Research Article

Optimization Analysis Method of New Orthotropic Steel Deck Based on Backpropagation Neural Network-Simulated Annealing Algorithm

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To study the effects of the fatigue performance due to the major design parameter of the orthotropic steel deck and to obtain a better design parameter, a construction parameter optimization method based on a backpropagation neural network (BPNN) and simulated annealing (SA) algorithm was proposed. First, the finite element (FE) model was established, and the numerical results were validated against available full-scale fatigue experimental data. Then, by calculating the influence surface of each fatigue detail, the most unfavorable loading position of each fatigue detail was obtained. After that, combined with the data from actual engineering applications, the weight coefficient of each fatigue detail was calculated by an analytic hierarchy process (AHP). Finally, to minimize the comprehensive stress amplitude, a BPNN and SA algorithm were used to optimize the construction parameters, and the optimization results for the conventional weight coefficients were compared with the construction parameters. It can be concluded that compared with the FE method through single-parameter optimization, the BPNN and SA method can synthetically optimize multiple parameters. In addition, compared with the common weighting coefficients, the weighting coefficients proposed in this paper can be better optimized for vulnerable parts. The optimized fatigue detail stress amplitude is minimized, and the optimization results are reliable. For these reasons, the parameter optimization method presented in this paper can be used for other similar applications.

1. Introduction

As a pivotal structure form of steel bridge decks, orthotropic steel decks possess features such as a low selfweight, high ultimate bearing capacity, and wide range of applications [1–3]. However, in the long-term service, fatigue cracking problems are present in many orthotropic steel bridge decks (OBDs). According to the statistics, fatigue almost accounts for 80%–90% of metallic failure [4–6]. Fatigue cracks occur for a variety of reasons, but there are three major reasons. First, the weld has quality defects of its own. Second, the single-side fillet weld between the longitudinal rib and deck plate is in an eccentric stress state when subjected to wheel loads, and the fatigue resistance is lower [7]. Third, the stiffness of the connections among the deck plate, longitudinal rib, and diaphragm are quite different, resulting in uncoordinated deformation. When combined deformation of out-of-plane bending and torsion occurs at the diaphragm due to the wheel load effects, a stress concentration can be generated at the rib-to-diaphragm details because of the restraint of the longitudinal rib on the diaphragm’s lateral deformation, and the fatigue performance will be weakened [8, 9].

To address the problem outlined above, a new semi-opened longitudinal rib orthotropic steel deck was designed (referred to as the new steel bridge deck in the following paper, Figure 1), and the 10 million cycles fatigue test on a full-scale partial model was completed. Each construction detail showed no sign of fatigue cracking, which indicated that the new steel bridge deck possessed relatively strong fatigue resistance performance [10]. However, the most unfavorable loading position of each fatigue detail was not considered in the fatigue test, and the stress of the rib-to-deck weld joints was approximately 30% higher than that of
conventional structures. Therefore, it is necessary to further analyze the influence of structural details and design parameters on the fatigue performance of a new steel bridge deck in order to obtain better structural parameters.

Scholars have carried out studies on the construction parameters of orthotropic steel decks. Kainuma et al. [11] performed full-scale fatigue tests on orthotropic steel decks with different structure parameters, and the outcomes showed that raising the penetration rate had positive influences on preventing root cracking. Song et al. [12] considered the influence of geometric parameters on the fatigue performance through a parametric analysis model under wheel loads. Xia et al. [13] studied the effects of cutouts, the deck thickness, and other important parameters on the fatigue performance based on calibrated FE models. According to the results of the laboratory tests and parametric studies, suggestions for grid deck optimization design were given by Huang et al. [14]. De Corte [15] analyzed the influence of the rib height and rib inclination on the stress at the cutout. It was concluded that the load stresses decrease with both the rib height as well as the rib inclination. Oh et al. [16] studied the effect of the height, thickness, and shear area of cross-beam shapes of bulkhead plates and verified his results by tests. Then, they concluded that increasing the height, thickness, or shear area of the cross-beam reduced the maximum principal stress. The optimizations of OBDs were based on FE models and tests by single-factor analysis, which lacked comprehensive optimization of the structure parameters. With the development of computer technology, artificial intelligence is often used to accomplish the multiparameter optimization. Ahmadi et al. [17–19] studied the data forecasting based on the least square support vector machine (LSSVM), and acceptable results were obtained. After that, they used the genetic algorithm (GA) to optimize the results [20, 21]. The artificial neural network (ANN) models and gene-expression programming (GEP) were adopted by Baghban and Ahmadi et al. [22–27] to estimate the hydrogen sulfide and carbon dioxide solubility in ionic liquids, and those models had a good performance of estimation. For structural optimization, Bagheri et al. [28] used a genetic optimization algorithm to evaluate the fuzzy reliability index. Meng et al. [29] solved the design problem of the wellhead 73 platform based on reliability-based design and optimization (RBDO). Xin et al. [30] optimized the design parameters of the bridge based on the proposed multiscale optimization model. Zhuang et al. [31] established a partial FE model to optimize a steel box girder under vehicle loads. However, the weight coefficient was not considered in their work.

