Introduction to multifractal detrended fluctuation analysis in Matlab

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INTRODUCTION

The structural characteristics of biomedical signals are often visually apparent, but not captured by conventional measures like the average amplitude of the signal. Biomedical signals from a wide range of physiological phenomena possess a scale invariant structure. A biomedical signal has a scale invariant structure when the structure repeats itself on subintervals of the signal. Formally, the biomedical signal $X(t)$ are scale invariant when $X(ct) = c^H X(t)$. Fractal analyses estimates the power law exponent, $H$, that defines the particular kind of scale invariant structure of the biomedical signal. Fractal analyses are frequently employed in biomedical signal processing to define the scale invariant structure in ECG, EEG, MR, and X-ray pictures (cf. Lopes and Betrouni, 2009). The scale invariant structures of inter-spike-interval of neuron firing, inter-stride-interval of human walking, inter-breath-interval of human respiration, and inter-beat intervals of the human heart has differentiated between healthy and pathological conditions (e.g., Ivanov et al., 1999; Peng et al., 2002; Zheng et al., 2005; Hausdorff, 2007), and between different types of pathological conditions (e.g., Wang et al., 2007). Scale invariant structures are also found in spatial phenomena like the branching of the nervous system and lungs (e.g., Bassingthwaighte et al., 1990; Abbound et al., 1991; Weibel, 1991; Krenz et al., 1992), bone structure (Parkinson and Fazzalari, 1994), and are able to differentiate between healthy and cancer tissues (Atupelage et al., 2012). Several reports during the last decade suggest that changes in the scale invariant structure of biomedical signals reflect changes in the adaptability of physiological processes and successful treatment of pathological conditions might change fractal structure and improve health (Goldberger, 1996; Goldberger et al., 2002). Fractal analyses are therefore promising prognostic and diagnostic tools in biomedical signal processing.

Mono fractal and multifractal structures of the biomedical signal are particular kind of scale invariant structures. Most commonly, the monofractal structure of biomedical signals are defined by a single power law exponent and assumes that the scale invariance is independent on time and space. However, spatial and temporal variation in scale invariant structure of the biomedical signal often appears. These spatial and temporal variations indicate a multifractal structure of the biomedical signal that is defined by a multifractal spectrum of power law exponents. As an example, age related changes in the scale invariant structure of heartbeat variability are indicated by changes of the multifractal spectrum rather than a single power law exponent (e.g., Makowiec et al., 2011). The width and shape of the multifractal spectrum can also differentiate between the heart rate variability from patients with heart diseases like ventricular tachycardia, ventricular fibrillation and congestive heart failure (e.g., Ivanov et al., 1999; Wang et al., 2007). The multifractal structure of heart rate variability is therefore suggested to reflect important properties of the autonomic regulation of the heart rate (Goldberger et al., 2002). Furthermore, the multifractal spectrum of endogenous brain dynamics and response times is more sensitive to the influence of age and cognitive performance compared to a single power law exponent alone (Suckling et al., 2008; Ihlen and Vereijken, 2010). Furthermore, the multifractal structure of EEG and series of inter-spike intervals have been able to differentiate between the neural activities of brain areas (Zheng et al., 2005). Multifractal analyses might therefore be important as a computer aided tool to increase the precision of neurosurgeries. The main aim of the present tutorial is to introduce a robust analysis called the multifractal detrended fluctuation analysis (MFDFA) that can estimate the multifractal spectrum of power law exponents from a biomedical time series (Kanterhardt et al., 2002). Those readers not familiar with analysis...
of monofractal fluctuations in biomedical signals are referred to Eke et al. (2000).

The tutorial is intended to be a self-sustained guide to the implementation of MFDFA to time series and interpretation of the resulting multifractal spectra to the readers that are unfamiliar to fractal analysis. In order to be a self-sustained guide, the tutorial decomposes MFDFA into a series of simple Matlab codes that are introduced in a step-wise manner to the reader. The tutorial is meant to be interactive where the reader can employ the Matlab codes while reading the text to enhance the understanding of MFDFA. The reader is therefore advised to download the folder “Introduction to MFDFA” at the web site www.ntnu.edu/inm/geri/software where all Matlab codes used in the tutorial are available. The reader should set the folder as the current directory folder in Matlab before reading the following sections of the tutorial. The folder can be set as current directory folder by pasting it into the current directory window after opening Matlab. Matlab variables, parameters, and commands are written in the Matlab command font and a red color to separate them from the rest of the text. The reader can type the red commands in the Matlab command window wherever they appear in the text to access variables and parameters or plot them with Matlab’s plot function. A translation of the Matlab codes of MFDFA to the mathematical notations used by Kantelhardt et al. (2002) are given for the readers interested in the mathematical details of the MFDFA. The rest of the tutorial is divided into two sections: the implementation of MFDFA in Matlab is introduced step-by-step in Section “Multifractal Detrended Fluctuation Analysis in Matlab” where the interpretation of the resulting multifractal spectrum is emphasized. Important issues for the best practice of MFDFA are discussed in Section “The Best Practice of Multifractal Detrended Fluctuation Analysis.”

MULTIFRACTAL DETRENDED FLUCTUATION ANALYSIS IN MATLAB

The construction of MFDFA is divided into eight steps: Section “Noise and Random Walk Like Variation in a Time Series” introduces a method to convert a noise like time series into a random walk like time series that is a preliminary step for MFDFA. Section “Computing the Root-Mean-Square Variation of a Time Series” introduces root-mean-square (RMS) that is the basic computation within MFDFA and a typical way to compute the average variation of biomedical time series. Section “Local Root-Mean-Square Variation in the Time Series” introduces the computation of local fluctuation in the time series as RMS of the time series within non-overlapping segments. In Section “Local Detrending of the Time Series,” the same local RMS is computed around trends that are often encountered in biomedical time series. In Section “Monofractal Detrended Fluctuation Analysis,” the amplitudes of the local RMS are summarized into an overall RMS. The overall RMS of the segments with small sample sizes is dominated by the fast fluctuations in the time series. In contrast, the overall RMS for segments with large sample sizes is dominated by slow fluctuations. The power law relation between the overall RMS for multiple segment sample sizes (i.e., scales) is defined by a monofractal detrended fluctuation analysis (DFA) and is called the Hurst exponent. In Section “Multifractal Detrended Fluctuation Analysis of Time Series,” MFDA is obtained by the q-order extension of the overall RMS. The q-order RMS can distinguish between segments with small and large fluctuations. The power law relation between the q-order RMS is numerical identified as the q-order Hurst exponent. In Section “The Multifractal Spectrum of Time Series,” several multifractal spectra are computed from the q-order Hurst exponent. In Section “A Direct Estimation of the Multifractal Spectrum,” an alternative version of MFDA is introduced that compute the multifractal spectrum directly from the local fluctuations without the q-order overall RMS.

Before starting the introduction of MFDA, the reader can type load fractaldata.mat in the Matlab command window to access the time series, whitenoise, monofractal, and multifractal. These time series will be used as test series in the rest of Section “Multifractal Detrended Fluctuation Analysis in Matlab” while constructing MFDFA piece-by-piece. The construction of the Matlab code for MFDFA is represented as Matlab code boxes within the text. The main intention of these Matlab code boxes is that the reader should paste the Matlab code into the Matlab command window while reading the tutorial. Figures are accessed by typing the plot command at the end of the Matlab code boxes. The reader can access all Matlab code boxes by opening the m-file Matlabcodes contained in the “Introduction to MFDA” folder.

