Valuation of the Energy Performance of a Greenhouse with an Electric Heater Using Numerical Simulations

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Abstract: In Mexico, there are regions where the temperature drops below the minimum threshold for tomato cultivation (10 °C), requiring the implementation of auxiliary equipment to heat greenhouse air. The objective of this work was to estimate the energy consumption necessary to maintain climate requirements of a greenhouse located in Texcoco, State of Mexico, by using a model of energy balance implemented on Computational Fluid Dynamics (CFD) simulations. The temperature prediction relied on a numerical model based on CFD, proposing a benchmarking on the position and direction of the heater to estimate its effect on the thermal distribution. Results indicated that heater operation on January 2019, a power of 85.56 kW was needed to keep the greenhouse at 12 °C. Also, simulations indicated that electric heater used was not enough to get a homogeneous temperature inside the greenhouse. To achieve well-distributed thermal conditions, it was necessary to consider both the direction and position of heaters. Consequently, airflow direction became more important than height of the heater in order to homogenize the greenhouse area, given that the thermal gradient was reduced due to reverse heat flows.

Keywords: energy engineering; thermal stratification; crop requirements; Computational Fluid Dynamics (CFD)

1. Introduction

Plant growth greatly depends on the temperature and humidity. For winter production in Central Mexico, greenhouses provide better environmental conditions for plant growth compared to most agricultural production systems. Given that a greenhouse is a structure favoring environment for crop production, there are consequences such as heat excess during the day is absorbed by the ground and during the night it is used to meet the heating needs in enclosed greenhouses [1]. In this way, one of the characteristics of enclosed greenhouses is that they are energy saving compared to greenhouses fully relying on natural ventilation. However, accumulation of energy during the day may become insufficient [2] with higher frequency during the winter. Therefore, night temperature becomes a critical factor in the efficiency of a crop cultivated in a greenhouse. Adequate greenhouse energy management can serve to avoid low night temperatures and reduce condensation phenomena causing dripping process on crops [3–6].

A conventional solution for low-temperature problems is using heating systems inside the greenhouse. Since energy and fuel prices are not cheap [7], their efficient use directly impacts production costs and should be balanced with the risks of crop loss [8,9]. Nonetheless, the amount of heat added to the greenhouse depends on the changing weather conditions, where winter becomes the
critical period [10]. Previous research [10,11] have stated that more attention should be given to the night due to significant heat losses, which should be compensated by means of an artificial heat input. In addition to conventional heating systems (fossil fuels), there are alternative systems used to heat the interiors of greenhouses, among which are renewable energy source systems. These systems allow the use of biomass, solar, and geothermal energy sources [12–17], with solar energy being the most recommendable, given that it is a clean, abundant, and safe source. One of the greenhouse heating systems that uses solar energy as a main source and that has been studied by many researchers is rock bed storage. This type of system uses underground rocks to store heat during the day and release it at night, generating an increase in air temperature of up to 3 °C, causing improvement of fruit quality by up to 29% [18,19].

In some greenhouse production systems, the energy consumption represents more than 50% of the total cost of production, and it is necessary to calculate its consumption. The more accurate approach is employing mathematical models based on the principle of heat and mass conservation in order to estimate the feasibility of the implementation of control systems during the winter. Numerical models are also used to improve the understanding of convective, radioactive, and conductive phenomena and the environment-plant iteration within the greenhouse [20–23]. These findings have allowed us to deepen our understanding of the dynamics of the microclimate and the energy needed to maintain environmental comfort, achieve a high-performance production, and improve the quality and efficiency of heating systems [24–26].

Modeling by means of Computational Fluid Dynamics (CFD) has achieved an approach to simulate air movement and temperature variation within the greenhouse and the impact of heating systems on the thermal gradient [27–32]. Along with this, it has allowed us to refine sub-systems of the greenhouse such as the heating system to increase its effectiveness and efficiency. Some studies carried out in CFD have allowed us to establish that, by using heating pipes, it was possible to increase the temperature inside the greenhouse by up to 4.5 °C [11]. In 2018, Yilmaz and Selbas [33] investigated the thermal performance of a solar collector, a heat pump, and a boiler for heating a greenhouse. The results showed that the solar collector had a greater impact on the thermal gradient of the greenhouse, with a thermal efficiency of 33.11%. Another work in 2017, Tadj et al. [27] demonstrated that perforated polyethylene duct heating systems generated a uniform temperature compared to other heating systems (hot water pipes and air heaters). These results agreed with what was established in the literature, in which the temperature distribution was more homogeneous in a vertical plane than in a horizontal plane [34].

