NECESSARY AND SUFFICIENT CONDITIONS FOR OSCILLATION OF SOLUTIONS TO SECOND-ORDER NEUTRAL DIFFERENTIAL EQUATIONS WITH IMPULSES

SHYAM SUNDAR SANTRA

Department of Mathematics, JIS College of Engineering, Kalyani, Nadia, West Bengal, INDIA

ABSTRACT. In this work, necessary and sufficient conditions for oscillation of solutions of second-order neutral impulsive differential system

\[
\begin{align*}
&\left( r(t)(z'(t))^\gamma \right)' + q(t)x^\alpha(\sigma(t)) = 0, \quad t \geq t_0, \quad t \neq \lambda_k, \\
&\Delta (r(\lambda_k)(z'(\lambda_k))^\gamma) + h(\lambda_k)x^\alpha(\sigma(\lambda_k)) = 0, \quad k \in \mathbb{N}.
\end{align*}
\]

are established, where

\[ z(t) = x(t) + p(t)x(\tau(t)). \]

Under the assumption \( \int_{-\infty}^{\infty} (r(\eta))^{-1/\alpha} \, d\eta = \infty \), two cases when \( \gamma > \alpha \) and \( \gamma < \alpha \) are considered. The main tool is Lebesgue’s Dominated Convergence theorem. Examples are given to illustrate the main results, and state an open problem.

1. Introduction

Consider the neutral impulsive differential system

\[
\begin{align*}
&\left( r(t)(z'(t))^\gamma \right)' + q(t)x^\alpha(\sigma(t)) = 0, \quad t \geq t_0, \quad t \neq \lambda_k, \\
&\Delta (r(\lambda_k)(z'(\lambda_k))^\gamma) + h(\lambda_k)x^\alpha(\sigma(\lambda_k)) = 0, \quad k \in \mathbb{N},
\end{align*}
\]

where

\[ z(t) = x(t) + p(t)x(\tau(t)), \quad \Delta x(a) = \lim_{s \to a^+} x(s) - \lim_{s \to a^-} x(s), \]

© 2020 Mathematical Institute, Slovak Academy of Sciences.
2010 Mathematics Subject Classification: 34K, 34C10, 34K11.
Keywords: Oscillation, non-oscillation, neutral, delay, Lebesgue’s Dominated Convergence theorem, impulses.
Licensed under the Creative Commons Attribution-NC-ND4.0 International Public License.
there exists a differentiable function $\sigma$ that satisfies 0 $< \lambda_1 < \lambda_2 < \ldots$ as $k \to \infty$; and $\gamma$ and $\alpha$ are the quotient of two odd positive integers.

(A1) $\sigma \in C([0, \infty), \mathbb{R}_+)$, $\tau \in C^2([0, \infty), \mathbb{R}_+)$, $\sigma(t) < t$, $\tau(t) < t$, $\lim_{t \to \infty} \sigma(t) = \infty$, $\lim_{t \to \infty} \tau(t) = \infty$.

(A2) $r \in C^1([0, \infty), \mathbb{R}_+)$, $q, h \in C([0, \infty), \mathbb{R}_+)$; $0 < r(t)$, $0 \leq q(t)$, $0 \leq h(t)$, for all $t \geq 0$; $q(t)$ is not identically zero in any interval $[b, \infty)$.

(A3) $\int_0^{\infty} r^{-1/\gamma}(s) \, ds = \infty$; let $\Pi(t) = \int_0^t r^{-1/\gamma}(\eta) \, d\eta$.

(A4) $-1 < -p_0 \leq p(t) \leq 0$ for $t \geq t_0$.

(A5) there exists a differentiable function $\sigma_0(t)$ such that $0 < \sigma_0(t) \leq \sigma(t)$ and $\sigma_0'(t) \geq \alpha$ for $t \geq t^*$, $\alpha > 0$.

The main feature of this article is having conditions that are both necessary and sufficient for the oscillation of all solutions to (1.1). Sufficient conditions for the oscillation and nonoscillation of all solutions to the first and second order neutral impulsive differential systems are provided in [12, 15, 21, 29–32]. The necessary and sufficient conditions for oscillation of all solutions to the first order neutral impulsive differential systems are discussed in [30, 31]. In this work, our main aim is to present the necessary and sufficient conditions for oscillation of all solutions to (1.1).

In 2011, Dimitrova and Donev [13–15] considered the first order impulse differential system of the form

$$
\begin{align*}
\begin{cases}
(x(t) + p(t)x(t)\tau(t))' + q(t)x(\sigma(t)) = 0, & t \neq \lambda_k, \ k \in \mathbb{N}, \\
\Delta(x(\lambda_k) + p(\lambda_k)x(\tau(\lambda_k))) + q(\lambda_k)x(\sigma(\lambda_k)) = 0, & k \in \mathbb{N}
\end{cases}
\end{align*}
$$

(1.2)

and established several sufficient conditions for oscillation of the solutions of (1.2).

In 2014, Tripathy [29] established sufficient conditions for oscillation of all solutions of

$$
\begin{align*}
\begin{cases}
(x(t) + p(t)x(t)\tau(t))' + q(t)f(x(t-\sigma)) = 0, & t \neq \lambda_k, \ k \in \mathbb{N}, \\
\Delta(x(\lambda_k) + p(\lambda_k)x(\tau(\lambda_k - \tau)) + q(\lambda_k)x(\sigma(\lambda_k - \sigma))) = 0, & k \in \mathbb{N}
\end{cases}
\end{align*}
$$

(1.3)

In 2015, Tripathy and Santra [30] obtained the necessary and sufficient conditions for oscillatory and asymptotic behavior of solutions of

$$
\begin{align*}
\begin{cases}
(x(t) + p(t)x(t)\tau(t))' + q(t)f(x(t-\sigma)) = g(t), & t \neq \lambda_k, \ k \in \mathbb{N}, \\
\Delta(x(\lambda_k) + p(\lambda_k)x(\lambda_k - \tau)) + q(\lambda_k)f(x(\lambda_k - \sigma)) = h(\lambda_k), & k \in \mathbb{N}
\end{cases}
\end{align*}
$$
In 2016, Tripathy, Santra and Pinelas [31] obtained necessary and sufficient conditions of (1.1). In the subsequent year, Tripathy and Santra [32] established sufficient conditions for oscillation and existence of positive solutions of
\[
\begin{align*}
\left\{ (r(t) (x(t) + p(t) x(t-\tau)))' + q(t) f(x(t-\sigma)) = 0, \quad t \neq \lambda_k, \ k \in \mathbb{N}, \\
\Delta (\lambda_k) (x(\lambda_k) + p(\lambda_k) x(\lambda_k-\tau))' + q(\lambda_k) f(x(\lambda_k-\sigma)) = 0, \quad k \in \mathbb{N}.
\end{align*}
\]

