ANALYTICITY, MAXIMAL REGULARITY
AND MAXIMUM-NORM STABILITY
OF SEMI-DISCRETE FINITE ELEMENT SOLUTIONS
OF PARABOLIC EQUATIONS
IN NONCONVEX POLYHEDRA

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Abstract. In general polygons and polyhedra, possibly nonconvex, the analyticity of the finite element heat semigroup in the $L^q$-norm, $1 \leq q \leq \infty$, and the maximal $L^p$-regularity of semi-discrete finite element solutions of parabolic equations are proved. By using these results, the problem of maximum-norm stability of the finite element parabolic projection is reduced to the maximum-norm stability of the Ritz projection, which currently is known to hold for general polygonal domains and convex polyhedral domains.

1. Introduction

Let $\Omega$ be a polygonal or polyhedral domain in $\mathbb{R}^N$, $N = 2, 3$, and consider the heat equation

\[
\begin{cases}
\frac{\partial u(t,x)}{\partial t} - \Delta u(t,x) = f(t,x) & \text{for } (t,x) \in \mathbb{R}_+ \times \Omega, \\
 u(t,x) = 0 & \text{for } (t,x) \in \mathbb{R}_+ \times \partial \Omega, \\
 u(0,x) = u_0(x) & \text{for } x \in \Omega.
\end{cases}
\]

(1.1)

In the case $f = 0$, it is well known that the solution of (1.1) is given by $u(t,x) = (e^{t\Delta}u_0)(x)$, where $E(t) = e^{t\Delta}$ extends to a bounded analytic semigroup on $C_0(\bar{\Omega})$ and $L^q(\Omega)$ for arbitrary $1 \leq q < \infty$ (cf. [38]), satisfying the following estimates:

\[
\sup_{t > 0} \left( \left\| E(t)v \right\|_{L^q(\Omega)} + t \left\| \partial_t E(t)v \right\|_{L^q(\Omega)} \right) \leq C \left\| v \right\|_{L^q(\Omega)}, \quad v \in L^q(\Omega), \quad 1 \leq q < \infty,
\]

(1.2)

\[
\sup_{t > 0} \left( \left\| E(t)v \right\|_{C_0(\bar{\Omega})} + t \left\| \partial_t E(t)v \right\|_{C_0(\bar{\Omega})} \right) \leq C \left\| v \right\|_{C_0(\bar{\Omega})}, \quad v \in C_0(\bar{\Omega}).
\]

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In the case $u_0 = 0$, the solution of (1.1) possesses the maximal $L^p$-regularity in the space $L^q(\Omega)$, namely, for all $f \in L^p(\mathbb{R}^+; L^q(\Omega))$,

$$\|\partial_t u\|_{L^p(\mathbb{R}^+; L^q(\Omega))} + \|\Delta u\|_{L^p(\mathbb{R}^+; L^q(\Omega))} \leq C_{p,q}\|f\|_{L^p(\mathbb{R}^+; L^q(\Omega))},$$

if $u_0 = 0$, $1 < p, q < \infty$.

Such maximal $L^p$-regularity as (1.3) has important applications in the analysis of nonlinear partial differential equations (PDEs) [4,7,35], and has been widely studied in the literature; see [25] and the references therein.

This paper is concerned with the discrete analogues of (1.2)-(1.3), namely,

$$\sup_{t > 0} \left( \|E_h(t)v_h\|_{L^q(\Omega)} + \|\partial_t E_h(t)v_h\|_{L^q(\Omega)} \right) \leq C\|v_h\|_{L^q(\Omega)}$$

for all $v_h \in S_h$, $1 \leq q \leq \infty$,

$$\|\partial_t u_h\|_{L^p(\mathbb{R}^+; L^q(\Omega))} + \|\Delta_h u_h\|_{L^p(\mathbb{R}^+; L^q(\Omega))} \leq C_{p,q}\|f\|_{L^p(\mathbb{R}^+; L^q(\Omega))}$$

if $u_{h,0} = 0$, $1 < p, q < \infty$,

where $E_h(t) = e^{t\Delta_h}$ is the semigroup generated by the discrete Laplacian operator $\Delta_h$ (on a finite element subspace $S_h \subset H^1_0(\Omega)$ with mesh size $h$), defined by

$$(\Delta_h \phi_h, \varphi_h) = -(\nabla \phi_h, \nabla \varphi_h) \quad \forall \phi_h, \varphi_h \in S_h,$$

and $u_h$ is the finite element solution of (1.1), i.e.,

$$\begin{cases} 
(\partial_t u_h, v_h) + (\nabla u_h, \nabla v_h) = (f, v_h) \quad \forall v_h \in S_h \forall t \in (0, T), \\
u_h(0) = u_{h,0}.
\end{cases}$$

The constants $C$ and $C_{p,q}$ in (1.4)-(1.5) should be independent of $f$ and $h$. For the maximal $L^p$-regularity (1.5) we require $u_{h,0} = 0$ (as the continuous problem), while for error estimate we choose $u_{h,0}$ to be the $L^2$ projection of $u_0$ (see Corollary 2.3).

The discrete analyticity (1.4) and the discrete maximal $L^p$-regularity (1.5) are important mathematical tools for numerical analysis of parabolic equations. For example, (1.4) can be used to derive error estimates for both semi-discrete and fully discrete finite element methods [19,37,39,46], and (1.5) has been used to study the convergence rates of finite element solutions of semilinear parabolic equations [16] as well as nonlinear parabolic equations with nonsmooth diffusion coefficients [32]. The time-discrete extension of the maximal $L^p$-regularity (1.3) has been used to study the stability and convergence of time discretization methods for nonlinear parabolic equations with general (possibly degenerate) nonlinearities [2,3,24].

Being the foundation for many existing numerical analyses, the discrete analyticity (1.4) and the discrete maximal regularity (1.5) have been studied by many authors in the literature. In the case $q = 2$, (1.4) holds trivially [46, Lemma 3.2] and (1.5) is an immediate consequence of (1.4) due to the Hilbert space structure of $L^2(\Omega)$ (cf. 20). The discrete analyticity (1.4) for $q \in [1, \infty)$ is a simple consequence of the result in the end-point case $q = \infty$ (via complex interpolation and duality), which was proved in [43] for $N = 2$ and $r = 1$ and was proved in [30] for $N = 1, 2, 3$ and $r \geq 4$, where $r$ is the degree of finite elements. The general case $N \geq 2$ and $r \geq 1$ was proved in [14] and [17] for the Neumann and Dirichlet boundary conditions, respectively, and was extended to parabolic equations with nonsmooth diffusion coefficients in [31]. The analyses presented in these works were all restricted to smooth domains. The discrete analyticity (1.4) was proved in [40].
for convex polygons in the case $N = 2$ and $r = 1$ with a logarithmic factor $|\ln h|^\frac{3}{2}$, and was proved in [33] for convex polyhedra in the case $N = 2, 3$ and $r \geq 1$. In the presence of an extra logarithmic factor $|\ln h|^3$, the discrete analyticity (1.4) can be extended to general two-dimensional polygons (cf. [46, Theorems 6.1 and 6.3]). However, the sharp estimate (without logarithmic factor) of (1.4) remains open in nonconvex polygons and polyhedra.

Similarly, (1.5) has been proved in smooth domains and convex polygons/polyhedra [15, 33]. The extension of (1.5) to the fully discrete finite element methods has been considered in [22, section 6] and [30, 34], which rely on the semi-discrete results. For the lumped mass method, both (1.4) and (1.5) have been proved in general polygons by using the maximum principle [8, 21]. However, for the finite element method, sharp estimates of (1.4) and (1.5) remain open in nonconvex polygons and polyhedra. In particular, the techniques used in the existing works rely on the $H^2$-regularity of elliptic equations, which only holds in smooth or convex domains.

It is worth mentioning that the proof of the discrete maximal $L^p$-regularity (1.5) is closely related to the proof of the maximum-norm stability (best approximation property) of finite element solutions of parabolic equations, namely,

$$
\|u - u_h\|_{L^\infty(0,T;L^\infty(\Omega))} \leq C \ln((2 + 1/h) \inf_{\chi_h} \|u - \chi_h\|_{L^\infty(0,T;L^\infty(\Omega))}),
$$

where the infimum extends over all $\chi_h \in L^\infty(0,T;S_h)$, and the logarithmic factor “$\ln(2 + 1/h)$” in (1.8) is sharp for piecewise linear finite elements (possibly removable for higher order finite elements). Such a priori $L^\infty$-norm best approximation property has been proved in smooth domains [27, 31, 36, 43, 44, 47] and convex polygons (2D) [40], but remains open in convex polyhedra and nonconvex polygons/polyhedra, though the maximum-norm a posteriori error estimates for finite element solutions of parabolic equations have been derived in general polyhedra [11]. The a priori $L^\infty$-norm best approximation property has been proved in the fully discrete settings with discontinuous Galerkin time-stepping methods [29] (the result does not cover the semi-discrete case due to a logarithmic dependence on the time-step size). Related maximum-norm stability for finite element solutions of elliptic equations can be found in [12, 18, 28, 11, 42].

In this paper, we prove (1.4)-(1.5) in general polygons and polyhedra, possibly nonconvex (cf. Theorem 2.1), and we reduce (1.8) to the maximum-norm stability of the Ritz projection (cf. Corollary 2.2). In particular, (1.8) is proved completely in nonconvex polygons and convex polyhedra (cf. Corollary 2.3). The proof of these results relies on a dyadic decomposition of the domain $(0,1) \times \Omega = \bigcup_{s,j} Q_j$ together with some local $L^2 H^{1+\alpha}(Q_j)$ and $L^\infty H^{1+\alpha}(Q_j)$ estimates of the Green’s function (Lemma 4.1) and a local energy error estimate for finite element solutions of parabolic equations (Lemma 5.1). Related maximum-norm stability for finite element solutions of elliptic equations can be found in [12, 18, 28, 11, 42].
2. Main results and their consequences

Let \( L^q = L^q(\Omega) \). Let \( \Gamma_h(t, x, x_0) \) be the kernel of the operator \( E_h(t) \), i.e.,
\[
(2.1) \quad (E_h(t)v_h)(x_0) = \int_{\Omega} \Gamma_h(t, x, x_0)v_h(x) \, dx \quad \forall v_h \in S_h,
\]
and define \( |E_h(t)| \) to be the linear operator on \( L^q \) with the kernel \( |\Gamma_h(t, x, x_0)| \), namely,
\[
(2.2) \quad (|E_h(t)|v)(x_0) := \int_{\Omega} |\Gamma_h(t, x, x_0)||v(x)| \, dx \quad \forall v \in L^q.
\]

The main result of this paper is the following theorem.

**Theorem 2.1.** Let \( \Omega \) be a polygon in \( \mathbb{R}^2 \) or a polyhedron in \( \mathbb{R}^3 \) (possibly nonconvex), and let \( S_h, 0 < h < h_0 \), be a family of finite element subspaces of \( H^1_0(\Omega) \) consisting of piecewise polynomials of degree \( r \geq 1 \) subject to a quasi-uniform triangulation of the domain \( \Omega \) (with mesh size \( h \)). Then we have the following analytic semigroup estimate and maximal function estimate:
\[
(2.3) \quad \sup_{t > 0} \|E_h(t)v_h\|_{L^q} + t\|\partial_t E_h(t)v_h\|_{L^q} \leq C\|v_h\|_{L^q} \quad \forall v_h \in S_h \quad \forall 1 \leq q \leq \infty,
\]
\[
(2.4) \quad \sup_{t > 0} \|\partial_t E_h(t)|v|\|_{L^q} \leq C_q\|v\|_{L^q} \quad \forall v \in L^q \quad \forall 1 < q \leq \infty.
\]

Further, if \( u_{h,0} = 0 \) and \( f \in L^p(0, T; L^q) \), then the finite element solution given by (1.7) possesses the following maximal \( L^p \)-regularity:
\[
(2.5) \quad \|\partial_t u_h\|_{L^p(0, T; L^q)} + \|\Delta_h u_h\|_{L^p(0, T; L^q)} \leq \max(p, (p - 1)^{-1})C_q\|f\|_{L^p(0, T; L^q)} \quad \forall 1 < p, q < \infty,
\]
\[
(2.6) \quad \|\partial_t u_h\|_{L^\infty(0, T; L^q)} + \|\Delta_h u_h\|_{L^\infty(0, T; L^q)} \leq C\ell_h\|f\|_{L^\infty(0, T; L^q)} \quad \forall 1 \leq q \leq \infty,
\]
where \( \ell_h := \log(2 + 1/h) \).

The constant \( C \) in (2.3) and (2.6) is independent of \( f, h, p, q \) and \( T \), and the constant \( C_q \) in (2.4) and (2.5) is independent of \( f, h, p, q, \) and \( T \).

**Remark 2.1.** By the theory of analytic semigroups [51, p. 254], the inequality (2.3) implies the existence of a positive constant \( \theta \in (0, \pi/2) \), independent of \( h \) and \( q \), such that the semigroup \( \{E_h(t)\}_{t > 0} \) extends to be a bounded analytic semigroup \( \{E_h(z)\}_{z \in \Sigma_\theta} \) in the sector \( \Sigma_\theta := \{z \in \mathbb{C} \setminus \{0\} : |\arg(z)| < \theta\} \), i.e.,
\[
(2.7) \quad E_h(z_1 + z_2) = E_h(z_1)E_h(z_2) \quad \forall z_1, z_2 \in \Sigma_\theta,
\]
\[
(2.8) \quad \sup_{z \in \Sigma_\theta} \|E_h(z)v_h\|_{L^q} + |z|\|\partial_z E_h(z)v_h\|_{L^q} \leq C\|v_h\|_{L^q} \quad \forall v_h \in S_h \quad \forall 1 \leq q \leq \infty.
\]

An immediate consequence of Theorem 2.1 is the following \( R \)-boundedness result for the discrete heat semigroup and discrete resolvent operator, which has important application in deriving the time-discrete maximal \( L^p \)-regularity of the fully discrete finite element solutions discretized with backward Euler, Crank-Nicolson, second-order BDF and A-stable Runge-Kutta schemes (cf. [22, Section 6]).

**Corollary 2.1.** (\( R \)-boundedness of the discrete resolvent). Under the assumptions of Theorem 2.1 for any \( 1 < q < \infty \) there exists \( \theta_q > 0 \) (independent of \( h \)) such that:
\[
(2.9) \quad |\Gamma_h(t, x, x_0)| \leq C\|\Gamma_h(t, x, x_0)\|_{L^1} \quad \forall t > 0, x, x_0 \in \Omega.
\]
(1) The semigroup of operators \( \{E_h(z) : z \in \Sigma_{\theta_q} \} \) is R-bounded in \( \mathcal{L}(L^q, L^q) \) (the space of bounded linear operators on \( L^q \)), and the R-bound is independent of \( h \).

(2) The collection of finite element resolvent operators \( \{z(z - \Delta_h)^{-1} : z \in \Sigma_{\Delta + \theta_q} \} \) is R-bounded in \( \mathcal{L}(L^q, L^q) \), and the R-bound is independent of \( h \).

**Proof.** It is easy to see that the maximal semigroup estimate (2.4) implies the maximal ergodic estimate

\[
\left( \sup_{t \geq 0} \frac{1}{t} \int_0^t |E_h(s)||v| \, ds \right)_{L^q} \leq C_q \|v\|_{L^q} \quad \forall \ 1 < q \leq \infty.
\]

According to [49, Lemma 4.c], for \( q \in (1, 2] \) the above maximal ergodic estimate implies the R-boundedness of the semigroup of operators \( \{E_h(z)\}_{z \in \Sigma_{\theta_q}} \) in \( \mathcal{L}(L^q, L^q) \) with \( \theta_q = (\theta - \epsilon)q/2 \), where \( \epsilon \) can be arbitrarily small. For \( q \in (2, \infty) \), a duality argument shows that the semigroup \( \{E_h(z)\}_{z \in \Sigma_{\theta_q}} \) is R-bounded in \( \mathcal{L}(L^q, L^q) \) with angle \( \theta_q = (\theta - \epsilon)q/2 \) (cf. [49, Proof of Lemma 4.d]).

The second statement in Corollary 2.1 is actually a consequence of the first statement (cf. [50, Theorem 4.2]). □

Recall that the \( L^2 \) projection \( P_h : L^2(\Omega) \to S_h \) and Ritz projection \( R_h : H^1_0(\Omega) \to S_h \) onto the finite element spaces are defined by

\[
(P_h \phi, \varphi_h) = (\phi, \varphi_h) \quad \forall \phi \in L^2(\Omega) \quad \forall \varphi_h \in S_h,
\]

\[
(\nabla R_h \phi, \nabla \varphi_h) = (\nabla \phi, \nabla \varphi_h) \quad \forall \phi \in H^1_0(\Omega) \quad \forall \varphi_h \in S_h.
\]

In particular, the \( L^2 \) projection actually can be extended to \( L^q(\Omega), 1 \leq q \leq \infty \), satisfying the following estimate:

\[
\|P_h \phi\|_{L^q} \leq C\|\phi\|_{L^q} \quad \forall \phi \in L^q(\Omega), \ 1 \leq q \leq \infty,
\]

where the constant \( C \) is independent of the mesh size \( h \). The estimate above is a consequence of [46, Lemma 6.1] and the self-adjointness of \( P_h \); also see [14, 48, Lemma 7.2] and the properties of the finite element spaces stated in Section 3.2.

