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Collection Analysis for Horn Clause Programs

[Extended Abstract]

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Abstract

We consider approximating data structures with collections of the items that they contain. For examples, lists, binary trees, tuples, etc, can be approximated by sets or multisets of the items within them. Such approximations can be used to provide partial correctness properties of logic programs. For example, one might wish to specify that whenever the atom sort(t, s) is proved then the two lists t and s contain the same multiset of items (that is, s is a permutation of t). If sorting removes duplicates, then one would like to infer that the sets of items underlying t and s are the same. Such results could be useful to have if they can be determined statically and automatically. We present a scheme by which such collection analysis can be structured and automated. Central to this scheme is the use of linear logic as a computational logic underlying the logic of Horn clauses.

Categories and Subject Descriptors F.4.1 [Mathematical Logic]: Computational logic; I.2.3 [Deduction and Theorem Proving]: Logic programming

General Terms Design, Theory, Verification

Keywords proof search, static analysis, Horn clauses, linear logic

1. Introduction

Static analysis of logic programs can provide useful information for programmers and compilers. Typing systems, such as in λProlog [2, 24], have proved valuable during the development of code: type errors often represent program errors that are caught at compile time when they are easier to find and fix than at runtime when they are much harder to repair. Static type information also provides valuable documentation of code since it provides a concise approximation to what the code does.

In this paper we describe a method by which it is possible to infer that certain relationships concerning collections underlying structured data hold. We shall focus on relations that are also decidable and can be done during compile time analysis of logic programs. We shall use multisets and sets to approximate more complicated structures as lists and binary trees. Consider, for example, a list sorting program that maintains duplicates of elements. Part of the correctness of a sort program includes the fact that if the atomic formula sort(t, s) is provable, then s is a permutation of t that is in order. The proof of such a property is likely to involve inductive arguments requiring the invention of invariants: in other words, this is not likely to be a property that can be inferred statically during compile time. On the other hand, if the lists t and s are approximated by multisets (that is, if we forget the order of items in lists), then it might be possible to establish that if the atomic formula sort(t, s) is provable, then the multiset associated to s is equal to the multiset associated to t. If that is so, then it is immediate that the lists t and s are, in fact, permutations of one another (in other words, no elements were dropped, duplicated, or created during sorting). As we shall see, such properties based on using multisets to approximate lists can often be done statically.

This paper considers exclusively the static analysis of first-order Horn clauses but it does so by making substitution instances of such Horn clauses that carry them into linear logic. Proofs for the resulting linear logic formulas are then attempted as part of static analysis.

2. The undercurrents

There are various themes that underlie our approach to inferring properties of Horn clause programs. We list them explicitly below. The rest of the paper can be seen as a particular example of how these themes can be developed.

2.1 If typing is important, why use only one?

Types and other static properties of programming languages have proved important on a number of levels. Typing can be useful for programmers: they can offer important invariants and document for code. Static analysis can also be used by compilers to uncover useful structures that allow compilers to make choices that can improve execution. While compilers might make use of multiple static analysis regimes, programmers do not usually have convenient access to multiple static analyzes for the code that they are composing. Sometimes, a programming language provides no static analysis, as is the case with Lisp and Prolog. Other programming languages offer exactly one typing discipline, such as the polymorphic typing disciplines of Standard ML and λProlog (SML also statically determines if a given function defined over concrete data structures cover all possible input values). It seems clear, however, that such analysis of code, if it can be done quickly and incrementally, might have significant benefits for programmers during the process of writing code. For example, a programmer might find it valuable to know that a recursive program that she has just written has linear or quadratic runtime complexity, or that a relation she just specified actually defines a function. The Ciao system preprocessor [4] provides for such functionality by allowing a programmer to write various properties about code that the preprocessor attempts to verify.
Having an open set of properties and analysis tools is an interesting direction for the design of a programming language. The collection analysis we discuss here could be just one such analysis tool.

2.2 Logic programs as untyped \( \lambda \)-expressions

If we do not commit to just one typing discipline, then it seems sensible to use a completely untyped setting for encoding programs and declarations. Given that untyped \( \lambda \)-terms provide for arbitrary applications and arbitrary abstractions, such terms can provide an appealing setting for the encoding of program expressions, type expressions, assertions, invariants, etc. Via the well developed theory of \( \lambda \)-conversion, such abstractions can be instantiated with a variety of other objects. Abstractions can be used to encode quantifiers within formulas as well as binding declarations surrounding entire programs.

