On a systematic bias in SBF-based distances due to gravitational microlensing

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ABSTRACT

The effect of gravitational microlensing on the determination of extragalactic distances using surface brightness fluctuations (SBF) technique is considered and a method to calculate SBF amplitudes in presence of microlensing is presented. With a simple approximation for the magnification power spectrum at low optical depth the correction to the SBF-based luminosity distance is calculated. The results suggest the effect can be safely neglected at present but may become important for SBF-based Hubble diagrams at luminosity distances of about 1 Gpc and beyond.

Key words: gravitational lensing – methods: analytical – stars: statistics – galaxies: distances and redshifts – galaxies: stellar content – dark matter

1 INTRODUCTION

For many centuries, measuring distances to celestial objects has been a central part of astronomy. Historically, building on the trigonometric parallax technique, astronomers have developed a long cosmic distance ladder, within which every step is supplied by observing more and more luminous objects further and further away, whose calibration is based on distances obtained at preceding steps.

About two decades ago a new method to determine extragalactic distances using surface brightness fluctuations (SBFs) was proposed by Tonry & Schneider (1988). The method relies on a simple but powerful idea that less numerous stellar populations show greater relative fluctuations in their total brightness as Poissonian fluctuations in the number of stars are more pronounced in them compared to more numerous ones. This allows one to estimate the true average number of stars in and therefore intrinsic luminosities of pixels in images of distant galaxies. Comparing these estimates with the observed flux then estimates the luminosity distance directly. Although the idea of the method was clear to some astronomers long ago (see comments in Tonry & Schneider 1988), it was not until the mass introduction of linear panoramic detectors (CCDs) into astronomical observations, that the method could be usefully employed.

Since then, SBF technique has proven extremely fruitful in independent distance determination for galaxies and also in studies of their stellar populations (for review material, see Blakeslee, Ajhar & Tonry 1999 or Blakeslee, Vazdekis & Ajhar 2001). Various ways for the calibration of surface brightness fluctuations – both empirically and on the basis of stellar evolution simulations – have been developed, allowing to reduce uncertainty in distance determination to the level of five to ten per cent, making it one of the most precise methods in extragalactic astronomy. The range of the method has also increased nearly ten-fold compared to original estimates, and the distances to galaxies at nearly 200 Mpc have been successfully measured using the Hubble Space Telescope (Jensen et al. 2001).

Since the major limiting factor in the implementation of the method is photon noise, the trend in SBF observations has been towards the infrared for at least a decade, as one gets more infrared photons at a given flux level and the SBF signal is dominated by late-type giant stars. In addition, IR surface brightness fluctuations turned to be very interesting for stellar populations studies (e.g., Jensen et al. 2003; Mouhcine, Gonzalez & Liu 2001).

One of the external factors which can potentially contribute to the fluctuations of stellar magnitudes is gravitational microlensing by compact objects in the Universe. The presence of such population has been inferred from long-term photometrical monitoring of quasars (Hawkins 1993, 1994). The effect of such population on photometrical and spectroscopical properties of quasars has been considered previously (Canizares 1982; Dalcanton et al. 1994) and useful observational constraints on the properties of such population have been obtained (Schneider 1993).

This effect has been proposed as a tool to detect dark objects in galaxy clusters by observing temporal variations in the flux of a given pixel (Lewis, Ibar & Wyithe 2000; Lewis & Ibar 2001; Tuntsov et al. 2004). However, microlensing also introduces extra scatter in flux variations among different pixels and makes the distances inferred via...
SBF method systemically lower than the true ones. The correction due to microlensing increases with redshift dramatically, and the compact objects therefore have a potential to profoundly affect SBF-based Hubble diagrams at high $z$.

In the present paper, we investigate how strong this effect is and whether it represents a serious issue for the present-day SBF observations. Borrowing some technique from our previous work on galaxy clusters (Tuntsov et al. 2004), we show how microlensing can be taken into account for SBF studies, and then calculate relevant quantities under some general assumptions about potential microlensing population.

We start in Section 2 with an alternative derivation of the SBF amplitude which allows to take microlensing into account. Section 3 presents a simple summation approximation we use for the magnification spatial power spectrum and discusses a possible contribution to microlensing by an occasional intervening low surface brightness galaxy on the line of sight to the source. Then, in section 4 we first show that the interstellar correlations within the pixel can be neglected and then introduce and calculate the correction to SBF distances due to microlensing for simulated stellar populations. Section 5 discusses our results.

2 SURFACE BRIGHTNESS FLUCTUATIONS IN PRESENCE OF MICROLensing

The method to estimate extragalactic luminosity distances $d$ using surface brightness fluctuations (SBF) aims at measuring the ratio between the dispersion and average value of the flux at the pixels comprising a distant galaxy image

$$\frac{\sigma_F^2}{\langle F \rangle} = \frac{1}{4\pi d^2} \langle L \rangle,$$

where $L$ is the total luminosity of the pixel. For a given stellar population of the galaxy, the second fraction on the right-hand side of this equation can be calculated using stellar evolution models. Alternatively, one can assume that this quantity does not vary much from one galaxy to another once they have similar stellar populations in terms of age and metallicity and determine its value by calibrating it on a sample of nearby galaxies for which the distance $D$ can be obtained via other methods.

Any particular implementation of the method needs to find a way to estimate the intrinsic value of $\sigma_F^2/\langle F \rangle$ from an observed CCD image of the galaxy getting rid of different sources of noise present in the real image in comparison to an ideal one — non-independence of the pixels introduced by a finite-width point-spread function of the optical system, contamination due to globular clusters of the target galaxy, photon count fluctuations and readout noise, sky background etc. Advanced methods to do so have been developed over two decades which have passed since the method was proposed by Tonry and Schneider (1988) and the intrinsic — in the sense that they are unaffected by the sources of noise just mentioned — fluctuations in the flux can now be measured with high precision.

However, the interpretation of the quantity $L$ has always been that it is the true luminosity of the stars comprising a pixel, i.e. the sum of the luminosities of all stars the pixel contains. Such an interpretation does not take into account that the observed flux contributed by a star can in fact be affected by microlensing en route to the observer. In this paper we investigate whether this is an observationally important issue and in which ways microlensing affects distance determination. Since $\sigma_F^2/\langle F \rangle$ can be determined from observations and there is such a simple relation between this ratio, distance $d$ and $\sigma_L^2/\langle L \rangle$, we will focus on the latter quantity and the way these apparent pixel luminosity fluctuations are affected by microlensing.

In the method establishing paper of Tonry and Schneider (1988), $\sigma_L^2/\langle L \rangle$ was computed in a ‘filling number’ fluctuations manner. That is, it was assumed that there is a certain number of different luminosity levels $l_k$ (minuscule letter $l$ is used for individual star luminosities while the capital $L$ is reserved for the total luminosity of the pixel), and the number $N_k$ of stars of a certain type $k$ in the pixel is a Poissonian random variable with the mean parameter $\bar{N}_k = \bar{N} \phi_k$, where $\bar{N}$ is the mean number of stars in the pixel and $\phi_k$ is the luminosity distribution. This method is not applicable when microlensing is involved and we will be forced to take a less elegant approach, assuming instead that luminosity of a given star is a random variable with distribution $\phi_k$, and the total number of stars in the pixel is a Poissonian variable; microlensing magnification value will also be introduced as a random function. It is therefore reasonable to compare the two types of calculations and point out assumptions of the original methods which do not hold when microlensing is involved.

