Indirect readout: detection of optimized subsequences and calculation of relative binding affinities using different DNA elastic potentials

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ABSTRACT

Essential biological processes require that proteins bind to a set of specific DNA sites with tuned relative affinities. We focus on the indirect readout mechanism and discuss its theoretical description in relation to the present understanding of DNA elasticity on the rigid base pair level. Combining existing parametrizations of elastic potentials for DNA, we derive elastic free energies directly related to competitive binding experiments, and propose a computationally inexpensive local marker for elastically optimized subsequences in protein–DNA co-crystals. We test our approach in an application to the bacteriophage 434 repressor. In agreement with known results we find that indirect readout dominates at the central, non-contacted bases of the binding site. Elastic optimization involves all deformation modes and is mainly due to the adapted equilibrium structure of the operator, while sequence-dependent elasticity plays a minor role. These qualitative observations are robust with respect to current parametrization uncertainties. Predictions for relative affinities mediated by indirect readout depend sensitively on the chosen parametrization. Their quantitative comparison with experimental data allows for a critical evaluation of DNA elastic potentials and of the correspondence between crystal and solution structures. The software written for the presented analysis is included as Supplementary Data.

INTRODUCTION

Besides encoding for the identity of proteins in a living cell, the DNA base pair sequence carries information which is read out by proteins that bind to specific sites on DNA with remarkable selectivity. Sequence-specific binding is essential in gene regulation, DNA replication and compaction, and there has been much effort to understand its mechanism. In contrast to the genetic code, it has proven impossible to describe specific protein–DNA interactions entirely by a simple ‘recognition code’, based on direct chemical contacts of amino acid side chains to bases (1). Even when taking the 3D arrangement of protein–DNA contacts into account (2,3), the observed specificity cannot always be explained.

In general, complexation free energies also depend on the deformation required to distort both the protein and the DNA binding site into their 3D structure in the complex. In this way, sequence-dependent structure and deformability of DNA contribute to sequence-specific binding, an effect called indirect readout.

The bacteriophage 434 repressor, Figure 1, is a well-studied example. It was shown that mutations in the non-contacted region affect binding affinities 50-fold (4), and a correlation of affinity to the twisting rigidity and intrinsic twist of these mutations was found (5–7).

The importance of direct and indirect readout and protein–DNA binding affinities have been addressed computationally by sequence-structure threading. The elastic models considered range from a combination of fixed coarse-grained protein structure with DNA rigid rod (8,9), rigid base pair (10,11) and rigid base (12) models, to all-atom force fields with sequence-independent partial protein structure relaxation (13,14) and more recently, with sequence-dependent protein side chain relaxation (15,16), leading to high computational requirements.

In this article we focus on indirect readout and discuss its theoretical description in relation to the present understanding of DNA elasticity on the rigid base pair level. Available computational tools allow the convenient analysis of the base pair geometry in protein–DNA co-crystal structures (17,18). Here we add the calculation of elastic (free) energies which quantify elastic optimization and have a well-defined relation to competitive binding experiments. To estimate accuracy, we calculate all quantities for a set of five different (hybrid) DNA elastic potentials, which we obtained from parametrizations based on MD simulation (19) and structural data (20). This allows us to evaluate the robustness of our qualitative and quantitative conclusions with respect to inevitable parametrization uncertainties. The results are relevant also for coarse-grained models that include direct readout.
Rigid base pair model of DNA

We describe DNA elasticity at the level of rigid base pairs, see e.g. (21). The deformations in this model are given by a set of 3 + 3 variables specifying the relative position and orientation of two adjacent base pairs. We use the 6 bp step sequence step \( s \) for the 434 repressor complex, we can ask further, (vi) How strongly do the results of the analysis vary for different structural templates? (vii) Among the three solved properties of DNA suffice to predict the relative binding affinities of sequences which are mutated in regions of indirect readout? (v) Can we a posteriori evaluate different parameterizations of the DNA elastic potential, by comparing predicted and measured relative binding affinities? Given that there exist three different high-resolution X-ray structures of the 434 repressor complex, we can ask further, (vi) How strongly do the results of the analysis vary for different structural templates? (vii) Among the three solved co-crystal structures, is there one which seems to provide a better model of the solution complex?

The article is structured as follows: in the Materials and Methods section, we first derive the relevant elastic free energies starting from existing parameterizations of the rigid base pair DNA elastic potential, and considering the approximations involved in sequence-structure threading. Form these we then construct markers for indirect readout. In the Results and Discussion section, we apply our approach to a detailed re-investigation of elastic specificity in the 434 repressor complex. We discuss the robustness of our qualitative and quantitative observations to parametrization uncertainty and compare them to experimental data.

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ensemble covariance matrices $\mathcal{C}$. Stiffness matrices can be extracted under the assumption that equipartition of energy at some effective temperature occurs also in crystal ensembles.

To determine the effective temperature, we require that the fluctuation strength of the MD ensemble and that of a crystal ensemble $X = B, P$ be equal, i.e. $Z_X(\sigma, T) = Z_{MD}(\sigma, T)$. We consequently define the crystal stiffness matrices by $S_X(\sigma) = k_B T_X C_X(\sigma)^{-1}$. Here, the average of effective temperatures needed to reach equal fluctuation strength for each sequence is the ensemble’s effective temperature, 

$$T_X = 300 \text{ K} \left\langle \frac{\det \mathcal{C}_X(\sigma)^{-\frac{1}{2}}}{\det C_{MD}(\sigma)} \right\rangle_\sigma. \quad (2)$$

We obtain $T_B = 107 \text{ K}$ and $T_P = 233 \text{ K}$. Our B and P ensembles then have equilibrium values and stiffness matrices $\{\xi_{0,B}, S_B\}$ and $\{\xi_{0,P}, S_P\}$, respectively. In summary, the observed fluctuations in the crystal appear as strong as if they were thermally excited at their respective effective temperature, judging by the MD simulation.

In (19), the effective temperature for the P-DNA ensemble (20) was computed by comparing the persistence lengths for DNA oligomers extrapolated from a normal mode analysis of oligomers without temperature scale (24), to experimental values for B-DNA in solution. This yielded a value of $T_P = 295 \text{ K}$. While our microscopic approach matches fluctuations of all six rigid bp degrees of freedom to an MD simulation, this mesoscopic method (19) effectively matches the bending fluctuations only, to experimental data. For comparison, we have repeated our determination of effective temperatures using only the bending (i.e. Roll and Tilt) stiffness submatrices. This gives effective temperatures of $T_B' = 166 \text{ K}$ and $T_P' = 232 \text{ K}$, the latter value surprisingly unchanged from $T_P$. We denote the resulting crystal ensembles by B’ and P’.

