Wireless Scheduling with Power Control

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Abstract

We consider the scheduling of arbitrary wireless links in the physical model of interference to minimize the time for satisfying all requests. We study here the combined problem of scheduling and power control, where we seek both an assignment of power settings and a partition of the links so that each set satisfies the signal-to-interference-plus-noise (SINR) constraints.

We give an algorithm that attains an approximation ratio of \(O(\log n \cdot \log \log \Delta)\), where \(n\) is the number of links and \(\Delta\) is the ratio between the longest and the shortest link length. Under the natural assumption that lengths are represented in binary, this gives the first approximation ratio that is polylogarithmic in the size of the input. The algorithm has the desirable property of using an oblivious power assignment, where the power assigned to a sender depends only on the length of the link. We give evidence that this dependence on \(\Delta\) is unavoidable, showing that any reasonably-behaving oblivious power assignment results in a \(\Omega(\log \log \Delta)\)-approximation.

These results hold also for the (weighted) capacity problem of finding a maximum (weighted) subset of links that can be scheduled in a single time slot. In addition, we obtain improved approximation for a bidirectional variant of the scheduling problem, give partial answers to questions about the utility of graphs for modeling physical interference, and generalize the setting from the standard 2-dimensional Euclidean plane to doubling metrics. Finally, we explore the utility of graph models in capturing wireless interference.

1 Introduction

We are interested in fundamental limits on communication in wireless networks. How much communication throughput is possible? This is an issue of efficient spatial separation, keeping the interference from simultaneously communicating links sufficiently low. The interference scheduling problem is then to schedule an arbitrary set of communication links in the least amount of time while satisfying interference constraints. In this paper, we focus on the power control version, where we also choose the power settings for the links.

The scheduling problem depends strongly on the model of interference. Until recently, previous algorithmic work has revolved around various graph-based models, where interference is modeled as a pairwise constraint. This, however, fails to capture the accumulative property of actual radio signals. In contrast, researchers in information, communication, or network theory ("EE") are working with wireless models that sum up interference and respect attenuation. The standard model is the signal-to-interference-plus-noise (SINR) model, to be formally introduced in Section\(\text{2}\). The SINR model reflects physical reality more accurately and is therefore often simply called the physical model. On the other hand, most research in the SINR model has focused

\[\text{References}\]

\[\text{Footnotes}\]
on heuristics that are evaluated by simulation, which neither give insights into the complexity of the problem nor give algorithmic results that may ultimately lead to new protocols.

Formally, given is an arbitrary set of links, each a sender-receiver pair of points in the plane. We seek an assignment of power settings to the senders and a partition of the linkset into minimum number of slots, so that the set of links in each slot satisfies the SINR-constraints. We refer to this as the PC-Scheduling problem. We also consider two closely related throughput maximization problems, both with power control. In the PC-Capacity problem, we seek a maximum cardinality subset of links satisfying the SINR constraints, while in the PC-Weighted-Capacity problem, the links have given weights and we seek to maximize the total weight of a feasible subset. Finally, we also touch on the bidirectional setting, where both nodes in a link may be transmitting, implying a stronger, symmetric form of interference.

For reasons of simplicity of use, it is strongly desirable to use power assignments that are precomputable independent of other links. Such oblivious assignments depend only on the length of the given link. In fact, oblivious assignments appear essential in the distributed setting. The two most frequently used power assignment strategies are indeed of this type, using either uniform (or fixed) power for all the links, or linear assignment that ensures that the signals received at the intended receivers are identical.

The other issue of particular interest is the utility of graphs for modeling interference. It is clear that graphs are imperfect models, given both the non-locality and the additive nature of interference in the SINR model. The perceived difficulty in reasoning analytically about these additional complications has been cited as a factor against SINR model. Still, graphs have proved to be highly versatile tools for analysis and algorithm design, and pairwise constraints are in general much easier to handle than many-to-many constraints. We would therefore like to quantify the cost of doing business using graphs, or the overhead that amenable graph models have over non-graphic models, as well as pinpointing particular situations where graphs work especially well.

1.1 Our Contributions

We give upper and lower bounds on the quality of oblivious power assignments for wireless scheduling problems with power control. We obtain algorithms for all three problems that attain a \(O(\log \log \Delta \cdot \log n)\)-approximation, using a recently introduced oblivious mean (or square root) power assignment. This is an exponential improvement over previous results in terms of \(\Delta\), and leads to a polylogarithmic approximation ratio in terms of the length of the input (under the natural assumptions that lengths be represented in binary). This dependence on \(\Delta\) turns out to be unavoidable — we show that any reasonable oblivious power function forces \(\Omega(\log \log \Delta)\)-approximate schedules.

In the bidirectional setting, we obtain a \(O(\log n)\)-approximation, improving on the previous \(O(\log^c n)\)-factor for PC-Scheduling with \(c > 5\) \cite{14} using considerably simpler arguments.

We precede this analysis with a study of the applicability of uniform power, as a form of ultra-oblivious power assignment, tying together a number of known results. Namely, \(O(\log \Delta)\)-ratios can be attained online or by distributed algorithms. This had previously only been stated explicitly for PC-Capacity. We additionally extend the current state-of-the-art in two ways.

We generalize the setting from the plane to the class of doubling metrics. This assumes that path-loss constant \(\alpha\) is greater than the doubling constant of the metric, which is equivalent to the standard assumption that \(\alpha > 2\) in the plane (see Section \ref{sec:metrics}). This is to assume that the cumulative power of a transmission fades away, and dub this combination of metric and path-loss constant as a fading metric.

Our work aims also to address the utility of graphs in representing physical models of interference, and our results indicate that even if imperfect as models, graphs can still play a useful role. In particular, for links of nearly equal length, we show that unit-disc graphs capture the
SINR-constraints, within constant factors, reducing the problems to the well-studied (weighted) independent set and coloring problems. The $O(\log n \cdot \log \log \Delta)$-approximation result is also relative to the underlying graph.

The current paper refines the results and the arguments in the earlier draft [23], and adds to it approximations of PC-Weighted-Capacity. Additionally, the draft [23] contained a faulty lemma (Lemma 4.3), which is corrected here by proving the main results in Section 4 differently. The new treatment involves an extension of a graph-theoretic approximation property, which may be of independent interest.

1.2 Related Work

Most work in wireless scheduling in the physical (SINR) model has been of heuristic nature, e.g. [11]. Only after the work of Gupta and Kumar [22] did analytical results become en vogue, but were largely non-algorithmic and restricted to networks with a well-behaving topology and traffic pattern such as uniform geometric distribution.

In contrast, the body of algorithmic work is mostly on graph-based models that ultimately abstract away the nature of wireless communication. The inefficiency of graph-based protocols in the SINR model is well documented and has been shown both theoretically and experimentally [21, 30, 35].

Algorithmic work in the SINR model started in 2006 with the seminal work ofMoscibroda and Wattenhofer [33]. In this paper, Moscibroda and Wattenhofer present an algorithm that successfully schedules a set of links (carefully chosen to strongly connect an arbitrary set of nodes) into polylogarithmic number of slots, even in arbitrary worst-case networks. In contrast to our work, the links themselves are not arbitrary (but do have structure that will simplify the problem). This work has been extended and applied to topology control [17, 36], sensor networks [31], and combined scheduling and routing [8]. However, arbitrary networks are beyond the scope of these papers. Apart from these papers, algorithmic SINR results also started showing up here and there, for instance in a game theoretic context or a distributed algorithms context, e.g., [4, 5, 7, 19, 37, 27].

Approximation algorithms for the problem of scheduling wireless links with power control in the SINR model were given in [36], [32] and [8]. In all cases the performance ratios obtained consist of the product of structural properties and a function of the number of nodes. The structural properties are different but can all grow linearly with the size of the network.