In 2018, Santra [21] established sufficient conditions for oscillations of solutions of
\[
\begin{align*}
\left\{ (r(t) (x(t) + p(t) x(t-\tau)))' + q(t) f(x(t-\sigma)) = 0, \quad t \neq \lambda_k, \ k \in \mathbb{N}, \\
\Delta (\lambda_k) (x(\lambda_k) + p(\lambda_k) x(\lambda_k-\tau))' + q(\lambda_k) f(x(\lambda_k-\sigma)) = 0, \quad k \in \mathbb{N}.
\end{align*}
\]

By a solution \(x\) we mean a function differentiable on \([t_0, \infty)\) such that \(z(t)\) and \(z'(t)\) are differentiable for \(t \neq \lambda_k\), and \(z(t)\) is left continuous at \(\lambda_k\) and has right limit at \(\lambda_k\), and \(x\) satisfies (1.1). We restrict our attention to solutions for which \(\sup_{t \geq b} |x(t)| > 0\) for every \(b \geq 0\). A solution is called oscillatory if it has arbitrarily large zeros; otherwise is non-oscillatory.

To define a particular solution, we need an initial function \(\phi(t)\) which is twice differentiable for \(t\) in the interval
\[
\min \{ \inf \{ \tau(t) : t_0 \leq t \}, \inf \{ \sigma(t) : t_0 \leq t \} \} \leq t.
\]
Then a solution is obtained using the method of steps: When replacing \(x(\tau(t))\) by \(\phi(\tau(t))\), and \(x(\sigma(t))\) by \(\phi(\sigma(t))\) in (1.1), we obtain a second-order differential equation. We solve this equation by taking into account discrete equation of (1.1), let say on an interval \([t_0, t_1]\). Then we repeat the process starting at \(t = t_1\).

2. Necessary and Sufficient Conditions

**Lemma 2.1.** Assume that (A1)–(A4) hold for \(t \geq t_0\). If \(x\) is an eventually positive solution of (1.1), then \(z\) satisfies any one of the following two cases:

(i) \(z(t) < 0\), \(z'(t) > 0\), \((r(z'))' (t) \leq 0\);

(ii) \(z(t) > 0\), \(z'(t) > 0\), \((r(z'))' (t) \leq 0\)

for all sufficiently large \(t\).

**Proof.** Let \(x\) be an eventually positive solution. Then by (A1) there exists a \(t^*\) such that \(x(t) > 0\), \(x(\tau(t)) > 0\) and \(x(\sigma(t)) > 0\) for all \(t \geq t^*\). From (1.1) it
follows that
\[
\left( r(t)(z'(t))^\gamma \right)' = -q(t)x^\alpha(\sigma(t)) \leq 0 \quad \text{for } t \neq \lambda_k,
\]
\[
\Delta \left( r(\lambda_k)(z'(\lambda_k))^\gamma \right) = -h(\lambda_k)x^\alpha(\sigma(\lambda_k)) \leq 0 \quad \text{for } k \in \mathbb{N}.
\] (2.1)

Therefore, \( r(t)(z'(t))^\gamma \) is non-increasing for \( t \geq t^* \), including jumps of discontinuity. Next we show the \( r(t)(z'(t))^\gamma \) is positive. By contradiction assume that \( r(t)(z'(t))^\gamma \leq 0 \) at a certain time \( t \geq t^* \). Using that \( q \) is not identically zero on any interval \([b, \infty)\), and by (2.1), there exists \( t_2 \geq t^* \) such that
\[
r(t)(z'(t))^\gamma \leq r(t_2)(z'(t_2))^\gamma < 0 \quad \text{for all } t \geq t_2.
\]
Recall that \( \gamma \) is the quotient of two positive odd integers. Then
\[
z'(t) \leq \left( \frac{r(t_2)}{r(t)} \right)^{1/\gamma} z'(t_2) \quad \text{for } t \geq t_2.
\]
Since \( r(\lambda_k)(z'(\lambda_k))^\gamma \leq r(t_2)(z'(t_2))^\gamma < 0 \) for all \( \lambda_k \geq t_2 \). Integrating from \( t_2 \) to \( t \), we have
\[
z(t) \leq z(t_2) + \sum_{t_2 \leq \lambda_k < \infty} z'(\lambda_k) + (r(t_2))^{1/\gamma} z'(t_2) (\Pi(t) - \Pi(t_2))
\]
\[
\leq z(t_2) + (r(t_2))^{1/\gamma} z'(t_2) (\Pi(t) - \Pi(t_2)) \to -\infty
\]
as \( t \to \infty \) due to (A3). Now, we consider the following two possibilities.

If \( x \) is unbounded, then there exists a sequence \( \{\eta_k\} \to \infty \) such that
\[
x(\eta_k) = \sup \{x(\eta) : \eta \leq \eta_k\}.
\]
By \( \tau(\eta_k) \leq \eta_k \), we have \( x(\tau(\eta_k)) \leq x(\eta_k) \) and hence
\[
z(\eta_k) = x(\eta_k) + p(\eta_k)x(\tau(\eta_k)) \geq (1 + p(\eta_k))x(\eta_k) \geq (1 - p_0)x(\eta_k) \geq 0,
\]
which contradicts \( \lim_{k \to \infty} z(t) = -\infty \). Recall that \( \{\lambda_k\} \) is the sequence of points for \( t \geq \lambda_k \), then by similar argument we can show that \( z(\lambda_k) \geq 0 \) to get a contradiction to \( \lim_{k \to \infty} z(t) = -\infty \). Therefore \( r(t)(z'(t))^\gamma > 0 \) for all \( t \geq t^* \).