The original gives the following value for the total luminosity of the pixel:

$$L = \sum_k l_k N_k.$$  \hspace{1cm} (2)

To find its average value one averages the filling numbers:

$$\langle L \rangle = \langle \sum_k l_k N_k \rangle = \sum_k l_k \langle N_k \rangle = \sum_k l_k \bar{N}_k = \bar{N} \langle l \rangle \phi.$$  \hspace{1cm} (3)

where $\langle l \rangle \phi$ is the average individual star luminosity determined by its distribution $\phi$. The square of this quantity is

$$\langle L \rangle^2 = \sum_k (l_k \bar{N}_k) + \sum_{k \neq k'} l_k \bar{N}_k \langle N_{k'} \rangle$$

The average of the luminosity squared $L^2$ is, similarly,

$$\langle L^2 \rangle = \sum_k (l_k \bar{N}_k)^2 + \sum_{k \neq k'} l_k l_{k'} \langle N_k N_{k'} \rangle$$

and for the dispersion $\sigma_L^2 = \langle L^2 \rangle - \langle L \rangle^2$ one has

$$\sigma_L^2 = \sum_k (l_k \bar{N}_k)^2 \left( \langle N_{k'}^2 \rangle - \langle N_{k'} \rangle^2 \right)$$

$$+ \sum_{k \neq k'} l_k l_{k'} \left( \langle N_k N_{k'} \rangle - \langle N_k \rangle \langle N_{k'} \rangle \right)$$

The value in the brackets on the first line of the right-hand side is, for Poissonian distribution, $\sigma_{N_k}^2 = \bar{N}_k = \bar{N} \phi_k$ while the second line vanishes as $\langle N_k N_{k'} \rangle = \langle N_{k'} \rangle \langle N_k \rangle$ because the numbers of different stars in the pixel are independent –
at least, this is a very reasonable approximation if the galaxy stellar population is considered homogeneous. As a result, one has

$$\sigma_L^2 = \bar{N} \sum_k (l_k^2) \phi_k = \bar{N} \langle l^2 \rangle_\phi.$$  \hspace{1cm} (7)

Since Poissonian statistics remains valid for arbitrary low mean numbers $\bar{N}_k$, the transition to continuous distribution density $\phi(l)$ requires no effort.

The independence mentioned above is lost when microlensing is introduced – the magnification values $\mu$ inside the pixel are correlated: knowledge that a certain number $N_j$ of stars have magnification value $\mu_j$ can be used to predict the probability that the number of stars with magnification $\mu_j$ is $N_j$. We therefore have to resort to a different solution.

In an alternative approach, the values considered random are

- the total number of stars in the pixel $N$, its distribution is assumed Poissonian with mean $\bar{N}$;
- the type of each star, characterized by its luminosity $l_i$ and spatial profile $\psi_i(r)$ ($i = \bar{1}, \bar{N}$); the values of the luminosity $l$ will be randomly drawn with the distribution $\phi(l)$ independently of each other;\footnote{For simplicity, we assume a unique relation between $l_i$ and $\psi_i$, although index $i$ can denote both without any changes to the notation.}
- the coordinates of each star within the pixel $r_i$ with $i = \bar{1}, \bar{N}$, these coordinates will be considered independently and uniformly distributed in the pixel;
- the magnification field realization $\mu(r)$, its properties will be specified as we progress through the calculation.

When calculating $\sigma_L^2$, we will have to average with respect to all of these quantities, and, where necessary, appropriate averages will be denoted by $N$, $\phi$, $r$ or $\mu$ subscripts at the angled brackets, respectively.

Then, the apparent luminosity of a certain realization of the pixel is

$$L = \sum_i l_i \mu_i(r_i).$$  \hspace{1cm} (8)

As the magnification can depend on the type of the source star – most importantly, its size, – $\mu$ was given the index $i$ as well. These values can be calculated by convolving $\psi_i(r)$ and the underlying magnification map $\mu_i(r)$ and therefore $\mu_i$ Fourier transform is the product of $\psi_i$ and $\mu$ transforms (times $2\pi$ as we choose Fourier transformation kernel normalization in symmetric convention such that only the phase is reversed in the inverse transform):

$$\tilde{\mu}_i(k) = \tilde{\psi}_i(k)2\pi\tilde{\psi}_i(k)$$  \hspace{1cm} (9)

In particular, for a statistically homogeneous magnification map the average does not depend on $r$:

$$\langle \tilde{\mu}(k) \rangle_\mu = \langle \mu \rangle 2\pi\delta(k),$$  \hspace{1cm} (10)

where $\langle \mu \rangle$ is the average magnification. Therefore,

$$\langle \mu \rangle = \langle \mu \rangle 2\pi\tilde{\psi}_i(0) = \langle \mu \rangle_\mu.$$

Since $2\pi\tilde{\psi}_i(0) = 1$ – it is more convenient to put the normalization of the spatial profile into the value of $l_i$. Then, one has

$$\langle L \rangle = \left\langle \sum_{i=1}^N (l_i \langle \mu \rangle_\mu) \right\rangle = \bar{N} \langle \mu \rangle_\mu \langle l \rangle_\phi.$$  \hspace{1cm} (12)

The square of the pixel luminosity is

$$L^2 = \sum_{i}^N l_i^2 \mu_i^2(r_i) + \sum_{i \neq i'} l_i l_{i'} \mu_i \mu_{i'}(r_i) r_{i'}.$$  \hspace{1cm} (13)

One first averages this over different $\mu(r)$ realizations

$$\langle L^2 \rangle_\mu = \sum_{i}^N l_i^2 \langle \mu_i^2(r_i) \rangle_\mu + \sum_{i \neq i'}^N l_i l_{i'} \langle \mu_i \mu_{i'}(r_i) r_{i'} \rangle_\mu.$$  \hspace{1cm} (14)

Homogeneity of the underlying magnification map $\mu(r)$ implies that its autocorrelation function depends only on the difference of its arguments:

$$\langle \tilde{\mu}_{i}(k) \tilde{\mu}_{i}(k) \rangle_\mu = P_{\mu}(k)\delta(k + k'),$$  \hspace{1cm} (15)

where $P_{\mu}(k)$ is the magnification spatial power spectrum, or $2\pi$ the Fourier transform of the autocorrelation function. It follows then that the factor in front of a $\delta$-function in the Fourier transform of the cross-correlation between the magnifications of stars $i$ and $i'$ is

$$P_{\psi i}(k) = P_{\mu}(k)4\pi^2 \tilde{\psi}_i(k) \tilde{\psi}_{i'}(-k)$$  \hspace{1cm} (16)

and, in particular, the diagonal values of the cross-correlation matrix are independent of $r$:

$$\langle \mu_i^2(r) \rangle_\mu = \int \mathrm{d}^2k P_{\mu}(k) \tilde{\psi}_i(k)^2 = \langle \mu_i^2 \rangle_\mu.$$  \hspace{1cm} (17)

