Utility Maximization for Delay Constrained QoS in Wireless

I-Hong Hou
CSL and Department of CS
University of Illinois
Urbana, IL 61801, USA
ihou2@illinois.edu

P. R. Kumar
CSL and Department of ECE
University of Illinois
Urbana, IL 61801, USA
prkumar@illinois.edu

Abstract—This paper studies the problem of utility maximization for clients with delay based QoS requirements in wireless networks. We adopt a model used in a previous work that characterizes the QoS requirements of clients by their delay constraints, channel reliabilities, and delivery ratio requirements. In this work, we assume that the utility of a client is a function of the delivery ratio it obtains. We treat the delivery ratio for a client as a tunable parameter by the access point (AP), instead of a given value as in the previous work. We then study how the AP should assign delivery ratios to clients so that the total utility of all clients is maximized.

We apply the techniques introduced in two previous papers to decompose the utility maximization problem into two simpler problems, a CLIENT problem and an ACCESS-POINT problem. We show that this decomposition actually describes a bidding game, where clients bid for the service time from the AP. We prove that although all clients behave selfishly in this game, the resulting equilibrium point of the game maximizes the total utility. In addition, we also establish an efficient scheduling policy for the AP to reach the optimal point of the ACCESS-POINT problem. We prove that the policy not only approaches the optimal point but also achieves some forms of fairness among clients. Finally, simulation results show that our proposed policy does achieve higher utility than all other compared policies.

I. INTRODUCTION

We study how to provide QoS to maximize utility for wireless clients. We jointly consider the delay constraint and channel unreliability of each client. The access point (AP) assigns delivery ratios to clients under the delay and reliability constraints. This distinguishes our work from most other work on providing QoS where the delivery ratios to clients are taken as given inputs rather than tunable parameters.

We consider the scenario where there is one AP that serves a set of wireless clients. We extend the model proposed in a previous work [8]. This model analytically describes three important factors for QoS: delay, channel unreliability, and delivery ratio. The previous work also provides a necessary and sufficient condition for the demands of the set of clients to be feasible. In this work, we treat the delivery ratios for clients as variables to be determined by the AP. We assume that each client receives a certain amount of utility when it is provided a delivery ratio. The relation between utility and delivery ratio is described by an utility function, which may differ from client to client. Based on this model, we study the problem of maximizing the total utility of all clients, under feasibility constraints. We show that this problem can be formulated as a convex optimization problem.

Instead of solving the problem directly, we apply the techniques introduced by Kelly [10] and Kelly, Maulloo, and Tan [11] to decompose the problem of system utility maximization into two simpler subproblems that describe the behaviors of the clients and the AP, respectively. We prove that the utility maximization problem can be solved by jointly solving the two simpler subproblems. Further, we describe a bidding game for the reconciliation between the two subproblems. In this game, clients bid for service time from the AP, and the AP assigns delivery ratios to clients according to their bids, to optimize its own subproblem, under feasibility constraints. Based on the AP's behavior, each client aims to maximize its own net utility, that is, the difference between the utility it obtains and the bid it pays. We show that, while all clients behave selfishly in the game, the equilibrium point of the game solves the two subproblems jointly, and hence maximizes the total utility of the system.

We then address how to design a scheduling policy for the AP to solve its subproblem. We propose a very simple priority based scheduling algorithm for the AP. This policy requires no information of the underlying channel qualities of the clients and thus needs no overhead to probe or estimate the channels. We prove that the long-term average performance of this policy converges to a single point, which is in fact the solution to the subproblem for the AP. Further, we also establish that the policy achieves some forms of fairness.

Our contribution is therefore threefold. First, we formulate the problem of system utility maximization as a convex optimization problem. We then show that this problem is amenable to solution by a bidding game. Finally, we propose a very simple priority based AP scheduling policy to solve the AP's subproblem, that can be used in the bidding iteration to reach the optimal point.
of the system’s utility maximization problem.

Finally, we conduct simulation studies to verify all the theoretical results. Simulations show that the performance of the proposed scheduling policy converges quickly to the optimal value of the subproblem for AP. Also, by jointly applying the scheduling policy and the bidding game, we can achieve higher total utility than all other compared policies.

The rest of the paper is organized as follows: Section II reviews some existing related work. Section III introduces the model for QoS proposed in [8] and also summarizes some related results. In Section IV, we formulate the problem of utility maximization as a convex program and provide a quick convergence result. Section V addresses the problem of utility maximization as a convex program and provides a quick convergence result. Section VI addresses the phase consists of the AP scheduling client transmissions to optimize its subproblem. Section VII addresses the problem of utility maximization as a convex program and provides a quick convergence result. Section VII demonstrates some simulation studies. Finally, Section VIII concludes this paper.

II. RELATED WORK

There has been a lot of research on providing QoS over wireless channels. Most of the research has focused on admission control and scheduling policies. Hou, Borkar, and Kumar [8] and Hou and Kumar [9] have proposed analytical models to characterize QoS requirements and have also proposed both admission control and scheduling policies. Ni, Romdhani, and Turtles [13] provides an overview of the IEEE 802.11 mechanisms and discusses the limitations and challenges in providing QoS in 802.11. Gao, Cai, and Ngan [7], Niyato and Hossain [14], and Ahmed [1] have surveyed existing admission control algorithms in different types of wireless networks. On the other hand, Fattah and Leung [6] and Cao and Li [5] have provided extensive surveys on scheduling policies for providing QoS.

There is also research on utility maximization for both wireline and wireless networks. Kelly [10] and Kelly, Maulloo, and Tan [11] have considered the rate control algorithm to achieve maximum utility in a wireline network. Lin and Shroff [12] has studied the same problem with multi-path routing. As for wireless networks, Xiao, Shroff, and Chong [15] has proposed a power-control framework to maximize utility, which is defined as a function of the signal-to-interference ratio and cannot reflect channel unreliability. Cao and Li [4] has proposed a bandwidth allocation policy that also considers channel degradation. Bianchi, Campbell, and Liao [2] has studied utility-fair services in wireless networks. However, all the aforementioned works assume that the utility is only determined by the allocated bandwidth. Thus, they do not consider applications that require delay bounds.

III. SYSTEM MODEL AND FEASIBILITY CONDITION

We adopt the model proposed in a previous work [8] to capture two key QoS requirements, delay constraints and delivery ratio requirements, and incorporating channel conditions for users. In this section, we describe the proposed model and summarize relevant results of [8].

