Self-calibrating the gravitational shear–intrinsic ellipticity–intrinsic ellipticity cross-correlation

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ABSTRACT

We extend the 3-point intrinsic alignment self-calibration technique to the gravitational shear–intrinsic ellipticity–intrinsic ellipticity (GII) bispectrum. While significantly decreased from using cross-correlations instead of autocorrelation in a single photo-$z$ bin, the GII contamination persists in adjacent photo-$z$ bins and must be accounted for and removed from the lensing signal. The proposed technique will allow the measurement and removal of the GII intrinsic alignment contamination from the cross-correlation weak lensing signal. We relate the GII and galaxy density–intrinsic ellipticity–intrinsic ellipticity (gII) bispectra through use of the galaxy bias, and develop the estimator necessary to isolate the gII bispectrum from observations. We find that the GII self-calibration technique performs at a level comparable to that of the gravitational shear–gravitational shear–intrinsic ellipticity correlation (GGI) self-calibration technique, with measurement error introduced through the gII estimator generally negligible when compared to minimum survey error. The accuracy of the relationship between the GII and gII bispectra typically allows the GII self-calibration to reduce the GII contamination by a factor of 10 or more for all adjacent photo-$z$ bin combinations at $\ell > 300$. For larger scales, we find that the GII contamination can be reduced by a factor of 3–5 or more. The GII self-calibration technique is complementary to the existing GGI self-calibration technique, which together will allow the total intrinsic alignment cross-correlation signal in 3-point weak lensing to be measured and removed.

Key words: gravitational lensing: weak – cosmology: theory – large-scale structure of Universe.

1 INTRODUCTION

Weak gravitational lensing due to large-scale structure (cosmic shear) has become a promising source of cosmological information. A new generation of ground- and space-based surveys suited for precision weak lensing measurements have been developed with the importance of this new probe in mind. These ongoing, future and proposed surveys (e.g. CFHTLS, DES, EUCLID, HSC, HST, JWST, LSST, Pan-STARRS and WFIRST) promise to provide greatly improved measurements of cosmic shear using the shapes of up to billions of galaxies. Much work has been done to explore the potential of these cosmic shear measurements, which we review in Troxel & Ishak (2012a), for both the 2- and 3-point cosmic shear correlations.

Beyond the constraints obtained on cosmological parameters from the 2-point cosmic shear correlation and the corresponding shear power spectrum, the 3-point cosmic shear correlation and shear bispectra are able to break degeneracies between the cosmological parameters that
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the power spectrum alone does not (Takada & Jain 2003; Vafaei et al. 2010). The results of Takada & Jain (2004), for example, showed that the constraints on the dark energy parameters and the matter fluctuation amplitude should be able to be improved by a further factor of 2–3 using the bispectrum measured in a deep lensing survey. Most recently, parameter constraints were derived by Semboloni et al. (2010) using weak lensing data from the HiST COSMOS survey, measuring the third-order moment of the aperture mass measure. Their independent results were consistent with Wilkinson Microwave Anisotropy Probe 7 best-fitting cosmology and provided an improved constraint when combined with the 2-point correlation. The bispectrum also allows us to explore information about non-Gaussianity in the universe that is inaccessible at the 2-point level, providing constraints on the degree of non-Gaussianity in addition to the information on other cosmological parameters (see for example Mararrese, Verde & Jimenez 2000; Verde et al. 2001; Takada & Jain 2004; Jeong & Komatsu 2009; Hutero, Komatsu & Shandera 2010; Munshi et al. 2012, and references therein).

However, several systematic effects limit the precision of cosmic shear measurements, which must be accounted for in order to make full use of the potential of future weak lensing surveys (for a summary see Troxel & Ishak 2012a and references therein), and one of the serious systematic effects of weak lensing is the correlated intrinsic alignment of galaxy ellipticities, which act as a nuisance factor (see for example Croft & Metzler 2000; Catelan, Kamionkowski & Blandford 2001; Crittenden et al. 2001; Brown et al. 2002; Jing 2002; King & Schneider 2002, 2003; Heymans & Heavens 2003; Hirata & Seljak 2003, 2004; King 2005; Heymans et al. 2006; Mandelbaum et al. 2006; Bridle & King 2007; Hirata et al. 2007; Semboloni et al. 2008; Faltenbacher et al. 2009; Okumura & Jing 2009; Joachimi & Bridle 2010; Joachimi et al. 2010; Kirk, Bridle & Schneider 2010; Blazek, McQuinn & Seljak 2011; Krause & Hirata 2011; Troxel & Ishak 2012b, and references therein). The dark energy equation of state can be biased by as much as 50 per cent, for example, if intrinsic alignment is ignored (Bridle & King 2007; Joachimi & Bridle 2010). Hirata et al. (2007) found that the matter power spectrum amplitude can be affected by up to 30 per cent due to intrinsic alignment, demonstrating the importance of developing methods to isolate and remove the intrinsic alignment from the cosmic shear signal.

There are two 2-point intrinsic alignment correlations. The first is known as the intrinsic ellipticity–intrinsic ellipticity (II) correlation, between the ellipticities of two intrinsically aligned galaxies. The second, known as the gravitational shear–intrinsic ellipticity (GI) correlation, was identified by Hirata & Seljak (2004) and is due to a matter structure both causing the alignment of a nearby galaxy and contributing to the lensing signal of a background galaxy. The large-scale GI correlation was first reported by Mandelbaum et al. (2006) in the SDSS, with Hirata et al. (2007) finding an even stronger GI correlation for luminous red galaxies (LRGs). The authors showed that this contamination can affect the lensing measurement and cosmology by up to 10 per cent while affecting the matter fluctuation amplitude by up to 30 per cent. Heymans et al. (2006) confirmed this through numerical simulations, where a level of contamination of 10 per cent was found. The GI correlation was also measured in the SDSS data set by Faltenbacher et al. (2009) and Okumura & Jing (2009), and most recently, Joachimi et al. (2010) measured strong 2-point intrinsic alignment correlation in various SDSS and MegaZ-LRG samples.

Similarly, when we consider the 3-point correlation, the gravitational shear–gravitational shear–gravitational shear (GGG) bispectrum suffers from contamination by the 3-point intrinsic alignment correlations. The first correlation is between the intrinsic ellipticities of three spatially close galaxies which are intrinsically aligned by a nearby matter structure, known as the intrinsic ellipticity–intrinsic ellipticity–intrinsic ellipticity (III) correlation. The second is the gravitational shear–intrinsic ellipticity–intrinsic ellipticity (GII) correlation, where a matter structure which contributes to the lensing of a galaxy in the background also intrinsically aligns two spatially nearby galaxies. Finally, there is the gravitational shear–gravitational shear–intrinsic ellipticity (GGI) correlation, where a matter structure which intrinsically aligns a galaxy in the foreground also lenses two galaxies in the background. The sign of the GGI and GII correlations can depend both on triangle shape and scale. The 3-point intrinsic alignment correlations are represented diagrammatically in Fig. 1. It was shown in numerical simulations by Semboloni et al. (2008) that compared to the lensing spectrum, the lensing bispectrum is typically more strongly contaminated by galaxy intrinsic alignment up to 15–20 per cent compared to the GGG lensing signal.

Troxel & Ishak (2012c) demonstrated that the III and GII intrinsic alignment correlations can be greatly reduced with photo-z’s by using the cross-spectra of galaxies in two different redshift bins so that the galaxies are separated by large enough distances to assure that the tidal effect is weak. However, as shown in fig. 4 of Troxel & Ishak (2012c), while the III bispectrum is suppressed almost totally for adjacent, large redshift bins, the GII bispectrum is not. Thus, we propose below an extension to the GGI self-calibration technique (Troxel & Ishak 2012a) for the GII bispectrum. Significant work has been done in recent years towards measuring and removing the effect of galaxy intrinsic alignment on cosmological measurements, and we review these briefly. The 2-point intrinsic alignment correlations and methods for their removal have been well studied in the recent literature (see for example King & Schneider 2003; Hirata & Seljak 2004; King 2005; Bridle & King 2007; Joachimi & Schneider 2008, 2009, 2010; Joachimi & Bridle 2010; Kirk et al. 2010; Zhang 2010a,b). Using a geometrical approach, Shi, Joachimi & Schneider (2010) generalized the nulling technique to the 3-point GGI correlation by exploiting its redshift dependence, but it was found that the technique throws out some of the valuable lensing signal. Finally, we have recently generalized the approaches of Zhang (2010a,b) to develop a set of 3-point self-calibration techniques. We proposed using additional galaxy density (cross-)correlations which are already present in weak lensing survey measurements to self-calibrate the GGI cross-correlation in Troxel & Ishak (2012a), while the unique redshift dependences of the intrinsic alignment bispectra allowed us to self-calibrate the intrinsic alignment autocorrelations in Troxel & Ishak (2012c).

We propose here an extension to the GGI self-calibration technique of Troxel & Ishak (2012a), developing a technique to self-calibrate the GII cross-correlation bispectrum. While the impact of the GII cross-correlation on cosmological information is significantly less than the impact of the GGI cross-correlation, especially for widely separated redshift bin combinations, it still has a contribution to adjacent redshift bin combinations, which must be measured and removed if one hopes to achieve precision, systematic free bispectrum measurements. To do
Figure 1. The 3-point galaxy intrinsic alignment correlations. Blue galaxies are intrinsically aligned (I), while red galaxies are lensed (G). The view of the system on the sky is represented in the lower-right panels. Each preceding panel demonstrates the galaxy configuration at some distinct redshift such that \( z_i < z_j < z_k \). This, we develop a relationship between the GII and galaxy density–intrinsic ellipticity–intrinsic ellipticity (gII) bispectrum. We also devise an estimator to measure the gII bispectrum from the observed galaxy density–ellipticity–ellipticity bispectrum. We then discuss the performance of such a self-calibration technique, describing both measurement and systematic errors due to the self-calibration.

We organize the paper as follows. In Section 2, we briefly discuss the necessary survey parameters and lensing calculations. In Section 3, we develop the 3-point GII self-calibration. We first develop a relation between the GII and gII bispectra, which allows for the estimation and removal of the GII intrinsic alignment cross-correlation from the cosmic shear signal. We then establish an estimator to extract the galaxy density–density–intrinsic ellipticity correlation (ggI) from the observed galaxy density–density–ellipticity measurement for a photo-z galaxy sample. Section 4 describes the residual sources of error to the GII self-calibration technique, and we present the necessary relations to quantify these errors. Finally, we summarize the effectiveness and impact of the GII self-calibration in Section 5. We expand in Appendix A upon the detailed calculation of the coefficients in the error calculation found in Section 4.1 and provide a list of expected values.

