On the Ambrosio–Figalli–Trevisan superposition principle
for probability solutions to Fokker–Planck–Kolmogorov equations

Vladimir I. Bogachev\textsuperscript{a1}, Michael Röckner\textsuperscript{b}, Stanislav V. Shaposhnikov\textsuperscript{a}

\textsuperscript{a}Lomonosov Moscow State University, Russia and National Research University Higher School of Economics, Russian Federation
\textsuperscript{b}Fakultät für Mathematik, Universität Bielefeld, D-33501 Bielefeld, Germany

Abstract We prove a generalization of the known result of Trevisan on the Ambrosio–Figalli–Trevisan superposition principle for probability solutions to the Cauchy problem for the Fokker–Planck–Kolmogorov equation, according to which such a solution is generated by a solution to the corresponding martingale problem. The novelty is that in place of the integrability of the diffusion and drift coefficients \( A \) and \( b \) with respect to the solution we require the integrability of \( \| A(t, x) \| + |b(t, x)|/\sqrt{1 + |x|^2} \). Therefore, in the case where there are no a priori global integrability conditions the function \( \| A(t, x) \| + |b(t, x)| \) can be of quadratic growth. Moreover, as a corollary we obtain that under mild conditions on the initial distribution it is sufficient to have the one-sided bound \( \langle b(t, x), x \rangle \leq C + C|x|^2 \log |x| \) along with \( \| A(t, x) \| \leq C + C|x|^2 \log |x| \).

Keywords: Fokker–Planck–Kolmogorov equation, martingale problem, superposition principle

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1. Introduction

We study solutions to the Cauchy problem for the Fokker–Planck–Kolmogorov equation

\[ \partial_t \mu_t = \partial_{x_i} \partial_{x_j} (a^{ij} \mu_t) - \partial_{x_i} (b^i \mu_t), \quad \mu_0 = \nu. \]  

(1.1)

Below we write this equation in the short form \( \partial_t \mu_t = L^* \mu_t \), where \( L^* \) is the formal adjoint operator to the differential operator

\[ Lu = a^{ij} \partial_{x_i} \partial_{x_j} u + b^i \partial_{x_i} u, \]

where the usual convention about summation over repeated indices is employed. We assume throughout that the matrix \( A(t, x) = (a^{ij}(t, x))_{i,j \leq d} \) is symmetric and nonnegative definite and the functions \( (t, x) \mapsto a^{ij}(t, x) \) and \( (t, x) \mapsto b^i(t, x) \) are Borel measurable on \([0, T] \times \mathbb{R}^d\). By a solution we mean a mapping \( \mu_t \) from \([0, T] \) to the space of probability measures \( \mathcal{P}(\mathbb{R}^d) \) that is continuous with respect to the weak topology and satisfies the integral equality

\[ \int_{\mathbb{R}^d} \varphi \, d\mu_t = \int_{\mathbb{R}^d} \varphi \, d\nu + \int_0^t \int_{\mathbb{R}^d} L\varphi \, d\mu_s \, ds \]

for all \( t \in [0, T] \) and all \( \varphi \in C_0^\infty(\mathbb{R}^d) \), where it is assumed that \( a^{ij} \) and \( b^i \) are locally (i.e., on compact sets in \([0, T] \times \mathbb{R}^d\)) integrable with respect to the measure \( \mu_t \, dt \):

\[ a^{ij}, b^i \in L_{1 \text{loc}}(\mu_t \, dt). \]

The measure \( \mu = \mu_t \, dt \) on \([0, T] \times \mathbb{R}^d \) is defined as usual by the equality

\[ \int f \, d\mu = \int_0^T \int_{\mathbb{R}^d} f(t, x) \, \mu_t(dx) \, dt \]

This measure can be identified with the solution, which is also denoted by \( \{\mu_t\} \).

Recall that the weak topology on \( \mathcal{P}(\mathbb{R}^d) \) is generated by the seminorms

\[ \sigma \mapsto \left| \int_{\mathbb{R}^d} f(x) \, \sigma(dx) \right| \]

\textsuperscript{1}Corresponding author.

E-mail addresses: vibogach@mail.ru (V. Bogachev), roeckner@math.uni-bielefeld.de (M. Röckner), starticle@mail.ru (S. Shaposhnikov)
on the linear space of all bounded Borel measures, where \( f \) is a bounded continuous function on \( \mathbb{R}^d \) (see [7]). Recent accounts on the theory of Fokker–Planck–Kolmogorov equations can be found in [11] and [12]. The inner product and norm on \( \mathbb{R}^d \) are denoted by \( \langle x, y \rangle \) and \( |x| \), respectively. The operator norm of a matrix \( A \) is denoted by \( \|A\| \).

In the case \( A = 0 \) (the continuity equation) the following superposition principle of Ambrosio [1] is known (see also [2], [4], and [26]). If \( \mu = \mu_t \, dt \) with probability measures \( \mu_t \) on \( \mathbb{R}^d \) satisfies the continuity equation

\[
\partial_t \mu_t + \text{div}(b \mu_t) = 0
\]

and \(|b(x, t)|/(1 + |x|)\) is \( \mu \)-integrable, then there exists a nonnegative Borel measure \( \eta \) on the space \( \mathbb{R}^d \times C([0, T], \mathbb{R}^d) \) concentrated on the set of pairs \((x, \omega)\) such that \( \omega \) is an absolutely continuous solution of the integral equation

\[
\omega(t) = x + \int_0^t b(\omega(s), s) \, ds
\]

and, for each function \( \varphi \in C_b(\mathbb{R}^d) \) and each \( t \in [0, T] \), one has

\[
\int \varphi(x) \, \mu_t(dx) = \int \varphi(\omega(t)) \eta(dx d\omega).
\]

In other words, the measure \( \mu_t \) coincides with the image of \( \eta \) under the evaluation mapping \((x, \omega) \mapsto \omega(t)\). Of course, the integral on the right coincides with the integral against the projection of \( \eta \) on \( C([0, T], \mathbb{R}^d) \) (see [1, Remark 3.1] about the connection between the two measures). A discussion of analogous representations for signed solutions and interesting counter-examples can be found in [19].

The case of possibly nonzero \( A \) and bounded \( A \) and \( b \) was first considered by Figalli [17], who proved that every probability solution to the Cauchy problem for the Fokker–Planck–Kolmogorov equation is represented by a martingale measure on the path space. Generalizing this seminal achievement, Trevisan [28] obtained the following important and very general result.

Suppose that a mapping \( t \mapsto \mu_t \) from \([0, T]\) to the space of probability measures \( \mathcal{P}(\mathbb{R}^d) \) is continuous with respect to the weak topology and satisfies the Cauchy problem (1.1). Suppose also that it satisfies the condition

\[
\int_0^T \int_{\mathbb{R}^d} \left( \|A(t, x)\| + |b(t, x)| \right) \mu_t(dx) \, dt < \infty. \tag{1.2}
\]

Then there exists a Borel probability measure \( \nu \) on the path space

\[
\Omega := C([0, T], \mathbb{R}^d)
\]

of continuous functions \( \omega: [0, T] \to \mathbb{R}^d \) with its standard sup-norm \( \|\omega\| = \sup_t |\omega(t)| \) such that

(i) \( \nu(\omega: \omega(0) \in B) = \nu(B) \) for all Borel sets \( B \subset \mathbb{R}^d \),

(ii) for every function \( f \in C_0^\infty(\mathbb{R}^d) \), the function

\[
(\omega, t) \mapsto f(\omega(t)) - f(\omega(0)) - \int_0^t Lf(s, \omega(s)) \, ds
\]

is a martingale with respect to the measure \( \nu \) and the natural filtration \( \mathcal{F}_t = \sigma(\omega(s), s \in [0, t]) \).

(iii) for every function \( f \in C_0^\infty(\mathbb{R}^d) \), there holds the equality

\[
\int_{\mathbb{R}^d} f \, d\mu_t = \int_{\Omega_d} f(\omega(t)) \, \nu(d\omega) \quad \forall t \in [0, T].
\]

The latter means that \( \mu_t \) is the law of \( \omega(t) \) under \( \nu \), while (i) means that \( \nu \) is the law of \( \omega(0) \).
Then the hypotheses of the main theorem are fulfilled, hence its conclusion holds.

Corollary 1.2. Suppose that

\[ \int_{\mathbb{R}} |g(x)| \rho(x) \, dx = \int_{\mathbb{R}} |g'(x)| \, dx = \infty. \]

In this paper we reinforce the aforementioned result by replacing condition (1.2) with a weaker assumption.

Throughout we assume that the coefficients are Borel measurable on \([0, T] \times \mathbb{R}^d\),

\[ a^{ij}, b^i \in L^1([0, T] \times U, \mu_t \, dt) \]

for every ball \( U \) in \( \mathbb{R}^d \), and the following condition is fulfilled:

\[ \int_0^T \int_{\mathbb{R}^d} \frac{|A(t, x)| + |\langle b(t, x), x \rangle|}{(1 + |x|)^2} \mu_t(dx) \, dt < \infty. \quad (1.3) \]

It follows from Proposition 2.2 below (see also Example 2.3) that in order to ensure condition (1.3) it suffices that \( \log(1 + |x|) \in L^1(\nu) \) and

\[ |A(t, x)| \leq C + C|x|^2 \log(1 + |x|), \quad \langle b(t, x), x \rangle \leq C + C|x|^2 \log(1 + |x|). \]

Obviously, it is also sufficient without any assumptions about \( \nu \) that

\[ |A(t, x)| + |\langle b(t, x), x \rangle| \leq C + C|x|^2. \]

Our main result is the following theorem (its proof is given in the last section).

**Theorem 1.1.** Suppose that \( \{\mu_t\} \) is a solution to the Cauchy problem \( \partial_t \mu_t = L^* \mu_t \) on \([0, T]\) with \( \mu_0 = \nu \) and (1.3) is fulfilled. Then there exists a Borel probability measure \( \nu_t \) on \( \Omega_t = C([0, T], \mathbb{R}^d) \) for which all assertions (i), (ii) and (iii) are true.

It is important that our theorem assumes no uniqueness of probability solutions to the Cauchy problem, the martingale representation exists for each probability solution satisfying (1.3).

