On the Growth Rate of the Weight Distribution of Irregular Doubly-Generalized LDPC Codes

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Abstract

In this paper, an expression for the asymptotic growth rate of the number of small linear-weight codewords of irregular doubly-generalized LDPC (D-GLDPC) codes is derived. The expression is compact and generalizes existing results for LDPC and generalized LDPC (GLDPC) codes. Ensembles with check or variable node minimum distance greater than 2 are shown to be have good growth rate behavior, while for other ensembles a fundamental parameter is identified which discriminates between an asymptotically small and an asymptotically large expected number of small linear-weight codewords. Also, in the latter case it is shown that the growth rate depends only on the check and variable nodes with minimum distance 2. An important connection between this new result and the stability condition of D-GLDPC codes over the BEC is highlighted. Such a connection, previously observed for LDPC and GLDPC codes, is now extended to the case of D-GLDPC codes. Finally, it is shown that the analysis may be extended to include the growth rate of the stopping set size distribution of irregular D-GLDPC codes.

Index Terms

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I. INTRODUCTION

Recently, low-density parity-check (LDPC) codes have been intensively studied due to their near-Shannon-limit performance under iterative belief-propagation decoding. Binary regular LDPC codes were first proposed by Gallager in 1963 [1]. In the last decade the capability of irregular LDPC codes to outperform regular ones in the waterfall region of the performance curve and to asymptotically approach (or even achieve) the communication channel capacity has been recognized and deeply investigated (see for instance [2], [3], [4], [5], [6], [7]).

It is usual to represent an LDPC code as a bipartite graph, i.e., as a graph where the nodes are grouped into two disjoint sets, namely, the variable nodes (VNs) and the check nodes (CNs), such that each edge may only connect a VN to a CN. The bipartite graph is also known as a Tanner graph [8]. In the Tanner graph of an LDPC code, a generic degree-$q$ VN can be interpreted as a length-$q$ repetition code, as it repeats $q$ times its single information bit towards the CNs. Similarly, a degree-$s$ CN of an LDPC code can be interpreted as a length-$s$ single parity-check (SPC) code, as it checks the parity of the $s$ VNs connected to it.

The growth rate of the weight distribution of Gallager’s regular LDPC codes was investigated in [1]. The analysis demonstrated that, provided that the smallest VN degree is at least 3, the ensemble has good growth rate behavior, i.e. a code randomly chosen from the ensemble contains an asymptotically small expected number of small linear-weight codewords.

More recently, the study of the weight distribution of binary LDPC codes has been extended to irregular ensembles. Pioneering works in this area are [9], [10], [11]. In [11] a complete solution for the growth rate of the weight distribution of binary irregular LDPC codes was developed. One of the main results of [11] is a connection between the expected behavior of the weight distribution of a code randomly chosen from the ensemble and the parameter $\lambda'(0)\rho'(1)$, $\lambda(x)$ and $\rho(x)$ being the edge-perspective VN and CN degree distributions, respectively. More specifically, it was shown that for a code randomly chosen from the ensemble, one can expect an exponentially small number of small linear-weight codewords if $0 \leq \lambda'(0)\rho'(1) < 1$, and an exponentially large number of small linear-weight codewords if $\lambda'(0)\rho'(1) > 1$.

This result establishes a connection between the statistical properties of the weight distribution of binary irregular LDPC codes and the stability condition of binary irregular LDPC codes over 2
Prior to the rediscovery of LDPC codes, binary generalized LDPC (GLDPC) codes were introduced by Tanner in 1981 [8]. A GLDPC code generalizes the concept of an LDPC code in that a degree-$s$ CN may in principle be any $(s, h)$ linear block code, $s$ being the code length and $h$ the code dimension. Such a CN accounts for $s - h$ linearly independent parity-check equations. A CN associated with a linear block code which is not a SPC code is said to be a generalized CN. In [8] regular GLDPC codes (also known as Tanner codes) were investigated, these being GLDPC codes where the VNs are all repetition codes of the same length and the CNs are all linear block codes of the same type.

The growth rate of the weight distribution of binary GLDPC codes was investigated in [12], [13], [14], [15]. In [12] the growth rate is calculated for Tanner codes with BCH check component codes and length-2 repetition VNs, leading to an asymptotic lower bound on the minimum distance. The same lower bound is developed in [13] assuming Hamming CNs and length-2 repetition VNs. Both works extend the approach developed by Gallager in [1] Chapter 2] to show that these ensembles have good growth rate behavior. The growth rate of the number of small weight codewords for GLDPC codes with a uniform CN set (all CN of the same type) and an irregular VN set (repetition VNs with different lengths) is investigated in [14]. It is shown
that the ensemble has good growth rate behavior when either the uniform CN set is composed of linear block codes with minimum distance at least 3, or the minimum length of the repetition VNs is 3. On the other hand, if the minimum distance of the CNs and the minimum length of the repetition VNs are both equal to 2, the goodness or otherwise of the growth rate behavior of the ensemble depends on the sign of the first order coefficient in the growth rate Taylor series expansion. The results developed in [14] were further extended in [15] to GLDPC ensembles with an irregular CN set (CNs of different types). It was there proved that, provided that there exist CNs with minimum distance 2, a parameter $\lambda'(0)C$, generalizing the parameter $\lambda'(0)\rho'(1)$ of LDPC code ensembles, plays in the context of the weight distribution of GLDPC codes the same role played by $\lambda'(0)\rho'(1)$ in the context of the weight distribution of LDPC codes. The parameter $C$ is defined in Section III.

Interestingly, this latter results extends to binary GLDPC codes the same connection between the statistical properties of the weight distribution of irregular codes and the stability condition over the BEC. In fact, it was shown in [16] that the stability condition of binary irregular GLDPC codes over the BEC is given by

$$q^* \leq [\lambda'(0)C]^{-1}.$$  \hspace{1cm} (2)

Generalized LDPC codes represent a promising solution for low-rate channel coding schemes, due to an overall rate loss introduced by the generalized CNs [17]. Doubly-generalized LDPC (D-GLDPC) codes generalize the concept of GLDPC codes while facilitating much greater design flexibility in terms of code rate [18] (an analogous idea may be found in the previous work [19]). In a D-GLDPC code, the VNs as well as the CNs may be of any generic linear block code types. A degree-$q$ VN may in principle be any $(q,k)$ linear block code, $q$ being the code length and $k$ the code dimension. Such a VN is associated with $k$ D-GLDPC code bits. It interprets these bits as its local information bits and interfaces to the CN set through its $q$ local code bits. A VN which corresponds to a linear block code which is not a repetition code is said to be a generalized VN. A D-GLDPC code is said to be regular if all of its VNs are of the same type and all of its CNs are of the same type and is said to be irregular otherwise. The structure of a D-GLDPC code is depicted in Fig. I.

1Note that VNs associated with different representations of the same linear block code (i.e. with different generator matrices) are regarded as belonging to different types.
A related class of bipartite-graph codes was considered in [20] where both CNs and VNs were generalized, but where the code bits were associated directly with the edges of the Tanner graph (and thus the generator matrices associated with VNs were irrelevant). In this work it was shown that in certain regular code ensembles with the same local code of minimum distance \( \geq 3 \) at every CN and VN, asymptotically good codes exist in the ensemble which meet the Gilbert-Varshamov bound. These ensembles are generalizations of expander code ensembles [21]. Also, [22] presented similar results in the context of regular hypergraph codes with random coding at the nodes (for a fixed hypergraph), random hypergraphs (with the same local code at every CN and VN), and random selection of both hypergraph and local codes. Also, [23] investigates the asymptotic weight enumerators of many LDPC-like codes including turbo codes and repeat-accumulate codes.

In this paper the growth rate of the weight distribution of binary irregular D-GLDPC codes is analyzed for small weight codewords. It is shown that a given irregular D-GLDPC code ensemble has good growth rate behavior when there are no VNs with minimum distance 2, and likewise when there are no CNs with minimum distance 2. It is also shown that, in the case where there exist both VNs and CNs with minimum distance 2, a parameter \( 1/P^{-1}(1/C) \) discriminates between an asymptotically small and an asymptotically large expected number of small linear-weight codewords (the function \( P(x) \) is defined in Section III). The parameter \( 1/P^{-1}(1/C) \) generalizes the above mentioned parameters \( \lambda'(0)\rho'(1) \) and \( \lambda'(0)C \) to the case where both generalized VNs and generalized CNs are present. The obtained result also represents the extension to the D-GLDPC case of the previously recalled connection with the stability condition over the BEC. In fact, it was proved in [16, Theorem 2] that the stability condition of D-GLDPC codes over the BEC is given by

\[
q^* \leq P^{-1}(1/C) .
\]  

The paper is organized as follows. Section II defines the D-GLDPC ensemble of interest, and introduces some definitions and notation pertaining to this ensemble. Section III defines further terms regarding the VNs and CNs which compose the D-GLDPC codes in the ensemble. Section IV presents the main result of the paper regarding the growth rate of the weight distribution, together with several corollaries. Section V proves this main result, and Section VI concludes the paper.
II. IRREGULAR DOUBLY-GENERALIZED LDPC CODE ENSEMBLE

We define a D-GLDPC code ensemble \( \mathcal{M}_n \) as follows, where \( n \) denotes the number of VNs. There are \( n_c \) different CN types \( t \in I_c = \{1, 2, \cdots, n_c\} \), and \( n_v \) different VN types \( t \in I_v = \{1, 2, \cdots, n_v\} \). For each CN type \( t \in I_c \), we denote by \( h_t, s_t \) and \( r_t \) the CN dimension, length and minimum distance, respectively. For each VN type \( t \in I_v \), we denote by \( k_t, q_t \) and \( p_t \) the VN dimension, length and minimum distance, respectively. For \( t \in I_c \), \( \rho_t \) denotes the fraction of edges connected to CNs of type \( t \). Similarly, for \( t \in I_v \), \( \lambda_t \) denotes the fraction of edges connected to VNs of type \( t \). Note that all of these variables are independent of \( n \).

The polynomials \( \rho(x) \) and \( \lambda(x) \) are defined by

\[
\rho(x) = \sum_{t \in I_c} \rho_t x^{s_t-1}
\]

and

\[
\lambda(x) = \sum_{t \in I_v} \lambda_t x^{q_t-1}.
\]

If \( E \) denotes the number of edges in the Tanner graph, the number of CNs of type \( t \in I_c \) is then given by \( E \rho_t / s_t \), and the number of VNs of type \( t \in I_v \) is then given by \( E \lambda_t / q_t \). Denoting as usual \( \int_0^1 \rho(x) \, dx \) and \( \int_0^1 \lambda(x) \, dx \) by \( \int \rho \) and \( \int \lambda \) respectively, we see that the number of edges in the Tanner graph is given by

\[
E = \frac{n}{\int \lambda}
\]

and the number of CNs is given by \( m = E \int \rho \). Therefore, the fraction of CNs of type \( t \in I_c \) is given by

\[
\gamma_t = \frac{\rho_t}{s_t \int \rho} \quad (4)
\]

and the fraction of VNs of type \( t \in I_v \) is given by

\[
\delta_t = \frac{\lambda_t}{q_t \int \lambda} \quad (5)
\]

Also the length of any D-GLDPC codeword in the ensemble is given by

\[
N = \sum_{t \in I_v} \left( \frac{E \lambda_t}{q_t} \right) k_t = \frac{n}{\int \lambda} \sum_{t \in I_v} \frac{\lambda_t k_t}{q_t} \quad (6)
\]

Note that this is a linear function of \( n \). Similarly, the total number of parity-check equations for any D-GLDPC code in the ensemble is given by

\[
M = \frac{m}{\int \rho} \sum_{t \in I_c} \frac{\rho_t (s_t - h_t)}{s_t}
\]
A code in the irregular D-GLDPC ensemble then corresponds to a permutation on the $E$ edges connecting CNs to VNs. The design rate of the D-GLDPC ensemble is given by

$$R = 1 - \frac{M}{N} = 1 - \frac{\sum_{t \in I_c} \rho_t (1 - R_t)}{\sum_{t \in I_v} \lambda_t R_t}$$  \hspace{1cm} (7)$$

where for $t \in I_c$ (resp. $t \in I_v$), $R_t$ is the local code rate of CNs (resp. VNs) of type $t$. Each code in the ensemble has a code rate larger than or equal to $R$.

