QUADRATIC TRANSPORTATION INEQUALITIES FOR SDES WITH MEASURABLE DRIFT

KHALED BAHLALI, SOUFIANE MOUCHTABIH, AND LUDOVIC TANGPI

Abstract. Let \( X \) be the solution of the multidimensional stochastic differential equation
\[
dX(t) = b(t, X(t)) \, dt + \sigma(t, X(t)) \, dW(t)
\]
where \( W \) is a standard Brownian motion. In our main result we show that when \( b \) is measurable
and \( \sigma \) is in an appropriate Sobolev space, the law of \( X \) satisfies a uniform quadratic transportation
inequality.

1. Introduction and main results

Throughout this work, we fix \( d \in \mathbb{N} \) and \( T \) a strictly positive real number. Let \((\Omega, \mathcal{F}, P)\)
be the canonical space of a \( d \)-dimensional Brownian motion denoted by \( W \) and equipped with the \( P\)-
completion of the raw filtration \( \sigma(W_s, s \leq t) \) generated by \( W \). That is \( \Omega = C([0,T], \mathbb{R}^d) \)
edowed with the supremum norm, and \( W_t(\omega) = \omega(t) \). Further denote by \( \mathcal{P}(\Omega) \) the set of all Borel probability
measures on \( \Omega \). For \( \mu, \nu \in \mathcal{P}(\Omega) \) define the (second order) Wasserstein distance and the Kullback-
Leibler divergence respectively by
\[
W_2(\mu,\nu) := \left( \inf_{\pi} \int_{\Omega \times \Omega} ||\omega - \eta||^2 \pi(d\omega,d\eta) \right)^{1/2} \quad \text{and} \quad H(\nu|\mu) := \int \frac{d\nu}{d\mu} \log \frac{d\nu}{d\mu} \, d\mu
\]
where the infimum is taken over all, probability measures \( \pi \) on the product with first marginal \( \mu \)
and second marginal \( \nu \), and we used the convention \( \frac{d\nu}{d\mu} = +\infty \) if \( \nu \) is not absolutely continuous
w.r.t. \( \mu \). Given a constant \( C \), a probability measure \( \mu \) is said to satisfy Talagrand’s \( T_2(C) \) inequality
(or quadratic transportation inequality) if
\[
W_2(\mu,\nu) \leq \sqrt{CH(\nu|\mu)} \quad \text{for all} \quad \nu \in \mathcal{P}(\Omega).
\]
This inequality was popularized in probability theory by the works of Talagrand [25] and Marton [18]
on the concentration of measure phenomenon. It has since found numerous applications, for instance
to isoperimetric problems, to randomized algorithms [9], or to quantitative finance [26, 15] and to
various problems of probability in high dimensions [7, 19, 16]. We refer the reader e.g. to Ledoux
[17] for an overview, notably for the connection to the concentration of measures. Transportation
inequalities are also related to various other functional inequalities as Poincaré inequality, log-Sobolev
inequality, inf-convolution and hypercontractivity, see [4], [20].

Our objective is to investigate transportation inequalities for stochastic differential equations of the form
\[
X(t) = x + \int_0^t b(s, X(s)) \, ds + \int_0^t \sigma(s, X(s)) \, dW(s) \quad \text{for} \quad t \in [0,T], \ x \in \mathbb{R}^d.
\]
under minimal regularity assumptions on the coefficients \( b : [0,T] \times \mathbb{R}^d \to \mathbb{R}^d \) and \( \sigma : [0,T] \times \mathbb{R}^d \to
\mathbb{R}^{d \times d} \). To state our main result, let us recall the following functional spaces. For \( p \geq 1 \) denote by
\( L^p_{\text{loc}}([0,T]) := L^p_{\text{loc}}([0,T] \times \mathbb{R}^d) \) the (Lebesgue) space of classes of locally integrable functions and for