In logic programming, proofs can be viewed as computation traces and such proof objects can also be encoded as untyped \( \lambda \)-terms. Instantiations into proofs is also well understood since it is closely related to the elimination of cut in sequent calculus or to normalization in natural deduction proofs. The fact that proofs and programs can be related simply in a setting where substitution into both has well understood properties is certainly one of the strengths of the proof theoretic foundations of logic programming (see, for example, [33]).

2.3 What good are atomic formulas?

In proof theory, there is interesting problem of duality involving atomic formulas. The initial rule and the cut rule given as

\[
\text{Initial Rule:} \quad C \cdot C \rightarrow C \\
\text{Cut:} \quad \Gamma_1 \cdot C, \Delta_1, \Gamma_2, C \cdot \Delta_2 \rightarrow \Gamma_1, \Gamma_2 \cdot \Delta_1, \Delta_2
\]

Can be seen as being dual to each other [13]. In particular, the initial rule states that an occurrence of a formula on the left is stronger than the same occurrence on the right, whereas the cut rule states the dual: an occurrence of a formula on the right is strong enough to remove the same occurrence from the left. In most well designed proof systems, all occurrence of the cut-rule can be eliminated (whether or not \( C \) is an atomic formula) whereas only non-atomic initial rules (where \( C \) is non-atomic) can be eliminated. Atoms seem to spoil the elegant duality of the meta-theory of these inference rules.

While the logic programming world is most comfortable with the existence of atomic formulas, there have been a couple of recent proof theoretic approaches that try to eliminate them entirely. For example, in the work on definitions and fixed points by Schroeder-Heister [24], Girard [11], and McDowell & Miller [13], atoms are defined to be other formulas. In this approach, the only primitive judgment involving terms is that of equality. In that setting, if definitions are stratified (no recursion through negations) and noetherian (no infinite descent in recursion), then all instances of cut and initial can be removed. The setting of ludics of Girard [12] is a more radical presentation of logic in which atomic formulas do not exist: formulas can be probed to arbitrary depth to uncover “subformulas”.

Another approach to atoms is to consider all constants as being variables. On one hand this is a trivial position: if there are no constants (thus, no predicate constants) there are no atomic formulas (which are defined as formulas with non-logical constants at their head). On the other hand, adopting a point-of-view that constants can vary has some appeal. We describe this next.

2.4 Viewing constants and variables as one

The inference rule of \( \forall \)-generalization states that if \( B \) is provable then \( \forall x.B \) is provable (with appropriate provisos if the proof of \( B \) depends on hypotheses). If we are in a first-order logic, then the free first-order variable \( x \) of \( B \) becomes bound in \( \forall x.B \) by this inference rule.

Observe the following two things about this rule. First, if we are in an untyped setting, then we can, in principle, quantify over any variable in any expression, even those that play the role of predicates or functions. Mixing such rich abstractions with logic is well known to be inconsistent so when we propose such rich abstractions in logic, we must accompany it with some discipline (such as typing) that will yield consistency.

Second, we need to observe that differences between constants and variables can be seen as one of “scope”, at least from a syntactic, proof theoretic, and computational point of view. For example, variables are intended as syntactic objects that can “vary”. During the computation of, say, the relation of appending lists, universal quantified variables surrounding Horn clauses change via substitution (via backchaining and unification) but the constructors for the empty and non-empty lists as well as the symbol denoting the append relation do not change and, hence, can be seen as constants. But from a compiling and linking point-of-view, the append predicate might be considered something that varies: if append is in a module of Prolog that is separately compiled, the append symbol might denote a particular object in the compiled code that is later changed when the code is loaded and linked. In a similar fashion, we shall allow ourselves to instantiate constants with expression during static analysis.

Substituting for constants allows us to “split the atom”: that is, by substituting for the predicate \( p \) in the atom \( p(t_1, \ldots, t_n) \), we replace that atom with a formula, which, in this paper, will be a linear logic formula.

2.5 Linear logic underlies computational logic

Linear logic [10] is able to explain the proof theory of usual Horn clause logic programming (and even richer logic programming languages [13]). It is also able to provide means to reason about resources, such as items in multisets and sets. Thus, linear logic will allow us to sit within one declarative framework to describe both usual logic programming as well as “sub-atomic” reasoning about the resources implicit in the arguments of predicates.

