Dendritic spines are the postsynaptic sites that receive most of the excitatory synaptic inputs, and thus provide the structural basis for synaptic function. Here, we describe an accurate method for measurement and analysis of spine morphology based on structured illumination microscopy (SIM) and computational geometry in cultured neurons. Surface mesh data converted from SIM images were comparable to data reconstructed from electron microscopic images. Dimensional reduction and machine learning applied to large data sets enabled identification of spine phenotypes caused by genetic mutations in key signal transduction molecules. This method, combined with time-lapse live imaging and glutamate uncaging, could detect plasticity-related changes in spine head curvature. The results suggested that the concave surfaces of spines are important for the long-term structural stabilization of spines by synaptic adhesion molecules.
Endocytic spines are submicron-scale structures protruding from neuronal dendrites that receive excitatory synaptic inputs from afferent axons. Precise measurement of spine morphology and objective analysis of large numbers of spines are required to understand both the physiological regulation of synaptic transmission and pathological changes in this process. Dendritic spines exhibit a high degree of structural variability: their sizes vary over more than one order of magnitude, and their shapes range from thin elongated filopodia-like protrusions to round mushroom-like structures. Recent analyses of spine images obtained by quantitative and super-resolution optical imaging argued against the conventional categories of thin, mushroom, or stubby spines, and suggested that continuous morphological variables should be used instead. Structural studies of spines by electron microscopic (EM) reconstruction also opposed the idea of well-defined categories of dendritic spines. In light of these developments, it is necessary to develop new strategies that allow comprehensive analysis of highly variable spine structures.

Traditionally, structural analysis of dendritic spines has relied on reconstruction of EM images. Although new technologies for automated acquisition of serial EM images greatly accelerated quantitative analysis of spine morphological features, the lack of information about the dynamic properties of spines limits the application of these methods to functional studies. Recent progress in multiple technologies related to super-resolution imaging has raised the possibility of accurate and high-throughput imaging of submicron spine structures. Several recent studies proposed computational methods for objective shape classification and modeling of dynamic spine behavior. First, spine shape analysis based on a commercially available software package, such as Imaris software, was proposed. This study utilized three structural parameters and simple formulas for spine classification. Second, Rodrigue et al. proposed a spine analysis algorithm in the platform of a freely distributed software NeuronStudio. With this tool, spine classification is performed by a decision tree with three key parameters, aspect ratio (the extent of shape elongation), head-to-neck ratio (ratio of their diameters), and spine head diameter. Small numbers of parameters for spine shape in these studies may not be adequate for complex three-dimensional (3D) spine images obtained by super-resolution microscopy. Third, spine classification by semi-supervised learning in combination with multiple spine structural parameters was reported. This method has an advantage of requiring a relatively small number of a training dataset, and seven features were reported to be effective for spine classification. Because the details of the datasets and the selection of effective features were not provided, general applicability of this method to other image samples should be judged by further trials. In summary, these efforts have not yet fully utilized the high 3D resolution of new imaging modalities capable of overcoming the diffraction barrier.

Here, we describe an accurate method for spine morphological measurement based on structured illumination microscopy (SIM) and subsequent data conversion to the surface mesh data. Dimensional reduction and supervised machine learning enabled us to perform objective spine classification and identify morphological impairments caused by genetic mutations in key signal transduction molecules. Time-lapse SIM imaging could be combined with this analytical method to generate shape transition diagrams. Furthermore, analysis of spines exposed to locally uncaged glutamate revealed stable concave surfaces on activated spine heads, which may serve as core structural elements of synaptic plasticity.

Results and Discussion
A method for measuring nanoscale surface geometry of spines. Our analytical pipeline for spine computational geometry consists of three steps (Fig. 1a, b). First, three-dimensional SIM (3D-SIM) images of dendritic segments in dissociated hippocampal neurons labeled with either fluorescent proteins or the lipophilic dye Dil were obtained, and voxel data of fluorescent spines were converted to the surface mesh data using automated algorithms. Second, the numerical features of 3D spine morphology were calculated by computational geometry from a dataset for a large population of spines. Finally, the high-dimensional data of recorded numerical features (descriptors) were transformed to a space with fewer dimensions by principal component analysis (PCA), followed by support vector machine (SVM)-based shape classification. To validate this method, we analyzed neurons derived from heterozygous synGAP mutant mice (synGAP1−/−) or mice harboring a knock-in of a kinase-dead allele of CaMKIIα/ calmodulin-dependent protein kinase IIα (CaMKIIαK42R/K42R) and confirmed that this method can detect mutated gene-specific spine structural changes.

We obtained 3D-SIM images of cultured hippocampal neurons expressing GFP (Fig. 1a). 3D-SIM microscopy theoretically offers a twofold resolution gain in both the lateral and axial directions in comparison with conventional wide-field microscopy. This property was confirmed by measuring intensity profiles of diffraction-limited images and SIM images of fluorescent beads (Supplementary Fig. 1). We found that correction of spherical aberration by precise matching of refractive index and stabilization of sample temperature improved the resolution close to the theoretical limit and enabled reliable detection of dendritic spines protruding vertically in the axial direction (Supplementary Fig. 1). We next tested multiple image segmentation algorithms and found that Otsu’s method, modified for multi-level thresholding, combined with the technique of geodesic active contours, was resistant to variations in dendritic morphology and image intensity (Supplementary Fig. 2). Individual spines were detected and isolated automatically using a custom software (Fig. 1a, Supplementary Fig. 3). The method is based on fitting of dendritic shafts with elliptic cylinders followed by detection of structures outside of the cylinder as spine candidates (Supplementary Fig. 4). These spine candidates were further sorted automatically by criteria based on their volumes and shapes (see the Methods section for the details). This method is based on the morphological criteria and cannot distinguish very short spines from small raised structures on dendritic shafts. Nevertheless, the detection criteria of spines are objective and the results are reproducible. After spine isolation, polygonal meshes of iso-surfaces were extracted from the spine voxel data using the marching cube algorithm (Fig. 1b, Supplementary Fig. 3). These spine mesh objects were automatically analyzed by techniques for feature extraction from 3D mesh models or by discrete differential-geometry operators (Supplementary Fig. 5). Ultimately, we obtained 10 descriptors of spine shape from experimental datasets of more than a 1000 spines. These descriptors include both basic shape features (e.g., length, surface area, and volume) and more complex shape and surface features (e.g., convex hull, mean curvature, and Gaussian curvature).

