What is the minimum time required to take a temperature? In this paper, we solve this question for a large class of processes where temperature is inferred by measuring a probe (the thermometer) weakly coupled to the sample of interest, so that the probe’s evolution is well described by a quantum Markovian master equation. Considering the most general control strategy on the probe (adaptive measurements, arbitrary control on the probe’s state and Hamiltonian), we provide bounds on the achievable measurement precision in a finite amount of time, and show that in many scenarios these fundamental limits can be saturated with a relatively simple experiment. We find that for a general class of sample-probe interactions the scaling of the measurement uncertainty is inversely proportional to the time of the process, a shot-noise like behaviour that arises due to the dissipative nature of thermometry. As a side result, we show that the Lamb shift induced by the probe-sample interaction can play a relevant role in thermometry, allowing for finite measurement resolution in the low-temperature regime. More precisely, the measurement uncertainty decays polynomially with the temperature as $T \to 0$, in contrast to the usual exponential decay with $T^{-1}$. We illustrate these general results for (i) a qubit probe interacting with a bosonic sample, where the role of the Lamb shift is highlighted, and (ii) a collective superradiant coupling between a $N$-qubit probe and a sample, which enables a quadratic decay with $N$ of the measurement uncertainty.

1 Introduction

Temperature is a physical quantity important in most natural sciences and some aspects of daily life. The task of thermometry – measuring the temperature – is essential in physics, chemistry, medicine, and cooking, to name a few. A good thermometer should be accurate (on average it provides the right temperature) and precise (fluctuations around the true value are small). The former requires an accurate design of the thermometer, whereas the latter demands collecting enough statistics: either by using a macroscopic thermometer where each subsystem equilibrates with the sample, or by repeating the experiment enough times when dealing with thermometers at the quantum scale [1–5]. Such processes take time, and in fact we also wish a good thermometer to be fast. Motivated by this practical limitation, in this paper we derive fundamental limits on finite-time thermometry, and discover that in some situations these limits can be saturated with a relatively simple experiment.

Concretely, we consider a probe (acting as a thermometer) in contact with a sample – a reservoir at temperature $T$. Their interaction leaks information on the sample’s temperature (or another physical property) to the state of the probe. After some time, the latter is measured in order to estimate the parameter $T$. To benchmark the quality of such estimation schemes we consider the quantum Fisher information (QFI) of the final state of the probe $\mathcal{F}$ [6].

The most natural starting point is equilibrium thermometry, where the probe is given sufficient time to thermalize to its Gibbs state, $\rho = e^{-\beta H} / \text{tr} e^{-\beta H}$ with $\beta = 1/k_B T$ and $k_B$ the Boltzmann constant ($k_B = 1$ in what follows) [7–12]. Remarkably, the (quantum) Fisher information of the Gibbs state is proportional to the heat capacity of the system, because the average energy turns out to be the optimal estimator for temperature as it saturates the Cramer-
Rao bound [7, 8, 13, 14]. This provides a practical recipe to design good equilibrium thermometers: the probe’s Hamiltonian $H$ needs to be engineered to maximise the heat capacity of the probe around the estimated temperature $T$. For example, this can be achieved by preparing the probe close to a critical point, see some examples in [3, 15]. The fundamental limits of equilibrium thermometry where derived by Correa et al. in [8] by maximising the QFI with respect to probe’s Hamiltonian, showing in particular that it can scale at most quadratically with the number of subsystems in the probe [12, 16].

Nonequilibrium thermometry offers an alternative framework to enhance the QFI of the probe. In this case, the probe is measured before reaching equilibrium, so that extra information can be potentially achieved. This requires knowledge of the dissipative dynamics and precise timing for the measurement, but can lead to substantially higher QFI than standard equilibrium thermometry [9, 17–33]. The maximum achievable QFI in any such scenario has been recently derived in [32] (note that, in contrast to the present work, the sensing time is not taken to be a resource in [32]).

These results are promising for the design of quantum thermometers. However, in most cases they disregard the importance of the sensing time, i.e. how long it takes to reach the desired state. A clear example is equilibrium thermometry: whereas critical systems have a higher heat capacity (i.e. QFI), they also require longer thermalisation times [34]. There is hence an interesting tradeoff between the probe’s QFI and the required time of the estimation process. In fact, in analogy with frequency estimation [35, 36], it is natural to consider both the number of probes and the sensing time are resources for thermometry.

To take time into account, in this article we consider the QFI rate as the figure of merit – the QFI of the final state divided by the total interaction time [3, 8]. Considering the most general control strategy on the probe (adaptive measurements, control on the probe’s state and Hamiltonian), we derive upper bounds on the QFI rate whenever the thermalisation process is well described by a general class of Markovian master equations by exploiting techniques derived in [37–39] in the context of frequency estimation. Using Markovian master equations for non-equilibrium thermometry is ubiquitous in theoretical works (see e.g. the review [3]), but also of crucial experimental relevance: recent experiments in non-equilibrium thermometry involving single-atom probes for quantum gases [31] can be well described by this framework [40].

Our main results and their implications can be summarised as follows:

- We show that, for a large class of Markovian dynamics, the QFI grows at most linearly with the total sensing time $\tau$, a shot-noise like behaviour common of dissipative processes. More precisely, the QFI $\mathcal{F}$ is upper bounded by an inequality of the form $\mathcal{F} \leq f(\mathcal{L})\tau$, see Eq. (17) and (30), where $f(\mathcal{L})$ is a function that depends on the specific Lindblad evolution. The bounds can be easily computed from the jump operators and the corresponding rates without the need to solve the dynamics.

- We apply these bounds to Lindblad master equations derived from a probe-sample weak interaction of the form $H_I = A \otimes B$, with $A(B)$ acting on the probe (sample). Then, we show that for arbitrarily probe Hamiltonian $H$ our bounds can be put in a very intuitive form (see Eq. (28)):

$$\mathcal{F} \leq \tau f(B)(\Delta A)^2$$

where $\Delta(A) = \lambda_{\text{max}} - \lambda_{\text{min}}$ is the spectral gap of the operator $A$ (the difference between its maximal and minimal eigenvalues), and $f(B)$ is a function that depends on the spectral density of the sample. This can be understood as a speed limit relating the amount of information that the probe can acquire about the sample with their coupling given by $H_I = A \otimes B$. We also show how to engineer the probe Hamiltonian $H$ in order to attain the bound.

- In absence of temperature dependent Lamb shift, these upper bounds on the QFI can be saturated by a fast measure-and-prepare strategy. The optimality of these strategies were already noted numerically for qubit probes [3, 8], and our results generalise these considerations to arbitrary Markovian evolutions. We also develop an autonomous
scheme where the fast measure-and-prepare strategy is achieved through coupling the probe to an external zero-temperature bath, and monitoring the energy flux from the sample to the bath.

- The fast measure-and-prepare strategy can in principle be improved in the presence of a temperature-dependent Lamb shift. Whereas this contribution is usually negligible compared to that obtained from the temperature-dependent decay rates, we argue that it plays a dominant role at low temperatures. By focusing on a qubit probe with frequency \( w \) interacting with a bosonic sample, we show that the QFI can scale as \( \mathcal{F} \propto T^{1+\alpha} \) as \( T \to 0 \) (\( \alpha \) is the Ohmicity of the sample), in contrast to the standard exponential \( \mathcal{F} \propto e^{-w/T} \) obtained when the Lamb shift is neglected \([7, 41]\). Similar polynomial decays had been obtained in the steady state of strongly coupled sample-probes states \([27, 41–43]\). To exploit this advantage, we show that the probe has to be left to evolve coherently for a finite time analogously to frequency estimation scenarios (see in this context \([25, 33]\)), which is markedly different from the fast measure-and-prepare strategy.

- To illustrate the general applicability of our framework, we also develop optimal thermometric protocols for more complex probes, consisting of a \( N \) qubits coupled to the sample through a collective coupling \([44, 45]\). In this case, we show that the QFI can scale as \( N^2 \), and characterise the experimental requirements to obtain this enhanced scaling.

It is also important to emphasise that the bounds and measurement schemes we derive are not limited to the task of thermometry. They apply to any scenario where the probe’s interaction with the sample is well described by a Markovian master equation for the state of the probe, with the jump rates and the Lamb shift depending on some physical property of the sample. Our bounds only rely on the form of this master equation, and hence set a general (and in many cases attainable) limit on how well a physical property of the sample can be estimated through the probe in a finite time. As an illustration we consider the estimation of the Ohmicity of the bath.

![Figure 1: The general sensing scheme we consider. The temperature \( T \) (or another parameter) of a large sample at thermal equilibrium is estimated by coupling it to a probe for a finite time \( \tau \). We assume that the probe’s evolution is well modeled by Markovian semi-group dynamics. In addition, we allow the possibility that probe’s dynamics is assisted with general fast quantum control. In particular, this may include continuous measurements, adaptive schemes with feedback, and entangling gates with auxiliary quantum systems.](image)

The paper is structured as follows. In Sec. 2, we introduce the different techniques and quantities of interest. The main results, consisting of the different bounds on QFI as well as optimal measurement strategies, are then presented in Sec. 3. In Sec. 4, we apply such general considerations to a qubit interacting with a bosonic sample, and to a collective coupling between the sample and a \( N \)-qubit probe. We close in Sec. 5 with a short summary and a discussion of future endeavours.

## 2 Framework

In this section, we start by reviewing the basics of parameter estimation, with emphasis on thermometry. We then introduce Lindblad master equations, which are used to describe the thermalisation of the probe when put in contact with the sample, as well as the general framework to describe arbitrary quantum control on the probe (including measurements and adaptive strategies), see Fig. 1. Finally, we describe the results of \([37–39]\), which are the main technical tools used to find optimal finite-time protocols for thermometry.

### 2.1 Parameter estimation and Quantum Fisher Information

Consider a random variable \( X \) collecting the results of all measurements performed during an
experiment. To simplify the following discussion we assume that $X$ is discrete. For thermometry (or any parameter estimation task) the description of the experiment is fully captured by the dependence of $X$ on the parameter $T$, as given by the family of probability distributions $p(x|T)$ modelling $X$. The Fisher information $\mathcal{I}(T) = \mathbb{E} \left[ \left( \frac{\partial}{\partial T} \log p(X|T) \right)^2 \right]$, associated to $X$ at a given $T$, quantifies how much information the experiment reveals about the parameter (note that the expected value $H(X) = \mathbb{E} [\log p(X|T)|T]$ is the entropy of $X$). Denoting $p_x = p(x|T)$ the Fisher information can be easily expressed as

$$\mathcal{I}(T) = \sum_x \frac{(p_x)^2}{p_x} \tag{2}$$

under some regularity conditions\textsuperscript{1}. Here and in the rest of the paper we use the dot to denote the derivative with respect to the estimated parameter $\dot{p}_x = \frac{\partial}{\partial p} p_x$. One verifies from Eq. (2) that $\mathcal{I}(T)$ can also be understood geometrically as the temperature susceptibility of the probability measure $p(T) = (p_1, p_2, \ldots)$ with respect to Kullback-Leibler divergence (also Hellinger or Bhattacharyya distances).

Fisher information plays a central role in statistics. In particular, via the famous Cramér-Rao bound it sets a limit on how well the parameter can be estimated with an unbiased estimator $\hat{T}(X)$

$$\mathbb{E} \left[ (\hat{T} - T)^2 \right] \geq \frac{1}{\mathcal{I}(T)}. \tag{3}$$

This bound can also be adjusted to the context of Bayesian inference \cite{16}, where the prior knowledge of the parameter $T$ is explicitly taken into account. Futhermore, for a fixed prior Bernstein–von Mises theorem suggests (under some regularity conditions) that if the experiment is long enough and done well the posterior distribution is fully determined by $\mathcal{I}(T)$.

In a quantum experiment the final state of the system (that can include classical registers) is not described by a probability measure $p(T)$ but by a density matrix $\rho(T)$. Fixing the measurement performed on the final state relates $\rho(T)$ to a random variable $X$ and its Fisher information $\mathcal{I}(T)$. It then natural to define the quantum Fisher information $\mathcal{F}(T)$ (QFI) of the state $\rho(T)$ as the maximal Fisher information for all possible measurements. With this definition it is clear that the role that $\mathcal{I}(T)$ plays for parameter estimation is endorsed by QFI in quantum experiments. Remarkably, $\mathcal{F}(T)$ can be written in a closed form

$$\mathcal{F}_{\rho(T)} = \text{tr} L \dot{\rho} \tag{4}$$

with the symmetric logarithmic derivative operator $L$ given by the equation $\frac{1}{2} \{ L, \rho \} = \dot{\rho}$ \cite{6,47,48}. Analogously to the classical case the QFI can be understood geometrically as temperature susceptibility of the state $\rho(T)$ with respect to Bures distance (or Uhlmann’s fidelity).

