Adaptive Sparse Channel Estimation for Time-Variant MIMO Communication Systems

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Abstract—Channel estimation problem is one of the key technical issues in time-variant multiple-input multiple-output (MIMO) communication systems. To estimate the MIMO channel, least mean square (LMS) algorithm was applied to adaptive channel estimation (ACE). Since the MIMO channel is often described by sparse channel model, such sparsity can be exploited to improve the estimation performance by adaptive sparse channel estimation (ASCE) methods using sparse LMS algorithms. However, conventional ASCE methods have two main drawbacks: 1) sensitive to random scale of training signal and 2) unstable in low signal-to-noise ratio (SNR) regime. To overcome the two harmful factors, in this paper, we propose a novel ASCE method using normalized LMS (NLMS) algorithm (ASCE-NLMS). In addition, we also proposed an improved ASCE method using normalized least mean fourth (NLMF) algorithm (ASCE-NLMF). Two proposed methods can exploit the channel sparsity effectively. Also, stability of the proposed methods is confirmed by mathematical derivation. Computer simulation results show that the proposed sparse channel estimation methods can achieve better estimation performance than conventional methods.

Keywords—least mean square (LMS), least mean fourth (LMF), normalized LMF (NLMF), adaptive sparse channel estimation (ASCE), multiple-input multiple-output (MIMO).

I. INTRODUCTION

Signal transmission over multiple-input multiple-output (MIMO) channel is becoming one of mainstream techniques for the next generation communication systems. The major motivation is due to the fact that MIMO technology is a way of using multiple antennas to simultaneously transmit multiple streams of data in wireless communications. MIMO in cellular systems brings improvements on four fronts: improved data rate, improved reliability, improved energy efficiency, and reduced interference. However, coherent receivers require accurate channel state information (CSI) due to the fact that wireless signal propagates over frequency-selective fading channel. In these systems, the basic channel estimation problem is reduced to estimating multiple-input single-output (MISO) channel at each antenna at the receiver side. One of the typical examples is using very large number of antennas (so-called “massive MIMO”) at base station and only one antenna at mobile terminal (as shown in Fig. 1), which makes high data rate communication possible with very low transmit power in a frequency-selective fading channel [1]. Besides, in the high mobility environment, the MIMO channel is subject to time-variant fading (i.e., double-selective fading). The accurate estimation of channel impulse response (CIR) is a crucial and challenging issue in coherent modulation and its accuracy has a significant impact on the overall performance of the communication system.

During last decades, many channel estimation methods were proposed for MIMO-OFDM systems [2–10]. However, all these methods are categorized into two groups. The first group contains the linear channel estimation methods, e.g., least squares (LS) algorithm, based on the assumption of dense CIRs. By applying these approaches, the performance of linear methods depend only on the size of MIMO channel. Note that narrowband MIMO channel may be modeled as dense channel model because of its very short time delay spread; however, broadband MIMO channel is often modeled as sparse channel model [11–13]. A typical example of sparse channel is shown in Fig. 2. It is well known that linear channel estimation methods are relatively simple to implement due to their low computational complexity [4–9]. However, their main drawback is the failure to exploit the inherent channel sparsity. The second group is the sparse channel estimation methods
which use compressive sensing (CS) [14], [15]. Optimal sparse channel estimation often requires that its training signal satisfies restrictive isometry property (RIP) [16] in high probability. However, designing the RIP-satisfied training signal is a non-polynomial (NP) hard problem [17]. However, there exist some proposed methods which are stable with the cost of extra computational burden, especially in time-variant MIMO-OFDM systems. For example, sparse channel estimation method using Dantzig selector was proposed for double-selective fading MIMO systems [9]. However, the proposed method needs to be solved by linear programming which incurs high computational complexity. To reduce complexity, sparse channel estimation methods using greedy iterative algorithms were also proposed in [8], [10]. However, their complexity depends on the number of nonzero taps of channel.

