Article

Global Analysis and the Periodic Character of a Class of Difference Equations

George E. Chatzarakis 1, Elmetwally M. Elabbasy 2, Osama Moaaz 2,* and Hamida Mahjoub 2,3

1 Department of Electrical and Electronic Engineering Educators, School of Pedagogical and Technological Education (ASPETE), 14121 N. Heraklio, Athens, Greece.
2 Department of Mathematics, Faculty of Science, Mansoura University, 35516 Mansoura, Egypt
3 Department of Mathematics, Faculty of Science, Benghazi 0021861, Libya

* Correspondence: o_moaaz@mans.edu

Received: 22 July 2019; Accepted: 30 August 2019; Published: 15 November 2019

Abstract: In biology, Difference equations is often used to understand and describe life phenomenon through mathematical models. So, In this work, we study a new class of difference equations by focusing on the periodicity character, stability (local and global) and boundedness of its solutions. Furthermore, this equation involves a May’s Host Parasitoid Model, as a special case.

Keywords: difference equations; stability; boundedness; periodicity character; may’s host parasitoid model

MSC: 39A10; 39A23; 39A30

1. Introduction

The goal of our paper is to research the dynamics of solutions of equation

\[ J_{n+1} = \alpha + \frac{\beta J_n^2}{(\gamma + J_n) J_{n-1}}, \quad n = 0, 1, \ldots, \]  

(1)

where \( \alpha, \beta, \gamma \in [0, \infty), \beta \neq 0 \) and the initial data \( J_{-1}, J_0 \in (0, \infty) \).

When describing the evolution of any phenomenon as a mathematical model, difference equations often arise, frequently due to the discrete nature of time-evolving variable measurements and detached sciences. Difference equations are used in situations of real life, in various sciences (population models, genetics, psychology, economics, sociology, stochastic time series, combinatorial analysis, queuing problems, number theory, geometry, radiation quanta and electrical networks).

In fact, the nonlinear DEs have the efficiency to make a complicated behavior, regardless of their order. Among the well-known examples, the family \( J_{n+1} = y \lambda (J_n), \lambda > 0, \) depends on \( \eta \), and its conduct changes from a bounded number of periodic solutions to chaos. Due to the many applications of differential equations, there is a growing interest in searching for various aspects in terms of dynamics and behaviors of difference equations (see [1–43]).

Our focus in this paper is on the study of qualitative behavior of solutions of the nonlinear difference equations. Furthermore, a new equation includes a May’s Host Parasitoid Model, as a special case. Minutely, we discuss the local/global stability, boundedness and periodicity character of the solution. Moreover, by applying our results, we will prove the following conjecture:

Conjecture 1 ([24]). Let \( \beta > 1 \). Show that every positive solution of May’s Host Parasitoid Model (Equation (1) with \( \alpha = 0 \) and \( \gamma = 1 \)) is bounded.
2. Periodic Solutions with Period $p$

Here, we will study the existence of periodic solutions to the Equation (1).

**Theorem 1.** If $\alpha, \beta, \gamma \in [0, \infty)$, then equation (1) does not have positive period two solutions. Moreover, if $\alpha, \beta, \gamma \in \mathbb{R} \setminus \{0\}$ and

$$\frac{1}{\beta} (\alpha + \beta + \gamma) > 2,$$

then equation (1) has a period two solutions.

**Proof.** Assume that equation (1) has a prime period two solution ... $r, s, r, s, \ldots$ ($r \neq s$). Let $\alpha, \beta$ and $\gamma$ are nonnegative real number. From (1), we get

$$r = \alpha + \frac{\beta s^2}{(\gamma + s) r} \quad (2)$$

and

$$s = \alpha + \frac{\beta r^2}{(\gamma + r) s}. \quad (3)$$

Consequently,

$$r - s = \frac{\beta s^2}{(\gamma + s) r} - \frac{\beta r^2}{(\gamma + r) s}$$

and so

$$(r - s) \left(1 + \frac{1}{rs} \left(\frac{\beta (r^2 s + \gamma r^2 + rs^2 + \gamma rs + \gamma s^2)}{(r + \gamma) (s + \gamma)}\right)\right) = 0.$$

Since $\alpha, \beta, \gamma \in [0, \infty)$, this means that $r = s$, a contradiction.