The final state of the system depends on how it was prepared at the beginning of the experiment. Just like the final measurement the preparation procedure is in principle under control. It is thus more natural to describe the experiment by a quantum channel $\mathcal{E}_T$ mapping the initial state of the system $\varrho_0$ to its final state $\rho(T) = \mathcal{E}_T(\varrho_0)$, and define the QFI of the channel by optimizing over the preparation

$$\mathcal{F}_{\mathcal{E}_T} = \max_{\varrho_0} \mathcal{F}_{\rho(T)}. \tag{5}$$

As for the states the QFI of a channel can be expressed in a simple form, if one allows trivial extensions of the channel $\mathcal{E}_T \otimes \text{id}$ \cite{49}.

Finally, in practice it is important to consider the duration of the experiment $\tau$ as a resource for parameter estimation. To benchmark experiments we analyse the QFI as a function of time $\mathcal{F}_{\mathcal{E}_T,\tau}$. Intuitively, the longer the experiment the better one can estimate the parameter. For example, because the (quantum) Fisher information is additive for independent random variables $\mathcal{I}_{X,Y}(T) = \mathcal{I}_X(T) + \mathcal{I}_Y(T)$ and product states $\rho(T) \otimes \sigma(T) = \mathcal{F}_\rho(T) + \mathcal{F}_\sigma(T)$, it is doubled if an experiment is repeated twice. This observation gives rise to the so called diffusive (or standard quantum limit) scaling $\mathcal{F}_{\mathcal{E}_T,\tau} \propto \tau$. Among others it describes experiments where the same preparation and measurement is repeated many times. The best scaling, called ballistic (or Heisenberg), possible in quantum experiments is $\mathcal{F}_{\mathcal{E}_T,\tau} \propto \tau^{\frac{3}{2}}$ \cite{50}. This is for example the case when the dynamics of the system is unitary $\mathcal{E}_T[\rho_0] = e^{-iT \hat{H}} \rho_0 e^{iT \hat{H}}$. This gives rise to a faster scaling of precision with which the parameter is estimated with respect to the sensing time.

\textsuperscript{1}The expression is not well defined if some of the probabilities $p_x$ are strictly zero.
2.2 Probe-Sample interaction as a Lindblad master equation

In the context of this paper the sample is a large reservoir at thermal equilibrium. Ideally, the state of the reservoir is unaffected by the interaction with a small probe, so that the reservoir can be virtually replaced with a fresh one all the time. In consequence the probe-sample interaction can be naturally described by a time-independent Markovian semi-group evolution of the probe system alone. Thus we assume the dynamics of the probe to be given by a master equation of the form

\[ \frac{d}{dt} \rho = \mathcal{L}(\rho) = -i[H + H_{LS}, \rho] + \mathcal{D}(\rho), \]

with

\[ \mathcal{D}(\rho) = \sum_{\omega} \gamma_{\omega} \left( A_{\omega} \rho A_{\omega}^\dagger - \frac{1}{2} \{ A_{\omega}^\dagger A_{\omega}, \rho \} \right). \] (6)

We assume, that the dissipator \( \mathcal{D}(\rho) \) is of the Lindblad form with respect to the jump operators \( A_{\omega} \) that do not depend on bath temperatures (but the rates \( \gamma_{\omega} \) do). Furthermore, the jump operators satisfy

\[ A_{\omega} = \sum_{(\epsilon, \epsilon') \in P_{\omega}} \Pi_\epsilon A_{\omega} \Pi_{\epsilon'}, \] (7)

for a family of orthogonal projectors \( \{ \Pi_\epsilon \}_{\epsilon} \), where each pair \((\epsilon, \epsilon')\) with \( \epsilon \neq \epsilon' \) can only appear once (for one \( \omega \)). In words, the operators \( A_{\omega} \) describe jumps between subspaces labeled by \( \omega \) and \( \epsilon \) appearing in \( P_{\omega} \). A simple example, is when \( \Pi_\epsilon \) defines the subspace associate to energy \( \epsilon \) of the probe’s Hamiltonian \( H \). Then, \( P_{\omega} \) might collect all pairs of energies \((\epsilon, \epsilon')\) such that \( \epsilon' - \epsilon = \omega \). We chose to write the jump operators in a more abstract form so that the master equation (6) can be applied very generally, in particular to the local master equation [52–54], partial secular approximations [55–60], as well as reaction-coordinate mappings to deal with strong coupling [61].

The Hamiltonian \( H_{LS} \) is the Lamb shift correction to the energy of the probe system induced by the interaction with the sample. \( H_{LS} \) is typically small as compared to the energy of the probe and is very often neglected in the thermometry literature (see Ref. [62] for an exception). Nevertheless, it is generally a temperature dependent correction \( H_{LS} \neq 0 \) and may play an important role in low-temperature thermometry as we shall see.

2.3 The master equation from a microscopic model

To vehicle some physical insight into Eq. (6) let us give explicit expressions for the microscopic derivation of the so-called global master equation [51]. As the starting point consider the probe-sample coupling given by the global Hamiltonian in the form

\[ H_{\text{tot}} = H + H_B + A \otimes B, \] (8)

where \( H(H_B) \) is the Hamiltonian of the probe (bath or sample), and the interaction Hamiltonin has a form \( H_I = A \otimes B \) with Hermitian operators \( A \) and \( B \) acting on the probe and sample respectively. It is convenient to diagonalize the probe Hamiltonian

\[ H = \sum_{\varepsilon \in \text{Sp}(H)} \varepsilon \Pi_\varepsilon, \] (9)

where \( \text{Sp}(H) \) is the spectrum of \( H \), defining the energy subspaces given by the set of orthogonal projectors \( \{ \Pi_\varepsilon \} \).

Assuming that the coupling between the probe and the sample is weak and using the Born-Markov and secular approximations\(^5\), one can derive the master equation for the probe with of the form of Eq. (6) [51]:

\[ \mathcal{D}(\rho) = \sum_{\omega} \gamma_{\omega} \left( A_{\omega} \rho A_{\omega}^\dagger - \frac{1}{2} \{ A_{\omega}^\dagger A_{\omega}, \rho \} \right) \]

\[ H_{LS} = \sum_{\omega} s_{\omega} A_{\omega}^\dagger A_{\omega} \] (10)

\[ A_{\omega} = \sum_{\epsilon' \sim \omega} \Pi_\epsilon A \Pi_{\epsilon'}, \]

The coefficients \( \gamma_{\omega} \) and \( s_{\omega} \) are real and imaginary parts of the correlation function of the reservoir

\[ \Gamma_\omega = \frac{1}{2} \gamma_{\omega} + i s_{\omega} = \int_{0}^{\infty} e^{i\omega t} \langle B(0) B(t) \rangle dt \]

where \( B(t) \equiv e^{-iH_B t} B e^{-iH_B t} \) are operators of the sample in the interaction picture. One notes that Eq. (10) is a particular case of Eqs. (6-7).

In the following we consider the possibility of engineering the probe Hamiltonian \( H \). In contrast, we treat the operator \( A \) describing the coupling of the probe to the sample as being fixed.

\(^5\)The secular approximation requires that any non-zero frequency \( \omega = \epsilon' - \epsilon \) is larger than the interaction strength, see e.g. [55–60].
2.4 Fast quantum control

On top of the thermalisation process, we assume that the probe and an additional auxiliary system of arbitrary dimension (not interacting with the sample) can be externally measured and controlled at will. The control capabilities are introduced in two steps. First, the Hamiltonian $H$ (acting on the probe and the ancillae) can be engineered. In principle, we allow it to vary in time as long as instantaneous thermalization at $t$ is well described by Eq. (6) for some fixed $H(t)$ \(^3\). Second, the dissipative evolution is being interjected with arbitrary control operations and measurements on the probe and the ancillae. Following [37] this can be formally described by dividing the total time $\tau$ in $m$ steps, $dt = \tau/m$ (in principle $m$ can be arbitrary large). The systems evolve accordingly to the master equation during each step $e^{dt\mathcal{L}}$ but in-between any two steps an arbitrary gate, measurement or initialization can be applied. In fact because the dimension of the auxiliary system is kept free, all control operations can be implemented as unitary gates $U_k$. In particular, the information acquired with a measurement along the process can mapped coherently onto some ancilia and used in the next steps, thus allowing for adaptive schemes. It is important to stress that, as above, we assume that the control operations do not hinder the approximations and time-scale separation used to derive the master equation (6) in the first place.

At any time $\tau$ the state of the probe and ancillae is given by a density matrix $\rho(\tau|T)$. The QFI of this state with respect to the temperature sets a fundamental limit on the precision of the whole scheme seen as a thermometer. Our goal is then to develop finite-time strategies that maximise the QFI of the channel

$$\mathcal{E}_{\tau|T} = e^{dt\mathcal{L}} \cdot U_m \cdots \circ e^{dt\mathcal{L}} \circ U_1.$$  

Crucially, the control and presence of ancillae can not alter the coupling $H_I = A \otimes B$ between the probe and the sample. The intuition is that $H_I$ gives the bottleneck for how fast a change of temperature in the sample causes an effect on the probe, setting a limit on thermometry even in presence of arbitrary quantum control.

2.5 QFI bounds for control-assisted Markovian semi-group dynamics

It is straightforward to verify that a thermalisation of an infinitesimal duration $dt$ is well described by a quantum channel $e^{dt\mathcal{L}}$ which admits a Kraus representation $\mathcal{K} = (K_0 \ldots K_\omega \ldots)$ composed of Kraus operators

$$K_0 = 1 - dt\frac{1}{2} \sum_\omega \gamma_\omega A_\omega \dagger A_\omega - i dt (H + H_{LS})$$

$$K_\omega = \sqrt{dt\gamma_\omega} A_\omega \quad \forall \omega,$$  

where the terms of order $dt^{3/2}$ and higher are ignored. A Kraus representation of a quantum channel is of course not unique, any vector of operators $\tilde{K} = uK$ with a unitary gauge matrix $u$ describes the same channel\(^4\). It has been shown in [37, 38] that if there exist a Hermitian matrix $h = -iu^\dagger \dot{u}$, such that

$$\|K^\dagger (\tilde{K} + ihK)\| = O(dt^{3/2}),$$  

then the QFI of any channel $\mathcal{E}_{\tau|T}$ of form of Eq. (11) is upper bounded by

$$\mathcal{F}_{\mathcal{E}_{\tau|T}} \leq 4 \frac{\tau}{dt} \| (K^\dagger - iK^\dagger h)(\tilde{K} + ihK) \|,$$  

with $\| \cdots \|$ the operator norm, which is given by $\| A \| \equiv \max_j \lambda_j$ where $\lambda_j$ are the eigenvalues of the Hermitian operator $A$. Note that if the master equation has an explicit time dependence, but Eq. (13) is fulfilled at all times for some $h_t$, one can simply replace the bound with $\mathcal{F}_{\mathcal{E}_{\tau|T}} \leq 4 \int_0^\tau \| (\dot{K}_t^\dagger - iK_t^\dagger h_t)(\tilde{K}_t + ih_tK_t)\|$, this is analogous to the phase-estimation scenario with time-dependent noise discussed in the supplementary material of [38].

3 Results

We are now ready to present the main results of this article. We start by showing that the diffusive scaling $\mathcal{F}_{\mathcal{E}_{\tau|T}} \propto \tau$ induced by Eq. (14)

\(^3\)This is well justified when the driving is sufficiently slow, for the so called adiabatic master equation [63, 64], or if the driving is very fast, e.g. quenches, so that the bath does not have time to react. However, we will see that all protocols considered here, including optimal ones, do not require driving of $H$ when the QFI is the figure of merit. It is enough to optimise $H$ at the beginning of the process.

\(^4\)Note that the gauge matrix can explicitly depend on the parameter
applies to a wide class of probe-sample interactions. We then derive upper bounds on $\mathcal{F}_{\varepsilon_{ij}T}$ for both fixed and engineered probe’s Hamiltonian $H$, and show how to saturate them by simple measurement strategies. Finally, we discuss the potential effect of the Lamb shift Hamiltonian in thermometry.

