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Detection of Frozen Soil Using Sentinel-1 SAR Data

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Abstract: The objective of this paper is to evaluate the potential of Sentinel-1 Synthetic Aperture Radar “SAR” data (C-band) for monitoring agricultural frozen soils. First, investigations were conducted from simulated radar signal data using a SAR backscattering model combined with a dielectric mixing model. Then, Sentinel-1 images acquired at a study site near Paris, France were analyzed using temperature data to investigate the potential of the new Sentinel-1 SAR sensor for frozen soil mapping. The results show that the SAR backscattering coefficient decreases when the soil temperature drops below 0 °C. This decrease in signal is the most important for temperatures that ranges between 0 and −5 °C. A difference of at least 2 dB is observed between unfrozen soils and frozen soils. This difference increases under freezing condition when the temperature at the image acquisition date decreases. In addition, results show that the potential of the C-band radar signal for the discrimination of frozen soils slightly decreases when the soil moisture decreases (simulated data were used with soil moisture contents of 20 and 30 vol%). The difference between the backscattering coefficient of unfrozen soil and the backscattering coefficient of frozen soil decreases by approximately 1 dB when the soil moisture decreases from 30 to 20 vol%). Finally, the results show that both VV and VH allow a good detection of frozen soils but the sensitivity of VH is higher by approximately 1.5 dB. In conclusion, this study shows that the difference between a reference image acquired without freezing and an image acquired under freezing conditions is a good tool for detecting frozen soils.

Keywords: frozen soils; dielectric constant; IEM; SAR; C-band; Sentinel-1

1. Introduction

Frost frequently causes serious crop damages and consequently loss of yield. A frozen soil map is a key tool to assess the extent of loss of yield in agricultural areas. This map requires a monitoring system that can map the frozen zones with fine spatial and temporal resolutions. The arrival of Sentinel-1 (S1) satellites encourages the analysis of Synthetic Aperture Radar (SAR) data for mapping agricultural frozen soils with a high revisit time and high spatial resolution (up to plot scale). Some studies have shown from SAR and radiometer-scatterometer data (e.g., ERS, ENVISAT/ASAR and RADARSAT) that the SAR backscattering coefficient decreases when soil freezes [1–5]. A decrease in the radar signal of approximately 3 dB was observed when the soil was frozen [2,3]. Wegmüller [1] studied the effect of freezing and thawing on the microwave signatures of bare soil using radiometer-scatterometer system at frequencies between 3 and 11 GHz. His results showed that freezing increases the emissivity and decreases the backscattering coefficient. Rignot et al. [2] observed from temporal ERS-1 SAR images (C-band) pronounced temporal variations in radar backscattering coefficient in Taiga forests due to freezing events. They detected a 3 dB decrease when the soil and vegetation freeze. Khaldoune et al. [3] mapped agricultural frozen soils under snow cover using RADARSAT-1 images (C-band). They developed classification algorithm based on
soil-freezing threshold from the backscattering coefficient in HH polarization. Park et al. [4] used ENVISAT/ASAR images (C-band) to monitor freeze/thaw cycles of permafrost areas. A difference of 3–4 dB was observed between ASCAT signal in freezing condition and ASCAT signal in thawing condition. Jagdhuber et al. [5] showed over a study site in Finland the high sensitivity of RADARSAT-2 signal (C-band) to soil freezing and thawing states even under dry snow cover.

Under cold winter conditions, much of soil water freezes, which leads to a significant decrease of the soil dielectric constant. The decrease in the dielectric constant due to a decrease of the volumetric moisture content causes a decrease of the radar signal [6]. This variation in the radar signal due to the variation in the soil dielectric constant can be estimated using SAR images [1–5]. Currently, several high-resolution SAR images can be acquired at a given study site due to the availability of SAR data in the C-band (e.g., Radarsat-2 and Sentinel-1) and X-band (e.g., TerraSAR-X and COSMO-SkyMed). However, only Sentinel-1 satellites provide users with free and open access SAR data at high spatial and temporal resolutions (revisit time of six days over Europe and spatial resolution of 10 m). This high spatial resolution of SAR sensors will make it possible to follow the soil freezing at very fine spatial scales in agricultural areas (plot scale or sub-plot scale).

Recently, a freeze/thaw product generated from SMAP data is available at low spatial resolution [7]. The product based on temporal change detection approach assumes that the high variation in the temporal dynamics of the normalized polarization ratio (NPR) of the brightness temperature is related to a large change in dielectric constant (passing from frozen to non-frozen condition, or reciprocally) [7].

