On Inference of Overlapping Coefficients in Two Inverse Lomax Populations

Hamza Dhaker¹*, El Hadji Deme², Salah El-Adlouni³

¹Département de mathématiques et statistique, Université de Moncton, NB, E1A 3E9, Canada
²LERSTAD, UFR SAT, Université Gaston Berger, Saint-Louis, Senegal

ABSTRACT
Overlapping coefficient is a direct measure of similarity between two distributions which is recently becoming very useful. This paper investigates estimation for some well-known measures of overlap, namely Matusita's measure \( \rho \), Weitzman's measure \( \Delta \) and \( \Lambda \) based on Kullback-Leibler. Two estimation methods considered in this study are point estimation and Bayesian approach. Two inverse Lomax populations with different shape parameters are considered. The bias and mean square error properties of the estimators are studied through a simulation study and a real data example.

1. INTRODUCTION
Inverse Lomax distribution is a special case of the generalized beta distribution of the second kind. It is one of the notable lifetime models in statistical applications. The inverse Lomax distribution is one of significant lifetime models. Kleiber and Kotz [1] used this inverse Lomax distribution to get Lorenz ordering relationship among ordered statistics. McKenzie et al. [2] applied this life time distribution on geophysical data on the sizes of land fires in the California State, United States.

The overlapping coefficients (OVL) represents the proportion of overlap between two probability density functions (pdfs) as a measure of similarity between distributions. Generally it is measured on the scale of 0 to 1 (see Figure 1). Values of measure close to 0 corresponding to the distributions having supports with no intersection and 1 to the perfect matching of the two distributions. This paper investigates point and interval estimation for four measures of overlap (OVL) for two inverse Lomax populations with different shape parameters.

- Matusia's measure [3]

\[
\rho = \sqrt{f_1(x)f_2(x)}dx
\]

- Weitzman's measure [4]

\[
\Delta = \int \min\{f_1(x), f_2(x)\}dx
\]

- OVL-based Kullback and Leibler [5]

\[
\Lambda = \frac{1}{1 + KL(f_1 \parallel f_2)}
\]

with \( KL(f_1 \parallel f_2) = \int (f_1(x) - f_2(x)) \log \left( \frac{f_1(x)}{f_2(x)} \right) dx \)

*Corresponding author. Email: hamza.dhaker@umoncton.ca
The mathematical structure of these measures is complicated; there are no results available on the exact sampling distributions of the commonly used OVL estimators. Researchers such as Smith [6] derived formulas for estimating the mean and the variance of discrete version of Weitzman’s measure using the delta method. Mishra et al. [7] gave small and large sample properties of the sampling distribution for a function of $\Delta$ under the assumption of homogeneity of variances. Recently, several authors including Al-Saidy et al. [8], Clemons [9], Dhaker et al. [10], Inman and Bradley [11], Jose et al. [12], Mulekar and Mishra [13] and Reiser and Faraggi [14] considered this measure.

In this article, we consider the point and interval estimation for some measures of overlap (OVL) for two inverse Lomax populations with different shape parameters using “Simple Random Sample (SRS) and Ranked Set Sampling (RSS) and Bayesian methodology.”

The first method (RSS, McIntyre [15]) was earlier applied by Helu and Samawi [16] for the point and interval estimation of the overlapping coefficients for two Lomax distributions. We will use their methodology for the point estimate and interval in the case of inverse Lomax distribution. The second approach, we use another method for parameter estimation using Bayesian inference [17].

The primary purpose of this study is to compare the confidence intervals for the overlap coefficients ($\rho$, $\Delta$ and $\Lambda$) computed using SRS, RSS, Bayesian methods. Section 2 defines the inverse Lomax distribution and derivations of the three OVL measures. In Section 3 we draw some statistical inference on the OVL measures using SRS. Section 4 draws an inference on the OVL measures using RSS. In Section 5, we provide Bayesian estimators along with approximate bias and variances for the three measures of overlap. In Section 6, a simulation study is performed to evaluate and compare biases and mean square errors of OVL measures estimates. In Section 7 we give an example using a real dataset. Finally, the conclusion is presented in Section 8.

2. OVL MEASURES FOR INVERSE LOMAX DISTRIBUTION

A random variable $X$ is said to have a Lomax distribution if the corresponding probability density function and cumulative density function are given by Yadav et al. [18].

$$g(y; \alpha, \beta) = \frac{\alpha}{\beta} \left(1 + \frac{y}{\beta}\right)^{-(\alpha+1)} \quad y \geq 0, \quad \alpha, \beta > 0 \quad (2)$$

$$G(y; \alpha, \beta) = 1 - \left(1 + \frac{y}{\beta}\right)^{-\alpha} \quad y \geq 0, \quad \alpha, \beta > 0 \quad (3)$$

Consider the random variable $Z = \frac{1}{Y}$. Then $Z$ has the inverse Lomax distribution with pdf and cdf as

$$h(z; \alpha, \beta) = \frac{\beta}{\alpha z^\alpha} \left(1 + \frac{\beta}{z}\right)^{-1/(1+\alpha)} \quad z \geq 0, \alpha, \beta > 0 \quad (4)$$

$$H(z; \alpha, \beta) = \left(1 + \frac{\beta}{z}\right)^{-1/\alpha} \quad z \geq 0, \alpha, \beta > 0 \quad (5)$$
respectively. Note that \( h(y; \alpha, \beta) = \frac{1}{z} f \left( \frac{1}{z} \right) \) and \( H(y; \alpha, \beta) = 1 - F \left( \frac{1}{z} \right) \).

