Sensory and Motor Systems

Decreased Dorsomedial Striatum Direct Pathway Neuronal Activity Is Required for Learned Motor Coordination

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Visual Abstract

It has been suggested that the dorsomedial striatum (DMS) is engaged in the early stages of motor learning for goal-directed actions, whereas at later stages, control is transferred to the dorsolateral striatum (DLS), a process that enables learned motor actions to become a skill or habit. It is not known whether these striatal regions are simultaneously active while the expertise is acquired. To address this question, we developed a mouse “Treadmill Training Task” that tracks changes in mouse locomotor coordination during running practice and simultaneously provides a means to measure local neuronal activity using photometry. To measure change in motor coordination over treadmill practice sessions, we used DeepLabCut (DLC) and custom-built code to analyze body position and paw movements. By evaluating improvements in motor coordination during

Significance Statement

Motor disorders, including Parkinson’s disease, present with several motor dysfunction, including degradation of motor learning. While individuals with Parkinson’s disease are able to learn, certain aspects of learning, especially automatic responses to feedback, are damaged. Our current knowledge of motor learning comes from studies on models of motor dysfunction or analysis of simple in-laboratory skills that may not apply to more complex skills. In this work, we developed the “Treadmill Training Task” to track changes in mouse locomotor coordination during practice at running that simultaneously provides a means to measure local neuronal activity using photometry. This work will assist in the development of more efficient therapies for motor impairments because of a multitude of condition, including Parkinson’s disease.
training with simultaneous neuronal calcium activity in the striatum, we found that DMS direct pathway neurons exhibited decreased activity as the mouse gained proficiency at running. In contrast, direct pathway activity in the DLS was similar throughout training. Pharmacological blockade of D1 dopamine receptors in these subregions during task performance demonstrated that dopamine neurotransmission in the direct pathway activity is necessary for efficient motor coordination learning. These results provide new tools to measure changes in fine motor skills with simultaneous recordings of brain activity and reveal fundamental features of the neuronal substrates of motor learning.

Key words: direct pathway; dopamine; motor learning; skill acquisition; striatum; treadmill

Introduction

Neural circuits in the striatum are central to basal ganglia functions, including the learning and organization of motor skills. The development of techniques to record the activity of specific populations of neurons in the striatum along with pharmacological or genetic models of motor disorders has revealed new details about the pathways that underlie motor performance and motor learning. The dorsal portion of the striatum has been found to be particularly important for expressing automatic actions (Yin et al., 2009). In rodents, this region is typically separated into two major regions: the dorsomedial striatum (DMS) and the dorsolateral striatum (DLS), corresponding to the human caudate and putamen, respectively. The DMS receives afferents from prefrontal and associative cortices, while the DLS mostly receives input from sensorimotor cortical areas (Graybiel, 2008; Hunnicutt et al., 2016; Cataldi et al., 2022).

In vivo electrophysiological recordings indicate that the DMS is engaged in early training on a rotarod (Yin et al., 2009; Lingawi and Balleine, 2012), a task commonly used to study motor coordination, while the DLS is particularly active later in training. A recent study that analyzed corticostriatal synaptic responses in brain slices prepared from mice trained on the rotarod indicated a transient decrease in postsynaptic response by DMS striatal spiny projection neurons (SPNs) following training (Badreddine et al., 2022). However, single unit recording during a lever press task showed a similar activity pattern in DLS and DMS after this skill was acquired (Vandaele et al., 2019).

Materials and Methods

Animals

Wild-type (WT) and transgenic mice expressing Cre-recombinase in D1-expressing SPNs (D1-cre) were used for these experiments. All animal procedures were approved...
by the Institutional Animal Care and Use Committee of the New York State Psychiatric Institute. Experiments were performed on three- to six-month-old male and female mice. C57BL/6 mice from The Jackson Laboratory (Jax #000664) were used as control animals. D1-Cre transgenic mice were obtained from MMRC/Jax (ey262 D1-crc tgdrla-cre) and crossed with C57BL/6 mice. AAV vectors containing Cre-inducible GCaMP6f (AAV.Syn.Flex.GCaMP6f.WPRE.SV40, Addgene; Titre ≥ 2.1 × 10^13 GC/ml) were injected into the right DLS or DMS by stereotaxic surgery. During the surgery, a small skull craniotomy (1 × 1 mm) above the injection site was opened with a dental drill. A glass pipette attached to a Nanoject II (Drummond Scientific) was filled with the GCaMP6f AAV and lowered to target locations in the dorsomedial or DLS (tip coordinates from bregma: AP −0.5 mm, ML +2.5 DV −3.2 mm for DLS, AP +1.2 mm ML −0.8 mm DV −2.8 mm for DMS). A total volume of 150 nl AAV vector per site was injected over 10 min. The pipette was left in place for five more minutes before removal. A 4-mm-long 300-μm diameter optic fiber (Doric Lenses; MFC 300/370-0.22_4 mm_MF2.5_FLT) was subsequently lowered to the same coordinates. The skull was then covered with dental acrylic to secure the optic fiber in place. Alternatively, opto-fluid cannulas (Doric Lenses; OmFC_MF1.25_300/370-0.22_4.2_FLT_4) were implanted for simultaneous GCaMP6f recording and local microinjection of drug or saline. Animals were allowed to recover, and photometry experiments were performed four weeks after surgery, for optimal viral expression. Three to 5 d before running on the treadmill, animals were placed in an open field chamber to record baseline calcium signals and habituate to the tethered optical fiber.

