ABSTRACT

Multipath TCP (MPTCP) is an extension to TCP which aggregates multiple parallel connections over available network interfaces. MPTCP bases its scheduling decisions on the individual RTT values observed at the subflows, but does not attempt to perform any kind of joint optimization over the subflows. Using the MPTCP scheduler as an example, in this paper we demonstrate that exploiting cross-layer information and optimizing scheduling decisions jointly over the multiple flows, can lead to significant performance gains. While our results only represent a single data point, they illustrate the need to look at MPTCP from a more holistic point of view and not treat the connections separately, as is currently being done. We call for new approaches and research into how multiple parallel connections offered by MPTCP should be used in an efficient and fair manner.

1. INTRODUCTION

The Transport Control Protocol (TCP) is an essential part of the Internet and is used by a majority of applications to reliably transport their data over the network. Since its inception, TCP has seen a lot of research, particularly regarding how its performance and throughput could be improved [11, 22, 23]. More recent work has led to the development of Multipath TCP (MPTCP), standardized by IETF, which is an extension to standard TCP. It operates under the viewpoint that end hosts like smartphones, servers, etc., are equipped with multiple access interfaces such as Ethernet, WiFi, 3G/4G, Bluetooth and can form multiple parallel network paths between communicating devices. Unlike a single path TCP connection, MPTCP utilizes multiple parallel TCP subflows between hosts via (all) available network interfaces for simultaneous data transfer. It achieves robustness and resilience to link failures, provides seamless connection handovers over different network interfaces and aggregates throughput and bandwidth of the underlying TCP connections [3, 26]. Due to the benefits offered by MPTCP, researchers have proposed utilizing it in datacenters [24], opportunistic networks [25], etc. The Linux implementation of the protocol has been made open-source to network researchers [21] and a commercial version is being used by Apple Inc. to support its digital assistant Siri in iOS and MacOS systems. Recently, Apple Inc. has also made its MPTCP API open to iOS application developers such that they can fully utilize its capability [13].

MPTCP protocol design is influenced by network compatibility and ensuring fairness to existing TCP connections. Figure 1 shows the network stack of an MPTCP-compliant client. MPTCP adds a scheduling layer over existing TCP connections and routes application packets to one of the subflows based on a decision parameter. Efficient scheduling decisions can improve the delay performance of MPTCP. Several schedulers have been proposed by researchers but due to its compliance with modular TCP design, the default scheduler injects packets on a subflow with the lowest smoothed TCP RTT (SRRT) value [19]. TCP RTT presents delayed information of the internal network behavior such as congestion, packet drops, queuing, etc., and does not explicitly indicate the reason for the change in network conditions. Unlike traditional TCP, MPTCP has the capability to proactively switch TCP flows if it senses any issues on one of the flows. However, MPTCP primarily treats the individual streams as separate entities and does not attempt to optimize performance across them.

In this paper, we argue that MPTCP should take a more comprehensive view over individual subflows and attempt to optimize the overall performance, as opposed to treating them as separate parallel entities. MPTCP currently is limited to the TCP-level information provided by the individual TCP subflows, but we claim that a more holistic approach is needed to exploit the possibilities offered by multiple flows to the full extent. This implies the need to take a different
approach in MPTCP research and in general on how to exploit parallel resources in networking, which can also serve other areas of networking [1][10][14][15].

To illustrate one aspect of the problem and to provide motivation for future work, we present several issues in current implementation and working of MPTCP due to its reliance on TCP layer information. We show via controlled experiments that the default minSRRT scheduler of MPTCP essentially forces the protocol to use only one of the many available flows and thus leads to lower performance. To demonstrate the possible performance that can be achieved by MPTCP, we develop the QueueAware scheduler which considers network interface device queue size while making scheduling decisions. We evaluate and compare the performance of QueueAware with minSRRT scheduler in several realistic scenarios over WiFi and 4G network interfaces. We also sketch how other parameters and network conditions currently ignored by MPTCP could be used for improved efficiency of network communication.

