Decomposition spaces and restriction species

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Abstract. We show that Schmitt’s restriction species (such as graphs, matroids, posets, etc.) naturally induce decomposition spaces (a.k.a. unital 2-Segal spaces), and that their associated coalgebras are an instance of the general construction of incidence coalgebras of decomposition spaces. We introduce the notion of directed restriction species that subsume Schmitt’s restriction species and also induce decomposition spaces. Whereas ordinary restriction species are presheaves on the category of finite sets and injections, directed restriction species are presheaves on the category of finite posets and convex maps. We also introduce the notion of monoidal (directed) restriction species, which induce monoidal decomposition spaces and hence bialgebras, most often Hopf algebras. Examples of this notion include rooted forests, directed graphs, posets, double posets, and many related structures. A prominent instance of a resulting incidence bialgebra is the Butcher–Connes–Kreimer Hopf algebra of rooted trees. Both ordinary and directed restriction species are shown to be examples of a construction of decomposition spaces from certain cocartesian fibrations over the category of finite ordinals that are also cartesian over convex maps. The proofs rely on some beautiful simplicial combinatorics, where the notion of convexity plays a key role. The methods developed are of independent interest as techniques for constructing decomposition spaces.

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2010 Mathematics Subject Classification. 18G30, 16T10, 06A07; 18-XX, 55Pxx.

The first author was partially supported by grants MTM2012-38122-C03-01, 2014-SGR-634, MTM2013-42178-P, MTM2015-69135-P, and MTM2016-76453-C2-2-P, the second author by MTM2013-42293-P and MTM2016-80439-P and the third author by MTM2013-42178-P and MTM2016-76453-C2-2-P.
0. Introduction

The notion of decomposition space was introduced in [18] as a very general framework for incidence (co)algebras and Möbius inversion. Let us briefly recount the abstraction steps that led to this notion, taking as starting point the classical theory of incidence algebras of locally finite posets. More extensive introductions can be found in [18] and in [21]. A very different motivation and formulation of the notion is due to Dyckerhoff and Kapranov [10].

The first step is the observation due to Leroux [37], that both the notions of locally finite poset (Rota et. al [26, 45]) and monoid with the finite decomposition property (Cartier–Foata [6]) admit a natural common generalisation in the notion of Möbius category, and that this setting allows for good functorial properties.

The next step is to observe that in many examples where symmetries play a role, a more elegant treatment can be achieved by considering groupoid-enriched categories instead of plain (set-enriched) categories, as illustrated in [15]. This involves a homotopical viewpoint, in which the algebraic identities arise as homotopy cardinality of equivalences of groupoids, rather than just ordinary cardinality of bijections of sets. At the same time it becomes clear that the algebraic structures can actually be defined and manipulated at the objective level, postponing the act of taking cardinality, and that structural phenomena can be seen at this level which are not visible at the usual ‘numerical’ level. For example, at this level of abstraction one can view the algebra of species under the Cauchy tensor product as the incidence algebra of the symmetric monoidal category of finite sets and bijections [21]. (The homotopy viewpoint induces one to consider even $\infty$-groupoids [17, 18], but this is not important in the present contribution.)

Finally, considering groupoid-enriched categories as simplicial groupoids via the nerve construction led to the discovery [18] that the Segal condition, which essentially characterises category objects among simplicial groupoids, is not actually needed, and that a weaker notion suffices for the theory of incidence (co)algebras and Möbius inversion: this is the notion of decomposition space, which can be seen as the systematic theory of decompositions, where categories are the systematic theory of compositions.

While many coalgebras and bialgebras in combinatorics do arise from (groupoid-enriched) categories, there are also many examples that can easily be seen not to arise from such categories. Two prominent examples are the Schmitt Hopf algebra of graphs [47] (also called the chromatic Hopf algebra [1]), and the Butcher–Connes–Kreimer Hopf algebra of rooted trees (see [9] and [7]). These two examples are reviewed below, where we shall see that they cannot possibly arise directly from categories, but that they do naturally come from decomposition spaces, cf. [18, 21]. (They can be obtained indirectly from certain auxiliary categories, by means of a reduction step, cf. Dür [9].)

The aim of the present paper is to fit these two examples into a large class of decomposition spaces. One may say there are two large classes of decomposition spaces, but the first can be regarded as a special case of the second. The first is the class of decomposition spaces coming from Schmitt’s restriction species [46]—Schmitt already showed that the Hopf algebra of graphs comes from a restriction species. While restriction species are presheaves on the category of finite sets and injections, expressing the ability to decompose combinatorial structures, the new notion of directed restriction species expresses decompositions compatible with an underlying partial order:
Definition. A directed restriction species is a presheaf on the category of finite posets and convex maps.

Ordinary restriction species can be regarded as directed restriction species supported on discrete posets.

We show that every directed restriction species defines a decomposition space, and hence a coalgebra. Instead of constructing these simplicial objects by hand, we found it worth taking a slight detour through some more abstract constructions. On one hand, this serves to exhibit the general principles behind the results, and on the other to develop machinery of independent interest for the sake of constructing decomposition spaces. We route the construction through certain sesquicartesian fibrations over \( \Delta \) (the category of finite ordinals, including the empty ordinal): they are cocartesian fibrations which are furthermore cartesian over convex maps, satisfying Beck–Chevalley, and subject to one further condition which we refer to as the \( \text{iesq} \) (for ‘identity-extension-square’) condition.

The main results can now be organised as follows:

**Theorem.** (Proposition 10.6 and Corollary 10.8.) Restriction species and directed restriction species naturally induce \( \text{iesq} \) sesquicartesian fibrations.

**Theorem 9.7.** \( \text{iesq} \) sesquicartesian fibrations naturally induce decomposition spaces.

Together, and more precisely:

**Theorem.** (Theorems 11.4 and 11.5.) There is a functor from restriction species to decomposition spaces \( \text{CULF} \) over \( I \), and this functor is fully faithful. Similarly there is a functor from directed restriction species to decomposition spaces \( \text{CULF} \) over \( C \), also fully faithful.

Here \( I \) is a certain decomposition space of layered finite sets (§4), and \( C \) is a certain decomposition space of layered finite posets (§6). For CULF functors, see 1.11 below.

Many combinatorial structures which form (directed) restriction species are closed under taking disjoint union in a way compatible with restrictions. We capture this through the notion of monoidal directed restriction species (7.8), and show:

**Proposition 7.9.** Monoidal directed restriction species naturally induce monoidal decomposition spaces and hence bialgebras.

Examples of this notion include rooted forests, directed graphs, posets, double posets, and many related structures. A prominent instance of a resulting incidence bialgebra is the Butcher–Connes–Kreimer Hopf algebra of rooted trees.

**Note.** This paper was originally posted as Section 6 of the long manuscript *Decomposition spaces, incidence algebras and Möbius inversion* [16], which has now been split into six papers, the first five being [17, 18, 19, 20, 21]. The relevant definitions and results from these papers (mostly [18]) are reviewed below as needed, to render the paper reasonably self-contained.

**Acknowledgments.** We wish to thank André Joyal and Mark Weber for some very pertinent remarks, and apologise for not being able to follow them through to their full depth in the present contribution.
1. Decomposition spaces

In this section we briefly recall and motivate the notion of decomposition space.

1.1. Incidence coalgebras of locally finite posets and categories. Recall from Rota et al. [26, 45] that for a locally finite poset, a coalgebra structure is induced on the vector space spanned by its intervals, with comultiplication given by

$$\Delta([x, y]) = \sum_{m \in [x,y]} [x,m] \otimes [m,y].$$

The local finiteness condition is precisely what ensures that the sum is finite. Coassociativity is a consequence of transitivity of the poset relation.

A poset can be regarded as a category in which there is one arrow from $x$ to $y$ if and only if $x \leq y$. Thus intervals in a poset correspond to arrows in the category, and the incidence coalgebra construction generalises immediately to locally finite categories, as first observed by Leroux [37]: the coalgebra has as underlying vector space the one spanned by the arrows, and the comultiplication is given by

$$\Delta(f) = \sum_{bo=f} a \otimes b.$$ 

Coassociativity follows from associativity of composition of arrows.

1.2. Nerves, and an objective comultiplication. The nerve of a category $\mathcal{C}$ (e.g. a poset) is the simplicial set $X : \Delta^{op} \to \text{Set}$ whose $n$-simplices are sequences of $n$ composable arrows. This can be written formally as

$$X_n = \text{Fun}([n], \mathcal{C}),$$

where $\text{Fun}([n], \mathcal{C})$ denotes just the set of functors $[n] \to \mathcal{C}$. The face maps $d_i : X_{n+1} \to X_n$ compose the two consecutive arrows at the $i$th object (for the inner face maps, $0 < i < n$) or project away the first or last arrow in the sequence (for the outer face maps, $i = 0$ or $i = n$). The comultiplication formula can now be seen at the objective level of the arrows themselves (not the vector space spanned by them) as given by the canonical span

$$X_1 \xleftarrow{d_1} X_2 \xrightarrow{(d_2,d_0)} X_1 \times X_1$$

by pullback along $d_1$ and composing along $(d_2,d_0)$. Indeed the fibre of $d_1$ over an arrow $f \in X_1$ is the set of composable pairs with composite $f$, and $(d_2,d_0)$ then returns the two constituents. Properly formalising this construction involves working with the slice category $\text{Set}_{/X_1}$ instead of the vector space spanned by $X_1$, and the comultiplication is then a functor rather than just a function. The classical viewpoint can be recovered by taking cardinality of the sets involved.

1.3. Groupoids and homotopy viewpoints. In practice one is often interested in combinatorial objects up to isomorphism, but at the same time wants to keep track of automorphisms. This can be accomplished elegantly by working with groupoids instead of sets, provided the homotopy viewpoint is taken consistently. The classical viewpoint is recovered by taking homotopy cardinality, and all constructions should be performed in a homotopy invariant way. In particular, all pullbacks must be homotopy pullbacks, since this is the homotopy invariant notion.

Throughout, when we say pullback, we refer to the homotopy pullback.
Strict pullbacks are not in general homotopy invariant, except if one of the maps pulled back along is an iso-fibration; this will be exploited occasionally. Similarly, when we talk about simplicial groupoids, we must allow pseudo-functors $\Delta^{op} \to \text{Grpd}$ instead of just strict functors, since this is the homotopy invariant notion. Most of our simplicial groupoids will actually happen to be strict, though, as is the case with fat nerves:

1.4. Fat nerve. Starting with a small category $\mathcal{C}$, instead of working with its ordinary nerve as above, one considers instead its fat nerve. This is a simplicial groupoid $X = N\mathcal{C} : \Delta^{op} \to \text{Grpd}$ rather than a simplicial set, and is defined formally by

$$X_n = \text{Map}([n], \mathcal{C}),$$

the groupoid whose objects are functors $[n] \to \mathcal{C}$ (i.e. $n$-sequences of arrows), and whose morphisms are invertible natural transformations between them. This means that we keep track of the fact that two arrows $f$ and $g$ in $\mathcal{C}$ may be isomorphic by way of a commutative square

$$\begin{array}{ccc}
\ast & \xrightarrow{f} & \ast \\
\downarrow & & \downarrow \\
\ast & \xrightarrow{g} & \ast
\end{array}$$

and similarly for $n$-sequences. The fat nerve constitutes a functor from categories to simplicial groupoids, and this functor is fully faithful.

The comultiplication formula resulting from the span construction now concerns isoclasses of arrows, and the sum is over isoclasses of factorisations. In practice this is precisely what one wants. For example, if $\mathcal{C}$ is the category of finite sets and surjections, the incidence coalgebra resulting from the fat nerve is the Faà di Bruno coalgebra [27]. Recovering the classical setting now involves homotopy cardinality of groupoids rather than cardinality of sets—this is just a question of taking the isomorphisms into account properly. This will be recalled below in 1.10.

1.5. Decomposition spaces. It turns out that simplicial groupoids other than fat nerves of categories induce coalgebras. Fat nerves of categories can be characterised (in part) by the Segal condition, which can be stated as requiring all squares of the form

$$\begin{array}{ccc}
X_{n+1} & \xrightarrow{d_0} & X_n \\
\downarrow & \downarrow & \downarrow \\
X_n & \xrightarrow{d_n} & X_{n-1}
\end{array}$$

to be pullbacks. The most important one is

$$\begin{array}{ccc}
X_2 & \xrightarrow{d_0} & X_1 \\
\downarrow & \downarrow & \downarrow \\
X_1 & \xrightarrow{d_0} & X_0
\end{array}$$

which says that $X_2$ can be identified with the groupoid $X_1 \times_{X_0} X_1$ of composable pairs of arrows. The Segal condition thus expresses the ability to compose.
The decomposition-space axiom, which is weaker, stipulates that certain other squares are pullbacks, the most important cases being

\[
\begin{array}{c}
\begin{array}{ccc}
X_3 & \xrightarrow{d_2} & X_2 \\
\downarrow{d_0} & & \downarrow{d_0} \\
X_2 & \xrightarrow{d_1} & X_1
\end{array}
& \quad & \\
\begin{array}{ccc}
X_3 & \xrightarrow{d_1} & X_2 \\
\downarrow{d_3} & & \downarrow{d_2} \\
X_2 & \xrightarrow{d_1} & X_1
\end{array}
\end{array}
\]

We refer to [21] for an explanation of the combinatorial meaning of this condition and a picture. It can be interpreted as the expression of the ability to decompose.

To define more formally what a decomposition space is—and to construct them—we need some simplicial technicalities.

1.6. Generic and free maps (active and inert maps [38]). The category $\Delta$ of nonempty finite ordinals $\{0, 1, \ldots, n\}$ and monotone maps has a so-called generic-free factorisation system (a general categorical notion, important in monad theory [52, 53]). An arrow $a : [m] \to [n]$ in $\Delta$ is generic (also called active) when it preserves endpoints, $a(0) = 0$ and $a(m) = n$; we use the special arrow symbol $\rightarrow$ to denote generic maps. An arrow $a : [m] \to [n]$ in $\Delta$ is free (also called inert) if it is distance preserving, $a(i + 1) = a(i) + 1$ for $0 \leq i \leq m - 1$; we use the special arrow symbol $\rightsquigarrow$. The generic maps are generated by the codegeneracy maps $s^i : [n+1] \to [n]$ and by the inner coface maps $d^i : [n-1] \to [n]$, $0 < i < n$, while the free maps are generated by the outer coface maps $d^\perp := d^0$ and $d^{\top} := d^n$. Every morphism in $\Delta$ factors uniquely as a generic map followed by a free map. Furthermore, it is a basic fact [18] that generic and free maps in $\Delta$ admit pushouts along each other, and the resulting maps are again generic and free.

1.7. Decomposition spaces [18]. A simplicial groupoid $X : \Delta^{\text{op}} \to \text{Grpd}$ is called a decomposition space when it takes generic-free pushouts in $\Delta$ to pullbacks.

The notion is equivalent to the unital 2-Segal spaces of Dyckerhoff and Kapranov [10], formulated in terms of triangulations of polygons. Their work shows that the notion is of interest well beyond combinatorics.

**Theorem 1.8.** [18] If $X : \Delta^{\text{op}} \to \text{Grpd}$ is a decomposition space, the span construction above induces on $\text{Grpd}/X_1$ the structure of a coassociative and counital coalgebra (up to coherent equivalence). Upon taking homotopy cardinality (in suitably finite situations, cf. 1.9 below), this yields a coalgebra in the classical sense.

The fat nerve of a category is always a decomposition space. Since the Segal-axiom squares are not special cases of the decomposition-space axioms, this requires proof, but it is not a deep result [18]. Intuitively, the reason is that in situations where one can compose (that is, in a category), one can always decompose, by summing over all possible ways an object could have arisen by composition.

1.9. Finiteness conditions (cf. [19]). Various finiteness conditions are important for various reasons. They tend to be satisfied in examples coming from combinatorics, and we shall establish them for all restriction species and directed restriction species. Let us briefly comment on these conditions.

In order to be able to take homotopy cardinality to get a coalgebra in vector spaces, it is necessary to assume that $X$ is locally finite (cf. [19, §7]). This means first of all that
$X_1$ is a locally finite groupoid (i.e. has finite automorphism groups), and second that each generic map is a finite map (i.e. has finite fibres). For a decomposition space $X$, this can be measured on the two maps

$$X_0 \xrightarrow{s_1} X_1 \xleftarrow{d_1} X_2.$$ 

For the comultiplication formula to be free of denominators, another condition is required, namely that $X$ must be locally discrete (cf. [21, §1.4]), which for a decomposition space amounts to the two displayed maps having discrete fibres.

