Operational one-to-one mapping between coherence and entanglement measures

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We establish a general operational one-to-one mapping between coherence measures and entanglement measures: Any entanglement measure of bipartite pure states is the minimum of a suitable coherence measure over product bases. Any coherence measure of pure states, with extension to mixed states by convex roof, is the maximum entanglement generated by incoherent operations acting on the system and an incoherent ancilla. Remarkably, the generalized CNOT gate is the universal optimal incoherent operation. In this way, all convex-roof coherence measures, including the coherence of formation, are endowed with (additional) operational interpretations. By virtue of this connection, many results on entanglement can be translated to the coherence setting, and vice versa. As applications, we provide tight observable lower bounds for generalized entanglement concurrence and coherence concurrence, which enable experimentalists to quantify entanglement and coherence of the maximal dimension in real experiments.

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I. INTRODUCTION

Quantum entanglement is a crucial resource for many quantum information processing tasks, such as quantum teleportation, dense coding, and quantum key distribution; see Ref. [1] for a review. It is also a useful tool for studying various intriguing phenomena in many-body physics and high-energy physics, such as quantum phase transition and black hole information paradox.

Quantum coherence underlies entanglement and is even more fundamental. It plays a key role in various research areas, such as interference [2–5], laser [2], quantum metrology [6–8], quantum computation [9–12], quantum thermodynamics [13–20], and photosynthesis [21,22]. However, the significance of coherence as a resource was not fully appreciated until the works of Aberg [3] and Baumgratz et al. [23], who studied coherence from the perspective of resource theories [24–29]. Coherence has since found increasing applications and attracted increasing attention. Accordingly, great efforts have been devoted to quantifying coherence, and a number of useful coherence measures have been proposed and studied [3,5,8,11,12,23,28–45]; see Ref. [29] for an overview.

The resource theory of coherence is closely related to the resource theory of entanglement [3,11,23,28–38,46–57]. Many results on coherence theory are inspired by analogs on entanglement theory, including many coherence measures, such as the relative entropy of coherence (equal to the distillable coherence) [3,23,28], coherence of formation (equal to the coherence cost) [3,28,31], and robustness of coherence [33,34]. In addition, coherence transformations under incoherent operations are surprisingly similar to entanglement transformations under local operations and classical communication (LOCC) [28–32,49]. Furthermore, coherence and entanglement can be converted to each other under certain scenarios of special interest [3,11,35,36,46–48,53]. In Refs. [46] and [47], it was shown that any degree of coherence in some reference basis can be converted to entanglement via incoherent operations. In addition, this procedure can induce coherence measures, including the relative entropy of coherence and geometric coherence, from entanglement measures [47]. However, little is known about which measures can be induced in this way beyond a few examples, and the connection between coherence and entanglement is far from clear.

In this paper, we show that any entanglement measure of bipartite pure states is the minimum of a suitable coherence measure over product bases. Conversely, any coherence measure of pure states, with extension to mixed states by convex roof, is equal to the maximum entanglement generated by incoherent operations acting on the system and an incoherent ancilla. Remarkably, the generalized CNOT gate is the universal optimal incoherent operation. In this way, we endow all convex-roof coherence measures with additional operational meanings, including the coherence of formation (3,28,31) and (generalized) coherence concurrence [35,36]. In addition, our work is instrumental in studying interconversion between coherence and entanglement.

By virtue of the connection established here, many results on entanglement detection and quantification can be translated to the coherence setting, and vice versa, which has wide applications in quantum information processing. As an illustration, we provide tight observable lower bounds for the generalized entanglement concurrence [58] in terms of the negativity and robustness of entanglement. In parallel, we also provide tight observable lower bounds for the generalized coherence concurrence [36] in terms of the $l_1$-norm coherence.

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The operation is strictly incoherent if both Kn states are separable states, and free operations are LOCC [1]. Local unitary transformations. Any coherent monotone Cf system B is the maximum of Ef [24–26,29]. In the resource theory of entanglement, free states namely, the set of free operations acting on the system B and an incoherent ancilla A. The generalized CNOT gate is the universal optimal incoherent operation.

and robustness of coherence. Remarkably, these lower bounds can be estimated in a way that is device independent. These results are useful in detecting and quantifying entanglement and coherence of the maximal dimension in real experiments.

The rest of the paper is organized as follows. In Sec. II, we review the general frameworks for constructing entanglement monotones (measures) and coherence monotones (measures) based on the convex roof. In Sec. III, we establish an operational one-to-one mapping between coherence monotones and entanglement monotones based on the convex roof. In Sec. IV, we derive a necessary condition on converting coherence into entanglement. In Sec. V, we derive tight observable lower bounds for the generalized entanglement concurrence and coherence concurrence. Section VI summarizes this paper.

The Appendices provide additional details on entanglement monotones, coherence monotones, coherence transformations under incoherent operations (including the majorization criterion), and some technical proofs.

II. PRELIMINARIES

A. Basic concepts

A resource theory is characterized by two basic ingredients, namely, the set of free states and the set of free operations [24–26,29]. In the resource theory of entanglement, free states are separable states, and free operations are LOCC [1]. In the case of coherence, free states are incoherent states, which correspond to density matrices that are diagonal in the reference basis, and free operations are incoherent operations (IO). Recall that an operation with Kraus representation \( \{ K_n \} \) is incoherent if each Kraus operator is incoherent in the sense that \( K_n^\dagger K_n \) is incoherent whenever \( \rho \) is [3,23,28,29]. The operation is strictly incoherent if both \( K_n \) and \( K_n^\dagger \) are incoherent; the set of such operations is denoted by SIO.

A central question in any resource theory is to quantify the utility of resource states, states that are not free [24–26,29]. Here are four typical requirements for a coherence measure C [23,29] (the counterpart for entanglement is analogous): (C1) nonnegativity \( C(\rho) \geq 0 \) (usually \( C(\rho) = 0 \) for incoherent states); (C2) monotonicity under any incoherent operation \( \Lambda \), \( C(\Lambda(\rho)) \leq C(\rho) \); (C3) monotonicity under any selective incoherent operation \( \{ K_n \}, \sum_n p_n C(\sigma_n) \leq C(\rho) \), where \( \sigma_n = K_n \rho K_n^\dagger / p_n \) with \( p_n = \text{tr}(K_n \rho K_n^\dagger) \); and (C4) convexity, \( \sum_j q_j C(\rho_j) \geq C(\sum_j q_j \rho_j) \). Note that (C2) follows from (C3) and (C4). A coherence monotone satisfies (C2-4), while a coherence measure satisfies all (C1-4).

B. Entanglement monotones and coherence monotones based on the convex roof

Before discussing the connection between coherence and entanglement, it is instructive to review the general framework for constructing entanglement monotones introduced by Vidal [59] and its analog for coherence [30]. Let \( \mathcal{H} \) be a \( d \times d \) bipartite Hilbert space. Denote by \( \mathcal{F}_{\text{sc}} \) the set of real symmetric concave functions on the probability simplex. Given any \( f \in \mathcal{F}_{\text{sc}} \), an entanglement monotone for \( |\psi \rangle \in \mathcal{H} \) can be defined as

\[
E_f(\psi) := f(\lambda(\psi)),
\]

where \( \lambda(\psi) \) is the Schmidt vector of \( \psi \), that is, the vector of Schmidt coefficients (eigenvalues of each reduced density matrix), which form a probability vector. The monotone extends to mixed states by the convex roof,

\[
E_f(\rho) := \min_{\{\psi_j\}} \sum_j p_j E_f(\psi_j),
\]

where the minimum (or infimum) is taken over all pure state decompositions \( \rho = \sum_j p_j |\psi_j\rangle \langle \psi_j| \). The extension to systems with different local dimensions is straightforward. The connection between entanglement monotones and symmetric concave functions is summarized in Theorem 1 below, a variant of the result in Ref. [59], but tailored to highlight the connection with coherence monotones; see Appendix A for background and a proof.

**Theorem 1.** For any \( f \in \mathcal{F}_{\text{sc}} \), the function \( E_f \) defined by Eqs. (1) and (2) is an entanglement monotone. Conversely, the restriction to pure states of any entanglement monotone is identical to \( E_f \) for certain \( f \in \mathcal{F}_{\text{sc}} \).

