Knotted optical vortices in exact solutions to Maxwell’s equations

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We construct a family of exact solutions to Maxwell’s equations in which the points of zero intensity form knotted lines topologically equivalent to a given but arbitrary algebraic link. These lines of zero intensity, more commonly referred to as optical vortices, and their topology are preserved as time evolves and the fields have finite energy. To derive explicit expressions for these new electromagnetic fields that satisfy the nullness property, we make use of the Bateman variables for the Hopf field as well as complex polynomials in two variables whose zero sets give rise to algebraic links. The class of algebraic links includes not only all torus knots and links thereof, but also more intricate cable knots. While the unknot has been considered before, the solutions presented here show that more general knotted structures can also arise as optical vortices in exact solutions to Maxwell’s equations.

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The discovery of the electromagnetic Hopf field by Ranada [1–4] initiated further studies of knotted electromagnetic field lines [5–11]. This led to the formulation of a family of knotted electromagnetic fields encoding torus knots by Kedia et al. [8]. These solutions were shown to be equivalent to elementary states arising in twistor theory [7], which allowed for a generalization of the knotted solutions to other massless field equations, in particular the linearized Einstein equations [12]. More recently Kedia et al. [13] have proposed a method capable of constructing divergence-free vector fields with knotted field lines more general than torus knots. However, a knotted structure can also be encoded in optical vortices, the lines of zero intensity of an electromagnetic field. These vortices and their topology have up to now primarily been studied in paraxial fields [14–17]. For example, Dennis et al. [18] employed the paraxial wave approximation to derive and produce knotted optical vortices. In contrast, Biaynlisnki–Burila used the Bateman construction [19] to introduce optical vortices topologically equivalent to lines and circles in exact solutions to Maxwell’s equations [20]. Here we extend the class of known optical vortices in exact solutions to Maxwell’s equations to include all algebraic links [21–24], providing the first examples of topologically nontrivial vortices in this context.

Algebraic links. We start with an exposition of those aspects of knot theory necessary to describe the topology of the family of optical vortices constructed in this paper [21–24]. Let \( h \) be a polynomial in two complex variables with vanishing constant term. Then the zero set of this polynomial in \( \mathbb{C}^2 \) intersected with the three-sphere of radius \( \epsilon > 0 \), denoted by \( S^3_\epsilon \), is diffeomorphic to a disjoint union of circles provided that \( \epsilon \) is sufficiently small. This intersection is called an algebraic link, and the topology of this link is essentially independent of \( \epsilon \). Thus, in particular, an algebraic link is a one-dimensional submanifold of \( S^3_\epsilon \) and can therefore be regarded as a one-dimensional submanifold of \( \mathbb{R}^3 \) via stereographic projection. Every component of such an algebraic link corresponds uniquely to an irreducible factor of the polynomial by which it is induced. Therefore, if the polynomial inducing the algebraic link is irreducible, the corresponding link has one component and is called an algebraic knot.

There exists a method due to Newton to solve \( h(v, w) = 0 \) for \( w \) in terms of \( v \) for any irreducible polynomial \( h \) that vanishes at the origin. This method gives an explicit algorithm to obtain successive approximations to the exact solution of \( h(v, w) = 0 \) for \( w \) in terms of \( v \) of the form

\[
\begin{align*}
  w_0 &= a_0 v^{q_0/p_0}, \\
  w_1 &= v^{q_1/p_1}(a_0 + a_1 v^{q_1/p_1}), \\
  &\vdots
\end{align*}
\]

for some complex numbers \( a_0, a_1, \ldots \). The pairs of coprime numbers \( (p, q) \) determining the exponents in the expansion are called the Newton pairs, of which a finite number determine the topology of the knot. Therefore, some approximation \( w_k \) containing all the information relevant to the topology of the knot can be obtained in a finite number of steps. For example, consider the general case for one Newton pair \( (p, q) \) with corresponding polynomial

\[
  h(v, w) = \sqrt{v} v^p - \sqrt{w} w^p.
\]

In this case we can take \( \epsilon \) equal to one and we obtain a parametrization \( (v, w) \) for the knot by plugging \( v = e^{i\theta p}/\sqrt{2} \) into \( w = \sqrt{v^q/p} v^q/p \). This curve lies on the standard torus and closes after going \( p \) and \( q \) times around the toroidal and poloidal direction, respectively. Such a knot is called a \((p, q)\) torus knot of which an example is illustrated in Fig. 1(a).