NOISE AND RANDOM WALK LIKE VARIATION IN A TIME SERIES

The red traces in Figure 1 show an ordinary random walk (lower panel), a monofractal random walk (middle panel) and a multifractal random walk (upper panel). The fractal property of these random walks is reflected by their picture-in-picture similarity as illustrated in the upper panel of Figure 1. Small “hills” and “valleys” with similar structure appear when you zoom on the large “hills” and “valleys” of the random walk. The DFA is employed to time series with a random walk like structure (Peng et al., 1995). However, most biomedical time series have fluctuations that are more similar to the increments of the random walks (see the blue traces in Figure 1). If the biomedical time series has the noise like structure of the blue traces in Figure 1, it should be converted to a random walk like time series before employing DFA. Noises can be converted to random walks by subtracting the mean value and integrate the time series. Time series whitenoise, monofractal, and multifractal are all noise like time series and are converted to random walk like time series by Matlab code 1 below:

Matlab code 1:

RM1=cumsum(whitenoise-mean(whitenoise));
RM2=cumsum(monofractal-mean(monofractal));
RM3=cumsum(multifractal-mean(multifractal));

Type plot1 in the command window to access Figure 1.

COMPUTING THE ROOT-MEAN-SQUARE VARIATION OF A TIME SERIES

A conventional analysis of variation in biomedical time series is to compute the average variation as a RMS. The reader can use Matlab
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FIGURE 1 | The time series multifractal (upper panel), monofractal (middle panel), and white noise (lower panel) are shown as blue traces. They are examples of noise like time series used in the present tutorial. All time series contain 8000 data samples each where the sample numbers are indicated by the horizontal axis. Matlab code 1 converts the noises (blue traces) to random walks (red traces) that have a picture-in-picture similarity (subplot in the upper panel). Notice that the time series multifractal has distinct periods with small and large fluctuations in contrast to time series monofractal and white noise. The aim of this section is to introduce MFDFA that quantify the structure of fluctuations within the periods with small and large fluctuations.

code 2 below to compute RMS for the time series whitenoise, monofractal, and multifractal:

Matlab code 2:
```
RMS_ordinary=sqrt(mean(whitenoise.^2));
RMS_monofractal=sqrt(mean(monofractal.^2));
RMS_multifractal=sqrt(mean(multifractal.^2));
```

Type plot2 in the Matlab command window to access Figure 2.

Figure 2 illustrates that the average amplitude of variation (i.e., RMS) is equal for all three time series, whitenoise, monofractal, and multifractal, even though they have quite different structures. MFDFA will be able to distinguish between these structures as we will see in the sections below.

LOCAL ROOT-MEAN-SQUARE VARIATION IN THE TIME SERIES

The multifractal time series in the upper panel have local fluctuations with both large and small magnitudes. RMS in Matlab code 2 can be computed for segments of the time series to differentiate between the magnitudes of the local fluctuations. A simple procedure is to cut the time series into equal-sized non-overlapping segments and compute a local RMS for each segment. This can be done by Matlab code 3 below and is the core procedure of MFDFA:

Matlab code 3:
```
X=cumsum(multifractal-mean(multifractal));
X=transpose(X);
scale=1000;
m=1;
segments=floor(length(X)/scale);
for v=1:segments
    Idx_start=((v-1)*scale)+1;
    Idx_stop=v*scale;
    Index{v}=Idx_start:Idx_stop;
    X_Idx=X(Index{v});
    C=polyfit(Index{v},X(Index{v}),m);
    fit{v}=polyval(C,Index{v});
    RMS{1}(v)=sqrt(mean((X_Idx-fit{v}).^2));
end
```

Type plot3 in Matlab command window to access Figure 3.

The first line of Matlab code 3 converts the noise like time series, multifractal, to a random walk like time series X (i.e., Matlab code 1). The third line of Matlab code 3 set the parameter scale that defines the sample size of the non-overlapping segments in which the local RMS, RMS{1}, are computed. The fifth line is the number of segments that the time series X can be divided into where length(X) is the sample size of time series X. Thus, segments = 8 when length(X) = 8000 and scale = 1000. The sixth to fourteenth line is a loop that computes the local RMS around a trend fit{v} for each segment by...
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FIGURE 2 | The time series multifractal (upper panel), monofractal (middle panel), and whitenoise (lower panel) with zero average (red dashed lines) and ±1 RMS (red solid lines). All time series have equal RMS = 1, but quite different structure. RMS is only sensitive to differences in the amplitude of variation and not differences in the structure of variation. Notice the different scaling for the vertical axis of the multifractal time series.

upating the time Index (see red $v$ arguments in Matlab code 3). In the first loop $v = 1$, the Index{1} goes from sample 1 to sample 1000. In the second loop $v = 2$, the Index{2} goes from sample 1001 to sample 2000. In the final loop $v = 8$, the Index{8} goes from sample 7001 to 8000.

LOCAL DETRENDING OF THE TIME SERIES

Slow varying trends are present in biomedical time series and detrending of the signal is therefore necessary to quantify the scale invariant structure of the variation around these trends. In Matlab code 3, a polynomial trend fit{$v$} is fitted to $X$ within each segment $v$ (see blue command lines in Matlab code 3). The first blue command line is the parameter $m$ that defines the order of the polynomial. The polynomial trend are linear when $m = 1$, quadratic when $m = 2$, and cubic when $m = 3$ (see Figures 3A–C). The first blue command line within the loop defines the polynomial coefficients $C$ used to create the polynomial trend fit{$v$} of each segment (see dashed red lines in Figure 3). The local fluctuation, RMS{1}($v$), is then computed for the residual variation, $X(\text{Index}{v}) - \text{fit}{v}$, within each segment $v$. The local fluctuation, RMS{1}($v$), is illustrated in Figure 3 as the distance between the red dashed trends and the red solid lines.

MONOFRACTAL DETRENDED FLUCTUATION ANALYSIS

In the DFA the variation of the local RMS{1} are quantified by an overall RMS ($F$) in Matlab code 4 below:

Matlab code 4:
\[
F = \sqrt{\text{mean}(\text{RMS}{1} .* \text{RMS}{1})};
\]

The fast changing fluctuations in the time series $X$ will influence the overall RMS, $F$, for segments with small sample sizes (i.e., small scale) whereas slow changing fluctuations will influence $F$ for segments with large sample sizes (i.e., large scale). The scaling function, $F$, should therefore be computed for multiple segments sizes (i.e., multiple scales) to emphasize both fast and slow evolving fluctuations that influence the structure of the time series. The scaling function, $F(ns)$, can be computed for multiple scales by including Matlab code 3 and 4 within a new loop marked as red command lines and arguments ns below:

Matlab code 5 Part 1 of DFA
\[
X = \text{cumsum}([\text{multifractal}-\text{mean}([\text{multifractal}])]);
X = \text{transpose}(X);
scale=[16,32,64,128,256,512,1024];
m=1;
\]
\[
\text{for } ns=1:\text{length}(\text{scale}),
\text{segments}(ns)=\text{floor}(\text{length}(X)/\text{scale}(ns));
\text{for } v=1:\text{segments}(ns),
\text{Idx_start}=((v-1)*\text{scale}(ns))+1;
\text{Idx_stop}=v*\text{scale}(ns);
\text{Index}{v,ns}=\text{Idx_start} : \text{Idx_stop};
X_{,ns}=X(\text{Index}{v,ns});
C=\text{polyfit}(\text{Index}{v,ns},X(\text{Index}{v,ns}),m);
\text{fit}{v,ns}=\text{polyval}(C,\text{Index}{v,ns});
\text{end}
\text{end}
\]

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FIGURE 3 | The computation of local fluctuations, \( \text{RMS}_1 \), around linear (A), quadratic (B), and cubic trends (C) by Matlab code 3 \( (m = 1, 2, \text{ and } 3) \), respectively. The red dashed line is the fitted trend, \( \text{fit}_v \), within eight segments of sample size 1000. The distance between the red dashed trend and the solid red lines represents \( \pm 1 \text{RMS}_1 \). The local fluctuation, \( \text{RMS}_1 \), around trends is the basic “building block” of the detrended fluctuation analysis.

\[
\text{RMS}_{\text{ns}}(v) = \sqrt{\text{mean}((X_{\text{Idx}}-\text{fit}_v{\text{ns}})^2)};
\]

\[
F_{\text{ns}} = \sqrt{\text{mean}(\text{RMS}_{\text{ns}})^2};
\]

Type \texttt{plot4} in the Matlab command window to access Figure 4.

