The multicomponent 2D Toda hierarchy: discrete flows and string equations

Manuel Mañas, Luis Martínez Alonso and Carlos Álvarez-Fernández

Departamento de Física Teórica II, Universidad Complutense, 28040-Madrid, Spain
E-mail: manuel.manas@fis.ucm.es

Received 16 September 2008, in final form 3 March 2009
Published 21 April 2009
Online at stacks.iop.org/IP/25/065007

Abstract
The multicomponent 2D Toda hierarchy is analyzed through a factorization problem associated with an infinite-dimensional group. A new set of discrete flows is considered and the corresponding Lax and Zakharov–Shabat equations are characterized. Reductions of block Toeplitz and Hankel bi-infinite matrix types are proposed and studied. Orlov–Schulman operators, string equations and additional symmetries (discrete and continuous) are considered. The continuous-discrete Lax equations are shown to be equivalent to a factorization problem as well as to a set of string equations. A congruence method to derive site-independent equations is presented and used to derive equations in the discrete multicomponent KP sector (and also for its modification) of the theory as well as dispersive Whitham equations.

1. Introduction
This paper revisits the multicomponent 2D Toda hierarchy [32] from the point of view of the factorization problem associated with an infinite-dimensional group. Our main motivation is the recent discovery [3] of underlying integrable structures of the multicomponent type in the theory of multiple orthogonal polynomials which is in turn connected to models of non-intersecting Brownian motions. Having in mind the fruitful applications of the Toda hierarchy to the theory of orthogonal polynomials and to the Hermitian random matrix model (see for instance [15, 23]), it is expected that the formalism of multicomponent integrable hierarchies can be similarly applied to the study and characterization of multiple orthogonal polynomials and non-intersecting Brownian motions. In particular, the semiclassical (dispersionless) limit of multicomponent integrable hierarchies should be relevant to the analysis of large $N$ type limits; see for instance [24]. An important piece of the technique required for these applications was recently provided by Takasaki and Takebe [29, 30]. Indeed, they proved that the universal Whitham hierarchy (genus 0 case) [17] can be obtained as a particular dispersionless limit of the multicomponent KP hierarchy.
The applications of the Toda hierarchy to the characterization of semiclassical limits make an essential use of the notion of string equations [10–12, 15, 23]. As is known, orthogonal polynomials satisfy string equations of the form

\[ \partial_z P_N(z) = A P_N(z), \quad z P_N(z) = B P_N(z), \quad [B, A] = 1, \]  

where \( A \) and \( B \) are finite-difference operators in the discrete index \( N \). These equations are very useful for the derivation of the large \( N \) asymptotics of the Hermitian random matrix model. The point is that the explicit form of the operators \( A \) and \( B \) can be found from the string equations satisfied by the Lax and Orlov–Schulman operators of the underlying solution of the Toda hierarchy (see for instance [27] and [23]). In recent years, the formalism of string equations for dispersionless integrable hierarchies [28] has been much developed [21, 35] but, to our knowledge, a similar formalism for dispersive multicomponent integrable hierarchies is not yet available. One of the main goals of this paper is to extend the formalism of string equations to multicomponent 2D Toda hierarchies. In this sense the consideration of factorization problems for these hierarchies turns to be of great help in order to introduce basic ingredients such as discrete flows, Orlov–Schulman operators and additional symmetries.

The theory of the multicomponent KP hierarchy is discussed in length in the papers [4, 16]; see also [22] for its applications to geometric nets of the conjugate type. In [32], it was noted that \( r \) functions of a \( 2N \)-multicomponent KP provide solutions to the \( N \)-multicomponent Toda hierarchy. The introduction of integer parameters in the multicomponent KP hierarchy goes back to [8] and the corresponding discrete flows, which are used in two different ways in [4, 16], are essential for the derivation of the dispersionless Whitham hierarchy from the multicomponent KP hierarchy [29–31]. In the present paper, we introduce a set of discrete flows for the multicomponent 2D Toda hierarchy. Its role in the formulation of the corresponding dispersionless limits is discussed in [20].

The layout of the paper is as follows. In section 1, we introduce a factorization problem in a Lie group as that presented in [32]:

\[ g = W^{-1} \bar{W}, \]

which involves initial data \( g \) and two wave operators \( W \) and \( \bar{W} \) respectively. This factorization problem is rooted in the ideas used for the KP case in [1, 26], for the so-called discrete KP hierarchy. Then, in section 2 we derive the continuous and discrete Lax equations for the multicomponent 2D Toda hierarchy. We note that in our discussion the set of discrete flows, which to our knowledge were not considered before for this hierarchy, are formulated in equal footing to the continuous flows. We also show some examples of members of the hierarchy and, in particular, multicomponent equations of the Toda type involving partial difference operators only or combined partial difference and partial derivatives. We end this section with the formulation of several classes of reductions of the multicomponent 2D Toda hierarchy involving bi-infinite block Toeplitz and Hankel matrices. The consideration of these types of reductions is motivated by their relevance in integrable hierarchies such as the infinite Toda hierarchy [2] or the Ablowitz–Ladik lattice hierarchy [6]. For some reductions, we characterize the solutions of the hierarchy which are periodic in the discrete variables. Moreover, for the Hankel case we get generalizations of the bigraded reduction (see [7]) associated with extended flows of the one-component 1D Toda hierarchy [13].

In section 3 we formulate the theory of string equations for the multicomponent 2D Toda hierarchy. We start by defining the Orlov–Schulman operator [25] and then we derive its Lax equations from the factorization problem introduced in section 1. We also show how the Lax equations imply in turn the factorization problem. In this way we establish the equivalence between the factorization problem and the extended Lax formulation, involving discrete flows and the Orlov–Schulman operator, of the multicomponent 2D Toda hierarchy.
We also prove the equivalence between the extended Lax formulation and a particular type of string equations for the multicomponent 2D Toda hierarchy. This generalizes the result for the one-component case established in [28]. Finally, we use the factorization problem and the canonical pair of Lax and Orlov–Schulman operators to provide a natural formulation of the additional symmetries of the multicomponent 2D Toda hierarchy. Moreover, we prove that the string equations satisfied by the Lax and Orlov–Schulman operators are determined by the symmetries of the initial condition \( g \) of the factorization problem. This formalism can be applied to characterize string equations (1) for families of multiple orthogonal polynomials associated with matrix Riemann–Hilbert problems [33] (see for instance [24] for the cases of multiple orthogonal polynomials of types I and II).

The paper ends with two appendices. In the first appendix, the congruence method for deriving \( n \)-independent equations is shown. It is applied to get the main equations of the discrete multicomponent KP hierarchy: \( N \)-wave equations, Darboux equations and multiquadrilateral lattice equations [9]. We also use this method to formulate the dispersive Whitham equations in terms of scalar Lax and Orlov–Schulman operators, which constitute the starting point for the discussion of the dispersionless limits of the multicomponent 2D Toda hierarchy. Finally, the second appendix contains the proofs of the main propositions of the paper.

1.1. Lie algebra setting

In this paper, we only consider formal series expansions in the Lie group theoretic setup without any assumption on their convergency. We also remark that along the paper, we use the following notations. For given Lie algebras \( g_1 \subset g_2 \) and \( X, Y \in g_2 \); then \( X = Y + g_1 \) means \( X - Y \in g_1 \). For any Lie groups \( G_1 \subset G_2 \) and \( a, b \in G_2 \); then \( a = G_1 \cdot b \) stands for \( a \cdot b^{-1} \in G_1 \). Let \( \{E_{kl}\}_{k,l=1}^{N} \) be the standard basis \( (E_{kl})_{k,l} = \delta_{ll'}\delta_{kk'} \) of \( M_N(\mathbb{C}) \) and \( I_N \) denote the identity matrix in \( M_N(\mathbb{C}) \). We also denote the algebra unit as 1.

If \( M_N(\mathbb{C}) \) denotes the associative algebra of complex \( N \times N \) matrices, we will consider the linear space of sequences

\[
\begin{align*}
\mathbb{Z} & \longrightarrow M_N(\mathbb{C}) \\
n & \longmapsto f(n).
\end{align*}
\]

The shift operator \( \Lambda \) acts on these sequences as \( (\Lambda f)(n) := f(n+1) \). A sequence \( X: \mathbb{Z} \rightarrow M_N(\mathbb{C}) \) acts by left multiplication in this space of sequences, and therefore we may consider expressions of the type \( X\Lambda^j \), where \( X = X(n) \) is a sequence which acts by left multiplication: \( (X\Lambda^j)(f)(n) := X(n) \cdot f(n+j) \).

Moreover, defining the product \( (X(n)\Lambda^j) \cdot (Y(n)\Lambda^k) := X(n)Y(n+i)\Lambda^{i+j} \) and extending it linearly we have that the set \( g \) of Laurent series in \( \Lambda \) is an associative algebra, which under the standard commutator is a Lie algebra. Observe that \( g \) can be thought of either as \( M_\mathbb{Z}(M_N(\mathbb{C})) \), i.e. bi-infinite matrices with \( M_N(\mathbb{C}) \) coefficients, or as \( M_N(M_\mathbb{Z}(\mathbb{C})) \), i.e. \( N \times N \) matrices with coefficient bi-infinite matrices.

This Lie algebra has the following important splitting:

\[
g = g_+ + g_-, \tag{2}
\]

where

\[
g_+ = \left\{ \sum_{j \geq 0} X_j(n)\Lambda^j, X_j(n) \in M_N(\mathbb{C}) \right\}, \quad g_- = \left\{ \sum_{j < 0} X_j(n)\Lambda^j, X_j(n) \in M_N(\mathbb{C}) \right\},
\]

are Lie subalgebras of \( g \) with trivial intersection.
1.2. The Lie group and the factorization problem

The group of linear invertible elements in $g$ will be denoted by $G$ and has $g$ as its Lie algebra; then the splitting (2) leads us to consider the following factorization of $g \in G$:

$$g = g_+^{-1} \cdot g_+, \quad g_\pm \in G_\pm,$$

where $G_\pm$ have $g_\pm$ as their Lie algebras. Explicitly, $G_+$ is the set of invertible linear operators of the form $\sum_{j\geq 0} g_j(n)\Lambda^j$, while $G_-$ is the set of invertible linear operators of the form $1 + \sum_{j<0} g_j(n)\Lambda^j$.

An alternative factorization is the Gauss factorization:

$$g = \hat{g}^{-1} \cdot \hat{g}_+, \quad \hat{g}_\pm \in \hat{G}_\pm,$$

where $\hat{G}_+$ is the set of invertible linear operators of the form $\hat{g}_{0,+}(n) + \sum_{j>0} \hat{g}_j(n)\Lambda^j$, with $\hat{g}_{0,+} : \mathbb{Z} \rightarrow \text{GL}(N, \mathbb{C})$ being an invertible upper triangular matrix, while $\hat{G}_-$ is the set of invertible linear operators of the form $\hat{g}_{0,-}(n)^{-1} + \sum_{j<0} \hat{g}_j(n)\Lambda^j$ with $\hat{g}_{0,-} : \mathbb{Z} \rightarrow \text{GL}(N, \mathbb{C})$, such that $\hat{g}_{0,-} = I_N + A$. $A$ being a strictly lower triangular matrix in $M_N(\mathbb{C})$. If the factorization (4) exists, then (3) will also exist by defining $g_+ = \hat{g}_{0,+} \cdot \hat{g}_+$, $g_- = \hat{g}_{0,-} \cdot \hat{g}_-$.

The elements $g$ with a factorization (4) are said to belong to the big cell [4]; hence, the factorization can be considered only locally. Thus, we will consider elements $g$ in the big cell so that the factorization (3) holds, avoiding the generation of additional problems connected with these local aspects.

Now we introduce two sets of indices, $S = \{1, \ldots, N\}$ and $\tilde{S} = \{\tilde{1}, \ldots, \tilde{N}\}$, of the same cardinality $N$. In what follows we will use letters $k, l$ and $\tilde{k}, \tilde{l}$ to denote elements in $S$ and $\tilde{S}$, respectively. Furthermore, we will use letters $a, b, c$ to denote elements in $S := S \cup \tilde{S}$.

We define the following operators $W_0, \tilde{W}_0 \in G$:

$$W_0 := \sum_{k=1}^{N} E_{\tilde{k}k} \Lambda^k s_k e^{\sum_{l=0}^{\infty} t_{kl}\Lambda^l},$$

$$\tilde{W}_0 := \sum_{k=1}^{N} \tilde{E}_{\tilde{k}k} \Lambda^{-k} \bar{s}_k e^{\sum_{l=0}^{\infty} \tilde{t}_{k\tilde{l}}\Lambda^{-l}},$$

where $s_k, \bar{s}_k, t_{kl}, \tilde{t}_{k\tilde{l}} \in \mathbb{C}$ are deformation parameters, which in the following will play the role of discrete and continuous times, respectively.

The factorization problem. Given an element $g \in G$, in the big cell, and a set of deformation parameters $s = (s_k)_{k \in S}, t = (t_{kl})_{k \in S, l \in \mathbb{N}_{\geq 1}, N_{s_1} = \{0, 1, 2, \ldots\}, N_{s_{-1}} = \{1, 2, \ldots\}$, we consider the factorization problem

$$W_0 \cdot g \cdot \tilde{W}_0^{-1} = S(s, t)^{-1} \cdot \bar{S}(s, t), \quad S \in G_- \text{ and } \bar{S} \in G_+.$$  

We will confine our analysis to the zero charge sector:

$$|s| := \sum_{k \in S} s_k = 0,$$

and consider small enough values of the continuous times. Observe that normally, but not always, the $t_{0k}$ times are disregarded. The reason is the triviality of factorization associated with these deformations. In fact, if we have a solution to the factorization problem for $t_{0k} = 0$, with factors $S_0$ and $\bar{S}_0$, then the factors corresponding to the factorization with arbitrary $t_{0k}$ are $S = \exp \left( \sum_{k=1}^{N} t_{0k} E_{\tilde{k}k} \right) S_0 \exp \left( - \sum_{k=1}^{N} t_{0k} E_{\tilde{k}k} \right)$ and $\bar{S} = \exp \left( \sum_{k=1}^{N} t_{0k} E_{\tilde{k}k} \right) \bar{S}_0$. The reason to consider them here is due to the reductions we will study later.
At this point, we discuss some relevant subalgebras and subgroups which will play an important role hereafter. First, we note that an operator \( A = \sum_{j \in \mathbb{Z}} A_j(n) \Lambda^j \) commutes with \( \Lambda \) if and only if the coefficients \( A_j \) do not depend on \( n \). Thus, the centralizer of \( \Lambda \) is 
\[ \mathfrak{z}_\Lambda := \{ A \in \mathfrak{g} : [A, \Lambda] = 0 \} = \{ \sum_{j \in \mathbb{Z}} A_j \Lambda^j, A_j \in M_N(\mathbb{C}) \}. \]
Observe that \( \mathfrak{z}_\Lambda \subset \mathfrak{g} \) is a Lie subalgebra as now \( \Lambda \) commutes with the matrix coefficients of the Laurent expansions.

Another interpretation is that we have block bi-infinite Toeplitz or Laurent operators \([5]\).

A particular Abelian subalgebra \( \mathfrak{h} \) of \( \mathfrak{z}_\Lambda \) is given by the centralizer of \( C(\Lambda, E_{kk})_{k=1}^N \), i.e. \( \mathfrak{h} := \{ A \in \mathfrak{g} : [A, \Lambda] = [A, E_{kk}] = 0, k = 1, \ldots, N \} = \{ \sum_{j \in \mathbb{Z}} A_j \Lambda^j, A_j \in \text{diag}(N, \mathbb{C}) \} \), where \( \text{diag}(N, \mathbb{C}) \) is the subalgebra of diagonal matrices of \( M_N(\mathbb{C}) \). Thus, \( \mathfrak{h} \) is the set of Laurent series in \( \Lambda \) with diagonal \( n \)-independent coefficients. There are two important subgroups: \( G_- \cap \mathfrak{z}_\Lambda = \{ 1 + c_1 \Lambda^{-1} + c_2 \Lambda^{-2} + \cdots, c_j \in M_N(\mathbb{C}) \} \) and \( G_+ \cap \mathfrak{z}_\Lambda = \{ c_0 + c_1 \Lambda + c_2 \Lambda^2 + \cdots, c_0 \in \text{GL}(N, \mathbb{C}), c_j \in M_N(\mathbb{C}), j \geq 1 \} \). Finally, we have the corresponding Abelian Lie subgroups \( H := G \cap \mathfrak{h} \) and \( H_\pm := G_\pm \cap \mathfrak{h} \) and \( W_0, \bar{W}_0 \) take values in \( H \).

