INFLUENCE OF INTERFACIAL FORCES ON THE MIXTURE PREDICTION OF AN ANAEROBIC SEQUENCING BATCH REACTOR (ASBR)

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(Submitted: February 14, 2014; Revised: June 30, 2014; Accepted: July 2, 2014)

Abstract - In the operation of bioreactors, the fluid movement promotes mixing between sludge and substrate. The dynamics of this system are complex, and the interaction between the phases is difficult to evaluate accurately. In this work, Computational Fluid Dynamics is applied to simulate a pilot-scale anaerobic sequencing batch reactor, using a three-dimensional, transient and multiphase modeling. Several correlations were applied to estimate the interfacial forces. Results indicate that the use of different coefficients for the drag and lift forces strongly affects the predicted turbulent kinetic energy, and thus the mixture estimation in the bioreactor. The use of the drag as the only interfacial force provided an average turbulent kinetic energy close to the value found using a more complete model. However, the absence of lift and virtual mass forces had a significant impact on the resulting turbulence distribution.

Keywords: Computational fluid dynamics; Interfacial forces; Anaerobic sequencing batch reactor.

INTRODUCTION

Environmental issues cause great concern today. The consumption of fossil fuels is one of the factors that contribute to the greenhouse effect, due to the amount of carbon dioxide that is released into the atmosphere during the combustion of these fuels. This has motivated the search for new non-polluting fuels, including methane and biohydrogen.

Hydrogen is known to be a clean and ideal energy source due to its renewable status and green effect on the global environment (Nurtono \textit{et al.}, 2012). It can be obtained through physicochemical and biological routes. The hydrogen produced by microorganisms (biohydrogen) is affected simultaneously by biological, physical, and chemical factors (Ding \textit{et al.}, 2010; Wang \textit{et al.}, 2009; Wang \textit{et al.}, 2010). One of the most applied approaches for biohydrogen production involves the use of anaerobic sequencing batch reactors (ASBR), which also benefit the environment by consuming agro-industrial wastes.

The operation of an ASBR takes place in a single tank and comprises the following steps: (i) filling with wastewater; (ii) biotransformations of the wastewater constituents by microbial activity; (iii) settling of the biological sludge after reaction termination; (iv) discharge of reactor (Pinheiro \textit{et al.}, 2008; Michelian \textit{et al.}, 2009). This sequence is repeated for each new batch and most of the operation time is spent in the microbial activity, when the liquid is continuously recirculated to improve mass transfer. Thus, mixture is a key parameter, since a good mixture be-
between the phases promotes contact between the microorganisms and the substrate, and enhances the production of biogas in the form of bubbles dispersed through fermentation reactions.

The mixture is promoted by the fluid movement within the reactor, subjected to numerous interactions between gas, liquids, and solids. The dynamics of this multiphase mixture are complex, and the evaluation of the interaction between phases is challenging. Nonetheless, it is needed to predict the physical characteristics of bioreactors, which are seldom well described (Cao et al., 2010).

In this sense, computational fluid dynamics (CFD) tools can be valuable to study the fluid dynamics in bioreactors, as it provides estimatives of velocity and turbulence intensity in any location inside the reactor. However, there are difficulties when simulating the interaction between the disperse gas and the continuous liquid phases, which is affected by interfacial forces (drag, lift, and virtual mass forces). Multiphase modeling relies on various correlations to predict the interaction between the phases, and the difference among the estimated forces can affect the fluid dynamics. The estimated drag and lift force coefficients can vary significantly, depending on the operating conditions and on the correlation considered (Pang and Wei, 2011), leading to differences of the simulated results. It has been found that the magnitude of the drag force is more than 100 times higher than the magnitude of other interfacial forces (Laborde-Boutet et al., 2009). Still, forces such as lift and virtual mass can also play an important role in the motion of bubbles under the normal gravity condition (Pang et al., 2010).

Therefore, the correct modeling of these forces is of prime importance for capturing the physics correctly (Tabib et al., 2008). Nevertheless, the lift force model has not been well established yet (Hibiki and Ishii, 2007). Despite a large number of correlations which disregard the influence of the shear rate on the lift force coefficient estimation, it was found recently that this influence is strong (Dijkhuizen et al., 2010).

The present work uses CFD techniques to determine the influence of drag, lift, and virtual mass forces on the behavior of a gas-liquid flow in an existing pilot-scale ASBR, which runs under operating conditions typically found in fermentative processes. The simulated bioreactor has a capacity of 1 m³, operating with a mixture of wastewater and biomass for biohydrogen production. It features asymmetries not commonly found in traditional bubble columns. As mixture is an important parameter in the design of bioreactors, the turbulent kinetic energy predicted from the use of different models is evaluated.

