NONLINEAR DIFFUSION EQUATIONS FOR ANISOTROPIC MAGNETOHYDRODYNAMIC TURBULENCE WITH CROSS-HECILICIY

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ABSTRACT

Nonlinear diffusion equations of spectral transfer are systematically derived for anisotropic magnetohydrodynamics in the regime of wave turbulence. The background of the analysis is the asymptotic Alfvén wave turbulence equations from which a differential limit is taken. The result is a universal diffusion-type equation in k-space which describes in a simple way and without free parameter the energy transport perpendicular to the external magnetic field $B_\mathbf{0}$ for transverse and parallel fluctuations. These equations are compatible with both the thermodynamic equilibrium and the finite flux spectra derived by Galtier et al.; it improves therefore the model built heuristically by Lithwick & Goldreich for which only the second solution was recovered. This new system offers a powerful description of a wide class of astrophysical plasmas with non-zero cross-helicity.

Key words: magnetohydrodynamics (MHD) – Sun: corona – turbulence

1. INTRODUCTION

The observations of astrophysical plasmas by various spacecraft have added substantially to our knowledge of magnetohydrodynamic (MHD) turbulence. Among the different media widely analyzed such as the interstellar medium (Scalo & Elmegreen 2004) or the Sun’s atmosphere (Chae et al. 1998), the solar wind is certainly the most interesting plasma since direct measurements are possible. This unique situation in astrophysics allows us to probe deeply the nature of the fluctuations and to investigate, for example, the origin of anisotropy (Matthaeus et al. 1996; Alexakis et al. 2007; Galtier 2009b; Podesta 2009), to evaluate the mean energy dissipation rate (MacBride et al. 2008), to detect intermittency (Salem et al. 2009), or to analyze the transition to the regime of dispersive turbulence characterized by a steepening of the magnetic field fluctuations spectrum with a power-law index going from $-5/3$, at frequencies lower than 1 Hz, to indices lying around $-2.5$ at higher frequencies (Galtier 2006, 2008; Smith et al. 2006; Sahraoui et al. 2009).

The low solar corona provides a second interesting example where it is believed that MHD turbulence plays a central role in the dynamics and the small-scale heating. For example, in active region loops spectrometer analyses revealed non-thermal velocities sometimes reaching 50 km s$^{-1}$ (Chae et al. 1998); this line broadening is generally interpreted as unresolved turbulent motions with length scales smaller than the diameter of coronal loops which is about 1 arcsec and timescales shorter than the exposure time of the order of few seconds. Turbulence is evoked in the solar coronal heating problem since it offers a natural process to produce small-scale heating (Heyvaerts & Priest 1992; Galtier 1999; Cranmer 2010). Weak MHD turbulence is now proposed as a possible regime for some coronal loops since a very small ratio is expected between the fluctuating magnetic field and the axial component (Rappazzo et al. 2007). Inspired by the observations and by recent direct numerical simulations of three-dimensional MHD turbulence (Bigot et al. 2008a), an analytical model of coronal structures has been proposed (Bigot et al. 2008b) where the heating is seen as the end product of a wave turbulent cascade. Surprisingly, the heating rate found is non-negligible and may explain the observational predictions.

A third example where MHD turbulence seems to be fundamental is given by the upper solar corona which makes a connection between the lower corona and the stationary solar wind. Observations reveal that the heating in this region affects preferentially the ions in the direction perpendicular to the mean magnetic field. The electrons are much cooler than the ions, with temperatures generally less than or close to $10^6$ K (David et al. 1998). Additionally, the heavy ions become hotter than the protons within a solar radius of the coronal base. Ion cyclotron waves could be the agent which heats the coronal ions and accelerates the fast wind. Naturally, the question of the origin of these high-frequency waves arises. Among different scenarios, turbulence appears to be a natural and efficient mechanism to produce ion cyclotron waves. In this case, the Alfvén waves launched at low altitude with frequencies in the MHD range would develop a turbulent cascade to finally degenerate and produce ion cyclotron waves at much higher frequencies. In that context, the wave turbulence regime was considered in the weakly compressible MHD case at low $\beta$ plasmas (where $\beta$ is the ratio between the thermal and the magnetic pressure) in order to analyze the nonlinear three-wave interaction transfer to high-frequency waves (Chandran 2005). The wave turbulence calculation shows—in the absence of slow magnetosonic waves—that MHD turbulence is a promising explanation for the anisotropic ion heating.