The growth rate of the weight distribution of the irregular D-GLDPC ensemble sequence $\{M_n\}$ is defined by

$$G(\alpha) = \lim_{n \to \infty} \frac{1}{n} \log \mathbb{E}_{M_n} [N_{\alpha n}]$$  \hspace{1cm} (8)$$

where $\mathbb{E}_{M_n}$ denotes the expectation operator over the ensemble $M_n$, and $N_w$ denotes the number of codewords of weight $w$ of a randomly chosen D-GLDPC code in the ensemble $M_n$. The limit in (8) assumes the inclusion of only those positive integers $n$ for which $\alpha n \in \mathbb{Z}$ and $\mathbb{E}_{M_n}[N_{\alpha n}]$ is positive (i.e., where the expression whose limit we seek is well defined). Note that the argument of the growth rate function $G(\alpha)$ is equal to the ratio of D-GLDPC codeword length to the number of VNs; by (6), this captures the behaviour of codewords linear in the block length, as in [11] for the LDPC case.

**Definition 2.1:** Let $G(\alpha)$ be the growth rate of the weight distribution of an irregular D-GLDPC ensemble sequence. The critical exponent codeword weight ratio is defined as $\alpha^* = \inf\{\alpha > 0 \mid G(\alpha) \geq 0\}$. Also, the ensemble sequence is said to have **good growth rate behavior** if $\alpha^* > 0$, and **bad growth rate behavior** if $\alpha^* = 0$.

Thus an irregular D-GLDPC code ensemble sequence has good growth rate behavior if and only if it contains an asymptotically small expected number of small linear-weight codewords. Note that an ensemble with good growth rate behavior must necessarily contain asymptotically good code sequences. The present definition of the critical exponent codeword weight ratio may also be found in [27].

We next define the concepts of assignment and split assignment. The concept of assignment was used in [11] to develop an expression for the growth rate of the weight distribution of irregular LDPC code ensembles. The concept of split assignment is introduced in this paper.

**Definition 2.2:** An assignment is a subset of the edges of the Tanner graph. An assignment is said to have **weight** $k$ if it has $k$ elements. An assignment is said to be **check-valid** if the
following condition holds: supposing that each edge of the assignment carries a 1 and each of the other edges carries a 0, each CN recognizes a valid local codeword.

**Definition 2.3:** A split assignment is an assignment, together with a subset of the D-GLDPC code bits (called a codeword assignment). A split assignment is said to have split weight \((u, v)\) if its assignment has weight \(v\) and its codeword assignment has \(u\) elements. A split assignment is said to be check-valid if its assignment is check-valid. A split assignment is said to be variable-valid if the following condition holds: supposing that each edge of its assignment carries a 1 and each of the other edges carries a 0, and supposing that each D-GLDPC code bit in the codeword assignment is set to 1 and each of the other code bits is set to 0, each VN recognizes a local input word and the corresponding valid local codeword.

Note that for any D-GLDPC code, there is a bijective correspondence between the set of D-GLDPC codewords and the set of split assignments which are both variable-valid and check-valid.

### III. Further Definitions and Notation

The weight enumerating polynomial for CN type \(t \in I_c\) is given by

\[
A^{(t)}(x) = \sum_{u=0}^{s_t} A^{(t)}_u x^u = 1 + \sum_{u=r_t}^{s_t} A^{(t)}_u x^u.
\]

Here \(A^{(t)}_u \geq 0\) denotes the number of weight-\(u\) codewords for CNs of type \(t\). Note that \(A^{(t)}_{r_t} > 0\) for all \(t \in I_c\). Also, for each \(t \in I_c\), corresponding to the polynomial \(A^{(t)}(x)\) we denote the sets

\[
U_t = \{i \in \mathbb{N} : A^{(t)}_i > 0\}
\]

and

\[
U_t^- = U_t \setminus \{0\}.
\]

The bivariate weight enumerating polynomial for VN type \(t \in I_v\) is given by

\[
B^{(t)}(x, y) = \sum_{u=0}^{k_t} \sum_{v=0}^{q_t} B^{(t)}_{u,v} x^u y^v = 1 + \sum_{u=1}^{k_t} \sum_{v=p_t}^{q_t} B^{(t)}_{u,v} x^u y^v.
\]
Here $B_{u,v}^{(t)} \geq 0$ denotes the number of weight-$v$ codewords generated by input words of weight $u$, for VNs of type $t$. Also, for each $t \in I_v$, corresponding to the polynomial $B^{(t)}(x,y)$ we denote the sets

$$S_t = \{(i, j) \in \mathbb{N}^2 : B_{i,j}^{(t)} > 0\}$$

and

$$S_t^- = S_t \setminus \{(0, 0)\}.$$  

We also define

$$S^- = \bigcup_{t \in I_v} S_t^-.$$  

We denote the smallest minimum distance over all CN types by

$$r = \min\{r_t : t \in I_c\} \geq 2$$

and the set of CN types with this minimum distance by

$$X_c = \{t \in I_c : r_t = r\}.$$  

We define the parameter

$$\psi = r/(r - 1)$$

and note that we have $1 < \psi \leq 2$ with equality if and only if $r = 2$. We define the parameter

$$C = r \sum_{t \in X_c} \frac{p_t A_{s_t}^{(t)}}{s_t} > 0.$$  

We also define $\bar{r}$ as the smallest integer $i > r$ such that there exists some CN with a non-zero number of weight-$i$ codewords:

$$\bar{r} = \min\{i > r : A_i^{(t)} > 0 \text{ for some } t \in I_c \text{ and } i \in U_t^-\}.$$  

The parameter $\bar{r}$ represents the second smallest minimum distance over all CN types.

Similarly, we denote the smallest minimum distance over all VN types by

$$p = \min\{p_t : t \in I_v\} \geq 2$$

and the set of VN types with this minimum distance by

$$X_v = \{t \in I_v : p_t = p\}.$$
We also define $\bar{p}$ as the smallest integer $j > p$ such that there exists some VN with a non-zero number of weight-$j$ codewords:

$$\bar{p} = \min\{j > p : \exists t \in I_v, (i, j) \in S_t^{-} \}.$$  \hspace{1cm} (17)

The parameter $\bar{p}$ represents the second smallest minimum distance over all VN types.

For each $(i, j) \in S^{-}$, define

$$T_{i,j} = \frac{j - \psi}{i},$$  \hspace{1cm} (18)

and define the parameter

$$T = \min_{(i, j) \in S^{-}} \{T_{i,j}\}$$  \hspace{1cm} (19)

and the set

$$Y_v = \left\{ t \in I_v : \min_{(i, j) \in S_t^{-}} \{T_{i,j}\} = T \right\}.$$  \hspace{1cm} (20)

We also define the parameter

$$\chi = \min_{(i, j) \in S^{-} : T_{i,j} > T} \{(T_{i,j} - T)i\}.$$  \hspace{1cm} (21)

Since $1 < \psi \leq 2$ with equality if and only if $r = 2$, and $j \geq p \geq 2$ for all $(i, j) \in S^{-}$, it follows that $T \geq 0$ with equality if and only if $r = p = 2$. Also, for $t \in Y_v$, define

$$P_t = \left\{ (i, 2) \in S_t^{-} : \frac{j - \psi}{i} = T \right\}.$$  \hspace{1cm} (22)

Note that in the specific case $r = p = 2$, we have $T = 0$ and $Y_v = X_v$, and we may write $P_t = \{(i, 2) : i \in L_t\}$ where $L_t = \{i \in \mathbb{N} : B_{i,2}^{(t)} > 0\}$ for each $t \in X_v$ – note that these sets are nonempty.

We define the polynomials

$$Q_1(x) = \sum_{t \in Y_v} \frac{\lambda_t}{q_t} \sum_{(i, j) \in P_t} j B_{i,j}^{(t)} C^{j/r} \left( \frac{\int \lambda}{e} \right)^{iT/\psi} x^i$$ \hspace{1cm} (23)

and

$$Q_2(x) = \sum_{t \in Y_v} \frac{\lambda_t}{q_t} \sum_{(i, j) \in P_t} i B_{i,j}^{(t)} C^{j/r} \left( \frac{\int \lambda}{e} \right)^{iT/\psi} x^i.$$  \hspace{1cm} (24)

Since all of the coefficients of $Q_1(x)$ and $Q_2(x)$ are positive, these polynomials are both monotonically increasing on $[0, \infty)$ and therefore their inverses, denoted by $Q_1^{-1}(x)$ and $Q_2^{-1}(x)$
respectively, are well-defined and unique on this interval. Note that in the case $r = p = 2$, we have

$$Q_1(x) = C \cdot P(x)$$

where

$$P(x) = 2 \sum_{t \in X_v} \frac{\lambda_t}{q_t} \sum_{i \in L_t} B_{i,2}^{(t)} x^i .$$

(24)

Also note that in the case $r = p = 2$, (15) becomes

$$C = 2 \sum_{t \in X_v} \frac{\rho_t A_{2}^{(t)}}{s_t}$$

(25)

and we define

$$V = 2 \sum_{t \in X_v} \frac{\lambda_t B_{2}^{(t)}}{q_t} > 0$$

(26)

as the counterpart of the parameter $C$ in the variable node domain. Here $B_{2}^{(t)} = \sum_{i \in L_t} B_{i,2}^{(t)}$ is the total number of weight-2 codewords for VNs of type $t$. Note that in this case the parameter $C$ depends only on the CNs with minimum distance 2, and the parameter $V$ and the polynomial $P(x)$ depend only on the VNs with minimum distance 2. Also note that while the polynomial $P(x)$ given by (24) depends on the VN representations (i.e. generator matrices), the parameter $V$ given by (26) does not.

Throughout this paper, we make use of the following standard notation. Let $g(x)$ be a nonnegative real-valued function, and let $f(x)$ be a real-valued function. We say that $f(x)$ is $O(g(x))$, writing $f(x) \sim O(g(x))$, if and only if there exist positive real numbers $k$ and $\epsilon$, both independent of $x$, such that

$$|f(x)| \leq kg(x) \quad \forall \ 0 \leq x \leq \epsilon .$$

Let $a(n)$ and $b(n)$ be two real-valued sequences, where $b(n) \neq 0$ for all $n$, and let $q(n) = a(n)/b(n)$. We say that $a(n)$ is asymptotically equal to $b(n)$ as $n \to \infty$, writing $a(n) \overset{n}{\sim} b(n)$, if and only if $\lim_{n \to \infty} q(n) = 1$.

Finally, throughout this paper, the notation $e = \exp(1)$ denotes Napier’s number.
IV. GROWTH RATE FOR DOUBLY-GENERALIZED LDPC CODE ENSEMBLE

The following theorem constitutes the main result of the paper.

