Effective Pore Fluid Bulk Modulus at Patchy Saturation: An Analytic Study

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Abstract A patchy saturated two-layered porous rock, with each layer filled with a different fluid, is examined. We assume that this system is probed by an elastic wave having a wavelength much larger than the layers’ thicknesses. We also assume that the diffusion length is smaller than the thickness of an individual layer, which implies hydraulic disconnection between layers. In the context of Gassmann’s fluid substitution theory, we analytically derived an exact expression for the effective fluid bulk modulus assuming that both layers have the same porosity, dry frame, and mineral matrix properties. In addition we derived an approximate solution that works well at relatively high porosities. Both solutions are expressed as a weighted average of the arithmetic and harmonic averages of individual bulk moduli of the pore fluid. These weights are explicitly given as functions of the porosity, the fractional thicknesses of both layers, and the elastic moduli of the constituents. For the approximate solution, one does not require explicit knowledge of the shear modulus of the rock. The comparison with laboratory data showed that, in the case where a porous, isotropic rock is filled with water and gas, the approximate solution can be used to model the measured data for high values of water saturation.

1. Introduction

Understanding the effects of the pore fluid on the elastic response of fluid-saturated porous rock is crucial to the field of quantitative interpretation of seismic data for reservoir detection and characterization. The theoretical assessment of these effects has been primarily based on the fundamental works by Gassmann (1951) and Biot (1956a, 1956b). These developments have often represented real rock by simple geometries, like concentric cylinders and spheres (e.g., Dutta & Ode, 1979a, 1979b; White, 1975; Vogelaar et al., 2010) and parallel layers (e.g., Gelinsky & Shapiro, 1997; Milani et al., 2016; Norris, 1993; Wollner & Dvorkin, 2016; Wollner & Mavko, 2017). Another type of approximation of real rock is random isotropic porous media composed of two constituents (e.g., Berryman & Milton, 1991).

One important application of Gassmann (1951) work is the ability to predict the elastic response of a fully saturated homogeneous isotropic rock as its single-phase pore fluid is substituted with another and assuming that the rate of rock’s deformation is zero. Specifically, Gassmann’s equation predicts the elastic response of a rock at different saturating conditions given that its porosity and dry-frame elastic moduli are known and that the pore fluids, as well as the mineral matrix, can be characterized by their bulk moduli. In other words, no matter how many pore fluid or mineral phases are present, they have to have a single bulk modulus for the composite pore fluid and also one for the composite mineral matrix.

Of course, such idealized scenario is rarely found in natural rock, given that it is heterogeneous at all scales. The fluids occupying the pore space can be different in different parts of the rock, and its mineral matrix is usually constituted of multiple minerals. Moreover, the rate of deformation of a porous system is never zero during a dynamic experiment pertinent to elastic wave propagation. Still, the use of Gassmann’s fluid substitution appears fairly accurate unless the frequency is very high (ultrasonic) or the viscosity of the fluid is much higher than that of water or conventional oil (e.g., Cadoret, 1993; Lebedev et al., 2009; Müller et al., 2010). Specifically, Gassmann’s equations are applicable at instances when the frequency of the wave is sufficiently low such that the characteristic patch size of fluid heterogeneities is much smaller than the diffusion length, thus allowing wave-induced pore-pressure perturbations to equilibrate within a single period of a probing wave (Monachesi et al., 2015; Müller et al., 2010; Rubino et al., 2013).
One approach to relax the single-fluid requirement of Gassmann’s theory for a multiphase pore-fluid system is to represent the fluid mixture as a single ideal fluid by assigning to it an effective bulk modulus. An example of such approach is to compute the bulk modulus of a multiphase pore fluid using the Reuss average (Reuss, 1929) of the bulk moduli of individual fluids. Thereafter, this effective bulk modulus $\bar{K}_f$ is used as an input to the Gassmann fluid-substitution equation. This approach inherently assumes that the frequency of the wave that probes the saturated rock allows the wave-induced pore-pressure perturbations to equilibrate within a single period of the probing wave. Numerous studies have validated this approach, including Murphy (1984), Mavko and Mukerji (1998), Müller and Gurevich (2004), and Masson and Pride (2011). It has been found that the Reuss mixing law acts as a lower bound for $\bar{K}_f$.