**Viral expression of GCaMP6f and fiber implants**

To achieve neuronal subtype-specific expression of the genetically encoded calcium sensor GCaMP6f in direct pathway SPNs, AAV vectors containing Cre-inducible GCaMP6f (AAV.Syn.Flex.GCaMP6f.WPRE.SV40, Addgene; Titre ≥ 2.1 × 10^13 GC/ml) were injected into the right DLS or DMS by stereotaxic surgery. During the surgery, a small skull craniotomy (1 × 1 mm) above the injection site was opened with a dental drill. A glass pipette attached to a Nanoject II (Drummond Scientific) was filled with the GCaMP6f AAV and lowered to target locations in the dorsomedial or DLS (tip coordinates from bregma: AP −0.5 mm, ML +2.5 DV −3.2 mm for DLS, AP +1.2 mm ML −0.8 mm DV −2.8 mm for DMS). A total volume of 150 nl AAV vector per site was injected over 10 min. The pipette was left in place for five more minutes before removal. A 4-mm-long 300-μm diameter optic fiber (Doric Lenses; MFC 300/370-0.22_4 mm_MF2.5_FLT) was subsequently lowered to the same coordinates. The skull was then covered with dental acrylic to secure the optic fiber in place. Alternatively, opto-fluid cannulas (Doric Lenses; OmFC_MF1.25_300/370-0.22_4.2_FLT_4) were implanted for simultaneous GCaMP6f recording and local microinjection of drug or saline. Animals were allowed to recover, and photometry experiments were performed four weeks after surgery, for optimal viral expression. Three to 5 d before running on the treadmill, animals were placed in an open field chamber to record baseline calcium signals and habituate to the tethered optical fiber.

**Custom-built treadmill**

To precisely control the animal’s locomotion, mice were placed on a custom motorized treadmill (Extended Data Fig. 1-1A). The treadmill consisted of a 1-m clear belt stretched between two 3 inch diameter acrylic wheels on an aluminum frame (8020.net). Treadmill speed was controlled by an Arduino-based system (OpenMaze.org, OM4 board) that adjusted the speed of a 12 V gear motor attached to the axle of one of the treadmill wheels through pulse-width modulation (PWM). Belt speed was measured using a quadrature rotary encoder (Digikey #ENS1J) attached to the other axle and decoded by the Arduino. The Arduino/OpenMaze setup was also used to send synchronization pulses to coordinate behavior with video recording and fiber photometry. Mouse movement on the treadmill was constrained by placing the mouse into a six-inch-long clear acrylic box over the center of the treadmill and covering the entire width of the belt, which ensured the animal was walking along the belt to avoid being forced into the back wall during belt movement. An acrylic mirror was fixed at a 45° angle under the clear acrylic box and mesh belt to allow high speed videography of the animal’s locomotion from lateral and ventral viewpoints simultaneously.

**Treadmill Training Task**

Mice undergoing experimental procedures were weighed before testing. All tests were performed in the morning between 9:30 A.M. and 1:30 P.M., during the animals’ typical awake phase. All animals were assessed at four to six months of age, and all experimentation and analysis were conducted with the experimenter blinded to the location of the implant or condition. After 3-d familiarization to experimenter handling, mice underwent the following training paradigm.

Mice were placed on the treadmill within the clear inbuilt open box and were left free to explore the environment for 30 s. After the 30 s, the treadmill movement was activated through the Arduino system at a low speed of 3 m/min, with an increment every 60 s up to 12 m/min (total of five speeds; intermediate speeds are 6, 8, and 10 m/min; Fig. 1A). After 5 min of running, the treadmill was turned off for a final baseline recording of 30 s. Finally, animals were removed from the treadmill and returned to their home cage. This process was then repeated for 12 consecutive days, including home cage baseline recording and pre/ postrunning treadmill recording epochs. Animal weight was recorded every day after training and showed no significant changes (Extended Data Fig. 1-1B). The Arduino source code is freely available on https://github.com/DSulzerLab/Motor_coordination_score and attached as Extended Data 1.

