_5(T) > 0$ such that introducing the numbers

$$M_k := \max \left\{1, \sup_{t \in (\tau, \hat{T})} \int_\Omega z^{p_k}(\cdot, t)\right\}, \quad k \in \{0, 1, 2, \ldots\},$$

all finite due to Lemma 4.4 for $p = p_k$ and each $k \in \{1, 2, 3, \ldots\}$ we have

$$c_4(T) \cdot p^2 \cdot \int_\tau^t \int_\Omega z^p \leq c_5(T) \cdot p^2 \cdot \int_\tau^t \|\nabla z^p(\cdot, s)\|_{L^2(\Omega)} \|z^p(\cdot, s)\|_{L^1(\Omega)} ds
\leq c_5(T) \cdot p^2 \cdot M_{k-1} \cdot \int_\tau^t \|\nabla z^p(\cdot, s)\|_{L^2(\Omega)} ds
\leq c_2(T) \int_\tau^t \|\nabla z^p\|_2^2 + c_5^2(T)T \cdot p^4 \cdot M_{k-1}^2 \quad \text{for all } t \in (\tau, \hat{T}),$$

whence (4.15) entails that for some $c_6(T) > 0$,

$$M_k \leq c_4(T) \int_\Omega z^{p_k}(\cdot, \tau) + c_6(T) \cdot p_k^4 \cdot M_{k-1}^2 \quad \text{for all } k \geq 1.$$

By means of a standard recursive argument, both when $p_k^4 M_{k-1}^2 \leq \|z(\cdot, \tau)\|_{L^\infty(\Omega)}^{p_k}$ for infinitely many $k \geq 1$, and as well in the opposite case this can readily be seen to imply the existence of $c_7(T) > 0$ such that

$$\|z(\cdot, t)\|_{L^\infty(\Omega)} \leq c_7(T) \quad \text{for all } t \in (\tau, \hat{T}),$$

from which the claim immediately follows. \hspace{1cm} \Box

5 Global extensibility. Proof of Theorem 1.1

Having thus ruled out blow-up of the first quantity appearing in the second alternative from (2.3), it hence remains to derive appropriate bounds for the haptotactic gradient. A first observation relates the latter to some spatio-temporal regularity properties of $z$ and $h$. 

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Lemma 5.1 Let $T > 0$ and $q \geq 1$. Then there exists $C(q, T) > 0$ fulfilling
\[
\|
\nabla v(\cdot, t)\|_{L^q(\Omega)} + \|
\nabla w(\cdot, t)\|_{L^q(\Omega)} \leq C(q, T) \int_t^T \left\{ \|
\nabla z(\cdot, s)\|_{L^q(\Omega)} + \|
\nabla h(\cdot, s)\|_{L^q(\Omega)} \right\} ds + C(q, T) \tag{5.1}
\]
for all $t \in (\tau, \hat{T})$, with $\hat{T} := \min\{T, T_{\max}\}$ and $\tau := \frac{1}{2} \hat{T}$.

Proof. Differentiating in (1.3) and recalling (2.1), we see that throughout $\Omega \times (0, T_{\max})$,
\[
\partial_t \nabla v = (-\alpha v + \nu \phi_u e^{\lambda u}) \nabla z + (-\alpha \lambda u \nabla \phi_u + \nu \nabla \phi_u + \phi) \nabla v + (\nu \phi_w + \psi) \nabla w + \nu \phi_h \nabla h \tag{5.2}
\]
and
\[
\partial_t \nabla w = (\beta e^{\lambda v} + \nu e^{\lambda v} \phi_u) \nabla z + (\beta \lambda u + \nu \phi_u + \psi) \nabla w - \nu \phi_h \nabla h, \tag{5.3}
\]
where we have suppressed the argument $(u, v, w, h)$ in $\phi$, $\psi$ and the derivatives thereof. Now as a consequence of Lemma 2.2, Lemma 4.5 and (2.1), our requirements (1.8), (1.9) and (1.10) guarantee that herein all the functions $-\alpha v + \nu \phi_u e^{\lambda u}$, $-\alpha \lambda u - \alpha \phi_u + \nu \phi_u + \phi$, $\nu \phi_w + \psi$, $\nu \phi_h$, $\beta e^{\lambda v} + \nu e^{\lambda v} \phi_u$, $\beta \lambda u + \nu \phi_u + \psi$, $\nu \phi_h$ and $\psi$, $\nu \phi_h$ are bounded in $\Omega \times (0, \hat{T})$, so that (5.2) and (5.3) imply that with some $c_1(T) > 0$ we have
\[
\|
\nabla v(\cdot, \tau)\|_{L^q(\Omega)} = \left\| \nabla v(\cdot, \tau) + \int_\tau^T \partial_t \nabla v(\cdot, s) ds \right\|_{L^q(\Omega)} \leq c_1(T) + c_1(T) \int_\tau^T \left\{ \|
\nabla z(\cdot, s)\|_{L^q(\Omega)} + \|
\nabla v(\cdot, s)\|_{L^q(\Omega)} \right\} ds + \|
\nabla h(\cdot, s)\|_{L^q(\Omega)} \right\} ds
\]
and, similarly,
\[
\|
\nabla w(\cdot, t)\|_{L^q(\Omega)} \leq c_1(T) + c_1(T) \int_\tau^T \left\{ \|
\nabla z(\cdot, s)\|_{L^q(\Omega)} + \|
\nabla v(\cdot, s)\|_{L^q(\Omega)} \right\} ds + \|
\nabla h(\cdot, s)\|_{L^q(\Omega)} \right\} ds
\]
for all $t \in (\tau, \hat{T})$. Adding these inequalities and invoking Gronwall’s lemma readily leads to (5.1). \qed