The objective of this paper is to study the potential of Sentinel-1 SAR data for monitoring agricultural frozen soils. A SAR backscattering model combined with a dielectric mixing model was used to study the behavior of the SAR signal after freezing. Assuming that the soil moisture and the surface roughness were unchanged between the date of unfrozen soil condition and the date of frozen soil condition, a time series of Sentinel-1 images acquired on a study site in France was analyzed to identify frozen soils. After a detailed description of the semi-empirical frozen soil–water dielectric mixing model is presented in Section 2, Section 3 describes the data used (modeling settings, Sentinel-1 images and temperature data). In Section 4, the results are given (dielectric constant behavior, SAR modeling on frozen soils, and interpretation of Sentinel-1 images). A discussion is presented in Section 5. Finally, Section 6 presents the main conclusions.

2. Radar Signal Modeling

To investigate the potential of the new C-band SAR Sentinel-1 sensor for monitoring frozen soils in an agricultural context, the radar backscattering coefficients of frozen soils were simulated using the Integral Equation model [8,9] and a dielectric constant model of frozen soil. In these simulations, only the case of bare soils was considered.

2.1. Semi-Empirical Dielectric Mixing Model for Frozen Soil–Water

Dobson et al. [10] developed a semi-empirical soil–water dielectric mixing model for the 1.4–18 GHz frequency range of the following form:

\[ \varepsilon_m = \varepsilon'_m - j\varepsilon''_m \]  

where \( \varepsilon_m \) is the relative complex dielectric constant of the soil–water mixture, \( \varepsilon'_m \) is the real part and \( \varepsilon''_m \) is the imaginary part. \( \varepsilon'_m \) and \( \varepsilon''_m \) are given by:

\[ \varepsilon'_m = \left[ 1 + \frac{\rho_b}{\rho_s} (\varepsilon^a - 1) + m_v \varepsilon'_w - m_{av} \right]^{1/\alpha} \]  

\[ \varepsilon''_m = \left[ m_v \varepsilon''_w \right]^{1/\alpha} \]
where \( \rho_b \) is the bulk density (g/cm\(^3\)), \( \rho_s \) is the specific density of the solid soil particles (g/cm\(^3\)), \( \varepsilon_s \) is the dielectric constant of soil solid, \( m_w \) is the volumetric moisture content (vol%), \( \varepsilon_{f w} \) is the real part of the dielectric constant of free water, \( \varepsilon_{f w}' \) is the imaginary part of the dielectric constant of free water, \( \alpha \) is an empirically determined constant (=0.65 [10]), and \( \beta' \) and \( \beta'' \) are soil-texture-dependent coefficients.

The dielectric constant of soil solid, \( \varepsilon_s \), given in Equation (2), is expressed by Dobson et al. [10]:

\[
\varepsilon_s = (1.01 + 0.44\rho_b)^2 - 0.062
\]  

(4)

For a given soil with \( \rho_s = 2.66 \text{ g/cm}^3 \), \( \varepsilon_s = 4.7 \).

To calculate \( \beta' \) and \( \beta'' \) of Equations (2) and (3), the following expressions are used [10,11]:

\[
\beta' = (127.48 - 0.519S - 0.152C) / 100
\]  

(5)

\[
\beta'' = (133.797 - 0.603S - 0.166C) / 100
\]  

(6)

where \( S \) and \( C \) are the percentages of sand and clay, respectively.

The quantities \( \varepsilon_{f w}' \) and \( \varepsilon_{f w}'' \) presented in Equations (2) and (3) are defined in Dobson et al. [10] and Peplinski et al. [11] as follows:

\[
\varepsilon_{f w}' = \frac{\varepsilon_{w0} - \varepsilon_{w0}}{1 + (2\pi f \tau_w)}
\]  

(7)

\[
\varepsilon_{f w}'' = \frac{2\pi f \tau_w (\varepsilon_{w0} - \varepsilon_{w0})}{1 + (2\pi f \tau_w)} + \frac{\sigma_{eff} (\rho_s - \rho_b)}{\rho_b \varepsilon_0 f \tau_w}
\]  

(8)

where \( \varepsilon_{w0} = 4.9 \) is the high frequency limit of \( \varepsilon_{f w}' \), \( \varepsilon_{w0} \) is the static dielectric constant of water, \( f \) is the frequency (Hz), \( \tau_w \) is the relaxation time for water, \( \varepsilon_0 = 8.854 \times 10^{-12} \text{ F/m} \) is the permittivity of free space, and \( \sigma_{eff} \) is the effective conductivity.