If \( x \) is bounded, then \( z \) is also bounded, which is a contradiction to
\[
\lim_{k \to \infty} z(t) = -\infty.
\]

From \( r(t)(z'(t))^\gamma > 0 \) and \( r(t) > 0 \), it follows that \( z'(t) > 0 \). Then there is \( t_1 \geq t^* \) such that \( z \) satisfies only one of two cases (i) and (ii). This completes the proof. □
Oscillation of solutions to second-order neutral differential equ.

**Lemma 2.2.** Assume that (A1)–(A4) hold. If \( x \) is an eventually positive solution of (1.1), then any one of following two cases exists:

1. if \( z \) satisfies (i), \( \lim_{t \to \infty} x(t) = 0 \);
2. if \( z \) satisfies (ii), there exist \( t_1 \geq t_0 \) and \( \delta > 0 \) such that

\[
0 < z(t) \leq \delta \Pi(t),
\]

\[
(\Pi(t) - \Pi(t_1)) \left[ \int_t^\infty q(\zeta)x^\alpha(\sigma(\zeta)) \, d\zeta + \sum_{\lambda_k \geq t} h(\lambda_k)x^\alpha(\sigma(\lambda_k)) \right]^{1/\gamma} \leq z(t) \leq x(t), \quad \text{for all } t \geq t_1.
\]

**Proof.** Let \( x \) be an eventually positive solution. Then by (A1) there exist \( t^* \) such that \( x(t) > 0, x(\tau(t)) > 0 \) and \( x(\sigma(t)) > 0 \) for all \( t \geq t^* \). Then Lemma 2.1 holds and we have following two possible cases.

**Case 1:** Let \( z \) satisfies (i) for all \( t \geq t_1 \). Note that \( \lim_{t \to \infty} z(t) \) exists and by (A1), \( \limsup_{t \to \infty} x(t) = \limsup_{t \to \infty} x(\tau(t)) \). Then \( 0 > z(t) \geq x(t) - p_0 x(\tau(t)) \) implies

\[
0 \geq \lim_{t \to \infty} z(t) \geq \lim_{t \to \infty} \left[ x(t) - p_0 x(\tau(t)) \right] \geq (1 - p_0) \limsup_{t \to \infty} x(t).
\]

Since \( (1 - p_0) > 0 \), it follows that \( \limsup_{t \to \infty} x(t) = 0 \); hence \( \lim_{t \to \infty} x(t) = 0 \) for \( t \neq \lambda_k, k \in \mathbb{N} \). We may note that \( \{x(\lambda_k - 0)\}_{k \in \mathbb{N}} \) and \( \{x(\lambda_k + 0)\}_{k \in \mathbb{N}} \) are sequences of real numbers, and because of continuity of \( x \)

\[
\lim_{k \to \infty} x(\lambda_k - 0) = 0 = \lim_{k \to \infty} x(\lambda_k + 0)
\]

due to \( \liminf_{t \to \infty} x(t) = 0 = \limsup_{t \to \infty} x(t) \). Hence, \( \lim_{t \to \infty} x(t) = 0 \) for all \( t \) and \( \lambda_k, k \in \mathbb{N} \).

**Case 2:** Let \( z \) satisfies (ii) for all \( t \geq t_1 \). Note that \( x(t) \geq z(t) \) and \( z \) is positive and increasing so \( x \) cannot converge to zero. From \( r(t)(z'(t))^\gamma \) being non-increasing, there exist a constant \( \delta > 0 \) and \( t \geq t_1 \) such that \( (r(t))^{1/\gamma}z'(t) \leq \delta \), and hence \( z(t) \leq \delta \Pi(t) \) for \( t \geq t_1 \).

Since \( r(t)(z'(t))^\gamma \) is positive and non-increasing, \( \lim_{t \to \infty} r(t)(z'(t))^\gamma \), exists and is non-negative. Integrating (1.1) from \( t \) to \( a \), we have

\[
r(a)(z'(a))^\gamma - r(t)(z'(t))^\gamma = - \int_t^a q(\eta)x^\alpha(\sigma(\eta)) \, d\eta + \sum_{t \leq \lambda_k < a} \Delta(r(\lambda_k)z'(\lambda_k))^\gamma.
\]

Computing the limit as \( a \to \infty \),

\[
r(t)(z'(t))^\gamma \geq \int_t^\infty q(\eta)x^\alpha(\sigma(\eta)) \, d\eta + \sum_{\lambda_k \geq t} h(\lambda_k)x^\alpha(\sigma(\lambda_k)). \tag{2.4}
\]

161
Then
\[ z'(t) \geq \left[ \frac{1}{r(t)} \left( \int_t^\infty q(\eta)x^\alpha(\sigma(\eta)) \, d\eta + \sum_{t \leq \lambda_k} h(\lambda_k)x^\alpha(\sigma(\lambda_k)) \right) \right]^{1/\gamma}. \]
Since \( z(t_1) > 0 \), integrating the above inequality yields
\[ z(t) \geq \int_{t_1}^t \left[ \frac{1}{r(\eta)} \left( \int_\eta^\infty q(\zeta)x^\alpha(\sigma(\zeta)) \, d\zeta + \sum_{\eta \leq \lambda_k} h(\lambda_k)x^\alpha(\sigma(\lambda_k)) \right) \right]^{1/\gamma} \, d\eta. \]
Since the integrand is positive, we can increase the lower limit of integration from \( s \) to \( t \), and then use the definition of \( \Pi(t) \) to obtain
\[ z(t) \geq (\Pi(t) - \Pi(t_1)) \left[ \int_t^\infty q(\zeta)x^\alpha(\sigma(\zeta)) \, d\zeta + \sum_{t \leq \lambda_k} h(\lambda_k)x^\alpha(\sigma(\lambda_k)) \right]^{1/\gamma}, \]
which yields \((2.3)\). \( \square \)

2.1. The Case \( \alpha < \gamma \).

In this subsection, we assume that there exists a constant \( \beta_1 \), the quotient of two positive odd integers such that \( 0 < \alpha < \beta_1 < \gamma \).