MHD turbulence modeling is the main tool for investigating the situations previously discussed. Although it cannot be denied that numerical resources have been significantly improved during the last decades (Mininni & Pouquet 2007), direct numerical simulations of MHD equations are still limited for describing highly turbulent media. For that reason, shell cascade models are currently often used to investigate the small-scale coronal heating (Buchlin & Velli 2007) and its impact in terms of spectroscopic emission lines. Transport equations are also used, for example, in the context of solar wind acceleration in the extended solar corona (Cranmer & van Ballegooijen 2003). The ad hoc model is an advection–diffusion equation for the evolution of the energy spectrum whose inspiration is found in the original paper by Leith (1967). It is also a
cascade model where the locality of the nonlinear interactions is assumed but where the dynamics is given by a second-order nonlinear partial differential equation whereas we have ordinary differential equations for shell models.

In the next section, the origin of the Leith’s model is discussed and in Section 3 the Alfvén wave turbulence equations are recalled in the case of non-zero cross-helicity. In Section 4, the differential limit is taken on the previous wave turbulence equations and the associated nonlinear diffusion equations for anisotropic MHD turbulence are systematically derived. Finally, a conclusion is developed in the last section.

2. LEITH’S MODEL

A theoretical understanding of the statistics of turbulence and the origin of the power-law energy spectrum, generally postulated from dimensional considerations à la Kolmogorov, remains one of the outstanding problems in classical physics which continues to resist modern efforts at solution. The difficulty lies in the strong nonlinearity of the governing equations which leads to an unclosed hierarchy of equations. Faced with that situation different models have been developed such as closure models in Fourier space for hydrodynamic and MHD turbulence (Kraichnan 1963; Orszag & Kruskal 1968). In the meantime—and following an approach often fruitful in radiation and neutron transport theory (Davidson 1958)—Leith introduced the idea of a diffusion approximation to inertial energy transfer in isotropic turbulence (Leith 1967). This new class of ad hoc models describes the time evolution of the spectral energy density, $e(k)$, for originally an isotropic three-dimensional incompressible hydrodynamic turbulence, in terms of a partial differential equation by making a diffusion approximation to the energy transport process in the $k$-space representation. Ignoring forcing and dissipation the three-dimensional isotropic Navier–Stokes equations read in Fourier space

$$\frac{\partial e(k)}{\partial t} = -\nabla \cdot \mathcal{F} = -\frac{1}{k^2} \frac{\partial}{\partial k} (k^2 \mathcal{F}_r),$$  \hspace{1cm} (1)

The radial component of the energy flux vector is modeled as

$$\mathcal{F}_r = -D(k) \frac{\partial e(k)}{\partial k},$$  \hspace{1cm} (2)

where $D(k)$ is a diffusion coefficient that remains to be determined. It is straightforward to show dimensionally that the diffusion coefficient scales as

$$D \sim \frac{k^2}{\tau},$$  \hspace{1cm} (3)

where $\tau$ is the typical transfer time of the Navier–Stokes equations which can be identified as the eddy turnover time $\tau_{\text{edd}}$. Therefore, we may evaluate this time as

$$\tau = \tau_{\text{edd}} \sim \frac{1}{k \sqrt{\varepsilon k^3}}.$$  \hspace{1cm} (4)

We recall that the total kinetic energy per mass is by definition $\int e(k)dk = \int E(k)dk$. After substitution of Equation (4) into Equation (3) it is possible to rewrite (up to a factor) the model equation (1) for the omnidirectional spectrum (Leith 1967) as

$$\frac{\partial E(k)}{\partial t} = \frac{\partial}{\partial k} \left( k^{1/2} E^{1/2} \frac{\partial}{\partial k} (E/k^2) \right),$$  \hspace{1cm} (5)

which is commonly named the Leith’s equation. Beyond its relative simplicity, Equation (5) exhibits several important properties like the preservation after time integration of a nonnegative spectral energy and the production of the Kolmogorov spectrum in the inertial range which corresponds to a finite energy flux solution. It is straightforward to prove that by imposing a constant energy flux in the inertial range, namely,

$$k^{11/2} E^{1/2} \frac{\partial}{\partial k} (E/k^2) = \text{constant.}$$  \hspace{1cm} (6)

If we look for power-law solutions, $E \sim k^{x}$, then the unique solution that emerges is $x = -5/3$. Note that this equation may also exhibit an anomalous scaling during the nonstationary phase with a steeper power law (Connaughton & Nazarenko 2004).

