Fast noise-resistant control for nuclear spin qubits in silicon

James Simon\textsuperscript{1,2}, F. A. Calderon-Vargas\textsuperscript{2}, Edwin Barnes\textsuperscript{2}, and Sophia E. Economou\textsuperscript{*} \textsuperscript{1}
\textsuperscript{1}Department of Physics, University of California, Berkeley, California 94720, USA
\textsuperscript{2}Department of Physics, Virginia Tech, Blacksburg, Virginia 24061, USA

The high degree of controllability and long coherence time make the nuclear spin of a phosphorus donor in isotopically purified silicon a promising candidate for a quantum bit. However, long-distance two-qubit coupling and fast, robust gates remain outstanding challenges for these systems. Here, following recent proposals for long-distance coupling via dipole-dipole interactions, we present a simple method to implement arbitrary fast, high-fidelity single- and two-qubit gates. Moreover, our method makes the single-qubit gates robust to moderate levels of charge noise to well within an error bound of 10\(^{-3}\).

I. INTRODUCTION

Nuclear spins in the solid state present unparalleled advantages as a platform for quantum computing due to their long coherence times \textsuperscript{1}[2] and high degree of controllability \textsuperscript{3}[5]. In particular, the nuclear spin of a phosphorus donor in silicon is a promising candidate for a quantum bit \textsuperscript{6}[7] owing to its coherent control \textsuperscript{8}[10] and minute-long coherence time \textsuperscript{2}. The use of isotopically-purified silicon nanostructures \textsuperscript{11} considerably reduces magnetic environmental noise, allowing high-fidelity control \textsuperscript{8}. However, long coherence times are only useful when gates are very fast in comparison. One of the difficulties of using the nuclear spin as a qubit has been the implementation of fast single- and two-qubit gates. Controlling a nuclear spin with an oscillating magnetic field as in nuclear magnetic resonance is slow, with typical gate times ranging from a few to tens of microseconds \textsuperscript{8}[9][12]. Moreover, most of the approaches for multi-qubit operations require short interaction distances \textsuperscript{6}[13], and thus demand near-atomic precision in the placement of the donors \textsuperscript{14}[15].

To overcome these challenges, Ref. \textsuperscript{16} proposes the dynamical creation of a strong electric dipole transition at microwave frequencies for the nuclear spin by sharing an electron between the donor and the Si/SiO\(_2\) interface and applying an oscillating magnetic field. This facilitates the implementation of two-qubit gates via dipole-dipole interactions or, alternatively, the qubit’s coupling to other quantum systems. Moreover, nuclear spin-flip transitions can also be sped up by including an oscillating electric field along with the magnetic drive. A potential downside of making the system amenable to electrical control is that it increases its sensitivity to charge noise due to the charge component in the states encoding the qubit. However, Ref. \textsuperscript{16} shows that there are regions in parameter space (“clock transitions”) where the nuclear spin transition is insensitive to electrical noise to at least first order.

In this work, we propose an alternative path toward robust high-fidelity single-qubit gates that does not rely on clock transitions. Our approach is based on using optimally designed control pulse waveforms and energy transition modulation. Accordingly, we derive a time-independent analytical approximation for the system’s Hamiltonian, explain how to rapidly implement arbitrary, noise-resistant single-qubit gates with fidelities exceeding 99.9\% even in the presence of significant charge noise, and provide a method to use the dipole-dipole interaction to implement cphase gates across a distance of 0.5\(\mu\)m. The single-qubit and cphase gates have maximum durations of 500 ns and 750 \(\mu\)s, respectively, with special cases such as single-qubit Z gates being much faster (< 25 ns).

The paper is organized as follows. In Sec. \textsuperscript{II} we introduce the system and its Hamiltonian. In Sec. \textsuperscript{III} we derive an analytical time-independent Hamiltonian following two approaches. In Sec. \textsuperscript{IV} we define the qubit states and explain how to implement robust single-qubit gates, specifically arbitrary Z-rotations and X-rotations. We give a method for implementing fast controlled-phase gates between two adjacent qubits separated by a distance of 0.5\(\mu\)m in Sec. \textsuperscript{V} We conclude in Sec. \textsuperscript{VI}.

II. THE SYSTEM

The system follows the experimental proposal reported in Refs. \textsuperscript{16} and \textsuperscript{17}, where a donor \textsuperscript{31}P atom is embedded in enriched \textsuperscript{28}Si a distance \(d\) away from a Si/SiO\(_2\) interface, as shown in Figure \textsuperscript{1}. The donor atom provides a nuclear spin \(I = 1/2\) with gyromagnetic ratio \(\gamma_n/2\pi = 17.23\) MHz\(^{-1}\) and a free electron with spin \(S = 1/2\) and gyromagnetic ratio \(\gamma_e/2\pi = 27.97\) GHz\(^{-1}\). The electron and nuclear spins are coupled via a hyperfine interaction with coupling strength \(A\), which is approximately equal to 117 MHz when the electron is bound to the nucleus. A metal gate positioned on top of the donor atom is used to control the position of the electron via electric fields, which also tunes the hyperfine interaction \(A\) down to zero when the electron is at the interface. Moreover, the gyromagnetic ratio of the electron bound to the nucleus can differ from that of an electron at the interface by an amount \(\Delta\gamma\) that can reach up to 0.7\% \textsuperscript{18}. Therefore, the Hilbert space includes three
binary degrees of freedom: the nuclear spin of the donor atom, the spin of the free electron, and the position of the free electron, which is quantized into a state on the donor atom, a state on the interface, and both the electron and nuclear spins are used. Static and oscillating electric and magnetic fields are used to control the system. The qubit is ultimately stored in the nuclear spin state, with the other degrees of freedom used for driving gates.

The system has two control fields, an electric and a magnetic one, each with static (DC) and oscillating (AC) components. The DC component of the electric field, \( E \), points along the donor-interface axis and controls the electron position (see Fig. 1), determining the amplitudes of the states \(|i\rangle\) and \(|d\rangle\) in the orbital ground state. The AC electric field is parallel to \( E \) and is given by \( E_{ac}(t) = E_0 \cos(\omega t) \). In particular, when \( E = E_0 \), where \( E_0 \) is the magnitude of the electric field at the ionization point, the orbital ground state of the electron has equal probability to be at the donor nucleus and at the interface. The transition frequency between the orbital ground and excited states at the ionization point is equal to the tunnel coupling \( V_t \). A strong static magnetic field \( B_0 (B_0 (\gamma_e + \gamma_n) \gg A) \) splits the energy of the nuclear and electron spin states (\(|\uparrow\rangle, |\downarrow\rangle\) and \(|\uparrow\rangle, |\downarrow\rangle\)), respectively. The AC magnetic field is applied perpendicularly to \( B_0 \) and is given by \( B_{ac} = B_0 \cos(\omega_B t) \).

