Subsurface contrast due to friction in heterodyne force microscopy

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Abstract
The nondestructive imaging of subsurface structures on the nanometer scale has been a long-standing desire in both science and industry. A few impressive images were published so far that demonstrate the general feasibility by combining ultrasound with an atomic force microscope. From different excitation schemes, heterodyne force microscopy seems to be the most promising candidate delivering the highest contrast and resolution. However, the physical contrast mechanism is unknown, thereby preventing any quantitative analysis of samples. Here we show that friction at material boundaries within the sample is responsible for the contrast formation. This result is obtained by performing a full quantitative analysis, in which we compare our experimentally observed contrasts with simulations and calculations. Surprisingly, we can rule out all other generally believed responsible mechanisms, like Rayleigh scattering, sample (viscoelasticity, damping of the ultrasonic tip motion, and ultrasound attenuation. Our analytical description paves the way for quantitative subsurface-AFM imaging.

Keywords: heterodyne force microscopy, contrast mechanism, subsurface, friction, ultrasound, atomic force microscopy, excitation scheme

(Some figures may appear in colour only in the online journal)

1. Introduction

Many fields of research are in need of a nondestructive way of imaging nanometer-sized subsurface features. To this end, ultrasound was combined with atomic force microscopy (AFM) to invent ultrasound force microscopy (UFM) in 1993 [1] and Waveguide-UFM in 1996 [2]. The combination of these two techniques led to the development of heterodyne force microscopy (HFM) in 2000 [3, 4]. HFM makes use of two ultrasound waves at slightly different frequencies, one of which is sent through the sample and the other through the cantilever. The mixed, heterodyne signal (amplitude and phase) at their frequency difference contains possible subsurface information at an experimentally accessible frequency [5]. Regarding subsurface imaging, HFM is considered to be the technique that delivers the highest sensitivity, the best resolution, and the least damage to the sample/surface: the smaller the amplitudes are of the ultrasonic vibrations, the higher is the contrast [6]. Therefore, HFM measurements penetrate the sample at most a few nanometer, while comparable UFM measurements typically need ultrasonic amplitudes that are large enough to generate a tip induced stress field that extends down to the depth of the buried structures. This is because UFM relies on feeling through the sample [1, 7, 8], while HFM picks up the soundwave that traveled through the sample, like a radio [9]. Note that there exists a unique report, in which UFM is applied even at GHz
frequencies: the observed contrast relies on diffraction [10]. Using HFM, we will show here that it is possible to observe 20 nm large Au nanoparticles below 82 nm of polymer, although we use an (combined) ultrasonic vibration amplitude of only 1.71 nm and indent at maximum 6 nm into the sample.

Using HFM, subsurface images with remarkable contrast and resolution have been reported [3, 11–22], like the detection of 17.5 nm large gold nanoparticles buried at a depth of 500 nm in a polymer [14]. Surprisingly, the generated contrast clearly exceeds the background variations in these images, although the size of the nanoparticles is only a fraction of the sample thickness, and the lateral fingerprint on the surface (resolution) is equal to the diameter of the nanoparticles. Both observations are hard to understand, if one considers the wavelengths of the ultrasonic excitations, which is in the order of mm’s and therefore much larger than both the size of the nanoparticles (nm’s) and their depth below the surface (up to μm’s). Unfortunately, none of the published HFM experiments provide quantitative information on the measured amplitude and phase range, on the applied contact force during the measurement, and on the precise excitation scheme in combination with the resonance frequencies of the cantilever.

To pave the way for quantitative subsurface measurements, it is of crucial importance to understand the physical contrast formation mechanism [23]. This requires a detailed, quantitative understanding of the ultrasound propagation within the sample [24], the cantilever dynamics [6, 7, 25–27], nonlinear mixing [9, 28, 29], the explicit excitation scheme, the resonance frequency spectrum of the cantilever [2, 30, 31], resonance frequency shifting [31], and the response to variations in the tip–sample interaction [31–34] that are determined by the local elasticity and adhesion of the sample. All these factors can significantly change the heterodyne signal leading to a measurable contrast. Published HFM experiments that provide (at least some) quantitative information are scarce [15] and the actual depth of the subsurface features is confirmed independently only in [13].

