EIGENVALUES AND ENTROPYS UNDER THE HARMONIC-RICCI FLOW

YI LI

Abstract. In this paper, the author discuss the eigenvalues and entropys under the harmonic-Ricci flow, which is the Ricci flow coupled with the harmonic map flow. We give an alternative proof of results for compact steady and expanding harmonic-Ricci breathers. In the second part, we derive some monotonicity formulas for eigenvalues of Laplacian under the harmonic-Ricci flow. Finally, we obtain the first variation of the shrinker and expanding entropys of the harmonic-Ricci flow.

Contents

1. Introduction 1
2. Notation and commuting identities 8
3. Harmonic-Ricci flow and the evolution equations 9
4. Entropys for harmonic-Ricci flow 10
5. Compact steady harmonic-Ricci flow 13
6. Compact expanding harmonic-Ricci breathers 14
7. Eigenvalues of the Laplacian under the harmonic-Ricci flow 19
8. Eigenvalues of the Laplacian-type under the harmonic-Ricci flow 25
9. Another formula for $\frac{d}{dt}\lambda(f(t))$ 30
10. The first variation of expander and shrinker entropys 35

References 43

1. Introduction

After successfully applying the Ricci flow to topological and geometric problems, people study some analogues flows, including the harmonic-Ricci flow[9, 11], connection Ricci flow[14], Ricci-Yang-Mills flow[13, 16, 17], and renormalization group flows[6, 8, 12, 15], etc. In this note, we study the eigenvalue problems of the harmonic-Ricci flow which is the following coupled system

\begin{align}
\frac{\partial}{\partial t} g(x, t) & = -2\text{Ric}_g(x, t) + 4du(x, t) \otimes du(x, t), \\
\frac{\partial}{\partial t} u(x, t) & = \Delta_{g(x, t)} u(x, t).
\end{align}
For convenience, we introduce a new symmetric 2-tensor $S_{g(t),u(t)}$ whose components $S_{ij}$ are defined by

$$S_{ij} := R_{ij} - 2\partial_i u \partial_j u.$$ 

Its trace is $S_{g(t),u(t)} := g^{ij} S_{ij} = R_{g(t)} - 2 |g(t) \nabla u(t)|^2_{g(t)}$.

Suppose that $M$ is a Riemannian manifold. For any Riemannian metric $g$ and any smooth functions $u, f$, we have a number of functionals

$$\mathcal{F}(g, u, f) = \int_M \left( R_g + |g \nabla f|^2_g - 2 |g \nabla u|^2_g \right) e^{-f} dV_g,$$

$$\mathcal{E}(g, u, f) = \int_M \left( R_g - 2 |g \nabla u|^2_g \right) e^{-f} dV_g,$$

$$\mathcal{F}_k(g, u, f) = \int_M \left( k R_g + |g \nabla f|^2_g - 2k |g \nabla u|^2_g \right) e^{-f} dV_g.$$ 

List\[9] and Müller\[11] showed that, as in the case of Perelman’s $\mathcal{F}$-functional, under the following evolution equation

$$\frac{\partial}{\partial t} g(t) = -2 \text{Ric}_{g(t)} + 4 du(t) \otimes du(t),$$

$$\frac{\partial}{\partial t} u(t) = \Delta_{g(t)} u(t),$$

$$\frac{\partial}{\partial t} f(t) = -\Delta_{g(t)} f(t) - R_{g(t)} + \left| g(t) \nabla f(t) \right|^2_{g(t)} + 2 \left| g(t) \nabla u(t) \right|^2_{g(t)}$$

the evolution equation for $\mathcal{F}$-functional is

$$\frac{d}{dt} \mathcal{F}(g(t), u(t), f(t)) = 2 \int_M \left| S_{g(t),u(t)} + g(t) \nabla^2 f(t) \right|^2_{g(t)} e^{-f(t)} dV_{g(t)}$$

$$+4 \int_M \left| \Delta_{g(t)} u(t) - (du(t), df(t))_{g(t)} \right|^2_{g(t)} e^{-f(t)} dV_{g(t)}. \quad (1.4)$$

that is nonnegative. Based on (1.4), we derive

**Theorem 1.1.** Under the evolution equation (1.3), one has

$$\frac{d}{dt} \mathcal{E}(g(t), u(t), f(t)) = 2 \int_M \left| S_{g(t),u(t)} \right|^2_{g(t)} e^{-f(t)} dV_{g(t)}$$

$$+4 \int_M \left| \Delta_{g(t)} u(t) \right|^2_{g(t)} e^{-f(t)} dV_{g(t)}, \quad (1.5)$$

$$\frac{d}{dt} \mathcal{F}_k(g(t), u(t), f(t)) = 2(k - 1) \int_M \left| S_{g(t),u(t)} + g(t) \nabla^2 f(t) \right|^2_{g(t)} e^{-f(t)} dV_{g(t)}$$

$$+2(k - 1) \int_M \left| \Delta_{g(t)} u(t) \right|^2_{g(t)} e^{-f(t)} dV_{g(t)}$$

$$+4k \int_M \left| \Delta_{g(t)} u(t) - (du(t), df(t))_{g(t)} \right|^2_{g(t)} e^{-f(t)} dV_{g(t)}, \quad (1.6)$$

.$$
As a corollary we give a new proof of the following

**Corollary 1.2.** There is no compact steady harmonic-Ricci breather other than \((M, g(t))\) is Ricci-flat and \(u(t)\) is constant.

When we deal with the expanding harmonic-Ricci breather, we need the following two functionals

\[
\mathcal{L}_+(g, u, \tau, f) = \tau^2 \int_M \left( R_g + \frac{n}{2\tau} + \Delta_g f - 2 |g \nabla u|^2_g \right) e^{-f} dV_g,
\]

\[
\mathcal{L}_{+,k}(g, u, \tau, f) = \tau^2 \int_M \left[ k \left( R_g + \frac{n}{2\tau} \right) + \Delta_g f - 2k |g \nabla u|^2_g \right] e^{-f} dV_g.
\]

Under the following evolution equation

\[
\frac{\partial}{\partial t} g(t) = -2\text{Ric}_g(t) + 4du(t) \otimes du(t),
\]

\[
\frac{\partial}{\partial t} u(t) = \Delta_g(t) u(t),
\]

\[
\frac{\partial}{\partial t} f(t) = -\Delta_g(t) f(t) + \left| g(t) \nabla f(t) \right|^2_{g(t)} - R_g(t) + 2 \left| g(t) \nabla u(t) \right|^2_{g(t)},
\]

\[
\frac{d}{dt} \tau(t) = 1,
\]

we have

**Theorem 1.3.** Under the above evolution equation, one has

\[
\frac{d}{dt} \mathcal{L}_+(g(t), u(t), \tau(t), f(t)) = 2\tau(t)^2 \int_M \left| \mathcal{S}_{g(t), u(t)} + g(t) \nabla^2 f(t) + \frac{1}{2\tau(t)} g(t) \right|^2_{g(t)} e^{-f(t)} dV_g(t)
\]

\[
+4\tau(t)^2 \int_M |\Delta_g(t) u(t) - \langle du(t), df(t) \rangle_{g(t)}|^2_{g(t)} e^{-f(t)} dV_g(t),
\]

\[
\frac{d}{dt} \mathcal{L}_{+,k}(g(t), u(t), \tau(t), f(t)) = 2\tau(t)^2 \int_M \left| \mathcal{S}_{g(t), u(t)} + g(t) \nabla^2 f(t) + \frac{1}{2\tau(t)} g(t) \right|^2_{g(t)} e^{-f(t)} dV_g(t)
\]

\[
+4\tau(t)^2 \int_M |\Delta_g(t) u(t) - \langle du(t), df(t) \rangle_{g(t)}|^2_{g(t)} e^{-f(t)} dV_g(t)
\]

\[
+4(k - 1)\tau(t)^2 \int_M |\Delta_g(t) u(t)|^2_{g(t)} e^{-f(t)} dV_g(t).
\]

As a corollary, we obtain a new proof of the following
Corollary 1.4. There is no expanding harmonic-Ricci breather on compact Riemannian manifolds other than \( M \) is an Einstein manifold and \( u(t) \) is constant.

The second part of this paper focuses on the eigenvalue of the Laplacian operator under the harmonic-Ricci flow. Suppose that \( \lambda(t) \) is an eigenvalue of the Laplacian \( \Delta_{g(t)} \) with eigenfunction \( f(t) \), then

\[
\frac{d}{dt} \lambda(t) \cdot \int_M f(t)^2 dV_{g(t)} = \lambda(t) \int_M S_{g(t),u(t)} f(t)^2 dV_{g(t)}
\]

(1.9)

(1.10) \[ S_{\text{min}}(0) := \min_{x \in M} S_{g(t),u(t)}(x) \]

the minimum of \( S_{g(t),u(t)} \) over \( M \) at the time 0.

Theorem 1.5. If \((g(t), u(t))\) is a solution of the harmonic-Ricci flow on a compact Riemannian manifold \( M \) and \( \lambda(t) \) denotes the eigenvalue of the Laplacian \( \Delta_{g(t)} \), then

\[
\frac{d}{dt} \lambda(t) \cdot \int_M f(t)^2 dV_{g(t)} = \lambda(t) \int_M S_{g(t),u(t)} f(t)^2 dV_{g(t)} \\
- \int_M S_{g(t),u(t)} \left| g(t) \nabla f \right|^2_{g(t)} dV_{g(t)} \\
+ 2 \int_M \langle S_{g(t),u(t)}, df(t) \otimes df(t) \rangle_{g(t)} dV_{g(t)}.
\]

The above equation (1.9) is a general formula to describe the evolution of \( \lambda(t) \) under the harmonic-Ricci flow. Under a curvature assumption, we can derive some monotonicity formulas for the eigenvalue \( \lambda(t) \).

Set

(1.10) \[ S_{\text{min}}(0) := \min_{x \in M} S_{g(t),u(t)}(x) \]

the minimum of \( S_{g(t),u(t)} \) over \( M \) at the time 0.

Theorem 1.6. Let \((g(t), u(t))_{t \in [0,T]}\) be a solution of the harmonic-Ricci flow on a compact Riemannian manifold \( M \) and \( \lambda(t) \) denote the eigenvalue of the Laplacian \( \Delta_{g(t)} \). Suppose that \( S_{g(t),u(t)} - \alpha S_{g(t),u(t)} g(t) \geq 0 \) along the harmonic-Ricci flow for some \( \alpha \geq 1/2 \).

1. If \( S_{\text{min}}(0) \geq 0 \), then \( \lambda(t) \) is nondecreasing along the harmonic-Ricci flow for any \( t \in [0,T] \).
2. If \( S_{\text{min}}(0) > 0 \), then the quantity

\[
\left( 1 - \frac{2}{n} S_{\text{min}}(0) t \right)^{n\alpha} \lambda(t)
\]

is nondecreasing along the harmonic-Ricci flow for \( T \leq \frac{n}{2S_{\text{min}}(0)} \).
3. If \( S_{\text{min}}(0) < 0 \), then the quantity

\[
\left( 1 - \frac{2}{n} S_{\text{min}}(0) t \right)^{n\alpha} \lambda(t)
\]

is nondecreasing along the harmonic-Ricci flow for any \( t \in [0,T] \).

Corollary 1.7. Let \((g(t), u(t))_{t \in [0,T]}\) be a solution of the harmonic-Ricci flow on a compact Riemannian surface \( \Sigma \) and \( \lambda(t) \) denote the eigenvalue of the Laplacian \( \Delta_{g(t)} \).
Suppose that $\text{Ric}_{g(t)} \leq \epsilon du(t) \otimes du(t)$ where

$$\epsilon \leq 4 \frac{1 - \alpha}{1 - 2\alpha}, \quad \alpha > \frac{1}{2}.$$  

(1) If $S_{\text{min}}(0) \geq 0$, then $\lambda(t)$ is nondecreasing along the harmonic-Ricci flow for any $t \in [0, T]$.

(1-1) If $S_{\text{min}}(0) > 0$, then the quantity

$$(1 - S_{\text{min}}(0)t)^{2\alpha} \lambda(t)$$

is nondecreasing along the harmonic-Ricci flow for $T \leq \frac{1}{S_{\text{min}}(0)}$.

(2) Suppose that

$$\left| g(t) \nabla u(t) \right|_{g(t)}^2 g(t) \geq 2du(t) \otimes du(t).$$

(1-1) If $S_{\text{min}}(0) \geq 0$, then $\lambda(t)$ is nondecreasing along the harmonic-Ricci flow for any $t \in [0, T]$.

(1-2) If $S_{\text{min}}(0) > 0$, then the quantity

$$(1 - S_{\text{min}}(0)t) \lambda(t)$$

is nondecreasing along the harmonic-Ricci flow for $T \leq \frac{1}{S_{\text{min}}(0)}$.

(3) If $S_{\text{min}}(0) < 0$, then the quantity

$$(1 - S_{\text{min}}(0)t) \lambda(t)$$

is nondecreasing along the harmonic-Ricci flow for any $t \in [0, T]$.

When we restrict to the Ricci flow, we obtain

Corollary 1.8. Let $(g(t))_{t \in [0, T]}$ be a solution of the Ricci flow on a compact Riemannian surface $\Sigma$ and $\lambda(t)$ denote the eigenvalue of the Laplacian $\Delta_{g(t)}$.

(1) If $R_{\text{min}}(0) \geq 0$, then $\lambda(t)$ is nondecreasing along the Ricci flow for any $t \in [0, T]$.

(1-1) If $R_{\text{min}}(0) > 0$, then the quantity $(1 - R_{\text{min}}(0)t) \lambda(t)$ is nondecreasing along the Ricci flow for $T \leq \frac{1}{R_{\text{min}}(0)}$.

(2) If $S_{\text{min}}(0) > 0$, then the quantity

$$(1 - S_{\text{min}}(0)t) \lambda(t)$$

is nondecreasing along the harmonic-Ricci flow for any $t \in [0, T]$.

Remark 1.9. Let $(g(t))_{t \in [0, T]}$ be a solution of the Ricci flow on a compact Riemannian surface $\Sigma$ with nonnegative scalar curvature and $\lambda(t)$ denote the eigenvalue of the Laplacian $\Delta_{g(t)}$. Then $\lambda(t)$ is nondecreasing along the Ricci flow for any $t \in [0, T]$. 
Since

\[(1.11) \quad \mu(g,u) := \inf \left\{ F(g,u,f) \, | \, f \in C^\infty(M), \int_M e^{-f} dV_g = 1 \right\} \]

is the smallest eigenvalue of the operator \( \Delta_{g,u} := -4\Delta_g + R_g - 2 |\nabla u|^2_{g} \), we can consider the evolution equation for this eigenvalue under the harmonic-Ricci flow.

To the operator \( \Delta_{g,u} \) we associate a functional

\[(1.12) \quad \lambda_{g,u}(f) := \int_M f \cdot \Delta_{g,u}f \cdot dV_g. \]

When \( f \) is an eigenfunction of the operator \( \Delta_{g,u} \) with the eigenvalue \( \lambda \) and normalized by \( \int_X f^2 dV_g = 1 \), we obtain

\[ \lambda_{g,u}(f) = \lambda. \]

So, we can suffice to study the evolution equation for \( \frac{d}{dt} \lambda_{g,u}(f) \) under the harmonic-Ricci flow.

**Theorem 1.10.** Suppose that \((g(t), u(t))\) is a solution of the harmonic-Ricci flow on a compact Riemannian manifold \(M\) and \(f(t)\) is an eigenvalue of \( \Delta_{g(t),u(t)} \), i.e., \( \Delta_{g(t),u(t)}f(t) = \lambda(t)f(t) \) (where \( \lambda(t) \) is only a function of time \( t \)), with the normalized condition \( \int_M f(t)^2 dV_g = 1 \). Then we have

\[
\frac{d}{dt} \lambda(t) = \frac{d}{dt} \lambda_{g,u}(f(t)) = \int_M 2 \langle S_{g(t),u(t)}, df(t) \otimes df(t) \rangle_{g(t)} dV_g(t) \\
+ \int_M f(t)^2 \left[ |S_{g(t),u(t)}|^2_{g(t)} + 2 |\Delta_{g(t),u(t)}u(t)|^2_{g(t)} \right] dV_g(t).
\]

In [9], List proved the nonnegativity of the operator \( S_{g(t),u(t)} \) is preserved by the harmonic-Ricci flow, hence

**Corollary 1.11.** If \( \text{Ric}(0) - 2du(0) \otimes du(0) \geq 0 \), then the eigenvalues of the operator \( \Delta_{g(t),u(t)} \) are nondecreasing under the harmonic-Ricci flow.

**Remark 1.12.** If we choose \( u(t) \equiv 0 \), then we obtain X. Cao’s result [3].

There is another expression of \( \frac{d}{dt} \lambda(t) \).

