Analysis of implicit type of a generalized fractional differential equations with nonlinear integral boundary conditions

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\textbf{Abstract}

The given paper describes the implicit fractional differential equation with nonlinear integral boundary conditions in the frame of Caputo-Katugampola fractional derivative. We obtain an analogous integral equation of the given problem and prove the existence and uniqueness results of such a problem using the Banach and Krasnoselskii fixed point theorems. To show the effectiveness of the acquired results, convenient examples are presented.

Keywords: implicit fractional differential equation, fractional derivative and fractional integral, fixed point theorem.

2010 MSC: 35A22, 26A33, 34A08.

1. Introduction

The subject of fractional differential equations (FDEs) has lately developed as a motivating area of research. In reality, fractional derivatives kinds supply an excellent tool for the description of the memory and hereditary properties of different materials and operations. More researchers have established that FDEs show in many research scopes, such as physics, chemical technology, biotechnology, population dynamics, and economics. There has been considerable growth in FDEs involving many fractional derivatives such as Caputo, Riemann-Liouville, Hilfer, and Hadamard have been investigated and advanced by employing various tools from the nonlinear analysis. See the monographs of Podlubny [1], Kilbas et al. [2], Malinowska et al. [3], and some articles, for e.g., [4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14, 15, 16, 17] and the references cited therein. The forward evolution of the FDEs have been caught much interest lately as study some results on the existence and uniqueness of solutions of various types of FDEs under different conditions have been studied by

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many authors by employing fixed point techniques, see [18, 19, 20, 21, 22, 23, 24, 25, 26] and many other references.

In recent years [27] the researcher inserted a new fractional integral, which generalizes the Riemann-Liouville and Hadamard integrals into one form. For more properties of this new operator and similar operators, can be seen in [28, 29]. The identical fractional derivatives were established in [3, 30, 31] which named Katugampola fractional operators.

The existence and uniqueness results of FDEs involving Caputo-Katugampola derivative

\[ CKD_0^{\sigma, \rho} \omega(\vartheta) = g(\vartheta, \omega(\vartheta)), \quad \vartheta \in [0, T], \tag{1.1} \]

\[ \omega^{(k)}(0) = \omega_0^{(k)}, \quad k = 0, 1, ..., m - 1 \tag{1.2} \]

have been discussed using the Peano and Picard-Lindelöf theorems in [32].

In [33], the author presented a new type of fractional operator as a generalization of the Caputo and Caputo–Hadamard fractional derivative operators. Also, he applied the Gronwall inequality type to obtain the uniqueness theorem of the problem (1.1)–(1.2).

In [34], the authors established the existence, uniqueness, and Ulam-Hyers stability results of boundary value problems (BVP) for an implicit FDEs with anti-periodic condition involving Caputo-Katugampola type

\[ CKD_{a}^{\sigma, \rho} \omega(\vartheta) = g(\vartheta, \omega(\vartheta), CKD_{a}^{\sigma, \rho} \omega(\vartheta)), \quad \vartheta \in \mathcal{J} = [a, T], \]

\[ \omega(a) + \omega(T) = 0, \]

by applying some fixed point theorems and generalized Gronwall inequality.

Recently, there are some papers dealing with the qualitative properties of solutions of nonlinear FDEs by using techniques of nonlinear functional analysis see for e.g. [35, 36, 37, 38, 39, 40, 41].

Motivated by the previous results, we study in this paper a new type of BVP for implicit FDE that is

\[ CKD_{a}^{\sigma, \rho} \omega(\vartheta) = g(\vartheta, \omega(\vartheta), CKD_{a}^{\sigma, \rho} \omega(\vartheta)), \quad \vartheta \in \mathcal{J} = [a, T], \tag{1.3} \]

\[ \omega(a) = 0, \quad \omega(T) = \int_{a}^{T} h(\tau, \omega(\tau)) d\tau, \tag{1.4} \]

where \( 1 < \sigma \leq 2, \) \( CKD_{a}^{\sigma, \rho} \) is the Caputo-Katugampola fractional derivatives of order \( \sigma, \)

\[ h : \mathcal{J} \times \mathbb{R} \rightarrow \mathbb{R} \] and \( g : \mathcal{J} \times \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R} \) are continuous functions.

The aim of this study is to extend and generalize some reported results in the literature through investigation in the existence and uniqueness of solutions for the given problem (1.3)–(1.4), in which the studied problem with nonlinear integral boundary condition is more general. Our analysis is depends on Banach’s and Krasnoselskii’s fixed point theorems [42].