At instances where the frequency of the probing wave does not allow for sufficient time for the wave-induced pore-pressure perturbations to equilibrate, different fluid-mixture relations were proposed to estimate $\bar{K}_f$ to be used in Gassmann's equation. In all such cases, the wavelength of the probing wave was still assumed to be much larger than local heterogeneities, therefore neglecting any scattering effects on the computed elastic moduli. The idea of applying a different fluid-mixture relation came about as Domenico (1976) experimentally demonstrated that the effective bulk modulus of the brine/gas system deviated from the harmonic averaging scheme of Reuss. This author proposed to use instead the arithmetic averaging of the bulk moduli of the two fluids as an estimate for $\bar{K}_f$. Cadoret (1993) confirmed this finding through laboratory velocity measurements conducted using ultrasonic pulse transmission. Later, Brie et al. (1995) were able to observe this effect in acoustic logging data and proposed another ad hoc fluid-mixing law relating the volume fraction of water in the pore space ($S_w$) as well as the bulk moduli of gas ($K_g$) and brine ($K_w$). Another fluid-mixing relation was recently proposed by Wollner and Dvorkin (2018) based on a numerical study of fluid effects on the elastic response of a porous body. In their numerical experiment, the mineralogy, porosity, and the dry-frame elastic moduli of each layer in a two-layered package were the same. The only difference between the layers was the pore fluid. This study assumed perfect hydraulic isolation between layers, relevant for frequency regimes where the diffusion length of pore fluid filtration in rock is much smaller than the layer thickness. To obtain a fluid-mixing law, Wollner and Dvorkin (2018) first applied Gassmann’s equation to each layer to obtain their bulk moduli. Afterward, they applied Hill’s (1963) average to the elastic moduli thus computed to obtain the effective bulk modulus of the layered package. In fact, the computed effective bulk modulus of the package is the upper bound for such medium if treated as a homogeneous body. It is also known as the Gassmann-Hill bound explored, for example, by Mavko and Mukerji (1998). Using the effective bulk modulus of the package thus computed, Wollner and Dvorkin (2018) used Gassmann's equation once again to obtain a value for the effective ideal fluid $\bar{K}_f$. Based on their study, the following approximate mixing law was proposed:

$$\bar{K}_f = 0.75K_{f,AR} + 0.25K_{f,HR}. \quad (1)$$

In this equation $K_{f,AR}$ and $K_{f,HR}$ are the arithmetic (the Voigt upper bound) and harmonic (the Reuss lower bound) averages of the composite pore fluids computed respectively as

$$K_{f,AR} = f_1K_{f,1} + f_2K_{f,2}. \quad (2)$$

$$K_{f,HR} = \left(\frac{f_1}{K_{f,1}} + \frac{f_2}{K_{f,2}}\right)^{-1}. \quad (3)$$

where $f_1$ and $f_2 = 1 - f_1$ are the fractional thicknesses of the layers.

Essentially, the Wollner and Dvorkin (2018) empirical mixing law provided an approximation for the upper bound for the effective bulk modulus of a two-phase fluid that is valid for the layered configuration under examination.

At the same time, it is interesting to find exact values of the coefficients in front of $K_{f,AR}$ and $K_{f,HR}$ in the aforementioned mixing law to be used for fluid substitution in the entire layered package. Finding these coefficients under varying properties of the layers will allow to determine an exact expression for the effective bulk modulus for the layered configuration and setting in question, and it is the main problem we pose in this work.
The outline of the paper is as follows: In the next section, we develop an exact representation for \( K_f \) under similar assumptions as used in Wollner and Dvorkin (2018). For relatively high porosity rocks, we also provide an approximation for \( K_f \) as a function of the rock’s dry P-wave modulus, porosity, and the volume fraction of the two fluids in the system. Next, in the section 3, we validate the approximate solution via stochastic simulations and compare the results to laboratory data.

Finally, we discuss our results and offer a conclusion.

2. Theory

In this section we start by briefly deriving the effective fluid bulk modulus in the case of a two-layered package in the same way it was recently derived by Wollner and Dvorkin (2018). Once the final expression is obtained, we proceed by deriving an equivalent expression which is a linear combination of \( K_{f,AR} \) and \( K_{f,HRI} \).

Let us start by assuming that the porosity \( \phi \), the bulk modulus of the mineral matrix \( K_i \), and dry-frame bulk and shear moduli \( K_{di} \) and \( G_i \) respectively, are the same for both layers. If each layer is filled with a different fluid, and the bulk moduli of these fluids are different, then Gassmann’s (1951) theory predicts that the saturated rock bulk modulus of layer 1 (\( K_1 \)) will be different from the corresponding modulus of layer 2 (\( K_2 \)); meanwhile, the shear modulus will be the same for both layers. As a consequence of the latter condition, the resulting medium is isotropic (Hill, 1963), which implies that the effective compressional modulus of the two-layered system \( M_{sat} \) can be computed as the harmonic average of the corresponding individual moduli \( M_1 \) and \( M_2 \):

\[
\frac{1}{M_{sat}} = \frac{f_1}{M_1} + \frac{f_2}{M_2}.
\]