**Theorem 1.13.** Suppose that \((g(t), u(t))\) is a solution of the harmonic-Ricci flow on a compact Riemannian manifold \(M\) and \(f(t)\) is an eigenvalue of \( \Delta_{g(t),u(t)} \), i.e., \( \Delta_{g(t),u(t)}f(t) = \lambda(t)f(t) \) (where \( \lambda(t) \) is only a function of
Suppose that

\[ \frac{d}{dt} \lambda(t) = \frac{d}{dt} \lambda_{g,u}(f(t)) \]

\[ = \frac{1}{2} \int_M \left| \mathcal{S}_{g(t),u(t)} + g(t) \nabla^2 \varphi(t) \right|^2_{g(t)} e^{-\varphi(t)} dV_{g(t)} \]

\[ + \frac{1}{4} \int_M \left| \mathcal{S}_{g(t),u(t)} \right|^2_{g(t)} e^{-\varphi(t)} dV_{g(t)} + \int_M \left| \langle du(t), d\varphi(t) \rangle_{g(t)} \right|^2 e^{-\varphi(t)} dV_{g(t)} \]

\[ (1.14) + 2 \int_M \left| g(t) \nabla^2 u(t) \right|^2_{g(t)} e^{-\varphi(t)} dV_{g(t)} \]

\[ + \frac{1}{4} \int_M \left| \mathcal{S}_{g(t),u(t)} + 4 du(t) \otimes du(t) \right|^2_{g(t)} e^{-\varphi(t)} dV_{g(t)} \]

\[ - \int_M \Delta_{g(t)} \left( \left| g(t) \nabla u(t) \right|^2_{g(t)} \right) e^{-\varphi(t)} dV_{g(t)} \]

where \( f(t)^2 = e^{-\varphi(t)} \).

**Remark 1.14.** When \( u \equiv 0 \), (1.14) reduces to J. Li's formula [7].

Suppose that \( M \) is a closed manifold of dimension \( n \). For any Riemannian metric \( g \), any smooth functions \( u, f \), and any positive number \( \tau \), we define

\[ W_{\pm}(g, u, f, \tau) := \int_M \left[ \tau \left( \mathcal{S}_g + |g^2 f|^2 \right) \mp f \pm n \right] \frac{e^{-f}}{(4\pi \tau)^{n/2}} dV_g. \]

Set

\[ \mu_{\pm}(g, u, \tau) := \inf \left\{ W_{\pm}(g, u, f, \tau) \mid f \in C^\infty(M), \int_M \frac{e^{-f}}{(4\pi \tau)^{n/2}} dV_g = 1 \right\}, \]

\[ \nu_{\pm}(g, u) := \inf \{ \mu_{\pm}(g, u, \tau) \mid \tau > 0 \}. \]

The first variation of \( \nu_{\pm}(g(s), u(s)) \) is

**Theorem 1.15.** Suppose that \( (M, g) \) is a compact Riemannian manifold and \( u \) a smooth function on \( M \). Let \( h \) be any symmetric covariant 2-tensor on \( M \) and set \( g(s) := g + sh \). Let \( v \) be any smooth function on \( M \) and \( u(s) := u + sv \). If \( \nu_{\pm}(g(s), u(s)) = W_{\pm}(g(s), u(s), f_{\pm}(s), \tau_{\pm}(s)) \) for some smooth functions \( f_{\pm}(s) \) with \( \int_M e^{-f_{\pm}(s)} dV/(4\pi \tau_{\pm}(s))^{n/2} = 1 \) and constants \( \tau_{\pm}(s) > 0 \), then

\[ \left. \frac{d}{ds} \right|_{s=0} \nu_{\pm}(g(s), u(s)) \]

\[ = -\tau_{\pm} \int_M \left( \langle h, \mathcal{S}_{g,u} \rangle_g + \langle h, g^2 f \rangle_g \mp \frac{1}{2\tau_{\pm}} \text{tr}_g h \right) \frac{e^{-f_{\pm}}}{(4\pi \tau_{\pm})^{n/2}} dV_g \]

\[ + 4\tau_{\pm} \int_M v (\Delta_g u - \langle du, df_{\pm} \rangle_g) \frac{e^{-f_{\pm}}}{(4\pi \tau_{\pm})^{n/2}} dV_g, \]

where \( f(t)^2 = e^{-\varphi(t)} \).
where \( f_\pm := f_\pm(0) \) and \( \tau_\pm := \tau_\pm(0) \). In particular, the critical points of \( \nu_\pm(\cdot, \cdot) \) satisfy
\[
S_{g,u} + g \nabla^2 f_\pm + \frac{1}{2\tau_\pm} g = 0, \quad \Delta_g u = \langle du, df_\pm \rangle_g.
\]
Consequently, if \( W_\pm(g, u, f, \tau) \) and \( \nu_\pm(g, u) \) achieve their minimums, then \((M, g)\) is a gradient expanding and shrinker harmonic-Ricci soliton according to the sign.

**Corollary 1.16.** Suppose that \((M, g)\) is a compact Riemannian manifold and \( u \) a smooth function on \( M \). Let \( h \) be any symmetric covariant 2-tensor on \( M \) and set \( g(s) := g + sh \). Let \( v \) be any smooth function on \( M \) and \( u(s) := u + sv \). If \( \nu_\pm(g(s), u(s)) = W_\pm(g(s), u(s), f_\pm(s), \tau_\pm(s)) \) for some smooth function \( f_\pm(s) \) with \( \int_M e^{-f_\pm(s)} dV/(4\pi \tau_\pm(s))^{n/2} = 1 \) and a constant \( \tau_\pm(s) > 0 \), and \((g, u)\) is a critical point of \( \nu_\pm(\cdot, \cdot) \), then
\[
\text{Ric}_g = \mp \frac{1}{2\tau_\pm} g, \quad f_\pm \equiv \text{constant}, \quad u \equiv \text{constant}.
\]
Thus, if \( W_\pm(g, u, f, \tau) \) achieve their minimum and \((g, u)\) is a critical point of \( \nu_\pm(\cdot, \cdot) \), then \((M, g)\) is an Einstein manifold and \( u \) is a constant function.

**Remark 1.17.** In the situation of Corollary 1.16 by normalization, we may choose \( f_\pm = \frac{n}{2} \) and \( u = 0 \).

**Acknowledgements.** Part of work was done when the author visited Center of Mathematical Science at Zhejiang University. The author would like to thank Professor Kefeng Liu, who teaches the author mathematics. Furthermore, I also thank Professor Hongwei Xu and other staffs in Center of Mathematical Science.

2. **Notation and Commuting Identities**

Let \( M \) be a closed (i.e., compact and without boundary) Riemannian manifold of dimension \( n \). For any vector bundle \( E \) over \( M \), we denote by \( \Gamma(M, E) \) the space of smooth sections of \( E \). Set
\[
\varnothing^2(M) := \{ v = (v_{ij}) \in \Gamma(M, T^\ast M \otimes T^\ast M) | v_{ij} = v_{ji} \},
\]
\[
\varnothing^2_+(M) := \{ g = (g_{ij}) \in \varnothing^2(M) | g_{ij} > 0 \}.
\]
Thus, \( \varnothing^2(M) \) is the space of all symmetric covariant 2-tensors on \( M \) while \( \varnothing^2_+(M) \) the space of all Riemannian metrics on \( M \). The space of all smooth functions on \( M \) is denoted by \( C^\infty(M) \).

For a given Riemannian metric \( g \in \varnothing^2_+(M) \), the corresponding Levi-civita connection \( ^g\Gamma = (^g\Gamma^k_{ij}) \) is given by
\[
^g\Gamma^k_{ij} = \frac{1}{2} g^{kl} \left( \partial_i g_{jl} + \partial_j g_{il} - \partial_l g_{ij} \right)
\]
where $\partial_i := \frac{\partial}{\partial x^i}$ for a local coordinate system $\{x^1, \ldots, x^n\}$. The Riemann tensor $Rm_g = (g R_{ij})$ is determined by

\begin{equation}
R_{ij} \equiv \partial_i g_{jl} - \partial_j g_{il} + g_{jl} \Gamma^k_{il} - g_{il} \Gamma^k_{jl}.
\end{equation}

The Ricci curvature $\text{Ric}_g = (g R_{ij})$ is

\begin{equation}
R_{ij} = g_{kl} \cdot g R_{lkl}.
\end{equation}

The scalar curvature $R_g$ of the metric $g$ now is given by

\begin{equation}
R_g = g_{ij} \cdot g R_{ij}.
\end{equation}

For any tensor $A = (A_{j_1 \cdots j_p}^{k_1 \cdots k_q})$ the covariant derivative of $A$ is

\begin{equation}
g \nabla_i A_{j_1 \cdots j_p}^{k_1 \cdots k_q} = \partial_i A_{j_1 \cdots j_p}^{k_1 \cdots k_q} + \sum_{r=1}^p g \Gamma_{ij}^{kl} A_{j_1 \cdots j_p}^{k_1 \cdots k_{r-1}k_{r+1} \cdots k_q} + \sum_{s=1}^q g \Gamma_{ik}^{lm} A_{l_1 \cdots l_{s-1}l_{s+1} \cdots l_q}^{m_1 \cdots m_p}.
\end{equation}

Next we recall the Ricci identity:

\begin{equation}
g \nabla_i \nabla_j A_{k_1 \cdots k_p}^{l_1 \cdots l_q} - g \nabla_j \nabla_i A_{k_1 \cdots k_p}^{l_1 \cdots l_q} = \sum_{r=1}^p g R_{ijk}^{l} A_{l_1 \cdots l_{r-1}l_{r+1} \cdots l_q}^{m_1 \cdots m_p} + \sum_{s=1}^q g R_{ikl}^{s} A_{l_1 \cdots l_{s-1}l_{s+1} \cdots l_q}^{m_1 \cdots m_p}.
\end{equation}

In particular, for any smooth function $f \in C^\infty(M)$ we have

\begin{equation}
g \nabla_i g \nabla_j f = g \nabla_j g \nabla_i f.
\end{equation}

The Bianchi identities are

\begin{align}
0 &= g R_{ijkl} + g R_{iklj} + g R_{iljk}, \\
0 &= g \nabla_q g R_{ijkl} + g \nabla_i g R_{jkl} + g \nabla_j g R_{qikl}
\end{align}

and the contracted Bianchi identities are

\begin{align}
0 &= 2g \nabla_j g R_{ij} - g \nabla_i g R, \\
0 &= g \nabla_i R_{jk} - g \nabla_j g R_{ik} + g \nabla_l g R_{lki}.
\end{align}

3. Harmonic-Ricci flow and the evolution equations

Motivated by static Einstein vacuum equation, List introduced the harmonic-Ricci flow (Originally, it is called the Ricci flow coupled with the harmonic map flow.). Such a flow is called similar to the Ricci flow and is the following coupled system

\begin{align}
\frac{\partial}{\partial t} g(x, t) &= -2 \text{Ric}_g(x, t) + 4 du(x, t) \otimes du(x, t), \\
\frac{\partial}{\partial t} u(x, t) &= \Delta g(x, t) u(x, t)
\end{align}

for a family of Riemannian metrics $g(x, t)$ (or written as $g(t)$) and a family of smooth functions $u(x, t)$ (or written as $u(t)$). Locally, we have

\begin{equation}
\frac{\partial}{\partial t} g_{ij} = -2 R_{ij} + 4 \partial_i u \cdot \partial_j u, \quad \frac{\partial}{\partial t} u = \Delta u.
\end{equation}
Introduce a new symmetric tensor field \( S_{g(t),u(t)} = (S_{ij}) \in \mathcal{O}^2(M) \) by
\[
S_{ij} := R_{ij} - 2\partial_i u \cdot \partial_j u.
\]
Then its trace \( S_{g(t),u(t)} \) is equal to
\[
S_{g(t),u(t)} = g^{ij}S_{ij} = R_{g(t)} - 2 \left| g(t)\nabla u(t) \right|^2_{g(t)}.
\]

The evolution equation for \( R_{g(t)} \) is
\[
\frac{\partial}{\partial t} R_{g(t)} = \Delta_{g(t)} R_{g(t)} + 2 |\text{Ric}_{g(t)}|^2_{g(t)} + 4 \left| \Delta_{g(t)} u(t) \right|^2_{g(t)} - 8 \left\langle \text{Ric}_{g(t)}, du(t) \otimes du(t) \right\rangle_{g(t)}.
\]

Also, we have the evolution equation for \( |g(t)\nabla u(t)|^2_{g(t)} \):
\[
\frac{\partial}{\partial t} \left| g(t)\nabla u(t) \right|^2_{g(t)} = \Delta_{g(t)} \left| g(t)\nabla u(t) \right|^2_{g(t)} - 2 \left| g(t)\nabla^2 u(t) \right|^2_{g(t)} - 4 \left| g(t)\nabla u(t) \right|^4_{g(t)}.
\]

and the evolution equation for \( S_{g(t),u(t)} \):
\[
\frac{\partial}{\partial t} S_{g(t),u(t)} = \Delta_{g(t)} S_{g(t),u(t)} + 2 \left| S_{g(t),u(t)} \right|^2_{g(t)} + 4 \left| \Delta_{g(t)} u(t) \right|^2_{g(t)}.
\]

4. Entropys for harmonic-Ricci flow

Motivated by Perelman’s entropy, List [9] introduced the similar functional for the harmonic-Ricci flow:
\[
\mathcal{O}^2_+(M) \times C^\infty(M) \times C^\infty(M) \rightarrow \mathbb{R}, \quad (g, u, f) \mapsto \mathcal{F}(g, u, f)
\]
where
\[
\mathcal{F}(g, u, f) := \int_M \left( R_g + \left| g^f \nabla f \right|^2_{g} - 2 \left| g^f \nabla u \right|^2_{g} \right) e^{-f} dV_g.
\]
He also showed that if \((g(t), u(t), f(t))\) satisfies the following system
\[
\frac{\partial}{\partial t} g(t) = -2\text{Ric}_{g(t)} + 4du(t) \otimes du(t) - 2g(t)\nabla^2 f(t),
\]
\[
\frac{\partial}{\partial t} u(t) = \Delta_{g(t)} u(t) - \left\langle du(t), df(t) \right\rangle_{g(t)},
\]
\[
\frac{\partial}{\partial t} f(t) = -\Delta_{g(t)} f(t) - R_{g(t)} + 2 \left| g(t)\nabla u(t) \right|^2_{g(t)},
\]
then the evolution of the entropy is given by
\[
\frac{d}{dt} \mathcal{F}(g(t), u(t), f(t)) = 2 \int_M \left( \left| S_{g(t),u(t)} + g(t)\nabla^2 f(t) \right|^2_{g(t)} + 2 \left| \Delta_{g(t)} u(t) - \left\langle du(t), df(t) \right\rangle_{g(t)} \right|^2_{g(t)} \right) e^{-f(t)} dV_{g(t)} \geq 0.
\]
Remark 4.1. The above system (4.2) is equivalent to the following

$$
\frac{\partial}{\partial t} g(t) = -2\text{Ric}_g(t) + 4du(t) \otimes du(t),
$$

(4.4)

$$
\frac{\partial}{\partial t} u(t) = \Delta_g(t) u(t),
$$

$$
\frac{\partial}{\partial t} f(t) = -\Delta_g(t) f(t) - R_g(t) + \left|g(t)\nabla f(t)\right|_{g(t)}^2 + 2\left|g(t)\nabla u(t)\right|_{g(t)}^2.
$$

The same evolution of the entropy holds for this system (4.4).

In particular, the entropy is nondecreasing and the equality holds if and only if \((g(t), u(t), f(t))\) satisfies

(4.5) \(S_{g(t), u(t)} + g(t)^2 f(t) = 0, \quad \Delta_g(t) u(t) - \langle du(t), df(t)\rangle_{g(t)} = 0.\)

Definition 4.2. The \(E\)-functional is defined as

\[
\otimes_c^2 (M) \times C^\infty (M) \times C^\infty (M) \rightarrow \mathbb{R}, \quad (g, u, f) \mapsto \mathcal{E}(g, u, f),
\]

where

(4.6) \(\mathcal{E}(g, u, f) := \int_M \left(R_g - 2 |g\nabla u|_g^2\right) e^{-f} dV_g.\)

Proposition 4.3. Under the evolution equation (4.4), one has

(4.7) \(\frac{d}{dt} \mathcal{E}(g(t), u(t), f(t)) = 2 \int_M \left|S_{g(t), u(t)}\right|_{g(t)}^2 e^{-f(t)} dV_g(t) + 4 \int_M \left|\Delta_g(t) u(t)\right|_{g(t)}^2 e^{-f(t)} dV_g(t).\)

Proof. Since \(S_{g(t), u(t)} = R_g(t) - 2 |g(t)\nabla u(t)|_{g(t)}^2\) and

\[
\frac{\partial}{\partial t} S_{g(t), u(t)} = \Delta_g(t) S_{g(t), u(t)} + 2 \left|S_{g(t), u(t)}\right|_{g(t)}^2 + 4 \left|\Delta_g(t) u(t)\right|_{g(t)}^2,
\]

\[
\frac{\partial}{\partial t} dV_g(t) = -S_{g(t), u(t)} dV_g(t),
\]
we have
\[
\frac{d}{dt} \mathcal{E}(g(t), u(t), f(t)) = \int_M \left( \frac{\partial}{\partial t} S_{g(t), u(t)} \right) e^{-f(t)} dV_{g(t)} + \int_M S_{g(t), u(t)} \frac{\partial}{\partial t} \left( e^{-f(t)} dV_{g(t)} \right)
\]
\[
= \int_M \left( \Delta_{g(t)} S_{g(t), u(t)} + 2 |S_{g(t), u(t)}|_{g(t)}^2 + 4 |\Delta_{g(t)} u(t)|_{g(t)}^2 \right) e^{-f(t)} dV_{g(t)}
\]
\[
+ \int_M S_{g(t), u(t)} \left( -\frac{\partial}{\partial t} f(t) - S_{g(t), u(t)} \right) e^{-f(t)} dV_{g(t)}
\]
\[
= 2 \int_M |S_{g(t), u(t)}|_{g(t)}^2 e^{-f(t)} dV_{g(t)} + 4 \int_M |\Delta_{g(t)} u(t)|_{g(t)}^2 e^{-f(t)} dV_{g(t)}
\]
\[
+ \int_M S_{g(t), u(t)} \left( -\Delta_{g(t)} f(t) + |g(t)\nabla f(t)|_{g(t)}^2 \right) e^{-f(t)} dV_{g(t)}
\]
which implies (4.7).

\[\square\]

**Definition 4.4.** For any \( k \geq 1 \) we define
\[
\mathcal{F}_k(g, u, f) := \int_M \left( k R_g + |g \nabla f|_g^2 - 2k |g \nabla u|_g^2 \right) e^{-f} dV_g.
\]
By definition, it is easy to show that
\[
\mathcal{F}_k(g, u, f) = (k - 1) \mathcal{E}(g, u, f) + \mathcal{F}(g, u, f).
\]
When \( k = 1 \), this is the \( \mathcal{F} \)-functional.

