Deformation Measurement Method Using Moiré Fringes at High Scanning Speed Under a Laser Scanning Microscope

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Abstract: A full-field deformation measurement method using moiré fringes generated at high scanning speed under a laser scanning microscope (LSM) was proposed. The formation principle and the deformation measurement principle were presented. Simulation and experiment verifications were performed to show the effectiveness and the accuracy of the proposed fast scanning moiré method, where the scanning line spacing is an integral multiple of the basic scanning line spacing. The moiré spacing, and the deformation measurement sensitivity and accuracy are almost the same as in the traditional LSM scanning moiré method. The fast scanning process allows a high scanning speed and a large view field without reducing the deformation measurement sensitivity. The higher measurement speed makes this method more suitable to be combined with the phase-shifting technique than the traditional LSM scanning moiré method. Besides, the application scope of the LSM moiré method in the field of deformation measurement is extended because more specimen gratings can be used to generate moiré fringes.

Keywords: Deformation Measurement, Strain, High Speed, Fast Scanning Moiré Method, Microscope, Grating

1. Introduction

Full-field deformation measurement plays an increasingly important role in mechanical properties evaluation, defect detection, instability as well as failure assessment, residual stress measurement [1] and interfacial bonding strength estimation of multifarious materials and structures. Among various deformation measurement techniques, moiré methods are robust and mature optical methods owing to the non-contact and full-field advantages [2, 3]. With the decrease in the sizes of the test objects [4, 5], various micron/nano-scale moiré methods have been developed to meet the demands for the micron/nano-scale deformation measurement. The most widely used micron/nano-scale moiré method is the high-power microscope moiré method based on the high-resolution and simple-operation features of high-power microscopes [6, 7].

In the last decades, the laser scanning microscope (LSM) moiré method [8-10], the scanning electron microscope (SEM) moiré method [11-14], the atomic force microscope (AFM) moiré method [15] and the transmission electron microscope (TEM) moiré method [16] have been investigated and applied to deformation measurement of a variety of materials and structures. Because of the advantages of non-vacuum environment and simple operation [17], the LSM moiré method have attracted great attention of researchers [8-10, 18]. The LSM moiré fringes can be scanning moiré fringes (interference between the specimen grating and the scanning lines), overlapping moiré fringes (superimposed by the specimen gratings before and after deformation) and secondary moiré fringes (interference between the scanning moiré fringes before and after deformation) [18]. As the LSM scanning moiré has a greater view field than the LSM overlapping moiré and is easier to be generated than the LSM secondary moiré, the LSM moiré refers to the LSM scanning moiré in this study.

Although the LSM scanning moiré method is simple, the discontinuous magnification of the LSM limits its application and popularization. As the magnifications of the LSM objective lens are usually 5×, 10×, 20×, 50×, 100× and
150×, only some specimen gratings with pitches close to scanning spacing can be used to generate clear moiré fringes. Besides, the scanning moiré image acquisition takes time, making the moiré pattern easier to be affected by the specimen creep.

In this study, we propose to generate LSM moiré fringes at high scanning speed. The application scope of the LSM moiré method is extended and the moiré image acquisition speed is much higher than the traditional scanning moiré method.

2. Moiré Formation at High Scanning Speed

The LSM moiré fringes come from the interference between the specimen grating and the LSM scanning lines (reference grating). If the pitch of the specimen grating and the spacing of the scanning lines are respectively defined as \( p \) and \( T_0 \) in the direction \( y \), the phase expressions of the specimen grating and the scanning lines will be \( \phi_s = 2\pi y / p \) and \( \phi_y = 2\pi y / T_0 \), respectively. The direction \( y \) is perpendicular to the direction of the scanning lines.

For the generation of the primary (traditional) scanning moiré fringes, there is a small mismatch or misalignment between the scanning lines and the specimen grating, i.e., \( T_0 \) is close to \( p \). The phase of the primary moiré can be expressed as

\[
\phi_m = 2\pi y \left( \frac{1}{p} - \frac{1}{T_0} \right) + \phi_s + \phi_y
\]

(1)

Where \( \phi_s \) and \( \phi_y \) stand for the phase of the higher frequency items (including \( 2\pi y (1 / p + 1 / T_0) \), \( 2\pi y / p \)) and the initial phase, respectively.