The Hamiltonian of the system, therefore, consists of the orbital part, the Zeeman part, and the hyperfine coupling:

\[
H = H_{orb} + H_B + H_A. \tag{1}
\]

Here each term can be expressed in terms of the electron position operators \( \tau_z = |i\rangle \langle i| - |d\rangle \langle d| \), \( \tau_x = |i\rangle \langle i| + |d\rangle \langle d| \), and the electron (nuclear) spin operator \( S \) (I) as follows:

\[
H_{orb} = - \frac{de (\Delta E + E_a \cos(\omega_E t))}{2\hbar} \tau_z + \frac{V_t}{\varepsilon_0} \tau_x,
\]

\[
H_B = B_0 \left[ \gamma_e \left( \frac{1}{2} - \frac{\Delta E}{\hbar \varepsilon_0} \right) S_z - \gamma_n I_z \right] + B_0 \cos(\omega_B t) (\gamma_e S_z - \gamma_n I_z),
\]

\[
H_A = A \left( \frac{1}{2} - \frac{\Delta E}{\hbar \varepsilon_0} \right) S \cdot I,
\]

where \( \Delta E = E - E_0 \) is the deviation of the electric field away from the ionization point.

The qubit is encoded in the two lowest-energy eigenstates of the system, which, in the absence of AC driving, are approximately \(|g \\downarrow\rangle\) and \(|g \\downarrow\rangle\), where \(|g\rangle\) is the ground eigenstate of the orbital part of the Hamiltonian with no AC fields. Therefore, it is convenient to express the total Hamiltonian in (1) in a basis spanned by the orbital eigenstates \(|g\rangle, |e\rangle\). The electron position operators \( \tau_z \) and \( \tau_x \) in the orbital eigenbasis are

\[
\tau_z = \frac{de \Delta E}{\hbar \varepsilon_0} \tau_z + \frac{V_t}{\varepsilon_0} \tau_x,
\]

\[
\tau_x = \frac{V_t}{\varepsilon_0} \tau_z + \frac{de \Delta E}{\hbar \varepsilon_0} \tau_x,
\]

III. DERIVING THE TIME-INDEPENDENT HAMILTONIAN

The dominant energy scales of this system are the charge splitting \( \varepsilon_0 \) and the electron spin splitting \( B_0 \gamma_e \), which are driven at frequencies \( \omega_E \) and \( \omega_B \), respectively. We transform into a rotating frame involving both frequencies, leaving a Hamiltonian that is largely static. Therefore, we move the Hamiltonian to the rotating frame \( \hat{H} = \hbar \hat{H} + \Delta \hat{H} \) with \( \Delta A \hat{A}^\dagger = \exp(-it (\omega_E (\tau_z / 2 + I_z) - \omega_B (S_z + I_z))) \), where the system’s dominant off-diagonal energy terms \( (B_0 \gamma_e \text{ and } \Delta \hat{A}^\dagger) \) become effectively static. Assuming that the driving fields’ detunings are small and the orbital and electron spin splittings are similar (i.e. \( \varepsilon_0 \approx \omega_E \approx B_0 \gamma_e \approx \omega_B \)), the Hamiltonian in the rotating frame is

\[
\hat{H} = \hbar \left[ \gamma_e \left( \frac{1}{2} - \frac{\Delta \hat{H}}{\hbar \varepsilon_0} \right) S_z - \gamma_n I_z \right] + B_0 \cos(\omega_B t) (\gamma_e S_z - \gamma_n I_z),
\]

\[
\hat{H} = A \left( \frac{1}{2} - \frac{\Delta \hat{H}}{\hbar \varepsilon_0} \right) S \cdot I,
\]
\( \omega_B \), we can then apply the rotating wave approximation (RWA), dropping all rapidly oscillating terms from \( \tilde{H} \) to get:

\[
\tilde{H}_0 = -\frac{\varepsilon_0 + \omega_E}{2} \tau_z - E_a(t) \frac{dV_i}{4 \hbar \varepsilon_0} \tau_x + (B_0 \gamma_e - \omega_B) S_z
\]

\[
- (B_0 \gamma_n + \omega_B - \omega_E) I_z + B_0 \gamma_s \Delta \gamma \frac{1}{2} \left( \frac{dE}{\hbar \varepsilon_0} \tau_z \right) S_z
\]

\[
+ \frac{E_a(t) \gamma_e}{2} S_x + A \left( 1 - \frac{dE}{\hbar \varepsilon_0} \tau_z \right) S_z I_z
\]

\[
- \frac{AV_i}{4\varepsilon_0} \left( |g \uparrow \downarrow \rangle \langle e \downarrow \uparrow | + |e \downarrow \uparrow \rangle \langle g \uparrow \downarrow | \right).
\]

Except for the final term coupling the \( |g \uparrow \downarrow \rangle \) and \( |e \downarrow \uparrow \rangle \) states, this Hamiltonian is entirely diagonal when the driving fields are zero.

This approximate RWA Hamiltonian works very well for short times. However, as the system evolves, the approximate evolution gradually becomes dephased relative to the true evolution due to energy shifts caused by the dropped high-frequency terms, in a similar effect to the Bloch-Siegert shift \[19\]. Corrections to the RWA are required, and thus we use multi-frequency Floquet theory to construct a Floquet Hamiltonian \( \tilde{H}_F \) that takes into account these higher-frequency modes. Then we use 2nd-order quasi-degenerate perturbation theory to reduce it to a (still non-oscillating) approximation \( \tilde{H}' \) that reproduces the evolution given by the oscillating lab-frame Hamiltonian with typical fidelity > 0.9999 for the gates we describe in this paper. The derivation of this approximation is detailed in Appendix [A].

As with \( \tilde{H}_0 \), this approximation’s only time dependence is in the changing envelopes of the control pulses, making it both conceptually simpler and faster to simulate with common software. It is thus useful for optimizing gates or running accurate simulations much faster than with the lab-frame Hamiltonian. In this paper, we use the lab-frame Hamiltonian in all of our final results for the sake of caution, but we have confirmed that using this approximation gives the same results.

IV. QUBIT STATES AND GATES

The qubit is defined to be the two lowest-energy eigenstates of the system. In the absence of driving, these are approximately equal to \( |g \downarrow \rangle \) and \( |e \downarrow \rangle \), so we refer to the exact ground states as \( \langle \uparrow \rangle \) and \( \langle \downarrow \rangle \), respectively. With zero AC fields and typical parameter values (given below), the approximations \( |\uparrow \rangle \approx |g \downarrow \rangle \) and \( |\downarrow \rangle \approx |e \downarrow \rangle \) hold to within an overlap error of at most \( 10^{-4} \), which becomes much lower still when \( \Delta E > 0 \).

The dominant source of decoherence in this system is quasi-static charge noise with a typical \( 1/f \) spectrum \[18\] [20]. We model the quasi-static charge noise as acting along the z-axis, directly perturbing the applied electric field \( \Delta E \) \[21\]. The energy splitting \( \delta_q \) between the two qubit states depends on the applied electric field (see Figure 2), so noise in the electric field will lead to uncertainty in the energy difference of the qubit states, causing dephasing. This energy splitting can be very accurately approximated by

\[
\delta_q \equiv E_{\uparrow \uparrow} - E_{\downarrow \downarrow} \approx B_0 \gamma_n + \frac{(A)}{2}
\]

where \( E_{\uparrow \uparrow} \) and \( E_{\downarrow \downarrow} \) are the energies of the respective states and \( \langle A \rangle = A |\langle g | d \rangle|^2 = \langle A/2 \rangle (1 - dE/\varepsilon_0) \). If the system idles for a time \( t \) with a small error in the electric field \( \delta E \), we expect the dephasing to be approximately given by \( R_z(-\frac{\delta q}{\Delta E} \delta E t) \).