To overcome the two harmful factors, in this paper, we propose a novel ASCE method for MIMO time-variant channel using normalized LMS (NLMS) algorithm (ASCE-NLMS). Additionally, we also propose an improved ASCE methods using a sparse normalized least mean fourth (NLMF) algorithm [18] (ASCE-NLMF). Since NLMF outperforms the NLMS algorithm [19] in achieving a better balance between complexity and estimation performances, in our previous research in [20], stable sparse NLMF algorithm was proposed to achieve better estimation than sparse NLMS algorithm [21]. Computer simulation results confirm the effectiveness of our proposed methods.

The remainder of this paper is organized as follows. A MIMO-OFDM system model is described and problem formulation is given in Section II. In section III, sparse NLMS and sparse NLMF algorithms are introduced and ASCE in time-variant MIMO-OFDM systems is highlighted. Computer simulation results are given in Section IV in order to evaluate and compare performances of the proposed ASCE methods. Finally, we conclude the paper in Section V.

II. SYSTEM MODEL AND PROBLEM FORMULATION

A time-variant MIMO communication system using OFDM modulation, as shown in Fig. 1, is considered. Frequency-domain signal vector $\mathbf{x}_n(t) = [x_{n_1}(t), \ldots, x_{n_1}(t,K-1)]^T$, $n_t = 1,2, \ldots, N_t$ is fed to inverse discrete Fourier transform (IDFT) at the $n_t$-th antenna, where $K$ is the number of subcarriers. Assume that the transmit power is $\|\mathbf{x}_n(t)\|_2^2 = KE_0$. The resultant vector $\mathbf{x}_n(t) \triangleq \mathbf{F}^H\mathbf{x}_n(t)$ is padded with cyclic prefix (CP) of length $L_{CP}$ to avoid inter-block interference (IBI), where $\mathbf{F}$ is $K \times K$ DFT matrix with entries $[\mathbf{F}]_{kq} = 1/K e^{-j2\pi kq/K}$, $k,q=0,1,\ldots,K-1$. After CP removal, the received signal vector for time $t$ is written as $\mathbf{r}$. Then, the received signal $\mathbf{y}$ and input signal vector $\mathbf{x}$ are related by

$$\mathbf{y} = \sum_{n_t=1}^{N} \mathbf{h}_{n_t}^T \mathbf{x}_{n_t} + \mathbf{z} = \mathbf{h}^T \mathbf{x} + \mathbf{z},$$

where $\mathbf{x} = [x_1^T, x_2^T, \ldots, x_{N_t}^T]^T$ combines all of the input signal vectors; additive noise variable $\mathbf{z}$ satisfies $\mathcal{CN}(0,\sigma_n^2)$ and the MIMO channel vector $\mathbf{h}$ can be written as

$$\mathbf{h} = \begin{bmatrix} \mathbf{h}_1^T \mathbf{h}_2^T \ldots \mathbf{h}_{N_t}^T \end{bmatrix}^T \in \mathbb{C}^{N_{\text{ant}} \times 1},$$

where $\mathbf{h}_{n_t}$ ($n_t = 1,2,\ldots, N_t$) is assumed equal $N$-length sparse channel vector from receiver to $n_t$-th antenna. In addition, we also assume that each channel vector $\mathbf{h}_{n_t}$ is only supported by $T$ dominant channel taps. A typical example of 16-paths sparse multipath channel, which is supported by 3 dominant taps, is depicted in Fig. 2. According to the system model in Eq. (1), the $n$-th adaptive updating channel estimation error $e(n)$ can be written as

$$e(n) = y - y(n) = y - \mathbf{h}^T(n)\mathbf{x}(n),$$

where $\mathbf{h}(n)$ denotes an adaptive MIMO channel estimator of $\mathbf{h}$ and $y(n)$ is the output signal. A diagram of ASCE method for MIMO-OFDM communication system was shown in Fig. 3. The goal of ASCE is to estimate MIMO channel $\mathbf{h}$ using error signal $e(n)$ and input training signal $\mathbf{x}(n)$. Traditional ASCE methods using sparse LMS algorithms were proposed to exploit channel sparsity. The cost function of ASCE method is concluded as