A generalization of the Leith’s model to three-dimensional isotropic MHD turbulence was proposed by Zhou & Matthaeus (1990). (Note that Iroshnikov (1964) proposed the first such model for MHD from which the $-3/2$ spectrum was derived.) The main modification happens in the evaluation of the transfer time $\tau$ for which a combination of the eddy turnover time $\tau_{\text{edd}}$ and the Alfvén time $\tau_A$ is proposed. The phenomenological evaluation of the transfer time allows the recovering of either the Heisenberg–Kolmogorov ($-5/3$) or the Iroshnikov–Kraichnan ($-3/2$) spectrum when the ratio $\tau_{\text{edd}}/\tau_A$ is respectively much less or much larger than one (Kolmogorov 1941; Heisenberg 1948; Iroshnikov 1964; Kraichnan 1965). The model was also adapted to the case of a non-zero cross-helicity for which a distinction was made between the Elsässer energies $E^+$ and $E^-$. The generalization of the Leith’s model to the more realistic situation of anisotropic MHD turbulence where an external magnetic field $B_0$ is imposed was proposed only recently (Matthaeus et al. 2009). As already announced by Zhou & Matthaeus (1990), the departure from the assumption of isotropic turbulence generates a difficult mathematical treatment since, in particular, a diffusion tensor is expected instead of a scalar. Another difficulty comes from the locality of the nonlinear interaction which is assumed in the isotropic case: when a mean magnetic field is imposed the situation is different since a reduction of nonlinear transfers occurs along $B_0$. In terms of triads, $k = k + L$, it means that one of the wavevectors, say $k$, is mainly oriented transverse to $B_0$. The sophisticated model proposed by Zhou & Matthaeus (1990) is an attempt to describe such a nontrivial dynamics.

The case of Alfvén wave turbulence for which a relatively strong $B_0$ is required is an important limit for which a rigorous analysis is possible (Galtier et al. 2000). The wave kinetic equations derived are a set of coupled integro-differential equations which are not obvious to simulate numerically in the most general case (Galtier et al. 2000; Bigot et al. 2008c). This was a motivation for deriving a model made of two coupled diffusion equations which describe Alfvén wave turbulence with a non-zero cross-helicity (Lithwick & Goldreich 2003). These model equations are able to recover the finite flux spectra which are exact solutions of the wave kinetic equations (Galtier et al. 2000). In this paper, it is shown that a set of two coupled nonlinear diffusion equations may be derived systematically from the asymptotic equations of Alfvén wave turbulence by taking a differential limit. An important difference is found between the nonlinear diffusion equations derived here and the model proposed by Lithwick & Goldreich (2003). The main physical problem is the inability of the model to reproduce the thermodynamic equilibrium solutions which are
exact solutions of the wave turbulence equations. It is believed that the higher degree of accuracy of the new system offers a powerful description of a wide class of astrophysical plasmas with non-zero cross-helicity.

3. ASYMPTOTIC THEORY OF ALFVÉN WAVE TURBULENCE

The wave turbulence theory for three-dimensional incompressible MHD was rigorously derived by Galtier et al. (2000). It is a perturbative theory which necessitates heavy calculations which will not be reproduced here. We refer the reader to the original paper for a global explanation or to two satellite papers where simplified approaches are adopted (Galtier et al. 2002; Galtier & Chandran 2006). Since it is important to understand the wave turbulence equations from which our analysis will start, we shall recall below the main steps in their derivation.

The inviscid incompressible three-dimensional MHD equations read

$$\partial_t \mathbf{z}^r - s \mathbf{B}_0 \cdot \nabla \mathbf{z}^r = -\mathbf{z}^r \cdot \nabla \mathbf{z}^r - \nabla P_s,$$

$$(7) \nabla \cdot \mathbf{z}^r = 0,$$

where $\mathbf{z}^r = \mathbf{v} + s \mathbf{b}$ are the Elsässer fields ($s = \pm$), $\mathbf{v}$ is the fluid velocity, $\mathbf{b}$ is the magnetic field in velocity units, $\mathbf{B}_0$ is a uniform magnetic field (in velocity units, i.e., the Alfvén speed), and $P_s$ is the total (thermal plus magnetic) pressure. We assume that the uniform magnetic field is relatively strong ($\mathbf{B}_0 \gg \mathbf{z}^r$) and that the higher degree of accuracy of the new system offers a statistical development, the timescale separation, $\tau_\text{A}/\tau_\text{eddy} \ll 1$.