In Equations (7) and (8), the expressions for the static dielectric constant of water, \( \varepsilon_{w0} \), and the relaxation time for water, \( \tau_w \), are given as a function of the water temperature (\( T_w \) in °C) [12,13]:

\[
\varepsilon_{w0} = 88.045 - 0.4147 T_w + 6.295 \times 10^{-4} T_w^2 + 1.075 \times 10^{-5} T_w^3
\]  

(9)

\[
2\pi \tau_w = (1.1109 \times 10^{-10} - 3.824 \times 10^{-12} T_w + 6.938 \times 10^{-14} T_w^2 - 5.096 \times 10^{-16} T_w^3)
\]  

(10)

For \( T_w = 20 \text{ °C}, \varepsilon_{w0} = 80.1 \) and \( 2\pi \tau_w = 0.58 \times 10^{-10} \text{ s} \).

The effective conductivity, \( \sigma_{eff} \), defined in Equation (8), is given by Peplinski et al. [11]:

\[
\sigma_{eff} = -1.645 + 1.939\rho_b - 0.0225622S + 0.01594C
\]  

(11)

An extension of this semi-empirical dielectric mixing model was proposed by Zhang et al. [14] to include freezing conditions. The dielectric constant of frozen soil–water mixture \( \varepsilon_{mf} \) is given by:

\[
\varepsilon_{mf}' = \left[ 1 + \frac{\rho_b}{\rho_s} (\varepsilon_i^s - 1) + m_{vu}\varepsilon_{f w}' - m_{vi}\varepsilon_i^v \right]^{1/\alpha}
\]  

(12)

\[
\varepsilon_{mf}'' = \left[ m_{vu}\varepsilon_{f w}'' \right]^{1/\alpha}
\]  

(13)

where \( m_{vu} \) is the unfrozen volumetric moisture content (vol%), \( m_{vi} \) is the volumetric ice content (vol%), and \( \varepsilon_i \) is the dielectric constant of ice (=3.15). \( m_{vu} \) and \( m_{vi} \) are given by Zhang et al. [14]:

\[
m_{vu} = A T_s - 273.2 B \left( \frac{\rho_b}{\rho_w} \right)
\]  

(14)
where $T_s$ is the soil temperature steering the amount of liquid to frozen water in the soil (K), $\rho_w$ is the density of water ($=1 \text{ g/cm}^3$), $\rho_i$ is the specific density of ice ($=0.9175 \text{ g/cm}^3$) [5], and A and B are empirical coefficients related to soil texture. In Zhang et al. [14], A and B were calculated for three soil types (Silty-clay, Silt-loam and Sandy-loam, Table 1). For $T_s$ above 273.2 °K, $m_{vi} = 0$ and $m_{vu} = m_v$.

### Table 1. Coefficients A and B derived for three soil types by Zhang et al. [14].

| Soil Type   | Soil Texture (%) | $\rho_b$ | $\rho_s$ | A     | B     |
|-------------|------------------|----------|----------|-------|-------|
| Silty-clay  | Sand             | 6.83     | 45.76    | 47.41 | 1.62  | 2.60  | 11.3301 | 0.6166 |
|             | Silt             | 28.58    | 51.46    | 19.96 | 1.58  | 2.58  | 5.2752  | 0.5675 |
|             | Clay             | 50.73    | 39.61    | 9.66  | 1.59  | 2.63  | 2.6945  | 0.6104 |