In the first red command line, a vector with multiple segment sizes (i.e., scales) is set by the reader. In the second red command line, a loop is initiated where Matlab code 3 is computed from the smallest to the largest scale. The segment sample size, \( \text{scale}(\text{ns}) \), are updated by the red index \( \text{ns} \). The local fluctuation, \( \text{RMS}(\text{ns}) \), is a set of vectors where each vector have a length equal to the number of segments [i.e., \( \text{segments}(\text{ns}) \)]. In the first loop for \( \text{ns} = 1 \), the local fluctuation \( \text{RMS}[1] \) is a vector of local RMS values computed for 500 segments [i.e., \( \text{segments}(1) \)] each containing 16 samples [i.e., \( \text{scale}(1) \)]. In the last loop for \( \text{ns} = 7 \), the local fluctuation \( \text{RMS}[7] \) is a vector with local RMS values computed for seven segments [i.e., \( \text{segments}(7) \)] each containing 1024 samples [i.e., \( \text{scale}(7) \)]. In the last command line, the scaling function (i.e., overall RMS), \( F_{\text{ns}} \), are computed for multiple scales by Matlab code 4. Figure 4 illustrates the local fluctuations, \( \text{RMS}(\text{ns}) \), and the overall RMS, \( F_{\text{ns}} \), for multiple scales.

DFA indentifies the monofractal structure of a time series as the power law relation between the overall RMS (i.e., \( F \) in Matlab code 4) computed for multiple scales (i.e., \( \text{scale} \) in Matlab code 5). The power law relation between the overall RMS is indicated by the slope (\( H \)) of the regression line (\( \text{RegLine} \)) computed by Matlab code 6 below:

\[
C = \text{polyfit}(|\log_2(\text{scale})|,|\log_2(F)|,1);
H = C(1);\]

\[\text{RegLine} = \text{polyval}(C, \log_2(\text{scale}))\];

Type \texttt{plot5} in Matlab command window to access Figure 5.

The slope, \( H \), of the regression line, \( \text{RegLine} \), is called the Hurst exponent (Hurst, 1951). The Hurst exponent defines the monofractal structure of the time series by how fast the overall RMS, \( F \), of local fluctuations, \( \text{RMS} \), grows with increasing segment sample size (i.e., \( \text{scale} \)). Figure 5 shows that the overall RMS, \( F \), of local fluctuations, \( \text{RMS} \), is growing faster with the segment sample size for the monofractal and multifractal time series compared with whitenoise time series. The larger Hurst exponent, \( H \), is visually seen as more slow evolving variations (i.e., more persistent structure) in monofractal and multifractal time series compared with whitenoise. Figure 6 illustrates that the Hurst exponents defines a continuum between a noise like time series and a random walk like time series. The Hurst exponent will be in the interval between 0 and 1 for noise like time series whereas above 1 for a random walk like time series. A time series has a long-range dependent (i.e., correlated) structure when the Hurst exponent is in the interval 0.5–1 and an anti-correlated
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FIGURE 4 | The local fluctuations, $RMS_{ns}$ (blue lines), computed by Matlab code 5 for segments with multiple segment sizes (i.e., scale). The scaling function $F_{ns}$ is the overall RMS (red line) of the local fluctuation $RMS_{ns}$. Notice that $F_{ns}$ decreases on smaller scales.

FIGURE 5 | The plot of overall RMS (i.e., $F$ in Matlab code 5) versus the segment sample size (i.e., $scale$ in Matlab code 5) where both $F$ and $scale$ are represented in log-coordinates. The scale invariant relation is indicated by the slope, $H$, of the regression lines, RegLine, computed by Matlab code 6. The slope, $H$, is a power law exponent called the Hurst exponent because $F$ and $scale$ are represented in log-coordinates. Notice that both the monofractal and multifractal time series have more apparent slow fluctuations compared to white noise indicated by larger amplitudes of the overall RMS on the larger scales.
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FIGURE 6 | The range of Hurst exponents defines a continuum of fractal structures between white noise \((H = 0.5)\) and Brown noise \((H = 1.5)\). The pink noise \(H = 1\) separates between the noises \(H < 1\) that have more apparent fast evolving fluctuations and random walks \(H > 1\) that have more apparent slow evolving fluctuations. The examples monofractal (red trace) and whitenoise (turquoise trace) used in the present tutorial are both noise like time series. The long-range dependent structure of most biomedical signals is located within the illustrated continuum of fractal structures.

structure when the Hurst exponent is in the interval 0–0.5. The time series has an independent or short-range dependent structure in the special case when the Hurst exponent is equal to 0.5. According to Figure 5, time series whitenoise has a time independent structure with Hurst exponent close to 0.5 whereas monofractal, and multifractal has a long-range dependent structure with Hurst exponent between 0.7 and 0.8. The reader should notice that short-range dependent processes can mimic the scale invariance in Figure 5 for certain scaling ranges (cf. Gao et al., 2006).

MULTIFRACTAL DETRENDED FLUCTUATION ANALYSIS OF TIME SERIES

The structure of the monofractal and multifractal time series are different even though they have similar overall RMS and slopes \(H\) in Figure 5. The multifractal time series have local fluctuations with both extreme small and large magnitudes that is absent in the monofractal time series. The absence of fluctuations with extreme large and small magnitudes results in a normal distribution for the monofractal time series whereas the multifractal has a long-range dependent structure with Hurst exponent between 0.7 and 0.8. The q-order statistical moments should be considered. Thus, it’s necessary to extend the overall RMS in the monofractal DFA (i.e., \(F\) in Matlab code 4) to the following q-order RMS of the multifractal DFA (\(F_q\) in Matlab code 7 below):

Matlab code 7:

```matlab
q=[-5,-3,-1,0,1,3,5];
for nq=1:length(q),
    qRMS{1}=RMS{1}.'^{q(nq)};
    Fq(nq)=mean(qRMS{1}).'^(1/q(nq));
end
Fq(q==0)=exp(0.5*mean(log(RMS{1}.'^2)));
```

Type `plot7` in the Matlab command window to access Figure 7.

The first command line in Matlab code 7 defines a set of q-orders from \(-5\) to 5. The second line initiates a loop that computes the overall q-order RMS, \(F_q(nq)\), from negative to positive q’s (see the red arguments \(nq\)). The q-order weights the influence of segments with large and small fluctuations, \(RMS\{1\}\), based on the second order statistics of the overall RMS (i.e., \(F\) in Matlab code 4). In the multifractal time series, local fluctuation, \(RMS\{ns\}\{v\}\), will be extreme large magnitude for segments \(v\) within the time periods of large fluctuations and extreme small magnitude for segments \(v\) within the time periods of small fluctuations. Consequently, the multifractal time series are not normal distributed and all q-order statistical moments should to
FIGURE 7 | An illustration of qRMS{1} computed by Matlab code 7.

qRMS{1} is the q-order of the local fluctuations (i.e., RMS{1}) and are the building block of the overall q-order RMS (i.e., Fq in Matlab code 7). qRMS{1} is represented for the monofractal (green traces) and multifractal (blue traces) time series. The negative q-order (q = −3 and −1) amplifies the segments in the multifractal time series with extreme small RMS{1} whereas positive q-order (q = 3 and 1) amplifies the segments with extreme large RMS{1}. Notice that q = −3 and q = 3 amplify the small and large variation, respectively, more than q = −1 and q = 1. Notice also that the monofractal time series has no segments with extreme large or small fluctuations and, thus, no peaks in qRMS{1}. The overall q-order RMS is able to distinguish between the structure of small and large fluctuations and, consequently, between the monofractal and multifractal time series.