We consider another variable with \( X = \frac{Z}{\beta} \)

\[
f(x; \alpha) = \frac{1}{\alpha x^2} \left( 1 + \frac{1}{x} \right)^{-(1+1/\alpha)} x \geq 0, \alpha > 0
\] (6)

\[
F(x; \alpha) = \left( 1 + \frac{1}{x} \right)^{1-\alpha} x \geq 0, \alpha > 0
\] (7)

The computation or estimation of OVL for two inverse Lomax distributions, with density functions:

\[
f_1(x; \alpha_1) = \frac{1}{\alpha_1 x^2} \left( 1 + \frac{1}{x} \right)^{-(1+1/\alpha_1)} x \geq 0, \alpha_1 > 0
\] (8)

\[
f_2(x; \alpha_2) = \frac{1}{\alpha_2 x^2} \left( 1 + \frac{1}{x} \right)^{-(1+1/\alpha_2)} x \geq 0, \alpha_2 > 0
\] (9)

Let \( R = \frac{\alpha_1}{\alpha_2} \), the continuous version of the three overlap measures can be expressed as a function of \( C \) as follows:

\[
\rho = \frac{2\sqrt{R}}{R + 1},
\] (10)

\[
\Delta = 1 - R \frac{1}{1-R} \left| 1 - \frac{1}{R} \right|, \quad R \neq 1,
\] (11)

and

\[
\Lambda = \frac{R}{R^2 - R + 1}.
\] (12)

Figure 2 shows curves of the three overlap measures according to \( R \). All three measures are monotone for all \( R > 0 \).

**Proposition 2.1.** For OVLs defined earlier,

i. \( 0 \leq OVL \leq 1 \) for all \( R \geq 0 \)

ii. \( OVL = 1 \) iff \( R = 1 \)

iii. \( OVL = 0 \) iff \( R = 0 \) or \( R = \infty \).

**Proposition 2.2.** All four OVLs possess properties of reciprocity, invariance and piecewise monotonicity

i. \( OVL(R) = OVL(1/R) \),

ii. \( OVLs \) are monotonically increasing in \( R \) for \( 0 \leq R \leq 1 \) and decreasing in \( R > 1 \).

![Figure 2](image-url) | Measures of similarity as functions of R.
3. STATISTICAL INFERENCE USING SRS

3.1. Estimation

As in Helu and Samawi [16], parallel results to those of the two Lomax populations can be established for the inverse Lomax populations. Suppose \( X_{ij}; j = 1, \ldots, n; i = 1, 2 \) denote independent observations from two independent inverse Lomex populations. Let \( f_i(x)(i = 1, 2) \) denote the inverse Lomex densities with shape parameters \( \alpha_i \) and \( \alpha_2 \) respectively. Define \( R = \alpha_1/\alpha_2 \). The likelihood function the Inverse Lomax distribution (6) is given as

\[
L(\alpha_i|x) = \frac{1}{\alpha_i^n} \prod_{j=1}^{n} \frac{1}{x_i^j} \prod_{j=1}^{n} \ln \left( 1 + \frac{1}{x_i^j} \right) \quad i = 1, 2; j = 1, \ldots, n. \tag{13}
\]

The maximum likelihood estimators (MLEs) based on the two samples are given by

1. From the first sample:
   \[
   \hat{\alpha}_{1SRS} = \frac{1}{n_1} \sum_{j=1}^{n_1} \log \left( 1 + \frac{1}{x_{ij}} \right)
   \]

2. From the second sample:
   \[
   \hat{\alpha}_{2SRS} = \frac{1}{n_2} \sum_{j=1}^{n_2} \log \left( 1 + \frac{1}{x_{2j}} \right)
   \]

The maximum likelihood estimators \( \hat{\alpha}_{SRS1} \) and \( \hat{\alpha}_{SRS2} \) exist and are unique. Using a simple transformation, it can be shown that

\[
\hat{\alpha}_{SRS1} \sim Gamma \left( n_1, \frac{\alpha_1}{n_1} \right) \quad \text{and} \quad \hat{\alpha}_{SRS2} \sim Gamma \left( n_2, \frac{\alpha_2}{n_2} \right)
\]

Consequently, the means and variances of those MLE’s are respectively

\[
E(\hat{\alpha}_{SRS1}) = \alpha_1, \quad E(\hat{\alpha}_{2}) = \alpha_2,
\]

and

\[
V(\hat{\alpha}_{SRS1}) = \frac{\alpha_1^2}{n_1}, \quad V(\hat{\alpha}_{SRS2}) = \frac{\alpha_2^2}{n_2}.
\]

Then we may define an estimate of \( R \) is

\[
\hat{R} = \frac{\hat{\alpha}_{SRS1}}{\hat{\alpha}_{SRS2}}.
\]

Therefore, using the relationship between gamma distribution and chi-square distribution and the fact that the two samples are independent, it is easy to show that \( \frac{\hat{\alpha}_{1}}{\hat{\alpha}_{2}} \) has \( F \)-distribution with \( 2n_1 \) and \( 2n_2 \) degrees of freedom \((F_{2n_1, 2n_2})\). Hence, the variance of \( \hat{R} \) is

\[
\text{Var}(\hat{R}_{SRS}) = \frac{n_1^2(n_1 + n_2 - 1)}{n_1(n_1 - 1)^2(n_2 - 2)} R^2.
\]

Also, an unbiased estimate \( R \) is given by \( \hat{R}^*_{SRS} = \frac{n_1 - 1}{n_2} \hat{R}_{SRS} \) with

\[
\text{Var}(\hat{R}^*_{SRS}) = R^2 \frac{n_1(n_1 - 1)^2(n_2 - 2)}{n_1(n_2 - 2)}.
\]

Clearly, \( \hat{R}^*_{SRS} \) has less variance than \( \hat{R}_{SRS} \).