**Theorem 2.1.** Under assumptions (A1)–(A4), each solution of \((1.1)\) is either oscillatory or converges to zero if and only if
\[ \int_0^\infty q(\eta)\Pi^\alpha(\sigma(\eta)) \, d\eta + \sum_{k=1}^\infty h(\lambda_k)\Pi^\alpha(\sigma(\lambda_k)) = \infty. \] (2.5)

**Proof.** We prove the sufficiency by contradiction. Initially, we assume that a solution \( x \) is eventually positive which does not converge to zero. So, Lemma 2.1 holds and \( z \) satisfies any one of two cases (i) and (ii). In Lemma 2.2, Case 1 leads to \( \lim_{t \to \infty} x(t) = 0 \) which is a contradiction.

For Case 2, we can find \( t_1 > 0 \) such that
\[ x(t) \geq z(t) \geq (\Pi(t) - \Pi(t_1)) \frac{1}{2} R(t) \geq 0 \quad \text{for } t \geq t_1, \]
where
\[ w(t) = \int_t^\infty q(\zeta)x^\alpha(\sigma(\zeta)) \, d\zeta + \sum_{\lambda_k \geq t} h(\lambda_k)x^\alpha(\sigma(\lambda_k)) \geq 0. \]
As \( \lim_{t \to \infty} \Pi(t) = \infty \), there exists \( t_2 \geq t_1 \), such that \( \Pi(t) \geq \frac{1}{2} R(t) \) for \( t \geq t_2 \) and hence
\[ z(t) \geq \frac{1}{2} \Pi(t) w^{1/\gamma}(t). \] (2.6)
Note that \( w \) is left continuous at \( \lambda_k \),
\[
    w'(t) = -q(t)x^\alpha(\sigma(t)) \quad \text{for } t \neq \lambda_k, \\
    \Delta w(\lambda_k) = -h(\lambda_k)x^\alpha(\sigma(\lambda_k)) \leq 0.
\]
Thus \( w \) is non-negative and non-increasing for \( t \geq t_2 \). Using (2.2), \( \alpha - \beta_1 < 0 \) and (2.6), we have
\[
x^\alpha(t) \geq z^{\alpha-\beta_1}(t)z^{\beta_1}(t) \geq (\delta \Pi(t))^{\alpha-\beta_1}z^{\beta_1}(t) \\
    \geq (\delta \Pi(t))^{\alpha-\beta_1} \left( \frac{\Pi(t)w^{1/\gamma}(t)}{2} \right)^{\beta_1} = \frac{\delta^{\alpha-\beta_1}}{2^{\beta_1}} \Pi^\alpha(t)w^{1/\gamma}(t) \quad \text{for } t \geq t_2.
\]
Since \( w \) is non-increasing, \( \beta_1/\gamma > 0 \), and \( \sigma(\eta) < \eta \), it follows that
\[
x^\alpha(\sigma(\eta)) \geq \frac{\delta^{\alpha-\beta_1}}{2^{\beta_1}} \Pi^\alpha(\sigma(\eta))w^{1/\gamma}(\sigma(\eta)) \geq \frac{\delta^{\alpha-\beta_1}}{2^{\beta_1}} \Pi^\alpha(\sigma(\eta))w^{1/\gamma}(\eta).
\]
Now, we have
\[
    \left( w^{1-\beta_1/\gamma}(t) \right)' = \left( 1 - \frac{\beta_1}{\gamma} \right) w^{-\beta_1/\gamma}(t) \left( -q(t)x^\alpha(\sigma(t)) \right) \quad \text{for } t \neq \lambda_k. \tag{2.7}
\]
To estimate the discontinuities of \( w^{1-\beta_1/\gamma} \) we use a Taylor polynomial of order 1 for the function \( h(x) = x^{1-\beta_1/\gamma} \), with \( 0 < \beta_1 < \gamma \), about \( x = a \):
\[
b^{1-\beta_1/\gamma} - a^{1-\beta_1/\gamma} \leq \left( 1 - \frac{\beta_1}{\gamma} \right) a^{-\beta_1/\gamma}(b - a).
\]
Then \( \Delta w^{1-\beta_1/\gamma}(\lambda_k) \leq (1 - \frac{\beta_1}{\gamma}) w^{-\beta_1/\gamma}(\lambda_k) \Delta w(\lambda_k) \). Integrating (2.7) from \( t_2 \) to \( t \), we have
\[
    w^{1-\beta_1/\gamma}(t_2) \geq \left( 1 - \frac{\beta_1}{\gamma} \right) \left[ -\int_{t_2}^{t} w^{-\beta_1/\gamma}(\eta)w'(\eta) \, d\eta - \sum_{t_2 \leq \lambda_k < t} w^{-\beta_1/\gamma}(\lambda_k)\Delta w(\lambda_k) \right] \\
    = \left( 1 - \frac{\beta_1}{\gamma} \right) \left[ \int_{t_2}^{t} w^{-\beta_1/\gamma}(\eta)\left( q(\eta)x^\alpha(\sigma(\eta)) \right) \, d\eta \right. \\
    \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad + \left. \sum_{t_2 \leq \lambda_k < t} w^{-\beta_1/\gamma}(\lambda_k)h(\lambda_k)x^\alpha(\sigma(\lambda_k)) \right] \\
    \geq \left( 1 - \frac{\beta_1}{\gamma} \right) \frac{1}{2^\beta_1 \delta^{\beta_1-\alpha}} \left[ \int_{t_2}^{t} q(\eta)\Pi^\alpha(\sigma(\eta)) \, d\eta + \sum_{t_2 \leq \lambda_k < t} h(\lambda_k)\Pi^\alpha(\sigma(\lambda_k)) \right],
\]
which contradicts (2.5) as \( t \to \infty \) and completes the proof of sufficiency for eventually positive solutions. For an eventually negative solution \( x \), we introduce the variables \( y = -x \) so that we can apply the above process for the solution \( y \).
SHYAM SUNDAR SANTRA

For an eventually negative solution $x$, we introduce the variables $y = -x$ so
that we can apply the above process for the solution $y$.