We shall denote by \( n \in \mathfrak{g} \) the multiplication operator by the sequence \( [nI_N]_{n \in \mathbb{Z}} \), i.e.
\[ n[X(n)]_{n \in \mathbb{Z}} = [nX(n)]_{n \in \mathbb{Z}}. \tag{8} \]
Observe that \([A, n] = \Lambda\) and that for any \( X \in \mathfrak{g} \), we have \( X = \sum_{i \geq 0} X_{ij} n^i \Lambda^j, X_{ij} \in M_N(\mathbb{C}) \). This expansion follows from the assumption that \( X_j(n) = X_{0j} + X_{1j} n + \cdots \). The set of operators commuting with \( \Lambda, n \) and \( E_{kk}, k = 1, \ldots, N \), is given by \( \{ A \in \mathfrak{g} : [A, \Lambda] = [A, n] = [A, E_{kk}] = 0, k = 1, \ldots, N \} = \text{diag}(N, \mathbb{C}) \).

2. Lax and Zakharov–Shabat equations

2.1. Dressing procedure. Lax and C operators

We now introduce important elements for the following of this paper.

**Definition 1.** We define the dressing operators \( W, \bar{W} \) as follows:
\[ W := S \cdot W_0, \quad \bar{W} := \bar{S} \cdot W_0. \tag{9} \]

In terms of these dressing operators, the factorization problem \((7)\) in \( G \) reads as
\[ W \cdot \mathfrak{g} = \bar{W}. \tag{10} \]

Observe the expansions of the factors \( S, \bar{S}:
\[ S = I_N + \varphi_1(n) \Lambda^{-1} + \varphi_2(n) \Lambda^{-2} + \cdots \in G_-, \quad \bar{S} = \bar{\varphi}_0(n) + \bar{\varphi}_1(n) \Lambda + \bar{\varphi}_2(n) \Lambda^2 + \cdots \in G_+. \tag{11} \]

Sometimes we will use the notation
\[ \beta := \varphi_1, \quad e^\beta := \bar{\varphi}_0. \]

We have the following expressions:
\[ W = (I_N + \varphi_1(n) \Lambda^{-1} + \varphi_2(n) \Lambda^{-2} + \cdots) \cdot \left( \sum_{k=1}^N E_{kk} \Lambda^k \exp \left( \sum_{j=0}^{\infty} t_{jk} \Lambda^j \right) \right) \]
\[ \bar{W} = (\bar{\varphi}_0(n) + \bar{\varphi}_1(n) \Lambda + \bar{\varphi}_2(n) \Lambda^2 + \cdots) \cdot \left( \sum_{k=1}^N E_{kk} \Lambda^{-k} \exp \left( \sum_{j=0}^{\infty} t_{jk} \Lambda^{-j} \right) \right). \tag{12} \]
Other important objects are

**Definition 2.** The Lax operators \( L, \tilde{L}, C_{kl}, \tilde{C}_{kl} \in g \) are given by

\[
L := W \cdot \Lambda \cdot W^{-1}, \quad \tilde{L} := \tilde{W} \cdot \Lambda \cdot \tilde{W}^{-1}, \quad C_{kl} := W \cdot E_{kl} \cdot W^{-1}, \quad \tilde{C}_{kl} := \tilde{W} \cdot E_{kl} \cdot \tilde{W}^{-1}, \quad C_{kl} := S \cdot E_{kl} \cdot S^{-1}, \quad \tilde{C}_{kl} := \tilde{S} \cdot E_{kl} \cdot \tilde{S}^{-1}.
\] (13)

Note that in the above definitions of \( L, \tilde{L}, C_{kk} \) and \( \tilde{C}_{kk} \)—as \( W_0, \tilde{W}_0 \in H \)—we may replace the dressing operators \( W \) and \( \tilde{W} \) by \( S \) and \( \tilde{S} \), respectively. A straightforward calculation yields

**Proposition 1.**

1. The following relations hold:

\[
C_{kl} = L^{u_{n-1}} \exp \left( \sum_{j=0}^{\infty} (t_{jk} - t_{jl}) L^j \right) C_{kl},
\]

\[
\tilde{C}_{kl} = \tilde{L}^{u_{n-1} + \bar{t}_{n-1}} \exp \left( \sum_{j=1}^{\infty} (t_{jk} - t_{jl}) \tilde{L}^{-j} \right) \tilde{C}_{kl}.
\]

2. The Lax operators have the following expansions:

\[
L = \Lambda + u_1(n) + u_2(n) \Lambda^{-1} + \cdots, \quad \tilde{L}^{-1} = \tilde{u}_0(n) \Lambda^{-1} + \tilde{u}_1(n) + \tilde{u}_2(n) \Lambda + \cdots,
\]

\[
C_{kl} = E_{kl} + C_{kl,1}(n) \Lambda^{-1} + C_{kl,2}(n) \Lambda^{-2} + \cdots,
\]

\[
\tilde{C}_{kl} = \tilde{C}_{kl,0}(n) + \tilde{C}_{kl,1}(n) \Lambda + \tilde{C}_{kl,2}(n) \Lambda^2 + \cdots.
\] (16)

3. These operators fulfill

\[
I_N = \sum_{k=1}^{N} C_{kk}, \quad \tilde{I}_N = \sum_{k=1}^{N} \tilde{C}_{kk}, \quad C_{kl} C_{k'l'} = \delta_{k'k} C_{kl}, \quad C_{kl} L = LC_{kl}, \quad \tilde{C}_{kl} \tilde{C}_{k'l'} = \delta_{k'k} \tilde{C}_{kl}, \quad \tilde{C}_{kl} \tilde{L} = \tilde{L} \tilde{C}_{kl}.
\] (17)

2.2. Lax and Zakharov–Shabat equations

In this section, we will use the factorization problem (10) to derive two sets of equations: Lax equations and Zakharov–Shabat equations, and we will show that they all are equivalent. Let us first introduce some convenient notation.

**Definition 3.**

1. \( \partial_{j_{a}} := \frac{\partial}{\partial t_{j_{a}}} \).

2. The zero-charge shifts \( T_K \) for \( K = (a, b) \) are defined as follows:

\[
s_a \rightarrow s_a + 1, \quad s_b \rightarrow s_b - 1,
\]

and all the other discrete variables remain unchanged.
\[ \theta_{ja} := \partial_{ja} W_0 \cdot W_0^{-1}, \quad \tilde{\theta}_{ja} := \tilde{\partial}_{ja} \tilde{W}_0 \cdot \tilde{W}_0^{-1}, \]
\[ q_K := T_K W_0 \cdot W_0^{-1}, \quad \tilde{q}_K := T_K \tilde{W}_0 \cdot \tilde{W}_0^{-1}, \quad K = (a, b). \]

\[ C_{aa} := W \pi_a W^{-1}, \quad \tilde{C}_{aa} := \tilde{W} \tilde{\pi}_a \tilde{W}^{-1}, \]
\[ R_{ja} := \tilde{\partial}_{ja} \tilde{W}_0 \cdot \tilde{W}_0^{-1}, \quad \tilde{R}_{ja} := \tilde{\partial}_{ja} \tilde{W}_0 \cdot \tilde{W}_0^{-1}, \]
\[ U_K := W q_K W^{-1}, \quad \tilde{U}_K := \tilde{W} \tilde{q}_K \tilde{W}^{-1}. \]

\[ B_{ja} := R_{ja} - (R_{ja} - \tilde{R}_{ja})_+ = \tilde{R}_{ja} + (R_{ja} - \tilde{R}_{ja})_+, \quad (R_{ja} - \tilde{R}_{ja})_\pm \in \mathfrak{g}, \]
\[ \omega_K := (\mathfrak{u}_k \cdot \tilde{U}_K^{-1})_+ \cdot U_K = (\mathfrak{u}_k \cdot \tilde{U}_K^{-1})_+ \cdot \tilde{U}_K \in G, \quad (\mathfrak{u}_k \tilde{U}_K^{-1})_\pm \in \mathfrak{g}_ \pm. \]

Note that if
\[ \pi_a := \begin{cases} E_{kk}, & a = k \in \mathcal{S}, \\ 0, & a \in \mathfrak{s}, \end{cases} \quad \tilde{\pi}_a := \begin{cases} 0, & a \in \mathcal{S}, \\ E_{kk}, & a \in \mathfrak{s} \text{ and } a = \bar{k} \text{ for some } k \in \mathcal{S}, \end{cases} \]
we can write
\[ \theta_{ja} = \pi_a \Lambda^j, \quad \tilde{\theta}_{ja} = \tilde{\pi}_a \Lambda^{-j}, \quad q_K = \mathbb{I}_N + \pi_a (\Lambda - \mathbb{I}_N) + \pi_b (\Lambda^{-1} - \mathbb{I}_N), \]
\[ \tilde{q}_K = \mathbb{I}_N + \tilde{\pi}_a (\Lambda^{-1} - \mathbb{I}_N) + \tilde{\pi}_b (\Lambda - \mathbb{I}_N), \quad K = (a, b). \]

Observe that all the shift operators preserve the zero charge sector and form a commutative group
\[ T_K T_{K'} = T_{K'} T_K, \]
\[ T_{(a,b)} T_{(b,a)} = \text{id}, \]
satisfying the following cohomological relations:
\[ T_{(a,b)} T_{(b,c)} T_{(c,a)} = \text{id}. \]

**Proposition 2.** Relations (21)–(23) are equivalent to
\[ T_{(a,b)} T_{(b,c)} T_{(a,c)} = \text{id}, \]
where \( T_{(a,a)} = \text{id}. \)

**Proof.** See appendix B.

Also note that \( B_{jk} = (C_{kk} L^j)_+, \quad B_{jk} = (C_{kk} L^{-j})_- \) and that (19) and (20) give
\[ \omega_K = \pi_a \Lambda + a_k + \tilde{a}_k \Lambda^{-1}, \]
for some matrix sequences \( a_K(n) \) and \( \tilde{a}_K(n) \).

The factorization problem (7) implies that the partial differential equations
\[ \partial_{ja} W \cdot W^{-1} = \partial_{ja} S \cdot S^{-1} + S \cdot \theta_{ja} \cdot S^{-1} = \partial_{ja} \tilde{S} \cdot \tilde{S}^{-1} + \tilde{S} \cdot \tilde{\theta}_{ja} \cdot \tilde{S}^{-1} = \partial_{ja} \tilde{W} \cdot \tilde{W}^{-1} \]
and partial difference equations
\[ T_K W \cdot W^{-1} = T_K S \cdot q_K \cdot S^{-1} = T_K \tilde{S} \cdot \tilde{q}_K \cdot \tilde{S}^{-1} = T_K \tilde{W} \cdot \tilde{W}^{-1} \]
hold.

From the previous proposition, we derive the following linear systems for the dressing operators and Lax equations for the Lax operators, and its compatibility conditions.
Theorem 1.

(1) The dressing operators are subject to

\[ \partial_{ja} W = B_{ja} \cdot W, \quad \partial_{ja} \bar{W} = B_{ja} \cdot \bar{W}, \quad T K W = \omega_K \cdot W, \quad T K \bar{W} = \omega_K \cdot \bar{W}. \]

(2) The Lax equations

\[ \partial_{ja} L = [B_{ja}, L], \quad \partial_{ja} \bar{L} = [B_{ja}, \bar{L}], \]
\[ \partial_{ja} C_{kk} = [B_{ja}, C_{kk}], \quad \partial_{ja} \bar{C}_{kk} = [B_{ja}, \bar{C}_{kk}], \]
\[ T K L = \omega_K \cdot L \cdot \omega_K^{-1}, \quad T K \bar{L} = \omega_K \cdot \bar{L} \cdot \omega_K^{-1}, \]
\[ T K C_{kk} = \omega_K \cdot C_{kk} \cdot \omega_K^{-1}, \quad T K \bar{C}_{kk} = \omega_K \cdot \bar{C}_{kk} \cdot \omega_K^{-1}. \]

are satisfied.

(3) The following Zakharov–Shabat equations hold:

\[ \partial_{ja} B_{ib} - \partial_{ib} B_{ja} + [B_{ib}, B_{ja}] = 0, \]
\[ T K B_{ja} = \partial_{ja} \omega_K \cdot \omega_K^{-1} + \omega_K \cdot B_{ja} \cdot \omega_K^{-1}, \]
\[ T K \omega_K \cdot \omega_K^{-1} = T K \omega_K \cdot \omega_K^{-1}. \]

Proof.

(1) First, observe that (26) implies \( \partial_{ja} S \cdot S^{-1} + R_{ja} = \partial_{ja} S \cdot S^{-1} + R_{ja} \), and therefore \( \partial_{ja} S \cdot S^{-1} = -(R_{ja} - R_{ja})_+ \in g_- \) and \( \partial_{ja} \bar{S} \cdot \bar{S}^{-1} = (R_{ja} - R_{ja})_+ \in g_+ \) so that again using (26), we get

\[ \partial_{ja} W \cdot W^{-1} = -(R_{ja} - R_{ja})_+ + R_{ja} = B_{ja} = (R_{ja} - R_{ja})_+ + R_{ja} = \partial_{ja} \bar{W} \cdot \bar{W}^{-1}. \]

Equation (27) implies

\[ T K W \cdot W^{-1} = T K S \cdot q_K \cdot S^{-1} = T K S \cdot S^{-1} \cdot \bar{q}_K = T K \bar{S} \cdot \bar{q}_K \cdot \bar{S}^{-1} = T K \bar{W} \cdot \bar{W}^{-1} \]

so that \( (T K S \cdot S^{-1})^{-1} \cdot (T K \bar{S} \cdot \bar{S}^{-1}) = \bar{q}_K \cdot \bar{q}_K^{-1} \) and we conclude \( T K S \cdot S^{-1} = (\bar{q}_K \cdot \bar{q}_K^{-1})_+ \in G_- \) and \( T K \bar{S} \cdot \bar{S}^{-1} = (\bar{q}_K \cdot \bar{q}_K^{-1})_+ \in G_+ \) which introduced back in (36) gives

\[ T K W \cdot W^{-1} = T K S \cdot q_K \cdot S^{-1} = (\bar{q}_K \cdot \bar{q}_K^{-1})_+ \cdot \bar{q}_K = \omega_K \]
\[ = (\bar{q}_K \cdot \bar{q}_K^{-1})_+ \cdot \bar{q}_K = T K \bar{S} \cdot \bar{q}_K \cdot \bar{S}^{-1} = T K \bar{W} \cdot \bar{W}^{-1}. \]

(2) From definition (13), we get

\[ \partial_{ja} L = [\partial_{ja} W \cdot W^{-1}, L], \quad \partial_{ja} \bar{L} = [\partial_{ja} \bar{W} \cdot \bar{W}^{-1}, \bar{L}], \]
\[ \partial_{ja} C_{kk} = [\partial_{ja} \bar{W} \cdot \bar{W}^{-1}, C_{kk}], \quad \partial_{ja} \bar{C}_{kk} = [\partial_{ja} \bar{W} \cdot \bar{W}^{-1}, \bar{C}_{kk}], \]
\[ T K L = (T K W \cdot W^{-1}) \cdot L \cdot (T K W \cdot W^{-1})^{-1}, \]
\[ T K \bar{L} = (T K \bar{W} \cdot \bar{W}^{-1}) \cdot \bar{L} \cdot (T K \bar{W} \cdot \bar{W}^{-1})^{-1}, \]
\[ T K C_{kk} = (T K W \cdot W^{-1}) \cdot C_{kk} \cdot (T K W \cdot W^{-1})^{-1}, \]
\[ T K \bar{C}_{kk} = (T K \bar{W} \cdot \bar{W}^{-1}) \cdot \bar{C}_{kk} \cdot (T K \bar{W} \cdot \bar{W}^{-1})^{-1}, \]

and using (28) and (29) we find (30) and (31), respectively.
The compatibility of (28) and (29) implies (32)–(34).