A number of recent related results have featured a $O(\log \Delta)$-like approximation in the plane (assuming $\alpha > 2$). Goussievskaia, Oswald and Wattenhofer [20] gave a $O(\log \Delta)$-factor approximation for both the scheduling and the (weighted) capacity problem. They compared their algorithm to the optimal solution constrained to use uniform power assignment, but it requires only a small step to relate it to optimum with power control. Andrews and Dinitz [2] applied this extra step to obtain a $O(\log \Delta)$-approximation for PC-Capacity. Fangh"anel, Kesselheim and V"ocking [15] used a different approach and gave a randomized algorithm for PC-Scheduling that uses $O(OPT \log \Delta + \log^2 n)$ slots. Finally, Avin, Lotker and Pignolet [6] show that the assumption of $\alpha > 2$ used by all previous work may not be necessary, in that the ratio between optimal non-oblivious and oblivious capacity is $O(\log \Delta)$, at least in the 1-dimensional metric.

In [14], Fangh"anel et al. gave a construction that shows that any schedule based on any oblivious power assignment can be a factor of $n$ from optimal. They also introduced the bidirectional version of the scheduling problem and give a $O(\log^{3.5+\alpha} n)$-approximation factor using the mean power assignment in general metrics. Their proof involves non-trivial embeddings into tree metric spaces.

In contrast, the scheduling complexity of arbitrary links in the case of fixed, uniform power is better understood. Constant factor approximation for the corresponding capacity problem
in the plane was given in [18], yielding a $O(\log n)$-approximation for the scheduling problem. Both of these problems are known to be NP-complete [20]. The results obtained here for power control build on and extend the techniques and properties derived in the case of uniform power in [18, 25].

In developments since the original presentation of this work [23], Erlebach and Grant [12] gave a $O(\log \Delta)$-factor approximation algorithm for the problem of multicast scheduling, where each transmission is to be sent to a collection of receivers. Their work uses in a fundamental way the results of the current paper on nearly-equilength links and unit-disc graphs. Fanghænel et al. [13] studied the online version of PC-Capacity problem, obtaining a tight bound of $\theta(\Delta^{d/2})$ on the competitive ratio of deterministic algorithms in $d$-dimensional Euclidean space.

In a breakthrough, Kesselheim [28] has very recently obtained a $O(1)$-approximation algorithm for PC-Capacity. It necessarily uses instance-specific power assignment, and the question of optimal schedules using oblivious power assignment remains interesting both from a theoretical and practical viewpoint. Halldórsson and Mitra [24] have generalized our results for PC-Capacity to arbitrary metric spaces. They additionally obtained the improved approximation factors of $O(\log n + \log \log \Delta)$ and $O(1)$ in the uni-directional and bi-directional cases, respectively. For PC-Scheduling with oblivious power, however, ours are still the best approximation factors known.

2 Notation and Preliminaries

Given is a set $L = \{\ell_1, \ell_2, \ldots, \ell_n\}$ of links, where each link $\ell_v$ represents a communication request from a sender $s_v$ to a receiver $r_v$. The distance between two points $x$ and $y$ is denoted $d(x, y)$. The asymmetric distance from link $\ell_v$ to link $\ell_w$ is the distance from $\ell_v$'s sender to $\ell_w$'s receiver, denoted $d_{vw} = d(s_v, r_w)$. The length of link $\ell_v$ is denoted simply $\ell_v$. We shall assume for simplicity of exposition that all links are of different length; this does not affect the results materially. We assume that each link has a unit-traffic demand, and model the case of non-unit traffic demands by replicating the links.

The nodes can transmit with different power. Let $P_v$ denote the power assigned to link $\ell_v$. We assume the path loss radio propagation model for the reception of signals, where the signal received from $s_w$ at receiver $r_v$ is $P_w/d_{vw}^\alpha$ and $\alpha$ denotes the path-loss exponent. We adopt the physical interference model, in which a node $r_v$ successfully receives a message from a sender $s_v$ if and only if the following condition holds:

$$\frac{P_v/\ell_v^\alpha}{\sum_{\ell_w \in S \setminus \{\ell_v\}} P_w/d_{vw}^\alpha + N} \geq \beta,$$

where $N$ is the ambient noise, $\beta$ denotes the minimum SINR (signal-to-noise-ratio) required for a message to be successfully received, and $S$ is the set of concurrently scheduled links in the same slot. Note that by scaling the power of all the senders, the effect of the noise $N$ can be made arbitrarily small, thus we ignore this term. Of course, in real situations, there are upper bounds on maximum power which we ignore here. We shall also assume that $\beta \geq 3^\alpha$; by the signal-strengthening results of [25], this can only affect the constants in the approximation results. We say that $S$ is SINR-feasible if (1) is satisfied for each link $\ell_v$ in $S$.

This paper deals with power control, i.e., determining the power assignment to the links is a part of the problem. In particular, we focus on oblivious power assignments, where the power depends only on the length of the link, while we compare it to an optimal solution that is free to use any power assignment. The most basic assignment is uniform power, where each link $\ell_v$ uses the same power $P_v = P$. Another common oblivious assignment is linear power, where $P_v = \ell_v^\alpha$. We will focus on uniform power, along with another oblivious assignment, the mean (or, square-root [15]) power $M$ given by $P_v = M_v = \ell_v^{\alpha/2}$. [15]
The affectance of link $\ell_v$ caused by a set $S$ of links \cite{18, 25} under a given power assignment $P$, is the sum of the interferences of the links in $S$ on $\ell_v$ relative to the power received, or

$$a_S(\ell_v) = \sum_{\ell_w \in S \setminus \{\ell_v\}} \frac{P_w/q_{wv}}{P_v/d_{wv}^\alpha} = \sum_{\ell_w \in S \setminus \{\ell_v\}} \frac{P_w}{P_v} \cdot \left(\frac{\ell_v}{d_{wv}}\right)^\alpha$$

For a single link $\ell_v$, we use the shorthand $a_w(v) = a_{\{\ell_v\}}(\ell_v)$. Note that affectance is additive in that for disjoint sets of links $S_1, S_2$, $a_{S_1 \cup S_2}(\ell_v) = a_{S_1}(\ell_v) + a_{S_2}(\ell_v)$.

A $p$-signal set or a schedule is one where the affectance of any link is at most $1/p$, with respect to the given power assignment. A set is SINR-feasible iff it is a $1/\beta$-signal set, i.e., $a_S(\ell_v) \leq 1/\beta$, for each link $\ell_v \in S$. Let $OPT_p$ be a $p$-signal schedule with minimum number of slots. Let $\Delta$ denote the ratio between the maximum and minimum length of a link.

For a graph $G$, let $\chi(G)$ denote its chromatic number, and $\alpha(G)$ its independence number (or the maximum cardinality of a subset of mutually non-adjacent vertices). Define the neighborhood $N(v)$ of a vertex $v$ to be the set consisting of $v$’s neighbors, and the closed neighborhood $N[v]$ to include $v$ as well. For a vertex subset $S$, let $G[S]$ denote the subgraph induced by $S$.

We say that a collection of links is $q$-independent if any two of them, $\ell_v$ and $\ell_w$, satisfy the constraint

$$d_{vw} \cdot d_{wv} \geq q^2 \cdot \ell_w \ell_v .$$

Define the link graph $G_q(L)$ on a link set $L$, parameterized by a constant $q$, such that a pair of links are adjacent in $G_q$ iff they are not $q$-independent.

The following observation shows that a schedule of a linkset forms a coloring of the corresponding link graph. The converse, however, does not necessarily hold, as we shall see. Thus, the graph representation is more relaxed than required.

**Lemma 2.1** If $S$ is a $q^\alpha$-signal set under some power assignment, then $S$ is $q$-independent.

**Proof:** Let $P$ be a power assignment for which $S$ is a $q^\alpha$-signal set. Since the links belong to the same $p$-signal set, for $p = q^\alpha$, they satisfy

$$\frac{P_v/\ell_v^\alpha}{P_w/d_{wv}^\alpha} \geq p, \quad \text{and} \quad \frac{P_w/\ell_w^\alpha}{P_v/d_{wv}^\alpha} \geq p .$$

By multiplying these inequalities together and rearranging, we get that $d_{vw} \cdot d_{wv} \geq p^{2/\alpha} \cdot \ell_w \ell_v = q^2 \cdot \ell_w \ell_v$. □

## 3 Approximations Using Uniform Power

One of the most widely used power assignment is the uniform one, where senders use the same power setting. This might be viewed as ultra-oblivious, as transmissions are now independent of link length.

