Expressing the three-particle finite-volume spectrum in terms of the three-to-three scattering amplitude

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In this article we complete our formalism relating the finite-volume energy spectrum of a scalar quantum field theory to the three-to-three scattering amplitude, $M_3$. In previous work (Ref. [1]) we found a quantization condition relating the spectrum to a non-standard infinite-volume quantity, denoted $K_{df,3}$. Here we present the relation between $K_{df,3}$ and $M_3$. We then discuss briefly how our now completed formalism can be practically implemented to extract $M_3$ from the finite-volume energy spectrum.

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I. INTRODUCTION

This work completes the formalism that was partially developed in Ref. [1]. In that work we determined the finite-volume spectrum of a relativistic scalar quantum field theory by calculating an appropriate finite-volume correlator to all orders in perturbation theory. All contributing Feynman diagrams were decomposed into products of finite- and infinite-volume quantities. Summing these factored expressions gave a result for the correlator in terms of finite-volume kinematic functions and infinite-volume scattering quantities. The poles in the resulting expression determine the energies of the finite-volume states, and identifying their locations gave a relation between the finite-volume spectrum and infinite-volume scattering quantities.

The central drawback of the result of Ref. [1] is that it depends on a nonstandard infinite-volume three-particle quantity, a modified three-particle K-matrix denoted $K_{df,3}$. For our formalism to be useful, it is necessary to relate $K_{df,3}$ to the physical three-particle scattering amplitude $M_3$. This is what we achieve in the present work. This shows that, in a relativistic context, the finite-volume spectrum of three particles is determined by infinite-volume observables (up to corrections falling faster than any power of $1/L$). This result was previously established using nonrelativistic effective field theory [2].

To give a sense of what is involved in relating $K_{df,3}$ to $M_3$, we recall from Ref. [1] the major differences between the two quantities. Both are obtained by summing contributions from diagrams with six external lines. However, divergences that are present in $M_3$ are removed from $K_{df,3}$ (leading to the subscript “df” for “divergence free”). These divergences are due to diagrams containing pairwise scatterings, such as that shown in Fig. 1. They have nothing to do with bound states but are instead a result of on-shell three-particle intermediate states [3–6].

It is not surprising that the finite-volume spectrum is related to a modified quantity in which these divergences are removed. We stress that the terms removed depend only on the on-shell two-to-two scattering amplitude, $M_2$. These can thus be separately computed and added to the divergence-free quantity to recover $M_3$.

A second and more important difference between $M_3$ and $K_{df,3}$ concerns the pole prescription used to define momentum integrals over products of propagators. In $M_3$ the standard $i\epsilon$ prescription is used, while $K_{df,3}$ uses a modified principal value prescription (denoted PV). The use of a nonstandard pole prescription is required in order to remove the unitary threshold cusp in the two-particle scattering amplitude, as was pointed out in Ref. [2].

As described in detail in Ref. [1] and sketched in Fig. 2, such cusps, if not removed, generate important finite-volume effects when two-to-two scattering is considered as a subprocess of three-to-three scattering. Our prescription avoids such cusps, but at the cost of introducing a nonstandard infinite-volume quantity.

A third difference between $M_3$ and $K_{df,3}$ is that the latter is defined using an ultraviolet cut-off (the function $H(\vec{k})$ defined in Eqs. (A8)–(A10) of the appendix) while $M_3$, being a physical quantity, is independent of the cut-off function.

The final difference is that $K_{df,3}$ involves contributions in addition to the standard Feynman diagrams, which we denote “decorations”. These make the definition of $K_{df,3}$ very complicated, as explained in Ref. [1].

In this work, we relate these two quantities using an indirect approach. By extending the methods of Ref. [1], we obtain a relation between $M_{3L}$, which is a finite-volume version of $M_3$, and $K_{df,3}$, Eq. (68) below. The desired relation between $M_3$ and $K_{df,3}$ is then reached by taking the infinite-volume limit. This approach avoids the need to directly reference the very complicated definition of $K_{df,3}$. As a side benefit, we obtain some intuition about the properties of $K_{df,3}$ itself.

The remainder of this article is organized as follows. In the following section, we recall the results of Ref. [1] that are needed here. In Secs. [II] and [IV] we derive the relationship between $M_{3L}$ and $K_{df,3}$. The former section includes only two-particle Bethe-Salpeter kernels, while the latter adds in three-particle kernels. In Sec. [V] we take an appropriate infinite-volume limit of $M_{3L}$ and obtain the desired relation between $M_3$ and $K_{df,3}$. We then show, in Sec. [VI] how to invert this relationship so that $K_{df,3}$ can be obtained from $M_3$. Section [VII] shows how the general relation between these quantities simplifies in two approximations studied in Ref. [1]. We conclude in Sec. [VIII].
an appendix which collects the definitions of key quantities from Ref. [1].

II. FINITE-VOLUME CORRELATOR FROM PREVIOUS WORK

In this section we summarize the relevant results from Ref. [1], and rewrite them in a form useful for our subsequent analysis. We also introduce the finite-volume three-to-three scattering amplitude $M_{3,L}$, the quantity that plays a central role in our analysis.

We begin by reviewing the set-up for the calculation presented in Ref. [1]. We work with a quantum field theory containing a real scalar, $\phi$, having physical mass $m$. The theory is assumed to have a $\mathbb{Z}_2$ symmetry so that only even powers of $\phi$ appear in the Lagrangian and thus even- and odd-particle states have zero overlap. The derivation of Ref. [1] also requires that the total center-of-mass (CM) energy is such that only three-particle states can go on-shell, and also such that there are no resonances in the two particle subchannels of the three-particle states. The theory is otherwise assumed to be completely general. In particular, it need not be renormalizable and can contain all possible even-legged vertices with no assumptions about relative coupling strengths.

This theory is then considered in a finite, cubic spatial volume of extent $L$ with periodic boundary conditions. The time extent is taken infinite. In this geometry, only spatial momenta whose components are integer multiples of $2\pi/L$ can propagate. The volume extent $L$ is also assumed to be large enough that exponentially suppressed corrections of the form $e^{-mL}$ can be neglected. Such terms are dropped throughout the derivation. Power-law corrections proportional to powers of $1/(mL)$ are kept to all orders.

The analysis of Ref. [1] considers a finite-volume correlator defined by

$$C_L(E, \vec{P}) = \int_L d^4 x \ e^{i(E x^0 - \vec{P} \cdot \vec{x})} \langle 0 | T \sigma(x) \sigma^\dagger(0) | 0 \rangle \ .$$  

(1)

Here $T$ indicates time-ordering while $\sigma(x)$ and $\sigma^\dagger(x)$ are interpolating fields coupling to states with an odd number of particles. The Fourier transform restricts the intermediate states contributing to the correlator to have total energy $E$ and momentum $\vec{P} \in (2\pi/L)\mathbb{Z}^3$. Thus the energy in the center of mass (CM) frame is $E^* = \sqrt{E^2 - \vec{P}^2}$. Our analysis concerns the region $m < E^* < 5m$, where only three-particle states contribute. Note that, although we work in Minkowski space, the finite-volume spectrum is not affected by this choice. Our result is applicable even if the energies are determined in some other way, for example by using a Euclidean correlator as in a lattice QCD calculation.

The finite-volume correlator, $C_L$, has the skeleton expansion shown in Fig. 3. This is explained in Ref. [1] (where precise definitions of the kernels $K_2$ and $B_3$ can also be found). Here we only note the essential features. Note first that $C_L$ differs from its infinite-volume counterpart, $C_{\infty}$, only in that spatial loop momenta are summed rather than integrated. The key observation is then that replacing sums with integrals leads to power-law finite-volume corrections only when all particles in a cut can go on shell. Since we have chosen $m < E^* < 5m$, this can occur only for three-particle cuts. For loops with cuts involving five or more particles one makes only exponentially suppressed errors when replacing sums with integrals. As we neglect such corrections throughout, the Bethe-Salpeter kernels (for which cuts contain either one or else five or more particles) can be replaced by their infinite-volume counterparts.
The same holds true for the dressing functions of the propagators. Thus the only impact of working in finite volume is that the propagators contained within the dashed rectangles in the figure have spatial momenta that are summed.

The task accomplished in Ref. [1] is to factorize the power-law finite-volume dependence contained in $C_L$ from quantities defined in infinite volume. The end result is

$$C_L(E, \vec{P}) = C_\infty(E, \vec{P}) + i A' \frac{1}{1 + F_3 K_{df,3}} F_3 A . \tag{2}$$

Here $A'$, $A$, and $K_{df,3}$ (as well as $C_\infty$) are infinite-volume quantities, while $F_3$ depends on $L$ [as well as on $E$, $\vec{P}$ and the two-particle scattering amplitude—see below]. The result (2) is a matrix equation, in which $A'$ is a row vector, $K_{df,3}$ and $F_3$ are matrices and $A$ is a column vector. The index space is a direct product of two-particle angular momentum, parametrized by spherical harmonic indices $\ell$ and $m$, together with a discrete finite-volume momentum, $\vec{k} \in (2 \pi/L) \mathbb{Z}^3$. So, for example, $K_{df,3} = K_{df,3; k' \ell' m'; k \ell m}$ where $k'$ and $k$ are shorthand for discretized three-vectors.

As we will see below, $C_\infty$, $A$ and $A'$ do not appear in the main results of this paper and so we do not recapitulate their definitions from Ref. [1]. As for $K_{df,3}$, the main task of this paper, as noted in the introduction, is to come up with an alternative to the very complicated and implicit definition given in Ref. [1]. Thus at this stage we only present the definition of $F_3$, which is

$$i F_3 \equiv \frac{i F}{2 \omega L^3} \left[ \frac{1}{3} + \frac{1}{1 - i M_{2,L} i G} i M_{2,L} i F \right] . \tag{3}$$

Like $F_3$, the quantities $1/(2 \omega L^3)$, $F$, $G$, $M_{2,L}$ are all matrices with indices $k' \ell' m'; k \ell m$. The first three of these quantities are known kinematic functions that depend on $L$ (as well as $E$, $\vec{P}$, and $m$). They are defined in the appendix. The final quantity is the finite-volume, two-to-two scattering amplitude, $M_{2,L}$. This in turn can be expressed (up to exponentially suppressed corrections) as

$$i M_{2,L} \equiv \frac{1}{1 - i K_2 i F} i K_2 . \tag{4}$$

where $K_2$ is a modified two-particle infinite-volume K-matrix introduced in Ref. [1]. The relation (4) is needed to show the equivalence of the result (3) to the expressions for $F_3$ given in Ref. [1].

Since $M_{2,L}$ was barely used in Ref. [1], but plays an important role here, we discuss its properties in some detail. A useful, although imprecise, way of thinking about $M_{2,L}$ is as the two-particle scattering amplitude in finite volume.
Recall that $\mathcal{M}_{2,L}$ has indices $k\ell m'; k\ell m$, with $k$ and $k'$ short for $\vec{k}$ and $\vec{k}'$, respectively. For a two-particle quantity such as $\mathcal{M}_{2,L}$, the momenta $\vec{k}$ and $\vec{k}'$ are those of the third, spectator particle, which is unscattered. Thus $\vec{k} = \vec{k}'$, or, in matrix notation, $\mathcal{M}_{2,L; k\ell m'; k\ell m} \propto \delta_{k'k}$. The same holds for $K_2$ and $F$. Thus the spectator momentum serves only to determine the energy-momentum flowing through the scattered pair, which is

$$P_2 = (E - \omega_k, \vec{P} - \vec{k}), \text{ with } \omega_k = \sqrt{\vec{k}^2 + m^2}. \quad (5)$$

The energy of the two scattered particles in their CM frame is therefore

$$E_{2,k}^* \equiv [P_2^2]^{1/2} = [(E - \omega_k)^2 - (\vec{P} - \vec{k})^2]^{1/2}, \quad (6)$$

while the magnitude of their momenta in this frame is

$$q_k^* = [E_{2,k}^*/4 - m^2]^{1/2}. \quad (7)$$

The only unconstrained degrees of freedom are the incoming and outgoing directions of one of the particles in their CM frame, which we denote $\hat{a}^*$ and $\hat{a}'^*$, respectively.