Interestingly, coherence monotones for pure states are also in one-to-one correspondence with symmetric concave functions on the probability simplex [30]. Given any \( f \in \mathcal{F}_{\text{sc}} \), a coherence monotone on \( d \)-dimensional pure states can be defined as follows:

\[
C_f(\psi) := f(\mu(\psi)),
\]

where \( \mu(\psi) = (|\psi_0|^2, |\psi_1|^2, \ldots, |\psi_{d-1}|^2)^T \) is the coherence vector, and \( \psi_j \) are the components of \( \psi \) in the reference basis. For mixed states,

\[
C_f(\rho) := \min_{\{\psi_j\}} \sum_j p_j C_f(\psi_j).
\]

This construction is summarized in Theorem 2 below, which is applicable when either IO or SIO is taken as the set of free operations. The result concerning IO was first presented in Ref. [30]; the original proof has a gap but can be filled. A simple proof was given in Appendix B, which also leads
to a simple proof of the majorization criterion on coherent transformations [49].

Theorem 2. For any \( f \in \mathcal{F}_c \), the function \( C_f \) defined by Eqs. (3) and (4) is a coherence monotone. Conversely, the restriction to pure states of any coherence monotone is identical to \( C_f \) for certain \( f \in \mathcal{F}_c \).

Theorems 1 and 2 provide many useful entanglement and coherence measures. When \( f(p) = -\sum p_j \log_2 p_j \) denotes the Shannon entropy, \( E_f \) is the entanglement of formation \( E_F \) (coinciding with the relative entropy of entanglement \( E_F \) for pure states) [1], and \( C_f \) is the coherence of formation \( C_V \) [3,31] (equal to the coherence cost \( C_{G} \) [28]). When \( f(p) = d(\prod p_j)^{1/d} \), \( E_f \) and \( C_f \) reduce to the generalized entanglement concurrence [58] and coherence concurrence [36]. These measures play important roles in theoretical studies and practical applications, so a number of methods have been developed to compute or approximate them [60–64].

III. OPERATIONAL ONE-TO-ONE MAPPING BETWEEN COHERENCE MEASURES AND ENTANGLEMENT MEASURES

The similarity between entanglement monotones and coherence monotones reflected in Theorems 1 and 2 calls for a simple explanation. Here we shall reveal the operational underpinning of this resemblance.

Our study benefits from the theory of majorization [65,66], which has found extensive applications in quantum informatics and geometry [30,49,56,67–71]. Given two \( d \)-dimensional real vectors \( x = (x_0, x_1, \ldots, x_{d-1})^T \) and \( y = (y_0, y_1, \ldots, y_{d-1})^T \), vector \( x \) is majorized by \( y \), written as \( x \prec y \) or \( y \succ x \), if

\[
\sum_{j=0}^{k} x_j^i \leq \sum_{j=0}^{k} y_j^i \quad \forall k = 0,1, \ldots, d-1, \tag{5}
\]

with equality for \( k = d-1 \). Here \( x^i \) denotes the vector obtained by arranging the components of \( x \) in decreasing order. In this work, we need to consider majorization relations between vectors of different dimensions. In such cases, it is understood implicitly that the vector with fewer components is padded with a number of “0” to match the other vector. The notation \( x \prec y \) means that \( x \prec y \) and \( y \succ x \), so that \( x \) and \( y \) have the same nonzero components up to permutations.

A. Entanglement as minimal coherence

Now we clarify the relation between coherence and entanglement for a bipartite state \( | \psi \rangle \) in the Hilbert space \( \mathcal{H} = \mathcal{H}_B \otimes \mathcal{H}_A \) of dimension \( d_B \times d_A \). The reference basis is the tensor product of respective reference bases. Denote by \( E_{\Lambda}(\psi) \) the Schmidt rank of \( \psi \) and \( C_{\Lambda}(\psi) \) the coherence rank (number of nonzero components of \( \mu(\psi) \)).

Lemma 1. \( \mu(\psi) \prec \lambda(\psi) \) and \( C_{\Lambda}(\psi) \geq E_{\Lambda}(\psi) \) for any \( | \psi \rangle \in \mathcal{H}_B \otimes \mathcal{H}_A \). If \( \mu(\psi) \simeq \lambda(\psi) \), then \( C_{\Lambda}(\psi) = E_{\Lambda}(\psi) \), and vice versa; both of them hold if and only if \( | \psi \rangle \) has the form

\[
| \psi \rangle = \sum_j \sqrt{\lambda_j(\psi)} \varphi_{1j}^0 | \pi_1(j)\pi_2(j) \rangle, \tag{6}
\]

where \( \theta_j \) are arbitrary phases, and \( \pi_1, \pi_2 \) are permutations of basis states of \( \mathcal{H}_B, \mathcal{H}_A \), respectively.

Lemma 1 is proved in Appendix C. It implies that \( \mu(U_1 \otimes U_2)(\psi) \prec \lambda(\psi) \) for arbitrary local unitaries \( U_1, U_2 \), where \( U_1, U_2 \) denote the channels corresponding to \( U_1, U_2 \). In addition,

\[
\max_{U_1, U_2} \mu^{1/2}(U_1 \otimes U_2)(\psi) \simeq \lambda^{1/2}(\psi). \tag{7}
\]

Here the maximization is taken with respect to the majorization order, which is well defined, as guaranteed by Lemma 1 and the Schmidt decomposition. In this way, Lemma 1 offers an appealing interpretation of the Schmidt vector in terms of the coherence vector.

Theorem 3. For any \( f \in \mathcal{F}_c \),

\[
E_f(\rho) \leq \min_{U_1, U_2} \sup_{| \psi \rangle} C_f(U_1 \otimes U_2 \rho (U_1 \otimes U_2)^{\dagger}) \quad \forall \rho; \tag{8}
\]

the inequality is saturated if \( \rho \) is pure.

The bound in Eq. (8) is also saturated by maximally correlated states [28,47,72] according to Theorem 4 below.

Proof. If \( \rho = | \psi \rangle \langle \psi | \) is pure, then \( \mu(\psi) \prec \lambda(\psi) \) by Lemma 1, so \( E_f(\rho) = f(\lambda(\psi)) \leq f(\mu(\psi)) = C_f(\rho) \) since \( f \) is concave and thus Schur concave. This result confirms Eq. (8) for pure states since entanglement is invariant under local unitary transformations. The inequality is saturated thanks to the Schmidt decomposition.

Now suppose \( \rho \) is a mixed state with an optimal decomposition \( \rho = \sum p_j \rho_j \) with respect to \( C_f \). (For simplicity, here we assume that the value of \( C_f(\rho) \) can be attained by some decomposition of \( \rho \), but this assumption is not essential to completing the following proof.) Then

\[
C_f(\rho) = \sum_j p_j C_f(\rho_j) \geq \sum_j p_j E_f(\rho_j) \geq E_f(\rho), \tag{9}
\]

from which Eq. (8) follows.

B. Coherence as maximal entanglement

In contrast with Theorem 3, in this section we show that every coherence monotone of pure states, with extension to mixed states by convex roof, is the maximum entanglement generated by incoherent operations acting on the system and an incoherent ancilla.

This line of research is inspired by a recent work of Streltsov et al. [47], according to which any coherent state on \( \mathcal{H}_B \) can generate entanglement under incoherent operations acting on the system and an incoherent ancilla. Moreover, the maximum entanglement \( E \) generated with respect to any given entanglement monotone defines a coherence monotone \( C_E \) as follows:

\[
C_E(\rho) := \lim_{d_{\Lambda} \to \infty} \left\{ \sup_{\Lambda} E(\Lambda_1|\rho \otimes |0\rangle\langle 0|) \right\}, \tag{10}
\]

Here \( d_{\Lambda} \) is the dimension of the ancilla, and the supremum runs over all incoherent operations. Interestingly, \( C_E = C_c, C_G \) when \( E = E_c, E_G \). However, little is known about other coherence monotones so constructed.
By Eq. (10), we can introduce another coherence monotone for any symmetric concave function $f \in \mathcal{F}_{sc}$:
\[
\hat{C}_f(\rho) := C_{E_f} := \lim_{d_{\lambda} \to \infty} \left\{ \sup \left\{ E_f(\Lambda_1[\rho \otimes |0\rangle\langle 0|]) \right\} \right\}.
\]
(11)

Surprisingly, $\hat{C}_f(\rho)$ coincides with $C_f$ for any $f \in \mathcal{F}_{sc}$. A key to establishing this result is the generalized CNOT gate $U_{\text{CNOT}}$ corresponding to the unitary $C_{\text{CNOT}}$:
\[
U_{\text{CNOT}}|jk\rangle = \left\{ \begin{array}{ll} |j(j + k)\rangle & k < d_B, \\
|jk\rangle & k \geq d_B,
\end{array} \right.
\]
(12)
where the addition is modulo $d_B$. This operation (defined when $d_A \geq d_B$) turns any state $\rho = \sum_{jk} \rho_{jk} |j\rangle \langle k|$ on $\mathcal{H}_B$ into a maximally correlated state [28,47,72].
\[
\rho_{\text{MC}} := U_{\text{CNOT}}|0\rangle\langle 0| = \sum_{jk} \rho_{jk} |j\rangle \langle k|.
\]
(13)

Theorem 4. $E_f(\rho_{\text{MC}}) = C_f(\rho_{\text{MC}}) = C_f(\rho) = \hat{C}_f(\rho)$ for any $f \in \mathcal{F}_{sc}$.