If we were to introduce multiple effective temperatures, matching all sequences and degrees of freedom separately to the MD stiffness matrices, we would finally end up with the B and P equilibrium values combined with the MD stiffness matrices $\{\xi_{0,B}, S_{MD}\}$ and $\{\xi_{0,P}, S_{MD}\}$. Since the equilibrium values obtained from MD using the parm94 force field (25) generally have a Twist that is lower than commonly accepted values obtained from MD using the parm94 force field (25), we also included these two hybrid parametrizations, denoted MB and MP.

For the plots in the Results section, all quantities were calculated separately for the parametrizations MD, B, P, MB and MP. The mean and error bar of these lists are shown, giving an overview of the agreement between the available parametrizations. The B’ and P’ parametrizations are used only where indicated, for comparison.

When the effective temperature is set, we replace the observed distribution of deformations, $p_X(\xi \mid \sigma)$, by the corresponding Boltzmann distribution $p_X(\xi \mid \sigma) = e^{-F_X(\xi)} e^{-\beta K(\xi, \sigma)} = \frac{1}{Z_X} e^{-\beta F_X(\xi)}$ at $T = 300 \text{ K}$, given by (27) below. This distribution has covariance $C_X(\sigma)$, which is a rescaled version of $C_X(\sigma)$. The rescaled joint distribution $p_X(\xi, \sigma) = p_X(\xi \mid \sigma) p(\sigma)$ is the starting point of the discussion in the section on free energies below.

**Detecting indirect readout**

When some protein binds a specific sequence, it is because this sequence has optimal binding free energy. It is interesting to ask which part of the binding free energy is most important for specificity. Certainly, if DNA elasticity were the dominant part, the operator would be optimal with respect to DNA elasticity. Our working hypothesis is the converse: we assume that indirect readout dominates at positions where the operator sequence is optimal with respect to DNA elasticity. Otherwise, elastic optimization would be coincidental. To systematically exclude false positive detections, additional information on direct readout is required, which is beyond the scope of this work. We can still greatly reduce the probability of false positives by a high threshold for optimization and by considering simultaneous optimization of subsequences.

The question whether an operator is elastically optimal can be given two different precise meanings. Consider a known structure of some stretch of DNA in a co-crystal. We may ask

(i) Is the structure optimal for the observed sequence? i.e. how relaxed is this sequence in the given structure? 
(ii) Is the sequence optimal for the observed structure? In other words, are other sequences distorted more strongly?

These questions can be answered by considering two different thermodynamic potentials or free energies. In the following two, more technical subsections, we introduce a deformation free energy $F(\xi)$ and a sequence potential $G(\sigma)$, both defined for single as well as for multiple bps. $F$’ is relevant when comparing different structures, and answers question (i) above. $G$ is the relevant free energy when comparing different sequences in the same structure, and answers question (ii). We then relate these free energies to competitive binding experiments and indirect readout.

**Free energies derived from a bps ensemble**

Suppose we are given some (MD or crystal) ensemble $\{\xi_i, \sigma_i\}_{i=1}^N$ of elastically fluctuating, single bps. The step deformations and sequences are jointly distributed according to some normalized probability density function (pdf) $p(\xi, \sigma)$, which contains all available statistical information.

At a temperature $T = 300 \text{ K}$ (in our case) we can associate to the joint pdf a free energy $K$,

$$\beta K(\xi, \sigma) = - \ln [p(\xi, \sigma)], \quad (3)$$

where $\beta = 1/(k_B T)$. The constant $\nu$ is a volume scale in $\xi$ space needed to fix dimensions, and drops out in all free energy differences. Differences in $K$ correspond to relative probabilities in the ensemble, of bps that differ in sequence and structure.

Taking partial averages, we get the marginal pdf’s: $p(\sigma) = \int p(\xi, \sigma) d\xi$ gives the frequency of a sequence step in the ensemble while $p(\xi) = \sum_\sigma p(\xi, \sigma)$ is the pdf to find the deformation $\xi$ in any sequence step.

The deformations of a chosen sequence step $\sigma$ follow the conditional pdf $p(\xi \mid \sigma)$ to find $\xi$, given $\sigma$. Since in DNA the angular distributions are quite sharply peaked, it is safe to neglect the curvature and finite boundaries of $\xi$-space. A fit of $p(\xi \mid \sigma)$ with a 6D Gaussian, which is the maximum entropy distribution with the mean and covariance of the data,

$$p(\xi \mid \sigma) = \frac{p(\xi, \sigma)}{p(\sigma)} = (2\pi)^{-3} Z(\sigma)^{-1} e^{-\beta E(\xi)}, \quad (4)$$

where $Z(\sigma)$ is the partition function for $\sigma$.
defines the parameters $\xi_0$ and $S$ of the quadratic elastic energy $E_d(\xi)$, Equation 1. The partition sum $Z(\sigma) = \det[S(\sigma)/(k_BT)^{1/2}]$ gives the overall fluctuation strength (20). This Gaussian fit is by no means necessary to define the elastic free energies below. We use it here since the parameter sets we consider are given to this approximation. With more detailed (multi-modal) energy functions, conformation space integrals would get more involved but the formalism would not change. We associate a deformation free energy.

$$\beta F_d(\xi) = -\ln[v_p(\xi \mid \sigma)] = \beta K(\xi, \sigma) + \ln[p(\sigma)].$$

A free energy difference $F_d(\xi') - F_d(\xi) = E_d(\xi') - E_d(\xi)$ expresses the relative probability to find the deformation $\xi$ rather than $\xi'$ in the data, given that we are looking at a fixed sequence $\sigma$. $F$ corresponds to a canonical potential (or Helmholtz free energy) at fixed sequence, depending on the state variable $\xi$. Using Equation 4 one can see that up to a constant, we have the relation $F = E - T\Delta S$. Here

$$\Delta S(\sigma) = +k_B \int p(\xi \mid \sigma) \ln[v_p(\xi \mid \sigma)] d\xi$$

$$= -k_B \ln[v^{-1}Z(\sigma)] + \text{const}$$

6 is the entropy change upon binding of the fluctuating harmonic bps. Softer steps lose more entropy when forming a complex. The difference in $\Delta S$ between sequence steps is up to $2 k_BT$. Here we do not assume that the fluctuations are fixed completely, but only that for all sequence steps $\sigma$ and we associate a deformation free energy, without the additional requirement that the sequence steps match, $\sigma_i = (b_j, b_{j+1})$, where $\sigma = (b_1, \ldots, b_{l+1})$ is a sequence of $l + 1$ bases.

