Structured Spectrum Allocation and User Association in Heterogeneous Cellular Networks

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Abstract—We study joint spectrum allocation and user association in heterogeneous cellular networks with multiple tiers of base stations. A stochastic geometric approach is applied as the basis to derive the average downlink user data rate in a closed-form expression. Then, the expression is employed as the objective function in jointly optimizing spectrum allocation and user association, which is of non-convex programming in nature. A computationally efficient Structured Spectrum Allocation and User Association (SSAUA) approach is proposed, solving the optimization problem optimally when the density of users is low, and near-optimally with a guaranteed performance bound when the density of users is high. A Surcharge Pricing Scheme (SPS) is also presented, such that the designed association bias values can be achieved in Nash equilibrium. Simulations and numerical studies are conducted to validate the accuracy and efficiency of the proposed SSAUA approach and SPS.

I. INTRODUCTION

Traditional single-tiered macro-cellular networks provide wide coverage for mobile user equipments (UEs), but they are insufficient to satisfy the exploding demand driven by modern mobile traffic, such as multimedia transmissions and cloud computing tasks. One efficient means to alleviate this problem is to install a diverse set of small-cells (e.g., picocells and femtocells), overlaying the macrocells, to form a multi-tiered heterogeneous cellular network [1]. Each small-cell is equipped with a shorter-range and lower-cost base station (BS), to provide nearby UEs with higher-quality communication links with lower power usage.

However, in the presence of multiple tiers of BSs in a cellular network, user association control becomes more challenging. A most direct approach is association by maximum received power, in which UEs are associated with the BS (in any tier) with the largest received power. However, in this case, because small-cell BSs are transmitting at lower power levels, only the UEs very close to them will connect with them, while most other UEs are still crowding in macrocells, leading to degraded performance. An example is shown in Fig. 1(a), in which many UEs are occupying the macrocells, while some small-cells are nearly empty.

In order to resolve this issue, a flexible user association approach may be employed [2], [3], in which each tier of BSs is assigned a user association bias value, and a UE is associated with a BS with the largest received power multiplied by the bias value. If small-cell BSs are associated with larger association bias values, the small-cells are “expanded” accordingly. This can result in a more balanced mobile traffic pattern and thus better network performance. Fig. 1(b) shows an example of flexible user association. However, if the association bias values for small-cell BSs are too large, it will cause improper expansions of small-cells such that UEs at their cell-edge may suffer from inadequate received power. As a consequence, the association bias values should be properly designed so that the overall network performance is optimized.

Further complicating the resource management problem in a multi-tier cellular network, the radio spectrum licensed by the network operator needs to be shared by BSs of widely different power and coverage areas. How to optimally allocate spectrum among different tiers is an important open problem. In order to avoid cross-tier interference, and the prohibitive complexity in tracking and provisioning for such interference especially with unplanned deployment of small cells, a disjoint spectrum mode is commonly advocated [4]–[6], where different tiers of BSs are allocated non-overlapping portions of the spectrum. Even so, it is still a challenging problem to properly divide the spectrum for optimal network performance.

In this work, our objective is to study jointly optimal spectrum allocation and user association in a heterogeneous cellular network with multiple tiers of BSs. First, we develop a stochastic geometric model to study the network performance analytically. A closed-form expression for the average downlink UE data rate is derived, which is then employed as the objective function for jointly optimizing the spectrum allocation among tiers and the user association bias values.

This resultant optimization problem is of non-convex programming in nature and cannot be solved with a standard method. Instead, we explore two important structures in solving the problem. Referred to as the density thresholding structure, we show that the problem can be studied separately over sparse UE and dense UE scenarios, divided by a parameter specific threshold. Referred to as the priority ordering structure, we show that a tier with higher BS density should have higher priority in spectrum allocation. Based on these ob-
ervations, we propose a computationally efficient Structured Spectrum Allocation and User Association (SSAUA) approach to solve the problem optimally in the sparse UE scenario, and near-optimally in the dense UE scenario with a quantified performance bound.

Finally, toward practical implementation of SSAUA, we propose a Surcharge Pricing Scheme (SPS), such that the designed association bias values can be achieved in Nash equilibrium. Hence, each UE is incentivized to adopt the proposed design with individual rationality.

The rest of the paper is organized as follows. In section [I] we discuss the relation between our work and prior works. In Section [III] we present the system model. In Sections [V] and [VI] we present our contributions in UE data rate derivation, SSAUA design, and SPS, respectively. In Section [VII] we present numerical results. Finally, conclusions are given in Section [VIII].

II. RELATED WORKS

A. Stochastic Geometry as Analytical Basis

Stochastic geometry [2]–[10] is a powerful mathematical modeling tool to analyze the performance (e.g., outage probability and data rate) of cellular networks with random spatial patterns of UEs and BSs. In this work, we focus on the downlink user data rate as performance measure. Pioneering works on downlink performance analysis using stochastic geometry include [11], [12], and [13], for either the single-tier or the multi-tier case. None of them considered spectrum allocation or user association.

B. Spectrum Allocation and User Association

Most prior studies considered either spectrum allocation or user association separately. For example, [6], [14] studied optimal spectrum allocation, in cellular networks limited to two tiers of BSs, without flexible user association.

Assuming a fixed number of UEs and BSs and without considering their random spatial patterns, [13]–[19] studied optimal user association with deterministic utility optimization. With a stochastic geometric approach, [2] proposed the flexible user association model with bias values, which is adopted in our work. It also derived the coverage probability and UE data rate, considering cross-tier interference, but in non-closed forms. [2] did not provide any design insights to optimize the derived performance metrics. It was later extended in [3] to study optimal user association in a network with two tiers of BSs, without considering spectrum allocation.

Joint spectrum allocation and user association was studied in [20]. It was limited to two tiers of BSs. [20] presented a qualitative study on the optimal network performance in terms of coverage probability and data rate, without further providing analytical details in solving the optimization problems. A similar problem was also studied in [21], with frequency reuse instead of tiered spectrum division as the approach for spectrum sharing. It could accommodate more than two tiers, but it provided only conditionally optimal user association given frequency reuse factors or conditionally optimal frequency reuse factors given user association bias values. Joint optimization remained an open problem.

