Active Evaluation: Efficient NLG Evaluation with Few Pairwise Comparisons

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Abstract

Recent studies have shown the advantages of evaluating NLG systems using pairwise comparisons as opposed to direct assessment. Given \( k \) systems, a naive approach for identifying the top-ranked system would be to uniformly obtain pairwise comparisons from all \( \binom{k}{2} \) pairs of systems. However, this can be very expensive as the number of human annotations required would grow quadratically with \( k \). In this work, we introduce Active Evaluation, a framework to efficiently identify the top-ranked system by actively choosing system pairs for comparison using dueling bandit algorithms. We perform extensive experiments with 13 dueling bandits algorithms on 13 NLG evaluation datasets spanning 5 tasks and show that the number of human annotations can be reduced by 80%. To further reduce the number of human annotations, we propose model-based dueling bandit algorithms which combine automatic evaluation metrics with human evaluations. Specifically, we eliminate sub-optimal systems even before the human annotation process and perform human evaluations only on test examples where the automatic metric is highly uncertain. This reduces the number of human annotations required further by 89%. In effect, we show that identifying the top-ranked system requires only a few hundred human annotations, which grow linearly with \( k \). Lastly, we provide practical recommendations and best practices to identify the top-ranked system efficiently.\(^1\)

1 Introduction

In the last few years, the field of NLG has made rapid progress with the advent of large-scale models trained on massive amounts of data (Vaswani et al., 2017; Xue et al., 2020; Liu et al., 2020; Brown et al., 2020). However, evaluation of NLG systems continues to be a challenge. On the one hand, we have automatic evaluation metrics which are easy to compute but unreliable. In particular, many studies have shown that they do not correlate well with human judgments (Novikova et al., 2017; Elliott and Keller, 2014; Sai et al., 2019, 2020a,b). On the other hand, we have human evaluations, which are relatively more reliable but tedious, expensive, and time-consuming. Further, recent studies have highlighted some limitations of human evaluations that involve direct assessment on an absolute scale, e.g., Likert scale. Specifically, human evaluations using direct assessment have been shown to suffer from annotator bias, high variance and sequence effects where the annotation of one item is influenced by preceding items (Kulikov et al., 2019; Sudoh et al., 2021; Liang et al., 2020; See et al., 2019; Mathur et al., 2017).

In this work, we focus on reducing the cost and time required for human evaluations while not compromising on reliability. We take motivation from studies which show that selecting the better of two options is much easier for human annotators than providing an absolute score, which requires annotators to maintain a consistent standard across samples (Kendall, 1948; Simpson and Gurevych, 2018). In particular, recent works show that ranking NLG systems using pairwise comparisons is a more reliable alternative than using direct assessment (See et al., 2019; Li et al., 2019; Sedoc et al., 2019; Dhingra et al., 2019). While this is promising, a naive approach for identifying the top-ranked system from a set of \( k \) systems using uniform exploration is prohibitively expensive. Specifically, uniform exploration obtains an equal number of annotations for all the \( \binom{k}{2} \) system pairs; as a result, the required human annotations grows as \( O(k^2) \).

To reduce the number of pairwise annotations, we introduce Active Evaluation, a framework to efficiently identify the top-ranked NLG system. Our Active Evaluation framework consists of a learner that selects a pair of systems to compare
at each time step. The learner, then, receives a feedback signal indicating the (human) preference between the selected systems on one input context, randomly sampled from the test dataset. The learner’s objective is to reliably compute the top-ranked system with as few human annotations as possible. We adopt algorithms from the stochastic dueling bandits literature (Bengs et al., 2021) to decide which pair of NLG systems to compare at each time step. To check if existing dueling bandit algorithms can indeed provide reliable top-rank estimates with minimal annotations, we evaluate 13 such algorithms on 13 NLG evaluation datasets spanning five tasks viz., machine translation, summarization, data-to-text generation, paraphrase generation, and grammatical error correction. We show that the best performing dueling bandit algorithm can reduce the number of human annotations by 80% when compared to uniform exploration.

To further reduce human annotations, we leverage automatic evaluation metrics in our Active Evaluation framework. We utilize existing automatic metrics such as BLEU (Papineni et al., 2002), BertScore (Zhang et al., 2020), etc. for pairwise evaluations by converting the direct evaluation scores into preference probabilities using pairwise probability models. We also develop trained pairwise algorithms that directly predict the comparison outcome given pairs of generated texts and context or reference as input. To incorporate such evaluation metrics in our Active Evaluation framework, we propose three model-based dueling bandits algorithms, viz., (i) Random Mixing: human annotations and evaluation metric predictions are randomly mixed, (ii) Uncertainty-aware selection: human annotations are obtained only when the predictions from the evaluation metric is highly uncertain, (iii) UCB Elimination: poorly performing NLG systems are eliminated using an Upper Confidence Bound (UCB) on the evaluation metric scores. Through our experiments, we show that the number of human annotations can be further reduced by 89% on average (this reduction is over and above the 80% reduction that we got earlier).

In effect, we show that given \( k \) and above the 80% reduction that we got earlier). Lastly, we provide practical recommendations to efficiently identify the top-ranked NLG system based on our empirical study on various design choices and hyperparameters.

2 Active Evaluation Framework

We introduce the problem and our Active Evaluation setup in section 2.1. Later in section 2.2, we describe the different approaches to decide which pairs of NLG systems to compare at each time step. Finally, in section 2.3, we formalize the notion of top-ranked system.

2.1 Problem Formulation and Setup

We consider the problem of finding the top-ranked NLG system from a given set of \( k \) systems, denoted by \( S = \{1, 2, \ldots, k\} \). Our Active Evaluation framework consist of a learner which at each time step \( t \), chooses a pair of systems \( s_1^{(t)}, s_2^{(t)} \in S \) for comparison. Then, we ask human annotators to compare the outputs of the chosen systems on a randomly sampled input context and provide the comparison outcome as feedback to the learner. Specifically, we first sample an input context \( X^{(t)} \) from the test dataset and obtain the generated texts \( Y_1^{(t)}, Y_2^{(t)} \) from the chosen systems \( s_1^{(t)}, s_2^{(t)} \). We then display the generated texts \( Y_1^{(t)}, Y_2^{(t)} \) along with the context \( X^{(t)} \) to human annotators and obtain a comparison outcome \( w^{(t)} = 1, 0 \) or 0.5 denoting whether \( Y_1^{(t)} \) is of better, worse, or equal (tie) quality as \( Y_2^{(t)} \). Note that the feedback \( w^{(t)} \) indicates the preference on only one input sample and not the entire test dataset. The overall framework is depicted in figure 1. The learner’s objective is to find the top-ranked system with as few pairwise comparisons as possible.