In this paper, we present a full quantitative analysis that addresses all physical contrast mechanisms we can imagine to explain our experimental observations on a well characterized sample. This quantitative analysis is the first of its kind and has become only possible, due to series of our earlier work, in which we focused on the generation of the signal at the difference frequency in HFM: first we showed that the ultrasound amplitude of the cantilever does not decrease when indenting into the sample [6, 25], which means the cantilever works only as a pickup. Based on this, we derived full analytical equations that describe the generation of the heterodyne signal at the difference frequency, which we confirmed both experimentally and via simulations [9, 25]. To derive hard numbers from our model, one only needs to know the applied ultrasound waves, which are set by the user, and the tip–sample interaction, which can be measured experimentally. Note that the exact (theoretical) tip–sample model is not important as long as it quantitatively matches the experimentally measured interaction [9]. Equipped with this insight, we show that Rayleigh scattering [24] would produce a contrast that is orders of magnitude smaller than in the experiment. By calculating the cantilever dynamics for different tip–sample interactions, we show that variations in sample elasticity indeed can lead to contrasts that are, in magnitude, comparable to the experiments. However, we can also rule out this mechanism, as the contrast is inverted with respect to the experimentally observed one. The only remaining possibility is dissipation! As we can also exclude tip damping and ultrasound attenuation, we finally conclude that friction at shaking nanoparticles is the responsible physical contrast mechanism. Additional evidence for this comes from an estimate of the involved energy dissipation.

Our analysis shows that the contrast strongly depends on the applied contact force and the precise ultrasonic excitation scheme with respect to the resonance frequencies (and their shifts) of the cantilever.

2. Methods

All measurements described in this paper are performed with a Digital Instruments (Nanoscope 3) AFM that we equipped with a homebuilt cantilever holder as well as ultrasonic sample transducer [4].

As a quantitative analysis of the contrast mechanism is impossible without a well-characterized sample, we carefully prepared a stack consisting of the following layers (from bottom to top, see figure 1): a Si wafer with native oxide, a ~97 nm thick PMMA layer, a 30 nm thick PVA layer with embedded gold nanoparticles (diameter 20 nm), and a 82 nm thick PVA top layer. The density of the gold nanoparticles was determined via AFM and SEM to be 0.7 ± 0.6 particles μm⁻². The precise sample preparation as well as its detailed characterization, in which we even determined the depth of the Au nanoparticles with an independent measurement based on Rutherford backscattering, is described in detail in supplementary note 1 and 2.

In our HFM experiment, we chose the ultrasonic excitation frequencies of both the tip and the sample as well as the difference frequency off resonance, i.e. not on (or within the width) of a resonance peak of the cantilever, see figure 2. We call this excitation scheme off–off resonance. The first on/off indication describes whether \( f_{\text{diff}} \) (heterodyne signal) is tuned to a resonance frequency of the cantilever, whereas the second on/off indication describes whether \( f_t \) (ultrasonic tip excitation) is tuned to a resonance. This leads to four different excitation schemes, of which we evaluate also the off–on scheme in more detail in supplementary note 8.
3. Results

To enable a quantitative analysis of our measurements, we carefully prepared a sample with 20 nm large gold nanoparticles embedded 82 nm below the surface, see figure 1. The preparation as well as the independently determined characterization of the sample with AFM, Rutherford backscattering spectroscopy (RBS), and scanning electron microscopy (SEM) is described in supplementary notes 1 and 2.

As the explicit excitation scheme is of crucial importance for the measured HFM contrast, figure 2 shows our particular experimental choice, called experimental scheme, with an off-off resonance excitation scheme (see methods for the definition of schemes).

We calibrated the spring constant to be 2.7 N m\(^{-1}\) using the thermal noise method [35]. Then, we determined the spring constants of the higher modes by matching the observed resonance frequencies to the ones found in the numerical calculation [31]. By extracting the slope of the analytical mode shape at the free end of the cantilever and comparing it to the one of the fundamental mode, we quantified the vibration amplitude of the cantilever at the ultrasonic excitation frequency to be \(A_t = 1.34\) nm. Finally, we used the measured tip–sample interaction together with the simultaneously measured amplitude at the difference frequency \(A_{\text{diff}}\) to determine the ultrasonic vibration amplitude of the sample: \(A_s = 0.37\) nm. This method is described in detail in [9, 25].

