Functional Genetic Screen to Identify Interneurons Governing Behaviorally Distinct Aspects of Drosophila Larval Motor Programs

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ABSTRACT Drosophila larval crawling is an attractive system to study rhythmic motor output at the level of animal behavior. Larval crawling consists of waves of muscle contractions generating forward or reverse locomotion. In addition, larvae undergo additional behaviors, including head casts, turning, and feeding. It is likely that some neurons (e.g., motor neurons) are used in all these behaviors, but the identity (or even existence) of neurons dedicated to specific aspects of behavior is unclear. To identify neurons that regulate specific aspects of larval locomotion, we performed a genetic screen to identify neurons that, when activated, could elicit distinct motor programs. We used 165 Janelia CRM-Gal4 lines—chosen for sparse neuronal expression—to ectopically express the warmth-inducible neuronal activator TrpA1, and screened for locomotor defects. The primary screen measured forward locomotion velocity, and we identified 63 lines that had locomotion velocities significantly slower than controls following TrpA1 activation (28°C). A secondary screen was performed on these lines, revealing multiple discrete behavioral phenotypes, including slow forward locomotion, excessive reverse locomotion, excessive turning, excessive feeding, immobile, rigid paralysis, and delayed paralysis. While many of the Gal4 lines had motor, sensory, or muscle expression that may account for some or all of the phenotype, some lines showed specific expression in a sparse pattern of interneurons. Our results show that distinct motor programs utilize distinct subsets of interneurons, and provide an entry point for characterizing interneurons governing different elements of the larval motor program.

KEYWORDS Drosophila sensory motor glia CPG wave propagation

Understanding the neurobiological basis of behavior and brain disorders is a grand challenge of the 21st century, as outlined by the BRAIN Initiative (Jorgenson et al. 2015). The study of invertebrates has yielded numerous insights into the neural basis of behavior (Marder 2007). Invertebrates offer an elegant platform to investigate behavioral patterns due to the stereotypy of behaviors, as well as the ability to reproducibly identify individual neurons that generate behaviors. Examples include detailed studies of escape behaviors driven by command neurons of crayfish (Edwards et al. 1999), central pattern generating circuits of crustaceans (Hooper and DiCaprio 2004), reciprocal inhibition motifs in the visual system of the horseshoe crabs (Hartline and Ratliff 1957, 1958), and learning and memory habituation in the sea hare (Kandel 2001). While these principles were discovered in invertebrates, they are broadly applicable to aspects of neural circuit function in vertebrates.

An integral component of all motor systems is central pattern generators (CPGs), which underlie the generation of rhythmic motor patterns (Marder and Calabrese 1996; Marder and Bucher 2001). CPGs are diverse and modular, and can be recruited to function depending on context and exposure to aminergic neuromodulators such as serotonin (Harris-Warrick 2011). Neural circuits that comprise CPGs can function autonomously of sensory or descending inputs (Pulver et al. 2015). The study of insects has led to advances in understanding unique
aspects of motor programs, including patterned motor output, sensory or descending inputs, and the local control of musculature (Burrows 1996; Büschges et al. 2011).

Although it is possible to study neural circuits in Drosophila melanogaster (Wilson et al. 2004; Stockinger et al. 2005; Yu et al. 2010; Ruta et al. 2010), historically, this has been challenging due to the small size and inaccessibility of Drosophila neurons. However, the recent advent of advanced techniques to target, label, and monitor physiological input and output has made Drosophila an excellent model to investigate the neurobiological basis of behaviors, and the development of neural circuits (Pfeiffer et al. 2008, 2010; Pulver et al. 2009; Chen et al. 2013; Klapoetke et al. 2014; Hecksher et al. 2015; Nern et al. 2015). Furthermore, serial section transmission electron microscopy (ssTEM) maps of neural connectivity (Cardona 2013; Cardona et al. 2010; Ohyama et al. 2015; Saalfeld et al. 2009; Takemura et al. 2013; Schneider-Mizell et al. 2016; Berck et al. 2016), and advanced computational ‘ethomic’ approaches to establish behavioral categories (Branson et al. 2009; Kabra et al. 2013; Vogelstein et al. 2014) will greatly aid future investigations.