The remainder of the paper is organised as follows. In Section 2 we show the gap in performance of the default MPTCP scheduler via controlled experiments. In Section 3 we describe the scheduling policy used by QueueAware. Section 4 describes how we evaluate the efficacy of QueueAware using ns-3 simulations. Section 5 quantifies gains in performance achieved by QueueAware over the default MPTCP scheduler. We discuss related works in Section 6. In Section 7 we discuss various network parameters and network conditions that are currently overlooked by MPTCP when making scheduling decisions. These motivate future avenues for research. We conclude in Section 8.

2. DOWNSIDES OF IGNORING LOCAL INFORMATION

Figure 2(a) exemplifies goodput obtained from controlled testbed experiments that show how the default MPTCP scheduler optimizes over two available TCP subflows that use non-interfering end-to-end paths. The network topology used in the experiment is shown in Figure 3. The topology emulates a situation where the access network is a bottleneck, but the core network has high-speed pipes.

Neither flow drops any packets during the length of the experiment. One would, therefore, expect to fill packets on both flows and achieve stable goodput on both. However, MPTCP more often than not prefers to send packets on one flow over the other and is unable to optimize jointly over the available paths. As a result, MPTCP is only able to utilize ≈ 60% of available aggregated bandwidth in the experiment. We will argue that the reasons for this are two-fold: (a) decision making by the scheduler only uses the SRRT values of the flows, which is an end-to-end feedback mechanism and hence delayed; and (b) this delayed SRRT feedback leads to the scheduler selecting one flow over the other for undesirably long intervals, instead of suitably allocating packets on both flows. These reasons are in fact a consequence of MPTCP being incognizant of cross-layer information that is readily available locally.

Interestingly, the scheduling decisions that lead to high device queue occupancy and increase in SRRT were made using values of SRRT that corresponded to an earlier interval when the device queue was lightly loaded. So while a device queue (local to the MPTCP sender and used by an MPTCP flow) is full with packets, MPTCP remains oblivious to the same. Instead, it waits to be informed via a delayed end-to-end SRRT based feedback mechanism about the fact that the flow it has been assigning packets to is in fact loaded. In the process, it loses out on many opportunities of scheduling packets to the other better flow, one experiencing lower queue delay. Further, as the device queue is drop-tail in nature, i.e. it starts dropping incoming packets if full, MPTCP has to retransmit locally dropped packets, the information of which it infers after a missing ACK. Finally, a rapid dip in SRRT is noticed when a flow, which was earlier heavily queued but stayed unused for a while, is assigned new packets. These packets experience smaller waiting times and thus have a small RTT.

Next, we describe the QueueAware scheduler for MPTCP which is motivated by the observation that MPTCP doesn’t have to rely on delayed increase in SRRT to identify local queue delay. We show that instead, using the occupancy of the device queues together with SRRT enables MPTCP to use all available flows more efficiently.
policy. However, for the case when the arrivals are Poisson and the service times are non-identical but exponentially distributed, a scheduling policy that assigns a packet to a service facility that minimizes the conditional expected waiting time of the packet, conditioned on the knowledge of the number of packets waiting for service in the facility, is shown to have good performance [27]. Our QueueAware scheduler uses the policy in an MPTCP setting.

Consider $K$ service facilities indexed $1, \ldots, K$. Let facility $k$ have a service rate of $\mu_k$. Let $n_k(t)$ be the number of packets waiting for service in facility $k$ at time $t$. The policy assigns a packet to a service facility $k^*$ given by

$$k^* = \arg \min_k \frac{n_k(t)}{\mu_k}. \quad (1)$$

Note that $1/\mu_k$ is the expected service time of a packet in facility $k$. As a result, the conditional waiting time of a packet that enters such a facility is $n_k(t)/\mu_k$, which is the sum of the expected service times of the $n_k(t)$ packets currently waiting for service in the facility.

Adapting policy (1) to multiple end-to-end TCP subflows: The number of packets $n_k(t)$ in service facility $k$ (corresponding to TCP subflow $k$) is the number of packets in the corresponding device queue and can be obtained. However, we must estimate the service rate $\mu_k$.