Besides Corollary 2.1, the maximal \( L^p \)-regularity results (2.5)–(2.6) also imply the following sharp \( L^p(0, T; L^q) \) error estimates for finite element solutions of parabolic equations.

**Corollary 2.2.** Let \( u \) and \( u_h \) be the solutions of (1.1) and (1.7), respectively. Then, under the assumptions of Theorem 2.1, we have

\[
\|u_h - P_h u\|_{L^p(0, T; L^q)} \leq C_{p,q}(\|u - R_h u\|_{L^p(0, T; L^q)} + \|P_h u(0) - u_h(0)\|_{L^q}),
\]

\[
\|u_h - P_h u\|_{L^\infty(0, T; L^\infty)} \leq C\ell_h(\|u - R_h u\|_{L^\infty(0, T; L^\infty)} + \|P_h u(0) - u_h(0)\|_{L^\infty}),
\]

for \( 1 < p, q < \infty \), where \( P_h \) and \( R_h \) denote the \( L^2 \) projection and Ritz projection onto the finite element space \( S_h \), respectively, and the constants \( C_{p,q} \) and \( C \) are independent of \( u \) and \( T \).

**Proof.** Let \( \phi_h := P_h u - u_h - e^{-t}(P_h u(0) - u_h(0)) \). Then \( \phi_h \) satisfies the following operator equation:

\[
\begin{aligned}
\partial_t \phi_h - \Delta_h \phi_h &= \Delta_h (R_h u - P_h u + e^{-t}(P_h u(0) - u_h(0))) + e^{-t}(P_h u(0) - u_h(0)), \\
\phi_h(0) &= 0.
\end{aligned}
\]
Multiplying the last equation by $\Delta_h^{-1}$, we obtain

\begin{equation}
\partial_t (\Delta_h^{-1} \phi_h) - \Delta_h (\Delta_h^{-1} \phi_h) = R_h u - P_h u + (e^{-t} + e^{-t} \Delta_h^{-1})(P_h u(0) - u_h(0)),
\end{equation}

and

\[ \Delta_h^{-1} \phi_h(0) = 0. \]

By applying (2.6) to the equation above (with $q = \infty$), we have

\begin{equation}
\| \phi_h \|_{L^\infty(0,T;L^\infty)} = \| \Delta_h (\Delta_h^{-1} \phi_h) \|_{L^\infty(0,T;L^\infty)} \\
\leq C \ell_h \| R_h u - P_h u + (e^{-t} + e^{-t} \Delta_h^{-1})(P_h u(0) - u_h(0)) \|_{L^\infty(0,T;L^\infty)} \\
\leq C \ell_h (\| R_h u - P_h u \|_{L^\infty(0,T;L^\infty)} + \| P_h u(0) - u_h(0) \|_{L^\infty}),
\end{equation}

where we have used the following $L^\infty$ estimate of finite element solutions of the Poisson equation (a proof is given in Appendix C)

\begin{equation}
\| \Delta_h^{-1}(P_h u(0) - u_h(0)) \|_{L^\infty} \leq C \| P_h u(0) - u_h(0) \|_{L^\infty}.
\end{equation}

By using the $L^\infty$ stability of the $L^2$ projection (i.e., using (2.12) with $q = \infty$), (2.14) further reduces to

\begin{equation}
\| \phi_h \|_{L^\infty(0,T;L^\infty)} \leq C \ell_h (\| P_h (R_h u - u) \|_{L^\infty(0,T;L^\infty)} + \| P_h u(0) - u_h(0) \|_{L^\infty}) \\
\leq C \ell_h (\| R_h u - u \|_{L^\infty(0,T;L^\infty)} + \| P_h u(0) - u_h(0) \|_{L^\infty}).
\end{equation}

This proves the second statement of Corollary 2.2. The first statement of Corollary 2.2 can be proved similarly by applying (2.3) to (2.13).

One of the advantages of Corollary 2.2 is that it reduces the $L^\infty$ stability of finite element solutions of parabolic equations to the $L^\infty$ stability of the Ritz projection, which immediately implies the following $L^\infty$ stability results in nonconvex polygons and convex polyhedra.

**Corollary 2.3.** Under the assumptions of Theorem 2.1 if $\Omega$ is a polygon in $\mathbb{R}^2$ (possibly nonconvex) or a convex polyhedra in $\mathbb{R}^3$, and $u_{h,0} = P_h u_0$ or $u_{h,0} = R_h u_0$, then the solutions of (1.1) and (1.7) satisfy

\begin{equation}
\| u - u_h \|_{L^\infty(0,T;L^\infty)} \leq C \ell_h^2 \inf_{\chi_h} \| u - \chi_h \|_{L^\infty(0,T;L^\infty)},
\end{equation}

where the constant $C$ is independent of $h$ and $T$, and the infimum extends over all $\chi_h \in L^\infty(0,T;S_h)$.

**Proof.** In a two-dimensional polygon (possibly nonconvex) or a convex polyhedra, both the $L^2$ projection $P_h$ and the Ritz projection $R_h$ have been proved to be stable in the maximum norm (cf. [16 Lemma 6.1] and [28,42]), i.e.,

\[ \| u - P_h u \|_{L^\infty} + \| u - R_h u \|_{L^\infty} \leq C \ell_h \inf_{\chi_h \in S_h} \| u - \chi_h \|_{L^\infty}. \]

Hence, Corollary 2.2 and the inequality above imply (2.17). \qed

In the next section, we introduce the notations to be used in this paper. The proof of Theorem 2.1 is presented in Section 4.
3. Notations

3.1. Function spaces. We use the conventional notation of Sobolev spaces $W^{s,q}_0(\Omega)$, $s \geq 0$ and $1 \leq q \leq \infty$ (cf. [1]), with the abbreviations $L^q = W^{0,q}_0(\Omega)$, $W^{s,q} = W^{s,q}_0(\Omega)$ and $H^s := W^{s,2}_0(\Omega)$. The notation $H^{-s}_0(\Omega)$ denotes the dual space of $H^s_0(\Omega)$, the closure of $C_0^\infty(\Omega)$ in $H^s(\Omega)$.

For any given function $f : (0, T) \rightarrow W^{s,q}_0$ we define the Bochner norm

$$\|f\|_{L^p(0,T;W^{s,q})} := \|\|f(\cdot)\|_{W^{s,q}}\|_{L^p(0,T)} \quad \forall \ 1 \leq p, q \leq \infty, \ s \in \mathbb{R}.$$ 

For any subdomain $D \subset \Omega$, we define

$$\|f\|_{W^{s,q}(D)} := \inf_{\bar{f} \in D} \|\bar{f}\|_{W^{s,q}(\Omega)} \quad \forall \ 1 \leq q \leq \infty, \ s \in \mathbb{R},$$

where the infimum extends over all possible $\bar{f}$ defined on $\Omega$ such that $\bar{f} = f$ in $D$.

Similarly, for any subdomain $Q \subset Q = (0, 1) \times \Omega$, we define

$$\|f\|_{L^pW^{s,q}(Q)} := \inf_{\bar{f} \in Q} \|\bar{f}\|_{L^p(0,T;W^{s,q})} \quad \forall \ 1 \leq p, q \leq \infty, \ s \in \mathbb{R},$$

where the infimum extends over all possible $\bar{f}$ defined on $Q$ such that $\bar{f} = f$ in $Q$.

We use the abbreviations

$$\langle \phi, \varphi \rangle := \int_\Omega \phi(x)\varphi(x) \, dx, \quad [u, v] := \int_0^T \int_\Omega u(t,x)\varphi(t,x) \, dx \, dt,$$

and denote $w(t) = w(t, \cdot)$ for any function $w$ defined on $Q$. The notation $1_{0 < t < T}$ will denote the characteristic function of the time interval $(0, T)$, i.e., $1_{0 < t < T}(t) = 1$ if $t \in (0, T)$ while $1_{0 < t < T}(t) = 0$ if $t \notin (0, T)$.

3.2. Properties of the finite element space. For any subdomain $D \subset \Omega$, we denote by $S_h(D)$ the space of functions of $S_h$ restricted to the domain $D$, and denote by $S_h^0(D)$ the subspace of $S_h(D)$ consisting of functions which equal zero outside $D$. For any given subset $D \subset \Omega$, we denote $B_d(D) = \{x \in \Omega : \text{dist}(x, D) \leq d\}$ for $d > 0$. On a quasi-uniform triangulation of the domain $\Omega$, there exist positive constants $K$ and $\kappa$ such that the triangulation and the corresponding finite element space $S_h$ possess the following properties ($K$ and $\kappa$ are independent of the subset $D$ and $h$).

(P1) Quasi-uniformity: 
For all triangles (or tetrahedron) $\tau_h$ in the partition, the diameter $h_l$ of $\tau_h$ and the radius $\rho_l$ of its inscribed ball satisfy

$$K^{-1}h \leq \rho_l \leq h_l \leq Kh.$$

(P2) Inverse inequality: 
If $D$ is a union of elements in the partition, then

$$\|\chi_h\|_{W^{l,p}(D)} \leq Kh^{-(l-k)-(N/q-N/p)}\|\chi_h\|_{W^{k,q}(D)} \quad \forall \ \chi_h \in S_h,$$

for $0 \leq k \leq l \leq 1$ and $1 \leq q \leq p \leq \infty$.

(P3) Local approximation and superapproximation: 
There exists an operator $I_h : H^1_0(\Omega) \rightarrow S_h$ with the following properties (cf. Appendix B):

1. $$\|v - I_hv\|_{L^2} + h\|\nabla(v - I_hv)\|_{L^2} \leq Kh^{1+\alpha}\|v\|_{H^{1+\alpha}} \quad \forall \ v \in H^{1+\alpha}(\Omega) \cap H^1_0(\Omega), \ \alpha \in [0, 1],$$

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(2) If \( d \geq 2h \), then the value of \( I_h v \) in \( D \) depends only on the value of \( v \) in \( B_d(D) \). If \( d \geq 2h \) and \( \text{supp}(v) \subseteq \bar{D} \), then \( I_h v \in S_h^0(B_d(D)) \).

(3) If \( d \geq 2h \), \( \omega = 0 \) outside \( D \) and \( |\partial^\beta \omega| \leq Cd^{-|\beta|} \) for all multi-index \( \beta \), then

\[
\psi_h \in S_h(B_d(D)) \implies I_h(\omega \psi_h) \in S_h^0(B_d(D)),
\]

\[
\|\omega \psi_h - I_h(\omega \psi_h)\|_{L^2} + h\|\omega \psi_h - I_h(\omega \psi_h)\|_{H^1} \leq Kh d^{-1}\|\psi_h\|_{L^2(B_d(D))}.
\]

(4) If \( d \geq 2h \) and \( \omega \equiv 1 \) on \( B_d(D) \), then \( I_h(\omega \psi_h) = \psi_h \) on \( D \).

The properties (P1)-(P3) hold for any quasi-uniform triangulation with the standard finite element spaces consisting of globally continuous piecewise polynomials of degree \( r \geq 1 \) (cf. [45, Appendix]), and have been used in many works in studying the discrete maximal \( L^p \)-regularity and maximum-norm stability of finite element solutions of parabolic equations; see [15, 27, 31, 33, 44, 45, 47]. Property (P3)-(1) and Definition (3.2) imply the following estimate for \( \alpha \in [0,1] \):

\[
\|v - I_h v\|_{L^2(D)} + h\|v - I_h v\|_{H^1(D)} \leq Kh^{1+\alpha}\|v\|_{H^{1+\alpha}(B_d(D))} \quad \forall v \in H^{1+\alpha}(B_d(D)) \cap H^1_0(\Omega).
\]

### 3.3. Green’s functions.

For any \( x_0 \in \tau_l^h \) (where \( \tau_l^h \) is a triangle or a tetrahedron in the triangulation of \( \Omega \)), there exists a function \( \delta_{x_0} \in C^3(\Omega) \) with support in \( \tau_l^h \) such that

\[
\chi_h(x_0) = \int_\Omega \chi_h \delta_{x_0} \, dx \quad \forall \chi_h \in S_h,
\]

and

\[
\|\delta_{x_0}\|_{W^{l,p}} \leq Kh^{l-N(1-1/p)} \quad \text{for} \quad 1 \leq p \leq \infty, \quad l = 0, 1, 2, 3,
\]

\[
\sup_{y \in \Omega} \int_\Omega |\delta_{x_0}(x)| \, dx + \sup_{x \in \Omega} \int_\Omega |\delta_{x_0}(x)| \, dy \leq C.
\]

The construction of \( \delta_{x_0} \) can be found in [47, Lemma 2.2]. Let \( \delta_{x_0} \) denote the Dirac Delta function centered at \( x_0 \). In other words,

\[
\int_\Omega \delta_{x_0}(y) \varphi(y) \, dy = \varphi(x_0)
\]

for arbitrary \( \varphi \in C(\overline{\Omega}) \). Then the discrete Delta function

\[
\delta_{h,x_0} := P_h \delta_{x_0} = P_h \delta_{x_0}
\]

decays exponentially away from \( x_0 \) (cf. [48, Lemma 7.2]):

\[
|\delta_{h,x_0}(x)| = |P_h \delta_{x_0}(x)| \leq Kh^N e^{-\frac{|x-x_0|}{kh}} \quad \forall x, x_0 \in \Omega.
\]

Let \( G(t, x, x_0) \) denote the Green’s function of the parabolic equation, i.e., \( G = G(\cdot, \cdot, x_0) \) is the solution of

\[
\begin{cases}
\partial_t G(\cdot, \cdot, x_0) - \Delta G(\cdot, \cdot, x_0) = 0 & \text{in } (0, T) \times \Omega, \\
G(\cdot, \cdot, x_0) = 0 & \text{on } (0, T) \times \partial \Omega, \\
G(0, \cdot, x_0) = \delta_{x_0} & \text{in } \Omega.
\end{cases}
\]
The Green’s function $G(t, x, y)$ is symmetric with respect to $x$ and $y$. It has an analytic extension to the right half-plane, satisfying the following Gaussian estimate (cf. [10], p. 103):

\begin{equation}
|G(z, x, y)| \leq C_\theta |z|^{-N} e^{-\frac{|x-y|^2}{C_\theta}} \quad \forall \; z \in \Sigma_\theta \forall \; x, y \in \Omega \quad \forall \; \theta \in (0, \pi/2),
\end{equation}

where the constant $C_\theta$ depends only on $\theta$. Then Cauchy’s integral formula says that

\begin{equation}
\partial_t^k G(t, x, y) = \frac{k!}{2\pi i} \int_{|z-t| = \frac{1}{t}} \frac{G(z, x, y)}{(z-t)^{k+1}} \, dz,
\end{equation}

which further yields the following Gaussian pointwise estimate for the time derivatives of Green’s function (cf. [15, Appendix B with $\alpha = \beta = 0$]):

\begin{equation}
|\partial_t^k G(t, x, x_0)| \leq \frac{C_k}{t^{k+N/2}} e^{-\frac{|x-x_0|^2}{C_k t^2}} \quad \forall \; x, x_0 \in \Omega \; \forall \; t > 0, \; k = 0, 1, 2, \ldots.
\end{equation}

Let $\Gamma = \Gamma(\cdot, \cdot, x_0)$ be the regularized Green’s function of the parabolic equation, defined by

\begin{equation}
\begin{cases}
\partial_t \Gamma(\cdot, \cdot, x_0) - \Delta \Gamma(\cdot, \cdot, x_0) = 0 & \text{in } (0, T) \times \Omega, \\
\Gamma(\cdot, \cdot, x_0) = 0 & \text{on } (0, T) \times \partial \Omega, \\
\Gamma(0, \cdot, x_0) = \delta_{x_0} & \text{in } \Omega,
\end{cases}
\end{equation}

and let $\Gamma_h = \Gamma_h(\cdot, \cdot, x_0)$ be the finite element approximation of $\Gamma$, defined by

\begin{equation}
\begin{cases}
\partial_t \Gamma_h(t, \cdot, x_0), v_h) + (\nabla \Gamma_h(t, \cdot, x_0), \nabla v_h) = 0 & \forall \; v_h \in S_h, \; t \in (0, T), \\
\Gamma_h(0, \cdot, x_0) = \delta_{h,x_0}.
\end{cases}
\end{equation}

By using the Green’s function and the discrete Green’s function, the solutions of (1.1) and (1.7) can be represented by

\begin{equation}
u(t, x_0) = \int_\Omega G(t, x, x_0)u_0(x) \, dx + \int_0^t \int_\Omega G(t-s, x, x_0)f(s, x) \, dx \, ds,
\end{equation}

\begin{equation}u_h(t, x_0) = \int_\Omega \Gamma_h(t, x, x_0)u_0,h(x) \, dx + \int_0^t \int_\Omega \Gamma_h(t-s, x, x_0)f(s, x) \, dx \, ds,
\end{equation}

and

\begin{equation}(E(t)v)(x_0) = \int_\Omega G(t, x, x_0)v(x) \, dx,
\end{equation}

\begin{equation}(E_h(t)v_h)(x_0) = \int_\Omega \Gamma_h(t, x, x_0)v_h(x) \, dx.
\end{equation}

The regularized Green’s function can be represented by

\begin{equation}\Gamma(t, x, x_0) = \int_\Omega G(t, y, x)f \tilde{\delta}_{x_0}(y) \, dy = \int_\Omega G(t, y, x)\tilde{\delta}_{x_0}(y) \, dy.
\end{equation}

From the representation (3.18) one can easily derive that the regularized Green’s function $\Gamma$ also satisfies the Gaussian pointwise estimate:

\begin{equation}|\partial_t^k \Gamma(t, x, x_0)| \leq \frac{C_k}{t^{k+N/2}} e^{-\frac{|x-x_0|^2}{C_k t^2}} \forall \; x, x_0 \in \Omega, \forall \; t > 0
\end{equation}

such that $\max(|x-x_0|, \sqrt{t}) \geq 2h$,

with $k = 0, 1, 2, \ldots$. 