In order to have a M"obius inversion formula, yet another finiteness condition is needed, which refers to a notion of non-degeneracy which is meaningful for complete decomposition spaces (cf. [19, §2]), i.e. those for which $s_0$ is mono. The condition is to have locally finite length, and it means (cf. [19, §6]) that for each $a \in X_1$ there is an upper bound on the $n$ for which the map $X_n \rightarrow X_1$ has non-degenerate elements in the fibre. See op cit. for precision—the upshot is that there are only finitely many ways of splitting an object into non-degenerate pieces.

**1.10. Homotopy cardinality.** Assuming local finiteness, the groupoid-level incidence coalgebra yields a vector-space level coalgebra by taking homotopy cardinality. We refer to [17] for the full story (in the setting of $\infty$-groupoids) and to [21] for some introduction geared towards combinatorics. Very briefly, the homotopy cardinality of a groupoid $X$ is defined to be $\sum_{x \in \pi_0 X} |\text{Aut}(x)|$. The groupoid slice $\text{Grpd}_S$ is the objective counterpart of the vector space $\mathbb{Q}_{\pi_0 S}$ spanned by the symbols $\delta_s$ denoting isoclasses of objects in $S$. The cardinality of an object $X \rightarrow S$ is then the formal linear combination $\sum_{s \in \pi_0 S} \frac{|X_s|}{|\text{Aut}(s)|} \delta_s$, where $|X_s|$ is the homotopy cardinality of the homotopy fibre $X_s$.

If the groupoids involved are just sets, the automorphism groups are trivial, and the notion reduces to ordinary cardinality. Building the automorphism groups into the definition ensures it behaves well with respect to all the important operations, such as products and sums, (homotopy) pullbacks and (homotopy) fibres, etc.

**1.11. CULF functors.** The relevant notion of morphism between decomposition spaces is that of CULF functor [18]: CULF functors between decomposition spaces induce coalgebra homomorphisms. A simplicial map is called ULF (unique lifting of factorisations) if it is cartesian on generic face maps, and it is called conservative if cartesian on degeneracy maps. We say CULF for conservative and ULF, that is, cartesian on all generic maps.

Since CULFness refers to generic maps, just as the finiteness conditions just stated, we have the following useful result.

**Lemma 1.12.** Let $P$ denote a property of decomposition spaces which is measured on generic maps (such as being locally discrete or of locally finite length). Then if $F : Y \rightarrow X$ is CULF and $X$ has property $P$, then also $Y$ has property $P$. This is also the case for the property of being locally finite, except we must check additionally that $Y_1$ is locally finite.

In fact, also:

**Lemma 1.13.** A simplicial groupoid CULF over a decomposition space is itself a decomposition space.

**1.14. Monoidal decomposition spaces and bialgebras.** There is a natural notion of monoidal decomposition space [18], leading to bialgebras. Briefly, it is a decomposition space $X$ equipped with a functor $\otimes : X \times X \rightarrow X$ required to be a monoidal structure,
and required to be CULF. The homotopy cardinality of this monoidal structure is an algebra structure, and the CULF condition ensures the compatibility with the coalgebra structure to result altogether in a bialgebra. This is important in most applications to combinatorics, where almost always this monoidal structure, and hence the algebra structure, is given by disjoint union. In the present contribution we focus mostly on the comultiplication, but comment on monoidal structure in 5.14–5.15 and 7.8–7.9.

1.15. Decalage. (See [25].) Given a simplicial groupoid $X$ as the top row in the following diagram, the lower $\text{Dec}_\perp \colon \text{Dec}_\perp(X)$ is a new simplicial groupoid (the bottom row in the diagram) obtained by deleting $X_0$ and shifting everything one place down, deleting also all $d_0$ face maps and all $s_0$ degeneracy maps. It comes equipped with a simplicial map, called the dec map, $d_\perp : \text{Dec}_\perp(X) \to X$ given by the original $d_0$:

$$
\begin{array}{ccccccc}
X_0 & \xrightarrow{d_1} & X_1 & \xrightarrow{d_2} & X_2 & \xrightarrow{d_3} & X_3 & \ldots \\
\downarrow{d_0} & & \downarrow{d_0} & & \downarrow{d_0} & & \downarrow{d_0} & \\
X_1 & \xrightarrow{d_1} & X_2 & \xrightarrow{d_2} & X_3 & \xrightarrow{d_1} & X_4 & \ldots
\end{array}
$$

In the present contribution, we shall exploit decalage to relate the fat nerve of the Grothendieck construction of a restriction species with its associated decomposition space (Proposition 11.1 and Corollary 11.3), in turn important in proving fully faithfulness of the construction of decomposition spaces.

In a broader perspective, decalage plays an important role in the theory of decomposition spaces: on one hand, many reduction procedures in classical combinatorics can be expressed in terms of decalage [21], and on the other hand, the very notion of decomposition space can be characterised in terms of decalage, by virtue of the following result from [18, Theorem 4.11] (see also [10]):

**Theorem 1.16.** $X$ is a decomposition space if and only if $\text{Dec}_\top(X)$ and $\text{Dec}_\perp(X)$ are Segal spaces, and the dec maps $d_\top : \text{Dec}_\top(X) \to X$ and $d_\perp : \text{Dec}_\perp(X) \to X$ are CULF.

1.17. Right fibrations and left fibrations. (See [18].) A functor between simplicial groupoids $f : Y \to X$ is called a right fibration if it is cartesian on all bottom face maps $d_\perp$. This implies that it is also cartesian on all generic maps (i.e. is CULF). The terminology is motivated by the case where $Y$ and $X$ are Segal spaces, in which case it corresponds to standard usage in the theory of ∞-categories. If $X$ and $Y$ are fat nerves of categories, then ‘right fibration’ corresponds to groupoid fibration in the sense of Street [50].

Similarly, $f$ is called a left fibration if it is cartesian on $d_\top$ (and consequently on all generic maps also).

**Lemma 1.18.** If $f : Y \to X$ is a CULF functor between decomposition spaces, then $\text{Dec}_\perp(f) : \text{Dec}_\perp(Y) \to \text{Dec}_\perp(X)$ is a right fibration of Segal spaces. Similarly, $\text{Dec}_\top(f) : \text{Dec}_\top(Y) \to \text{Dec}_\top(X)$ is a left fibration.
2. Two motivating examples and two basic examples

While many important examples of coalgebras in combinatorics come from decomposition spaces which are just (fat nerves of) categories, there are also many examples which do not (directly) come from a category. (Sometimes, a construction can be made, involving a reduction procedure [9].)

In this section we first explain the two examples that triggered the present investigations, and then explain the most basic example from the two families they belong to. The first example, Schmitt’s Hopf algebra of graphs, is an example of a restriction species. The terminal restriction species is that of finite sets. The second example, the Butcher–Connes–Kreimer Hopf algebra is an example of a new notion we introduce, directed restriction species, and the terminal such is the example of finite posets.

2.1. The chromatic Hopf algebra (of graphs).

The following Hopf algebra of graphs was first studied by Schmitt [47], and later by Aguiar–Bergeron–Sottile [1] and Humpert–Martin [24]. For a graph $G$ with vertex set $V$ (admitting multiple edges and loops), and a subset $U \subset V$, define $G|U$ to be the graph whose vertex set is $U$, and whose graph structure is induced by restriction (that is, the edges of $G|U$ are those edges of $G$ both of whose incident vertices belong to $U$). On the vector space spanned by isoclasses of graphs, define a comultiplication by the rule

$$\Delta(G) = \sum_{A+B=V} G|A \otimes G|B.$$ 

This coalgebra is the cardinality of the coalgebra of a decomposition space but not directly of a category. Indeed, define a simplicial groupoid with $G_1$ the groupoid of graphs, and more generally $G_k$ the groupoid of graphs with an ordered partition of the vertex set $V$ into $k$ parts (possibly empty), i.e. a function $V \rightarrow k$ (this is what we shall call a layering (4.1)). In particular, $G_0$ is the contractible groupoid consisting only of the empty graph. The outer face maps delete the first or last part of the graph, and the inner face maps join adjacent parts. The degeneracy maps insert an empty part. It is clear that this is not a Segal space: a graph structure on a given set cannot be reconstructed from knowledge of the graph structure of the parts of the set, since chopping up the graph and restricting to the parts throws away all information about edges going from one part to another. One can easily check that it is a decomposition space (see [21], where there is also a nice picture illustrating the decomposition-space axiom in this case), hence induces a coalgebra. Note that disjoint union of graphs makes this into a bialgebra. With grading by the number of vertices, this is a connected graded bialgebra, hence a Hopf algebra, clearly precisely Schmitt’s chromatic Hopf algebra.

2.2. Butcher–Connes–Kreimer Hopf algebra.

A rooted tree is a connected and simply-connected graph with a specified root vertex; a forest is a disjoint union of rooted trees. The Butcher–Connes–Kreimer Hopf algebra of rooted trees [7] is the free algebra on the set of isoclasses of rooted trees, with comultiplication defined by summing over certain admissible cuts $c$:

$$\Delta(T) = \sum_{c \in \text{adm. cuts}(T)} P_c \otimes R_c.$$ 

An admissible cut $c$ is a splitting of the set of nodes into two subsets, such that the second forms a subtree $R_c$ containing the root node (or is the empty forest); the first subset, the
complement ‘crown’, then forms a subforest $P_c$, regarded as a monomial of trees. Note that compared to the arbitrary splitting allowed in Schmitt’s Hopf algebra of graphs, the admissible cuts are thus required to be compatible with the partial order underlying trees and forests.

Dür [9] (Ch.IV, §3) gave an incidence-coalgebra construction of the Butcher–Connes–Kreimer coalgebra by starting with the category $\mathcal{C}$ of forests and root-preserving inclusions, generating a coalgebra (in our language the incidence coalgebra of the fat nerve of $\mathcal{C}$, cf. [21]), and imposing the equivalence relation that identifies two root-preserving forest inclusions if their complement crowns are isomorphic forests. To be precise, this yields the opposite of the Butcher–Connes–Kreimer coalgebra, in the sense that the factors $P_c$ and $R_c$ are interchanged. To remedy this, one should just use $\mathcal{C}^{\text{op}}$ instead of $\mathcal{C}$.

We can obtain the Butcher–Connes–Kreimer coalgebra directly from a decomposition space (cf. [21]): let $H_1$ denote the groupoid of forests, and let $H_2$ denote the groupoid of forests with an admissible cut. More generally, $H_k$ is defined to be a point, and $H_k$ is the groupoid of forests with $k-1$ compatible admissible cuts. These form a simplicial groupoid $H$ in which the inner face maps forget a cut, and the outer face maps project away either the crown or the bottom layer (the part of the forest below the bottom cut). It is clear that $H$ is not a Segal space: a tree with a cut cannot be reconstructed from its crown and its bottom tree, which is to say that $H_2$ is not equivalent to $H_1 \times_{H_0} H_1$. It is straightforward to check that it is a decomposition space, and that its incidence coalgebra is precisely the Butcher–Connes–Kreimer coalgebra.

The relationship with Dür’s construction is this (cf. [21]): the ‘raw’ decomposition space $N(\mathcal{C}^{\text{op}})$ is the decalage of $H$:

$$\text{Dec}_\top H \simeq N(\mathcal{C}^{\text{op}}).$$

Furthermore, the dec map $\text{Dec}_\top H \to H$, always a CULF functor, realises precisely Dür’s reduction.

As in the graph example, disjoint union makes this coalgebra into a bialgebra. It is graded by the number of nodes, and since the empty forest is the only one without nodes, this bialgebra is connected, and hence a Hopf algebra.

(While the decomposition space $H$ is not a Segal space, it admits important variations which are Segal spaces, namely by replacing the combinatorial trees above by operadic trees, as explained in 7.12.)

### 2.3. Getting decomposition spaces from restriction species and directed restriction species.

The graph example is just one in a large family of coalgebras (and bialgebras) constructed by Schmitt [46], namely coalgebras induced by restriction species (see also [2]). We shall show, first of all, that restriction species in the sense of Schmitt [46] are examples of decomposition spaces, and that they and their associated coalgebras exemplify the general construction. The example with trees does not come from a restriction species, but we introduce the notion of directed restriction species, which covers this examples and many others, and which also define decomposition spaces.

The next two examples are the basic ones.

#### 2.4. The binomial Hopf algebra.

Define a comultiplication on the vector space spanned by isoclasses of finite sets by

$$\Delta(A) = \sum_{A_1 + A_2 = A} A_1 \otimes A_2.$$
2.5. The Hopf algebra of finite posets. Define a comultiplication on the vector space spanned by isoclasses of finite posets by

\[ \Delta(P) = \sum_{c \in \text{cuts}(P)} D_c \otimes U_c. \]

Here the sum is over all admissible cuts of \( P \); an admissible cut \( c = (D_c, U_c) \) is by definition a way of writing \( P \) as the disjoint union of a lower-set \( D_c \) and an upper-set \( U_c \). This coalgebra was studied by Aguiar–Bergeron–Sottile [1], who trace its origins back to Gessel [22]. See also Figueroa–Gracia-Bondía [11].

3. Simplicial preliminaries

A key ingredient in our constructions is the beautiful interplay between the topologist’s Delta and the algebraist’s Delta. After setting up the notation, we establish a certain correspondence between squares in the two categories.

3.1. ‘Topologist’s Delta’. The category \( \Delta \) is the skeleton of the category of non-empty finite ordered sets and monotone maps.

Notation: its objects are \([n] := \{0, 1, \ldots , n\}, \quad n \geq 0\).

The monotone maps are generated by

- \( s^k : [n+1] \rightarrow [n] \) that repeats the element \( k \in [n] \),
- \( d^k : [n] \rightarrow [n+1] \) that skips the element \( k \in [n+1] \).

Note that \([0]\) is terminal.

3.2. ‘Algebraist’s Delta’. The category \( \underline{\Delta} \) is the skeleton of the category of finite ordered sets (including the empty set) and monotone maps.

Notation: its objects are \( \underline{n} := \{1, \ldots , n\}, \quad n \geq 0\).

The monotone maps are generated by

- \( s^k : n+1 \rightarrow n \) that repeats the element \( k+1 \in \underline{n}, \quad (0 \leq k \leq n-1) \),
- \( d^k : n \rightarrow n+1 \) that skips the element \( k+1 \in \underline{n+1}, \quad (0 \leq k \leq n) \).

Note that \( \underline{1} \) is terminal, \( \underline{0} \) is initial, and the only map with target \( \underline{0} \) is the identity.

There is a full inclusion \( \Delta \rightarrow \underline{\Delta} \) which on objects sends \( [n] = \{0, \ldots , n\} \) to \( \underline{n+1} = \{1, \ldots , n+1\} \). On maps it just does nothing, up to the canonical relabelling of the elements, \( [n] \cong \underline{n+1} \). Thus it sends \( d^k \) to \( d^k \) and \( s^k \) to \( s^k \).

More important is the following duality, which is standard [28].

Lemma 3.3. There is a canonical isomorphism of categories

\[ \Delta_{\text{gen}}^{\text{op}} \cong \underline{\Delta}. \]

- \( \underline{n} \) corresponds to \([n]\),
- \( d^k : \underline{n} \rightarrow \underline{n+1} \) corresponds to \( s^k : [n+1] \rightarrow [n] \),
- \( s^k : n+1 \rightarrow n \) corresponds to the inner coface map \( d^{k+1} : [n] \rightarrow [n+1] \).
The following graphical representation may be helpful. In \(\Delta\), draw the elements in \(n\) as \(n\) dots, and in \(\Delta_{\text{gen}}\) draw the elements in \([n]\) as \(n+1\) walls. A map operates as a function on the set of dots when considered a map in \(\Delta\) while it operates as a function on the walls when considered a map in \(\Delta_{\text{gen}}\). Here is a picture of a certain map \(5 \to 4\) in \(\Delta\) and of the corresponding map \([5] \leftarrow [4]\) in \(\Delta_{\text{gen}}\).