2.2 Choosing System Pairs for Comparison

The learner should decide the pair of systems \((s_1^{(t)}, s_2^{(t)})\) to compare at each time step \( t \). The naive approach is to uniformly explore all the \( \binom{k}{2} \) system pairs. Specifically, the probability of selecting a pair \((i, j), i \neq j\) at time \( t \) is given by

\[
P_{\text{uniform}}((s_1^{(t)}, s_2^{(t)}) = (i, j)) = \frac{1}{\binom{k}{2}}
\]

However, as we show in our experiments, the number of human annotations required to find the top-ranked system by this approach is very expensive and grows quadratically with the number of systems since we equally explore all \( \binom{k}{2} \) pairs. To reduce the number of annotations, we use dueling bandit algorithms to actively choose pairs of systems to compare based on the history of previous observations. We provide an overview of 13 dueling bandit algorithms proposed in the literature in...
We define the top-ranked system as the one that "beats" system \( j \) when \( p_{ij} > \frac{1}{2} \). In other words, system \( i \) beats system \( j \) if the probability of winning in a pairwise comparison is larger for \( i \) than it is for \( j \). We define the top-ranked system \( i^* \) as the one that beats all other systems, i.e., \( p_{i^*j} > \frac{1}{2}, \forall j \in S - i^* \).

### 3 Pairwise Probability Models

Our Active Evaluation framework, which we described in the previous section, completely relies on human annotators to compare pairs of generated texts \( (Y_1, Y_2) \) to provide the preference feedback \( w \). We can further reduce the number of required human annotations by estimating the human preference feedback using automatic evaluation metrics. However, most existing evaluation metrics are designed for direct assessment and not directly suitable for pairwise evaluations. In this section, we describe three pairwise probability models to convert direct evaluation scores into pairwise preference probabilities. Let \( f(Y) \) denote the score provided by a direct assessment metric \( f \) to a generated text \( Y \) (The dependence of \( f \) on the reference/context is omitted for brevity). The pairwise preference probability \( \hat{p}(Y_1 > Y_2) \) between any two hypotheses \( Y_1 \) and \( Y_2 \) can be modeled in 3 different ways:

- **Linear:**
  \[
  \hat{p}(Y_1 > Y_2) = \frac{1}{2} + (f(Y_1) - f(Y_2))
  \]

- **Bradley-Terry-Luce (BTL)** (Bradley and Terry, 1952; Luce, 1979):
  \[
  \hat{p}(Y_1 > Y_2) = \frac{f(Y_1)}{f(Y_1) + f(Y_2)}
  \]

- **BTL-logistic:**
  \[
  \hat{p}(Y_1 > Y_2) = \frac{1}{1 + e^{-(f(Y_1) - f(Y_2))}}
  \]

As detailed in appendix C.2, we appropriately preprocess the scores \( f(Y) \) to ensure that preference probability lies between 0 and 1. We can now predict the comparison outcome \( w \) by thresholding the preference probability at two thresholds \( \tau_1 \) and \( \tau_2 (\geq \tau_1) \) to incorporate ties i.e.:

\[
\hat{w} = \begin{cases} 
1, & \text{if } \hat{p}(Y_1 > Y_2) > \tau_2 \\
0, & \text{if } \hat{p}(Y_1 > Y_2) < \tau_1 \\
0.5, & \text{Otherwise}
\end{cases}
\]

We choose \( \tau_1 \) and \( \tau_2 \) using grid search on the validation set. Refer appendix C.2 for more details.

### 4 Model-based Dueling Bandits

In the previous section, we discussed pairwise probability models to obtain the estimated preference probability \( \hat{p}(Y_1 > Y_2) \) and the comparison outcome \( \hat{w} \) using scores assigned by direct assessment metrics. We now propose three model-based dueling bandit algorithms wherein we combine such predictions from evaluation metrics with human annotations in the Active Evaluation framework.

#### 4.1 Random Mixing

Here, we randomly provide either the real (human) or the evaluation metric predicted feedback to the learner. Specifically, at any time \( t \), we use the predicted comparison outcome \( \hat{w}^{(t)} \) as the feedback with probability \( p_m \) and use human annotations \( w^{(t)} \) as feedback with probability \( 1 - p_m \). The hyperparameter \( p_m \) controls the ratio of estimated and real feedback given to the learner. As with other hyperparameters, we tune \( p_m \) on the validation set.
4.2 Uncertainty-aware Selection

In this algorithm, we estimate uncertainty in the evaluation metric predictions and decide to ask for human annotations only when the evaluation metric is highly uncertain. We specifically focus on trainable neural evaluation metrics such as Bleurt (Sellam et al., 2020) where we estimate the prediction uncertainty using recent advances in Bayesian deep learning. Let \( \hat{p}(Y_1 > Y_2|\theta) \) denote the preference probability modelled by a neural evaluation metric with parameters \( \theta \). Given a training dataset \( \mathcal{D}^{tr} \), Bayesian inference involves computing the posterior distribution \( p(\theta|\mathcal{D}^{tr}) \) and marginalization over the parameters \( \theta \):

\[
\hat{p}(Y_1 > Y_2|\mathcal{D}^{tr}) = \int_\theta \hat{p}(Y_1 > Y_2|\theta) p(\theta|\mathcal{D}^{tr}) d\theta
\]

However, computing the true posterior and averaging over all possible parameters is intractable in practice. Hence, several approximations have been proposed in variational inference such as finding a surrogate distribution \( q_\phi(\theta) \) for the true posterior.

Gal and Ghahramani (2016) have shown that we can use the Dropout distribution (Srivastava et al., 2014) as the approximate posterior \( q_\phi(\theta) \). Specifically, we can perform approximate Bayesian inference by applying Dropout during test time. Hence, the posterior can now be approximated with Monte-carlo samples as follows:

\[
\hat{p}(Y_1 > Y_2|\mathcal{D}^{tr}) \approx \frac{1}{L} \sum_{l=1}^{L} \hat{p}(Y_1 > Y_2|\theta_l)
\]

where \( \{\theta_l\}_{l=1}^{L} \) are \( L \) samples from the Dropout distribution \( q_\phi(\theta) \) (i.e. we apply Dropout \( L \) times independently during testing). We now discuss two different Bayesian uncertainty measures:

**BALD:** The Bayesian Active Learning by Disagreement (BALD) (Houlsby et al., 2011) is defined as the mutual information between the model predictions and the model posterior. Let \( p_l = \hat{p}(Y_1 > Y_2|\theta_l) \), where \( \theta_l \sim q_\phi(\theta) \), be the evaluation metric prediction using the \( l^{th} \) sample \( \theta_l \) from the Dropout distribution. Also, let \( \hat{p} = \frac{1}{L} \sum_{l=1}^{L} p_l \) be the mean prediction. As shown in (Gal et al., 2017), we can approximate the BALD measure using samples from the Dropout distribution as:

\[
\hat{I} = \mathbb{H}(\hat{p}) - \frac{1}{L} \sum_{l=1}^{L} \mathbb{H}(p_l)
\]

where \( \mathbb{H} \) is the binary cross entropy function. The BALD uncertainty score is essentially the difference in entropy of the mean prediction \( \hat{p} \) and the average entropy of the individual predictions \( \{p_l\}_{l=1}^{L} \). Hence, the BALD uncertainty score is high when the metric’s mean prediction is uncertain (high entropy) but the individual predictions are highly confident (low entropy), i.e., when the metric produces disagreeing predictions with high confidence.