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3.4. Dyadic decomposition of the domain $Q = (0, 1) \times \Omega$. In the proof of Theorem 2.1, we need to partition the domain $Q = (0, 1) \times \Omega$ into subdomains, and present estimates of the finite element solutions in each subdomain. The following dyadic decomposition of $Q$ was introduced in [44] and has been used by many authors [15, 27, 31, 33, 47]. The readers may pass this subsection if they are familiar with such dyadic decompositions.

For any integer $j$, we define $d_j = 2^{-j}$. For a given $x_0 \in \Omega$, we let $J_1 = 1$, $J_0 = 0$ and $J_*=\text{an integer satisfying } 2^{-J_*} = C_*h$ with $C_* \geq 16$ to be determined later. If

\begin{equation}
(3.20) 
\frac{h}{C_*} < 1/4
\end{equation}

then

\begin{equation}
(3.21) 
2 \leq J_* = \log_2[1/(C_*h)] \leq \log_2(2 + 1/h).
\end{equation}

Let

\begin{equation*}
Q_*(x_0) = \{(x, t) \in \Omega_T : \max(|x - x_0|, t^{1/2}) \leq d_{J_*}\}, \\
\Omega_*(x_0) = \{x \in \Omega : |x - x_0| \leq d_{J_*}\}.
\end{equation*}

We define

\begin{align*}
Q_j(x_0) &= \{(x, t) \in \Omega_T : d_j \leq \max(|x - x_0|, t^{1/2}) \leq 2d_j\} \quad \text{for } j \geq 1, \\
\Omega_j(x_0) &= \{x \in \Omega : d_j \leq |x - x_0| \leq 2d_j\} \quad \text{for } j \geq 1, \\
D_j(x_0) &= \{x \in \Omega : |x - x_0| \leq 2d_j\} \quad \text{for } j \geq 1,
\end{align*}

and

\begin{equation*}
Q_0(x_0) = Q \setminus \bigcup_{j=1}^{J_*} Q_j(x_0) \cup Q_*(x_0), \\
\Omega_0(x_0) = \Omega \setminus \bigcup_{j=1}^{J_*} \Omega_j(x_0) \cup \Omega_*(x_0).
\end{equation*}

For $j < 0$, we simply define $Q_j(x_0) = \Omega_j(x_0) = \emptyset$. For all integer $j \geq 0$, we define

\begin{align*}
\Omega_j'(x_0) &= \Omega_j(x_0), \\
Q_j'(x_0) &= Q_j(x_0), \\
\Omega_j''(x_0) &= \Omega_j(x_0), \\
Q_j''(x_0) &= Q_j(x_0), \\
D_j'(x_0) &= D_j(x_0), \\
D_j''(x_0) &= D_j(x_0).
\end{align*}

Then we have

\begin{equation}
(3.22) 
\Omega_T = \bigcup_{j=0}^{J_*} Q_j(x_0) \cup Q_*(x_0) \quad \text{and} \quad \Omega = \bigcup_{j=0}^{J_*} \Omega_j(x_0) \cup \Omega_*(x_0).
\end{equation}

We refer to $Q_*(x_0)$ as the “innermost” set. We shall write $\sum_{*j}$ when the innermost set is included and $\sum_j$ when it is not. When $x_0$ is fixed, if there is no ambiguity, we simply write $Q_j = Q_j(x_0)$, $Q_j' = Q_j'(x_0)$, $Q_j'' = Q_j''(x_0)$, $\Omega_j = \Omega_j(x_0)$, $\Omega_j' = \Omega_j'(x_0)$ and $\Omega_j'' = \Omega_j''(x_0).$
We shall use the notations
\[
\|v\|_{k,D} = \left( \int_D \sum_{|\alpha| \leq k} |\partial^\alpha v|^2 \, dx \right)^{1/2}, \quad \|v\|_{k,Q} = \left( \int_Q \sum_{|\alpha| \leq k} |\partial^\alpha v|^2 \, dx \, dt \right)^{1/2}
\]
for any subdomains \( D \subset \Omega \) and \( Q \subset (0,1) \times \Omega. \) Throughout this paper, we denote by \( C \) a generic positive constant that is independent of \( h, x_0, \) and \( C_\ast \) (until \( C_\ast \) is determined in Section 5). To simplify the notations, we also denote \( d_\ast = d_{L_\ast}. \)

4. Proof of Theorem 2.1

4.1. Estimates of the Green’s function. In this subsection, we prove the following local \( L^2H^{1+\alpha} \) and \( L^\infty H^{1+\alpha} \) estimates for the Green’s function and regularized Green’s function. These local estimates are needed in the proof of Theorem 2.1.

Lemma 4.1. Let \( \Omega \) be a polygon in \( \mathbb{R}^2 \) or a polyhedron in \( \mathbb{R}^3 \) (possibly nonconvex). There exists \( \alpha \in (\frac{1}{2}, 1] \) and \( C > 0, \) independent of \( h \) and \( x_0, \) such that the Green’s function \( G \) defined in (3.4) and the regularized Green’s function \( \Gamma \) defined in (3.10) satisfy the following estimates:

\[
\begin{align*}
\alpha d_j^{-4-\alpha N/2} \|\Gamma(\cdot, \cdot, x_0)\|_{L^\infty(Q_j(x_0))} & + \sum_{j=1}^\infty \|\nabla \Gamma(\cdot, \cdot, x_0)\|_{L^2(Q_j(x_0))} \\
& + \sum_{j=1}^\infty \|\partial_t \Gamma(\cdot, \cdot, x_0)\|_{L^2(Q_j(x_0))} \leq C d_j^{-N/2-4-\alpha} \\
\|G(\cdot, \cdot, x_0)\|_{L^\infty H^{1+\alpha}(\bigcup_{k \leq j} Q_k(x_0))} & + \|\partial_t G(\cdot, \cdot, x_0)\|_{L^\infty H^{1+\alpha}(\bigcup_{k \leq j} Q_k(x_0))} \leq C d_j^{-N/2-1-\alpha}
\end{align*}
\]

To prove Lemma 4.1 we need to use the following two lemmas.

Lemma 4.2. Let \( \Omega \) be a polygon in \( \mathbb{R}^2 \) or a polyhedron in \( \mathbb{R}^3 \) (possibly nonconvex). Then there exists a positive constant \( \alpha \in (\frac{1}{2}, 1] \) (depending on the domain \( \Omega \)) such that the solution of the Poisson equation

\[
\begin{align*}
\Delta \varphi &= f \quad \text{in } \Omega, \\
\varphi &= 0 \quad \text{on } \partial \Omega,
\end{align*}
\]

satisfies

\[
\|\varphi\|_{H^{1+\alpha}} \leq C \|f\|_{H^{-1+\alpha}}.
\]

Lemma 4.2 is a consequence of [9, Theorem 18.13], where either “\( n_x = 2 \) (\( x \) is an edge point) and \( \mu_1(\Gamma_x) > 1/2 \) (first eigenvalue of the Laplacian in a 2D sector)” or “\( n_x = 3 \) (\( x \) is a vertex) and \( \mu_1(\Gamma_x) > 0 \) (first eigenvalue of the Laplacian in a 3D cone)”. Such regularity also holds for the Neumann Laplacian (cf. [9, Corollary 23.5]).

Lemma 4.3. Let \( \Omega \) be a polygon in \( \mathbb{R}^2 \) or a polyhedron in \( \mathbb{R}^3 \) (possibly nonconvex). Then there exists \( \alpha \in (\frac{1}{2}, 1] \) such that

\[
\|u\|_{H^{1+\alpha}} \leq C \|\nabla u\|_{L^2}^{-\alpha} \|\Delta u\|_{L^2}^\alpha \quad \forall u \in H^1_0 \quad \text{such that } \Delta u \in L^2.
\]

\[\int_D \sum_{|\alpha| \leq k} |\partial^\alpha v|^2 \, dx \]
Proof. Let $\phi_j$, $j = 1, 2, \ldots$, be the orthonormal eigenfunctions of the Dirichlet Laplacian $-\Delta$, corresponding to the eigenvalues $\lambda_j > 0$, $j = 1, 2, \ldots$, respectively. With these notations, if $u = \sum_{j=1}^{\infty} a_j \phi_j$, then

$$(-\Delta)^{\alpha/2} u := \sum_{j=1}^{\infty} \lambda_j^{\alpha/2} a_j \phi_j, \quad \alpha \in [0, 2].$$

The norm $\|(-\Delta)^{\alpha/2} u\|_{L^2} := \left(\sum_{j=1}^{\infty} \lambda_j^{\alpha/2} a_j^2\right)^{1/2}$ can be viewed as the a weighted $l^2$-norm of the sequence $(a_1, a_2, \ldots)$. Since $\|(-\Delta)^{\alpha} v\|_{L^2} = \|v\|_{H^\alpha}^2$ and $C^{-1}\|v\|_{H^1} \leq \|(-\Delta)^{1/2} v\|_{L^2} \leq C\|v\|_{H^1}$, the complex interpolation method (cf. [5, Theorem 5.4.1]) yields the following equivalence of norms:

$$C^{-1}\|v\|_{H^{1-\alpha}(\Omega)} \leq \|(-\Delta)^{(1-\alpha)/2} v\|_{L^2(\Omega)} \leq C\|v\|_{H^{1-\alpha}(\Omega)}$$

$$\forall v \in H^{1-\alpha}(\Omega) \quad \forall \alpha \in (\frac{1}{2}, 1].$$

Hence, we have

$$\|(-\Delta u, v)\| = \|(-\Delta)^{(1+\alpha)/2} u, (-\Delta)^{(1-\alpha)/2} v)\|$$

$$\leq \|(-\Delta)^{(1+\alpha)/2} u\|_{L^2} \|(-\Delta)^{(1-\alpha)/2} v\|_{L^2}$$

$$\leq C \|(-\Delta)^{(1+\alpha)/2} u\|_{L^2} \|v\|_{H^{1-\alpha}}$$

$$\forall v \in C_0^\infty(\Omega),$$

which implies (via the duality argument)

$$\|\Delta u\|_{H^{-1+\alpha}}^2 \leq C \|(-\Delta)^{(1+\alpha)/2} u\|_{L^2}^2$$

$$= \sum_j \lambda_j^{1+\alpha} a_j^2$$

$$= \sum_j (\lambda_j a_j^2)^{1-\alpha} (\lambda_j a_j^2)^\alpha$$

$$\leq \left(\sum_j \lambda_j a_j^2\right)^{1-\alpha} \left(\sum_j \lambda_j a_j^2\right)^\alpha$$

(Hölder’s inequality)

$$= \|(-\Delta)^{1/2} u\|_{L^2}^{2(1-\alpha)} \|\Delta u\|_{L^2}^{2\alpha}$$

$$= \|\nabla u\|_{L^2}^{2(1-\alpha)} \|\Delta u\|_{L^2}^{2\alpha}.$$

Lemma 4.2 implies the existence of $\alpha \in (\frac{1}{2}, 1]$ such that $\|u\|_{H^{1+\alpha}} \leq C \|\Delta u\|_{H^{-1+\alpha}}$ for all $u \in H^1_0$ such that $\Delta u \in L^2$. This (together with the inequality above) yields Lemma 4.3. \qed

Proof of Lemma 4.3. To simplify the notation, we denote $Q_j = Q_j(x_0)$. Let $0 \leq \omega_j(x, t) \leq 1$ and $0 \leq \tilde{\omega}_j(x, t) \leq 1$ be smooth cut-off functions vanishing outside $Q_j'$ and equal to 1 in $Q_j$, such that $\tilde{\omega}_j = 1$ on the support of $\omega_j$, and

$$|\partial_t^{k_1} \nabla^{k_2} \omega_j| + |\partial_t^{k_1} \nabla^{k_2} \tilde{\omega}_j| \leq C d_j^{-2k_1-k_2}$$

for all nonnegative integers $k_1$ and $k_2$. By the definition in (3.3), it suffices to prove the corresponding global estimates for the function $\omega_1 G$, which equals $G$ in $Q_j$.

Consider $\omega_j G$, which is the solution of

$$\partial_t (\omega_j G) - \Delta (\omega_j G) = \tilde{\omega}_j G \partial_t \omega_j + \omega_j G \Delta \omega_j - \nabla \cdot (2\tilde{\omega}_j G \nabla \omega_j)$$

(4.5)
in the domain $(0, \infty) \times \Omega$, with zero boundary and initial conditions. The standard energy estimate yields (cf. [24, Lemma 2.1 of Chapter III], with $q_1 = r_1 = (2N + 4)/(N + 4)$):

\begin{equation}
\|\omega_j G\|_{L^\infty(0,T;L^2)} + \|\omega_j G\|_{L^2(0,T;H^1)} \leq C\|\overline{\omega}_j G\|_{L^2(Q_j')} + C\|\Delta \omega_j\|_{L^2(Q_j')},
\end{equation}

\begin{equation}
\leq C d_j^{-2} \|G\|_{L^2(Q_j')} + C d_j^{-1} \|G\|_{L^2(Q_j')},
\end{equation}

where we have used the Gaussian estimate \textbf{(3.12)} in the last step. The last inequality implies

\begin{equation}
\|G\|_{L^\infty L^2(Q_j)} + \|G\|_{L^2 H^1(Q_j)} \leq C d_j^{-N/2},
\end{equation}

and

\begin{equation}
\|\nabla \cdot (2\overline{\omega}_j G \nabla \omega_j)\|_{L^2(Q_j')} \leq C \|\omega_j G\|_{L^2(Q_j')} + C \|\nabla \cdot \omega_j G\|_{L^2(Q_j')} \leq C d_j^{-2} \|G\|_{L^2(Q_j')} + C d_j^{-1} \|G\|_{L^2(Q_j')},
\end{equation}

where we have used \textbf{(4.7)} in the last inequality (replacing $Q_j$ by $Q_j'$). By applying the energy estimate to \textbf{(4.5)}, we have

\begin{equation}
\|\partial_t (\omega_j G)\|_{L^2(0,T;L^2)} + \|\Delta (\omega_j G)\|_{L^2(0,T;L^2)} \leq C \|\overline{\omega}_j G\|_{L^2(Q_j')} + C \|\omega_j G\|_{L^2(Q_j')} + C \|\nabla \cdot (2\overline{\omega}_j G \nabla \omega_j)\|_{L^2(Q_j')},
\end{equation}

where we have used \textbf{(3.12)}, \textbf{(4.4)} and \textbf{(4.8)} in the last step.

Lemma \textbf{4.3} implies the existence of $\alpha \in \left(\frac{1}{2}, 1\right]$ (depending on the domain $\Omega$) such that

\begin{equation}
\|\omega_j G\|_{L^2(0,T;H^{1+\alpha})} \leq C \|\nabla (\omega_j G)\|_{L^2(0,T;L^2)}^{1-\alpha} \|\Delta (\omega_j G)\|_{L^2(0,T;L^2)}^{\alpha} \leq C d_j^{-\alpha - N/2},
\end{equation}

where we have used \textbf{(4.6)} and \textbf{(4.9)} in the last step.