The remainder of the paper is displayed as follows: In Section 2, we recall some essential definitions and properties which will be useful throughout this article and we proving some axiom lemmas which play a key role in the sequel. Section 3 contains certain sufficient conditions to corroborate the existence and uniqueness results of the
problem (1.3)–(1.4) via fixed point techniques of Banach and Krasnoselskii. At the end, some examples are involved to illustrate the applicability of the obtained results in Section 4.

2. Preliminaries

For the sake of convenience of the readers, we present some background materials from fractional calculus theory and nonlinear analysis [27, 30, 33, 34, 42, 43] to facilitate the analysis of our problem (1.3)–(1.4).

**Definition 2.1.** [27] The Katugampola fractional integral of order $\sigma > 0$ with $\rho > 0$ is defined by

$$I_{a^+}^{\sigma;\rho}z(\theta) = \frac{\rho^{1-\sigma}}{\Gamma(\sigma)} \int_{a}^{\theta} \tau^{\rho-1} (\theta^\rho - \tau^\rho)^{\sigma-1} z(\tau) d\tau, \quad \theta > a,$$

(2.1)

if the integral exists, where, $\Gamma(\cdot)$ is a gamma function.

**Definition 2.2.** [30] The Katugampola fractional derivative of order $\sigma (n-1 < \sigma < n)$ with $\rho > 0$ is defined as

$$D_{a^+}^{\sigma;\rho} z(\theta) = \left( \theta^{1-\rho} \frac{d}{d\theta} \right) \left[ I_{a^+}^{\sigma;\rho} z(\theta) \right] = \gamma n \rho^{\sigma-n+1} \int_{a}^{\theta} \tau^{\rho-1} (\theta^\rho - \tau^\rho)^{n-\sigma-1} z(\tau) d\tau, \quad \theta > a,$$

(2.2)

where $\gamma = (\theta^{1-\rho} \frac{d}{d\theta})$ and $n = [\sigma] + 1.$

**Definition 2.3.** [30] The Caputo-Katugampola fractional derivative of order $\sigma > 0$ with $\rho > 0$ is defined by

$$\mathcal{D}_{a^+}^{\sigma;\rho} z(\theta) = I_{a^+}^{n-\sigma;\rho} \left[ z(\theta) - \sum_{k=0}^{n-1} \frac{z^{(k)}(a)}{k!} (\theta - a)^k \right],$$

(2.3)

where $z^{(k)}(\theta) = (\theta^{1-\rho} \frac{d}{d\theta})^k z(\theta).$ In case $1 < \sigma \leq 2,$ and $z \in C^2(\Theta, \mathbb{R}),$ we have

$$\mathcal{D}_{a^+}^{\sigma;\rho} z(\theta) = I_{a^+}^{n-\sigma;\rho} \left[ z(\theta) - z(a) - z'(a) (\theta - a) \right].$$

(2.4)

One has

$$\mathcal{D}_{a^+}^{\sigma;\rho} z(\theta) = I_{a^+}^{n-\sigma;\rho} \left( \theta^{1-\rho} \frac{d}{d\theta} \right)^n z(\theta).$$

**Lemma 2.4.** [27, 33] $I_{a^+}^{\sigma;\rho}, \mathcal{D}_{a^+}^{\sigma;\rho}$ are bounded operators from $C[a, T]$ into $C[a, T].$

**Lemma 2.5.** [33] Let $\sigma > 0, \beta > 0, z \in C^1[a, T].$ Then we have

$$I_{a^+}^{\sigma;\rho} J_{a^+}^{\beta;\rho} z(\theta) = J_{a^+}^{\sigma+\beta;\rho} z(\theta), \quad \mathcal{D}_{a^+}^{\sigma;\rho} J_{a^+}^{\beta;\rho} z(\theta) = \mathcal{D}_{a^+}^{\sigma+\beta;\rho} z(\theta).$$
Lemma 2.6. [27, 33] Let $\sigma > 0$ and $\delta > n - 1$. Then we have
\[
\mathcal{D}^{\sigma;\rho}_{a^+}(\vartheta) = \frac{\rho^{\sigma - \delta} \Gamma(\delta + 1)}{\Gamma(\delta - \sigma + 1)} \left( \varphi - a^\rho \right)^{\sigma - \delta},
\]
and
\[
\mathcal{D}^{\sigma;\rho}_{a^+}(\vartheta)^k = 0, \quad \sigma > 0, \quad k = 0, 1, \ldots, n - 1.
\]