Theorem 4.1: Consider an irregular D-GLDPC code ensemble sequence $M_n$. The growth rate of the weight distribution is given by

$$G(\alpha) = \frac{T}{\psi} \alpha \log \alpha + \alpha \left[ \log \left( \frac{1}{Q_1^{-1}(1)} \right) + \frac{T}{\psi} \log \left( \frac{1}{Q_2(Q_1^{-1}(1))} \right) \right] + O(\alpha^\xi), \quad (27)$$

where

$$\xi = \min \left\{ \bar{r}, \chi + 1, 2 \right\}. \quad (28)$$

This theorem is proved in Section V. We next provide a series of corollaries to this result; this serves to illustrate the manner in which several related results in the literature follow as special cases of Theorem 4.1.

Corollary 4.2: In the case where either $r > 2$ or $p > 2$, the growth rate of the weight distribution is given by

$$G(\alpha) = \frac{T}{\psi} \alpha \log \alpha + O(\alpha), \quad (29)$$

where $T > 0$.

Thus if either $r > 2$ or $p > 2$, we have $\alpha^* > 0$ and the ensemble sequence exhibits good growth rate behavior. This generalizes results along this line in [14], [15], [20]. A special case of Corollary 4.2 is as follows.

Corollary 4.3: Suppose $r > 2$ or $p > 2$ and also $\bigcup_{t \in Y_v} P_t = \{(i, j)\}$ for a single point $(i, j)$, i.e. a single point $(i, j)$ achieves the minimum in (19) although this $(i, j)$ may be manifest in different VN types $t \in Y_v$. Then

$$G(\alpha) = \frac{T}{\psi} \alpha \log \alpha + K\alpha + O(\alpha^\xi), \quad (30)$$

where $K$ is given by

$$K = \frac{1}{i} \left[ \log \left( \sum_{t \in Y_v} B_{i,j}(t) \delta_t \right) + \frac{j}{r} \log C + \frac{j}{\psi} \log \left( \frac{j \int \lambda}{i} \right) \right] - \frac{T}{\psi}. \quad (31)$$
**Proof:** This result follows by making the appropriate substitutions in Theorem 4.1 and noting that in this case $Q_1(x)$ and $Q_2(x)$ are monomials satisfying $Q_2(Q_1^{-1}(1)) = i/j.$

**Corollary 4.4:** Consider a GLDPC code ensemble with irregular CN set and irregular VN set (i.e. different VN degrees). Let $r$ denote the smallest minimum distance of the CNs, and $p$ denote the minimum VN degree. Then

$$G(\alpha) = \left(p - \frac{P}{r} - 1\right) \alpha \log \alpha + K \alpha + O(\alpha^{\xi}) ,\quad (32)$$

where

$$K = \log \left(e \tilde{\delta}\right) + \frac{P}{r} \log C + \frac{p}{\psi} \log \left(\frac{p \int \lambda}{e}\right) .\quad (33)$$

where $\tilde{\delta}$ represents the fraction of VNs of degree $p$.

**Proof:** In this case, each VN type $t \in I_v$ satisfies $B^{(t)}(x, y) = 1 + xy^{pt}$. Let $\tilde{t} \in I_v$ represent the VN type with minimum length (degree), i.e., $p_{\tilde{t}} = p$, and note that $\tilde{\delta} = \delta_{\tilde{t}}$; then $Y_v = \{\tilde{t}\}$ and $\cup_{t \in Y_v} P_t = P_{\tilde{t}} = \{(1, p)\}$. Application of Corollary 4.3 then directly yields the required result, where we use the fact that $T = p - \psi$ in this case.

This provides a generalization of the result of [14] which derived (32) for the case of GLDPC codes with regular CN sets and irregular VN degrees, and which did not include the result (33) regarding the evaluation of the parameter $K$.

**Corollary 4.5:** Consider a D-GLPDC code ensemble $\mathcal{M}_n$ satisfying $r = p = 2$. Then the growth rate of the weight distribution is given by

$$G(\alpha) = \alpha \log \left[\frac{1}{P^{-1}(1/C)}\right] + O(\alpha^{\xi}) ,\quad (34)$$

where the polynomial $P(x)$ and the parameter $C$ are given by (24) and (25) respectively, and where

$$\xi = \min \left\{\frac{\bar{r}}{2}, \frac{\bar{p}}{2}, 2\right\} = \begin{cases} 2 & \text{if } \bar{r} > 3 \text{ or } \bar{p} > 3 \\ 3/2 & \text{otherwise.} \end{cases} \quad (35)$$

**Proof:** When $r = p = 2$, we have $T = 0$ and $\psi = 2$; also by (20) we have

$$\chi = \min_{(i,j) \in S^- : T_{i,j} > 0} \{iT_{i,j}\} = \min_{(i,j) \in S^- : j > 2} \{j - \psi\} = \bar{p} - 2 ,$$
which implies that $\chi/\psi + 1 = \bar{p}/2$. Also, it may be verified that $Q_1^{-1}(1) = P^{-1}(1/C)$ in this case.

Corollary 4.5 first appeared in [24]. A necessary and sufficient condition for a D-GLDPC ensemble satisfying $r = p = 2$ to have good growth rate behavior follows in a straightforward manner as shown next.

**Corollary 4.6:** Consider a D-GLPDC code ensemble $\mathcal{M}_n$ satisfying $r = p = 2$. Then, a necessary and sufficient condition for $\mathcal{M}_n$ to have good growth rate behavior is

$$C \cdot V < 1$$

(36)

where $C$ and $V$ are given by (25) and (26) respectively.

**Proof:** From (34) the necessary and sufficient condition is $1/P^{-1}(1/C) < 1$; rearranging and using the monotonicity of $P(x)$ yields the result.

It is worth noting that an analogous theorem to Theorem 4.1 holds also for the stopping set size distribution of irregular D-GLDPC codes. The proof is almost identical to that of Theorem 4.1 and is outlined in Appendix B.

A. **Discussion**

From Theorem 4.1 and from the definitions of $Q_1(x)$ and $Q_2(x)$ given in (22) and (23) respectively, we observe that the triples $(t, i, j)$ (or, equivalently, VN input-output weight enumerating function coefficients $B_{i,j}^{(t)}$) such that $(i, j)$ lies in one of the sets $P_t$ $(t \in Y_v)$ make a dominating contribution to the growth rate for values of $\alpha$ close to zero. We will refer to the set of such triples as the **dominant set**. Note that the dominant set may equivalently be described as the set of triples $(t, i, j)$ such that $T_{i,j} = T$ for some $t \in I_v$, $(i, j) \in S^{-}_t$.

Interestingly, the dominant set admits an instructive graphical interpretation and may be easily identified using a very simple geometric construction. In the $(i, j)$ plane, a line $L$ through the fixed point $(0, \psi)$ is rotated in an anticlockwise fashion until it comes in contact with one or more of the points $(i, j) \in S^{-}$. The slope of the line $L$ at this point is the parameter $T$ defined in (19), the set of $t \in I_v$ which have points $(i, j) \in L$ is the set defined as $Y_v$, and for each such $t$ the set of such points on $L$ is the set $P_t$ defined in (21). Note that due to (14), the position
of the fixed point \((0, \psi)\) depends only on the smallest CN minimum distance \(r\), and always lies somewhere on the line segment joining \((0, 1)\) and \((0, 2)\), including the latter endpoint.

This interpretation is illustrated in Fig. 2 for an example D-GLDPC code with two VN types \(I_v = \{1, 2\}\). Type 1 ∈ \(I_v\) (open circles) corresponds to the Hamming code of length \(q_1 = 7\), dimension \(k_1 = 4\), minimum distance \(p_1 = 3\) and represented by the systematic generator matrix \(G_H = [1000111, 0100110, 0010101, 0001011]\). Type 2 ∈ \(I_v\) (filled diamonds) corresponds to the first-order Reed-Muller code of length \(q_2 = 8\), dimension \(k_2 = 4\), minimum distance \(p_2 = 4\) and represented by the generator matrix \(G_{RM} = [11111111, 11110000, 11001100, 10101010]\). In the

Fig. 2. Diagram of the VN input-output weight enumerating functions and growth rate dominant set in the \((i, j)\) plane. The illustration is for a smallest CN minimum distance of \(r = 3\), so \(\psi = 3/2\). The sets \(S_t^{-}\) for the two VN types \(t \in I_v = \{1, 2\}\) are illustrated by open circles and filled diamonds respectively. The line \(L\) has a fixed point at \((0, \psi)\) and is rotated in an anticlockwise fashion until it touches any of these points. In this example, this occurs at the point \((3, 3)\) ∈ \(S_1^{-}\). Therefore in this example \(T = 1/2\), \(Y_v = \{1\}\), \(P_1 = \{(3, 3)\}\) and for small values of \(\alpha\) the dominating contribution to the growth rate comes from weight-3 local codewords of the type-1 VNs generated by weight-3 local input words.
specific case of Fig. 2 we have \( \psi = 3/2 \), which corresponds to \( r = 3/2 \). It may be deduced from the figure that for values of \( \alpha \) close to zero the growth rate \( G(\alpha) \) is dominated by weight-3 local codewords of the Hamming VNs associated with weight-3 local input words.

From Corollary 4.5 we observe that in the special case where \( r = p = 2 \), the growth rate depends only on the CNs and VNs with minimum distance equal to 2, and (34) is a first-order Taylor series around \( \alpha = 0 \) which directly generalizes the results of [11] and [15] (for irregular LDPC and GLDPC codes respectively) to the case of irregular D-GLDPC codes. Note that the error term in (34) is \( O(\alpha^2) \), which is different to the error term \( O(\alpha^2) \) reported in previous literature (Theorem 4.1 in [24], Theorem 5 in [11]); this difference is manifest in the case where \( r = p = 2 \) and either \( \bar{r} = 3 \) or \( \bar{p} = 3 \). Corollary 4.5 indicates that in the analysis of the asymptotic growth rate of the weight distribution, the parameter \( \frac{1}{P} - \frac{1}{C} \) in the context of D-GLDPC codes plays an analagous role to the parameter \( \lambda'(0) \rho'(1) \) for irregular LDPC codes, and to the parameter \( \lambda'(0)C \) for irregular GLDPC codes. It discriminates between ensemble sequences with good growth rate behavior, for which \( 1/P^{-1}(1/C) < 1 \), and ensemble sequences with bad growth rate behavior, for which \( 1/P^{-1}(1/C) > 1 \).

V. PROOF OF THE MAIN RESULT

In this section, Theorem 4.1 is proved. For ease of presentation, the proof is broken into four parts.

A. Number of check-valid assignments of weight \( \epsilon m \) over \( \gamma m \) CNs of type \( t \in I_c \)

Consider \( \gamma m \) CNs of the same type \( t \in I_c \). Using generating functions, the number of check-valid assignments (over these CNs) of weight \( \epsilon m \) is given by:

\[
N_{c,t}^{(\gamma m)}(\epsilon m) = \text{Coeff} \left[ \left( A^{(t)}(x) \right)^{\gamma m}, x^{\epsilon m} \right]
\]

For example, assuming a uniform CN set composed of \((15, 11)\) Hamming codes, and assuming \( \lambda_1 = 7/15 \) and \( \lambda_2 = 8/15 \), through 4 this would represent a rate \( R = 1/2 \) ensemble.

