ANALYSIS OF THERMOMECHANICAL PROPERTIES OF POLYMERIC MATERIALS PRODUCED BY A 3D PRINTING METHOD

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Abstract: A comparative analysis of the thermomechanical properties of semicrystalline and amorphous polymeric materials was carried out. Samples were produced by using a 3D printing technology on the SIGNAL printer - ATMAT. The following polymeric materials were used to make the samples: TPU-thermoplastic polyurethane elastomer, ABS-copolymer acrylonitrile-butadiene-styrene, Nosewood, PET-ethylene terephthalate, PLA-poly (lactic acid). The research included a thermal analysis of the dynamic properties (DMTA) of manufactured materials.

Keywords: polymer materials; thermal analysis of dynamic properties; 3D print

1 INTRODUCTION

3D printed parts are more and more often used in different industry branches as specially prototyping and commonly used items. Those sectors use the printing technology due to the short time between the project and final item production, and also because of the lower prices of manufacturing small batches compared to the injection moulding technology. Furthermore, 3D printing gives an opportunity to change the shape of the next part only by adding some changes in the 3D model. It also gives us the possibility of creating very complicated shapes [1, 2]. Modern printers, due to the new software and hardware could cause problems, such as, for example, early wear of the element, difficulties in obtaining adequate model accuracy, inaccurate filling of internal spaces, etc. Another difficulty in the process of 3D printing is the selection of adequate parameters for filament type processes, such as the printing temperature or the working table temperature. Incorrect selection of these factors may result in: clogging printer nozzles, larger material shrinkage than the expected, incomplete plasticization when applying subsequent layers, resulting in delamination of the element and the occurrence of non-uniformity of the model filling which causes a decrease in its strength [6-8].

The aim of the paper is to analyze changes in the thermomechanical properties as a function of the temperature and vibration frequency of materials used to manufacture products by using 3D printing. The polymers were chosen because they are widely used in 3D printing. Some of these materials are not suitable for injection moulding due to the clogging of injection channels or too long exposure to higher temperatures, which changes the properties of the injected material such as Laywood. Tests were conducted for comparison purposes for significantly different materials. The following materials were used as a test material: ABS, Laywood, PLA, PET, TPU. A thermal analysis of the dynamic properties (DMTA) was performed. Researches show that thermomechanical properties of these materials are strictly dependent on the processing method. To obtain those comparisons, the paper examines the samples made by the injection moulding and printing technology [9-15]. In order to compare the properties of the samples produced by 3D printing and injection, samples were made from the ABS material, which is widely used in many industry branches. This enabled the determining of the differences between the properties of the tested materials obtained in various processing technologies.

2 RESEARCH METHODOLOGY

The DEVIL DESIGN filaments with a thickness of 1.75 mm were used in the research.

They were made of the following polymer materials: Laywood, ABS, PLA, PET, TPU. Samples were made by
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using the 3D printing technology on an ATMAT SIGNAL printer, with the option of mounting nozzles with a through-going from 0.1 mm to 1.0 mm. A printer nozzle can warm up to 270 °C, while the table can reach a temperature of 110 °C. The accuracy of filament printing is 0.1 mm for the speed from 0.1 to 1 cm/min. 3D printing was done by using a 0.8 mm nozzle and the DIMAFIX adhesive for printing was applied to the table and printing parameters were used, and the most favorable properties were obtained. Parameters at which 3D printing samples were produced guaranteed the stability of the printing process, no deformation and favourable thermomechanical properties (Tab. 1). The filament feeding speed was used in accordance with the manufacturer's recommendations, and print cooling was also applied. The layer height of 0.21 mm was adopted.

