DISCONTINUOUS STOCHASTIC DIFFERENTIAL EQUATIONS DRIVEN BY LÉVY PROCESSES

XICHENG ZHANG

School of Mathematics and Statistics, Wuhan University, Wuhan, Hubei 430072, P.R.China,
Email: XichengZhang@gmail.com

ABSTRACT. In this article we prove the pathwise uniqueness for stochastic differential equations in \( \mathbb{R}^d \) with time-dependent Sobolev drifts, and driven by symmetric \( \alpha \)-stable processes provided that \( \alpha \in (1, 2) \) and its spectral measure is non-degenerate. In particular, the drift is allowed to have jump discontinuity when \( \alpha \in (\frac{2}{d+1}, 2) \). Our proof is based on some estimates of Krylov’s type for purely discontinuous semimartingales.

1. Introduction and Main Result

Consider the following SDE driven by a symmetric \( \alpha \)-stable process in \( \mathbb{R}^d \):

\[
dX_t = b_t(X_t)dt + dL_t, \quad X_0 = x,
\]

where \( b : \mathbb{R}_+ \times \mathbb{R}^d \rightarrow \mathbb{R}^d \) is a measurable function, \((L_t)_{t \geq 0}\) is a \( d \)-dimensional symmetric \( \alpha \)-stable process defined on some filtered probability space \((\Omega, \mathcal{F}, P; (\mathcal{F}_t)_{t \geq 0})\). The aim of this paper is to study the pathwise uniqueness of SDE (1.1) with discontinuous \( b \).

Let us first briefly recall some well known results in this direction. When \( L_t \) is a standard \( d \)-dimensional Brownian motion, Veretennikov [19] first proved the existence of a unique strong solution for SDE (1.1) with bounded measurable \( b \). In [11], Krylov and Röckner relaxed the boundedness assumptions on \( b \) to the following integrability assumptions:

\[
\int_0^T \left( \int_{\mathbb{R}^d} |b_t(x)|^p dx \right)^{\frac{q}{p}} dt < +\infty, \quad \forall T > 0,
\]

provided that

\[
\frac{d}{p} + \frac{2}{q} < 1.
\]

Recently, in [20] we extended Krylov and Röckner’s result to the case of non-constant Sobkoev diffusion coefficients and meanwhile, obtained the stochastic homeomorphism flow property of solutions and the strong Feller property.

In the case of symmetric \( \alpha \)-stable processes, the pathwise uniqueness for SDE (1.1) with irregular drift is far from being complete. When \( d = 1, \alpha \in [1, 2) \) and \( b \) is time-independent and bounded continuous, Tanaka, Tsuchiya and Watanabe [17] proved the pathwise uniqueness of solutions to SDE (1.1). When \( d > 1, \alpha \in [1, 2) \), the spectral measure of \( L_t \) is non-degenerate, and \( b \) is time-independent and bounded Hölder continuous, where the Hölder index \( \beta \) satisfies

\[
\beta > 1 - \frac{\alpha}{2},
\]

Priola [8] recently proved the pathwise uniqueness and the stochastic homeomorphism flow property of solutions to SDE (1.1). When \( d = 1, \alpha \in (1, 2) \) and \( b \) is only bounded measurable,

\[\text{Keywords: Pathwise uniqueness, symmetric } \alpha \text{-stable process, Krylov’s estimate, fractional Sobolev space.}\]
where Krylov’s type: for any Kurenok [12] obtained the existence of weak solutions for SDE (1.1) by proving an estimate of spectral measure when

\[ \beta \]

some knowledge, there are few results about the pathwise uniqueness for multidimensional SDE (1.1) with discontinuous drifts.

In particular, if \( \mu \) is a symmetric finite measure on the unit sphere \( \mathbb{S}^{d-1} : = \{ \theta \in \mathbb{R}^d : |\theta| = 1 \} \), called spectral measure of stable process \( L \). By an elementary calculation, we have

\[ \psi(\xi) = \int_{\mathbb{R}^d} (1 - e^{i\langle \xi, x \rangle} + i\langle \xi, x \rangle 1_{|x| \leq 1}) \nu(dx), \]

and the Lévy measure \( \nu \) with \( \nu(\{|0\}) = 0 \) is given by

\[ \nu(U) = \int_{\mathbb{S}^{d-1}} \int_0^{+\infty} \frac{1_{U}(r\theta)}{r^{d+\alpha}} d\mu(d\theta), \quad U \in \mathcal{B}(\mathbb{R}^d), \]

where \( \mu \) is a symmetric finite measure on the unit sphere \( \mathbb{S}^{d-1} \), called spectral measure of stable process \( L \). By an elementary calculation, we have

\[ \psi(\xi) = \int_{\mathbb{R}^d} (1 - \cos \langle \xi, x \rangle) \nu(dx) = c_\alpha \int_{\mathbb{S}^{d-1}} |\langle \xi, \theta \rangle|^\alpha \mu(d\theta). \]

In particular, if \( \mu \) is the uniform distribution on \( \mathbb{S}^{d-1} \), then \( \psi(\xi) = c_\alpha |\xi|^\alpha \), here \( c_\alpha \) may be different. Throughout this paper, we make the following assumption:

\textbf{(H\( ^{\alpha} \))} For some \( \alpha \in (0, 2) \) and constant \( C_\alpha > 0 \),

\[ \psi(\xi) \geq C_\alpha |\xi|^\alpha, \quad \forall \xi \in \mathbb{R}^d. \]

We remark that the above condition is equivalent that the support of spectral measure \( \mu \) is not contained in a proper linear subspace of \( \mathbb{R}^d \) (cf. [8] page 4).

We now introduce the class of local strong solutions for SDE (1.1). Let \( \tau \) be any \( (\mathcal{F}_t) \)-stopping time. For \( x \in \mathbb{R}^d \), let \( \mathcal{F}_b^\tau(x) \) be the class of all \( \mathbb{R}^d \)-valued \( (\mathcal{F}_t) \)-adapted càdlàg stochastic process \( X_t \) on \([0, \tau)\) satisfying

\[ P \left\{ \omega : \int_0^T |b_s(X_s(\omega))| ds < +\infty, \forall T \in [0, \tau(\omega)) \right\} = 1, \]

and such that

\[ X_t = x + \int_0^t b_s(X_s) ds + L_t, \quad \forall t \in [0, \tau), \quad a.s. \]

The main result of the present paper is:

\textbf{Theorem 1.1.} Assume that \textbf{(H\( ^{\alpha} \))} holds with \( \alpha \in (1, 2) \), and \( b : \mathbb{R}_+ \times \mathbb{R}^d \rightarrow \mathbb{R}^d \) satisfies that for some \( \beta \in (1 - \frac{\alpha}{2}, 1) \), \( p > \frac{2d}{\alpha} \) and any \( T, R > 0 \),

\[ \sup_{t \in [0, T]} \int_{B_R} \int_{B_R} |b_s(x) - b_s(y)|^p |x - y|^{d+\beta p} dxdy < +\infty \quad (1.7) \]
We aim to derive some smoothing and asymptotic properties about the Markovian semigroup associated with $L_0$. In particular, the interpolation techniques will be used frequently. This will be done in Section 2. In Section 3, partly following Kurenok’s idea, we shall prove two Krylov’s estimates for multidimensional purely discontinuous semimartingales. In Section 4, we prove our main result by using Zvonkin’s transformation of phase space to remove the drift.

In the remainder of this paper, the letter $C$ with or without subscripts will denote a positive constant whose value may change in different occasions.
2. Preliminaries

For \( p \geq 1 \), the norm in \( L^p \)-space \( L^p(\mathbb{R}^d) \) is denoted by \( \| \cdot \|_p \). For \( \beta \geq 0 \) and \( p \geq 1 \), let \( \mathbb{H}_p^\beta \) be the space of Bessel potential, i.e.,

\[
\mathbb{H}_p^\beta = (I - \Delta)^{-\beta}(L^p(\mathbb{R}^d)).
\]

In other words, \( \mathbb{H}_p^\beta \) is the domain of fractional operator \((I - \Delta)^\beta\), where \((I - \Delta)^\beta\) is defined through

\[
(I - \Delta)^\beta f = \mathcal{F}^{-1}((1 + |\cdot|^2)^\beta \mathcal{F} f), \quad f \in C_0^\infty(\mathbb{R}^d),
\]

where \( \mathcal{F} \) (resp. \( \mathcal{F}^{-1} \)) denotes the Fourier transform (resp. the Fourier inverse transform). Notice that for \( \beta = m \in \mathbb{N} \), an equivalent norm of \( \mathbb{H}_p^\beta \) is given by (cf. [18, p.177])

\[
\|f\|_{m,p} = \|f\| + \|\nabla^m f\|_p.
\]

By Sobolev’s embedding theorem, if \( \beta - \frac{d}{p} > 0 \) is not an integer, then (cf. [18, p.206, (16)])

\[
\mathbb{H}_p^\beta \hookrightarrow C^{\beta - \frac{d}{p}}(\mathbb{R}^d),
\]

where for \( \gamma > 0 \), \( C^\gamma(\mathbb{R}^d) \) is the usual Hölder space with the norm:

\[
\|f\|_{C^\gamma} := \sum_{k=0}^{[\gamma]} \sup_{x \in \mathbb{R}^d} |\nabla^k f(x)| + \sup_{x \neq y} \frac{|\nabla^k f(x) - \nabla^k f(y)|}{|x - y|^{\gamma - k}},
\]

where \([\gamma] := \max\{m \in \mathbb{N} : m \leq \gamma\}\) is the integer part of \( \gamma \).