On the Other hand, if $\alpha, \beta$ and $\gamma$ are real numbers. From (2), we get

$$r = \alpha + \frac{\beta s^2}{(\gamma + s) r} = \alpha + \frac{\beta}{t^2} \left(\frac{1}{\gamma + \frac{s}{t}}\right),$$

where $t = r/s$. Then,

$$r^2 - \left(\alpha + \frac{\beta}{t} - \gamma t\right) r - t \alpha \gamma = 0,$$

which gives

$$r = \frac{1}{2t} \left(\beta + t \alpha - t^2 \gamma + A\right), \quad (4)$$

where

$$A = \pm \sqrt{t^4 \gamma^2 + 2t^3 \alpha \gamma + t^2 \alpha^2 - 2t^2 \beta \gamma + 2t \alpha \beta + \beta^2}.$$

Similarly, from (3), we obtain

$$s = \frac{1}{2t} \left(-\gamma + t \alpha + t^2 \beta + B\right), \quad (5)$$

with

$$B = \pm \sqrt{t^2 \alpha^2 + t^4 \beta^2 + \gamma^2 + 2t \alpha \gamma + 2t^3 \alpha \beta - 2t^2 \beta \gamma}.$$

By using the fact $r - st = 0$, (4) and (5), we find

$$A + C = Bt,$$
where
\[ C = \beta t + t\alpha + t\gamma - t^2\alpha - t^2\gamma - t^3\beta. \]

By simple computation, (10) shows that
\[ A^4 + C^4 + t^4B^4 - 2A^2B^2t^2 - 2B^2C^2t^2 + 2A^2C^2 - 4A^2C^2 = 0. \]

From definitions of \(A, B\) and \(C\), we have
\[ t^3\alpha\gamma (t - 1)^2 (\beta + t\alpha + t\gamma + t^2\beta)^2 = 0. \]

Since \(\alpha\gamma t \neq 0\) and \(t \neq 1\), we obtain
\[ \frac{\alpha + \beta + \gamma}{\beta} = -\left(\frac{t^2 + 1}{t}\right). \] (7)

Now, if \(t \in \mathbb{R}^+\), then the function \(H(t) := \frac{1 + t^2}{t}\) attains its minimum value on \(\mathbb{R}^+\) at \(t^* = 1\) and \(H(t) > \min_{t \in \mathbb{R}^+} H(t) = 2\). In contrast, if \(t \in \mathbb{R}^\times\), then the function \(H\) attains its maximum value on \(\mathbb{R}^\times\) at \(t^- = -1\) and \(H(t) < \max_{t \in \mathbb{R}^\times} H(t) = -2\). Thus, from (7), we see that
\[ \frac{1}{\beta} (\alpha + \beta + \gamma) < -2 \text{ if } rs > 0 \]

or
\[ \frac{1}{\beta} (\alpha + \beta + \gamma) > 2 \text{ if } rs < 0. \]

The proof is complete. \(\square\)

**Theorem 2.** If \(\alpha = 0, \beta, \gamma \in \mathbb{R} \setminus \{0\}\) and either
\[ \frac{\gamma}{\beta} < -3, \text{ for } x_{-1}x_0 > 0, \]

or
\[ \frac{\gamma}{\beta} > 1, \text{ for } x_{-1}x_0 < 0, \]

then equation (1) has a period two solutions.