In this paper, a FE model was established for the new steel bridge deck based on tests and research. The FE model was verified through fatigue tests, and the influence surfaces of the major fatigue details were determined to locate the most unfavorable loading position. In addition, the parameter-optimizing method was established based on the combination of the BPNN and SA, and the weight coefficient of fatigue details was determined through the AHP according to the statistical data from practical engineering projects. At last, reasonable values of the major parameters were obtained. The flow chart is shown in Figure 2.

2. New Orthotropic Steel Deck Structure

The fatigue crack problem of regular orthotropic steel decks mainly occurs at the connection of the rib-to-deck and rib-to-diaphragm. To optimize the fatigue performance of the fatigue details outlined above, the construction form of the steel bridge deck was redesigned, and a new orthotropic steel deck structure was proposed. The spacing of the longitudinal ribs was increased for the welding operations. At the bottom of longitudinal ribs, several connection plates were attached to guarantee the rigidity of the structure. The lining plates were provided at the diaphragm so that the integrity of the structure can be ensured. This new type of structure can also realize double-surface welding between the deck and longitudinal ribs, improve the welding quality between them and address the eccentric adaptive force problem of the welded seams of the single-edged angle [10]. Semiopened longitudinal ribs weaken the extent of the force concentration and improve the fatigue performance of the connection between the longitudinal ribs and diaphragms. The construction of the new steel bridge deck is shown in Figure 1.

The rib of the steel bridge deck in Figure 1 was 380 mm high, 400 mm wide, and 10 mm thick; the opening was 400 mm wide; the connection plate was 560 mm long, 280 mm wide, and 10 mm thick with a 430 mm longitudinal serial interval; the deck was 16 mm thick; the interval between intermediate diaphragms was 3.2 m. The major fatigue details of the new steel bridge deck feature a diaphragm cutout (DC), rib-to-diaphragm joint (RDI), rib-to-deck joint (RD), deck-to-lining plate joint (DL), and rib-to-connection plate joint (RC), which are shown in Figure 3.

3. FE Simulation Test on Fatigue Performance of New Steel Bridge Deck

The fatigue test results on the new steel bridge deck have been recorded in the literature [10]. This model measured 7000 mm long, and the lane width was set to 3500 mm, including three diaphragms and four ribs, and two vertical ribs were set at the ends of the model considering the border effect. The wheel load position was 600 mm away from the diaphragm, and it was at the top of the rib-to-deck plate weld in the transverse direction. The 50-T actuator was selected as
the loading device, and the load distribution beam was set under the actuator. The stress amplitude was set at 270 kN, and the number of load cycles for this fatigue test was 10 million. Considering the diffusion effect of the pavement layer, the loading area was 310 mm × 710 mm. Two 310 mm × 710 mm × 40 mm steel plates were installed at the bottom of the distribution beam to achieve uniform load transmission, and a 20 mm thick rubber mat was glued to the bottom of the steel plate. The constraint conditions of the experimental model adopted the method of bottom consolidation. The FE model is shown in Figure 4, the wheel load position is shown in Figure 5, and the test scene is shown in Figure 6.