Lemma 2.7. [32, 34] Let $\sigma, \rho > 0$ and $z \in C(\mathbb{J}, \mathbb{R}) \cap C^1(\mathbb{J}, \mathbb{R})$. Then the Caputo-Katugampola type FDE
\[
\mathcal{D}^{\sigma;\rho}_{a^+} z(\vartheta) = 0
\]
has a solution
\[
z(\vartheta) = c_0 + c_1 \left( \frac{\varphi - a^\rho}{\rho} \right) + c_2 \left( \frac{\varphi - a^\rho}{\rho} \right)^2 + \ldots + c_{n-1} \left( \frac{\varphi - a^\rho}{\rho} \right)^{n-1},
\]
where $c_i \in \mathbb{R}$, $i = 0, 1, 2, \ldots, n - 1$ and $n = [\sigma] + 1$.

Theorem 2.8. [42] (Banach fixed point theorem) Let $(X, \rho)$ be a nonempty complete metric space with $F : X \to X$ is a contraction mapping. Then map $F$ has a fixed point.

Theorem 2.9. [42] (Krasnoselskii’s fixed point theorem) Let $X$ be a Banach space, let $\Omega$ be a bounded closed convex subset of $X$ and let $F_1, F_2 : \Omega \to \Omega$ be mapping such that $F_1x + F_2y \in \Omega$ for every pair $x, y \in \Omega$. If $F_1$ is contraction and $F_2$ is completely continuous, then there exists $z \in \Omega$ such that $F_1z + F_2z = z$.

3. Existence and uniqueness theorems for (1.3)–(1.4)

In this section, we give the results on the existence, the uniqueness of solution for problem (1.3)–(1.4) depending on Theorems 2.8, 2.9. The next lemma plays a necessary role in analysis our results.

Lemma 3.1. Let $1 < \sigma \leq 2$, $\rho > 0$ and $\varphi, \varrho \in C(\mathbb{J}, \mathbb{R})$. Then a function $\varphi$ is a solution of the Caputo-Katugampola type FDE
\[
\mathcal{D}^{\sigma;\rho}_{a^+} \varphi(\vartheta) = \varphi(\vartheta), \quad \vartheta \in \mathbb{J},
\]
Clearly, \( G \) and \( F \) are continuous and \( \omega \) be a function.

Substitute (3.5) and (3.6) into (3.4), we obtain

\[
\omega(\sigma) = c_0 + c_1 \left( \frac{\sigma^a - \sigma^a}{\rho} \right) \left[ \int_a^\tau h(\tau) d\tau - \frac{\sigma^1 - \sigma}{\Gamma(\sigma)} \int_a^\tau \tau^\sigma (\tau^\rho - \tau^\rho)^\sigma - 1 \omega(\tau) d\tau \right]
\]

\[
+ \frac{\sigma^1 - \sigma}{\Gamma(\sigma)} \int_a^\tau \tau^\sigma (\tau^\rho - \tau^\rho)^\sigma - 1 \omega(\tau) d\tau.
\]

The converse follows by Lemmas 2.5 and 2.6. The proof is completed. \( \square \)

As result of Lemma 3.1, we have the following Lemma:

**Lemma 3.2.** Assume that \( g : \mathbb{J} \times \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R} \) and \( h : \mathbb{J} \times \mathbb{R} \rightarrow \mathbb{R} \) be a function. The problem (1.3)–(1.4) has a solution \( \omega(\sigma) \) if and only if \( \omega(\sigma) \) is a fixed-point of the operator \( F : C(\mathbb{J}, \mathbb{R}) \rightarrow C(\mathbb{J}, \mathbb{R}) \) defined by

\[
F\omega(\sigma) = \left( \frac{\sigma^a - \sigma^a}{\rho} \right) \left[ \int_a^\tau h(\tau, \omega(\tau)) d\tau - \frac{\sigma^1 - \sigma}{\Gamma(\sigma)} \int_a^\tau \tau^\sigma (\tau^\rho - \tau^\rho)^\sigma - 1 G_\omega(\tau) d\tau \right]
\]

\[
+ \frac{\sigma^1 - \sigma}{\Gamma(\sigma)} \int_a^\tau \tau^\sigma (\tau^\rho - \tau^\rho)^\sigma - 1 G_\omega(\tau) d\tau.
\]

and \( G_\omega(\sigma) : [a, T] \rightarrow \mathbb{R} \) be a function satisfying the functional equation

\[
G_\omega(\sigma) := g(\sigma, \omega(\sigma)), C^K \mathbb{D}_{t_a}^{\sigma_\rho} \omega(\sigma)
\]

