Quasi-Optimal Energy-Efficient Leader Election Algorithms in Radio Networks

Christian LAVault∗ Jean-François MARCKERT†
Vlady RAVELOMANANA‡

Abstract

Radio networks (RN) are distributed systems (ad hoc networks) consisting in $n \geq 2$ radio stations. Assuming the number $n$ unknown, two distinct models of RN without collision detection (no-CD) are addressed: the model with weak no-CD RN and the one with strong no-CD RN. We design and analyze two distributed leader election protocols, each one running in each of the above two (no-CD RN) models, respectively. Both randomized protocols are shown to elect a leader within $O(\log(n))$ expected time, with no station being awake for more than $O(\log \log(n))$ time slots (such algorithms are said to be energy-efficient). Therefore, a new class of efficient algorithms is set up that match the $\Omega(\log(n))$ time lower-bound established by Kushilevitz and Mansour in [11].

1 Introduction

Electing a leader is a fundamental problem in distributed systems and it is studied in a variety of contexts including radio networks [3]. A radio network (RN, for short) can be viewed as a distributed system of $n$ radio stations with no central controller. The stations are bulk-produced, hand-held devices and are also assumed to be indistinguishable: no identification numbers (or IDs) are available. A large body of research has already focused on finding efficient solutions to elect one station among an $n$-stations RN under various assumptions (see e.g. [3, 11, 17]). It is also assumed that the stations run on batteries. Therefore, saving battery power is important, since recharging batteries may not be possible in standard working conditions. We are interested in designing power-saving protocols (also called energy-efficient protocols). The present work is motivated by various applications in emerging technologies: from wireless communications, cellular telephony, cellular data, etc., to simple hand-held multimedia services.

∗Corresponding author: LIPN, CNRS UMR 7030, Université Paris 13 – 99, av. J.-B. Clément 93430 Villetaneuse, France. E-mail: lavault@lipn.univ-paris13.fr
†CNRS, LaBRI Université Bordeaux 1, 351, cours de la Libération 33405 Talence cedex, France, E-mail: marckert@labri.fr
‡LIPN, UMR CNRS 7030, Université Paris 13, France. E-mail: vlad@lipn.univ-paris13.fr
The models. As customary, the time is assumed to be slotted, the stations work synchronously and they have no IDs available. No a priori knowledge is assumed on the number \(n \geq 2\) of stations involved in the RN: neither a (non-trivial) lower-bound nor an upper-bound on \(n\). During a time slot, a station may be awake or sleeping. When sleeping, a station is unable to listen or to send a message. Awake stations communicate globally, i.e. the underlying graph is a clique, by using a unique radio frequency channel with no collision detection (no-CD for short) mechanism. In each time slot, the status of the unique channel can be in one of the following two states:
- either SINGLE: there is exactly one transmitting station,
- or NULL: there is either no station or more than two (\(\geq 2\)) broadcasting stations.

When the status is NULL, each listening station hears some noise and can not decide whether 0 or more than 2 station are broadcasting. When the status is SINGLE, each listening station hears clearly the message sent by the unique broadcasting station.

In the weak no-CD model of RN, during a time slot each awake station may either send (broadcast) a message or listen to the channel, exclusively. By contrast, in the strong no-CD model of RN, both operations can be performed simultaneously by each awake station, during a time slot. Hence, in the strong no-CD model, when exactly one station sends at time slot \(t\), then all the stations that listen at time \(t\), transmitter included, eventually receive the message. In the literature, the no-CD RN usually means the strong model of RN, see e.g. [11, 14]. In the weak no-CD case, such a transmitting station is not aware of the channel status.

Related works. The model of RN considered is the broadcast network model (see e.g. [3]). In this setting, the results of Willard [17], Greenberg et al. [7] (with collision detection) or Kushilevitz and Mansour [11] (no-CD) for example, are among the most popular leader election protocols.

In such a model, Massey and Mathys [12] serves as a global reference for basic conflict-resolution based protocols. Previous researches on RN with multiple-access channel mainly concern stations that are kept awake during all the running time of a protocol even when such stations are the “very first losers” of a coin flipping game algorithm [15]. In [9], the authors design an energy-efficient protocol (with \(o(\log \log(n))\) energy cost) that approximate \(n\) up to a constant factor. However, the running time achieved is \(O(\log^{2+\epsilon}(n))\) in strong no-CD RN. Also, an important issue in RN is to perform distribution analysis of various randomized election protocols as derived in [4, 8] for example.

Our results. Two leader election protocols are provided in the present paper. The first one (Algorithm 1) is designed for the strong no-CD model of RN, while the second one (Algorithm 2) is designed for the weak no-CD model of RN. Both are double-loop randomized algorithms, which use a simple coin-tossing procedure (rejection algorithms).
Our leader election protocols achieve a (quasi) optimal $O(\log n)$ average running time complexity, with no station in the RN being awake for more than $O(\log \log (n))$ time slots. Indeed, both algorithms match the $\Omega(\log n)$ time lower-bound established in [11] and also allow the stations to keep sleeping most of the time. In other words, each algorithm greatly reduces the total awake time slots of the $n$ stations: shrinking from the usual $O(n \log n)$ down to $O(n \log \log n)$, while their expected time complexity still remains $O(\log n)$. Our protocols are thus “energy-efficient” and suitable for hand-held devices working with batteries.