**Proof.** Assume that equation (1) has a prime period two solution \(r, s, r, s, ..., (r \neq s)\). From (1), we get
\[ r = \frac{\beta}{\left(\frac{\gamma}{\beta} + \frac{1}{t}\right)t^2}. \]

where \(t = r/s\). Then
\[ r = \frac{\beta}{t} - \gamma t. \] (8)

Similarly, we obtain
\[ s = \beta t - \gamma t. \] (9)

By using the fact \(r - st = 0\), (8) and (9), we find
\[ -\beta t^3 - \gamma t^2 + \gamma t + \beta = 0, \]
and so
\[ \frac{\gamma}{\beta} = -\frac{1}{t} \left( t^2 + t + 1 \right). \]

Now, if \( t \in \mathbb{R}^+ \), then the function \( H(t) := \frac{t^2 + t + 1}{t} \) attains its minimum value on \( \mathbb{R}^+ \) at \( t^*_+ = 1 \) and \( H(t) > \min_{t \in \mathbb{R}^+} H(t) = 3 \). In contrast, if \( t \in \mathbb{R}^- \), then the function \( H \) attains its maximum value on \( \mathbb{R}^- \) at \( t^*_- = -1 \) and \( H(t) < \max_{t \in \mathbb{R}^-} H(t) = -1 \). Thus, from (7), we see that
\[ \frac{\gamma}{\beta} < -3 \text{ if } rs > 0 \]
or
\[ \frac{\gamma}{\beta} > 1 \text{ if } rs < 0. \]

The proof is complete.

**Theorem 3.** Let \( p \) be a positive integer and \( p > 2 \). If every positive solution of Equation (1) is periodic with period \( p \), then \( \alpha = 0 \).

**Proof.** Assume that every positive solution of Equation (1) is periodic with period \( p \). Now, we consider the solution with
\[ J_{-1} = 1 \text{ and } J_0 \in (0, \infty). \]

Hence, \( J_{p-1} = 1 \) and \( J_p = J_0 \). From Equation (1), we have
\[
J_p = \alpha + \frac{\beta J_{p-1}^2}{(\gamma + J_{p-1}) J_{p-2}}
= \alpha + \frac{\beta}{(\gamma + 1) J_{p-2}} = J_0,
\]
or
\[
\alpha (\gamma + 1) J_{p-2} + \beta = (\gamma + 1) J_0 J_{p-2}.
\]

Assume that \( \alpha \neq 0 \) and \( \beta > 0 \). If we choose \( J_0 < \alpha \), then
\[
\alpha (\gamma + 1) J_{p-2} + \beta = (\gamma + 1) J_0 J_{p-2}
< \alpha (\gamma + 1) J_{p-2}
\]
which is impossible and hence \( \alpha = 0 \). The proof of the theorem is complete.

**Remark 1.** Let \( \alpha = 0 \), it is possible that every positive solution of Equation (1) is periodic with period \( p \). As a special case, if \( \alpha = \gamma = 0 \), then we see that every positive solution of equation
\[ J_{n+1} = \beta \frac{J_n}{J_{n-1}} \]
is periodic with period six
\[ J_{-1}, J_0, \beta \frac{J_0}{J_{-1}}, \beta^2 \frac{1}{J_{-1}}, \beta^2 \frac{1}{J_0}, \beta \frac{J_1}{J_0}, \ldots. \]
3. Stability and Boundedness

Let \( J_e \) be a point in the domain of the function \( F \). Then, \( J_e \) is said to be an equilibrium point of equation \( J_{n+1} = F(J_n, J_{n-1}) \) if \( J_e \) is a fixed point of \( F \), i.e., \( F(J_e, J_e) = J_e \). The idea of equilibrium points (states) is focal in the investigation of the dynamics of any physical system. In numerous applications in science, physics, engineering, and so on., it is known that all states (solutions) of a given system tend to its equilibrium state (point). We presently give the Formula of an equilibrium point of Equation (1). To find the positive equilibrium points, we let \( F(J_e, J_e) = J_e \), or

\[
J_e = \alpha + \frac{\beta J_e^2}{(\gamma + J_e) J_e}
\]

and so

\[
J_e^2 - (\alpha + \beta - \gamma) J_e - \alpha \gamma = 0.
\]

Thus, we have both cases:

**Case (1):** If \( \alpha + \beta = \gamma \), then the only positive equilibrium point is

\[
J_e = \sqrt{\alpha \gamma}.
\]

**Case (2):** If \( \alpha + \beta \neq \gamma \), then the only positive equilibrium point is

\[
J_e = \frac{1}{2} (\alpha + \beta - \gamma) + \frac{1}{2} \sqrt{(\alpha + \beta - \gamma)^2 + 4 \alpha \gamma}.
\]

Also, if \( \alpha \gamma = 0 \), then the only positive equilibrium is

\[
J_e = \alpha + \beta - \gamma, \text{ if } \alpha + \beta > \gamma.
\]

One of the fundamental objectives in the investigation of a dynamical system is to determine the behavior of its solutions near an equilibrium point. For the basic definitions of stability see [24]. To study the local stability of a positive equilibrium point, we define the function \( F : (0, \infty) \times (0, \infty) \to (0, \infty) \) by

\[
F(u, v) = \alpha + \frac{\beta u^2}{(\gamma + u) v}.
\]

(10)

The partial derivatives of function \( F \) are

\[
\frac{\partial}{\partial u} F(u, v) = \frac{u \beta}{v (u + \gamma)^2 (u + 2 \gamma)}
\]

(11)

and

\[
\frac{\partial}{\partial v} F(u, v) = -\frac{u^2 \beta}{v^2 (u + \gamma)}.
\]

(12)

The equilibrium point \( J_e \) is called a sink or an attracting equilibrium if every eigenvalue of Jacobian matrix of \( J_e \) has absolute value less than one, see [23]. In the following theorem, by using Theorem 1.1.1 in [24], we study a locally asymptotically stable for positive equilibrium point of (1) when \( \alpha, \beta, \gamma \in [0, \infty) \).

**Theorem 4.** Let \( \alpha \neq 0 \). Then the positive equilibrium point of Equation (1) is locally asymptotically stable and sink.
Proof. By replacing both \( u \) and \( v \) with \( J_e \) in Equations (11) and (12), we get

\[
\frac{\partial}{\partial u} F(J_e, J_e) = \frac{\beta}{(\gamma + J_e)} (2\gamma + J_e) := \mu_u \tag{13}
\]

and

\[
\frac{\partial}{\partial v} F(J_e, J_e) = -\frac{\beta}{\gamma + J_e} := \mu_v. \tag{14}
\]

Then, the linearized equation associated with (1) about \( J_e \) is

\[
z_{n+1} - \mu_u z_n - \mu_v z_{n-1} = 0.
\]

Now, we have

\[
J_e = \frac{1}{2} (\alpha + (\beta - \gamma)) + \frac{1}{2} \sqrt{\left(\frac{\alpha + (\beta - \gamma)}{2}\right)^2 + 4\alpha \gamma}
\]

and so

\[
\frac{\beta}{\gamma + J_e} < 1.
\]

Moreover, we see that

\[
\frac{\beta \gamma}{(\gamma + J_e)^2} < \frac{\gamma}{\gamma + J_e} < 1. \tag{15}
\]

From (13)–(15), we obtain

\[
|\mu_u| + \mu_v = \frac{\beta}{(\gamma + J_e)^2} (2\gamma + J_e) - \frac{\beta}{\gamma + J_e}
\]

and

\[
\mu_v = -\frac{\beta}{\gamma + J_e} > -1.
\]

Hence, we have \(|\mu_u| < 1 - \mu_v < 2\). Therefore, \( J_e \) is locally asymptotically stable and sink. The proof of the theorem is complete. \( \square \)

Theorem 5. Let \( \alpha = 0 \) and \( \beta > \gamma \). Then the positive equilibrium point of Equation (1) is locally asymptotically stable and sink.

Proof. The proof is similar to the proof of Theorem 4 and so we omit it. \( \square \)

Lemma 1. If \( \alpha > 0 \), then

\[
\alpha < J_n \leq \alpha + \beta \left(1 + \frac{\beta}{\alpha}\right), \tag{16}
\]

for all \( n > 0 \) and so every solution of Equation (1) is bounded.