### 2.2. Radar Backscattering Model

In this study, the Integral Equation Model modified by Baghdadi (IEM_B) was used to simulate soil surface scattering in a context of bare agricultural fields. In addition to SAR instrumental parameters (radar wavelength, incidence angle and polarization), the radar signal depends on the soil dielectric constant and surface roughness ($H_{rms}$) [15–19]. Only the surface scattering was considered in this study, with one permittivity layer. The IEM_B was used since it provides simulated SAR backscattering coefficients with a good accuracy (RMSE about 2 dB) [20]. In fact, several studies reported important discrepancies between backscattering coefficients simulated by the original IEM developed by Fung et al. [21] and those measured by SAR sensors [22–24]. According to Baghdadi et al. [25], this discrepancy is mainly due to the in situ measured correlation length “$L$” which is difficult to measure in the field with good accuracy. To reduce such discrepancies between simulated and measured backscattering values, Baghdadi et al. [8,9,26–28] proposed a semi-empirical calibration of the original IEM in order to improve the accuracy of the simulated backscattering values. This semi-empirical calibration consists of replacing the in situ measured correlation length by a fitting parameter, called $L_{opt}$. $L_{opt}$ depends on surface roughness conditions and SAR configurations (incidence angle, polarization and radar wavelength). The calibrated IEM_B was carried separately at X-band in [27], C-band in [8,9] and L-band in [26]. The proposed calibration reduces the number of IEM’s input soil parameters from three to two parameters (root mean square surface height “$H_{rms}$” and soil moisture content “$m_v$” only, instead of $H_{rms}$, $L$ and $m_v$).

### 2.3. Modeling Settings

First, the semi-empirical frozen soil–water dielectric mixing model was used to estimate the dielectric constant for the three same soil types defined in Zhang et al. [14] (Silty-clay, Silt-loam and Sandy-loam, Table 1) with a soil temperature $T_s$ between 253 °K and 283 °K. The simulated dielectric constants were then used in the IEM_B to estimate the backscattering coefficients in VV polarization, with a radar frequency of 5.405 GHz, an incidence angle of 40°, soil moisture “$m_v$” of 30 vol%, and soil roughness “$H_{rms}$” of 1 cm.

### 3. Description of Data

#### 3.1. Sentinel-1 Images

A database of Sentinel-1 (S1) images collected over the Orgeval Basin situated near Paris was used (centered on lat.: 48.86°E and long.: 3.17°N, Figure 1). Relatively flat, the Orgeval Basin is mainly composed of cereal fields (wheat, colza, maize, barley, etc.) and forest. The soil texture is relatively
uniform over the whole basin, with clay 20%, silt 70% and sand 10% [29]. Sixty-one S1 images obtained from the Sentinel-1A (S1A) and Sentinel-1B (S1B) satellite constellation operating at the C-band (frequency = 5.406 GHz, wavelength ~6 cm) were collected for the period between 1 November 2016 and 1 March 2017. Over our site, S1A and S1B provide three images every four days, on average. One image is in the Descending mode (acquisition time ~05:58 TU), with an incidence angle of approximately 38°; one is in the Ascending mode (acquisition time ~17:40 TU), with an incidence angle of approximately 42°; and one is in the Ascending mode (acquisition time ~17:31 TU), with an incidence angle of approximately 33°. The 61 S1 images used were acquired in the IW imaging mode with the VV and VH polarizations. In addition, the images were generated from the high-resolution Level-1 Ground Range Detected (GRD) product with a spatial resolution of 10 m × 10 m. These Sentinel-1 images are available via the Copernicus website (https://scihub.copernicus.eu/dhus/#/home). The Sentinel-1 Toolbox (S1TBX), developed by the ESA (European Spatial Agency), was used to calibrate the S1 images. The calibration aims to convert the digital number values of S1 images into backscattering coefficients (σ°) in a linear unit. The radiometric accuracy of Sentinel-1 SAR backscattering coefficient is approximately 0.70 dB (3σ) for the VV polarization and 1.0 dB (3σ) for the VH polarization [30].

A 2017 land cover map based on field trips was used in this study [29]. This map is a thematic vector file with one value per type of land cover. For each vector/segment (one cereal field, one forest stand, etc.), the mean backscattering coefficient was calculated from each calibrated S1 image by averaging the σ° values of all pixels within that vector/segment.

Figure 1. Location of the study site.

3.2. Temperature Data

The meteorological data available for our study site describe the air and soil temperatures. The hourly mean air temperature at 5 cm above ground, soil temperature at 5 cm depth, and 0 cm ground surface temperature were used. The continuous temperature series between 1 November 2016 and 1 March 2017 shows three periods with frozen soil conditions, namely 30 November 2016–9 December 2016, 30 December 2016–9 January 2017, and 16 January 2017–31 January 2017, with temperatures that dropped to −5 °C (Figure 2).
4. Results

4.1. Behavior of the Dielectric Constant with the Temperature

Figure 3 shows the modeling results of the relative dielectric constant of soil (real part $\varepsilon_m'$, and imaginary part $\varepsilon_m''$) at different temperatures for the three typical soils used in this study (Table 1). $\varepsilon_m'$ and $\varepsilon_m''$ increase strongly, especially for temperatures between $-5^\circ$ and $0^\circ$ C. The highest difference of the real part of the dielectric constant before and after freezing is approximately 10 for soil of silty clay, 11 for soil silt loam and 13 for soil sandy loam (for soil moisture content of 30 vol%). The imaginary part of the dielectric constant decreases from 3.2 to 0 for silty clay and silt loam soils and from 3.6 to 0 for sandy loam soil.