Besides the algorithms use a parameter $\alpha$ which works as a flexible regulator. By tuning the value of $\alpha$ the running time ratio of each protocol to its energy consumption may be adjusted: the running time and the awake duration are functions of $\alpha$.

Furthermore, the design of Algorithms 1 and 2 suggests that within both the weak and the strong no-CD RN, the average time complexity of each algorithm only differs from a slight constant factor. Also, our results improve on [13].

**Outline of the paper.** In Section 2, we present Algorithm 1 and Algorithm 2, and the main complexity results are given: Theorem 1 and Theorem 2, corresponding to Algorithm 1 and Algorithm 2. Section 3 and 4 are devoted to the analysis of both algorithms, by means of tight asymptotic techniques.

## 2 Algorithms and Results

Both algorithms rely on the intuitive evidence that all stations must be awake altogether within a sequence of predetermined time slots in order to be informed that the election succeeds or fails.

To realize the election a first naive idea is to have stations using probabilities $1/2$, $1/4$, ... to wake up and broadcast. This solution is not correct since with probability $> 0$ never a station ever broadcasts alone. In order to correct the failure we will plan an unbounded sequence of rounds with predetermined length. Awake time slots are programmed at the end of each rounds in order to allow all stations to detect the possible termination of the session.

In the following, we let $\alpha$ denote a real (tuning) parameter value, which is required to be $> 1$ (this is explained in Remarks 2 and 3).

### 2.1 Algorithm 1

In Algorithm 1 the stations work independently. Given a round $j$ in the outer loop (repeat-until loop), during the execution time of the inner loop each station randomly chooses to sleep or to be awake: in this last case it listens and broadcast, simultaneously. If a unique station is broadcasting, this station knows the status of the radio channel; if the status is SINGLE, it becomes a candidate. At the end of round $j$, every station wakes up and listens to the channel and the candidates broadcast. If there is a single
candidate, the status is SINGLE again, and this candidate is elected. Every listening station knows the channel status, and is informed that the election is done. Otherwise, the next round begins.

```plaintext
round ← 1;
Repeat
    For k from 1 to ⌈α\textsuperscript{round}⌉ do
        /* probabilistic phase */
        Each station wakes up independently with probability 1/2\textsuperscript{k}.
        An awake station listens and broadcasts
        If a unique station broadcasts Then it becomes a candidate station EndIf
    EndFor
    /* deterministic phase */
    At the end of each round, all stations wake up, listen, and in addition all candidate stations broadcast;
    If there is a unique candidate then it is elected EndIf;
    round ← round + 1;
until a station is elected
```

Algorithm 1. Leader election protocol for strong no-CD RN

The brackets in both algorithm represent the actions that take place in one time slot. Notice that the content of the broadcasting message is not specified, since it has no importance. The status “candidate” is valid for one round duration only.

**Definition and Notation 1** For the sake of simplicity, the following notations are used throughout the paper. We let

\[ j^* \equiv j^*(n) \overset{\text{def}}{=} \lceil \log_\alpha \log_2(n) \rceil. \] (1)

Let also \( C : \mathbb{R}^2 \rightarrow \mathbb{R} \) defined by

\[ C(x, y) \overset{\text{def}}{=} \frac{xy^3}{(y - 1)(1 - y(1 - x))}. \] (2)

We have

**Theorem 1** Let \( \alpha \in (1, 1.1743\ldots) \) and \( p_1^* = .14846\ldots \). On the average, Algorithm 1 elects a leader in at most \( C(p_1^*, \alpha) \log_2(n) + O(\log \log n) \) time slots, with no station being awake for more than \( 2 \log_\alpha \log_2(n) \left( 1 + o(1) \right) \) mean time slots.
2.2 Algorithm 2

In the case of the weak no-CD model of RN a potential candidate alone cannot be aware of its status since it cannot broadcast and listen simultaneously. The awake stations choose to broadcasts or (exclusively) to listen. In the inner loop of Algorithm 2 any exclusively broadcasting station is called an initiator; when there is a unique initiator, a station that is listening to the channel, hears clearly the message. Such a station is said to be a witness. Witnesses are intended to acknowledge an initiator in the case when there is exactly one initiator.

\[
\text{round} \leftarrow 1;
\]

\textbf{Repeat}

\textbf{For} \( k \) from 1 to \( \lceil \alpha^{\text{round}} \rceil \) \textbf{do} /* probabilistic phase */

\begin{itemize}
  \item Each station wakes up independently with probability \( 1/2^k \);
  \item With probability \( 1/2 \), each awake station \textit{either} broadcasts the message \( \langle k \rangle \) \textit{or} listens, exclusively;
  \item If there is a unique initiator, the status is SINGLE;
  \item The witness(es) record(s) the value \( \langle k \rangle \)
\end{itemize}

\textbf{EndFor} /* deterministic phase */

\begin{itemize}
  \item At the end of each round, all stations wake up;
  \item All witnesses forward the recorded message;
  \item If the status is SINGLE
  \begin{itemize}
    \item there is a unique witness, the other stations receive the message \( \langle k \rangle \)
    \item Then the unique initiator of the message \( \langle k \rangle \) is elected
    \item \quad and replies to all the stations to advise of its status \textbf{EndIf}
  \end{itemize}
\end{itemize}

\( \text{round} \leftarrow \text{round} + 1; \)

\textbf{until} a station is elected.