3. A primer for linear logic

Linear logic connectives can be divided into the following groups: the multiplicatives \( \otimes, \otimes, \otimes; \) the additives \( \oplus, 0, \& \); the exponentials \( !, ?; \) the implication \( \multimap \) (where \( B \multimap C \) is defined as \( B \otimes \multimap C \)) and \( \Rightarrow \) (where \( B \Rightarrow C \) is defined as \( !B \Rightarrow \multimap C \)), and the quantifiers \( \forall \) and \( \exists \) (higher-order quantification is allowed). The equivalence of formulas in linear logic, \( B \multimap \otimes C \), is defined as the formula \( (B \multimap \otimes C) \otimes (C \multimap B) \).

First-order Horn clauses can be described as formulas of the form

\[ \forall x_1 \ldots \forall x_m [A_1 \land \ldots \land A_n \supset A_0] \quad (m, n \geq 0) \]

where \( \land \) and \( \supset \) are intuitionistic or classical logic conjunction and implication. There are at least two natural mappings of Horn clauses into linear logic. The “multiplicative” mapping uses the \( \otimes \) and \( \multimap \) for the conjunction and implication: this encoding is used in, say, the linear logic programming settings, such as Lolli [13], where Horn clause programming can interact with the surrounding linear aspects of the full programming language. Here, we are not interested in linear logic programming per se but with using linear logic to help establish invariants about Horn clauses when these are interpreted in the usual, classical setting. As a result, we shall encode Horn clauses into linear logic using the conjunction \( \& \) and implication \( \Rightarrow \): that is, we take Horn clauses to be formulas of the
∀x₁...∀xₙ[A₁ & ... & Aₙ ⇒ A₀].  (n, m ≥ 0)

The usual proof search behavior of first-order Horn clauses in classical (and intuitionistic) logic is captured precisely when this style of linear logic encoding is used.

4.  A primer for proof theory

A sequent is a triple of the form Σ; Γ ⊢ Δ were Σ, the signature, is a list of non-logical constants and eigenvariables paired with a simple type, and where both Γ and Δ are multisets of Σ-formulas (i.e., formulas all of whose non-logical symbols are in Σ). The rules for linear logic are the standard ones [[4]], except here signatures have been added to sequents. The rules for quantifier introduction are the only rules that require the signature and they are reproduced here:

\[ \Sigma; y: \tau; B[y/x], \Gamma \vdash \Delta \quad \Sigma; \exists x.B, \Gamma \vdash \Delta \]
\[ \Sigma; t: \tau \quad \Sigma; \Gamma \vdash B[t/x], \Delta \quad \Sigma; \Gamma \vdash \exists x.B, \Delta \]
\[ \Sigma; t; \tau \quad \Sigma; \Gamma; B[t/x] \vdash \Delta \quad \Sigma; \Gamma; \exists x.B, \Delta \]

The premise \( \Sigma; \vdash t; \tau \) is the judgment that the term \( t \) has the (simple) type \( \tau \) given the typing declaration contained in \( \Sigma \).

We now outline three ways to instantiate things within the sequent calculus.

4.1  Substituting for types

Although we think of formulas and proofs as untyped expressions, we shall use simple typing within sequents to control the kind of formulas that are present. A signature is used to bind and declare typing for (eigen)variables and non-logical constants within a sequent. Simple types are, formally speaking, also a simple class of untyped A-terms: the type \( o \) is used to denote formulas (following Church [7]). In a sequent calculus proof, simple type expressions are global and admit no bindings. As a result, it is an easy matter to show that if one takes a proof with a type constant \( \sigma \) and replaces everywhere \( \sigma \) with some type, say, \( \tau \), one gets another valid proof.

We shall do this later when we replace a list by a multiset that approximates it: since we are using linear logic, we shall use formulas to encode multisets and so we shall replace the type constant \( \lambda \)at with \( o \).