Proof. The equality $C_f(\rho_{\text{MC}}) = C_f(\rho)$ is clear from the definition of $\rho_{\text{MC}}$. The equality $E_f(\rho_{\text{MC}}) = C_f(\rho)$ follows from the fact that any |Ψ⟩ in the support of $\rho_{\text{MC}}$ has the form |Ψ⟩ = $\sum_j c_j |j\rangle$ with $\sum_j |c_j|^2 = 1$, so that $E_f(|Ψ⟩) = C_f(|Ψ⟩)$. Therefore, $C_f(\rho) = E_f(\rho_{\text{MC}}) \leq C_f(\rho)$. The converse $C_f(\rho) \leq C_f(\rho)$ holds because
\[
E_f(\Lambda_1[\rho \otimes |0\rangle\langle 0|]) \leq C_f(\Lambda_1[\rho \otimes |0\rangle\langle 0|]) \leq C_f(\rho) \leq C_{E_f}(\rho) \leq C_f(\rho),
\]
(14)
where the first inequality follows from Theorem 3 and the second one from the monotonicity of $C_f$.

Theorem 4 endows every coherence monotone of pure states with an operational meaning as the maximal entanglement that can be generated between the system and an incoherent ancilla under incoherent operations. This connection extends to all coherence monotones of mixed states that are based on the convex roof. Remarkably, the generalized CNOT gate is optimal with respect to all these monotones, which further implies that SIO and IO are equally powerful for entanglement generation. Theorems 3 and 4 together establish a one-to-one mapping between coherence monotones and entanglement monotones based on the convex roof, as illustrated in Fig. 1. Recently, this mapping was extended to many other monotones which are not based on the convex roof [73,74].

Theorem 4, in particular, applies to measures based on Rényi $\alpha$ entropies $f(\rho) = (\log_2 \sum_j p_j^{\alpha})(1 - \alpha)$ with $0 \leq \alpha \leq 1$ [30,32,59], which play a key role in catalytic entanglement and coherence transformations [70,71]. The limit $\alpha \to 1$ recovers the relation $E_C(\rho_{\text{MC}}) = E_F(\rho_{\text{MC}}) = C_f(\rho)$ [28]. Theorem 4 also implies $E_G(\rho_{\text{MC}}) = C_G(\rho)$ [47].

Moreover, the generalized CNOT gate is the universal optimal incoherence operation. This conclusion was known for the geometric measure [47], but our proof is simpler even in this case.

The power of Theorem 4 is not limited to entanglement monotones based on the convex roof. It provides a nontrivial upper bound on entanglement generation for every entanglement monotone $E$. Note that when restricted to pure states, $E$ is determined by a symmetric concave function $f_E \in \mathcal{F}_{sc}$, which in turn defines an entanglement monotone $\hat{E} := E_{f_E}$, usually referred to as the convex roof (or convex-roof extension) of $E$. For example, $E_F$ is the convex roof of $E_C$. By construction, $\hat{E}(\sigma) \geq E(\sigma)$ for any bipartite state $\sigma$ (with equality for pure states), so $C_E(\rho) \leq C_{E_F}(\rho) = C_{f_E}(\rho)$. The same idea can also extend the scope of Theorem 3.

As another extension, Theorems 3 and 4 still apply if $E_f,C_f$ are replaced by $h(E_f),h(C_f)$, with $h$ a real function that is monotonically increasing. In addition, the constructions in Eqs. (1)–(4) can be extended to functions $f$ that are Schur concave but not necessarily concave; the resulting quantifiers $E_f,C_f$ are not necessarily full monotones but are useful in some applications [69–71]. Theorem 3 holds as before, and so do the equalities $E_f(\rho_{\text{MC}}) = C_f(\rho_{\text{MC}}) = C_f(\rho)$ in Theorem 4.

IV. CONVERTING COHERENCE INTO ENTANGLEMENT

As an application of the results presented in the previous section, here we derive a necessary condition on converting coherence into entanglement with incoherent operations, which is sufficient in a special case. We also derive an upper bound on the conversion probability when there is no deterministic transformation.

Theorem 5. Suppose $|\phi⟩⟨\Phi| = \Lambda_1[|\psi⟩⟨\psi| \otimes |0⟩⟨0|]$, with $\Lambda_1$ being an incoherent operation. Then $\lambda(\Phi) > \mu(\psi)$. If $|\Phi⟩$ has Schmidt form in the reference basis, that is, $|\Phi⟩ = \sum_j \sqrt{\lambda_j} |j\rangle j⟩$ with $\lambda_j \geq 0$ and $\sum_j \lambda_j = 1$, then $|\phi⟩$ can transform to $|\phi⟩$ under IO or SIO iff $\lambda(\Phi) > \mu(\psi)$.

Proof. By Lemma 1, $\lambda(\Phi) > \mu(\Phi) > \mu(\psi)$, where the second inequality follows from the coherence analog of the majorization criterion [49,67]; cf. Theorem 10 in Appendix B.

When $|\phi⟩ = \sum_j \sqrt{\lambda_j} |j\rangle j⟩$, let $|\phi⟩ = \sum_j \sqrt{\lambda_j} |j\rangle j⟩$. If $\lambda(\Phi) > \mu(\psi)$, then $\mu(\psi) > \mu(\psi)$, so $|\psi⟩$ can transform to $|\phi⟩$ under SIO [49] (cf. Theorem 10), which implies the theorem given that $|\Phi⟩ = U_{\text{CNOT}}(|\phi⟩ ⟨\phi|)$.

Theorem 6. Let $P(\psi \to \Phi)$ be the maximal probability of generating $|\Phi⟩$ from $|\psi⟩$ by IO (or SIO) acting on the system and an incoherent ancilla. Then
\[
P(\psi \to \Phi) \leq \min_{m \geq 0} \frac{\sum_{j \geq m} \mu_j^\dagger(\psi)}{\sum_{j \geq m} \lambda_j^\dagger(\Phi)}.
\]
(15)
with equality if $|\Phi⟩$ has the Schmidt form $\sum_j \sqrt{\lambda_j} |j\rangle j⟩$.

Theorem 6 implies that the Schmidt rank of $|\Phi⟩$ cannot exceed the coherence rank of $|\psi⟩$, even probabilistically.

Proof. Define $f_m(\rho) = \sum_{j \geq m} p_j^\alpha$ for positive integers $m$. Then $E_{f_m}$ and $C_{f_m}$ are entanglement measures and coherence measures according to Theorems 1 and 2; cf. Refs. [59] and [30]. Therefore,
\[
P(\psi \to \Phi) \leq \frac{C_{f_m}(\psi)}{C_{f_m}(\psi)} \leq \frac{C_{f_m}(\psi)}{E_{f_m}(\Phi)} \leq \sum_{j \geq m} \frac{\mu_j^\dagger(\psi)}{\sum_{j \geq m} \lambda_j^\dagger(\Phi)},
\]
(16)
which verifies Eq. (15), since $\sum_{j \geq m} \lambda_j^\dagger(\Phi) = \sum_{j \geq m} \mu_j^\dagger(\Phi)$.