\textbf{Algorithm 2. Leader election protocol for weak no-CD RN}

During the last deterministic phase all stations wake up. An election takes place in a round if this round is the first when there is a unique time slot in which there remain exactly a unique initiator and a unique witness. When a station is a witness, it continues to behave as it were not. Hence, a witness can be a witness twice or more, or even be an initiator. This is obviously not optimal but simpler for the analysis.

We have

\textbf{Theorem 2} Let \( \alpha \in (1, 1.0861 \ldots) \) and \( p_2^* = .07929 \ldots \). On the average, Algorithm 2 elects a leader in at most \( \mathcal{O}(p_2^* \alpha \log_2(n)) + \mathcal{O}(\log \log n) \) time slots, with no station being awake for more than \( 5/2 \log_\alpha \log_2(n) \left( 1 + o(1) \right) \) mean time slots.
3 Analysis of Algorithm 1

Assume that Algorithm 1 begins with its variable round = \( j \), and let \( p_j \) be the probability that one station is elected at the end of this round \( j \). One may also view \( p_j \) has the conditional probability that an election occurs at round \( j \) knowing that it did not occur before. Within that round, that is for \( k \) ranging from 1 to \( \lceil \alpha^j \rceil \), every station decides to broadcast with the sequence of probabilities \( \left( \frac{1}{2^k} \right)^{1 \leq k \leq \lceil \alpha^j \rceil} \).

The probability \( \rho(i,n) \) that there is exactly one candidate for \( k = i \) in a round is

\[
\rho(i,n) = \frac{n}{2^i} \left( 1 - \frac{1}{2^i} \right)^{n-1}.
\]

We then have

\[
p_j = \sum_{k=1}^{\lceil \alpha^j \rceil} \rho(k,n) \prod_{i=1, \neq k}^{\lceil \alpha^j \rceil} (1 - \rho(i,n)) = \sum_{k=1}^{\lceil \alpha^j \rceil} \rho(k,n) \left( 1 - \rho(k,n) \right)^{-1} \prod_{i=1}^{\lceil \alpha^j \rceil} (1 - \rho(i,n))
\]

(3)

and \( p_j = t_j s_j \), with

\[
t_j \equiv \sum_{m=0}^{\infty} \sum_{k=1}^{\lceil \alpha^j \rceil} \rho(k,n)^{(m+1)} \quad \text{and} \quad s_j \equiv \prod_{i=1}^{\lceil \alpha^j \rceil} (1 - \rho(i,n)).
\]

(4)

Note that \( s_j \) represents the probability of having no candidate in the \( j \)th round.

**Remark 1** Simple considerations show that when \( 2^{\alpha^j} \ll n \), the probability \( s_j \) is close to 1 (and is “far from” 1 when \( 2^{\alpha^j} \gg n \)). This remark explains the occurrences of the crucial values \( n/2^{\alpha^j} \) and the definition of \( j^* \) in Eq. (1).

3.1 Two Lemmas for a Lower Bound on \( p_j \)

Lemma 1 provides a lower bound on the finite product denoted by \( s_j \) in Eq. (4).

**Lemma 1** Let \( j \equiv j(n) \) such that \( j(n) \to +\infty \) and \( n/2^{\alpha^j} \to 0 \). We have

\[
\liminf_{n} s_j \geq .1809\ldots
\]

**Proof:** We divide the product \( s_j \) in (4) as follows: for any \( r \in \{2, \ldots, \lceil \alpha^j \rceil \} \),

\[
s_j = \prod_{i=1}^{r-1} (1 - \rho(i,n)) \times \prod_{i=r}^{\lceil \alpha^j \rceil} (1 - \rho(i,n)).
\]

(5)

Since for any \( a \in [0,1] \) and \( n \geq 1 \), \( (1 - a)^n \leq e^{-an} \), we have for any \( i \geq 1 \),

\[
1 - \rho(i,n) \geq 1 - \frac{n}{2^i} \exp \left( -\frac{n}{2^i} \right) \geq 1 - \frac{n}{2^i} \exp \left( -\frac{n}{2^i} \right) e^{1/2};
\]

(6)
and more precisely, for \( i \in \{ r, \ldots, \lceil \alpha \rceil \} \), with \( r \) large enough,

\[
1 - \rho(i,n) \geq 1 - \frac{n}{2^r} \exp \left( -\frac{n}{2^r} \right) \exp \left( \frac{1}{2^r} \right) \geq 1 - \frac{n}{2^r} \exp \left( -\frac{n}{2^r} \right) \left( 1 + \frac{2}{2^r} \right). \tag{7}
\]

Now we let \( r \equiv r(n) = \lfloor 1/2 \log_2 (n) \rfloor \), ensuring that \( 2^r / \sqrt{n} \) is bounded. A simple bounding argument in Eq. (6) shows that \( \prod_{i=1}^{r-1} (1 - \rho(i,n)) \to 1 \) when \( n \to \infty \).