Proof. Suppose that \( \{J_n\}_{n=1}^\infty \) be a solution of (1). It follows from (1) that

\[
J_{n+1} = \alpha + \frac{\beta J_n^2}{(\gamma + J_n) J_{n-1}} > \alpha.
\]
Since \( \gamma > 0 \), we have \( J_n < \gamma + J_n \), and thus

\[
J_{n+1} = \alpha + \frac{\beta J_n^2}{(\gamma + J_n)J_{n-1}} < \alpha + \beta \frac{J_n}{J_{n-1}}. \tag{17}
\]

Next, we let

\[
\phi_{n+1} = \alpha + \beta \frac{\phi_n}{\phi_{n-1}}. \tag{18}
\]

From (18), we get \( \phi_n > \alpha \) for all \( n > 1 \), and so

\[
\phi_{n+1} = \alpha + \beta \left( \frac{\alpha}{\phi_{n-1}} + \frac{\beta}{\phi_{n-2}} \right) < \alpha + \beta \left( 1 + \frac{\beta}{\alpha} \right).
\]

Thus, and from (17), we get

\[
\alpha < J_n < \alpha + \beta \left( 1 + \frac{\beta}{\alpha} \right),
\]

for all \( n > 1 \). The proof of the lemma is complete. \( \square \)

**Lemma 2.** If \( \alpha = 0 \) and \( \beta > \gamma \), then all solution of (1) is bounded.

**Proof.** As in the proof of Lemma 1, (17) holds. If \( \alpha = 0 \), then (17) becomes

\[
J_{n+1} < \beta \frac{J_n}{J_{n-1}}.
\]

Moreover, every positive solution of equation \( y_{n+1} = \beta y_n / y_{n-1} \) is periodic with period six \( \{ y_{-1}, y_0, \beta y_0 / y_{-1}, \beta^2 / y_{-1}, y_0, \beta y_0 / y_0 \} \). Thus,

\[
0 < J_{n+1} < \max \left\{ \frac{J_{-1}}{J_0}, \frac{\beta J_0}{J_{-1}}, \frac{\beta^2}{J_1}, 1, \frac{\beta}{J_0}, \frac{\beta^2}{J_1} \right\}.
\]

The proof of the lemma is complete. \( \square \)

**Theorem 6.** Assume that \( \alpha \neq 0 \), \( \gamma > \beta \) and \( \alpha^6 > 2\beta \gamma (\alpha^2 + \alpha \beta + \beta^2)^2 \). Then (1) has a unique equilibrium \( J_e \) and every solution of (1) converges to \( J_e \).

**Proof.** Consider the function \( F \) defined as (10). From (11) and (12), we have that \( F \) is increasing in \( u \) and decreasing in \( v \). Now, let \( (U, L) \) be a solution of the system

\[
\begin{align*}
J &= F(J, y); \\
y &= F(y, J).
\end{align*}
\]

Then, we get

\[
U = \alpha + \frac{\beta U^2}{(\gamma + U) L}.
\]
and

\[ L = \alpha + \frac{\beta L^2}{(\gamma + L) U}. \]

Hence, we have

\[
U - L = \frac{\beta U^2}{(\gamma + U) L} - \frac{\beta L^2}{(\gamma + L) U} = (U - L) \frac{\beta (L^2 U + \gamma L^2 + LU^2 + \gamma LU)}{LU (L + \gamma) (U + \gamma)}
\]

and

\[
(U - L) \left( 1 - \frac{\beta \gamma (L^2 + U^2) + \beta (L^2 U + LU^2 + \gamma LU)}{L^2 U^2 + \gamma (L^2 U + LU^2 + \gamma LU)} \right) = 0. \quad (19)
\]

From Lemma 1, we have

\[ \alpha < L, U < \alpha + \beta \left( 1 + \frac{\beta}{\alpha} \right). \]