### 3.4. Ordinal sum.

The ordinal sum monoidal structure \((\Delta, +, 0)\) gives a monoidal structure \((\Delta_{\text{gen}}, \lor, [0])\), via Lemma 3.3. The free maps \([n] \mapsto [n']\) in \(\Delta\) may be expressed uniquely as \([n] \mapsto [a] \lor [n] \lor [b]\). Any map \([k] \to [n']\) in \(\Delta\) has a unique factorisation as a generic map \(f : [k] \to [n] \lor [n] \lor [b] = [n']\).

### 3.5. Pullbacks in \(\Delta\).

We shall need the following lemmas, whose proofs are straightforward.

**Lemma 3.6.** For each \(0 \leq k \leq n\), the following square is a pullback in \(\Delta\):

\[
\begin{array}{ccc}
  n & \xrightarrow{d^k} & n+1 \\
  \downarrow & & \downarrow \\
  n & \xrightarrow{d^k} & n+1.
\end{array}
\]

**Lemma 3.7.** For each \(0 \leq k \leq n\), the following square is a pullback in \(\Delta\):

\[
\begin{array}{ccc}
  n & \xrightarrow{d^k} & n+1 \\
  \downarrow & & \downarrow \\
  n & \xrightarrow{d^k} & n+1.
\end{array}
\]

**Lemma 3.8.** For \(0 < k < n\) and all \(j\) the following squares are pullbacks

\[
\begin{array}{ccc}
  n & \xrightarrow{d^j} & n+1 \\
  \downarrow & & \downarrow \\
  n & \xrightarrow{d^j} & n+1 \\
  \downarrow & & \downarrow \\
  n & \xrightarrow{d^j} & n+1 \\
  \downarrow & & \downarrow \\
  n & \xrightarrow{d^j} & n+1.
\end{array}
\]

### 3.9. Convex maps.

A map \(j\) in \(\hat{\Delta}\) is called convex and written \(j : n \to n'\) if it is distance-preserving: \(j(x+1) = j(x) + 1\), for all \(x \in n\). (In the subcategory \(\Delta \subset \hat{\Delta}\) we called these ‘free maps’. We prefer to use different names since they play a different role in the two categories.) Observe that the convex maps are just the canonical inclusions

\[j : n \to a + n + b,\]

and that, for \(k > 0\), there is a canonical bijection

\[\Delta_{\text{convex}}(k, n) \cong \Delta_{\text{convex}}(k+1, n+1).\]
In combination with the full inclusion $\Delta \subset \Delta$, we get

**Lemma 3.10.** For $k > 0$, there is a canonical isomorphism

$$\Delta_{\text{free}}^{\geq 1} \cong \Delta_{\text{convex}}^{\geq 1}, \quad [k] \mapsto k \quad (k \geq 1).$$

Note that this does not extend to $k \geq 0$ (since $0$ is initial but $[0]$ is not).

**Lemma 3.11.** Convex maps in $\Delta$ admit pullback along any map: given the solid cospan consisting of $g$ and $i$, with $i$ convex,

$$\begin{array}{ccc}
  n' & \xleftarrow{j} & n \\
  g & \xrightarrow{i} & \\
  k' & \xleftarrow{i} & k,
\end{array}$$

the pullback exists and $j$ is again convex.

**Lemma 3.12.** For $k > 0$, there is a bijection between the set of pullback squares along convex maps in $\Delta$ and the set of commutative squares of generic against free maps in $\Delta$,

$$\left\{ \begin{array}{c}
  n' \xleftarrow{j} n \\
  i \downarrow \\
  k' \xleftarrow{i} k
\end{array} \right\} \quad \text{in} \quad \Delta \quad \cong \quad \left\{ \begin{array}{c}
  [n'] \xleftarrow{f} [n] \\
  [k'] \xleftarrow{i} [k]
\end{array} \right\} \quad \text{in} \quad \Delta.$$

The bijection is given by Lemma 3.3 on the vertical maps, and by Lemma 3.10 on the bottom horizontal map.

In the case $k = 0$, we necessarily have $n = 0$ and $n' = k'$, but there is not even a bijection on the bottom arrows in this case.

**Proof.** The bijection is the composite of the three bijections

$$\left\{ \begin{array}{c}
  n' \xleftarrow{j} n \\
  i \downarrow \\
  k' \xleftarrow{i} k
\end{array} \right\} \quad \cong \quad \left\{ \begin{array}{c}
  n' \xleftarrow{j} n \\
  i \downarrow \\
  k' \xleftarrow{i} k
\end{array} \right\} \quad \cong \quad \left\{ \begin{array}{c}
  [n'] \xleftarrow{f} [n] \\
  [k'] \xleftarrow{i} [k]
\end{array} \right\} \quad \cong \quad \left\{ \begin{array}{c}
  [n'] \xleftarrow{f} [n] \\
  [k'] \xleftarrow{i} [k]
\end{array} \right\},$$

where the first bijection is by existence of pullbacks along convex maps (Lemma 3.11), the second is by Lemmas 3.3 and 3.10 (here we use that $k > 0$), and the third is by unique generic–free factorisation of the composite $[k] \to [k'] \to [n']$. It can be checked that the bijection between the right-hand arrows is again that of Lemma 3.3. In fact, the bijection is

$$\left\{ \begin{array}{c}
  a_1 + n + a_2 \xleftarrow{f_1 + f_2} n \\
  i \downarrow \\
  b_1 + k + b_2 \xleftarrow{i} k
\end{array} \right\} \quad \cong \quad \left\{ \begin{array}{c}
  [a_1] \vee [n] \vee [a_2] \xleftarrow{f} [n] \\
  g_1 \vee f \vee g_2 \downarrow \\
  [b_1] \vee [k] \vee [b_2] \xleftarrow{i} [k]
\end{array} \right\}.$$  

$\square$
3.13. **Identity-extension squares.** A square in $\Delta$ is called an identity-extension square (iesq) if it is of the form

\[
\begin{array}{ccc}
  a + n + b & \xleftarrow{j} & n \\
\downarrow{\text{id}_a + f + \text{id}_b} & & \downarrow{f} \\
  a + k + b & \xleftarrow{i} & k,
\end{array}
\]

where $i$ and $j$ are convex. Note that an iesq is both a pullback and a pushout.

**Lemma 3.14.** Under the correspondence of Lemma 3.12, identity-extension squares in $\Delta$ correspond to generic-free pushouts in $\Delta$.

4. **The decomposition space $I$ of layered finite sets**

Let $I$ be the category of finite sets and injections. We define and study the monoidal decomposition space $I$ of *layered finite sets*: finite sets with an ordered partition into any number of possibly empty layers. It is equivalent to the monoidal nerve of the monoidal groupoid of finite sets and bijections, but the layering viewpoint will generalise nicely to the directed case (§6).

4.1. **The groupoid of $n$-layered finite sets.** An *$n$-layering*, or just a layering, of a finite set $A$ is a function $p : A \to \underline{n}$. We refer to the fibres $A_i = p^{-1}(i)$, $i \in \underline{n}$, as layers. Layers may be empty. We consider the groupoid $I_n := I_{\text{iso}}/\underline{n}$ of all $n$-layerings of finite sets, whose arrows are commutative triangles,

\[
\begin{array}{ccc}
  A & \xrightarrow{a} & A' \\
\downarrow{k} & & \downarrow{k'} \\
\end{array}
\]

4.2. **The simplicial groupoid of layered finite sets.** We now assemble the groupoids of layered finite sets into a simplicial groupoid. For a generic map $g : \underline{n} \to \underline{m}$ of $\Delta$, consider the map $g^* : I^\text{iso}_{\underline{m}} \to I^\text{iso}_{\underline{n}}$ given by postcomposition with the corresponding map $g : \underline{m} \to \underline{n}$ of $\Delta$ under the correspondence of Lemma 3.3,

\[
g^* := g^* : I^\text{iso}_{\underline{m}} \to I^\text{iso}_{\underline{n}}, \quad (A \to \underline{m}) \mapsto (A \to \underline{n} \xrightarrow{g}).
\]

To define the outer face maps $d_\perp, d_\top : I^\text{iso}_{\underline{k}} \to I^\text{iso}_{\underline{k}-1}$, we take $A \to \underline{k}$ to the pullbacks

\[
\begin{array}{ccc}
  A' & \xrightarrow{A'} & A \\
\downarrow{d_\perp} & \xleftarrow{\text{d}_\perp(a)} & \downarrow{\text{d}^{-1}} \\
  k-1 & \xleftarrow{d^{-1}} & k,
\end{array}
\]

\[
\begin{array}{ccc}
  A' & \xrightarrow{A'} & A \\
\downarrow{d_\top} & \xleftarrow{\text{d}_\top(a)} & \downarrow{\text{d}^+} \\
  k-1 & \xleftarrow{d^+} & k,
\end{array}
\]

projecting away the first or the last layer. We make the specific choice that the pullbacks are given by subsets; this will ensure that the simplicial object we are defining is strict. More abstractly, for a free map $f : \underline{n} \to \underline{m}$ of $\Delta$, the map $f^* : I^\text{iso}_{\underline{m}} \to I^\text{iso}_{\underline{n}}$ is defined by pullback along the corresponding convex map $f : \underline{n} \to \underline{m}$ in $\Delta$, given for $n \geq 1$ by the correspondence of Lemma 3.10 between free maps in $\Delta$ and convex maps in $\Delta$. Note that all maps $[0] \to [n]$ correspond to the unique map $\underline{0} \to \underline{n}$. 
Proposition 4.3. The groupoids $I_i$ and the maps $g^*, f^*$ above form a simplicial groupoid $I$, which is a Segal space, and hence a decomposition space.

PROOF. The generic-generic simplicial identities are already known to hold by construction, because they correspond under $\Delta^{op}_{gen} \simeq \Delta$ to identities in $\Delta$.

We need to check the following nine simplicial identities involving outer face maps:

$$d_\top \circ d_\top = d_\bot \circ d_1$$
$$d_\bot \circ s_\bot = id$$
$$s_k \circ d_\bot = d_\bot \circ s_{k+1}$$
$$d_k \circ d_\bot = d_\bot \circ d_{k+1}$$

These relations, according to the definitions we have given of outer face maps in $I$, translate into the following relations between pullback (upperstar) and postcomposition (lowershriek) operations, using the dictionary compiled in Lemma 3.3.

$$d_\top^* \circ d_\bot^* = d_\bot^* \circ d_\top^*$$
$$d_\bot^* \circ d_1^* = id \circ d_\bot^*$$
$$d_1^* \circ d_\bot^* = d_\bot^* \circ d_1^*$$
$$d_1^* \circ d_\bot^* = d_\bot^* \circ d_1^*$$
$$d_1^* \circ d_\bot^* = d_\bot^* \circ d_1^*$$

The first of these is induced from a commutative square in $\Delta$. The other eight hold by Beck–Chevalley, since the squares in $\Delta$ are pullbacks by Lemmas 3.6–3.8.

The simplicial identities can be arranged to hold on the nose: the only subtlety is the pullback construction involved in defining the outer face maps, but these pullbacks can all be chosen to be always actual subset inclusions.

Finally, since $\mathbb{I}^\text{iso}_m \simeq 1$, the Segal condition says (for each $m, n$) the projection map $\mathbb{I}^\text{iso}_m \to \mathbb{I}^\text{iso}_m \times \mathbb{I}^\text{iso}_n$ must be an equivalence. But this is clear, since an inverse is given by sending $(A \to m, B \to n)$ to $A + B \to m + n$.

□

Lemma 4.4. The decomposition space $I$ is complete, locally finite, locally discrete, and of locally finite length.

PROOF. The checks are straightforward verifications. (Some indications can be found in the similar Lemma 6.13.)

□

Proposition 4.5. The lower Dec of $I$ is naturally equivalent to $\mathbb{N}\mathbb{I}$, the fat nerve of finite sets and injections. This equivalence identifies a map $A \to k$ with the string of $k - 1$ injections

$$A_1 \hookrightarrow A_1 + A_2 \hookrightarrow \ldots \hookrightarrow A_1 + \cdots + A_{k-1} \hookrightarrow A_1 + \cdots + A_k.$$  

(Similarly, the upper dec $\text{Dec}_\top(I)$ is naturally equivalent to $\mathbb{N}\mathbb{I}^{op}$.)

We refer to [21] for a proof. The fat nerve of finite sets and injections is the approach of Dür [9] to the binomial coalgebra, as explained in [21].

Lemma 4.6. $I$ is a monoidal decomposition space under disjoint union.

PROOF. As the proof of Lemma 6.14, but changing $\mathbb{C}$ to $\mathbb{I}$ and $\mathbb{C}$ to $I$ everywhere. □
5. Restriction species

5.1. Schmitt’s restriction species. Recall that $\mathbb{I}$ denotes the category of finite sets and injections. Schmitt [46] defines restriction species to be presheaves on $\mathbb{I}$,

$$R : \mathbb{I}^{\text{op}} \longrightarrow \text{Set}$$

$$A \mapsto R[A].$$

An element $X$ of $R[A]$ is called an $R$-structure on the set $A$. Compared to a classical species [27], a restriction species $R$ is thus functorial not only in bijections but also in injections, meaning that an $R$-structure on a set $A$ induces also such a structure on every subset $B \subset A$ (denoted with a restriction bar):

$$R[A] \longrightarrow R[B]$$

$$X \mapsto X|_B.$$

A morphism of restriction species is just a natural transformation $R \Rightarrow R'$ of functors $\mathbb{I}^{\text{op}} \to \text{Set}$, i.e. for each finite set $A$ a map $R[A] \to R'[A]$, natural in $A$.

5.2. Schmitt construction. The Schmitt construction [46] associates to a restriction species $R : \mathbb{I}^{\text{op}} \to \text{Set}$ a (cocommutative) coalgebra structure on the vector space spanned by the isoclasses of $R$-structures: the comultiplication is

$$\Delta(X) = \sum_{A_1 + A_2 = A} X|A_1 \otimes X|A_2,$$

and the counit sends $X \in R[\emptyset]$ to 1 and other structures to 0.

Since the summation in the comultiplication formula only involves the underlying sets, it is readily seen that a morphism of restriction species induces a coalgebra homomorphism.

A great many (cocommutative) combinatorial coalgebras can be realised by the Schmitt construction (see [46] and also [2]). For example, graphs (2.1), matroids, simplicial complexes, posets, categories, etc., form restriction species and hence coalgebras. In many cases, disjoint union furthermore defines an algebra structure, and altogether a bialgebra. Finally, in most cases, $R[\emptyset]$ is singleton. This implies that the bialgebra is connected and hence a Hopf algebra. Schmitt actually includes this condition in his definition of restriction species. In the present work, we shall not assume $R[\emptyset]$ singleton.

5.3. Groupoid-valued species. In line with our general philosophy, we shall work with groupoids rather than sets, aspiring to a native treatment of symmetries. Groupoid-valued species were first advocated by Baez and Dolan [3] (who called them stuff types, as opposed to structure types, their translation of Joyal’s espèces de structures [27]), for the sake of dealing with symmetries of Feynman diagrams. They showed also that over groupoids (but not over sets), the generating function of a species is the homotopy cardinality of its associated analytic functor. Furthermore, over groupoids, analytic functors are polynomial [30], meaning that they are given by pullback functors and their adjoints. Since the decomposition-space machinery is based on homotopy pullbacks and homotopy cardinality, we may as well consider groupoid-valued species, which we do from now on.

For the sake of taking cardinality, it is furthermore natural to require the groupoid values to be locally finite. This means that every object has finite automorphism group. This is usually the case of combinatorial objects. In particular, every set (finite or not) is locally finite. So a classical species is always locally finite.
5.4. Restriction species. A restriction species is a groupoid-valued presheaf on \( I \),

\[
R : \text{Grpd}^{\text{op}} \rightarrow I
\]

A morphism of restriction species is a natural transformation. We actually allow pseudo-functors and pseudo-natural transformations, but make some remarks on the strict case in §12. This defines the category \( RSp \) of restriction species.

