WEIGHING THE NON-TRANSITING HOT JUPITER \( \tau \) Boo b

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ABSTRACT

We report the detection of the orbital velocity of non-transiting hot Jupiter \( \tau \) Boo b. By employing high-resolution ground-based spectroscopy around 2.3 \( \mu \)m during one half-night, we are able to detect carbon monoxide absorption lines produced in the planet atmosphere, which shift significantly in wavelength during the course of the observations due to the orbital motion of the planet. This detection of the planetary signal results in the determination of the orbital inclination as being \( i = 47^\circ \pm 6^\circ \) deg and, furthermore, allows us to solve for the exact planetary mass, \( m_p = 5.6 \pm 0.7 M_{\text{Jup}} \). This clearly confirms the planetary nature of the non-transiting companion to \( \tau \) Boo.

Key words: planets and satellites: atmospheres – planets and satellites: individual (\( \tau \) Boo b) – techniques: radial velocities – techniques: spectroscopic

1. INTRODUCTION

The radial velocity (RV) technique is the most successful exoplanet detection method, with more than 600 planets detected to date. This technique monitors the variation of the RV of the star due to the gravitational pull of an unseen companion. Due to the fact that the RV of the planet is not measured directly, neither the orbital inclination \( i \) of the planet nor its exact mass can be determined. Instead, only an estimation of the minimum mass of the planet can be derived by applying Kepler’s Laws, which gives \( m_p \sin i = m_p \sin i \), where \( m_p \) is the unknown planetary mass. Transiting planets periodically occult their host stars and allow the measurement of the orbital inclination \( i \) and therefore the determination of the exact planetary mass. However, the vast majority of extrasolar planets found to date are non-transiting and therefore without an exactly determined mass. Consequently, many of these non-transiting planets, especially the ones with the largest minimum masses, can only be labeled as planetary candidates, owing to the fact that for very low orbital inclination, they might turn out to be brown dwarfs.

One strategy to determine the exact mass of non-transiting planets is to directly measure the planetary RV signal via high-resolution spectroscopy with very large telescopes. The key to this method is to observe a large number of spectral features coming from the planet and to observe them at different orbital phases so that the traveling faint planetary signal can be disentangled from the dominating stellar one. In the past, several high-resolution spectroscopy campaigns at the optical with the goal to detect starlight reflected from hot Jupiters (i.e., massive planets that are a few stellar radii away from their host stars) and to measure their exact masses were carried out. Although all of them resulted in non-detections of reflected light, these campaigns confirmed the low reflectivity of hot Jupiters at visual wavelengths (e.g., Charbonneau et al. 1999; Collier Cameron et al. 2002; Leigh et al. 2003; Rodler et al. 2008). Toward near-infrared (NIR) wavelengths, the planet-to-star flux ratios drastically increase due to the strong thermal emission of hot Jupiters. Wiedemann et al. (2001), Barnes et al. (2007, 2008, 2010), and Cubillos et al. (2011) observed hot Jupiters by means of high-resolution spectroscopy at near-infrared wavelengths, but were not able to detect any molecules in their atmospheres.

The molecule carbon monoxide (CO) is one key to detecting the radial velocity of an exoplanet, since it exhibits a dense forest of deep absorption lines in a spectral band around 2.3 \( \mu \)m. Models predict CO to be one of the most abundant molecules in hot gas giant exoplanets (Cooper & Showman 2006; Sharp & Burrows 2007). To test those models, some papers have already been published reporting the detection or suggesting the presence of CO in the atmosphere of some transiting hot Jupiters (Grillmair et al. 2008; Swain et al. 2009; Désert et al. 2009; Tinetti et al. 2010). All these measurements were obtained with very low resolution (\( R < 40 \)) Hubble Space Telescope NICMOS NIR spectra or broad Spitzer photometry between 3.6 and 24 \( \mu \)m, both via transmission (primary transit) and emission (secondary eclipse) observations. Snellen et al. (2010) reported the detection of CO via the analysis of the transmission spectrum of the transiting planet HD 209458b using high-resolution spectroscopy between 2.30 and 2.33 \( \mu \)m. This allowed these authors to directly measure the RV of a transiting hot Jupiter for the very first time. We note that all those CO detections were done on transiting planets, but neither atmospheric chemicals nor RV shifts have yet been detected for non-transiting exoplanets.

Here, we present the results of our attempt to detect the motion of the non-transiting planet \( \tau \) Boo b via observations of its atmospheric CO spectrum in the NIR, by using a technique similar to Snellen et al. (2010). The main goal of our study has been the measurement of the orbital inclination and the absolute mass of the planet, but, as a by-product, we can also confirm the presence of CO.

