Statistical Economics on Multi-Variable Layered Networks

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Abstract. We propose a Statistical-Mechanics inspired framework for modeling economic systems. Each agent composing the economic system is characterized by a few variables of distinct nature (e.g. saving ratio, expectations, etc.). The agents interact locally by their individual variables: for example, people working in the same office may influence their peers’ expectations (optimism/pessimism are contagious), while people living in the same neighborhood may influence their peers’ saving patterns (stinginess/largeness are contagious). Thus, for each type of variable there exists a different underlying social network, which we refer to as a “layer”. Each layer connects the same set of agents by a different set of links defining a different topology. In different layers, the nature of the variables and their dynamics may be different (Ising, Heisenberg, matrix models, etc). The different variables belonging to the same agent interact (the level of optimism of an agent may influence its saving level), thus coupling the various layers. We present a simple instance of such a network, where a one-dimensional Ising chain (representing the interaction between the optimist-pessimist expectations) is coupled through a random site-to-site mapping to a one-dimensional generalized Blume-Capel chain (representing the dynamics of the agents’ saving ratios). In the absence of coupling between the layers, the one-dimensional systems describing respectively the expectations and the saving ratios do not feature any ordered phase (herding). Yet, such a herding phase emerges in the coupled system, highlighting the non-trivial nature of the present framework.

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1 Introduction

Statistical Mechanics provides a universal framework to model and analyze large systems with interacting components, even beyond the traditional realm of physics. Many techniques of Statistical Mechanics are applied today in diverse areas of scientific research, such as biology, sociology and economics\[^1\]. A decade ago, the economist Jean-Michel Grandmont\[^2\] coined the term *Statistical Economics*, pointing to the analogy between large economic systems and large physical systems, and suggested that large economic systems can be appropriately modeled using techniques developed in Statistical Mechanics\[^3\].

For Statistical Economics to benefit from the vast knowledge that accumulated in Statistical Mechanics, it is crucial to establish which structures are shared by physical and economic systems, and which are essentially different. Economic systems, like physical systems, involve local interactions of both attractive and repulsive type. To formalize such interactions, a Boltzmann-Gibbs measure derived from a Hamiltonian function is an appropriate formal object. However, a proper interpretation of the Hamiltonian is still an open issue in economics. While in the present paper we work within the Hamiltonian formalism, the ideas herein apply also to dynamical systems\[^4,5\] that do not admit an energy function, i.e. the interactions may be asymmetric.

The locality of the interactions raises the issue of the structure of the underlying network. In physics, a regular lattice is often an adequate approximation of the graph structure underlying the interaction in the real world. In contrast, economic dynamics involve social networks, for which a regular graph topology is usually a very rough and often unjustifiable approximation. Scale-free graphs are presumably more appropriate, yet empirical evidence on the actual structure of communication and social networks is only beginning to emerge\[^6\]. For theoretical and empirical results in this emerging field we refer the reader to\[^7,8\].

Lately agent-based economic models have been introduced that take into account the inhomogeneous character of the various agent variables. However, the connections/interactions between the agents were usually represented by a single network. In the present paper we address a different aspect of economic systems: their multi-layered structure (Figure 1).

Isolating the economic interactions of one type (e.g. wealth exchange) from the wider economic context of the agents’ interactions (e.g. exchange of convictions, preferences, expectations, risk attitudes, assets etc.) is often unrealistic. In general, individual economic decisions result from an interplay of such distinct variables. In fact, it is a pillar of classical economics that diverse individual variables interrelatedly determine decisions. Yet, such systems have found so far little attention in Statistical Economics models\[^8\].

In the present paper we aim at formulating a general framework for modeling economic systems, where each agent is characterized by multiple variables of

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\[^1\] Multi-layered models of a different nature were considered in other areas of physics-inspired research, like neural networks\[^9\] and opinion formation\[^10\].
distinct nature. Each type of variable constitutes a layer with a particular graph structure, with only the set of nodes (agents) common to all layers. In addition to local interaction of neighboring variables within a layer, variables associated with the same agent in different layers interact. This introduces coupling between the layers, which qualitatively changes the dynamical pattern of every layer. We call a system with the above properties a “Solomon Network” (SN) \(^2\).