**Theorem 4.5.** Under the evolution equation (4.4), one has
\[
\frac{d}{dt} \mathcal{F}_k(g(t), u(t), f(t)) = 2(k - 1) \int_M |S_{g(t), u(t)}|_{g(t)}^2 e^{-f(t)} dV_{g(t)}
\]
\[
+ 2 \int_M |S_{g(t), u(t)} + g(t) \nabla f(t)|_{g(t)}^2 e^{-f(t)} dV_{g(t)}
\]
\[
+ 4(k - 1) \int_M |\Delta_{g(t)} u(t)|_{g(t)}^2 e^{-f(t)} dV_{g(t)}
\]
\[
+ 4 \int_M |\Delta_{g(t)} u(t) - \langle du(t), df(t) \rangle_{g(t)}|_{g(t)}^2 e^{-f(t)} dV_{g(t)}.
\]
Furthermore, the monotonicity is strict unless \( g(t) \) is Ricci-flat, \( u(t) \) is constant and \( f(t) \) is constant.

**Proof.** It immediately follows from (4.3) and (4.7).

\[\square\]

Set
\[
\mu_k(g, u) := \inf \left\{ \mathcal{F}_k(g, u, f) \Bigg| f \in C^\infty(M), \ \int_M e^{-f} dV_g = 1 \right\}.
\]
Then \( \mu_k(g, u) \) is the lowest eigenvalue of \(-4\Delta_g + k \left( R_g - 2 |g \nabla u|_g^2 \right).\)
5. Compact steady harmonic-Ricci breathers

In this section we give an alternative proof on some results on compact steady harmonic-Ricci breathers that were proved in [9, 11].

**Definition 5.1.** A solution \((g(t), u(t))\) of the harmonic-Ricci flow is called a **harmonic-Ricci breather** if there exist \(t_1 < t_2\), a diffeomorphism \(\psi : M \to M\) and a constant \(\alpha > 0\) such that

\[
g(t_2) = \alpha \psi^* g(t_1), \quad u(t_2) = \psi^* u(t_1).
\]

The case \(\alpha < 1, \alpha = 1, \) and \(\alpha > 1,\) correspond to **shrinking**, **steady** and **expanding harmonic-Ricci breathers**.

**Theorem 5.2.** If \((g(t), u(t))\) is a solution of the harmonic-Ricci flow on a compact Riemannian manifold \(M\), then the lowest eigenvalue \(\mu_k(g(t), u(t))\) of the operator

\[
-4\Delta g + k \left( R_g - 2 |g^{ij}(t) \nabla u(t)|^2 g_{ij}(t) \right)
\]

is nondecreasing under the harmonic-Ricci flow. The monotonicity is strict unless \(g(t)\) is Ricci-flat and \(u(t)\) is constant.

**Proof.** The proof is similar to that given in [7]. For any \(t_1 < t_2\), suppose that

\[
\mu_k(g(t_2), u(t_2)) = \mathcal{F}_k(g(t_2), u(t_2), f_k(t_2))
\]

for some smooth function \(f_k(x)\). Being an initial value, \(f_k(x) = f_k(x, t)\) for some smooth function \(f_k(x, t)\) satisfying the evolution equation (4.4). The monotonicity formula (1.10) implies

\[
\mu_k(g(t_2), u(t_2)) \geq \mathcal{F}_k(g(t_1), u(t_1), f_k(t_1)) \geq \mu_k(g(t_1), u(t_1)).
\]

This completes the proof. \(\square\)

**Corollary 5.3.** On a compact Riemannian manifold, the lowest eigenvalues of

\[
-\Delta_g g(t) + \frac{1}{2} \left( R_g - 2 |g^{ij}(t) \nabla u(t)|^2 g_{ij}(t) \right)
\]

are nondecreasing under the harmonic-Ricci flow.

**Proof.** Since \(\mu_2(g(t), u(t))/4\) is the lowest eigenvalue of the above operator, the result immediately follows from Theorem 5.2. \(\square\)

**Corollary 5.4.** There is no compact steady harmonic-Ricci breather other than \((M, g(t))\) is Ricci-flat and \(u(t)\) is constant.

**Proof.** If \((g(t), u(t))\) is a steady harmonic-Ricci breather, then for \(t_1 < t_2\) given in the definition, we have

\[
\mu_k(g(t_1), u(t_1)) = \mu_k(g(t_2), u(t_2))
\]

hence, using Theorem 5.2 for any \(t \in [t_1, t_2]\) we must have

\[
\frac{d}{dt} \mu_k(g(t), u(t)) \equiv 0.
\]

Thus \((M, g(t))\) is Ricci-flat and \(u(t)\) is constant. \(\square\)
6. Compact expanding harmonic-Ricci breathers

Inspired by [7], we define a new functional

$$\odot_2^2 (M) \times C^\infty(M) \times C^\infty(\mathbb{R}) \times C^\infty(M) \longrightarrow \mathbb{R}, \quad (g, u, \tau, f) \longmapsto W_+(g, u, \tau, f),$$

where \((\tau = \tau(t), t \in \mathbb{R})\)

\[(6.1) \quad W_+(g, u, \tau, f) := \tau^2 \int_M \left( R_g + \frac{n}{2\tau} + \Delta_g f - 2 |\nabla u|^2_g \right) e^{-f} dV_g.
\]

Similarly, we define a family of functionals

\[(6.2) \quad W_{+,k}(g, u, \tau, f) := \tau^2 \int_M \left[ k \left( R_g + \frac{n}{2\tau} \right) + \Delta_g f - 2k |\nabla u|^2_g \right] e^{-f} dV_g.
\]

It’s clear that \(W_{+,1}(g, u, \tau, f) = W_+(g, u, \tau, f)\).

**Lemma 6.1.** One has

\[
\begin{align*}
W_+(g, u, \tau, f) &= \tau^2 F(g, u, f) + \frac{n}{2\tau} \int_M e^{-f} dV_g, \\
W_{+,k}(g, u, \tau, f) &= \tau^2 F_k(g, u, f) + \frac{k n}{2\tau} \int_M e^{-f} dV_g, \\
W_{+,k}(g, u, \tau, f) &= W_+(g, u, \tau, f) + (k - 1) \left( \tau^2 E(g, u, f) + \frac{n}{2\tau} \int_M e^{-f} dV_g \right).
\end{align*}
\]

**Proof.** Since \(\Delta (e^{-f}) = \left( -\Delta f + |\nabla f|^2 \right) e^{-f}\), it follows that

\[
\begin{align*}
W_+(g, u, \tau, f) &= \tau^2 F_0(g, u, f) - \tau^2 F(g, u, f) \\
&= \frac{n}{2\tau} \int_M e^{-f} dV_g + \tau^2 \int_M \left( \Delta_g f - |\nabla f|^2_g \right) e^{-f} dV_g \\
&= \frac{n}{2\tau} \int_M e^{-f} dV_g + \tau^2 \int_M \Delta_g \left( e^{-f} \right) dV_g = \frac{n}{2\tau} \int_M e^{-f} dV_g.
\end{align*}
\]

Similarly, we can prove the rest two relations. \(\Box\)

**Theorem 6.2.** Under the following coupled system

\[
\begin{align*}
\frac{\partial}{\partial t} g(t) &= -2\text{Ric}_{g(t)} + 4du(t) \otimes du(t) - 2g(t) \nabla^2 f(t), \\
\frac{\partial}{\partial t} u(t) &= \Delta_{g(t)} u(t) - \langle du(t), df(t) \rangle_{g(t)}, \\
\frac{\partial}{\partial t} f(t) &= -\Delta_{g(t)} f(t) - R_{g(t)} + 2 \left| g(t) \nabla u(t) \right|_{g(t)}^2, \\
\frac{d}{dt} \tau(t) &= 1,
\end{align*}
\]
the first variation formula for $W_+(g(t), u(t), \tau(t), f(t))$ is

\begin{align}
(6.3) \quad \frac{d}{dt} W_+(g(t), u(t), \tau(t), f(t)) &= 2\tau(t)^2 \int_M \left| S_{g(t), u(t)} + g(t) \nabla^2 f(t) + \frac{1}{2\tau(t)} g(t) \right|^2 \left| g(t) \right| e^{-f(t)} dV_{g(t)} \\
&+ 4\tau(t)^2 \int_M \left| \Delta_{g(t)} u(t) - \langle du(t), df(t) \rangle_{g(t)} \right|^2 \left| g(t) \right| e^{-f(t)} dV_{g(t)},
\end{align}

and the first variation formula for $W_{+,k}(g(t), u(t), \tau(t), f(t))$ is

\begin{align}
(6.4) \quad \frac{d}{dt} W_{+,k}(g(t), u(t), \tau(t), f(t)) &= 2\tau(t)^2 \int_M \left| S_{g(t), u(t)} + g(t) \nabla^2 f(t) + \frac{1}{2\tau(t)} g(t) \right|^2 \left| g(t) \right| e^{-f(t)} dV_{g(t)} \\
&+ 2(k - 1)\tau(t)^2 \int_M \left| S_{g(t), u(t)} + \frac{1}{2\tau(t)} g(t) \right|^2 \left| g(t) \right| e^{-f(t)} dV_{g(t)} \\
&+ 4\tau(t)^2 \int_M \left| \Delta_{g(t)} u(t) - \langle du(t), df(t) \rangle_{g(t)} \right|^2 \left| g(t) \right| e^{-f(t)} dV_{g(t)} \\
&+ 4(k - 1)\tau(t)^2 \int_M \left| \Delta_{g(t)} u(t) \right|^2 \left| g(t) \right| e^{-f(t)} dV_{g(t)}.
\end{align}

Proof. Under the above coupled system, we first observe that

\begin{align}
(6.5) \quad \frac{d}{dt} \left( \int_M e^{-f(t)} dV_{g(t)} \right) = 0.
\end{align}

In fact, from $\frac{\partial}{\partial \tau} dV_{g(t)} = \left( -S_{g(t), u(t)} - \Delta_{g(t)} f(t) \right) dV_{g(t)}$ we obtain

\begin{align*}
\frac{d}{dt} \left( \int_M e^{-f(t)} dV_{g(t)} \right) &= \int_M \left( -\frac{\partial}{\partial \tau} f(t) \cdot dV_{g(t)} + \frac{\partial}{\partial \tau} dV_{g(t)} \right) e^{-f(t)} \\
&= \int_M \left[ \Delta_{g(t)} f(t) + S_{g(t), u(t)} - S_{g(t), u(t)} - \Delta_{g(t)} f(t) \right] e^{-f(t)} dV_{g(t)} \\
&= 0.
\end{align*}
Lemma 6.1 and the identity (6.5) implies
\[
\frac{d}{dt} W_+(g(t), u(t), \tau(t), f(t)) = \tau(t)^2 \frac{d}{dt} F(g(t), u(t), f(t)) + 2\tau(t) F(g(t), u(t), f(t)) + \frac{n}{2} \int_M e^{-f(t)} dV_{g(t)}
\]
which is (6.3). Using Lemma 6.1 and the identity (6.5) implies (6.4).

Remark 6.3. Under the following coupled system
\[
\frac{\partial}{\partial t} g(t) = -2\text{Ric}_{g(t)} + 4du(t) \otimes du(t), \quad \frac{\partial}{\partial t} u(t) = \Delta_{g(t)} u(t), \quad \frac{\partial}{\partial t} f(t) = -\Delta_{g(t)} f(t) + \left( g(t) \nabla f(t) \right)^2 - R_{g(t)} + 2 \left( g(t) \nabla u(t) \right)^2,
\]
the same formulas (6.3) and (6.4) hold for $W_+$ and $W_{+,k}$.

Define
\[
\mu_+(g, u, \tau) := \inf \left\{ W_+(g, u, \tau, f) \middle| f \in C^\infty(M), \int_M e^{-f} dV_g = 1 \right\}.
\]

Lemma 6.4. For any $\alpha > 0$, one has
\[
\mu_+(\alpha g, u, \alpha \tau) = \alpha \mu_+(g, u, \tau).
\]

Proof. If we set $\widehat{\tau} := \alpha \tau$, then $R_{\widehat{\tau}} = \alpha^{-1} R_g$, $\Delta_{\widehat{\tau}} f = \alpha^{-1} \Delta_g f$, and $\left| \nabla_{\widehat{\tau}} u \right|^2 = \alpha^{-1} \left| g \nabla u \right|^2$. Hence
\[
W_+(\widehat{g}, u, \alpha \tau, f) = \alpha^2 \tau^2 \int_M \left( R_{\widehat{\tau}} + \frac{n}{2\alpha \tau} + \Delta_{\widehat{\tau}} f - 2 \left| \nabla_{\widehat{\tau}} u \right|^2 \right) e^{-f} dV_{\widehat{\tau}}
\]
which implies $f \mapsto f - \frac{n}{2} \ln \alpha$ is one-to-one and onto, by taking the infimum we derive
\[
\mu_+(\alpha g, u, \alpha \tau) = \alpha \mu_+(g, u, \tau).
\]
\[
\square
\]
Definition 6.5. A solution \((g(t), u(t))\) of the harmonic-Ricci flow is called a \textbf{harmonic-Ricci soliton} if there exists an one-parameter family of diffeomorphisms \(\psi_t : M \to M\), satisfying \(\psi_0 = id_M\), and a positive scaling function \(\alpha(t)\) such that

\[ g(t) = \alpha(t) \psi_t^* g(0), \quad u(t) = \psi_t^* u(0). \]

The case \(\frac{\partial}{\partial t} \alpha(t) = \dot{\alpha} < 0\), \(\dot{\alpha} = 0\), and \(\dot{\alpha} > 0\) correspond to \textbf{shrinking}, \textbf{steady}, and \textbf{expanding harmonic-Ricci solitons}, respectively. If the diffeomorphisms \(\psi_t\) are generated by a (possibly time-dependent) vector field \(X(t)\) that is the gradient of some function \(f(t)\) on \(M\), then the soliton is called \textbf{gradient harmonic-Ricci soliton} and \(f\) is called the \textbf{potential} of the harmonic-Ricci soliton.

In [11], Müller showed that if \((g(t), u(t))\) is a gradient harmonic-Ricci soliton with potential \(f\), then

\[ 0 = \text{Ric}_g(t) - 2 du(t) \otimes du(t) + g(t) \nabla^2 f(t) + cg(t), \]

\[ 0 = \Delta_g(t) u(t) - \left< g(t) \nabla u(t), g(t) \nabla f(t) \right>_{g(t)} \]

for some constant \(c\).