Since the OVL measures are functions of \( R \), therefore, based on MLE estimate of \( R \), the OVL measures can be estimated by

\[
\hat{\rho}_{SRS} = 2\sqrt{\hat{R}^*_{SRS}} / \hat{R}^*_{SRS} + 1, \quad (14)
\]
\[ \Delta = 1 - (\hat{R}^*)^2 | 1 - \frac{1}{R^*}|, \quad R \neq 1, \quad \text{(15)} \]

and

\[ \hat{\Lambda}_{SRS} = \frac{\hat{R}^*_{SRS}}{(\hat{R}^*_{SRS})^2 - \hat{R}^*_{SRS} + 1}. \quad \text{(16)} \]

### 3.2. Asymptotic Properties

Let OVL = \( g(R) \), and its estimator \( \hat{OVL}_{SRS} = g(\hat{R}^*_{SRS}) \). Using the well-known delta method (expansion of the Taylor series) the asymptotic sampling variance of the OVL measures is given by the following theorem.

**Theorem 3.1.** Let \( \hat{\rho}_{SRS}, \hat{\Delta}_{SRS} \) and \( \hat{\Lambda}_{SRS} \) are the estimates of \( \rho, \Delta \) and \( \Lambda \) respectively, then for \( n \geq 3 \), we have the approximate expressions for variances of the OVL measures can be obtained as follows:

\[
\begin{align*}
\text{Var}(\hat{\rho}_{SRS}) &= \frac{(n_1 + n_2 - 1) R(1 - R)^2}{n_1(n_2 - 2)(R + 1)^2}, \\
\text{Var}(\hat{\Delta}_{SRS}) &= \frac{(n_1 + n_2 - 1) R^2 (\ln R)^2}{n_1(n_2 - 2)(1 - R)^2}, \\
\text{Var}(\hat{\Lambda}_{SRS}) &= \frac{(n_1 + n_2 - 1) R^4 (1 - R)^2}{n_1(n_2 - 2)(R^2 - R + 1)^2}. 
\end{align*}
\]

**Proof.** Let function \( g(R) \) has one parameter of \( R \) and let \( \hat{R}^*_{SRS} \) be an almost sure consistent estimate of \( R \).

Then the variance of \( g(\hat{R}^*_{SRS}) \) may be obtained from the linear Taylor approximation around \( R \):

\[ g(\hat{R}^*_{SRS}) = g(R) + (\hat{R}^*_{SRS} - R) g'(R) \]

for the estimator \( \hat{R}^*_{SRS} \):

\[ g'(R) = \frac{1 - \hat{R}}{\sqrt{R(1 + \hat{R})}^2} \]

\[ \text{Var}(\hat{\rho}_{SRS}) = \text{Var}(g(\hat{R}^*_{SRS})) = \text{Var}(g(R)) + \text{Var}(\hat{R}^*_{SRS} - R) g'(R) \]

\[ = (g'(R))^2 \text{Var}(\hat{R}^*_{SRS}) = \frac{(1 - R)^2 R(1 + R)^2}{R(1 + R)^2} \frac{n_1 + n_2 - 1}{n_1(n_2 - 1)} \]

\[ = \frac{(n_1 + n_2 - 1) R(1 - R)^2}{n_1(n_2 - 2)(1 + R)^2} \]

Similar arguments can be used for the other overlaps coefficients. \( \square \)

**Theorem 3.2.** Using Taylor series expansion, then for \( n \geq 3 \). Approximations for the biases of the OVL coefficients estimates are as follows:

\[ \text{Bias}(\hat{\rho}_{SRS}) = \frac{(n_1 + n_2 - 1) \sqrt{R(3R^2 - 6R - 1)}}{2n_1(n_2 - 2)(1 + R)^3} \]

\[ \text{Bias}(\hat{\Delta}_{SRS}) = \begin{cases} 
- \frac{(n_1 + n_2 - 1) R^2}{2n_1(n_2 - 2)} \left[ \frac{2R - 1}{R - R} R(2R - \ln R - 2)\ln R - (R - 1)^2 \right] & \text{if } 0 < R < 1 \\
\frac{(n_1 + n_2 - 1) R^2}{2n_1(n_2 - 2)} \left[ \frac{2R - 1}{R - R} R(2R - \ln R - 2)\ln R - (R - 1)^2 \right] & \text{if } R \geq 1 
\end{cases} \]
From the first sample:

\[
Bias(\hat{\Lambda}_{SRS}) = \frac{(n_1 + n_2 - 1) R^2 - 3 R^3 - R^2}{n_1(n_2 - 2)} (R^2 - R + 1)^2
\]