A restriction species corresponds, by the Grothendieck construction, to a right fibration (i.e. a cartesian fibration with groupoid fibres)

\[
\mathbb{R} \rightarrow I.
\]

Here \( \mathbb{R} \) is the category of elements of \( R \), whose objects are \( R \)-structures and whose arrows are structure-preserving injections. More precisely, an object is a pair \((A, X)\) where \( A \) is a finite set and \( X \in R[A] \), and a morphism \((A', X') \rightarrow (A, X)\) is an injection \( A' \rightarrow A \) in \( I \) and an arrow \( X' \sim X|A' \) in the groupoid \( R[A'] \). The category of restriction species is canonically equivalent to the categories of groupoid-valued presheaves on \( I \), and of right fibrations over \( I \):

\[
RSp \simeq \text{Grpd}^{\text{op}} \simeq \text{RFib}_{/I}.
\]

It is sometimes more informative to describe a restriction species by describing the right fibration \( \mathbb{R} \rightarrow I \) rather than describing the functor \( R : \text{Grpd}^{\text{op}} \rightarrow I \), because the description of the category \( \mathbb{R} \) already has the specifics about the restrictions, encoded in the arrows of the category. We shall see this in the examples.

5.5. Examples of restriction species. (See [46] for these and more examples.)

(1) **Graphs.** The species of finite graphs is a restriction species, cf. Example 2.1. It is fruitful to look at it also as a right fibration \( G \rightarrow I \): the category \( G \) is then the category whose objects are finite graphs, and whose morphisms are full graph inclusions. Full means that if two vertices \( x \) and \( y \) are in the subgraph then all edges between \( x \) and \( y \) must also be included. (Allowing non-full inclusions, such as \( \bullet \bullet \rightarrow \bullet \bullet \), would prevent \( G \rightarrow I \) from being a right fibration.)

(2) **Matroids.** (See Oxley [44] for definitions.) The species of matroids is a restriction species [46]. Many important classes of matroids are stable under restriction and are therefore also restriction species. For example, transversal matroids, representable matroids, regular matroids, graphic matroids, bond matroids, planar matroids, and so on.

(3) **Posets.** The species of posets is a restriction species. The corresponding right fibration is \( F \rightarrow P \), where \( P \) is the category of finite posets and full poset inclusions \( F \leftrightarrow P \). ‘Full’ means that for two elements \( x, y \) in \( F \) we have \( x \leq_F y \) if and only if \( x \leq_P y \).

In §7 we shall introduce directed restriction species, based on a different category of posets, namely the category \( C \) of finite posets and convex maps. The forgetful functor \( C \rightarrow I \) is not a right fibration: there is no convex lift of the set inclusion \( \{0, 2\} \rightarrow \{0, 1, 2\} \) to the linear order \( \{0 \leq 1 \leq 2\} \).

(4) **Categories.** The species of finite categories assigns to a finite set the groupoid of all finite-category structures on that set of objects. In this case the right fibration is \( F \rightarrow I \), where \( F \) is the category of finite categories and full subcategory inclusions (or more precisely, injective-on-objects fully faithful functors). The underlying-set functor \( F \rightarrow I \)
is a right fibration because clearly any subset of the object set of a category determines uniquely a full subcategory.

Note: in the examples of graphs and categories we stress the word ‘finite’: if we allowed an infinite number of edges/arrows between two elements, an infinite automorphism group would result, violating the local finiteness assumption made in 5.3.

5.6. Slices of examples. Recall that for any object \( x \) in a category \( \mathcal{C} \), the domain projection \( \mathcal{C}/x \to \mathcal{C} \) is a right fibration. In particular, if \( R \to I \) is a restriction species, for any \( R \)-structure \( X \), the slice category \( R/X \) is again a restriction species. It is the restriction species of \( R \)-substructures of \( X \). See Bergner et al. [5] for examples of slices of the decomposition space of graphs. The fact that slicing a restriction species produces again restriction species reflects the local nature of coalgebras: every element in a coalgebra generates a coalgebra.

5.7. Restriction species as decomposition spaces over \( I \). From a restriction species \( R \), or a right fibration \( R \to I \), we shall construct a simplicial groupoid \( R \) of layered \( R \)-structures, together with a CULF functor \( R \to I \).

As in §4, the subtlety is that the obvious functoriality is in \( \Delta \simeq \Delta_{\text{gen}}^{\text{op}} \), not in all of \( \Delta^{\text{op}} \). Consider first the functor \( I/\sim : \Delta \to \text{Grpd} \) and form the pullbacks

\[
R_k = \prod_{/k} \times_{/\bot} \prod_{/k-1}
\]

along the functor \( \prod_{/\sim} \to \prod_{/\sim} = \prod_{/\bot} \). Thus \( R_k \) is the groupoid of \( R \)-structures with a \( k \)-layering of the underlying sets. This defines a diagram of shape \( \Delta = \Delta_{\text{gen}}^{\text{op}} \).

\[
R_{\text{gen}} : \Delta \to \text{Grpd}.
\]

The pullback construction also shows that forgetting the \( R \)-structure and retaining only the layering of the underlying set provides a cartesian natural transformation (of \( \Delta_{\text{gen}}^{\text{op}} \)-diagrams)

\[
R_{\text{gen}} \to I_{\text{gen}}.
\]

So far the construction works for any species, not necessarily restriction species. To define also the free maps (i.e. outer face maps) we need the restriction structure on \( R \), which allows us to lift the outer face maps we constructed for \( I \). Recall that the outer face map \( d_\bot : \prod_{/k} \to \prod_{/k-1} \) is defined by sending \( A \to k \) to the pullback

\[
\begin{array}{ccc}
A' & \xrightarrow{c} & A \\
\downarrow \downarrow d_\bot & & \downarrow d_\bot \downarrow k_1 \\
k-1 & \xrightarrow{d_\bot} & k.
\end{array}
\]

Since \( A' \hookrightarrow A \) is an injection, we can use functoriality of \( R \) (the fact that \( R \) is a restriction species) to get also the face map for \( R_k \): for example,

\[
d_\bot : R_k \to R_{k-1}
\]

is defined as

\[
(A \to k, X) \mapsto (d_\bot k A \to k-1, X[d_\bot k A]).
\]

We see that the point is to be covariantly functorial in all maps in \( \Delta \) and to be contravariantly functorial in convex maps. To establish the simplicial identities is to exhibit a certain compatibility between these two functorialities. These conditions are
precisely condensed in the notion of sesquicartesian fibration which we introduce in §9 below.

**Theorem 5.8.** Given a restriction species \( R \), the above construction defines a simplicial groupoid \( R \), which is a decomposition space. Furthermore, a morphism of restriction species \( R' \to R \) induces a CULF functor \( R' \to R \). These assignments define a functor from the category of restriction spaces to that of decomposition spaces and CULF functors.

**Proof.** The simplicial identities in \( R \) can be checked by hand, arguing along the lines of the proof of Proposition 4.3. (Later we will give a more elegant proof using the machinery introduced in Sections 8–10 and there will be no need for ad hoc arguments). Since by construction the simplicial groupoid \( R \) is CULF over a decomposition space \( I \), it is itself a decomposition space (by Lemma 1.13).

A morphism \( f : R' \to R \) amounts to a morphism of right fibrations

\[
\begin{array}{ccc}
R' & \xrightarrow{f} & R \\
\downarrow & & \downarrow \\
I & \xrightarrow{I} & I
\end{array}
\]

inducing simplicial maps

\[
\begin{array}{ccc}
R' & \xrightarrow{f} & R \\
\downarrow & & \downarrow \\
I & \xrightarrow{I} & I
\end{array}
\]

Indeed, at level \( n \), the morphism of groupoids \( R'/\underline{n} \to R/\underline{n} \) is induced from \( R' \to R \), since the layering only affects the underlying set which does not change. Finally, \( f \) is CULF since the projection maps to \( I \) are. \( \square \)

**5.9. Decalage.** The decomposition space \( R \) constructed from the restriction species \( R \) can be seen as an ‘un-decking’: we have

\[
\text{Dec}_\perp R \simeq NR, \quad \text{Dec}_\top R \simeq NR^{\text{op}}.
\]

We postpone the proof until 11.3.

**Lemma 5.10.** The groupoid \( R_1 = R^{\text{iso}} \) is locally finite.

**Proof.** For each \( n \in \underline{\text{iso}} \) we have a fibre sequence (homotopy pullback)

\[
\begin{array}{ccc}
R[n] & \xrightarrow{\cdot n} & R^{\text{iso}} \\
\downarrow & & \downarrow \\
1 & \xrightarrow{(n)} & \underline{\text{iso}}.
\end{array}
\]

Since \( \underline{\text{iso}} \) is locally finite, and since \( R[n] \) is locally finite by our standing assumption, also \( R^{\text{iso}} \) is locally finite. \( \square \)

**Proposition 5.11.** The decomposition space \( R \) is complete, locally finite, locally discrete, and locally of finite length.

**Proof.** \( R_1 \) is locally finite by Lemma 5.10. The remaining finiteness properties and the discreteness property follow from Lemmas 1.12 and 4.4 since \( R \) is CULF over \( I \). \( \square \)
5.12. Coalgebras. (See [18] and [19].) To any decomposition space \( X \), there is associated a coalgebra at the objective level, namely a comultiplication functor \( \Delta : \text{Grpd} / X_i \rightarrow \text{Grpd} / X_i \otimes \text{Grpd} / X_i \) and a counit functor \( \varepsilon : \text{Grpd} / X_i \rightarrow \text{Grpd} \). Similarly a CULF functor \( X' \rightarrow X \) induces a coalgebra homomorphism, i.e. a linear functor \( \text{Grpd} / X_i \rightarrow \text{Grpd} / X_i \) compatible with the coalgebra structures. If the decomposition spaces are locally finite, one can take homotopy cardinality to obtain coalgebras over \( \mathbb{Q} \) and coalgebra homomorphisms in the classical sense. It is outside the scope of the present paper to go into details, and we only sketch the proof of the following proposition which is the motivation for channelling the Schmitt construction through decomposition spaces.

**Proposition 5.13.** For \( R \) a restriction species, the Schmitt coalgebra of \( R \) is the homotopy cardinality of the incidence coalgebra of the associated decomposition space \( R \). For a morphism of restriction species \( R' \rightarrow R \), Schmitt’s coalgebra homomorphism is the cardinality of the associated CULF functor \( R' \rightarrow R \).

**Proof.** (Sketch). At the objective level, the comultiplication is given by pullback along \( d_1 : R_2 \rightarrow R_1 \), followed by composing with \((d_2, d_0)\). For a given \( R \)-structure \( X \), viewed as a morphism \( \Gamma X^+ : 1 \rightarrow R_1 \), the pullback is the \( d_1 \)-fibre over \( X \), that is the groupoid \((R_2)_X\) of all \( R \)-structures with a 2-layering such that the union of the two layers is \( X \). This is a groupoid over \( R_1 \times R_1 \) by composing with \((d_2, d_0)\), which amounts to returning the restriction of \( X \) to each of the two layers. To recover the formula in 5.2, it remains to take homotopy cardinality of this groupoid, relative to \( R_1 \times R_1 \). This is meaningful since \( R \) is locally finite by Proposition 5.11. There are general formulae for this in [21], but in the present case it is straightforward: since \( R \) is locally discrete by Proposition 5.11, the groupoid \((R_2)_X\) is discrete, and hence homotopy cardinality amounts to counting isomorphism classes, yielding Schmitt’s formula in 5.2. The statement about morphisms does not present further difficulties. \( \square \)

5.14. Monoidal restriction species. We introduce the notion of monoidal restriction species. The idea is simply that many restriction species are ‘closed under disjoint union’, in a way compatible with restrictions. This compatibility with restrictions ensures that the resulting algebra structure is compatible with the coalgebra structure to result altogether in a bialgebra. This bialgebra is always graded (by the number of elements in the underlying set), and most often connected (this happens when there is only one possible structure on the empty set), and hence a Hopf algebra. Schmitt [46] arrives at Hopf algebras through a notion of coherent exponential restriction species. Our notion is a bit more general, and conceptually simpler.

The category \( I \) has a symmetric monoidal structure given by disjoint union, as already exploited to make \( I \) a monoidal decomposition space (Lemma 4.6). We define a monoidal restriction species to be a right fibration \( R \rightarrow I \) for which the total space \( R \) has a monoidal structure \( \sqcup \) and the projection to \( I \) is strong monoidal.

If \( X_1 \) is an \( R \)-structure with underlying set \( S_1 \), and \( X_2 \) is an \( R \)-structure with underlying set \( S_2 \), and if \( K_1 \subset S_1 \) and \( K_2 \subset S_2 \) are subsets (or injective maps), then there is a canonical isomorphism

\[
(X_1 \sqcup X_2) | (K_1 + K_2) \simeq (X_1 | K_1) \sqcup (X_2 | K_2).
\]

This follows from unique comparison between cartesian lifts and the fact that the projection is strong monoidal. This isomorphism expresses the desired compatibility between the monoidal structure and restrictions.
A morphism of monoidal restriction species is a strong monoidal functor which is also a morphism of right fibrations.

**Proposition 5.15.** The functor of Theorem 5.8 extends to a functor from the category of monoidal restriction species and their morphisms to that of monoidal decomposition spaces and CULF monoidal functors.

**Proof.** If \( R \) is a monoidal restriction species, then the associated decomposition space \( R \) is monoidal: in degree \( n \), this is simply given by the monoidal structure \( \sqcup : R/\mu \times R/\mu \to R/\mu \). This is well defined because the projection functor is strong monoidal. Furthermore, this monoidal structure is CULF thanks to the above compatibility: to give a pair of \( R \)-structures with a layering of each is the same as giving a pair of \( R \)-structures with a layering of its disjoint union. This is to say that this square is a pullback:

\[
\begin{array}{ccc}
R_{/\mu} \times R_{/\mu} & \xrightarrow{g \times g} & R_{/\mu} \\
\downarrow & & \downarrow \\
R_{/\mu} & \xrightarrow{g} & R_{/\mu}
\end{array}
\]

where \( g \) is the unique generic map (and \( k \) could be 0). \( \square \)

It follows that every monoidal restriction species defines a bialgebra (a Hopf algebra in the connected case), and a morphism of monoidal restriction species defines a bialgebra homomorphism.

**5.16. Remark.** There is a kind of converse to the construction \( R \leadsto R \). Namely, starting from a decomposition space \( R \) CULF over \( I \) (and with \( R \) locally finite), we can take lower dec of both and obtain a Segal space which by Lemma 1.18 is a right fibration over \( \text{Dec} \bot I = N I \) (Proposition 4.5). In fact \( \text{Dec} \bot R \) is a Rezk-complete Segal space. Indeed, since \( R \) is CULF over \( I \), it is complete, locally finite, locally discrete and of locally finite length, by Lemma 1.12. But also the dec map \( \text{Dec} \bot R \to R \) is CULF, so \( \text{Dec} \bot R \) also has all these properties. Since it is furthermore a Segal space, it follows from a general result of [20] that it is Rezk complete. Hence \( \text{Dec} \bot R \) is essentially the fat nerve of a category \( R \) (with a right fibration over \( I \)).

### 6. The decomposition space \( C \) of layered finite posets

We define and study the monoidal decomposition space \( C \) of finite posets and their ‘admissible cuts’, which will play the same role for directed restriction species as \( I \) does for plain restriction species. An important difference is that while the simplicial groupoid \( I \) is a Segal space, \( C \) is only a decomposition space, not a Segal space.

**6.1. Convex maps of posets.** A subposet \( K \) of a poset \( P \) is convex if it is full and if \( a \leq x \leq b \) in \( P \) and \( a, b \in K \) imply \( x \in K \). A map of posets \( f : K \to P \) is convex if for all \( a, b \in K \) and \( fa \leq x \leq fb \) in \( P \) there is a unique \( k \in K \) with \( a \leq k \leq b \) and \( fk = x \). In other words, \( f \) is injective and \( f(K) \subset P \) is a convex subposet. We denote by \( C \) the category of finite posets and convex maps.

**Lemma 6.2.** In the category of posets, convex maps are stable under pullback.

**Lemma 6.3.** For a subposet \( K \subset P \) the following are equivalent.
(1) $K$ is convex
(2) $K$ is the middle fibre of some monotone map $P \to \mathbb{3}$
(3) $K \subset P$ is a fully faithful ULF functor of categories.

**6.4. Layered posets.** An $n$-layering of a finite poset $P$ is a monotone map $\ell : P \to \mathbb{3}$. We refer to the fibres $P_i = \ell^{-1}(i)$, $i \in \mathbb{3}$, as layers. Layers are convex subposets, by the previous lemma, and may be empty.

