PROTOSTELLAR DISK DYNAMOS AND HYDROMAGNETIC OUTFLOWS IN PRIMORDIAL STAR FORMATION

JONATHAN C. TAN 1 AND ERIC G. BLACKMAN 2
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ABSTRACT

Are magnetic fields important in primordial star formation? Assuming that star formation occurs via an accretion disk that is turbulent, initially because of local gravitational instability, we calculate the disk structure for realistic accretion rates. We predict that local gravitational viscosity is able to drive accretion, without the disk fragmenting. We then estimate the rate of dynamo amplification of seed magnetic field. Turbulence in a stratified disk can be helical, with different signs of the helicity in each hemisphere. This provides a key ingredient for production of global-scale magnetic fields whose sign of flux is sustained over many orbit times. The resulting fields can drive collimated protostellar outflows that reduce the star formation efficiency from the initial gas cloud, especially once the protostar has contracted to the main sequence, at \( \sim 100 M_\odot \). We estimate that the outflows are powerful enough to eject some material from the host dark matter halo and to initiate relatively strong magnetization of the local intergalactic medium. Close to the protostar, the outflow acts to shield the disk and equatorial regions from radiative feedback, such as ionizing photons, and this may enable accretion up to relatively large stellar masses. We conclude that magnetic fields cannot be ignored in models of primordial star formation.

Subject headings: early universe — MHD — stars: formation — stars: magnetic fields — stars: winds, outflows

1. INTRODUCTION

Primordial star formation has attracted much attention recently, as a result of advances in numerical models of cosmic structure formation that can resolve down to solar system scales (Abel, Bryan, & Norman 2002, hereafter ABN02), constraints on the reionization epoch from the Wilkinson Microwave Anisotropy Probe observations of the microwave background (Kogut et al. 2003), and the discovery of very metal-poor Galactic halo stars (Aoki et al. 2002; Christlieb et al. 2002), whose elemental abundances may be the fingerprints of the earliest supernovae.

The typical mass of the first stars is an important, but unknown, quantity. It may be set by feedback processes local to the forming star. To investigate this possibility, it is necessary to model the star formation process by including as much physics as possible, while making allowance for a realistic geometry of the accreting gas. Magnetic fields play crucial roles in present-day star formation but have usually been assumed to be unimportant in the primordial case. It is the goal of this paper, which builds on the detailed, yet nonmagnetic, theoretical models of star formation. Outflows are now thought to play a key role in redistributing angular momentum in the accretion disk (Blandford & Payne 1982), setting the star formation efficiency (Levreault 1984; Myers et al. 1988; Matzner & McKee 2000), and depositing energy into the star-forming interstellar medium (Norman & Silk 1980). It has often been speculated that magnetic fields and outflows may be unimportant for primordial star formation because the strength of seed fields is presumably very weak. Thus, they have generally been ignored in studies of the collapsing gas cloud (e.g., Haiman, Thoul, & Loeb 1996; Tegmark et al. 1997; Nakamura & Umemura 1999; ABN02; Bromm et al. 2002) and in models of the formation of the protostellar core (Stahler, Palla, & Salpeter 1986; Omukai & Nishi 1998; Ripamonti et al. 2002; Tan & McKee 2004a). However, as in the local universe, the presence or absence of dynamically important magnetic fields and outflows from primordial protostellar disks has important implications for the basic star formation process.

The ubiquity and energy of molecular outflows from present-day protostars (Zuckerman, Kuiper, & Kuiper 1976; Kwan & Scoville 1976; Edwards & Snell 1982; Bally & Lada 1983) were a surprise and forced a radical change in theoretical models of star formation. Outflows are now thought to be a key role in redistributing angular momentum in the accretion disk (Blandford & Payne 1982), setting the star formation efficiency (Levreault 1984; Myers et al. 1988; Matzner & McKee 2000), and depositing energy into the star-forming interstellar medium (Norman & Silk 1980). It has often been speculated that magnetic fields and outflows may be unimportant for primordial star formation because the strength of seed fields is presumably very weak. Thus, they have generally been ignored in studies of the collapsing gas cloud (e.g., Haiman, Thoul, & Loeb 1996; Tegmark et al. 1997; Nakamura & Umemura 1999; ABN02; Bromm et al. 2002) and in models of the formation of the protostellar core (Stahler, Palla, & Salpeter 1986; Omukai & Nishi 1998; Ripamonti et al. 2002; Tan & McKee 2004a). However, as in the local universe, the presence or absence of dynamically important magnetic fields and outflows from primordial protostellar disks has important implications for the basic star formation process.

The amplification of seed magnetic field by dynamo action in Population III protostars and its ejection in outflows may also bear on the long-standing question of the origin of galactic and intergalactic field strengths (e.g., Kulsrud et al. 1997 and references therein), particularly if this mode of star formation was widely and evenly spread throughout the universe. Such a model would be analogous to those that propose that fields are ejected from active galactic nuclei (AGNs; Daly & Loeb 1990; Colgate & Li 1999; Kronberg et al. 2001), although the AGN models would produce more ordered flux on large scales. If field amplification in Population III star formation is very efficient, then much of the intergalactic magnetic field may have been in place before or at the

1 Princeton University Observatory, Peyton Hall, Princeton, NJ 08544; jt@astro.princeton.edu.
2 Department of Physics and Astronomy and Laboratory for Laser Energetics, University of Rochester, Rochester, NY 14627; blackman@pas.rochester.edu.
same time as the era of reionization, which has implications for models of field generation in cosmic ionization fronts (Subramanian, Narasimha, & Chitre 1994; Gnedin, Ferrara, & Zweibel 2000).

Starting from conditions representative of the end state of the numerical simulation of ABN02, Tan & McKee (2004a) predicted the mass infall rate, accretion disk structure, and protostellar evolution associated with primordial star formation. Using these results, in this paper we consider a wider range of possible accretion disk models, calculate their structure over the evolution of the protostar, and assess their gravitational stability with respect to fragmentation (§ 2). We discuss the ability of these disks to generate large-scale magnetic fields via a dynamo (§ 3), which is likely to be a key requirement (Lubow, Papaloizou, & Pringle 1994; Blackman 2004; Blackman & Tan 2004) for magnetically mediated outflows from thin disks (e.g., Blandford & Payne 1982; Lovelace, Wang, & Sulkane 1987; Pelletier & Pudritz 1992; Königl & Pudritz 2000). We show that strong, dynamically important fields can be produced even from the weak seed fields expected of primordial protostellar disks. We address the implications of feedback from hydromagnetic winds on the star formation process in § 4 and conclude in § 5.

2. PRIMORDIAL PROTOSTELLAR ACCRETION DISKS

The dark matter halos and gas clouds relevant to primordial star formation form from hierarchical mergers of smaller structures, including the accretion of matter along filaments (ABN02). Thus, in general we expect that the initial conditions for star formation are gas cores with nonzero angular momentum. The collapse should proceed to a disk, which then channels mass to the protostar via viscous torques.

We use the Tan & McKee (2004a) model of the rotating, freely falling accretion envelope that develops inside the sonic point, \( r_{sp} \), of the collapsing gas. The rotation is parameterized by

\[
 f_{Kep} = \frac{r_{rot}(r_{sp})}{v_{Kep}(r_{sp})} = \frac{v_{rot}(r_{sp})}{(GM_{sp}/r_{sp})^{1/2}},
\]

which is the ratio of the mass-weighted rotational velocities, \( v_{rot} \), relative to Keplerian, \( v_{Kep} \), of infalling matter at a radial distance from the protostar corresponding to the mean location of the sonic point. Inside this region, which contains a total mass \( M_{sp} \), we assume conservation of angular momentum (Ulrich 1976) so that matter falls freely to the midplane and forms a disk of size

\[
 r_d = f_{Kep}^2 r_{sp} \rightarrow 3.44 \left( \frac{f_{Kep}}{0.5} \right)^2 \left( 1 + f_d \right)^{9/7} \left( \frac{m_*}{M_*} \right)^{9/7} K^{10/7} \text{AU}.
\]

For the numerical evaluation we have used the mass-radius relation expected at the sonic point of the collapsing cloud (Tan & McKee 2004a), which involves the entropy parameter, \( K' \), of the polytropic equation of state of the cloud, relative to the fiducial case with \( T = 300 \text{ K} \) at a hydrogen density of \( 10^4 \text{ cm}^{-3} \); larger values of \( K' \) correspond to denser gas cores. We have also assumed an efficiency, \( \epsilon_{sd} \), of collapse from the core to the disk, which is unity when feedback processes are unimportant, and related \( M_{sp} \) to the stellar mass, \( m_* \), at the time when \( M_{sp} \) has collapsed to the disk: \( m_*(1 + f_d) = M_{sp} \), where \( f_d \) is the disk mass relative to the star’s and with the assumption that there is little diversion of the accretion flow from \( r_{sp} \) to \( r_d \). From the results of the simulations of ABN02 we have taken a fiducial value of \( f_{Kep} = 0.5 \), but there is likely to be a significant dispersion depending on the formation history of the halo and cloud. The fiducial value of \( f_d \) adopted by Tan & McKee (2004a) is \( 1/3 \) because the disks are expected to be relatively massive since their angular momentum transport must initially be driven by gravitational instabilities.