3.1 The diffusive scaling of the QFI in thermometry

The first question to ask is whether ballistic scaling of QFI is possible in thermometry, i.e. whether there exists a $h$ satisfying Eq. (13) as we just discussed. Following the argumentation of [38], we derive the general condition for diffusive scaling of the QFI that can be found in the Appendix 6. A simpler but slightly more restrictive version of it reads

$$\dot{H}_{LS} \in \text{span}\left\{1, \gamma_\omega A_\omega^\dagger A_\omega\right\}, \quad (15)$$

see Appendix 6. In words, if the derivative of the Lamb shift Hamiltonian $H_{LS}$ is linearly dependent of identity $1$ and the operators $\gamma_\omega A_\omega^\dagger A_\omega$ for all $\omega$, then $\mathcal{F}_{\varepsilon_{ij}T} \propto \tau$. It is worth noting that the condition (15) is also sufficient to enforce a diffusive scaling of the QFI if the Lamb shift Hamiltonian is block-diagonal $H_{LS} = \sum_\varepsilon \Pi_\varepsilon H_{LS} \Pi_\varepsilon$, c.f. Appendix 6.

In the case of our microscopic model introduced in section 2.3 the Lamb shift Hamiltonian takes the form $H_{LS} = \sum_\omega s_\omega A_\omega^\dagger A_\omega$. Clearly, a sufficient condition for (15) is that all the jump rates $\gamma_\omega$ are non-vanishing whenever the jump operator $A_\omega$ is not zero and the derivative of the Lamb shift contribution $\dot{s}_\omega$ are non zero. We argue that this is usually the case. It is possible that some frequencies $\omega$ are missing in the spectrum of the bath, however in this case both $\gamma_\omega$ and $s_\omega$ are identically zero. If the frequency is present it typically gives rise to the dissipative term $\gamma_\omega$, and not just a coherent temperature dependent Lamb shift $\dot{s}_\omega$. In such cases we can conclude that the QFI is bound to a diffusive scaling

$$\mathcal{F}_{\varepsilon_{ij}T} \leq \text{const} \cdot \tau. \quad (16)$$

Intuitively speaking, this scaling is a consequence of the inevitable presence of noise/dissipation in the process of temperature estimation, which prevents the ballistic scaling $\mathcal{F}_{\varepsilon_{ij}T} \propto \tau^2$ commonly obtained in quantum-coherent evolutions (e.g. in noiseless phase interferometry [65]).

On the other hand, it is interesting to ask the question whether one can engineer a more exotic reservoir in such a way that the condition for diffusive scaling of the QFI is not fulfilled. For example, if the interaction in (8) is replaced by the more general form $\sum_i A_i \otimes B_i$, then the diffusive scaling of the QFI is not guaranteed by the argument above. In this case, ballistic scaling of the QFI could be achieved, possibly requiring active control [39].

3.2 Upper bound on QFI for a fixed $H$ (no Lamb shift)

For clarity of the exposition, we start by ignoring the Lamb shift $H_{LS}$ term in the master equation in the following sections. More precisely, we assume that the Lamb shift is constant around the true value of the bath temperature ($\dot{\omega}_\omega = 0$ if $A_\omega^\dagger A_\omega \neq 0$), so that it can be ignored. Indeed, any parameter independent term in the Hamiltonian can be cancelled via appropriate control operations. We will come back to the effect of $H_{LS}$ later.

We start by considering a fixed probe Hamiltonian $H$, and discuss its engineering in the following section. In absence of Lamb shift Eq. (13) can be satisfied by setting $h = 0$. This gives a particularly simple upper-bound on the QFI for thermalization. Straightforward application of Eq. (14) gives a very intuitive expression

$$\mathcal{F}_{\varepsilon_{ij}T} \leq \tau \left\| \sum_w \frac{\gamma_w^2}{\gamma_w^2} A_w^\dagger A_w \right\|, \quad (17)$$

see Appendix 7. Note that the bound only depends on the jump operators $A_\omega$ and the rates $\gamma_\omega$, and neither requires solving the master equation nor considering explicit control strategies. Remarkably, this bound can be saturated with a simple strategy as we now show.

3.3 Saturation of the bound (17) with a continuous measure-and-prepare scheme

To save some space let us denote the norm appearing in the rhs of Eq. (17) as $\Theta = \left\| \sum_w \frac{\gamma_w^2}{\gamma_w^2} A_w^\dagger A_w \right\|$. For simplicity we start with the expression of the the jump operators $A_\omega$ in...
Eq. (10). It gives
\[
O = \sum_{\omega} \gamma^2 \sum_{\varepsilon} \sum_{\varepsilon'} \Pi_{\varepsilon'} A_{\Pi_{\varepsilon'}} A \Pi_{\varepsilon}
\]
\[
= \sum_{\omega} \gamma^2 \varepsilon e^{-\varepsilon} \Pi_{\varepsilon'} A_{\Pi_{\varepsilon}} A \Pi_{\varepsilon}
\]
(18)

Here, we used \(\Pi_{\varepsilon} \Pi_{\varepsilon} = \delta_{\varepsilon} \Pi_{\varepsilon}\) and the fact that for a fixed \(\omega\) and \(\varepsilon\) there can only be one \(\varepsilon'\) fulfilling \(\varepsilon' - \varepsilon = \omega\). Since all the operators \(\Pi_{\varepsilon} \Pi_{\varepsilon'}\) for different \(\varepsilon'\) are orthogonal, we can simplify the operator norm to
\[
O = \max_{\varepsilon'} \left\| \Pi_{\varepsilon'} \left( \sum_{\omega,\varepsilon} \frac{\gamma^2}{\omega} A_{\Pi_{\varepsilon}} A \right) \Pi_{\varepsilon'} \right\|
\]
(19)

We denote the energy which attains the maximum by \(\varepsilon_\star\).

With the more general form of the jump operators \(A_{\omega} = \sum_{(\varepsilon',\varepsilon) \in \Pi_{\varepsilon}} \Pi_{\omega} A_{\omega} \Pi_{\omega} \) in Eq. (7) the expression takes the form
\[
O = \max_{\varepsilon'} \left\| \Pi_{\varepsilon'} \left( \sum_{\omega,\varepsilon} \frac{\gamma^2}{\omega} A_{\Pi_{\varepsilon}} A_{\omega} \right) \Pi_{\varepsilon'} \right\|
\]
(20)

which follows from identical arguments, with the maximum attained for \(\varepsilon' = \varepsilon_\star\).

So far we have just rewritten Eq. (17). To show that it can be attained, consider the following strategy. Prepare the probe in some state \(|\Psi_{\varepsilon_\star}\rangle = \Pi_{\varepsilon_\star} |\Psi_{\varepsilon_\star}\rangle\) in the \(\varepsilon_\star\)-subspace. Let it evolve for an infinitesimal time \(dt\) and measure in which subspace \(\Pi_{\omega}\) it is (i.e. the energy of the probe). The probability that the jump jumps to another energy subspace labeled by \(\varepsilon \neq \varepsilon_\star\) is given by
\[
\begin{align*}
p_{\varepsilon} &= \text{tr} \Pi_{\varepsilon} e^{\rho dt} \langle \Psi_{\varepsilon_\star} | \Psi_{\varepsilon_\star} \rangle \\
&= \text{tr} \Pi_{\varepsilon} \sum_{\omega} \gamma_{\omega} A_{\omega} |\Psi_{\varepsilon_\star}\rangle \langle \Psi_{\varepsilon_\star}| A_{\omega}^\dagger \ \\
&= \text{tr} \gamma_{\omega} \langle \Psi_{\varepsilon_\star}| A_{\omega}^\dagger \Pi_{\omega} A_{\omega} |\Psi_{\varepsilon_\star}\rangle,
\end{align*}
\]
for \(\omega = \omega(\varepsilon, \varepsilon_\star)\) such that \((\varepsilon, \varepsilon_\star) \in \Pi_{\omega}\). While the probability that it remains at \(\varepsilon_\star\) is simply \(p_{\varepsilon_\star} = 1 - \sum_{\varepsilon \neq \varepsilon_\star} p_{\varepsilon}\). Computing the Fisher information for this measurement after \(dt\) we find that in the leading order
\[
\mathcal{I}_{dt} = \sum_{\varepsilon} \left( \frac{\gamma_{\omega}}{p_{\varepsilon}} \right)^2 = \text{tr} \langle \Psi_{\varepsilon_\star}| \sum_{\omega,\varepsilon} \frac{\gamma^2}{\omega} A_{\omega}^\dagger \Pi_{\omega} A_{\omega} |\Psi_{\varepsilon_\star}\rangle
\]
(22)

By maximizing this expression over all states \(|\Psi_{\varepsilon_\star}\rangle\) we find the optimal Fisher information
\[
\mathcal{I}_{dt} = \text{tr} \left\| \Pi_{\varepsilon_\star} \sum_{\omega,\varepsilon} \frac{\gamma^2}{\omega} A_{\omega}^\dagger \Pi_{\omega} A_{\omega} \right\|
\]
by definition of the operator norm. After the measurement the probe is reinitialized to the optimal state \(|\Psi_{\varepsilon_\star}\rangle\), and the same procedure is repeated. By additivity, the overall Fisher information of this scheme reads
\[
\mathcal{I}_r = \int_0^r \mathcal{I}_{dt} = \tau \sum_{\omega,\varepsilon} \frac{\gamma^2}{\omega} A_{\omega}^\dagger \Pi_{\omega} A_{\omega} \Pi_{\omega}
\]
(23)

which coincides with the upper-bound as expressed in the form of Eq. (20) (and also Eq. (19) as a particular case).

This shows that the upper-bound (17) is indeed saturated with a simple continuous measure-and-prepare strategy, where the jumps (the energy) of the probe are constantly monitored and the probe is actively reinitialized to the initial state. The optimality of fast-measurements for qubit probes was already noted numerically in Ref. [8] (see also [3, 21]), and we generalised these results to general probes and arbitrary control-assisted/adaptive schemes. In contrast to such previous results, it is worth stressing that our approach neither requires solving the Lindblad dynamics nor considering specific strategies, instead the optimal protocol can be inferred directly from simple calculation of (17) and (28). This enables us to study optimal protocols for more complex interactions and probes, as we will illustrate in Sec. 4.

3.4 Engineering of the optimal spectrum for \(H\)

The bound (17) is saturable and holds independently of the unitary control operations \(U_k\) applied during the sensing process. Nevertheless, in the context of the microscopic model in Sec. 2.3 it does depend on the probe Hamiltonian \(H\) via the jump operators \(A_{\omega}\) and the corresponding rates. The goal of this section is to find the Hamiltonian maximizing the QFI of our thermometer, given the form of the observable \(A\) coupling the probe to the sample, its temperature \(T\) and the spectral dependence of the rates \(\gamma_{\omega}\) and \(\gamma_{\omega}\). Recall that we allow the usage of auxiliary systems of arbitrary dimension. Hence, we consider Hamiltonians \(H = \sum_{\varepsilon} \varepsilon \Pi_{\varepsilon}\) acting on the probe and the auxiliary system, while only the

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probe couples to the sample $A = A_{\text{probe}} \otimes I_{\text{ancilla}}$ (this is implicit in the following discussion).