Also observe that the trivial flows $t_0, k = 1, \ldots, N$, are immediately integrated and if $L_0, \bar{L}_0, C_{kl}$ and $\bar{C}_{kl}$ are the Lax and $C$ operators corresponding to $t_0 = 0$ for arbitrary $t_0$ we only need to conjugate these operators with $\exp \left( \sum_{k=1}^N E_{kk} t_0 \right)$.

The compatibility conditions (32)–(34) for operators $B_{ja}$ and $\omega_K$ formally imply the local existence of a matrix potential $\xi$ such that $B_{ja} = \partial_{ja} \xi \cdot \xi^{-1}$ and $\omega_K = \bar{T}_K \xi \cdot \xi^{-1}$. Moreover, any operator $\xi$ generates a gauge transformation so that $B_{ja} \rightarrow \partial_{ja} \xi \cdot \xi^{-1} + \xi \cdot B_{ja} \cdot \xi^{-1}$ and $\omega_K \rightarrow \bar{T}_K \xi \cdot \omega_K \cdot \xi^{-1}$, providing new solutions to (32)–(34).

Proposition 3. The relations
\[(T(a,b) \omega(b,c)) \omega(a,b) = (T(b,c) \omega(a,b)) \omega(b,c) = \omega(a,c)\] (38)
and the compatibility conditions (34) are equivalent.

Proof. See appendix B.

We have seen that the Lax equations (30) and (31) and Zakharov–Shabat equations (32)–(34) appear as a consequence of the factorization problem. The compatibility conditions for the Lax equations are satisfied if the Zakharov–Shabat equations hold. It is a standard fact in the theory of integrable systems that by construction, the Lax equations imply the Zakharov–Shabat equations and therefore the system is compatible. In [32] the fact for the differential equations (not the difference nor the difference-differential equations) involved in the multicomponent 2D Toda hierarchy is proven, that is, (30) \Rightarrow (32). Here, we give an extended proof in order to include the continuous–discrete and discrete–discrete cases.

Proposition 4. Let $\{L, C_{kl}\}_{k=1}^N \subset \mathfrak{g}$ and $\{\bar{L}, \bar{C}_{kl}\}_{k=1}^N \subset \mathfrak{g}$ be two sets, each of them composed of commuting operators, consider functions $R_{ja} \in \mathfrak{g}, U_K \in G$ of $L, C_{11}, \ldots, C_{kk}$ and $\bar{R}_{ja} \in \mathfrak{g}, \bar{U}_K \in G$ of $\bar{L}, \bar{C}_{11}, \ldots, \bar{C}_{kk}$, and define $B_{ja}$ and $\omega_K$ according to (20); then the Lax equations (30) and (31) imply the Zakharov–Shabat equations (32)–(34).

Proof. See appendix B.

2.3. The multicomponent Toda equations

Here we write down some of the nonlinear partial differential-difference equations appearing as a consequence of the factorization problem (10). From (35) and (37), taking into account that $\tilde{S} \in G_-$ and $\bar{S} \in G_+$, we deduce the following.

Corollary 1. We have the expressions
\[
B_{ja} = \pi_a \Lambda + U_a + \bar{U}_a \Lambda^{-1},
\]
\[
\omega_K := \pi_a \Lambda + \bar{a}_K + \bar{a}_K \Lambda^{-1}, \\
K = (a, b),
\] (39)
where the coefficients have the alternative expressions
\[
U_a := \beta(n) \pi_a - \pi_a \beta(n + 1) = \begin{cases} \partial_{\lambda a} \left( e^{\phi(n)} \right) \cdot e^{-\phi(n)}, & a \in \mathbb{S}, \\ 0, & a \in \mathbb{S}, \end{cases}
\]
\[
\bar{U}_a = e^{\phi(n)} \bar{R}_a e^{-\phi(n+1)} = \begin{cases} 0, & a \in \mathbb{S}, \\ \partial_{\lambda a} \beta(n), & a \in \mathbb{S}, \end{cases}
\]
we cross the first two equations, we get

\[ a_k := l_N - \pi_a - \pi_b + T_k \beta(n) \pi_a - \pi_a \beta(n + 1) = \begin{cases} e^{T_k \phi(n)} \cdot (l_N - \bar{\pi}_b) \cdot e^{-\phi(n)}, & a \in S, \\ l_N - \pi_b, & a \in \bar{S}. \end{cases} \]

\[ \bar{a}_k := e^{T_k \phi(n)} \bar{\pi}_a e^{-\phi(n - 1)} = \begin{cases} 0, & a \in \bar{S}, \\ T_k \beta(n)(l_N - \pi_b) - (l_N - \pi_b) \beta(n) + \pi_b, & a \in S. \end{cases} \]

From (40), we deduce the following set of nonlinear partial differential-difference equations:

\[
\begin{aligned}
\beta(n) E_{kk} - E_{kk} \beta(n + 1) &= \partial_{l_k} (e^{\phi(n)} \cdot e^{-\phi(n)}, \\
\partial_{l_k} \beta(n) &= e^{\phi(n)} E_{kk} e^{-\phi(n - 1)}, \\
T_{(k,b)} \beta(n) E_{kk} - E_{kk} \beta(n + 1) + l_N - E_{kk} - \pi_b &= e^{T_{(k,b)} \phi(n)} (l_N - \bar{\pi}_b) \cdot e^{-\phi(n)}, \\
T_{(k,b)} \beta(n)(l_N - \pi_b) - (l_N - \pi_b) \beta(n) + \pi_b &= e^{T_{(k,b)} \phi(n)} E_{kk} \cdot e^{-\phi(n - 1)}. \\
\end{aligned}
\] (41)

These equations constitute what we call the multicomponent Toda equations. Observe that if we cross the first two equations, we get

\[
\partial_{l_k} \partial_{l_{k'}} (e^{\phi(n)} \cdot e^{-\phi(n)}) = e^{\phi(n)} E_{k'k} \cdot e^{-\phi(n - 1)} E_{kk} - E_{kk} e^{\phi(n + 1)} E_{k'k} \cdot e^{-\phi(n)},
\]

which is the matrix extension of the 2D Toda equation, which appears for \( N = 1 \):

\[
\partial_{l_1} \partial_{l_{1'}} (\phi(n)) = e^{\phi(n) - \phi(n - 1)} - e^{\phi(n + 1) - \phi(n)}.
\]

If in the last equation we set \( b = l \in \bar{S} \), we have

\[
\Delta_{(k,l}, \beta(n) = e^{T_{(k,l)} \phi(n)} \cdot E_{kk} \cdot e^{-\phi(n - 1)},
\]

which when considered simultaneously with the first gives

\[
\Delta_{(k,l)} (\partial_{l_{k'}} (e^{\phi(n)} \cdot e^{-\phi(n)}) = e^{T_{(k,l)} \phi(n)} \cdot E_{k'k} \cdot e^{-\phi(n - 1)} E_{kk} - E_{kk} e^{T_{(k,l)} \phi(n + 1)} \cdot E_{k'k} \cdot e^{-\phi(n)},
\]

which is a Toda-type equation. A completely discrete equation appears, for example, when crossing the last two equations, i.e.

\[
\Delta_{(k,l)} (e^{T_{(k,l)} \phi(n)} \cdot (l_N - \bar{\pi}_b) \cdot e^{-\phi(n)}) = T_{(k,b)} (e^{T_{(l,k)} \phi(n)} \cdot E_{k'k'} \cdot e^{-\phi(n - 1)} E_{kk})
\]

\[
- E_{kk} e^{T_{(k,l)} \phi(n + 1)} \cdot E_{k'k} \cdot e^{-\phi(n)}.
\]

So forth and so on we may get a continuous-discrete set of Toda-type equations. Finally, observe that when \( N = 1 \) we only have the shift \( T_{(n_1,n_1)} \) which corresponds to a shift \( n \to n + 1 \).

### 2.4. Block Toeplitz/Hankel reductions

We now consider some reductions of the multicomponent 2D Toda hierarchy. In the first place we discuss an extension of the periodic reduction [32] and the bigraded reduction [7] to the multicomponent case, which we call the Toeplitz/Hankel reduction. Finally, we discuss an extension of the one-dimensional reduction discussed in [32]. These reductions are relevant when we work with semi-infinite cases, as in the construction of families of bi-orthogonal and orthogonal matrix polynomials, to be published elsewhere.

Given a set \( \{l_{i} \}_{a \in S} \subset \mathbb{Z} \), we seek for initial conditions \( g \) satisfying

\[
g \cdot \left( \sum_{k=1}^{N} E_{kk} \Lambda^{-l_{k}} \right) = \left( \sum_{k=1}^{N} E_{kk} \Lambda^{l_{k}} \right) \cdot g. \quad (42)
\]

Relation (42) gives the following constraints over the Lax operators:

\[
\sum_{k=1}^{N} C_{kk} L^{l_{k}} = \sum_{k=1}^{N} \bar{C}_{kk} L^{-l_{k}}. \quad (43)
\]
for any \( j \in \mathbb{Z} \). To proceed further in the analysis of these reductions, we define the sets

\[
\mathbb{S}_\pm := \{ a \in \mathbb{S} : \pm \ell_a > 0 \}, \quad \mathbb{S}_0 := \{ a \in \mathbb{S} : \ell_a = 0 \},
\]

\[
\bar{\mathbb{S}}_\pm := \{ a \in \bar{\mathbb{S}} : \pm \ell_a > 0 \}, \quad \bar{\mathbb{S}}_0 := \{ a \in \bar{\mathbb{S}} : \ell_a = 0 \},
\]

so that \( \mathbb{S} = \mathbb{S}_+ \cup \mathbb{S}_0 \cup \mathbb{S}_- \), and \( \bar{\mathbb{S}} = \bar{\mathbb{S}}_+ \cup \bar{\mathbb{S}}_0 \cup \bar{\mathbb{S}}_- \).

**Proposition 5.** If (43) holds, then we have the following.

1. The dressing operators are subject to

\[
\left( \sum_{a \in \mathbb{S}_+ \cup \mathbb{S}_0 \cup \bar{\mathbb{S}}_+} \partial j_{\ell_a, a} \right) (W) = W \sum_{k=1}^{N} E_{kk} A^{j_{\ell_k}},
\]

\[
\left( \sum_{a \in \mathbb{S}_- \cup \mathbb{S}_0 \cup \bar{\mathbb{S}}_-} \partial j_{\ell_a, a} \right) (\bar{W}) = \bar{W} \sum_{k=1}^{N} E_{kk} A^{-j_{\ell_k}},
\]

for \( j > 0 \).

2. The Lax operators are invariant:

\[
\left( \sum_{a \in \mathbb{S}_+ \cup \mathbb{S}_0 \cup \bar{\mathbb{S}}_+} \partial j_{\ell_a, a} \right) (L) = \left( \sum_{a \in \mathbb{S}_- \cup \mathbb{S}_0 \cup \bar{\mathbb{S}}_-} \partial j_{\ell_a, a} \right) (\bar{L}) = 0,
\]

where \( j > 0 \).

Moreover, if

\[
\sum_{a \in \mathbb{S}} \ell_a = 0,
\]

then

1. The dressing operators fulfill

\[
W(s_1 + \ell_1, \ldots, s_N + \ell_N, s_{\bar{1}} + \ell_{\bar{1}}, \ldots, s_{\bar{N}} + \ell_{\bar{N}}) = W(s_1, \ldots, s_N, s_{\bar{1}}, \ldots, s_{\bar{N}}) \sum_{k=1}^{N} E_{kk} A^{\ell_k},
\]

\[
\bar{W}(s_1 + \ell_1, \ldots, s_N + \ell_N, s_{\bar{1}} + \ell_{\bar{1}}, \ldots, s_{\bar{N}} + \ell_{\bar{N}}) = \bar{W}(s_1, \ldots, s_N, s_{\bar{1}}, \ldots, s_{\bar{N}}) \sum_{k=1}^{N} E_{kk} A^{-\ell_k},
\]

for \( j > 0 \).

2. The Lax operators are periodic

\[
L(s_1 + \ell_1, \ldots, s_N + \ell_N, s_{\bar{1}} + \ell_{\bar{1}}, \ldots, s_{\bar{N}} + \ell_{\bar{N}}) = L(s_1, \ldots, s_N, s_{\bar{1}}, \ldots, s_{\bar{N}}),
\]

\[
\bar{L}(s_1 + \ell_1, \ldots, s_N + \ell_N, s_{\bar{1}} + \ell_{\bar{1}}, \ldots, s_{\bar{N}} + \ell_{\bar{N}}) = \bar{L}(s_1, \ldots, s_N, s_{\bar{1}}, \ldots, s_{\bar{N}}).
\]
To prove this we need

**Lemma 1.** If (43) holds, then for \( j > 0 \) we have

\[
\sum_{a \in \mathbb{S}_\ell} B_{j, \ell a} = \sum_{k=1}^{N} C_{kk} L^{\ell j} = \sum_{k=1}^{N} \bar{C}_{kk} \bar{L}^{-\ell j},
\]

\[
\sum_{a \in \mathbb{S}_\ell \cup \mathbb{R}_0 \cup \mathbb{R}_-} B_{j, \ell a} = \sum_{k=1}^{N} C_{kk} L^{-\ell j} = \sum_{k=1}^{N} \bar{C}_{kk} \bar{L}^{\ell j}.
\]

(48)

**Proof.** The projection of \( A = \sum_{k=1}^{N} C_{kk} L^{\ell j}, j > 0 \), on \( g_a \) is \( \sum_{a \in \mathbb{S}_\ell \cup \mathbb{R}_0 \cup \mathbb{R}_-} B_{j, \ell a} \) while the projection of \( A = \sum_{k=1}^{N} \bar{C}_{kk} \bar{L}^{-\ell j}, j > 0 \), on \( g_a \) is \( \sum_{a \in \mathbb{S}_\ell} B_{j, \ell a} \). The first formula is just \( A = A_+ + A_- \). The second formula follows in a similar way when \( j < 0 \). \( \square \)

Now we proceed with the

**Proof of proposition 5.** Equations (44) and (45) follow from the previous lemma and theorem 1 respectively. To deduce (46) and (47), we argue as follows. If

\[
\sum_{a \in \mathbb{S}} \ell_a = 0,
\]

the periodicity follows from the factorization problem

\[
S \cdot W_0 \cdot \left( \sum_{k=1}^{N} E_{kk} A^{\ell k} \right) = g = S \cdot W_0 \cdot g \cdot \left( \sum_{k=1}^{N} E_{kk} A^{-\ell k} \right) = \bar{S} \cdot \bar{W}_0 \cdot \left( \sum_{k=1}^{N} E_{kk} A^{-\ell k} \right)
\]

by observing that

\[
W_0(s_1 + \ell_1, \ldots, s_N + \ell_N) = W_0(s_1, \ldots, s_N) \sum_{k=1}^{N} E_{kk} A^{\ell k},
\]

\[
\bar{W}_0(s_1 + \ell_1, \ldots, s_N + \ell_N) = \bar{W}_0(s_1, \ldots, s_N) \sum_{k=1}^{N} E_{kk} A^{-\ell k},
\]

and recalling the uniqueness property of the factorization problem we deduce the periodicity condition for the solutions

\[
S(s_1 + \ell_1, \ldots, s_N + \ell_N, s_1 + \ell_1, \ldots, s_N + \ell_N) = S(s_1, \ldots, s_N, s_1, \ldots, s_N),
\]

\[
\bar{S}(s_1 + \ell_1, \ldots, s_N + \ell_N, s_1 + \ell_1, \ldots, s_N + \ell_N) = \bar{S}(s_1, \ldots, s_N, s_1, \ldots, s_N),
\]

which imply (46) and (47). \( \square \)

Now we justify the name of this reduction. If we write \( g = \sum_{j \in \mathbb{Z}} g_j(n) A^j \), and think of it as an element in \( M_N(M_{2\pi}(\mathbb{C})) \), i.e. \( g = \sum_{k_1, k_2=1}^{N} g_{k_1 k_2} E_{k_1 k_2} \), and \( g_{k_1 k_2} = \sum_{j \in \mathbb{Z}} g_{j, k_1 k_2}(n) A^j \), then (42) gives

\[
g_{j, k_1 k_2}(n) = g_{j, k_1 k_2 (n)} = g_{j, k_1 k_2 (n - \ell_{k_1})}.
\]

(49)

If \( \ell_{k_1} + \ell_{k_2} = 0 \), then \( g_{j, k_1 k_2} \) is a \( |\ell_{k_1}| \)-periodic function in \( n \). If this period is 1, we get that \( g_{j, k_1 k_2} \) is a bi-infinite Toeplitz or Laurent matrix. We will see that in the general case, we deal with block Toeplitz [5] and block Hankel [34] bi-infinite matrices.