Here the crucial ingredient containing $\nabla z$ will ultimately be controlled by using the following result which extends a corresponding statement from [45, Lemma 3.14] to the present more complex system (2.2).

Lemma 5.2 Let $T > 0$. Then there exists $C(T) > 0$ with the property that
\[
\int_\Omega |\nabla z(\cdot, t)|^2 \leq C(T) \quad \text{for all } t \in (\tau, \hat{T}) \quad \text{and} \quad \int_T^T \int_\Omega |\Delta z|^2 \leq C(T), \tag{5.4}
\]
where again $\hat{T} := \min\{T, T_{\max}\}$ and $\tau := \frac{1}{2} \hat{T}$. 24
Proof. Defining
\[ A(x,t) := \lambda Du \nabla v - \nabla h \quad \text{and} \quad B(x,t) := -\chi z \Delta h - \chi \lambda z \nabla v \cdot \nabla h + e^{-\lambda v} f(e^\lambda v, z, v, w, h) \]
for \((x,t) \in \Omega \times (0,T_{\max})\), we see that the first equation in (2.2) simplifies to the identity
\[ z_t = Du \Delta z + A(x,t) \cdot \nabla z + B(x,t), \quad x \in \Omega, \ t \in (0,T_{\max}), \]
which we multiply by \(-\Delta z\) and integrate to find using Young’s inequality that for all \(t_0 \in [0, T)\) and any \(t \in (t_0, T)\),
\[
\int_{\Omega} |\nabla z(\cdot, t)|^2 + Du \int_{t_0}^t \int_{\Omega} |\Delta z|^2 = \int_{\Omega} |\nabla z(\cdot, t_0)|^2 - \int_{t_0}^t \int_{\Omega} (A \cdot \nabla z) \Delta z - \int_{t_0}^t \int_{\Omega} B \Delta z \\
\leq \int_{\Omega} |\nabla z(\cdot, t_0)|^2 + Du \int_{t_0}^t \int_{\Omega} |\Delta z|^2 + \frac{1}{2Du} \int_{t_0}^t \int_{\Omega} |A \cdot \nabla z|^2 \\
+ \frac{1}{2Du} \int_{t_0}^t \int_{\Omega} B^2. \tag{5.5}
\]
Here we note that given \(T > 0\), in view of the boundedness property of \(z\) in \(\Omega \times (0, \tilde{T})\) asserted by Lemma 4.5 we can fix \(c_1(T) > 0\) such that due to Young’s inequality,
\[
\frac{1}{Du} \int_{t_0}^t \int_{\Omega} B^2 \leq c_1(T) \int_{t_0}^\tilde{T} \int_{\Omega} |\Delta h|^2 + c_1(T) \int_{t_0}^\tilde{T} \int_{\Omega} |\nabla v \cdot \nabla h|^2 + c_1(T) \\
\leq c_1(T) \int_{t_0}^\tilde{T} \int_{\Omega} |\Delta h|^2 + c_1(T) \int_{t_0}^\tilde{T} \int_{\Omega} |\nabla v|^4 + \frac{c_1(T)}{4} \int_{t_0}^\tilde{T} \int_{\Omega} |\nabla h|^4 \\
+ c_1(T) \quad \text{for all } t_0 \in [0, \tilde{T}) \text{ and } t \in (t_0, \tilde{T}). \tag{5.6}
\]
Moreover, as the Gagliardo-Nirenberg inequality together with elliptic estimates and Lemma 4.3 provides \(c_2 > 0\) and \(c_3(T) > 0\) such that