Clearly, \( G_\omega \in C(\mathbb{J}, \mathbb{R}) \). In addition, by Lemma 2.4, \( F \omega \in C(\mathbb{J}, \mathbb{R}) \).
Now, we present results on the existence and uniqueness of solution for the problem (1.3)–(1.4) depending on Theorems 2.8, 2.9. Assume that the functions \( g : J \times \mathbb{R} \to \mathbb{R} \) and \( h : J \times \mathbb{R} \to \mathbb{R} \) are continuous and satisfy the following conditions:

**H**\(_1\) There exists a constant \( 0 < L_g < 1 \) such that:

\[
|g(\theta, x_1, x_2) - g(\theta, y_1, y_2)| \leq L_g \|x_1 - y_1\| + \|x_2 - y_2\|, \quad \forall \theta \in J, \; x_i, y_i \in \mathbb{R}, (i = 1, 2).
\]

**H**\(_2\) There exists a constant \( 0 < L_h < 1 \) such that:

\[
|h(\theta, x) - h(\theta, y)| \leq L_h |x - y|, \quad \forall \theta \in J, \; x, y \in \mathbb{R}.
\]

**H**\(_3\) The following inequality holds

\[
\gamma := L_h (T - a) + \frac{2L_g \rho^{-\sigma} (T^\rho - a^\rho)^\sigma}{1 - L_g} < 1.
\] (3.8)

**Theorem 3.3.** Suppose that \( (H_1), (H_2) \) and \( (H_3) \) hold. Then the problem (1.3)–(1.4) has a unique solution on \( J \).

**Proof.** First, we show that \( \mathcal{B}_r \subseteq \mathcal{B}_r \), such that be \( F : C(J, \mathbb{R}) \to C(J, \mathbb{R}) \) defined by (3.7) and

\[
\mathcal{B}_r = \{ \omega \in C(J, \mathbb{R}), \| \omega \| \leq r \},
\] (3.9)

with select \( r \geq \frac{\Theta}{1 - \gamma} \), where \( \gamma < 1 \) and

\[
\Theta := \left( \mu_g (T - a) + \frac{2 \mu_g \rho^{-\sigma} (T^\rho - a^\rho)^\sigma}{1 - L_g} \right).
\]

Set \( \sup_{\theta \in J} |g(\theta, 0, 0)| := \mu_g < \infty \), and \( \sup_{\theta \in J} |h(\theta, 0)| := \mu_h \). For \( \theta \in J \), with our hypotheses we have

\[
|F \omega(\theta)| \leq \left\{ \begin{array}{lcl}
\left( \frac{\rho}{T^\rho} - a^\rho \right) \left[ \int_a^T |h(\tau, \omega(\tau))| d\tau + \frac{\rho^{-\sigma}}{\Gamma(\sigma)} \int_a^T \tau^{\rho-1}(T^\rho - \tau^\rho)^{\sigma-1} |G_{\omega}(\tau)| d\tau \right] \\
+ \frac{\rho^{-\sigma}}{\Gamma(\sigma)} \int_a^\theta \tau^{\rho-1}(\rho^\rho - \tau^\rho)^{\sigma-1} |G_{\omega}(\tau)| d\tau \end{array} \right\}.
\]

From \( (H_1) \), we have

\[
|G_{\omega}(\tau)| = |g(\tau, \omega(\tau), \mathcal{D}_{a^+}^{\sigma, \rho} \omega(\tau))| \\
\leq |g(\tau, \omega(\tau), \mathcal{D}_{a^+}^{\sigma, \rho} \omega(\tau)) - g(\tau, 0, 0)| + |g(\tau, 0, 0)| \\
\leq L_g |\omega(\tau)| + L_g |\mathcal{D}_{a^+}^{\sigma, \rho} \omega(\tau)| + \mu_g \\
= L_g |\omega(\tau)| + L_g |G_{\omega}(\tau)| + \mu_g.
\]

Since \( L_g < 1 \) and for any \( \omega \in \mathcal{B}_r \), we get

\[
|G_{\omega}(\tau)| \leq \frac{(L_g r + \mu_g)}{1 - L_g}.
\] (3.10)
From (H₂), we obtain
\[ |h(\tau, \omega(\tau))| \leq |h(\tau, \omega(\tau)) - h(\tau, 0)| + |h(\tau, 0)| \leq L_h |\omega(\tau)| + \mu_h. \]