We consider a system with \( N \) clients, numbered as \( \{1, 2, \ldots, N\} \), and one access point (AP). Packets for clients arrive at the AP and the AP needs to dispatch packets to clients to meet their respective requirements. We assume that time is slotted, with slots numbered as \( \{0, 1, 2, \ldots\} \). The AP can make exactly one transmission in each time slot. Thus, the length of a time slot would include the times needed for transmitting a DATA packet, an ACK, and possibly other MAC headers. Assume there is one packet arriving at the AP periodically for each client, with a fixed period of \( \tau \) time slots, at time slots \( 0, \tau, 2\tau, \ldots \). Each packet that arrives at the beginning of a period \( k\tau, (k+1)\tau \) must be delivered within the ensuing period, or else it expires and is dropped from the system at the end of this period. Thus, a delay constraint of \( \tau \) time slots is enforced on all successfully delivered packet. Further, unreliable and heterogeneous wireless channels to these clients are considered. When the AP makes a transmission for client \( n \), the transmission succeeds (by which is meant the successful deliveries of both the DATA packet and the ACK) with probability \( p_n \). Due to the unreliable channels and delay constraint, it may not be possible to deliver the arrived packets of all the clients. Therefore, each client stipulates a certain delivery ratio \( q_n \) that it has to receive, which is defined as the average proportion of periods in which its packet is successfully delivered. The previous work also shows how this model can be used to capture scenarios where both uplink traffic and downlink traffic exist.

Below we describe the formal definitions of the concepts of fulfilling a set of clients and the feasibility of a set of client requirements.

Definition 1: A set of clients with the above QoS constraints is said to be fulfilled by a particular scheduling policy \( \eta \) of the AP if the time averaged delivery ratio of each client is at least \( q_n \) with probability 1.

Definition 2: A set of clients is feasible if there exists some scheduling policy of the AP that fulfills it.

Whether a certain client is fulfilled can be decided by the average number of time slots that the AP spends on working for the client per period:

Lemma 1: The delivery ratio of client \( n \) converges to \( q_n \) with probability one if and only if the work performed on client \( n \), defined as the long-term average number of time slots that the AP spends on working for client \( n \) per period, converges to \( w_n(q_n) = \frac{q_n}{p_n} \) with probability one. We therefore call \( w_n(q_n) \) the workload of client \( n \).

Since expired packets are dropped from the system at the end of each period, there is exactly one packet for each client at the beginning of each period. Therefore, there may be occasions where the AP has delivered all packets before the end of a period and is therefore forced to stay idle for the remaining time slots in the period. Let \( I_S \) be the expected number of such forced idle time slots in a period when the client set is just \( S \subseteq \{1, 2, \ldots, N\} \) (i.e., all clients except those in \( S \) are removed from consideration), and the AP only caters to the subset \( S \).
of clients. Since each client \( n \in S \) requires \( w_n \) time slots per period on average, we can obtain a necessary condition for feasibility: \( \sum_{i \in S} w_i(q_i) + I_S \leq \tau \), for all \( S \subseteq \{1, 2, \ldots, N\} \). It is shown in [8] that this necessary condition is also sufficient:

**Theorem 1:** A set of clients, with delivery ratio requirements \( [q_n] \), is feasible if and only if \( \sum_{i \in S} \frac{q_i}{p_i} \leq \tau - I_S \), for all \( S \subseteq \{1, 2, \ldots, N\} \).

IV. UTILITY MAXIMIZATION AND DECOMPOSITION

In the previous section, it is assumed that the delivery ratio requirements, \( [q_n] \), are given and fixed. In this paper, we address the problem of how to choose \( q := [q_n] \) so that the total utility of all the clients in the system can be maximized.

We begin by supposing that each client has a certain utility function, \( U_n(q_n) \), which is strictly increasing, strictly concave, and continuously differentiable function over the range \( 0 < q_n \leq 1 \), with the value at 0 defined as the right limit, possibly \( -\infty \). The problem of choosing \( q_n \) to maximize the total utility, under the feasibility constraint of Theorem 1, can be described by the following convex optimization problem:

**SYSTEM:**

\[
\begin{align*}
\text{Max} & \quad \sum_{i=1}^{N} U_i(q_i) \\
\text{s.t.} & \quad \sum_{i \in S} \frac{q_i}{p_i} \leq \tau - I_S, \forall S \subseteq \{1, 2, \ldots, N\}, \\
& \quad q_n \geq 0, \forall 1 \leq n \leq N.
\end{align*}
\]

It may be difficult to solve SYSTEM directly. So, we decompose it into two simpler problems, namely, \( \text{CLIENT} \) and \( \text{ACCESS-POINT} \), as described below. This decomposition was first introduced by Kelly [10], though in the context of dealing with rate control for non-real time traffic.

Suppose client \( n \) is willing to pay an amount of \( \rho_n \) per period, and receives a long-term average delivery ratio \( q_n \) proportional to \( \rho_n \), with \( \rho_n = \psi_n q_n \). If \( \psi_n > 0 \), the utility maximization problem for client \( n \) is:

**CLIENT\(_n\):**

\[
\begin{align*}
\text{Max} & \quad U_n\left(\frac{\rho_n}{\psi_n}\right) - \rho_n \\
\text{s.t.} & \quad 0 \leq \rho_n \leq \psi_n.
\end{align*}
\]

On the other hand, given that client \( n \) is willing to pay \( \rho_n \) per period, we suppose that the AP wishes to find the vector \( q \) to maximize \( \sum_{i=1}^{N} p_i \log q_i \), under the feasibility constraints. In other words, the AP has to solve the following optimization problem:

**ACCESS-POINT:**

\[
\begin{align*}
\text{Max} & \quad \sum_{i=1}^{N} p_i \log q_i \\
\text{s.t.} & \quad \sum_{i \in S} \frac{q_i}{p_i} \leq \tau - I_S, \forall S \subseteq \{1, 2, \ldots, N\}, \\
& \quad q_n \geq 0, \forall 1 \leq n \leq N.
\end{align*}
\]

We begin by showing that solving \( \text{ACCESS-POINT} \) is equivalent to jointly solving \( \text{CLIENT}_n \) and \( \text{ACCESS-POINT} \).

**Theorem 2:** There exist non-negative vectors \( q, \rho := [\rho_n] \), and \( \psi := [\psi_n] \), with \( \rho_n = \psi_n q_n \), such that:

(i) For \( n \) such that \( \psi_n > 0 \), \( \rho_n \) is a solution to \( \text{CLIENT}_n \);
(ii) Given that each client \( n \) pays \( \rho_n \) per period, \( q \) is a solution to \( \text{ACCESS-POINT} \).

Further, if \( q, \rho \), and \( \psi \) are all positive vectors, the vector \( q \) is also a solution to \( \text{SYSTEM} \).

**Proof:** We will first show the existence of \( q, \rho \), and \( \psi \) that satisfy (i) and (ii). We will then show that the resulting \( q \) is also the solution to \( \text{SYSTEM} \).