The segments with extreme large RMS{1} are neutral to influence of segments with small and large RMS{1}. Notice that the last line of Matlab code 7 redefines the special case q(nq) = 0 because 1/0 goes to infinity [i.e., 1/q(q == 0) = inf in Matlab]. The reader should also notice that Fq(q == 2) are equal to second order statistics F in Matlab code 4 because sqrt(x) = x^(1/2) in Matlab. The monofractal DFA in Matlab code 5 can now be extended to a MFDFA by simply changing Matlab code 4 to Matlab code 7 in the last line of Matlab code 5. This change is highlighted with red command lines in Matlab code 8 below:

Matlab code 8 Part 1 of MFDFA

X=cumsum(multifractal-mean(multifractal));
X=transpose(X);
scale=[16,32,64,128,256,512,1024];
q=[-5,-3,-1,0,1,3,5];
m=1;
for ns=1:length(scale),
    segments(ns)=floor(length(X)/scale(ns));
    for v=1:segments(ns),
        Index=((((v-1)*scale(ns))+1):(v*scale(ns)));
        C=polyfit(Index,X(Index),m);
        fit=polyval(C,Index);
        RMS{ns}(v)=sqrt(mean((X(Index)-fit).^2));
    end
    for nq=1:length(q),
        qRMS{nq,ns}=RMS{ns}.^q(nq);
        Fq(nq,ns)=mean(qRMS{nq,ns}).^(1/q(nq));
    end
    Fq(q==0,ns)=exp(0.5*mean(log(RMS{ns}.^2)));
end

The relationship between Matlab code 8 and the mathematical equations used to introduce the MFDFA in Kantelhardt et al. (2002) are given below:

Eq. 1 in Kantelhardt et al. (2002):

\[ Y(i) = \sum_{k=1}^{N_i} x_k - (x) \]

\[ x(i) \]

\[ (x) \]

The number \( N_i \) of non-overlapping segments:

\[ N_i = \text{int}(N/s) \]

\[ N \]

\[ s \]
THE MULTIFRACTAL SPECTRUM OF TIME SERIES

The $q$-order Hurst exponent $H_q$ is only one of several types of scaling exponents used to parameterize the multifractal structure of time series. The typical procedure in the literature of MFDFA is to first convert $H_q$ to the $q$-order mass exponent (t$q$) and thereafter convert t$q$ to the $q$-order singularity exponent (h$q$) and $q$-order singularity dimension (D$q$) (Kantelhardt et al., 2002). The plot of h$q$ versus D$q$ is referred to as the multifractal spectrum (see Figure 9C). The $q$-order mass exponent t$q$ can be computed from $H_q$ by the Matlab code 10 below (see Figure 9B):

Matlab code 10 Part 3 of MFDFA

t$q$=$H_q$.*$q$-1;

Eq. 13 in Kantelhardt et al. (2002)

The mass exponent t$q$ is used to compute the $q$-order singularity exponent (h$q$) and the $q$-order singularity dimension (D$q$) by Matlab code 11 below (see upper right Figure 9):

Matlab code 11 Part 4 of MFDFA

h$q$=diff(t$q$)./(q(2)-q(1));
D$q$=(q(1):end-1).‘*h$q$‘-t$q$‘(1:end-1);

Equation 15 in Kantelhardt et al. (2002)

Type plot9 in the Matlab command window to access Figure 9.

The monofractal and white noise time series has a mass exponent t$q$ with a linear $q$-dependency. The linear $q$-dependency of t$q$ leads to a constant h$q$ of these time series because h$q$ is the tangent slope of t$q$ (see the first command line in Matlab code 11). The constant h$q$ reduces the multifractal spectrum to a small arc for the monofractal and white noise time series (see Figure 9C). In contrast, the multifractal time series has mass exponents t$q$ with a curved $q$-dependency and, consequently, a decreasing singularity exponent h$q$. The resulting multifractal spectrum is a large arc where the difference between the maximum and minimum h$q$ are called the multifractal spectrum width (see arrow in Figure 9C).

The reader should notice that the $q$-order singularity exponent h$q$ and corresponding dimension D$q$ computed by Matlab code 11 are referred to as a and f(a) in Kantelhardt et al. (2002), but as $h$ and $D(h)$ in other literature (e.g. Ihlen and Vereijken, 2010). Furthermore, the singularity dimension can be confused with the generalized dimension and the box counting dimension that is other ways to parameterize the multifractal structure of time series (see Equation 14 in Kantelhardt et al., 2002). The Hurst exponent defined by the monofractal DFA represents the average fractal structure of the time series as illustrated in Figure 6 and is closely related to the central tendency of multifractal spectrum. The deviation from average fractal structure for segments with large and small fluctuations is represented by the multifractal spectrum width. Thus, each average fractal structure in the continuum of Hurst exponents (see Figure 6) has a new continuum of multifractal spectrum widths that represents...
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FIGURE 8 | q-order RMS $F_q(nq,:)$ and corresponding regression line $q\text{RegLine}[nq]$ computed by MFDFA (i.e., Matlab code 8 and 9) for time series multifractal (A), monofractal (B), and whitenoise (C). (A) The scaling functions $F_q$ (blue dots) and corresponding regression slopes $H_q$ (blue dashed lines) are $q$-dependent. (B,C) The scaling functions $F_q$ (red and turquoise dots) and regression slope $H_q$ (red and turquoise dashed lines) are $q$-independent.

(D) The $q$-order Hurst exponent $H_q$ for the time series multifractal (blue trace), monofractal (red trace) and whitenoise (turquoise trace) where the colored dots represents the slopes $H_q$ for $q = -3, -1, 1, 3$ illustrated in (A–C). Notice that the intercept of $H_q$ for multifractal and monofractal time series (intercept between blue and red trace in (D)) are close to $q = 2$. This intercept reflects the similarity between their overall RMS, $F$, in Figure 5.

the deviations from the average fractal structure (see Figure 10). Furthermore, the shape of the multifractal spectrum in Figure 10 does not have to be symmetric. The multifractal spectrum can also have either a left or a right truncation that originate from a leveling of the $q$-order Hurst exponent for negative or positive $q$’s, respectively (see Figure 11). The leveling of $q$-order Hurst exponent reflects that the $q$-order RMS is insensitive to the magnitude of the local fluctuations. The multifractal spectrum will have a long left tail when the time series have a multifractal structure that is insensitive to the local fluctuations with small magnitudes (see upper Figure 11). In contrast, the multifractal spectrum will have a long right tail when the time series have a multifractal structure that is insensitive to the local fluctuations with large magnitudes (see lower Figure 11). Another continuum of right and left truncations exists for each multifractal spectrum width in the continuum illustrated in Figure 10. Thus, the width and shape of the multifractal spectrum is able to classify a wide range of different scale invariant structures of biomedical time series.