When $|\Phi⟩ = \sum_j \sqrt{\lambda_j} |j\rangle j⟩$, let $\phi = \sum_j \sqrt{\lambda_j} |j\rangle j⟩$. Then $|\Phi⟩ = U_{\text{CNOT}}(|\phi⟩ \otimes |0⟩)$. Therefore
\[
P(\psi \to \Phi) \geq P(\psi \to \Phi) = \min_{m \geq 0} \frac{\sum_{j \geq m} \mu_j^\dagger(\psi)}{\sum_{j \geq m} \mu_j^\dagger(\psi)}.
\]
(17)
Here \( P(\psi \to \phi) \) is the maximal probability of transforming \(|\psi\rangle \) to \(|\phi\rangle \) under IO (or SIO), which was determined in Ref. [30]; cf. Theorem 11 in Appendix B. So the inequality in Eq. (15) is saturated given that \( \mu(\phi) \simeq \lambda(\Phi) \).

V. LOWER BOUNDS ON GENERALIZED COHERENCE CONCURRENCE AND ENTANGLEMENT CONCURRENCE

The connection between coherence and entanglement established in this work is useful not only to theoretical studies of resource theories, but also to practical applications in quantum information processing. By virtue of this connection, many results on entanglement detection and quantification can be translated to the coherence setting, and vice versa. As an illustration, we provide tight observable lower bounds for the generalized entanglement concurrence \( E_{\text{gc}} \) [58] and its coherence analog \( C_{\text{gc}} \) [36], which correspond to the convex-roof measures \( E_f \) and \( C_f \) with \( f(p) = d([\prod_i p_i]^{1/d}) \). Note that the definitions of \( E_{\text{gc}} \) and \( C_{\text{gc}} \) depend explicitly on the dimension, unlike most other measures considered in this paper. The measure \( E_{\text{gc}} \) quantifies entanglement of the maximal dimension and may serve as a dimension witness. The analog \( C_{\text{gc}} \) is equally important in the study of coherence.

Before presenting our main result in this section, we need to review a few coherence and entanglement measures. The \( l_1 \)-norm coherence

\[
C_{\text{li}}(\rho) := \sum_{j \neq k} |\rho_{jk}| = \sum_{j,k} |\rho_{jk}| - 1
\]  

is the simplest and one of the most useful coherence measures [23]. The robustness of coherence is an observable coherence measure defined as

\[
C_{\text{R}}(\rho) := \min \left\{ \frac{C_{\text{R}}(\rho)}{\text{tr}[\rho^{T_A}]} - 1 \right\},
\]

where \( \mathcal{I} \) denotes the set of incoherent states. It has an operational interpretation in connection with the task of phase discrimination [33,34]. When \( \rho \) is pure, it is known that \( C_{\text{R}}(\rho) = C_{\text{li}}(\rho) \) [34,74].

The negativity of a bipartite state \( \rho \) shared by B and A reads

\[
\mathcal{N}(\rho) := \text{tr}[\rho^{T_A}] - 1,
\]

where \( T_A \) denotes the partial transpose on subsystem A. (The definition in some literature differs by a factor of 2.) It is essentially the only useful entanglement measure that is easily computable in general [1]. The robustness of entanglement is defined as

\[
E_{\text{R}}(\rho) := \min \left\{ \frac{E_{\text{R}}(\rho)}{\text{tr}[\rho^{T_A}]} - 1 \right\},
\]

where \( \mathcal{S} \) denotes the set of separable states. This measure has two variants: \( \sigma \) is required to be separable in one variant but could be arbitrary in the other variant [1]. When \( \rho \) is pure, both variants are equal to the negativity. Theorem 8 below is applicable to both cases.

A. Tight observable lower bounds

**Theorem 7.** Any state \( \rho \) in dimension \( d \) satisfies

\[
C_{\text{gc}}(\rho) + (d - 2) \geq \hat{C}_{\text{li}}(\rho) \geq C_{\text{li}}(\rho) \geq C_{\text{R}}(\rho).
\]  

**Proof of Theorem 7.** The inequality \( \hat{C}_{\text{li}}(\rho) \geq C_{\text{li}}(\rho) \) follows from the convexity of \( C_{\text{li}} \) and the definition of the convex roof. The inequality \( C_{\text{li}}(\rho) \geq C_{\text{R}}(\rho) \) was derived in Ref. [34].

To prove the inequality \( C_{\text{gc}}(\rho) + (d - 2) \geq \hat{C}_{\text{li}}(\rho) \), it suffices to consider the case in which \( \rho \) is pure because both \( C_{\text{gc}}(\rho) \) and \( \hat{C}_{\text{li}}(\rho) \) are based on the convex roof. Let \( \rho = |\psi\rangle\langle\psi| \) with \( |\psi\rangle = \sum_j c_j |j\rangle \) and \( \sum_j |c_j|^2 = 1 \). Then we have

\[
E_{\text{R}}(\rho) + (d - 2) = d \left( \sum_j |c_j|^2 \right)^{2/d} + (d - 2) \geq \left( \sum_j |c_j|^2 \right)^2 - 1 = C_{\text{li}}(\rho) = \hat{C}_{\text{li}}(\rho),
\]

where the inequality follows from Lemma 2 below.

**Proof of Theorem 8.** The inequality \( \hat{N}(\rho) \geq N(\rho) \) is obvious. The inequality \( \hat{N}(\rho) \geq E_{\text{R}}(\rho) \) follows from the fact that the negativity and robustness of entanglement are convex and that they coincide on pure states, so they share the same convex roof, that is, \( \hat{N}(\rho) = E_{\text{R}}(\rho) \).

To prove the inequality \( E_{\text{R}}(\rho) + (d - 2) \geq \hat{N}(\rho) \), it suffices to consider the case in which \( \rho \) is pure, as in the proof of Theorem 7. Applying a local unitary transformation if necessary, we may assume that \( \rho \) has the form \( \rho = |\Psi\rangle\langle\Psi| \).
with |Ψ⟩ = ∑|j⟩cj|jj⟩, so that ρ is maximally correlated. Let

\[ ρ = |Ψ⟩⟩⟨Ψ| = ∑|j⟩cj|jj⟩. \]

Then it is straightforward to verify that \( E_{gc}(\rho) = C_{gc}(\rho) \) (cf. Theorem 4) and \( N(\rho) = C_{\bar{I}}(\rho) \). Now the inequality \( E_{gc}(\rho) + (d − 2) ≥ \hat{N}(\rho) \) follows from Theorem 7.

The following lemma was essentially proved in the Supplemental Material of Ref. [63], though this result was not highlighted there. See Appendix D for a self-contained proof.

**Lemma 2.** Any sequence of \( d \) complex numbers

\[ c_0, c_1, \ldots, c_{d−1} \]

satisfies

\[ d \prod_j |c_j|^2 ≥ \left( \sum_j |c_j|^2 \right)^2 − (d − 1) \sum_j |c_j|^2. \]

When \( d ≥ 3 \), the inequality is saturated iff all \( |c_j| \) are equal, or all of them are equal except for one of them, which equals 0.

**B. Generalized concurrence of states with high symmetry**

In this section we derive generalized coherence concurrence and entanglement concurrence of certain states with high symmetry and thereby show that the lower bounds for \( C_{gc}(\rho) \) and \( E_{gc}(\rho) \) established in Theorems 7 and 8 are tight.

Let \( ρ \) be a convex combination of the maximally coherent state and the completely mixed state in dimension \( d \), that is,

\[ ρ = p(|Ψ⟩⟨Ψ|) + (1 − p) I/d, \]

with \( 0 ≤ p ≤ 1 \). Let \( F := ⟨Ψ|ρ|Ψ⟩ = p + \frac{1−p}{d} \) be the fidelity between \( ρ \) and \(|Ψ⟩⟨Ψ|⟩ \), then \( 1/d ≤ F ≤ 1 \). The following proposition is proved in Appendix E.

**Proposition 1.** The state \( ρ \) in Eq. (26) with \( 0 ≤ p ≤ 1 \) satisfies

\[ \hat{C}_{\bar{I}}(\rho) = C_{\bar{I}}(\rho) = C_{\bar{F}}(\rho) = p(d−1) = dF − 1, \]

\[ E_{gc}(\rho) = max\{0, p(d−1)−(d−2)\} \]

\[ = max\{0, dF − (d−1)\}. \]

Proposition 1 shows that all the inequalities in Eq. (22) of Theorem 7 are saturated by the state \( ρ \) in Eq. (26) with \( (d−2)/(d−1) ≤ p ≤ 1 \), that is, \( (d−1)/d ≤ F ≤ 1 \).