There exists some \( \epsilon > 0 \) so that by letting \( q_n \equiv \epsilon \), the vector \( q \) is an interior point of the feasible region for both \( \text{SYSTEM} \) and \( \text{ACCESS-POINT} \). Therefore, by Slater’s condition, a feasible point for SYSTEM, \( \text{CLIENT}_n \), or \( \text{ACCESS-POINT} \), is the optimal solution for the respective problem if and only if it satisfies the corresponding Karush-Kuhn-Tucker (KKT) condition for the problem. Further, since the feasible region for each of the problems is compact, and the utilities are continuous on it, or since the utility converges to \( -\infty \) at \( q_n = 0 \), there exists an optimal solution to each of them.

The Lagrangian of \( \text{SYSTEM} \) is:

\[
L_{\text{SYS}}(q, \lambda, \nu) := -\sum_{i=1}^{N} U_i(q_i) + \sum_{S \subseteq \{1, 2, \ldots, N\}} \lambda_S \left[ \sum_{i \in S} \frac{q_i}{p_i} - (\tau - I_S) \right] - \sum_{i=1}^{N} \nu_i q_i,
\]

where \( \lambda := [\lambda_S : S \subseteq \{1, 2, \ldots, N\}] \) and \( \nu := [\nu_n : 1 \leq n \leq N] \) are the Lagrange multipliers. By the KKT condition, a vector \( q^* := [q_1^*, q_2^*, \ldots, q_N^*] \) is the optimal solution to \( \text{SYSTEM} \) if \( q^* \) is feasible and there exists vectors \( \lambda^* \) and \( \nu^* \) such that:

\[
\frac{\partial L_{\text{SYS}}}{\partial q_n} \bigg|_{q^*, \lambda^*, \nu^*} = -U'_n(q_n^*) + \frac{\sum_{i \in S} \lambda_S}{\rho_n} - \nu_n^* = 0, \forall 1 \leq n \leq N,
\]

\[
\lambda_S' \left[ \sum_{i \in S} \frac{q_i^*}{p_i} - (\tau - I_S) \right] = 0, \forall S \subseteq \{1, 2, \ldots, N\},
\]

\[
\nu_n^* q_n^* = 0, \forall 1 \leq n \leq N,
\]

\[
\lambda_S^* \geq 0, \forall S \subseteq \{1, \ldots, N\}, \quad \text{and} \quad \nu_n^* \geq 0, \forall 1 \leq n \leq N.
\]

The Lagrangian of \( \text{CLIENT}_n \) is:

\[
L_{\text{CLI}}(\rho_n, \xi_n) := -U_n\left(\frac{\rho_n}{\psi_n}\right) + \rho_n - \xi_n \rho_n,
\]

where \( \xi_n \) is the Lagrange multiplier for \( \text{CLIENT}_n \). By the KKT condition, \( \rho_n^* \) is the optimal solution to \( \text{CLIENT}_n \) if \( \rho_n^* \geq 0 \) and there exists \( \xi_n^* \) such that:

\[
\frac{dL_{\text{CLI}}}{d\rho_n} \bigg|_{\rho_n^*, \xi_n^*} = -\frac{1}{\psi_n} U'_n\left(\frac{\rho_n^*}{\psi_n}\right) + 1 - \xi_n^* = 0,
\]

\[
\xi_n^* \rho_n^* = 0,
\]

\[
\xi_n^* \geq 0.
\]
Finally, the Lagrangian of \textit{ACCESS-POINT} is:

\[
L_{\text{NET}}(q, \zeta, \mu) := -\sum_{i=1}^{N} \rho_i \log q_i + \sum_{S \subseteq \{1,\ldots,N\}} \zeta_S \left[ \sum_{i \in S} \frac{q_i}{p_i} - (\tau - I_S) \right] - \sum_{i=1}^{N} \mu_i q_i,
\]

where \( \zeta := \{S : S \subseteq \{1,\ldots,N\} \} \) and \( \mu := \{\mu_n : 1 \leq n \leq N\} \) are the Lagrange multipliers. Again, by the KKT condition, a vector \( q^* := [q_n^*] \) is the optimal solution to \textit{ACCESS-POINT} if \( q^* \) is feasible and there exists vectors \( \zeta^* \) and \( \mu^* \) such that:

\[
\frac{\partial L_{\text{NET}}}{\partial q_n} \bigg|_{q^*, \zeta^*, \mu^*} = -\frac{\rho_n}{q_n} + \sum_{S \subseteq S} \frac{\zeta_S}{p_n} - \mu_n^* = 0, \forall 1 \leq n \leq N,
\]

\[
\zeta_S \left[ \sum_{i \in S} \frac{q_i^*}{p_i} - (\tau - I_S) \right] = 0, \forall S \subseteq \{1,\ldots,N\},
\]

\[
\mu_n^* q_n^* = 0, \forall 1 \leq n \leq N,
\]

\[
\zeta_S \geq 0, \forall S \subseteq \{1,\ldots,N\}, \text{ and } \mu_n^* \geq 0, \forall 1 \leq n \leq N.
\]

Let \( q^* \) be a solution to \textit{SYSTEM}, and let \( \lambda^*, \nu^* \) be the corresponding Lagrange multipliers that satisfy conditions (2)–(12). Let \( q_n = q_n^*, \rho_n = \sum_{S \subseteq S} \frac{\lambda_S}{p_n} q_n^* \), and \( \psi_n = \sum_{S \subseteq S} \frac{\lambda_S}{p_n} \psi_n^* \), for all \( n \). Clearly, \( q, \rho, \) and \( \psi \) are all non-negative vectors. We will show \( (q, \rho, \psi) \) satisfy (1) and (11).

We first show (1) for all \( n \) such that \( \psi_n = \sum_{S \subseteq S} \frac{\lambda_S}{p_n} > 0 \). It is obvious that \( \rho_n = \psi_n q_n \). Also, \( \rho_n \geq 0 \), since \( \lambda_S \geq 0 \) (by (12)) and \( q_n \geq 0 \) (since \( q^* \) is feasible). Further, let the Lagrange multiplier of \textit{CLIENT}_n, \( \xi_n \), be equal to \( \nu_n^* / \sum_{S \subseteq S} \frac{\lambda_S}{p_n} \). Then we have:

\[
\frac{\partial L_{\text{SYS}}}{\partial q_n} \bigg|_{q, \lambda, \nu} = -U_n'(q_n) + \sum_{S \subseteq S} \frac{\lambda_S}{p_n} \psi_n^* - \nu_n = 0, \forall S \subseteq \{1,\ldots,N\}, \text{ by (13)},
\]

\[
\lambda_S \sum_{n \in S} \psi_n^* [\tau - I_S] = 0, \forall S, \text{ by (17)},
\]

\[
\nu_n q_n = \xi_n \rho_n, \forall \rho, \psi, \xi.
\]

Thus, \( (q, \lambda, \nu) \) satisfy the KKT condition for \textit{SYSTEM}, and so \( q \) is a solution to \textit{SYSTEM}.