For sets, considered as discrete posets, the notion of set layering from 4.1 agrees with the notion of poset layering. Poset layering is more subtle, however, as it contains more information than just the list of layers.

**6.5. The groupoid of $n$-layered finite posets.** Consider the groupoid $C_{\text{iso}}/\mathbb{3}$ of $n$-layerings of finite posets. That is, the objects of $C_{\text{iso}}/\mathbb{3}$ are monotone maps $\ell : P \to \mathbb{3}$, and the morphisms are commutative triangles

$$
\begin{tikzcd}
P \ar{rr}{\sim} & & P' \ar{dl} \ar{dr} \\
\mathbb{3} & & &
\end{tikzcd}
$$

where $P \sim P'$ is a monotone bijection (a poset isomorphism).

**6.6. The simplicial groupoid of layered finite posets.** We can define face and degeneracy maps between the groupoids of layered finite posets to assemble them into a simplicial groupoid $C$, in the same way as for layered finite sets in 4.2:

The degeneracy and the inner face maps are defined using the correspondence $\Delta^{\text{op}}_{\text{gen}} \simeq \Delta$: if $g : [n] \to [m]$ is a generic map in $\Delta$ then $g^* : C_{\text{iso}}/\mathbb{m} \to C_{\text{iso}}/\mathbb{n}$ is given by postcomposition with the corresponding map $g : m \to n$ in $\Delta$,

$$
P \to m \quad \mapsto \quad P \to m \to n.
$$

The definition for free maps (composites of outer face maps) is by pullback: for example, $d_\top : C_{\text{iso}}/\mathbb{n} \to C_{\text{iso}}/\mathbb{n-1}$ is given by taking $P \to \mathbb{n}$ to $P \to \mathbb{n-1}$ in the pullback square

$$
\begin{tikzcd}
P \ar{rr}{d_\top} & & P' \\
\mathbb{n-1} \ar{rr} \ar{ur} & & \mathbb{n} \ar{ur} \ar{ul}
\end{tikzcd}
$$

Since $d_\top : n-1 \to n$ is a convex map of posets, so is $P \to P'$. To be explicit, we can take this convex map to be an actual subset inclusion.

**Proposition 6.7.** The groupoids $C_{\text{iso}}/\mathbb{3}$ and the maps between them, defined above, form a simplicial groupoid $C$.

**Proof.** The check may be performed in precisely the same way as done for $I$ in Proposition 4.3: one checks the constructions above are covariantly functorial in all maps in $\Delta$ (giving the generic part), contravariantly functorial in the convex maps of $\Delta$ (giving the free part), and that these two functorialities are compatible. We will formalise this later in the notions of $\mathbb{V}$-spaces and sesquicartesian fibrations (Sections 8–9).

$\square$
6.8. Lower-set inclusions. Let $P$ be a poset. A full subposet $L \subseteq P$ is a lower set (also called an ideal) if $x \leq b$ in $P$ implies $x \in L$. A map of posets $L \to P$ is a lower-set inclusion if it is injective, full, and its image is a lower set in $P$. Clearly lower-set inclusions are convex. Let $\mathbb{C}^{\text{lower}}$ denote the category of finite posets and lower-set inclusions. Clearly lower-set inclusions are stable under pullback.

**Lemma 6.9.** In the category of posets, lower-set inclusions are stable under pullback.

**Proposition 6.10.** The map $d_\top : 1 \to 2$ classifies lower-set inclusions. That is, if $P$ is a poset, pullback along $d_\top$ defines a bijection

\[
\{\text{monotone maps } P \to 2\} \cong \{\text{isoclasses of lower-set inclusions } L \subseteq P\}.
\]

**Proposition 6.11.** There are natural (levelwise) equivalences

\[
\text{Dec}_\bot(\mathbb{C}) \simeq \mathbb{N}\mathbb{C}^{\text{lower}} \quad \text{Dec}_\top \mathbb{C} \simeq \mathbb{N}(\mathbb{C}^{\text{upper}})^{\text{op}}
\]

**Proof.** There is a natural equivalence

\[
\mathbb{C}^{\text{iso}}_{/0} \cong \text{Map}([n-1], \mathbb{C}^{\text{lower}})
\]

Given an $n$-layering of a poset $P$ (i.e. a monotone map $P \to n$), let $P_n = P$ and define inductively $P_k \to k$ as the pullback of $P_{k+1} \to k+1$ along the lower-set inclusions $d_\top : k \to k+1$. By Lemma 6.9, we obtain lower-set inclusions $P_k \to P_{k+1}$. Then the equivalence assigns to $P \to n$ the sequence of lower-set inclusions

\[
(P_1 \hookrightarrow P_2 \hookrightarrow \cdots \hookrightarrow P_{n-1} \hookrightarrow P) \in \text{Map}([n-1], \mathbb{C}^{\text{lower}}).
\]

This assignment is fully faithful since each automorphism of such sequences corresponds to a unique automorphism of $P$ over $n$. Finally, given such a sequence of lower-set inclusions, we recover a monotone map $P \to n$, sending $x$ to the least $k$ for which $x \in P_k$. It is straightforward to check that the face maps match up as required, so as to assemble these equivalences into a levelwise equivalence of simplicial groupoids.

The result for the upper dec is analogous. The ‘op’ appears in that case because the smallest subset in the chain is the last one, not the first as above. □

**Proposition 6.12.** $\mathbb{C}$ is a decomposition space (but not a Segal space).

**Proof.** We apply the decalage criterion [18, Theorem 4.11 (4)]. We already proved that the two Decs are Segal spaces. It remains to check that the following two squares are pullbacks:

\[
\begin{array}{ccc}
\mathbb{C}^{\text{iso}}_{/0} & \xrightarrow{s_0} & \mathbb{C}^{\text{iso}}_{/1} \\
\downarrow d_1 & & \downarrow d_1 \\
\mathbb{C}^{\text{iso}}_{/1} & \xrightarrow{s_0} & \mathbb{C}^{\text{iso}}_{/2}
\end{array}
\quad
\begin{array}{ccc}
\mathbb{C}^{\text{iso}}_{/0} & \xrightarrow{s_0} & \mathbb{C}^{\text{iso}}_{/1} \\
\downarrow d_\top & & \downarrow d_\top \\
\mathbb{C}^{\text{iso}}_{/1} & \xrightarrow{s_0} & \mathbb{C}^{\text{iso}}_{/2}
\end{array}
\]

But it is clear they are strict pullbacks: this amounts to saying that if a 2-layered poset has one layer empty, it is determined by the other layer. Since the free face maps are iso-fibrations, the squares are also (homotopy) pullbacks. Clearly $\mathbb{C}$ is not a Segal space as $\mathbb{C}^{\text{iso}}_{/m+n} \neq \mathbb{C}^{\text{iso}}_{/m} \times \mathbb{C}^{\text{iso}}_{/n}$.

**Lemma 6.13.** The decomposition space $\mathbb{C}$ is complete, locally finite and locally discrete, and of locally finite length.
Proof. Since $C^\text{iso}_{/0}$ is contractible, consisting of the empty poset with no non-trivial automorphisms, we know $s_0 : C^\text{iso}_{/0} \to C^\text{iso}_{/1}$ is mono, so $C$ is complete. Now observe that $C^\text{iso}_{/1}$ is locally finite as each finite poset has only finitely many automorphisms. We have just seen that $s_0 : C^\text{iso}_{/0} \to C^\text{iso}_{/1}$ is finite and discrete, and for $d_1 : C^\text{iso}_{/2} \to C^\text{iso}_{/1}$ the fibre over each finite poset $P$ is the finite discrete groupoid $\{P \to \underline{2}\}$ of all monotone maps. Lastly, $C$ is of locally finite length: the degenerate simplices are precisely the layerings with an empty layer. The fibre of $g : C^\text{iso}_{/n} \to C^\text{iso}_{/1}$ over $P$ has no non-degenerate simplices if $n$ is greater than the number of elements of the finite poset $P$. □

Lemma 6.14. $C$ is a monoidal decomposition space under disjoint union.

Proof. For fixed $k$, we have $C^\text{iso}_{/k} \times C^\text{iso}_{/k} \to C^\text{iso}_{/k}$ given by disjoint union. It is clear that these maps assemble into a simplicial map $C \times C \to C$. CULFness of this simplicial map follows because to give a pair of posets, each with a $k$-layering, is the same as giving a pair of posets, together with a $k$-layering of their disjoint union. In other words, disjoint union of layered posets are computed layer-wise. Diagrammatically, this square is a pullback:

\[
\begin{array}{ccc}
C^\text{iso}_{/k} \times C^\text{iso}_{/k} & \xrightarrow{g \times g} & C^\text{iso}_{/k} \times C^\text{iso}_{/k} \\
\downarrow & & \downarrow \\
C^\text{iso}_{/k} & \xrightarrow{g} & C^\text{iso}_{/k},
\end{array}
\]

where $g$ is the unique generic map (and $k$ could be 0). □

7. Directed restriction species

We introduce the new notion of directed restriction species, with associated incidence coalgebras generalising well-known constructions with rooted forests [9, 7], acyclic directed graphs [40, 42], posets and distributive lattices [47, 11], and double posets [39].

7.1. Directed restriction species. A directed restriction species is by definition a (pseudo)-functor

$R : C^{\text{op}} \to \text{Grpd},$

or equivalently, by the Grothendieck construction, a right fibration $R \to C$. We shall always assume that all values are locally finite groupoids.

The idea is that the value on a poset $S$ is the groupoid of all possible $R$-structures that have $S$ as underlying poset.

A morphism of directed restriction species is just a (pseudo)-natural transformation. This defines the category of directed restriction species $\mathbf{DRSp}$, equivalent to the categories of groupoid-valued presheaves on $C$, and of right fibrations over $C$:

$\mathbf{DRSp} \simeq \text{Grpd}^{C^{\text{op}}} \simeq \mathbf{RFib}_{/C}.$

7.2. Coalgebras from directed restriction species. Let $R$ be any directed restriction species. An admissible cut of an object $X \in R[P]$ is by definition a 2-layering of the underlying poset. In other words, the cut separates $P$ into a lower-set and an upper-set. This agrees with the notion of admissible cut in Butcher–Connes–Kreimer (as in 2.2 above), and in related examples.
A coalgebra is defined by the rule
\begin{equation}
\Delta(X) = \sum_{c \in \text{cut}(P)} X|D_c \otimes X|U_c, \quad X \in R[P],
\end{equation}
where the sum is over all admissible cuts $c = (D_c, U_c)$.

Note that the incidence coalgebra of a directed restriction species is generally non-cocommutative. It is cocommutative if and only if it is actually supported on discrete posets, so that in reality it is an ordinary restriction species, as we explain next.

**7.3. Sets as discrete posets.** Any finite set can be regarded as a discrete poset, and any injective map of sets is then a convex map. Hence there is a natural functor $\mathbb{I} \to \mathbb{C}$. This functor is easily seen to be a right fibration. Hence every restriction species is also a directed restriction species. This is to say that there is a natural functor
\[ RSp \to DRSp \]
from restriction species to directed restriction species, clearly fully faithful.

**7.4. Directed restriction species as decomposition spaces.** If $R : \mathbb{C} \to \text{Grpd}$ is a directed restriction species, let $R_k$ be the groupoid of $R$-structures on posets $P$ with a $k$-layering. (In other words, $R_2$ is the groupoid of $R$-structures with an admissible cut, and $R_k$ is the groupoid of $R$-structures with $k-1$ compatible admissible cuts.)

**Theorem 7.5.** The $R_k$ form a simplicial groupoid $R$, which is a decomposition space. Morphisms of directed restriction species induce CULF functors between decomposition spaces. The construction defines a functor from the category of directed restriction species and their morphisms to that of decomposition spaces and CULF maps.

**Proof.** This can be proved in the same way as Theorem 5.8 for ordinary restriction species, or a more elegant proof will be given in Theorem 10.9, after setting up fancier machinery.

Since we assume directed restriction species $R : \mathbb{C}^{\text{op}} \to \text{Grpd}$ take locally finite groupoids as values, it follows by Lemma 5.10 that $R_1$ is a locally finite groupoid. Now by Lemmas 1.12 and 6.13 we have the necessary finiteness conditions to obtain classical incidence coalgebras by taking homotopy cardinality:

**Lemma 7.6.** The decomposition space $R$ is complete, locally finite, locally discrete, and of locally finite length.

**Proof.** The main point here is that since $R$ is locally discrete by Lemma 7.6, the homotopy sum resulting from the decomposition space is just an ordinary sum, as in (2).

**7.8. Monoidal directed restriction species.** The category $\mathbb{C}$ is symmetric monoidal under disjoint union. We define a monoidal directed restriction species to be a directed restriction species $R : \mathbb{C} \to \text{Grpd}$ for which the total space $R$ has a monoidal structure and the right fibration is also a strong monoidal functor. This extends the notion of ordinary monoidal restriction species introduced in 5.14, as $\mathbb{I} \to \mathbb{C}$ is easily seen to be a monoidal directed restriction species. Since strong monoidal right fibrations compose, every monoidal restriction species is also a monoidal directed restriction species. We have:
Proposition 7.9. The functor of Theorem 7.5 extends to a functor from monoidal directed restriction species and their morphisms, to monoidal decomposition spaces and CULF monoidal functors.

If a restriction species is monoidal, the associated incidence coalgebra becomes a bialgebra. The projection \( \mathcal{R} \to \mathcal{C} \) is monoidal, and so the incidence bialgebra of \( \mathcal{R} \) comes with a bialgebra homomorphism to the incidence bialgebra of \( \mathcal{C} \).

Except when explicitly mentioned otherwise, all the following examples are in fact monoidal directed restriction species and hence induce bialgebras.

7.10. First examples. Just as for ordinary restriction species, it is sometimes useful to describe a directed restriction species by describing the associated right fibration \( \mathcal{R} \to \mathcal{C} \), where the restriction structure is encoded in the arrows.

(1) Posets. The category \( \mathcal{C} \) of finite posets and convex maps is the terminal directed restriction species. The resulting coalgebra comultiplies a poset by splitting it along ‘admissible cuts’ into lower-sets and upper-sets (cf. Example 2.5).

(2) One-way categories and Möbius categories. For a finite category \( \mathcal{C} \) to have an underlying poset, it is required that for any two objects \( x, y \in \mathcal{C} \) at least one of the hom sets \( \text{Hom}_\mathcal{C}(x,y) \) and \( \text{Hom}_\mathcal{C}(y,x) \) is empty. (This implies that \( \mathcal{C} \) is skeletal.) The underlying poset \( \mathcal{C} \) is then given by declaring \( x \leq y \) to mean that \( \text{Hom}_\mathcal{C}(x,y) \) is nonempty. Such categories form a directed restriction species \( \mathcal{U} \): for a convex map of posets \( K \subset \mathcal{C} \), the restriction of \( \mathcal{C} \) to \( K \) is given as the full subcategory spanned by the objects in \( K \). For the corresponding right fibration \( \mathcal{U} \to \mathcal{C} \), the arrows in \( \mathcal{U} \) are the fully faithful CULF functors (automatically injective on objects since the categories are skeletal).

With the further condition imposed that the only endomorphisms are the identities, we arrive at the notion of finite delta, in the terminology of Mitchell [43], now more commonly called finite one-way categories. This is equivalent (cf. [36]) to the notion of finite Möbius category of Leroux [37]. Möbius categories play an important role as a generalisation of locally finite posets, and in particular admit Möbius inversion. It is clear that we also have a directed restriction subspecies of finite Möbius categories.

7.11. Convex-closed classes of posets. Ordinary (restriction) species are mostly about structure, not property, since the only property that can be assigned to a finite set is its cardinality. For directed restriction species, property plays a more important role, since posets can have many properties. Any class of posets closed under taking convex subposets and closed under isomorphisms defines a (fully faithful) right fibration, and hence a directed restriction species. Such a class may or may not be monoidal under disjoint union. (Note that this notion, which could reasonably be called convex-closed classes of posets, is different from the classical closure property in incidence coalgebras, where a class of intervals is required to be closed under subintervals [47].)

For example, forests (cf. 7.12 below), linear orders, and discrete posets (cf. 7.3) are convex-closed classes of posets, and form (monoidal) directed restriction species. Considering linear orders leads to \( \mathbb{L} \)-species, in the sense of [4].