Similarly, we may ask for the probability to find the sequence step $\sigma$ among all steps at fixed deformation $\xi$. It is given by the (discrete) conditional pdf

$$p(\sigma \mid \xi) = \frac{p(\xi, \sigma)}{p(\xi)}.$$  

7 and we associate a sequence potential

$$\beta G_2(\sigma) = -\ln[p(\sigma \mid \xi)] = \beta K(\xi, \sigma) + \ln[v_p(\xi)].$$

8 A potential difference $G_2(\sigma) - G_2(\sigma')$ expresses the relative probability to find the sequence $\sigma$ rather than $\sigma'$, given we are looking at a fixed deformation $\xi$. A value $G_2(\sigma) = 0$ at deformation $\xi$, the sequence $\sigma$ occurs with certainty in the ensemble. $G_2(\sigma)$ corresponds to the Gibbs free energy in the grand canonical ensemble, at fixed deformation $\xi$.

Often, it is interesting to compare sequences in an unbiased ensemble where each sequence step is equally probable, so $p(\sigma) = \text{const}$. In this situation, the formulas look simpler. We obtain

$$\beta G_2(\sigma) = \beta F_d(\xi) + \ln \sum_{\sigma'} e^{-\beta F_d(\xi'}).$$

9 In fact, since now $G_2(\sigma) - G_2(\sigma') = F_d(\xi) - F_d(\xi')$ the relative probabilities of sequences are in this case expressed by their $F$ differences. Still, $E$ differences (10) cannot be used instead, since they lack the term $T\Delta S$ (see Equation 6).

Multiple steps

We extend the free energies introduced above for single steps to a sequence of consecutive steps. These may be efficiently calculated without making the approximation (12) of additive single step free energies.

By assumption, the deformations in our model fluctuate independently. However, we have to make sure that consecutive steps form a meaningful sequence, e.g. AC can be followed by CG but not by GC. This clearly correlates the sequence steps. To get the correct free energies for a stretch of multiple bps, we go back to the probabilities.

Extending previous notation, we now denote a base pair step sequence (bps) by $(\xi, \sigma)$. It consists of $l$ bps $(\xi_j, \sigma_j)$ with the additional requirement that the sequence steps match, $\sigma_i = (b_j, b_{j+1})$, where $\sigma = (b_1, \ldots, b_{l+1})$ is a sequence of $l + 1$ bases.

Computing the pdf’s, we have $p(\xi \mid \sigma) = \prod_j p(\xi_j \mid \sigma_j)$ since the deformations are independent. Consequently, $\beta F_d(\xi) = \beta \sum \beta F_d(\xi)$. The sequence pdf $p(\sigma)$ has to be renormalized so that its sum over matching sequences is unity. Define

$$W_l = \sum_{\sigma} \prod_{i=1}^l p(\sigma_i),$$

10 where the primed sum runs only over matching sequences with $l$ steps. Then clearly $p(\sigma) = W_l^{-1} \prod_i p(\sigma_i)$ and $p(\xi, \sigma) = W_l^{-1} \prod_j p(\xi_j, \sigma_j)$ are properly normalized. In the case where all sequences are equally likely, one can check that $p(\sigma) = 4^{-l(l+1)}$. The joint free energy $K$ is not additive because of the renormalization,

$$\beta K(\xi, \sigma) = -\ln[v^l p(\xi, \sigma)] = \beta \sum_{j=1}^l K(\xi_j, \sigma_j) + \ln W_l.$$  

11 For the sequence potential we obtain

$$\beta G_{2l}(\xi) = -\ln[p(\sigma \mid \xi)] = \beta K(\xi, \sigma) + \ln[v^l \sum_{\sigma'} p(\xi, \sigma')].$$

12 Noting that

$$W_l v^l \sum_{\sigma'} p(\xi, \sigma') = \prod_j p(\xi_j) \sum_{b_i, \ldots, b_{l+1}} p((b_j, b_{j+1}) \mid \xi_j),$$

13 we can introduce the $4 \times 4$ transfer matrix $T(\xi)$ with entries

$$T(\xi)_{b', b''} = p((b', b'') \mid \xi_j) = e^{-\beta E_t((b', b''))}$$

14 and rewrite the primed sum as a matrix multiplication. With $1^T = (1, 1, 1, 1)$, the sequence potential of a bps finally acquires the compact form

$$\beta G_{2l}(\xi) = \beta \sum_{j=1}^l G_{2l}(\xi_j) + \ln [1^T T(\xi_1) \cdots T(\xi_l) 1],$$

15 which is again not additive. Even though there are $4^{l+1}$ possible sequence mutations, $G$ can be computed in a time $\propto l$. Note that for $l = 1$, the formula reduces to the single step result since $p(\sigma \mid \xi)$ is normalized.
Whenever the steps are equidistributed, \( p(\sigma) = \text{const} \), the formulas become simpler. In particular, one can see from Equations 14 and 15 that, as in the single step case, \( G_\sigma(\sigma) - G_\sigma(\sigma') = F_\sigma(\xi) - F_\sigma(\xi') \), while \( E \) differences would give a different result.

**Competitive binding**

The free energies just derived in the context of freely fluctuating bps, have a direct relation to an idealized competitive binding experiment. Consider a protein that can bind any operator sequence \( \sigma \) in some corresponding structure \( \xi \), but has no intrinsic sequence preference. That is direct readout that drives complex formation has the same strength for all operators, and is absent for non-operator sequences. This protein may be in contact with a bps ensemble, such as a genome containing operators with relative frequencies \( p(\sigma) \) (different from the frequencies in the reference ensemble above). Then the relative occupancies of the protein with different sequences are determined only by elastic free energy differences.