2. THE PLANETARY SYSTEM OF \( \tau \) Boo

\( \tau \) Boo b is a massive hot Jupiter, orbiting its host star every 3.31 days, and is estimated to have an atmospheric temperature above 1800 K following the formalism in López-Morales & Seager (2007), assuming zero albedo and no energy redistribution from day-to-night side. Table 1 summarizes the parameters of the planet and its very bright host star.

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2 The Extrasolar Planets Encyclopedia; http://www.exoplanet.eu.
Table 1. Parameters of the Star τ Boo and Its Planetary Companion

| Parameter | Value     | Error   | Ref. |
|-----------|-----------|---------|------|
| Star:     |           |         |      |
| Spectral type | F7 IV-V    |         | B97  |
| K (mag)   | 3.36      | 0.05    | VV09 |
| m∗ (M⊕)   | 1.33      | 0.11    | VF05 |
| R∗ (R⊙)   | 1.31      | 0.06    | G98  |
| T eff (K) | 6360      | 80      | G98  |
| P orb (d) | 3.31      |         | B06  |
| v sin i (km s⁻¹) | 14.9  | 0.5     | H00  |
| Age (Gyr) | 1.3       | 0.4     | VF05 |

Notes. Abbreviations for the references are: B06 = Butler et al. (2006) and references therein, B97 = Baliunas et al. (1997), G98 = Gonzalez (1998), H00 = Henry et al. (2000), VF05 = Valenti & Fischer (2005), and VV09 = van Belle & von Braun (2009).

We updated the orbital ephemerides by an RV-analysis of high-resolution UVES spectra of τ Boo published in Rodler et al. (2010).

The maximum possible RV semi-amplitude of the companion τ Boo b is calculated to be $K_{p,\text{max}} = 157.3 \pm 4.4$ km s⁻¹ via

$$K_{p,\text{max}} = \left(\frac{2\pi G m*}{P_{\text{orb}}}\right)^{1/3},$$

where $G$ is the gravitational constant, $m*$ is the stellar mass, and $P_{\text{orb}}$ is the orbital period. Due to the absence of transits in high-precision photometry (Henry et al. 2000), orbital inclinations larger than $i = 83°$ can be excluded. Baliunas et al. (1997) found that the star τ Boo rotates rapidly with a period commensurate with the orbital period of the planet, suggesting tidal locking. Catala et al. (2007) and Donati et al. (2008) carried out spectropolarimetric observations of τ Boo and measured differential rotation in the star, confirming that its rotation is synchronized with the orbital motion of the planet and suggesting an orbital inclination around 40°. Leigh et al. (2003) and Rodler et al. (2010) attempted to measure starlight reflected from τ Boo b, and found candidate features of marginal significance, indicating orbital inclinations of $i = 37°$ and $41°$, respectively. Under the assumption of a tidal lock and that the stellar equator and the orbital plane are co-aligned, Rodler et al. (2010) predicted an orbital inclination of $i \approx 46°$ and a planetary mass of $m_p \approx 5.6$ M⊕.

3. OBSERVATIONS AND DATA REDUCTION

We observed τ Boo during 5 hr on 2011 June 10, by using CRIRES (Kaeufl et al. 2004), mounted on the Very Large Telescope/UT1 on Cerro Paranal, Chile. We collected a total of 116 high-resolution spectra of our target plus 2 spectra of the A-type star HD 116160, which does not show any intrinsic absorption lines in the observed wavelength regime and therefore could be used for the calibration of our telluric model. The date of the observations was selected in such a way that the observations were carried out at orbital phases between $\phi = 0.55$ and 0.61 ($\phi = 0$ corresponds to the mid-transit position if $i \approx 90°$), when the hot day side of the planet facing the star was largely visible and consequently appeared bright in the NIR. In addition, based on the ephemerides in Table 1 and the value of $K_p$, we expected a variation of the RV of the companion up to 40 km s⁻¹ during the course of the observations.

The observations were carried out with the CRIRES standard setting of the order of 24 and a reference wavelength of $\lambda = 2.3252 \mu$m. We used the 0’2 slit to achieve a spectral resolution of $R = 100,000$. We made use of the AO system of CRIRES to minimize slit losses. Observing conditions were good, with seeing between 0’6 and 1’8. The observations were taken at two different nodding positions along the slit, with the intention to remove the faint OH lines in the sky background. We chose the integration times in such a way that the peak count rates per exposure were low (~4000 counts) to avoid nonlinear sensitivity in the four detectors.