It is a perturbative theory which necessitates heavy calculations (with $\tau_\text{A} = 1/\omega_k$ and $\tau_\text{eddy} = 1/k_\parallel z^r$), leads asymptotically to the destruction of some nonlinear terms—including the fourth-order cumulants—and only resonance terms survive (Galtier et al. 2000; Galtier 2009a). It leads to a natural asymptotic closure for the moment equations. In such a statistical development, the following general definition for the total (shear- plus pseudo-Alfvén wave) energy spectrum is used;

$$\langle a_j^* (k) a_j^* (k') \rangle = E^s (k) \delta (k + k') / k_\perp. \quad (12)$$

where $\langle \rangle$ stands for an ensemble average and $k_\parallel = |k_\parallel|$. In the absence of magnetic helicity and in the case of an axially symmetric turbulence, the asymptotic equations simplify. For shear-Alfvén waves, the energy spectrum is given by

$$E^\text{shea}r (k_\parallel, k_\parallel) = g(k_\parallel) E^s (k_\parallel), \quad (13)$$

where $g(k_\parallel)$ is a function fixed by the initial conditions (i.e., there is no energy transfer along the parallel direction). In the limit $k_\parallel \gg k_\parallel$, the transverse part obeys the following nonlinear equation (the small parameter $\epsilon$ is now included in the time variable and the limits of the integration are explicitly written)

$$\delta E^s (k_\perp) = \frac{\pi}{B_0} \int_0^\infty \int_0^\infty \cos^2 \phi \sin \theta \frac{k_\parallel}{k_\perp} E^s (k_\parallel) \times \left[ k_\perp E^s (L_\perp) - L_\perp E^s (k_\parallel) \right] d\kappa_\perp dL_\perp. \quad (14)$$

Here, $P_j$ is the projector on solenoidal vectors such that $P_j (\mathbf{k}) = \delta_{jn} - k_j k_n / k^2$; $\delta_{k_\bm{x}L} \equiv \delta (k - \kappa - \mathbf{L})$ reflects the triadic interaction and $\Delta \omega = \omega_\Lambda - \omega_k - \omega_\kappa$ is the frequency mixing. The appearance of an integration over wave vectors $\mathbf{k}$ and $\mathbf{L}$ is directly linked to the quadratic nonlinearity of Equation (9) (as a result of Fourier transform of a correlation product).

Equation (11) is nothing else than the compact expression of the incompressible MHD equations when a strong uniform magnetic field is present. It is the point of departure of the wave turbulence formalism which consists in writing equations for the long-time behavior of second-order moments. In such a statistical development, the timescale separation, $\tau_\text{A}/\tau_\text{eddy} \ll 1$
pseudo-Alfvén waves which are passively advected by shear-Alfvén waves, namely,

\[
\partial_t E^i_{\perp}(k_{\perp}) = \frac{\pi}{B_0} \int_0^{+\infty} \int_0^{+\infty} h \sin \theta \frac{k_{\perp}}{k_{\perp}} E^{-i}_{\perp} (k_{\perp}) \times [k_{\perp} E^i_{\perp}(L_{\perp}) - L_{\perp} E^i_{\perp}(k_{\perp})] d\kappa_{\perp} dL_{\perp},
\]

(15)

with by definition

\[
E^i_{\text{pseudo}}(k_{\perp}, k_0) = \tilde{g}(k_0) E^i_0(k_{\perp}),
\]

(16)

where \(\tilde{g}(k_0)\) is a function determined by the initial condition.

Equations (14) and (15) are asymptotically exact. These master equations of Alfvén wave turbulence describe the nonlinear evolution of MHD turbulence in the presence of a strong uniform magnetic field, with non-zero cross-helicity and zero magnetic helicity. In the limit \(k_{\perp} \gg k_0\) considered, Equations (14) and (15) describe respectively the dynamical evolution of transverse and parallel fluctuations.

4. DIFFERENTIAL LIMIT FOR STRONGLY LOCAL INTERACTIONS

We shall take a differential limit of Equations (14) and (15) for strongly local interactions (Dyachenko et al., 1992). It is important to note that by taking this limit we shall extract a subset of the full set of interactions that is present in the Alfvén wave turbulence Equations (14) and (15). In terms of triads, strongly local interactions\(^5\) means that we will only retain triangles which are approximately equilateral. (Note that the locality concerns only perpendicular wavevectors.) Therefore, the differential limit will lead to an approximate description of Alfvén wave turbulence which is believed, however, sufficiently rich to reproduce the most important properties of the original system. The rigorous derivation will be presented only for shear-Alfvén waves since the generalization to pseudo-Alfvén waves is straightforward. Multiplying Equation (14) by an unknown function \(f(k_{\perp})\) we obtain, after integration in \(k_{\perp}\),

\[
\partial_t \int_0^{+\infty} E^i_{\perp}(k_{\perp}) f(k_{\perp}) dk_{\perp} = \int_0^{+\infty} \int_0^{+\infty} T(k_{\perp}, L_{\perp}, \kappa_{\perp}) \times f(k_{\perp}) dk_{\perp} d\kappa_{\perp} dL_{\perp},
\]

