Lévy flights on the half line

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We study the probability distribution function (pdf) of the position of a Lévy flight of index $0 < \alpha < 2$ in presence of an absorbing wall at the origin. The solution of the associated fractional Fokker-Planck equation can be constructed using a perturbation scheme around the Brownian solution (corresponding to $\alpha = 2$), as an expansion in $\epsilon = 2 - \alpha$. We obtain an explicit analytical solution, exact at the first order in $\epsilon$, which allows us to conjecture the precise asymptotic behavior of this pdf, including the first subleading corrections, for any $\alpha$. Careful numerical simulations, as well as an exact computation for $\alpha = 1$, confirm our conjecture.

I. INTRODUCTION

Random walks are trajectories consisting of a collection of random steps. They are employed to model the stochastic activity observed in many fields such as physics, biology, quantitative finance or computer science. As such they have been widely studied by mathematicians [1;3] and physicists [4;7]. One of the simplest example is given by a symmetric one dimensional random walker whose position, $x(n)$, after $n$ steps evolves, for $n \geq 1$, according to

$$x(n) = x(n-1) + \eta(n),$$  \hspace{1cm} (1)

starting from $x(0) = 0$. Moreover we consider random steps independent and identically distributed, according to a probability distribution $\varphi(\eta)$: consequently the random walk is Markovian and homogeneous.

Despite being simple to define, most of the properties of a random walk remain difficult to determine analytically. However, when the number of steps is large, the random walk displays a ”universal” behavior and the statistics of the position $x(n)$ becomes independent of most of the details of $\varphi(\eta)$. This asymptotic regime is the one we have more chance to characterize and it is often the one which is relevant for applications. In this limit, two cases should be distinguished. If $\varphi(\eta)$ is a narrow distribution the random walk exhibits a diffusive behavior, $x(n) \sim n^{1/2}$ and only the second moment of the step distribution, $\int_{-\infty}^{\infty} \eta^2 \varphi(\eta) d\eta = \sigma^2$, affects the statistics of $x(n)$. On the other hand if the random variables $\eta(n)$’s have a broad distribution, with a diverging second moment, i.e.

$$\varphi(\eta) \sim \frac{c}{|\eta|^{1+\alpha}}, \quad |\eta| \gg 1,$$  \hspace{1cm} (2)

with $0 < \alpha < 2$, the random walk exhibits a super-diffusive behavior $x(n) \sim n^{1/\alpha}$. Such power law distributions [2;4] have been initially studied in the early sixties in economy [8] and finance [9] and in the early eighties they started to proliferate in physics where they have found many applications ranging from disordered and glassy systems, super-diffusion in micellar systems, laser-cooling of cold atoms [10], random matrices [11], photons in hot atomic vapours [12] etc... One striking feature of such processes is that their statistical behavior is governed by a few rare events, whose occurrence are thus governed by the tail of the distribution.

Also in this case, when the number of steps becomes large, we expect that the statistics of $x(n)$ becomes independent of the details of $\varphi(\eta)$ except for the index $\alpha$ and the constant $c$. In particular, in absence of boundaries, the central limit theorem ensures that the propagator, $P(x,n)$, i.e. the probability to find the particle in $x$ after $n$ steps, converges to a stable distribution given by:

$$P(x,n) = \frac{1}{\mu^{1/\alpha}} R(y),$$  \hspace{1cm} (3)

$$\int_{-\infty}^{\infty} R(y) e^{iky} dy = e^{-|ak|^{\alpha}},$$  \hspace{1cm} (4)

where the parameter $a$ is related to the constant $c$ [see Eq. (3) below] and where we have introduced, from dimensional analysis, the rescaled variable

$$y \equiv \frac{x}{\mu^{1/\alpha}}.$$  \hspace{1cm} (5)

Although the Fourier transform of $R(y)$, its characteristic function, has a very simple expression [4;9], there is no simple closed form expression for $R(y)$, except for $\alpha = 1$ which corresponds to Cauchy distribution. It however admits the following asymptotic expansion, valid for any value of $\alpha$ [3]:

$$R(y) \sim \frac{1}{\pi |y|} \sum_{k=1}^{\infty} a^{\alpha k} \sin \left( \frac{ak\pi}{2} \right) \Gamma(\alpha k + 1)(-1)^{k+1} \frac{k!|y|^{\alpha k}}{k!|y|^{\alpha k}}.$$  \hspace{1cm} (6)
One thus sees on this expression that $R(y)$ inherits the power law tail of the step distribution \([2]\). One can further show \([2,3]\) that the amplitude itself is not renormalized such that to leading order

$$
R(y) \sim \frac{c}{y^{1+\alpha}} + \frac{d}{y^{1+2\alpha}} + O(y^{-1-3\alpha}) ,
$$

which fixes the value of $a$

$$
a^{\alpha} = \frac{\pi c}{\sin \left( \frac{\alpha \pi}{2} \right) \Gamma(\alpha + 1)} ,
$$

while $d$ can also be obtained explicitly from Eq. \((6)\).

Although free Lévy flights are thus perfectly well understood, there are physical situations which actually involve Lévy flights in a confined geometry. An interesting example is the Lévy flight model which has been proposed \([13]\) to describe the transports of solar photons in cloudy atmosphere. These photons are eventually reflected back to space or absorbed by the ground, so their trajectories are bounded random walks. In such cloudy atmosphere, whose heigth is typically of the order of 10 kms, the photons can be trapped in optically dense region (inside the clouds), travelling less than a meter between scatterings, while they can "fly" many kilometers from cloud to cloud. It was shown experimentally that Lévy flights provide a reliable description of the photons transport in such situations \([14]\). It was shown, in addition, that the one-dimensional model is a reasonable approximation of the three-dimensional geometry \([15]\). More recently, Lévy flights in confined geometry have also found applications in the context of random search problems \([16]\).