Let \( A \) and \( B \) be two Banach spaces. For \( \theta \in [0,1] \), we use \([A,B]_\theta\) to denote the complex interpolation space between \( A \) and \( B \). We have the following relation (cf. [18, p.185, (11)]): for \( p > 1, \beta_1 \neq \beta_2 \) and \( \theta \in (0,1) \),

\[
[H_\beta p^1, H_\beta p^2]_\theta = H_\beta p^{\beta_1+\theta\beta_2-\beta_1}. \quad (2.2)
\]

On the other hand, for \( 0 < \beta \neq \text{integer} \), the fractional Sobolev space \( \mathbb{H}_p^\beta \) is defined by (cf. [18, p.190,(15)])

\[
\|f\|_{\beta,p} := \|f\|_p + \sum_{k=0}^{[\beta]} \left( \int_{\mathbb{R}^d} \int_{\mathbb{R}^d} \frac{|\nabla^k f(x) - \nabla^k f(y)|^p}{|x - y|^{d+\beta-|\beta|}p} \, dx \, dy \right)^{1/p} < +\infty. \quad (2.3)
\]

For \( \beta = 0, 1, 2, \cdots \), we set \( \mathbb{H}_p^\beta : = \mathbb{H}_p^\beta \). The relation between \( \mathbb{H}_p^\beta \) and \( \mathbb{H}_p^\beta \) is given as follows (cf. [18, p.180, (9)]): for any \( \beta > 0, \epsilon \in (0,\beta) \) and \( p > 1 \),

\[
\mathbb{H}_p^{\beta+\epsilon} \hookrightarrow \mathbb{H}_p^{\beta} \hookrightarrow \mathbb{H}_p^{\beta-\epsilon}. \quad (2.4)
\]

We recall the following complex interpolation theorem (cf. [18, p.59, Theorem (a)]).

**Theorem 2.1.** Let \( A_i \subset B_i, i = 0,1 \) be Banach spaces. Let \( \mathcal{T} : A_i \to B_i, i = 0,1 \) be bounded linear operators. For \( \theta \in [0,1] \), we have

\[
\|\mathcal{T}\|_{A_i \to B_i} \leq \|\mathcal{T}\|_{A_\theta \to B_\theta}^{1-\theta} \|\mathcal{T}\|_{A_\theta \to B_\theta}^\theta, \quad (2.5)
\]

where \( A_\theta := [A_0,A_1]_\theta, B_\theta := [B_0,B_1]_\theta, \) and \( \|\mathcal{T}\|_{A_0 \to B_0} \) denotes the operator norm of \( \mathcal{T} \) mapping \( A_\theta \) to \( B_\theta \).

Let \( f \) be a locally integrable function on \( \mathbb{R}^d \). The Hardy-Littlewood maximal function is defined by

\[
Mf(x) := \sup_{0<r<\infty} \frac{1}{|B_r|} \int_{B_r} |f(x+y)| \, dy,
\]

where \( B_r := \{x \in \mathbb{R}^d : |x| < r\} \). The following well known results can be found in [14, 21] and [16 page 5, Theorem 1].
Lemma 2.2. (i) For $f \in \mathbb{H}^{1}_r$, there exists a constant $C_d > 0$ and a Lebesgue zero set $E$ such that for all $x, y \notin E$,

$$|f(x) - f(y)| \leq C_d \cdot |x - y| \cdot (\mathcal{M}|\nabla f|(x) + \mathcal{M}|\nabla f|(y)). \tag{2.5}$$

(ii) For $p > 1$, there exists a constant $C_{d,p} > 0$ such that for all $f \in L^p(\mathbb{R}^d)$,

$$\|\mathcal{M}f\|_p \leq C_{d,p}\|f\|_p. \tag{2.6}$$

We now recall the following well known properties about the symmetric $\alpha$-stable process $(L_t)_{t \geq 0}$ (cf. [15, Theorem 25.3] and [8, Lemma 3.1]).

Proposition 2.4. Let $\mu_\lambda$ be the law of $\alpha$-stable process $L_\lambda$.

(i) (Scaling property): For any $\lambda > 0$, $(L_\lambda)_{t \geq 0}$ and $(\lambda^{-\frac{1}{\alpha}}L_\lambda)_{t \geq 0}$ have the same finite dimensional law. In particular, for any $t > 0$ and $A \in \mathcal{B}(\mathbb{R}^d)$, $\mu_\lambda(A) = \mu_1(t^{-\frac{1}{\alpha}}A)$.

(ii) (Existence of smooth density): For any $t > 0$, $\mu_t$ has a smooth density $p_t$ with respect to the Lebesgue measure, which is given by

$$p_t(x) = \frac{1}{(2\pi)^d} \int_{\mathbb{R}^d} e^{-i(x,\xi)} e^{-\frac{|\xi|^\alpha}{2t}} d\xi.$$ 

Moreover, $p_t(x) = p_t(-x)$ and for any $k \in \mathbb{N}$, $\nabla^k p_t \in L^1(\mathbb{R}^d)$.

(iii) (Moments): For any $t > 0$, if $\beta < \alpha$, then $\mathbb{E}|L_t|^{\beta} < +\infty$; if $\beta \geq \alpha$, then $\mathbb{E}|L_t|^{\beta} = \infty$.

The Markovian semigroup associated with the Lévy process $(L_t)_{t \geq 0}$ is given by

$$\mathcal{T}_t f(x) = \mathbb{E}(f(L_t + x)) = \int_{\mathbb{R}^d} p_t(x - z)f(z)dz = \int_{\mathbb{R}^d} p_t(x - z)f(z)dz. \tag{2.8}$$

We have:
Lemma 2.5. (i) For any $\alpha \in (0, 2)$, $p > 1$ and $\beta, \gamma \geq 0$, we have for all $f \in \mathbb{H}^\beta_p$,
\[ \|T_\cdot f\|_{\beta+\gamma,p} \leq C \tau^{-\gamma/\alpha} \|f\|_{\beta,p}. \] (2.9)
(ii) For any $\alpha \in (1, 2)$, $\theta \in [0, 1]$ and $p > 1$, there exists a constant $C = C(d, p, \theta) > 0$ such that for all $f \in \mathbb{H}^\theta_p$,
\[ \|T_\cdot f - f\|_p \leq C \tau^{\theta/\alpha} \|f\|_{\beta,p}. \] (2.10)

Proof. (i) Let $f \in C^\infty_0(\mathbb{R}^d)$. For any $k, m \in \mathbb{N}$, by the scaling property, we have
\[ \nabla^{k+m}T_\cdot f(x) = t^{-(d+k)/\alpha} \int_{\mathbb{R}^d} (\nabla^k p)\left(t^{-1/\alpha}(x-z)\right) \nabla^m f(z)dz. \]
Hence,
\[ \|\nabla^{k+m}T_\cdot f\|_p \leq t^{-k/\alpha} \|\nabla^m f\|_p \int_{\mathbb{R}^d} |\nabla^k p|(x)dx. \]
Since $C^\infty_0(\mathbb{R}^d)$ is dense in $\mathbb{H}^m_p$, we further have for any $f \in \mathbb{H}^m_p$,
\[ \|\nabla^{k+m}T_\cdot f\|_p \leq t^{-k/\alpha} \|f\|_m \int_{\mathbb{R}^d} |\nabla^k p|(x)dx. \]
On the other hand, it is clear that
\[ \|T_\cdot f\|_p \leq \|f\|_p. \]
By Theorem 2.1, we obtain (2.9).
(ii) First, we assume that $f \in \mathbb{H}^1_p$. By (2.5), we have for Lebesgue almost all $x \in \mathbb{R}^d$,
\[ |T_\cdot f(x) - f(x)| \leq \int_{\mathbb{R}^d} |f(x+y) - f(x)| \cdot p_t(y)dy \]
\[ \leq C \int_{\mathbb{R}^d} (M\|\nabla f\|(x+y) + M\|\nabla f\|(x) \cdot |y| \cdot p_t(y)dy, \]
and so, by (2.6) and the scaling property,
\[ \|T_\cdot f - f\|_p \leq C \|\nabla f\|_p \int_{\mathbb{R}^d} |y| \cdot p_t(y)dy \]
\[ \leq C \|\nabla f\|_p \mathbb{E}[L_t] = C t^{1/\alpha} \|\nabla f\|_p \mathbb{E}[L_1]. \]
Estimate (2.10) follows by (iii) of Proposition 2.4 and Theorem 2.1 again. \( \square \)

We also need the following simple result for proving the uniqueness.

Lemma 2.6. Let $(Z_t)_{t \geq 0}$ be a locally bounded and $(\mathcal{F}_t)$-adapted process and $(A_t)_{t \geq 0}$ a continuous real valued non-decreasing $(\mathcal{F}_t)$-adapted process with $A_0 = 0$. Assume that for any stopping time $\eta$ and $t \geq 0$,
\[ \mathbb{E}[\tau_{A\wedge \eta}] \leq \mathbb{E} \int_0^{\tau_{A\wedge \eta}} |Z_s|dA_s. \]
Then $Z_t = 0$ a.s. for all $t \geq 0$.