### METHODOLOGY

#### Mathematical Modeling

Three-dimensional transient simulations were carried out to predict the fluid dynamics of the proposed cases. The two-fluids approach was applied to resolve the flow of two Eulerian, interpenetrating phases. The phases considered were: (1) a continuous liquid mixture and (2) gas bubbles. The formulation described by Weller (2002) (apud Rusche (2002)) for the incompressible two-phase flow equations was adopted. The equations of continuity and momentum transport are presented in Equations (1) and (2), respectively:

\[
\frac{\partial}{\partial t} \left( \alpha_g \rho_g \right) + \nabla \cdot \left( \alpha_g \rho_g \mathbf{U}_g \right) + \nabla \cdot \left( \alpha_g \rho_g \mathbf{U}_w \right) = 0 \tag{1}
\]

\[
\frac{\partial}{\partial t} \left( \alpha_i \mathbf{U}_i \right) + \nabla \cdot \left( \alpha_i \mathbf{U}_i \right) + \nabla \cdot \left( \alpha_i R_i^{\text{eff}} \right) + \frac{\nabla \alpha_i}{\alpha_i} R_i^{\text{eff}} = -\nabla p + g + \frac{M_i}{\alpha_i \rho_i} \tag{2}
\]

where the index \( i \) represents the phase ("g" stands for gas, "r" for liquid). \( \mathbf{U}_i \) represents the velocity of the phase, \( U_r \) is the relative velocity between the phases, \( \alpha_i \) is its volume fraction, \( g \) is the gravity acceleration, \( p \) is the pressure, \( \rho_i \) is the phase density, and \( M_i \) represents the momentum transfer between the phases due to interfacial forces. Where \( \alpha_i \) appears in the denominator, it is summed with a small value to avoid numerical errors. \( R_i^{\text{eff}} \) represents the stress tensor, related to viscous forces, and is defined in Equation (3):

\[
R_i^{\text{eff}} = -\nu_i^{\text{eff}} \left( \nabla \mathbf{U}_i + (\nabla \mathbf{U}_i)^T - \frac{2}{3} \mathbf{I} \nabla \mathbf{U}_i \right) + \frac{2}{3} \mathbf{I} k_i = 0 \tag{3}
\]

where \( \mathbf{I} \) is a unit tensor, \( \nu_i^{\text{eff}} \) is the effective viscosity, and \( k_i \) is the turbulent kinetic energy of the phase \( i \). The \( k-\epsilon \) turbulence model was used to determine the influence of turbulence in the liquid phase. It considers the Boussinesq assumption, in which the effective continuous phase viscosity is given by the sum of the laminar viscosity \( \nu_i \) and the eddy viscosity \( \nu' \), which is defined in Equation (4):

\[
\nu' = C_\mu \left( \frac{k_\epsilon}{\epsilon} \right) \tag{4}
\]

where \( C_\mu \) is a constant, and \( \epsilon \) is the turbulent kinetic energy dissipation. The \( k \) and \( \epsilon \) transport equations are given in Equations (5) and (6), respectively.
\[ \frac{\partial}{\partial t} (k_i) + (U_i \cdot \nabla) k_i - \nabla \cdot \left( \frac{\nu_{ij}^{\text{eff}}}{\sigma_k} \nabla k_i \right) = P_k - \varepsilon_i \]  \hspace{1cm} (5)

\[ \frac{\partial}{\partial t} (\varepsilon_i) + (U_i \cdot \nabla) \varepsilon_i - \nabla \cdot \left( \frac{\nu_{ij}^{\text{eff}}}{\sigma_\varepsilon} \nabla \varepsilon_i \right) = \frac{\varepsilon_i}{\kappa} (C_1 P_k - C_2 \varepsilon_i) \]  \hspace{1cm} (6)

where \( \sigma_k, \sigma_\varepsilon, C_1 \) and \( C_2 \) are constants of the model. \( P_k \) represents the turbulence production, expressed in Equation (7):

\[ P_k = 2 \nu_{ij}^{\text{eff}} \left( \nabla U_i, \text{dev} \left( \nabla U_i + (\nabla U_i)^T \right) \right) \]  \hspace{1cm} (7)

The constants of the turbulence model used in this work are listed in Table 1.

**Table 1: Constants of the \( k-\varepsilon \) turbulence model.**

| \( C_\mu \) | \( C_1 \) | \( C_2 \) | \( \sigma_k \) | \( \sigma_\varepsilon \) |
|---|---|---|---|---|
| 0.09 | 1.44 | 1.92 | 1.0 | 0.76923 |

The term \( M_i \) in Equation (2) represents the contribution of different forces to momentum: drag, lift, virtual mass, and “other forces”, as expressed in Equation (8).

\[ M_i = M_D + M_L + M_{VM} + M_O \]  \hspace{1cm} (8)

The drag force (\( M_D \)) depends on the relative velocity between the phases, and it is the dominant force in bubble columns. There are many correlations to estimate this force, and it is important to evaluate it properly, as it can also depend on the form of the bubbles, and their concentration. Because the operating conditions of the system indicate that it is in the homogeneous regime (Kantarci et al., 2005), the drag force (Equation (9)) can be considered as acting on spherical, rigid bubbles.

