Production of Few-Layer Graphene in Synthetic Oil Using a Rod Drum Mill

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Abstract

The article analyzes the methods of obtaining few-layer and multilayer graphene in machines where the main working body is a smooth rotating drum. Possible mechanisms for separating crystalline graphite particles are considered. The method of graphite exfoliation only due to shearing forces is viewed as the most economical one. A new design of the rod mill where only shearing forces affect graphite particles was introduced. The results of experimental studies on the influence of geometrical and mode parameters on the intensity of the shear exfoliation process are presented. The dependence for calculating the performance of a rod drum mill was obtained. A parametric series of mills with a capacity for few-layer and multilayer graphene from 0.077 to 0.884 g/h was developed.

Keywords

Few-layer graphene; shear exfoliation; light transmission coefficient; performance; parametric series.

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Introduction

Starting from the second half of the nineteenth century, grinding in ball drum mills has been widely used in various industries. Currently grinding using balls is one of the largest industries in the world [1]. A little later, planetary mills were invented, but the rotating drum and spherical grinding bodies also play the main roles in the grinding process. Moreover, since the gravitational force field acting on particles of material in traditional drum mills and the field of centrifugal forces acting on particles in planetary mills are potential fields, it can be assumed that the movement modes of the material and grinding bodies in drum and planetary mills are similar. The intensity and efficiency of grinding depends on the mode of movement of the grinding balls and material in the cross section of a rotating drum. The movement modes of the material in the cross section of the drum (Fig. 1) are avalanching, slumping, rolling, cascading, cataracting, and centrifuging. In practice, two modes are used more often than others, i.e. cascading [3, 4] and cataracting [5, 6]. The cascade or circulation mode is usually used in mixers [7 – 10], granulators [11 – 14], classifiers or screens [15], cement kilns [16, 17], general issues of the bulk material movement in rotating drums are discussed in [18, 19]. In the circulation mode of movement [20], the bulk material in the cross section of a smooth rotating drum forms a closed circulation loop. Part of the material particles rises up together with the rotating drum shell, forming a “rising layer”, while another part of the particles rolls down forming a “rolling layer”. Many researchers in the mathematical description of the material particles movement process make the assumption that the boundary between the rising and sliding layers is symmetrical about the circulation center. This assumption is correct only in the transition from a periodic collapse mode (slumping mode) to a circulation mode (cascading mode).

In fact, the specified boundary is clearly asymmetric, relative to the center of circulation (cascading mode, Fig. 2).
Different mathematical models are used to describe the bulk material movement in the cross section of a smooth rotating drum [21 – 24]. The main disadvantage of these models lies in the complexity of the experimental determination of numerous parameters. In [20], the energy approach adequately describes the distribution of the material and calculate the movement parameters of particles with a minimum of assumptions was proposed [25].

Analysis of the grinding process in smooth rotating drums

Machines, the main working body of which is a smooth rotating drum, are widely used for grinding different materials. First of all, these are ball drum mills and ball planetary mills.

Grinding building materials, such as gypsum, is used for thousands of years. In particular, gypsum was used in the construction of the pyramids, in about 3700 BC. Gypsum is found on all continents of the world and is one of the leaders among construction materials [26]. In this work, the effect of mode parameters on the intensity of gypsum grinding in drum ball mills was studied. Gypsum is widely used as special fillers, additional white pigment, fertilizer in agriculture, a binder of various building materials, as well as in dentistry. In all these industries, gypsum is needed in an ultra-fine ground form [27].