Just as in the case of ordinary restriction species, the minimal such ‘ideals’ are defined by picking any single poset \( P \), and considering the ‘principal ideal generated by \( P \)’, more precisely the slice category \( \mathcal{C}/P \). Note that \( \mathcal{C}/P \) cannot be monoidal in the sense of 7.8. Since the morphisms in \( \mathcal{C} \) are just the convex maps, \( \mathcal{C}/P \) is equivalent to the full
subcategory of $\mathbb{C}$ consisting of $P$ and all its convex subposets. This reflects the standard fact that any element in a coalgebra spans a subcoalgebra.

### 7.12. Examples: various flavours of trees (actually forests).

1. **Combinatorial trees.** Consider the directed restriction species of rooted forests: a rooted forest has an underlying poset, whose convex subposets inherit each a rooted-forest structure. Regarded as a right fibration $\mathcal{H} \to \mathbb{C}$, the category $\mathcal{H}$ has objects rooted forests and morphisms subforest inclusions (not required to preserve the root). The resulting bialgebra is the Butcher–Connes–Kreimer Hopf algebra [9, 7] already treated in 2.2. As explained, this is not a Segal groupoid: a tree cannot be reconstructed from its layers. An important non-commutative variation comes from planar forests [12].

2. **Operadic trees (with nodes).** Consider the combinatorial structure of rooted forests allowing open-ended edges (leaves and root) as in [29, 15], but disallowing isolated edges, i.e. edges not adjacent to any node. As before, each such forest has an underlying poset of nodes, and for each convex subset of the node set, there is induced a forest again. These are full forest inclusions, meaning that for each node, all incoming edges as well as the outgoing edge must be included (see [29] for details). It is an important feature that the local structure at the nodes is always preserved under taking such subforests. This means that one can consider trees whose nodes are decorated with ‘operation symbols’ of matching arity (more precisely $P$-trees for $P$ a polynomial endofunctor [29, 30]) and that subtrees inherit such decorations. This is not possible for combinatorial trees, where the cuts destroy the local structure of nodes (such as for example being a binary node). Operadic forests (with nodes) form a directed restriction species. Note that in contrast to what happens for combinatorial trees, cuts do not delete inner edges, they cut them in two (as a consequence of the fullness of subforest inclusions). But if an isolated edge results from a cut, it is deleted, as illustrate in this figure:

![Operadic tree diagram]

3. **Non-example: operadic trees, including nodeless ones.** If one allows the nodeless tree, the resulting notion of forest does not form a directed restriction species. Indeed, with all the nodeless forests being different structures on the empty set of nodes, and since there exist non-invertible maps between such node-less forests, the functor to $\mathbb{C}$ cannot be a right fibration (it has non-invertible arrows in its fibres). (It is only over the empty set that this problem arises: for trees with nodes, every non-invertible map can be detected on nodes.)

This variation, which is subsumed in the class of decomposition spaces coming from operads [21, 35], has some different features which have been exploited to good effect in various contexts [15, 31, 32, 34]. In particular it is important that the cut locus expresses a type match between the roots of the crown forest and the leaves of the bottom tree, and that there is a grading [19] given by number of leaves minus number of roots. The incidence bialgebra is not connected: the zeroth graded piece is spanned by the node-less forests. These are all group-like, and the connected quotient (dividing out by this coideal) is precisely the incidence Hopf algebra of the directed restriction species of forests without isolated edges. One can then further take core [31, 34], which means shave off leaves and root (and forget the $P$-decoration). This is a monoidal CULF functor, and altogether there is a monoidal CULF functor from the decomposition space of $P$-trees.
to the decomposition space of combinatorial trees. This is an interesting example of a relative 2-Segal space in the sense of Young [54] and Walde [51].

7.13. Examples: various flavours of acyclic directed graphs. (1) Acyclic directed graphs. These have underlying posets, where \( x \leq y \) if there is a directed path from \( x \) to \( y \). Any convex subposet of the poset of vertices induces a subgraph \( S \), which is convex in the usual sense of directed graphs, meaning that any directed path from \( x \in S \) to \( y \in S \) in the whole graph must be entirely contained in \( S \). There is now induced a natural notion of admissible cut, similar to Butcher–Connes–Kreimer, and a Hopf algebra results (see Manchon [40, §5]).

(2) Acyclic directed open graphs. Now we allow open-ended edges, thought of as input edges and output edges (see [33]), but we do not allow graphs containing isolated edges. This situation and the resulting bialgebra have been studied by Manchon [40, §4]. Interesting decorated versions have been studied by Manin [41, 42] in the theory of computation. His graphs are decorated by operations on partial recursive functions and switches.

(3) Non-example: Acyclic directed open graphs, allowing isolated edges. Again, if one allows isolated edges, it is not a restriction species. In contrast it is a Segal groupoid, and the comultiplication resulting from it enjoys a nice grading (by number of input edges minus number of output edges).

7.14. Examples: double posets and related structures. A double poset [39] is a poset \((P, \leq)\) with an additional poset structure \(\preceq\), not required to have any compatibility with \(\leq\). Let \(\mathbb{D}\) denote the category of finite double posets \((P, \leq, \preceq)\) and inclusions that are convex for \(\leq\). For every \(\leq\)-convex subset \((K, \leq) \subset (P, \leq)\), there is induced a \(\preceq\) structure on \(K\), simply by the fact that posets form an ordinary restriction species (cf. 5.5 (3)). It follows that \(\mathbb{D} \to \mathbb{C}\) is a right fibration, and hence a directed restriction species. The associated incidence coalgebra was first studied by Malvenuto and Reutenauer [39]; see [13] and [14] for more recent developments.

The case where the second poset structure is a linear order is called special double poset or just special poset, and is equivalent to Stanley’s notion of labelled poset [48].

Double posets and special posets are just two instances of the following general construction: for any ordinary restriction species \(R\), consider the directed restriction species consisting of having simultaneously a poset structure and an \(R\)-structure, without compatibility conditions. Let the morphisms be inclusions that are convex for the poset structure.

7.15. Decalage. While for ordinary restriction species \(R \to \mathbb{I}\) we have \(\text{Dec}_\perp R \simeq \mathbb{N}R\) and \(\text{Dec}_\top R \simeq \mathbb{N}R^{\text{op}}\), the situation is slightly more complicated for directed restriction species. The result is (as we shall see in Proposition 11.1):

\[
\text{Dec}_\perp R \simeq \mathbb{N}R^{\text{lower}} \quad \text{Dec}_\top R \simeq \mathbb{N}(R^{\text{upper}})^{\text{op}}
\]

where \(R^{\text{lower}} \subset R\) denotes the subcategory of \(R\)-structures with all the objects, but only the maps whose underlying poset map is a lower-set inclusion. (Similarly, \(R^{\text{upper}}\) has only upper-set inclusion.) (Note that this result does not contradict 5.9: if an ordinary restriction species \(R\) is considered a directed restriction species (as in 7.3) supported on discrete posets, then all inclusion maps are both lower-set inclusions and upper-set inclusions.)
This result is interesting because it relates to classical reduced-incidence-coalgebra constructions. Recall from Example 2.2 that Dürr [9] constructs the Butcher–Connes–Kreimer Hopf algebra as the reduced incidence coalgebra of the (opposite of the) category of rooted forests and root-preserving inclusions. The reduction identifies two forests inclusions if they have isomorphic complement crowns. The reduction is now seen to be the upper-dec map, since the underlying poset of a forest is oriented from leaves to roots, so the root-preserving inclusions are the upper-set inclusions.

8. Convex correspondences and ‘nabla spaces’

8.1. Convex correspondences. Consider the category $\Delta$ of convex correspondences in $\overline{\Delta}$, a subcategory of the category of spans in $\overline{\Delta}$. Objects are those of $\overline{\Delta}$, and morphisms are spans

$$\begin{array}{ccc}
n' & \xleftarrow{j} & n \\
\downarrow{f} & & \downarrow{k}
\end{array}$$

where $j$ is convex. Composition of such spans is given by pullback, which exist by Lemma 3.11. By construction, $\nabla$ has a factorisation system in which the left-hand class (called backward convex maps) consists of spans of the form $\begin{array}{ccc}
\cdot & \xleftarrow{i} & = \\
\downarrow{g} & & \downarrow{f}
\end{array}$, and the right-hand class (called ordinalic maps) consists of spans of the form $\begin{array}{ccc}
\cdot & \xrightarrow{j} & = \\
\downarrow{f} & & \downarrow{k}
\end{array}$.

Composition of an ordinalic map followed by backward convex map is defined by

$$\begin{array}{ccc}
\cdot & \xleftarrow{i} & = \\
\downarrow{g} & & \downarrow{f}
\end{array} \circ \begin{array}{ccc}
\cdot & \xrightarrow{j} & = \\
\downarrow{f} & & \downarrow{k}
\end{array} = \begin{array}{ccc}
\cdot & \xrightarrow{j} & = \\
\downarrow{f} & & \downarrow{k}
\end{array}$$

with reference to the pullback square

$$\begin{array}{ccc}
\cdot & \xleftarrow{i} & = \\
\downarrow{g} & & \downarrow{f}
\end{array}$$

Lemma 8.2. There is a canonical functor

$$\gamma : \Delta \rightarrow \nabla, \quad [n] \mapsto \underline{n},$$

restricting to isomorphisms

$$\Delta \approx \nabla_{\text{gen \ ordinalic}}, \quad (\Delta_{\text{free}})_{\text{op}} \approx (\Delta_{\text{convex}})_{\text{op}} \approx \nabla_{\text{back.conv}.},$$

and sending all maps $[0] \rightarrow [n]$ in $\Delta$ to the zero map $\underline{0} \leftarrow \underline{n} \rightarrow \underline{0}$ in $\nabla$. In particular, $\gamma$ is bijective on objects and full.

In summary, the categories $\Delta_{\text{op}}$ and $\nabla$ differ only in the fact that $\underline{0} \in \nabla$ is initial and terminal, whereas $\text{Hom}_{\Delta_{\text{op}}}(\underline{n}, [0])$ contains $n + 1$ maps.

Proof. The first isomorphism is Lemma 3.3 and the second is Lemma 3.10. □

Proposition 8.3. Precomposing with the canonical functor $\gamma : \Delta_{\text{op}} \rightarrow \nabla$ of Lemma 8.2 induces a fully faithful functor

$$\gamma^* : \text{Fun}(\nabla, \text{Grpd}) \rightarrow \text{Fun}(\Delta_{\text{op}}, \text{Grpd})$$

whose essential image is the full subcategory consisting of simplicial objects with $d_\perp = d_\top : X_1 \rightarrow X_0$. 

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Proof. Any functor which is bijective on objects and full induces a fully faithful functor of the presheaf categories. The main point is to characterise the essential image. Note that every simplicial object \( X \) in the image will have all maps \( X_n \to X_0 \) equal, since the functor \( \gamma \) sends all maps \([0] \to [n]\) to the same image. Given a simplicial object \( X \) with all \( X_n \to X_0 \) equal, we define a \( \nabla \)-diagram by sending each object \( n \) to \( X_n \) and sending each convex correspondence \( n' \overset{f}{\to} n \) to the composite \( X_{(\gamma^{-1}(f))} \to X_{(\gamma^{-1}(j))} \to X_k \), assuming \( n > 0 \) so as to invoke the bijections (4) separately on backward convex and ordinalic maps. For \( n = 0 \), \( \gamma^{-1}(j) \) is not well defined in \( \Delta \), but taking \( X \) on it is well defined, since we have assumed all the maps \( X_n \to X_0 \) coincide. To check functoriality of the assignment, it is enough to treat the situation of an ordinalic map followed by a backward convex map. These compose by pullback in \( \Delta \), and by Lemma 3.12 these pullback squares correspond to commutative squares in \( \Delta \), in a way compatible with the assignments on arrows, so as to ensure that composition is respected. It is clear that this nabla space induces \( X \) as required.

\[ \text{8.4. issq condition on functors.} \] For a functor \( X : \nabla \to \text{Grpd} \), the image of a backward convex map is denoted by upperstar: if the backward convex map corresponds to \( i : k \to k' \) in \( \Delta \), we denote its image by \( i^* : X_{k'} \to X_k \). Similarly, the image of an ordinalic map, corresponding to \( f : n \to k \) in \( \Delta \) is denoted \( f^! : X_n \to X_k \). As observed in 3.13, any identity-extension square in \( \Delta \)

\[
\begin{array}{ccc}
a + n + b & \overset{j}{\to} & n \\
\downarrow \text{id}_a + f + \text{id}_b = g & & \downarrow f \\
\frac{a + k + b}{\text{id}_a + f + \text{id}_b = g} & \overset{i}{\to} & k
\end{array}
\]

is a pullback and hence a commutative square in \( \nabla \) between maps from \( a + n + b \) to \( k \).

The corresponding square of groupoids

\[
\begin{array}{ccc}
X_{a+n+b} & \overset{j^*}{\to} & X_n \\
\downarrow \text{gi} & & \downarrow f_i \\
X_{a+k+b} & \overset{i^*}{\to} & X_k
\end{array}
\]

therefore commutes by functoriality (this is the ‘Beck–Chevalley condition’ (BC)).

We say that \( X \) satisfies the \emph{issq condition} if (6) not only commutes but is furthermore a pullback for every identity-extension square (5).

If a nabla space \( M : \nabla \to \text{Grpd} \) sends identity-extension squares to pullbacks then the composite \( \Delta^{op} \to \nabla \to \text{Grpd} \) is a decomposition space. This follows from the correspondence between issq in \( \Delta \) and generic-free squares in \( \Delta \) (Lemma 3.14).

A morphism of nabla spaces is called \emph{CULF} if it is cartesian on (forward) ordinalic maps, i.e. on arrows in \( \Delta \subset \nabla \). If \( u : M' \Rightarrow M : \nabla \to \text{Grpd} \) is a CULF natural transformation between functors that send identity-extension squares to pullbacks, then it induces a CULF functor between decomposition spaces. Altogether:
Proposition 8.5. Precomposition with $\Delta^{op} \to \nabla$ defines a canonical functor

$$\text{Fun}_{\text{iesq}}(\nabla, \text{Grpd}) \to \text{Decomp}^{\text{culf}}$$

from iesq (pseudo)-functors (and CULF (pseudo)-natural transformations) to decomposition spaces and CULF functors.

9. Sesquicartesian fibrations

9.1. Functors out of $\nabla$. In view of the Proposition 8.5, we are interested in defining functors out of $\nabla$. By its construction as a category of spans, this amounts to defining a covariant functor on $\Delta$ and a contravariant functor on $\Delta_{\text{convex}}$ which agree on objects, and such that for every pullback along a convex map the Beck–Chevalley condition holds. Better still, we can describe these as certain fibrations over $\Delta_{\text{convex}}$ called sesquicartesian fibrations, which we now introduce.

9.2. Sesquicartesian fibrations. A sesquicartesian fibration is a cocartesian fibration $X \to \Delta$ that is also cartesian over $\Delta_{\text{convex}}$, and in addition satisfies the Beck–Chevalley condition: for each pullback in $\Delta$ of a convex map $\tau$, $\sigma' \rightarrowtail \tau \leftarrowtail \sigma$, the comparison map $\sigma' \tau'^* \rightarrow \tau^* \sigma$ is an isomorphism.

Let $\text{Sesq}$ be the category that has as objects the sesquicartesian fibrations and as arrows the functors of sesquicartesian fibrations (required to preserve cocartesian arrows and cartesian arrows over convex maps).

Proposition 9.3. There is a canonical functor

$$\text{Sesq} \longrightarrow \text{Fun}(\nabla, \text{Cat})$$

Recall that $\text{Fun}$ denotes the category of pseudo-functors and pseudo-natural transformations.

Proof. Given a sesquicartesian fibration $p : X \to \Delta$, we can define a pseudo-functor $P : \nabla \to \text{Cat}$ as follows. On objects, send $n$ to the category $X_n$. Send a convex correspondence $n' \xleftarrow{j} n \xrightarrow{f} k$ to the composite functor $X_{n'} \xrightarrow{f^*} X_n \xrightarrow{j^*} X_k$. Individually, the covariant and contravariant reindexing functors compose up to coherent isomorphisms because that’s how cocartesian and cartesian fibrations work. The Beck–Chevalley isomorphisms provide the coherence isomorphisms for general composition.