In Sec. 3.2 we show that uniform power assignment performs well when links are of nearly equal lengths. The global nature of the problem disappears, and local strategies become sufficient. This results in $O(\log \Delta)$-approximation algorithms using any oblivious power assignment, which is argued in Sec. 3.3. In fact, the algorithms for PC-Scheduling and PC-Capacity are $O(\log \Delta)$-competitive online algorithms. These results essentially follow with minor effort from previous works, in particular \cite{20}.

The new contributions in this section are twofold. We introduce fading metrics in Sec. 3.1 and show that a well-dispersed set of links in such a metric has good signal properties. We also show in Sec. 3.2 that unit-disc graphs capture well links of nearly equal lengths.
| **Notation** | **Meaning** | **Topic** | **Page** |
|-------------|-------------|-----------|----------|
| \( \ell_v \) | Link \( \ell_v = (s_v, r_v) \); denotes also its length | 4 |
| \( P_v \) | Power assigned to link \( \ell_v \) | 4 |
| \( \mathcal{M}_v \) | Mean power assignment \( \mathcal{M}_v = \ell_v^{\alpha/2} \) | 4 |
| \( \alpha \) | Path loss constant (signal decay exponent). | SINR | 4 |
| \( \beta \) | SINR requirement (assumed to be at least \( 3^\alpha \)). | 4 |
| \( d(x, y) \) | Distance between points \( x \) and \( y \). | 4 |
| \( d_{vw} \) | \( = d(s_v, r_w) \) | 4 |
| \( a_S(\ell_v) \) | Affectance of linkset \( S \) on link \( \ell_v \) | 5 |
| \( a_w(v) \) | \( = a_{\ell_w}(\ell_v) \) | 5 |
| \( OPT_p \) | Optimal \( p \)-signal schedule | Analysis | 5 |
| \( \Delta \) | Ratio of longest to shortest link length | 5 |
| \( \zeta(x) \) | Riemann zeta-function. | 7 |
| \( q \)-independent | \( d_{vw} \cdot d_{uw} \geq q^2 \cdot \ell_v \ell_w \) | 5 |
| \( t \)-close | \( \max(a_w(w), a_w(v)) \geq t \) | 12 |
| well-separated | Link Lengths differ by factor \( \leq 2 \) or \( \geq \Lambda \) | Link relationships | 13 |
| \( \tau \) | \( 2\beta n \) | 12 |
| \( \Lambda \) | \( 2^\tau^{1/\alpha} \) | 12 |
| \( \chi(G) \) | Chromatic number of graph \( G \) | 5 |
| \( \alpha(G) \) | Independence number of graph \( G \) | 5 |
| \( G_q(L) \) | \( q \)-independence relation on linkset \( L \) | 5 |
| \( U_z(L) \) | Unit-disc graph on the senders in \( L \) | Graphs | 8 |
| \( G[X] \) | Graph induced by vertex subset \( X \) | 5 |
| \( N_G(v) \) | Set of neighbors of node \( v \) in graph \( G \) | 5 |
| \( N_G[v] \) | Closed neighborhood of \( v \), \( = N_G(v) \cup \{v\} \) | 5 |
| \( A = \text{dim}_A(U, d) \) | The Assouad (doubling) dimension (2, for \( \mathbb{R}^2 \)) | 7 |
| \( B(y, \epsilon) \) | Ball of radius \( \epsilon \) centered at \( y \). | Metrics | 7 |
| \( C \) | Constant in doubling dimension definition | 7 |
| \( C' \) | \( = \alpha C_4^A \zeta(\alpha + 1 - A) \) | 7 |
| \( z_1 = z_1(p) \) | \( = 4(pC')^{1/\alpha} \). Sufficient sender separation. | 7 |
| \( z_2 = z_2(p) \) | \( = p^{1/\alpha} - 1 \). Necessary sender separation. | 9 |

Table 1: List of notation
3.1 Scheduling in Fading Metrics

We extend the traditional setting from the Euclidean plane to doubling metrics (see Clarkson [9]).

A metric space is a pair $(\mathcal{U}, d)$, where $\mathcal{U}$ is a set and $d$ is a distance function, satisfying: $d(x, x) = 0$, $d(x, y) = d(y, x)$ (symmetry), and $d(x, y) + d(y, z) \leq d(x, z)$ (triangular inequality), for any points $x, y, z \in \mathcal{U}$. Intuitively, a metric space is doubling if the volume of a ball increases by at most a constant times the radius. Let $B(y, \epsilon) = \{x \in \mathcal{U} | d(x, y) < \epsilon\}$ be the $\epsilon$-ball centered at $y$. A set $Y \subseteq \mathcal{U}$ is an $\epsilon$-packing if $d(x, y) > 2\epsilon$, for any $x, y \in Y$. That is, the set of balls $\{B(y, \epsilon) | y \in Y\}$ are disjoint. The packing number $\mathcal{P}(\mathcal{U}, \epsilon)$ is the size of the largest $\epsilon$-packing, i.e., the maximum number of $\epsilon$-balls that can be packed into the body $\mathcal{U}$. The Assouad dimension $\text{dim}_A(\mathcal{U}, d)$ [3] (also known as uniform metric dimension or doubling dimension) for a metric space $(\mathcal{U}, d)$ is the value $t$, if it exists, such that

$$\sup_{x \in \mathcal{U}; r > 0} \mathcal{P}(B(x, r), \epsilon r) = C \cdot 1/\epsilon^t,$$

as $\epsilon \to 0$, where $C$ is an absolute constant. It is known that $\text{dim}_A(\mathbb{R}^k) = k$ for the $k$-dimensional Euclidean space $\mathbb{R}^k$, and in particular for the plane $C = \frac{1}{4}\pi \sqrt{3} \approx 0.907$ [16, 38].

We require that the path loss exponent $\alpha$ be strictly greater than the doubling dimension $A = \text{dim}_A(\mathcal{U}, d)$ of the metric. This requirement is the reason for not using simpler dimension definitions that are equivalent only up to a constant factor. We shall refer to such a combination of distance metric and path loss constant as a fading metric.

The following result extends similar lemmas in previous works (see [18, 25]) from the setting of the Euclidean plane to the more general class of fading metrics. It yields a converse of Lemma 2.1 for the case of nearly-equilength links. This is the only place where we use the fading property of the metric, i.e., that $\alpha$ is strictly greater than the doubling dimension.

Let $\zeta(x) = \sum_{t \geq 1} \frac{1}{t^\alpha}$ be the Riemann zeta-function, which is well-defined for any $x > 1$. Let $C' = \alpha C A^4 \zeta(\alpha + 1 - A) \text{ and let } z_1(p) = 4(pC')^{1/\alpha}$.

**Lemma 3.1** (Far-away lemma) Let $p$ be positive and let $S$ be a set of links whose senders are of mutual distance at least $zD/2$, where $D$ is the length of the longest link in $S$ and $z = z_1(p)$. Then, using uniform power assignment, $S$ forms a $p$-signal set in any fading metric.

**Proof:** Let $S'$ be the set of senders of links in $S$. Let $Z = zD/4$. The separation of the senders implies that $S'$ is a $Z$-packing. The definition of a doubling metric implies that for any $t > 0$, the packing number of the $tZ$-ball centered at any point is bounded by

$$\mathcal{P}(B(x, tZ), Z) \leq Ct^A.$$

Namely, any packing of balls of radius $Z$ inside a ball of radius $tZ$ contains at most $Ct^A$ balls.

