Optimized Trajectories to the Nearest Stars Using Lightweight High-velocity Photon Sails

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Abstract

New means of interstellar travel are now being considered by various research teams, assuming lightweight spaceships to be accelerated via either laser or solar radiation to a significant fraction of the speed of light (c). We recently showed that gravitational assists can be combined with the stellar photon pressure to decelerate an incoming lightsail from Earth and fling it around a star or bring it to rest. Here, we demonstrate that photogravitational assists are more effective when the star is used as a bumper (i.e., the sail passes “in front of” the star) rather than as a catapult (i.e., the sail passes “behind” or “around” the star). This increases the maximum deceleration at α Cen A and B and reduces the travel time of a nominal graphene-class sail (mass-to-surface ratio 8.6 × 10⁻⁴ g m⁻²) from 95 to 75 years. The maximum possible velocity reduction upon arrival depends on the required deflection angle from α Cen A to B and therefore on the binary’s orbital phase. Here, we calculate the variation of the minimum travel times from Earth into a bound orbit around Proxima for the next 300 years and then extend our calculations to roughly 22,000 stars within about 300 lt-yr. Although α Cen is the closest star system, we find that Sirius A offers the shortest possible travel times into a bound orbit: 69 years assuming 12.5% c can be obtained at departure from the solar system. Sirius A thus offers the opportunity of flyby exploration plus deceleration into a bound orbit of the companion white dwarf after relatively short times of interstellar travel.

Key words: radiation mechanisms: general – solar neighborhood – space vehicles – stars: individual (Alpha centauri, Sirius) – stars: kinematics and dynamics

Supporting material: animation, machine-readable table

1. Introduction

The possibility of interstellar travel has recently been revived through developments in laser technology, material sciences, and the construction of high-performance nano computer chips (Lubin 2016; Manchester & Loeb 2017). The small weight of only a few grams of onboard equipment (communication, navigation, propulsion, science instruments, etc.) and the possible mass production of these probes results in reduced costs for production, launch, and operation—benefits that could make such a mission affordable within the current century. Moreover, the first interplanetary solar sail mission (IKAROS; Tsuda et al. 2011) has been completed and further concepts are now being tested in near-Earth orbits (e.g., LightSail; Ridenoure et al. 2016). The idea of using solar light to accelerate a space probe in the solar system is not new (Kepler 1619; Tsander 1924; Tsiolkovsky 1936; Garwin 1958; Tsu 1959). Key challenges are in the high temperatures close to the Sun, where the thrust is strongest but the sail could melt (Dachwald 2005), and in the loss of effective propulsion at several au from the Sun. Using a close (0.1 au) solar encounter and a 1000 m radius sail, Matloff et al. (2008) calculated a maximum velocity of 0.2% c for the departure of a 150 kg probe from the solar system. Alternatively, it has been proposed that lasers could solve the decreasing-strength-with-distance problem due to their high flux of coherent light (Forward 1962; Marx 1966). As noted by Redding (1967), however, this launch technology meets the problem of deceleration at the destination since there would be no obvious way to decelerate the spacecraft at the target star.

Heller & Hipke (2017) suggested to decelerate and deflect incoming high-velocity sails from Earth using the stellar radiation and gravitation, a maneuver they referred to as photogravitational assist. Assuming that the sail would be made of a strong, ultralight material such as graphene, which would be covered by a highly reflective broadband coating made of sub-wavelength thin metamaterials (Slovick et al. 2013; Moitra et al. 2014b), such a sail could have a maximum speed at arrival \(v_{\text{in, max}}\) of about 4.6% c to be successively decelerated at the stellar triple α Cen A, B, and C (Proxima; Matloff 2013). Such a tour could potentially park the lightsail in a bound orbit around the Earth-mass habitable zone exoplanet Proxima b (Anglada-Escudé et al. 2016). The travel times would be 95 years from Earth to α Cen AB and another 46 years from the AB binary to Proxima, or 141 years in total.

Here, we present an alternative way of using photogravitational assists at α Cen, which reduces travel times significantly. We also present a detailed analysis of the AB orbital motion for the next three centuries, which is crucial for a detailed study of the expected travel times at a given launch time from the solar system. We then apply this method to stars within 300 lt-yr of the Sun and identify other highly interesting targets for bound-orbit exploration by interstellar lightsails.

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See the Breakthrough Starshot Initiative at http://breakthroughinitiatives.org.
2. Methods

2.1. A Nominal Graphene-class Sail

In our nominal scenario, we consider a sail made of a graphene structure ($\sigma = 7.6 \times 10^{-4}$ g m$^{-2}$) with a graphene-based rigid skeleton and highly reflective coating that is capable of transporting a science payload (laser communication, navigation, cameras, etc.) of about 1 g (Heller & Hippke 2017). Such a sail must have an area of about $10^3$ m$^2 = (316 \text{ m})^2$ to make the weight of the science payload negligible against the weight of the sail structure. At this size, the graphene structure would contribute 76 g, the skeleton and coating could add 9 g, and the payload would add another 1 g, implying $\sigma_{\text{nom}} = 8.6 \times 10^{-4}$ g m$^{-2}$ for our nominal graphene-class sail.