**Proof.** Again by using the well-known Delta method (Taylor series expansion) the asymptotic bias of the OVL measures can be obtained as follows:

\[
g(\hat{R}_{SRS}^*) = g(R) + (\hat{R}_{SRS}^* - R)g'(R) + \frac{1}{2} (\hat{R}_{SRS}^* - R)^2 g''(R)
\]

for the estimator \(\hat{\rho}_{SRS}\):

\[
g(\hat{R}_{SRS}^*) = 2\sqrt{\hat{R}_{SRS}^* (\hat{R}_{SRS}^* + 1)}
\]

Since, in this case,

\[
g'(\hat{R}_{SRS}^*) = \frac{1 - \hat{R}_{SRS}^*}{\sqrt{\hat{R}_{SRS}^* (\hat{R}_{SRS}^* + 1)^2}} \quad \text{so} \quad g''(\hat{R}_{SRS}^*) = \frac{\sqrt{R (3R^2 - 6R - 1)}}{R^{3/2} (1 + R)^2}
\]

\[
E(\hat{\rho}_{SRS}) = E(g(\hat{R}_{SRS}^*)) = g(R) + E[(\hat{R}_{SRS}^* - R)] g'(R) + \frac{1}{2} E[(\hat{R}_{SRS}^* - R)^2] g''(R)
\]

\[
Bias(\hat{\rho}_{SRS}) = \frac{1}{2} \text{Var}(\hat{R}_{SRS}^*) g''(R) = \frac{(n_1 + n_2 - 1) \sqrt{R (3R^2 - 6R - 1)}}{2n_1(n_2 - 2)} (1 + R)^3
\]

the bias Similar arguments can be used for the bias the other overlaps coefficients.

\]

### 3.3. Interval Estimation

For large sample, normal approximation to the sampling distribution, using the delta method, works fairly well. Therefore, the asymptotic 100(1 − \(\alpha_0\))% confidence intervals for the OVL coefficients can be computed easily as

\[
\left\{ \hat{OVL}_{SRS} \pm Z_{1-\alpha_0/2} \sqrt{\text{Var}(\hat{OVL}_{SRS})} \right\}
\]

where \(Z_{1-\alpha_0/2}\) is the \(\alpha_0/2\) upper quantile of the standard normal distribution.

These confidence intervals are not the best because of the bias involved in OVL coefficients estimates, however, for large samples they work fairly well. Using these approximations, the bias corrected interval can be computed as

\[
\left\{ \hat{OVL}_{SRS} - \text{Bias}(\hat{OVL}_{SRS}) \pm Z_{1-\alpha_0/2} \sqrt{\text{Var}(\hat{OVL}_{SRS})} \right\}
\]

### 4. STATISTICAL INFERENCE USING RSS

#### 4.1. Estimation

Similar to the previous section, suppose \(X_{i(1:k)}X_{i(2:k)} \ldots X_{i(1:k)}\) and \(X_{i(1:k)}X_{i(2:k)} \ldots X_{i(1:k)}\), \(k = 1, 2, \ldots, m\) are two independent RSS samples drawn from \(f_1(x)\) and \(f_2(x)\) respectively. The estimates of \(\hat{\theta}_1\) and \(\hat{\theta}_2\) using RSS sample are given by:

1. From the first sample:

\[
\hat{\alpha}_{1RSS} = \frac{1}{n_1} \sum_{i=1}^{n_1} \sum_{k=1}^{n_i} \log \left( 1 + \frac{1}{x_{1i(k)}^2} \right), \quad n_1 = r_1 m.
\]

2. From the second sample:

\[
\hat{\alpha}_{2RSS} = \frac{1}{n_2} \sum_{i=1}^{n_2} \sum_{k=1}^{n_i} \log \left( 1 + \frac{1}{x_{2i(k)}^2} \right), \quad n_2 = r_2 m.
\]
Note that, it is easy to show that

\[ E(\hat{\alpha}_{1\text{RSS}}) = \alpha_1, \quad E(\hat{\alpha}_{2\text{RSS}}) = \alpha_2, \]

\[ \text{Var}(\hat{\alpha}_{1\text{RSS}}) = \frac{\alpha_{1\text{RSS}}^2}{n} \sum_{i=1}^{n} \frac{1}{r_i - 1}, \quad \text{Var}(\hat{\alpha}_{2\text{RSS}}) = \frac{\alpha_{2\text{RSS}}^2}{n} \sum_{i=1}^{n} \frac{1}{r_i - 1} + 1 \]

Also, \( R \) can be estimated by \( \hat{R}_{\text{RSS}} = \frac{\hat{\rho}_{\text{RSS}}}{\hat{\rho}_{\text{SRS}}} \). Hence, by using Delta method of approximation, the variance of \( \hat{R}_{\text{RSS}} \) can be approximated by

\[ \text{Var}(\hat{R}_{\text{RSS}}) \cong R^2 \left[ \frac{\sum_{i=1}^{n} \frac{1}{r_i - 1}}{n} + \frac{\sum_{i=1}^{n} \frac{1}{r_i - 1}}{n^2} \right]. \]

Thus, we have

\[ \hat{\rho}_{\text{RSS}} = \frac{2\sqrt{\hat{R}_{\text{RSS}}}}{\hat{R}_{\text{RSS}}^n + 1} \tag{17} \]

\[ \hat{\Lambda}_{\text{RSS}} = \begin{cases} 1 - (\hat{R}_{\text{RSS}}) \frac{R^2}{R - 1} + (\hat{R}_{\text{RSS}}) \frac{\rho_{\text{SRS}}}{R - 1} & \text{if } 0 < R < 1 \\ 1 + (\hat{R}_{\text{RSS}}) \frac{R^2}{R - 1} - (\hat{R}_{\text{RSS}}) \frac{\rho_{\text{SRS}}}{R - 1} & \text{if } R \geq 1 \end{cases} \tag{18} \]

\[ \hat{\Lambda}_{\text{RSS}} = \frac{\hat{R}_{\text{RSS}}}{(\hat{R}_{\text{RSS}})^2 - \hat{R}_{\text{RSS}} + 1} \tag{19} \]

### 4.2. Asymptotic Properties

Let \( OVL = g(R) \), and its estimator \( \hat{OVL}_{\text{RSS}} = g(\hat{R}_{\text{RSS}}) \). Using the well-known delta method (expansion of the Taylor series) the asymptotic sampling variance of the OVL measures is given by the following theorem.