Here we make use of the following general result 3. Let \( a_i \) be the number of ways of obtaining an outcome \( i \in Z \) in experiment \( A \), and let \( b_j \) be the number of ways of obtaining an outcome \( j \in Z \) in experiment \( B \). Also let \( c_k \) be the number of ways of obtaining an outcome \( (i,j) \) in the combined experiment \( (A,B) \) with sum \( i + j = k \). Then the generating functions \( A(x) = \sum_i a_ix^i, B(x) = \sum_j b_jx^j \) and \( C(x) = \sum_c c_kx^k \) are related by \( C(x) = A(x)B(x) \).
where \( \text{Coeff} [p(x), x^c] \) denotes the coefficient of \( x^c \) in the polynomial \( p(x) \). We now use the following result, the proof of which appears in [10, Appendix A]:

**Lemma 5.1:** Let \( A(x) = 1 + \sum_{u=c}^{d} A_u x^u \), where \( 1 \leq c \leq d \), be a polynomial satisfying \( A_c > 0 \) and \( A_u \geq 0 \) for all \( c < u \leq d \). For a fixed positive rational number \( \xi \), consider the set of positive integers \( \ell \) such that \( \xi \ell \in \mathbb{N} \) and \( \text{Coeff} [(A(x))^{\ell}, x^{\ell \xi}] > 0 \). Then either this set is empty, or it has infinite cardinality; if \( t \) is one such \( \ell \), then so is \( j t \) for every positive integer \( j \). In the latter case, the following limit is well defined and exists:

\[
\lim_{\ell \to \infty} \frac{1}{\ell} \log \text{Coeff} \left[ (A(x))^{\ell}, x^{\ell \xi} \right] = \max_{\beta} \sum_{i \in U} \beta_i \log \left( \frac{A_i}{\beta_i} \right)
\]  

(37)

where \( U = \{ i \in \mathbb{N} : A_i > 0 \} \), \( \beta = (\beta_i)_{i \in U} \), and the maximization is subject to the constraints \( \sum_{i \in U} \beta_i = 1 \), \( \sum_{i \in U} i \beta_i = \xi \) and \( \beta_i \geq 0 \) for all \( i \in U \).

Applying this lemma by substituting \( A(x) = A(t)^{(t)}(x) \), \( \ell = \gamma m \) and \( \xi = \epsilon / \gamma \), we obtain that with \( \gamma \) fixed, as \( m \to \infty \)

\[
N_{c,t}^{(\gamma m)}(\epsilon m) = \text{Coeff} \left[ (A(t)(x))^{\gamma m}, x^{\gamma m} \right]
\]

(38)

\[
\approx \exp \left\{ m \gamma \max_{\beta(t)} \sum_{i \in U_t} \beta_i^{(t)} \log \left( \frac{A_i^{(t)}}{\beta_i^{(t)}} \right) \right\}
\]

(39)

\[
\triangleq \exp \left\{ m W_{t}^{(\gamma)}(\epsilon) \right\}
\]

(40)

where the maximization over \( \beta(t) = (\beta_i^{(t)})_{i \in U_t} \) is subject to the constraints \( \sum_{i \in U_t} \beta_i^{(t)} = 1 \), \( \sum_{i \in U_t^c} i \beta_i^{(t)} = \epsilon / \gamma \) and \( \beta_i^{(t)} \geq 0 \) for all \( i \in U_t \) (recall that the sets \( U_t \) and \( U_t^c \) are given by (9) and (10)).

**B. Number of check-valid assignments of weight \( \delta m \)**

Next we derive an expression, valid asymptotically, for the number of check-valid assignments of weight \( \delta m \). For each \( t \in I_c \), let \( \epsilon_t m \) denote the portion of the total weight \( \delta m \) apportioned to CNs of type \( t \). Then \( \epsilon_t \geq 0 \) for each \( t \in I_c \), and \( \sum_{t \in I_c} \epsilon_t = \delta \). Also denote \( \epsilon = (\epsilon_1 \epsilon_2 \cdots \epsilon_{n_c}) \).

The number of check-valid assignments of weight \( \delta m \) satisfying the constraint \( \epsilon \) is obtained by multiplying the numbers of check-valid assignments of weight \( \epsilon_t m \) over \( \gamma_t m \) CNs of type \( t \), for each \( t \in I_c \),

\[
N_c^{(\epsilon)}(\delta m) = \prod_{t \in I_c} N_{c,t}^{(\gamma_t m)}(\epsilon_t m)
\]

(41)
where the fraction $\gamma_t$ of CNs of type $t \in I_c$ is given by (4).

The number of check-valid assignments of weight $\delta m$, which we denote $N_c(\delta m)$, is equal to the sum of $N_c(\epsilon)(\delta m)$ over all admissible vectors $\epsilon$; therefore, as $m \to \infty$

$$N_c(\delta m) \approx \sum_{\epsilon : \sum_{t \in I_c} \epsilon_t = \delta} \exp \left\{ m \sum_{t \in I_c} W_t(\gamma_t)(\epsilon_t) \right\}$$  \hspace{1cm} (42)

where we have used (40) and (41). However, the asymptotic expression as $m \to \infty$ is dominated by the distribution $\epsilon$ which maximizes the argument of the exponential. Therefore as $m \to \infty$

$$N_c(\delta m)^m \approx \exp \{ mW \}$$  \hspace{1cm} (43)

where

$$W = \max_{\epsilon} \sum_{t \in I_c} \gamma_t \max_{\beta(t)} \sum_{i \in U_t} \beta_i(t) \log \left( \frac{A_i(t)}{\beta_i(t)} \right) ,$$  \hspace{1cm} (44)

the maximization over $\epsilon$ is subject to the constraint

$$\sum_{t \in I_c} \epsilon_t = \delta ,$$  \hspace{1cm} (45)

and for each $t \in I_c$ the maximization over $\beta(t) = (\beta_i(t))_{i \in U_t}$ is subject to the constraints

$$\sum_{i \in U_t} \beta_i(t) = 1$$  \hspace{1cm} (46)

$$\sum_{i \in U_t^\perp} i \beta_i(t) = \epsilon_t / \gamma_t$$  \hspace{1cm} (47)

and

$$\beta_i(t) \geq 0 \ \forall i \in U_t .$$  \hspace{1cm} (48)

Next, for each $t \in I_c$ we define

$$F_t(\beta(t)) = \beta_0(t) \log \left( \frac{1}{\beta_0(t)} \right) - \sum_{i \in U_t^\perp} \beta_i(t) .$$

We then have the following lemma.

\textbf{Lemma 5.2}: The expression $\sum_{t \in I_c} \gamma_t F_t(\beta(t))$ is $O(\delta^2)$ for any $\beta(t)$ satisfying the optimization constraints (45)–(48).

\footnote{Observe that as $m \to \infty$, $\sum_t \exp(mZ_t) \approx \exp(m \max_t \{ Z_t \})$}
A proof of this lemma is given in Appendix A. It follows from Lemma 5.2 that the expression
\[ \sum_{t \in I_c} \gamma_t F_t(\beta^{(t)}) \] is \( O(\delta^2) \) for the maximizing \( \beta^{(t)} \). Therefore

\[
W = \max_{\epsilon} \sum_{t \in I_c} \gamma_t \max_{\beta^{(t)}} \left[ \sum_{i \in U_t^-} \beta_i^{(t)} \log \left( \frac{eA_i^{(t)}}{\beta_i^{(t)}} \right) + F_t(\beta^{(t)}) \right]
\]

\[
= \max_{\epsilon} \sum_{t \in I_c} \gamma_t \max_{\beta^{(t)}} \sum_{i \in U_t^-} \beta_i^{(t)} \log \left( \frac{eA_i^{(t)}}{\beta_i^{(t)}} \right) + O(\delta^2)
\]

where the maximization over \( \beta^{(t)} = (\beta_i^{(t)})_{i \in U_t^-} \) (for each \( t \in I_c \)) is subject to the constraint \( (47) \) together with \( \beta_i^{(t)} \geq 0 \) for all \( i \in U_t^- \). In what follows, for convenience of presentation we shall temporarily omit the \( O(\delta^2) \) term in the expression for \( W \).

Next we make the substitution \( \theta_i^{(t)} = \gamma_t \beta_i^{(t)} \) for all \( t \in I_c, i \in U_t^- \). This yields

\[
W = \max_{\epsilon} \sum_{t \in I_c} \max_{\theta^{(t)}} \sum_{i \in U_t^-} \theta_i^{(t)} \log \left( \frac{eA_i^{(t)} \gamma_t}{\theta_i^{(t)}} \right)
\]

where the maximization over \( \theta^{(t)} = (\theta_i^{(t)})_{i \in U_t^-} \) (for each \( t \in I_c \)) is subject to the constraints \( \sum_{i \in U_t^-} i \theta_i^{(t)} = \epsilon_t \) and \( \theta_i^{(t)} \geq 0 \) for all \( i \in U_t^- \). We observe that this maximization may be recast as

\[
W = \max_{\theta} \sum_{t \in I_c} \sum_{i \in U_t^-} \theta_i^{(t)} \log \left( \frac{eA_i^{(t)} \gamma_t}{\theta_i^{(t)}} \right)
\]

where by (45) the maximization, which is now over \( \theta = (\theta_i^{(t)})_{t \in I_c, i \in U_t^-} \), is subject to the constraints

\[
\sum_{t \in I_c} \sum_{i \in U_t^-} i \theta_i^{(t)} = \delta
\]

and \( \theta_i^{(t)} \geq 0 \) for all \( t \in I_c, i \in U_t^- \).

Making the substitution \( \upsilon_i^{(t)} = \theta_i^{(t)}/\delta \) for all \( t \in I_c, i \in U_t^- \), we obtain

\[
W = \delta \max_{\upsilon} \sum_{t \in I_c} \sum_{i \in U_t^-} \upsilon_i^{(t)} \log \left( \frac{eA_i^{(t)} \gamma_t}{\delta \upsilon_i^{(t)}} \right)
\]

(49)

where the maximization over \( \upsilon = (\upsilon_i^{(t)})_{t \in I_c, i \in U_t^-} \) is subject to the constraints

\[
\sum_{t \in I_c} \sum_{i \in U_t^-} i \upsilon_i^{(t)} = 1
\]

(50)

and \( \upsilon_i^{(t)} \geq 0 \) for all \( t \in I_c, i \in U_t^- \).
Solving the constrained optimization (49) using Lagrange multipliers yields
\[
v_i(t) = \frac{A_i(t) \gamma_t}{\delta} e^{-i\lambda} \quad \forall t \in I_c, i \in U^-_t, \tag{51}
\]
where \(\lambda\) is the Lagrange multiplier. Substituting (51) into (50) and defining \(z = e^{-\lambda}\) yields
\[
\sum_{t \in I_c} \sum_{i \in U^-_t} \frac{A_i(t)}{\delta} \gamma_t z^i = \delta. \tag{52}
\]
We may write this as
\[
\sum_{t \in X_c} rA_r(t) \gamma_t z^r + \sum_{t \in I_c} \sum_{i \in U^-_t \setminus \{r\}} iA_i(t) \gamma_t z^i = \delta \tag{53}
\]
from which we obtain (since all coefficients are positive and \(z = e^{-\lambda} > 0\))
\[
\sum_{t \in X_c} rA_r(t) \gamma_t z^r \leq \delta
\]
and therefore
\[
z \leq \frac{1}{\left(\sum_{t \in X_c} rA_r(t) \gamma_t\right)^{1/r} \delta^{1/r}} \tag{54}
\]
is valid for all \(\delta > 0\). Thus
\[
z \sim O(\delta^{1/r}). \tag{55}
\]
Recalling the definition \(z = e^{-\lambda}\), (51) and (55) together imply that
\[
v_i(t) \sim O(\delta^{i/r-1}) \quad \forall t \in I_c, i \in U^-_t. \tag{56}
\]
Next, since the value of \(\upsilon\) which achieves the maximum in (49) satisfies (51), we may develop (49) as
\[
W = \delta \sum_{t \in I_c} \sum_{i \in U^-_t} v_i(t) (1 + i\lambda) \tag{57}
\]
\[
= \delta \left(\sum_{t \in I_c} \sum_{i \in U^-_t} v_i(t) + \lambda\right) \tag{58}
\]
where in the second line we have used the constraint (50).