Averaging with respect to $r_i$ is performed by convolving with the distribution of $r_i$, $i = \bar{1}, \bar{N}$. Since these coordinates are assumed independent and uniformly distributed in the pixel $S$ of area $||S||$, this leads to

$$\left\langle L^2 \right\rangle_{\mu, r_i} = \sum_{i}^N l_i^2 \langle \mu_i^2 \rangle_\mu + \sum_{i \neq i'}^N l_i l_{i'} \langle \mu_i \mu_{i'} \rangle S_s.$$  \hspace{1cm} (18)

where the average value of the correlation function

$$\langle \mu_i \mu_{i'} \rangle_S = \int \frac{\mathrm{d}^2r_1 \mathrm{d}^2r_2}{||S||^2} \langle \mu_i(r_1) \mu_{i'}(r_2) \rangle_\mu$$  \hspace{1cm} (19)

can be computed using $\left(19\right)$:

$$\langle \mu_i \mu_{i'} \rangle_S = \int \frac{\mathrm{d}^2k P_{\mu}(k) \tilde{\psi}_i(k) \tilde{\psi}_{i'}(k) ||\tilde{s}(k)||^2}{2\pi^2}.$$  \hspace{1cm} (20)

Here $\tilde{s}(k)$ is the coordinates characteristic function, or the Fourier transform of its distribution density $s(r)$:

$$s(r) = ||S||^{-1} \left\{ \begin{array}{ll} 1, & r \in S \\ 0, & r \notin S \end{array} \right.$$  \hspace{1cm} (21)

Since each star type is chosen independently of all others, one has

$$\langle l_i^2 \langle \mu_i^2 \rangle_\mu \rangle_\phi = \langle l^2 \rangle_\phi \int \mathrm{d}^2k P_{\mu}(k) ||\tilde{s}(k)||_\phi.$$  \hspace{1cm} (22)
\[ \langle |d_L| \mu (\mu_i) S \rangle_\phi = \langle l \rangle_\phi \int d^2 k \, P_\mu (\mathbf{k}) \langle |\hat{\psi}(\mathbf{k})| \rangle_\phi^2 / 2\pi \hat{s}(\mathbf{k})^2, \]  

where the ‘luminosity-weighed’ averages of the source star profile \( \langle \hat{\psi}(\mathbf{k}) \rangle \) and its square \( \langle |\hat{\psi}|^2(\mathbf{k}) \rangle \) have been introduced as, respectively,

\[ \langle \hat{\psi}(\mathbf{k}) \rangle_\phi \equiv \langle l \rangle_\phi^{-1} \langle |l, \hat{\psi}_i(\mathbf{k})| \rangle_\phi \]  

and

\[ \langle |\hat{\psi}|^2(\mathbf{k}) \rangle_\phi \equiv \langle l^2 \rangle_\phi^{-1} \langle |l, \hat{\psi}_i(\mathbf{k})|^2 \rangle_\phi. \]

The number of equal terms in the first and second sums of the magnification fluctuations \( \Delta \mu \) are \( \bar{\mu} \) and \( \bar{\mu} \bar{\sigma} \), respectively, as, respectively,

\[ \bar{\mu} \equiv \mu_{\text{phys}} \]  

and

\[ \bar{\mu} \bar{\sigma} \equiv \mu_{\text{phys}} \bar{\sigma}. \]

We can change the second term of the last equation into a more intuitively clear form by noticing that \( \bar{\psi} = (2\pi)^{-1} \) and \( 2\pi \bar{s}(0) = 1 \) while Fourier transform of a constant is proportional to a \( \delta \)-function. As a result, the value in the brackets can be calculated as

\[ \bar{P} \psi S_{\mu} \equiv \bar{P} \psi S - \mu^2 \mu \equiv \int d^2 k \, P_{\Delta \psi}(\mathbf{k})(|\hat{\psi}(\mathbf{k})|)^2 / 2\pi \bar{s}(\mathbf{k})^2, \]

where \( P_{\Delta \psi}(\mathbf{k}) = P_{\psi}(\mathbf{k}) - 4\pi^2 \mu^2 \bar{s}(\mathbf{k}) \) is the power spectrum of the magnification fluctuations \( \Delta \mu(r) = \mu(r) - \langle \mu \rangle \).

The dispersion and average value of the observed flux in the pixel \( F \) differ from those of the luminosity by factors \((4\pi d^2)^{-2} \) and \((4\pi d^2)^{-1} \), respectively. In the absence of microlensing – \( \langle \mu \rangle = 1, \mu^2 = 1, \bar{P} \Delta \psi = 0 \) – this gives the following estimate for the luminosity distance \( d \):

\[ d^{-2} = 4\pi \sigma_F^2 / \langle l \rangle^2. \]

By comparing this formula with \( \bar{P} \psi S \) and \( \bar{P} \mu \mu \), one finds that when lensing is important this estimate is biased compared to the true distance \( d \). The relationship between the two values reads:

\[ d^{-2} = d^{-2} \frac{\langle \mu^2 \rangle}{\mu^2} + 4\pi \frac{\langle F \rangle}{\langle l \rangle} \frac{\bar{P} \psi S}{\bar{P} \Delta \psi} \]

or

\[ d^{-2} = d^{-2} \frac{\langle \mu^2 \rangle}{\mu^2} + N \frac{\langle l \rangle^2}{\langle l^2 \rangle} \frac{\bar{P} \psi S}{\bar{P} \Delta \psi}. \]

Since \( \mu \geq 1 \) and \( \bar{P} \Delta \psi \geq 0 \), the estimate \( d \) is systematically lower than the true value \( d \) – microlensing introduces extra scatter in the pixel fluxes; in addition, mass along the line of sight makes distant sources generally brighter on average (the first term on the right-hand side of \( \langle \mu^2 \rangle / \mu = \langle \mu \rangle + (\Delta \mu^2 / \langle \mu \rangle) \), but this magnification effect is less important than the additional scatter (see discussion in section 4).

The second term in \( \bar{P} \psi S \) is the most troublesome as it could potentially change the recipe for \( \sigma_F^2 / \langle L \rangle \) empirical determination – the ratio between the local fluctuation amplitude and mean would no longer be constant and the way the mean is subtracted would have to be changed. However, as we demonstrate below, typical correlation scale of the magnification map is much smaller than the typical distance between the stars. Hence, the correlation term is small.

Further to this point, the calculation presented above does not take into account any correlations which can arise between different pixels; taking these correlations into account would force us to significantly extend this simple study by reconsidering the way in which the intrinsic fluctuations in the flux are related to the observed CCD measurement statistics. However, interpixel correlations are much weaker than interstellar ones and can thus be safely neglected.

