Performance Analysis and Optimization for RIS-Assisted Multi-User Massive MIMO Systems With Imperfect Hardware

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Abstract—The paper studies a reconfigurable intelligent surface (RIS)-assisted multi-user uplink massive multiple-input multiple-output (MIMO) system with imperfect hardware. At the RIS, the paper considers phase noise, while at the base station, the paper takes into consideration the radio frequency impairments and low-resolution analog-to-digital converters. The paper derives approximate expressions for the ergodic achievable rate in closed forms under Rician fading channels. For the cases of infinite numbers of antennas and infinite numbers of reflecting elements, asymptotic data rates are derived to provide new design insights. The derived power scaling laws indicate that while guaranteeing a required system performance, the transmit power of the users can be scaled down at most by the factor $\frac{1}{\sqrt{M}}$ when $M$ goes infinite, or by the factor $\frac{1}{\sqrt{MN}}$ when $M$ and $N$ go infinite, where $M$ is the number of antennas and $N$ is the number of the reflecting units. Furthermore, an optimization algorithm is proposed based on the genetic algorithm to solve the phase shift optimization problem with the aim of maximizing the sum rate of the system. Additionally, the optimization problem with discrete phase shifts is considered. Finally, numerical results are provided to validate the correctness of the analytical results.

Index Terms—Reconfigurable intelligent surface (RIS), massive MIMO, phase noise, radio frequency impairments, analog-to-digital converter, achievable rate.

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A S FIFTH generation (5G) commercial networks began to be deployed in 2020, there is an increasing demand for the future communication systems to support the ever-increasing number of devices while guaranteeing the high quality of the communication service [1]. Massive-multiple-input-multiple-output (MIMO) has been widely used to enhance the system performance, since it can efficiently reduce multi-user interference and scale down the transmit power of users [2]–[4]. Recently, reconfigurable intelligent surface (RIS), also known as intelligent reflecting surface (IRS) or large intelligent surface (LIS), has been proposed as a promising technique to extend the coverage and improve the spectrum efficiency (SE) and energy efficiency (EE) of communication networks [5]–[10]. RIS is mainly composed of numerous reflecting elements, each of which imposes an independent phase shift on the incident signals. In particular, by carefully tuning the phase shifts, RIS can shape the wireless radio propagation environment to be customized to meet specific targets. Different from the relay, the reflecting elements at RIS require no active hardware components such as radio frequency (RF) chains and amplifiers, which significantly reduce the power consumption and hardware cost. Furthermore, RIS can work in the full-duplex mode without the self-loop interference [11].

Due to its appealing advantages, RIS has attracted extensive research attention from both academia and industry. For instance, the authors in [12] studied an RIS-assisted single-user downlink system, derived the upper bound expression of the SE, and optimized the phase shifts at the RIS. In the case where the working base station (BS) was interfered by another BS, the authors in [13] obtained tractable expressions for the data rates under both instantaneous and statistical channel state information (CSI). In [14], the authors applied RIS to Internet of Things, analyzed the system performance and proposed a time-length allocation scheme for minimizing the energy consumption. The authors in [15] investigated a multi-RIS downlink system with imperfect location information of the users, and analyzed the impacts of the system parameters with derived approximate expressions for the ergodic AR. In [16], the authors studied a multi-pair system assisted by RIS, and utilized the genetic algorithm (GA) to solve the phase shift optimization problem for maximizing the sum ergodic achievable rate (AR).
In [17], the authors in took into account the interplay of the responses between the phase shift and the amplitude in an RIS-assisted single-user system. The authors in [18] investigated a downlink RIS-assisted massive MIMO system with statistical CSI at the BS, and optimized the beamformings at the RIS and the BS. The authors in [19] derived closed-form sum rates for RIS-assisted uplink systems under spatially correlated Rician Fading, and jointly optimized the phase-shifting matrix and the transmit covariance matrix. In [20], the authors focused on an RIS-assisted multi-user uplink massive MIMO system, and proposed a GA-based algorithm for maximizing the sum ergodic AR according to the derived closed-form expressions.

It should be noted that the assumption of perfect hardware was considered in the aforementioned works. However, in practice, communication systems suffer from imperfect hardware, which leads to hardware impairments (HIs), such as oscillator phase noise, in-phase/quadrature-phase (I/Q) imbalance, non-linearities and quantization errors [21], [22]. Although compensation algorithms can alleviate the effects of HIs [23]–[25], the residual HIs still degrade and limit the system performance. Therefore, it is necessary to take HIs into consideration when analyzing practical systems. The authors in [26] considered HIs at the transmitters in an RIS-assisted single-user downlink system. They first obtained closed-form solutions for the optimal beamforming at the multi-antenna source, and then optimized the phase shifts at the RIS for maximizing the signal-to-noise ratio (SNR). In [27], the secrecy rate was studied in RIS-assisted systems with HIs at the transmitters of the BS. The authors proposed an iterative method to optimize the beamforming vectors at both the BS and the RIS. For a multi-RIS-assisted full-duplex system, the authors in [28] investigated the impacts of HIs at the transceivers of the BS and users, and jointly optimized the beamformings at the BS and the RISs and the transmit power of the users for maximizing the sum AR.

Moreover, in massive MIMO systems, the BS is equipped with a large number of antennas, which requires a large number of analog-to-digital converters/digital-to-analog converters (ADCs/DACs), leading to a high power consumption and hardware cost. To address this, researchers use low-resolution ADCs/DACs to reduce the power consumption and hardware cost while sacrificing a certain system performance [29]–[31]. The authors in [32] investigated an RIS-assisted single-user uplink system with low-resolution ADCs at the BS, and derived the AR expressions and analyzed the system performance. In [33], an RIS-assisted multi-user downlink system with low-resolution DACs was studied. The authors derived the approximate expressions for AR and optimized the phase shifts at the RIS.

On the other hand, the phase noise has recently gain much attention in RIS-assisted systems, which is generated from the DACs was studied. The authors derived the approximate expres-sions for ergodic AR, analyze the system performance and optimize the phase shift optimization problems for maximizing the sum rates of the considered system. Moreover, we verify in simulations that the proposed optimization algorithm can largely improve the sum rates of the considered system.

The remainder of this paper is organized as follows: Section II models the RIS-assisted multi-user uplink massive MIMO system under Rician fading channels and with imperfect hardware. Section III derives the approximate expressions for ergodic AR, and analyzes the system performance. Section IV proposes an algorithm based on GA to solve the continuous and discrete phase shift optimization problems for maximizing the sum rates of the system. Moreover, we verify in simulations that the proposed optimization algorithm can largely improve the sum rates of the considered system.
with independently and identically distributed (i.i.d) elements following the distribution of $CN(0, 1)$. Vector $\mathbf{\tilde{h}}_k \in \mathbb{C}^{N \times 1}$ and matrix $\mathbf{G} \in \mathbb{C}^{M \times N}$ are the LoS parts of the channels, which are expressed respectively as

$$\mathbf{\tilde{h}}_k = \mathbf{a}_N (\phi_k^r, \phi_k^e), \quad (3)$$

$$\mathbf{G} = \mathbf{a}_M (\phi^r, \phi^e) \mathbf{a}_N^H (\phi^r, \phi^e), \quad (4)$$

where $\phi_k^r$ and $\phi_k^e$ represent the azimuth angles of arrival (AoA) and elevation AoA at the RIS from user $k$, respectively. $\phi^r$ and $\phi^e$ are the azimuth angles of departure (AoD) and elevation AoD from the RIS to the BS, respectively. $\phi^r$ and $\phi^e$ stand for the azimuth AoA and elevation AoA at the BS from the RIS, respectively. Furthermore, it is assumed that uniform square planar arrays are equipped at both the RIS and the BS with size of $\sqrt{N} \times \sqrt{N}$ and $\sqrt{M} \times \sqrt{M}$, respectively. Thus, the $i$th element of vector $\mathbf{a}_X \in \mathbb{C}^{N \times 1}$ is expressed as [20], [38]

$$[\mathbf{a}_X (\phi_1, \phi_2)]_i = e^{j2\pi \frac{x}{2X}} (x \sin \phi_1 \sin \phi_2 + y \cos \phi_2),$$

$$x_i = (i - 1) \mod \sqrt{X}, \quad y_i = \left\lfloor \frac{i - 1}{\sqrt{X}} \right\rfloor, \quad (5)$$

where $d$ is the antenna/unit spacing, and $\lambda$ is the carrier wavelength.