Figure 3 shows the actual HFM experiment with simultaneously measured height (a)–(d), amplitude \(A_{\text{diff}}\) (e)–(h) and phase \(\phi_{\text{diff}}\) (i)–(l) of the difference frequency \(f_{\text{diff}}\) for various contact forces \(F_c\). Feedback was performed in contact mode operation. The contact force \(F_c\) is decreased from top to bottom: 163, 115, 67, and 2.4 nN. The gold nanoparticles are visible in the height, \(A_{\text{diff}}\), and the phase at \(F_c = 163\) nN. The observed density of 1.2 particles \(\mu\text{m}^{-2}\) fits the independently determined density (see supplementary note 1). Most of the gold nanoparticles are still visible at \(F_c = 115\) nN, although the contrasts are significantly reduced. At lower forces, we do not (or just barely) detect any nanoparticles, which supports the RBS measurements that the gold nanoparticles are indeed fully buried under a 82 nm thick PVA layer. Considering the tip indentation depths of less than 6.5 nm (note that this is different from the total height variation, see left side in figure 3) in combination with the total ultrasonic vibration amplitude of the sample and the tip of \(A_s + A_t = 1.71\) nm, it is striking that we see the nanoparticles in the height images: the total ultrasonic vibration amplitude is at least ten times smaller than the depth of the nanoparticles\(^3\) (82 nm).

\(^3\) We only see the nanoparticles also in the height, if we have both ultrasound signal switched on. This surprising effect is subject to an own publication that we are currently preparing.
comparison, subsurface contrast in UFM or waveguide-UFM is only obtained, if the tip induced stress field generated by the sound wave extends all the way down to the depth of the subsurface features. In [8] they need an ultrasonic amplitude of 27 nm to see the buried particles at a depth of 34 nm, while our amplitude is only 1.71 nm and we still see the particles even at a depth of 82 nm.

At $F_c = 2.4$ nN, we probe the attractive part of the tip–sample interaction as the total ultrasonic vibration amplitude is smaller than the indentation depth and recognize that we have damaged the surface slightly, while measuring earlier at higher contact forces. The root-mean-square amplitude of the induced height variation is only 0.9 nm. Please note that in UFM the sample is significantly more damaged, due to the required large ultrasound amplitudes.

At $F_c = 2.4$ nN, both the $A_{\text{diff}}$ and $\phi_{\text{diff}}$ image show a clear correlation with the height. As the cantilever mainly probes the attractive part of the tip–sample interaction during an oscillation, the effective contact area of the tip depends on the height variations of the sample: it is much smaller on a mountain than in a valley. Adhesion is directly proportional to the contact area and a variation of it indeed leads to a variation in both the amplitude and the phase of the subsurface signal [9]. We conclude that variations in the adhesion do generate a contrast in $A_{\text{diff}}$ and $\phi_{\text{diff}}$.

To quantify the contrasts of the gold nanoparticles in figure 3, we extract from cross sectional lines, as shown in figure 4, the average values above the nanoparticles for the height, $A_{\text{diff}}$, and $\phi_{\text{diff}}$ with respect to their background, see table 1.

Let us first compare the experimental values with the expected contrast based on Rayleigh scattering [24], for which we have to normalize the amplitudes $A_{\text{diff}}$ with respect to their background amplitudes $A_b$. At $F_c = 163$ nN, we measure a normalized amplitude contrast, $A_n$, of $-0.44$ and a phase $\phi_{\text{diff}}$ of $7.2^\circ$. At $F_c = 115$ nN, the normalized amplitude contrast is $-0.11$ and the phase contrast is $2.9^\circ$. Based on Rayleigh scattering, the expected normalized amplitude contrast is $10^{-6}$ and the phase contrast is 0.1 millidegree for a gold particle with a diameter of 20 nm buried 50 nm deep under a polymer (PMMA) [24]. As the experimentally observed normalized amplitude contrast is 5 orders of magnitude larger (and the phase contrast 4 orders of magnitude) than the theoretically predicted ones, we have to conclude that Rayleigh scattering takes place, but does not form a major contribution to the physical contrast mechanism (at least not at MHz frequencies).

Recently, it was elucidated how the heterodyne signal is generated: its magnitude strongly depends on both the applied contact force and the specific characteristics of the tip–sample interaction [6, 9, 25]. In supplementary notes 3 and 4 we show, both experimentally and analytically, that the heterodyne signal depends on the elastic properties of the sample, which is characterized by its Young’s modulus $E$. For sufficiently soft samples, the amplitude $A_{\text{diff}}$ increases linearly with increasing $E$ (see equation (9) in supplementary note 4). Let us, in the following, consider elasticity variations in the sample, due to the presence of the nanoparticles, as a possible contrast mechanism.