We can now make precise the requirement mentioned above, namely that the theory should not have any two-particle resonances. The condition is that $K_2$ should not have poles in the range of allowed two particle energies. This requirement is most stringent for $\vec{k} = 0$, since this maximizes the energy in the two particle subsystem. Thus $K_2$ should have no poles in the range of two particle CM energies $0 \leq E_{2,0}^* \leq [(E - m)^2 - \vec{P}^2]^{1/2}$. Such poles would lead to power law finite-volume effects when converting sums to integrals in diagrams like that shown in Fig. 2(b), and such effects are not accounted for in the derivation of Ref. [1].

Returning to $\mathcal{M}_{2,L}$, it is useful to have a diagrammatic definition in addition to the expression in terms of $K_2$ and $F$, Eq. (4). This is given in Fig. 4(a), and defines $\mathcal{M}_{2,L}(E_{2,k}^*, \hat{a}'^*, \hat{a}^*)$. Note that the spectator particle is not shown—it contributes an additional factor of $\delta_{kk'}$. What appears in Fig. 4(a) is the same sum of two-to-two connected Feynman diagrams as occurs in the infinite-volume two-particle scattering amplitude (with external propagators amputated and on shell) except that spatial components of loop momenta are summed rather than integrated. These sums can be replaced by integrals within the Bethe-Salpeter kernels (making only exponentially suppressed corrections), but not within the “boxed” loops.

We now encounter for the first time an issue that will recur repeatedly in the following. This is that the external momenta in quantities such as $\mathcal{M}_{2,L}$ must be allowed to differ from finite-volume momenta (which we refer to as “not being in the finite-volume set”). By contrast, internal momenta are in the finite-volume set. This distinction is already present to some extent in Ref. [1], since when the non-spectator pair are put on shell their directions $\hat{a}^*$ and $\hat{a}'^*$ are maintained, but their magnitudes are changed to $q_k^*$, so that they are no longer finite-volume momenta. Here we extend this by allowing $\hat{a}^*$ and $\hat{a}'^*$ to be arbitrary. This allows us to decompose the angular dependence in spherical harmonics and define the matrix form of $\mathcal{M}_{2,L}$ used in Eq. (3):

$$4\pi Y_{\ell m}^*(\hat{a}'^*) \mathcal{M}_{2,L;k\ell m';k\ell m} Y_{\ell m}(\hat{a}^*) \equiv \delta_{k'k} \mathcal{M}_{2,L}(E_{2,k}^*, \hat{a}'^*, \hat{a}^*). \quad (8)$$

Here and in the following there is an implicit sum over repeated indices. Note that $\mathcal{M}_{2,L}$ is not diagonal in its angular-momentum indices, unlike its infinite-volume counterpart, because rotation symmetry is broken by the restriction of internal momenta to the finite-volume set.

In fact, we will need to consider more general external momenta when we take the infinite-volume limit in Sec. V. This is because we take this limit holding the total momentum $\vec{P}$, as well as the external momenta of individual particles such as $\vec{k}$, fixed. Thus, as $L$ varies, $\vec{P}$ and $\vec{k}$ are not, in general, finite-volume momenta. This in turn implies that the total momentum flowing through the boxed loops in Fig. 4(a), which is $\vec{P} - \vec{k}$, is not, in general, in the finite-volume set. We define the extended $\mathcal{M}_{2,L}$ by keeping the summed momentum in the set, i.e. of the form $2\pi m/L$, where the other loop momentum is not in the set. Since the Bethe-Salpeter kernels are symmetric under particle interchange, the choice of which momentum is summed is irrelevant.

As noted above, the name “finite-volume scattering amplitude” is an imperfect moniker for $\mathcal{M}_{2,L}$. For one thing, there are no in- or out-states in finite volume, and for another, $\mathcal{M}_{2,L}$ is purely real (with no unitary cut). Nevertheless, we persist with the name because, as described in Sec. V, if we take the infinite-volume limit in an appropriate way, $\mathcal{M}_{2,L}$ does go over to the infinite-volume scattering amplitude $\mathcal{M}_2$.

In the following section we derive a result closely related to Eq. (2), in which the left-hand side is replaced with a quantity that we call the finite-volume three-to-three scattering amplitude, and denote $\mathcal{M}_{3,L}$. In direct analogy to $\mathcal{M}_{2,L}$, $\mathcal{M}_{3,L}$ is defined as the sum of all on-shell, amputated six-point diagrams evaluated in finite-volume, as shown
in Fig. 4). As for $M_{2,L}$, the external momenta are not, in general, constrained by the finite volume, while some of the internal momenta are. The details are described in the following section. The quantities on which $M_{3,L}$ depends are simply the degrees of freedom for two copies of three-particle phase space at fixed total energy and momentum, i.e., the dependence is $M_{3,L}(\vec{k}', \hat{a}^{\alpha*}, \vec{k}, \hat{a}^*)$. This is closely related to the dependence of $M_{2,L}(E_{2,L}, \hat{a}^{\alpha*}, \hat{a}^*)$ except that now all three particles are involved in scattering, so the partitioning into “spectators” ($\vec{k}$ and $\vec{k}'$) and “scattering pairs” ($\hat{a}^{\alpha*}$ and $\hat{a}^*$) is purely a choice of kinematic variables. In particular, it is no longer true that $\vec{k}' = \vec{k}$, so that the CM energies and momenta of the scattering pair are different in the initial and final states. Nevertheless, one can separately boost to the scattering-pair CM frames, and define the directions of one of the pair as $\hat{a}^*$ and $\hat{a}^{\alpha*}$ for initial and final states, respectively. This completely fixes the kinematic configuration.

A key observation is that the diagrams contributing to $M_{3,L}$, shown in Fig. 4(b), are closely related to those building up $C_L$, shown in Fig. 3. Indeed, if we first discard the first diagram on the first line and the entire second line of diagrams in the latter figure, and then, for each remaining diagram, remove the $\sigma$ and $\sigma^\dagger$ blobs, amputate and put on shell the six external propagators, we obtain exactly the diagrams for $M_{3,L}$. This observation allows us to make substantial use of the work of Ref. [1].

As with $M_{2,L}$, calling $M_{3,L}$ a scattering amplitude for finite $L$ is somewhat misleading, as it has no direct relation to scattering. However, as we discuss in Sec. IV, $M_{3,L}$ does go over to the infinite-volume scattering amplitude $M_3$ when $L \to \infty$, as long as one takes the limit in the appropriate way. Thus, if we can derive a relation between $M_{3,L}$ and $K_{df,3}$, then taking the $L \to \infty$ limit gives the desired relation between $M_3$ and $K_{df,3}$.

### III. $M_{3,L}$ WITH $B_2$ KERNELS ONLY

In this section and the next we determine the relation between $M_{3,L}$ and $K_{df,3}$. This section includes only the $B_2$ kernels in the skeleton expansions, while the next completes the job by adding $B_3$ kernels. This splitting mirrors the breakup of the derivation given in Ref. [1].

The contributions containing only $B_2$ kernels are those of all but the first and last lines of Fig. 4(b). We find it convenient to work first with an unsymmetrized sum of these diagrams, which we label $\mathcal{M}_{3,L}^{(u)}(\beta, \tilde{\beta}^*; \vec{k}, \hat{a}^*)$. This

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1 For brevity we have chosen the outgoing momenta to be $\vec{p}$ rather than $\vec{k}'$. The definitions of $\hat{a}^{\alpha*}$ and $\hat{a}^*$ are as for $M_{3,L}$ in the previous
quantity is defined by requiring that $\vec{p}$ and $\vec{k}$ are the momenta that are not scattered by the outermost $B_2$ insertions. The superscript “$u$” indicates “unscattered”, and “$(u,u)$” means that this choice of coordinates is made in both initial and final states. This is the same notation as used in Ref. [1]. We decompose this function in harmonics in our standard way

$$M^{(u,u)[B_2]}_{3,L}(\vec{p},\vec{k};\vec{a}^*;\vec{k}) = 4\pi Y_{\ell m}^* (\vec{a}^*) M^{(u,u)[B_2]}_{3,L;\ell;\ell',m} Y_{\ell m}(\vec{a}^*).$$  \hspace{1cm} (9)

Note that $M^{(u,u)[B_2]}_{3,L}$ is defined for any $\vec{p}$ and $\vec{k}$, but in this equation we are restricting these to be finite-volume momenta.

In Ref. [1], three-particle quantities similar to $M^{(u,u)[B_2]}_{3,L}$ are needed only when $\vec{p}$, $\vec{p}$ and $\vec{k}$ are finite-volume momenta. This implies that all three momenta in internal three-particle cuts in Fig. 4(b) can simultaneously be in the finite-volume set. However, as noted in the previous section, when we take the infinite-volume limit we must consider general values of the external momenta. It is then not possible that all internal momenta are in the finite-volume set, and we must generalize the definition of $M^{(u,u)[B_2]}_{3,L}$. This is straightforward for the diagrams in the top line of Fig. 4(b): we simply take the two momenta that are being summed to be in the finite-volume set, implying that the third is not. Since $B_3$ is symmetric, it does not matter which two momenta are chosen. In diagrams involving a boxed two-particle loop, we proceed as for $M_{2,L}$, and choose (arbitrarily) one of the momenta to be in the finite-volume set. For the remaining figures, such as those in the third line of Fig. 4(b), one has a non-trivial choice as to which of the loop momenta to sum. However, in all cases, the derivation of Ref. [1] provides a natural choice. The convention we use to define the extended $M^{(u,u)[B_2]}_{3,L}$ is that the summed momenta always lie in the finite-volume set. We emphasize that the details of this choice are not relevant for our final result, since the distinction completely vanishes in the infinite-volume limit.

To identify the desired expression for $M_{3,L}$ we begin by introducing the relevant building blocks as presented in Ref. [1]. The first of these is  \hspace{1cm} (10)

This quantity is related to $M_{2,L}$, given in Eq. (4), by

$$i M_{2,L} = i K_2 + (2\omega L^3) i K_2 A i K_2.$$  \hspace{1cm} (11)

Thus $A$ contains the volume dependence of $M_{2,L}$, entering through the factors of $F$.

The second building block from Ref. [1] is $K^{(n,u,u)}_{3,L}$, a quantity defined in Fig. 5. This object is built from $n \geq 2$ factors of $K_2$, with adjacent insertions scattering different pairs. It arises from sections of diagrams where $B_2$ kernels change at least once to a different pair of propagators. It contains power-law finite-volume effects, due to the presence of sums over the spatial momenta in loops. Summing over all possible numbers of $K_2$ factors leads to the quantity

$$K^{(u,u)}_{3,L} \equiv \sum_{n=2}^{\infty} K^{(n,u,u)}_{3,L}.$$  \hspace{1cm} (12)

Both $K^{(n,u,u)}_{3,L}$ and $K^{(u,u)}_{3,L}$ can be expressed as matrices in the same fashion as $M^{(u,u)[B_2]}_{3,L}$.

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*Footnote:* In Ref. [1] we denoted this quantity $[A]$, whereas here we drop the brackets. Note that $1/(2\omega L^3)$ commutes with $K_2$ and $F$, while $K_2$ and $F$ do not commute.
We can now state our result for the partial decomposition of $\mathcal{M}^{(u,u)[B_2]}_{3,L}$:

$$i\mathcal{M}^{(u,u)[B_2]}_{3,L} = \frac{1}{1 - iK_{21}F} \sum_{n=0}^{\infty} \left( iK_{3,3}^{(u,u)}\mathbf{A} \right)^n \frac{1}{1 - iF\mathbf{K}_2}.$$

(13)

This decomposition makes explicit all finite-volume dependence arising from sum-integral differences (i.e. factors of $F$) on chains in which scattering occurs on the same pair of propagators. It is a partial decomposition, however, because $k_{3,3}^{(u,u)}$ still depends on $L$. One can understand the result (13) qualitatively as follows: In order to have a connected scattering diagram, there must be at least one $k_{3,3}^{(u,u)}$ present. This can be “decorated” with chains of two-to-two scattering $K$-matrices and $F$ factors on either the outside or between factors of $k_{3,3}^{(u,u)}$. Summing the geometric series of two-to-two chains and then summing over any number of $k_{3,3}^{(u,u)}$ insertions leads to the result shown.

If the external momenta are in the finite-volume set, then a derivation of Eq. (13) can be given by a straightforward application of the methods of Ref. [1]. We provide this derivation first, and then comment (toward the end of this section) on the generalization to arbitrary external momenta.