However, care should be taken when trying to obtain parametrizations of knots associated with more general Newton pairs in this way. This is due to the fact that plugging some \( v \) of fixed absolute value into an expression for \( w \) consisting of multiple terms will in general result in \( (v, w) \) not being a subset of \( S^3_\epsilon \). To resolve this issue, it is common to deform \( S^3_\epsilon \) into a union of two solid tori:

\[
  \{(v, w) \in \mathbb{C}^2 : |v| = \epsilon, |w| \leq \delta \text{ or } |v| \leq \epsilon, |w| = \delta \}.
\]

This deformation can be performed in such a way that the zero set of the polynomial \( h \) corresponding to the knot under consideration intersects this set in only one of the two tori. Furthermore, it can be shown that this intersection is
Algebraic links in electromagnetism. Now we go on to show how algebraic links can be implemented as optical vortices in electromagnetic fields. To do so, we describe an electromagnetic field with its Riemann–Silberstein vector
\[ \mathbf{F} = \mathbf{E} + i \mathbf{B}. \] (4)
Provided that an electromagnetic field is null, i.e., satisfies \( \mathbf{F} \cdot \mathbf{F} = 0 \) which means that the fundamental invariants of the electromagnetic field \( \mathbf{E} \cdot \mathbf{B} = 0 \) and \( |\mathbf{E}|^2 - |\mathbf{B}|^2 \) are zero, there exist smooth complex-valued functions \( \alpha, \beta \) on Minkowski space satisfying
\[ \nabla \alpha \times \nabla \beta = \pm i(\partial_t \alpha \nabla \beta - \partial_t \beta \nabla \alpha), \] (5)
for which the field can be written as \( \mathbf{F} = \nabla \alpha \times \nabla \beta \), as shown by Hogan [25]. Given such functions \( \alpha \) and \( \beta \), which we will refer to as Bateman variables, as well as arbitrary smooth maps \( f \) and \( g \) from \( \mathbb{C}^2 \) to \( \mathbb{C} \), it holds that \( f(\alpha, \beta) \) and \( g(\alpha, \beta) \) are also Bateman variables [19]. The Bateman variables for the Hopf field seem to have originated from work by Robinson and Trautman [26] and Bialinicki–Birula [20], which was expanded upon by Besieris and Sharaawi [6], Van Enk [9], and Kedia et al. [8]. Here we will use a specific choice of Bateman variables for the Hopf field that is given in Ref. [8]:
\[ \alpha = \frac{r^2 - t^2 - 1 + 2iz}{r^2 - (t-i)^2} \quad \text{and} \quad \beta = \frac{2(x-iy)}{r^2 - (t-i)^2}. \] (6)
How the Hopf field and its Bateman variables can be obtained from a solution of the scalar wave equation is described in the Appendix. By multiplying \( \alpha \) and \( \beta \) with \( \epsilon / \sqrt{2} \) for any \( \epsilon > 0 \), we obtain Bateman variables \( \alpha_\epsilon \) and \( \beta_\epsilon \) for a scaled version of the Hopf field \( \mathbf{F}_H \). Then the map \((\alpha_\epsilon, \beta_\epsilon)\), restricted to a fixed time, can be interpreted as a map from \( \mathbb{R}^3 \) to \( S^3_\epsilon \) because \( |\alpha_\epsilon|^2 + |\beta_\epsilon|^2 = \epsilon^2 \) holds at any fixed time. To obtain an electromagnetic field with an optical vortex that is topologically equivalent to a given algebraic link \( L \), we take a corresponding polynomial \( h \) and \( \epsilon > 0 \) and choose
\[ f(v, w) = \int h(v, w)dv \quad \text{and} \quad g(v, w) = w. \] (7)
Then, as we now show, the null field given by
\[ \mathbf{F}_L = \nabla f(\alpha_\epsilon, \beta_\epsilon) \times \nabla g(\alpha_\epsilon, \beta_\epsilon) = h(\alpha_\epsilon, \beta_\epsilon) \nabla \alpha_\epsilon \times \nabla \beta_\epsilon \] (8)
has optical vortices topologically equivalent to \( L \) at every time. This construction is possible by virtue of the fact that the intensity of the Hopf field is never zero and the fact that Bateman variables of the Hopf field can be written as done in Eq. (6), which at \( t = 0 \) describe the inverse stereographic projection.

First, we note that since the intensity of the Hopf field is nowhere zero, the optical vortices of \( \mathbf{F}_L \) are determined completely by the zero set of \( h(\alpha_\epsilon, \beta_\epsilon) \). Second, the fact that, restricted to \( t = 0 \), the map \((\alpha_\epsilon, \beta_\epsilon)\) describes the inverse stereographic projection implies that the optical vortices of \( \mathbf{F}_L \) at \( t = 0 \) are topologically equivalent to the zero set of \( h \) in \( S^3_\epsilon \), provided that the latter does not contain (1,0). If it does, we can choose another polynomial giving rise to the same link for which this is not the case. Third, it turns out that \((\alpha_\epsilon, \beta_\epsilon)\) restricted to any fixed time \( t_0 \) has rank three, which means that
FIG. 2. The Hopf link as an optical vortex. These plots are created by taking the intersection of the surfaces where the real and imaginary parts of \( h_1 \) are zero at (a) \( t = 0 \) and (b) \( t = 3 \). The aforementioned surfaces are included for clarity and are denoted by the transparent orange surfaces.