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every \( m_1, m_2 \in \mathbb{N} \), let \( W^{m_1,m_2}_p([0,T]) := W^{m_1,m_2}_p([0,T] \times \mathbb{R}^d) \) be the usual Sobolev space of weakly differentiable functions \( f : [0,T] \times \mathbb{R}^d \to \mathbb{R} \) such that
\[
\|f\|_{W^{m_1,m_2}_p} := \sum_{|\alpha| \leq m_1} \|\partial_\alpha f\|_{L^p} + \sum_{|\alpha| \leq m_2} \|\partial_\alpha^p f\|_{L^p} < \infty
\]
where \( \alpha \) is a multiindex. Denote by \( W^{m_1,m_2}_{p,loc}([0,T]) \) the space of weakly differentiable functions \( f : [0,T] \times \mathbb{R}^d \to \mathbb{R} \) such that
\[
\|f\|_{L^p_{loc}} + \sum_{|\alpha| \leq m_1} \|\partial_\alpha f\|_{L^p_{loc}} + \sum_{|\alpha| \leq m_2} \|\partial_\alpha^p f\|_{L^p_{loc}} < \infty.
\]
Further let \( L^q_p([0,T]) := L^q_p([0,T], L^p(\mathbb{R}^d)) \) be the space of (classes of) measurable functions \( f : [0,T] \times \mathbb{R}^d \to \mathbb{R} \) such that
\[
\|f\|_{L^q_p} := \left( \int_0^T \left( \int_{\mathbb{R}^d} |f(s,x)|^p \, dx \right)^{q/p} \, ds \right)^{1/q} < \infty.
\]

The aim of this note is to prove the following:

**Theorem 1.** Assume that one of the following sets of assumptions is satisfied:

(A) \( \sigma, b \in L^{\infty}([0,T] \times \mathbb{R}^d) \), the function \( \sigma \) is continuous in \( (t,x) \) and belongs to \( W^{0,1}_{2(d+1),loc}([0,T]) \), there is \( \lambda > 0 \) such that
\[
\xi^* \sigma(t,x) \xi \geq \lambda \|\xi\|^2
\]
for all \( (t,x,\xi) \in [0,T] \times \mathbb{R}^d \times \mathbb{R}^d \), where \( \ast \) denotes the transpose, and \( T \) is small enough.

(B) \( \sigma \in W^{0,1}_{2(d+1),loc}([0,T]) \cap L^{\infty}([0,T] \times \mathbb{R}^d), \sigma \) is uniformly continuous in \( x \) and there is \( \lambda > 0 \) such that \( \sigma \) satisfies \( (2) \). The function \( b \) satisfies \( b \in L^q_p([0,T]) \) for some \( p, q \) such that \( d/p + 2/q < 1 \), \( 2(d+1) \leq p \) and \( q > 2 \).

Then, Equation \( (1) \) admits a unique strong solution \( X \) with continuous paths and the law \( \mu_x \) of \( X \) satisfies \( T_2(C) \)
for some constant \( C \) depending on the data, namely \( \|b\|_{L^q_p} \), \( \|\sigma\|_{\infty}, T, x, d, p \) and \( q \).

Since \( b \) is only assumed to be measurable, this result gives transportation inequality for singular SDEs as \( dX(t) = \text{sgn}(X(t)) \, dt + dW(t) \), or for "regime switching" models as
\[
\frac{dX(t)}{dt} = \{b_1(t, X(t))1_A(X(t)) + b_2(t, X(t))1_{A^c}(X(t))\} \, dt + \sigma(t, X(t)) \, dW(t)
\]
with \( A \) a measurable subset of \( \mathbb{R}^d \). Other examples are discussed at the end of the article.

Regarding the related literature, Talagrand \( (25) \) proved a quadratic transportation inequality for the multidimensional Gaussian distribution with optimal constant \( C = 2 \). Using stochastic analysis techniques, notably Girsanov’s theorem, Talagrand’s work was then extended to Wiener measure on the path space by Feyel and Üstünel \( (11) \). The case of SDEs was first analyzed by Djellout et al. \( (8) \) using a technique based on Girsanov’s transform that we also employ here. Their results gave rise to an interesting literature, including the papers \( (21), (27) \) on SDEs driven by Brownian motion and \( (23), (24) \) on SDEs driven by abstract Gaussian noise. Note that all the aforementioned works on SDEs assume that the coefficients are Lipschitz-continuous or satisfy a dissipative condition.