### B. Data Transmission With Imperfect Hardware

Since the RIS is employed to assist the communications between the users and the BS, the signals are first transmitted to the RIS, then reflected to the BS. Therefore, when the RIS and the BS have ideal configurations, the received signal at the BS can be expressed as

$$\mathbf{y}_p = \mathbf{G}\Phi\mathbf{H}\mathbf{P}\mathbf{x} + \mathbf{n}, \quad (6)$$

where $\mathbf{x} = [x_1, x_2, \ldots, x_K]^T$ with $x_k$ representing the signal transmitted from user $k$ and subject to $E[|x_k|^2] = 1$. $\mathbf{P} = \text{diag}\{p_1, p_2, \ldots, p_K\}^{1/2}$, and $p_k$ is the transmit power of user $k$. $\Phi = \text{diag}\{e^{j\theta_1}, e^{j\theta_2}, \ldots, e^{j\theta_N}\}$ stands for the phase shift matrix, and $\theta_n$ is the phase shift at the unit $n$ of the RIS. $\mathbf{n}$ is the additive white Gaussian noise (AWGN) at the BS, whose elements follow i.i.d $CN(0, \sigma^2)$.

However, in real scenarios, the imperfect hardware at the RIS and the BS should be taken into consideration, which would limit the system performance. To address this, we consider the phase noise at the RIS, the RF impairments and low-resolution ADCs at the BS.

The phase noise is induced by the imperfection of the reflecting elements, or by the imperfect channel estimation [34]. In this paper, it is modelled as

$$\Theta = \text{diag}\{e^{j\varepsilon_1}, e^{j\varepsilon_2}, \ldots, e^{j\varepsilon_N}\}, \quad (7)$$

where $\varepsilon_n$ follows a zero-mean Von Mises distribution with the probability density function (PDF) of [41]

$$M_\nu (\varepsilon_n) = \frac{1}{2\pi I_0 (\nu)} e^{\nu \cos \varepsilon_n}, \quad \varepsilon_n \in [0, 2\pi), \quad (8)$$

with $\nu$ being the concentration parameter.
Then, we adopt the extended error vector magnitude (EEVM) model to depict the impacts of the RF impairments, such as I/Q imbalance and carrier frequency offset [31], [38], [42]. Thus, the received signal at the RF chains is re-expressed as

$$y_{RF} = \chi G\Phi \Theta H p x + n_{RF} + n,$$  \hspace{1cm} (9)

where $\chi = \text{diag}\{\chi_1, \chi_2, \ldots, \chi_M\}$ with $\chi_m = \kappa_m e^{j\varphi_m}$ representing the amplitude attenuation and phase shift for the $m$th RF chain. The scalar $\kappa_m$ satisfies $|\kappa_m| \leq 1$, while $\varphi_m$ follows a uniform distribution of $[-\eta_m, \eta_m]$ with $\eta_m \in [0, \pi)$. Additionally, vector $n_{RF} = [n_{RF,1}, n_{RF,2}, \ldots, n_{RF,M}]^T$ stands for the additive distortion noise at the RF chains, where $n_{RF,m}$ has the distribution of $CN(0, \sigma^2_{RF,m})$. In the following analysis, we assume $\kappa_m = \kappa, \eta_m = \eta$ and $\sigma^2_{RF,m} = \sigma^2_{RF}$ for all $m$ for simplicity, which means all the RF chains have the same level of imperfections.

Moreover, the BS uses low-resolution ADCs to reduce the hardware cost and power consumption, the impacts of which can be modelled by the additive quantization noise model (AQNM) [29], [31]. Therefore, the quantized signals can be obtained as

$$y_{Q} = \tau \chi G\Phi \Theta H p x + \tau n_{RF} + \tau n + n_{Q},$$ \hspace{1cm} (10)

where $\tau = 1 - \varrho$, and $\varrho$ is the inverse of the signal-to-quantization-noise ratio. For the quantization bits $b \leq 5$, the values of $\varrho$ are listed in Table I, while for $b > 5$, we have $\varrho = \frac{2^{2b}}{\sqrt{2^{2b} + 2^{b-2}}}$.

| $b$ | 1 | 2 | 3 | 4 | 5 |
|-----|---|---|---|---|---|
| $\varrho$ | 0.3634 | 0.1175 | 0.03454 | 0.009497 | 0.002499 |

Table I: Values of $\varrho$

Note that at the right hand side of (13), the first term is the desired signal from user $k$; the second term is the multi-user interference from the other users; the third and the fourth terms are generated from the distortion noise and the AWGN at RF chains, respectively; the last term is from the quantization noise.

III. ACHIEVABLE RATE ANALYSIS

In this section, we investigate the uplink ergodic AR of this multi-user massive MIMO system and the impacts of the system settings, such as the number of the reflecting elements $N$ at the RIS and the number of the antennas $M$ at the BS.

According to (13), the uplink ergodic AR for user $k$ is expressed as (14) at the bottom of this page, where the power of the distortion noise, the AWGN, and the quantization noise are respectively expressed as

$$D_{N} = \sum_{i \neq k} \left| h_{k}^{H} G^{H} H \chi G \Phi \Theta h_{i} \right|^2,$$  \hspace{1cm} (15)

$$A_{N} = \tau^2 \sigma^2_{RF} \left| h_{k}^{H} G^{H} H \right|^2,$$ \hspace{1cm} (16)

$$Q_{N} = \tau (1 - \tau) \left| h_{k}^{H} G^{H} H S_{Q}^{1/2} \right|^2.$$ \hspace{1cm} (17)

Based on (14), we present the following theorem.

**Theorem 1:** With MRC processing, the uplink ergodic AR for user $k$ in the RIS-assisted multi-user uplink massive MIMO system can be approximated in a closed form as (18) at the bottom of the next page, where $\xi_k, \gamma_k, \varphi_k$ and $\varphi_k$ are respectively given by (67), (78), (86), and (94) in Appendix A.

**Proof:** See Appendix A.  \hspace{1cm} $\Box$

It can be readily observed from Theorem 1 that the uplink ergodic AR of user $k$ depends on $M$, $N$, the AoA at the BS, the AoA and AoD at the RIS, the power of users, the large-scale fading coefficients, the Rician factors, the phase shifts and noise at the RIS, the RF impairments, and the quantization bit and accuracy.

In particular, when the Rician factors satisfy $\mu_k = 0$, $\forall k$ and $\delta = 0$, the Rician fading channels expressed in (1) and (2) degenerate to Rayleigh fading channels, where only the nLoS parts of the channels remain. The following remark discusses the uplink ergodic AR with Rayleigh fading channels under the considered system.

**Remark 1:** When Rayleigh fading channels are considered, where $\mu_k = 0$, $\forall k$ and $\delta = 0$, the closed-form expression of the uplink ergodic AR for user $k$ in the RIS-assisted multi-user uplink massive MIMO system is obtained as (19) at the bottom of the next page.
of the page, where \( \rho \) and \( \iota \) are respectively given by (39) and (57) in Appendix A.

A. Asymptotic Analysis

According to (54) in Appendix A, it is noted that \( |f_k| \leq N \) and the equality holds when the RIS is aligned to user \( k \). Specifically, the phase shifts aligned to user \( k \) at the RIS should satisfy

\[
\theta_n = -2\pi \frac{d}{\lambda} (x_n p_k + y_n q_k), \quad \forall n,
\]

\[
p_k = \sin \phi_k^\theta \sin \phi_k^\tau - \sin \phi_k^\theta \sin \phi_k^\iota,
\]

\[
q_k = \cos \phi_k^\theta - \cos \phi_k^\iota. \tag{20}
\]

In this case, we assume that \( |f_i| \) is bounded when \( i \neq k \). Therefore, when the RIS is aligned to user \( k \), the numerator \( p_k \xi_k \) in (18) is on the order of \( \mathcal{O}(M^2, N^4) \).

To obtain the order of the denominator in (18), we need to focus on the term \( \tilde{H}_k^H \tilde{H}_i \) in (79) and (82) first, which can be further expressed as

\[
\tilde{H}_k^H \tilde{H}_i = \sum_{n=1}^{N} a_{N,n}^* (\phi_k^\tau, \phi_k^\iota) a_{N,n}^* (\phi_i^\tau, \phi_i^\iota)
\]

\[
= \sum_{n=1}^{N} e^{j2\pi \frac{n}{N} (x_n (\sin \phi_k^\tau \sin \phi_i^\tau - \sin \phi_k^\iota \sin \phi_i^\tau + y_n (\cos \phi_k^\theta - \cos \phi_i^\theta))}
\]

\[
= \sum_{n=1}^{N} e^{j2\pi \frac{n}{N} (x_n s_k + y_n t_k)} a_{N,n}^* (\phi_k^\tau, \phi_k^\iota)
\]

\[
= \sum_{n=1}^{N} e^{j2\pi \frac{n}{N} (x_n s_k + y_n t_k)} a_{N,n}^* (\phi_k^\tau, \phi_k^\iota)
\]

\[
= \sqrt{N-1} \sqrt{N-1} \sum_{n=1}^{N} e^{j2\pi \frac{n}{N} (x_n s_k + y_n t_k)} a_{N,n}^* (\phi_k^\tau, \phi_k^\iota)
\]

\[
= \sum_{n=1}^{N} e^{j2\pi \frac{n}{N} (x_n s_k + y_n t_k)} a_{N,n}^* (\phi_k^\tau, \phi_k^\iota)
\]

\[
= e^{j2\pi \frac{N-1}{N} \sum_{n=1}^{N} e^{j2\pi \frac{n}{N} (x_n s_k + y_n t_k)}} a_{N,n}^* (\phi_k^\tau, \phi_k^\iota)
\]

\[
= \frac{e^{j2\pi \frac{N-1}{N} \sum_{n=1}^{N} e^{j2\pi \frac{n}{N} (x_n s_k + y_n t_k)}} a_{N,n}^* (\phi_k^\tau, \phi_k^\iota)}{\sin \left( \frac{\pi}{N} \right)}
\]

\[
= \frac{e^{j2\pi \frac{N-1}{N} \sum_{n=1}^{N} e^{j2\pi \frac{n}{N} (x_n s_k + y_n t_k)}} a_{N,n}^* (\phi_k^\tau, \phi_k^\iota)}{\sin \left( \frac{\pi}{N} \right)}
\]

which yields

\[
\sum_{n=1}^{N} e^{j2\pi \frac{n}{N} s_k} \xrightarrow{N \to \infty} 0. \tag{23}
\]