In some cases, it is not easy to meet the condition that the scanning line spacing is close to the specimen grating pitch. Under this circumstance, if the scanning line spacing is close to an integer multiple of the specimen grating pitch, i.e., \( T(n) \) is close to \( np \) (\( n \) is a positive integer), moiré fringes will also emerge as shown in Fig. 1. This case can be realized by scanning the specimen at high scanning speed to make the scanning line spacing greater. The scanning line spacing at high scanning speed can be defined as

\[
T(n) = nT_0
\]

(2)

where \( T_0 \) is the basic scanning line spacing close to the specimen grating pitch (the same meaning as in Eq. (1)). When \( n = 1 \), \( T(1) = T_0 \) and the moiré fringes are the same to the primary moiré fringes.

As \( T(n) \) is close to \( p \), i.e., \( n / T(n) \) is close to \( 1/p \), the dominant frequency item of the moiré phase is \( 2\pi y (1 / p - n / T(n)) \). The phase of the moiré fringes at high scanning speed can be represented by

\[
\phi_m(n) = 2\pi y \left( \frac{1}{p} - \frac{n}{T(n)} \right) + \phi_s(n) + \phi_y(n)
\]

(3)

where \( \phi_s(n) \) and \( \phi_y(n) \) denote the phase of the higher frequency items (including \( 2\pi y (1 / p + n / T(n)) \), \( 2\pi y / p \)) and the initial phase of the moiré fringes at high scanning speed, respectively.

\[\text{Figure 1. Formation principle of moiré fringes at high scanning speed.}\]

3. Principle of Deformation Measurement

As moiré fringes are in approximate periodic distribution, the moiré phase at high scanning speed and the moiré spacing have the following relationship:

\[
\phi_m(n) = 2\pi y / d(n) + \phi_s(n) + \phi_y(n)
\]

(4)

where \( d(n) \) is the moiré spacing in the direction \( y \), and \( \phi_s(n) \) and \( \phi_y(n) \) also indicate the phase of the higher frequency items and the initial phase at high scanning speed, respectively.

By comparing the dominant frequency items of the moiré phase in Eq.(3) and Eq.(4), we can get the relationship between the specimen grating pitch, the scanning line spacing and the moiré spacing as follows:

\[
\frac{1}{p} - \frac{n}{T(n)} = \frac{1}{d(n)}
\]

(5)

Substituting Eq. (2) into Eq. (5), we can find that the moiré spacing remains unchanged no matter what the value of \( n \) is \((n=1, 2, 3, \ldots)\). The following two relationships can be obtained:

\[
d(n) = d, \quad (n = 1, 2, 3, \ldots)
\]

(6)

\[
\frac{1}{p} - \frac{1}{T_0} = \frac{1}{d}
\]

(7)

The moiré fringes at high scanning speed are essentially the contours of equal displacement as a function of the basic scanning line spacing \( T_0 \). If a moiré fringe order is \( k \) (integer), the displacement in the direction \( y \) at the position of this moiré fringe will be

\[
u(n) = kT_0 = kT(n) / n
\]

(8)
The strain of the specimen grating (with pitch of $p$) relative to the basic scanning line (with spacing of $T_0$) is usually given by

$$
\varepsilon(n) = \frac{p-T_0}{T_0} = \frac{p-T(n)/n}{T(n)/n} \quad (9)
$$

Based on Eq. (7) and Eq. (9), the strain of the specimen grating relative to the basic scanning line can be calculated from the following expressions

$$
\begin{align*}
\varepsilon(n) &= \frac{T_0}{d-T_0} \left( \frac{T(n)}{n} - \frac{T(n)/n}{d-T(n)/n} \right) \quad (T(n) < np) \\
\varepsilon(n) &= \frac{-T_0}{d+T_0} \left( \frac{T(n)}{n} - \frac{T(n)/n}{d+T(n)/n} \right) \quad (T(n) > np)
\end{align*}
$$

As the moiré spacing is usually much greater than the basic scanning line spacing ($d >> T_0$) in the direction $y$, Eq. (10) can be simplified to

$$
|\varepsilon(n)| = \frac{T_0}{d} = \frac{T(n)}{nd} \quad (11)
$$

The deformation measurement method from the moiré fringes generated at high scanning speed is called the fast scanning moiré method. The scanning speed is higher than the traditional moiré method. The deformation measurement sensitivity will be discussed in Section 5.