To test the reliability of the FE modelling method, the outcomes of the models were verified. The model utilized a shell element simulation, and the sizes, thicknesses, construction details, loading methods, and border conditions were the same as those of the test model. In the test, the calculated values and measured values of the fatigue details were compared to verify the accuracy of the FE calculation. The FE calculated values and measured values of DC, RDI, and DL are shown in Figure 7.

Figure 7 shows the changing trends of both the calculated values and measured values of the measuring points of DC, RDI, and RD all showed linear changes. The calculated values of RDI and RD were slightly higher than the measured values, while the outcomes of DC showed the opposite phenomenon; the calculated values were slightly lower than the measured values. The primary reason for this phenomenon is that, during the loading process, the loading equipment tilted slightly toward the longitudinal direction, producing a small horizontal force; in the meantime, the force in the vertical direction was relatively lower compared to the FE load, and the measured values of RDI and RD, therefore, seemed to be low. This horizontal force caused large out-of-plane distortions of the intermediate diaphragms, while the out-of-plane distortion had a remarkable influence on the opening of the diaphragms. Consequently,
Figure 5: Continued.
4. Ensuring the Most Unfavorable Loading Position and Loading Condition

The stress on the key details of the orthotropic steel deck is extremely sensitive to the wheel effect, and it is vitally important to locate the most unfavorable loading position of each fatigue detail [32–34]. Therefore, targeting each fatigue detail, the stress history of the wheel loading effect in different areas was established to create the influence surface and ensure the most unfavorable position of each fatigue detail.

4.1. Load Condition. The vehicle model of fatigue load III from the Chinese Specification for the Design of Highway Steel Bridges was selected to perform the calculation (which is shown as Figure 8), and the axle load was set to 120 kN. The wheel load area was set to 0.6 m × 0.2 m.

4.2. FE Model. To analyze the stress response of the new steel bridge deck under standard fatigue wheel load, a 3-D FE shell model was established that measured 25.6 m in the longitudinal direction, including 10 diaphragms and measured 8 m in the transverse direction, including 10 longitudinal ribs. The elastic modulus was set to 206 GPa, Poisson’s ratio was set to 0.3, and the type of mesh was S4. For the concentrated regions, the two sections that were within the range measured 6.4 m forward and back toward the deck were specialized into units, and the total model units added up to 813,457, with regard to 810,901 joints. The border conditions were set as follows: the diaphragms’ translational and rotational degrees of freedom were restricted in the X, Y, and Z directions; the translational degrees of freedom of the ends of the ribs’ beam and deck were restricted in three directions, as shown in Figure 9.

4.3. Ensuring the Most Unfavorable Loading Position. The center of the standard fatigue vehicle wheel axle took the centerline of the 6th and 7th ribs (i.e., U6 and U7) as the initial position (shown as Figure 10), and the 6th longitudinal rib was the concerned position.

Considering the symmetry of the wheel load, 11 conditions were considered in the transverse direction, and 37
conditions were considered in the longitudinal direction. Based on the statistics of the outcomes of the FE calculation, the influence surface of each fatigue detail was established, which is shown in Figure 11.

The highest stress response position of RD was equal to the wheel loading effect position, and it changed following the changing trend of the wheel loading position. We could thus ascertain the most unfavorable position through the longitudinal and transverse stress change curves under the wheel loading effect, as shown in Figure 12.

From Figures 11 and 12, we can tell that the stress changing pattern of DC and RDI were basically the same. Specifically, the most unfavorable loading positions were both at a transverse location of 400 mm and a longitudinal location of 3800 mm on the bridge, which were above the 6th longitudinal ribs in the transverse direction and 600 mm in
longitudinal direction from the 5th diaphragm. The values of the stress on DC and RDI fluctuated, and the primary cause was that the wheel load was directly loaded at the position of the lining plate.

The most unfavorable loading position of RD was at a transverse location of 400 mm and a longitudinal location of 3600 mm on the bridge, which was above the web of the 6th longitudinal rib in transverse direction and 400 mm from the 5th diaphragm in the longitudinal direction.