For a long time, the processes of grinding, in particular in ball mills, were subjected to statistical and kinetic analysis [28, 29], especially widely used ball mills in the mining industry [30]. The traditional forms of the grinding bodies are balls and rods [31]. Studying the behavior of the grinding load and the effect of the balls on the material particles allows us to determine the conditions in which the grinding bodies have the maximum effect on the material and ensure the maximum performance of the mill [32]. In [26], the effect of drum rotation speed, drum fill factor with grinding balls, ball size, material fill factor of a drum, particle size distribution of grinding balls and material particles, as well as the grinding time on the grinding intensity and grain size of the finished material was investigated. Studies were performed on a laboratory stainless steel ball mill with a drum diameter of 200 mm and a drum length of 200 mm. The grinding bodies were stainless steel balls with a density
of 8000 kg/m³ and with three different diameters (2, 3 and 4 cm). Gypsum ore was used as a grinding material. Pre-ore was ground in a jaw crushe r to a maximum size of -2 mm. Methods for describing particle size distributions, which take into account not only the width of the size distribution [33], but also the “slope” of the particle size distribution curve [34] are of particular interest in this study. The concepts “wide” and “narrow” or “steep” particle size distribution curve are used [35]. This approach is more informative than the traditional one. The rotation speed of the drum varied from 50 to 90 % of the critical speed, which is equal to:

\[ \omega_{ct} = \sqrt{g/R}, \]

where \( g \) is the acceleration of gravity, 9.81 m/s², \( R \) is the inner radius of the drum, m.

Experimental results showed that the most intensive grinding occurs at speeds of the drum rotation from 80 to 90 % of the critical speed. Since at a speed of 80 % of the critical speed, the energy consumption is substantially less, it is this speed that the authors recommend for industrial production.

In the past two decades, more adequate models have been developed using the finite element method, describing the movement and configuration of the loading circuit of grinding bodies in drums. However, finite element methods currently do not imitate the actual behavior of the particles to be ground and the effect of the particles on the balls movement; therefore, the true results of grinding are not predictable. The authors of [36] distinguish three main zones in the cross section of the drum: the grinding zone, where the balls collide with each other and crush the particles that fall into the collision zone; the ascending zone where the balls move up along the wall of the mill; the drop zone where the balls are in free fall. In fact, grinding occurs only in one zone. It is noted that if the material is small, the particles occupy the free space between the grinding balls. The balls fall on the balls located at the bottom and the grinding does not occur, because there are no material particles in the area where the balls hit. The paper presents the results of comparing calculations with experimental data obtained by other researchers. The influence of different parameters on the grinding intensity is analyzed. Despite the importance of this work for the theory and practice of grinding, it does not provide specific recommendations. Analyzing the influence of the balls diameter on the grinding process, it is noted that with an increase in the diameter, the impact energy increases, but at the same time the number of areas of simultaneous collision of the balls decreases. As the degree of the drum filling with grinding balls increases, the number of grinding zones increases, but at the same time the impact energy decreases, as the height of the falling balls decreases.

In conclusion, it should be noted that a grinding theory has been developed, which is based on the dispersion coefficient and the Peclet number in a continuous ball mill. The dispersion coefficient was expressed by statistical parameters taking into account the random walk of balls and particles. Then the statistical parameters were determined taking into account the geometrical and operational parameters of the mill. The obtained equations showed that the dispersion coefficient is a function of the dispersion zone size and the mobility of the balls in the grinding zone. The mobility is characterized by an average speed and free path. The results obtained from the theory agree with the experiment. In addition, the theory predicted a significant effect of the length and diameter of the mill, not only on productivity, but also on the quality of grinding. The results of this work are very useful in designing drum mills.

