Spray Volume, Distribution, and Efficacy of 5-Chloro-3-methyl-4-nitro-1H-pyrazole for Loosening Sweet Orange

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Abstract. The abscission compound CMNP (5-chloro-3-methyl-4-nitro-1H-pyrazole) was applied to fully mature sweet orange trees at different spray volumes using a vertical, multi-fan air-blast sprayer to determine distribution of fruit loosening throughout the canopy and subsequent effects on mechanical harvester efficiency. CMNP was applied at 0, 935, 1871, and 2806 L ha⁻¹ in three ‘Valencia’ and one ‘Hamlin’ grove. Spray coverage was measured using water-sensitive paper and fruit loosening was measured by fruit detachment force (FDF). Spray coverage and FDF were measured at 1-, 2-, and 4-m height within the canopy and inside the canopy near the trunk and on the periphery of the canopy. Spray coverage increased with volume of CMNP applied. Spray coverage was higher at 4 m than 1 and 2 m, which were similar. Spray coverage within the canopy was decreased almost half compared with that of the periphery. FDF was unaffected by spray volume at the different heights except in one trial where fruit had higher FDF at 4 m. Fruit inside the canopy did not loosen as much as fruit outside the canopy in three of the four trials. FDF inside the canopy averaged 52 to 84 N, whereas fruit on the periphery of the canopy averaged 50 to 74 N. CMNP promoted fruit drop, but only in two trials was the amount over 5% of the total yield for the 2806-L ha⁻¹ treatment. The fruit were harvested by canopy shakers that captured fruit on catch frames, except one of the ‘Valencia’ trials in which the canopy shaker did not have a catch frame. The percent of the total crop removed by the harvesters increased when CMNP was applied at higher spray volumes except in the ‘Hamlin’ trial in which there was no difference among volume treatments. The percent of the total crop removed by the harvester but not captured by the catch frame increased at higher volumes of CMNP applied for two of the three trials in which catch frames were used. Fruit loss with greater volume of CMNP applied was promoted by peripheral canopy contact with the front shield of the harvester that knocked fruit down before the catch frame moved under that portion of the canopy. Recovery percentage, or the percentage of total yield that was caught and conveyed to bulk collection by the harvester catch frame, averaged 78.1% to 87.8% of total yield. Higher CMNP volume with increased removal rate compensated for higher catch frame loss, providing overall higher recovery percentage. Based on the goals of minimizing fruit drop and maximizing fruit recovery, the range of FDF that should be reached by harvest is 40 N to 65 N for canopy shakers equipped with catch frames. These trials underscore the importance of adequate CMNP coverage for reducing in-canopy variation of fruit loosening and maximizing fruit removal.
technology, the objective of this study was to determine the relationship of CMNP spray volume applied per hectare to the distribution of spray and fruit loosening in the canopy and percent crop removed by mechanical harvesters. The relationships were determined under the most challenging grove conditions by using fully mature trees with full canopies.

Materials and Methods

2006 trials

Plant material and culture. Two trials were conducted near Immokalee, FL, in commercial groves that used standard cultural practices. The first trial was conducted on 17-year-old, ‘Hamlin’ orange trees [Citrus sinensis (L.) Osbeck] on Swingle citrange roots (Lykes Brothers, Lake Wales, Camp Mack grove). The trees were spaced 3.0 m in height and 4.2 m in diameter. Lower limbs of the canopy were pruned to 1.1 m above the soil line (skirted). The second trial was conducted on 20-year-old ‘Valencia’ orange trees on Swingle rootstock at a commercial grove (Barron Collier, Silverstrand North, block C-13). Trees were spaced 3.6 m × 7.3 m (350 trees/ha) and the canopy averaged 4.4 m in height and 4.2 m in diameter. Lower limbs of the canopy were pruned to 1.1 m above the soil line (skirted). The second trial was conducted on 20-year-old ‘Valencia’ orange trees on Swingle rootstock at a commercial grove (Barron Collier, Silverstrand III, block E-3). Trees were spaced 3.0 m × 6.5 m (500 trees/ha) and the canopy averaged 4.2 m in height and 3.8 m in diameter with the dimensions maintained by annual hedging. The canopy was skirted up to 0.8 m above the soil line.