The most unfavorable loading position of DL was at a transverse location of 800 mm and a longitudinal location of 3200 mm and 4400 mm on the bridge, which was 300 mm from the lining plate in the transverse direction and above the lining plate in the longitudinal direction. Besides, the wheel loading effect area of DL was relatively small.

The most unfavorable position of RC was at a longitudinal location of 2400 mm and a transverse location of 500 mm on the bridge, which was above the connection plate on which we concentrated in the transverse direction and 800 mm from the 5th diaphragm in the longitudinal direction. Moreover, due to the wheel loading effect, the force values changed from tensile stress to compressive stress. According to the calculation, the values of the stress amplitude of RC were approximately 20 MPa, which was much lower than its fatigue level of 80 (Eurocode3 specifications). To simplify the calculation, we did not consider the influences of RC itself.

The most unfavorable position and loading condition of each fatigue detail is shown in Figure 13. Because the most unfavorable position of RD was very similar to those of DC and RDI, the stress difference between them was approximately 2%. During the following loading condition calculation, the most unfavorable loading position of RD was considered as loading condition 1.

5. Optimizing the Parameter of the New Orthotropic Steel Bridge Deck Based on BP-SA-AHP Method

The fatigue performance and fatigue life of the fatigue details are related to the stress amplitude under the wheel load [35, 36]. Considering the axle load of the wheel load and pavement layer, the loading amplitude for a single wheel load was considered to be 60 kN, and the wheel load area was 710 mm × 310 mm. According to the settled loading conditions above, the stress amplitude of each fatigue test was calculated based on different construction parameters. The
Figure 12: Longitudinal and transverse stress curve of RD.

Figure 13: Continued.
corresponding relationship between stress amplitudes of the fatigue details and construction parameters was established based on the BPNN algorithm, and the values were selected for the weight coefficients of the fatigue details through AHP. After optimizing the outcomes by SA, the optimized construction parameters of the new orthotropic steel bridge deck were obtained. The workflow is shown in Figure 14.

5.1. Ensuring the Training Samples and the Test Samples. It is reported [37–40] that when the thickness is too large, the welding penetration rate of the orthotropic steel bridge deck will be reduced, and the welding quality will decline. Moreover, the increase of thickness will lead to excessive welding residual stress. These factors will weaken the fatigue life of OBDs. When the thickness is too small, it will lead to excessive deflection. Therefore, according to the Eurocode3 specifications and stiffness requirements, 5 dimensions were selected as the optimized range, as is shown in Table 1. Considering the samples were distributed evenly, we added the samples through the L25 Taguchi orthogonal array method [41], as shown in Table 2, among which five samples were chosen as the test samples, as shown in Table 3. The total number of samples was 85 + 25, featuring 105 sets of training samples and 5 sets of test samples.

In the tables above, $h$ stands for the height of the ribs, $t_d$ stands for the thickness of the deck, $t_h$ stands for the thickness of the diaphragm and lining plate, $t_r$ stands for the thickness of the ribs, and $t_l$ stands for the thickness of the connection plate. The parameters above functioned as design variations, and the stress amplitudes of fatigue details were objective functions. The five construction parameters were used as input variations, and the stress amplitudes of five fatigue details were treated as output layers of the BPNN. After repetitive training on the BPNN through MATLAB software, the corresponding relationship between each construction parameter and the stress amplitude of each fatigue detail was obtained [22–26, 31]. The prediction ability of the BPNN was evaluated by comparing with the (radial basis function neural network) RBFNN [23, 25] and SVM [17–19].

5.2. Predicted Outcomes. We could obtain the predicted values of the stress amplitude of each fatigue detail according to the test samples in training Table 3. The calculated and predicted values of three models are shown in Figure 15. Performance of proposed models can be measured by using the mean square errors (MSEs), mean relative errors (MREs), and standard deviations (STD) [24–27], which are...
Formulas of the MSEs, MREs, and STD are shown in the following equations:

\[
\text{MSE} = \frac{1}{N} \sum_{i=1}^{N} (\alpha_{\text{pre}} - \alpha_{\text{cal}})^2 ,
\]

\[
\text{MRE} = \frac{1}{N} \sum_{i=1}^{N} \left| \frac{\alpha_{\text{pre}} - \alpha_{\text{cal}}}{\alpha_{\text{pre}}} \right|,
\]

\[
\text{STD} = \left( \frac{1}{N-1} \sum_{i=1}^{N} (\text{error} - \text{error})^2 \right)^{0.5}.
\]

