Automatic Integral Reduction for Higher Order Perturbative Calculations

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ABSTRACT: We present a program for the reduction of large systems of integrals to master integrals. The algorithm was first proposed by Laporta; in this paper, we implement it in MAPLE. We also develop two new features which keep the size of intermediate expressions relatively small throughout the calculation. The program requires modest input information from the user and can be used for generic calculations in perturbation theory.

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1. Introduction

Perturbation theory is an indispensable calculational tool in particle physics. Methods for perturbative calculations have been developed concurrently with the introduction of field theories for describing particle interactions. It is not surprising that we already have very efficient tools which confront experimental data at a quantitative level.

It is evident, however, that the current methods are not suitable for computing with sufficient accuracy all the required cross-sections at modern experiments. At the LHC or a future Linear Collider, for example, we must study a number of new complicated processes in the Standard Model or other theories. In addition, small effects arising at higher orders in perturbation theory will become significant in these experiments. It is important for such studies to improve or replace methods which require substantial human intervention. Ideally, we should develop automated methods applicable to every process, theory, and order in the perturbative expansion.

Two types of computations are generally required for the evaluation of cross-sections and decay rates: loop integrations over the momenta of virtual particles, and phase-space integrations over the momenta of particles in the final state. At higher orders in perturbation theory both tasks are hard; this is primarily due to the large number of integrals which typically appear. Unfortunately, methods for the analytic computation of loop and phase-space integrals are complicated; it is usually unrealistic to attempt a brute-force computation for all terms in the matrix-elements. A solution to this problem is to construct algorithms which reduce the number of integrals to a few master integrals, and calculate directly the master integrals only.

The method of integration by parts (IBP) for the reduction of loop integrals was introduced in [2, 1]. Integrals which have common propagators (or, equivalently, belong to the same topology) satisfy linear algebraic identities. These identities can be derived with the IBP method and can be cleverly combined to produce reduction identities to master integrals. Gehrmann and Remiddi introduced a new class of identities for scalar loop integrals due to their invariance under Lorentz transformations [3]. Lorentz invariance (LI) identities are particularly useful for multiloop integrals with many external legs and massive propagators. Recently, the method of IBP and LI identities was extended to phase-space integrals that appear in the evaluation of total cross-sections [4, 5] and various differential distributions [6, 7, 8].

Because of its conceptual simplicity, the IBP method was used to construct reduction algorithms for many classes of multi-loop integrals (see for example [9, 10, 11, 12, 13]). Nevertheless, the construction of such programs was laborious and a systematic approach to produce reduction identities for arbitrary topologies was not available; this was the main reason for the rather slow pace of multiloop calculations.

This situation is now improved due to Laporta, who has proposed a fully automated method for the reduction of generic loop amplitudes [14]. In contrast to
earlier approaches, his method does not attempt to derive reduction identities applicable to all the integrals of a topology. Instead, the aim is to reduce one-by-one the integrals by solving a large system of IBP/LI equations. This is achieved using Gauss elimination, after the IBP/LI system is ordered according to the complexity of the equations. Starting from the simplest one, each IBP/LI equation of the system is rearranged following a few algorithmic rules: the terms of the equation are assigned a relative weight for their complexity, and the most complicated term is then isolated on the left hand side. A recursive application of this procedure leads to expressions for complicated loop integrals in terms of master integrals.

The algorithm proposed by Laporta has already been used in a variety of calculations (for example in [15, 16, 17, 4, 5, 18, 19, 20, 7, 8, 21, 22, 23]). However, we have found that its efficient implementation in a computer program is not trivial. The main difficulties arise from the fact that typical multiloop calculations, such as the ones mentioned earlier, require an enormous number of IBP/LI equations ($10^5 - 10^6$). In the process of Gauss elimination the algorithm can produce very large expressions; one must optimize for their efficient manipulation.

In this paper, we provide a MAPLE 9 [24] computer program (AIR) based on the method of [14], for the Automatic Integral Reduction at higher orders in perturbation theory. The user should supply template IBP/LI equations for the integrals of a topology, optional information on the vanishing integrals of the topology and the master integrals (if known), and a small number of parameters controlling the treatment of large expressions. There is no need for advanced knowledge of the MAPLE platform. The input can be supplied with easy to modify text files, and AIR can be controled with very simple scripts.

We believe that theorists who do not wish to invest in studying and implementing reduction methods, but need to study higher order effects in perturbation theory for various physical processes, will find this to be a valuable tool. We also hope that this publication will initiate some activity and exchange of ideas on practical issues concerning the implementation of reduction algorithms. In this program, we have implemented computational tricks which were developed during practical computations; we hope our program will be improved from the experience of other users.

The cost in computer resources grows rapidly with the complexity of the study process. It is inevitable that AIR will fail to solve arbitrarily large systems of equations with large number of symbolic parameters (corresponding to kinematic scales, dimension, etc). However, we do expect AIR to be used for many applications in particle phenomenology beyond the current state-of-the-art. For this purpose, we have included routines which minimize the number of computations during the reductions, mainly by keeping the number and the size of the actively processed expressions for Gauss-elimination to a minimum.

In Section 2 we review the main features of the algorithm of Laporta using the massless one-loop box integral as a pedagogical example. In Section 3, we explain
the main features of AIR. In the rest of the paper we demonstrate the usage of AIR through examples. In Section 4 we reduce the massless one-loop box topology with no special algorithms activated for handling large expressions. In Section 5 we repeat the reduction by activating a “masking” algorithm which reduces the amount of computations during Gauss elimination by storing away the expressions which get reduced in terms of master integrals. In Section 6 we apply a different masking algorithm for very large integral coefficients. In Section 7 we show how to reduce topologies with a very large number of kinematic scales, by switching off simplification routines. We use the reduction of the massless one-loop pentagon topology as an explicit example. Finally, we present our conclusions in Section 8.

2. The reduction algorithm

In this Section we present the reduction algorithm which is used in our program. A detailed description of the algorithm can also be found in Ref. [14]. Here we will present its main features using the massless one-loop box topology as an explicit example.