Surface geometry of spines and quantitative analysis. To confirm the accuracy of multiple shape descriptors extracted from SIM imaging, we performed quantitative comparison of SIM-based data from fixed samples with surface mesh data generated by EM reconstruction of identical dendritic segments (Fig. 1c). All spines detected in EM images were also recovered in SIM-based surface mesh data irrespective of the protrusion direction. A minor fraction of spines (<15%) overlapped with adjacent spines and were excluded from the analysis. Mean curvature plots revealed that negative and positive curvatures of spine surfaces are...
were preserved between the SIM-based and EM-based 3D data (Fig. 1d). The concave surface was present in 61% of spines of which volumes were more than 0.18 $\mu$m$^3$ (this spine population corresponds to 25% of the total spines and 84% of them are classified as mushroom spines using our machine-learning method. See the next section for the detection of mushroom spines.) and matched the position of the synaptic junction and postsynaptic density (PSD) (Fig. 1c, d, Supplementary Figs. 6 and 7). Thus, the spine concave surface may be a biologically important feature that reflects the presence of junctional complex between pre- and postsynaptic membranes. The values of descriptors for basic shape features (length, surface area, and volume) were highly correlated between surface mesh data extracted from 3D-SIM and EM images (Fig. 1e), indicating the precision of SIM-based spine analysis.

Lengths of spines protruding from dendritic shafts at different angles were measured in both 3D-SIM and EM images (Supplementary Fig. 8). Both horizontally and vertically
Spine structural features with impaired synaptic plasticity. Spine distribution in the feature space exhibited a continuum of morphological properties of spines. Spine distribution in Fig. 2a, b) were located closely to each other in the feature space, raising the possibility of automatically identifying mushroom spines. These results demonstrate the potential of this analytical method to detect spine morphological changes associated with mutations in structural characteristics of dendritic spines.

We next applied this automated classification method to the detection of spine structural changes associated with mutations in gene encoding plasticity-related signaling molecules. To this end, we obtained 3D-SIM images of neurons derived from heterozygous synGAP mutant mice (synGAP+/−) or mice harboring a knock-in of a kinase-dead allele of Ca2+/calmodulin-dependent protein kinase IIa (CaMKIIaK42R/K42R)16 (Fig. 2d). Both mutations result in severe impairment of long-term potentiation in the hippocampus15,16. To avoid possible bias of GFP transfection into specific types of neurons, we stained randomly selected neurons by applying DiI (Supplementary Figs. 9 and 10). SIM-based quantitative analysis revealed changes in spine morphology specific for each mutation (Fig. 2e). Neurons from either synGAP+/− mice or CaMKIIaK42R/K42R mice formed mushroom spines with reduced volume, with no change in the volume of non-mushroom spines (Fig. 2f). The two mutants exhibited distinct spine length phenotypes, with shorter mushroom spines in synGAP+/− neurons and longer non-mushroom spines in CaMKIIaK42R/K42R neurons. The results suggest a more specific impairment in mushroom spines with the synGAP mutation, and a specific role of CaMKIIa in suppression of long non-mushroom spines. These results demonstrate the potential of this analytical system to detect spine morphological changes associated with dysfunction of specific signaling pathways.

Computational geometry of spines in vivo. Spine geometrical analysis requires high-resolution imaging of dendritic spines. SIM imaging of dissociated neurons in culture has sufficient resolution, but alternative approaches are required for the analysis in intact brain tissue. To test if confocal laser scanning microscopy is suitable for spine geometrical analysis, we performed in silico analysis of spine shape degradation by optical blur (Supplementary Fig. 11a–c). By narrowing confocal aperture [0.5 airy unit (AU)], the resolution was sufficient to detect spine head curvature...
for large spines (>0.18 μm$^3$). Because SIM analysis of cultured neurons showed that only 13% of middle-to-small-sized spines (<0.18 μm$^3$) had concave surfaces, the confocal scanning microscopy may still be useful in feature extraction of large spines in intact tissue. We also confirmed that spine size distribution was similar between hippocampal neurons in culture and in the intact hippocampal tissue$^{23}$ (Supplementary Fig. 12). Therefore, we expected that geometrical features of large spines could be detected by high-resolution confocal microscopy applied to intact brain tissue.

We applied confocal microscopy with confocal aperture of 0.5 AU to CA1 pyramidal neurons expressing YFP in fixed brain sections (Supplementary Fig. 11d, f). Horizontally and vertically protruding spines could be detected and converted to the surface...
mesh data. Consistent with the prediction of in silico analysis, concave surfaces were detected in large spines (~20% of the total spine population). We conclude that this application in intact tissue is useful in geometrical analysis of spine head surface, which reflect the presence of the junctional complex between pre- and postsynaptic membranes (Supplementary Figs. 6 and 7).

Spine population data obtained by confocal microscopy of intact tissue may be useful in analysis of spine phenotypes based on dimensional reduction and machine learning. To test this possibility, we collected the data of spine surface geometry in tissue sections (n = 165) and compared the distribution in the feature space with the data from cultured neurons (Supplementary Fig. 13a). Distributions of spine geometrical features from samples in culture and in vivo show high similarity, and the concave surfaces were detected in large spines (~20% of the total spine population).

**Shape transition of spines studied by time-lapse 3D-SIM.** An advantage of SIM-based geometrical analysis is its potential use in the studies of spine dynamics and activity-dependent regulation. To follow temporal changes in spine shape, we performed time-lapse 3D-SIM imaging of living hippocampal neurons expressing GFP (Supplementary Fig. 14a, b). Comparison of live and fixed spines confirmed that the reconstructed mesh structures from live and fixed cells were of comparable quality, and the concave surface in the spine head was preserved (Supplementary Fig. 14c).

