Stochastic Time

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Abstract. We present a simple dynamical model to address the question of introducing a stochastic nature in a time variable. This model includes noise in the time variable but not in the “space” variable, which is opposite to the normal description of stochastic dynamics. The notable feature is that these models can induce a “resonance” with varying noise strength in the time variable. Thus, they provide a different mechanism for stochastic resonance, which has been discussed within the normal context of stochastic dynamics.

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“Time” is a concept that has gained a lot of attention from thinkers in virtually all disciplines[1]. In particular, our ordinary perception of time is not the same as that of space, and this difference has been appearing in a variety of contemplations about nature. It appears to be the main reason for the theory of relativity, which has conceptually brought space and time closer to receiving equal treatment, continues to fascinate and attract discussion in diverse fields. Also, issues such as “directions” or “arrows” of time are current interests of research[2]. Another manifestation of this difference is the treatment of noise or fluctuations in dealing with dynamical systems. When we consider dynamical systems, whether classical, quantum, or relativistic, time is commonly viewed as not having stochastic characteristics. In stochastic dynamical theories, we associate noise and fluctuations with only “space” variables, such as the position of a particle, but not with the time variables. In quantum mechanics, the concept of time fluctuation is well accepted through the time-energy uncertainty principle. However, time is not treated as a dynamical quantum observable, and a clearer understanding has been explored[3].

Against this background, our main theme of this paper is to consider fluctuations of time in classical dynamics through the presentation of a simple model. There are a variety of ways to bringing stochasticity to some temporal aspects of dynamical systems. The model which we present is one way, it is an extension of delayed dynamical models[4, 5, 6, 7, 8]. With stochastic time, we have found that the model exhibits behaviors similar to those investigated in the topic of stochastic resonance[9, 10, 11], which are studied in a variety of fields[12, 13, 14, 15, 16]. The difference is that the phenomena are induced by noise in time rather than by noise in space.

The general differential equation of the class of delayed dynamics with stochastic time is

$$\frac{d x(\bar{t})}{d \bar{t}} = f(x(\bar{t}), x(\bar{t} - \tau)).$$

(1)

Here, $x$ is the dynamical variable, and $f$ is the “dynamical function” governing the dynamics. $\tau$ is the delay. The difference from the normal delayed dynamical equation appears in “time” $\bar{t}$, which contains stochastic characteristics. We can define $\bar{t}$ in a variety of ways.
of ways as well as the function $f$. To avoid ambiguity and for simplicity, we focus on
the following dynamical map system incorporating the basic ideas of the above general
definition.

$$
x_{nk+1} = f(x_n, x_{nk-\tau}), \\
n_{k+1} = n_k + \xi_k
$$

(2)

Here, $\xi_k$ is the stochastic variable which can take either +1 or −1 with certain prob-
abilities. We associate “time” with an integral variable $n$. The dynamics progress by
incrementing integer $k$, and $n$ occasionally “goes back a unit” with the occurrence of
$\xi = -1$. Let the probability of $\xi_k = -1$ be $p$ for all $k$, and we set $n_0 = 0$. Then naturally,
with $p = 0$, this map reduces to a normal delayed map with $n_k = k$. We update the vari-
able $x_n$ with the larger $k$. Hence, $x_n$ in the “past” could be “re-written” as $n$ decreases
with the probability $p$.

Qualitatively, we can make an analogy of this model with a tele–typewriter or a tape–
recorder, which occasionally moves back on a tape. A schematic view is shown in Figure
1A. The recording head writes on the tape the values of $x$ at a step, and “time” is
associated with positions on the tape. When there is no fluctuation ($p = 0$), the head
moves only in one direction on the tape and it records values of $x$ for a normal delayed
dynamics. With probability $0 < p$, it moves back a unit of “time” to overwrite the value
of $x$. The question is how the recorded patterns of $x$ on the tape are affected as we change
$p$.