$$L_e(n) = \frac{1}{2} e(n)^2 + \lambda_{\text{spar}} \|\mathbf{h}(n)\|_p,$$

where $0 \leq p < 1$ and $\lambda_{\text{spar}} \geq 0$ denotes the sparse regulation parameters which trade off the mean square error and sparsity of $\mathbf{h}$. Without loss of generality, corresponding update equation of ASCE methods can be written as
\( h(n + 1) = h(n) - \mu_s \frac{\partial_j e(n)}{\partial h(n)} \)

\[ = h(n) + \mu_s e(n)x(n) - \rho_{\text{stp}} \frac{||h(n)||_2^p \text{sgn}(h(n))}{\sigma + ||h(n)||_2^{1-p}}, \] (5)

where \( \rho_{\text{stp}} = \mu_s \lambda_{\text{stp}} \) and \( \mu_s \in (0, \gamma_{\text{max}}^{-1}) \) is the step size of LMS gradient descend and \( \gamma_{\text{max}} \) is the maximum eigenvalue of the covariance matrix \( R = E\{x(n)x^T(n)\} \).

### III. PROPOSED ASCE METHODS

#### A. ASCE - NLMS

A \( L_p \)-norm sparse penalty on cost function of NLMS is considered to produce sparse channel estimator, since this penalty term forces the values for channel taps of \( h \) to approach zero. It is termed as LP-NLMS and first was proposed for a single-antenna systems in [21]. According to Eqs. (4) and (5), update equation of LP-NLMS based ASCE method is given by

\[ h(n + 1) = h(n) + \mu_s e(n)x(n) - \rho_{\text{stp}} \frac{||h(n)||_2^p \text{sgn}(h(n))}{\sigma + ||h(n)||_2^{1-p}} \] (6)

where \( ||\cdot||_2 \) is the Euclidean norm operator and \( ||x||_2^p = \sum_i |x_i|^2 \). If \( p = 0 \), then the zero-attracting which forces the channel taps values of \( h \) to approach zero is called \( L_0 \)-norm penalty or L0-NLMS [21] and its cost function is given by

\[ \sum_{i=0}^N |\theta_i| \] (7)

where \( |\theta_i| \) is the L0-norm operator that counts the number of nonzero taps in \( h \) and \( \lambda_{\text{sto}} \) is a regularization parameter to balance the estimation error and sparse penalty. Since solving the \( L_0 \)-norm minimization is a NP-hard problem [17], we replace it with an approximate continuous function [22]

\[ ||h||_0 \approx \sum_{i=0}^N \lambda_{\text{sto}} |\theta_i| \] (8)

According to the approximate function, L0-LMS cost function can be revised as

\[ L_{\text{sto}}(n) = \frac{1}{2} e^2(n) + \lambda_{\text{sto}} ||h(n)||^2 \]

Then, the update equation of L0-LMS based ASCE can be derived by

\[ h(n + 1) = h(n) + \mu_s e(n)x(n) - \rho_{\text{sto}} \lambda_{\text{sto}} \text{sgn}(h(n)) e^{-\beta |h(n)|}, \] (9)

where \( \rho_{\text{sto}} = \mu_s \lambda_{\text{sto}} \). It is worth mentioning that the exponential function in (10) will cause high computational complexity. To reduce the computational complexity, the first order Taylor series expansion of the exponential functions is considered as [22]

\[ e^{-\beta |h|} \approx \begin{cases} 1 - \beta |h|, & \text{when } |h| \leq 1/\beta \\ 0, & \text{others.} \end{cases} \] (11)

where \( h \) is any element of channel vector \( h \). Then, the update equation of L0-NLMS based adaptive sparse channel estimation is given by

\[ h(n + 1) = h(n) + \mu_s e(n)x(n) - \rho_{\text{sto}} \lambda_{\text{sto}} \text{sgn}(h(n)) e^{-\beta |h(n)|}, \] (10)

where \( f(h) \) is defined as

\[ f(h) = \begin{cases} 2\beta^2 h - 2\beta \text{sgn}(h), & \text{when } |h| \leq 1/\beta \\ 0, & \text{others.} \end{cases} \] (15)