On arrows: given a morphism $c : p' \to p$ of sesquicartesian fibrations, assign a pseudo-natural transformation $u : P' \Rightarrow P$: its component on $n$ is $c_n : X'_n \to X_n$, its pseudo-naturality square on a backward convex map $n' \xleftarrow{j} n \xrightarrow{f} k$ is given (at an object $x' \in X'_{n'}$) by the isomorphisms $c(j^*(x')) \simeq j^*(c(x'))$ expressing that $c$ preserves cartesian arrows (but not chosen cartesian). Similarly with the forward maps and cocartesian lifts. Again BC is invoked to ensure these are really pseudo-natural.

9.4. Remark. From work of Hermida [23] and Dawson–Paré–Pronk [8], it can be expected that this functor is actually an equivalence, but we do not need this result and do not pursue the question further here.
9.5. The iesq property. A sesquicartesian fibration $p : X \rightarrow \Delta$ is said to have the iesq property if for every identity-extension square

$$
\begin{array}{ccc}
  a + n + b & \xrightarrow{j} & n \\
  \downarrow{\text{id}_a + f + \text{id}_b = g} & & \downarrow{f} \\
  a + k + b & \xrightarrow{i} & k
  \end{array}
$$

the diagram of categories

$$
\begin{array}{ccc}
  X_{a+n+b} & \xrightarrow{j^*} & X_n \\
  \downarrow{g} & & \downarrow{f} \\
  X_{a+k+b} & \xrightarrow{i^*} & X_k
  \end{array}
$$

not only commutes up to natural isomorphism (the BC condition), but is furthermore a homotopy pullback of categories (i.e. it is equivalent to a iso-comma square).

Let $\text{IesqSesq}$ be the category whose objects are the sesquicartesian fibrations $p : X \rightarrow \Delta$ having the iesq property, and whose arrows are functors over $\Delta$ that preserve cocartesian arrows and cartesian arrows (over convex maps), and satisfying the condition that for every arrow $f : n \rightarrow k$ in $\Delta$, the following square is a homotopy pullback:

$$(7)$$

$$
\begin{array}{ccc}
  X_n & \xrightarrow{f_i} & X_k \\
  \downarrow{c} & & \downarrow{c} \\
  Y_n & \xrightarrow{f_i} & Y_k
  \end{array}
$$

This condition on arrows $c : X \rightarrow Y$ is equivalent to saying that the associated (pseudo)-natural transformation of pseudo-functors $\Delta \rightarrow \text{Cat}$ is homotopy cartesian, i.e. all its (pseudo)-naturality squares are homotopy pullbacks.

**Proposition 9.6.** The functor of Proposition 9.3 restricts to a functor

$$
\text{IesqSesq} \rightarrow \text{Fun}_{\text{culf}}^{\text{iesq}}(\Delta, \text{Cat})
$$

Here $\text{Fun}_{\text{culf}}^{\text{iesq}}(\nabla, \text{Cat})$ is the subcategory of $\text{Fun}(\nabla, \text{Cat})$ whose objects are those $X : \nabla \rightarrow \text{Cat}$ such that for every identity extension square the corresponding Beck–Chevalley square is a homotopy pullback in $\text{Cat}$, and whose morphisms are those pseudo-natural transformations $X \rightarrow Y$ that are homotopy cartesian on (forward) ordnical maps, i.e. on arrows in $\Delta \subset \nabla$. Compare 8.4 for corresponding notions in $\text{Fun}(\nabla, \text{Grpd})$.

Taking maximal subgroupoids to get a functor $\text{Fun}_{\text{culf}}^{\text{iesq}}(\nabla, \text{Cat}) \rightarrow \text{Fun}_{\text{culf}}^{\text{iesq}}(\nabla, \text{Grpd})$, and combining Propositions 9.6 and 8.5, we obtain:

**Theorem 9.7.** The constructions so far define a functor

$$
\text{IesqSesq} \rightarrow \text{Decomp}^{\text{culf}}.
$$
9.8. Decomposition categories. The notion of decomposition space admits an obvious variation: that of decomposition category given by a (pseudo)-functor \( X : \Delta^{\text{op}} \to \text{Cat} \) such that the generic-free squares are homotopy pullbacks. It is clear that iesq sesquicartesian fibrations define actually decomposition categories—it is sort of artificial that we took groupoid interior as the last step to force the result to be a decomposition space instead of a decomposition category (the motivation being of course to take homotopy cardinality and get coalgebras). While for \( \triangledown \)-diagrams and \( \Delta^{\text{op}} \)-diagrams it is obvious how to take groupoid interior, corresponding to taking the left fibration associated to a cocartesian fibration, this is not so for sesquicartesian fibrations, which have genuinely categorical fibres.

Decomposition categories arose also in our work \([20]\) where the universal decomposition space of Möbius intervals is in fact constructed as a decomposition \( \infty \)-category. We leave for another occasion a more systematic study of decomposition categories.

9.9. Example: monoids. A monoid viewed as a monoidal functor \( X : (\mathbf{A}, +, 0) \to (\text{Grpd}, \times, 1) \) defines a iesq sesquicartesian fibration. The contravariant functoriality on the convex maps is given as follows. The cartesian lift of a convex map \( a + n + b \to n \) is simply the projection

\[
X_{a+n+b} \simeq X_a \times X_n \times X_b \to X_n,
\]

where the first equivalence expresses that \( X \) is monoidal. For any identity-extension square (5), it is clear that the corresponding diagram

\[
\begin{array}{ccc}
X_{a+n+b} & \xrightarrow{j^*} & X_n \\
\downarrow{g} & & \downarrow{f} \\
X_{a+k+b} & \xrightarrow{i^*} & X_k
\end{array}
\]

is a pullback, since the upperstar functors are just projections. The associated decomposition space is the classifying space of the monoid.

10. From restriction species to iesq-sesqui

In order to construct nabla spaces satisfying the iesq property, we can construct sesquicartesian fibrations satisfying iesq, and then take maximal sub-groupoid.

All our examples originate as the left leg of a two-sided fibration, as we proceed to explain.

10.1. Two-sided fibrations. Classically (the notion is due to Street \([49]\)), a two-sided fibration is a span of functors

\[
\begin{array}{ccc}
X & \xrightarrow{q} & T \\
\downarrow{p} & & \downarrow{=} \\
S & \xrightarrow{=} & T
\end{array}
\]

such that

— \( p \) is a cocartesian fibration whose \( p \)-cocartesian arrows are precisely the \( q \)-vertical arrows,
— \( q \) is a cartesian fibration whose \( q \)-cartesian arrows are precisely the \( p \)-vertical arrows,
— for \( x \in X \), an arrow \( f : px \to s \) in \( S \) and \( g : t \to qx \) in \( T \), the canonical map \( f_*g^*x \to g^*f_*x \) is an isomorphism.
In the setting of \(\infty\)-categories, Lurie [38, §2.4.7] (using the terminology ‘bifibration’) characterises two-sided fibrations as functors \(X \to S \times T\) subject to a certain horn-filling condition, which among other technical advantages makes it clear that the notion is stable under pullback along functors \(S' \times T' \to S \times T\). The classical axioms are derived from the horn-filling condition.

**10.2. Comma categories.** \(\text{Ar}(\mathcal{C}) \xrightarrow{(\text{dom}, \text{codom})} \mathcal{C} \times \mathcal{C}\) is a two-sided fibration. Given categories and functors

\[
\begin{array}{ccc}
S & \xrightarrow{G} & \mathcal{C} \\
\downarrow{F} & & \downarrow{} \\
T & \xrightarrow{} & I
\end{array}
\]

the *comma category* \(T \downarrow S\) is the category whose objects are triples \((t, s, \phi)\), where \(t \in T\), \(s \in S\), and \(\phi : Ft \to Gs\). More formally it is defined as the pullback two-sided fibration

\[
\begin{array}{ccc}
T \downarrow S & \xrightarrow{} & \text{Ar}(I) \\
\downarrow{J} & & \downarrow{} \\
S \times T & \xrightarrow{G \times F} & I \times I
\end{array}
\]

Note that the factors come in the opposite order: \(T \downarrow S \to S\) is the cocartesian fibration, and \(T \downarrow S \to T\) the cartesian fibration. The left leg cocartesian fibration comes with a canonical splitting. The two-sided fibration sits in a comma square which we depict like this:

\[
\begin{array}{ccc}
T \downarrow S & \xrightarrow{} & T \\
\downarrow{} & & \downarrow{} \\
S & \xrightarrow{=} & I
\end{array}
\]

**Lemma 10.3.** In a diagram

\[
\begin{array}{ccc}
X \times_T R & \xrightarrow{R} & R \\
\downarrow{J} & & \downarrow{w} \\
X & \xrightarrow{q} & T \\
\downarrow{p} & & \downarrow{} \\
\Delta & \xrightarrow{} & \Delta
\end{array}
\]

where

- \((p, q) : X \to \Delta \times T\) is a two-sided fibration;
- \(p : X \to \Delta\) is a iesq sesquicartesian fibration; and
- \(w : R \to T\) is a cartesian fibration;

we have

1. \(f\) is a iesq sesquicartesian fibration.
2. the map \(X \times_T R \to X\) is a morphism of iesq sesquicartesian fibrations from \(f\) to \(p\) (in the sense of 9.5).

**Proof.** (1) \(f\) is a cocartesian fibration because it is the left leg of the pullback two-sided fibration of \(X \to \Delta \times T\) along \(\Delta \times R \to \Delta \times T\). The \(f\)-cartesian lift of a given convex
arrow has components \((\ell, c)\) where \(\ell\) is a \(p\)-cartesian lift to \(X\), and \(c\) is a \(w\)-cartesian lift of \(q(\ell)\). Given the pullback square

\[
\begin{array}{ccc}
X_{a+n+b} & \xrightarrow{j^*} & X_n \\
\sigma' \downarrow & & \downarrow \sigma_i \\
X_{a+k+b} & \xrightarrow{i^*} & X_k
\end{array}
\]

expressing that \(X \to \Delta\) has the iesq property, the corresponding square for \(X \times_T R \to \Delta\) is simply obtained applying \(- \times_T R\) to it, hence is again a pullback, so \(f\) has the iesq property.

(2) By construction \(X \times_T R \to X\) preserves cocartesian arrows and cartesian arrows over convex maps, so it is indeed a morphism of sesquicartesian fibrations. For each arrow \(\sigma : n \to k\) in \(\Delta\), the square required to be a pullback is

\[
\begin{array}{ccc}
X_n \times_T R & \xrightarrow{\sigma \times_T R} & X_k \times_T R \\
\downarrow & & \downarrow \\
X_n & \xrightarrow{\sigma_i} & X_k
\end{array}
\]

which is clear.

\[\square\]

10.4. Restriction species and directed restriction species. Recall that \(I\) denotes the category of finite sets and injections, and that a restriction species is a functor \(R : I^{\text{op}} \to \text{Grpd}\), or equivalently, a right fibration \(R \to I\). Recall also that \(C\) denotes the category of finite posets and convex maps, and that a directed restriction species is a functor \(R : C^{\text{op}} \to \text{Grpd}\), or equivalently, a right fibration \(R \to C\).

We are going to establish that every ordinary restriction species and every directed restriction species defines naturally a iesq sesquicartesian fibration. We will do the proofs for directed restriction species, and then exploit the fact that ordinary restriction species are a special kind of directed restriction species to deduce the results also for ordinary restriction species.

**Proposition 10.5.** The projection \(C \downarrow \Delta \to \Delta\) is a iesq sesquicartesian fibration.

**Proof.** The comma category is taken over \(\text{Poset}\). The objects of \(C \downarrow \Delta\) are poset maps \(P \to k\), and the arrows are squares in \(\text{Poset}\)

\[
\begin{array}{ccc}
Q & \xrightarrow{f} & P \\
\downarrow \quad & & \downarrow \\
\quad \quad n & \xrightarrow{} & k
\end{array}
\]

with \(Q \to P\) a convex map and \(n \to k\) a monotone map. Just from being a comma category projection, \(C \downarrow \Delta \to \Delta\) is a (split) cocartesian fibration. The chosen cocartesian arrows are squares in \(\text{Poset}\) of the form

\[
\begin{array}{ccc}
P & \xrightarrow{i} & P \\
\downarrow \quad & & \downarrow \\
\quad \quad n & \xrightarrow{} & k
\end{array}
\]
Over $\Delta_{\text{convex}}$ it is also a (split) cartesian fibration, as follows readily from Lemma 6.2 on pullback stability of convex maps in Poset: the cartesian arrows over a convex map are squares in Poset of the form

$$
\begin{array}{ccc}
P & \xrightarrow{\beta} & P' \\
p^* & \downarrow & \downarrow \\
\alpha & \downarrow & \downarrow \\
k^* & \downarrow \beta & \downarrow \beta \\
k' & \rightarrow & k'.
\end{array}
$$

The chosen cartesian arrows are the squares in which the map $P \to P'$ is an actual inclusion.

Finally for the iseq property, we need to check that given

$$
\begin{array}{ccc}
a + n + b = n' \\
\alpha + f + id_b & = & f \\
a + k + b = k' \\
\beta & \downarrow & \downarrow \\
k & \rightarrow & k'.
\end{array}
$$

the resulting strictly commutative square

$$
\begin{array}{ccc}
C_{/n'} & \xrightarrow{j*} & C_{/n} \\
g_! & \downarrow & \downarrow \\
C_{/k'} & \xrightarrow{i*} & C_{/k}
\end{array}
$$

is a pullback. To this end, note first that lowershriek functors between slices are cartesian fibrations, so it is enough to show that this square is a strict pullback. We first compute the strict pullback at the level of objects. A pair $(P' \xrightarrow{\beta} k', P \xrightarrow{\alpha} n)$ lies in the pullback $C_{/k'} \times_{C_{/k}} C_{/n}$ if $i*\beta = f_!\alpha$, that is, $P$ is an actual subposet of $P'$ and this diagram is a pullback:

$$
\begin{array}{ccc}
P & \xrightarrow{\alpha} & P' \\
\downarrow & & \downarrow \\
f & \downarrow & \downarrow \\
k' & \rightarrow & k'.
\end{array}
$$

The claim is then that there is a unique way to complete this diagram to

$$
\begin{array}{ccc}
P & \xrightarrow{\alpha} & P' \\
\downarrow & & \downarrow \\
\beta & \downarrow \beta & \downarrow \beta \\
k & \rightarrow & k'.
\end{array}
$$

Indeed, at the level of elements, $P'$ is constituted by three subsets, namely the inverse images $P'_{a^*}$, $P'_{k^*}$ and $P'_{k^*}$. (We don’t need to worry about the poset structure, since we already know all of $P'$. The point is that the covariant functoriality does not change the
total space.) We now define $P' \to \underline{n'} = a + \underline{n} + b$ as follows: we use $\beta$ to define $P'_a \to a$ and $P'_b \to b$ on the outer subsets, and on the middle subset we use $\alpha$ to define $P'_k = P \to \underline{n}$. Conversely, an element in $C/\underline{n}'$ defines an element in the pullback, and it is clear that the two constructions are inverse to each other. Having established that the two groupoids have the same objects, it remains to check that their automorphism groups agree. An automorphism of a pair $(P' \beta \to k', P \alpha \to \underline{n})$ is an automorphism of $P'$ compatible with the $k'$-layering and whose restriction to $k$ is furthermore compatible with the refined layering here, given by $P \to \underline{n}$. But this is precisely to say that it is an automorphism of $P'$ that is compatible with the layering $P' \to \underline{n}'$ constructed. \qed

**Proposition 10.6.** There is a natural functor

$$\text{DRSp} \simeq \text{RFib}_C \to \text{IesqSesq},$$

which takes a directed restriction species $R : C^{\text{op}} \to \text{Grpd}$ with associated right fibration $R \to C$ to the comma category projection $R \downarrow \Delta \to \Delta$.