Proof. By replacing $A_t$ by $A_t + t$, one may assume that $t \mapsto A_t$ is strictly increasing. For $t \geq 0$, define the stopping time
\[ \tau_t := \inf\{s \geq 0 : A_s \geq t\}. \]
It is clear that $\tau_t$ is the inverse of $t \mapsto A_t$. Fix $T > 0$. By the assumption and the change of variable, we have
\[ \mathbb{E}[Z_{T \wedge \tau_t}] \leq \mathbb{E} \int_0^{T \wedge \tau_t} |Z_s|dA_s \leq \mathbb{E} \int_0^{\tau_t} |Z_{T \wedge \eta}|dA_s = \int_0^{T \wedge \eta} \mathbb{E}[Z_{T \wedge \eta}]ds. \]
By Gronwall’s inequality, we obtain $Z_{T∧τ_i} = 0$. Letting $t \to \infty$ gives the conclusion. □

3. Krylov’s estimates for purely discontinuous semimartingales

Let $(L_t)_{t \geq 0}$ be a symmetric $α$-stable process. The associated Poisson random measure is defined by

$$N((0, t] \times U) := \sum_{s \in (0, t]} 1_{U}(L_s - L_{s-}), \quad U \in \mathcal{B}(\mathbb{R}^d \setminus \{0\}), \ t > 0.$$  

The compensated Poisson random measure is given by $\tilde{N}((0, t] \times U) = N((0, t] \times U) - tv(U)$. By Lévy-Itô’s decomposition, one may write (cf. [15])

$$L_t = \int_{0}^{t} x\tilde{N}(ds, dx) + \int_{0}^{t} xN(ds, dx). \quad (3.1)$$

Let $X_t$ a purely discontinuous semimartingale with the form

$$X_t = X_0 + \int_{0}^{t} \xi_s ds + L_t,$$  \quad (3.2)

where $X_0 \in \mathcal{F}_0$ and $(\xi_t)_{t \geq 0}$ is a measurable and $(\mathcal{F}_t)$-adapted $\mathbb{R}^d$-valued process. Let $u$ be a bounded smooth function on $\mathbb{R}_+ \times \mathbb{R}^d$. By Itô’s formula (cf. [3]), we have

$$u_t(X_t) = u_0(X_0) + \int_{0}^{t} \left( [\partial_i u_s + \mathcal{L}_0 u_s](X_s) + \xi^i_s \partial_i u_s(X_s) \right) ds$$

$$+ \int_{0}^{t} \int_{\mathbb{R}^d \setminus \{0\}} [u_s(X_s + y) - u_s(X_s - y)] \tilde{N}(ds, dy).$$

In this section, we prove two estimates of Krylov’s type for the above $X_t$. Let us first prove the following simple Krylov’s estimate, which will be used in Section 4 to prove the existence of weak solutions for SDE (1.1) with singular drift $b$.

**Theorem 3.1.** Suppose that $α \in (1, 2)$, $p > \frac{d}{α - 1}$ and $q > \frac{pq}{p(α - 1) - d}$. Then, for any $T_0 > 0$, there exist a constant $C = C(T_0, d, α, p, q) > 0$ such that for any stopping time $τ$, and $0 ≤ s < T ≤ T_0$, and all $f \in L^q(S, T]; L^p(\mathbb{R}^d))$,

$$\mathbb{E}\left( \int_{S ∧ T} f_s(X_s) ds \right) \leq C \left( 1 + \mathbb{E}\left( \int_{S ∧ T} |ξ_s| ds \right) \right) \|f\|_{L^q(S, T]; L^p(\mathbb{R}^d))}. \quad (3.3)$$

**Proof.** Let us first assume that $f \in C^0_{\infty}(\mathbb{R}_+ \times \mathbb{R}^d)$ and define

$$u_t(x) = \int_{0}^{t} \mathcal{T}_{t-s} f_s(x) ds,$$

where $\mathcal{T}_t$ is defined by (2.8). By Lemma 2.5 it is easy to see that $u_t(x) \in C^0_{\infty}(\mathbb{R}_+ \times \mathbb{R}^d)$ and solves the following PIDE:

$$\partial_t u_t(x) = \mathcal{L}_0 u_t(x) + f_t(x).$$

Choosing $γ ∈ (1 + \frac{d}{p}, α - \frac{d}{q})$, by (2.9) and Hölder’s inequality, we have

$$\|u_t\|_{γ,p} \leq \int_{0}^{t} \|\mathcal{T}_{t-s} f_s\|_{γ,p} ds \leq C \int_{0}^{t} (t - s)^{-γ/α} \|f_s\|_{p} ds$$

$$\leq C \left( \int_{0}^{t} (t - s)^{-q^*/q} ds \right)^{1/p} \|f\|_{L^q(S, T]; L^p(\mathbb{R}^d))} \leq C_1 \|f\|_{L^q(S, T]; L^p(\mathbb{R}^d))}, \quad (3.4)$$

where $q^* = q/(q - 1)$. 

7
Fix $T_0 > 0$ and an $(\mathcal{F}_i)$-stopping time $\tau$. Using Itô’s formula for $u_{T_0-t}(X_t)$ and by Doob’s optimal theorem, we have

$$
\mathbb{E}(u_{T_0-T_\wedge\tau}(X_{T_\wedge\tau})|\mathcal{F}_S) - u_{T_0-S_\wedge\tau}(X_{S_\wedge\tau})
$$

$$
= \mathbb{E} \left( \int_{S_\wedge\tau}^{T_\wedge\tau} \left[ \partial_t u_{T_0-t} + \mathcal{L}_0 u_{T_0-t}(X_t) + \xi_s^i \partial_s u_{T_0-t}(X_s) \right] dt \Bigg| \mathcal{F}_S \right)
$$

$$
\leq \mathbb{E} \left( \int_{S_\wedge\tau}^{T_\wedge\tau} \left( - f_s(X_s) + |\xi_s| : |\nabla u_{T_0-t}(X_s)| \right) ds \Bigg| \mathcal{F}_S \right),
$$

which yields by (3.4) and (2.1) that,

$$
\mathbb{E} \left( \int_{S_\wedge\tau}^{T_\wedge\tau} f_s(X_s) ds \Bigg| \mathcal{F}_S \right) \leq 2 \sup_{s,x} |u_s(x)| + \sup_{s,x} |\nabla u_s(x)| \cdot \mathbb{E} \left( \int_{S_\wedge\tau}^{T_\wedge\tau} |\xi_s| ds \Bigg| \mathcal{F}_S \right)
$$

$$
\leq C \|f\|_{L^q([S,T];L^p(\mathbb{R}^d))} \left( 1 + \mathbb{E} \left( \int_{S_\wedge\tau}^{T_\wedge\tau} |\xi_s| ds \Bigg| \mathcal{F}_S \right) \right),
$$

where we have used $p(y-1) > d$. By a standard density argument, we obtain (3.3) for general $f \in L^q([S,T];L^p(\mathbb{R}^d))$. □

In one dimensional case, as in [13], we even have:

**Theorem 3.2.** Let $X_t$ take the following form:

$$
X_t = X_0 + \int_0^t \xi_s ds + \int_0^t h_s dL_s,
$$

where $h_s$ is a bounded predictable process. Suppose that $\alpha \in (1,2)$ and $p > \frac{1}{\alpha-1}$. Then, for any $T_0 > 0$, there exist a constant $C = C(T_0, \alpha, p, q) > 0$ such that for any $(\mathcal{F}_i)$-stopping time $\tau$, and $0 \leq S < T \leq T_0$, and all $f \in L^q(\mathbb{R}^d)$,

$$
\mathbb{E} \left( \int_{S_\wedge\tau}^{T_\wedge\tau} |h_s|^\alpha f(X_s) ds \Bigg| \mathcal{F}_S \right) \leq C \left( 1 + \mathbb{E} \left( \int_{S_\wedge\tau}^{T_\wedge\tau} (|\xi_s| + |h_s|^\alpha) ds \Bigg| \mathcal{F}_S \right) \right) \|f\|_p.
$$

(3.5)

**Proof.** Fix $T_0 > 0$. For $f \in C^\infty_0(\mathbb{R}^d)$, let us define

$$
u_t(x) := \int_0^T \mathcal{T}_{T_0-s} f(x) ds.
$$

It is easy to see that

$$
\mathcal{L}_0 u_t(x) = \mathcal{T}_{T_0} f(x) - f(x).
$$

(3.6)

Using Itô’s formula for $u_{T_0}(X_t)$ (cf. [4] Proposition 2.1], one finds that

$$
\mathbb{E}(u_{T_0}(X_T)|\mathcal{F}_S) = u_{T_0}(X_{S_\wedge\tau}) + \mathbb{E} \left( \int_{S_\wedge\tau}^{T_\wedge\tau} (|h_s|^\alpha \mathcal{L}_0 u_{T_0}(X_s) + \xi_s u_{T_0}(X_s)) ds \Bigg| \mathcal{F}_S \right),
$$

which together with (3.6) yields that

$$
\mathbb{E} \left( \int_{S_\wedge\tau}^{T_\wedge\tau} |h_s|^\alpha f(X_s) ds \Bigg| \mathcal{F}_S \right) \leq 2 \|u_{T_0}\|_\infty + \|u_T\|_\infty \mathbb{E} \left( \int_{S_\wedge\tau}^{T_\wedge\tau} \xi_s ds \Bigg| \mathcal{F}_S \right)
$$

$$
+ \|\mathcal{T}_{T_0} f\|_\infty \mathbb{E} \left( \int_{S_\wedge\tau}^{T_\wedge\tau} |h_s|^\alpha ds \Bigg| \mathcal{F}_S \right)
$$

$$
\leq C \left( 1 + \mathbb{E} \left( \int_{S_\wedge\tau}^{T_\wedge\tau} (|\xi_s| + |h_s|^\alpha) ds \Bigg| \mathcal{F}_S \right) \right) \|f\|_p,
$$

8
where we have used \( p(\alpha - 1) > 1, (2.9) \) and (2.1). By a standard density argument, we obtain (3.5) for general \( f \in L^p(\mathbb{R}^d) \).

In the above two theorems, the requirement of \( p > \frac{d}{\gamma - 1} \) is too strong to prove Theorem 3.1. It is clear that this is caused by directly controlling the \( \infty \)-norm of \( \nabla u_t(x) \) by Sobolev embedding theorem. In what follows, we shall relax it to \( p > \frac{d}{\gamma} \). The price to pay is that we need to assume that \( \xi_t \) is a bounded \( (\mathcal{F}_t) \)-adapted process. Nevertheless, Theorem 3.1 can be used to prove the existence of weak solutions for SDE (1.1) with globally integrable drift.

We now start by solving the following semi-linear PIDE:

\[
\partial_t u = \mathcal{L}_0 u + \kappa |\nabla u| + f, \quad u_0 \equiv 0, \quad t \geq 0
\]

(3.7)

where \( \kappa > 0 \), \( \mathcal{L}_0 \) is the generator of Lévy process \((L_t)_{t \geq 0}\) given by (1.11), and \( f \) is a locally integrable function on \( \mathbb{R}_+ \times \mathbb{R}^d \).

We first give the following definition of generalized solutions to PIDE (3.7).