Compared with the above studies, we consider multiple tiers of BSs with disjoint spectrum and provide optimal and analytically bounded near-optimal solutions for joint spectrum allocation and user association.

III. SYSTEM MODEL

A. Multi-tier Cellular Network

We consider a heterogeneous cellular network with randomly spatially distributed $K \geq 2$ tiers of BSs. As in conventional stochastic geometric modeling of multi-tier cellular networks [2], [3], [12], [20], [21], each tier of BSs independently forms a homogeneous Poisson point process (PPP) in two dimensional Euclidean space $\mathbb{R}^2$. Let $\Phi_k$ denote the PPP corresponding to tier-$k$ BSs, with intensity $\lambda_k$. Without loss of generality, we assume that $\lambda_1 < \lambda_2 < \ldots < \lambda_K$. (If $\lambda_i = \lambda_j$, $i \neq j$ in reality, we may approximate $\lambda_j = \lambda_i + \xi$, where $\xi$ is arbitrarily close to 0.) UEs are also modeled as a homogeneous PPP $\Psi$ with intensity $\mu$, independent of all BSs. We assume each BS is connected to the core network by separate high-capacity wired or wireless links that have no influence on our performance analysis. In addition, because we focus on downlink analysis, we assume that the downlink and uplink of the system are operated in different spectrum, so that the uplink interference and capacity have no influence on the downlink analysis.

B. Power and Pathloss Model

We define the tiers of BSs by their transmission power. Let $P_k$ be the transmission power of tier-$k$ BSs, which is a given parameter. If $P_k(x)$, $P_k(x) \in \{P_1, P_2, \ldots, P_K\}$, is the transmission power from a BS at $x$ and $P_r(y)$ is the received power at $y$, we have $P_r(y) = P_k(x) h_{x,y}$, where $\alpha |x-y|^\gamma$ is the propagation loss function with predetermined constants $\alpha$ and $\gamma$ (where the path loss exponent $\gamma > 2$ in practice), and $h_{x,y}$ is the fast fading term. Corresponding to common Rayleigh fading with power normalization, $h_{x,y}$ is independently exponentially distributed with unit mean. Let $H(\cdot)$ be the cumulative distribution function of $h_{x,y}$.

C. Spectrum Allocation

In order to avoid cross-tier interference, different tiers of BSs are allocated separated spectrum. Assume the total spectrum bandwidth is $W$. The network operator allocates $\eta_k W$ to each tier-$k$ BS, where $\eta_k$ is the spectrum allocation factor and $\sum_{k=1}^K \eta_k = 1$. Let $\eta = (\eta_1, \eta_2, \ldots, \eta_K)$. Note that BSs in the same tier are operated on the same spectrum.

We additionally consider the possible constraints $\eta_{\text{min},k} \leq \eta_k \leq \eta_{\text{max},k}$, for $k = 1, 2, \ldots, K$. Clearly, we have $\sum_{k=1}^K \eta_{\text{min},k} \leq 1 \leq \sum_{k=1}^K \eta_{\text{max},k}$. Furthermore, we assume that $0 < \eta_{\text{min},1} \leq \eta_{\text{min},2} \leq \cdots \leq \eta_{\text{min},K}$ and $0 < \eta_{\text{max},1} \leq \eta_{\text{max},2} \cdots \leq \eta_{\text{max},K}$, i.e., the network operator is likely (but not necessarily) to allocate more spectrum to a tier with higher
BS density. Note that this is a general condition that contains the special case where there is no constraint on $\eta$.

Given a specific tier-$k$ BS, it is common to assume that all its associated UEs are equally allocated spectrum [2]. [6]. [21]. Hence, the per-UE assigned spectrum bandwidth is $\beta_k = \eta_k W/N_k$, where $N_k$ is a random variable denoting the number of UEs associated with the BS.

D. Coverage Probability and UE Data Rate

Let $T$ denote the minimum required Signal-to-Interference Ratio (SIR) of UEs. The coverage probability of a UE is defined as the probability that its SIR is no less than $T$ [7]. As in conventional wireless modeling [2], [6], [21], if a UE experiences coverage probability $P^s$ and is allocated spectrum bandwidth $\beta'$, its data rate is $\beta' \log (1 + T)$ if the SIR is no less than $T$, and its data rate is 0 if the SIR is less than $T$ (i.e., outage occurs). Thus, the overall data rate of the UE is $\beta' \log (1 + T) P^s$. Note that, unless otherwise stated, log represents $\log_2$. Also, the thermal noise is assumed to be negligible compared with interference.

E. Flexible User Association

Given that a UE is located at $y$, it associates itself with the BS that provides the maximum biased received power [2], [3], [21] as follows:

$$BS(y) = \arg \max_{x \in \Phi_k} B_k P_k |x - y|^{-\gamma},$$

(1)

where $BS(y)$ denotes the location of the BS associated with the UE, and $P_k |x - y|^{-\gamma}$ is the received power from a tier-$k$ BS located at $x$, and $B_k$ is the association bias, indicating the connecting preference of a UE toward tier-$k$ BSs. In this case, the resultant cell splitting forms a generalized Dirichlet tessellation, or weighted Poisson Voronoi [22], shown in Fig. [1(b)]. Note that for $B_1, B_2, \ldots, B_K$, their effects remain the same if we multiply all of them by the same positive constant. Thus, without loss of generality, we normalize them such that $\sum_{k=1}^{K} B_k = 1$. Let $B = (B_1, B_2, \ldots, B_K)$.

Let $A_k$ denote the probability that a UE associates itself with a tier-$k$ BS, and $A = (A_1, A_2, \ldots, A_K)$. As derived in [2], we have

$$A_k = \frac{\lambda_k (P_k B_k)^{\frac{\gamma}{2}}}{\sum_{j=1}^{K} \lambda_j (P_j B_j)^{\frac{\gamma}{2}}},$$

(2)

and thus

$$B_k = \frac{P_k^{-1} (A_k/\lambda_k)^{\frac{\gamma}{2}}}{\sum_{j=1}^{K} P_j^{-1} (A_j/\lambda_j)^{\frac{\gamma}{2}}}. $$

(3)

Hence, there is a one-to-one mapping between $A$ and $B$, so we can view them interchangeably.