4.2. Signal Modeling on Frozen Soils

The dielectric constants calculated in Section 4.1 were used in the IEM_B to calculate the backscattering coefficient of the soil surface. Figure 4 shows the difference $\Delta\sigma^\circ$ between the backscattering coefficient ($\sigma^\circ$) of unfrozen soil that corresponds to a soil temperature higher than $0^\circ$ C (in this study the reference soil temperature of unfrozen soil was considered equal to $0^\circ$ C) and the backscattering coefficient ($\sigma^\circ_{mf}$) of frozen soil with a temperature between $-20$ and $0^\circ$ C. The maximum difference $\Delta\sigma^\circ$ between unfrozen soil and frozen soil is between 4.6 and 5.6 dB depending on the soil...
type (temperature = −20 °C). For soil with the most clay (silty clay soil type), the difference Δσ° is lower than that for soils with less clay (sandy loam followed by silt loam). For temperatures between −5 and −20 °C, the increase of Δσ° is smaller than 1 dB regardless of soil type. This result is consistent with Figure 3 where the dielectric constant of a frozen soil water mixture increases only slightly with the soil temperature Ts for Ts-values between −20 °C and −5 °C. Figure 4 also shows that, even when the temperature drops to −2 °C, Δσ° ranges between 2.6 and 4.7 dB.

This decrease in the radar signal due to freezing (increase in Δσ°) is more important for sandy soils than for clay soils because sandy soils freeze more quickly than clay soils because of their lesser capacity to store water. To understand the behavior of the radar signal (σ°) with the temperature for the three soil types, the unfrozen volumetric moisture content (mvol) and volumetric ice content (mvii) were plotted according to the temperature. Figure 5 shows that when there is more clay, the mvol of frozen soil is higher than those of the other soils, and, therefore, σ° is higher. Therefore, σ° for frozen soil with more clay is higher than σ° for frozen soil with less clay. As for all unfrozen soils (whatever the soil type), with more or less clay, σ° is the same since the total volumetric moisture content is the same (in this paper, mvol = 30 vol%) and Δσ° (σ° of frozen soil − σ° of unfrozen soil) for clay soils is lower than Δσ° for soils that are less clay.

**Figure 4.** Difference Δσ° between the modeled backscattering coefficient of unfrozen soil with reference temperature Ts equal to 0 °C “σ° (Ts = 0°)” and the modeled backscattering coefficient of frozen soil with soil temperature between −20 °C and 0 °C “σ° (Ts)” . For soil temperatures above 0 °C, Δσ° (σ° (Ts = 0) − σ° (Ts > 0°)) is equal to 0 dB. Radar frequency f = 5.405 GHz, mvol = 30 vol%, Hrms = 1 cm, incidence angle θ = 40°, and polarization = VV.

**Figure 5.** Unfrozen volumetric moisture content (mvol) and corresponding volumetric ice content (mvii) of soil during freezing according to the soil temperature for three soil types (Table 1). mvol = 30 vol%, ρw = 1 g/cm³, ρi = 0.9175 g/cm³, A, B and ρb are given in Table 1.
In addition, the effect of the soil moisture value on the potential of the C-band radar signal to discriminate and identify frozen soils was analyzed using a \( m_v \)-value of 20 vol%. In comparison with Figure 4 \((m_v = 30 \text{ vol{%}\)}\), Figure 6 shows that the potential for discriminating frozen soils slightly decreases when the soil moisture decreases. For \( m_v \) of 20 vol% and a soil temperature of \(-20 \, ^\circ\text{C}\), \( \Delta \sigma^\circ \) varies between 3.9 and 5.1 dB. Thus, the \( \Delta \sigma^\circ \) values for \( m_v = 20 \text{ vol{%}\)} decreased of approximately 0.6 dB (0.7 dB for silty clay and 0.5 dB for sandy loam) compared to \( \Delta \sigma^\circ \) calculated for \( m_v = 30 \text{ vol{%}\)}.

