ABSTRACT

This paper presents our latest investigations on dialog act (DA) classification on automatically generated transcriptions. We propose a novel approach that combines convolutional neural networks (CNNs) and conditional random fields (CRFs) for context modeling in DA classification. We explore the impact of transcriptions generated from different automatic speech recognition systems such as hybrid TDNN/HMM and End-to-End systems on the final performance. Experimental results on two benchmark datasets (MRDA and SwDA) show that the combination CNN and CRF improves consistently the accuracy. Furthermore, they show that although the word error rates are comparable, End-to-End ASR system seems to be more suitable for DA classification.

Index Terms—dialog act classification, automatic speech recognition

1. INTRODUCTION

According to Austin’s theory [11], every utterance in a dialog has an illocutionary force, which causes an effect over the course of the conversation. Utterances can then be grouped into dialog act (DA) categories depending on the relationship between words and the meaning of the expression [2]. A DA conveys the intention of the speaker rather than the literal meaning of words for each utterance in a dialog.

Automatic DA classification is a crucial preprocessing step for language understanding and dialog systems. This task has been approached using traditional statistical algorithms, for instance hidden Markov models (HMMs) [3], conditional random fields (CRFs) [4], and more recently deep learning (DL) models, such as convolutional neural networks (CNNs) [5], recurrent neural networks (RNNs) [6, 7] and attention mechanism (AM) [8, 7], achieve state-of-the-art results.

Several works have shown that context, i.e. preceding utterances, plays an important role at determining automatically the DA of the current utterance [5, 7, 8]. This fact is also supported by the detailed analysis of the influence of context on DA recognition presented in [9], whose main conclusion is that contextual information helps the DA classification, as long as such information is distinguishable from the current utterance information.

In alignment with the aforementioned approaches, we present a model that employs preceding utterances and the current one. However, the particularity of this model relies on using a linear chain CRF on top of a CNN architecture to predict the DA sequence at utterance level. Using linear chain CRF layers on top of neural network (NN) models has been already introduced for sequence labeling tasks at the word level such as named entity recognition [10], part-of-speech tagging [11] or for joint entity recognition and relation classification [12].

To the best of our knowledge, all work on DA classification has been done using only manual transcriptions (MTs). Nonetheless, this type of data differs substantially from real data, i.e. automatic transcriptions (ATs), generated by automatic speech recognition (ASR) systems. In this paper, we explore the effect of training and testing the proposed model on ATs. Our goal at this point is to bring the DA classification task into a more realistic scenario.

In sum, we introduce a model that combines CNNs and CRFs for automatic DA classification. We train and test our model on different scenarios to contrast the effect of using manual and automatically generated transcriptions from two different ASR architectures (hybrid time-delay neural network (TDNN)/HMM and End-to-End (E2E) ASR systems). Our results show that the combination of CNNs and CRFs improves consistently the accuracy of the model achieving state-of-the-art performance on MRDA and SWBD. Furthermore, results on ASR outputs reveal that, although word error rates (WERs) are comparable, the E2E ASR system seems to be more suitable for DA classification.

2. DIALOG ACT CLASSIFICATION

The DA classification model proposed in this paper, depicted in [Figure 1], consists of two parts: a CNN that generates vector representations for consecutive utterances and a CRF that performs DA sequence labeling.
2.1. Utterance representation

Based on [8], the grid-like representations of the current utterance and \( n \) previous ones are concatenated and used as input for a CNN that generates a vector representation for each of the utterances.

CNNs perform a discrete convolution using a set of different filters on an input matrix, where each column of the matrix is the word embedding of the corresponding word. We use 2D filters \( f \) (with width \(|f|\)) spanning over all embedding dimensions \( d \) as described by the following equation:

\[
(w * f)(x, y) = \sum_{i=1}^{d} \sum_{j=|f|/2}^{d} w(i, j) \cdot f(x - i, y - j)
\]

After convolution, an utterance-wise max pooling operation is applied in order to extract the highest activation. Then, the feature maps are concatenated resulting in one vector per utterance that is represented in Figure 1 as \( p_{t-2}, p_{t-1} \) and \( p_t \).