It is a local diffeomorphism from \( \{ t_\ast \} \times \mathbb{R}^3 \) to \( S^3 \). Thus, the zero set of \( h(\alpha_\epsilon, \beta_\epsilon) \) at any fixed time is diffeomorphic to a disjoint union of circles and hence a link. Finally, it should be noted that the restriction of \( h \) to \( S^3 \) has rank two which, together with the fact that \( (\alpha_\epsilon, \beta_\epsilon) \) restricted to a fixed time \( t_\ast \) is a local diffeomorphism, implies that the zero set of \( h(\alpha_\epsilon, \beta_\epsilon) \) in Minkowski space is a two-dimensional manifold. This implies that the zero set of \( h(\alpha_\epsilon, \beta_\epsilon) \) at any fixed time is topologically equivalent to the zero set of \( h(\alpha_\epsilon, \beta_\epsilon) \) at \( t = 0 \), which, in turn, is equivalent to \( L \) as mentioned above.

We note that the fields under consideration here fall into a class for which it is known that the structure is transported by a rescaled nowhere zero version of the Poynting vector field \([27,28]\). This observation leads to the same conclusion as our proof above.

We will now examine some general properties of the class of electromagnetic fields that we have constructed. First, we note that the energy density of an electromagnetic field \( \mathbf{F}_L \) with corresponding polynomial \( h \) and \( \epsilon \) is given by

\[
\mathbf{F}_L \cdot \tilde{\mathbf{F}}_L = |h(\alpha_\epsilon, \beta_\epsilon)|^2 \mathbf{F}_H \cdot \tilde{\mathbf{F}}_H,
\]

where \( \tilde{\mathbf{F}} \) denotes the complex conjugate of \( \mathbf{F} \). Since the energy of the Hopf field is finite and \( |h(\alpha_\epsilon, \beta_\epsilon)|^2 \) is bounded from above, we can conclude that the energy of \( \mathbf{F}_L \) is finite as well.

Second, the Poynting vector is given by

\[
\mathbf{S}_L = \text{Re}[\mathbf{F}_L] \times \text{Im}[\mathbf{F}_L]
= |h(\alpha_\epsilon, \beta_\epsilon)|^2 \text{Re}[\mathbf{F}_H] \times \text{Im}[\mathbf{F}_H].
\]

Thus, away from the zero set of the Poynting vector field which is topologically equivalent to the algebraic link \( L \), the integral curves of the Poynting vector have the structure of the Hopf fibration. Also, since the momentum of the Hopf field is finite, the same holds for the momentum of \( \mathbf{F}_L \).

The vector potentials for the electric and magnetic fields can be described by a complex vector

\[
\mathbf{V} = C + iA,
\]

where \( C \) and \( A \) are given by the real and imaginary parts of \( f(\alpha, \beta)\mathbf{V} \), respectively. Since the fields under consideration
are null, the electric and magnetic helicities, which can be computed from the vector potentials, are conserved quantities [11].

Now we will illustrate some of the general properties for the Hopf link and a cable knot. The polynomial corresponding to the Hopf link is given by

$$h_1(v, w) = v^2 + w^2.$$  \hspace{1cm} (12)

The polynomial corresponding to a cable knot with Newton pairs (2,3) and (3,2) is given by

$$h_2(v, w) = w^6 - 3w^4v^3 + 3w^2v^6 - 6w^2v^8 - v^9 - 2v^{11} - v^{13},$$  \hspace{1cm} (13)

Then $F_1 = h_1(\alpha, \beta)\nabla \alpha \times \nabla \beta$ and $F_2 = h_2(\alpha, \beta)\nabla \alpha \times \nabla \beta$ are electromagnetic fields with optical vortices that are at any time topologically equivalent to the Hopf link and a cable knot with Newton pairs (2,3) and (3,2), respectively. The evolution of the vortex in $F_1$ is illustrated in Fig. 2. Furthermore, the energy densities at $t = 0$ of both $F_1$ and $F_2$ are illustrated in Fig. 3.

Summary. We have derived analytic expressions for a new family of finite-energy null electromagnetic fields with optical vortices that are topologically equivalent to algebraic links. Furthermore we provide a rigorous explanation for the emergence of these new topologically nontrivial structures. Since our solutions are based on the Bateman construction, it follows from a recent result by Goulart [29] that they are also exact solutions of nonlinear electrodynamics. We expect that the implementation of knot theory to generate topologically nontrivial structures in electromagnetism introduced here will lead to generalizations in linearized gravity [12,30], Bose–Einstein condensate configurations [31], and plasma configurations [32,33].