Material falls onto the disk (and directly to the star) at all radii \( r < r_d \) (Fig. 2 of Tan & McKee 2004a; Cassen & Moosman 1981). The characteristic disk scale is much greater than the stellar radius \( r_* \approx 100 R_\odot = 0.5 \text{ AU} \); Tan & McKee (2004a), so most matter accretes to the star via the disk. The evolution of \( r_* \) as the stellar mass increases is shown in the top panel of Figure 1, together with the linear growth of \( r_d \). Although infall onto the disk provides some effective viscosity, this is not important in the very inner regions and so we assume a standard “\( \alpha_{ss} \)” model for the viscosity (Shakura & Sunyaev 1973). We discuss the choices for the value of \( \alpha_{ss} \) below.

The overall rate of collapse and thus accretion rate of the star is given approximately by \( \dot{m}_* \sim m_*/t_{ff} \), where \( t_{ff} \) is the local free-fall timescale evaluated at the density of the region that contains mass \( m_* \) at the moment it undergoes dynamical collapse. The accretion rate is thus set by the structure of the prestellar gas core, which in turn is set by the cooling properties of trace amounts of molecular hydrogen in the

![Figure 1](image-url)

**Fig. 1.**—Top: Evolution of the radius of the protostar, \( r_* \), and the radial extent of the ionized \( [\text{H}^+] > 0.5 \) region of the accretion disk, \( r_{ion} \), for models with viscosity parameter \( \alpha_{ss} = 0.01 \) and 0.3 (dashed and dotted lines, respectively). The formation is from the collapse of a core with \( K' = 1 \) and \( f_{Kep} = 0.5 \) (see Tan & McKee 2004a for more details). The full extent of the accretion disk \( r_d \) is shown by the long-dashed line. Bottom: Mean number of orbits of fluid elements in the ionized region of the disk for \( \alpha_{ss} = 0.01 \) and 0.3 (dashed and dotted lines, respectively). The gap at \( m_*/M_* = 10 \) is when \( r_{ion} = r_* \), because of the expansion of the protostar during this stage of the evolution (Tan & McKee 2004a).
primordial gas. A more careful evaluation of the accretion rate to the star (Tan & McKee 2004a) yields

\[
\dot{m}_* = 0.026(1 + f_d)^{-10/7} \epsilon_{sd}^{-10/7} K^{15/7} \left( \frac{\dot{m}_s}{M_\odot} \right)^{-3/7} M_\odot \text{ yr}^{-1}. \tag{3}
\]

These high accretion rates make it likely that the disk will build itself up to a mass that is significant compared to the stellar mass (we have set \( f_d = 1 \)) and will become susceptible to gravitational instabilities. Two-dimensional simulations of clumpy, self-gravitating disks show self-regulation with \( \alpha_{ss} \approx (\Omega t_\text{sd})^{-1} \) up to a maximum value \( \alpha_{ss} \approx 0.3 \) (Gammie 2001), where \( \Omega \) is the orbital angular velocity, \( t_\text{sd} = \Sigma K t_{c,d} / (\sigma t_{\text{sd},d}^4) \) is the thermal timescale, \( \Sigma \) is the surface density, \( T_{c,d} \) is the disk’s central (midplane) temperature, and \( T_{\text{eff},d} \) is the effective photospheric temperature at the disk’s surface. Fragmentation occurs when \( \Omega t_\text{sd} \lesssim 3 \): this condition has the best chance of being satisfied in the outermost parts of the disk that are still optically thick (see below). In addition to local gravitational instability, global (\( n = 1 \)) instabilities (Adams, Ruden, & Shu 1989; Shu et al. 1990) may be efficient at driving inflow if the disk becomes too massive.

In addition to gravitational instabilities, the magnetorotational instability (MRI) may become important, yielding viscous stresses that correspond to somewhat smaller values of \( \alpha_{ss} \). This process could be particularly important in the inner accretion disk, where gravitational instability is suppressed. Values often quoted for the MRI are \( \alpha_{ss} \approx 0.01 \) (Balbus & Hawley 1998), but larger values have also been measured and neither simulations nor physical understanding have yet determined why it cannot differ by an order of magnitude (or whether the constant \( \alpha_{ss} \) formalism is really appropriate for MRI-driven turbulence). We evaluate the ability of the MRI to operate in \( \S \) 3. If the disk is stable with respect to the MRI, then \( \alpha_{ss} \) may be set by molecular viscosity and thus much smaller. In this case the accretion rate may effectively go to zero. However, the disk is still being fed at a rate given by equation (3), so that the surface mass density inevitably builds up until self-gravity (and the associated larger values of \( \alpha_{ss} \)) becomes important.

Given these considerations, we calculate the radial structure of the inner disk at any given point in the protostellar evolution by assuming that it is fed smoothly at a rate given by equation (3). We also use the standard theory of steady, thin, viscous accretion disks, with a spatially constant viscosity parameter, \( \alpha_{ss} \), and ignore energy injection from the star. The viscosity is assumed to be a function of the total pressure, although it is gas pressure that dominates over radiation pressure in the earlier stages (\( m_s \approx 20 M_\odot \)), which we think are relevant for field growth (\( \S \) 3). We evaluate cases with \( \alpha_{ss} = 0.01, 0.3 \).

The inner scale of the disk is set by \( r_* \), which is predicted from the protostellar evolution model of Tan & McKee (2004a). It is somewhat sensitive to the choice of \( \alpha_{ss} \) for \( m_s \approx 20 M_\odot \) because this sets the temperature of gas in the inner disk and this thermal energy is advected into the star (Fig. 1, top panel). We adopt primordial gas abundances \( X = 0.76 \) and \( Y = 0.24 \), so that in the atomic phase \( \mu = 1.22 m_t \) and \( n_{\text{He}} = 0.079 n_t \), and use the opacities of zero-metallicity gas of Iglesias & Rogers (1996) for \( T \approx 6000 \) K and of Lenzuni, Chornoff, & Salpeter (1991) for \( T \approx 6000 \) K (although here we are interested primarily in the higher temperature regime). The method assumes that the disk’s central temperature, \( T_{c,d} \), is much greater than the surface temperature, \( T_{\text{eff},d} \), i.e., that the disk is very optically thick: this condition is not well satisfied during the very earliest stages or for the outer disk, since the opacity is set by H\(^+\) and declines rapidly for \( T \lesssim 7000 \) K.

We calculate the ionization state of H and He from the Saha equation and include the energy needed for ionization of H and He and the thermal energy in the disk’s energy equation:

\[
F = \frac{3Gm_s \dot{m}_s}{8 \pi r^3} \left[ 1 - \left( \frac{\bar{r}}{\bar{r}_0} \right)^{1/2} \right] + \dot{m}_s \frac{d}{4 \pi r^2} \left[ \frac{5}{3} \bar{r}_h + \bar{r}_l \right], \tag{4}
\]

where \( F \) is the flux emitted from one side of the disk and \( \bar{r}_h \) and \( \bar{r}_l \) are the thermal energy and dissociation/ionization energy per unit mass, respectively, averaged over the thickness of the disk. The first term on the right-hand side of equation (4) is the viscous dissipation per unit disk face area. Note that usually \( d\dot{m}_s/dr > 0 \) and \( d\dot{m}_s/dr < 0 \). The effect of the thermal energy term is small for thin disks such as those we consider; so we drop it from our numerical calculations. However, the dissociation/ionization term, which is often neglected, can be an order of magnitude larger than the thermal term and can have a major impact on the disk structure. We therefore retain this term. We follow Frank, King, & Raine (1995), using an approximate solution based on radiative diffusion so that \( F \approx 4\pi T_{c,d}^4 / 3\pi \), where \( T_{c,d} \) is the midplane temperature and \( \bar{r} \) is the optical depth from the midplane to the surface.