(17)

where

\[
T(k_{\perp}, L_{\perp}, \kappa_{\perp}) = \frac{\pi}{B_0} h \cos^2 \phi \sin \phi \frac{k_{\perp} L_{\perp}}{k_{\perp}^2} E^{-i}_{\perp} (k_{\perp}) \times [k_{\perp} E^i_{\perp}(L_{\perp}) - L_{\perp} E^i_{\perp}(k_{\perp})].
\]

(18)

Note the use of the triangle relation (see Figure 1)

\[
\sin \theta = \sin \phi \frac{L_{\perp}}{k_{\perp}}.
\]

(19)

It is convenient to introduce the following definition \(S = \pi \cos^2 \phi \sin \phi\). Then, by changing the name of indices one can write

\[
\partial_t \int_0^{+\infty} E^i_{\perp}(k_{\perp}) f(k_{\perp}) dk_{\perp} = \frac{1}{2} \int_0^{+\infty} \int_0^{+\infty} \int_0^{+\infty} [T(k_{\perp}, L_{\perp}, \kappa_{\perp}) f(k_{\perp}) + T(L_{\perp}, k_{\perp}, \kappa_{\perp}) f(L_{\perp})] dk_{\perp} d\kappa_{\perp} dL_{\perp}.
\]

(20)

However, by symmetry we also have

\[
T(L_{\perp}, k_{\perp}, \kappa_{\perp}) = -T(k_{\perp}, L_{\perp}, \kappa_{\perp}),
\]

(21)

which gives

\[
\partial_t \int_0^{+\infty} E^i_{\perp}(k_{\perp}) f(k_{\perp}) dk_{\perp} = \frac{1}{2} \int_0^{+\infty} \int_0^{+\infty} \int_0^{+\infty} T(k_{\perp}, L_{\perp}, \kappa_{\perp}) f(k_{\perp}) - f(L_{\perp}) dk_{\perp} d\kappa_{\perp} dL_{\perp}.
\]

(22)

For strongly local interactions, we have the following relations:

\[
k_{\perp} = k_{\perp}(1 + \epsilon_{k}), \quad |\epsilon_{k}| \ll 1,
\]

(23)

\[
L_{\perp} = k_{\perp}(1 + \epsilon_{L}), \quad |\epsilon_{L}| \ll 1,
\]

(24)

where \(\epsilon_{k}\) and \(\epsilon_{L}\) are two variables of small amplitude. Then, at first order we have

\[
f(L_{\perp}) = f(k_{\perp}) + \epsilon_{L} k_{\perp} \frac{\partial f(k_{\perp})}{\partial k_{\perp}},
\]

(25)

and also at first order

\[
T(k_{\perp}, k_{\perp}(1 + \epsilon_{L}), k_{\perp}(1 + \epsilon_{k})) = \frac{S}{B_0} h E^{-i}_{\perp} (k_{\perp}) k_{\perp} \epsilon_{L}
\]

\[
\times \left[ k_{\perp} \frac{\partial E^i_{\perp}(L_{\perp})}{\partial k_{\perp}} - E^i_{\perp}(k_{\perp}) \right]
\]

\[
= \frac{S}{B_0} h E^{-i}_{\perp} (k_{\perp}) \epsilon_{L} \frac{\partial}{\partial k_{\perp}} \left( E^i_{\perp}(k_{\perp}) / k_{\perp} \right).
\]

(26)

Therefore, Equation (22) may be reduced at first order as

\[
\partial_t \int_0^{+\infty} E^i_{\perp}(k_{\perp}) f(k_{\perp}) dk_{\perp} = -\frac{1}{B_0} \int_0^{+\infty} \int_{-\epsilon}^{+\epsilon} \int_{-\epsilon}^{+\epsilon} \left[ \frac{S}{2} h E^{-i}_{\perp}(k_{\perp}) k_{\perp} \epsilon_{L}^2 \frac{\partial}{\partial k_{\perp}} \left( E^i_{\perp}(k_{\perp}) / k_{\perp} \right) \right] \frac{\partial f(k_{\perp})}{\partial k_{\perp}} dk_{\perp} d\epsilon_{k} d\epsilon_{L}.
\]