Next, we show the necessity part by a contrapositive argument. Let \((2.5)\) do
not hold. Then, it is possible to find $t_1 > 0$ such that

$$
\int_{\eta}^{\infty} q(\zeta) \Pi^\alpha(\sigma(\zeta)) \, d\zeta + \sum_{\lambda_k \geq \eta} h(\lambda_k) \Pi^\alpha(\sigma(\lambda_k)) \leq \epsilon / \delta^\alpha
$$

(2.8)

for all $\eta \geq t_1$ and $\delta, \epsilon > 0$ satisfying the relation

$$(2\epsilon)^{1/\gamma} = (1 - p_0) \delta,$$

(2.9)

so that $0 < \epsilon^{1/\gamma} \leq (1 - p_0) \delta / 2^{1/\gamma} < \delta$. Define the set of continuous functions

$$M = \{ x \in C([0, \infty)) : \epsilon^{1/\gamma}(\Pi(t) - \Pi(t_1)) \leq x(t) \leq \delta(\Pi(t) - \Pi(t_1)), \ t \geq t_1 \}$$

and define an operator $\Phi$ on $M$ by

$$(\Phi x)(t) = \begin{cases} 0 & \text{if } t \leq t_1, \\ -p(t)x(\tau(t)) + \int_{t_1}^{t} \left[ \frac{1}{r(\eta)} \left[ \epsilon + \int_{\eta}^{\infty} q(\zeta)x^\alpha(\sigma(\zeta)) \, d\zeta + \sum_{\lambda_k \geq \eta} h(\lambda_k)x^\alpha(\sigma(\lambda_k)) \right]^{1/\gamma} \right] \, d\eta & \text{if } t > t_1. \end{cases}$$

We need to show that if $x$ is a fixed point of $\Phi$, i.e. $\Phi x = x$, then $x$ is a solution

of (1.1).

First we estimate $(\Phi x)(t)$ from below. For $x \in M$, we have $0 \leq \epsilon^{1/\gamma}(\Pi(t) - \Pi(t_1)) \leq x(t)$ and by (A2) and (A3) we have

$$(\Phi x)(t) \geq 0 + \int_{t_1}^{t} \left[ \frac{1}{r(\eta)} [\epsilon + 0 + 0] \right]^{1/\gamma} \, d\eta = \epsilon^{1/\gamma}(\Pi(t) - \Pi(t_1)).$$

Now we estimate $(\Phi x)(t)$ from above. For $x$ in $M$, by definition of the set $M$, we have $x^\alpha(\sigma(\eta)) \leq (\delta \Pi(\sigma(\eta)))^\alpha$. Therefore, by (2.8),

$$(\Phi x)(t) \leq p_0 \delta(\Pi(t) - \Pi(t_1)) + \int_{t_1}^{t} \left[ \frac{1}{r(\eta)} \left[ \epsilon + \delta^\alpha \int_{\eta}^{\infty} q(\zeta) \Pi^\alpha(\sigma(\zeta)) \, d\zeta + \delta^\alpha \sum_{\lambda_k \geq \eta} h(\lambda_k) \Pi^\alpha(\sigma(\lambda_k)) \right]^{1/\gamma} \right] \, d\eta$$

$$\leq p_0 \delta(\Pi(t) - \Pi(t_1)) + (2\epsilon)^{1/\gamma}(\Pi(t) - \Pi(t_1)) = \delta(\Pi(t) - \Pi(t_1)).$$

Therefore, $\Phi$ maps $M$ to $M$.  

164
To find a fixed point for $\Phi$ in $M$, let us define a sequence of functions in $M$ by the recurrence relation

$$u_0(t) = 0 \quad \text{for } t = 0,$$

$$u_1(t) = (\Phi u_0)(t) = \begin{cases} 0 & \text{if } t < t_1, \\ e^{1/\gamma} (\Pi(t) - \Pi(t_1)) & \text{if } t \geq t_1, \end{cases}$$

$$u_{n+1}(t) = (\Phi u_n)(t) \quad \text{for } n \geq 1, \ t \geq t_1.$$

Note that for each fixed $t$, we have $u_1(t) \geq u_0(t)$. Using mathematical induction, we can show that $u_{n+1}(t) \geq u_n(t)$. Therefore, the sequence $\{u_n\}$ converges pointwise to a function $u$. Using the Lebesgue dominated convergence theorem, we can show that $u$ is a fixed point of $\Phi$ in $M$. This shows under assumption (2.8), there is non-oscillatory solution that does not converge to zero.

**Corollary 2.1.** Under the assumptions of Theorem 2.1, every unbounded solution of (1.1) is oscillatory if and only if (2.5) holds.

**Proof.** The proof of the corollary is an immediate consequence of Theorem 2.1.

2.2. The Case $\alpha > \gamma$.

In this subsection, we assume that there exists a constant $\beta_2$, the quotient of two positive odd integers such that $\gamma < \beta_2 < \alpha$.

**Theorem 2.2.** Under assumptions (A1)–(A5) and $r(t)$ is non-decreasing, every solution of (1.1) is either oscillatory or converges to zero if and only if

$$\int_0^\infty \frac{1}{r(\eta)} \left[ \int_\eta^\infty q(\zeta) \, d\zeta + \sum_{k=1}^\infty h(\lambda_k) \right]^{1/\gamma} \, d\eta = \infty. \quad (2.10)$$

**Proof.** We prove the sufficiency by contradiction. Initially, we assume that $x$ is an eventually positive solution not converging to zero. So, Lemma 2.1 holds and $z$ satisfies any one of two cases (i) and (ii). In Lemma 2.2 Case 1 leads to $\lim_{t \to \infty} x(t) = 0$ which is a contradiction.