Following Ref. [16] in all the following calculations we use \( A/2\pi = 117 \text{ MHz} \), \( \gamma_e/2\pi = 27.97 \text{ GHz T}^{-1} \), \( \gamma_n/2\pi = 17.23 \text{ MHz T}^{-1} \), and \( \Delta \gamma = -0.002 \), and choose \( d = 15 \text{ nm} \), \( B_0 = 0.2 T \), and \( V_i = B_0 (\gamma_e + \gamma_n) \). Moreover, we choose \( \Delta E = 10^4 \text{ V m}^{-1} \) so that in the absence of AC driving, the qubit idles far from the ionization point in a region where \( d\delta q / d\Delta E \) is very small and dephasing is reduced (see Appendix [B] for further discussion). Every gate shown here starts and ends at this chosen idling point. We also define our gates in the idling frame of the qubit, so the evolution while idling is simply the identity.

Any single-qubit gate can be decomposed into the form \( R_z(\theta_1) R_z(\theta_2) R_z(\theta_3) \), where a Z rotation is defined as \( R_z(\theta) = \exp \left[-i\frac{\theta}{2} \sigma_z \right] \), \( \theta \in [0, 2\pi] \), and an X rotation is defined as \( R_x(\theta) = \exp \left[-i\frac{\theta}{2} \sigma_x \right] \), \( \theta \in [0, \pi] \). The Pauli operators are defined following \( \sigma_z = |\uparrow \rangle \langle \uparrow | - |\downarrow \rangle \langle \downarrow | \). Below we show how to implement a noise-resistant \( R_z(\theta) \) gate.
A. $R_x(\theta)$ Gates

Figure 2 shows that simply changing $\Delta E$ changes $\delta_q$, causing a phase difference between the qubit states to accumulate. If leakage were not a concern, one could implement an effectively noiseless $Z$ rotation by shifting from the idling condition of $\Delta E \gg 0$ to $\Delta E \ll 0$. $\delta_q$ then shifts by $\sim 2\pi \cdot 60 \text{ MHz}$, causing a full $2\pi$ rotation in $\sim 20 \text{ ns}$, and $d\delta_q/d\Delta E$ will be small as during idling. However, the non-oscillating electric field $\Delta E$ cannot be shifted arbitrarily fast, and changing $\Delta E$ changes the transformation we have used in going from the $\{|i\},\{|d\}\}$ basis to the $\{|g\},\{|e\}\}$ basis, causing another term to appear in $H$ (as derived in Appendix C) that can drive the system out of the logical space. Nonetheless, the effect on the fidelity is negligible for shift times of a few ns, so this does not significantly affect the gate time. The resulting evolution will be adiabatic in the qubit subspace, so we only need to consider the phase accumulated.

We can calculate the phase accumulated using

$$\theta = -\int_0^T (\delta_q(t) - \delta_q^0) dt,$$

(7)

where $\delta_q^0$ is the qubit splitting while idling, which we subtract so we work in a frame where, at idling, the evolution operator is the identity. For the pulse shapes, we use a cosine window function $w$ defined as follows:

$$w(t, \tau, T) = \begin{cases} 
(1 - \cos(\pi t/\tau))/2 & 0 \leq t < \tau, \\
1 & \tau \leq t < T - \tau, \\
(1 - \cos(\pi(T - t)/\tau))/2 & T - \tau \leq t \leq T, \\
0 & t < 0 \text{ or } t > T.
\end{cases}$$

(8)

When implementing an $R_x(\theta)$ gate as described above, the varying function $\Delta E(t)$ is constrained by the fact that $\Delta E$ has to change slowly enough for evolution to be adiabatic. We choose a minimum time of 5 ns to move from idling to minimum $\Delta E$, so, for $R_x(\theta)$ gates with total time $T$ shorter than 10 ns, there will not be time for $\Delta E$ to reach its minimum value, so we simply make the $\Delta E(t)$ pulse shallower. We choose $\Delta E(t) = \Delta E_{\text{idle}} - S \cdot w(t, \tau, T)$, where $E_{\text{idle}} = 10^4 \text{ V m}^{-1}$, $\tau = \min(5 \text{ ns}, T/2)$ and $S = (2 \times 10^3 \text{ V m}^{-1}) \cdot \min(1, T/(10 \text{ ns}))$. Figure 3 shows several examples of $\Delta E(t)$ for various $T$. As no AC fields are needed, we choose $E_n(t) = B_n(t) = 0$.

The angle of the implemented $R_x(\theta)$ gate as a function of $T$ is plotted in Fig. 4. An arbitrary $Z$-rotation can be generated in under 25 ns, and a $Z$-gate with $\theta = \pi$ is generated in $T \approx 14 \text{ ns}$. The numerically calculated phase is quite close to a simple approximation obtained using Eqs. 3 and 7, demonstrating that the phase of the gate is accumulating as we describe.

As mentioned before, quasi-static charge noise is the most deleterious source of error for this type of system [17,22]. In this work, we model this noise by adding a constant stochastic error $\delta E$ to $\Delta E$ for the duration of a gate. Since the charge noise is statistical in nature, we draw $\delta E$ from a normal distribution with standard deviation $\sigma_{\delta E}$ and report average infidelity over the distribution. The gate infidelity is defined as $\begin{array}{c}
\end{array}$

$$1 - F = 1 - \frac{1}{n(n+1)} \left[ \text{Tr}(U^\dagger U) + \text{Tr}(U_0^\dagger U_0)^2 \right],$$

where $n$ is the Hilbert space dimension, $U$ is the generated gate, and $U_0$ is the desired gate. Figure 4 shows the gate infidelity for three different angles of rotation. For typical noise with an r.m.s. of $100 \text{ V m}^{-1}$ [17, the error is well below $10^{-4}$ for all angles. Our $R_x(\theta)$ scheme is quite noise-resistant as it is, because the system spends most of its time with $\Delta E \ll 0$ or $\Delta E \gg 0$, so that $d\delta_q/d\Delta E$ is small for most of the gate.

B. $R_x(\theta)$ Gates

An $R_x(\theta)$ gate requires a coupling between the two qubit states. The simplest way to achieve this is by driving $B_{ac}$ on resonance with the nuclear spin, but the scale

FIG. 3. Examples of $\Delta E$ pulses used to implement $R_x(\theta)$ gates for various values of the total gate time. For long times, $\Delta E$ is moved to its minimum value, is held for several ns, and then returns. For short times, $\Delta E$ cannot be changed fast enough to reach the minimum while remaining adiabatic, so a shallower pulse is used.