(27)

where

\[
C_{\perp} \equiv \int_{-\epsilon}^{+\epsilon} \int_{-\epsilon}^{+\epsilon} \frac{S}{2} h \epsilon_{L}^2 d\epsilon_{k} d\epsilon_{L}.
\]

(28)
with $\epsilon$ being a small positive number. The introduction of $\epsilon$ is necessary to ensure the strong locality of the interactions and therefore the convergence of integral equation (28). An integration by parts gives

$$\partial_t \int_0^{+\infty} E_\perp^i (k) f(k) dk = \frac{1}{B_0} \int_0^{+\infty} \frac{\partial}{\partial k} \left[ C_\perp E_\perp^{-i}(k) k_{\perp}^{6} \frac{\partial}{\partial k} (E_\perp^i(k)/k_{\perp}) \right] f(k) dk.$$  

Note that this operation implies for the function $f$ some constraints of convergence at the boundaries. Since $f$ is an arbitrary function one can write

$$\partial_t E_\perp^i(k) = \frac{C_\perp}{B_0} \frac{\partial}{\partial k}(k_{\perp}^{6} E_\perp^{-i}(k) \frac{\partial}{\partial k} \left( \frac{E_\perp^i(k)}{k_{\perp}} \right)),$$  

which is the differential limit of the wave turbulence equation for shear-Alfvén waves. It is useful to get an evaluation of $C_\perp$ since the constant in front of an equation always enters into account in the evaluation of the timescale dynamics. By noting that for strongly local interactions the angles of the triads are approximately $\pi/3$, one obtains at first order

$$C_\perp = \frac{\pi \sqrt{3}}{16} \int_{-\epsilon}^{+\epsilon} \int_{-\epsilon}^{+\epsilon} \epsilon^2 d\epsilon d\epsilon_L = \frac{\pi \epsilon^4}{4\sqrt{3}}.$$  

Clearly, the degree of locality will strongly modify the timescale. For example, for strictly local interactions $\epsilon = 0$ and no evolution of the spectra is expected. This is consistent with the original equation (14) for which the right-hand side is trivially zero if $L_{\perp} = k_{\perp}$.

The same type of analysis for pseudo-Alfvén waves gives

$$\partial_t E_\perp^i(k) = \frac{C_\perp}{B_0} \frac{\partial}{\partial k}(k_{\perp}^{6} E_\perp^{-i}(k) \frac{\partial}{\partial k} \left( \frac{E_\perp^i(k)}{k_{\perp}} \right)),$$  

where at first order $C_\perp = \overline{\epsilon} \int_{-\epsilon}^{+\epsilon} (\epsilon/2) \epsilon \sin \phi d\epsilon d\epsilon_L = \pi \epsilon^4/\sqrt{3}$.

5. FINITE FLUX SOLUTIONS AND KOMOGOROV CONSTANTS

Equations (30) and (32) are the main results of the paper. They describe respectively the dynamical evolution of perpendicular and parallel fluctuations to the background magnetic field $B_0$. We see that in the differential limit of strongly local interactions the wave turbulence equations are much simpler. They still satisfy the finite flux solutions as we will see below by looking at the power-law solutions for shear-Alfvén waves. First of all let us introduce the energy flux $P_\perp^i(k)$ which is by definition

$$\partial_t E_\perp^i(k) \equiv -\frac{\partial}{\partial k_{\perp}} P_\perp^i(k_{\perp}).$$  

We obtain

$$P_\perp^i(k_{\perp}) = -\frac{C_\perp}{B_0} k_{\perp}^{6} E_\perp^{-i}(k_{\perp}) \frac{\partial}{\partial k_{\perp}} \left( \frac{E_\perp^i(k_{\perp})}{k_{\perp}} \right).$$  

We shall find the power-law solutions by introducing $E_\perp^i = C^{n_i} k_{\perp}^{n_i}$ into Equation (35); one gets

$$P_\perp^i(k_{\perp}) = -\frac{C_\perp}{B_0} C^{n_i} C^{-n_i} (n_i - 1) k_{\perp}^{n_i+1 - n_i}.$$  

Therefore, the finite flux solutions, $P_\perp^i(k_{\perp}) = P_\perp^i = \text{constant}$, correspond to

$$n_+ + n_- = -4,$$  

with

$$C^+ C^{-i} = \frac{P_\perp^i B_0}{C_\perp(1 - n_i)} = \frac{P_\perp^{-i} B_0}{C_\perp(1 - n_{-i})}.$$  

which leads to

$$E_\perp^+(k_{\perp}) E_\perp^-(k_{\perp}) = \frac{B_0}{C_\perp} \int \frac{1}{(1 - n_i)(1 - n_{-i})} \sqrt{P_\perp^i P_\perp^{-i}} k_{\perp}^{-4}$$  