4. Simulation and Experiment Verifications

4.1. Simulation Verification

The phenomenon that the moiré spacing keeps constant regardless of the value of $n$ was verified from simulation and experiments. The deformation measurement accuracy of the fast scanning moiré method was also studied by comparing with the traditional scanning moiré method.

Figure 2 illustrates the simulated (digital sampling) moiré fringes at different scanning resolutions (sampling pitch). A cosine-type parallel grating with pitch of 13 pixels was treated as the specimen grating, as shown in Fig. 2(a). $T_0$=12 pixels was chosen as the basic scanning line spacing. The superposition of the specimen grating and a digital grating with pitch of $T_0$=12 pixels generated the primary moiré pattern, as seen in Fig. 2(b). The digital sampling moiré from the specimen grating at a sampling interval of $T(1)$=12 pixels also produced the primary moiré pattern (Fig. 2(c)), the same as in Fig. 2(b). As a consequence, the digital sampling moiré was used in comparison and discussion on behalf of superposition moiré and the scanning moiré.

The digital sampling moiré patterns at different sampling intervals $T(2)$=24, $T(3)$=36, $T(4)$=48 are displayed in Fig. 2(d), Fig. 2(e) and Fig. 2(f), respectively. It is clear that the moiré spacing remains unchanged no matter what $n$ is ($n=1, 2, 3, 4$). In other words, the moiré spacing stays the same as long as the scanning line spacing $T(n)$ is $n$ times the basic scanning line spacing $T_0$. It should be mentioned that, the moiré contrast decreases with the increase of $n$, since the gray scales in Figs. 2(a)-(f) are the same ranging from -1 to 1. However, the image contrast can be enhanced to make the moiré fringe clear both in the simulation tests and in the real experiments using image processing technique.

Figure 2. Simulation moiré fringes from interference between a specimen grating and reference gratings with different pitches: (a) specimen grating with pitch of 13 pixels, (b) digital sampling moiré from superposition of (a) and a reference grating with pitch of 12 pixels, (c)-(f) simulation moiré from superposition of (a) and reference gratings with pitches of 12 pixels, 24 pixels, 36 pixels and 48 pixels, respectively.

Figure 3. Specimen grating fabricated by UV nanoimprint lithography on silicon.
4.2. Experiment Verification

The deformation measurement accuracy was studied from experiments in this section. A cross grating with pitch of around 0.79 µm was first fabricated on a silicon wafer by UV nanoimprint lithography [20] as presented in Fig. 3.

The silicon wafer with the specimen grating was then put on the sample stage of a laser scanning microscope (Lasertec, OPTELICS HYBRID L3). The scanning line number could be 1024, 512 and 256 in the y direction. When we chose the objective lens with magnification of 20 × and the scanning line number is 512 in the y direction, the scanning line spacing was \( T_0 = 0.726 \) µm, close to the specimen grating pitch. The primary scanning moiré pattern from the interference between the specimen grating and the scanning line with spacing of 0.726 µm is shown in Fig. 4(a). Under the same objective lens, the scanning line spacing was \( T(2) = 2T_0 = 1.452 \) µm when the scanning line number was 256. In this case, the fast scanning moiré pattern from the interference between the specimen grating and the scanning line with spacing of 1.452 µm emerged as seen in Fig. 4(b).

![Figure 4](image1.png)

(a) The scanning line spacing is \( T(1) = 0.726 \) µm when the scanning line number is 512

(b) The scanning line spacing is \( T(2) = 1.452 \) µm when the scanning line number is 256

Figure 4. LSM moiré patterns at different scanning resolutions on silicon when the magnification of the objective lens is 20×.

To prevent the influence of the potential scanning distortion on the moiré fringes in the edge region, two same areas labeled by the red squares in Figs. 4(a) and (b) were chosen to be used for deformation measurement. The intensity profiles of the LSM moiré patterns in the labeled areas (217.7×217.7 µm²) in Figs. 4(a) and (b) were plotted in Figs. 5(a) and (b), respectively. It can be seen that the intensity profile and the moiré spacing when the scanning line spacing is 0.726 µm are almost the same to those when the scanning line spacing is 1.452 µm. It also confirms the phenomenon that the moiré spacing remain unchanged as long as the scanning line spacing is several times the basic scanning line spacing.