Treatments. Trees were sprayed with a multihead air-blast sprayer (“GreenTech,” Model 4000L; OXBO International, Clear Lake, WI) with two vertical 5.5-m booms oriented parallel to and arched over the outer part of the canopy in opposing directions. Each boom had six equally spaced fan/nozzle assemblies. Each fan assembly contained eight Conejet #12 nozzles (Spraying Systems Col., Wheaton, IL) operating at 16.2 Mpa cm⁻². CMNP (17% a.i.) was applied at 200 mg L⁻¹ with Kinetic adjuvant (Helena Chemical Co., Memphis, TN) with different volumes per hectare as treatments. The ‘Hamlin’ orange trees were sprayed on 9 Jan. 2006 with 1873 and 2810 L ha⁻¹ and the ‘Valencia’ trees were sprayed on 27 Mar. 2006 with 935, 1871, and 2806 L ha⁻¹. The water volume treatments were achieved by varying ground speed of the tractor at 5.6, 2.5, and 1.6 km h⁻¹, respectively. Each trial had an unsprayed control.

Data collected. Fruit detachment force (DFD) was determined 4 d after CMNP application from 10 randomly selected fruit per canopy position. There were six canopy positions sampled, which varied by height and depth within the canopy. Fruit were sampled at 1-, 2-, and 4-m heights and inner (0.3 m from the trunk) and outer (0.3 m from the canopy edge) the canopy. FDF was measured using a force gauge (Force One digital force gauge; Wagner Instruments, Greenwich, CT) as described previously (Pozo et al., 2004). Immediately before harvesting with the mechanical harvester, fruit beneath each tree were counted and the total weight estimated by using the average weight of 10 fruit. Preharvest dropped fruit weight was divided by total yield of each tree to determine a percent of preharvest fruit drop. Trees were mechanically harvested using a trunk shaker equipped with a catch frame (Coe-Collier Citrus Harvesting, LLP, Immokalee, FL). Each tree was shaken for 5 s at 8 Hz. Fruit mechanically harvested and caught on the catch frame were collected, weighed, and divided by total yield to determine percent removal. Fruit on the ground that had missed the catch frame during machine harvesting were collected, weighed, and divided by total yield to determine percent fruit frame loss. Fruit remaining in the canopy after shaking were removed by hand, weighed, and divided by total yield to determine percent gleaned.

Total yield was determined by adding the weights of the preharvest drop fruit, the fruit caught by the catch frame, the fruit that missed the catch frame, and the fruit gleaned.

Experimental design. Both trials were set up as randomized complete block designs with four blocks and three adjacent trees per plot. There was a buffer row between treatment rows and at least two buffer trees between plots. The data from the three trees were collected and the average per tree estimated before analysis.

2008 trials

Plant material and culture. Two trials were conducted, the first near Lake Wales, FL, and the second near Immokalee, FL, in commercial groves that used standard cultural practices.

The first trial was conducted on 20-year-old ‘Valencia’ orange trees on Swingle rootstock (Lykes Brothers, Lake Wales, Camp Mack grove). The trees were spaced 3.0 m × 6.5 m (500 trees/ha) and the canopy averaged 4.2 m in height and 3.8 m in diameter. The canopy was skirted to 0.8 m above the soil line. The second trial was conducted on 20-year-old ‘Valencia’ orange trees on Carrizo citrange [C. sinensis × Poncirus trifoliata (L.) Raf.] rootstock at a commercial grove (Barron Collier, Oak Hammock Grove block A-1). The trees were spaced 3.0 m × 6.1 m (542 trees/ha) and the canopy averaged 4.0 m in height and 3.1 m in diameter with the dimension maintained by annual hedging. The canopy was skirted to 1.2 m above the soil line.

Treatments. Trees in both trials were sprayed with a vertical, multihead sprayer (Model T1000; OXBO International). The sprayer design was identical to that of the “GreenTech” sprayer described previously. Each fan had HCX #12 nozzles (Spraying Systems Col.) operating at 165 psi. CMNP (17% a.i.) was applied at 250 mg L⁻¹ in the first trial and 300 mg L⁻¹ in the second trial. Both trials used Activator 90 as an adjuvant (Alkylphenol ethoxylate, alcohol ethoxylate, and tall oil fatty acid; Loveland Products, Inc., Greeley, CO). Both trials were sprayed with 935, 1871, and 2806 L ha⁻¹. The first trial was sprayed at 1015 hlx on 10 Apr. and the second trial was sprayed at 1130 hlx on 17 Apr. 2008. The 935-, 1873-, and 2810-L ha⁻¹ treatments
were achieved by varying ground speed of the tractor and pressure of the sprayer at 8.1 km h⁻¹ and 7.0 kg cm⁻², 4.3 km h⁻¹ and 8.8 kg cm⁻², and 2.9 km h⁻¹ and 8.8 kg cm⁻², respectively. Each trial had an unsprayed control.