Corollary 6.6. \textit{There is no expanding breather on compact Riemannian manifolds other than expanding gradient harmonic-Ricci solitons.}

\textbf{Proof.} The proof is similar to that given in [7]. Suppose there is an expanding breather on a compact Riemannian manifold \(M\), then by definition we have

\[ g(t_2) = \alpha \Phi^* g(t_1), \quad u(t_2) = \Phi^* u(t_1) \]

for some \(t_1 < t_2\), where \(\Phi\) is a diffeomorphism and the constant \(\alpha > 1\). Let \(f_+(x)\) is a smooth function where \(\mathcal{W}_+(g(t_2), u(t_2), \tau(t_2), f(t_2))\) attains its minimum. Then there exists a smooth function \(f_+(x, t) : M \times [t_1, t_2] \to \mathbb{R}\) with initial value \(f_+(x, t_2) = f_+(x)\) and satisfies the coupled system appeared in 6.3. Define a linear function

\[ \tau : [t_1, t_2] \to (0, +\infty), \quad \tau(t_2) = T + t_2 \]

where \(T\) is a constant. By the monotonicity formula, we have

\[ \mu_+(g(t_2), u(t_2), \tau(t_2)) = \mathcal{W}_+(g(t_2), u(t_2), \tau(t_2), f_+(t_2)) \]

\[ \geq \mathcal{W}_+(g(t_1), u(t_1), \tau(t_1), f_+(t_1)) \]

\[ \geq \mu_+(g(t_1), u(t_1), \tau(t_1)). \]

Lemma [6.3] and the diffeomorphic invariant property of the functionals shows

\[ \mu_+(g(t_1), u(t_1), \tau(t_1)) \leq \alpha \mu_+(g(t_1), u(t_1), \tau(t_1)) \]

which yields

\[ \mu_+(g(t_1), u(t_1), \tau(t_1)) \geq 0 \]

since \(\alpha > 1\).
If we impose an additional condition \( \tau(t_2) = \alpha \tau(t_1) \) and \( \tau(t_1) = T + t_1 \), we have
\[
\tau(t) = \frac{(t - t_1) - (t - t_2)}{\alpha - 1}, \quad T = \frac{t_2 - \alpha t_1}{\alpha - 1}.
\]
Then
\[
\frac{\tau(t_2)^{\frac{n}{2}}}{V_{g(t_2)}} = \left[ \frac{\alpha(t_2-t_1)}{\alpha-1} \right]^{\frac{n}{2}} \frac{\tau(t_1)^{\frac{n}{2}}}{V_{g(t_1)}}.
\]
The mean value theorem tells us that there exists a time \( \bar{t} \in [t_1, t_2] \) with
\[
0 = \left. \frac{d}{dt} \right|_{t=\bar{t}} \log \frac{\tau(t)^{\frac{n}{2}}}{V_{g(t)}}
\]
\[
= \left. \frac{V_{g(\bar{t})}}{\tau(\bar{t})^{\frac{n}{2}}} \frac{n \tau(\bar{t})^{\frac{n}{2}} - n \tau(\bar{t}) \frac{d}{dt} V_{g(\bar{t})}}{V_{g(\bar{t})}} \right|_{t=\bar{t}}
\]
\[
= \frac{n}{2 \tau(\bar{t})} - \frac{1}{V_{g(\bar{t})}} \frac{\partial}{\partial t} |_{t=\bar{t}} V_{g(\bar{t})}.
\]
From the evolution equation for the volume element \( dV_{g(t)} \) we have
\[
\frac{d}{dt} V_{g(t)} = \int_M \frac{\partial}{\partial t} V_{g(t)} = \int_M (-S_{g(t),u(t)} - \Delta_{g(t)} f(t)) dV_{g(t)} = - \int_M S_{g(t),u(t)} dV_{g(t)}.
\]
Putting those together yields
\[
0 = \frac{n}{2 \tau(\bar{t})} + \frac{1}{V_{g(\bar{t})}} \int_M S_{g(\bar{t}),u(\bar{t})} dV_{g(\bar{t})} = \frac{1}{V_{g(\bar{t})}} \int_M \left( S_{g(\bar{t}),u(\bar{t})} + \frac{n}{2 \tau(\bar{t})} \right) dV_{g(\bar{t})}.
\]
If we set \( \bar{t} = \log V_{g(\bar{t})} \) then
\[
0 = W_+(g(\bar{t}), u(\bar{t}), \tau(\bar{t}), \bar{t}) \geq \mu_+(g(\bar{t}), u(\bar{t}), \tau(\bar{t})).
\]
By the monotonicity of \( \mu_+ \) we obtain
\[
0 \leq \mu_+(g(t_1), u(t_1), \tau(t_1)) \leq \mu_+(g(\bar{t}), u(\bar{t}), \tau(\bar{t})) \leq 0.
\]
Hence \( \mu_+(g(t_1), u(t_1), \tau(t_1)) = \mu_+(g(t_2), u(t_2), \tau(t_2)) = 0 \) and \( W_+ = 0 \) on the interval \([t_1, t_2] \). This indicates that the first variation of \( W_+ \) must vanish. So the expanding breather is a gradient soliton, i.e.,
\[
S_{g(t),u(t)} + g(t) \nabla^2 f(t) + \frac{1}{2 \tau(t)} g(t) = 0.
\]
Moreover, in this case \( \Delta_{g(t)} u(t) = \langle du(t), df(t) \rangle_{g(t)} \).
\( \square \)

As \( (6.7) \), we define
\[
(6.8)
\mu_{+,k}(g, u, \tau) := \inf \left\{ W_{+,k}(g, u, \tau, f) \big| f \in C^{+\infty}(M), \int_M e^{-f} dV_g = 1 \right\}
\]
As Lemma [6.4] we still have
\[
(6.9)
\mu_{+,k}(\alpha g, u, \alpha \tau) = \alpha \mu_{+,k}(g, u, \tau).
\]
Corollary 6.7. If \((g(t), u(t))\) is an expanding harmonic-Ricci breathers on compact Riemannian manifolds, then \(M\) is an Einstein manifold and \(u(t)\) is constant.

Proof. Using the same method in Corollary 6.6 and \(\mu_{+, k}\), we can show that the first variation of \(W_{+, k}\) must vanish. Hence, from (6.4) one has
\[
\begin{align*}
S_{g(t), u(t)} + \frac{1}{2\tau(t)} g(t) &= 0, \\
S_{g(t), u(t)} + \frac{1}{2\tau(t)} g(t) &= 0, \\
\Delta_{g(t)} u(t) &= \langle du(t), df(t) \rangle_{g(t)}, \\
\Delta_{g(t)} u(t) &= 0.
\end{align*}
\]
The above four equations can be reduced to a coupled equation
\[
S_{g(t), u(t)} + \frac{1}{2\tau(t)} g(t) = 0 = \Delta_{g(t)} u(t)
\]
which indicates that \(u(t)\) is a constant and \(\text{Ric}_{g(t)} = -\frac{1}{2\tau(t)} g(t)\). \(\square\)

7. Eigenvalues of the Laplacian under the harmonic-Ricci flow

In this section we consider the eigenvalues of the Laplacian \(\Delta_{g(t)}\) under the harmonic-Ricci flow
\[
\begin{align*}
\frac{\partial}{\partial t} g(t) &= -2\text{Ric}_{g(t)} + 4du(t) \otimes du(t), \\
\frac{\partial}{\partial t} u(t) &= \Delta_{g(t)} u(t).
\end{align*}
\]
Suppose that \(\lambda(t)\), which is a function of time \(t\) only, is an eigenvalue of the Laplacian \(\Delta_{g(t)}\) with an eigenfunction \(f(t) = f(x, t)\), i.e.,
\[
-\Delta_{g(t)} f(t) = \lambda(t) f(t).
\]
Taking the derivative with respect to \(t\), we get
\[
-\left(\frac{\partial}{\partial t} \Delta_{g(t)}\right) f(t) - \Delta_{g(t)} \left(\frac{\partial}{\partial t} f(t)\right) = \left(\frac{d}{dt} \lambda(t)\right) f(t) + \lambda(t) \frac{\partial}{\partial t} f(t).
\]
Integrating above equation with \(f\) yields
\[
-\int_M f(t) \left(\frac{\partial}{\partial t} \Delta_{g(t)}\right) f(t) dV_{g(t)} - \int_M f(t) \Delta_{g(t)} \left(\frac{\partial}{\partial t} f(t)\right) dV_{g(t)} = \frac{d}{dt} \lambda(t) \cdot \int_M f(t)^2 dV_{g(t)} + \lambda(t) \int_M f(t) \frac{\partial}{\partial t} f(t) dV_{g(t)}.
\]
Since
\[
-\int_M f(t) \Delta_{g(t)} \left(\frac{\partial}{\partial t} f(t)\right) dV_{g(t)} = -\int_M \Delta_{g(t)} f(t) \cdot \frac{\partial}{\partial t} f(t) dV_{g(t)} = \lambda(t) \int_M f(t) \frac{\partial}{\partial t} f(t) dV_{g(t)},
\]

it follows that

\[ (7.4) \quad \frac{d}{dt} \chi(t) \cdot \int_M f(t)^2 dV_{g(t)} = - \int_M f(t) \left( \frac{\partial}{\partial t} \Delta_g(t) \right) f(t) dV_{g(t)}. \]

If we set \( v_{ij} = -2R_{ij} + 4\partial_i u \partial_j u \), then

\[ \frac{\partial}{\partial t} \Gamma^k_{ij} = \frac{1}{2} g_{kl} \left( \partial_i v^l_{ij} + \partial_j v^l_{ij} - \partial^l v_{ij} \right). \]

Multiplying with \( g^{ij} \) on both sides, we obtain

\[ g^{ij} \frac{\partial}{\partial t} \Gamma^k_{ij} = \frac{1}{2} g^{kl} (2\nabla^i v^l_{ij} - \nabla^i (g^{ij} v_{ij})) = g^{kl} \nabla^i v^l_{ij} + \nabla^k S \]

\[ = g^{kl} \nabla^i (-2R_{il} + 4\nabla_i u \nabla_l u) + \nabla^k \left( R - 2|\nabla u|^2 \right) \]

\[ = -\nabla^k R + 4\Delta u \cdot \nabla^k u + 4\nabla_i u \cdot \nabla^i \nabla^k u + \nabla^k R - 4\nabla^k \nabla^i u \cdot \nabla_i u \]

\[ = 4\Delta u \cdot \nabla^k u. \]

Therefore,

\[ \frac{\partial}{\partial t} (\Delta f) = \frac{\partial}{\partial t} (g^{ij} \nabla_i \nabla_j f) \]

\[ = \left( \frac{\partial}{\partial t} g^{ij} \right) \nabla_i \nabla_j f + g^{ij} \left[ \partial_i \partial_j \frac{\partial f}{\partial t} - \left( \frac{\partial}{\partial t} \Gamma^k_{ij} \right) \partial_k f - \Gamma^k_{ij} \partial_k \frac{\partial f}{\partial t} \right] \]

\[ = \left( \frac{\partial}{\partial t} g^{ij} \right) \nabla_i \nabla_j f + \nabla \left( \frac{\partial}{\partial t} f \right) - g^{ij} \left( \frac{\partial}{\partial t} \Gamma^k_{ij} \right) \nabla_k f \]

\[ = (2R_{ij} - 4\nabla_i u \nabla_j u) \nabla^i \nabla^j f - 4\Delta u \cdot \nabla^k u \nabla_k f + \nabla \left( \frac{\partial}{\partial t} f \right). \]

Plugging it into (7.4) we derive

\[ \frac{d}{dt} \chi(t) \cdot \int_M f(t)^2 dV_{g(t)} = -2 \int_M R_{ij} \nabla^i \nabla^j f dV + 4 \int_M f \nabla^i u \nabla^j u \nabla_i \nabla_j f dV \]

\[ + 4 \int_M f \Delta u \cdot \nabla^k u \nabla_k f dV. \]

The first term can be rewritten as

\[ -2 \int_M R_{ij} \nabla^i \nabla^j f dV = \int_M \nabla^i (2f R_{ij}) \nabla^j f dV \]

\[ = 2 \int_M (\nabla^i f \cdot R_{ij} + f \cdot \nabla^i R_{ij}) \nabla^j f dV \]

\[ = 2 \int_M R_{ij} \nabla^i f \nabla^j f dV + \int_M f \nabla_j R \nabla^j f dV \]

\[ = 2 \int_M R_{ij} \nabla^i f \nabla^j f dV - \int_M R \nabla_j (f \nabla^j f) dV \]

\[ = \lambda \int_R f^2 dV - \int_M R |\nabla f|^2 dV + 2 \int_M R_{ij} \nabla^i f \nabla^j f dV. \]
Hence
\[
\left( \frac{d}{dt} \lambda(t) \right) \cdot \int_M f(t)^2 dV_{g(t)} = 
\lambda(t) \int_M R_{g(t)} f(t)^2 dV_{g(t)} - \int_M R_{g(t)} \left| g(t) \nabla f(t) \right|^2 dV_{g(t)} \\
+ 2 \int_M R_{ij} \nabla^i u \nabla^j f \nabla^i u \nabla^j f dV \\
+ 4 \int_M f \Delta u \cdot \nabla^k u \nabla^k f dV.
\]

On the other hand,
\[
\int_M f \nabla^i u \nabla^j u \nabla^i \nabla^j f dV = - \int_M \nabla^i (f \nabla^i u \nabla^j u) \nabla^j f dV \\
= - \int_M (\nabla^i f \nabla^i u \nabla^j u + f \Delta u \nabla^j u) \nabla^j f dV \\
= - \int_M f \Delta u \langle \nabla u, \nabla f \rangle dV - \int_M \nabla^i u \nabla^j u \nabla^i \nabla^j f dV \\
- \int_M f \nabla^i u \nabla^j f \nabla^i \nabla^j u dV
\]
and therefore
\[
\left( \frac{d}{dt} \lambda(t) \right) \int_M f(t)^2 dV = \lambda(t) \int_M R_{g(t)} f(t)^2 dV_{g(t)} \\
- \int_M R_{g(t)} \left| g(t) \nabla f(t) \right|^2 dV_{g(t)} \\
+ 2 \int_M S_{ij} \nabla^i f \nabla^j f dV - 4 \int_M f \nabla^i u \nabla^j f \nabla^i \nabla^j u dV.
\]
The last term in above can be simplified as follows:
\[
- \int_M f \nabla^i u \nabla^j f \nabla^i \nabla^j u dV = \int_M \nabla^j (f \nabla^i u \nabla^j f) \nabla^i u dV \\
= \int_M (\nabla^j f \nabla^i u \nabla^j f + f \nabla^j \nabla^i u \nabla^j f + f \nabla^i u \Delta f) \nabla^i u dV \\
= \int_M |\nabla u|^2 |\nabla f|^2 dV + \int_M f \Delta f |\nabla u|^2 dV + \int_M f \nabla^i u \nabla^j f \nabla^i \nabla^j u dV
\]
consequently,
\[
-2 \int_M f \nabla^i u \nabla^j f \nabla^i \nabla^j u dV = \int_M |\nabla u|^2 |\nabla f|^2 dV - \lambda \int_M f^2 |\nabla u|^2 dV.
\]
Therefore we derive the following

**Theorem 7.1.** If \((g(t), u(t))\) is a solution of the harmonic-Ricci flow on a compact Riemannian manifold \(M\) and \(\lambda(t)\) denotes the eigenvalue of the
Let $\Delta_g$, then
\[
\frac{d}{dt} \lambda(t) \cdot \int_M f(t)^2 dV_g(t) = \lambda(t) \int_M S_{g(t),u(t)} f(t)^2 dV_g(t) - \int_M S_{g(t),u(t)} \left\langle g(t) \nabla f(t), f(t)^2 \right\rangle dV_g(t) + 2 \int_M \left\langle S_{g(t),u(t)}, df(t) \otimes df(t) \right\rangle dV_g(t).
\] (7.5)

We set
\[
S_{\min}(0) := \min_{x \in M} S(x,0).
\] (7.6)

**Theorem 7.2.** Let $(g(t),u(t))_{t \in [0,T]}$ be a solution of the harmonic-Ricci flow on a compact Riemannian manifold $M$ and $\lambda(t)$ denote the eigenvalue of the Laplacian $\Delta_g(t)$. Suppose that $S_{g(t),u(t)} - \alpha S_{g(t),u(t)} g(t) \geq 0$ along the harmonic-Ricci flow for some $\alpha \geq \frac{1}{2}$.

1. If $S_{\min}(0) \geq 0$, then $\lambda(t)$ is nondecreasing along the harmonic-Ricci flow for any $t \in [0,T]$.
2. If $S_{\min}(0) > 0$, then the quantity
\[
\left(1 - \frac{2}{n} S_{\min}(0)t\right)^{n\alpha} \lambda(t)
\]

is nondecreasing along the harmonic-Ricci flow for $T \leq \frac{n}{2S_{\min}(0)}$.
3. If $S_{\min}(0) < 0$, then the quantity
\[
\left(1 - \frac{2}{n} S_{\min}(0)t\right)^{n\alpha} \lambda(t)
\]

is nondecreasing along the harmonic-Ricci flow for any $t \in [0,T]$.

**Proof.** By Theorem 7.1 we have
\[
\frac{d}{dt} \lambda(t) \geq \left( \frac{\int_M S_{g(t),u(t)} f(t)^2 dV_g(t)}{\int_M f(t)^2 dV_g(t)} \right) \lambda(t) + (2\alpha - 1) \left( \frac{\int_M S_{g(t),u(t)} \left\langle g(t) \nabla f(t), f(t)^2 \right\rangle^2}{\int_M f(t)^2 dV_g(t)} \right).
\]

By definition we have $-f(t) \Delta_g(t) = \lambda(t)f(t)$. Taking the integration on both sides yields that $\lambda(t) \geq 0$. Since
\[
\frac{\partial}{\partial t} S_{g(t),u(t)} = \Delta_g(t) S_{g(t),u(t)} + 2 \left| S_{g(t),u(t)} \right|_{g(t)}^2 + 4 \left| \Delta g(u(t)) \right|_{g(t)}^2
\]

and $\left| S_{g(t),u(t)} \right| \geq \frac{1}{n} S_{g(t),u(t)}^2$, it follows that
\[
\frac{\partial}{\partial t} S_{g(t),u(t)} \geq \Delta_g(t) S_{g(t),u(t)} + \frac{2}{n} S_{g(t),u(t)}^2.
\]
The corresponding ODE
\[ \frac{d}{dt} a(t) = \frac{2}{n} a(t)^2, \quad a(t) = S_{\text{min}}(0) \]
has the solution
\[ a(t) = \frac{S_{\text{min}}(0)}{1 - \frac{2}{n} S_{\text{min}}(0) t} \]
Then the maximum principle implies \( S_{g(t),u(t)} \geq a(t) \) and hence, using the assumption that \( 2\alpha - 1 \geq 0 \),
\[ \frac{d}{dt} \lambda(t) \geq a(t) \lambda(t) + (2\alpha - 1) a(t) \frac{\int_M |g(t)^{\frac{1}{2}} \nabla f(t)|^2 dV_{g(t)}}{\int_M f(t)^2 dV_{g(t)}}. \]
By integration by parts, we note that
\[ \int_M |\nabla f|^2 dV = - \int_M f \cdot \Delta f dV = \lambda \int_M f^2 dV \]
which indicates
\[ \frac{d}{dt} \lambda(t) \geq a(t) \lambda(t) + (2\alpha - 1) a(t) \lambda = 2\alpha a(t) \lambda(t) \]
and
\[ \frac{d}{dt} \left( \lambda(t) \cdot e^{-2\alpha \int_0^t a(\tau) d\tau} \right) \geq 0. \]
Plugging the expression into above yields the desired result. If \( S_{\text{min}}(0) \geq 0 \), by the nonnegativity of \( S_{g(t)} \) preserved along the harmonic-Ricci flow, we conclude that \( \frac{d}{dt} \lambda(t) \geq 0 \). \( \square \)

**Corollary 7.3.** Let \((g(t), u(t))_{t \in [0,T]}\) be a solution of the harmonic-Ricci flow on a compact Riemannian surface \( \Sigma \) and \( \lambda(t) \) denote the eigenvalue of the Laplacian \( \Delta_{g(t)} \).