4.2  Substituting for non-logical constants

Consider the sequent

\[ \Sigma; p; \tau; D₁, ! D₂, ! \Gamma \vdash p(t₁, ..., tₘ) \]

where the \( \tau \) is a predicate type (that is, it is of the form \( \tau₁ → ... → \tauₙ → o \)) and where \( p \) appears in, say, \( D₁ \) and \( D₂ \) and in no formula of \( \Gamma \). The linear logic exponential ! is used here to encode the fact that the formulas \( D₁ \) and \( D₂ \) are available for arbitrary reuse within a proof (the usual case for program clauses). Using the right introduction rules for implication and the universal quantifier, it follows that the sequent

\[ \Sigma; ! \Gamma \vdash \forall t \{ D₁ \Rightarrow D₂ \Rightarrow p(t₁, ..., tₘ) \} \]

is also provable. Since this is a universal quantifier, there must be proofs for all instances of this quantifier. Let \( \theta \) be the substitution \( \{ p → x₁, ..., xₙ, S \} \), where \( S \) is a term over the signature \( \Sigma \cup \{ x₁, ..., xₙ \} \) of type \( o \). A consequence of the proof theory of linear logic is that there is a proof also of

\[ \Sigma; ! \Gamma \vdash D₁\theta ⇒ D₂\theta ⇒ S[t₁/x₁, ..., tₘ/xₘ] \]

and of the sequent

\[ \Sigma; ! D₁\theta, ! D₂\theta, ! \Gamma \vdash S[t₁/x₁, ..., tₘ/xₘ] \]

As this example illustrates, it is possible to instantiate a predicate (here \( p \)) with an abstraction of a formula (here, \( \lambda x₁...\lambda xₙ.S \)). Such instantiation carries a provable sequent to a provable sequent.

4.3  Substituting for assumptions

An instance of the cut-rule (mentioned earlier) is the following:

\[ \Sigma; ! \Gamma \vdash ! D₁\theta \quad \Sigma; ! \Gamma \vdash ! D₂\theta \]
\[ \Sigma; ! \Gamma \vdash ! D₁\theta, ! D₂\theta \]
\[ \Sigma; ! \Gamma \vdash ! D₁\theta, ! D₂\theta, ! \Gamma \vdash C \]
\[ \Sigma; ! \Gamma \vdash C \]

This inference rule (especially when associated with the cut-elimination procedure) provides a way to merge (substitution) the proof of a formula (here, \( B \)) with a use of that formula as an assumption. For example, consider the following situation. Given the example in the Section 4.2, assume that we can prove

\[ \Sigma; ! \Gamma \vdash ! D₁\theta \quad \Sigma; ! \Gamma \vdash ! D₂\theta \]
\[ \Sigma; ! \Gamma \vdash ! D₁\theta, ! D₂\theta, ! \Gamma \vdash t₁, ..., tₘ \]

to a proof of

\[ \Sigma; ! \Gamma \vdash ! \Gamma \vdash S[t₁/x₁, ..., tₘ/xₘ] \]

We shall see this style of reasoning about proofs several times below. This allows us to "split an atom" \( p(t₁, ..., tₘ) \) into a formula \( S[t₁/x₁, ..., tₘ/xₘ] \) and to transform proofs of the atom into proofs of that formula. In what follows, the formula \( S \) will be a linear logic formula that provides an encoding of some judgment about the data structures encoded in the terms \( t₁, ..., tₘ \).

A few simple examples of using higher-order instantiations of logic programs in order to help reasoning about them appear in [20].

5.  Encoding multisets as formulas

We wish to encode multisets and sets and simple judgments about them (such as inclusion and equality) as linear logic formulas. We consider multisets first. Let token \( \text{item} \) be a linear logic predicate of one argument: the linear logic atomic formula \( \text{item} x \) will denote the multiset containing just the one element \( x \) occurring once. There are two natural encoding of multisets into formulas using this predicate. The \textit{conjunctive} encoding uses \( \bot \) for the empty multiset and \( \odot \) to combine two multisets. For example, the multiset \( \{ 1, 2, 2 \} \) is encoded by the linear logic formula \( \text{item} 1 \odot \text{item} 2 \odot \text{item} 2 \).