FIG. 4. Exact and approximate $R_x(\theta)$ angles for different gate durations $T$ using the gate scheme described in Section IV.A. The approximate curve is found from the approximations in Eq. 3 integrated according to Eq. 7. The exact and approximate curves agree to within an angle of .08 rad.
FIG. 5. Gate infidelity vs noise strength for three $R_x(\theta)$ gates with $\theta = -\pi/4$ ($T = 6.632\,\text{ns}$), $\theta = \pi$ ($T = 13.560\,\text{ns}$), and $\theta = 2\pi$ ($T = 22.116\,\text{ns}$). The numerical error in our simulations is roughly $10^{-6}$.

of $\gamma_n$ makes this slow, with typical times ranging from a few to tens of microseconds for $\pi$ rotations [24]. A faster solution in this system is to create an effective coupling through intermediate non-computational states. Figure 5 shows a level diagram of the system including all strong, near-resonance couplings between states, as reflected in $H_D$. The simplest way to drive fast transitions between the qubit states is to use two intermediate states:

$$|g \downarrow\uparrow\rangle \xrightarrow{B_{ac}} |g \uparrow\downarrow\rangle \xrightarrow{A} |e \downarrow\uparrow\rangle \xrightarrow{E_{ac}} |g \downarrow\uparrow\rangle.$$ 

The first major problem one encounters is the fact that, if the driving frequencies are simply chosen to be on resonance, there will be severe leakage into the non-computational states. The complexity of the system and the limited number of controllable parameters would seem to make this a difficult problem. However, with slightly different choices of driving fields, one can drive a transition adiabatically with respect to the qubit subspace. If $\Delta E$ and $B_0$ are chosen so that the lab-frame energies of $|g \uparrow\downarrow\rangle$ and $|e \downarrow\uparrow\rangle$ are similar (i.e., $\varepsilon_0 \approx B_0(\gamma_c + \gamma_n)$), the hyperfine coupling strongly hybridizes these states. Transitions between the qubit states can then be seen as similar to Raman transitions [24], but with two intermediate states instead of one. The driving field amplitudes and frequencies can be set like in an adiabatic Raman transition (i.e. making the driving matrix elements equal and the large detunings from intermediate states the same) to give a transition close to an X-gate with a leakage probability below $10^{-4}$. The large detunings separate the qubit subspace from the rest of the Hilbert space, and we use slowly-varying pulse shapes instead of square pulses, so the resulting transition is very adiabatic. The driving amplitudes and frequencies can then be optimized while worrying only about the computational subspace, while also using the $R_z(\theta)$ gates described previously to cancel unwanted accumulated phases, giving a high-fidelity $R_z(\theta)$ for any given angle.

This gate scheme, however, is extremely sensitive to electrical noise. This can be seen by writing out the three relevant transition energies as follows:

$$\delta_\theta \equiv E_{|g\uparrow\downarrow\rangle} - E_{|g\downarrow\uparrow\rangle} \approx B_0\gamma_c - \langle A \rangle/2,$$
$$\delta_\uparrow \equiv E_{|e\downarrow\uparrow\rangle} - E_{|g\uparrow\downarrow\rangle} \approx \varepsilon_0 - A/4 + \langle A \rangle/2,$$
$$\delta_{mid} \equiv E_{|e\downarrow\uparrow\rangle} - E_{|g\uparrow\downarrow\rangle} \approx \varepsilon_0 - B_0(\gamma_c + \gamma_n) - A/4 + \langle A \rangle/2. \quad (9)$$

All three of these transition energies depend on $\Delta E$. In addition, $\varepsilon_0$ strongly depends on $|\Delta E|$ when $|\Delta E| > 0$, while $\langle A \rangle$ strongly depends on $\Delta E$ when $|\Delta E| < 0$, so there is no value for $\Delta E$ that ameliorates this problem. If any of the three transitions are far off resonance, the effective coupling between the qubit states approaches zero and an X-rotation becomes impossible. Thus, while the two qubit states are effectively coupled, $\Delta E$ has to be known to high precision.

Our solution to this is to have $\Delta E$ sweep through a broad range of values at a fixed rate instead of remaining constant. The probability transfer between the two qubit states will happen in a short period in the middle whenever $\Delta E \approx 0$. If there is quasi-static charge noise, the constant sweep rate ensures that this transition will still happen identically, but it will simply be shifted slightly in time, and there will be only noisy Z-rotations before and after the gate. To explain this, consider sweeping $\Delta E$ from $-D$ to $D$ at a constant rate, first without error in $\Delta E$, and second with an error of $\delta E > 0$, so $\Delta E$ actually sweeps from $-D + \delta E$ to $D + \delta E$. In both cases, there is a segment of the evolution in which $\Delta E$ sweeps from $-D + \delta E$ to $D$. The difference is that in the first case, there is a sweep from $-D$ to $-D + \delta E$ before this segment, and in the second case, there is a sweep from $D$ to $D + \delta E$ after it. Far from $\Delta E \approx 0$, the evolution operator will be
diagonal in the qubit subspace, so these small pieces are just $R_z$ rotations, so the effect of this error $\delta E$ is just to introduce phase errors before and after the gate. To explain why, consider a gate that sweeps from $\Delta E = -D$ to $\Delta E = D$ at a constant rate. Let $U(a, b)$ represent the evolution operator resulting from sweeping $\Delta E$ through the range $[a, b]$. As shown in Fig. 7, in the ideal case, we get the evolution $U_0 = U(-D + \delta E, D)U(-D, -D + \delta E)$, while if there is a static charge noise $\delta E$, the actual evolution operator is $U_{1E} = U(D, D + \delta E)U(-D, -D + \delta E, D)$. The middle stretches of these evolution operators, from $\Delta E = -D + \delta E$ to $\Delta E = D$, are essentially identical; apart from the ramping up of the AC fields, all parameters as a function of time are the same. If $D$ is large, then the AC electric driving is very far off resonance at the ends of the evolution span, and there is no effective coupling between the computational states, so the computational states, so the error operators $U(D, D + \delta E)$ and $U(D, D + \delta E)$ are entirely diagonal and amount to $R_z$ errors. The effect of small charge noise, then, is only to add dephasing before and after the sweep gate.

As discussed above, an arbitrary gate $U$ can be decomposed into Euler angle form $U = R_z(\theta_2)R_y(\theta_1)R_z(\theta_2)$, and the three angles of this decomposition vary continuously with $U$ except when $\theta_1 = 0, \pi$ due to a phenomenon called gimbal lock. Except at these points, then, to first order, an arbitrary gate’s dependence on charge noise can be decomposed as $R_z(\theta_2 + \theta_1 \delta E)R_z(\theta_1 + \theta_2 \delta E)R_z(\theta_2 + \theta_3 \delta E)$. The effect of this sweep will be to make $\theta_2 = 0$, eliminating the noise-dependence of the $R_z$ component. Additionally, tweaking the start and end points of the sweep can change $\theta_1$ and $\theta_2$. In the special case of $\theta_1 = \pi$, $\theta_1 = \theta_2$, the two error terms cancel because $R_z(\theta_1)R_z(\pi) = R_z(\pi)R_z(\theta_1)$, and the noise dependence is eliminated. Gimbal lock is not a problem here because in practice $\theta_1 \neq \pi$, so $\theta_1$ and $\theta_3$ do not diverge, and even at $\theta_1 = \pi$ they diverge together and the divergences cancel. This means that to create an $X$-gate, we can apply a $R_z(-\theta_1 + \theta_3)$ gate after the sweep to remove the residual $R_z$ gates and leave only $R_z(\pi) \equiv X$. We use numerical simulations in conjunction with the Euler decomposition to determine the driving parameters necessary to produce this cancellation.