F. Problem Statement

We first aim to derive a closed-form expression for the average UE data rate. Then, our objective is to maximize the average UE data rate by jointly optimizing the spectrum allocation factors $\eta$ and the user association bias values $B$ (or equivalently $A$). Finally, we give a pricing scheme to incentivize each UE to adopt the designed $B$.

IV. Closed-form Average UE Data Rate

In this section, we derive the average UE data rate via stochastic geometric analysis. Consider a reference UE, termed as the typical UE, communicating with its BS, termed as the typical BS. We are interested in the typical UE since the average UE performance in the system is the same as the performance of the typical UE [7]. Furthermore, due to the stationarity of UEs and BSs, throughout this section we will re-define the coordinates so that the typical UE is located at 0.

First, we study the coverage probability given that the typical UE is associating with a tier-$k$ BS and their distance is $d$. In this case, the overall interference to the typical UE is the sum interference from all tier-$k$ BSs other than the typical BS. Let $I_k(d)$ denote such interference. Then

$$I_k(d) = \sum_{x \in \Phi_k^d} P_k h_{x,0} \frac{\alpha |x|^\gamma}{\alpha |x|^\gamma},$$

(4)

where $\Phi_k^d$ is the Palm point process corresponding to all tier-$k$ BSs other than the typical BS, given that the typical BS is located at a distance of $d$ from the typical UE. It can be shown that $\Phi_k^d$ is a PPP with intensity 0 in $B(0, d)$ and intensity $\lambda_k$ in $\mathbb{R}^2 \setminus B(0, d)$, where $B(0, d)$ denotes the disk region centered at 0 with radius $d$ [7].

The distribution of $I_k(d)$ is derived through its Laplace transform as follows:

$$L_{I_k}(d, s) = \mathbb{E} \left[ \exp \left( - \sum_{x \in \Phi_k^d} s P_k h_{x,0} \frac{\alpha |x|^\gamma}{\alpha |x|^\gamma} \right) \right] = \exp \left( - \lambda_k \int_{\mathbb{R}^2 \setminus B(0, d)} \int_{\mathbb{R}^+} e^{-s P_k h_{x,0} \frac{\alpha |x|^\gamma}{\alpha |x|^\gamma} H(h)} \text{d}x \right) \text{d}h,$$

(5)

$$= \exp \left( - \lambda_k \int_{\mathbb{R}^2 \setminus B(0, d)} \int_{\mathbb{R}^+} e^{-s P_k \frac{\alpha h}{\alpha |x|^\gamma} \frac{\alpha |x|^\gamma}{\alpha |x|^\gamma}} \text{d}x \right)$$

(6)

$$= \exp \left( - \frac{2 \pi \lambda_k}{d} \int_{d}^{\infty} \frac{\text{d}r}{\alpha + r^\gamma} \right),$$

(7)

where (5) is obtained from the Laplace functional of PPP $\Phi_k^d$. (6) is because $h$ is exponentially distributed with unit mean, and (7) is through a transformation to polar coordinates.

Let $P_{cover,k}(d)$ denote the conditional coverage probability of the typical UE (given $k$ and $d$). Then

$$P_{cover,k}(d) = P \left( \frac{P_k h_{x_B,0} \frac{\alpha |x|^\gamma}{\alpha |x|^\gamma}}{1 + T I_k(d)} \geq T I_k(d) \right)$$

(8)

where $x_B$ is the coordinate of the typical BS, and $|x_B| = d$. Substituting (7) into (8), we have

$$P_{cover,k}(d) = \exp \left( - \frac{2 \pi \lambda_k}{d} \int_{d}^{\infty} \frac{T d \gamma r \frac{\alpha}{\alpha + r^\gamma}}{\text{d}r} \right)$$

(9)

$$= \frac{1}{\pi \sqrt{2 \pi d^\gamma}} \exp \left( - \frac{\pi \lambda_k T^2}{2} \int_{d}^{\infty} \frac{1}{\text{d}t} \right).$$

(9)
Furthermore, the probability density function of the distance between the typical UE and its associated tier-$k$ BS is

$$f_k(d) = \frac{2\pi \lambda_k}{A_k} d \exp \left( -\pi d^2 \sum_{i=1}^{K} \lambda_j \frac{P_j B_j}{P_k B_k} \right)^2$$

(10)

$$= \frac{2\pi \lambda_k}{A_k} d \exp \left( -\pi d^2 \frac{\lambda_k}{A_k} \right),$$

(11)

where (10) is derived in [2], and (11) is by substituting (2) into (10).

Hence, the coverage probability $P_{\text{cover}, k}$ of the typical UE associated with a tier-$k$ BS can be computed as

$$P_{\text{cover}, k} = \int_{0}^{\infty} f_k(d) P_{\text{cover}, k}(d) dd$$

$$= \int_{0}^{\infty} \frac{2\pi \lambda_k}{A_k} d \exp \left( -\pi d^2 \frac{\lambda_k}{A_k} \right) \exp \left( -\pi \lambda_k (T)^2 d^2 \int_{0}^{\infty} \frac{1}{(\pi d)^2} 1 + e^{-\pi d^2} \right) dd$$

$$= \frac{1}{A_k} \frac{1}{\lambda_k} + C,$$

(12)

where $C = (T)^2 \int_{0}^{\infty} \frac{1}{(\pi d)^2} 1 + e^{-\pi d^2} dt$ is a system-level constant only related to $\gamma$ and $T$.