Finally, another important thing that should be addressed is the convergence of the variance. Here we only calculate the dispersion of the magnification value distribution, which is an overestimate of the most likely variance of a finite sample of \( N_\star \) stars forming the galaxy. This happens because, for a small source, the dispersion is dominated by a long \( \propto \mu^{-3} \) tail of the distribution density (Peacock 1989), which is in fact unlikely to be properly populated by the stars. We can estimate the impact of this shortcoming by considering a model magnification distribution density

\[ p(\mu) = \frac{2(\mu_0 - 1)^2 (\mu - 1)}{([\mu - 1]^2 + (\mu_0 - 1)^2)^2}, \]

that takes into account three major theoretically established properties of the magnification distribution function (correct normalization and the first moment \( \mu \) and the large \( \mu \) behaviour; see Tuntsov et al. 2004 for further details) for \( \mu_0 = 1 - 2(\bar{\mu} - 1)/\pi \). In order to model the finite sample effect, we, when calculating the dispersion, will truncate the integration not at the value \( \mu_{\text{max}} = 2\bar{\mu}/R \) determined by the source size \( R \) relative to the projection of the Einstein radius of the lens \( \theta_E \), but at the value where the cumulative probability \( P(> \mu_{\text{E}}) \) drops below the inverse size of the sample \( N_{\star}^{-1} \). This truncation occurs inside the \( p(\mu) \propto \mu^{-3} \) tail and does not noticeably affect either the normalization or the first moment of the distribution.

In the case when \( \bar{\mu} - 1 \ll 1 \), which corresponds to the low optical depth (estimates in the next two sections show that this is the applicable limit), the cumulative probability of the magnification greater than \( \mu \) is

\[ P(> \mu) = \left[ 1 + \left( \frac{\pi \mu - 1}{2(\bar{\mu} - 1)} \right)^2 \right]^{-1}, \]

and therefore for \( \mu_{\text{E}} \) where \( P(> \mu_{\text{E}}) \) drops below \( N_{\star}^{-1} \) one has

\[ \mu_{\text{E}} = 1 + \frac{2}{\pi} (\bar{\mu} - 1) \sqrt{N_{\star} - 1} \]

At redshift \( z \sim 0.1 \), the average magnification value due to a population of lenses that comprise a fraction \( \Omega_L \) of the critical density, is roughly \( \bar{\mu} - 1 \sim 10^{-7} \Omega_L \) (see figures 2–3). Therefore, for a target galaxy with \( N_{\star} \sim 10^{10} \) stars in it, the bound of \( \mu \) due to the sample size is \( \mu_{\text{E}} \sim (10^7 - 10^8) \Omega_L \). At the same time, the other bound, which is due to the finite size of the source is, for a Solar-mass lens, \( \mu_{\text{max}} \sim (10^7 - 10^8) \Omega_L \). Depending on the size of the source star. Given that the dispersion is roughly proportional to the logarithm of the truncation value \( \mu \) (since \( p(\mu) \mu^2 \propto 1/\mu \) at large \( \mu \)), the finite sample effect can decrease the value of the microlensing correction to SBF-based distances by a factor of a few.
This reduction of the effect magnitude is dependent on the number of stars in the galaxy and will not be calculated beyond this estimate. As we will see in the following, the effect can be safely neglected in present but the finite-sample reduction should be kept in mind when the point is reached observationally for the effect to be important; in such cases the finite-sample reduction should be calculated individually for every galaxy.

3 MAGNIFICATION POWER SPECTRUM

3.1 The summation approximation

In this section we calculate the magnification power spectrum \( P_\mu(k) \) using an approximation that magnifications due to individual lenses simply add up in the limit of very low optical depth.

This is different from the widely used multiplication approximation \cite{Vietri82,Pei93,Schneider82.1} where the magnification \( \mu \) of a source seen through a number of lensing planes is taken as the product of the magnification values \( \mu_i \) each lensing plane has at the position of the source \( r_s \):

\[
\mu(r_s) \approx \prod_i \mu_i(r_s), \tag{34}
\]

where the product is over all lensing plane along the line of sight.

We, instead, assume that this value can be calculated as a sum:

\[
\mu(r_s) - 1 \approx \sum_i (\mu_i(r_s) - 1), \tag{35}
\]

where the summation extends over all lenses. It is much simpler in this approximation to calculate the average and the power spectrum of the magnification due to the linearity of taking the average.

This assumption could be justified by saying that the two approaches give very similar results when all but one of the magnifications are close to unity and a reference to the logarithm to both sides but averaging this quantity over possible magnification map configurations would produce statistical properties of \( \ln \mu \) which are hard to convert to those of \( \mu \) unless some additional assumptions are invoked.

3.2 Summation for randomly distributed lenses

We calculate the average magnification and the magnification power spectrum in the approximation \cite{Schneider82.1} assuming that lenses are distributed uniformly and independently of each other.

Consider a cylinder of cross-section \( L \) between the observer at \( D = 0 \) and the source at \( D = D_s \), with \( N \) lenses inside it. For a point-like lens of mass \( M \) at position \( r_s \in L \), individual magnification value is given by \( \mu \approx \frac{\Omega_{\text{fid}}}{M} \) (e.g., Schneider, Ehlers and Falco 1992):

\[
\tau \equiv \int dD \pi \tau^2(D) n(D), \tag{36}
\]

where integration extends from the observer to the source, \( n(D) \) is the number density of lenses and the Einstein radius of a lens of mass \( M \) at the angular diameter distance \( D_L \) from the observers and \( D_{LS} \) from the source is

\[
r_E = \sqrt{\frac{4GM_L D_{LS}^2}{c^2}}, \tag{37}
\]

For a cosmological population of compact lenses with constant closure density fraction \( \Omega_L \) in a flat Universe, one has, at low redshifts \( z \lesssim 0.1 \) (e.g., Press & Gunn 1973):

\[
\tau \approx \int_0^{D_s} dD \frac{4\pi G M_n D(D_s - D)}{c^2} = \Omega_d \frac{z^2}{4} \tag{38}
\]

and thus is relatively small.

This quantity is also a measure of how many microimages will be appreciably magnified since the Poissonian statistics implies that this number is \( e^{-\tau} \) which is approximately \( \tau \) when \( \tau \ll 1 \); we consider just this case of low optical depth in the present study. A situation where more than one lens contributes noticeable flux to the macroimage is less likely by a factor of approximately \( 3\tau/2 \).

In addition to always present \( N + 1 \) image, additional pairs of (tertiary?) images may form when the source moves into a region bound by a caustic curve. Magnification diverges at these curves so these additional images could contribute significantly to the total flux. However, Wambsganss, Witt and Schneider (1992) derived the mean number of these extra pairs to be \( N_p \approx \tau^2 \) in the case of zero external shear which is also very low. Granot, Schechter and Wambsganss (2003) calculate this quantity for non-zero shear numerically and find similar behaviour at low values of \( \tau \); they also show that the statistics of \( N_p \) is approximately Poissonian, so that \( \tau \ll 1 \) ensures these images can be neglected on average. These studies relate to two-dimensional distribution of lenses and there have not been studies exploring a 3D case but at low optical depth there should not be much difference.

Each of the secondary microimages contributes \( \propto (\mu_i - 1)/2 \) to the total flux and shears the beam of the primary image in such a way that its area, on average, shrinks by a fraction \( \mu_i - 1 \). As a result, the input of every lens to the magnification value is approximately \( \mu_i - 1 \) and the total magnification is given by \( \approx \).