Using PCA, we mapped the trajectories of shape transitions of individual spines in the feature space (Fig. 3a) and generated a 3D map depicting the behavior of the spine population (Fig. 3b). We found that spines in different domains of the feature space behaved differently. For example, the large mushroom-shaped spine in Fig. 3a (magenta arrows) moved bidirectionally in the upper right and lower left directions. The medium-sized spine (orange arrows) exhibited short trajectories, resembling a random walk process, whereas the trajectory of the small spine (green arrows) was in the upper left direction. To further clarify the overall tendency of the shape transition, we generated a diagram in the feature space that shows the direction and length of trajectories partitioned into voxels with edge length of 1 x standard deviation (SD) (Fig. 3c). This diagram further confirmed the relationship between spine shape transition and spine shape features. Using the SVM classifier combined with trajectory analysis, it was possible to label spines with groups 1–3 (Supplementary Fig. 15). Spines of group 1 (small mushroom spines without an orientation preference in their trajectories), group 2 (large mushroom spines with preferred trajectories along the axis of medium/thin and large/round shape features), and group 3 (non-mushroom spines) had different shape characteristics and dynamics (Fig. 3d).

The three groups of spines overlapped in the feature space, and their distribution did not reflect the existence of distinct shape classes. However, spines may have additional geometric features that would aid in understanding the mechanisms underlying the maintenance of their shapes and behaviors. Correlative analysis of 3D-SIM and EM images indicated that the concave surfaces of spine heads tended to be associated with the presynaptic component and formed synaptic junctions (Fig. 1c, d). When the concave surfaces of spine heads were mapped at multiple time points, their stability differed markedly among groups (Fig. 3e). Most group 2 spines maintained the concave surface during imaging sessions of 60 min (10 out of 11 spine time-lapse images), whereas group 1 spines changed their shape and either lost the concave surface or changed its position (5 out of 7 time frames, 3 spines, Fig. 3f). Group 3 spines formed the concave surface less frequently than those of the other two groups, and exhibited a strong tendency to progressively decrease their size, suggesting that this spine population was undergoing the process of retraction. This result indicates that formation of stable junctions between presynaptic and postsynaptic compartments is associated with maintenance of spine shape and dynamics.
Time-lapse 3D-SIM images before and after uncaging revealed stabilization of the concave surface on the spine head (Fig. 4b). To evaluate the size of the concave surface, we calculated the volume difference between the convex hull and the spine head, normalized by the spine head volume (Fig. 4c). This index (concave volume ratio) reflects the relative size of the concave surface on the spine head, and its increase lasted more than an hour after the induction of synaptic plasticity (Fig. 4d).

The increase in the size of a spine’s concave surface may indicate an increase in the junctional area between the presynaptic and postsynaptic components. Synaptic cell adhesion molecules are involved in the formation of synaptic junctional...
structures. Trans-synaptic interaction between the neurexin and neuroligin is important for formation of excitatory synapses and is essential for synaptic plasticity. Moreover, the extracellular domains of these proteins can form a superstructure resembling the extracellular structure of the synaptic cleft. Among the four neuroligin isoforms in rodents, neuroligin 1 localizes at excitatory postsynaptic sites and plays a dominant role in hippocampal long-term potentiation. Because the affinity of neurexin 1 for neuroligin 1 is significantly higher than that of other neuroligin isoforms, we expected that exogenous application of neurexin 1-IgG fusion protein would effectively and transiently block neuroligin 1 function (Fig. 4e). This manipulation inhibited enlargement and stabilization of the concave surface, supporting the idea that membrane adhesion mediated by neuroligin 1 is involved in increasing the junctional surface of spines (Fig. 4f). This neuroligin-dependent mechanism of stabilization of the postsynaptic concave surface may be independent from the activity-
dependent neurelin cleavage, which rapidly regulates presynaptic function via the neurexin 30.

The time course of spine structural plasticity has been proposed to consist of three phases 31. After the initial phase of rapid actin reorganization, on the order of several minutes, the actin cytoskeleton is stabilized for about an hour, followed by slow accumulation of PSD proteins. Because the postsynaptic concave surface is maintained for more than an hour after uncaging, and neurelin 1 directly binds the prominent PSD scaffolding protein PSD-95 25, we next investigated whether blockade of neurelin 1 function also affects the delayed accumulation of PSD-95. Consistent with previous studies 31, the amount of PSD-95 in spines was unaltered within the initial 60 min, but began to increase ~80 min after uncaging (Fig. 4g, h). We found that application of neurexin 1β-Fc effectively blocked the delayed increase of PSD-95 (Fig. 4g, h). Together, these results suggest that the postsynaptic concave surface stabilized by neurelin 1 is an important structural element for the consolidation of synaptic plasticity.

In summary, we developed a method of reliably reconstructing and measuring the surface geometry of dendritic spines from 3D-SIM images. The data regarding spine volume, area, and length can be converted to absolute values after calibration with mesh data obtained from EM images. The method is efficient enough to perform data acquisition and quantitation of more than 1000 spines within several days, which cannot be achieved by reconstruction of EM data. The method could be modified for the analysis of images obtained by other super-resolution techniques, such as stimulated emission depletion (STED) microscopy, which is suitable for the analysis of dendritic spines in the tissue environment 7,32,33. Although the lateral resolution of 3D-SIM is lower than that of STED microscopy, the superior axial resolution of 3D-SIM is advantageous for reconstruction of spine geometry. Ideally, isotropic 3D-STED imaging combined with the technique of the surface mesh reconstruction should be applied to achieve higher-resolution measurement of spines 31.

We identified the concave surface of spine heads, which interact with the presynaptic terminal, as a unique structure that is expanded and stabilized by plasticity-inducing signals. We propose that this surface structure plays important roles in actin-dependent shape changes by recruiting regulatory molecules of actin filament nucleation and branching 34. A recently identified interaction between neurelin and the WAVE complex may play a role in increased actin-dependent shape changes after expansion of the concave spine surface. This model suggests that concave spine surface that persists after glutamate uncaging serves as a core structural element of synaptic plasticity.

**Methods**

**Neuronal culture from genetically modified mice.** ICR mice (Japan SLC), heterozygous synGAP mutant mice (synGAPΔ15) 35, homozygous knock-in mice harboring a knock-in of a kinase-dead K42R mutation in Ca2+/calmodulin-dependent protein kinase Iα (CaMKIIαK42R/K42R) 16, and Thy1-GFP 17 mice were used in this study. All animal experiments were approved by the animal welfare ethics committee of the University of Tokyo.