**Definition 4.** Given a block matrix \( \Omega = (\Omega_{i,j})_{i,j \in \mathbb{Z}} \) made up of \( p \times q \)-blocks \( \Omega_{i,j} \), we say that \( \Omega \) is a block Toeplitz matrix if \( \Omega_{i+1,j+1} = \Omega_{i,j} \) and a block Hankel matrix if \( \Omega_{i+1,j-1} = \Omega_{i,j} \).

**Proposition 6.** Condition (49) implies for \( g_{k_1 k_2} \) that

\[
\sum_{a \in \mathbb{S}_\ell} B_{j, \ell a} = \sum_{k=1}^{N} C_{kk} L^{\ell j} = \sum_{k=1}^{N} \bar{C}_{kk} \bar{L}^{-\ell j},
\]

\[
\sum_{a \in \mathbb{S}_\ell \cup \mathbb{R}_0 \cup \mathbb{R}_-} B_{j, \ell a} = \sum_{k=1}^{N} C_{kk} L^{-\ell j} = \sum_{k=1}^{N} \bar{C}_{kk} \bar{L}^{\ell j}.
\]
For $\ell k, \ell k > 0$, $g k, k$ is a $|\ell k| \times |\ell k|$-block bi-infinite Hankel matrix.

• For $\ell k, \ell k \leq 0$, $g k, k$ is a $|\ell k| \times |\ell k|$-block bi-infinite Toeplitz matrix.

• For $\ell k = 0$ with $\ell k \neq 0$, $g k, k$ has a diagonal band structure, $|\ell k|$ being its width, and for $\ell k = 0$ with $\ell k \neq 0$ a $|\ell k| \times |\ell k|$ block bi-infinite matrix.

Proof. See appendix B □

The Toeplitz/Hankel block structure appears not only in the structure of $g k, k$, but also in the structure of $g$ itself, thought as an element in $M_2(M_2(C))$, for example if one takes $\ell k = -\ell k = 1, k = 1, \ldots, N$, we get an $N \times N$-block bi-infinite Toeplitz matrix, while for $\ell k = \ell k = 1, k = 1, \ldots, N$, we get an $N \times N$-block bi-infinite Hankel matrix.

Note that for the particular case $\ell k = \ell k, k = 1, \ldots, N$, we have that $g$ is a block Hankel bi-infinite matrix and

$$g \sum_{k=1}^{N} E_{kk} \Lambda^{-\ell k} = \sum_{k=1}^{N} E_{kk} \Lambda^{\ell k} g,$$

$$g \sum_{k=1}^{N} E_{kk} \Lambda^{\ell k} = \sum_{k=1}^{N} E_{kk} \Lambda^{-\ell k} g.$$

From these two equivalent conditions on $g$, we conclude for $g^2$ the following constraint:

$$g^2 \sum_{k=1}^{N} E_{kk} \Lambda^{\ell k} = \sum_{k=1}^{N} E_{kk} \Lambda^{-\ell k} g^2,$$

i.e. $g^2$ is a block Toeplitz bi-infinite matrix and the corresponding solution to $g^2$ of the periodic type with bared and non-bared periods equals to each other for each component: $\ell k = -\ell k, k = 1, \ldots, N$.

In the one-component case, we get the condition

$$L^{\ell k} = \bar{L}^{-\ell k}. \quad (50)$$

If $\ell_1 + \ell_1 = \ell$ we may choose $\ell = \ell \in \mathbb{N}$ and $\ell_1 = -\ell$ and the constraint for $g$ is $g \Lambda^\ell = \Lambda^\ell g$ which leads $L^\ell = \bar{L}^{-\ell}$, i.e. the $\ell$ th periodic reduction of the one-component 2D Toda hierarchy [32]. When $\ell_1, \ell_1 > 0$ are two nonnegative integers, this constraint (50) gives the reduction of the one-component 2D Toda hierarchy suitable to be extended with additional flows as described in [7], named there as bigraded. This is why we refer to this reduction when all $\ell a$ are positive as multigraded reduction. Note that this multigraded constraint over $g$ is never of the periodic type and $\bar{S} = \bar{S},$ and $\bar{S} = \bar{S}_a$.

1D reduction and generalizations. Given a set of nonnegative integers $\{\ell a\}_{a \in S}$, we request $g$ in (10) the following constraint:

$$g \cdot \left( \sum_{k=1}^{N} E_{kk} (\Lambda^{\ell k} + \Lambda^{-\ell k}) \right) = \left( \sum_{k=1}^{N} E_{kk} (\Lambda^{\ell k} + \Lambda^{-\ell k}) \right) \cdot g.$$ 

Now, as $z^j + z^{-j} = (z + z^{-1})^j + a_{j,-j} (z + z^{-1})^{-j} + \cdots + a_{j,0}$, for some $a_{j,0} \in \mathbb{Z}$, we have

$$g \cdot \left( \sum_{k=1}^{N} E_{kk} (\Lambda^{j k} + \Lambda^{-j k}) \right) = \left( \sum_{k=1}^{N} E_{kk} (\Lambda^{j k} + \Lambda^{-j k}) \right) \cdot g$$

and therefore

$$\sum_{k=1}^{N} C_{kk} (L^{j k} + L^{-j k}) = \sum_{k=1}^{N} \bar{C}_{kk} (\bar{L}^{j k} + \bar{L}^{-j k})$$

is fulfilled for any $j \geq 0$. 

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From here, we conclude that
\[ \sum_{k=1}^{N} (B_{j_1\ell_1,k} + B_{j_2\ell_2,k}) = \sum_{k=1}^{N} C_{kk}(L^{j_1\ell_1} + L^{-j_2\ell_2}) = \sum_{k=1}^{N} \overline{C}_{kk}(\overline{L}^{j_1\ell_1} + \overline{L}^{-j_2\ell_2}) \]
and therefore we deduce the invariance
\[ \sum_{k=1}^{N} \left( \partial_{j_1\ell_1,k} + \partial_{j_2\ell_2,k} \right) = \sum_{k=1}^{N} \left( \partial_{j_1\ell_1,k} + \partial_{j_2\ell_2,k} \right) \overline{L} = 0. \] (51)

In the one-component case if we choose \( \ell_1 = \ell_2 = 1 \), we get the invariance under \( \partial_{j_1} + \partial_{j_2} \), \( j > 0 \). This is the one-dimensional reduction as discussed, for example, in [32].

It must be stressed here that being the same invariance conditions (51) for this reduction and the previous multigraded reduction, the conditions are different for \( g \) and therefore for the class of solutions considered in the 2D Toda hierarchy. In fact the Ueno–Takasaki 1D reduction has soliton solutions, which appear as a particular class of the general soliton solutions of his 2D Toda hierarchy. However, this Ueno–Takasaki’s family of soliton solutions of 2D Toda does not admit the bigraded-type condition. On the other hand, the condition \( \overline{L} = \overline{L}^{-1} \) appears as a string equation in 2D Toda leading to solutions of the 1-matrix models; see for example [27].

3. Orlov–Schulman operators, undressing and string equations

3.1. Introducing the Orlov–Schulman operator

Given solutions \( W, \overline{W} \) of the factorization problem (10), we introduce the Orlov–Schulman operators [25] for the multicomponent 2D Toda hierarchy.

**Definition 5.** The Orlov–Schulman operators are defined as follows:
\[ M := WnW^{-1}, \quad \overline{M} := Wn\overline{W}^{-1}. \] (52)

**Proposition 7.**
- The Orlov–Schulman operators satisfy the following commutation relations:
\[ [L, M] = L, \quad [M, C_{kk}] = 0, \quad [\overline{L}, M] = \overline{L}, \quad [\overline{M}, \overline{C}_{kk}] = 0. \] (53)
- The following relations hold:
\[ M = \mathcal{M} + \sum_{k=1}^{N} C_{kk} \left( s_k + \sum_{j=1}^{\infty} j\ell_k L^j \right), \quad \mathcal{M} = n + g \Lambda. \]
\[ \overline{M} = \mathcal{N} - \sum_{k=1}^{N} \overline{C}_{kk} \left( s_k + \sum_{j=1}^{\infty} j\ell_k \overline{L}^{-j} \right), \quad \mathcal{N} = n + g \Lambda. \] (54)

**Proof.** See appendix B. \( \square \)

**String equations for Lax and Orlov–Schulman operators from the factorization problem.** Given the initial condition \( g \in G \) in the factorization problem (10), we introduce the important functions \( p_{k,l} \), \( q_{k,l} \) for the formulation of the string equations through
\[ g \Lambda E_{kk}g^{-1} = \sum_{l,l' = 1}^{N} p_{k,l}(n, \Lambda)E_{ll'}, \quad gnE_{kk}g^{-1} = \sum_{l,l' = 1}^{N} q_{k,l}(n, \Lambda)E_{ll'}. \]
and define

\[ P_k := \sum_{l,l' = 1}^{N} p_{k,l,l'}(M, L)C_{ll'}, \quad Q_k := \sum_{l,l' = 1}^{N} q_{k,l,l'}(M, L)C_{ll'}, \]

so that

\[ [P_k, Q_k] = \delta_{kk} P_k. \] (56)

Then, as \( Wg = \bar{W} \), we get, in the language of \([28]\), the string equations

\[ \sum_{l,l' = 1}^{N} p_{k,l,l'}(M, L)C_{ll'} := \bar{L}\bar{C}_{kk}, \quad \sum_{l,l' = 1}^{N} q_{k,l,l'}(M, L)C_{ll'} := \bar{M}\bar{C}_{kk}. \] (57)

### 3.2. Undressing Lax equations for the Lax and Orlov–Schulman operators

The Orlov–Schulman operators

\[
M = WnW^{-1}, \quad \bar{M} = \bar{W}n\bar{W}^{-1}
\]

satisfy

\[
\partial_{ja} M = [\partial_{ja} W \cdot W^{-1}, M], \quad \partial_{ja} \bar{M} = [\partial_{ja} \bar{W} \cdot \bar{W}^{-1}, \bar{M}],
\]

\[
T_K M = (T_K W \cdot W^{-1})M(T_K W \cdot W^{-1})^{-1}, \quad T_K \bar{M} = (T_K \bar{W} \cdot \bar{W}^{-1})\bar{M}(T_K \bar{W} \cdot \bar{W}^{-1})^{-1},
\]

and the factorization problem (10) then holds the results of theorem 1 implying the following Lax equations for the Orlov–Schulman operators:

\[
\partial_{ja} M = [B_{ja}, M], \quad \partial_{ja} \bar{M} = [B_{ja}, \bar{M}],
\]

\[
T_K M = \omega_K M\omega_K^{-1}, \quad T_K \bar{M} = \omega_K \bar{M}\omega_K^{-1}.
\] (58)

We now prove the local equivalence between the factorization problem and the Lax equations.

**Theorem 2.** Let us suppose that

(1) The operators \( L, \bar{L}, C_{kk}, \bar{C}_{kk}, M \) and \( \bar{M} \) satisfy the conditions

\[
L = \Lambda + \frac{u_1(n)}{\Lambda} + \frac{u_2(n)}{\Lambda^2} + \cdots, \quad \bar{L} = \bar{u}_0(n)\Lambda^{-1} + \bar{u}_1(n) + \frac{\bar{u}_2(n)}{\Lambda} + \cdots,
\]

\[
C_{kk} = E_{kk} + C_{kk,1}(n)\Lambda^{-1} + C_{kk,2}(n)\Lambda^{-2} + \cdots,
\]

\[
\bar{C}_{kk} = \bar{C}_{kk,0}(n) + \bar{C}_{kk,1}(n)\Lambda + \bar{C}_{kk,2}(n)\Lambda^2 + \cdots,
\]

\[
M = \cdots + M_{-1} \Lambda^{-1} + n \sum_{k=1}^{N} C_{kk} \left( j + \sum_{j=1}^{\infty} jL \right),
\]

\[
\bar{M} = \cdots + \bar{M}_{-1} \Lambda + n \sum_{k=1}^{N} \bar{C}_{kk} \left( j + \sum_{j=1}^{\infty} j\bar{L} \right),
\]

with \( k = 1, \ldots, N, \bar{u}_0(n) \in \text{GL}(N, \mathbb{C}) \), and fulfill the equations

\[
\|L\|_{N} = \sum_{k=1}^{N} C_{kk}, \quad C_{kk}C_{ll} = \delta_{kl} C_{kk}, \quad C_{kk}L = LC_{kk},
\]

\[
\|L\|_{N} = \sum_{k=1}^{N} \bar{C}_{kk}, \quad \bar{C}_{kk}\bar{C}_{ll} = \delta_{kl} \bar{C}_{kk}, \quad \bar{C}_{kk}\bar{L} = \bar{L}C_{kk},
\]

\[
\|L\|_{N} = \sum_{k=1}^{N} \bar{C}_{kk}, \quad \bar{C}_{kk}\bar{C}_{ll} = \delta_{kl} \bar{C}_{kk}, \quad \bar{C}_{kk}\bar{L} = \bar{L}C_{kk},
\]

\[
L M = ML, \quad \bar{L} \bar{M} = \bar{M} \bar{L}.
\] (60)
Proof. Observe that what we need to find is the representation
\[ \text{such that} \]
which transmutes into (61) once we replace \( \phi \)
so forth and so on, we get all the coefficients \( \bar{\phi} \), \( \bar{\phi}^\prime \), \( \bar{\phi}^\prime \) with \( \Lambda^1, \ldots, \Lambda^N \)
Thus, all the coefficients \( \bar{\phi} \), \( \bar{\phi}^\prime \), \( \bar{\phi}^\prime \) as in (B.3).
We first undress the Lax operators \( L, \bar{L} \).
Now, we proceed to undress \( \bar{U}_{kk} \):
\[ C_{kk} := S^{-1} C_{kk} S, \quad \bar{C}_{kk} := S^{-1} \bar{C}_{kk} S. \]
These operators commute with \( \Lambda \), satisfying
\[ C_{kk} = E_{kk} + C_{kk,1} \Lambda^{-1} + C_{kk,2} \Lambda^{-2} + \cdots, \]
\[ \bar{C}_{kk} = \bar{C}_{kk,0} + \bar{C}_{kk,1} \Lambda + \bar{C}_{kk,2} \Lambda^2 + \cdots. \]

Note that the set of constrains (59) and (60) is preserved by the Lax equations.

Therefore, if we define \( \Sigma_\pm[f] := \sum_{j=0}^{\infty} f(n \pm j) \), we have
\[ \phi_i^\prime = c_i + \Sigma_+[u_2(n) + u_1 \phi_i^\prime]. \]
So forth and so on, we get all the coefficients \( \phi_i^\prime \) up to integration constants \( c_j \).

Now we analyze (62), which we write as follows:
\[ (\bar{\psi}_0 - \bar{\psi}_1 - \bar{\psi}_2 \Lambda^{-1} - \cdots) \bar{\phi}_i = (\bar{\psi}_0 - \bar{\psi}_1 \Lambda^{-1} + \bar{\psi}_2 \Lambda^{-2} + \cdots) \Lambda, \]
with \( \bar{\psi}_j(n) := \bar{\psi}_j(n) - \bar{\psi}_0(n) \Lambda^{-j} \).
From this, we deduce that \( \bar{\psi}_0 = \bar{\psi}_1 \Lambda^{-1} \bar{\phi}_0 \Lambda^{-2} + \cdots \Lambda^{-j} \Lambda \), \( \bar{\psi}_0 \) equals 
\[ \psi_0 := \psi_0(n) \phi_0((n + 1) \phi_0^\prime). \]
Denoting \( \phi' := \log \psi_0 \), we get \( \Lambda = (1 - \Lambda^{-1}) \phi' \)
so forth and so on, we get all the coefficients \( \phi_i^\prime \) up to integration constants \( c_j \).

