SEQUENTIAL MONITORING WITH CONDITIONAL RANDOMIZATION TESTS

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Sequential monitoring in clinical trials is often employed to allow for early stopping and other interim decisions, while maintaining the type I error rate. However, sequential monitoring is typically described only in the context of a population model. We describe a computational method to implement sequential monitoring in a randomization-based context. In particular, we discuss a new technique for the computation of approximate conditional tests following restricted randomization procedures and then apply this technique to approximate the joint distribution of sequentially computed conditional randomization tests. We also describe the computation of a randomization-based analog of the information fraction. We apply these techniques to a restricted randomization procedure, Efron’s [Biometrika 58 (1971) 403–417] biased coin design. These techniques require derivation of certain conditional probabilities and conditional covariances of the randomization procedure. We employ combinatorial techniques to derive these for the biased coin design.

1. Introduction. Sequential monitoring refers to analyzing data periodically during the course of a clinical trial, with the purpose of detecting early evidence in support of or against a hypothesis. A desirable feature of such a monitoring plan would be flexible inspections of the data that can occur at arbitrary time points. At the same time, sequentially tested hypotheses must maintain the overall probability of type I error at the prespecified level, since repeated testing is known to inflate it. The Lan and DeMets (1983) error spending approach for sequential monitoring allows this. The approach makes use of a type I error spending function, which depends on the amount of “statistical information” available at the time of the interim inspection. In
the context of sequential monitoring, the statistical information is a measure of how far a trial has progressed. Under a population model, the amount of interim information—the information fraction—is defined as the proportion of Fisher’s information observed thus far in the trial. The type I error spending function rations the amount of type I error that may be spent at each look commensurate to the information fraction. The critical value associated with the allowable probability of type I error at a certain interim look is obtained and compared to the observed value of the statistic. The decision whether to continue, or stop, the trial is based on this comparison. Sequential monitoring is typically discussed in the context of a population model. However, it is not uncommon for the FDA to require a “re-analysis” of data using a “re-randomization test,” or, as we call it here, a randomization test, defined below.

Let \( T = T_1, \ldots, T_n \) be a randomization sequence, where \( T_i = 1 \) if subject \( i \) is randomized to treatment 1; \( T_i = 0 \) if subject \( i \) is randomized to treatment 2, \( i = 1, \ldots, n \). Let \( N_1(j) = \sum_{i=1}^{j} T_i \) be the number of subjects randomized to treatment 1 after \( j \) assignments. Let \( X = (X_1, \ldots, X_n) \) be the responses based on some primary outcome variable, and let \( x \) be the realization. A valid test of the treatment effect can be conducted permuting \( T \) in all possible ways [e.g., Lehmann (1986), Chapter 5]. However, if one wishes to incorporate the randomized design into the analysis, under restricted randomization, such permutations are not equiprobable [e.g., Rosenberger and Lachin (2002), Chapter 7]. The family of linear rank tests provides a large class of test statistics with which to conduct randomization tests. The form of the statistic is \( V(T) = a_n' T \), for a score vector \( a_n = (a_{1n} - \bar{a}_n, \ldots, a_{nn} - \bar{a}_n)' \), where \( a_{jn} \) is some function of the rank of the \( j \)th observation and \( \bar{a}_n = \sum_{j=1}^{n} a_{jn}/n \). The \( p \)-value of the randomization test is computed with respect to a reference set of sequences. The unconditional reference set contains all possible allocation sequences, including those that give little or no information about the treatment effect (e.g., 1, 1, \ldots, 1). Also, the random numbers on each treatment arm, \( N_1(n) \) and \( N_2(n) \), are ancillary statistics, and therefore the conditional reference set is preferred, which finds probabilities conditional on \( N_1(n) = n_1 \), that is, the observed number on treatment 1 [e.g., Cox (1982), Berger (2000)]. This leads to a conditional test.

The literature is largely silent on the subject of sequential monitoring of randomization tests (brief exceptions are found in Rosenberger and Lachin [(2002), Section 7.10] and Zhang and Rosenberger (2008), whose techniques only extend to one interim inspection). The computation of conditional randomization tests is also inherently difficult, even without sequential monitoring. We address these issues in this paper by proposing a technique, based on deriving exact conditional distributions of randomization procedures, that leads to a simple computational method for approximating the distribution of sequentially computed randomization tests. We also discuss the appro-
appropriate analog for "information fraction" in the context of a randomization model. Our focus will be on one particular restricted randomization procedure, Efron’s (1971) biased coin design, which induces a beautiful closed-form combinatoric structure that facilitates such an analysis. However, the technique can be applied to any randomization procedure for which we can determine certain exact conditional distributional results.

Let \( \phi_{j+1} \) be a restricted randomization procedure such that

\[
\phi_{j+1} = \Pr(T_{j+1} = 1|N_1(j)).
\]

Efron’s (1971) biased coin design is a restricted randomization procedure for clinical trials that has exceptional properties: it balances treatment assignments throughout the course of the trial with low variability [e.g., Antognini (2008)], and it mitigates selection and accidental biases [Rosenberger and Lachin (2002)]. Then the biased coin design \( \text{BCD}(p) \) for a parameter \( p \in [1/2, 1] \), \( q = 1 - p \), is defined as

\[
\phi_{j+1} = \begin{cases} 
1/2, & \text{when } N_1(j) = j/2, \\
p, & \text{when } N_1(j) < j/2, j = 0, 1, 2, \ldots, \\
q, & \text{when } N_1(j) > j/2.
\end{cases}
\]

(1.1)