Thus, using also inequation (7), Eq. (5) yields

\[
\lim inf_n s_j \geq \exp \left( \sum_{i=r}^{\lceil \alpha \rceil} \ln \left( 1 - \left( 1 + \frac{2}{2^r} \right) \frac{n}{2^r} \exp \left( -\frac{n}{2^r} \right) \right) \right) \geq \exp \left( -\sum_{m \geq 1} \frac{(1 + \frac{2}{2^r})^m (m!)^2}{(\ln 2)^m 2^m} \exp \left( -\frac{nm}{2^r} \right) \right). \tag{8}
\]

Denote by \( A_n \) the right hand side of the inequality. Computing the second sum (inside the exponential in \( A_n \)) is completed through asymptotic approximations using the Mellin transform in Lemma 4 given in Appendix A (this is possible since \( n/2^{\alpha'} \to 0 \) by assumption). By Lemma 4,

\[
A_n \geq \exp \left( o(1) - \sum_{m \geq 1} \frac{(1 + \frac{2}{2^r})^m (m!)^2}{(\ln 2)^m 2^m} \sup_\nu |U_\nu(\log_2 n)| \right), \tag{9}
\]

where \( \sup_\nu |U_\nu(z)| < .024234 \) for all \( z \), as stated in Lemma 4 (Appendix A).

Therefore, the third term in Eq. (9) is bounded from below by

\[
\exp \left( -0.024234 \sum_{m \geq 1} \frac{1}{m^2} \right) = .96092 \ldots
\]

Next, the second term within the exponential in Eq. (9) expresses as

\[
\sum_{m=1}^{\infty} \frac{(1 + \frac{2}{2^r})^m m!}{(\ln 2)^m m^{m+2}} \leq \sum_{m=1}^{n^{1/6}} \frac{(1 + \frac{2}{2^r})^m m!}{(\ln 2)^m m^{m+2}} + \sum_{m=n^{1/6}+1}^{\infty} \frac{2^m m!}{(\ln 2)^m m^{m+2}}. \tag{10}
\]

When \( n \) (and so \( r \)) tends to \( +\infty \), the first sum on the right hand side of Eq. (10) converges to \( \sum_{m \geq 1} \frac{m!}{(\ln 2)^m m^{m+2}} = 1.6702 \ldots \), as a consequence of Lebesgue’s dominated convergence theorem. And the second term goes to 0, as derived from Stirling formula. Finally, combining all these facts we obtain the announced lower bound on \( s_j \). \( \square \)

The following Lemma 2 provides a lower bound on \( \lim inf_n p_j \).
**Lemma 2** Let \( j \equiv j(n) \) such that \( j(n) \to +\infty \) and \( n/2^{\alpha j} \to 0 \). We have
\[
\liminf_n p_j > p_1^* = .14846 \ldots
\]

**Proof:** Since \((1 - x) \geq \exp(-2x)\) for \( x \in [0,1/2] \), we get the following
\[
\sum_{k=1}^{[\alpha j]} (\rho(k,n))^{(m+1)} \\
\geq \sum_{k=1}^{[\alpha j]} \left( \frac{n}{2^k} \exp\left( -\frac{n - 1}{2^k - 1} \right) \right)^{(m+1)} \\
\geq \sum_{k=1}^{[\alpha j]} \frac{1}{2^{m+1}} \left( \frac{n}{2^k} \right)^{m+1} \exp\left( -\frac{n(m+1)}{2^{k-1}} \right) \\
+ \frac{1}{2^{m+1}} \left( \frac{n}{2^k} \right)^{m+1} \exp\left( -\frac{n(m+1)}{2^{k-1}} \right) \\
= \frac{1}{2^{m+1}} \left( \frac{m+1}{m+1} \right)! \left( \frac{n}{2^{m+1}} \right)^{m+1} + O\left( \frac{\log_2(n)}{n^{m+1}} + \frac{1}{n^{2m+1}} \right).
\]

By assumption, \( n/2^{\alpha j} \to 0 \). So, the latter expression comes from Lemma 4, where the term \( U_m(z) \) is defined in Eq. (18). Now, summing on \( m \) in Eq. (4) we derive
\[
t_j \geq O\left( \frac{n}{2^{\alpha j}} + \frac{1}{n} \right) + \sum_{m=1}^{\infty} \frac{m!}{2^m m^{m+1} \ln 2} - \sum_{m=1}^{\infty} \sup_{t \geq 0} \left| U_t \right| \frac{\log_2(n)}{m^2 4^m}.
\]
By Eq. (19), numerical evaluation of the sums (with Maple) give \( \liminf_n t_j \geq .82092 \ldots \)

Finally, by using both lower bounds on \( s_j \) and \( t_j \) (in Lemma 1 and in the above proof, resp.) we obtain the desired lower bound on \( \liminf_n p_j \): \( p_1^* = .14846 \ldots \)

**3.2 Proof of Theorem 1**

To prove Theorem 1, we use the following Lemma 3 that allows us to control the mean of the quantities of interests, whenever having a bound on the probability of success in each round.

**Lemma 3** Let \((X_i)_{i \geq 1}\) and \((Y_i)_{i \geq 1}\) be two sequences of independent Bernoulli random variables, denoted by \( B(P_i) \) and \( B(Q_i) \), respectively, and such that \( P_i \geq Q_i \) for any \( i \).