**Corollary 4.1.** Let \( \hat{\rho}_{\text{RSS}}, \hat{\Lambda}_{\text{RSS}} \) and \( \hat{\Lambda}_{\text{RSS}} \) are the estimates of \( \rho, \Lambda \) and \( \Lambda \) respectively, then for \( n_2 \geq 3 \), we have the approximate expressions for variances of the OVL measures can be obtained as follows:

\[ \text{Var}(\hat{\rho}_{\text{RSS}}) = \left[ \frac{\sum_{i=1}^{n_2} \frac{1}{r_i - 1}}{n_2^2} + \frac{1}{n_2} \right] R(1 - R)^2 \left( \frac{1}{R + 1} \right)^2 \]

\[ \text{Var}(\hat{\Lambda}_{\text{RSS}}) = \left[ \frac{\sum_{i=1}^{n_2} \frac{1}{r_i - 1}}{n_2^2} + \frac{1}{n_2} \right] R(1 - R)^2 \left( \frac{1}{R + 1} \right)^2 \]

\[ \text{Var}(\hat{\Lambda}_{\text{RSS}}) = \left[ \frac{\sum_{i=1}^{n_2} \frac{1}{r_i - 1}}{n_2^2} + \frac{1}{n_2} \right] R(1 - R)^2 \left( \frac{1}{R^2 - R + 1} \right)^2 \]

**Proof.** Same proof of Theorem 3.1, replacing \( \hat{R}_{\text{RSS}} \) with the \( \hat{R}_{\text{SRS}} \) estimator.

**Corollary 4.2.** Using Taylor series expansion, then for \( n_2 \geq 3 \). Approximations for the biases of the OVL coefficients estimates, are as follows:

\[ \text{Bias}(\hat{\rho}_{\text{RSS}}) = \left[ \frac{\sum_{i=1}^{n_2} \frac{1}{r_i - 1}}{n_2^2} + \frac{1}{n_2} \right] \sqrt{R(3R^2 - 6R - 1)} \frac{1}{2(1 + R)^4} \]
These confidence intervals are not the best because of the bias involved in attention for statistical inference. In our study normal approximations for the shape parameter

In recent decades, the Bayes viewpoint, as a powerful and valid alternative to traditional statistical perspectives, has received frequent attention for statistical inference. In our study normal approximations for the shape parameter $\alpha$ of Inverse Lomax distribution will be obtained using Jeffery’s prior. Noted that the choice of this type of distribution, thus often leads to classical estimators of the maximum likelihood approach.

### 5.1. Estimation

**Jeffery’s Prior:** Using Jeffery’s prior for the scale parameter $\alpha$

$$P(\alpha) = \alpha^{-1} \quad 0 < \alpha < \infty$$

Using (20) and (13) we get the posterior distribution for $\alpha$ is as

$$P(\alpha|x) \propto P(\alpha)L(\alpha|x) = \frac{1}{\alpha n+1} \exp \left( -\frac{n}{\alpha} + \frac{1}{x} \right)$$

The log posterior is $\log(P(\alpha|x)) = -(n+1) \log(\alpha) - \frac{1}{\alpha} \sum_{i=1}^{n} \log \left( 1 + \frac{1}{x_i} \right)$

The first derivative is

$$\frac{\partial P(\alpha|x)}{\partial \alpha} = -\frac{n+1}{\alpha} + \frac{1}{\alpha^2} \sum_{i=1}^{n} \log \left( 1 + \frac{1}{x_i} \right)$$

and the posterior mode is obtained as

1. From the first sample:

$$\hat{\alpha}_{ij} = \frac{1}{n_1 + 1} \sum_{i=1}^{n_1} \log \left( 1 + \frac{1}{x_{ij}} \right)$$
2. From the second sample:

\[ \hat{\alpha}_{2j} = \frac{1}{n_2 + 1} \sum_{i=1}^{n_2} \log \left( 1 + \frac{1}{x_{2i}} \right) \]

Using simple transformation, it can be shown that

\[ \hat{\alpha}_{2j} \sim \text{Gamma} \left( n_1, \frac{\alpha_1}{n_1 + 1} \right) \quad \text{and} \quad \hat{\alpha}_{2j} \sim \text{Gamma} \left( n_2, \frac{\alpha_2}{n_2 + 1} \right) \]

A consequent estimate of \( R \) is \( \hat{R}_i = \frac{\alpha_i}{\alpha'_{ij}} \). Hence, an approximation variance of \( \hat{R}_i \) can be given by

\[ \text{Var} (\hat{R}_i) = \left( \frac{n_2 + 1}{n_1 + 1} \right)^2 \frac{n_2(n_1 + n_2 - 1)}{n_1(n_2 - 1)^2(n_2 - 2)} R^2 \]