The data were reduced with IRAF. All four detectors showed a pattern aligned with the reading direction. This pattern consisted of alternating rows or columns of larger and smaller intensities than the mean value and is called the odd–even effect. We applied a correction for the odd–even effect, which was most common in the data recorded with Detectors 1 and 4, for which the reading direction was perpendicular to the spectral dispersion. Since after this step strong noise features coming from those two detectors were still present in the data, we discarded those two detectors from any further analysis. The frames were taken in an A-A-B-B-B-B-A- sequence, where A and B denote the different nodding positions along the slit. For all frames as well as for each of each two remaining detectors, we combined the two consecutive frames, which had been taken at the same nodding position. This reduced the number of spectra to 58. Nodded images were then subtracted to remove sky background and dark current. White-light spectra obtained with the same instrumental configuration in the afternoon before and after the observations were used to flat-field the data. Using the aper task, we first identified and optimally centered the orders in the two individual nodding frames and traced these orders by adopting a second-order Legendre polynomial along the dispersion axis. We then extracted the one-dimensional spectra in Detectors 2 and 3 and calculated a second-order polynomial wavelength solution by adopting as a reference system the telluric lines present in the spectra. The vacuum wavelengths of the telluric lines were identified using the line-by-line radiative transfer model (LBLRTM) routine, which is based on the FASCODE algorithm (Clough et al. 1992). Detectors 2 and 3 covered the wavelength regions 2.303–2.317 μm and 2.319–2.332 μm, respectively, with a pixel size corresponding to $\approx 1.6$ km s⁻¹. We furthermore identified and removed obviously bad pixels in each spectrum coming from defects of the detector.

4. DATA ANALYSIS

4.1. Overview

The observed target spectra were heavily contaminated by telluric lines, and to much less of an extent, by the rotationally broadened stellar absorption lines of the host star. A crucial step of the data analysis was the removal of the telluric and stellar spectra, and the search for the planetary spectrum in

5. IRAF Project Home Page: http://iraf.noao.edu/.

4 An algorithm to correct this effect is provided at http://www.eso.org/sci/facilities/paranal/instruments/cires/tools/.
the residuals. In the following, we provide a description of the different data analysis steps.

4.2. Step 1: Determination of the Instrumental Profile

To calculate the instrumental profile (IP) of the spectrograph for each target observation, we made use of the telluric contamination, which dominated our data, and of the telluric model spectra (see Step 2). In contrast to the large number of telluric lines, the stellar spectrum of τ Boo exhibits very few absorption features in the observed wavelength regime, which appeared rotationally broadened due to the high $v \sin i$ (Table 1). Those regions of stellar absorption features were excluded from the determination of the instrumental profile. We normalized the spectra in such a way that the flux in the telluric/pseudo-stellar continuum was at one, and stored the photon noise error per spectral pixel. We then determined the IP to be the sum of seven Gaussian profiles in a similar way as described in Valenti et al. (1995): Around a central Gaussian, we grouped three satellite Gaussians on each side of it, which allowed us to account for asymmetries in the IP. Free parameters were the width of the central Gaussian, plus the amplitudes of the six satellite Gaussians, while the positions and the widths of those satellites were fixed and set a priori in a way that their half-widths overlapped. By employing a Brent algorithm, we finally determined the free parameters and convolved the telluric model spectrum with the IP. We found that for all spectra, the shape of the IP remained constant. However, the width of the IP was slightly different at each nodding position and also changed during the course of the night.

4.3. Step 2: Telluric Model

For the calculation of the atmospheric transmission spectrum, we used the LBLRTM code, which is available as a Fortran source code. As our molecular database, we adopted HITRAN (Rothman et al. 2005), which contains the 42 most prominent molecules and isotopes present in the atmosphere of the Earth. Following the approach presented by Seifahrt et al. (2010), we created a high-resolution theoretical vacuum-wavelength telluric spectrum for each observed spectrum by accounting for the air mass of the star as well as the weather conditions (water vapor density column, temperature and pressure profiles) during the observations. We retrieved the weather information from the Global Data Assimilation System (GDAS). GDAS models are available in 3 hr intervals for any location around the globe. We first calibrated the line depths of the telluric lines by using the A-star observations, which had been taken at the beginning of the night. For five water and methane lines, the line depths were systematically underestimated in the HITRAN model; for these lines, we consequently updated the abundances in our telluric model. In addition to that, the amount of water vapor in the atmosphere constantly changed during the observations, which resulted in variations of the line depths of the water lines in the observed spectra. Consequently, for each observed target spectrum, we created a set of two telluric model spectra, one for water and one for the other molecules, most notably CH$_4$. We then globally scaled the line depths for those two models for each target observation. Finally, we multiplied the two different high resolution telluric spectra, convoluted it with the IP to create the telluric model.