At first glance, the dynamics of each layer in a SN may look similar to a single variable system in some external field provided by the rest of the variables. Yet, SN models are unique in the sense that the interaction between layers is bi-directional, allowing for feedback between each layer and its “external” field. The dramatic effect that this feedback can have on the system behavior is demonstrated already at the level of the simplest model described below. This is a step toward substituting the usual closed system and stationary/quenched environment paradigm with economics models that provide a wider and interactive (and reactive) representation of the environment.

The topology of the coupling between the layers in a SN is formally characterized by the mapping between the nodes of the different layers. In physical systems the graph structure is often formalizing physical proximity, and therefore if a physical system would be under investigation, we would expect such a mapping to be isometric (preserving distance). In contrast, social networks formalize communication links rather than physical proximity. Therefore, preserving distance is not a natural property of a mapping between different social networks. It may well be the case that an agent’s reference group for a certain social or economic interaction is entirely different from her reference group for another type of interaction. For example, we may think of a scenario where, for certain people, consumption and saving patterns are formed by comparing themselves to people who live in their residential neighborhood, while their expectation of the general state of the market is formed through discussions with their colleagues at work. These two reference groups may be totally distinct, or have any degree of correlation (overlap). In general, the graph structures associated with different layers may differ; for example, a random graph may be coupled with a regular graph. Moreover, one may extend the above definition of SN to include cases in which the site correspondence between the layers is not one-to-one (e.g. people that do not go to work, or people who work in more than one place).

As a first step toward an understanding of such models and the properties of corresponding economic systems, we formulate in Section 2 a simple model with only two layers. In section 3 we discuss the theoretically expected properties of the model and in section 4 we study the model by using Monte Carlo simulations. We return to the general paradigm and discuss its possible ramifications in Section 5.

\(^2\) This nomenclature has been introduced by Dietrich Stauffer with reference to the biblical dilemma of an agent being “claimed” by (i.e. is part of) different social networks.
Let $A$ denote a set consisting of $N$ economic agents. Each agent $i \in A$ is characterized by two random variables. First, the variable $X_i$ represents the agent’s saving ratio, i.e. the proportion of the individual budget which is saved, rather than consumed. Each variable $X_i$ takes values in the set $S_x = \{1, 2, \ldots, Q\}$ with some natural number $Q$. To interpret $X_i$ as a savings ratio, one considers $\frac{1}{Q}X_i$ rather than $X_i$.

Second, the variable $S_j$ represents the agent’s expectation about the prospects of the economy. For simplicity, we allow only two individual states, called “optimism” and “pessimism”. Accordingly, each variable $S_j$ takes values in the set $S_s = \{-1, 1\}$, and we arbitrarily interpret 1 as “optimism”, and $-1$ as “pessimism”.

Thus we define two layers for the model consisting respectively of the variables $(X_i)_{i \in A}$ and $(S_j)_{j \in A}$. Both layers are modeled as spin systems with nearest-neighbor interaction, with respect to the graph structure underlying each layer. In addition, there is interaction between those pairs of variables from different layers, which correspond to the same agent. Thereby the two spin-fields are coupled.

In the present simple SN model, we confine ourselves to one-dimensional layers with periodic boundary conditions (chains). Thus, the agent $i$’s neighbors in the $X$-layer are $(i+1) \mod N$ and $(i-1) \mod N$. The neighborhood relation on the $S$-layer is specified through a permutation $r$ of the elements of $A$. More precisely, the agent $i$ is represented on the layer $S$ by the site $r(i)$. Accordingly, the two variables associated with agent $i \in A$ are $X_i$ and $S_{r(i)}$. The neighbors of $r(i)$ in $S$ are $(r(i)+1) \mod N$ and $(r(i)-1) \mod N$. Thus the agent $i$ interacts directly with four agents: $i+1$, $i-1$, $r^{-1}(r(i)+1)$, and $r^{-1}(r(i)-1)$. Note that the interaction with the first pair is of a different nature (and in fact parametrized by different variables) than the interaction with the other pair. Note also that in this model we have chosen a one-to-one, totally random correspondence between the layers.