At \(-2 \, ^\circ\text{C}\), \( \Delta \sigma^\circ \) varies between 1.5 and 4.1 dB, a decrease of approximately 0.9 dB (1.1 dB for silty clay and 0.6 dB for sandy loam) compared to \( \Delta \sigma^\circ \) calculated with \( m_v = 30 \text{ vol{%}\)}.

The effect of the \( H_{rms} \) was also investigated using simulations with \( H_{rms} = 3 \text{ cm} \) (in addition to \( H_{rms} = 1 \text{ cm} \)). Similar results were obtained concerning the difference \( \Delta \sigma^\circ \) between the modeled backscattering coefficient of unfrozen soil and the modeled backscattering coefficient of frozen soil.

![Figure 6](image)

**Figure 6.** Difference in \( \Delta \sigma^\circ \) between the modeled backscattering coefficient of unfrozen soil with reference temperature \( T_s \) equal to 0 \(^\circ\text{C}\) \("\sigma^\circ \) (\( T_s = 0 \)\)\) and the modeled backscattering coefficient of frozen soil with soil temperature between \(-20 \, ^\circ\text{C}\) and 10 \(^\circ\text{C}\) \("\sigma^\circ \) (\( T_s \)\)\). Frozen soils correspond to \( T_s \) lower than 0 \(^\circ\text{C}\). Radar frequency \( f = 5.405 \, \text{GHz, } m_v = 20 \text{ vol{%}, } H_{rms} = 1 \text{ cm, incidence angle } \theta = 40 \circ, \) and polarization = VV.

### 4.3. Interpretation of Sentinel-1 Images

Figure 7 illustrates the temporal behavior for a wheat field, forest stand, and urban area for the Sentinel-1 backscattering coefficient \( (\sigma^\circ) \) in the VV and VH polarizations. For our study site, the vegetation cover of winter crop plots (wheat for example) is relatively low between November and January (height of approximately 5–10 cm). For the wheat field shown in Figure 7a, a decrease in \( \sigma^\circ_{VV} \) of approximately 3–4 dB is observed for the main dates of freezing (soil temperature between \(-0.6 \) and \(-3.7 \, ^\circ\text{C}\): 1, 7 and 31 December 2016; 6 January 2017; and between 18 and 26 January 2017. In addition, a slight decrease in \( \sigma^\circ_{VV} \) by approximately 1.5 dB is noted on 11 February 2017, when the soil was slightly frozen (soil temperature = \(-0.6 \, ^\circ\text{C}\)). With VH polarization, the difference between \( \sigma^\circ \) of unfrozen soil and \( \sigma^\circ \) of frozen soil is 1–2 dB higher compared to results obtained in VV polarization, which indicates that the volume scattering strongly influences the cross-polarized signal. Figure 7b shows a slight decrease of the radar signal for the forest stand after a frost episode. This decrease is 3 dB in VH at most (on 18 January 2017) and 2 dB in VV. This decrease of the radar signal corresponds mainly to a decrease of the dielectric constant of ground. The time series of \( \sigma^\circ \) for an urban area logically shows a relatively stable signal independent of frozen soil conditions (Figure 7c).
We calculated the difference in $\Delta \sigma^\circ$ for all fields corresponding to agricultural land cover (1016 fields) at two dates from Sentinel-1 images (VV and VH), one with an unfrozen soil condition (12 January 2017) and one with a frozen soil condition (18 January 2017). The $\Delta \sigma^\circ$ at a given date $t = \sigma^\circ (t_0) - \sigma^\circ (t)$, where $t_0$ is a date corresponding to the unfrozen soil condition date earlier than $t$. For a given field, $\sigma^\circ$ corresponds to the average of $\sigma^\circ$ of all pixels of the field. The histograms of the difference in $\Delta \sigma^\circ$ show that the mean $\Delta \sigma^\circ$ on 12 January 2017, is approximately $-1.5$ dB in VV and $-1$ dB in VH (Figure 8). For 18 January 2017 (frozen condition), the mean of $\Delta \sigma^\circ$ is approximately...
3.5 dB in VV and 5 dB in VH. Negative $\Delta \sigma^\circ$ values correspond to unfrozen soil and positive $\Delta \sigma^\circ$ values correspond to frozen soil. The $\Delta \sigma^\circ$ values between $-1$ and $+1$ dB are difficult to interpret because the error corresponding to Sentinel-1 radiometric accuracy is approximately 0.70 dB ($3\sigma$) for the VV polarization and 1.0 dB ($3\sigma$) for the VH polarization [30,31]. Fields with $\Delta \sigma^\circ$ values larger than 2 dB have a high probability of being frozen. Higher $\Delta \sigma^\circ$ values indicate a robust freezing degree. Figure 8a,b shows negative $\Delta \sigma^\circ$ values (or $\Delta \sigma^\circ < 1$ dB) corresponding to unfrozen fields on 12 January 2017 (unfrozen condition). For 18 January 2017 (frozen condition), most fields are detected from Sentinel-1 data as frozen (Figure 8c,d) with better identification using VH polarization (most fields have $\Delta \sigma^\circ > 2$ dB).