**STD:** We also adopt the standard deviation of the preference probability taken over the posterior distribution as a measure of uncertainty:

\[
\sigma = \sqrt{\text{Var}_{\theta \sim p(\theta|\mathcal{D}^{tr})}(\hat{p}(Y_1 > Y_2|\theta))}
\]

Similar to BALD, we can approximate the above measure using the empirical standard deviation of samples drawn from the dropout distribution.

Our proposed algorithm asks for human annotations only if the uncertainty measure (BALD or STD) is above a particular threshold.

4.3 UCB Elimination

The key idea here is to eliminate a set of "poorly performing" NLG systems using the automatic metric and perform human evaluations with the remaining set of systems. To eliminate sub-optimal systems, we first need to quantify a performance measure for the systems. We use the Copeland score (Zoghi et al., 2015) which is defined as the normalized total number of pairwise wins for a system:

\[
C_i = \frac{1}{k-1} \sum_{j \neq i} 1(p_{ij} > \frac{1}{2}).
\]

Copeland score is the highest for the top-ranked system with a value of 1 and it is less than 1 for all other systems. To estimate the Copeland score, we first predict the pairwise preference probability between any two systems \( i \) and \( j \) as follows:

\[
\hat{p}_{ij} = \frac{1}{N} \sum_{Y_1,Y_2 \in \mathcal{D}_{ij}} \hat{p}(Y_1 > Y_2|\theta)
\]

where \( \mathcal{D}_{ij} \) is the test dataset consisting of generated texts from systems \( i \) and \( j \), \( N \) is the total number of test examples, \( \theta \) is the learned model parameters. We can now estimate the Copeland score \( \hat{C}_i \) using the estimated preference \( \hat{p}_{ij} \) and eliminate all systems with Copeland scores below a threshold. However, a major problem with this approach is that evaluation metrics are often inaccurate and we could wrongly eliminate the true top-ranked system without performing any human evaluations. For example, consider the example where \( \hat{r}^* \) is the
top-ranked system with $p_{ij} > 0.51$, $\forall j \in S - i$. If several of the predicted probabilities $p_{ij}$ are less than 0.5, our top-ranked system $i^*$ will receive a low estimated Copeland score and will be incorrectly eliminated. To overcome this problem, we define an Upper Confidence Bound (UCB) on the preference probability using uncertainty estimates that we described in 4.2. Specifically, the upper confidence bound $\hat{u}_{ij}$ is given by $\hat{u}_{ij} = \hat{p}_{ij} + \alpha \hat{\sigma}_{ij}$ where $\alpha$ is a hyperparameter that controls the size of the confidence region and $\hat{\sigma}_{ij}$ is the estimated variance given by:
\[
\hat{\sigma}_{ij}^2 = \frac{1}{N^2} \sum_{Y_1,Y_2 \in \mathcal{D}_{ij}} \text{Var}_{\theta \sim \phi_\theta(y_1 > y_2 | \theta)} \hat{p}(Y_1 > Y_2 | \theta)
\]
where $\phi_\theta(y_1 > y_2 | \theta)$ is the Dropout distribution. Using the upper confidence bound $\hat{u}_{ij}$, we now define the optimistic Copeland score for a system $i$ as $\hat{C}_i^u = \frac{1}{N-1} \sum_{j \neq i} \mathbb{I}(\hat{u}_{ij} > \frac{1}{2})$. Here, we consider a system $i$ to beat another system $j$ ($\hat{u}_{ij} > 0.5$) if either the estimated preference is high ($\hat{p}_{ij}$ is high) or if there is high uncertainty in the estimation ($\hat{\sigma}_{ij}$ is high). In UCB Elimination, we eliminate a system only if the optimistic Copeland score is below a threshold.

5 Experimental Setup

In this section, we describe the (i) NLG tasks and datasets used in our experiments, (ii) automatic evaluation metrics used in our model-based algorithms, and (iii) annotation complexity measure used for comparing dueling bandit algorithms.

5.1 Tasks & Datasets

We use a total of 13 datasets spanning 5 tasks in our experiments which are summarized in Table 1.

| Task               | Dataset                          | # Systems | # Human Annotations |
|--------------------|----------------------------------|-----------|--------------------|
| Machine Translation| WMT15 fin$\rightarrow$eng        | 14        | 31577              |
|                    | WMT15 rus$\rightarrow$eng        | 13        | 44539              |
|                    | WMT15 deu$\rightarrow$eng        | 13        | 40535              |
|                    | WMT16 tur$\rightarrow$eng        | 9         | 10188              |
|                    | WMT16 rom$\rightarrow$eng        | 7         | 15822              |
|                    | WMT16 cze$\rightarrow$eng        | 12        | 125788             |
| Grammatical Error Correction | CoNLL-2014 Shared Task | 10        | 20937              |
| Data-to-Text       | E2E NLG Challenge                | 16        | 17089              |
| Paraphrase         | ParaBank                         | 28        | 151148             |
| Summarization      | TLD$_{\text{OpenAI}}$            | 11        | 4809               |

Table 1: Description of tasks and datasets with the number of NLG systems and pairwise human annotations. The task here is to generate natural language utterance from dialogue acts.

Paraphrase Generation: We use human evaluations of model generated English paraphrases released with the ParaBank dataset (Hu et al., 2019).

Summarization: We use the human evaluations (Stiennon et al., 2020) of GPT3-like transformers on the TL;DR dataset (Völkske et al., 2017). We provide further details including preprocessing steps and downloadable links in appendix A.1.

5.2 Automatic NLG Evaluation Metrics

We can predict the comparison outcome $w$ using two approaches. First, we can use pairwise probability models with existing direct assessment metrics as discussed in section 3. Alternatively, we can train evaluation metrics to directly predict the comparison outcome given pairs of generated texts and context/reference as input. We discuss both these approaches below.

Direct Assessment Metrics: We experiment with a total of 10 direct assessment metrics viz. chrF (Popovic, 2015), BLEU-4 (Papineni et al., 2002), ROUGE-L (Lin, 2004), Embedding Average (Wieting et al., 2016), Vector Extrema (Forgues et al., 2014), Greedy Matching (Rus and Lintean, 2012), Laser (Artetxe and Schwenk, 2019), BertScore (Zhang et al., 2020), MoverScore (Zhao et al., 2019) and Bleurt (Sellam et al., 2020). We mention the implementation details in appendix A.2.

Pairwise Evaluation Metrics: We finetune the pretrained Electra-base transformer model (Clark et al., 2020) to directly predict the comparison outcome $w$. We curate task-specific human evaluation datasets consisting of tuples of the form (context/reference, hypothesis 1, hypothesis 2, label) for finetuning. Due to space constraints, we mention...
We report the annotation complexity of the top 7 best performing dueling bandit algorithms along with the uniform exploration algorithm on 13 datasets spanning 5 NLG tasks.