The most direct path to a derivation of Eq. (13) is to start from Eq. (193) of Ref. [1], which we reproduce here:

$$C_{L}^{[B_2]} = C_{\infty}^{[B_2]} + \delta C_{\infty}^{[B_2]} + A^{[B_2]} \left[ -\frac{2}{3} iF \frac{2}{\omega L^3} + A \sum_{n=0}^{\infty} \left( iK_{3,3}^{(u,u)} \mathbf{A} \right)^n \right] A^{[B_2]}.$$

(14)

This is an expression for the finite-volume correlator including only $B_2$ kernels. Now, the main difference between $C_L$ and $\mathcal{M}_{3,L}$ is the presence of the “endcaps” $\sigma$ and $\sigma^\dagger$ in the former. When dressed by $B_2$ kernels these give the factors of $A^{[B_2]}$ and $A^{[B_2]}$ in Eq. (14), which are infinite-volume quantities. To obtain $\mathcal{M}_{3,L}$ we can discard these endcap factors by noting that the kinematic factor $F$, which contains the finite-volume dependence arising from a three-particle cut, amputates and puts on shell the adjacent matrices. Thus the factor between the outermost $F$ cuts in $C_L$ is precisely the amputated on-shell $\mathcal{M}_{3,L}$ that we are after, as long as the contribution contains two such cuts. There are no such cuts in the first two terms on the right-hand side of Eq. (14), since these are infinite-volume quantities, and so they do not contribute to $\mathcal{M}_{3,L}$. The third term also does not contribute since it contains only a single $F$ cut. We conclude that we need only keep the final term, i.e.

$$A^{[B_2]} \left[ A \sum_{n=0}^{\infty} \left( iK_{3,3}^{(u,u)} \mathbf{A} \right)^n \right] A^{[B_2]}.$$

(15)

If we drop the external factors of $A^{[B_2]}$ and $A^{[B_2]}$ and then further multiply by an inverse of $iF/(2\omega L^3)$ on each side, we are left with all amputated six-point diagrams. This includes, however, disconnected diagrams (arising from the diagrams on the second line of Fig. [3]). Since these are not contained in the definition of $\mathcal{M}_{3,L}$ they must be discarded.

This is effected by summing from $n = 1$ rather than $n = 0$. In this way, and using the results in Eq. (10) for $A$, we obtain Eq. (13).

In the remainder of this section we follow the method of analysis used in Sec. IVD of Ref. [1], where the result (14) for $C_L^{[B_2]}$ is completely decomposed into finite- and infinite-volume quantities. Here we apply the method to the result (13) for $\mathcal{M}^{(u,u)[B_2]}_{3,L}$. In this case it turns out that we cannot simply borrow results from Ref. [1], but need to introduce two new quantities. Thus we provide a more detailed derivation.

The starting point is to use the result for $k_{3,3}^{(u,u)}$ presented in Eq. (215) of Ref. [1], namely

$$iK_{3,3}^{(u,u)} = iTiG[2\omega L^3]iK_2 + \left( 1 + iTiF \right) \left( iK_{df,3}^{(u,u)} \right) \sum_{j=0}^{\infty} \left( \begin{array}{c} 0 \\ 1 \end{array} \right) \frac{iF}{2\omega L^3} \left( 1 + iTiF \right) \left( iK_{df,3} \right)^j \left( \begin{array}{c} 1 \\ iT2\omega L^3 \end{array} \right),$$

(16)

where [Eqs. (212) and (213) of Ref. [1]]

$$iT = \frac{1}{1 - iK_{21}G} iK_2.$$

(17)

$$\left( iK_{df,3}^{(u,u)} \right) = \left( \begin{array}{c} iK_{df,3}^{(u,u)} \\ iK_{df,3}^{(s,u)} + iK_{df,3}^{(s,u)} \\ iK_{df,3}^{(s,s)} + iK_{df,3}^{(s,s)} + iK_{df,3}^{(s,s)} + iK_{df,3}^{(s,s)} \end{array} \right),$$

(18)
The result (16) separates finite-volume dependence—contained in $F$ and $G$—from the infinite-volume quantities $K_2$ and $K_{df,3}$. All these quantities are matrices with our usual $k\ell m$ indices. In Eq. (18), $K_{df,3}$ appears in various forms, with different superscripts, and it is convenient to collect these into a second level of matrices as shown. The differences between the forms of $K_{df,3}$ are explained thoroughly in Ref. [1], and here we give only an overview.

The simplest quantity to understand is $K_{df,3}^{(u,u)}$. This is given by $K_{3,L}^{(u,u)}$ except for two changes: sums are replaced by integrals, and singular terms are subtracted (along the lines discussed in the introduction) so that it is divergence-free. The integrals use our non-standard pole prescription, and, in the case of multiple loops, must be ordered in the manner described in Ref. [1]. Since loop momenta are integrated, there are no subtleties defining $K_{df,3}$ by integrals, and singular terms are subtracted (along the lines discussed in the introduction) so that it is divergence-free. 

Between the forms of $K_{df,3}$ with different superscripts, and it is convenient to collect these into a second level of matrices as shown. The differences $K_{df,3}$ must symmetrize over the initial and final assignments of momenta. In our matrix notation, this is achieved by rewriting $C_L^{(B_2)}$ in terms of the symmetric quantity, and the same is true in the following.

To proceed, we substitute Eq. (16) into Eq. (13) and organize the result in powers of $K_{df,3}$. For example, the contribution which is independent of $K_{df,3}$ is given by substituting

$$iK_{3,L} = iT G[2\omega L^3]iK_2 + O(K_{df,3}),$$

[i.e. the first term in Eq. (19)] to find

$$iM_{3,L}^{(u,u)} = iD_L^{(u,u)} + O(K_{df,3}),$$

where $\hat{p}$ is the momentum of the particle chosen as spectator (so that the first two-particle kernel $B_2$ scatters the other two particles) while $\hat{a}^*$ is the direction of one of the other two particles in their CM frame. In the original frame the momentum of this second particle is called $\vec{a}$—a momentum that is fully determined given $\vec{k}$ and $\vec{a}^*$ (along with $E$ and $\vec{P}$). The third particle thus has momentum $\vec{P} - \vec{k} - \vec{a}$ in the original frame. A similar notation with $\vec{k} \rightarrow \vec{p}$ and $\vec{a} \rightarrow \vec{a}'$ is used for the final state. As noted above, the first superscript of $K_{df,3}$ is related to the choice of momentum variables for the final state, and the second to the choice for the initial state. Focusing on the initial state, quantities with superscripts “$s$” and “$\tilde{s}$” are obtained by choosing the spectator momentum to be $\vec{a}$ and $\vec{P} - \vec{k} - \vec{a}$, respectively. For example,

$$K_{df,3}^{(u,s)}(\vec{p},\vec{a}^*;\vec{k},\vec{a}^*) = 4\pi Y_{\ell \nu}(\hat{a}^*)K_{df,3}^{(u,u)}(\vec{p},\vec{a}^*;\vec{a},\vec{k}^*),$$

where $\vec{k}^*$ is the direction of the particle with momentum $\vec{k}$ after it is boosted to the CM frame containing it and the particle with momentum $\vec{P} - \vec{k} - \vec{a}$. Note that we could equally well have used the direction of the particle with momentum $\vec{P} - \vec{k} - \vec{a}$ after boosting in place of $\vec{k}^*$ as the final argument on the right-hand side of Eq. (20), since $K_{df,3}^{(u,u)}$ is symmetric under this interchange. Independently making analogous changes of variables in the final state we obtain all the versions of $K_{df,3}$. We stress that this argument relies on $K_{df,3}^{(u,u)}$ being well defined for external momenta which are not in the infinite-volume set, since, even if $\vec{k}$ and $\vec{P}$ are in this set, $\vec{a}$ is not.

The final step to obtain the matrix forms of $K_{df,3}$ appearing in Eq. (18) is to decompose the angular dependence in spherical harmonics. For example, the matrix form of $K_{df,3}^{(u,u)}$ is obtained from the left-hand side of Eq. (20) in exactly the same way as for $K_{df,3}^{(u,u)}$ [see Eq. (19)].

As is the case for $K_{df,3}^{(u,u)}$, all the other forms of $K_{df,3}$ are separately unphysical. To obtain a physical quantity we must symmetrize over the initial and final assignments of momenta. In our matrix notation, this is achieved by

$$\begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} \left( iK_{df,3} \right) \begin{pmatrix} 1 \\ 1 \end{pmatrix}.$$
where

\[ iD_L^{(u,u)} = \frac{1}{1 - i\mathbf{k}_2 iF} \sum_{n=0}^{\infty} (iT_i G[2\omega L^3] i\mathbf{k}_2 A)^n iT_i G[2\omega L^3] i\mathbf{k}_2 \frac{1}{1 - iF i\mathbf{k}_2}. \] (24)

After some algebra using the definitions of \( A \) and \( T \) this simplifies to

\[ iD_L^{(u,u)} = \frac{1}{1 - iM_{2,2} iG} iM_{2,2} iG iM_{2,2} [2\omega L^3]. \] (25)

The superscript on \( D_L^{(u,u)} \) is a reminder that the external momentum indices are those of the particles not affected by the outermost factors of \( M_{2,2} \).

Next we consider the term linear in \( K_{df,3} \). To identify this it is necessary to substitute the \( K_{df,3} \)-independent and \( \mathcal{O}(K_{df,3}) \) terms from \( i\rho_{3,1}^{(u,u)} \). Summing all contributions to the left and right of the single \( K_{df,3} \) insertion then gives [see also Eq. (224) of Ref. \[1\]]

\[ iM_{3,3}^{(u,u)[B_2]} \supset \left( L_L^{(u)} \right) \left( \mathcal{K}_{df,3} \right) \left( R_L^{(u)} \right), \] (26)

where

\[ \left( L_L^{(u)} \right) = \begin{pmatrix} 1 & 0 \\ 1 \\ 0 \end{pmatrix} + \frac{1}{1 - iM_{2,2} iG} iM_{2,2} iG \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}, \] (27)

\[ \left( R_L^{(u)} \right) = \begin{pmatrix} 1 & 0 \\ 1 \\ 0 \end{pmatrix} + \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} \frac{iF}{2\omega L^3} \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} iM_{2,2} iG iM_{2,2} [2\omega L^3]. \] (28)

These are the two new quantities that do not appear in Ref. \[1\]. The superscripts again indicate a particular choice of spectator momentum.

To see the all orders pattern, it is sufficient to work out the \( \mathcal{O}(K_{df,3}^2) \) term. We find this to be

\[ iM_{3,3}^{(u,u)[B_2]} \supset \left( L_L^{(u)} \right) \left( \mathcal{K}_{df,3} \right) \left[ \left( iF_3 \right) + \begin{pmatrix} i\rho \\ i\omega \end{pmatrix} \right] \left( \mathcal{K}_{df,3} \right) \left( R_L^{(u)} \right), \] (29)

where we have introduced two new “second-level” matrices,

\[ \left( iF_3 \right) \equiv \begin{pmatrix} 1 \\ 1 \end{pmatrix} iF_3 \begin{pmatrix} 1 & 1 \end{pmatrix}, \] (30)

\[ \left( i\rho \right) \equiv \begin{pmatrix} 1 \\ 1 \end{pmatrix} \frac{i\rho}{2\omega} \begin{pmatrix} 1 & 1 \end{pmatrix}. \] (31)

The factor between the \( \mathcal{K}_{df,3} \) in Eq. (29) is exactly the same as that in the corresponding analysis in Ref. \[1\] [see Eq. (230) of that work]. As in Ref. \[1\], the term containing \( \rho \) is integrated, rather than summed, over spectator momentum (with sums over angular momentum indices remaining). More precisely, our notation means

\[ \mathbf{\left( \mathcal{K}_{df,3} \mathcal{K}_{df,3} \mathbf{\right)(\mathbf{k}_{df,3},\mathbf{k}_{df,3})} \equiv \int \frac{d^3 s}{(2\pi)^3} \mathbf{\left( \mathcal{K}_{df,3}(\mathbf{p},\mathbf{s}) \mathcal{K}_{df,3}(\mathbf{p},\mathbf{s}) \mathcal{K}_{df,3}(\mathbf{k}_{df,3},\mathbf{k}_{df,3}) \right),} \] (32)

where \( \rho(\mathbf{k}) \) is the phase-space factor defined in Eq. (A6), and \( \mathbf{p} \) and \( \mathbf{k} \) on the right-hand side are finite-volume momenta which match the “outside” indices on the left hand side. The second level matrices involving \( \mathcal{K}_{df,3} \) on the right hand side are the same as those defined in Eq. (15), except here we replace the spectator momentum indices with continuous momenta. We comment that the asymmetric form in which \( \rho(\mathbf{k}) \) appears here arises from our convention for ordering the PV integrals, as is described in detail in Ref. \[1\].