Let $E_0(\beta_k)$ denote the expected spectrum bandwidth allocated to the typical UE (connecting to a tier-$k$ BS). Following the model in Section III-C, $E_0(\beta_k)$ equals the spectrum bandwidth allocated to the typical tier-$k$ BS divided by the average number of UEs associated with it conditioned on the typical UE, which is $A_k \mu / \lambda_k + 1$. Hence,

$$E_0(\beta_k) = \frac{\eta_k W}{A_k \mu / \lambda_k + 1}.$$

(13)

Then, by Section III-D, the conditional expected data rate of the typical UE, given it is associated with a tier-$k$ BS, can be computed as

$$\bar{R}_k = E_0(\beta_k) \log(1 + T) P_{\text{cover}, k}.$$

(14)

Finally, the average data rate of the typical UE, and hence the average data rate per UE in the system, is

$$\mathbf{F} = \sum_{k=1}^{K} A_k \bar{R}_k = \sum_{k=1}^{K} A_k E_0(\beta_k) \log(1 + T) P_{\text{cover}, k}$$

$$= \sum_{k=1}^{K} \eta_k W \log(1 + T) \left( \frac{A_k \mu / \lambda_k + 1}{A_k} + C \right).$$

(15)

Note that stochastic geometric analysis often leads to non-closed forms requiring numerical integrations (e.g., [2], [3], [11], [12]), due to the integral form of the Laplace functional or generating functional of PPPs applied in analysis [7], [10]. Fortunately, our derived closed-form expression for the average UE data rate facilitates the tractability of the resultant optimization problem.

V. JOINT OPTIMIZATION PROBLEM AND SSAUA

We aim to maximize the average UE data rate $\mathbf{F}$ with respect to $\eta$ and $\mathbf{A}$. As there is a one-to-one mapping between $\mathbf{A}$ and $\mathbf{B}$, we study the optimization problem over $\{\eta, \mathbf{A}\}$ instead for analytical convenience. This is formally stated as optimization problem $\mathbf{P}$ as follows:

$$\text{maximize}_{\eta, \mathbf{A}} \quad \mathbf{F}(\eta, \mathbf{A}) = \sum_{k=1}^{K} \eta_k M_k(A_k)$$

subject to

$$\sum_{k=1}^{K} \eta_k = 1, \quad \eta_{\min,k} \leq \eta_k \leq \eta_{\max,k}, \forall k,$$

$$\sum_{k=1}^{K} A_k = 1, \quad A_k > 0, \forall k,$$

where $M_k(A_k)$ is defined as

$$M_k(A_k) = \frac{1}{(A_k \mu / \lambda_k + 1) \left( \frac{A_k}{\lambda_k} + C \right)}.$$

(17)

Problem $\mathbf{P}$ is non-convex and cannot be solved through a standard method. Instead, we investigate into two important structures of the optimal solution, termed density thresholding and priority ordering, based on which we propose a computationally efficient Structured Spectrum Allocation and User Association (SSAUA) approach to solve the problem.

A. Density Thresholding Structure

First, we define an important parameter

$$a_k \triangleq \sqrt{\frac{\mu}{\lambda_k}}.$$

(18)

Note that $M_k(A_k)$ is increasing on $[0, a_k]$ and decreasing on $[a_k, \infty)$. We further observe several useful properties of $M_k(A_k)$, which are presented in Appendix A. Based on these properties, we obtain the following lemma, whose proof is given in Appendix B.

**Lemma 1:** Consider a potential solution $(\eta^{**}, \mathbf{A}^{**})$ to Problem $\mathbf{P}$. If $\exists i \neq j$, such that $A^{**}_i < a_i$ and $A^{**}_j > a_j$, then $(\eta^{**}, \mathbf{A}^{**})$ is not an optimal solution.

**Lemma 1** suggests that, in an optimal solution, every $A_k$ must be on the same side of $a_k$. This directly leads to the following theorem, which is fundamental to our optimization solution.

**Theorem 1:** (Density Thresholding) Let $(\eta^*, \mathbf{A}^*)$ be an optimal solution to Problem $\mathbf{P}$. If $\sum_{k=1}^{K} a_k > 1$, then $\forall k, A^*_k \leq a_k$; if $\sum_{k=1}^{K} a_k < 1$, then $\forall k, A^*_k \geq a_k$; if $\sum_{k=1}^{K} a_k = 1$, then $\forall k, A^*_k = a_k$.

**Proof:** If $\sum_{k=1}^{K} a_k > 1$, because $\sum_{k=1}^{K} A^*_k = 1$, $\exists l$ such that $A^*_l < a_l$. This leads to $A^*_k \leq a_k$, $\forall k$, according to Lemma 1. The cases where $\sum_{k=1}^{K} a_k < 1$ and $\sum_{k=1}^{K} a_k = 1$ are similar.

Note that, the condition $\sum_{i=1}^{K} a_i > 1$ is equivalent to

$$\sqrt{\eta^*} \left( \sum_{i=1}^{K} \sqrt{\eta_i} \right) > \sqrt{\pi},$$

implying the density of UEs is sparse (compared with that of BSs). Thus, we refer to the case $\sum_{i=1}^{K} a_i > 1$ as the sparse UE scenario. On the other hand, we refer to the case $\sum_{i=1}^{K} a_i < 1$, which is equivalent...
as follows: \( \sum_{i=1}^{n} \sqrt{a_i} < \sqrt{n} \), as the dense UE scenario. If \( \sum_{i=1}^{n} a_i = 1 \), Problem P can be trivially solved and is ignored in the rest of our discussion. Note that because \( a_k \) can be computed directly from the given parameters, one can judge which scenario Problem P falls within before solving the problem. Next, the solution to P will be investigated separately in the sparse UE and dense UE scenarios.

B. SSAUA in the Sparse UE Scenario
In this case, the original Problem P becomes Problem P1 as follows:

\[
\begin{aligned}
\text{maximize} & \quad F(\eta, A) = \sum_{k=1}^{K} \eta_k M_k(A_k) \\
\text{subject to} & \quad \sum_{k=1}^{K} \eta_k = 1, \quad \eta_{\min,k} \leq \eta_k \leq \eta_{\max,k}, \forall k, \\
& \quad \sum_{k=1}^{K} A_k = 1, \quad 0 \leq A_k \leq a_k, \forall k.
\end{aligned}
\]

We first observe an important ordering property of the optimal solution to P1, as shown in the following lemma, whose proof is given in Appendix C.

**Lemma 2:** (Ordering Property) Let \( A^* \) be optimal for P1, then \( M_1(A_1^*) \leq M_2(A_2^*) \leq \ldots \leq M_K(A_K^*) \).