### Annotation Complexity Measure

To evaluate the performance of dueling bandit algorithms, we define **annotation complexity** as the minimum number of human annotations needed by an algorithm to identify the top-ranked NLG system with high confidence. Let $i^*$ be the actual top-ranked system, and $\hat{i}(n)$ denote the estimated winner by the algorithm after obtaining $n$ human annotations, then query complexity is defined as:

$$\min\ n' : \forall n \geq n', P(\hat{i}(n) = i^*) > 1 - \delta_{acc}$$

where $\delta_{acc}$ is the allowable failure probability *i.e.* the learner can make a mistake with at most $\delta_{acc}$ probability. To compute the annotation complexity, we run each dueling bandit algorithm with 200 different random seeds and find the minimum number of human annotations after which the algorithm correctly returns the top-ranked NLG system in at least 190/200 runs (we set $\delta_{acc} = 0.05$).

### Results & Discussion

We discuss the performance of dueling bandit algorithms in 6.1, automatic metrics in 6.2 and our proposed model-based algorithms in 6.3. Lastly in 6.4, we analyze the variation of annotation complexity with the number of NLG systems.

#### 6.1 Analysis of Dueling Bandit Algorithms

We report the annotation complexity of the top 7 dueling bandit algorithms along with uniform exploration on 13 datasets in table 2. We observe that the annotation complexity of uniform exploration is consistently high across all 13 datasets. In particular, the required human annotations become prohibitively expensive when the number of NLG systems is high, *e.g.* E2E NLG (16 systems) and ParaBank (28 systems) datasets. On the other hand, dueling bandit algorithms such as RUCB (Zoghi et al., 2014b), RCS (Zoghi et al., 2014a), RMED (Komiyama et al., 2015) are able to effectively identify the top-ranked system with much fewer annotations. In particular, RMED performs the best with a reduction of 80.01% in human annotations compared to uniform exploration. We also examine an alternative approach to assess the performance of dueling bandit algorithms. Here, we fix the number of human annotations (fixed annotation budget) and compute the accuracy in predicting the top-ranked system. As we show in figure 2, RMED achieves the highest top-ranked prediction accuracy for any given number of human annotations. We provide the complete results in appendix F.1.

#### 6.2 Performance of Evaluation Metrics

Before we utilize automatic evaluation metrics using our proposed model-based algorithms, we analyze the effectiveness of these metrics for pairwise NLG evaluations. In table 4, we report the sentence-level accuracy in predicting the comparison outcome $w$ using direct assessment metrics with the Linear probability model (as discussed in section 3) along with our trained Electra metric. Across the tasks, we observe that metrics that utilize con-
We compare the annotation complexity of various model-based algorithms in Table 3. We observe that the Random Mixing algorithm with Bleurt and Electra reduces annotation complexity by 70.43% and 73.15%, respectively, when compared to the standard (model-free) RMED algorithm (row 1). Our Uncertainty-aware selection algorithm with the BALD measure further reduces the annotation complexity by around 37% (compared with Random Mixing). We notice that our UCB Elimination algorithm also provides significant improvements over standard RMED. Since UCB Elimination is complementary to Uncertainty-aware selection, we apply both these algorithms together and observe the lowest annotation complexity with a reduction of 89.54% using Electra and 84.00% using Bleurt over standard RMED. Lastly, in figure 3, we analyze the effect of using various automatic evaluation metrics such as BLEU, BertSore, etc., in Random Mixing. Interestingly, we notice that using metrics such as BLEU, which have low accuracy values, results in a higher annotation complexity than standard (model-free) RMED in some datasets. That is, we may even require a greater number of human annotations to over-compensate for the inaccuracy.

6.3 Analysis of Model-based Algorithms

We use our proposed model-based algorithms and incorporate the two best-performing evaluation metrics, viz., Bleurt and Electra with the best performing dueling bandit algorithm, viz., RMED. We compare the annotation complexity of various model-based algorithms in Table 3. We observe that the Random Mixing algorithm with Bleurt and Electra reduces annotation complexity by 70.43% and 73.15%, respectively, when compared to the standard (model-free) RMED algorithm (row 1). Our Uncertainty-aware selection algorithm with the BALD measure further reduces the annotation complexity by around 37% (compared with Random Mixing). We notice that our UCB Elimination algorithm also provides significant improvements over standard RMED. Since UCB Elimination is complementary to Uncertainty-aware selection, we apply both these algorithms together and observe the lowest annotation complexity with a reduction of 89.54% using Electra and 84.00% using Bleurt over standard RMED. Lastly, in figure 3, we analyze the effect of using various automatic evaluation metrics such as BLEU, BertSore, etc., in Random Mixing. Interestingly, we notice that using metrics such as BLEU, which have low accuracy values, results in a higher annotation complexity than standard (model-free) RMED in some datasets. That is, we may even require a greater number of human annotations to over-compensate for the inaccuracy.
rate predictions from metrics like BLEU. However, with Laser, MoverScore, and BertScore, we observe significant reductions in annotation complexity. Please refer appendix F.3 for further results.

6.4 Effect of Number of NLG systems

We analyze how annotation complexity varies with the number of NLG systems. Specifically, we chose a subset of $k$ systems out of the total 28 systems in the ParaBank dataset and computed the annotation complexity among these $k$ systems. As shown in figure 4, the annotation complexity of uniform exploration grows quadratically with $k$ as it explores all system pairs equally. However, for (model-free) dueling bandit algorithms such as RMED, the annotation complexity is much lower and only varies as $O(k)$. As shown in appendix F.4, we observed similar trends with model-based algorithms.

7 Practical Recommendations

We summarize the key insights from this study and provide practical recommendations on efficiently identifying the top-ranked NLG system.

1. Use RMED dueling bandit algorithm to actively choose system pairs for comparison.

2. If human evaluation datasets are available, train a metric to predict the comparison outcome directly. Otherwise, use Bleurt with any of the Linear, BTL, BTL-logistic models.

3. Manually annotate a few examples from the test dataset and evaluate the sentence-level accuracy of the metric. If the performance is poor (e.g., accuracy near the random baseline), do not use model-based approaches, obtain feedback only from human annotators.

4. If the metric is reasonably accurate, use UCB Elimination with Uncertainty-aware Selection (BALD). Tune the hyperparameters of these algorithms, if possible. Otherwise, refer appendix D for best practices developed based on analyzing the sensitivity of model-based algorithms to hyperparameters.

5. We can reduce the annotation time if we use multiple annotators in parallel. We observed that dueling bandit algorithms, though originally proposed for sequential annotations, are robust to asynchronous feedback from multiple annotators (Refer appendix E for details).