Binding the sequence \( \sigma \) in a structure \( \xi \) costs a deformation free energy \( F_\sigma(\xi) \). Multiplying the probability \( p(\sigma) \) to find \( \sigma \) at all in the ensemble gives the relative occupancy of \( (\sigma, \xi) \) compared to \( (\sigma', \xi') \) as \( \exp\{-\beta[K(\xi, \sigma) - K(\xi, \sigma')]\} = p(\sigma, \xi)/p(\sigma', \xi') \). In two different situations this general result simplifies.

A complex structure that minimizes \( F_\sigma(\xi) \) is optimal in the sense of question 1. above, i.e. it is the most relaxed structure for \( \sigma \). Whenever all steps in the bps ensemble are equally frequent, those sequences will bind whose bound structures are most relaxed. We get \( p(\sigma, \xi)/p(\sigma', \xi') = \exp\{-\beta[G_\sigma(\sigma) - G_\sigma(\sigma')]\} \), see (4). Protein–DNA binding can be driven by enthalpy or by entropy or by a combination thereof (28). While the total entropy of complex formation may be nonuniform, but all sequences bind in one fixed deformation \( \xi \) in the complex, and softer steps acquire a higher entropic contribution that counteracts complexation. This trend persists also if the suppression of fluctuations upon binding is only partial.

Consider a binding experiment as above, in which now the protein is very stiff. Here, the sequence distribution \( p(\sigma) \) may be nonuniform, but all sequences bind in one fixed deformation \( \xi \). In this situation, we see from Equation 8 that \( p(\sigma, \xi)/p(\sigma', \xi) = \exp\{-\beta[G_\sigma(\sigma) - G_\sigma(\sigma')]\} \). The sequence that minimizes \( G \) is optimal in the sense of question 2. above, i.e. it is the sequence that fits best with the prescribed structure, taking into account its frequency in the ensemble.

If both special cases occur at the same time, we have a fixed \( \xi \) and constant \( p(\sigma) \). Then indeed \( F \) and \( G \) differ only by a constant, so they give the same relative occupancies. However, the elastic energy \( E \) will still give different results.

**Measures of elastic optimization**

For some stretch \( (\xi, \sigma) \) of DNA in a given co-crystal structure, we would like to tell whether it is specifically bound because of DNA elasticity. Naively, one might assume that this is the case if it carries a small elastic energy, but this is not correct. We are really asking: compared to all mutated sequences, is \( \sigma \) elastically optimal? In general, this is the case if \( K(\xi, \sigma) < K(\xi', \sigma') \) for all other \( (\xi', \sigma') \).

Most of the time however, there is only one crystal structure \( \xi \) available as a model for the solution complex. We can still plug all possible sequence mutations into that structure and calculate their free energies. For sequence-structure threading, we therefore make the additional simplifying approximation that the experimentally inaccessible complexes \( (\xi', \sigma') \) of the protein with any other DNA sequence \( \sigma' \) will force the DNA into essentially the same structure \( \xi \). One can check that

\[
K(\xi, \sigma) - K(\xi', \sigma) = G_\xi(\sigma) - G_\xi(\sigma') + F_\sigma(\xi) - F_\sigma(\xi').
\]

Then our approximation is that \( |F_\sigma(\xi) - F_\sigma(\xi')| \ll |G_\xi(\sigma) - G_\xi(\sigma')| \), which could be called the stiff protein limit, and we disregard the \( F \) difference between structures. The same approximation is effectively made in (13), where after an initial partial structure relaxation the structure was kept fixed, and in the static model of (12). The validity of the stiff protein limit depends on the protein in question. However, when only one structure is known, it is a reasonable first approximation to consider only the known part of the free energy difference. As an aside we note that when the protein is stiffer than DNA, it will itself store less elastic energy, making the protein elastic energy contribution to the total binding energy less important.

Consider a competitive binding experiment where all possible mutated sequences occur with equal probability \( p(\sigma') = \text{const} \). To find an optimal sequence, we can then look for minimal \( F_\sigma(\xi) \). An example of an \( F \) histogram of all sequence mutations is shown in Figure 4. One widely used (11,22) way to quantify optimization of the native sequence is the Z-score, given by the difference of the mean \( F \) to the native \( F \), normalized by the width of the \( F \) histogram. We add another option: Looking only at the low \( F \) tail, we consider the normalized difference of the native \( F \) to the minimal \( F \). For an example of both quantities see Figure 3. Any Z-score disregards information on the global scale of free energy differences in a histogram. The normalization with the histogram width makes quantitative comparison with experiments impossible.

A more direct way to quantify optimization is to consider just the free energy \( G_\xi(\sigma) \) of the native sequence. Since this is the logarithm of a normalized pdf, \( \sigma \) has a higher-than-random probability of occurring if \( G_\xi(\sigma) \) is lower than that of an ensemble with \( p(\sigma' \mid \xi) = \text{const} \). By normalization, a value \( G_\xi(\sigma) = 0 \) means that \( \sigma \) occurs with certainty at that deformation, \( G_\xi(\sigma) \approx \ln 2 \) means that \( \sigma \) has half of the total probability, and \( G_\xi(\sigma) = (l+1) \ln 4 \) is the random value for a bps with \( l \) bps. It is clear that the value of \( G(\sigma) \) alone contains information about how low-lying the corresponding \( F_\sigma \) is in the \( F \) histogram. In fact, the sequence potential \( G_\xi(\sigma) \) is similar to a Z-score, but computed for the Boltzmann factors: In the case \( p(\sigma') = \text{const} \), by rewriting Equation 9, we get \( G_\xi(\sigma) = F_\sigma(\xi) - \bar{F}(\xi) \), where

\[
\beta \bar{F}(\xi) = -\ln \sum_{\sigma} e^{-\beta F_\sigma(\xi)}.
\]
This can be interpreted as the difference of \( F_{\sigma} \) to an ‘exponential mean’ \( F \) over all mutations, where sequences with high \( F \) value are exponentially suppressed, according to their statistical weight.