It should be noted that the superposition principle does not work without global assumptions even for smooth coefficients and \( A = I \), because it can happen that there are many probability solutions to the Fokker–Planck–Kolmogorov equation (see [12, Section 9.2], while the martingale problem has a unique solution in this case (see [27, Corollary 10.1.2]) and this solution necessarily corresponds to a subprobability solution to the FPK equation due to a blow up.

Note that the integrability of \((1 + |x|)^{-2}|\langle b(t, x), x \rangle|\) can hold even in the case where the function \((1 + |x|)^{-1}|b(t, x)|\) is not integrable with respect to the solution (see Example 3.2).

Not only is the assumption of integrability of \((1 + |x|)^{-2}|\langle b(t, x), x \rangle|\) weaker than the assumption of integrability of \((1 + |x|)^{-1}|b(t, x)|\), but it is also simpler to verify. For example, as already noted above, if \( \log(1 + |x|) \) is \( \nu \)-integrable, it suffices to have a one-sided bound.

**Corollary 1.2.** Let \( \log(1 + |x|^2) \in L^1(\nu) \) and

\[ |A(t, x)| \leq C + C|x|^2 \log(1 + |x|^2), \quad \langle b(t, x), x \rangle \leq C + C|x|^2 \log(1 + |x|^2). \]

Then the hypotheses of the main theorem are fulfilled, hence its conclusion holds.
For the proof, see Example 2.3. Such a bound allows coercive drift coefficients typical in the theory of diffusion processes and is a simple algebraic condition, a verification of which does not use any information about the unknown solution to the Cauchy problem. Note that if no information about the solution \( \{\mu_t\} \) is given, then our result applies to \( A \) and \( b \) of linear growth, more precisely, the function \( \|A(t,x)\| + |\langle b(t,x), x \rangle| \) can be of quadratic growth. Note also that the superposition principle holds for nonlinear equations (see Remark 3.4).

2. Auxiliary results

For the proof of the main result we need some auxiliary assertions. The next lemma is a simple consequence of the fact that \( \mu_t \) is the law of \( \omega(t) \) under \( P_{\nu} \), but it will be applied repeatedly below.

**Lemma 2.1.** Let \( g \geq 0 \) be a bounded Borel function on \( \Omega_d \) and let \( f \geq 0 \) be a Borel function on \( \mathbb{R}^d \) integrable with respect to the measure \( \mu_t \) for some \( t \in (0,T] \). If \( P_{\nu} \) is a probability measure on \( \Omega_d \) with property (iii) above, then

\[
\int_{\Omega_d} f(\omega(t))g(\omega) \, P_{\nu}(d\omega) \leq \sup_\omega \int_{\mathbb{R}^d} f(x) \mu_t(dx).
\]  

(2.1)

The following proposition not only provides an important a priori estimate in the spirit of classical Lyapunov functions (see [12], where a variety of similar results can be found), but also contains an interesting new result: the integrability of \( |LV| \) with respect to the solution.

**Proposition 2.2.** Suppose that \( \{\mu_t\} \) is a solution of the Cauchy problem \( \partial_t \mu_t = L^* \mu_t \) with \( \mu_0 = \nu \) and there exists a nonnegative function \( V \in C^2(\mathbb{R}^d) \) along with a measurable nonnegative function \( W \) such that \( V \in L^1(\nu) \) and for some numbers \( C \geq 0 \) and \( \tau \in (0,T] \) one has

\[
\lim_{|x| \to +\infty} V(x) = +\infty, \quad LV(t,x) \leq W(t,x) + CV(x), \quad \int_0^\tau \int_{\mathbb{R}^d} W(t,x) \, \mu_t(dx) \, dt < \infty.
\]

Then

\[
\int_{\mathbb{R}^d} V \, d\mu_t \leq \left( \int_{\mathbb{R}^d} V \, d\nu + \int_0^\tau \int_{\mathbb{R}^d} W \, d\mu_s \, ds \right) e^{Ct} \quad \forall t \in [0,\tau],
\]

\[
\int_0^\tau \int_{\mathbb{R}^d} |LV| \, d\mu_t \, dt \leq 2e^{C\tau} \left( \int_0^\tau \int_{\mathbb{R}^d} W \, d\mu_s \, ds + \int_{\mathbb{R}^d} V \, d\nu \right).
\]

**Proof.** Let \( \zeta_N \in C^{1\infty}_b(\mathbb{R}) \) be such that \( \zeta_N(t) = t \) if \( t \leq N - 1 \), \( \zeta_N(t) = N \) if \( t > N + 1 \) and \( 0 \leq \zeta_N' \leq 1 \), \( \zeta_N'' \leq 0 \). In the proof we omit indication of \( \mathbb{R}^d \) in integration over the whole space. Since

\[
L\zeta_N(V) = \zeta_N'(V)LV + \zeta_N''(V)|\sqrt{A}\nabla V|^2 \leq \zeta_N'(V)LV,
\]

there holds the inequality

\[
\int \zeta_N(V) \, d\mu_t \leq \int \zeta_N(V) \, d\nu + \int_0^t \int \zeta_N'(V)LV \, d\mu_s \, ds.
\]

Therefore,

\[
\int \zeta_N(V) \, d\mu_t \leq \int \zeta_N(V) \, d\nu + \int_0^t \int \zeta_N'(V)(W + CV) \, d\mu_s \, ds
\]

and

\[
\int \zeta_N(V) \, d\mu_t \leq \int V \, d\nu + \int_0^\tau \int W \, d\mu_s \, ds + C \int_0^t \int \zeta_N(V) \, d\mu_s \, ds.
\]

The announced bound on the integral of \( V \) against \( \mu_t \) is obtained with the aid of Gronwall’s inequality by passing to the limit as \( N \to \infty \).

Next we write the first inequality in the following form:

\[
\int \zeta_N(V) \, d\mu_t + \int_0^t \int \zeta_N'(V)(LV^-) \, d\mu_s \, ds \leq \int \zeta_N(V) \, d\nu + \int_0^t \int \zeta_N'(V)(LV^+) \, d\mu_s \, ds,
\]
Proposition 2.4. Suppose that
\[ (LV)^+ = \max\{LV, 0\}, \quad (LV)^- = \max\{-LV, 0\} \text{ and } LV = (LV)^+ - (LV)^-. \]

Since \((LV)^+ \leq W + CV\), we have
\[
\int \zeta_N(V) \, d\mu_t + \int_0^t \int \zeta'_N(V)(LV)^- \, d\mu_s \, ds \leq \int \zeta_N(V) \, d\nu + \int_0^t \int W + CV \, d\mu_s \, ds.
\]

On account of the obtained estimate on \(V\) we arrive at the inequality
\[
\int_0^T \int (LV)^- \, d\mu_s \, ds \leq e^{C\tau} \left( \int_0^T \int W \, d\mu_s \, ds + \int V \, d\nu \right),
\]
which yields the announced estimate on the integral of \(|LV| = (LV)^+ + (LV)^-\).

Example 2.3. If \(\log(1 + |x|^2) \in L^1(\nu)\) and
\[
\|A(t, x)\| \leq C + C|x|^2 \log(1 + |x|^2), \quad \langle b(t, x), x \rangle \leq C + C|x|^2 \log(1 + |x|^2),
\]
then for some number \(C_1\) we have
\[
L(\log(1 + |x|^2)) \leq C_1 + C_1 \log(1 + |x|^2), \quad \|A(t, x)\|/(1 + |x|^2) \leq C_1 + C_1 \log(1 + |x|^2),
\]
\[
\|\langle b(t, x), x \rangle/(1 + |x|^2) \leq |L(\log(1 + |x|^2))| + C_1 + C_1 \log(1 + |x|^2).
\]

Hence by Proposition 2.2 the functions \(\log(1 + |x|^2)\) and \(|L(\log(1 + |x|^2)|\) are integrable on \([0, T] \times \mathbb{R}^d\) with respect to \(\mu_t\) and condition (1.3) is fulfilled.

Proposition 2.4. Suppose that \(V \in C^2(\mathbb{R}^d)\) and \(\lim_{|x| \to +\infty} V(x) = +\infty\).

(i) There exists a function \(\theta \in C^2(\mathbb{R})\) such that \(\theta(V) \in L^1(\nu)\) and
\[
\theta \geq 0, \quad \theta(0) = 0, \quad 0 \leq \theta'(t) \leq 1, \quad \theta'' \leq 0, \quad \lim_{t \to +\infty} \theta(t) = +\infty.
\]

(ii) Assume that for some \(\tau \in (0, T]\) one has
\[
\int_0^\tau \int_{\mathbb{R}^d} \left( |A\nabla V|^2 + |LV| \right) \, d\mu_t \, dt < \infty
\]
and that \(\theta\) satisfies all assumptions listed in (i) and \(\theta(V) \in L^1(\nu)\). Then \(\theta(V)\) satisfies the following inequality:
\[
\int_0^\tau \int_{\mathbb{R}^d} \left( |A\nabla \theta(V)|^2 + |L\theta(V)| \right) \, d\mu_t \, dt
\]
\[
\leq 2e^{C\tau} \left( \int \theta(V) \, d\nu + \int_0^\tau \int_{\mathbb{R}^d} \left( |A\nabla V|^2 + |LV| \right) \, d\mu_t \, dt \right).
\]

Proof. In the proof of Proposition 7.18 in [12] it was shown that there is a function \(\theta \in C^2(\mathbb{R})\) such that \(\theta \geq 0, \theta(0) = 0, \theta'(t) \leq 1, \theta'' \leq 0\) and \(\theta(V) \in L^1(\nu)\). Then
\[
|A\nabla \theta(V)|^2 = |\theta'|^2 |A\nabla V|^2 \leq |A\nabla V|^2,
\]
\[
L\theta(V) = \theta''(V)|A\nabla V|^2 + \theta'(V)LV \leq |LV|.
\]
Applying Proposition 2.2 with \(W = |LV|\) and \(C = 0\) we obtain our claim.

The next assertion enables us to estimate the measure of a ball in the path space with the aid of the function \(V\).