To optimize over all Hamiltonians $H$ one can vary its spectrum $(\varepsilon_1, \varepsilon_2, \ldots)$ and the subspaces $\sum \Pi_\varepsilon = 1$ independently. To find the best Hamiltonian we have to maximize the quantity $O = \left\| \sum_w \frac{\hat{\gamma}}{\gamma_0} A_w^\dagger A_w \right\|$. Starting with any Hamiltonian let us label the energy subspace that attains the maximum in Eq. (19) with $\varepsilon_\ast$, without loss of generality we can shift all the energies such that $\varepsilon_\ast = 0$ ($\Pi_{\varepsilon_\ast} \rightarrow \Pi_0$). The sum inside the norm in Eq. (19) involves positive operators $\Pi_0 A \Pi_0 A \Pi_0 = (\Pi_0 A \Pi_0) (\Pi_0 A \Pi_0)^\dagger$ and positive scalar coefficients $(\hat{\gamma}^2_\varepsilon / \gamma_{\varepsilon-\varepsilon})$. Therefore, for fixed subspaces $\Pi_\varepsilon$ the expression $O$ is maximized when all the scalar coefficients are maximized. But for any bath temperature $T$ there is indeed an optimal energy difference $\delta T$ maximizing the coefficients

$$f_T = \max \frac{\hat{\gamma}^2_\varepsilon}{\gamma_{\varepsilon-\varepsilon}}, \quad \delta T = - \arg \max \frac{\hat{\gamma}^2_\varepsilon}{\gamma_{\varepsilon-\varepsilon}}.$$ (24)

Hence, for a fixed $\Pi_0$ it is optimal to set the energies of all the other levels to the same value $\varepsilon = \delta T$. Using $\sum_{\varepsilon \neq 0} \Pi_\varepsilon = 1 - \Pi_0$ we get for the optimal choice of energies

$$O = f_T \| \Pi_0 A (1 - \Pi_0) A \Pi_0 \|.$$ (25)

For a fixed $\Pi_0$ the norm is attained by some state $|\Psi\rangle = \Pi_0 |\Psi\rangle$. Denoting $\Pi_{0,\Psi} = \Pi_0 - |\Psi\rangle \langle \Psi|$ we obtain

$$\| \Pi_0 A (1 - \Pi_0) A \Pi_0 \| = \langle \Psi | A (1 - |\Psi\rangle \langle \Psi | - \Pi_{0,\Psi}) A |\Psi\rangle \leq \langle \Psi | A (1 - |\Psi\rangle \langle \Psi |) A |\Psi\rangle.$$ (26)

But changing the Hamiltonian to one with $\Pi_0 = |\Psi\rangle \langle \Psi|$ saturates this inequality. Thus, an optimal Hamiltonian is necessarily of this form $H = \delta T (1 - |\Psi\rangle \langle \Psi |)$, which is fully degenerate except for one energy eigenstate (coincidentally, this same structure is optimal for equilibrium thermometry [8]). It remains to find the optimal state $|\Psi\rangle$. For a rank one projector $\Pi_0 = |\Psi\rangle \langle \Psi |$ the expression $\| \Pi_0 A (1 - \Pi_0) A \Pi_0 \| = \langle \Psi | A^2 |\Psi\rangle - \langle \Psi | A |\Psi\rangle^2$ is simply the variance of $A$ with respect to the state $|\Psi\rangle$. The variance of an operator is maximized on the state, which is an equal superposition

$$|\Psi_{\Delta(A)}\rangle = \frac{1}{\sqrt{2}} (|a_{\text{max}}\rangle + |a_{\text{min}}\rangle)$$ (27)

of two extremal eigenstates of $A$ $|a_{\text{max}}(\text{min})\rangle = \lambda_{\text{max}}(\text{min}) |a_{\text{max}}(\text{min})\rangle$. As a result we obtain the simple and general bound

$$F_{\varepsilon_{1T}} \leq \tau \left( \max \frac{\hat{\gamma}^2_\varepsilon}{\gamma_{\varepsilon}} \left( \frac{\Delta(A)}{2} \right)^2 \right),$$ (28)

where $\Delta(A) = \lambda_{\text{max}} - \lambda_{\text{min}}$ is the spectral gap of the operator $A$ (the difference between its maximal and minimal eigenvalues).

In summary, we have shown that the QFI of our thermometer is maximized for the almost degenerate Hamiltonian

$$H = \delta T (1 - |\Psi_{\Delta(A)}\rangle \langle \Psi_{\Delta(A)} |),$$ (29)

with the unique nondegenerate energy level $|\Psi_{\Delta(A)}\rangle$ of the form in Eq. (27). This bound allows us to formalize the original intuition – the form of the operator $A$ coupling the probe to the sample does set a general “speed limit” on thermometry. Recall that the bound can be attained with the continuous measure-and-prepare strategy, where the probe is reinitialized to the state $|\Psi_{\Delta(A)}\rangle$. It is worth noting that this strategy does not require an auxiliary system.

### 3.5 Autonomous implementation of the fast measure-and-prepare strategy

In order to exploit these ideas in practice, a possible autonomous implementation is depicted in Fig. 2. We consider a scenario where the probe is simultaneously coupled to the sample and to a zero temperature bath ($T = 0$). If $\kappa$ and $\gamma$ are parameters describing the coupling strength between the probe and each bath, $\kappa$ for the zero-temperature bath and $\gamma$ for the sample, we consider the regime $\kappa \gg \gamma$. This ensures that, every time the probe gains an excitation due to the interaction with the sample, the cold bath quickly reinitialises the probe back to its ground state. By monitoring the heat current between the probe and the cold bath at the single-photon level, one is able to keep track of the energy jumps induced on the probe by the sample (the same approach is used in quantum thermodynamics to measure heat and work statistics, see e.g. [66, 67]). This provides a simple way of performing the fast measure-and-prepare strategy introduced earlier, in which the cold bath simultaneously prepares and measures the probe.
Fisher information is still diffusive $\mathcal{F}_{\mathcal{E}}|_{\mathcal{T}} \propto \tau$ in presence of a temperature-dependent Lamb shift if the condition (15) holds. In this case, the derivative of the Lamb shift Hamiltonian can be expressed as

$$\dot{H}_{LS} = h_1 \mathbb{1} + \sum_{\omega} h_\omega A^\dagger_\omega A_\omega,$$

(30)

with some real coefficients $h_1$ and $h_\omega$ such that $h_\omega = 0$ if $\gamma_\omega = 0$. Then, we show in the appendix 7 that the bounds for a fixed $H$ (17) and for the optimal $H$ (28) are modified to the form

$$\mathcal{F}_{\mathcal{E}}|_{\mathcal{T}} \leq \tau \left| \sum_{\omega} \frac{\dot{\omega}^2_\omega + 4h^2_\omega}{\gamma_\omega} A^\dagger_\omega A_\omega \right|,$$

$$\mathcal{F}_{\mathcal{E}}|_{\mathcal{T}} \leq \tau \left( \max_{\omega} \sum_{\omega} \frac{\dot{\omega}^2_\omega + 4h^2_\omega}{\gamma_\omega} \right) \left( \frac{\Delta(A)}{2} \right)^2.$$

(31)

Here, to get the second inequality one simply repeats the derivation of section 3.4 for the new scalar functions $\left( \frac{\dot{\omega}^2_\omega + 4h^2_\omega}{\gamma_\omega} \right) \left( \frac{\Delta(A)}{2} \right)^2$.

In the case of the microscopic model, a particularly simple choice of the coefficients $h_1$ and $h_\omega$ in Eq. (30) is offered by the original expression for the Lamb shift

$$\dot{H}_{LS} = \sum_{\omega} \dot{s}_\omega A^\dagger_\omega A_\omega$$

(32)

assuming that $\gamma_\omega \neq 0$ if $\dot{s}_\omega \neq 0$. This choice gives rise to simple upper bounds

$$\mathcal{F}_{\mathcal{E}}|_{\mathcal{T}} \leq \tau \left| \sum_{\omega} \frac{\dot{\omega}^2_\omega + 4\dot{s}^2_\omega}{\gamma_\omega} A^\dagger_\omega A_\omega \right|,$$

$$\mathcal{F}_{\mathcal{E}}|_{\mathcal{T}} \leq \tau \left( \max_{\omega} \sum_{\omega} \frac{\dot{\omega}^2_\omega + 4\dot{s}^2_\omega}{\gamma_\omega} \right) \left( \frac{\Delta(A)}{2} \right)^2.$$

(33)

that are directly expressible with quantities appearing in the master equation (10). The disadvantage is that they might diverge in the low-temperature limit where the jump rates $\gamma_\omega$ can become negligible compared to $s_\omega$, as we will see in the next section. In this case it is better to use the more general bounds of Eqs. (30) and (31) with an appropriate choice of $h_\omega$.

The main difference between Eq. (31) and (17) concerns the attainability of these bounds. First, it is important to note that the Fisher information of the fast measure-and-prepare strategy is not affected by a Lamb shift. Indeed, due

This assumption is common in the literature on quantum thermometry.

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to the Zeno effect it does not affect the measurement probabilities after an infinitesimal time \(dt\). Therefore, the values on the rhs of the inequalities (17) and (28) can still be attained in presence of a Lamb shift. However, these values are not tight with the new upper-bounds. Furthermore, the Zeno effect also implies that to approach the new bounds one has to move away from continuous measurement schemes which are insensitive to Lamb shift. Even if the bounds (31) and (33) are not necessarily attainable by any measurement strategy, it is important to stress that the presence of the Lamb shift can only improve the estimation precision. This will be illustrated in the following example, where we will see that the presence of Lamb shift can enable dramatic enhancements in the low-temperature regime.

4 Case studies

In this section we apply our general results to two pedagogical and experimentally relevant examples. First, we consider a qubit probe with an explicit model of the sample as a collection of bosonic modes. This allows us to obtain explicit expressions for the jump rates in terms of sample properties, and discuss different temperature regimes. Second, we consider the case of an \(N\)-qubit probe with a two-body Hamiltonian and coupled collectively to the sample. Here, we discuss the scaling of the thermometer precision with \(N\).

4.1 Qubit probe

We consider a qubit probe weakly interacting with a bosonic sample (bath). This is a common scenario in thermometry experiments at the quantum scale, such as in the temperature measurement of cold atomic ensembles \([72, 73]\), nanoresonators \([17, 18]\), and black body radiation thermometry \([74]\) through two-level probes.

We start from the Hamiltonian

\[
H_{\text{tot}} = \frac{\omega}{2} \sigma_z + \sigma_x \int_0^\Omega \sqrt{J(x)} \left( b_x + b_x^\dagger \right) \, dx + \int_0^\Omega x b_x^\dagger b_x \, dx,
\]

(34)

where \(\omega\) is the frequency of the probe, \(b_x\) (\(b_x^\dagger\)) are annihilation (creation) operators of a bosonic mode at frequency \(x\), \(J(x)\) is the spectral density of the sample or bath, and \(\Omega\) is a cut-off frequency. This is a particular case of the model discussed in Sec. 2.3 with \(H = \frac{\omega}{2} \sigma_z, A = \sigma_x, B = \int_0^\Omega \sqrt{J(x)} \left( b_x + b_x^\dagger \right) \, dx \) and \(H_2 = \int_0^\Omega x b_x^\dagger b_x \, dx\). Following the standard derivation of the master equation in the weak coupling regime through the Born-Markov and secular approximations \([51]\), we obtain the Lindblad equation (6) where

\[
A_w = \sigma_- \quad A_{-w} = \sigma_+ \quad (35)
\]

and the rates \(\gamma_w = 2\pi J(w)(1 + N(w)), \gamma_{-w} = 2\pi J(w)N(w) < \gamma_w, \) with \(N(w) = (e^{\beta w} - 1)^{-1}\) the Bose-Einstein distribution. Furthermore, the Lamb shift takes the form \(H_{LS} = s_w A_w^\dagger A_w + s_{-w} A_{-w}^\dagger A_{-w}, \) with \(s_w = -\Delta T + \Delta, s_{-w} = \Delta T, \Delta T, \Delta\) are given by (see e.g. \([59]\)):

\[
\Delta = \mathbb{P} \left[ \int_0^\Omega J(x) \frac{dx}{x - w} \right],
\]

\[
\Delta T = \mathbb{P} \left[ \int_0^\Omega J(x)N(x) \frac{dx}{x - w} \right].
\]

(36)

Here \(\mathbb{P}\) denotes the Cauchy principle value of the integral. Note that all the temperature dependence is encoded in \(N(w)\), which enters into \(\gamma_w, \gamma_{-w}\) and \(H_{LS}\). This implies \(\dot{s}_{-w} = -\dot{s}_w\) with

\[
H_{LS} = -\dot{s}_w \sigma_z,
\]

(37)

and \(\dot{\gamma}_{-w} = \dot{\gamma}_w\). For concreteness, in what follows we assume a spectral density of the form

\[
J(w) = gw^\alpha, \quad w \leq \Omega
\]

(38)

where \(\alpha\) determines the Ohmicity of the sample \((\alpha = 1\) for an Ohmic bath).