Next, by sequentially computing \( \eta^* \) as follows:

\[
\begin{aligned}
\eta^*_K &= \min(1 - \sum_{k=1}^{K-1} \eta_{\min,k}, \eta_{\max,K,k}), \\
\eta^*_{K-1} &= \min(1 - \eta^*_K - \sum_{k=1}^{K-2} \eta_{\min,k} - \eta_{\max,K-1}), \\
& \ldots, \\
\eta^*_i &= \min(1 - \sum_{k=i+1}^{K} \eta^*_k - \sum_{k=1}^{i-1} \eta_{\min,k} - \eta_{\max,i}), \\
& \ldots, \\
\eta^*_1 &= \min(1 - \sum_{k=2}^{K} \eta^*_k - \eta_{\max,1}).
\end{aligned}
\]

we have the following theorem:

**Theorem 2:** (Priority Ordering) Let \( A^* \) be optimal for Problem P1, then \( (\eta^*, A^*) \), where \( \eta^* \) is computed in (20), is an optimal solution to P1.

**Proof:** Consider Problem P1A as follows:

\[
\begin{aligned}
\text{maximize} & \quad \eta \sum_{k=1}^{K} \eta_k M_k(A_k^*) \\
\text{subject to} & \quad \sum_{k=1}^{K} \eta_k = 1, \quad \eta_{\min,k} \leq \eta_k \leq \eta_{\max,k}, \forall k.
\end{aligned}
\]

Then P1A is a simple linear programming problem with ordered linear coefficients in the objective, since \( M_1(A_1^*) \leq M_2(A_2^*) \leq \ldots \leq M_K(A_K^*) \) due to Lemma 2. Note that \( \eta^* \) does not depend on the exact values of \( A^* \); it only requires the ordering property as shown in Lemma 2. Also, \( \eta^* \) is in the feasible region due to \( \sum_{k=1}^{K} \eta_{\min,k} \leq 1 \leq \sum_{k=1}^{K} \eta_{\max,k} \). It is easy to verify that, \( (\eta^*, A^*) \) is an optimal solution to P1.

Equation (20) indicates the priority ordering structure in spectrum allocation. We see that tier-K has the highest priority in spectrum allocation, followed by tier-(K - 1), and so forth. Theorem 2 provides a means to derive an optimal \( \eta^* \) regardless of the \( A^* \) values. We need one further step to derive the corresponding optimal \( A^* \) by solving the following Problem P1B:

\[
\begin{aligned}
\text{maximize} & \quad \sum_{k=1}^{K} \eta_k M_k(A_k) \\
\text{subject to} & \quad \sum_{k=1}^{K} A_k = 1, \quad 0 \leq A_k \leq a_k, \forall k.
\end{aligned}
\]

Note that P1B is a convex programming problem, since \( M_k(A_k) \) is concave on \( [0, a_k] \). Thus, \( A^* \) can be computed by a computationally efficient algorithm, such as the interior point method. Hence the both steps to compute the jointly optimal solution \( (\eta^*, A^*) \) have low computational complexity.

C. SSAUA in the Dense UE Scenario with Performance Bound
In this case, the original Problem P becomes Problem P2 as follows:

\[
\begin{aligned}
\text{maximize} & \quad F(\eta, A) = \sum_{k=1}^{K} \eta_k M_k(A_k) \\
\text{subject to} & \quad \sum_{k=1}^{K} \eta_k = 1, \quad \eta_{\min} \leq \eta_k \leq \eta_{\max}, \forall k, \\
& \quad \sum_{k=1}^{K} A_k = 1, \quad A_k \geq a_k, \forall k.
\end{aligned}
\]

Problem P2 is more complicated compared with Problem P1, as \( M_k(A_k) \) is not concave, but an S-shaped function, in the feasible region. Hence, P2 generally incurs high computational complexity even if an optimal \( \eta^* \) is given [24], [25].

Therefore, instead of directly solving P2, we first approximate \( M_k(A_k) \) by \( \bar{M}_k(A_k) \) defined as follows:

\[
\bar{M}_k(A_k) = \frac{1}{(A_k \mu/\lambda_k) \left( \frac{1}{\mu} + C \right)}.
\]

Note that this approximation is reasonable because \( A_k \mu/\lambda_k \) is much larger than 1 when \( \mu \) is large (i.e., the dense UE scenario). This observation is also supported by the small performance gap as derived in Section V.C2. Some useful properties of \( M_k(A_k) \) are shown in Appendix D.

The approximated problem is referred to as Problem P2A, where we simply replace the objective function of P2 by the following:

\[
F'(\eta, A) = \sum_{k=1}^{K} \eta_k \bar{M}_k(A_k).
\]

1) Solution to P2A: The important ordering property still holds for Problem P2A, as formalized in the following lemma, whose proof is given in Appendix E.

**Lemma 3:** (Ordering Property) Let \( (\bar{\eta}^*, \bar{A}^*) \) be an optimal solution to P2A, then \( \bar{M}_1(\bar{A}_1^*) \leq \bar{M}_2(\bar{A}_2^*) \leq \ldots \leq \bar{M}_K(\bar{A}_K^*) \).

We observe that with the same ordering property, (20) can again be adopted as an optimal solution to P2A in the dense UE scenario, leading to the following theorem:
Theorem 3: (Priority Ordering) Let $\tilde{A}^*$ be optimal for Problem P2A, then $(\tilde{\eta}^*, \tilde{A}^*)$, where $\tilde{\eta}^*$ is computed the same way as $\eta^*$ in (20), is an optimal solution to P2A.

Proof: The proof is similar to that of Theorem 2.

Given an optimal $\tilde{\eta}^*$ for P2A, we find the corresponding optimal $\tilde{A}^*$ for P2A by solving the following Problem P2B:

$$\begin{align*}
\text{maximize} & \quad \sum_{k=1}^{K} \tilde{\eta}_k^* \tilde{A}_k(A_k) \\
\text{subject to} & \quad \sum_{k=1}^{K} A_k = 1, \quad A_k \geq a_k, \forall k.
\end{align*}$$

Unlike in the sparse UE scenario, here we have an explicit solution, as stated in the following theorem:

Theorem 4: Given an optimal $\tilde{\eta}^*$ for P2A (computed in the same way as $\eta^*$ in (20)), the corresponding optimal $\tilde{A}^*$ can be expressed as follows:

$$\begin{align*}
\tilde{A}_k^* &= a_k, \\
\tilde{A}_1^* &= 1 - \sum_{i=2}^{K} \tilde{A}_i^*.
\end{align*}$$

Proof: See Appendix E.