It can be seen from Figure 15 and Table 4, the accuracy of BPNN, RBFNN, and SVM can reach more than 90%, which meant that three models were able to reflect the relationship between the design parameters and the stress amplitude. Compared with SVM, for multiobjective and multiparameter prediction, ANN had a better estimation. Compared with the two ANN models, the MSE, MRE, and STD of BPNN were smaller, which meant that BPNN had higher accuracy. In the process of prediction operation, the computing time of BPNN was 1.78 s, and the computing time of RBFNN was 1.45 s, which showed that RBFNN had a better efficiency.
Table 3: Test samples (unit: mm).

| Test samples | \( H \) | \( t_d \) | \( t_b \) | \( t_r \) | \( t_l \) |
|--------------|--------|--------|--------|--------|--------|
| 1            | 340    | 18     | 13     | 10     | 9      |
| 2            | 360    | 17     | 11     | 12     | 10     |
| 3            | 380    | 16     | 14     | 9      | 11     |
| 4            | 400    | 15     | 12     | 11     | 12     |
| 5            | 420    | 14     | 10     | 8      | 8      |

Figure 15: Continued.
5.3. Ensuring the Weight and the Objective Function. Considering that the impacts on different fatigue details are brought by changing the design parameters, to cover every fatigue detail and optimize the outcomes, we converted the multiobjective problem into a single-objective problem; thus, we need to determine the weight coefficient for each fatigue detail.

For an objective optimizing problem, we assigned each subobjective as a weight representing the importance of the subfunction in multiobjective optimizing problems, and the linear weight of each subobjective can be illustrated as

\[ f(x) = \sum_{i=1}^{n} w_i f_i(x), i = 1, 2, \ldots, n. \]  \hfill (4)

Considering the conditions, formula (4) can be rewritten as

\[ w_{ij} = \frac{\Delta \sigma_{ij}}{N_j} \times \lambda_j, \]  \hfill (5)

\[ S = \sum_{i=1}^{2} \sum_{j=1}^{4} w_{ij} \times s_{ij}, \]  \hfill (6)

\( w_{ij} \) stands for the expected values of the stress amplitude of the fatigue detail in different engineering conditions, \( i \) stands for the corresponding condition, and \( j \) stands for the corresponding fatigue detail. \( \Delta \sigma_{ij} \) is the average stress amplitude of the fatigue detail in different conditions, \( N_j \) is the 2,000,000 times fatigue level strength of the fatigue detail, where that of DC and RC are 71, that of RDI, RD, and RC are 80, according to the Eurocode 3 specifications; \( w_{ij} \) is the weight coefficient of the fatigue detail in different conditions. \( \lambda_j \) is the odd weight coefficient of the fatigue detail, which is inferred from existing statistical data through AHP.

The AHP forms the judging matrix through paired comparisons based on a 9-level scale and implements preference analysis by using matrix theories, finally obtaining the level-weight coefficients [42].

In reference [3], 7000 fatigue damage cases of orthotropic steel decks were analyzed, as shown in Figure 16 and Table 5, and the major types of cracks were obtained.

The fatigue cracks of deck-to-vertical stiffener weld accounted for a high proportion in 7000 fatigue damage cases, which has been cancelled in the current design of the orthotropic steel bridge deck [3]. The importance of each fatigue detail was ensured by the proportion of delicate parts.
To judge whether the created matrix could be accepted, the betweenthefatiguedetails,whichareneededtoberounded. The proportion of each fatigue detail is shown in Table 6. According to Table 6, we concluded that the judging matrix only considered the proportion of each detail, which is shown in the following formula:

\[
M = \begin{bmatrix}
1 & 1 & 1 & 8 \\
1 & 1 & 1 & 8 \\
1 & 1 & 1 & 8 \\
1/8 & 1/8 & 1/8 & 1 \\
\end{bmatrix}
\]

where \( m_{ij} = C_i/C_j \), \( C_n \) stands for the importance of the fatigue detail; here, it represents the proportion of each fatigue detail cracks. \( m_{ij} \) represents the relative importance between the fatigue details, which are needed to be rounded. To judge whether the created matrix could be accepted, the judging matrix needs to be calculated based on consistency evaluating indicators, as shown in the following formulas:

\[
C.R = \frac{C.I}{R.I}
\]

\[
C.I = \frac{(\lambda_{\text{max}} - n)}{(n - 1)}
\]

