Limit on the anisotropy of the one-way maximum attainable speed of the electron

W. Bergan,1 M. J. Forster,1 V. Khachatryan,1 N. Rider,1 D. L. Rubin,1 B. Vlahovic,2 and B. Wojtsekhowski3,4,*

1Cornell University, Ithaca, New York 14853, USA
2North Carolina Central University, Durham, North Carolina 27707, USA
3College of William and Mary, Williamsburg, Virginia 23187, USA
4Thomas Jefferson National Accelerator Facility, Newport News, Virginia 23606, USA

(Received 18 December 2019; accepted 16 January 2020; published 12 February 2020)

We report here the first experimental result for the anisotropy of the one-way maximum attainable speed of the electron, $\Delta c_{1,e}$, obtained via the study of a sidereal time dependence of the difference between momenta of the counterrotating electron and positron beams in the Cornell Electron Storage Ring at Cornell University. At 95% confidence, an upper limit for the component of $\Delta c_{1,e}/c$ perpendicular to Earth’s rotational axis is found to be $5.5 \times 10^{-15}$.

DOI: 10.1103/PhysRevD.101.032004

I. INTRODUCTION

The theory of special relativity (TSR) [1] was formulated from a few postulates whose experimental tests were important for the universal acceptance of this foundation of modern physics. The principle of relativity has been confirmed by perfect agreement between the TSR predictions and experiments. The universal value of the speed of light in inertial reference systems has been also tested experimentally. Since 1905, the precision of the tests has improved by many orders, and now such experiments represent an important approach to the search for physics which has some degree of Lorentz invariance violation (LIV). According to the original theory by A. Einstein, the speed of light in a vacuum is isotropic and the maximum attainable speed for all particles is equal to the speed of light. However, it is important to differentiate between the two-way speed (average over a closed path, $c_2$), whose isotropy for light was addressed for the first time in the Michelson-Morley experiment [2], and the one-way speed, $c_1$, whose isotropy is a more general postulate.

A number of later formulations of TSR are based on the postulate of relativity and the isotropy of the two-way speed; see for review [3]. At the same time, high precision measurement of $c_1$ isotropy is a well-developed approach for tests of LIV in several frameworks including the Standard Model Extension (SME) [4]. The maximum attainable speed of elementary particles could differ from the speed of light. The current limits on deviations of the maximum attainable speed of particles from the speed of light and related bounds on the anisotropies of the maximum attainable speed (AMAS) are discussed in Ref. [5].

The current upper bound for the photon AMAS, $\Delta c_{2,\text{photon}}/c$ is $10^{-18}$; see Ref. [6], which is already in the domain of quantum gravity (QG) effects [7]. The more challenging for experiment, the $\Delta c_{1,\text{photon}}/c$ bound is $\sim 1.6 \times 10^{-14}$, according to Ref. [8]. A number of TSR predictions have also been tested with increasing accuracy; see Ref. [9]. For example, the test of the relativistic Doppler transformation performed with high speed atoms provided an LIV test on the level of $10^{-9}$ [10].

II. MOMENTUM ANISOTROPY

In the TSR, the momentum of the particle is a four vector whose transformation between the inertial reference frames follows Lorentz’s transformations. The space component of the momentum is $\vec{p} = m \cdot \vec{v}/\sqrt{1-(v/c)^2}$, where $m$ is the particle mass, $\vec{v}$ is the particle velocity, $v$ is the absolute value of $\vec{v}$, and $c$ is the speed of light. When taking into account the difference between the maximum attainable speed of the particle, $c_{\text{part}}$ (with a possible directional anisotropy AMAS) and the speed of light, $c$, we should avoid nonphysical results for $p$, and the expression above should be written as $\vec{p} = m \cdot \vec{v}/\sqrt{1-(v/c_{\text{part}})^2}$, where $c_{\text{part}}$ is the maximum attainable speed of the particle in the direction of the particle velocity $\vec{v}$. 