Let $g$ be a number. Let $s_x$ be a sender in $S'$ belonging to link $\ell_x$. Let $S_g = \{s_y \in S' | d(s_x, s_y) < gZ\}$ be the set of senders within distance less than $gZ$ from $s_x$, and let $T_g = S_g \setminus S_{g-1}$. By assumption, $S_2 = \emptyset$. Each sender $s_y$ in $T_g$ is of distance at least $(g-1)Z$ from $s_x$, so $d_{yx} \geq (g-1)Z - D \geq (g-2)Z$. Since $\ell_x \leq D$, the affectance of $\ell_y$ on $\ell_x$ is at most

$$a_y(x) = \frac{1/d_{yx}}{1/\ell_x} \leq \left(\frac{D}{(g-2)Z}\right)^\alpha = \left(\frac{4}{(g-2)z}\right)^\alpha, \quad \forall \ell_y \in T_g.$$

Observe that

$$\frac{1}{(g-1)^\alpha} - \frac{1}{g^\alpha} = \frac{g^\alpha - (g-1)^\alpha}{g^\alpha(g-1)^\alpha} \leq \frac{\alpha g^{\alpha-1}}{g^\alpha(g-1)^\alpha} < \frac{\alpha}{(g-1)^{\alpha+1}}.$$
Then,

\[ a_S(x) = \sum_{g \geq 3} a_{T_g}(x) \]

\[ \leq \sum_{g \geq 3} |S_g \setminus S_{g-1}| \cdot \left( \frac{4}{(g-2)^z} \right)^\alpha \]

\[ = \left( \frac{4}{z} \right)^\alpha \sum_{g \geq 3} |S_g| \left( \frac{1}{(g-2)^\alpha} - \frac{1}{(g-1)^\alpha} \right) \]

\[ \leq \left( \frac{4}{z} \right)^\alpha \sum_{g \geq 3} |S_g| \frac{\alpha}{(g-2)^{\alpha+1}} . \]

(3)

The balls of radius \( Z \) centered at points in \( S_g \) are all contained within the ball \( B(x, (g+1)Z) \). For \( g \geq 3 \), the packing bound (2) then implies that \( |S_g| \leq \mathcal{P}(B(x, (g+1)Z), Z) \leq C(g+1)^A \), and thus we have that

\[ \frac{|S_g|}{(g-2)^{\alpha+1}} \leq \frac{C(g+1)^A}{(g-2)^{\alpha+1}} \leq \frac{4^A C}{(g-2)^{\alpha+1-A}} . \]

Continuing from (3),

\[ a_S(x) \leq \left( \frac{4}{z} \right)^\alpha \cdot 4^A C \sum_{x \geq 1} \frac{1}{x^{\alpha+1-A}} = \left( \frac{4}{z} \right)^\alpha \cdot 4^A C \zeta(\alpha + 1 - A) = \left( \frac{4}{z} \right)^\alpha C' . \]

Thus, \( S \) is an \( s \)-signal set, where \( s = \frac{1}{\mathcal{P}(\frac{4}{z})^\alpha} = p \). \( \square \)

**Remark 3.2** Lemma 3.1 does not hold in general for arbitrary distance metrics. In particular, it fails for \( \mathbb{R}^2 \) when \( \alpha \leq 2 \). In fact, unit-length links arranged in a grid with separation \( q \) will be \( q^\alpha \)-independent, while maximum affectance becomes \( \Omega(\log n) \).

### 3.2 Modelling Nearly-Equilibrium Links as Unit-Disc Graphs

We observe here that if the links are of nearly equal length, then we can simplify the many-to-many interference relationships by a pairwise relationship, modulo small constant factors in the approximation. These pairwise relationships correspond to the graphs formed by discs of fixed radius in the plane. With one radius, we capture the necessary distance between any pair of links in a feasible solution, while with another larger radius, we have the sufficient distance so that any set of links of such mutual separation is guaranteed to be SINR-feasible (in any given fading metric). This leads to simple and effective approximation algorithms that can be made online and turned into distributed algorithms.

We say that a set of links is *nearly-equilibrium* if lengths of any pair of links in the set differ by a factor of less than 2. The key observation is that we can represent the link graph \( G_q = G_q(L) \) of a set \( L \) of nearly-equilibrium links approximately with a unit-disc graph (UDG).

**Definition 3.3** Let \( L \) be a linkset in a fading metric, and let \( d \) denote the minimum link length in \( L \). Given a number \( z \), the unit-disc graph \( U_z(L) \) of \( L \) is the graph with a node for each sender of \( L \) with two nodes adjacent if the distance between the two senders is less than \( z \cdot d \).

That is, \( U_z(L) \) is the graph formed by the intersection of balls of radius \( zd/2 \) that are centered at the senders. We find that the link graphs and UDGs are closely related, in that pairs of graphs of one type sandwich graphs of the other type.
Lemma 3.4 For any \( q \geq 1 \) and any nearly-equilength linkset \( L \), \( U_{q-1}(L) \subseteq G_q(L) \) and \( G_q(L) \subseteq U_{2(q+1)}(L) \).

Proof: Recall that the links have lengths in the range \([d, 2d]\). Let \( \ell_u \) and \( \ell_w \) be links that are neighbors in \( U_{q-1}(L) \). Then, \( d(s_u, s_w) < (q-1) \cdot d \), by definition. Thus, \( d_{uw} \leq d(s_u, s_w) + \ell_w < qd \cdot \ell_u \), and similarly \( d_{uw} < qd \cdot \ell_w \). Hence, \( d_{uw} \cdot d_{uw} < q^2 \ell_u \cdot \ell_w \), so \( \ell_u \) and \( \ell_w \) are neighbors in \( G_q \).

On the other hand, suppose we have neighbors \( \ell_u \) and \( \ell_w \) in \( G_q \). Notice that \( d(s_u, s_w) \leq d_{uw} + \ell_w < d_{uw} + 2d \), and similarly \( d(s_u, s_w) < d_{uw} + 2d \). Then,

\[
(d(s_u, s_w) - 2d)^2 < d_{uw} \cdot d_{uw} < q^2 \ell_u \cdot \ell_w < (2qd)^2.
\]

Thus, \( d(s_u, s_w) < 2(q + 1)d \). Hence, \( \ell_u \) and \( \ell_w \) are neighbors in \( U_{2(q+1)}(L) \).

Read differently, the above lemma implies that sender separation and signal strength of a linkset go hand in hand. Namely, if \( S \) is a \( q \)-independent set of nearly-equilength links, then the senders of the links are of mutual distance at least \((q-1)d\), and thus \( U_{q-1}(S) \) is an empty graph (independent set). Conversely, if \( X \) is an independent set in unit-disc graph \( U_{2(q+1)}(L) \), where \( L \) is nearly-equilength linkset, then \( X \) is \( q \)-independent.

We can now argue our claim that unit-disc graphs capture well nearly-equilength links in fading metrics. Define \( z_2 = z_2(p) = p^{1/\alpha} - 1 \). We show that a linkset with minimum link length \( d \) and pairwise sender separation of at least \( z_1(p) \cdot d \) will be a \( p \)-signal set, while any \( p \)-signal set must obey a separation of at least \( z_2(p) \cdot d \).

Theorem 3.5 For a set \( L \) of nearly-equilength links, any independent set in \( U_{z_1}(L) \) is a \( p \)-signal linkset under uniform power, and any \( p \)-signal subset of \( L \) is an independent set in \( U_{z_2}(L) \).

Proof: By Lemma 3.4 an independent set \( X \) in \( U_{z_1}(L) \) is a \( p \)-signal set. By Lemma 2.1 a \( p \)-signal subset \( S \) of \( L \) is \((p^{1/\alpha})\)-independent (i.e., an independent set in \( G_{p^{1/\alpha}} \)). By Lemma 3.4, it is then an independent set in \( U_{p^{1/\alpha}-1}(L) \).

We note that unit-disc graphs in fading metrics satisfy a bounded-independence property as follows. Recall that \( \alpha(G) \) is the cardinality of a maximum independent set in \( G \).

Observation 3.6 Let \( a \) and \( b \) be given constants, \( a \geq b \). Let \( U_a = U_a(L) \) and \( U_b = U_b(L) \) be unit-disc graphs on the same linkset \( L \) but with different radii. Let \( \ell_v \) be a link in \( L \), corresponding to a node \( v \) in \( U_a \) with closed neighborhood \( N_1 = N_{U_a}[v] \). Then, \( \alpha(U_b[N_1]) \leq C(1 + 2a/b)^A \).

Proof: The nodes in an independent set \( I \) in \( U_b \) form disjoint balls of radius \( bd/2 \) centered at the senders of the links. All senders of links in \( N_1 \) are contained in the ball \( B(s_v, ad) \), where \( d \) is the minimum link length in \( L \). Thus, all the balls corresponding to \( I \) are contained in the larger ball \( B(s_v, (a + b/2)d) \). The packing constraint of the metric ensures that a limited number of the smaller disjoint balls fit inside the large ball, implying that \( |I| \leq P(B(s_v, (a + b/2)d), bd/2) \leq C(1 + 2a/b)^A \).