2.2. Photogravitational Assists at $\alpha$ Cen

2.2.1. An Improved Method for Deceleration

In Heller & Hippke (2017), we showed how it is possible to use both the photon pressure of a star and its gravitational tug to decelerate and deflect an incoming lightsail. Our main aim was to determine the maximum possible injection speed ($v_{\text{c, max}}$) at $\alpha$ Cen A to allow a swing-by maneuver to $\alpha$ Cen B and to finally achieve a bound orbit around Proxima. The key challenge that we identified for the determination of $v_{\text{c, max}}$ is in reaching the maximum deceleration upon arrival at $\alpha$ Cen A while simultaneously achieving the required deflection angle ($\delta$) between the inbound and outbound trajectories in order to swing from $\alpha$ Cen A to B. Analytical estimates for our nominal graphene-class sail, which would approach the star as close as five stellar radii ($R_\star$), show that it could be possible to drop as much as 12,900 km s$^{-1}$ at A, 8800 km s$^{-1}$ at B, and another 1270 km s$^{-1}$ at Proxima, giving an additive deceleration of up to $v_{\text{c, max}} = 22,970$ km s$^{-1}$ in total.

We then performed numerical calculations using a modified $N$-body code that included the forces on the sail imposed by the stellar photon pressure. We imposed an analytic boundary condition on the sail’s pitch angle ($\alpha$, the angle between the normal to the sail plane and the radius vector to the star) to maximize the loss of speed along its trajectory. In our simulations, the sail was inserted into the gravitational well of the star in such a way that it would pass the star on the one side (e.g., on the right, see Figure 2 in Heller & Hippke 2017) and have a net deflection after its passage to the other side (e.g., to the left).

These numerical simulations revealed that the maximum velocity upon arrival at A, which would allow a deflection to B (assuming $\delta \approx 10^5$), is limited to $v_{\text{c, max}} = 13,800$ km s$^{-1}$. And so while analytical estimates of the additive nature of the photogravitational assist suggest that up to $v_{\text{c, max}} = 22,970$ km s$^{-1}$ could be successively absorbed at the $\alpha$ Cen stellar triple, numerical simulations show that the particular geometry of the system limits $v_{\text{c, max}}$ to 13,800 km s$^{-1}$.

Following up on these simulations, we recently discovered that a simple modification of the incoming trajectory yields higher deflection angles at even higher incoming speeds. It turns out that it is more effective to use the stellar photon pressure (rather than gravity) to enhance the deflection. From a geometry perspective, it is more efficient to let the sail approach the star on the same side (e.g., on the left; see Figure 1) as the desired deflection (i.e., to the left). We then find that, using the same optimization strategy for deceleration as Heller & Hippke (2017), a maximum total deceleration of $v_{\text{c, max}} = 17,050$ km s$^{-1}$ can be reached at $\delta = 19^\circ$, where 8800 km s$^{-1}$ and 8400 km s$^{-1}$ can be lost at A and B, respectively. If the lightsail is supposed to continue its journey to Proxima, then it would actually be better to orient the sail during its passage at B in a way to avoid maximum deceleration, so that the sail can continue its cruise to Proxima with a residual speed of 1270 km s$^{-1}$. This is the maximum speed that can ultimately be absorbed at Proxima.

2.2.2. A Timetable of Launch Opportunities to Proxima

The orbital motion of the $\alpha$ Cen AB binary leads to a periodic variation ($P = 79.929 \pm 0.013$ years; Kervella et al. 2016) of the deflection at $\alpha$ Cen A that is required by the sail to reach B. We calculate the binary’s orbital motion for the next 300 years, based on the works of Kervella et al. (2016), and we include the computation of Proxima’s orbit around the $\alpha$ Cen AB binary based on Kervella et al. (2017b). Figure 2 shows the orbits of $\alpha$ Cen A (orange) and B (red) as a projection on the sky with dates around the year 2100 labeled along the ellipses. The blue line illustrates the sky-projected AB vector at the time when the deflection required by the sail for a sequential AB photogravitational assist is smallest. This event will take place on 2092 September 8 (2092.69).

We then use our results for $\delta(t)$, where $t$ symbolizes time, together with a range of numerical trajectory simulations, to first determine $v_{\text{c, max}}(\delta)$, then $v_{\text{c, max}}(t)$, that is, the maximum possible injection speed at $\alpha$ Cen to reach a bound orbit at
Proxima, and ultimately the travel time from Earth to $\alpha$ Cen AB over the next 300 years. For the final step, the conversion from travel speed to travel time, we adopt a barycentric distance to $\alpha$ Cen AB of 4.365 lt-yr (Kervella et al. 2016).