**Photometry recording**

Calcium signals were recorded using a commercial fiber photometry apparatus (Doric Lenses). The system consisted of a console connected to a computer, a four-channel programmable LED driver, and two LEDs at 405 and 465 nm connected to fluorescence dichroic mini cubes and photometric multipliers tubes (PMTs). The 405-nm wavelength is the isosbestic point for GCaMP, where fluorescence does not change depending on cytosolic calcium concentration (Extended Data Fig. 2-1A). Detection at this wavelength was used to remove background noise (movement artifact or GCaMP auto-fluorescence). The 465-nm excitation provides detection of calcium signals where the intensity of fluorescence is proportional to cytosolic calcium concentration. Calcium signals from each animal were recorded for 5 min as the mice explored their home cage before treadmill testing. This is used as a baseline to evaluate whether...
Figure 1. A, Timeline of behavioral protocol in the Treadmill Training Task. On each training day, a mouse is connected to the photometry patch cord in its home cage and a 5-min calcium baseline signal recorded. After this habituation period, the mouse is placed on the treadmill and allowed to explore the environment for 30 s. The treadmill motor is then started at a velocity of 3 m/min, with the speed increased every 60 s up to 12 m/min, after which the treadmill is turned off for another 30 s. This protocol is repeated for 12 consecutive days. A photograph of the treadmill is shown in Extended Data Figure 1-1. B, Schematic of the behavioral analysis. Positions of mouse body parts are obtained by analysis with DeepLabCut. For head position, the ventral 2D field of view are divided into five zones and the probability of the head of the mouse to be in each zone calculated. Color code for the body part is indicated in the legend on the right. C, Samples of head positions on day 1 (top) and day 4 (bottom) for a control mouse. Each point represents the head position in one frame and all frames from one video/session are overlapped. On day 1, the head position was frequently toward the rear of the field, indicating the mouse was falling behind the belt speed and often hitting the back wall. By day 4, the animal was able to keep up with the moving belt, and so the position of the head was more consistently toward the front. Plots of the four paws are shown in Extended Data Figure 1-2. D, Process for obtaining the mouse motor coordination score. Motor coordination score is calculated from the expected value of the head position in the five zones, position along the y-axis (calculated from standard deviation, SD, of y-axis value), and step length (distance between steps for each paw), as detailed in Materials and Methods. E, Motor coordination score for a cohort of control animals. Control mice show significant improvement in the coordination score over the 12 d of testing (n = 9; one-way ANOVA p < 0.001, Bonferroni’s multiple comparisons test as detailed in main text). Mouse weight and data by sex is shown in Extended Data Figure 1-1.
there is any loss of signal over the several days of testing, as well as to habituate the animal to the optical cable.

**Calcium signal analysis**

Calcium signals were processed using custom-built Python code to remove background noise and detect individual calcium peak events. The process consisted of (1) down sampling the signal to 30 samples/s to match the sampling rate of behavioral recording, (2) normalization of the data and removal of background noise, (3) identification and quantification of peak events (events count and event amplitude). In detail, 465 and 405 signals were normalized using the following formula:

\[ \frac{F - \Delta F}{\Delta F} \]

where \( \Delta F \) is calculated by a rolling mean of 125 of the overall trace. Then the 405 signal is subtracted from the 465 signal to remove movement artifacts and background noise. The resulting normalized trace is then analyzed using the Python function `find_peaks`, which identifies individual peak events that have a prominence (actual peak height) greater than 0.02, and are at least 60 samples away from each other (2 s). Individual traces are inspected to ensure accuracy of peak identification. The source code is freely available on [https://github.com/DSulzerLab/CaMPs_analysis](https://github.com/DSulzerLab/CaMPs_analysis) and attached as Extended Data 1.

We normalized behavior measures between a range of 0–1 and identified events in which the rolling mean varied by 0.1, indicating a significant change in the given measures. Variation in the head position was used to identify events in which the mouse did not keep up with the running tape and hit the back of the box. Variation in step length was used to detect events in which the mouse made a longer step to catch up with the running tape. Corresponding calcium traces were averaged to calculate the likelihood of a calcium peak event to occur at the same time as a given behavioral event. The source code is freely available on [https://github.com/DSulzerLab/Motor_coordination_score](https://github.com/DSulzerLab/Motor_coordination_score) and attached as Extended Data 1.