(1) Suppose that \( \text{Ric}_{g(t)} \leq \epsilon du(t) \otimes du(t) \) where
\[ \epsilon \leq \frac{1}{1 - 2\alpha}, \quad \alpha > \frac{1}{2} \]
(1-1) If \( S_{\text{min}}(0) \geq 0 \), then \( \lambda(t) \) is nondecreasing along the harmonic-Ricci flow for any \( t \in [0,T] \).
(1-2) If \( S_{\text{min}}(0) > 0 \), then the quantity
\[ (1 - S_{\text{min}}(0) t)^{2\alpha} \lambda(t) \]
is nondecreasing along the harmonic-Ricci flow for \( T \leq \frac{1}{S_{\text{min}}(0)} \).
(3) If \( S_{\text{min}}(0) < 0 \), then the quantity
\[ (1 - S_{\text{min}}(0) t)^{2\alpha} \lambda(t) \]
is nondecreasing along the harmonic-Ricci flow for any \( t \in [0,T] \).
(2) Suppose that

$$
|g(t)\nabla u(t)|^2_{g(t)} \geq 2\alpha t \otimes du(t).
$$

(1-1) If $S_{\min}(0) \geq 0$, then $\lambda(t)$ is nondecreasing along the harmonic-Ricci flow for any $t \in [0,T]$.

(1-2) If $S_{\min}(0) > 0$, then the quantity

$$(1 - \frac{1}{S_{\min}(0)t}) \lambda(t)$$

is nondecreasing along the harmonic-Ricci flow for $T \leq \frac{1}{S_{\min}(0)}$.

(3) If $S_{\min}(0) < 0$, then the quantity

$$(1 - \frac{1}{S_{\min}(0)t}) \lambda(t)$$

is nondecreasing along the harmonic-Ricci flow for any $t \in [0,T]$.

Proof. In the case of surface, we have $R_{ij} = \frac{1}{2} g_{ij}$. Then

$$T_{ij} := S_{ij} - \alpha S g_{ij} = \frac{1}{2} g_{ij} - 2\nabla_i u \nabla_j u - \alpha \left( R - 2|\nabla u|^2 \right) g_{ij}$$

$$= \left( \frac{1}{2} - \alpha \right) R g_{ij} - 2\nabla_i u \nabla_j u + 2\alpha |\nabla u|^2 g_{ij}.$$ 

For any vector $V = (V^i)$, we calculate

$$T_{ij} V^i V^j = \left( \frac{1}{2} - \alpha \right) R|V|^2 - 2|\nabla_i u V^i|^2 + 2\alpha |\nabla u|^2 |V|^2 \geq 0.$$ 

If $R_{ij} \leq \epsilon \nabla_i u \nabla_j u$, then $T_{ij} V^i V^j = \left( \frac{1}{2} - \alpha \right) \epsilon - 2 + 2\alpha |\nabla u|^2 |V|^2 \geq 0$.

For the second case, we note that

$$T_{ij} V^i V^j = R_{ij} V^i V^j - 2\nabla_i u V^i \nabla_j u V^j - \frac{R}{2} |V|^2 + |\nabla u|^2 |V|^2$$

$$\geq R_{ij} V^i V^j - |\nabla u|^2 |V|^2 - \frac{R}{2} |V|^2 + |\nabla u|^2 |V|^2 = 0.$$ 

Hence, the corresponding results follow by Theorem 7.2.

When we consider the Ricci flow, we have the following two results derived from Corollary 7.3.

**Corollary 7.4.** Let $(g(t))_{t \in [0,T]}$ be a solution of the Ricci flow on a compact Riemannian surface $\Sigma$ and $\lambda(t)$ denote the eigenvalue of the Laplacian $\Delta g(t)$.

1. If $R_{\min}(0) \geq 0$, then $\lambda(t)$ is nondecreasing along the Ricci flow for any $t \in [0,T]$.
2. If $R_{\min}(0) > 0$, then the quantity $(1 - R_{\min}(0)t)\lambda(t)$ is nondecreasing along the Ricci flow for $T \leq \frac{1}{R_{\min}(0)}$. 


(3) If $R_{\text{min}}(0) < 0$, then the quantity $(1 - R_{\text{min}}(0)t)\lambda(t)$ is nondecreasing along the Ricci flow for any $t \in [0, T]$.

**Remark 7.5.** Let $(g(t))_{t \in [0,T]}$ be a solution of the Ricci flow on a compact Riemannian surface $\Sigma$ with nonnegative scalar curvature and $\lambda(t)$ denote the eigenvalue of the Laplacian $\Delta_g(t)$. Then $\lambda(t)$ is nondecreasing along the Ricci flow for $t \in [0, T]$.

8. **Eigenvalues of the Laplacian-type under the harmonic-Ricci flow**

Recall

\[ \mu(g, u) = \mu_1(g, u) = \inf \left\{ F(g, u, f) \mid \int_M e^{-f} dV_g = 1 \right\}. \]

We showed that $\mu(g, u)$ is the smallest eigenvalue of the operator $-4\Delta_g + R_g - 2|\nabla u|_g^2$. Inspired by [3, 4], we define a Laplacian-type operators associated with quantities $g, u, c$:

\[ \Delta_{g,u,c} := -\Delta_g + c \left( R_g - 2|\nabla u|_g^2 \right), \]

\[ \Delta_{g,u} := \Delta_{g,u,\frac{1}{2}} = -\Delta_g + \frac{1}{2} \left( R_g - 2|\nabla u|_g^2 \right). \]

Then $\mu(g, u)$ is the smallest eigenvalue of the operator $4\Delta_{g,u,\frac{1}{2}}$.

To the operator $\Delta_{g,u}$ we associate a functional

\[ C^\infty(M) \to \mathbb{R}, \quad f \mapsto \lambda_{g,u}(f) := \int_M f \cdot \Delta_{g,u} f \cdot dV_g. \]

When $f$ is an eigenfunction of the operator $\Delta_{g,u}$ with the eigenvalue $\lambda$, i.e., $\Delta_{g,u}f = \lambda f$ and normalized by $\int_M f^2 dV_g = 1$, we obtain

\[ \lambda_{g,u}(f) = \lambda. \]

Next lemma will deal with the evolution equation for $\lambda(f(t))$ where $f(t)$ is an eigenvalue of $\Delta_{g(t),u(t)}$ and the couple $(g(t), u(t))$ satisfies the harmonic-Ricci flow. Set

\[ v_{ij} := -2S_{ij} = -2R_{ij} + 4\partial_i u \cdot \partial_j u, \quad v := g^{ij} v_{ij}. \]

The obtained symmetric tensor field is denoted by $V_{g(t),u(t)} = (v_{ij})$.

**Lemma 8.1.** Suppose that $(g(t), u(t))$ is a solution of the harmonic-Ricci flow on a compact Riemannian manifold $M$ and $f(t)$ is an eigenvalue of $\Delta_{g(t),u(t)}$, i.e., $\Delta_{g(t),u(t)}f(t) = \lambda(t)f(t)$ (where $\lambda(t)$ is only a function of time ...
where the metric \( t \) only), with the normalized condition \( \int_M f(t)^2 dV_{g(t)} = 1 \). Then we have

\[
(8.6) \quad \frac{d}{dt} \lambda_{g(t),u(t)}(f(t)) = \int_M \left[ \langle \nabla g(t,u(t), \nabla^2 g(t) \rangle_{g(t)} + \frac{1}{4} \left( \frac{\partial}{\partial t} R_{g(t)} \right) f(t) \right] f(t) dV_{g(t)} \\
+ \int_M \left( \nabla^i v_{ik} - \frac{1}{2} \nabla_k v \right) \nabla^k f(t) \cdot f(t) dV_{g(t)} \\
- \int_M \left( \frac{\partial}{\partial t} \left| g(t) \nabla u(t) \right|_{g(t)}^2 \right) f^2(t) dV_{g(t)}.
\]

Before proving the lemma, we recall a formula that is an immediate consequence of the evolution equation:

\[
(8.7) \quad \frac{\partial}{\partial t} \left( \Delta_{g(t),f} \right) = -g^{ip}g^{jq}v_{pq} \nabla_i \nabla_j f - g^{ij}g^{kl} \nabla_{i} v_{jl} \nabla_k f \\
+ \frac{1}{2} \left( \langle g(t) \nabla v_{g(t)}, g(t) \nabla f(t) \rangle_{g(t)} \right)
\]

where the metric \( g(t) \) evolves by \( \frac{\partial}{\partial t} g_{ij} = v_{ij} \).

**Proof.** Using (8.7) and integration by parts, we get

\[
\frac{d}{dt} \lambda_{g(t),u(t)}(f(t)) = \frac{\partial}{\partial t} \left[ \int_M \left[ -\Delta_{g(t),f} + \left( \frac{R_{g(t)}}{2} - \left| g(t) \nabla u(t) \right|_{g(t)}^2 \right) f(t) \right] f(t) dV_{g(t)} \\
+ \int_M \left[ -\Delta_{g(t)} f(t) + \left( \frac{R_{g(t)}}{2} - \left| g(t) \nabla u(t) \right|_{g(t)}^2 \right) \frac{\partial}{\partial t} f(t) \right] f(t) dV_{g(t)} \\
+ \int_M \left[ \Delta_{g(t),u(t)} f(t) + \left( \frac{R_{g(t)}}{2} - \left| g(t) \nabla u(t) \right|_{g(t)}^2 \right) \frac{\partial}{\partial t} f(t) \right] f(t) dV_{g(t)} \\
= \int_M \left( g^{ip}g^{jq}v_{pq} \nabla_i \nabla_j f + \frac{1}{2} \left( \frac{\partial}{\partial t} R_{g(t)} \right) f(t) \right) f(t) dV_{g(t)} \\
+ \int_M \left( g^{ij}g^{kl} \nabla_{i} v_{jl} \nabla_k f - \frac{1}{2} g^{kl} \nabla_i \nabla_k f \right) f(t) dV_{g(t)} \\
+ \int_M \Delta_{g(t),u(t)} f(t) \left( \frac{\partial}{\partial t} f(t) dV_{g(t)} + \frac{\partial}{\partial t} \left( f(t) dV_{g(t)} \right) \right) \\
- \int_M \frac{\partial}{\partial t} \left( \left| g(t) \nabla u(t) \right|_{g(t)}^2 \right) f(t)^2 dV_{g(t)}.
\]
Since \( f(t) \) is an eigenvalue of \( \Delta_{g(t), u(t)} \), it follows that
\[
\int_M \Delta_{g(t), u(t)} f(t) \left( \frac{\partial}{\partial t} f(t) dV_{g(t)} + \frac{\partial}{\partial t} \left( f(t) dV_{g(t)} \right) \right)
= \lambda(t) \frac{\partial}{\partial t} \int_M f(t)^2 dV_{g(t)} = 0
\]
by the normalized condition. Thus we complete the proof. □

Using (3.6), we find that the first term in the right hand side of (8.6) can be written as
\[
\int_M \left[ v_{ij} \nabla^i \nabla^j f + \frac{1}{2} \left( \frac{\partial}{\partial t} R_{g(t)} \right) f(t) \right] f(t) dV_{g(t)}
= \int_M \left[ -2f(t) \left\langle \text{Ric}_{g(t)}, g(t) \nabla^2 f(t) \right\rangle_{g(t)} 
+ 4f(t) \left\langle du(t) \otimes du(t), g(t) \nabla^2 f(t) \right\rangle_{g(t)} \right] dV_{g(t)}
+ \int_M \left[ \left( \frac{1}{2} \Delta_{g(t)} R_{g(t)} + |\text{Ric}_{g(t)}|^2_{g(t)} \right) f(t)^2 + 2f(t)^2 |\Delta_{g(t)} u(t)|^2_{g(t)} 
- 2f(t)^2 \left| g(t) \nabla^2 u(t) \right|^2_{g(t)} - 4f(t)^2 \left\langle \text{Ric}_{g(t)}, du(t) \otimes du(t) \right\rangle_{g(t)} \right] dV_{g(t)}
= \int_M \left[ -2f(t) \left\langle \text{Ric}_{g(t)}, g(t) \nabla^2 f(t) \right\rangle_{g(t)} 
+ \left( \frac{1}{2} \Delta_{g(t)} R_{g(t)} + |\text{Ric}_{g(t)}|^2_{g(t)} \right) f(t)^2 \right] dV_{g(t)}
+ \int_M \left[ 4f(t) \left\langle du(t) \otimes du(t), g(t) \nabla^2 f(t) \right\rangle_{g(t)} - 4f^2 \left\langle du(t) \otimes du(t), \text{Ric}_{g(t)} \right\rangle_{g(t)} \right.
+ 2f(t)^2 |\Delta_{g(t)} u(t)|^2_{g(t)} - 2f(t)^2 \left| g(t) \nabla^2 u(t) \right|^2_{g(t)} \right] dV_{g(t)}
\]

For the second term in (8.6) one has, using the contracted Bianchi identities,
\[
\int_M \left( g^{ij} \nabla_i v_{jk} - \frac{1}{2} \nabla_k v \right) \nabla^k f \cdot f(t) dV_{g(t)}
= \int_M \left[ g^{ij} \nabla_i (-2R_{j k} + 4 \partial_j u \cdot \partial_k u) - \frac{1}{2} \nabla_k \left( -2R_{g(t)} + 4 \left| g(t) \nabla u(t) \right|^2_{g(t)} \right) \right]
\nabla^k f \cdot f(t) dV_{g(t)}
= \int_M 4f(t) \Delta_{g(t)} u(t) \left\langle g(t) \nabla u(t), g(t) \nabla f(t) \right\rangle_{g(t)} dV_{g(t)}
+ \int_M \left( 4g^{ij} \nabla_j u \cdot \nabla_i \nabla_k u - 2 \nabla_k \left| g(t) \nabla u(t) \right|^2_{g(t)} \right) \nabla^k f \cdot f(t) dV_{g(t)}
= \int_M 4f(t) \Delta_{g(t)} u(t) \left\langle g(t) \nabla u(t), g(t) \nabla f(t) \right\rangle_{g(t)} dV_{g(t)}
\]
where in the last step we use the identity $\nabla_k|\nabla u|^2 = 2g^{pq}\nabla_k\nabla_p u \cdot \nabla_q u$. Therefore

$$
\frac{d}{dt} \lambda_{g(t),u(t)}(f(t)) = \int_M \left[ -2f(t) \left\langle \Ric_{g(t)}, g(t)\nabla^2 f(t) \right\rangle_{g(t)} + \left(\frac{1}{2} \Delta_{g(t)} R_{g(t)} + \left|\Ric_{g(t)}\right|^2_{g(t)} \right) f(t)^2 \right] dV_{g(t)} + \int_M \left[ 4f(t) \left\langle du(t) \otimes du(t), g(t)\nabla^2 f(t) \right\rangle_{g(t)} \right] dV_{g(t)}$$

(8.8)

$$
-4f(t)^2 \left\langle du(t) \otimes du(t), \Ric_{g(t)} \right\rangle_{g(t)} + 2f(t)^2 \left| \Delta_{g(t)} u(t) \right|^2_{g(t)} - 2f(t)^2 \left| g(t)\nabla^2 u(t) \right|^2_{g(t)} + 4f(t) \Delta_{g(t)} u(t) \left\langle g(t)\nabla u(t), g(t)\nabla f(t) \right\rangle_{g(t)} dV_{g(t)} + \int_M \left( -\Delta_{g(t)} \left| g(t)\nabla u(t) \right|^2_{g(t)} + 2 \left| g(t)\nabla^2 u(t) \right|^2_{g(t)} \right) f(t)^2 dV_{g(t)}.
$$