Proposition 2.5. Let \(\tau \in (0, T]\). Suppose that \(\{\mu_t\}\) is a solution to the Cauchy problem \(\partial_t \mu_t = L^* \mu_t\) on \([0, \tau]\) with \(\mu_0 = \nu\) and that there exists a Borel probability measure \(P_\nu\) on \(C([0, \tau], \mathbb{R}^d)\) such that (i), (ii) and (iii) are fulfilled. Suppose also that there is a nonnegative function \(V \in C^2(\mathbb{R}^d)\) with \(\lim_{|x| \to \infty} V(x) = +\infty\) such that \(V \in L^1(\nu)\) and
\[
\int_0^\tau \int_{\mathbb{R}^d} \left( |A\nabla V|^2 + |LV| \right) \, d\mu_t \, dt < \infty.
\]

Then for every \(q > 0\) one has
\[
P_\nu \left( \omega : \sup_{t \in [0, \tau]} V(\omega(t)) \geq q \right) \leq \frac{2}{q} \left( \int_{\mathbb{R}^d} V \, d\nu + \int_0^\tau \int_{\mathbb{R}^d} \left( |A\nabla V|^2 + |LV| \right) \, d\mu_s \, ds \right).
Proof. Using the function $\zeta_{\nu}(V)$ in place of $V$ and the assumption about the integrability of the function $LV$ one can verify that
\[
V(\omega(t)) - V(\omega(0)) - \int_0^t LV(s, \omega(s)) \, ds
\]
is a martingale with the quadratic variation
\[
\int_0^t |\sqrt{A}\nabla V(s, \omega(s))|^2 \, ds.
\]
By Doob’s inequality we have
\[
P_\nu\left( \omega: \sup_{t \in [0,\tau]} |V(\omega(t)) - V(\omega(0)) - \int_0^t LV(s, \omega(s)) \, ds| \geq q \right)
\leq \frac{1}{q} \int_0^\tau \int_{\mathbb{R}^d} |\sqrt{A}\nabla V|^2 \, d\mu_s \, ds.
\]
Since
\[
P_\nu\left( \omega: \sup_{t \in [0,\tau]} V(\omega(t)) \geq q \right)
\leq P_\nu\left( \omega: \sup_{t \in [0,\tau]} |V(\omega(t)) - V(\omega(0)) - \int_0^t LV(s, \omega(s)) \, ds| \geq q/2 \right)
+ P_\nu\left( \omega: \sup_{t \in [0,\tau]} V(\omega(0)) + \int_0^t LV(s, \omega(s)) \, ds \geq q/2 \right),
\]
we obtain
\[
P_\nu\left( \omega: \sup_{t \in [0,\tau]} V(\omega(t)) \geq q \right) \leq \frac{2}{q} \left( \int_{\mathbb{R}^d} V \, d\nu + \int_0^\tau \int_{\mathbb{R}^d} \left( |\sqrt{A}\nabla V|^2 + |LV| \right) \, d\mu_s \, ds \right),
\]
which completes the proof.

\[\square\]

3. Proof of the main result

The proof of the theorem follows the scheme used by Figalli [17] and Trevisan [28]. However, there are some differences: Trevisan’s result is not applicable even for smooth coefficients without global integrability of the coefficients. Here we substantionally used some recent results on the uniqueness of probability solutions to Fokker–Planck–Kolmogorov equations from [12] and [24]. When reducing the general case to that of smooth coefficients (as also Figalli and Trevisan did), we encounter two problems: 1) it is necessary to control that the solutions with smoothed coefficients converge to the considered solution, which is not automatic due to the lack of uniqueness, 2) for a priori estimates it is necessary to keep condition (1.3) uniformly. The first problem is overcome by using the smoothing involving not only the space variable, but also the time. The second problem is solved with the aid of the equation itself, namely, we estimate the integral of $\langle \beta(t, x), x \rangle$ for the approximating drift $\beta$ by means of some integral of the diffusion matrix. Note also that before picking a common compact set of measure close to 1 for the corresponding measures on $\Omega_d$ we first pick a common ball of measure close to 1. Finally, we verify that for passing to the limit our local integrability conditions on the coefficients are sufficient.

\textbf{Proof of Theorem 1.1.} First we assume that all our hypotheses hold on some larger interval $[0, T_1], T_1 > T$, and at the last step explain how to obtain a representation on $[0, T]$ without that assumption. Set
\[
V(x) = \log(1 + |x|^2).
\]
Take a function $\theta$ such that $\theta(\log(3 + 2|x|^2)) \in L^1(\nu)$ and all conditions from (i) in Proposition 2.4 are fulfilled. According to Proposition 2.2 there is a number $N_\theta$ such that
\[
\sup_{t \in [0, T_1]} \int \theta(\log(3 + 2|x|^2)) \mu_t(dx) \leq N_\theta.
\]
Note that the coefficients 3 and 2 are only technical things.

**I. Justification of the replacement of \( \mu_t \) by \( \mu_t^\delta = \mu_{t+\delta} \).**

Passing from \( \mu_t \) to \( \mu_{t+\delta} \) enables us to smooth solutions not only with respect to \( x \), but also with respect to \( t \).

Suppose that for every \( \delta \in (0, T_1 - T) \) there exists a measure \( P_\delta \) on \( \Omega_d \) satisfying (i), (ii) and (iii) with the coefficients

\[
A_\delta(t, x) = A(t + \delta, x), \quad b_\delta(t, x) = b(t + \delta, x)
\]

and the corresponding operator

\[
L_\delta f = a^{ij}_\delta \partial_{x_i} \partial_{x_j} u + b^i_\delta \partial_{x_i} u
\]

such that \( \mu_t^\delta = \mu_{t+\delta} \) solves the Cauchy problem with initial condition \( \mu_0^\delta = \mu_0 \). We show that it is possible to extract from \( P_\delta \) a weakly convergent sequence \( P_{\delta_n} \) with \( \delta_n \to 0 \) such that its limit is a solution to the original martingale problem and gives a representation for the original solution \( \mu_t \). We observe that \( \mu_0^\delta \) converges weakly to \( \mu_t \) as \( \delta \to 0 \) for every \( t \) by the continuity of the mapping \( t \mapsto \mu_t \). Omitting again indication of \( \mathbb{R}^d \) when integrating over the whole space, we have

\[
\int \theta(V) \, d\mu_t^\delta \leq \sup_{t \in [0, T_1]} \int \theta(V) \, d\mu_t \leq N_\theta.
\]

Moreover,

\[
\int_0^T \left( |\sqrt{A_\delta} \nabla V|^2 + |L_\delta V| \right) \, d\mu_t^\delta \, dt \leq \int_0^{T_1} \left( |\sqrt{A} \nabla V|^2 + |L \theta(V)| \right) \, d\mu_t \, dt \leq C_1,
\]

where \( C_1 \) does not depend on \( \delta \). By Proposition 2.4

\[
\int_0^T \left( |\sqrt{A_\delta} \nabla \theta(V)|^2 + |L_\delta \theta(V)| \right) \, d\mu_t^\delta \, dt \leq C(T)(N_\theta + C_1).
\]

By Proposition 2.5 applied to the function \( \theta(V) \), for every \( \varepsilon > 0 \), there exists \( R > 0 \) such that for all \( \delta \in (0, T_1 - T) \) we have

\[
P_\delta(\omega : \| \omega \| \leq R) \geq 1 - \varepsilon.
\]

We now need two results from [28]. The first one is Theorem A2. Let \( \Theta : [0, +\infty) \to [0, +\infty) \) be a lower semicontinuous function and let \( \Theta_1, \Theta_2 : [0, +\infty) \to [0, +\infty) \) be convex functions such that \( \Theta_2(2x) \leq C \Theta_2(x) \), \( \Theta_1(0) = \Theta_2(0) = 0 \) and

\[
\lim_{x \to +\infty} \Theta(x) = \lim_{x \to +\infty} \frac{\Theta_1(x)}{x} = \lim_{x \to +\infty} \frac{\Theta_2(x)}{x} = +\infty.
\]

Then there is a compact function \( \Psi : C[0, T] \to [0, +\infty] \), i.e., the sets \( \{ \Psi \leq R \} \) are compact for finite \( R \), such that, whenever \( \{ \alpha_t \}, \{ \beta_t \}, \varphi = \{ \varphi_t \} \) are progressively measurable processes on a filtered probability space \( (\Omega, (\mathcal{F}_t), (P)) \) for which

\[
M_t := \varphi_t - \int_0^t \beta_s \, ds \quad \text{and} \quad M_t^2 - \int_0^t \alpha_s \, ds
\]

are \( P \)-a.s. continuous local martingales and \( \alpha_t \geq 0 \) a.s., one has

\[
\mathbb{E} \Psi(\varphi) \leq \mathbb{E} \left[ \Theta(\varphi_0) + \int_0^T \left( \Theta_1(|\beta_t|) + \Theta_2(\alpha_t) \right) \, dt \right].
\]

Next, according to [28, Corollary A5], if \( \eta \in \mathcal{P}(C[0, T], \mathbb{R}^d) \) is a solution to the martingale problem associated with an elliptic operator \( L \) (not necessarily our operator), then, for every function \( f \in C_{0}^{\infty}(\mathbb{R}^d) \) and the marginal distributions \( \eta_t \) for \( \eta \) it holds

\[
\int \Psi(f) \, d\eta \leq \int \Theta(|f(0, x)| \, d\eta_0(\eta)) + \int_0^T \left[ \Theta_1(|L f|) + \Theta_2(|\sqrt{A} \nabla f|^2) \right] \, d\eta_t \, dt,
\]

where \( \Psi, \Theta, \Theta_1 \) and \( \Theta_2 \) are the same as above and \( \Psi(f(\omega)(\cdot)) = \Psi(f(\omega(\cdot))) \). Note that the right-hand side is finite due to our hypotheses on \( A \) and \( b \) and the compactness of support of \( f \) in \( x \).
Now take $\psi_R \in C_0^\infty(\mathbb{R}^d)$ with $\psi_R(x) = 1$ if $|x| \leq R$, $\psi_R(x) = 0$ if $|x| > 2R$. Let us apply the cited corollary to the function $f_i(x) = x_i \psi_R(x)$ independent of $t$. Denoting by $E_{P_\delta}$ the integral with respect to $P_\delta$, we obtain the estimate

$$E_{P_\delta} \Psi(f_i) \leq \int \Theta(x_i \psi_R(x)) \mu_\delta(dx) + \int_0^T \int \left( \Theta_1(|L_\delta (x_i \psi_R(x))|) + \Theta_2(\sqrt{A_\delta} \nabla(x_i \psi_R(x))^2) \right) \mu_\delta(dx) dt,$$