2 BACKGROUND

The self-calibration technique proposed by Zhang (2010a) for the 2-point intrinsic alignment correlations and generalized by Troxel & Ishak (2012a) for the 3-point correlations makes use of the information already found in a lensing survey, including galaxy shape, angular position and photometric redshift, in order to calculate and remove the dominant intrinsic alignment contaminations. In evaluating the performance of the self-calibration technique, we will consider as an example survey parameters to match an LSST-like weak lensing survey (LSST Science Collaborations and LSST Project 2009), but of course the calculations are applicable to all current and planned weak lensing surveys (e.g. CFHTLS, DES, EUCLID, HSC, HST, JWST, LSST, Pan-STARRS and WFIRST). We divide galaxies into photo-z bins according to photo-z \( z^p \), where the \( i \)th photo-z bin has a range \( \bar{z}_i - \Delta z_i / 2 \leq z^p \leq \bar{z}_i + \Delta z_i / 2 \) for mean photo-z \( \bar{z}_i \). In this notation, \( i < j \) implies that \( \bar{z}_i < \bar{z}_j \). The galaxy redshift distribution over the \( i \)th redshift bin is \( n_i(z) \) and \( n_i(z) \) as a function of photo-z and true redshift, respectively. These are then related by a photo-z probability distribution function (PDF) \( p(z|z^p) \).

Our calculations assume that the survey will achieve a half sky coverage (\( f_{\text{sky}} = 0.5 \)) and a galaxy surface density of 40 arcmin\(^{-2}\) with the redshift density distribution of

\[
n(z) = \frac{1}{2z_0} \left( \frac{z}{z_0} \right)^2 \exp(-z/z_0),
\]

with \( z_0 = 0.5 \). The ellipticity shape noise is described by \( \gamma_{\text{im}} = 0.18 + 0.042z \) (Zhang 2010a) and the photo-z error by a Gaussian PDF of the form

\[
p(z|z^p) = \frac{1}{\sqrt{2\pi \sigma_z^2}} \exp \left( -\frac{(z - z^p)^2}{2\sigma_z^2} \right).
\]
with \( \sigma_\varepsilon = 0.05(1 + z) \). We construct photo-z redshift bins with width \( \Delta z = 0.2 \), centred at \( \bar{z}_i = 0.2(i + 1) \) \( (i = 1, \ldots, 9) \). Redshifts below \( z^p = 0.3 \) are excluded, not because of poor performance in the GII self-calibration technique, but rather due to the weaker lensing signal at low redshifts, which artificially inflates the fractional errors we evaluate in Section 4. These errors are measured with respect to the lensing signal, and thus lower photo-z bins are not useful in evaluating the true performance of the GII self-calibration.

The intrinsic alignment self-calibration techniques (GII and GGI) both rely upon two basic observables measured in a weak lensing survey: galaxy surface density and galaxy shape. The galaxy surface density, \( \delta \), is a function of the 3D galaxy distribution \( \delta_g \) in a given photo-z bin. The galaxy shape is expressed in terms of ellipticity, which measures the cosmic shear \( \gamma \). However, the intrinsic ellipticities of galaxies contaminate the cosmic shear. This intrinsic ellipticity has a random component, which is simple to correct for and which we include as part of the shot noise in the error estimations of Section 4. A second component to this intrinsic ellipticity is due to the correlated intrinsic alignment of galaxies and was introduced in Section 1. The measured shear can be labelled as \( \gamma_i = \gamma + \gamma^I \), where \( \gamma^I \) denotes the correlated intrinsic ellipticity due to intrinsic galaxy alignment. We are concerned only with the weak limit of gravitational lensing, so we can work with the lensing convergence \( \kappa \) instead. Thus from the measured \( \gamma_i \), we can obtain the convergence \( \kappa = \kappa + \kappa^I \).

We assume a standard, flat \( \Lambda \) cold dark matter universe in our calculations. The convergence \( \kappa \) of a source galaxy at comoving distance \( \chi_G \) and direction \( \hat{\theta} \) is then related in the Born approximation to the matter density \( \delta \) by the lensing kernel \( W_L(z', z) \),

\[
\kappa(\hat{\theta}) = \int_0^{\chi_G} \delta(\chi_L, \hat{\theta}) W_L(\chi_L, \chi_G) d\chi_L,
\]

where the lensing kernel in a flat cosmology is

\[
W_L(\chi_L, \chi_G) = \frac{3}{2} \Omega_m (1 + z_L) \chi_L \left( 1 - \frac{\chi_L}{\chi_G} \right).
\]

The convergence bispectrum is defined from \( \kappa \) as

\[
\langle \tilde{\kappa}(\ell_1) \tilde{\kappa}(\ell_2) \tilde{\kappa}(\ell_3) \rangle = (2\pi)^3 \delta^3(\ell_1 + \ell_2 + \ell_3) B_{\kappa \kappa \kappa}(\ell_1, \ell_2, \ell_3),
\]

where the ensemble average is denoted by \( \langle \ldots \rangle \) and \( \delta^3(\ell) \) is the Dirac delta function. \( \delta^3(\ell_1 + \ell_2 + \ell_3) \) enforces the condition that the three vectors form a triangle in Fourier space. Under the Limber approximation, we express the 2D angular cross-correlation bispectrum as

\[
B_{\kappa \kappa \kappa}^{\text{cross}}(\ell_1, \ell_2, \ell_3) = \int_0^{\chi_G} \frac{W_{\text{rad}}(\chi')}{\chi'^4} B_{\kappa \kappa \kappa}(k_1, k_2, k_3; \chi') d\chi',
\]

where when we consider the convergence bispectrum with \( \alpha = \beta = \gamma = G \), for example, \( B_{\kappa \kappa \kappa}(k; \chi') \) \( (\mu = \nu = \delta = 1) \) is the 3D matter bispectrum. However, more generally \( \alpha, \beta, \gamma \in \{G, I\} \), \( g \) and \( \lambda, \mu, \nu \in \{\delta_g, \delta_i, \delta_E\} \), with \( G (\delta) \) representing the lensing (matter overdensity), \( I (\delta^I) \) the intrinsic alignment and \( g (\delta_g) \) the galaxy density. The intrinsic alignment and galaxy bispectra are calculated as described below. The redshift is simply related through the Hubble parameter, \( H(z) \), to \( \chi \), and we can write the weighting function in terms of redshift as

\[
W_{\text{rad}}^{\text{red}}(z(\chi')) = W_i^n(z) W_i^G(z) W_i^g(z),
\]

\[
W_i^n(z) = W_i(z) = \int_0^{\chi_G} W_i(z', z) n_i(z') dz',
\]

\[
W_i^G(z) = W_i^g(z) = n_i(z).
\]

\( W_i^G(z) \) is simply the weighted lensing kernel for redshift bin \( i \), while \( W_i^g(z) = W_i^g(z) \) is the normalized galaxy distribution. The required lensing, intrinsic alignment and galaxy bispectra are calculated following Troxel & Ishak (2012a,b). A deterministic galaxy bias is assumed for the galaxy bispectra, and the galaxy intrinsic alignment signal is calculated using the fiducial parametrized model of Schneider & Bridle (2010, hereafter SB10), which is based on the halo model prescription. The SB10 model reduces by design to the linear alignment model (Hirata & Seljak 2004) at large scale, but aims for more motivated modelling of intrinsic alignment at small scales.

Following the fitting formula of Scoccimarro & Couchman (2001) with coefficients \( F_{22}^{\text{eff}}(k_1, k_2) \) described in section 2.4.3 of Takada & Jain (2004), we compute the 3D bispectrum due to non-linear gravitational clustering

\[
B_{\kappa \kappa \kappa}(k_1, k_2, k_3; \chi) = 2 F_{22}^{\text{eff}}(k_1, k_2) P_{\kappa \kappa}(k_1; \chi) P_{\kappa \kappa}(k_2; \chi) + 2 \text{perm.}
\]

We make a direct expansion of this method to approximate the 3D intrinsic alignment bispectra, using the intrinsic alignment power spectra instead of the non-linear matter power spectrum, where

\[
B_{\kappa \kappa \kappa}(k_1, k_2, k_3; \chi) = 2 F_{22}^{\text{eff}}(k_1, k_2) P_{\kappa \kappa}(k_1; \chi) P_{\kappa \kappa}(k_2; \chi) + 2 F_{22}^{\text{eff}}(k_2, k_3) P_{\kappa \kappa}(k_2; \chi) P_{\kappa \kappa}(k_3; \chi)
\]

\[
+ 2 F_{22}^{\text{eff}}(k_3, k_1) P_{\kappa \kappa}(k_3; \chi) P_{\kappa \kappa}(k_1; \chi)
\]

\[
B_{\text{galgal}}(k_1, k_2, k_3; \chi) = 2 F_{22}^{\text{eff}}(k_1, k_2) P_{\text{galgal}}(k_1; \chi) P_{\text{galgal}}(k_2; \chi) + 2 F_{22}^{\text{eff}}(k_2, k_3) P_{\text{galgal}}(k_2; \chi) P_{\text{galgal}}(k_3; \chi)
\]

\[
+ 2 F_{22}^{\text{eff}}(k_3, k_1) P_{\text{galgal}}(k_3; \chi) P_{\text{galgal}}(k_1; \chi)
\]

\[
B_{\kappa \kappa \kappa}(k_1, k_2, k_3; \chi) = 2 F_{22}^{\text{eff}}(k_1, k_2) P_{\kappa \kappa}(k_1; \chi) P_{\kappa \kappa}(k_2; \chi) + 2 \text{perm.}
\]

This treatment provides reasonable results for the intrinsic alignment bispectra.

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3 THE GII SELF-CALIBRATION TECHNIQUE

A lensing survey will capture the information necessary for several sets of correlations between the $\delta_b$ and $\kappa^s$ which can be constructed for galaxy triplets. Like the GGI self-calibration technique, the GII self-calibration requires only three of these observed correlations. The first is the angular cross-correlation bispectrum between galaxy ellipticities ($\kappa^s$) in the $i^{th}$, $j^{th}$ and $k^{th}$ redshift bins,

$$B_{ijk}^{\ell_{\delta\kappa}}(\ell_1, \ell_2, \ell_3) = B_{ijk}^{\delta\kappa\kappa}(\ell_1, \ell_2, \ell_3) + \gamma_{ijk} B_{ijk}(\ell_1, \ell_2, \ell_3) + (2 \text{ perm.}) + B_{ijk}^{\delta\kappa\kappa}\text{(perm.)} + B_{ijk}^{\kappa\kappa\kappa}(\ell_1, \ell_2, \ell_3).$$

(14)

Unless catastrophic photo-z errors overwhelm the data, we can safely neglect the III cross-correlation, which is negligible for thick photo-z bins, by selecting galaxy triplets where $i < j < k$. Though the impact of the GII correlation under these conditions was also neglected in Troxel & Ishak (2012a) due to being greatly diminished for cross-correlations, it can still impact the bispectrum for adjacent bins and should be taken into account if the goal is to make a precise measurement of the total intrinsic alignment contamination. For bin combinations which are not adjacent, this GII term can again be safely neglected and the GGI self-calibration is sufficient. Under the requirement that $i < j < k$, we find that $B_{ijk}^{(2)} \gg B_{ijk}^{(1)}$, $B_{ijk}^{(3)}$ due to the lensing geometry, where $B_{ijk}^{(1)}$ and $B_{ijk}^{(3)}$ can only exist due to photo-z uncertainty, and will be negligible compared to $B_{ijk}^{\delta\kappa\kappa}$ except in surveys with a large fraction of catastrophic photo-z error. We then have for $i < j < k$,

$$B_{ijk}^{\ell_{\delta\kappa}}(\ell_1, \ell_2, \ell_3) \approx B_{ijk}^{\delta\kappa\kappa}(\ell_1, \ell_2, \ell_3) + \gamma_{ijk} B_{ijk}(\ell_1, \ell_2, \ell_3) + (2 \text{ perm.}) + B_{ijk}^{\delta\kappa\kappa}(\ell_1, \ell_2, \ell_3).$$

(15)

The contribution from the GII bispectrum $B_{ijk}^{\delta\kappa\kappa}(\ell_1, \ell_2, \ell_3)$ ($i < j < k$) is typically very small and in some cases effectively zero. The GII self-calibration technique, which seeks to calculate and remove the GII cross-correlation which survives in adjacent photo-z bins, then acts as a correction to the GGI self-calibration, which is the only intrinsic alignment contamination that survives for non-adjacent photo-z bin combinations. We will denote the GII bispectrum as $B_{ijk}^{\delta\kappa\kappa}$ in order to preserve the association of each quantity $G$ or $I$ with its redshift bin.