A DIRECT ESTIMATION OF THE MULTIFRACTAL SPECTRUM

The transformation of the $q$-order Hurst exponent $H_q$ to the mass exponent $t_q$ and, finally, to the multifractal spectrum $D_q$ and $h_q$ is stated as a “just-the-way-it-is” argument in the above section without mathematical details. The reader might ask at this point why one should define and interpret the multifractal spectrum $D_q$ and $h_q$ and not only $H_q$ that are directly estimated by Matlab code 8 and 9. Estimating the multifractal spectrum directly from the local fluctuation, will answer this question and give a less abstract definition of the multifractal spectrum. A local Hurst exponent can be defined directly from, $RMS\{ns\}(v)$, for each time instant $v$. The local Hurst exponent estimated for a multifractal time series will fluctuate in time in contrast to the time independent Hurst exponent estimated by the monofractal DFA (see Matlab code 5 and 6; Figure 5). The temporal variation of the local Hurst exponent can be summarized in a probability distribution and the multifractal spectrum is just the normalized probability distribution in log-coordinates. Thus, the width and shape of the multifractal spectrum reflect the temporal variation of the local Hurst exponent or, in other words, the temporal variation in the local scale invariant structure of the time series. In order to estimate the local Hurst exponent, the local fluctuation, $RMS\{ns\}(v)$, has to be defined within a translating segment centered at sample $v$ instead of within non-overlapping segments. Thus, Matlab code
FIGURE 9 | Multiple representations of multifractal spectrum for multifractal (blue traces), monofractal (red traces), and white noise (turquoise trace) time series. (A) q-order Hurst exponent $H_q$ computed in Matlab code 9. (B) Mass exponent $t_q$ computed in Matlab code 10. (C) Multifractal spectrum of $D_q$ and $h_q$ (upper right panels) computed in Matlab code 11 and plotted against each other. The arrow indicates the difference between the maximum and minimum $h_q$ that are called the multifractal spectrum width. Notice that the constant $H_q$ for monofractal and white noise times series leads to a linear $t_q$ that further leads to a constant $h_q$ and $D_q$ that, finally, are joined to become only tiny arcs in (C).

8 has to be modified to Matlab code 12 below (see red command lines):

Matlab code 12  Part 1 of MFDFA2

X=cumsum(multifractal-mean(multifractal));
X=transpose(X);
scale_small=[7,9,11,13,15,17];
halfmax=floor(max(scale_small)/2);
Time_index=halfmax+1:length(X)-halfmax;
m=1;
for ns=1:length(scale_small),
halfseg=floor(scale_small(ns)/2);
    for v=halfmax+1:length(X)-halfmax;
        T_index=v-halfseg:v+halfseg;
        C=polyfit(T_index,X(T_index),m);
        fit=polyval(C,T_index);
        RMS{ns}(v)=sqrt(mean((X(T_index)-fit).^2));
    end
end
(The reader must be patient because this code might take a couple of minutes)

The first red command line defines a vector of small segment sizes (i.e., scale_small) where the segment sizes increases with two samples. This increase of two samples is necessary to align the center of segments according to the Time_index. The third red line set the Time_index for the local fluctuation, $\text{RMS}\{\text{ns}\}(v)$, that exclude the halfmax number of samples at the start and the end of the time series (see second red command line). Then a loop are initiated for each segment size where the local fluctuations, $\text{RMS}\{\text{ns}\}(v)$, are computed for a translating segment centered at sample $v=\text{Time\_index}$. The translating segment includes the local samples that are updated by $T\_\text{index}$ (see last red command line). The local Hurst exponent ($h_t$) can now be computed from the local fluctuation, $\text{RMS}\{\text{ns}\}$, by the Matlab code 13 below:

Matlab code 13  Part 2 of MFDFA2

C=polyfit(log2(scale),log2(Fq(q==0,:)),1);
Regfit=polyval(C,log2(scale_small));
maxL=length(X);
for ns=1:length(scale_small),
    RMSt=RMS{ns}(Time_index);
    resRMS{ns}=Regfit(ns)-log2(RMSt);
    logscale(ns)=log2(maxL)-log2(scale_small(ns));
    Ht{ns,:}=resRMS{ns}/logscale(ns)+Hq(q==0);
end

Type plot12 in the Matlab command window to access Figure 12.

The first two command line defines the regression line $\text{Regfit}$ equal to the regression line $\text{qRegLine}\{q==0\}$ computed by Matlab code 8. $\text{Regfit}$ represents the center of the spread of local $\text{RMS}$ and are the regression line of the overall $q$-order $\text{RMS}$, $Fq(q==0,:)$.

A loop for each scale $\text{ns}$ computes
FIGURE 10 | Illustration of a continuum of multifractal time series with the same $q$-order Hurst exponent for $q = 2$ but with different multifractal spectrum width [compare vertical axis of the (A) and the arrow in the (B)]. Notice the growth of structural differences between the periods with small and large fluctuations as the multifractal spectrum width become larger.

FIGURE 11 | Illustration of multifractal spectra with a right truncation (upper right panel) and a left truncation (upper left panel). These truncations originate from the leveling of the $q$-order Hurst exponents for negative $q$'s (upper right panel) and positive $q$'s (upper left panel), respectively.
the residual fluctuation \( \text{resRMS}_{\text{ns}} \) of \( \log 2 (\text{RMS}_{\text{ns}}) \) around the regression line \( \text{Regfit} \) for each sample \( v \) of the time series. In Figure 12B, the differences between the overall \( q \)-order RMS, \( F_q \), converge toward each other with increasing scale. This convergence is inevitable for multifractal variation by the linear relationship between \( F_q \) for all \( q \)-order and the assumption of monotonically decreasing \( q \)-order Hurst exponent, \( H_q \) (see Figure 8D). The same convergence is seen for the local RMS in Figure 12A and is used to estimate the local Hurst exponents, \( H_{t(ns,:)} \). \( H_{t(ns,:)} \) is estimated as the slope of the line from local RMS in log-coordinates to the endpoint of the regression line, \( \text{Regfit} \), at the largest scale, \( \text{maxL} \) (see Figure 12). Consequently, \( H_{t(ns,:)} \) are obtained by dividing the residuals \( \text{resRMS}_{\text{ns}} \) by \( \text{logscale} \) (i.e., the difference between maximal scale \( \text{maxL} \) and the \( \text{scale}(\text{ns}) \) in log-coordinates) and adding the slope \( H_q = 0 \) of regression line, \( \text{Regfit} \) (see Figure 12A). Figure 13A illustrates the local Hurst exponent \( H_{t(ns,:)} \) for \( ns = 5 \) (i.e., \( \text{scale}(\text{ns}) = 15 \)) for the multifractal, monofractal, and whitenoise time series. The local Hurst exponent \( H_{t(ns,:)} \) has larger variation for the multifractal time series compared to the monofractal and whitenoise time series. The small \( H_{t(ns,:)} \) in the periods of the multifractal time series with local fluctuations of large magnitudes (i.e., large \( \text{RMS}_{\text{ns}} \)) reflects the noise-like structure of the local fluctuations (see red dashed lines in Figure 13A). In contrast, the larger \( H_{t(ns,:)} \) in the periods with local fluctuations of small magnitudes (i.e., small \( \text{RMS}_{\text{ns}} \)) reflects the random walk-like structure of the local fluctuations (see black dashed lines in Figure 13A). The local Hurst exponent \( H_{t} \) in periods with fluctuations of small and large magnitudes is therefore consistent with the \( q \)-order Hurst exponent \( H_q \) for negative and positive \( q \)'s, respectively. The advantage of local Hurst exponent \( H_{t} \) compared with \( q \)-order Hurst exponent \( H_q \) is the ability of \( H_{t} \) to identify the time instant of structural changes within the time series. In studies where the physiological phenomenon is perturbed at some time instant \( v \), the local Hurst exponent \( H_{t(ns,v)} \) can identify how this perturbation affects the local scale invariant structure of the biomedical time series. The temporal variation of local Hurst exponent \( H_{t} \) can be summarized in a histogram representing the probability distribution (Ph) of \( H_{t} \) (see Figure 13B). The multifractal spectrum (\( \text{Dh} \)) is defined simply...
by the log-transformation of the normalized probability distribution (Ph_norm). The probability distribution (Ph) and multifractal spectrum (Dh) are computed by Matlab code 14 below:

Matlab code 14 Part 3 of MFDFA2

\[
\begin{align*}
\text{Ht\_row} &= \text{Ht}(:,:) ; \\
\text{BinNumb} &= \text{round}(\sqrt{\text{length}(\text{Ht\_row})}) ; \\
[freq, Htbin] &= \text{hist(} \text{Ht\_row, BinNumb}) ; \\
\text{Ph} &= \text{freq} ./ \text{sum(freq)} ; \\
\text{Ph\_norm} &= \text{Ph} ./ \text{max(Ph)} ; \\
\text{Dh} &= 1 - (\log(\text{Ph\_norm}) ./ -\log(\text{mean(scale)})) ; \\
\end{align*}
\]

Type \text{plot13} in Matlab command window to access Figure 13.

The first line in Matlab code 14 convert the matrix \text{Ht} to the vector \text{Ht\_row} that are the input argument in \text{hist} function used to compute the histogram for \text{Ht\_row}. The second input argument in \text{hist} function are \text{BinNumb} that set the number of bins in the histogram. A sufficient choice for \text{BinNumb} is the square root of the sample size of \text{Ht\_row} (see the second command line). The output variables of \text{hist} function are the center of each bin \text{Htbin} and the number \text{freq} of local Hurst exponents that fall into each bin. The probability distribution \text{Ph} are computed by dividing the number \text{freq} of local Hurst exponents in each bin by the total number of local Hurst exponents, \text{sum(freq)} (see Figure 13B). The multifractal spectrum \text{Dh} are computed by first define \text{Ph\_norm} by normalizing \text{Ph} to the maximum probability \text{max(Ph)} and then divide \text{log(Ph\_norm)} by \text{–log(mean(scale))} (cf. Struzik, 2000; Scafetta et al., 2003). The multifractal spectrum \text{Dh} are therefore directly related to the distribution \text{Ph} of the local fractal structure of the time series. The distribution \text{Ph} is the same for the local scale invariant structure of the time series as the conventional probability distribution are for the local amplitudes of the time series. The present state of the physiological system is connected to both past and future states that influence the local scale invariant structure of time series. Thus, distribution \text{Ph} and the multifractal spectrum \text{Dh} of biomedical time series might reflect important properties of the self-regulation of physiological processes.

THE BEST PRACTICE OF MULTIFRACTAL DETRENDED FLUCTUATION ANALYSIS

The MFDFA introduced piece-by-piece in Section “Multifractal Detrended Fluctuation Analysis in Matlab” can be combined into two Matlab function \text{MFDFA1} and \text{MFDFA2}, respectively:
Matlab functions for MFDFA
Matlab code 8 to 11:

```
[Hq,tq,hq,Dq,Fq]=MFDFA1(signal,scale,q,m,Fig);
```
Matlab code 12 to 14:

```
[Ht,Htbin,Ph,Dh]=MFDFA2(signal,scale,m,Fig);
```

Type help MFDFA1 or help MFDFA2 in the Matlab command window to access the definition of the input and output variables. The help functions provide examples for the employment of MFDFA1 and MFDFA2 to time series.

The main aim of Section “The Best Practice of Multifractal Detrended Fluctuation Analysis” is to guide the application of MFDFA1 and MFDFA2 to biomedical time series. In Section “Multifractal Detrended Fluctuation Analysis in Matlab” the readers has gained insight into the construction of MFDFA1 and MFDFA2 and this insight will help them to avoid potential pitfalls in the application of MFDFA1 and MFDFA2. The best practice of MFDFA1 and MFDFA2 has several steps. First, the structure of biomedical time series must be similar to noise before employing MFDFA1 and MFDFA2 (see blue traces in Figure 1). Section “Random Walk or Noise Like Time Series?” introduces conversions to make the biomedical time series similar to a noise like time series. Secondly, the local fluctuations within the biomedical time series cannot be close to zero. Section “Local Fluctuations Close to Zero?” discusses possible origins for local fluctuations close to zero and possible solutions to this problem. Thirdly, the biomedical time series must be scale invariant within the predefined range of scales. Section “Is the Time Series Scale Invariant?” discusses the general assumption of a scale invariant time series as input in MFDFA1 and MFDFA2. Fourth, the input parameters scale, q, and m in MFDFA1 and MFDFA2 must be sufficiently defined for each biomedical time series. Section “How to Set the Input Parameters Scale, q, and m in MFDFA1 and MFDFA2” introduces guidelines for the optimal parameter setting. Finally, Section “Other Multifractal Analysis” lists other multifractal analyses where results can be compared to results from MFDFA1 and MFDFA2.

**Random Walk or Noise Like Time Series?**

MFDFA1 and MFDFA2 have the best performance when signal are a noise like time series. However, it can be difficult according to Figure 6 to visually differentiate between random walk and noise like time series. A possible solution suggested by Eke et al. (2002) is to run a monofractal DFA (i.e., Matlab code 5 and 6) before running MFDFA1 and MFDFA2. The time series are noise like if Hurst exponent H is between 0.2 and 0.8. In this case, MFDFA1 and MFDFA2 can be employed directly without transformation of the time series. However, the time series are random walk like when H is between 1.2 and 1.8. In these cases, the time series should either be differentiated before entering the MFDFA1 or MFDFA2 or the conversion to random walk in the first line of Matlab code 8 and 12 should be eliminated. If the time series are random walk like +1 should be added to the output variables Hq,hq, and tq from MFDFA1 and Ht and Htbin from MFDFA2. Table 1 summarize the categories of the Hurst exponent estimated by a monofractal DFA with corresponding conversion of the biomedical time series that should be performed before entering it into MFDFA1 and MFDFA2.

| Hurst exponent (H) | Conversion | Adjustment of Hq and Ht |
|-------------------|------------|-------------------------|
| <0.2              | signal=cumsum(X-mean(X)) | −1 |
| 0.2–0.8           | No conversion | 0 |
| 0.8–1.2           | No conversion | 0 |
| 1.2–1.8           | signal=diff(X) | +1 |
| >1.8              | signal=diff(diff(X)) | +2 |

**LOCAL FLUCTUATIONS CLOSE TO ZERO?**

The local fluctuation in the time series is defined as a local RMS within both MFDFA1 and MFDFA2. Large error appears in the multifractal spectrum when RMS is close to zero because both log2(Fq) for negative q’s in Matlab code 8 and log2(RMS) in Matlab code 12 becomes infinitely small (i.e., -inf in Matlab). Extreme large Hq will be present for negative q’s as output from MFDFA1. Equivalently, extreme large outliers in Ht will be present as output from MFDFA2. Consequently, local RMS close to zero will lead to large right tails for the multifractal spectrum. The problem of segments with RMS close to zero can be solved by eliminating RMS below a certain threshold (eps). The threshold eps can be set to the precision of the measurement device that is recording the biomedical time series. As an example, the measurement of the inter-beat intervals of the human heart is measured below a certain threshold (eps). Therefore, extreme outliers in Ht will be present as output from MFDFA2. Consequently, local RMS close to zero will lead to large right tails for the multifractal spectrum.