**Obtaining graphene structures in planetary mills**

After the discovery of the electric field effect in graphene in 2004 [37], the academic community was very interested in this material. Graphene has great potential for use in many areas due to its excellent thermal conductivity [38, 39]. Much effort was made to obtain graphene with one or several layers, including micromechanical separation of highly ordered pyrolytic graphite oxide [40], chemical vapor deposition [41, 42], separation of the graphite liquid phase [43 – 45], epitaxial growth [46], thermal peeling [47]. In [48], to obtain graphene structures, hexagonal graphite (HG) powders were used as a raw material. The HG powders were dried at 75°C for 2 hours in an oven. Then the dehydrated HG powders were ground in a Fritsch Pulverisette Premium line 7 laboratory planetary mill using balls with a diameter of 19 mm at 400 rpm for 50 hours. The powders obtained after the grinding process were mixed with saturated acids, H₂SO₄ and HNO₃, for 12 hours using a magnetic stirrer. The powder mixture filtered from the acidic mixture was irrigated with distilled water until its pH was neutral. The powder obtained at the end of this process is called graphite intercalating compound (GIC). GIC was heated to 950°C to obtain expanded graphite (EG). EG is a structure in which the distance between the layers is increased compared to the original graphite, but the layers are still connected to each other by peder-Waals bonds. EG was mixed in N, N-dimethylformamide (DMF) using an ultrasonic
homogenizer (Bandelin Sonoplus, model HD 3200, 200 W, at 50% power, i.e. 100W) for 2 hours. Next, the EG suspension in DMF with a concentration of 0.05 mg/ml was prepared. Then the mixture was centrifuged at 5000 rpm for 8 hours to remove DMF. The powders were sprinkled with ethanol and dried in a vacuum oven at 75 °C for 4 hours to remove alcohol. The results of studies using high-resolution transmission electron microscopy (HRTEM, JEOL Jem 2100F), Raman spectroscopy (Witecsnom-Raman) using 532 nm laser excitation through a 100-fold objective and thermogravimetric analysis (TGA) of the samples showed that most of graphite has passed into an amorphous state as a result of strong shock influences. Fig. 3 shows TEM images of the resulting graphene sheets.

The photographs show graphene nanoplates found in each product area obtained as a result of the liquid-phase exfoliation method in a spherical planetary mill. Fig. 3a and 3b display a lot of sheets with several nanometers thickness. The width of these sheets reaches several micrometers. Electron diffraction (ED), shown in Fig. 3d, confirmed the crystallinity of the graphene structure. However, when the ED pattern was examined, it could also be argued that there were disordered areas in the structure. The inner parts of the layers and even partially the entire layer had disordered structures. The dark colored particles were present in graphene layers or and areas close to them in all TEM images shown in Fig. 3. These particles were amorphous carbon structures. It was previously stated that partial amorphization occurs during HG grinding. X-ray diffraction analysis carried out at the end of the grinding process also showed that amorphization was present in HG.

Fig. 3. TEM micrographs (a – c); Electron diffraction pattern of synthesized pectros layers (d) [48]
The Raman spectroscopy is an effective method used to characterize carbon materials, both with an ordered and disordered crystalline structure. In addition, this method allows us to analyze the thickness of graphene nanolayers. Fig. 4 shows the Raman spectra of HG, EG and synthesized graphene milled layers.

Fig. 3 presents characteristic peaks found in the Raman spectra of carbon materials. Among these peaks, the peak of the “D” band was observed at about 1350 cm⁻¹. This peak was an indicator of defects found within the structure. A peak that is visible at about 1600 cm⁻¹ is the peak of the “G” band. Carbon atoms linked by the sp² bond are marked at this peak. In other words, it was a graphite array indicator. The “2D” peak is observed at approximately 2700 cm⁻¹. It is this peak that is used to determine the number of layers in multilayer structures. The intensity of the characteristic peaks in the Raman spectra of a sample obtained after 50-hour HG grinding is relatively low (Fig. 4). This situation indicates that amorphous carbon prevailed throughout the structure at the end of the 50-hour grinding.

In [49], high productivity was achieved in the production of few-layer graphene (≤5 layers) by treating wood graphite in a planetary ball mill in the presence of dry ice for 48 hours. The resulting product has a high dispersibility in various solvents. The findings confirm the possibility of obtaining graphene as a result of shear effects on graphite without oxidizing the original graphite. In our opinion, one of the most promising areas of graphene production on an industrial scale is liquid-phase shear exfoliation in a drum mill, especially since there are examples of how to obtain nanoscale particles in ball drum mills [50].

Each crystalline graphite particle is a deck in which the cards are graphene sheets one carbon thick. The number of graphene sheets is different and can vary from hundreds to several thousand. If the reduction of graphene layers in graphite particles is considered as the final result of the exfoliation process, then it can be stratified only in two ways: tear one particle from another or move one particle relative to another. In the work [51] on the basis of molecular modeling, the delamination scheme shown in Fig. 5 was proposed. It should be noted that the substrate is taken only for clarity and instead you can use the second graphene sheet.