**Pharmacological experiments**

SCH39166 (Tocris), a selective D1-antagonist, was dissolved in 100% DMSO and then diluted to 1% DMSO concentration with saline (0.9% NaCl) containing 1 μM rhodamine (Rhodamine B Base; Aldrich 234141-10G), for a final concentration of 48.13 μM SCH39166 (total injected 5.7 ng). To ensure that the drug’s effect was not because of the injection or presence of rhodamine, an additional cohort of control animals was injected with the same concentration of DMSO. Saline solution without the drug was mixed with rhodamine to obtain a final concentration of 1% DMSO (sham solution).

The mice were injected locally in the DMS or DLS with 300 nl of either the SCH39166 or control solution, at a rate of 100 nl/min using a microinjection pump (UltraMicroPump III, World Precision Instruments) through an injection cannula attached to the photometry fiber (Doric Lenses, Fl_OmFC_ZF_100/170_4.2) while running on the treadmill. Local injection was confirmed by recording the 565 nm signal from the rhodamine dye (Extended Data Fig. 3-1).

**Video analysis**

Behavioral experiments were recorded using a high speed USB webcam (Sony PS3eye) and commercial video acquisition software (Kinovea), synchronized to the Arduino/OpenMaze behavior system with an infrared LED, and analyzed post hoc using DeepLabCut (Mathis et al., 2018) to track movement of individual body parts (the four paws, head, rear of the body, and tail were labeled as shown in Fig. 1 and Movie 1). Data were processed using Google Colaboratory and ~30,000–40,000 iterations were sufficient for good quality tracking. A sample of an analyzed video is shown (see Movie 1).

The DeepLabCut results were subsequently processed with custom-built Python code to return a “motor coordination score” from 1 to 5, with 1 representing poor and 5 representing excellent coordination. The coordination score was computed using three values: the expected value of the mouse head’s x-axis position, the SD of the mouse head’s y-axis position, and the average step length of the four individual paws. First, the expected value of the mouse head’s x-axis position was computed by dividing the box into five zones, with zone 1 being the frontmost and zone 5 the rearmost (Fig. 1B), and calculating the probability of the head being positioned in a specific zone. Second, the SD of the mouse head’s y-axis position was computed to identify the sideways movement. Third, the step length was computed using the Python package “traja” (Shenk et al., 2021), which uses spatiotemporal animal tracking data to estimate parameters such as the length of each step, straightness (running along a straight line), and speed. The average step length for each paw was then computed, and the “paw stability” determined by calculating the step length’s distance from the median of the average step length measurements. Along with the paw
stability, the percentiles of the expected values and the y-axis SD were computed, and these three values were given weights of 20/40/40, respectively. The percentiles of the weighted average were scaled between 1 and 5 to determine an overall coordination score. We arbitrarily chose the head position for this analysis, although position of either paw can also be used. Parallel analysis of the likelihood of paw placement over training demonstrates a higher fraction of steps within specific coordinates that are closer to the front of the box (Extended Data Fig. 1-2).

Manual scoring of the videos under blinded conditions confirmed the validity and reproducibility of the test and analysis method. The source code is freely available on https://github.com/DSulzerLab/Motor_coordination_score and attached as Extended Data 1.

**Immunohistochemistry**

After the completion of the behavioral experiments, mice were terminally anesthetized (euthasol 240 mg/kg, 200 µl, i.p.) and intracardially perfused with PBS then 4% paraformaldehyde (PFA). Brains were extracted and post-fixed overnight (4% PFA, 4°C). coronal slices (100 µm) were obtained by vibratome (Leica VT 1200). Sections were rinsed with 0.6% Triton X-100 in 1× PBS (PBST; 6×60 min) and blocked in 10% normal donkey serum (NDS) in PBST (60 min, room temperature (RT)). Primary antibodies: chicken polyclonal GFP (ab13970 Abcam; 1:500) and rabbit polyclonal anti-tyrosine hydroxylase (TH; ab152 Abcam; 1:500), were applied in 2% NDS in PBST (48 h 4°C) before washing (6×60 min PBST) and secondary incubation with species specific Alexafluor IgG secondary antibodies (60 min, RT, Invtrogen; 1:500). Tissues were washed again in 0.1% PBST (6×60 min), then mounted using DAPI Fluoromount-G (0100–20, SouthernBiotech). Images were acquired using a 20× oil objective on an Olympus microscope (see sample images in Extended Data Fig. 2-3).

**Code accessibility and statistics and data reporting**

The code described in the paper is freely available online at https://github.com/DSulzerLab. The code is available as Extended Data 1.

Data are presented throughout as mean ± SEM, where n is the number of animals. Comparisons were conducted by one-way or two-way ANOVA with appropriate post hoc tests detailed in the text, using Prism 9.0 (GraphPad).