In regions with mild winters and at specific periods of the year, an emergent heating system is being needed to mitigate occasional frosts. In central Mexico, it is common to place pop-up heaters aiding to stabilize the internal temperature when the outside temperature drops abruptly in specific hours before sunrise. Even though empirical experience has been gained, there is still scarce research about optimal use of electrical heating systems. For instance, recommendations about the position and direction of heaters to optimize amounts of heat that guarantees thermal homogeneity during these critical periods. Nor it is found related research on the energy and economic costs of this emerging heating system.

Then, the aim of this work was to estimate the necessary energy consumption to maintain thermal homogeneity using an electric heater in the greenhouse under winter conditions in central Mexico, using a model of energy balance and CFD to predict the thermal distribution under different heating scenarios.

2. Materials and Methods

2.1. Experimental Ground Description

The site of the experimental greenhouse was located at Campus Graduate College in the State of Mexico (19°27′45.5" N, 98°54′12.2" W) at 2239 masl, situated on flat ground with no structures around
it. In the region, the minimum monthly temperatures range between 2.49 °C and 11.24 °C throughout the year.

The prototype greenhouse had an area of 1050 m². It was of the zenith type with three spans covered with translucent polyethylene on the floor and sides, polycarbonate on the roof, and anti-insect on the windows. The greenhouse had a natural ventilation system based on the closure and opening of the overhead and front windows and a heating system using an electric heater (CM-VAX, Calelec, Monterrey, Mexico) recommended for enclosed spaces with an area of 96 m². The electric heater was located 3 m above the ground level in span 2 in the windward zone and had a power of 15 kW. Its electrical characteristics were 230/3/60 (Volts/Phases/Cycles), and it had an axial fan with a motor of 1/8 HP that worked with 120 V.

For data acquisition, an Eddy Covariance system 2.4 m away from the windward position with a sonic anemometer (CSAT 3D, Campbell Scientific Ltd., Antony, France), an EC150 gas analyzer (Campbell Scientific Inc., Logan, UT, USA), a temperature and humidity sensor (HMP155A, Campbell Scientific Logan, UT, USA) and four sensors for soil temperature (TCav thermocouple Campbell Scientific Logan, UT, USA) which were placed inside the greenhouse. Seven temperature sensors (DS18B20, Maxim Integrated, San Jose, CA, USA) and three relative humidity sensors (DHT22, Zhengxinyuan Electronics Co., Ltd., Shenzhen, China) were distributed in the three spans at a height of 3 m (Figure 1).

Data recording and storage were performed every 5 s for the temperature and humidity and every 100 ms for the anemometer. The monitoring period was from February 3 to February 24, 2019, which was enough time to investigate the emergent heater, since the meteorological data recorded minimum temperatures during this month of below 12 °C. The data was stored with a data logger system (CR3000 Micrologger, Campbell Scientific, Inc., Logan, UT, USA) for the Eddy Covariance system and an Arduino data Logger Shield for the DS18B20 and DHT22 sensors. Outside the greenhouse, a weather station (Vantage Pro2 Plus, Davis Instruments, Hayward, CA, USA) was available and used to record data on temperature, humidity, wind direction, and wind speed—these values were used as the initial boundary condition of the computer model. All data was processed in Microsoft Excel to determine the environmental input conditions of the computational model.
2.2. Heat Calculation

The greenhouse temperature model was developed based on the energy and mass balances [24,25,35,36] in the completely closed greenhouse without environment-plant iteration, because at the time of data recording there was no crop. The calculation of $Q_h$ was estimated by establishing the necessary energy consumption transferred by the electric heater to attenuate the thermal gradient, expressed as follows:

$$Q_h = Q_i + Q_l + Q_s - Q_l \quad (W).$$

The thermal radiation transferred from the inside to the outside of the greenhouse ($Q_l$) depended on the emission of energy into the atmosphere and on the roofing materials.

$$Q_l = S_{sc} \cdot \sigma \cdot \varepsilon \cdot \text{atm} \left( \varepsilon \cdot T_{atm}^4 - \varepsilon \cdot T_e^4 \right) \quad (W),$$

where $S_{sc}$ is the floor area covered (m$^2$), $\sigma$ is the Stefan–Boltzmann constant (W m$^{-2}$ K$^{-4}$), $\varepsilon$ is the transmittance coefficient of the cover material for thermal radiation, $\varepsilon_{atm}$ is the emissivity of the atmosphere, $T_{atm}$ is the temperature of the emission of energy to the atmosphere (K), $\varepsilon_{ter}$ is the emissivity of the roofing material for thermal radiation, and $T_e$ is the absolute temperature of the roof (K).