#### B. ASCE-NLMF

In this section, we propose another improved ASCE methods using sparse NLMF algorithms. First, the cost function, \( L_{\text{nlmf}} \), of standard LMF can be constructed as

\[ L_{\text{f}}(n) = \frac{1}{4} e^4(n) \] (16)

The update equation of ASCE using LMF algorithm can be derived by

\[ h(n + 1) = h(n) + \mu_f e^3(n)x(n) \] (17)

where \( \mu_f \in (0, 2) \) is a gradient descend step-size which controls the convergence speed and steady-state performance; The LMF algorithm only works stable in low SNR regime [23], however, based on our previous research in [21], ACE using the normalized LMF is stable for different SNR regime. The update equation of NLME-based ASCE is given by

\[ h(n + 1) = h(n) + \mu_f \frac{e^3(n)x(n)}{||x||_2^2 (||x||_2^2 + e^2(n))} \] (18)

where \( \mu_f(n) = \mu_f e^2(n) / (||x||_2^2 + e^2(n)) \). Here, we observe that when \( e^2(n) \gg ||x||_2^2 \), then \( \mu_f(n) \rightarrow \mu_f \); when \( e^2(n) \approx ||x||_2^2 \), then \( \mu_f(n) \rightarrow \mu_f / 2 \); when \( e^2(n) \ll ||x||_2^2 \), then \( \mu_f(n) \rightarrow 0 \). Hence, NLME algorithm in Eq. (18) is stable which is equivalent to NLMS algorithm in Eq. (6). According to the previous research in [21], regarding the single-antenna communication systems, if the standard NLMF algorithm is stable, then its corresponding ASCE method using sparse NLMF algorithm is also stable. Hence, stable ASCE using sparse NLMF algorithms are presented as follows.

For the MIMO channel vector \( h(n) \), its cost function of ASCE using LP-NLMF algorithm is given by

\[ L_{\text{f,lp}}(n) = \frac{1}{4} e^4(n) + \lambda_{\text{f,lp}} \|h(n)\|_2 \] (19)

where \( \lambda_{\text{f,lp}} \) is a regularization parameter which trades off the fourth-order mismatching estimation error and \( L_p \)-norm sparse penalty of \( h \). The update equation of ASCE method using LP-NLMF can be derived as

\[ h(n + 1) = h(n) + \mu_f \frac{e^3(n)x(n)}{||x||_2^2} - \rho_{\text{f,lp}} \lambda_{\text{f,lp}} \frac{||h(n)||_2^p \text{sgn}(h(n))}{\sigma + ||h(n)||_2^{1-p}} \] (20)

where \( \rho_{\text{f,lp}} = \mu_f \lambda_{\text{f,lp}} \) depends on step-size \( \mu_f \) and parameter \( \lambda_{\text{f,lp}} \). Similarly, cost function of ASCE method using L0-NLMF algorithm can also be written as

\[ L_{\text{f,10}}(n) = \frac{1}{4} e^4(n) + \lambda_{\text{f,10}} \|h(n)\|_0 \] (21)

where \( \lambda_{\text{f,10}} > 0 \) is a regularization parameter which trades off the fourth-order mismatching estimation error and sparseness of MIMO channel. Then, its updating equation algorithm can be written as
\( \mathbf{h}(n + 1) = \mathbf{h}(n) + \mu_f(n) \frac{e(n) \mathbf{h}(n)}{\| \mathbf{h}(n) \|^2} - \beta_2 / (\mathbf{h}(n)), \quad (22) \)

where \( \beta_2 = \mu_f \lambda_{f0} \) and \( f(\mathbf{h}(n)) \) is an approximate sparse \( L_0 \)-norm function which was defined in Eq. (15).