\( C.R \) is the consistent proportion to judge the matrix when \( C.R = 0 \), and the judging matrix is a perfectly consistent matrix; when \( C.R < 0.1 \), the judging matrix is a satisfying consistent matrix; \( \lambda_{\text{max}} \) is the max eigenvalue for the judging matrix; \( C.I \) is the indicator to judge the consistency of the matrix; \( R.I \) is the indicator to judge the random consistency of the matrix, which is relevant to the order of the judging matrix and is equal to 0.89 here.

After the calculation, the consistent indicator \( C.I = 0 \) refers to a perfect consistent matrix. The weights of the odds of occurrence of fatigue crack for DC, RDI, RD, and DL are 0.320, 0.320, 0.320, and 0.04, respectively.

According to the weight calculated through formula (6) under two different engineering conditions and after a series of standardizing processes based on the summation of the factors of each row of the matrix, the values are shown in the following formula:

\[
W = \begin{bmatrix}
0.443 & 0.139 & 0.411 & 0.007 \\
0.352 & 0.092 & 0.495 & 0.061 \\
\end{bmatrix}
\]

(10)

The value of the common weight coefficient was based on the literature [31], which is 1/4 of each fatigue detail under every condition.

### 5.4. Optimized Outcomes

SA is a universal optimizing algorithm that is able to go beyond the partial best solutions and refine the solutions to obtain the overall best solutions [43]. When smaller objective function values were not found after 1000 iteration calculations, the current minimum values were considered as the local optimal solution. In this paper, we adopted two different types of weight coefficients to optimize the stress amplitude in formula (6) through SA and obtained the best construction parameters, as shown in Table 7. The differences of the stress amplitude between the design sizes and the optimized sizes in this paper are shown in Figure 17. \( \delta = \Delta \sigma_o - \Delta \sigma_d \), where \( \delta \) stands for the optimized stress amplitude, \( \Delta \sigma_o \) stands for the stress amplitude of the corresponding optimized sizes, and \( \Delta \sigma_d \) stands for the stress amplitude of the corresponding design sizes.

To meet the requirements for actual engineering applications, the design parameters should be rounded up in Table 7. After the optimization mentioned above, the optimized outcomes of the two types of weights could both decrease the stress amplitude of each fatigue detail; compared with the common weight, except for RDI under engineering condition 2, AHP optimization results showed a better performance of declining stress amplitude. The optimized design parameter could effectively enhance the fatigue performance of the new orthotropic steel deck.
6. Conclusion

The main conclusions can be summarized as follows:

(1) Multiscale analysis models for the new orthotropic steel deck were established, and the calculated stress values of each fatigue detail coincided with the test outcomes, showing the reliability of the FE model.

(2) Considering different types of engineering conditions, the interfere surface for each fatigue detail of the new orthotropic steel deck was established, and the most unfavorable loading position of each fatigue detail was ensured.

(3) The relationship between the design parameters and stress amplitudes was obtained through BPNN, RBFNN, and SVM. Compared with SVM, ANN was more suitable for multiparameter and multiobjective prediction; compared with the two ANN models, BPNN had a better prediction performance and RBFNN had a better efficiency.

(4) A parameter-optimizing method for the new orthotropic steel deck based on BPNN-AHP-SA was proposed. Compared with the optimized outcomes gained by common weight coefficients, the optimized outcomes of the weight coefficients outlined in this essay were more efficient, and the optimized design parameters were able to substantially improve the fatigue performance of the new orthotropic steel deck.

Data Availability

The data used to support the findings of this study are available from Master Kewei Shi upon request through email (skw1@njtech.edu.cn).

Conflicts of Interest

The authors declare that they have no conflicts of interest.

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