For \( \omega \in \mathcal{B}_r \),
\[ |h(\tau, \omega(\tau))| \leq L_h \tau + \mu_h. \quad (3.11) \]

Consequently,
\[
|F\omega(\vartheta)| \leq \left\{ \frac{\theta^\rho - a^\rho}{T^\rho - a^\rho} \left[ (L_h \tau + \mu_h) \int_a^T \frac{(L_g \tau + \mu_g) \rho^{1-\sigma} \tau^{\rho-1}}{1-L_g} \Gamma(\sigma) \right] \frac{T}{T^\rho - a^\rho} \tau^{\rho-1} |(T^\rho - \tau^\rho)^{\sigma-1}| d\tau \right\}
\[ \leq \left[ (L_h \tau + \mu_h)(T - \alpha) + \frac{(L_g \tau + \mu_g) \rho^{-\sigma} (T^\rho - a^\rho)^\sigma}{1-L_g} \frac{T}{T^\rho - a^\rho} \Gamma(\sigma + 1) \right] \left[ (L_h \tau + \mu_h)(T - \alpha) + \frac{2\mu_g \rho^{-\sigma} (T^\rho - a^\rho)^\sigma}{1-L_g} \frac{T}{T^\rho - a^\rho} \Gamma(\sigma + 1) \right]
\[ \leq \gamma \tau + \Theta < \tau, \]
which gives \( |F\omega| < \tau \), i.e., \( F\omega \in \mathcal{B}_r \). Moreover, by (3.7), and lemmas 2.5, 2.6, we deduce
\[ C^k\mathcal{D}_{\alpha^+}^{\sigma, \rho} F\omega(\vartheta) = C^k\mathcal{D}_{\alpha^+}^{\sigma, \rho} \gamma \omega(\vartheta) = \gamma \omega(\vartheta). \]

Since \( G_\omega(\cdot) \) is continuous on \( \mathcal{J} \), the operator \( C^k\mathcal{D}_{\alpha^+}^{\sigma, \rho} F\omega(\vartheta) \) is continuous on \( \mathcal{J} \), that is \( F \mathcal{B}_r \subseteq \mathcal{B}_r \).

Second, we apply the Theorem 2.8 to show that \( F \) has a fixed point. In fact, it sufficient to prove that \( F \) is contraction. Let \( \omega_1, \omega_2 \in C(\mathcal{J}, \mathbb{R}) \) and \( \vartheta \in \mathcal{J} \). Then
\[
|F\omega_1(\vartheta) - F\omega_2(\vartheta)| \leq \left\{ \frac{\theta^\rho - a^\rho}{T^\rho - a^\rho} \left[ \int_a^T |h(\tau, \omega_1(\tau)) - h(\tau, \omega_2(\tau))| d\tau \right] \right\}
\[ + \frac{\rho^{1-\sigma}}{\Gamma(\sigma + 1)} \int_a^T \tau^{\rho-1} (T^\rho - \tau^\rho)^{\sigma-1} |G_{\omega_1}(\tau) - G_{\omega_2}(\tau)| d\tau \right\}
\[ + \frac{\rho^{1-\sigma}}{\Gamma(\sigma + 1)} \int_a^T \tau^{\rho-1} (T^\rho - \tau^\rho)^{\sigma-1} |G_{\omega_1}(\tau) - G_{\omega_2}(\tau)| d\tau. \quad (3.12) \]
By (H1), we get
\[ |G_{\omega_1}(\tau) - G_{\omega_2}(\tau)| = |g(\tau, \omega_1(\tau), C_K D_\alpha^{\sigma, \rho} \omega_1(\tau)) - g(\tau, \omega_2(\tau), C_K D_\alpha^{\sigma, \rho} \omega_2(\tau))| \leq L_0 |\omega_1 - \omega_2| + L_0 \left| C_K D_\alpha^{\sigma, \rho} \omega_1(\tau) - C_K D_\alpha^{\sigma, \rho} \omega_2(\tau) \right|, \]
which yields
\[ |G_{\omega_1}(\tau) - G_{\omega_2}(\tau)| \leq \frac{L_0}{1-L_0} |\omega_1 - \omega_2|, \tag{3.13} \]
and using (H2), we obtain
\[ |h(\tau, \omega_1(\tau)) - h(\tau, \omega_2(\tau))| \leq L_0 |\omega_1 - \omega_2|. \tag{3.14} \]

