Chiral Pattern in Nonrotating Spherical Convection

Akira Kageyama

Department of Computational Science, Kobe University, Kobe 657-8501, Japan

Nobuaki Ohno

Graduate School of Information Science, University of Hyogo, Kobe 651-2197, Japan

When the Rayleigh number is low, Rayleigh-Bénard convection in a nonrotating spherical shell with central gravity has symmetric solutions in terms of three-dimensional discrete rotation. All the known patterns with the regular polyhedral symmetries accompany reflection symmetry. We found a new type of steady convection in a nonrotating spherical shell by computer simulations. The pattern has the discrete rotational symmetry of a regular tetrahedron with no reflection symmetry. The convection consists of six pairs of spiral rolls placed on 12 faces of a spherical dodecahedron. Depending on the winding of the spirals, there are two possible configurations that are mirror images of one another.

I. INTRODUCTION

Rayleigh-Bénard convection in a nonrotating spherical layer provides a venue of pattern formation that is finite but free of borders. In order to classify the spherical patterns, here we refer to the five finite subgroups of $SO(3)$ as the cyclic group ($C$), dihedral group ($D$), tetrahedral group ($T$), octahedral group ($O$), and icosahedral group ($I$). Among them, we are interested in the regular polyhedral groups, $T$, $O$, and $I$. Solutions are known for all of them: $T$, $O$, $I$. In this paper, we focus on the reflection symmetry, another symmetry of a nonrotating sphere. In theoretical models dealing with spherical pattern formation based on the reaction-diffusion equation, chiral solutions naturally appear as spiral patterns on spheres. Also in the spherical shell convection system, a chiral solution with spiral pattern was found. This solution is a single-arm spiral in which a long roll covers the entire spherical shell with both ends on antipodal points. It can be right- or left-handed winding. The solution has dihedral symmetry, that is, it is symmetric when flipped around an axis perpendicular to the diameter through the antipodal points. In the planar convection system, multiple spiral patterns, called spiral defect chaos, are known to appear, but they are not chiral because the numbers of opposite windings are the same when no rotation is externally applied.

We report in this paper a class of steady, chiral, and symmetric solutions in a nonrotating spherical shell. It has the discrete rotational symmetry of group $T$. 

II. BASIC EQUATIONS AND METHOD

We numerically integrated the time development of the fluid equation until we obtained steady solutions. This approach was challenging in terms of both computation and visualization, because multiple simulation jobs with different parameters, each requiring sufficiently long integration in a diffusion timescale, have to be executed.

We assumed that an ideal gas is confined in a spherical shell layer between inner and outer spheres of radii $r_i$ and $r_o$, respectively. We normalized the length by $r_o = 1.0$ and set $r_i = 0.945$. The shell depth is $d = r_o - r_i = 0.055$. We used the mass density $\rho$, mass flux density $f$, and pressure $p$ as basic variables and the flow velocity $v = f/\rho$ and normalized temperature $T = p/\rho$ as subsidiary variables. We solved the time development of the variables by
using the following equations.

\[ \frac{\partial p}{\partial t} = -\nabla \cdot f, \]

\[ \frac{\partial f}{\partial t} = -\nabla \cdot (vf) - \nabla p - \rho g + \mu \left\{ \nabla^2 v + (1/3)\nabla(\nabla \cdot v) \right\}, \]

\[ \frac{\partial p}{\partial t} = -v \cdot \nabla p - \gamma p \nabla \cdot v + (\gamma - 1)\kappa \nabla^2 T + (\gamma - 1)\Phi, \]

where \( \mu \) and \( \kappa \) were dynamic viscosity and thermal diffusivity, and we assumed \( \mu = \kappa \). \( \Phi \) was the dissipation function; \( \Phi = 2\mu \{ \text{tr}(\epsilon) - (1/3)\text{tr}(\epsilon)^2 \} \) with the strain-rate tensor \( \epsilon \). Ignoring the self-gravity of the fluid, the gravity acceleration was given by \( g = G\hat{r}/r^2 \), where \( \hat{r} \) was the unit vector in the radial direction and \( G \) was a constant. The specific heat ratio was \( \gamma = 5/3 \).