\[ M_D = \alpha_g \frac{3 \rho_l C_D}{4 d_b} |U_r| |U_r| \]  \hspace{1cm} (9)

where \( d_b \) is the bubble diameter. In this work, five correlations to estimate the drag force coefficient (\( C_D \)) between the fluid and rigid spherical bubbles were used. The Schiller and Naumann (1935) correlation (Equation (10)) is one of the first correlations proposed. It tends to the observed experimental values of \( C_D = 24 / Re_b \) and \( C_D = 0.44 \) at low and high bubble Reynolds numbers (\( Re_b \), respectively).

\[ C_D = \begin{cases} 
24 & \text{Re} \leq 1000 \\
1 + 0.15 \text{Re}_b^{0.687} & \text{Re} > 1000
\end{cases} \]  \hspace{1cm} (10)

According to Pang and Wei (2011), the Dalla Valle (1948) correlation offers a continuous expression, but results in slightly higher values for \( C_D \) in the range of \( 1 \leq \text{Re}_b \leq 200 \). It was evaluated using Equation (11):

\[ C_D = \left( \frac{4.8}{\text{Re}_b} \right)^2 + \frac{0.63}{\sqrt{\text{Re}_b}} \]  \hspace{1cm} (11)

The Ma and Ahmadi (1990) correlation and Zhang and Vanderheiden (2002) correlation were also used. They are also continuous, and estimate values for \( C_D \) very close to those obtained with the Schiller and Naumann correlation. These correlations were evaluated using Equations (12) and (13), respectively.

\[ C_D = \frac{24}{\text{Re}_b} \left( 1 + 0.1 \text{Re}_b^{0.75} \right) \]  \hspace{1cm} (12)

\[ C_D = 0.44 + \frac{24}{\text{Re}_b} + \frac{6}{1 + \sqrt{\text{Re}_b}} \]  \hspace{1cm} (13)

The Lain et al. (2002) correlation (Equation (14)) was also evaluated. It uses four expressions to provide smooth changes of \( C_D \) with \( Re_b \), but it also gives lower values when compared to the Schiller and Naumann correlation.

\[ C_D = \begin{cases} 
16 \text{Re}_b & \text{Re}_b \leq 1.5 \\
14.9 & 1.5 < \text{Re}_b \leq 80 \\
48 \left( 1 - \frac{2.21}{\sqrt{\text{Re}_b}} \right) + 1.86 \times 10^{-15} \text{Re}_b^{4.756} & 80 < \text{Re}_b \leq 1500 \\
2.61 & \text{Re}_b > 1500
\end{cases} \]  \hspace{1cm} (14)
where \( \text{Re}_b \) denotes the bubble Reynolds number, defined as:

\[
\text{Re}_b = \frac{U_d d_b}{\nu_b}
\]  

Equation (16) was used to evaluate the lift contribution to the momentum equation \( (L_M) \), in which the lift is defined as a force perpendicular to the flow direction:

\[
M_L = \alpha_g C_L \rho_f U_g \times \left( \nabla \times U_g \right)
\]  

Velocity gradients are present in the bioreactor, at least near the inlet and close to the walls. Depending on the operating condition, reflux can also be present between the walls and the center of the bioreactor. These gradients result in a force acting on each bubble, towards higher velocity regions in the case of small, rigid bubbles. A constant value of the lift coefficient was considered in this work, as \( C_L = 0.5 \) is the value expected for a spherical bubble in the high Reynolds limit (Dijkhuizen et al., 2010). Three other estimates for \( C_L \) were also evaluated: one was the Saffman (1965) correlation (Equation (17)), which relates \( C_L \) to the shear stress.

\[
C_L = \frac{9.69}{\pi} \left( \text{Re}_b S_{rb} \right)^{-1/2}
\]  

Another correlation considered was the Legendre and Magnaudet (1998) correlation (Equation (18)), which is the result of a blend between two analytical solutions for \( C_L \) at low and high Reynolds numbers, corrected to take account of the bubble deformation effect on the lift force (Hibiki and Ishii, 2007).

\[
C_L = \left( 2 - \exp \left( 2.92 d_g^{2.21} \right) \right) \sqrt{C_{L,\text{low Re}}^2 + C_{L,\text{high Re}}^2}
\]  

The Tomiyama et al. (2002) correlation (Equation (19)), which was obtained experimentally with a linear shear field in viscous liquids (Pang and Wei, 2011), was also used:

\[
C_L = \min \left( 0.288 \tanh \left( 0.121 \text{Re}_b \right), f \left( \text{Eo}_d \right) \right)
\]  

In these equations, \( S_{rb} \) (dimensionless shear rate), \( C_{L,\text{low Re}} \) and \( C_{L,\text{high Re}} \) are defined as:

\[
S_{rb} = \frac{w d_b}{U_r \nu_b}
\]

\[
C_{L,\text{low Re}} = \frac{6}{\pi \sqrt{\text{Re}_b S_{rb}}} \left( \frac{2.255}{\left( 1 + 0.2 \text{Eo}^{-2} \right)^{1.5}} \right)
\]

\[
C_{L,\text{high Re}} = \frac{1}{2} \left( \frac{1 + 16 / \text{Re}_b}{1 + 29 / \text{Re}_b} \right)
\]

where \( w \) is the magnitude of the velocity gradient. \( \text{Eo} \) is the Eötvös number, which is the ratio between buoyancy and surface tension forces. It is also used in the calculation of \( f \left( \text{Eo}_d \right) \) and \( d_H \) as follows:

\[
\text{Eo} = \frac{g \left( \rho_l - \rho_g \right) d_b^2}{\sigma}
\]

\[
d_H = d_g \left( 1 + 0.163 \text{Eo}^{0.757} \right)
\]

\[
f \left( \text{Eo}_d \right) = 0.00105 \text{Eo}_d^3 - 0.0159 \text{Eo}_d^2 - 0.0204 \text{Eo}_d + 0.474
\]

where \( \sigma \) is the surface tension coefficient.