Our problems reduce then, within constant factors, to coloring and (weighted) independent sets in UDGs. We say that an independent set in a weighted graph is greedy if it is obtained by the iterative process of selecting a vertex whose weight is greater than each of its neighbours’, deleting the neighbors, and recursing on the remaining graph.

The following result is immediate from Thm. 3.5 and Obs. 3.6.

Theorem 3.7 Let \( L \) be a nearly-equilength linkset. Then, any maximal independent set of \( U_{z_1}(L) \) is an \( O(1) \)-approximation of PC-Capacity and any greedy independent set of \( U_{z_1}(L) \) is an \( O(1) \)-approximation of PC-Weighted-Capacity.
We define a coloring of a graph $G$ to be minimal if it uses at most $D(G) + 1$ colors, where $D(G)$ is the maximum degree of a vertex in $G$.

**Theorem 3.8** Let $L$ be a nearly-equilength linkset. Let $S$ be a minimal coloring of $U_{z_1}(L)$. Then, using uniform power, $S$ induces a schedule that yields a $O(1)$-approximation to PC-Scheduling.

**Proof:** The coloring $S$ forms an SINR-feasible schedule of $L$, by Thm. 3.5 and uses at most $D(U_{z_1}(L)) + 1$ colors, by the minimality of the coloring. Consider the closed neighborhood $N_1 = N_{U_{z_1}}[v]$ of a maximum degree node $v$ in $U_{z_1}$. By Obs. 3.6 at most $s = C(1 + 2z_1/z_2)^A$ nodes in $N_1$ can be in any feasible slot. Hence, the optimal solution uses at least $|N_1|/s = (D(U_{z_1}(L)) + 1)/s$ slots, for a performance ratio of $s$. □

The performance ratio of our algorithms is bounded by $C(1 + 2z_1/z_2)^A$.

Efficient distributed algorithms are known for coloring unit-disc graphs in the plane [10] and more generally bounded-independence graphs [34]. Thus, our characterization can be translated into distributed constant-factor approximation algorithms of PC-Scheduling and PC-Capacity in nearly-equilength linksets, when given the appropriate communication primitives.

### 3.3 Scheduling Arbitrary Linksets

We can handle links of arbitrary lengths by partitioning them into groups, where lengths of links in each group differ by a factor of at most 2. A simple approach is to schedule each group separately using Thm. 3.8 or to select the largest of the approximately maximum (weighted) capacity subsets from each of the groups.

Let $g(L) = |\{m : \exists \ell_v, \lceil \log \ell_v \rceil = m\}|$ denote the length diversity of the link set $L$, or the number of length groups. Note that $g(L) \leq \log \Delta$.

**Theorem 3.9** The PC-Scheduling, PC-Capacity, and PC-Weighted-Capacity problems are $O(g(L))$-approximable, using uniform power assignment.

Moscibroda and Wattenhofer [33] showed that uniform power scheduling can be highly sub-optimal, and Moscibroda, Oswald and Wattenhofer [32] showed that it can be as much as a factor of $n$ or $\Omega(\log \Delta)$ from optimal. Specifically, they constructed a set of links with the property that any there exists a power assignment that makes the linkset feasible, while any use of uniform power results in the trivial schedule of $n$ slots. Hence, the ratio of $\theta(\log \Delta)$ is best possible for uniform power.

We can also claim easy online algorithms. The algorithm for PC-Scheduling is in fact online.

**Corollary 3.10** There is a deterministic online algorithm for PC-Scheduling that is constant competitive on nearly-equilength links and $O(\log \Delta)$-competitive in general.

A similar result can be attained by PC-Capacity by a randomized online algorithm that randomly picks one of the length groups and then picks greedily from that group. If the value of $\Delta$ is not known, then an approach of Lipton and Tomkins [29] can be used.

**Corollary 3.11** There is a randomized $O(\log \Delta)$-competitive algorithm for PC-Capacity, when $\Delta$ is known in advance, and an $O(\Delta^{1+\epsilon})$-competitive algorithm otherwise, for any $\epsilon > 0$. 

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10
4 Approximations Using Mean Power

We explore in this section the power of oblivious assignments. The results of the preceding section apply to all oblivious power functions, but are tight only for uniform and linear power assignments. We can greatly surpass these bounds by being selective about the oblivious function used; in particular, we obtain these improvements for the mean power assignment $M$.

We present in Sec. 4.2 a scheduling algorithm using $M$ that achieves a ratio of $O(\log \log \Delta \cdot \log n)$. In the bidirectional setting, the algorithm obtains an improved $O(\log n)$-ratio, as shown in Sec. 4.3. The same results hold also for the (weighted) capacity problem. We complement these results with a construction in Sec. 4.4 that suggests a $\Omega(\log \log \Delta)$-separation between the lengths of optimal schedules with or without oblivious power assignments.

We first introduce our approximation technique, which may be of independent interest. This subsection may be skipped by the reader that is not concerned with methods for weighted capacity or extensions of the graph-theoretic notion of inductiveness.

4.1 Approximation Via Inductiveness

A common heuristic for subset problems is to find a “good” item, and then recurse on the set of remaining items that are compatible with the first one. This yields good approximations if we can show that only a small number of the items eliminated in each round can belong to any optimal solution. For instance, if the incompatibilities are in the form of a graph and the set of nodes eliminated can be covered by $k$ cliques, a $k$-approximation follows. We generalize this well-known concept to fit to our situation.

We have a set of links $L$, and a set property on $L$ in the form of $p$-signal sets. We shall partially capture this property with a graph in the following sense. For a set of links to be feasible it is a sufficient but not a necessary condition for it to form an independent set in the graph. E.g., for set $L$ of nearly-equilength links, this property holds for the graph $U_{2n}(L)$, by Thm. 3.5. This motivates the extensions we put forth below.

A set property $\pi$ is said to be hereditary if, whenever $\pi(S)$ holds for a set $S$, it also holds for any $S' \subseteq S$. In other words, $\pi$ represents a monotone Boolean function. A (sub)set satisfying $\pi$ is said to be a $\pi$-(sub)set. Let $\Pi(S)$ be the maximum cardinality of a $\pi$-subset of $S$. We say that a graph $G = (V, E)$ is compatible with a property $\pi$ on $V$ if any independent set in $G$ satisfies $\pi$.

Definition 4.1 Let $V$ be a set of elements, $\pi$ be a hereditary set property defined on $V$, and $G = (V, E)$ be a graph on $V$ that is compatible with $\pi$. Then, $G$ is $k$-\pi-independent if there is an ordering $v_1, v_2, \ldots, v_n$ of the elements, such that for any $v_i$, $1 \leq i \leq n$, it holds that $\Pi(N[v_i] \cap \{v_i, v_{i+1}, \ldots, v_n\}) \leq k$.

To be useful in this context, property $\pi$ needs to be polynomial-time checkable; this holds for the case of SINR feasibility by solving a system of linear constraints. Additionally, there needs to be an oracle to determine the inductive ordering of the vertices.

This property generalizes the property of being sequentially $k$-independent, where $\pi$ is the property of a vertex set being independent in the graph. This latter property has been around for a while, but was first studied explicitly in [1], followed by [39]. Various optimization problems can be approximated on sequentially $k$-independent graphs within a factor of $k$, including Weighted Independent Set [1] and Graph Coloring [39], when an appropriate vertex ordering can be determined.

The (Weighted) Maximum $\pi$-subset problem is defined as follows for a given hereditary property $\pi$: Given a set $V$ of items and a (vertex-weighted) graph $G = (V, E)$ compatible with $\pi$, find a maximum (weight) subset $X \subset V$ that satisfies $\pi$. In the Minimum Partition into $\pi$-Subsets problem, we seek a partition of $V$ into fewest number of $\pi$-subsets. Note that optimal
solutions to these problems do not depend on the graph $G$; rather, the structure of $G$ specifies the inductiveness characteristic.

**Proposition 4.2** Let $\pi$ be a polynomially-time verifiable hereditary property with a polynomial-time oracle to find $k$-$\pi$-inductive orderings. Then, there are $k$-approximation algorithms for the Weighted Maximum $\pi$-Subset and Minimum Partition into $\pi$-Subsets problems on $k$-$\pi$-inductive instances.