2.2. CRF-based DA sequence labeling

Given that a dialog is a sequence of utterances, we approach DA classification as a sequence labeling problem. Therefore, we employ CRFs for this task. The first step is to generate the score vectors, depicted in Figure 1 as \( s_{t-2}, s_{t-1} \) and \( s_t \), by the means of a linear function in each time step \( t \):

\[
s_t = W p_t + b
\]

where \( W \) (weight matrix) and \( b \) (bias) are trainable parameters. Using score vectors as input we perform sequence labeling with a CRF layer.

CRFs are probabilistic models that calculate the likelihood of a possible output \( y \) given an observation \( s \). They are commonly represented as factor graphs, in which each factor computes the aforementioned likelihood. Mathematically, each factor graph is defined as:

\[
p(y|s) = \frac{\prod(\phi(s, y))}{Z(s)}
\]

where \( Z(s) \), a normalization function, is the sum of all possible outputs for each observation \( s \).

To perform sequence labeling, we consider a linear chain CRF. Analogous to Equation 3, the probability of an output sequence \( \hat{y} \) given a sequence of observations \( s \) is:

\[
p(\hat{y}|s) = \frac{\prod(\phi(s, y), \phi'(y, y'))}{Z(s)}
\]

In Equation 4, not only the factors associating input and output \( \phi \) are calculated, but also the likelihood between adjacent labels \( \phi' \), where \( y \) and \( y' \) are neighbors. In this case the normalization function \( Z \) takes the sequence \( s \) as input.

3. AUTOMATIC SPEECH RECOGNITION

In recent times, deep learning techniques have boosted the ASR performance significantly [13]. In this section, we introduce the two types of ASR architectures used to generate ATs.

3.1. Hybrid TDNN/HMM architecture

In hybrid ASR systems, NNs are used to predict emission probabilities of HMM given speech frames. Recently, various DL models have been proposed and developed to improve ASR performance. Most of them are variations of CNNs or RNNs [13, 14]. [15] presented a hybrid TDNN/HMM system trained with lattice-free maximum mutual information, which is fast to train and outperforms significantly other models on many ASR tasks. To the extent of our knowledge, it is one of the best hybrid ASR systems available for research and thus was selected for our experiments.

3.2. End-to-End architecture

More recently, an E2E architecture was introduced, which simplifies the training process and achieves competitive results in several benchmark datasets [16]. Many studies have proposed E2E architectures based on either connectionist temporal classification (CTC) [17] or AM [18].

ESPnet, an End-to-End speech processing toolkit, benefits from two major E2E ASR implementations based on CTC and attention-based encoder-decoder network [16]. It employs the multiobjective learning framework to improve robustness and achieve faster convergence. For decoding, ESPnet executes a joint decoding by combining both attention-based and CTC scores in a one-pass beam search algorithm to
eliminate irregular alignments. The training loss function is defined in Equation 5, where \( L_{\text{ctc}} \) and \( L_{\text{att}} \) are the CTC-based and attention-based cross entropy, respectively. \( \alpha \) is the tuning parameter to linearly interpolate both objective function.

\[
L = \alpha L_{\text{ctc}} + (1 - \alpha) L_{\text{att}}
\]

During beam search, the following score combination with attention \( p_{\text{att}} \) and CTC \( p_{\text{ctc}} \) log probabilities is performed

\[
\log p_{\text{hyb}}^{\text{high}}(y_n|y_{1:n-1}, h_{1:T'}) = \alpha \log p_{\text{ctc}}^{\text{high}}(y_n|y_{1:n-1}, h_{1:T'}) + (1 - \alpha) \log p_{\text{att}}^{\text{high}}(y_n|y_{1:n-1}, h_{1:T'})
\]

where \( y_n \) is a hypothesis of output label at position \( n \) given a history \( y_{1:n-1} \) and encoder output \( h_{1:T'} \) \cite{16}.