We denote by $S = \{-1, 1\} \times \{1, 2, \ldots, Q\}$ the individual spin-space of the composite system. A configuration assigns to each agent $i \in A$ values from $S$. The configuration space, denoted as usual by $S^A$, consists of $(2Q)^N$ configurations.

The dynamics is defined by introducing the Hamiltonian function $H$ that assigns to each configuration $\omega \in S^A$ some real number $H(\omega)$, such that the probability of $\omega$ is given by the Boltzmann distribution associated with $H$

$$Pr(\omega) = 1/Z_T \exp(-H(\omega)/T). \tag{1}$$

with $T$ denoting the temperature parameter of the Boltzmann distribution, and $Z_T$ being the normalizing constant given by $Z_T = \sum_{\omega \in S^A} \exp(-H(\omega)/T)$. The ratio $H/T$ measures the relative strength of the social interaction of the system against other random perturbations. For $T = 0$ the peer pressure is absolute, and basically the individual has no freedom. For $T = \infty$, there is no influence between any of the variables and all states of the system are equally probable.
In our model, there are three components of interaction: 1) the nearest-neighbor interaction among different agents on the \(X\)-layer, 2) the nearest-neighbor interaction among different agents on the \(S\)-layer, and 3) interaction between the variables corresponding to the same agent in the two layers.

The term in the Hamiltonian representing the interaction within the \(X\)-layer is specified as
\[
H_X(\omega) = J_x \sum_{<i,j>^X} (X_i(\omega) - X_j(\omega))^2. \tag{2}
\]
with \(<i,j>^X\) denoting the summation over pairs of nearest neighbors according to the \(X\)-layer topology. The basic economic content of this specification is the notion of herding behavior \([11,12]\). That notion stands in economics for a variety of effects where market actors, such as stock traders, consumers, managers etc., tend to align their opinions and/or actions with those in their social neighborhood. In our case, if the current state \(X_i\) of the agent \(i\) is very different from the typical opinions \(X_j\) of its neighbors \(j\), Eq. 2 indicates a strong energy preference for the next moves to bring \(X_i\) and \(X_j\) closer. This specification is in accordance with experimental results from social psychology \([6,13,14]\) suggesting that the likelihood of realignment of one’s own actions and beliefs (i.e. the saving behavior, in the present model) with those observed in the reference group, will increase with the perceived difference in those actions and beliefs. In physics, a Hamiltonian of the above type have been used, for instance, in the Blume-Capel model \([15,16]\).

A similar herding behavior is observed for the agents’ expectations: the expectations of the individuals, with respect to the future market behavior, will tend to conform with the opinion of their social surrounding. Thus the interaction between the agents’ expectations has a similar form as Eq. 2. Since we use a rougher characterization of expectations (-1 corresponds to a pessimist view, and +1 corresponds to an optimist view), the interaction on the \(S\)-layer reduces to the classical Ising-model Hamiltonian:
\[
H_S(\omega) = J_s \sum_{<i,j>^S} (S_i(\omega) - S_j(\omega))^2. \tag{3}
\]
If \(Q = 2\), the \(X\)-layer is also an Ising chain, and the model reduces to a classical Ising model on a peculiar SN graph structure. This special case was discussed in \([17]\). However, a key property of the SN framework is, in our view, the distinct character of the respective layers, both in terms of the spin-space and the underlying graph structure.