Proofs search using this style encoding places multiset on the left of the sequent arrow. This approach is favored when an intuitionistic subset of linear logic is used, such as in Lolli [15], LinearLF [1], and MSR [1]. The dual encoding, the \textit{disjunctive} encoding, uses \( \bot \) for the empty multiset and \( \lor \) to combine two multisets. Proofs search using this style encoding places multisets on the right of the sequent arrow. Multiple conclusion sequents are now required. Systems such as LO [1] and Forum [19] use this style of encoding. If negation is available, then the choice of which encoding one chooses is mostly a matter of style. We pick the disjunctive encoding for the rather shallow reason that the inclusion judgment for multisets and sets is encoded as an implication instead of a reverse implication, as we shall now see.
Let $S$ and $T$ be the two formulæ $s_1 \not\approx \ldots \not\approx s_n$ and $t_1 \not\approx \ldots \not\approx t_m$, respectively $(n, m \geq 0)$. Notice that $\vdash S \not\approx \bigcirc T$ if and only if $\vdash T \not\approx S$ if and only if the two multisets $\{s_1, \ldots, s_n\}$ and $\{t_1, \ldots, t_m\}$ are equal. Consider now, however, the following two ways for encoding the multiset inclusion $S \subseteq T$.

- $S \not\approx 0 \not\approx T$. This formula mixes multiplicative connectives with the additive connective $0$: the latter allows items that are not matched between $S$ and $T$ to be deleted.
- $\exists q(S \not\approx q \not\approx T)$. This formula mixes multiplicative connectives with a higher-order quantifier. While we can consider the instantiation for $q$ to be the multiset difference of $S$ from $T$, there is no easy way in the logic to enforce that interpretation of the quantifier.

As it turns out, these two approaches are equivalent in linear logic: in particular, $\vdash 0 \not\approx \bigcirc \forall p \ldots (\exists q(q \not\approx T))$ and $\vdash \exists q(S \not\approx q \not\approx T)$. Thus, below we can choose either one of these encodings for multiset inclusion.

### 6. Multisets approximations

A *multiset expression* is a formula in linear logic built from the predicate symbol $\exists$ (denoting the singleton multiset), the linear logic multiplicative disjunction $\not\approx$ (for multiset union), and the unit $\bot$ for used (denoted the empty multiset). We shall also allow a predicate variable $\rho$ to range over these two judgments, which are formally binary relations of type $o \not\rightarrow o \not\rightarrow o$. A *multiset statement* is a formula of the form

$$\forall x \exists \overline{s}(F \not\approx Y) \not\approx \exists Y,$$

where the quantified variables $\overline{s}$ are either first-order or of type $\rho$ and formulas $S_0, T_0, \ldots, S_n, T_n$ are possibly open multiset expressions.

If $S$ and $T$ are closed multiset expressions, then we write $\models S \subseteq T$ whenever the multiset (of closed first-order terms) denoted by $S$ is contained in the multiset denoted by $T$, and we write $\models S \subseteq T$ whenever the multisets denoted by $S$ and $T$ are equal.

Similarly, we write $\models S \subseteq T$ whenever the multisets denoted by $S$ and $T$ are equal.

The following Proposition is central to our use of linear logic to establish multiset statements for Horn clause programs.

**Proposition 1.** Let $S_0, T_0, \ldots, S_n, T_n$ $(n \geq 0)$ be multiset expressions all of whose free variables are in the list of variables $x$. For each judgment $s \not\rho t$ we write $s \not\rho t$ to denote $\exists q(s \not\approx q \not\approx t)$ if $\rho$ is $x$ and $t \not\approx s$ if $\rho$ is $\bot$. If $\forall x \exists \overline{s}(F \not\approx Y) \not\approx \exists Y$ is provable in linear logic, then $\models S \subseteq T$.

This Proposition shows that linear logic can be used in a sound way to infer valid multiset statement. On the other hand, the converse (completeness) does not hold: the statement $\forall x \forall y. (x \not\leq y) \ldots (y \not\leq x)$ is valid but its translation into linear logic is not provable.

To illustrate how deduction in linear logic can be used to establish the validity of a multiset statement, consider the first-order Horn clause program in Figure 1. The signature for this collection of clauses can be given as follows:

```
nil  : list
cons : int -> list -> list
append : list -> list -> list -> o
split : int -> list -> list -> list -> o
sort : list -> list -> o
leq : int -> int -> o
gt : int -> int -> o
```

The first two declarations provide constructors for empty and non-empty lists, the next three are predicates whose Horn clause definition is presented in Figure 1 and the last two are order relations that are apparently defined elsewhere.
If we think of lists as collections of items, then we might want to check that the sort program as written does not drop, duplicate, or create any elements. That is, if the atom \( \text{sort}(s,t) \) is provable then the multiset of items in the list denoted by \( s \) is equal to the multiset of items in the list denoted by \( t \). If this property holds then \( t \) and \( s \) are lists that are permutations of one another: of course, this does not say that it is the correct permutation but this more simple fact is one that, as we show, can be inferred automatically.