Note that both (20) and (27) can be computed with low computational complexity.

2) Bounding the Performance Gap: Since $(\tilde{\eta}^*, \tilde{A}^*)$ is optimal for P2A rather than P2, we next quantify the performance gap between $(\tilde{\eta}^*, \tilde{A}^*)$ and an optimal solution $(\eta^*, A^*)$ to P2.

The performance gap is defined as

$$E = F(\eta^*, A^*) - F(\tilde{\eta}^*, \tilde{A}^*).$$

Because $F(\tilde{\eta}^*, \tilde{A}^*) \leq F(\eta^*, A^*) \leq F'(\eta^*, A^*) \leq F'(\tilde{\eta}^*, \tilde{A}^*)$, we have

$$E \leq F'(\eta^*, A^*) - F(\tilde{\eta}^*, \tilde{A}^*) \leq E'.$$

Substituting $\tilde{\eta}^*$ and $\tilde{A}^*$ into $E'$, we have

$$E' = \sum_{k=1}^{K} \frac{A_k \mu}{\lambda_k} (\tilde{\eta}_k^* + 1) \left( \frac{1}{A_k^*} + C \right).$$

Therefore, the relative performance gap is bounded by

$$\epsilon \leq \frac{E}{F(\eta^*, A^*)} \leq \frac{E'}{F'(\eta^*, A^*)} = \sum_{k=1}^{K} \frac{A_k \mu}{\lambda_k} \left( \tilde{\eta}_k^* + 1 \right) \left( \frac{1}{A_k^*} + C \right)$$

where inequality (a) is obtained by observing the common factor in the summations in the numerator and denominator of (32). This implies that $\epsilon$ scales as $O \left( \sqrt{\lambda K / \mu} \right)$. Note that because we are considering the dense UE scenario (i.e., $\sqrt{\sum_{i=1}^{K} \sqrt{A_i}} < \sqrt{D}$), $O \left( \sqrt{\lambda K / \mu} \right)$ is small by definition.

D. Estimation for Complexity of Exhaustive Search

In this subsection, we briefly discuss the complexity of the exhaustive search approach to solve Problem P. First, as explained in details in our technical report [26], we observe that at least one of the optimal solutions to $P$, $(\eta^*, A^*)$, has the following property: there is at most one $k \in \{1, \ldots, K\}$ such that $\eta_{\min,k} < \eta_k^* < \eta_{\max,k}, \forall j \neq k$, either $\eta_j^* = \eta_{\min,j}$ or $\eta_j^* = \eta_{\max,j}$ (i.e., at the boundary). Thus, the search for $\eta^*$ needs to be performed only at these boundary cases, leading to a complexity of $\Omega(2^K)$. Furthermore, in the dense UE scenario, a numerical search over all locally optimal A (at least $2^K$ of them) is required, leading to another fold of $\Omega(2^K)$, i.e., $\Omega(4^K)$ overall, in complexity. Numerical studies on the computational complexity will be presented in Section VII.

VI. NASH EQUILIBRIUM FOR SSAUA

Individual UEs may behave selfishly to derive unfair advantage despite our design of $B^*$ (or equivalently $A^*$). Thus, in this section, we propose a Surcharge Pricing Scheme (SPS), such that the designed $B^*$ is the natural outcome of a Nash equilibrium. Note that the designed spectrum allocation factors $\eta^*$ can be maintained by the network operator and is beyond our concern.

We consider a reference individual UE, whose association bias values are $B^* = (B_1', B_2', \ldots, B_K')$. Let $A' = (A_1', A_2', \ldots, A_K')$ be its corresponding association probabilities. For the other UEs, suppose they all obey the association bias values $B^*$ assigned by the network operator. Similar to the discussions in Section III and V the average data rate of the reference UE is

$$E = \sum_{k=1}^{K} \frac{\eta_k^* W \log(1 + T)}{(A_k^* \mu / \lambda_k + 1) \left( \frac{1}{A_k^*} + C \right)}. $$

If the reference UE performs an optimization on $F$ with respect to $A'$, the resultant optimal $A'^* = (A_1'^*, A_2'^*, \ldots, A_K'^*)$ is unlikely to be the same as $A^*$. Therefore, we add the following Surcharge Pricing Scheme: the network operator applies a surcharge $c_k$ to each UE associated with a tier-$k$ BS. Let $c = (c_1, c_2, \ldots, c_K)$. In this case, the average surcharge for the reference UE is $\sum_{k=1}^{K} c_k A_k$. Accordingly, the reference UE will perform the following optimization Problem P3:

$$\begin{align*}
\text{maximize} & \quad F' = \sum_{k=1}^{K} \left( \frac{\eta_k^* W \log(1 + T)}{(A_k^* \mu / \lambda_k + 1) \left( \frac{1}{A_k^*} + C \right)} - c_k A_k \right) \\
\text{subject to} & \quad \sum_{k=1}^{K} A_k = 1, \quad A_k \geq 0.
\end{align*}$$

Different from P, it can be shown that P3 is a standard convex optimization problem. By the KKT conditions, its optimal solution $A'^*$ satisfies

$$\begin{align*}
\frac{H_k}{(1 + CA_k'^*)^2} - c_k - \nu + \theta_k = 0, \\
\theta_k A_k'^* = 0, \quad \theta_k \geq 0,
\end{align*}$$
We also compare (\(\eta^*,B^*\)) and (\(\hat{\eta},\hat{B}\)) in the sparse and dense UE scenarios, respectively. Note that (\(\hat{\eta},\hat{B}\)) is optimal in the sparse UE scenario. We also compare (\(\eta^*,B^*\)) with an optimal solution (\(\eta^*,\hat{B}\)) obtained from exhaustive search in the dense UE scenario.

