Phase Space Approach to Laser-driven Electronic Wavepacket Propagation

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We propose a phase space method to propagate a quantum wavepacket driven by a strong external field. The method employs the so-called biorthogonal von Neumann basis recently introduced for the calculation of the energy eigenstates of time-independent quantum systems [A. Shimshovitz and D.J. Tannor, arXiv:1201.2299v1]. While the individual elements in this basis set are time-independent, a small subset is chosen in a time-dependent manner to adapt to the evolution of the wavepacket in phase space. We demonstrate the accuracy and efficiency of the present propagation method by calculating the electronic wavepacket in a one-dimensional soft-core atom interacting with a superposition of an intense, few-cycle, near-infrared laser pulse and an attosecond extreme-ultraviolet laser pulse.

With the emergence of attosecond laser technology,1 there is a fascinating prospect of observing and controlling the correlated dynamics of multiple electrons on its natural time scale of ten to one hundred attoseconds.2 In order to unravel the complex and sometimes counterintuitive quantum dynamics from the experimental data, and to develop theories that reproduce the essence of the dynamics, an accurate and efficient numerical method to simulate the multi-electron wavepacket dynamics is indispensable.

However, accurate simulation of the electronic dynamics in a high-intensity laser field is a challenging task: the electronic wavepacket is dispersed by the laser field over a wide region of coordinate space while retaining high momentum near the atomic nuclei. Straightforward representation of the wavefunction on a equally-spaced coordinate grid [i.e., a Fourier grid (FG)] requires a large range with a small interval between points. Simulation on such a large grid quickly becomes prohibitive as the number of degrees of freedom (DOF) increases. Even with sophisticated treatments such as multi-configuration time-dependent Hartree-Fock (MCTDHF), simulation of ionization dynamics have been limited to small systems such as the helium atom and the hydrogen molecule.7,12

In this article, we present a new approach to solving the time-dependent Schrödinger equation (TDSE), as the helium atom and the hydrogen molecule. In our approach, we utilize the localized nature of the dynamics, resolving the identification of linear ordinary differential equations (ODEs) for the expansion coefficients in the truncated bvN basis.

The bases \(|\theta_m\rangle\) and \(|\phi_m\rangle\) are orthonormal and span the same N-D Hilbert space denoted here as \(\mathcal{H}\), resolving the identity in \(\mathcal{H}\) as

\[
1_{\mathcal{H}} = \sum_{m=1}^{N} |\phi_m\rangle \langle \phi_m | = \sum_{m=1}^{N} |\theta_m\rangle \langle \theta_m |.
\]

The bases \(|\theta_m\rangle\) and \(|\phi_m\rangle\) are localized at the FG points \(\{x_m\}_{m=1,...,N}\) in the position space and \(\{p_m\}_{m=1,...,N}\) in the momentum space, respectively. For any quantum state \(|\Psi\rangle\in\mathcal{H}\), \(\langle \theta_m | \Psi \rangle = \langle x_m | \Psi \rangle \sqrt{\Delta x}\) and \(\langle \phi_m | \Psi \rangle = \langle p_m | \Psi \rangle \sqrt{\Delta p}\), where \(\Delta x\) and \(\Delta p\) are the grid intervals in position and momentum spaces, respectively.

The pvN basis20,21 \(|\tilde{g}_j\rangle\) is defined as

\[
|\tilde{g}_j\rangle = \sum_{m=1}^{N} |\theta_m\rangle |x_m\rangle |g_j\rangle \sqrt{\Delta x},
\]

\[j=1,...,N\]

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where \( \{ |g_j\rangle \}_j=1,...,N \) are the phase space Gaussians,
\[
\langle x|g_j\rangle = \left( \frac{\gamma}{\pi} \right)^{1/4} \exp \left( -\frac{\gamma}{2} (x - q_j)^2 + i \frac{\gamma}{\hbar} p_j (x - q_j) \right)
\]
\[
+ i \frac{\gamma}{2\hbar p_j} (x - q_j),
\]
whose centers \( \{(q_j, p_j)\}_j=1,...,N \) constitute a finite lattice in the phase space with the unit cell of area \( 2\pi\hbar \) and the momentum-to-position aspect ratio \( \hbar\gamma \). Note that the number of Gaussians \( N \) is the same as the number of FG points used.