*Proof:* Let $G = (V, E)$ denote an input instance, which by definition is compatible with $\pi$. To approximate the unweighted $\pi$-subset problem, we process the nodes in the $k$-$\pi$-inductive order. For each vertex we encounter, we add it to our solution if it has no neighbor among the previously added vertices. This results in an independent set in $G$, which is a feasible $\pi$-subset since $G$ is compatible with $\pi$. For each node added to the solution, at most $k$ nodes from any feasible solution are eliminated from consideration, by Def. [41]. Hence, our solution is within a factor of $k$ from optimal.

To approximate the partitioning problem, we process the nodes in the reverse $k$-$\pi$-inductive order and assign each node to the first class to which no neighbor in $G$ has previously been assigned. Again, each set is independent and thus we obtain a proper partition into $\pi$-sets. Let $v_i$ be a node assigned the largest numbered class by this algorithm and let $N_i = \{v_j: (j > i) \land (v_j, v_i) \in E(G)\}$ be the neighbors of $v_i$ that follow it in the inductive order. Observe that the number of the class that $v_i$ is assigned, and thus the total number of classes used by the algorithm, is at most $|N_i| + 1$. On the other hand, by the definition of $k$-$\pi$-inductiveness, at most $k$ nodes in $N_i \cup \{v_i\}$ belong to any $\pi$-set, and thus the optimal partition of $V$ uses at least $(|N_i| + 1)/k$ classes. Hence, the algorithm is $k$-approximate.

To approximate the weighted $\pi$-subset problem, we use the local ratio algorithm of [39]. The algorithm and its proof are given in the appendix for completeness. \hfill \Box

### 4.2 Unidirectional Scheduling

In this subsection, which is the heart of the paper, we obtain qualitatively improved link scheduling with oblivious power.

We shall utilize the mean power assignment (or, square-root assignment [15]) given by $M_v = \ell_v^{1/2}$. The affectance of link $\ell_w$ on link $\ell_v$ under $M$ is

$$a_w(v) = \frac{M_w/d_{wv}^\alpha}{M_v/d_v^\alpha} \left(\frac{\ell_w}{\ell_v}\right)^{\alpha/2} \left(\frac{\ell_v}{d_{wv}}\right)^\alpha = \left(\frac{\sqrt{\ell_v\ell_w}}{d_{wv}}\right)^\alpha.$$  

The following observation motivates the consideration of this power assignment.

**Observation 4.3** Suppose $d_{wv} = d_{v}w$, for two links $\ell_v$, $\ell_w$. Then, $a_w(v) = a_v(w)$ iff we use mean power assignment.

Let $\tau = 2\beta n$ and $\Lambda = 2\tau^{2/\alpha}$. We say that a link $\ell_v$ and $\ell_w$ are $t$-close under mean power assignment if, $\max(a_v(w), a_w(v)) \geq t$.

The key observation that we make is that each link affects (or is affected by) few links that are of widely different length. We can then treat those affectance relationships in a graph-theoretic manner. This central observation holds independent of metric. Recall that we assumed that $\beta \geq 3^\alpha$, and thus it follows from Lemma [24] that any slot in an optimal solution is a 3-independent linkset.

**Lemma 4.4** Let $Q$ be a 3-independent set of links in an arbitrary metric space, and let $\ell_v$ be a link that is shorter than the links in $Q$ by a factor of at least $\Lambda$. Suppose all the links in $Q$ are $1/\gamma$-close to $\ell_v$ under mean power assignment. Then, $|Q| = O(\log \log \Delta)$.  


**Proof:** The set $Q$ consists of two types of links: those that affect $\ell_v$ by at least $\frac{1}{\tau}$ under mean power, and those that are affected by $\ell_v$ by that amount. We shall consider the former type; the argument is nearly identical for the latter type, and will be omitted.

Consider a pair $\ell_w, \ell_{w'}$ in $Q$ that affect $\ell_v$ by at least $1/\tau$, and suppose without loss of generality that $\ell_w \geq \ell_{w'}$. The affectance of $\ell_w$ on $\ell_v$ implies that $\sqrt{\ell_v \ell_w} \geq d_{wv}^{1/\alpha} \cdot 1/\tau$, or

$$d_{wv} \leq \sqrt{\ell_v \ell_w}^{1/\alpha} = \sqrt{\ell_v \ell_w}^{1/2}. $$

Similarly, $d_{w'v} \leq \sqrt{\ell_v \ell_w}^{1/2}$. By the triangular inequality we have that

$$d_{w'w} \leq d(s'_{w'}, r_v) + d(r_v, s_w) + d(s_w, r_w) \leq \ell_w + \sqrt{2 \Lambda \ell_v \ell_w} < 3 \ell_w,$$

using that $\sqrt{\ell_w} \geq \sqrt{\Lambda \ell_v}$. Similarly,

$$d_{ww'} \leq d_{wv} + d_{w'v} + \ell_{w'} \leq \ell_{w'} + \sqrt{2 \Lambda \ell_v \ell_w}. $$

Multiplying together, we obtain that

$$d_{w'w} \cdot d_{ww'} \leq 3 \ell_w \ell_{w'} + 3 \sqrt{2 \Lambda \ell_v \ell_{w'}} \cdot \ell_w. $$

By 3-independence, $d_{w'w} \cdot d_{ww'} \geq 9 \ell_w \ell_{w'}$. By combining the last two inequalities and cancelling a $6\ell_w$ factor, we have that $\ell_{w'} \leq \sqrt{\Lambda \ell_v \ell_w} / 2$, or

$$\ell_{w'} \geq \frac{2 \ell_w^2}{\Lambda \ell_v}. \quad (4)$$

Label the links in $Q$ by $\ell_1, \ell_2, \ldots, \ell_t$ in increasing order of length. Equation (4) implies that

$$\frac{\ell_{i+1}}{\ell_i} \geq \frac{2\ell_i}{\ell_v \Lambda} \geq \frac{2 \ell_i}{\ell_1}, \quad (5)$$

for any $i = 2, 3, \ldots, t$. Thus, if we let $\lambda_i = \ell_i / \ell_1$, we get from (5) that $\lambda_{i+1} \geq 2\lambda_i^2$, and by induction that $\lambda_t \geq 2^{t^2 - 1}$. Hence, $|Q| = t \leq \frac{\lg \Lambda}{\lg \lambda_t} + 2 \leq \frac{\lg \Delta}{\lg \Delta} + 2$, and the lemma follows. \hfill \Box

We say that a set $S$ of links is well-separated if any pair of links differ in length by a factor that is either less than 2 or greater than $\Lambda$, and that a link $\ell_w$ is length-separated from link $\ell_v$ if $\ell_w > \Lambda \ell_v$.

We now proceed as follows. We partition a given linkset $L$ into classes $L_1, L_2, \ldots, L_M$, where $M = \lceil 2 \Lambda \rceil$, such that $L_i = \{ \ell_v : \exists k, [\lg \ell_v] = i + kM \}$. Namely, each $L_i$ is a well-separated set. We shall solve the problems independently on the classes $L_i$ and combine the subsolutions in the obvious way.

Let $S$ be a well-separated linkset and $d$ be the minimum link length in $S$. Let $z = z_1(2^{1+\alpha/2} \beta)$. Define the graph $H(S)$ on $S$ where two links $\ell_v$ and $\ell_w$ are adjacent if they are either: a) nearly-equilength and the distance between their senders is at most $zd$, or b) length-separated and 1/\tau-close. We show the scheduling and capacity problems are captured well as coloring and independent set problems on the graph $H$.