Data collected. For both trials, FDF was determined 4 d after CMNP application from five randomly selected fruit per canopy position as described previously. Fruit beneath each plot were collected and weighed before mechanical harvest and preharvest drop determined as described in the 2006 procedure. In the first trial, trees were mechanically harvested using a pull-behind canopy shaker without a catch frame (Model 3210; OXBO International). Fruit on the ground were collected and weighed. Preharvest fruit drop, removal, and gleaning percentage were calculated as described in the 2006 procedure. In the second trial, fruit were mechanically harvested by two self-propelled canopy shakers (Model 3220; OXBO International) working on either side of each tree in tandem at 2.4 km h⁻¹ with the canopy shakers operating at 3.7 Hz. Preharvest drop, removal, catch frame loss, recovery, and gleaning percentage were calculated as described in the 2006 procedure.

Total yield was determined using the same method as the 2006 trials.

Spray deposition. In the second trial, and before application of CMNP, water-sensitive paper (product number 20301-2N; Rittenhouse Co., Ontario, Canada) was placed in the canopy at six positions, at 1-, 2-, and 4-m heights and inside (0.3 m from the trunk) and outside (0.3 m from the canopy edge). After spray, the cards were removed from the trees and pooled by plot and a digital image taken using a digital camera (Model S8100FD; Fujifilm Holdings Corp., Tokyo, Japan). The Hunter “b” color value, which measures the relative yellow to blue ratio (McGuire, 1992; Voss and Robinson, 1992), was determined from two randomly selected 60 × 500-pixel areas of the treatment cards. Cards removed from control trees were measured, and the mean “b” value was determined and used to represent 0% coverage using digital analysis software (ImageJ 1.41; Wayne Rasband, National Institutes of Health, Bethesda, MD). The “b” values of five cards completely wetted by the spray treatment and thus showing the highest level of blue color were determined similarly and the mean value used to represent 100% coverage. The average “b” value for each card was determined and the percent coverage was calculated.

Experimental design. Both trials were set up as randomized complete block designs with four blocks. The first trial had three adjacent trees per plot and the second trial had eight trees per plot. There was a buffer row between treatment rows and at least two buffer trees between plots. The data from all trees per plot were collected and the average per tree estimated before analysis.

Statistical analysis. Water-sensitive paper and FDF data were analyzed by finding the mean at each location within the canopy, and testing location effects by including in the model the height by depth interaction and the height and depth main effects, and using the residual sums of squares to test their significance. Yield data were analyzed as randomized complete block designs by using the means from the three-tree replicates as the experimental units. These data were analyzed using the General Linear Models procedures of the Statistical Analysis System (SAS Institute, Cary, NC). Linear regressions for CMNP applied in the Immokalee 2008 study were developed with spray card coverage and FDF using the regression software of SigmaPlot (SigmaPlot 11.0; Systat Software, Inc., San Jose, CA).

Results and Discussion

Distribution of spray and fruit loosening within the canopy. Analysis of color change on wetted paper allowed for estimates of penetration by spray volume. There was no significant height by depth interaction with the percent of wetted paper that was contacted by spray droplets; however, there were significant depth (P < 0.0030) and height (P < 0.0001) effects on spray coverage (Table 1). As expected, there was less coverage inside (25%) than on the periphery (40%) of the canopy. There was also better coverage at the 4-m height in the canopy (51%) than at the 1 m (20%) and 2 m (28%), which were similar. Better spray coverage at the 4-m height is the result of the structure of the sprayer, which has the upper fan at a more horizontal angle than the lower five fans, which are more vertically oriented (Fig. 1). Thus, the upper two fans provide greater overlap in spray coverage. The Hunter “b” color value, which measures the relative yellow to blue ratio (McGuire, 1992; Voss and Robinson, 1992), was determined from two randomly selected 60 × 500-pixel areas of the treatment cards. Cards removed from control trees were measured, and the mean “b” value was determined and used to represent 0% coverage using digital analysis software (ImageJ 1.41; Wayne Rasband, National Institutes of Health, Bethesda, MD). The “b” values of five cards completely wetted by the spray treatment and thus showing the highest level of blue color were determined similarly and the mean value used to represent 100% coverage. The average “b” value for each card was determined and the percent coverage was calculated.