The bvN basis \( \{ |\tilde{b}_j\rangle \}_j=1,...,N \) is defined to be biorthogonal (dual) to the pvN basis, i.e., \( \langle \tilde{b}_j|g_j\rangle = \delta_{ij} \). This gives
\[
|\tilde{b}_j\rangle = \sum_{l=1}^N |\tilde{g}_l\rangle (S^{-1})_{lj},
\]
where \( S^{-1} \) is the inverse of the overlap matrix \( S_{lj} = \langle \tilde{g}_l|\tilde{g}_j\rangle = \Delta x \sum_{m=1}^N \langle g_l|x_m\rangle \langle x_m|g_j\rangle \) of the pvN basis. The pvN and bvN bases span the same Hilbert space \( \mathcal{H} \) as \( \{ |\phi_m\rangle \} \) and \( \{ |\theta_m\rangle \} \), resolving the identity as
\[
1_{\mathcal{H}} = \sum_{j=1}^N |\tilde{b}_j\rangle \langle \tilde{b}_j| = \sum_{j=1}^N |g_j\rangle \langle g_j|.
\]
Thus, any wavepacket \( |\Psi(t)\rangle \in \mathcal{H} \) can be represented as
\[
|\Psi(t)\rangle = \sum_{j=1}^N |\tilde{b}_j\rangle \langle g_j|\Psi(t)\rangle.
\]
Due to the localized nature of the Gaussians \( \{|g_j\rangle\} \), the magnitude of \( \langle \tilde{g}_j|\Psi(t)\rangle \) can be extremely small if the corresponding classical system cannot reach the phase space region around \( (q_j, p_j) \). Defining a set \( \mathcal{A} \) such that \( \langle \tilde{g}_j|\Psi(t)\rangle \) is negligible if \( j \not\in \mathcal{A} \), we can approximate the wavepacket by a subset of the bvN basis as
\[
|\Psi(t)\rangle \approx \sum_{j\in\mathcal{A}} |\tilde{b}_j\rangle c_j(t),
\]
where \( c_j(t) := \langle \tilde{g}_j|\Psi(t)\rangle \). Note that the set \( \mathcal{A} \) of active indices can be changed in time in order to keep the number \( N_{\mathcal{A}} \) of elements in \( \mathcal{A} \) small at all time.

By substituting eq. (11) to the TDSE, we obtain a set of linear ODEs for the active bvN coefficients \( \{c_j\}_{j\in\mathcal{A}} \),
\[
\frac{dc_j}{dt} = -i \frac{\hbar}{\Delta t} \sum_{l\in\mathcal{A}} \sum_{m\in\mathcal{A}} (\Omega^{-1})_{jl} \langle \tilde{b}_l|H(t)|\tilde{b}_m\rangle c_m(t),
\]
where \( \Omega^{-1} \) is the inverse of the overlap matrix \( \Omega_{lj} = \langle \tilde{b}_j|\tilde{b}_l\rangle = (S^{-1})_{lj} \) of the bvN basis, and \( H(t) \) is the Hamiltonian operator of the system. The overlap and Hamiltonian matrix elements in eq. (3) can be computed simply via the representations in \( \{|\theta_m\rangle\} \) and \( \{|\phi_m\rangle\} \). The matrix \( \Omega^{-1} \) is Hermitian positive-definite, and the elements \( \{ \langle \tilde{b}_l|H(t)|\tilde{b}_m\rangle \} \) constitute an Hermitian matrix. Therefore, the product of these matrices yields all real eigenvalues \( \delta \), and eq. (3) can be solved stably by many standard numerical algorithms.