For balance turbulence, $n_+ = n_- = -2$, and the finite flux solution is

$$E_\perp^+(k_{\perp}) E_\perp^-(k_{\perp}) = \frac{B_0}{C_\perp} \int \frac{1}{(5 + n_i n_{-i})} \sqrt{P_\perp^i P_\perp^{-i}} k_{\perp}^{-4}.$$  

We see that the Kolmogorov constant depends on an arbitrary truncation of the integration domain in Equation (31). We recall that the Kolmogorov constant found by Galtier et al. (2000) for balance turbulence was $C_K = 0.585 \sqrt{B_0}$; therefore, the constants coincide for $\epsilon \simeq 1.21$. Although the previous value violates the assumption of smallness for $\epsilon$ it could be taken a posteriori to find a unique solution compatible with the exact derivation of Galtier et al. (2000).

A similar analysis for pseudo-Alfvén waves (32) gives the energy flux

$$P_\perp^i(k_{\perp}) = -\frac{C_\perp}{B_0} k_{\perp}^{6} E_\perp^{-i}(k_{\perp}) \frac{\partial}{\partial k_{\perp}} \left( \frac{E_\perp^i(k_{\perp})}{k_{\perp}} \right).$$  

By introducing $E_\perp^i = \tilde{C}^{n_i} k_{\perp}^{n_i}$ we find the finite flux solutions $m_+ + m_{-} = -4$ and thus

$$m_+ + m_{-} = -4,$$  

and

$$E_\perp^+(k_{\perp}) E_\perp^-(k_{\perp}) = \frac{B_0 C_\perp 5 + n_i n_{-i}}{C_\perp 5 + m_i m_{-i}} \sqrt{P_\perp^i P_\perp^{-i}}.$$  

We see that the Kolmogorov constant depends on an arbitrary truncation of the integration domain in Equation (31). We recall that the Kolmogorov constant found by Galtier et al. (2000) for balance turbulence was $C_K = 0.585 \sqrt{B_0}$; therefore, the constants coincide for $\epsilon \simeq 1.21$. Although the previous value violates the assumption of smallness for $\epsilon$ it could be taken a posteriori to find a unique solution compatible with the exact derivation of Galtier et al. (2000).
which reduces for balance turbulence to
\[
E_{\parallel}(k_{\perp}) = \frac{B_0 C_{\parallel}}{3C_{\parallel}^{\perp}} P_{\parallel} k_{\perp}^{-2} = \frac{B_0}{4\pi \sqrt{3\epsilon}} P_{\parallel} k_{\perp}^{-2} \approx 0.214 \frac{B_0}{\epsilon} P_{\parallel} k_{\perp}^{-2}.
\]

Note that the Kolmogorov constant found by Galtier et al. (2000) for balance turbulence was \(C_{\parallel}^e = 0.0675 \sqrt{B_0}\); in this case, the constants coincide for \(\epsilon \simeq 1.78\).

Additionally, Equations (30) and (32) reproduce the thermodynamic equilibrium solutions which correspond to zero flux (Galtier et al. 2000). In this case, it is straightforward to show from Equations (30) and (32) that
\[
n_+ = m_+ = 1.
\]

As explained above, Equations (30) and (32) are different from the model equations (73) and (74) derived in Lithwick & Goldreich (2003) (where the notation is different; a comparison is possible if one takes \(k_\epsilon^{\perp} \sim E_{\perp}^\pm\)) which do not give the thermodynamic equilibrium solutions. The new system systematically derived here improved therefore the previous description while keeping the simplicity of a diffusion model.

The nonlinear diffusion equations (30)–(32) for non-zero cross-helicity may exhibit different power laws as finite flux solutions. Our knowledge of the initial system (14) and (15) imposes a priori that the power-law indices satisfy the condition \(-3 < n_+, m_+ < -1\) (Galtier et al. 2000). However, if we look at the diffusion equations we do not find any other constraint than relations (36) and (41) which means that in principle the power-law indices are not bounded. The simplicity of the diffusion equations allows us to write a simple relation for shear-Alfvén energy fluxes, namely,
\[
\frac{P_+}{P_{\perp}} = \frac{E_{\parallel}^+ \delta(E_{\perp}^+/k_{\perp})/\partial k_{\perp}}{E_{\parallel}^\pm \delta(E_{\perp}^+/k_{\perp})/\partial k_{\perp}} = \frac{\partial \ln(E_{\parallel}^+/k_{\perp})/\partial k_{\perp}}{\partial \ln(E_{\parallel}^+/k_{\perp})/\partial k_{\perp}}.
\]