According to (21), it is noted that \( \tilde{H}_k^H \tilde{H}_i \) is below the order of \( \mathcal{O}(N) \), which means \( \tilde{H}_k^H \tilde{H}_i \) is not the term which dominates the order of the denominator. Since the quantization noise is proportional to the power of the received signals, the denominator is on the order of \( \mathcal{O}(M^3 N^3) \). Thus, the fraction in (18) is on the order of \( \mathcal{O}(M) \). Then, we have the following corollary:

**Corollary 1:** When the RIS is aligned to user \( k \) and the number of the reflecting elements at the RIS satisfies \( N \to \infty \), the uplink ergodic AR for user \( k \) in the RIS-assisted multi-user uplink massive MIMO system converges to

\[
\hat{R}_k \to \log_2 \left( \frac{\tau^2}{1-\tau} M + 1 - \iota^2 \tau \right), \tag{24}
\]

where \( \iota \) is given by (57) in Appendix A.

It can be seen from Corollary 1 that the converged uplink ergodic AR for user \( k \) is determined by \( M \), the quantization parameter \( \tau \), and the scalar \( \iota \) which is related to the RF impairments.

Furthermore, we can find that the impact of the phase noise at the RIS vanishes in the converged AR for user \( k \). This is because when the RIS is aligned to user \( k \), the signal transmitted from user \( k \) is on the order of \( \mathcal{O}(N^3) \), while the interference from the other users is on the order of \( \mathcal{O}(N^3) \). Then as \( N \) goes to infinity, the signal transmitted from user \( k \) becomes dominant. On the other hand, the phase noise at the RIS is multiplicative to the transmitted signal, and the quantization noise at the ADCs is proportional to the signal power. Therefore, the impact of phase noise at the RIS vanishes as the equal parts of coefficients in the numerator and denominator are eliminated.

When none of the users is aligned to the RIS, we assume that \( |f_k| \) is bounded for \( \forall k \). In this case, both of the numerator and the denominator in the fraction of (18) are on the order of \( \mathcal{O}(M^2 N^2) \). Then, we have the following conclusion.

**Corollary 2:** When none of the users is aligned to the RIS, as the number of the reflecting elements \( N \) at the RIS and the number of the antennas \( M \) at the BS satisfy \( N, M \to \infty \), the uplink ergodic AR for user \( k \) in the RIS-assisted multi-user uplink massive MIMO system converges to

\[
\hat{R}_k \to \log_2 \left( 1 + \frac{(\mu_k + \iota^2 + 1)^2 + \mu_k + 1 - \iota^2 \mu_k}{\sum_{\ell \neq k} p_{\ell,\alpha_k} (\mu_{\ell,\alpha_k} + 1) (\mu_{\ell} + 1 - \iota^2 \mu_{\ell})} \right), \tag{25}
\]

where \( \rho \) is given by (39) in Appendix A.

In Corollary 2, the converged uplink ergodic AR for user \( k \) is determined by the power of the users, the large-scale fading coefficients, the Rician factors, and the level of phase noise.
B. Power Scaling Laws

An important feature of massive MIMO is that it reduces the transmit power of the users proportionally to the number of antennas while maintaining the required system performance. As such, to gather valuable insights on energy savings, we investigate the power scaling laws of the users.

We scale down the power as $p_k = \frac{E_u}{M^2}$, $\forall k$, with fixed $E_u$, where $\epsilon \geq 0$ is the power scaling factor deciding the power scaling level. Then, from (18) in Theorem 1, as the number of antennas $M \to \infty$, we have

$$\tilde{R}_k \to \begin{cases} 0, & \epsilon > 1 \\ \log_2 \left( 1 + \frac{E_u \Gamma_k}{\sum_{i \neq k} E_u \Gamma_{ki} + (\sigma^2 + \sigma^2) \tau \omega_k} \right), & \epsilon = 1 \\ \log_2 \left( 1 + \frac{E_u \Gamma_k}{\sum_{i \neq k} E_u \Gamma_{ki}} \right), & \epsilon < 1 \\
\end{cases},$$

where $\Gamma_k$ and $\Gamma_{ki}$ are respectively defined as (27) and (28)

$$\Gamma_k = \frac{\rho^2 \sigma^2 \alpha^2}{(\delta + 1)^2 (\mu_k + 1)^2} \times \left[ \left( \rho^2 (\mu_k + \delta + 1)^2 + (1 - \rho^2) \delta^2 \mu_k + \delta^2 \right) N^2 \right] + \left( \left( 2 \mu_k + 3 \delta + 2 - \delta \mu_k \right) \rho^2 + (1 + \mu_k) \delta \delta \mu_k |f_k|^2 \right) + \left( \mu_k + \delta + 2 \right)^2 - \rho^2 (\mu_k + \delta + 1)^2 - 2 \rho^2 \delta^2 \mu_k - 2 \right) N + \rho^2 \delta^2 \mu_k^2 |f_k|^4 + 2 \left( (1 - \rho^2) (\mu_k + \delta) + 2 \right) \delta^2 \mu_k |f_k|^2 \right]$$

and $\rho$, $\epsilon$, and $\omega_k$ are respectively given by (39), (57), and (86) in Appendix A.

It is noted that the converged AR is determined by the power scaling factor $\epsilon$. When $\epsilon > 1$, the converged AR goes to zero as $M \to \infty$. This is because the transmit power is aggressively scaled down with a large $\epsilon$, which certainly degrades the system performance. When $\epsilon \leq 1$, the converged AR is a non-zero value as $M \to \infty$. It means the system performance can be maintained when the transmit power is scaled down. Furthermore, when $\epsilon = 1$, the transmit power can be scaled down by the factor $\frac{1}{M^2}$ at most while guaranteeing the required system performance. Therefore, we obtain the following corollary.

Corollary 3: As the number of antennas $M \to \infty$, the transmit power of the users can be scaled down at most to $p_k = \frac{E_u}{M^2}$, $\forall k$, with fixed $E_u$, then the uplink ergodic AR for user $k$ in the RIS-assisted multi-user uplink massive MIMO system converges to

$$\tilde{R}_k \to \log_2 \left( 1 + \frac{E_u \Gamma_k}{\sum_{i \neq k} E_u \Gamma_{ki} + (\sigma^2 + \sigma^2) \tau \omega_k} \right),$$

where $\Gamma_k$ and $\Gamma_{ki}$ are respectively defined in (27) and (28).

Corollary 3 illustrates the power scaling law related to $M$. Theoretically, the transmit power of the users can be further cut down according to the number of reflecting elements $N$ at the RIS in the considered RIS-assisted system. The following corollary shows the power scaling law related to $M$ and $N$, when none of the users is aligned to the RIS.

Corollary 4: When none of the users is aligned to the RIS, as the number of antennas and reflecting elements $M, N \to \infty$, the transmit power of the users can be scaled down at most to $p_k = \frac{E_u}{M^2 N}$, $\forall k$, with fixed $E_u$, then the uplink ergodic AR for user $k$ in the RIS-assisted multi-user uplink massive MIMO system converges to (30) at the bottom of the page.

Corollary 4 investigates the power scaling law in the case where none of the users is aligned to the RIS. Moreover, the following Corollary 5 investigates the power scaling law in the case where the RIS is aligned to user $k$.

Corollary 5: When the RIS is aligned to user $k$, as the number of antennas and reflecting elements $M, N \to \infty$, the transmit power of user $k$ can be scaled down at most to $p_k = \frac{E_u}{M^2 N}$, while the transmit power of other users is scaled down to $p_i = \frac{E_u}{M^2 N}$, $i \neq k$, with fixed $E_u$, then the uplink ergodic AR for user $k$ in the RIS-assisted multi-user uplink massive MIMO system converges to (31) at the bottom of the next page.