where for some number $C_2$ independent of $\delta$ the right-hand side is estimated by

$$\sup_x |\Theta(x_i \psi_R(x))| + C_2 \int_0^{T_1} \int_{|x| \leq 2R} \left( \Theta_1(\|A(t,x)\| + |b(t,x)|) + \Theta_2(\|A(t,x)\|) \right) \mu_t(dx) dt,$$

which does not depend on $\delta$. As in [28], we consider the compact function

$$\Psi_d(\omega) = \sum_{i=1}^d \Psi(\omega_i)$$

on $\Omega_d$. We have

$$E_{P_\delta} (I_{\|\omega\| \leq R} \Psi_d) = E_{P_\delta} (I_{\|\omega\| \leq R} \Psi(f_i)) \leq \sum_{i=1}^d E_{P_\delta} (\Psi(f_i)) \leq C_3(R),$$

where $C_3(R)$ depends on $R$, but does not depend on $\delta$. Taking a sufficiently large number $M$ we conclude that for the compact set

$$K = \{ \omega : \Psi_d(\omega) \leq M, \|\omega\| \leq R \}$$

in $\Omega_d$ there holds the estimate

$$P_\delta(K) \geq 1 - 2\varepsilon.$$

Therefore, the family of measures $P_\delta$ contains a sequence $P_{\delta_k}$ with $\delta_k \to 0$ weakly converging to some probability measure $P$. Let us verify that the measure $P$ satisfies (i), (ii) and (iii). The first and last properties are obtained in the limit as $\delta_k \to 0$ in the equality

$$\int_{\Omega_d} f(\omega(t)) P_{\delta_k}(d\omega) = \int f(x) \mu_t + \delta_k(dx) \quad \forall f \in C_0^\infty(\mathbb{R}^d).$$

For the proof of the second (martingale) property we have to show that for every bounded continuous function

$$g : \Omega_d \to \mathbb{R}$$

that is measurable with respect to the $\sigma$-algebra $\mathcal{F}_s$ there holds the equality

$$\int_{\Omega_d} \left[ f(\omega(t)) - f(\omega(s)) - \int_s^t L f(\tau, \omega(\tau)) d\tau \right] g(\omega) P(d\omega) = 0, \quad t \geq s,$$

where $f \in C_0^\infty(\mathbb{R}^d)$. To this end, it suffices to show that

$$\lim_{\delta_k \to 0} \int_{\Omega_d} \left[ \int_s^t L_{\delta_k} f(\tau, \omega(\tau)) d\tau \right] g(\omega) P_\delta(d\omega) = \int_{\Omega_d} \left[ \int_s^t L f(\tau, \omega(\tau)) d\tau \right] g(\omega) P(d\omega),$$

because convergence of the integrals of $[f(\omega(t)) - f(\omega(s))] g(\omega)$ is obvious by the continuity of this function on $\Omega_d$. Let $q^{ij}, z^i \in C^\infty([-1, T_1] \times \mathbb{R}^d)$ and

$$\bar{L} = q^{ij} \partial_{x_i} \partial_{x_j} + z^i \partial_{x_i}$$

and let $\bar{L}_{\delta}$ be the corresponding operator with the time-shifted coefficients $q^{ij}(t + \delta, x)$ and $z^i(t + \delta, x)$.

It is clear from (2.1) that the difference

$$\int_{\Omega_d} \left[ \int_s^t \bar{L}_{\delta} f(\tau, \omega(\tau)) d\tau \right] g(\omega) P_\delta(d\omega) - \int_{\Omega_d} \left[ \int_s^t \bar{L} f(\tau, \omega(\tau)) d\tau \right] g(\omega) P(d\omega)$$

is bounded by $2\varepsilon$. Hence we have

$$\int_{\Omega_d} \left[ \int_s^t \bar{L}_{\delta} f(\tau, \omega(\tau)) d\tau \right] g(\omega) P_\delta(d\omega) \leq \int_{\Omega_d} \left[ \int_s^t \bar{L} f(\tau, \omega(\tau)) d\tau \right] g(\omega) P(d\omega).$$

The validity of (iii) is immediate from (2.1).
tends to zero. Moreover, by Lemma 2.1 the expression
\[
\left| \int_{\Omega_t} \left[ \int_s^t (\tilde{L} - L) f(\tau, \omega(\tau)) \right] g(\omega) \, P(d\omega) \right|
\]
is estimated by
\[
\int_0^T \left( |a^{ij} - q^{ij}| \| \partial_x, \partial_{x_j} f \| + |b^i - z^i| \| \partial_x, f \| \right) d\mu_t \, dt,
\]
which can be made arbitrarily small by a suitable choice of \( q^{ij} \) and \( z^i \) approximating \( a^{ij} \) and \( b^i \) in \( L^1 \) with respect to the measure \( \mu_t \, dt \) on \([0, T_1] \times U\), where \( U \) is a ball containing the support of \( f \). Since the functions \((\tilde{L} - L) f(t, x)\) converge to zero uniformly on \([0, T] \times \mathbb{R}^d\) as \( \delta \to 0 \), the expression
\[
\int_{\Omega_t} \left[ \int_s^t (\tilde{L} - L_\delta) f(\tau, \omega(\tau)) \right] g(\omega) \, P_\delta(d\omega)
\]
tends to zero as \( \delta \to 0 \). Finally, we observe that the expression
\[
\int_{\Omega_t} \left[ \int_s^t (\tilde{L} - L_\delta) f(\tau, \omega(\tau)) \right] g(\omega) \, P_\delta(d\omega)
\]
is estimated by
\[
\int_0^{T_1} \left( |a^{ij} - q^{ij}| \| \partial_x, \partial_{x_j} f \| + |b^i - z^i| \| \partial_x, f \| \right) d\mu_t \, dt,
\]
which can be made arbitrarily small by a suitable choice of \( q^{ij} \) and \( z^i \) as above. Thus, we have verified (i), (ii), (iii) for \( P \). Therefore, for completing the proof of the theorem it suffices to show that for each fixed \( \delta > 0 \) there exists a suitable measure \( P_\delta \) for the solution \( \mu^\delta_t \) to the Cauchy problem \( \partial_t \mu^\delta_t = L^\delta \mu^\delta_t \) with \( \mu^\delta_0 = \mu^\delta \).

II. Smoothing of the coefficients and verification of the conditions with the Lyapunov function.

Let us fix \( \delta \in (0, T_1 - T) \). Let \( \zeta \in C^\infty([0, +\infty)) \), \( 0 \leq \zeta \leq 1 \), \( \zeta' \leq 0 \), \( \zeta(t) = 1 \) if \( t < 1 \) and \( \zeta(t) = 0 \) if \( t > 2 \). Set
\[
\eta(t) = \int_t^{+\infty} \zeta(s) \, ds.
\]
It is clear that \( \eta \geq 0 \), \( \eta(t) = 0 \) if \( t > 2 \) and \( \eta'(t) = -\zeta(t) \). Let \( c_1 \) and \( c_2 \) be numbers such that
\[
c_1 \int_{\mathbb{R}^d} \zeta(|x|^2) \, dx = 1, \quad c_2 \int_{\mathbb{R}} \zeta(|t|^2) \, dt = 1.
\]
For every \( \varepsilon \) with \( 0 < \varepsilon < \min\{\delta/16, 1/2\} \) set
\[
h_\varepsilon(t, x) = c_1 c_2 \varepsilon^{-d-1} \zeta(|t|^2/\varepsilon^2) \zeta(|x|^2/\varepsilon^2).
\]
Let \( \gamma \) be the standard Gaussian density on \( \mathbb{R}^d \). Set
\[
\sigma^\varepsilon(t, x) = \varepsilon \gamma(x) + (1 - \varepsilon) \int \int h_\varepsilon(t - s, x - y) \mu^\delta_s(dy) \, ds,
\]
where the integration is formally taken over all of \( \mathbb{R}^{d+1} \). However, we take into account that the function \( h_\varepsilon(t - s, x - y) \) vanishes if \( s \leq -\delta/2 \) or \( s \geq T + \delta/2 \), so that actually the integration in \( s \) is taken within the limits \( -\delta/2 \) and \( T + \delta/2 \) and for such \( s \) the measures \( \mu^\delta_s \) are defined. It is clear that \( \sigma^\varepsilon > 0 \) and
\[
\int \sigma^\varepsilon(t, x) \, dx = 1.
\]
In addition, for every function \( f \in C^\infty_0(\mathbb{R}^d) \) and every \( t \in [0, T] \) we have
\[
\lim_{\varepsilon \to 0} \int f(x) \sigma^\varepsilon(t, x) \, dx = \int f(x) \mu^\delta_t(dx).
\]
Indeed,
\[
\int f(x)\sigma^\varepsilon(t, x) \, dx = \varepsilon \int f \gamma \, dx + 
(1 - \varepsilon) \int c_2 \varepsilon^{-1} \zeta(|t - s|^2/\varepsilon^2) \int \left(\int f(x) c_1 \varepsilon^{-d} \zeta(|x - y|^2/\varepsilon^2) \, dx\right) \mu_\delta(dy) \, ds.
\]

Since
\[
sup_y \left| \int f(x) c_1 \varepsilon^{-d} \zeta(|x - y|^2/\varepsilon^2) \, dx - f(y) \right| \leq \varepsilon \sup |\nabla f| c_1 \int |x| \zeta(|x|^2) \, dx,
\]
it suffices to show that the limit of the expression
\[
\int c_2 \varepsilon^{-1} \zeta(|t - s|^2/\varepsilon^2) \int f(y) \mu_\delta(dy) \, ds
\]
is equal to the integral of \(f\) against \(\mu_\delta^e\). This follows immediately by the continuity of the function
\[
s \mapsto \int f(y) \mu_\delta(dy).
\]
Thus, for every \(t \in [0, T]\) the measures \(\sigma^\varepsilon(t, x) \, dx\) converge weakly to \(\mu_\delta^e\).