The heat transfer by conduction and convection ($Q_t$) was estimated by the temperature between the inside and outside of the greenhouse.

$$Q_t = S_{dc} \cdot K_{cc} (t_i - t_e) \quad (W),$$

where $S_{dc}$ is the developed area of the greenhouse cover (m$^2$), $t_i$ is the interior temperature of the greenhouse (K), $t_e$ is the exterior temperature of the greenhouse (K), and $K_{cc}$ is the overall coefficient of heat loss by conduction and convection (W m$^{-2}$ K$^{-1}$).

The sensitive and latent heat lost by the renewal of indoor air ($Q_l$) was considered minimal when establishing as an initial condition the closing of the side and overhead windows. However, there is air infiltration through the structure as it is an old construction becoming a partially airtight greenhouse.

$$Q_i = V_{gh} \cdot \frac{R}{3600} \rho \left[ c_{pv} \cdot (t_i - t_e) + \lambda_{0r} \cdot (x_i - x_e) + c_{pv} \cdot (x_i - x_e) \cdot t_e \right] \quad (W),$$

where $V_{gh}$ is the volume of the greenhouse (m$^3$), $c_{pv}$ is the specific heat of the air (J kg$^{-1}$ K$^{-1}$), $\rho$ is the density of the air (kg m$^{-3}$), $c_{pv}$ is the specific heat of the superheated steam (J kg$^{-1}$ K$^{-1}$), $x_i$, $x_e$ is the absolute indoor and outdoor humidity (kg kg$^{-1}$), $\lambda_0$ is the latent heat of vaporization (J kg$^{-1}$), and $R$ is the air renewal rate (h$^{-1}$).

The heat transfer through the ground ($Q_s$) is a function of the difference in the indoor and soil temperature.

$$Q_s = K_{sc} \cdot S_{sc} \cdot \frac{(t_i - t_s)}{p} \quad (W),$$

where $K_{sc}$ is the coefficient of thermal exchange through the soil (W m$^{-1}$ K$^{-1}$), $t_s$ is the soil temperature (K), and $p$ is the depth at which the temperature is estimated (m).

The parameters of the energy balance model were analyzed considering the effect of the greenhouse environment, its characteristics, and the roof materials (Tables 1 and 2).

The heat calculation was made using the average weather condition rates of minimum daily temperature. Inside temperature of the greenhouse was established as 12 °C based on the thermal requirement of the tomato (Solanum Lycopersicum L.), which, for proper growth, the temperature should be higher than 10 °C at night [40,41].
Table 1. Variables for the heat calculation obtained from the literature.

| Symbol | Variable                                | Value       | Unit            | Source |
|--------|-----------------------------------------|-------------|-----------------|--------|
| $\sigma$ | Stefan–Boltzmann constant               | $5.67 \times 10^{-0.8}$ | W m$^{-2}$ K$^{-4}$ | [37]  |
| $\alpha$ | Polycarbonate absorbency                | 0.09        |                 |        |
| $\tau_{\text{ter}}$ | Transmittance coefficient of the polycarbonate | 0.025      |                 | [37,38] |
| $\varepsilon_{\text{ter}}$ | Polycarbonate emissivity             | 0.935       |                 | [37,38] |
| $C_{pa}$  | Specific heat of the air                | 1008        | J kg$^{-1}$ K$^{-1}$ | [24,25] |
| $R$     | Air renewal rate                        | 4           | h$^{-1}$        | [39]   |

Table 2. Characteristics of the greenhouse and its components.

| Symbol | Variable                          | Value   | Unit   |
|--------|-----------------------------------|---------|--------|
| $S_{dc}$ | The developed area of the greenhouse cover | 1113    | m$^2$   |
| $S_{sc}$ | Floor area covered               | 1050    | m$^2$   |
| $\varepsilon_{1}$ | Polycarbonate thickness         | 0.06    | m      |
| $\varepsilon_{2}$ | Polyethylene thickness          | 0.000018 | m      |
| $V_{gh}$  | Greenhouse volume                 | 4,068,076 | m$^3$ |

2.3. Computational Model

Building and simulation of the computational model was carried out in ANSYS® Fluent® (ANSYS, Inc., Canonsburg, PA, USA). The geometry was developed in the design modeler tool. The meshing was done in meshing, and the greenhouse had dimensions of $30 \times 35 \times 5$ m, with 490,000 average structured elements, an orthogonal quality of 0.98, and a distortion of $1.935 \times 10^{-0.02}$.