**Results**

**Treadmill running**

To explore motor coordination learning during locomotion, we designed a custom-made motorized treadmill that provides detection of fine improvement in paw mobility as a mouse learns to run on the treadmill at a range of velocities (referred as the Treadmill Training Task; Fig. 1B; Extended Data Fig. 1-1A).

A cohort of WT mice were initially examined. On the first day of the protocol, animals were placed on the treadmill and allowed to freely explore the environment for 30 s, after which the treadmill was activated using the Arduino system. After 5 min of running, the treadmill was turned off for a final baseline recording of 30 s (Fig. 1A). This protocol was repeated for 12 consecutive days to track changes in the mouse running motor coordination.

The videos were analyzed with the machine-learning based videographic analysis platform DeepLabCut (DLC; Mathis et al., 2018), which allowed us to track paw movements in space and time. DLC provides x and y coordinates of the 2D plane of the video for each body part of interest across individual frames (Fig. 1B,C; Extended Data Fig. 1-2).

Results obtained by DLC were processed through custom-built Python scripts to compute a “motor coordination score” (see Materials and Methods) using variables such as the mouse head’s position within the box zones (X-axis), the mouse’s sideways movement along the treadmill mouse’s sideways movement along the treadmill (y-axis standard deviation, SD), and the mouse paw coordination on the treadmill (average step length). Individually, each variable did not accurately represent the running capability. For example, at lower speeds, running requires little effort for the animals and they often explore the box and move sideways, rear, or groom. This would affect a coordination score based only on the length of each step (data not shown). Similarly, at higher speed, the mouse is often mostly in the rear section of the box as it tries to catch up with the moving tape, yielding a low score for the head position. We find that a combination of these factors provides a more accurate estimate of coordination. Indeed, in the initial days of training, mice had a significantly lower motor coordination score than during later sessions (Fig. 1E), as they had not been exposed to the treadmill before and displayed poor coordination during running: the task naive mice would tend to fall behind and make longer steps trying to catch up with the running tape. Moreover, naive animals tended to run sideways rather than along a straight line (Extended Data Fig. 1-2B). On later days of training, as mice accrued competency in running and better coordination, their score improved (Fig. 1E) and their likelihood of stepping in the same region increased (Extended Data Fig. 1-2B). Control animals trained on the treadmill showed a significantly higher coordination score within the fourth day of training. By day 4, all mice performed significantly better than on the first training day (one-way ANOVA F<sub>11,96</sub> = 3.753, p < 0.001, Bonferroni’s multiple comparisons test day 4 ***p < 0.001, day 5 **p < 0.01, day 6 **p < 0.01, day 7 **p < 0.01, day 8 ***p < 0.0001, day 9 **p < 0.01, day 10 ***p < 0.001, day 11 **p < 0.01, day 12 **p < 0.01; Fig. 1E), with no significant differences between male and females mice (two-way ANOVA Day vs Sex F<sub>2,246</sub> = 1.34, p = 0.33, Day F<sub>60,26,144.9</sub> = 11.61, p < 0.0001, Sex F<sub>1,24</sub> = 5.502, p = 0.07, Subject F<sub>24,264</sub> = 7.96, p < 0.0001; Extended Data Fig. 1-1C).

**DMS and DLS D1-SPNs calcium activity during running**

We next explored the role of the direct pathway in skill acquisition by recording calcium signals from D1-SPNs in...
either the DMS or DLS. Recording of baseline D1-SPNs activity in the DMS show no significant changes over the 12 d (one-way ANOVA $F_{(11,84)} = 1.562, p = 0.13$; Extended Data Fig. 2-1C). Similarly, no changes were found in D1-SPNs activity in the DLS (one-way ANOVA $F_{(11,96)} = 0.61, p = 0.82$; Extended Data Fig. 2-1D).

During treadmill running, GCaMP6f-injected mice performance was identical to control animals (one-way ANOVA for DMS mice $F_{(11,84)} = 2.547, p < 0.01$, Bonferroni’s multiple comparisons test day 4 $p < 0.05$, day 5 $p < 0.05$, day 6 $p < 0.05$, day 7 $p < 0.01$, day 8 $p < 0.01$, day 9 $p < 0.05$, day 10 $p < 0.01$, day 11 $p < 0.01$, day 12 $p < 0.06$ and for DLS mice $F_{(11,96)} = 2.547, p < 0.05$, Bonferroni’s multiple comparisons test day 6 $p < 0.06$, day 7 $p < 0.06$, day 8 $p < 0.01$, day 9 $p < 0.06$, day 10 $p < 0.06$, day 11 $p < 0.06$, day 12 $p < 0.06$; Extended Data Fig. 2-1B), indicating that the surgery, viral expression, and implant did not affect the ability to run on the treadmill. We then evaluated brain activity with the coordination score to examine neural changes as the mice gained proficiency at running on the motorized treadmill. No difference in behavior or calcium signals was found during the 30-s periods before and after the running time (data not shown), and the data from both off periods were merged and reported as “off-time.”