### 4. EXPERIMENTAL SETUP

#### 4.1. Data for DA classification

We evaluate our model on two DA labeled corpora: 1) MRDA: ICSI Meeting Recorder Dialog Act Corpus \cite{19,20,21}, a dialog corpus of multiparty meetings. The 5-tag-set used in this work was introduced by \cite{22}, and 2) SwDA: NXT-format Switchboard Corpus \cite{23}, a dialog corpus of 2-speaker conversations.

Train, validation and test splits on both datasets were taken as defined in \cite{5}. Table 1 presents statistics about the corpora. Both datasets contain a highly unbalanced distribution of classes. The majority class is 59.1% on MRDA and 33.7% on SwDA.

| Dataset | C | V | Train | Validation | Test |
|---------|---|---|-------|------------|------|
| MRDA    | 5 | 12k | 78k   | 16k        | 15k  |
| SwDA    | 42 | 20k | 193k  | 23k        | 5k   |

Table 1. Data statistics. C: number of classes, |V|: vocabulary size and Train/Validation/Test: number of utterances.

#### 4.1.1. Hyperparameters and training

In Table 2 we present the model hyperparameters for both corpora. Most of them were taken from \cite{8}. However we tuned the optimizer, the learning rate and the mini-batch size. We found the most effective hyperparameters by changing one at a time while keeping the others fixed based on the model performance on the validation split.

Training was done with context length \( n \) ranging from 1-5. After tuning different stochastic learning algorithms with several learning rates, stochastic gradient descent (SGD) \cite{24} seemed to work best on MRDA and adaptive gradient algorithm (AdaGrad) \cite{25} on SwDA. The learning rate was initialized at 0.01 on MRDA and 0.07 on SwDA. Any kind of parameter tuning was done only on the validation split. Word vectors were initialized with the 300-dimensional pretrained word vectors from word2vec \cite{26} and fine-tuned during training.

| Hyperparameter | MRDA | SwDA |
|----------------|------|------|
| Activation function | ReLU |      |
| Dropout rate | 0.5  | 0.5  |
| Filter width | 3, 4, 5 | 3, 4, 5 |
| Filters per width | 100 | 100 |
| Learning rate | 0.01 | 0.07 |
| Mini-batch size | 70 | 170 |
| Optimizer | SGD | AdaGrad |
| Pooling size | utterance-wise |      |
| Word embeddings | word2vec (dim. 300) |         |

Table 2. Hyperparameters.

#### 4.2. Data for automatic speech recognition

We employed KALDI \cite{27} to build the hybrid TDNN/HMM ASR system. In the recipe, 40 Mel-frequency cepstral coefficients (MFCCs) were computed at each time step and each frame was appended a 100-dimensional iVector to the 40-dimensional MFCC input. Speaker adaptive feature transform techniques and data augmentation techniques were implemented. The Gaussian Mixture Model (GMM)/HMM system generated the alignments for NN training \cite{15}. For the Switchboard Dialog Act Corpus (SwDA) dataset, we interpolated the 3-gram language model trained on the transcriptions and the 4-gram Fisher model \cite{28}. For ICSI Meeting Recorder Dialog Act Corpus (MRDA), we employed a 3-gram language model trained on the MTs.

End-to-End Speech Processing Toolkit (ESPnet) was used to build the E2E ASR system. The 80-bins log-mel filterbank features with speed-perturbation were used to train the VGG+BLSTM model with five layers encoder with 1024 units and one layer decoder with 1024 units \cite{16}. The language model utilized 100 subword units based on byte-pair-encoding technique, which seems to perform better than the character-level language model \cite{29}.

Both hybrid TDNN/HMM and E2E ASR systems were trained on the same train and validation splits and were later used to generate the automatic transcriptions of all splits (train, validation and test) for the DA classification model. Table 3 shows the performance of hybrid TDNN/HMM and E2E ASR systems on seen (train and validation splits) data and on unseen data (test split) for SwDA and MRDA.