Next, we show that all the inequalities in Theorem 8 are saturated by isotropic states with sufficiently high purity. Let \( ρ \) be an isotropic state in dimension \( d × d [1] \), which has the form

\[ ρ = p(|Ψ⟩⟨Ψ|) + (1 − p) I/d, \]

with \( 0 ≤ p ≤ 1 \). Let \( F := ⟨Ψ|ρ|Ψ⟩ = p + \frac{1−p}{d} \) be the fidelity between \( ρ \) and \(|Ψ⟩⟨Ψ|⟩ \). Then \( 1/d^2 ≤ F ≤ 1 \) and

\[ ρ = F(|Ψ⟩⟨Ψ|) + (1 − F) \frac{I − |Ψ⟩⟨Ψ|}{d^2 − 1}. \]

The following proposition is an analog of Proposition 1. Here Eq. (32) follows from Ref. [63]; Eq. (31) should also be known before. See Appendix E for a self-contained proof.

**Proposition 2.** The state \( ρ \) in Eq. (30) with \( F ≥ 1/d^2 \) satisfies

\[ N(\rho) = \hat{N}(\rho) = E_{\bar{F}}(\rho) = max\{0, F(d−1)\}, \]

\[ E_{gc}(\rho) = max\{0, dF − (d−1)\}. \]

Proposition 2 shows that all the inequalities in Eq. (23) of Theorem 8 are saturated by the state \( ρ \) in Eq. (30) with \( (d−1)/d ≤ F ≤ 1 \).

**VI. SUMMARY**

In summary, we established a general operational one-to-one mapping between coherence measures and entanglement measures. Any entanglement measure of bipartite pure states is the minimum of a suitable coherence measure over product bases; any coherence measure of pure states, with extension to mixed states by the convex roof, is the maximum entanglement generated by incoherent operations acting on the system and an incoherent ancilla. Besides its foundational significance in bridging the two resource theories, this connection has wide applications in quantum information processing. Thanks to this connection, many results on entanglement can be generalized to the coherence setting, and vice versa. As an illustration, we provided tight observable lower bounds for generalized entanglement concurrence and coherence concurrence, which enable experimentalists to quantify entanglement and coherence of the maximal dimension in real experiments.

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**APPENDIX A: ENTANGLEMENT MONOTONES**

In this Appendix, we provide additional details on the connection between entanglement monotones and symmetric concave functions on the probability simplex. We then prove Theorem 1 in the main text, which is a variant of a result first established by Vidal [59]. This result is now well known among the experts, but some subtlety discussed here may be helpful to other readers.

Denote by \( T(C^d) \) the space of density matrices on \( C^d \) and \( U(d) \), the group of unitary operators on \( C^d \). Let \( \mathcal{F}_0 \) be the set of

\[ \{ \rho \otimes \sigma : \rho ∈ T(C^d), \sigma ∈ U(d) \}. \]

The states in \( \mathcal{F}_0 \) are mapped by tensoring a pure state of \( C^d \) with a unitary of \( U(d) \) to states of \( C^d \) that are completely mixed.

\[ \mathcal{F}_0 = \{ \rho \otimes \sigma : \rho ∈ T(C^d), \sigma ∈ U(d) \}. \]
unitarily invariant functions on the space of density matrices. We assume that each function \( f \in \mathcal{F}_d \) is defined on \( T(C^d) \) for each positive integer \( d \). For given \( d \), the function satisfies
\[
 f(UpU^\dagger) = f(\rho) \quad \forall \rho \in T(C^d), \quad U \in U(d). \tag{A1}
\]
So \( f(\rho) \) is a function of the eigenvalues of \( \rho \). We also assume implicitly that the number of “0” in the spectrum of \( \rho \) does not affect the value of \( f(\rho) \). Let \( \mathcal{F}_{ac} \subset \mathcal{F}_d \) be the set of unitarily invariant real concave functions on the space of density matrices. For given \( d \), each function \( f \in \mathcal{F}_{ac} \) satisfies Eq. (A1), and in addition,
\[
 f[\rho_1 + (1 - p)\rho_2] \geq pf(\rho_1) + (1 - p)f(\rho_2)
\]
\[
 \forall \rho_1, \rho_2 \in T(C^d), \quad 0 \leq p \leq 1. \tag{A2}
\]
Let \( \mathcal{H} = C^d \otimes C^d \) be a bipartite Hilbert space shared by \( B \) and \( A \). For simplicity, here we assume that the Hilbert spaces for the two subsystems have the same dimension \( d \), but this is not essential. Any function \( f \in \mathcal{F}_{ac} \) can be used to construct an entanglement monotone \( E_f \) on \( T(\mathcal{H}) \) as follows [59]. For a pure state \( |\psi\rangle \in \mathcal{H} \),
\[
 E_f(\psi) := f(\text{tr}_A(|\psi\rangle\langle\psi|)). \tag{A3}
\]
The monotone is then extended to mixed states \( \rho \in T(\mathcal{H}) \) by the convex roof,
\[
 E_f(\rho) := \min_{\{p_i, \rho_i\}} \sum_f p_i E_f(\rho_i), \tag{A4}
\]
where the minimization runs over all pure state ensembles of \( \rho \) for which \( \rho = \sum_i p_i \rho_i \).

The following theorem is reproduced from Ref. [59], where the reader can find a detailed proof.

**Theorem 9.** For any \( f \in \mathcal{F}_{ac} \), the function \( E_f \) defined by Eqs. (A3) and (A4) is an entanglement monotone. Conversely, the restriction to pure states of any entanglement monotone is identical to \( E_f \) for certain \( f \in \mathcal{F}_{ac} \).

Next we clarify the relation between Theorem 9 and Theorem 1 in the main text. Let \( \Delta_d \) be the probability simplex of probability vectors with \( d \) components. A function on \( \Delta_d \) is symmetric if it is invariant under permutations of the components of probability vectors. Let \( \mathcal{F}_s \) be the set of symmetric functions on the probability simplex. Here we assume implicitly that each \( f \in \mathcal{F}_s \) is defined on \( \Delta_d \) for each positive integer \( d \). In addition, the value of \( f(x) \) does not depend on the number of “0” in the components of \( x \); in other words, \( f(x) = f(y) \) whenever \( x \simeq y \) (which means \( x < y \) and \( y < x \)), even if \( x \) and \( y \) have different numbers of components.

Any symmetric function \( f \) on the probability simplex can be lifted to a unitarily invariant function on the space of density matrices,
\[
 f(\rho) := f(\text{eig}(\rho)) \quad \forall \rho \in T(C^d). \tag{A5}
\]
Conversely, any unitarily invariant function \( f \) on the space of density matrices defines a symmetric function on the probability simplex when restricted to diagonal density matrices,
\[
 f(\rho) := f(\text{diag}(\rho)) \quad \forall \rho \in \Delta_d. \tag{A6}
\]
It is straightforward to verify that \( f \) is a lift of \( f \) if \( f \in \mathcal{F}_s \), and that \( f \) is a lift of \( f \) if \( f \in \mathcal{F}_a \). So the lifting map \( f \mapsto \hat{f} \) and the restriction map \( f \mapsto \hat{f} \) establish a one-to-one correspondence between symmetric functions in \( \mathcal{F}_s \) and unitarily invariant functions in \( \mathcal{F}_a \).

Recall that a real function \( f \) on the probability simplex is Schur convex if it preserves the majorization order, that is, \( f(x) \leq f(y) \) whenever \( x \simeq y \). By contrast, \( f \) is Schur concave if it reverses the majorization order, that is, \( f(x) \geq f(y) \) whenever \( x \simeq y \) [65,66]. Note that Schur convex functions and Schur concave functions are necessarily symmetric. In addition, symmetric convex (concave) functions are automatically Schur convex (concave) but not vice versa in general. With this background, it is not difficult to show that the maps defined by Eqs. (A5) and (A6) preserve (Schur) convexity and (Schur) concavity for real functions. Here we prove one of these properties that is most relevant to the current study; the other three properties follow from a similar reasoning. Recall that \( \mathcal{F}_{ac} \) is the set of real symmetric concave functions on the probability simplex.