The above evolution equation can be simplified as

**Theorem 8.2.** Suppose $(g(t), u(t))$ is a solution of the harmonic-Ricci flow on a compact Riemannian manifold $M$ and $f(t)$ is an eigenvalue of $\Delta_{g(t),u(t)}$, i.e., $\Delta_{g(t),u(t)} f(t) = \lambda(t) f(t)$ (where $\lambda(t)$ is only a function of time $t$ only), with the normalized condition $\int_M f(t)^2 dV_{g(t)} = 1$. Then we have

$$
\frac{d}{dt} \lambda_{g(t),u(t)}(f(t)) = \int_M 2 \left\langle \S_{g(t)}, df(t) \otimes df(t) \right\rangle_{g(t)} dV_{g(t)} + \int_M f(t)^2 \left[ \left| \S_{g(t)} \right|^2_{g(t)} + 2 \left| \Delta_{g(t)} u(t) \right|^2_{g(t)} \right] dV_{g(t)}.
$$

(8.9)

**Proof.** Calculate

$$
\int_M 4f(t) \Delta_{g(t)} u(t) \left\langle g(t)\nabla u(t), g(t)\nabla f(t) \right\rangle_{g(t)} dV_{g(t)}
$$

$$
= -4 \int_M \nabla u \left[ \nabla^i f : \nabla\nabla f \right] dV
$$

$$
= -4 \int_M \left| \nabla u, \nabla f \right|^2 dV_g - 4 \int_M f \nabla u \left( \langle \nabla^i \nabla u, \nabla f \rangle + \langle \nabla u, \nabla^i \nabla f \rangle \right) dV.
$$

By the same method, we have

$$
\int_M -\Delta_{g(t)} \left| g(t)\nabla u(t) \right|^2_{g(t)} f(t)^2 dV_{g(t)} = - \int_M |\nabla u|^2 \left( 2f \Delta f + 2|\nabla f|^2 \right) dV
$$

$$
= -2 \int_M |\nabla f|^2 |\nabla u|^2 dV - 2 \int_M f \Delta f |\nabla u|^2 dV.
$$
However, 
\[
\int_M f \Delta f |\nabla u|^2 dV = \int_M -\nabla_i f \cdot \nabla^i (f |\nabla u|^2) dV \\
= -\int_M \nabla_i f (\nabla^i f |\nabla u|^2 + f \nabla^i |\nabla u|^2) dV \\
= -\int_M |\nabla u|^2 |\nabla f|^2 dV - \int_M f \nabla_i f \cdot \nabla^i |\nabla u|^2 dV.
\]

Plugging it into above yields 
\[
\int_M -\Delta_{g(t)} \left| g(t) \nabla u(t) \right|^2_{g(t)} f(t)^2 dV_{g(t)} = 2 \int_M f \nabla_i f \cdot \nabla^i |\nabla u|^2 dV
\]

Using the contracted Bianchi identities we may simplify the term \( \int_M f^2 \frac{\Delta R}{2} dV \) as follows:
\[
\int_M \frac{f(t)^2}{2} \Delta_{g(t)} R_{g(t)} dV_{g(t)} = -\frac{1}{2} \int_M \nabla_i R \cdot \nabla^i (f^2) dV \\
= -\int_M \nabla_i R \cdot f \nabla^i f dV = -2 \int_M \nabla^k R_{ki} \cdot f \nabla^i f dV \\
= 2 \int_M R_{ki} \nabla^k (f \nabla^i f) dV = 2 \int_M R_{ki} \left( \nabla^k f \cdot \nabla^i f + f \nabla^k \nabla^i f \right) dV \\
= 2 \int_M \left\langle \text{Ric}_{g(t)}, df(t) \otimes df(t) \right\rangle_{g(t)} dV_{g(t)} \\
\quad + 2 \int_M f(t) \left\langle \text{Ric}_{g(t)}, g(t) \nabla^2 f(t) \right\rangle_{g(t)} dV_{g(t)}.
\]

Hence (8.8) becomes
\[
\frac{d}{dt} \lambda_{g(t),u(t)}(f(t))
\]
\[
= \int_M \left[ 2 \left\langle \text{Ric}_{g(t)}, df(t) \otimes df(t) \right\rangle_{g(t)} + \left| \text{Ric}_{g(t)} \right|_{g(t)}^2 f(t)^2 \right] dV_{g(t)} \\
\quad + \int_M \left[ 2 \left| \Delta_{g(t)} u(t) \right|_{g(t)}^2 + 4 \left| g(t) \nabla u(t) \right|_{g(t)}^2 \right] f(t)^2 dV_{g(t)} \\
\quad - \int_M 4f(t)^2 \left\langle du(t) \otimes du(t), \text{Ric}_{g(t)} \right\rangle_{g(t)} dV_{g(t)} \\
\quad - \int_M 4 \left\langle g(t) \nabla u(t), g(t) \nabla f(t) \right\rangle_{g(t)}^2 dV_{g(t)} \\
\quad = \int_M 2 \left\langle S_{g(t)}, df(t) \otimes df(t) \right\rangle_{g(t)} dV_{g(t)} \\
\quad + \int_M f(t)^2 \left[ \left| \text{Ric}_{g(t)} - 2 du(t) \otimes du(t) \right|_{g(t)}^2 + 2 \left| \Delta_{g(t)} u(t) \right|_{g(t)}^2 \right] dV_{g(t)}
where by definition \( S_{ij} = R_{ij} - 2\partial_i u \partial_j u \).

In \( [8] \), List proved that the nonnegativity of operator \( S_{g(t)} \) is preserved by the harmonic-Ricci flow, hence

Corollary 8.3. If \( \text{Ric}_{g(0)} - 2d\text{u}(0) \otimes d\text{u}(0) \geq 0 \), then the eigenvalues of the operator \( \Delta_{g(t), u(t)} \) are nondecreasing under the harmonic-Ricci flow.

Remark 8.4. If we choose \( u(t) \equiv 0 \), then we obtain X. Cao’s result \( [3] \).

9. Another formula for \( \frac{d}{dt} \lambda(f(t)) \)

In this section we give another formula for \( \frac{d}{dt} \lambda(f(t)) \) using the similar method in \( [7] \). Recall the formula

\[
\frac{d}{dt} \lambda_{g(t), u(t)}(f(t)) = \int_M 2 \langle S_{g(t), u(t)}, df(t) \otimes df(t) \rangle_{g(t)} dV_{g(t)}
\]

Consider the function \( \varphi \) determined by \( f^2(t) = e^{-\varphi(t)} \). Then we have

\[
df = \frac{-e^\varphi d\varphi}{2f}, \quad \nabla f = -\frac{\nabla \varphi}{2}, \quad \frac{\Delta f}{f} = -\frac{1}{2} \Delta \varphi + \frac{1}{4} |\nabla \varphi|^2.
\]

Hence

\[
2 \frac{d}{dt} \lambda_{g(t), u(t)}(f(t)) = \int_M \langle S_{g(t), u(t)}, u(t), d\varphi(t) \otimes d\varphi(t) \rangle_{g(t)} e^{-\varphi(t)} dV_{g(t)}
\]

\[+ 2 \int_M \left[ |S_{g(t), u(t)}|^2_{g(t)} + 2 |\Delta_{g(t), u(t)}|^2_{g(t)} \right] e^{-\varphi} dV_{g(t)}.
\]

Using the integration by parts and contracted Bianchi identities yields

\[
\int_M \langle S_{g(t), u(t)}, d\varphi(t) \otimes d\varphi(t) \rangle_{g(t)} e^{-\varphi(t)} dV_{g(t)}
\]

\[= \int_M S_{ij} \nabla^i \varphi \nabla^j \varphi e^{-\varphi} dV = - \int_M S_{ij} \nabla^i \varphi \nabla^j (e^{-\varphi}) dV
\]

\[= \int_M e^{-\varphi} \nabla^i (S_{ij} \nabla^j \varphi) dV
\]

\[= \int_M \nabla^i S_{ij} \varphi \cdot e^{-\varphi} dV + \int_M S_{ij} \nabla^i \nabla^j \varphi \cdot e^{-\varphi} dV
\]

\[= \int_M \nabla^i R_{ij} \varphi \cdot e^{-\varphi} dV_g + \int_M S_{ij} \nabla^i \nabla^j \varphi \cdot e^{-\varphi} dV_g
\]

\[+ \int_M \nabla^i (2\nabla_i u \nabla_j u) \nabla^j \varphi \cdot e^{-\varphi} dV_g
\]

\[= \frac{1}{2} \int_M R \Delta (e^{-\varphi}) dV + \int_M S_{ij} \nabla^i \nabla^j \varphi \cdot e^{-\varphi} dV
\]

\[-2 \int_M (\nabla^i u \nabla_j u) \nabla^i \nabla^j (e^{-\varphi}) dV.
\]
Thus
\[
\int_M S_{ij} \nabla^i \nabla^j \varphi \cdot e^{-\varphi} \, dV = \int_M \nabla^i \varphi \nabla^j \varphi e^{-\varphi} \, dV - \frac{1}{2} \int_M R \Delta (e^{-\varphi}) \, dV \\
+ 2 \int_M (\nabla^i u \nabla^j u) \nabla^i \nabla^j (e^{-\varphi}).
\]

On the other hand, one gets
\[
\int_M |g(t) \nabla^2 \varphi(t)|^2 e^{-\varphi} \, dV(t) = \int_M \nabla_i \nabla_j \varphi \nabla^i \nabla^j \varphi \cdot e^{-\varphi} \, dV
\]
\[
= - \int_M \nabla_j \varphi \cdot \nabla_i \nabla^i \nabla^j \varphi \cdot e^{-\varphi} \, dV - \int_M \nabla_j \varphi \cdot \nabla^i \nabla^j \varphi \cdot \nabla_i (e^{-\varphi}) \, dV
\]
\[
= - \int_M \nabla_j \varphi \cdot \nabla_i \nabla^i \nabla^j \varphi \cdot e^{-\varphi} \, dV - \int_M \nabla_j \varphi \cdot \nabla^i \nabla^j \varphi \cdot \nabla_i (e^{-\varphi}) \, dV.
\]

Since
\[
\int_M \nabla_j \varphi \cdot \nabla^i \nabla^j \varphi \cdot \nabla_i (e^{-\varphi}) \, dV
\]
\[
= - \int_M \nabla^i (\nabla_j \varphi \cdot \nabla_i (e^{-\varphi})) \, \nabla_j \varphi \, dV
\]
\[
= - \int_M \nabla_j \varphi \cdot \nabla^i \nabla^j \varphi \cdot \nabla_i (e^{-\varphi}) \, dV - \int_M |\nabla \varphi|^2 \Delta (e^{-\varphi}) \, dV
\]

which implies
\[
\int_M \nabla_j \varphi \cdot \nabla^i \nabla^j \varphi \cdot \nabla_i (e^{-\varphi}) \, dV = - \frac{1}{2} \int_M |\nabla \varphi|^2 \Delta (e^{-\varphi}) \, dV,
\]

it follows that
\[
\int_M |\nabla^2 \varphi|^2 e^{-\varphi} \, dV = - \int_M \nabla_j \varphi \cdot \nabla_i \nabla^j \nabla^i \varphi \cdot e^{-\varphi} \, dV + \frac{1}{2} \int_M |\nabla \varphi|^2 \Delta (e^{-\varphi}) \, dV.
\]

By Ricci identity the term $\nabla^i \nabla^j \nabla^i \varphi$ equals
\[
\nabla_i \nabla^j \nabla^i \varphi = g^{ik} g^{jl} \nabla_i \nabla_k \nabla_l \varphi
\]
\[
= g^{ik} g^{jl} (\nabla_k \nabla_l \nabla_i \varphi - R_{ikl}^p \nabla_p \varphi)
\]
\[
= \nabla_j \nabla_i \nabla \varphi - g^{ik} g^{jl} R_{ikl} \nabla^p \varphi
\]
\[
= \nabla_j \Delta \varphi + g^{ik} g^{jl} R_{ikl} \nabla^p \varphi
\]
\[
= \nabla_j \Delta \varphi + g^{ik} R_{kp} \nabla^p \varphi.
\]
Hence

\[ - \int_M \varphi_j \varphi \cdot \nabla_i \nabla_j \nabla^i \varphi \cdot e^{-\varphi} dV \]

\[ = - \int_M \nabla_i \varphi \cdot \nabla_j \Delta \varphi \cdot e^{-\varphi} dV - \int_M R_{kp} \nabla^k \varphi \cdot \nabla^p \varphi e^{-\varphi} dV \]

\[ = \int_M \nabla^j \Delta \varphi \cdot \nabla_j (e^{-\varphi}) + \int_M R_{kp} \nabla^k \varphi \cdot \nabla^p (e^{-\varphi}) dV \]

\[ = - \int_M \Delta \varphi \cdot \Delta (e^{-\varphi}) - \int_M e^{-\varphi} \left( \nabla^p R_{kp} \cdot \nabla^k \varphi + R_{kp} \nabla^p \nabla^k \varphi \right) dV \]

\[ = - \int_M \Delta (e^{-\varphi}) \cdot \Delta \varphi dV + \frac{1}{2} \int_M \nabla R \cdot \nabla^k (e^{-\varphi}) dV \]

\[ - \int_M e^{-\varphi} R_{kp} \nabla^k \nabla^p \varphi dV \]

\[ = - \int_M \Delta (e^{-\varphi}) \left( \Delta \varphi + \frac{1}{2} R \right) - \int_M R_{kp} \nabla^k \nabla^p \varphi \cdot e^{-\varphi} dV. \]

Putting those formulas together, we obtain

\[ \int_M 2S_{ij} \nabla^i \nabla^j \varphi \cdot e^{-\varphi} dV + \int_M |\nabla^2 \varphi|^2 e^{-\varphi} dV \]

\[ = \int_M S_{ij} \nabla^i \nabla^j \varphi \cdot e^{-\varphi} dV + \int_M (-2 \nabla_i u \nabla_j u) \nabla^i \nabla^j \varphi \cdot e^{-\varphi} dV \]

\[ - \int_M \Delta (e^{-\varphi}) \left( \Delta \varphi + \frac{R}{2} - \frac{1}{2} |\nabla \varphi|^2 \right) e^{-\varphi} dV \]

\[ = \int_M S_{ij} \nabla^i \varphi \nabla^j \varphi \cdot e^{-\varphi} dV - \int_M \Delta (e^{-\varphi}) \left( \Delta \varphi + R - \frac{1}{2} |\nabla \varphi|^2 \right) e^{-\varphi} dV \]

\[ + 2 \int_M (\nabla_i u \nabla_j u \cdot \nabla_i \nabla^j (e^{-\varphi}) - \nabla_i u \nabla_j u \cdot \nabla^i \nabla_j \varphi \cdot e^{-\varphi}) dV. \]

Since \( f \) is an eigenfunction of \( \lambda \), it induces

\[ \lambda = - \frac{\Delta f}{f} + \frac{R}{2} - |\nabla u|^2 \]

\[ = \frac{1}{2} \Delta \varphi - \frac{1}{4} |\nabla \varphi|^2 + \frac{R}{2} - |\nabla u|^2 \]

and therefore

\[ \int_M 2S_{ij} \nabla^i \nabla^j \varphi \cdot e^{-\varphi} dV + \int_M |\nabla^2 \varphi|^2 e^{-\varphi} dV \]

\[ = \int_M S_{ij} \nabla^i \varphi \nabla^j \varphi \cdot e^{-\varphi} dV - 2 \int_M \Delta (|\nabla u|^2) \cdot e^{-\varphi} dV \]

\[ + 2 \int_M (\nabla_i u \nabla_j u \cdot \nabla_i \nabla^j (e^{-\varphi}) - \nabla_i \nabla^j \varphi \cdot e^{-\varphi}) dV. \]
Plugging into the expression of $\frac{d}{dt} \lambda(f(t))$ yields

$$
2 \frac{d}{dt} \lambda_{g(t), u(t)}(f(t)) = \int_M S_{ij} \nabla^i \varphi \nabla^j \varphi \cdot e^{-\varphi} dV + \int_M |S|^2 e^{-\varphi} dV
+ \int_M |\Delta u|^2 e^{-\varphi} dV + 4 \int_M \Delta u |\nabla u|^2 e^{-\varphi} dV
$$

$$
= \int_M \left| S_{g(t), u(t)} + g(t) \nabla^2 \varphi(t) \right|^2_{g(t)} e^{-\varphi(t)} dV_{g(t)} + \int_M \left| S_{g(t), u(t)} \right|^2_{g(t)} e^{-\varphi(t)} dV_{g(t)}
+ 4 \int_M |\Delta_{g(t)} u(t)|^2_{g(t)} e^{-\varphi(t)} dV_{g(t)} + 2 \int_M \Delta_{g(t)} |\nabla u(t)|^2_{g(t)} e^{-\varphi(t)} dV_{g(t)}
$$

$$
+ 2 \int_M \nabla_i u \nabla_j u \left[ -\nabla^i \nabla^j (e^{-\varphi}) + \nabla^i \nabla^j \varphi \cdot e^{-\varphi} \right] dV
$$