With approximately 10,000–15,000 neurons (Scott et al. 2001), Drosophila larvae offer a relatively simple preparation for investigating neural circuit formation at single cell resolution. Considerable progress has been made in understanding larval and embryonic neurogenesis with markers of neuroblasts, and well characterized progeny (Doe 1992; Schmid et al. 1999; Birkholz et al. 2015; Harris et al. 2015). Recent anatomical studies show that many, if not all, interneurons of the ventral nerve cord (VNC) have a unique morphology (Rickert et al. 2011), and possible unique molecular profile (Heckscher et al. 2014). Importantly, there are over 7000 Gal4 lines generated by the Rubin lab (Jenett et al. 2012); we previously screened these lines for late embryonic expression, and identified several hundred expressed in sparse numbers of neurons within the VNC (Manning et al. 2012). These tools allow genetic access to the majority of interneurons within the VNC, and allow us to characterize their role in late embryonic or newly hatched larval behaviors by expression of ion channels to silence neuronal activity (KIR; Baines et al. 2001), or induce neuronal activity (TrpA1; Pulver et al. 2009). By screening these Gal4 patterns for unique behavioral phenotypes, it becomes possible to connect neuronal anatomy to neuronal function and development. Recent work in adults has used this approach to connect adult behaviors to their neurogenic origins in late larva (Harris et al. 2015).

Drosophila larval locomotion is an excellent model to study rhythmic behavior. Stereotypic movements include turns, head sweeps, pauses, and forward and backward locomotion (Figure 1A) (Green et al. 1983). Larval forward and reverse locomotion is generated by abdominal somatic body wall muscle contractions moving from posterior to anterior (forward locomotion), or anterior to posterior (reverse locomotion) (Heckscher et al. 2012). Consecutive bouts of forward or backward waves are called runs (Figure 1B). Asymmetric contractions of thoracic body wall musculature generate turns (Lahiri et al. 2011). Neural control of turning movements is located within the thoracic and abdominal segments of the VNC (Berni 2015), while the CGPs that drive larval locomotion have also been shown to be located in the thoracic and abdominal segments of the VNC (Berni et al. 2012; Pulver et al. 2015). However, the specific neurons that comprise the CGP are currently unknown (Gjorgieva et al. 2013). Similarly, little is known about the neurons specifically used in other aspects of locomotion, such as forward or reverse movements, head sweeps, and pauses.

Here, we screen a collection of several hundred Gal4 lines that are sparsely expressed in the CNS to identify neurons that, when activated, can induce specific alterations in the larval locomotor program. The results presented here will provide the basis for future functional studies of motor control and neural circuit formation in Drosophila larva.

**MATERIALS AND METHODS**

**Imaging Gal4 expression patterns in whole first instar larvae**

For every Gal4 line, we imaged whole newly hatched “L0” first instar larvae, defined as between 0 and 4 hr of hatching, for native GFP fluorescence and nuclear red stinger fluorescence. We used a newly developed protocol to fix and stain intact larvae to confirm the expression pattern. Briefly, intact L0–L3 larvae were prepared for staining by incubating in 100% bleach for 10 min at room temperature (rt), digesting with chymotrypsin/collagenase for 1 hr at 37°C, fixing in 9% formaldehyde for 30 min at rt, incubating in 1:1 methanol:heptane for 1 min at rt, and postfixed in methanol for 1–3 d at −20°C (l. Manning and C.Q.D., unpublished data). Subsequently, standard methods were used for staining with chick anti-GFP (1:2000; Aves).

**Bright-field whole larva behavioral recordings**

All behavior was monitored using “L0” first instar larvae. Behavior arenas were made of 6% agar in grape juice, 2 mm thick and 5.5 cm in diameter. Temperature was measured using an Omega HH508 thermometer, with a type K hypodermic thermocouple directly measuring agar surface temperature. Temperature was controlled using a custom-built thermoelectric controller and pelier device. The arenas were placed under a Leica S8APO dissecting microscope and red light (700 nm, Metaphase Technologies) illuminated a single larva. The microscope was equipped with a Scion1394 monochrome CCD Camera, using Scion VisiCapture software. Images were acquired via ImageJ at either 4 Hz for low magnification videos, or 7.5 Hz for high magnification.

**TrpA1 screen**

Adult UAS-TrpA1 virgin females were crossed to males of select Janelia CRM-Gal4 lines that were kept in standard collection bottles (Genesee Scientific) and allowed to lay eggs on apple caps with yeast paste. For low magnification screening, a single larva was staged on a behavior arena, and given a 5–10 min period of acclimation. For recordings, larvae were permitted to crawl freely, and the stage was manually recentered when the larva left the field of view. Individual larvae were recorded at permissive (23°C) and restrictive (28°C) temperatures for 800 frames at 4 Hz.