For Case 2, $z(t) > 0$ is non-decreasing for $t \geq t_1$ and

$$x^\alpha(t) \geq z^\alpha(t) \geq z^{\alpha-\beta_2}(t) z^{\beta_2}(t) \geq z^{\alpha-\beta_2}(t_1) z^{\beta_2}(t)$$

implies that

$$x^\alpha(\sigma(t)) \geq z^{\alpha-\beta_2}(t_1) z^{\beta_2}(\sigma(t)) \quad \text{for } t \geq t_2 > t_1. \quad (2.11)$$

Using (2.4), (2.11) and $\sigma(t) \geq \sigma_0(t)$, we have

$$r(t) \left( z'(t) \right)^\gamma \geq z^{\alpha-\beta_2}(t_1) \left[ \int_t^\infty q(\eta) \, d\eta + \sum_{\lambda_k \geq t} h(\lambda_k) \right] z^{\beta_2}(\sigma_0(t)) \quad \text{for } t \geq t_2. \quad (2.12)$$
Being \( r(t)(z'(t))^\gamma \) non-increasing and \( \sigma_0(t) \leq t \), we have
\[
r(\sigma_0(t))(z'(\sigma_0(t)))^\gamma \geq r(t)(z'(t))^\gamma.
\]
Using the last inequality in (2.12) and then dividing by \( z_2^\beta (\sigma_0(t)) > 0 \), we get
\[
\frac{z'(\sigma_0((t)))}{z_2^\beta (\sigma_0(t))} \geq \frac{z_0^\alpha - \beta_2 (t_1)}{r(\sigma_0(t))} \left[ \int_{t}^{\infty} q(\eta) \, d\eta + \sum_{\lambda_k \geq t} h(\lambda_k) \right]^{1/\gamma} \text{ for } t \geq t_2.
\]
Multiplying the left-hand side by \( \sigma'_0(t)/\alpha \geq 1 \) and integrating from \( t_1 \) to \( t \),
\[
\frac{1}{\alpha} \int_{t_1}^{t} \frac{z'(\sigma_0(\eta))\sigma'_0(\eta)}{z_2^\beta (\sigma_0(\eta))} \, d\eta \geq \frac{z^{(\alpha - \beta_2)/\gamma}(t_1)}{r(\sigma_0(\eta))} \int_{t_1}^{t} \left[ \int_{\eta}^{\infty} q(\zeta) \, d\zeta + \sum_{\eta \leq \lambda_k} h(\lambda_k) \right]^{1/\gamma} \, d\eta \text{ for } t \geq t_2.
\]

(2.13)

Since \( \gamma < \beta_2 \), \( r(\sigma_0(\eta)) \leq r(\eta) \) and
\[
\frac{1}{\alpha(1 - \beta_2/\gamma)} \left[ z_1 - \beta_2 (\sigma_0(\eta)) \right]^{t_{\eta=t_2}} \leq \frac{1}{\alpha(\beta_2/\gamma - 1)} z_1 - \beta_2 (\sigma_0(t_2)),
\]
then (2.13) becomes
\[
\int_{t_1}^{t} \left[ \int_{\eta}^{\infty} q(\zeta) \, d\zeta + \sum_{\eta \leq \lambda_k} h(\lambda_k) \right]^{1/\gamma} \, d\eta < \infty,
\]
which is a contradiction to (2.10). This contradiction implies that the solution \( x \) cannot be eventually positive. Eventually negative solution is similar.

To prove the necessity part, we assume that (2.10) does not hold. For given
\[
\epsilon = \left( \frac{2}{1 - p_0} \right)^{1/\gamma} > 0,
\]
we can find a \( t_1 > 0 \) such that
\[
\int_{t_1}^{\infty} \left[ \int_{\eta}^{\infty} q(\zeta) \, d\zeta + \sum_{\lambda_k \geq s} h(\lambda_k) \right]^{1/\gamma} \, d\eta < \epsilon. \quad (2.14)
\]
Consider
\[
M = \left\{ x \in C([0, \infty)) : 1 \leq x(t) \leq \frac{2}{1 - p_0} \text{ for } t \geq t_1 \right\}.
\]
OSCILLATION OF SOLUTIONS TO SECOND-ORDER NEUTRAL DIFFERENTIAL EQU.

Define the operator

\[
(\Phi x)(t) = \begin{cases} 
0 & \text{if } t < t_1, \\
1 - p(t)x(\tau(t)) & \text{if } t \geq t_1,
\end{cases}
\]

\[
+ \int_{t_1}^t \left[ \frac{1}{r(\eta)} \int_\eta^\infty q(\zeta)x^\alpha (\sigma(\zeta)) \, d\zeta \\
+ \sum_{\lambda_k \geq \eta} h(\lambda_k)x^\alpha (\sigma(\lambda_k)) \right] \frac{1}{\gamma} \, d\eta
\]

Indeed, \( \Phi x = x \) implies that \( x \) is a solution of (1.1).

First, we estimate \( (\Phi x)(t) \) from below. Let \( x \in M \). Then \( 1 \leq x \) implies that \( (\Phi x)(t) \geq 1 \), on \([t_1, \infty)\). Estimating \( (\Phi x)(t) \) from above. Let \( x \in M \). Then \( x \leq 2/(1 - p_0) \) and thus

\[
(\Phi x)(t) \leq 1 - p(t) \frac{2}{1 - p_0} + \int_{t_1}^t \left[ \frac{1}{r(\eta)} \int_\eta^\infty q(\zeta) \left( \frac{2}{1 - p_0} \right)^\alpha \, d\zeta \\
+ \sum_{\lambda_k \geq \eta} h(\lambda_k) \left( \frac{2}{1 - p_0} \right)^\alpha \right] \frac{1}{\gamma} \, d\eta.
\]

Since \( \sigma_0(\eta) \leq \eta \) and \( r(\cdot) \) is non-decreasing, we can replace \( r(\eta) \) by \( r(\sigma_0(\eta)) \) and the above inequality is still valid. By (2.14) and the definition of \( \epsilon \), we have

\[
(\Phi x)(t) \leq 1 + \frac{2p_0}{1 - p_0} + \left( \frac{2}{1 - p_0} \right)^{\alpha/\gamma}\epsilon = 1 + \frac{2p_0}{1 - p_0} + 1 = \frac{2}{1 - p_0}.
\]

Therefore \( \Phi \) maps \( M \) to \( M \).