The virtual mass force \( M_{VM} \) represents a resistance to the free acceleration of the bubbles, as they move through the surrounding fluid. A value of \( C_{VM} = 0.5 \) was applied to evaluate the virtual mass force, expressed in Equation (27).

\[
M_{VM} = \alpha_g C_{VM} \rho_l \left( \frac{D U_l}{dt} - \frac{d U_g}{dt} \right)
\]  

**Geometry and Mesh**

The reactor studied in this work consists of a pilot scale ASBR with an internal diameter of 0.604 m, height of 3.8 m and a total capacity of 1.0 m³. In its operation, the liquid mixture is recirculated through a pipe which has an internal diameter of 0.04 m. Gas is injected through the entire base of the reactor, to make the distribution of the bubbles as uniform as possible, as expected in a bioreactor. Both phases
leave the reactor through different pipes located at the top of the reactor. A diagram of the reactor is shown in Figure 1A.

Three-dimensional meshes with different refinement were elaborated, in order to verify the optimal mesh to carry out the multiphase simulations. Results were obtained for meshes with refinement ranging from 60,000 to 210,000 control volumes. Comparing pressure and radial profiles of liquid velocity, it was determined in a previous work (Maurina et al., 2013) that a mesh containing approximately 130,000 volumes is sufficiently refined to predict accurately the behavior inside the reactor. It has y+ values (dimensionless measure of the thickness of the control volumes adjacent to the walls of the reactor) close to 37, which is suitable for turbulent case simulations. Details of the mesh are shown in Figures 1B, 1C and 1D.

Figure 1: (A) Schematic diagram of the bioreactor; details of the mesh used: (B) superior section, (C) inferior section, and (D) transversal cut.

Operating Conditions

The fluid adopted for simulations was considered to be Newtonian, with rheological properties similar to the mixture of microbial culture and substrate composed of vinasse and glycerin, discarded respectively in alcohol plants and biodiesel units. The gas phase has the properties of biogas, and it is initially present at the top section of the reactor. The bubble diameter was set to 0.001 m (Ding et al., 2010) with the assumption of spherical bubbles. As no reaction was considered in the simulations, biogas was assumed to enter at the entire base of the bioreactor, in order to consider the interaction between bubbles and the liquid phase. An approximate production of $9.259 \times 10^{-5} \text{ m}^3/\text{s}$ of biogas was applied as a uniform inlet condition. A liquid flow rate of $2.25 \times 10^{-3} \text{ m}^3/\text{s}$ is specified at the recirculation pipe. The outlets of liquid and gas are located in the top region. Table 2 shows the boundary conditions and physical properties used in the cases proposed.

Table 2: Boundary conditions and physical properties used in the numerical simulations.

| Boundary Conditions          | Liquid inlet | Gas inlet | Top outlet | Lateral outlet | Walls |
|-----------------------------|--------------|-----------|------------|----------------|-------|
| Gas inlet                   | Mixture flow rate: $2.25 \times 10^{-3} \text{ m}^3/\text{s}$ | Turbulence intensity: 5% | Gas flow rate: $9.259 \times 10^{-5} \text{ m}^3/\text{s}$ | 101.325 Pa | Fixed velocity (recirculation pipe) |
| Top outlet                  |              |           |            |                |       |
| Lateral outlet              |              |           |            |                | Smooth velocity condition for both phases |
| Walls                       |              |           |            |                |       |
| Physical Properties         |              |           |            |                |       |
| Phase                       | Disperse (gas) | Continuous (liquid) |            |                |       |
| Phase Density               | 0.089 kg/m$^3$ | 1.0097 kg/m$^3$ |            |                |       |
| Kinematic viscosity         | $8.4 \times 10^{-6} \text{ m}^2/\text{s}$ | $1 \times 10^{-6} \text{ m}^2/\text{s}$ |            |                |       |
| Bubble diameter             | 0.001 m      |           |            |                |       |
| Surface tension             | 0.072 N/m$^2$ |           |            |                |       |

Although most of the gas exits through the top outlet, a small fraction can also flow through the recirculation pipe. Thus, the amount of liquid that leaves the reactor varies. In order to maintain the volume of liquid inside the reactor constant, an expression was elaborated to determine the liquid flow through the outlet, and use it as an inlet condition. The exact expression coded in OpenFOAM, which depends on the gas volume fraction ($\alpha_g$), liquid velocity ($U_l$) and the boundaries area ($A$), is presented in Equation (28):

$$\alpha_{g,in} = 1 - \frac{U_{l,\text{out}} A_{\text{out}} \left(1 - \alpha_{g,\text{out}}\right)}{U_{l,\text{in}} A_{\text{in}}}$$

Numerical Solution

The results were obtained through simulations conducted with the OpenFOAM CFD toolbox, using a modified “twoPhaseEulerFoam” code. The Schiller and Naumann correlation was provided by the original code, as well as the choice to use constant values for $C_L$ and $C_{VM}$. Other correlations evaluated in this work were included in the source code.