Note that \( p = 0.5 \) results in complete randomization and \( p = 1 \) results in permuted blocks with block size 2. When \( p < 1 \), the design is fully randomized, in that each subject will be assigned to treatment randomly, which differs markedly from the permuted block design, where some subjects in the tail of each block are assigned with probability 1. Let \( D_j = 2N_1(j) - j \) be the difference in numbers assigned to treatments 1 and 2; \( \{D_n\}_{n=1}^\infty \) forms an asymmetric random walk when \( p \in (1/2, 1) \). Markaryan and Rosenberger (2010) derive the exact distribution of \( D_j \) for the \( \text{BCD}(p) \), from which the exact distribution of \( N_1(n) \) follows immediately:

\[
P(N_1(n) = n_1) = \begin{cases} 
p^{n_1} \sum_{l=0}^{n_1-1} \frac{n - 2l}{n + 2l} \binom{n_1 + l}{l} q^l, & n_1 = \frac{n}{2}, \\
p^n \frac{n!}{2} \sum_{l=0}^{n} \frac{n - n_1 - l}{n - n_1 + l} \binom{n - n_1 + l}{l} q^{n-2n_1+l-1}, & 0 \leq n_1 < \frac{n}{2}, \\
\frac{n!}{2} \sum_{l=0}^{n - n_1} \frac{n_1 - l}{n_1 + l} \binom{n_1 + l}{l} q^{2n_1-n+l-1}, & \frac{n}{2} < n_1 \leq n.
\end{cases}
\]

Their paper also provides the exact expression for the variance–covariance matrix of the treatment assignments \( \mathbf{T} \).

In this paper we provide the exact conditional distribution of \( N_1(n) \) given \( N_1(j), 1 \leq j < n \), and the expression for the variance–covariance matrix of \( \mathbf{T} \).
given $N_1(n), \Sigma_{|n_1|}$. While these are heretofore unknown results on theoretical properties of a random walk, our primary interest is that these results give us a computational method to approximate conditional randomization tests following the BCD($p$). We then extend these results to the case where sequential analysis is implemented in the course of a clinical trial.

Rosenberger and Lachin (2002) distinguish among three techniques that can be used to compute randomization tests: exact, Monte Carlo and asymptotic. Exact tests are computationally intensive, even with today’s computing, and require networking algorithms [Mehta, Patel and Wei (1988)]. Hollander and Peña (1988) developed a clever recursive algorithm to determine the exact distribution of both conditional and unconditional randomization tests following Efron’s biased coin design and applied it to a sample of size of $n = 37$. It can be assumed that such computational techniques would be able to solve much larger problems with today’s computing resources. While authors have determined the asymptotic normality of conditional randomization tests under various score functions and randomization procedures [e.g., Smythe (1988)], Efron’s biased coin induces a stationary distribution, and hence the test statistic may not be asymptotically normal. This phenomenon was noted in a number of papers, first by counterexample in Smythe and Wei (1983) for the unconditional test, and then by simulation by Hollander and Peña (1988) for the conditional test.

Mehta, Patel and Senchaudhuri (1988) use importance sampling to estimate the conditional randomization test’s $p$-value; their technique employs an elegant, but complex, networking algorithm. The efficiency of the estimator relies on the convergence to normality of the test statistic, which may not hold under the biased coin design. One might be able to modify the network algorithm in Mehta, Patel and Wei (1988) or the recursive algorithm in Hollander and Peña (1988) to compute the exact distribution of sequentially monitored conditional randomization tests, but here we provide a method that is not very computationally intensive and allows us to sample directly from the conditional reference set under a broad class of restricted randomization procedures.

The paper is organized as follows. In Section 2, we present a method for sampling directly from the conditional distribution of $V(T)$, which facilitates the computation of conditional tests. We need to compute certain exact conditional probabilities to apply this method, and we do this for Efron’s biased coin design. We extend this application to develop a computational technique for sequential monitoring of conditional randomization tests in Section 3. In Section 4, we describe the analog of “information” in the context of a randomization model. In defining a randomization-based information fraction, we must derive the conditional variance–covariance matrix of $T$, which we do for Efron’s biased coin design. We draw conclusions in Section 5. All the major proofs, some of which require careful combinatorics, are relegated to the online supplement.
2. Computation of conditional randomization tests.

2.1. Generating sequences from the unconditional reference set. Suppose a total of \( n \) subjects are randomized to two treatments. Let \( n_1 \) be the observed number of assignments on treatment 1. A conditional randomization test can be approximated by sampling sufficiently many sequences from the conditional reference set, \( \Omega_c \), the collection of sequences that satisfy \( N_1(n) = n_1 \). This can be achieved by generating sequences from the unconditional reference set, the set of all possible assignments, and retaining those that belong to \( \Omega_c \).

Suppose at least \( N_c \) number of sequences that satisfy \( N_1(n) = n_1 \) are sufficient to approximate the conditional randomization distribution of \( V(T) \). Let \( K \) sequences be sampled, \( T_1, \ldots, T_K \), independently and with replacement from the unconditional reference using \( \phi_{j+1} \) as the sampling mechanism. This number of Monte Carlo sequences must be large enough such that at least \( N_c \) sequences satisfy the condition \( N_1(n) = n_1 \). The requisite number of sequences, \( K \), follows a negative binomial random variable with parameters \( \pi = P(N_1(n) = n_1) \) and \( r = N_c \) [Zhang and Rosenberger (2011)]. Let \( N \) denote a value in the range of \( K, N = N_c, N_c + 1, \ldots \). For \( k = 1, \ldots, N \), a sequence \( T_k = t \) is sampled from the unconditional reference set with probability