Extending to all orders in \( \mathcal{K}_{df,3} \), and rearranging the sum, we deduce

\[ iM_{3,3}^{(u,u)[B_2]} = iD_L^{(u,u)} + \left( L_L^{(u)} \right) \left( \mathcal{K}_{df,3}^{[B_2,u]} \right) \sum_{n=0}^{\infty} \left[ \left( iF_3 \right) \left( i\mathbf{k}_{df,3}^{[B_2,u]} \right) \right]^n \left( R_L^{(u)} \right), \] (33)
The second line defines the action of the symmetrization operator $S$ discussed for $u$. Note that, as discussed above at length, we can treat all the external momenta as continuous variables, not constrained by $\rho$ which is the analog of Eq. (234) of Ref. [1]. Here the $\rho$-dependent terms are summed into the new infinite-volume quantity

$$\left( iK^{{[B_2,\rho]}}_{d \ell,3} \right) \equiv \sum_{n=0}^{\infty} \left( iK_{d \ell,3} \right) \left[ \left( \frac{i\rho}{2\omega} \right) \left( iK_{d \ell,3} \right) \right]^n.$$  \hspace{1cm} (34)

We refer to these $\rho$-dependent terms as “decorations”.

The result \([33]\) has been derived assuming that the external spectator momenta and the total momentum take finite-volume values \([3]\). We now argue that it holds for arbitrary choices of these momenta, as long as the finite-volume quantities $F$ and $G$ contained in $F_3$ and $M_{2,L}$ are extended to arbitrary external momenta in the very straightforward manner described in the appendix. The derivation of Eq. (33) relies on repeated replacements of momentum sums over three particle cuts with momentum integrals plus the difference, $F$ \([4]\). One must ensure that replacements are done in an appropriate order (and that integrals are defined with the PV prescription), as discussed in detail in Ref. [1]. But what matters here are the following observations. First, the determination of which summands lead to a non-trivial difference function $F$ maintains its form (given in the appendix) for arbitrary external momenta. Third, the sums over spectator momentum indices, implicitly contained in the multiplication of matrices in Eq. (33) (and which are, by definition, over finite-volume momenta) correspond precisely to those loop momenta which should be summed over finite-volume momenta, according to the diagrammatic definition of $M_{3,L}^{(u,u)[B_2]}$ given at the beginning of this section. In other words, the correct choice of which internal momenta to keep in the finite-volume set is being made. And, finally, the kinematic factor $G$ (which contains no momentum sums) extends to non-finite-volume momenta in a very straightforward way, as described in the appendix. Combining these observations, it is straightforward to see that the expression for $M_{3,L}^{(u,u)[B_2]}$ given above remains valid for arbitrary external momenta, with one proviso. The proviso is that the external momenta, which propagate into the expression until there is a factor of $G$ (either in $D^{(u,u)}_L$, $F^{(u)}_L$ or $R^{(u)}_L$) or a factor of $K^{[B_2,\rho]}_{d \ell,3}$, are not in the finite-volume set. Thus the first matrix that appears on either end of the expression has different indices from matrices in the middle of the expression. In particular, the matrices on the end have one index which is an external momentum while the other is an (internal) finite-volume momentum. Fortunately, these subtleties become irrelevant when one takes the infinite-volume limit and sums become integrals.

The final step in the construction of the contribution of $M_{3,L}$ from $B_2$ kernels is to symmetrize over initial and final momentum assignments. However, a complication arises because $D^{(u,u)}_L$, $F^{(u)}_L$ and $R^{(u)}_L$ contain poles. When one changes the assignment of momentum labels, the angular dependence now sweeps over the poles. Since this implies that the functions are not square integrable, one cannot decompose into spherical harmonics. To avoid this technical problem one must first change from spherical harmonic indices to an explicit dependence on angular variables, and only then symmetrize. For almost all choices of external momenta, one then avoids the singularity.

To make the symmetrization operator explicit, we first convert to angular variables for $M_{3,L}^{(u,u)[B_2]}$ in the standard way:

$$M_{3,L}^{(u,u)[B_2]}(\vec{p}, \hat{a}^*; \vec{k}, \hat{a}^*) = 4\pi Y_{m_1}^* (\hat{a}^*) M_{3,L;\ell',m';k,\ell,m} Y_{m_2} (\hat{a}^*).$$  \hspace{1cm} (35)

Note that, as discussed above at length, we can treat all the external momenta as continuous variables, not constrained to lie in the finite-volume set. We now define the quantities with $u$ replaced by $s$ and $\tilde{s}$ in exactly the same way as discussed for $K_{d \ell,3}$ above—see Eq. [20] and surrounding text. We stress that this is simply implementing the interchange of the choice of spectator particle. Then we have

$$M_{3,L}^{[B_2]}(\vec{p}, \hat{a}^*; \vec{k}, \hat{a}^*) = \sum_{x=u,s,\tilde{s}} \sum_{y=u,s,\tilde{s}} M_{3,L}^{(x,y)[B_2]}(\vec{p}, \hat{a}^*; \vec{k}, \hat{a}^*)$$

$$= S \left\{ M_{3,L;\ell',m';k,\ell,m}^{(u,u)[B_2]} \right\}.$$  \hspace{1cm} (36)

The second line defines the action of the symmetrization operator $S$, and applies to any “$(u,u)$” quantity that can be defined for general external momenta.

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3 The momenta of the scattered pair in the initial and final states are not in the finite-volume set, due to the on-shell condition, as discussed around Eq. [8]. The direction vectors for these momenta, $\hat{a}^*$ and $\hat{a}''$, can be chosen arbitrarily.

4 To see this most clearly, one should expand out the geometric series contained in $F_3$, $M_{2,L}$ and $D^{(u,u)}_L$, in which case $M_{3,L}^{(u,u)[B_2]}$ is a sum of terms each of which consists of products of either $F$ or $G$ alternating with factors of $K_2$ and $K^{[B_2,\rho]}_{d \ell,3}$. 
Finally, on the right-hand end there is always a segment connecting the rightmost type of segment was analyzed in Ref. [1], while the other two are new to this work. The first connects the final state fields to the leftmost kernel, and appears on the left-hand end of all diagrams considered in this section. The second type lies between two $B_3$ kernels, and can appear any number of times (including zero) in the middle of the diagram. Finally, on the right-hand end there is always a segment connecting the rightmost $B_3$ to the initial state. The second ("middle") type of segment was analyzed in Ref. [1], while the other two are new to this work.

Applying $S$ to both sides of Eq. (33) we find, after some algebra, the final result of this section,

$$i \mathcal{M}^{[B_2]}_{3,L}(\vec{p}, \vec{a}^*; \vec{k}, \vec{a}^*) = i \mathcal{D}_{L}(\vec{p}, \vec{a}^*; \vec{k}, \vec{a}^*) + S \left\{ \frac{1}{3} \left[ 1 + \frac{1}{1 - i \mathcal{M}_{2,L} i \mathcal{G}} \right] i \mathcal{K}^{[B_2,\rho]}_{df,3} \right\} \left[ \frac{1}{1 - i F_3 i \mathcal{K}^{[B_2,\rho]}_{df,3}} \right] \left[ \frac{1}{1 - \frac{1}{2 \omega L^3} i \mathcal{M}_{2,L} i \mathcal{G} i \mathcal{M}_{2,L}(2 \omega L^3)} \right].$$

(38)

Here $\mathcal{D}_{L}$ is the symmetrized form of $\mathcal{D}^{(u,u)}_{L}$,

$$\mathcal{D}_{L}(\vec{p}, \vec{a}^*; \vec{k}, \vec{a}^*) = S \left\{ \mathcal{D}^{(u,u)}_{L} \right\},$$

(39)

and

$$i \mathcal{K}^{[B_2,\rho]}_{df,3} \equiv \left( \begin{array}{cc} 1 & 1 \\ 1 & 1 \end{array} \right) \left( i \mathcal{K}^{[B_2,\rho]}_{df,3} \right) \left( \begin{array}{c} 1 \\ 1 \end{array} \right).$$

(40)

equals the quantity of the same name appearing in Ref. [1].

Several comments are in order about the derivation of Eq. (38). When symmetrizing over the row vector $\mathcal{L}^{(u)}_L$, defined in Eq. (27), the row vector $(1,0)$ is now converted into $(1,1)$ as long as we include a factor of $1/3$. The row vector $(1,1)$ can now be factored out and applied to the right. A similar discussion holds for $\mathcal{R}^{(u)}_L$, with the symmetric column vector $(1,1)$ factoring out at its left-hand end. Together with the fact that the matrix form of $F_3$, Eq. (30), contains symmetric column and row vectors, this implies that all entries of the matrix $\left( i \mathcal{K}^{[B_2,\rho]}_{df,3} \right)$ in Eq. (33) are now sandwiched between symmetric vectors. This is why the symmetric quantity $\mathcal{K}_{df,3}^{[B_2,\rho]}$ of Eq. (40) appears in our final result. One is then left with a geometric series of powers of $F_3 \mathcal{K}_{df,3}^{[B_2,\rho]}$ which sums to the form shown in Eq. (38).

We stress that $\mathcal{K}_{df,3}^{[B_2,\rho]}$, while symmetric under external particle exchange, violates this symmetry internally. This is because of the above-mentioned decorations involving the matrix $\rho$, which contains the asymmetric row vector $(2/3, -1/3)$. Furthermore, our PV pole prescription breaks particle interchange symmetry. These facts make $\mathcal{K}_{df,3}^{[B_2,\rho]}$ a difficult quantity to interpret.

It is of course crucial that Eq. (38) contains the same $\mathcal{K}_{df,3}^{[B_2,\rho]}$ as appears in the analogous expression for $\mathcal{C}^{(B_2)}_L$ given in Eq. (234) of Ref. [1]. We will see that this continues to hold when $B_3$ kernels are included. This means that the same quantity $\mathcal{K}_{df,3}$ that appears in the quantization condition will appear in the relation to $\mathcal{M}_3$.

**IV. $M_{3,L}$ WITH $B_2$ AND $B_3$ KERNELS**

In this section we complete the decomposition of $\mathcal{M}_{3,L}$ by including all remaining diagrams, i.e. those with at least one $B_3$ kernel. This set is illustrated by the first and last lines of Fig. 4(b). Although the final result is straightforward, with the form of Eq. (38) being preserved aside from a new definition of $\mathcal{K}_{df,3}$, the derivation of this result is quite involved. While we are able to partly reuse results from Ref. [1], significant additional work is required. As in the previous section, we derive the result first with finite-volume external spectator and total momenta, and then note that the result maintains its form if these momenta are allowed to be general.

$B_3$ kernels are symmetric functions of incoming and outgoing momenta that are smooth in the energy range of interest. They naturally divide diagrams contributing to $\mathcal{M}_{3,L}$ into segments within which finite-volume dependence can arise. These segments can be treated separately, and are of three types. The first connects the final state fields to the leftmost $B_3$ kernel, and appears on the left-hand end of all diagrams considered in this section. The second type lies between two $B_3$ kernels, and can appear any number of times (including zero) in the middle of the diagram. Finally, on the right-hand end there is always a segment connecting the rightmost $B_3$ to the initial state. The second ("middle") type of segment was analyzed in Ref. [1], while the other two are new to this work.