4.1.1 Upper bounds on the QFI

In order to compute Eq. (31), we first note that the condition (15,30)

\[
\dot{H}_{LS} = -\dot{s}_w \sigma_z = h_1 1 + h_w |1\rangle\langle 1| + h_{-w} |0\rangle\langle 0|
\]

(39)

implies

\[
\begin{cases}
\dot{h}_w = \dot{s}_w - x \\
\dot{h}_{-w} = -\dot{s}_w - x,
\end{cases}
\]

(40)

leaving a free parameter \(x = h_1\). The bound (31) then takes the form

\[
\mathcal{F}_{\text{QFI}} \leq T \min_x \left\| \frac{\hat{J}^2 + 4(s_w + x)^2}{\gamma_{-w}} \frac{\hat{J}^2 + 4(s_w - x)^2}{\gamma_w} \right\|.
\]

(41)
In the appendix we derive the closed form expression of the bound optimized with respect to \( x \). The resulting expression is a little lengthy, but two limiting regimes are simple to understand. In the low temperature limit \((T \to 0)\) the rate \( \gamma_w \) goes to zero faster than \( \dot{s}_w \). To cancel the diverging term \((\dot{s}_w + x)^2 \) we then choose \( x = -\dot{s}_w \) so that the bound reads

\[
F_{E_r} | T \leq \tau \frac{\dot{s}_w^2 + 16\dot{s}_w^2}{\gamma_w}. \tag{42}
\]

In the high temperature limit \((T \to \infty)\) the values \( \gamma_w \approx \gamma_{-w} \) become relatively close. Then a good choice is to set \( x = 0 \), yielding the bound

\[
F_{E_r} | T \leq \tau \frac{\gamma_w^2 + 4\dot{s}_w^2}{\gamma_{-w}}. \tag{43}
\]

Of course both bounds (42,43) remain valid for all \( T \), but are the tightest in the respective temperature limits.

In Fig. 3 we plot the upper bound (41) for an Ohmic sample (similar results are obtained for different \( \alpha \)). In the temperature range of Fig. 3(a) we observe that most of the contribution to the upper bound of \( F \) arises from the rates, whereas the Lamb shift provides a small but non-negligible contribution. Interestingly, a completely different picture appears in the low-temperature regime \( T \ll w \) of Fig. 3(b). In this case, it is well known that thermometry becomes exponentially hard: \( F \propto e^{w/T} \) \[7, 41, 42\], as it can be inferred from \( N(w) = \mathcal{O}(e^{w/T}) \). Remarkably, this is no longer the case if the Lamb shift contribution is not neglected. We find that \( \Delta_T \) at low temperatures takes the form:

\[
\Delta_T \approx J(w)b_\alpha \left( \frac{T}{w} \right)^{1+\alpha}, \quad T \ll w, \tag{44}
\]

where we have defined \( b_\alpha \equiv f_\alpha \Gamma(\alpha + 1) \) with \( \Gamma(\alpha) \) the Gamma function and \( f_\alpha = \mathcal{O}(1) \). From (42) using \( \gamma_w \approx 2\pi J(w) \) we obtain the upper bound

\[
F_{E_r} | T \leq \tau \frac{8J(w)(1+\alpha)^2b_\alpha^2}{\pi w^2} \left( \frac{T}{w} \right)^{2\alpha} \quad \text{for} \quad T \ll w. \tag{45}
\]

Notably, for a flat spectral density \((\alpha = 0)\), the QFI can in principle remain constant with \( T \to 0 \), which is not in contradiction with the fundamental bounds derived in Ref. [27, 43]. In Sec. 4.1.4 we will discuss the saturability of this bound with explicit measurement schemes.
4.1.2 Optimal finite-time thermometry through a qubit probe

We first consider the scenario where control over $w$ is possible, so that the probe can be engineered to perform at the maximum QFI, as in Fig. 3 (a). In this case, the Lamb shift plays a secondary role, and we neglect it in this subsection. In this case, we can use the bound of Eq. (17), which becomes $F_{\mathcal{E}_{w}|T} \leq \tau \gamma w^3 e^{2\beta} w^{2+\beta} 1 \tau^{-1}$. 

As discussed above, it can be saturated with the fast measurement-and-prepare strategy where the probe’s state is not reinitialised. The determination of spectral asymmetry based on strong sample-probe coupling have been suggested to avoid the exponential decaying QFI [27, 41–43]. We now sketch a new non-equilibrium approach that works in the weak coupling regime, and instead exploits the temperature dependence of the Lamb shift via a coherent evolution of the probe.

4.1.4 Low temperature regime: Lamb shift thermometry

We have already noticed the potential importance of the Lamb shift contribution to the bound in the low-temperature regime through the upper bound shown in Fig. 3 (b). This is arguably the most challenging regime for thermometry, and several strategies for equilibrium thermometry based on strong sample-probe coupling have been suggested to avoid the exponential decaying QFI [27, 41–43].

We start by explicitly solving the qubit master equation. In the limit $T \ll w$ the rate $\gamma_w \rightarrow 0$, so that the jumps induced by the operator $A_{-w} = \sigma_+$ can be neglected. Furthermore, in this regime $\gamma_w \ll \delta_w$ as discussed around Eq. (??) regime, and the contribution of $\gamma_w$ to the QFI can also be neglected. The qubit master equation then becomes

$$\frac{d}{dt} \rho = -i [\frac{1}{2} w \sigma_z + H_{LS}, \rho] + \gamma_w \left( \sigma_+ \rho \sigma_+ - \frac{1}{2} \{ |1\rangle\langle 1|, \rho \} \right).$$

The Lamb shift contribution to the Hamiltonian reads $H_{LS} = \begin{pmatrix} \Delta_T + \frac{1}{2} \Delta & 0 \\ 0 & -\Delta_T - \frac{1}{2} \Delta \end{pmatrix}$, where we shifted the energy scale to $\text{tr} H_{LS} = 0$. The solution of the master equation is straightforward, and can be found in Appendix 8.2. From Eq. (48) it is clear that we are dealing here with the problem of frequency estimation in presence of spontaneous noise ($\tau_1$-relaxation).

We consider three different sensing strategies, described in appendix 8.2 in detail. The simplest strategy (i) consists in preparing the qubit in the state $|\Psi_0\rangle = \sqrt{T-a} |0\rangle + \sqrt{a} |1\rangle$, letting it evolve for some finite time $t$, after which the qubit is measured and the procedure is repeated. For the second strategy (ii) we introduce an auxiliary qubit, which is not in contact with the sample. The probe and auxiliary qubits are repeatedly prepared in the state $|\Psi_0\rangle = \sqrt{T-a} |00\rangle + \sqrt{a} |11\rangle$, evolve freely, and are measured after some time $t$. The entanglement between the two qubits allows the final measurement to know if a jump $\sigma_-$ occurred dur-

---

Note that accounting for the Lamb shift can only make the protocol better. At the same time, the fast measurement-and-prepare strategy is completely insensitive to the presence of a Lamb shift. Hence, exploiting the Lamb shift requires finite times between subsequent measurements of the probe.
ing the evolution (such a jump projects the system to the state $|01\rangle$ changing the parity). The third strategy (iii) requires some continuous control on top of entanglement with the auxiliary qubit. Here, the qubits are again prepared in the state of the form $|\Psi_0\rangle = \sqrt{1-a} |00\rangle + \sqrt{a} |11\rangle$, but the parity of the pair is monitored continuously, with repeating the measurement described by the POVM $\{\Pi_0 = |00\rangle\langle00| + |11\rangle\langle11|, \Pi_x = |1 - \Pi_0\}$. As often as possible. If the error outcome “x” occurs the qubit pair is reinitialised. Otherwise, if no errors are observed for some time $t$ the system is measured and reinitialised.

One notes that the coherent part of the dynamics $-i[\sigma_z \otimes 1, \rho]$ does not change the parity of the qubit pair and is unperturbed by the measurements $\{\Pi_0, \Pi_x\}$. The strategy (i) describes the usual Ramsey interferometer. The strategies (ii) and (iii) build on (i) by implementing the error-detection schemes considered in [37]. After long enough running time $t \gg t$ all three strategies lead to the QFI of the form

$$\mathcal{F}_{E_x} = \frac{\alpha^2}{\gamma_{\text{w}}},$$

(49)

with different constants $\alpha$. Optimizing the parameters $a$ and $t$ we find the values of $\alpha$ given in Table 1. These values are interesting to compare with the upper-bound of Eq. (42) $\mathcal{F}_{E_x} = 16 \frac{a^2}{\gamma_{\text{w}}}$. In the low temperature regime, the $\mathcal{F}_{E_x}$ hence also scales as $T^{2a}$, as seen from Eq. (42), which can be compared to similar polynomial scalings at low $T$ obtained in the literature via strong coupling [41–43]. These results illustrate the potential of quantum coherent control and entanglement for low-temperature thermometry.

| strategy | description | $\alpha$ |
|----------|-------------|---------|
| (i)      | Ramsey interferometer | 1.5 0.5 |
| (ii)     | +entanglement with ancilla | 2.47 0.68 |
| (iii)    | + continuous control | $\approx$ 4.16 0.83 |

Table 1: The performance of the thee low-temperature Lamb shift thermometers with a qubit probe, described in the text. In all cases the QFI is given by $\mathcal{F}_{E_x} = t \frac{\alpha^2}{\gamma_{\text{w}}}$. Initially the system is prepared in the state $|\Psi_0\rangle = \sqrt{1-a} |00\rangle + \sqrt{a} |11\rangle$ for (i), and $|\Psi_0\rangle = \sqrt{1-a} |00\rangle + \sqrt{a} |11\rangle$ for (ii) and (iii), which involve an auxiliary qubit.

4.2 Collective thermalisation

We now consider a $N$-qubit probe, which is coupled collectively to a sample. The interaction Hamiltonian takes the form

$$H_I = J_x \otimes B$$

(50)

with $J_x = \sum_j \sigma_x^{(j)}$, and $B$ is an unspecified operator acting on the bath. This type of collective coupling leads to the well known phenomena of sub/superradiance [44], and has received renewed interest due to the possibility of realising it in several physical platforms [77]. It is also worth pointing out that equilibrium thermometry with this collective coupling has been recently studied in [45]. We now study it in the context of finite-time non-equilibrium thermometry.

First of all, we note that the fundamental upper bound Eq. (28), obtained under Born-Markov and secular approximations, yields

$$\mathcal{F}_{E_{\text{max}}} \leq \tau \left( \max_j \frac{i^2 \omega}{\gamma_{\omega}} \right) N^2.$$  

(51)

which holds independently of the specific local Hamiltonian of the probe and sample (note that the $\gamma_{\omega}$’s depend on the specific sample into consideration). Hence, the coupling (50) in principle enables a quadratic scaling with $N$, as it may be expected from the phenomenon of superradiance. However, saturating (51) in principle requires engineering the $N$-qubit probe Hamiltonian of Eq. (29) discussed in Sec. 3.4, i.e the probe needs to behave as an effective two level system (with a $2^{N-1}$ degeneracy of the upper-level). This corresponds to an $N$-body interaction between the qubits, and is a priori very hard to achieve experimentally. In what follows we consider structurally simpler probes.