We recall that \(b_\delta(t, x) = b(t + \delta, x)\) and \(A_\delta(t, x) = A(t + \delta, x)\). Set
\[
\beta_\varepsilon^j(t, x) = \frac{1 - \varepsilon}{\sigma^\varepsilon(t, x)} \int b_\delta(s, y) h_\varepsilon(t - s, x - y) \mu_\delta(dy) \, ds,
\]
\[
\alpha_\varepsilon^{ij}(t, x) = \frac{1 - \varepsilon}{\sigma^\varepsilon(t, x)} \int a_\delta^{ij}(s, y) h_\varepsilon(t - s, x - y) \mu_\delta(dy) \, ds.
\]
Recall that \(\gamma\) is the standard Gaussian density on \(\mathbb{R}^d\). We shall deal with the operator
\[
L_\varepsilon u(t, x) = \text{trace}(\alpha_\varepsilon(t, x) D^2 u(x)) + \langle \beta_\varepsilon(t, x), \nabla u(x) \rangle + \frac{\varepsilon \gamma(x)}{\sigma^\varepsilon(t, x)} \left(\Delta u(x) - \langle x, \nabla u(x) \rangle\right),
\]
which should not be confused with the previously defined \(L_\varepsilon\); moreover, \(L_\varepsilon\) depends also on \(\delta\), which is now fixed and is not shown in this notation. Set also
\[
A_\varepsilon = \alpha_\varepsilon + \frac{\varepsilon \gamma(x)}{\sigma^\varepsilon(t, x)} f.
\]
It is readily seen that \(\sigma^\varepsilon\) solves on \([0, T] \times \mathbb{R}^d\) the Cauchy problem
\[
\partial_t \sigma^\varepsilon = L_\varepsilon^* \sigma^\varepsilon, \quad \sigma^\varepsilon(0, x) = \varepsilon \gamma(x) + (1 - \varepsilon) \int \int h_\varepsilon(s, x - y) \mu_\delta(dy) \, ds.
\]
We now investigate the expression \(\langle \beta_\varepsilon(t, x), x \rangle\). We have
\[
\langle \beta_\varepsilon(t, x), x \rangle = \frac{1 - \varepsilon}{\sigma^\varepsilon(t, x)} \int \int \langle b_\delta(s, y), y \rangle h_\varepsilon(t - s, x - y) \mu_\delta(dy) \, ds 
+ \frac{1 - \varepsilon}{\sigma^\varepsilon(t, x)} \int \int \langle b_\delta(s, y), x - y \rangle h_\varepsilon(t - s, x - y) \mu_\delta(dy) \, ds.
\]
Let us consider the expression
\[
\int \int \langle b_\delta(s, y), x - y \rangle h_\varepsilon(t - s, x - y) \mu_\delta(dy) \, ds 
= \int c_2 \varepsilon^{-1} \zeta(|t - s|^2/\varepsilon) \left(\int \langle b_\delta(s, y), x - y \rangle c_1 \varepsilon^{-d} \zeta(|x - y|^2/\varepsilon^2) \mu_\delta(dy) \right) \, ds.
\]
We observe that \(\zeta = -\eta'\) and
\[
\langle b_\delta(s, y), x - y \rangle c_1 \varepsilon^{-d} \zeta(|x - y|^2/\varepsilon^2) = -2^{-1} \varepsilon^{-2} \langle b_\delta(s, y), \nabla x(\varepsilon^{-d} \eta(|x - y|^2/\varepsilon^2)) \rangle.
\]
Therefore,
\[
\int \int \langle b_\delta(s,y), x-y \rangle h_\varepsilon(t-s, x-y) \mu_s^\delta(dy) ds \\
= -2^{-1}c_1c_2\varepsilon^2 \partial_x \left( \int \int b_\delta(s,y) \varepsilon^{-d-1} \zeta(|t-s|^2/\varepsilon^2) \eta(|x-y|^2/\varepsilon^2) \mu_s^\delta(dy) ds \right).
\]

Recall that
\[
\partial_t \mu_t^\delta = \partial_x_i \partial_x_j (a_{ij}^\delta \mu_t^\delta) - \partial_x_i (b_\delta \mu_t^\delta)
\]
on $(-\delta, T + \delta) \times \mathbb{R}^d$ and for every fix $(t, x) \in [0, T] \times \mathbb{R}^d$ the function
\[
\zeta(|t-s|^2/\varepsilon^2) \eta(|x-y|^2/\varepsilon^2)
\]
has compact support in $(-\delta, T + \delta) \times \mathbb{R}^d$. Thus, there holds the equality
\[
- \partial_x_i \left( \int \int b_\delta(s,y) \varepsilon^{-d-1} \zeta(|t-s|^2/\varepsilon^2) \eta(|x-y|^2/\varepsilon^2) \mu_s^\delta(dy) ds \right)
\]
\[
= \partial_t \left( \int \int \varepsilon^{-d-1} \zeta(|t-s|^2/\varepsilon^2) \eta(|x-y|^2/\varepsilon^2) \mu_s^\delta(dy) ds \right)
\]
\[
- \partial_x_i \partial_x_j \left( \int \int a_{ij}^\delta(s,y) \varepsilon^{-d-1} \zeta(|t-s|^2/\varepsilon^2) \eta(|x-y|^2/\varepsilon^2) \mu_s^\delta(dy) ds \right).
\]

We can estimate the terms in the right-hand as follows:
\[
\partial_t \left( \int \int \varepsilon^{-d-1} \zeta(|t-s|^2/\varepsilon^2) \eta(|x-y|^2/\varepsilon^2) \mu_s^\delta(dy) ds \right)
\]
\[
\leq 2\varepsilon^{-d-3} \int \int |t-s| \zeta'(|t-s|^2/\varepsilon^2) |\eta(|x-y|^2/\varepsilon^2)| \mu_s^\delta(dy) ds,
\]
\[
- \partial_x_i \partial_x_j \left( \int \int a_{ij}^\delta(s,y) \varepsilon^{-d-1} \zeta(|t-s|^2/\varepsilon^2) \eta(|x-y|^2/\varepsilon^2) \mu_s^\delta(dy) ds \right)
\]
\[
= 4\varepsilon^{-d-5} \int \int \langle A_\delta(x-y), (x-y) \rangle \zeta(|t-s|^2/\varepsilon^2) \zeta'(|x-y|^2/\varepsilon^2) \mu_s^\delta(dy) ds
\]
\[
+ 2\varepsilon^{-d-3} \int \int (\text{trace } A_\delta) \zeta(|t-s|^2/\varepsilon^2) \zeta(|x-y|^2/\varepsilon^2) \mu_s^\delta(dy) ds
\]
\[
\leq 2\varepsilon^{-d-3} \int \int (\text{trace } A_\delta) \zeta(|t-s|^2/\varepsilon^2) \zeta(|x-y|^2/\varepsilon^2) \mu_s^\delta(dy) ds.
\]

For obtaining the last inequality we have used that $\zeta' \leq 0$ and
\[
\langle A_\delta(x-y), (x-y) \rangle \geq 0.
\]

We observe that whenever $|x-y| \leq 2\varepsilon \leq 1$ one has
\[
\frac{1}{1 + |x|^2} \leq \frac{3}{1 + |y|^2}.
\]

Thus, we have obtained the estimate
\[
\frac{\langle \beta_\varepsilon(t,x), x \rangle}{1 + |x|^2} \leq \frac{3}{\sigma \varepsilon(t,x)} \int \int \frac{|b_\delta, y|}{1 + |y|^2} h_\varepsilon(t-s, x-y) \mu_s^\delta(dy) ds
\]
\[
+ \frac{c_1c_2\varepsilon^{-d-1}}{\sigma^2(t,x)} \int \int |t-s| \zeta'(|t-s|^2/\varepsilon^2) |\eta(|x-y|^2/\varepsilon^2)| \mu_s^\delta(dy) ds
\]
\[
+ \frac{3c_1c_2\varepsilon^{-d-1}}{\sigma^2(t,x)} \int \int \text{trace } A_\delta \zeta(|t-s|^2/\varepsilon^2) \zeta(|x-y|^2/\varepsilon^2) \mu_s^\delta(dy) ds.
\]
Let us denote the right-hand side of this inequality by $W_1(t, x)$ and observe that $W_1 \geq 0$ and
\[
\int_0^T \int W_1(t, x) \sigma^\varepsilon(t, x) \, dx \, dt \leq C_4 \int_{-\delta}^{T+\delta} \int \frac{|\langle b_\delta, y \rangle| + |\text{trace } A_\delta|}{1 + |y|^2} \mu_\delta(dy) \, ds \\
+ c_1 c_2 \int \int |t| \zeta'(t^2) \eta(|x|^2) \, dx \, dt,
\]
where $C_4$ does not depend on $\varepsilon$. The function
\[
\frac{|\alpha^\varepsilon_{ij}(t, x)|}{1 + |x|^2}
\]
is estimated by
\[
W_2(t, x) := \frac{3}{\sigma^\varepsilon(t, x)} \int \int \frac{|a^\delta_{ij}(s, y)|}{1 + |y|^2} h_\varepsilon(t - s, x - y) \mu_\delta(dy) \, ds.
\]
We observe that $W_2 \geq 0$ and
\[
\int_0^T \int W_2(t, x) \sigma^\varepsilon(t, x) \, dx \, dt \leq 3 \int_{-\delta}^{T+\delta} \int \frac{|a^\delta_{ij}(s, y)|}{1 + |y|^2} \mu_\delta(dy) \, ds.
\]
Set
\[
W_3(t, x) = \frac{\varepsilon \gamma(x)}{(1 + |x|^2) \sigma^\varepsilon(t, x)}.
\]
Note that
\[
\int_0^T \int W_3(t, x) \sigma^\varepsilon(t, x) \, dt \, d\mu \leq T \int (1 + |x|^2)^{-1} \gamma(x) \, dx.
\]
Thus, we arrive at the estimates
\[
\mathcal{L}_\varepsilon \log(1 + |x|^2) \leq C_5(W_1 + W_2 + W_3), \quad \left| \sqrt{\mathcal{A}_\varepsilon} \nabla \log(1 + |x|^2) \right|^2 \leq C_5(W_2 + W_3),
\]
where $C_5$ does not depend on $\varepsilon$. Note that for our function $V(x) = \log(1 + |x|^2)$ we have
\[
\mathcal{L}_\varepsilon \theta(V) = \theta''(V) |\sqrt{\mathcal{A}_\varepsilon} \nabla V|^2 \leq C_5(W_1 + W_2 + W_3),
\]
and
\[
|\sqrt{\mathcal{A}_\varepsilon} \nabla \theta(V)|^2 \leq |\sqrt{\mathcal{A}_\varepsilon} \nabla V|^2 \leq C_5(W_2 + W_3).
\]
Moreover,
\[
\int \theta(V(x)) \sigma^\varepsilon(0, x) \, dx \leq \varepsilon \int V(x) \gamma(x) \, dx \\
+ (1 - \varepsilon) \int \int h_\varepsilon(s, x - y)V(x) \mu_\delta(dy) \, dx \, ds.
\]
Note that $\log(1 + |x|^2) \leq \log(1 + 2|x - y|^2 + 2|y|^2) \leq \log(3 + 2|y|^2)$ if $|x - y| \leq 1$. Recall also that
\[
\sup_{t \in [0, T]} \theta(\log(3 + 2|y|^2)) \mu_\delta(dy) \leq N_\theta.
\]
Hence
\[
\int \theta(V(x)) \sigma^\varepsilon(0, x) \, dx \leq \int V(x) \gamma(x) \, dx + N_\theta.
\]
Applying Proposition 2.2 we obtain
\[
\int_0^T \int \left( |\mathcal{L}_\varepsilon \theta(V)| + |\sqrt{\mathcal{A}_\varepsilon} \nabla \theta(V)|^2 \right) \sigma^\varepsilon(t, x) \, dx \, dt \leq C_6,
\]
where $C_6$ does not depend on $\varepsilon$ (recall that $V(x) = \log(1 + |x|^2)$).