2.3. An Interstellar Travel Catalog

2.3.1. Analytical Estimates

While the $\alpha$ Cen system is the natural first target for interstellar travels to consider, given its proximity and the presence of the Earth-sized, potentially habitable planet Proxima b, other nearby stars offer compelling opportunities, too. We thus extend our investigations of photogravitational assists to a full stop around other nearby stars and estimate the travel time $\tau$ to a nearby star with a given radius $R_*$ and luminosity $L_*$ as

$$\tau = \frac{d}{\sqrt{2E_{\text{kin,p}}}} = \frac{d}{2\pi c r_{\text{min}}}.$$  (1)

where $d$ is the stellar distance to the Sun, $M$ is the sail mass, $E_{\text{kin,p}} = \int_{r_{\text{min}}}^{\infty} dr F(r)$

$$= \frac{L_* A}{3\pi c R_*} \int_{r_{\text{min}}}^{\infty} dr \left[ 1 - \left( \frac{R_*}{r} \right)^2 \right]^{3/2} \frac{1}{R_*} \quad (2)$$

is the kinetic energy of the sail that can be absorbed by the stellar photons during approach (McInnes & Brown 1990; Heller & Hippke 2017), and $A$ is the sail’s surface area. The integral in Equation (2), which we refer to as the photointegral, is independent of the actual value of $R_*$ and only depends on the choice of $r_{\text{min}}$. Figure 3 shows the numerical value of the photointegral for $1 R_* \leq r_{\text{min}} \leq 100 R_*$. Four different functions are given for comparison (dotted lines). In particular, we found that $1.5/r_{\text{min}}$ (with $r_{\text{min}}$ in units of $R_*$) provides an excellent approximation with deviations <$1\%$ for $r_{\text{min}} \geq 3 R_*$ (blue dotted line). Using this approximation, Equation (2) becomes

$$E_{\text{kin,p}} = \frac{L_* A}{2\pi c R_* (r_{\text{min}}/R_*)} = \frac{L_* A}{2\pi c r_{\text{min}}} \quad (3)$$

and Equation (1) then is equivalent to

$$\tau = \frac{d}{\sqrt{L_* A}} \sqrt{\frac{\ln(10)}{c r_{\text{min}} M}} \ln \left( \frac{d/\text{year}}{\sqrt{L_* A}} \right) \quad (4)$$

We chose the latter equivalent transformation to describe the travel time as a logarithmic spiral of the form $\phi = 1/k \ln(d/a)$, where the constant $k > 0$ defines the curvature of the spiral and $a$ is the radius of the circle for $k \to 0$. As an
Table 1

| β     | Stellar Mass |
|-------|--------------|
| 3.05 ± 0.14 | $M_\odot \lesssim 0.5 M_\odot$ |
| 4.76 ± 0.01 | $0.6 M_\odot \lesssim M_\star \lesssim 1.5 M_\odot$ |
| 3.68 ± 0.05 | $1.5 M_\odot \lesssim M_\star$ |

Aside, note that the first line in Equation (6) is equivalent to $\tau \propto \sigma$, a relation that we will come back to below.

For a nominal minimum stellar approach of $r_{\text{min}} = 5 R_\star$, the photointegral yields a value of 0.299 and Equation (2) collapses to

$$E_{\text{km,p}} = \frac{L A}{10 \pi c R_\star}, \quad \text{for } r_{\text{min}} = 5 R_\star,$$

so that

$$\log_{10}(\tau(\text{year})) = \frac{1}{\ln(10)} \ln \left( \frac{d/\text{year}}{L A} \sqrt{\frac{5 \pi c R_\star M}{L A}} \right),$$

where $\tau$ is the time to close the optical distance of the Earth to the star. (6)

2.3.2. Numerical Simulations

In addition to our analytical estimates, we perform numerical simulations of photogravitational assists around stars in the solar neighborhood as in Heller & Hippke (2017). For 117 stars within 21 lt-yr around the Sun, we use distances, luminosities, masses, and radii from Allende Prieto et al. (2004), Valenti & Fischer (2005), van Leeuwen (2007), and Holmberg et al. (2009).

For more distant stars but within 316 lt-yr, we use parallax measurements from Hipparcos (Perryman et al. 1997) and Gaia DR1 (Gaia Collaboration et al. 2016a, 2016b; Lindegren et al. 2016) to estimate stellar distances. We pull available estimated temperatures from the Radial Velocity Experiment (Casey et al. 2017; Kunder et al. 2017) and add additional stars from the Hipparcos and Tycho-2 catalog (Hog et al. 2000), where only color information ($B−V$) is available. For these latter stars, we follow the procedure of Heller et al. (2009) to estimate the effective temperature as

$$T_{\text{eff}} = 10^{14.551 \ln \left(\frac{(B−V)/3.684}{1000}\right)},$$

the stellar radius $R_\star$ as

$$\frac{R_\star}{R_\odot} = \left[ \frac{5770 K}{T_{\text{eff}}} \right]^{4} \left[ 10^{(4.83−M_\odot)/2.5} \right]^{1/2},$$

and the stellar mass $M_\star$ as

$$\frac{M_\star}{M_\odot} = \left( \frac{4\pi R^2 c M_{\text{eff}}}{L_\odot} \right)^{-1/\beta},$$

where $\sigma_{\text{SB}}$ is the Stefan–Boltzmann constant and where the coefficient $\beta$ in the relation $L \propto M^\beta$ depends on the stellar mass (see Table 1; values taken from Cester et al. 1983).