For this diagram of force and delamination variants, according to the laws of classical mechanics, the minimum force at which delamination can occur corresponds to the shear mechanism. The authors introduced the slip coefficient λ, the numerical value of which is determined by the following expression:

$$\lambda = l/(l + 1d).$$  (2)

At $\lambda = 1$, lateral sliding is absent ($d = 0$) and only vertical peeling of the 2D material occurs; at $\lambda = 0$ ($\alpha = 0$), purely lateral sliding without vertical delamination occurs. Fig. 6 shows the action zones of the separation and shear mechanisms ($b$ is the width of the graphene plate).

Thus, it is necessary to create a structure in which only shearing forces will be transmitted to the particle, without any effort of separation.
Rod drum mill for graphite liquid-phase shift exfoliation

Fig. 1 shows that in a drum mill it is possible to organize a mode in which material periodically slides along the inner surface of the drum (slumping mode). The ability to organize such a mode for grinding balls was theoretically proved in [52], and experimentally confirmed in [53]. This paper establishes that some balls moving downward rotate without sliding relative to the inner surface of the drum. Initially, the production of graphene structures in the graphite grease was implemented in a laboratory planetary mill made in accordance with [54]. The study of the tribological characteristics of the graphite grease processed in a new design of the planetary mill showed that due to the formation of graphene structures all the characteristics have improved. In particular, the friction coefficient decreased by 1.5–2 times [55]. It was also experimentally established that graphene increases the viscosity of the dispersion medium [56], therefore, when preparing greases, less thickener is required. Thus, the use of graphene is one of the promising methods for the commercial production of environmentally friendly grease [57].

Studies have been conducted on the replacement of grinding balls with rods, which made it possible to significantly increase the contact zone of the grinding bodies with the drum, i.e. increase the area of the zone in which the separation of graphite particles is possible. Taking into account the above circumstances, a new design of a rod drum mill [58] was developed to obtain graphene suspensions in an oil base. The principal difference of this design is that the rods slide relative to the inner surface of the drum and on the particles that fall into the contact zone between the rods and the drum. Only shear forces are applied.

Experiment, findings and discussion

To obtain graphene suspensions, a laboratory drum mill with grinding rods was used, which were interconnected, as shown in Fig. 7. Video recording of the rods movement in the cross section of a smooth rotating drum showed that the rods interconnected by a flexible cable, as well as the free rods, periodically move upwards together with the drum and then slide down to the starting position. Shift effects on particles can occur only when the rods slide down. It was established experimentally that the time of the rods upward movement and the time of the rods sliding down are almost the same. Thus, during the time \((T)\) when the material and rods stay in the rotating drum, the graphite particles are stratified during the time \((T_E)\) which is at best half the time \(T\). To eliminate this drawback, the rods were connected to the fixed base using a bracket. Similarly, rods were fixed in a laboratory setup with a drum diameter of 140 mm and a length of 100 mm. During the experiments, the angular velocity of the drum rotation was changed from 56 to 141 rpm, which is from 0.5 to 1.25 from \(\omega_{cr}\), but remained constant throughout one experiment.