IV. Phase Shift Optimization

Theorem 1 shows that the uplink ergodic AR depends on the phase shift of the RIS. Thus, to enhance the system performance, we can optimize the phase shifts at the RIS for maximizing the sum uplink ergodic AR.

From (18), the sum uplink ergodic AR of the RIS-assisted massive MIMO system can be expressed as

$$\tilde{R}_{\text{sum}} = \sum_{k=1}^{K} \tilde{R}_k.$$

and $\rho$, $\epsilon$, and $\omega_k$ are respectively given by (39), (57), and (86) in Appendix A.

It is noted that the converged AR is determined by the power scaling factor $\epsilon$. When $\epsilon > 1$, the converged AR goes to zero as $M \to \infty$. This is because the transmit power is aggressively scaled down with a large $\epsilon$, which certainly degrades the system performance. When $\epsilon \leq 1$, the converged AR is a non-zero value as $M \to \infty$. It means the system performance can be maintained when the transmit power is scaled down. Furthermore, when $\epsilon = 1$, the transmit power can be scaled down by the factor $\frac{1}{M^2}$ at most while guaranteeing the required system performance. Therefore, we obtain the following corollary.

Corollary 3: As the number of antennas $M \to \infty$, the transmit power of the users can be scaled down at most to $p_k = \frac{E_u}{M^2}$, $\forall k$, with fixed $E_u$, then the uplink ergodic AR for user $k$ in the RIS-assisted multi-user uplink massive MIMO system converges to

$$\tilde{R}_k \to \log_2 \left( 1 + \frac{E_u \Gamma_k}{\sum_{i \neq k} E_u \Gamma_{ki} + (\sigma^2 + \sigma^2) \tau \omega_k} \right),$$

where $\Gamma_k$ and $\Gamma_{ki}$ are respectively defined in (27) and (28).

Corollary 3 illustrates the power scaling law related to $M$. Theoretically, the transmit power of the users can be further cut down according to the number of reflecting elements $N$ at the RIS in the considered RIS-assisted system. The following corollary shows the power scaling law related to $M$ and $N$, when none of the users is aligned to the RIS.

Corollary 4: When none of the users is aligned to the RIS, as the number of antennas and reflecting elements $M, N \to \infty$, the transmit power of the users can be scaled down at most to $p_k = \frac{E_u}{M^2 N}$, $\forall k$, with fixed $E_u$, then the uplink ergodic AR for user $k$ in the RIS-assisted multi-user uplink massive MIMO system converges to (30) at the bottom of the page.

Corollary 4 investigates the power scaling law in the case where none of the users is aligned to the RIS. Moreover, the following Corollary 5 investigates the power scaling law in the case where the RIS is aligned to user $k$.

Corollary 5: When the RIS is aligned to user $k$, as the number of antennas and reflecting elements $M, N \to \infty$, the transmit power of user $k$ can be scaled down at most to $p_k = \frac{E_u}{M^2 N}$, while the transmit power of other users is scaled down to $p_i = \frac{E_u}{M^2 N}$, $i \neq k$, with fixed $E_u$, then the uplink ergodic AR for user $k$ in the RIS-assisted multi-user uplink massive MIMO system converges to (31) at the bottom of the next page.
Algorithm 1: Algorithm for Selection.
1: Generate \( c \) from a uniform distribution in \((0, 1)\);
2: Set \( \text{acc} = f_{\text{fit},j} \);
3: for \( j = 1 : N_{\text{tot}} \) do
4: if \( c > \text{acc} \) then
5: \( j = j + 1 \);
6: \( \text{acc} = \text{acc} + f_{\text{fit},j} \);
7: else
8: Set the \( j \)th individual in the LIST 1 as a parent;
9: break;
10: end if
11: end for

Since the phase shift at each unit of the RIS lies in the range of \([0, 2\pi]\), the phase shift optimization problem can be expressed as

\[
\max_{\Phi} \tilde{R}_{\text{sum}}
\quad \text{s.t.} \quad \theta_n \in [0, 2\pi), \forall n, \tag{33}
\]

where \( \tilde{R}_{\text{sum}} \) is the sum uplink ergodic AR defined in (32), \( \Phi \) is the phase shift matrix, and \( \theta_n \) is the phase shift at unit \( n \) of the RIS. According to (18) and (32), the expression for the objective function of Problem (33) is complicated, which makes the problem challenging to be solved. Herein, we apply GA to solve our phase shift optimization problem.

Simulating the evolution of nature population, GA mainly includes five parts: population initialization, fitness evaluation \& sort, selection, crossover and mutation. By tailoring it to our phase shift optimization problem, we further discuss the five parts of GA.

1) Population initialization: In the beginning, \( N_{\text{tot}} \) individuals are generated in the initial population. For the \( N \) phase shifts at the \( N \) reflecting elements of the RIS, each individual has one chromosome containing \( N \) genes. Furthermore, the value of each gene is initially generated in \([0, 2\pi)\).

2) Fitness evaluation \& sort: The fitness value of the individual \( i \) is evaluated by the fitness function, which is given by

\[
f_{\text{fit},i} = \tilde{R}_{\text{sum},i}, \quad i = 1, 2, \ldots, N_{\text{tot}}, \tag{34}
\]

where \( \tilde{R}_{\text{sum},i} \) is the sum uplink ergodic AR corresponding to individual \( i \). Since we use the objective function in Problem (33) as the fitness function, the individual corresponding to a higher sum uplink ergodic AR has a higher fitness value. Then, \( N_{\text{tot}} \) individuals are sorted by the fitness values given in (34) as LIST 1.

3) Selection: The selection operation is to choose individuals from the current population as parents. Before the selection operation, we choose the top \( N_e \) individuals in LIST 1 as elite individuals, which are directly copied to the next generation.

Algorithm 2: Algorithm for Crossover.
1: Generate \( c_1 \) and \( c_2 \) from a uniform distribution in \((0, 1)\);
2: if \( c_1 > p_c \) then
3: \( \text{child1} = \text{parent1} \);
4: \( \text{child2} = \text{parent2} \);
5: else
6: \( \text{child1} = [c_1 N]; \)
7: \( \text{child2} = [\text{parent2}(1 : c_2) \text{parent1}(c_2 + 1 : N)] \);
8: end if
9: end for

The operation for the elite individuals is to make sure that the optimal individuals in the current population are passed to the next. Then, we scale the fitness values of the individuals in LIST 1 as follows:

\[
f_{\text{fit},j} = \frac{f_{\text{fit},i}}{\sum_{s=1}^{N_{\text{tot}}} f_{\text{fit},s}^\text{list}}, \quad j = 1, 2, \ldots, N_{\text{tot}}, \tag{35}
\]

where \( f_{\text{fit},i}^\text{list} \) is the fitness value of the \( i \)th individual in LIST 1. Based on (35), the selection algorithm is given in Algorithm 1, which is used to select one parent once at a time.

4) Crossover: The crossover operation needs two parents. Simply, we execute the selection operation two times to generate two parents for one crossover operation. The crossover algorithm is given in Algorithm 2, where \( p_c \) stands for the crossover probability, and parent1 and parent2 are generated from the selection operation.

5) Mutation: The mutation operation is after the crossover operation. Each gene of the child generated from the crossover operation can mutate under the mutation probability \( p_m \). The mutation operation is shown in Algorithm 3. Finally, the child after the mutation operation is added to the next generation.

Based on Algorithms 1–3, we propose a GA for the phase shift optimization problem (33) to obtain the optimal phase shifts \( \{\theta_n^*\}_{n=1,2,\ldots,N} \) along with the maximum sum rate \( \tilde{R}_{\text{sum}}^* \). The GA is given in Algorithm 4. Additionally, the complexity of the proposed GA-based algorithm is \( N_{\text{tot}} \times n \), where \( N_{\text{tot}} \) is the population size, and \( n \) is the number of generations evaluated which is determined by the convergence behavior of the GA [43].

\[
\tilde{R}_k \rightarrow \log_2 \left( 1 + \frac{\rho^2 \mu_k}{\sum_{i \neq k} \alpha_i (\mu_i + 1)} \left( \mu_i + 1 - \rho^2 \mu_i \right) + \left( \sigma_{RF}^2 + \sigma^2 \right) \frac{E_s}{E_n} \frac{(\delta + 1)(\mu_k + 1)}{\pi^2 \kappa^2 \beta_c \delta} \right) \tag{31}
\]
Algorithm 4: GA for Phase Shift Optimization.

1: initialization: Generate the initial population \( P_1 \) with
\( N_{\text{tot}} \) individuals. The \( N \) genes of each individual are
initially generated in \([0, 2\pi)\). Set the iteration number \( t = 1 \). The number of the termination iteration times is \( t_T \), and the termination value is \( f_T \).