The effort to extend results from \( (8) \) to diffusions with non-smooth coefficients was started by Bartl and Tangpi \( (3) \) where it is proved that \( T_2(C) \) holds for one-dimensional equations, if \( b \) is measurable in space and differentiable in time and \( \sigma \) Lipschitz continuous. The idea of \( (3) \) is based on a transformation that is tailor-made for the one-dimensional case. The present note deals with the multidimensional case and further weakens the regularity requirements imposed in \( (3) \). In this case we use Zvonkin’s transformation, a technique well-known in SDE theory) along with gradient estimates for singular, second order parabolic PDEs. Note that considering multidimensional equations is, for instance,
fundamental for applications to concentration and asymptotic results on interacting particle systems, see e.g. [3, Section 5] and the various examples we give in the final section.

The proof of Theorem 1 is given in the next section, and the final section presents some examples.

2. Transportation inequalities

2.1. Equation with Sobolev coefficients. The goal of this section is to prove a quadratic transportation inequality for SDE (1) when the coefficients belong to some Sobolev spaces. Along with gradient estimates for solutions of singular PDEs, this will be an essential building block for the proof of the main result.

Proposition 2. Let $\sigma \in W_{2(d+1),\text{loc}}^0([0, T]) \cap L^\infty([0, T] \times \mathbb{R}^d)$ and $b \in W_{(d+1),\text{loc}}^0([0, T]) \cap L^\infty([0, T] \times \mathbb{R}^d)$. Assume that there exists $\lambda > 0$ such that (2). Then, equation (1) admits a unique strong solution $X$, and the law $\mu_x$ of $X$ satisfies $T_2(C)$ with $C = \inf_{0 < \varepsilon < 1} 2 \exp \left( \frac{C_{\text{BDG}}^2 \varepsilon^2}{\varepsilon (1 - \varepsilon)} \right) \frac{1}{1 - \varepsilon} \| \sigma \|_{\infty}^2$ where $C_{\text{BDG}}$ is the universal constant appearing in the Burkholder-Davis-Gundy inequality.

The proof of this proposition follows a coupling argument introduced in [8]. The main challenge here being the lack of regularity of the coefficients $\sigma$ and $b$. We start by a Lemma whose proof can be found in Step 1 of the proof of [8, Theorem 5.6].

Lemma 3. Let $\nu \in P(\Omega)$ be such that $\nu \ll \mu_x$ and $H(\nu|\mu_x) < \infty$, and let $X$ be the solution of (1). Then, the probability measure $\nu$ given by $Q := \frac{d\nu}{d\mu_x}(X)P$ satisfies

$$H(\nu|\mu_x) = E_Q \left[ \frac{1}{2} \int_0^T |q(s)|^2 \, ds \right]$$

for some progressively measurable, square integrable process $q$ such that $\tilde{W} := W - \int_0^T q(s) \, ds$ is a $Q$-Brownian motion.

Proof of Proposition 2. That (1) admits a unique strong solution follows from e.g. [1, Theorem 2.1]. Let $\nu \in P(\Omega)$ be absolutely continuous with respect to $\mu$. We can assume without loss of generality that $H(\nu|\mu_x) < \infty$. Let $Q$ and $q$ be as in Lemma 3. Under the probability measure $Q$, the SDE (1) takes the form

$$dX(t) = \sigma(t, X(t))d\tilde{W}(t) + \{\sigma(t, X(t))q(t) + b(t, X(t))\} dt, \quad \text{with} \quad X(0) = x$$

and the law of $X$ under $Q$ is $\nu$. Furthermore, the SDE

$$dY(t) = \sigma(t, Y(t))d\tilde{W}(t) + b(t, Y(t)) \, dt, \quad \text{with} \quad Y(0) = x$$

admits a unique solution whose law under $Q$ is $\mu_x$. That is, $(X, Y)$ under $Q$ is a coupling of $(\nu, \mu_x)$. Thus,

$$\mathcal{W}_2^2(\nu, \mu_x) \leq E_Q \left[ \sup_{0 \leq t \leq T} |X(t) - Y(t)|^2 \right].$$
We now estimate the right hand side above. By Itô’s formula, we have