Now, the constraint (50) may be written as
\[
1 = \sum_{t \in I_c} \sum_{i \in U^-_t} rv_i(t) + \sum_{i,j : i > r} (i - r)v_i(t)
\]

20
\[
\sum_{t \in I} \sum_{i \in U_t} v_i^{(t)} = \frac{1}{r} - \frac{1}{r} \sum_{t,i : i > r} (i - r)v_i^{(t)}. \quad (59)
\]

Also, we may write by (51)
\[
\delta v_i^{(t)} e^{r\lambda} = A_r^{(t)} \gamma_t, \quad \forall t \in X_c.
\]

Multiplying by \(r\) and summing over all \(t \in X_c\) yields
\[
\delta e^{r\lambda} \sum_{t \in X_c} r v_i^{(t)} = \sum_{t \in X_c} r A_r^{(t)} \gamma_t.
\]

Extracting \(\lambda\) yields
\[
\lambda = \frac{1}{r} \log \left( \frac{\sum_{t \in X_c} r A_r^{(t)} \gamma_t}{\delta \sum_{t \in X_c} r v_i^{(t)}} \right)
= \frac{1}{r} \log \left( \frac{\sum_{t \in X_c} r A_r^{(t)} \gamma_t}{\delta} \right) - \frac{1}{r} \log \left( \sum_{t \in X_c} r v_i^{(t)} \right)
= \frac{1}{r} \log \left( \frac{\sum_{t \in X_c} r A_r^{(t)} \gamma_t}{\delta} \right) - \frac{1}{r} \log \left( 1 - \sum_{t,i : i > r} i v_i^{(t)} \right).
\quad (60)
\]

where we have used (50) in the final line. Substituting (59) and (60) back into (58) yields
\[
W = \left( \frac{\delta}{r} \right) \log \left( \frac{e^{\sum_{t \in X_c} r A_r^{(t)} \gamma_t}}{\delta} \right) - \left( \frac{\delta}{r} \right) \left[ \sum_{t,i : i > r} (i - r)v_i^{(t)} + \log \left( 1 - \sum_{t,i : i > r} i v_i^{(t)} \right) \right]
= \left( \frac{\delta}{r} \right) \log \left( \frac{eC}{\delta \int \rho} \right) - \left( \frac{\delta}{r} \right) \left[ \sum_{t,i : i > r} (i - r)v_i^{(t)} + \log \left( 1 - \sum_{t,i : i > r} i v_i^{(t)} \right) \right]
= \left( \frac{\delta}{r} \right) \log \left( \frac{eC}{\delta \int \rho} \right) + O(\delta^{r/r})
\]

where in the second line we have used (15), and in the final line we have used (56) and the fact that \(\log(1 + \alpha) \sim O(\alpha)\) (also recall the definition (16)).

Substituting this expression for \(W\) into (43) while recalling the \(O(\delta^2)\) term in the expression for \(W\), we have that as \(m \to \infty\)
\[
N_c(\delta m) \approx \exp \left\{ m \left[ \frac{\delta}{r} \log \left( \frac{eC}{\delta \int \rho} \right) + O\left( \delta^{\min\{r,2\}} \right) \right] \right\}. \quad (61)
\]

Note that (61) generalizes [11, eqn. (30)] to the case of a generalized CN set.
C. Number of variable-valid split assignments of split weight \((\tau_n, \sigma_n)\) over \(\gamma_n\) VNs of type \(t \in I_v\)

Consider \(\gamma_n\) VNs of the same type \(t \in I_v\). We now evaluate the number of variable-valid split assignments (over these VNs) of split weight \((\tau_n, \sigma_n)\). Using generating functions, this is given by

\[
N_{\nu,t}^{(\gamma_n)}(\tau_n, \sigma_n) = \text{Coeff} \left[ \left( B(t)(x,y) \right)^{\gamma_n}, x^{\tau_n} y^{\sigma_n} \right]
\]

where \(\text{Coeff} \left[ p(x,y), x^c y^d \right]\) denotes the coefficient of \(x^c y^d\) in the bivariate polynomial \(p(x,y)\).

We make use of the following result, the proof of which appears in \([10, \text{Appendix A}]\):

**Lemma 5.3:** Let

\[
B(x,y) = 1 + \sum_{u=1}^{k} \sum_{v=c}^{d} B_{u,v} x^u y^v
\]

where \(k \geq 1\) and \(1 \leq c \leq d\), be a bivariate polynomial satisfying \(B_{u,v} \geq 0\) for all \(1 \leq u \leq k\), \(c \leq v \leq d\). For fixed positive rational numbers \(\xi\) and \(\theta\), consider the set of positive integers \(\ell\) such that \(\xi \ell \in \mathbb{N}, \theta \ell \in \mathbb{N}\) and \(\text{Coeff} \left[ (B(x,y))^\ell, x^{\xi \ell} y^{\theta \ell} \right] > 0\). Then either this set is empty, or has infinite cardinality; if \(t\) is one such \(\ell\), then so is \(jt\) for every positive integer \(j\). Assuming the latter case, the following limit is well defined and exists:

\[
\lim_{\ell \to \infty} \frac{1}{\ell} \log \text{Coeff} \left[ (B(x,y))^\ell, x^{\xi \ell} y^{\theta \ell} \right] = \max_{\eta} \sum_{(i,j) \in S} \eta_{i,j} \log \left( \frac{B_{i,j}}{\eta_{i,j}} \right)
\]

where \(S = \{(i,j) \in \mathbb{N}^2 : B_{i,j} > 0\}\), \(\eta = (\eta_{i,j})_{(i,j) \in S}\), and the maximization is subject to the constraints \(\sum_{(i,j) \in S} \eta_{i,j} = 1\), \(\sum_{(i,j) \in S} i \eta_{i,j} = \xi\), \(\sum_{(i,j) \in S} j \eta_{i,j} = \theta\) and \(\eta_{i,j} \geq 0\) for all \((i,j) \in S\).

\(^5\)We use the following result on bivariate generating functions \([25]\). Let \(a_{i,j}\) be the number of ways of obtaining an outcome \((i,j) \in \mathbb{Z}^2\) in experiment \(A\), and let \(b_{k,l}\) be the number of ways of obtaining an outcome \((k,l) \in \mathbb{Z}^2\) in experiment \(B\). Also let \(c_{p,q}\) be the number of ways of obtaining an outcome \(\langle (i,j), (k,l) \rangle\) in the combined experiment \((A,B)\) with sums \(i+k=p\) and \(j+l=q\). Then the generating functions \(A(x,y) = \sum_{i,j} a_{i,j} x^i y^j\), \(B(x,y) = \sum_{k,l} b_{k,l} x^k y^l\) and \(C(x,y) = \sum_{p,q} c_{p,q} x^p y^q\) are related by \(C(x,y) = A(x,y)B(x,y)\).
Applying this lemma by substituting $B(x, y) = B^{(t)}(x, y)$, $\ell = \gamma n$, $\xi = \tau / \gamma$ and $\theta = \sigma / \gamma$, we obtain that with $\gamma$ fixed, as $n \to \infty$

\[ N_{c,t}(\gamma n, \sigma n) = \text{Coeff} \left[ (B^{(t)}(x, y))^\gamma n, x^\tau n y^\sigma n \right] \]  \hspace{1cm} (63)

\[ \approx \exp \left\{ n \gamma \max_{\eta^{(t)}} \sum_{(i,j) \in S_t} \eta_{i,j}^{(t)} \log \left( \frac{B_{i,j}^{(t)}}{\eta_{i,j}^{(t)}} \right) \right\} \]  \hspace{1cm} (64)

\[ \triangleq \exp \left\{ n X_t^{(\gamma)}(\tau, \sigma) \right\} \]  \hspace{1cm} (65)

where the maximization over $\eta^{(t)} = (\eta_{i,j}^{(t)})_{(i,j) \in S_t}$ is subject to the constraints $\sum_{(i,j) \in S_t} \eta_{i,j}^{(t)} = 1$, $\sum_{(i,j) \in S^-_t} \eta_{i,j}^{(t)} = \tau / \gamma$, $\sum_{(i,j) \in S^-_t} j \eta_{i,j}^{(t)} = \sigma / \gamma$ and $\eta_{i,j}^{(t)} \geq 0$ for all $(i, j) \in S_t$ (recall that the sets $S_t$ and $S^-_t$ are given by (11) and (12)).

D. Growth rate of the weight distribution of the irregular D-GLDPC code ensemble sequence

Recall that the number of check-valid assignments of weight $\delta m$ is $N_c(\delta m)$; also, the total number of assignments of weight $\delta m$ is $E_{\delta m}$. Therefore, the probability that a randomly chosen assignment of weight $\delta m$ is check-valid is given by

\[ P_{\text{valid}}(\delta m) = \frac{N_c(\delta m)}{E_{\delta m}} . \]

Here we adopt the notation $\delta m = \beta n$; also we have $E = m / \int \rho = n / \int \lambda$. The binomial coefficient may be asymptotically approximated using the fact, based on Stirling’s approximation, that as $n \to \infty$

\[ \left( \frac{\tau n}{\sigma n} \right)^n \approx \exp \left\{ n \left[ \sigma \log \left( \frac{e \tau}{\sigma} \right) + O(\sigma^2) \right] \right\} \]

(valid for $0 < \sigma < \tau < 1$) which yields, in this case,

\[ \left( \frac{n / \int \lambda}{\beta n} \right)^n \approx \exp \left\{ n \left[ \beta \log \left( \frac{e \beta \int \lambda}{\beta} \right) + O(\beta^2) \right] \right\} \]

as $n \to \infty$. Applying this together with the asymptotic expression (61), we find that as $n \to \infty$ (exploiting the fact that $\delta \int \rho = \beta \int \lambda$)

\[ P_{\text{valid}}(\beta n) \approx \exp\{nY(\beta)\} \]  \hspace{1cm} (66)

where

\[ Y(\beta) = \frac{\beta}{r} \log \left( \frac{e C}{\beta \int \lambda} \right) - \beta \log \left( \frac{e}{\beta \int \lambda} \right) + O(\beta^{\min\{r/\lambda, 2\}}) . \]  \hspace{1cm} (67)
Next, we note that the expected number of D-GLDPC codewords of weight $\alpha n$ in the ensemble $\mathcal{M}_n$ is equal to the sum over $\beta$ of the expected number of split assignments of split weight $(\alpha n, \beta n)$ which are both check-valid and variable-valid, denoted $N_{\alpha n, \beta n}^{v,c}$:

$$E_{\mathcal{M}_n} [N_{\alpha n}] = \sum_{\beta} E_{\mathcal{M}_n} [N_{\alpha n, \beta n}^{v,c}].$$

This may then be expressed as

$$E_{\mathcal{M}_n} [N_{\alpha n}] = \sum_{\beta} P_{\text{valid}}(\beta n) \sum_{\sum \alpha_t = \alpha \atop \sum \beta_t = \beta} \prod_{t \in I_v} N_{v,t}^{(\delta_t n)}(\alpha_t n, \beta_t n),$$

where the fraction $\delta_t$ of VNs of type $t \in I_v$ is given by (5) and the second sum is over all partitions of $\alpha$ and $\beta$ into $n_v$ elements, i.e., we have $\alpha_t, \beta_t \geq 0$ for all $t \in I_v$, and $\sum_{t \in I_v} \alpha_t = \alpha$, $\sum_{t \in I_v} \beta_t = \beta$.