Thus, and from \(2\beta \gamma (a^2 + a\beta + \beta^2)^2 < a^6\), we get

\[
\beta \gamma (L^2 + U^2) < 2\beta \gamma \left( a + \beta \left( 1 + \frac{\beta}{a} \right) \right)^2 = \frac{2}{\alpha^2} \beta \gamma \left( a^2 + a\beta + \beta^2 \right)^2 < a^4 < L^2 U^2.
\]

Since \(\gamma > \beta\), we find

\[
\frac{\beta \gamma (L^2 + U^2) + \beta (L^2 U + LU^2 + \gamma LU)}{L^2 U^2 + \gamma (L^2 U + LU^2 + \gamma LU)} < 1. \quad (20)
\]

From (19) and (20), we obtain \(L = U\). From Theorem 1.4.5 in [24], we have that all solution of (1) converges to \(J_e\). The proof of the theorem is complete. \(\Box\)

4. Application and Discussion

In Equation (1), if \(\alpha = 0\) and \(\gamma = 1\), we get the May’s Host Parasitoid Model

\[
J_{n+1} = \frac{\beta J_n^2}{(1 + J_n)} J_{n-1}. \quad (21)
\]

By using Theorems 1 and 5 and Lemma 2, respectively, we get the following corollaries:

**Corollary 1.** Model (21) does not have positive period two solutions.

**Corollary 2.** Assume that \(\beta > 1\). The positive equilibrium point of equation \(J_e = (\beta - 1)\) of model (21) is locally asymptotically stable and sink.

**Corollary 3.** If \(\beta > 1\), then every solution of model (21) is bounded.

**Remark 2.** Note that, Corollaries 1–3 gave some qualitative behaviors of the model (21). Moreover, Corollary 3 confirms the Conjecture 1.
Example 1. Let the equation

\[ J_{n+1} = \alpha + \frac{3J_n^2}{(0.5 + J_n)J_{n-1}}. \]  

(22)

Figure 1 shows the dynamics of (22) with \( J_{-1} = 1.5 \) and \( J_0 = 0.1 \). Let \( N_e \) be the first value of \( n \) in which the solution is stable (by approximation \( 10^{-6} \)), for example, let \( \alpha = 1 \), we have

| \( n \) | 89 | 90 | 91 | 92 |
|-------|----|----|----|----|
| \( J_n \) | 3.63746 | 3.63745 | 3.63745 | 3.63745 |

So, \( N_e = 90 \). Note that,

| \( \alpha \) | 0.5 | 1 | 3 | 7 |
|------------|-----|---|---|---|
| \( N_e \) | 150 | 90 | 43 | 28 |
| \( J_e \) | 3.08114 | 3.63745 | 5.76040 | 9.85514 |

Figure 1. The stable solution of Equation (22) when \( \alpha = 0.5, 1, 3 \) and 7.

Remark 3. Note that, when the value of \( \alpha \) increases, stability occurs faster.

Author Contributions: The author contributed equally to the manuscript and read and approved the final manuscript.

Funding: This research received no external funding.

Conflicts of Interest: The authors declare no conflict of interest.

References
1. Abdelrahman, M.A.E.; Chatzarakis, G.E.; Li, T.; Moaaz, O. On the difference equation \( J_{n+1} = aJ_{n-1} + bJ_{n-k} + f (J_{n-1}, J_{n-k}) \). Adv. Differ. Equ. 2018, 431, 2018.
2. Agarwal, R.P.; Elsayed, E.M. Periodicity and stability of solutions of higher order rational difference equation. Adv. Stud. Contemp. Math. 2008, 17, 181–201.
3. Ahlbrandt, C.D.; Peterson, A.C. Discrete Hamiltonian Systems: Difference Equations, Continued Fractions, and Riccati Equations; Kluwer Academic Publishers: Dordrecht, The Netherlands, 1996.
4. Ahmad, S. On the nonautonomous Volterra-Lotka competition equations. *Proc. Am. Math. Soc.* **1993**, *117*, 199–204.