Similarly (replacing $G$ by $\partial_t G$ and $\partial_t G$ in the estimates above), one can prove the following estimates:

\begin{equation}
d_j^{-\alpha} \|\nabla (\omega_j \partial_t G)\|_{L^2(0,T;L^2)} + d_j^{-1-\alpha} \|\Delta (\omega_j \partial_t G)\|_{L^2(0,T;L^2)} \leq C d_j^{-\alpha - 2 - N/2},
\end{equation}

\begin{equation}
d_j^{-\alpha} \|\nabla (\omega_j \partial_t G)\|_{L^2(0,T;L^2)} + d_j^{-1-\alpha} \|\Delta (\omega_j \partial_t G)\|_{L^2(0,T;L^2)} \leq C d_j^{-\alpha - 4 - N/2}.
\end{equation}

By using \textbf{(3.12)} and \textbf{(4.4)}, the last two inequalities imply

\begin{equation}
\|\partial_t (\omega_j G)\|_{L^2(0,T;H^{1+\alpha})} \leq \|\partial_t \omega_j G\|_{L^2(0,T;H^{1+\alpha})} + \|\omega_j \partial_t G\|_{L^2(0,T;H^{1+\alpha})} \leq C d_j^{-\alpha - 2 - N/2},
\end{equation}
The estimates (4.7) and (4.10)-(4.14) imply

\[ \| \partial_t (\omega_j G) \|_{L^2(0,T;H^{1+\alpha})} \leq \| \partial_t \omega_j G \|_{L^2(0,T;H^{1+\alpha})} + 2 \| \partial_t \omega_j \partial_t G \|_{L^2(0,T;H^{1+\alpha})} + \| \omega_j \partial_t G \|_{L^2(0,T;H^{1+\alpha})} \]
\[ \leq Cd_j^{-\alpha-4N/2}. \]

The estimates (4.14) imply (4.15)

\[ d_j^{-4-\alpha+N/2} \| G(\cdot, \cdot, x_0) \|_{L^\infty(Q_j(x_0))} + d_j^{-4-\alpha} \| \nabla G(\cdot, \cdot, x_0) \|_{L^2(Q_j(x_0))} \]
\[ + d_j^{-4} \| G(\cdot, \cdot, x_0) \|_{L^2 H^{1+\alpha}(Q_j(x_0))} + d_j^{-2} \| \partial_t G(\cdot, \cdot, x_0) \|_{L^2 H^{1+\alpha}(Q_j(x_0))} \]
\[ + \| \partial_t \omega_j G(\cdot, \cdot, x_0) \|_{L^2 H^{1+\alpha}(Q_j(x_0))} \leq Cd_j^{-N/2-4-\alpha}. \]

The estimate (4.15) can also be proved for the regularized Green’s function \( \Gamma \) by using the following expression:

\[ \Gamma(t, x, x_0) = \int_{\tau_t^h} G(t, y, x) \tilde{\delta}_{x_0}(y) \, dy = \int_{\tau_t^h} G(t, y, x) \tilde{\delta}_{x_0}(y) \, dy, \]

where \( \tau_t^h \) is the triangle/tetrahedron containing \( x_0 \) (thus \( \tilde{\delta}_{x_0} \) is supported in \( \tau_t^h \)). For example, if \( y \in \tau_t^h \), then \( (t, x) \in Q_j(x_0) \Rightarrow (t, x) \in Q_j(y) \), which implies

\[ \| \Gamma(\cdot, \cdot, x_0) \|_{L^2 H^{1+\alpha}(Q_j(x_0))} = \left\| \int_{\tau_t^h} G(\cdot, \cdot, y) \tilde{\delta}_{x_0}(y) \, dy \right\|_{L^2 H^{1+\alpha}(Q_j(x_0))} \]
\[ \leq \int_{\tau_t^h} \| G(\cdot, \cdot, y) \|_{L^2 H^{1+\alpha}(Q_j(x_0))} \left| \tilde{\delta}_{x_0}(y) \right| \, dy \]
\[ \leq \int_{\tau_t^h} \| G(\cdot, \cdot, y) \|_{L^2 H^{1+\alpha}(Q_j(y))} \left| \tilde{\delta}_{x_0}(y) \right| \, dy \]
\[ \leq \int_{\Omega} Cd_j^{-\alpha-N/2} \left| \tilde{\delta}_{x_0}(y) \right| \, dy \]
\[ \leq Cd_j^{-\alpha-N/2}. \]

This completes the proof of (4.1).

From (4.6) and (4.9) we see that

\[ \| \nabla G \|_{L^2(\cup_{k \leq j} Q_k')} \leq \sum_{k \leq j} \| \nabla G \|_{L^2(Q_k')} \leq C \sum_{k \leq j} d_k^{-N/2} \leq Cd_j^{-N/2}, \]
\[ \| \Delta G \|_{L^2(\cup_{k \leq j} Q_k')} \leq \sum_{k \leq j} \| \Delta G \|_{L^2(Q_k')} \leq C \sum_{k \leq j} d_k^{-1-N/2} \leq Cd_j^{-1-N/2}. \]

Let \( \chi_j \) be a smooth cut-off function which equals 1 on \( \bigcup_{k \leq j} Q_k \) and equals zero outside \( \bigcup_{k \leq j} Q_k' \), satisfying \( |\partial_l^m \nabla \chi_j| \leq C d_j^{2l-m} \) for all nonnegative integers \( l \) and \( m \). Then \( \chi_j G \) is a function defined on \( \mathcal{Q} \) and equals \( G \) on \( \bigcup_{k \leq j} Q_k \). The inequalities (3.12) and (4.17)-(4.18) imply

\[ \| \nabla (\chi_j G) \|_{L^2(0,T;L^2)} \leq Cd_j^{-N/2}, \quad \| \Delta (\chi_j G) \|_{L^2(0,T;L^2)} \leq Cd_j^{-1-N/2}. \]

Then Lemma 4.3 implies

\[ \| \chi_j G \|_{L^2(0,T;H^{1+\alpha})} \leq C \| \nabla (\chi_j G) \|_{L^2(0,T;L^2)}^{-\alpha} \| \Delta (\chi_j G) \|_{L^2(0,T;L^2)}^{-\alpha} \]
\[ \leq Cd_j^{-\alpha-N/2}. \]
Similarly, one can prove (by using (4.11)-(4.12))

$$\| \partial_t (\chi_j G) \|_{L^2(0, T; H^{1+\alpha})} \leq C \| \nabla \partial_t (\chi_j G) \|_{L^2(0, T; L^2)}^{1-\alpha} \| \Delta \partial_t (\chi_j G) \|_{L^2(0, T; L^2)}^\alpha \leq C d_j^{-\alpha-2-N/2},$$

$$\| \partial_{tt} (\chi_j G) \|_{L^2(0, T; H^{1+\alpha})} \leq C \| \nabla \partial_{tt} (\chi_j G) \|_{L^2(0, T; L^2)}^{1-\alpha} \| \Delta \partial_{tt} (\chi_j G) \|_{L^2(0, T; L^2)}^\alpha \leq C d_j^{-\alpha-4-N/2}.$$

Hence, the interpolation between the last two inequalities yield

$$\| \chi_j G \|_{L^\infty(0, T; H^{1+\alpha})} \leq \| \chi_j G \|_{L^2(0, T; H^{1+\alpha})}^{1/2} \| \partial_t (\chi_j G) \|_{L^2(0, T; H^{1+\alpha})}^{1/2} \leq C d_j^{-\alpha-1-N/2},$$

$$\| \partial_t (\chi_j G) \|_{L^\infty(0, T; H^{1+\alpha})} \leq \| \partial_t (\chi_j G) \|_{L^2(0, T; H^{1+\alpha})}^{1/2} \| \partial_{tt} (\chi_j G) \|_{L^2(0, T; H^{1+\alpha})}^{1/2} \leq C d_j^{-\alpha-3-N/2}.$$  

This completes the proof of (4.2). \(\square\)

Besides Lemma 4.4, we also need the following lemma in the proof of Theorem 2.1. The proof of this lemma is deferred to Section 5.

**Lemma 4.4.** Under the assumptions of Theorem 2.1, the functions \(\Gamma(t, x, x_0), \Gamma(t, x, x_0), \text{ and } F(t, x, x_0) := \Gamma_h(t, x, x_0) - \Gamma(t, x, x_0)\) satisfy

$$\sup_{t \in (0, \infty)} \left( |\Gamma(t, \cdot, x_0)|_{L^1(\Omega)} + t |\partial_t \Gamma(t, \cdot, x_0)|_{L^1(\Omega)} \right) \leq C,$$

$$\sup_{t \in (0, \infty)} \left( |\Gamma(t, \cdot, x_0)|_{L^1(\Omega)} + t |\partial_t \Gamma(t, \cdot, x_0)|_{L^1(\Omega)} \right) \leq C,$$

$$\| \partial_t F(\cdot, x_0) \|_{L^1((0, \infty) \times \Omega)} + \| t \partial_{tt} F(\cdot, x_0) \|_{L^1((0, \infty) \times \Omega)} \leq C,$$

$$\| \partial_t g(t, \cdot, x_0) \|_{L^1} \leq C e^{-\lambda_0 t} \quad \forall t \geq 1,$$

where the constants \(C\) and \(\lambda_0\) are independent of \(h\).

**4.2. Proof of (2.3)-(2.4).** By denoting

$$\Gamma_h(t) = \Gamma_h(t, \cdot, x_0), \quad \Gamma(t) = \Gamma(t, \cdot, x_0) \quad \text{and} \quad F(t) = \Gamma_h(t) - \Gamma(t),$$

and using the Green’s function representation (3.17), we have

$$(\mathcal{E}(t)v_h)(x_0) = (\Gamma_h(t), v_h) = (F(t), v_h) + (\Gamma(t), v_h)$$

$$= \int_0^t (\partial_s F(s), v_h) \, ds + (F(0), v_h) + (\Gamma(t), v_h)$$

and

$$(t \partial_t \mathcal{E}(t)v_h)(x_0) = (t \partial_t F(t), v_h) + (t \partial_t \Gamma(t), v_h)$$

$$= \int_0^t (s \partial_{ss} F(s) + \partial_s F(s), v_h) \, ds + (t \partial_t \Gamma(t), v_h),$$

with (cf. (3.6)-(3.8) and Lemma 4.4)

$$\| F(0) \|_{L^1} + \| \Gamma(t) \|_{L^1} + \| t \partial_t \Gamma(t) \|_{L^1} \leq C \| \delta_h, x_0 - \delta_{x_0} \|_{L^1} + \| \Gamma(t) \|_{L^1} + \| t \partial_t \Gamma(t) \|_{L^1} \leq C.$$
By applying Lemma 4.4 to the last two equations, we obtain

\[ |(E_h(t)v_h)(x_0)| \leq (\| \partial_t F \|_{L^1([0,\infty) \times \Omega)} + \| F(0) \|_{L^1} + \| \Gamma(t) \|_{L^1}) \| v_h \|_{L^\infty} \leq C \| v_h \|_{L^\infty}, \]
\[ |(t \partial_t E_h(t)v_h)(x_0)| \leq (\| t \partial_t F \|_{L^1([0,\infty) \times \Omega)} + \| \partial_t F \|_{L^1([0,\infty) \times \Omega)} + \| t \partial_t \Gamma(t) \|_{L^1}) \| v_h \|_{L^\infty} \leq C \| v_h \|_{L^\infty}. \]

This proves (2.3) in the case \( q = \infty \). The case \( 2 \leq q \leq \infty \) follows from the two endpoint cases \( q = 2 \) and \( q = \infty \) via interpolation, and the case \( 1 \leq q \leq 2 \) follows from the case \( 2 \leq q \leq \infty \) via duality (the operators \( E_h(t) \) and \( \partial_t E_h(t) \) are self-adjoint). The proof of (2.3) is complete.

In order to prove (2.4), we need to construct a symmetrically truncated Green’s function (since the regularized Green’s function \( \Gamma(t, x, x_0) \) may not be symmetric with respect to \( x \) and \( x_0 \)). In fact, there exists a truncated Green’s function \( G_{tr}^*(t, x, y) \) satisfying the following conditions (cf. [31,33]):

1. \( G_{tr}^*(t, x, y) \) is symmetric with respect to \( x \) and \( y \), namely, \( G_{tr}^*(t, x, y) = G_{tr}^*(t, y, x) \).
2. \( G_{tr}^*(\cdot, \cdot, y) = 0 \) in \( Q_\ast(y) := \{(t, x) \in Q : \max(|x - y|, \sqrt{t}) < d_\ast\} \), and \( G_{tr}^*(0, \cdot, y) \equiv 0 \) in \( \Omega \).
3. \( 0 \leq G_{tr}^*(t, x, y) \leq G(t, x, y) \) and \( G_{tr}^*(t, y, x) = G(t, x, y) \) when \( \max(|x - y|, \sqrt{t}) > 2d_\ast \).
4. \( |\partial_t G_{tr}^*(t, x, y)| \leq C d_\ast^{-N-2} \) when \( \max(|x - y|, t^{1/2}) \leq 2d_\ast \).

Note that for the fixed triangle/tetrahedron \( \tau_l^h \) and the point \( x_0 \in \tau_l^h \), the function \( \delta_{x_0} \) is supported in \( \tau_l^h \subset \Omega_\ast(x_0) \) with \( \int_{\Omega} \delta_{x_0}(y) \, dy = 1 \). By using Lemma 4.1, there exists \( \alpha \in (\frac{1}{2}, 1] \) such that (with \( Q_{2\ast}(y) := \{(t, x) \in Q : \max(|x - y|, \sqrt{t}) < 2d_\ast\} \))

\[
(4.29) \quad \int_{(0, \infty) \times \Omega \setminus Q_{2\ast}(x_0)} |\partial_t \Gamma(t, x, x_0) - \partial_t G_{tr}^*(\tau, x, x_0)| \, dx \, dt
\]

\[ = \int_{(0, \infty) \times \Omega \setminus Q_{2\ast}(x_0)} |\partial_t \Gamma(t, x, x_0) - \partial_t G(t, x, x_0)| \, dx \, dt \]

\[ \leq \int_{(0, \infty) \times \Omega \setminus Q_{2\ast}(x_0)} \int_{\tau_l^h} |\partial_t G(t, x, y)\delta_{x_0}(y)| \, dy \, dx \, dt
\]

\[ \quad - \int_{\tau_l^h} |\partial_t G(t, x, x_0)\delta_{x_0}(y)| \, dy \, dx \, dt
\]

\[ + \int_{(0, \infty) \times \Omega \setminus Q_{2\ast}(x_0)} |\partial_t \Gamma(t, x, x_0) - \partial_t G(t, x, x_0)| \, dx \, dt
\]

\[ \leq C \int_{\Omega \setminus Q_{2\ast}(x_0)} h^{\alpha - (N-2)/2} |\partial_t G(t, x, \cdot)|_{C^{\alpha - (N-2)/2}(\tau_l^h)} \, dx \, dt
\]

\[ + \int_{(0, \infty) \times \Omega \setminus Q_{2\ast}(x_0)} |\partial_t \Gamma(t, x, x_0) - \partial_t G(t, x, x_0)| \, dx \, dt
\]

\[ =: \mathcal{I}_1 + \mathcal{I}_2. \]
By using (3.12) and (3.19) we have

$$\mathcal{I}_2 = \int_{(1,\infty) \times \Omega} |\partial_t \Gamma(t, x, x_0) - \partial_t G(t, x, x_0)| \, dx \, dt$$

$$\leq C \int_{(1,\infty) \times \Omega} \frac{C}{t^{1+N/2}} e^{-\frac{|x-x_0|^2}{c^2}} \, dx \, dt \leq C.$$

For \((t, x) \in Q_j(x_0)\) and \(y \in \mathbb{T}_j\), we have \((t, y) \in Q_j'(x)\), which implies that

$$\mathcal{I}_1 \leq C \sum_j \int_{Q_j(x_0)} h^{\alpha-(N-2)/2} |\partial_t G(t, x, \cdot)|_{C^{\alpha-(N-2)/2}(\mathbb{T}_j)} \, dx \, dt$$

$$\leq C \sum_j \int_{Q_j(x_0)} h^{1+\alpha-N/2} |\partial_t G(t, \cdot, x)|_{C^{\alpha-(N-2)/2}(Q_j(x))} \, dx \, dt$$

$$\leq C \sum_j d_j^{N+2} h^{1+\alpha-N/2} \sup_{x \in \Omega} \|\partial_t G(\cdot, \cdot, x)\|_{L^\infty C^{\alpha-(N-2)/2}(Q_j(x))}$$

$$\leq C \sum_j d_j^{N+2} h^{1+\alpha-N/2} \sup_{x \in \Omega} \|\partial_t G(\cdot, \cdot, x)\|_{L^\infty H^{1+\alpha}(Q_j(x))}$$

$$\leq C \sum_j (h/d_j)^{1+\alpha-N/2}$$

$$\leq C,$$

where \(\sum_j\) indicates summation over \(j = 0, 1, \ldots, J_*\) (see the notations at the end of Section 3.3), and the last inequality is due to the fact that \(h 2^{J_*} \leq C\).