The relations (3.13), (3.14) and (3.12) give
\[
\|F \omega_1 - F \omega_2\| \\
\leq \left( \frac{\partial^\rho - a^\rho}{T^\rho + a^\rho} \right) \left\{ L_0 \int_a^T d\tau \\
+ \frac{L_0}{1-L_0} \frac{\rho^{1-\sigma}}{\Gamma(\sigma)} \int_a^T \tau^{\rho-1}(T^\rho - \tau^\rho)^{\sigma-1} d\tau \right\} \|\omega_1 - \omega_2\| \\
+ \frac{L_0}{1-L_0} \frac{\rho^{1-\sigma}}{\Gamma(\sigma)} \int_a^0 \tau^{\rho-1}(\rho^\rho - \tau^\rho)^{\sigma-1} d\tau \|\omega_1 - \omega_2\| \\
\leq \left[ L_0 (T-a) + \frac{2L_0 \rho^{-\sigma} (T^\rho - a^\rho)^\sigma}{1-L_0} \frac{\Gamma(\sigma+1)}{\Gamma(\sigma)} \right] \|\omega_1 - \omega_2\| \\
= \Upsilon \|\omega_1 - \omega_2\|. 
\]

Since \( \Upsilon < 1 \), the operator \( F \) is contraction. Consequently, Theorem 2.8 shows that the problem (1.3)–(1.4) has a unique solution. \( \square \)

Our second existence result for the problem (1.3)–(1.4) is based on the Theorem 2.9.

**Theorem 3.4.** Suppose that (H1), (H2) and (H3) hold. Then there exist at least one solution of the problem (1.3)–(1.4) on \( J \).

**Proof.** Consider the operator \( F \) defined by (3.7). Set the ball \( B_{r_0} := \{ \omega \in C(J, \mathbb{R}) : \|\omega\| \leq r_0 \} \), with \( r_0 \geq \frac{\Theta}{1-\Upsilon} \), where \( \Theta \) and \( \Upsilon \) is defined as in Theorem 3.3. Moreover, we define the operators \( F_1 \) and \( F_2 \) on \( B_{r_0} \) by
\[
F_1 \omega(\delta) = \left( \frac{\partial^\rho - a^\rho}{T^\rho + a^\rho} \right) \left[ \int_a^T h(\tau, \omega(\tau)) d\tau - \frac{\rho^{1-\sigma}}{\Gamma(\sigma)} \int_a^T \tau^{\rho-1}(T^\rho - \tau^\rho)^{\sigma-1} G_\omega(\tau) d\tau \right] \\
and
F_2 \omega(\delta) = \frac{\rho^{1-\sigma}}{\Gamma(\sigma)} \int_a^0 \tau^{\rho-1}(\delta^\rho - \tau^\rho)^{\sigma-1} G_\omega(\tau) d\tau. 
\]
The proof will be divided into several stages as follows:

**Stage 1:** \( F_1 \omega_1 + F_2 \omega_2 \in \mathcal{B}_{r_0} \) for every \( \omega_1, \omega_2 \in \mathcal{B}_{r_0} \).

Applying the same arguments in (3.10) and (3.11), we obtain

\[
|G_{\omega_1}(\tau)| \leq \frac{L_\rho r_0 + \mu_\rho}{1 - L_\rho}, \quad \text{and} \quad |G_{\omega_2}(\tau)| \leq \frac{L_\rho r_0 + \mu_\rho}{1 - L_\rho},
\]

\[
|h(\tau, \omega_1(\tau))| \leq \mu_\rho r_0 + \mu_\rho, \quad \text{and} \quad |h(\tau, \omega_2(\tau))| \leq \mu_\rho r_0 + \mu_\rho.
\]

For each \( \omega_1, \omega_2 \in \mathcal{B}_{r_0} \) and \( \theta \in \mathcal{J} \), we have