Certainly, \cite{Press73} and \cite{Schneider82.1} agree in the limit of average individual magnification values close to unity. It is also trivial that \cite{Press73} can be written as a sum simply by applying logarithm to both sides but averaging this quantity over possible magnification map configurations would produce statistical properties of \( \ln \mu \) which are hard to convert to those of \( \mu \) unless some additional assumptions are invoked.
\begin{align}
\mu_i(r_s) - 1 &= \frac{y_i^2 + 2}{y_i \sqrt{y_i^2 + 4}} - 1, \quad (39)
\end{align}

where
\begin{align}
y_i &= \frac{1}{\hat{r}_{Ei}} \left( r_s - \frac{D_s}{D_i} r_i \right) \quad (40)
\end{align}

and the Einstein radius projection onto the source plane is
\begin{align}
\hat{r}_{Ei} = \frac{D_s}{D_i} r_{Ei} = \sqrt{\frac{4GM_i}{c^2} \frac{D_s - D_i}{D_i}}, \quad (41)
\end{align}

where we have assumed that the distance between the i-th lens and the source is \(D_{L,i} = D_s - D_i\), which is a good approximation for source at low redshift \(z \lesssim 0.1\) in a spatially flat Universe.

Then for the Fourier transform of \(\nu \equiv \mu - 1\) is given by the sum
\begin{align}
\tilde{\nu}(k) = \sum_i \tilde{\nu}_i(k)
\end{align}

and each term amounts to
\begin{align}
\tilde{\nu}_i(k) &= \int \frac{d^2 r_s}{k^2} \exp\left(-\frac{i k \cdot r_s}{r_{Ei}}\right) \left( \frac{y_i^2 + 2}{y_i \sqrt{y_i^2 + 4}} - 1 \right) \quad (43)
\end{align}

\begin{align}
= \exp\left(-\frac{i k \cdot r_i}{D_i} \right) \hat{r}_{Ei} \tilde{\nu}_0(\hat{r}_{Ei} k),
\end{align}

where we changed to the integration variable \(r_i \rightarrow y_i\) according to (40) and introduced a dimensionless Fourier transform
\begin{align}
\tilde{\nu}_0(\xi) &= \int \frac{d^2 y}{k^2} \exp\left(-\frac{i \xi \cdot y}{2}\right) \left( \frac{y^2 + 2}{\sqrt{y^2 + 4}} - 1 \right) = \tilde{\nu}_0(\xi). \quad (44)
\end{align}

This function is \(\approx \xi^{-1}\) for large \(\xi\) and tends to unity as \(\xi \rightarrow 0\); a good approximation can be provided by
\begin{align}
\tilde{\nu}_a(\xi) = \frac{1}{\xi^2 + 1} \quad (45)
\end{align}

which only slightly (by less than two per cent compared to the numerically evaluated \(\tilde{\nu}_0(\xi)\)) overestimates its value at low \(\xi \lesssim 1\).

Averaging with respect to the position of lens in the appropriate plane \(r_i \in \mathcal{L}\) produces, in the limit of infinite cylinder cross-section \(\mathcal{L} \rightarrow R^2\)
\begin{align}
\left\langle \exp\left(-\frac{i k \cdot r_i}{D_i} \right) \right\rangle_{r_i} = \left(\frac{2\pi}{\mathcal{L}}\right)^2 \left(\frac{D_s}{D_i}\right)^2 \mathcal{P}(||\mathcal{L}||^{-1}) \quad (46)
\end{align}

and if the distribution of lenses along the \(D\) coordinate is some \(\varphi(D) \propto n(D)\), one has in \(\tilde{\nu}(k)\) a sum of \(N\) equal terms:
\begin{align}
\langle \tilde{\nu}(k) \rangle_{\mu} = \frac{2}{||\mathcal{L}||} \int_0^{D_s} dD \pi^2 \mathcal{P}(D)n(D)\tilde{\nu}_0(\hat{r}_{E} k). \quad (47)
\end{align}

Since \(\tilde{\nu}_0(0) = 1\) and the average number of lenses within the cylinder is \(\bar{N} = \int dD ||\mathcal{L}|| n(D)\) we arrive at
\begin{align}
\langle \tilde{\nu}(k) \rangle_{\mu} = \langle \nu \rangle_{\mu} 2\pi\delta(k) = (\langle \mu \rangle_{\mu} - 1) 2\pi\delta(k) = 2\pi^2 \mathcal{P}(k). \quad (48)
\end{align}

The optical depth is proportional to the first power of mass of the lens \((\hat{r}_{E} \propto \sqrt{M})\), therefore a distribution of masses can be taken into account by using the average value of the mass.

In a similar fashion, when calculating the correlation function, one has:
\begin{align}
\langle \tilde{\nu}(k_1) \tilde{\nu}(k_2) \rangle = \sum_{i=1}^{N} \tilde{\nu}_i(k_1) \tilde{\nu}_i(k_2) + \sum_{i \neq j} \tilde{\nu}_i(k_1) \tilde{\nu}_j(k_2) \quad (49)
\end{align}

\begin{align}
= \sum_{i=1}^{N} \hat{r}_{Ei}^2 \exp\left[-i(k_1 + k_2) \cdot \hat{r}_i\right] \tilde{\nu}_0(\hat{r}_{Ei} k_1) \tilde{\nu}_0(\hat{r}_{Ei} k_2)
\end{align}

\begin{align}
+ \sum_{i \neq j} \hat{r}_{Ei}^2 \hat{r}_{Ej}^2 \exp\left[-i(k_1 - ik_2) \cdot \hat{r}_i\right] \tilde{\nu}_0(\hat{r}_{Ei} k_1) \tilde{\nu}_0(\hat{r}_{Ej} k_2),
\end{align}

where for typographical clarity we used lens coordinate projections onto the source plane: \(\hat{r}_i = r_i D_s/D_i\).

Averaging of the second sum produces \(N(N-1)\) equal terms of the form:
\begin{align}
\langle \tilde{\nu}_i(k_1) \tilde{\nu}_i(k_2) \rangle = \left(\frac{2\pi}{N}\right)^2 4\pi^2 \delta(k_1) \delta(k_1 + k_2) \quad (50)
\end{align}

while the first sum produces \(N\) terms of the form
\begin{align}
\langle \tilde{\nu}_i(k_1) \tilde{\nu}_j(k_2) \rangle = \delta(k_1 + k_2) \left(\frac{2\pi}{||\mathcal{L}||}\right)^2 \left(\frac{D_s}{D_i}\right)^2 \hat{r}_{Ei}^2(\mathcal{P}(D_i) ||\tilde{\nu}_0(k \hat{r}_{Ei} D_i)||^2) \quad (51)
\end{align}