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5 Recall that our second-level matrix notation combines superscripts $s$ and $\tilde{s}$ into the lower entry; see, e.g., Eq. (18).
We first recall the expression for a middle segment. To understand this we need the final result for the finite-volume correlator including only $B_2$ kernels, $C_L^{[B_2]}$. This is given by Eq. (239) of [1]:

$$C_L^{[B_2]} = C_{\infty}^{[B_2,\rho]} + A^{[B_2,\rho]} Z A^{[B_2,\rho]},$$

with

$$Z = \frac{1}{1 - i K_{df,3}^{[B_2,\rho]} i F_3}.$$

This is obtained by performing manipulations analogous to those of the previous section on the starting form, Eq. (41). $C_{\infty}^{[B_2,\rho]}$ is the infinite-volume version of $C_L$ with only $B_2$ kernels included, using the PV prescription, and including decorations due to $\rho$. It is defined in Sec. IVD of Ref. [1]. The second term in (41) contains the finite-volume dependence, which is collected into $Z$. All infinite-volume contributions between the $\sigma$ at the left and the first finite-volume cut $F$ are contained in $A^{[B_2,\rho]}$, while $A^{[B_2,\rho]}$ contains such contributions between the rightmost $F$ and the $\sigma^\dagger$. Following Ref. [1], we define “decoration operators” $D_C$, $D_A$, and $D_A$ such that [Eq. (241) of [1]]

$$C_{\infty}^{[B_2,\rho]} = \sigma D_C^{[B_2,\rho]} \sigma^\dagger,$$

$$A^{[B_2,\rho]} = \sigma D_A^{[B_2,\rho]},$$

$$A^{[B_2,\rho]} = D_A^{[B_2,\rho]} \sigma^\dagger.$$

These are infinite-volume integral operators. The point of these definitions is that the decoration operators do not depend on the choice of functions at the ends. In $C_L^{[B_2]}$ these are $\sigma$ and $\sigma^\dagger$, but if both are replaced by $B_3$ then one obtains a middle segment of $M_{3,L}$. Thus the latter can be written

$$\ldots i B_3 M^{[B_2,\rho]} i B_3 \ldots,$$

where $M^{[B_2,\rho]} = D_C^{[B_2,\rho]} + D_A^{[B_2,\rho]} Z D_A^{[B_2,\rho]},$

which is Eq. (243) of [1].

We now turn to the end segments. We call the integral operator appearing in the left-hand segment $L^{(u)[B_2,\rho]}$, and the corresponding operator for the right-hand segment $R^{(u)[B_2,\rho]}$. Using this notation, the contribution to $M_{3,L}^{(u,u)}$ containing one and two $B_3$s is

$$i M_{3,L}^{(u,u)} \supset L^{(u)[B_2,\rho]} i B_3 R^{(u)[B_2,\rho]} + L^{(u)[B_2,\rho]} i B_3 M^{[B_2,\rho]} i B_3 R^{(u)[B_2,\rho]}.$$

No $(u,u)$ superscripts are necessary for the middle segment due to the symmetry of $B_3$.

The result for $R^{(u)[B_2,\rho]}$ can be obtained by reflection from that for $L^{(u)[B_2,\rho]}$, so we focus on the latter. Our starting point is a result that follows from Eq. (174) of [1] by the same argument given above for obtaining Eq. (13) from Eq. (14). We find

$$L^{(u)[B_2,\rho]} \sigma^\dagger = \frac{1}{1 - i K_{24} F} \sum_{n=0}^{\infty} \left( i K_{3,L}^{(u,u)} A \right)^n \sum_{m=0}^{\infty} A_L^{(m,u)} - \frac{2}{3} \sigma^\dagger.$$

Note that we are acting $L^{(u)[B_2,\rho]}$ on $\sigma^\dagger$ rather than $B_3$. This is just a convenience, as it allows us to reuse notation from Ref. [1]. The operator $L^{(u)[B_2,\rho]}$ is the same for either choice. The new quantity $A_L^{(m,u)}$ is defined in Ref. [1], and represents diagrams in which $\sigma^\dagger$ is dressed with $m$ factors of $K_2$, with the scattering pair switching between each factor. All loops except that closest to the $\sigma^\dagger$ involve sums over spatial momenta, and thus contain $L$ dependence. This is illustrated in Fig. 17(a) of [1]. The leading term is $A_L^{(0,u)} = \sigma^\dagger$ (which will ultimately become $B_3$ in our case). The last term on the right-hand side in Eq. (48) is needed since the first term equals $\sigma^\dagger$ at leading order, but we require $\sigma^\dagger/3$ in the unsymmetrized endcap. In the construction of $M_{3,L}^{(u,u)}$ this will correspond to factors of $B_3$ being multiplied by 1/3 whenever they are the outermost insertions. This is the correct definition to recover a factor of $B_3$ without the 1/3 from such diagrams within the symmetrized amplitude. Since $B_3$ is itself symmetric, the effect of symmetrization on such diagrams is multiplication by 3, which cancels the 1/3 included here.

The form (48) is next rewritten using the results in Eqs. (188), (191) and (192) in [1], leading after some algebra to

$$L^{(u)[B_2,\rho]} \sigma^\dagger = \frac{1}{1 - i K_{24} F} \sum_{n=0}^{\infty} \left( i K_{3,L}^{(u,u)} A \right)^n A^{[B_2]} + \frac{1}{3} \sigma^\dagger + A^{(u)[B_2]} - A^{[B_2]}.$$
Here $A^{(u)[B_2]}$ and $A^{[B_2]}$ are infinite-volume quantities involving any number of $K_2$s connected to $\sigma^\dagger$. $A^{[B_2]}$ is the symmetrized version, which has already appeared in Eqs. (14) and (15). Both quantities are defined in Ref. [1]. The result (19) is the analog of Eq. (13) above when there is a $B_3$ on the right-hand end rather than an initial state.

Using the definitions of $A$ and $M^{(u,u)[B_2]}$, Eqs. (10) and (13) respectively, we can rewrite our result for $L^{(u)[B_2;\rho]}$ as

$$L^{(u)[B_2;\rho]}\sigma^\dagger = iM^{(u,u)[B_2]}_{3,L} \frac{iF}{2\omega L^3} A^{[B_2]} + \frac{1}{3} \sigma^\dagger + A^{(u)[B_2]} + \frac{iK_2 iF}{1 - iK_2 iF} A^{[B_2]}.$$  \hfill (50)

This allows us to reuse the work from the previous section, which led to the result (33) for $M^{(u,u)[B_2]}$. Substituting the latter into Eq. (50), we encounter a new combination that can be rewritten as follows

$$\left( R_L^{(u)} \right) \frac{iF}{2\omega L^3} A^{[B_2]} = \left\{ \begin{array}{c} 1 \\ 1 \end{array} \right\} iF_3 + \left( \begin{array}{c} 2/3 \\ -1/3 \end{array} \right) \frac{i\rho}{2\omega} A^{[B_2]}$$  \hfill (51)

$$= \left\{ \begin{array}{c} iF_3 \\ \frac{i\rho}{2\omega} \end{array} \right\}^T \left( A^{[B_2]} \right),$$  \hfill (52)

where

$$\left( \begin{array}{c} i\rho \\ 2\omega \end{array} \right)^T = \left( \begin{array}{c} 2/3 \\ -1/3 \end{array} \right) \frac{i\rho}{2\omega} \left( \begin{array}{cc} 1 & 1 \end{array} \right),$$  \hfill (53)

and

$$\left( A^{[B_2]} \right) = \left( \begin{array}{c} \sigma^\dagger/3 + A^{(u)[B_2]} \\ 2\sigma^\dagger/3 + A^{(s)[B_2]} + A^{(s)[B_2]} \end{array} \right).$$  \hfill (54)

Here we have split up the symmetric quantity $A^{[B_2]}$ into a column matrix, such that

$$A^{[B_2]} = \left( \begin{array}{cc} 1 & 1 \end{array} \right) \left( A^{[B_2]} \right).$$  \hfill (55)

Introducing the definition [equivalent to Eq. (237) of [1]]

$$\left( A^{[B_2;\rho]} \right) = \left( A^{[B_2]} \right) + \left( \frac{i\rho}{2\omega} \right)^T \left( A^{[B_2]} \right),$$  \hfill (56)

we find, after considerable algebra, that we can rewrite (50) as

$$L^{(u)[B_2;\rho]}\sigma^\dagger = \left( L^u_L \right) \sum_{n=0}^\infty \left\{ \left( \frac{i\rho}{2\omega} \right)^T \left( iF_3 \right) \right\}^n \left( A^{[B_2;\rho]} \right).$$  \hfill (57)

Finally, defining asymmetric decoration operators by

$$\left( \begin{array}{c} D_{A}^{(u)[B_2;\rho]} \\ D_{A}^{[B_2;\rho]} - D_{A}^{(u)[B_2;\rho]} \end{array} \right) \sigma^\dagger \equiv \left( A^{[B_2;\rho]} \right),$$  \hfill (58)

we can write a stand-alone expression for the integral operator appearing in the left-hand segment

$$L^{(u)[B_2;\rho]} = \left( L^u_L \right) \sum_{n=0}^\infty \left\{ \left( iK_2^{[B_2;\rho]} \right) \left( iF_3 \right) \right\}^n \left( \frac{D_{A}^{(u)[B_2;\rho]}}{D_{A}^{[B_2;\rho]} - D_{A}^{(u)[B_2;\rho]}} \right).$$  \hfill (59)

\[\footnote{In Ref. [1], $A^{(u)}$ denotes what we refer to here as $A^{(u)[B_2]}$. Note that $A^{(u)[B_2]}$ does not include an isolated factor of $\sigma^\dagger$, i.e. all terms in $A^{(u)[B_2]}$ have at least one insertion of $K_2$. By contrast the symmetrized version, $A^{[B_2]}$ does start with an isolated $\sigma^\dagger \left[ A^{[B_2]} = \sigma^\dagger + O(K_2) \right].} \]
As for the middle segment, \( M[^{B_{2, \rho}}] \), finite-volume dependence enters through the factors of \( F_3 \).

The corresponding expression for the right-hand segment is

\[
R[^{(u)}][^{B_{2, \rho}}] = \left( D[^{(u)}][^{B_{2, \rho}}, A'] - D[^{(u)}][^{B_{2, \rho}}, A'] \right) \sum_{n=0}^{\infty} \left\{ \left( iF_3 \right) \left( iK[^{B_{2, \rho}}]_{df, 3} \right) \right\}^n \left( R[^{(u)}]_L \right),
\]

where we have defined the mirrored decoration operators

\[
\sigma \left( D[^{(u)}][^{B_{2, \rho}}, A'] - D[^{(u)}][^{B_{2, \rho}}, A'] \right) \equiv \left( A[^{(u)}][^{B_{2, \rho}}] \right),
\]

with

\[
\left( A[^{(u)}][^{B_{2, \rho}}] \right) = \left( A[^{(u)}][^{B_{2}}] \right) + \left( A[^{(u)}][^{B_{2, \rho}}] \right) \left( \frac{iC}{2\omega} \right) \left( iK[^{B_{2, \rho}}]_{df, 3} \right),
\]

where

\[
\left( A[^{(u)}][^{B_{2}}] \right) \equiv \left( \sigma / 3 + A[^{(u)}], 2\sigma / 3 + A[^{(s)}] + A[^{(s)}] \right).
\]

The quantities \( A[^{(u)}], A[^{(s)}] \) and \( A[^{(s)}] \) are defined in [1].

We now have all the pieces needed to construct the full unsymmetrized finite-volume scattering amplitude. The result is

\[
iM[^{(u,u)}]_{3,L} = iM[^{(u,u)}][^{B_{2}}] + L[^{(u)}][^{B_{2, \rho}}] iB_3 \sum_{n=0}^{\infty} \left\{ M[^{B_{2, \rho}}] iB_3 \right\}^n R[^{(u)}][^{B_{2, \rho}}].
\]

Reorganizing the sums, and introducing the quantity

\[
\left( iK[^{B_{2, \rho} \& B_{3}}]_{df, 3} \right) \equiv \left( iK[^{B_{2, \rho}}]_{df, 3} \right) + \left( iB[^{B_{2, \rho}}]_3 \right),
\]

where

\[
\left( iB[^{B_{2, \rho}}]_3 \right) = \sum_{n=0}^{\infty} \left( D[^{B_{2, \rho}}][^{B_{2, \rho}}, A'] - D[^{B_{2, \rho}}][^{B_{2, \rho}}, A'] \right) \left[ iB_3 D[^{B_{2, \rho}}] \right] \sum_{n=0}^{\infty} \left[ \left( iF_3 \right) \left( iK[^{B_{2, \rho} \& B_{3}}]_{df, 3} \right) \right]^n \left( R[^{(u)}]_L \right),
\]

we find

\[
iM[^{(u,u)}]_{3,L} = iD[^{(u,u)}]_L + \left( L[^{(u)}] \right) \left( iK[^{B_{2, \rho} \& B_{3}}]_{df, 3} \right) \sum_{n=0}^{\infty} \left[ \left( iF_3 \right) \left( iK[^{B_{2, \rho} \& B_{3}}]_{df, 3} \right) \right]^n \left( R[^{(u)}]_L \right).
\]

As claimed above, this has exactly the same form as the previous section, but now the \( B_3 \) contributions are contained within the modified \( K[^{B_{2, \rho} \& B_{3}}]_{df, 3} \). As in the previous section, this result remains valid when the external momenta take arbitrary values instead of being restricted to the finite-volume set. Indeed, the argument for this is unchanged, since the new features introduced by factors of \( B_3 \) only impact the infinite-volume quantities in Eq. (67) for which the transition to arbitrary external momenta is not problematic.