Dissociated hippocampal cultures were prepared from E16.5 ICR mouse embryos 36. Briefly, hippocampi were treated with trypsin (Gibco) and DNase (SIGMA), and then mechanically dissociated. Cell suspension in the MEM containing B18 supplement, L-glutamine (Gibco), and 5% FCS (Equitech-Bio) was plated onto a glass-bottom dish (MatTek, #1.5) coated with poly-L-lysine (SIGMA). Two days after plating, 5 μM ara-C (SIGMA) was added to prevent glial cell proliferation.

Hippocampal dissociated cultures from synGAPΔ15/− mice or CaMKIIαK42R/K42R mice were prepared using the same basic culture protocol as in the experiments using wild-type ICR mice, except that hippocampi from each embryo were dissociated separately. For genotyping of dissociated cultures, a piece of tissue from each embryo was saved prior to dissection of hippocampi. Genomic DNA purification was performed with the QuickGene DNA tissue kit (WAKO), and genotypes were determined by PCR using either High-Speed DNA polymerase (Kaneka) or ExTaq (TAKARA) according to the standard protocols provided by the manufacturers.

**Fluorescent protein expression and Dil labeling of neurons.** Ca2+/3,3′,3′,3′′-tetramethylindocarbocyanine perchlorate (DiI; Molecular Probes) 38. Fixed neurons in a culture dish were placed on the stage of an inverted microscope (IX71, OLYMPUS). Dil was dissolved in fish liver oil at saturation concentration and applied to individual cell bodies by pressure ejection with a Femtotet (Eppendorf). The cells were left to stand for 30 min at 25 °C to allow the dye to spread, and then washed three times with PBS.

**Uncaging of caged glutamate.** Single-photon laser photolysis of 4-methoxy-7-nitroindolinyl-caged glutamate (MNI-Glu) was performed using a 405 nm continuous-wave (CW) laser 39. An uncaging laser (OBIS 405LX-100, Coherent) was used to generate a calcium phosphate precipitate, and cells were incubated for 50 min in a 5% CO2 incubator at 37 °C. The composition of transfection medium was identical to that of the culture medium, except that hippocampi from each embryo were dissociated separately.

**Embryonic day 16.5 ICR mouse hippocampal culture.** Dissociated hippocampal cultures were prepared from E16.5 ICR mouse embryos 36. Briefly, hippocampi were treated with trypsin and DNase. Cell suspension in the MEM containing B18 supplement, L-glutamine (Gibco), and 5% FCS (Equitech-Bio) was plated onto a glass-bottom dish (MatTek, #1.5) coated with poly-L-lysine (SIGMA). Two days after plating, 5 μM ara-C (SIGMA) was added to prevent glial cell proliferation.

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was combined with an imaging line of a Nikon Structured Illumination Microscope system (N-SIM) using a dichroic mirror. The uncaging laser was controlled separately using the Coherent Connection software (Coherent) via a transistor–transistor logic (TTL) generated by an Arduino UNO microcontroller. The uncaging laser was aligned to the center of the imaging field before each experiment.

For glutamate uncaging, hippocampal neurons were maintained at 37 °C in Mg2+-free Tyrode’s solution (119 mM NaCl, 2.5 mM KCl, 4 mM CaCl2, 0 mM MgCl2, 25 mM HEPES, and 30 mM glucose; pH 7.4) with 1 μM tetrodotoxin (TTX; WAKO) and 500 μM N-Methyl-D-aspartate (NMDA). Medium-size spines with clear heads and necks were selected for induction of structural change. Single-photon glutamate uncaging was performed by 2 μs, Q-switched pulses at 1 Hz for 1 min with the center of the focused laser beam 1–2 μm away from the tip of the spine. Precise control of the sample position was achieved by operating a motorized XY stage with N-SIM encoders. Laser intensity was set to 0.05–0.15 mW at the back aperture of the objective lens.

Sample preparation for SIM imaging. After 18–22 days in vitro, hippocampal neurons were washed with PBS and fixed with 4% paraformaldehyde and 0.5% glutaraldehyde in PBS for 30 min at 25 °C. Samples after transfection of GFP expression plasmids were mounted in ProLong®Diamond (Molecular Probes). Dif-labeled neurons were imaged in PBS. For correlative light microscopic and EM observation, cells were washed with PBS and fixed with 2% paraformaldehyde and 2% glutaraldehyde in PBS for 30 min at 25 °C.

Apparatus for SIM imaging. SIM imaging was performed with a N-SIM based on an inverted microscope (ECLIPSE Ti-E, NIKON), equipped with an oil immersion TIRF objective lens (SR Apo TIRF 100 ×, N.A. 1.49, NIKON), a laser system consisting of 405, 488, 561, and 640-nm diode lasers (LU-NV, NIKON), and an EMCCD camera (iXon3 DU-897E, Andor Technology). SIM imaging with this system is based on a previous report. Briefly, excitation lasers were coupled to a multimode optical fiber, collimated, and directed to a fused silica linear transmission-phase grating. A shutter in an intermediate pupil plane discarded all diffraction orders except for 0 and ±1. The three beams were refocused in the back focal plane of the objective lens. The beams produced as diffraction orders ±1 and −1 were focused near the opposing edges of the back focal plane aperture, and the beam produced as order 0 was refocused at its center. Three-dimensional data were acquired with five-pattern phases spaced by 2π/5 and three-pattern orientations spaced 60° apart. The acquired images were computationally reconstructed to obtain a high-resolution image with resolutions of ~115 nm in the x- and y-dimensions and ~270 nm in the z-dimension.

SIM image acquisition. Prior to SIM imaging, the temperature of the microscope system and specimens was stabilized at 28 ± 2°C to minimize position and aberration fluctuation. Spherical aberration induced by refractive index mismatch was corrected for each sample by adjustment of an objective correction collar. The EMCCD camera, which has a 512 × 512 pixel array consisting of 16-μm square pixels, was operated in read-out mode at 1 MHz with 16-bit analog-to-digital conversion of the pixel signal. Each image stack with its dimension was acquired at 63 axial planes with 120 nm z-steps that satisfied the Nyquist criterion requirements. Dendritic segments that were isolated from unintended signals, such as axons or dendrites from other neurons, were carefully selected, because objects brighter than targeted dendritic segments were problematic in threshold setting for SIM image reconstruction.