Dividing the disk into many discrete radial zones, we solve the full set of disk structure equations (e.g., Frank et al. 1995), starting from the outer regions where the gas is almost completely neutral. The high accretion rates of protostellar protostars lead to the ionization energy being quite important, particularly in the earlier stages of evolution before the protostar starts contracting toward the main sequence. For complete ionization of atomic gas, the energy absorption rate is

\[
\frac{dE}{dt} \bigg|_{\text{ion}} = \dot{m}_s \epsilon_{\text{ion}} = 2.4 \times 10^4 \left( \frac{\dot{m}_s}{10^{-2} M_\odot \text{ yr}^{-1}} \right) L_\odot, \tag{5}
\]

calculated assuming a dissociation energy of 13.6 eV for H ionization and 24.6 and 54.4 eV for the first and second stages of He ionization, respectively.\(^3\)

Figure 2 shows three examples of disk structure for \( \alpha_{ss} = 0.01 \), with \( m_s = 1, 10 \), and 100 \( M_\odot \). At these masses the stellar sizes are taken to be \( r_* = 100, 300, \) and 4 \( R_\odot \), and the accretion rates (eq. [3]) are \( \dot{m}_s = (17, 6.4, 2.4) \times 10^{-3} M_\odot \text{ yr}^{-1} \), respectively. Figure 3 shows the equivalent models with \( \alpha_{ss} = 0.3 \).

The self-gravity in the disks can be gauged by considering the Toomre stability parameter for a Keplerian disk, \( Q \equiv c_s \Omega / \left( \pi G \Sigma \right) \), which is less than 1 in unstable regions. The outer parts of the disk are most susceptible to gravitational instability. Following a line of reasoning similar to that presented by Goodman (2003) concerning self-gravity in quasar accretion disks, consider a disk with \( \alpha_{ss} = 0.01 \) provided by the MRI: the model will be physically self-consistent inside the radius at which \( Q = 1 \). At larger radii, we expect that gravitational viscosity will become important, allowing larger

\(^3\) The results of ABN02 indicate that the first solar mass or so of material to be accreted would be almost fully molecular, which for a dissociation energy of 4.48 eV for H\(_2\) increases the coefficient of eq. (5) by 11%. We do not include this minor correction factor in our numerical calculations.
values of $\alpha_{ss}$ so that $Q$ remains approximately equal to unity. The results of Gammie (2001) show that once $\alpha_{ss} \approx 0.3$, then fragmentation occurs. This corresponds to the location in our $\alpha_{ss} = 0.3$ models where $Q = 1$. From Figure 3 we can see that $Q > 1$ for all the regions of the disks with $T_{c,d} \approx 7000$ K, and so fragmentation should not occur in these regions. At larger radii we expect the disks to become optically thin because of the temperature dependence of $H^-$ opacity (approximately $\propto T^{-14}$) and have thermal timescales that are long compared to the orbital period. This appears to occur before $Q < 1$, so that fragmentation would then not occur anywhere in the disk.

The infall of material onto the disk provides an effective viscosity and source of turbulence that is likely to be quite important in the outer disk, and this will also help prevent fragmentation. Even if $Q$ became less than 1, fragmentation is not inevitable: global modes of gravitational instability, such as spiral waves, could develop instead. These modes, if present, are relatively efficient at transporting angular momentum and could then connect the outer infall region with the inner, viscous accretion disk, where first local gravitational viscosity, and then perhaps viscosity from the MRI, brings material all the way to the immediate vicinity of the protostar. The final accretion to the stellar surface may be mediated in part by angular momentum loss in protostellar outflows, the properties of which are discussed in § 4.

We conclude that fragmentation of typical primordial protostellar accretion disks does not occur, if the results of Gammie’s (2001) simulations are applicable. However, further numerical studies are desirable to confirm this prediction. We note that in the most advanced simulations to date (ABN02) of the global primordial star formation process, which probe conditions in the initial collapse down to scales of the order of AU (just before formation of a hydrostatic protostellar core and an optically thick accretion disk), there is also no
indication of fragmentation. Primordial star formation appears to favor single (or perhaps binary) stars rather than star clusters. The reservoir of gas available to the forming star is several hundreds to thousands of solar masses, but the typical mass of the stars is likely to be set by feedback from the protostar acting on its own accretion. Following Tan & McKee (2004a), here we consider the uninterrupted growth of the star at rate given by equation (3), accreting from a stable accretion disk, and use this as the framework for assessing magnetic field generation and subsequent feedback effects.

3. DYNAMOS AND PROTOSTELLAR DISKS

Stahler et al. (1986) and Omukai & Palla (2001, 2003) considered the structure of primordial protostars in the limit of spherical accretion. They found that the protostar is radiatively stable (apart from a very thin outer layer, \( \sim 10^{-7} \) of the stellar mass; K. Omukai 2003, private communication) until \( m_* \approx 100 M_\odot \), when nuclear H burning creates a convective core. Thus, except at very high masses, little dynamo amplification in the protostar is expected. We therefore study helical disk dynamos, focusing on the production of large-scale ordered fields because these are the most susceptible to escape into the corona (Blackman 2004; Blackman & Tan 2004). There they can drive outflows that produce a feedback on the star formation process. A nonhelical dynamo may also be present, but this produces disordered random fields that do not drive a strong outflow. For the helical dynamo to operate, turbulence in a stratified rotator is the crucial requirement.

3.1. Basic Theory

We discuss likely sources of turbulence, the ability of MRI-driven turbulence to produce large-scale fields, and then the helical dynamo.

3.1.1. Sources of Turbulence

We expect that the initial driver of turbulence is gravitational instability (Gammie 2001). This may then be followed by MRI-driven turbulence (Balbus & Hawley 1998).
For sufficiently ionized and magnetized disks, the combination of radially decreasing angular velocity in a rotating plasma and seed magnetic fields can in principle drive the MRI (Balbus & Hawley 1991, 1998). The vertical stratification then provides the turbulence with the helical property from which a large-scale helical dynamo feeds. However, the critical wavenumber below which the MRI grows depends on the initial field strength: there is a minimum initial field for the instability to drive turbulence in the disk. Since primordial star-forming environments have only very weak seed fields (discussed later), it is important to evaluate this critical field strength. It is determined by requiring that the MRI growth time is shorter than the diffusion time at the scale of the initial critical vertical growth wavenumber associated with the initial seed field (Balbus & Hawley 1991, 1998). This wavenumber is \( k^2 = 3\Omega/v_A \). Since the growth rate is of the order of \( \Omega \), the condition that a given dissipation process is slower than the growth rate requires

\[
\frac{\chi^2}{\Omega} \leq \frac{3\Omega}{v_A^2} < 1,
\]

where \( \chi \) is a particular microphysical diffusion coefficient to be considered. Note that if \( \chi \) is an ambipolar diffusion coefficient, then no constraint on the field emerges since then \( \chi \propto v_A^2 \). However, if \( \chi \) is the Spitzer magnetic diffusivity (Spitzer 1967, p. 138), then the condition becomes

\[
\left( \frac{B}{G} \right)^2 > 4.0 \times 10^{-4} T_\text{s}^{-3/2} \left( \frac{m_s}{M_\odot} \right)^{1/2} \left( \frac{r}{1000 R_\odot} \right)^{-3/2} \times \left( \frac{\ln \Lambda}{10} \right)^{1/2} \left( \frac{\rho}{10^{-9} \text{ g cm}^{-3}} \right),
\]

where \( \Lambda \) is the usual Coulomb logarithm and \( T_\text{s} = T/10^3 \) K.

From this estimate we can see that while the MRI process may be able to operate given the expected initial conditions of present-day star formation, in the early universe the fields are likely to be too weak: we estimate in \( \S 3.2 \) that the initial fields that thread the disk have a maximum value of the order of \( 10^{-16} \) G. Yet, even if the MRI does not work initially, gravitational instability in the disk can in principle provide local turbulence that is amenable to an \( \alpha_{ss} \) treatment (e.g., Gammie 2001; Wada, Meurer, & Norman 2002). As we argued in \( \S 2 \), lacking other sources of viscosity, the accretion disk should establish a state in which the accretion is driven by gravitational instability. The angular momentum transport could also be global, via modes that are not describable with the \( \alpha_{ss} \) formalism. The issue of which mechanism operates and at what levels is not fully resolved (Balbus & Papaloizou 1999), requiring further numerical study. Here we assume that local turbulence does arise.

In this context and for the interpretation of simulations, it should be noted that the meaning of \( \alpha_{ss} \) is sometimes misunderstood: a turbulent disk incurs large fluctuations so that simulation data must be averaged temporally or spatially for appropriate comparisons to the \( \alpha_{ss} \) formalism to be made. The formalism for the helical dynamo that we discuss below only requires that the stratified helical turbulence yields a viscosity that can be modeled by an \( \alpha_{ss} \) parameter in the mean statistical sense.