8 Related Work

Several works (Bojar et al., 2014, 2015; Sakaguchi et al., 2014, 2016) in Machine translation and Grammatical Error Correction adopt the TrueSkill algorithm (Herbrich et al., 2006), originally used for ranking Xbox gamers, to efficiently rank NLG systems from pairwise annotations. A recent work (Sakaguchi and Durme, 2018) proposes an online algorithm to rank NLG systems when we receive pairwise preference feedback in the form of a continuous scalar with bounded support. The key difference in our work is that we focus on the problem of identifying the top-rank system instead of ranking all the systems. Experimental study of dueling bandit algorithms have been limited to synthetic simulations in a few works (Yue and Joachims, 2011; Urvoy et al., 2013). Most others (Zoghi et al., 2014b,a; Komiyama et al., 2015; Zoghi et al., 2015; Wu and Liu, 2016) focus on information retrieval applications that involve evaluating search retrieval algorithms (Radlinski et al., 2008). To the best of our knowledge, ours is the first work to extensively study the effectiveness of dueling bandit algorithms for NLG evaluation.

9 Conclusion & Future work

In this work, we focused on the problem of identifying the top-ranked NLG system with few pairwise annotations. We formulated this problem in an Active Evaluation framework and showed that dueling bandit algorithms can reduce the number of human annotations by 80%. We then proposed model-based algorithms to combine automatic metrics with human evaluations and showed that human annotations can be reduced further by 89%; thereby requiring only a few hundred human annotations to identify the top-ranked system. In future work, we would like to extend our analysis to the general problem of finding the top-k ranked systems.
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A Further Details on Experiments

A.1 Tasks & Datasets

In table 5, we report the dataset statistics along with links to download the original datasets. We now discuss the preprocessing steps:

**Machine Translation:** In WMT 2015 and 2016 tasks, human annotators were asked to rank five system outputs (translated sentences) relative to each other. As recommended by the organizers (Bojar et al., 2014), we convert each of these rankings into \( \binom{5}{2} \) pairwise comparisons of systems.

**Grammatical Error Correction:** The Grammarly evaluation datasets follow the RankME (Novikova et al., 2018) annotation style where annotators were shown 8 outputs side by side for each input and were asked to provide a numerical score to each of them. We discarded one of the outputs out of the 8, which was human crafted, and used the remaining 7 model-generated outputs. We then convert these 7 scores into \( \binom{7}{2} \) pairwise comparisons of systems. Human evaluations of the CoNLL-2014 Shared Task followed the same process as WMT 2015. Hence, we follow the same preprocessing steps as WMT.

**Data-to-Text Generation:** The E2E NLG Challenge also follows the RankME annotation format. We follow the same preprocessing steps as the Grammarly datasets. Out of the total 21 systems, we held out 5 systems to train the Electra model and use the remaining 16 systems.

**Paraphrase Generation:** For ParaBank, we follow the same preprocessing steps as the Grammarly datasets. Out of the total 35 systems, we held out 7 systems and only used the remaining 28 systems.

**Summarization:** We select 11 systems that have human annotations between each pair of them. These systems are GPT3-like models with varying model sizes (3B, 6B, 12B) and training strategies. We do not perform any additional preprocessing here.

A.2 Direct Assessment Metrics: Implementation Details

We use the nlg-eval library\(^2\) for the implementation of BLEU-4, ROUGE-L, Embedding Average, Vector Extrema, and Greedy Matching. For chrF, Laser and BertScore, we use the implementations from the VizSeq library \(^3\). We use the official implementation released by the original authors for Mover-

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\(^2\)https://github.com/Maluuba/nlg-eval

\(^3\)https://github.com/facebookresearch/vizseq

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A.3 Finetuning Datasets

Here, we describe the task-specific datasets used for finetuning the Electra model (pairwise evaluation metric described in section 5.2). For MT, we used human evaluations of WMT 2013 and 2014, consisting of a total of 650k examples. For GEC, we curated a training dataset of 180k pairs of texts and human preference using data released by (Napoles et al., 2013b) and the development set released by (Napoles et al., 2019). We utilize 11k examples from 5 held-out systems in the E2E NLG Challenge (apart from the 16 systems used for evaluations) for Data-to-Text generation. Lastly, we use a dataset of 180k examples from 7 held-out systems in the ParaBank dataset for paraphrase generation. We use 90% - 10% split for splitting the dataset into train and validation sets. Note that these datasets do not have any overlap with the datasets used for evaluating dueling bandit algorithms.

A.4 Finetuning Details

We use the pretrained Electra-base model (Clark et al., 2020) with 110M parameters (12 layers and 12 attention heads) as our base model. We finetune the model using ADAM optimizer with \( \beta_1 = 0.9 \) and \( \beta_2 = 0.99 \). We use a linear learning rate decay with a maximum learning rate of 1e-5 and warm-up for 10% of training. We use a batch size of 128 and finetune for four epochs. We finetune all the models on Google Cloud TPU v3-8. To estimate prediction, we apply Dropout to the Electra model during test time as described in 4.2.

B Summary of Dueling Bandit Algorithms

We now provide an overview of various dueling bandit algorithms in the literature. We first introduce a few additional notations and terminologies in B.1. Later in B.2, we describe the various structural assumptions made by different dueling bandit algorithms. Finally, in B.3, we summarize 13 dueling bandit algorithms that we analyze in this work.
Table 5: Description of tasks and datasets with the number of NLG systems, number of pairwise human annotations, label distribution and the downloadable links to the datasets before preprocessing

| Task               | Dataset               | # Systems | # Human Annotations | Label Distrib. (0-0.5-1) | Downloadable Link |
|--------------------|-----------------------|-----------|---------------------|--------------------------|-------------------|
| Machine Translation| WMT15 fr-en           | 14        | 31577               | 37%-26%-37%              | Click here        |
|                    | WMT15 es-en           | 13        | 44539               | 36%-27%-37%              |                   |
|                    | WMT15 deu-en          | 13        | 40558               | 32%-36%-32%              |                   |
|                    | WMT16 tur-en          | 9         | 10188               | 28%-44%-28%              |                   |
|                    | WMT16 ro-en           | 7         | 15822               | 38%-24%-38%              |                   |
|                    | WMT16 cs-en           | 12        | 125788              | 38%-25%-37%              |                   |
|                    | WMT16 deu-en          | 10        | 20937               | 37%-26%-37%              |                   |
| Grammatical Error  | Grammarly (FCE)       | 7         | 20328               | 29%-40%-31%              | Click here        |
| Correction         | Grammarly (Wiki)      | 7         | 20832               | 29%-40%-31%              |                   |
| Data-to-Text       | E2E NLG Challenge     | 16        | 17089               | 24%-50%-26%              | Click here        |
| Paraphrase         | ParaBank              | 28        | 151148              | 44%-2%-54%               | Click here        |
| Summarization      | TLDR OpenAI           | 11        | 4809                | 49%-0%-51%               | Click here        |

B.1 Notations and Terminologies

Let $\Delta_{ij} = p_{ij} - \frac{1}{2}$ where $p_{ij}$ is the preference probability of system $i$ over $j$, as defined in section 2.3. We call a system as the Copeland winner if it beats more number of systems than any other system. Mathematically, a Copeland winner $i^*$ is defined as $i^* = \arg \max_i \sum_{j=1}^{k} 1 (\Delta_{ij} > 0)$. A special case of the Copeland winner is the Condorcet winner, which is the system that beats all other systems. In all our NLG tasks and datasets, we observed that this special case holds true i.e. there exists a system that beats all other $k - 1$ systems, and we define it as the top-ranked system. Nevertheless, we mention these two definitions to distinguish algorithms that work for the general Copeland winner, even if the Condorcet winner does not exist.