SIM image reconstruction. All image processing steps were performed in three dimensions. The acquired datasets, comprising 63 axial sections of 512 × 512 pixels, were computationally reconstructed using reconstruction stack algorithm V2.10 of NIS-Elements AR (NIKON). The voxel size of the reconstructed images was 32 nm in the x- and y-dimensions and 120 nm in the z-dimension, with 16-bit depth. 3D-SIM data were acquired using the SIMcheck plugin for Fiji (Supplementary Fig. 1). First, the standard SIMcheck procedure was performed using raw SIM data and the reconstructed image. Second, using a standalone Fourier transform plugin of SIMcheck, 2D fast Fourier transform (FFT) was applied to each slice of the reconstructed SIM image. The plugin, which was set to operate without a cutoff function, with a window function (6% width), generated an 8 bit log-scaled (amplitude2) Fourier power spectrum that was the same as the default FFT function and with a window function (6% width), generated an 8 bit log-scaled image stack of the 3D-SIM images were sequentially acquired at the same z-position, and this step was repeated with multiple z-positions. The final imaging volume spanned 65 × 65 × 50 μm of 45 axial planes separated by 120-μm z-steps. The two channels of the image stacks were reconstructed in parallel using reconstruction stack algorithm V2.10 of NIS-Elements AR.

Live SIM imaging. Live cell imaging was performed after 18–22 days in vitro. Cells in the culture medium were placed in a heater stage system (INUG2H-TIZSH, Tokai Hit) at 37 °C with a continuous flow of 5% CO2 to maintain the pH of the medium. The glass-bottom lid with its imaging stage was utilized to minimize evaporation of the culture medium. During live imaging, the z-position was maintained by a perfect focus system (NIKON).

For live 3D-SIM, an image stack 7.56-μm thick was acquired, consisting of 63 axial planes separated by 120-μn m z-steps. The series of 3D-SIM images were acquired using the SIMcheck plugin for Fiji and lasted 10 min for a total of up to 5 h and the total number of frames was 6615 (15 patterns × 63 axial planes × 7 time points) at most. Excitation laser power was set to be minimal but sufficient to reconstruct images with a sufficient signal-to-noise ratio even at the end of the time-lapse series (Supplementary Fig. 14). Bleaching of GFP fluorescence may be attenuated by fast diffusion of GFP within the dendritic cytoplasm. Data quality of 3D-SIM imaging sets was confirmed using the SIMcheck plugin for ImageJ. Acquisition of a single 3D-SIM image stack took 490 s (100 ms exposure time × 15 patterns × 63 axial planes × 7 z-steps). The acquisition speed of N-SIM was mainly limited by rotating and laterally translating the grating. The 3D-SIM volume at each time point was imaged and reconstructed with SIMcheck algorithm with NIS-Elements AR. Neurons were confirmed as remaining alive for at least 1 day after time-lapse imaging.

Prior to glutamate uncaging, live 3D-SIM images were obtained every 10 min in the same volume in a volume 3.48 × 3.48 × 29 (29 axial planes separated by 120-μm z-steps). Subsequently, the culture medium was replaced with Mg2+-free Tyrode’s solution containing 1 μM TTX and 500 μM N-Methyl-D-aspartate (NMDA) and an uncaging laser was applied to spines that protruded horizontally from dendritic shafts. During uncaging, the external solution was replaced with the original culture medium for subsequent live 3D-SIM imaging. For neurobiolin blocking experiments, neurons were cultured in the culture medium. Glutamate uncaging was performed in Mg2+-free Tyrode’s solution containing 1 μM TTX, 500 μM N-Methyl-D-aspartate, and either 50 μg/ml recombinant human neurexin 1β-Fc (without splice insert 4, R&D Systems) or 50 μg/ml recombinant human Fc (R&D Systems) as a control. After uncaging, the external solution was replaced with the original culture medium containing 50 μg/ml recombinant human neurexin 1β-Fc or control-Fc, followed by time-lapse 3D-SIM imaging.

For imaging of PSD-95-GFP, N-SIM was operated in the wide-field mode. Hippocampal neurons expressing PSD-95-GFP and dsRed2 were examined after 18–22 days in vitro. Spines that protruded horizontally from dendritic shafts were imaged, and single-photon glutamate uncaging was performed. To avoid possible photo-bleaching of PSD-95-GFP, the output power and focus position of the uncaging laser were carefully adjusted. For neurobiolin blocking experiments, the culture medium was replaced with Mg2+-free Tyrode’s solution containing 1 μM TTX, 500 μM N-Methyl-D-aspartate, and either 50 μg/ml recombinant human neurexin 1β-Fc or 50 μg/ml recombinant human Fc (R&D Systems) as a control. After imaging, the external solution was replaced with the original culture medium containing 50 μg/ml recombinant human neurexin 1β-Fc or control-Fc, followed by time-lapse 3D-SIM imaging.

Corellar light microscopic and EM observation. Correlative light and electron microscopy was performed with dissociated neuronal culture. Following SIM imaging, phase contrast images of the same neurons were recorded and used as a reference to obtain EM images of the identical dendritic segments. For transmission electron microscopy, samples were post-fixed with 1.0% OsO4 and 1.5% potassium ferrocyanide in 0.1 M cacodylate buffer, and stained with 1.0% tannic acid in 0.05 M cacodylate buffer. Samples were dehydrated and embedded in epoxy resin (Poly/Bed®812 Luft Formulations, Polysciences). After 2 days of curing at 60 °C, the area imaged by SIM was cut out, and the bottom glass was removed by treating with hydrogen fluoride. After trimming the block, ultra-thin sections of 50–60 nm thickness were prepared in a Reichert ultramicrotome with a diamond knife and mounted in Formvar-coated copper slot grids. TEM images were acquired at 80 keV on a transmission electron microscope (JEM-1010, JEOL) with a CCD camera (TemCam-F216, TVIPS) at ×5000 magnification. Image alignment and reconstruction were performed using the Reconstruct software package (SynapseeWeb). Two operators manually identified the area (about 0.25 μm2) with the largest negative curvature from 3D-SIM data of each spine head. The positions of the recipient functional areas were recorded independently from the 3D-SIM images. The positions of the smallest negative curvature and the synaptic junctional area were compared and judged to determine whether the two areas overlapped. The positions were matched in 9 mushroom-shaped spines out of 10.