Symmetrizing proceeds as in the previous section, and leads to the final form for the finite-volume scattering amplitude:

\[
iM[^{(u,u)}]_{3,L}(\vec{p}, \vec{a}^*; \vec{k}, \vec{a}^*) = iD[^{(u,u)}]_L(\vec{p}, \vec{a}^*; \vec{k}, \vec{a}^*) + \frac{1}{3} + \frac{1}{1-iM[^{(u,u)}][^{B_{2, \rho}}, iG]iM[^{(u,u)}][^{B_{2, \rho}}, iF]} \left\{ \left[ \frac{1}{3} + \frac{1}{1-iM[^{(u,u)}][^{B_{2, \rho}}, iG]iM[^{(u,u)}][^{B_{2, \rho}}, iF]} \right] \right\}.
\]

---

7 We note that there is a simple mnemonic that one can use to obtain this result from the full finite-volume correlator given in Eq. (3). This follows the procedure used to derive Eq. (13) from the corresponding result for the finite-volume correlator, Eq. (13). More precisely, identifying terms with at least two insertions of \( F \), discarding the endcaps \( A' \) and \( A \), multiplying each side by an inverse of \( iF/2\omega L^3 \), discarding disconnected diagrams, and then symmetrizing, one reaches the final expression for the finite-volume three-to-three scattering amplitude given in Eq. (68). This procedure cannot, however, be rigorously justified, for two reasons. The first issue is that various redefinitions of the infinite-volume quantities were required to reach Eq. (2). This obscures which diagrams are contributing to which quantities, and the only way we could resolve this uncertainty was by starting at an earlier stage of the derivation, Eq. (13), before such redefinitions have been made. The second issue is that the quantity reached by amputating \( A, A' \) as well as the outermost \( iF/2\omega L^3 \) has ill-defined exchange symmetry. It contains certain contributions which are symmetrized and others which are not. It turns out that symmetrizing the result in the manner described in the text removes this ambiguity, without overcounting or neglecting terms.
Here $K_{df,3}$, given by

$$iK_{df,3} \equiv \begin{pmatrix} 1, & 1 \\ \end{pmatrix} \left( iK_{[B_2B_3]} \right) \begin{pmatrix} 1 \\ 1 \end{pmatrix},$$

(69)

is equal to the quantity of the same name appearing in Eq. (251) of Ref. 1. Thus we have achieved our objective—expressing $M_{3,L}$ in terms of the same intermediate quantity $K_{df,3}$ that appears in our quantization condition.

The result (69) suggests an intuitive interpretation of $K_{df,3}$ as an effective local three-particle interaction. In words, one can describe the second term on the right-hand side of Eq. (68) as having any number of two-particle interactions, jumping back and forth between scattering pairs, followed by a three-particle interaction (given by $K_{df,3}$), followed by more two-to-two scattering ($F_3$), possibly another three-particle interaction, etc., and ending with more two-to-two scattering. We note, however, that separating the local part of the three-particle scattering process involves some ambiguity, which here is manifested by the presence of the cut-off function $H$, whose detailed form is arbitrary.

V. INFINITE-VOLUME LIMIT

In this section we take the infinite-volume limit of Eq. (68) and thereby derive a relation between $M_3$, the standard three-to-three scattering amplitude, and $K_{df,3}$, the infinite-volume quantity appearing in the quantization condition.

As a warm-up, we consider first the infinite-volume limit of the two-to-two finite-volume scattering amplitude, whose form we recall is

$$M_{2,L} = \frac{1}{1 + K_2F} K_2,$$

(70)

with $F$ defined in Eqs. (A3)-(A5). $M_{2,L}$, $K_2$ and $F$ are all matrices with both spectator momentum and angular momentum indices. The total energy and momentum is $(E, \vec{P})$, while we call the incoming and outgoing spectator momenta $\vec{k}$ and $\vec{p}$, respectively. As stressed repeatedly above, these momenta are not constrained to lie in the finite-volume set. We take $L \to \infty$ holding these momenta fixed.

The crucial question when taking the infinite-volume limit is how to treat sums over finite-volume momenta. We know that (suitably normalized) sums go over to integrals

$$\frac{1}{L^3} \sum_{\vec{p}} \longrightarrow \int \frac{d^3p}{(2\pi)^3},$$

(71)

up to corrections which vanish as $L \to \infty$. If the summand is smooth the corrections vanish exponentially, while if there are singularities the corrections fall as powers of $L$. Keeping track of the latter was the main task in the analysis of Ref. 1. Here, by contrast, we do not care how the corrections fall off, only that they vanish in the limit. However a subtlety arises for summands containing singularities, because the corresponding integrals are only well-defined with a pole prescription. For any finite $L$, the finite-volume momenta will avoid the singularities unless the energy $E$ is equal to that of three non-interacting particles. But as $L \to \infty$, these singularities become arbitrarily dense and the limit is ill-defined. To take the limit we must first introduce a pole prescription for the sum. The natural choice is the $i\epsilon$ prescription, since this is the choice used in defining scattering amplitudes in infinite volume. We also consider below what happens if we use the PV prescription.

This $i\epsilon$ prescription works for sums in a straightforward way. The procedure is as follows: (1) Replace all poles in sums by poles with nonzero $i\epsilon$; (2) Send $L \to \infty$ at fixed $i\epsilon$—this limit is well defined with all sums becoming integrals; (3) Send $\epsilon \to 0$. In this limit the contribution of each diagram in the skeleton expansion for $M_{2,L}$ [see Fig. 3(b)] is converted into the corresponding contribution for $M_2$. Thus $M_{2,L} \to M_2$ when using this prescription, and similarly $M_{3,L} \to M_3$.

Focusing first on $M_{2,L}$, we note that it contains two types of finite-volume sums: those arising from matrix multiplications over the index $k$, and that contained in $F_3$. In this case (but not for $M_{3,L}$ below) the former sums are trivial. This is because spectator momentum is conserved, so all matrices are proportional to $\delta_{k_1 k_2}$. Multiplying these out leads \(^8\) to an overall $\delta_{kp}$.

---

\(^8\) The matrix multiplications over the angular momentum indices $\ell m$ go over unchanged to the infinite-volume limit.

\(^9\) There is a minor inconsistency between our matrix notation—designed for summing over finite-volume momenta—and the fact that we have generalized to arbitrary spectator momenta. In particular, since the external momenta do not appear in the finite-volume set, what does the $\delta_{k_1 k_2}$ mean? Working back through the derivation, we find that it is simply a mnemonic for spectator-momentum conservation, with no sums over intermediate spectator momenta actually appearing. The same comment applies below for all instances of this Kronecker delta.
The non-trivial sum is that contained in \( F \). Naively one might say that, since \( F \) contains a sum-integral difference [see Eq. (A5)], \( F \to 0 \) when \( L \to \infty \). After all, \( F \) is the source of finite-volume corrections. However, as already noted, this conclusion depends on the pole prescription chosen to define the sum before the limit is evaluated. If we choose the PV prescription for the sum, then, indeed, \( F \) vanishes in the limit.\(^{10}\)

\[
\lim_{L \to \infty} \left| \left. F \right\|_{\text{PV}} = 0, \right. \tag{72}
\]

Here we denote the choice of pole prescription by the subscript. On the other hand, if we define the limit by regulating the sum with an \( i\epsilon \) prescription, then it is \( F^{i\epsilon} \) of Eq. (A5) that vanishes, so that

\[
\lim_{L \to \infty} \left| \left. F \right\|_{i\epsilon} = \delta_{k\ell m} \rho_{\ell m'; \ell m}(\tilde{k}) \equiv \rho, \right. \tag{73}
\]

where \( \rho_{\ell m'; \ell m}(\tilde{k}) \) is the phase space matrix given in Eq. (A6). We stress that, in the following, \( \rho \) without an argument is a matrix with full \( k\ell m \) indices while \( \rho(\tilde{k}) \) has only \( \ell m \) indices.

Above threshold, \( \tilde{PV} \) is equivalent to the principal value prescription. Thus Eq. (74) reproduces the well known result that evaluating scattering diagrams using the PV prescription in loops (i.e. dropping the imaginary part) leads to the K-matrix. This is not, however, the infinite-volume limit that we desire. If we instead use the \( i\epsilon \) prescription we obtain

\[
\lim_{L \to \infty} \left| \left. M_{2,L} \right\|_{i\epsilon} = \frac{1}{1 + \mathcal{K}_2 \rho} \mathcal{K}_2. \right. \tag{75}
\]

Above threshold, this is indeed the standard relation between \( M_2 \) and \( \mathcal{K}_2 \), with \( \rho \) adding in the cuts needed for unitarity. This provides a check that we are taking the infinite-volume limit correctly. Below threshold (i.e. with the spectator momentum chosen so that the scattering pair are below threshold), this result provides an alternative expression for \( \mathcal{K}_2 \) in terms of \( M_2 \) analytically continued below threshold:

\[
\mathcal{K}_2^{-1} = M_2^{-1} - \rho. \tag{76}
\]

Note that, although \( \mathcal{K}_2 \) and \( \rho \) depend on the cut-off function \( H(\tilde{k}) \), this dependence cancels in \( M_2 \).

We now apply the same limiting procedure to our result for \( M_{3,L} \), Eq. (68). To do so we need some new notation. Since \( \vec{p} \) and \( \vec{k} \) become continuous variables, while angular-momentum indices remain unchanged, we adopt a hybrid notation for \( \mathcal{K}_{3,df} \) and \( \mathcal{D}^{(u,u)} \), e.g.

\[
\mathcal{K}_{3,df; p\ell' m'; k\ell m} = \mathcal{K}_{3,df; p\ell' m'; k\ell m}(\vec{p}, \vec{k}). \tag{77}
\]

We stress here that \( \mathcal{K}_{3,df} \) was already defined for arbitrary \( \vec{p} \) and \( \vec{k} \) above so that Eq. (77) is only a relabeling. Similarly, we make the continuous spectator momentum an argument of \( M_2 \), and drop the Kronecker delta from its definition:

\[
\lim_{L \to \infty} \left| \left. M_{2,L; p\ell' m'; k\ell m} \right\|_{i\epsilon} = \delta_{p k} M_{2; p\ell' m'; k\ell m}(\vec{p}). \right. \tag{78}
\]

This is similar to the notation for \( \rho \) in Eq. (73). Finally, for \( M_3 \) and its divergent part \( \mathcal{D} \), which, after symmetrization, are functions of angular variables rather than spherical harmonics [as discussed in Sec. III around Eq. (56)], we use

\[
\lim_{L \to \infty} \left| \left. M_{3,L}(\vec{p}, \hat{a}^*; \vec{k}, \hat{a}^*) \right\|_{i\epsilon} = M_3(\vec{p}, \hat{a}^*; \vec{k}, \hat{a}^*), \right. \tag{79}
\]

\(^{10}\) This is because the \( \rho \) term in Eq. (A4) is exactly what is required to turn the integral with the \( i\epsilon \) prescription in Eq. (A5) into an integral with the PV prescription. See Ref. [1] for further discussion.
and similarly for $\mathcal{D}$.

Our task is now to evaluate the limit in

\[
i\mathcal{M}_3(\vec{p}, \hat{a}^*; \vec{k}, \hat{a}^*) = \lim_{L \to \infty} \left| S \left\{ i\mathcal{D}_L^{(u,u)}(\vec{p}, \hat{a}^*; \vec{k}, \hat{a}^*) \right\} \right| \cdot \left\{ i\mathcal{K}_{df,3} \frac{1}{3} + i\mathcal{F}_3 i\mathcal{K}_{df,3} \left[ \frac{1}{3} + \frac{iF}{2\omega L^3} \right] \right\} .
\]

(80)

We can interchange the symmetrization and the taking of $L \to \infty$ because the changes of variables involved in symmetrization are independent of $L$. We thus begin by determining the $L \to \infty$ limit of $\mathcal{D}_L^{(u,u)}$, given in Eq. (25).