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There was no significant height × depth interaction for FDF in all trials. There was also no significant difference among the different heights within the canopy for three of the four trials. Only the Immokalee 2006 trial for ‘Valencia’ had a significant height effect with the 4-m height fruit having higher FDF than fruit at the 1- and 2-m heights, which were similar. The higher FDF for the Immokalee 2006 trial for ‘Valencia’ occurred despite the greater spray coverage at that height by the sprayer. Fruit near the top of canopies tend to have higher FDF (Kender and Hartmond, 1999), indicating that spray coverage will be especially important in this part of the canopy to optimize loosening by CMNP. Depth was significant for three of four of the trials with the fruit inside having higher FDF, or less loosening, than fruit on the canopy periphery. The lack of a location effect in the Immokalee 2008 trial may relate to the low FDF at the start of the trial and the high rate of CMNP applied (300 mg L⁻¹), which may have minimized differences among locations within the canopy. The average FDF across the three trials where depth within the canopy was significant was 72 N inside the canopy and 62 N on the canopy periphery. Commercial spray recommendations should consider depth effects within the canopy for full-grown trees such as used in these trials. FDF across spray volumes was significant for all trials with higher volumes promoting lower FDF where different.

Relationship between spray coverage and loosening. There were linear relationships between CMNP volume and the percent coverage and FDF (Fig. 2). These results indicate that any adjustment in volume applied per hectare using a vertical, multiple-fan sprayer.
hectare of CMNP will result in a linear response in coverage and fruit loosening.

Yield components by mechanical harvesters. The ultimate goal of CMNP as an aid to mechanical harvesting is to maximize fruit recovery (fruit removed from the tree by the harvester minus fruit missed by the catch frame) while minimizing preharvest fruit drop. The percent preharvest fruit drop was generally higher with increasing volume of CMNP applied for each trial (Table 2). For all ‘Valencia’ trials, however, only the highest volume applied was significantly different from the control. There was a significant effect for all spray volumes applied in the ‘Hamlin’ trial. In general, we consider fruit drop above 2% unacceptable for harvester systems with catch frames. The 1871-L·ha⁻¹ rate was acceptable for all trials except the ‘Hamlin’ 2006 trial in which drop was 6.2%, whereas the 2806-L·ha⁻¹ rate was unacceptable for two of the four trials.

Where different, the percent fruit removal generally increased when CMNP was applied at higher water volumes, except the ‘Hamlin’ trial conducted in 2006. The highest removal rate was increased by 16.9% when CMNP was applied at the two highest application volumes in Lake Wales 2008.

Catch frame loss, where different, was higher when CMNP was applied with higher water rates. The principle cause of fruit loss from catch frames was observed to be the result of impact of fruit by shields in front of the canopy shakers, which are designed to protect the equipment from branches. As a result of the heterogeneity of the canopy structure, especially with branches leaning into the tractor row from heavy crop load, the shields impacted the branches causing fruit to drop before the catch frame moved under the branch. We observed that higher spray volumes caused less fruit swinging and therefore easier detachment by the canopy shaker tines. This effect would be expected to improve fruit recovery by the machines because less fruit would be flung away from the catch frame. Maximum fruit recovery by mechanical harvesters will be aided by canopy architecture that promotes a uniform, relatively vertical canopy along the tractor row. Fruit recovery may also benefit by adjusting tractor and harvester designs with shields more offset to the center of the row and the canopy shakers and catch frames more exposed to the canopy.

Despite higher catch frame loss with CMNP application, the percent recovery was higher with higher spray volumes in two of the three trials in which machines with catch frames were used. These results indicate that CMNP application improves recovery when machines have catch frames. It would be expected that improvements in machine design and groove architecture to minimize catch frame loss may improve recovery.