\[ |X(t) - Y(t)|^2 = \int_0^t 2(X(s) - Y(s))\sigma(s, X(s))q(s) + |\sigma(s, X(s)) - \sigma(s, Y(s))|^2 ds \]

\[ + \int_0^t 2(X(s) - Y(s))(b(s, X(s)) - b(s, Y(s))) ds \]

\[ + \int_0^t 2(X(s) - Y(s))(\sigma(s, X(s)) - \sigma(s, Y(s))) d\tilde{W}, \]

where we simply denote by \(ab\) the inner product between two vectors \(a\) and \(b\). The difficulty is to deal with the terms \(\sigma(s, X(s)) - \sigma(s, Y(s))\) and \(b(s, X(s)) - b(s, Y(s))\). To that end, we introduce the following random times: First consider the sequence of stopping times

\[ \tau^N := \inf\{t > 0 : |X(t)| > N \text{ or } |Y(t)| > N\} \land T. \]

It is clear that \(\tau^N \uparrow T\). For each \(\lambda\) in \([0, 1]\) and \(t\) in \([0, T]\), we put \(Z_t^\lambda := \lambda X(t) + (1 - \lambda)Y(t)\). For every \(N \geq 0\) and \(t \in [0, \infty)\), define

\[ A^N(t) := \int_0^{t \land \tau^N} \int_0^1 (|\partial_x \sigma(s, Z_s^\lambda)|^2 + |\partial_x b(s, Z_s^\lambda)|) d\lambda ds, \]

where the (weak) derivative acts on the spatial variable. The process \(k^N(t) := t + A^N(t)\) is continuous, strictly increasing and \(k^N(0) = 0\). Moreover, \(k^N\) maps \([0, \infty)\) onto itself. We denote by \(\gamma^N\) the unique inverse map of \(k^N\). Using \([\text{BDG}],\) Cauchy-Schwarz and Burkholder-Davis-Gundy inequalities, one can show that for each \(t \in [0, \infty)\) it holds that

\[ E_Q \left[ \sup_{s \in [0, \gamma^N \land \tau^N]} |X(s) - Y(s)|^2 \right] \leq E_Q \left[ \int_0^{\gamma^N \land \tau^N} |X(s) - Y(s)|^2 ds + \|\sigma\|^2_{\infty} \int_0^{\gamma^N \land \tau^N} |q(s)|^2 ds \right] \]

\[ + E_Q \left[ \int_0^{\gamma^N \land \tau^N} |\sigma(s, X(s)) - \sigma(s, Y(s))|^2 + 2(X(s) - Y(s))(b(s, X(s)) - b(s, Y(s))) ds \right] \]

\[ + 2C_{BDG} E_Q \left[ \left( \int_0^{\gamma^N \land \tau^N} |X(s) - Y(s)|^2 |\sigma(s, X(s)) - \sigma(s, Y(s))|^2 ds \right)^{1/2} \right] \]

(7) \[ := I_1 + I_2 + I_3, \]

for a (universal) constant \(C_{BDG} > 0\).

Let \(\varepsilon > 0\). By Young’s inequality, we have

\[ I_3 \leq \varepsilon E_Q \left[ \sup_{s \in [0, \gamma^N \land \tau^N]} |X(s) - Y(s)|^2 \right] + \frac{2C_{BDG}^2}{\varepsilon} I_2. \]

We shall estimate \(I_2\). We denote by \(K_N\) the ball \(\{x \in \mathbb{R}^d, |x| \leq N\}\). For \(K := [0, T] \times K_N\). Let \(b_n, \sigma_n \in C^\infty\) be such that,

\[ \|\sigma_n - \sigma\|_{W^{0,1}_{2(d+1)}(K)} \to 0 \quad \text{and} \quad \|b_n - b\|_{W^{0,1}_{d+1}(K)} \to 0. \]