On day 1 of training, all mice showed similar average calcium event amplitude between baseline, the running (on-time; independently of the speed of the treadmill) and pre/postrunning epochs in which the treadmill was off (off-time; Fig. 2C for DMS RM one-way ANOVA $F_{(2,8)} = 0.662, p = 0.66$; Fig. 2D for DLS RM one-way ANOVA $F_{(2,12)} = 0.258, p = 0.73$). Similarly, event rates were comparable between baseline recording and while on the treadmill, whether it was on or off (three conditions analyzed separately over the 12 d: baseline calcium, on-time, and off-time, Extended Data Fig. 2-1E; one-way ANOVA for DMS baseline $F_{(11,84)} = 1.761, p = 0.08$, for DMS time-on $F_{(11,84)} = 1.971, p = 0.07$, for DMS time-off $F_{(11,84)} = 1.184$,...
Interestingly, DMS D1-SPNs calcium signals displayed a significant decrease in overall event amplitude beginning on day 3 while running (on-time) compared with off-time (RM one-way ANOVA for DLS baseline \(F_{(1,96)} = 0.767, p = 0.67, \) for DLS time-on \(F_{(1,96)} = 0.849, p = 0.59, \) for DLS time-off \(F_{(1,96)} = 0.447, p = 0.93)."

For DLS on-time condition, Bonferroni’s multiple comparisons test \(p < 0.05 \) DMS on-time vs DMS off-time; \(\text{Fig. 2C} \), which remained consistent throughout the 12 d of testing (day 7 RM one-way ANOVA \(F_{(2,8)} = 12.53, p < 0.01, \) Bonferroni’s multiple comparisons test \(p < 0.05 \) DMS on-time vs DMS off-time and \(**p < 0.01 \) DMS on-time vs DMS home cage; for day 12 RM one-way ANOVA \(F_{(2,8)} = 7.618, p < 0.05, \) Bonferroni’s multiple comparisons test \(p < 0.05 \) DMS on-time vs DMS off-time and \(**p < 0.01 \) DMS on-time vs DMS home cage (Fig. 2C). The difference is also apparent when peak epochs amplitudes are compared with the baseline home cage recording (for DMS on-time one-way ANOVA \(F_{(1,64)} = 0.887, p < 0.0001, \) Bonferroni’s multiple comparisons test: day 4 \(p < 0.05, \) day 5 \(*p < 0.01, \) day 6 \(*p < 0.01, \) day 7 \(*p < 0.001, \) day 8 \(*p < 0.001, \) day 9 \(*p < 0.001, \) day 10 \(*p < 0.001, \) day 11 \(*p < 0.001, \) day 12 \(*p < 0.001; \) Extended Data Fig. 2-1C), while off-time average peak amplitudes do not change over training (for DMS off-time one-way ANOVA \(F_{(1,64)} = 1.349, p = 0.21; \) Extended Data Fig. 2-1C). The data remain significant when on-time is compared directly to off-time recording (RM two-way ANOVA where the two conditions are on-time vs off-time, Day \(*p < 0.01, \) Condition \(F_{(1,123)} = 1.045, p = 0.41, \) Day \(F_{(2,682,32.18)} = 7.864, p < 0.001, \) Condition \(F_{(1,12)} = 7.093, p < 0.01, \) Subjects \(F_{(12,123)} = 8.244, p < 0.0001, \) Bonferroni’s multiple comparisons test for day 7 \#p < 0.05, \) day 8 \##p < 0.01, \) day 9 \#p < 0.05, \) day 10 \#p < 0.01, \) day 11 \##p < 0.01, \) day 12 \##p < 0.01; \) Extended Data Fig. 2-1C). Conversely, D1-SPN calcium signals recorded from the DLS showed no significant difference in either calcium event amplitude or rate between running time and off-time over training (Fig. 2D); day 3: RM one-way ANOVA \(F_{(2,12)} = 1.150, p = 0.34; \) day 7 RM one-way ANOVA \(F_{(2,12)} = 0.631, p = 0.53; \) day 12: RM one-way ANOVA \(F_{(2,12)} = 3.235, p = 0.07; \) Extended Data Fig. 2-1D, for DLS on-time one-way ANOVA \(F_{(1,96)} = 0.801, p = 0.64, \) for DLS off-time one-way ANOVA \(F_{(1,96)} = 0.947, p = 0.50.\)

When the data were further analyzed by motor feature (step length, head position) there was no apparent correlation between each specific behavior events and calcium epochs. Specifically, no apparent peak was present at times in which the mouse fell behind and attempted to catch up with the moving tape (evaluated as a sudden change in the head position; Extended Data Fig. 2-2). Similarly, there was no apparent increase in calcium signals at events in which the mouse performed larger steps to position itself in the front of the cage after struggling to keep up (data not shown).