Given that

\[
\tilde{M}_{sat} = \tilde{K}_{sat} + \frac{4}{3} G; \quad \text{and} \quad M_i = K_i + \frac{4}{3} G, \quad i = 1, 2,
\]

where \( \tilde{K}_{sat} \) represents the effective bulk modulus of the system, equation (4) can be equivalently expressed in terms of bulk moduli as follows

\[
\frac{1}{\tilde{K}_{sat} + \frac{4}{3} G} = \frac{f_1}{K_1 + \frac{4}{3} G} + \frac{f_2}{K_2 + \frac{4}{3} G},
\]

from which \( \tilde{K}_{sat} \) can be obtained:

\[
\tilde{K}_{sat} = \left( \frac{f_1}{K_1 + \frac{4}{3} G} + \frac{f_2}{K_2 + \frac{4}{3} G} \right)^{-1} - \frac{4}{3} G.
\]

The bulk moduli of the individual layers, \( K_1 \) and \( K_2 \), are computed upon \( K_{dry}, \phi \), and \( K_s \) as (Gassmann, 1951)

\[
K_i = K_s \phi K_{dry} + \frac{1 - (1 + \phi) K_{dry}/K_s}{\phi K_s + (1 - \phi) - K_{dry}/K_s} K_{f,i}, \quad i = 1, 2.
\]

In this equation, \( K_{f,i} \) represents the bulk modulus of the fluid contained in the \( i \)th layer.

The purpose now is to find the effective fluid bulk modulus \( \tilde{K}_f \) that, when replaced in Gassmann’s fluid substitution equation, will give the effective saturated-rock bulk modulus \( \tilde{K}_{sat} \). In order to do so, we assume that the porosity, together with the dry frame and mineral moduli can also be used for the two-layer package considered as a homogeneous body. With these assumptions, we can apply Gassman’s equation as follows (e.g., Mavko et al., 2009):

\[
\frac{\tilde{K}_{sat}}{K_i - \tilde{K}_{sat}} = \frac{K_{dry}}{K_i - K_{dry}} + \frac{1}{\phi} \frac{K_f}{K_i - K_f},
\]

and, as a consequence,

\[
K_f = K_s \frac{\phi \left( \frac{K_{sat}}{K_f - K_{sat}} - \frac{K_{dry}}{K_f - K_{dry}} \right)}{1 + \phi \left( \frac{K_{sat}}{K_f - K_{sat}} - \frac{K_{dry}}{K_f - K_{dry}} \right)}.
\]
Table 1
Elastic Moduli of the Rock Constituents Employed to Generate the Layered Package

| Material | Bulk modulus [GPa] | Shear modulus [GPa] |
|----------|--------------------|---------------------|
| Quartz   | 36.6               | 45                  |
| Clay     | 10.5               | 3.5                 |
| Water    | 2.61               | 0                   |
| Gas      | 0.06               | 0                   |

where $\bar{K}_{\text{sat}}$ is given by equation (7). This last equation gives the effective bulk modulus of the pore fluid for the two-layered package derived by Wollner and Dvorkin (2018). As can be noticed from simple inspection of equations (8), (9), and (10), the dependence of $\bar{K}_f$ upon the pore fluid bulk moduli $K_{f,1}$ and $K_{f,2}$ is rather complicated. However, after algebraic manipulations, it is possible to prove (see the appendix for a detailed derivation) that the following equivalent expression of $\bar{K}_f$ holds

$$\bar{K}_f = aK_{f,AR} + (1 - a)K_{f,HR},$$

where the $a$ coefficient appearing in equation (11) is given by

$$a = \frac{\phi M_{\text{dry}}}{\phi M_{\text{dry}} + \left[1 - (1 + \phi) \frac{K_{\text{dry}}}{K_s} + \frac{4}{3} \frac{G}{K_s} \left(1 - \phi \frac{K_{\text{dry}}}{K_s}\right)\right](f_2K_{f,1} + f_1K_{f,2})},$$

and $M_{\text{dry}} = K_{\text{dry}} + \frac{4}{3} G$ is the compressional modulus of the dry frame. Equation (11) is an expression equivalent to equation (10) where the relative contribution of the arithmetic and harmonic averages to the effective bulk modulus of the pore fluid are explicitly given by $a$. The derivation of this new parameter constitutes the main result of this paper, and as can be seen in equation (12), it is expressed in terms of the porosity, the fractional thicknesses of both layers, and the elastic moduli of the constituents. As a result, equation (12) provides a means to compute the exact relative contributions of $K_{f,AR}$ and $K_{f,HR}$ to the effective fluid bulk modulus of the two-layer package upon the elastic properties of its constituents.

2.1. Approximate Solution
A more convenient expression for $a$ can be obtained if we use the following approximation:

$$\left[1 - (1 + \phi) \frac{K_{\text{dry}}}{K_s} + \frac{4}{3} \frac{G}{K_s} \left(1 - \phi \frac{K_{\text{dry}}}{K_s}\right)\right] \approx 1.$$

This approximation could be accurate in most cases given that $K_{\text{dry}}/K_s$ and $G/K_s$ are typically small compared to 1, although it would be more accurate in the case of high porosity rocks. Using equation (13), $a$ can be approximated by

$$a_{\text{app}} = \frac{\phi M_{\text{dry}}}{\phi M_{\text{dry}} + f_2K_{f,1} + f_1K_{f,2}}.$$

Note that equation (14) is very simple and shows that the value for $a$ is mainly controlled by the relative magnitudes of $\phi M_{\text{dry}}$ and $f_2K_{f,1} + f_1K_{f,2}$. In other words, the approximate solution does not require explicit knowledge of the shear modulus of the rock. This approximation is especially useful if one does not have $S$ wave data to be able to compute the shear modulus of the rock.