Using Krylov’s estimate ([14, Theorem 2.2.4]), we get

\[ I_2 \leq C_{T,N,d} \|\sigma - \sigma_n\|_{L^{2(d+1)}(K)} + C_{T,N,d} \|b - b_n\|_{L^{d+1}(K)} \]

\[ + 2E_Q \left[ \int_0^{\gamma^N \land \tau^N} |X(s) - Y(s)|^2 \int_0^1 (|\partial_x \sigma_n(s, Z_s^\lambda)|^2 + |\partial_x b_n(s, Z_s^\lambda)|) d\lambda ds \right] \]

\[ + 2E_Q \left[ \int_0^{\gamma^N \land \tau^N} |X(s) - Y(s)|^2 \int_0^1 (|\partial_x \sigma_n(s, Z_s^\lambda)|^2 + |\partial_x b_n(s, Z_s^\lambda)|) d\lambda ds \right] \]

(8) \[ := I_4. \]
where $C_{T,N,d}$ is a positive constant which depends on $T, N$ and $d$. Taking the limit as $n$ goes to infinity in the last inequality and using the fact that $dA^N(s) \leq dk^N(s)$, we obtain

$$I_2 \leq 2E_Q \left[ \int_0^\gamma \left| X(s) - Y(s) \right|^2 dk^N(s) \right].$$

Therefore,

$$I_3 \leq \varepsilon E_Q \left[ \sup_{s \in [0, \gamma \wedge T_N]} \left| X(s) - Y(s) \right|^2 \right] + \frac{6C_B^2 + \varepsilon}{\varepsilon} E_Q \left[ \int_0^\gamma \left| X(s) - Y(s) \right|^2 dk^N(s) \right].$$

Coming back to (7), since $k^N(t) := t + A^N(t)$, we have

$$E_Q \left[ \sup_{s \in [0, \gamma \wedge T_N]} \left| X(s) - Y(s) \right|^2 \right] \leq 4E_Q \left[ \int_0^\gamma \left| X(s) - Y(s) \right|^2 dk^N(s) + \|\sigma\|_\infty^2 \int_0^\gamma \left| q(s) \right|^2 ds \right]$$

$$+ \varepsilon E_Q \left[ \sup_{s \in [0, \gamma \wedge T_N]} \left| X(s) - Y(s) \right|^2 \right]$$

$$+ \frac{6C_B^2 + \varepsilon}{\varepsilon} E_Q \left[ \int_0^\gamma \left| X(s) - Y(s) \right|^2 dk^N(s) \right].$$

The time change $t = \gamma s$ gives

$$E_Q \left[ \sup_{s \in [0, \gamma \wedge T_N]} \left| X(s) - Y(s) \right|^2 \right] \leq \|\sigma\|_\infty^2 E_Q \left[ \int_0^\gamma \left| q(s) \right|^2 ds \right]$$

$$+ \varepsilon E_Q \left[ \sup_{s \in [0, \gamma \wedge T_N]} \left| X(s) - Y(s) \right|^2 \right]$$

$$+ \frac{C_B^2 + \varepsilon}{\varepsilon} E_Q \left[ \int_0^t \sup_{r \in [0, \gamma \wedge T_N]} \left| X(s) - Y(s) \right|^2 ds \right].$$

Choosing $\varepsilon < 1$ then using Gronwall’s lemma, we get

$$E_Q \left[ \sup_{s \in [0, \gamma \wedge T_N]} \left| X(s) - Y(s) \right|^2 \right] \leq \frac{1}{1 - \varepsilon} \|\sigma\|_\infty^2 E_Q \left[ \int_0^T \left| q(s) \right|^2 ds \right] \exp \left( \frac{6C_B^2 + \varepsilon}{\varepsilon(1 - \varepsilon)} T \right)$$

where we also used the fact that $\tau^N \wedge \gamma^N \leq T$. Letting successively $t$ then $N$ go to infinity, it follows by using Fatou’s lemma, $\gamma^N \uparrow \infty$, $\tau^N \uparrow T$ and the continuity of $X$ and $Y$ that

$$E_Q \left[ \sup_{s \in [0, T]} \left| X(s) - Y(s) \right|^2 \right] \leq \exp \left( \frac{6C_B^2 + \varepsilon}{\varepsilon(1 - \varepsilon)} T \right) \frac{1}{1 - \varepsilon} \|\sigma\|_\infty^2 E_Q \left[ \int_0^T \left| q(s) \right|^2 ds \right].$$