Figure 8. Histograms of the difference in $\Delta \sigma^\circ$ for two dates calculated from Sentinel-1 images, one with an unfrozen soil condition (12 January 2017) and one with a frozen soil condition (18 January 2017): (a) 12 January 2017, VV polarization; (b) 12 January 2017, VH polarization; (c) 18 January 2017, VV polarization; and (d) 18 January 2017, VH polarization. $\Delta \sigma^\circ$ at a given date $t = \sigma^\circ (t_0) - \sigma^\circ (t)$, where $t_0$ is a date corresponding to an unfrozen soil condition date earlier than $t$.

4.4. Frozen Soil Mapping

Analysis of the results from the previous sections shows that, when the soil temperature is below 0 °C, there is a significant difference in the radar signal compared to the radar signal with temperatures above 0 °C. Therefore, a simple approach can be proposed for frozen soil mapping. The approach is based on the difference in $\Delta \sigma^\circ$ for each field of the agricultural land cover between one image acquired under an unfrozen soil condition and one image acquired under a frozen condition. The date of the image under the non-freezing condition was acquired prior to that of the image acquired under the freezing condition. A difference greater than 2 dB corresponds to a frozen soil. In this approach, we assumed that soil surface roughness is constant between the dates used to calculate $\Delta \sigma^\circ$. 

\[ \Delta \sigma^\circ = \sigma^\circ (t_0) - \sigma^\circ (t) \]
Since the different images are not necessarily acquired at the same incidence angle (images in ascending/descending mode, with different strip map beams), it is necessary to reduce the incidence angle effect by normalizing the backscattering coefficients $\sigma_0^\circ$ by a function that represents the angular dependence. Consequently, the backscattering coefficient $\sigma_0^\circ$ acquired at an incidence angle $\theta$ can be normalized to a fixed reference angle $\theta_{\text{ref}}$ (for example $40^\circ$) using the following equation [32,33]:

$$\sigma_{\text{ref}}^0 = \frac{\sigma_0^0 \cos^2(\theta_{\text{ref}})}{\cos^2(\theta)}$$  \hspace{1cm} (16)

Surface frozen soil maps were built for all available dates. Figure 9 shows the presence or absence of frozen soils for one date with a frozen soil condition and another date with an unfrozen soil condition. A mask was applied to exclude forest and urban areas, as well as mixed land cover (urban + agriculture or forest + agriculture). The maps do not show the presence of frozen soils on 12 January 2017, using VV or VH polarizations (Figure 9a,b), which is consistent with the temperature data. Figure 9c,d shows our basin in a frozen soil condition on 18 January 2017, with better identification of frozen fields with VH polarization ($\Delta \sigma^\circ$ higher than 3 dB).

Figure 9. Maps of the frozen/unfrozen soil conditions: one date (12 January 2017) in an unfrozen soil condition (a,b); and one date (18 January 2017) corresponding to a frozen soil condition (c,d). Only crop fields were considered: (a,c) using VV; and (b,d) using VH. The mask in white corresponds to forest stands, urban areas and some mixed land cover (urban + agriculture or forest + agriculture).
For mapping frozen soils in an operational way, it is possible to classify the fields into three categories: (1) unfrozen soils for $\Delta \sigma^o$ values lower than 2 dB; (2) soils touched by freezing for $\Delta \sigma^o$ between 2 and 3; and (3) extremely frozen for fields with $\Delta \sigma^o$ higher than 3.