In order to evaluate the applicability of equations (13) and (14), in the following section a comparison between the exact and approximate solutions for $a$ is made by considering different rock-physics models. An example of the application of equation (14) is also presented in the next section.

3. Results
3.1. Evaluation of the Applicability of $a_{\text{app}}$
To evaluate the applicability of $a_{\text{app}}$, we perform a comparison between equations (12) and (14) by synthetically generating a two-layered package having the same $\phi$, $K_s$, $K_{\text{dry}}$, and $G$ in both layers. The only difference between layers are their volume fractions $f_i$ and the bulk moduli of the saturating pore fluid $K_{f,i}$ ($i = 1, 2$).
Table 2

| Model            | $P_d$ [MPa] | $n$ | $\phi_c$ | $\gamma$ | $A_r$ |
|------------------|-------------|-----|----------|----------|-------|
| Soft Sand        | 16.5        | 6   | 0.4      | 1        |       |
| Stiff Sand       | 16.5        | 6   | 0.4      | 1        |       |
| Constant Cement  | 16.5        | 14  | 0.4      | 1        |       |
| DEM              | 0.1         |     |          |          |       |

Note: $P_d$ is the differential pressure; $n$ is the coordination number; $\phi_c$ is the critical porosity; $\gamma$ is the shear correction factor; and $A_r$ is the aspect ratio.

To generate the two-layered package, both the porosity $\phi$ and the fractional thickness $f_1$ were randomly varied within the intervals $(0.15, 0.35)$ and $(0, 1)$, respectively. The solid frame was assumed to be composed of a quartz/clay mixture, and the effective bulk modulus $K_s$ was computed as the Hill’s average (e.g., Mavko et al., 2009) of the bulk moduli of both constituents. These moduli were computed using the mineral moduli listed in Table 1 and randomly varying the clay content between zero and 100%. Layer 1 was fully saturated with water, meaning that $f_1$ is equivalent to the water saturation $S_w$ of the package, while Layer 2 was fully saturated with gas. The values for water and gas bulk moduli are also listed in Table 1.

To compute the dry-frame elastic moduli of the system, we employed four different rock-physics models that depend on porosity and mineralogy: Soft Sand (the modified lower Hashin-Shtrikman bound); Stiff Sand (the modified upper Hashin-Shtrikman bound); Constant-Cement (the Soft Sand model with high coordination number); and the Differential Effective Medium (DEM; Mavko et al., 2009). For the computation of these rock-physics models, we employed the model parameters listed in Table 2.

Figure 1. Approximate parameter $\alpha_{app}$ (equation (14)) against the exact $\alpha$ (equation (12)) obtained for multiple statistical realizations of a two-layered package. The elastic properties of each package are generated using a rock-physics model, namely, (a) Soft Sand, (b) Constant Cement, (c) Stiff Sand, and (d) DEM. The difference between any two layers in each package is the saturating fluid. One layer is fully water saturated, whereas the second layer is fully gas saturated. The plotted values are color-coded by porosity values.
Table 3
Poroelastic Parameters of Sample S7 From Cadoret (1993) and Pore Fluids Used in This Study

| Variables | Meaning                               | Value          |
|-----------|---------------------------------------|----------------|
| $M_s$     | Compressional modulus of solid grain  | 120 GPa        |
| $\phi$    | Porosity                              | 0.3            |
| $\kappa$  | Permeability                           | $2.6 \times 10^{-13}$ m$^2$ |
| $K_w$     | Bulk modulus of water                  | 2.25 GPa       |
| $K_g$     | Bulk modulus of gas                    | 0.03 GPa       |
| $\rho_s$  | Density of solid                       | 2.7 g/cm$^3$   |
| $\rho_w$  | Density of water                       | 1 g/cm$^3$     |
| $\rho_g$  | Density of gas                         | 0.006 g/cm$^3$ |

Figure 1 shows a plot of the computed approximate parameter $a_{app}$ obtained from equation (14), against the exact $a$ value obtained from equation (12) for several statistical realizations. These results are color-coded using the porosity values of the package. We observe that regardless of the rock-physics model used, at relatively high porosities ($>0.25$), equation (14) approximates well the exact solution. This observation is understandable as higher porosity lead to softer rock, thus corroborating the approximation of equation (14).