On the other hand,

$$
I := \int_M (\nabla_i u \nabla_j u \cdot \nabla^i \nabla^j \varphi) e^{-\varphi} dV
$$

$$
= - \int_M \nabla^i (\nabla_i u \nabla_j u \cdot e^{-\varphi}) \nabla^j \varphi dV
$$

$$
= - \int_M \nabla^j \varphi \left( \Delta u \cdot \nabla_j u \cdot e^{-\varphi} + \nabla_j u \nabla^i \nabla_j u \cdot e^{-\varphi} - \nabla_i u \nabla_j u \nabla^i \varphi \cdot e^{-\varphi} \right) dV
$$

$$
= - \int_M \nabla_j u \nabla^j \varphi \Delta u \cdot e^{-\varphi} dV - \int_M \nabla_i u \nabla^j \varphi \nabla^i \nabla_j u \cdot e^{-\varphi} dV
+ \int_M |\langle du, d\varphi \rangle|^2 e^{-\varphi} dV
$$

and

$$
II := \int_M \nabla_i u \nabla_j u \nabla^i \nabla^j (e^{-\varphi}) dV
= \int_M \nabla^i \nabla^j (\nabla_i u \nabla_j u) e^{-\varphi} dV
$$

$$
= \int_M \nabla^i (\nabla^j \nabla_i u \cdot \nabla_j u + \nabla_i u \Delta u) e^{-\varphi} dV
$$

$$
= \int_M \left( \Delta \nabla^i u \cdot \nabla_i u + \nabla^i \Delta u \cdot \nabla_i u + |\nabla^2 u|^2 + |\Delta u|^2 \right) e^{-\varphi} dV
$$

and

$$
III := \int_M \Delta \left( |\nabla u|^2 \right) e^{-\varphi} dV
= 2 \int_M \nabla^i (\nabla_i u \nabla^j u) e^{-\varphi} dV
$$

$$
= 2 \int_M \left( \Delta \nabla_i u \cdot \nabla^j u + |\nabla^2 u|^2 \right) e^{-\varphi} dV.
$$

If we set

$$
B := 2 (III + I - II)
$$
then
\[ \frac{B}{2} = \int_M \left[ \Delta \nabla_i u \cdot \nabla^i u - \nabla_i \Delta u \cdot \nabla^i u + |\nabla^2 u|^2 - |\Delta u|^2 + |\langle du, d\varphi \rangle|^2 \right. \\
\left. - \nabla_i u \cdot \nabla^i \varphi \cdot \Delta u - \nabla_i u \cdot \nabla^j \varphi \cdot \nabla^i \nabla_j u \right] e^{-\varphi} dV \]
\[ = \int_M \left( R_{ij} \nabla^i u \nabla^j u + |\nabla^2 u|^2 - |\Delta u|^2 + |\langle du, d\varphi \rangle|^2 \right. \\
\left. - \nabla_i u \cdot \nabla^i \varphi \cdot \Delta u - \nabla_i u \cdot \nabla^j \varphi \cdot \nabla^i \nabla_j u \right) e^{-\varphi} dV. \]

On the other hand,
\[ \int_M \nabla^i u \cdot \nabla^i \varphi \cdot \Delta u \cdot e^{-\varphi} dV = \int_M (\nabla_i u \cdot \Delta u) \nabla^i (e^{-\varphi}) dV \]
\[ = - \int_M \nabla^i (\nabla_i u \cdot \Delta u) e^{-\varphi} dV \]
\[ = \int_M (-|\Delta u|^2 - \nabla_i u \cdot \nabla^i \Delta u) e^{-\varphi} dV \]

and
\[ \int_M \nabla_i u \nabla^j \varphi \nabla^i \nabla_j u \cdot e^{-\varphi} dV = \int_M \nabla_i u \nabla^i \nabla_j u \nabla^j (e^{-\varphi}) dV \]
\[ = - \int_M \nabla^j (\nabla_i u \nabla^i \nabla_j u) e^{-\varphi} dV \]
\[ = \int_M (-|\nabla^2 u|^2 - \nabla_i u \Delta \nabla^i u) e^{-\varphi} dV. \]

Therefore
\[ \frac{B}{2} = \int_M \left[ -2 |\Delta u|^2 + |\langle du, d\varphi \rangle|^2 - 2 \langle \nabla u, \nabla \Delta u \rangle \right] e^{-\varphi} dV. \]

By definition,
\[ \Delta (|\nabla u|^2) = \Delta (\nabla_i u \cdot \nabla^i u) = 2 \nabla^i u \cdot \Delta \nabla_i u + 2 |\nabla^2 u|^2. \]

So
\[ \Delta |\nabla u|^2 = 2 |\nabla^2 u|^2 + 2 (\nabla_i \Delta u + R_{ij} \nabla^j u) \nabla^i u \]
\[ = 2 |\nabla^2 u|^2 + 2 R_{ij} \nabla^i u \cdot \nabla^j u + 2 \langle \nabla u, \nabla \Delta u \rangle. \]

Pugging it into (9.1) yields
\[ \frac{B}{2} = \int_M \left[ -2 |\Delta u|^2 + |\langle du, d\varphi \rangle|^2 + 2 |\nabla^2 u|^2 - \Delta |\nabla u|^2 + 2 R_{ij} \nabla^i u \nabla^j u \right] e^{-\varphi} dV. \]

Since
\[ 2 R_{ij} \nabla^i u \nabla^j u \]
\[ = 2 (S_{ij} + 2 \nabla_i \nabla^j u) \nabla^i u \nabla^j u \]
\[ = 2 S_{ij} \nabla^i u \nabla^j u + 4 |\nabla u|^4 \]
\[ = \frac{1}{4} |S + 4 \nabla u \otimes \nabla u|^2 - \frac{1}{4} |S|^2, \]
it follows that
\[
\frac{B}{2} = III + I - II
\]
\[
= \int_M \left[ (\Delta u)^2 - 2|\Delta u|^2 - \frac{1}{4} |S|^2 + 2 \nabla^2 u^2 + \frac{1}{4} |S + 4du \otimes du|^2 \right] e^{-\varphi} dV - III.
\]
Hence
\[
B = \int_M \left[ -4 |\Delta u|^2 + 2 (\Delta u)^2 - \frac{1}{2} |S|^2 + 4 \nabla^2 u^2 + \frac{1}{2} |S + 4du \otimes du|^2 \right] e^{-\varphi} dV - 2III.
\]

**Theorem 9.1.** Suppose that \((g(t), u(t))\) is a solution of the harmonic-Ricci flow on a compact Riemannian manifold \(M\) and \(f(t)\) is an eigenvalue of \(\Delta_{g(t), u(t)}\), i.e., \(\Delta_{g(t), u(t)} f(t) = \lambda(t) f(t)\) (where \(\lambda(t)\) is only a function of time \(t\)), with the normalized condition \(\int_M f(t)^2 dV_{g(t)} = 1\). Then we have

\[
(9.2) \frac{d}{dt} \lambda(t) = \frac{d}{dt} \lambda_{g(t),u(t)}(f(t))
\]
\[
= \frac{1}{2} \int_M \left[ S_{g(t),u(t)} + g(t) \nabla^2 \varphi(t) \right] e^{-\varphi(t)} dV_{g(t)}
\]
\[
+ \frac{1}{4} \int_M \left| S_{g(t),u(t)} \right|^2_{g(t)} e^{-\varphi(t)} dV_{g(t)}
\]
\[
+ \int_M \left[ (du(t), d\varphi(t))_{g(t)} \right]^2 e^{-\varphi(t)} dV_{g(t)} + 2 \int_M \left| g(t) \nabla^2 u(t) \right|^2_{g(t)} e^{-\varphi(t)} dV_{g(t)}
\]
\[
+ \frac{1}{4} \int_M \left| S_{g(t),u(t)} + 4du(t) \otimes du(t) \right|^2_{g(t)} e^{-\varphi(t)} dV_{g(t)}
\]
\[
- \int_M \Delta g(t) \left( \left| g(t) \nabla u(t) \right|^2_{g(t)} \right) e^{-\varphi(t)} dV_{g(t)}.
\]

**Remark 9.2.** When \(u \equiv 0\), (9.2) reduces to J. Li’s formula [7].

10. The first variation of expander and shrinker entropys

Suppose that \(M\) is a closed manifold of dimension \(n\). We define

\[
\mathcal{W}_\pm : \mathcal{C}^\infty(M) \times \mathcal{C}^\infty(M) \times \mathbb{R}^+ \to \mathbb{R}, \quad (g, u, f, \tau) \mapsto \mathcal{W}_\pm(g, u, f, \tau)
\]

where

\[
(10.1) \quad \mathcal{W}_\pm(g, u, f, \tau) := \int_M \left[ \tau \left( S_{g,u} + \left| g \nabla f \right|^2_{g} \right) \mp f \pm n \right] \frac{e^{-f}}{(4\pi \tau)^{n/2}} dV_g.
\]
Set
\[ \mu_\pm(g, u, \tau) := \inf \left\{ W_\pm(g, u, f, \tau) \mid f \in C^\infty(M), \int_M \frac{e^{-f}}{(4\pi\tau)^n/2} dV_g = 1 \right\}, \]
\[ \nu_\pm(g, u) := \inf \{ \mu_\pm(g, u, \tau) \mid \tau > 0 \}. \]

**Lemma 10.1.** Suppose \( \nu_\pm(g, u) = W_\pm(g, u, f_\pm, \tau_\pm) \) for some functions \( f_\pm \) and constants \( \tau_\pm \) satisfying
\[ \int_M \frac{e^{-f_\pm}}{(4\pi\tau_\pm)^n/2} dV_g = 1, \quad \tau_\pm > 0, \]
then we must have
\[ \tau_\pm \left( -2\Delta_g f_\pm + |g\nabla f_\pm|^2 - S_{g,u} \right) \pm f_\pm \mp n + \nu_\pm(g, u) = 0, \]
\[ \int_M \frac{f_\pm e^{-f_\pm}}{(4\pi\tau_\pm)^n/2} dV_g = \frac{n}{2} \mp \nu_\pm(g, u). \]

**Proof.** Since \( g \) and \( u \) are fixed, we consider the corresponding Lagrangian multiplier function
\[ \mathcal{L}_\pm(f, \tau; \lambda) := W_\pm(g, u, f, \tau) - \lambda \left( \int_M \frac{e^{-f}}{(4\pi\tau)^n/2} dV_g - 1 \right). \]
Then the variation of \( \mathcal{L}_\pm \) in \( f \) direction is
\[ \delta_f \mathcal{L}_\pm(f, \tau; \lambda) = \int_M \left[ 2\tau \nabla^i f \nabla_i (\delta f) \mp \delta f + \lambda \delta f \right] \frac{e^{-f}}{(4\pi\tau)^n/2} dV_g \]
\[ - \int_M \left[ \tau \left( S_{g,u} + |g\nabla f_\pm|^2 \right) \mp f_\pm \mp n \right] \frac{e^{-f}}{(4\pi\tau)^n/2} dV_g. \]
By the divergence theorem, we calculate
\[ \int_M \nabla^i f \cdot \nabla_i (\delta f) \frac{e^{-f}}{(4\pi\tau)^n/2} dV_g = - \int_M \nabla_i \left( \nabla^i f \frac{e^{-f}}{(4\pi\tau)^n/2} \right) \delta f dV_g \]
\[ = - \int_M \left( \Delta_g f - |g\nabla f_\pm|^2 \right) \delta f \frac{e^{-f}}{(4\pi\tau)^n/2} dV_g. \]
Hence
\[ \delta_f \mathcal{L}_\pm(f, \tau; \tau) = \int_M \left[ \tau \left( -2\Delta_g f + |g\nabla f_\pm|^2 - S_{g,u} \right) \pm f_\pm \mp n \mp 1 + \lambda \right] \frac{e^{-f}}{(4\pi\tau)^n/2} dV. \]
This implies that
\[ \tau_\pm \left( -2\Delta_g f_\pm + |g\nabla f_\pm|^2 - S_{g,u} \right) \pm f_\pm \mp n \mp 1 + \lambda_\pm = 0. \]
Since \( f_\pm \) satisfies the normalized condition, it follows that
\[ 0 = \lambda_\pm \mp 1 + \int_M \left[ \tau_\pm \left( -2\Delta_g f_\pm + |g\nabla f_\pm|^2 - S_{g,u} \right) \pm f_\pm \mp n \right] \frac{e^{-f_\pm}}{(4\pi\tau_\pm)^n/2} dV_g. \]
From the identity
\[
\int_M \Delta_g f \frac{e^{-f}}{(4\pi \tau)^{n/2}} dV_g = \int_M |\nabla_g f|^2 \frac{e^{-f}}{(4\pi \tau)^{n/2}} dV_g
\]
and the definition (10.1), we obtain
\[
\nu_\pm(g, u) = W_\pm(g, u, f_\pm, \tau_\pm) = \lambda_{\pm} \mp 1,
\]
and consequently,
\[
\tau_\pm \left( -2 \Delta_g f_\pm + |g \nabla f_\pm|^2 - S_{g,u} \right) \pm f_\pm \mp n + \nu_\pm(g, u) = 0.
\]

The variation of \( L_\pm \) with respect to \( \tau \) indicates
\[
\delta_\tau L_\pm(f, \tau; \lambda) = \int_M \delta \tau \left( S_{g,u} + |g \nabla f_\pm|^2 \right) \frac{e^{-f}}{(4\pi \tau)^{n/2}} dV_g
\]
\[
-\lambda \int_M \left( -\frac{n \delta \tau}{\tau} \right) \frac{e^{-f}}{(4\pi \tau)^{n/2}} dV_g,
\]
\[
+ \int_M \left( -\frac{n \delta \tau}{\tau} \right) \left[ \tau \left( S_{g,u} + |g \nabla f_\pm|^2 \right) \pm f_\pm \mp n \right] \frac{e^{-f}}{(4\pi \tau)^{n/2}} dV_g
\]
\[
= \int_M \delta \tau \left( 1 - \frac{n}{2} \right) \left( S_{g,u} + |g \nabla f_\pm|^2 \right)
\]
\[
+ \frac{n}{2\tau} (\lambda \pm f \mp n) \right] \frac{e^{-f}}{(4\pi \tau)^{n/2}} dV_g.
\]

Using the first proved equation we have
\[
0 = \int_M \left[ (\nu_\pm(g, u) \pm f_\pm \mp n) \left( 1 - \frac{n}{2} \right) \right.
\]
\[
+ \frac{n}{2} (\nu_\pm(g, u) \pm f_\pm \mp n \pm 1) \right] \frac{e^{-f_\pm}}{(4\pi \tau_{\mp})^{n/2}} dV_g
\]
\[
= \int_M \left( \nu_\pm \pm f_\pm \mp n \right) \frac{e^{-f_\pm}}{(4\pi \tau_{\pm})^{n/2}} dV_g
\]
and therefore we obtain the second one. \( \square \)

For a symmetric 2-tensor \( h = (h_{ij}) \in \mathcal{O}^2(M) \), we set
\[
g(s) := g + sh
\]
Then the variation of \( g(s) \) is
\[
(10.2) \quad \frac{\partial}{\partial s} \bigg|_{s=0} R_{g(s)} = -h^{ij} R_{ij} + \nabla^i \nabla^j h_{ij} - \Delta_g (\text{tr}_g h).
\]

**Theorem 10.2.** Suppose that \((M, g)\) is a compact Riemannian manifold and \( u \) a smooth function on \( M \). Let \( h \) be any symmetric covariant 2-tensor on \( M \) and set \( g(s) := g + sh \). Let \( v \) be any smooth function on \( M \) and \( u(s) := u + sv \). If \( \nu_\pm(g(s), u(s)) = W_\pm(g(s), u(s), f_\pm(s), \tau_\pm(s)) \) for some
smooth functions \( f_{\pm}(s) \) with \( \int_M e^{-f_{\pm}(s)}dV/(4\pi \tau_{\pm}(s))^{n/2} = 1 \) and constants \( \tau_{\pm}(s) > 0 \), then

\[
\frac{d}{ds} \left|_{s=0} \nu_{\pm}(g(s), u(s)) \right.
= -\tau_{\pm} \int_M \left( \langle h, S_{g,u} \rangle_g + \langle h, g^2 f \rangle_g + \frac{1}{2\tau_{\pm}} \text{tr}_g h \right) \frac{e^{-f_{\pm}(s)}}{(4\pi \tau_{\pm}(s))^{n/2}}dV_g + 4\tau_{\pm} \int_M v(\Delta_g u - \langle du, df_{\pm} \rangle_g) \frac{e^{-f_{\pm}(s)}}{(4\pi \tau_{\pm}(s))^{n/2}}dV_g,
\]

where \( f_{\pm} := f_{\pm}(0) \) and \( \tau_{\pm} := \tau_{\pm}(0) \). In particular, the critical points of \( \nu_{\pm}(\cdot, \cdot) \) satisfy

\[
S_{g,u} + g^2 f + \frac{1}{2\tau_{\pm}} = 0, \quad \Delta_g u = \langle du, df_{\pm} \rangle_g.
\]

Consequently, if \( W_{\pm}(g, u, f, \tau) \) and \( \nu_{\pm}(g, u) \) achieve their minimums, then \( (M, g) \) is a gradient expanding and shrinker harmonic-Ricci soliton according to the sign.