In our modified N-body simulations, we impose an upper temperature ($T$) limit of 100°C (373 K) on the sail. At these temperatures, modern silicon semiconductors are still operational (Intel Corporation 2016) and the sail material is likely not a limitation. For comparison, aluminum has a melting point of 933 K, and graphene melts at 4510 K (Los et al. 2015).

We assume a sail reflectivity of 99.99%, which might be achievable in the broad band using multiple coatings, or metamaterials with sub-wavelength thickness (Slovick et al. 2013; Moitra et al. 2014a; Liu et al. 2016). From the Boltzmann law, we first deduce

$$T_{\text{eff}} < T \times (n^2/\zeta)^{1/4},$$

where $\zeta = (1 − 0.9999)$ is the absorptivity of the sail and $n = r_{\text{min}}/R_\star$, and then we calculate

$$n = \sqrt[8]{T_{\text{eff}}/T}$$

as the minimum (float) number of stellar radii for the sail to prevent heating above $T = 373$ K. As an example, for Sirius A ($T_{\text{eff}} = 8860K$) we obtain $n = \sqrt[8]{1 - 0.9999} \times (8860/373)^{2} = 5.6$ (stellar radii) as a minimum distance. For stars with $T_{\text{eff}} < 8340$ K we have $n < 5$ and so we impose $n = 5$ to limit the destructive perils of flares, magnetic fields, electron/proton impacts, etc.

3. Results

3.1. Optimized Trajectories to Proxima

Using photogravitational assists at the same side of the star as the desired deflection (see Figure 1) rather than gravitational swing-bys “behind” the star (as in Heller & Hippke 2017), we find that the maximum possible injection speed at $\alpha$ Cen A to allow deflections to B and then to C can be significantly increased. For a nominal graphene-class lightsail with a mass-to-surface ratio of $\sigma_{\text{nom}} = 10 \times 8.6$ g m$^{-2}$, we find $v_{\text{c,max}} = 17,050$ km s$^{-1}$ (5.7% c). Compared to the previously published value of $v_{\text{c,max}} = 13$, 800 km s$^{-1}$ (4.6% c; Heller & Hippke 2017), this corresponds to an increase of 24% in speed and implies a reduction of the travel time from Earth to $\alpha$ Cen AB from 95 to 75 years. The total travel time from Earth to a full stop at Proxima then becomes 75 years + 46 years = 121 years, assuming a residual velocity of 1280 km s$^{-1}$ can be absorbed at Proxima after 46 years of travel between $\alpha$ Cen B and Proxima.

In Figure 4, we present our results for the variation of the total travel time to Proxima over the next 300 years. The upper left panel shows the deflection angle required by the sail upon passage of $\alpha$ Cen A to reach B. The minimum value is 10.7°.

In the top right panel, we show the maximum possible injection speed at A that allows deflection by an angle $\delta$. The peak velocity of 17, 050 km s$^{-1}$ occurs at an angle of 19°. The shaded regions in the panel denote angles smaller (or larger) than the smallest (or largest) angular separation between A and B, which are thus irrelevant for real trajectories.

The bottom left panel shows the variation of the total travel time from Earth to $\alpha$ Cen A given our knowledge about the upcoming orbital alignments (top left panel) and the possible maximum injection speeds (top right panel). The pairs of depressions, e.g., near the departure years 2093 and 2106, correspond to phases of close alignments between A and B, with the first deflection referring to an A–B sequence and the second depression corresponding to a B–A sequence, where B...
is visited first and A thereafter (since A in this case is behind B, as seen from Earth).

The bottom right panel, finally, shows the year of arrival given a year or departure and assuming maximum injection speeds at α Cen required by a nominal lightsail made of graphene to perform photogravitational assists into a bound orbit around Proxima. Values have been determined by numerical trajectory simulations with minimum stellar approaches of 5 R, around either α Cen A or B, whichever was closer to Earth at the time of arrival. Top left: temporal variation of the angular deflection required upon arrival at α Cen to either reach B after the encounter with A or to reach A after the encounter with B. Top right: maximum possible injection speed at α Cen A to achieve a given deflection angle. The maximum speed can be obtained for δ = 19°. Bottom left: year of departure from Earth vs. travel time between Earth and α Cen AB. The pairs of depressions correspond to maximum injection speeds of 17,050 km s⁻¹ at angular separations of 19° (see the top right panel), which occur a few years before and after the closest encounter of the α Cen AB binary. Bottom right: arrival time at α Cen AB as a function of departure time from Earth.

Figure 5 extends our study and investigates other possible mass-to-surface ratios for the lightsail. The two panels show the maximum injection speed as a function of the deflection angle (left) and the travel time from Earth to α Cen AB as a function of time for an aluminum lattice sail as proposed by Drexler (1979). The corresponding mass-to-surface ratio is σ = 7 × 10⁻² g m⁻². The results from these numerical simulations suggest that vₘₐₓ is about a factor of 10 smaller for any given deflection angle than for our nominal graphene-class sail and that the travel time is about a factor of 10 higher. This is consistent with our analytical estimate that τ ∝ σ (see Equation (4)), which suggests travel times of an aluminum lattice are extended by a factor of \( \sqrt{7 \times 10^{-2}/7.6 \times 10^{-4}} = 9.7 \) compared to a graphene-class sail.