Consider the $i$th packet arrival. Let $t_i^s$ be the time the packet is assigned to a service facility. Let $t_i^e$ be the time that a TCP ACK acknowledges receipt of the packet. The RTT of the packet can be denoted as $\text{RTT}_i = t_i^e - t_i^s$. Note that the RTT includes the time this packet waits in the queue in its assigned service facility before it starts service and the time it spends in service. Let the wait time be $W_i$. This can be calculated locally at the MPTCP sender. The time $X_i$ that the packet spends in service begins when the packet enters the NIC for transmission and ends when a TCP ACK for the packet is received. Given $W_i$ and $\text{RTT}_i$, we have $X_i = \text{RTT}_i - W_i$. The estimate of the service rate is updated on receipt of a TCP ACK. Let $\hat{S}_k$ be the current estimate of the average service time of facility $k$. On receipt of a TCP ACK for the packet, we update

$$\hat{S}_k = \alpha \hat{S}_k + (1 - \alpha) X_i, \quad (2)$$

where $0 < \alpha < 1$ applies appropriate weights to the last estimate of the average and the most current service time. We use $\alpha = 0.8$ in this work. The corresponding estimate of the service rate is $1/\hat{S}_k$. At time $t$, QueueAware schedules to the TCP subflow $k^*$ that satisfies

$$k^* = \arg \min_k n_k(t) \hat{S}_k. \quad (3)$$

### 4. EVALUATION METHODOLOGY

We simulated network topologies of the kind shown in Figure 3 using the network simulator ns-3. An MPTCP client

1For simplicity of exposition we ignore the time a TCP ACK may have to wait in a queue before being sent to the TCP layer.
uses two TCP subflows to the MPTCP server. The simulator ns-3 has an implementation of MPTCP [8] that we modified to include QueueAware. We compare the performance of the default minSR TT scheduler of MPTCP with that of QueueAware.

We simulated scenarios where both the MPTCP flows have reliable paths, and where one of the paths is unreliable and drops TCP packets. We will show that QueueAware, unlike minSR TT , is able to jointly use available flow capacities to achieve larger per flow (and aggregate) goodputs. Also, it does at least as well as the default minSR TT scheduler in scenarios where paths used by TCP subflows are unreliable.

**Reliable Paths:** We consider two non-interfering paths that see no packet drops but the corresponding access networks (last mile in Figure 3) have different bottleneck rates. Specifically, we simulated the following network scenarios:

- **Identical WiFi Access Points:** MPTCP client uses its WiFi interfaces to connect to identical WiFi access points providing reliable links. This use case may occur in an enterprise WiFi network, where a client may have more than one good access point in its vicinity. We set the WiFi link rate to each access point to 6 Mbps.

- **Non-Identical WiFi Access Points:** The use case remains the same as above. However, one of the two access points has a faster link of 12 Mbps, for example, because of greater proximity to the MPTCP client.

- **Heterogeneous networks of WiFi and 4G:** MPTCP client uses its WiFi interface and 4G interface to connect to access points of the different technologies. The WiFi link rate is 6 Mbps and 4G link rate is 12 Mbps. Though the link rate of 4G is large, packets experience larger RTT over 4G [5].

**Unreliable Paths:** We simulated an MPTCP client that uses its two WiFi interfaces to connect to access points. However, the tcp subflow using one of the access points suffers TCP packet errors. We set packet error rate to $10^{-2}$. In a real setting, this could happen because the client is close to losing coverage from the access point or because the access point is heavily loaded.

Lastly, for a selection of paths and network technologies, we simulated short time MPTCP subflows by performing a small file upload of 10 MB.

For all simulations, the backbone link was modeled as a Ethernet with rate 30 Mbps, and the core network was modeled as a 50 Mbps link. Our choice of links within the access networks makes them the bottleneck. The application at the MPTCP client generated a load of 50 Mbps. All results were averaged over 10 simulation runs. The access networks, backbone, and the core see no traffic other than that created by our MPTCP client. We defer performance evaluation of QueueAware under more realistic loads and larger numbers of MPTCP clients to future work.