From an analytical 1D model, we estimate that the Young’s modulus above a gold nanoparticle is $\sim 10\%$ higher than the Young’s modulus of PMMA or PVA, which is 2.4 GPa, see supplementary note 6. Note that we experimentally verified that the Young’s modulus of our final sample (stack) indeed equals the Young’s modulus of PMMA, see supplementary note 5. To determine the contrast formation based on these elasticity variations, we numerically calculated the motion of the cantilever for different tip–sample interactions using the method outlined in [6]. The result is shown in figure 5, in which we, for reasons of clarity, only show the approach curves. To receive an upper bound on the contrast and to elucidate the contrast formation effect on the basis of small elasticity variations, we consider Young’s moduli between 2 and 6 GPa. As the specific vibration spectrum of the cantilever has great influence on the results, we first matched the spectrum used in the calculations to that of our experiment, see supplementary note 7. We call the particular off–resonance excitation scheme that we used in this experiment (see figure 2), experimental excitation. The graphical result, see figure 5, shows the corresponding tip–sample interactions and, as a function of the applied contact force, the indentations as well as the amplitudes $A_{\text{diff}}$ and phases $\phi_{\text{diff}}$ of the heterodyne signal at the difference frequency. The contrasts at a certain contact force can now be evaluated from the difference in the signals stemming from different elasticities (colors in the graphs). The indentation contrast decreases with decreasing contact force. The amplitude contrast stays almost constant over a large range (and even increases slightly), before it collapses, like the phase contrast, to zero at very small contact forces. The extracted height, amplitude and phase values are listed in table 1. In
To receive clear upper estimates, we determined (most of) the contrasts from the differences in the curves of figure 5 between a sample with 2 and 6 GPa. For completeness, we provide, for the experimental scheme, also the contrasts obtained from the difference in samples with 2.4 GPa (PVA) and 2.6 GPa (effective elasticity above the nanoparticles, as derived in supplementary note 6).

### Table 1. Comparison between experimentally determined and analytically predicted values: the obtained contrasts in the height, the amplitude \( A_{\text{diff}} \), the normalized amplitude \( A_h \), and the phase \( \phi_{\text{diff}} \) for a contact force of 163 and 115 nN. The contrasts are obtained from different numerical calculations taking into account specific excitation schemes, see supplementary note 8.

| Method               | \( F_{\text{contact}} \) (nN) | Height (nm) | \( \Delta A_{\text{diff}} \) (pm) | \( A_h \) (pm) | \( \Delta A_{\text{diff}} / A_h \) | \( \Delta \phi_{\text{diff}} \) (°) |
|----------------------|-------------------------------|-------------|-----------------------------------|----------------|-----------------------------------|---------------------------------|
| Experiment           | 163                           | 2.8         | -120                               | 270            | -0.44                             | 7.2                             |
|                      | 115                           | 1.2         | -40                                | 360            | -0.11                             | 2.9                             |
| Exp. scheme (2.4 → 2.6 GPa) | 163                           | 0.08        | 0.87                               | 17             | 0.05                              | 0.027                           |
|                      | 115                           | 0.03        | 1.1                                | 21             | 0.05                              | 0.008                           |
| Exp. scheme (2 → 6 GPa) | 163                           | 1.8         | 17                                 | 15             | 1.1                               | 0.120                           |
|                      | 115                           | 1.2         | 32                                 | 19             | 1.7                               | 0.083                           |
| Off–off resonance\(^a\) | 163                           | 1.8         | 42                                 | 20             | 2.1                               | 0.014                           |
| (2 → 6 GPa)          | 115                           | 1.3         | 63                                 | 24             | 2.6                               | -0.002                          |
| Off–on resonance     | 163                           | 1.8         | -0.86                              | 7.0            | -0.12                             | 11                              |
| (2 → 6 GPa)          | 115                           | 1.2         | -0.23                              | 9.6            | -0.02                             | 12                              |

\(^a\) The ultrasound signals are midway between two resonance frequencies.