**Proof.** Just note that stacking pullbacks on top of a comma square yields again comma squares:

$$\begin{array}{ccc}
R \downarrow \Delta & \longrightarrow & R' \\
\downarrow & & \downarrow \\
R \downarrow \Delta & \longrightarrow & R \\
\downarrow & & \downarrow \\
C \downarrow \Delta & \longrightarrow & C \\
\downarrow & & \downarrow \\
\Delta & \longrightarrow & \text{Poset}.
\end{array}$$

Now $C \downarrow \Delta \to \Delta$ is a iesq sesquicartesian fibration by Proposition 10.5, so the statement about objects follows from Lemma 10.3 (1) and the statement about morphisms from Lemma 10.3 (2). \qed

From these results for directed restriction species, the analogous results for ordinary restriction species can be deduced, remembering from 7.3 that $I \to C$ is a right fibration.

**Corollary 10.7.** The projection $I \downarrow \Delta \to \Delta$ is a iesq sesquicartesian fibration.

**Corollary 10.8.** For any ordinary restriction species $R : I^{\text{op}} \to \text{Grpd}$ with associated right fibration $R \to I$, the comma category projection $R \downarrow \Delta \to \Delta$ is a iesq sesquicartesian fibration.

Proposition 10.6, together with Theorem 9.7 (that is, Propositions 8.5 and 9.6), gives the following result, summarising our constructions so far.

**Theorem 10.9.** The constructions above define functors

$$\begin{array}{ccc}
\text{RSp} & \xrightarrow{7.3} & \text{DRSp} \\
& \xrightarrow{10.6} & \text{IesqSesq} \\
& \xrightarrow{9.6} & \text{Fun}_{\text{iesq}}(\nabla, \text{Grpd}) \\
& \xrightarrow{8.5} & \text{Decomp}^{\text{culf}}.
\end{array}$$

These functors are not exactly fully faithful but we shall see in the next section that they become fully faithful when suitably sliced.
10.10. Unpacking, and comparison with the discussion in §7. Given a directed restriction species \( R : \mathcal{C}^{\text{op}} \to \text{Grpd} \), we may consider the associated right fibration \( p : R \to \mathcal{C} \) as a morphism in \( \text{RFib}_\mathcal{C} \) from \( p \) to the terminal object \( \mathcal{C} \to \mathcal{C} \). Theorem 10.9 then associates to this a decomposition space \( R : \Delta^{\text{op}} \to \text{Grpd} \) with a CULF functor \( \Psi(p) : R \to \mathcal{C} \), constructed via ieq-sesqui and nabla spaces.

Indeed, we have a functor
\[
\Psi : \text{RFib}_\mathcal{C} \to \text{Decomp}^{\text{culf}}_\mathcal{C}
\]
to the category of decomposition spaces which are CULF over \( \mathcal{C} \).

Let us unpack the constructions. Consider the pullback of \( p \) to the comma categories

\[
\begin{array}{c}
\mathcal{C}/n \\
\downarrow \\
\downarrow \\
\downarrow \\
\Downarrow \\
\Delta \\
\downarrow \\
\mathcal{C} \\
\downarrow \\
\downarrow \\
\downarrow \\
\downarrow \\
\downarrow \\
\Delta \\
\downarrow \\
\text{Poset}.
\end{array}
\]

The values of the simplicial groupoids \( R \) and \( \mathcal{C} \) at \([n]\), are groupoid interiors of the fibres over \( n \in \Delta \).

\[
\begin{align*}
\mathcal{C}_n &= (\mathcal{C}\downarrow \Delta)_{/n} = \mathcal{C}_{/n}, \\
R_n &= (R\downarrow \Delta)_{/n} = R_{/n} = \mathcal{C}_{/n} \times \mathcal{C}_{/n} \times \mathcal{R}_{/n},
\end{align*}
\]

and \( \Psi(p)_n : R_n \to \mathcal{C}_n \) is the canonical projection. The simplicial structure is given as follows:

- A generic map \( g : [n] \to [k] \) in \( \Delta \) and the corresponding \( g : k \to n \) in \( \Delta \) induce, by postcomposition, the map of groupoids
  \[
  \mathcal{C}_k \to \mathcal{C}_n, \quad (P \to k) \mapsto g(P \to k) = (P \to k \to n).
  \]

  This in turn induces the map \( R_k \to R_n \),

  \[
  \begin{array}{c}
  R_k \\
  \downarrow \\
  \downarrow \\
  \downarrow \\
  \downarrow \\
  \mathcal{C}_k \\
  \downarrow \\
  \downarrow \\
  \downarrow \\
  \downarrow \\
  \downarrow \\
  \mathcal{C}_1.
  \end{array}
  \]

  and hence the projection \( R \to \mathcal{C} \) is cartesian on generic maps.

- A free map \( f : [n] \to [k] \) in \( \Delta \) and the associated convex map \( f : n \to k \) in \( \Delta \) induce, by pullback, the homomorphism
  \[
  \mathcal{C}_k \to \mathcal{C}_n, \quad (P \to k) \mapsto (f^*P \to n).
  \]

  The definition of \( R_k \to R_n \) uses the directed restriction species structure,

  \[
  \begin{align*}
  \mathcal{C}_k \times \mathcal{C}_1 R_1 &\to \mathcal{C}_n \times \mathcal{C}_1 R_1, \\
  (P \to k, S) &\mapsto (f^*P \to n, (S \downarrow f^*P)).
  \end{align*}
  \]
11. Decalage and fully faithfulness

We have already exploited (Proposition 6.11) the decalage formulae
\[ \text{Dec}_\perp(C) \simeq N(C_{\text{lower}}) \quad \text{Dec}_\top C \simeq N((C_{\text{upper}})^{\text{op}}) \]
which we now generalise as follows. For each directed restriction species \( R \), we can pull back the corresponding right fibration \( R \to C \) to these subcategories of upper- and lower-set inclusions, giving
\[ R_{\text{lower}} := C_{\text{lower}} \times_C R, \quad R_{\text{upper}} := C_{\text{upper}} \times_C R, \]
the categories of \( R \)-structures and their lower-set and upper-set inclusions. Thus we have pullback functors
\[ RFib_{/C_{\text{lower}}} \leftarrow\leftarrow RFib_{/C} \rightarrow\rightarrow RFib_{/C_{\text{upper}}}. \]

**Proposition 11.1.** We have the following natural (levelwise) equivalences of simplicial groupoids:
\[ \text{Dec}_\perp R \simeq N R_{\text{lower}} \quad \text{Dec}_\top R \simeq N((R_{\text{upper}})^{\text{op}}). \]

**Proof.** The equivalences are expressed by commutativity of the left-hand faces (incident with the edge labelled by the functor \( \Psi : R \to R \)) of the cube in the following lemma. \( \square \)

**Lemma 11.2.** We have the commutative diagram

\[ \begin{array}{ccc}
RFib_{/C} & \xrightarrow{\text{N}} & \text{Fib}_{/C_{\text{iso}}} \\
\downarrow \Psi & & \downarrow N \\
RFib_{/(\text{Dec}_\top C)^{\text{op}}} & \xrightarrow{\text{N}} & RFib_{/C_{\text{iso}}} \\
\downarrow \text{Dec}_\top & & \downarrow \text{N} \\
\text{Decomp}_{/C_{\text{cart}}} & \xrightarrow{\text{Dec}_\perp} & RFib_{/C_{\text{lower}}} \\
\downarrow \text{Dec}_\perp & & \downarrow \text{Dec}_\perp \\
RFib_{/Dec_{\perp}C} & \xrightarrow{\text{Dec}_\perp} & Cart_{/C_1} \\
\downarrow \text{Dec}_\perp & & \downarrow \text{Dec}_\perp \\
RFib_{/C} & \xrightarrow{\text{Dec}_\perp} & Cart_{/C_1} \\
\end{array} \]

**Proof.** We first prove that the left-hand faces commute. In simplicial degree zero the images of \( p : R \to C \) clearly coincide: they are \( p^{\text{iso}} : R_1 = R_{\text{iso}} \to C_1 = C_{\text{iso}} \). Analogously to 10.10 we can write
\[
(\text{Dec}_\perp R)_k = R_{k+1} = C_{k+1} \times_{C_1} R_1 = (\text{Dec}_\perp C)_k \times_{C_1} R_1 \\
(N R_{\text{lower}})_k = (N C_{\text{lower}})_k \times (N C_{\text{lower}})_0 \times (N R_{\text{lower}})_0 = (N C_{\text{lower}})_k \times_{C_1} R_1,
\]
and similarly for \( \text{Dec}_\top \) and the categories of upper-set inclusions. From Proposition 6.11 we have canonical equivalences of simplicial groupoids \( \text{Dec}_\perp C = N C_{\text{lower}} \) and \( \text{Dec}_\top C = \)

We also have commuting diagrams for generic or bottom face maps

\[
\begin{array}{ccc}
(\text{Dec } R)_k & \xrightarrow{\cong} & (N(C)_{\text{lower}})_k \\
\downarrow & & \downarrow \\
(\text{Dec } R)_n & \xrightarrow{\cong} & (N(C)_{\text{lower}})_n
\end{array}
\]

The diagram for \(d_T : [k-1] \to [k]\) also commutes:

\[
\begin{array}{ccc}
\left( \begin{array}{c}
P \\ k+1 \end{array} \right) & \xrightarrow{\phi} & (P_\perp \subseteq P_2 \subseteq \cdots \subseteq P, S) \\
\downarrow & & \downarrow \\
\left( \begin{array}{c}
d_T P \\ k \end{array} \right) & \xrightarrow{\phi} & (P_\perp \subseteq \cdots \subseteq P_k, (S|d_T * P_k)).
\end{array}
\]

This shows that the two left-hand faces commute.

The top face is just pullback to \(C_{\text{iso}}\) taken in two steps in two ways. For the bottom face, observe first that \(C_1\) is the constant simplicial groupoid with value \(C_1 = C_{\text{iso}}\). The bottom face commutes because both ways around send a CULF map \(R \to C\) to the (obviously cartesian) simplicial map of constant simplicial groupoids \(R_1 \to C_1\). The right-hand faces are easier to understand with \(RFib_{N(C)_{\text{upper}}}\) instead of \(LFib_{/\text{Dec } C}\) and \(RFib_{N(C)_{\text{lower}}}\) instead of \(RFib_{/\text{Dec } C}\): commutativity of the two squares then just amounts to the fact that the fat nerve commutes with pullbacks. \(\square\)

Since ordinary restriction species are just directed restriction species supported on discrete posets, Proposition 11.1 implies the following result, remembering that for discrete posets, every inclusion is both a lower-set and an upper-set inclusion:

**Corollary 11.3.** For an ordinary restriction species \(R \to I\) with associated decomposition space \(R\), we have

\[
\text{Dec}_{\perp}(R) \simeq N(R) \quad \text{Dec}_{\top}(R) \simeq N(R)^{\text{op}}.
\]

**Theorem 11.4.** The functor

\[
\Psi : DRSp \longrightarrow \text{Decomp}_{/C}^{\text{cufl}}
\]

is fully faithful.

**Proof.** From the cube diagram in Lemma 11.2 we get the commutative square

\[
\begin{array}{ccc}
RFib_{/C} & \xrightarrow{(\text{pbk, pbk})} & RFib_{/C_{\text{lower}}} \times RFib_{/C_{\text{iso}}} \\
\downarrow & & \downarrow \\
\text{Decomp}_{/C}^{\text{cufl}} & \xrightarrow{(\text{Dec}_{\perp}, \text{Dec}_{\top})} & RFib_{/\text{Dec}_{\perp}C} \times LFib_{/\text{Dec}_{\top}C}.
\end{array}
\]

Now the main point is that the pair of pullback functors is jointly fully faithful. Indeed, a transformation is natural in all convex maps if and only if it is natural in both lower-set inclusions and upper-set inclusions, since every convex inclusion factors (non-uniquely)
as a lower-set inclusion followed by an upper-set inclusion. Since also the fibre product of fat nerves is fully faithful, and since the pair of Decs is faithful, we conclude that \( \Psi \) is fully faithful.

\[ \square \]

**Theorem 11.5.** The functor

\[ RSp \rightarrow \text{Decomp}_{/I}^{\text{culf}} \]

is fully faithful.

**Proof.** In the commutative diagram

\[
\begin{array}{ccc}
RSp & \longrightarrow & \text{Decomp}_{/I}^{\text{culf}} \\
\downarrow & & \downarrow \\
DRSp & \longrightarrow & \text{Decomp}_{/C}^{\text{culf}}
\end{array}
\]

\( RSp \subset DRSp \) is clearly fully faithful; \( DRSp \rightarrow \text{Decomp}_{/C}^{\text{culf}} \) is fully faithful by Theorem 11.4, and \( \text{Decomp}_{/I}^{\text{culf}} \rightarrow \text{Decomp}_{/C}^{\text{culf}} \) is fully faithful since \( l \rightarrow C \) is a monomorphism in \( \text{Decomp}^{\text{culf}} \).

\[ \square \]

12. Remarks on strictness

Since our general philosophy is that the homotopy content is the essence—and in the end we want to take homotopy cardinality anyway—we have worked in this paper with groupoids up to homotopy: when we say simplicial groupoid, we mean pseudo-functor \( \Delta^{\text{op}} \rightarrow \text{Grpd} \), and all pullbacks mentioned are homotopy pullbacks.

Nevertheless, one may rightly feel that it is nicer to work with strict simplicial objects. In the present situation one can actually have a strict version of everything, if just restriction species and directed restriction species are assumed to be strict groupoid-valued functors, not pseudo-functors (and their morphisms strict natural transformations rather than pseudo-natural transformations). It is doable to trace through all the construction with sufficient care to ensure that the resulting decomposition spaces are again strict.

We finish the paper by outlining the arguments going into this. First of all:

12.1. **Strict decomposition spaces.** We define **strict decomposition spaces** to be strict functors \( \Delta^{\text{op}} \rightarrow \text{Grpd} \) such that the generic-free squares are simultaneously strict pullbacks and homotopy pullbacks.

Note that the squares in question are already strictly commutative since they are strict simplicial identities, so in practice the pullback condition happens because it is a strict pullback in which one of the legs is an iso-fibration.

For example, the fat nerve of a small category is a strict decomposition space: it is clearly a strict functor, the Segal squares are readily seen to be strict pullbacks, and the face maps are iso-fibrations because the coface maps in \( \Delta \) are injective on objects.

12.2. **Strict CULF functors.** We define a **strict CULF functor** to be a strictly simplicial map, whose naturality squares on generic maps are simultaneously strict pullbacks and homotopy pullbacks.

Again, this typically happens when the simplicial map is degree-wise an iso-fibration.
Theorem 12.3. The functors $RSp \to DRSp \to \text{Decomp}^{\text{culf}}$ of Theorem 10.9 take strict (directed) restriction species and their strict morphisms to strict decomposition spaces and strict CULF functors.

Let us explain the main intermediate step.

12.4. Strictly iesq sesquicartesian fibrations. A sesquicartesian fibration is split when there are specified functorial cocartesian lifts for all maps and specified functorial cartesian lifts for convex maps, and such that the Beck–Chevalley isomorphisms are strict identities. A split sesquicartesian fibration is strictly iesq when the strictly commutative Beck–Chevalley squares are both strict pullbacks and homotopy pullbacks. A strict morphism of strictly iesq sesquicartesian fibrations is by definition a functor that preserves the specified lifts, both cocartesian and cartesian, and for which the square (7) is both a strict pullback and a homotopy pullback.

Lemma 12.5. The functors $RSp \to DRSp \to \text{IesqSesq}$ of Proposition 10.6 take strict (directed) restriction species and their strict morphisms to strictly iesq sesquicartesian fibrations and strict morphisms.

The main ingredient in checking this is the fact that the base case $\mathcal{C} \downarrow \Delta \to \Delta$ is a strictly iesq sesquicartesian fibration. This follows from inspection of the proof of Proposition 10.5, where in fact the crucial pullback square was established as a strict pullback along an isofibration. For this we exploited in particular that the pullbacks of convex maps can be taken to be actual subset inclusions.

For the general strict directed restriction species (which includes $I$), the proof follows from niceness of comma categories, including the fact that comma-category projections are always split cartesian and cocartesian fibrations, and therefore the top squares in the proof of Proposition 10.6 can be taken to be strict pullbacks.

Finally, it is straightforward to verify that all the strictnesses are preserved by the functor of Proposition 9.6 to (suitably strict) nabla spaces, and from there to strict decomposition spaces via Proposition 8.5.

We stress that for the sake of taking homotopy cardinality to obtain incidence coalgebras, the strictness is irrelevant.

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