\[
\int_{\Omega} |\nabla z|^4 \leq c_2 \|\Delta z\|_{L^2(\Omega)}^2 \|z\|_{L^4(\Omega)}^2 + c_2 \|z\|_{L^4(\Omega)}^4 \leq c_3(T) \|\Delta z\|_{L^2(\Omega)}^2 + c_3(T) \quad \text{for all } t \in (0, \tilde{T}), \tag{5.7}
\]
\[25\]
by combining the Cauchy-Schwarz inequality with Young’s inequality we obtain
\[
\frac{1}{D_u} \int_{t_0}^t \int_{\Omega} |A \cdot \nabla z|^2 \leq \frac{1}{D_u} \int_{t_0}^t \|A(\cdot, s)\|_{L^4(\Omega)}^2 \|\nabla z(\cdot, s)\|_{L^2(\Omega)}^2 ds \\
\leq \sqrt{\frac{c_3(T)}{D_u}} \int_{t_0}^t \|A(\cdot, s)\|_{L^4(\Omega)} \sqrt{\|\Delta z(\cdot, s)\|_{L^2(\Omega)}^2 + 1} ds \\
\leq \frac{D_u}{4} \cdot \left\{ \int_{t_0}^t \int_{\Omega} |\Delta z|^2 + (t-t_0) \right\} + \frac{c_3(T)}{D_u^3} \int_{t_0}^t \int_{\Omega} |A|^4 \\
\leq \frac{D_u}{4} \int_{t_0}^t \int_{\Omega} |\Delta z|^2 + \frac{D_u T}{4} \\
\quad + 4 c_3(T) \lambda^4 D_u \int_{t_0}^t \int_{\Omega} |\nabla v|^4 \\
\quad + \frac{4 c_3(T) \lambda^4}{D_u} \int_{t_0}^t \int_{\Omega} |\nabla h|^4 \text{ for all } t_0 \in [0, \hat{T}) \text{ and } t \in (t_0, \hat{T}),
\]
which along with (5.6) shows that (5.5) implies the inequality
\[
\int_{\Omega} |\nabla z(\cdot, t)|^2 + \frac{D_u}{4} \int_{t_0}^t \int_{\Omega} |\Delta z|^2 \\
\leq \int_{\Omega} |\nabla z(\cdot, t_0)|^2 + c_4(T) \int_{\tau}^{\hat{T}} \int_{\Omega} |\Delta h|^2 + c_4(T) \int_{\tau}^{\hat{T}} \int_{\Omega} |\nabla h|^4 \\
+ c_4(T) \int_{t_0}^t \int_{\Omega} |\nabla v|^4 + c_4(T) \text{ for all } t_0 \in [\tau, \hat{T}) \text{ and } t \in (t_0, \hat{T}) \tag{5.8}
\]
with some appropriately large \( c_4(T) > 0 \).

To proceed from this, we observe that as a consequence of Lemma 5.1 we can find \( c_5(T) > 0 \) such that
\[
\int_{\Omega} |\nabla v|^4 \leq c_5(T) + c_5(T) \int_{\tau}^{\hat{T}} \int_{\Omega} |\nabla z|^4 + c_5(T) \int_{\tau}^{\hat{T}} \int_{\Omega} |\nabla h|^4 \text{ for all } t \in (\tau, \hat{T}),
\]
and that another application of the Gagliardo-Nirenberg inequality in conjunction with Lemma 3.8 provides \( c_6 > 0 \) and \( c_7(T) > 0 \) fulfilling
\[
\int_{\Omega} |\nabla h|^4 \leq c_6 \cdot \left\{ \int_{\Omega} |\Delta h|^2 \right\} \cdot \left\{ \int_{\Omega} |\nabla h|^2 \right\} \\
\leq c_7(T) \cdot \int_{\Omega} |\Delta h|^2 \text{ for all } t \in (0, \hat{T}).
\]