Since \( G \) is a true free energy, it is directly related to relative affinities in a competitive binding experiment, unlike their statistical weight. Assuming a stiff protein with structure \( \xi \), and regarding only DNA elasticity, any mutated subsequence \( \sigma' \) of length \( l \) binds with a probability \( p(\sigma' | \xi) = e^{-\beta G_i(\sigma')} \). Instead of looking at an entire subsequence one can ask for the probability to find just one base \( b \) at a certain position \( i \) in all length \( l \) subsequences. This probability \( p_i(b) \) is given by the expectation

\[
p_i(b) = \sum_\sigma \delta_{b|\sigma} e^{-\beta G_i(\sigma)},
\]

where \( \delta \) is the Kronecker delta. Using Equation 15, we obtain

\[
p_i(b) = \frac{1^T\left(T(\xi_1) \cdots T(\xi_{l-1})P_{b_1}T(\xi_2) \cdots T(\xi_{l+1})1\right)}{1^T\left(T(\xi_1) \cdots T(\xi_{l+1})1\right)}.
\]

Elastic consensus sequences

Assuming a stiff protein with structure \( \xi \), and regarding only DNA elasticity, any mutated subsequence \( \sigma' \) of length \( l \) binds with a probability \( p(\sigma' | \xi) = e^{-\beta G_i(\sigma')} \). Instead of looking at an entire subsequence one can ask for the probability to find just one base \( b \) at a certain position \( i \) in all length \( l \) subsequences. This probability \( p_i(b) \) is given by the expectation

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\]

Here the matrix \( (P_{b})_{\sigma'\sigma} = \delta_{b|\sigma} \delta_{\sigma'|\sigma} \) is a projector onto the base \( b \). This expression takes into account sequence correlations up to the window length \( l \). Calculating \( p_i(b) \) for all bases \( b = A, T, C, G \) along a given structure, using centered windows of constant length, gives a complete base-per-base picture of elastic preference in the structure. To check for elastic preference for the native sequence, one can just set \( b = \) native base at each position.

Similarly, we can ask for the joint probability \( p_{i,i+k}(\sigma) \) to find \( k \) bases \((b_i, \ldots, b_{i+k}) = \sigma \) at positions \((i, \ldots, i+k)\) in all length \( l \) subsequences. To calculate it, we have to insert projectors at all base positions in question,

\[
p_{i,i+k}(\sigma) = \frac{1^T\left(T(\xi_1) \cdots T(\xi_{l-1})P_{b_i}T(\xi_2) \cdots P_{b_{i+k}}T(\xi_{l+1})1\right)}{1^T\left(T(\xi_1) \cdots T(\xi_{l+k})1\right)}.
\]

The difference of this expression to the probability \( p(\sigma | \xi) \) of the \( k + 1 \) bp sequence \( \sigma \) is that \( p_{i,i+k}(\sigma) \) takes sequence correlations up to the boundary of the length \( l \) subsequences into account, while \( p(\sigma | \xi, \ldots, \xi_{l+k}) \) cuts them off at length \( k \). Whenever \( k = l \), there are projectors to the left and right of all transfer matrices and both expressions agree. Note that in general \( p_{i,i+k}(\sigma) \) is a function of the window length \( l \) up to arbitrary \( l \). In practice, one can simply choose for \( l \) the complete binding site length, since the computational cost is \( \propto l \) only. We remark that no approximation of base-wise or step-wise additivity (12) is necessary here.

It has been pointed out (29) that different distributions \( p_i(b) \) contain varying amounts of information. For example, a position \( i \) at which all bases are equally probable has no information and should be considered as carrying no elastic specificity. Extending this to the case of \( k + 1 \) bases, we need to calculate the entropy of the distribution \( p_{i,i+k}(\sigma) \),

\[
\Sigma_{i,i+k} = - \sum_\sigma p_{i,i+k}(\sigma') \ln p_{i,i+k}(\sigma') \leq (k + 1) \ln 4.
\]

A measure for the information content of the distribution that ranges from 0 to 1 is given by \( I_{i,i+k} = 1 - \Sigma_{i,i+k} / [(k + 1) \ln 4] \). An extension of a sequence logo (29) for length \( k + 1 \) subsequences can then be constructed by plotting the relative frequency of each subsequence, scaled with the information content, along the complex. For \( k > 0 \), the subsequences overlap, so the usual letter scaling notation cannot be used. However, the most interesting information can be shown by plotting \( I_{i,i+k} p_n(b,i,k)(\sigma) \) for native subsequences only, see Figure 6 below. Such a plot shows directly how well the native sequence coincides with an elastic consensus sequence, and gives a local marker for which significantly nonzero values point to elastic specificity. Again, since the subsequence length of interest is usually just a few base pairs, computation is cheap.

RESULTS AND DISCUSSION

Indirect readout in 434 repressor

The 434 repressor is a viral transcription factor that forms part of a genetic switch between the lytic and lysogenic states in the bacteriophage 434 virus. There exist two operator regions \( O_R \), \( O_L \) with three binding sites of 14 bp in each region (4). The protein dimer binds in a helix–turn–helix motif, making the structure (27,30,31) approximately 2-fold rotationally symmetric. The outermost 5 + 5 bases on each binding site are directly contacted by the protein, and the sequence of the outermost 4 + 4 bases is conserved with a single base exception in all six binding sites. The consensus sequence of the contacted outer 5 + 5 bases shows the 2-fold symmetry expected from the structural symmetry. In contrast, the inner four bases are not contacted directly. Their sequence is neither conserved nor rotationally symmetric. Interestingly, binding affinities of the native binding sites vary 40-fold, and those of synthetic binding sites vary as much as 200-fold, depending only on the sequence of the inner four bases (4,30). This is true even though in the existing structures none of the individual bps is kinked strongly, and the overall bend is between 25 and 40 degrees. In gel shift experiments (32), the overall bend was found to be small and sequence-independent, supporting the idea that the protein is stiffer than DNA.

Together these facts indicate that indirect readout in the central part is important in tuning the relative affinities of 434 repressor for different operators. For the contacted outer 5 + 5 base pairs we expect no elastic specificity, since protein–DNA contacts are likely to dominate interaction energies there. DNA distortion is moderate and the protein is reasonably stiff, so quadratic bps potentials should reflect this behavior.

Elastic energies

For an overview over DNA elastic energy in the 434 repressor, we plot elastic energies \( E_F(\xi) \) versus base pair number in Figure 2. Here, \( \sigma \) denotes the sequence of a bps or a bpss, and
within each structure. In important partial energy varies between the structures and even any one of the partial energies. Rather, the identity of the most ably different and show no common features at the central non-

Since all coupling stiffnesses are averaged out, the partial ener-

Figure 2. Elastic energy $E$ along $O_{R1}$, 2, 3. A 3 bps window was used. The elastic energy and parametrization uncertainty per bps are shown in units of $k_BT$. The top curve shows the full elastic energy, while partial energies are shown subsequently shifted down by $2 k_BT$ for clarity.