Tissue preparation and laser scanning confocal microscopy. Male transgenic mice (Thy1-H2BFP-GFP, 3 months old) were deeply anaesthetized and perfused with 4% paraformaldehyde in 0.1 M phosphate buffer. Brains were removed, post-fixed in 4% paraformaldehyde for 6–8 h, and then sectioned with 40-μm thickness in the
coronal plane on a vibratome (VT-1000S, Leica). The sections were washed with 88% (weight by volume) histodenz (SIGMA) in 0.1 M phosphate buffer and were mounted on coverslips (high-tolerance coverglass D = 0.17 ± 0.005 mm, Matsunami) in 88% histodenz for imaging.

Confocal microscopy was performed with an A1 confocal laser scanning microscope (Nikon). An oil immersion TIRF objective lens (Apo TIRF 100 ×, N.A. 1.49, NIKON) was used, and images were collected with confocal aperture of 0.5 AU. The image stacks with their size of 30.7 μm in x-y plane and 7.56 μm in the z axis were acquired. The voxel size of the images was 30 nm, 30 nm, and 120 nm in the x, y, and z directions, respectively. Prior to imaging, the temperature of the microscope system and specimens was confirmed to be stabilized, and spherical aberration was corrected for each sample by adjustment of an objective correction collar.

Automated image thresholding and surface mesh generation. Two independent thresholding methods were used to automatically isolate dendrites and spines from SIM image stacks. The reconstructed SIM image stacks were first processed by multilevel thresholding based on Otsu’s method, and the resultant binary images were further processed by geodesic active contours to refine object boundaries.

Otsu’s method automatically searches the threshold that maximizes the between-class variance of pixel intensity43. Direct application of Otsu’s method for thresholding SIM images of dendrites was not successful, mainly because the images contained both large objects with strong fluorescence (dendrites) and small objects with weak fluorescence (spines). However, Otsu’s method was previously extended for multilevel thresholding, and we found that the modified method could reliably detect multiple thresholds for both the strong fluorescence signal of dendrites and the weak signal of spines (Supplementary Fig. 2). After generation of binary images by multilevel thresholding, the resultant binary images were further processed to refine the boundaries of dendrites and spines by geodesic active contours45. The technique is based on active contours (snakes) evolving in time and pulled toward object boundaries until the energy function reaches its minimum. The evolving contours can split and merge in the iterative process, and this property helps to eliminate and merge isolated image pixels below the resolution of SIM microscopy (Supplementary Fig. 2). MATLAB has built-in functions for both multilevel thresholding [multithresh()] and geodesic active contours [activecontour()]. A custom MATLAB script was developed for processing SIM image stacks with these two image processing techniques (Supplementary Software "SIM_activecontour").

The binary image stack generated by thresholding SIM images was processed for automated detection of spines (Supplementary Fig. 3). A custom MATLAB script was developed for spine detection and polygon mesh generation (Supplementary Software "SIM_spine_detection"). Individual spines were detected and isolated automatically (Fig. 1a, Supplementary Figs. 3 and 4). Dendritic shafts were fitted with elliptic cylinders, and voxel clusters outside of the best fit of elliptic cylinders were identified as spine candidates (Supplementary Fig. 4b). These spine candidates were further sorted by criteria of their volumes and shape characteristics. We first rejected spine candidates with their volumes close to the upper limit of the volume from the best spine mesh (the largest volume available in our currently used Blender software). Next, we calculated the largest cross-section (OCS) in the plane normal to the longitudinal axis of the parent dendritic shaft and the length of the object along the longitudinal axis of the dendritic shaft (OL). If the ratio of OCS to OL was < 0.32 μm3, we finally calculated the convex hull volume (CHV) of the spine (Supplementary Fig. 5). Convex hull volume (CHV) is volume of the smallest convex set of vertices that contains the spine polygon mesh. Vertices and volume of the convex hull for a given spine mesh can be calculated by the built-in MATLAB function convhull(). From CHV, convex hull ratio (CHR) was calculated as follows:

\[
CHR = \frac{CHV}{V - V_i}/V
\]

Average distance (AD), the average distance between the individual vertices and the centroid of the spine/shaft junctional plane, was calculated using the following equation:

\[
AD = \frac{1}{N} \sum_{i=1}^{N} |A_i|
\]

where i and N stand, respectively, for the index of all vertices and their total number. Coefficient of variation in distance (CVD) is coefficient of variation of the calculated distances between the individual vertices and the centroid of the spine/shaft junctional plane.

Open angle (OA) is the average angle formed by the spine axis and each vertex vector. (A vertex vector starts from the centroid of the spine/shaft junctional plane and ends at a vertex. Spine axis is specified by the average of all vertex vectors.) Mushroom spines with flat spine heads, as well as stubby spines, have larger values of OA. OA was calculated using the following equations:

\[
OA = \frac{1}{N} \sum_{i=1}^{N} \cos^{-1} \left( \frac{M \cdot A_i}{|M| \cdot |A_i|} \right)
\]

where i and N stand, respectively, for the index of all vertices and their total number.

The third group of parameters associated with spine morphology involves surface geometry. Curvatures on discrete surfaces made by polygon meshes can be estimated by the following operators21.

**Spine geometrical analysis.** Three-dimensional triangular mesh surfaces of spines were processed using custom MATLAB scripts (Supplementary Software "Geometric_calculation" and "Geometric_curvature"). First, basic geometrical parameters, including spine length, spine surface area, and spine volume, were calculated using the following equations:

Spine length \((L)\) was calculated using the following equation:

\[
L = \sum_{i=1}^{N} \left( |A_i| \right)
\]

where \(i\) stands for the index of all vertices with distances from the centroid of the spine/shaft junctional plane \((c_x, c_y, c_z)\) larger than the upper 95% of the distances for all vertices. \((x_i, y_i, z_i)\) are the coordinates of the vertices. (Note that this parameter is different from the authentic curvilinear length from the base to the tip of the spine. Our parameter gives more reasonable estimates for spines with complex morphology, which have multiple protrusions and extending thin edges, but provides lower estimates for long curved spines.)