### 5. EXPERIMENTAL RESULTS

#### 5.1. Experiments on manual transcriptions

Table 4 shows the results from a baseline model and our proposed model trained on MTs with context length varying from
Table 3. ASR performance in WER(%) on train, validation and test splits from SwDA and MRDA.

| Dataset | ASR System | Train WER | Validation WER | Test WER |
|---------|------------|-----------|----------------|----------|
| SwDA    | TDNN/HMM   | 13.8      | 14.29          | 18.02    |
|         | E2E        | 2.90      | 8.90           | 18.80    |
| MRDA    | TDNN/HMM   | 9.89      | 19.28          | 21.48    |
|         | E2E        | 2.30      | 16.80          | 18.80    |

Table 4. Baseline model and proposed model’s accuracy (%). For the latter we report for contexts from 1 to 5. Results appear like average (minimum, maximum) calculated on 5 runs.

| Context | MRDA | SwDA |
|---------|------|------|
| 0 (baseline) | 80.2 (80.4, 80.0) | 72.0 (72.2, 71.6) |
| 1 | 84.6 (84.6, 84.5) | 74.1 (74.3, 74.0) |
| 2 | 84.7 (84.6, 84.7) | 74.6 (74.5, 74.8) |
| 3 | 84.6 (84.5, 84.6) | 74.5 (74.2, 74.8) |
| 4 | 84.7 (84.4, 84.8) | 74.1 (73.6, 74.6) |
| 5 | 84.6 (84.4, 84.8) | 74.2 (73.8, 74.5) |

Table 5. Accuracy (%) of the model trained on MTs with context 2 and tested on MTs and ATs.

| Transcriptions | MRDA | SwDA |
|----------------|------|------|
| MTs            | 84.7 (84.6, 84.7) | 74.6 (74.5, 74.8) |
| TDNN/HMM       | 59.2 (58.9, 59.7) | 65.7 (65.4, 66.0) |
| E2E            | 66.1 (65.7, 66.3) | 67.4 (66.6, 67.9) |

Table 6. Accuracy (%) of the model trained on TDNN/HMM transcriptions with context 2 and tested on MTs and ATs.

| Transcriptions | MRDA | SwDA |
|----------------|------|------|
| MTs            | 70.9 (68.3, 72.7) | 66.6 (65.3, 70.0) |
| TDNN/HMM       | 73.2 (71.2, 73.3) | 67.1 (66.2, 67.6) |
| E2E            | 76.6 (75.5, 76.7) | 68.7 (68.4, 69.0) |

Table 7. Accuracy (%) of the model trained on E2E transcriptions with context 2 and tested on MTs and ATs.

| Transcriptions | With punctuation | Without punctuation |
|----------------|------------------|---------------------|
| MRDA transcriptions | 84.7 (84.6, 84.7) | 81.3 (81.1, 81.5) |
| TDNN/HMM         | 59.2 (58.9, 59.7) | 69.3 (69.3, 69.4) |
| E2E              | 66.1 (65.7, 66.3) | 76.2 (76.0, 76.4) |

Table 8. Accuracy (%) of the model with context 2 trained on MRDA’s MTs without punctuation and tested on MTs and ATs.

It can be seen from Table 8 that punctuation is a strong cue for DA classification. Nonetheless, it leads to a high negative impact while testing on AT without punctuation. If MTs are used to train a model, it is advisable to remove punctuation. According to our results, by doing this a 10% improvement in accuracy terms is achieved on both ASR transcriptions of MRDA.

6. CONCLUSION

We explored dialog act classification on MTs with a novel approach for context modeling that combines CNNs and CRFs, reaching state-of-the-art results on two benchmark datasets (MRDA and SwDA). We also investigated the impact of ATs from two different automatic speech recognition systems (hybrid TDNN/HMM and End-to-End) on the final performance. Experimental results showed that although the WERs are comparable, the End-to-End ASR system might be more suitable for dialog act classification. Moreover, results confirm that punctuation yields central cues for the task suggesting that punctuation should be integrated into the ASR output in future works.
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