B.2 Assumptions

All the dueling bandit algorithms that we analyze in this work assume a stochastic feedback setup in which the feedback is generated according to an underlying (unknown) stationary probabilistic process. Specifically, in our Active Evaluation framework, this is equivalent to assuming that the annotator preference is stationary over time and is given by some fixed distribution $p_0(w|Y_1^{(t)}, Y_2^{(t)})$. Further, many dueling bandit algorithms make various assumptions on the true pairwise preferences and exploit these assumptions to derive theoretical guarantees (Bengs et al., 2021). In table 6, we describe the various commonly used assumptions by dueling bandit algorithms. For example, the stochastic triangle inequality assumption (STI), described in row 4 of table 6, assumes that the true preference probabilities between systems obey the triangle inequality. We note here that one cannot verify the validity of these assumptions apriori since we do not have access to the true preferences.

B.3 Algorithms

In table 7, we describe the various dueling bandit algorithms along with the assumptions (used to provide theoretical guarantees) and the target winner. We summarize these algorithms below:

IF: Interleaved Filtering (IF) (Yue et al., 2012) algorithm consists of a sequential elimination strategy where a currently selected system $s_i$ is compared against the rest of the active systems (not yet eliminated). If the system $s_j$ beats a system $s_i$ with high confidence, then $s_i$ is eliminated, and $s_j$ is compared against all other active systems. Similarly, if the system $s_j$ beats $s_j$ with high confidence, then $s_j$ is eliminated, and $s_i$ is continued to be compared against the remaining active systems. Under the assumptions of TO, SST, and STI, the authors provide theoretical guarantees for the expected regret achieved by IF.

BTM: Beat The Mean (BTM) (Yue and Joachims, 2011), similar to IF, is an elimination-based algorithm that selects the system $s_i$ with the fewest comparisons and compares it with a randomly chosen system from the set of active systems. Based on the comparison outcome, a score and confidence interval are assigned to the system $s_i$. BTM eliminates a system as soon as there is another system with a significantly higher score.
Knockout, Seq Elim, Single Elim: Knockout (Falahatgar et al., 2017b), Sequential Elimination (Falahatgar et al., 2017a), Single Elimination (Mohajer et al., 2017) are all algorithms that proceed in a knockout tournament fashion where the systems are randomly paired, and the winner in each duel will play the next round (losers are knocked out) until the overall winner is determined. During a duel, the algorithm repeatedly compares the two systems to reliably determine the winner. The key difference between the three algorithms is the assumptions they use and how they determine the number of comparisons required to identify the winning system in a duel with high probability.

Plackett Luce: Plackett Luce Condorcet winner identification algorithm (Szörényi et al., 2015) assumes that the true rank distribution follows the Placket-Luce model (Plackett, 1975). The algorithm is based on a budgeted version of QuickSort. The authors show that it achieves a worst-time average complexity of the order $k \log k$ under the Placket-Luce assumption.

RUCB: Relative Upper Confidence Bound (RUCB) (Zoghi et al., 2014b) is an adaptation of the well-known UCB algorithm (Auer et al., 2002) to the dueling bandit setup. Similar to UCB, RUCB selects the first system $s_1^{(1)}$ based on "optimistic" estimates of the pairwise preference probabilities $i.e.$ based on an upper confidence bound of preference probabilities. The second system $s_2^{(2)}$ is chosen to be the one that is most likely to beat $s_1^{(1)}$.

RCS: Relative Confidence Sampling (RCS) (Zoghi et al., 2014a) follows a Bayesian approach by maintaining a posterior distribution over the preference probabilities. At each time step $t$, the algorithm samples preference probabilities from the posterior and simulates a round-robin tournament among the systems to determine the Condorcet winner. The estimated Condorcet winner is chosen as the first system $s_1^{(1)}$ and second system $s_2^{(2)}$ is chosen such that it has the best chance of beating $s_1^{(1)}$.

RMED: Relative Minimum Empirical Divergence I (RMED) algorithm (Komiyama et al., 2015) maintains an empirical estimate of the "likelihood" that a system is the Condorcet winner. It then uses this estimate to sample the first system $s_1^{(1)}$ and then selects the second system $s_2^{(2)}$ that is most likely to beat $s_1^{(1)}$.

SAGE: Sensitivity Analysis of Variables for Generic Exploration (SAGE) (Urvoy et al., 2013) is a generic algorithm that can be adopted for various ranking problems such as Copeland winner identification. SAGE (Copeland) algorithm, at each time step, randomly samples a pair of systems from the set of active system pairs (not yet eliminated) and updates the preference estimates. A system pair $(s_i, s_j)$ is eliminated if either (i) the result of comparison between $s_i$ and $s_j$ is already known with high probability, or (ii) there exists some system $s_k$ where the estimated Copeland score of $s_k$ is significantly higher than $s_i$ or $s_j$.

CCB: Copeland Confidence Bound (CCB) (Zoghi et al., 2015) is similar to the RUCB algorithm but is designed to identify the Copeland Winner (a generalization of the Condorcet winner). The CCB algorithm maintains optimistic preference estimates and uses them to choose the first system $s_1^{(1)}$ and then selects the second system $s_2^{(2)}$ that is likely to discredit the hypothesis that $s_1^{(1)}$ is indeed the Copeland winner. The algorithm successively removes all other systems that are highly unlikely to be a Copeland winner.

Table 6: Various assumptions made by dueling bandit algorithms in the literature

| Algorithm | Assumptions | Target |
|-----------|-------------|--------|
| IF (Yue et al., 2012) | TO+SST+STI | Condorcet |
| Seq-Elim. (Falahatgar et al., 2017a) | SST | Condorcet |
| Plackett Luce (Szörényi et al., 2015) | PL model | Condorcet |
| Knockout (Falahatgar et al., 2017b) | SST+STI | Condorcet |
| Single Elim. (Mohajer et al., 2017) | TO | Condorcet |
| RUCB (Zoghi et al., 2014b) | CW | Condorcet |
| RCS (Zoghi et al., 2014a) | CW | Condorcet |
| RMED (Komiyama et al., 2015) | CW | Condorcet |
| SAVAGE (Urvoy et al., 2013) | - | Copeland |
| CCB (Zoghi et al., 2015) | - | Copeland |
| DTS (Wu and Liu, 2016) | - | Copeland |
| DTS++ (Wu and Liu, 2016) | - | Copeland |
DTS, DTS++: The Double Thompson Sampling (DTS) algorithm (Wu and Liu, 2016) maintains a posterior distribution over the pairwise preference matrix, and selects the system pairs \( s_{i}^{(1)}, s_{i}^{(2)} \) based on two independent samples from the posterior distribution. The algorithm updates the posterior distributions based on the comparison outcome and eliminates systems that are unlikely to be the Copeland winner. DTS++ is an improvement proposed by the authors, which differs from DTS in the way the algorithm breaks ties. Both have the same theoretical guarantees, but DTS++ has been empirically shown to achieve better performance (in terms of regret minimization).