Now, using (63)-(65), as $n \to \infty$ we have for each $t \in I_v$

$$N_{v,t}^{(\delta_t n)}(\alpha_t n, \beta_t n) \approx \exp \left\{ n X_t^{(\delta_t)}(\alpha_t, \beta_t) \right\},$$

where, for each $t \in I_v$,

$$X_t^{(\delta_t)}(\alpha_t, \beta_t) = \delta_t \max_{\eta^{(t)}} \sum_{(i,j) \in S_t} \eta^{(t)}_{i,j} \log \left( \frac{B_{i,j}^{(t)}}{\eta^{(t)}_{i,j}} \right)$$

and the maximization over $\eta^{(t)} = (\eta^{(t)}_{i,j})_{(i,j) \in S_t}$ is subject to the constraints

$$\sum_{(i,j) \in S_t} \eta^{(t)}_{i,j} = 1 \quad (69)$$

$$\sum_{(i,j) \in S_t^-} i \eta^{(t)}_{i,j} = \alpha_t / \delta_t \quad (70)$$

$$\sum_{(i,j) \in S_t^-} j \eta^{(t)}_{i,j} = \beta_t / \delta_t \quad (71)$$

and

$$\eta^{(t)}_{i,j} \geq 0 \quad \forall (i,j) \in S_t. \quad (72)$$

Therefore, recalling (66), we have that as $n \to \infty$,

$$E_{\mathcal{M}_n} [N_{\alpha n}] \approx \sum_{\beta} \sum_{\sum \alpha_t = \alpha \atop \sum \beta_t = \beta} \exp \left\{ n \left[ \sum_{t \in I_v} X_t^{(\delta_t)}(\alpha_t, \beta_t) + Y(\beta) \right] \right\}. \quad (73)$$
Next, for each $t \in I_v$ we define
\[
F_t(\eta^{(t)}) = \eta^{(t)}_{0,0} \log \left( \frac{1}{\eta^{(t)}_{0,0}} \right) - \sum_{(i,j) \in S^-_t} \eta^{(t)}_{i,j}.
\]

Note that the expression (73) is dominated as $n \to \infty$ by the term which maximizes the argument of the exponential. Thus using (67) and (68) we may write
\[
G(\alpha) = \max_{\beta} \max_{\eta^{(t)}} \left\{ \sum_{t \in I_v} \delta_t \max_{\eta^{(t)}} \left[ \sum_{(i,j) \in S^-_t} \eta^{(t)}_{i,j} \log \left( \frac{eB^{(t)}_{i,j}}{\eta^{(t)}_{i,j}} \right) + F_t(\eta^{(t)}) \right] \right. \\
+ \frac{\beta}{r} \log \left( \frac{eC}{\beta} \right) - \beta \log \left( \frac{e}{\beta} \right) + O \left( \beta^{\min(\nu/r,2)} \right) \}
\]
where the maximization over $\eta^{(t)} = (\eta^{(t)}_{i,j})_{(i,j) \in S^-_t}$ (for each $t \in I_v$) is subject to constraints (70) and (71) together with $\eta^{(t)}_{i,j} \geq 0$ for all $(i, j) \in S^-_t$.

We next have the following lemma.

**Lemma 5.4:** The expression $\sum_{t \in I_v} \delta_t F_t(\eta^{(t)})$ is $O(\alpha^2)$ for any $\eta^{(t)}$ satisfying the optimization constraints (69)-(72).

The proof of this lemma follows the same lines as the proof of Lemma 5.2 and is therefore omitted. It follows from Lemma 5.4 that the expression $\sum_{t \in I_v} \delta_t F_t(\eta^{(t)})$ is $O(\alpha^2)$ for the maximizing $\eta^{(t)}$. Also, since $\beta/\alpha$ is bounded between two positive constants, any expression which is $O(\beta^\kappa)$ must necessarily also be $O(\alpha^\kappa)$ (where $\kappa > 0$). Therefore
\[
G(\alpha) = \max_{\beta} \max_{\eta^{(t)}} \left[ \sum_{t \in I_v} \delta_t \max_{\eta^{(t)}} \sum_{(i,j) \in S^-_t} \eta^{(t)}_{i,j} \log \left( \frac{eB^{(t)}_{i,j}}{\eta^{(t)}_{i,j}} \right) \right. \\
+ \frac{\beta}{r} \log \left( \frac{eC}{\beta} \right) - \beta \log \left( \frac{e}{\beta} \right) + O \left( \alpha^{\min(\nu/r,2)} \right)
\]
where the optimization is (as before) subject to the constraints (70) and (71) together with $\eta^{(t)}_{i,j} \geq 0$ for all $(i, j) \in S^-_t$. In what follows, for convenience of presentation we shall temporarily omit the $O \left( \alpha^{\min(\nu/r,2)} \right)$ term in the expression for the growth rate.

Next we make the substitution $\gamma^{(t)}_{i,j} = \delta_t \eta^{(t)}_{i,j}$ for all $t \in I_v$, $(i, j) \in S^-_t$. This yields
\[
G(\alpha) = \max_{\beta} \max_{\gamma^{(t)}} \left[ \sum_{t \in I_v} \max_{\gamma^{(t)}} \sum_{(i,j) \in S^-_t} \gamma^{(t)}_{i,j} \log \left( \frac{eB^{(t)}_{i,j}}{\gamma^{(t)}_{i,j}} \right) \right. \\
+ \frac{\beta}{r} \log \left( \frac{eC}{\beta} \right) - \beta \log \left( \frac{e}{\beta} \right)
\]
where the maximization over \( \gamma^{(t)} = (\gamma^{(t)}_{i,j})_{(i,j) \in S^-_t} \) (for each \( t \in I_v \)) is subject to the constraints \( \sum_{(i,j) \in S^-_t} i \gamma^{(t)}_{i,j} = \alpha_t \), \( \sum_{(i,j) \in S^-_t} j \gamma^{(t)}_{i,j} = \beta_t \), and \( \gamma^{(t)}_{i,j} \geq 0 \) for all \( (i, j) \in S^-_t \). We observe that this maximization may be recast as

\[
G(\alpha) = \max_{\gamma} \left[ \sum_{t \in I_v} \sum_{(i,j) \in S^-_t} \gamma^{(t)}_{i,j} \log \left( \frac{eB^{(t)}_{i,j} \delta_t}{\alpha \nu^{(t)}_{i,j}} \right) + \frac{\beta(\gamma)}{r} \log \left( \frac{eC}{\beta(\gamma) \int \lambda} \right) - \beta(\gamma) \log \left( \frac{e}{\beta(\gamma) \int \lambda} \right) \right]
\]

where the maximization, which is now over \( \gamma = (\gamma^{(t)}_{i,j})_{t \in I_v, (i,j) \in S^-_t} \), is subject to the constraints

\[
\sum_{t \in I_v} \sum_{(i,j) \in S^-_t} i \gamma^{(t)}_{i,j} = \alpha
\]

and \( \gamma^{(t)}_{i,j} \geq 0 \) for all \( t \in I_v, (i, j) \in S^-_t \), and where

\[
\beta(\nu) = \sum_{t \in I_v} \sum_{(i,j) \in S^-_t} j \nu^{(t)}_{i,j}.
\]

Making the substitution \( \nu^{(t)}_{i,j} = \gamma^{(t)}_{i,j} / \alpha \) for all \( t \in I_v, (i, j) \in S^-_t \), we obtain

\[
G(\alpha) = \alpha \max_{\nu} \left[ \sum_{t \in I_v} \sum_{(i,j) \in S^-_t} \nu^{(t)}_{i,j} \log \left( \frac{eB^{(t)}_{i,j} \delta_t}{\alpha \nu^{(t)}_{i,j}} \right) + \frac{z(\nu)}{r} \log \left( \frac{eC}{\alpha z(\nu) \int \lambda} \right) - \frac{z(\nu)}{\alpha} \log \left( \frac{e}{\alpha z(\nu) \int \lambda} \right) \right]
\]

where the maximization over \( \nu = (\nu^{(t)}_{i,j})_{t \in I_v, (i,j) \in S^-_t} \) is subject to the constraint

\[
\sum_{t \in I_v} \sum_{(i,j) \in S^-_t} i \nu^{(t)}_{i,j} = 1,
\]

as well as \( \nu^{(t)}_{i,j} \geq 0 \) for all \( t \in I_v, (i, j) \in S^-_t \), and where

\[
z(\nu) \triangleq \sum_{t \in I_v} \sum_{(i,j) \in S^-_t} j \nu^{(t)}_{i,j}.
\]

By solving (75) directly using Lagrange multipliers, one shows that

\[
\log \left( \frac{B^{(t)}_{i,j} \delta_t}{\alpha \nu^{(t)}_{i,j}} \right) + \frac{j}{r} \log \left( \frac{C}{\alpha z(\nu) \int \lambda} \right) - \frac{j}{\alpha} \log \left( \frac{1}{\alpha z(\nu) \int \lambda} \right) = \lambda i
\]

By solving (75) directly using Lagrange multipliers, one shows that

\[
\log \left( \frac{B^{(t)}_{i,j} \delta_t}{\alpha \nu^{(t)}_{i,j}} \right) + \frac{j}{r} \log \left( \frac{C}{\alpha z(\nu) \int \lambda} \right) - \frac{j}{\alpha} \log \left( \frac{1}{\alpha z(\nu) \int \lambda} \right) = \lambda i
\]
holds for all $t \in I_v, (i, j) \in S_t^-$; here $\lambda$ denotes the Lagrange multiplier. Substituting (78) back into (75) yields

$$G(\alpha) = \alpha \left( \sum_{t \in I_v} \sum_{(i, j) \in S_t^-} \nu_{i,j}^{(t)} \left[ 1 + \lambda i - \frac{j}{r} \log \left( \frac{C}{\alpha z(\nu) \int \lambda} \right) + j \log \left( \frac{1}{\alpha z(\nu) \int \lambda} \right) \right] \right)$$

$$+ \frac{z(\nu)}{r} \log \left( \frac{e C}{\alpha z(\nu) \int \lambda} \right) - z(\nu) \log \left( \frac{e}{\alpha z(\nu) \int \lambda} \right)$$

$$= \alpha \left[ \sum_{t \in I_v} \sum_{(i, j) \in S_t^-} \nu_{i,j}^{(t)} + \lambda + \frac{z(\nu)}{r} - z(\nu) \right]$$

$$= \alpha \left[ \lambda + \sum_{t \in I_v} \sum_{(i, j) \in S_t^-} \nu_{i,j}^{(t)} \left( 1 + \frac{j}{r} - j \right) \right]$$

$$= \alpha \left[ \lambda - \frac{1}{\psi} \sum_{t \in I_v} \sum_{(i, j) \in S_t^-} \nu_{i,j}^{(t)} (j - \psi) \right] \right),$$

where in the second line we have used (76) and (77). Note that (78) may be rearranged as

$$\alpha \nu_{i,j}^{(t)} = B_{i,j}^{(t)} \delta_t C^{j/r} \left( \alpha z(\nu) \int \lambda \right)^{j/\psi} \omega^{j}, \quad (80)$$

where $\omega = e^{-\lambda}$ is a positive real number. Substituting this solution into (77) (i.e. into the definition of $z(\nu)$) and using (5) yields

$$\sum_{t \in I_v} \lambda t \sum_{(i, j) \in S_t^-} \nu_{i,j}^{(t)} C^{j/r} \left( \alpha z(\nu) \int \lambda \right)^{j/\psi} \omega^{j} = 1, \quad (81)$$

and similarly the constraint (76) may be written as

$$\sum_{t \in I_v} \lambda t \sum_{(i, j) \in S_t^-} i B_{i,j}^{(t)} C^{j/r} \left( \alpha z(\nu) \int \lambda \right)^{i/\psi} \omega^{i} = \frac{1}{z(\nu)}. \quad (82)$$