We used rigid boundary conditions for velocity, \( v = 0 \), and fixed temperature conditions on \( r = r_1 \) and \( r_o \). The initial temperature profile \( T_0(r) \), pressure \( p_0(r) \), and density \( \rho_0(r) \) were spherically symmetric hydrostatic equilibrium states with thermal conduction. The initial velocity was \( v_0 = 0 \). We normalized the thermodynamic variables in terms of their values on \( r = r_o(=1) \), that is, \( T_0(r_o) = p_0(r_o) = \rho_0(r_o) = 1.0 \). The initial state was given as \( T_0(r) = \beta/r^1 - \beta, p_0(r) = T_0^2 \), and \( \rho_0(r) = T_0^{n-1} \). Here, \( \beta \) was set such that \( T_0(r_1) = 1.05 \); further, \( n = 1.25 \) and \( G = n \beta \). In the simulations, the Mach number of the flow was at most \( 3.7 \times 10^{-3} \). The density stratification was also small, being \( \rho(r_1) \approx 1.012 \). Time was normalized by the diffusion timescale \( \tau = d^2/\mu = d^2/\kappa \).

The Rayleigh number of an ideal gas depends on the radius \( c_p \) as

\[ Ra = \frac{g \left\{ -(dT/dr)/T - g/c_pT \right\} \alpha^4}{(\kappa/c_p \rho)(\mu/\rho)} = \frac{n \beta^2(c_p - n)\alpha^4}{\kappa \mu} f(r), \]

where \( c_p = \gamma/(\gamma - 1) \) is the specific heat. The radial factor \( f(r) = T(r)^{2n-3}/r^4 \) does not change greatly in the shell; \( f(r_o) = 1 \) and \( f(r_1) \approx 1.224 \). Below, we estimated \( Ra \) at the middle of the shell \( 24 \) at \( r = (r_o + r_1)/2 \) and denoted it as \( R \).

We discretized the right-hand sides of Eqs. (1)–(3) using a second-order finite difference method on a Yin-Yang grid \( 25 \). The total grid size was \( N_r \times N_\theta \times N_\phi = 60 \times 404 \times 1208 \times 2 \) in the radial \((r)\), colatitudinal \((\theta)\), and longitudinal \((\varphi)\) directions. The last factor 2 was for the Yin and Yang components. For numerical integration over time, we used a fourth-order explicit Runge-Kutta method.

We used VISMO-YY \( 26 \) to generate in-situ visualization images of the isosurfaces of radial velocity, that is, \( v_i(r, \theta, \varphi) = \pm \alpha \), where \( \alpha \) is constant. VISMO-YY is a parallelized open-source software rendering library that is specialized for the in-situ visualization of Yin-Yang grid simulations \( 27 \). The level of the isosurface \( \alpha \) was set to half the maximum radial velocity, \( \alpha = 0.5 \times \max\{|v_i|\} \), at each snapshot. The rising fluid \( (v_i = +\alpha) \) and sinking fluid \( (v_i = -\alpha) \) are respectively colored in orange and blue in the following images.

To apply the idea of Four-Dimensional Street View (4DSV) \( 28 \), that is, in-situ visualization with multiple viewpoints, we placed 10 visualization cameras, \( C_1, C_2, \ldots, C_{10} \), around the spherical shell. The distance from the origin to the cameras was \( r = 2.6 \). Cameras \( C_k (1 \leq k \leq 8) \) were placed on the “equator,” that is, at \( \theta = \pi/2 \) and \( \varphi = (k - 1)\pi/4 \). Cameras \( C_9 \) and \( C_{10} \) were located above the north and south poles, that is, at \( \theta = 0 \) and \( \pi \), respectively.

### III. CRITICAL RAYLEIGH NUMBER

A standard approach to spherical pattern formation is the stability analysis for each degree \( \ell \) of the spherical harmonics \( Y^n_\ell \). Zhang et al. \( 17 \) performed linear computations for convection in a thin spherical shell with radii ratio \( r_i/r_o \sim 0.8475 \) and found that the critical Rayleigh numbers \( R_c \) for \( \ell = 17, 18, 19, \) and 20 are 1723.5, 1710.7, 1712.4, and 1727.1, respectively. The \( R_c \) values are very close to each other. Because the spherical shell in our study \( (r_i/r_o = 0.945) \) is thinner than theirs, there would be more modes (having larger degree \( \ell \)) with close \( R_c \) values. The mixed existence of multiple unstable modes with large \( \ell \) values means that it is highly demanding to investigate the nature of the bifurcation for the onset of convection in our thin spherical shell. In addition to that, our numerical method, which is a point-based spatial discretization rather than the commonly used spectral method using spherical harmonics, makes the numerical stability analysis hard for each degree \( \ell \).