Obviously, when the walker is confined inside a domain, the central limit theorem does not apply, but the scaling analysis is still valid and the "universal" behavior of the rescaled position $y = x/n^{1/\alpha}$ is still expected. Computing the statistics of the rescaled variable $y$ in presence of confinement is in general possible for Brownian motion ($\alpha = 2$) for which powerful analytical tools are available such as path-integral techniques \([17,18]\). Unfortunately, for Lévy flights, analytical approaches are usually quite difficult. Recently a lot of papers advertised the possibility to write a Fractional Fokker-Planck equation for Lévy flight propagator \([6]\):

$$
\frac{\partial}{\partial t} P(x,t) = a^{\alpha} \frac{\partial^{\alpha}}{\partial |x|^{\alpha}} P(x,t) , \quad P(x,t = 0) = \delta(x) ,
$$

where the continuum time $t$ captures the large $n$ behavior of the random walk and the fractional operator, $\frac{\partial^{\alpha}}{\partial |x|^{\alpha}}$, is the Riesz-Feller derivative of fractional order $\alpha > 0$ \([19,20]\), which has an integral representation involving a singular kernel of power-law form. In absence of boundaries this equation can be simply written in Fourier space

$$
\frac{\partial}{\partial t} \hat{P}(k,t) = -|ak|^{\alpha} \hat{P}(k,t) , \quad \hat{P}(k,t = 0) = 1 ,
$$

and it is easy to check that the free propagator introduced in Eq. \((3)\) is a solution of Eq. \((10)\), (with the identification, $t \rightarrow n \gg 1$).

In presence of boundaries the translational invariance is broken and the Fourier representation becomes useless. For $\alpha = 2$, when the fractional operator becomes the standard Laplacian, the method of images allows to express the propagator in presence of boundaries as a linear combination of free propagators. Unfortunately we will see that these techniques can not be applied, for $\alpha < 2$ \([21,22]\). More generally, if translational invariance is lost, the fractional Fokker-Planck equation in Eq. \((9)\) becomes a difficult integro-differential equation with non-local boundary conditions. One could conclude that the Fokker-Planck formalism is of little help for Lévy flights. However, following a recent work by Zoia, Rosso and Kardar \([23]\), we show that Eq. \((9)\) can be studied also in presence of boundaries using a perturbation theory where the small parameter $\epsilon \ll 1$ is $\alpha = 2 - \epsilon$. At variance with the method of Ref. \([23]\) we perform this perturbation theory directly in the continuum limit without resorting to a discretization (in space) of the trajectories. The calculations turn out to be somewhat simpler in this continuum setting.

For concreteness we will study in detail the case where there is an absorbing wall in $x = 0$ as depicted in Fig. \(1\). We thus consider only the paths that remain positive up to the $n$th step. In the limit of large $n$ the probability density function to find the particle in $x$ after $n$ time steps also takes the scaling form, as in Eq. \((3)\):

$$
P_{+}(x,n) = \frac{1}{n^{1+\alpha}} R_{+}(y) .
$$

We emphasize that $R_{+}(y)$, being a probability density function, is normalized, i.e. $\int_{0}^{\infty} R_{+}(y) dy = 1$, while, in Ref. \([21]\) Zumofen and Klafter studied a similar quantity, which is however not normalized (see also Ref. \([24]\)). In particular, they were able to show that the small ar-

![Final position](image-url)
argument behavior of \( R_+(y) \) is given by [21] [25]

\[
R_+(y) \sim y^{\alpha/2} ,
\]

in contrast with the method of images that would predict \( R_+(y) \sim y \). Our perturbative approach allows us to conjecture the exact behavior of the tail of \( R_+(y) \), which controls the statistics of rare events:

\[
R_+(y) = \frac{c_+}{y^{1+\alpha}} + \begin{cases} 
\frac{d_+}{y^{1-\alpha}} + o(y^{-2-\alpha}) , & 2 > \alpha > 1 , \\
\frac{d_-}{y^{1-\alpha}} + o(y^{-1-2\alpha}) , & 1 > \alpha > 0 . 
\end{cases}
\]

To our knowledge, only the exponent of the leading term \( R_+(y) \propto y^{-1-\alpha} \), was known from Ref. [21]. Here we obtain the exact result for the amplitude \( c_+ \)

\[
c_+ = 2c ,
\]

where \( c \) is the amplitude of the tail of the jump distribution [2]. In addition, the first sub-leading corrections in Eq. [13], by comparison to the free case [7], also bear the fingerprints of the absorbing wall. These results are first obtained analytically for \( \alpha \) close to 2, i.e. \( \alpha = 2 - \epsilon \), using a perturbation theory to first order in \( \epsilon \). We also obtain this behavior for \( \alpha = 1 \), albeit with logarithmic corrections for the subleading term, for which an exact calculation can be done. We then demonstrate this behavior using thorough numerical simulations.

The paper is organized as follows. In Section II we present the general framework of the perturbation scheme. We first illustrate it on the simplest example of the free propagator in Section II A, and then in Section II B we study the case with an absorbing boundary at the origin. The discussion of the results is left in Section II C. Section III contains the results of our numerical simulations and our conclusions are in section IV. The Appendices A, B, C contain some technical details.

II. PERTURBATION SCHEME

In this section, we set \( \alpha = 1 \) for simplicity and without loss of generality, and write the Fractional Fokker-Planck equation [9] in the familiar Schrödinger form

\[
\partial_t P(x, x_0, t) = \mathcal{H} P(x, x_0, t) ,
\]

\[
P(x, x_0, t = 0) = \delta(x – x_0) ,
\]

where the propagator \( P(x, x_0, t = 0) \) represents the probability density to find a particle in the interval \([x, x + dx] \) at time \( t \), knowing that the particle was in \( x_0 \) at time \( 0 \) and the operator \( \mathcal{H} \) is the fractional operator of index \( \alpha \). In Quantum Mechanics Eq. [15] corresponds to the Schrödinger equation of the element \((x, x_0)\) of the density matrix \( P \) at the temperature \( 1/t \). The general solution of Eq. [15] reads

\[
P(x, x_0, t) = \int dq \psi_q^*(x_0) \psi_q(x)e^{E(q)t} ,
\]

where \( E(q) \) are the eigenvalues and \( \psi_q(x) \) the associated eigenfunctions of the operator \( \mathcal{H} \). They are solutions of the eigenvalue problem, \( \mathcal{H}\psi_q(x) = E(q)\psi_q(x) \), with the appropriate boundary conditions and satisfy the orthogonality and closure relations:

\[
\int \psi_q(x)\psi_q^*(x')dx = \delta(q – q') ,
\]

\[
\int \psi_q(x)\psi_q^*(x')dq = \delta(x – x') .
\]

Please note that the domain of integration over \( x \) depend on the boundary condition and the integration over \( q \) is meant over the all spectrum. If the spectrum is discrete the integral is replaced by a discrete sum.