OpenFOAM solvers use the finite volume method to solve the system of partial differential equations, and provides a comprehensive list of interpolation schemes. In this work, linear Gaussian integration was chosen for gradient operators. It is based on summing the value on cell faces, which must be interpolated from cell centers. A Gauss linear scheme, which interpolates variables based on fluxes, was used for discretization of divergence terms. For the first time derivative, the choice was the Euler implicit (Open
FOAM, 2013). The solution of the resulting equations is made with the segregated technique, solving each set of algebraic equations separately within an iterative cycle until convergence is achieved. Numerical solution of the pressure-velocity coupling was performed using a mix between the SIMPLE and PISO algorithms. It involves a momentum predictor and a correction loop in which a pressure equation based on the volumetric continuity equation is solved, and the momentum is corrected based on the pressure change (Rushe, 2002).

A maximal tolerance of $10^{-5}$ for the residuals was specified to establish the convergence of the iterative solution procedure. A Courant-Friedrichs-Lewy (CFL) condition of less than 1 was applied to ensure the stability of the transient solution.

\[ CFL = \frac{U \Delta t}{\Delta x} \]  

(29)

where $U$ is the mixture velocity, $\Delta t$ is the time step and $\Delta x$ is the control volume size.

A total of fourteen cases were simulated to evaluate the influence of the interfacial forces. Five simulations were carried out considering only the presence of the drag force, evaluated using different correlations. The remaining simulations considered the Zhang and Vanderheyden correlation for the drag force. Four simulations were calculated, including different correlations to estimate the lift force. One simulation considered the drag and the virtual mass forces, and another considered the three forces. The last four simulations considered the drag, drag and lift, drag and virtual mass, and all three forces, in the case of both gas and liquid phases entering the reactor through the recirculation pipe. Each case was calculated using four processes in parallel to simulate 300 s of flow, with the last 100 s used to obtain average values.

RESULTS AND DISCUSSION

Drag Correlations

Five correlations were used to estimate the coefficient of the drag force between the liquid mixture and spherical bubbles: Schiller and Naumann, Dalla Valle, Ma and Ahmadi, Zhang and Vanderheyden, and Lain. Average axial velocity profiles of the liquid phase, collected at different heights, are presented in Figure 2. Small differences can be seen in the flow pattern obtained using different drag correlations. At the height of 0.7 m (Figure 2A), all velocity profiles obtained presented a similar profile, with higher values between the center and the left side of the bioreactor. The velocity in this region is strongly influenced by the inlet stream.

Velocity profiles observed at the height of 2 m (Figure 2B) present maximum values near the walls of the reactor. However, these values are very small, compared to those collected at the height of 0.7 m. Lower velocities can also be observed in the top region of the reactor, at the height of 3 m (Figure 2C). At this position, most correlations resulted in a similar behavior, with higher velocity in the side opposite to the outlet of the reactor. Results obtained using the Schiller and Naumann correlation deviates from this behavior, showing an almost symmetrical axial velocity profile. The use of the Lain correlation resulted in a different flow pattern, with higher velocity on the same side of the reactor outlet. It must be emphasized that these results represent the average values calculated between 200 and 300 s of flow.

The mixture inside the reactor can be evaluated through its turbulent kinetic energy. Higher values of the turbulent kinetic energy indicate the presence of sub-grid vortices, which promote mixing. Thus, a weighted average of the turbulent kinetic energy ($\bar{k}$) was calculated, weighted by the liquid volume ($V_l$) (Equation (30)).

\[ \text{Average axial velocity profile} \]

\[ \text{Average liquid axial velocity (m/s)} \]

\[ \text{Normalized radial position} \]

\[ \text{Schiller and Naumann} \quad \text{Dalla Valle} \quad \text{Ma and Ahmadi} \quad \text{Zhang and Vanderheyden} \quad \text{Lain} \]

Figure 2: Time-averaged axial velocity profiles of the liquid phase using different drag correlations, at the heights of (A) 0.7 m, (B) 2 m, and (C) 3 m.
\[ k = \frac{\sum (k_j V_j)}{\sum (V_j)} \]  

With the calculation of the turbulent kinetic energy \( \bar{k} \) for each simulation, it was possible to compare how turbulent the flow is in the reactor, when simulated with different models. Another method used to compare the simulations consisted in estimating the difference of the turbulent kinetic energy \( \Delta k \) predicted in each simulation, using as reference the results obtained with the Zhang and Vanderheyden correlation \( k_{\text{ref}} \). It is found in the literature that this correlation gives good results in simulations of bubbles dispersed in liquid (Pang and Wei, 2011; Tabib et al., 2008). Thus, the difference in the turbulence field predicted using other drag correlations was calculated using Equation (31). 

\[ \Delta k = \frac{\sum \left| k_j - k_{\text{ref}} \right| V_j}{\sum (V_j)} \]  

Values of \( \Delta k \) provide a measure of the difference in the turbulent kinetic energy pattern from different simulations. Higher values indicate that the distribution of the turbulent kinetic energy of two simulations do not agree with each other. Table 3 summarizes the properties defined in Equations (30) and (31).