**Quantification of crawl parameters**

We conducted two locomotion assays: low magnification for screening and high magnification in order to discern the etiology of crawl defects. For our initial low magnification screening, we calculated the speed of larval locomotion with automated analysis using custom Matlab scripts (Supplemental Material, File S1 and Table S1). Scripts were written in MATLAB and are available upon request.

**Object recognition:** For low magnification tracking an individual larva was detected in each frame using the following steps. The image was mildly blurred using a Gaussian blurring function to reduce background artifacts and make the appearance of the larva more uniform. The built-in MATLAB thresholding function utilizing Otsu’s method was used to segment the image. The image was then made binary and objects were morphologically closed. In each frame, a single object was selected as

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the larva based on an empirically determined and manually entered size. Built-in MATLAB functions were used to determine the larval object’s area and centroid position in each frame. The script returned no data if more than one object was found, or if no object was found.

Crawling speed: An approximate instantaneous speed was calculated by taking the distance traveled by the larval object between two consecutive frames and dividing by the time elapsed. All instantaneous speeds were then averaged to get an average crawling speed. If there was more than one behavioral recording for a given larva, data from up to three recordings were included. Standard deviation was then calculated. To exclude points in which the larva appeared to travel large distances due to manual repositioning of larva during behavioral recording, if the distance traveled by the larval object between successive frames was farther than half the length of the larva (see below), then the frames were excluded from speed calculations.

Larval length: The mean area of the larva was averaged to get "LarvalLen"; then, larval length was calculated as $\sqrt{\text{LarvalLen}/3.14}$.

Normalized data: Normalized values ($n$) refer to values for a given larva at restrictive (r) temperature, less the values for that larva at permissive (p) temperature, divided by values at permissive temperature $[n = (r - p)/p]$.

Test statistics: A built-in MATLAB function was used to run a 1-tailed, t-test assuming equal means but unequal variance ('ttest2' function).

Representation of slow hits: To represent lines that exhibited crawling defects at restrictive temperature, we chose two criteria to define slow crawls. First were those that were slow at restrictive compared to controls (students t-test), and second were those that did not increase their speed by the same rate when shifted from permissive to restrictive when compared to control (Students t-test). Average speed at restrictive temperature was then divided by that at permissive temperature.

High mag quantification: We calculated head sweeps, and forward and reverse wave propagation, manually.
Fly stocks
The following stocks obtained from the Bloomington Drosophila Stock Center (NIH P40OD108537) were used in this study: 10xUAS-IVS-myr::GFP (BL #32198), UAS-RedStinger (BL# 8546), UAS-TrpA1 (BL #26263), D42-Gal4 (BL #8816), OK6-Gal4, Mef2-Gal4 (BL #27390), repo-Gal4 (BL #7415), clav-Gal4 (BL #8760), EL-Gal4, RN2-Gal4 (BL #7470), CQ-Gal4 (BL #7466), OK371-Gal4 (BL #26160), GAD1-Gal4 (BL #51630), ple-Gal4 (BL# 8848), thr-Gal4 (BL# 38389), painless-gal4 (BL# 27894), iav-Gal4 (BL# 52273), nan-Gal4 (BL #24903), en-Gal4 (BL #1973), and pBDP-Gal4.Uw in attP2 (gift from B. D. Pfeiffer). Flies were raised on conventional cornmeal agar medium at 25°C.

Data availability
The authors state that all data necessary for confirming the conclusions presented in the article are represented fully within the article.

RESULTS
TrpA1 activation of sparse neuronal subsets results in slower, but not faster, larval locomotion
To identify neurons that can generate specific aspects of locomotor behaviors (pause, turn, forward, reverse, etc.), we screened Janelia CRM-Gal4 lines containing sparse expression patterns at either embryonic stage 16, or in newly hatched “L0” first instar larvae (0–4 hr after hatching) (Figure 1C). We began with 7000 CRM-Gal4 patterns; 4500 were screened at embryonic stage 16 with UAS-nls::GFP marking the cell nucleus, and 2500 were screened at first instar with UAS-myr::GFP, UAS-redstinger labeling the cell membrane and cell nucleus. From the initial 4500, we selected 75 patterns that had sparse expression patterns, and entered them into the eNeuro atlas (Heckscher al. 2014), which allows us to determine if they are motor neurons, interneurons, or glia. In addition to these 75 lines, we identified an additional 65 lines that had sparse embryonic VNC expression. A final 30 lines with sparse larval (L0) VNC expression were selected from the 2500 first instar expression patterns. We assayed newly hatched L0 larva behavior because it was closest in time to the stage where our Gal4 expression patterns were documented, making it less likely for the pattern to have changed; most embryonic Gal4 patterns are completely different by third larval instar (Manning al. 2012; Jenett al. 2012).