Now we proceed to undress \( \bar{C}_{kk} \):
\[ C_{kk} := S^{-1} C_{kk} S, \quad \bar{C}_{kk} := S^{-1} \bar{C}_{kk} S. \]
These operators commute with \( \Lambda \), satisfying
\[ C_{kk} = E_{kk} + C_{kk,1} \Lambda^{-1} + C_{kk,2} \Lambda^{-2} + \cdots, \]
\[ \bar{C}_{kk} = \bar{C}_{kk,0} + \bar{C}_{kk,1} \Lambda + \bar{C}_{kk,2} \Lambda^2 + \cdots. \]

(2) Given operators \( B \) and \( \omega \) as in (20), the Lax equations (30), (31) and (58) hold.
Then, there exist operators \( S \in G_\omega \) and \( \bar{S} \in G_\omega \) such that for \( W = SW_0 \) and \( \bar{W} = \bar{S}\bar{W}_0 \), we may write
\[ L = W \Lambda W^{-1}, \quad M = W^{-1} W, \quad C_{kk} = W E_{kk} W^{-1}, \]
\[ \bar{L} = \bar{W} \bar{\Lambda} \bar{W}^{-1}, \quad \bar{M} = \bar{W}^{-1} \bar{W}, \quad \bar{C}_{kk} = \bar{W} E_{kk} \bar{W}^{-1}, \]
such that \( W \) and \( \bar{W} \) solve the factorization problem (10) for some constant operator \( g \).
and provide us with two different resolutions of the identity,

$$
\mathbb{I}_N = \sum_{k=1}^{N} C_{kk}, \quad C_{kk} C_{kk}^* = \delta_{kk} C_{kk}^*, \quad \mathbb{I}_N = \sum_{k=1}^{N} C_{kk}^*, \quad C_{kk}^* C_{kk}^* = \delta_{kk} C_{kk}.
$$

In fact, it is easy to show that there exist operators $Q = \mathbb{I}_N + \Lambda^{-1} + \cdots + \Lambda^{-1} \in \mathbb{G}_2 \cap \mathbb{J}_2$, and $\check{Q} = \check{Q}_0 + \check{Q}_1 + \cdots + \check{Q}_{2} \in \mathbb{G}_2 \cap \mathbb{J}_2$ such that $C_{kk} = Q E_{kk} Q^{-1}$ and $C_{kk}^* = \check{Q} E_{kk} \check{Q}^{-1}$. Thus, to undress $L, \check{L}, C_{kk}, \check{C}_{kk}, k = 1, \ldots, N$, we just take $S = S' \cdot Q, \check{S} = \check{S} \cdot \check{Q}$.

With these operators at hand, we proceed to undress $M$ and $\check{M}$ (see (B.3)):

$$
S^{-1} MS = \alpha + \mu, \quad E_{kk}, S^{-1} MS = n, \\
S^{-1} M \check{S} = \bar{\alpha} + \bar{\mu}, \quad E_{kk}, \check{S}^{-1} M \check{S} = 0,
$$

but

$$
[\Lambda, S^{-1} MS] = \Lambda, \quad [E_{kk}, S^{-1} MS] = 0, \\
[\Lambda, \check{S}^{-1} M \check{S}] = \Lambda, \quad [E_{kk}, \check{S}^{-1} M \check{S}] = 0
$$

and $[\Lambda, \mu] = \Lambda$ and $[\Lambda, \bar{\mu}] = \Lambda$, so that

$$
[\Lambda, \alpha] = 0, \quad [E_{kk}, \alpha] = 0, \quad [\Lambda, \bar{\alpha}] = 0, \quad [E_{kk}, \bar{\alpha}] = 0 \Rightarrow \alpha, \bar{\alpha} \in \mathfrak{h}.
$$

Now, recalling that $M = n + g_\alpha$, and $\check{M} = n + \Lambda g_\alpha$, we write $\alpha = S^{-1} n S - n + g_\alpha$ and $\bar{\alpha} = \check{S}^{-1} n \check{S} - n + g_\alpha$ so that $\alpha = \alpha_1 \Lambda^{-1} + \alpha_2 \Lambda^{-2} + \cdots$ and $\bar{\alpha} = \bar{\alpha}_1 \Lambda + \bar{\alpha}_2 \Lambda^2 + \cdots$ with $\alpha_i, \bar{\alpha}_i \in \text{diag}(N, \mathbb{C})$ for all $i \in \mathbb{N}$. We define $\gamma := - \sum_{j \geq 1} \frac{\alpha_j}{\Lambda^{-j}}, \check{\gamma} := \phi_0 + \sum_{j \geq 1} \frac{\check{\gamma}_j}{\Lambda^j}$, where $\phi_0 \in \text{diag}(N, \mathbb{C})$, and find that

$$
e^{\gamma} n e^{-\gamma} = n + [\gamma, n] = n + \alpha = S^{-1} MS, \quad e^{\check{\gamma}} \check{n} e^{-\check{\gamma}} = n + [\check{\gamma}, n] = n + \bar{\alpha} = \check{S}^{-1} \check{M} \check{S},$$

which allows us to write (see (B.3))

$$
e^{\gamma} W_0 e^{\gamma} = e^{\gamma} n e^{-\gamma} + \gamma = S^{-1} MS + \gamma, \quad e^{\check{\gamma}} W_0 \check{e}^{-\check{\gamma}} = e^{\check{\gamma}} \check{n} e^{-\check{\gamma}} + \check{\gamma} = \check{S}^{-1} \check{M} \check{S} + \check{\gamma}.
$$

Therefore, if we replace $S \rightarrow S e^{\gamma}$ and $\check{S} \rightarrow \check{S} e^{\check{\gamma}}$, we get the desired result.

From (30) and (31), we get that

$$
A_{ja} := \langle S \rangle^{-1} \cdot (B_{ja} - \partial_{ja} S) S S^{-1} S, \quad \check{A}_{ja} := \langle \check{S} \rangle^{-1} \cdot (B_{ja} - \partial_{ja} \check{S}) S \check{S}^{-1} S,
$$

$$
\rho_K := T_K (S)^{-1} \omega_K S, \quad \check{\rho}_K := T_K (S)^{-1} \check{\omega}_K \check{S},
$$

commute with $\Lambda$ and all $E_{kk}, k = 1, \ldots, N$, i.e. they are $n$-independent and diagonal (58). We may deduce that

$$
[A_{ja}, \mu] = j \partial_{ja} \Rightarrow [A_{ja}, n] = j \partial_{ja} [A_{ja} - \partial_{ja}, n] = 0, \quad (44)
$$

and

$$
\omega_K M \omega_K^{-1} = (T_K S^{-1} M T_K S \cdot S^{-1} M)^{-1} + (T_K S)(\pi_a - \pi_{\check{b}})(T_K S)^{-1}, \quad \check{\omega}_K M \check{\omega}_K^{-1} = (T_K \check{S}^{-1} \check{M} T_K \check{S} \cdot \check{S}^{-1} \check{M})^{-1} - (T_K \check{S})(\check{\pi}_a - \check{\pi}_{\check{b}})(T_K \check{S})^{-1},
$$

which imply

$$
[\rho_{K}, \mu] = (\pi_a - \pi_{\check{b}}) \rho_{K} \Rightarrow [\rho_{K}, n] = (\pi_a - \pi_{\check{b}}) \rho_{K} \Rightarrow [(\rho_{K} q_{K}^{-1}, n] = 0, \quad (65)
$$

$$
[\check{\rho}_{K}, \check{\mu}] = -(\check{\pi}_a - \check{\pi}_{\check{b}}) \check{\rho}_{K} \Rightarrow [\check{\rho}_{K}, n] = -(\check{\pi}_a - \check{\pi}_{\check{b}}) \check{\rho}_{K} \Rightarrow [(\check{\rho}_{K} \check{q}_{K}^{-1}, n] = 0.
$$

Thus,

$$
A_{ja} - \partial_{ja}, \check{A}_{ja} - \partial_{ja}, \rho_{K} q_{K}^{-1}, \check{\rho}_{K} \check{q}_{K}^{-1} \in \text{diag}(N, \mathbb{C}).
$$
As the Lax equations (30) and (31) are satisfied by proposition 4, we know that \( B_{ja} \) and \( \omega_K \) satisfy the compatibility conditions (32)--(38). However, we see from (63) that \( \{A_{ja}, \rho_K \} \) and \( \{\bar{A}_{ja}, \bar{\rho}_K \} \) are gauge transforms of \( B_{ja}, \omega_K \) and thereby do have zero curvature. Therefore, we conclude the local existence of potentials \( \xi \) and \( \bar{\xi} \) such that

\[
A_{ja} = \partial_{ja} \xi \cdot \xi^{-1}, \quad \bar{A}_{ja} = \partial_{ja} \bar{\xi} \cdot \bar{\xi}^{-1}, \quad \rho_K = T_K \xi \cdot \xi^{-1}, \quad \bar{\rho}_K = T_K \bar{\xi} \cdot \bar{\xi}^{-1}.
\]

(67)

These potentials are determined up to right multiplication \( \xi \to \xi \cdot h, \quad \bar{\xi} \to \bar{\xi} \cdot \bar{h} \), where \( h, \bar{h} \in G \) are constant operators independent of \( t_{ja}, s_a \). Up to this freedom, we may take the potentials \( \xi, \bar{\xi} \in H \). Now, recalling (20) we get

\[
B_{ja} = R_{ja} + g_+ = \bar{R}_{ja} + g_+, \quad \omega_K = G_+ \cdot \Upsilon_k = G_+ \cdot \bar{\Upsilon}_k,
\]

which together with (63) imply \( A_{ja} - \partial_{ja} \in g_-, \quad \bar{A}_{ja} - \partial_{ja} \in g_+ \), \( \rho_K q^{-1}_K \in G_- \), \( \bar{\rho}_K q^{-1}_K \in G_+ \), but these operators belong to \( \text{diag}(N, C) \). Thus, from the first two relations we conclude \( A_{ja} = \partial_{ja}, \rho_K = q_K \) and \( \xi = W_0 \) while the second two imply that if \( \xi = e^{\phi} \cdot W_0 \) then \( \phi_0 \in \text{diag}(N, C) \).

Therefore, we may write

\[
A_{ja} = \partial_{ja} W_0 \cdot W_0^{-1}, \quad \bar{A}_{ja} = \partial_{ja} (e^{\phi} \bar{W}_0) \cdot (e^{\phi} \bar{W}_0)^{-1},
\]

\[
\rho_K = T_K W_0 \cdot W_0^{-1}, \quad \bar{\rho}_K = T_K (e^{\phi} \bar{W}_0) \cdot (e^{\phi} \bar{W}_0)^{-1}.
\]

We make the replacement \( \bar{S} \to S e^{\phi} \) to get

\[
B_{ja} = \partial_{ja} W \cdot W^{-1} = \partial_{ja} S \cdot S^{-1} + 5 \partial_{ja} S^{-1} = \partial_{ja} S \cdot S^{-1} + \bar{S} \partial_{ja} S^{-1} = \partial_{ja} W \cdot W^{-1},
\]

\[
\omega_K = (T_K W) \cdot W^{-1} = (T_K S) q_K S^{-1} = (T_K S) q_K S^{-1} = (T_K \bar{W}) \cdot \bar{W}^{-1}.
\]

In terms of \( g = W^{-1} \cdot \bar{W} \), the previous equations can be written as \( \partial_{ja} g = 0 \) and \( T_K g = g \).

Thus, we finally find \( W g = \bar{W} \) where \( g \) is a constant operator in \( G \).

A further result regarding the operators \( C_{kl} \) introduced in definition 2 and characterized in proposition 1 that will be needed later is given now.

**Proposition 8.** Given operators \( L, \bar{L}, M, \bar{M}, C_{kk} \) and \( \bar{C}_{kk} \) as in theorem 2, then: if we find operators \( C_{kl} \) of the form

\[
C_{kl} = \text{L}^{a} \text{e}^{(t_{ja} - \partial_{ja}) \text{L}^j} (E_{kl} + g_-),
\]

such that

\[
[C_{kl}, L] = [C_{kl}, M] = 0, \quad C_{k\ell} C_{l\ell} = \delta_{k\ell} C_{\ell\ell}, \quad C_{k\ell} C_{\ell\kappa} = \delta_{k\ell} C_{\kappa\ell},
\]

then the undressing operator \( W \) of theorem 2 satisfies \( C_{kl} = W E_{kl} W^{-1} \).

**Proof.** See appendix B.

3.3. String equations, factorization problem and Lax equations

We will show here that the string equations (57) for the Lax and Orlov–Schulman operators do indeed imply the factorization (10) and also the Lax equations (30) and (31). In fact, only one of these implications is needed as the other one will follow from the results described previously. However, we show that these two facts can be derived directly from the string equations, showing the importance of this formulation of integrable systems.

**Theorem 3.** Let \( L, M, C_{kk}, \bar{L}, \bar{M}, \bar{C}_{kk}, k = 1, \ldots, N \), be operators as in theorem 2 and operators \( C_{kl}, k, l = 1, \ldots, N \), be as in proposition 8. Let us suppose that we have operators \( P_k, Q_k \) as in (55) and that the string equations (57) hold. Then,
(1) we can choose the operators \( W \) and \( \tilde{W} \) of theorem 2 such that the factorization (10) holds for some constant operator \( g \in G \).

(2) the Lax equations (30)–(31) are fulfilled.

**Proof.** From the first part of the proof of theorem 2 (not considering the Lax equations) and proposition 8, we know that there are undressing operators \( W = SW_0 \) and \( \tilde{W} = \tilde{SW}_0, S \in G_-, \) and \( \tilde{S} \in G_+ \). Let us introduce some convenient notation

\[
D_{ja} := \partial_{ja} W \cdot W^{-1} - \partial_{ja} \tilde{W} \cdot \tilde{W}^{-1}, \quad D_{ja}^0 := \tilde{W}^{-1} D_{ja} \tilde{W},
\]

\[
\sigma_K := (T_K \tilde{W} \cdot \tilde{W}^{-1})^{-1} T_K W \cdot W^{-1}, \quad \sigma_K^0 := \tilde{W}^{-1} \sigma_K \tilde{W},
\]

and observe that if we define

\[
\zeta := W^{-1} \cdot W, \quad (68)
\]

we have

\[
D_{ja}^0 = \partial_{ja} \zeta \cdot \zeta^{-1}, \quad \sigma_K^0 = T_K \zeta \cdot \zeta^{-1}. \quad (69)
\]

The string equations (57) read as

\[
P_k = W P_k^0 W^{-1} = \tilde{W} E_{kk} A \tilde{W}^{-1}, \quad P_k^0 = \sum_{l,l'=1}^N p_{k,l'}(n, \Lambda) E_{l'l'},
\]

\[
Q_k = W Q_k^0 W^{-1} = \tilde{W} E_{kk} \tilde{W}^{-1}, \quad Q_k^0 = \sum_{l,l'=1}^N q_{k,l'}(n, \Lambda) E_{l'l'}, \quad (70)
\]

which in turn imply

\[
\partial_{ja} P_k = [\partial_{ja} W \cdot W^{-1}, P_k] = [\partial_{ja} \tilde{W} \cdot \tilde{W}^{-1}, P_k],
\]

\[
\partial_{ja} Q_k = [\partial_{ja} W \cdot W^{-1}, Q_k] = [\partial_{ja} \tilde{W} \cdot \tilde{W}^{-1}, Q_k].
\]

\[
T_K P_k = (T_K W \cdot W^{-1}) P_k (T_K W \cdot W^{-1})^{-1} = (T_K \tilde{W} \cdot \tilde{W}^{-1}) P_k (T_K \tilde{W} \cdot \tilde{W}^{-1})^{-1},
\]

\[
T_K Q_k = (T_K W \cdot W^{-1}) Q_k (T_K W \cdot W^{-1})^{-1} = (T_K \tilde{W} \cdot \tilde{W}^{-1}) Q_k (T_K \tilde{W} \cdot \tilde{W}^{-1})^{-1}.
\]

Hence, recalling \( P_k = L C_{kk} \) and \( Q_k = M C_{kk} \) we conclude that

\[
[D_{ja}, \tilde{L}] = [D_{ja}, \tilde{M}] = [D_{ja}, \tilde{C}_{kk}] = 0, \quad [\sigma_K, \tilde{L}] = [\sigma_K, \tilde{M}] = [\sigma_K, \tilde{C}_{kk}] = 0. \quad (72)
\]

Thus, we deduce that \( D_{ja}^0, \sigma_K^0 \in \text{diag}(N, \mathbb{C}) \), and therefore \( D_{ja} \in G_e \) and \( \sigma_K \in G_+ \). With these preliminaries, let us start proving the two statements in the theorem

(1) Given the representation (70) in terms of \( \zeta \) as in (69), we deduce that we can write \( \zeta = \xi \cdot g^{-1} \) for some \( \xi \in \text{diag}(N, \mathbb{C}) \) and some \((s, t)\)-independent operator \( g \in G \).