4.2.1 Non-interacting qubits probe

We start by considering $N$ independent qubits, i.e $H = w J_z$ with $J_z = \frac{1}{2} \sum_j \sigma_z^{(j)}$ and a tunable frequency $w$. The eigenstates of $H$ can be conveniently expressed in the collective spin basis. Here, it will suffice to focus on the set of sym-
metric states (Dicke states)\(^7\)
\[
|\psi_n\rangle = \frac{J_+}{\sqrt{N_n}} |\psi_{n-1}\rangle, \quad \Gamma_n \equiv n(N + 1 - n)
\]
\[
H|\psi_n\rangle = w (n - N/2) |\psi_n\rangle
\]  
(52)
with \(n = 0, ..., N\), and where \(|\psi_0\rangle = |0\rangle^\otimes N\) is the ground state and \(J^+ = \sum_j \sigma_j(1)\) (where \(\sigma_+ = |1\rangle\langle 0|\)). Constraining to the states (52) is justified because (i) the dynamics do not mix the subspace spanned by \{\{|\psi_n\rangle\}\} with the rest of the Hilbert space, and (ii) the states (52) have the fastest decay rate, and hence are the most useful for finite-time thermometry. In this subspace, there are two jump operators in the master equation reading \(A_w = \sum_{n=0}^{N-1} |\psi_n\rangle\langle \psi_n| J_x |\psi_{n+1}\rangle\langle \psi_n| = \sum_{n=0}^{N-1} \sqrt{\Gamma_{n+1}} |\psi_{n+1}\rangle\langle \psi_n| = J_+\) for the transition \(+w\), and \(A_{-w} = A_w^\dagger = J_-\) for the transition \(-w\) (here \(J_\pm\) operators are restricted to subspace of symmetric states). Plugging these expressions in (17), we obtain
\[
\frac{\mathcal{F}_{\text{fast}}}{\tau} \leq \sum_{n=0}^{N} |\psi_n\rangle\langle \psi_n| \left[ \Gamma_n \frac{\gamma_w^2}{\gamma_w^2 + \Gamma_{n+1} \gamma_{-w}} + \Gamma_{n+1} \frac{\gamma_{-w}^2}{\gamma_{-w}^2 + \Gamma_n \gamma_w} \right] = \frac{N}{2} \left(\frac{N}{2} + 1\right) \left( \frac{\gamma_w^2}{\gamma_w^2 + \Gamma_n \gamma_{-w}} + \frac{\gamma_{-w}^2}{\gamma_{-w}^2 + \Gamma_{n+1} \gamma_w} \right),
\]  
(53)
where the operator norm is saturated for \(n = N/2\) for which \(\Gamma_n \frac{\gamma_w^2}{\gamma_w^2 + \Gamma_n \gamma_{-w}} = \frac{N}{4}(N/2 + 1)\), for simplicity we assume an even \(N\) here and in the rest of the section. Compared to the general upper bound (51), we also observe a quadratic scaling with \(N\) but with a worse prefactor. In particular, since \(0 \leq \frac{\gamma_w^2}{\gamma_w^2 + \Gamma_n \gamma_{-w}} \leq \frac{\gamma_w^2}{\gamma_{-w}^2 + \Gamma_{n+1} \gamma_w}\), we notice that for large \(N\) one loses a factor laying between 1/2 and 1/4 as compared to the general upper bound (51). For example, for a bosonic reservoir with rates
\[
\gamma_w = gw^\alpha N(w)
\]
\[
\gamma_{-w} = gw^\alpha (1 \pm N(w))
\]  
(54)
and \(N(w) = (e^{\beta w} - 1)^{-1}\), it is satisfied that \(\frac{\gamma_w^2}{\gamma_{-w}^2} = e^{\beta w} \gamma_w^2 / \gamma_w\), so that the ratio between (53) and (51) becomes \((1 + e^{-\beta w})/4\) at leading order in \(N\). It is remarkable that such a good performance can be obtained with arguably the simplest probe consisting of non-interacting qubits with \(H = w J_z\).

\(^7\)associated to the maximal value \(\frac{N}{2}(\frac{N}{2} + 1)\) of the total spin \(J^2\).

Figure 4: Classical Fisher information for the fast measure-and-prepare protocol where the state \(|\psi_{N/2}\rangle\) evolves for a finite amount of time \(\delta t\) before performing the measurement. The superradiant advantage \(\mathcal{I} \propto N^2\) requires \(\delta t \propto 1/N^2\).

4.2.2 The effect of measurement frequency

The bound (53) can be saturated by the fast measure-and-prepare strategy, where the probe is continuously reinitialised in the state \(|\psi_{N/2}\rangle\). In practice, the frequency of the measurements can be limited and it is relevant to consider sub-optimal strategies where the state evolves for a finite time \(\delta t\) before being measured. For a given \(\delta t\) and total sensing time \(\tau\), we then consider the fast measure-and-prepare strategy with a finite measurement frequency, described below.

The probe is initialised in the state \(|\psi_{N/2}\rangle\), and is left to interact with the sample for a time \(\delta t\) according to the master equation
\[
\frac{d}{dt}\rho = -i[H, \rho] + \gamma_w \left( J_+ \rho J_+ - \frac{1}{2} \{J_+, J_-, \rho\}\right) + \gamma_{-w} \left( J_- \rho J_- - \frac{1}{2} \{J_-, J_+, \rho\}\right).
\]  
(55)
Focusing on the superradiant subspace, it is convenient to express this as a stochastic evolution of the probabilities \(p_n \equiv \langle \psi_n | \rho | \psi_n \rangle\) to occupy each state, given by
\[
\frac{d}{dt} p_m = -p_m \left( \gamma_w \Gamma_m + \gamma_{-w} \Gamma_{m+1}\right) + \gamma_w p_{m+1} \Gamma_{m+1} + \gamma_{-w} p_{m-1} \Gamma_m.
\]  
(56)
After a time \(\delta t\), the resulting state \(p_j = p_j(\delta t)\) is measured, providing the classical Fisher information \(\mathcal{I}_{\delta t} = \sum_j p_j^2 / p_j\).

This process is repeated for \(k\) times until \(k\delta t = \tau\), yielding a total Fisher information of
Ib correspond to different values of \( \alpha \) obtained. In (b) we instead vary \( \gamma \), \( \delta t \).

\[ H = \omega J_z + b J_z^2, \quad (57) \]

Figure 5: Classical Fisher information of the measure-and-prepare scheme in the limit \( \delta t \to 0 \) for the generalised Hamiltonian \( H(b) = \omega J_z/2 + b J_z^2 \). In (a), we compare a scheme where the probe is prepared in the optimal state with one where it is prepared in the ground state. In this figure, we vary \( \omega \) while keeping \( \alpha = 1 \), \( T = 1 \) and \( N = 50 \), and compare the results to those obtained. In (b) we instead vary \( N \) and different curves correspond to different values of \( b \).

\[ \mathcal{I}_{\text{tot}} = k \mathcal{I}_{\delta t} = \tau \frac{\mathcal{I}_{\delta t}}{\tau} \].

In Fig. 4, we plot \( \mathcal{I}_{\text{tot}}/\tau = \mathcal{I}_{\delta t}/\delta t \) as a function of \( \delta t \) for different \( N \) and for a bosonic sample with Ohmic spectral density, \( \alpha = 1 \) in Eq. (54). While Fig. 4 clearly shows the quadratic advantage for \( g \delta t \to 0 \), it is also observed that this requires \( g \delta t < 1/N^2 \). When this condition is not met, the superradiant advantage is rapidly lost, and in fact non-superradiant states (\( N = 1 \), prepared in the ground state) become better for \( g \delta t \geq 0.1 \).

Summarising, although the simplest probe allows for a quadratic scaling of the Fisher information with \( N \), this quantum advantage faces two main challenges. (i) The probe needs to be repeatedly prepared in the state \( |\psi_{N/2}\rangle \), which is highly non-trivial in practice (see e.g. [78]). (ii) As shown in Fig. 4, the time \( \delta t \) after which each measurement and state preparation must be repeated decreases as \( \delta t \propto 1/N^2 \), which becomes increasingly difficult with increasing probe size \( N \).

### 4.2.3 Interacting qubits probe

We will now show that a potential route to overcome both challenges is offered by engineering slightly more complicated probes. In particular, we now consider \( N \) qubit probes subject to two-body interactions \( \sigma_z^{(i)} \sigma_z^{(j)} \), the probe Hamiltonian

\[ H = w J_z + b J_z^2, \]

for tunable parameters \( w \) and \( b \). This is arguably the simplest probe Hamiltonian after the non-interacting case \( (b=0) \) considered above, and such two-body interaction are for example implemented in spin squeezing experiments (one axis twisting [71]). The additional term \( bJ_z^2 \) keeps the eigenvectors \( |\psi_n\rangle \) unmodified, but changes the spectrum of the Hamiltonian \( H |\psi_n\rangle = e_n |\psi_n\rangle \), which is now given by

\[ e_n = w \left(n - \frac{N}{2}\right) + b \left(n - \frac{N}{2}\right)^2. \quad (58) \]

By deriving the energy \( e_n \) with respect to \( n \) to find it’s local minimum, one concludes that the ground state \( |\psi_n^*\rangle \) corresponds to

\[ n^* = \text{argmin}_n e_n \in \left\{ \left\lfloor \frac{N}{2} - \frac{w}{2b} \right\rfloor, \left\lfloor \frac{N}{2} - \frac{w}{2b} + 1 \right\rfloor \right\}, \quad (59) \]

depending on the parameter values. It is simple to see that \( n^* \) approaches \( N/2 \) as \( b \) is increased.

In particular, for \( b > w \) the state \( |\psi_{N/2}\rangle \) with \( e_{N/2} = 0 \) becomes the ground state, and the energy gaps to the next levels read

\[ \Delta = e_{N/2} - e_{N-1} = -(b - w) \]
\[ \Delta' = e_{N/2} - e_{N+1} = -(b + w). \quad (60) \]

Our autonomous strategy of Sec. 3.5, then gives

\[ \mathcal{I}_{\text{tot}} = \tau \left( \Gamma_{N/2} \frac{\Delta^2}{\Delta} + \Gamma_{N+1} \frac{\Delta'^2}{\Delta'} \right) \]
\[ = \tau \frac{N}{2} \left( N^2 - 1 \right) \left( \frac{\Delta^2}{\Delta} + \frac{\Delta'^2}{\Delta'} \right). \quad (61) \]

By choosing \( w = 0 \) and maximizing over \( b \) we get the optimal Fisher information of

\[ \mathcal{I}_{\text{tot}} = \frac{1}{2} \tau \left( N^2 + 2N \right) \max_b \frac{\Delta^2}{\Delta}, \quad (62) \]

![Graph](image_url)
which is only a factor 1/2 lower as compared to the general upper-bound of Eq. (51). Thus, engineering a quadratic Hamiltonian allows one to attain half of the optimal QFI with a simple autonomous strategy: the probe is measured and reinitialized to the ground state via its coupling to the cold bath (Fig. 2).

In practice, it might be difficult to reach a regime where \( b > w \), while getting some superradiance effect does not require going to the state \( |\psi_{N/2}\rangle \). For this reason we also numerically study the regime of lower \( b \). In Fig. 5 we plot \( \mathcal{I}_{\text{tot}}/\tau \) given a bosonic sample and setting \( w = 1 \) and \( N = 50 \). Interestingly, low values of \( b \approx 0.05 \) provide the best performance, which is close to that obtained with \( |\psi_{N/2}\rangle \) for \( b = 0 \) (here \( w \) is not optimized but kept fixed). Furthermore, in Fig. 5 (b), we show that this conclusion remains true as \( N \) is increased.

In conclusion, the quadratic scaling \( \mathcal{I}_{\text{tot}} \propto N^2 \) can in principle be realised through the autonomous scheme described in Fig. 2, where the probe is also (collectively) coupled to a \( T = 0 \) bath. Furthermore, from the numerical example we picked one sees that this can be done even when the quadratic interaction term in the Hamiltonian of Eq. (57) is lower than the energy splitting of individual qubit by at least an order of magnitude \( b/w < 5\% \). In principle, depending on the sample temperature \( T \) and the size of the probe \( N \) the required ratio \( b/w \) might be much lower, but we leave this question for future work.

5 Outlook and conclusions

In this paper, we considered the task of estimating the temperature of a sample by letting it interact with a probe for a finite duration. We derived fundamental bounds on the measurement precision for a large class of processes where the probe’s evolution is well described by a Markovian master equation. This was achieved by considering the most general quantum control on the probe: arbitrary control on its state and Hamiltonian, and the possibility to realise arbitrary (adaptive, entangling) measurements. In contrast, we assumed the sample-probe interaction to be fixed, setting a bottleneck for how fast the temperature of the sample can be imprinted on the state of the probe. In this sense, our results can be understood as a “causation” speed limit relating a particular sample-probe interaction with the speed at which a property of the sample causes a detectable change in the probe (quantified by the Quantum Fisher Information of the probe with respect to a particular parameter of the sample). While deriving these results, we realised that beyond thermometry these limits are valid in a much broader context where a physical property of a sample is estimated through its interaction with the probe, whose evolution can be well described by a Markovian evolution. Our results hence provide a general framework for placing fundamental limits in finite-time sensing in open (quantum) systems.

We also discussed the attainability of these limits. Whenever the Lamb shift term in the master equation can be neglected, we showed that they can be saturated by a fast measure-and-prepare strategy, and developed an autonomous implementation of this scheme (see Fig. 2). In principle, the presence of a temperature-dependent Lamb shift can enhance the sensitivity, which however requires moving away from the fast measurement limit to a frequency estimation regime, that we illustrated with some examples. This becomes particularly relevant at low temperatures, where we argued that the Lamb shift can play a dominant role for finite-time sensing (see Fig. 3).