Our precise control protocol for implementing a noise-resistant $X$-gate is summarized as follows. We sweep $\Delta E$ from $-2000$ V m$^{-1}$ to $2000$ V m$^{-1}$ in $110$ ns using the function $l(t, \tau_1, \tau_2, \tau_3, \tau_4, \lambda) = \begin{cases} y_1 t / \tau_1, & 0 \leq t < \tau_1, \\ y_1 + (y_2 - y_1) \frac{t - \tau_1}{\tau_2 - \tau_1}, & \tau_1 \leq t < \tau_2, \\ y_2 - \frac{T - t}{\tau_2 - \tau_1}, & \tau_2 \leq t < T, \\ 0, & \text{otherwise.} \end{cases}$

Then the control pulse is $\Delta E(t) = \Delta E_{idle} + l(t, \tau_1, -\Delta E_{idle} - D, \tau_1 + \tau_3, -\Delta E_{idle} + D, 2\tau_1 + \tau_3)$, where $\Delta E_{idle} = 10000$ V m$^{-1}$ is the idling voltage, $D = 2000$ V m$^{-1}$ is the amplitude of the sweep, $\tau_1 = 5$ ns is the setup time and $\tau_3 = 110$ ns is the duration of the sweep. For the AC driving fields, we use the window functions from Eq. 8 and choose $E_a(t) = \lambda \cdot (255.2$ V m$^{-1}) \cdot |w^3(t - \tau_1 - \tau_2 + 5/2, \tau_2) + B_0(t) = \lambda \cdot (33.26$ mT$) \cdot |w^3(t - \tau_1 + \tau_2 + 5/2, \tau_2) + \tau_2 = \tau_1 + \tau_2 + \omega_E = \tau_0 - 2\pi \cdot 232.428$ MHz, $\omega_B = B_0 + 4 - 2\pi \cdot 217.096$ MHz. Squaring the window function produces pulses that turn on more gradually, improving adiabaticity. We include the free parameter $\lambda$ to control $\theta_1$; the amplitudes have been chosen so that $\lambda = 1$ gives $R_x(\theta_1)$, and $\lambda = 0$ must give $\theta_x = 0$ as the driving fields are off, so varying $\lambda$ in $(0,1)$ necessarily gives intermediate values of $\theta_x$. All other parameters are set to the values quoted at the beginning of Sec. IV. Plots of $\Delta E$ and the AC fields are given in Fig. 8.

Figure 8(a) shows the effect of quasi-static charge noise on both a naive $X$-gate as described earlier and on our noise-resistant $X$-gate. Both gates take roughly 140 ns, including the corrective $Z$-rotations at the beginning and end of the gate. The noise-resistant gate shows substantially better performance, with an error well below $10^{-3}$ for a noise with r.m.s. of 100 V m$^{-1}$.

The reason that even the naive $X$-gate scheme could
have such high fidelity without noise correction is that the large detunings and slowly-changing pulse envelopes ensure that the evolution is very nearly adiabatic. Using our corrected rotating-frame Hamiltonian $H'$ (see Appendix A), we can find the eigenstates in the middle of a gate’s evolution and examine the purity of the evolution operator in the computational subspace to quantify the adiabaticity. Doing so, we find that the $R_z(\theta)$ gates described above have leakage due to nonadiabaticity near or below $10^{-4}$ at any given point throughout the evolution. However, one complication with our scheme is the fact that if $\delta \approx 2\omega_E$ at some point while the oscillating electric field is on, there is a weak, sharp two-photon resonance that excites the $|g\rangle$ states to $|e\rangle$ states. The result of this is that, with our scheme, if $\Delta E$ is swept over too broad a range, there will be nonadiabaticity of order $10^{-2}$ and a discrepancy between the exact and approximate evolution. With our parameters, this occurs near $\Delta E = \pm 2500 \text{ V m}^{-1}$, so this limits the sweeping range of $\Delta E$.

We now consider the problem of a general, noise-resistant $R_z(\theta)$ gate. The challenge is to take our noise-vulnerable sweep gate, which gives an evolution of the form $R_z(\theta_{1z} + \theta'_{z1} \delta E) R_z(\theta_{2z} + \theta'_{z2} \delta E)$, and find a way to cancel the first-order error terms $\theta'_{z1} \delta E$. Once the errors are cancelled, the residual $\theta_{zi}$ terms can be removed by $R_z(\theta)$ gates as before, leaving only the $R_z(\theta_x)$.

For a given $\theta_x$, we can run simulations with different values of $\delta E$ and decompose the resulting gates to numerically find $\{\theta_{z1}', \theta_{z2}', \theta_{z2}'\}$. To apply this protocol in specific experiments, we can use numerical simulations to approximate these parameters, with further optimization using the physical system to account for error. We find that the first-order approximation for the noise-dependence of the $R_z(\theta)$ components of the decomposition is quite accurate (i.e. there is no need to include a $\theta'_{z1} \delta E^2/2$ term, for example), indicating that correcting noise to first-order should give a good noise-resistant gate.

The key ingredient in our approach will be a modified, noise-vulnerable $R_z(\theta)$ gate whose dependence on charge noise we use to cancel the noise in the sweep gate. If, in an $R_z(\theta)$ gate, we idle at a nominal value of $\Delta E = 0$ instead of $\Delta E \ll 0$ (a noise-vulnerable point instead of a noise-resistant point according to Fig. 2), we get a rotation error $R_z\left(\frac{\delta \omega_{\text{det}}}{\text{det}} \delta E\right)$ in addition to the normal $Z$ rotation. For idling times on the order of tens of ns, this produces an error that is comparable to the dephasing errors $\theta'_{z1}$. If these dephasing angles had the opposite sign as the $\theta'_{z1}$, the solution would be simple: one could apply a gate of this form before and after the sweep gate with the dephasing angles equal to $\theta'_{z1}$ to cancel the noise. However, the two types of error have the same sign. Our solution is to use the noise-resistant $R_z(\pi)$ we constructed earlier to flip the sign of this dephasing to use it to cancel the dephasing in the sweep gate. Here, we are again using $R_z(\theta_x) R_z(\pi) = R_z(\pi) R_z(\theta_x) = R_z(\theta_x)$.

The full noise-resistant gate is generated as follows:

$$R_z(\theta_x) = R_z(\theta_x - \nu_1) R_z(\nu_1 + \theta'_{z1} \delta E) X$$

$$R_z(\theta_x + \theta'_{z1} \delta E) R_z(\theta_x) R_z(\theta_{z2} + \theta'_{z2} \delta E) X R_z(\nu_2 + \theta'_{z2} \delta E) R_z(\theta_{z2} - \nu_2).$$

In creating this gate, first one chooses $\theta_x$, which fixes $\lambda$ and the second line of Eq. 11 which is a sweep gate. Next, the echo $R_z$ gates are adjusted to cancel the noise terms. All remaining phases are then cancelled by the corrective $R_z$ gates. In practice, one can avoid the corrective $R_z$ gates contained in the $X$-gates and simply absorb them into the main corrective $R_z$ gates. The majority of the gate duration comes from the three sweeping
gates, each contributing 120 ns to the total gate time of ∼450 ns. The noise-resistance of X-gates of various angles is plotted in Fig. [3]. For charge noise with a r.m.s. of 100 V m⁻¹, all have error near 10⁻³.