To assess the function of the neurons labeled by each of these Gal4 lines, we screened nearly 200 strains using the warmth-gated neural activator TrpA1 (Pulver al. 2009). In our assay regime, we monitored crawl speeds of individual newly hatched larvae at permissive temperature (23°C), and then at restrictive temperature (28°C). As with previous behavior experiments using JRC CRM-Gal4 constructs (Vogelstein al. 2014), we used larvae containing the ‘empty’ vector pBDP-Gal4U crossed to UAS-TrpA1 flies as our control; this transgene does not express TrpA1 in the VNC, and larva have normal locomotor velocities (Figure 1D, top). This is an appropriate control as the experimental Gal4 lines from the Rubin collection have a similar genetic background. We noted that control larvae increased their speed from 65.0 µm/sec at permissive temperature (+/− 47.0 SD, n = 10) to 98.7 µm/sec at restrictive temperature (+/− 66.3 SD, n = 10), or an increase of roughly 1.5-fold (Figure 1D, top).

Approximately 40% of lines we screened exhibited elements of crawl defects. We defined a genotype as slow by the following criteria: at restrictive temperature they were slower compared to controls (student t-test P < 0.05), and normalized permissive to restrictive change was statistically different (one-tailed student t-test P < 0.05). Of those lines that were slow, approximately half had uniquely evolvable behaviors that we describe below. We expected to elicit ‘fast’ crawl phenotypes; however, we detected only normal or slow phenotypes.

TrpA1 activation of sparse neuronal subsets generates multiple, distinct locomotor phenotypes
Control larva on naturalistic terrain exhibit pauses, head casts, turns, and forward and backward locomotion (Figure 1, A and B) (Green al. 1983; Riedl and Louis 2012), but in our assay they showed a strong bias toward forward locomotion, perhaps due to the temperature shift from 23°C to 28°C (Barbagallo and Garrity 2015) (Figure 2, A and A’). Each of the CRM-Gal4 UAS-TrpA1 lines we characterize below has a defect in the frequency or velocity of forward locomotion (Figure 1D, above), and, in this section, we describe each of the multiple, distinct locomotor phenotypes observed. We present the phenotype of one representative line in Figure 2, larval expression patterns for representative lines in each category are shown in Figure 3, and the cell type expression patterns for all lines in each category are shown in Figure 4.

Reverse: We found one line in this category; R53F07 (Figure 2, B and B’). Whereas control larvae normally display a range of movements (Figure 1, A and B), larvae in this category are strongly biased toward reverse locomotion. Forward propagating waves were generated occasionally, but they often failed to reach the anterior thoracic head region, instead switching prematurely to reverse waves.

Anatomical characterization shows both interneurons and motor neurons (Figure 3E and Figure 4), but many other lines contained motor neurons without showing the reverse locomotion phenotype. We also did not observe expression in any sensory neurons such as the Bolwig organ or Class IV MD neurons, which have been shown to play a role in the light-mediated aversive response (Xiang al. 2010). This suggests that the phenotype is due to activation of one or more interneurons in the pattern.

Immobile: We found 12 lines in this category, including R17C07 and 95A04, that showed expression only in interneurons (Figure 2, E and E’), and, in this section, we describe each of the multiple, distinct locomotor phenotypes observed. We present the phenotype of one representative line in Figure 2, larval expression patterns for representative lines in each category are shown in Figure 3, and the cell type expression patterns for all lines in each category are shown in Figure 4.

Rigid paralysis: We found four lines in this category, including R23A02 (Figure 2, D and D’). Hallmarks of this category include immobility, tonic contraction of all body segments, and shortening of larval body length. There was also a nearly complete lack of forward and reverse peristaltic waves. Larvae did not move when prodded, however, distinguishing this category from the next two “paralysis” categories.

Anatomical characterization shows sparse interneuron expression as well as a few lines with additional sensory neuron, motor neuron, or muscle expression (Figure 3G and Figure 4).

Delayed paralysis: We found one line in this category: R55B12 (Figure 2, E and E’). Larvae appeared identical to controls upon shifting to 28°C, but, over time, exhibited full tonic contraction paralysis (Figure 2C).

Larvae are sometimes observed recovering from this paralysis, but...
continue to cycle through paralysis periodically. Paralyzed larvae did not move when prodded.