To complete the definition of the system, one has to specify the interaction between variables corresponding to the same agent in the two layers, i.e. \(X_i\) and \(S_{r(i)}\). This interaction expresses the prominent economic behavioral regularity that an optimistic agent is likely to save less than a pessimistic agent \([18]\). Thus we introduce a term that couples the variables corresponding to the same agent:
\[
H_C(\omega) = J_c \sum_i (X_i(\omega) - C(S_{r(i)}(\omega)))^2. \tag{4}
\]
The function \( C(\cdot) \) goes from \( S_s \) to the real numbers, with \( C(-1) > C(1) \). Obviously, when \( J_c = 0 \), the system breaks down to two independent chains.

Finally, the Hamiltonian of the system is obtained by adding the three components:

\[
H(\omega) = H_X(\omega) + H_S(\omega) + H_C(\omega). \tag{5}
\]

Since (cf. Eq. 1) the parameters of the model appear dynamically in the combination \( H/T \), we will often consider the coupling parameters \( J \) as constants and study the behavior of the system under the variation of \( T \). Thus in the following we use the parameter \( \beta = 1/T \) as a measure of interaction-to-noise ratio in the economic system.

In the next two sections we will discuss this system from the theoretical and respectively simulation point of view.

3 Discussion of the Expected Model Properties

For complete characterization of the phases of the model, one may have to perform numerical simulations of the type we present in the next section. However, the experience accumulated in the last 30 years in Statistical Mechanics can be used to extract quite a number of predictions and intuitions about the model, and especially its herding (order-disorder transition) properties.

While the SN model was not studied before, the properties of each layer in separate are covered by rigorous general theorems \[19\]. To understand the import of the theorems let us start with the behavior of the decoupled layers at \( T=0 \). In this case, both layers are in a “ground state”, i.e. the state of minimal energy.

The case of the \( S \) layer is easier to analyze. The minimal energy is realized for \( S_i = S_0 \forall i \), with \( S_0 = \pm 1 \). In general, for dimensions larger then one, there exists a critical value \( T = T_c \) such that for the entire range \( T < T_c \) the system remains ordered. Indeed, for \( T_c > T > 0 \), the configurations are not exactly uniform, but the \( S_i \)'s across the entire system remain “herded” around one of the values \pm 1. The degree of herding of each configuration \( \omega \) is measured by the magnetization \( M \) defined as the average of the \( S_i(\omega) \) over the entire range \( i \in A \):

\[
M = \frac{\sum_i S_i}{N} \tag{6}
\]

The transition at \( T_c \) between the ordered \((M \neq 0)\) and disordered \((M = 0)\) phases is called, following the Statistical Mechanics conventions, a Phase Transition. In the present article we will use interchangeably the words “magnetization” and “herding” to denote \( M \).

Interestingly enough, in one-dimensional systems the order-disorder phase transition is absent \((T_c = 0)\)[19]. Thus, theory predicts the absence of herding in the absence of coupling between the “expectations” layer and the “savings/consumption” layer of our model. In fact, rigorous theorems insure that
ANY system with local interactions in one dimension is in the disordered phase for any $T > 0$. Thus, even the coupled system will not present herding, as long as the two layers have a roughly similar metric (i.e. $|r(i) - i| < N \forall i$). Only when the two layers have significantly different neighborhood assignments a herding phase can emerge at finite $T$. This is because such a system would not be amenable to the format of a one-dimensional model with local interactions. Moreover, the transition between the herding and disordered phase will have a character that is not necessarily the one characteristic to any of the higher dimension Ising (or Blume -Capel) models. The Monte Carlo simulations we report in the next section confirm these predictions.

In higher dimensions each of the layers, when taken independently, may display quite different critical parameters $T_{X}^{c} \neq T_{S}^{c}$. As one brings the layers “in contact” by making them interact, the composite system might preserve two independent phase transitions (if the inter-layer interaction is weak) or change its behavior qualitatively.

One may ask how relevant is the phase transition analysis for an actual system. After all, it is a priori probable that the parameters of the system realized in nature are far from the critical ones. Thus the system would spend its entire life span in just one phase and ignore the other. The answer is that it falls upon the shoulders of the modeler to identify the interactions and parameters that DO matter qualitatively in the real system. Modeling interactions that do not matter is of course useless (nobody would model the current financial markets in terms of the issue of whether the dollar is or not going to be devaluated by 100% during the current trading day or whether the side of the road on which the cars drive would spontaneously flip). Thus pessimism and optimism, and in general the values that the dynamical variables can take, should be and are usually chosen such as to reflect operative possibilities so that the system may very well be in either phase.