Therefore, again through Lemma 3.8 (5.8) reduces to
\[
\int_{\Omega} |\nabla z(\cdot, t)|^2 + \frac{D_u}{4} \int_{t_0}^t \int_{\Omega} |\Delta z|^2 \leq \int_{\Omega} |\nabla z(\cdot, t_0)|^2 + c_8(T) \int_{t_0}^t \int_{\Omega} \int_{\Omega} |\nabla z(x, \sigma)|^4 dx d\sigma ds \\
+ c_8(T) \text{ for all } t_0 \in [\tau, \hat{T}) \text{ and } t \in (t_0, \hat{T}), \tag{5.9}
\]

26
where by the Fubini theorem and, again, (5.7),
\[
c_8(T) \int_{t_0}^t \int_s^t \int_\Omega |\nabla z(x,\sigma)|^4 \, dx \, d\sigma \, ds
\]
\[
= c_3(T)c_8(T) \int_{t_0}^t (t-\sigma) \cdot \int_\Omega |\nabla z(x,\sigma)|^4 \, dx \, d\sigma
\]
\[
+ c_8(T) \cdot (t-t_0) \int_\tau^t \int_\Omega |\nabla z|^4
\]
\[
\leq c_8(T) \cdot (t-t_0) \cdot \int_{t_0}^t \int_\Omega |\nabla z|^4
\]
\[
+ c_8(T) \cdot (t-t_0) \cdot \int_\tau^t \int_\Omega |\nabla z|^4
\]
\[
\leq c_3(T)c_8(T) \cdot (t-t_0) \cdot \int_{t_0}^t \int_\Omega |\nabla z|^2 + c_8(T)C_3(T)(t-t_0)
\]
\[
+ c_3(T)c_8(T)T \int_{\tau}^{t_0} \int_\Omega |\Delta z|^2 + c_8(T)C_3(T)(t_0-\tau)
\]
for all \(t_0 \in [\tau, \hat{T})\) and \(t \in (t_0, \hat{T})\). (5.10)

We now let \(\delta > 0\) be small enough such that \(c_3(T)c_8(T)\delta \leq \frac{D_u}{8}\), and choose \(N \in \mathbb{N}\) and \((t_i)_{i \in \{1,\ldots,N\}} \subset [\tau, \hat{T}]\) such that \(t_1 = \tau, t_N = \hat{T}\) and \(0 < t_{i+1} - t_i \leq \delta\) for all \(i \in \{1,\ldots,N-1\}\). Then inserting (5.10) into (5.9) shows that
\[
I_i := \sup_{t \in (t_i, t_{i+1})} \int_\Omega |\nabla z(\cdot, t)|^2
\]
\[
J_i := \frac{D_u}{8} \int_{t_i}^{t_{i+1}} \int_\Omega |\Delta z|^2,
\]
along with \(I_0 := \int_\Omega |\nabla z(\cdot, \tau)|^2\) and \(J_0 := 0\) satisfy
\[
\max\{I_i, J_i\} \leq I_{i-1} + c_3(T)c_8(T)T \cdot \sum_{j=0}^{i-1} J_j + c_8(T)
\]
for all \(i \in \{1,\ldots,N-1\}\),
whence if we let
\[
K_i := \sum_{k=1}^i \max\{I_k, J_k\} + 1
\]
for \(i \in \{1,\ldots,N-1\}\),
\[
K_i \leq \sum_{k=1}^{i} I_{k-1} + c_3(T)c_8(T)T \cdot \sum_{k=1}^{i} \sum_{j=0}^{k-1} J_j + ic_8(T) + 1
\]

\[
\leq I_0 + \sum_{j=1}^{i-1} I_j + c_3(T)c_8(T)T \cdot \sum_{j=1}^{i-1} \sum_{k=j+1}^{i} J_j + (N-1)c_8(T) + 1
\]

\[
= \sum_{j=1}^{i-1} \left\{ I_j + c_3(T)c_8(T)T \cdot (i-j)J_j \right\} + I_0 + (N-1)c_8(T) + 1
\]

\[
\leq \left\{ 1 + (N-2)c_3(T)c_8(T)T \right\} \cdot K_{i-1} + I_0 + (N-1)c_8(T) + 1
\]

\[
c_9(T) \cdot K_{i-1} \quad \text{for all } i \in \{1, \ldots, N-1\}
\]

with \(c_9(T) := \max\{1 + (N-2)c_3(T)c_8(T)T, I_0 + (N-1)c_8(T) + 1\}\). Therefore, \(K_i \leq K_0 \cdot c_9^{-1}(T)\) for all \(i \in \{1, \ldots, N-1\}\), which in view of the definitions of \((I_i)_{i \in \{1, \ldots, N-1\}}\) and \((J_i)_{i \in \{1, \ldots, N-1\}}\) yields (5.4).