Anatomical characterization showed expression of R55B12 restricted to neuropil “astrocyte” glia. A similar phenotype of “delayed paralysis” was obtained by crossing the glial-specific Repo-Gal4 line to UAS-TrpA1 and shifting to 28°C (data not shown), confirming that the phenotype is due to glial activation.

**Head cast:** We found one line in this category: R15D07 (Figure 2, F and F'). Larvae had a “zigzag” pattern of locomotion (Figure 2F) due to persistent head casting (Figure 2F). Whereas control larvae normally exhibit head casts as part of their exploratory program (Gomez-Marin et al. 2011), larvae in this category exhibited continuous head casts during crawls. High magnification time-lapse analysis reveals that posterior-to-anterior body wall muscle waves characteristic of forward locomotion still occurred in larvae of this category, but the larva often initiated a head cast prior to completion of the wave of muscle contraction (data not shown).

Anatomical characterization showed expression in interneurons in the brain and VNC, plus dorsally projecting motor neurons (Figure 3D and Figure 4). Because other lines contained dorsally projecting motor neurons without showing the head cast phenotype, we suggest the phenotype is due to activation of brain or VNC interneurons.

**Feeding:** We found three lines in this category: line R76F05 is shown in Figure 2G. Hallmarks of this category were a bias toward feeding behavior, including pharyngeal pumping, mouth hook movement, and head tilting. White arrowheads indicate rhythmic bubble ingestion (larva viewed ventrally). (H–I) Ventral contraction. Ventral contraction displays little movement and most extreme postures are pictured (larva viewed ventrally). (H–I) Dorsal contraction. Head and tail off the substrate illustrated in lateral view. (I–I') Ventral contraction. Ventral contraction displays little movement and most extreme postures are pictured (larva viewed ventrally). (H–I) Dorsal contraction. Head and tail off the substrate illustrated in lateral view.
Anatomical characterization showed that all lines had a sparse pattern of interneurons in the brain and VNC (Figure 3H and Figure 4); R21C06 showed additional expression in motor neurons, which is likely to be the cause of the additional rigid paralysis phenotype.

**Dorsal contraction:** We found 10 lines in this category; the R70H08 and R89F12 lines expressing only in sparse interneuronal patterns are shown in Figure 2H. This phenotype is characterized by the most anterior and posterior segments of the larva lifted vertically off the substrate when viewed laterally (Figure 2H). The phenotype varies in severity with some larvae permanently stuck with their thoracic head region and tail lifted up. At times, some continue crawling but periodically become stuck in this position. This phenotype may arise from premotor interneurons stimulating dorsal projecting motor neurons, and we have confirmed that TrpA1-induced activation of just two dorsal projecting motor neurons, aCC and RP2, is sufficient to generate a “dorsal contraction” phenotype (RN2-Gal4 UAS-TrpA1; data not shown).

Anatomical characterization showed many lines that had dorsally projecting motor neuron expression. Interestingly, there were lines that expressed in interneurons only and exhibited a similar phenotype (Figure 3C and Figure 4). These interneurons are strong candidates for excitatory interneurons that directly or indirectly specifically stimulate dorsal-projecting motor neurons. We also found a line (R65D02) with muscle expression in dorsal acute and dorsal oblique muscle groups that gave a similar phenotype (data not shown).
Ventral contraction: We found eight lines in this category; the R92C05 and R79E03 lines expressing only in sparse interneuronal patterns are shown in Figure 2I. Similar to the dorsal contraction phenotype, yet opposite in conformation, the ventral contraction phenotype was first discovered when we activated Gal4 patterns that expressed in ventrally projecting motor neurons (Nkx6, Hb9, and lim3B Gal4 lines; data not shown). When viewed laterally, the head and tail regions are ventrally contracted toward each other (Figure 2I). Similar to the dorsal contraction postural phenotypes, we saw a spectrum of severity, with some continually stuck with tonically contracted ventral muscles, while others would go through bouts of ventral contraction, then make attempts to crawl.

Anatomical characterization showed lines that had ventrally projecting motor neuron expression. Interestingly, there were lines that expressed in interneurons only and exhibited a similar phenotype (Figure 3F and Figure 4). These interneurons are strong candidates for excitatory interneurons that directly or indirectly specifically stimulate ventral-projecting motor neurons.

We also found two lines (R40D04, R33E02) with muscle expression in ventral acute, ventral oblique, and ventral longitudinal muscle groups that gave similar phenotypes (data not shown).