**III. The representation of $\sigma^\varepsilon$ by a solution to the martingale problem with $\mathcal{L}_\varepsilon$.**
According to [24, Theorem 3.5] (see also [12, Theorem 9.4.3]), the function \( \sigma^\varepsilon \) is a unique subprobability solution to the Cauchy problem. It is shown in [24] and it is very important in our situation that the integrability condition (3.1) just for one probability solution \( \sigma^\varepsilon \) implies the uniqueness in the class of all sub-probability solutions.

We show that there exists a solution to the martingale problem with the operator \( \mathcal{L}_\varepsilon^N \) and initial condition \( \sigma^\varepsilon(0, x) \, dx \). Let \( \varphi_N(x) = \varphi(x/N), \, 0 \leq \varphi \leq 1, \, \varphi \in C_0^\infty(\mathbb{R}^d) \) and \( \varphi(x) = 1 \) if \( |x| < 1 \). Set

\[
\mathcal{L}_\varepsilon^N = \varphi_N \mathcal{L}_\varepsilon.
\]

According to the Trevisan result (for the case of Dirac’s initial condition, see also [27, Theorem 3.2.6]), there exists a solution \( Q_{\varepsilon}^N \) to the martingale problem associated with \( \mathcal{L}_\varepsilon^N \) and the initial condition \( \sigma^\varepsilon(0, x) \, dx \). Let \( \varphi(t) \, dx \, dt \) be the corresponding probability solution to the Cauchy problem with \( \mathcal{L}_\varepsilon \).

As in the proof of [24, Theorem 2.5] and [12, Theorem 6.7.3], one can choose a subsequence \( \{N_k\} \) such that \( \varphi(t) \, dx \, dt \) converges weakly to \( \varphi(t) \, dx \, dt \) on every compact set in \([0, T] \times \mathbb{R}^d\) and \( \varphi(t) \, dx \, dt \) converges weakly to \( \varphi(t) \, dx \, dt \) on every compact set in \( \mathbb{R}^d \) for each \( t \in [0, T] \). Moreover, \( \varphi(t) \, dx \, dt \) is a sub-probability solution to the Cauchy problem with \( \mathcal{L}_\varepsilon \) and initial condition \( \sigma^\varepsilon(0, x) \, dx \). By the cited uniqueness result for the Cauchy problem we have \( \varphi(t) \, dx \, dt \).

Let us prove that the family of measures \( Q_{\varepsilon}^{N_k} \) is compact in the weak topology. Let \( q > 1 \) and \( \zeta_q(t) = t \) if \( t < q - 1 \) and \( \zeta_q(t) = q \) if \( t > q + 1 \), \( 0 \leq \zeta_q'(t) \leq 1 \), \(-c \leq \zeta''_q \leq 0 \), where \( c \) does not depend on \( q \). Set \( V_1 = \theta(V) \). Note that

\[
Q_{\varepsilon}^{N_k} \left( \omega: \sup_{t \in [0, T]} V_1(\omega(t)) \geq q - 1 \right) = Q_{\varepsilon}^{N_k} \left( \omega: \sup_{t \in [0, T]} \zeta_q(V_1(\omega(t))) \geq q - 1 \right)
\]

Repeating the arguments from Proposition 2.5 with \( \zeta_q(V_1) \) in place of \( V \) and taking into account that \( \zeta''_q(V_1) = \zeta''_q(V_1) = 0 \) if \( V_1 > q + 1 \) we obtain the estimate

\[
Q_{\varepsilon}^{N_k} \left( \omega: \sup_{t \in [0, T]} V_1(\omega(t)) \geq q - 1 \right) \leq \frac{2C_7}{(q - 1)} \int V_1(x) \sigma^\varepsilon(0, x) \, dx + \int_0^T \int_{V_1 \leq q + 1} \left( |\mathcal{L}_\varepsilon V_1| + \sqrt{A_\varepsilon \nabla V_1} \right) \varphi \, dx \, dt.
\]

Since \( \{x: V_1(x) \leq q + 1\} \) is a compact set, for sufficiently large \( N_k \) the last integral is close to

\[
\int_0^T \int_{V_1 \leq q + 1} \left( |\mathcal{L}_\varepsilon V_1| + \sqrt{A_\varepsilon \nabla V_1} \right) \sigma^\varepsilon(t, x) \, dx \, dt.
\]

Thus, for every \( \lambda \in (0, 1) \) one can take \( q \) so large that there exists a number \( k_0 \) such that for every \( k > k_0 \) we have

\[
Q_{\varepsilon}^{N_k} \left( \omega: \sup_{t \in [0, T]} V_1(\omega(t)) \geq q - 1 \right) \leq \lambda.
\]

It follows that for every \( \lambda \in (0, 1) \) there exists \( R > 0 \) such that

\[
Q_{\varepsilon}^{N_k} \left( \omega: \|\omega(t)\| \leq R \right) \geq 1 - \lambda \quad \forall N_k.
\]

Repeating the arguments from the first part of the proof and using the functions \( \Theta_1 \) and \( \Theta_2 \) appearing from Trevisan’s result and de la Vallée Poussin’s theorem for \( \|A(t, x)\|I_{|x| \leq R} \) and \( |b(t, x)I_{|x| \leq R} \), we obtain the estimate

\[
\mathbb{E}_{Q_{\varepsilon}^{N_k}} \psi_d(f_i) \leq C_8 \sup_x |\Theta(x_i \psi_R(x))| + C_9 T \sup_{x,t} \left( \Theta_1(|A_{\varepsilon}(x_i \psi_R(x))|) + \Theta_2(|A_{\varepsilon}(x, t)|) \right)
\]

with the functions \( \Theta(t) = \Theta_1(t) = \Theta_2(t) = t^2 \). Here the right-hand side does not depend on \( N_k \). We have

\[
\mathbb{E}_{Q_{\varepsilon}} (I_{|\omega| \leq R} \psi_d) \leq C_9(R),
\]
where $C_9(R)$ depends on $R$, but does not depend on $\varepsilon$. For any number $\lambda \in (0, 1)$ one can take a sufficiently large number $M$ such that for the compact set $K = \{\omega: \Psi_\delta(\omega) \leq M, \|\omega\| \leq R\}$ there holds the estimate
\[ Q_{\varepsilon}^{N_k}(K) \geq 1 - 2\lambda \quad \forall N_k. \]

Therefore, the family of measures $Q_{\varepsilon}^{N_k}$ contains a sequence $\{Q_{\varepsilon}^{N_k}\}$ weakly converging to some probability measure $Q_{\varepsilon}$. Let us verify that $Q_{\varepsilon}$ corresponds to the solution $\sigma^\varepsilon$. Clearly, conditions (i) and (iii) are fulfilled. Note that if $f \in C^0_0(\mathbb{R}^d)$, then $\varphi_N L_\varepsilon f = L_\varepsilon f$ for all sufficiently large $N$. Hence (ii) follows from weak convergence of $Q_{\varepsilon}^{N_k}$.

Thus, for every $\varepsilon$ there exists a probability measure $Q_{\varepsilon}$ on $\Omega_d$ for which (i), (ii), (iii) are fulfilled with the operator $L_\varepsilon$ and $\sigma^\varepsilon$ solves the Cauchy problem. Moreover, by Proposition 2.5 for every $\lambda \in (0, 1)$ there exists $R > 0$ such that
\[ Q_{\varepsilon}\left(\omega: \|\omega\| \leq R\right) \geq 1 - \lambda \quad \forall \varepsilon > 0. \]

**IV. Verification of the compactness of the family of measures $Q_{\varepsilon}$ and the proof of the fact that the limit is the required measure.**

We need the following version of Jensen’s inequality. Let $\Phi$ be a convex and increasing function on $[0, +\infty)$ with $\Phi(0) = 0$, $\nu$ a subprobability measure on some space $X$, and $f \geq 0$ a measurable function on $X$. Then
\[ \Phi\left(\int_X f \, d\nu\right) \leq \int_X \Phi(f) \, d\nu, \]
which follows by Jensen’s inequality and the inequality $\Phi(\alpha t) \leq \alpha \Phi(t)$ for $\alpha \in [0, 1]$ that follows from the convexity of $\Phi$. Let $\chi_R \geq 0$ be a smooth function such that $\chi_R(x) = 1$ if $|x| \leq 2R$ and $\chi_R(x) = 0$ if $|x| \geq 3R$. Note that
\[ \frac{\varepsilon \gamma(x)}{\sigma^\varepsilon(t, x)} \leq 1. \]
Hence
\[ \Phi\left(|\beta_\varepsilon(x, t)|\chi_R(x) + \frac{\varepsilon \gamma(x)|x|}{\sigma^\varepsilon(t, x)}\chi_R(x)\right) \leq \frac{1}{2}\Phi(2|\beta_\varepsilon(x, t)|\chi_R(x)) + \frac{1}{2}\Phi(6R). \]