We consider the class of integrals:

$$B(\nu_1, \nu_2, \nu_3, \nu_4) = \int \frac{1}{[k^2]^{\nu_1} [(k+p_1)^2]^{\nu_2} [(k+p_{12})^2]^{\nu_3} [(k+p_{123})^2]^{\nu_4}},$$

(2.1)

where we have introduced the shorthand notation $p_{i...k} = p_i + p_j + \ldots + p_k$. The terms in the denominator are raised into positive or negative integer powers $\nu_i$. Zero powers correspond to scalar triangle and bubble integrals; negative powers correspond to triangle and bubble integrals with irreducible numerators. The external momenta are all taken to be light-like, $p_1^2 = p_2^2 = p_3^2 = p_{123}^2 = 0$. These integrals arise in one-loop QCD amplitudes for $2 \rightarrow 2$ scattering processes (e.g. $gg \rightarrow gg$ [25]).

It will be useful to know the values of the parameters $\nu_i$ for which the corresponding integrals vanish (tadpoles, scale-less bubbles). This information is not formally required; by solving the IBP equations one will eventually find that tadpoles, etc, are indeed vanishing. However, it is more efficient for the reduction to utilize the
fact that many terms in the IBP equations are zero. We find the following vanishing integrals:

\[ B(v_1, v_2, v_3, v_4) = 0, \]  

if

\[ \Theta(v_1) + \Theta(v_2) + \Theta(v_3) + \Theta(v_4) < 2, \]  

or

\[ \Theta(v_1) + \Theta(v_2) = 0, \]  

or

\[ \Theta(v_2) + \Theta(v_3) = 0, \]  

or

\[ \Theta(v_3) + \Theta(v_4) = 0, \]  

or

\[ \Theta(v_4) + \Theta(v_1) = 0, \]  

where we define \( \Theta(x) = 1 \) for \( x > 0 \) and \( \Theta(x) = 0 \) for \( x \leq 0 \).

Now we proceed to find algebraic equations for the integrals of the box topology. An easy way to derive such identities is the IBP method [1, 2]; we multiply the integrand with a loop or external momentum and differentiate it with the loop momentum. These total derivatives integrate to zero:

\[ 0 = \int \frac{d^d k}{\partial k_\mu} \frac{\eta_\mu}{[k^2]^{\nu_1} [(k + p_1)^2]^{\nu_2} [(k + p_{12})^2]^{\nu_3} [(k + p_{123})^2]^{\nu_4}}, \]  

where \( \eta = k, k + p_1, k + p_{12}, k + p_{123} \). We obtain four IBP identities:

\[ T_1 : 0 = \left[ s v_1 1^+ + (d - v_{1234}) - \left( v_1 1^+ + v_2 2^+ + v_4 4^+ \right) 3^- \right] B \]  

\[ T_2 : 0 = \left[ t v_2 2^+ + (d - v_{1234}) - \left( v_1 1^+ + v_2 2^+ + v_3 3^+ \right) 4^- \right] B \]  

\[ T_3 : 0 = \left[ s v_3 3^+ + (d - v_{1234}) - \left( v_2 2^+ + v_3 3^+ + v_4 4^+ \right) 1^- \right] B \]  

\[ T_4 : 0 = \left[ t v_4 4^+ + (d - v_{1234}) - \left( v_1 1^+ + v_3 3^+ + v_4 4^+ \right) 2^- \right] B \]  

where the action of \( 1^+ \) \( 1^- \) increases (decreases) \( v_i \) by one in the integral \( B \), e.g.

\[ 3^\pm B = B(v_1, v_2, v_3 \pm 1, v_4). \]  

Products of operators have a straightforward interpretation, e.g.

\[ 3^+ 1^- B = B(v_1 - 1, v_2, v_3 + 1, v_4). \]  

We have also used the shorthand: \( \nu_{ijjk...} = \nu_i + 2\nu_j + \nu_k + ... \), and we define the usual Mandelstam variables \( s = p_{12}^2, t = p_{23}^2 \).

The IBP Eqs. 2.9-2.12 and, optionally, the results of Eqs. 2.3-2.7 are sufficient to reduce any integral of the box topology to master integrals by using the algorithm
of Laporta [14]. In Ref. [14], the reader can find a detailed and complete description of the algorithm; here we intend to emphasize its salient features. The user is not required to have knowledge of the algorithm, however, some familiarity will be beneficial. We will describe the algorithm by tracing the first steps of our code when solving the box topology. For concreteness, we will stop when the integral $B(1, -1, 1, 0)$ is reduced in terms of master integrals.

- **Seed generation:** The program starts with the simplest list $(\nu_1, \nu_2, \nu_3, \nu_4)$ for which $B(\nu_1, \nu_2, \nu_3, \nu_4)$ is not vanishing,

$$S_1 : (\nu_1, \nu_2, \nu_3, \nu_4) = (1, 0, 1, 0). \quad (2.15)$$

$S_1$ will be our first 'seed' for generating identities from the topology IBP equations $T_1, \ldots, T_4$ (Eqs. 2.9-2.12), which we use as templates.

- **Identities generated from the template IBP equations:** Our first identity is Eq. $T_1$ substituting the values of $\{\nu_i\}$ found in $S_1$:

$$E_1^1 : sB(2, 0, 1, 0) + (d - 3)B(1, 0, 1, 0) = 0. \quad (2.16)$$

In $E_1^1$, we have already used our knowledge for the vanishing integrals of the topology (Eqs. 2.3-2.7).

The above equation can be recast to express one of the two integrals in terms of the other. We would like to use such equations to express more complicated integrals in terms of simpler ones and, finally, in terms of the master integrals. It is therefore necessary to introduce criteria for the complexity of the integrals; the most complicated should receive first priority and will be isolated in the left hand side.