$\xi$ denotes the corresponding step deformations. The bps deformations were extracted from the structure data using the program 3DNA (17). The energy per step in a moving window of length three steps around each bps was computed, using the five hybrid potentials introduced in Materials and Methods. The mean and SD of these five values give a data point and error bar in the plot, respectively.

Partial energies for bend, twist, shear and stretch are also shown. These are calculated by replacing the full correlation matrix $C = S^{-1}$ by its $(Ti,Ro)$, $(Tw)$, $(Sh,Sl)$ and $(Ri)$ submatrices, respectively. This corresponds to integrating out the other variables. In each case, the correlation $1 \times 1$ or $2 \times 2$ submatrix is inverted to give the partial energy stiffness matrix. Since all coupling stiffnesses are averaged out, the partial energies obtained in this way do not sum up to the full energy.

The full and partial energies for the three crystal structures show variation along the structure that is well above the parametrization uncertainty. However, all curves look remarkably different and show no common features at the central non-contacted bases. Elastic energy is not strongly dominated by any one of the partial energies. Rather, the identity of the most important partial energy varies between the structures and even within each structure. In $O_{R1}$ and $O_{R3}$, bend and stretch appear most important, respectively. In $O_{R2}$ there is a remarkable balance between all four partial energies. We checked that the main contributions to the twist energy at bases 6 to 10 result from overwisting, in accord with experimental results that indicate overwisting of the central region (5). However, twist does not appear more important than other partial energies. The overall bending angles for $O_{R1}$, 2, 3 are around 25, 40 and 30 degrees, respectively. Although $O_{R1}$ has the lowest overall bend, $O_{R3}$ clearly is the most relaxed structure.

Free energies and specificity

We now return to the full elastic energies. For an overview of elastic optimization in the three 434 repressor complex structures, the upper two rows in Figure 3 show the elastic energy $E$ and the deformation free energy $F$ of the native sequence, normalized per bps. They are computed in a centered moving window of length 3 bps, which gives sufficient spatial resolution to distinguish the central from the outer base pairs while smoothing the curves. Although, the deformation free energy $F$ includes conformational entropy of the bps, this contribution is smoothed by the mov-

Overall, the $E$ or $F$ profiles give no clear signal that would correspond to the experimentally observed specificity in the central 4 bp. This is not surprising since only the value of $F$ compared to the whole $F$ distribution of all mutated sequences is relevant for sequence optimization, see Materi-

Quantifying these observations, we return to Figure 3. The third row shows the $F$ difference of the native sequence to the mean ($Z_{mean}$) and to the minimum ($Z_{min}$), computed from $F$ histograms of all mutated sequences in the same moving windows as in the rest of the panel, and normalized by the width of the histograms. In line with Figure 4, the $O_{R2}$ plot shows a maximum in the central region. The corresponding maxima in the other $Z$-score plots show that also in $O_{R1}$, 3 the native sequence is especially low-lying at the central base positions. Generally, the constant difference $Z_{mean} - Z_{min}$ indicates that while the width of the histograms may change, the shape of the distribution stays the same. Note that through its normalization by the width of the histogram, any $Z$-score discards information about the width of the $F$ histogram, which as illustrated by Figure 4, may vary with the window position. The native sequence comes close to the minimal $F$ only in a small region which coincides well with the four central base pairs.

The fourth row of Figure 3 shows the sequence potential $G$, given per bp, together with the random $G$ level. It is computed in a 3 bps window and assuming a uniform sequence probability $p(\sigma)$. In contrast, to the deformation energies, $G$ shows a significant dip below the random value close to the center, in all structures. Since $G$ is normalized per bp, a value $G = 0.5$ corresponds to $8\%$ probability of the native 4 bp sub-

The $G$ dip shows that subsequences around the central, but not the outer, base pairs of the binding site occur with a probability above chance, when accounting only for DNA elasticity. In this sense the native sequence of the central base pairs is optimized, in each of the three available structures. The minimum in $G$ agrees well with the maximum of $Z_{min}$, which can be explained with the exponentially high weight of the sequences with low $F$. Following the reasoning in the Materials and Methods section, these measures give a clear indication for indirect readout mediated by DNA elasticity in the central region of the 434 repressor. The fact...
bps 3, 7 and 11 from left to right. The structure is units. All possible mutations inside a 5 bps window were generated, around exactly the same as a simple moving average of the single

indicates the set combined with P-DNA equilibrium values is used. The vertical line

Deformation energy in kBT sequence potential mean (green) and minimum (gray), third row. The fourth row shows the marks the inner 4 bp.

bps. Error bars indicate parametrization uncertainty, and lighter shading out from one representative crystal structure in general.

Figure 3. Elastic optimization in 434 repressor structures OR1, 2, 3. Deformation energy E and free energy F, first and second rows. Z-scores of mean (green) and minimum (gray), third row. The fourth row shows the sequence potential G together with the random G level. All energies are given in k_BT. E and F are per bps while G is per bp. The moving window length is 3 bps. Error bars indicate parametrization uncertainty, and lighter shading marks the inner 4 bp.

Figure 4. Histograms of the free energy per bps of mutated sequences, in k_BT units. All possible mutations inside a 5 bps window were generated, around bps 3, 7 and 11 from left to right. The structure is OR2, and the MD parameter set combined with P-DNA equilibrium values is used. The vertical line indicates the F value of the native sequence.

that all available structures show the same feature lends support to the method of inferring the presence of indirect readout from one representative crystal structure in general.

In the above results, the moving window length is not crucial for the central dip. While any window from 1 to 5 bps will show the same trend, there is a tradeoff between spatial resolution and noise.

Native versus elastic consensus sequences in 434 repressor

We have shown that the central 4 bp native subsequences are elastically optimized in the 434 repressor structures. But how strongly is the identity of each individual base of the native sequence preferred? When using very short subsequences to calculate G, the results get noisy. We show one typical example of the tradeoff between spatial resolution and noise in Figure 5.

We stress that while using a moving window for E is exactly the same as a simple moving average of the single bps energies, this is not the case for G; as can be seen from Equation 15, the difference is an additional term that account for sequence continuity.