The second observable is the angular cross-correlation bispectrum between convergence ($\kappa^s$) in the $i^{th}$ and $j^{th}$ redshift bins and the galaxy density ($\delta_b$) in the $k^{th}$ redshift bin. The self-calibration requires the case where $i = j = k$,

$$B_{iik}^{\ell_{\delta\kappa}}(\ell_1, \ell_2, \ell_3) = B_{iik}^{\delta\kappa\kappa}(\ell_1, \ell_2, \ell_3) + \gamma_{iik} B_{iik}(\ell_1, \ell_2, \ell_3) + (2 \text{ perm.}) + B_{iik}^{\delta\kappa\kappa}(\ell_1, \ell_2, \ell_3).$$

(16)

This correlation contributes further information about the intrinsic alignment of galaxies.

The final observable is measured in the angular cross-correlation bispectrum between galaxy density ($\delta_b$) in the $i^{th}$, $j^{th}$ and $k^{th}$ redshift bins for $i = j = k$, giving

$$B_{iik}^{\ell_{\delta\kappa}}(\ell_1, \ell_2, \ell_3) = B_{iik}^{\delta\kappa\kappa}(\ell_1, \ell_2, \ell_3).$$

(17)

We also require for the GII self-calibration results from both the GII cross-correlation and intrinsic alignment autocorrelation self-calibration techniques (Zhang 2010a,b). We have neglected thus far the contribution of magnification bias to these measurements. This was discussed and justified for the 3-point measurements in section 4.3 of Troxel & Ishak (2012a) and was shown to be negligible. There is also a non-Gaussian contribution to the observed bispectra, which is also neglected as discussed in section 4.4 of Troxel & Ishak (2012a).

Our GII self-calibration technique calculates and removes the GII contamination in equation (15) through the measurements from equations (16) and (17), which are both available in the same lensing survey. The fractional contamination of the correlated intrinsic alignment to the lensing signal is expressed as

$$f_{ijk}^{(\delta\kappa\kappa)}(\ell_1, \ell_2, \ell_3) = B_{ijk}^{\delta\kappa\kappa}(\ell_1, \ell_2, \ell_3) / B_{ijk}^{\delta\kappa\kappa}(\ell_1, \ell_2, \ell_3).$$

(18)

For the self-calibration to work, the contamination $f_{ijk}^{(\delta\kappa\kappa)}(\ell_1, \ell_2, \ell_3)$ must be sufficiently large as to contribute a detectable $B_{ijk}^{\delta\kappa\kappa}(\ell_1, \ell_2, \ell_3)$ at the corresponding $\ell$ bins to $B_{ijk}^{\delta\kappa\kappa}(\ell_1, \ell_2, \ell_3)$. We denote this threshold by $f_{ijk}^{\text{thresh}}$. When $f_{ijk}^{(\delta\kappa\kappa)} \geq f_{ijk}^{\text{thresh}}$, the GII self-calibration can be applied to reduce the GII contamination. The residual error after the GII self-calibration will be expressed as a residual fractional error in the lensing measurement. We differentiate $f_{ijk}$ as statistical error and $\delta f_{ijk}$ as systematic error, as in the discussion of the GGI self-calibration. The performance of the GII self-calibration will then be quantified by the parameters $f_{ijk}^{\text{thresh}}$, $\Delta f_{ijk}$ and $\delta f_{ijk}$, which are discussed and calculated in Section 4. For parallelism, we preserve the notation from Troxel & Ishak (2012a) in most cases, though it is essential to note that the quantities are often not the same in each technique.

3.1 Relating $B_{ijk}^{\delta\kappa\kappa}$ and $B_{ijk}^{\delta\kappa\kappa}$

In order to self-calibrate the GII bispectrum, we must first determine the relationship between $B_{ijk}^{\delta\kappa\kappa}$ and $B_{ijk}^{\delta\kappa\kappa}$. We follow the same general approach as for the GGI bispectrum, relating the two by use of a deterministic galaxy bias $b_{z,k}$ (Fry & Gaztanaga 1993) such that the smoothed galaxy density is a function of matter density expressed as

$$\delta_b(x; \chi) = b_{z,k}(\chi) \delta_m(x; \chi) + \frac{b_{z,k}(\chi)}{2} \delta_m^2(x; \chi) + O(\delta^3).$$

(19)

The linear galaxy bias ($b_{z,k}$) was used by Zhang (2010a) for the 2-point correlations. In addition, $b_{z,k}$ represents the first-order non-linear contribution, $b_{z,k}$ is typically expected to be negative and $\leq b_{z,k}$ (Cooray & Sheth 2002), and it is insufficient to model the bias as simply scale dependent as in the 2-point case (Jeong & Komatsu 2009). Following Troxel & Ishak (2012a), we use this expression for the galaxy density to relate $B_{iik}^{\delta\kappa\kappa}$ to $B_{iik}^{\delta\kappa\kappa}$. We neglect the portion of the bispectrum due to primordial non-Gaussianity and the trispectrum term, which
contains further information about the non-Gaussianity. This was justified and discussed further in section 4.4 of Troxel & Ishak (2012a), and it results in the relationship
\[
B_{ij}^{(g)}(k_1, k_2, k_3; \chi) = b_\chi \langle (\chi)B_{ij}^{(g)}(k_1, k_2, k_3; \chi) \\
+ b_\chi (\chi) b_\chi (\chi) \left[ P_{ij}(k_1; \chi) P_{ij}(k_2; \chi) + P_{ij}(k_2; \chi) P_{ij}(k_3; \chi) + P_{ij}(k_3; \chi) P_{ij}(k_1; \chi) \right] \right].
\] (20)

If the galaxy bias changes slowly over the ith redshift bin with median comoving distance \( \chi_i \), we can write to a good approximation \( b_\chi = b_\chi (\chi_i) \). We can further approximate \( B(k_1, k_2, k_3; \chi) \approx B(k_1, k_2, k_3; \chi_i) \) and \( P(k; \chi) \approx P(k; \chi_i) \) in the limit where the comoving distance distribution of galaxies in the ith redshift bin is narrow, and substituting equation (20) into Limber’s approximation for \( B_{ij}^{(g)} \) and comparing to \( B_{ij}^{(g)} \), we have the approximations
\[
B_{ij}^{(g)}(\ell_1, \ell_2, \ell_3) \approx \frac{\Pi_{ij}}{\chi_i^4} \left( b_\chi^{(i)} B_{ij}^{(g)}(k_1, k_2, k_3; \chi_i) \right.)
+ \frac{b_\chi^{(i)} b_\chi^{(i)}}{2} \left[ P_{ij}(k_1; \chi_i) P_{ij}(k_2; \chi_i) + P_{ij}(k_2; \chi_i) P_{ij}(k_3; \chi_i) + P_{ij}(k_3; \chi_i) P_{ij}(k_1; \chi_i) \right] \right) \right)
\] (21)

and
\[
B_{ij}^{(g)}(\ell_1, \ell_2, \ell_3) \approx \frac{W_{ij}(\ell_1, \ell_2, \ell_3)}{b_\chi^{(i)} \Pi_{ij}} B_{ij}^{(g)}(\ell_1, \ell_2, \ell_3) \approx \frac{b_\chi^{(i)} W_{ij}(\ell_1, \ell_2, \ell_3)}{\chi_i^4} \times \left[ P_{ij}(k_1; \chi_i) P_{ij}(k_2; \chi_i) + P_{ij}(k_2; \chi_i) P_{ij}(k_3; \chi_i) + P_{ij}(k_3; \chi_i) P_{ij}(k_1; \chi_i) \right] \right).
\] (23)

In order to express the 3D power spectra in equation (23) as 2D spectra, we will use the approximations \( C_{ij}^{(i)}(\ell) \approx P_{ij}(k; \chi_i) \frac{n_i^2(\chi)}{\chi_i^4} \) and \( C_{ij}^{(i)}(\ell) \approx P_{ij}(k; \chi_i) \frac{n_i^2(\chi)}{\chi_i^4} \), where \( \Pi_{ii} = \int_0^\infty n_i^2(\chi) d\chi \). Equation (23) is then
\[
B_{ij}^{(g)}(\ell_1, \ell_2, \ell_3) \approx \frac{W_{ij}(\ell_1, \ell_2, \ell_3)}{b_\chi^{(i)} \Pi_{ij}} B_{ij}^{(g)}(\ell_1, \ell_2, \ell_3) \approx \frac{b_\chi^{(i)} W_{ij}(\ell_1, \ell_2, \ell_3)}{\chi_i^4} \left[ C_{ij}^{(i)}(\ell_1) C_{ij}^{(i)}(\ell_2) + (b_\chi^{(i)})^{-1} C_{ij}^{(i)}(\ell_1) C_{ij}^{(i)}(\ell_3) + C_{ij}^{(i)}(\ell_1) C_{ij}^{(i)}(\ell_3) \right].
\] (24)

This expression now relates \( B_{ij}^{(g)} \) to \( B_{ij}^{(g)} \), allowing us to identify the GII bispectrum in the observable \( B^{(2)} \). Like the similar expression for the GGI self-calibration, it is necessary to have information about the gl and II power spectra obtained from the 2-point self-calibration techniques (Zhang 2010a,b).

### 3.2 \( B_{ij}^{(g)} \) estimator

We can measure \( B_{ij}^{(g)} \) through the information contained within the observable \( B^{(2)} = B_{ij}^{(g)} + B_{ij}^{(g)} + B_{ij}^{(g)} \). To measure it directly, we must first remove the contamination of the geometry-dependent \( B_{ij}^{(g)} + B_{ij}^{(g)} \), which is not useful for the GII self-calibration. Lensing geometry simply requires eliminating those triplets of galaxies where the redshift of the galaxy used to measure the ellipticity is lower than those used to measure galaxy number density in the case of a spectroscopic galaxy sample. In this way, those triplets remaining have no contamination from lensing and measure only \( B_{ij}^{(g)} \). However, for a photo-z galaxy sample, the typically large photo-z error prevents us from directly employing this method. Photo-z error causes a true redshift distribution of width \( \pm 2\sigma_p = 0.1(1+z) \) even for a photo-z bin with width \( \Delta z \rightarrow 0 \). In practice, photo-z bin widths are typically \( \geq 0.2 \). It is possible with such photo-z errors for galaxy triplets in the ith redshift bin to provide a measurable lensing contribution even when \( i < j, k \), except for the special cases where the redshift or both the photo-z error and bin size are limited to sufficiently low values. A general photo-z galaxy sample then requires a more careful approach when separating \( B_{ij}^{(g)} \) from \( B_{ij}^{(g)} + B_{ij}^{(g)} \).