DISCUSSION

We identified a number of distinct behavior phenotypes elicited by activation of sparse subsets of neurons in the larval brain and VNC (Figure 5), but this is by no means an exhaustive exploration of TrpA1-induced larval phenotypes. As noted previously, roughly half of the statistically slow genotypes did not show any of the ‘overt’ phenotypic categories described in this paper. To fully characterize the remaining lines by phenotype would require advanced annotation of crawl dynamics and quantification of additional parameters. For example, upon high magnification observation of the slow hits, many simply appeared slow. Careful analysis by measuring wave duration and frequency may reveal additional phenotypes. Indeed, using refined analysis we investigated a slow line (R11F02), and discovered it was due to a defect in maintaining left-right symmetric muscle contraction amplitude during forward locomotion (Heckscher et al. 2015).

Recently developed larval tracking methods for multiplexed computational analysis would greatly assist the further definition of TrpA1-induced larval phenotypes. Examples of novel tracking methods include FIM, MaggotTracker, Multiple Worm Tracker, and iDTracker (Risse et al. 2013; Vogelstein et al. 2014; Pérez-Escudero et al. 2014; Aleman-Meza et al. 2015). For example, MaggotTracker can characterize aberrations in run distance, duration, strides, and many other abnormalities in crawl patterns not readily identifiable by human eyes. A study from Vogelstein et al. (2014) used the optogenetic effector Channelrhodopsin and Multiple Worm Tracker to screen third instar Drosophila larval Gal4 patterns, which yielded both fast and slow hits. Using unsupervised machine learning, they were further able to identify and cluster unique behavioral phenotypes or ‘behaviotypes’. Post hoc human analysis of these categories yielded four general categories consisting of still or back-up, turners, escape, turn-avoid, and as many as 29 refined subtype categories. Our study complements this investigation by describing additional categories, while also noting similar behaviotypes, such as head cast or turn, and immobile or still.

Many of the phenotypes we illustrated contained anatomical expression patterns with only interneurons, suggesting that those behavioral phenotypes were generated in the CNS. However, there were a large majority of lines that also expressed in tissues such as muscles, motor neurons, sensory neurons or glia. Many of these ‘off target’ neurons can be discounted; for example, it is highly unlikely that motor neuron activation induces the head cast, reverse, or feeding phenotypes because our extensive tests of Gal4 lines driving TrpA1 in subsets of motor neurons never produced such phenotypes. Of course, motor neuron expression can lead to complex phenotypes, such as a combination of feeding and paralysis phenotypes (R21C06) or reverse and dorsal contraction phenotype (R53F07).

Some phenotypic categories contained single Gal4 lines, whereas some categories had multiple Gal4 lines that generated a particular behavior. The latter could be due to multiple lines expressed in a
common neuron or pool of neurons—or due to several different neurons being able to produce the same phenotype (e.g., premotor and motor neurons). Further characterization of the expression patterns of lines with similar phenotypes will be necessary to resolve this question.

In the future it will be important to define the neurons within each Gal4 line expression pattern that generate a specific motor pattern. *Drosophila* genetic techniques have made it possible to restrict expression of Gal4 patterns to successfully identify individual neurons that generate a behavior. For example, stochastic flipping (Flood et al. 2013; Tasteckin et al. 2015), the FLP/FRT system (von Philipsborn et al. 2011; Sivanantharajah and Zhang 2015), and the split-Gal4 system (Luan et al. 2006; Aso et al. 2014; Bidaye et al. 2014) all allow subdivision of a Gal4 pattern. An intersectional technique has used the FLP/FRT system to successfully dissect the functional elements of the fru circuit (Yu et al. 2010; von Philipsborn et al. 2011), and we recently used the split Gal4 system to identify a subset of functionally relevant interneurons governing muscle contraction amplitude during forward locomotion (Heckscher et al. 2015). We are currently using these methods to characterize the neurons in the R53F07 pattern that can elicit reverse locomotion. Application of these methods should allow identification of the neuron(s) responsible for each of the eight locomotor phenotypes described in this article.

ACKNOWLEDGMENTS

We thank the reviewers for comments on the manuscript; Jimmy Kelly for help annotating ‘rigid paralysis’ phenotype; and the *Drosophila* Stock Center (Bloomington, IN, USA) and Todd Laverty at the JRC (VA, USA) for fly stocks. This work was supported by the APS Porter Physiology Development Fellowship (to M.Q.C) and the Howard Hughes Medical Institute, where C.Q.D. is an Investigator.

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