To demonstrate the accuracy and efficiency of the present method, we solve eq. (3) for the electronic wavepacket of a 1D atom in the combined field of NIR and XUV laser pulses. The Hamiltonian of this system is given as
\[
H(t) = H_0 + V(t),
\]
where \( H_0 \) is the field-free Hamiltonian expressed as
\[
H_0 = \frac{p^2}{2\mu} - \frac{Q e^2}{4\pi\epsilon_0 \sqrt{x^2 + a^2}}.
\]
Here \( \mu = 1 \) a.u. is the electron mass, \( e = -1 \) a.u. is the electron charge, \( -Q e = 1 \) a.u. is the charge of the atomic nucleus, \( a = 1 \) a.u. is the soft-core parameter, and \( \epsilon_0 = 1/4\pi \) a.u. is the electric constant. The laser-electron coupling \( V(t) \) is, in the velocity gauge,
\[
V(t) = -\frac{e}{\mu} [A_{\text{NIR}}(t) + A_{\text{XUV}}(t)] p,
\]
where \( A_{\text{NIR}}(t) \) and \( A_{\text{XUV}}(t) \) are the vector potentials of the NIR and XUV laser pulses, respectively. We used an NIR pulse of wavelength 800 nm, peak intensity \( 5 \times 10^{13} \) W/cm², and duration 1.5 cycles (4 fs, FWHM of intensity profile). The XUV pulse had wavelength 15 nm, peak intensity \( 1 \times 10^{12} \) W/cm², and duration 5.0 cycles (250 as). The peak of the XUV pulse was delayed from that of the NIR pulse by 0.25 NIR cycles, as shown in Fig. 1.

The initial state was chosen as the ground state of \( H_0 \) with energy eigenvalue \( -0.66978 \) a.u., and the wavepacket was propagated from the turn-on of the NIR laser pulse at \( t_{\text{min}} \) to its end at \( t_{\text{max}} \) by the short-iterative Arnoldi algorithm \( 27,28 \) in a 6D Krylov space with a constant time-step of \( \Delta t = 0.0379 \) a.u. We divided the time span from \( t_{\text{min}} \) to \( t_{\text{max}} \) into 8 time segments and changed the active set \( \mathcal{A} \) from one segment to the next. The number of FG points was \( N = 4096 \), and they were distributed over \( -750 \) a.u. \( \leq x \leq 750 \) a.u. and \( -8.58 \) a.u. \( \leq p \leq 8.58 \) a.u. This phase space rectangle was divided...
FIG. 2. Snapshots of \(|c_j(t)|^2\) shown by the ellipses located at the Gaussian centers \(\{(q_j, p_j)\}\). The colors of the ellipses indicate the magnitude of \(|c_j|^2\) according to the scale above the figure. The sequence of dark blue dots represent the simple-man trajectories for direct ionization; the light blue dots represent the rescattered simple-man trajectories. The dark blue + marks represent the simple-man trajectories absorbing one XUV photon in the presence of the NIR field. The snapshots were taken at (a) \(t = -2.06\), (b) \(t = 0.69\), and (c) \(t = 2.06\) in units of NIR cycles. These times are indicated by the green \(\times\) marks in Fig. 1.

FIG. 3. Comparison of the photoelectron momentum distributions obtained with the reduced bvN basis (blue solid line) and full bvN basis (red dashed line). The momentum distribution from a simulation without the XUV pulse (using the full bvN basis) is also shown (gray solid line). The vertical dashed lines indicate the cut-offs of the direct (N1 and N1') and rescattered (N2 and N2') photoelectrons, as well as the NIR-streaked single-XUV-photon ionization peaks (X1 and X1'), estimated by the simple-man model.

In Fig. 2 snapshots of \(|c_j(t)|^2\) are shown by the color scale of the ellipses located at the active Gaussian centers \(\{(q_j, p_j)\}\). The outer rectangular boundary of each panel indicates the phase space area corresponding to the Hilbert space \(\mathcal{H}\) spanned respectively by the Fourier spectral and pseudospectral bases as well as the full pvN and the full bvN bases. The wavepacket, initially concentrated at the atomic core [Fig. 2(a)], is ionized by the NIR and XUV laser pulses and spreads into parts of the first \((x > 0 \text{ and } p > 0)\) and third \((x < 0 \text{ and } p < 0)\) quadrants [Fig. 2(b,c)], but a large area is never accessed. This can be intuitively expected from the classical mechanics, and indeed we see that the wavepacket closely follows the so-called simple-man trajectories (dots and + marks in Fig. 2) which obey the classical Hamiltonian of the same form as eq. (9) with \(H_0\) replaced by \(p^2/2\mu\). In fact, we chose \(\mathcal{A}\) so that the active phase space domain contains these simple-man trajectories (with an additional margin).

In Fig. 3 we compare the photoelectron momentum distributions obtained using the reduced basis of Fig. 2 and the full bvN basis. The excellent agreement between the two results indicates that the present method not only preserves the qualitative features — cut-offs of the direct and rescattered NIR photoelectrons, and the NIR-streaked single-XUV-photon ionization peaks — but also has quantitative accuracy.