Thus, \( D_{ja}^0 = \partial_{ja} \xi \cdot \xi^{-1} \) and \( \sigma_K^0 = T_K \xi \cdot \xi^{-1} \). But recalling definition (69), we get \( \tilde{W} \zeta = W \Rightarrow \tilde{SW}_0 \tilde{\xi} = Wg \). Observe that \( [\tilde{W}_0, \tilde{\xi}] = 0 \) and replace \( S \rightarrow \tilde{S} \cdot \tilde{\xi} \) to get the factorization problem.

(2) From definition (68), we get

\[
\partial_{ja} W \cdot W^{-1} = \partial_{ja} S \cdot S^{-1} + \mathcal{R}_{ja} = \partial_{ja} \tilde{S} \cdot \tilde{S}^{-1} + \mathcal{R}_{ja} + D_{ja} = \partial_{ja} W \cdot W^{-1} + D_{ja},
\]

\[
T_K W \cdot W^{-1} = T_K S \cdot S^{-1} \cdot \mathcal{U}_K = T_K \tilde{S} \cdot \tilde{S}^{-1} \cdot \mathcal{U}_K \cdot \sigma_K = T_K \tilde{W} \cdot \tilde{W}^{-1} \cdot \sigma_K.
\]

Reasoning as in the proof of theorem 2 and recalling that \( D_{ja} \in G_e, \sigma_K \in G_+ \) and \( [\mathcal{U}_K, \sigma_K] = 0 \), we have

\[
\partial_{ja} S \cdot S^{-1} = -(\mathcal{R}_{ja} - \mathcal{R}_{ja})_-, \quad \partial_{ja} \tilde{S} \cdot \tilde{S}^{-1} + D_{ja} = (\mathcal{R}_{ja} - \mathcal{R}_{ja})_+,
\]

\[
T_K S \cdot S^{-1} = ([\mathcal{U}_K, \mathcal{U}_K^{-1}]_-, \quad T_K \tilde{S} \cdot \tilde{S}^{-1} \cdot \sigma_K = ([\mathcal{U}_K, \mathcal{U}_K^{-1}]_+.
\]
so that, according to (20),
\[ \partial_{ja} W \cdot W^{-1} = B_{ja} = \partial_{ja} W \cdot \bar{W}^{-1} + D_{ja}, \quad T_{k} W \cdot W^{-1} = \omega_{k} = T_{k} \bar{W} \cdot \bar{W}^{-1} \cdot \sigma_{k}. \]

Therefore, we immediately get the following Lax equations:
\[
\begin{align*}
\partial_{ja} L &= [\partial_{ja} W \cdot W^{-1}, L] = [B_{ja}, L], \\
T_{k} L &= (T_{k} W \cdot W^{-1}) L (T_{k} W \cdot W^{-1})^{-1} = \omega_{k} L \omega_{k}^{-1}, \\
\partial_{ja} M &= [\partial_{ja} W \cdot W^{-1}, M] = [B_{ja}, M], \\
T_{k} M &= (T_{k} W \cdot W^{-1}) M (T_{k} W \cdot W^{-1})^{-1} = \omega_{k} M \omega_{k}^{-1}, \\
\partial_{ja} C_{kk} &= [\partial_{ja} W \cdot W^{-1}, C_{kk}] = [B_{ja}, C_{kk}], \\
T_{k} C_{kk} &= (T_{k} W \cdot W^{-1}) C_{kk} (T_{k} W \cdot W^{-1})^{-1} = \omega_{k} C_{kk} \omega_{k}^{-1}.
\end{align*}
\]

Now, as \( \partial_{ja} W \cdot W^{-1} = B_{ja} - D_{ja} \) and \( T_{k} W \cdot W^{-1} = \omega_{k} \cdot \sigma_{k} \) with \( D_{ja} \) and \( \sigma_{k} \) commuting with any function of \( \bar{L}, \bar{M} \) and \( \bar{C}_{kk} \), we get the remaining Lax equations:
\[
\begin{align*}
\partial_{ja} \bar{L} &= [\partial_{ja} W \cdot W^{-1}, \bar{L}] = [B_{ja}, \bar{L}], \\
\bar{T}_{k} \bar{L} &= (T_{k} \bar{W} \cdot \bar{W}^{-1}) \bar{L} (T_{k} \bar{W} \cdot \bar{W}^{-1})^{-1} = \omega_{k} \bar{L} \omega_{k}^{-1}, \\
\partial_{ja} \bar{M} &= [\partial_{ja} W \cdot W^{-1}, \bar{M}] = [B_{ja}, \bar{M}], \\
\bar{T}_{k} \bar{M} &= (T_{k} \bar{W} \cdot \bar{W}^{-1}) \bar{M} (T_{k} \bar{W} \cdot \bar{W}^{-1})^{-1} = \omega_{k} \bar{M} \omega_{k}^{-1}, \\
\partial_{ja} \bar{C}_{kk} &= [\partial_{ja} W \cdot W^{-1}, \bar{C}_{kk}] = [B_{ja}, \bar{C}_{kk}], \\
\bar{T}_{k} \bar{C}_{kk} &= (T_{k} \bar{W} \cdot \bar{W}^{-1}) \bar{C}_{kk} (T_{k} \bar{W} \cdot \bar{W}^{-1})^{-1} = \omega_{k} \bar{C}_{kk} \omega_{k}^{-1}.
\end{align*}
\]

The above result might be slightly generalized by considering string equations of the form
\[
\sum_{I,I' = 1}^{N} p_{k,II'} (M, L) C_{II'} = \sum_{I,I' = 1}^{N} \bar{p}_{k,II'} (\bar{M}, \bar{L}) \bar{C}_{II'},
\]
\[
\sum_{I,I' = 1}^{N} q_{k,II'} (M, L) C_{II'} = \sum_{I,I' = 1}^{N} \bar{q}_{k,II'} (\bar{M}, \bar{L}) \bar{C}_{II'},
\]
where we assume that
\[
\bar{p}_{k}^{0} := \sum_{I,I' = 1}^{N} \bar{p}_{k,II'} (n, \Lambda) \bar{E}_{II'}, \quad \bar{q}_{k}^{0} := \sum_{I,I' = 1}^{N} \bar{q}_{k,II'} (n, \Lambda) \bar{E}_{II'}, \quad k = 1, \ldots, N,
\]
belong to the adjoint orbit \( \mathcal{O} \) of \( E_{kk} \Lambda, E_{kk} n, k = 1, \ldots, N \), i.e. there exists \( \bar{g} \in G \) such that
\[
\begin{align*}
p_{k}^{0} &= \bar{g} \cdot E_{kk} \Lambda \cdot \bar{g}^{-1}, \\
q_{k}^{0} &= \bar{g} \cdot E_{kk} n \cdot \bar{g}^{-1}.
\end{align*}
\]

For that aim, the proof needs to be modified only in the definition of \( D_{ja}^{0} \rightarrow \bar{g}^{-1} D_{ja} \bar{g}^{-1} \) and \( \sigma_{k}^{0} \rightarrow \bar{g}^{-1} \sigma_{k}^{0} \bar{g} \) and \( g \rightarrow \bar{g} \cdot \bar{g} \). Observe that elements in \( \mathcal{O} \) can be constructed in terms of operators \( \mathcal{C}_{k}, \mathcal{P} \) and \( \mathcal{Q} \), such that
\[
\sum_{k = 1}^{N} \mathcal{C}_{k} = 1_{N}, \quad \mathcal{C}_{k} \mathcal{C}_{k} = \delta_{kk} \mathcal{C}_{k}, \quad [\mathcal{C}_{k}, \mathcal{P}] = [\mathcal{C}_{k}, \mathcal{Q}] = 0, \quad [\mathcal{P}, \mathcal{Q}] = \mathcal{P}.
\]

What we do not know yet is if the orbit \( \mathcal{O} \) is characterized precisely by these properties. However, if we request the following properties: \( \mathcal{C}_{k} - E_{kk} \in \mathfrak{g}_{-}, \mathcal{P} - \Lambda \in \mathfrak{g}_{-}, \mathcal{Q} - n \in \mathfrak{g}_{-} \), one could prove, following similar arguments as in the proof of theorem 2, that these elements lay in \( \mathcal{O} \). This implies an alternative formulation of string equations (57):
\[
\sum_{I,I' = 1}^{N} \mathcal{C}_{k,II'} (L, M) C_{II'} = \bar{C}_{kk}, \quad \sum_{I,I' = 1}^{N} \mathcal{P}_{II'} (L, M) C_{II'} = \bar{L}, \quad \sum_{I,I' = 1}^{N} \mathcal{Q}_{II'} (L, M) C_{II'} = \bar{M}.
\]
3.4. Additional symmetries and string equations

3.4.1. Additional symmetries. Suppose that the operator \( g \) in (10) depends on an additional, or external, parameter \( b \), which might belong to \( \mathbb{C} \) or to \( \mathbb{Z} \). Now, we will describe the induced dependence on the elements defining the multicomponent Toda hierarchy. We shall denote by \( \partial_b = \partial / \partial b \) when \( b \in \mathbb{C} \) is continuous and by \( T_b \) the corresponding shift \( b \to b + 1 \), when \( b \in \mathbb{Z} \) is an integer. In this case, we shall replace (10) by the equivalent factorization problem

\[
W \cdot h = W \cdot \tilde{h},
\]

with

\[
g = h \cdot \tilde{h}^{-1}. \tag{73}
\]

Observe that for \( b \in \mathbb{C} \), we may write

\[
\partial_b W \cdot W^{-1} + W(\partial_b h \cdot h^{-1})W^{-1} = \partial_b S \cdot S^{-1} + W(\partial_b h \cdot h^{-1})W^{-1} = \partial_b \tilde{W} \cdot \tilde{W}^{-1} + \tilde{W}(\partial_b \tilde{h} \cdot \tilde{h}^{-1})\tilde{W}^{-1}, \tag{74}
\]

while for \( b \in \mathbb{Z} \) we have

\[
T_b W \cdot W^{-1} = (T_b h \cdot h^{-1}) \cdot W^{-1} = T_b S \cdot S^{-1} \cdot W \cdot (T_b h \cdot h^{-1}) \cdot W^{-1} = T_b \tilde{W} \cdot \tilde{W}^{-1} \cdot W \cdot (T_b \tilde{h} \cdot \tilde{h}^{-1}) \cdot \tilde{W}^{-1}. \tag{75}
\]

Now we suppose that the dependence on \( b \) is given by the following equations:

\[
\partial_b h \cdot h^{-1} = F_0 = \sum_{i,j=1}^{N} F_{i,j}(n, \Lambda) E_{i,j},
\]

\[
\partial_b \tilde{h} \cdot \tilde{h}^{-1} = \tilde{F}_0 = \sum_{i,j=1}^{N} \tilde{F}_{i,j}(n, \Lambda) E_{i,j} \quad \text{when} \quad b \in \mathbb{C}, \tag{76}
\]

\[
T_b h \cdot h^{-1} = F_0 = \sum_{i,j=1}^{N} F_{i,j}(n, \Lambda) E_{i,j},
\]

\[
T_b \tilde{h} \cdot \tilde{h}^{-1} = \tilde{F}_0 = \sum_{i,j=1}^{N} \tilde{F}_{i,j}(n, \Lambda) E_{i,j} \quad \text{when} \quad b \in \mathbb{Z},
\]

and define

\[
F := \sum_{i,j=1}^{N} F_{i,j}(M, L) C_{i,j}, \quad \tilde{F} := \sum_{i,j=1}^{N} \tilde{F}_{i,j}(M, \tilde{L}) \tilde{C}_{i,j} \quad \text{when} \quad b \in \mathbb{C}, \tag{77}
\]

\[
\mathcal{F} := \sum_{i,j=1}^{N} F_{i,j}(M, L) C_{i,j}, \quad \mathcal{F} := \sum_{i,j=1}^{N} \tilde{F}_{i,j}(M, \tilde{L}) \tilde{C}_{i,j} \quad \text{when} \quad b \in \mathbb{C}.
\]

From (74)–(75), we get

\[
\partial_b W \cdot W^{-1} = \partial_b S \cdot S^{-1} = -(F - \tilde{F})_-, \quad \partial_b \tilde{W} \cdot \tilde{W}^{-1} = \partial_b \tilde{S} \cdot \tilde{S}^{-1} = (F - \tilde{F})_+, \quad (F - \tilde{F})_{\pm} \in \mathfrak{g},
\]

\[
T_b W \cdot W^{-1} = T_b S \cdot S^{-1} = (\mathcal{F} \cdot \mathcal{F}^{-1})_-, \quad T_b \tilde{W} \cdot \tilde{W}^{-1} = T_b \tilde{S} \cdot \tilde{S}^{-1} = (\mathcal{F} \cdot \mathcal{F}^{-1})_+, \quad (\mathcal{F} \cdot \mathcal{F}^{-1})_{\pm} \in G_{\pm}
\]

so that

**Proposition 9.** Given a dependence on an additional parameter \( b \) according to (73) and (76), introduce \( H := F - \tilde{F} \) and \( \mathcal{H} := \mathcal{F} \cdot \mathcal{F}^{-1} \) where \( F \) and \( \tilde{F} \) are defined (77); then
(1) The dressing operators \( W \) and \( \tilde{W} \) satisfy the following equations:
\[
\partial_b W = -H_- \cdot W, \quad \partial_b \tilde{W} = H_+ \cdot \tilde{W}, \quad \text{or}
\]
\[
T_b W = \mathcal{H}_- \cdot W, \quad T_b \tilde{W} = \mathcal{H}_+ \cdot \tilde{W}.
\]

(2) The Lax and Orlov–Schulman operators are subject to
\[
\partial_b L = [-H_-, L], \quad \partial_b M = [-H_-, M], \quad \partial_b C_{kk} = -[H_-, C_{kk}],
\]
\[
\partial_b \tilde{L} = [H_+, \tilde{L}], \quad \partial_b \tilde{M} = [H_+, \tilde{M}], \quad \partial_b \tilde{C}_{kk} = [H_+, \tilde{C}_{kk}]
\]
\text{or}
\[
T_b L = \mathcal{H}_- \cdot L \cdot \mathcal{H}_-^{-1}, \quad T_b M = \mathcal{H}_- \cdot M \cdot \mathcal{H}_-^{-1}, \quad T_b C_{kk} = \mathcal{H}_- \cdot C_{kk} \cdot \mathcal{H}_-^{-1},
\]
\[
T_b \tilde{L} = \mathcal{H}_+ \cdot \tilde{L} \cdot \mathcal{H}_+^{-1}, \quad T_b \tilde{M} = \mathcal{H}_+ \cdot \tilde{M} \cdot \mathcal{H}_+^{-1}, \quad T_b \tilde{C}_{kk} = \mathcal{H}_+ \cdot \tilde{C}_{kk} \cdot \mathcal{H}_+^{-1}.
\]

3.4.2. String equations. The factorization problem (10) depends decisively on the ‘initial data’ \( g \). Now, we are going to see some consequences of the form of \( g \) and derive the so-called string equations. Let us suppose that given two operators
\[
F_0 := \sum_{l,l'=1}^N F_{ll'}(n, \Lambda) E_{ll'}, \quad \tilde{F}_0 := \sum_{l,l'=1}^N \tilde{F}_{ll'}(n, \Lambda) E_{ll'},
\]
we have the following constraint satisfied by \( g \):
\[
g \tilde{F}_0 = F_0 g.
\]

Then, if
\[
F(M, L) := \sum_{l,l'=1}^N F_{ll'}(M, L) C_{ll'}, \quad \tilde{F}(\tilde{M}, \tilde{L}) = \sum_{l,l'=1}^N \tilde{F}_{ll'}(\tilde{M}, \tilde{L}) \tilde{C}_{ll'},
\]
we have
\[
F(M, L) = \tilde{F}(\tilde{M}, \tilde{L}). \tag{80}
\]

We refer to these types of equations as string equations (see for example [27]) and we have seen that they reflect properties such as (79) of the initial condition \( g \) in (10).