Since
\[ \frac{1 - \varepsilon}{\sigma^\varepsilon(t, x)} \int \int h_\varepsilon(t - s, x - y) \mu_\varepsilon^\delta(dy) \, ds \leq 1, \]

one has
\[ \Phi(2|\beta_\varepsilon(x, t)|\chi_R(x)) = \Phi\left(\frac{1 - \varepsilon}{\sigma^\varepsilon(t, x)} \int \int 2|b_\delta(s, y)|\chi_R(x)h_\varepsilon(t - s, x - y) \mu_\varepsilon^\delta(dy) \, ds\right) \leq \frac{1 - \varepsilon}{\sigma^\varepsilon(t, x)} \int \int \Phi(2|b_\delta(s, y)|\chi_R(x))h_\varepsilon(t - s, x - y) \mu_\varepsilon^\delta(dy) \, ds. \]

Therefore, we obtain
\[ 2 \int_0^T \int \Phi\left(|\beta_\varepsilon|\chi_R + \frac{\varepsilon \gamma(x)|x|}{\sigma^\varepsilon(t, x)}\chi_R\right) \sigma^\varepsilon(x, t) \, dx \, dt \leq \int_0^{T_1} \int \Phi(2|b|\chi_R) \, d\mu_t \, dt + T_1\Phi(6R). \]

In the same way we obtain
\[ 2 \int_0^T \int \Phi(\|A_\varepsilon\|\chi_R) \sigma^\varepsilon(x, t) \, dx \, dt \leq \int_0^{T_1} \int \Phi(2\|A\|\chi_R) \, d\mu_t \, dt + \Phi(2). \]

Analogous estimates are fulfilled for
\[ \|A_\varepsilon\| + |\beta_\varepsilon| \leq \frac{\varepsilon \gamma(x)|x|}{\sigma^\varepsilon(t, x)}. \]
Repeating the arguments from the first part of the proof and again using the functions \( \Theta_1 \) and \( \Theta_2 \) appearing from Trevisan’s result and de la Vallée Poussin’s theorem for \( \|A(t,x)\| < R \) and \( |b(t,x)| < R \), we obtain the estimate

\[
\mathbb{E}_{Q_\varepsilon}(\Psi_d(f)) \leq \int \Theta(x;\psi_R(x)) \mu_\delta(dx) + \int \left( \Theta_1(\|L_\varepsilon(x;\psi_R(x))\|) + \Theta_2(\sqrt{L_\varepsilon(x;\psi_R(x))}) \right) \sigma^\varepsilon(x) dx dt,
\]

where \( f_i(x) = x;\psi_R(x) \) and the right-hand side is estimated by

\[
\sup_x |\Theta(x;\psi_R(x))| + \int_0^{T_1} \int_{|x| \leq 2R} \left( \Theta_1(\|A(t,x)\| + |b(t,x)|) + \Theta_2(\|A(t,x)\|) \right) \mu_\delta(dx) dt + \Theta_1(6R) + \Theta_2(2),
\]

which does not depend on \( \varepsilon \). Here we apply the above estimates with \( \Phi = \Theta_1 \) and \( \Phi = \Theta_2 \) for the measure \( Q_\varepsilon \). We have

\[
\mathbb{E}_{Q_\varepsilon}(I_{\|\omega\| \leq R}\Psi_d) \leq C_{11}(R)
\]

where \( C_{11}(R) \) depends on \( R \), but does not depend on \( \varepsilon \). For any number \( \lambda \in (0,1) \) one can take a sufficiently large number \( M \) such that for the compact set \( K = \{ \omega: \Psi_d(\omega) \leq M, \|\omega\| \leq R \} \) there holds the estimate

\[
Q_\varepsilon(K) \geq 1 - 2\lambda \quad \forall \varepsilon > 0.
\]

Therefore, the family of measures \( Q_\varepsilon \) contains a sequence \( \{Q_{\varepsilon_k}\} \) with \( \varepsilon_k \to 0 \) weakly converging to some probability measure \( P_\delta \).

Let us verify that the measure \( P_\delta \) satisfies (i), (ii) and (iii). The first and last properties are obtained in the limit letting \( \varepsilon_k \to 0 \) in the equality

\[
\int_{\Omega_\delta} f(\omega(t)) Q_{\varepsilon_k}(d\omega) = \int f(x) \sigma^{\varepsilon_k}(x,t) dx \quad \forall f \in C_0^\infty(\mathbb{R}^d).
\]

For the proof of (ii) (the martingale property), as above, we have to show that for every bounded continuous function \( g: \Omega_\delta \to \mathbb{R} \) that is measurable with respect to the \( \sigma \)-algebra \( \mathcal{F}_s \) there holds the equality

\[
\int_{\Omega_\delta} \left[ f(\omega(t)) - f(\omega(s)) - \int_s^t L_\delta f(\tau,\omega(\tau)) d\tau \right] g(\omega) P_\delta(d\omega) = 0, \quad t \geq s,
\]

where \( f \in C_0^\infty(\mathbb{R}^d) \). To this end, exactly as at the first step, it suffices to show that

\[
\lim_{\varepsilon_k \to 0} \int_{\Omega_\delta} \left[ \int_s^t L_{\varepsilon_k} f(\tau,\omega(\tau)) d\tau \right] g(\omega) Q_{\varepsilon_k}(d\omega) = \int_{\Omega_\delta} \left[ \int_s^t L_\delta f(\tau,\omega(\tau)) d\tau \right] g(\omega) P_\delta(d\omega).
\]

Let \( q^{ij}, z^j \in C^\infty([-1,T_1] \times \mathbb{R}^d) \) and \( \tilde{L} = q^{ij} \partial_x^i \partial_x^j + z^j \partial_x^i \). It is clear that the difference

\[
\int_{\Omega_\delta} \left[ \int_s^t \tilde{L} f(\tau,\omega(\tau)) d\tau \right] g(\omega) Q_{\varepsilon_k}(d\omega) - \int_{\Omega_\delta} \left[ \int_s^t \tilde{L}_\delta f(\tau,\omega(\tau)) d\tau \right] g(\omega) P_\delta(d\omega)
\]

tends to zero again by Lemma 2.1. Moreover, the expression

\[
\left| \int_{\Omega_\delta} \left[ \int_s^t (\tilde{L} - L_\delta) f(\tau,\omega(\tau)) \right] g(\omega) P_\delta(d\omega) \right|
\]

is estimated by

\[
\int_0^T \int_{\mathbb{R}^d} \left( |a^{ij}_\delta - q^{ij}| \|\partial_x^i \partial_x^j f\| + |b^i_\delta - z^i| \|\partial_x^i f\| \right) d\mu_\delta dt,
\]
which can be made arbitrarily small by a suitable choice of \( q^{ij} \) and \( z^i \) approximating \( a^{ij}_\delta \) and \( b^i_\delta \) in \( L^1 \) with respect to the measure \( \mu^\delta_t \) on \([0, T_1] \times U\), where \( U \) is a ball containing the support of \( f \). Set

\[
\begin{align*}
\lambda^i_\varepsilon(t, x) &= \frac{1 - \varepsilon}{\sigma^\varepsilon(t, x)} \int \int z^i(s, y) h^\varepsilon(t - s, x - y) \mu^\delta_s(dy) ds, \\
q^{ij}_\varepsilon(t, x) &= \frac{1 - \varepsilon}{\sigma^\varepsilon(t, x)} \int \int q^{ij}(s, y) h^\varepsilon(t - s, x - y) \mu^\delta_s(dy) ds,
\end{align*}
\]

\( \tilde{L}_\varepsilon = q^{ij}_\varepsilon \partial_{x^i} \partial_{x^j} + z^i \partial_{x^i} \).

Note that \( \lambda^i_\varepsilon - \lambda^i \) and \( q^{ij}_\varepsilon - q^{ij} \) converge to zero uniformly on \([0, T_1] \times U\) for every ball \( U \). Since the functions \((\tilde{L} - \tilde{L}_\varepsilon) f(t, x)\) converge to zero uniformly on \([0, T] \times \mathbb{R}^d\) as \( \varepsilon_k \to 0 \), the expression

\[
\int_{\Omega_d} \left[ \int_{s}^{t} (\tilde{L} - \tilde{L}_\varepsilon) f(\tau, \omega(\tau)) d\tau \right] g(\omega) Q_{\varepsilon_k}(d\omega)
\]

tends to zero as \( \varepsilon_k \to 0 \). Let

\[
C(f) = d \sup_x |\nabla f(x)| + d \sup_x \|D^2 f(x)\|.
\]

and \( f(x) = 0 \) if \( |x| > r \). Note that

\[
|\tilde{L}_\varepsilon - L_{\varepsilon_k} f(t, x)| \leq \frac{1 - \varepsilon_k}{\sigma^\varepsilon_k(t, x)} \int \int [a^{ij}_\delta(s, y) - q^{ij}(s, y)] \cdot \partial_{x^i} \partial_{x^j} f(x) |\sigma^\varepsilon_k(x)|
\]
\[
+ |b^i_\delta(s, y) - z^i(s, y)||\partial_{x^i} f(x)| h^\varepsilon_k(t - s, x - y) \mu^\delta_s(dy) ds
\]
\[
+ \frac{\varepsilon_k \gamma}{\sigma_k} (|\Delta f| + |x||\nabla f|)
\]
\[
\leq C(f) \frac{1 - \varepsilon_k}{\sigma^\varepsilon_k(t, x)} \int \int_{|y| \leq r + 1} [a^{ij}_\delta(s, y) - q^{ij}(s, y)] + |b^i_\delta(s, y) - z^i(s, y)|
\]
\[
\times h^\varepsilon_k(t - s, x - y) \mu^\delta_s(dy) dx + \varepsilon_k C(f) \frac{(1 + |x|) \gamma(x)}{\sigma^\varepsilon_k}.
\]