The eigenvalue problem of the operator \( \mathcal{H} \) is in general very difficult and the solution is known only in the absence of boundaries where the eigenfunctions are simple plane waves. The case \( \alpha = 2 \) corresponds to the standard Laplacian for which a lot of results are known. In particular the spectrum can be exactly solved in one dimension. A possible strategy to gain insights on the behavior of a Lévy flights in presence of boundaries is to use the perturbation scheme around the well studied \( \alpha = 2 \) case. For \( \alpha = 2 - \epsilon \) the operator \( \mathcal{H} \) and the propagator can be expanded in powers of \( \epsilon \),

\[
P(x, x_0, t) = P^{(0)}(x, x_0, t) - \epsilon P^{(1)}(x, x_0, t) + \mathcal{O}(\epsilon^2)
\]

\[
\mathcal{H} = \mathcal{H}_0 - \epsilon \mathcal{H}_1 + \mathcal{O}(\epsilon^2) ,
\]

where \( P^{(0)}(x, x_0, t) \) is the propagator associated to \( \mathcal{H}_0 = \partial_x^2 \), with the prescribed boundary conditions. The expression of the first correction \( P^{(1)}(x, x_0, t) \) in Eq. [20] is well known from Quantum Mechanics and it is re-derived in Appendix A. It reads, writing \( P^{(1)} \equiv P^{(1)}(x, x_0, t) \):

\[
P^{(1)} = \int_q \int_{q'} \psi_q(x)\psi_q^*(x_0)e^{E(q)t}e^{-E(q')}t \langle q|\mathcal{H}_1|q'\rangle ,
\]

where we use the notation \( \int_q \equiv \int dq \) and where it is understood here that \( \psi_q(x) \) are the eigenvectors and \( E(q) \) the corresponding eigenvalues of \( \mathcal{H}_0 \) and for the matrix elements \( \langle q|\mathcal{H}_1|q'\rangle \) we use the bra-ket notation, borrowed from Quantum Mechanics with \( \langle x|q\rangle = \psi_q(x) \). This formula [21] is the cornerstone of the perturbation approach presented here.

A. Absence of boundaries

We first illustrate this perturbative approach by computing the first order correction to the Brownian propagator in absence of boundaries, i.e. the Gaussian propagator, when \( \alpha = 2 - \epsilon \) and \( x_0 = 0 \). In this simple case the eigenvalue problem of \( \mathcal{H}_0 = \partial_x^2 \) gives:

\[
\psi_q(x) = \frac{1}{\sqrt{2\pi}}e^{iqx} ,
\]

\[
E(q) = -q^2 ,
\]

\[
-\infty < q < \infty .
\]
Using that $k^{2-\epsilon} = k^2 - \epsilon k^2 \log |k| + \mathcal{O}(\epsilon^2)$, the matrix element $\langle q | \mathcal{H}_1 | q' \rangle$ can be explicitly computed:

$$\langle q | \mathcal{H}_1 | q' \rangle = \int \int dx_1 \, dx_2 \, \frac{dk}{2\pi} \, \psi_q(x_1) \psi_{q'}(x_2) \times k^2 \log |k| e^{ik(x_1 - x_2)} = \delta(q - q') y^2 \log |q|,$$

where the integral over $x_1, x_2, k$ is performed over the whole real axis. Note that, thanks to the oscillating term $e^{ik(x_1 - x_2)}$, the integral over $k$ in (23) is dominated by the small values of $k$ where one can safely expand $k^{2-\epsilon}$ in powers of $\epsilon$. From Eq. (21) one obtains:

$$P^{(1)}(x, t) = -t \int_0^\infty dq \, q^2 \log q \, e^{-q^2 t}. \tag{24}$$

Using $k = q \sqrt{t}$ and the scaling variable $z = x / \sqrt{t}$, Eq. (24) can be recast in a simpler form

$$\sqrt{t} P^{(1)}(x, t) = R_A(z) + R_B(z) \log t, \tag{25}$$

$$\begin{align*}
R_A(z) &= -\int_0^\infty \frac{dk}{\pi} \cos k z \, k^2 \log k \, e^{-k^2}, \\
R_B(z) &= \int_0^\infty \frac{dk}{2\pi} \cos k z \, k^2 \, e^{-k^2}. \tag{26}
\end{align*}$$

From scaling argument one expects (3)

$$\begin{align*}
\sqrt{t} P^{(1)}(x, t) &= \frac{1}{t^{1/\alpha}} \log t \\
R_A(z) &= \frac{1}{2 \sqrt{\pi}} e^{-y^2/4}, \\
R_B(z) &= \frac{2}{\alpha} z \log t + \frac{4}{\alpha} \log \Gamma(1 + \frac{z}{\sqrt{t}}) R_0(z). \tag{30}
\end{align*}$$

This can be done if in the equation $t^{1/\alpha} P(x, t) = R(y)$ we expand at the first order in $\epsilon$ both $t^{1/\alpha} \sim \sqrt{t} + \frac{z}{4} \sqrt{t} \log t$ and $y \sim z + \frac{3}{4} z \log z$. After some simple algebra we can write

$$\sqrt{t} P^{(1)}(x, t) = R^{(1)}(z) + \frac{3}{4} \log t \left( 1 + z \partial_z \right) R^{(0)}(z). \tag{31}$$

Comparing with Eq. (25) we identify $4 R_B(z) = R^{(0)}(z) + z \partial_z R^{(0)}(z)$ so that we conclude that $R^{(1)}(y)$ in Eq. (29) is given by:

$$R^{(1)}(y) = -\int_0^\infty \frac{dk}{\pi} \cos k y \, k^2 \log k \, e^{-k^2}. \tag{32}$$

By performing an asymptotic analysis of Eq. (32) for large $y$ one finds a series expansion of $R(y)$ given in Eq. (29) which converges nowhere but exists as a formal power series:

$$R(y) \sim \epsilon \sum_{k=1}^{\infty} \frac{(2k)!}{2(k-1)!} \frac{1}{y^{2k+1}} \sim \epsilon \left( \frac{1}{y^2} + \frac{12}{y^4} + \frac{180}{y^6} + \ldots \right).$$

This result is in perfect agreement with the expansion given in Eq. (3) for $\alpha = 2 - \epsilon$.