- **Integral priority criteria:** We check on three parameters in order to isolate the most complicated integral. First we select the integrals with the largest number of propagators:

$$N_{prop} = \sum_i \Theta(\nu_i). \quad (2.17)$$

If more that one integral has the maximum $N_{prop}$, we select the one with the largest sum of positive indices $\nu_i$

$$N_+ = \sum_i \Theta(\nu_i)(\nu_i - 1). \quad (2.18)$$

If more than one integral has the maximum values of $N_{prop}$ and $N_+$, we select the one with the largest sum for the magnitudes of negative indices $\nu_i$

$$N_- = -\sum_i \Theta(-\nu_i)\nu_i. \quad (2.19)$$

If still there is an ambiguity, we randomly choose one of the integrals which has survived all three criteria.
• **Rearranging the identities:** Following the previous criteria, we find that \( B(2, 0, 1, 0) \) is the most complicated integral in \( E_1 \). We then rearrange the identity to produce:

\[
E_1^1 : B(2, 0, 1, 0) = \frac{3-d}{s} B(1, 0, 1, 0).
\]

We proceed, in the same manner, with the remaining identities \( T_2, T_3, T_4 \) for \( S_1 \). We obtain:

\[
E_2^2 : B(2, 0, 1, -1) = (d-2)B(1, 0, 1, 0) - B(1, 0, 2, -1),
\]

\[
E_3^3 : B(1, 0, 2, 0) = \frac{3-d}{s} B(1, 0, 1, 0),
\]

and

\[
E_4^4 : B(2, -1, 1, 0) = (d-2)B(1, 0, 1, 0) - B(1, -1, 2, 0).
\]

• **Seed priority criteria:** We have now processed all IBP equations for the first seed \( S_1 \). It is therefore necessary to choose a new seed to obtain more identities. It is important to choose seeds that are most likely to produce equations coupled with the ones which have been processed earlier. For this purpose, we could select the seeds with the opposite priorities than the integral priorities, i.e. the seed with successively minimum values for \([N_{prop}, N_-, N_+]\). However, the rules for choosing the seeds are mostly empirical and require some experimentation. In fact, the order for applying the criteria for minimum \( N_- \) and \( N_+ \) can be judiciously chosen according to the class of integrals that the user needs to compute. For example, we could now pick either \((1, -1, 1, 0)\) or \((2, 0, 1, 0)\) as the next seed. Since our goal is to compute \( B(1, -1, 1, 0) \) it is better to choose:

\[
S_2 : (\nu_1, \nu_2, \nu_3, \nu_4) = (1, -1, 1, 0).
\]

which in the IBP equations generates integrals with the same structure as the one we want to solve. Our program generates the seeds automatically; the user must provide the range of \( N_{prop}, N_-, N_+ \) as input. It is relatively straightforward to decide the values for these parameters by inspecting the integrals that are required in the study process.

• **Substitutions and Gauss-Elimination:** We now find a new feature in Eq. \( T_1 \) for the seed \( S_2 \):

\[
E_2^1 : sB(2, -1, 1, 0) + (d-2)B(1, -1, 1, 0) = 0.
\]

The integral \( B(2, -1, 1, 0) \) is isolated at the left hand side (lhs) of a previous equation (\( E_1^1 \)). In such cases, we eliminate the known integral from the
equation. Substituting Eq. 2.23, and applying the integral priority criteria, we have:

\[ E_2^1 : B(1, -1, 2, 0) = \frac{d - 2}{s} B(1, -1, 1, 0) + (d - 2) B(1, 0, 1, 0) \]  \hspace{1cm} (2.26)

- **Back-substitution:** \( E_2^1 \) is solved in terms of an integral that can be substituted back to \( E_4^1 \). We can now see how the Laporta algorithm works in practice; by adding new equations to the already solved equations we form new subsystems of coupled equations which eliminate previously unknown integrals. In our example, performing the substitution of \( E_2^1 \) into \( E_4^1 \) we obtain,

\[ E_4^1 : B(2, -1, 1, 0) = \frac{2 - d}{s} B(1, -1, 1, 0). \]  \hspace{1cm} (2.27)

We process two more equations for the seed \( S_2 \):

\[ E_2^2 : B(2, -1, 1, -1) = -t B(1, 0, 1, 0) + (d - 1) B(1, -1, 1, 0) \]
\[ + B(1, 0, 1, -1) - B(1, -1, 2, -1), \]  \hspace{1cm} (2.28)

and

\[ E_2^3 : B(1, -1, 1, 0) = -\frac{s}{2} B(1, 0, 1, 0). \]  \hspace{1cm} (2.29)

In the last equation we have computed the integral that we wanted in terms of a simpler one: \( B(1, 0, 1, 0) \). It is clear from the previous equations that \( B(1, 0, 1, 0) \) is a master integral.

In summary, the algorithm requires the successive generation of identities with terms of increasing complexity. The newly added equations usually contain terms which are also found in equations generated at earlier stages; this produces small subsystems of coupled algebraic identities. A series of substitutions diagonalizes these algebraic subsystems and yields complicated integrals expressed in terms of master integrals. The algorithm is a clever implementation of Gauss elimination. It exploits the fact that Feynman integrals can be ordered according to very simple criteria.

We demonstrated how the algorithm reduces a number of integrals belonging to the massless one-loop box topology. However, there was no step in the previous reduction that depended on the specifics of the topology. Therefore, this algorithm is suitable for the reduction of generic multiloop integrals or, more generally, of parametric functions which satisfy coupled algebraic identities (e.g. hypergeometric functions).