The right panel of Figure 5 covers times of departure from Earth between 1900 and 2300 as the bottom right panel of Figure 4. Minimum travel times for an aluminum-class lightsail are tₛ(750 years ± 910 years). Note that any given departure year from Earth allows multiple, in fact, up to five possible travel times. Each individual travel time corresponds to a specific, sub-vₘₐₓ interstellar speed of the lightsail and a specific orbital cycle of the AB binary upon arrival.

Figure 6 illustrates the complete trajectory of a lightsail from Earth to α Cen A, B, and C with an arrival at α Cen AB in the year 2092.69. At that instance, the sky-projected AB separation is 19° and vₘₐₓ = 17,050 km s⁻¹ is possible, providing the
minimum travel time from Earth of 75 years (see Figure 4, bottom left). The left panel shows a global overview of the Sun–AB–C trajectory in Galactic coordinates and on a scale of light years. Our nominal graphene-class sail would require a minimum of 75 years to cover the distance of the long blue line between the Sun and the AB binary and another 46 years to complete the travel from the AB binary to C. The right panel shows a zoom into the AB binary at the time of arrival in 2092.69. With an instantaneous separation of 30.84 au between A and B and assuming a residual speed of the sail of 8400 km s\(^{-1}\) (see Section 2.2.1), the travel time between encounters of A and B would be 6 days and 8.6 hr. After the encounter with B, the lightsail would be deflected toward Proxima. A projection of the blue trajectory on the Earth sky is shown in Figure 2.

### 3.2. Photogravitational Assists in the Solar Neighborhood

Moving on to other stars in the solar neighborhood, Figure 7 illustrates our findings for the minimum possible travel times of a graphene-class lightsail to perform a photogravitational assist to a full stop, i.e., into a bound orbit around the respective star. The left panel shows 117 stars within 21 lt-yr, and the right panel shows 22,683 stars out to 316 lt-yr. The meanings of the symbols and lines are described in the figure caption. For these full-stop maneuvers to work, note that the injection speeds need to be achieved at departure from the solar system in the first place.

As an intriguing result of this study, we find that Sirius A, though being about twice as far from the Sun as \(\alpha\) Cen, could actually decelerate an incoming lightsail to a full stop after only about 69 years of interstellar travel \((v_{\infty, \text{max}} = 12.5\%c)\).\(^9\) This is due to the star’s particularly high luminosity of about 24.2 solar luminosities. The derived travel time compares to a minimum travel time of 75 years to \(\alpha\) Cen if a sequence of photogravitational assists is used at stars A and B to perform a full stop, and it compares to 101 years of interstellar travel to \(\alpha\) Cen A or 148 years to \(\alpha\) Cen B if only the target star is used for a slowdown to zero. The case of Sirius is particularly interesting because it is actually a binary system and Sirius B is a white dwarf (Bessel 1844; Adams 1915). Photogravitational assists in the Sirius AB system would need an exact determination of the binary orbit prior to launch (for recent astrometry of the orbit, see Bond et al. 2017), which could then allow a sequence of flybys around an AIV main-sequence star and a white dwarf.

Table 2 lists our results for the maximum injection speeds and minimum travel durations to the 10 most nearby stars shown in Figure 7 in order to perform a full stop via photogravitational braking (the full list of 22,683 objects is available as a machine-readable table). The results have been obtained using numerical trajectory simulations from our modified \(N\)-body integrator. The objects are ordered by increasing travel time.

### 4. Discussion

#### 4.1. Launch Strategy and Aiming Accuracy

A graphene-class sail could have a maximum ejection speed of about 11,500 km s\(^{-1}\) from the solar system if it was possible to bring it as close as five solar radii to the Sun and then initiate a photogravitational launch (Heller & Hippke 2017). This is much less than the maximum injection speed of 17,050 km s\(^{-1}\) that can be absorbed by successive photogravitational assists at \(\alpha\) Cen A to C. If sunlight were to be used to push a lightsail away from the solar system, then its propulsion would need to be supported by a second energy source, e.g., a ground-based laser array, to fully exploit the potential of photogravitational deceleration upon arrival. A combination with sunlight might in fact reduce the huge energy demands of a ground-based laser system.

The aiming accuracy at departure from the solar system is key to a successful photogravitational assist at \(\alpha\) Cen. Hence, the position, proper motion, and the binary orbital motion of the \(\alpha\) Cen AB binary will need to be known very precisely at the time of departure. This is a rather delicate question as \(Gaia\) will not observe \(\alpha\) Cen AB at all.