Therefore, the integral

\[
\int_{\Omega_d} \left[ \int_{s}^{t} (\tilde{L}_\varepsilon - L_{\varepsilon_k}) f(\tau, \omega(\tau)) d\tau \right] g(\omega) Q_{\varepsilon_k}(d\omega)
\]

is estimated by

\[
C(f) \int_0^T \int_{|x| \leq r + 1} (|a^{ij}_\delta - q^{ij}| + |b^i_\delta - z^i|) d\mu^\delta_t dt + \varepsilon_k C(f) \int (1 + |x|) \gamma(x) dx,
\]

which can be made arbitrarily small by a suitable choice of \( q^{ij} \) and \( z^i \) as above. Denoting by \( I(L, P) \) the integral

\[
\int_{\Omega_d} \left[ \int_{s}^{t} L f(\tau, \omega(\tau)) d\tau \right] g(\omega) P(d\omega),
\]

we have

\[
I(L_{\varepsilon_k}, P_{\varepsilon_k}) - I(L_{\delta}, P_{\delta}) = (I(L_{\varepsilon_k}, P_{\varepsilon_k}) - I(L_{\delta}, P_{\varepsilon_k})) + (I(L_{\delta}, P_{\varepsilon_k}) - I(L_{\delta}, P_{\delta}))
\]
\[
+ (I(L_{\varepsilon_k}, P_{\varepsilon_k}) - I(L_{\delta}, P_{\delta})) + (I(L_{\delta}, P_{\delta}) - I(L_{\delta}, P_{\delta})).
\]

Let \( \lambda > 0 \). First we take \( q^{ij} \) and \( z^i \) such that for the first and forth terms in the right-hand side the integrals with \( \mu^\delta_t \) in the corresponding bounding expressions (3.2) are smaller than \( \lambda \). Next we take \( k \) such that the part with \( \varepsilon_k \) in (3.2) for the first term and also the second and third terms are smaller than \( \lambda \). It follows that \( I(L_{\varepsilon_k}, P_{\varepsilon_k}) - I(L_{\delta}, P_{\delta}) \to 0 \). Thus, we have verified (i), (ii), (iii) for \( P_{\delta} \).

V. Extension to the whole interval.
We have constructed martingale representations $P_n$ defined on $C([0, T - 1/n], \mathbb{R}^d)$ for every smaller interval $[0, T - 1/n]$. It now remains to observe that Trevisan’s a priori estimate employed above (that is, [28, Theorem A2 and Corollary A5]) enables one to construct a representation on the whole interval $[0, T]$ on which we have a solution to the Fokker–Planck–Kolmogorov equation. To this end we extend the measures $P_n$ to $C([0, T], \mathbb{R}^d)$ by using the natural extension operator that associates to every function $\omega$ on $[0, T - 1/n]$ the function that extends it by the constant value $\omega(T - 1/n)$ on $(T - 1/n, T]$. In addition, the compact function $\Psi_d$ on $C([0, T - 1/n], \mathbb{R}^d)$ ensured by Trevisan’s result for each $P_n$ (used at Step I) can be chosen in a unified way, namely, by taking such a function on $C([0, T], \mathbb{R}^d)$ and then restricting it to $C([0, T - 1/n], \mathbb{R}^d)$ embedded into $C([0, T], \mathbb{R}^d)$ by means of extensions as explained above. It is readily seen from the formulation of the cited results from [28] mentioned above that in this way we obtain a compact function on $\Omega_d$ the integrals of which with respect to the extensions of $P_n$ to $\Omega_d$ remain uniformly bounded (here it is important, of course, that in our condition (1.3) the integral is taken over all of $[0, T]$). Hence the sequence of extensions of measures $P_n$ contains a weakly convergent subsequence. The limit of this subsequence gives the desired representation. The verification of this is analogous to the previous steps. Of course, the main point is to check the martingale property, which is not automatic in case of discontinuous $A$ and $b$, but follows again my smooth approximations and estimate (2.1).

The main difficulty with the smoothing of coefficients is due to the necessity to obtain in the limit the solution we consider (but not an arbitrary solution, since there can exist many), in addition, for the approximating solutions we have to keep our Lyapunov-type condition.

**Remark 3.1.** If the Cauchy problem has a solution on the whole half-line, then a similar reasoning gives a representing martingale measure on the space of paths on $[0, +\infty)$, but here one must be careful, since this space is not separable, so the desired measure is defined not on all Borel sets, but on some smaller $\sigma$-field.

Finally, we give an example showing that the integrability of $(1 + |x|)^{-2}|\langle b(t, x), x \rangle|$ can hold even in the case where the function $(1 + |x|)^{-1}|\langle b(t, x) \rangle|$ is not integrable with respect to the solution.

**Example 3.2.** Let $d = 2$ and let $(r, \varphi)$ be polar coordinates. We construct an example of a stationary solution $\mu = \varrho \, dx$ to the equation with the unit matrix $A$ and the drift coefficient $b = \nabla \varrho / \varrho$ for a suitable function $\varrho$. We recall that

$$|
abla \varrho(x)|^2 = r^{-2} |\partial_r \varrho|^2 + |\partial_\varphi \varrho|^2.$$  

Therefore, it suffices to find a smooth nonnegative function $\varrho$ for which

$$\varrho, (1 + r)^{-1} |\partial_r \varrho| \in L^1(\mathbb{R}^2), \quad (1 + r)^{-2} |\partial_\varphi \varrho| \notin L^1(\mathbb{R}^2).$$

Set

$$\varrho(r, \varphi) = \sum_{n=1}^{\infty} 2^{-n} \psi(r - n)(2 + \sin(4^n \varphi)),$$

where $\psi \in C_0(\mathbb{R})(0, 1)$ and $\psi \geq 0$ is not identically zero. We observe that for every point $(r, \varphi) \in (0, +\infty) \times [0, 2\pi]$ only one term of the series is nonzero. It is clear that $\varrho \in C^\infty(\mathbb{R}^2)$, $\varrho \geq 0$ and

$$\varrho(r, \varphi) + |\partial_r \varrho(r, \varphi)| \leq C 2^{-r}$$

for some number $C > 0$. However,

$$|\partial_\varphi \varrho(r, \varphi)| = \sum_{n=1}^{\infty} 2^n \psi(r - n) |\cos(4^n \varphi)|.$$

Since the integral of $|\cos(4^n \varphi)|$ is estimated from below by $2\pi$, we have

$$\int_0^{2\pi} \int_0^1 r^{-1} |\partial_r \varrho| \, d\varphi \, dr \geq \sum_{n=1}^{\infty} 2\pi c_n (n + 1)^{-1} 2^n = +\infty, \quad c_n = \int_0^1 |\psi(s)| \, ds.$$
Thus, $r^{-2} |\partial_2 g| \notin L^1(\mathbb{R}^2)$. In this example $b$ is a gradient. An example without this additional property is even simpler. We observe that the standard Gaussian density $\gamma$ is a stationary solution to the equation with $A = I$ and $b(x) = -x$, so it remains a solution for the equation with a perturbed drift $-x + v(x)$, where a smooth vector field $v$ is chosen such that $\text{div}(\gamma v) = 0$ and $(v, v(x)) = 0$. For example, we can take $v$ of the form $v(x) = \gamma(x)^{-1} h(|x|^2) U x$ with an orthogonal operator $U$ such that $(U x, x) = 0$. Of course, $h$ can be rapidly increasing, so that $|v|\gamma$ will not be integrable.

Remark 3.3. The presented results can be extended with minor technical changes to as follows. Let $V \in C^2([1, +\infty)$, there is $C > 0$ such that

$$\left| \frac{V''(s)}{V''(t)} \right| + \left| \frac{V'(s)}{V'(t)} \right| \leq C \quad \text{whenever} \ |t - s| \leq 1,$$

$V \geq 0$, $|V''| + |V'| \leq C$ and $\lim_{s \to +\infty} V(s) = +\infty$, i.e., the integral of $V'$ diverges. Then condition (1.3) can be replaced by

$$\int_0^T \int_{\mathbb{R}^d} \left[ (|V''(1 + |x|^2)| (1 + |x|^2) + |V'(1 + |x|^2)|) \right] |A(t,x)| \mu_t(dx) dt < \infty.$$

For $V(s) = \log s$ we obtain the original condition (1.3). If $V(s) = \log(1 + \log s)$, then we arrive at the condition

$$\frac{|A(t,x)|}{(1 + |x|^2) \log(1 + |x|^2)}, \quad \frac{|b(t,x), x|}{(1 + |x|^2) \log(1 + |x|^2)} \in L^1(\mu_t dt).$$

Remark 3.4. The superposition principle applies not only to linear Fokker–Planck–Kolmogorov equations, but also to nonlinear equations. Let $\{\mu_t\}$ be a solution to the Cauchy problem

$$\partial_t \mu_t = \partial_{x^j} (a^{ij}(t, x, \mu) \mu_t) - \partial_{x^j} (b^{i}(t, x, \mu) \mu_t), \quad \mu_0 = \nu.$$

For a precise definition of a solution and typical examples of dependence of $A$ and $b$ on the solution $\mu$ are given in [12, Chapter 6], [22], [23]. In particular, typical global assumptions are expressed in terms of a Lyapunov function $V$:

$$L_\nu V \leq C(\mu) + C(\mu) V, \quad V \in L^1(\nu).$$

If $V(x) = \log(1 + |x|^2)$, then by Proposition 2.2 the solution $\{\mu_t\}$ satisfies condition (1.3). Given a solution $\{\mu_t\}$, we can regard it as a solution to the linear operator $L_\mu$. Therefore, there exists the corresponding solution $P_\nu$ to the martingale problem such that $\mu_t$ is the one-dimensional distribution of the measure $P_\nu$ on $C([0, T], R^d)$. Hence we can assume that the measure $P_\nu$ solves the martingale problem with the operator $L_\mu$ that depends on $P_\nu$ through $\mu$, i.e., solves the martingale problem corresponding to the stochastic McKean–Vlasov equation (see [18]). Thus, using the superposition principle and solutions to the Fokker–Planck–Kolmogorov equation one can construct solutions to the martingale problem for nonlinear stochastic equations. This approach is applied for constructing probabilistic representations of solutions to PDEs (see, e.g., [6]).

It is worth noting that the superposition principle can be useful for the study of uniqueness problems for Fokker–Planck–Kolmogorov equations with coefficients of low regularity, on this topic see the book [12] and the papers [13], [14], [15], [16], [20], [25], [29]. We also plan to study analogous questions for infinite-dimensional equations in the spirit of [8], [9] and [10].

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