3.2. Comparison With Experimental Data
Cadoret (1993) exemplified the effect of patchy saturation on the effective elastic properties of rocks obtained from bench top measurements on various carbonate rocks. Cadoret saturated dry rock samples with water, and, at different water saturation levels, he recorded the time it took for a $P$ wave to traverse the rock sample from one end of the rock to the other. By measuring the thickness of the sample, Cadoret then computed the velocity of the $P$ wave. Patches of water were shown to form as fully water saturated rocks were dried. In this section, we wish to validate the approximate solution $a_{app}$ for one of Cadoret’s rock samples that exhibited patchy saturation.

Recall that the underlying requirement of this work is that the examined rock specimen is treated as a homogeneous body having effective elastic and petrophysical properties. In other words, the wavelength of a probing wave is much larger than local heterogeneity within the rock. In addition, we assumed that the fluid saturating regions can be considered to be hydraulically isolated from each other given that the thickness of each region exceeds the diffusion length. That is to say, the interplay between porosity, permeability, dynamic viscosity, and fluid bulk modulus for a given frequency of the probing wave determine whether local fluid patches are hydraulically communicating or not.

Though we had posed our problem as one dealing with layered media, our mathematical derivations are not limited to this setting as long as our assumptions of the rock properties are met. In our initial problem statement, we required that our two-layered media had both layers with the same $\phi$, $K_r$, $K_dry$, and $G$. The difference between the layers is the saturating fluid. In other words, we had initially considered the case of layered fluids patches. However, equivalent effective elastic behavior of such rock will be observed if the fluid patches were in a different configuration inside it that are spatially variable. This is the case observed by Cadoret.

Specifically, we chose to examine the bench top measurements performed at 50 kHz by Cadoret for sample Estaillades S7 (Limestone) during drainage process. The rock sample was approximately isotropic. The poroelastic parameters of this sample, as recorded by Cadoret ($\phi$, $\rho_s$, permeability $\kappa$), and other parameters used in this study are given in Table 3. $K_w$, $K_g$, $\rho_w$, $\rho_g$, and $M_s$ were selected based on studies listed in Mavko et al. (2009).

During his measurements, Cadoret also CT scanned the rock at different water saturation stages. Toms-Stewart et al. (2009) used these images to estimate the spatial correlation length of water patches for Cadoret’s partially saturated sample. They noted that it increased with increasing $S_w$. Later, Kobayashi and Mavko (2016) suggested a power law relation relating the characteristic diffusion length $L_c$ and $S_w$ to fit their model to Cadoret’s data. They defined $L_c$ as $L_c = a_0 \times S_w/(1 − S_w)$. This relation shows an increase in $L_c$ with an increase in $S_w$ for given dry rock heterogeneity scale $a_0$. The term $L_c$ essentially characterizes the
Figure 2. (a) $P$ wave velocity values plotted against the fraction of water saturated pore space. The black markers are those measured by Cadoret (1993) for sample S7 using a 50-kHz transducer showing effect of patchy saturation on measured $V_p$. The red, green, and blue markers are approximated solutions to the observed $V_p$-$S_w$ behavior as $\bar{K}_f$ is approximated and then used as input to the $V_p$-only fluid substitution. $K_f$ is approximated as either $K_f{_{AR}}$ (red markers), $K_f{_{HR}}$ (blue markers), and using equations (14) and (11) (green markers). The magenta markers were computed assuming $\alpha = 0.75$ (equation (1)). (b) The computed $\alpha_{app}$ parameter as a function of water saturation.

patch size of fluid heterogeneities. The larger the characteristic patch size compared to the diffusion length in a rock, the less fluid flow occurs within the rock. Hence, wave-induced pore-pressure perturbations cannot reach equilibrium. In other words, at high water saturation levels we expect to see patchy saturation behavior.

Since Cadoret only measured the $P$ wave velocity of this sample at different saturation levels, we cannot determine the dry bulk modulus of the sample and Gassmann’s fluid substitution relations. To overcome this issue, we utilized the approximate Gassmann’s fluid substitution equation for isotropic bodies suggested by Mavko et al. (1995), also known as the $V_p$-only fluid substitution relations, to approximate the dry $P$ wave modulus from the fully gas-saturated rock. This approximation is given by

$$M_{\text{dry}} = M_{\text{sat}} \left( \frac{\phi M_{s}/K_s}{\rho_b} + 1 - \phi \right) - M_s \frac{\phi M_s/K_s + M_{\text{sat}}/M_s - 1 - \phi}{\rho_b},$$

(15)

where $M_s$ is the $P$ wave modulus of the mineral component comprising the rock and $M_{\text{sat}}$ is given by

$$M_{\text{sat}} = V_p^2 \rho_b,$$

(16)

with

$$\rho_b = (1 - \phi) \rho_s + \phi \rho_g.$$  

(17)