By definition,
\[
\mathbb{P}(X_i = 1) = 1 - \mathbb{P}(X_i = 0) = P_i \quad \text{and} \quad \mathbb{P}(Y_i = 1) = 1 - \mathbb{P}(Y_i = 0) = Q_i.
\]

Let \( H = \inf\{ j, X_j = 1 \} \) and \( K = \inf\{ j, Y_j = 1 \} \), which may be regarded as a first success in each sequence \( X_i \) and \( Y_i \) (resp.). Then, the “stochastic inequality” \( H \leq S K \) holds: for any non-negative integer \( k \), \( \mathbb{P}(H \leq k) \geq \mathbb{P}(K \leq k) \).
Moreover, for any non-decreasing function \( f \),

\[
\mathbb{E}(f(H)) \leq \mathbb{E}(f(K)).
\]  

(11)

**Proof:** The first part of the Lemma can be proved by constructing a probability space \( \Omega \) in which the sequences of r.v. \( (X_i) \) and \( (Y_i) \) “live” and in which, for each \( \omega \in \Omega \), \( X_i(\omega) \geq Y_i(\omega) \). Since for any \( \omega \), \( K(\omega) \geq H(\omega) \), the stochastic order is a simple consequence of this almost sure order on \( \Omega \). Next, for any non-decreasing function \( f \), \( f(K(\omega)) \geq f(H(\omega)) \) also holds almost surely and whence Eq. (11).

We come back to the proof of Theorem 1. It is straightforward to check that, when \( n \to \infty \), \( n/2^{(j^*+1)} \to 0 \). According to Lemma 2, if \( n \) is large enough,

\[
p_j \geq p_1^* \mathbb{I}_{j \geq j^*+1}
\]  

(12)

As a consequence, let \( N_1 \) denote the number of rounds in Algorithm 1 and \( N_1' = j^*+G \) where \( G \) is a geometric random variable with parameter \( p_1^* \), then

\[
N_1 \leq S(N_1'),
\]  

(13)

\( N_1 \) is smaller with respect to the stochastic order than \( N_1' \).

We recall that the geometrical distribution with parameter \( p \) is given by \( p(1-p)^k \) for any \( k \geq 1 \); this is the law of the first success in a sequence of independent Bernoulli random variables with parameter \( p \).

To show Eq. (13), notice first that \( N_1 \) has the same distribution as \( \inf\{i, X_i = 1\} \), where the \( (X_i) \) are independent and \( X_i \) is \( B(p_i) \)-distributed.

Next, \( N_1' = \inf\{i, Y_i = 1\} \), where \( Y_i \) is \( B(q_i) \)-distributed for \( q_i = p_1^* \mathbb{I}_{j \geq j^*+1} \). Indeed, the first \( j^* \) trials fail and afterwards, each trial results in a success with probability \( p_1^* \).

Finally, Eq. (12) and Lemma 11 allow to conclude,

\[
\mathbb{E}(N_1) \leq \mathbb{E}(N_1') = j^* + 1/p_1^* = \log_\alpha \log_2(n) + \mathcal{O}(1).
\]

Let \( T_1 \equiv T_1(n) \) be the time needed to elect a leader in Algorithm 1. Since \( N_1' \) is larger than \( N_1 \) for the stochastic order and since \( r \mapsto \sum_{i=1}^{r} \lceil \alpha^j \rceil \) is non-decreasing, by Lemma 3,

\[
\mathbb{E}(T_1) = \mathbb{E} \left( \sum_{j=1}^{N_1} \lceil \alpha^j \rceil \right) \leq \mathbb{E} \left( \sum_{j=1}^{N_1'} \lceil \alpha^j \rceil \right) \leq \sum_{k=1}^{+\infty} j^*+k \sum_{j=1}^{k} (1+\alpha^j)p_1^*(1-p_1^*)^{k-1} \]

\[
\leq C(p_1^*, \alpha) \log_2(n) + \mathcal{O}(\log \log n).
\]  

(14)

During a round, the mean number of awake time slots for a given station is at most 2. (Two at the end, one from the contribution of \( \sum_{k=1}^{j^*} 1/2^k \), 1/2\(^k\) being the probability to be awake at time slot \( k \).)

Since the number of rounds is smaller than, say: \( \log_\alpha \log_2(n) + \log \log \log(n) \) with probability going to 1, we get the announced result. 

\( \square \)
Remark 2 It is easily seen that the algorithm and the convergence of the double sum in Eq. (14) (resp.) require the conditions $\alpha > 1$ and $\alpha (1 - p^*_1) < 1$, with $p^*_1 = .14846$ (resp.). The value of $\alpha$ may thus be chosen in the range $(1, 1.743\ldots)$, so as to achieve a tradeoff between the average execution time of the algorithm and the global awake time. Thus, the minimum value of the constant $C(p^*_1, \alpha)$ is $C(p^*_1, \tilde{\alpha}) \approx 29.058\ldots$, with $\tilde{\alpha} = 1.0767\ldots$.

4 Analysis of Algorithm 2

Two awake stations are needed in Algorithm 2: the one is only sending (the initiator) and the other is listening. The probability $p'_j$ that one station is elected in round $j$ expresses along the same lines as in Eq. (4) with the corresponding probability. The probability of having exactly one initiator and one witness for $k = j$ in a round is

$$ q^n_j = \frac{1}{2} \left( \frac{n}{2} \right) \left( 1 - \frac{x}{2i} \right)^{n-2}. $$

Hence $p'_j = t'_j s'_j$, where

$$ t'_j = \sum_{k=1}^{[\alpha^j]} q(k,n) (1 - q(k,n))^{-1}, \quad s'_j = \prod_{i=1}^{[\alpha^j]} (1 - q(i,n)). \quad (15) $$

All computations are quite similar to those in the proof of Theorem 1. Again, the value of $p'_j$ in Eq. (15) is obtained by asymptotic approximation (see Lemma 5 in Appendix A).