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APPENDIX

The Bateman variables for the electromagnetic Hopf field have been found and presented in the literature without an explicit derivation. Here we show how the Bateman variables emerge naturally when the Hopf field is derived from a superpotential.

Throughout this Appendix, we describe electromagnetic fields with differential two-forms on Minkowski space. In this formalism [23], Maxwell’s equations in free space are given by

$$dF = 0 \text{ and } d \star F = 0,$$  \hspace{1cm} (A1)

where $\star$ is the Hodge star operator induced by the metric. The Hodge star operator on Minkowski space satisfies $\star^2 F = -F$ for any two-form $F$. Therefore, the eigenvalues of $\star$ are $\pm i$ which leads us to choose $F$ to be complex valued. A real solution to Maxwell’s equations can always be obtained from the complex-valued form due to linearity of Maxwell’s equations. If $\star F = iF$ holds, we call the form self-dual and if $\star F = -iF$ holds, we call the form anti-self-dual. A complex-valued two-form is a solution to Maxwell’s equations if it is (anti-)self-dual and closed. Given smooth maps $\alpha, \beta : M \rightarrow C$, the two-form $F = d\alpha \wedge d\beta$ is closed by construction but only (anti-)self-dual if

$$\nabla \alpha \times \nabla \beta = \pm i(\partial_i \alpha \nabla \beta - \partial_i \beta \nabla \alpha).$$  \hspace{1cm} (A2)

Provided that $\alpha$ and $\beta$ satisfy this equation, one can easily show that $F = d(\alpha \beta) \wedge d(\gamma \delta) = \alpha \beta \gamma \delta$ is also a solution to Maxwell’s equations for arbitrary smooth maps $f, g : C^2 \rightarrow C$. This shows how the Bateman construction arises naturally from the formalism employed here.

Now we show how a solution to Maxwell’s equations can be constructed from a superpotential, i.e., a solution to the scalar wave equation $\Delta W = (\partial_\alpha \delta \partial_\beta) W = 0$. This construction, for which we base ourselves on Chapter 9 of Synge’s book on special relativity [34], can be formulated in the formalism of differential forms as follows: Let $W$ be a solution of the scalar wave equation, and let $K$ be a constant two-form on Minkowski space, then

$$A = \star(dW \wedge K)$$  \hspace{1cm} (A3)

is a potential. To see this, note that this one-form satisfies the Lorentz gauge condition $\partial A = 0$ which implies that it is a potential since its components satisfy the wave equation. In the same chapter, Synge notes that

$$W = [a^2 - (t - i)^2]^{-1}$$  \hspace{1cm} (A4)

is a solution of the wave equation without singularities. If we take $K$ to be given by

$$K = -dz \wedge dx - idy \wedge dz - dx \wedge dt + idy \wedge dt,$$  \hspace{1cm} (A5)

the construction described above gives a potential given by

$$A = \frac{-2(y + ix)}{[x^2 + y^2 + z^2 - (t - i)^2]^2} dz$$
$$+ \frac{2(y + ix)}{[x^2 + y^2 + z^2 - (t - i)^2]^2} dt$$
$$- \frac{2it + 2iz - 2}{[x^2 + y^2 + z^2 - (t - i)^2]^2} dx$$
$$- \frac{-2t + 2z + 2i}{[x^2 + y^2 + z^2 - (t - i)^2]^2} dy.$$  \hspace{1cm} (A6)

The field $F = dA$ corresponding to this potential is then a self-dual two-form for which the corresponding electric and magnetic fields are that of the Hopf field. Note that for an electromagnetic field of the form $F = d\alpha \wedge d\beta$, potentials are given by $A = \alpha d\beta$ and $A' = -\beta d\alpha$. Also, in Eq. (A6) there are four functions that serve as components, but two of them are related by a minus sign and the other two by a factor $i$. However, these two functions cannot be Bateman variables since the denominator of the product of one of these functions with the derivative of the other will be of higher order than the denominator of $A$. Therefore it is natural to consider the same functions without the square in the denominator. These maps are
indeed Bateman variables for the Hopf field and are given by

\[
\tilde{\alpha}(t,x,y,z) = \frac{2i - 2t + 2z}{r^2 - (t - i)^2}, \tag{A7}
\]

\[
\tilde{\beta}(t,x,y,z) = \frac{2(i(x + y))}{r^2 - (t - i)^2}. \tag{A8}
\]

To obtain the Bateman variables used in the main article from the Bateman variables derived here, one has to take a factor \(i\) from \(\tilde{\beta}\) to \(\tilde{\alpha}\) and add one to \(i\tilde{\alpha}\). This explicit form is necessary in the main text as it allows us to interpret \((\alpha, \beta)\) as points on the three-sphere.

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