Figure 5. Results for the experimental excitation scheme: we calculated the tip–sample interaction and, as a function of the applied contact force, the corresponding sample indentation as well as the amplitude \( A_{\text{diff}} \) and phase \( \phi_{\text{diff}} \) of the heterodyne signal for different sample elasticities: 2 GPa (black), 3 GPa (red), 4 GPa (magenta), 5 GPa (green), and 6 GPa (blue). The inset in the lower left panel shows \( A_{\text{diff}} \) for 6 GPa plotted as a function of the height of the cantilever’s base, \( z_b \), such that a comparison becomes possible with other calculations [6, 9, 25].

addition, to elucidate the effect of different ultrasonic excitation schemes, we also considered an off–off resonance excitation, in which both ultrasound signals are midway between two resonance frequencies, as well as an off–on resonance excitation, see supplementary note 8. These results are, in addition, tabulated in table 1 for comparison.

The experimental scheme with 2.4 GPa (PVA) to 2.6 GPa (effective elasticity above the nanoparticles, see supplementary note 6) perfectly reflects both the sample and the measurement conditions. To receive clear upper bounds, we determined further all excitations schemes from the differences between a sample with 2 and 6 GPa. Starting with the height contrast, we find comparable values between the experiment and the calculated excitation schemes, except for the experimental scheme 2.4 → 2.6 GPa. The decrease in height contrast for smaller contact forces \( F_c \) is reproduced for all cases. Considering the amplitude contrast \( \Delta A_{\text{diff}} \), the absolute values in the experiment are up to 10 times larger than the calculated ones. Although this already indicates a problem, the most striking issue is the sign of the contrast, which is inverted in comparison with the experiment!

As the (visco)elasticity above the nanoparticle is for sure increased, which theoretically leads to a higher amplitude \( A_{\text{diff}} \) (see figure 5 and supplementary note 4), one expects a positive amplitude contrast \( \Delta A_{\text{diff}} \) and thus islands instead of holes. In conclusion, although taking place, elasticity variations cannot explain the observed contrast, as it is inverted. Consequently, a different physical mechanism must be present.

Please note that the amplitude contrast inversion of \( \Delta A_{\text{diff}} \) in the off–on resonance case is due to its particular excitation scheme with the frequency shift of the 4th mode [31]. Above the nanoparticle, the amplitude reduction of the ultrasonic tip vibration \( A_t \) is significantly larger than the reduction on the PVA without nanoparticles (see supplementary note 8). This indicates the importance of the precise excitation scheme and the spectrum of the cantilever for each published HFM measurement. Without these information it is impossible to compare measurements or understand them quantitatively.

For the sake of completeness, we shortly turn our attention to the phase behavior. The magnitude of the experimentally observed phase contrast \( \Delta \phi_{\text{diff}} \) is only comparable to the special case of the off–on resonance excitation scheme. The large phase shift in this scheme is due to the frequency shift of
the 4th resonance: the particular off–on resonance excitation scheme makes the tip vibration especially sensitive to phase changes based on frequency shifts [31]. Although much smaller in magnitude, a similar argument holds also for the phase shifts in the off–off resonance and experimental excitation schemes. Since the ultrasonic tip excitation in the experimental scheme is closer to the 4th resonance frequency of the cantilever, we observe a larger phase contrast than in the off–off resonance scheme where the excitation of the tip is midway between resonance frequencies.

Summarizing this part, we conclude that the contrast from (small) variations in the sample elasticity results in a much larger contrast than Rayleigh scattering: the order of magnitude is comparable to the experiments. However, variations in sample elasticity cannot be the physical contrast mechanism in our HFM experiment, as it would imply an opposite sign.

4. Discussion

Ruling out both variations in the tip–sample interaction (elasticity and adhesion) and Rayleigh scattering, the remaining physical contrast mechanism must lead to a significant reduction of the tip amplitude \(A_t\) or the sample amplitude \(A_s\) above the nanoparticles, as

\[
A_{\text{diff}} \sim A_t A_s / \sqrt{A_t^2 + A_s^2}
\]

(1)

(see [9] for the derivation). These reductions can be described as tip or sample damping. Tip damping can also be excluded, as it has been surprisingly shown that \(A_t\) keeps 99.7% of its amplitude at a contact force of 25 nN even on a hard sample like Si [25]. Please note that the damping of the resonance frequencies of a cantilever that is in contact with a sample, is generally assumed to be directly proportional to the Young’s modulus of the sample [36]. Without significant tip damping, the contrast must be due to a reduction in the sample amplitude. Since a reduction of \(A_s\) is expected to occur also on the polymer without nanoparticles, and since \(A_{\text{diff}}\) is larger above the nanoparticle due to the increase in the effective Young’s modulus, we need a mechanism that leads to a strong decrease of \(A_s\) only above the nanoparticle to overcompensate the increase in \(A_{\text{diff}}\) such that it effectively leads to a contrast inversion (holes in \(A_{\text{diff}}\), see figure 3).