2: repeat
3: Calculate the fitness values for \( P_t \) as \( \{ f_{\text{fit}}, i \} = \{ R_{\text{sum}}, i, i = 1, 2, \ldots, N_{\text{tot}} \}; \)
4: Sort the individuals in \( P_t \), select the top \( N_e \) individuals as elites, and add them to the population \( P_{t+1} \);
5: Scale the fitness values of the individuals in LIST 1;
6: for \( j = 1 : (N_{\text{tot}} - N_e) / 2 \) do
7: Execute Algorithm 1 two times for selection, and
8: Execute Algorithm 2 for crossover, and generate
9: For each child, execute Algorithm 3 for mutation, and then add child1 and child2 to the population \( P_{t+1} \);
10: end for
11: Set \( t = t + 1 \);
12: until \( t > t_T \) or \( \max(\{ f_{\text{fit}}, i \}) > f_T \)
13: Output \( \max(\{ f_{\text{fit}}, i \}) \) as the maximum sum rate \( \hat{R}_{\text{sum}} \)
\end{algorithm}

\( \Phi \)
\begin{align}
\max_{\Phi} & \quad \hat{R}_{\text{sum}} \\
\text{s.t.} & \quad \theta_n \in \left\{ \frac{2\pi}{2^B}, 2 \times \frac{2\pi}{2^B}, \ldots, (2^B - 1) \times \frac{2\pi}{2^B} \right\}, \forall n, \quad (36)
\end{align}

where the range of the phase shifts is divided into \( B \) bits. It is readily to be seen that with a larger \( B \), the phase shifts can be adjusted more accurately. When the values of the genes are generated from the discrete range, Algorithm 4 can be applied to solve Problem (36) with discrete phase shifts as to solve Problem (33).

V. Numerical Results

In this section, numerical results are provided. Similar to the settings in [44] and [20], we consider a scenario placed in an XYZ Cartesian coordinate system, where the BS is at coordinate \((0, 0, 25)\), and the RIS is at \((5, 100, 30)\). Users are assumed to be randomly distributed within the circle in Plane \( z = 1.6 \) with the center at \((0, 0, 1.6)\). The values for the AoA and AoD of the BS and the RIS are generated from a uniform distribution in \([0, 2\pi)\). Furthermore, we set the spacing distance at the BS and the RIS as \( d = \frac{1}{2} \), the number of users as \( K = 4 \), the Rician factors as \( \delta = 1 \) and \( \mu_k = 10 \), \( \forall k \), the transmit power of users as \( p_u = 30 \text{ dBm}, \forall k \), the parameter of the phase noise as \( \nu = 20 \), the amplitude and phase parameters of RF impairments as \( \kappa = 0.9 \) and \( \eta = \pi / 6 \), the noise power as \( \sigma^2 = \sigma_{RF}^2 = -104 \text{ dBm} \), and the ADC quantization bits as \( b = 2 \). The large-scale fading coefficient is modeled as
\begin{align}
\text{pathloss} = \frac{l^{\alpha_p}}{1000^2}, \quad (37)
\end{align}

where \( l \) is the distance between the source and the destination. \( \alpha_p \) is the path-loss exponent, which is assumed to be \( \alpha_p = 2.8 \) in this section. Additionally, the simulation results in this section are obtained by averaging over 2000 Monte Carlo realizations.

In Fig. 2, we study how the sum rates vary with the number of the antennas \( M \) at the BS, setting the number of the reflecting elements \( N \) at the RIS as \( N = 16 \) and \( N = 64 \). The curves marked with “Simulation” are obtained based on (14), while the curves marked with “Approximation” are obtained according to (18) in Theorem 1. Two cases are considered: 1) Case 1: the phase shifts at the RIS are fixed, each of which is randomly generated from a uniform distribution in \((0, 2\pi)\); 2) Case 2: the phase shifts at the RIS are obtained by applying the GA in Algorithm 4 to Problem (33). The parameters of the GA are set as: the population is \( N_{\text{tot}} = 200 \), the number of elites is \( N_e = 10 \), the crossover probability is \( p_c = 0.4 \), the mutation probability is \( p_m = 0.1 \), and the number of the termination iteration times is \( t_T = 2000 \). It can be seen that the approximation curves match well with the simulation curves, which supports the results in Theorem 1. Moreover, it is noted that the sum rates with the optimized phase shifts obtained by Algorithm 4 are better than that with the fixed phase shifts. Furthermore, the sum rates increase with \( M \) in Case 2 with the optimized phase shifts, while for Case 1 with the fixed phase shifts, the sum rates first increase and then tend to be saturated with \( M \). Additionally, the sum rates with \( N = 64 \) are higher than that with \( N = 16 \) in both Case 1 and 2. Therefore, we can improve the performance of the RIS-assisted multi-user massive MIMO system by increasing
Fig. 3. Power scaling laws of the users.

Fig. 4. Sum AR versus the parameter \( \upsilon \) of RIS phase noise.

Fig. 5. Sum AR versus the amplitude parameter \( \kappa \) of RF impairments.

Fig. 6. Sum AR versus the phase parameter \( \eta \) of RF impairments.

In Fig. 3, we investigate the power scaling laws of the users. Two groups of fixed phase shifts are considered, which are obtained by using the GA in Algorithm 4 with \( N = 16 \) and \( N = 64 \) respectively, when \( M = 64 \). We set the power as \( p_k = E_u M \epsilon_k \), \( \forall k \), with fixed \( E_u = 10 \text{ dB} \). The curves marked with “Approximation” in Fig. 3 are obtained according to (26). It can be seen that when the power scaling factor \( \epsilon = 1 \), as \( M \to \infty \), the sum rates converge to zero in both cases with \( N = 16 \) and \( N = 64 \). This is because the transmit power is scaled down too fast with \( M \). Furthermore, when \( \epsilon = 1 \), as \( M \to \infty \), the sum rates converge to non-zero limits in both cases with \( N = 16 \) and \( N = 64 \). It means the system maintains a required performance when the transmit power is scaled down by the factor \( \frac{1}{M} \), which validates our analysis in Section III.

Fig. 4 shows the impacts of the phase noise at the RIS on the sum rates. It can be seen that the sum rates increase as the concentration parameter \( \upsilon \) increases. For both \( N = 16 \) and \( N = 64 \) cases, the increase of the sum rates is rapid when \( \upsilon \) is small, and then slows down when \( \upsilon \) is large. Since the phase noise \( \epsilon_n \) at the unit \( n \) of the RIS follows a Von Mises distribution, a higher concentration parameter \( \upsilon \) means the fluctuation for \( \epsilon_n \) lies in a smaller range. Specifically, when \( \upsilon \to \infty \), we have \( \epsilon_n \to 0 \), which means there is no phase noise at the RIS. Therefore, the sum rates converge to the case without phase noise as the concentration parameter \( \upsilon \) grows to infinity, which is consistent with the results in Fig. 4, where the sum rates first increase and then become saturated as \( \upsilon \) increases.

Fig. 5 and 6 focus on the impacts of RF impairments on the sum rates while setting \( M = 64 \). In Fig. 5, we can find that the sum rates increase with the amplitude parameter \( \kappa \) in both
$N = 16$ and $N = 64$ cases. It should be mentioned that $\kappa = 1$ means RF impairments have no impacts on the amplitude of the receiving signals. Thus, a smaller $\kappa$ stands for severer RF impairments, causing larger reduction of the system performance, as is shown in Fig. 5. In Fig. 6, it is observed that the sum rates decrease with the phase parameter $\eta$ in both $N = 16$ and $N = 64$ cases. This is because when $\eta$ is large, the phase shifts brought by RF impairments would lie in a large range, which leads to poor system performance.

Fig. 7 depicts how the sum rates vary with the ADC quantization bits $b$. It is readily seen that in both $N = 16$ and $N = 64$ cases, the sum rates first increase fast with $b$, and then become saturated. It is well known that the power consumption and hardware cost of wireless systems increase rapidly as ADC quantization bits $b$ increases. Thus, Fig. 7 indicates that we can choose $b = 3$ for the considered system to obtain a balance between system performance, power consumption and hardware cost.

Finally, we make a comparison between the cases with continuous phase shifts and with discrete phase shifts in Fig. 8. The phase shifts for the curves marked with “Discrete” is obtained by applying Algorithm 4 to Problem (36) with discrete phase shifts. The RIS discrete bits $B$ is defined in (36). In practical scenarios, discrete phase shifts are used, while the continuous phase shifts are considered for ideal scenarios. Therefore, it is essential to study the system performance with discrete phase shifts. From Fig. 8, the sum rates with the optimized discrete phase shifts increase as $B$ increases, and converge to that with the optimized continuous phase shifts. It is noted that $B = 6$ and $B = 3$ are reasonable choices for the discrete case with $N = 16$ and $N = 64$, respectively, since they achieve the performance for the corresponding continuous cases, while a higher $B$ leads to more cost.