In a turbulent disk, the small-scale field grows faster than the helical large-scale field by a factor of the order of \( \alpha_{ss}^{-1/2} \) (Blackman 1998, 2004). Thus, well before the large-scale field growth saturates, the small-scale field will grow to the critical value required for the MRI to operate. For this reason, even if the initial turbulence is driven by gravitational instability, we expect the later phase of field amplification to be mediated by the MRI and its associated \( \alpha_{ss} \).

3.1.2. Comment on MRI and Large-Scale Fields

Field amplification by the MRI in a nonstratified disk is sometimes said to produce large-scale fields (Balbus & Hawley 1998), but the meaning is subtle and easily misunderstood. In the simplest MRI simulations that use a nonstratified periodic box, the saturated magnetic energy spectrum emerges as Kolmogorov with a \( k^{-5/3} \) shape. No global flux can grow in a periodic box. The toroidal field has the largest coherent scale, but this is only of the order of the disk height. Most importantly, although the energy of this field is sustained, the sign of the field fluctuates rapidly, on a timescale of the order of the turbulent correlation time (about equal to a Keplerian rotation time for MRI unstable disks). The reason is that scales of the order of the box thickness are themselves unstable to the MRI and thus are the largest turbulent scale. The largest scale fields produced by the nonstratified MRI have the same spatial and temporal properties of the largest scale of the turbulence (Hawley, Gammie, & Balbus 1995). Such turbulent-scale fields can be shed before buoyantly rising to the coronae (Blackman 2004; Blackman & Tan 2004) and are therefore not ideally suited for driving outflows.

However, when stratification is present, the MRI can produce helical turbulence. “Helical” describes the property that rising turbulent eddies in the northern (southern) hemisphere expand and twist clockwise (counterclockwise) to conserve angular momentum, while falling turbulent eddies twist counterclockwise (clockwise). Both rising plasma and falling plasma maintain the same sign of pseudoscalars such as \( \langle v \cdot \nabla \times v \rangle \) and \( \langle b \cdot \nabla \times b \rangle \) (where \( v \) and \( b \) are the turbulent velocity and turbulent magnetic field in Alfvén units, respectively), with each having opposite signs in opposite hemispheres. Such finite pseudoscalars enable amplification of global-scale fields by helical dynamo action when the rising plasma is threaded by a magnetic field (e.g., Moffatt 1978; Parker 1979; Brandenburg 2001; Blackman & Field 2002). In a real nonperiodic system the helical dynamo can maintain a global large-scale flux over many rotation periods, as seen in nonperiodic box simulations of disks (Brandenburg et al. 1995; Brandenburg & Donner 1997). Note that Stone et al. (1996) claimed that no helicity was observed in their stratified periodic box disk simulations, when averaged over hemispheres (J. M. Stone 2003, private communication). Further studies are required to reconcile these results.

3.1.3. The Helical Dynamo

Recently, Blackman & Field (2002) developed a dynamical nonlinear helical dynamo theory that accounts for the nonlinear back-reaction of the magnetic field on large-scale field growth and agrees with recent helical dynamo simulations (Brandenburg 2001). The driver of exponential large-scale field growth, \( \alpha_d \), turns out to be proportional to the residual helicity \( \langle v \cdot \nabla \times v \rangle - \langle b \cdot \nabla \times b \rangle \) (Pouquet, Frisch, & Leorat 1976), rather than just the kinetic helicity \( \langle v \cdot \nabla \times v \rangle \) used in textbooks for similar dynamos. Large-scale field growth occurs in two phases: an early, fast kinematic phase and a late, slow resistive phase. Generation of the large-scale field is
associated with large-scale magnetic helicity, while helicity conservation means that the small-scale helicity grows with the opposite sign. As this happens, \( \langle \mathbf{b} \cdot \nabla \times \mathbf{h} \rangle \) grows and offsets the \( \langle \mathbf{v} \cdot \nabla \times \mathbf{v} \rangle \), shutting down the dynamo. These principles seem to survive in dynamos with shear (Blackman \& Brandenburg 2002). Although the above results are for simplified dynamos, we use the saturation principles in what follows, by incorporating them into an \( \alpha \cdot \Omega \) accretion disk dynamo. Other approaches to mean field accretion dynamo models have been developed by, for example, Pudritz (1981), Rüdiger, Elstner, \& Stepinski (1995), Stepinski (1995), Reyes-Ruiz \& Stepinski (1997, 1999), and Campbell \& Caunt (1999).

To estimate the large-scale field, \( \mathbf{B} \), produced by a helical dynamo, we need the growth rate. We use a mean field theory for large-scale field growth in a turbulent disk. This approach presumes that the mean quantities vary on timescales long compared to that of the fluctuating turbulent quantities. Therefore, the derived mean field growth rate, \( \gamma \), should be slower than the eddy turnover rate, i.e., \( \gamma < \Omega \), where the latter is also the growth rate of the random field (e.g., Balbus \& Hawley 1998). We find that this condition is indeed satisfied.

We assume \( \mathbf{B} = \mathbf{B}_0 \exp(\gamma t + ikz) \), where \( k_z \) is the vertical wavenumber. The basic equations for the radial and toroidal field in an “\( \alpha \cdot \Omega \)” dynamo for a Keplerian disk become (e.g., Ruzmaikin, Shukurov, \& Sokoloff 1988, p. 163)

\[
\gamma \mathbf{B}_r = -ik_z (\alpha_d \mathbf{B}_0) - \beta k_z^2 \mathbf{B}_r
\]  
(8)

and

\[
\gamma \mathbf{B}_\phi = -\frac{1}{2} \Omega \mathbf{B}_r - \beta k_z^2 \mathbf{B}_\phi,
\]  
(9)

where we ignore spatial dependencies of the pseudoscalar \( \alpha_d \) and turbulent transport scalar \( \beta \) and assume that averages are taken within a given hemisphere. We assume \( \alpha_d = q \alpha_{d0} \), where the time-dependent multiplicative factor \( q \leq 1 \) represents the back-reaction from \( \langle \mathbf{b} \cdot \nabla \times \mathbf{b} \rangle \), with \( q = 1 \) in the kinematic regime.

There are two possible dominant contributions to \( \alpha_{d0} \): a Coriolis force effect and a magnetic buoyancy effect. First consider the Coriolis force acting on the turbulent eddies, of typical scale \( l \). A rising and expanding (falling and contracting) eddy rotates in the opposite (same) sense as that of the underlying disk rotation during its turbulent correlation time, \( t_{\text{ed}} = l/\nu \). Therefore, while conserving angular momentum about the disk axis, such eddies gain a specific angular momentum about their own symmetry axis such that \( \langle \mathbf{v} \cdot \nabla \times \mathbf{v} \rangle \) is nonvanishing and of opposite sign in each hemisphere. Using the equation for \( \nabla \times \mathbf{v} \) evolution and the mass continuity equation and assuming that the density varies on scale \( h \), this leads to the estimate (Ruzmaikin et al. 1988)

\[
\alpha_{d0} = t_{\text{ed}} (\mathbf{v} \cdot \nabla \times \mathbf{v}) \sim \frac{t_{\text{ed}}}{v} [ \nabla \times (\Omega \times \mathbf{v}) ]
\]  
(10)

where the last relation follows from mass continuity and \( \text{Ro}_h \equiv \nu/\nu_\text{Rossby} \) is the Rossby number.

For thin disks in the Shakura-Sunyaev formalism,

\[
l \sim \alpha_{s0}^{1/2} h / \text{Ro}_b^{1/2}
\]  
(11)

and

\[
\nu \sim \alpha_{s0}^{1/2} \text{Ro}_b^{1/2} \epsilon_s,
\]  
(12)

which follow since \( \nu \sim \nu_0^2 / (\Omega \text{Ro}_d) = \alpha_{s0} \epsilon_s \nu_0 \) and \( \Omega h \sim \epsilon_s \). Using equation (11) in equation (10), we have

\[
\alpha_d = q \alpha_{d0} \sim q \alpha_{s0} \nu_0. \]  
(13)

It also follows that the maximum fractional kinetic helicity satisfies

\[
f_h = \min \left( \frac{\alpha_{d0}}{\nu}, \frac{\alpha_{s0}^{1/2}}{\text{Ro}_b^{1/2}} \right). \]  
(14)

It is important to note that while equation (10) is a standard estimate for \( \alpha_{d0} \), Brandenburg \& Donner (1997) found that for large-scale field generation in local shearing box simulations the contribution seemed to have the opposite sign of that required to produce the measured mean field. It was later suggested (Brandenburg 1998) that a magnetic buoyancy term of the form \( t_{\text{ed}} (b_x b_y (g_z/p)) \), where \( b_x, b_y \) are the fluctuating components of the magnetic field, \( g_z \) is the vertical gravity, and \( p \) is the pressure, actually has the correct sign. Since this term is \( \sim (1/\Omega) (v_i^2/e_z)^n e_z \sim \Omega^2 / h \), which has the same order of magnitude and scalings as equation (10), it does not significantly affect our calculations based on the use of equation (13), unless the two cancel to high order. The cycle period analyzed by Brandenburg \& Donner (1997) suggests some cancellation. However, they studied the late time evolution of the dynamo, after the kinematic regime saturates.