5. Discussion

Mapping of frozen soils has some limitations. The presence of snow can lead to poor mapping. If the soil at the acquisition date of the image considered under an unfrozen soil condition is covered with wet snow (temperatures above 0 °C), the radar signal will be at least 3 dB lower compared to the signal for snow-free surfaces or dry snow, which will cause confusion with the signal of a frozen soil and therefore will make it impossible to detect frozen soils. Thus, the difference between an image under a freezing condition and an image without frost but with wet snow will be quite small. The presence of dry snow on the reference image (unfrozen condition) does not lead to the misidentification of frozen soils because the backscatter is relatively high for dry snow or snow-free surfaces, whereas the backscatter can be 3 dB lower for wet snow.

In this study, we assumed that the soil roughness does not change over time. If the roughness of some fields increases on the frost date, then in this case, the difference $\Delta \sigma^o$ ($\sigma^o$ with freezing and with high roughness, and $\sigma^o$ without freezing with low roughness) will decrease and there may be poor detection of frozen soils. On the other hand, if the roughness decreases between the date of the image without freezing and the date of the image with freezing, the identification of frozen soils will be easier because the decrease of roughness on the date of the image with freezing will increase the signal difference $\Delta \sigma^o$ ($\sigma^o$ with freezing and with low roughness, and $-\sigma^o$ without freezing with high roughness).

To minimize the effect of a roughness change or the presence of snow on a date, the mapping frozen soils algorithm can use the average of all images acquired in an unfrozen condition before the acquisition date of the image to be analyzed under a freezing condition.

If the soil volumetric moisture content $m_v$ increases between the date of the image acquired without freezing and the date of the image under freezing condition, the difference between the radar signal without freezing and the radar signal with freezing should be less than the difference that would have been obtained if there was no rain between the date of the two images. However, if the soil volumetric moisture content decreases between the image dates, the difference between the radar signal for unfrozen soils and the radar signal for frozen soils will be greater than the difference that would have been obtained if there was no drying of the soil between the two images. This soil drying configuration will lead to a negligible decrease in soil moisture content between the two dates because the soil freezing process is mainly observed in winter and the natural soil drying could be assumed low between two images acquired with a few days of lag.

Knowing that the radar signal penetration depth in agricultural area is only a few centimeters at C-band [35], the C-band SAR images provide information on frozen soils only for the top soil surface layer. Thus, the few centimeters of C-band radar signal penetration depth do not allow obtaining information on deep frozen soils.

This study also showed that, for temperatures slightly below 0 °C (around −4 °C), the freeze in forest stands is slightly visible, probably because these areas freeze at much lower temperatures. Rignot et al. [2] observed at 3 dB decrease in the ERS-1 radar signal (C-Band) when the soil and vegetation freeze (air temperature reaches −30 °C).

It is worth mentioning that our study was carried out during the winter season with very low vegetation cover. In the case of more developed vegetation cover, possibly frozen areas mapping could be more difficult especially if the temperature is slightly below 0 °C (signal difference between unfrozen and frozen areas will be lower). Further investigations are necessary to analyze the effect of frozen water content in crop on the SAR backscattering coefficient.
6. Conclusions

This paper investigates, from a semi-empirical dielectric constant model and times series of Sentinel-1 images, the potential of the new C-band SAR Sentinel-1 sensor for classifying frozen/unfrozen soils in an agricultural context.

When the soil temperature decreases, the liquid water content also decreases, and, consequently, the backscattered signal decreases. The results indicate that frozen soils showed a lower radar backscattering signal than the unfrozen soils by approximately 3 dB. A classification of frozen soils using Sentinel-1 images was proposed to identify frozen and unfrozen soils for all crop fields. The method uses the difference between the radar backscattering coefficient of the image acquired at a date without any freezing condition (temperature higher than 0 °C) and the radar backscattering coefficient of acquired image under a frozen condition (temperature lower than 0 °C). Simulations performed from a semi-empirical dielectric constant model show that the difference between frozen soils and unfrozen soils increases when the soil moisture content increases.

If the soil roughness of a given field changes between the acquisition dates of the two images used, the image under a freezing condition and the image under a non-freezing condition, the detection of frozen soils can be problematic. In addition, the presence of wet snow on the image acquired under a non-freezing condition can lead to poor identification of frozen soils.

The results of this study provide an interesting way to map frozen soils using the high spatial and temporal resolutions of Sentinel-1 sensors. The frozen soil maps are of great interest to assess damage in agricultural areas.

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