**Lemma 3.** The two maps \( f \mapsto \hat{f} \) and \( f \mapsto \hat{f} \) set a bijection between \( \mathcal{F}_{ac} \) and \( \mathcal{F}_{ac} \).

**Proof.** To prove the lemma, it suffices to show that the two maps \( f \mapsto \hat{f} \) and \( f \mapsto \hat{f} \) preserve concavity. Given \( f \in \mathcal{F}_{ac} \), let \( p_1, p_2 \in T(C^d) \) be two arbitrary density matrices and \( 0 \leq p \leq 1 \). It is well known that [66]
\[
 \text{eig}(p_1 + (1 - p)p_2) \preceq p \text{eig}(p_1) + (1 - p)\text{eig}(p_2), \tag{A7}
\]
where \( \text{eig}(\rho) \) denotes the vector of eigenvalues of \( \rho \). Consequently,
\[
 \hat{f}(p_1 + (1 - p)p_2) \leq f(p \text{eig}(p_1) + (1 - p)\text{eig}(p_2)) \leq pf(\text{eig}(p_1)) + (1 - p)f(\text{eig}(p_2))
\]
\[
 = p f(\text{eig}(p_1)) + (1 - p)f(\text{eig}(p_2)) = p \hat{f}(p_1) + (1 - p)\hat{f}(p_2). \tag{A8}
\]
where the first inequality follows from Eq. (A7) and Schur convexity of \( f \), and the second inequality from the concavity of \( f \). Therefore \( \hat{f} \) is concave whenever \( f \) is concave.

On the other hand, if \( f \in \mathcal{F}_{ac} \), then \( f \) is concave in particular on diagonal density matrices, which implies that \( \hat{f} \) is concave.

**Proof of Theorem 1.** The theorem is an immediate consequence of Theorem 9 and Lemma 3.

**APPENDIX B: COHERENCE MONOTONES AND COHERENCE TRANSFORMATIONS**

In this section we present a self-contained proof of Theorem 2, which connects coherence monotones and symmetric concave functions on the probability simplex. A variant of this result was first presented by Du et al. [30] (Theorem 1 there). The original proof has a gap in one direction [in particular, the reasoning leading to Eq. (12) there was not fully justified]. Nevertheless, all essential ideas are already manifested in the proof. It should be emphasized that the set of coherence monotones is the same irrespective whether IO or
SIO is taken as the set of free operations. Our study also leads to a simpler proof of the majorization criterion on coherent transformations under incoherent operations [49], which is the analog of Nielsen’s majorization criterion on entanglement transformations under local operations and classical communication (LOCC) [67]. As we shall see, the two proofs share a key ingredient, which reflects the strong connection between coherence measures and coherence transformations.

Recall that any quantum operation \( \Lambda \) (completely positive trace-preserving map) has a Kraus representation, that is, \( \Lambda(\rho) = \sum_n K_n \rho K_n^\dagger \), where the Kraus operators \( K_n \) satisfy \( \sum_n K_n K_n^\dagger = I \). Denote by \( \mathcal{I} \) the set of incoherent states with respect to a given reference basis. Then the operator \( K_n \) is incoherent if \( K_n \rho K_n^\dagger / p_n \in \mathcal{I} \) whenever \( \rho \in \mathcal{I} \) and \( p_n = \text{tr}(K_n \rho K_n^\dagger) > 0 \). It is strictly incoherent if in addition \( K_n \) is also incoherent. Simple analysis shows that \( K_n \) is incoherent iff it’s representation with respect to the reference basis has at most one nonzero entry in each column and strictly incoherent if the same is also true for each row. The operation \( \Lambda \) with Kraus representation \( \{K_n\} \) is (strictly) incoherent if each Kraus operator \( K_n \) is (strictly) incoherent. Although we are primarily concerned with incoherent operations (IO), most of our results concerning IO also apply to strictly incoherent operations (SIO).

1. Coherence monotones

Recall that \( \mathcal{F}_c \) is the set of real symmetric concave functions on the probability simplex and that each function \( f \in \mathcal{F}_c \) can be used to define a coherence monotone \( C_f \) [30]. When \( |\psi\rangle \) is a pure state,

\[
C_f(\psi) := f(\mu(\psi)); \tag{B1}
\]

in general,

\[
C_f(\rho) := \min_{\{p_{j}, \rho_{j}\}} \sum_j p_j C_f(\rho_j), \tag{B2}
\]

where the minimization runs over all pure state ensembles of \( \rho \) for which \( \rho = \sum_j p_j \rho_j \).

**Proof of Theorem 2.** By the nature of the convex-roof construction, \( C_f \) is automatically convex. In addition, to prove monotonicity under selective operations, it suffices to consider the scenario with a pure initial state \( \psi \). Let \( \Lambda = \{K_n\} \) be an arbitrary incoherent operation and \( |\phi_n\rangle = K_n |\psi\rangle / \sqrt{p_n} \) with \( p_n = \text{tr}(K_n |\psi\rangle \langle \psi| K_n^\dagger) \).

Then

\[
\sum_n p_n C_f(\phi_n) = \sum_n p_n f(\mu^k(\phi_n)) \leq f\left( \sum_n p_n \mu^k(\phi_n) \right)
\]

\[
\leq f(\mu(\psi)) = C_f(\psi), \tag{B3}
\]

where the first inequality follows from the concavity of \( f \), and the second inequality follows from Lemma 4 below and Schur concavity of \( f \). (Note that a symmetric concave function is automatically Schur concave.) Therefore, \( C_f \) is indeed a coherence monotone.

Now we come to the converse, which is based on Ref. [30]. Let \( C \) be an arbitrary coherence monotone, then \( C(\psi) \) is necessarily a symmetric function of \( \mu(\psi) \) given that monomial unitaries (including permutations) are incoherent. Define \( f \) on the probability simplex as follows:

\[
f(x) = C(\psi(x)), \text{ with } |\psi(x)\rangle = \sum_j \sqrt{x_j} |j\rangle. \tag{B4}
\]

Then \( f \) is clearly symmetric. To prove concavity, let \( x, y \) be two probability vectors, and \( z = px + (1-p)y \) with \( 0 \leq p \leq 1 \). Let \( |\psi(y)\rangle = \sum_j \sqrt{y_j} |j\rangle \) and \( |\psi(z)\rangle = \sum_j \sqrt{z_j} |j\rangle \). Construct the quantum operation with the following two Kraus operators:

\[
K_1 = \sqrt{p} \text{ diag}\left( \frac{x_0}{z_0}, \frac{x_1}{z_1}, \ldots, \frac{x_d-1}{z_d-1} \right),
\]

\[
K_2 = \sqrt{1-p} \text{ diag}\left( \frac{y_0}{z_0}, \frac{y_1}{z_1}, \ldots, \frac{y_d-1}{z_d-1} \right). \tag{B5}
\]

Since \( C \) is a coherence monotone by assumption, we deduce that

\[
C(\psi(z)) \geq p C(\psi(x)) + (1-p) C(\psi(y)), \tag{B6}
\]

which implies that

\[
f(px + (1-p)y) = f(z) \geq p f(x) + (1-p) f(y). \tag{B7}
\]

Therefore, \( f \) is both symmetric and concave. In addition, the coherence monotone \( C \) coincides with \( C_f \) when restricted to pure states.

Note that the above proof applies when either IO or SIO is taken as the set of free operations. Therefore, the set of convex-roof coherence monotones (measures) does not change under the interchange of IO and SIO.

2. Coherent transformations under incoherent operations

Lemma 4 below was inspired by Refs. [49] and [30]. It is a key ingredient for proving Theorem 2 and for establishing the majorization criterion on coherence transformations. Upon completion of this paper, we discovered that Lemma 4 follows from Theorem 1 in Ref. [56]. However, the proof there crucially depends on Theorem 1 in Ref. [30] by the same authors, which is a variant of Theorem 2 in our main text that we try to prove. To avoid circular argument and to make our presentation self-contained, the discussion here is instrumental.