V. A BIDDING GAME BETWEEN CLIENTS AND ACCESS POINT

Theorem 2 states that the maximum total utility of the system can be achieved when the solutions to the problems \textit{CLIENT}_n and \textit{ACCESS-POINT} agree. In this section, we formulate a repeated game for such reconciliation. We also discuss the meanings of the problems \textit{CLIENT}_n and \textit{ACCESS-POINT} in this repeated game.

The repeated game is formulated as follows:

Step 1: Each client \( n \) announces an amount \( \rho_n \) that it pays per period.

Step 2: After noting the amounts, \( \rho_1, \rho_2, \ldots, \rho_N \), paid by the clients, the AP chooses a scheduling policy so that the resulting long-term delivery ratio, \( q_n \), for each client maximizes \( \sum_{i=1}^{N} \rho_i \log q_i \).

Step 3: The client \( n \) observes its own delivery ratio, \( q_n \). It computes \( \psi_n := \rho_n / q_n \). It then determines \( \rho_n^* \geq 0 \) to maximize \( U_n(\rho_n^*) - \rho_n^* \). Client \( n \) updates the amount it pays to \( (1 - \alpha) \rho_n + \alpha \rho_n^* \), with some fixed \( 0 < \alpha < 1 \), and announces the new bid value.

Step 4: Go back to Step 2.

In Step 3 of the game, client \( n \) chooses its new amount of payment as a weighted average of the past amount and
the derived optimal value, instead of the derived optimal value. This design serves two purposes. First, it seeks to avoid the system from oscillating between two extreme values. Second, since \( \rho_n \) is initiated to a positive value, and \( \rho_n^* \) derived in each iteration is always non-negative, this design guarantees \( \rho_n \) to be positive throughout all iterations. Since \( \psi_n = \rho_n / q_n \) this also ensures \( \psi_n > 0 \) and the function \( U_n(q_n) \) is consequently always well-defined.

We show that the fixed point of this repeated game maximizes the total utility of the system:

**Theorem 3:** Suppose at the fixed point of the repeated game, each client \( n \) pays \( \rho_n^* \) per period, and receives delivery ratio \( q_n^* \). If both \( \rho_n^* \) and \( q_n^* \) are positive for all \( n \), the vector \( q^* \) maximizes the total utility of the system.

**Proof:** Let \( \psi_n^* = \frac{\rho_n^*}{q_n^*} \). It is positive since both \( \rho_n^* \) and \( q_n^* \) are positive. Since the vectors \( q^* \) and \( \rho^* \) are derived from the fixed point, \( \rho_n^* \) maximizes \( U_n(q_n^*) - \rho_n \), over all \( \rho_n \geq 0 \), as described in Step 3 of the game. Thus, \( \rho_n^* \) is a solution to \( \text{CLIENT}_n \), given \( \rho_n^* = \psi_n^* q_n^* \). Similarly, from Step 2, \( q_n^* \) is the feasible vector that maximizes \( \sum_{n=1}^{N} \rho_n^* \log q_n \), over all feasible vectors \( q \). Thus, \( q^* \) is a solution to \( \text{ACCESS-POINT} \), given that each client \( n \) pays \( \rho_n^* \) per period. By Theorem 2 \( q^* \) is the unique solution to \( \text{SYSTEM} \) and therefore maximizes the total utility of the system. \( \blacksquare \)

Next, we describe the meaning of the game. In Step 3, client \( n \) assumes a linear relation between the amount it pays, \( \rho_n \), and the delivery ratio it receives, \( q_n \). To be more exactly, it assumes \( \rho_n = \psi_n q_n \), where \( \psi_n \) is the price. Thus, maximizing \( U_n(q_n) - \rho_n \) is equivalent to maximizing \( U_n(q_n) - \rho_n^* \). Recall that \( U_n(q_n) \) is the utility that client \( n \) obtains when it receives delivery ratio \( q_n \). \( U_n(q_n) - \rho_n \) is therefore the net profit that client \( n \) gets. In short, in Step 3, the goal of client \( n \) is to selfishly maximize its own net profit using a first order linear approximation to the relation between payment and delivery ratio.

We next discuss the behavior of the AP in Step 2. The AP schedules clients so that the resulting delivery ratio vector \( q \) is a solution to the problem \( \text{ACCESS-POINT} \), given that each client \( n \) pays \( \rho_n \) per period. Thus, \( q \) is feasible and there exists vectors \( \zeta \) and \( \mu \) that satisfy conditions (16)–(19). While it is difficult to solve this problem, we consider a special restrictive case that gives us a simple solution and insights into the AP’s behavior.

Let \( \text{TOT} := \{1, 2, \ldots, N\} \) be the set that consists of all clients. We assume that a solution \((q, \zeta, \mu)\) to the problem has the following properties: \( \zeta_S = 0 \), for all \( S \neq \text{TOT} \), \( \zeta_{\text{TOT}} > 0 \), and \( \mu_n = 0 \), for all \( n \). By (16), we have:

\[
-\frac{\rho_n}{q_n} + \frac{\sum_{S \neq \text{TOT}} \zeta_S}{p_n} - \mu_n = -\frac{\rho_n}{q_n} + \frac{\zeta_{\text{TOT}}}{p_n} = 0,
\]

and therefore \( q_n = \rho_n / \zeta_{\text{TOT}} \). Further, since \( \zeta_{\text{TOT}} > 0 \), (17) requires that:

\[
\sum_{i \in \text{TOT}} \frac{q_i - (\tau - I_{\text{TOT}})}{p_i} = \sum_{i \in \text{TOT}} \frac{\rho_i}{p_i} = (\tau - I_{\text{TOT}}) = 0.
\]

Thus, \( \zeta_{\text{TOT}} = \sum_{i=1}^{N} \frac{\rho_i}{\tau - I_{\text{TOT}}} \) and \( \rho_n = \sum_{i=1}^{N} \frac{\rho_i}{\tau - I_{\text{TOT}}} \), for all \( n \). Notice that the derived \((q, \zeta, \mu)\) satisfies conditions (16)–(19). Thus, under the assumption that \( q \) is feasible, this special case actually maximizes \( \sum_{i=1}^{N} \rho_i \log q_i \). In Section VI we will address the general situation without any such assumption, since it needs not be true.

Recall that \( I_{\text{TOT}} \) is the average number of time slots that the AP is forced to be idle in a period after it has completed all clients. Also, by Lemma 1 \( \frac{\rho_i}{p_i} \) is the workload of client \( n_i \), that is, the average number of time slots that the AP should spend working for client \( n_i \). Thus, letting \( \frac{\rho_i}{p_i} = \sum_{i=1}^{N} \frac{\rho_i}{\sum_{i=1}^{N} \rho_i} \), for all \( n_i \), the AP tries to allocate those non-idle time slots so that the average number of time slots each client gets is proportional to its payment. Although we only study the special case of \( I_{\text{TOT}} \) here, we will show that the same behavior also holds for the general case in the Section VI.