To find the critical Rayleigh number of this system, we performed parameter runs with different Rayleigh numbers \( R \) under random perturbations on the pressure in the initial condition as follows:

\[ p(r, \theta, \varphi) = p_0(r) + c p_1(\theta, \varphi) \sin \{ \pi(r - r_1)/d \}, \]
where $c$ is a small positive number. The perturbation profile $p_1$ is a linear combination of spherical harmonics.

$$p_1(\vartheta, \varphi) = \sum_{\ell=1}^{L_{\text{max}}} \sum_{m=0}^{\ell} \delta_{\ell m} \hat{P}_\ell^m(\vartheta, \varphi) \cos (m\varphi + d_{\ell m}),$$

(6)

where $L_{\text{max}} = 202$; $\hat{P}_\ell^m$ are normalized Legendre function; $\delta_{\ell m}$ are binary coefficient ($\delta_{\ell m} = 0$ or 1); and $d_{\ell m}$ are random phase between 0 and $2\pi$. We randomly selected 5% of all possible $(\ell, m)$ pairs and set $\delta_{\ell m} = 1$ for them and $\delta_{\ell m} = 0$ for the others. The constant $c$ in eq. (5) was specified after these random pickups so that the maximum amplitude of the resulting perturbation all over the shell, that is, $\max\{|c p_1(\vartheta, \varphi)|\}$, was $1.0 \times 10^{-3}$.

When we changed $\bar{R}$, we fixed $\beta$ and other constants in the numerator of the last term in eq. (4). In other words, we changed only the diffusivities $\mu(=\kappa)$ in these parameter runs.

![FIG. 1: Time developments of convection flow energy for three different Rayleigh numbers $\bar{R}$. Time was normalized by the diffusion time $\tau_d$. The dotted blue curve ($\bar{R} = 1712$) and dashed green curve ($\bar{R} = 1723$) show simulation results obtained starting from random perturbations. We assumed that the critical Rayleigh number $\bar{R}_c$ was the midpoint of the two $\bar{R}$ values. The solid magenta curve ($\bar{R} = 2209 = 1.29\bar{R}_c$) shows the simulation result obtained starting from a controlled initial condition.](image)

We performed several jobs to find the critical $\bar{R}$; Fig. 1 shows two decisive runs among these. In this figure, the horizontal axis represents the simulation time normalized by the diffusion time $\tau_d$, and the vertical axis represents the total energy of the convection flow. We first focus on the case of $\bar{R} = 1712$ (blue dotted line). The flow initiated by the random perturbation decays, or the fluid is stable. By contrast, in the case of $\bar{R} = 1723$ (green dashed line), the energy increases exponentially with time. These observations indicate that the critical Rayleigh number $\bar{R}_c$ is between these two values. Here, we assume that it is the midpoint, that is, $\bar{R}_c = (1712 + 1723)/2 = 1717.5$, which is close to the value of 1708 for convection in horizontal planes [29]. It is known that $\bar{R}_c$ in spherical thin shells becomes slightly larger than that in the plane layer convection [17].
FIG. 2: Time development of convection for $\bar{R} = 1.29 \bar{R}_c$ when initial condition is random. Time is presented on the diffusion timescale $\tau_d$ in the upper-right corner of each panel. From (d) to (f), the pattern slowly changes in time.

Fig. 2 shows snapshots of convection when $\bar{R} = 1.29 \bar{R}_c$ started from the random initial condition used to determine the critical Rayleigh number. The random cellular pattern observed in the very early stage in Figs. 2(a) and (b) is replaced by a set of unsteady rolls as shown in Figs. 2(c) to (f). It resembles the onset of spiral defect chaos in the plane layer convection at small Prandtl number [19–21]. The pattern is constantly moving and there is no sign of settling down to a steady state.

IV. INITIAL CONDITION

For the numerical demonstration of steady chiral convection, we adopted the controlled initial condition method in convection experiments [30, 31]. Our strategy was to specify a perturbation in the initial condition with chirality and find if it led to a steady solution without breaking the chirality.

For the initial condition, we constructed 12 Archimedean spirals with the same winding [blue curves in Fig. 3(a)] on a regular dodecahedron [red lines in Fig. 3(a)]. Next, we selected six adjacent pairs from the 12 faces of the dodecahedron and smoothly connected two spirals on each pentagon together. We called a pair of connected spirals a dipole [22].