C Hyperparameters Details

We discuss the details of the hyperparameters and the tuning procedure used for dueling bandit algorithms in C.1, pairwise probability models in C.2 and our model-based algorithm in C.3. In all three cases, we use the validation split of the finetuning datasets described in A.3 as our validation dataset. For example, the validation split of the finetuning datasets for MT consists of 10% of the WMT 2013 and 2014 datasets. We use this dataset to tune the hyperparameters for WMT 2015 and 2016 datasets.

C.1 Dueling Bandit Algorithms

For all algorithms other than Knockout and Single Elimination, we use the hyperparameters recommended by the original authors for all the datasets. For example, in the RMed algorithm, described in algorithm 1 of (Komiyama et al., 2015), we use \( f(K) = 0.3K^{1.01} \) as suggested by the authors. For the RCS algorithm, described in algorithm 1 of (Zoghi et al., 2014a), we use \( \alpha \) (exploratory constant) = 0.501. For RUCB (algorithm 1 of (Zoghi et al., 2014b)), we use \( \alpha = 0.51 \). Similarly, for all algorithms other than Knockout and Single Elimination, we use the recommended hyperparameters mentioned in the original paper. For Knockout and Single Elimination, we found that the performance was very sensitive to the hyperparameters. For these two algorithms, we manually tuned the hyperparameters on the validation set. In Knockout, algorithm 3 of (Falahatgar et al., 2017b), we use \( \epsilon = 0.2, \delta = 0.05, \gamma = 1.0 \) for WMT’16 ron-eng and TLDR OpenAI datasets. We use \( \epsilon = 0.2, \delta = 0.05, \gamma = 0.6 \) for ParaBank and Grammarly-Wiki datasets and \( \epsilon = 0.2, \delta = 0.09, \gamma = 0.6 \) for all other datasets. In Single Elimination, we use \( m \) (number of pairwise comparisons per duel) = 1000 for WMT’16 ron-eng, E2E NLG, Grammarly-FCE, \( m = 1500 \) for CoNLL’14 shared task and \( m = 500 \) for all other datasets.

C.2 Pairwise Probability Models

Let \( \tilde{f}(Y) \) be the unnormalized score given an automatic evaluation metric for an hypothesis \( Y \). We preprocess the score \( \tilde{f}(Y) \) to obtain \( f(Y) \) to ensure that the pairwise probability scores is always a valid i.e. lies between 0 and 1. To preprocess the scores, we use the validation dataset consisting of tuples of the form \( \{Y_1^{(i)}, Y_2^{(i)}, w^{(i)}\}_{i=1}^N \) where \( Y_1^{(i)}, Y_2^{(i)} \) represent the ith generated texts and \( w^{(i)} \) is the corresponding comparison outcome provided by human annotators.

- **Linear**: \( \Delta_i = |\tilde{f}(Y_1^{(i)}) - \tilde{f}(Y_2^{(i)})| \) and \( \Delta = \max_i \Delta_i \). We divide the unnormalized \( \tilde{f}(Y) \) scores by \( 2\Delta \) i.e.
  \[
  f(Y) = \frac{\tilde{f}(Y)}{2\Delta}.
  \]

- **BTL**: \( f_m = \max\{\tilde{f}(Y_1^{(i)}), \tilde{f}(Y_2^{(i)})\} \), \( f_m = \max_i f_m^i \). We now subtract the scores by \( f_m \) to ensure that the scores are non-negative i.e.
  \[
  f(Y) = \frac{\tilde{f}(Y) - f_m}{\gamma}
  \]

We tune \( \gamma \) using grid search between 0.005 and 1 on the validation set to minimize the cross-entropy loss between the preference probabilities \( \tilde{p}(Y_1 > Y_2) \) and the human labels \( w \).

**Thresholds**: As described in section 3, we threshold the preference probabilities \( \tilde{p}(Y_1 > Y_2) \) at two thresholds \( \tau_1 \) and \( \tau_2 \) to obtain the predicted comparison outcome \( \tilde{w} \). We perform a grid search by varying \( \tau_1 \) from 0.4 to 0.5 and \( \tau_2 \) from 0.5 to 0.6 with a step size of 0.001. We choose the optimal thresholds that maximize the prediction accuracy on the validation dataset.
C.3 Model-based Algorithms

We manually tune the hyperparameters in our model-based algorithms on the validation dataset. For clarity, we first describe the hyperparameters in the different model-based algorithms. In Random Mixing, we need to choose the mixing probability \( p_m \) hyperparameter. In Uncertainty-aware Selection (BALD), we need to choose a threshold value \( \tau_{BALD} \) for the BALD score at which we decide to ask for human annotations. For UCB elimination, we should choose a threshold \( \tau_{cop} \) for optimistic Copeland scores and the \( \alpha \) hyperparameter, which controls the size of the confidence region. In tables 8 and 9, we report the tuned hyperparameter values when using Electra and Bleurt (with the Linear probability model) as the evaluation model. Another hyperparameter is the number of Monte-Carlo samples \( L \) to obtain from the Dropout distribution as discussed in section 4.2. We set \( L = 20 \), i.e. we independently apply dropout 20 times for each test predictions.

D Effect of Hyperparameters in Model-based Algorithms

D.1 Sensitivity to Hyperparameters

We study how hyperparameters in our proposed model-based algorithms affect annotation complexity. Recall that in Random Mixing, the mixing probability \( p_m \) controls the ratio of real and model-generated feedback given to the learner. In Uncertainty-aware Selection (BALD), we obtain human annotations when the BALD score is above a threshold \( \tau_{BALD} \). Here, as well \( \tau_{BALD} \) implicitly controls the fraction of real and predicted feedback. In figure 5, we show the effect of \( p_m \) in Random Mixing with Bleurt and \( \tau_{BALD} \) in Uncertainty-aware Selection with Bleurt. We observe that with increases in both the hyperparameters, the annotation complexity decreases, i.e., with a greater amount of feedback received from Bleurt, the number of required human annotations is lower. However, as shown in figure 6, we observe the opposite trend when we use metrics such as BLEU, which are highly inaccurate. In these cases, we require a greater number of human annotations to compensate for the highly erroneous feedback received from the evaluation metric. Therefore, the optimal mixing probability \( p_m \) in such cases is close to 0 i.e. equivalent to the model-free case. For moderately accurate metrics such as Laser, we observed the optimal \( p_m \) was close to 0.4 to 0.6. The key insight from these observations is that the higher the accuracy of the metric, the higher amount of feedback can be obtained from the metric to identify the top-ranked system. In figure 7, we analyze how the annotation complexity of UCB Elimination with Bleurt varies with the optimistic Copeland threshold \( \tau_{cop} \) hyperparameter. We fixed \( \alpha \) hyperparameter to 0.6. We observed that UCB Elimination is much more robust to \( \tau_{cop} \) and a general value of \( \tau_{cop} = 0.8 \) worked well across all datasets and metrics.