\[
(2.1) \quad f(t) = \frac{1}{2} \prod_{j=1}^{n-1} (\phi_{j+1})^{t_j+1}(1 - \phi_{j+1})^{1-t_j+1},
\]

where \( t_{j+1} \) are the observed values of \( T_{j+1} \). The \( j \)th sampled sequence induces two Bernoulli random variables

\[
Y_j = \begin{cases} 
1, & \text{if } N_1(n) = n_1, \\
0, & \text{otherwise},
\end{cases}
\]

and

\[
X_j = \begin{cases} 
1, & \text{if } N_1(n) = n_1 \text{ and } V(T_j) \geq v^*, \\
0, & \text{otherwise},
\end{cases}
\]

where \( v^* \) is the observed value of the statistic. A strongly consistent estimator for the \( p \)-value of the upper-tailed conditional test can be computed as

\[
(2.2) \quad \hat{p}_c = \frac{\sum_{j=1}^{N} X_j}{\sum_{j=1}^{N} Y_j}.
\]

Table 1 reports the 95th percentile of \( K \) when sampling from the unconditional reference set and \( N_c = 2500 \) for Efron’s biased coin design. These sample sizes are reasonable when there is perfect balance in the assignments,
Table 1
Approximate 95th percentile of $K$ for various $n$, $n_1$, $N_c = 2500$

| $n$  | $n_1 = 0.45n$          | $n_1 = 0.48n$          | $n_1 = 0.50n$          |
|------|------------------------|------------------------|------------------------|
| 100  | 3,531,344              | 55,060                 | 5117                   |
| 200  | 3,611,280,266          | 881,557                | 5117                   |
| 500  | $3.877 \times 10^{12}$ | $3,611,026,232$        | 5117                   |

BCD($p = 2/3$)

| $n$  | $n_1 = 0.45n$          | $n_1 = 0.48n$          | $n_1 = 0.50n$          |
|------|------------------------|------------------------|------------------------|
| 100  | 114,384,212            | 156,865                | 3822                   |
| 200  | $6.754 \times 10^6$    | 12,709,307             | 3822                   |
| 500  | $1.390 \times 10^{21}$ | $6.754 \times 10^6$   | 3822                   |

BCD($p = 3/4$)

but increase considerably in the presence of imbalance. This technique cannot be used in the presence of any imbalance.

2.2. Our method: Generating sequences from the conditional reference set.

Rather than sampling too many sequences and discarding those that do not satisfy the condition $N_1(n) = n_1$, it is more efficient to sample directly from $\Omega_c$—the collection of all randomization sequences that satisfy the condition $N_1(n) = n_1$. The set $\Omega_c$ will be called the conditional reference set.

Let $N_c$ randomization sequences, $T_1, \ldots, T_{N_c}$, be sampled independently and with replacement strictly from $\Omega_c$, each with respective probabilities $h(t_1), \ldots, h(t_{N_c})$. For an upper-tailed test, the $k$th sampled sequence induces a Bernoulli random variable

$V_k = \begin{cases} 
1, & \text{if } V(T_k) \geq v^*, \\
0, & \text{otherwise.} 
\end{cases}$

(2.3)

The Monte Carlo estimator of the upper-tailed test’s $p$-value is the strongly consistent and unbiased estimator $\hat{V} = \sum_{k=1}^{N_c} V_k/N_c$. (It may be possible to find an estimator with a smaller variance, but we do not address the issue of estimation of $p$-values in this paper.)

To guarantee a sequence from $\Omega_c$, $T_{j+1}$ in $\phi_{j+1}$ must be conditioned on both $N_1(j)$ and $N_1(n)$. Consequently, for $0 \leq m_j \leq j$, the procedure

$p_{j+1} = \begin{cases} 
P(T_{j+1} = 1|N_1(j) = m_j, N_1(n) = n_1), & 1 \leq j \leq n - 1, \\
P(T_{j+1} = 1|N_1(n) = n_1), & j = 0, 
\end{cases}$

(2.4)

must be applied to generate a random sequence strictly from $\Omega_c$. We now provide a general formula relating the conditional and the unconditional reference sets, which facilitates the generation of sequences from the conditional reference set for any restricted randomization procedure of the form $\phi_{j+1} = \Pr(T_{j+1} = 1|N_1(j))$. 

Theorem 2.1. For \( n = 1, 2, 3, \ldots, 0 \leq n_1 \leq n, 0 \leq j < n, 0 \leq m_j \leq j \) and \( \phi_{j+1}(m_j) = P(T_{j+1} = 1|N_1(j) = m_j) \), the rule

\[
p_{j+1} = \begin{cases} 
\phi_{j+1}(m_j) \frac{P(N_1(n) = n_1|N_1(j+1) = m_j+1)}{P(N_1(n) = n_1|N_1(j) = m_j)}, & 1 \leq j \leq n-1, \\
\phi_{j+1}(m_j) \frac{P(N_1(n) = n_1|T_{j+1} = 1)}{P(N_1(n) = n_1)}, & j = 0,
\end{cases}
\]

(2.5)
can be used to sample a sequence that satisfies \( N_1(n) = n_1 \).

Proof. The result follows from an application of Bayes theorem to (2.4) and the Markovian property of \( N_1 \).

Furthermore, for \( k = 1, \ldots, N_c \), a sequence \( T_k = t \) is sampled from \( \Omega_c \) with probability

\[
h(t) = \prod_{j=0}^{n-1} (p_{j+1})^{t_{j+1}} (1 - p_{j+1})^{1-t_{j+1}}.
\]

(2.6)
In the simplest case, complete randomization, \( p_{j+1} = (n_1 - m_j)/(n - j) \), \( 0 \leq j \leq n - 1 \), and this is the random allocation rule [see Rosenberger and Lachin (2002)], which is sometimes used to fill permuted blocks.