Note that the reduction of (42) is a particular case of (79) with \( \tilde{F}_0 := \sum_{k=1}^N E_{kk} \Lambda^{-k} \) and \( F_0 := \sum_{k=1}^N E_{kk} \Lambda^k \), in which the Orlov–Schulman operator does not appear. This suggests an important family of diagonal string equations with
\[
F_0 := \sum_{k=1}^N E_{kk} F_{0,k}(n, \Lambda), \quad \tilde{F}_0 := \sum_{k=1}^N E_{kk} \tilde{F}_{0,k}(n, \Lambda). \tag{81}
\]

Equations (57) are also a set of string equations; moreover, the invariance conditions under the additional flow (78) imply that \( H = 0 \) or \( \mathcal{H} = \text{id} \) so that we are led to the string-type equations of form (80), namely
\[
F(M, L) = \tilde{F}(\tilde{M}, \tilde{L}) \quad \text{or} \quad F(M, L) = \tilde{F}(\tilde{M}, \tilde{L}). \tag{82}
\]

This also follows from
\[
\partial_b g = (\partial_b h \cdot h^{-1}) g - g (\partial_b \tilde{h} \cdot \tilde{h}^{-1}) = F_0 g - g \tilde{F}_0,
\]
\[
T_b g = (T_b h \cdot h^{-1}) \cdot g \cdot (T_b \tilde{h} \cdot \tilde{h}^{-1})^{-1} = \mathcal{F}_0 \cdot g \cdot \mathcal{F}_0^{-1}.
\]

Observe that if we consider arbitrary forms of \( F_0, \tilde{F}_0 \) or \( \mathcal{F}_0, \mathcal{F}_0 \), it will be the same to deal with the description given here or that obtained just setting \( \tilde{h} = \text{id} \). However, the situation is different if we consider the function \( F_0, \tilde{F}_0 \) or \( \mathcal{F}_0, \mathcal{F}_0 \) of the diagonal type (81). In this case, to set \( \tilde{h} = \text{id} \) will generically imply to abandon the diagonal family for \( F_0 \).
Acknowledgments

The authors wish to thank the Spanish Ministerio de Ciencia e Innovación, research projects FIS2005-00319 and FIS2008-00200, and acknowledge the support received from the European Science Foundation (ESF) and the activity entitled Methods of Integrable Systems, Geometry, Applied Mathematics (MISGAM). This paper was finished during the research visits of one of the authors (MM) to the Université Catholique de Louvain and to the Scuola Internazionale Superiore di Studi Avanzati/International School for Advanced Studies (SISSA) in Trieste. MM wishes to thank Professor van Moerbeke and Professor Dubrovin for their warm hospitality, acknowledge economical support from MISGAM and SISSA, and reckons different conversations with P van Moerbeke, T Grava, G Carlet and M Caffasso.

Appendix A. Congruences

We will show here how to derive from the multicomponent Toda hierarchy equations involving only the fields at each site \( n \in \mathbb{Z} \), i.e. not mixing fields at different values of \( n \), the sequence variable. This is particularly useful to show the role of the discrete multicomponent KP hierarchy in the multicomponent Toda hierarchy, which appears when we freeze the bared continuous and discrete times.

First, we present a queue observation.

**Proposition 10.** Let us suppose that we have operators \( R, \bar{R} \in g \) such that

\[
RW^{-1}_0 \in g_-, \quad \bar{R}W^{-1}_0 \in g_+,
\]

(A.1)

satisfying \( R \cdot g = \bar{R} \). Then \( R = \bar{R} = 0 \).

**Proof.** We have

\[
\bar{R} = Rg = RW^{-1}Wg = RW^{-1} \Rightarrow \bar{R}W^{-1} = RW^{-1};
\]

therefore \( \bar{R}W^{-1}S^{-1} = RW^{-1}S^{-1} \) and recalling (A.1), and the fact that \( S \in G_- \) and \( \bar{S} \in G_+ \), we conclude the statement. \( \square \)

Next, and without proof (which consist in a systematic and sometimes elaborated application of the previous result) we show the appearance of some well-known integrable hierarchies within the multicomponent Toda hierarchy. We first point out that continuous variables, and for each value of \( n \), we have solutions of the \( N \)-wave hierarchy and its modifications; moreover, some discretizations of the modified \( N \)-wave equations are proposed. These results are just a manifestation of the fact that if we freeze the bared times we are just dealing with a discrete \( N \)-component KP hierarchy in the spirit of [1]. Next, we recover within this context the quadrilateral lattice equations. Finally, we present what we call the dispersive Whitham hierarchy in complete analogy to that proposed in [29, 30].

**Theorem 4.** The dressing operators satisfy the following equations:

\[
\partial_{ja}W = Q_{ja}(W), \quad \bar{\partial}_{ja}\bar{W} = Q_{ja}(\bar{W}),
\]

(A.2)
where

\[ Q_{jk} = u_{jk,j} \partial^j + u_{jk,j-1} \partial^{j-1} + \cdots + u_{jk,0}, \]

\[ Q_{\bar{j}k} = v_{jk,j} \bar{\partial}^j + v_{jk,j-1} \bar{\partial}^{j-1} + \cdots + v_{jk,1} \bar{\partial}^{1}. \]

with the coefficients \( u_{jk,i}, v_{jk,i} \) depending on \( \partial_s \phi, \bar{\partial}_s \bar{\phi} \), respectively,

\[
\begin{align*}
Q_{jk} = & \sum_{i=0}^{\infty} \left( E_{kk} \partial^i + \phi E_{kk} - \sum_{a=0}^{i-1} u_{jk,j-a} \sigma_{j-a,i-a} \right), & i = 1, \ldots, j, \\
Q_{\bar{j}k} = & \sum_{i=0}^{\infty} \left( \bar{\phi} E_{kk} \bar{\partial}^i \sigma_{j-1,i-1,0} \right), & i = 0, \\
u_{jk,j-i} = & \left( \sum_{r=0}^{i} \binom{j}{r} \phi^r \sigma_{j-r,i-r} \right), & i = 1, \ldots, j-1, \\
v_{jk,j-i} = & \left( \sum_{r=0}^{i-1} \binom{j}{r} \bar{\phi}^r \bar{\sigma}_{j-r,i-r} \right) E_{kk} \bar{\partial}^r \bar{\sigma}_{j-1,i-1,0}, & i = 1, \ldots, j-1,
\end{align*}
\]

and

\[
\begin{align*}
\sigma_{j,i} := & \sum_{r=0}^{i-1} \binom{j}{r} \phi^r \sigma_{j-r,i-r}, \\
\bar{\sigma}_{j,i} := & \sum_{r=0}^{i} \binom{j}{r} \bar{\phi}^r \bar{\sigma}_{j-r,i-r}.
\end{align*}
\]

Observe that \( \sigma_{j1} = \beta \) and \( \bar{\sigma}_{j,0} = e^\phi \), and also that the first of the differential operators \( Q_{jk} \) and \( \bar{Q}_{jk} \) are given by

\[
\begin{align*}
Q_{jk} = & E_{kk} \partial^j + [\beta, E_{kk}] \partial^{j-1} + ([\varphi_2, E_{kk}] - j E_{kk} \partial \beta - [\beta, E_{kk} \beta]) \partial^{j-2} + \cdots + u_{jk,0}, \\
Q_{\bar{j}k} = & e^\phi E_{kk} e^{-\phi} \partial^j + (\bar{\phi} E_{kk} - \bar{\partial}^j E_{kk} e^{-\phi}) \partial^j - 1 + \cdots + v_{jk,1} \bar{\partial}.
\end{align*}
\]

**Lemma 2.** The only differential operators \( Q = u_j \partial^j + \cdots + u_0 \) and \( \bar{Q} = v_j \bar{\partial}^j + \cdots + v_0 \) such that

\[ Q(W) = 0, \quad \bar{Q}(\bar{W}) = 0 \]

are

\[ Q = \bar{Q} = 0. \]

**Proof.**

- Let us suppose that \( \sum_{i=0}^{j} u_i \partial^i W = 0 \) but \( \sum_{i=0}^{j} u_i \partial^i W = \left( \sum_{i=0}^{j} (u_i + \sum_{r=1}^{j-i} u_{ir} \sigma_{i+r,r}) \Lambda^i + g_+ \right) W_0 \). Thus, \( u_j = u_{j-1} = \cdots = u_0 = 0 \). Now assume that \( \sum_{i=1}^{j} v_i \bar{\partial}^i W = 0 \) and take into account that

\[
\begin{align*}
\sum_{i=1}^{j} v_i \bar{\partial}^i \bar{W} = & \left( \sum_{j=1}^{j} \left( \sum_{r=0}^{j-i} v_{jr} \bar{\sigma}_{i+r,r} \right) \Lambda^{-1} + g_+ \right) \bar{W}_0.
\end{align*}
\]

Thus, \( v_j = v_{j-1} = \cdots = v_1 = 0 \). \( \square \)

From this lemma, it follows that
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Proposition 11. The Zakharov–Shabat conditions
\[ \partial_{jk} Q_{il} - \partial_{il} Q_{jk} + [Q_{il}, Q_{jk}] = 0, \quad \partial_{jk} Q_{il} - \partial_{il} Q_{jk} + [Q_{il}, Q_{jk}] = 0 \]
hold.

Proof. Just consider the compatibility conditions of (A.2) together with lemma 2. □

The site-independent relations described in theorem 4 constitute the \( N \)-wave hierarchy, for the non-bared flows, and its modification for the bared flows. These multicomponent equations contain many integrable systems \([18]\); for \( N = 1 \), we have the KP equation in non-bared variables and the modified KP equation in bared variables, and for \( N = 2 \), the Davey–Stewartson equation in the \( t \)-variables and the Ishimori equation in the \( \bar{t} \)-variables. For \( N = 3 \), we find the 3-resonant wave system (\( t \)-variables) and a modified version of it (\( \bar{t} \)-variables).

Proposition 12. The \( N \)-wave equations
\[ \partial_{lk}[\beta, E_{ll}] - \partial_{ll}[\beta, E_{lk}] + [[\beta, E_{ll}], [\beta, E_{lk}]] = 0 \]
and the modified \( N \)-wave equations
\[ \partial_{lk}(v_l) - \partial_{ll}(v_k) + v_l \hat{\beta}(v_k) - v_k \hat{\beta}(v_l) = 0 \]
with \( v_k := \hat{\varphi}_0 E_{kk} \hat{\varphi}_0^{-1} \) are satisfied.

Proof. The \( N \)-wave equations appear as the compatibility of \( Q_{lk} = E_{kk} \partial_l + [\beta, E_{kk}] \). A ‘modified’ \( N \)-wave system \([18]\) appears when one considers compatibility \( \bar{Q}_{lk} = v_k \hat{\beta}, k = 1, \ldots, N \). □

Discrete versions of the modified \( N \)-wave equations.
For a fixed \( l = 1, \ldots, N \), let us introduce the following shift operator:
\[ \bar{T} := \sum_{k=1, k \neq l}^{N} T_{(k,l)} \]
and the operator
\[ \bar{X}(A) := \sum_{k \neq l} T_{(k,l)}(A) E_{kk}, \quad P_l := \sum_{k \neq l} E_{kk}, \quad A \in \mathfrak{g}. \]
Finally, we also introduce
\[ \Omega_k := V E_{kk} V^{-1}, \quad V := E_{ll} + \bar{X}(e^\phi), \]
and the difference operators
\[ \Delta_{(k,l)} := T_{(k,l)} - 1, \quad \hat{\Delta} := \sum_{k \neq l} \Delta_{(k,l)} = \bar{T} - (N - 1). \]

Proposition 13. The dressing operators \( W \) and \( \bar{W} \) satisfy
\[ \Delta_{(k,l)}(W) = \Omega_k \hat{\Delta}(W), \quad \Delta_{(k,l)}(\bar{W}) = \Omega_k \hat{\Delta}(\bar{W}). \]

Conjugate nets and quadrilateral lattices. We now show the role of conjugate nets and quadrilateral lattices as a part of the multicomponent Toda hierarchy. For this aim, we first prove
Proposition 14. If $\epsilon_i \in M_N(\mathbb{C}), i = 1, 2$, are such that $\epsilon_1 E_{kk} = \epsilon_2 E_{ll}$, then

\[
\epsilon_1 (\partial_{lk} - \beta_{kk}) W = \epsilon_2 (T_K - (T_K \beta_{ll} + I_N - E_{ll} - \pi_a)) W, \quad K = (l, a)
\]

\[
\epsilon_1 (\partial_{lk} - \beta_{kk}) \bar{W} = \epsilon_2 (T_K - (T_K \beta_{ll} + I_N - E_{ll} - \pi_a)) \bar{W}, \quad K = (l, a)
\]

\[
\epsilon_1 e^{-\phi} \partial_{lk} W = \epsilon_2 e^{-T \phi} (\Delta_K + \pi_a) W, \quad K = (l, a)
\]

\[
\epsilon_1 e^{-\phi} \bar{\partial}_{lk} W = \epsilon_2 e^{-T \phi} (\Delta_K + \pi_a) \bar{W}, \quad K = (l, a)
\]

A particular consequence is

\[
\epsilon_1 (\varphi_2 E_{kk} + \partial_{kk} \varphi_1 - \varphi_1 E_{kk} \varphi_1) = \epsilon_2 (T_K \varphi_2 E_{kk} + T_K \varphi_1 (I_N - E_{ll} - E_{kk}) + E_{ll} - (T_K \varphi_1 E_{kk} + I_N - E_{ll} - E_{kk}) \varphi_1).
\]

If we right multiply this relation by $E_{mm}'$ with $m' \neq k$ and we take

1. $\epsilon_1 = E_{mm}$ with $m \neq k$ and $\epsilon_2 = 0$
2. $\epsilon_1 = 0$ and $\epsilon_2 = E_{mm}$ with $m \neq k, l$
3. $\epsilon_1 = 0$ and $\epsilon_2 = E_{ll}$
4. $\epsilon_1 = \epsilon_2 = E_{kk}$

we find

\[
\partial_{lk} b_{mm'} - b_{mk} b_{km'} = 0, \quad \text{for } m, m' \neq k
\]

\[
\Delta_{(k,l)} b_{mm'} - (T_{(k,l)} \beta_{mk}) b_{km'} = 0, \quad \text{for } m, m' \neq k, l,
\]

\[
(T_{(k,l)} \beta_{mk}) b_{kl} + b_{ml} = 0, \quad m \neq k, l,
\]

\[
T_{(k,l)} \beta_{lm'} - (T_{(k,l)} \beta_{lk}) b_{km'} = 0, m' \neq k, l,
\]

\[
(T_{(k,l)} \beta_{lk}) b_{kl} - 1 = 0,
\]

\[
\partial_{lk} \log b_{km'} - (T_{(k,l)} \beta_{km'}) / b_{km'} + \Delta_{(k,l)} \beta_{kk} = 0, \quad m' \neq l,
\]

\[
\partial_{lk} \log b_{kl} + \Delta_{(k,l)} \beta_{kk} = 0.
\]

The dispersionfull Toda–Whitham hierarchy. We fix $l \in S$ and consider the shifts $T_{(a,l)}$ for $a \in S$ with $a \neq l$, and as we cannot put $a = l$ for $a' \in S, a' \neq l$.

Proposition 15.