Hence, we conclude from (3) and (5) that

$$W_{2(d+1), loc}^2(\mu_x, \nu) \leq \exp \left( \frac{6C_B^2 + \varepsilon}{\varepsilon(1 - \varepsilon)} T \right) \frac{1}{1 - \varepsilon} \|\sigma\|_\infty^2 H(\nu | \mu_x).$$

This concludes the proof. \[\square\]

Remark 4. As it appears from the proof, it is conceivable that the above lemma extends to functions $\sigma$ in weighted Sobolev spaces when the set of smooth functions with compact support is dense. We restrict ourselves to $W_{2(d+1), loc}^0([0, T])$ since this space is enough for our purpose and to simplify the presentation.
2.2. Proof of Theorem 1

We start by the case where condition (A) is fulfilled. By [10, Theorem 3.1] equation (1) admits a unique strong solution. As in [10, Theorem 2], the idea consists in using Zvonkin’s transform in order to transform equation (1) into an SDE without drift then using Proposition 2 to conclude. In the rest of the paper, we denote by \( \mathcal{L} \) the differential operator defined by

\[
\mathcal{L} \phi := b \partial_x \phi + \frac{1}{2} r(\sigma^* \sigma \partial_x \phi).
\]

According to [30, Theorem 2], there exists a \( T > 0 \) small enough such that the PDE

\[
\begin{cases}
\partial_t \varphi + \mathcal{L} \varphi = 0 \\
\varphi(T, x) = x
\end{cases}
\]

admits a unique solution \( \varphi \) such that: for every \( t \), the function \( x \mapsto \varphi(t, x) \) is one-to-one from \( \mathbb{R}^d \) onto \( \mathbb{R}^d \), both \( \varphi \) and its inverse \( \psi \) belong to \( W^{1,2}_{p,\text{loc}}([0, T]) \) for each \( p > 1 \), both \( \varphi(t, \cdot) \) as well as its inverse \( \psi(t, \cdot) \) are Lipschitz continuous, with Lipschitz constants depending on \( d, T, \|b\|_\infty \) and \( \|\sigma\|_\infty \).

Applying Itô-Krylov’s formula, see [14, Theorem 2.10.1] to \( \varphi(t, X_t) := Y_t \), it follows that \( Y \) satisfies the drift-less SDE

\[ Y_t = Y_0 + \int_0^t \hat{\sigma}(s, Y_s) dW_s \]

with \( \hat{\sigma}(t, x) := (\sigma^* \partial_x \varphi)(t, \psi(t, y)) \). Since \( \sigma \) belongs to \( W^{0,1}_{2(d+1),\text{loc}}([0, T]) \), it follows that \( \varphi \) belongs to \( W^{1,2}_{p,\text{loc}}([0, T]) \) for each \( p > 1 \) and both \( \varphi \) and \( \psi \) are Lipschitz, it follows that \( \hat{\sigma} \in W^{0,1}_{2(d+1),\text{loc}}([0, T]) \).

Hence, by Lemma 2 the law \( \mu_y \) of \( Y \) satisfies \( T_2(C) \), where \( C \) is the constant in Proposition 2. But \( X_t = \psi(t, Y_t) \) and \( \psi \) is Lipschitz continuous. Thus, the result follows from [8, Lemma 2.1].

We now assume that condition (B) is fulfilled. We need to introduce the following Banach spaces:

For every \( k \geq 0 \) and \( m \geq 1 \), let \( H^k_m := (I - \Delta)^{-k/2} L^m \) be the usual space of Bessel potentials on \( \mathbb{R}^d \) and denote

\[
\mathbb{H}_p^2([0, T]) := L^q([0, T], H^2_p) \quad \text{and} \quad H^{2,q}_p([0, T]) := \{ u : [0, T] \to H^2_p \quad \text{and} \quad \partial_t u \in L^q_p([0, T]) \}.
\]

The space \( H^2_p \) is equipped with the norm

\[
\|u\|_{H^2_p} := \|(I - \Delta)u\|_{L^p}
\]

making it isomorphic to the Sobolev space \( W^{2,q}_p(\mathbb{R}^d) \).