3. **Features of AIR**

In this Section we describe the basic functions of our program. The program is included as a gzipped and tarred file in the source submission of the electronic preprint.
for this paper, and can also be downloaded from Ref. [26]. It is convenient to unzip
and untar the distribution file in a directory where AIR can be located permanently.

```
/home> tar -zxvf air.tar.gz
AIR/
AIR/main.map
AIR/BOXA/
AIR/BOXA/input_boxa.map
AIR/BOXA/script_boxa.map
AIR/BOXB/
AIR/BOXB/input_boxb.map
AIR/BOXB/script_boxb.map
AIR/BOXC/
AIR/BOXC/input_boxc.map
AIR/BOXC/script_boxc.map
AIR/Pentagon/
AIR/Pentagon/input_pentagon.map
AIR/Pentagon/script_pentagon.map
AIR/Pentagon5/
AIR/Pentagon5/input_pentagon.map
AIR/Pentagon5/script_pentagon.map
```

The distribution includes the program file `main.map`, input files `input-...map`, as well as MAPLE scripts `script-...map` for the example reductions in the rest of
the paper. The program consists of MAPLE routines for generating seeds for the
template IBP/LI identities, finding integral priorities, generating the IBP equations
from the seeds, performing Gauss-elimination, masking large integral coefficients and
reduced expressions, performing nested substitutions, and collecting the results. The
function of the more important routines will be detailed in the following Sections.

In typical multiloop computations, a large number of identities should be pro­
cessed. A database system is therefore required to access, modify, and store the
equations. We have implemented a rather simple database system, where each IBP
equation is stored in a single file; the name of the file is determined by the integral
on the lhs of the equation. We also create separate auxiliary files which serve to
point to the equations in the IBP system where a particular integral can be found.
Our database system is very robust; however, it creates a rather extended tree of
directories which usually contain very short ASCII files.

The program can perform very complicated multiloop reductions. It is often
possible to simplify all the terms in the IBP equations as they get substituted and
rearranged for Gauss elimination. However, if the topology depends on many kine­
matic scales, or the IBP equations are loosely coupled (creating large subsystems of
equations before they get diagonalized), or the values for $N_{prop}, N_{\pm}$ are large, it may
not be feasible to perform all simplifications within acceptable times or the available memory. We have implemented two algorithms to perform the reductions efficiently and reduce the amount of computations; the algorithms can be used independently or in conjunction.

The first algorithm masks subexpressions which are reduced in terms of master integrals. The program detects the reduced expressions, stores them in files, and replaces them by an indexed symbol. Thus, the masked expressions are protected from subsequent manipulations during Gauss elimination. This feature is implemented recursively; whenever a new expression is written in terms of masked expressions and/or master integrals, the new expression is also masked. At the end of the reduction, a series of nested substitutions is required in order to rewrite the masked expressions in terms of the master integrals. We will discuss the required nested substitutions later; for now, we should note that the masking algorithm reduces significantly the amount of computations during the process of Gauss elimination. The algorithm requires that the master integrals of the topology are known. To determine them, one can perform a less involved reduction for relatively small values of \( \mathcal{N}_\pm \) without using the masking algorithm. When the master integrals are found, the user can repeat the reduction for larger values of \( \mathcal{N}_\pm \), activating the masking algorithm.

The second algorithm aims to reduce the size of the equations by masking all integral coefficients which are lengthier than a user-defined maximum value. During Gauss-elimination, however, some integral coefficients vanish; the elimination cannot take place if the coefficients contain masked expressions. To solve this problem we check numerically for cancelations. The user needs to provide as input, numerical values for all the parameters (kinematic scales, dimension) which enter in the symbolic expressions for the integral coefficients of the IBP/LI equations. The masking algorithm substitutes these numerical values and stores both the numerical result and the symbolic expression for the coefficients. The program determines if a coefficient is zero by inspecting the numerical result, thus, avoiding complicated symbolic manipulations. To ensure that cancelations are not accidental, the program can perform the numerical testing of the values of the coefficients for more than one choices of numerical values for the kinematic parameters and the dimension. The analytical value of the lengthy coefficients is computed at the end of the reduction, and only for the integrals that are required for practical purposes.

The purpose of the two algorithms is to remove complications from the symbolic manipulation of very large expressions. However, after Gauss-elimination we must still perform computations which were deferred by using the masking algorithms, i.e. we must perform a series of nested symbolic substitutions for the used alias symbols in order to compute the masked expressions explicitly in terms of the kinematic parameters, the dimension, and the master integrals. It is possible to imagine that this additional computation is as difficult as using the program without the masking.
algorithms, where all substitutions take place explicitly during Gauss elimination. This is not the case; usually, only a fraction of the total number of masked expressions is required for the integrals that appear in the matrix-elements of a physical process. For example, the integral $B(2, -1, 1, 0)$ of the previous Section does not appear in the computation of e.g. $gg \rightarrow gg$, however, it appears in the IBP equations. By using the masking algorithms, we avoid computing the masked expressions for many such integrals.

The remaining nested substitutions can still be challenging for very complicated problems. One can resort to tricks such as expanding in the dimension parameter [9] or in kinematic parameters (e.g. electron mass in Bhabba scattering), if this is justified from the physics of the process. However, this is rarely needed; there are many processes where we can perform the substitutions without giving up on a valid evaluation of the integral coefficients for all values of the kinematic parameters and the dimension. AIR includes general purpose routines for a straightforward computation of recursive substitutions; these routines attempt a brute-force symbolic simplification of all the intermediate expressions. It also provides the option to switch off simplification of expressions that exceed a maximum length or, if necessary, to transfer the most complicated substitutions to another platform, e.g. FORM [27].

In the following Sections we perform four example reductions which can serve as a tutorial for using AIR and its main features. A technical description of the AIR routines can be found in [26]. The source code of the program is openly distributed; the users are free to modify it. The authors will be grateful to receive suggestions and constructive feedback.