In order to construct such an estimator, we first consider the orientation dependence of the two components. We define a redshift for each galaxy in the triplet: \( z_G, z_G, z_I, z_I \) or \( z_G \) for the galaxies used in the lensing/intrinsic alignment measurement and \( z_G \) for the galaxy used in the number density measurement. The gII correlation is independent of the relative position of the three galaxies. For example, the correlations with \( z_1 < z_2 < z_3, z_2 < z_1 < z_3, \) or \( z_3 < z_2 < z_1 \) are statistically identical when the sides of the triangle are fixed. However, the GgG and GgI correlations do depend on the relative position of the three galaxies. Due to the lensing geometry dependence, the correlation with \( z_G, z_G, z_I < z_G \) is statistically smaller than other orientations.

This dependence provides two observables from \( B_{ij}^{(g)} \). The first is \( B_{ij}^{(g)} \), which counts only those triplets with \( z_G, z_G, z_I < z_G \). This weighting is denoted by the subscript ‘S’. This ordering is necessarily different from that employed in the GGI self-calibration. From our previous discussion, we then have \( B_{ij}^{(g)} = B_{ij}^{(g)} \) and \( B_{ij}^{(g)} + B_{ij}^{(g)} + B_{ij}^{(g)} \) for \( B_{ij}^{(g)} = B_{ij}^{(g)} \) and \( B_{ij}^{(g)} \) and \( B_{ij}^{(g)} \) have different signs, and despite \( B_{ij}^{(g)} \) being more strongly suppressed, \( B_{ij}^{(g)} \) is the dominant contributor on both sides of the inequality, forcing it to hold in general.
dependence which had been previously neglected. This ratio describes the suppression of the signal
for equilateral triangles ($\ell_1 = \ell_2 = \ell_3$) over three redshift bins spanning the survey range. The expected values of $Q_{\text{GG}}$ are similar to those found for the GGI self-calibration, though with more $\ell$ dependence. This is primarily due to the greater complexity found in $Q_{\text{GG}}$, as the sum of two components instead of one. The suppression ratio is dependent on the redshift bin chosen, increasing with redshift due to increased photo-z error at higher redshift. Generally, $Q \approx 0.4$, and the significant deviation from unity ensures that the estimator $B_{\text{GG}}$ is valid for lensing surveys of interest.

We now define the suppression ratio

\[
Q_{\text{GG}}(\ell_1, \ell_2, \ell_3) = \frac{B_{\text{GG}}^{\ell_1|\ell_2, \ell_3}(\ell_1, \ell_2, \ell_3) + B_{\text{GG}}^{\ell_2|\ell_1, \ell_3}(\ell_1, \ell_2, \ell_3) + B_{\text{GG}}^{\ell_3|\ell_1, \ell_2}(\ell_1, \ell_2, \ell_3)}{B_{\text{GG}}^{\ell_1, \ell_2, \ell_3}(\ell_1, \ell_2, \ell_3)},
\]

where we have explicitly included the $\ell$ dependence which had been previously neglected. This ratio describes the suppression of the signal due to the weighting of triplets described for the subscript 'S'. By definition $0 < Q_{\text{GG}} < 1$, with $Q_{\text{GG}} = 0$ if the photo-z is perfectly accurate and $Q_{\text{GG}} = 1$ if the photo-z has no correlation with the true redshift. $Q_{\text{GG}}$ is calculated using the galaxy redshift distribution, which is discussed in Section 3.3.

The definition of $Q_{\text{GG}}(\ell_1, \ell_2, \ell_3)$ possesses an explicit dependence on the intrinsic alignment, which in principle would make the estimator dependent on the intrinsic alignment model. However, as we discuss in Section 3.3, we find that for an LSST-like survey, $B_{\text{GG}}^{\ell_1, \ell_2, \ell_3}$ is large enough compared to $B_{\text{GG}}^{\ell_1|\ell_2, \ell_3}$ that we can approximate $Q_{\text{GG}}(\ell_1, \ell_2, \ell_3) \approx B_{\text{GG}}^{\ell_1|\ell_2, \ell_3} / B_{\text{GG}}^{\ell_1, \ell_2, \ell_3}$ to very high accuracy. We can thus treat $Q_{\text{GG}}(\ell_1, \ell_2, \ell_3)$ as independent of the intrinsic alignment model for sufficiently deep surveys.

We now define the estimator for $B_{\text{GG}}^{\ell_1, \ell_2, \ell_3}$, which we denote by $\hat{B}_{\text{GG}}^{\ell_1, \ell_2, \ell_3}$, in terms of $Q_{\text{GG}}(\ell_1, \ell_2, \ell_3)$ and the two observables

\[
B_{\text{GG}}^{\ell_1|\ell_2, \ell_3}(\ell_1, \ell_2, \ell_3) = B_{\text{GG}}^{\ell_1|\ell_2, \ell_3}(\ell_1, \ell_2, \ell_3) + B_{\text{GG}}^{\ell_2|\ell_1, \ell_3}(\ell_1, \ell_2, \ell_3) + B_{\text{GG}}^{\ell_3|\ell_1, \ell_2}(\ell_1, \ell_2, \ell_3),
\]

\[
B_{\text{GG}}^{\ell_1, \ell_2, \ell_3}(\ell_1, \ell_2, \ell_3) = B_{\text{GG}}^{\ell_1, \ell_2, \ell_3}(\ell_1, \ell_2, \ell_3) + B_{\text{GG}}^{\ell_2, \ell_3|\ell_1}(\ell_1, \ell_2, \ell_3) + B_{\text{GG}}^{\ell_3, \ell_1|\ell_2}(\ell_1, \ell_2, \ell_3). \tag{26}
\]

This estimator is

\[
\hat{B}_{\text{GG}}^{\ell_1, \ell_2, \ell_3}(\ell_1, \ell_2, \ell_3) = \frac{B_{\text{GG}}^{\ell_1|\ell_2, \ell_3}(\ell_1, \ell_2, \ell_3) - Q_{\text{GG}}(\ell_1, \ell_2, \ell_3)B_{\text{GG}}^{\ell_2, \ell_3|\ell_1}(\ell_1, \ell_2, \ell_3)}{1 - Q_{\text{GG}}(\ell_1, \ell_2, \ell_3)}.
\]

As expected, when $Q_{\text{GG}} = 0$ this gives $\hat{B}_{\text{GG}}^{\ell_1, \ell_2, \ell_3} = B_{\text{GG}}^{\ell_2, \ell_3|\ell_1}$ as for a spectroscopic galaxy sample with no photo-z error. However, $Q_{\text{GG}}$ must not approach unity, where $\hat{B}_{\text{GG}}^{\ell_1, \ell_2, \ell_3}$ is singular. For the LSST-like survey described in Section 2, we calculate $Q_{\text{GG}}$ for various redshift bins following the procedure described in Section 3.3. This result is given in Fig. 2 for equilateral triangles, where we find $Q_{\text{GG}} \approx 0.4$ and, in general, that $Q_{\text{GG}}$ should deviate significantly from unity. The estimator $\hat{B}_{\text{GG}}^{\ell_1, \ell_2, \ell_3}$ is thus expected to be applicable in any typical lensing survey.

3.3 Evaluating $Q_{\text{GG}}(\ell_1, \ell_2, \ell_3)$

The ratio $Q_{\text{GG}}$ in equation (25) must first be evaluated in order to employ the estimator $\hat{B}_{\text{GG}}^{\ell_1, \ell_2, \ell_3}$. This mirrors the derivation in section 3.3 of Troxel & Ishak (2012a), which we will summarize here as it applies to $Q_{\text{GG}}$. We begin from the real space angular correlation functions $w^{\text{GG}}(\theta_1, \theta_2, \theta_3; \zeta_G, \zeta_G, \zeta_G)$ and $w^{\text{GG}}(\theta_1, \theta_2, \theta_3; \zeta_G, \zeta_G, \zeta_G)$. Taking the average correlation, we express this in terms of the ensemble average and calculate the associated bispectra. For the correlations with galaxy triplets weighted by the subscript 'S', we define the statistical weighting.
functions as
\[ \eta(z_1, z_2, z_g) = \frac{3 \int dz_1^P \int dz_2^P \int dz_g^P \int_0^\infty dz_G W_L(z_1, z_g, z_2) N_P^G S \left( z_1^P, z_2^P, z_g^P \right)}{\int dz_1^P \int dz_2^P \int dz_g^P \int_0^\infty dz_G W_L(z_1, z_g, z_2) N_P^G}, \]  
(28)
\[ \eta'(z_1, z_2) = \frac{3 \int dz_1^P \int dz_2^P \int dz_g^P \int_0^\infty dz_G W_L(z_1, z_g, z_2) N_P^G S \left( z_1^P, z_2^P, z_g^P \right)}{\int dz_1^P \int dz_2^P \int dz_g^P \int_0^\infty dz_G W_L(z_1, z_g, z_2) N_P^G}, \]  
(29)
where
\[ N_P^G = p \left( z_G | z_1^P \right) p \left( z_1 | z_1^P \right) n_P^G (z_1^P) n_P^G (z_2^P) n_P^G (z_g^P). \]  
(30)
\[ N_P^G = p \left( z_G | z_2^P \right) p \left( z_2 | z_2^P \right) n_P^G (z_1^P) n_P^G (z_2^P) n_P^G (z_g^P). \]  
(31)
and \( S(z_1^P, z_2^P, z_g^P) = 1 \) if \( z_1^P, z_2^P < z_1^P, z_2^P < z_g^P \) is and otherwise. Since \( S(\ldots) \) allow only 1/3 of the integral to survive, \( \eta \) and \( \eta' \) are normalized by a factor of 3 in order to remove the suppression due to the selection function and measure only that due to the lensing geometry.

We can now express directly the bi-spectra necessary to compute \( Q_{\text{GII}} \).
\[ B_{\text{GII}}(\ell_1, \ell_2, \ell_3) = \int_0^\infty B_{\text{GII}}^G(k_1, k_2, k_3; \chi) W_L(\chi) n_1^G(\chi) \chi^4 d\chi \]  
(32)
\[ B_{\text{GII}}^G(\ell_1, \ell_2, \ell_3) = \int_0^\infty B_{\text{GII}}^G(k_1, k_2, k_3; \chi) W_L(\chi) n_1^G(\chi) \chi^4 d\chi \]  
(33)
and
\[ B_{\text{GII}}^G \left|_S \right( \ell_1, \ell_2, \ell_3) = \int_0^\infty B_{\text{GII}}^G(k_1, k_2, k_3; \chi) W_L(\chi) n_1^G(\chi) \chi^4 \eta(\chi, \chi(z_1) = \chi, \chi(z_2) = \chi) d\chi \]  
(34)
\[ B_{\text{GII}}^G \left|_S \right( \ell_1, \ell_2, \ell_3) = \int_0^\infty B_{\text{GII}}^G(k_1, k_2, k_3; \chi) W_L(\chi) n_1^G(\chi) \chi^4 \eta(\chi, \chi(z_2) = \chi) d\chi. \]  
(35)

The ratio \( Q_{\text{GII}} \) is defined through equations (33) and (35) and is shown in Fig. 2. For the deep survey we are considering, we find that we can approximate to very high accuracy \( Q_{\text{GII}} \approx \eta' \), where \( \eta' \) is the mean value of \( \eta \) across the \( i \)th redshift bin. This is because for a deep survey, \( B_{\text{GII}}^G \) is much larger than \( B_{\text{GII}}^G \), making the contribution from \( \eta \) negligible. In the limit where photo-z error dominates, \( \sigma_P \gg \Delta z \), and so \( \eta, \eta' \rightarrow 1 \). In this limit, the estimator \( B_{\text{GII}}^G \) becomes singular and \( B_{\text{GII}}^G \) can no longer be differentiated from \( B_{\text{GII}}^G + B_{\text{GII}}^G \). In the opposite limit, where \( \sigma_P \ll \Delta z \), \( \eta, \eta' \rightarrow 0 \), where our estimator mirrors the extraction method for \( B_{\text{GII}}^G \) in spectroscopic galaxy samples.