Because we increased the speed of the treadmill every minute, we investigated whether there was an increase in calcium activity at the time of each acceleration. We did not observe a clear peak event at the specific time any of the acceleration on any of the 12 d of training (example traces in Extended Data Fig. 2-2).

### Inhibition of D1-SPNs with a D1-receptor antagonist

Despite the absence of calcium peaks associated with specific motor features of running behavior, we hypothesized that the overall change in DMS activity during training may be important for skill acquisition. To investigate this, we locally injected SCH39166, a selective D1-antagonist, into the DMS or DLS as the mouse was running to inhibit the activity of direct pathway D1-SPNs during task learning. An example trace from a DMS implanted mouse shows significant reduction in calcium signals in D1-SPNs as the drug is injected, while the red wavelength rhodamine signal increased (Extended Data Fig. 3-1), confirming local infusion. A cohort of mice was injected with a saline solution in either the DMS or the DLS (data combined) as a control for possible effect of the injection.

All SCH39166-injected mice, independent of the region of injection, showed delayed improvement in performance until day 5. By day 6, performance quickly improved (Fig. 3A). The coordination scores for days 2 through 5 were significantly lower for animals injected with SCH39166 in the DMS (two conditions: SCH39166 vs saline, two-way ANOVA Day \(\times\) Condition \(F_{(6,192)} = 2.019, p < 0.05, \) Day \(F_{5,134,61.61} = 5.762, p < 0.001, \) Condition \(F_{(1,12)} = 3.695, p = 0.08, \) Subjects \(F_{(12,192)} = 4.374, p < 0.0001, \) Bonferroni’s multiple comparisons test for day 2 \(*p < 0.01, \) day 4 \(*p < 0.05, \) day 5 \(*p < 0.01), \) than for saline-injected animals. Interestingly, injections of the D1-antagonist in the DLS also slowed learning, though this only reached significance for day 5 (two conditions: SCH39166 vs saline, two-way ANOVA Day \(\times\) Condition \(F_{(6,176)} = 1.943, p < 0.05, \) Day \(F_{5,887,64.76} = 6.037, p < 0.0001, \) Condition \(F_{(1,11)} = 5.476, p < 0.05, \) Subjects \(F_{(11,176)} = 4.422, p < 0.0001, \) Bonferroni’s multiple comparisons test for day 5 \#p < 0.05)."

To investigate DMS and DLS contributions to performance once the skill is acquired, we recorded 5 additional days one week after the first session (labeled day 13 to day 17). On day 16, mice were injected with the same dose of SCH39166 as previously. Interestingly, injection in the DLS decreased the coordination score, although this did not reach significance by post hoc test (one-way ANOVA \(p < 0.01, \) Bonferroni’s multiple comparisons test \(p = 0.47; \) Fig. 3A,B). No decrease was observed on the following day when mice were tested again without the D1-antagonist. D1-receptor inhibition in the DMS on day 16 resulted in no impairment in performance (one-way ANOVA \(p = 0.85; \) Fig. 3A,B). The lack of change in coordination score on day 16 for DMS injected mice suggest that D1 dopamine receptor activation in this region is highly relevant in early training but is less necessary for performance of the previously learned task.

### Discussion

Current knowledge of the synaptic circuitry underlying motor learning comes from studies analyzing simple tasks, such as lever presses to achieve a food or drug reward or counting the number of falls from a motorized rotarod.
While much has been learned from these approaches, they may not be applicable to learning more complex skills, such as changes in motor coordination during practice, a feature of activities ranging from athletic tasks to performance on a musical instrument. The training protocol introduced here, referred to as the Treadmill Training Task, provides a means to record activity of the direct pathway in the medial and lateral portions of the dorsal striatum while analyzing complex motor activity in freely moving animals in a carefully controlled locomotor task. We furthermore developed a computational method to interpret multi-limb behavioral data and identify patterns of motor function that contribute to the improvement of coordination of a running mouse during practice. In doing so, we found that DMS and DLS activity progresses differently as animals gain skill in a motor task, revealing neuroanatomic specificity in progressive motor learning.