*Corresponding author.
bogdanw@jlab.org

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The immediate prediction of the TSR is that in process which preserves the absolute value of particle speed, the absolute value of particle momentum is unchanged. By testing a such a prediction for different orientations of the momentum, one can obtain a bound on LIV. This method (momentum anisotropy) is especially sensitive for a particle with a large Lorentz factor, \( \gamma = 1/\sqrt{1 - (v/c)\text{part}}^2 \), in the expression above for the momentum, because of a \( \gamma^2 \) enhancement,

\[
\Delta p / p \approx -\gamma^2(\Delta c_{\text{part}} / c),
\]

where \( \Delta p \) is a variation of the momentum. Similar kinematical enhancement of the sensitivity to LIV for other high \( \gamma \) factor processes was obtained previously; see, e.g., Refs. [11–13].

In the current report, we present the first experiment carried out by using the momentum anisotropy method [14] and the obtained limit for the electron AMAS.

Independent of the high precision test of TSR, the search for sidereal time variation of the maximum attainable one-way speed of particles provides an interesting way to study the directional isotropy of the universe. Tests of directional isotropy have been conducted by high precision magnetic resonance (MR) since the 1960s [15]. For a review and perspectives on the current MR-based search methods, see Ref. [16].

A simple model for the \( c_1 \) anisotropy is based on the concept of a local ether, as distinct from the global ether ruled out in the famous experiment [2]. This possible local ether moves relative to the Solar System and has a tiny refractive index [17]. For example, this local ether may be related to the cosmic microwave background radiation.

### III. MAGNETIC DEFLECTION FOR THE AMAS SEARCH

We implemented the momentum anisotropy method for a search of the electron AMAS. The particle momentum was precisely measured via deflection in a transverse magnetic field. The magnetic field transverse to the direction of motion also allows us to change the direction of the particle’s momentum and repeat the momentum measurement, for example, when the particle is moving in the reverse direction (where the impact of AMAS reaches its maximum). In other words, the 180° magnetic arc acts as a heavy mirror which reflects an electron (positron) elastically.

In the search for an LIV effect, the conventional form of the Lorentz force needs to be corrected because its textbook form suppresses possible LIV contributions, for example, the rotational noninvariant options. The nature and exact form of such a correction are unknown, so in the current analysis of kinematics of the particle motion in the transverse magnetic field we use a minimum number of parameters and considerations. These are a vector of the particle speed \( \vec{v} \) and another vector of the magnetic field \( \vec{B} \), which is an axial vector.

The first assumption is a proportionality of the acceleration and the magnitude of each of these vectors—the absence of nonlinear terms. We assume here the parity conserving nature of the acceleration of a charged particle moving in a transverse magnetic field, so the acceleration of the particle should be directed along the vector product \( \vec{v} \times \vec{B} \). For such a direction of the acceleration, the absolute value of the particle speed remains constant, which is an important consideration used later in the interpretation of the experimental observable: the limit on a variation of the difference between the particle speed and the maximum attainable speed in direction of the particle motion, \( v - c_{1,e} \).

We searched for a variation of the particle momentum allowed according to the QG dispersion relations [7] and assumed energy conservation.

### IV. EXPERIMENTAL CONSIDERATIONS

Our experiment was performed with bunched beams of high energy electrons and positrons circulating in a storage ring. The precision of the experiment for \( \Delta c_{1,e} / c \) benefits from a large value of the beam Lorentz factor, \( \gamma \), and the high precision of the measurement of the beam centroid location in the transverse direction (especially at high beam current in a storage ring).

The stable geometry and magnetic field of the accelerator magnets are of paramount importance in our method. These requirements are significantly relaxed when the experiment uses two counterrotating beams of a particle and an antiparticle in one set of magnets. The difference between the counterrotating particle momenta is relatively insensitive to drifts in the storage ring magnetic fields and geometry, while the sensitivity to \( \Delta c_{1,e} / c \) is doubled, assuming that the anisotropy is the same for the electron and positron (validity of CPT for AMAS). The equality of the masses and opposite sign and equal value of the electrical charges for the electron and positron, which are also important for our analysis, are confirmed by the experiments [18] to a much higher precision than is essential to our experiment.