First,

$$ s'_j \geq \prod_{i=1}^{[\alpha^j]} \left( 1 - \frac{1}{2} \left( \frac{n}{2} \right) \exp \left( -\frac{n - 2}{2i} \right) \right), \quad \text{since } \forall x \in [0, 1], 1 - x \leq e^{-x}, $$

$$ \geq \prod_{i=1}^{[\alpha^j]} \left( 1 - \frac{n^2}{4i+1} \exp \left( -\frac{n - 2}{2i} \right) \right), \quad \text{since } \left( \frac{n}{2} \right) \leq \frac{n^2}{2}, $$

$$ \geq \prod_{i=1}^{[\alpha^j]} \left( 1 - \frac{n^2}{4i} \exp \left( -\frac{n}{2i} \right) \right) \geq \prod_{i=1}^{[\alpha^j]} \left( 1 - \frac{n^2}{4i} \exp \left( -\frac{n}{2i} \right) \right). $$

Using this latter lower bound in Lemma 5 yields

$$ s'_j \geq \exp \left( -\sum_{m=1}^{\infty} \sum_{i=1}^{[\alpha^j]} \frac{1}{m} \frac{n^{2m}}{4^m} \exp \left( -\frac{nm}{2i} \right) \right) $$

$$ \geq \exp \left( o(1) - \sum_{m=1}^{\infty} \frac{1}{m} \frac{(2m - 1)!}{m^m (2m+1) \ln 2} - \sum_{m=1}^{\infty} \frac{1}{m^3} \sup_{\nu} \left| V_\nu (\log_2 n) \right| \right), $$

with the following value of the lower bound on $s'_j$ (computed with Maple):

$$ \liminf_{n} s'_j \geq .19895\ldots $$
Next, $1 - x^2 \geq e^{-x}$ when $x$ is close to $0$ and so \( \frac{n}{2} \geq \frac{n^2}{2} \exp \left( -\frac{1}{\sqrt{n}} \right) \); whence $t'_j$ also is bounded from below as follows,

$$t'_j \geq \sum_{k=1}^{m} \sum_{m=1}^{\infty} \left( \frac{1}{2} \left( \frac{n}{2^k} \right)^n \left( 1 - \frac{1}{2^k} \right) \right)^m \geq \sum_{m=1}^{\infty} \sum_{k=1}^{m} \left( \frac{1}{2} \left( \frac{n^2}{4k} \exp \left( -\frac{1}{\sqrt{n}} \right) \right)^m \left( 1 - \frac{1}{2^k} \right) \right)^m .$$

Now, $1 - x \geq \exp (-x - x^2)$ when $x \in [0, 1/2]$, and

$$t'_j \geq \sum_{m=1}^{\infty} e^{-m} \sum_{k=1}^{\infty} \frac{1}{4m} \left( \frac{n^2}{4k} \exp \left( -\frac{n}{2^k} \right) \right)^m \geq \sum_{m=1}^{\infty} e^{-m} \sum_{k=m}^{\infty} \frac{1}{4m} \left( \frac{n^2}{4k} \exp \left( -\frac{n}{2^k} \right) \right)^m , \quad (16)$$

where the last summation is starting from $r \equiv r(n) = 3/2 \log_2(n)$. For such a choice of $r$, we have $2^r \ll n \ll 4^r$ (which is used in the following).

Therefore, we can now use Lemma 5 to deal with the inner sum in Eq. (16)

$$t'_j \geq \sum_{m=1}^{\infty} \exp \left( -\frac{m}{\sqrt{n}} \right) \sum_{k=m}^{\infty} \frac{1}{4m} \left( \frac{n^2}{4k} \exp \left( -\frac{n}{2^k} \right) \right)^m \geq \sum_{m=1}^{\infty} e^{-m} \frac{1}{4m} \left( \frac{(2m - 1)!}{4m m^{2m+1} \ln 2} - \frac{1}{m^2} \sup_{\nu} |V'_\nu(\log_2 n)| \right) + o(1).$$

By Lebesgue’s monotone convergence theorem, this sum converges to

$$\sum_{m=1}^{\infty} \left( \frac{(2m - 1)!}{4m m^{2m+1} \ln 2} - \frac{1}{m^2} \sup_{\nu} |V'_\nu(\log_2 n)| \right),$$

and the numerical value obtained is $\lim \inf \frac{t'_j}{n} \geq .39856 \ldots$

Finally, from the lower bounds values on $s'_j$ and $t'_j$, we find

$$\lim \inf \frac{p'_j}{n} \geq .079294 \ldots$$

**Remark 3** The lower bound $p^*_j$ in Algorithm 2 is already defined in (2). Now, since $p^*_2 = .07929$, $\alpha$ meets the new condition if it belongs to $(1, 1.086 \ldots)$, and the minimum value of the constant $C(p^*_2, \alpha)$ is $C(p^*_2, \tilde{\alpha}) \approx 52.516$, with $\tilde{\alpha} = 1.0404 \ldots$