We then computed $\alpha_{app}$ using equation (14) and the resulting effective fluid bulk modulus of the sample using equation (11). The effective fluid bulk modulus is then used as input to the $V_p$-only fluid substitution to obtain the $P$ wave modulus of the rock sample at different water saturation stages assuming the gas and water patches are hydraulically disconnected from each other. The resulting $P$ wave velocity is computed as

$$V_p = \sqrt{M_{\text{sat}}/\rho_b},$$

(18)

where

$$M_{\text{sat}} = M_s \frac{\phi M_{\text{dry}} - (1 + \phi)\bar{K}_f M_{\text{dry}}/M_s + \bar{K}_f}{(1 - \phi)\bar{K}_f + \phi M_s - \bar{K}_f M_{\text{dry}}/M_s},$$

(19)

and $\rho_b$ given by

$$\rho_b = (1 - \phi) \rho_s + \phi \left[ S_w \rho_w + (1 - S_w) \rho_g \right].$$

(20)
These results are shown in Figure 2a along with the measurements recorded by Cadoret (1993). For comparison, we also added the resulting $P$ wave velocity of equations (18) to (20), given the effective fluid bulk modulus of the rock sample is computed either as $K_{f,AR}$ or $K_{f,HR}$. Furthermore, we added the resulting $P$ wave velocity relation using equation (1) as suggested by Wollner and Dvorkin (2018).

We observe that patchy saturation with complete hydraulic disconnection between fluid patches can be better estimated using $\alpha_{app}$ (green markers) at high saturations ($S_w > 85\%$), whereas at low saturations, this analytical solution overestimate the measured data. One reason for this observation is that at low values of $S_w$, the size of the water patches are smaller or comparable to the diffusion length. On the other hand, at high saturation values, the size of the water patches become larger than the diffusion length, resulting in complete hydraulic disconnection; this is the setting we assumed in this study. For further details on the effects of the size of water patches and diffusion length on the measured $P$ wave velocity on a rock, the reader is referred to Müller et al. (2010).

As the $\alpha$ parameter (both in its exact or approximated version) depends on water saturation $S_w$, there is not a unique value of $\alpha$ in the computation of the the effective fluid bulk modulus of Figure 2a. Figure 2b illustrates this dependence.

We note that the curve generated by equation (1) (Wollner & Dvorkin, 2018) does provide a better match to the $V_p$ data, in this case, than using $\alpha_{app}$ in equation (11). However, we must reiterate that the notion of using $\alpha_{app}$ was to model a complete hydraulic disconnection between water patches. Thus, a deviation from this assumption will likely cause a discrepancy between modeled $V_p, S_w$ dependency and the measured one.

4. Discussion

The main purpose of the present study was to analytically address the effect of the pore fluid distribution on the elastic properties of fluid-saturated porous rock. We focused on the case of a two-layered package where the mineralogy, porosity, and dry-frame elastic moduli were constant and the only difference between the layers was in the pore fluid. We also considered that no hydraulic communication occurs between the layers since it is often associated with the concept of patchy saturation. An important result addressed by Wollner and Dvorkin (2016) was to find an analytic solution that could be used in anisotropic Gassmann’s fluid substitution applied to a sequence of layers considered as an anisotropic homogeneous body (equation (10)). Wollner and Dvorkin (2018) provided an exact relation for the effective fluid bulk modulus for a layered package, as is assumed in this study. They also hypothesized that this effective modulus can also be computed as a linear combination of the arithmetic and harmonic averages of the fluid bulk moduli in the individual layers. However, Wollner and Dvorkin (2018) only provided an empirical solution for the weights to be used in the linear fit (equation (1)). The main result of the present study was to analytically develop the weighting coefficients for Wollner and Dvorkin (2018) proposed linear fit and obtain an exact alternative expression for the effective fluid bulk modulus of a two-layered package. These weights are related to each other by the $\alpha$ parameter (equation (12)). This new parameter is explicitly expressed as a function of the porosity, the fractional thicknesses of both layers and the elastic properties of the constituents.

The analytic solution derived for the $\alpha$ parameter was approximated by a rather simpler mathematical expression (equation (14)). It is informative to note that this expression does not require knowledge of the shear modulus of the rock, which makes it specifically useful if one does not have $S$ wave data to be able to compute this modulus. We performed a comparative stochastic analysis between both the exact and the approximate solutions for $\alpha$ by considering four different rock-physics models. The analysis clearly showed that for relatively high porosities $\alpha_{app}$ turns out to be a very good approximation of $\alpha$, regardless of the model considered. The obtained results are consistent with the approximation made in equation (13), which is more accurate for softer rocks.

The derived analytic solution for $K_f$ was tested with experimental data of $P$ wave velocity collected by Cadoret (1993) from a rock sample exhibiting patchy saturation. In order to compare our model predictions with the laboratory data, we computed the $V_p$ velocity as a function of water saturation using the effective fluid bulk modulus predicted by equation (11) with $\alpha$ given by its approximate expression (14). We concluded that when the patches are hydraulically disconnected, the effective fluid bulk modulus can be modeled using $\alpha_{app}$ at high saturations; meanwhile, at intermediate and low saturations, the proposed solution overestimates the experimental data. This result was expected, given that for high saturations, water
patches become larger than the diffusion length, resulting in complete hydraulic disconnection, which is the setting we assume in this study.