To find a fixed point for \( \Phi \) in \( M \), we define a sequence of functions by the recurrence relation

\[
\begin{align*}
 u_0(t) &= 0 & \text{for } t = 0, \\
 u_1(t) &= (\Phi u_0)(t) = 1 & \text{for } t \geq t_1, \\
 u_{n+1}(t) &= (\Phi u_n)(t) & \text{for } n \geq 1, \ t \geq t_1.
\end{align*}
\]

Note that for each fixed \( t \), we have \( u_1(t) \geq u_0(t) \). Using that \( f \) is non-decreasing and mathematical induction, we can prove that \( u_{n+1}(t) \geq u_n(t) \). Therefore \( \{u_n\} \) converges pointwise to a function \( u \) in \( M \). Then \( u \) is a fixed point of \( \Phi \) and a positive solution to (1.1) that does not converge to zero. \( \square \)

**Corollary 2.2.** Under the assumptions of Theorem 2.2, every unbounded solution of (1.1) is oscillatory if and only if (2.10) hold.

**Example 2.1.** Consider the neutral differential equation

\[
\begin{align*}
\left( e^{-t} \left( (x(t) - e^{-t} x(\tau(t)))^{1/3} \right) \right)' + \frac{1}{t+1} (x(t-2))^{1/3} &= 0, \\
\left( e^{-k} \left( (x(k) - e^{-k} x(\tau(k)))^{1/3} \right) \right)' + \frac{1}{k+4} (x(k-2))^{1/3} &= 0.
\end{align*}
\]
Here \( \gamma = \frac{11}{3} \), \( r(t) = e^{-t} \), \( -1 < p(t) = -e^{-t} \leq 0 \), \( \sigma(t) = t - 2 \), \( \lambda_k = k \) for \( k \in \mathbb{N} \), \( \Pi(t) = \int_0^t e^{5s/3} \, ds = \frac{3}{5}(e^{5t/3} - 1) \), and \( \alpha = \frac{1}{3} \).

For \( \beta_1 = \frac{7}{3} \) we have \( 0 < \alpha < \beta_1 < \gamma \), and \( u^{\alpha-\beta_1} = u^{-2} \) which is a decreasing function.

To check (2.10) we have

\[
\int_0^\infty q(\eta) \Pi^\alpha(\eta) \, d\eta + \sum_{k=1}^\infty h(\lambda_k) \Pi^\alpha(\sigma(\lambda_k)) \geq \int_0^\infty q(\eta) \Pi^\alpha(\eta) \, d\eta = \int_0^\infty \frac{1}{\eta + 1} \left( \frac{3}{5}(e^{5(\eta - 2)/3} - 1) \right)^{1/3} d\eta = \infty,
\]

since the integral approaches \( +\infty \) as \( \eta \to +\infty \). So, all the conditions of Theorem 2.1 hold, therefore, each solution of (2.15) is oscillatory or converges to zero.

**Example 2.2.** Consider the neutral differential equation

\[
\begin{align*}
\left\{ \begin{array}{l}
\left( \left( x(t) - e^{-t} x(\tau(t)) \right)' \right)^{1/3} & + t x(t - 2) \right)^{7/3} = 0, \\
\left( \left( x(2^k) - e^{-2^k} x(\tau(2^k)) \right)' \right)^{1/3} & + \frac{t}{2} x(2^k - 2) \right)^{7/3} = 0.
\end{array} \right.
\]

(2.16)

Here \( \gamma = \frac{1}{3} \), \( r(t) = 1 \), \( \sigma(t) = t - 2 \) and \( \alpha = \frac{7}{3} \).

For \( \beta_2 = \frac{5}{3} \), we have \( \alpha > \beta_2 > \gamma \) and \( u^{\alpha-\beta_2} = u^{2/3} \) which is a increasing functions.

To check (2.10) we have

\[
\int_{t_0}^\infty \left[ \int_{\eta}^\infty \frac{1}{r(\eta)} \left( \int_{\eta}^\infty q(\zeta) \, d\zeta + \sum_{\lambda_k \geq \eta} h(\lambda_k) \right) \right]^{1/\gamma} \, d\eta \\
\geq \int_{t_0}^\infty \left[ \int_{\eta}^\infty \frac{1}{r(\eta)} \left( \int_{\eta}^\infty q(\zeta) \, d\zeta \right) \right]^{1/\gamma} \, d\eta \geq \int_{t_0}^\infty \left[ \int_{\eta}^\infty \zeta \, d\zeta \right]^{3} \, d\eta = \infty.
\]

So, all the conditions of of Theorem 2.2 hold. Thus, all solution of (2.16) is oscillatory or converges to zero.

**Remark 2.1.** Based on this work and \([13–15, 21, 29–32]\) an open problem that arises is to establish necessary and sufficient conditions for the oscillation of the solutions of the second-order nonlinear neutral differential equation (1.1) for \( p > 0 \) and \( -\infty < p \leq -1 \).

**Acknowledgement.** The author would like to thank reviewers for their careful reading and valuable comments that helped to correct and improve the paper.
OSCILLATION OF SOLUTIONS TO SECOND-ORDER NEUTRAL DIFFERENTIAL EQU.

REFERENCES

[1] BAINOV, D. D.—SIMEONOV, P. S.: Systems with Impulse Effect: Stability, Theory and Applications. Ellis Horwood, Chichester, 1989.

[2] BAINOV, D. D.—COVACHEV, V.: Impulsive Differential Equations with a Small Parameter. In: Series on Advances in Mathematics for Applied Sciences, Vol. 24. World Scientific Publishing Co., Inc., River Edge, NJ, 1994.

[3] BAINOV, D. D.—SIMEONOV, P. S.: Theory of Impulsive Differential Equations: Asymptotic Properties of the Solutions and Applications. World Scientific Publishers, Singapore, 1995.

[4] BAINOV, D. D.—SIMEONOV, P. S.: Impulsive Differential Equations: Asymptotic Properties of the Solutions. Series on Advances in Mathematics for Applied Sciences Vol. 28, World Scientific Publishers, Singapore, 1995.

http://www.naturalspublishing.com/files/published/x28z4tsz4912zt.pdf

[5] BAINOV, D. D.—DIMITROVA, M. B.: Oscillatory properties of the solutions of impulse differential equations with a deviating argument and nonconstant coefficients, Rocky Mountain J. Math. 27 (1997), 1027–1040.

[6] BAINOV, D. D.—DIMITROVA, M. B.—DISHLIEV, A. B.: Oscillation of the solutions of impulsive differential equations and inequalities with a retarded argument, Rocky Mountain J. Math. 28 (1998), 25–40.