The beam momentum, \( p \), and accelerator lattice dispersion function, \( \eta(s) \), where \( s \) is a coordinate along the reference orbit of the beam, relate to the deviation of the horizontal beam position, \( x(s) \), and to the nominal beam positions in the accelerator at location \( s \) as \( x(s) - x_{\text{nom}}(s) = \eta(s) \times (p - p_{\text{nom}}) / p \), where \( x_{\text{nom}}(s) \) is the horizontal closed orbit at momentum \( p_{\text{nom}} \) and \( (p - p_{\text{nom}}) \) is a deviation of the momentum from its nominal value [19]. Variation in the measured position difference of the two beams at \( s \) thus corresponds to the measurement of variation in their momenta difference. By measurement of the beam position in an area free from accelerating elements, the beam momenta variations in different directions of motion can be found. The uncertainty in the absolute position of the beams is irrelevant as we are
attempts to measure only the time dependence of the momenta at the frequency of a sidereal rotation. While the particle energy varies with the coordinate $s$ due to synchrotron radiation energy loss and beam acceleration in the rf cavities, the energy at any $s$ is stable and calculable with high precision.

The primary experimental observable is a momentum difference at time moment $t$ between the two counter-rotating beams defined as $\Delta p_\pm(s,t) = \frac{[x_+(t) - x_-(t)]}{\eta(s)}$, which allows us to search for a potential signal using the following equation (for the dipole form of AMAS):

$$
\Delta p_\pm(s,t) = a_\pm [\cos(\Omega \cdot t - \Phi) \times \cos(\Psi(s)) + \sin(\theta_{\text{CESR}}) \times \sin(\Omega \cdot t - \Phi) \times \sin(\Psi(s))],
$$

where $a_\pm = 2r^2 \times \Delta c_{t,e}^+/c$ is a fit parameter, $\gamma$ is the beam Lorentz factor, $\Delta c_{t,e}^+/c$ is an AMAS value, $\Omega$ is a sidereal frequency which is close to the Earth’s rotational frequency, $\Phi$ is the phase which is defined by the direction of anisotropy, $\Psi(s)$ is the phase of the beam position monitor location at position $s$ in the storage ring, and $\theta_{\text{CESR}}$ is the geographic latitude of the Cornell Electron Storage Ring (CESR).

V. THE EXPERIMENT

Our experiment used beams of electrons and positrons with an energy of 5.29 GeV in the CESR [20], Fig. 1. The ring layout is mirror symmetric about its north-south diameter and has a 768 m circumference. Its lattice is of the focusing-defocusing type, with each half cell consisting of a dipole, quadrupole, and sextupole magnet. The design of the magnetic lattice minimizes beta functions at the collision points in order to mitigate current dependence of the beam-beam interaction on the closed orbits. The impact of the remaining beam-beam interaction was investigated in the collected orbit data and found to be much smaller than can be detected at the achieved accuracy of the beam position monitor (BPM) and consistent with theoretical expectations. The dispersion function has a value of between 1 and 2 m in most of the orbit. The rf accelerating cavities are located symmetrically near the south straight section.

The beams’ electrostatic separation system and automatic beam orbit feedback system were turned off. The ring was filled with one electron bunch and one positron bunch with $1.2 \times 10^{10}$ particles in each bunch corresponding to 0.75 mA. The collision points were chosen to be at the location of the interaction point for the former CLEO detector and its diametric counterpart in the north straight section. The beam lifetime was an average of 5 hours. A typical data taking cycle/fill lasted about 1–2 hours, during which the beam currents dropped to a level of 0.5–0.6 mA.

The measurement of the beam positions was performed by means of the CESR BPM system, which includes 99 BPMs [21]. The CESR four-electrode BPM configuration shown in Fig. 2 allows determination of both the horizontal and vertical coordinates. The BPM signal is amplified and digitized at a sampling rate of 125 MHz. Each of the four electrodes has a programmable delay to ensure that the bunch signal is sampled at the peak. The delay step is 10 ps.

The data acquisition system (DAQ) allows accumulation of data for many thousands of turns from each BPM for each beam (electron or positron). The sign of the bipolar pulse depends on the particle species. The signal is sampled at the peak of the leading pulse which is of the opposite sign for electrons and positrons [22].