The impact of catastrophic photo-z errors should enter the GII self-calibration most strongly in the calculation of the components of \( \eta \) and \( \eta' \). The estimation of the impact of catastrophic photo-z outliers in the determination of \( Q_{\text{GII}} \) is then a test of the self-calibration against photo-z outliers. Catastrophic photo-z error was discussed by Zhang (2010a) as it relates to the 2-point GI self-calibration, but the methods to control its impact apply to the GII self-calibration as well. To quantify the effect of catastrophic photo-z error in the GII self-calibration, we employ a Gaussian outlier distribution as described in Troxel & Ishak (2012c) for the PDF with a fraction of outlier galaxies \( p_{\text{cat}} = 10 \) per cent, which is the required level for LSST and similar lensing surveys (LSST Science Collaborations and LSST Project 2009). We find that the impact of these photo-z outliers is 1–2 per cent for the lowest photo-z bins and negligible for higher redshift bins. This is due to both the numerator and denominator of \( \eta \) and \( \eta' \) being affected in similar ways, which strongly suppresses the effect of non-negligible outliers on the determination of \( Q_{\text{GII}} \).

4 PERFORMANCE OF THE GII SELF-CALIBRATION

We will quantify the performance of the GII self-calibration technique using the survey parameters described in Section 2. This includes both a statistical measurement error introduced through the estimator \( B_{\text{GII}}^G \), which propagates into the final measurement of \( B_{\text{GII}}^G \) and thus of \( B_{\text{GII}}^G \), and a systematic error due to inaccuracy in the scaling relation between \( B_{\text{GII}}^G \) and \( B_{\text{GII}}^G \). We will also summarize other possible sources of error which might impact the performance of the self-calibration, though a more detailed account can be found in Troxel & Ishak (2012a).

4.1 The estimator \( B_{\text{GII}}^G \)

The estimator \( B_{\text{GII}}^G \) introduces a statistical error into the measurement of \( B_{\text{GII}}^G \) and thus of \( B_{\text{GII}}^G \). In order to quantify the accuracy of the estimator \( B_{\text{GII}}^G(\ell_1, \ell_2, \ell_3) \), we consider the contribution of measurement errors such as shot noise and shape noise in \( B_{\text{GII}}^G(\ell_1, \ell_2, \ell_3) \) which propagate into our measurement of \( B_{\text{GII}}^G(\ell_1, \ell_2, \ell_3) \) through the estimator. For a given redshift bin, we calculate the rms error, working in a pixel space with \( N_P \), sufficiently fine and uniform pixels of photo-z \( z_P^P \) and angular position \( \theta_\omega \). The measured overdensity is given by \( \delta_\omega + \delta_N^P \), and the measured ‘shear’ is given by \( \kappa_\omega + \kappa_N^P \), where ‘N’ represents the measurement noise. From equation (26), we construct the pixel
space angular bispectra

\[ B^{(2)}(\ell_1, \ell_2, \ell_3) = N_p^{-3} \sum_{\alpha \beta \gamma} \left[ \delta_{\alpha} + \delta_{\beta} + \delta_{\gamma} \right] \left[ \kappa_{\beta} + \kappa_{\gamma} \right] \left[ \kappa_{\beta} + \kappa_{\gamma} \right] \exp \left[ i \left( \ell_1 \cdot \theta_a + \ell_2 \cdot \theta_b + \ell_3 \cdot \theta_c \right) \right]. \]

\[ B^{(2)}(\ell_1, \ell_2, \ell_3) = N_p^{-3} \sum_{\alpha \beta \gamma} \left[ \delta_{\alpha} + \delta_{\beta} + \delta_{\gamma} \right] \left[ \kappa_{\beta} + \kappa_{\gamma} \right] \left[ \kappa_{\beta} + \kappa_{\gamma} \right] \exp \left[ i \left( \ell_1 \cdot \theta_a + \ell_2 \cdot \theta_b + \ell_3 \cdot \theta_c \right) \right] \]

\( S_{\alpha \beta \gamma} = 1 \) when \( z_{\alpha}^2 + z_{\beta}^2 + z_{\gamma}^2 \) and is zero otherwise. Thus in the limit \( N_p \gg 1 \), \( S_{\alpha \beta \gamma} = N_p^3/3 \) and the average \( S_{\alpha \beta \gamma} = 1/3 \).

From our definition of the estimator in equation (27), we can construct the difference

\[ \frac{B_{\text{II}}^{\text{HI}} - B_{\text{II}}^{\text{AB}}}{(1 - Q_{\text{GII}})} = N_p^{-3} \sum_{\alpha \beta \gamma} \left[ \delta_{\alpha} + \delta_{\beta} + \delta_{\gamma} \right] \left[ \kappa_{\beta} + \kappa_{\gamma} \right] \left[ \kappa_{\beta} + \kappa_{\gamma} \right] \exp \left[ i \left( \ell_1 \cdot \theta_a + \ell_2 \cdot \theta_b + \ell_3 \cdot \theta_c \right) \right] \]

\( \times \left( \delta_{\alpha} + \delta_{\beta} + \delta_{\gamma} \right) \left( \kappa_{\beta} + \kappa_{\gamma} \right) \left( \kappa_{\beta} + \kappa_{\gamma} \right) - (1 - Q_{\text{GII}}) \delta_{\alpha} \kappa_{\beta} \kappa_{\gamma} \]

\( = N_p^{-3} \sum_{\alpha \beta \gamma} \left[ \delta_{\alpha} + \delta_{\beta} + \delta_{\gamma} \right] \left( \kappa_{\beta} + \kappa_{\gamma} \right) \left( \kappa_{\beta} + \kappa_{\gamma} \right) \exp \left[ i \left( \ell_1 \cdot \theta_a + \ell_2 \cdot \theta_b + \ell_3 \cdot \theta_c \right) \right] \]

\[ \times \left( \delta_{\alpha} + \delta_{\beta} + \delta_{\gamma} \right) \left( \kappa_{\beta} + \kappa_{\gamma} \right) \left( \kappa_{\beta} + \kappa_{\gamma} \right) - (1 - Q_{\text{GII}}) \delta_{\alpha} \kappa_{\beta} \kappa_{\gamma} \].

In the second line of equation (37), we have used the approximation \( S_{\alpha \beta \gamma} = 1/3 \) for large \( N \) and that the gII correlation does not depend on the relative position of the galaxy triplets in order to incorporate the term \((1 - Q_{\text{GII}}) \delta_{\alpha} \kappa_{\beta} \kappa_{\gamma} \) into the primary term which is multiplied by \( 3S_{\alpha \beta \gamma} - Q_{\text{GII}} \). We can now write the rms error in a similar way to equation 41 of Troxel & Ishak (2012a) and simplify the resulting 256 6-point correlations which arise from expanding equation (37). We apply Wick’s theorem, which allows us to express each 6-point correlation as 15 products of three 2-point correlations. This results in 3840 products, most of which are zero. For example, any correlation between signal and noise or between dissimilar noise terms vanishes. Further, due to the angular dependence of the correlations \( \langle A_i B_i \rangle = w_{\alpha \beta \gamma} (\theta_a - \theta_b) \), only the correlations with \( (A_i B_i) \) where \( a \in \alpha, \beta, \gamma \) and \( b \in \lambda, \mu, v \) are non-vanishing. This leaves 124 surviving products in the rms error expression

\[ \left( \Delta B_{\text{II}}^{\text{HI}} \right)^2 = \frac{1}{\left(1 - Q_{\text{GII}}\right)} N_p^{-6} \sum_{\alpha \beta \gamma} \sum_{\alpha \beta \gamma} \exp \left[ i \left( \ell_1 \cdot \theta_a + \ell_2 \cdot \theta_b + \ell_3 \cdot \theta_c \right) \right] \exp \left[ i \left( \ell_1 \cdot \theta_a + \ell_2 \cdot \theta_b + \ell_3 \cdot \theta_c \right) \right] \]

\[ \times \left( \delta_{\alpha} + \delta_{\beta} + \delta_{\gamma} \right) \left( \kappa_{\beta} + \kappa_{\gamma} \right) \left( \kappa_{\beta} + \kappa_{\gamma} \right) \exp \left[ i \left( \ell_1 \cdot \theta_a + \ell_2 \cdot \theta_b + \ell_3 \cdot \theta_c \right) \right] \]

\( \times \left( \delta_{\alpha} + \delta_{\beta} + \delta_{\gamma} \right) \left( \kappa_{\beta} + \kappa_{\gamma} \right) \left( \kappa_{\beta} + \kappa_{\gamma} \right) - (1 - Q_{\text{GII}}) \delta_{\alpha} \kappa_{\beta} \kappa_{\gamma} \]

\( = \frac{1}{\left(1 - Q_{\text{GII}}\right)} N_p^{-6} \sum_{\alpha \beta \gamma} \sum_{\alpha \beta \gamma} \exp \left[ i \left( \ell_1 \cdot \theta_a + \ell_2 \cdot \theta_b + \ell_3 \cdot \theta_c \right) \right] \exp \left[ i \left( \ell_1 \cdot \theta_a + \ell_2 \cdot \theta_b + \ell_3 \cdot \theta_c \right) \right] \]

\( \times \left( \delta_{\alpha} + \delta_{\beta} + \delta_{\gamma} \right) \left( \kappa_{\beta} + \kappa_{\gamma} \right) \left( \kappa_{\beta} + \kappa_{\gamma} \right) \exp \left[ i \left( \ell_1 \cdot \theta_a + \ell_2 \cdot \theta_b + \ell_3 \cdot \theta_c \right) \right] \]

\( \times \left( \delta_{\alpha} + \delta_{\beta} + \delta_{\gamma} \right) \left( \kappa_{\beta} + \kappa_{\gamma} \right) \left( \kappa_{\beta} + \kappa_{\gamma} \right) - (1 - Q_{\text{GII}}) \delta_{\alpha} \kappa_{\beta} \kappa_{\gamma} \].