### B. Propagator in presence of an absorbing boundary at $x = 0$

We consider now $G_+(x, x_0, t) \, dx$, the probability to find a particle in the interval $[x, x + dx]$ at time $t$, knowing that the particle was in $x_0$ at time $0$ and given that it stayed positive up to time $t$ (see Fig. 1). At variance with the free propagator, the integral over $x$ of $G_+(x, x_0, t)$ is smaller than one and gives the fraction of surviving walker up to time $t$ (i.e. the survival probability). In the geometry defined by Eq. (1) the initial position of the discrete random walk is $x_0 = 0$. Here we are considering a process which is continuous in time and this initial condition $x_0 = 0$, together with the presence of an absorbing boundary at the origin is ill-defined. Indeed, it is well known that if the continuous time walker crosses zero once it will re-cross zero infinitely many times immediately after the first crossing. Therefore, it is impossible to enforce the constraint $x_0 = 0$ and simultaneously forcing the position of the continuous time walker to be strictly positive immediately after. Therefore we set $x_0 > 0$ and small in order to regularize the continuous time process and we will take the limit $x_0 \to 0$ at the end of the calculation. Our final result corresponds to the geometry of the Eq. (1) in the limit of a large number of steps.

It is useful to express $G_+(x, x_0, t)$ in terms of rescaled variables as in Eq. (35):

$$G_+(x, x_0, t) = \frac{1}{t^{1/\alpha}} Z(y, y_0). \tag{33}$$

The scaling function $Z(y, y_0)$ depends explicitly on $\alpha$ and we compute it here in perturbation theory for $\epsilon = 2 - \alpha \ll 1$:

$$Z(y, y_0) = Z^{(0)}(y, y_0) - \epsilon Z^{(1)}(y, y_0) + \mathcal{O}(\epsilon^2). \tag{34}$$

In presence of an absorbing boundary at the origin, the action of the fractional operator can be written as

$$\int_0^\infty dx' \, \psi_q(x') \int_{-\infty}^{\infty} \frac{dk}{2\pi} \langle -|k|^{\alpha} e^{ik(x-x')} \rangle = E(q) \psi_q(x), \tag{35}$$

and the solution is known only for $\alpha = 2$:

$$\psi_q(x) = \theta(x) \sqrt{\frac{2}{\pi}} \sin(qx) , \quad E(q) = -q^2, \quad q > 0, \tag{36}$$

where $\theta(x)$ is the Heaviside function: $\theta(x) = 1$ if $x \geq 0$ and $\theta(x) = 0$ if $x < 0$. At zeroth order in $\epsilon$,
the scaling function \( Z^{(0)}(y, y_0) \) can be computed from Eq. (17) with \( \psi_q(x) \) given in Eq. (36). Using the identity

\[
2 \sin(k y) \sin(k y_0) = \cos[k(y - y_0)] - \cos[k(y + y_0)]
\]

one obtains:

\[
Z^{(0)}(y, y_0) = \theta(y)\theta(y_0) \int_0^{\infty} \frac{dk}{\pi} e^{-k^2} \left( \cos[k(y - y_0)] - \cos[k(y + y_0)] \right).
\]

Let us note that the same result can be straightforwardly obtained using the method of images:

\[
Z^{(0)}(y, y_0) = \theta(y)\theta(y_0) [R^{(0)}(y-y_0)-R^{(0)}(y+y_0)].
\]

At the first order in \( \epsilon \) we first compute the matrix element \( \langle q | H_1 | q' \rangle \) which has the form given in Eq. (23) with the prescription that the integrals over \( x_1 \) and \( x_2 \) are performed over the interval \((0, \infty)\) and \( \psi_q(x) \) are the eigenvectors given in Eq. (36). The integrals over \( x_1 \) and \( x_2 \) need to be regularized to be well defined and this can be done via the identity:

\[
\lim_{\epsilon \to 0} \int_0^{\infty} \frac{dx}{\pi} e^{ikx-\epsilon x} \sin(qx) = PV \frac{q}{\pi(k^2 - q^2)} + \frac{i}{2} (\delta(q-k) - \delta(q+k)),
\]

where \( PV \) indicates a principal value. After some algebra, left in the Appendix B one gets [see Eq. (B11)]:

\[
\langle q | H_1 | q' \rangle = \delta(q-q')q^2 \log |q| + \frac{qq'}{2(q+q')}.
\]

Combining the latter equation with Eq. (21) we can write an expression for \( P_+^{(1)}(x, x_0, t) \). Analogously to the case of the propagator in absence of boundaries, the integrals involved in the expression of \( P_+^{(1)}(x, x_0, t) \) can be naturally recast in term of the variables \( z = x/\sqrt{t} \) and \( z_0 = x_0/\sqrt{t} \) instead of the correct scaling variables \( y \) and \( y_0 \). Following the same lines of the previous discussion we easily write the scaling function \( Z^{(1)}(y, y_0) \) as:

\[
Z^{(1)}(y, y_0) = Z_A(y, y_0) + Z_B(y, y_0),
\]

\[
Z_A(y, y_0) = R^{(1)}(y-y_0) - R^{(1)}(y+y_0),
\]

\[
Z_B(y, y_0) = \int dk_1 dk_2 k_1 k_2 e^{ik_1 z_0 - ik_2 z_0} \frac{k_1 k_2 (k_1^2 - k_2^2)}{\pi(k_1^2 + k_2^2)(k_1^2 - k_2^2)} \sin(k_1 y) \sin(k_2 y_0),
\]

where the integrals over \( k_1, k_2 \) run over the interval \((0, \infty)\). It is worth to stress that the term \( Z_A \) corresponds to the images method prediction while the term \( Z_B \) represents the violation of the images prediction at the first order level.