4. Reduction with no masking

We now perform the reduction of the massless one-loop box topology. In this Section we do not activate any of the two masking algorithms. The input file and the corresponding script for the reduction can be found in the directory:

/home/AIR/BOXA

The input file for the reduction is named input_boxa.map. It contains variables which are used globally by AIR. These are:

```plaintext
ibp_equations:= [  
-nu3*B(nu1-1,nu2,nu3+1,nu4) -nu4*B(nu1-1,nu2,nu3,nu4+1)  
-nu2*B(nu1-1,nu2+1,nu3,nu4) +nu3*s*B(nu1,nu2,nu3+1,nu4)  
+(-nu3-nu2-2*nu1+d-nu4)*B(nu1,nu2,nu3,nu4),  
nu4*t*B(nu1,nu2,nu3,nu4+1)-nu3*B(nu1,nu2-1,nu3+1,nu4)  
+(d-2*nu2-nu3-nu4)*B(nu1,nu2,nu3,nu4)  
-nu4*B(nu1,nu2-1,nu3,nu4+1)-nu1*B(nu1+1,nu2-1,nu3,nu4),
```


\[-\nu_1 B(nu_1 + 1, nu_2, nu_3 - 1, nu_4) + (-\nu_2 + d - nu_4 - nu_1 - 2*nu_3)\]
\* B(nu_1, nu_2, nu_3, nu_4) - nu_4 B(nu_1, nu_2, nu_3 - 1, nu_4 + 1)
\- \nu_2 B(nu_1, nu_2 + 1, nu_3 - 1, nu_4) + nu_1 s B(nu_1 + 1, nu_2, nu_3, nu_4),
\- nu_1 B(nu_1 + 1, nu_2, nu_3, nu_4 - 1) - nu_2 B(nu_1, nu_2 + 1, nu_3, nu_4 - 1)
\- nu_3 B(nu_1, nu_2, nu_3 + 1, nu_4 - 1) + nu_2 t B(nu_1, nu_2 + 1, nu_3, nu_4)
\+ (-\nu_3 + d - nu_2 - nu_1 - 2*nu_4) B(nu_1, nu_2, nu_3, nu_4) \]

- This is a list of template IBP identities (Eqs. 2.9- 2.12) for the box topology. The program reads off some additional implicit definitions from the structure of the IBP equations. For example, it is now defined that the name of the topology is ‘‘B’’ and the powers of the propagators are defined through the variables nu1, nu2, nu3, nu4.

```
ZERO_TOPOLOGIES := [
  ThetaF(nu1) + ThetaF(nu2) + ThetaF(nu3) + ThetaF(nu4) < 2,
  ThetaF(nu1) + ThetaF(nu2) = 0,
  ThetaF(nu2) + ThetaF(nu3) = 0,
  ThetaF(nu3) + ThetaF(nu4) = 0,
  ThetaF(nu4) + ThetaF(nu1) = 0,
  NULL];
```

- This is a list of statements (Eq. 2.3-2.7) which undergo boolean evaluation when the propagator powers are substituted by integers. If any of the statements is true, then the corresponding integral is set to zero.

```
MASTERS := []:
```

- This variable activates the algorithm for masking reduced expressions to master integrals. It contains a list of known master integrals. In this example, we do not want to activate the algorithm; therefore we define the above variable to be an empty list.

```
check_values := []:
```

- This variable activates the masking algorithm for integral coefficients which exceed a maximum value. It should contain numerical values for all the kinematic parameters and the dimension in the IBP/LI equations. For this example, we do not want to activate the masking algorithm and we set the variable to an empty list.

```
MAXLENGTH := 1000:
```
• This variable is used by the masking algorithm for large integral coefficients. It defines the maximum length for a coefficient in order not to get masked. The length of an expression is measured by the number of characters in the expression and is determined by a MAPLE routine. The value of the variable is irrelevant if the check_values list is empty.

\[ \text{MAXSIMPLIFY} := 10^{10} : \]

• This variable is used by the routines which perform nested substitutions for the masked expressions and the routines which display the final results. It sets a maximum length for the expressions that MAPLE is allowed to simplify. Larger expressions get substituted but not simplified.

\[ \text{MAPLEMAXSUB} := 10^{10} : \]

• This variable is used by the routines which perform nested substitutions of masked expressions, and the routines which display the results. It sets a maximum length for the expressions that MAPLE is allowed to substitute. Larger expressions are not written explicitly and are kept masked. In this reduction we want all coefficients to be explicit, and we set the value of the variable to a practically unreachable value.

\[ \text{VERBOSE} := \text{FALSE} : \]

• This variable is used to display information about the progress of the program. If set to TRUE, the program outputs on the screen the seed that is processing, or, after Gauss-elimination is completed, the index of the masked expression that is evaluating.

The file \texttt{script.boxa.map} contains all the calls to AIR for reducing the box topology. We can run the script from the shell command line:

\[
\text{/home/AIR/BOXA> maple script.boxa.map}
\]

It will be more instructive for this first application to call the routines interactively from within the MAPLE platform. We first launch MAPLE,

\[
\text{/home/AIR/BOXA> maple}
\]

and load the input for the topology and the main program:

\[
> \text{currentdir(''/home/AIR/BOXA'')}:
> \text{read 'input.boxa.map'}:
> \text{read ';/home/AIR/main.map'}:
\]
The user should now perform the following tasks:

- **Seed generation:** We create a list with sets of integers for deriving IBP equations from the template equations of `ibp.equations`. This is accomplished by calling the routine

  \[
  \text{SEEDGEN(“filename”, maxtop, [minNprop,maxNprop], [minNminus, maxNminus], [minNplus, maxNplus]) ;}
  \]

  The first argument is the filename where the seeds will be written. The next argument, `maxtop`, is a list with integers \( \{i\} \) denoting the propagators raised to positive powers \( \{v_i^\} \) in the seed with the highest priority. For example, if we are interested in reducing all the integrals of the box topology and all its subtopologies we should set `maxtop = [1, 2, 3, 4]`, indicating that all \( \nu_1, \nu_2, \nu_3, \nu_4 \) can appear with positive values. If we only required integrals of e.g. a \( t \)-channel triangle subtopology, we could set `maxtop = [1, 3, 4]`, indicating that seeds with positive \( \nu_2 \) do not need to be included in the reduction. The next three entries determine the range of \( N_{\text{prop}}, N_-, \) and \( N_+ \) respectively. These values are mostly empirical. A rule of thumb is that one should generate seeds which include the indices of the most complicated integrals to be reduced, as well as the complete tower of integrals with lower priorities. To give a concrete example, we will generate seeds for the integrals that appear in the one-loop \( gg \rightarrow gg \) amplitude. We find integrals from all subtopologies (bubble and triangles) of the box topology, therefore we set \( 2 \leq N_{\text{prop}} \leq 4 \). We also find that all integrals have \( N_+ = 0 \) (there are no squared propagators in the amplitude), and can have up to 4 powers of irreducible numerators: \( 0 \leq N_- \leq 4 \). To emphasize differences in the running times for various algorithms of the program we will extend the latter interval to \( 0 \leq N_- \leq 10 \).

  \[
  \text{> SEEDGEN(‘‘seeds.map’’, [1, 2, 3, 4], [2, 4], [0, 10], [0, 0]);}
  \]

  The routine produces a list of ordered seeds in the file `/home/AIR/BOXA/seeds.map`.