VI. CONCLUSION

The paper studied an RIS-assisted multi-user uplink massive MIMO system under Rician fading channels and with imperfect hardware at both the RIS and BS. At the RIS, the paper used Von Mises distribution to model the phase noise, while at the BS, the paper adopted EEVM model for RF impairments and AQNM for low-resolution ADCs. Based on that, asymptotic data rates were obtained with infinite $M$ and $N$, when the RIS was aligned to a specific user and when the RIS was aligned to none of the users. Besides, the paper investigated the power scaling laws of the users, and showed that while guaranteeing a required system performance, the transmit power of the users can be scaled down at most by the factor $\frac{1}{M}$ when $M$ goes infinite, or by the factor $\frac{1}{MN}$ when $M$ and $N$ go infinite. Furthermore, an optimization algorithm was proposed based on GA, which can be applied to solve the continuous and discrete phase shift optimization problems for maximizing the sum rates of the system. Numerical results were provided to support the main results. The numerical results revealed that the sum rate of the considered system can be improved by increasing $M$ and $N$. Moreover, the impacts of the parameters of the imperfect hardware on the system performance were revealed. The numerical results also revealed that when $M = 64$, $B = 6$ and $B = 3$ are reasonable choices for the discrete cases with $N = 16$ and $N = 64$, respectively.

It should be aware that the considered system model can be further extended to investigate a more practical scenario. For example, this work considered perfect CSI, while perfect CSI is usually hard to obtain in practical. Furthermore, due to the large number of antennas at BS and reflecting units at RIS, channels are usually correlated with each other in a practical RIS-assisted massive MIMO system. Therefore, the future work would take channel estimation and channel correlation into consideration to provide more insights for RIS-assisted massive MIMO systems.

APPENDIX A
PROOF OF THEOREM 1

First, we review some key preliminary results given in the following lemmas.

**Lemma 1** [45, Lemma 1] If $X = \sum_{i=1}^{t_1} X_i$ and $Y = \sum_{j=1}^{t_2} Y_j$ are both sums of nonnegative random variables $X_i$
and $Y_j$, then we get the following approximation

$$ E\left\{ \log_2 \left( 1 + \frac{X}{Y} \right) \right\} \approx \log_2 \left( 1 + \frac{E\{X\}}{E\{Y\}} \right). $$  

(38)

Note that it is not necessary for the random variables $X$ and $Y$ to be independent. In addition, the approximation becomes more accurate as $t_1$ and $t_2$ increase.

**Lemma 2:** If $\varepsilon$ is a random variable following zero-mean Von Mises distribution with a concentration parameter $\upsilon$, the characteristic function of $\varepsilon$, $E\{e^{\iota \varepsilon}\}$, equals to $\frac{I_1(\upsilon)}{I_0(\upsilon)}$ when $t = 1$. In other words, we have

$$ E\{e^{\iota \varepsilon}\} = \frac{I_1(\upsilon)}{I_0(\upsilon)} \triangleq \rho, $$  

(39)

where $I_n(\upsilon)$ represents the modified Bessel function of the first kind and order $n$.

**Proof:** The Bessel Function of the first kind and order $n$ is given by

$$ J_n(\upsilon) = \frac{1}{2\pi} \int_0^{2\pi} e^{j(\upsilon - n \sin \theta)} d\theta, $$  

(40)

and the corresponding Modified Bessel Function is given by

$$ I_n(\upsilon) = j^{-n} J_n(j\upsilon) = j^{-n} \frac{1}{2\pi} \int_0^{2\pi} e^{j(\upsilon + n \sin \theta)} d\theta. $$  

(41)

When $n = 1$, we can obtain

$$ I_1(\upsilon) = j^{-1} J_1(j\upsilon) = j^{-1} \frac{1}{2\pi} \int_0^{2\pi} e^{j(\upsilon + \sin \theta)} d\theta 
= e^{-j\frac{\upsilon}{2}} \frac{1}{2\pi} \int_0^{2\pi} e^{j(\upsilon - \frac{\upsilon}{2} + \sin \frac{\upsilon}{2})} d\theta 
= \frac{1}{2\pi} \int_0^{2\pi} e^{j(\upsilon - \frac{\upsilon}{2}) + \sin \frac{\upsilon}{2}} d\theta 
= \frac{1}{2\pi} \int_0^{2\pi} e^{j(\upsilon - \frac{\upsilon}{2}) + \cos \frac{\upsilon}{2}} d\theta 
= \frac{1}{2\pi} \int_0^{2\pi} e^{j\upsilon + \cos \frac{\upsilon}{2}} d\theta. $$  

(42)

On the other hand, the PDF of $\varepsilon$ is given by

$$ M_\upsilon(\varepsilon) = \frac{1}{2\pi I_0(\upsilon)} e^{\upsilon \cos \varepsilon}, \quad \varepsilon \in [0, 2\pi). $$  

(43)

Then the characteristic function with $t = 1$ can be calculated as

$$ E\{e^{\iota \varepsilon}\} = \int_0^{2\pi} e^{\iota \varepsilon} M_\upsilon(\varepsilon) d\varepsilon = \int_0^{2\pi} e^{\iota \varepsilon} \frac{1}{2\pi I_0(\upsilon)} e^{\upsilon \cos \varepsilon} d\varepsilon 
= \frac{1}{2\pi I_0(\upsilon)} \int_0^{2\pi} e^{\iota \varepsilon + \upsilon \cos \varepsilon} d\varepsilon = I_1(\upsilon) \frac{I_1(\upsilon)}{I_0(\upsilon)} = \rho. $$  

(44)

From (14), by using Lemma 1, we can obtain (45) at the bottom of this page. Then, we start to derive the expectations in (45) one by one.

Based on (1) and (2), the term $h^H_k \Phi^H_k G^H \chi \Phi \Theta h_k$ can be written as (46) at the bottom of this page, where the matrix $A$ is defined as

$$ A = \Phi^H \left( \delta G^H \chi \bar{G} + \sqrt{\beta} G^H \chi \bar{G} + \sqrt{\beta} \bar{G}^H \chi \bar{G} + \bar{G}^H \chi \bar{G} \right) \Phi. $$  

(47)

Therefore, $E\{|h^H_k \Phi^H_k G^H \chi \Phi \Theta h_k|^2\}$ can be expressed as

$$ E\{h^H_k \Phi^H_k G^H \chi \Phi \Theta h_k \} = \frac{\beta^2 \alpha_k^2}{(\delta + 1)^2 (\mu_k + 1)^2} E\{\sum_{i=1}^{4} \omega_{kk}^2\} 
= \frac{\beta^2 \alpha_k^2}{(\delta + 1)^2 (\mu_k + 1)^2} \left( \sum_{i=1}^{4} E\{|\omega_{kk}^i|^2\} + 2 \sum_{i=1}^{4} \sum_{j=1}^{4} E\{|\omega_{kk}^i \omega_{kk}^j|^2\} \right) \equiv \frac{\beta^2 \alpha_k^2}{(\delta + 1)^2 (\mu_k + 1)^2} \left( \sum_{i=1}^{4} E\{|\omega_{kk}^i|^2\} + 2 \sum_{i=1}^{4} E\{|\omega_{kk}^i \omega_{kk}^j|^2\} \right), $$  

(48)

$$ R_k \approx \bar{R}_k = \log_2 \left( 1 + \frac{p_k \tau^2 E\{|h^H_k \Phi^H_k G^H \chi \Phi \Theta h_k|^2\}}{\sum_{i \neq k} \sum_{L_i} p_i \tau^2 E\{|h^H_k \Phi^H_k G^H \chi \Phi \Theta h_i|^2\} + E\{D_{N_k}\} + E\{A_{N_k}\} + E\{Q_{N_k}\}} \right) $$  

(45)

$$ h^H_k \Phi^H_k G^H \chi \Phi \Theta h_k = h^H_k \Phi^H_k \frac{\beta}{\delta + 1} \left( \delta G^H \chi \bar{G} + \sqrt{\beta} G^H \chi \bar{G} + \sqrt{\beta} \bar{G}^H \chi \bar{G} + \bar{G}^H \chi \bar{G} \right) \Phi \Theta h_k 
= \frac{\beta \alpha_k}{(\delta + 1) (\mu_k + 1)} \left( \sqrt{\mu_k} \bar{h}_k + \Gamma_k^H \right) A \Theta \left( \sqrt{\mu_k} \bar{h}_k + \bar{h}_k \right) 
= \frac{\beta \alpha_k}{(\delta + 1) (\mu_k + 1)} \left( \mu_k \bar{h}_k A \Theta \bar{h}_k + \sqrt{\mu_k} \bar{h}_k A \Theta \bar{h}_k + \sqrt{\mu_k} \bar{h}_k A \Theta \bar{h}_k + \bar{h}_k A \Theta \bar{h}_k \right) $$  