It is easy to realize that the probability density function \( R_+(y) \) is simply related to \( Z(y, y_0) \) in the following way:

\[
R_+(y) = \lim_{y_0 \to 0} \int_0^{\infty} dy' \frac{Z(y, y_0)}{Z(y', y_0)}.
\]

For \( \alpha = 2 \) one has from Eq. (38) in the limit \( y_0 \to 0 \):

\[
Z^{(0)}(y, y_0) = y_0 Z^{(0)}(y) + O(y_0^2), \quad Z^{(1)}(y) = \frac{y}{2\sqrt{\pi}} e^{-\frac{y^2}{4}},
\]

which yields

\[
R_+(y) = \frac{y}{2} e^{-\frac{y^2}{4}}.
\]

The integrals in Eqs. (42) and (43) which give the term \( R_+^{(1)}(y) \) have to be discussed carefully and the details are left in the Appendix C. The net result of this analysis is that \( R_+(y) \) can be written as

\[
R_+(y) = R^{(0)}_+(y) (1 + c W_+(y) + O(\epsilon^2)),
\]

where \( W_+(y) \) can be expressed in terms of elementary and special functions, see Eq. (C18). From this expression, one obtains the asymptotic behaviors of \( R_+(y) \). In the limit \( y \to 0 \), one finds

\[
R_+(y) \sim \frac{y}{2} - \frac{\epsilon^2}{4} (\log y + \kappa) + O(y^2 \log y, \epsilon^2),
\]

where \( \kappa = 2 - \log 2 - \frac{3}{2} \gamma_E \). In particular, the small \( y \) behavior in Eq. (48) is consistent with \( R_+(y) \sim y^2 \) in agreement with previous findings [21, 23]. For \( y \to \infty \) one finds

\[
R_+(y) \sim \epsilon \left( \frac{2}{y^3} + \frac{3\sqrt{\pi}}{y^2} + \frac{32}{y^5} \right) + O(y^{-6}, \epsilon^2),
\]

where the leading term, vanishing as \( 1/y^3 \), is expected from previous analysis [21]. We notice that the right tail of the \( R_+(y) \) has the same behavior as the right tail of \( R(y) \). Quite interestingly, our perturbative result shows that

\[
c_+ \equiv \frac{c}{c} = \lim_{y \to \infty} \frac{R_+(y)}{R(y)} = 2 + O(\epsilon),
\]

where \( c \) and \( c_+ \) are defined in Eq. (7) and Eq. (13) respectively. Another signature of the boundary, revealed by this perturbative calculation, appears in the sub-leading correction which vanishes as \( 1/y^4 \) for \( R_+(y) \) [see Eq. (49)] instead of \( 1/y^5 \), as for \( R(y) \) [see Eq. (43)].

C. Discussion and conjectures

It is interesting to compare our perturbative results, valid in principle for \( 2 - \alpha \ll 1 \), with the exact results which we can obtain for the special case \( \alpha = 1 \). In this case, corresponding to Cauchy random variables, i.e. \( \varphi(\eta) = \pi^{-1} (1 + \eta^2)^{-1} \), one can use the results which were obtained by Darling [20] and Nevzorov [27] in the context of the extreme statistics of such Lévy statistics, to obtain an exact result for \( R_+(z) \) in terms of a single integral:

\[
R_+(z) = -\sqrt{z} \int_0^1 g \left( \frac{z}{v} \right) v^{-3/2} (1-v)^{-1/2} dv.
\]

\[
g(z) = \frac{d}{dz} \left[ \frac{1}{\pi} \frac{1}{(1+z^2)^{3/4}} \exp \left( -\frac{1}{\pi} \int_0^z \frac{\log u}{1+u^2} du \right) \right].
\]
Its asymptotic behaviors are given by

\[ R_+(z) \sim \frac{1}{2} \sqrt{z}, \quad z \to 0 \]  
\[ R_+(z) \sim \frac{2}{\pi} \frac{z}{z^2} + \frac{16}{3} \log z + \mathcal{O}(z^{-3}), \quad z \to \infty. \]  

On the other hand, one has in this case \( R(y) \sim 1/(\pi y^2) \) when \( y \to \infty \) such that one obtains also in this case \( \alpha = 1 \)

\[
\frac{c_+}{c} = \lim_{y \to \infty} \frac{R_+(y)}{R(y)} = 2. 
\]  

Based on the perturbative result obtained above \( \alpha = 1 \) and on this exact result \( \alpha = 2 \), we conjecture that this relation \( c_+ = 2c \) actually holds for all value of \( \alpha \), as stated in the introduction. This conjecture is corroborated below by our numerical simulations.

Besides, we interpret the exponent of the sub-leading correction in \( R_+(y) \), which decays as \( 1/y^4 \) in Eq. (49), as \( 4 = 2 + \alpha \), with \( \alpha = 2 + \mathcal{O}(\epsilon) \) while the sub-leading corrections in \( R(y) \) decay as \( 1/y^5 \) with, instead \( 5 = 1 + 2\alpha \), for \( \alpha = 2 + \mathcal{O}(\epsilon) \). This leads us to conjecture that the subleading corrections behave actually differently for \( \alpha > 1 \) or \( \alpha < 1 \), as announced in the introduction.

\[
R_+(y) = \frac{c_+}{y^{1+\alpha}} + \begin{cases} 
\frac{d_+}{y^{4+\alpha}} + o(y^{-2-\alpha}), & 2 > \alpha > 1, \\
\frac{d_+}{y^{2+\alpha}} + o(y^{-1-2\alpha}), & 1 > \alpha > 0.
\end{cases} 
\]

Hence \( \alpha = 1 \) appears as a critical value regarding these sub-leading corrections, for which it is not surprising to observe logarithmic corrections \( \mathcal{O}(\epsilon) \). This also implies that the coefficient \( d_+ \) above is diverging when \( \alpha \to 1 \) from above. Below, we will test this behavior by means of numerical simulations.

### III. NUMERICAL SIMULATIONS

We consider the case where the increments distribution \( \phi(\eta) \) is the symmetric Pareto distribution:

\[
\phi(\eta) = \begin{cases} 
\frac{\alpha}{|\eta|^{\alpha+1}}, & \text{for } |\eta| > 2^{\frac{1}{\alpha}}, \\
0, & \text{otherwise.}
\end{cases} 
\]  

This distribution can be sampled efficiently using random number drawn from a uniform distribution:

\[
\eta = \begin{cases} 
[\text{ran}(0,1/2)]^{-1/\alpha}, & \text{with probability } \frac{1}{2}, \\
-\left[\text{ran}(0,1/2)\right]^{-1/\alpha}, & \text{with probability } \frac{1}{2},
\end{cases} 
\]

where \( \text{ran}(0,1/2) \) is a random number in the interval \( (0,1/2) \).