The angular diameter of \(\alpha\) Cen A is about 0\(^{\prime}\)008 = 8 mas as seen from Earth (Kervella et al. 2003, 2017a). In order for an

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\(^9\) Heller & Hippke (2017) calculated a value of \(v_{\infty, \text{max}} = 14.9\%c\). They used \(\eta_{\text{max}} = 5\, R_{\odot}\), without any constraints on the maximum effective temperature of the sail to prevent overheating; see Equation (10).
interstellar projectile to successfully hit α Cen A, a pointing accuracy of <R* is key. A fiducial accuracy of 0.2 R*, translates into a funnel <1.6 mas as seen from Earth. The current uncertainty of 3.9 mas yr\(^{-1}\) in the proper motion (pm) vector of α Cen (\(\mu = 3685.8 \pm 3.9\) mas yr\(^{-1}\); Kervella et al. 2016) will result in an offset of 78 mas (0.1 au at α Cen) after a nominal 20 year journey, as proposed by the Breakthrough Starshot Initiative. Hence, the current knowledge of the celestial position and motion of α Cen AB prevents an aimed orbital injection and swing-by to Proxima. That said, pm accuracies <2 mas/20 years = 100 μas yr\(^{-1}\) can in principle be reached for α Cen using dedicated astrometry. These observations will be key to a successful direction of an interstellar ballistic probe from Earth to α Cen.

The aiming accuracy will also be affected by the presence of interstellar magnetic fields if the sail has an electric charge. In fact, it might be impossible for a sail to prevent getting electrically charged due to the continuous collisions with the interstellar medium. Studies of the effects of magnetic effects on the interstellar trajectories of lightsails are beyond the scope of this study but they might be crucial to assess whether aiming accuracies of the order of 1 stellar radius at the target are actually possible.

### 4.2. Deflection during Stellar Encounter

The limiting factor to the full leverage of the additive nature of the photogravitational effect in the α Cen AB system is in their orbital inclination with respect to the Earth’s line of sight. The optimal deflection angle to achieve maximum injection speeds at α Cen A is 19° (Figure 4). A and B will never come closer than 10''7 from our point of view. If it were possible to let the incoming lightsail tack from an angle (\(\lambda\)), or “from the side,” then this might allow faster departures than permitted for straight trajectories if the sky-projected AB angular separation upon arrival is >19° (see Figure 4, top right). In fact, due to the binary’s sky-projected proper motion of 23.4 km s\(^{-1}\) and given α Cen A’s barycentric tangential velocity of \(\approx 8 \pm 5\) km s\(^{-1}\) (Kervella et al. 2016) upon encounter, the incoming sail will have a minimal (≈0.1) tangential velocity with respect to the line of sight from Earth.

We have looked at different possibilities to add an additional tangential speed component (\(v_t\)) to the sail and found that \(\lambda = \arctan(v_t/v_\infty)\). One option that seems physically feasible, though technically challenging, would be to send the sail with a slight offset to α Cen A, and then fire the onboard communication laser perpendicular to the trajectory for a time \(t_i\). This maneuver would result in a curved sail trajectory. Assuming that the laser energy output (\(E_l = Pt_i\); \(P_l\) being the laser power) would be transformed into kinetic energy of the sail (\(E_{kin}\)), we have

\[
\lambda = \arctan(v_t/v_\infty) = \arctan\left(\sqrt{\frac{2P_l t_i}{M}} v_\infty^{-1}\right).
\] (12)
To deflect our fiducial sail with $v_\infty = 17,050 \, \text{km} \, \text{s}^{-1}$ by $\lambda = 1^\circ$, a 100 W (or a 10 kW) laser would have to fire for a whole year (or 10 days), yielding $E_l = 8.6 \times 10^9 \, \text{GJ}$. If an adequate miniature propulsion system could be implemented to change the incoming trajectory by $1^\circ$, then the gain in $v_{\infty, \text{max}}$ would be up to several 100 km s$^{-1}$ and the travel time from Earth to $\alpha$ Centauri A could be reduced by a few years.

Assuming that this maneuver shall not add more than about 1 g to the total weight, we find that an energy density of $8.6 \times 10^9 \, \text{GJ} \, \text{g}^{-1}$ is several orders of magnitudes higher than that of conventional chemical reactants or of modern lithium batteries. Only nuclear fission could possibly yield high enough energy densities, but this technology would likely add up to much more weight to feed the laser. In turn, an increased weight will reduce the tangential velocity that can be achieved through the conversion of laser power into kinetic energy. We conclude that current means of energy storage and conversion do not permit higher incoming sail speeds $v_{\infty, \text{max}}$ by steering the sail onto a significantly curved trajectory.

### 4.3. Sirius Afterburner

Using numerical simulations, we investigated scenarios in which a graphene-class lightsail approaches Sirius A from Earth but minimizing the deceleration during approach while maximizing the acceleration after passage of $r_{\text{min}}$ (set to 5.64 $R_\odot$ to prevent fatal damage). We refer to this setup as the “Sirius afterburner” since the star is used to accelerate the space probe to even faster interstellar velocities than might be achievable with Earth-based technology and/or using solar photons.