**Lemma 4.5** Let $S$ be a well-separated linkset in a fading metric. Then, any subset of $S$ that is independent in $H(S)$ is SINR-feasible using mean power.
Proof: Let \( X \) be a subset of \( S \) that is independent in \( H(S) \). Consider a link \( \ell_v \) in \( X \). Let \( S_v \) be the set of links in \( S \) that are nearly-equal length to \( \ell_v \) (including \( \ell_v \)), \( X_v = X \cap S_v \) and \( \hat{X} = X \setminus X_v \). We bound the affectance on \( \ell_v \) separately for \( X_v \) and \( \hat{X} \). None of the links in \( \hat{X} \) are \( 1/\tau \)-close to \( \ell_v \), so each affects \( \ell_v \) by at most \( 1/\tau \), for a total of \( a_X(\ell_v \leq n \cdot 1/\tau = 1/(2\beta) \). By definition, \( X_v \) is independent in \( U_{\delta}(S_v) \), where \( z = z_1(2^{1+\alpha/2}\beta) \), and so by Thm 3.5 it is a \( 2^{1+\alpha/2}\beta \)-signal set under uniform power. Changing to mean power introduces a variance of at most \( 2^{\alpha/2} \) in the transmission powers, since the variance in length is at most 2. Thus, \( X_v \) is a \( 2\beta \)-signal set under mean power. Hence, under mean power, \( a_X(\ell_v) \leq 1/(2\beta) \) and \( a_X(\ell_v) = a_X(\ell_v) + a_X(\ell_v) \leq 1/\beta \). \( \square \)

The graph \( H(S) \) of a well-separated linkset \( S \) has good inductiveness properties. Denote the case of \( k\pi \)-inductiveness when \( \pi \) refers to SINR feasibility as \( k\text{-SINR}-inductive \).

**Lemma 4.6** Let \( S \) be a well-separated linkset in a fading metric. Then, \( H(S) \) is \( O(\log \log \Delta) \)-SINR-inductive. The inductive ordering is that of non-decreasing link length.

**Proof:** Let \( \ell_v \) be the shortest link in \( S \). Let \( X \) be an SINR-feasible subset of \( N_H(\ell_v) \), the closed neighborhood of \( \ell_v \) in \( H(S) \). We shall show that \( |X| = O(\log \log \Delta) \). We can then order \( \ell_v \) first and apply the claim inductively on \( S \setminus \{\ell_v\} \) to obtain the remainder of the inductive order, yielding the lemma.

Let \( S_v \) be the subset of nearly-equal length links in \( S \) of length at most double that of \( \ell_v \). The nearly-equal length feasible (\( \beta \)-signal) linkset \( X_v = X \cap S_v \) is an independent set in \( U_{z_2(\beta)}(S_v) \), by Thm 3.5. Note that \( X_v \) is contained in the closed-neighborhood of \( \ell_v \) in \( U_{z_1(2\beta)}(S_v) \). Then, by Obs. 3.6

\[
|X_v| \leq \alpha(U_{z_2(\beta)}[X]) \leq C(1 + 2z_1(2\beta)/z_2(\beta))^{\alpha} = O(1) .
\]

The other neighbors of \( \ell_v \), those in \( X \setminus X_v \), are length-separated from \( \ell_v \). By Lemma 4.4, \( \ell_v \) has at most \( O(\log \log \Delta) \) length-separated neighbors in \( X \). Hence, \( |X| = O(\log \log \Delta) + O(1) = O(\log \log \Delta) \).

We now apply Prop. 4.2 on each of the \( O(\log n) \) classes \( L_i \) separately to obtain our main result.

**Theorem 4.7** **PC-Scheduling, PC-Capacity, and PC-Weighted-Capacity** are \( O(\log \log \Delta \cdot \log n) \)-approximable in fading metrics.

Finally, we obtain as corollary, a relationship between schedule length and the chromatic number of a certain graph on the links. Let \( G'(L) \) be the graph on the linkset \( L \) formed by the complete union of the graphs \( H(L_i) \), for \( i = 1, 2, \ldots \). Namely, links in different length classes are adjacent in \( G' \), while links in the same length class \( L_i \) induce the subgraph \( H(L_i) \).

**Corollary 4.8** There is an algorithm that outputs a feasible scheduling using \( O(\log \log \Delta \cdot \log n) \cdot \chi(G'(L)) \) slots in fading metrics.

### 4.3 Bidirectional Scheduling

In the bidirectional variant introduced by Fanghäl et al [14], a stronger separation criteria applies, since communication along each link can occur in either direction. The asymmetry between sender and receiver disappears and thus studying this model is useful in order to explore the cost of asymmetry.

The distance between two links is now the shortest distance between any endpoints of the links. Thus, \( d_{uv} = d_{vu} = \min(d(r_v, r_u), d(r_v, s_u), d(s_v, s_u), d(s_v, r_u)) \). Other definitions are unchanged.
We can obtain a better approximation ratio for this problem, with essentially the same algorithm, via the following stronger version of Lemma 4.4.

Lemma 4.9 Let $S$ be a set of $2$-independent links in a bidirectional fading metric and let $\ell_v$ be a link. Then, there is at most one link $\ell_w$ in $S$ with $\ell_w > \tau^{2/\alpha} \cdot \ell_v$ that is $1/\tau$-close under mean power assignment.

**Proof:** Suppose the lemma is false and let $\ell_w, \ell_{w'}$ be two links in $S$ that are longer than $\tau^{2/\alpha}$ times $\ell_v$ and affect it by at least $1/\tau$ each. Suppose without loss of generality that $\ell_w \geq \ell_{w'}$. The assumption of affectance under mean power assignment implies that
\[
\left(\frac{\sqrt{\ell_v \ell_u}}{d_{vu}}\right)^\alpha \geq \frac{1}{\tau},
\]
for $u \in \{w, w'\}$. Thus, $d_{vu} \leq \tau^{1/\alpha} \sqrt{\ell_v \ell_u}$. In the bidirectional case, $d_{vu} = d_{uv}$. Thus, by the triangular inequality, we have that
\[
d_{w'w} = d_{ww'} \leq d_{ww} + d_{w'w} \leq 2\tau^{1/\alpha} \sqrt{\ell_v \ell_w} < 2\tau^{1/\alpha} \sqrt{(\ell_{w'}/\Lambda)\ell_w} = 2\ell_{w'}\ell_w.
\]
Then, $\ell_w$ and $\ell_{w'}$ are not $2$-independent, which contradicts our assumption.

The rest of the argument is identical to the unidirectional case. Lemma 4.5 still holds, while we get a stronger version of Lemma 4.6.

Lemma 4.10 Let $S$ be a well-separated linkset in a bidirectional fading metric and let $q$ be as in Lemma 4.5. Then, $H(S)$ is $O(1)$-SINR-inductive. The inductive ordering is that of non-decreasing link length.

As before, we partition $L$ into $O(\log n)$ well-separated subsets $L_1, L_2, \ldots$, using Prop. 4.2 on each of them. This results in the following approximation results.

Theorem 4.11 There is an $O(\log n)$-approximation for the bidirectional versions of PC-Scheduling, PC-Capacity, and PC-Weighted-Capacity in fading metrics.

Finally, we get a tighter relationship with graphs. Let $G'(L)$ be defined as in the previous subsection.

Corollary 4.12 There is an algorithm that outputs a feasible scheduling using $O(\log n) \cdot \chi(G'(L))$ slots in fading metrics, in the bidirectional setting.

4.4 Construction

We now give evidence that the upper bounds obtained are close to the best possible for oblivious power functions. A similar result follows also from the constructions in [15] by analyzing the dependence on $\Delta$.

We say that a function $f$ is *well-behaved* if there is an $\epsilon > 0$, such that either a) for any $x > x' > 0$, it holds that $f(x) = O((x/x')^{\alpha-\epsilon}) f(x')$ or b) for any $x > x' > 0$, it holds that $f(x) = \Omega((x/x')^{\epsilon}) f(x')$. Essentially, the definition stipulates that the function either grows at a steady polynomial (possibly of very small degree) rate, or is limited in its growth by a polynomial of degree strictly less than $\alpha$. This means that the function can be jittery and locally unstable, but on a large scale it can’t be all over the place. Intuitively, any reasonable power assignment function is well-behaved; in particular, it holds for all functions considered in the literature, which are polynomials.
Theorem 4.13 For any well-behaved power function $\phi$, there is a SINR-feasible instance for which any schedule under $\phi$ requires $\Omega(\log \log \Delta)$ slots.

Proof: Consider first the case when $\phi$ grows moderately slowly, i.e., there are fixed constants $\epsilon, c, c_0$ such that for any $x, x'$ with $x > c_0 x'$, $\phi(x) \leq c \cdot x^{\alpha - \epsilon} \phi(x')$. We assume for simplicity that $\beta = 1$.