[7] BEREZANSKY, L.—BRAVERMAN, E.: Oscillation of a linear delay impulsive differential equations, Comm. Appl. Nonlinear Anal. 3 (1996), 61–77.

[8] MING-PO CHEN, M.-P.—YU, J. S.—SHEN, J. H.: the persistence of nonoscillatory solutions of delay differential equations under impulsive perturbations, Comput. Math. Appl. 27 (1994), 1–6.

[9] DOMOSHNITSKY, A.—DRAKHLIN, M.: Nonoscillation of first order impulse differential equations with delay, J. Math. Anal. Appl. 206 (1997), 254–269.

[10] DOMOSHNITSKY, A.—DRAKHLIN, M.—LITSYN, E.: On boundary value problems for N-th order functional differential equations with impulses, Adv. Math. Sci. Appl. 8 (1998), no. 2, 987–996.

[11] DIMITROVA, M. B.—MISHEV, D.: Oscillation of the solutions of neutral impulsive differential-difference equations of first order, Electron. J. Qual. Theory Differ. Equ. 16 (2005), 1–11.

[12] DIMITROVA, M. B.—DONEV, V. I.: Sufficient conditions for the oscillation of solutions of first-order neutral delay impulsive differential equations with constant coefficients, Nonlinear Oscil. 13 (2010), no. 1, 17–34.

[13] DIMITROVA, M. B.—DONEV, V. I.: Oscillatory properties of the solutions of a first order neutral nonconstant delay impulsive differential equations with variable coefficients, Int. J. Pure Appl. Math. 72 (2011), no. 4, 537–554.

[14] DIMITROVA, M. B.—DONEV, V. I.: Oscillation criteria for the solutions of a first order neutral nonconstant delay impulsive differential equations with variable coefficients, Int. J. Pure Appl. Math. 73 (2011), no. 1, 13–28.

[15] DIMITROVA, M. B.—DONEV, V. I.: On the nonoscillation and oscillation of the solutions of a first order neutral nonconstant delay impulsive differential equations with variable or oscillating coefficients, Int. J. Pure Appl. Math. 73 (2011), no. 1, 111–128.

[16] DOMOSHNITSKY, A.—LANDSMAN, G.—YANETZ, S.: About positivity of Green's functions for impulsive second order delay equations, Opuscula Math. 34 (2014), no. 2, 339–362.

[17] KARPZU, B.—SANTRA, S. S.: Oscillation theorems for second-order nonlinear delay differential equations of neutral type Hacet. J. Math. Stat. 48 (2019), no. 3, 633–643.

169
[18] PINELAS, S.—SANTRA, S.S.: Necessary and sufficient condition for oscillation of nonlinear neutral first-order differential equations with several delays. J. Fixed Point Theory Appl. 20 (2018), no. 27, 1–13.

[19] PINELAS, S.—SANTRA, S.S.: necessary and sufficient conditions for oscillation of nonlinear first order forced differential equations with several delays of neutral type, Analysis, 39 (2019), no. 3, 97–105.

[20] SANTRA, S.S.: Oscillation analysis for nonlinear neutral differential equations of second-order with several delays. Mathematica, 59(82) (2017), no. 1–2, 111–123.

[21] SANTRA, S.S.: On oscillatory second order nonlinear neutral impulsive differential systems with variable delay, Adv. Dyn. Syst. Appl. 13 (2018), no. 2, 176–192.

[22] SANTRA, S.S.—TRIPATHY, A.K.: On oscillatory first order nonlinear neutral differential equations with nonlinear impulses, J. Appl. Math. Comput. 59 (2019), no. 1–2, 257–270.

[23] SANTRA, S.S.: Necessary and sufficient conditions for oscillation to second-order half-linear delay differential equations, J. Fixed Point Theory Appl. 21, Article id 85, (2019), 1–10.

[24] SANTRA, S.S.: Oscillation analysis for nonlinear neutral differential equations of second-order with several delays and forcing term, Mathematica, 61(84) (2019), no. 1, 63–78.

[25] SANTRA, S.S.—DIX, J. G.: Necessary and sufficient conditions for the oscillation of solutions to a second-order neutral differential equation with impulses, Nonlinear Studies, 27 (2020), no. 2, 375–387.

[26] SANTRA, S.S.: Necessary and Sufficient Condition for Oscillatory and Asymptotic Behavior of Second-order Functional Differential Equations, Krag. J. Math. 44 (2020), no. 3, 459–473.

[27] SANTRA, S.S.: Necessary and sufficient conditions for oscillatory and asymptotic behavior of solutions to second-order nonlinear neutral differential equations with several delays, Tatra Mountain Mathematical Publication, 75 (2020), 121–134.

[28] SANTRA, S.S.: Necessary and sufficient conditions for oscillation of second-order delay differential equations, Tatra Mountain Mathematical Publication, 75 (2020), 135–146.

[29] A. K. Tripathy; Oscillation criteria for a class of first order neutral impulsive differential-difference equations, J. Appl. Anal. Comput. 4 (2014), 89–101.

[30] TRIPATHY, A. K.—SANTRA, S.S.: Necessary and sufficient conditions for oscillation of a class of first order impulsive differential equations, Funct. Differ. Equ. 22 (2015), no. 3–4, 149–167.

[31] TRIPATHY, A. K.—SANTRA, S.S.—PINELAS, S.: Necessary and sufficient condition for asymptotic behaviour of solutions of a class of first-order impulsive systems, Adv. Dyn. Syst. Appl. 11 (2016), no. 2, 135–145.

[32] TRIPATHY, A. K.—SANTRA, S.S.: Oscillation properties of a class of second order impulsive systems of neutral type, Funct. Differ. Equ. 23 (2016), no. 1–2, 57–71.

[33] TRIPATHY, A. K.—SANTRA, S.S.: Characterization of a class of second order neutral impulsive systems via pulsatile constant, Differ. Equ. Appl. 9 (2017), no. 1, 87–98.

Received May 18, 2020

Department of Mathematics
JIS College of Engineering
Kalyani - 741235
Nadia, West Bengal
INDIA
E-mail: shyam01.math@gmail.com