Given that a phase transition (say herding-disorder) exists, one may wonder whether establishing its type (universality class) in detail is of interest in economics. The difference between a discontinuous (first order) phase transition and a continuous one may give precious indications on whether to expect large fluctuations or rather a plain collapse. Even if the transition is continuous, it is often important to know which of the layers has the dominating role in triggering it.

4 Monte Carlo Study of the Model

We simulated the above-defined model using standard Monte Carlo simulation methods. In particular, we update the agents’ state in a random order. Each Monte Carlo Step (MCS) is composed of $N$ such random selections. In each computational step, after an agent $i$ is chosen at random, we run a Heat-Bath algorithm to generate the next state. The new values for the selected $X_i$ and $S_i$ are sampled according to the Boltzmann distribution (Eq. 1) with respect to the potential $H$ (cf. Eq. 5): given a particular configuration of the system $\omega \in \mathcal{S}^A$, 
let us denote \( \omega^i_{x,s} \) the configuration of the system which is identical to \( \omega_i \) except for the variables associated with agent \( i \), where \( X_i = x \) and \( S_{r(i)} = s \). The probability to move from \( \omega \) to \( \omega^i_{x,s} \) is given by the following equation:

\[
P(x,s) = 1/Z^i T \exp(-H(\omega^i_{x,s})/T)
\]  

(7)

where \( Z^i T = \sum_{(x,s) \in S} \exp(-H(\omega^i_{x,s})/T) \) i.e. the sum over all possible values for \( X_i \) and \( S_{r(i)} \).

In the present investigation, we simulated a system with \( N = 10^6 \) agents and \( Q = 10 \) saving ratios. Our simulations around the \( T_c \) consisted of \( 6.4 \times 10^5 \) MCS, and the results were averaged over the last \( 3.2 \times 10^5 \) MCS. Less iterations were needed for the \( T \) ranges outside the critical slowing-down zone, where \( 2 \times 10^4 \) MCS were sufficient, and the results were averaged over the last \( 10^4 \) MCS in that case. Unless stated otherwise, simulations were run with \( J_s = J_x = J_c = \frac{1}{3} \), \( C(-1) = 8 \) and \( C(1) = 3 \). The initial conditions were set to either the ordered configuration \( (S_j = -1 \text{ and } X_i = 8) \) or to a totally random one. We obtained the randomly generated permutations \( r \) by mapping every \( X \)-layer site to a \( S \)-layer site chosen from the entire lattice with equal probability.

We found a phase transition occurring at a critical value of approximately \( T_c = 2.79 \). Both layers become ordered below \( T_c \). Figures 2 and 3 depict the herding of each of the two layer as a function of \( T \). The functional dependence of the herding \( M \) on \( T \) close to \( T_c \) appears to be: (cf. Figures 2b and 3b)

\[
M \propto 1/\log(T_c - T).
\]

(8)

In contrast, [17] measured the critical exponent \( \beta \) of the SN model with two Ising layers to be \( 1/2 \) (i.e. in the Ising universality class). Therefore this feature of the model is attributed to the coupling of two layers carrying different dynamics, and not merely a result of the particular topology.

The two ordered states (\( M < 0 \) and \( M > 0 \)) for \( T < T_c \) can be called “pessimistic economy” and “optimistic economy” respectively. The transition between them is a first order one similar to the transition when crossing the line of zero magnetic field \( H = 0 \) below the critical Ising temperature. Thus our model is capable of capturing empirical results describing dramatic swings in the market mood [22]. Moreover the model predicts that in the herding phase, the transition between an optimistic and pessimistic mood in the \( S \)-layer induces a transition between the “saving” and “spending” modes in the \( X \)-layer.