The following theorem gives these probabilities for Efron’s biased coin design. The distribution of \( N_1(n) \) given \( N_1(j) = m_j \), \( 0 \leq m_j \leq j \), has three cases depending on the value of \( m_j \) with respect to \( j \), \( 1 \leq j < n \). Within each case, \( P(N_1(n) = n_1|N_1(j) = m_j) \) depends on \( n_1 \) with respect to \( n, j \), \( j \), and \( m_j \).

Theorem 2.2. Let \( n = 2, 3, 4, \ldots, 1 \leq j < n, 0 \leq m_j \leq j \) and \( m_j \leq n_1 \leq n - j + m_j \). Denote

\[
C(x, l) := \frac{x-l}{x+l} \binom{x+l}{l} \quad \text{and} \quad D := \binom{n-j}{n_1-m_j} - \binom{n-j}{n_1-j+m_j}.
\]

For the BCD(\( p \)):

(1) When \( 0 \leq m_j < j/2 \), \( P(N_1(n) = n_1|N_1(j) = m_j) \) is

\[
\binom{n-j}{n_1-m_j} p^{n_1-m_j} q^{n-j-n_1+m_j} \quad \text{if } m_j \leq n_1 < j - m_j,
\]

\[
0.5 p^{n_1-m_j} \sum_{l=0}^{n_1+m_j} C(n-n_1-m_j, l) q^{n-2n_1-l+1} + D p^{n_1-m_j} q^{n-j-n_1+m_j} \quad \text{if } j - m_j \leq n_1 < n/2,
\]
\[ p^{n_1 - m_j} \sum_{l=0}^{n_1 - n_1 + m_j} C(n_1 - m_j, l) q^l \quad \text{if } n_1 = n/2, \]
\[ 0.5 p^{n_1 - m_j} \sum_{l=0}^{n_1 - n_1 + m_j} C(n_1 - m_j, l) q^{2n_1 - n - 1 + l} \quad \text{if } n/2 < n_1 \leq n - j + m_j. \]

(2) When \( m_j = j/2 \),
\[ P(N_1(n) = n_1 | N_1(j) = m_j) = P(N_1(n - j) = n_1 - m_j), \quad m_j \leq n_1 \leq n - j + m_j, \]
where the unconditional distribution is derived in Markaryan and Rosenberger (2010).

(3) When \( j/2 < m_j \leq j \), \( P(N_1(n) = n_1 | N_1(j) = m_j) \) is
\[ 0.5 p^{n_1 + m_j - j} \sum_{l=0}^{n_1 - m_j} C(n - j - n_1 + m_j, l) q^{n - 2n_1 - 1 + l} \quad \text{if } m_j \leq n_1 < n/2, \]
\[ p^{n - j - n_1 + m_j} \sum_{l=0}^{n_1 - m_j} C(n - j - n_1 + m_j, l) q^l \quad \text{if } n_1 = n/2, \]
\[ 0.5 p^{n - j - n_1 + m_j} \sum_{l=0}^{n_1 - n_1 - m_j} C(n_1 + m_j - j, l) q^{2n_1 - n - 1 + l} \]
\[ + D p^{n - j - n_1 + m_j} q^{n_1 - m_j} \quad \text{if } n/2 < n_1 \leq n - m_j, \]
\[ \left( \frac{n - j}{n_1 - m_j} \right) p^{n - j - n_1 + m_j} q^{n_1 - m_j} \quad \text{if } n - m_j < n_1 \leq n - j + m_j. \]

**Proof.** See Appendix A in the supplementary material [Plamadeala and Rosenberger (2011)]. \( \square \)

Note that if \( n = j \) and \( n_1 = m_j \), \( P(N_1(n) = n_1 | N_1(j) = m_j) = 1 \), and if \( m_j > n_1 \) or \( n - j < n_1 - m_j \), \( P(N_1(n) = n_1 | N_1(j) = m_j) = 0 \). Also, \( P(N_1(n) = n_1 | N_1(0) = 0) = P(N_1(n) = n_1) \).

The procedure then follows by simply generating \( N_c \) sequences using (2.5). This allows us to reduce the magnitude of the problem from the astronomical numbers in Table 1 to just \( N_c \). A satisfactory value for \( N_c \) can be obtained from the constraint \( \text{MSE}(\bar{V}) = p_c(1 - p_c)/N_c \leq 1/4N_c \leq \varepsilon \). For \( \varepsilon = 0.0001, \ N_c \geq 2500 \). Higher precision in estimation is possible by finding \( N_c \) that ensures \( P(|\bar{V} - p_c| \leq 0.1p_c) = 0.99 \), for instance. It follows that
Table 2
Approximations for the upper 0.1 tail of the randomization distribution of the linear rank statistic by sampling from $\Omega_c$; $N_c = 2500$, BCD(0.6)

| $n$  | $n_1$ | Exact   | 1000 Monte Carlo runs; mean (SD) |
|------|-------|---------|---------------------------------|
| $P(\mathbf{V}(\mathbf{T}) \geq 21.5)$ | 30 | 15 | 0.1057 | 0.1053 (0.0061) |
| $P(\mathbf{V}(\mathbf{T}) \geq 23)$ | 30 | 12 | 0.1009 | 0.1008 (0.0059) |
| $P(\mathbf{V}(\mathbf{T}) \geq 31)$ | 40 | 20 | 0.1011 | 0.1009 (0.0061) |
| $P(\mathbf{V}(\mathbf{T}) \geq 34)$ | 40 | 16 | 0.1000 | 0.0997 (0.0060) |
| $P(\mathbf{V}(\mathbf{T}) \geq 82)$ | 100 | 50 | 0.1055 | 0.1056 (0.0060) |
| $P(\mathbf{V}(\mathbf{T}) \geq 113)$ | 100 | 40 | 0.1043 | 0.1042 (0.0062) |
| $P(\mathbf{V}(\mathbf{T}) \geq 299)$ | 500 | 250 | 0.1104 | 0.1104 (0.0063) |
| $P(\mathbf{V}(\mathbf{T}) \geq 1000)$ | 500 | 200 | 0.1030 | 0.1030 (0.0058) |