V. TWO-QUBIT GATES

The spin-charge hybridization obtained by the displacement of the electron from the donor towards the interface induces an electric dipole that can be used for long-range coupling between qubits via a dipole-dipole interaction. As with single-qubit gates, however, it is not obvious how to implement such a gate without leakage into the large two-qubit leakage space. Ref. [16] presents a method that uses an AC magnetic field to couple the nuclear spin qubit to the charge qubit, leading to an iSWAP gate. Here we show an alternative method, implementing a cPHASE gate between two qubits with only an AC electric field.

First, we must derive the dipole-dipole interaction term. The electric dipole operator of a qubit depends only on the electron orbital. We can write the dipole operator of qubit $k$ as

$$P_k = p_i \langle i | + p_d | d \rangle \langle d |,$$  \hspace{1cm} (12)

where $p_i$ and $p_d$ are the effective dipoles when the electron is in the $| i \rangle$ and $| d \rangle$ states, respectively. Because the electron is at the interface in the $| i \rangle$ state and generally near the donor nucleus in the $| d \rangle$ state, we expect $p_i \approx de$ and $p_d \approx 0$. We use these approximations for the remainder of this section for simplicity. The interaction energy of two qubits, 1 and 2, separated by a displacement $r$ is given by

$$V_{dip} = \frac{P_1 \cdot P_2 - 3(P_1 \cdot r)(P_2 \cdot r)/r^2}{4\pi \epsilon_0 \epsilon_r r^3},$$  \hspace{1cm} (13)

where $\epsilon_0$ is the vacuum permittivity and $\epsilon_r$ is the dielectric constant of the material ($\epsilon_r = 11.7$ for silicon). We assume that all qubits will be fabricated with their dipoles perpendicular to the surface on which they are arrayed. In this case $P_k \cdot r = 0$, so the interaction simplifies to

$$V_{dip} = \frac{e^2 d^2 |i_1 i_2 \rangle \langle i_1 i_2|}{4\pi \epsilon_0 \epsilon_r r^3}.$$  \hspace{1cm} (14)

We can then model the system with the Hamiltonian $H_{2q} = H \otimes 1 + 1 \otimes H + V_{dip}$. The lowest four eigenstates will be very similar to the tensor product of the individual qubit eigenstates without $V_{dip}$, so we call them \{$(\uparrow \uparrow), (\uparrow \downarrow), (\downarrow \uparrow), (\downarrow \downarrow)$\} and use them as the computational states. Our goal is to use the dipole-dipole interaction to implement a cPHASE gate between two adjacent qubits. We use a method similar to our $R_z(\theta)$ scheme: we use electric fields to cause an adiabatic evolution in which the four computational states shift in energy and accumulate phases without transitions between eigenstates.

The evolution operator $U$ at the end of the evolution will be of the form

$$U = e^{i\alpha|\uparrow \uparrow \rangle \langle \uparrow \uparrow| + e^{i\beta|\uparrow \downarrow \rangle \langle \uparrow \downarrow| + e^{i\gamma|\uparrow \downarrow \rangle \langle \uparrow \downarrow| + e^{i\delta|\uparrow \downarrow \rangle \langle \uparrow \downarrow|}.$$  \hspace{1cm} (15)

If we apply the local rotations $R_z(\gamma - \alpha)$ to qubit 1 and $R_z(\beta - \alpha)$ to qubit 2, and ignore a global phase of $(\beta + \gamma)/2$, we get

$$U' = |\uparrow \uparrow \rangle \langle \uparrow \uparrow| + |\uparrow \downarrow \rangle \langle \uparrow \downarrow| + e^{i(\alpha - \beta - \gamma + \delta)}|\uparrow \downarrow \rangle \langle \uparrow \downarrow|.$$  \hspace{1cm} (16)

Thus if $\phi \equiv \alpha - \beta - \gamma + \delta$ is nonzero, we obtain a cPHASE gate.

Assuming that the evolution will be adiabatic, we can find the angles $\alpha, \beta, \gamma, \delta$ and thus calculate $\phi$ using an expression similar to that of Eq. [7], where we integrate each state’s energy over the course of the evolution. Using our approximation, the energies are given by

$$E_{ab} \approx E_a + E_b + \frac{e^2 d^2}{4\pi \epsilon_0 \epsilon_r r^3} \cdot |\langle i|a\rangle|^2 \cdot |\langle i|b\rangle|^2,$$  \hspace{1cm} (17)

where $a \in \{\uparrow_1, \uparrow_2\}$ and $b \in \{\uparrow_2, \downarrow_2\}$. When one finds the equation for $\phi$, the $E_i$ terms cancel, and the result can be simplified to

$$\phi \approx \int_0^T dt \frac{-e^2 d^2}{4\pi \epsilon_0 \epsilon_r r^3} \cdot (|\langle i|\uparrow_1\rangle|^2 - |\langle i|\downarrow_1\rangle|^2) \cdot (|\langle i|\uparrow_2\rangle|^2 - |\langle i|\downarrow_2\rangle|^2).$$  \hspace{1cm} (18)

A key first question is how the dipole-dipole interaction affects the qubits while idling. For our choice of idling states, both qubit states have the electron in the $| g \rangle$ state, so $|\langle i|\uparrow_1\rangle|^2 = |\langle i|\downarrow_1\rangle|^2$. This implies that $\phi \approx 0$. Furthermore, even if only one qubit is idling, the corresponding factor in Eq. [18] will be zero, so there will still be no accumulated $\phi$. The fact that there is no entanglement when at least one of the qubits is idling is a major advantage of this choice of idling point and basis states.

Eq. [18] implies that both qubits’ two computational states must have different average dipoles in order for a nonzero $\phi$ to accumulate. We can achieve this with only oscillating electric fields at each qubit. The key ingredient is the fact that the two computational states have different ground-excited electron orbital splittings due to the hyperfine interaction: $E_{|\downarrow\uparrow\rangle} - E_{|\downarrow\downarrow\rangle} \approx \varepsilon_0 - A/4 + \langle A \rangle/2$, and $E_{|\uparrow\downarrow\rangle} - E_{|\uparrow\uparrow\rangle} \approx \varepsilon_0 + A/4 - \langle A \rangle/2$. Driving $E_{ac}$ for both qubits near, for example, the $|\downarrow\rangle$ state’s electron orbital transition energy but far detuned from the $|\uparrow\rangle$ state’s will give the $|\downarrow\rangle$ state a significant $|\epsilon\rangle$ component, creating a difference in dipole and leading to a nonzero $\phi$ according to Eq. [18].

To give an example of a square-pulse implementation of this idea, we assume a qubit spacing of $r = 500$ nm, and setting $E_a = 30$ V m⁻¹, $\omega_E = \varepsilon_0 + A/4 - \langle A \rangle/2 + 2\pi \cdot 5$ MHz, $B_a = 0$, $\Delta E = 2000$ V m⁻¹, while keeping the
other parameters the same as before, we find from $H'$ (see Appendix A) that $|f⟩ \approx 0.923|g \downarrow⟩ - 0.368|e \downarrow⟩$ and $|i⟩ \approx 0.711|g \downarrow⟩ - 0.703|e \downarrow⟩$: the $|i⟩$ state is driven closer to its electron orbital resonance and thus has a greater $|e⟩$ component. We have changed $ΔE$ from idling because in Eq. [5], the oscillating electric field is attenuated by a coefficient of $V_f/\varepsilon_0$, so decreasing $|ΔE|$ will allow a smaller driving electric field to achieve the same effect. We can now use Eq. [18] and the definitions of the $\{|g⟩,|e⟩\}$ states to find that $φ/T \approx 2τ \cdot 1.9$ MHz. This yields a $cz$ gate, with $φ = π$, implemented when $T = 494$ ns.