Spine surface area \((S)\) was calculated using the following equation:

\[
S = \sum_{i=1}^{N} \left( \frac{1}{2} (v_{x2} w_{x3} - v_{x3} w_{x2})^2 + (w_{x1} v_{x2} - u_{x1} w_{x2})^2 + (u_{x1} v_{x3} - v_{x1} u_{x3})^2 \right)
\]

where \(i\) stands for the index of all elementary triangles. \((u_{x1}, v_{x1}, w_{x1})\) and \((u_{x2}, v_{x2}, w_{x2})\) are vectors corresponding to two edges of triangle \(i\).

Spine volume \((V)\) was calculated using the following equation:

\[
V = \sum_{i=1}^{N} \left( -\frac{1}{6} (s_{y2} z_{y3} a_i + s_{y3} z_{y2} a_i + s_{x2} z_{x3} a_i - s_{x3} z_{x2} a_i - s_{x2} z_{x3} a_i + s_{x3} z_{x2} a_i) \right)
\]

where \(i\) stands for the index of all elementary triangles. \((s_{x1}, y_{x1}, z_{x1})\) and \((s_{x2}, y_{x2}, z_{x2})\) are the coordinates of the vertices of triangle \(i\).

Additional geometric parameters that reflect more complex morphological features were also included. Schematic explanations of the measured values are provided in Supplementary Fig. 5.

**Mushroom spines with flat spine heads, as well as stubby spines, have larger values of OA.**

**Open angle (OA) is the average angle formed by the spine axis and each vertex vector.**
Mean curvature (MC) at the vertex \((x_i)\) specified by the vector \((\mathbf{x}_i)\) was calculated using the discrete approximation of the Laplace-Beltrami operator \(K\):

\[
K(x_i) = \frac{1}{2A} \sum_{j \neq i} \left( \cot \alpha_j + \cot \beta_j \right) (\mathbf{x}_i - \mathbf{x}_j) 
\]

where \(n\) is a group of vertices surrounding the central vertex \(x_i\), \(A\) is the size of the barycentric region with its center at \(x_i\), \(\alpha_j\) and \(\beta_j\) are the opposite angles of the two triangles sharing the edge \(ij\).

Gaussian curvature (GC) at the vertex \((x_i)\) was calculated using the following equation:

\[
GC = \frac{1}{2} \left( 2 - \sum_{j \neq i} \theta_j \right) \sin \theta_i
\]

where \(n\) is a group of vertices surrounding the central vertex \(x_i\), \(\theta_j\) is the \(jth\) angle of the triangle \((x_i, x_j, x_k)\), and \(A\) is the size of the barycentric region with its center at \(x_i\).

MC and GC were calculated for all vertices belonging to spine surface meshes. Averages of MC and GC (avMC and avGC) were used as morphological parameters for individual spines. For the quantitative analysis of local surface curvature, spine mesh sizes were increased to maintain the resolution of the SIM (the minimum area of triangle meshes was >0.004 \(\mu m^2\)).

In summary, we calculated 10 parameters \((L, S, V, \text{CHV}, \text{CHR}, \text{AD}, \text{CVD}, \text{OA}, \text{avMC}, \text{and avGC})\) for each spine as descriptors of spine shape features.

**PCA and SVM.** Geometrical parameters of spines were calculated and analyzed by the PCA method. From our initial analysis of independence among 10 descriptors \((L, S, V, \text{CHV}, \text{CHR}, \text{AD}, \text{CVD}, \text{OA}, \text{avMC}, \text{and avGC})\), we selected five descriptors \((L, V, \text{CHR}, \text{CVD}, \text{OA})\) based on two criteria. First, we selected two descriptors that reflect principal structural features (length and volume). Second, three other descriptors that were relatively independent with the initial two descriptors and with each other (the averages of pairwise correlation coefficients were <0.3) were selected. PCA was applied to two types of image samples, neurons expressing GFP and neurons labeled by Dil\(^4\). In both cases, the first three components in the reduced representation covered more than 94% of the variance. Comparison of the weights for GFP and Dil projection matrices indicated that the differences were small \((5.6 \pm 4.1%\), mean \pm SD, for weights \(>0.4\)). Based on this observation, whether the projection matrix generated from the merged data of GFP and Dil could be used for efficient dimensionality reduction was next investigated. When the two datasets were merged, the GFP dataset was converted to Dil data using the coefficients determined from the data obtained from neurons imaged by both GFP and Dil (Supplementary Fig. 9). Again, the first three PCs after PCA covered >90% of the variance in the data. This projection matrix was used in subsequent spine analyses for neurons from genetically modified mice and time-lapse 3D-SIM experiments. For this purpose, the class sklearn.decomposition.PCA in scikit-learn, a machine-learning library (scikit-learn.org), was used.

For classification of mushroom and non-mushroom spines with SVM\(^4\), one expert manually labeled 1335 and 914 polygon meshes of spines generated from 3D-SIM images of GFP-expressing and Dil-labeled neurons, respectively. Using these labeled datasets, two hyperparameters, \(C\) (penalty parameter) and \(\gamma\) (coefficient for radial basis function (rbf) kernel), were optimized by grid search, and the model performance was assessed by k-fold cross-validation (Fig. 2a). The trained SVM classified mushroom spines of GFP-expressing and Dil-labeled neurons with identical accuracy (89%). When the trained SVMs for GFP and Dil were exchanged, the high accuracy was still preserved (85% for classifying GFP data with a SVM trained with Dil data; 87% for classifying Dil data with a SVM trained with GFP data). Because the distinction between mushroom and non-mushroom spines is not always unambiguous, and classification by human operators is prone to high variability, three additional experts were introduced for manual labeling of 400 polygon meshes of spines from GFP-expressing neurons. Comparison of the classifications by the three experts and SVM revealed that the percentage match between human operators and SVM was comparable with that among human operators, implying that SVM-based classification of spines is advantageous because it removes human subjectivity (Supplementary Table 1). Hyperparameter tuning and SVM classification were performed using classes sklearn.model_selection.GridSearchCV and sklearn.decomposition.SVC in scikit-learn.