**Table 3: Turbulence properties using different drag correlations.**

| Correlation            | \( \bar{k} \) (m²/s²) | % difference of \( \bar{k} \) | \( \Delta k \) (m²/s²) |
|------------------------|------------------------|-----------------------------|------------------------|
| Schiller and Naumann   | 0.001329               | 13.21%                      | 0.000416               |
| Dalla Valle            | 0.001345               | 12.18%                      | 0.000573               |
| Ma and Ahmadi          | 0.001406               | 8.23%                       | 0.000439               |
| Zhang and Vanderheyden | 0.001532               | –                           | 0.000594               |
| Lain                   | 0.001247               | 18.57%                      | 0.000594               |

Comparing the results, significant deviations can be seen in the weighted average turbulent kinetic energy \( \bar{k} \), when considering different correlations for the drag force coefficient. It was found that the Lain correlation provided the lowest estimate for turbulence in the reactor. The analysis of \( \Delta k \) also confirms that the turbulent kinetic energy field predicted using the Lain correlation was very different from the field obtained using the Zhang and Vanderheyden correlation. One explanation for this difference could be due to values of \( C_D \) tending to 16 / Re₉ when using the Lain correlation in the Stokes region, Re₉ < 1 (Pang and Wei, 2011). \( C_D \) values obtained using the Zhang and Vanderheyden correlation tend to 24 / Re₉ in this region. It is noteworthy that the flow in the simulated bioreactor has values of Re₉ around 106.20, although lower values can be found close to the walls.

Slight differences were also found using other correlations. Nonetheless, the values in Table 3 confirm the behavior found in Figure 2, as results for turbulence using the Ma and Ahmadi correlation were in good agreement with results obtained using the Zhang and Vanderheyden correlation. This model also tends to 24 / Re₉ in the Stokes region. Thus, it can be concluded that using different drag correlations, the predicted mean turbulence can vary as much as 18.57%, influencing the design of bioreactors.

**Lift Correlations**

To evaluate the effect of different lift force coefficient values, four models were considered: a constant value \( C_L = 0.5 \), and the correlations from Saffman, Legendre and Magnaudet, and Tomiyama. The Zhang and Vanderheyden correlation was maintained to estimate the drag force in these cases.

The average axial velocity profiles for the liquid phase, collected along the diameter of the reactor at the heights of 0.7 m, 2 m and 3 m, are presented in Figures 3A, 3B and 3C respectively. At the height of 0.7 m the fluid is near the inlet region; thus it is expected to have the higher velocity gradients, which interfere in the lift force calculation. It can be seen in Figure 3A that all correlations to estimate the lift force provided similar profiles for the average axial velocity. Small differences were observed near the left side of the reactor, when using the Saffman correlation.

At higher heights (Figures 3B and 3C), the lift force should lose its strength, and results obtained using different correlations are expected to be close. However, differences were still observed, mostly when using a constant value for \( C_L \) and the Saffman correlation. Using \( C_L = 0.5 \), it is assumed that the lift force acting on the bubbles has the same intensity of the lift force at high Reynolds numbers. It resulted in differences in the prediction of this force, which are evidenced at higher heights. The axial velocity profile obtained using the Saffman correlation also differs from those obtained using the Legendre and Magnaudet, and Tomiyama correlations. The Saffman correlation offers a dependency of \( C_L \) on the shear rate, even in flows with high Reynolds numbers.
A method used to compare the results was to calculate the turbulence properties. Table 4 summarizes the results found considering different estimates for the lift force. The Legendre and Magnaudet correlation provides a strong dependence on both Reynolds number and the shear rate only for low Reynolds number (Hibiki and Ishii, 2007). This correlation was used to calculate the difference between the results.

Figure 3: Time-averaged axial velocity profiles of the liquid phase using different lift correlations, at the heights of (A) 0.7 m, (B) 2 m, and (C) 3 m.

Table 4: Turbulence properties using different lift correlations.

| Correlation         | \( \bar{k} \) (m\(^2\)/s\(^2\)) | % difference of \( \bar{k} \) | \( \Delta k \) (m\(^2\)/s\(^2\)) |
|---------------------|---------------------------------|---------------------------|--------------------------------|
| Constant \( C_L \)  | 0.001376                        | 9.03%                     | 0.000234                       |
| Saffman             | 0.001341                        | 6.30%                     | 0.000411                       |
| Legendre and Magnaudet | 0.001262                  | –                         | –                               |
| Tomiyama            | 0.001354                        | 7.29%                     | 0.000206                       |

In Table 4, it can be noted that the use of a constant \( C_L \) resulted in the largest difference (9.03%), which may be due to its consideration of a high Reynolds number in the reactor. The Saffman correlation has a dependency on the shear rate, independent of the Reynolds number of the flow. It resulted in the higher difference of the turbulent kinetic energy field (\( \Delta k \)). The weighted average turbulent kinetic energy obtained with this correlation was 6.30% higher than the value obtained using the correlation from Legendre and Magnaudet. The Tomiyama correlation provides a dependency of \( C_L \) on \( Re_b \) at low Reynolds numbers, and it tends to a constant value of \( C_L = 0.3 \) at high Reynolds numbers.