(46)
where step (a) is obtained by removing the zero-expectation terms. Then, we focus on deriving the expectation \( E\{ |\omega_{kk}^1|^2 \} \). Note that
\[
\omega_{kk}^1 = \mu_k \tilde{n}_{kk}^H A \Theta \tilde{n}_k
= \delta \mu_k \bar{h}_{kk}^H \Phi^H \bar{G}^H \chi \Gamma \Phi \Theta \tilde{n}_k + \sqrt{\delta \mu_k \bar{h}_{kk}^H \Phi^H \bar{G}^H \chi \Gamma \Phi \Theta \tilde{n}_k}
+ \sqrt{\delta \mu_k \bar{h}_{kk}^H \Phi^H \bar{G}^H \chi \Gamma \Phi \Theta \tilde{n}_k} + \mu_k \bar{h}_{kk}^H \Phi^H \bar{G}^H \chi \Gamma \Phi \Theta \tilde{n}_k
= \delta \mu_k \omega_{kk}^{1,1} + \sqrt{\delta \mu_k} \omega_{kk}^{1,2} + \sqrt{\delta \mu_k} \omega_{kk}^{1,3} + \mu_k \omega_{kk}^{1,4},
\]
where the term \( \omega_{kk}^{1,1} \) in (49) is expressed as
\[
\omega_{kk}^{1,1} = \kappa f_k^* \sum_{n=1}^M e^{j \varphi_{m,n}} e^{j \varphi_n} f_{k,n},
\]
and \( \omega_{kk}^{1,2}, \omega_{kk}^{1,3} \) and \( \omega_{kk}^{1,4} \) in (49) are respectively expressed as (51)–(53) at the bottom of the page, where the terms \( f_k \) and \( f_{k,n} \) are defined as
\[
f_k \triangleq \sum_{n=1}^N f_{k,n}, \quad f_{k,n} \triangleq a_{N,n} (\phi_{kr}, \varphi_{kr}) e^{j \varphi_n} a_{N,n} (\phi_{kr}, \varphi_{kr}).
\]
Thus, the expectation \( E\{ |\omega_{kk}^{1,1}|^2 \} \) can be calculated as
\[
E \{ |\omega_{kk}^{1,1}|^2 \}
= E \{ \delta \mu_k \omega_{kk}^{1,1} + \sqrt{\delta \mu_k} \omega_{kk}^{1,2} + \sqrt{\delta \mu_k} \omega_{kk}^{1,3} + \mu_k \omega_{kk}^{1,4} \}
= \delta \mu_k^2 E \{ |\omega_{kk}^{1,1}|^2 \} + \delta \mu_k^2 E \{ |\omega_{kk}^{1,2}|^2 \} + \delta \mu_k^2 E \{ |\omega_{kk}^{1,3}|^2 \} + \mu_k^2 E \{ |\omega_{kk}^{1,4}|^2 \} + 2 \delta \mu_k^2 E \{ \text{Re} \omega_{kk} \times \omega_{kk}^* \}.
\]
Step (a) is obtained by removing zero-valued terms. The expectation \( E\{ |\omega_{kk}^{1,1}|^2 \} \) in (55) is further calculated as
\[
E \{ |\omega_{kk}^{1,1}|^2 \} = E \{ |f_k|^2 \sum_{m=1}^M e^{j \varphi_{m,n}} e^{j \varphi_n} f_{k,n} \}
= \kappa^2 |f_k|^2 \left( \sum_{m=1}^M e^{j \varphi_{m,n}} \right)^2 \left( \sum_{n=1}^N e^{j \varphi_n} f_{k,n} \right)^2
= \kappa^2 |f_k|^2 \left( \sum_{m=1}^M e^{j \varphi_{m,n}} \right)^2 \left( \sum_{n=1}^N e^{j \varphi_n} f_{k,n} \right)^2.
\]
Thus,
\[
\omega_{kk}^{1,2} = \kappa f_k^* \sum_{n=1}^M a_{M,n} (\phi_{kr}, \varphi_{kr}) e^{j \varphi_n} \gamma_{mn} e^{j \varphi_n} a_{N,n} (\phi_{kr}, \varphi_{kr})
\omega_{kk}^{1,3} = \kappa f_k^* \sum_{n=1}^M a_{M,n} (\phi_{kr}, \varphi_{kr}) e^{j \varphi_n} \gamma_{mn} e^{j \varphi_n} a_{M,n} (\phi_{kr}, \varphi_{kr})
\omega_{kk}^{1,4} = \kappa f_k^* \sum_{n=1}^M a_{N,n} (\phi_{kr}, \varphi_{kr}) e^{j \varphi_n} \gamma_{mn} e^{j \varphi_n} a_{N,n} (\phi_{kr}, \varphi_{kr})
\]
where scalar \( \tau \) is defined as
\[
\tau \triangleq E \{ e^{j \varphi_{m,n}} \} = \frac{\sin(\varphi)}{\eta} = E \{ e^{j \varphi_{m,n}} \}. \]

The \( \rho \) is given by (39) in Lemma 2. Additionally, it is well known that \( E\{ e^{j \varphi_{m,n}} \} = E\{ e^{j \varphi_{m,n}} \} \), since \( \rho \) is real. The other expectations in (55) can be obtained in a similar way, which are respectively expressed as follows:
\[
E \{ |\omega_{kk}^{1,2}|^2 \} = \kappa^2 MN |f_k|^2,
E \{ |\omega_{kk}^{1,3}|^2 \} = \kappa^2 \rho^2 MN |f_k|^2 + \kappa^2 (1 - \rho^2) MN^2,
E \{ |\omega_{kk}^{1,4}|^2 \} = \kappa^2 MN (\rho^2 N + 1 - \rho^2) + \kappa^2 MN^2,
\]
and
\[
E \{ \text{Re} \omega_{kk} \times \omega_{kk}^* \} = \kappa^2 |f_k|^2 M (\rho^2 N + 1 - \rho^2)
\]

Then, we arrived at (62) at the bottom of the next page. Similar to the calculation for \( E\{ |\omega_{kk}^{1,1}|^2 \} \), the rest expectations in (48) can be obtained as (63)–(66) at the bottom of the next page. Substituting (62)–(66) into (48), we can obtain
\[
E \{ |h_k^H \Phi^H \bar{G}^H \chi \Gamma \Phi \Theta \tilde{n}_k|^2 \}
= \frac{\beta^2 \alpha_k^2 \kappa^2 M}{(\delta + 1)^2 (\mu_k + 1)^2} \times (c_{k,1} + c_{k,2} N^2 + c_{k,3} + c_{k,4}) \triangleq \xi_k,
\]
where the coefficients \( c_{k,1}, c_{k,2}, c_{k,3} \) and \( c_{k,4} \) are respectively given by
\[
c_{k,1} = \rho^2 (\mu_k + \delta + 1)^2 + (1 - \rho^2) \delta^2 \mu_k + \delta^2 \mu_k
\]

where the coefficients \( c_{k,1}, c_{k,2}, c_{k,3} \) and \( c_{k,4} \) are respectively given by
\[
c_{k,1} = \rho^2 (\mu_k + \delta + 1)^2 + (1 - \rho^2) \delta^2 \mu_k + \delta^2 \mu_k
\]
+ (\mu_k + \delta + 2)^2 - \rho^2 (\mu_k + \delta + 1)^2 - 2\rho^2 \delta \mu_k - 2)N
+ \rho^2 \delta^2 \mu_k |f_k|^4 + 2 ((1 - \rho^2) (\mu_k + \delta) + 2) \delta \mu_k |f_k|^2.
(68)

\begin{align*}
c_{k,2} &= \left((1 - \iota^2) (\mu_k + \delta + 1)^2 - \delta \mu_k (\mu_k + 1 + \delta + \iota^2 \delta) \right) \rho^2
+ (\delta + \mu_k + 1) \delta \mu_k + (\mu_k + \delta + 1)^2 - (\mu_k + 1) \iota^2 \delta^2, \\
&= \left((1 - \iota^2) (\mu_k + \delta + 1)^2 - \delta \mu_k (\mu_k + 1 + \delta + \iota^2 \delta) \right) \rho^2
+ (\delta + \mu_k + 1) \delta \mu_k + (\mu_k + \delta + 1)^2 - (\mu_k + 1) \iota^2 \delta^2.
(69)
\end{align*}

Thus, the expectation \( E\{h_k^H\Phi^H G^H \chi G \Phi \Theta h_i\} \) can be expressed as

\begin{align*}
E\left\{h_k^H\Phi^H G^H \chi G \Phi \Theta h_i\right\} &= \frac{\beta^2 \alpha_k \alpha_i}{(\delta + 1)^2 (\mu_k + 1) (\mu_i + 1)} E \left\{ \sum_{s=1}^{4} \omega_{ki}^2 \right\} \\
&\times \left( \sum_{s=1}^{4} E \left\{ \frac{\omega_{ki}^2}{\omega_{ki}} \right\} + 2 \sum_{s=1}^{4} E \left\{ \text{Re} (\omega_{ki}^2 (\omega_{ki})^*) \right\} \right) \\
&= \frac{\beta^2 \alpha_k \alpha_i}{(\delta + 1)^2 (\mu_k + 1) (\mu_i + 1)} \times \sum_{s=1}^{4} E \left\{ \omega_{ki}^2 \right\} \cdot \sum_{s=1}^{4} E \left\{ \omega_{ki}^2 \right\}.
(70)
\end{align*}