We next proceed by proving an upper bound on all terms $\nu_{i,j}^{(t)}$ such that $(t, i, j)$ does not lie in the dominant set discussed in Section [IV-A] i.e., on all terms $\nu_{i,j}^{(t)}$ where $t \in I_v, (i, j) \in S_t^-$ and $T_{t,i,j} > T$. To this end, fix $s \in I_v, (k, l) \in S_s^-$ with $T_{k,l} = T$, and consider arbitrary $t \in I_v, (i, j) \in S_t^-$ (for which we have $T_{t,i,j} \geq T$). Then applying (78) in the two pertinent cases yields

$$\lambda = \frac{1}{t} \log \left[ \frac{B_{i,j}^{(t)} \delta_t C^{j/r}}{\alpha \nu_{i,j}^{(t)}} \cdot \left( \alpha z(\nu) \int \lambda \right)^{j/\psi} \right]$$
respectively. Thus it follows that for any
and

\[ z \]

for every

\[ \nu \]

is bounded above and below as \( \alpha \to 0 \); this may be easily shown since (76) and (77) imply

\[ 0 < \left( \min_{(i,j) \in S^-} i \right) \sum_{t \in I_v (i,j) \in S^-} \nu_{i,j}^{(t)} \leq 1 \leq \left( \max_{(i,j) \in S^-} i \right) \sum_{t \in I_v (i,j) \in S^-} \nu_{i,j}^{(t)} \]

and

\[ 0 < \left( \min_{(i,j) \in S^-} j \right) \sum_{t \in I_v (i,j) \in S^-} \nu_{i,j}^{(t)} \leq z(\nu) \leq \left( \max_{(i,j) \in S^-} j \right) \sum_{t \in I_v (i,j) \in S^-} \nu_{i,j}^{(t)} \]

respectively. Thus it follows that for any \( t \in I_v, (i,j) \in S^- \), the function \( F_{i,j}(\alpha) \) given by (83) is bounded above and below as \( \alpha \to 0 \). Therefore

\[ \frac{(\nu_{i,j})^{1/k}}{(\nu_{k,l})^{1/k}} = \frac{\Gamma_{i,j}(\alpha)}{\Gamma_{k,l}(\alpha)} \frac{T_{i,j} - T}{\psi} \]

(84)

where \( \Gamma_{i,j}(\alpha) = \exp(F_{i,j}(\alpha)) > 0 \) for every \( t \in I_v, (i,j) \in S^- \). We next write (84) as

\[ \nu_{i,j}^{(t)} = (\nu_{k,l})^{i/k} \Delta_{i,j,k,l}^{(t,s)}(\alpha) \alpha^{\frac{T_{i,j} - T}{\psi}} \]

(85)

where for conciseness we have defined

\[ \Delta_{i,j,k,l}^{(t,s)}(\alpha) = \left( \frac{\Gamma_{i,j}(\alpha)}{\Gamma_{k,l}(\alpha)} \right)^{i} > 0 \]

Substituting into (76) we obtain

\[ \sum_{t \in I_v (i,j) \in S^-} \sum_{i,j} \Delta_{i,j,k,l}^{(t,s)}(\alpha) \alpha^{\frac{T_{i,j} - T}{\psi}} = 1 , \]

which in particular implies (since all terms involved are nonnegative, and \( T_{i,j} = T \) for all \( t \in Y_v \), \((i,j) \in P_t\))

\[ \sum_{t \in Y_v (i,j) \in P_t} \sum_{i,j} \Delta_{i,j,k,l}^{(t,s)}(\alpha) \leq 1 . \]
If we now define \( \hat{i} = \max \{ i : (i, j) \in P_t \text{ for some } t \in Y^v \} \), the previous inequality leads to

\[
\nu_{k,l}^{(s)} \leq \left( \frac{1}{\sum_{t \in Y^v} \sum_{(i,j) \in P_t} \hat{i} \Delta_{i,j,k,l}^{(t,s)}(\alpha)} \right)^{k/i}.
\]

Since, for every triple \( (t, i, j) \), \( F_{i,j}^{(t)}(\alpha) \) is bounded above and below, so are \( \Gamma_{i,j}^{(t)}(\alpha) \) and \( \Delta_{i,j,k,l}^{(t,s)}(\alpha) \). Therefore, the previous inequality implies

\[
\nu_{k,l}^{(s)} \sim O(1),
\]

which holds for any \( s \in Y^v, (k, l) \in P_s \), i.e., for any triple \( (s, k, l) \) lying in the dominant set. Recalling (85), for general \( \nu_{i,j}^{(t)} \) we have

\[
\nu_{i,j}^{(t)} \sim O(\alpha^{-\frac{T_{i,j} - T}{\psi}}) \quad \text{for all } t \in I^v, (i, j) \in S_t^-.
\]

Next observe that (87) may be used to upper bound \( \omega = e^{-\lambda} \). In fact, it may be seen that applying (80) for any triple \( (t, i, j) \) and taking into account (87) leads to

\[
\omega = \frac{1}{B_{i,j}^{(t)} \delta t \lambda^{j/\psi}} \cdot \frac{\alpha \nu_{i,j}^{(t)}}{(\alpha z(\nu) \int \lambda^{j/\psi})} \sim O(\alpha^{-\frac{T}{\psi}})
\]

i.e.,

\[
\omega \sim O(\alpha^{-\frac{T}{\psi}}).
\]

Next, (87) implies that

\[
\frac{1}{\psi^2} \sum_{t \in I^v} \sum_{(i,j) \in S_t^-} (j - \psi) \nu_{i,j}^{(t)} = \frac{1}{\psi} \left[ \sum_{t \in I^v} \sum_{(i,j) \in S_t^-} iT_{i,j}^{(t)} \nu_{i,j}^{(t)} + \sum_{t \in I^v} \sum_{(i,j) \in S_t^-} i(T_{i,j} - T) \nu_{i,j}^{(t)} \right] = \frac{T}{\psi} \frac{1}{\psi} \sum_{t \in I^v} \sum_{(i,j) : T_{i,j} > T} (T_{i,j} - T) \nu_{i,j}^{(t)} = \frac{T}{\psi} + O \left( \alpha^{\frac{1}{\chi}} \right).
\]

where in the second line we have used (76), and in the final line we have used (87) and also recalled the definition (20) of the parameter \( \chi \).

Next note that, recalling (22) and (23), equations (81) and (82) may be written as

\[
Q_1(y) + f_1(\alpha) = 1
\]

and

\[
Q_2(y) + f_2(\alpha) = \frac{1}{z(\nu)}
\]
respectively, where we define

\[ y = (e^{\alpha z(\nu)})^{T/\psi} \omega, \quad (92) \]

\[ f_1(\alpha) = \sum_{t \in I_v} \frac{\lambda_t}{q_t} \sum_{(i,j): T_{i,j} > T} j B_{i,j}^{(t)} C_{i,j}^{\frac{1}{r}} \left[ \left( \alpha z(\nu) \int \lambda \right)^{T_{i,j}/\psi} \omega \right]^i \]

and

\[ f_2(\alpha) = \sum_{t \in I_v} \frac{\lambda_t}{q_t} \sum_{(i,j): T_{i,j} > T} i B_{i,j}^{(t)} C_{i,j}^{\frac{1}{r}} \left[ \left( \alpha z(\nu) \int \lambda \right)^{T_{i,j}/\psi} \omega \right]^i. \]

Note that since \( z(\nu) \) is bounded below as \( \alpha \to 0 \), from (88) we have \( f_1(\alpha) \sim O(\alpha^{\frac{1}{r}}) \) and \( f_2(\alpha) \sim O(\alpha^{\frac{1}{r}}) \). Recalling that \( \omega = e^{-\lambda} \), from (92) we obtain the following expression for the Lagrange multiplier \( \lambda \):

\[ \lambda = \frac{T}{\psi} + \frac{T}{\psi} \log \alpha + \frac{T}{\psi} \log z(\nu) - \log y. \quad (93) \]

From (90) and (91) this latter expression may be written as

\[ \lambda = \frac{T}{\psi} + \frac{T}{\psi} \log \alpha - \frac{T}{\psi} \log \left[ Q_2(Q_1^{-1}(1 - f_1(\alpha))) + f_2(\alpha) \right] - \log \left[ Q_1^{-1}(1 - f_1(\alpha)) \right]. \]

Using the Taylor series of \( Q_1^{-1}(1 + x) \) around \( x = 0 \), we have

\[ Q_1^{-1}(1 - f_1(\alpha)) = Q_1^{-1}(1) + g_1(\alpha), \quad (94) \]

where

\[ g_1(\alpha) = \frac{dQ_1^{-1}}{dx}(1) \cdot f_1(\alpha) + O(f_1^2(\alpha)). \]

Note that since \( f_1(\alpha) \sim O(\alpha^{\frac{1}{r}}) \), we also have \( g_1(\alpha) \sim O(\alpha^{\frac{1}{r}}) \). Substituting the obtained expression (94) for \( Q_1^{-1}(1 - f_1(\alpha)) \) into the previous expression (93) for \( \lambda \) we obtain

\[ \lambda = \frac{T}{\psi} + \frac{T}{\psi} \log \alpha - \frac{T}{\psi} \log \left[ Q_2(Q_1^{-1}(1) + g_1(\alpha)) + f_2(\alpha) \right] - \log \left[ Q_1^{-1}(1) + g_1(\alpha) \right]. \]

We may now develop \( Q_2(Q_1^{-1}(1) + g_1(\alpha)) \) using the Taylor series for \( Q_2(Q_1^{-1}(1) + x) \) around \( x = 0 \) and \( \log \left[ Q_1^{-1}(1) + g_1(\alpha) \right] \) using the Taylor series for \( \log(Q_1^{-1}(1) + x) \) around \( x = 0 \). We obtain

\[ Q_2(Q_1^{-1}(1) + g_1(\alpha)) = Q_2(Q_1^{-1}(1)) + g_2(\alpha) \]

where

\[ g_2(\alpha) = \frac{dQ_2}{dx}(Q_1^{-1}(1)) \cdot g_1(\alpha) + O(g_1^2(\alpha)). \]

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and
\[
\log \left[ Q_1^{-1}(1) + g_1(\alpha) \right] = \log Q_1^{-1}(1) + h_1(\alpha)
\]

where
\[
h_1(\alpha) = \frac{1}{Q_1^{-1}(1)} g_1(\alpha) + O(g_1^2(\alpha)).
\]

Again, note that since \( g_1(\alpha) \sim O(\alpha^{\frac{1}{2}}) \), we have \( g_2(\alpha) \sim O(\alpha^{\frac{1}{2}}) \) and \( h_1(\alpha) \sim O(\alpha^{\frac{1}{2}}) \). Therefore, we have
\[
\lambda = \frac{T}{\psi} \log \alpha - \frac{T}{\psi} \log \left[ Q_2(Q_1^{-1}(1)) + g_2(\alpha) + f_2(\alpha) \right] + \log \frac{1}{Q_1^{-1}(1)} - h_1(\alpha).
\]

Finally, we develop \( \log \left[ Q_2(Q_1^{-1}(1)) + g_2(\alpha) + f_2(\alpha) \right] \) using the Taylor series for \( \log \left[ Q_2(Q_1^{-1}(1)) + x \right] \) around \( x = 0 \). We obtain
\[
\log \left[ Q_2(Q_1^{-1}(1)) + g_2(\alpha) + f_2(\alpha) \right] = \log Q_2(Q_1^{-1}(1)) + h_2(\alpha)
\]

where
\[
h_2(\alpha) = \frac{1}{Q_2(Q_1^{-1}(1))} (g_2(\alpha) + f_2(\alpha)) + O((g_2(\alpha) + f_2(\alpha))^2).
\]

Using this expression we obtain
\[
\lambda = \frac{T}{\psi} \log \alpha + \frac{T}{\psi} \log \frac{1}{Q_2(Q_1^{-1}(1))} + \log \frac{1}{Q_1^{-1}(1)} - \frac{T}{\psi} h_2(\alpha) - h_1(\alpha).
\]

Since \( g_2(\alpha) \sim O(\alpha^{\frac{1}{2}}) \) and \( f_2(\alpha) \sim O(\alpha^{\frac{1}{2}}) \), we have \( h_2(\alpha) \sim O(\alpha^{\frac{1}{2}}) \); hence, we obtain
\[
\lambda = \frac{T}{\psi} \log \alpha + \frac{T}{\psi} \log \frac{1}{Q_2(Q_1^{-1}(1))} + \log \frac{1}{Q_1^{-1}(1)} + O(\alpha^{\frac{1}{2}}).
\]

Finally, substituting (89) and (95) into (79) and recalling the \( O(\alpha^{\min\{\frac{1}{r}, \frac{2}{r}\}}) \) term completes the proof of the theorem.