Two groups of measurements were performed. In the first group (A), the data for the electron beam and the data for the positron beam were recorded at close but

![FIG. 2. CESR four-electrode BPM; see [23].](image-url)
different moments in time. These moments are shifted by 20–30 seconds due to the time needed for loading different versions of the local readout code into the BPM electronics. We called the combined information from the time-consecutive position measurements for the two beams a data “shot.” Measurements for both beams used the same set of electronics, which allowed us to reduce the impact of the electronic instability in the beam position difference. The raw data included the amplitudes from four electrodes from each of 99 BPMs and the combined (electron plus positron) beam current. Data for one shot were collected for each beam over 4000 turns in CESR, which in total covered about a 10 ms time period. Data analyzed in this paper were obtained during several multihour periods in December 2016 and October 2017. In total, in group A, 1714 data shots were taken using 35 fills of the ring.

In the second group (B), beam data were recorded at each BPM for each sequential bunch passage on each turn (the time difference between readsouts is less than 2 μs) but with different electronics (amplifier and digitizer) for the two species. The electron beam data for 4000 turns and similar positron beam data constitute a pair of synchronized measurements (a shot). The interval between the sequential shots was about 200 seconds. Information for group B was collected in January 2018. In total, in group B, 228 data shots were taken over a 14-hour period using five fills of the ring.

VI. EXPERIMENT SENSITIVITY TO THE ELECTRON AMAS

The experiment’s sensitivity to the signal of interest is defined by the coordinate resolution of the BPMs, the lattice functions of the storage ring, statistics of measurements, duration of data taking and systematics due to remaining beam-beam interaction, and electronics instabilities. The combined sensitivity of the data and effect of the analysis procedure on the detected parameters of the signal (a⊥ and Φ) was investigated by adding to the actual BPM data a “test wave” which has the shape of a potential signal. After the adding of the test wave, a full analysis procedure was performed and the wave parameters were reconstructed. The sensitivity studies performed for the signal with an amplitude in the range down to a⊥ = 0.25 ppm show that the reconstructed amplitude is reduced by a factor of 0.74, which is a typical effect for a multiparameter fit analysis. The phase, Φ, which defines the preferable direction for AMAS for the lowest amplitude of the test wave was reconstructed with an accuracy of 0.5 radian.

The drift of the BPM electronics and magnets introduces systematical effects which can create artificial signals. In the analysis of the data, as presented below, we excluded some BPMs with exceedingly large noise or drift. In addition, for run group A, the instability of the horizontal steering magnets (kickers) introduced large orbit distortions. The effect of the kickers has been corrected by a fitting procedure. The data were analyzed with various groupings which allowed us to evaluate the systematics from the spread of the results and obtain a best estimate for an upper limit on the AMAS value.

VII. ANALYSIS OF THE DATA

For analysis, the data from group A were arranged in five sets, each from 6–8 hours long, and the data from group B were used in one set. Analysis was performed independently for each of these six sets.

The analysis procedure started from an evaluation of the noise in the raw amplitudes of the four-electrode BPMs. For this purpose, we checked the correlation between the signal from an individual electrode of each BPM, Ai, of a BPM and the beam current, Ibeam. The rms of the correlation α = Ai/Ibeam was analyzed. It was found that the relative value of the rms, σα/α, averaged over all usable BPMs, was 0.002. When the σα/α exceeded a four times larger value (0.008), which corresponds to about a 200 μm position change or about a 100 ppm momentum change, the corresponding BPM was removed from further analysis. The applied cut eliminated on average a few BPMs of the 99 available in CESR.

For all accepted BPMs, the beam horizontal position x⊥ for positrons (x− for electrons) was calculated from the corresponding four amplitudes in the BPM electrodes by using an updated iterative procedure which starts from a linearized expression [23]. The value of x⊥ = x+ − x− provides the beam position difference. It has contributions from (i) the difference in the beam energies, which varies along the orbit but is time independent; (ii) the off-set, which is due to electronic calibration and for most BPMs is sufficiently stable over selected periods of several hours; (iii) the small random differences in the magnetic system between the moments of measurements of the coordinates of the electron and positron beams (essential for group A); and (iv) a potential AMAS signal, which has time dependence according to the sidereal period of the Earth’s rotation and smooth variation along the beam orbit.