**Proof.** By definition, one has

\[
\frac{d}{ds} \nu_{\pm}(g(s), u(s)) = \frac{d}{ds} W_{\pm}(g(s), u(s), f_{\pm}(s), \tau_{\pm}(s))
= \int_M \left[ \frac{\partial}{\partial s} \tau_{\pm}(s) \left( S_{g(s),u(s)} + \left| \frac{g(s)\nabla f_{\pm}(s)}{g(g(s))} \right|^2 \right) \right] \frac{e^{-f_{\pm}(s)}}{(4\pi \tau_{\pm}(s))^{n/2}}dV_{g(s)}
+ \int_M \left[ \tau_{\pm}(s) \frac{\partial}{\partial s} \left( S_{g(s),u(s)} + \left| \frac{g(s)\nabla f_{\pm}(s)}{g(g(s))} \right|^2 \right) \right] \frac{e^{-f_{\pm}(s)}}{(4\pi \tau_{\pm}(s))^{n/2}}dV_{g(s)}
+ \int_M \left[ \tau_{\pm}(s) \left( S_{g(s),u(s)} + \left| \frac{g(s)\nabla f_{\pm}(s)}{g(g(s))} \right|^2 \right) \right] f_{\pm}(s) \pm n
\left( \frac{\partial}{\partial s} \left( \frac{e^{-f_{\pm}(s)}}{(4\pi \tau_{\pm}(s))^{n/2}}dV_{g(s)} \right) \right).
\]

Since

\[
\frac{\partial}{\partial s} S_{g(s),u(s)} = \frac{\partial}{\partial s} R_{g(s)} - 2 \frac{\partial}{\partial s} \left| \frac{g(s)\nabla u(s)}{g(s)} \right|^2
= \frac{\partial}{\partial s} R_{g(s)} - 2 \left( \frac{\partial}{\partial s} g^{ij} \right) \nabla_i u \nabla_j u - 4 g^{ij} \frac{\partial}{\partial s} \nabla_i u \cdot \nabla_j u
= \frac{\partial}{\partial s} R_{g(s)} - 2 \left( -g^{ip} g^{jq} h_{pq} \right) \nabla_i u \nabla_j u - 4 g^{ij} \nabla_i \left( \frac{\partial}{\partial s} u \right) \nabla_j u
= \frac{\partial}{\partial s} R_{g(s)} + 2 h_{pq} \nabla_p u \nabla_q u - 4 \nabla_i \left( \frac{\partial}{\partial s} u \right) \nabla_i u
\]
\[
\frac{\partial}{\partial s} \left( \frac{e^{-f_{\pm}(s)}}{(4\pi \tau_{\pm}(s))^{n/2}} dV_g(s) \right)
= \left( -\frac{\partial}{\partial s} f_{\pm}(s) - \frac{n}{2\tau_{\pm}(s)} \frac{\partial}{\partial s} \tau_{\pm}(s) \right) \frac{e^{-f_{\pm}(s)}}{(4\pi \tau_{\pm}(s))^{n/2}} dV_g(s) + \frac{e^{-f_{\pm}(s)}}{(4\pi \tau_{\pm}(s))^{n/2}} \frac{\partial}{\partial s} dV_g(s)
= \left( -\frac{\partial}{\partial s} f_{\pm}(s) - \frac{n}{2\tau_{\pm}(s)} \frac{\partial}{\partial s} \tau_{\pm}(s) + \frac{1}{2} \text{tr}_g h \right) \frac{e^{-f_{\pm}(s)}}{(4\pi \tau_{\pm}(s))^{n/2}} dV_g(s),
\]

it follows that
\[
\frac{d}{ds} \nu_{\pm}(g(s), u(s)) = \int_M \frac{\partial}{\partial s} \tau_{\pm}(s) \left( S_{g(s), u(s)} + \left| g(s) \nabla f_{\pm}(s) \right|^2_{g(s)} \right) \frac{e^{-f_{\pm}(s)}}{(4\pi \tau_{\pm}(s))^{n/2}} dV_g(s)
+ \int_M \left[ \tau_{\pm}(s) \left( \frac{\partial}{\partial s} R_{g(s)} + 2h_{pq} \nabla p u \nabla q u - 4 \nabla_i \left( \frac{\partial}{\partial s} u \right) \nabla^i u \right)
- h_{pq} \nabla^p f \nabla^q f + 2 \nabla_i \left( \frac{\partial}{\partial s} f \right) \nabla^i f \right] \frac{e^{-f_{\pm}(s)}}{(4\pi \tau_{\pm}(s))^{n/2}} dV_g(s)
+ \int_M \left( -\frac{\partial}{\partial s} f_{\pm}(s) - \frac{n}{2\tau_{\pm}(s)} \frac{\partial}{\partial s} \tau_{\pm}(s) + \frac{1}{2} \text{tr}_g h \right) \cdot \left[ \tau_{\pm}(s) \left( S_{g(s), u(s)} + \left| g(s) \nabla f_{\pm}(s) \right|^2_{g(s)} \right) \pm f_{\pm}(s) \pm n \right] \frac{e^{-f_{\pm}(s)}}{(4\pi \tau_{\pm}(s))^{n/2}} dV_g(s).
\]

Since
\[
\int_M \Delta_g \text{tr}_g h \cdot e^{-f} dV_g = \int_M \text{tr}_g h \cdot (e^{-f}) dV_g = \int_M \text{tr}_g \left( -\Delta_g f + \left| g \nabla f \right|^2_g \right) e^{-f} dV_g,
\]
\[
\int_M \nabla^i \nabla^j h_{ij} \cdot e^{-f} dV_g = \int_M h_{ij} \nabla^i \nabla^j (e^{-f}) dV = \int_M h_{ij} \left( -\nabla^i \nabla^j f + \nabla^i f \nabla^j f \right) e^{-f} dV_g,
\]
\[
\int_M \nabla_i \left( \frac{\partial}{\partial s} f \right) \nabla^i f e^{-f} dV_g = \int_M -\frac{\partial}{\partial s} f \left( \Delta_g f - \left| g \nabla f \right|^2_g \right) e^{-f} dV_g,
\]
\[
\int_M \Delta_g (e^{-f}) dV_g = \int_M \left( -\Delta_g f + \left| g \nabla f \right|^2_g \right) e^{-f} dV_g,
\]
and using Lemma 10.1, we obtain

$$\frac{d}{ds}|_{s=0} \nu_{\pm}(g(s), u(s))$$

$$= \int_{M} \frac{\partial}{\partial s}|_{s=0} \tau_{\pm}(s) \left( S_{g,u} + |\nabla f|_g^2 \right) \frac{e^{-f_{\pm}}}{(4\pi \tau_{\pm})^{n/2}} dV_g$$

$$+ \int_{M} \left[ \tau_{\pm} \left( -h^{ij} R_{ij} + \nabla^i \nabla_j f_{\pm} \right) - \Delta_g \left( \tau_{\pm} - h^{ij} \nabla_i \nabla_j f_{\pm} \right) + 2h_{pq} \nabla_p u \nabla_q u 
- 4\nabla_i v \nabla^i u - h_{pq} \nabla^p f_{\pm} \nabla^q f_{\pm} + 2\nabla_i \left( \frac{\partial}{\partial s}|_{s=0} f(s) \right) \nabla^i f \right)$$

$$\mp \left[ \frac{\partial}{\partial s}|_{s=0} f(s) \right] \frac{e^{-f_{\pm}}}{(4\pi \tau_{\pm})^{n/2}} dV_g$$

$$= \int_{M} \left[ \frac{\partial}{\partial s}|_{s=0} \tau_{\pm}(s) \left( |\nabla f|_g^2 + S_{g,u} \right) 
- \tau_{\pm} \left( h^{ij} \nabla_i \nabla_j f_{\pm} + h^{ij} S_{ij} + 4\nabla_i v \cdot \nabla^i u \right) \mp \frac{\partial}{\partial s}|_{s=0} f_{\pm} \right] \frac{e^{-f_{\pm}}}{(4\pi \tau_{\pm})^{n/2}} dV_g$$

$$+ \int_{M} \tau_{\pm} \left( \Delta_g f_{\pm} - |\nabla f|_g^2 \right) \left( \tau_{\pm} - h^{ij} \nabla_i \nabla_j f_{\pm} \right) + 2h_{pq} \nabla_p u \nabla_q u 
- 4\nabla_i v \nabla^i u - h_{pq} \nabla^p f_{\pm} \nabla^q f_{\pm} + 2\nabla_i \left( \frac{\partial}{\partial s}|_{s=0} f(s) \right) \nabla^i f \right)$$

$$\mp \left[ \frac{\partial}{\partial s}|_{s=0} f(s) \right] \frac{e^{-f_{\pm}}}{(4\pi \tau_{\pm})^{n/2}} dV_g.$$
Plugging it into the definition of $B$ yields

\[
B = \int_M \left( -\frac{\partial}{\partial s} \bigg|_{s=0} f_\pm(s) - \frac{n}{2\tau_\pm} \frac{\partial}{\partial s} \bigg|_{s=0} \tau_\pm(s) + \frac{1}{2} \text{tr}_g h \right) \\
\cdot \left[ 2\tau_\pm \left( |g \nabla f_\pm|^2 - \Delta_\psi f_\pm \right) + \nu_\pm(g, u) \right] e^{-f_\pm} \frac{(4\pi\tau_\pm)^{n/2}}{dV_g}
\]

\[
= \int_M \left( -\frac{\partial}{\partial s} \bigg|_{s=0} f_\pm(s) - \frac{n}{2\tau_\pm} \frac{\partial}{\partial s} \bigg|_{s=0} \tau_\pm(s) + \frac{1}{2} \text{tr}_g h \right) \\
\cdot \left[ 2\tau_\pm \left( |g \nabla f_\pm|^2 - \Delta_\psi f_\pm \right) \right] e^{-f_\pm} \frac{(4\pi\tau_\pm)^{n/2}}{dV_g}
\]

where we use the fact that $\int_M \Delta_\psi (e^{-f}) dV_g = 0$. Hence $B$ cancels with the last term in $A$. Therefore, the above variation equals

\[
\frac{d}{ds} \bigg|_{s=0} \nu_\pm(g(s), u(s)) = 0
\]

\[
\int_M \left[ \frac{\partial}{\partial s} \bigg|_{s=0} \tau_\pm(s) \left( |g \nabla f_\pm|^2 + S_{g,u} \pm \frac{n}{2\tau_\pm} \right) - \tau_\pm \left( h^{ij} \nabla_i \nabla_j f + h^{ij} S_{ij} \right) + \frac{1}{2\tau_\pm} \text{tr}_g h + 4v (\langle du, df \rangle - \Delta_\psi u) \right] \frac{e^{-f_\pm}}{(4\pi\tau_\pm)^{n/2}} dV_g.
\]

To prove the theorem, it is sufficient to show that

\[
\int_M \left( |g \nabla f_\pm|^2 + S_{g,u} \pm \frac{n}{2\tau_\pm} \right) e^{-f_\pm} \frac{(4\pi\tau_\pm)^{n/2}}{dV_g} = 0.
\]

Since $M$ is compact, we have

\[
0 = \int_M \Delta_\psi (e^{-f_\pm}) = \int_M \left( -\Delta_\psi f_\pm + |g \nabla f_\pm|^2 \right) e^{-f_\pm} dV.
\]

Hence

\[
\int_M \left( |g \nabla f_\pm|^2 + S_{g,u} \pm \frac{n}{2\tau_\pm} \right) e^{-f_\pm} \frac{(4\pi\tau_\pm)^{n/2}}{dV_g} = 0.
\]

\[
\int_M \left( 2\Delta_\psi f_\pm - |g \nabla f_\pm|^2 \right) e^{-f_\pm} \frac{(4\pi\tau_\pm)^{n/2}}{dV_g} = 0.
\]
Then, Lemma 10.1 now indicates
\[
\int_M \left( |\nabla f_\pm|^2 + S_{g,u} \pm \frac{n}{2\tau_\pm}\right) \frac{e^{-f_\pm}}{(4\pi\tau_\pm)^{n/2}} dV
\]
\[
= \int_M \left( \pm f_\pm \mp n + \nu_\pm(g,u) \pm \frac{n}{2}\right) \frac{e^{-f_\pm}}{(4\pi\tau_\pm)^{n/2}} dV
\]
\[
= \int_M \frac{1}{\tau_\pm} \left( \pm f_\pm \mp n + \nu_\pm(g,u) \right) \frac{e^{-f_\pm}}{(4\pi\tau_\pm)^{n/2}} dV
\]
\[
= \frac{1}{\tau_\pm} \left( \pm \frac{n}{2} - \nu_\pm(g,u) \mp \frac{n}{2} + \nu_\pm(g,u) \right) = 0.
\]
The sign + corresponds to the gradient expanding soliton while − to the gradient shrinker soliton. □

**Corollary 10.3.** Suppose that \((M,g)\) is a compact Riemannian manifold and \(u\) a smooth function on \(M\). Let \(h\) be any symmetric covariant 2-tensor on \(M\) and set \(g(s) := g + sh\). Let \(v\) be any smooth function on \(M\) and \(u(s) := u + sv\). If \(\nu_\pm(g(s),u(s)) = W_\pm(g(s),u(s),f_\pm(s),\tau_\pm(s))\) for some smooth function \(f_\pm(s)\) with \(\int_M e^{-f_\pm(s)/4\pi\tau_\pm(s)} dV = 1\) and a constant \(\tau_\pm(s) > 0\), and \((g,u)\) is a critical point of \(\nu_\pm(\cdot,\cdot)\), then
\[S_{g,u} = \pm \frac{1}{2\tau_\pm} g, \quad f_\pm \equiv \text{constant}.
\]
Thus, if \(W_\pm(g,u,\cdot,\cdot)\) achieve their minimum and \((g,u)\) is a critical point of \(\nu_\pm(\cdot,\cdot)\), then \((M,g,u)\) satisfies the static Einstein vacuum equation.

**Proof.** According to Lemma 10.1 and Theorem 10.2, we have
\[
\tau_\pm \left( -2\Delta_g f_\pm + |\nabla f_\pm|^2_g - S_{g,u} \right) \pm f_\pm \mp n = -\nu_\pm
\]
\[
= - \int_M \left[ \tau_\pm \left( S_{g,u} + |\nabla f_\pm|^2_g \right) \pm f_\pm \mp n \right] \frac{e^{-f_\pm}}{(4\pi\tau_\pm)^{n/2}} dV_g,
\]
and hence
\[
2\Delta_g f_\pm - |\nabla f_\pm|^2_g + S_{g,u} = \int_M \left( S_{g,u} + |\nabla f_\pm|^2_g \right) \frac{e^{-f_\pm}}{(4\pi\tau_\pm)^{n/2}} dV_g
\]
\[
= \int_M \left( S_{g,u} + \Delta_g f_\pm \right) \frac{e^{-f_\pm}}{(4\pi\tau_\pm)^{n/2}} dV_g
\]
\[
= \mp \frac{n}{2\tau_\pm} = S_{g,u} + \Delta_g f_\pm.
\]
From this we get \(\Delta_g f_\pm = |\nabla f_\pm|^2_g\). After taking the integration on both sides, the functions \(f_\pm\) must be constant that imply \(S_{g,u} \pm \frac{1}{2\tau_\pm} g = 0\). □

**Remark 10.4.** In the situation of Corollary 10.3, by normalization, we may choose \(f_\pm = \frac{n}{2}\).
References

[1] Cao, H., Hamilton, R., Ilmanen, T., Gaussian densities and stability for some Ricci solitons, arXiv: math.DG/0401165.
[2] Cao, H., Zhu, M., On second variation of Perelman’s Ricci shrinker entropy, arXiv: math.DG/1008.0842.
[3] Cao, X., Eigenvalues of $(-\Delta + \frac{R}{2})$ on manifolds with nonnegative curvature operator, Math. Ann., 337(2007), 435–441.
[4] Cao, X., First eigenvalues of geometric operators under the Ricci flow, Proc. Amer. Math. Soc., 136(2008), 4075–4078.
[5] Feidman, M., Ilmanen, T., Ni, L., Entropy and reduced distance for Ricci expanders, arXiv: math.DG/0405036.
[6] He, C., Hu, S., Kong, D., Liu, K., Generalized Ricci flow I: Local existence and uniqueness, Topology and physics, 151–171, Nankai Tracts Math., 12, World Sci. Publ., Hackensack, NJ, 2008.
[7] Li, J., Eigenvalues and energy functionals with monotonicity formulae under Ricci flow, Math. Ann., 338(2007), 927–946.
[8] Li, Y., Generalized Ricci flow I: higher derivatives estimates for compact manifolds, arXiv: math.DG/0905.0045.
[9] List, B., Evolution of an extended Ricci flow system, PhD thesis, AEI Potsdam, 2005.
[10] Müller, R., Monotone volume formulas for geometric flows, arXiv: math.DG/0905.2328.
[11] Müller, R., Ricci flow coupled with harmonic map flow, arXiv: math.DG/0912.2907.
[12] Oliynyk, T., Sunneeta, V., Woolgar, E., A gradient flow for worldsheet nonlinear sigma models, Nuclear Phys. B 739(2006), 441–458.
[13] Streets, J., Ricci Yang-Mills flow, PH.D. Thesis, Duck University, 2007.
[14] Streets, J., Regularity and expanding entropy for connection Ricci flow, J. Geom. Phys., 58(2008), 900–912.
[15] Streets, J., Singularity of renormalization group flows, J. Geom. Phys., 59(2009), 8–16.
[16] Streets, J., Ricci Yang-Mills flow on surfaces, Adv. Math., 223(2010), 454–475.
[17] Young, A., Modified Ricci flow on a principal bundle, Ph.D., thesis, University of Texas at Austin, 2008.
[18] Zhu, M., The second variation of the Ricci expanding entropy, arXiv: math.DG/0901.2942.

Department of Mathematics, Harvard University, One Oxford street, Cambridge, MA 02138
E-mail address: yili@math.harvard.edu