Our results are consistent with the hypothesis that DMS activity might decrease during complex motor learning (Cataldi et al., 2022), and is consistent with reports by Kupferschmidt and colleagues showing that activity of associative inputs to the DMS are active during skill acquisition but less so during the execution of a mastered skill (Kupferschmidt et al., 2017). Similarly, a recent investigation shows that corticostriatal postsynaptic responses in the DMS undergo a transient decrease after training on the rotarod task, although those recordings were conducted in brain slice preparations and could not measure changes in activity during the task training (Badreddine et al., 2022).

Although we found that the amplitude of calcium events in the DMS changes over training, the rate of calcium activity transients did not. Our results are consistent with a report by Wightman et al., that demonstrated distinct active and silent regions in the striatum that exhibit different SPN activity and dopamine release patterns as a task is acquired (Owesson-White et al., 2016), a feature further consistent with the recent study on brain slices from trained animals (Badreddine et al., 2022). Badreddine’s study suggests that a reorganization of high activity cells increases the signal-to-noise ratio and contributes to better transmission of information. In this regard, we note that calcium signals detected by fiber photometry describe the bulk activity of a multitude of neurons, and an overall reduction in amplitude but not in the number of events could indicate that fewer, “specialized” neurons fire at the same rate once the skill is acquired (Bamford et al., 2018). Future experiments may explore this hypothesis by examining single cell activity over training using imaging techniques that use miniature head-mounted microscopes.

An important advantage to our approach is the ability to expose the regions being recorded to local pharmacological manipulations. Such experiments demonstrate that inhibition of D1 receptors delayed motor coordination learning in both the DMS and the DLS. The ability of mice to still learn improved performance on the Treadmill Training Task, albeit with a substantial lag compared with saline-treated mice, suggests that additional regions or cell types may promote motor learning with a lower efficiency in the absence of striatal activity. Interestingly, while no change in DLS activity was detected during training, inhibition of D1 dopamine receptors in the DLS delayed learning to an extent similar to the inhibition of DMS D1-SPNs. Similarly, Badreddine and colleagues did not find changes in mean amplitude nor overall changes in percentage of high activity cells in DLS brain slices because of training, although they...
detected a spatial reorganization of clusters of high activity cells in this region in late training (Badreddine et al., 2022). Notably, despite reduction in DMS activity during learning, D1 antagonism of the DMS did not improve coordination, suggesting that an initial re-organization of the neuronal circuit may be necessary for improvement in a specific skill, and disruption of this system (in this case by D1 antagonism) can alter the process. Further work should explore additional approaches that inhibit the dorsal striatum during and after training to evaluate the contribution of DLS more precisely in learning versus performance. The use of miniature microscopes or 2-photon imaging that image precisely in learning versus performance. The use of 

Conversely, inhibition of DMS D1-SPNs did not decrease coordination scores after learning, consistent with the idea that later in training the DMS is disengaged and no longer necessary for expression of the skill (Badreddine et al., 2022; Cataldi et al., 2022). This is consistent with work in monkeys and rats, where dopamine transmission is required to learn reward-related behaviors, but is no longer required once the behavioral response is learned (Graybiel, 1998; Schultz et al., 2015; Schultz, 2019). Indeed, this step may be required to “chain” more and more complex behaviors. Other studies have demonstrated a dopamine-dependent change in synaptic plasticity that lasts for months and does not require dopamine to be present after it is established (Bamford et al., 2008). In summary, these results suggest that dopaminergic regulation of activity of D1-SPNs in the DMS is required for proper skill acquisition, while DLS direct pathway neurons may contribute to performance in early training, although at this juncture, a contribution to learning cannot be excluded.

Given the complexity of the circuits involved in motor learning and the multiple behavioral variables of each task, caution is required when interpreting the animal behavior and the interaction between the different brain regions. Dopamine neurons display different patterns of activation in different behavioral tasks, e.g., in head fixed versus freely moving animals or depending on whether a reward is present (Coddington and Dudman, 2019) and the activity of striatal neurons may be influenced by similar considerations (Cataldi et al., 2022). We note that the treadmill protocol could encompass aspects of aversion, as the mouse attempts to avoid hitting the back of the box, although we observed no change in calcium signals when the mouse was placed in the box, arguing against a classical fear response. A similar approach could be developed to examine spontaneous running on a wheel, which would avoid box confinement and the forced component of running given by the motorized system.

The Treadmill Training Task provides a means to evaluate motor ability in healthy animals and disease models and is designed to be useful for the evaluation of motor disorders and motor learning deficits because of neurodevelopmental disease, drug dependence, neurotoxic regimens, stroke, seizures, or injury.

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