With our assumed form for \( \mathbf{B} \), we solve equations (8) and (9), use equation (13), and set \( k_z \sim 1/\nu \) and \( \beta \sim \nu = \alpha_{s0} \nu_0 \), to derive the growth rate

\[
\gamma = \left( \frac{3 \alpha_{d0} \nu_0}{4} \right)^{1/2} \beta k_z^2 \sim \frac{1}{2} \alpha_{s0} \epsilon_s \left( \sqrt{5} q / 2 - \alpha_{s0}^{1/2} \right) h.
\]  
(15)

Note that with \( q = 1 \), for growth this requires a dynamo number \( D \equiv \langle 3/2 \rangle \Omega \text{Ro}_h^3 / \beta^2 \rangle > 2 = D_\epsilon \), the critical dynamo number. Critical dynamo numbers for disks are sometimes derived to be greater than 8 (e.g., Ruzmaikin et al. 1988), but this value depends on the assumed profile of \( \alpha(z) \). We have crudely assumed a nearly constant profile with \( z > 0 \), and thus our critical dynamo number is low.

At a given stage in the evolution when the stellar mass is \( m_* \), we estimate \( \mathbf{B} \) as the smaller of (1) the saturation value at the end of the kinematic regime and (2) the value reached given the growth time that the disk dynamo has been able to operate,

\[
t_{\text{grow}} = t(m_*) - t_{\text{init}},
\]  
(16)

where \( t_{\text{init}} \) is the time at which the protostellar disk becomes susceptible to turbulence. We define \( t = 0 \) at the time when the protostellar core has just started to form, and then from equation (3) we have

\[
t(m_*) = \frac{27 (1 + f_d) 3^{10/7} c_d^{-10/7} K^{-15/7} \left( \frac{m_*}{M_\odot} \right)^{10/7}}{yr}.
\]  
(17)
Several factors potentially determine $t_{\text{init}}$. First, we require a critical level of ionization so that the field’s growth time due to the dynamo is substantially shorter than the diffusion time. Brandenburg et al. (1995) found a critical fractional ionization of disk material of $\sim 10^{-14}$ for growth of the MRI, corresponding to a neutral-ion collision frequency $\sim 10$ times the orbital frequency. The MRI has a growth time $\alpha_{\text{ss}}$ times that of the large-scale helical field, and so our critical ionization fraction is $\sim \alpha_{\text{ss}}^{-1} 10^{-14} \sim 10^{-13}$. This condition is well satisfied for the inner regions of primordial protostellar disks, once the star has a mass that is even just a small fraction of a solar mass. Thus, $t_{\text{init}}$ (and the corresponding $m_{\text{init}}$) is set by the time for disk formation in the collapsing flow, i.e., when the centrifugal radius of the flow becomes significantly larger than the protostellar radius. For the fiducial case of $K'=1$ and $f_{\text{kep}} = 0.5$, this occurs very early on, when the star has mass $m_{\text{init}} \sim 0.4 M_{\odot}$.

One might think that the time available for field growth at a given radius is the accretion timescale at that radius, rather than the disk age. However, since the mean field formalism is statistical, amplification occurs as long as the system remains in quasi-statisical equilibrium (i.e., as long as helically turbulent plasma is steadily supplied to that location). A related point is that as long as $\beta > (L^2/\mu)^{1/2}$, where $L \sim h$ is the vertical variation scale of the large-scale field, a poloidal mean field is likely not frozen into the plasma on an accretion timescale and would diffuse away if the $\alpha_d$ helicity effect is ignored. This then motivates the need for the $\alpha_d$ effect and large-scale dynamos in the first place (Lubow et al. 1994; Blackman 2004; Blackman & Tan 2004). For completeness, however, we also provide the estimated field when the growth time is limited to the local accretion time.

After the kinematic regime, subsequent field growth becomes resistively limited as the kinetic and current helicities nearly balance. The magnitude of the helical component of the mean field when this occurs is given by (Blackman & Field 2002; Blackman 2004)

$$\mathbf{B}_H \sim (4\pi \rho h)^{1/2} v \left( \frac{1}{h} \right)^{1/2} \alpha_{\text{ss}} c_s, \quad (18)$$

where the latter similarity follows from equations (11), (12), and (14). We take this to be an estimate of the poloidal field; i.e., we assume $\mathbf{B}_r \sim \mathbf{B}_H$. We assume that the strength of the toroidal field at the surface $\mathbf{B}_\theta$ is comparable to its value within the disk. This toroidal field is larger than $\mathbf{B}_r$ because it is linearly amplified above the value of $\mathbf{B}_r$ by shear as it rises into the coronae during a buoyancy or diffusion timescale. These timescales are $t_{\text{bun}} \sim h(4\pi \rho h)^{1/2}/\mathbf{B}_3$ and $t_{\text{diff}} \sim h/\alpha_{\text{ss}} c_s$, respectively. Linear growth of $\mathbf{B}_\theta$ above the level predicted by equation (18) in a time $t_{\text{bun}}$ gives $\mathbf{B}_\theta = \mathbf{B}_3 \Omega_{\text{bun}} = \alpha_{\text{ss}} c_s (4\pi \rho h)^{1/2}$, which from equations (18) and (12) implies $\mathbf{B}_\theta / \mathbf{B}_3 = \alpha_{\text{ss}}^{1/2}$. Similarly, if the growth of $\mathbf{B}_r$ is limited by turbulent diffusion, then $\mathbf{B}_r = \mathbf{B}_0 \Omega_{\text{diff}}$, so that $\mathbf{B}_\theta / \mathbf{B}_0 \sim \alpha_{\text{ss}}$.

To summarize, for an initial seed field $\mathbf{B}_0$ we expect the final field strengths to be

$$\mathbf{B}_r \simeq \min \left[ \mathbf{B}_0 \exp \left( \gamma_0 t_{\text{grow}} \right), \alpha_{\text{ss}} c_s (4\pi \rho h)^{1/2} \right], \quad (19)$$

where $\gamma_0 \sim \alpha_{\text{ss}}^{1/2} c_s / h = \alpha_{\text{ss}}^{1/2} \Omega$ is the kinematic $\gamma$, obtained from equation (15) with $q \sim 1$, and

$$\mathbf{B}_\theta = \alpha_{\text{ss}}^{-1} \mathbf{B}_r. \quad (20)$$

if $\mathbf{B}_\theta / (4\pi \rho h)^{1/2} < \alpha_{\text{ss}} c_s$ (i.e., when $t_{\text{bun}} > t_{\text{diff}}$) or

$$\mathbf{B}_\theta = \alpha_{\text{ss}}^{-1/2} \mathbf{B}_r$$

(21)

if $\mathbf{B}_\theta / (4\pi \rho h)^{1/2} > \alpha_{\text{ss}} c_s$ (i.e., when $t_{\text{bun}} < t_{\text{diff}}$). The latter case applies in the saturated state.

### 3.2. Expected Values for Star-forming Disks

To determine the expected $\mathbf{B}$ in star-forming disks, we must estimate the seed field, assess flux freezing for the initial collapse of the cloud to form the disk, and estimate the growth timescale to determine if the field has saturated. The seed field for the primordial star-forming environment can be estimated from the Biennmann battery mechanism for nonharotropie flows. On scales much larger than that of an individual star, numerical simulations indicate that by $z = 18$, seed fields of the order of $\mathbf{B}_0 \sim 10^{-26}$ G can be generated (Kulsrud et al. 1997). We assume that such a field is generated inside the prestellar core region in the simulation of ABN02, which has a size $\sim 100$ pc and a density $\sim 10^{-26}$ g cm$^{-3}$. The infall speeds within this region are of the order of km s$^{-1}$, vastly greater than the drift speeds of the ions through the neutrals (the ionization fractions are much greater than the equilibrium values for the gas, which has a minimum temperature of $\sim 200$ K). Thus, the field is frozen into the contracting gas going from parsec to AU scales; the field strength increases by factors of $\sim 10^{10}$, so the seed field in the disk may then be $\sim 10^{-16}$ G.