Among the various possible combinations of the six pairs of pentagonal faces, we selected the special one shown in Fig. 3(a) that has a discrete rotational symmetry. A dodecahedron can be constructed by adding a “roof” to each face of a cube [32]. The rotational symmetry of the dipoles is much easier to understand if we observe the underlying cube with a spiral texture, as shown in Fig. 3(b).
FIG. 3: Design of initial condition with chirality. (a) Six pairs of Archimedean spirals (blue) were placed on 12 faces of a regular dodecahedron (red). (b) Discrete rotational symmetry of $T$ (tetrahedral) group, with four 3-fold rotations indicated by light blue triangles and three 2-fold rotations indicated by light blue ellipses.

The rotational symmetries of a plain cube partially disappear owing to the spiral texture. The remaining rotational symmetries of the texture shown in Fig. 3(b) are four 3-fold rotations with axes about the cube’s diagonal [indicated by light blue triangles in Fig. 3(b)] and three 2-fold rotations about axes perpendicular to square faces [indicated by light blue ellipses in Fig. 3(b)]. The dodecahedron with the spiral texture has the discrete rotational symmetry of the tetrahedral group $T$. $T$

We took the above $T$-symmetric dipole curves as the skeleton of a pressure perturbation $p_1(\vartheta, \varphi)$ in Eq. (5). We first mapped the dipole curves on the regular dodecahedron onto a unit sphere, and for each point $(\vartheta, \varphi)$ on the sphere, we found the distance $\delta$ to the closest dipole curve on the sphere from the point. We then specified the perturbation $p_1(\vartheta, \varphi)$ in terms of a Gaussian function of $\delta$. A free parameter in the configuration of the skeleton was the winding number $n$ of each spiral in a pentagon. Fig. 4 shows the $p_1$ profile when $n = 5$, which was used in all simulations described below. Depending on the winding of the spirals, there are two possible configurations that are mirror images of one another. A set of programs to calculate $p_1(\vartheta, \varphi)$ and to draw Fig. 4 is available at GitHub [33]. As in the case of random perturbations, the constant $c$ in eq. (5) was adjusted so that $\max\{|c p_1(\vartheta, \varphi)|\} = 1.0 \times 10^{-3}$.

![Figure 4](image)

FIG. 4: Pressure perturbation profile $p_1(\vartheta, \varphi)$ used in the controlled initial condition in this study.

V. CHIRAL PATTERN CONVECTION

We first present the simulation results for $\tilde{R} = 1.29\tilde{R}_c$. The chiral profile similar to the initial perturbation appeared in the convection flow, which becomes steady. Fig. 5 shows a sequence of snapshots taken by camera $C_1$ from $t = 0.136\tau_d$ to $t = 203.3\tau_d$. The viewing direction of $C_1$ is shown by the arrow in the diagrams in the upper-left,
in which the red, green, and blue lines denote x, y, and z axes, respectively, and the yellow solid below the gray sphere represents configuration of the regular dodecahedron used in the pressure perturbation.

The convection appeared according to the initial stripe pattern of the pressure perturbation as shown in Fig. 5(a) at \( t = 0.136 \tau_d \). Each pentagon’s spiral slowly rotated around its axis. In the initial phase, a more notable change was observed at the five corners around each pentagon, which correspond to the vertices of the original regular dodecahedron. The flow was initially absent at the corner regions before they were gradually filled with convection. The filling pattern in each corner seemed to have three-fold rotational symmetry in the early stage, as indicated by the three short blue bars around the small red point in Fig. 5(d). The three-fold rotational symmetry is still observed in Fig. 5(c) \( t = 2.71 \tau_d \), following which the corner slowly loses its three-fold symmetry (see Fig. 5(f), \( t = 13.6 \tau_d \)).

The convection reached almost the final pattern by \( t = 13.6 \tau_d \), although a slight adjustment of the whole pattern was still observed.

**FIG. 5:** Time development of convection when \( \bar{R} = 1.29 \bar{R}_c \). Time is presented on the diffusion timescale \( \tau_d \) in the upper-right corner of each panel. The convection reached the steady state by \( t = 67.8 \tau_d \). No shift or rotation of spiral arms was observed. Panels (a) to (i) show the convection started by the pressure perturbation shown in Fig. 4. Panel (j) shows a snapshot of another simulation started by the mirrored perturbation of Fig. 4.