5. Allman, E.S.; Rhodes, J.A. *Mathematical Models in Biology: An Introduction*; Cambridge University Press: Cambridge, UK, 2003.

6. Andres, J.; Pennequin, D. Note on Limit-Periodic Solutions of the Difference Equation $x_{n+1} - [h(x_t) + \lambda]x = rt, \lambda > 1$. *Axioms* **2019**, *8*, 19, doi:10.3390/axioms8010019

7. Din, Q.; Elsayed, E.M. Stability analysis of a discrete ecological model. *Comput. Ecol. Soft.* **2014**, *4*, 89–103.

8. Grove E.A.; Ladas, G. *Periodicities in Nonlinear Difference Equations*; Chapman & Hall/CRC: Boca Raton, FL, USA, 2005; Volume 4.

9. Elabbasy, E.M.; El-Metwally, H.; Elsayed, E.M. On the difference equation $I_{n+1} = (aI_{n-1} + bI_{n-k} + cI_{n-s} - \varepsilon)$. *Acta Math. Vietnam.* **2008**, *33*, 85–94.

10. Elabbasy, E.M.; Elsayed, E.M. Dynamics of a rational difference equation. *Chin. Ann. Math. Ser. B* **2009**, *30*, 187–198.

11. El-Dessoky, M.M. On the difference equation $I_{n+1} = aI_{n-k} + bI_{n-1} + cI_{n-s}$ / (c$I_{n-1} + dI_{n-k}$). *Acta Math. Vietnam.* **2018**, *60*, 89–103.

12. Elsayed, E.M. New method to obtain periodic solutions of period two and three of a rational difference equation. *J. Nonlinear Sci. Appl.* **2019**, *5*, 1463–1474.

13. Elsayed, E.M. Dynamics and behavior of a higher order rational difference equation. *Adv. Differ. Equ.* **2012**, *69*, 2012.

14. Elsayed, E.M.; Iricanin, B.D. On a max-type and a min-type difference equation. *Axioms* **2019**, *8*, 47, doi:10.3390/axioms8020047

15. Elsayed, E.M.; Iricanin, B.D. On the recursive sequence $x_{n+1} = (a^n x_{n-k} + b^n x_{n-l} + c^n x_{n-m} - d^n x_{n-l})$. *Axioms* **2019**, *8*, 20, doi:10.3390/axioms8010020

16. Elsayed, E.M.; El-Dessoky, M.M. Dynamics and behavior of a higher order rational recursive sequence. *Adv. Differ. Equ.* **2012**, *69*, 2012.

17. Foupouagnigni, M.; Mboutngam, S. On the Polynomial Solution of Divided-Difference Equations of the Hypergeometric Type on Nonuniform Lattices. *Axioms* **2019**, *8*, 47, doi:10.3390/axioms8020047

18. Foupouagnigni, M.; Koepf, W.; Kenfack-Nangho, M.; Mboutngam, S. On Solutions of Holonomic Divided-Difference Equations on Nonuniform Lattices. *Axioms* **2013**, *2*, 404–434, doi:10.3390/axioms2030404

19. Gil, M. Solution Estimates for the Discrete Lyapunov Equation in a Hilbert Space and Applications to Difference Equations. *Axioms* **2019**, *8*, 20, doi:10.3390/axioms8010020

20. Haghighi, A.M.; Misheva, D.P. *Difference and Differential Equations with Applications in Queueing Theory*; John Wiley & Sons Inc.: Hoboken, NJ, USA, 2013.

21. Kalabusic, S.; Kulenovic, M.R.S. On the recursive sequence $x_{n+1} = (a^n x_{n-k} + b^n x_{n-l}) / (c^n x_{n-k} + d^n x_{n-l})$. *J. Differ. Equ. Appl.* **2003**, *9*, 701–720.

22. Kelley, W.G.; Peterson, A.C. *Difference and Differential Equations with Applications in Queueing Theory*; Chapman & Hall/CRC Press: Boca Raton, FL, USA, 2001.