\[
|F_1 \omega_1(\theta) + F_2 \omega_2(\theta)| \\
\leq |F_1 \omega_1(\theta)| + |F_2 \omega_2(\theta)| \\
\leq \left( \frac{\theta - a}{T - a} \right) \left[ \int_a^T |h(\tau, \omega_1(\tau))| \, d\tau + \frac{\rho^{1-\sigma}}{1-\rho} \int_a^T \rho^{\sigma-1}(T^\rho - \tau^\rho)^{\sigma-1}|G_{\omega_1}(\tau)| \, d\tau \right] \\
+ \frac{\rho^{1-\sigma}}{1-\rho} \int_a^\theta \rho^{\sigma-1}(\theta^\rho - \tau^\rho)^{\sigma-1}|G_{\omega_2}(\tau)| \, d\tau \\
\leq \left[ \left( \frac{L_\rho (T - a)}{1 - L_\rho} + \frac{L_\rho \rho^{-\sigma} (T^\rho - a^\rho)^{\sigma}}{1 - L_\rho \Gamma(\sigma + 1)} \right) + \frac{L_\rho \rho^{-\sigma} (T^\rho - a^\rho)^{\sigma}}{1 - L_\rho \Gamma(\sigma + 1)} \right] r_0 \\
+ \left[ \left( \frac{\mu_\rho (T - a)}{1 - L_\rho} + \frac{\mu_\rho \rho^{-\sigma} (T^\rho - a^\rho)^{\sigma}}{1 - L_\rho \Gamma(\sigma + 1)} \right) + \frac{\mu_\rho \rho^{-\sigma} (T^\rho - a^\rho)^{\sigma}}{1 - L_\rho \Gamma(\sigma + 1)} \right] r_0 \\
= \left( \frac{L_\rho (T - a)}{1 - L_\rho} + \frac{2L_\rho \rho^{-\sigma} (T^\rho - a^\rho)^{\sigma}}{1 - L_\rho \Gamma(\sigma + 1)} \right) r_0 \\
+ \left( \frac{\mu_\rho (T - a)}{1 - L_\rho} + \frac{2\mu_\rho \rho^{-\sigma} (T^\rho - a^\rho)^{\sigma}}{1 - L_\rho \Gamma(\sigma + 1)} \right) r_0 \\
= G_\rho r_0 + \Theta < r_0,
\]

which implies

\[
|F_1 \omega_1 + F_2 \omega_2| \leq r_0.
\]  

(3.15)

This proves that \( F_1 \omega_1 + F_2 \omega_2 \in \mathcal{B}_{r_0} \) for every \( \omega_1, \omega_2 \in \mathcal{B}_{r_0} \).

**Stage 2** \( F_1 \) is a contraction mapping on \( \mathcal{B}_{r_0} \).

Since \( F \) is contraction mapping as in Theorem 3.3, then \( F_1 \) is a contraction map too.

**Stage 3.** Here, we shall prove that operator \( F_2 \) is completely continuous on \( \mathcal{B}_{r_0} \).

Obviously, \( F_2 \) is continuous due to the continuity of \( G_{\omega} \).

Next, it is not difficult to conclude that

\[
|F_2 \omega| \leq \frac{L_\rho r_0 + \mu_\rho \rho^{-\sigma}}{1 - L_\rho \Gamma(\sigma + 1)} (T^\rho - a^\rho)^{\sigma} < r_0,
\]

due to definitions of \( \gamma \) and \( r_0 \). This verifies that \( F_2 \) is uniformly bounded on \( \mathcal{B}_{r_0} \).

Finally, we show that \( F_2 \) maps bounded sets into equicontinuous sets of \( C(\mathcal{J}, \mathbb{R}) \).
Let $\vartheta_1, \vartheta_2 \in \mathbb{J}$, with $\vartheta_1 < \vartheta_2$ and for any $\omega \in \mathcal{B}_{r_0}$. Then we have
\[
|F_2 \omega(\vartheta_2) - F_2 \omega(\vartheta_1)| = \left| \frac{\rho^{1-\sigma}}{\Gamma(\sigma)} \int_{a}^{\vartheta_2} \tau^{\rho-1} (\vartheta_2^{\rho} - \tau^{\rho}) \sigma^{-1} G_\omega(\tau) \, d\tau - \frac{\rho^{1-\sigma}}{\Gamma(\sigma)} \int_{a}^{\vartheta_1} \tau^{\rho-1} (\vartheta_1^{\rho} - \tau^{\rho}) \sigma^{-1} G_\omega(\tau) \, d\tau \right|
\leq \frac{\rho^{1-\sigma}}{\Gamma(\sigma)} \int_{a}^{\vartheta_2} \tau^{\rho-1} |(\vartheta_2^{\rho} - \tau^{\rho}) \sigma^{-1} - (\vartheta_1^{\rho} - \tau^{\rho}) \sigma^{-1}| |G_\omega(\tau)| \, d\tau
+ \frac{\rho^{1-\sigma}}{\Gamma(\sigma)} \int_{\vartheta_1}^{\vartheta_2} \tau^{\rho-1} |(\vartheta_2^{\rho} - \tau^{\rho}) \sigma^{-1}| |G_\omega(\tau)| \, d\tau
\leq \frac{L_{\rho} r_0 + \mu_g}{1 - L_{\rho}} \frac{\rho^{-\sigma}}{\Gamma(\sigma+1)} (\vartheta_2 - \vartheta_1)^{\sigma}.
\]
As $\vartheta_1 \rightarrow \vartheta_2$ the right-hand side of the above inequality is not dependent on $\omega$ and tends to zero. Therefore,
\[
|F_2 \omega(\vartheta_1) - F_2 \omega(\vartheta_2)| \rightarrow 0, \quad \forall \ |\vartheta_2 - \vartheta_1| \rightarrow 0, \quad \omega \in \mathcal{B}_{r_0}.
\]
This proves that $F_2$ is equicontinuous on $\mathcal{B}_{r_0}$. An application of Arzela-Ascoli Theorem shows that $F_2$ is relatively compact on $\mathcal{B}_{r_0}$. Hence all the assumptions of the Theorem 2.9 are satisfied. Thus, we deduce that the problem (1.3)–(1.4) has at least one solution on $\mathbb{J}$. 