It may actually be that much larger seed fields could arise in the protostar from the Biennmann battery term if the pressure and density gradients are misaligned inside the protostar as well. The protostellar Biennmann battery (e.g., Kulsrud et al. 1997) value reached after a rotation time (at which point other growth terms become important) can be estimated to be $\mathbf{B}_0 \simeq (m_{\text{H}} e/[(\nabla_\rho \cdot \mathbf{V}_\rho)/\rho \Omega]) \sim 2 \times 10^{-11} (T/10^5 \text{ K})^{1/2} (r/10^{13} \text{ cm})^{-3/2} (h/r) \text{ G}$, where we have used $\Omega = c_s/h$ and have conservatively taken $\nabla \sim 1/r$. In the disk, flux freezing and field advection are not guaranteed since, as discussed above, turbulent diffusion of the mean field may be relatively efficient and the accretion timescale may be relatively long. Thus, in addition to a fiducial initial seed field strength of $\mathbf{B}_0 = 10^{-16}$ G, we also consider a conservative value of $\mathbf{B}_0 = 10^{-26}$ G. Since the disk dynamo amplifies the initial field exponentially, the uncertainties in the strength of the seed field do not significantly affect the time to reach saturation.

Using $\gamma_0 \sim \alpha_{\text{ss}}^{1/2} c_s / h = \alpha_{\text{ss}}^{1/2} \Omega$ from equation (15) with $q = 1$ and approximating $t_{\text{grow}} = t(m_*) = 0.7 m_*/M_{\odot}$, the first term on the right-hand side of equation (19) becomes

$$\mathbf{B}_r \sim 8.9 \times 10^8 G \left( \frac{\mathbf{B}_0}{10^{-26} \text{ G}} \right) \exp \left[ \alpha_{\text{ss}} \frac{1}{0.01} \left( \frac{m_*}{M_{\odot}} \right)^{3/2} \right] \times \left( \frac{r}{10^{13} \text{ cm}} \right)^{-3/2} \left( \frac{m_*}{0.01 M_{\odot} \text{ yr}^{-1}} \right)^{-1}, \quad (22)$$

while the second term gives

$$\mathbf{B}_\theta \sim 49 G \left( \frac{\alpha_{\text{ss}}}{0.01} \right)^{1/2} \left( \frac{m_*}{M_{\odot}} \right)^{1/4} \left( \frac{M_{\odot}}{0.01 M_{\odot} \text{ yr}^{-1}} \right)^{1/2} \times \left( \frac{r}{10^{10} \text{ cm}} \right)^{-3/2} \left( \frac{h}{10^2 \text{ cm}} \right)^{-1/2}, \quad (23)$$
where mass continuity at \( r = 2r_{\ast} \), \( \rho = \dot{m}_{\ast}/(4\pi r^2 \alpha_{ss} c_s) \), was used, and we choose parameters commensurate with the results of § 2. Although primordial protostars are thought to have accretion rates somewhat higher than the \( 10^{-2} M_\odot \) yr\(^{-1} \) adopted in equation (22), it is clear from these equations that we expect the field to saturate when the protostar has a relatively small mass. Note that the seed fields for present-day Galactic protostellar disks would be many orders of magnitude higher than the primordial case: the initial Galactic interstellar material possesses a field of \( \lesssim 10^{-6} \) G. Thus, for a wide range of parameters equation (23) is the relevant estimate for the dynamo-amplified large-scale field strengths in present-day, as well as primordial, protostellar disks. For the primordial case, we evaluate the saturation point more accurately in the \( m_{\ast}\dot{m}_{\ast} \) plane and show the results in Figure 4.

In the fiducial case the field in the inner disk saturates by about 1 \( M_\odot \), and this does not depend very sensitively on \( \alpha_{ss} \). In lower angular momentum cores the disk emerges later, at which point the dynamo rapidly causes the field to saturate. Although we expect that mean field dynamo can grow field at a given location for longer than the local accretion time, we also evaluate the cases where \( t_{\text{grow}} = t_{\text{acc}} \sim 2\pi \dot{m}_{\text{inf}}/\Omega \approx r^2/(\alpha_{ss} c_s h) \). The resulting field strength must always be smaller than that from equation (22) for disks for which \( \alpha_{ss} \) models are self-consistent. The saturation point is delayed until masses \( m_{\ast} \sim 10 - 20 M_\odot \) in the fiducial case.

4. IMPLICATIONS OF LARGE-SCALE FIELDS FOR PRIMORDIAL STAR FORMATION

4.1. The Power of Magnetically Mediated Outflows

The primary effect of the magnetic field that we consider is the generation of a magnetically mediated jet or wind. Integrating the vertical Poynting flux through the disk in each vertical half gives an estimate of the magnetic luminosity available for driving each outflow:

\[
L_{\text{mag},1/2} \sim B_0 \dot{\Omega} B_{z,1/2} \Omega r^3, \tag{24}
\]

where \( B_{0,1/2} \) and \( B_{z,1/2} \) are the toroidal and vertical fields just inside the disk surface (defined at 1 scale height above the midplane). The field strengths we estimated in the previous section represent fields inside the disk, so the use of equation (24) really requires a solution of the global boundary value problem (e.g., Rügier et al. 1995; Reyes-Ruiz & Stepienski 1997, 1999). For present purposes, we make crude estimates for the surface fields. We take \( B_{0,1/2} \approx \alpha_{ss}^{-1/2} B_{r,1/2} \), as estimated in the previous section, where \( B_{0,1/2} \approx \frac{1}{2} B_{\phi,1/2} \) and \( B_{z,1/2} \approx \frac{1}{2} B_{r,1/2} \) are the respective average values over a scale height, using flux freezing in which the density falls a factor of 1/e between the midplane and surface. Note that for a constant \( \alpha_{ss} \) disk, \( v_{\text{e}}/c_s \) is a constant (Blackman 1998). Then with \( c_s \approx r^{-1/2} \) and \( \rho \approx r^{-3/2} \), we have \( B_r \propto r^{-5/4} \), so that \( L_{\text{mag}} \) is dominated by the contribution generated at the inner disk radius.

Now we use the above relations to estimate \( B_{z,1/2} \), by appealing to \( \nabla \cdot \mathbf{B} = 0 \). We integrate this over an annular wedge of the disk extending from the midplane to the surface, with azimuthal extent \( \Delta \phi \), and with radial extent \( \delta r \), where \( \delta r \sim r \) is the characteristic radial scale over which the vertical and radial fields change significantly. The toroidal flux does not contribute to this integral, and by the assumption that the vertical field vanishes at the midplane, no net flux penetrates the equatorial plane. Then integrating \( \nabla \cdot \mathbf{B} = 0 \) over the described volume gives

\[
\Delta \phi \left[ B_{r,1/2} h_i r_i - r_o B_{r,1/2} \right] \left( \frac{r_i}{r_o} \right)^{5/4} \left( \frac{h_i}{r_i} \right) \frac{r_i}{r_o} = \Delta \phi \frac{4}{3} \left[ B_{z,1/2} r_i^{5/4} \left( \frac{r_o}{r_i} \right)^{3/4} - r_i^{3/4} \right], \tag{25}
\]

where the subscripts \( i \) and \( o \) refer to inner and outer radii, respectively, and we assume \( h/r = h_i/r_i \), that is, the ratio is independent of \( r \), which is a reasonable approximation (see Figs. 2 and 3). In the limit \( r_o \gg r_i \) and using \( B_{r,1/2} = \frac{1}{2} B_r \) from above, we obtain

\[
\frac{B_{z,1/2}}{B_{r,1/2}} = \frac{9 h}{16 r}. \tag{26}
\]

From equation (21), \( B_{\phi,1/2} = \alpha_{ss}^{-1/2} B_{r,1/2} \), so that equation (24) for the outflow power becomes

\[
L_{\text{mag},1/2} \sim \frac{27 h}{64 r} \alpha_{ss}^{-1/2} B_r^2 \Omega r^3. \tag{27}
\]

The procedure for using equation (27) to assess the value of \( L_{\text{mag}} \) for star-forming disks is to pick a particular star
formation model (which means choosing \( \alpha_{ss}, m_\star, \) and \( \dot{m}_\star \)) and inferring from its solution whether the field has saturated or not (from eqs. [22] and [23]). The appropriate field strength is then used in equation (27) to estimate the wind luminosity.