**Definition 3.3.** For \( p \geq 1 \), a function \( u \in C([0, \infty); \mathbb{H}_p^1) \) is called a generalized solution of (3.7), if for all function \( \varphi \in C_c^\infty([0, \infty) \times \mathbb{R}^d) \), it holds that

\[
- \int_0^\infty \int_{\mathbb{R}^d} u_0 \varphi \, \mathrm{d}z = \int_0^\infty \int_{\mathbb{R}^d} u \mathcal{L}_0^* \varphi \, \mathrm{d}z + \int_0^\infty \int_{\mathbb{R}^d} (\kappa |\nabla u| + f) \varphi \, \mathrm{d}z
\]

where \( \mathcal{L}_0^* \) is the adjoint operator of \( \mathcal{L}_0 \) given by

\[
\mathcal{L}_0^* \varphi(x) = \int_{\mathbb{R}^d} (\varphi(x - z) - \varphi(x) + 1_{|z| \leq 1} z_i \partial_i \varphi(x)) \nu(\mathrm{d}z).
\]

**Remark 3.4.** If we extend \( u \) and \( f \) to \( \mathbb{R} \) by setting \( u_t = f_t \equiv 0 \) for \( t \leq 0 \), then for all \( \varphi \in C_c^\infty(\mathbb{R}^{d+1}) \),

\[
- \int_{\mathbb{R}^{d+1}} u_0 \varphi \, \mathrm{d}z = \int_{\mathbb{R}^{d+1}} u \mathcal{L}_0^* \varphi \, \mathrm{d}z + \int_{\mathbb{R}^{d+1}} (\kappa |\nabla u| + f) \varphi
\]

Since the Lévy measure \( \nu \) is symmetric, \( \mathcal{L}_0^* \) is in fact the same as \( \mathcal{L}_0 \).

The following proposition is now standard. We omit the proof.

**Proposition 3.5.** For \( p \geq 1 \), let \( u \in C([0, \infty); \mathbb{H}_p^1) \) and \( f \in L^1_{\text{loc}}([0, \infty) \times \mathbb{R}^d) \). The following three statements are equivalent:

(i) \( u \) is a generalized solution of (3.7);

(ii) For any \( \varphi \in C_c^\infty(\mathbb{R}^d) \), it holds that for all \( t \geq 0 \),

\[
\int_{\mathbb{R}^d} u_t \varphi \, \mathrm{d}z = \int_0^t \int_{\mathbb{R}^d} u \mathcal{L}_0^* \varphi \, \mathrm{d}z + \int_0^t \int_{\mathbb{R}^d} (\kappa |\nabla u| + f) \varphi \, \mathrm{d}z
\]

(iii) \( u \) satisfies the following integral equation:

\[
u_t(x) = \int_0^\infty \mathcal{T}_{t-s}(\kappa |\nabla u_s| + f_s)(x) \, \mathrm{d}s, \quad \forall t \geq 0.
\]

We have the following existence-uniqueness result about the generalized solution of equation (3.7).

**Theorem 3.6.** For \( p > 1, \alpha \in (1, 2), \gamma \in [1, \alpha) \) and \( q > \frac{\alpha - 1}{\alpha - \gamma} \), assume that \( f \in L^q_{\text{loc}}(\mathbb{R}_+; L^p(\mathbb{R}^d)) \). Then, there exists a unique generalized solution \( u \in C([0, \infty); \mathbb{H}_p^1) \) to PIDE (3.7). Moreover,

\[
\|u_t\|_{L^p} \leq C_t \|f\|_{L^q(0, t; L^p)}, \quad \forall t \geq 0,
\]

(3.8)

where \( C_t \geq 0 \) is a continuous increasing function of \( t \) with \( C_t = O(t^{1 - \frac{1}{2} - \frac{1}{q}}) \) as \( t \to 0 \).
Proof. Let \(u^{(0)} \equiv 0\). For \(n \in \mathbb{N}\), define \(u^{(n)}\) recursively by
\[
u^{(n)}(x) = \int_0^t \mathcal{T}_{t-s}(k|\nabla u_s^{(n-1)}| + f_s)(x) ds, \quad \forall t \geq 0.
\] (3.9)

By (i) of Lemma 2.5 and Hölder’s inequality, we have for \(q > \frac{\alpha}{\alpha - \gamma}\),
\[
\|u^{(n)}_t\|_{y,p} \leq C \int_0^t (t-s)^{-\frac{q}{2}}(k\|\nabla u_s^{(n-1)}\|_p + \|f_s\|_p) ds
\]
\[
\leq C \left( \int_0^t (t-s)^{-\frac{q\alpha}{\alpha - \gamma}} ds \right)^{\frac{2}{\alpha}} \left( \int_0^t (k\|\nabla u_s^{(n-1)}\|_p^q + \|f_s\|_p^q) ds \right)^{\frac{1}{q}},
\]
which yields that
\[
\|u^{(n)}_t\|_{y,p}^q \leq C t^{\frac{2\alpha-q\alpha}{\alpha}} \left( \int_0^t \|u_s^{(n-1)}\|_{1,p}^q ds + \int_0^t \|f_s\|_p^q ds \right)
\]
\[
\leq C t^{\frac{2\alpha-q\alpha}{\alpha}} \left( \int_0^t \|u_s^{(n-1)}\|_{y,p}^q ds + \int_0^t \|f_s\|_p^q ds \right).
\]

By Gronwall’s inequality, we obtain that for all \(t \geq 0\),
\[
\sup_{n\in\mathbb{N}} \|u^{(n)}_t\|_{y,p}^q \leq C_t \int_0^t \|f_s\|_p^q ds.
\] (3.10)

Next, fixing \(T > 0\), we want to prove the Hölder continuity of mapping \([0, T] \ni t \mapsto u^{(n)}_t \in \mathbb{H}_y^y\). For \(T \geq t > t' \geq 0\), we have
\[
u^{(n)}_t - u^{(n)}_{t'} = \int_0^{t'} (\mathcal{T}_{t-s} - \mathcal{T}_{t'-s})(k|\nabla u_s^{(n-1)}| + f_s) ds
\]
\[
+ \int_{t'}^t \mathcal{T}_{t-s}(k|\nabla u_s^{(n-1)}| + f_s) ds =: I_1(t, t') + I_2(t, t').
\]

For \(I_1(t, t')\), using the semigroup property of \(\mathcal{T}_t\), we further have
\[
I_1(t, t') = \int_0^{t'} \mathcal{T}_{(t'-s)/2}(\mathcal{T}_{t'-t} - I)\mathcal{T}_{(t'-s)/2}(k|\nabla u_s^{(n-1)}| + f_s) ds.
\]

Hence, by Lemma 2.5 and (3.10), for \(\delta \in (0, \alpha - \gamma - \frac{2}{q})\), we have
\[
\|I_1(t, t')\|_{y,p} \leq C \int_0^{t'} (t'-s)^{-\frac{q}{2}}\|\mathcal{T}_{t'-t} - I\|_{\mathbb{H}^y} \|\nabla u_s^{(n-1)}| + f_s\|_{y,p} ds
\]
\[
\leq C \int_0^{t'} (t'-s)^{-\frac{q}{2}}(t-t')^{\frac{q}{2}}\|\mathcal{T}_{(t'-s)/2}\|_{\mathbb{H}^y} \|\nabla u_s^{(n-1)}| + f_s\|_{y,p} ds
\]
\[
\leq C (t-t')^{\frac{q}{2}} \int_0^{t'} (t'-s)^{-\frac{2\alpha-q\alpha}{\alpha}} (\|\nabla u_s^{(n-1)}| + f_s\|_{y,p}) ds
\]
\[
\leq C (t-t')^{\frac{q}{2}} \|f\|_{L^2([0,T];L^p(\mathbb{R}^d))}.
\] (3.11)

For \(I_2(t, t')\), using (3.10), we also have
\[
\|I_2(t, t')\|_{y,p} \leq C_T (t-t')^{1 - \frac{2}{\alpha} - \frac{2}{q}} \|f\|_{L^p([0,T];L^p)}.
\] (3.12)

Combining (3.11) and (3.12), we obtain the desired Hölder continuity.

Now, as above, we can make the following estimation:
\[
\|u^{(n)}_t - u^{(m)}_t\|_{y,p} \leq C \int_0^t (t-s)^{-\frac{q}{2}} (\|\nabla u_s^{(n-1)}| - |\nabla u_s^{(m-1)}|\|^q_p) ds
\]
\[
= C_T (t-t')^{1 - \frac{2}{\alpha} - \frac{2}{q}} \|f\|_{L^2([0,T];L^p(\mathbb{R}^d))}.
\]
\[
\leq C t^{1 - \frac{2}{\alpha} - \frac{1}{q}} \left( \int_0^t \| \nabla (u_s^{(n-1)} - u_s^{(m-1)}) \|_{\gamma,p}^q ds \right)^{\frac{1}{q}},
\]
which then gives that
\[
\| u_t^{(n)} - u_t^{(m)} \|_{\gamma,p}^q \leq C t^{\frac{2 - 2\gamma - \alpha}{\alpha}} \int_0^t \| u_s^{(n-1)} - u_s^{(m-1)} \|_{\gamma,p}^q ds,
\]
where \( C \) is independent of \( n, m \) and \( t \). Using (3.10) and Fatou’s lemma, we find that
\[
\lim_{n,m \to \infty} \sup_{s \in [0,t]} \| u_s^{(n)} - u_s^{(m)} \|_{\gamma,p}^q = 0.
\]
Thus, there exists a \( u \in C([0,\infty); H^p_\gamma) \) such that for any \( t > 0 \),
\[
\lim_{n \to \infty} \sup_{s \in [0,t]} \| u_s^{(n)} - u_s \|_{\gamma,p} = 0.
\]
Taking limits for both sides of (3.9), we obtain the existence of a generalized solution, and (3.8) is direct from (3.10).

As for the uniqueness, it follows from a similar calculation. The proof is complete. \( \square \)

Let us now prove our second Krylov’s estimate.