Let us start with a possible vertical motion of the nanoparticles in the polymer matrix. At low ultrasonic sample frequencies, this motion is surely in phase with the excitation. However, if the ultrasonic excitation is above the resonance frequency of the system ‘nanoparticle in polymer’, the motion will be out of phase leading to a significant reduction of \(A_s\) only above the nanoparticles. The problem is, however, that the sample excitation is at 2.5 MHz and that we estimate the resonance frequency of the ‘nanoparticle in polymer’ system, i.e. the resonance frequency of a mass (the nanoparticle) that is firmly hold by two springs (the PVA layer above and the PMMA layer below), to be \(\sim 2.2 \text{ GHz}\) (see supplementary note 9). The nanoparticles should, therefore, simply follow the ultrasonic displacements of the polymer.

Another mechanism worth considering is sample damping (reduction of \(A_s\) in equation (1)) by energy dissipation at the nanoparticles. Next to contrast formation based on attenuation or friction, a temperature effect might additionally enhance the contrast, especially if the elasticity of the polymer would have a strong temperature dependence. Therefore, we measure the energy dissipation from our experiment. We determine the sample amplitude \(A_s\) (far away from the nanoparticle) in analogy to the method described in [6]. At \(F_c = 163 \text{ nN}\) we determine \(A_s\) to be \(A_s \sim 0.22 \text{ nm}\). From the \(A_{\text{diff}}\)-line above the nanoparticle, see figure 6, we determine the reduction of \(A_{\text{diff}}\) to be 44%. Applying equation (1), \(A_s\) must be, therefore, decreased with 41%. A similar determination can be performed for the measurement at \(F_c = 115 \text{ nN}\) and one receives that \(A_s\) must be decreased with 12%, see figure 4. These measured values can be converted into more appropriate units: using the effective spring constant \(k_{\text{eff}} = 4 \text{ N m}^{-1}\) of the sample computed via \(\left( k_{\text{PMMA}} + k_{\text{PVA}} \right)^{-1}\) (see values in supplementary note 9), the difference in potential energy per oscillation cycle is given by 0.5 \(k_{\text{eff}} A_s^2\). Multiplying this value with \(2 \pi f_c\) results finally in the power dissipation per oscillation cycle. From our measurements we determine 0.53 and 0.86 pW for a contact force of 163 nN and 115 nN, respectively. Following surface science units, this converts to an energy dissipation at the nanoparticles of 2.07 eV oscillation\(^{-1}\) of the ultrasonic sample excitation at \(f_c = 2.52 \text{ MHz}\). This dissipation is extremely small, which becomes clear, if one compares it to the cohesive/binding energy of a single Au atom of \(E_c = 3.8 \text{ eV}\). The table in figure 6 provides an overview, in which we list also the contribution of all other contrast mechanisms that (partly) take place simultaneously. The measured dissipation must be slightly higher than determined (2.79 eV oscillation\(^{-1}\) instead of 2.07 eV oscillation\(^{-1}\)), as the magnitude of both the tip–sample interaction and ultrasound attenuation are not negligible and have, in addition, an inverted sign in the contrast.
The measured energy dissipation is so small that we can rule out also any temperature effects. The only remaining physical mechanisms that might cause this energy dissipation is ultrasound attenuation within the nanoparticles as well as dissipation at the interface between the nanoparticles and the polymer.

The ultrasound attenuation for gold is ~150 times smaller than the attenuation for PVA. Therefore the total energy dissipation is less at the positions measured above the nanoparticles than at the positions far away from them. This effect results, in comparison to the experiment, again in a wrong sign of the contrast, as \( A_s \) should be larger above the nanoparticles. We estimate this resulting energy ‘gain’ based on a smaller ultrasound attenuation at the nanoparticles to be 0.45 eV oscillation\(^{-1}\). The dissipation that causes the observed contrast, must be increased with this value to overcompensate it and lead to contrast inversion.