The case of a saturated field (eq. [23]) is the most interesting:

\[
L_{\text{mag,1/2}} \sim \frac{27}{64} \alpha_{ss}^{1/2} \frac{Gm_\star \dot{m}_\star}{r} = 0.84 \alpha_{ss}^{1/2} \frac{L_{\text{max,1/2}}}{r} = 92 \left( \frac{\alpha_{ss}}{0.01} \right)^{1/2} \frac{\dot{m}_\star}{M_\odot} \frac{\dot{m}_w}{0.01 \text{ yr}^{-1}} \left( \frac{r}{10^{13} \text{ cm}} \right)^{-1} L_\odot,
\]

(28)

where \( L_{\text{max,1/2}} = Gm_\star \dot{m}_\star / 2r \) is the upper limit on the magnetic luminosity through each disk plane available from accretion. Note that \( L_{\text{mag,1/2}} < L_{\text{max,1/2}} \) as expected, for all reasonable values of \( \alpha_{ss} \) (formally \( \alpha_{ss} < 1 \)). The evolution of \( L_{\text{mag}} \) with \( m_\star \) is shown in the top panel of Figure 5, together with the radiative luminosity from the fiducial protostellar evolution model of Tan & McKee (2004a). The wind luminosity is a fixed fraction of the accretion luminosity from the inner disk.

Fields produced by a helical dynamo are ordered such that their smallest gradient scale exceeds that which would otherwise result in their turbulent destruction before rising to the corona. However, there is an additional process in the generation of global large-scale fields in the corona that we have not discussed above: the fields supplied by the disk dynamo must incur further evolution to even larger scales once in the corona. Their scale in the disk is a few times \( h \), but the required large scale in the corona is \( \sim r \). While this further opening or “dynamical magnetic relaxation” process requires further study with direct application to the disk-corona system, there is ample reason to believe that it happens sufficiently fast when the supplied fields from the dynamo are helical (as they would be from a helical disk dynamo, and further supplemented by footprint shear): it has long been known that helical fields relax to the largest scale available to them in magnetically dominated environments (Taylor 1986), and it has been further shown recently that when helical magnetic fields are injected into such a magnetically dominated region, this relaxation occurs on an Alfvén crossing time (Blackman & Field 2002). The speed is independent of the value of the magnetic diffusivity, as long as the latter is not identically zero. For this reason the dynamical relaxation in the corona would naturally allow further opening of disk-supplied fields to global scales, not unlike the “magnetic carpet” evolution in the solar corona (Schrijver & Zwaan 2000).

Given the magnetic luminosity, we estimate the mass loading and momentum of the outflow. We assume that at large distances from the star the energy content of the flow is dominated by the kinetic energy of the matter, so that \( L_{\text{mag}} = \dot{m}_w v_w^2 / 2 \), where \( \dot{m}_w \) is the mass outflow rate and \( v_w \) is the terminal velocity. Theoretical models of magnetocentrifugally driven outflows suggest that \( v_w \) is about equal to the escape velocity from the protostar, \( v_{\text{esc},*} \) (e.g., Shu et al. 2000; Königl & Pudritz 2000). We write \( v_w = f_{v_{\text{esc},*}} \), where \( f_v \) is a factor of order unity. Then the mass flux of the outflow is

\[
\dot{m}_w = \frac{27 \alpha_{ss}^{1/2}}{32} \frac{\dot{m}_\star}{f_v^2} \sim 0.084 \dot{m}_\star.
\]

(29)

We note that \( \alpha_{ss} \) is uncertain, as are the numerical prefactors of equations (28) and (29). For a massive protostar that is approaching the Eddington limit, the mass loading of the outflow may be significantly enhanced.

4.2. Feedback Effects from Outflows

In present-day star formation, protostellar outflows contribute the following feedback effects: (1) they prevent the accretion of gas in the polar regions of the star-forming core that would otherwise have joined the star, and they divert a fraction of the accretion flow in the disk (e.g., Matzner & McKee 2000); (2) they inject mechanical energy into giant molecular clouds, which helps to keep the clouds turbulent (Norman & Silk 1980); and (3) through the presence of dense, outflowing gas near the star, they inhibit the reach of other feedback effects, such as ionizing radiation (Tan & McKee 2004b). We discuss the significance of these processes in the context of primordial star formation.

4.2.1. Star Formation Efficiency

First, consider the expulsion of gas from the polar regions of the core. By balancing magnetic tension and magnetic
pressure gradients, Matzner & McKee (1999; see also Shu et al. 1995; Ostriker 1997) showed that far from the star the angular distribution of the momentum in a radial hydromagnetic wind can be approximated by

\[
\frac{dp_w}{d\Omega} = p_w \frac{1}{4\pi \ln(2/\theta_0)(1 + \mu_0^2 - \mu^2)},
\]

where \(\mu = \cos \theta\) and \(\theta_0\) is a small angle, which is estimated to be \(\sim 0.01\) for winds from low-mass stars (Matzner & McKee 1999) but may be somewhat larger for winds from massive stars. We adopt this value in the primordial case (our results are not particularly sensitive to this choice). Equation (30) is also a reasonable description for the angular distribution of the mass flux in the wind, assuming that the terminal velocity (far from the star, but before deceleration by the ambient gas) is independent of \(\theta\).

To evaluate the efficiency of star formation from a core (i.e., the fraction of mass that forms a star) \(\epsilon_{core}\), we follow Matzner & McKee (2000) and find the angle, \(\epsilon_{esc} \equiv \cos^{-1} \mu_{esc}\), where the wind sweeps up core material to the surface escape speed of the core, \(v_{esc,c}\). The analysis assumes thin, radiative shocks, purely radial motion, and monopole gravity. We consider cores with angular mass distributions of the form \(dM/d\Omega = (1/4\pi)Q(\mu)\) \(M\) with \(Q(\mu) = (1 - \mu^2)^n / \int_0^1 (1 - \mu^2)^n d\mu\) and evaluate models with \(n\), ranging from 0, isotropic, to 4, which describes a flattened distribution that mimics the effect of some rotational support. In the notation of Matzner & McKee (2000), the escape condition is given by \((1 + \mu_0^2 - \mu^2)^n Q(\mu_{esc}) = m_*/(XM)\), where \(X = 0.132 c_0 \ln(2/\theta_0)/\ln(200 v_{esc,c} \mu_{esc})\), \(p_w/m_0\), and \(c_0\) is a factor of order unity that accounts for the effects of gravity on shock propagation. Using the results of Matzner & McKee (2000), we estimate \(c_0 \approx 4.6\), for steady winds that decouple from the swept-up shell at the core edge in a core with \(k = 20/9\) (which is the fiducial value of Tan & McKee 2004a). These cores have \(v_{esc,c} = 3.22(M/1000 M_\odot)^{-1/7} R_1^{5/7}\) \(\text{km} \cdot \text{s}^{-1}\). We ignore the influence of material beyond the core “edge,” which is partly balanced by our neglect of the wind’s influence on the shell beyond this point. The efficiency is given by

\[
\epsilon_{core} = \frac{1}{1 + (m_\text{w}/m_*) (1 - \phi_w)} \int_0^{\phi_w} Q d\mu,
\]

where \(\phi_w \equiv \int_0^{\phi_w} P d\mu\) and \(P(\mu)\) is the dimensionless force distribution in angle. Note that unlike \(\epsilon_{sd}\), which was used in equation (3), this definition of efficiency includes the effect of diversion of material from the disk into the outflow. However, since \(f_w \equiv m_\text{w}/m_* \ll 1\), \(\epsilon_{core} \approx \epsilon_{sd}\).

In summary, we are assuming that the properties of the protostellar outflow, and how they evolve with \(m_*\), do not depend on \(\epsilon_{core}\). In reality, as \(\epsilon_{core}\) and \(m_*\) become smaller, then the protostellar evolution changes, e.g., the stellar growth time becomes longer relative to the Kelvin-Helmholtz time, so that the star would tend to be smaller. However, since \(p_w\) is integrated over the stellar evolution, it should not be so sensitive to these changes.

We show the evolution of \(p_w/m_*\) with \(m_*\) for our fiducial model in the middle panel of Figure 5. Initially \(r_s\) is approximately constant and the specific momentum of the wind grows only because of the increasing mass and escape velocity from the star. Then above \(m_* \approx 20 M_\odot\), the star starts shrinking toward the main sequence and there is a jump in the momentum input. This marks the start of the transition to lower efficiency star formation from the core (Fig. 5, bottom panel). This transition may have important implications for the final mass of the star and will be examined in more detail in a future paper. Note that this efficiency is not particularly sensitive to the parameter \(\theta_0\) when the critical angle for ejection of gas from the core is \(\gtrsim \theta_0\). In other words, mass limits to star formation resulting from this process do not depend on \(\theta_0\) so long as \(\theta_0 \ll 1\).