We construct a large number of random walks, for each random walk we record the final position \( x(n) \) after \( n \) steps and compute the correspondent rescaled variable \( y = x(n)/n^{1/\alpha} \). We first present our data for \( \alpha = 1.5 \), for which \( \phi(\eta) = 1.5/|\eta|^{3/2} \) for \( |\eta| > 2^{3/2} \). For large \( n \) the distribution of \( y \) should converge to the a stable distribution centered around 0 and with an asymptotic tail

\[
R(y) = \frac{3}{2y^{5/2}} + \frac{24}{y^3} + o(y^{-4}). 
\]  

This prediction is confirmed by our direct simulation, in Fig. 2 we show that the tail of \( \phi(\eta) \) and \( R(y) \) coincide when \( \eta, y \to \infty \). The symmetric distribution \( R(y) \) is also plotted in Fig. 3 where we also show \( R_+(y) \), the histogram of the rescaled final position of the random walks constrained to be positive. \( R_+(y) \) is clearly defined only for positive \( y \), vanishes at \( y = 0 \) and, when \( y \to \infty \), decays as \( c_+/y^{5/2} \). One of our main prediction is that, for large \( y \), \( R_+(y)/R(y) = 2 \) which means \( c_+ = 3 \) for our model. This is verified in Fig 4.
A. Finite size effect and different values of $\alpha$

Stable distributions and universal behavior are expected in the limit of a large number of steps (i.e. $n \to \infty$). In our numerical simulation the asymptotic behavior of $R(y)$ and $R_{+}(y)$ is studied for $n = 1000$. Is this number enough to capture universality? In Fig. 4 and Fig. 5 we study how the finite number of steps affect the function $R_{+}(y)$. Finite size effects are visible close to the boundary $y = 0$ where, only for very large size, the distribution vanishes with the predicted exponent $\alpha/2 = 0.75$. For $y \simeq 10$ the convergence with the size $n$ becomes faster and the constant

$$c_{+} = \lim_{y \to \infty} R_{+}(y) y^{\alpha+1}$$

(59)

can be correctly estimated even with a moderate number of steps (see Fig. 6).

Finally we have checked that our result for $c_{+}$ apply to all range of $0 < \alpha < 2$ for symmetric Lévy flights. The asymptotic tail is more and more pronounced as $\alpha \ll 2$. This means that the insights given by our perturbative calculation are actually valid for all Lévy flights (see Fig. 7).
B. Subleading corrections

We also check the behavior of the sub-leading correction \( \delta \beta \). For \( \alpha > 1 \) this correction is expected to behave like \( d_+ y^{-\alpha - 1} \), while for \( \alpha < 1 \) we expect that it decays as \( \sim d_+ y^{-2\alpha - 1} \). This prediction is confirmed in Fig. 8 for \( \alpha > 1 \) and Fig. 9 for \( \alpha < 1 \).

![Fig. 8](image)

FIG. 8. Sub-leading correction for \( \alpha = 1.25 > 1 \). Random walks constrained to be positive for \( n = 1000 \) steps. Histograms are performed over \( 10^8 \) samples. The plateau reached at large \( y \) gives a numerical estimation of \( d_+ \).

![Fig. 9](image)

FIG. 9. Sub-leading correction for \( \alpha = 0.5 < 1 \). Random walks constrained to be positive for \( n = 1000 \) steps. Histograms are performed over \( 10^7 \) samples. The plateau reached at large \( y \) gives a numerical estimation of \( d_+ \).

IV. CONCLUSION

To conclude, we have presented a perturbative approach to the study of a Lévy flight, of index \( 0 < \alpha < 2 \) on a half-line, where the perturbative parameter is \( \epsilon = 2 - \alpha \). This approach, following the work of Zoia, Rosso and Kardar \[23\], amounts to construct a perturbative solution of the fractional Fokker-Planck equation \[9\] with appropriate (non-local) boundary conditions. Here, at variance with Ref. \[23\] the perturbation theory is carried out directly for a process which is continuous both in space and time.

We have then used this perturbative method to compute, to order \( O(\epsilon) \), the probability density function, \( R_+ \), of the position of such a walker with an absorbing wall at the origin. A different perturbation scheme (based on path integral) was used recently \[28\] to compute the same quantity for the fractional Brownian motion, a non-Markovian process displaying anomalous diffusion. Our main result here is to give a precise conjecture, valid for any value of \( \alpha \), on the relation between the tail of this distribution and the tail of the steps of the random walk. Numerical simulation confirm our conjecture.

This perturbative scheme opens the way to an analytical study and can be used for any confined domain for which the Brownian solution, corresponding to \( \alpha = 2 \), is known. More realistic confined geometry, like the one relevant to the scattering of solar photons, can be studied along these lines. Here we have proposed the simplest of these geometries. A first extension of the present study concerns the study of the extreme statistics of a Lévy bridge, which is a Lévy random walk on the time interval \([0,t] \) constrained to start and end at the origin. Such a constrained Lévy random walk, for which little is known, has recently received some attention in statistical physics \[29\] – in relation with some real-space condensation phenomena –, as well as in finance \[30\]. Another interesting application of such a perturbative calculation could be the study of non-intersecting Lévy walkers, the so-called "vicious" Lévy walkers, which were recently introduced in Ref. \[31\].

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Appendix A: Perturbative scheme to order \( O(\epsilon) \)