Combining this with Lemma 5.1 readily implies the following.

**Lemma 5.3** For all \(q \geq 1\) and \(T > 0\) one can fix \(C(q, T) > 0\) such that with \(\hat{T} := \min\{T, T_{max}\}\) and \(\tau := \frac{1}{2}\hat{T}\) we have

\[
\|\nabla v(\cdot, t)\|_{L^q(\Omega)} \leq C(q, T) \quad \text{for all } t \in (\tau, \hat{T}).
\]

Proof. From Lemma 5.2 in conjunction with elliptic regularity theory we obtain \(c_1(T) > 0\) such that

\[
\int_\tau^{\hat{T}} \|z(\cdot, t)\|^2_{W^{2,2}(\Omega)} dt \leq c_1(T),
\]

which we combine with the continuity of the embedding \(W^{2,2}(\Omega) \hookrightarrow W^{1,q}(\Omega)\) and the Cauchy-Schwarz inequality to conclude that with some \(c_2(q) > 0\) we have

\[
\int_\tau^{\hat{T}} \|\nabla z(\cdot, t)\|_{L^q(\Omega)} dt \leq c_2(q) \int_\tau^{\hat{T}} \|z(\cdot, t)\|_{W^{2,2}(\Omega)} dt \leq c_2(q)\sqrt{\hat{T}} \cdot \left\{ \int_\tau^{\hat{T}} \|z(\cdot, t)\|^2_{W^{2,2}(\Omega)} dt \right\}^{\frac{1}{2}} \leq \sqrt{c_1(T)c_2(q)} \cdot \sqrt{T}.
\]

Since Lemma 3.8 in quite a similar fashion yields the existence of \(c_3(q, T) > 0\) such that

\[
\int_\tau^{\hat{T}} \|\nabla h(\cdot, t)\|_{L^q(\Omega)} \leq c_3(q, T),
\]

the claimed estimate is a consequence of Lemma 5.1.
Now our main result has actually already been established:

**Proof of Theorem 1.1.** Thanks to Lemma 2.1, and in particular the extensibility criterion (2.3) therein, we only need to combine the outcome of Lemma 4.5 with an application of Lemma 5.3 to $q := 5$. □

6 Simulations and discussion

To illustrate our theoretical results we also performed some numerical simulations of the version

\[
\begin{align*}
    u_t &= D_u \Delta u - \chi \nabla \cdot (u \nabla h) - \xi \nabla \cdot (u \nabla v) + \mu u (1 - u - v - w), \\
    h_t &= D_h \Delta h - h + \alpha w, \\
    v_t &= -hv + \eta v (1 - u - v) + \beta \frac{w}{1+w}, \\
    w_t &= \gamma u,
\end{align*}
\]

(6.12)

of the indirect signal production model (1.1) and – for comparison purposes – we also simulated some solutions of the system

\[
\begin{align*}
    u_t &= D_u \Delta u - \chi \nabla \cdot (u \nabla h) - \xi \nabla \cdot (u \nabla v) + \mu u (1 - u - v - w), \\
    h_t &= D_h \Delta h - h + \alpha u, \\
    v_t &= -hv + \eta v (1 - u - v),
\end{align*}
\]

(6.13)

in which the signal (MDEs) is directly produced by the tumor cells. Since for both models there is no blow-up as long as $\mu > 0$ (see [24] for the result concerning (6.13)), we only considered here the case with no tumor cell proliferation, i.e. $\mu = 0$.