In summary, the game proposed in this section actually describes a bidding game, where clients are bidding for non-idle time slots. Each client gets a share of time slots that is proportional to its bid. The AP thus assigns delivery ratios, based on which the clients calculate a price and selfishly maximize their own net profits. Finally, Theorem 2 states that the equilibrium point of this game maximizes the total utility of the system.

### VI. A SCHEDULING POLICY FOR SOLVING ACCESS-POINT

In Section V we have shown that by setting \( q_n = \frac{p_n \sum_{i=1}^{N} \rho_i (\tau - I_{\text{TOT}})}{\sum_{i=1}^{N} p_i \rho_i} \), the resulting vector \( q \) solves \( \text{ACCESS-POINT} \) provided \( q \) is indeed feasible. Unfortunately, such \( q \) is not always feasible and solving \( \text{ACCESS-POINT} \) is in general difficult. Even for the special case discussed in Section V solving \( \text{ACCESS-POINT} \) requires knowledge of channel conditions, that is, \( \rho_n \). In this section, we propose a very simple priority based scheduling policy that can achieve the optimal solution for \( \text{ACCESS-POINT} \), and that too without any knowledge of the channel conditions.

In the special case discussed in Section V, the AP tries, though it may be impossible in general, to allocate non-idle time slots to clients in proportion to their payments. Based on this intuitive guideline, we design the following scheduling policy. Let \( w_n(t) \) be the number of time slots that the AP has allocated for client \( n \) up to time \( t \). At the beginning of each period, the AP sorts all clients in increasing order of \( \frac{w_n(t)}{\rho_n} \), so that \( \frac{w_n(t)}{\rho_n} \leq \frac{w_n(t)}{\rho_n} \leq \ldots \) after renumbering clients if necessary. The AP then schedules transmissions according to the priority ordering, where clients with smaller \( \frac{w_n(t)}{\rho_n} \) get higher priorities. Specifically, in each time slot during the period, the AP chooses the smallest \( i \) for which the packet for client \( i \) is not yet delivered, and then transmits the packet for client \( i \) in that time slot. We call this the weighted transmission policy (WT). Notice that the policy only requires the AP to keep track of the bids of clients and the number of time slots each client has been allocated in the past, followed by a sorting of \( \frac{w_n(t)}{\rho_n} \) among all clients. Thus, the policy requires no information on the actual channel conditions, and is tractable. Simple as it is, we show that the policy actually achieves the optimal solution for \( \text{ACCESS-POINT} \). In the following sections, we first prove that the vector of
delivery ratios resulting from the WT policy converges to a single point. We then prove that this limit is the optimal solution for ACCESS-POINT. Finally, we establish that the WT policy additionally achieves some forms of fairness.

A. Convergence of the Weighted Transmission Policy

We now show that, by applying the WT policy, the delivery ratios of clients will converge to a vector q. To do so, we actually prove the convergence property and precise limit of a more general class of scheduling policies, which not only consists of the WT policy but also a scheduling policy proposed in [8]. The proof is similar to that used in [8] and is based on Blackwell’s approachability theorem [3]. The proof in [8] only shows that the vector of delivery ratios approaches a desirable set in the policy proposed in [8]. The proof is similar to that used in [3]. The proof in [8] only shows that the vector of delivery ratios converges to a single point under a more general class of scheduling policies. Thus, our result is both stronger and more general than the one in [8].

We start by introducing Blackwell’s approachability theorem. Consider a single player repeated game. In each round i of the game, the player chooses some action, a(i), and receives a reward r(i), which is a random vector whose distribution is a function of a(i). Blackwell studies the long-term average of the rewards received, \[ \lim_{n \to \infty} \frac{1}{n} \sum_{i=1}^{n} r(i) / j, \] defining a set as approachable, under some policy, if the distance between \( \sum_{i=1}^{n} r(i) / j \) and the set converges to 0 with probability one, as j \( \to \infty \).

Theorem 4 (Blackwell [3]): Let A \( \subseteq \mathbb{R}^N \) be any closed set. Suppose that for every \( x \notin A \), a policy \( \eta \) chooses an action \( a = a(x) \), which results in an expected payoff vector \( E(r) \). If the hyperplane through \( y \), the closest point in A to x, is approachable with the policy \( \eta \).

Now we formulate our more general class of scheduling policies. We call a policy a generalized transmission time policy if, for a choice of a positive parameter vector \( a \) and non-negative parameter vector \( b \), the AP sorts clients by \( a_n u_n - b_n t \) at the beginning of each period, and gives priorities to clients with lower values of this quantity. Note that the special case \( a_n \equiv \frac{1}{\tau_n} \) and \( b_n \equiv 0 \) yields the WT policy, while the choice \( a_n \equiv 1 \) and \( b_n \equiv \frac{2}{\tau_n} \) yields the largest time-based debt first policy of [8], and thus we describe a more general set of policies.

Theorem 5: For each generalized transmission time policy, there exists a vector \( q \) such that the vector of work loads resulting from the policy converges to \( w(q) := [w_n(q_n)] \).

Proof: Given the parameter \( \{a_n, b_n\} \) for the limiting q, we give an exact expression for the limiting q. We define a sequence of sets \( \{H_k\} \) corresponding values \( \{\theta_k\} \) iteratively as follows. Let \( H_0 := \emptyset, \theta_0 := 0 \), and

\[
H_k := \text{arg min}_{S \subseteq \mathbb{N}} \frac{1}{|S|} (I_{H_k \neq S} - I_S) - \sum_{n \in S \setminus H_{k-1}} \frac{b_n}{a_n},
\]

\[
\theta_k := \frac{1}{|H_k \setminus H_{k-1}|} - \sum_{n \in H_k \setminus H_{k-1}} \frac{b_n}{a_n}, \quad \text{for all } k \geq 1.
\]

In selecting \( H_k \), we always choose a maximal subset, breaking ties arbitrarily. \((H_1, \theta_1), (H_2, \theta_2), \ldots \), can be iteratively defined until every client is in some \( H_k \). Also, by the definition, we have \( \theta_k \geq \theta_{k-1} \), for all \( k \geq 0 \). If client \( n \) is in \( H_k \setminus H_{k-1} \), we define \( q_n := \tau_n b_n / a_n \), and so \( w_n(q_n) = \tau_n b_n / a_n \). The proof of convergence consists of two parts. First we prove that the vector of work performed (see Lemma 1 for definition) approaches the set \( \{w_n \geq w_n(q_n)\} \). Then we prove that \( w(q) \) is the only feasible vector in the set \( \{w_n \geq w_n(q_n)\} \). Since the feasible region for work loads, defined as the set of all feasible vectors for work loads, is approachable under any policy, the vector of work performed resulting from the generalized transmission time policy must converge to \( w(q) \).