Taking into account equation (48) and the fact that the average values of \(N\) and \(N(N-1)\) are \(N\) and \(N^2\), respectively, one has
\begin{align}
\langle \tilde{\nu}(k_1) \tilde{\nu}(k_2) \rangle = \delta(k_1 + k_2) \left(\frac{2\pi}{||\mathcal{L}||}\right)^2 \left(\frac{D_s}{D_i}\right)^2 \hat{r}_{Ei}^2(\mathcal{P}(D_i) ||\tilde{\nu}_0(k \hat{r}_{Ei} D_i)||^2) \quad (52)
\end{align}

\begin{align}
= 2 \int_0^{D_s} dD \pi^2 \mathcal{P}(D)n(D) \hat{r}_{E}^2(\mathcal{P}(D)||\tilde{\nu}_0(k \hat{r}_{E} D)||^2) \quad (53)
\end{align}

\begin{align}
\quad = \frac{4\pi^2 \hat{r}_{E}^2}{9(1 + k \hat{r}_{E}^2 + 2k^2 \hat{r}_{E}^2 + \mathcal{P}(\tau))}. \quad (54)
\end{align}

valid to within four per cent for any \(k\), where the Einstein radius projection for the lens halfway to the source is
\begin{align}
\hat{r}_{E} = \sqrt{\frac{4GM_s}{c^2} D_s}. \quad (55)
\end{align}

### 3.3 The contribution of LSB galaxies

An inevitable source of noise to the microlensing correction that needs to be quantified is the potential presence of a low surface brightness (LSB) galaxy on the line of sight to the
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Tuntsov et al. 2004 and discussion following (67) in this paper, it is clear that the source size is large enough (see the Appendix B of the present paper) to allow a two-dimensional lens on the fluctuation properties. Using their equation (14) and neglecting the interstellar contribution to the SBF amplitude can easily be estimated using its equation (19) of the present paper (see below) we find that the effect of a low surface brightness galaxy on the SBF amplitude can be expressed as an extra factor of

\[
\frac{(\mu^2)^\prime}{\langle \mu \rangle} = \langle \mu \rangle c_\mu^2, \tag{56}
\]

where \(c_\mu^2\) is the ‘correlation amplitude’ defined by (19) of Tuntsov et al. 2004.

To determine the two factors above, we need to know the typical mass of the microlenses and calculate the dimensionless convergence \(\kappa\) and shear \(\gamma\) of their population in the foreground galaxy, as well as their ‘effective’ values (Paczynski 1986; Kayser, Refsdal & Stabell 1986) given by the mix of the compact and smoothly distributed matter in the galaxy. As for the first ingredient, the resulting value of the dispersion is very weakly dependent on the ratio of the microlens mass provided that the ratio of its Einstein radius to the source size is large enough (see the Appendix B of Tuntsov et al. 2004 and discussion following (67) in this paper), which is the case here, as shown in the next subsection. We therefore can adopt solar values for an estimate.

Then, one has \(\langle \mu \rangle = \langle |(1 - \kappa)^2 - \gamma^2| \rangle^{-1}\) and \(c_\mu^2(\kappa; \gamma, \theta_R, R)\) calculated in subsection 2.2 and shown in Figure 1 of Tuntsov et al. 2004. The value of the scaled convergence can be calculated from the observed surface brightness of the foreground galaxy \(\mu\) (in magnitudes per square arcsecond) and the mass-to-light ratio \(\Upsilon\) of the component of interest by comparing it with the bolometric irradiance of the Earth by the Sun as

\[
\kappa = \frac{4\pi G M_\odot}{c^2 \Upsilon} \frac{D_{LS} D_{DL}}{D_{OS}} \left( \frac{1 \text{ rad}}{1''} \right)^2 (1 + z) \left( 1 + 0.4(z_{\text{bol}} - z) \right) \tag{57}
\]

\[
\approx 2.04 \times 10^{-3.0 - 0.4(u - 22.5)} \Upsilon (1 + z) D_{LS} \frac{D_{DL}}{D_{OS}} 100 \text{ Mpc},
\]

Here \(D_{LS}, D_{DL}\) and \(D_{OS}\) are the angular diameter distances between the lens and the source, the observer and the lens and the observer and the source, respectively, and \(z_l\) is the lens redshift. Given that the mass-to-light ratio for stellar populations is of order unity (this value is not known well for LSB galaxies though), and for a galaxy to be non-detectable one needs its surface brightness to be below \(\sim 23 \text{ mag} - 24 \text{ mag}\) per square arcsecond, the typical values of the scaled convergence in stars are of order \(10^{-3} - 10^{-2}\) up to moderate redshifts. If, in addition, one assumes that a significant amount of mass in LSB galaxies is present in a dark and smooth form (Impey & Bothun 1992), the total convergence is \(\kappa_{\text{tot}} \sim 10^{-2} - 10^{-1}\); the difference between the stellar and effective convergence values is insignificant in this case.

To evaluate the shear \(\gamma\), one would need an accurate determination of the surface brightness density over the entire surface of the foreground galaxy, which is not possible if it is invisible. Generally, however, the scaled shear takes the values of the same order as the scaled convergence, and \(\kappa_{\text{eff}}^2 \sim \sigma(\kappa)\) in this case (again, assuming the typical Einstein radius is much larger than the typical target star size).

Therefore, a typical contribution to the correction of the SBF amplitude due to an occasional intervening LSB galaxy along the line of sight is of order \(10^{-5} - 10^{-2}\) at moderate redshifts. This is less than what we find in the next section for a cosmological distribution of compact objects if they make up any significant fraction of the matter content of the Universe, but can be comparable and even dominant in case no such distribution is present.

4 EVALUATION OF CORRECTIONS

4.1 Unimportance of interstellar correlations

The expressions above are sufficient for the calculation of \(\langle \mu^2 \rangle_\phi\) and \(\Sigma^2_\phi\) once the average source star profiles \(\langle \psi'(k) \rangle_\phi\), \(\langle \psi^2(k) \rangle_\phi\) and the pixel shape \(\tilde{s}(k)\) have been specified.

However, we will first make some estimates to see what the typical values of the parameters of the problem are. There are four main length scales of the problem: the source size \(R\), the Einstein radius projection to the source \(\tilde{r}_E\) and the pixel size \(x\), as well as the typical projected separation of stars in the galaxy \(\Delta\).

The pixel size is determined by the resolution of the CCD matrix and the distance to the source. The typical pixel size is, in the angular measure, of order \(\theta \approx 0.2'' \approx 10^{-6} \text{ rad}\). At the distance \(D\) this translates into

\[
x = 100 \text{ pc} \quad D_{100} \theta_{0.2} = 3.1 \times 10^{20} \text{ cm} D_{100} \theta_{0.2} \tag{58}
\]

\[
= 4.1 \text{ kpc} \quad z \theta_{0.2} = 1.3 \times 10^{22} \text{ cm} z \theta_{0.2},
\]

where \(D_{100} = D/100 \text{ Mpc}\), \(\theta_{0.2}\) and the second line is valid at low redshifts \(z \lesssim 0.1\).