Performing a similar gate with realistic, smooth pulses is slightly more complicated due to the need to vary the AC electric field adiabatically and to the fact that the ground-excited splitting is changed slightly by the presence of a second qubit, requiring an adjustment in $ω_E$. Like the $R_2$ gate, we parameterize $cphase$ gates in terms of their total duration $T$ and calculate the resulting angle $φ$. We choose $ΔE(t) = ΔE_{idle} + l(t, τ_1, −ΔE_{idle} + D, τ_1 + τ_{ac}, −ΔE_{idle} + D, T)$, $E_a(t) = E_{\max} \cdot \sin(t−τ_1, τ_2, τ_{ac})$, and $ω_E = ϵ_0 + A/4 − ⟨A⟩/2 − 2π \cdot 10$ MHz, where $ΔE_{idle} = 10000$ V m$^{-1}$, $D = 2000$ V m$^{-1}$ is the value $ΔE$ moves to during the gate, $E_{\max} = (40$ V m$^{-1}) \cdot \min(1, (T3/300$ ns)$^2)$ is the max amplitude of $E_{ac}$, $τ_1 = 5$ ns is the setup time, $τ_{ac} = T − 2τ_1$ is the time when $ΔE$ is constant and $E_{ac}$ is nonzero, $τ_2 = \min(300$ ns, $andτ_{ac}/2)$ is the ramp-up time of $E_{ac}$. When $T$ is small, $E_{\max}$ is smaller to maintain adiabaticity, and the ramp-up time $τ_2$ must also be small to fit within $T$. These pulses are very similar in shape to those used for the sweep $R_2$ gate, except that here $B_{ac} = 0$ and $ΔE$ is constant for most of the duration of the gate.

Figure 10 shows the value of $φ$ of our $cphase$ gate as the gate duration varies. Including the local $Z$-rotations to correct the local phases, a $cz$ gate takes $≈ 500$ ns and an arbitrary $cphase$ gate takes less than $750$ ns, fast enough that hundreds or thousands of two-qubit gates can be implemented within the decoherence time.

To be truly practical, this $cphase$ gate scheme must have a degree of charge-noise-resistance. This is a significant challenge because of the requirement that the two states of each qubit have different but precisely known dipole moments. Charge noise $δE$ will lead to a perturbation of the form $−(δE/2h)τ_{id}^d$, which, taken to first order, will then perturb the energies of the two qubit states by different amounts. This change in the qubit energy splitting causes significant dephasing even for small $δE$. Finding a way to make this entangling gate scheme or an alternative scheme noise-resistant remains an open problem and will be the subject of future work.

VI. CONCLUSION

To conclude, we have introduced quantum control schemes to implement fast high-fidelity single- and two-qubit gates for $^{31}$P nuclear spin qubits in silicon. We presented protocols for implementing arbitrary $R_2(θ)$ and $R_x(θ)$ single-qubit gates, which can be combined to make an arbitrary, noise-resistant single-qubit gate in under $500$ ns. For typical charge noise levels of $100$ V m$^{-1}$, our procedure achieves fidelities over $99.99\%$ for arbitrary $Z$-rotations and fidelities over $99.9\%$ for arbitrary $X$-rotations. This is well above the threshold error rate of some quantum error correction codes, e.g., the surface code [25,26]. We choose a computational basis such that two qubits are only entangled when both are driven simultaneously, allowing for single-qubit gates to be performed without crosstalk from adjacent idling qubits. We also introduced a method for implementing two-qubit controlled-phase gates with arbitrary phases that take less than $750$ ns for an inter-qubit distance of $0.5$ μm, using only an oscillating electric field. These results are immediately relevant to ongoing experiments on donor-based nuclear spin qubits.

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Appendix A: Multi-Frequency Floquet Theory

This appendix shows how to use multi-frequency Floquet theory and second-order perturbation theory to find $H'$, an accurate time-independent approximation to the system Hamiltonian. The first step is to find $\{H_{ω_j}\}$, the frequency components of $H$ such that $H = \sum_j H_{ω_j} e^{iω_j t}$. The frequencies present are $\{ω_j\}_i = \{0, ±ω_E, ±2ω_E, ±2ω_B, ±(2ω_B − ω_E)\}$. $H_0$ is given in Section III and the rest are given by the following ex-
pressions, noting that $\tilde{H}_j = \tilde{H}^\dagger_j$:

$$\tilde{H}_{\omega_E} = \frac{A}{4}(S_x - iS_y)(I_x + iI_y) - \frac{B_a(t)\gamma_m}{4}(I_x + iI_y)$$

$$+ \left( \frac{A}{2} - \frac{A}{4} \right)(S_x - iS_y)(I_x + iI_y)$$

$$- AV_i(\sigma_x - i\sigma_y)S_z I_z + \frac{V_iB_0\gamma_{\Delta}\gamma}{4E_0}(\sigma_x - i\sigma_y)S_z$$

$$- \frac{d^2e^2\Delta E a(t)}{4\hbar^2 E_0}\sigma_z.$$

$$\tilde{H}_{2\omega_E} = -\frac{AV_i}{8\hbar}(\sigma_x - i\sigma_y)(S_x - iS_y)(I_x + iI_y)$$

$$- \frac{V_i\Delta E a(t)}{8\hbar E_0}(\sigma_x - i\sigma_y),$$

$$\tilde{H}_{2\omega_B} = -\frac{B_a(t)\gamma_m}{4}(I_x - iI_y).$$

(A1)

A system with one driving frequency can be analyzed in a time-independent way by considering a Floquet Hamiltonian $[27]$, an infinite Hamiltonian whose basis is the tensor product of the original basis with the space of integers, with each integer representing a Fourier component of the solution. When the RWA fails because the driving is strong, perturbation theory on the Floquet Hamiltonian can derive corrections (like in the Bloch-Siegert shift) that preserve the time-independent approximation. We do a similar process here, using the multi-frequency Floquet formalism given in Ref. [28].