A variable of major interest for economics is the empirical distribution of the \( X \)-layer, since it characterizes the aggregate saving in the economy. Figure 4 depict empirical distributions of the \( X \)-layer at different \( T \)'s. The distribution is symmetric above \( T_c \), i.e. in the disordered state. Below \( T_c \), the distribution is skewed, reflecting symmetry breaking in the herded state. If \( C(-1) \) and \( C(1) \) are further apart, the empirical distribution of the \( X \)-layer for \( T > T_c \) becomes bimodal (Figure 5).

In accordance with the theoretical prediction, no phase transition was found in simulations where \( r(\cdot) \) was the identity permutation (results not shown), since the system is essentially one-dimensional. Also, when the layers are defined on
similar lattices (as is the case in our simulations), one may construct the \( r \)-
transformation to be bound (i.e. \( |r(i) - i| < C_0 \forall i \)). In this case as well, no
ordered phase emerges (results not shown). According to the theory, the ordered
phase shrinks to \( T = 0 \) as one lowers \( J_c \to 0 \) (Figure 6).

In order to connect the model to the actual economic reality, one can calibrate
the model by comparing it to empirically measurable data. In particular one can
measure the size of the various groups as defined by their expectations and saving
patterns. From this, one can infer by inverse engineering the realistic values for
the coupling constants in the model. We studied the relation between the sizes
of the groups and the values of the \( J \)'s as described below. In the “pessimistic”
phase, the agents \( i \in A \) with \( s_r(i) = -1 \) and \( x_i \in \{6, \ldots, 10\} \) constitutes the
majority. In contrast, we can arbitrarily define three different minority groups.
First, the set of agents with \( s_r(i) = 1 \) and \( x_i \in \{6, \ldots, 10\} \) is called \( S \)-minority;
second, the set of agents with \( s_r(i) = -1 \) and \( x_i \in \{1, \ldots, 5\} \) is called \( X \)-minority;
and the set of agents with \( s_r(i) = 1 \) and \( x_i \in \{1, \ldots, 5\} \) is called \( SX \)-minority.
The values chosen for the coupling constants \( J \) determine the balance between
the different minority groups. Figure 7 shows the distribution of the different
minority groups for various ratios of the interaction constants. If a certain inter-
action constant increases, the proportion of the corresponding minority group
will decline for every \( T < T_c \). For example, when \( J_s = 0.6 \) and \( J_x = 0.2 \), the
\( X \)-minority group is downsized considerably (Figure 7). This is because every
agent “prefers” conforming to its neighbors on the \( S \)-layer (i.e. having the same
\( S \) value), even at the “price” of non-conformity with its neighbors on the \( X \)-layer
(i.e. having a different \( X \) value). Also, this figure shows certain symmetry of the
\( J \)'s. Both layers respond equally to increased preference, at least in the aspect of
minority ratios - the same preference imbalance results in the same bias in the
distribution between minority groups.

5 Conclusions and Outlook

In the present paper we have presented one of the simplest instances of an
application of the SN framework to economic systems modeling. Already at this
level one obtains interesting results, underlying the importance of the coupling
of the various types of economic variables in determining the order-disorder
dynamics of the global system.

Using representative agents, population averages or differential equations
governing the global (macro-economic) system variables, one might have guessed
that by coupling weakly two types of economic variables that do not present
herding the resulting system will be in the disordered phase, i.e. the coupled
system would behave somewhat as the average of the respective behaviors of its
components. Instead, using theoretical and simulation tools adapted from Statis-
tical Mechanics one finds that the coupling of two disordered economic variables
has a dramatic herding effect on both variables. This shows the importance of
the further study of SN models in uncovering the subtle effects of feedback in
systems with multiple economic variables.
The study of SN models can be developed in quite a few directions. First, instead of the completely random mapping \( r(i) \) between the positions of the nodes in different layers, one may consider less extreme alternatives: after all, there is often some correlation between the workplace of people and their residence districts. For instance, one may consider mappings in which for a significant number of \( i \)'s one has \( r(i) = i \), or mappings which preserve the topology of the neighborhoods but not their metric. This might elucidate which properties of the SN model can be traced to the mere coupling between layers (and thus possibly detectable by standard macro-economic methods), and which are a result of the particular inter-layer projection afforded by the SN framework.