4. An example

Here, we stipulate an interpretative example to support the obtained results.

Example 4.1. Consider the following implicit FDE
\[
CK_{0+}^{\frac{3}{2}, \frac{1}{2}} \omega(\vartheta) = \left\{ \begin{array}{l}
\frac{1}{\vartheta} e^{\sqrt{\vartheta} + 1} + \frac{5 + |\omega(\vartheta)| + \int_{0}^{\vartheta} \omega(\vartheta)}{12e^{2\vartheta} (1 + |\omega(\vartheta)| + \int_{0}^{\vartheta} \omega(\vartheta))} \\
\omega(0) = 0, \quad \omega(1) = \int_{0}^{1} \frac{\cos \omega(\tau)}{20(\vartheta + 2)(1 + \vartheta)} \, d\tau.
\end{array} \right.
\] (4.1)

where $\sigma = \frac{3}{2}$ and $\rho = \frac{1}{2}$. Take
\[
g(\vartheta, u, v) = \frac{1}{\vartheta} e^{\sqrt{\vartheta} + 1} + \frac{5 + u + v}{12e^{2\vartheta} (1 + u + v)}, \quad \vartheta \in [0, 1], u, v \in \mathbb{R}^+,
\]
\[
h(\vartheta, u) = \frac{\cos u}{20(\vartheta + 2)(1 + u)}, \quad \vartheta \in [0, 1], u \in \mathbb{R}^+
\]

Obviously, the functions $g, h \in C([0, 1], \mathbb{R})$. Moreover, $\sup_{\vartheta \in \mathbb{J}} |g(\vartheta, 0, 0)| = \frac{1}{12} e^2 + \frac{5}{12e} = \mu_g < \infty$, and $\sup_{\vartheta \in \mathbb{J}} |h(\vartheta, 0)| = \frac{1}{40} = \mu_h < \infty$. For each $u, v, u^*, v^* \in \mathbb{R}^+$ and $\vartheta \in [0, 1]$, we have
\[
|g(\vartheta, u, v) - g(\vartheta, u^*, v^*)| = \left| \frac{5 + u + v}{12e^{2\vartheta} (1 + u + v)} - \frac{5 + u^* + v^*}{12e^{2\vartheta} (1 + u^* + v^*)} \right|
\leq \frac{1}{12e^{2\vartheta} (|u - u^*| + |v - v^*|)}
\leq \frac{1}{12e (|u - u^*| + |v - v^*|)}.
\]
and

\[
|h(\vartheta, u) - h(\vartheta, u^*)| = \left| \frac{\cos u}{20(\vartheta + 2)(1 + u)} - \frac{\cos u^*}{20(\vartheta + 2)(1 + u^*)} \right| \leq \frac{1}{20} |u - u^*|
\]

Hence, the assumption \((H_1)\) and \((H_2)\) is satisfied with \(L = \frac{1}{120}, L_h = \frac{1}{20}\) respectively. We can easily check that \((H_3)\). It can be seen by direct calculations that \(Y = 0.18458 < 1\). Since all the assumptions of Theorem \((3.3)\) are obtained, therefore problem \((4.1)\) has a unique solution.

5. Conclusions

In this article, we have studied a type of a nonlinear IFDE with the nonlinear integral boundary condition involving a Caputo-Katugampola fractional derivative. We have also established sufficient conditions ensuring existence, and uniqueness of solutions for a proposed problem by applying some fixed point theorems. We confident the obtained results here will have a favorable impact on the evolution of more applications in applied sciences and engineering.

Acknowledgment

We thank the reviewers for their constructive remarks on our manuscript.

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