Noises only correlate at zero lag \( (\delta_{\beta}^2 \delta_{\gamma}^2) \propto \delta_{\alpha \beta \gamma} \), \( (\kappa_{\beta} \kappa_{\gamma}) \propto \delta_{\alpha \beta \gamma} \), and the correlations not involving \( \kappa \) depend only on separation, not on the relative orientation of the galaxy pairs along the line of sight. However, correlations like \( \langle \kappa \delta \rangle \) and \( \langle \kappa \kappa \rangle \) are dependent on the relative orientation and must be treated with care when evaluating equation (38). In order to quantify this orientation dependence, we apply the suppression ratio \( Q_{GII} \equiv Q_2 \) (Zhang 2010a; Troxel & Ishak 2012a)

\[ Q_{GII} = \left( \frac{C_{GII}^{\text{HI}}}{\left| C_{GII}^{\text{HI}} \right|} \right) \]

\[ and Q_{GII} \]

\( \langle \delta_{\alpha} \kappa_{\beta} \rangle \rightarrow \frac{1}{2} \left( \frac{S_{\delta \kappa}}{\left(1 - Q_{GII}\right)} + \frac{S_{\delta \kappa}}{Q_{GII}} \right) \langle \delta_{\alpha} \kappa_{\beta} \rangle \]

\[ \langle \kappa_{\beta} \kappa_{\mu} \rangle \rightarrow \frac{1}{2} \left( \frac{S_{\kappa \kappa}}{\left(1 - Q_{GII}\right)} + \frac{S_{\kappa \kappa}}{Q_{GII}} \right) \langle \kappa_{\beta} \kappa_{\mu} \rangle. \]
The suppression ratio $Q_{IG} \approx Q_{GG}$ is defined in an identical way to $Q_{GG}$, but for the $C_{IG}$ power spectrum. We can now evaluate equation (38) analytically, converting it to its Fourier representation

$$ \left( \Delta B_{ii}^{eG} \right)^2 = 2 \left[ \left( C_{GG} + C^{II} \right) C_{II}^{GG} K_1 + C_{GG} \left( \left( C_{GG} + 2C^{II} \right) \left( C_{EE} + C_{EE}^{r}a_1 \right) + 2C_{EE}^{r}C_{EE}^{g} \right) ight. $$

$$ + C_{II}^{r}C_{II}^{g} K_2 + C_{GG} \left( C_{EE} K_1 + C_{EE}^{r} K_3 + C_{GG}^{r} \left( C_{KK} + C_{EE}^{r} K_6 \right) \right) $$

$$ + C_{GG} \left( C_{EE} K_7 + C_{EE}^{r} K_8 + C_{GG}^{r} C_{EE}^{g} K_9 + C_{GG}^{r} C_{EE}^{g} K_{10} + C_{GG}^{r} \left( C_{II} K_{11} + C_{EE}^{r} K_{12} \right) \right) $$

$$ + C_{GG}^{r} \left[ C_{GG}^{r} \left( C_{II} + C_{EE}^{r} e_1 \right) + C_{II}^{g} C_{EE}^{g} \left( C_{II} K_5 + C_{EE}^{r} K_6 \right) \right. $$

$$ + C_{II}^{g} C_{II}^{g} K_1 + C_{GG}^{r} C_{II}^{g} K_4 \right\} . $$

(41)

The details of this calculation and the coefficients $K_1 - K_{14}$ and $a_1, c_1$ and $e_1$ are included in Appendix A.

The final rms error $\Delta B_{iij}^{eG}$ evaluated for a given triangle with bin width $\Delta \ell$ is then given by

$$ \left( \Delta B_{iij}^{eG} \right)^2 = \frac{4 \pi^2}{\ell_1 \ell_2 \ell_3 \Delta \ell_1 \Delta \ell_2 \Delta \ell_3 f_{ijk}^{\text{sys}}} \left\{ \left( C_{GG} + C^{II} \right) C_{II}^{GG} K_1 + C_{GG} \left( \left( C_{GG} + 2C^{II} \right) \left( C_{EE} + C_{EE}^{r} a_1 \right) + 2C_{EE}^{r} C_{EE}^{g} \right) \right. $$

$$ + C_{II}^{r} C_{II}^{g} K_2 + C_{GG} \left( C_{EE} K_1 + C_{EE}^{r} K_3 + C_{GG}^{r} \left( C_{KK} + C_{EE}^{r} K_6 \right) \right) $$

$$ + C_{GG} \left( C_{EE} K_7 + C_{EE}^{r} K_8 + C_{GG}^{r} C_{EE}^{g} K_9 + C_{GG}^{r} C_{EE}^{g} K_{10} + C_{GG}^{r} \left( C_{II} K_{11} + C_{EE}^{r} K_{12} \right) \right) $$

$$ + C_{GG}^{r} \left[ C_{GG}^{r} \left( C_{II} + C_{EE}^{r} e_1 \right) + C_{II}^{g} C_{EE}^{g} \left( C_{II} K_5 + C_{EE}^{r} K_6 \right) \right. $$

$$ + C_{II}^{g} C_{II}^{g} K_1 + C_{GG}^{r} C_{II}^{g} K_4 \right\}. $$

(42)

$C_{EE}^{r} = 1/\bar{n}_i$ and $C_{GG}^{r} = \gamma_{mm}/\bar{n}_i$, where $\bar{n}_i$ is the average number density of galaxies in the $i$th redshift bin. The statistical error $\Delta B_{iij}^{eG}$ differs in several key ways from the statistical error $\Delta B_{iij}^{GG}$ in the GGI self-calibration, both in the complexity of its calculation due to the additional $\kappa$ term and the resulting components, which include terms like $C_{IG}^{r}$. It is more sensitive to the intrinsic alignment contamination than in the $Ig$ and 2-point cases, but is still safe from strong dependence in the limit where $B_{iij}^{GG}$ is dominant.

The errors $\Delta B_{iij}$ and $\Delta C_{ii}^{GG}$ (Zhang 2010a) propagate into the measurement of $B_{iij}^{eG}$ through equation (24). To find the fractional error $\Delta f_{ijk}^{\text{sys}}$ which induces the in the lensing bispectrum, we simply scale $B_{iij}^{eG}$ by the factor $f_{ijk}^{\text{sys}}$ such that $f_{ijk}^{\text{sys}} = f_{ijk}^{\kappa} \Delta B_{iij}^{eG}$. This error is equal to $f_{ijk}^{\text{thresh}}$, the minimum intrinsic alignment $f_{ijk}^{\kappa}$ which can be detected through the self-calibration with signal-to-noise of 1 or $\Delta B_{iij}^{eG} = B_{iij}^{eG}$. Thus, both the residual statistical error in the measurement of $C_{GG}^{GG}$ and the lower limit at which the intrinsic alignment can be calculated and removed with the self-calibration are represented by $f_{ijk}^{\text{thresh}} = f_{ijk}^{\kappa} \Delta f_{ijk}^{\kappa}$. Thus, the GGI self-calibration technique can turn a systematic contamination $f_{ijk}^{\kappa}$ of the lensing signal into a statistical error $\Delta f_{ijk}^{\kappa} < f_{ijk}^{\kappa}$, which is insensitive to the original intrinsic alignment contamination.

We show in Fig. 3 $\Delta f_{ijk}^{\kappa}$ for the survey parameters described in Section 2. Compared to the minimum survey error as found in Troxel & Ishak (2012a), $\Delta f_{ijk}^{\kappa}$ is negligible for most scales, only becoming comparable for some photo-z bin combinations at very large scales.

### 4.2 The accuracy of the $B_{iij}^{eG} - B_{iij}^{eG}$ relation

In addition to the statistical error introduced through the estimator $\hat{B}_{iij}^{eG}$, there is a systematic error which is introduced by equation (24), which relates the intrinsic alignment contamination $B_{iij}^{eG}$ in the lensing bispectrum to other survey observables. The accuracy of equation (24) is quantified by

$$ \epsilon_{ijk}^{\text{sys}} = \left( \frac{W_{ijk} B_{ijk}^{eG}(\ell_1, \ell_2, \ell_3)}{\hat{B}_{ijk}^{eG}(\ell_1, \ell_2, \ell_3)} - \frac{b_{ijk}^{\kappa}}{b_{ijk}^{\kappa}} \right) \frac{1}{\Pi_{ii}^{\kappa}} \Pi_{ii}^{\kappa} \left( f_{ijk}^{\text{thresh}}(\ell_1, \ell_2, \ell_3) \right) $$

$$ \times \left[ \left( \Pi_{kk}^{\kappa}(\ell_1) C_{II}^{g}(\ell_2) + (b_{ijk}^{\kappa})^{-1} C_{II}^{g}(\ell_1) C_{II}^{g}(\ell_3) \right) \right]^{-1} . $$

(43)

This induces a residual systematic error in the lensing measurement of $\delta f_{ijk} = \epsilon_{ijk}^{\text{sys}} f_{ijk}^{\kappa}$. $\epsilon_{ijk}^{\text{sys}}$ is evaluated numerically and shown in Fig. 4 for equilateral triangles and a variety of neighbouring photo-z bin choices. We neglect totally non-adjacent photo-z bin combinations, as the GII signal is truly negligible in such cases. The accuracy of equation (24) reflects the differences between $B_{iij}^{eG}$ and $B_{iij}^{GG}$. The accuracy of equation (24) depends primarily on the mean redshift of the photo-z bins chosen, becoming more accurate at higher redshifts where the intrinsic alignment is less strong. By comparison, the accuracy of the equivalent scaling relation for the GGI self-calibration shows strong tendencies towards the effects of the lensing kernel, since the lensing contribution to the signal is much stronger. Equation (24) is accurate to within $\sim 30$ per cent for all scales and photo-z bin combinations. However, for most
Figure 3. The residual statistical uncertainty \( \Delta f_{ijk}^{\text{stat}} \) for equilateral triangles \((\ell = \ell_1 = \ell_2 = \ell_3)\) in the \( B_{ijk}^{\text{BG}} \) measurement and threshold of intrinsic alignment contamination \( f_{ijk}^{\text{thresh}} \) at which the GII self-calibration technique can calculate and remove the intrinsic alignment contamination at S/N = 1 are plotted for a variety of redshift bin combinations. At large \( \ell \), we see the effects of shot noise beginning to take over. Generally, \( \Delta f_{ijk}^{\text{stat}} \) is less than the minimum survey error expected for such a survey and is thus negligible. We expect this result to hold for non-equilateral triangles as well, but the use of the GII self-calibration is limited by our understanding of non-Gaussian effects for very elongated triangle shapes, as discussed in Troxel & Ishak (2012a), and we leave the discussion of its applicability for these very elongated triangle shapes to a future work.

scales and photo-z bin choices, it is accurate to within 10 per cent. This is comparable to the accuracy found in the GGI self-calibration, and we expect the GII self-calibration to be capable of reducing the GII intrinsic alignment contamination by a factor of 10 or so for scales smaller than \( \ell = 300 \). At very small scales, however, the assumptions in the galaxy bias model we have employed tend to break down, as we discuss in Section 4.3 (see also Troxel & Ishak 2012a). However, we do not expect significant error due to the galaxy bias model over the scales shown in Fig. 4, up to \( \ell \approx 2000 \). These results are insensitive to the original intrinsic alignment contamination, such that for any \( f_{ijk}^{\text{thresh}} < f_{ijk}^I < 1 \), the GII self-calibration will reduce the GII contamination down to survey limits or by a factor of 10 or so, whichever is less, for all but a few photo-z bin choices at large scales. The impact of the systematic on the measurement of \( B_{\text{GGG}} \) is significantly less, however, as it is scaled by \( f_{ijk}^I \), which is typically expected to be of the order of 10–20 per cent. This would lead to an actual systematic error on the percent level.