We find that such a flyby at Sirius A can increase the velocity of a graphene-class lightsail by up to $27,000 \, \text{km} \, \text{s}^{-1}$ (9.0% $c$) in the non-relativistic regime with deflection angles $\delta \lesssim 20^\circ$. Consequently, stars at distances $d_1 > d_S$ to the Sun ($d_S$ being the Sun–Sirius distance) and within a sky-projected angle

$$\phi = \delta \left(1 - \arcsin\left(\frac{d_S}{d_1}\right)\right)$$

(13)

around Sirius (as seen from Earth) can be reached significantly faster using a photogravitational assist at Sirius. The maximum velocity boost of 9.0% $c$ is smaller than $v_{\infty, \text{max}} = 12.5\% \, c$, which we determined as the maximum loss of speed upon...
arrival at Sirius A to a full stop in Section 3.2, as the stellar photon pressure is not acting antiparallel to the instantaneous velocity vector during flyby. The same principle applies to other combinations of nearby and background stars, but Sirius A with its huge luminosity and relative proximity to the Sun is the most natural choice for an interstellar photogravitational hub for humanity.

4.4. Particular Objects to Visit in the Solar Neighborhood

Beyond the many single-target stars, there are other interesting objects in the solar neighborhood, which an ultralight photon sail could approach into a bound orbit after deceleration at the host star, such as

1. The nearby exoplanet Proxima b (Anglada-Escude et al. 2016);
2. A total of 328 known exoplanet host stars within 316 lt-yr (right panel Figure 7);
3. The young Fomalhaut triple system with its enigmatic exoplanet Fomalhaut b (Kalas et al. 2008) and protoplanetary debris disks around Fomalhaut A and C (Holland et al. 1998; Kennedy et al. 2014);
4. The two white dwarfs Sirius B, located at 8.6 lt-yr from the Sun, and Procyon B at a distance of 11.44 lt-yr;
5. 36 Ophiuchi, consisting of three K stars and located at 19.5 lt-yr from the Sun, is the most nearby stellar triple;
6. TV Crateris, a quadruple system of T Tau stars and located at 150 lt-yr from the Sun; and
7. PSR J0108-1431, between about 280 lt-yr and 424 lt-yr away, is the nearest neutron star (Tauris et al. 1994).

Fomalhaut A is a moderately fast rotator with rotational speeds of about 100 km s⁻¹ at the equator. Altair and Vega are very fast rotating stars (Auldenberg et al. 2006) with strongly anisotropic radiation fields. This would certainly affect the steering of the sail. An interstellar probe from Earth would approach Vega from a polar perspective. With the poles being much hotter and thus more luminous than the rest of the star, this could be beneficial for an efficient braking.

Beyond that, it could be possible to visit stars of almost any spectral type from red dwarf stars to giant early-type stars, which would allow studies of stellar physics on a fundamentally new level of detail. In principle, an adaptation of the Breakthrough Starshot concept that is capable of flying photogravitational assists could visit these objects and conduct observations from a nearby orbit. That said, photogravitational assists into bound orbits around single low-luminous M dwarfs imply very long travel times even in the solar neighborhood. The case of Proxima and its habitable zone exoplanet Proxima b is an exceptional case since this red dwarf is a companion of two Sun-like stars, both of which can be used as photon bumpers to allow a fast and relatively short travel to Proxima.

4.5. Prospects of Building a Highly Reflective Graphene Sail

Since the advent of modern graphene studies in the early 2000s (Novoselov et al. 2004), huge progress has been made in the characterization of this material and in its high-quality, wafer-scale production (Lee et al. 2014). For example, Sanchez-Valencia et al. (2014) presented a method to synthesize single-walled carbon nanotubes, which have interesting electronic properties that make it a candidate material for extremely light wires in the onboard electronics of a graphene-class sail. Carbon nanotubes might also be the natural choice for a material to build a rigid sail skeleton of. Sorensen et al. (2016) patented a high-yield method for the gram-scale production of pristine graphene nanosheets through a controlled, catalyst-free detonation of C2H2 in the presence of O2.

Private companies offer cm²-sized mono-atomic layers of graphene sheets at a price of about 75 EUR, which translates into a price of 750 million EUR for a 10⁵ m² sail. If the price decline for graphene production continues its trend of three orders of magnitude per decade over the next 10 years, this could result in costs of 750,000 EUR for the production of graphene required for a 10⁵ m² sail in the late 2020s. The availability of affordable, high-quality graphene for large structures is key to the mission concept assumed in this study.

One key challenge that will affect the sail’s performance of a photogravitational assist is in the emergence of inhomogeneities of the reflectivity across the sail area. A sail reflectivity of 99.99% has been assumed in our calculations, but the bombardment of the interstellar medium will create tiny holes in the sail (Hoang et al. 2017) that would cause local decreases of reflectivity. Certainly, the sail would need to be able to autonomously compensate for the resulting torques during the deceleration phase, e.g., via proper orientation with respect to the approaching star.