A way around the large local free energy variations is to check how similar the native base is to an elastic consensus sequence, at each position, see Materials and Methods. This is quantified by first obtaining the probability p_i(b_i) to find the native base b_i at position i, in the full distribution of sequence free energies for the complete binding site. This probability can then be scaled by the information I_i contained in the probabilities p_i of all four bases at position i. The information I_i is the height at position i of a sequence logo (29) constructed from DNA elasticity, while the scaled probability I_i p_i(b_i) gives the height of the native base in such a logo. In the same way, the similarity of small native subsequences with a elastic consensus subsequences may be defined Methods.

In Figure 6 the similarity to elastic consensus is shown for native subsequences of 1, 2 and 4 bases. The information is scaled to range from 0 (equidistribution) to 1 (total concentration to a single subsequence). The scaled native probability indicates elastic specificity of the native sequence on the level of single bases, dimers, and tetramers, from top to bottom. Interestingly, in the OR1, 2 complex structures, elastic specificity is concentrated on two central bases, and while the information still has a maximum in the center for the 4 bp logo, the native 4 bp subsequences have a very small part of the total probability. In contrast, in the OR3 structure, specificity is not as strong as expected from the G plots, Figure 3, for the one base and two base subsequences. Instead, specificity for the native sequence is distributed over several bases, as can be seen in the 4 bp row, where the native sequence still has high probability. It appears that the more relaxed structure of OR3 achieves selectivity by a combination of several smaller base preferences.

Origins of specificity

Indirect readout is caused by the sequence dependence of both DNA structure and DNA stiffness. Does the structure or the stiffness dependence have a stronger effect? We can selectively switch off either one, by averaging either the equilibrium values or the covariance matrices of the bps potential over all possible sequence steps. The profiles of the resulting averaged sequence free energies in 434 repressor are shown in Figure 7. The characteristic G dip at the central bases persists when the stiffness matrices are averaged, and the G curve roughly traces the original one. However, averaging the equilibrium values and retaining sequence dependent stiffness, does alter the shape of the curves, and the central G dip is lost. This indicates that sequence dependent structure is more important for indirect readout than sequence dependent stiffness, at least in the present example.

Is it possible to explain sequence specificity by a reduced set of variables? For example, can twisting alone explain indirect readout in the 434 repressor, as suggested by the fact (5) that operators with higher twist in the central region have higher affinity for 434 repressor than those with lower twist? We investigated this question using partial sequence free energies derived from the partial elastic energies in the same way as the full G is derived from the full E.
In Figure 8 we show both full and partial sequence free energies (compare Figure 2). The result is ambiguous. In OR2, twist and shear together do account for the characteristic $G$ minimum in the center. In the other structures, sequence specificity appears to arise from an interplay between all deformation modes.

Comparison of parametrizations

In order to emphasize the features in the energy profiles that are robust with respect to parametrization, we have so far shown mean values and standard deviations of our set of five parametrizations. In the present section we compare these results for different elastic potentials in more detail, using the 434 structures as an example. In Figure 9 we show plots of the elastic energy $E$ and of the sequence free energy $G$ of all mentioned parametrizations, and in addition the crystal ensembles rescaled using effective temperatures for bending only, $B_0$ and $P_0$ (see Materials and Methods).

When comparing $B_0$ and $P_0$ to $B$ and $P$, the elastic energy is simply scaled by the effective temperature ratio and thus depends quite sensitively on the choice of this parameter. However, the sequence free energy depends much less on variations in effective temperature. In particular, the predicted regions of elastic optimization are remarkably insensitive to effective temperature uncertainty.

Comparing the OR2 elastic energy profiles for different parametrizations, the overall shape generally agrees better for the partial energies than for the total energy, suggesting that the coupling terms vary more strongly. The main contribution to the twist energy comes from overtwisting. Consequently, the MD parametrization which has low equilibrium twist values, gives the highest twist energy. In contrast, the overall shape of the total sequence free energy profiles is less affected by the choice of parameters. In particular, the dip in the central region always appears. The robustness of this qualitative feature is also directly evident from the parametrization error bars that we used throughout the article.

Binding affinities

Experimental evidence for indirect readout in 434 repressor comes from the dependence of binding affinity on the sequence of the central, non-contacted bases (4). Does DNA elasticity alone already capture the observed affinities? If DNA elasticity dominates over chemical effects, and if in addition the protein forces all of the artificial sequences into a common structure $x$, then one expects that

$$\beta [F_0(\xi) - F_\sigma(\xi)] = \ln [c_{1/2}(\sigma)/c_{1/2}(\xi)]$$

Here $c_{1/2}(\sigma)$ is the affinity, given by the (normalized) repressor concentration needed to occupy half of the operators $\sigma$. Note that the mere existence of three different 434-operator co-crystals implies that the above equation is an approximation.
together with MP (MP, OR3). Error bars indicate the spread in line indicates equality.

In Figure 10 we plot left hand side versus right hand side of the equation. We used affinity data of ten 14 bp artificial sequences, which differ only in the central base pairs (4). The experimental affinities for the R1–R69 subdomain of the repressor were used, since this eliminates cooperative binding effects and corresponds to the domain that was crystallized (30). The \( F \) differences are computed as the total deformation free energy for the same sequences in each of the 14 bp \( O_R \) structures. Out of the two possible orientations in which the repressor can bind, we used the one with lower \( F \) value. This makes a difference only for those three artificial sequences that are not self-complementary. All possible combinations of \( \sigma \) and \( \sigma' \) are shown, so the plots are inversion symmetric.

Clearly there is a positive correlation between the log affinity and \( F \) differences in all panels. A priori, we have no way to single out one of the crystal structures or one of the parametrization as corresponding best to the experiment. When we consequently plot error bars resulting from all possible combinations of structure and parametrization (AVG), the result is compatible with the data but has no predictive power. Possible reasons are (i) our basic assumptions (independent bps, stiff proteins, elasticity dominating binding in 434) are not justified, (ii) the crystal structures do not correspond to the relevant structures in solution closely enough and (iii) the parametrizations of the potential are inexact.

A posteriori, we can check whether one combination of parametrization and crystal structure stands out as the best model for the measured solution affinities. Figure 11 gives an overview of affinity-free energy plots for all such combinations. They show widely varying RMS deviation, ranging from 1.5 \( k_B T \) to 26 \( k_B T \) depending on the parametrization and structure used. Note that the global energy scales agree for all potentials except \( B' \). Only for the rescaled ensembles \( B' \) and \( P' \) is it higher, increasing the spread of computed affinities.