The dynamical function is chosen to be a negative feedback function (Figure 1B) and
the concrete map model that we will study is given as follows.

$$
x_{nk+1} = x_{nk} + d\delta(-\alpha x_{nk} - \frac{2}{1+e^{-\beta x_{nk-\tau}}} + 1),
$$

(3)

with $\alpha$, $\beta$ and $d\delta$ as parameters. With both $\alpha$ and $\beta$ positive and no stochasticity
in time, this map has the origin as a stable fixed point with no delay. We consider
the case of $\alpha = 0.5$, $\beta = 6$, and $d\delta = 0.1$. By a linear stability analysis, the critical
delay $\tau_c$, at which the stability of the fixed point is lost, is given as $\tau_c \sim 6$. The
larger delay gives an oscillatory dynamical path. We have found, through computer
simulations, that an interesting behavior arises when delay is smaller than this critical
delay. The tuned noise in the time flow gives the system a tendency for oscillatory
behavior. In other words, adjusting the value of $p$ controlling $\xi$ induces an oscillatory
dynamical path. Some examples are shown in Figure 1C. With increasing probability
for the time flow to reverse, i.e., with $p$ increasing, we observe oscillatory behavior
both in the sample dynamical path as well as in the corresponding power spectrum.
However, when $p$ reaches beyond an optimal value, the oscillatory behavior begins to
deteriorate. The change in the peak heights is shown in Figure 1D. This phenomenon
resembles stochastic resonance. A resonance with delay and noise, called “delayed
stochastic resonance”[20], has been proposed for an additive noise in “space”. Analytical
understanding of the mechanism is yet to be explored for our model. However, this
mechanism of stochastic time flow is clearly of a different type and new.

We would like to now discuss a couple of points with respect to our model. First,
we can view this model as a dynamical model with non-locality and fluctuation on time
FIGURE 1. A: A schematic view of the model. B: Dynamical functions \( f(x) \) with parameters as examples of simulations presented in this paper. Negative feedback function with parameters \( \beta = 6 \). Straight line has slope of \( \alpha = 0.5 \). C: Dynamics (left) and power spectrum (middle) of delayed dynamical model with stochastic time flow (right). This is an example of the dynamics and associated power spectrum through the simulation of the model given in Eq. (3) with the probability \( p \) of stochastic time flow varied. The parameters are set as \( \alpha = 0.5, \beta = 6, d\delta = 0.1, \tau = 5 \) and the stochastic time flow parameter \( p \) are set to (a) \( p = 0 \), (b) \( p = 0.1 \), (c) \( p = 0.25 \), (d) \( p = 0.35 \), and (e) \( p = 0.45 \). We used the initial condition that \( x_n = 0.5(n \leq 0) \), and \( n_0 = 0 \). The simulation is performed up to \( k = 5000 \) steps. At that point the values of \( x_n \) for \( 0 \leq n \leq L \) with \( L = 512 \) are recorded. The 50 averages are taken for the power spectrum on this recorded \( x_n \). The unit of frequency \( \lambda \) is set as \( \frac{1}{L} \), and the power \( P(\lambda) \) is in arbitrary units. D: The signal to noise ratio \( S/N \) at the peak height as a function of the probability \( p \) of stochastic time flow. The parameter settings are the same as in C.
axis. Both factors are familiar in “space”, but not on time. We may extend this model to include non-locality and fluctuations in the space variable $x$. Proceeding in this way, we have a picture of dynamical systems with non-locality and fluctuations on both the time and space axes. The analytical framework and tools for such a description need to be developed, along with a search for appropriate applications.

Another way might be to extend the path integral formalism. The question of whether this extension bridges to quantum mechanics and/or leads to an alternative understanding of such properties as time-energy uncertainty relations also requires further investigation. Also, there is a theory of elementary particles with a fluctuation of space–time, where the noise term is added to the metric. If we can connect our ideas here to such a theory remains to be seen.

Finally, if these models do capture some aspects of reality, particularly with respect to stochasticity in the time flow, this resonance may be used as an experimental indication for probing fluctuations or stochasticity in time. We have previously proposed “delayed stochastic resonance”, a resonance that results from the interplay of noise and delay. It was theoretically extended, and recently, the effect was experimentally observed in a solid-state laser system with a feedback loop. It is left for the future to see if an analogous experimental test could be developed with respect to stochastic time.

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