Substituting the estimates of \(\mathcal{I}_1\) and \(\mathcal{I}_2\) into (4.29) yields

$$(4.30) \quad \int_{(0,\infty) \times \Omega \setminus Q_2(x_0)} |\partial_t \Gamma(t, x, x_0) - \partial_t G^*_tr(t, x, x_0)| \, dx \, dt \leq C.$$

Furthermore, by using the basic energy estimate, we have

$$(4.31) \quad \int_{Q_2(x_0)} |\partial_t \Gamma(t, x, x_0)| \, dx \, dt \leq C d_1^{N/2+1} \|\partial_t \Gamma(\cdot, \cdot, x_0)\|_{L^2(Q)}$$

$$\leq C d_1^{N/2+1} \|\partial_0 x_0\|_{H^1(\Omega)}$$

$$\leq C d_1^{N/2+1} h^{-N/2-1} \leq C C_1^N/2+1,$$

and (cf. Property (4) of the function \(G^*_tr(t, x, x_0)\))

$$\int_{Q_2(x_0)} |\partial_t G^*_tr(t, x, x_0)| \, dx \, dt \leq C d_1^{-N-2} d_1^{N+2} \leq C.$$

The last three inequalities imply \(\int_{(0,\infty) \times \Omega} |\partial_t \Gamma(t, x, x_0) - \partial_t G^*_tr(t, x, x_0)| \, dx \, dt \leq C\), which together with Lemma 4.4 further implies

$$(4.32) \quad \int_{(0,\infty) \times \Omega} |\partial_t \Gamma_h(t, x, x_0) - \partial_t G^*_tr(t, x, x_0)| \, dx \, dt \leq C.$$
Since both $\Gamma_h(t, x, y)$ and $G^*_{tr}(t, x, y)$ are symmetric with respect to $x$ and $y$, from the last inequality we see that the kernel
\[ K(x, y) := \int_0^\infty |\partial_t \Gamma_h(t, x, y) - \partial_t G^*_{tr}(t, x, y)| \, dt \]
is symmetric with respect to $x$ and $y$, and satisfies
\[ \sup_{y \in \Omega} \int \Omega K(x, y) \, dx + \sup_{x \in \Omega} \int \Omega K(x, y) \, dy \leq C. \]

By Schur’s lemma [23, Lemma 1.4.5], the operator $M_K$ defined by
\[ M_K v(x) := \int \Omega K(x, y) v(y) \, dy \]
is bounded on $L^q$ for all $1 \leq q \leq \infty$, i.e.,
\[ \| M_K v \|_{L^q} \leq C \| v \|_{L^q} \quad \forall \ 1 \leq q \leq \infty. \]

Then we have
\[ \sup_{t > 0} (|E_h(t)| |v|)(x_0) \]
\[ = \sup_{t > 0} \left| \int \Omega |\Gamma_h(t, x, x_0)| |v(x)| \, dx \right| \]
\[ \leq \sup_{t > 0} \int \Omega |\Gamma_h(t, x, x_0) - G^*_{tr}(t, x, x_0)| |v(x)| \, dx 
+ \sup_{t > 0} \int \Omega |G^*_{tr}(t, x, x_0)| |v(x)| \, dx \]
\[ \leq \sup_{t > 0} \int \Omega \left( |\Gamma_h(0, x, x_0) - G^*_{tr}(0, x, x_0)| \right. 
+ \int_0^t |\partial_t (\Gamma_h(s, x, x_0) - G^*_{tr}(s, x, x_0))| \, ds \bigg) |v(x)| \, dx 
+ \sup_{t > 0} \int \Omega |G^*_{tr}(t, x, x_0)| |v(x)| \, dx \]
\[ = \sup_{t > 0} \int \Omega \left( |\delta_{h,x_0}(x)| + \int_0^t |\partial_t (\Gamma_h(s, x, x_0) - G^*_{tr}(s, x, x_0))| \, ds \right) |v(x)| \, dx 
+ \sup_{t > 0} \int \Omega G(t, x, x_0) |u_h(x)| \, dx \]
\[ \leq \int \Omega Kh^{-N} e^{-\frac{|x-x_0|^2}{Kh}} |v(x)| \, dx + (M_K |v|)(x) + \sup_{t > 0} (E(t)|v|)(x_0), \]

where we have used (3.3) and (4.33) in the last step.
From (3.12) we know that \( G(t, x, x_0) \leq t^{-n/2} \Phi((x - x_0)/\sqrt{t}) \) with \( \Phi(x) := Ce^{-|x|^2/C} \), which is a radially decreasing and integrable function. Let \( \tilde{u}_h \) denote the zero extension of \( u_h \) from \( \Omega \) to \( \mathbb{R}^N \). Then Corollary 2.1.12 of [17] implies

\[
\sup_{t > 0} (E(t)|v|(x_0)) = \sup_{t > 0} \int_G(t, x, x_0)|v(x)| \, dx
\]

where \( M \) is the Hardy–Littlewood maximal operator. Since the Hardy–Littlewood maximal operator is strong-type \((\infty, \infty)\) and weak-type \((1, 1)\) ([17], Theorem 2.1.6), it follows that (via real interpolation)

\[
\|M|v||_{L^q(\mathbb{R}^N)} \leq \frac{Cq}{q-1} \|v||_{L^q(\mathbb{R}^N)} = \frac{Cq}{q-1} \|v||_{L^q(\Omega)} \quad \forall 1 < q \leq \infty.
\]

By substituting (4.34) and (4.36) into (4.35), we obtain (2.4). \( \square \)

### 4.3. Proof of (2.5) for \( 2 \leq p = q < \infty \)

In this subsection, we prove (2.5) in the simple case \( 2 \leq p = q < \infty \). The general case \( 1 < p, q < \infty \) will be proved in the next subsection based on the result of this subsection, by using the mathematical tool of singular integral operators.

Let \( f_h = P_h f \) and consider the expression

\[
\partial_t u_h(t, x_0) = \partial_t \int_0^t (E_h(t - s)f_h(s, \cdot))(x_0) \, ds
\]

where \( \mathcal{M}_h \) and \( \mathcal{K}_h \) are certain linear operators. By Lemma 4.4 we have

\[
\int_0^t \int_\Omega |\partial_t F(t - s, x, x_0)| \, dx \, ds \leq \int_0^\infty \int_\Omega |\partial_t F(t, x, x_0)| \, dx \, dt \leq C,
\]

which implies

\[
\|\mathcal{M}_h f_h\|_{L^\infty(\mathbb{R}^+; L^\infty)} \leq C\|f_h\|_{L^\infty(\mathbb{R}^+; L^\infty)}.
\]

Since the classical energy estimate implies

\[
\|\mathcal{M}_h f_h\|_{L^2(\mathbb{R}^+; L^2)} \leq C\|f_h\|_{L^2(\mathbb{R}^+; L^2)},
\]

the interpolation of the last two inequalities yields

\[
\|\mathcal{M}_h f_h\|_{L^q(\mathbb{R}^+; L^q)} \leq C\|f_h\|_{L^q(\mathbb{R}^+; L^q)} \quad \forall 2 \leq q \leq \infty.
\]

It remains to prove

\[
\|\mathcal{K}_h f_h\|_{L^q(\mathbb{R}^+; L^q)} \leq C_q\|f_h\|_{L^q(\mathbb{R}^+; L^q)} \quad \forall 2 \leq q < \infty.
\]
To this end, we express $K_h f_h$ as

$$K_h f_h(t, x_0) = \int_0^t \int_\Omega \partial_t \Gamma(t-s, x, x_0) f_h(s, x) \, dx \, ds$$

$$= \int_0^t \int_\Omega \partial_t G(t-s, x, y) \tilde{\delta}_{x_0}(y) f_h(s, x) \, dy \, dx \, ds$$

$$= \int_\Omega \tilde{\delta}_{x_0}(y) \left( \int_0^t \int_\Omega \partial_t G(t-s, x, y) f_h(s, x) \, dx \, ds \right) \, dy.$$

In view of (3.7), Schur’s lemma [23, Lemma 1.45] implies

$$\|K_h f_h(\cdot, t)\|_{L^q} \leq C \left\| \int_0^t \int_\Omega \partial_t G(t-s, x, y) f_h(s, x) \, dx \, ds \right\|_{L^q(\mathbb{R}^d; L^q)} \quad \forall 1 \leq q \leq \infty,$$

and so

$$\|K_h f_h\|_{L^q(\mathbb{R}^d; L^q)} \leq C \left\| \int_0^t \int_\Omega \partial_t G(t-s, x, y) f_h(s, x) \, dx \, ds \right\|_{L^q(\mathbb{R}^d; L^q)}$$

$$= C \left\| \partial_t W - f_h \right\|_{L^q(\mathbb{R}^d; L^q)},$$

where $W$ is the solution of the PDE problem

$$\begin{cases}
\partial_t W - \Delta W = f_h & \text{in } \mathbb{R}^+ \times \Omega, \\
W = 0 & \text{on } \mathbb{R}^+ \times \partial \Omega, \\
W(0, \cdot) = 0 & \text{in } \Omega,
\end{cases}$$

which possesses the following maximal $L^q$-regularity (in view of (1.3)):

$$\|\partial_t W\|_{L^q(\mathbb{R}^d; L^q)} \leq C_q \|f_h\|_{L^q(\mathbb{R}^d; L^q)} \quad \forall 2 \leq q < \infty.$$

The last inequality implies (4.38). Then substituting (4.42)-(4.43) into (4.38) yields

$$\|\partial_t u_h\|_{L^q(\mathbb{R}^d; L^q)} \leq C_q \|f_h\|_{L^q(\mathbb{R}^d; L^q)} \quad \forall 2 \leq q < \infty.$$

Since replacing $f_h(t, x)$ by $f_h(t, x)\delta_{t_0}, 0 < t_0 < T$ does not affect the value of $u_h(t, x)$ for $t \in (0, T)$, the last inequality implies (2.5) for $2 \leq p = q < \infty$.  

4.4. Proof of (2.5) for $1 < p, q < \infty$. In the last subsection, we have proved (2.5) for $2 \leq p = q < \infty$ by showing that the operator $E_h$ defined by

$$\langle E_h f_h(t, \cdot) \rangle = \int_0^t \partial_t E_h(t-s) f_h(s, \cdot) \, ds = (M_h f_h)(t, \cdot) + (K_h f_h)(t, \cdot)$$

satisfies

$$\|E_h f_h\|_{L^q(\mathbb{R}^d; L^q)} \leq C_q \|f_h\|_{L^q(\mathbb{R}^d; L^q)} \quad \forall 2 \leq q < \infty.$$

In this subsection, we prove (2.5) for all $1 < p, q < \infty$ via a duality argument and the singular integral operator approach.

In fact, by the same method, one can also prove that the operator $E'_h$ defined by

$$\langle E'_h f_h(t, \cdot) \rangle = \int_s^\infty \partial_t E_h(t-s) f_h(t, \cdot) \, dt$$

satisfies

$$\|E'_h f_h\|_{L^q(\mathbb{R}^d; L^q)} \leq C_q \|f_h\|_{L^q(\mathbb{R}^d; L^q)} \quad \forall 2 \leq q < \infty.$$


Since $\mathcal{E}_h'$ is the dual of $\mathcal{E}_h$, by duality we have

\begin{equation}
\|\mathcal{E}_h f_h\|_{L^q(\mathbb{R}^+; L^q)} \leq C_q \|f_h\|_{L^q(\mathbb{R}^+; L^q)} \quad \forall \ 1 < q \leq 2.
\end{equation}

The two inequalities (4.49) and (4.52) can be summarized as

\begin{equation}
\|\mathcal{E}_h f_h\|_{L^q(\mathbb{R}^+; L^q)} \leq C_q \|f_h\|_{L^q(\mathbb{R}^+; L^q)} \quad \forall \ 1 < q < \infty.
\end{equation}

Therefore, we have

\begin{equation}
\|\partial_t u_h\|_{L^q(\mathbb{R}^+; L^q)} \leq C_q \|f_h\|_{L^q(\mathbb{R}^+; L^q)} \quad \forall \ 1 < q < \infty.
\end{equation}

Overall, for any fixed $1 < q < \infty$ the operator $\mathcal{E}_h$ is bounded on $L^q(\mathbb{R}^+; L^q)$, and $\{E_h(t)\}_{t > 0}$ is an analytic semigroup satisfying (see Lemma 4.4):

\begin{align}
&\|\partial_t E_h(t - s)\|_{\mathcal{L}(L^q, L^q)} \leq C(t - s)^{-1} \quad \forall \ t > s > 0, \\
&\|\partial_{tt} E_h(t - s)\|_{\mathcal{L}(L^q, L^q)} \leq C(t - s)^{-2} \quad \forall \ t > s > 0.
\end{align}

From (4.48) and (4.55)-(4.56) we see that $\mathcal{E}_h$ is an operator-valued singular integral operator whose kernel $\partial_t E_h(t - s)1_{t > s}$ satisfying the Hörmander conditions (cf. [17] condition (4.6.2)):

\begin{align}
&\sup_{s, s_0 \in \mathbb{R}} \int_{|t - s_0| \geq 2|s - s_0|} \|\partial_t E_h(t - s)1_{t > s} - \partial_t E_h(t - s_0)1_{t > s_0}\|_{\mathcal{L}(L^q, L^q)} \ dt \leq C, \\
&\sup_{t, t_0 \in \mathbb{R}} \int_{|t - s| \geq 2|t - t_0|} \|\partial_t E_h(t - s)1_{t > s} - \partial_t E_h(t_0 - s)1_{t_0 > s}\|_{\mathcal{L}(L^q, L^q)} \ ds \leq C.
\end{align}

Under the conditions (4.57)-(4.58), the theory of singular integral operators (cf. [17] Theorem 4.6.1]) says that if $\mathcal{E}_h$ is bounded on $L^q(\mathbb{R}^+; L^q)$ for some $q \in (1, \infty)$ as proved in (4.54), then it is bounded on $L^p(\mathbb{R}^+; L^q)$ for all $p \in (1, \infty)$:

\begin{equation}
\|\mathcal{E}_h f_h\|_{L^p(\mathbb{R}^+; L^q)} \leq \max(p, (p - 1)^{-1}) C_q \|f_h\|_{L^p(\mathbb{R}^+; L^q)}.
\end{equation}

Since replacing $f_h(t, x)$ by $f_h(t, x)1_{0 < t < T}$ does not affect the value of $u_h(t, x)$ for $t \in (0, T)$, the last inequality implies (2.5) for all $1 < p, q < \infty$.

4.5. Proof of (2.6). Again, we consider

\begin{equation}
(\mathcal{E}_h f_h)(t, \cdot) = \int_0^t \partial_t E_h(t - s) f_h(s, \cdot) \ ds = \int_0^t \int_\Omega \partial_t \Gamma_h(t - s, x, \cdot) f_h(s, x) \ dx \ ds
\end{equation}
and use the following inequality: for $t \in (0, T)$,

\begin{equation}
\|E_h f_h(t, \cdot)\|_{L^\infty} \leq \left( \sup_{x_0 \in \Omega} \int_0^t \int_\Omega |\partial_t \Gamma_h(t - s, x, x_0)| \, dx \, ds \right) \|f_h\|_{L^\infty(0,T; L^\infty)}
\leq \left( \sup_{x_0 \in \Omega} \int_0^t \int_\Omega |\partial_t \Gamma_h(t, x, x_0)| \, dx \, dt \right) \|f_h\|_{L^\infty(0,T; L^\infty)}
\leq \left( \int_0^\infty \sup_{x_0 \in \Omega} \int_\Omega |\partial_t \Gamma_h(t, x, x_0)| \, dx \, dt \right) \|f_h\|_{L^\infty(0,T; L^\infty)},
\end{equation}

\begin{equation}
\|E_h f_h(t, \cdot)\|_{L^1} \leq \left( \int_0^t \sup_{x_0 \in \Omega} \int_\Omega |\partial_t \Gamma_h(t - s, x, x_0)| \, dx_0 \, ds \right) \|f_h\|_{L^\infty(0,T; L^1)}
= \left( \int_0^t \sup_{x_0 \in \Omega} \int_\Omega |\partial_t \Gamma_h(t - s, x, x_0)| \, dx \, ds \right) \|f_h\|_{L^\infty(0,T; L^1)}
\leq \left( \int_0^\infty \sup_{x_0 \in \Omega} \int_\Omega |\partial_t \Gamma_h(t, x, x_0)| \, dx \, dt \right) \|f_h\|_{L^\infty(0,T; L^1)},
\end{equation}

where we have used the symmetry $\partial_t \Gamma_h(t - s, x, x_0) = \partial_t \Gamma_h(t - s, x, x)$, due to the self-adjointness of the operator $E_h(t - s)$. By interpolation between $L^\infty$ and $L^1$, we get

\begin{equation}
\|E_h f_h\|_{L^\infty(0,T; L^q)} \leq \left( \int_0^\infty \sup_{x_0 \in \Omega} \int_\Omega |\partial_t \Gamma_h(t, x, x_0)| \, dx \, dt \right) \|f_h\|_{L^\infty(0,T; L^q)}
\end{equation}

\forall 1 \leq q \leq \infty.

It remains to prove

\begin{equation}
\int_0^\infty \sup_{x_0 \in \Omega} \int_\Omega |\partial_t \Gamma_h(t, x, x_0)| \, dx \, dt \leq C \log(2 + 1/h).
\end{equation}

To this end, we note that $\partial_t \Gamma_h(t, \cdot, x_0) = \Delta_h \Gamma_h(t, \cdot, x_0) = E_h(t) \Delta_h P_h \delta_{x_0}$. By using \(4.25\) of Lemma 4.3 and \(2.3\) (proved in Section 4.2), we have

\begin{equation}
\|\partial_t \Gamma_h(t, \cdot, x_0)\|_{L^1} \leq C t^{-1},
\end{equation}

\begin{equation}
\|\partial_t \Gamma_h(t, \cdot, x_0)\|_{L^1} \leq C \|\Delta_h P_h \delta_{x_0}\|_{L^1} \leq C h^{-2} \|P_h \delta_{x_0}\|_{L^1} \leq C h^{-2}.
\end{equation}

The interpolation of the last two inequalities gives $\|\partial_t \Gamma_h(t, \cdot, x_0)\|_{L^1} \leq \frac{C}{\theta \log(2 + 1/h)}$ for arbitrary $\theta \in (0, 1)$, where the constant $C$ is independent of $\theta$. Hence, we have

\begin{equation}
\int_0^1 \sup_{x_0 \in \Omega} \|\partial_t \Gamma(t, \cdot, x_0)\|_{L^1} \, dt \leq \frac{C}{\theta \log(2 + 1/h)}
\end{equation}

for arbitrary $\theta \in (0, 1)$. By choosing $\theta = 1/\log(2 + 1/h)$, we obtain

\begin{equation}
\int_0^1 \sup_{x_0 \in \Omega} \int_\Omega |\partial_t \Gamma(t, x, x_0)| \, dx \, dt \leq C \log(2 + 1/h).
\end{equation}

The estimate \(4.28\) implies

\begin{equation}
\int_1^\infty \sup_{x_0 \in \Omega} \int_\Omega |\partial_t \Gamma(t, x, x_0)| \, dx \, dt \leq C.
\end{equation}

The last two inequalities imply \(4.64\), and this completes the proof of \(2.6\).

The proof of Theorem 2.1 is complete (up to the proof of Lemma 4.4). \(\square\)
5. Proof of Lemma 4.4

In this section we prove Lemma 4.4, which is used in proving Theorem 2.1 in the last section. To this end, we use the following local energy error estimate for finite element solutions of parabolic equations, which extends the existing work [44, Lemma 6.1] and [33, Proposition 3.2] to nonconvex polyhedra without using the superapproximation results of the Ritz projection (cf. [44, Theorem 5.1] and [33, Proposition 3.1], which only hold in convex domains).