First, we construct the multi-frequency Floquet Hamiltonian $H_F$. Because the base Hamiltonian is $8 \times 8$ and there are 9 distinct frequencies, the Floquet Hamiltonian will be $72 \times 72$. The diagonal will be populated with copies of $H_0$ shifted by unique frequencies - just the frequencies present in $H$ in our truncated approximation - and the off-diagonal will have the components of $H$ whose frequencies are the differences of the shifts of the matrices along the diagonal. $H_F$, truncated to one order in each frequency, is shown in Eq. (A2) in which each matrix element represents the corresponding $8 \times 8$ matrix. It will turn out that only the matrices that are part of the diagonal or the central row or column will matter to our approximation, but we include them all for completeness.

$$H_F = \begin{bmatrix}
\tilde{H}_0 - 2\omega_E & 0 & \tilde{H}_{-\omega_E} & 0 & \tilde{H}_{-\omega_b} + \omega_E & \tilde{H}_{-\omega_b} & 0 & 0 & 0 \\
0 & \tilde{H}_0 - 2\omega_B & \tilde{H}_{-2\omega_E} & \tilde{H}_{-2\omega_b} + \omega_E & \tilde{H}_{-2\omega_b} & 0 & 0 & 0 & 0 \\
\tilde{H}_{\omega_E} & \tilde{H}_{2\omega_b - \omega_E} & \tilde{H}_{\omega_b} & \tilde{H}_{2\omega_b} & \tilde{H}_{2\omega_b} & 0 & 0 & 0 & 0 \\
0 & \tilde{H}_{\omega_b} & \tilde{H}_{\omega_b} & \tilde{H}_{\omega_b} & \tilde{H}_{\omega_b} & 0 & 0 & 0 & 0 \\
0 & 0 & \tilde{H}_{2\omega_b} & \tilde{H}_{2\omega_b} & \tilde{H}_{2\omega_b} & 0 & 0 & 0 & 0 \\
0 & 0 & 0 & \tilde{H}_{2\omega_b} & \tilde{H}_{2\omega_b} & \tilde{H}_{2\omega_b} & 0 & 0 & 0 \\
0 & 0 & 0 & 0 & \tilde{H}_{2\omega_b} & \tilde{H}_{2\omega_b} & \tilde{H}_{2\omega_b} & 0 & 0 \\
0 & 0 & 0 & 0 & 0 & \tilde{H}_{2\omega_b} & \tilde{H}_{2\omega_b} & \tilde{H}_{2\omega_b} & 0 \\
H_{-2\omega_E} & 0 & 0 & 0 & 0 & 0 & 0 & \tilde{H}_{0} + 2\omega_E
\end{bmatrix}
$$

(A2)

If we note that the eigenvalues of $H_0$ will be much smaller than either $\omega_E$ or $\omega_B$ (by a factor of over $\sim 10$ with our parameters), the dynamics can be easily approximated. The matrices along the diagonal are all very well-separated in energy from $H_0$, so we can treat all the off-diagonal elements in $H_F$ as a perturbation and derive an effective $H_0$ using second-order quasi-degenerate perturbation theory, also called a Schrieffer-Wolff transformation [29].

We choose the 8-dimensional subspace through the unshifted $H_0$ at the center of $H_F$ as the target subspace of the Schrieffer-Wolff transformation. We now define $H_{(0)}^{(0)}$ as the diagonal (the diagonal, not just a block diagonal) of $H_F$, and define the perturbation $H_F'$ so $H_F = H_{(0)}^{(0)} + H_F'$. Our goal is to apply a small transformation such that the target subspace becomes decoupled from the rest of the Floquet Hamiltonian, leaving an effective Hamiltonian $H_{eff}$. As derived in Ref. [29] this is given by

$$H_{eff} = H^{(0)} + H^{(1)} + H^{(2)} + \ldots,$$

(A3)

where

$$H_{mm'}^{(0)} = H_0^{F_{mm'}},$$

$$H_{mm'}^{(1)} = H_{F_{mm'}},$$

$$H_{mm'}^{(2)} = \frac{1}{2} \sum_l H_{F_{ml}} F_{l_{ml}} \left[ \frac{1}{E_m - E_l} + \frac{1}{E_{m'} - E_l} \right],$$

(A4)

where the states $m$ and $m'$ are states within the target subspace and $E_l$ is the energy of state $l$ before the perturbation, which is simply $H_0^{(0)}$ because $H_0^{(0)}$ is diagonal. Note that $H^{(0)}$ is just the diagonal of $H_0$ and $H^{(1)}$ is the off-diagonal, so $H^{(0)} + H^{(1)} = H_0$. Summing the 0th-, 1st- and 2nd-order terms in $H_{eff}$ gives $H'$, the accurate, time-independent approximation mentioned in Section III, with typical fidelity $> .9999$ to the exact evolution for our gates.
Appendix B: Qubit Dephasing Rates

We here derive the dephasing rate of the qubit in our scheme due to charge noise. The critical value is the derivative of the qubit energy difference with respect to the electric field,

$$\frac{d\delta_q}{d\Delta E} = -\frac{AdV_i^2}{4\hbar\varepsilon_0^2}. \quad (B1)$$

When \(d\Delta E/\hbar \gg V_i, \varepsilon_0 \approx d\Delta E/\hbar\), so the above equation simplifies to

$$\frac{d\delta_q}{d\Delta E} \approx -\frac{A\hbar^2 V_i^2}{4d^2\varepsilon_0^2\Delta E^3}. \quad (B2)$$

With our idling parameters, this is \(2\pi \cdot 70\) Hz/V m\(^{-1}\), so assuming a typical noise in \(\Delta E\) of 100 V m\(^{-1}\) gives a dephasing time on the order of 0.1 ms.

Appendix C: Effect of a Time-Dependent \(|g, e\rangle\) Basis

When we transform the system Hamiltonian from the \(|i\rangle, |d\rangle\) basis to the \(|g\rangle, |e\rangle\) basis in Section II, we treat \(\Delta E\) as static and don’t include a \(-i\tilde{\Lambda}\dagger\) term for that change of basis, even though \(\Delta E\) is not constant during gates. Here we give that correction and show that it is negligible, a conclusion which we checked by comparing our simulations to simulations in the original \(|i\rangle, |d\rangle\) basis.

The transformation from the \(|i\rangle, |d\rangle\) basis to the \(|g\rangle, |e\rangle\) is given by

$$\Lambda = \frac{1}{\sqrt{2}} \left[ \sqrt{1 + \frac{d\Delta E}{\hbar\varepsilon_0}} \right] - i\frac{\hbar}{\sqrt{2}} \left[ \frac{d\Delta E}{\hbar\varepsilon_0} \right]^{\sigma_y}. \quad (C1)$$

yielding

$$-i\Lambda\dagger = \frac{dV_i}{2\hbar\varepsilon_0^2}\sigma_y \cdot \frac{d\Delta E}{dt}. \quad (C2)$$

The factor \(dV_i/2\hbar\varepsilon_0^2\) reaches a maximum of \(2 \times 10^{-3}\) m V\(^{-1}\) when \(\Delta E = 0\).

There are two situations where this extra term could be problematic. First, during the very rapid shifts in electric field at the start and end of the Z- and X-rotations, the large term could cause unwanted \(|g\rangle - |e\rangle\) coupling. Second, in the middle of an X-rotation, the system dynamics are fairly sensitive to the detunings between states, so a smaller added term from the more-slowly changing electric field could be problematic.

For the first case, at maximum, \(|d\Delta E/dt| \sim 10^{13}\) V m\(^{-1}\) s\(^{-1}\), so Eq. \([C2]\) is of order \(2\pi \cdot 1\) GHz, while \(\varepsilon_0 \sim 2\pi \cdot 5\) GHz. This term is big enough to be problematic if it were turned on suddenly, but the fact that it waxes and wanes over the course of several ns preserves adiabaticity, and it is only large for a very short time, so it does not significantly affect the gate.

In the second case, in the middle of an X-rotation, the term is of order \(2\pi \cdot 5\) MHz. This is two orders of magnitude smaller than the detunings and much smaller than the energy splitting \(\varepsilon_0\) of the states it couples. If it were included in the derivation of \(H’\), it would only contribute as a small correction. We have confirmed that it does not significantly affect the results of our simulations.

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