In the stationary state, we obtain
\[
\frac{P_+}{P_{\perp}} = \frac{n_+-1}{n_+-1} = -\left(\frac{n_+-1}{n_+ + 5}\right),
\]

which gives \(P_+/P_{\perp} = 1/2\) for \(n_+ = -1\) and \(P_+/P_{\perp} = 2\) for \(n_+ = -3\). Note that the zero cross-helicity case corresponds to \(n_+ = n_- = -2\) for which \(P_+/P_{\perp} = P_{\perp}\). In the general case which includes nonlocal interactions, we recall that we have \(P_+/P_{\perp} = 0\) for \(n_+ = -1\) and \(P_+/P_{\perp} = +\infty\) for \(n_+ = -3\) (Galtier et al. 2000). Therefore, the differences found between both predictions (from the diffusion and the integro-differential equations) give an evaluation of the nonlocal contributions.

6. NUMERICAL ILLUSTRATIONS

In order to check if the constant flux solutions are attractive we have performed two numerical simulations of the nonlinear diffusion equations. Only the case of shear-Alfvén waves (transverse fluctuations) has been considered. A linear viscous term is added in order to introduce a sink for the energy. In practice, the following equations are simulated:
\[
\partial_t E_{\perp}(k_{\perp}) = \frac{\partial}{\partial k_{\perp}} \left( k_{\perp}^2 E_{\perp}^\pm(k_{\perp}) \frac{\partial}{\partial k_{\perp}} \frac{E_{\perp}^\pm(k_{\perp})}{k_{\perp}} \right) - \nu k_{\perp}^2 E_{\perp}^\pm(k_{\perp}),
\]

where \(\nu\) is the viscosity (a unit magnetic Prandtl number is chosen). These types of equations are favorable to the use of a logarithmic subdivision of the \(k_{\perp}\)-axis such that in our case
\[
k_{\perp,i} = 2^i/10
\]

which includes nonlocal interactions, we recall that we have \(P_+/P_{\perp} = 0\) for \(n_+ = -1\) and \(P_+/P_{\perp} = +\infty\) for \(n_+ = -3\) (Galtier et al. 2000). Therefore, the differences found between both predictions (from the diffusion and the integro-differential equations) give an evaluation of the nonlocal contributions.

![Figure 2](image-url)

Figure 2. Time evolution of the energy spectrum \(E_{\perp}(k_{\perp})\) for a cross-helicity \(\rho = 0\). The stationary spectrum is well fitted by a power law in \(k_{\perp}^{-2}\). Forty spectra are shown with a constant interval of time.

7. DISCUSSION

It would be relevant to investigate if whether or not the system recently derived by Matthaeus et al. (2009) for strong
Figure 3. Time evolution of the compensated energy spectra $E^+ E^- k_\perp^4$ for a cross-helicity $\rho = 0.8$. The stationary spectra satisfy the relation $n_+ + n_- = -4$. Forty spectra are shown with a constant interval of time.

(anisotropic) MHD turbulence is able to recover the present equations when the limit of wave turbulence is taken. It would also be interesting to analyze if an anomalous scaling is detected during the front propagation (which is not easy to find here). We recall that the wave kinetic equations (14) exhibit a $k_\perp^{-7/3}$-spectrum during the non-stationary phase (at zero cross-helicity) which is still not understood (Galtier et al. 2000). Anomalous scalings are weaker in diffusion models of turbulence than in wave kinetic equations (Connaughton & Newell 2010). We plan to further investigate this point by using, for example, a higher order numerical scheme. We also plan to further compare numerically the nonlinear diffusion equations and the wave kinetic equations to determine the domain of divergence between them or the influence of an external force (see, e.g., Galtier & Nazarenko 2008).

The nonlinear diffusion equations for non-zero cross-helicity (Equations (30)–(32)) are a simple and therefore useful system for describing a wide class of astrophysical plasmas. The solar corona with the myriad of magnetic loops which are characterized by a strong axial magnetic field is probably a good example of the application of Alfvén wave turbulence (Rappazzo et al. 2007; Bigot et al. 2008b). This regime is also relevant for coronal holes where the solar wind is produced. For both examples, Equations (30)–(32) could give a description of MHD turbulence at large scales since it seems inevitable that at smaller scales the strong turbulence regime overcomes. In this case, a coupling with for example the advection–diffusion model proposed by Chandran (2008) would be relevant.

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