Figs. 5(g)–(i) show the convection in the last two-thirds of the simulation time. The three panels appeared identical, which was true in views from other cameras. This indicated that the convection had reached a steady state. No rotation of the arms was observed, unlike the global or local spirals in the case of planar convections [34, 35]. The same was true of other steady solutions with different \( \bar{R} \), as described below.

The twelve spirals in the steady state had the same winding direction as the initial pattern of the pressure perturbation. We can expect that mirrored pattern with the opposite winding is also stable. We confirmed this by performing a simulation with the initial condition of pressure perturbation that is the mirror image of Fig. 4. The time development as well as the final steady state of the convection was the same, except that they had the opposite
winding. A snapshot in the final steady state is shown in Fig. 5(j) in the lower-left of the figure. The two final states shown in Fig. 5(j) and in Fig. 5(g) [or panels (h) and (i)] are mirror images one another.

Fig. 6 shows the isosurfaces of positive $v_r$ in the steady state when $\bar{R} = 1.29 \bar{R}_c$. Snapshots for in-situ visualization were taken at the same time ($t = 203.3 \tau_d$) from six different visualization cameras: $C_1$–$C_4$ for (a)–(d) and $C_9$ and $C_{10}$ for (e) and (f). The viewing direction of each camera is indicated by the arrow in the lower right in each panel. The spirals were located on the faces of a spherical dodecahedron, and the whole pattern kept rotational $T$-symmetry with the chiralities of the initial perturbation.

Starting from the same $p_1$ perturbation, we also performed simulations with different $\bar{R}$ values. The results are summarized in the upper part in Fig. 7. Black circles (a and f) correspond to unsteady, while white circles (b to e) correspond to steady convection. The steady solutions span a range of Rayleigh numbers, $1.29 \bar{R}_c \leq \bar{R} \leq 3.86 \bar{R}_c$. They have basically the same pattern, with slight variations in the pentagonal corners.

The lower six panels in Fig. 7 show convection patterns for different $\bar{R}$. All panels except Fig. 7(f) show snapshots taken at $t = 113 \tau_d$.

We first examine Fig. 7(a) for $\bar{R} = 1.09 \bar{R}_c$. The $T$-symmetric spirals on the regular dodecahedron, similar to the case of $\bar{R} = 1.29 \bar{R}_c$, grew initially but were just barely unstable. Ripple-like modes along the spiral arms appeared in Fig. 7(a). As the ripple grew, the rolls were broken and the convection pattern shifted to irregular cells.

Fig. 7(b) shows the steady solution for $\bar{R} = 1.29 \bar{R}_c$, that we have examined above. Fig. 7(c)–(e) also show solutions in the steady solution range.

The convection pattern under $\bar{R} = 4.50 \bar{R}_c$ was unstable, as shown in Fig. 7(f). The collapse of the pattern was so fast that we show a snapshot at $t = 12.2 \tau_d$ in this case.

The steady states shown in panels (b)–(e) indicate that the chiral pattern of six sets of spiral dipoles on a spherical dodecahedron is a stable solution in a nonrotating spherical shell in the Rayleigh number regime.
VI. CONCLUSION

Because of geometrical isotropy, Rayleigh-Bénard convection in a spherical vessel with central gravity is expected to exhibit symmetric patterns in terms of rotation. All three polyhedral groups, namely, $T$ (tetrahedral), $O$ (octahedral), and $I$ (icosahedral), are known to appear in the solutions of spherical shell convection.

We found a new type of chiral solution in a nonrotating spherical shell. The solution had discrete rotational symmetry of group $T$. The pattern consisted of six pairs of spiral rolls placed on 12 faces of a spherical dodecahedron. The solution kept chirality as well as rotational symmetry for Rayleigh numbers in the range of $\bar{R} = 1.29 \bar{R}_c$ to $3.86 \bar{R}_c$.

The chiral solution was found by using a carefully adjusted initial condition. Chiral patterns with discrete rotational symmetry of the $O$ or $I$ group might exist; however, we have not yet explored this possibility. Matthews [10] used the bifurcation theory and showed that $I$-symmetry is preferred in pattern formations on a sphere in general. An $I$-symmetric chiral solution could possibly be constructed using the same kind of controlled initial condition method adopted in the present study.

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