1. For $a', l, a' \neq l$, there exist scalar operators

\[
\beta_{jl} = T_{(a',l)} + B_{j,l-1} T_{(a',l)}^{-1} + \cdots + B_{j,0},
\]

\[
\alpha_{jl} = \delta_{jl} + \alpha_{j,l-2} \delta_{jl}^{-2} + \cdots + \alpha_{j,0},
\]

where the coefficients $B_{j,l}$ and $\alpha_{j,l}$ are scalar polynomials in the $T_{(a',l)}$-shifts or the $\partial_{jl}$-derivatives of $\beta_{jl}, \varphi_{2,l} \ldots, \varphi_{j,l}$, respectively, for example $B_{j,l-1} = \beta_{jl} - T_{(a',l)} \beta_{jl}$

\[
\partial_{jl}(E_l W) = \beta_{jl}(E_l W) = \alpha_{jl}(E_l W), \quad \partial_{jl}(E_l \bar{W}) = \beta_{jl}(E_l \bar{W}) = \alpha_{jl}(E_l \bar{W}).
\]

(A.5)

2. For $a \neq l$, there exist scalar operators

\[
\beta_{ja} = B_{ja,l} T_{(a,l)} + \cdots + B_{ja,1} T_{(a,l)},
\]

\[
\alpha_{ja} = \delta_{ja} + \alpha_{j,a-2} \delta_{ja}^{-2} + \cdots + \alpha_{j,0}.
\]
where \( B_{i(a)} \) are scalar polynomials in the \( T_{(a,a)} \)-shifts of \( \beta_i k \), \( \varphi_{2,k} \), \( \ldots \), \( \varphi_{j,k} \) when \( a = k \) and of \( \varphi_{0,k} \), \( \ldots \), \( \varphi_{j-1,k} \) for \( a = k \), for example

\[
B_{j,a,i} = \begin{cases}
\beta_{i k} \bigg/ \phi_{i k}, & a = k \in \mathbb{S}, \\
\phi_{0 k} \bigg/ \phi_{0 k}, & a = k \in \mathbb{S},
\end{cases}
\]

such that for \( a \neq k \)

\[
\partial_j a (E_{i l} W) = \mathcal{B}_{j a} (E_{i l} W), \quad \partial_j a (E_{i l} \tilde{W}) = \mathcal{B}_{j a} (E_{i l} \tilde{W}).
\]

Appendix B. Proofs of propositions

- **Proposition 2.** Obviously (24) is implied by (21)–(23). It is also easy to conclude that (22) and (23) follow from (24). The non-trivial part of the proposition is to prove that (24) implies (21):

\[
T_{(a,b)} T_{(c,d)} = T_{(a,c)} T_{(b,c)} T_{(b,d)} T_{(c,b)} = T_{(a,c)} T_{(b,c)} T_{(b,d)} T_{(c,b)} = T_{(a,c)} T_{(b,d)} T_{(a,b)}.
\]

- **Proposition 3.** We only need to show that (38) implies (34) as the reverse is evident. We proceed as in the proof of proposition 2:

\[
(T_{(a,b)} \omega_{(c,d)}) \omega_{(a,b)} = (T_{(a,b)} (T_{(b,d)} \omega_{(a,b)}) (T_{(a,c)} \omega_{(c,b)}) (T_{(c,d)} \omega_{(a,c)}) (T_{(a,c)} \omega_{(c,d)}) (T_{(b,d)} \omega_{(a,b)}) (T_{(c,b)} \omega_{(a,c)})) \omega_{(a,c)}
\]

- **Proposition 4.** We do not prove the differential case and refer the reader to [32]. Therefore, we proceed to the remaining cases involving discrete times.

(1) We start by proving (33). First, from definition (20) we deduce that

\[
\partial_j a \omega_{K} \cdot \omega_{K}^{-1} = \partial_j a (uK \cdot \tilde{u}_{K}^{-1})_{-} \cdot (uK \cdot \tilde{u}_{K}^{-1})_{-}^{-1} + (uK \cdot \tilde{u}_{K}^{-1})_{-} \cdot \partial_j a (uK \cdot \tilde{u}_{K}^{-1})_{-}^{-1} \cdot (uK \cdot \tilde{u}_{K}^{-1})_{-}^{-1}
\]

\[
= \partial_j a (uK \cdot \tilde{u}_{K}^{-1})_{-} \cdot (uK \cdot \tilde{u}_{K}^{-1})_{-}^{-1} + (uK \cdot \tilde{u}_{K}^{-1})_{-}
\]

\[
\times (B_{j a} - uK B_{j a} uK) (uK \cdot \tilde{u}_{K}^{-1})_{-}^{-1}
\]

\[
= \partial_j a (uK \cdot \tilde{u}_{K}^{-1})_{-} \cdot (uK \cdot \tilde{u}_{K}^{-1})_{-}^{-1} + (uK \cdot \tilde{u}_{K}^{-1})_{-}
\]

\[
\times B_{j a} (uK \cdot \tilde{u}_{K}^{-1})_{-}^{-1} - \omega_{K} B_{j a} \omega_{K}^{-1}
\]

and similarly

\[
= \partial_j a (uK \cdot \tilde{u}_{K}^{-1})_{-} \cdot (uK \cdot \tilde{u}_{K}^{-1})_{-}^{-1} + (uK \cdot \tilde{u}_{K}^{-1})_{-} B_{j a} (uK \cdot \tilde{u}_{K}^{-1})_{-}^{-1} - \omega_{K} B_{j a} \omega_{K}^{-1}
\]

so that

\[
\partial_j a \omega_{K} \cdot \omega_{K}^{-1} + \omega_{K} B_{j a} \omega_{K}^{-1} = \partial_j a (uK \cdot \tilde{u}_{K}^{-1})_{-} \cdot (uK \cdot \tilde{u}_{K}^{-1})_{-}^{-1} + (uK \cdot \tilde{u}_{K}^{-1})_{-}
\]

\[
\times B_{j a} (uK \cdot \tilde{u}_{K}^{-1})_{-}^{-1} - \partial_j a (uK \cdot \tilde{u}_{K}^{-1})_{-} \cdot (uK \cdot \tilde{u}_{K}^{-1})_{-}^{-1} B_{j a} (uK \cdot \tilde{u}_{K}^{-1})_{-}^{-1} + (uK \cdot \tilde{u}_{K}^{-1})_{-} B_{j a} (uK \cdot \tilde{u}_{K}^{-1})_{-}^{-1}.
\]
Now, using (34) and the commuting character of the Lax operators we get
\[ T_K B_{ja} = (U_K \cdot \bar{U}_K^{-1})_\gamma R_{ja} (U_K \cdot \bar{U}_K^{-1})_\gamma^{-1} - T_K (R_{ja} - \bar{R}_{ja}) - \]
\[ = (U_K \cdot \bar{U}_K^{-1})_\gamma \bar{R}_{ja} (U_K \cdot \bar{U}_K^{-1})_\gamma + T_K (R_{ja} - \bar{R}_{ja}) - \]
and we deduce for \( I := \partial_{ja} \omega_K \cdot \omega_K^{-1} + \omega_K B_{ja} \omega_K^{-1} - T_K B_{ja} \) the following expressions:
\[ I = \partial_{ja} (U_K \cdot \bar{U}_K^{-1})_\gamma \cdot (U_K \cdot \bar{U}_K^{-1})_\gamma^{-1} - (U_K \cdot \bar{U}_K^{-1})_\gamma (R_{ja} - \bar{R}_{ja}) - (U_K \cdot \bar{U}_K^{-1})_\gamma^{-1} \]
\[ + T_K (R_{ja} - \bar{R}_{ja}) - \]
\[ = \partial_{ja} (U_K \cdot \bar{U}_K^{-1})_\gamma \cdot (U_K \cdot \bar{U}_K^{-1})_\gamma^{-1} + (U_K \cdot \bar{U}_K^{-1})_\gamma (R_{ja} - \bar{R}_{ja}) + (U_K \cdot \bar{U}_K^{-1})_\gamma^{-1} \]
\[ - T_K (R_{ja} - \bar{R}_{ja}) + \]
which hold only if \( I = 0 \), as desired.

(2) Let us now prove (34). From (20) and (31), we get
\[ T_K \omega_K = T_K (U_K \bar{U}_K^{-1})_\gamma \cdot \omega_K U_K \omega_K^{-1} = T_K (U_K \bar{U}_K^{-1})_\gamma \cdot \omega_K \bar{U}_K \omega_K^{-1} \]
or again using (20)
\[ T_K \omega_K \cdot \omega_K = T_K (U_K \bar{U}_K^{-1})_\gamma \cdot (U_K \bar{U}_K^{-1})_\gamma U_K \omega_K = T_K (U_K \bar{U}_K^{-1})_\gamma \cdot (U_K \bar{U}_K^{-1})_\gamma \bar{U}_K \omega_K. \]
Then, we deduce
\[ (T_K \omega_K \cdot \omega_K)_\gamma = (U_K U_K)_\gamma, \quad (T_K \omega_K \cdot \omega_K)_\gamma = (U_K \bar{U}_K^{-1})_\gamma. \]
Interchanging \( K \leftrightarrow K' \) and recalling the commuting character of the Lax operators, we get the desired result.

- **Proposition 6.** Let \( a_{ij} \) denote the elements of the bi-infinite matrix \( g_{k,\ell} \); we now proceed to analyze the meaning of (49) in different situations.

  - **Block Hankel case.** Let us assume that \( \ell_{k_1} \ell_{k_2} > 0 \). In particular, let us discuss the case where both integers are positive. If we start from element \( a_{ij} \), equation (49) says that it is equal to some other element. To determine this element in the matrix, we observe that (49) requires to move in the \( rth \) row \( \ell_{k_1} \ell_{k_2} \) positions to the right and in the diagonal passing through that position go left \( \ell_{k_2} \) positions on this diagonal, i.e. go up \( \ell_{k_2} \) positions and to the left also \( \ell_{k_1} \) positions. This gives us the block structure over off-diagonals as illustrated below.

  ![Diagram](image.png)

  For negative integers \( \ell_{k_1}, \ell_{k_2} < 0 \) we have a similar discussion, replacing right motions in the row with left motions and up motions in the diagonal with down motions in the diagonal, and the same block Hankel structure appears.
- **Block Toeplitz case.** We now assume that \( \ell_k \ell_{k_2} < 0 \). Suppose that \( \ell_k \) is positive. Then, when \( \ell_k > |\ell_{k_2}| \) if we start from element \( a_{ij} \), equation (49) says that it is equal to some other element, say \( a_{i-j} \). To determine row \( i' \) and column \( j' \), we observe that (49) tells us to advance in the \( i \)th row \( |\ell_{k_2}| - |\ell_k| \) positions to the right and in the diagonal passing through that position go left \( \ell_k \) positions on this diagonal, i.e. go up \( \ell_k \) positions and to the left also \( \ell_k \), positions, so that we have

\[
a_{ij} = a_{i-\ell_k, j+|\ell_k|} = a_{i-\ell_k, j-|\ell_k|}.
\]

For the case \( \ell_k < |\ell_{k_2}| \) we use \( g_{j,k,k_2}(n) = g_{j+|\ell_k|, k,k_2}(n + \ell_k) \) so that we move \( |\ell_{k_2}| - \ell_k \) positions to the right and on the diagonal \( \ell_k \) positions down, which amounts to \( \ell_k \) rows down and \( \ell_k \) columns right, i.e.

\[
a_{ij} = a_{i-\ell_k, j+|\ell_{k_2}| - \ell_k, j+|\ell_{k_2}|} = a_{i-\ell_k, j-|\ell_{k_2}|}
\]

and we get the same result, which immediately tells us about the block structure over diagonals as illustrated below.

A similar discussion goes on for the case of negative \( \ell_k \) and positive \( \ell_{k_2} \).

- The case \( \ell_k = 0 \) with \( \ell_{k_2} \neq 0 \) gives \( g_{j,k,k_2}(n) = g_{j+\ell_{k_2}, k,k_2}(n) \), which implies a diagonal band structure, whether for \( \ell_{k_2} = 0 \) with \( \ell_k \neq 0 \) gives \( g_{j,k,k_2}(n) = g_{j+\ell_k, k,k_2}(n + \ell_k) \), which describes a \( \ell_k \times \ell_k \) block structure. Note that these two cases can only exist for two or more components.

- **Proposition 7.** Let us compute

\[
M = WnW^{-1} = SW_0\mu W_0^{-1} S^{-1}, \quad (B.1)
\]

\[
\bar{M} = \bar{W}n\bar{W}^{-1} = \bar{S}W_0\bar{\mu}W_0^{-1} \bar{S}^{-1} \quad (B.2)
\]

for this aim, we must take into account that

\[
\mu := W_0nW_0^{-1} = n + v, \quad v = \sum_{k=1}^{N} E_{kk} \left( s_k + \sum_{j=1}^{\infty} j t_{jk} \Lambda^j \right),
\]

\[
\bar{\mu} := \bar{W}_0n\bar{W}_0^{-1} = n + \bar{v}, \quad \bar{v} = -\sum_{k=1}^{N} E_{kk} \left( s_k + \sum_{j=1}^{\infty} j t_{jk} \Lambda^{-j} \right). \quad (B.3)
\]

Therefore, from (B.1) and (B.2) we deduce that

\[
M = S\mu S^{-1} = SnS^{-1} + \sum_{k=1}^{N} C_{kk} \left( s_k + \sum_{j=1}^{\infty} j t_{jk} L^j \right),
\]

\[
\bar{M} = \bar{S}\bar{\mu} \bar{S}^{-1} = \bar{S}n\bar{S}^{-1} - \sum_{k=1}^{N} \bar{C}_{kk} \left( s_k + \sum_{j=1}^{\infty} j t_{jk} L^{-j} \right).
\]
Finally,
\[ \mathcal{M} := S_n S^{-1} = (1 + \beta(n) \Lambda^{-1} + \varphi_2(n) \Lambda^{-2} + \cdots) n (1 + \beta(n) \Lambda^{-1} + \varphi_2(n) \Lambda^{-2} + \cdots)^{-1} \]
\[ = n - \beta(n) \Lambda^{-1} + \cdots, \]
\[ \tilde{\mathcal{M}} := \tilde{S}_n \tilde{S}^{-1} = (\tilde{e}^{\varphi(n)} + \tilde{\varphi}_1(n) \Lambda + \cdots) n (\tilde{e}^{\varphi(n)} + \tilde{\varphi}_1(n) \Lambda + \cdots)^{-1} \]
\[ = n + \tilde{\varphi}_1(n) e^{-\varphi(n+1)} \Lambda + \cdots. \]

**Proposition 8.** Let us take \( W \) of theorem 2 and consider \( \Theta_{kl} := W^{-1} C_{kl} W \) which satisfy 
\[ [\Theta_{kl}, \Lambda] = [\Theta_{kl}, n] = 0 \]
and hence \( \Theta_{kl} \) do not depend on \( \Lambda \) nor on \( n \). Now,
\[ E_{k'l'} \Theta_{kl} = \delta_{k'l'} \Theta_{kl}, \quad \Theta_{kl} E_{k'l'} = \delta_{k'l'} \Theta_{kl} \quad \Rightarrow \quad \Theta_{kl} = \bar{\Theta}_{kl}, \quad \Theta_{kl} \in \mathbb{C}, \]
\[ E_{k'l'} \tilde{\Theta}_{kl} = \delta_{k'l'} \tilde{\Theta}_{kl}, \quad \tilde{\Theta}_{kl} E_{k'l'} = \delta_{k'l'} \tilde{\Theta}_{kl} \quad \Rightarrow \quad \tilde{\Theta}_{kl} = \bar{\tilde{\Theta}}_{kl}, \quad \tilde{\Theta}_{kl} \in \mathbb{C}. \]
Thus,
\[ C_{kl} = W \Theta_{kl} W^{-1} = SW_0 \bar{\Theta}_{kl} E_{kl} W_0^{-1} S^{-1} = \partial_{kl} L^g e^{\sum_{j>1} (t_{jk} - t_{k}) L_j} (E_{kl} + g_{\cdots}) \]
\[ \Rightarrow \quad \partial_{kl} = 1 \Rightarrow C_{kl} = W E_{kl} W^{-1}. \]

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