Under assumption (B), the existence and uniqueness of \( X \) follow e.g. from [24, Theorem 1.1]. We now show that the law \( \mu_x \) of \( X \) satisfies \( T_2(C) \) for some \( C \). Let \( C_b \) be a constant to be determined later. By [13, Theorem 10.3 and Remark 10.4], the PDE

\[
\begin{cases}
\partial_t u^i + \mathcal{L} u^i + \frac{b^i}{1+C_b} = 0 \\
u^i(T, x) = 0
\end{cases}
\]

admits a unique solution \( u^i \in H^{2,q}_p([0, T]) \) and this solution satisfies

\[
\|\partial_t u^i\|_{L^q} + \|u^i\|_{H^{2,q}_p([0, T])} \leq \frac{C_1}{1+C_b} \|b^i\|_{L^q_p}
\]

for some constant \( C_1 \) depending on \( d, p, q, T \) and \( \|b\|_{L^q_p} \). Furthermore, since \( d/p + 2/q < 1 \), it follows by [13, Lemma 10.2] that

\[
|\partial_x u^i| \leq C_2 T^{-1/q} \left( \|u^i\|_{H^{2,q}_p([0, T])} + T \|\partial_t u^i\|_{L^q_p} \right)
\]

with \( \delta \in (0, 1] \) such that \( 2\delta + \frac{d}{p} + \frac{2}{q} < 2 \), and \( C_2 \) a constant depending on \( p, q \) and \( \delta \). Therefore, it holds that

\[
|\partial_x u^i| \leq C_1 C_2 T^{-1/q}(T + 1) \frac{1}{1+C_b} \|b^i\|_{L^q_p} \leq \frac{C_b}{1+C_b}
\]
with the choice $C_b := C_1 C_2 T^{-1/4} (T + 1) \max_{i \in \{1, \ldots, d\}} ||b^i||_{L_2^\gamma}$. Now consider the function $\Phi^i(t, x) := x^i + u^i(t, x)$, $i = 1, \ldots, d$. It is easily checked that the function $\Phi^i$ solves the PDE

$$
\begin{equation}
\begin{cases}
\partial_t \Phi^i + L \Phi^i = 0 \\
\Phi^i(T, x) = x^i.
\end{cases}
\end{equation}
$$

Put $\Phi(t, x) = (\Phi^1(t, x), \ldots, \Phi^d(t, x))$. Due to (3), it holds that

$$
\frac{1}{1 + C_b} |x - y| \leq |\Phi(x) - \Phi(y)| \leq \frac{1 + 2 C_b}{1 + C_b} |x - y| \quad \text{for all } x, y \in \mathbb{R}^d.
$$

As a consequence, $\Phi$ is one-to-one, (see e.g. the corollary on page 87 of [12]), and its inverse $\Psi := \Phi^{-1}$ is $\frac{1}{1 + C_b}$-Lipschitz continuous.

Since for every $t$, $u(t, \cdot)$ belongs to $H^2_p$, then it can be seen as an element of $W^2_p(\mathbb{R}^d)$. Moreover, the derivative of $u$ with respect to $t$ belongs to $L^p$, it thus follows that $u$ belongs to $W^{1,2}_p([0, T])$. Hence, the function $\Phi(t, x) := x + u(t, x)$ belongs to $W^{1,2}_{p,loc}([0, T])$. It-Krylov’s formula applied to $\Phi$ gives

$$
Y_t := \Phi(t, X_t) = \Phi(0, x) + \int_0^t (\partial_t \Phi + L \Phi)(s, X_s) \, ds + \int_0^t \partial_x \Phi(s, X_s) \sigma \, dW_s
$$

with $\tilde{\sigma}(t, y) := (\sigma^i \partial_{x^i} \Phi)(t, \Psi(t, y))$, and where the second equation follows by (13).

The rest of the proof follows as in the case of assumption (A). \qed

3. Examples

Let us now present a few examples of multidimensional diffusion models with non-Lipschitz coefficients which fit to our framework.