IV. NUMERICAL SIMULATIONS

In this section, the proposed ASCE estimators using 1000 independent Monte-Carlo runs for averaging. The length of channel vector \( \mathbf{h}_{nt} \) between each transmitter and receiver antenna is set as \( N = 16 \) and its number of dominant taps is set as \( T = 1 \) and 3, respectively. Values for dominant channel taps follow a Gaussian distribution and their positions are randomly allocated within the length of \( \mathbf{h}_{nt} \) with \( E[|| \mathbf{h}_{nt} ||^2] = 1 \). The received signal-to-noise ratio (SNR) is defined as \( 20 \log (E_0/\sigma^n_t) \), where \( E_0 = 1 \) is the transmit power at each antenna. Here, we set the SNR as 3dB, 6dB and 9dB in computer simulation. All of the step sizes and regularization parameters are listed in Tab. I. The estimation performance is evaluated by average mean square error (MSE) which is defined by

\[
\text{Average MSE}(\mathbf{h}(n)) = E[\| \mathbf{h} - \mathbf{h}(n) \|^2],
\]

where \( E[\cdot] \) denotes the expectation operator, \( \mathbf{h} \) and \( \mathbf{h}(n) \) are the actual MIMO channel vector and its \( n \)-th adaptive channel estimator, respectively.

| TABLE I. SIMULATION PARAMETERS. |
|----------------------------------|
| Parameters                      | Values                           |
|----------------------------------|
| Gradient descend step-size: \( \mu_g \) | 0.5                             |
| Gradient descend step-size: \( \mu_f \) | 1.5                             |
| Regularization parameter: \( \lambda_{g0} \) | \((2e - 4)\sigma^n_g \log (N/T)\) |
| Regularization parameter: \( \lambda_{f0} \) | \((2e - 6)\sigma^n_g \log (N/T)\) |
| Regularization parameter: \( \lambda_{g0} \) | \((2e - 3)\sigma^n_g \log (N/T)\) |
| Regularization parameter: \( \lambda_{f0} \) | \((2e - 5)\sigma^n_g \log (N/T)\) |

In the first example, the proposed methods are evaluated in Fig. 4 (\( T = 1 \)) and Fig. 5 (\( T = 3 \)) at SNR = 3dB. To balance the estimation performance and computational complexity, the step-size of sparse NLMS algorithms and sparse NLMF algorithms are set as \( \mu_g = 0.5 \) and \( \mu_f = 1.5 \), respectively. Note that the step-size \( \mu_g = 0.5 \) was also recommended by the paper [21]. As the two figures show, ASCE-NLMS method achieves better estimation performance than ACE-NLMS. Similarly, ASCE-NLMF method also achieves better estimation performance than ACE-NLMS method. We can also observe that ASCE-NLMF method outperforms the ASCE-NLMS method significantly but with the cost of higher computational complexity (iterative times). Relatively, the computational complexity of ASCE-NLMS is very low [21]. As a result, selecting a reasonable ASCE method depends on the requirements of the system to be designed.

In the second experiment, the proposed methods are evaluated at SNR regimes 6dB and 9dB as shown in Figs. 6-7. Again, we can notice improvement over conventional methods. Please note that computational complexity of ASCE-NLMF method increases with SNR. Our future work is finding a solution for reducing the complexity in ASCE-NLMF.

V. CONCLUSION

In this paper, we proposed a ASCE method using sparse NLMS and sparse NLMF algorithms for time-variant MISO-OFDM systems. First of all, system model was formulated to ensure each MISO channel vector can be estimated. Secondly, cost functions of the two proposed methods were constructed using sparse penalties, i.e., \( L_p \)-norm and \( L_0 \)-norm. Later, MISO channel vector was estimated using ASCE method. Simulation results indicate that the proposed ASCE-NLMS method achieves a better performance than the standard ACE-NLMS method without much increase in computational complexity. The simulation results also demonstrate that the proposed ASCE-NLMS method is even better than ASCE-NLMS method but has a higher amount of computation complexity.
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