Lemma 5.1. Suppose that \( \phi \in L^2(0,T;H^1_0(\Omega)) \cap H^1(0,T;L^2(\Omega)) \) and \( \phi_h \in H^1(0,T;S_h) \) satisfy the equation

\[
(\partial_t (\phi - \phi_h), \chi_h) + (\nabla (\phi - \phi_h), \nabla \chi_h) = 0 \quad \forall \chi_h \in S_h, \text{ a.e. } t > 0,
\]

with \( \phi(0) = 0 \) in \( \Omega'' \). Then, under the assumptions of Theorem 2.1, we have

\[
|||\partial_t (\phi - \phi_h)\|||_{Q_j} + d_j^{-1} |||\phi - \phi_h|||_{1,Q_j} \\
\leq C\epsilon^{-3} (I_j(\phi_h(0)) + X_j(I_h\phi - \phi) + d_j^{-2} |||\phi - \phi_h|||_{Q'_j}) \\
+ (Ch^{1/2}d_j^{-1/2} + C\epsilon^{-1}h^{-1}d_j^{-1} + \epsilon)(|||\partial_t (\phi - \phi_h)\|||_{Q'_j} + d_j^{-1} |||\phi - \phi_h|||_{1,Q'_j}),
\]

where

\[
I_j(\phi_h(0)) = |||\phi_h(0)|||_{1,Q'_j} + d_j^{-1} |||\phi_h(0)|||_{\Omega''},
\]

\[
X_j(I_h\phi - \phi) = d_j |||\partial_t (I_h\phi - \phi)\|||_{1,Q_j} + |||\partial_t (I_h\phi - \phi)\|||_{Q_j} \\
+ d_j^{-1} |||I_h\phi - \phi|||_{1,Q_j} + d_j^{-2} |||I_h\phi - \phi|||_{Q'_j},
\]

where \( \epsilon \in (0,1) \) is an arbitrary positive constant, and the positive constant \( C \) is independent of \( h, j, \) and \( C_\ast \); the norms \( |||\cdot|||_{k,Q'_j} \) and \( |||\cdot|||_{k,\Omega''} \) are defined in [32,33].

The proof of Lemma 5.1 is presented in Appendix A. In the rest of this section, we apply Lemma 5.1 to prove Lemma 4.4 by denoting \( \alpha \in (\frac{1}{2},1) \) a fixed constant satisfying Lemma 4.1. The proof consists of three parts. The first part is concerned with estimates for \( t \in (0,1) \), where we convert the \( L^1 \) estimates on \( Q = (0,1) \times \Omega = Q_s \cup \bigcup_{j=0}^{J} Q_j \) into weighted \( L^2 \) estimates on the subdomains \( Q_s \) and \( Q_j, j = 0,1,\ldots, J \). The second part is concerned with estimates for \( t \geq 1 \), which is a simple consequence of the parabolic regularity. The third part is concerned with the proof of (4.25)-(4.26), which are simple consequences of the results proved in the first two parts.
Part I. First, we present estimates in the domain $Q = (0, 1) \times \Omega$ with the restriction $h < 1/(4C_*)$; see (3.20). In this case, the basic energy estimate gives

\begin{align}
(5.3) \quad & \|\partial_t \Gamma\|_{L^2(Q)} + \|\partial_t \Gamma_h\|_{L^2(Q)} \leq C(\|\Gamma(0)\|_{H^1} + \|\Gamma_h(0)\|_{H^1}) \leq Ch^{-1-N/2}, \\
(5.4) \quad & \|\Gamma\|_{L^{\infty}L^2(Q)} + \|\Gamma_h\|_{L^{\infty}L^2(Q)} \leq C(\|\Gamma(0)\|_{L^2} + \|\Gamma_h(0)\|_{L^2}) \leq Ch^{-N/2}, \\
(5.5) \quad & \|\nabla \Gamma\|_{L^2(Q)} + \|\nabla \Gamma_h\|_{L^2(Q)} \leq C(\|\Gamma(0)\|_{L^2} + \|\Gamma_h(0)\|_{L^2}) \leq Ch^{-N/2}, \\
(5.6) \quad & \|\partial_t \Gamma\|_{L^2(Q)} + \|\partial_{tt} \Gamma_h\|_{L^2(Q)} \leq C(\|\Delta \Gamma(0)\|_{H^1} + \|\Delta_h \Gamma_h(0)\|_{H^1}) \leq Ch^{-3-N/2}, \\
(5.7) \quad & \|\nabla \partial_t \Gamma\|_{L^2(Q)} + \|\nabla \partial_{tt} \Gamma_h\|_{L^2(Q)} \leq C(\|\Delta \Gamma(0)\|_{L^2} + \|\Delta_h \Gamma_h(0)\|_{L^2}) \leq Ch^{-2-N/2},
\end{align}

where we have used (3.6) and (3.8) to estimate $\Gamma(0)$ and $\Gamma_h(0)$, respectively. Hence, we have

\begin{align}
(5.8) \quad & \|\Gamma\|_{Q_*} + \|\Gamma_h\|_{Q_*} \leq C d_* \|\Gamma\|_{L^{\infty}L^2(Q_*)} + C d_* \|\Gamma_h\|_{L^{\infty}L^2(Q_*)} \\
& \quad \leq C d_* h^{-N/2} \leq CC_* h^{1-N/2}.
\end{align}

Since the volume of $Q_j$ is $Cd_j^{2+N}$, we can decompose $\|\partial_t F\|_{L^1(Q)} + \|t \partial_{tt} F\|_{L^1(Q)}$ in the following way:

\begin{align}
(5.9) \quad & \|\partial_t F\|_{L^1(Q)} + \|t \partial_{tt} F\|_{L^1(Q)} \\
& \quad \leq \|\partial_t F\|_{L^1(Q_*)} + \|t \partial_{tt} F\|_{L^1(Q_*)} + \sum_j (\|\partial_t F\|_{L^1(Q_j)} + \|t \partial_{tt} F\|_{L^1(Q_j)}) \\
& \quad \leq C d_*^{1+N/2} (\|\partial_t F\|_{Q_*} + d_*^2 \|\partial_{tt} F\|_{Q_*}) \\
& \quad \quad + \sum_j C d_j^{1+N/2} (\|\partial_t F\|_{Q_j} + d_j^2 \|\partial_{tt} F\|_{Q_j}) \\
& \quad \leq C C_*^{3+N/2} + \mathcal{K},
\end{align}

where we have used (5.3) and (5.6) to estimate $C d_*^{1+N/2} (\|\partial_t F\|_{Q_*} + d_*^2 \|\partial_{tt} F\|_{Q_*})$, and introduced the notation

\begin{equation}
(5.10) \quad \mathcal{K} := \sum_j d_j^{1+N/2} (d_j^{-1} \|F\|_{1,Q_j} + \|\partial_t F\|_{Q_j} + d_j \|\partial_{tt} F\|_{1,Q_j} + d_j^2 \|\partial_{tt} F\|_{Q_j}).
\end{equation}

It remains to estimate $\mathcal{K}$. To this end, we set “$\phi_h = \Gamma_h$, $\phi = \Gamma$, $\phi_h(0) = P_h \delta_{x_0}$ and $\phi(0) = \delta_{x_0}$” and “$\phi_h = \partial_t \Gamma_h$, $\phi = \partial_t \Gamma$, $\phi_h(0) = \Delta_h P_h \delta_{x_0}$ and $\phi(0) = \Delta \delta_{x_0}$” in Lemma 5.1, respectively. Then we obtain

\begin{align}
(5.11) \quad & d_j^{-1} \|F\|_{1,Q_j} + \|\partial_t F\|_{Q_j} \leq C \epsilon_j^{-3} (\tilde{t}_j + \tilde{X}_j + d_j^{-2} \|F\|_{Q_j}) \\
& \quad + (Ch^{1/2} d_j^{-1/2} + C \epsilon_1^{-1} h d_j^{-1} + \epsilon_1)(d_j^{-1} \|F\|_{1,Q_j} + \|\partial_t F\|_{Q_j}).
\end{align}
and

\[ d_j \| \partial_t F \|_{1,Q_j} + d_j^2 \| \partial_{tt} F \|_{Q_j} \leq C \epsilon_2^{-3} (T_j + X_j + \| \partial_t F \|_{Q_j'}) \]

\[ + (Ch^{1/2}d_j^{-1/2} + C\epsilon_2^{-1}hd_j^{-1} + \epsilon_2)(d_j \| \partial_t F \|_{1,Q_j'} + d_j^2 \| \partial_{tt} F \|_{Q_j'}) , \]

respectively, where \( \epsilon_1, \epsilon_2 \in (0,1) \) are arbitrary positive constants. By using \( (3.5) \) (local interpolation error estimate), \( (3.3) \) (exponential decay of \( P_h \delta_{x_0} \)) and Lemma \( 4.1 \) (estimates of regularized Green’s function), we have

\[ \tilde{I}_j = \| P_h \delta_{x_0} \|_{1,\Omega_j'} + d_j^{-1} \| P_h \delta_{x_0} \|_{\Omega_j'} \leq C h^2 d_j^{-3-N/2} , \]

\[ \tilde{X}_j = d_j \| (I_h \Gamma - \Gamma) \|_{1,Q_j'} + d_j \| (I_h \Gamma - \Gamma) \|_{Q_j'} \]

\[ + d_j^{-1} \| I_h \Gamma - \Gamma \|_{1,Q_j'} + d_j^{-2} \| I_h \Gamma - \Gamma \|_{Q_j'} \]

\[ \leq (d_j h^\alpha + h^{1+\alpha}) \| \partial_t \|_{L^2 H^{1+\alpha}(Q_j')} + (d_j^{-1} h^\alpha + d_j^{-2} h^{1+\alpha}) \| \partial_{tt} \|_{L^2 H^{1+\alpha}(Q_j')} \]

\[ \leq C h^\alpha d_j^{-1-\alpha-N/2} . \]

and

\[ \tilde{T}_j = d_j^2 \| \Delta_h P_h \delta_{x_0} \|_{1,\Omega_j'} + d_j \| \Delta_h P_h \delta_{x_0} \|_{\Omega_j'} \leq C h^2 d_j^{-3-N/2} , \]

\[ \tilde{X}_j = d_j \| I_h \partial_t \Gamma - \partial_t \Gamma \|_{1,Q_j'} + d_j \| I_h \partial_t \Gamma - \partial_t \Gamma \|_{Q_j'} \]

\[ + d_j \| I_h \partial_t \Gamma - \partial_t \Gamma \|_{1,Q_j'} + \| I_h \partial_t \Gamma - \partial_t \Gamma \|_{Q_j'} \]

\[ \leq (d_j h^\alpha + d_j^2 h^{1+\alpha}) \| \partial_t \|_{L^2 H^{1+\alpha}(Q_j')} + (d_j h^\alpha + h^{1+\alpha}) \| \partial_{tt} \|_{L^2 H^{1+\alpha}(Q_j')} \]

\[ \leq C h^\alpha d_j^{-1-\alpha-N/2} . \]

By choosing \( \epsilon_1 = \epsilon^4 \) and \( \epsilon_2 = \epsilon \) in \( (5.11)-(5.12) \), and substituting \( (5.11)-(5.16) \) into the expression of \( \mathcal{K} \) in \( (5.10) \), we have

\[ \mathcal{K} = \sum_j d_j^{1+N/2} (d_j^{-1} \| F \|_{1,Q_j} + \| \partial_t F \|_{Q_j} + d_j \| \partial_t F \|_{1,Q_j} + d_j^2 \| \partial_{tt} F \|_{Q_j}) \]

\[ \leq C \epsilon \sum_j d_j^{1+N/2} (h^{2} d_j^{-3-N/2} + h^{\alpha} d_j^{-1-s-N/2} + d_j^{-2} \| F \|_{Q_j'}) \]

\[ + (C h^{1/2} d_j^{-1/2} + C h d_j^{-1} + \epsilon) \sum_j d_j^{1+N/2} (d_j^{-1} \| F \|_{1,Q_j'} + \| \partial_t F \|_{Q_j'}) \]

\[ + (C h^{1/2} d_j^{-1/2} + C h d_j^{-1} + \epsilon) \sum_j d_j^{1+N/2} (d_j \| \partial_t F \|_{1,Q_j'} + d_j^2 \| \partial_{tt} F \|_{Q_j'}) \]

\[ \leq C \epsilon + C \epsilon \sum_j d_j^{-1+N/2} \| F \|_{Q_j'} \]

\[ + (C h^{1/2} d_j^{-1/2} + C h d_j^{-1} + \epsilon) \sum_j d_j^{1+N/2} (d_j^{-1} \| F \|_{1,Q_j'} + \| \partial_t F \|_{Q_j'}) \]

\[ + (C h^{1/2} d_j^{-1/2} + C h d_j^{-1} + \epsilon) \sum_j d_j^{1+N/2} (d_j \| \partial_t F \|_{1,Q_j'} + d_j^2 \| \partial_{tt} F \|_{Q_j'}) . \]
where

\begin{equation}
\mathcal{K} \leq C + CC_\ast^{3+N/2} + \sum_j C d_j^{-1+N/2} \|F\|_{Q_j}.\tag{5.19}
\end{equation}

It remains to estimate \(\|F\|_{Q_j}\). To this end, we apply a duality argument below. Let \(w\) be the solution of the backward parabolic equation

\[ -\partial_t w - \Delta w = v \quad \text{with} \quad w(T) = 0, \]

where \(v\) is a function supported on \(Q_j\) and \(\|v\|_{Q_j} = 1\). Multiplying the above equation by \(F\) yields (using integration by parts, with the notations (3.4))

\begin{equation}
[F, v] = (F(0), w(0)) + [F_t, w] + [\nabla F, \nabla w],
\end{equation}

where (since \(\tilde{d}_{x_0} = 0\) on \(\Omega''_j\))

\[(F(0), w(0)) = (P_h \tilde{d}_{x_0} - \tilde{d}_{x_0}, w(0)) = (P_h \tilde{d}_{x_0} - \tilde{d}_{x_0}, w(0) - I_h w(0)) \]

\[= (P_h \tilde{d}_{x_0}, w(0) - I_h w(0))_{\Omega''_j} + (P_h \tilde{d}_{x_0} - \tilde{d}_{x_0}, w(0) - I_h w(0))_{\Omega''_j}\]

\[= : I_1 + I_2.\]
By using Property (P3) and (3.8) (the exponential decay of $P_h\tilde{x}_0$), we derive that

\begin{align}
|\mathcal{I}_1| &\leq C h \|P_h\tilde{x}_0\| L^2(\Omega_j') \|w(0)\| H^1(\Omega) \\
&\leq C h^{1-N/2} e^{-C d_j/h} \|v\|_{Q_j} \\
&= C(d_j/h)^{1+N/2} e^{-C d_j/h} d_j^{-1-N/2} \\
&\leq C h^2 d_j^{-1-N/2},
\end{align}

\begin{align}
|\mathcal{I}_2| &\leq C \|\tilde{x}_0\| L^2(\Omega_j^c) \|v(0) - I_h w(0)\| L^2(\Omega_j^c) \\
&\leq C h^{1+\alpha} \|\tilde{x}_0\| L^2(\Omega) \inf_{\tilde{w}} \|\tilde{w}\| H^{1+\alpha}(\Omega) \\
&= C h^{1+\alpha} \|\tilde{x}_0\| L^2(\Omega_0) \|v(0)\| H^{1+\alpha}(\Omega_j^c) \\
&\leq C h^{1+\alpha-N/2} \|v(0)\| H^{1+\alpha}(\Omega_j^c),
\end{align}

where the infimum extends over all possible $\tilde{w}$ extending $w(0)$ from $(\Omega_j')^c$ to $\Omega$, and we have used (3.8) in the last step.