Within one data shot in the group A set, the time delay between the x⊥ and x− measurements (20–30 seconds) sometimes leads to an orbit position change as large as 30 μm in some locations. The most common reason is magnets with a changed value of the field (kickers). They can be identified by analysis of the beam position as a function of s. The parameters of the kicker were obtained from the fit of the data with the closed orbit function [19],

\[
f(s, j) = \theta_j \cdot \frac{\sqrt{\beta(s)\beta(s_j)}}{2 \sin(\pi Q_s)} \cos[|\phi(s) − \phi(s_j)| − \pi Q_s],
\]

where f(s, j) is the closed orbit function for a kicker j, θj is the beam deflection angle of the beam by the kicker j, β(s) and β(s_j) are the ring lattice beta functions at location s and
The fit per Eq. (3) was used for determination of the number of BPMs, which was 80 or more. The fit per Eq. (3) was used for determination of the parameters of the kickers and \( \Delta x_{\pm}^{\text{eff}} \) for all other contributions combined. The total number of fit parameters for eight kickers in each data shot and the off-sets for \( N_{\text{BPM}} \) BPMs is at a maximum of \( 8 \times N_{\text{sh}} + 2 + N_{\text{BPM}} \), which is small compared to the number of fit points.

Figure 3 shows \( \Delta x_{\pm} \) versus the BPM location along the orbit in the storage ring for a typical data shot, residual \( \delta x_{\pm} \), and the corresponding rms. The significant variations of the \( \Delta x_{\pm} \), shown in the upper panel of Fig. 3, are due to the kickers. The rms for \( \Delta x_{\pm} \) is about 12 \( \mu \)m. The fit of the closed orbit function [Eq. (3)] with several kickers (the actual number of kickers was defined by the significance of the \( \chi^2 \) improvement) allowed us to find the residual \( \delta x_{\pm} = \Delta x_{\pm} - \sum f(s, j) \), where \( \sum f(s, j) \) is the sum of the closed orbit functions for all observed kickers. The \( \delta x_{\pm} \) values have a typical rms of 3 \( \mu \)m as is shown for one data shot in the lower panel of Fig. 3.

After the kickers were identified, their number and locations in each shot were fixed, and the fit was redone with optimization of the amplitudes of the kickers for each shot, off-sets, \( \Delta x_{\pm}^{\text{ref}} \), for each BPM (fixed in each group of 30-minute time intervals), the AMAS amplitude and phase (fixed within a given several-hour measurement set).

For group B, the analysis above was not needed because the synchronized readout of BPMs completely suppressed the kicker effect. At the same time, group B required...
additional electronics channels which added noise. Overall, the data from groups A and B have similar accuracies.

The second step of the analysis is the same for groups A and B and includes the following: the data were fitted by a two-parameter function of the signal and one parameter per BPM $\Delta x_{\text{ref}}^*$ as

\[
\Delta x_{\pm}^* = \eta^{-1}(s) \times a_{\perp \times} \times [\cos(\Omega \cdot t - \Phi) \times \cos(\Psi(s))
+ \sin(\theta_{\text{CESR}}) \times \sin(\Omega \cdot t - \Phi) \times \sin(\Psi(s))] + \Delta x_{\text{ref}},
\]  

(4)

For all datasets in the analysis of the AMAS signal, we calculated the sidereal time phase $\Phi$ relative to midnight, October 22, 2017, at the geographic location of CESR.

In the fit of the AMAS signal, we took into account that some of the BPMs have a significant drift. We determined the rate of BPM drifts by doing one-BPM fits per Eq. (4), for which the results are plotted in Fig. 4. For presentation of the search results below, we used the $a_{\perp \times}$ and $a_{\perp \gamma}$, which are the components of a projection of the anisotropy vector $\vec{a}$ to the plane of the CESR ring along the geographical meridian and orthogonal to it, respectively.

The mean values for the one-BPM analysis are $a_{\perp \times} = 0.72$ ppm and $a_{\perp \gamma} = -0.40$ ppm with the rms of 7 ppm. It is easy to see that the tails in the distribution of the widths are dominated by the systematics. The systematic uncertainty is much larger than the statistical uncertainty for the individual data points. Data points (corresponding BPMs) with an extra large deviation (above 15 ppm) were excluded from the next step of the analysis. The accuracy of the average values (0.72/0.40 ppm) is close to expected for these 500 data points.