The accuracy and the size of the active bvN basis set are expected to be inversely related. However, it is not straightforward to determine the minimal size of the active set that maintains a given accuracy. To seek an upper bound to such an optimal basis size, we carried out simulations with different active sets generated into 64 \times 64 cells of aspect ratio \(\hbar \gamma = 1.14 \times 10^{-2}\) a.u., each of which contained a Gaussian center \((q_j, p_j)\).
by changing the margins around the simple-man trajectories. The error of a simulation was measured by \( \epsilon := |(\langle \Psi_{\text{reduc}} | (t_{\text{max}}) | \Psi_{\text{full}} (t_{\text{max}}) \rangle - 1| \), where |\( \Psi_{\text{reduc}} (t_{\text{max}}) \rangle \) and \( |\Psi_{\text{full}} (t_{\text{max}}) \rangle \) are the final states calculated using a reduced and the full bvN bases, respectively. Figure 4 shows the dependence of this error on the basis set size. As the size \( N_A \) is time-dependent, and as the computational cost of wavepacket propagation depends on \( N_A \) quadratically, we characterized \( N_A \) by its root-mean-square, \( \langle N_A \rangle := \sqrt{\int_{t_{\text{min}}}^{t_{\text{max}}} dt [N_A(t)]^2/(t_{\text{max}} - t_{\text{min}})} \), as well as its minimum and maximum values. It can be seen that the bvN basis can be compressed down to \( \langle N_A \rangle/N = 0.14 \) or possibly further while maintaining the accuracy level at \( \epsilon = 4 \times 10^{-10} \), and at least to \( \langle N_A \rangle/N = 0.08 \) for \( \epsilon = 6 \times 10^{-8} \).

The computational cost of the present method is dominated by the multiplication of the matrix \( G_{jm} := (-i/\hbar) \sum_{l \in A} (\Omega^{-1})_{jl} (\hat{b}_l | H(t) | \hat{b}_m) \) and the vector \( c_m \) \((j, m \in A) \) which scales as \( O(N_A^3) \). There is also initial overhead that scales as \( O(N^3) \) originating from the computation of \( S_{mj} \) and \( (S^{-1})_{jl} \) \((m, j = 1, \ldots, N; \ l \in A) \). Our method can be extended straightforwardly to systems with multiple DOF.21 Defining the number \( M \) of DOF, the total number \( M \) of FG points increases exponentially as \( M = O(N^A) \). In contrast, the number \( M_A \) of active bvN basis states for atomic and molecular systems in a laser field is expected to scale more slowly than \( M \) since the phase space coordinates are generally correlated for such systems.28,29 The cost per time step of the present method goes as \( O(M_A^3) \). The initial overhead in calculating \( S_{mj} \) and \( (S^{-1})_{jl} \) stays at \( O(N^3) \) because the multi-D Gaussians can be factored into 1D Gaussians.22 The dominant part in the overhead is now the calculation of the matrix elements for the potential energy operator in the reduced bvN basis, and this goes as \( O(M A^2) \). For sufficiently large \( d \), the present method has the potential to perform better than the popular alternate-direction Crank-Nicolson scheme31,32 (which costs \( O(M) \) per step) and the FG split-operator method33,34 (which costs \( O(M \log_2 N) \) per step). The bvN basis may also be used for the one-body orbitals in MCTDHF as an alternative to the static scaling of the position coordinates33,34 used previously.10

In summary, we presented a new method to solve the TDSE based on the bvN basis. Although the basis is time-independent, the active subset is chosen in a time-dependent manner. As a first demonstration, we calculated the electronic wavepacket of a 1D atom in the combined fields of intense NIR and attosecond XUV laser pulses. This example demonstrates the high accuracy and efficiency of the method. We are currently working to extend the method to 3D with the aim of ultimately applying it to multi-electron systems in intense and ultrashort laser pulses.

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![FIG. 4. The error \( \epsilon \) as a function of \( \langle N_A \rangle/N \) (black x marks). The horizontal error bars indicate the range of \( \langle N_A \rangle/N \) in \( t_{\text{min}} \leq t \leq t_{\text{max}} \). The data marked by the red filled circle is from the simulation shown in Figs. 2 and 3.](image-url)