To estimate $\|v(0)\| H^{1+\alpha}(\Omega_j^c)$, we let $W_j$ be a set containing $(\Omega_j')^c$ but its distance to $\Omega_j$ is larger than $C^{-1}d_j$. Since

$$|x - y| + s^{1/2} \geq C_1^{-1}d_j \quad \text{for } x \in W_j \text{ and } (s, y) \in Q_j$$

for some positive constant $C_1$, it follows that $(s, x) \in \bigcup_{k \leq j + \log_2 C_1} Q_k(y)$ for $(s, y) \in Q_j$. Now, if we denote $\tilde{G}(\cdot, \cdot, y)$ as any extension of $G(\cdot, \cdot, y)$ from $\bigcup_{k \leq j + \log_2 C_1} Q_k(y)$ to $Q$, then for $x \in W_j$ we have

$$w(0, x) = \int_0^T \int_\Omega G(s, y, x)v(s, y) \, dy \, ds = \int_0^T \int_{Q_j} G(s, y, x)v(s, y) \, dy \, ds$$

$$= \int_0^T \int_{Q_j} \tilde{G}(s, y, x)v(s, y) \, dy \, ds,$$

where we have used the symmetric $G(s, y, x) = G(s, x, y)$ and the compact support of $v$ in $Q_j$. Hence, we have

\begin{align}
\|w(0, \cdot)\|_{H^{1+\alpha}(W_j)} &\leq \|w(0, \cdot)\|_{H^{1+\alpha}(\Omega)} \leq C \int_0^t \int_\Omega |\tilde{G}(s, \cdot, y)|_{H^{1+\alpha}(\Omega)} |v(s, y)| \, dy \, ds \\
&\leq C \sup_{y \in \Omega} \|\tilde{G}(\cdot, \cdot, y)\|_{L^\infty H^{1+\alpha}(\Omega)} \|v\|_{L^1(Q_j)},
\end{align}

Since the last inequality holds for all possible $\tilde{G}(\cdot, \cdot, y)$ extending $G(\cdot, \cdot, y)$ from $\bigcup_{k \leq j + \log_2 C_1} Q_k(y)$ to $Q$, it follows that (cf. definition (8.3))

\begin{align}
\|w(0, \cdot)\|_{H^{1+\alpha}(W_j)} &\leq C \sup_{y \in \Omega} \|G(\cdot, \cdot, y)\|_{L^\infty H^{1+\alpha}(\bigcup_{k \leq j + \log_2 C_1} Q_k(y))} \|v\|_{L^1(Q_j)} \\
&\leq C d_j^{-1-\alpha-N/2} \|v\|_{L^1(Q_j)} \quad \text{(here we use (4.2))} \\
&\leq C d_j^{-\alpha} \|v\|_{Q_j} = C d_j^{-\alpha}.
\end{align}

From (5.22) + (5.24), we see that the first term on the right-hand side of (5.20) is bounded by

\begin{align}
|(F(0), w(0))| &\leq C h^2 d_j^{-N/2} + C h^{1+\alpha-N/2} d_j^{-\alpha} \leq C h^{1+\alpha-N/2} d_j^{-\alpha},
\end{align}
and the remaining terms are bounded by (recall that $F = \Gamma_h - \Gamma$, where $\Gamma_h$ and $\Gamma$ are solutions of (3.13)-(3.14))
\begin{align}
\tag{5.26}
[F, w] + [\nabla F, \nabla w] &= [F_1, w - I_h w] + [\nabla F, \nabla (w - I_h w)] \\
&\leq \sum_{s,i} \left( C \| F \|_{Q_s} \| w - I_h w \|_{Q_i} + C \| F \|_{1, Q_i} \| w - I_h w \|_{1, Q_i} \right) \\
&\leq \sum_{s,i} \left( C h^{1+\alpha} \| F \|_{Q_s} + C h^\alpha \| F \|_{1, Q_i} \right) \| w \|_{L^2 H^{1+\alpha}(Q')},
\end{align}
where we have used Property (P3) of Section 3.2 in the last step.

To estimate $\| w \|_{L^2 H^{1+\alpha}(Q')}$, we consider the expression (note $v$ is supported in $Q_j$)
\begin{align}
\tag{5.27}
w(t, x) &= \int_0^T \int_\Omega G(s - t, x, y) v(s, y) 1_{s > t} \, dy \, ds \\
&= \int \int_{Q_j} G(s - t, x, y) v(s, y) 1_{s > t} \, dy \, ds.
\end{align}

For $i \leq j - 3$ (so that $d_i > d_j$), we have
\begin{align}
\tag{5.28}
&\text{if } t > 4d_j^2 \text{ then } w(t, x) = 0 \text{ (because $v$ is supported in $Q_j$)}; \\
&\text{if } t \leq 4d_j^2, (t, x) \in Q'_i \text{ and } (s, y) \in Q_j, \text{ then } d_i/4 \leq |x - y| \leq 4d_i \text{ and } s - t \in (0, d_j^2) \text{ thus } (s - t, x) \in Q'_i(y).
\end{align}

Hence, from (5.27) we derive
\begin{align}
\| w \|_{L^2 H^{1+\alpha}(Q')} &\leq \sup_y \| G(\cdot, \cdot, y) \|_{L^2 H^{1+\alpha}(Q'_i(y))} \| v \|_{L^1(Q_j)} \\
&\leq Cd_i \sup_y \| G(\cdot, \cdot, y) \|_{L^\infty H^{1+\alpha}(Q'_i(y))} \| v \|_{L^1(Q_j)} \\
&\leq Cd_i^{-\alpha - N/2} d_j^{1+N/2} \| v \|_{Q_j} \quad \text{ (here we use (4.2))} \\
&\leq Cd_i^{-\alpha} \left( \frac{d_j}{d_i} \right)^{\alpha + N/2}.
\end{align}

For $i \geq j + 3$ ($d_i \leq d_j$, including the case $i = \ast$), we have
\begin{align}
\tag{5.29}
&\text{if } (t, x) \in Q'_i \text{ and } (s, y) \in Q_j, \text{ then } \max(|s - t|^{1/2}, |x - y|) \geq d_{j+3}, \\
&\text{thus } (s - t, x) \in \bigcup_{k \leq j+3} Q_k(y), \\
&\text{if } (t, x) \in Q_\ast \text{ and } (s, y) \in Q_j \text{ with } j \leq J_\ast - 3, \text{ then } \max(|s - t|^{1/2}, |x - y|) \geq d_{j+3}, \\
&\text{thus } (s - t, x) \in \bigcup_{k \leq j+3} Q_k(y).
\end{align}

If $\widetilde{G}(\cdot, \cdot, y)$ is a function satisfying
\begin{align}
\tag{5.30}
\widetilde{G}(\cdot, \cdot, y) &= G(\cdot, \cdot, y) \quad \text{on } \bigcup_{k \leq j+3} Q_k(y),
\end{align}
then for \((t, x) \in Q'_i\) we have

\[
w(t, x) = \int_0^T \int_\Omega G(s - t, x, y)v(y, s)1_{s > t} \, dy \, ds \\
= \int\int_{Q_j} G(s - t, x, y)v(s, y)1_{s > t} \, dy \, ds.
\]

Hence, we have

\[
\|w\|_{L^2 H^{1+\alpha}(Q'_i)} \leq Cd_i \|w\|_{L^\infty H^{1+\alpha}(Q'_i)} \leq Cd_i \|w\|_{L^\infty H^{1+\alpha}(Q)} \\
\leq Cd_i \int_{Q_j} \|\tilde{G}(s - t, x, y)v(s, y)\|_{L^\infty H^{1+\alpha}(\Omega)} \, dy \, ds \\
\leq Cd_i \int_{Q_j} \|\tilde{G}(\cdot, \cdot, y)\|_{L^\infty H^{1+\alpha}(\Omega)} \|v(s, y)\|_{L^1(Q_j)} \\
\leq Cd_i \sup_{y \in \Omega} \|\tilde{G}(\cdot, \cdot, y)\|_{L^\infty H^{1+\alpha}(\Omega)} \|v\|_{L^1(Q_j)} \\
\leq Cd_i \sup_{y \in \Omega} \|\tilde{G}(\cdot, \cdot, y)\|_{L^\infty H^{1+\alpha}(\Omega)} \|v\|_{L^1(Q_j)}^{1+N/2}.
\]

In view of the definition (3.3), by taking infimum over all the possible choices of \(\tilde{G}(\cdot, \cdot, y)\) satisfying (5.30), we have

\[
\|w\|_{L^2 H^{1+\alpha}(Q'_i)} \leq Cd_i \sup_{y \in \Omega} \|G(\cdot, \cdot, y)\|_{L^\infty H^{1+\alpha}(\cup_{k \leq j+3} Q_k(y))} \|v\|_{L^1(Q_j)^{1+N/2}}. \\
\leq Cd_i d_j^{1-\alpha-N/2} d_j^{N/2+1} \quad \text{(here we use (4.2)} \\
= Cd_i^{1-\alpha} \left( \frac{d_i}{d_j} \right)^\alpha.
\]

For \(|i - j| \leq 2\), applying the standard energy estimate yields

\[
\|w\|_{L^2 H^{1+\alpha}(Q'_i)} \leq \|w\|_{L^2 H^{1+\alpha}(Q)} \\
\leq C \|v\|_{L^2 H^{\alpha-1}(Q)} \leq C \|v\|_{L^2 L^{\frac{N}{1+\alpha-N/2}}} \leq Cd_i^{1-\alpha} \|v\|_{Q} = Cd_i^{1-\alpha},
\]

where we have used the Sobolev embedding \(L^{\frac{N}{1+\alpha-N/2}} \hookrightarrow H^{\alpha-1}\) and the Hölder’s inequality

\[
\|v\|_{L^{\frac{N}{1+\alpha-N/2}}} \leq Cd_j^{1-\alpha} \|v\|_{L^2}
\]

(this requires the volume of the support of \(v\) to be bounded by \(d_j^N\)).

Combining the three cases above (corresponding to \(i \leq j - 3, i \geq j + 3\) and \(|i - j| \leq 2\), we have

\[
(w)_{L^2 H^{1+\alpha}(Q'_i)} \leq Cd_i^{1-\alpha} \left( \frac{\min(d_i, d_j)}{\max(d_i, d_j)} \right)^\alpha.
\]

Substituting (5.25)-(5.26) and (5.31) into (5.20) yields

\[
\|F\|_{Q_j} \leq Ch^{1+\alpha-N/2}d_j^{1-\alpha} + C \sum_{k,l} (h^{1+\alpha} \|F\|_{Q_j} + h^{\alpha} \|F\|_{1,Q_j})d_i^{1-\alpha} \left( \frac{\min(d_i, d_j)}{\max(d_i, d_j)} \right)^\alpha.
\]
Since $\alpha > 1/2$, it follows that
\begin{equation}
\sum_j d_j^{N/2-1} \left( \frac{\min(d_i, d_j)}{\max(d_i, d_j)} \right)^\alpha \leq C d_i^{N/2-1}.
\end{equation}

Hence, we have
\begin{align*}
\mathcal{K} &\leq C + C C_*^{3+N/2} + C \sum_j d_j^{-1+N/2} \|F\|_{Q_j} \\
&\leq C + C C_*^{3+N/2} + C \sum_j \left( \frac{h}{d_j} \right)^{1+\alpha-N/2} \tag{here we substitute \eqref{5.32}} \\
&+ C \sum_j d_j^{-1+N/2} \sum_{s,i} (h^{1+\alpha} \|F_i\|_{Q_i} + h^\alpha \|F\|_{1,Q_i}) d_i^{1-\alpha} \sum_j \left( \frac{\min(d_i, d_j)}{\max(d_i, d_j)} \right)^\alpha \\
&\leq C + C C_*^{3+N/2} + C \sum_{s,i} (h^{1+\alpha} \|F_i\|_{Q_i} + h^\alpha \|F\|_{1,Q_i}) d_i^{N/2-\alpha} \tag{here we use \eqref{5.33}} \\
&= C + C C_*^{3+N/2} + C \sum_{s,i} d_i^{1+N/2} \left( \frac{\|F_i\|_{Q_i}}{d_i} \left( \frac{h}{d_i} \right)^{1+\alpha} + d_i^{-1} \|F\|_{1,Q_i} \left( \frac{h}{d_i} \right)^\alpha \right) \\
&\leq C + C C_*^{3+N/2} + C d_i^{1+N/2} \left( \frac{\|F_i\|_{Q_i}}{d_i} + d_i^{-1} \|F\|_{1,Q_i} \right) \\
&+ C \sum_i d_i^{1+N/2} \left( \frac{\|F_i\|_{Q_i} + d_i^{-1} \|F\|_{1,Q_i}}{d_i} \right)^\alpha \\
&\leq C + C C_*^{3+N/2} + \frac{C \mathcal{K}}{C_*^{\alpha}}.
\end{align*}

By choosing $C_*$ to be large enough ($C_*$ is determined now), the term $\frac{C \mathcal{K}}{C_*^{\alpha}}$ will be absorbed by the left-hand side of the inequality above. In this case, the inequality above implies
\begin{equation}
\mathcal{K} \leq C.
\end{equation}

Substituting the last inequality into \eqref{5.19} yields
\begin{equation}
\|\partial_t F\|_{L^1(Q)} + \|t \partial_t F\|_{L^1(Q)} \leq C.
\end{equation}

\textit{Part II.} Second, we present estimates for $(t, x) \in (1, \infty) \times \Omega$. For $t > 1$, we differentiate \eqref{5.14} with respect to $t$ and integrate the resulting equation against $\partial_t \Gamma_h$. Then we get
\begin{align*}
\frac{d}{dt} \|\partial_t \Gamma_h(t, \cdot, x_0)\|_{L^2}^2 + \lambda_0 \|\partial_t \Gamma_h(t, \cdot, x_0)\|_{L^2}^2 &
\leq \frac{d}{dt} \|\partial_t \Gamma_h(t, \cdot, x_0)\|_{L^2}^2 + \langle \nabla \partial_t \Gamma_h(t, \cdot, x_0), \nabla \partial_t \Gamma_h(t, \cdot, x_0) \rangle \\
&= 0
\end{align*}
for \( t \geq 1 \), where \( \lambda_0 > 0 \) is the smallest eigenvalue of the operator \(-\Delta\). From the last inequality we derive the exponential decay of \( \partial_t \Gamma_h \) with respect to \( t \),

\[
\| \partial_t \Gamma_h(t, \cdot, x_0) \|_{L^2}^2 \leq e^{-\lambda_0(t-1)} \| \partial_t \Gamma_h(1, \cdot, x_0) \|_{L^2}^2 \leq C e^{-\lambda_0(t-1)},
\]

where the inequality \( \| \partial_t \Gamma_h(1, \cdot, x_0) \|_{L^2} \leq C \) can be proved by a simple energy estimate (omitted here). Similarly, we also have

\[
\| \partial_t \Gamma_h(t, \cdot, x_0) \|_{L^2}^2 + \| \partial_t \Gamma(t, \cdot, x_0) \|_{L^2}^2 \leq C e^{-\lambda_0(t-1)} \quad \text{for } t \geq 1.
\]

The estimate (5.35) and the last two inequalities imply (4.27)-(4.28) in the case \( h < h^* := 1/(4C_s) \). For \( h \geq h^* \), some basic energy estimates would yield

\[
\| \partial_t \Gamma_h(t, \cdot, x_0) \|_{L^2}^2 + \| \partial_t \Gamma_h(t, \cdot, x_0) \|_{L^2}^2 + \| \partial_t \Gamma(t, \cdot, x_0) \|_{L^2}^2 + \| \partial_t \Gamma(t, \cdot, x_0) \|_{L^2}^2 \\
\leq C e^{-\lambda_0 t}(\| \partial_t \Gamma_h(0, \cdot, x_0) \|_{L^2}^2 + \| \partial_t \Gamma(t, \cdot, x_0) \|_{L^2}^2 \\
+ \| \partial_t \Gamma(t, \cdot, x_0) \|_{L^2}^2 ) \\
= C e^{-\lambda_0 t}(\| \Delta_h P_h \tilde{\delta}_{xo} \|_{L^2}^2 + \| \Delta h P_h \tilde{\delta}_{xo} \|_{L^2}^2 + \| \Delta \tilde{\delta}_{xo} \|_{L^2}^2 + \| \Delta^2 \tilde{\delta}_{xo} \|_{L^2}^2 ) \\
\leq C e^{-\lambda_0 t}(h_s^{-4-N} + h_s^{-8-N})
\]

for arbitrary \( t > 0 \). This implies (4.27)-(4.28) in the case \( h \geq h^* \).

**Part III.** Finally, we note that (1.26) is a simple consequence of (3.6), (3.12), and (4.25), while (4.25) is a consequence of (1.26) and the following inequalities:

\[
\| \Gamma_h(t, \cdot, x_0) \|_{L^1(\Omega)} \leq \| \Gamma(t, \cdot, x_0) \|_{L^1(\Omega)} + \| F(t, \cdot, x_0) \|_{L^1(\Omega)} ,
\]

\[
\| t \partial_t \Gamma_h(t, \cdot, x_0) \|_{L^1(\Omega)} \leq \| t \partial_t \Gamma(t, \cdot, x_0) \|_{L^1(\Omega)} + \| t \partial_t F(t, \cdot, x_0) \|_{L^1(\Omega)} ,
\]

with

\[
\| F(t, \cdot, x_0) \|_{L^1(\Omega)} \leq \| F(0, \cdot, x_0) \|_{L^1(\Omega)} + \left\| \int_0^t \partial_s F(s, \cdot, x_0) \, ds \right\|_{L^1(\Omega)} \\
\leq \| P_h \tilde{\delta}_{xo} - \tilde{\delta}_{xo} \|_{L^1(\Omega)} + \| \partial_t F \|_{L^1(\Omega)} \leq C,
\]

\[
\| t \partial_t F(t, \cdot, x_0) \|_{L^1(\Omega)} \leq \left\| \int_0^t \left( s \partial_{ss} F(s, \cdot, x_0) + \partial_s F_h(s, \cdot, x_0) \right) \, ds \right\|_{L^1(\Omega)} \\
\leq \| t \partial_t F \|_{L^1(\Omega)} + \| \partial_t F \|_{L^1(\Omega)} \leq C,
\]

where we have used (4.27) in the last two inequalities, which was proved in Part I and Part II.

The proof of Lemma 4.4 is complete.

6. Conclusion

The analyticity and maximal \( L^p \)-regularity of finite element solutions of the heat equation are proved in general polygons and polyhedra, possibly nonconvex. The \( L^\infty \)-stability of the finite element parabolic projection has been reduced to the \( L^\infty \)-stability of the Ritz projection. Such \( L^\infty \)-stability of the Dirichlet Ritz projection is currently known in general polygons \([12]\) and convex polyhedra \([28]\), but still remains open in nonconvex polyhedra. The \( L^\infty \)-stability of the Neumann Ritz projection remains open in both nonconvex polygons and nonconvex polyhedra. This article focuses on the Lagrange finite element method. Extension of the results to other numerical methods, such as finite volume methods and discontinuous
Galerkin methods, are interesting and nontrivial. Such extension may need more precise \( W^{p,q} \)-approximation properties of local elliptic projectors onto finite element spaces (e.g., see \([13]\)).