Steel rods with a diameter of 8, 10 and 12 mm were used. Studies were performed as follows. The initial suspension by mixing synthetic oil 5W40 and graphite powder GSM-2 was prepared. The graphite concentration \((C_O)\) was changed from 5 to 20 wt. %. The suspension was loaded into the drum where there was a certain number of rods with a certain diameter. The number of rods (interconnected) was changed from 4 to 12. Every 3 hours the drum rotation was turned off and 3 samples were taken for analysis. The intensity of graphene structures formation was estimated from the change in the transmittance coefficient \(K\), the numerical value of which characterizes the average integral number of layers in graphite particles [59]. This type of analysis requires a small amount of samples, which is very important for laboratory research. Fig. 8 shows the characteristic dependences of the coefficient \(K\) on time. In this case, for dependence 1: the angular velocity of the drum rotation \((\omega)\) was equal to 11.8 s\(^{-1}\) (1.0 \(\omega_{cr}\), for dependence 2: \(\omega = 5.9\) s\(^{-1}\) (0.5 \(\omega_{cr}\), for dependence 3: \(\omega = 14.2\) s\(^{-1}\) (1.2 \(\omega_{cr}\), and the graphite concentration in the initial suspension \(C_O = 10\) wt. % for all variants.
The graph shows that at the beginning of the process the dependences can be considered linear, and the intensity of the process increases in direct proportion to the increase in the rotational speed. Fig. 9 presents the characteristic dependences of the coefficient $K$ on time, with different graphite concentrations in the initial suspension. The rotation speed of the drum was $11.8 \, \text{s}^{-1}$, but for dependence 1: $C_0 = 10 \, \text{wt.\%}$, and for dependence 2: $C_0 = 5 \, \text{wt.\%}$. The graph displays that the obtained dependencies are similar to those shown in Fig. 9, i.e. at the beginning of the process the dependencies can be considered linear, and the intensity of the process increases in direct proportion to the increase in the graphite concentration in the initial suspension. When a certain concentration of few-layer and multilayer graphene, about 6–7 mg/ml, is reached in suspension, the intensity drops sharply and asymptotically approaches its limiting value. In obtaining the dependences that are necessary to predict the intensity of the liquid-phase shear exfoliation process, the initial period of the process is of interest. As the analysis of numerous experiments has shown, with various combinations of mode and geometric parameters, the time during which the intensity drops and the content of graphene structures in the suspension reaches the limiting values is no more than 20 % of the total processing time of the initial suspension. It was also found that the optimal number of rods is one-fourth of the drum circumference located in the lower quadrant in the direction of the drum rotation. The pronounced dependence of the process intensity on the diameter of the rods during the experiments was not revealed. Perhaps this issue will be resolved when conducting research on a drum with a substantially large radius.

First of all increasing speed of the drum rotation leads to increasing the path that the graphite particles go through being in the contact zone of the rods with the drum inner surface. Therefore, it is logical...
to assume that the intensity of the process will be directly proportional to the radius of the drum. Taking into account the above justifications, the intensity of the exfoliation process and, ultimately, the performance of the rod mill \((Q)\) can be represented as follows:

\[
Q/Q_L = kC_L[(R/R_c)(L/L_c)(C_0/L_c)(\omega/\omega_c)],
\]

where \(k\) is a dimensionless coefficient of proportionality, the numerical value of which depends on the characteristics of the oil base.

The influence of the coefficient of filling the drum with a suspension, as a result of the experiments performed, was not revealed. The coefficient of filling the drum with suspension \((\xi)\) is numerically equal to:

\[
\xi = V_S / V_D,
\]

where \(V_S\) is the volume of the suspension, \(V_D\) is the volume of the drum.

As \(\xi\) increases, the volume of the suspension in the drum increases, but the number of particles in the shear zone does not change. Basis on this, with respect to the total volume of the suspension, an increase in the few-layer and multilayer graphene concentration per time unit will decrease in direct proportion to the increase in \(\xi\). However, the absolute value of the mass of these particles, and hence the performance, does not depend on \(\xi\).

The dependence (3) includes all the main geometrical and mode parameters that characterize the mill and the exfoliation process. To test the possibility of using this dependence when designing rod mills, the numerical value of \(Q_L\) was experimentally determined with the following parameters of the laboratory mill: radius \(R = 70\) mm; \(L = 100\) mm; \(C_{OL} = 10\) wt. %; \(\omega_L = \omega_c\); \(\xi_L = 0.1\). As a result of processing the experimental data, a value of \(Q_L = 0.064\) g/h was obtained, with few-layer and multilayer graphene concentration in suspension. After centrifugation and removal of sediment \(C_L = 6.4\) wt.% and light transmission coefficient \(K = 2.6\).