Also, an unbiased estimate \( R \) is given by \( \hat{R}^*_i = \frac{n_1(n_1 - 1)(n_1 + 1)}{n_2(n_2 + 1)} \hat{R}_{ij} \) with

\[ \text{Var} (\hat{R}^*_i) = \left( \frac{n_2 - 1}{n_1 - 1} \right)^2 \frac{n_2 + n_2 - 1}{n_1(n_2 - 2)} R^2 \]

Thus, we have

\[ \hat{\rho}_i = \frac{2\sqrt{\hat{R}^*_i}}{\hat{R}^*_i + 1} \quad (22) \]

\[ \hat{\Delta}_j = \left\{ \begin{array}{ll}
1 - (\hat{R}^*_j)^{\frac{1}{n_2 - 1}} + (\hat{R}^*_j)^{\frac{1}{n_2 - 1}} & \text{if} \quad 0 < R < 1 \\
1 + (\hat{R}^*_j)^{\frac{1}{n_2 - 1}} - (\hat{R}^*_j)^{\frac{1}{n_2 - 1}} & \text{if} \quad R \geq 1
\end{array} \right. \quad (23) \]

\[ \hat{\Lambda}_j = \frac{\hat{R}^*_j}{(\hat{R}^*_j)^2 - \hat{R}^*_j + 1} \quad (24) \]

The asymptotic variance of the OVL measures are given by

\[ \text{Var}(\hat{\rho}_i) = \left( \frac{n_2 - 1}{n_2 - 1} \right)^2 \frac{n_2 + n_2 - 1}{n_1(n_2 - 2)} \frac{R(1 - R)^2}{(1 + R)^4} \]

\[ \text{Var}(\hat{\Delta}_j) = \left( \frac{n_2 - 1}{n_2 - 1} \right)^2 \frac{n_2 + n_2 - 1}{n_1(n_2 - 2)} \frac{R^2(\ln R)^2}{(1 - R)^2} \]

\[ \text{Var}(\hat{\Lambda}_j) = \left( \frac{n_2 - 1}{n_2 - 1} \right)^2 \frac{n_2 + n_2 - 1}{n_1(n_2 - 2)} \frac{R^2(1 - R)^2}{(R^2 - R + 1)^4} \]

With the asymptotic bias given by

\[ \text{Bias}(\hat{\rho}_i) = \left( \frac{n_2 + 2}{n_1 + 1} \right)^2 \frac{n_1(n_1 + n_2 - 1)}{2(n_2 - 1)^2(n_2 - 2)} \frac{\sqrt{R}(3R^2 - 6R - 1)}{(1 + R)^3} \]
\[ \text{Bias}(\Delta_j) = \begin{cases} 
- \left( \frac{n_2 + 2}{n_1 + 1} \right)^2 \frac{n_1(n_1 + n_2 - 1)}{(n_2 - 1)^2(n_2 - 2)} R^2 \frac{\binom{2R-1}{R} R(2R - \ln R - 2)\ln R - (R - 1)^2}{(R - 1)^3} & \text{if } 0 < R < 1 \\
\left( \frac{n_2 + 2}{n_1 + 1} \right)^2 \frac{n_1(n_1 + n_2 - 1)}{(n_2 - 1)^2(n_2 - 2)} R^2 \frac{\binom{2R-1}{R} R(2R - \ln R - 2)\ln R - (R - 1)^2}{(R - 1)^3} & \text{if } R \geq 1 
\end{cases} \]

5.2. Interval Estimation

The \((1 - 2\alpha_0)\) confidence intervals for the overlap measures are computed as

\[
\left\{ \hat{OVL} \pm Z_{1-\alpha_0/2} \sqrt{\text{Var}(\hat{OVL})} \right\}
\]

Using these estimates the bias corrected interval, the \(100(1 - \alpha_0)\%\) confidence intervals for the OVL measures can be given by

\[
\left\{ \left[ \hat{OVL} - \text{Bias}(\hat{OVL}) \right] \pm Z_{1-\alpha_0/2} \sqrt{\text{Var}(\hat{OVL})} \right\}
\]

6. SIMULATION

In our simulation study we include the following: \(R = 0.1, 0.5, 0.75, 0.8,\) and \(r_1 = 2, 3, 4, 5; r_2 = 2, 3, 4, 5; m = 8, 40\) and \(\alpha_0 = 0.05\). A simulation study is conducted to get insight about the performance of the proposed estimators. All the 1000 simulated sets of observations were generated under the assumption that both densities have standard inverse Lomax distribution with the different shape parameter.

The performance of the OVL measure using RSS and SRS can be assessed using the asymptotic relative efficiency which is computed as

\[
\text{Eff}(\hat{OVL}_{\text{RSS}}, \hat{OVL}_{\text{SRS}}) = \frac{\text{MSE}(\hat{OVL}_{\text{SRS}})}{\text{MSE}(\hat{OVL}_{\text{RSS}})}
\]

Where \(\text{MSE}(\hat{OVL}) = \text{Var}(\hat{OVL}) + \text{Bias}(\hat{OVL})^2\)

Tables 1 and 2 show the asymptotic relative efficiencies for the OVL measures using RSS relative to using SRS.