The results of this paper have been obtained by assuming local control on the probe and effectively describing the thermal sample through a Markovian master equation. This framework is of relevance for both theoretical works in non-equilibrium thermometry [3] as well as for thermometry experiments through quantum probes [31, 40, 79]. Moving beyond the Markovian approximation, a challenging future endeavour is to derive similar results in the strong coupling regime, where the probe-sample evolution is generally described as a unitary process. Strong coupling naturally enables a faster rate of information transfer between sample and probe, and hence appears as a promising resource for non-equilibrium thermometry, whose potential remains mostly unexplored (see Refs. [5, 41–43] for works exploiting strong coupling for equilibrium thermometry). In particular, in order to generalise the results presented here, ideally one wishes to derive fundamental bounds on the probe’s QFI after a finite time for a given interaction and sample Hamiltonian. In general,
this appears as an impossible task when assum-
ing full quantum control on the probe as done
here. However, one may hope that some insights
can be obtained in constrained scenarios such as
in the the linear-response regime [80, 81].

When considering microscopic models for the
probe-sample interaction, in this paper we fo-
cused on interactions of the form $A \otimes B$ (see Eq.
(8)). It hence remains an open and relevant ques-
tion to investigate possibilities and fundamen-
tal limits arising when considering more general
probe-sample interactions of the form $\sum_j A_j \otimes B_j$.

In this sense, an exciting question that we leave
for future work is whether ballistic or Heisenberg
scaling is possible in thermometry, i.e., $F \propto \tau^2$.

The fact that the temperature can also be co-
erently estimated through the Lamb shift as a
frequency (see protocols in Sec. 4.1) suggests
that Heisenberg scaling could be possible in en-
gineered or exotic reservoirs.

Finally, in this article we took the Quantum/Classical Fisher Information as figures of
merit for thermometry. In the future, it will be
interesting to consider a Bayesian framework for
thermometry, and to better understand the im-
pliation of our bounds in this context.

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6 Diffusive scaling of the QFI

Consider the master equation \( \frac{d\rho}{dt} = \mathcal{L}(\rho) \) of Eq. (6) with the Hamiltonian \( H + H_{LS} \) and the dissipate term given by

\[
\mathcal{D}(\rho) = \sum_{\omega} \gamma_{\omega} \left( A_{\omega} \rho A_{\omega}^\dagger - \frac{1}{2} \{ A_{\omega}^\dagger A_{\omega}, \rho \} \right)
\]

A Kraus representation of the infinitesimal channel \( e^{it\mathcal{L}} \) is given in Eq. (12)

\[
K = \begin{pmatrix}
1 - dt \frac{1}{2} \sum_{\omega} \gamma_{\omega} A_{\omega}^\dagger A_{\omega} - i dt (H + H_{LS}) & \vdots & \sqrt{dt \gamma_{\omega} A_{\omega}} \\
\vdots & \ddots & \vdots \\
\sqrt{dt \gamma_{\omega} A_{\omega}} & \cdots & \frac{\sqrt{dt} \gamma_{\omega}}{2\sqrt{\gamma_{\omega}}} A_{\omega}
\end{pmatrix}
\]

Assuming that the jump operators are independent of the parameter, the derivatives of the Kraus operators with respect to to the parameter read

\[
\dot{K} = \begin{pmatrix}
dt \left( \frac{1}{2} \sum_{\omega} \dot{\gamma}_{\omega} A_{\omega}^\dagger A_{\omega} + i \dot{H}_{LS} \right) & \vdots & \frac{\sqrt{dt} \dot{\gamma}_{\omega}}{2\sqrt{\gamma_{\omega}}} A_{\omega} \\
\vdots & \ddots & \vdots \\
\frac{\sqrt{dt} \dot{\gamma}_{\omega}}{2\sqrt{\gamma_{\omega}}} A_{\omega} & \cdots & \frac{\sqrt{dt} \dot{\gamma}_{\omega}}{2\sqrt{\gamma_{\omega}}} A_{\omega}
\end{pmatrix} + i \dot{K}^\dagger h K
\]

Let us now compute \( K^\dagger (\dot{K} + i h K) \) up to the order \( O(dt) \) to determine if ballistic scaling of the QFI is possible

\[
K^\dagger (\dot{K} + i h K) = K^\dagger \dot{K} + i K^\dagger h K
\]

\[
= \begin{pmatrix}
1 - dt \frac{1}{2} \sum_{\omega} \gamma_{\omega} A_{\omega}^\dagger A_{\omega} + i dt (H + H_{LS}) & \vdots & \sqrt{dt \gamma_{\omega} A_{\omega}} \\
\vdots & \ddots & \vdots \\
\sqrt{dt \gamma_{\omega} A_{\omega}} & \cdots & \frac{\sqrt{dt} \gamma_{\omega}}{2\sqrt{\gamma_{\omega}}} A_{\omega}
\end{pmatrix}^T \begin{pmatrix}
\frac{\sqrt{dt} \gamma_{\omega}}{2\sqrt{\gamma_{\omega}}} A_{\omega} \\
\vdots \\
\frac{\sqrt{dt} \gamma_{\omega}}{2\sqrt{\gamma_{\omega}}} A_{\omega}
\end{pmatrix} + i K^\dagger h K
\]

\[
= -dt \left( \frac{1}{2} \sum_{\omega} \dot{\gamma}_{\omega} A_{\omega}^\dagger A_{\omega} + i \dot{H}_{LS} \right) + dt \frac{1}{2} \sum_{\omega} \dot{\gamma}_{\omega} A_{\omega}^\dagger A_{\omega} + i K^\dagger h K
\]

\[
= i \left( -dt \dot{H}_{LS} + K^\dagger h K \right).
\]

The last equation falls in the general context considered in [38], from which we know that \( -dt \dot{H}_{LS} + K^\dagger h K = O(dt^{3/2}) \) can be fulfilled if and only if

\[
\dot{H}_{LS} \in \text{span} \left\{ 1, \sqrt{\gamma_{\omega}} (A_{\omega} + A_{\omega}^\dagger), \sqrt{\gamma_{\omega}} (A_{\omega} - A_{\omega}^\dagger), \sqrt{\gamma_{\omega}} \gamma_{\omega'} (A_{\omega}^\dagger A_{\omega'} + A_{\omega'}^\dagger A_{\omega}), \sqrt{\gamma_{\omega}} \gamma_{\omega'} i(A_{\omega}^\dagger A_{\omega'} - A_{\omega'}^\dagger A_{\omega}) \right\}.
\]

One can see this explicitly by writing the Gauge matrix in the form \( h \) with a complex vector \( h = (\ldots, h_{\omega}, \ldots) \) and an Hermitian matrix \( \tilde{h} \), so that in the leading order

\[
K^\dagger h K = h_{00} + \sum_{\omega} \sqrt{\gamma_{\omega}} (h_{\omega} A_{\omega} + h_{\omega}^* A_{\omega}^\dagger) + \sum_{\omega,\omega'} dt \sqrt{\gamma_{\omega} \gamma_{\omega'}} (\tilde{h}_{\omega\omega'} A_{\omega}^\dagger A_{\omega'} + \tilde{h}_{\omega\omega'}^* A_{\omega'}^\dagger A_{\omega}).
\]
Let us now add the assumption that the Lamb shift Hamiltonian is block-diagonal $H_{LS} = \sum_\varepsilon \Pi_\varepsilon H_{LS} \Pi_\varepsilon$, which brings additional structure relating the jump operators $A_\omega$ and $H_{LS}$. Recall that the jump operators are off-diagonal

$$A_\omega = \sum_{(\varepsilon, \varepsilon')} \Pi_\varepsilon A_\omega \Pi_{\varepsilon'},$$

while $H_{LS}$ (and thus $\dot{H}_{LS}$) is block-diagonal

$$\dot{H}_{LS} = \sum_\varepsilon \Pi_\varepsilon \dot{H}_{LS} \Pi_\varepsilon.$$

It follows that $\dot{H}_{LS}$ is orthogonal to all the jump operators (with respect to the Hilbert-Schmidt product). Furthermore, a product of two jump operators for $\omega \neq \omega'$

$$A_{\omega}^\dagger A_{\omega'} = \sum_{(\varepsilon, \varepsilon')} \Pi_\varepsilon A_{\omega} \Pi_{\varepsilon'} A_{\omega'} = \sum_{(\varepsilon, \varepsilon')} \Pi_{\varepsilon'} A_{\omega} \Pi_\varepsilon A_{\omega'} \Pi_{\varepsilon} \delta_{\varepsilon \varepsilon'}$$

is also off diagonal $\Pi_\varepsilon A_{\omega}^\dagger A_{\omega'} \Pi_\varepsilon = 0$, because each pair $(\varepsilon, \varepsilon')$ can only appear for one $\omega$. Thus $A_{\omega}^\dagger A_{\omega'}$ for $\omega \neq \omega'$ are also orthogonal to $\dot{H}_{LS}$. Hence the only possibility for $\dot{H}_{LS}$ to fall in the span of the noise operators in Eq. (67) is that

$$\dot{H}_{LS} \in \text{span} \left\{ 1, \gamma_\omega A_{\omega}^\dagger A_\omega \right\}$$

since $A_{\omega}^\dagger A_\omega$ are the only block-diagonal contributions.

In the context of our microscopic model where the Lamb shift term the form

$$\dot{H}_{LS} = \sum_\omega \dot{s}_\omega A_{\omega}^\dagger A_\omega,$$

Clearly, a sufficient for the condition (72) it is sufficient that all the rates $\gamma_\omega$ are nonzero whenever $\dot{s}_\omega$ is nonzero.

7 Upper-bound on the QFI

We now assume $\dot{H}_{LS} \in \text{span} \left\{ 1, \gamma_\omega A_{\omega}^\dagger A_\omega \right\}$ and derive an upper-bound on the QFI. Given the assumption we can write

$$\dot{H}_{LS} = h_1 1 + \sum_\omega h_\omega A_\omega^\dagger A_\omega,$$

where $h_\omega = 0$ for $\gamma_\omega = 0$ such that the ration $\frac{h_\omega}{\gamma_\omega}$ is well defined. Then $\| K^\dagger (\dot{K} + i h K) \| = O(d t^{3/2})$ is fulfilled by the choice $h = \left( h_0 dt \ \text{diag}[h_\omega/\gamma_\omega] \right)$. To set an upper-bound on QFI we have to compute $\| (\dot{K}^\dagger - i K h) (\dot{K} + i h K) \|$. To do so, we write to the leading orders

$$(K + i h K) = \begin{pmatrix} -dt \left( \sum_\omega 1/2 \gamma_\omega A_{\omega}^\dagger A_\omega + i \dot{H}_{LS} \right) & \cdots & \left( i h_0 dt 1 \right) \\ \cdots & \cdots & \cdots \\ \sqrt{dt} \frac{h_\omega}{\gamma_\omega} A_{\omega} & \cdots & \left( i \frac{h_\omega}{\gamma_\omega} \sqrt{dt} \gamma_\omega A_{\omega} \right) \end{pmatrix} + \begin{pmatrix} \cdots & \cdots & \cdots \\ \cdots & \cdots & \cdots \\ \sqrt{dt} \frac{h_\omega}{2 \gamma_\omega} A_{\omega} & \cdots & \left( \sqrt{dt} \frac{h_\omega}{2 \gamma_\omega} A_{\omega} \right) \end{pmatrix}.$$
Which makes it easy to compute

\[
(K^\dagger - iKh)(K + ihK) = dt \sum_{\omega} \left| \frac{\dot{\gamma}_\omega + 2i\dot{h}_\omega}{2\sqrt{\gamma}_\omega} \right|^2 A^\dagger_{w}A_{w} = \frac{dt}{4} \sum_{\omega} \frac{\dot{\gamma}_\omega^2 + 4\dot{h}_\omega^2}{\gamma_\omega} A^\dagger_{w}A_{w}.
\]  

(76)

Taking the norm gives

\[
\left\| (K^\dagger - iKh)(K + ihK) \right\| = \frac{dt}{4} \left\| \sum_{\omega} \frac{\dot{\gamma}_\omega^2 + 4\dot{h}_\omega^2}{\gamma_\omega} A^\dagger_{w}A_{w} \right\|.
\]

(77)

Using Eq. (11), we obtain a bound on the QFI

\[
\mathcal{F}_{\varepsilon_i|T} \leq \tau \left\| \sum_{\omega} \frac{\dot{\gamma}_\omega^2 + 4\dot{h}_\omega^2}{\gamma_\omega} A^\dagger_{w}A_{w} \right\|
\]

(78)

For \( H_{LS} = \sum_{\omega} \delta_\omega A^\dagger_{w}A_{w} \) suggests a particularly simple choice of the coefficients \( h_\omega = \delta_\omega \), leading to

\[
\mathcal{F}_{\varepsilon_i|T} \leq \tau \left\| \sum_{\omega} \frac{\dot{\gamma}_\omega^2 + 4\delta_\omega^2}{\gamma_\omega} A^\dagger_{w}A_{w} \right\|
\]

(79)

Finally, in the in absence of temperature dependent Lamb shift \( \dot{H}_{LS} = 0 \), or for measurement schemes that are insensitive to it, we get the bound

\[
\mathcal{F}_{\varepsilon_i|T} \leq \tau \left\| \sum_{\omega} \frac{\dot{\gamma}_\omega^2}{\gamma_\omega} A^\dagger_{w}A_{w} \right\|.
\]

(80)

### 8 App: Qubit probe example

#### 8.1 Derivation of the optimal bound

To find the value of the parameter \( x \) that gives the tightest bound in Eq. (41), we write it as

\[
\mathcal{F}_{\varepsilon_i|T} \leq \tau \min_x \max \left\{ f_-(x) = \frac{\dot{\gamma}_\omega^2/\gamma_w + 4(\delta_\omega + x)^2}{\gamma_w}, f_+(x) = \frac{\dot{\gamma}_\omega^2/\gamma_w + 4(\delta_\omega - x)^2}{\gamma_w} \right\}.
\]

(81)

The two function \( f_\pm(x) \) are "upwards" parabolas centered at \( x = \pm \delta_\omega \), with the minimal values \( f_-(\delta_w) = \frac{\dot{\gamma}_\omega^2}{\gamma_w} \geq f_+(\delta_\omega) = \frac{\dot{\gamma}_\omega^2}{\gamma_w} \). To solve the minmax we distinguish two different regimes.