The Einstein radius projection (for the lens halfway to the source) is, according to (50),

\[
\tilde{r}_E = 4.5 \times 10^{-3} \text{ pc} \quad \frac{D_{100}^3}{m_1} = 1.4 \times 10^{16} \text{ cm} \quad \frac{D_{100}^3}{m_1} \tag{59}
\]

\[
= 2.8 \times 10^{-2} \text{ pc} \quad z_1^{1/2} m_1 = 8.7 \times 10^{16} \text{ cm} \quad z_1^{1/2} m_1^{1/2},
\]

where \(m = M/M_\odot\).

The stars which contribute non-negligibly to the luminosity all lie on the main sequence or above it in the Hertzsprung-Russell diagram. Their sizes therefore lie in the range

\[
R \approx 3 \times 10^{-9} \text{ pc} - 3 \times 10^{-6} \text{ pc} \approx 10^{10} \text{ cm} - 10^{13} \text{ cm}. \tag{60}
\]

The projected density of stars in galaxies hardly exceeds \(10^6 \text{ pc}^{-2}\) in their densest parts and is normally of order \(10^7 \text{ pc}^{-2}\) on average. Therefore, for the mean separation of stars in the pixel one has

\[
\Delta \gtrsim 10^{-2} \text{ pc} - 10^{-1} \text{ pc} \approx 3 \times 10^{16} \text{ cm} - 3 \times 10^{17} \text{ cm}. \tag{61}
\]
Therefore, in all extragalactic cases one has \( R \ll \hat{r}_E \ll x \). The respective scales in the Fourier images domain, which are given roughly by the inverse of these quantities and represent size of the region in \( k \) plane within which \( \psi, P_{\Delta \phi} \) and \( s \) differ appreciably from zero satisfy the opposite relation.

This observation allows us to interpret and estimate the second term in the brackets of (30). Namely, the integral \( \mathcal{P}_{\Delta \phi}^{S} \) is contributed almost exclusively by the region of size \( 1/x \) within which the values of \( P_{\Delta \phi} \) and \( \psi \) are nearly constant and equal to \( 4\pi \hat{r}_E^2/9 \) and \( 1/4\pi^2 \), respectively. As a result, we can write the following estimate for the correlation term using (53):

\[
\mathcal{P}_{\Delta \phi}^{S} \approx ||S||^{-1} \frac{\tau \hat{r}_E^2}{9\pi^2}.
\]

Therefore, \( \tilde{N}\mathcal{P}_{\Delta \phi}^{S} \) is proportional to the average number of stars within the Einstein-Chwolson circle of the typical lens \( \hat{N}_E \). Therefore, taking into account the estimates (60) and (61), \( \tilde{N}_E \sim 10^{-4} - 1 \) for distances from 100 Mpc up to a few Gpc.

Finally, for the luminosity ratio one has:

\[
\frac{\langle l^2 \rangle}{\langle l \rangle} = \frac{\langle l \rangle}{\mathcal{T}} = 10^{6-4(Ms-M)} \}
\]

where, in accordance with the tradition adopted in SBF studies, \( \mathcal{T} \) has been used to denote the luminosity-weighed average luminosity of source stars (this quantity is also called the surface brightness fluctuations amplitude in view of (28)); upright M are used for corresponding absolute magnitudes to avoid confusion with the lens mass. Due to a great range in stellar luminosities, \( M \) assumes values close to the absolute magnitudes of red giant branch stars while \( M \) are closer to those of red dwarfs dominating the main sequence. The ratio of their luminosities ranges from about a hundred to thousands, depending on the band. Therefore,

\[
\tilde{N}_e \frac{\langle l^2 \rangle}{\langle l \rangle} \ll \mathcal{P}_{\Delta \phi}^{S} \frac{\mathcal{T}}{\langle l \rangle} = \frac{\tau \hat{N}_E}{9\pi^2} 10^{6-4(Ms-M)} \ll \tau
\]

The other term in the brackets of (30) is given by the convolution of \( P_{\mu} \) with the source star profile. Assuming all stars are Lambert discs of the same radius \( R \), one has \( \langle \hat{\psi}(k) \rangle = \frac{J_1(kR)}{\pi kR} \).

and (27) taken with (51) gives

\[
\frac{\langle \hat{\mu}^2 \rangle}{\langle \hat{\mu} \rangle} = \langle \mu \rangle + \frac{8\tau}{9\pi^2} \frac{\hat{r}_E}{R} \approx 1 + \tau \frac{2 + \frac{8}{9\pi} \frac{\hat{r}_E}{R}}{1 + \tau} \]

where

\[
f_{\alpha}(\rho) \equiv \rho^2 \int_0^{\infty} \frac{d\zeta f_{\alpha}'(\zeta/\rho)}{\zeta(1 + \zeta + 2\zeta^2)} \approx \ln \rho \frac{\zeta}{8};
\]

the approximation is valid for large \( \rho \).

At \( D = 100 \) Mpc, \( \hat{r}_E/R \approx 2 \times \left(10^4 - 10^5\right) \) for solar-mass lenses and source radius \( R = (10-100) R_\odot \), typical for red giants which normally dominate SBF signal. Thus, the first term in (60) is much greater than the second for all sensible values of parameters. This supports the claim of the paragraph following that equation, and we will neglect the second term hereafter.

The only conceivable situation where the correlation term is non-negligible is if the microlenses are much more massive than the Sun. Since the average number of stars within the Einstein ring of the lens is proportional to the mass of the star, we see taking into account (94) and the estimate for the luminosity ratio, that a lens mass of order \( 10^3 - 10^5 \)\( M_\odot \) is needed for the correlation term to become of order \( \tau \). Increasing the mass would also affect the average in (60) but the dependence is much weaker - nearly logarithmic - in this case.

When the correlations are important the whole methodology of the SBF method breaks down as the dispersion of the pixel luminosity is no longer proportional to the average. Such change would manifest itself in the statistics of the surface brightness fluctuations generally enhancing the probability of large deviations from the mean value. Careful study of the observed fluctuation statistics therefore presents a potential means to detect a population of massive compact lenses. However, results of the next subsection show that the effect is unlikely to be important and we therefore do not extend our study beyond the present observation.

### 4.2 Corrections in cosmological settings

With interstellar correlations seemingly negligible, we can focus on a single quantity

\[
\frac{\langle \mu \hat{\mu} \rangle}{\langle \mu \rangle} = 1 + 2\tau + \int dk P_{\Delta \phi}(k)|\langle \hat{\psi}(k) \rangle| + o(\tau).
\]

In order to evaluate this quantity three inputs are needed – the optical depth to microlensing \( \tau \) and magnification fluctuations power spectrum \( P_{\Delta \phi}(k) \), given by (56) and (55), and the squared-luminosity-weighed average profile \( \langle \hat{\psi}(k) \rangle \) defined by (28).

The former two quantities depend on the global properties of the lensing population and include underlying cosmology through the use of angular diameter distances. In order to evaluate them, the approach of a classic paper by Press & Gunn (1973) will be used. For reasons of the economy of hypotheses we also assume that the number density of compact lenses is constant in comoving coordinates and all lenses have the same mass \( M \) while for the evaluation of distances the now-standard cosmographical model with \( \Lambda = 1 - \Omega = 0.74 \) and a flat geometry will be used.