The final method for combining of the data is based on four groups of BPMs. In group #1, we used every fourth BPM among those selected for the analysis starting from #1, then took #5, #9, and so on. In group #2, the starting BPM is #2, then #6, #10, and so on. Each group includes about 20 BPMs distributed almost uniformly around the

![FIG. 4. One-BPM fit results for the AMAS function parameters. The pink contour 30 × 30 ppm on the left plot contained 359 data points out of the 500 obtained. The distributions in the right side plots were fitted by a Gaussian function for the central areas of ±15 ppm.](image1)

![FIG. 5. The results for all six measurements presented by 24 data points. The points in black and red show the results from the run groups A and B, respectively. The error bars at individual points represent statistical accuracy. The rms is calculated from the distribution of the data points. The mean values are $a_{\perp \times} = 0.32 \pm 0.31$ ppm and $a_{\perp \gamma} = -0.12 \pm 0.29$ ppm. The solid and dashed blue contours show the borders of one and two sigma exclusion areas, respectively, per one data point out of the 24 obtained.](image2)
ring. In each of six sets of measurements, we fitted the signal by using those four groups of BPMs. A total of 24 data points were obtained and the results are shown in Fig. 5. The combined fit of these data points leads to the values \( a_{\perp,x} = 0.32 \pm 0.31 \) ppm and \( a_{\perp,y} = -0.12 \pm 0.29 \) ppm, where \( a_{\perp,x} = a_{\perp} \cos(\Phi) \) and \( a_{\perp,y} = a_{\perp} \sin(\Phi) \) per Eq. (2), which corresponds to the value of a combined fit amplitude \( a_{\perp} = 0.34 \pm 0.42 \) ppm and phase \( \Phi = -0.36 \) radian.

**VIII. SUMMARY**

The search for the anisotropy of the one-way maximum attainable speed of the electron was performed by means of precision monitoring of the variation of the difference in momenta of electron and positron beams versus location along the orbit of the CESR storage ring for 5.29 GeV beam energy. The sidereal time variation \( \Delta c_{\perp,e}/c_e \) (the combined result from all 24 sets of data) is below \( 5.5 \times 10^{-15} \) with \( \sim 95\% \) confidence (two-sigma level) as follows from Eqs. (1) and (2) with \( a_{\perp} = \sqrt{a_{\perp,x}^2 + a_{\perp,y}^2} \). This limit is about three times better than previously reported by the most accurate experiment [8].

The accuracy of this experiment is limited by the drift of individual electronics channels and to a lesser extent by the readout rate of the associated DAQ. With resolution of these issues, the technique will allow investigation of the \( \Delta c_{\perp,e} \) in the region potentially sensitive to a QG effect. Performing the experiment at different beam energies will provide an additional handle for the discrimination of the systematics and the possible AMAS effect.

It is interesting that the LHC collider, whose magnetic systems for two beams are coupled magnetically and geometrically, provides the possibility of doing a test of AMAS for the proton [24]. We would also like to mention that a synchronized measurement of the beam deflection in several storage rings with high accuracy opens additional opportunity for a search for the transient effects [25], which were proposed in a number of models for the physics beyond SM.

Many recent experiments on LIV were interpreted within the framework of the SME theory. It would be interesting to perform an SME-based analysis of our measurement as well. However, in the minimal SME theory, there is no sensitivity of the magnetic deflection to the dipole form of the AMAS [26], so the obtained limit could also be used for a test of the underlying assumption of SME. At the same time, within the SME framework, there is already a prediction of a nonvanishing eccentricity of the particle trajectory in the magnetic deflection [27], which could be investigated by using the beam trajectory in a storage ring, as we did here, when sufficient stability of the magnets is achieved.

**ACKNOWLEDGMENTS**

It is our pleasure to thank the CESR staff for the smooth operation of the storage ring. We would like to extend special thanks to V. Zelevinsky for his recommendations, D. Sagan and B. Schmookler for their contributions to data analysis at the initial stage of the experiment, and G. Cates for productive discussions and support of the experiment. This work supported by National Science Foundation under Grants No. PHYS-1416318 and No. DGE-1144153.

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