For the first part, we prove the following statement: for each \( k \geq 1 \), the set \( W_k := \{w_n \geq \tau_n b_n / a_n \} \) is approachable. Since \( \cap_{n \geq 0} W_i = \{w_n \geq w_n(q_n)\} \), we also prove that \( \{w_n \geq w_n(q_n)\} \) is approachable.

Consider a linear transformation on the space of work-loads \( L(w) := [l_n : l_n = a_n w_n / \sqrt{a_n}] \). Proving \( W_k \) is equivalent to proving that its image under \( L, V_k := \{l_n \geq \sqrt{a_n} \forall n \notin H_{k-1}\} \), is approachable. Now we apply Blackwell’s theorem. Suppose that at some time \( t \) that is the beginning of a period, the number of time slots that the AP has worked on client \( n \) is \( u_n(t) \). The work performed for client \( n \) is \( u_n(t) / \tau_n \), and the image under the generalized transmission time policy is \( x(t) := [x_n(t) = a_n u_n(t) / \sqrt{a_n}] \), which we shall suppose is not in \( V_k \). The generalized transmission time policy sorts clients so that \( a_1 u_1 - b_1 \leq a_2 u_2 - b_2 \leq \ldots \), or equivalently, \( \sqrt{a_1} x_1(t) \leq \sqrt{a_2} x_2(t) \leq \ldots \). The closest point in \( V_k \) to \( x(t) \) is \( y := [y_n], \) where \( y_n = \frac{\theta_n}{\sqrt{a_n}} \), and \( x_n(t) < \frac{\theta_n}{\sqrt{a_n}} \) and \( n \notin H_{k-1} \), and \( y_n = x_n \), otherwise. The hyperplane that passes through \( y \) and is orthogonal to the line segment \( xy \) is:

\[ \{z : f(z) := \sum_{n : n \leq n_0, n \notin H_{k-1}} (z_n - \frac{\theta_n}{\sqrt{a_n}})(x_n(t) - \frac{\theta_n}{\sqrt{a_n}}) = 0 \}. \]

Let \( \pi_n \) be the expected number of time slots that the AP spends on working for client \( n \) in this period under the generalized transmission time policy. The image under \( L \) of the expected reward in this period is \( \pi_L := [a_n \pi_n \sqrt{a_n}] \).

Blackwell’s theorem shows that \( V_k \) is approachable if \( x(t) \) and \( \pi_L \) are separated by the plane \( \{z : f(z) = 0\} \). Since \( f(x(t)) \geq 0 \), it suffices to show \( f(\pi_L) \leq 0 \).

We manipulate the original ordering, for this period, so that all clients in \( H_{k-1} \) have higher priorities than those not in \( H_{k-1} \), while preserving the relative ordering between clients not in \( H_{k-1} \). Note this manipulation will not give any client \( n \notin H_{k-1} \) higher priority than it had in the original ordering. Therefore, \( \pi_n \) will not increase for any \( n \notin H_{k-1} \). Since the value of \( f(\pi_L) \) only depends on \( \pi_n \) for \( n \notin H_{k-1} \), and increases as those \( \pi_n \) decrease, this manipulation will not decrease the value of \( f(\pi_L) \). Thus, it suffices to prove that \( f(\pi_L) \leq 0 \), under this new ordering.

Let \( n_0 := |H_{k-1} | + 1 \). Under this new ordering, we have:
\[ \sqrt{a_n x_{n0}(t)} \leq \sqrt{an_{0}x_{n0} + 1}x_{n0+1}(t) \leq \cdots \leq \sqrt{a_{n1}}x_{n1}(t) < \theta_k \leq \sqrt{a_{n1}x_{n1} + 1}x_{n1+1}(t). \]

Let \( \delta_n = \sqrt{a_n x_n(t)} - \sqrt{a_{n+1} x_n + 1}(t) \), for \( n_0 \leq n \leq n_1 - 1 \) and \( \delta_{n1} = \sqrt{a_{n1} x_{n1}(t)} < \theta_k \). Clearly, \( \delta_n \leq 0 \), for all \( n_0 \leq n \leq n_1 \). Now we can derive:

\[
 f(\pi_L) = \sum_{n=n_0}^{n_1} \left( \frac{a_n \pi_n (\tau - n) - \theta_k}{\sqrt{a_n}} \right) (x_n(t) - \theta_k) \\
 = \sum_{n=n_0}^{n_1} \left( \frac{\tau - n}{\tau} x_n(t) - \theta_k \right) (\sqrt{a_n}x_n(t) - \theta_k) \\
 = \sum_{i=n_0}^{n_1} \left( \sum_{n=n_0}^{n_1} \pi_n - \sum_{n=n_0}^{n_1} b_n - \theta_k \sum_{n=n_0}^{n_1} \frac{1}{\sqrt{a_n}} \right) \delta_i.
\]

Recall that \( I_S \) is the expected number of idle time slots when the AP only caters on the subset \( S \). Thus, under this ordering, we have \( \sum_{n=n_0}^{n_1} \pi_n = \tau - I_{(1,...,i)} \) for all \( i \), and \( \sum_{n=n_0}^{n_1} \pi_n = I_{(1,...,n_1)} - I_{(1,...,i)} \) for all \( i \geq n_0 \). By the definition of \( H_k \) and \( \theta_k \), we also have

\[
\sum_{n=n_0}^{n_1} \frac{\pi_n}{\tau} - \sum_{n=n_0}^{n_1} \frac{b_n}{\theta_k} \sum_{n=n_0}^{n_1} \frac{1}{\sqrt{a_n}} = \frac{1}{\tau} (\sum_{n=n_0}^{n_1} \frac{b_n}{\theta_k} - \sum_{n=n_0}^{n_1} \frac{b_n}{\theta_k n_0}) \geq 0.
\]

Therefore, \( f(\pi_L) \leq 0 \), since \( \delta_i \leq 0 \), and \( V_k \) is indeed approachable, for all \( k \).

We have established that the set \( \{ w^* | w^* \geq w(q) \} \) is approachable. Next we prove that \( |w(q)| \) is the only feasible vector in the set. Consider any vector \( w^* \neq w(q) \) in the set. We have \( w_n' \geq w_n(q) \) for all \( n \), and \( w_n' > w_n(q_n) \), for some \( n_0 \). Suppose \( n_0 \in H_k \backslash H_{k-1} \). We have:

\[
\sum_{n \in H_k} w_n' > \sum_{n \in H_k} w_n(q_n) = \sum_{i=1}^{k} \sum_{n \in H_k \backslash H_{i-1}} \frac{b_n + \theta_k}{\pi_n} \\
= \sum_{i=1}^{k} (I_{H_{i-1}} - I_{H_k}) = \tau - I_{H_k},
\]

and thus \( w' \) is not feasible. Therefore, \( w(q) \) is the only feasible vector in \( \{ w^* | w^* \geq w_n(q_n) \} \), and the vector of work performed resulting from the generalized transmission policy must converge to \( w(q) \).