5. Source code and manuals are available under http://rtweb.aer.com/lblrtm_description.html.
6. GDAS Web site: http://ready.arl.noaa.gov/READYamet.php.
star, which depends on both the orbital phase \( \phi \), which was a priori known, and the unknown orbital inclination \( i \) as

\[
V_p = K_{p,\text{max}} \sin 2\pi \phi \sin i = K_p \sin 2\pi \phi.
\]

(2)

For all residual spectra, we then calculated the correlation value for different RV semi-amplitudes \( K_p \) of the planetary signal and finally determined the cross-correlation function (CCF) with respect to \( K_p \).

4.6. Step 5: Confidence Level

The confidence level of the strongest peak of the CCF was determined by employing a bootstrap randomization method (e.g., Kuerster et al. 1997). We assigned random values of the orbital phases to the observed spectra, thereby creating \( N \) different data sets. Any signal present in the original data was then scrambled in these artificial data sets. For all these randomized data sets, we again evaluated the model for the free parameter \( K_p \) and located the best fit with its specific CCF-peak value.

The confidence level of the CCF peak was estimated to be \( \approx 1 - m/N \), where \( m \) is the number of the best fit models having a CCF-peak value larger or equal than the maximum of the CCF found in the original, unscrambled data sets. Notice that we consider a detection to have a confidence of \( \geq 0.9987 \), which translates to \( \geq 3\sigma \).

5. RESULTS AND DISCUSSION

As illustrated in Figures 2 and 3, the results of our cross-correlation analysis using a CO-model spectrum reveal Doppler velocity shifts consistent with a maximum RV semi-amplitude for the planet of \( K_p = 115 \pm 11 \text{ km s}^{-1} \). The 1σ error bar contains both the actual error of the velocity measurement, which was determined via bootstrap resampling (Barrow et al. 1984), and the shift in velocity due to the uncertainties in the orbital solution. In addition to that, our bootstrap randomization analysis revealed that this signal is significant at the 3.4σ confidence level, with two false positives in 3000 trials.

The measured RV semi-amplitude corresponds to an orbital inclination for the system of \( i = 47^\circ_{\text{c}} \), deg. Adopting the measured orbital inclination, the value of the stellar mass in Table 1, and Kepler’s Laws of planetary motion, we finally are able to derive an absolute mass for the planet of \( m_p = 5.6 \pm 0.7 \text{ } M_{\text{Jup}} \). This value clearly confirms the planet hypothesis for the hot Jupiter \( \tau \) Boo b.

Given the precision of our data, possible residuals of the planetary spectrum in the stellar template, the lack of detailed atmospheric temperature-pressure profile models for this planet, and uncertainties in the possible level of masking between CO and CH\(_4\) (both molecules are expected to coexist in \( \tau \) Boo; e.g., Burrows & Sharp 1999), we cannot provide a reliable estimation of the CO abundance in the atmosphere of \( \tau \) Boo b. However, we can place a lower limit on the planet-to-star flux ratio in the observed wavelength range based on the atmospheric model we adopted. To this end, we created data sets which were based on our residual spectra. For each of these data sets, we injected an artificial planetary CO signal having an RV semi-amplitude of \( K_p = 115 \text{ km s}^{-1} \), with selected planet-to-star flux ratios from \( 10^{-2} \) down to \( 10^{-4} \). To avoid an overlapping of the CCF peaks with the real signal, we redshifted the spectrum of the injected planet by \( 50 \text{ km s}^{-1} \). For each data set, we then determined that peak of the CCF apart from the one of real signal and determined its confidence level. We find that with our data set and our CO-model, we are sensitive enough to detect a planet with planet-to-star flux ratio larger than \( \approx 7 \times 10^{-3} \) at the 3σ confidence level.

We emphasize that this measurement of the exact mass of \( \tau \) Boo b represents the first successful determination of the mass of a non-transiting planet by means of high-resolution spectroscopy. This technique therefore has the potential of providing direct masses and estimation of the atmospheric composition of non-transiting exoplanets in the near-future, in particular as new facilities like E-ELT become available.

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