Computing this property of our example logic programming follows the following three steps.

First, we provide an approximation of lists as being, in fact, multiset: more precisely, as formulas denoting multisets. The first step, therefore, must be to substitute \( \theta \) for \( o \) in the signature above. Now we can interpret the constructors for lists using the substitution

\[
\begin{align*}
nil & \mapsto \bot \quad \text{cons} \mapsto \lambda x \lambda y. \text{item} \ x \ y.
\end{align*}
\]

Under such a mapping, the list \( \text{(cons} \ 1 \ \text{cons} \ 3 \ \text{cons} \ 2 \ \text{nil}) \) is mapped to the multiset expression \( \text{item} \ 1 \ \text{item} \ 3 \ \text{item} \ 2 \ \bot \ \bot \).

Second, we associate with each predicate in Figure 4 a multiset judgment that encodes an invariant concerning the multisets denoted by the predicate’s arguments. For example, if \( \text{append} \ r \ s \ t \) or \( \text{split} \ u \ l \ r \ s \) is provable then the multiset union of the items in \( r \) with those in \( s \) is equal to the multiset of items in \( t \), and if \( \text{sort} \ s \ t \) is provable then the multisets of items in lists \( s \) and \( t \) are equal. This association of multiset judgments to atomic formulas can be achieved formally using the following substitutions for constants:

\[
\begin{align*}
\text{append} & \mapsto \lambda x \lambda y \lambda z. (x \ y) \circ o z \\
\text{split} & \mapsto \lambda u \lambda x \lambda y. (y \ z) \circ o x \\
\text{sort} & \mapsto \lambda x \lambda y. x \circ o y
\end{align*}
\]

The predicates \( \text{leq} \) and \( \text{gr} \) (for the least-than-or-equal-to and greater-than relations) make no statement about collections of items, so that they can be mapped to a trivial tautology via the substitution

\[
\begin{align*}
\text{leq} & \mapsto \lambda x \lambda y. \ 1 \quad \text{gr} \mapsto \lambda x \lambda y. \ 1
\end{align*}
\]

Figure 3 presents the result of applying these mappings to Figure 2. Third, we must now attempt to prove each of the resulting formulas. In the case of Figure 2 all the displayed formulas are trivial theorems of linear logic.

Having taken these three steps, we now claim that we have proved the intended collection judgments associate to each of the logic programming predicates above: in particular, we have now shown that our particular sort program computes a permutation.

7. Formalizing the method

The formal correctness of this three-stage approach is easily justified given the substitution properties we presented in Section 4 for the sequent calculus presentation of linear logic.

Let \( \Gamma \) denote a set of formulas that contains those in Figure 2. Let \( \theta \) denote the substitution described above for the type list, for the constructors \( \text{n1} \) and \( \text{n2} \), and for the predicates in Figure 4. If \( \Sigma \) is the signature for \( \Gamma \) then split \( \Sigma \) into the two signatures \( \Sigma_1 \) and \( \Sigma_2 \) so that \( \Sigma_1 \) is the domain of the substitution \( \theta \) and let \( \Sigma_2 \) be the signature of the range of \( \theta \) (in this case, it just contains the constant \( \text{item} \)). Thus, \( \Gamma' \) is the set of formulas in Figure 2

Assume now that \( \Sigma_1, \Sigma_2; \Gamma' \vdash \text{sort}(t,s) \). Given the discussion in Sections 4.1 and 4.2, we know that

\[
\Sigma_1, \Sigma_2; \Gamma' \vdash \theta \circ o s \theta
\]

is provable. Since the formulas in \( \Gamma' \) are provable, we can use substitution into proofs (Section 4.1) to conclude that \( \Sigma_1, \Sigma_2; \Gamma \vdash \theta \circ o s \theta \). Given Proposition 1, we can conclude that \( \models_m \theta \circ o s \theta \); that is, that \( \theta \) and \( s \theta \) encode the same multiset.