The angular diameter distance \( D \) to redshift \( z \) is then

\[
D(z) = \frac{cz}{H_0}(1+z),
\]

where \( H_0 \) is the present-day Hubble constant and

\[
r(z) \equiv \int_0^z \frac{dz'}{\sqrt{\Omega(1+z')^3 + 1 - \Omega}}.
\]

If the present-day value of the critical density in compact objects is \( \Omega_d \) and it increases into the past \( \alpha(1+z)^3 \), one has \( D_{LS} = D_S - D_L(1+z_L)/(1+z_S) \)

\[
\tau(z_s) = \frac{3}{2} \Omega_d \int_0^{z_s} \frac{dz}{\sqrt{\Omega(1+z)^3 + 1 - \Omega}} \left[ 1 - \frac{r(z)}{r(z_s)} \right]
\]

while the magnification fluctuation power spectrum

\[
P_{\Delta \phi}(k) = 3\Omega_d r_0^2 \int_0^{z_s} \frac{dz}{(1+z)^2 [r(z_s) - r(z)]^2}
\]

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\[ d^2(z) = \frac{d^2(z)}{1 + q(z)\Omega_d} + \tau(\tau). \]  

Note, that when the microlenses represent a dominant fraction of the Universe matter density, the correction defined above is the one relative to the so-called 'empty beam' distances (Dyer & Roeder 1972; 1973). The combined action of all the masses in a respective 'filled beam' would produce an average magnification of $(1 + 4\tau)$ and therefore correction to the 'filled beam' distance is $q - 2\tau = \langle \Delta \mu^2 \rangle$. The difference between the two values is less than twenty per cent in the situations considered below.

To calculate $q$, we first compute the dispersion of the magnification as a function of stellar radius for a given source redshift $z_s$ using approximation (84) and source profile (72) – figure 1 shows examples of such functions – and then average it using results of numerical simulations separately in each spectral band. Then, the $2\tau$ value is added.

Figure 2 shows the results of our calculations. Correction $q$, defined above, and the optical depth $\tau/\Omega_d$ are shown as functions of the redshift $z$ and true luminosity distance $d$ (upper and lower horizontal scales, respectively). We adopted the currently favoured spatially flat Universe for this calculation with parameters $\Omega = 0.26$ and $H_0 = 73$ km s$^{-1}$ Mpc$^{-1}$ (Eidelman et al. 2004), as well as a microlens mass of $1 M_\odot$. An old, Galactic bulge-like population has been used to calculate the microlensing correction. We reiterate that the finite-sample effect discussed at the end of Section 2 should be considered for each galaxy individually, when the effect is computed for applications to real observations; it further reduces the magnitude of the lensing correction to SBF-based distances and depending on the number of stars in the target galaxy, this reduction can be a factor of a few for smaller galaxies.

As shown in the previous subsection, typical Einstein radii of the lenses are much larger than the stellar radii at most of the distances of interest and therefore for lenses of much larger mass the relation (66) in the large $p$ limit of (67) holds; at the same time, $r_E \propto \sqrt{M}$. Therefore, higher masses would produce corrections that are greater by an additive term of roughly $\tau \ln (M/M_\odot)/18r_0$, which is just 12 per cent of the $2\tau$ value for lens masses as large as $10^6 M_\odot$.

In order to avoid crowding in the graph, only bolometric, ultraviolet ($U$), visual ($V$) and two infrared ($I$ and $H$) values of $q$ are depicted. In fact, $B$ values are very close to those for $V$, being about five per cent lower than the latter for $z \leq 0.08$ and slightly higher (by up to four per cent) for larger redshifts. $K$ and $L$ graphs would be indistinguishable from those of $H$ on the scale of this graph, while $R$ and $J$
take values roughly half-way between $V$ and $I$, and $I$ and $H$, respectively.

Figure 3 shows the same quantities obtained for a disc-like population. The comment above concerning the finite-sample effect can be repeated in full here.

The complex behaviour of the graph in terms of the dependence on colour at low redshifts can be explained by the non-linear form of $(\Delta \mu^2)(R)$ dependence. It is proportional to the logarithm of $r_E/R$ for small source radii and falls of as $1/R^2$ for much larger sources, which introduces an extra weighing factor in averaging for close galaxies, when a significant fraction of the optical depth is contributed by nearby lenses. This behaviour is less pronounced for the disc-like population of figure 3.

By comparing the average values of $q$ with $(\Delta \mu^2)(R)$ in figures 2 and 3, we see that the typical effective radius of stars that contribute most to the correction is of order ten solar radii, except short-wavelength bands $U$, $V$, $I$, and $H$, where one can see a significant contribution due to stars with radii of solar order. Therefore, as is the case with the surface brightness fluctuations amplitude, the correction is dominated by late-type giant stars. This is quite natural because the average value we are interested in is weighted with the square of stellar luminosities, making red giants the most important contributors – especially, for old stellar populations such as the one used in our calculations.

5 CONCLUSIONS

In the present paper we have considered the correction to distances inferred from the surface brightness fluctuations analysis, caused by a potential population of compact objects along the line of sight to the source galaxy. Using a simple approximation for microlensing magnification fluctuations we have studied how this effect can be taken into account and whether such accounting is needed in observations. Although we have considered microlensing as the main factor of individual star brightness fluctuations, the technique developed should be applicable to a wider range of geometrical variability.

By combining the results shown in figure 2 with the upper limit of $\sim 0.3$ on the total fraction of matter in the energy budget of the Universe, one can see that microlensing can for now be safely neglected when interpreting SBF-based distances. The present-day observational facilities limit the range of the method to less than 200 Mpc while the uncertainty of this method is presently between five and ten per cent. The finite-sample effect discussed at the end of Section 2 further reduces the magnitude of the lensing correction.

However, for the next generations of telescopes, this situation can – at least, in principle – change. The main factor limiting the accuracy of the surface brightness fluctuations method is the photon noise, which is of geometrical origin. Therefore, a naïve expectation would be that increasing the diameter of the telescope $n$-fold would lead to a directly proportional increase in the range in terms of the comoving distance $c/H_0 r(z)$. Taken with the estimates given in this study, this implies that microlensing might just start to matter when space telescope diameters get closer to a ten-metre scale.

Alternatively, one might notice that $q$ turned to be of the same order as the total optical depth. Therefore, any large overdensity of compact microlenses – such as those potentially associated with galaxy clusters – would introduce noticeable change in the surface brightness fluctuations statistics and can thus be detected in this manner. However, the properties of strong lensing mapping need to be known in full detail for such project since local variations of the apparent luminosity distance are greatest near the critical curves of the mapping which yield galaxies most suitable for SBF studies. Temporal variability, therefore, seems to be a
better tool to study compact dark matter in galaxy clusters (Tuntsov et al. 2004).

We conclude that microlensing by a cosmological population of compact objects is unlikely to significantly bias determination of distances using surface brightness fluctuations technique. Similarly, present accuracy of this method does not allow to put useful constraints on the properties of such population from the absence of systematic discrepancies between distances determined via SBF and other methods. The effect considered in this paper, however, should not be overlooked when the accuracy and range of the SBF method reach the level of a few per cent and a gigaparsec, respectively.

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