4.3 Other sources of uncertainty

The GII self-calibration suffers from many additional potential sources of uncertainty, including uncertainties in galaxy bias modelling, limitations in the models used for the intrinsic alignment and bispectrum calculations, magnification bias effects and the effects of non-Gaussianity on the bispectrum. Troxel & Ishak (2012a) provide detailed calculations which compare the order at which magnification and non-Gaussian effects, as well as uncertainties in the galaxy bias model, might impact the self-calibration for the GGI bispectrum. While not all of these calculations apply directly to the GII self-calibration, it is trivial to replicate them following Troxel & Ishak (2012a). They also address a range of other possible factors which might influence the self-calibration, including for example cosmological uncertainties and catastrophic photo-z errors. In all cases, they find that the dominant impact on the performance of the self-calibration comes from the statistical and systematic errors described in Sections 4.1 and 4.2. We find that this holds for the GII self-calibration as well, with the exception of uncertainty in the galaxy bias parameters, which becomes comparable to the statistical measurement error in \( B_{\text{BGG}} \) at large scales.

In addition to non-Gaussianity and uncertainties in the galaxy bias, catastrophic photo-z errors and stochasticity of the galaxy bias and intrinsic alignment are primary concerns for the accuracy of the self-calibration. We discuss the impact of photo-z outliers on the determination of \( Q_{\text{GII}} \) in Section 3.3, but they also have an impact on the relationship between \( B_{ijk}^{\text{BG}} \) and \( B_{iii}^{\text{BG}} \), which is of similar magnitude. Stochasticity in the galaxy bias or intrinsic alignment is more difficult to quantify and less understood, particularly any correlation between the galaxy...
stochasticity and the intrinsic alignment (Albrecht et al. 2009). However, recent work has indicated that the effects of galaxy stochasticity may be reduced to the 1 per cent level up to $k \sim 1 \, h \, \text{Mpc}^{-1}$ (Baldauf et al. 2010), which would impact the self-calibration at the level of 0.01 $f_{ijk}^I$. This would be safely negligible compared to other sources of error like the systematic error in the relationship between $B_{ijk}^{IIG}$ and $B_{ijk}^{III}$. The effects of catastrophic photo-z errors and stochasticity on the self-calibration techniques, including methods to minimize their impact, are further discussed in Zhang (2010a) and Troxel & Ishak (2012a).

### 4.4 Summary of residual errors

The performance of the GII self-calibration can be summarized under three regimes, which are defined by the magnitude of the GII contamination as represented by $f_{ijk}^I$. The first is where the GII correlation is too small to detect in $B^{(2)}$, with $f_{ijk}^I \leq f_{ijk}^{I\text{thresh}}$. If the intrinsic alignment cannot be detected in $B^{(2)}$, the GII self-calibration is not applicable. This generally means that the GII contamination is also negligible when compared to $\epsilon_{ijk}^{I\text{max}}$, the minimum statistical error in the lensing bispectrum, and there is no need to correct for it. This is likely true for all totally non-adjacent photo-z bin choices, where the GII signal is naturally negligible as discussed in Troxel & Ishak (2012c).

However, the GII contamination to the lensing bispectrum is not likely negligible if $f_{ijk}^I > f_{ijk}^{I\text{thresh}}$, and it must be corrected for. The GII self-calibration is now able to detect and calculate the GII cross-correlation. In the second regime, where $\Delta f_{ijk}^{I\text{thresh}} > \epsilon_{ijk}^{I\text{max}} f_{ijk}^I$, the statistical error $\Delta f_{ijk}^{I\text{max}}$ induced by the measurement error in the estimator $\hat{B}_{ijk}^{II}$ is dominant. This error is generally negligible when compared to $\epsilon_{ijk}^{I\text{max}}$, and so in this regime, the GII self-calibration should perform at the statistical limit of the lensing survey.

Where $\Delta f_{ijk}^{I\text{thresh}} < \epsilon_{ijk}^{I\text{max}} f_{ijk}^I$, the systematic error $\delta f_{ijk}^I = \epsilon_{ijk}^{I\text{max}} f_{ijk}^I$ due to the relationship between $B_{ijk}^{IIG}$ and $B_{ijk}^{III}$ in equation (24) is dominant. In the case where $\epsilon_{ijk} < \epsilon_{ijk}^{I\text{max}} f_{ijk}^I$, $\epsilon_{ijk}^{I\text{max}}$ is still dominant. Otherwise, the GII self-calibration can suppress the GII contamination by a factor of 10 or so for all but a few photo-z bin choices at the largest scales. In this case, other complementary techniques could be employed to further reduce the GII contamination down to the statistical limit for the lensing survey.

For example, one such case has been explored by Zhang (2010b) for the 2-point correlations, but such studies of the 3-point intrinsic alignment are left to be carried out. Zhang, Pen & Bernstein (2010) combine the GI self-calibration with a photo-z self-calibration to better protect the GI self-calibration against catastrophic photo-z effects. Both methods are possible because the GI and GII/GGI self-calibrations use primarily those correlations in one redshift bin to estimate the intrinsic alignment, while Zhang (2010b) and Zhang et al. (2010) use those

---

**Figure 4.** The inaccuracy of the relationship between $B_{ijk}^{IIG}$ and the observable $B_{ijk}^{II}$ is quantified in equation (43) by $\epsilon_{ijk}^{I\text{max}}$. The dominant systematic error in the measurement of $B_{ijk}^{IIG}$ through the GII self-calibration technique is due to this inaccuracy. For equilateral triangles ($\ell = \ell_1 = \ell_2 = \ell_3$), $\epsilon_{ijk}^{I\text{max}}$ is plotted for several sets of adjacent redshift bins. We neglect totally non-adjacent photo-z bin combinations, as the GII signal is naturally negligible in such cases. Equation (24) is accurate to within $\sim 30$ per cent for all scales and photo-z bin combinations. However, for most scales and photo-z bin choices, it is accurate to within 10 per cent. This is comparable to the accuracy found in the GII self-calibration, and we expect the GII self-calibration to be capable of reducing the GII intrinsic alignment contamination by a factor of 10 or so in general. These results are insensitive to the original intrinsic alignment contamination, such that for any $f_{ijk}^{I\text{thresh}} < f_{ijk}^I < 1$, the self-calibration will reduce the GII/GGI contamination down to survey limits or by a factor of 10 or so, whichever is less, for all but a few photo-z bin choices at large scales.
correlations between redshift bins. Others have also used information between redshift bins to calibrate the intrinsic alignment contamination in the 2- and 3-point correlations (Joachimi & Schneider 2008, 2009; Okumura & Jing 2009; Joachimi & Bridle 2010; Kirk et al. 2010; Shi et al. 2010). Such techniques for the 3-point intrinsic alignment correlations should eventually complement the GII and GGI self-calibration techniques for improved reductions in the contamination by the intrinsic alignment in the cosmic shear signal, but further exploration is necessary in order to jointly apply these complementary techniques to realistic survey conditions.

5 CONCLUSION

The 3-point intrinsic alignment correlations (GGI, GII, III) are expected to strongly contaminate the galaxy lensing bispectrum at up to the 20 per cent level. Troxel & Ishak (2012c) showed that while the III correlation can be safely neglected by considering only the cross-correlation bispectrum between three different photo-z bins, the GII cross-correlation remains a contaminant for adjacent bins in addition to the GGI cross-correlation and thus must be considered in any self-calibration of adjacent photo-z bin combinations. Troxel & Ishak (2012a) first generalized the self-calibration technique to the bispectrum in order to calculate and remove the 3-point GGI contamination from the GGG bispectrum. In this work we extend the self-calibration to the 3-point GII cross-correlation in order to measure and remove its remaining contamination from adjacent bin triplets.

In order to do this, we establish the estimator $\hat{b}_{\text{III}}$ to extract the GII correlation from the galaxy ellipticity–ellipticity–density measurement for a photo-z galaxy sample. This estimator is expected to be generally applicable to weak lensing surveys and reduces to the simple extraction method for spectroscopic galaxy samples at low photo-z errors. We then develop a scaling relation between the GII and GGI bispectra using the linear and non-linear galaxy biases to relate the galaxy density and cosmic shear measurements. We can then calculate and remove the GII correlation from the GGG bispectrum. While this method is in principle applicable to all $\ell$ and triangle shapes, we maintain the modest restrictions of Troxel & Ishak (2012a) on very elongated triangles due to the effects of non-Gaussianity and at very non-linear scales due to limitations in the understanding of the galaxy bias model used. Combining the GII and GGI self-calibration techniques will then allow a complete removal of the 3-point intrinsic alignment contamination from the cosmic shear signal.

The performance of the GII self-calibration technique is also quantified for a typical weak lensing survey. The residual statistical error due to measurement uncertainty in the estimator $\hat{b}_{\text{III}}$ is shown to be generally negligible when compared to the minimum measurement error in the lensing bispectrum. We consider the systematic error introduced by the relationship between $\hat{b}_{\text{III}}$ and $\hat{b}_{\text{III}}$, showing that $|\epsilon_{ijk}| < 0.3$ for all photo-z bin choices and all scales, except that for the very largest scales, $|\epsilon_{ijk}| < 0.1$. The self-calibration technique can then reduce the GII contamination by a factor of 10 or more for all adjacent photo-z bin combinations at $\ell > 300$. For larger scales, we find that the GII contamination can be reduced by a factor of 3–5 or more. However, at very small scales beyond those shown ($\ell \approx 2000$) the assumptions in the galaxy bias model used break down, which hinders the performance of the self-calibration. This will potentially allow the GII self-calibration to reduce the GII correlation to the statistical limit of the lensing survey, as discussed in Section 4.4.

These results are not strongly sensitive to the original intrinsic alignment contamination, such that for any $f_{ijk}^{\text{thresh}} < f_{ijk}^l < 1$, the GII self-calibration can reduce the GII contamination down to survey limits or by a factor of 10 or so, whichever is less, for all but the largest scales. This is comparable to the GGI self-calibration, where for any $f_{ijk}^{\text{thresh}} < f_{ijk}^l < 1$, it can reduce the GII contamination down to survey limits or by a factor of 10 or greater for most photo-z bin choices, whichever is less. We thus expect the GII self-calibration to perform well with the GGI self-calibration, and together they promise to be an efficient technique to isolate the total 3-point intrinsic alignment signal from the cosmic shear measurement.

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APPENDIX A: CALCULATION OF COEFFICIENTS IN $\Delta B^\text{III}_{\gamma\delta}$

When evaluating the sum and converting equation (38) to Fourier space, the products of the correlations each have a numerical coefficient due to the restrictions on redshift ordering. Many, however, are identical due to symmetries, and others are numerically equivalent when specific suppression ratios are chosen. The calculation of the unique coefficients $K_i - K_{14}$ and $a_1$, $c_1$, $e_1$ in equations (41) and (42) is summarized here.