In this appendix we give a short derivation of the expression for the first correction \( P^{(1)}(x,x_0,t) \) \[20\] given in Eq. \[21\]. The equation for \( P^{(1)}(x,x_0,t) \) reads, see Eqs.
\( [15, 20] \): 
\[
\partial_t P^{(1)}(x, x_0, t) = \mathcal{H}_0 P^{(1)}(x, x_0, t) + \mathcal{H}_1 P^{(0)}(x, x_0, t),
\]
with the initial conditions \( P^{(1)}(x, x_0, t=0) = 0 \) and \( P^{(0)}(x, x_0, t) \) is given in [17]. Eq. (A1) is inhomogeneous and we can obtain its solution using the method of variation of constants. We look for a solution under the form
\[
P^{(1)}(x, x_0, t) = \int c^{(1)}_q(t) \psi_q(x)e^{E(q)t}dq,
\]
where \( \psi_q \) and \( E(q) \) are the eigenvectors and eigenvalues of \( \mathcal{H}_0 \), while the coefficient \( c^{(1)}_q(t) \) depends explicitly on time \( t \). Plugging Eqs. (A2) and (17) into (A1) one finds
\[
\int dq' e^{E(q')t}\psi'_{q'}(x)\partial_t c^{(1)}_q(t) = \int dq' e^{E(q')t}\psi'_{q'}(x_0)\mathcal{H}_1 \psi_{q'}(x).
\]
We multiply the left and right hand sides of Eq. (A3) by \( \psi^*_q(x) \) and we then integrate both sides over \( x \). Using the normalization relation \( \int dx \psi^*_q(x) \psi_q(x) = \delta(q-q') \) we obtain
\[
c^{(1)}_q(t) = \int dq' \langle q|\mathcal{H}_1|q'\rangle \psi^*_q(x_0)e^{E(q')t}, \tag{A5}
\]
where we have used the bra-ket notation, borrowed from Quantum Mechanics, and such that \( \langle x|q\rangle = \psi_q(x) \). This can be straightforwardly integrated, using the boundary condition at time \( t = 0 \)
\[
c^{(1)}_q(t) = \int dq' \langle q|\mathcal{H}_1|q'\rangle \psi^*_q(x_0)\frac{e^{E(q')t} - e^{E(q)t}}{E(q) - E(q')} \tag{A6}
\]
Combining (A6) and (A2) one obtains Eq. (20) given in the text.

**Appendix B: Evaluation of an integral**

Here we compute the principal value of the integral entering the matrix element in Eq. (40),
\[
I(q, q') = \text{PV} \int_{-\infty}^{\infty} dk \frac{q'k^2 \ln |k|}{\pi^2(k^2 - q'^2)(k^2 - q^2)}
\]
\[
= \frac{2q'^2}{\pi^2} \text{PV} \int_0^{\infty} dk \frac{k^2 \ln k}{(k^2 - q'^2)(k^2 - q^2)}. \tag{B1}
\]
Without any loss of generality, since \( I(q, q') = I(q', q) \), we assume \( q' \geq q \). Performing the change of variable \( k = s q \), one obtains straightly
\[
I(q, q') = \frac{2q'}{\pi^2} f_1 \left( \frac{q'}{q} \right) \ln q + \frac{2q'^2}{\pi^2} f_2 \left( \frac{q'}{q} \right), \tag{B2}
\]
where
\[
f_1(x) = \text{PV} \int_0^{\infty} ds \frac{s^2}{(s^2 - 1)(s^2 - x^2)}, \tag{B3}
\]
\[
f_2(x) = \text{PV} \int_0^{\infty} ds \frac{s^2 \ln s}{(s^2 - 1)(s^2 - x^2)}. \tag{B4}
\]
We notice that \( f_2(x) \) can be written as
\[
f_2(x) = f_1(x) \ln x + \text{PV} \int_0^{\infty} ds \frac{\ln(s/x)}{(s^2 - 1)(s^2 - x^2)}. \tag{B5}
\]
The purpose of this trick (B5) is that the integrand has now only a simple pole in \( s = 1 \) so that, taking the principal value, yields a perfectly smooth function of \( x \). This integral can then be evaluated to yield:
\[
f_2(x) = f_1(x) \ln x + \frac{\pi^2}{4(1 + x)}, \tag{B6}
\]
so that one has
\[
I(q, q') = \frac{2q'}{\pi^2} f_1 \left( \frac{q'}{q} \right) \ln q' + \frac{q q'}{2(q + q')}. \tag{B7}
\]
Looking at the expression of \( f_1(x) \) above (B3), one sees that for \( x = 1 \), the integrand has a double pole in \( s = 1 \) and one thus expects \( f_1(x) \) to be highly singular in \( x = 1 \). To characterize it, we compute its Fourier transform
\[
\hat{f}_1(p) = 2 \int_0^{\infty} dx f_1(x) \cos(px), \tag{B8}
\]
which yields after straightforward manipulations of Eq. (B3) (which can be done e.g. with Mathematica)
\[
\hat{f}_1(p) = \frac{\pi^2}{2} \cos p, \tag{B9}
\]
which yields
\[
f_1 \left( \frac{q'}{q} \right) = \frac{\pi^2 q}{4} \delta(q-q'), \tag{B10}
\]
and finally
\[
I(q, q') = \delta(q-q') \frac{1}{2} q^2 \ln q + \frac{q q'}{2(q + q')}, \tag{B11}
\]
which is used in the Eq. (40) in the text.

**Appendix C: Details about the perturbative calculation of the propagator with an absorbing wall**

This appendix is devoted to the analysis of \( Z^{(1)}(y, y_0) \) given by the sum of the two terms in Eqs. (41, 42, 43) in the limit \( y_0 \to 0 \). The first term \( Z_A(y, y_0) \) is easy to analyse and yields
\[
Z_A(y, y_0) = -2 y_0 \partial_y P^{(1)}(y) + O(y_0^2), \tag{C1}
\]
where \( P^{(1)}(y) \) admits the integral representation given in Eq. (32).
The analysis of the small $y_0$ behavior of $Z_B(y, y_0)$ given in Eq. (43) is more subtle. To deal with this double integral over $k_1$ and $k_2$, we first make the change of variable $k_1 = u'$ and $k_2 = uu'$ and observe that the integral over $u'$ can then be performed to yield

$$Z_B(y, y_0) = \frac{1}{4\sqrt{\pi}} \int_0^\infty \frac{du}{u^2(u + 1)^2} \left[ e^{-\frac{(y+y_0)^2}{4u^2}} - e^{-\frac{(y-y_0)^2}{4u^2}} \right] = \frac{1}{4\sqrt{\pi}} \int_0^\infty \frac{du}{u} \left[ e^{-\frac{(y+y_0)^2}{4u^2}} - e^{-\frac{(y-y_0)^2}{4u^2}} \right].$$

(C2)

Using now the identity

$$\frac{u}{(u-1)(u+1)^2} = \frac{1}{(u+1)^2} + \frac{1}{(u-1)(u+1)^2},$$

(C3)

we split $Z_B(y, y_0)$ into two parts:

$$Z_B(y, y_0) = \frac{1}{4\sqrt{\pi}} \left( \mathcal{I}_1(y, y_0) + \mathcal{I}_2(y, y_0) \right),$$

where

$$\mathcal{I}_1(y, y_0) = \int_0^\infty \frac{du}{(u+1)^2} \left[ e^{-\frac{(y+y_0)^2}{4u^2}} - e^{-\frac{(y-y_0)^2}{4u^2}} \right] \cdot u$$

and

$$\mathcal{I}_2(z, w) = \int_0^\infty \frac{du}{(u-1)(u+1)^2} \left[ e^{-\frac{(y+y_0)^2}{4u^2}} - e^{-\frac{(y-y_0)^2}{4u^2}} \right] \cdot u.$$