- **Gauss elimination:** We generate the IBP equations from the seeds and perform Gauss elimination by calling the routine

  \[
  \text{Reducer(“seeds_file”, “monitor_file”, “RESULTS_DIR”);}\]

  The first argument is the name of the file with the seeds for the reduction (as it was produced with `SEEDGEN`). The next argument is the name of a file which the program updates with the processed seeds; it serves to monitor the progress of the program. The last argument provides a directory path where the
program can deposit the database with the IBP equations. For our example, we type

> Reducer('seeds.map', 'calc.map', '.');

It is useful to inspect the /home/AIR/BOXA directory. The program has created a number of subdirectories (B_1.3, B_1.3.4, etc) which correspond to the non-vanishing subtopologies of the box topology. In these subdirectories, AIR stores the IBP equations after they have been rearranged to isolate the most complicated integral at the lhs of the equation. For example, Eq. 2.29 is stored in

/home/AIR/BOXA/B_1.3/B_1.-1.1.0.map

The first part of the file path /home/AIR/BOXA/ corresponds to the directory in the third argument of the Reducer command. The second part of the file path B_1.3 is created from the integers {i} for which the powers {μ_i} are positive. The ending of the file path is created from the indices {μ_i} of the integral.

- Collecting the results: Essentially the reduction is now complete; the reduced integrals can be found in the files of the database tree for the IBP equations. Inspecting some of the equations we find that many integrals are reduced in terms of three master integrals: B(1, 0, 1, 0), B(0, 1, 0, 1), and B(1, 1, 1, 1). However, we also find integrals which are not fully reduced, e.g. the integral B(2, 1, 1, -11). It is usually observed that integrals with the same indices as in the seeds are fully reduced. Motivated from this observation, we have written a routine for collecting in a separate directory the seed integrals:

```bash
tidy_list("seeds_file", "RESULTS_DIR");
```

The first argument is a file with seeds (as generated by SEEDGEN). The last argument is the directory where the program has placed the results (as in the third argument for Reducer). For our example, we type:

> tidy_list('seeds.map', '.');

The routine has created a subdirectory, named RESULTS, which contains the expressions for the seed integrals only. For example, one can find the integral B(1, -4, 1, 1) in the file /home/AIR/BOXA/RESULTS/B_1.3.4/B_1.-4.1.1.map.

We should note that when the masking algorithms are activated, the tidy_list routine also performs the required nested substitutions for expressing the coefficients of the master integrals in terms of the kinematic parameters and the
dimension. However, it does so only for coefficients with smaller size than the MAPLEMAXSUB value. It is possible to achieve a fast execution of the tidy_list routine if we choose a low value (100-500) of MAPLEMAXSUB. The task of computing large coefficients is postponed further, and is performed by a new routine which we shall describe shortly. This routine is customized to disentangle the newest masking, which has a simpler structure than the masking of Gauss-elimination, very efficiently.

- **Reading the results interactively:** A useful routine for reading the reduced integrals from within the MAPLE environment is

```maple
show_int(integral, RESULTS_DIR);
```

The first argument is the required integral, and the second is the directory of the reduction (as in Reducer). For example,

```maple
> show_int(B(1, -4, 1, 1), '');
```

outputs the expression for the required integral in terms of master integrals. This routine can be used for purposes of interfacing the results of the reduction to other programs that users develop for calculating matrix-elements. We should note that if the masking of master integrals is activated and the value of MAPLEMAXSUB is small, show_int will return the wanted integral as a linear combination of master integrals but with masked coefficients. The routine `show_full_int` displays the unmasked result.

We have described the basic variables and routines of AIR by performing the reduction of the box topology. It is worth noting that the total running time for the three main routines (SEEDGEN, Reducer, tidy_list) is approximately two minutes on a 1.6GHz processor.

### 5. Masking reduced expressions

In this section we repeat the reduction of the one-loop massless box topology providing the known master integrals as input to the program. The algorithm uses this information to find parts of expressions which are reduced to master integrals, and masks them. The reduction proceeds faster, having replaced the masked expressions by indexed symbols $K(i)$. When the step of Gauss elimination is completed, only the indexed symbols in the expressions of the seed integrals need to be computed explicitly.

The reduction is performed in the directory `/home/AIR/BOXB`. The program allows, in principle, activation of the masking algorithm for master integrals without changing directory. However, we recommend performing the reduction in a
new directory if new values for the variables ZERO_TOPOLOGIES, ibp_equations, MASTERS, check_values, and MAXLENGTH are required. This will prevent possible integral misidentifications caused from creating the database of IBP equations with inconsistent values for these variables.

The input file input_boxb.map is modified to activate the masking algorithm for master integrals. In particular, the variable for the master integrals is not empty; we have defined

MASTERS := [B(1,0,1,0), B(0,1,0,1), B(1,1,1,1)]:

These are the master integrals that we found in the first reduction.