Note also that Algorithms 1 and 2 can be improved by starting from $k = k_0$, $k_0 > 1$ (instead of 1) in the third line of the algorithms. Though the running time of each algorithm remains asymptotically the same, starting from $k = k_0 > 1$ reduces the awake time to $(1 + \epsilon) \log_2 \log_2(n)$ time slots for Algorithm 1, and $(1.5 + \epsilon) \log_2 \log_2(n)$ time slots for Algorithm 2 (with $\epsilon = 1/2^{k_0-1})$. Yet, this also makes the running time longer for small values of $n$; whence the (obvious) fact that the knowledge of any lower bound on $n$ greatly helps.
The following two technical Lemmas are at the basis of the asymptotic complexity analysis of Algorithm 1 or Algorithm 2, in the proof of Theorem 1 and Theorem 2, respectively. They both use Mellin transform techniques [5, 6, 10]

**Lemma 4** Let \( r \equiv r(n) \) such that, when \( n \to +\infty \) we have simultaneously \( r \to \infty \) and \( n/2^r \to 0 \). Then, for all positive integer \( m \),

\[
\sum_{k=1}^{r} \left( \frac{n}{2^k} \right)^m \exp\left( -\frac{nm}{2^k} \right) = \frac{m!}{m^{m+1}\ln 2} + \frac{1}{m} \frac{U_m\left( \log_2(n) \right)}{2^{m-1}\ln 2} + \mathcal{O}\left( \frac{\ln m}{m} \right) + \mathcal{O}\left( \frac{n^{m-1}m}{2^{r-m}} \right).
\]  

(17)

Denote \( \chi_\ell \equiv 2i\ell\pi/\ln 2 \). For any positive integer \( m \), \( U_m\left( \log_2(n) \right) \) is defined as

\[
U_m(z) = \sum_{\ell \in \mathbb{Z} \setminus \{0\}} \Gamma(m + \chi_\ell) \exp\left( -\chi_\ell \ln(m) \right) \exp(-2i\ell\pi z).
\]  

(18)

The Fourier series \( U_m(z) \) has mean value 0 and the amplitude of its coefficients does not exceed 0.024234.

**Proof:** The asymptotic approximation of the finite sum in Eq. (17) is obtained by direct use of the properties of the Mellin transform [5, 6].

The sum

\[
f(x) = \sum_{k=1}^{+\infty} \left( \frac{x}{2^k} \right)^m \exp\left( -\frac{mx}{2^k} \right)
\]

is to be analyzed as \( x \to \infty \). Its Mellin transform, with fundamental strip \((-1, 0)\), is

\[
f^*(s) = \frac{\Gamma(s + m)2^s}{m^{s+m}(1 - 2^s)}.
\]

There is a simple pole at \( s = 0 \), but also simple imaginary poles at \( s = \chi_\ell \equiv 2i\ell\pi/\ln 2 \) (for all non zero integers \( \ell \)), which are expected to introduce periodic fluctuations. The singular expansion of \( f^*(s) \) in \((-1/2, 2)\) is

\[
f^*(s) \asymp \left[ \frac{\Gamma(m)}{m^m \ln 2} \frac{1}{s} \right] - \frac{1}{m^m \ln 2} \sum_{\ell \in \mathbb{Z} \setminus \{0\}} \frac{\Gamma(m + \chi_\ell) \exp\left( -\chi_\ell \ln(m) \right)}{s - \chi_\ell}.
\]

Accordingly, by reinserting \( \sum_{k=1}^{r} \left( \frac{x}{2^k} \right)^m \exp\left( -\frac{mx}{2^k} \right) \) into \( f(x) \), one finds the results stated in Eqs. (17)) and (18). In Eq. (17), the periodic fluctuations are occurring under the
form of the Fourier series $U_m\left(\log_2(n)\right)$ with mean value 0. Besides, for any positive integer $m$, the maximum of the amplitude of the Fourier series is taken at $m = 11$ and it is rather small:

$$\forall m > 0 \quad |U_m(z)| \leq \sum_{\ell \in \mathbb{Z} \setminus \{0\}} \frac{2^m |\Gamma(m + \chi_\ell)|}{m^{m-1} \ln 2} < .024234$$

(19)

The Fourier coefficients also decrease very fast (see e.g., [6] or [10, p. 131]). The error terms $O(2^m/n^m)$ and $O(n^m/2^m)$ in Eq. (17) result from the “truncated” summation: $1 \leq k \leq r$. (The Mellin transform itself results in a $O\left(n^{-1}\right)$ error term.) □

Lemma 5

Again, let $r \equiv r(n)$ such that, when $n \to +\infty$, $r \to +\infty$ and $n/2^r \to 0$. Then, for all positive integer $m$,

$$\sum_{k=1}^{r} \frac{1}{4^m} \left(\frac{n^2}{2^k}\right)^m \exp\left(-\frac{nm}{2^k}\right) = \frac{(2m - 1)!}{4^m m^{2m+1} \ln 2} + \frac{1}{m^s} V_m\left(\log_2(n)\right) + O\left(\frac{m^s}{n^m}\right) + O\left(\frac{n^m}{2^m}\right).$$

(20)

Again denote $\chi_\ell \equiv 2i\ell\pi/\ln 2$. For any positive integer $m$, the above Fourier series

$$V_m(z) = -\frac{m}{4^m m^{2m} \ln 2} \sum_{\ell \in \mathbb{Z} \setminus \{0\}} \Gamma(2m + \chi_\ell) \exp\left(-2i\ell\pi \log_2(m)\right) \exp(-2i\ell\pi z)$$

has mean value 0 and the amplitude of the coefficients of $V_m(z)$ cannot exceed $9.0054 \times 10^{-5}$.