Let $t = \max\left(\left[(2\alpha + \log c)/\epsilon\right], 4\right)$ and $c_1 = \log \log c_0$. Consider the following set of links $L = \{\ell_1, \ell_2, \ldots, \ell_n\}$ located on the real line, where the length of link $\ell_i$ is $\ell_i = 2^i + c_1$. Let $a_i = \sum_{j=0}^{i} \ell_j$, where $\ell_0$ denotes $2^{c_1}$. Position the receiver $r_i$ of $\ell_i$ at location $+a_{i-1}$ and the sender $s_i$ at location $-(\ell_i - a_{i-1})$. Observe that for any $i > j$, we have that $\ell_i \geq c_0 \ell_j$, and thus

$$\frac{\phi(\ell_i)}{\phi(\ell_j)} < c \left(\frac{\ell_i}{\ell_j}\right)^{\alpha - \epsilon} < c d_i^{\alpha - \epsilon}, \quad (6)$$

where the second inequality uses that $\ell_j > 1$. Observe that for $i > j$,

$$d_{ji} = (\ell_j - a_{j-1}) + a_{i-1} \leq \ell_{i-1} - a_{i-2} + a_{i-1} = 2\ell_{i-1},$$

and that

$$\log \frac{\ell_i}{\ell_{i-1}} = t_i + c_1 \epsilon - t_i - 1 + c_1 \alpha \geq t \epsilon - \epsilon \alpha \geq \log c + \alpha,$$

which together imply that

$$\ell_i \geq c 2^\alpha \ell_{i-1} \geq c d_{ji}^\alpha. \quad (7)$$

Thus, using Inequalities (6) and (7), respectively, we have that for $i > j$,

$$a_j(i) = \frac{\phi_j}{\phi_i} \cdot \frac{\ell_i}{d_{ji}^\alpha} > \frac{1}{c d_i^{\alpha - \epsilon}} \cdot \frac{\ell_i}{d_{ji}^\alpha} = \frac{\ell_i}{c d_{ji}^\alpha} \geq 1.$$  

Hence, in any schedule based on the mean assignment, each of the $n$ links must be assigned to distinct slots.

Consider instead the oblivious power assignment function $\Psi(v) = \ell_v^\alpha / \log \ell_v$. Note that for $i > j$ in the configuration above, $d_{ji} = \ell_j - a_{j-1} + a_{i-1} > \ell_j$. Then, under $\Psi$, we have that for $i > j$,

$$a_j(i) = \frac{\Psi(\ell_j)/d_{ji}^\alpha}{\Psi(\ell_i)/d_{ji}^\alpha} = \frac{\ell_j}{d_{ji}^\alpha} \cdot \log \ell_i = \frac{\ell_j^{i-j}}{d_{ji}^\alpha} \leq t_i^{i-j}. $$

Note that for $k > i$, it holds that $d_{ki} = a_{i-1} + \ell_k - a_{k-1} \geq \ell_k/2$. Thus, for $k > i$,

$$a_k(i) = \frac{\Psi(\ell_k)/d_{ki}^\alpha}{\Psi(\ell_i)/d_{ki}^\alpha} = \frac{\ell_k}{d_{ki}^\alpha} \cdot \log \ell_i = \frac{\ell_k^{i-k}}{d_{ki}^\alpha} \leq 2t_i^{i-k}. $$

It follows that under $\Psi$, for any link $\ell_i \in L$, it holds that

$$a_L(i) \leq \sum_{j<i} t_i^{j-i} + \sum_{k>i} 2t_i^{i-k} < 3 \sum_{k=1}^\infty t^{-k} = \frac{3}{t-1} \leq 1,$$

using that $t \geq 4$. It follows that the linkset $L$ is SINR-feasible. We thus obtain a lower bound on the performance ratio of any schedule using $\phi$ of $n = \Omega(\log \log \Delta)$.

Consider now the complementary instance, where the direction or the role of senders and receivers, has been reversed. Then, nearly identical computation shows that any function that grows no slower than $\Omega((x/x')^\epsilon)$ can also only schedule a single link in a single slot. On the other hand, using power assignment $f(\ell_v) = \log \ell_v$, shows that the construction is SINR-feasible, giving the same $\Omega(\log \log \Delta)$ lower bound.

Finally, we can combine the two constructions into a single instance that is hard to schedule for all well-behaved oblivious power functions, by taking disjoint copies that are sufficiently separated in space. 

$\square$
5 Conclusions

From a practical perspective, it would be interesting if the logarithmic factor could be removed, giving a $O(\log \log \Delta)$-approximation. Alternatively, non-oblivious power strategies that could be implemented in a distributed setting would be highly desirable.

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A Approximating Weighted Capacity on $k$-$\pi$-Inductive Graphs

We apply the algorithm of Ye and Borodin [39] for Weighted Independent Set in sequentially $k$-independent graphs to the Weighted Maximum II-subgraph problem in $k$-$\pi$-inductive graphs.

**Theorem A.1** [39] Let $\pi$ be a polynomially-time verifiable property such that any independent set satisfies $\pi$. Then, the Weighted Maximum $\pi$-Subgraph problem is $k$-approximable on graphs that are $k$-$\pi$-inductive.

**Proof:** Let $G = (V, E)$ be a $k$-$\pi$-inductive graph with weight function $w : V \to \mathbb{R}$. The algorithm maintains a stack $S$ of nodes, first pushing the nodes onto the stack, and then popping them off.

Let $v_1, v_2, \ldots, v_n$ be the nodes in the $k$-$\pi$-inductive order.

1. Initialize $\hat{w}(v_i) \leftarrow w(v_i)$
2. for $i \leftarrow 1$ to $n$ do  
   // Push phase
   if $(\hat{w}(v_i) > 0)$
   push $v_i$ on $S$
   for each neighbor $v_j \in N(v_i) \cap \{v_{i+1}, \ldots, v_n\}$ do
   Subtract $\hat{w}(v_i)$ from $\hat{w}(v_j)$

3. $A \leftarrow \emptyset$
4. while ($S$ is not empty) do  
   // Pop phase
   $u \leftarrow \text{pop}(S)$
   if ($u \cup A$ is a $\pi$-set)
   add $u$ to $A$

output $A$

Let $A$ be the output of the algorithm and $O$ be an optimal solution. Let $S$ be the set of vertices in the stack at the end of the push phase and $S_i$ be the contents of the stack when $v_i$ is being considered in the push phase.

We first prove that the stack algorithm achieves at least the total weight of the stack. For a node $v_i$, let $\hat{w}(v_i)$ denote the final value of $\hat{w}(v_i)$, which it attains before iteration $i$. Then, it holds for each node $v_i$ that

$$w(v_i) = \hat{w}(v_i) + \sum_{v_j \in S_i \cap N(v_i)} \hat{w}(v_j).$$  \hfill (8)

If we sum up for all $v_i \in A$, we have

$$\sum_{v_i \in A} w(v_i) = \sum_{v_i \in A} \hat{w}(v_i) + \sum_{v_i \in A} \sum_{v_j \in S_i \cap N(v_i)} \hat{w}(v_j) \geq \sum_{v_i \in S} \hat{w}(v_i),$$  \hfill (9)

where the second equality holds because for any $v_i \in S$, we either have $v_i \in S_i \cap N(v_i)$ for some $v_i \in A$, or we have $v_i \in A$.

Now we prove that the optimal solution achieves at most $k$ times the weight of the stack. If we sum Equation (8) up for all $v_i \in O$, we have

$$\sum_{v_i \in O} w(v_i) \leq \sum_{v_i \in O} \hat{w}(v_i) + \sum_{v_i \in O} \sum_{v_j \in S_i \cap N(v_i)} \hat{w}(v_j) \leq k \sum_{v_i \in S} \hat{w}(v_i),$$  \hfill (10)

where the second inequality holds because when we sum up for all $v_i \in O$, each of the terms $\hat{w}(v_i)$ for any vertex $v_i \in S$ can appear at most $k$ times, since the ordering $v_1, v_2, \ldots, v_n$ is a $k$-$\pi$-inductive ordering. Combining (9) and (10), we have

$$\sum_{v_i \in O} w(v_i) \leq k \sum_{v_i \in A} w(v_i).$$