Model conditions and variables applied to the airflow to solve the transport equations, which were discretized into algebraic equations and calculated by numerical methods, were defined in Table 3.

Table 3. Boundary conditions of the computational model.

| Boundary Condition                          | Method                  |
|---------------------------------------------|-------------------------|
| Solver                                      | Pressure-based          |
| State                                       | Steady                  |
| Viscosity function                          | k-\varepsilon Estándar |
| Energy equation                             | Activated               |
| Entry                                       | Velocity inlet          |
| Output                                      | Pressure outlet          |
| Air temperature                             | Constant (12.73 °C)     |
| Wind speed                                  | Constant (0.513 m s$^{-1}$) |
| Heat source                                 | Boussinesq's hypothesis |
| Soil thermal condition                      | Temperature (4.7 °C)    |
| Walls and greenhouse padding (Polyethylene PE) | Wall ($\rho:925.5$, $C_p:1900$, $\lambda:0.3$) |
| Ceiling (Polycarbonate PC)                  | Wall ($\rho:1200$, $C_p:1200$, $\lambda:0.19$) |

Heater simulation included a pressure jump and angular velocity. The pressure jump calculation was estimated considering Equation (6):

$$\Delta p = \frac{1}{2} \rho_{\text{air}} v^2 \ (\text{Pa}),$$

where $\rho_{\text{air}}$ is the air density (kg m$^{-3}$) and $v$ is the fan speed (m s$^{-1}$).

Evaluation of the Computational Models

In order to obtain a reliable computational model, two scenarios were assessed: (I) no heat and (II) with heat. The evaluation was carried out by a statistical analysis of both temperature and wind speed.
using simulated and experimental data. The statistic studios were made by an analysis of variance (ANOVA), with a significance level of 0.05 used to contrast the difference of the variables in the different factors parametrically.

2.4. Simulation Scenarios

The analysis of the distribution of heat flow in the greenhouse was performed by comparing the effect of the position and direction of the heaters; two more heaters were included in the computational model, seeking to improve the system with a uniform temperature (Table 4). Simulations were carried out in a stationary state, and the provided energy was modified by the heater based on the assessed computational model’s results. The origin of the coordinates (x, y, z) is in the center of the greenhouse, and the flow direction of the evaluated heater is z.

| Sceneries | Heaters | Ubication in Greenhouse (Local Coordinates) | Heater Flow Direction |
|-----------|---------|---------------------------------------------|----------------------|
| a         | 0       | Span 2 (X: 0 m, Y: 3 m, Z: −16.5 m)         | Z                    |
| b         | 1       | Span 2 (X: 0 m, Y: 0.5 m, Z: −16.5 m)       | Z                    |
| c         | 1       | Span 1 (X: −10 m, Y: 3 m, Z: −16.5 m)       | Z                    |
| d         | 3       | Span 2 (X: 0 m, Y: 3 m, Z: −16.5 m)         | Z                    |
|           |         | Span 3 (X: 10 m, Y: 3 m, Z: −16.5 m)         | Z                    |
| e         | 3       | Span 1 (X: −10 m, Y: 0.5 m, Z: −16.5 m)      | Z                    |
| f         | 3       | Span 2 (X: 0 m, Y: 3 m, Z: 16.5 m)           | −Z                   |
| g         | 3       | Span 1 (X: −10 m, Y: 0.5 m, Z: −16.5 m)      | Z                    |

3. Results and Discussion

3.1. Energy Consumption

Figure 2 shows the estimation of the necessary heating days and their average power requirement. For their calculation, the results obtained from Equation (1) were used, considering that power requirement is required on days with a temperature below 12 °C inside the greenhouse. The monthly power requirement is the arithmetic average of the air conditioning calculation of the days with heating needs during the year.

Results from Figure 2 show that, during certain hours at night, it is necessary to heat the greenhouse’s air for 206 days. January was the month with the highest energy requirement, needing an implementation of five more heaters with the same conditions to cover the energy needs and maintain a 12 °C temperature. This means that for thermal comfort in the microclimate of the greenhouse, a device providing 85.56 kW is required.