(C5)

(C6)

In $\mathcal{I}_2(y, y_0)$ [C6], the small $y_0$ limit can be taken easily. It yields

$$\mathcal{I}_2(y, y_0) = y y_0 \int_0^\infty \frac{du}{(u-1)(u+1)^2} \left[ e^{-\frac{y^2}{4u^2}} - e^{-\frac{y_0^2}{4u^2}} \right] + O(y_0^2).$$

(C7)

We now decompose $\mathcal{I}_1(y, y_0)$ [C6] into two parts

$$\mathcal{I}_1(y, y_0) = \mathcal{I}_{11}(y, y_0) + \mathcal{I}_{12}(y, y_0),$$

(C8)

$$\mathcal{I}_{11}(y, y_0) = \int_0^\infty \frac{du}{(u+1)^2} \left[ e^{-\frac{(y+y_0)^2}{4u^2}} - e^{-\frac{(y-y_0)^2}{4u^2}} \right],$$

$$\mathcal{I}_{12}(y, y_0) = \int_0^\infty \frac{du}{u(u+1)^2} \left[ e^{-\frac{(y+y_0)^2}{4u^2}} - e^{-\frac{(y-y_0)^2}{4u^2}} \right].$$

In $\mathcal{I}_{12}(y, y_0)$, it is straightforward to obtain the small $y_0$ behavior as

$$\mathcal{I}_{12}(y, y_0) = y y_0 \int_0^\infty \frac{du}{u^2(u+1)^2} e^{-\frac{y_0^2}{4u^2}} + O(y_0^2).$$

(C9)

The integral in $\mathcal{I}_{11}(y, y_0)$ contains a logarithmic singularity when $y_0 \to 0$, which is a bit tricky to extract. To do so, we first perform a change of variable $s = y_0 u$ and then add and subtract the term $y_0 \int_0^\infty ds e^{-y^2/4} e^{-s^2/4-y^2}/(s + y_0)^2$. Now using

$$\int_0^\infty ds e^{-y^2/4} = y(\log y + \log y + \gamma_E) + O(y_0 \log y_0),$$

(C10)

one obtains, for $y_0 \to 0$:

$$\mathcal{I}_{11}(y, y_0) = (y_0 \log y_0) ye^{-s^2} + y_0 y e^{-y^2/4} (\gamma_E + \log y) - y e^{-y^2/4} Q(y) + O(y_0^2 \log y_0),$$

(C11)

where

$$Q(y) = \int_0^\infty ds \left( e^{-y^2/4 - 2 e^{-s^2} \sinh (y s/2)} \right).$$

(C12)

Finally combining Eqs. (C7), (C9) and (C11) one obtains the small $y_0$ behavior of $Z_B(y, y_0)$ in Eq. (C4) as

$$Z_B(y, y_0) = \frac{y e^{-y_0^2}}{4\sqrt{\pi}} \left[ (y_0 \ln y_0) - y_0 \left( Q(y) y - \gamma_E - \ln y - A(y) \right) \right] + O(y_0^2 \log y_0),$$

(C13)

where $A(y)$ is given by

$$A(y) = \int_0^\infty du \frac{1}{(u-1)(u+1)^2} \left( 1 e^{-\frac{x^2}{4u^2}} - u \right).$$

(C14)

One can then obtain $Z(y, y_0) = Z(0, y_0) - \epsilon(Z_A(y, y_0) + Z_B(y, y_0))$ in the limit $y_0 \to 0$ from the Eqs. (45), (C1) and (C13) as:

$$Z(y, y_0) = y_0 (1 - \frac{e}{2} \ln y_0) \frac{y}{2\sqrt{\pi}} e^{-\frac{y^2}{4}} - \epsilon y_0 \tilde{Z}_1(y),$$

(C15)

where $\tilde{Z}_1(z)$ can be read off straightforwardly from Eqs. (C1) and (C13):

$$\tilde{Z}_1(y) = -2\partial_y R^{(1)}(y) - \frac{y}{4\sqrt{\pi}} e^{-y^2/4} \left( \frac{Q(y)}{y} - \gamma_E - \ln y - A(y) \right).$$

(C16)

This perturbative expansion [C15] is fully consistent with the expected behavior [21, 22].

$$Z(y, y_0) \sim y_0 \frac{y}{2} \tilde{Z}(y), \quad y_0 \to 0, \quad \tilde{Z}(y) = \tilde{Z}(0)(y) - \epsilon \tilde{Z}^{(1)}(y),$$

(C17)

where $\tilde{Z}^{(1)}(y)$ is given in Eq. (C16). These integrals that enter the definition of $\tilde{Z}^{(1)}(y)$ can then be computed, for instance using Mathematica, to yield the following expression of $R^+(y)$ from Eq. (44):
\[ R_+(y) = R_+^{(0)}(y) \left( 1 + cW_+(y) + \mathcal{O}(c^2) \right), \]

\[
W_+(y) = \frac{1}{48} \left[ 60 \gamma_E - 48 \log 2 - y^2(18 - 6\gamma_E - 12 \log 2) - 6(2 - \sqrt{\pi}y)e^{\frac{y^2}{4}} + y^2(y^2 - 4) \frac{y^4}{2} {}_2F_2 \left( 1, 1; \frac{5}{2}, 3; \frac{y^2}{4} \right) - \frac{24\sqrt{\pi}}{y} e^{\frac{y^2}{4}} \text{Erf} \left( \frac{y}{2} \right) - 3\pi(y^2 - 2) \text{Erfi} \left( \frac{y}{2} \right) + 3(y^2 - 4) \text{Ei} \left( \frac{y^2}{4} \right) \right],
\]

where \( R_+^{(0)}(y) \) is given in Eq. (46) and \( {}_2F_2 \left( 1, 1; \frac{5}{2}, 3; \frac{y^2}{4} \right) \) is a hypergeometric series (32). From this expression (C18) it is straightforward to obtain the asymptotic behaviors given in the text (48, 49).

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