Tables 1 and 2 shows that, using SRS for estimating all three overlap measure is more efficient that using SRS. The efficiency increases as the set size \(r_1\) and \(r_2\) increases. Increasing the number of cycles’s \(m\) slightly decreases the efficiency. This may due the fact that this relative efficiency is based on a large sample approximation. Therefore, the larger is the sample size the closer is the relative efficiency to the exact one.

Tables 3 and 4 indicate that the bias of the proposed OVL estimators is negligible in most cases and \(|\text{bias}|\) decreases as the sample sizes are increased for both SRS, RSS and Bayes. However, the asymptotic bias when using SRS is smaller than when using RSS or Bayes.

The bias estimates for \(n = 25\) are plotted in Figure 3. Only one plot of bias values is presented because a similar pattern is observed for other sample sizes. For \(R < 0.5\) the bias estimates of the SRS, bayesian and behave more similarly, but for the bias of RSS shows a different pattern. For \(R > 0.5\), the bias estimate of the RSS is growing, that of of Bayes are decreasing and but for that SRS tends towards 0. The estimates of MSE are plotted in Figure 4 for all three methods. For \(R < 0, 6\), the MSE estimates for the SRS and RSS have almost the same values and for BB has a peak at \(R = 0.6\) and declining steadily thereafter as \(R\) increases.

7. REAL DATA APPLICATION

As applications, considers the dataset discussed by Proschan [19]. The data of 30 and 12 successive failure time intervals (in hours) of the air-conditioning system of jet plane, Plane 8044 and Plane-7912, for fitting to Lomax distribution (Gupta et al. [20]). The inverse Lomax random variable \(X\) can be obtained by using the transformation \(x = 1/y\) on Lomax random variable \(Y\) (Saleem and Aslam [21]).

Plane 8044: \(X_1(n = 12) : 487, 18, 100, 7, 98, 5, 85, 91, 43, 230, 3, 130.\)
8. CONCLUSION

In this paper we considered three measures of overlap, namely Matusia’s measure $\rho$, Weitzman’s measure $\Delta$ and Kullback-Leibler $\Lambda$. We studied the estimation of overlap measures and bias and variance of their estimates. The values of the OVL measures are very similar, the coefficient $\rho$ is of the best for having small values of Bias and MSE. The overall conclusion is that the biases of each of the OVL measures are close to zero and approximations are adequate for samples of size as small as 40. The SRS and RSS procedures provided sensible and reasonably reliable confidence intervals. These are also the simplest methods to use in practice that do not need any computers, special software or extensive computations.
|        | SRS       | RSS       | BAYES      |
|--------|-----------|-----------|------------|
|        | $\rho$    | $\Delta$  | $\Lambda$  | $\rho$    | $\Delta$  | $\Lambda$  | $\rho$    | $\Delta$  | $\Lambda$  |
|        | ratio L   | ratio L   | ratio L    | ratio L   | ratio L   | ratio L    | ratio L   | ratio L   | ratio L    |
| $(r_1, r_2)$ |           |           |           |           |           |           |           |           |           |
| $(2,2)$ | 0.026     | 0.283     | 0.288     | 0.002     | 0.215     | 0.024     | 0.146     | 0.035     | 0.437     | 0.237     | 0.002     | 0.120     | 0.163     | 0.881     | 0.288     | 0.324     | 0.999     | 0.024     | 0.002     | 0.018     | 0.393     |
| $(2,3)$ | 0.021     | 0.250     | 0.261     | 0.013     | 0.193     | 0.022     | 0.131     | 0.027     | 0.392     | 0.208     | 0.002     | 0.303     | 0.017     | 0.001     | 0.035     | 0.106     | 0.055     | 0.736     | 0.168     | 0.110     | 0.999     | 0.014     | 0.0007    | 0.009     | 0.256     |
| $(3,3)$ | 0.017     | 0.230     | 0.231     | 0.001     | 0.173     | 0.019     | 0.131     | 0.019     | 0.337     | 0.175     | 0.001     | 0.258     | 0.015     | 0.001     | 0.029     | 0.089     | 0.105     | 0.831     | 0.231     | 0.208     | 0.999     | 0.019     | 0.001     | 0.012     | 0.393     |
| $(3,4)$ | 0.014     | 0.214     | 0.214     | 0.001     | 0.161     | 0.018     | 0.109     | 0.017     | 0.317     | 0.163     | 0.001     | 0.242     | 0.014     | 0.001     | 0.028     | 0.083     | 0.060     | 0.717     | 0.159     | 0.098     | 0.999     | 0.103     | 0.0006    | 0.007     | 0.292     |
| $(4,4)$ | 0.012     | 0.199     | 0.198     | 0.0008    | 0.150     | 0.0170    | 0.010     | 0.014     | 0.296     | 0.151     | 0.0009    | 0.225     | 0.013     | 0.0006    | 0.026     | 0.077     | 0.077     | 0.789     | 0.198     | 0.153     | 0.999     | 0.0167    | 0.001     | 0.009     | 0.393     |
| $(5,5)$ | 0.010     | 0.178     | 0.176     | 0.0006    | 0.133     | 0.015     | 0.090     | 0.011     | 0.267     | 0.135     | 0.0007    | 0.202     | 0.011     | 0.0005    | 0.023     | 0.069     | 0.061     | 0.752     | 0.176     | 0.122     | 0.999     | 0.015     | 0.015     | 0.068     | 0.393     |
|        | $R = .1$  |           |           |           |           |           |           |           |           |           |           |           |           |           |           |           |           |           |           |           |           |           |           |           |           |           |
|        | $R = .5$  |           |           |           |           |           |           |           |           |           |           |           |           |           |           |           |           |           |           |           |           |           |           |           |           |           |
|        | $R = .75$ |           |           |           |           |           |           |           |           |           |           |           |           |           |           |           |           |           |           |           |           |           |           |           |           |           |
|        | $R = .9$  |           |           |           |           |           |           |           |           |           |           |           |           |           |           |           |           |           |           |           |           |           |           |           |           |           |           |