**Corollary 1:** For the policy of Theorem 5 the vector of delivery ratios converges to \( q \).

**Proof:** Follows from Lemma 1.

**B. Optimality of the Weighted Transmission Policy for ACCESS-POINT**

**Theorem 6:** Given \( |\rho_n| \), the vector \( q \) of long-term average delivery ratios resulting from the WT policy is a solution to ACCESS-POINT.

**Proof:** We use the sequence of sets \( \{ H_k \} \) and values \( \{ \theta_k \} \), with \( \theta_0 := \frac{1}{\rho} \) and \( \theta_0 := 0 \), as defined in the proof of Theorem 5. Let \( K := \{|\theta|\} \). Thus, we have \( H_k = TOT = \{ 1, 2, \ldots, N \} \). Also, let \( m_k := |H_k| \). For convenience, we renumber clients so that \( H_k = \{ 1, 2, \ldots, m_k \} \). The proof of Theorem 5 shows that \( q_n = \tau \rho_n \theta_n \), for \( n \in H_k \backslash H_{k-1} \). Therefore, \( w_n(q_n) = \tau \theta_n \rho_n \). Obviously, \( q \) is feasible, since it is indeed achieved by the WT policy. Thus, to establish optimality, we only need to prove the existence of vectors \( \xi \) and \( \mu \) that satisfy conditions (16)–(19).

Set \( \mu_n = 0 \), for all \( n \). Let \( \zeta_{HK} := \zeta_{TOT} := \frac{\rho_n}{w_n(q_n)} = \frac{1}{\tau \theta_n} \) and \( \zeta_{H_k} := \frac{\sum_{n \in H_k} \theta_n}{w_{\rho_n}(q_n)} = \frac{1}{\tau \theta_n} = \frac{1}{\tau \theta_n} \), for \( 1 \leq k \leq K - 1 \). Finally, let \( \zeta := 0 \), for all \( S \notin \{ H_1, H_2, \ldots, H_K \} \). We claim that the vectors \( \xi \) and \( \mu \), along with \( q \), satisfy conditions (16)–(19).

We first evaluate condition (16). Suppose client \( n \) is in \( H_k \backslash H_{k-1} \). Then client \( n \) is also in \( H_{k+1}, H_{k+2}, \ldots, H_K \). So,

\[
- \frac{1}{\tau \theta_n} + \frac{1}{\tau \theta_n} = 0.
\]

Thus, condition (16) is satisfied.

Since \( \mu_n = 0 \), for all \( n \), condition (19) is satisfied. Further, since \( \frac{1}{\theta_n} > \frac{1}{\theta_{n+1}} \), for all \( 1 \leq k \leq K - 1 \), condition (19) is also satisfied. It remains to establish condition (17).

Since \( \zeta_S = 0 \) for all \( S \notin \{ H_1, H_2, \ldots, H_K \} \), we only need to show \( \sum_{i=1}^{N} \zeta_{H_k} \theta_n = 0 \) for \( S \in \{ H_1, H_2, \ldots, H_K \} \).

Consider \( H_k \). For each client \( i \in H_k \) and each client \( j \notin H_k \), \( \frac{w_i(q_n)}{p_i} < w_i(q_n) \). Since \( w_i(q_n) \) is the average number of time slots that the AP spends on working for client \( i \), we have \( \frac{w_i(t)}{p_i} < \frac{w_i(t)}{p_j} \), for all \( i \in H_k \) and \( j \notin H_k \), after a finite number of periods. Therefore, except for a finite number of periods, clients in \( H_k \) will have priorities over those not in \( H_k \). In other words, if we only consider the behavior of those clients in \( H_k \), it is the same as if the AP only works on the subset \( H_k \) of clients. Further, recall that \( I_{H_k} \) is the expected number of time slots that the AP is forced to stay idle when the AP only works on the subset \( H_k \) of clients. Thus, we have \( \sum_{i \in H_k} w_i(q_n) = \tau - I_{H_k} \) and \( \sum_{i \in H_k} \frac{w_i(q_n)}{p_i} - (\tau - I_{H_k}) = 0 \), for all \( k \).

**C. Fairness of Allocated Delivery Ratios**

We now show that the WT policy not only solves the ACCESS-POINT problem but also achieves some forms of fairness among clients. Two common fairness criteria are max-min fair and proportionally fair. We extend the definitions of these two criteria as follows:

**Definition 3:** A scheduling policy is called weighted max-min fair with positive weight vector \( a = \{a_n\} \) if it achieves \( q \), and, for any other feasible vector \( q' \), we have:

\[
q_i' > q_i \Rightarrow q_j' < q_j,
\]

for some \( j \) such that \( \frac{w_i(q_n)}{a_n} \geq \frac{w_j(q)}{a_j} \).

**Definition 4:** A scheduling policy is called weighted proportionally fair with positive weight vector \( a \) if it achieves \( q \) and, for any other feasible vector \( q' \), we have:

\[
\sum_{n=1}^{N} w_n(q_n) - w_n(q_n) \leq 0.
\]

Next, we prove that the WT policy is both weighted max-min fair and proportionally fair with weight vector \( \rho \).

**Theorem 7:** The weighted transmission policy is weighted max-min fair with weight \( \rho \).
On the other hand, the feasibility condition requires \( \sum_{n \in H_k} w_n(q_n) = \tau - I_{H_k} \). On the other hand, the feasibility condition requires \( \sum_{n \in H_k} w_n(q_n) = \tau - I_{H_k} \). Further, since \( q'_i > q_i \), \( w_i(q'_i) > w_i(q_i) \), there must exist some \( j \in H_k \) so that \( w_j(q'_j) < w_j(q_j) \), that is, \( q'_j < q_j \). Finally, since \( i \in H_k \setminus H_{k-1} \), we have \( w_n(q'_n) \geq \frac{w_n(q_n)}{\rho_n} \), for all \( n \in H_k \), and hence \( \frac{w_n(q'_n)}{\rho_n} > \frac{w_n(q_n)}{\rho_n} \).

\[ \sum_{n \in H_k} w_n(q'_n) - w_n(q_n) = \frac{k_i}{\tau \theta_i} \leq 0, \text{ for all } k > 0. \]

First consider the case \( k = 1 \). The proof in Theorem 6 shows that \( \sum_{n \in H_k} w_n(q_n) = \tau - I_{H_k} \). Further, the feasibility condition requires \( \sum_{n \in H_k} w_n(q'_n) \leq \tau - I_{H_k} \). Define \( \Delta_k := \sum_{n \in H_k \setminus H_{k-1}} w_n(q_n) - w_n(q_n) \). Then, we have \( \frac{\Delta_k}{\rho_n} \leq 0 \).