Thus, in this evaluation, it was found that different correlations for the lift force coefficient can result in a difference of 9.03% in the estimate of the weighted average turbulence in the simulated bioreactor.

Drag, Lift and Virtual Mass Forces

It was demonstrated that the predicted mixture in the bioreactor can be biased due to the use of different correlations to estimate the drag and lift forces. The resulting mixture can also be influenced by an inaccurate choice of forces to represent the physical phenomena.

Simulations considering the drag force only (using the Zhang and Vanderheyden correlation), the drag and lift forces (including the Legendre and Magnaudet correlation), the drag and virtual mass forces (considering a constant coefficient \( C_{VMC} = 0.5 \)), and the three forces were compared. In Figure 4, profiles for the average liquid axial velocity along the diameter of the reactor are presented, at the heights of 0.7 m, 2 m and 3 m.

Near the bottom section of the reactor, at the height of 0.7 m (Figure 4A), the liquid axial velocity profile obtained considering the drag and virtual mass forces was unlike those obtained using other models. Profiles obtained considering all forces, the drag and lift forces, and the drag force only, agreed well among them. This indicates that, when using the virtual mass force, the lift force should also be considered, in order to have coherent results. Without these two forces, the drag force can still provide velocity profiles in good agreement with results obtained using a more complete modeling.

At the height of 2 m (Figure 4B), the average liquid axial velocity profile obtained applying the three forces shows a maximum value on the same side of the reactor outlet. Profiles obtained using the drag and lift forces, and using the drag and virtual mass forces present an inverse behavior, with negative values in this region. On the other side, the simulation using all forces predicted an almost null liquid axial velocity, but all other cases resulted in higher values, with the highest obtained using the drag and virtual mass interfacial forces.

Near the top section of the reactor (Figure 4C), all cases had a good qualitative agreement, except when using the drag force only, which predicted positive
values at the left side of the reactor, where other simulations resulted in negative values.

The choice of interfacial forces can influence the turbulent kinetic energy, as can be seen in Table 5.

The simulation considering the drag and lift forces resulted in the lowest weighted average turbulent kinetic energy ($\bar{k}$) and, compared to the results obtained with the three forces, it resulted in the highest difference, 10.71%. Considering the drag and virtual mass forces, $\bar{k}$ had the lowest difference, 4.64%, but also resulted in the most different distribution of the turbulence ($\Delta k$), which is in accordance with the fields observed in Figure 4. Inaccurate prediction of the mixture can lead to bioreactors that are not optimally designed. Nevertheless, comparing these values to those obtained in the previous sections, it was found that higher differences can be obtained using different correlations for each interfacial force.

### Drag, Lift and Virtual Mass Forces – One Inlet

The next four cases were carried out to analyze the consideration of different forces (drag force only, drag and lift forces, drag and virtual mass forces, and all three forces), when both gas and liquid phases are fed in only one inlet. Thus, the magnitude of each interfacial force is intensified, as well as differences among simulations.

It can be noted at the height of 0.7 m (Figure 5A) that the liquid average axial velocity profiles obtained disregarding the virtual mass force deviate from the results obtained by applying this force. Near the outlet (Figure 5C), these profiles are close to each other, though the profile predicted using the drag force only and using the drag and lift forces shows maximum values near the center, different from the other cases. This confirms the influence, in this case, of the virtual mass force over the flow pattern. Figure 5 also shows that the lift force, estimated with the Legendre and Magnaudet correlation, has its major influence at the bottom of the reactor, near the inlet, where high velocity gradients are present.
Results obtained for the average gas volume fraction considering the drag force only, including the lift force, the virtual mass force, and considering the three forces, are presented in Figures 6A, 6B, 6C and 6D, respectively.

The flow obtained with the drag force only is presented in Figure 6A. It can be seen that bubbles are concentrated on the axis of the reactor. At higher heights, the bubble plume predicted using the Zhang and Vanderheyden correlation maintains the same behavior.

The inclusion of the lift force alters this behavior. Although the higher concentration of bubbles is still found near the center of the reactor, the plume is dispersed towards the walls. It is in accordance with the formulation of the lift force, which is transversal to the flow. Comparing Figure 6B with the average velocity profiles in Figure 5, it can be seen that the lift force is acting towards regions with higher velocity – thus, with lower pressure.

In Figure 6C, the effect of virtual mass on gas distribution can be seen: the gas plume formed at the bottom of the reactor flows upward near one side of the reactor, in the region with higher velocity presented in Figure 5.