5. Conclusion

We derived a new analytic solution for the effective fluid bulk modulus \( \overline{K}_f \) to be used in fluid substitution. The solution is valid for a patchy saturated two-layer system where both layers, each filled with a different fluid, are assumed to be hydraulically disconnected. The solution is expressed as a weighted average of the arithmetic and harmonic averages of individual bulk moduli of the pore fluid. We also derived an approximate solution that is very simple and works well at relatively high porosities. This solution does not require knowledge of the shear modulus of the rock, which makes it specifically useful if one does not have S wave data to be able to compute this modulus. We performed a comparison of the approximate solution with laboratory data and showed that for high values of water saturation the solution can be safely used to model the measured data.

As a concluding remark, it is important to mention that the new derived analytic solutions provide a means to estimate the relative contributions of \( K_{f, AR} \) and \( K_{f, HR} \) to the effective fluid bulk modulus of the two-layer package upon the elastic properties of its constituents.

Appendix A: Derivation of Equations (11) and (12)

This appendix includes a full derivation of the equations (11) and (12). We start by defining the following constants:

\[
A = \phi K_{dry}, \quad B = 1 - (1 + \phi)K_{dry}/K_s, \\
C = \phi K_s, \quad D = 1 - \phi - K_{dry}/K_s.
\]  

(A1)

With them, equation (8) for \( K_i \) can be written as

\[
K_i = K_s \frac{A + BK_{f,i}}{C + DK_{f,i}}.
\]  

(A2)

Using equation (A2), we can write

\[
K_i + \frac{4}{3} G = K_s \frac{A + \frac{4}{3} G C}{C + DK_{f,i}} + \frac{B + \frac{4}{3} D}{C + DK_{f,i}} K_{f,i}.
\]  

(A3)

Now, let us call for simplicity

\[
E = A + \frac{4}{3} G C, \quad F = B + \frac{4}{3} D K_s
\]  

(A4)

then

\[
K_i + \frac{4}{3} G = K_s \frac{E + FK_{f,i}}{C + DK_{f,i}}.
\]  

(A5)

Using this last expression, we can write

\[
\frac{f_1}{K_i + \frac{4}{3} G} + \frac{f_2}{K_2 + \frac{4}{3} G} = \frac{1}{K_s} \frac{f_1(C + DK_{f,i})(E + FK_{f,i}) + f_2(C + DK_{f,i})(E + FK_{f,i})}{(E + FK_{f,i})(E + FK_{f,i})},
\]  

(A6)

from which the inverse results

\[
\left( \frac{f_1}{K_i + \frac{4}{3} G} + \frac{f_2}{K_2 + \frac{4}{3} G} \right)^{-1} = K_s \frac{f_1(C + DK_{f,i})(E + FK_{f,i}) + f_2(C + DK_{f,i})(E + FK_{f,i})}{(E + FK_{f,i})(E + FK_{f,i})},
\]  

(A7)
Combining equations (A9) and (A12), we obtain

\[ K_s = \frac{K_s}{f_1(C + DK_{f,1})(E + FK_{f,1}) + f_2(C + DK_{f,2})(E + FK_{f,1})} \]  

(A9)

Now, defining the constants as

\[ K_s = \frac{(H + IK_{f,1})(E + FK_{f,1}) + (J + KK_{f,1})(E + FK_{f,1})}{f_1(C + DK_{f,1})(E + FK_{f,1}) + f_2(C + DK_{f,2})(E + FK_{f,1})}, \]  

(A10)

we obtain \( K_{sat} \) (see equations (7) and (A7))

\[ K_{sat} = \frac{K_s}{f_1(C + DK_{f,1})(E + FK_{f,1}) + f_2(C + DK_{f,2})(E + FK_{f,1})} \]  

(A11)

Now, proceeding as follows:

\[ K_s - K_{sat} = \frac{K_s}{2} \left( \frac{(E + FK_{f,1}) \left[ (2f_s C - H) + (2f_s D - I) K_{f,1} \right]}{f_1(C + DK_{f,1})(E + FK_{f,1}) + f_2(C + DK_{f,2})(E + FK_{f,1})} \right) \]  

(A12)

Combining equations (A9) and (A12), we obtain

\[ \frac{K_{sat}}{K_s - K_{sat}} = \frac{(E + FK_{f,1})(H + IK_{f,1}) + (J + KK_{f,1})(E + FK_{f,1})}{(E + FK_{f,1})(L + MK_{f,1}) + (E + FK_{f,1})(N + PK_{f,2})} \]  

(A13)