**Lemma 4.** Suppose \( |\psi\rangle \) is an arbitrary pure state and \( \Lambda = \{K_n\} \) is an arbitrary incoherent operation acting on \( |\psi\rangle \). Let \( p_n = \text{tr}(K_n |\psi\rangle \langle \psi| K_n^\dagger) \) and \( |\phi_n\rangle = K_n |\psi\rangle / \sqrt{p_n} \) when \( p_n > 0 \). Then

\[
\mu(\psi) \prec \sum_n p_n \mu^k(\phi_n). \tag{B8}
\]

Although \( |\phi_n\rangle \) is not well defined when \( p_n = 0 \), this fact does not cause any difficulty because \( K_n |\psi\rangle \) is what really matters in our calculation, and it vanishes when \( p_n = 0 \). Alternatively, we may restrict the summation in Eq. (B8) to the terms with \( p_n > 0 \), and the conclusion is the same. Similar comments also apply to several other equations appearing in this paper but will not be mentioned again to avoid verbosity.
3. The majorization criterion on coherence transformations

In addition to proving Theorem 2, Lemma 4 enables us to construct a simple proof of the majorization criterion on coherence transformations under incoherent operations [49]. The result is the analog of Nielsen’s majorization criterion on entanglement transformations under LOCC [67].

**Theorem 10.** The pure state $|\psi\rangle$ can be transformed to $|\phi\rangle$ under IO or SIO iff $\mu(\psi)$ is majorized by $\mu(\phi)$.

The conclusion concerning IO was first presented in Ref. [49]; the original proof of the “only if” part has a gap, which was corrected upon completion of our work. In view of this gap, several recent works have derived weaker forms of Theorem 10. In particular, the conclusion concerning SIO was established in Refs. [28] and [32].

**Proof.** Suppose $|\psi\rangle$ can be transformed to $|\phi\rangle$ under an incoherent operation $\Lambda = \{K_n\}$. Let $|\phi_n\rangle = K_n|\psi\rangle/\sqrt{p_n}$, then $\sqrt{p_n}|\phi_n\rangle = \sum_k (K_n)_j^k |\psi_k\rangle$, so that

$$
\sum_{n=0}^{r} \sum_{j=0}^{n} p_n \mu_j (|\phi_n\rangle) = \sum_{n=0}^{r} \sum_{j=0}^{n} p_n (|\phi_n\rangle)_j^2 \\
= \sum_{k,l=0}^{r} \sum_{j=0}^{n} (K_n)_j^k (K_n)_j^l |\psi_k\rangle |\psi_l\rangle \\
= \sum_{k=0}^{r} |\psi_k\rangle^2 + \sum_{k>r} \sum_{j=0}^{n} \sum_{l=0}^{r} (K_n)_j^k |\psi_k\rangle |\psi_l\rangle \\
\geq \sum_{k=0}^{r} |\psi_k\rangle^2 = \sum_{k=0}^{r} \mu_k (|\psi\rangle),
$$

where the third equality follows from Eq. (B9).

Since permutations of basis states are incoherent, without loss of generality we may assume that the coefficients $|\psi_j\rangle$ of $|\psi\rangle$ in the reference basis are in decreasing order. Then Eq. (B10) implies that

$$
\mu(\psi) < \sum_{n=0}^{r} p_n \mu (|\phi_n\rangle) < \sum_{n=0}^{r} p_n \mu (|\phi_n\rangle) = \sum_{n=0}^{r} p_n \mu (|\phi_n\rangle);
$$

where the last step follows from the relation $|\phi_n\rangle = P_n |\phi_n\rangle$ with $P_n$ being a permutation, that is, $\mu (|\phi_n\rangle) \simeq \mu (|\phi_n\rangle)$.

As a side remark, Eq. (B10) in the proof of Lemma 4 actually holds for a larger class of operations whose Kraus operators have upper triangular form up to permutations on the left. Such operations may generate coherence, but Eq. (B8) still holds nevertheless if the coefficients $|\psi_j\rangle$ of $|\psi\rangle$ in the reference basis are in decreasing order. However, in general this conclusion no longer holds if the coefficients do not have this property. Although this property can be recovered by a suitable permutation, the permutation required may destroy the upper triangular structure of the Kraus operators, which cannot be recovered by permutations only on the left, in contrast with the scenario of incoherent operations. That is why Lemma 4 cannot hold in general for this wider class of operations, as expected.
Theorem 11. Let $P(\psi \rightarrow \varphi)$ be the maximal probability of transforming $|\psi\rangle$ to $|\varphi\rangle$ under IO. Then

$$P(\psi \rightarrow \varphi) = \min_{m \geq 0} \frac{\sum_{j \geq m} \mu_j^m(\psi)}{\sum_{j \geq m} \mu_j^m(\psi)}.$$  

(B15)

Theorem 11 still holds if IO is replaced by SIO. This is clear from the proof presented in Ref. [30] and Theorem 10, which imply that the incoherent operation achieving the maximal probability can be chosen to be strictly incoherent. It is worth pointing out that the sum $\sum_{j \geq m} \mu_j^m(\psi)$ for each positive integer $m$ is a bona fide coherence measure associated with the function $f_m(p) = \sum_{j \geq m} p_j$, which is symmetric and concave [30,68]. Theorem 11 is the analog of a similar result on entanglement transformations under LOCC, first established in Ref. [68]. The idea of the proof in Ref. [30] also mirrors the analog in the entanglement setting. Not surprisingly, the majorization criterion plays a crucial role in proving Theorem 11 as it does in proving the result in Ref. [68]. Also, the proof relies on Theorem 1 in Ref. [30], which is a variant of Theorem 2 in our main text. Since these stepping stones have been corroborated, Theorem 11 is well established by now.

APPENDIX C: PROOF OF LEMMA 1

Proof. Expand $|\psi\rangle$ in the reference basis $|\psi\rangle = \sum_{j<k} c_{jk}|j,k\rangle$, then $\mu(\psi) = \langle c_{jk}|^2\rangle_{jk}$. Let $\rho_B$ be the reduced density matrix for subsystem $B$, then the diagonal of $\rho_B$ reads $\text{diag}(\rho_B) = \langle \sum_{j} |c_{jk}|^2 \rangle$. It follows that $\mu(\psi) \propto \text{diag}(\rho_B) \propto \langle \text{eig}(\rho_B) \rangle$ where $\text{eig}(\rho_B)$ denotes the vector of eigenvalues of $\rho_B$, and we have applied the majorization relation $\text{diag}(\rho_B) \propto \langle \text{eig}(\rho_B) \rangle$ [66]. The inequality $\text{Cp}(\psi) \geq E_k(\psi)$ is an immediate consequence of the relation $\mu(\psi) \propto \lambda(\psi)$.

Let $r = E_k(\psi)$ be the Schmidt rank of $|\psi\rangle$. If $\mu(\psi) \propto \lambda(\psi)$, then $\text{Cp}(\psi) = E_k(\psi) = r$. If $\text{Cp}(\psi) = E_k(\psi) = r$, then $\{|j| \langle c_{jk} \neq 0 \exists k \} \geq r$ given that $\rho_B$ has rank $r$. By the same token, $\{|k| \langle c_{jk} \neq 0 \exists j \} \geq r$. So the coefficient matrix $c_{jk}$ has exactly $r$ nonzero components, with at most one on each row and each column. Therefore, $|\psi\rangle$ has the form $|\psi\rangle = \sum_{j} a_j |\pi_1(j)\pi_2(j)\rangle$ with $\sum_{j} |a_j|^2 = 1$, where $\pi_1,\pi_2$ are two permutations of basis states. In addition, $|a_j|^2$ coincide with the Schmidt coefficients of $|\psi\rangle$, which implies Eq. (6) after redefining $\pi_1,\pi_2$ if necessary. Conversely, the relation $\mu(\psi) \propto \lambda(\psi)$ holds automatically whenever $|\psi\rangle$ has the form of Eq. (6).

APPENDIX D: PROOF OF LEMMA 2

Proof. Lemma 2 is trivial when $d = 1,2$, so we assume $d \geq 3$ in the following discussion. Note that both sides of the inequality in Eq. (25) are invariant under permutations of $c_j$ and are independent of the phase factors, so we may assume that $c_0 \geq c_1 \cdots \geq c_{d-1} \geq 0$ without loss of generality; then it suffices to consider the nontrivial case $c_0 > 0$. Define

$$h(c_j) := d \left( \sum_j c_j \right)^{2/d} - \left( \sum_j c_j \right)^2 + (d-1) \sum_j c_j^2,$$

(D1)

then it remains to show that $h \geq 0$.