**Analysis of spine shape transition.** Automated image thresholding and surface mesh generation were applied independently for each time point. After image processing, the difference in threshold values for Otso’s method from the average were confirmed to be within 20%. Corresponding spines at different time points were further analyzed using the same parameters for spine geometrical analysis. Trajectories of spine shape transition over time were mapped in the feature space following PCA (Fig. 3b). Vectors of shape transitions in the feature space were mapped into grids with edge lengths of \(1\) \(\times\) \(SD\), and the total lengths of trajectories and the vector components projected onto orthogonal directions were calculated (Fig. 3c). Classification of spines after time-lapse imaging was based on SVM-based classification into mushroom and non-mushroom spines, followed by two-ring mapping to the plane, with the absicca representing position in PCA feature space and the ordinate representing the orientation preference of the trajectories (Supplementary Fig. 15b). The orientation preference was calculated by the ratio between two orthogonal components of the shape trajectories in the plane of PC1 and PC2. Two orthogonal directions were chosen to be either parallel or perpendicular to the line 45° counterclockwise from the PC1 axis. When the orientation preference was >1, the trajectory was judged to be closer to the direction from small/thin to large/round spines (Fig. 3c, d).

Stability of the concave surface of spine heads was based on MCs calculated at spine vertices. As a first step, up to 10 vertices with the smallest negative MC values were selected. Next, the average values of MCs were calculated over two-ring neighborhoods (a given start vertex plus the first and second neighborhood vertices), the area of which roughly corresponds to the size of the PSD, which has a diameter of 400 nm. Based on the average MCs for the 10 candidate areas, the area with the smallest negative average MC was selected and mapped to the spine head. When the smallest negative MC of a single vertex within the area was greater than −7 or the number of vertices with negative MC values was less than 4, this surface was rejected, and the spine was judged to have no clearly identifiable concave surface. This method reliably predicted the positions of pre- and postsynaptic interfaces in the correlative SIM and EM analyses when prominent concave surfaces were detected (Fig. 1c, Supplementary Figs. 6 and 7). Concave surface ratio was calculated as the number of time points, when the spine was judged to have a clear concave surface divided by the number of total imaging time points for that spine. Stability of concave spine surfaces in time-lapse experiments (Fig. 3f) was evaluated by dynamic representation of the central vertex \((V_c)\) in the concave surface divided by two time points \((t_1\) and \(t_2\)). The lines that passed the centroid of whole-spine polygon \((C_{spine})\) and the \(V_c\) were drawn at \(t_1\) and \(t_2\), and the angle between these two lines after alignment of \(C_{spine}\) was calculated \(\angle V_c(C_{spine},V(t_1))\). If this angle was >60°, the concave surface was judged to be unstable. Concave surface stability was calculated as the ratio of the number of time points when the spine was judged to have a stable concave surface divided by the number of total imaging time points minus 1.

Structural changes in concave surfaces before and after induction of spine structural plasticity were measured by evaluating CHV and V of the spine heads and calculating CHR. Larger CHR indicates more space between the convex hull and original spine volume, which mainly reflects the volume made by the concave surface of the spine.

**Model spine generation and simulation.** For simulation of spine image degration by optically induced blur, in-silico model spines were generated using a custom MATLAB script. Initial parameters were set as spine head radius of 500 nm, spine neck radius of 150 nm, and spine neck length of 700 nm. We also removed a part of spine head volume to mimic concave surface on the spine head. The volume removed from the spine head was defined by the overlap of two spheres, one for spine head volume and the other for exclusion volume, with its radius of 400 nm. The distance between the centers of two spheres was set to 250 nm to 450 nm. Model spines with different sizes were generated by proportionally transform the original spine shape. The model spine volume was set in a range of 0.08–0.57 \(\mu m^3\).

The image stacks were convolved with the Gaussian filters corresponding to SIM resolution \((115 nm, 115 nm, and 270 nm in the x, y, and z directions, respectively) or resolution of confocal microscopy with confocal aperture set to 0.5 AU \((190 nm, 190 nm, and 410 nm in the x, y, and z directions, respectively\) by the built-in MATLAB function convn\(^\). The convolved image stacks were first binarized by multilevel thresholding based on Otso’s method without geodesic active contours, followed by conversion to polygon mesh data of eqMCs generated at individual spine vertices. If clustered vertices of negative curvature \((-2.5\) were detected on a spine head, the spine image degraded by the optical system was judged to still preserve their original concave surface.

**Comparison of spine shape in culture and in vivo.** We compared our own spine volume data in cultured neurons expressing GFP \((n = 1335)\) with the data of EM-reconstructed in vivo spines \((n = 938)\) available in the open data repository linked to the publication by Bless et al.\(^\). Both data were generated from hippocampal pyramidal neurons. The data for spine length in vivo were also taken from a previous publication \((n = 100)\). Previous reports of direct comparison between chemical fixation and cryofixation reported that tissue shrinkage in the process of fixation, dehydration, and embedding for EM sample preparation was ~26% in the neuropil\(^\). We assumed that the shrinkage of spines should be proportional to the overall shrinkage of the neuropil. Based on this idea, we reduced the measured spine volume in cultured neurons by the factor of 0.74 before generating the histogram shown in Supplementary Fig. 12. It should be noted that in the case of chemical fixation of cultured neurons, shrinkage of dendrites and spines was negligible (Supplementary Fig. 14). This difference in the effect of shrinkage may be derived from the difference in the concentration of fixatives, the speed of chemical reaction, or the osmolality of fixative solutions\(^4\).
Statistics. Data are expressed as means ± SEM unless otherwise noted. The statistical tests used for each experiment and the exact value of n (number of spines) are indicated in the corresponding figure legends. Statistical significance was determined by one-way ANOVA followed by Tukey–Kramer procedures for multiple comparison tests, using the Statistics and Machine-Learning Toolbox of MATLAB (MathWorks). The equality of probability distributions was evaluated by Kolmogorov–Smirnov test. P-values < 0.05 were considered statistically significant (p < 0.05, *p < 0.01, **p < 0.001).

Reporting summary. Further information on experimental design is available in the Nature Research Reporting Summary linked to this article.

Code availability
Custom scripts written in MATLAB R2017b are provided as Supplementary Software, and custom scripts written in Python are available from the corresponding author upon request.

Data availability
All data files are available from the corresponding author on reasonable request.

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Author contributions
Y.K. and S.O. designed the research; Y.K, T.H., K.O. and Y.S. performed the experiments; N.H.K. and S.G.N.G. contributed to analysis of mutant animals; Y.K. and S.O. analyzed data; and Y.K. and S.O. wrote the paper.

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