There are two main reasons why the local fluctuation RMS becomes zero in segments with small sample sizes. First, the polynomial trend fits of the time series can be overfitted in segments with small sample sizes (i.e., small scale). An overfitted trend will be similar to the time series and cause the residual fluctuations, RMS, to be close to zero. The sample size of the smallest segment (i.e., scale) should therefore be much larger than the polynomial order m to prevent an overfitted trend. Secondly, the biomedical time series might be smooth with little apparent variation and therefore similar to the polynomial trend even for low order m. In these cases, the value of the smallest scales should be raised and the scale invariance checked carefully (see “Is the Time Series Scale Invariant?” below).

**IS THE TIME SERIES SCALE IN Variant?**

The application of both Matlab function MFDFA1 and MFDFA2 assumes that the biomedical time series are scale invariant. This means that plot(log2(scale),log2(Fq)) yield a linear relationship between log2(scale) and log2(Fq) (see Figure 8). The q-order Hurst exponent Hq should not be estimated by a linear regression if the relationship between log2(scale) and log2(Fq) is curved or S-shaped. Consequently, the first output from MFDFA1 to be visually checked.

---

**Table 1 | Conversions of the biomedical time series \( x \) and adjustment of \( Hq \) and \( Ht \).**

| Hurst exponent (H) | Conversion | Adjustment of \( Hq \) and \( Ht \) |
|-------------------|------------|-------------------------|
| <0.2              | signal=cumsum(X-mean(X)) | −1 |
| 0.2–0.8           | No conversion | 0 |
| 0.8–1.2           | No conversion | 0 |
| 1.2–1.8           | signal=diff(X) | +1 |
| >1.8              | signal=diff(diff(X)) | +2 |
should be \( \text{plot}(\log_2(\text{scale}), \log_2(\text{Fq})) \). Non-linear relation in this plot might arise from several reasons. First, an insufficient order \( m \) for the polynomial detrending will yield a non-linear relationship between \( \log_2(\text{scale}) \) and \( \log_2(\text{Fq}) \) for scale invariant time series with a trend. The solution is to run \text{MFDFA1} or \text{MFDFA2} multiple times with different \( m \) and compare their \( \text{plot}(\log_2(\text{scale}), \log_2(\text{Fq})) \). Secondly, local fluctuations RMS close to zero for small scales would yield a non-linear dip in lower end of \( \text{plot}(\log_2(\text{scale}), \log_2(\text{Fq})) \). This dip can be prevented by elimination of RMS below the measurement error suggested in Section “Local Fluctuations Close to Zero?” or by choosing a larger minimum input scale. Finally and most importantly, a non-linear relationship in \( \text{plot}(\log_2(\text{scale}), \log_2(\text{Fq})) \) might originate from the fast fluctuations of the heart rate variability (Stein and Kleiger, 1999) and cause the scale invariance to break down at the smallest scales. Another example is postural sway in humans where the variation of the center of pressure has two distinct scaling regions thought to represent two distinct modes for human balance control (Collins and De Luca, 1993). One way to detect the sub-regions with scale invariance is to look for periods with approximately constant \( \log_2(\text{Fq}(q = 1,:)./\text{scale}) \) in \( \text{plot}(\log_2(\text{scale}), \log_2(\text{Fq}(q = 1,:)./\text{scale})) \) within the entire scaling range (cf. Gao et al., 2006). The scales where \( \log_2(\text{Fq}(q = 1,:)./\text{scale}) \) are no longer constant indicates the segment sizes above and below which the local fluctuations (i.e., RMS) are no longer scale invariant. These points will in many cases have phenomenological explanations and should not be ignored.

**HOW TO SET THE INPUT PARAMETERS scale, q, AND m IN MFDFA1 AND MFDFA2**

The Matlab functions \text{MFDFA1} and \text{MFDFA2} have input parameters \( \text{scale}, q \) and \( m \). The estimation of the multifractal spectrum is dependent on these parameter settings. The rest of this section gives guidelines to the parameter settings in \text{MFDFA1} and \text{MFDFA2}:

**Scale**

The input parameters \( \text{scale} \) is the multiple segment sizes for the computation of local fluctuation RMS in Matlab code 8 and 12. A minimum and maximum sample size of the segments [i.e., \( \text{min} \text{scale} \) and \( \text{max} \text{scale} \) in Matlab] has to be chosen to construct the set of scales used in \text{MFDFA1} and \text{MFDFA2}. Both statistical and phenomenological arguments exist on how to choose the minimum and maximum segment size. The statistical argument is to choose minimum and maximum segment sizes that provide a numerical stable estimation of RMS and Fq in Matlab code 8 and 12. The minimum segment sample size should be large enough to prevent error in the computation of local fluctuation RMS. The minimum segment size larger than 10 samples is a “rule of thumb” for the computation of RMS. Furthermore, the minimum sample size must be considerably larger than the polynomial order \( m \) to prevent overfitting of polynomial trend (see “Local Fluctuations Close to Zero?” above). Thus, minimum segment size of 10 samples might be too small for large trend order \( m \) (Kantelhardt et al., 2002). In \text{MFDFA1}, the maximum segment size should be small enough to provide a sufficient number of segments in the computation of Fq in Matlab code 8. A maximum segment size below 1/10 of the sample size of the time series will provide at least 10 segments in the computation of Fq in Matlab code 8. Furthermore, it’s favorable to have a equal spacing between scales when they are represented in \( \text{plot}(\log_2(\text{scale}), \log_2(\text{Fq})) \) to obtain a optimal performance of the linear regression that estimates \( q \)-order Hurst exponent \( H_q \). Equal spacing between \( \log_2(\text{scale}) \) is provided by Matlab code 15 below:

Matlab code 15:

\[
\text{scmin}=16; \\
\text{scmax}=1024; \\
\text{scres}=19; \\
\text{exponents}=	ext{linspace}(\log_2(\text{scmin}), \log_2(\text{scmax}), \text{scres}); \\
\text{scale}=	ext{round}(2.^\text{exponents});
\]

Matlab code 15 is employed before running \text{MFDFA1} where the minimum segment size, \text{scmin}, maximum segment size, \text{scmax}, and the total number of segment sizes, \text{scres}, are predefined. The segment sizes (i.e., \text{scale}) in \text{MFDFA2} should be small in order to provide a stable estimation of the probability distribution \( \text{Ph} \) and, consequently, the multifractal spectrum \( \text{Dh} \) (Scarfetta et al., 2003). The local Hurst exponent \( H_t \) for large scale will have a smooth and slow varying dynamics that are not well described by a probability distribution \( \text{Ph} \). Thus, a small scaling range like \( \text{scale}=[7,9,11,13,15,17] \) used in Matlab code 12 are preferable in \text{MFDFA2}. However, the reader should notice that the small segment sizes (i.e., \text{scale}) in \text{MFDFA2} come at the expense of a less precise estimation of the local fluctuation RMS. The imprecise estimation of RMS can be seen as measurement noise of the local Hurst exponent \( H_t \) present for the monofractal and whitenoise time series in Figure 13A. The measurement noise in \( H_t \) is represented as a distribution \( \text{Ph} \) and multifractal spectrum \( \text{Dh} \) for monofractal and whitenoise time series with a non-zero width (see Figures 13B,C).