Similar to (46), we expand \( h_k^H\Phi^H G^H \chi G \Phi \Theta h_i \) as

\begin{align*}
h_k^H\Phi^H G^H \chi G \Phi \Theta h_i &= \frac{\beta}{\delta + 1} \sqrt{\frac{\alpha_k \alpha_i}{(\mu_k + 1) (\mu_i + 1)}}
\end{align*}

Step (a) in (73) is obtained by removing the zero terms. Again, similar to the calculation for \( E\{\omega_{kk}^4\} \), the expectations in (73) are obtained as (74)–(77) at the bottom of the next page.
Therefore, the expectation \( \mathbb{E}\{ |h_k^H \Phi H G^H \mathbf{G} \Phi \mathbf{h}_i|^2 \} \) can be obtained as
\[
\mathbb{E}\{ |h_k^H \Phi H G^H x G \Phi \mathbf{h}_i|^2 \} = \frac{\kappa^2 \beta^2 \alpha_k \alpha_i M}{(\delta + 1)^2 (\mu_k + 1) (\mu_i + 1)} \times (z_{k,i,1} \mu + z_{k,i,2} N^2 + z_{k,i,3} N + z_{k,i,4}) \triangleq \gamma_{k,i},
\]
(78)
where the coefficients \( z_{k,i,j} = (\mu_j + 1 - \rho^2 \mu_i) \delta^2 \mu_i \) are respectively given by
\[
z_{k,i,1} = (\mu_i + 1 - \rho^2 \mu_i) \delta^2 \mu_i^2
+ \left( (\mu_i + 1 - \rho^2 \mu_i) \delta^2 \mu_k |f_k|^2 + \rho^2 \delta^2 \mu_i |f_i|^2 \right)
+ (\mu_k + 2\delta + 1) (\mu_k + 1 - \rho^2 \mu_i) \mu_k |f_k|^2
+ (2\delta |f_i|^2 + \mu_k \bar{h}_k^H \bar{h}_i |^2 + 2\mu_k \text{Re} \left( f_k^* f_i \bar{h}_k^H \bar{h}_i \right)) \rho^2 \delta^2 \mu_i |f_i|^2,
\]
(79)
\[
z_{k,i,2} = \left( (\delta + 1) \mu_k + (\delta + 1) - \mu_i - 1 \right) \delta^2 \mu_i
- (\mu_k + \delta + 1 - \delta^2) \rho^2 \delta^2 \mu_i - 1,
\]
(80)
\[
z_{k,i,3} = ((1 - \mu_i) \delta (\mu_i + 1 - \rho^2 \mu_i) + \mu_k + 1) \delta \mu_k |f_k|^2
+ ((\mu_k + 1) (\mu_k + \delta + 1) - (\mu_k + 2\delta) \rho^2 \mu_i) (1 - \mu_i)
+ (\mu_k + \delta + 1 - \delta^2) \rho^2 \delta^2 \mu_i |f_i|^2,
\]
(81)
\[
z_{k,i,4} = \left( (\delta |f_i|^2 - 2) \rho^2 \mu_i + 2 \mu_i + 2 \right) (1 - \mu_i - 1) \delta \mu_k |f_k|^2
+ (1 - \mu_i) \rho^2 \mu_k \mu_i \left( \bar{h}_k^H \bar{h}_i \right)^2 + 2\delta \text{Re} \left( f_k^* f_i \bar{h}_k^H \bar{h}_i \right)
+ 2 (1 - \mu_i) \rho^2 \delta \mu_i |f_i|^2,
\]
(82)
Then, we focus on the expectations \( \mathbb{E}\{ \mathbf{D}_N \} \), \( \mathbb{E}\{ \mathbf{A}_N \} \) and \( \mathbb{E}\{ \mathbf{Q}_N \} \). According to (15)–(17), they can be expanded respectively as
\[
\mathbb{E}\{ \mathbf{D}_N \} = \tau^2 \sigma^2 \mathbf{I}_N \left( \right)
\]
(83)
\[
\mathbb{E}\{ \mathbf{A}_N \} = \tau^2 \sigma^2 \mathbf{I}_N \mathbf{A}_N \left( \right)
\]
(84)
\[
\mathbb{E}\{ \mathbf{Q}_N \} = \tau (1 - \tau) \sum_{m=1}^M |s_q|_{mm} \mathbb{E}\{ |h_k^H \Phi H G^H 1_{M,m}^H|^2 \}.
\]
(85)
To obtain the expectations in (83) and (84), we calculate the value of \( \mathbb{E}\{ |h_k^H \Phi H G^H 1_{M,m}^H|^2 \} \), which is shown as follows:
\[
\mathbb{E}\{ |h_k^H \Phi H G^H 1_{M,m}^H|^2 \} = \mathbb{E}\{ h_k^H \Phi H G^H \mathbf{G} \Phi \mathbf{h}_k \}
\]
(86)
where steps (a) and (b) are obtained by substituting (2) and (1) into the derivation respectively and then removing the zero terms. Step (c) is based on the calculation
\[
E\{ |\omega_{k,i}^2| \} = \kappa^2 \delta^2 \mu_k |f_k|^2
+ ((\delta N + 2) \delta |f_k|^2 + N + \rho^2 \delta |f_i|^2 + 2\rho^2 \delta |f_k|^2 + \delta |f_k|^2 + \delta |f_i|^2) \delta \mu_k |f_k|^2
\]
(74)
\[
E\{ |\omega_{k,i}^2| \} = \kappa^2 \delta^2 \mu_k |f_k|^2
+ ((\delta N + 2) \delta |f_k|^2 + N + \rho^2 \delta |f_i|^2 + 2\rho^2 \delta |f_k|^2 + \delta |f_k|^2 + \delta |f_i|^2) \delta \mu_k |f_k|^2
\]
(75)
\[
E\{ |\omega_{k,i}^2| \} = \kappa^2 \delta^2 \mu_k |f_k|^2
+ ((\delta N + 2) \delta |f_k|^2 + N + \rho^2 \delta |f_i|^2 + 2\rho^2 \delta |f_k|^2 + \delta |f_k|^2 + \delta |f_i|^2) \delta \mu_k |f_k|^2
\]
(76)
\[
E\{ |\omega_{k,i}^2| \} = \kappa^2 \delta^2 \mu_k |f_k|^2
+ ((\delta N + 2) \delta |f_k|^2 + N + \rho^2 \delta |f_i|^2 + 2\rho^2 \delta |f_k|^2 + \delta |f_k|^2 + \delta |f_i|^2) \delta \mu_k |f_k|^2
\]
(77)
\[
E \left\{ h_{1,\ldots,M}^H \Phi^H \Phi^H G^H G H_{1,\ldots,m}^H 1_{M,m} \chi G \Phi \Theta s_1 \right\} \\
= E \left\{ h_{1,\ldots,M}^H \Phi^H \Phi^H \left( G^H G H_{1,\ldots,m}^H 1_{M,m} \chi G \Phi \Theta s_1 \right) \right\} \\
= \frac{\kappa^2 \beta}{\delta + 1} E \left\{ \phi_N^a (\phi^a, \phi^\tau) \right\} \sum_{s=1}^{K} \frac{\kappa^2 \beta \alpha_s}{(\delta + 1)(\mu_s + 1)} \left( \mu_s E \left\{ h_{1,\ldots,M}^H (\phi^a, \phi^\tau) \Phi \Theta \Phi \Theta s_1 \right\}^2 + E \left\{ \phi_N^a (\phi^a, \phi^\tau) \Phi \Theta \Phi \Theta s_1 \right\}^2 \right\} + \frac{\beta}{\delta + 1} E \left\{ h_{1,\ldots,M}^H s_1 \right\} \\
= \frac{\kappa^2 \beta \alpha_s}{(\delta + 1)(\mu_s + 1)} \left( \rho^2 \delta \mu_s |f_s|^2 + (1 - \rho^2) \delta \mu_s + \delta + \mu_s + 1 \right) N. \\
\tag{91}
\]

\[
E \left\{ 1_{M,m} \chi G \Phi \Theta \Phi H P x^2 \right\} = \sum_{s=1}^{K} \frac{\kappa^2 \beta \alpha_s}{(\delta + 1)(\mu_s + 1)} \left( \rho^2 \delta \mu_s |f_s|^2 + (1 - \rho^2) \delta \mu_s + \delta + \mu_s + 1 \right) N \right\} \triangleq \zeta \\
\tag{94}
\]

Therefore, from (11), (86) and (94), we can obtain

\[
E \left\{ Q N_k \right\} = \tau(1 - \tau) \sigma_{RF}^2 (\zeta + \sigma^2_{RF} + \sigma^2). \tag{95}
\]

Finally, substituting (67), (78), (88), (89), and (95) into (45), we obtain (18) and complete the proof.

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