$N_c \approx (2.576/0.1)^2(1 - p_c)/p_c$. Thus, to estimate a $p$-value as large as 0.04 with an error of 10% of 0.04 with 0.99 probability, the Monte Carlo sample size must be $N_c = 15,924$. If a smaller $p$-value is expected, $N_c$ will be larger.

Table 2 provides approximations for the upper 0.1 tail of the linear rank statistic with simple rank scores under the BCD(0.6) randomization. For small sample sizes, we also provide the exact $p$-value for comparison purposes; Monte Carlo estimates are very close with small variability. As expected, the variability of the estimates does not change across different sample sizes $n$. The computational complexity of the sampling scheme for the BCD is invariant to the value of $p$. Comparing Tables 1 and 2, the conditional distribution method reduces the Monte Carlo sample size to a few thousand.

Following stratification on known covariates, the computation of a stratified linear rank test based on the conditional randomization distribution is straightforward by summing the stratum-specific linear-rank test statistics over $I$ independent strata. Using the methodology described in this section, a sequence is sampled independently from the conditional reference of each stratum; the linear-rank statistic is evaluated in each stratum and the stratum-specific test statistics are summed. The process is repeated $N_c$ times, and the stratified test’s $p$-value is estimated by the proportion of summed statistics as or more extreme than the one observed.

3. Extension to sequential monitoring. Suppose there are $L - 1$ interim inspections of the data after $1 \leq r_1 < r_2 < \cdots < r_{L-1} < r_L = n$ patients responded. Let $0 < t_1 < t_2 < \cdots < t_{L-1} < t_L = 1$ be the corresponding information fraction at those inspections. For conditional tests, let $N_1(r_1), N_1(r_2), \ldots, N_1(r_{L-1})$, and $N_1(r_L) = N_1(n)$ be the sample sizes randomized to treatment 1 after inspections 1, $\ldots$, $L$ and let $n_{11}, \ldots, n_{1(L-1)}$, and $n_{1L} = n_1$ be realizations of these sample sizes. Let the linear-rank randomization test
statistic computed at each of the inspections be given by 

\[ V_{r_l} = \sum_{j=1}^{r_l} (a_{j} - \bar{a}_{r_l}) T_{j} = a'_{r_l} T^{(r_l)}, l = 1, \ldots, L. \]

Using the alpha-spending function approach [Lan and DeMets (1983)], let \( \alpha^*(t), t \in [0, 1], \) be a nondecreasing function such that \( \alpha^*(0) = 0 \) and \( \alpha^*(1) = \alpha \), the significance level of the one-sided test. One such function is 

\[ \alpha^*(t) = 2 - 2\Phi(z_{\alpha/2}/\sqrt{t}), 0 < t \leq 1; \alpha^*(0) = 0, \]

where \( \Phi \) is the standard normal distribution function and \( z_{\alpha/2} = \Phi^{-1}(1-\alpha/2) \) [Lan and DeMets (1983), O’Brien and Fleming (1979)]. Following Zhang and Rosenberger (2008), the upper-tailed, conditional randomization test with \( L \) interim looks involves finding \( d_1, \ldots, d_L \) such that 

\[
\begin{aligned}
P(V_{r_1} > d_1 | N_1(r_1) = n_{11}) &= \alpha^*(t_1), \\
P(V_{r_1} \leq d_1, V_{r_2} > d_2 | N_1(r_1) = n_{11}, N_1(r_2) = n_{12}) &= \alpha^*(t_2) - \alpha^*(t_1), \\
P(V_{r_1} \leq d_1, V_{r_2} \leq d_2, V_{r_3} > d_3 | \bigcap_{j=1}^{3} N_1(r_j) = n_{1j}) &= \alpha^*(t_3) - \alpha^*(t_2), \\
&\vdots \\
P(V_{r_1} \leq d_1, \ldots, V_{r_L} > d_L | \bigcap_{j=1}^{L} N_1(r_j) = n_{1j}) &= \alpha - \alpha^*(t_{L-1}).
\end{aligned}
\]

The asymptotic joint normality of these conditional distributions has not been shown, except in the case of \( L = 2 \) under the generalized biased coin design [Zhang and Rosenberger (2008)].

We express (3.1) in terms of univariate conditional distributions, which are much easier to sample from than the joint distributions in (3.1).