D.2 Best Practices in Choosing Hyperparameters

The optimal approach to choose hyperparameters is usually to tune them on a validation set. But, at
times, it may not be possible either because of computational reasons or because a human-annotated validation dataset may not be available. In such cases, we provide a few heuristics based on our previous analysis to choose hyperparameters in our model-based algorithms:

1. Choose the mixing probability $p_m$ in Random Mixing proportionately with the accuracy of the metric. For example, we observed that for metrics with sentence-level prediction accuracy greater than 70%, $p_m = 0.8$ tend to work well. For accuracy between 65% to 70%, $p_m$ in the range of 0.5-0.7 worked well.

2. Once we choose a value of $p_m$, we can find an appropriate BALD threshold $\tau_{BALD}$ where $100 \times p_m \%$ of BALD scores are above $\tau_{BALD}$ and $100 \times (1-p_m) \%$ of BALD score are below $\tau_{BALD}$. Choosing the BALD threshold this way ensures that we can directly control the desired amount of model-predicted feedback given to the learner.

3. For UCB Elimination, we recommend using the default values of $\alpha = 0.6$ and $\tau_{cop} = 0.8$, which we found to work well across tasks and metrics.

## Additional Results

### F.1 Results of Dueling Bandit Algorithms

We report the annotation complexity of all 13 dueling bandit algorithms on 13 evaluation datasets in Table 10. In Figure 10, we show the top-rank prediction accuracy as a function of the number of human annotations for various dueling bandit algorithms on all the datasets, other than WMT 16 tur-eng, which is separately depicted in Figure 2.
Table 10: Annotation complexity of 13 dueling bandit algorithms along with the uniform exploration algorithm on 13 datasets spanning 5 NLG tasks.

| Metrics | WMT (Micro Average) | Grammatically | CoNLL-2014 | E2E NLG | ParaBank | TLDR OpenAI |
|---------|----------------------|---------------|------------|----------|----------|-------------|
|         | Linear | BTL | Log. | Linear | BTL | Log. | Linear | BTL | Log. | Linear | BTL | Log. | Linear | BTL | Log. | Linear | BTL | Log. | Linear |
| ChrF    | 62.6   | 62.0 | 62.6 | 75.7   | 73.5 | 75.9 | 78.4   | 78.3 | 78.4 | 47.4   | 48.8 | 48.3 | 66.1   | 66.1 | 66.1 | 34.2   | 35.4 | 35.4 |
| Bleu-4  | 41.5   | 53.4 | 41.5 | 73.2   | 73.0 | 73.2 | 78.9   | 78.7 | 78.9 | 45.0   | 45.0 | 50.1 | 63.8   | 63.2 | 63.8 | 42.8   | 44.0 | 42.8 |
| Rouge-L | 60.7   | 60.0 | 60.7 | 73.5   | 73.6 | 73.6 | 78.0   | 78.0 | 78.0 | 44.6   | 43.8 | 50.2 | 64.3   | 64.3 | 64.3 | 43.3   | 43.3 | 43.3 |
| Emb. Avg.| 56.5   | 59.1 | 57.5 | 70.1   | 70.3 | 71.5 | 76.0   | 76.7 | 77.0 | 49.8   | 51.6 | 51.8 | 64.9   | 64.9 | 64.9 | 38.2   | 38.2 | 38.2 |
| Greedy Match | 59.5   | 59.8 | 59.9 | 68.1   | 68.4 | 68.2 | 77.7   | 77.4 | 77.7 | 46.5   | 48.8 | 48.9 | 64.7   | 64.7 | 64.7 | 43.1   | 43.1 | 43.1 |
| Vector Exr | 59.4   | 59.5 | 59.3 | 66.0   | 66.3 | 66.5 | 76.3   | 76.7 | 76.7 | 44.9   | 46.2 | 49.1 | 63.7   | 63.7 | 63.7 | 47.4   | 47.1 | 48.1 |
| BertScore | 65.9   | 66.2 | 65.9 | 77.4   | 77.2 | 77.4 | 82.0   | 81.5 | 82.0 | 45.9   | 49.3 | 50.1 | 68.1   | 68.1 | 68.1 | 44.5   | 48.4 | 44.5 |
| Laser    | 65.3   | 65.1 | 65.3 | 75.1   | 73.0 | 75.1 | 78.0   | 76.4 | 78.0 | 47.2   | 49.9 | 50.5 | 67.0   | 67.0 | 67.0 | 35.4   | 35.4 | 35.4 |
| MoverScore | 66.1   | 66.5 | 66.1 | 74.7   | 70.9 | 73.0 | 80.6   | 79.6 | 80.3 | 50.1   | 49.3 | 50.4 | 68.0   | 68.0 | 67.8 | 40.7   | 40.7 | 40.7 |
| Bleurt   | 68.2   | 67.9 | 68.2 | 77.1   | 76.0 | 76.0 | 81.5   | 81.5 | 80.8 | 48.1   | 50.4 | 50.4 | 67.7   | 67.7 | 67.7 | 42.5   | 42.5 | 42.3 |
| Electra  | 65.7   | 74.0 | 74.0 | 81.1   | 81.6 | 81.6 | 54.3   | 81.7 | 81.7 | 42.5   | 42.5 | 42.5 |

Table 11: Sentence-level accuracy of direct assessment metrics with linear, BTL, and BTL-logistic probability models and our trained Electra metric in predicting the comparison outcome.

Figure 10: Top-rank prediction accuracy as a function of the number of human annotations for (model-free) Uniform exploration and RUCB, RCS, and RMED dueling bandit algorithms on 12 NLG datasets.
To further illustrate this, we plot the accuracy on the WMT datasets in figure 9 and observe that the performance across the three probability models is largely similar across Linear, BTL, and BTL-logistic models.

### F.2 Performance of Evaluation Metrics

In table 11, we report the sentence-level accuracy in predicting the comparison outcome for 10 direct assessment metrics using three probability models along with the trained pairwise metric (Electra). We observe that there is little variation in performance across the three probability models. To further illustrate this, we plot the accuracy on the WMT datasets in figure 9 and observe that the performance is largely similar across Linear, BTL, and BTL-logistic models.

### F.3 Model-based Algorithms

In figure 11, we show the top-rank prediction accuracy as a function of the number of human annotations for various model-based algorithms using the Electra metric with uniform exploration and dueling bandit algorithms as function of number of NLG systems. Further, when we use UCB Elimination with Uncertainty-aware Selection, the UCBA Elimination with Uncertainty-aware Selection has significantly higher prediction accuracy than model-free RMED for any given number of human annotations. Further, when we use UCB Elimination with Uncertainty-aware Selection, we observe the highest top-rank prediction accuracy for any given number of annotations.

### F.4 Effect of number of NLG systems

In figure 12, we compare the variations in annotation complexity of Random Mixing and Uncertainty-aware Selection (BALD) algorithms have significantly higher prediction accuracy than model-free RMED for any given number of human annotations. Further, when we use UCB Elimination with Uncertainty-aware Selection, we observe the highest top-rank prediction accuracy for any given number of annotations.