**Theorem 3.7.** Suppose that \( \alpha \in (1,2) \), \( p > \frac{4}{\alpha} \lor 1 \) and \( q > \frac{2\alpha}{3\alpha - 2} \). Let \( (\xi_t)_{t \geq 0} \) be a measurable and \((\mathcal{F}_t)\)-adapted process bounded by \( k \), and let \( X_t \) have the form (3.2). Then for any \( T_0 > 0 \), there exist a constant \( C = C(T_0, k, d, \alpha, p, q) > 0 \) such that for any \((\mathcal{F}_t)\)-stopping time \( \tau \), and \( 0 \leq S < T \leq T_0 \), and all \( f \in L^p([S,T]; L^p(\mathbb{R}^d)) \),
\[
\mathbb{E} \left( \int_{S \wedge \tau}^{T \wedge \tau} f_s(X_s) ds \bigg\vert \mathcal{F}_S \right) \leq C \| f \|_{L^p([S,T]; L^p(\mathbb{R}^d))}.
\]

**Proof.** Let us first assume that \( f \in C_0^\infty(\mathbb{R}^d) \). Choose \( q \in \left( \frac{2}{p}, \frac{\alpha - 2}{\alpha} \right) \) and let \( u \in C([0,\infty); H^p_\gamma) \) be the unique solution of PIDE (3.7). Fix \( T_0 > 0 \), and let \( v_t(x) = u_{t_0 - t}(x) \). It is easy to see that \( v_t \) is a generalized solution of the following PIDE:
\[
\partial_t v + L_0 v + k |\nabla v| + f = 0, \quad v_{T_0} \equiv 0.
\]

Let \( \rho \) be a smooth nonnegative function in \( \mathbb{R}^{d+1} \) with support in \( \{(s, x) \in \mathbb{R}^{d+1} : |s| + |x| \leq 1\} \) and \( \int_{\mathbb{R}^{d+1}} \rho = 1 \). For \( \varepsilon > 0 \), set
\[
\rho_\varepsilon(s, x) = \varepsilon^{-(d+1)} \rho(\varepsilon^{-1} s, \varepsilon^{-1} x)
\]
and
\[
\psi_\varepsilon(t) = \varepsilon \rho_\varepsilon, \quad f_\varepsilon = f * \rho_\varepsilon.
\]
Taking convolutions for both sides of (3.14), we obtain that
\[
\partial_t \psi_\varepsilon + L_0 \psi_\varepsilon + k |\nabla \psi_\varepsilon| + f_\varepsilon \leq (\partial_t \psi + L_0 \psi + k |\nabla \psi| + f) * \rho_\varepsilon = 0.
\]
Here we have used Remark 3.4.

Using Itô’s formula for \( \psi_\varepsilon(X_t) \), we get
\[
\mathbb{E} \left( \psi_\varepsilon(T_0 \wedge \tau)(X_{T_0 \wedge \tau}) \bigg\vert \mathcal{F}_S \right) - \psi_\varepsilon(S \wedge \tau)(X_{S \wedge \tau}) = \mathbb{E} \left( \int_{S \wedge \tau}^{T \wedge \tau} \left( \partial_s \psi_\varepsilon + L_0 \psi_\varepsilon \right)(X_s) + \xi_s \partial_s \psi_\varepsilon(X_s) \right) ds \bigg\vert \mathcal{F}_S \right)
\]
In fact, choosing \( \varepsilon \) sufficiently small, there exists a probability space \( (\tilde{\Omega}, \tilde{\mathcal{F}}, \tilde{\mathbb{P}}) \) and two càdlàg stochastic processes \( \tilde{X}_t \) and \( \tilde{L}_t \) defined on it such that for any \( f \in L^q([0,T];L^p(\mathbb{R}^d)) \)

Taking limits \( \varepsilon \to 0 \), by the dominated convergence theorem, we have

By a standard density argument, we obtain (3.13) for general \( f \in L^q([S,T];L^p(\mathbb{R}^d)) \).

4. Weak solutions for SDE (1.1) with globally integrable drift

In this section, we use Theorem 3.1 to prove the following existence of weak solutions for SDE (1.1).

**Theorem 4.1.** Suppose that \( \alpha \in (1,2), \gamma \in (1,\alpha), p > \frac{d}{\gamma-1} \) and \( q > \frac{\alpha}{\alpha-\gamma} \). Then for any \( b \in L^\infty_{loc}(\mathbb{R}^d;L^\infty(\mathbb{R}^d)) + L^q_{loc}(\mathbb{R}^d;L^p(\mathbb{R}^d)) \) and \( x_0 \in \mathbb{R}^d \), there exists a weak solution to SDE (1.1).

More precisely, there exists a probability space \( (\tilde{\Omega}, \tilde{\mathcal{F}}, \tilde{\mathbb{P}}) \) and two càdlàg stochastic processes \( \tilde{X}_t \) and \( \tilde{L}_t \) defined on it such that \( \tilde{L}_t \) is a symmetric \( \alpha \)-stable process with respect to the completed filtration \( \tilde{\mathcal{F}}_t := \sigma^{\tilde{\mathcal{F}}}(\tilde{X}_t, \tilde{L}_s, s \leq t) \) and

**Proof.** Our proof is adapted from the proof of [10, p.87, Theorem 1]. Let \( b = b_1 + b_2 \) with \( b_1 \in L^\infty_{loc}(\mathbb{R}^d;L^\infty(\mathbb{R}^d)) \) and \( b_2 \in L^q_{loc}(\mathbb{R}^d;L^p(\mathbb{R}^d)) \). Let \( b^{(n)}_i(t,x) = (b_i(t,\cdot)\ast \rho_n) \) be the mollifying approximation of \( b_i \), \( i = 1,2 \). It is easy to see that for some \( \ell_i^{(n)} \in L^1_{loc}(\mathbb{R}^d) \),

\[
|b^{(n)}_i(t,x) - b^{(n)}_i(t,x)| \leq \ell_i |x - y|, \quad \forall x,y \in \mathbb{R}^d.
\]

Let \( X^{(n)}_t \) solve the following SDE:

\[
X^{(n)}_t = x_0 + \int_0^t b^{(n)}(s,X^{(n)}_s)ds + L_t.
\]

**Claim 1:** For some \( \delta > 1 \), we have

\[
\sup_{n \in \mathbb{N}} \mathbb{E} \int_0^T |b^{(n)}(s,X^{(n)}_s)|^\delta ds < +\infty, \quad \forall T > 0.
\]

In fact, choosing \( \delta > 1 \) and \( p' \in (\frac{d}{\gamma-1}, p), q' \in (\frac{\alpha}{\alpha-\gamma}, q) \) such that \( p'\delta = p \) and \( q'\delta = q \), by (3.13) and Young’s inequality, we have

\[
\mathbb{E} \int_0^T |b^{(n)}_2(s,X^{(n)}_s)|^\delta ds \leq C_T \left( 1 + \mathbb{E} \int_0^T |b^{(n)}(s,X^{(n)}_s)|ds \right) \|b^{(n)}_2\|^\delta_{L^{p'}([0,T];L^{q'}(\mathbb{R}^d))}
\]

\[
\leq C_T \left( 1 + \|b_1\|_{L^\infty([0,T];L^p(\mathbb{R}^d))} + \mathbb{E} \int_0^T |b^{(n)}_2(s,X^{(n)}_s)|ds \right) \|b_2\|^\delta_{L^{p}([0,T];L^q(\mathbb{R}^d))}
\]
\[ \leq \frac{1}{2} \mathbb{E} \int_0^T |b_2^{(n)}(s, X_s^{(n)})|^2 \, ds + C_T \| b_2 \|_{L^2([0,T]; L^p(\mathbb{R}^d))}^2 + C_T \left( 1 + \| b_1 \|_{L^\infty([0,T] \times \mathbb{R}^d)} \right) \| b_2 \|_{L^2([0,T]; L^p(\mathbb{R}^d))}^2, \]

which then implies (4.1).

Let \( \mathbb{D} \) be the space of all càdlàg functions from \( \mathbb{R}_+ \) to \( \mathbb{R}^d \), which is endowed with the Skorohod topology so that \( \mathbb{D} \) is a Polish space. Set

\[ H^{(n)}_t := \int_0^t b^{(n)}(s, X_s^{(n)}) \, ds. \]

Using Claim 1, it is easy to check that the following Aldous’ tightness criterions hold:

\[ \lim \sup_{N \to \infty} \sup_{n \to \infty} P \left( \sup_{t \in [0,T]} |H^{(n)}_t| \geq N \right) = 0, \quad \forall T > 0, \]

and

\[ \lim \sup_{a \to 0} \sup_{n \to \infty} P \left( |H^{(n)}_T - H^{(n)}_{T+\epsilon}| \geq a \right) = 0, \quad \forall T, a > 0, \]

where \( S_T \) denotes all the bounded stopping times with bound \( T \). Thus, the law of \( t \mapsto H^{(n)}_t \) in \( \mathbb{D} \) is tight, and so does \( (H^{(n)}_t, L) \). By Prohorov’s theorem, there exists a subsequence still denoted by \( n \) such that the law of \( (H^{(n)}_t, L) \) in \( \mathbb{D} \times \mathbb{D} \) weakly converges, which then implies that the law of \( (X^{(n)}_t, L) \) weakly converges. By Skorohod’s representation theorem, there is a probability space \( (\bar{\Omega}, \bar{\mathcal{F}}, \bar{P}) \) and the \( \mathbb{D} \times \mathbb{D} \)-valued random variables \( (\tilde{X}^{(n)}, \tilde{L}^{(n)}) \) and \( (\bar{X}, \bar{L}) \) such that

(i) \( (\tilde{X}^{(n)}, \tilde{L}^{(n)}) \) has the same law as \( (X^{(n)}_t, L) \) in \( \mathbb{D} \times \mathbb{D} \);

(ii) \( (\tilde{X}^{(n)}, \tilde{L}^{(n)}) \) converges to \( (\bar{X}, \bar{L}) \), \( \bar{P} \)-almost surely.