The verification of the adequacy of the dependence (3) was checked by comparing the calculation results with the experimental data. Experimental values \(Q\) were determined in laboratory setups with the drum diameters of 140 and 200 mm for the following combinations of parameters:

- \(1 - R = 70\) mm; \(L = 100\) mm; \(C_{OL} = 5\) wt. %; \(\omega_L = 0.5\ (\omega_c); \xi_L = 0.13\)
- \(2 - R = 70\) mm; \(L = 100\) mm; \(C_{OL} = 10\) wt. %; \(\omega_L = 0.5(\omega_c); \xi_L = 0.1\)
- \(3 - R = 70\) mm; \(L = 100\) mm; \(C_{OL} = 10\) wt. %; \(\omega_L = 0.5(\omega_c); \xi_L = 0.13\)
- \(4 - R = 70\) mm; \(L = 100\) mm; \(C_{OL} = 10\) wt. %; \(\omega_L = 0.5(\omega_c); \xi_L = 0.13\)
- \(5 - R = 100\) mm; \(L = 120\) mm; \(C_{OL} = 5\) wt. %; \(\omega_L = 0.5(\omega_c); \xi_L = 0.13\)
- \(6 - R = 100\) mm; \(L = 120\) mm; \(C_{OL} = 10\) wt. %; \(\omega_L = 0.5(\omega_c); \xi_L = 0.1\)
- \(7 - R = 100\) mm; \(L = 120\) mm; \(C_{OL} = 10\) wt. %; \(\omega_L = 0.5(\omega_c); \xi_L = 0.1\)
- \(8 - R = 100\) mm; \(L = 120\) mm; \(C_{OL} = 10\) wt. %; \(\omega_L = 0.5(\omega_c); \xi_L = 0.13\)
- \(9 - R = 100\) mm; \(L = 120\) mm; \(C_{OL} = 20\) wt. %; \(\omega_L = 0.5(\omega_c); \xi_L = 0.13\)
- \(10 - R = 100\) mm; \(L = 120\) mm; \(C_{OL} = 20\) wt. %; \(\omega_L = 0.5(\omega_c); \xi_L = 0.13\)

The analysis of the obtained results showed that the deviations of the calculated productivity values from experimental values do not exceed 15 %. In our opinion, this is quite acceptable because finally a number of parameters, which ensure maximum performance and the required quality of the finished product, are determined during the commissioning tests of the industrial mill. These parameters include: \(C_D; \omega; \xi_L\). Based on these circumstances, we recommend, when designing rod mills, to provide the possibility of changing the angular velocity of rotation by about 20 – 30 % of the calculated values.

Dependence (3) became the basis for the development of a methodology for calculating rod mills for producing few-layer and multilayer graphene in liquids. As the initial data, the performance of the mill and the concentration of graphene structures in the finished product are specified. On the basis of the specified parameters using the data bank obtained experimentally, the geometric and operating parameters are calculated.

Using this technique, a parametric series of rod mills with graphene productivity was developed in suspension containing at least 6.4 wt. % graphene: 0.085; 0.269; 0.884 g/h. The modernization variants of serially produced laboratory mills MSF/2, MSF/4, MSF/8 and MSF/12 (Techno-Center LLC, Rybinsk, Yaroslavl Region) were developed. The numbers in the models indicate the volume of the porcelain drum in liters. A draft design of a modified mill with a unified bracket for fixing rods was prepared. If we consider the drums with dimensions which are actually used in industry, the performance of even a very small drum with a diameter of 1.4 m and a length of 1.5 m in terms of dry graphene structures is 370 g/h.
Conclusion

The literature data analysis showed that it is possible to organize the mode of periodic slips of the grinding bodies in the rotating drum relative to the inner surface of the rotating drum. It is during the sliding of the grinding bodies that the separation of graphite particles and the formation of graphene structures occur. A new design of a drum mill was developed, in which the grinding rods constantly slide along the surface of the drum. Studies have been carried out on the process of liquid-phase shear exfoliation of graphite in oil, and it has been established that the concentration of few-layer structures occurs. A new design of a drum mill was carried out on the process of liquid-phase shear exfoliation of graphite in oil, and it has been established that the concentration of few-layer graphene in the oil suspension increases in direct proportion to the increase in: the drum radius; the drum rotation speed; the initial concentration of graphite. A parametric row of rod drum mills was developed for the production of graphene oil-based suspensions with a dry graphene productivity from 0.096 to 0.884 g/h.

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