Proof: The asymptotic approximation of the finite sum in Eq. (20) is provided along the same lines as in Lemma 4. Now,

$$g(x) = \sum_{k=1}^{+\infty} \frac{1}{4^m} \left(\frac{x}{2^k}\right)^m \exp\left(-\frac{mx}{2^k}\right)$$

is to be analyzed when $x \to \infty$. Similarly, its Mellin transform is $g^*(s) = \frac{\Gamma(s + 2m)2^s}{m^{s+2m}(1 - 2^s)}$, with fundamental strip $\langle -1, 0 \rangle$. Again there is a simple pole at $s = 0$ and simple imaginary poles at $s = \chi_\ell \equiv 2i\ell\pi/\ln 2$ (for all non zero integers $\ell$), which are also expected to introduce periodic fluctuations.

As in Lemma 4 the singular expansion of $g^*(s)$ provides an asymptotic approximation of the finite sum in Eq. (20). The periodic fluctuations occur under the form of the Fourier series $V_m\left(\log_2(n)\right)$. As $U_m(z)$, $V_m(z)$ has mean value 0 and its coefficients have a very tiny amplitude. Their minimum is taken at $m = 2$, and

$$\forall m > 0 \quad |V_m(z)| \leq \sum_{\ell \in \mathbb{Z} \setminus \{0\}} \frac{|\Gamma(2m + \chi_\ell)|}{4^m m^{2m-1} \ln 2} < 9.0054 \times 10^{-5}.$$

The Fourier coefficients also decrease very fast (see e.g., [6] or [10, p. 131]). Last, the “truncated” summation $(1 \leq k \leq r)$ results again in error terms $O(2^m/n^m)$ and $O(n^m/2^m)$ in Eq. (20). □
References

[1] R. Bar-Yehuda, O. Goldreich and A. Itai, On the time complexity of broadcast in Multi-hop Radio Networks: an Exponential Gap between Determinism and Randomization, *J. of Computers and System Science*, 45: 104-126, 1992.

[2] R. Bar-Yehuda, O. Goldreich and A. Itai, Multiple Communication in Multi-Hop Radio Networks, *SIAM J. on Computing*, 22: 875-887, 1993.

[3] B.S. Chlebus, *Randomized Communication in Radio Networks*, Handbook on Randomized Computing, Vol. I, 401-456, P. M. Pardalos, S. Rajasekaran, J. H. Reif and J. D. P. Rolim (eds), Kluwer Academic Publishers, 2001.

[4] J. Fill, H. Mahmoud and W. Szpankowski, On the distribution for the duration of a randomized leader election algorithm, *Annals of Applied Probability*, 6: 1260-1283, 1996.

[5] Philippe Flajolet, Xavier Gourdon and Philippe Dumas, Mellin Transforms and Asymptotics: Harmonic Sums, *Theoretical Computer Science*, 144: 3-58, 1995.

[6] P. Flajolet and R. Sedgewick, *Analytic Combinatorics*, (to appear). Chapters are available as INRIA research reports, at http://algo.inria.fr/flajolet/books.

[7] A. G. Greenberg, P. Flajolet and R. E. Ladner, Estimating the Multiplicities of Conflicts to Speed Their Resolution in Multiple Access Channels, *Journal of the ACM*, 34: 289-325, 1987.

[8] S. Janson and W. Szpankowski, Analysis of an asymmetric leader election algorithm, *Electronic J. Combin.*, 4(1), R17, 1997.

[9] T. Jurzinski, M. Kutylowski and J. Zatopianski, Energy-Efficient Size Approximation of Radio Networks with no Collision Detection, in *Proc. of COCOON’02*, LNCS 34: 289-325, Springer-Verlag, 2002.

[10] D. E. Knuth, *The Art of Computer Programming – Sorting and Searching*, vol 3, Addison-Wesley, 1973.

[11] E. Kushilevitz and Y. Mansour, An $\Omega(D \log (N/D))$ Lower-Bound for Broadcast in Radio Networks, *SIAM J. on Computing*, 27: 702-712, 1998.

[12] J. L. Massey and P. Mathys, The Collision Channel without Feedback, *IEEE Trans. on Information Theory*, IT-31: 192-204, 1985.

[13] K. Nakano and S. Olariu, Randomized Leader Election Protocols in Radio Networks with No Collision Detection, *Proc. of ISAAC’2000*, LNCS 1969, Springer-Verlag, 362-373, 2000.

[14] K. Nakano and S. Olariu, Energy-Efficient Initialization Protocols for Radio Networks with no Collision Detection, *IEEE Transactions on Parallel and Distributed Systems*, 11: 851-863, 2000.

[15] H. Prodinger, How to Select a Loser?, *Discrete Math.*, 120: 149-159, 1993.

[16] E. T. Whittaker and G. N. Watson, *A Course in Modern Analysis*, Cambridge University Press, 1965.

[17] D. E. Willard, Log-logarithmic Selection Resolution Protocols in a Multiple Access Channel, *SIAM J. on Computing*, 15: 468-477, 1986.