In particular, \( \bar{L} \) is still a symmetric \( \alpha \)-stable process and

\[ \tilde{X}^{(n)}_t = x_0 + \int_0^t b^{(n)}(s, \tilde{X}^{(n)}_s) \, ds + \tilde{L}^{(n)}_t. \]

**Claim 2:** For any nonnegative measurable function \( f \) and \( T > 0 \), we have

\[ \mathbb{E} \int_0^T f_s(\tilde{X}_s) \, ds \leq C_T \| f \|_{L^p([0,T]; L^p(\mathbb{R}^d))}, \]

where \( \mathbb{E} \) denotes the expectation with respect to the probability measure \( \bar{P} \).

Let \( f \in C_0([0,T] \times \mathbb{R}^d) \). By the dominated convergence theorem, we have

\[ \mathbb{E} \int_0^T f_s(\tilde{X}_s) \, ds = \lim_{n \to \infty} \mathbb{E} \int_0^T f_s(\tilde{X}^{(n)}_s) \, ds \]

\[ = \lim_{n \to \infty} \mathbb{E} \int_0^T f_s(X^{(n)}_s) \, ds \]

\[ \leq C \| f \|_{L^p([0,T]; L^p(\mathbb{R}^d))}, \]

where in the last step we have used (3.3) and (4.1). For general \( f \), it follows by the monotone class theorem.

The proof will be finished if one can show the following claim:

**Claim 3:** For any \( T > 0 \), we have

\[ \lim_{n \to \infty} \mathbb{E} \left( \int_0^T |b_i^{(n)}(s, \tilde{X}_s^{(n)}) - b_i(s, \tilde{X}_s)| \, ds \right) = 0, \quad i = 1, 2. \] (4.2)
Let \( \chi_R(x) \) be a smooth nonnegative function on \( \mathbb{R}^d \) with \( \chi_R(x) = 1 \) for \( |x| \leq R \) and \( \chi_R(x) = 0 \) for \( |x| > R + 1 \). Then for any \( n, m \in \mathbb{N} \),

\[
\mathbb{E}\left( \int_0^T |b_1^{(n)}(s, \tilde{X}_s) - b_1(s, \tilde{X}_s)|ds \right) \leq \mathbb{E}\left( \int_0^T |b_1^{(n)}(s, \tilde{X}_s) - b_1^{(m)}(s, \tilde{X}_s)|ds \right) + \mathbb{E}\left( \int_0^T |\chi_R(|b_1^{(n)} - b_1^{(m)}|)(s, \tilde{X}_s)|ds \right)
\]

Similarly, by Claim 1, we have

\[
\mathbb{E}\left( \int_0^T |b_1^{(n)}(s, \tilde{X}_s) - b_1(s, \tilde{X}_s)|ds \right) \leq \frac{C}{R} + C\|\chi_R(|b_1^{(n)} - b_1^{(m)})\|_{L^p([0,T];L^p)}.
\]

For fixed \( m \), by the above (ii) and the dominated convergence theorem, we have

\[
\lim_{n \to \infty} I_2^{(n,m)} = 0.
\]

For \( I_1^{(n,m)} \), by Claim 1, we have

\[
I_1^{(n,m)} \leq \|b_1\|_{L^\infty([0,T];L^\infty(\mathbb{R}^d))} \mathbb{E}\left( \int_0^T |1 - \chi_R(\tilde{X}_s)|ds \right) + \mathbb{E}\left( \int_0^T |\chi_R(|b_1^{(n)} - b_1^{(m)}|)(s, \tilde{X}_s)|ds \right)
\]

Similarly, by Claim 2, we have

\[
I_3^{(n,m)} \leq \frac{C}{R} + C\|\chi_R(b_1^{(m)} - b_1)\|_{L^p([0,T];L^p)}.
\]

Taking limits for both sides of (4.3) in order: \( n \to \infty \), \( m \to \infty \) and \( R \to \infty \), we obtain (4.2) for \( i = 1 \). It is similar to prove (4.2) for \( i = 2 \). The whole proof is complete. \( \square \)

**Remark 4.2.** When \( b \) is time-independent and the Lévy measure \( \nu(d\xi) = \frac{C_p}{\xi^{\gamma}}d\xi \), Theorem 5.1 has been proven by Chen, Kim and Song \([7]\) Theorem 2.5 by different argument.

5. Proof of Theorem 5.1

We now consider the following linear PIDE for \( \lambda > 0 \):

\[
\partial_t u = (L_0 - \lambda)u + b^i\partial_i u + f, \quad u_0 \equiv 0.
\]

As in the previous section, one may define the notion of generalized solutions and has:

**Theorem 5.1.** Let \( \alpha \in (1, 2) \) and \( \gamma \in (1, \alpha) \). Assume that for some \( p > \frac{\gamma}{\gamma - 1} \) and \( 0 \leq \beta \in (1 - \gamma + \frac{d}{p}, 1) \),

\[
b \in L^\infty_{\text{loc}}(\mathbb{R}^d), L^\infty(\mathbb{R}^d) \cap \mathbb{W}^\beta_p, \quad f \in L^\infty_{\text{loc}}(\mathbb{R}^d; \mathbb{W}^\beta_p).
\]

Then, there exists a unique generalized solution \( u = u^1 \in C(\mathbb{R}^+; \mathbb{W}^\gamma + \beta_p) \) to PIDE (5.1). Moreover, for some \( \delta > 0 \) and any \( \lambda \geq 1 \),

\[
\|u_t^1\|_{\gamma + \beta_p} \leq C_t\lambda^{-\delta}\|f\|_{L^\infty([0,T];\mathbb{W}^\beta_p)}, \quad \forall t \geq 0,
\]

where \( C_t > 0 \) is an increasing function of \( t \) with \( \lim_{t \to 0} C_t = 0 \).
Proof. As in the proof of Theorem 3.7, we only need to prove the a priori estimate (5.2). Let \( u \) satisfy the following integral equation:

\[
  u_t(x) = \int_0^t e^{-\lambda(t-s)} T_{t-s}(b^i_j \partial_i u_s + f_s)(x) \, ds, \quad \forall t \geq 0.
\]

Let \( \varepsilon \in (0, \alpha - \gamma) \) and \( q > \frac{\alpha}{\alpha - \gamma - \varepsilon} \). By Lemma 2.5 and Hölder’s inequality, we have

\[
  \|u_t\|_{y+\beta,p} \leq C \left( \int_0^t e^{-\lambda(t-s)} (t-s)^{-\frac{q(q+1)}{q-1}} \left( \|b^i_j \partial_i u_s\|_{\beta-\varepsilon,p} + \|f_s\|_{\beta-\varepsilon,p} \right)^q \, ds \right)^{\frac{1}{q}}.
\]

In view of \((\gamma + \beta - 1)p > d \) and \( \gamma > 1 \), we have

\[
  \|b^i_j \partial_i u_s\|_{\beta,p} \leq \|b^i_j\|_{\infty} \|\nabla u_s\|_{p} + \left( \int_{\mathbb{R}^d} \int_{\mathbb{R}^d} \frac{|(b^i_j \partial_i u_s)(x) - (b^i_j \partial_i u_s)(y)|^p}{|x-y|^{d+fp}} \, dx \, dy \right)^{1/p},
\]

\[
  \leq \|b^i_j\|_{\infty} \|\nabla u_s\|_{p} + \|b^i_j\|_{\infty} \|\nabla u_s\|_{\beta,p} + \|b^i_j\|_{\beta,p} \|\nabla u_s\|_{\infty},
\]

\[
  \leq \|b^i_j\|_{\infty} \|u_s\|_{1,p} + \|b^i_j\|_{\infty} \|u_s\|_{1+\beta,p} + C \|b^i_j\|_{\beta,p} \|u_s\|_{y+\beta,p},
\]

Hence,

\[
  \|u_t\|_{y+\beta,p}^q \leq C \lambda^{\frac{q(q+1)}{q-1}-1} \left( \int_0^q \|b^i_j\|_{L^q_{\infty}([0,t];L^q_{\infty}([0,T] ; \mathbb{R}^d))} \, ds + t \|f\|_{L^q_{\infty}([0,t];\mathbb{R}^d)}^q \right)^{\frac{q}{q-1}}.
\]

By Gronwall’s inequality, we obtain (5.2) with \( \delta = q - 1 - \frac{q(q+1)}{\alpha} > 0 \). \( \square \)

Below, we assume that \( b \in L^\infty_{loc}(\mathbb{R}^d ; L^\infty_{loc}(\mathbb{R}^d) \cap \mathbb{R}^d) \) with

\[
  \beta \in \left( 1 - \frac{\alpha}{2}, 1 \right), \quad p > \frac{2d}{\alpha},
\]

and fix

\[
  \gamma \in \left( 1 + \frac{\alpha}{2} - \beta \right) \vee 1, \alpha.
\]

Let \( u^\ell \) solve the following PIDE:

\[
  \partial_t u^\ell = (L_0 - \lambda) u^\ell + b^i_j \partial_i u^\ell + b^\ell, \quad u^\ell_0(x) = 0, \quad \ell = 1, \cdots, d.
\]

Fix \( T > 0 \) and set

\[
  v_t(x) := (u^1_{T-t}(x), \cdots, u^d_{T-t}(x)).
\]

Then \( v_t(x) \) solves the following PIDE:

\[
  \partial_t v + (L_0 - \lambda) v + b^i_j \partial_i v + b = 0, \quad v_T(x) = 0.
\]

Since \((\gamma + \beta - 1)p > d\), by (2.1) and (5.2), one can choose \( \lambda \) sufficiently large such that

\[
  \sup_{t \in [0,T]} \sup_{x \in \mathbb{R}^d} |\nabla v_t(x)| \leq \sup_{t \in [0,T]} C \|v_t\|_{y+\beta,p} \leq C_T \lambda^{-\delta} \|f\|_{L^\infty([0,T] ; \mathbb{R}^d)} \leq \frac{1}{2}.
\]