The deformation distributions of the specimen grating relative to the basic scanning lines \( (T_0=0.726 \) µm) were calculated from the LSM moiré patterns in Figs. 5(a) and (b) based on Eqs. (8) and (10). The displacement between two moiré fringes was obtained from one-dimensional parabolic interpolation in the software Moiré Analysis. The displacement and the strain distributions calculated from Fig. 5(a) when \( T(1)=0.726 \) µm were drawn in Fig. 6, and those calculated from Fig. 5(b) when \( T(2)=1.452 \) µm were plotted in Fig. 7.

The average strain in Fig. 6(b) when \( T(1)=0.726 \) µm is...
0.08992, and the average strain in Fig. 7(b) when $T(2)=1.452$ μm is 0.08981 relative to the basic scanning lines ($T_0=0.726$ μm). Compared with the result from the traditional (primary) scanning moiré method when $T(1)=T_0=0.726$ μm, the relative error of the strain when $T(2)=1.452$ μm is only 0.12%, demonstrating the validity of the proposed fast scanning moiré method. The slight differences between the displacement and the strain distributions in Fig. 6 and Fig. 7 are due to vibration and random noise of detector.

![Figure 6](image1.png)
**Figure 6.** Deformation distributions of the specimen grating relative to the basic scanning lines ($T_0=0.726$ μm) calculated from Figure 5 (a) when $T(1)=0.726$ μm in an area of 217.7×217.7 μm².

![Figure 7](image2.png)
**Figure 7.** Deformation distributions of the specimen grating relative to the basic scanning lines ($T_0=0.726$ μm) calculated from Figs. 5 (b) when $T(2)=1.452$ μm in an area of 217.7×217.7 μm².

### 5. Discussion

From the simulation and experiment results in Section 4, the moiré spacing remain unchanged if the scanning line spacing is $n$ times the basic scanning line spacing ($T_0$ is close to $p$), i.e., $T(n)=nT_0$, regardless of the value of $n$. This phenomenon is different from the case that the moiré spacing changes with the variation of the scanning line spacing in the multiplication moiré method [21]. Experiments show that the high scanning speed only have little effect on the deformation measurement accuracy in the proposed method.

Next, the deformation measurement sensitivity of the proposed method will be analyzed theoretically. From Eq. (8), the displacement sensitivity of the proposed method is $T(n)/n$ per fringe, the same to the displacement sensitivity $T_0$ per fringe in the traditional scanning moiré method. The strain sensitivity is defined as the minimum strain which can be measured, i.e., the strain when there are only two moiré fringes in the full view field, i.e., $d=(N(n)-1)T(n)$, where $N(n)$ is the scanning line number (such as 1024, 512, 256). According to Eq. (11), the strain sensitivity of the proposed method is

$$
\frac{T(n)}{n(N(n)-1)T(n)} = \frac{1}{n(N(n)-1)}
$$

As the full view field can also be expressed as $d=(N_0-1)T_0$ ($N_0$ is the basic scanning line number when $T_0$ is close to $p$), the strain sensitivity can also be calculated from

$$
\frac{T(n)}{n(N_0-1)T_0} = \frac{1}{(N_0-1)}
$$

based on Eq. (11) and Eq. (2), the same to the strain sensitivity $1/(N_0-1)$ of the traditional moiré method. In other words, both the displacement and the strain measurement sensitivities of the proposed moiré method are the same to those of the traditional scanning moiré method.

The major advantage of the proposed fast scanning moiré method is that the scanning speed is several times higher than the traditional scanning moiré method because the scanning line number is several times less in the same view field. The proposed method is more insusceptible to the specimen creep and more suitable to be combined with the phase-shifting
technique to improve the measurement accuracy with high spatial resolution. The high scanning speed can also be realized by using an objective lens with reduced magnification when the scanning line number cannot be adjusted. On this occasion, the view field will be greater than the traditional scanning moiré method, which is another advantage. In addition, as more grating pitches can be used to generate moiré fringes, the application scope of the LSM moiré method for deformation measurement is extended.

6. Conclusions

In this study, a deformation measurement method using moiré fringes generated at high scanning speed, i.e., the fast scanning moiré method was proposed and studied under a laser scanning microscope (LSM). The deformation measurement principle was introduced. The high scanning speed has little effect on the moiré spacing and the deformation measurement sensitivity as well as accuracy. The proposed method has a high image acquisition speed in a large and full view field, making it more insusceptible to the specimen creep and more suitable to be integrated with the phase-shifting technique. Moreover, gratings with more pitches are usable in the LSM moiré method for the micron/submicron-scale deformation measurement.

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