Second, one should consider inhomogeneous layers, e.g. scale-free or small-world, and study projections \( r(i) \) of different types (e.g. preserving rank or not etc.). Of course the various layers may differ in their properties, such as their scaling exponent, clustering coefficient or K-core structure[23].

The SN modeling framework can also be extended to include global feedback schemes, which are particularly relevant in economic applications[24]. We intend to pursue this direction of research elsewhere[25].

To make contact with reality, one should find and use the parameter values that represent faithfully and realistically the empirics of the modeled economic phenomenon. For example, by looking at relative sizes of the herding groups with respect to various variables, one may receive hints as to the relative strength of the couplings governing each variable. This would require the use of cross-correlational micro-data. Such data exists, for instance, for savings and consumer confidence[26].

In summary, we believe that the framework of Solomon Networks addresses a key property of large economic systems - the cross-interaction between the dynamics of economic variables of different types. Further investigation of such models may shed light on the mechanisms governing economic dynamics, and increase our understanding of the complex system called Economy.

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Fig. 1. A schematic representation of the Solomon Network architecture. Each agent is represented by two variables, one on each layer, connected by a curved line, while thick lines represent nearest-neighbor relations on each layer. Not all the intra-layer neighbors of the agents are depicted. Two elements are of special interest: the variables on each layer are of a different type, and the neighbors of an agent on one layer are not her neighbors on the other layer.
Investigating The Scaling Law Of The S layer Near $T_c$

**Fig. 2.** Herding of the expectations as a function of $T$. Figure 2a displays the main feature of the model: as opposed to the behavior of the separate expectations and savings layers, the composite system present 2 distinct phases: one without herding $M = 0$ for $T > T_c$ and one with $M > 0$ for $T < T_c$. Figure 2b demonstrates the dramatic nature of the vanishing of the herding $M$ of the expectations as one approaches $T_c$ by showing that $M \propto 1/\log(T_c - T)$, i.e. all the derivatives are infinite at the vanishing point.
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Fig. 3. Similar results as in Figure 2, this time for the herding of the savings ratios. Since $X_i$ ranges between 1 and 10, 5.5 is the average value in the unordered phase.
Fig. 4. Empirical distribution of individual saving ratios ($X_i$) at different values of $T$. Figure 4a depicts the distribution of $X_i$'s at various $T$'s in the non-herding phase. At $T = \infty$, the distribution is uniform (not shown). Note how all distributions are symmetric in the non-herding phase. Figure 4b depicts the empirical distribution of $X_i$ at various values of $T$ in the herding phase. In the particular shown case, the herding pattern is in the “saving” mode and the distribution is skewed towards high $X_i$ values. Not shown, is the corresponding distribution of the $S$-layer which was in the herding “pessimistic” phase.
Fig. 5. Empirical distribution of individual savings ($X_i$) in the unordered phase for different values of $C(\cdot)$. If $C(1)$ and $C(-1)$ are far enough from each other, a bimodal distribution emerges, since most $X_i$ are in correlation with $S_{r(i)}$, and the $S$ variables are distributed equally between 1 and -1 at the unordered phase.

Fig. 6. Dependence of the $T_c$ on $J_c$. $J_x$ and $J_s$ are both held fixed at a value of $\frac{1}{3}$. As $J_c$ vanishes the system effectively decouples into two independent one-dimensional chains, and $T_c$ approaches 0.
Fig. 7. Comparing ratios of various minority groups, out of the total number of agents not in the majority group, at different values of coupling parameters. Note that for each set of bars, the ratios sum to 1. The effect of increasing the relative importance of one layer over the other is symmetric. When $J_x = J_s$, the minority groups are symmetrical independently of $J_c$. 