In Figure 3, a comparison was made between the average minimum monthly temperature in the study area and the energy required to maintain the greenhouse at 12 °C (Equation (1)). The calculation of the monthly energy requirement was carried out by assuming that the period in which the temperature falls below 12 °C during the days with heating needs occurs for an average of three hours per day. The peak of the needs was produced in January and is 13.94% higher than the one in December. During the period from June to September, there is no energetic demand. To cover the annual demand, 32,228.76 kWh is necessary, which represents a cost of MX $20,626.40 (US $540.0) according to the nine tariff charges applied to the agriculture in Mexico.
3.2. Mesh Sensitivity Analysis of the Computational Model

A sensibility mesh analysis was carried out in the greenhouse by 100 temperature measurements in a location 2 m above the ground. Four scenarios were performed by modifying the number of elements of the inside mesh of the greenhouse. The results showed that there is no meaningful difference between the simulated temperature results with a 490,000 average element mesh.

3.2.1. Validation

The evaluation of the computational model with and without heating was carried out statistically by correlating the values of temperature and wind speed simulated and recorded by the sensors during the nights of February 6th and 7th, 2019, respectively. In Table 5, it can be observed that the recorded and simulated temperature values were approximate. To measure this correlation, the statistical method ANOVA with a significance level of 0.05 was used, considering that if the F statistic test was less than the F critical value (F test statistic < F critical value), there was no significant difference between the measured and simulated variables (Table 6), so the evaluated model can be used in simulations.
### Table 5. Temperature data (°C) of the evaluated models.

| Sensor | Model without Heating | Heated Model |
|--------|-----------------------|--------------|
|        | Sensor Experimental | Simulated    | Sensor Experimental | Simulated    |
| T1     | 11.28                 | 11.42        | T1                 | 10.96        | 11.03        |
| T2     | 10.28                 | 11.43        | T2                 | 10.43        | 11.05        |
| T3     | 10.95                 | 11.3         | T3                 | 10.94        | 11.06        |
| T4     | 10.93                 | 11.33        | T4                 | 10.79        | 10.89        |
| T5     | 11.52                 | 11.31        | T5                 | 10.93        | 10.86        |
| T6     | 11.5                  | 11.4         | T6                 | 10.86        | 10.82        |
| T7     | 11.31                 | 11.29        | T7                 | 11.07        | 10.82        |
| Eddy   | 11.76                 | 11.85        | Eddy               | 11.08        | 10.91        |

### Table 6. Comparison between the F test statistic (ANOVA) and its critical value.

|                     | With Heating | Without Heating |
|---------------------|--------------|-----------------|
| Temperature         | 0.3 < 4.6    | 1.62 < 4.6      |
| Wind speed          | 0.005 < 7.7  | 3.25 < 7.7      |

#### 3.2.2. Environmental Analysis of the Assessed Model

An empty greenhouse was validated to give stability to the variables being analyzed. Once the model was validated, the crop could be modeled, since its thermal and relative humidity requirements were known. In some cases, tomato crop could be modeled as a source or sink of momentum, energy, and mass. The heatless model presented a thermic homogenization at 2 m high inside the three spans of the greenhouse. The speed was not superior to 0.018 m s\(^{-1}\), and the number of Rayleigh (Ra) varied around 2.8 \(\times\) 10\(^8\) for the three greenhouse’s spans, with a laminar flow induced by floating forces.

The computational model with heating shows that for span 2, there was an increase in the speed of wind generated by the fan (Figure 4). This rise in speed caused a low on span 2 near the windward. However, in the center of span 2, there was a rise of nearly 0.15 °C derived from the energy supply on the part of the heater.

![Figure 4. Temperature distribution (°C) and wind speed (m s\(^{-1}\)) to 2 m high.](image-url)
On spans 1 and 3 of the model with heat prevailed the laminar flows induced by floating forces with Ra numbers between $4.09 \times 10^8$ and $5.98 \times 10^8$. On span 2 near the fan, the thermic distribution was in accordance with the speed and temperature provided by the heater, causing a transition zone in a turbulent flow ($10 \times 10^8$ to $10 \times 10^10$) with Ra values of $2.42 \times 10^9$.

These simulations presented a thermal behavior similar to the one obtained by Chen et al. [24], when greenhouses subjected to non-heating, laminar flows induced by prevailing buoyancy forces. And in greenhouses with heating, there was a turbulent flow transition.

### 3.3. Thermal Spatial Distribution of Simulated Scenarios

Figure 5 shows a top view of the temperatures at 2 m from the ground in the simulated scenarios with initial data from the computational model with and without heating. The results from the simulations present an increase in temperature of 0.8 °C between scenarios a and b, and an increase of 2 °C between scenarios a, d, and e.