Let us define

\[
  \Phi_t(x) = x + v_t(x).
\]
Since for each $t \in [0, T],$
\[
\frac{1}{2}|x - y| \leq |\Phi_t(x) - \Phi_t(y)| \leq \frac{3}{2}|x - y|,
\]
x $\mapsto \Phi_t(x)$ is a diffeomorphism and
\[
|\nabla \Phi_t(x)| \leq \frac{3}{2}, \quad |\nabla \Phi_t^{-1}(x)| \leq 2.
\] (5.6)

**Lemma 5.2.** Let $\Phi_t(x)$ be defined as above. Fix an $(\mathcal{F}_t)$-stopping time $\tau$ and let $X_t \in \mathcal{S}_t^\tau(\mathcal{X})$ be a local solution of SDE (5.7). Then $Y_t = \Phi_t(X_t)$ solves the following SDE on $[0, T \wedge \tau):$
\[
Y_t = \Phi_0(x) + \int_0^t \tilde{b}_s(Y_s)ds + \int_0^t \int |z| I_{|z| \leq 1} g_s(Y_{s-}, z) \tilde{N}(ds, dz) + \int_0^t \int |z| > 1 g_s(Y_{s-}, z)N(ds, dz), \tag{5.7}
\]
where
\[
\tilde{b}_s(y) := \lambda v_s(\Phi_s^{-1}(y)) - \int |z| [v_s(\Phi_s^{-1}(y) + z) - v_s(\Phi_s^{-1}(y))]v(dz),
\]
and
\[
g_s(y, z) := \Phi_s(\Phi_s^{-1}(y) + z) - y. \tag{5.9}
\]

**Proof.** Set
\[
v_t^\rho(x) := (v \ast \rho_\rho(t, x), \quad \Phi_t^\rho(x) = x + v_t^\rho(x).
\]
By Itô’s formula, we have for all $t \in [0, T \wedge \tau),$
\[
\Phi_t^\rho(X_t) = \Phi_0^\rho(X_0) + \int_0^t \left[ \partial_t \Phi_t^\rho(X_t) + (b_t(x, X_t) - \partial_t \Phi_t^\rho(X_t)) \right]ds + \int_0^t \int |z| I_{|z| \leq 1} \left[ \Phi_t^\rho(X_{s-} + z) - \Phi_t^\rho(X_{s-}) - \partial_t \Phi_t^\rho(X_{s-}) \right]v(dz)ds + \int_0^t \int |z| > 1 \left[ \Phi_t^\rho(X_{s-} + z) - \Phi_t^\rho(X_{s-}) \right]N(ds, dz)
\]
\[
=: \Phi_0^\rho(X_0) + I_1^\rho(t) + I_2^\rho(t) + I_3^\rho(t) + I_4^\rho(t).
\]

We want to take limits for the above equality. First of all, for $I_4^\rho(t)$, by the dominated convergence theorem, we have
\[
I_4^\rho(t) = \int_0^t \int |z| \tilde{N}(ds, dz) + \int_0^t \int |z| I_{|z| \leq 1} [v_s^\rho(X_{s-} + z) - v_s^\rho(X_{s-})]N(ds, dz)
\]
\[
\rightarrow \int_0^t \int |z| \tilde{N}(ds, dz) + \int_0^t \int |z| [v_s(X_{s-} + z) - v_s(X_{s-})]N(ds, dz)
\]
\[
= \int_0^t \int |z| [\Phi_s(X_{s-} + z) - \Phi_s(X_{s-})]N(ds, dz) = \int_0^t \int g_s(Y_{s-}, z)N(ds, dz),
\]
and for $I_3^\rho(t),$
\[
\mathbb{E} \left[ \int_0^{T \wedge \tau} \int |z| [\Phi_s^\rho(X_{s-} + z) - \Phi_s^\rho(X_{s-}) - \Phi_s(X_{s-} + z) + \Phi_s(X_{s-})] \tilde{N}(ds, dz) \right]^2
\]
\[
= \mathbb{E} \int_0^{T \wedge \tau} \int |z| [\Phi_s^\rho(X_{s-} + z) - \Phi_s^\rho(X_{s-}) - \Phi_s(X_{s-} + z) + \Phi_s(X_{s-})]^2 \nu(dz)ds \to 0,
\]

16
where we have used that for some $C$ independent of $\varepsilon$,

$$|\Phi^\varepsilon_s(X_{s-} + z) - \Phi^\varepsilon_s(X_{s-})| \leq C|z|^2.$$  

Noting that

$$\partial_s \Phi^\varepsilon = \partial_s v^\varepsilon = -(\mathcal{L}_0 - \lambda)v^\varepsilon - (b'\partial_i v) * \rho_\varepsilon - b * \rho_\varepsilon = -(\mathcal{L}_0 - \lambda)v^\varepsilon - (b'\partial_i \Phi) * \rho_\varepsilon,$$

we have

$$I_1^\varepsilon(t) + I_2^\varepsilon(t) = \lambda \int_0^t v^\varepsilon_s(X_s) ds - \int_0^t \int_{|z|>1} [v^\varepsilon_s(X_s + z) - v^\varepsilon_s(X_s)] v(dz) ds$$

$$+ \int_0^t [(b'\partial_i \Phi^\varepsilon_s)(X_s) - ((b'\partial_i \Phi) * \rho_\varepsilon)(s, X_s)] ds.$$

By the dominated convergence theorem, the first two terms converge to

$$\lambda \int_0^\tau v_s(X_s) ds - \int_0^\tau \int_{|z|>1} [v_s(X_s + z) - v_s(X_s)] v(dz) ds = \int_0^\tau \tilde{b}_s(Y_s) ds.$$

Using Krylov’s estimate (3.13), we have

$$\mathbb{E} \int_0^{\tau/\alpha} |(b'\partial_i \Phi^\varepsilon_s)(X_s) - ((b'\partial_i \Phi) * \rho_\varepsilon)(s, X_s)| ds$$

$$\leq C \int_0^{\tau} \left( \int_{\mathbb{R}^d} |(b'\partial_i \Phi^\varepsilon_s)(x) - ((b'\partial_i \Phi) * \rho_\varepsilon)(s, x)|^p dx \right)^{\frac{q}{p}} ds \to 0,$$

where $q > \frac{\alpha}{\alpha - 1}$. Combining the above calculations, we obtain that $Y_t$ solves (5.7). \qed

We are now in a position to give:

**Proof of Theorem 7.1** We first assume that for some $\beta, p$ satisfying (5.3),

$$b \in L^\infty_{\text{loc}}(\mathbb{R}_+; L^\infty(\mathbb{R}^d) \cap \mathcal{W}_{\beta}^p).$$

The existence of weak solutions has been obtained in Theorem 4.1. Below, we concentrate on the proof of the pathwise uniqueness.

Fix an $(\mathcal{F}_t)$-stopping time $\tau$ and let $X_t, \hat{X}_t \in \mathcal{F}_b^\tau(x)$ be two solutions of SDE (1.1). Fixing $T > 0$, we want to prove that

$$Y_t := \Phi_t(X_t) = \Phi_t(\hat{X}_t) =: \hat{Y}_t, \quad \forall t \in [0, T \wedge \tau).$$

Define $\sigma_0 \equiv 0$ and for $n \in \mathbb{N}$,

$$\sigma_n := \inf \{ t \geq \sigma_{n-1} : |L_t - L_{t-}| > 1 \}.$$

Set

$$\sigma^T_n = \sigma_n \wedge T \wedge \tau.$$

Recall (3.1) and

$$\int_0^\tau \int_{|z|>1} g_s(Y_{s-}, z) N(ds, dz) = \sum_{s \in (0, \tau]} g_s(Y_{s-}, L_s - L_{s-}) \cdot 1_{|L_s - L_{s-}| > 1}.$$

By Lemma 5.2 $Z_t := Y_t - \hat{Y}_t$ satisfy the following equation on random interval $[\sigma^T_n, \sigma^T_{n+1})$:

$$Z_t = Z_{\sigma^T_n} + \int_{\sigma^T_n}^t [\tilde{b}_s(Y_s) - \tilde{b}_s(\hat{Y}_s)] ds + \int_{\sigma^T_n}^t \int_{|z|<1} [g_s(Y_{s-}, z) - g_s(\hat{Y}_{s-}, z)] N(ds, dz). \quad (5.10)$$