Samples for comparative purposes made of injected ABS were produced on a Krauss Maffei type KM with a 30 mm diameter screw, LD ratio of 23, constant pitch over the entire length and mold closing force of 650 kN. The optimal properties of the specimens were obtained for the following injection parameters recommended by the material manufacturer:

| Sample | Nozzle temperature, °C | Table temperature, °C | Printing speed, mm/s | Fulfilment, % |
|--------|------------------------|-----------------------|---------------------|--------------|
| LAYWOOD | 230                    | 55                    | 60                  | 96           |
| ABS    | 230                    | 100                   | 60                  | 96           |
| PLA    | 230                    | 55                    | 60                  | 96           |
| PET    | 242                    | 60                    | 50                  | 96           |
| TPU    | 250                    | 60                    | 25                  | 96           |

An analysis of the dynamic thermal properties was carried out with the NETZSCH DMA 242 device with a handle for a three-point free bending sample in the form of a beam with the dimensions of 50×10×4 mm. The samples in the holder were subjected to a sinusoidal force of 1 Hz and 10 Hz with constant amplitude, while heating the samples at a rate of 3 °C/min from 20 °C to a different temperature for the materials tested (Tab. 2).

The elastic modulus $E'$ and the mechanical loss factor $\tan \delta$ were calculated on the basis of force and strain values in relation to the dimensions of the samples. In order to be sure of the results, all tests were repeated for three samples.

3 DISCUSSION OF RESEARCH

The results of the analysis of dynamic mechanical properties are presented in Figs. 1 - 5a, 5b in the form of graphs of changes in the modulus of the elasticity and tangent of the angle of the mechanical losses depending on the temperature and the frequencies of 1 and 10 Hz. In the case of LAYWOOD, it was observed that the polymer is in the elastic deformation phase of about 54 °C. You can then see a quick transition to the glass transition phase state. At the beginning of the elastic deformation phase, the $E'$ module is strongly dependent on the temperature of −30 °C and the relationship decreases significantly. In this phase, the $E'$ module drops from 2700 MPa to 1800 MPa at 54 degrees Celsius. In this phase, it can be concluded that the tangent of the mechanical loss angle is characterized by a small dependence on the temperature, ranging from −10 °C to 54 °C. The transition to the elastoplastic state occurs rapidly at 54 °C, when the $E'$ module rapidly decreases with a simultaneous sudden increase in $\tan \delta$ several times. This means that the polymer begins to bend and does not back to its normal shape, i.e. it bends permanently. That is why the machine could not read the data and that is why the chart ends at about 62 °C.

Tab. 2 Temperatures of the DMTA testing

| Sample | DMTA |
|--------|------|
| LAYWOOD | −50 °C - 60 °C |
| PLA    | −50 °C - 60 °C |
| TPU    | −50 °C - 170 °C |
| ABS    | −50 °C - 190 °C |
| PET    | −50 °C - 200 °C |

Fig. 2 is similar to Figure 1 because the LAYWOOD material is made of PLA with the addition of wood chips, which is why DMTA for PLA ends in the same way as LAYWOOD.

In the elastic deformation phase of PLA DMTA, which ends at −57 °C, the $E'$ modulus shows a negligible temperature dependence and is shaped at 4800 MPa, while the $\tan \delta$ values increase almost twice, showing a strong temperature dependence. The glass transition phase starts at 51 °C and the chart ends at about 62 °C for reasons similar as to why LAYWOD is characterized by an extension between −42 °C and 56 °C. In this phase, the $\tan \delta$ increases slightly to 0.08, and finally the phase is reduced to 0.05, followed by an increase in the tangent of the mechanical loss angle, which indicates the variability of vibration damping and material rigidity in the glass transition phase and a strong temperature dependence of the mechanical loss angle [9,12,16].

In the case of TPU (Fig. 3), the elastic deformation phase ends at −47 °C. The glass transition phase occurs in a wide temperature range, form −47 °C to 30 °C, in which $E'$ and $\tan \delta$ show a strong temperature dependence. A high-viscoelastic deformation phase is extended in a wide temperature range: between 30 °C and 95 °C, and here you can see a strong temperature dependence of $\tan \delta$, which indicates the variability of vibration damping and material rigidity. The high-viscoelastic deformation phase begins with a rapid reduction in the value of $\tan \delta$ (from 0.17 to 0.04), which is associated with strong elasticity at ambient temperatures and a poor dependence of the $E'$ module on the temperature. In the elastic transition phase, it starts at 95 °C, where the polymer begins to flow.
Fig. 1 shows the dependence of tanδ and $E'$ on temperature and frequency for PET. This material is a brittle and rigid body in the elastic deformation phase up to 73 °C, in which tanδ and $E'$ are poorly dependent on temperature. In the glass transition phase, the dependence of $E'$ is substantial, because the $E'$ modulus is reduced from 2400 MPa to 200 MPa, tanδ shows a notable temperature dependence rising from 0.05 to 0.5 and at the end of the phase, it drops to 0.18 at the smallest frequency of extortion. The high-viscoelastic deformation phase begins with a rapid decrease of tanδ (1 Hz) from 0.18 to 0.02 at 122 °C and at this temperature, the high-viscoelastic deformation phase begins [16-18]. Maximum tanδ indicates that PET samples made in 3D printing do not show a high vibration damping ability and are characterized by low stiffness in relation to the other tested materials.
Figure 4 Results of DMTA investigations of PET: A - elastic deformation phase; B - glass transition phase; C - high-viscoelastic deformation phase; D - elastic transition phase.