3.1. Particles interacting through their rank. Let $W^1, \ldots, W^n$ be $n$ independent Brownian motions. Rank-based interaction models are given by

$$
dX^{i, n}_t = \sum_{j=1}^n \delta_j \mathbb{1}_{X^{i,n}(t) = X^{j,n}(t)} \, dt + \sigma^i(t) \, dW^i(t) \quad X^{i,n}(0) = x^i
$$

for some real numbers $\delta_j$, some measurable, bounded functions $\sigma^i$, with $X^{1,n}(t) \leq X^{2,n}(t) \leq \cdots \leq X^{(n),n}(t)$ is the system in increasing order. More generally, this model can be written as

$$
dX^{i,n}_t = b \left( \sum_{j=1}^n \mathbb{1}_{X^{i,n}(t) \leq X^{j,n}(t)} \right) \, dt + \sigma^i(t) \, dW^i(t) \quad X^{i,n}(0) = x^i
$$

for a given (deterministic) functions $b$. This model was introduced by Fernholz and Karatzas [10] in the context of stochastic portfolio theory. Concentration of measures results for such systems can be found in [22]. When $0 < c \leq \inf_{i,t} |\sigma^i(t)| \leq \sup_{i,t} |\sigma^i(t)| \leq C$ for some $c, C$ and $b \in L^\infty$ or $b \in L^p(\mathbb{R}, dx)$ (with appropriate $p, d$), our main result shows that the law of $(X^{1,n}, \ldots, X^{n,n})$ satisfies $T_2(C)$ for some $C > 0$. This result is also valid for the so-called (finite) Atlas model of [2] given by

$$
dX^{i,n}_t = \sum_{j=1}^n \delta \mathbb{1}_{X^{i,n}(t) = X^{j,n}(t)} \, dt + \sigma^i(t) \, dW^i(t) \quad X^{i,n}(0) = x^i,
$$

for some constant $\delta$ and a permutation $(p_1, \ldots, p_n)$ of $(1, \ldots, n)$.
3.2. **Particles in quantile interaction.** Quantile interaction models are given by
\[ dX^{i,n}(t) = b(t, X^{n,i}(t), V^{\alpha,n}(t)) dt + \sigma(t, X^{n,i}(t)) dW(t) \quad X^{i,n}(0) = x^i, \]
where \( V^{\alpha,n}(t) \) is the quantile at level \( \alpha \in [0, 1] \) of the empirical measure of the system \((X^{1,n}(t), \ldots, X^{n,n}(t))\). That is,
\[ V^{\alpha,n}(t) := \inf \{ u \in \mathbb{R} : \frac{1}{n} \sum_{i=1}^{n} 1_{\{X^{i,n}(t) \leq u\}} \geq \alpha \}. \]
This model is considered for instance in [6] in connection to exchangeable particle systems. Theorem 1 can be applied to this case under integrability conditions on \( b \) and mild regularity conditions \( \sigma \).

3.3. **Brownian motion with random drift.** In addition to particle systems, our main result can also allow to derive transportation inequalities for semimartingales. We illustrate this in the next corollary. Let \( g \) be a progressive stochastic process. We call Brownian motion with drift the process
\[ X(t) = x + \int_0^t g(s) \, ds + \sigma W(t). \]
We have the following corollary of Theorem 1:

**Corollary 5.** Assume that the constant matrix \( \sigma \) satisfies [2]. If the drift \( g \) is bounded and \( T \) small enough, then the law \( \mu^*_t \) of \( X_t \) given by \( X(t) \) satisfies \( T^2(C) \) for some \( C > 0 \) depending on \( T, \sigma, d \) and \( \|g\|_\infty \).

**Proof.** Consider the Borel measurable function
\[ b(t, x) := E[g(t)|X(t) = x]. \]
By Corollary 3.7, we have \( \mu^*_t = \tilde{\mu}_t \), where \( \tilde{\mu}_t \) is the law of the weak solution \( \tilde{X}_t \) of the SDE
\[ \tilde{X}(t) = x + \int_0^t b(s, \tilde{X}(s)) \, ds + \sigma W(t). \]
Since \( g \) is bounded so is the function \( b \). Thus, the SDE admits a unique strong solution, see e.g. [1] or [28]. Thus, \( \tilde{X} \) is necessarily a strong solution and by Theorem \( \tilde{\mu} \) satisfies \( T^2(C) \), which concludes the argument.

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