Let us first prove that

$$Z_t = 0 \text{ a.s. on } [0, \sigma^T_1).$$


Note that by (5.8), (5.5) and (5.6),
\begin{equation}
|\tilde{b}_s(y) - \tilde{b}_s(y')| \leq C |y - y'|, 
\end{equation}
and by (2.5),
\begin{align*}
|g_s(y, z) - g_s(y', z)| &= |\Phi_s(\Phi_s^{-1}(y) + z) - \Phi_s(\Phi_s^{-1}(y)) - \Phi_s(\Phi_s^{-1}(y') + z) + \Phi_s(\Phi_s^{-1}(y'))| \\
&= |v_s(\Phi_s^{-1}(y) + z) - v_s(\Phi_s^{-1}(y)) - v_s(\Phi_s^{-1}(y') + z) + v_s(\Phi_s^{-1}(y'))| \\
&= |(\mathcal{F}_s v_s)(\Phi_s^{-1}(y)) - (\mathcal{F}_s v_s)(\Phi_s^{-1}(y'))| \\
&\leq C|\Phi_s^{-1}(y) - \Phi_s^{-1}(y')| \cdot (\mathcal{M} |\nabla \mathcal{F}_s v_s|(\Phi_s^{-1}(y)) + \mathcal{M} |\nabla \mathcal{F}_s v_s|(\Phi_s^{-1}(y'))) \\
&\leq C|y - y'| \cdot (\mathcal{M} |\nabla \mathcal{F}_s v_s|(\Phi_s^{-1}(y)) + \mathcal{M} |\nabla \mathcal{F}_s v_s|(\Phi_s^{-1}(y'))). 
\end{align*}
Since $\mathbb{E}|X_t|^2 = +\infty$, for taking expectations for (5.10), we need to use stopping time to cut off it. For $R > 0$, define
\begin{equation}
\zeta_R := \inf\{t > 0 : |X_t| \vee |\hat{X}_t| \geq R\}. 
\end{equation}
Let $\eta$ be any $(\mathcal{F}_t)$-stopping time. By (5.10), (5.11) and (5.12), we have
\begin{align*}
\mathbb{E}[Z_t &\wedge \sigma^T_\eta \wedge \zeta_R \wedge \eta] \leq C \mathbb{E} \int_0^{\tau \wedge \eta} \left( |Z_s|^2 + \int_{|z| \leq 1} |g_s(Y_s, z) - g_s(\hat{Y}_s, z)|^2 \nu(\text{d}z) \right) \text{d}s \\
&\leq C \mathbb{E} \int_0^{\tau \wedge \eta} |Z_s|^2 \text{d}(s + A_s) \leq C \mathbb{E} \int_0^{\tau \wedge \eta} |Z_{s \wedge \sigma^T_\eta \wedge \zeta_R} - |Z_s|^2 \text{d}(s + A_s), 
\end{align*}
where
\begin{equation}
A_s := \int_0^s \int_{|z| \leq 1} \left( \mathcal{M} |\nabla \mathcal{F}_s v_s|(\Phi_s^{-1}(Y_s)) + \mathcal{M} |\nabla \mathcal{F}_s v_s|(\Phi_s^{-1}(\hat{Y}_s)) \right)^2 \nu(\text{d}z) \text{d}s. 
\end{equation}
By Fubini’s theorem, we have
\begin{align*}
\mathbb{E}[A_T] &= \int_{\{s \leq 1\}} \mathbb{E} \int_0^{\tau \wedge T} \left( \mathcal{M} |\nabla \mathcal{F}_s v_s|(X_s) + \mathcal{M} |\nabla \mathcal{F}_s v_s|(\hat{X}_s) \right)^2 \text{d}s \nu(\text{d}z) \\
&\leq C \int_{\{s \leq 1\}} \sup_{\{z \in [0, T]\}} ||(\mathcal{M} |\nabla \mathcal{F}_s v_s|)||_{L^2}^2 \nu(\text{d}z) \\
&= C \int_{\{s \leq 1\}} \sup_{\{z \in [0, T]\}} ||\mathcal{F}_s v_s||_{L^\beta}^2 \nu(\text{d}z) \\
&\leq C \sup_{\{z \in [0, T]\}} ||v_s||_{L^{2\gamma + \beta - 1}}^2 \int_{|z| \leq 1} |z|^{2(\gamma + \beta - 1)} \nu(\text{d}z) < +\infty, 
\end{align*}
where in the last step we have used (5.5), $2(\gamma + \beta - 1) > \alpha$ and (1.5). Therefore, $t \mapsto A_{t \wedge T}$ is a continuous $(\mathcal{F}_t)$-adapted increasing process. By Lemma 2.6 we obtain that for all $t \geq 0$,
\begin{equation}
Z_{t \wedge \sigma^T_\eta \wedge \zeta_R} = 0, \text{ a.s.} 
\end{equation}
Letting $R \to \infty$ yields that for all $t \in [0, T \wedge \tau)$,
\begin{equation}
Z_{t \wedge \sigma_1} = Z_{t \wedge \sigma^T_1} = 0, \text{ a.s.} 
\end{equation}
Thus, if $\sigma_1 < T \wedge \tau$, then
\begin{equation}
Z_{\sigma_1} = Z_{\sigma_1} + [g_{\sigma_1}(Y_{\sigma_1}, L_{\sigma_1} - L_{\sigma_1}) - g_{\sigma_1}(\hat{Y}_{\sigma_1}, L_{\sigma_1} - L_{\sigma_1})] = 0. 
\end{equation}
Repeating the above calculations, we find that for all $n \in \mathbb{N}$ and $t \in [0, T \wedge \tau)$,
\begin{equation}
Z_{t \wedge \sigma_n} = 0 \text{ a.s.} 
\end{equation}
Letting \( n, T \to \infty \) produces that for all \( t \in [0, \tau) \),
\[
Z_t = 0 \Rightarrow Y_t = \hat{Y}_t \Rightarrow X_t = \hat{X}_t \text{ a.s.}
\]

Lastly, we assume that \( b \) satisfies (1.7) and (1.8). For \( n \in \mathbb{N} \), let \( X_n \in C_0^\infty(\mathbb{R}^d) \) with \( X_n(x) = 1 \) for \( |x| \leq n \) and \( X_n(x) = 0 \) for \( |x| > n + 1 \). Define
\[
b^{(n)}_t(x) = b_t(x) \chi_n(x).
\]
Then \( b^{(n)} \in L^\infty(\mathbb{R}^d; L^\infty(\mathbb{R}^d) \times \mathcal{M}_P) \). By the previous proof, for each \( x \in \mathbb{R}^d \), there exists a unique strongly solution \( X^{(n)}_t \in \mathcal{D}(0, t) \) to SDE (1.1) with drift \( b^{(n)} \). For \( n \geq k \), define
\[
\tau_{n,k}(x, \omega) := \inf\{t \geq 0 : |X^{(n)}_t(\omega, x)| \geq k\}.
\]
It is easy to see that
\[
X^{(n)}_t(x), X^{(k)}_t(x) \in \mathcal{D}_{b^{(k)}}(x).
\]
As the local uniqueness has been proven, we have
\[
P[\omega : X^{(n)}_t(\omega, x) = X^{(k)}_t(\omega, x), \forall t \in [0, \tau_{n,k}(x, \omega))] = 1,
\]
which implies that for \( n \geq k \),
\[
\tau_{k,k}(x) \leq \tau_{n,k}(x) \leq \tau_{n,n}(x), \text{ a.s.}
\]
Hence, if we let \( \zeta_k(x) := \tau_{k,k}(x) \), then \( \zeta_k(x) \) is an increasing sequence of \( (\mathcal{F}_t) \)-stopping times and for \( n \geq k \),
\[
P[\omega : X^{(n)}_t(\omega, x) = X^{(k)}_t(\omega, x), \forall t \in [0, \zeta_k(x, \omega))] = 1.
\]
Now, for each \( k \in \mathbb{N} \), we can define \( X_t(x, \omega) = X^{(k)}_t(x, \omega) \) for \( t < \zeta_k(x, \omega) \) and \( \zeta(x) = \lim_{k \to \infty} \zeta_k(x) \).
It is clear that \( X_t(x) \in \mathcal{D}_b(\zeta(x)) \) and (1.9) holds. \( \square \)

Acknowledgements:

The author would like to express his deep thanks to Professor Jiagang Ren for teaching him the interpolation techniques and the fact (1.10) about ten years ago. The supports of NSFs of China (No. 10971076; 10871215) are also acknowledged.

References

[1] Aldous, D.: Stopping times and tightness. Ann. Prob., Vol. 6(1978), 335-340.
[2] Airault, H. and Zhang, X.: Smoothness of indicator functions of some sets in Wiener spaces. J. Math. Pures Appl., Vol. 79, No. 5, (2000) 515-523.
[3] Applebaum D.: Lévy processes and stochastic calculus. Cambridge Studies in Advance Mathematics 93, Cambridge University PRess, 2004.
[4] Bass, R.: Stochastic differential equations driven by symmetric stable processes. Seminaire de Probabilities, XXXVI, Lecture Notes in Math., 1801,302-313(2003).
[5] Bass, R.: Stochastic differential equations with jumps. Probability Surveys, Vol.1, (2004)1-19.
[6] Bogdan K. and Jakubowski T.: Estimates of heat kernel of fractional Laplacian perturbed by gradient operators. Commun. Math. Phys., 271(2007), 179-198.
[7] Chen Z., Kim P. and Song R.: Dirichlet heat kernel estimates for fractional Laplacian with gradient perturbation. http://arxiv.org/abs/1011.3273
[8] Priola E.: Pathwise uniqueness for singular SDEs driven by stable processes. http://arxiv.org/abs/1005.4237
[9] Ikeda N., Watanabe, S.: Stochastic differential equations and diffusion processes, 2nd ed., North-Holland/Kodanska, Amsterdam/Tokyo, 1989.
[10] Krylov N.V.: Controlled diffusion processes. Translated from the Russian by A.B. Aries. Applications of Mathematics, 14. Springer-Verlag, New York-Berlin, 1980.
[11] Krylov N.V. and Röckner M.: Strong solutions of stochastic equations with singular time dependent drift. Probab. Theory Relat. Fields, 131, 154-196(2005).
[12] Kurenok V.P.: Stochastic equations with time time-dependent drifts driven by Lévy processes. J. Theoretic Prob., 20(2007)859-869.
[13] Kurenok V.P.: A note on $L_2$-estimates for stable integrals with drift. Trans. Amer. Math. Soc. 360 (2008), 925-938.

[14] Ren, J. and Zhang, X.: Limit theorems for stochastic differential equations with discontinuous coefficients. to appear in SIAM J. Math. Anal.

[15] Sato K.I.: Lévy processes and infinite divisible distributions. Cambridge University Press, Cambridge, 1999.

[16] Stein E.M.: Singular integrals and differentiability properties of functions. Princeton, N.J., Princeton University Press, 1970.

[17] Tanaka H., Tsuchiya M. and Watanabe S.: Perturbation of drift-type for Lévy processes. J. Math. Kyoto Univ. 14(1974), 73-92.

[18] Triebel, H.: Interpolation Theory, Function Spaces, Differential Operators. North-Holland Publishing Company, Amsterdam, 1978.

[19] Veretennikov, A. Ju.: On the strong solutions of stochastic differential equations. Theory Probab. Appl., 24(1979),354-366.

[20] Zhang X.: Stochastic homeomorphism flows of SDEs with singular drifts and Sobolev diffusion coefficients. http://arxiv.org/abs/1010.3403.

[21] Zhang X.: Well-posedness and large deviation for degenerate SDEs with Sobolev coefficients. http://arxiv.org/abs/1002.4297.

[22] Zvonkin, A.K.: A transformation of the phase space of a diffusion process that removes the drift. Mat. Sbornik, No.1. 93(135),129-149(1974).