4.2.2. Feedback on the Larger Scale Cloud and Breakout from the Dark Matter Halo

We have seen that the protostellar outflow is eventually able to break free of the core. With the distribution of momentum given by equation (30), this is particularly true near the rotation axis, since about half of the initial outflow mass is concentrated inside \(r_s\). A \(100 M_\odot\) star releases a wind with total momentum of about \(10^4 M_\odot \text{ cm} \cdot \text{s}^{-1}\), with about a quarter of this inside \(r_s\) of each jet, for which the injected mass is about \(2 M_\odot\). Each central jet region can then sweep up \(\sim 500 M_\odot\) to about \(5 \text{ km} \cdot \text{s}^{-1}\), which is the approximate sound speed and escape speed of the gas in the vicinity of the dark matter minihalo. The fiducial core of Tan & McKee (2004a) has a total virialized baryonic mass of \(\sim 10^3 M_\odot\) (based on the simulation of Abel et al. 2002), with a few times \(10^4 M_\odot\) of gas still infalling within a couple hundred parsecs. For reasonable values of \(\theta_0 \lesssim 0.1\), and even with allowance for turbulent entrainment of matter at the sides of the jets and lateral spreading, the outflows should easily be able to eject some gas from the dark matter halo. Thus, we expect the extent of mechanical feedback to reach beyond the immediate environment of the star-forming core.

The physical implications of this feedback are difficult to assess, since radiative feedback from the massive protostar is also acting on the cloud during this time. If outflows do escape from the halo, then they will start to pollute the intergalactic medium with their magnetic fields. This is only one possible mechanism for producing such fields. Others include field generation in shocks caused by supernovae or ionization fronts (Subramanian et al. 1994; Gnedin et al. 2000), and these mechanisms should have a longer reach than the protostellar outflows. Outflows from AGNs are also likely to be important, although these may be more sparsely distributed than Population III stars.

4.2.3. Confinement of Radiative Feedback by Protostellar Outflows

The presence of dense, outflowing gas near the protostar can suppress the influence of radiative feedback. For example, the propagation of ionizing photons should be impeded. The characteristic density at the base of the flow region near the star is

\[
m_{\text{H}_2, \text{base}} = 4 \times 10^{11} f_w^{-1} \left(\frac{f_w}{2}\right)^{-2} \left(\frac{f_w}{0.1}\right) \left(\frac{\dot{m}_w}{10^{-3} M_\odot \text{yr}^{-1}}\right) \times \left(\frac{r_s}{10 R_\odot}\right)^{-3/2} \left(\frac{m_*}{100 M_\odot}\right)^{-1/2} \text{cm}^{-3},
\]

where \(f_w \equiv m_\text{w}/m_*\) and we have assumed that the wind is launched from the inner part of the disk from an annulus of inner radius \(f_w r_s = 2r_s\) and outer radius \(2f_w r_s\).
Assuming an isotropic flux, the ionizing luminosity necessary to balance recombinations and fully ionize the gas is given by

\[ S_{\text{crit}} = \frac{\alpha}{4\pi} \int_{f_{\text{cr}}}^{2f_{\text{cr}}} \alpha(2) n_{\text{H}_1} n_e r^2 \, dr, \]

where \( \alpha(2) = 2.62 \times 10^{-13} \text{ s}^{-1} \) is the radiative recombination rate to the excited states of hydrogen at \( 10^4 \text{ K} \) and \( n_e \) is the electron number density. We assume singly ionized He, so that

\[ S_{\text{crit}} = 2.9 \times 10^4 f_e^{-2} \left( \frac{f_e}{0.1} \right)^2 \left( \frac{m_\star}{10^{-3} \text{ M}_\odot \text{ yr}^{-1}} \right)^2 \times \left( \frac{m_\star}{100 \text{ M}_\odot} \right)^{-1} \text{ photons s}^{-1}. \]  

Models of Population III stellar structure (Tumlinson & Shull 2000; Baraffe, Heger, & Woosley 2001; Bromm, Kudritzki, & Loeb 2001; Schaerer 2002) yield zero-age main-sequence (ZAMS) ionizing luminosities that can be approximated via

\[ S = 9.42 \times 10^{49} (m_\star/30 \text{ M}_\odot)^{2.3} \text{ photons s}^{-1} \text{ for } 12 < m_\star/\text{M}_\odot < 40, \]

\[ S = 9.17 \times 10^{49} (m_\star/100 \text{ M}_\odot)^{1.7} \text{ photons s}^{-1} \text{ for } 40 < m_\star/\text{M}_\odot < 120, \]

and

\[ S = 3.75 \times 10^{39} (m_\star/300 \text{ M}_\odot)^{1.2} \text{ photons s}^{-1} \text{ for } 120 < m_\star/\text{M}_\odot < 1000. \]

The critical ZAMS mass that can ionize the outflow from a protostar accreting at the fiducial rate (eq. [3]) is then given by

\[ m_{\star, \text{crit}} = 34 f_e^{-0.46} \left( \frac{f_e}{0.1} \right)^{-0.23} \left( \frac{f_e}{0.1} \right)^{0.46} \epsilon_{\text{rad}}^{0.66} K^{0.98} \text{ M}_\odot, \]

so long as \( 12 < m_{\star, \text{crit}}/\text{M}_\odot < 40 \). Similar relations can be derived for when \( m_{\star, \text{crit}} \) is in a higher mass range.

Primordial protostars only reach the ZAMS at masses around 100 \( \text{M}_\odot \) (Omukai & Palla 2001, 2003; Tan & McKee 2004a). Before this the ionizing luminosity is initially very small because the protostar is large and relatively cool. In the fiducial case the ionizing luminosity, including the contribution from accretion luminosity, then increases rapidly to become equal to the ZAMS value at about 40 \( \text{M}_\odot \). (Fig. 7 of Tan & McKee 2004a). Therefore, we expect the outflow to be able to confine ionizing radiation for much of the pre-main-sequence phase of protostellar evolution up to about 40 \( \text{M}_\odot \), but not after that. These results have implications for feedback models that are based on the ionization of the protostellar disk (e.g., Hollenbach et al. 1994). In present-day massive star formation this process of confinement by the outflow can create extremely compact \text{H II} regions around massive protostars (Tan & McKee 2004b). A more complete analysis of the feedback effects in the primordial case, including those from far-ultraviolet photons, is beyond the scope of this paper and is deferred to a future study.

5. CONCLUSIONS

We have presented calculations of the radial structure of primordial protostellar disks, using realistic models for the rate of accretion and the size of the protostar (Tan & McKee 2004a). We have followed the evolution of disk properties as the protostar grows in mass and changes in size. These disks differ from those around present-day protostars because of the lack of cooling due to dust and because of the high rates at which they are fed matter from the collapsing core. The high accretion rates and large protostellar sizes require inclusion of the ionization energy in the structure equations, the effect of which is to reduce the disk temperatures and luminosities, particularly for disks around protostars with masses \( \lesssim 20 \text{ M}_\odot \). We argue that fragmentation in the disks is unlikely to occur, if local gravitational instabilities can provide an effective viscosity of the magnitude seen in the simulations of Gammie (2001).

We have shown that in situ dynamos can produce dynamically significant large-scale magnetic fields in primordial star-forming disks. For present-day disks, such fields would likely be important for driving outflows in all star-forming systems. For the primordial case, the disks of the lowest mass protostars would not have enough time to generate strong fields, but the majority of the star-forming parameter regime at higher masses leads to strong fields even for very conservative assumptions about the initial seed magnetic field. Thus, models of primordial star formation should include the dynamical influence of magnetic fields.

We emphasize that for these conclusions to be valid, gravitational instability, rather than the MRI, must provide the initial source of turbulence in the disk. Even though the ionization fraction is high, the seed field is below the critical value required at the mode of fastest growth. This contrasts with the situation in present-day protostellar disks. A second requirement is that the turbulence in the disk must generate helicity. It is important for this stage of the evolution to be investigated with numerical simulations that can resolve the helicity.

If large-scale magnetic fields can be amplified to their saturation strength, then their main effect is to drive a collimated wind. This reduces the star formation efficiency by diverting material from the accretion disk and by sweeping up ambient gas from the polar regions, which otherwise would have collapsed. The star formation efficiency is significantly reduced once the protostar reaches about 100 \( \text{M}_\odot \). The outflows are probably strong enough to ejection matter from the dark matter minihalo and to start magnetizing the intergalactic medium. The presence of outflows also increases the density distribution of gas near the star in the region above the accretion disk. The full effects of this have not yet been worked out, but it appears likely that the propagation of ionizing photons is inhibited, at least while the protostar is in the earlier stages of contraction toward the main sequence. These results will be applied to a more detailed study of protostellar feedback in a forthcoming paper.

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