5. Conclusion

This report describes a new means of using stellar photons, e.g., in the α Cen system, to decelerate and deflect an incoming ultralight photon sail from Earth. This improved method of using photogravitational assists is different from gravitational slingshots as they have been performed many times in the solar system and different from the photogravitational assists described by Heller & Hippke (2017), in the sense that the lightsail is not flung around the star but it rather passes in front of it. In other words, we propose that the star is not being used as a catapult but rather as a bumper. If the mass-to-surface ratio of the lightsail is sufficiently small, then photogravitational assists may absorb enough kinetic energy to park it in a bound circumstellar orbit or even transfer it to other stellar or planetary members in the system.

Proxima b, the closest extrasolar planet to us, is a natural prime target for such an interstellar lightsail. Its M dwarf host star has a very low luminosity that could only absorb small amounts of kinetic energy from an incoming lightsail. Its two companion stars α Cen A and B, however, have roughly Sun-like luminosities, which means that successive photogravitational assists at α Cen A, B, and Proxima could be sufficiently effective to bring an ultralight photon sail to rest.

In this paper, we investigate the case of a graphene-class sail with a nominal mass-to-surface ratio of σnorm = 8.6 × 10⁻⁴ g m⁻² and find that our improved “bumper” technique of using photogravitational assists allows maximum injection speeds of up to vₜₚ,ₘₐₓ = 17,050 km s⁻¹ (5.7% c) at α Cen A, implying travel times as short as 75 years from Earth. The
maximum injection speed at Proxima is 1270 km s\(^{-1}\), which the sail would be left with after assists at \(\alpha\) Cen A and B. This residual speed means another 46 years of travel between the AB binary and Proxima, or a total of 121 years from Earth. Travel times for lightsails with larger mass-to-surface ratios (\(\sigma\)) scale as \(\sqrt{\sigma/\sigma_{\text{nom}}}\).

The exact value of \(v_{\text{c, max}}\) at the \(\alpha\) Cen system depends on the deflection angle (\(\delta\)) required by the sail to go from A to B and, hence, \(v_{\text{c, max}}\) depends on the instantaneous orbital alignment of the AB binary upon arrival of the sail. We performed numerical simulations of sail trajectories under the effects of both the gravitational forces between the sail and the star and the stellar photon pressure acting upon the sail to parameterize \(v_{\text{c, max}}(\delta)\). We then used calculations of the orbital motions of the AB stars to first obtain \(\delta(t)\) and then \(v_{\text{c, max}}(t)\) for the next 300 years. This provides us with the expected travel times \(t\) for the next 300 years. This provides us with the expected travel times between the maximum and minimum travel times to permit late 2167 after 75 years of interstellar travel. The difference in travel times \(\tau(t)\) and with the times of arrival at \(\alpha\) Cen A for launches within the next 300 years. In general, we find that 75 years \(\leq \tau(t) \leq 95\) years for a graphene-class sail cruising with \(v_{\text{c, max}}\).

A minimum in the travel time, which might be interesting for real mission planning, occurs for a departure on 2092 September 8 with a photogravitational assist at \(\alpha\) Cen A in late 2167 after 75 years of interstellar travel. The difference between the maximum and minimum travel times to permit photogravitational assists from \(\alpha\) Cen A via B to Proxima is only about 20 years, so that an earlier departure (e.g., in 2040) might entail somewhat longer travel times (e.g., 91 years) but still allow a much earlier arrival (e.g., 2131) than the departure near the next minimum of \(\tau(t)\).

Beyond that, photogravitational assists may allow injections into bound orbits around other nearby stars within relatively short travel times. We identified Sirius A as the star that permits the shortest travel times for a lightsail using stellar photons to decelerate into a bound orbit. At a distance of about 8.6 lt-yr, it is almost twice as distant as the \(\alpha\) Cen system, but its huge power output of about 24 solar luminosities allows injection speeds of up to \(v_{\text{c, max}} = 37,300\, \text{km s}^{-1}\) (12.5% \(c\)). These speeds cannot be obtained from the solar photons alone upon departure from the solar system, and so additional technologies (e.g., a ground-based laser array) will need to be used to accelerate the sail to the maximum injection speed at Sirius A. Beyond the compelling opportunity of sending an interstellar spacecraft into a bound orbit around Sirius A within a human lifetime, its white dwarf companion Sirius B could be visited as well using a photogravitational assist at Sirius A. We identify other interesting targets in the solar neighborhood that allow photogravitational assists into bound orbits, the first 10 of which imply travel times between about 75 years (\(\alpha\) Cen AB) and 360 years (Epsilon Eridani) with a nominal graphene-class lightsail.

Many of the technological components of the lightsail envisioned in this study are already available, e.g., conventional spacecraft to bring the lightsails into near-Earth orbits for Sun- or laser-assisted departure. Other components are currently being developed, e.g., procedures for the large-scale production of graphene sheets, nanowires with the necessary electronic properties consisting of single carbon atom layers, gram-scale cameras and lasers (for communication between the sail and Earth), or sub-gram-scale computer chips required to perform onboard processing, etc. We thus expect that a concerted effort of electronic, nano-scale, and space industries and research consortia could permit the construction and launch of ultralight photon sails capable of interstellar travels and photogravitational assists, e.g., to Proxima b, within the next few decades.

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