**Lemma 3.1.** The set of conditions (3.1) is equivalent to

\[
\begin{aligned}
P(V_{r_1} > d_1 | N_1(r_1) = n_{11}) &= \alpha^*(t_1), \\
P(V_{r_2} > d_2 | V_{r_1} \leq d_1, \bigcap_{j=1}^{2} \{N_1(r_j) = n_{1j}\}) &= \frac{\alpha^*(t_2) - \alpha^*(t_1)}{1-\alpha^*(t_1)}, \\
P(V_{r_3} > d_3 | \bigcap_{j=1}^{2} \{V_{r_j} \leq d_j\}, \bigcap_{j=1}^{3} \{N_1(r_j) = n_{1j}\}) &= \frac{\alpha^*(t_3) - \alpha^*(t_2)}{1-\alpha^*(t_2)}, \\
&\vdots \\
P(V_{r_L} > d_L | \bigcap_{j=1}^{L-1} \{V_{r_j} \leq d_j\}, \bigcap_{j=1}^{L} \{N_1(r_j) = n_{1j}\}) &= \frac{\alpha - \alpha^*(t_{L-1})}{1-\alpha^*(t_{L-1})}.
\end{aligned}
\]

**Proof.** See Appendix B in the supplementary material [Plamadeala and Rosenberger (2011)]. □
At each inspection \( l \) in (3.2), the conditional reference set is the collection of all sequences satisfying \( \bigcap_{i=1}^{l} \{ N_1(r_i) = n_{1i} \} \). The following theorem can be used to sample sequences from such sets.

**Theorem 3.1.** Let \( 1 \leq l \leq L \), \( r_0, r_1, r_2, \ldots, r_l \) and \( n_{10}, n_{11}, \ldots, n_{1l} \) be defined as before, with \( r_0 = 0 \) and \( n_{10} = 0 \). Let \( k = 1, \ldots, l \). For \( r_{k-1} \leq j < r_k \), \( n_{1(k-1)} \leq m_j \leq j \) and \( \phi_{j+1}(m_j) = P(T_{j+1} = 1|N_1(j) = m_j) \), the rule

\[
\psi_{j+1} = \phi_{j+1}(m_j) \frac{P(N_1(r_k) = n_{1k}|N_1(j + 1) = m_j + 1)}{P(N_1(r_k) = n_{1k}|N_1(j) = m_j)}
\]

(3.3) can be used to sample a sequence that satisfies \( \bigcap_{i=1}^{l} \{ N_1(r_i) = n_{1i} \} \).

**Proof.** See Appendix C in the supplementary material [Plamadeala and Rosenberger (2011)]. \( \square \)

Note that equation (3.3) reduces succinctly to the expected \( \psi_{j+1} = (n_{1k} - m_j)/(r_k - j) \) for complete randomization, \( l = 1, \ldots, L \), \( k = 1, \ldots, l \), \( r_{k-1} \leq j < r_k \) and \( n_{1(k-1)} \leq m_j \leq j \). For the BCD(\( p \)) the numerator and the denominator of \( \psi_{j+1} \) must be evaluated according to Theorem 2.2. To obtain a sequence from the reference set satisfying \( \bigcap_{i=1}^{l} \{ N_1(r_i) = n_{1i} \} \), the sampling must be done in \( k = 1, \ldots, l \) steps as follows:

1. At stage \( k = 1 \), apply \( \psi_{j+1} \) with \( r_0 \leq j < r_1 \) to sample the first \( r_1 \) assignments.
2. At stage \( k = 2 \), apply \( \psi_{j+1} \) with \( r_1 \leq j < r_2 \) to sample the next \( r_2 - r_1 \) assignments.
3. At stage \( 3 \leq k \leq l \), apply \( \psi_{j+1} \) with \( r_{k-1} \leq j < r_k \) to sample the next \( r_k - r_{k-1} \) assignments.

Suppose a sample of size \( N_c \) (sequences) is sufficient to estimate a distribution quantile using some quantile estimator. The Monte Carlo algorithm that estimates the boundary \( d_1, \ldots, d_L \) for an \( \alpha \)-level, upper-tailed, conditional randomization test with \( L - 1 \) interim inspections is as follows:

1. At stage 1, generate \( N_c \) randomization sequences of \( r_1 \) assignments from the reference set satisfying \( N_1(r_1) = n_{11} \). Evaluate \( V_{r_1} \) for each sequence; estimate \( d_1 \) using the nonparametric quantile estimator of Chen and Lazar (2010) based on the values of \( V_{r_1} \).
2. At stage 2, generate \( N_c/(1 - \alpha^*(t_1)) \) randomization sequences of \( r_2 \) assignments from the reference set satisfying \( \bigcap_{i=1}^{2} \{ N_1(r_i) = n_{1i} \} \). For each sequence, evaluate \( V_{r_1} \) using the first \( r_1 \) of \( r_2 \) assignments only. Retain those sequences that satisfy \( \{ V_{r_1} \leq d_1 \} \). Evaluate \( V_{r_2} \) for each retained sequence. Estimate \( d_2 \) using the quantile estimator of Chen and Lazar (2010) based on the values of \( V_{r_2} \).
(3) At stage \(3 \leq l \leq L\), generate \(N_c/\prod_{i=1}^{l-1}(1 - [\alpha^*(t_i) - \alpha^*(t_{i-1})]/[1 - \alpha^*(t_{i-1})])\) randomization sequences of \(r_l\) assignments from the reference set satisfying \(\cap_{i=1}^{l-1}\{N_1(r_i) = n_{1i}\}\). Note that \(\alpha^*(t_0) = 0\) and \(\alpha^*(t_L) = \alpha\). For each sequence, evaluate \(V_{r_1}, V_{r_2}, \ldots, V_{r_{l-1}}\) using the first \(r_1, r_2, \ldots, r_{l-1}\) assignments, respectively. Retain those sequences that satisfy \(\cap_{l=1}^{l-1}\{V_{r_l} \leq d_l\}\). Evaluate \(V_{r_l}\) for each retained sequence. Estimate \(d_l\) using the quantile estimator of Chen and Lazar (2010) based on the values of \(V_{r_i}\).

Requiring that \(N_c/\prod_{i=1}^{l-1}(1 - [\alpha^*(t_i) - \alpha^*(t_{i-1})]/[1 - \alpha^*(t_{i-1})])\) randomization sequences be sampled at stage \(l\) simply ensures that at least \(N_c\) sequences are used for the estimation of \(d_l\) at each stage \(l\).