To do so we replace $\mathcal{M}_{2,L}$ with $\mathcal{M}_2$, and introduce an infinite-volume version of $G$

\[
G_{\ell m; t m}^{\frac{s}{s'}}(\vec{p}, \vec{k}) \equiv \left( \frac{k^s}{q_p} \right) \frac{4\pi Y_{\ell m}^{s'}(\vec{k}^s) H(\vec{p}) H(\vec{k}) Y_{\ell m}^{s'}(\vec{p}^s)}{2\omega k_p(E - \omega_k - \omega_p - i\epsilon)} \left( \frac{p^s}{q_k} \right)^{\ell}.
\]

(81)

This differs from the matrix form of $G$, given in Eq. (A2), simply by the removal of a factor of $1/(2\omega k L^3)$. This factor either cancels the explicit $(2\omega L^3)$ in $\mathcal{D}_L^{(u,u)}$, or converts sums over internal spectator momentum indices into integrals.

For example the first two terms in the geometric series obtained by expanding $\mathcal{D}_L^{(u,u)}$ have the following limits:

\[
\lim_{L \to \infty} \iota \mathcal{M}_2 iG \mathcal{M}_2 = \mathcal{M}_2(\vec{p}) iG^\infty(\vec{p}, \vec{k}) i\mathcal{M}_2(\vec{k}) ,
\]

(82)

\[
\lim_{L \to \infty} \iota \mathcal{M}_2 iG \mathcal{M}_2 iG \mathcal{M}_2 = \int \frac{1}{2\omega k} \iota \mathcal{M}_2(\vec{p}) iG^\infty(\vec{p}, \vec{s}) i\mathcal{M}_2(\vec{s}) iG^\infty(\vec{s}, \vec{k}) i\mathcal{M}_2(\vec{k}) ,
\]

(83)

where angular momentum indices are implicit. Here we are using $\int_s \equiv \int d^3 s/(2\pi)^3$. Repeating for higher-order terms we find that the infinite-volume form of $\mathcal{D}_L^{(u,u)}$, satisfies the integral equation

\[
i\mathcal{D}^{(u,u)}(\vec{p}, \vec{k}) = \mathcal{M}_2(\vec{p}) iG^\infty(\vec{p}, \vec{k}) i\mathcal{M}_2(\vec{k}) + \int_s \frac{1}{2\omega s} \iota \mathcal{M}_2(\vec{p}) iG^\infty(\vec{p}, \vec{s}) \iota \mathcal{D}^{(u,u)}(\vec{s}, \vec{k}) .
\]

(85)

Symmetrizing following Eq. (37) leads to

\[
\mathcal{D}(\vec{p}, \hat{a}^*; \vec{k}, \hat{a}^*) = S \left\{ \mathcal{D}^{(u,u)}(\vec{p}, \vec{k}) \right\} .
\]

(86)

This quantity contains all the physical divergences in $\mathcal{M}_3$, i.e. divergences that occur above threshold for physical external momenta. The difference

\[
\mathcal{M}_{df,3}(\vec{p}, \hat{a}^*; \vec{k}, \hat{a}^*) = \mathcal{M}_3(\vec{p}, \hat{a}^*; \vec{k}, \hat{a}^*) - \mathcal{D}(\vec{p}, \hat{a}^*; \vec{k}, \hat{a}^*)
\]

(87)

is free of such divergences, and can, if desired, be expanded in spherical harmonics.

To determine the $L \to \infty$ limit of the remainder of $\mathcal{M}_{3,L}$ we need to evaluate

\[
\lim_{L \to \infty} \iota \mathcal{M}_3(\vec{p}, \hat{a}^*; \vec{k}, \hat{a}^*) + \mathcal{K}_{df,3} \frac{1}{3} + \frac{iF}{2\omega L^3} \iota \mathcal{F}_3 i\mathcal{K}_{df,3} \left[ \frac{1}{3} + \frac{iF}{2\omega L^3} \right] \iota \mathcal{M}_2 iG \mathcal{M}_2(2\omega L^3) \}
\]

(88)

where $F_3$ is defined in Eq. (3). We first take the infinite-volume limit of the central part of (88), i.e.

\[
\lim_{L \to \infty} \left[ \iota \mathcal{K}_{df,3} \frac{1}{3} + \frac{iF}{2\omega L^3} \iota \mathcal{K}_{df,3} \right]_{\ell m: t m} \equiv i\mathcal{T}_{\ell m: t m}(\vec{p}, \vec{k}) .
\]

(89)

Rewriting $F_3$ as

\[
i\mathcal{F}_3 = \frac{iF}{2\omega L^3} \left[ \frac{1}{3} + \mathcal{M}_2 i\mathcal{F} + i\mathcal{D}_L^{(u,u)} \frac{iF}{2\omega L^3} \right] .
\]

(90)
we find that \( \mathcal{T} \) is given by the solution to the integral equation

\[
i \mathcal{T}(\vec{p}, \vec{k}) = i \mathcal{K}_{df,3}(\vec{p}, \vec{k}) + \int_s \int_r i \mathcal{K}_{df,3}(\vec{p}, \vec{s}) \frac{i \rho(\vec{s})}{2 \omega_\rho} \mathcal{L}^{(u,u)}(\vec{s}, \vec{r}) i \mathcal{T}(\vec{r}, \vec{k}),
\]

(91)

where

\[
\mathcal{L}^{(u,u)}(\vec{p}, \vec{k}) = \left( \frac{1}{3} + i \mathcal{M}_2(\vec{p}) i \rho(\vec{p}) \right) (2\pi)^3 \delta^3(\vec{p} - \vec{k}) + i \mathcal{D}^{(u,u)}(\vec{p}, \vec{k}) \frac{i \rho(\vec{k})}{2 \omega_\rho},
\]

(92)

and one must additionally enforce that \( \mathcal{T} \) is symmetric under particle interchange symmetry on its left-hand argument. The factors of \( \rho(\vec{k}) \) arise from the infinite-volume limit of \( F \).

What remains to be considered are the combinations at the left- and right-hand ends of Eq. (98). These become integral operators in the infinite-volume limit. Putting everything together we find

\[
i \mathcal{M}_3(\vec{p}, \hat{a}^*; \vec{k}, \hat{a}^*) = i \mathcal{D}(\vec{p}, \hat{a}^*; \vec{k}, \hat{a}^*) + S \left\{ \int_s \int_r \mathcal{L}^{(u,u)}(\vec{p}, \vec{s}) i \mathcal{T}(\vec{s}, \vec{r}) \mathcal{R}^{(u,u)}(\vec{r}, \vec{k}) \right\},
\]

(93)

where \( \mathcal{R}^{(u,u)} \) is the reflection of \( \mathcal{L}^{(u,u)} \):

\[
\mathcal{R}^{(u,u)}(\vec{p}, \vec{k}) = \left( \frac{1}{3} + i \rho(\vec{p}) i \mathcal{M}_2(\vec{p}) \right) (2\pi)^3 \delta^3(\vec{p} - \vec{k}) + i \mathcal{D}^{(u,u)}(\vec{p}, \vec{k}) \frac{i \rho(\vec{k})}{2 \omega_\rho}.
\]

(94)

Eq. (93) is our final result. It shows that \( \mathcal{M}_3 \) can be obtained from \( \mathcal{K}_{df,3} \) by solving two integral equations (first for \( \mathcal{D}^{(u,u)} \), which requires \( \mathcal{M}_2 \), and then for \( \mathcal{T} \), applying two integral operators to \( \mathcal{T} \), symmetrizing, and then adding in the divergent part \( \mathcal{D} \). We note that all the integrals appearing above have a finite range because all integrands include the cutoff function \( H \). This may be helpful when making numerical approximations.

VI. EXPRESSING \( \mathcal{K}_{df,3} \) IN TERMS OF \( \mathcal{M}_3 \)

In this brief section we show how the result (93) can be inverted so as to obtain \( \mathcal{K}_{df,3} \) given \( \mathcal{M}_3 \) (and \( \mathcal{M}_2 \)). This will be useful if one has a model for \( \mathcal{M}_3 \) and wants to determine the prediction for \( \mathcal{K}_{df,3} \), which can then be inserted into the quantization condition of Ref. [11] in order to predict the finite-volume spectrum.

We begin by rewriting Eq. (93) in terms of symmetric quantities:

\[
i \mathcal{M}_{df,3}(\vec{p}, \hat{a}^*; \vec{k}, \hat{a}^*) = \int_s \int_r \int_{\tilde{b}^*} \left\{ (2\pi)^3 \delta^3(\vec{p} - \vec{s}) 4\pi \delta^2(\hat{a}^* - \tilde{b}^*) + \Delta_\mathcal{L}(\vec{p}, \hat{a}^*; \vec{s}, \tilde{b}^*) \right\}
\times i \mathcal{T}(\vec{s}, \tilde{b}^*; \vec{r}, \hat{b}^*) \left\{ (2\pi)^3 \delta^3(\vec{r} - \vec{k}) 4\pi \delta^2(\hat{b}^* - \hat{a}^*) + \Delta_\mathcal{R}(\vec{r}, \hat{b}^*; \vec{k}, \hat{a}^*) \right\}.
\]

(95)

Here the angular averages and corresponding delta-functions are defined by

\[
\int_b \equiv \frac{1}{4\pi} \int d\Omega_b, \quad \int_\tilde{b} \equiv \frac{1}{4\pi} \int d\Omega_{\tilde{b}}, \quad \int_\hat{b} \equiv \frac{1}{4\pi} \int d\Omega_{\hat{b}}.
\]

(96)

These angular averages arise from reexpressing the sums over repeated \( \ell m \) indices as angular integrals. We have also changed from spherical harmonic indices to explicit angular dependence for the quantity \( \mathcal{T} \), using our standard normalization [see, e.g., Eq. (35)]. Finally, the quantity \( \Delta_\mathcal{R} \) is defined by

\[
(2\pi)^3 \delta^3(\vec{p} - \vec{k}) 4\pi \delta^2(\hat{a}^* - \hat{a}^*) + \Delta_\mathcal{R}(\vec{p}, \hat{a}^*; \vec{k}, \hat{a}^*) \equiv \frac{1}{3} S \left\{ \mathcal{R}^{(u,u)}(\vec{p}, \vec{k}) \right\},
\]

(97)

with \( \Delta_\mathcal{L} \) defined analogously. Note that since \( \mathcal{R}^{(u,u)} \) and \( \mathcal{L}^{(u,u)} \) are singular quantities (due to the delta functions and the poles in \( \mathcal{D}^{(u,u)} \)), they must be symmetrized in the manner described by Eq. (37). This is why we must change to angular variables.

---

11 One way to do this would be to symmetrize the matrix appearing between \( \mathcal{K}_{df,3} \) and \( \mathcal{T} \).

12 One would expect the final result to involve integrals over Lorentz-invariant three-body phase space, and indeed this is the case. The implicit sum over angular momentum indices can be rewritten as an angular integral in the scattering pair’s CM frame. This integral, combined with that over the spectator momentum, gives three-body phase space (extended to include subthreshold particles) as long as one includes the Jacobian factor \( \rho(\vec{k})/2\omega_\rho \).
To obtain Eq. [95] from Eq. [93] we have, apart from the change to angular variables, used the fact that \( T \) is symmetric under independent particle exchange on both its initial and final arguments. This allows us to symmetrize \( \mathcal{L}^{(u,u)} \) and \( \mathcal{R}^{(u,u)} \) on both the outer and inner arguments, which is what is done by the operation of \( S \). To avoid over counting we must include the factor of 1/3. We note that, although \( \Delta_L \) and \( \Delta_R \) are complicated quantities, one can in principle construct them given \( M_2 \).