We now execute the MAPLE script in script_boxb.map:

currentdir("/home/AIR/BOXB"): read "input_boxb.map": read "/home/AIR/main.map": SEEDGEN("seeds.map", [1, 2, 3, 4], [2, 4], [0, 10], [0, 0]): Reducer("seeds.map", "calc.map", ":."): tidy_list("seeds.map", ":."): The script is executed in less than a minute; this is approximately 50% faster than without the masking algorithm. The routine Reducer has created a tree of subdirectories ICED/ICED#/KEXPR, where the masked expressions are stored in files named kexpr_i.map. The expressions are replaced in the reduction by the symbol $K(i)$, where $i$ is an integer index.

The masked expressions are defined recursively; it is therefore necessary to perform a series of nested substitutions before we obtain their explicit form in terms of master integrals. This task is performed by the tidy_list routine, which stores explicit results for the masked expressions in the directory /home/AIR/BOXB/KMELT. The user is not required to know the details about the file structure for the masked expressions; the integrals in the directory RESULTS are fully evaluated in terms of master integrals and can be accessed as before.

6. Masking large integral coefficients

In this Section we describe the function of the algorithm which masks large integral coefficients in the IBP equations. We perform the reduction in the directory /home/AIR/BOXC, which contains the input file input_boxc.map and the appropriate MAPLE script script_boxc.map. We have modified the input variables:
MASTERS:=[]:
check_values:=[
  [s=1, t=-0.12, d=3.3],
  [s=-1.2, t=12.2, d=42],
  [s=1.82, t=-0.345, d=-28.1]
]:
MAXLENGTH:=50:

In this run we have deactivated the algorithm for masking reduced expressions. Instead, we have provided a list of numerical values for the kinematic parameters and the dimension which activates the algorithm for masking the integral coefficients with length bigger that the value of the MAXLENGTH variable. The MAPLE commands for the reduction are collected in the file script_boxc.map,

restart;
currentdir("/home/AIR/BOXC"): 
read "input_boxc.map": 
read "/home/AIR/main.map": 
SEEDGEN("seeds.map", [1, 2, 3, 4], [2, 4], [0, 10], [0, 0]):
Reducer("seeds.map", "calc.map", ":
estid_list("seeds.map", ":

The script is executed in about 90 seconds; this is slower than previously. In general, masking large coefficients is not as fast as masking the reduced expressions to master integrals. However, in reductions of complicated IBP systems, such as in multiloop crossed topologies, we have found that this algorithm is indispensable. In extremely complicated problems it is required that both masking algorithms are activated.

In the directory ICED we find two new subdirectories: EXPR and NUM. The routine Reducer saves the expressions for the masked large integral coefficients in the first directory. In the second directory, it stores the numerical values of the same coefficients for the choices of the parameters in check_values. Expressions in the directory EXPR are defined recursively through other masked expressions. However, in the directory NUM they are explicitly evaluated for the special input values of the parameters. The program sets an expression to zero in the IBP equations if its numerical values is zero for all input choices in check_values. It is important to provide “sufficiently random” lists of numerical values for the parameters in order to reduce the risk for accidental cancelations. It is important to note that floating point numbers in check_values are automatically converted to fractional numbers when used in the program. Therefore, the numerical evaluation of coefficients is exact (using integer arithmetics), avoiding complications due to rounding.

Finally, the results are collected in the directory RESULTS using the routines tidy_list and show_int. We should stress, that the results
7. Reduction of one-loop pentagons

In this section we perform the reduction of the one-loop pentagon with massless propagators. This is an example of a topology with many kinematic parameters. As is common in such topologies, the expressions for the reduced integrals are large. We will therefore use this example to demonstrate the options in AIR for dealing with large expressions.

We consider the class of integrals:

\[
V(v_1, v_2, v_3, v_4, v_5) = \frac{1}{\prod_{i=1}^{5} [(k + p_i)^2]^{\mu_i} [(k + p_{12})^2]^{\mu_3} [(k + p_{23})^2]^{\mu_4} [(k + p_{1234})^2]^{\mu_5}},
\]

where \( p_{12345} = 0 \) and \( p_1^2 = p_2^2 = p_3^2 = p_4^2 = p_5^2 = 0 \). The IBP equations for the pentagon topology are:

\[
\begin{align*}
\nu_1^1 s_{12} + \nu_5^5 s_{34} + (d - \nu_{12345}) & - (\nu_1^1 + \nu_2^2 + \nu_4^4 + \nu_5^5) \cdot s_{3}^- = 0 \quad (7.2) \\
\nu_2^2 s_{23} + \nu_1^1 s_{45} + (d - \nu_{12345}) & - (\nu_1^1 + \nu_2^2 + \nu_3^3 + \nu_5^5) \cdot s_{4}^- = 0 \quad (7.3) \\
\nu_3^3 s_{34} + \nu_2^2 s_{51} + (d - \nu_{12345}) & - (\nu_1^1 + \nu_2^2 + \nu_3^3 + \nu_4^4 + \nu_5^5) \cdot s_{5}^- = 0 \quad (7.4) \\
\nu_4^4 s_{45} + \nu_3^3 s_{12} + (d - \nu_{12345}) & - (\nu_2^2 + \nu_3^3 + \nu_4^4 + \nu_5^5) \cdot s_{1}^- = 0 \quad (7.5) \\
\nu_5^5 s_{51} + \nu_4^4 s_{23} + (d - \nu_{12345}) & - (\nu_1^1 + \nu_3^3 + \nu_4^4 + \nu_5^5) \cdot s_{2}^- = 0 \quad (7.6)
\end{align*}
\]

where we denote the invariant masses \( s_{ij} \equiv \vec{p}_{ij}^2 \). We also note that the topology vanishes if any three adjacent propagators are raised to non-positive powers.