The gas volume fraction field obtained with the inclusion of the three forces, illustrated in Figure 6D, shows a flow pattern similar to the field observed in Figure 6C, in which the gas plume is close to one side of the bioreactor. Moreover, the gas plume tends to disperse, as seen in Figure 6B. Thus, both the lift and virtual mass forces contribute to determine the flow pattern in the bioreactor.

The fields presented in Figure 6 are very different from those obtained considering a uniform gas inlet. In previous cases, the gas volume fraction was spread out, and most of the reactor had a small concentration of disperse bubbles, without a clear difference among the cases.

As already seen in Table 5, the choice of interfacial forces affects the turbulent kinetic energy. Table 6 present values calculated for the simulations with gas and liquid phases fed through only one inlet. The use of only the drag force resulted in a weighted average turbulent kinetic energy (\(\bar{k}\)) close to the value obtained by applying the three forces, with a difference of only 2.72%, but also caused the most different turbulence distribution (measured with \(\Delta k\)). The inclusion of the lift force resulted in an average turbulent kinetic energy 4.98% lower. The inclusion of the virtual mass force increased it by 8.77%, and also resulted in a less different distribution of the turbulence (\(\Delta k\)). It can be seen in Figure 6 that, in spite of the close values predicted for \(\bar{k}\) when considering all forces and only the drag force, the bubble movements in these two simulations do not agree (Figures 6A and 6D). This emphasizes the need to analyze the difference of the fields (\(\Delta k\)): its calculation shows that the use of only the drag force results in the most different turbulent kinetic energy field.

![Figure 6](image)

**Table 6: Turbulence properties using different interfacial forces and one inlet.**

| Force                  | \(\bar{k} (m^2/s^2)\) | % difference of \(\bar{k}\) | \(\Delta k (m^2/s^2)\) |
|------------------------|------------------------|----------------------------|------------------------|
| Drag                   | 0.005109               | 2.72%                      | 0.001566               |
| Drag and lift          | 0.004726               | 4.98%                      | 0.001016               |
| Drag and virtual mass  | 0.005409               | 8.77%                      | 0.000747               |
| Drag, lift and virtual mass | 0.004973     | –                          | –                      |

Inaccurate prediction of the mixture can lead to bioreactors that are not optimally designed. Comparing these values to those obtained in the previous sections, it can be noted that higher differences were obtained using different correlations for each force.

**CONCLUSIONS**

The influence of different correlations for the drag, lift and virtual mass forces on the mixture prediction of an ASBR was verified in this paper, using the calculated turbulent kinetic energy to compare each modeling. This is an important parameter, which can be used as a measure of the mixture in the bioreactor, and thus influencing the design of new reactors.

Different drag force correlations had little impact
on the liquid average axial velocity profiles under the operating conditions evaluated in this work, except for the Lain correlation. However, they affected the predicted turbulent kinetic energy, with the highest difference of 18.57%. Considering different correlations for the lift force coefficient, it was verified that the lift force is most meaningful near the inlet, in the bottom region of the reactor, where strong velocity gradients are expected.

The choice of forces can also lead to differences in the turbulent kinetic energy. The largest difference in the turbulent kinetic energy resulted when omitting the virtual mass force (10.71%), which emphasizes the importance of this force under the operating conditions studied in this work. When considering only one inlet for both phases, the omission of the lift force resulted in a difference of 8.77%. Considering only the drag force resulted in the most different turbulent kinetic energy field, measured with ∂k. In cases with one inlet, and thus higher gas-liquid interactions, remarkable differences in the pattern of the gas volume fraction were obtained for each model.

Differences found disregarding some forces were below the differences found considering different correlations for the drag force coefficient. Thus, it is advised to carefully select the correlation to estimate each interfacial force, since they can greatly interfere with the results obtained. Provided each force are adequately estimated, the use of a more complete modeling to simulate the operational conditions found in the studied bioreactor is the safest approach to obtain accurate results, due to the differences found neglecting the lift and/or the virtual mass force. When possible, the model chosen must be validated with experimental values.

ACKNOWLEDGEMENTS

The authors are grateful to Petrobras and FAPERGS for their financial support.

NOMENCLATURE

**Latin Letters**

- A: boundary area (m²)
- Cμ, C1, C2: constant of the k-ε turbulence model
- CD: drag force coefficient (-)
- CL: lift force coefficient (-)
- CVVM: virtual mass force coefficient (-)
- d: diameter (m)
- Eo: Eötvös number (-)

**Greek Letters**

- α: volume fraction (-)
- Δx: control volume characteristic size (m)
- ρ: density (kg m⁻³)
- υ: kinematic viscosity (m² s⁻¹)
- ε: turbulent dissipation energy (m² s⁻³)
- σ: surface tension coefficient (N m⁻²)
- σκ, σε: constant of the k-ε turbulence model
- υl: laminar viscosity (m² s⁻¹)
- υ′: eddy viscosity (m² s⁻¹)

**Subscripts**

- b: bubble
- eff: effective
- g: gas phase
- i: phase
- l: liquid phase
- T: transposed vector

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