The ultimate goal of using CMNP to aid mechanical harvesting is to remove sufficient fruit so that hand labor is not needed to remove fruit remaining in the tree. Where

![Fig. 2. Regressions for volume of CMNP applied per hectare on average coverage as measured by water-sensitive paper and fruit detachment force throughout the canopy of ‘Valencia’ from the Immokalee 2008 trial. Both regressions were significant at the P < 0.0001 level. Each data point is the mean for each block within each treatment.](image)

Table 2. Yield components across spray volumes for one ‘Hamlin’ trial and three ‘Valencia’ trials.

| CMNP applied (L·ha⁻¹) | Preharvest drop (%) | Removal (%) | Catch frame loss (%) | Recovery (%) | Glean (%) |
|-----------------------|---------------------|-------------|---------------------|--------------|----------|
| **Hamlin**            |                     |             |                     |              |          |
| Immokalee 2006        |                     |             |                     |              |          |
| 0 1.8 c                | 84.7                | 4.6 b       | 80.1                | 13.4 a       |
| 1871 6.2 b             | 88.9                | 8.2 a       | 80.7                | 4.8 b        |
| 2806 8.0 a             | 88.4                | 8.3 a       | 80.0                | 3.6 b        |
| **Valencia**          |                     |             |                     |              |          |
| Immokalee 2006        |                     |             |                     |              |          |
| 0 0.8 b                | 87.4 b              | 5.8         | 81.6 b              | 12.3 a       |
| 935 1.3 b              | 92.9 a              | 7.0         | 85.8 a              | 6.1 b        |
| 1871 1.6 ab            | 94.2 a              | 7.2         | 87.0 a              | 4.7 b        |
| 2806 2.3 a             | 94.9 a              | 7.1         | 87.8 a              | 3.3 b        |
| **Immokalee 2008**    |                     |             |                     |              |          |
| 0 1.0 b                | 81.3 b              | 3.1 b       | 78.1 b              | 16.1 a       |
| 935 1.0 b              | 83.5 b              | 2.9 b       | 80.7 b              | 14.0 a       |
| 1871 2.1 ab            | 89.5 a              | 2.8 b       | 86.7 a              | 8.0 b        |
| 2806 7.3 a             | 88.0 a              | 6.6 a       | 81.4 ab             | 5.7 b        |
| **Lake Wales 2008**   |                     |             |                     |              |          |
| 0 1.2 b                | 70.6 b              | —           | —                   | 28.2 a       |
| 935 1.1 b              | 82.5 a              | —           | —                   | 16.3 b       |
| 1871 1.7 ab            | 87.2 a              | —           | —                   | 11.1 b       |
| 2806 2.4 a             | 87.5 a              | —           | —                   | 10.1 b       |

*Yield component means are the percent of the total yield.

*Preharvest drop = fruit under the canopy before mechanical harvesting; Removal = fruit removed by the mechanical harvester; Catch frame loss = fruit not captured by the catch frame during mechanical harvesting; Recovery = fruit caught by the catch frame; Glean = fruit left in tree after mechanical harvesting and removed by hand labor.

*Means within columns not followed by the same letter are significantly different at the P < 0.05 level using Duncan’s multiple range procedure. Means without letters indicate no significant difference.

*Not measured; no catch frame used by the harvester in this trial.
different, the percent fruit that had to be gleaned decreased with increased spray volume. A goal of less than 5% of fruit left on the tree should be considered for maximizing mechanical harvesting with CMNP (F. Roka, unpublished data). Varying canopy shaker rates and tractor speed may improve removal and reduce the need for gleaning.

Optimizing CMNP application. More work is needed to understand the relationship between removal and CMNP application at different spray volumes, concentrations, and environmental conditions. In cases in which catch frames are used, minimizing preharvest fruit drop is critically important, because if a significant amount of the crop drops before harvest, ground fruit would have to be collected by hand before machine harvest could begin. For harvesters without catch frames, CMNP could be used at rates that optimize fruit removal because fruit drop and catch frame loss are not important factors to consider. However, the ultimate goal of use of CMNP for mechanical harvesters with catch frames is to maximize recovery, which is accomplished by minimizing fruit drop, promoting fruit removal, and minimizing catch frame loss such that gleaning is not required. Development of commercial recommendations for CMNP for canopy shakers with catch frames will require matching rates of CMNP applied, including concentration and volume applied per hectare, to an array of canopy shaker settings, including shaker head speed (Hz) and tractor speed (km h⁻¹), that control the energy the machines apply to the canopies.

Matching CMNP applications to mechanical harvester settings would be facilitated by finding a range of FDF values that allow maximum recovery by mechanical harvesters. Based on maximum recovery rates and minimizing preharvest fruit drop in these studies, target CMNP-promoted fruit loosening may be 40 to 65 N.

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