Consider the following model-theoretic argument for establishing similar properties of Horn clauses. Let \( M \) be the Herbrand model that captures the invariants that we have in mind. In particular, \( M \) contains the atoms \( \text{append} \ r \ s \ t \) and \( \text{split} \ u \ l \ r \ s \) if the items in the list \( r \) added to the items in list \( s \) are the same as the items in \( t \). Furthermore, \( M \) contains all closed atoms of the form \( \text{leq} \ t \ s \) and \( \text{gr} \ t \ s \), and closed atoms \( \text{sort} \ s \ t \) where \( s \) and \( t \) are lists that are permutations of one another. One can now show that \( M \) satisfies all the Horn clauses in Figure 2. As a consequence of the soundness of first-order classical logic, any atom provable from the clauses in Figure 2 must be true in \( M \). By construction of \( M \), this means that the desired invariant holds for all atoms proved from the program.

The approach suggested here using linear logic and deduction remains syntactic and proof theoretic: in particular, showing that a model satisfies a Horn clause is replaced by a deduction within linear logic.

8. Sets approximations

It is rather easy to encode sets and the equality and subset judgments on sets into linear logic. In fact, the transition to set from multisets. The first

\[
\begin{align*}
\forall x. \text{(split} \ x \ \text{nil} \ \text{nil}) \\
\forall x,y,z. \text{(split} \ x \ y \ z) \Rightarrow \text{(split} \ x \ y \ z)
\end{align*}
\]
also equivalent to the formula \(?item \, x_1 \oplus \cdots \oplus item \, x_n\). This latter encoding is the one that we shall use for building our encoding of sets.

A set expression is a formula in linear logic built from the predicate symbol \(item\) (denoting the the singleton set), the linear logic additive disjunction \(\oplus\) (for set union), and the unit \(0\) for \(\otimes\) (used to denote the empty set). We shall also allow a predicate variable (a variable of type \(o\)) to be used to denote a (necessarily open) set expression. An example of an open multiset expression is \(item \, f(X) \oplus 0 \oplus Y\), where \(Y\) is a variable of type \(o\), \(X\) is a first-order variable, and \(S\) is some first-order term constructor.

Let \(S\) and \(T\) be two set expressions. The two \(set\, judgments\) that we wish to capture are set inclusion, written as \(S \subseteq T\), and equality, written as \(S \equiv T\). We shall use the syntactic variable \(\rho\) to range over these two judgments, which are formally binary relations of type \(o \to o \to o\). We shall also allow a predicate \(\text{relations}\) of type \(o \to \theta\) to range over these two judgments, which are formally binary clauses for deciding whether or not the "pivot" for the splitting is satisfied.

That figure contains a new definition of splitting that contains three relations of type \(\theta\), which is used to denote a (necessarily open) set expression. An example of an open multiset expression is \(item \, f(X) \oplus 0 \oplus Y\), where \(Y\) is a variable of type \(o\), \(X\) is a first-order variable, and \(S\) is some first-order term constructor.

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the endsequent is \( \Gamma; S \vdash T \) then all sequents in the proof have the form \( \Gamma; S \vdash T \) for some \( S \). Thus, the search for a proof either succeeds (proof search ends by placing \( \top \) on top), or fails to find a proof, or it cycles, a case we can always detect since there is only a finite number of atomic formulas that can be \( S \).

The proof system in Figure 6 can be used to characterize the structure of proofs of the linear logic encoding of multiset statements. Let

\[
\forall \exists [S_1 \rho_1 T_1 \& \ldots \& S_n \rho_n T_n \Rightarrow S_0 \rho_0 T_0]
\]

be the translation of a multiset statement into linear logic. Provability of this formula can be reduced to attempting to prove \( S_0 \rho_0 T_0 \) from assumptions of the form

\[
(A_1 \& \ldots \& A_m) \Rightarrow (B_1 \& \ldots \& B_m),
\]

where \( A_1, \ldots, A_m, B_1, \ldots, B_m \) are atomic formulas. Such formulas can be called multiset rewriting clauses since backchaining on such clauses amounts to rewriting the right-hand-side multiset of a sequent (see rule BC in Figure 6). Such rewriting clauses are particularly simple since they do not involve quantification.

