ChipSeg: An Automatic Tool to Segment Bacterial and Mammalian Cells Cultured in Microfluidic Devices

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ABSTRACT: Extracting quantitative measurements from time-lapse images is necessary in external feedback control applications, where segmentation results are used to inform control algorithms. We describe ChipSeg, a computational tool that segments bacterial and mammalian cells cultured in microfluidic devices and imaged by time-lapse microscopy, which can be used also in the context of external feedback control. The method is based on thresholding and uses the same core functions for both cell types. It allows us to segment individual cells in high cell density microfluidic devices, to quantify fluorescent protein expression over a time-lapse experiment, and to track individual mammalian cells. ChipSeg enables robust segmentation in external feedback control experiments and can be easily customized for other experimental settings and research aims.

INTRODUCTION

Live-cell imaging by automated microscopy enables the collection of large-scale data useful to study the link between cellular dynamics and emerging phenotypes. In the context of synthetic biology, the combination of control engineering algorithms with live-cell imaging has been shown to successfully enable the automatic regulation of gene expression across cellular chassis. 1−3 If employing microfluidics/microscopy platforms, then the external feedback control action is implemented by measuring the relevant control output (e.g., fluorescent reporter expression in cells grown within microfluidic devices) throughout the time-lapse experiment by means of automatic segmentation. This measurement informs a control algorithm that computes the control input to minimize the control error (i.e., the difference between the control target and output). The control input is automatically provided to cells, for example, by changing the culture media with motor-controlled pumps. Automatic segmentation needs to be performed in real time and to be robust over the whole time-lapse experiment.

We present here ChipSeg, a thresholding-based algorithm that automatically segments both bacterial and mammalian cells cultured in microfluidic devices. The same core functions are implemented for both cell types, making the code flexible for other chassis and applications. The algorithm is easy to use and shows robust segmentation results in external feedback control experiments with microfluidics/microscopy platforms. 5−10 ChipSeg can be easily adapted for open-loop experiments and other cell types/experimental settings.

ChipSeg is implemented in MATLAB, and it is publicly available. The source code and documentation can be found at https://github.com/LM-group/ChipSeg.

RESULTS

ChipSeg is broadly based on the Otsu thresholding method 11 and is implemented in MATLAB using both custom and built-in Image Processing Toolbox functions. When used within an external feedback control experiment, the segmentation is performed online: at each sampling time, the acquired image is imported by ChipSeg and the algorithm output is fed back to the computer for control input calculation (Figure 1A,B).

First, ChipSeg performs global thresholding to segment a bacterial or mammalian cell cluster in a region of interest within the microfluidic device used for cell culturing; pre-processing, such as filtering and contrast enhancement, can be applied (Supporting Information). Global thresholding can be performed on phase-contrast images or, in the case of poor contrast, on images of cells stained with a fluorescent dye (Supporting Information).

Individual cells can also be identified using local thresholding for bacterial cells. The segmentation can be refined in a customized way to fix possible artifacts, for example, by
Our algorithm is fully customizable as we provide a step-by-step explanation of all the pre-processing, segmentation, tracking, and fluorescence quantification functions (Supporting Information).

■ DISCUSSION

Many automated image segmentation tools exist to analyze microscopy images;12–14 user-friendly graphical interfaces within a software package are often presented as black-boxes which cannot be easily combined with other softwares (e.g., in external feedback control applications, where communication between segmentation and control code is required).

Other image analysis algorithms previously proposed to segment cells cultured and imaged within microfluidic devices are often specific for certain chip designs such as the mother machine device;15–19 instead, ChipSeg does not rely on the geometry of the devices we used (see refs 20 and 21 for bacterial and mammalian cell device description, respectively).

ChipSeg is based on simple MATLAB functions and should be easy to customize also for users lacking a computational background. While it is true that parameters within the algorithm might need to be tuned if using images of different cells or if varying the acquisition settings, a few trial-and-error iterations might be enough to fix them, even if using limited images. Segmentation of more complex images (e.g., tissues) might require different types of algorithms (e.g., refs 22 and 23).

Our algorithm has enough flexibility to be used across cell types, and adaptation of the code should be quicker than implementing deep learning-based approaches (e.g., refs 15–19 and 24–26), whose undeniable robustness, in most cases, comes at the cost of extensive algorithm training on manually annotated datasets.