Table 3: Bias, ratio, and length of interval (L.), using RSS, SRS and Baye, $m = 8$. 
Table 4: Bias, ratio, and length of interval (L.), using RSS, SRS and Bayes, m = 40.

| (r_1, r_2) | \( \rho \) | Bias \( \Delta \) ratio | L | Bias \( \Delta \) ratio | L | Bias \( \Delta \) ratio | L | Bias \( \Delta \) ratio | L |
|------------|------------|----------------|-----|----------------|-----|----------------|-----|----------------|-----|
| (2,2)      | 0.005      | 0.125          | 0.123 | 0.00303         | 0.094 | 0.0104         | 0.0002 | 0.0105         | 0.0628 | 0.0057         | 0.1923 | 0.0956         | 0.0003 | 0.1445         | 0.0080 | 0.0002         | 0.0162 | 0.0486 | 0.0300         | 0.1235 | 0.1235 | 0.0596         | 0.9985 | 0.0104         | 0.0004 | 0.0003 | 0.393         |
| (2,3)      | 0.004      | 0.114          | 0.112 | 0.0002          | 0.085 | 0.009          | 0.0002 | 0.009          | 0.0571 | 0.0047         | 0.1761 | 0.0873         | 0.0003 | 0.1321         | 0.0073 | 0.0002 | 0.0148         | 0.0444 | 0.0109 | 0.4352         | 0.0746 | 0.0217 | 0.9962         | 0.0063 | 0.0001 | 0.0002 | 0.261         |
| (3,3)      | 0.003      | 0.102          | 0.1005 | 0.0002          | 0.0765 | 0.008          | 0.0001 | 0.0085         | 0.051  | 0.0038         | 0.1580 | 0.0781         | 0.0002 | 0.1183         | 0.0065 | 0.0002 | 0.0132         | 0.0397 | 0.0199 | 0.5459         | 0.1005 | 0.0395 | 0.9979         | 0.0084 | 0.0003 | 0.0002 | 0.393         |
| (3,4)      | 0.003      | 0.0957         | 0.09391 | 0.0017          | 0.0714 | 0.0079         | 0.0001 | 0.0079         | 0.0477 | 0.0033         | 0.1481 | 0.0730         | 0.0002 | 0.1108         | 0.0061 | 0.0001 | 0.0124         | 0.0371 | 0.0097 | 0.4143         | 0.0702 | 0.01929 | 0.9957         | 0.0059 | 0.0002 | 0.0001 | 0.294         |
| (4,4)      | 0.002      | 0.0887         | 0.08691 | 0.0001          | 0.0662 | 0.007          | 0.0000 | 0.0073         | 0.0442 | 0.0028         | 0.1373 | 0.0676         | 0.0002 | 0.1027         | 0.0057 | 0.0001 | 0.0114         | 0.0344 | 0.0149 | 0.4908         | 0.0073 | 0.0295 | 0.9971         | 0.0073 | 0.0002 | 0.0001 | 0.393         |
| (5,5)      | 0.002      | 0.0793         | 0.07771 | 0.0001          | 0.0592 | 0.0065         | 0.0000 | 0.0066         | 0.0395 | 0.0023         | 0.1230 | 0.0605         | 0.0001 | 0.0920         | 0.0059 | 0.0000 | 0.0102         | 0.0307 | 0.0119 | 0.4496         | 0.0777 | 0.0236 | 0.9965         | 0.0065 | 0.0001 | 0.0001 | 0.393         |

*Note:* The table continues with similar entries for different intervals and parameters.
Figure 3 | The bias estimates of overlap coefficients by $R$.

Figure 4 | The Mean Squared Error (MSE) estimates for overlap coefficients by $R$.

Table 5 | Results based on the real data.

|       | \( \hat{\rho} = 0.995 \) |       | \( \hat{\Delta} = 0.906 \) |       | \( \hat{\Gamma} = 0.938 \) |
|-------|-----------------------------|-------|-----------------------------|-------|-----------------------------|
|       | SRS  | RSS  | Baye | SRS  | RSS  | Baye | SRS  | RSS  | Baye |
| \( Bias(\hat{OVL}) \) | 0.011 | 0.060 | 0.012 | 0.055 | 0.228 | 0.046 | 0.047 | 0.220 | 0.040 |
| \( Var(\hat{OVL}) \)  | 0.004 | 0.0003 | 0.0001 | 0.0015 | 0.007 | 0.001 | 0.022 | 0.018 | 0.030 |
| 95% confidence | (0.991, 1.0) | (0.915, 1.0) | (0.990, 1.0) | (0.803, 1.0) | (0.799, 1.0) | (0.798, 1.0) | (0.763, 1.0) | (0.94, 1.0) | (0.70, 1.0) |
CONFLICTS OF INTEREST

The authors declare that there are no conflicts of interest regarding the publication of this paper.

AUTHORS' CONTRIBUTIONS

All authors have read and agreed to the published version of the manuscript.

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