**4. Randomization-based information.** Fisher’s information is defined under a population model, and hence it is not defined in the context of randomization-based inference. However, since the Fisher’s information approximates the inverse of the asymptotic variance of the test, it seems reasonable to define the randomization-based analog of information as the ratio of the variances [Rosenberger and Lachin (2002)].

\[
(4.1) \quad t_l = \frac{a_l' \Sigma_{[r_l]} a_l}{a_l' \Sigma_{[n]} a_l},
\]

where \(\Sigma_{[r_l]} = \text{Var}(T^{(r_l)}|N_1(r_1) = n_{11}, \ldots, N_1(r_l) = n_{1l})\). This requires specification of \(\Sigma_{[r_l]}\) and \(\Sigma_{[n]}\). We now derive these for Efron’s biased coin design. We begin with three lemmas:

**Lemma 4.1.** Let \(n = 2, 3, \ldots, 0 \leq n_1 \leq n\). Let \(f_j(i, b) = P(T_j = 1 | N_1(i) = a)\) and \(f_j(i, a+1) = P(N_1(j - 1) = a | N_1(i) = a + 1)\). For \(1 \leq i < j \leq n\),

\[
E(T_j | N_1(n) = n_1) = \sum_{a=0}^{i-1} \phi_i(a) P(N_1(i - 1) = a) \sum_{b=a+1}^{j-1} \phi_j(b) f_j(i, a+1) f_j(j, b+1) P(N_1(i) = b | N_1(n) = n_1).
\]

The conditional probabilities \(f_j(i, a+1)\) and \(f_j(j, b+1)\) are given by Theorem 2.2.

**Proof.** The result follows from an application of Bayes theorem to \(P(T_i = 1, T_j = 1 | N_1(n) = n_1)\) and the Markovian property of \(N_1\).

Given that we observe \(N_1(n) = n_1\), we now derive the variance–covariance matrix of \(T\), denoted by \(\Sigma_{[n]}\).

**Lemma 4.2.** Let \(n = 1, 2, \ldots, 0 \leq n_1 \leq n\). \(\theta_i|n_1 = E(T_i | N_1(n) = n_1)\) and \(\phi_i(a) = P(T_i = 1 | N_1(i - 1) = a)\). For the BCD\((p)\)

\[
\theta_i|n_1 = \frac{\sum_{a=0}^{i-1} P(N_1(i - 1) = a) \phi_i(a) P(N_1(n) = n_1 | N_1(i) = a + 1)}{P(N_1(n) = n_1)}.
\]
where
\[ \vartheta_{i|n_1} = 1/2P(N_1(n) = n_1|N_1(1) = 1)/P(N_1(n) = n_1). \]

If \( i < j \), the \((i, j)\)th entry of \( \Sigma_{|n_1} \) is
\[ \sigma_{ij} = \frac{\sum_{a=0}^{i-1} \phi_i(a)P(N_1(i - 1) = a) \sum_{b=a+1}^{j-1} \phi_j(b) f_{ij}^{(i,a+1)} f_{j_1}^{(j,b+1)}}{P(N_1(n) = n_1)} - \vartheta_{i|n_1} \vartheta_{j|n_1}. \]

If \( i = j \), the \((i, i)\)th entry of \( \Sigma_{|n_1} \) is
\[ \sigma_{ii} = \vartheta_{i|n_1}(1 - \vartheta_{i|n_1}). \]

**Proof.** The result follows from an application of Bayes theorem to
\( P(T_i = 1|N_1(n) = n_1) \), the Markovian property of \( N_1 \) and Lemma 4.1. \( \Box \)

**Lemma 4.3.** Let \( 1 \leq l \leq L, r_0, r_1, r_2, \ldots, r_l \) and \( n_{10}, n_{11}, \ldots, n_{1l} \) be defined as before, with \( r_0 = n_{10} = 0 \). Let \( \phi_i(a) = P(T_i = 1|N_1(i - 1) = a) \), \( k = 1, \ldots, l \), and \( f_{i-1,a}^{(r_{k-1},n_{1(k-1)})} = P(N_1(i - 1) = a|N_1(r_{k-1}) = n_{1(k-1)}) \). Denote
\[ \vartheta_{i|r_l} = E(T_i|\bigcap_{q=1}^{l} \{N_1(r_q) = n_{1q}\}) \] and \( \lambda_{ij|r_l} = E(T_i T_j|\bigcap_{q=1}^{l} \{N_1(r_q) = n_{1q}\}) \).

For \( 1 \leq k \leq l \), \( r_{k-1} < i \leq r_k \),
\[ \vartheta_{i|r_l} = \frac{\sum_{a=n_{1(k-1)}}^{i-1} \phi_i(a) f_{i-1,a}^{(r_{k-1},n_{1(k-1)})} f_{r_k,n_{1k}}^{(i,a+1)}}{P(N_1(r_k) = n_{1k}|N_1(r_{k-1}) = n_{1(k-1)})}. \]

For \( 1 \leq k \leq l \) and \( r_{k-1} < i < j \leq r_k \),
\[ \lambda_{ij|r_l} = \frac{\sum_{a=n_{1(k-1)}}^{i-1} \phi_i(a) f_{i-1,a}^{(r_{k-1},n_{1(k-1)})} \sum_{b=n_{1(k-1)+1}}^{j-1} \phi_j(b) f_{j-1,b}^{(j,a+1)} f_{r_k,n_{1k}}^{(j,b+1)}}{f_{r_k,n_{1k}}^{(r_{k-1},n_{1(k-1)})}}. \]

For all other \( i, j \),
\[ \lambda_{ij|r_l} = E \left( T_i \bigg| \bigcap_{q=1}^{l} \{N_1(r_q) = n_{1q}\} \right) E \left( T_j \bigg| \bigcap_{q=1}^{l} \{N_1(r_q) = n_{1q}\} \right). \]

The probabilities \( f_{i-1,a}^{(r_{k-1},n_{1(k-1)})}, f_{r_k,n_{1k}}^{(i,a+1)}, f_{j-1,b}^{(i,a+1)} f_{r_k,n_{1k}}^{(j,b+1)} \) are given by Theorem 2.2.