The coefficients $K_i - K_{14}$ are simply collections of other coefficients, as shown below:

\[
\begin{align*}
K_1 &\equiv a_1 + b_1 \\
K_2 &\equiv a_2 + b_2 + 2c_2 \\
K_3 &\equiv d_2 + e_2 + f_2 + g_2 \\
K_4 &\equiv h_2 + i_2 + j_2 + k_2 \\
K_5 &\equiv a_1 + b_1 \\
K_6 &\equiv c_1 + d_1 \\
K_7 &\equiv g_3 + h_3 \\
K_8 &\equiv i_3 + j_3 \\
K_9 &\equiv a_4 + b_4 + c_4 + d_4 \\
K_{10} &\equiv c_3 + d_3 + e_3 + f_3 \\
K_{11} &\equiv h_2 + n_2 + a_2 + (j_2 + q_j)/2 \\
K_{12} &\equiv r_2 + s_2 + t_2 + u_2 \\
K_{13} &\equiv k_3 + l_3 \\
K_{14} &\equiv l_2 + m_2 + q_2 + r_2.
\end{align*}
\]

From these, we group the coefficients by the number of orientation-dependent correlations; for example, $\langle S \delta \kappa \rangle$ are involved in their calculation. The first coefficient is trivial, due to products with no noise correlations or orientation-dependent correlations. We then calculate

\[
\frac{N_P^{-6}}{(1 - Q_{\text{GII}})^2} \sum_{\Delta p} \sum_{\Sigma \mu \nu} (3S_{\mu \nu} - Q_{\text{GII}}) (3S_{\mu \nu} - Q_{\text{GII}}) \approx 1. \tag{A1}
\]

For the following terms, each is calculated as in the case of equation (A1), but limited by some ordering restriction due to a noise or orientation-dependent correlation.
For those terms in equations (41) and (42) with no orientation-dependent correlations, there exist five unique coefficients:

\[ a_1 = 1 + \frac{7}{20(1 - Q_{GII})^2} \]
\[ b_1 = 1 - \frac{7}{40(1 - Q_{GII})^2} \]
\[ c_1 = 1 + \frac{1}{8(1 - Q_{GII})^2} \]
\[ d_1 = 1 + \frac{1}{8(1 - Q_{GII})^2} \]
\[ e_1 = 1 + \frac{1}{2(1 - Q_{GII})^2} \]

The values of the coefficients \( a_1-e_1 \) as well as the specific restrictions on each due to noise correlations are summarized in Table A1. Noises only correlate at zero lag, so correlations of noise such as \( \langle k_{ij} S_i \rangle \) introduce a restriction in the form of the Kronecker delta \( \delta_{ij} \).

For those terms in equations (41) and (42) with one orientation-dependent correlation, there exist 21 unique coefficients:

\[ a_2 = 1 + \frac{29 - 18Q_{GII}}{40(1 - Q_{GII})^2} - \frac{11 - 6Q_{GII}}{8(1 - Q_{GII})} \]
\[ b_2 = 1 + \frac{17 + 6Q_{GII}}{40(1 - Q_{GII})^2} - \frac{11 - 6Q_{GII}}{8(1 - Q_{GII})} \]
\[ c_2 = 1 + \frac{49 - 18Q_{GII}}{80(1 - Q_{GII})^2} - \frac{11 - 6Q_{GII}}{8(1 - Q_{GII})} \]
\[ d_2 = 1 + \frac{61 - 42Q_{GII}}{80(1 - Q_{GII})^2} - \frac{1}{1 - Q_{GII}} \]
\[ e_2 = 1 + \frac{20(1 - Q_{GII})^2}{7 + 6Q_{GII}} - \frac{1}{1 - Q_{GII}} \]
\[ f_2 = 1 + \frac{19 + 4Q_{GII}}{80(1 - Q_{GII})^2} - \frac{1}{1 - Q_{GII}} \]
\[ g_2 = 1 + \frac{13 - 6Q_{GII}}{20(1 - Q_{GII})^2} - \frac{1}{1 - Q_{GII}} \]
\[ h_2 = 1 + \frac{3(1 + 7Q_{GII})}{20(1 - Q_{GII})^2} - \frac{1}{1 - Q_{GII}} \]
\[ i_2 = 1 + \frac{3(7 + 4Q_{GII})}{40(1 - Q_{GII})^2} - \frac{1}{1 - Q_{GII}} \]
\[ j_2 = 1 + \frac{3(2 + 5Q_{GII})}{20(1 - Q_{GII})^2} - \frac{1}{1 - Q_{GII}} \]

| Coefficient | Value   | Restrictions       |
|-------------|---------|--------------------|
| \( a_1 \)   | 1.97    | \( \delta_{\alpha\beta}; \delta_{\rho\mu}; \delta_{\gamma\nu} \) |
| \( b_1 \)   | 0.54    | \( \delta_{\rho\mu}; \delta_{\gamma\nu} \) |
| \( c_1 \)   | 1.35    | \( \delta_{\alpha\beta}; \delta_{\rho\mu}; \delta_{\alpha\gamma}; \delta_{\beta\nu}; \delta_{\rho\nu} \) |
| \( d_1 \)   | 3.43    | \( \delta_{\alpha\beta}; \delta_{\rho\mu}; \delta_{\gamma\nu} \) |
| \( e_1 \)   | 2.39    | \( \delta_{\alpha\beta}; \delta_{\rho\mu}; \delta_{\gamma\nu} \) |

The restrictions on each due to noise correlations are summarized in Table A1. In addition to noise correlations, orientation-dependent correlations such as \( \langle k_{ij} S_i \rangle \) introduce a restriction in the form of equation (40). We have introduced the shorthand

\[ \chi_{ij}^{AB} ≡ \langle S_{ij}/(1 - Q_{AB}) + S_{ji}/Q_{AB} \rangle / 2 \]

for convenience.

Similarly, for those terms with two orientation-dependent correlations, there exist 12 unique coefficients:

\[ a_3 = 1 - \frac{3(-24 - 41Q_{GII} + 50Q_{GII}^2)}{80(1 - Q_{GII})^2} - \frac{37 - 13Q_{GII} - 2Q_{GII}^2}{20(1 - Q_{GII})} \]
\[ b_3 = 1 + \frac{64 - 27Q_{GII} + 28Q_{GII}^2}{80(1 - Q_{GII})^2} - \frac{72 - 25Q_{GII} - 3Q_{GII}^2}{40(1 - Q_{GII})} \]
\[ c_3 = 1 - \frac{3(-23 - Q_{GII} + 3 + 8Q_{GII})Q_{GII}}{80(1 - Q_{GII})^2} - \frac{68 - 16Q_{GII} - (1 - 2Q_{GII})Q_{GII}}{40(1 - Q_{GII})} \]
\[ d_3 = 1 + \frac{3(20 - 4Q_{GII} + 3 + 2Q_{GII})Q_{GII}}{80(1 - Q_{GII})^2} - \frac{68 - 16Q_{GII} - (1 - 2Q_{GII})Q_{GII}}{40(1 - Q_{GII})} \]
\[ e_3 = 1 + \frac{56 - 13Q_{GII} + 2Q_{GII} + 3Q_{GII}Q_{GII}}{80(1 - Q_{GII})^2} - \frac{68 - 16Q_{GII} - (1 - 2Q_{GII})Q_{GII}}{40(1 - Q_{GII})} \]
\[ f_3 = 1 + \frac{35 - 4Q_{G0} - (1 + 10Q_{G0})Q_{G0}}{40(1 - Q_{G0})^2} \]
\[ g_3 = 1 + \frac{3\left(16 + 5Q_{G0} + 6Q_{G0}^2\right)}{80(1 - Q_{G0})^2} - \frac{31 - 4Q_{G0} + 4Q_{G0}^2}{20(1 - Q_{G0})^2} \]
\[ h_3 = 1 + \frac{3\left(27 - 17Q_{G0} + 6Q_{G0}^2\right)}{80(1 - Q_{G0})^2} - \frac{31 - 4Q_{G0} + 4Q_{G0}^2}{20(1 - Q_{G0})^2} \]
\[ i_3 = 1 + \frac{25 + 13Q_{G0} + 8Q_{G0}^2}{40(1 - Q_{G0})^2} - \frac{31 - 4Q_{G0} + 4Q_{G0}^2}{20(1 - Q_{G0})^2} \]
\[ j_3 = 1 + \frac{46 - 29Q_{G0} + 8Q_{G0}^2}{40(1 - Q_{G0})^2} - \frac{31 - 4Q_{G0} + 4Q_{G0}^2}{20(1 - Q_{G0})^2} \]
\[ k_3 = 1 + \frac{34 - 17Q_{G0} + 11Q_{G0}^2}{40(1 - Q_{G0})^2} - \frac{37 - 13Q_{G0} - 2Q_{G0}^2}{20(1 - Q_{G0})^2} \]
\[ l_3 = 1 + \frac{37 - 5Q_{G0} - 4Q_{G0}^2}{40(1 - Q_{G0})^2} = \frac{37 - 13Q_{G0} - 2Q_{G0}^2}{20(1 - Q_{G0})^2} \]

Typical values of the coefficients \(a_1\)–\(l_3\) as well as the specific restrictions on each due to noise and orientation-dependent correlations are summarized in Table A3.

\[ a_3 \approx \frac{11}{7} \approx 1.57 \]
\[ b_3 \approx \frac{79}{50} \approx 0.58 \]
\[ c_3 \approx \frac{7}{7} \approx 1 \]
\[ d_3 \approx \frac{7}{7} \approx 1 \]
\[ e_3 \approx \frac{7}{7} \approx 1 \]
\[ f_3 \approx \frac{7}{7} \approx 1 \]
\[ g_3 \approx \frac{7}{7} \approx 1 \]
\[ h_3 \approx \frac{7}{7} \approx 1 \]
\[ i_3 \approx \frac{119}{119} \approx 1 \]
\[ j_3 \approx \frac{119}{119} \approx 1 \]
\[ k_3 \approx \frac{133}{133} \approx 1 \]
\[ l_3 \approx \frac{147}{147} \approx 1 \]

Finally, for those terms with three-orientation-dependent correlations, there exist four unique coefficients:

\[ a_4 \equiv 1 + \frac{74 - 9Q_{G0} + 23Q_{G0}^2 - \left(11Q_{G0} + 20Q_{G0}^2\right)Q_{G0}}{80(1 - Q_{G0})^2} \]
\[ b_4 \equiv 1 + \frac{74 - 9Q_{G0} + 23Q_{G0}^2 - \left(11Q_{G0} + 20Q_{G0}^2\right)Q_{G0}}{80(1 - Q_{G0})^2} \]
\[ c_4 \equiv 1 + \frac{74 - 9Q_{G0} + 23Q_{G0}^2 - \left(11Q_{G0} + 20Q_{G0}^2\right)Q_{G0}}{80(1 - Q_{G0})^2} \]
\[ d_4 \equiv 1 + \frac{74 - 9Q_{G0} + 23Q_{G0}^2 - \left(11Q_{G0} + 20Q_{G0}^2\right)Q_{G0}}{80(1 - Q_{G0})^2} \]

Typical values of the coefficients \(a_1\)–\(d_4\) as well as the specific restrictions on each due to orientation-dependent correlations are summarized in Table A4.