After a preliminary run with no masking algorithms we find 11 master integrals:

- the pentagon integral \( V(1, 1, 1, 1, 1) \),
- the box integrals \( V(1, 1, 1, 1, 0) \), \( V(1, 1, 1, 0, 1) \), \( V(1, 0, 1, 1, 1) \), \( V(1, 0, 1, 1, 1) \), \( V(0, 1, 1, 1, 1) \), and
- the bubble integrals \( V(1, 0, 1, 0, 0) \), \( V(1, 0, 0, 1, 0) \), \( V(0, 1, 0, 1, 0) \), \( V(0, 1, 0, 0, 1) \), and \( V(0, 0, 1, 0, 1) \).
Remarkably, by using the algorithm for masking reduced expressions, the step of Gauss elimination is very fast and can be performed for far more complicated integrals than the ones that are practically needed; it only takes a few minutes before a sufficiently large number of integrals for QCD five-point amplitudes is solved. However, keeping the variable MAPLEMAXSUB in unreachable values (i.e. switching off the special routines for large coefficients, as we did in all previous examples), forces the routine tidy_int to carry the load of all substitutions and simplifications. The presence of five independent Mandelstam variables and the dimension parameter makes the step of nested substitutions very hard for the integrals with highest priority. The routine can get stalled in computers with a memory smaller than 1GB.

We set the variable MAPLEMAXSUB to a value of 100 in the input_pentagon.map. The reduction routine Reducer is not affected by the new setting, however, the nested substitution routine tidy_list runs differently; it does not perform simplifications on any expression with more than 100 characters. Instead, it replaces these coefficients with indexed aliases, \{f[i]\}. The routine does not process large coefficients, and finishes very quickly. The difficult substitutions for the masked expressions \(f[i]\) are performed with a new routine melt_all_f("."). This routine is designed to work with the smallest possible memory consumption. Finally, the user can display the seed integrals explicitly written in terms of master integrals, the dimension, and the kinematic parameters, using the show_full.int routine.

It is worth demonstrating some important technical details for the reduction. We perform the reduction in the directory /home/AIR/Pentagon, where we have placed the input file input_pentagon.map, and a script for executing the AIR routines script_pentagon.map. As usual, in the input file we have provided the IBP equations, conditions for vanishing integrals, and the list of master integrals. We also set values for the variables,

\begin{verbatim}
MAXLENGTH:=100:
MAXSIMPLIFY:=1500:
MAPLEMAXSUB:=100:
VERBOSE:=FALSE:
\end{verbatim}

We now perform the reduction of integrals of the pentagon topology with \(N_\leq 4\), and \(N_+ = 0\).

\begin{verbatim}
/home/AIR/Pentagon> maple script_pentagon.map
\end{verbatim}

The script is executed in approximately 10 minutes using approximately 40MB of memory. At this point it is worth making some observations about the results of the reduction. We launch a MAPLE window, load the AIR files for the pentagon topology, and read the result for one of the reduced integrals:

\begin{verbatim}
> currentdir("/home/AIR/Pentagon");
\end{verbatim}
> read "input_pentagon.map";
> read "/home/AIR/main.map";
> show_int(V(1, 1, 1, 1, -4), ".");

The result now contains masked expressions, e.g. \( f[67] \). Their value is stored in the ICED directory tree. We can see the value of the masked expressions using the routine:

\[ \text{show\_f(i, RESULTS\_DIR)}; \]

which displays the variable \( f[i] \) for the integer \( i \). We must also provide the reduction directory \( \text{RESULTS\_DIR} \). For example, the value of \( f[12] \) can be retrieved by typing:

\[ > \text{show\_f(12, ".")}; \]

Moreover, the command

\[ > \text{show\_full\_int(V(1,1,1,-4), ".")}; \]

will return the full expression of the wanted integral. The commands \text{show\_int}, \text{show\_full\_int} and \text{show\_f} are very convenient to collect the results and export them to other platforms for further calculations.

We proceed, next, with further reductions of integrals of the pentagon topology with \( \mathcal{N}_- \leq 5 \), and \( \mathcal{N}_+ = 0 \). To perform this reduction we have to prepare a run using the same input file and requiring additional seeds generated in the script file,

\[ > \text{SEEDGEN("seeds.map", [1,2,3,4,5], [2,5], [0,5], [0,0])}; \]

The script runs now in approximately 25 minutes making use of 65MB of memory. The coefficients involved are now larger, but they were computed very efficiently.

We have performed a number of reductions for one loop hexagon and heptagon topologies and various two-loop topologies. For example, all loop and phase-space integral topologies in [4, 6] are fully reduced in less than 6 hours. The reduction of the massless double box topology with \( \mathcal{N}_- \leq 4 \), and \( \mathcal{N}_+ = 0 \) can be performed in about three days; the \text{Reducer} routine was running for approximately 7 hours, the \text{tidy\_list} routine went through in one hour and ten minutes, while the \text{melt\_all\_f} routine worked for a couple of days. The cross-box massless box topology is reduced in approximately four days. In massive two-loop topologies, we have reduced integral topologies for the production of heavy quarks. The double-box topology with two massive external legs and a massive propagator (all carrying the same mass) is reduced using the masking algorithms in about 32 hours while the nested substitutions are completed in about 20 days for \( \mathcal{N}_- \leq 4 \), and \( \mathcal{N}_+ = 0 \).
8. Conclusions

We have presented a MAPLE program for Automated Integral Reductions in perturbative calculations. Our program is based on an algorithm introduced by Laporta [14], and uses the method of Gauss elimination for solving large systems of equations. The program can reduce generic loop or phase-space integrals or other functions (like hypergeometric functions) which satisfy coupled algebraic identities.

The main obstacle in multiloop reductions is the large size of the symbolic expressions. We have implemented two algorithms in our program which organize the reduction more efficiently and reduce the amount of computations. The routines mask reduced expressions or large integral coefficients. This enables solving the system of IBP equations without performing all substitutions explicitly. The computationally intensive task of nested substitutions is performed only after the procedure of Gauss-elimination is completed, and for only a small fraction of expressions which appear in the final results.

Reduction algorithms cannot be extended to arbitrarily large calculations due to finite computing resources. We believe, however, that many phenomenologically interesting problems are tractable using AIR. There are a few improvements that we expect to make in future releases, implementing a more flexible database for storing the equations, and including more efficient algorithms for performing nested substitutions and simplifying large expressions. The methods described in [28] are appropriate for achieving this goal.

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