VI. Conclusion

A compact expression for the asymptotic growth rate of the weight distribution of irregular D-GLDPC codes for small linear-weight codewords has been derived. Ensembles with check or variable node minimum distance greater than 2 are shown to have good growth rate behavior, while for other ensembles an important parameter is identified which discriminates between good and bad growth rate behavior of the ensemble. This generalizes known results for LDPC codes and GLDPC codes, and also generalizes the corresponding connection with the stability condition over the BEC.
APPENDIX A

PROOF OF LEMMA 5.2

Consider any $\beta^{(t)}$ which satisfies the optimization constraints (45)–(48). From constraint (45), $\delta$ small implies that $\epsilon_t$ is small for every $t \in I_c$. From constraint (47) we conclude that $\beta_i^{(t)}$ is small for every $t \in I_c$, $i \in U_t^-$, and so $\beta_0^{(t)}$ is close to 1 for all $t \in I_c$. Formally, for any $t \in I_c$ the term in the sum over $i \in U_t$ in (44) corresponding to $i = 0$ may be written as (here we use (46), and the Taylor series of $\log (1 - x)$ around $x = 0$

$$\beta_0^{(t)} \log \left( \frac{1}{\beta_0^{(t)}} \right) = \left( \sum_{i \in U_t^-} \beta_i^{(t)} - 1 \right) \log \left( 1 - \sum_{i \in U_t^-} \beta_i^{(t)} \right)$$

$$= \left( \sum_{i \in U_t^-} \beta_i^{(t)} - 1 \right) \left( - \sum_{i \in U_t^-} \beta_i^{(t)} + O \left( \left( \sum_{i \in U_t^-} \beta_i^{(t)} \right)^2 \right) \right)$$

$$= \sum_{i \in U_t^-} \beta_i^{(t)} + O \left( \left( \sum_{i \in U_t^-} \beta_i^{(t)} \right)^2 \right)$$

Therefore we have

$$F_t(\beta^{(t)}) = O \left( \left( \sum_{i \in U_t^-} \beta_i^{(t)} \right)^2 \right)$$

i.e.

$$\left| F_t(\beta^{(t)}) \right| \leq k_t \left( \sum_{i \in U_t^-} \beta_i^{(t)} \right)^2 \tag{96}$$

for some $k_t > 0$ independent of $\{\beta_i^{(t)}\}_{i \in U_t^-}$. It follows that

$$\left| \sum_{t \in I_c} \gamma_t F_t(\beta^{(t)}) \right| \leq \sum_{t \in I_c} \gamma_t \left| F_t(\beta^{(t)}) \right| \leq \sum_{t \in I_c} \gamma_t \left( \sum_{i \in U_t^-} \beta_i^{(t)} \right)^2 \tag{97}$$

where $\gamma_t' = k_t \gamma_t$ for each $t \in I_c$. Also, by (47) we have $\sum_{i \in U_t^-} \beta_i^{(t)} \leq \epsilon_t / \gamma_t$ and therefore

$$\sum_{t \in I_c} \gamma_t \left( \sum_{i \in U_t^-} \beta_i^{(t)} \right)^2 \leq \sum_{t \in I_c} \left( \frac{\gamma_t'}{\gamma_t^2} \right) \epsilon_t^2 \tag{98}$$

Denote $\gamma = \max_{t \in I_c} \{ \gamma_t' / \gamma_t^2 \}$; then, combining (97) and (98),

$$\left| \sum_{t \in I_c} \gamma_t F_t(\beta^{(t)}) \right| \leq \gamma \sum_{t \in I_c} \epsilon_t^2 < \gamma \left( \sum_{t \in I_c} \epsilon_t \right)^2 = \gamma \delta^2$$

and thus the expression $\sum_{t \in I_c} \gamma_t F_t(\beta^{(t)})$ is $O(\delta^2)$, as desired.
This appendix illustrates how the approach developed to analyze the growth rate of the weight distribution of D-GLDPC codes can also be used to analyze the growth rate of the stopping set size distribution. The concept of stopping set was introduced in [26] within the context of iterative decoding of LDPC codes over the BEC. A stopping set of an LDPC code is defined as any subset of the VNs such that if a CN is connected to it, it is connected to it at least twice. Over the BEC, stopping sets under iterative decoding play the same role as codewords under maximum likelihood decoding.

Stopping sets can also be defined within the context of D-GLDPC codes over the BEC. In contrast to the case of LDPC codes however, here the definition of stopping set is not unique as it depends on the decoding algorithm used at the VNs and CNs to locally recover from erasures. In the following, we assume maximum a posteriori (MAP) erasure decoding is used at both the VNs and the CNs.

Consider an \((n, k)\) linear block code and a generator matrix \(G\) for this code. Moreover, consider a \(k\)-bit information word \(u\) containing erasures. Encoding of this information word produces an \(n\)-bit word \(x\) containing erasures, where the non-erasure encoded bits are those depending only on the non-erasure information bits (through the relationship \(x = uG\)). We say that the erasure pattern on the encoded bits is \textit{induced} by the erasure pattern on the information bits.

Consider an \((s, h)\) CN of a D-GLDPC code over the BEC, and let \(G\) denote a generator matrix for this CN. A local stopping set for this CN is a subset of the local code bits such that, if all of these bits are erased, MAP decoding cannot recover any of these bits. This occurs if and only if each column of \(G\) corresponding to erased bits is linearly independent of the columns of \(G\) corresponding to the non-erased bits. The size of the local stopping set for the CN is equal to the number of erased local code bits.

Next consider a \((q, k)\) VN of a D-GLDPC code over the BEC, and let \(G\) denote the generator matrix for this VN, i.e. \(G\) expresses the relationship between the local information word and the local codeword whose bits are associated with the Tanner graph edges. A local stopping set

\footnote{Note that the definition of local stopping set is independent of the particular generator matrix chosen for the CN.}
for this VN is a subset of the local information bits, together with a subset of the local code
bits, such that if all of these bits are erased, MAP decoding at the VN cannot recover any of
these bits. Since MAP decoding over the BEC consists of running Gaussian elimination on the
\((k \times (q + k))\) matrix \(G' = [G \mid I_k]\), where \(I_k\) is the \((k \times k)\) identity matrix, this occurs if and
only if each column of \(G'\) corresponding to an erased bit is linearly independent of the columns
of \(G'\) corresponding to the non-erased bits. The split size of a VN stopping set is equal to \((u, v)\)
where there are \(u\) erasures among the local information bits, and \(v\) erasures among the local
code bits.

The concepts of assignment and split assignment remain valid also within the present context
of stopping sets. However we redefine the concepts of check-valid assignment, check-valid split
assignment and variable-valid split assignment as follows.

**Definition B.1:** An assignment is said to be check-valid if the following condition holds:
supposing that each edge of the assignment carries an erasure and each of the other edges carries
a non-erasure, each CN recognizes a local stopping set.

**Definition B.2:** A split assignment is said to be check-valid if its assignment is check-valid.
A split assignment is said to be variable-valid if the following holds. Supposing that each edge of
its assignment carries an erasure and each of the other edges carries a non-erasure, and supposing
that each D-GLDPC code bit in the codeword assignment is set to an erasure and each of the
other code bits to a non-erasure, each VN recognizes a local stopping set, where the erasure
pattern on its local code bits is that induced by the erasure pattern on its local information bits.

A stopping set of a D-GLDPC code may be defined as a codeword assignment such that the
split assignment formed by the codeword assignment and the corresponding induced assignment
is both variable-valid and check-valid. The size of such a stopping set is equal to the number
of elements in the codeword assignment. The growth rate of the stopping set size distribution is
defined as in (8), where in this context \(N_{\alpha n}\) denotes the number of stopping sets of size \(\alpha n\).

We define the stopping set size enumerating polynomial for CN type \(t \in I_c\) by

\[
\phi^{(t)}(x) = 1 + \sum_{u=r_1}^{s_t} \varphi_u^{(t)} x^u
\]

where \(\varphi_u^{(t)}\) denotes the number of local stopping sets of size \(u\) for CNs of type \(t\). Letting \(G_t\)
denote any generator matrix for CN type \(t\), note that \(\varphi_u^{(t)}\) is equal to the number of ways of
choosing $u$ columns of $G_t$ such that each of the selected columns is linearly independent of the $s_t - u$ non-selected columns.

We also define the bivariate stopping set split size enumerating polynomial for VN type $t \in I_v$ by

$$\Theta^{(t)}(x, y) = 1 + \sum_{u=1}^{k_t} \sum_{v=p_t}^{q_t} \vartheta^{(t)}_{u,v} x^u y^v$$

where $\vartheta^{(t)}_{u,v}$ denotes the number of local stopping sets of split size $(u, v)$ for VNs of type $t$. Letting $G_t$ denote the generator matrix for VN type $t$, note that $\vartheta^{(t)}_{u,v}$ is the number of ways of choosing $u$ columns of $I_{k_t}$ and $v$ columns of $G_t$ such that each of the selected columns is linearly independent of the $k_t + q_t - v - u$ non-selected columns of $G'_t = [G_t \mid I_{k_t}]$.

With these definitions in place, the analog of Theorem 4.1 may be developed in an identical manner for the growth rate of the stopping set size distribution. The proof is identical to that developed in Section [x] for the growth rate of the weight distribution, with the stopping set size enumerators in place of the weight enumerators, the new definitions of check- and variable-validity, and “stopping set size” in place of “codeword weight”. In particular, we have the following result for the case $r = p = 2$, which is the most important case in practice.

**Theorem B.1**: Consider a D-GLPDC code ensemble $\mathcal{M}_n$ satisfying $r = p = 2$. Assume the code is transmitted over the BEC, and it is decoded via iterative decoding with MAP erasure decoding at the VNs and CNs. The growth rate of the stopping set size distribution is given by

$$G(\alpha) = \alpha \log \left( \frac{1}{P - 1(1/C)} \right) + O(\alpha^{3/2})$$

where the polynomial $P(x)$ and the parameter $C$ are given by (24) and (25) respectively.

The proof of this result is completed by observing that, if $r = p = 2$, we have $\varphi_{2}^{(t)} = A_{2}^{(t)}$ for each $t \in X_c$ and $\varphi_{u,2}^{(t)} = B_{u,2}^{(t)}$ for each $t \in X_v$, $u = 1, 2, \ldots, k_t$. Note that, in contrast to (34), the error term is always $O(\alpha^{3/2})$ in (99) because in the context of stopping sets, $p = r = 2$ implies $\bar{p} = \bar{r} = 3$.

Finally, note that (99) generalizes to D-GLDPC codes the expression $G(\alpha) = \alpha \log(\lambda'(0)\rho'(1) + o(\alpha)$ obtained in [27] for the growth rate of the stopping set size distribution of LDPC codes.
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