The shown linear correlation coefficients vary between –0.52 and 0.64. They measure quality of a linear regression of the points with arbitrary slope. Although a negative correlation does identify bad correspondence, the correlation coefficients are clearly insufficient as indicators of fit quality. For example, \( B' \) has higher correlation than \( B \) but is far off the correct energy scale. Interestingly, high correlation coefficients often coincide with large absolute errors. Indeed, our model is a line of slope one. The shown RMSD from this model together with the linear correlation indicate clearly that overall, the combination of the MP potential and the \( O_R 3 \) structure agree best with measured affinities, at RMS error 1.5 \( k_B T \) and correlation 0.47.

When this choice is partially relaxed (Figure 10), one sees that the variation among parametrizations in the best structure (OR3), is greater than that among structures for the MP parametrization (MP), as summarized in Figure 10. A \( \chi^2 \)-test using the respective error bars reveals that the model \( \beta \Delta F = \Delta \log c_{12} \) is compatible with the (OR3) data, while it is rejected for (MP) at a 5% confidence level. This is in accord with the observation that MP together with \( O_R 1 \), 2 give no positive correlation, while \( O_R 3 \) together with \( B, MB, P \) and MP results in acceptable correlation with affinities.

These observations give some hope that the parametrization error (c) is more important than the basic approximations (a) made in the model, and that improvements in the determination of a harmonic base pair potential will eventually lead to quantitative affinity predictions. If we accept the MP potential as a valid representation of solution DNA elasticity based on its small RMS deviation, we can then identify the \( O_R 3 \) structure as the only co-crystal structure that is a good representative
Sequences used in (4) are shown with the experimental log affinity difference $\Delta \log c$. In addition to these, the five highest and lowest affinity random sequences are shown.

Table 1. Computed free energy differences for mutations of the inner four bases of the sequence ACATNNNNATGT

| Rank | $\beta \Delta F$ | $\Delta \log c$ | NNNN | Rank | $\beta \Delta F$ | $\Delta \log c$ | NNNN |
|------|------------------|-----------------|------|------|------------------|-----------------|------|
| 1    | $-1.9$           | 0.9             | AAAA | 39   | $0.9$           | 2.7             | ACGT |
| 2    | $-1.5$           | 1.3             | AAAG | 51   | $1.1$           | 1.1             | GTAC |
| 3    | $-1.4$           | 1.5             | ATAA | 55   | $2.8$           | 0.9             | AGCT |
| 4    | $-1.2$           | 0.3             | TTAA | 75   | $2.2$           | 0.3             | AATT |
| 5    | $-1$             | 5.7             | ATAG | 132  | $5.7$           | 5.7             | CATA |
| 8    | $-0.5$           | $-0.5$          | AATT | 133  | $6.2$           | 6.2             | TGCA |
| 17   | $0.0$            | 6.8             | ATAT | 134  | $6.8$           | 6.8             | CACA |
| 21   | $0.1$            | 7.0             | CTAG | 135  | $7.0$           | 7.0             | CATC |
| 25   | $0.3$            | 8.6             | GTAT | 136  | $8.6$           | 8.6             | CATG |
| 37   | $0.9$            | 1.4             | AGAT |       |                  |                 |      |

Obviously, the success of our approach depends on the applicability of the model used to describe DNA elasticity as well as on the quality of the parametrization. Here we have chosen a description on the rigid-base pair level, as a sensible compromise between computationally much more expensive all-atom models and rigid rod representations. We have combined state–of–the–art parametrizations from MD simulation and from structural data analysis, using a new, microscopic method of adapting the effective temperature scale. The resulting error bars allow an estimation of the effect of parametrization uncertainty. Qualitative observations appear quite robust with respect to the parametrization uncertainty. Examples are the location of indirect readout sites, the relative importance of structure and elasticity for specificity, or the distinction of contributions from different elastic degrees of freedom. Quantitative predictions for relative binding affinities depend more sensitively on the choice of parametrization. In the case of the 434 repressor, results averaged over the available elastic potentials and structural templates are compatible with measured binding affinities, but the margins of error are too wide to allow quantitative predictions. Closer inspection shows that our MP hybrid potential performs significantly better than alternative parameterizations. These observations underscore the importance of ongoing efforts to improve DNA elastic potentials (26), and suggest the quantitative prediction of locating elastically optimized subsequences in protein–DNA co-crystals. They are linked to experimentally measurable relative binding affinities of operators mutated at these sites. In particular, we propose the similarity $i, i+k|P_{i, i+k}(\sigma)$ of the length $k$ native subsequence to the corresponding elastic consensus subsequence as a non-additive local marker for indirect readout. Unlike a $Z$-score, this marker can be computed with little numerical effort for arbitrary lengths of the total binding site, and has a direct probabilistic interpretation.

SUMMARY AND CONCLUSION

We have developed a theoretical framework for modeling indirect readout based on appropriate elastic free energies. The resulting markers detect sites of dominant indirect readout by
indirect readout-mediated relative affinities as an efficient way to benchmark them.

For our test case, the 434 repressor complex, the detailed analysis of the elastic energy (Figure 2) and specificity (Figure 8) profiles reveals differences between the co-crystal structures of the three operator sequences $O_{91}, O_{2}, O_{3}$. However, in all three cases we find that agreement between the native and the elastic consensus sequence is confined to the central, not directly contacted part of the operator. On a qualitative level, this supports our working hypothesis that strong elastic optimization in protein–DNA co-crystals is an indicator for dominant indirect readout in real protein–DNA solution complexes. Our results suggest that twist (7) alone cannot account for specificity of the 434 repressor. Rather, the effect seems to be due to a coupling of bend, twist, and shear. Furthermore, we find in our relatively weakly distorted example that sequence dependent structure plays a larger role for the tuning of binding affinities than sequence dependent elasticity (Figure 7). Finally, the comparison of predicted and measured relative binding affinities identifies the $O_{93}$ structure as the best available structural template for the solution complexes of 434 repressor.

While the computational cost of the present analysis is negligible, we believe that DNA deformation (free) energies in protein–DNA co-crystals substantially extend the insights that can be gained from structural data. To encourage the application to other systems, we have included the required Mathematica (33) scripts as Supplementary Data.

SUPPLEMENTARY DATA
Supplementary Data are available at NAR online.

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