■ MATERIALS AND METHODS

Bacterial Cell Microfluidic Device, Strain, and Image Acquisition. The microfluidic device used for the experiments shown here was developed by Mondragón-Palomino and colleagues;21 soft lithography was used to make the device, as shown in ref 21. *Escherichia coli* MG1655 cells carrying the comparator construct described in ref 27 were loaded in the device, as shown in ref 21. For each experiment, time-lapse fluorescence microscopy experiments were performed using an inverted widefield fluorescence microscope (Leica) and images were taken using an Andor iXon Ultra digital camera. The microfluidic device was enclosed inside an incubation chamber set to 37 °C (Pecon). The microscope took every 5 min images of cells growing inside the microfluidic device trapping chambers. At each time point, a phase contrast image (PhC) and a green fluorescent image were acquired for each of the three trapping chambers. Green fluorescent images were used for the detection of GFP. Images were acquired using a 100× objective. Exposure times were set to 100 ms for the PhC and green spectra.

Mammalian Cell Microfluidic Device, Cell Lines, and Image Acquisition. Experiments analyzed in this paper were performed with either of the two cell lines: a mouse embryonic stem cell (mESC) line stably carrying a destabilized GFP, replacing the entire Rex1 coding sequence in one allele (Rex1-GFPd2),28 or dual-reporter mESCs carrying coding regions for eGFP and mCherry downstream of transcriptional start sites for mir-302 and mir-290 clusters, respectively.29 Cells were cultured on gelatinized tissue culture dishes at 37 °C in a 5% CO2...
humidified incubator in Dulbecco’s modified Eagle medium (DMEM; Sigma; D5796) supplemented with 15% fetal bovine serum (Sigma; F7524), nonessential amino acids (Gibco; 11140035), l-glutamine (Gibco; 25030024), sodium pyruvate (Gibco; 11360039), penicillin–streptomycin (Sigma; P4458), 2-mercaptoethanol (Gibco; 31350010), and 10 ng/mL mLIF (Peprotech; 250-02). Both cell lines were transfected with a plasmid to express a transgene to encode nuclear Histone 2B (H2B) tagged with infrared fluorescent protein (iRFP), as shown in ref 10. The microfluidic device for mammalian cells was designed and characterized, as shown in ref 20. A master mold of the device (MicroX technologies) was used to produce device replicas by PDMS molding. Microfluidic device fabrication, processing, and cell loading into devices were performed, as previously described.20 Cells were vacuum-loaded into microfluidic chips and precultured with constant perfusion of fresh media while allowing to attach overnight in a humidified incubator; Rex1-GFPd2 cells were supplemented with 10 μM cell permeable CellTracker blue (Invitrogen; C12881) and 2-mercaptoethanol (Gibco; 31350010), and 10 ng/mL mLIF (Peprotech; 250-02). Both cell lines were transfected with a plasmid to express a transgene to encode nuclear Histone 2B (Peprotech; 250-02). Both cell lines were transfected with a plasmid to express a transgene to encode nuclear Histone 2B (Peprotech; 250-02). Both cell lines were transfected with a plasmid to express a transgene to encode nuclear Histone 2B (Peprotech; 250-02). Both cell lines were transfected with a plasmid to express a transgene to encode nuclear Histone 2B (Peprotech; 250-02).

**ASSOCIATED CONTENT**

**Supporting Information**
The Supporting Information is available free of charge at https://pubs.acs.org/doi/10.1021/acsomega.0c03906.

Step-by-step explanation of the code (PDF).

Exemplar bacterial cell movie showing phase-contrast and GFP fluorescent images, ChipSeg-computed mask, average fluorescence, fluorescence distribution, and cell number (AVI).

Exemplar Rex1-GFPd2 mESC movie showing phase-contrast and green/blue fluorescent images as well as ChipSeg-computed mask and fluorescence (MP4).

Exemplar dual-reporter mESC movie showing phase-contrast and mCherry/infrared images, ChipSeg-computed cell labels and their tracking over time, and mCherry fluorescence of an individual cell (labeled as 5) over the time lapse (AVI).

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1M.d.B. and L.M. conceived the project and supervised the work; L.P., G.F., G.P., and S.N. developed the initial code; L.d.C. and C.G.Z.-C. refined the algorithm and analyzed time-lapse experiments; M.K., B.S., and E.P. performed the experiments; D.B. supervised S.N. and G.P.; N.J.S. and C.G. co-supervised the experimental activities in bacteria; and L.d.C., C.G.Z.-C., and L.M. wrote the paper with input from the other authors.

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