Suppose we have \( \sum_{i=1}^{k} \frac{\Delta_i}{\tau \theta_i} \leq 0 \), for all \( k \leq k_0 \). Again, the proof in Theorem 6 gives us \( \sum_{n \in H_{k_0+1}} w_n(q_n) = \tau - I_{H_{k_0+1}} \) and the feasibility condition requires \( \sum_{n \in H_{k_0+1}} w_n(q'_n) \leq \tau - I_{H_{k_0+1}} = \sum_{n \in H_{k_0+1}} w_n(q_n) \). Thus, \( \sum_{i=1}^{k_0} \Delta_i \leq 0 \). We can further derive:

\[ \sum_{i=1}^{k_0} \frac{\Delta_i}{\tau \theta_i} \leq \sum_{i=1}^{k_0} \frac{\Delta_i}{\tau \theta_i}(1 - \frac{\theta_i}{\theta_{k_0+1}}) \quad (\text{since } \sum_{i=1}^{k_0} \frac{\Delta_i}{\tau \theta_{k_0+1}} \leq 0) \]

\[ = \sum_{j=1}^{k_0} \left[ \frac{\theta_{j+1} - \theta_j}{\theta_{k_0+1}} \right] \frac{\Delta_i}{\tau \theta_i} \]

\[ \leq 0 \quad (\text{since } \sum_{i=1}^{k_0} \frac{\Delta_i}{\tau \theta_i} \leq 0, \text{ and } \theta_{j+1} > \theta_j, \forall j \leq k_0) \]

By induction, \( \sum_{i=1}^{k_0} \frac{\Delta_i}{\tau \theta_i} \leq 0 \), for all \( k \). Finally, we have:

\[ \sum_{n=1}^{N} \frac{w_n(q'_n) - w_n(q_n)}{w_n(q_n)/\rho_n} = \sum_{i=1}^{K} \frac{\Delta_i}{\tau \theta_i} \leq 0, \]

and the WT policy is proportionally fair with weight \( \rho \). ■

VII. SIMULATION RESULTS

We have implemented the WT policy and the bidding game, as described in Section VI on ns-2. We use the G.711 codec for audio compression to set the simulation parameters, as summarized in Table I. All results in this section are averages of 20 simulation runs.

| Packetization interval | 20 ms |
|------------------------|-------|
| Payload size per packet| 160 Bytes |
| Transmission data rate  | 11 Mbit/s |
| Transmission time (including MAC overheads) | 610 µs |
| # of time slots in a period | 32 |

A. Convergence Time for the Weighted Transmission Policy

We have proved that the vector of delivery ratios will converge under the WT policy in Section VI-A. However, the speed of convergence is not discussed. In the bidding game, we assume that the delivery ratio observed by each client is post convergence. Thus, it is important to verify whether the WT policy converges quickly. In this simulation, we assume that there are 30 clients in the system. The \( n^{th} \) client has channel reliability \((50 + n)\%\) and offers a bid \( \rho_n = (n \mod 2) + 1 \). We run each simulation for 10 seconds simulation time and then compare the absolute difference of \( \sum \rho_n \log q_n \) between the delivery ratios at the end of each period with those after 10 seconds. In particular, we artificially set \( q_n = 0.001 \) if the delivery ratio for client \( n \) is zero, to avoid computation error for \( \log q_n \).

Simulation results are shown in Fig. 1. It can be seen that the delivery ratios converge rather quickly. At time 0.2 seconds, the difference is smaller than 1.4, which is less than 10% of the final value. Based on this observation, we assume that each client updates its bid every 0.2 seconds in the following simulations.

B. Utility Maximization

In this section, we study the total utility that is achieved by iterating between the bidding game and the WT policy, which we call WT-Bid. We assume that the utility function of each client \( n \) is given by \( \gamma_n q_n^{\alpha_n - 1} \), where \( \gamma_n \) is a positive integer and \( 0 < \alpha_n < 1 \). This utility function is strictly increasing, strictly concave, and differentiable for any \( \gamma_n \) and \( \alpha_n \). In addition to evaluating the policy WT-Bid, we also compare the results of three other policies: a
policy that employs the WT policy but without updating the bids from clients, which we call WT-NoBid; a policy that decides priorities randomly among clients at the beginning of each period, which we call Rand; and a policy that gives clients with larger $\gamma_n$, higher priorities, with ties broken randomly, which we call P-Rand.

In each simulation, we assume there are 30 clients. The $n^{th}$ client has channel reliability $p_n = \frac{50 + n}{\%}$, $\gamma_n = (n \mod 3) + 1$, and $\alpha_n = 0.3 + 0.1(n \mod 5)$. In addition to plotting the average of total utility over all simulation runs, we also plot the variance of total utility.

Fig. 2 shows the simulation results. The WT-Bid policy not only achieves the highest average total utility but also the smallest variance. This result suggests that the WT-Bid policy converges very fast. On the other hand, the WT-NoBid policy fails to provide satisfactory performance since it does not consider the different utility functions that clients may have. The P-Rand policy offers much better performance than both the WT-NoBid policy and the Rand policy since it correctly gives higher priority to clients with higher $\gamma_n$. Still, it cannot differentiate between clients with the same $\gamma_n$ and thus can only provide suboptimal performance.

VIII. CONCLUDING REMARKS

We have studied the problem of utility maximization problem for clients that demand delay-based QoS support from an access point. Based on an analytical model for QoS support proposed in previous work, we formulate the utility maximization problem as a convex optimization problem. We decompose the problem into two simpler subproblems, namely, $\text{CLIENT}_n$ and $\text{ACCESS-POINT}$. We have proved that the total utility of the system can be maximized by jointly solving the two subproblems. We also describe a bidding game to reconcile the two subproblems. In the game, each client announces its bid to maximize its own net profit and the AP allocates time slots to achieve the optimal point of $\text{ACCESS-POINT}$. We have proved that the equilibrium point of the bidding game jointly solves the two subproblems, and therefore achieves the maximum total utility.

In addition, we have proposed a very simple, priority-based weighted transmission policy for solving the $\text{ACCESS-POINT}$ subproblem. This policy does not require that the AP know the channel reliabilities of the clients, or their individual utilities. We have proved that the long-term performance of a general class of priority-based policies that includes our proposed policy converges to a single point. We then proved that the limiting point of the proposed scheduling policy is the optimal solution to $\text{ACCESS-POINT}$. Moreover, we have also proved that the resulting allocation by the AP satisfies some forms of fairness criteria. Finally, we have implemented both the bidding game and the scheduling policy in ns-2. Simulation results suggest that the scheduling policy quickly results in convergence. Further, by iterating between the bidding game and the WT policy, the resulting total utility is higher than other tested policies.

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