In short, we concluded that Rayleigh scattering [24] forms an insignificant contribution to the observed contrast\(^4\). Elasticity variations within the sample, generate a contrast with opposite sign. As it was shown before that the ultrasound amplitude of the tip remains constant [6, 25], the ultrasonic vibration amplitude of the sample on the surface above the nanoparticle has to be decreased to explain the experimentally observed contrast with holes in \( A_{\text{diff}} \). Consequently, ultrasound energy has to be dissipated in or around the nanoparticles. As the ultrasound attenuation in gold is much smaller than in PMMA and PVA, this dissipation must happen at the interface between the gold and the polymer. Please note that whatever the exact physical mechanism of this energy dissipation is, one should always label it as friction by definition.

This means that we are left with friction at the interface between the nanoparticles and the PVA. Due to a weak (chemical) bonding between the gold and the PVA, the nanoparticles might (slightly) slip instead of following all displacements of the PVA. One might even consider a small cavity around the nanoparticles such that they are shaken up and down. Both effects would lead to a significant amount of friction at the interface. Considering shaking nanoparticles, we are able to explain our observed contrast with a total energy dissipation of 2.79 eV oscillation\(^{-1}\) at the nanoparticles, see figure 6.

To get a sense on this experimentally determined value, we compare it with the energy dissipation that occurs in atomic scale friction experiments, in which a sharp tip is laterally moved in contact with a surface [37]. The tip radius in these experiments is comparable to the radius of our nanoparticles! By integrating the stick-slip motion of figure 2(a) in [37], we find a dissipation of approximately 1 eV jump\(^{-1}\), which is associated with the friction when moving the tip only one atomic displacement. For a proper comparison, this value should be multiplied (at least) with a factor of 2, leading to 2 eV jump\(^{-1}\), as we have the complete spheres in contact with the polymer. This value nicely compares with our measured 2.79 eV oscillation\(^{-1}\) and definitely reflects the right order of magnitude!

We summarize the effect of friction at the interface between the nanoparticles and the polymer on the amplitude \( A_{\text{diff}} \) as follows. The dissipated energy per oscillation \( E_0 \) results in a reduction of the ultrasonic tip amplitude \( A_s \) to \( A'_s \):

\[
A'_s = A_s \left( 1 - \frac{2E_0}{kA_s^2} \right),
\]

in which \( k \) is the effective spring constant of the sample. In turn, this leads to a smaller \( A_{\text{diff}} \) as \( A_{\text{diff}} \sim A_s A_{\text{at}} / \sqrt{A_s^2 + A_{\text{at}}^2} \) [9].

As a remark, we point out that, depending on the roughness of the sample, significant lateral friction can take place between the surface of the sample and the tip. It has even been demonstrated that lateral friction enhances AFM contrasts [38]. However, the friction at the interface between the nanoparticles and the polymer occurs 82 nm below the surface. Therefore, lateral friction clearly cannot explain our results, as it is purely a surface effect.

Pinpointing the physical mechanism to friction at shaking nanoparticles, we can consider the consequences for the lateral resolution. If one assumes that the propagation in amplitude reduction obeys a scattering-like behavior, the ‘fingerprints’ of the nanoparticles at the surface should show a significantly larger diameter than the diameter of the nanoparticles. Moreover, as we are measuring in near-field, the size of the ‘fingerprints’ should be in the order of the depth of the nanoparticles. The deeper the nanoparticle is, the larger should be its image at the surface. These considerations stand in clear contrast to experimental observations: nanoparticles with a diameter of ~17.5 nm, buried 500 nm deep, are imaged with a diameter of only 20 nm [14], and the imaged fingerprint is even decreasing with increasing depth of the nanoparticles [13]. In contradiction to these observations, the full width half maximum of our observed contrast is approximately equal to the buried depth, exactly as it should be! The reason can be easily understood, if one realizes that we are insensitive to both elasticity variations in the sample and stress fields that can be generated by the tip. The fact that we measure the expected size of the fingerprints confirms one more time that we solely measure the ultrasonic sample vibration in a clean heterodyne detection scheme [9].

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Author contributions

The project was initiated and conceptualized by MJR. GJV performed all the measurements, the simulations, and the analytical calculations presented in this study. GJV and MJR interpreted the results and narrowed down the number of possible physical contrast mechanisms. THO helped with the interpretation and suggested ‘Friction at shaking nanoparticles’ as a possible contrast formation mechanism. GJV and MJR wrote the manuscript together, which was carefully read and improved by all authors.

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