On the one hand (i), if the minimal value of \( f_-(x) \), attained at \( x = -\delta_w \), is larger than \( f_+(\delta_w) \) the best upper bound is clearly given by \( f_-(\delta_w) \).

On the other (ii) if \( f_-(\delta_w) < f_+(\delta_w) \), the best bound is attained when the two functions are equal \( f_-(x) = f_+(x) \) for \( x \in [-\delta_w, \delta_w] \). Taking \( \delta_w > 0 \) without loss of generality (otherwise one can flip its sign), such an \( x \) is straightforward to find

\[
x_*(w) = \frac{-4\delta_\omega(\gamma_w + \gamma_w) - \sqrt{64\delta_\omega^4\gamma_w\gamma_w - \dot{\gamma}_\omega^2(\gamma_w - \gamma_w)^2}}{\gamma_w - \gamma_w}.
\]

(82)

And implies the optimal upper-bound \( f_+(x_*(w)) = f_-(x_*(w)) = \frac{16\delta_w^2}{\gamma_w - \gamma_w}( -x_*(w)) \). In summary, combining (i) and (ii) we find the form of the tightest upper-bound

\[
\mathcal{F}_{\varepsilon_i|T} \leq \tau \left\{ \begin{array}{c}
\frac{16\delta_w^2}{\gamma_w - \gamma_w}( -x_*(w)) \\
\frac{\dot{\gamma}_\omega^2}{\gamma_w}\gamma_w \\
\frac{\dot{\gamma}_\omega^2}{\gamma_w}
\end{array} \right. \begin{array}{c}
< \frac{\dot{\gamma}_\omega^2 + 16\delta_w^2}{\gamma_w} \\
\geq \frac{\dot{\gamma}_\omega^2 + 16\delta_w^2}{\gamma_w}
\end{array}
\]

(83)

with the expression of \( x_*(w) \) given in Eq. (82).
8.2 Solving the master equation

In this section we solve the master equation of the qubit probe of Sec. 4.1 in the low temperature regime $T \ll w$. We will assume a pure initial state $|\Psi_0\rangle$. The master equation takes the form

$$\frac{d}{dt} \rho = -i \left[ \frac{1}{2} \hat{w} \sigma_z, \rho \right] + \gamma_w \left( \sigma_- \rho \sigma_+ - \frac{1}{2} \{ |1\rangle \langle 1 |, \rho \} \right),$$

(84)

with $\hat{w} = w + 2 \Delta_T + \Delta$. One notes that in this equation the unitary dynamics commute with the dissipation $[\sigma_z, D(\rho)] = D([\sigma_z, \rho])$. Hence, we can decompose the evolution as "pure" dissipation $\frac{d}{dt} \rho = \gamma_w D(\rho)$ acting on the state for time $t$ followed by unitary evolution $\frac{d}{dt} \rho = -\frac{1}{2} \hat{w} [\sigma_z, \rho]$ of the same duration. The unitary dynamics results in the unitary operator

$$U_t = \exp\left(-\frac{1}{2} t \hat{w} \sigma_z \right).$$

(85)

The stochastic dynamics projects the system on the ground state $|0\rangle \langle 0 | \propto \sigma_-(\rho(t)) \sigma_+ \rho(t)$. At each time it gives result to two possible branches, either the jump $\sigma_-$ has already occurred and the system remains in $\rho_j(t) = p_j(t) |0\rangle \langle 0 |$, or it has not yet occurred $\rho_{nj}(t)$. In the no-jump branch the dynamics is given by $\frac{d}{dt} \rho_{nj}(t) = -\gamma_w \{ |1\rangle \langle 1 |, \rho_{nj}(t) \}$, and is straightforward to solve

$$\rho_{nj}(t) = |\Psi_{nj}(t)\rangle \langle \Psi_{nj}(t) |, \quad |\Psi_{nj}(t)\rangle = e^{-\frac{1}{2} \gamma_w |1\rangle \langle 1 |} |\Psi_0\rangle.$$  

(86)

The probability that a jump has occurred before $t$ is thus

$$p_j(t) = 1 - \text{tr} \rho_{nj}(t) = 1 - \text{tr} e^{-\gamma_w |1\rangle \langle 1 |} \rho_0.$$  

(87)

Plugging in the coherent evolution given by $U_t$, the state at time $t$ is

$$\rho_t = U_t \rho_D(t) U_t^\dagger, \quad \rho_D(t) = p_j(t) |0\rangle \langle 0 | + \rho_{nj}(t).$$  

(88)

We compute the QFI of the state as $F_{\rho_t} = \text{tr} \dot{\rho}_t L$ where $L$ is the symmetric logarithmic derivative $\frac{1}{2} \{ \rho_t, L \}$. In the frame rotating with $U_t$ one has

$$\dot{\rho}_t = \rho_D(t), \quad \dot{\rho}_t = -\frac{i}{2} t \hat{w} [\sigma_z, \rho_D(t)],$$  

(89)

where $\hat{w} = 2 \Delta_T = 2 s_w$.  

8.3 Ramsey scheme

Let us now consider a measurement scheme where the probe is prepared is subject to free evolution in Eq. (84) for time $t$, after which it is measured and reinitialised. Without loss of generality we assume that the probe is prepare in a state in the x-z plane of the Bloch sphere $|\Psi_0\rangle = \sqrt{1 - a} |0\rangle + \sqrt{a} |1\rangle$, such that

$$\rho_0 = \begin{pmatrix} 1 - a & \sqrt{a - a^2} \\ \sqrt{a - a^2} & a \end{pmatrix} = (\sqrt{1 - a} |0\rangle + \sqrt{a} |1\rangle)(\sqrt{1 - a} |0\rangle + \sqrt{a} |1\rangle)$$  

(90)

with $a \in [0, 1]$. From Eqs. (88-89) we get

$$\rho_t = \begin{pmatrix} 1 - e^{-t \gamma_w a} & e^{-\frac{\gamma_w}{2} t} \sqrt{a - a^2} \\ e^{-\frac{\gamma_w}{2} t} \sqrt{a - a^2} & e^{-\gamma_w t} a \end{pmatrix}, \quad \dot{\rho}_t = 2 s_w t e^{-\frac{\gamma_w}{2} t} \sqrt{a - a^2} \sigma_y.$$  

(91)

With these expressions one verifies that the SLD is given by $L = s_w t e^{-\frac{\gamma_w}{2} t} \sqrt{a - a^2} \sigma_x$ and the QFI $F_{\rho_t} = \text{tr} \dot{\rho}_t L = 16 s_w^2 t^2 e^{-\gamma_w t} (a - a^2)$. The QFI is maximized to

$$F_{\rho_t} = 4 s_w^2 t^2 e^{-\gamma_w t}.$$  

(92)
for $\rho_0 = | + \rangle \langle + |$, i.e. $a = \frac{1}{2}$. It remains to determin the optimal duration between the preparation and the measurement $t_{opt}$, i.e. which maximizes the QFI rate

$$t_{opt} = \arg\max_t \frac{F_{\rho_t}}{t} = \frac{1}{\gamma_w}. \quad (93)$$

The best strategy is then to measure the state of the probe after $t_{opt}$, and reinitialize it in the state $| + \rangle$ after the measurement. For a long enough running time given the QFI becomes

$$F_{\mathcal{E}_s} = \frac{F_{\rho_{opt}}}{t_{opt}} = \frac{4 \dot{s}_w^2}{\gamma_w} \approx 1.5 \frac{\dot{s}_w^2}{\gamma_w} \quad (94)$$

In comparison, the upper-bound of Eq. (42) reads $F_{\mathcal{E}_s} \leq 16 \frac{\dot{s}_w^2}{\gamma_w}$ in the limit $\dot{s}_w \gg \gamma_w$, and is larger by an order of magnitude.

### 8.4 Error detection scheme

Next, let us consider the case where the evolution is subject to quantum control. In particular, we introduce an auxiliary and prepare the initial state

$$|\Psi_0 \rangle = \sqrt{1 - a} |00\rangle + \sqrt{a} |11\rangle. \quad (95)$$

First, consider the case where no control operations are performed on the state between the preparation and the measurement. The Lindbladian in Eq. (84) acts trivially on the auxilliary qubit, and the evolution of the probe and ancilla system is thus almost identical with the case described above. The only difference is that the jump operator $\sigma_-$ (acting on the probe only) leaves the system in the state

$$(\sigma_- \otimes \mathbb{1}) \rho(t) (\sigma_+ \otimes \mathbb{1}) \propto |0\rangle \langle 0| \otimes |1\rangle \langle 1|, \quad (96)$$

which has a different parity as compared to the initial state. While in the no-jump branch the parity of the initial state is preserved, i.e. in the jump branch the state evolves to

$$|\Psi'_{nj}(t)\rangle = \sqrt{1 - a} |00\rangle + \sqrt{ae^{-\frac{\gamma_w}{2}\Delta t}} |11\rangle, \quad (97)$$

And the final state is now a direct sum

$$\rho_D(t) = |\Psi'_{nj}(t)\rangle \langle \Psi'_{nj}(t)| \oplus p_j(t) |01\rangle \langle 01| \quad (98)$$

rather then a mixture. Futhremore, note that the coherent evolution $U_t = \exp (-\frac{1}{2} t \hat{\omega} \sigma_z \otimes \mathbb{1})$, preserves the parity. Hence, by measuring the parity $\{\Pi_Y, \Pi_X\}$, with

$$\Pi_Y = |00\rangle \langle 00| + |11\rangle \langle 11|$$

$$\Pi_X = |01\rangle \langle 01| + |10\rangle \langle 10|, \quad (99)$$

of the two-qubit state at any time, one can learn if a jump has occurred without disturbing the coherent part of the evolution. From

$$\rho_t = |\Psi'_{nj}(t)\rangle \langle \Psi'_{nj}(t)| \oplus p_j(t) |01\rangle \langle 01| \quad \rho_t = 2\dot{s}_w t e^{-\frac{\gamma_w}{2} t} \sqrt{a - a^2 i} |11\rangle \langle 00| - |00\rangle \langle 11| \quad (100)$$

we compute

$$F_{\rho_t} = 16 \frac{(1 - a) a t^2 \dot{s}_w^2}{(1 - a)e^{\gamma_w t} + a}. \quad (101)$$

To find the optimal initial state $a$ and sensing time $t$, we again optimize the QFI rate

$$F_{\mathcal{E}_s} = \tau \max_{a,t} F_{\rho_t} \approx 2.47 \frac{\dot{s}_w^2}{\gamma_w}, \quad (102)$$

and obtained for an initial state with $a \approx 0.68$. We see that in improves over the previous strategy.