First, we study the network performance under different UE density \(\mu\). The network parameters are as follows: \(K = 3\), \(\lambda_1 = 1\) units/km\(^2\), \(\lambda_2 = 5\) units/km\(^2\), \(\lambda_3 = 10\) units/km\(^2\), \(P_1 = 56\) dBm, \(P_2 = 46\) dBm, \(P_3 = 36\) dBm, \(\eta_{\text{min},1} = 0.2\), \(\eta_{\text{min},2} = 0.25\), \(\eta_{\text{min},3} = 0.3\), \(\eta_{\text{max},1} = 0.35\), \(\eta_{\text{max},2} = 0.4\), \(\eta_{\text{max},3} = 0.45\), \(\gamma = 4\), \(W = 200\) MHz, and \(T = 0.2\). In each round of simulation, UEs and BSs are generated on a 10 km \(\times\) 10 km square, and the UEs in the central 5 km \(\times\) 5 km square are sampled for performance evaluation (in order to remove the edge effect). Each simulation data point is averaged over all sampled UEs during 100 rounds of simulations.

The results are shown in Fig. 2. A vertical line indicates the threshold value of \(\mu\), as given in Theorem 1 separating the sparse and dense UE scenarios. For both scenarios, we show results of the analytical and simulated performance of SSAUA, and analytical and simulated performance of a “max power” approach, which employs equal spectrum allocation and user association based on the maximum received power. Since SSAUA is not optimal in the dense UE scenario, we also add two sets of results accordingly: the analytical optimal performance \(F(\eta^*,B^*)\) through exhaustive search and its analytical upper bound \(F(\hat{\eta},\hat{B})\).

Fig. 3 illustrates that the SSAUA achieves near-optimal solution in the dense UE scenario. Furthermore, SSAUA substantially outperforms the max power solution. Finally, the analytical performance is only slightly smaller than the simulated performance, matching our discussions in Section IV.

Fig. 3 shows the optimal network performance under different path loss exponent \(\gamma\). The network parameters are the same as those used in Fig. 2 except \(\mu\) is fixed at 100 (i.e., sparse UE) and 500 (i.e., dense UE) units/km\(^2\) in Fig. 3(a) and (b) respectively. This figure further confirms the observations from Fig. 2. Furthermore, it shows that SSAUA is effective for a wide range of path loss conditions.

Fig. 4 shows \(B^*, B^*,\) and \(B^*;\) and Fig. 5 shows their corresponding prices \(c^*, \tilde{c}^*,\) and \(c^*\), under different \(\mu\). We observe that \(B^*\) and \(\tilde{c}^*\) computed based on SSAUA approach are close to their counterparts \(B^*\) and \(c^*\).

Finally, a run time experiment is conducted to compare the computational complexity of SSAUA with that of exhaustive search. The experiment is executed by Matlab R2011a on an ASUS PC with Intel i7-3610QM 2.3GHz processor and 4GB RAM. The results are averaged over 1000 runs for SSAUA and
10 runs for exhaustive search (both with randomly generated parameters). Fig. 6 shows that the run time of SSAUA is almost negligible compared with exhaustive search. Note that the y-axis is in log scale. When \( K \) increases, the run time of exhaustive search exhibits an exponential growth tendency, while SSAUA remains computationally efficient.

VIII. CONCLUSIONS

In this work, we provide a theoretical framework to study the joint optimization of spectrum allocation and user association in heterogeneous cellular networks. We establish a stochastic geometric model that captures the random spatial patterns of BSs and UEs, and a closed-form expression of the analytical average UE data rate is derived. We then consider the problem of maximizing the average UE data rate by jointly optimizing the spectrum allocation factors \( \eta \) and user association bias values \( B \), which is non-convex programming in nature. We propose the SSAUA approach to solve this problem with low computational complexity. We show that the SSAUA approach is optimal in the sparse UE scenario and near-optimal in the dense UE scenario, with a quantified tight bound scaling as \( O(\sqrt{\log K / m}) \). We also propose the SPS such that the designed association bias values can be achieved in Nash equilibrium.

APPENDIX

A. Useful Properties of \( M_k(A_k) \)

(M-1) \( M_k(A_k) \) is increasing on \([0, a_k]\) and decreasing on \([a_k, \infty)\).

(M-2) \( M_k(A_k) \) is concave on \([0, a_k']\) and convex on \([a_k', \infty)\), where \( a_k' \) is some threshold value \( a_k' > a_k \).

(M-3) If \( \lambda_i < \lambda_j \), then \( M_i(A) < M_j(A) \), \( \forall A > 0 \).

(M-4) If \( \lambda_i < \lambda_j \), then \( M_j(A) - M_i(A) \) is strictly increasing on \([0, a_j]\).

B. Proof of Lemma 7

Proof: Suppose \( A^{**} \) is optimal, \( A^{*} < a_i \), and \( A^{**} > a_j \). Consider that we increase \( A^{**} \) by a small value \( \Delta > 0 \) and decrease \( A^{*} \) by \( \Delta \). According to property (M-1), \( \eta_i^{**} M_i(A^{*}) + \eta_j^{**} M_j(A^{**}) < \eta_i^{**} M_i(A^{*} + \Delta) + \eta_j^{**} M_j(A^{**} - \Delta) \). Thus, through replacing \( A^{**} \) and \( A^{*} \) by \( A^{**} + \Delta \) and \( A^{*} - \Delta \) respectively, we find a better solution to \( P \), leading to a contradiction.

C. Proof of Lemma 2

Proof: Suppose \( \exists i < j \) such that \( M_i(A_i^*) > M_j(A_j^*) \). This implies that \( A_i^* > A_j^* \). (Otherwise, suppose \( A_i^* \leq A_j^* \), then we have \( M_i(A_i^*) \leq M_j(A_j^*) < M_j(A_i^*) \), leading to a contradiction.) A corresponding diagram is shown in Fig. 7.

Case 1: \( \eta_i^* \leq \eta_j^* \).

Let \( \hat{A}_j^* = A_i^* \) and \( \hat{A}_i^* = A_j^* \), then we have

\[
\begin{align*}
[\eta_i^* M_i(\hat{A}_i^*) + \eta_j^* M_j(\hat{A}_j^*)] - [\eta_i^* M_i(A_i^*) + \eta_j^* M_j(A_j^*)] \\
= [\eta_i^* M_i(A_i^*) + \eta_j^* M_j(A_j^*)] - [\eta_i^* M_i(A_i^*) + \eta_j^* M_j(A_j^*)] \\
= [\eta_i^* M_i(A_i^*) - M_i(A_j^*)] + [\eta_i^* M_i(A_i^*) - M_i(A_j^*)] \\
\geq [\eta_i^* M_j(A_j^*) - M_j(A_i^*)] + M_i(A_i^*) - M_i(A_j^*) > 0 \quad \text{(40)}
\end{align*}
\]

where \( \text{(40)} \) is due to property (M-4).