![Figure 5](image_url)

**Figure 5.** Distribution of temperature (K) at 2 m above the ground in the greenhouse under the initial conditions of the heating computational model in the (a–g) sceneries of simulation.

Given that the maximum thermal gradient was 0.2 °C when the heater height was modified (Figure 5b–g), it was determined that if the direction of heat flow was the same, the height has no significant effect on the temperature’s distribution at 2 m from the ground under the original conditions of the heater. Unless the heat flow direction was changed (scenarios f and g), in this case, the homogeneity
improved and the buoyancy forces had crucial importance in the heat distribution. The results of the simulations matched those presented in the works of Tadj et al. and Dhiman et al. [27,34], where the air heating was not the most efficient way in which to homogenize the greenhouse’s temperature on a horizontal level.

To review the results of Figure 5 and analyze the temperature behavior at 2 m from the ground and its influence on the height and direction of the flow of the heater under different energy supplies, four scenarios were performed (d, e, f, and g) considering a constant supply of air with a temperature of 30 °C by the heater.

Figure 6 shows the relationship of the longitudinal temperature at 2 m high off the ground in span 2 between scenarios d and e (Δ), with a constant temperature supply of 30 °C. The figure shows that if the direction of heat flow remained constant, there was no significant difference in the temperature at 2 m from the ground ($R^2 = 0.996$) between the heater at 0.5 and 3 m. However, this heater position was not adequate to homogenize the vertical temperatures longitudinally 2 m from the ground, since, as the energy provided by the heater increases, the thermal gradient was more significant between the area near the heater and its opposite side. Scenarios d and f (o) showed that in span 2, the direction of heat flow had a more significant impact on the distribution of horizontal temperatures at 2 m high, improving the homogenization and reducing the thermal gradient when mixed heat fluxes are present (scenario f).

Through the simulation results of this work, it was possible to assume that the direction of heat flow had a significant impact on thermal homogenization (scenarios d and g), reaffirming the work of Constantinos et al. [27], where the distribution of heat flow was caused by the position of the heating systems and the effect of floating forces created by the thermal gradient between the greenhouse temperature and the energy supplied by the heating system.

When selecting the location of the heater, it was necessary to take into account that the temperature was higher in the area near the heater, as shown in Figure 7. Therefore, to avoid crop damage, the heater must be installed at a height higher than the current crop. In the case of tomatoes, the recommended height was 3 m.
Figure 6. Temperature relationship (°C) at a 2 m height in span 2 of the greenhouse with 30 °C constant heating for 4 scenarios: d and e (∆) and d and f (o).

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When selecting the location of the heater, it was necessary to take into account that the temperature was higher in the area near the heater, as shown in Figure 7. Therefore, to avoid crop damage, the heater must be installed at a height higher than the current crop. In the case of tomatoes, the recommended height was 3 m.

Figure 7. Distribution of temperatures (°C) at 0.7 m high in span 1 of the greenhouse for scenarios f (°) and g (▲), with a 30 °C constant temperature supplied by the heater.

The power supplied by the greenhouse heater used in this research was insufficient to mitigate the temperature drop that occurs mainly during the winter period. In addition to the power, it was necessary to consider the distribution of electric heaters, since this type of system, compared to heating systems using pipe networks [34,42,43], was not the best option for homogenizing the temperature in the greenhouse. Currently, there are many techniques used to heat the air in the greenhouse [10,27,44]. However, due to the high investment cost of these systems, they sometimes become unfeasible.

4. Conclusions

During the winter in Central Mexico (December 21 to March 21), energy consumption is around 63% of the total for the year to maintain a temperature of up to 12 °C in the greenhouse during the night period. Such climatic conditions cause an approximate cost of MX $12,949.7 (US $540), according to the agricultural tariff in Mexico. Thermal distribution occurs in accordance with the speed and temperature provided by the heater, causing a zone with a turbulent flow and a difference in density between the air near the heater and the rest area of the greenhouse. Thermal homogenization in the greenhouse occurs when there are conditions for opposite heat flows (recirculation), causing an improvement in the greenhouse environment by the distribution of the heaters and reducing the temperature gradient between the area near the heater and its opposite side. This type of heater system, known as aerial, is not ideal for homogenizing the temperature of the greenhouse due to the effect of the buoyancy forces which can be overcome by adding fans at stagnant zones and aid to distribute the heat at all zones of the greenhouse.

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