5. **RESULTS**

5.1 **Reliable Paths**

We consider the scenario in which both TCP subflows use reliable paths. Figure 5(a) compares subflow goodputs for when there are two identical WiFi access points. Observe that both QueueAware and minSR TT show similar behavior in total goodputs per flow. However, a larger goodput per flow is achieved by QueueAware. As a result, it achieves a 46% increase in aggregate goodput over minSR TT. This is because minSR TT, as a consequence of only using the delayed feedback provided by SR TT, ends up scheduling packets to a subflow, which has a high device queue occupancy, for a longer time. Next, we shed more light on the differences in the behaviors of the schedulers, in Figures 6(a) and 6(b).

Figures 6(a) and 6(b) show the goodputs on the two flows obtained respectively by QueueAware and minSR TT as a function of time. While QueueAware can maintain a stable and almost equal goodput over both the flows, minSR TT at any given time chooses one flow over the other. This behavior of goodputs is made clear by Figures 7(a) and 7(b) that show SR TT behavior in same time duration. Subflows experience high SR TT for longer stretches of time when using the minSR TT scheduler, compared to when using the QueueAware scheduler. This corresponds to longer stretches of full queue occupancy of 100 packets when using minSR TT (see Figure 8(b)), when compared to the QueueAware scheduler (see Figure 8(a)).

Figure 5(b) shows the goodput performance when subflows use non-identical WiFi access points. It can be observed that QueueAware and minSR TT both perform similarly for the subflow that uses the faster link of 12 Mbps. However, importantly, QueueAware makes good use of the other available 6 Mbps link. Under QueueAware, the subflow using the slower link gets about 50% of the goodput obtained by the subflow using the faster link. On the other hand, minSR TT gets hardly any goodput on the subflow using the slower link. The use of locally available cross-layer device queue occupancy information together with SR TT enables QueueAware to make good use of both the available WiFi interfaces.

Finally, Figure 5(c) shows the goodput performance when one of the subflows uses a WiFi interface and the other uses a 4G interface that has twice the WiFi link rate. Recall that the 4G network suffers from larger RTT. Even in this case we observe that QueueAware utilizes bandwidth offered by both network interfaces considerably better than minSR TT. QueueAware achieves 26% more aggregate goodput when compared to minSR TT. The scheduler achieves a goodput that is $2.5 \times$ that of minSR TT via 4G. The underutilization of 4G by minSR TT has earlier been observed in real-world deployment tests. It has been found that the default scheduler utilizes the WiFi sub-flow 71% of time [6].
5.2 Unreliable Paths

On detecting packet loss, the congestion window of a sub-flow initiates the congestion avoidance phase. This limits the number of packets that can be sent on the sub-flow. Furthermore, MPTCP employs Penalization and Retransmission (PR), where on packet error MPTCP reduces the congestion window of the sub-flow with high RTT and reinjects the lost packet on the other available sub-flow [32]. Though this technique reduces the possibility of Head-of-Line (HoL) blocking, it also limits the sending rate and significantly impacts overall goodput.

Figure 5(d) shows the goodputs achieved by the two sub-flows when one of the subflows (subflow 1 in figure) experiences a packet loss rate of about $10^{-2}$. Due to the above stated reason both schedulers achieve rather small goodputs on the subflow experiencing errors. However, QueueAware is able to better exploit the subflow that has a reliable path. On this path, it achieves a goodput that is an improvement of about 100% over the goodput achieved by minSRTT.

5.3 Small File Upload

Table 1 shows the upload completion time of a 10 MB file for QueueAware and minSRTT for different interfaces and different path reliability. QueueAware achieves about 10% decrease in upload time with respect to minSRTT.

6. RELATED WORK

Several researchers have proposed improvements to the default minSRTT scheduler of MPTCP. Paasch et al. [20] designed a modular scheduler framework for MPTCP and had compared the performance of default minSRTT scheduler with a Round-Robin scheduler. Baidya et al. [2] propose RTT-based path quality metric to adapt out-of-order transmissions while limiting the usage of a slower path. Kuhn et al. [16] aim to reduce overall application delay by estimating maximum allowed receiver buffer blocking time to transmit out-of-order packets on multiple paths. On the other hand, Hwang et al. [12] propose to freeze the utilization of...
slower path when the difference in RTT’s of faster and slower paths exceeds a calculated threshold. BLEST [9] and OTIAS [32] balance heterogeneous flows and reduce Head-of-Line blocking by considering several parameters such as CWND, in-flight packets etc., along with SRTT. CMT-RMDS [4] proposes adopting receiver-centric path characteristics along with sender-driven RTT values to better estimate current path conditions.