23. Kocic, V.L.; Ladas, G. *Global Behavior of Nonlinear Difference Equations of Higher Order with Applications*; Kluwer Academic Publishers: Dordrecht, The Netherlands, 1993.

24. Kulenovic, M.R.S.; Ladas, G. *Dynamics of Second Order Rational Difference Equations with Open Problems and Conjectures*; Chapman & Hall/CRC Press: Boca Raton, FL, USA, 2001.

25. Liu, X. A note on the existence of periodic solutions in discrete predator-prey models. *Appl. Math. Model.* **2010**, *34*, 2477–2483.

26. Ma, W.-X. Global behavior of a new rational nonlinear higher-order difference equation. *Complexity* **2019**, *2019*, 2048941.

27. Migda, M.; Migda, J. Nonoscillatory Solutions to Second-Order Neutral Difference Equations. *Symmetry* **2018**, *10*, 207, doi:10.3390/sym10060207

28. Moaaz, O. Comment on new method to obtain periodic solutions of period two and three of a rational difference equation [Nonlinear Dyn 79: 241–250]. *Nonlinear Dyn.* **2017**, *88*, 1043–1049.

29. Moaaz, O. Dynamics of difference equation $x_{n+1} = f (x_{n-1}, x_{n-k})$. *Adv. Differ. Equ.* **2018**, *447*, 2018.

30. Moaaz, O.; Chalishajar, D.; Bazighifan, O. Some Qualitative Behavior of Solutions of General Class of Difference Equations. *Mathematics* **2019**, *7*, 585, doi:10.3390/math7070585.
31. Pogrebkov, A. Hirota Difference Equation and Darboux System: Mutual Symmetry. *Symmetry* 2019, 11, 436, doi:10.3390/sym11030436
32. Stevic, S. On the recursive sequence $x_{n+1} = a + x^p_{n-1}/x^p_n$. *J. Appl. Math. Comput.* 2005, 18, 229–234.
33. Stevic, S.; Kent, C.; Berenaut, S. A note on positive nonoscillatory solutions of the differential equation $x_{n+1} = a + x^p_{n-1}/x^p_n$. *J. Diff. Eqs. Appl.* 2006, 12, 495–499.
34. Stevic, S. On the recursive sequence $x_{n+1} = a_n + x_{n-1}/x_n$. *Dynam. Contin. Discret. Impuls. Syst. Ser. A Math. Anal.* 2003, 10, 911–917.
35. Stevic, S. A note on periodic character of a difference equation. *J. Differ. Equ. Appl.* 2004, 10, 929–932.
36. Stevic, S. A short proof of the Cushing–Henson conjecture. *Discret. Dyn. Nat. Soc.* 2006, 4, 37264.
37. Stevic, S. Global stability and asymptotics of some classes of rational difference equations. *J. Math. Anal. Appl.* 2006, 316, 60–68.
38. Stevic, S. Asymptotics of some classes of higher order difference equations. *Discret. Dyn. Nat. Soc.* 2007, 2007, 56813.
39. Stevic, S. Asymptotic periodicity of a higher order difference equation. *Discret. Dyn. Nat. Soc.* 2007, 2007, 13737.
40. Stevic, S. Existence of nontrivial solutions of a rational difference equation. *Appl. Math. Lett.* 2007, 20, 28–31.
41. Taousser, F.Z.; Defoort, M.; Djemai, M.; Djouadi, S.M.; Tomsovic, K. Stability analysis of a class of switched nonlinear systems using the time scale theory. *Nonlinear Anal. Hybrid Syst.* 2019, 33, 195–210.
42. Wang, C.; Agarwal, R.P. Almost periodic solution for a new type of neutral impulsive stochastic Lasota–Wazewska timescale model. *Appl. Math. Lett.* 2017, 70, 58–65.
43. Yang, C. Positive Solutions for a Three-Point Boundary Value Problem of Fractional Q-Difference Equations. *Symmetry* 2018, 10, 358, doi:10.3390/sym10090358