We now invert Eq. [95] in stages. The first step is to construct \( \mathcal{M}_{\text{df},3} \) from \( M_3 \) using Eq. (87). Next we invert the factors on the left and right sides of \( T \) in [95]. This is done using kernels \( I_L \) and \( I_R \) that solve the integral equations

\[
I_L(p, \hat{a}^*; \hat{k}, \hat{a}^*) = (2\pi)^3 \delta(p - \hat{k}) 4\pi \delta^2(\hat{a}^* - \hat{a}^*) - \int_{s} \int_{b^*} I_L(p, \hat{a}^*; \hat{s}, \hat{b}^*) \Delta_L(\hat{s}, \hat{b}^*; \hat{k}, \hat{a}^*) , \tag{98}
\]

\[
I_R(p, \hat{a}^*; \hat{k}, \hat{a}^*) = (2\pi)^3 \delta(p - \hat{k}) 4\pi \delta^2(\hat{a}^* - \hat{a}^*) - \int_{s} \int_{b^*} \Delta_R(p, \hat{a}^*; \hat{s}, \hat{b}^*) I_R(\hat{r}, \hat{b}^*; \hat{k}, \hat{a}^*) . \tag{99}
\]

One then finds that

\[
4\pi Y_{l'm'}^{*}(\hat{a}^*) i T(\hat{p}, \hat{K}) = \int_{s} \int_{r^*} \int_{b^*} Y_{l' m'}^{*}(\hat{r}) \Delta_L(\hat{s}, \hat{b}^*; \hat{r}, \hat{b}^*) i M_{\text{df},3}(\hat{s}, \hat{r}^*; \hat{r}, \hat{b}^*) i T(\hat{r}, \hat{b}^*) \tag{100}
\]

where we have used the fact that \( T \) is non-singular to keep it expressed with spherical harmonic indices.

Finally, we reconstruct \( K_{\text{df},3} \) from \( T \) by rewriting Eq. (97) as

\[
i K_{\text{df},3}(\hat{p}, \hat{k}) = i T(\hat{p}, \hat{k}) - \int_{s} \int_{r^*} \int_{b^*} i K_{\text{df},3}(\hat{p}, \hat{s}) \frac{i p(\hat{s})}{2\omega_s} \mathcal{L}^{(u,u)}(\hat{s}, \hat{r}) i T(\hat{r}, \hat{k}) \tag{101}
\]

and now solving \( K_{\text{df},3} \), which must be done with the added condition that it is symmetric under particle interchange symmetry.

VII. SIMPLIFYING CASES

In this section we describe two approximations in which the relation between \( \mathcal{M}_3 \) and \( K_{\text{df},3} \) simplifies substantially. Such simplifications are likely to be the first step towards using this formalism in practice. Both approximations were discussed in Ref. [1].

We begin by considering the result in the approximation that only the s-wave components of \( \mathcal{M}_2 \) and \( K_{\text{df},3} \) are nonzero—which we call the s-wave approximation. In this case the quantities \( K_{\text{df},3}, D^{(u,u)}, T, \mathcal{L}, \mathcal{R} \) and \( \mathcal{M}_2 \) all are non-zero only for \( \ell = m = 0 \), so the spherical harmonic indices can be dropped. This implies that Eqs. (85), (91), (92) and (94) retain their forms, except that now all quantities are no longer matrices. In addition, \( G^\infty \) becomes the function

\[
G^\infty(\hat{p}, \hat{k}) = \frac{\mathcal{H}(\hat{p}) \mathcal{H}(\hat{k})}{2\omega_{kp}(E - \omega_{k} - \omega_{p} - \omega_{kp} + i\epsilon)} . \tag{102}
\]

The final equation (93) is replaced by

\[
i \mathcal{M}_3(\hat{p}, \hat{a}^*; \hat{k}, \hat{a}^*) = S \left\{ i D_3^{(u,u)}(\hat{p}, \hat{k}) + \int_{s} \int_{r} \mathcal{L}^{(u,u)}(\hat{p}, \hat{s}; \hat{r}) i T(\hat{s}, \hat{r}) \mathcal{R}^{(u,u)}(\hat{r}, \hat{k}) \right\} , \tag{103}
\]

where symmetrization is defined as before [Eq. (87)] except that now the quantity being symmetrized has no dependence on \( \hat{a}^* \) and \( \hat{a}^* \). Nevertheless, such dependence is introduced by the symmetrization, and thus \( \mathcal{M}_3 \) maintains its dependence on the full set of kinematic variables (albeit in a much more simplified form).

Next we consider the more restrictive approximation—referred to in Ref. [1] as the isotropic approximation—in which the s-wave approximation is extended by assuming that \( K_{\text{df},3}(\hat{p}, \hat{k}) \) depends only on the total three-particle CM energy \( E^* \),

\[
K_{\text{df},3}(\hat{p}, \hat{k}) \rightarrow K_{\text{df},3}^{\text{iso}}(E^*) . \tag{104}
\]

In this case, it is shown in Ref. [1] that \( K_{\text{df},3}^{\text{iso}} \) can be obtained from the spectrum using a simple algebraic equation [Eq. (38) of [1]]. The integral equations which determine \( \mathcal{M}_3 \) are all at fixed \( E \) and \( \hat{P} \) and thus at fixed \( E^* \). Thus \( K_{\text{df},3}^{\text{iso}} \) is simply a constant, which simplifies some of the results.
We find that $\mathcal{D}^{(u,u)}$ is the same as in the s-wave approximation, while $\mathcal{L}$ and $\mathcal{R}$ simplify to

\[
\mathcal{L}(\vec{p}) = \left[ \left( \frac{1}{3} + i M_2(\vec{p}) i \rho(\vec{p}) \right) + \int_s i \mathcal{D}^{(u,u)}(\vec{p}, \vec{s}) \frac{i \rho(\vec{s})}{2 \omega_s} \right],
\]
\[
\mathcal{R}(\vec{k}) = \left[ \left( \frac{1}{3} + i \rho(\vec{k}) i M_2(\vec{k}) \right) + \int_r i \rho(\vec{r}) \frac{i \mathcal{D}^{(u,u)}(\vec{r}, \vec{k})}{2 \omega_r} \right].
\]

Introducing the new quantity

\[
i F_3^\infty = \int_s \frac{i \rho(\vec{s})}{2 \omega_s} \left[ \frac{1}{3} + i M_2(\vec{s}) i \rho(\vec{s}) \right] + \int_r \int_s \frac{i \rho(\vec{s})}{2 \omega_s} i \mathcal{D}^{(u,u)}(\vec{s}, \vec{r}) \frac{i \rho(\vec{r})}{2 \omega_r},
\]

the final result is

\[
i M_3(\vec{p}, \hat{a}^*; \vec{k}, \hat{a}^*) = S \left\{ i D_3^{(u,u)}(\vec{p}, \vec{k}) + \mathcal{L}(\vec{p}) i K_{\text{iso}} df \frac{1}{1 - i F_3^\infty i K_{\text{iso}} df} \mathcal{R}(\vec{k}) \right\}.
\]

Thus, in this approximation, the only integral equation that needs to be solved is that for $\mathcal{D}^{(u,u)}$. Apart from that, the result for $M_3$ is obtained simply by doing integrals, all of which are over a finite range due to the cutoff function $H$.

**VIII. CONCLUSIONS AND OUTLOOK**

In this work we have derived a relation between the non-standard three-particle K-matrix, $K_{\text{df,3}}$, and the standard three-to-three scattering amplitude, $M_3$. This completes the formalism relating the finite-volume three-particle spectrum to scattering observables and removes the central drawback of the formalism presented in Ref. [1].

Future work will be dedicated to providing non-trivial checks of the formalism completed here, as well as assessing its utility. Concerning the former aim, we are currently completing a study of the three-particle quantization condition for $P = 0$ and for energy close to three-particle threshold, $E \approx 3m$. In this region the relation between finite-volume spectrum and scattering can also be accessed using non-relativistic quantum mechanics, as has been done in Refs. [7,8].

As we describe in our upcoming work, we find nontrivial agreement between our result in this limit and the results of the earlier non-relativistic analysis.

Concerning the utility of this framework, one important focus will be on solving the integral equations relating $K_{\text{df,3}}$ and $M_3$. A possible direction that one might pursue follows from the observation that, with total energy and momentum fixed, the phase space for any number of particles is compact. This means that smooth functions which depend on this phase space, such as $M_2$ in the case of two-particles and $K_{\text{df,3}}$ in the case of three, must be expressible as an infinite series of generalized harmonics. In the two-particle case this is the standard decomposition in spherical harmonics, leading to the parametrization of $M_2$ in terms of an energy-dependent phase shift for each partial wave. Identifying an analogous decomposition for $K_{\text{df,3}}$ would be a first step in providing a well-motivated parametrization to extract this quantity from the spectrum and would likely also simplify the procedure for constructing $M_3$.

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Appendix A: Definitions

We collect here definitions from Ref. [1] that are not given in the main text. The matrices appearing in $F_3$, Eq. (3) are

$$[2\omega L^3]_{k'\ell' m' : k\ell m} \equiv \delta_{k' k} \delta_{\ell' \ell} \delta_{m' m} 2\omega_k L^3,$$

$$G_{p\ell' m' : k\ell m} \equiv \left( \frac{k^*}{q_k^*} \right)^{\ell'} \frac{4\pi Y_{\ell' m'}(\hat{\rho^*} P^*) H(\hat{k}) Y_{\ell m}(\hat{\rho^*})}{2\omega_k (E - \omega_k - \omega_p - \omega_{kp})} \left( \frac{p^*}{q_k^*} \right)^\ell \frac{1}{2\omega_k L^3},$$

$$F_{k'\ell' m' : k\ell m} \equiv \delta_{k' k} F_{\ell' m' : \ell m}(k),$$

$$F_{\ell' m' : \ell m}(\hat{k}) = F_{\ell' m' : \ell m}(\hat{k}) + \rho_{\ell' m' : \ell m}(\hat{k}),$$

$$F_{\ell' m' : \ell m}(\hat{k}) = \frac{1}{2} \left[ \frac{1}{L^3} \sum_{\hat{p}} - \int \frac{d^3 p}{(2\pi)^3} \right] \frac{4\pi Y_{\ell' m'}(\hat{\rho^*} P^*) Y_{\ell m}(\hat{\rho^*}) H(\hat{k}) H(\hat{p}) H(\hat{\bar{b}}_{kp}) \left( \frac{p^*}{q_k^*} \right)^{\ell' + \ell} \frac{1}{2\omega_k L^3}. \quad (A5)$$

where the sum over $\hat{p}$ runs over all finite-volume momenta. Here $\hat{b}_{kp} = \hat{p} - \hat{k} - \hat{\rho}$ is the momentum of the third particle, and $\omega_{kp} = \sqrt{\hat{b}_{kp}^2 + m^2}$ is its on shell energy. The momentum $\hat{\rho^*}$ is the result of boosting $\hat{\rho}$ to the frame in which the non-spectator pair [which has four-momentum $P_2$, see Eq. (5)] is at rest. If all three particles are on shell, then $|\hat{\rho^*}| \equiv p^* = q_k^*$, where $q_k^*$ is given in Eq. (7). The quantities $\hat{k}^*$ and $q_k^*$ are obtained similarly by interchanging the roles of $\hat{k}$ and $\hat{\rho}$. The matrix $\rho$ is a phase-space factor for the non-spectator pair, defined by

$$\rho_{\ell' m' : \ell m}(\hat{k}) \equiv \delta_{\ell' \ell} \delta_{m' m} H(\hat{k}) \hat{\rho}(P_2),$$

$$\hat{\rho}(P_2) \equiv \frac{1}{16\pi \sqrt{P_2^*}} \times \left\{ \begin{array}{ll} \frac{-i\sqrt{P_2^*/4 - m^2}}{} & (2m)^2 < P_2^* \frac{-i\sqrt{P_2^*/4 - m^2}}{} & 0 < P_2^* \leq (2m)^2 \end{array} \right. \quad (A7)$$

Here, and in the definitions of $G$ and $F$, $H$ provides a smooth ultraviolet cut-off. We require

$$H(\hat{k}) = \begin{cases} 0, & P_2^* \leq 0; \\ 1, & (2m)^2 < P_2^* \end{cases},$$

$$J(x) = \begin{cases} 0, & x \leq 0; \\ -\frac{1}{2} \exp \left[-\frac{1}{1-x} \right], & 0 < x \leq 1; \\ 1, & 1 < x. \end{cases} \quad (A10)$$

The definitions in Eqs. (A1)-(A7) are used in Ref. [1] solely with the spectator momenta $(\hat{k}, \hat{k}' \rho)$ as well as the total momentum $(\hat{P})$ all being finite-volume momenta. As noted repeatedly in the main text, in this work we need to consider the extension to the case that these momenta are not in the finite-volume set. This presents no problems for any of the above definitions—all extend smoothly to general values of $\hat{k}, \hat{k}', \hat{\rho}$ and $\hat{P}$.

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