With this last expression we can write

\[ \frac{K_{sat}}{K_s - K_{sat}} - \frac{K_{dry}}{K_s - K_{dry}} = \frac{(E + FK_{f,1})(H + IK_{f,1}) + (J + KK_{f,1})(E + FK_{f,1})}{(E + FK_{f,1})(L + MK_{f,1}) + (E + FK_{f,1})(N + PK_{f,2})} \]  

(A14)

Calling

\[ Q = H - \frac{K_{dry}}{K_s - K_{dry}} L, \quad R = I - \frac{K_{dry}}{K_s - K_{dry}} M, \]  

(A15)

\[ S = J - \frac{K_{dry}}{K_s - K_{dry}} N, \quad T = K - \frac{K_{dry}}{K_s - K_{dry}} P, \]  

we obtain

\[ \frac{K_{sat}}{K_s - K_{sat}} - \frac{K_{dry}}{K_s - K_{dry}} = \frac{(E + FK_{f,1})(Q + RK_{f,1}) + (E + FK_{f,1})(S + TK_{f,2})}{(E + FK_{f,1})(L + MK_{f,1}) + (E + FK_{f,1})(N + PK_{f,2})}. \]  

(A16)
Then,
\[
1 + \phi \left( \frac{\bar{K}_{sat}}{K_s - \bar{K}_{sat}} - \frac{K_{dry}}{K_s - K_{dry}} \right) = 1 + \phi \left( \frac{(E + FK_{f,2}) (Q + RK_{f,1}) + (E + FK_{f,1}) (S + TK_{f,2})}{(E + FK_{f,2}) (L + MK_{f,1}) + (E + PK_{f,2}) (N + PK_{f,2})} \right)
\]

(A17)

Finally, using equations (A16) and (A19) in the expression for \( \bar{K}_f \) given by equation (10), we get

\[
\bar{K}_f = \phi K_s \left( \frac{(E + FK_{f,2})(Q + RK_{f,1}) + (E + FK_{f,1})(S + TK_{f,2})}{(E + FK_{f,2})(U + VK_{f,1}) + (E + FK_{f,1})(W + XK_{f,2})} \right).
\]

(A20)

This last expression can be simplified given that the constants \( Q, S, V, \) and \( X \) verify

\[
Q + S = 0, \quad V + X = 0.
\]

(A21)

Then, \( \bar{K}_f \) can be written as

\[
\bar{K}_f = \phi K_s \left( \frac{ER + FS}{f_1} \right) K_{f,1} f_1 + \left( \frac{ET + FQ}{f_2} \right) K_{f,2} f_2 + \frac{F(R + T)K_{f,3} K_{f,2}}{E(U + W) + (EV + FW)f_1 \frac{k_{f,1}}{f_1} + (FU + EX)f_2 \frac{k_{f,2}}{f_2}}.
\]

(A22)

Now, calling

\[
Y_1 = \frac{ER + FS}{f_1}, \quad Y_2 = \frac{ET + FQ}{f_2},
\]

\[
Z_1 = (EV + FW)f_1, \quad Z_2 = (FU + EX)f_2,
\]

(A23)

it is possible to prove that \( Y_1 = Y_2 \) and \( Z_1 = Z_2 \). Let us call them for simplicity \( Y \) and \( Z \), respectively. Also, we can prove that the following relations hold

\[
E(U + W) = \phi K_s F(R + T).
\]

(A24)

Then, \( K_{f} \) can be written as

\[
K_f = \phi K_s Y \left( f_1 K_{f,1} + f_2 K_{f,2} \right) + \frac{Z}{f_1 f_2} K_{f,1} K_{f,2} + \phi K_s Y Z \left( \frac{k_{f,1}}{f_1} + \frac{k_{f,2}}{f_2} \right).
\]

(A25)

Equation (A25) can be rearranged as

\[
K_f = \frac{\phi K_s Y}{\phi K_s + \frac{Z}{f_1 f_2} (f_1 K_{f,1} + f_2 K_{f,2})} K_{f,AR} + \frac{\phi K_s Y + \frac{Z}{f_1 f_2} (f_2 K_{f,1} + f_1 K_{f,2})}{\phi K_s + \frac{Z}{f_1 f_2} (f_1 K_{f,1} + f_2 K_{f,2})} K_{f,HR}.
\]

(A26)
where $K_{f,AB}$ and $K_{f,AR}$ are given by equations (2) and (3), respectively. Using the relations given for the constants defined in (A1), (A4), (A8), (A11), (A15), and (A18), we find

$$\phi K_Y = \frac{2\phi^2 (K_s - K_{dry})}{K_{dry} + \frac{4}{3}G}.$$  

$$Z_{f,f_2} = \frac{2\phi (K_s - K_{dry})}{1 - (1 + \phi)\frac{K_{dry}}{K_s} + \frac{4}{3}\frac{G}{K_s}}.$$  

(A27)

Replacing the last expressions of (A27) in equation (A26), we obtain the final equations (11) and (12).

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