**Proof.** See Appendix D in the supplementary material [Plamadeala and Rosenberger (2011)]. \( \Box \)

Finally, the closed form of \( \Sigma_{|r_l} \) is given in the following theorem, which follows immediately from Lemma 4.3:

**Theorem 4.1.** Let \( 1 \leq l \leq L, k = 1, \ldots, l, r_0, r_1, r_2, \ldots, r_l \) and \( n_{10}, n_{11}, \ldots, n_{1l} \) be defined as before, with \( r_0 = n_{10} = 0 \).
Mean (SD) of simulated $\alpha$ for an $\alpha = 0.05$ upper tail sequential test over a Monte Carlo sample size of 1000, $N_c = 2500$, interpolating the unknown observations by sampling with replacement

| Look | $r_1$ | $n_{1l}$ | $t_l$ | $\alpha_l^*$ | $\hat{d}_l$ | $\hat{\alpha}$ |
|------|-------|---------|------|-------------|---------|----------|
| Look 1 | 250   | 126    | 0.3617 | 0.0011     | 1709    |          |
| Look 2 | 300   | 148    | 0.6248 | 0.0121     | 1688    |          |
| Look 3 | 350   | 174    | 1.0000 | 0.0373     | 1501    | 0.0495 (0.0043) |

* $\alpha_l = \frac{\alpha^*(t_l) - \alpha^*(t_{l-1})}{1 - \alpha^*(t_{l-1})}$.

The $(i,j)$th entry of $\Sigma_{|r_l}$ under the BCD$(p)$ is

$$
\sigma_{ij} = \begin{cases} 
\lambda_{ij|r_l} - \vartheta_{ij|r_l} \vartheta_{j|i|r_l}, & \text{if } i < j \text{ and } r_{k-1} < i < j \leq r_k, \\
\vartheta_{ij|r_l}(1 - \vartheta_{i|jr_l}), & \text{if } i = j, \\
0, & \text{otherwise,}
\end{cases}
$$

where $\vartheta_{ij|r_l}$ and $\lambda_{ij|r_l}$ are given by Lemma 4.3.

Although one can compute $\Sigma_n$ and $\Sigma_{|r_l}$ exactly using Theorem 4.1, $a'_n$ in (4.1) remains unknown at each interim inspection, since a portion of the data is unobserved. One would have to interpolate sequentially the remaining unknown data points in order to have a value for $a'_n$ and an approximation for (4.1). Interpolating the unknown observations by sampling with replacement the known observations is one way to obtain a value for $a'_n$. In our simulations with data generated from two normal distributions, $L = 3$, $n = 350$, $n_1 = 174$ and assignments following the BCD(3/4), the approximate information fraction at the first interim look with $r_1 = 250$ and $n_{11} = 126$ was 0.3791, compared to the true information of 0.3759. At the second interim look with $r_2 = 300$ and $n_{12} = 148$, the approximate information fraction was 0.6380, compared to the true information of 0.6382.

We also simulate the probability of type I error in an example. For this purpose, we generate a sample of $n = 350$ observations from $N(1, 0.9)$ and simulate treatment assignments from BCD($p = 3/4$). We plan $L = 3$ interim looks: at $r_1 = 250$, $r_2 = 300$ and $r_3 = 350$. The observed number assigned to treatment 1 at each look was $n_{11} = 126$, $n_{12} = 128$ and $n_{13} = 174$. We compute the boundary values using the algorithm in Section 3. Table 3 gives the estimated type I error rate ($\hat{\alpha}$) and standard deviation over 1000 replications for this sequential conditional test. The probability of type I error is preserved with low variability.

5. Conclusions. We have provided a computational method to approximate conditional randomization tests, which can be extended to clinical trials that incorporate sequential monitoring. The key is to determine cer-
tain conditional probabilities from the particular randomization procedure. These techniques apply to any restricted randomization procedure of the form $\phi_{j+1} = \Pr(T_{j+1} = 1|N_1(j))$ and for which closed form conditional probabilities can be obtained. We have derived the exact conditional distribution of $N_1(n)$, given $N_1(j)$, for Efron’s BCD($p$) using combinatoric arguments, also the conditional variance–covariance matrix of $T$, which allows computation of the information fraction.

The class of generalized biased coin designs (GBCD) [Wei (1978)] does not have a known form for the exact conditional distribution, and this remains an open problem. For the sequential monitoring of conditional tests using the GBCD with one interim look, Zhang and Rosenberger (2008) derived the joint asymptotic distribution of the interim and the final test statistics, which allows for an asymptotic test.

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**SUPPLEMENTARY MATERIAL**

**Supplement to “Sequential monitoring with conditional randomization tests”** (DOI: 10.1214/11-AOS941SUPP; .pdf). The supplement contains Appendix A (proof of Theorem 2.2), Appendix B (proof of Lemma 3.1), Appendix C (proof of Theorem 3.1), and Appendix D (proof of Lemma 4.3).

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