**Proposition 4.** Let \( S_0 \) and \( T_0 \) be multiset expressions all of whose free variables are in the list of variables \( x \) and let \( \Gamma \) be a set of multiset rewriting rules. The formula \( S_0 \Rightarrow T_0 \) is a linear logic consequence of \( \Gamma \) if and only if the sequent \( \Gamma; S_0 \vdash T_0 \) is provable using the inference rules in Figure 6.

**Proof** The soundness part of this proposition ("if") is easy to show. Completeness ("only if") is proved elsewhere, for example, in [13], Proposition 2. It is also an easy consequence of the completeness of focused proofs in [13] to fix the polarity to all atomic formulas to be positive.

Notice that the proofs using the rules in Figure 6 are straight line proofs (no branching) and that they are top-down (or goal-directed). Given these observation, it follows that determining if \( S_0 \Rightarrow T_0 \) is provable from a set of multiset rewriting clauses is decidable, since this problem is contained within the reachability problem of Petri Nets [13]. Proving a multiset inclusion judgment \( \exists q(S_0 \& q \Rightarrow T_0) \) involves first instantiating this higher-order quantifier. In principle, this instantiation can be delayed until attempting to apply the sole instance of the \( \exists \& \) rule (Figure 6).

### 10. List approximations

We now consider using lists as approximations. Since lists have more structure than sets and multisets, it is more involved to encode and reason with them. We only illustrate their use and do not follow a full formal treatment for them.

Since the order of elements in a list is important, the encoding of lists into linear logic must involve a connective that is not commutative. (Notice that both \( \& \) and \( \otimes \) are commutative.) Linear implication provides a good candidate for encoding the order used in lists. For example, consider proof search with the formula

\[
\text{item } a \Rightarrow (\text{item } b \Rightarrow (\text{item } c \Rightarrow (\text{item } \text{nil} \Rightarrow \text{nil})))
\]

The encoding of the list, say \( \text{(cons } a \text{ (cons } b \text{ nil}) \), is given by the \( \lambda \)-abstraction

\[
\lambda \text{item } a \Rightarrow (\text{item } b \Rightarrow (\text{item } \text{nil}))
\]

### 11. Difference list approximations

Since our framework includes \( \lambda \)-abstractions, it is natural to represent difference lists as a particular kind of list abstraction over a list. For example, in \( \lambda \text{Prolog} \) a difference list is naturally represented as a \( \lambda \)-term of the form

\[
\lambda \text{L.cons } x_1 \text{ (cons } x_2 \text{ (cons } \ldots \text{ (cons } x_n \text{ L} \ldots))
\]

Such abstracted lists are appealing since the simple operation of composition encodes the concatenation of two lists. Given concatenation, it is then easy to encode the judgments of prefix and suffix.

To see other example of computing on difference lists described in fashion, see [13]. Lists can be encoded using the difference list notion with the following mapping into linear logic formulas:

\[
\text{nil} \Rightarrow \lambda \text{L.nil} \text{ L}
\]

\[
\text{cons } \Rightarrow \lambda \lambda \text{L.nil} \text{L.item } x \Rightarrow (l \Rightarrow (\text{cons } \text{nil})
\]

The encoding of the list, say \( \text{(cons } a \text{ (cons } b \text{ nil}) \), is given by the \( \lambda \)-abstraction

\[
\lambda \text{L.item } a \Rightarrow (l \Rightarrow (\text{item } b \Rightarrow (\text{item } \text{L}))
\]

(none)
12. Future work

Various extensions of the basic scheme described here are natural to consider. In particular, it should be easy to consider approximating data structures that contain items of differing types: each of these types could be mapped into different items(z) predicates, one for each type $\alpha$.

It should also be simple to construct approximating mappings given the polymorphic typing of a given constructor’s type. For example, if we are given the following declaration for binary tree (written here in AProlog syntax),

kind bt -> type.

type emp -> btree A.

bt -> A -> btree A -> btree A -> btree A.

That can, for example, approximate a binary tree with the multiset of the labels for internal nodes.

Abstract interpretation [8] can associate to a program an approximation to its semantics. Such approximations can help to determine various kinds of properties of programs. It will be interesting to see how well the particular notions of collection analysis can be related to abstract interpretation. More challenging would be to see to what extent the general methodology described here – the substitution into proofs (computation traces) and use of linear logic – can be related to the very general methodology of abstract interpretation.

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