Phenomenological argumentations are important for the choice of minimum and maximum segment sizes within the boundaries that provide numerical stable computations. For example, it is unlikely that the movement of the center of mass is faster than 10 Hz during postural sway. If ground reaction force is sampled at 200 Hz by a force plate then the minimum segment size should be larger than 200/10 Hz = 20 samples. Another example is to exclude the smallest segment sizes in heart rate variability known to be dominated by oscillations due to the respiratory frequency. Furthermore, heart rate variability operates with several ranges of scales (i.e., fluctuations with high frequency, low frequency, very low frequency, ultra low frequency) that are suggested to be influenced by different mechanisms (e.g., respiratory frequency, baroceptive responses, circadian rhythm; e.g., Stein and Kleiger, 1999). Three scale invariant sub-bands are also found in EEG signal where the Hurst exponent are able to separate between healthy subjects and epileptic subjects (Gao et al., 2011). Thus, \text{MFDFA1} can be employed to sub-bands of the scaling range in these phenomena (e.g., Makowiec et al., 2011).
### q-order

The input parameter \( q \) in MFDFA\(_1\) decides the \( q \)-order weighing of the local fluctuation \( \text{RMS} \) in Matlab code 8. The \( q \)-orders should consist of both positive and negative \( q \)-s in order to weight the periods with large and small variation in a time series. The precision of the computation of the \( q \)-order Hurst exponent \( h_q \) decreases with increasing negative and positive \( q \)-orders. This imprecision is explained by the result in Figure 7. The single segment with the smallest and largest variation \( \text{RMS} \) will tower up as a single skyscraper by increasing negative and positive \( q \)-orders, respectively, and completely dominate the scaling function \( F_q \) (i.e., overall \( q \)-order \( \text{RMS} \) in Matlab code 7). The domination of the single segments with the smallest and largest variation destabilizes \( F_q \) and leads to an increasing spread around the regression lines of \( F_q \) (see \( q = 3 \) and \(-3 \) in Figure 8A). The choice of \( q \)-orders should therefore avoid large negative and positive values because they inflict larger numerical errors in the tails of the multifractal spectrum. The stability of the computation of the multifractal spectrum is also dependent on the differences between the segments of largest and smallest variation. Time series that have large multifractal spectrum width will have large differences between the segments with the smallest and largest variation and, consequently, destabilize the computation of \( F_q \) at smaller negative and positive \( q \)-orders (compare multifractal scaling in Figure 8A with the monofractal scaling in Figure 8B). A sufficient choice of \( q \)-orders will be between \(-5 \) and \( 5 \) for most biomedical time series (Lashermes et al., 2004). The destabilization of the \( F_q \) at large negative and positive \( q \)-orders is also dependent on the sample size of the time series. Time series with large sample size will have multiple segments with extremely large and small variation whereas time series with moderate sample size will only have a single segment. Multiple segments of large and small variation would stabilize the computation of \( F_q \) for large negative and positive \( q \)-orders. There exists no consensus for the definition of a “too small” sample sizes for multifractal analyses, but the reader should interpret the result with caution when MFDFA\(_1\) and MFDFA\(_2\) are employed to time series with less than 1000 samples.

### Trend order \( m \)

In both MFDFA\(_1\) and MFDFA\(_2\), the local fluctuation \( \text{RMS} \) is computed around a polynomial trend where its shape is defined by the order \( m \). A higher order \( m \) yield a more complex shape of the trend, but might lead to overfitting for time series with small segment sizes as discussed in Section “Local Fluctuations Close to Zero?” above. Thus, \( m = 1–3 \) are probably a sufficient choice when the smallest segment sizes contains 10–20 samples. Most studies that employ DFA to biomedical time series do not report the details of the polynomial detrending. Still, the multifractal spectrum for multiple orders \( m \) should be compare to ensure that the multifractal spectrum are not influenced by non-stationary trends in the time series. The trends present in biomedical signals do not have to be of a polynomial shape but might have oscillatory or ramp-like shapes. Both MFDFA\(_1\) and MFDFA\(_2\) can be extended to include more adaptive detrending procedures like wavelet decomposition (Maninmaran et al., 2009), moving average (Carbone et al., 2004), and empirical mode decomposition (Qian et al., 2009). Furthermore, an adaptive fractal analysis is shown to perform better than the DFA with polynomial detrending when employed to biomedical time series with strong trends (Gao et al., 2011). Extensions and modification of the detrending procedure in MFDFA\(_1\) and MFDFA\(_2\) is preferable if MFDFA are employed to biomedical time series with strong trends. Matlab functions for MFDFA with other detrending procedures are available at www.ntnu.edu/imm/geri/software.

### OTHER MULTIFRACTAL ANALYSIS

The basic component of both MFDFA\(_1\) and MFDFA\(_2\) are the local fluctuation, \( \text{RMS} \). Statistical parameters other than \( \text{RMS} \) can be used to define the local fluctuation in a time series. In multifractal analyses based on wavelet transformations, the local fluctuation is defined as the convolution product between the time series and a waveform fitted within local segments of the time series (cf. Daubechies, 1992; Mallat, 1999). The results from analyses called wavelet transformation modulus maxima (Muzy et al., 1991), multifractal analysis with wavelet leaders (Jaffard et al., 2006; Werd, 2008), and gradient modulus wavelet projection (Turiel et al., 2006) can therefore be directly compared with the results from MFDFA\(_1\) and MFDFA\(_2\). In an entropy-based estimation of the multifractal spectrum, the local fluctuation is defined as the sum of the time series within the local segment relative to the total sum of the entire time series (Chhabra and Jensen, 1989). This method uses a \( q \)-order entropy function instead of a \( q \)-order \( \text{RMS} \) and estimates \( h_q \) and \( D_q \), directly, as the regression slope of the \( q \)-order entropy functions. The MFDEA has been shown to perform as well as or better than these multifractal analyses (Kantelhardt et al., 2002; O´swie˛cimka et al., 2006; Serrano and Figliola, 2009; Huang et al., 2011). However, extensions of detrending procedure in MFDFA\(_1\) and MFDFA\(_2\) should be considered when the biomedical time series contains strong oscillatory or ramp-like trends (Hu et al., 2009; Huang et al., 2011).

### SUMMARY

The multifractal spectrum reflects the variation in the fractal structure of the biomedical time series. The multifractal structure of the inter-beat intervals can identify pathological conditions of the human heart (e.g., Ivanov et al., 1999; Wang et al., 2007). The multifractal structure in neural activity can separate the activity of different brain areas and thereby guide more precise neurosurgery (Zheng et al., 2005). The present tutorial has introduced a multifractal time series analysis called MFDFA (Kantelhardt et al., 2002). MFDFA is simply based on the computation of local \( \text{RMS} \) for multiple segment sizes as illustrated in Section “Multifractal Detrended Fluctuation Analysis in Matlab.” However, special issues in Section “The Best Practice of Multifractal Detrended Fluctuation Analysis” for the best practice of MFDFA are of paramount importance when MFDFA are employed to biomedical time series. First, a monofractal DFA should be employed to ensure that the biomedical time series has a noise like structure. A conversion according to Table 1 should be made if the time series has not a noise like structure. Secondly, local fluctuation close to zero should be eliminated within MFDFA. Thirdly, the presence of scale invariance should be checked by first running MFDFA\(_1\) over a large scaling range [e.g., \( \text{scmin} = 10 \) and \( \text{acmax} = \text{length(signal)}/10 \) in Matlab] and then plot \( \log(2) \text{scale} \) against \( \log(2) \text{Fq} \). If
scale invariance is not present for the entire range, then MFDA1 can be rerun with modified input parameter scale for scale invariant sub-bands within the original scaling range. MFDA1 should be employed with a q-orders between -5 and 5 and for multiple trend orders m, MFDA2 should be employed instead of MFDA1 when the time instant for structural change in the biomedical time series is of importance or when the biomedical time series contain less than 5000 samples.

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