Researchers have also proposed to utilize other network parameters to provide better path estimation. Corbillon et al. [7] leverage application layer information in transport layer flow scheduling decisions to provide delay-resilient video streaming in MPTCP. Lim et al. [28] labels WiFi subflow as active/inactive for data transmission based on a minimum desired signal strength. F2P-DPS [17] proposes to combine several TCP parameters such as CWND, SSThresh, RTTs to estimate subflow weights for data data transmissions. Ni et al. [18] utilizes reverse-path SACK packets to inform the sender of any out-of-order/lost packets at receiver buffer and calculate offset to provide successful data chunk delivery.

Although the solutions mentioned above tackle several critical issues affecting Multipath TCP in real-world, these techniques are significantly dependent on accurate estimation of current path characteristics. The solutions which utilize SRRT value as current path performance metric or are dependent upon it suffer from same issues as that of minSRRT shown in the paper. To efficiently handle varying application data traffic over heterogeneous paths in MPTCP, an ideal scheduler must be able to schedule packets over flows proactively and must adapt to network conditions swiftly.

Table 2: Network parameters impacting RTT

| Host Machine | Network | Receiver |
|--------------|---------|----------|
| Data rate    | Channel utilization | Bandwidth utilization |
| Retry percentage | Path congestion | Receiver queue delays |
| Network interface type | Number of nodes on path | Congestion window size |

Table: Network parameters impacting RTT

7. DISCUSSION AND FUTURE WORK

The aim of our evaluation was to show that RTT alone is not the best measure for scheduling packets over multiple network interfaces in MPTCP. Sender device queue is one such parameter which needs to be monitored and considered in overall network scheduling decision. Only by including cross-layer feedback into MPTCP control loop can we fully exploit the potential offered by multiple connections. As shown in the paper, treating the links as independent, parallel TCP flows restrict MPTCP’s performance.

Several other conditions can lead to changes MPTCP’s efficiency. Table 2 lists few such variables that impact RTT and the network path and which could be exploited by a more holistic MPTCP. These include host-specific parameters, such as device queue length; network-specific aspects, such as congestion, and receiver-specific parameters, such as window size. An efficient MPTCP should look at all or many of these parameters in conjunction while deciding how to schedule the packets and allocate the available flows for data transport.

Several other factors can also significantly impact network behavior. Congestion at an access point, over-utilization of channel capacity, queueing delay at receiver are some such scenarios. However, unlike the locally accessible parameters (such as device queue occupancy), explicitly monitoring and predicting these parameters is an interesting research question of its own. One possibility is to use explicit notifications such as ECN to convey occurrence of such a scenario. Incorporating these mechanisms and comparing its performance impact on current MPTCP implementation would be an interesting future avenue for research in the wider community.

In this paper, we argue that the current way of treating the individual subflows, practically separately relying only on their TCP level information, is not sufficient for fully exploiting the potential offered by multiple connections, and a more holistic approach to MPTCP and how it manages the connections is needed. Our results in this paper illustrate only one small facet of the bigger problem, but broader research efforts are needed to understand better how such multiple connections should be used in modern networks. These cover questions such as fairness to other network flows, general performance issues, flow control, and security issues, but they all apparently require a different approach to the problem than parallel, but largely independent connections.

8. CONCLUSION

In this paper, we demonstrated the shortcomings of MPTCP scheduling algorithm and the inadequacy of its reliance on SRTT. We proposed the QueueAware scheduler, which exploits device driver queue occupancy together with sRTT to obtain significantly better performance than the default MPTCP scheduler. We believe that the QueueAware scheduler highlights the need for a more holistic approach to multipath scheduling than currently being done by MPTCP.

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