Figure 5 Results of DMTA investigations of: a) ABS from 3D printing, b) ABS from injecting: A - elastic deformation phase; B - glass transition phase; C - high-viscoelastic deformation phase.
The graph of Fig. 5a shows the course of changes of the module $E'$ and $\tan\delta$ as a function of temperature and frequency of vibrations for ABS. In the case of ABS, the elastic deformation phase ends at 93 °C, smoothly going into the glass transition phase with a low temperature variation of $E'$ and with a lack of $\tan\delta$ temperature dependence. The glass transition phase is characterized by almost tremendous temperature compliance at 93 °C, and the module $E'$ drops from 1450 MPa to 100 MPa, $\tan\delta$ also shows temperature dependence because it goes from 0.1 to 1.2 and at the end of the phase drops to 0.6. In the high-viscoelastic deformation phase, $\tan\delta$ modules exhibit high temperature dependence, the $\tan\delta$ (1 Hz) drops to 0.1 at 146 °C. This polymer exhibits high stiffness and a very high vibration damping ability compared to the other tested samples as evidenced by the maximum $\tan\delta$ relaxation conversion for the smallest frequency of extortion.

The graph of Fig. 5b shows the course of changes of the module $E''$ and $\tan\delta$ as a function of temperature and frequency of vibrations for the ABS samples obtained by injection molding. These samples have the A phase, which starts from 2500 MPa, and it is more than the ABS printed samples have; in phase B, the module $E'$ drops very fast from 2000 MPa to 150 MPa, and this drop is faster that in the printing samples, but $\tan\delta$ in this phase is rising only to 0.45, i.e. it is 0.75 lower than in the 3D printed ABS. The phase C of the injected ABS is characterized by a fast drop of the $\tan\delta$ comparing to the printed ABS, because $\tan\delta$ reaches the lowest level at 134 °C, while printed ABS reaches the lower level of $\tan\delta$ at more than 150 °C [6, 11-14, 19].

4 CONCLUSIONS

An analysis of the results indicated that the samples made of Semi-Crystalline Polymers are characterized by an extended glass transition phase, in which the $E'$ and $\tan\delta$ modules have strong temperature dependence. LAYWOOD and PLA are characterized by an extended glass transition phase, after which the material begins to flow. On the other hand, the TPU polymer is characterized by a glass transition phase in which both the $\tan\delta$ and $E'$ modulus show a high temperature dependence at the lowest temperature in the samples tested. In PET, as well as the ABS, in both high-viscoelastic deformation phases, there is no temperature dependence of $E'$ and $\tan\delta$ is decreasing to the lowest level showing high temperature dependence. Analyzing the changes in the tangent value of the mechanical loss angle, it was found that the highest stiffness and damping ability is found in ABS in comparison to the remaining samples tested. The smallest stiffness and low vibration damping capacity is characterized by PLA. Moreover, ABS obtained from injection seams to act more stable when we heat it, but ABS samples obtained from 3D printing have a better vibration damping ability than the injected samples. 3D printing also has some disadvantages such as: long production time comparing to the injection time, printed elements have pores that allow air and water to get through, it is impossible to get sharp angles because printers are limited by nozzle dimensions, when angle is lower than 20 degrees, the printer will cut an area at end of angles due to minimal wall thickness, etc. Moreover, some of the printing filaments release intense chemical vapours that are harmful.

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