The simulations were performed using a discontinuous Galerkin FEM method. Thereby, the diffusion was discretized in space by using a symmetric interior penalty Galerkin (SIPG) method (see [35]), while for the drift term we did an upwind discretization. The time was discretized with an IMEX procedure handling the diffusion implicitly and the reaction and taxis terms explicitly. The computational domain was $\Omega = [0, 1]^2$ and the initial conditions for tumor cells and MDEs were chosen in the form $u_0(x) = \exp(-\frac{|x|^2}{2\varepsilon_u})$, $h_0(x) = \exp(-\frac{|x|^2}{2\varepsilon_h})$, with $\varepsilon_u = 0.05$, $\varepsilon_h = 0.1$. For the initial density of CAFs we considered a radially symmetric form $w_0(r) = \exp(-\frac{(r-r_0)^2}{2\varepsilon_w})$ with $\varepsilon_w = 0.01$ and $r_0 = 0.5$. Finally, the initial tissue density was characterized by $v_0(x) = \begin{cases} v_{\max}, & x \in \Omega_v \\ v_{\min}, & x \notin \Omega_v \end{cases}$, with $v_{\max} = 1$ and $v_{\min} = 0.2$, thus $\Omega_v \subset \Omega$ representing the stripes shown in the second columns of Figures 1 and 2. Together these initial conditions describe a heterogeneous tissue structure, in which a Gaussian-shaped tumor is embedded, surrounded by activated CAFs and featuring higher MDE concentration in the areas with many tumor cells. We considered for both models (where applicable) the following parameters: $\chi = 0.6$; $\xi = 0.5$; $D_u = 10^{-10}$; $D_h = 0.1$; $\eta = 10.6$; $\alpha = 5$; $\beta = 1$; $\gamma = 1.0$. The results are shown in Figure 1 for system (6.12) and in Figure 2 for system (6.13). The first rows represent the initial conditions, and the subsequent rows illustrate the solution behavior at several successive time steps.
Figure 1: Evolution of tumor (first column), tissue (2nd column), MDEs (3rd column), and CAFs (last column) for model (6.12) with $\mu = 0$. Successive times from top to bottom, top row: initial conditions.
The simulations of (6.12) depict an increase in tumor cell density, which is, however, limited. Same applies to the MDE concentration and CAFs density, but with smaller rates. The tissue is correspondingly degraded, and the CAFs spread into the region containing the main tumor mass, at the same time building up some tissue (for a sufficiently large $\beta$, as in these simulations) at the sites where they are abundant enough. In contrast, model (6.13) predicts localized tumor cell aggregates of very high density which are almost three orders of magnitude higher than the initial condition and keep growing in time, thus hinting on blow-up of the solution. Likewise, in this latter setting the MDE concentration is directly produced by the tumor cells and keeps growing as well, although to a much smaller rate than the cell density. The tissue degradation is much more localized and – where it happens – stronger. These results are conform with the theoretical findings in this and previous papers predicting blow-up of solutions when the signal was directly produced by the agents performing chemotaxis ([2]), while the solutions stay bounded in the case of indirect signal production.

From a biological viewpoint the tumor cells use CAFs (which are originally 'harmless' stroma cells only becoming supporters of tumor invasion upon activation) to produce matrix degrading factors. As mentioned above, the production of the latter seems to be decisively controled by CAFs, hence is rather indirect, as the neoplastic cells first need to activate the CAFs, which then enhance degradation of surrounding tissue and cell motility, including chemotaxis towards the gradient of proteolytic agents. Our mathematical result actually tells that such mediation of invasion leads to avoidance of blow-up, unlike previous models where the direct production of chemoattractant let the solution(s) become unbounded, a rather unrealistic biological scenario. The result is in line with many in vivo and in vitro observations that cancer cells 'hijack' their environment in order to gain migratory, survival, and proliferative advantages.

We considered here that CAFs were non-diffusing, although they are indeed able to spread [42]. Accounting for diffusion of the chemoattractant producer $w$ does not pose, however, any further challenge to the analysis of our model (1.1); in that case our setting belongs to the same mathematical class as the one in [3], to which it is also biologically related: both describe the evolution of a tumor under chemotaxis and haptotaxis, the chemoattractant(s) – of which MDEs are considered in both models – being supposed to diffuse.

Further chemotaxis-haptotaxis models belonging to the class studied here can be considered, of which (1.2) is just one example. As mentioned above, a diffusing signal producer can be easily accomodated to this model class – if the diffusion is linear. Solution-dependent diffusions of either involved species need further investigation; in [33] one such system extending that from [47] to allow for nonlinear diffusion of the chemotactic species has been studied, however without haptotaxis.

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Figure 2: Evolution of tumor (first column), tissue (2nd column), and MDEs (last column) for model (6.13) with \( \mu = 0 \). Successive times from top to bottom, top row: initial conditions.