As a consequence, if \( A_i^* \) and \( A_j^* \) are replaced by \( \hat{A}_i^* \) and \( \hat{A}_j^* \) respectively, we obtain a larger \( F \), leading to a contradiction.

Case 2: \( \eta_i^* > \eta_j^* \).

Let \( \tilde{A}_i^* = A_i^* \), \( \tilde{A}_j^* = A_j^* \), \( \tilde{\eta}_i^* = \eta_i^* \), and \( \tilde{\eta}_j^* = \eta_j^* \). (Note that because \( \eta_{\text{min}, i} \leq \eta_{\text{min}, j} \) and \( \eta_{\text{max}, i} \leq \eta_{\text{max}, j} \), \( \tilde{\eta}_i^* \) and \( \tilde{\eta}_j^* \) are guaranteed to be in the feasible region.)

\[
\begin{align*}
[\tilde{\eta}_i^* M_i(\tilde{A}_i^*) + \tilde{\eta}_j^* M_j(\tilde{A}_j^*)] - [\eta_i^* M_i(A_i^*) + \eta_j^* M_j(A_j^*)] \\
= [\eta_i^* M_i(A_i^*) + \eta_j^* M_j(A_j^*)] - [\eta_i^* M_i(A_i^*) + \eta_j^* M_j(A_j^*)] \\
= [\eta_i^* M_j(A_j^*) - M_j(A_i^*)] + [\eta_i^* M_j(A_j^*) - M_j(A_i^*)] \\
> [\eta_i^* M_j(A_j^*) - M_j(A_i^*)] + M_i(A_i^*) - M_i(A_j^*) > 0 \quad \text{(41)}
\end{align*}
\]

Thus, if \( A_i^* \), \( A_j^* \), \( \eta_i^* \), and \( \eta_j^* \) are replaced by \( \tilde{A}_i^* \), \( \tilde{A}_j^* \), \( \tilde{\eta}_i^* \), and \( \tilde{\eta}_j^* \) respectively, we can find a larger \( F \), leading to a contradiction.

D. Useful Properties of \( \tilde{M}_k(A_k) \)

(M-1) \( \tilde{M}_k(A_k) \) is a decreasing convex function.

(M-2) If \( \lambda_i < \lambda_j \), then \( \tilde{M}_i(A_i) < \tilde{M}_j(A_j) \).

(M-3) If \( \lambda_i < \lambda_j \), then \( \tilde{M}_i(A_i) - \tilde{M}_j(A_j) \) is a strictly decreasing function.

(M-4) \( \tilde{M}_k(A) - \tilde{M}_k(A + D) < \tilde{M}_k(A') - \tilde{M}_k(A' + D) \), for any \( A' > A \geq a_k \) and \( D > 0 \).

(M-5) If \( \lambda_i < \lambda_j \), then \( \tilde{M}_i(a_i) - \tilde{M}_j(a_j + D) > \tilde{M}_i(a_i) - \tilde{M}_j(a_j + D) \), for any \( D > 0 \).

(E-6) If \( \lambda_i < \lambda_j \), then \( \tilde{M}_i(a_i) - \tilde{M}_j(a_j + D) > \tilde{M}_i(a_i) - \tilde{M}_j(a_j + D) \), for any \( D > 0 \) and \( A' > a_i \) (combining (M-4) and (M-5)).

E. Proof of Lemma 3

Proof: Suppose that \( \exists i < j \) (i.e., \( i < j \)) such that \( \tilde{M}_i(A_i) > \tilde{M}_j(A_j) \), which also implies that \( a_i < A_i < A_j \).

The corresponding diagrams are shown in Fig. 8.
where \( \text{Case 1} \) is due to property (M-3').

Thus, if \( \tilde{A}_i^* \) and \( \tilde{A}_j^* \) are replaced by \( \tilde{A}_i^* \) and \( \tilde{A}_j^* \) respectively, we obtain a larger \( \tilde{P} \), leading to a contradiction.

**Case 1.2:** \( \tilde{A}_i^* < a_j \).

Let \( \tilde{A}_j^* = a_j \), \( D = \tilde{A}_j^* - a_j \) and \( \tilde{A}_i^* = \tilde{A}_i^* + D \), then we have

\[
\tilde{n}_i^* \tilde{M}_i(\tilde{A}_i^*) + \tilde{n}_j^* \tilde{M}_j(\tilde{A}_j^*) = \tilde{n}_i^* \tilde{M}_i(\tilde{A}^*_i) + \tilde{n}_j^* \tilde{M}_j(\tilde{A}^*_j) \\
\tilde{n}_i^* [\tilde{M}_i(\tilde{A}^*_i) - \tilde{M}_j(\tilde{A}^*_j)] + \tilde{n}_j^* [\tilde{M}_j(\tilde{A}^*_j) - \tilde{M}_i(\tilde{A}^*_i)] \\
\geq \tilde{n}_i^* [\tilde{M}_i(\tilde{A}^*_i) - \tilde{M}_j(\tilde{A}^*_j)] + \tilde{M}_i(\tilde{A}^*_i) - \tilde{M}_i(\tilde{A}^*_i) > 0,
\]

(43)

where \( \text{Case 2} \) is due to property (M-6').

Thus, if \( \tilde{A}_i^* \) and \( \tilde{A}_j^* \) are replaced by \( \tilde{A}_i^* \) and \( \tilde{A}_j^* \) respectively, we obtain a larger \( \tilde{P} \), leading to a contradiction.

**Case 2:** \( \tilde{n}_i^* > \tilde{n}_j^* \).

**Case 2.1:** \( \tilde{A}_i^* \geq a_j \).

**Case 2.2:** \( \tilde{A}_i^* < a_j \).

The proof for these cases can be found in our technical report [26].

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