First, consider the special case $c_0 = \cdots = c_{d-2} = a$ and $c_{d-1} = b$ with $a > 0$ and $0 \leq b \leq a$. Since $b$ is homogeneous, we may assume $a = 1$, so that $0 \leq b < 1$. Then

$$h(c_j) = g(b) := db^{2/d} + (d-2)b^2 - 2(d-1)b.$$  

(D2)

The first and second derivatives of $g(b)$ are given by

$$g'(b) = 2b^{(2-d)/d} + 2(d-2)b - 2(d-1),$$

$$g''(b) = \frac{2(d-2)}{d} - \frac{2(d-1)}{d}.$$  

(D3)

According to these formulas, it is easy to verify that $g'(b) > 0$ when $0 < b < b_0$ and $g'(b) < 0$ when $b_0 < b < 1$. Therefore, the minimum of $g(b)$ over the interval $0 \leq b \leq 1$ can only be attained at $b = 0$ or $b = 1$. Since $g(0) = g(1) = 0$, we conclude that $h(c_j) = g(b) \geq 0$ for $0 \leq b \leq 1$, and the inequality is saturated iff $b = 0$ or $b = 1$.

Next, consider the general case. Since $h$ is homogeneous, we may assume that $\sum_j c_j^2 = 1$ without loss of generality. Let $s := \sum_j c_j$; then

$$h(c_j) = d \left( \sum_j c_j \right)^{2/d} - s^2 + (d-1).$$  

(D4)

If $s < \sqrt{d-1}$, then $h > 0$. If $s = \sqrt{d-1}$, then $h \geq 0$ and the inequality is saturated iff $c_{d-1} = 0$, in which case we have $c_0 = c_1 = \cdots = c_{d-2} = 1/\sqrt{d-1}$. If $s > \sqrt{d}$, then $c_0 = c_1 = \cdots = c_{d-1} = \sqrt{d}/d$ and $h > 0$. It remains to consider the scenario $\sqrt{d-1} < s < \sqrt{d}$, in which case $c_j > 0$ for all $j$.

Now, we investigate the minimum of $h(c_j)$ for a given value of $s$. Suppose the minimum is attained at a given point. Using the method of Lagrangian multipliers, it is easy to show that $c_0, c_1, \ldots, c_{d-1}$ take on two different values, that is, $c_0 = \cdots = c_{k-1} > c_k = \cdots = c_{d-1}$, where $1 \leq k \leq d-1$. Note that not all $c_j$ can take on the same value due to the constraint $\sum_j c_j^2 = 1$ and $s < \sqrt{d}$. In the case $d = 3$, straightforward calculation shows that $k = 2$, in which case we have

$$c_0 = c_1 = \frac{2s + \sqrt{6-2s^2}}{6}, \quad c_2 = \frac{s - \sqrt{6-2s^2}}{3}. \quad (D5)$$

In general, we have $k = d-1$; otherwise, the values of $c_{k-1}, c_k, c_{d-1}$ can be adjusted so that the value of the product $c_0c_1c_{d-1}$ decreases, while $c_{k+1} + c_k + c_{d-1}$ and $c_k^2 + c_{k+1}^2 + c_{d-1}^2$ are left invariant, which leads to a contradiction. The fact $k = d-1$ implies that

$$c_0 = \cdots = c_{d-2} = s + \sqrt{(d-s^2)/(d-1)},$$

$$c_{d-1} = s - \sqrt{(d-s^2)/(d-1)}.$$  

(D6)

Since $c_0 = \cdots = c_{d-2} > c_{d-1}$ for $\sqrt{d-1} < s < \sqrt{d}$, it follows that $h(c_j) > 0$ according to the discussion after Eq. (D3). This observation completes the proof of Lemma 2.

APPENDIX E: PROOFS OF PROPOSITIONS 1 AND 2

Proof of Proposition 1. Equation (27) can be derived as follows. The equality $C_i(\rho) = p(d-1) = dF - 1$ is easy
to verify; the equality $\hat{C}_i(\rho) = C_i(\rho)$ follows from the inequality $\hat{C}_i(\rho) \geq C_i(\rho)$ and the convexity of $\hat{C}_i(\rho)$, which implies that $\hat{C}_i(\rho) \leq p\hat{C}_i(\psi) = p(d-1) = C_i(\rho)$; the equality $C_P(\rho) = C_i(\rho)$ follows from Theorem 6 in Ref. [34]. Alternatively, $C_P(\rho)$ can be computed based on the symmetry consideration that $\rho$ is invariant under arbitrary permutations of the basis states.

To derive Eq. (28), let $\rho_j = |\varphi_j\rangle\langle\varphi_j|$ with
\begin{equation}
|\varphi_j\rangle = \frac{1}{\sqrt{d-1}} \sum_{k=0, k\neq j}^{d-1} |k\rangle, \quad j = 0, 1, \ldots, d-1. \quad (E1)
\end{equation}

Then
\begin{equation}
\frac{1}{d} \sum_{j=0}^{d-1} \rho_j = a|\psi\rangle\langle\psi| + (1-a)I \quad (E2)
\end{equation}
with $a = (d-2)/(d-1)$. Observing that $C_{ge}(\rho_j) = 0$ for each $j = 0, 1, \ldots, d-1$, we conclude that $C_{ge}(\rho) = 0$ when $p = (d-2)/(d-1)$, which further implies that $C_{ge}(\rho) = 0$ for $0 \leq p \leq (d-2)/(d-1)$. When $p \geq (d-2)/(d-1)$,
\begin{equation}
C_{ge}(\rho) \leq \frac{p-a}{1-a} C_{ge}(\psi) = \frac{p(d-1) - (d-2)}{d} = dF - (d-1). \quad (E3)
\end{equation}

On the other hand, the opposite inequality follows from Theorem 7 and Eq. (27). This observation confirms Eq. (28).

Proof of Proposition 2. Equation (31) can be derived as follows. When $1/d^2 \leq F \leq 1/d$, we have $\hat{N}(\rho) = N(\rho) = E_P(\rho) = 0$ because $\rho$ is separable. When $F \geq 1/d$, the equality $N(\rho) = dF - 1$ is straightforward to verify. The equality $\hat{N}(\rho) = N(\rho)$ follows from the inequality $\hat{N}(\rho) \geq N(\rho)$ and the convexity of $\hat{N}(\rho)$, which implies that
\begin{equation}
\hat{N}(\rho) \leq \frac{F - \frac{1}{d}}{1 - \frac{1}{d}} \hat{N}(\psi) = dF - 1 = N(\rho). \quad (E4)
\end{equation}

Finally, the equality $E_P(\rho) = dF - 1$ can be derived based on the symmetry consideration that $\rho$ is invariant under the transformation $U \otimes U^*$ for any unitary $U$. (Here $U^*$ denotes the complex conjugate of $U$ with respect to a given basis; by contrast, the Hermitian conjugate of $U$ is denoted by $U^\dagger$.)

To derive Eq. (32), let
\begin{equation}
|\Phi\rangle = \frac{1}{\sqrt{d-1}} \sum_{j=0}^{d-2} |jj\rangle \quad (E5)
\end{equation}
and $F_0 = |\langle\Phi|\Phi\rangle|^2 = (d-1)/d$. Then
\begin{equation}
\int dU [(U \otimes U^*)(|\Phi\rangle\langle\Phi|)(U \otimes U^*)]\nonumber
= F_0(|\Phi\rangle\langle\Phi|) + (1 - F_0) \frac{I - |\Phi\rangle\langle\Phi|}{d-1}, \quad (E6)
\end{equation}
where the integral is taken with respect to the normalized Haar measure on the unitary group. Noting that $E_{ge}(|\Phi\rangle\langle\Phi|) = 0$, we conclude that $E_{ge}(\rho) = 0$ when $F = F_0$, which implies that $E_{ge}(\rho) = 0$ for $1/d^2 \leq F \leq F_0$. When $F \geq F_0$,
\begin{equation}
E_{ge}(\rho) \leq \frac{F - F_0}{1 - F_0} E_{ge}(\psi) = dF - (d-1). \quad (E7)
\end{equation}

On the other hand, the opposite inequality follows from Theorem 8 and Eq. (31). This observation confirms Eq. (32).

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