**APPENDIX A: PROOF OF LEMMA 5.1**

In this subsection, we prove Lemma 5.1 which is used in the last section in proving Lemma 4.4. Before we prove Lemma 5.1 we present a local energy estimate for finite element solutions of parabolic equations based on the decomposition \( Q_j = [(0, d_j^2) \times \Omega_j] \cup [(d_j^2, 4d_j^2) \times D_j] \).

**Lemma A.1.** Suppose that \( \phi_h(t) \in S_h, t \in (0, T) \), satisfies
\[
(\partial_t \phi_h, \chi_h) + (\nabla \phi_h, \nabla \chi_h) = 0 \quad \text{for} \quad \chi_h \in S_h^0(\Omega_j'), \quad t \in (0, d_j^2),
\]
\[
(\partial_t \phi_h, \chi_h) + (\nabla \phi_h, \nabla \chi_h) = 0 \quad \text{for} \quad \chi_h \in S_h^0(D_j'), \quad t \in (d_j^2/4, 2d_j^2).
\]

Then we have
\[
\|\partial_t \phi_h\|_{L^2(Q_j')} + d_j^{-1}\|\nabla \phi_h\|_{L^2(Q_j')}
\leq (Ch^{1/2}d_j^{-1/2} + C\varepsilon^{-1}h^{-1}d_j + \varepsilon)\left(\|\partial_t \phi_h\|_{L^2(Q_j')} + d_j^{-1}\|\nabla \phi_h\|_{L^2(Q_j')}ight) + C\varepsilon^{-1}d_j^{-2}\|\phi_h\|_{L^2(Q_j')} + d_j^{-1}\|\phi_h(0)\|_{L^2(\Omega_j')} + \|\nabla \phi_h(0)\|_{L^2(\Omega_j')},
\]
where the constant \( C \) is independent of \( h, j \) and \( C_\varepsilon \).

**Proof of Lemma A.1** We shall present estimates in the two subdomains \( (0, d_j^2) \times \Omega_j \) and \((d_j^2, 4d_j^2) \times D_j \), separately.

First, we present estimates in \((0, d_j^2) \times \Omega_j\). To this end, we let \( \omega \) be a smooth cut-off function which equals 1 on \( \Omega_j \) and equals 0 outside \( \Omega_j' \), and let \( \bar{\omega} \) be a smooth cut-off function which equals 1 on \( \Omega_j' \) and equals 0 outside \( \Omega_j'' \), such that
\begin{enumerate}
  \item \( \text{dist}(\text{supp}(\omega) \cap \Omega, \Omega \setminus \Omega_j') \geq d_j/8 \geq 2h \) and \( \text{dist}(\text{supp}(\bar{\omega}) \cap \Omega, \Omega \setminus \Omega_j'') \geq d_j/8 \geq 2h \),
  \item \( |\partial^\alpha \omega| + |\partial^\alpha \bar{\omega}| \leq C_\alpha d_j^{-|\alpha|} \) for any multi-index \( \alpha \).
\end{enumerate}

By Property (P3) of Section 3.2 the function \( v_h := I_h(\bar{\omega} \phi_h) \in S_h^0(\Omega_j'') \) satisfies \( v_h = \phi_h \) on \( \Omega_j' \) and
\[
\|v_h\|_{L^2(\Omega)} \leq C\|\phi_h\|_{L^2(\Omega_j')},
\]
\[
\|\nabla v_h\|_{L^2(\Omega)} \leq C\|\nabla \phi_h\|_{L^2(\Omega_j')} + Cd_j^{-1}\|\phi_h\|_{L^2(\Omega_j')},
\]
\[
(\partial_t v_h, \chi_h) + (\nabla v_h, \nabla \chi_h) = 0 \quad \forall \chi_h \in S_h^0(\Omega_j') \quad \forall t \in (0, d_j^2).
\]

Property (P3) of Section 3.2 also implies that \( I_h(\omega^2 v_h) \in S_h^0(\Omega_j') \) such that
\[
\|\omega^2 v_h - I_h(\omega^2 v_h)\|_{L^2} + h\|\nabla (\omega^2 v_h - I_h(\omega^2 v_h))\|_{L^2} \leq Chd_j^{-1}\|v_h\|_{L^2}.
\]

Since \( \omega \) and \( \bar{\omega} \) are time-independent, it follows that
\[
\frac{1}{2} \frac{d}{dt}\|\omega v_h\|^2 + (\omega^2 \nabla v_h, \nabla v_h) = \left[ (\partial_t v_h, \omega^2 v_h) + (\nabla v_h, \nabla (\omega^2 v_h)) \right] - (2v_h \omega \nabla \omega, \nabla v_h) = \left[ (\partial_t v_h, \omega^2 v_h - I_h(\omega^2 v_h)) + (\nabla v_h, \nabla (\omega^2 v_h - I_h(\omega^2 v_h))) \right] - (2v_h \nabla \omega, \nabla v_h) \leq \left[ C\|\partial_t v_h\|_{L^2}\|v_h\|_{L^2}h^{-1} + C\|\nabla v_h\|_{L^2}\|v_h\|_{L^2}d_j^{-1} \right] + Cd_j^{-1}\|v_h\|_{L^2}\|\nabla v_h\|_{L^2} \leq C\|\partial_t v_h\|^2_{L^2} + \varepsilon^4\|\nabla v_h\|^2_{L^2} + Ce^{-4}\|v_h\|^2_{L^2}d_j^{-2} \quad \forall \varepsilon \in (0, 1).
By using \((A.2)-(A.3)\), integrating the last inequality from 0 to \(d_j^2\) yields
\[
\|\phi_h\|_{L^\infty(0,d_j^2;L^2(\Omega_j))} + \|\nabla \phi_h\|_{L^2(0,d_j^2;L^2(\Omega_j))} \leq C\|\phi_h(0)\|_{L^2(\Omega_j')} + C\|\partial_t \phi_h\|_{L^2(0,d_j^2;L^2(\Omega_j'))} h + 2\epsilon\|\nabla \phi_h\|_{L^2(0,d_j^2;L^2(\Omega_j'))} d_j^{-1}.
\]

Furthermore, we have
\[
\|\omega^2 \partial_t v_h\|_{L^2} = \frac{1}{2} \frac{d}{dt} (\omega^4 \nabla v_h, \nabla v_h) = (\partial_t v_h, \omega^4 \partial_t v_h) + (\nabla v_h, \nabla (\omega^4 \partial_t v_h)) - (4 \partial_t v_h \omega^3 \nabla \omega, \nabla v_h)
\]
\[
= (\partial_t v_h, \omega^4 \partial_t v_h - I_h (\omega^4 \partial_t v_h)) + (\nabla v_h, \nabla (\omega^4 \partial_t v_h - I_h (\omega^4 \partial_t v_h))) - (4 \partial_t v_h \omega^3 \nabla \omega, \nabla v_h)
\]
\[
\leq C\|\partial_t v_h\|_{L^2} h d_j^{-1} + C\|\nabla v_h\|_{L^2} \|\partial_t v_h\|_{L^2} d_j^{-1} + C\|\omega^2 \partial_t v_h\|_{L^2} \|\nabla v_h\|_{L^2} d_j^{-1}
\]
\[
\leq (Ch d_j^{-1} + \epsilon^2)\|\partial_t v_h\|_{L^2} + \epsilon^2 \|\omega^2 \partial_t v_h\|_{L^2} d_j^{-2} + C\epsilon^2 \|\nabla v_h\|_{L^2} d_j^{-2} \quad \forall \epsilon \in (0, 1/2),
\]
which reduces to
\[
\|\omega^2 \partial_t v_h\|_{L^2(0,d_j^2;L^2)} \leq (Ch d_j^{-1} + \epsilon^2)\|\partial_t v_h\|_{L^2(0,d_j^2;L^2)} + C\epsilon^2 \|\nabla v_h\|_{L^2(0,d_j^2;L^2)} d_j^{-2}
\]
\[
+ C\|\nabla v_h(0)\|_{L^2}.\]

By using \((A.2)-(A.3)\), the last inequality further implies
\[
\|\partial_t \phi_h\|_{L^2(0,d_j^2;L^2(\Omega_j))} \leq C(\|\nabla \phi_h(0)\|_{L^2(\Omega_j')} + d_j^{-1} \|\phi_h(0)\|_{L^2(\Omega_j')})
\]
\[
+ (Ch^{1/2} d_j^{-1/2} + \epsilon)\|\partial_t \phi_h\|_{L^2(0,d_j^2;L^2(\Omega_j'))} + C\epsilon^{-1}(\|\phi_h\|_{L^2(0,d_j^2;L^2(\Omega_j'))} d_j^{-2} + \|\nabla \phi_h\|_{L^2(0,d_j^2;L^2(\Omega_j'))} d_j^{-1})
\]
\[
\leq C(\|\nabla \phi_h(0)\|_{L^2(\Omega_j')} + d_j^{-1} \|\phi_h(0)\|_{L^2(\Omega_j')})
\]
\[
+ (Ch^{1/2} d_j^{-1/2} + \epsilon)\|\partial_t \phi_h\|_{L^2(0,d_j^2;L^2(\Omega_j'))} + C\epsilon^{-1}(\|\phi_h\|_{L^\infty(0,d_j^2;L^2(\Omega_j'))} d_j^{-1} + \|\nabla \phi_h\|_{L^2(0,d_j^2;L^2(\Omega_j'))} d_j^{-1}).
\]

With an obvious change of domains (replacing \(\Omega_j\) by \(\Omega_j'\) on the left-hand side of \((A.5)\) and replacing \(\Omega_j'\) by \(\Omega_j\) on the right-hand side of \((A.6)\)), the two estimates \((A.5)\) and \((A.6)\) imply
\[
\|\phi_h\|_{L^\infty(0,d_j^2;L^2(\Omega_j'))} + \|\nabla \phi_h\|_{L^2(0,d_j^2;L^2(\Omega_j'))} \leq \hat{C}(\|\nabla \phi_h(0)\|_{L^2(\Omega_j')} + d_j^{-1} \|\phi_h(0)\|_{L^2(\Omega_j')})
\]
\[
+ \hat{C}\|\nabla v_h\|_{L^2(0,d_j^2;L^2(\Omega_j'))} + \hat{C}\epsilon^{-2} \|\phi_h\|_{L^2(0,d_j^2;L^2(\Omega_j'))} d_j^{-1}
\]
\[
\quad + 2\hat{C}\epsilon^{-1} d_j^{-1}(\|\phi_h\|_{L^\infty(0,d_j^2;L^2(\Omega_j'))} + \|\nabla \phi_h\|_{L^2(0,d_j^2;L^2(\Omega_j'))}),
\]
where \(\hat{C} \geq 1\) is some positive constant and \(\epsilon \in (0, 1)\) can be arbitrary. Then \(2\hat{C}\epsilon^{-1} d_j^{-1} \times (A.7) + (A.8)\) yields (the last term in \((A.8)\) can be absorbed by left-hand
side of $2\hat{C}e^{-1}d_j^{-1} \times \text{(A.7)}$

\begin{equation}
(A.9) \quad \|\partial_t \phi_h\|_{L^2(0,d_j^2;L^2(\Omega_j))} + d_j^{-1}\|\nabla \phi_h\|_{L^2(0,d_j^2;L^2(\Omega_j))} \\
\leq (Ch^{1/2}d_j^{-1/2} + Ce^{-1}h^d_j^{-1} + \epsilon) \times (\|\partial_t \phi_h\|_{L^2(0,d_j^2;L^2(\Omega''_j))} + d_j^{-1}\|\nabla \phi_h\|_{L^2(0,d_j^2;L^2(\Omega''_j))}) \\
+ Ce^{-3}\|\phi_h\|_{L^2(0,d_j^2;L^2(\Omega''_j))}d_j^{-2} + Ce^{-1} \\
\times (\|\nabla \phi_h(0)\|_{L^2(\Omega''_j)} + d_j^{-1}\|\phi_h(0)\|_{L^2(\Omega''_j)}).
\end{equation}

Second, we present estimates in $(d_j^2, 4d_j^2) \times D_j$. We redefine $\omega(x,t) := \omega_1(x)\omega_2(t)$ and $\tilde{\omega}(x,t) := \tilde{\omega}_1(x)\tilde{\omega}_2(t)$ such that

1. $\omega_1 = 1$ in $D_j$ and $\omega_1 = 0$ outside $D_j'$, $\tilde{\omega}_1 = 1$ in $D_j'$ and $\tilde{\omega}_1 = 0$ outside $D_j''$;
2. $\text{dist}(\text{supp}(\omega_1) \cap \Omega, \Omega \setminus D_j') \geq d_j/4 \geq \kappa h$ and $\text{dist}(\text{supp}(\tilde{\omega}_1) \cap \Omega, \Omega \setminus D_j'') \geq d_j/4 \geq \kappa h$;
3. $\omega_2 = 1$ for $t \in (d_j^2, 4d_j^2)$ and $\omega_2 = 0$ for $t \in (0, d_j^2/2)$;
4. $\tilde{\omega}_2 = 1$ for $t \in (d_j^2, 4d_j^2)$ and $\tilde{\omega}_2 = 0$ for $t \in (0, d_j^2/8)$;
5. $|\partial^\alpha \omega_1| + |\partial^\alpha \tilde{\omega}_1| \leq Cd_j^{-|\alpha|}$ for any multi-index $\alpha$;
6. $|\partial_t^k \omega_2| + |\partial_t^k \tilde{\omega}_2| \leq Cd_j^{-2k}$ for any nonnegative integer $k$.

Then the function $v_h := I_h(\tilde{\omega} \phi_h) \in S_h^0(D_j')$ satisfies $v_h = \tilde{\omega}_2 \phi_h$ on $D_j'$ and

\begin{align}
(A.10) \quad & \|v_h\|_{L^2(\Omega)} \leq C\|\tilde{\omega}_2 \phi_h\|_{L^2(D_j')}, \\
(A.11) \quad & \|\nabla v_h\|_{L^2(\Omega)} \leq C\|\tilde{\omega}_2 \nabla \phi_h\|_{L^2(D_j')} + Cd_j^{-1}\|\tilde{\omega}_2 \phi_h\|_{L^2(D_j')}, \\
(A.12) \quad & (\partial_t v_h, \chi_h) + (\nabla v_h, \nabla \chi_h) = 0 \quad \forall \chi_h \in S_h^0(D_j') \quad \forall t \in (d_j^2/4, 4d_j^2).
\end{align}

According to (P3) of Section 3.2, the function $\chi_h = I_h(\omega^2 v_h) \in S_h^0(D_j')$ satisfies

$$\|\omega^2 v_h - \chi_h\|_{L^2} + h\|\nabla(\omega^2 v_h - \chi_h)\|_{L^2} \leq Chd_j^{-1}\|v_h\|_{L^2}.$$ 

Therefore, we have

$$\frac{1}{2} \frac{d}{dt} \|\omega v_h\|^2 + (\omega^2 \nabla v_h, \nabla v_h)$$

$$= \left[ (\partial_t v_h, \omega^2 v_h) + (\nabla v_h, \nabla(\omega^2 v_h)) \right] + (\partial_t \omega v_h, v_h) - (2v_h \omega \nabla \omega, \nabla v_h)$$

$$= \left[ (\partial_t v_h, \omega^2 v_h - \chi_h) + (\nabla v_h, \nabla(\omega^2 v_h - \chi_h)) \right] + (\omega \partial_t \omega v_h, v_h) - (2v_h \nabla \omega, \omega \nabla v_h)$$

$$\leq C\|\partial_t v_h\|_{L^2(\Omega)} \|v_h\|_{L^2(\Omega)}h d_j^{-1} + C\|\nabla v_h\|_{L^2(\Omega)} \|v_h\|_{L^2(\Omega)}d_j^{-1}$$

$$+ Cd_j^{-2}\|v_h\|^2_{L^2(\Omega)} + C\|v_h\|_{L^2(\Omega)} \|\omega \nabla v_h\|_{L^2(\Omega)}$$

$$\leq C\|\partial_t v_h\|^2_{L^2(\Omega)}h^2 + \epsilon^4\|\nabla v_h\|^2_{L^2(\Omega)} + \epsilon^4\|\omega \nabla v_h\|^2_{L^2(\Omega)} + C\epsilon^{-4}\|v_h\|^2_{L^2(\Omega)}d_j^{-2}$$

$$\forall \epsilon \in (0, 1/2).$$
Integrating the last inequality in time for \( t \in (d_j^2/2, 4d_j^2) \), we obtain

\[
(A.13) \quad \|\phi_h\|_{L^\infty([d_j^2/4, 4d_j^2]; L^2(D_j))} + \|\nabla \phi_h\|_{L^2([d_j^2/2, 4d_j^2]; L^2(D_j))} \\
\leq C\|\partial_t \phi_h\|_{L^2([d_j^2/2, 4d_j^2]; L^2(D_j))} + \epsilon^2 \|\nabla \phi_h\|_{L^2([d_j^2/2, 4d_j^2]; L^2(D_j))} \\
+ C\epsilon^{-2} \|\phi_h\|_{L^2([d_j^2/2, 4d_j^2]; L^2(D_j))}d_j^{-1}.
\]

Furthermore, we have

\[
\|\omega^2 \partial_t v_h\|^2_{L^2} + \frac{1}{2} \frac{d}{dt} (\omega^4 \nabla v_h, \nabla v_h) \\
= [(\partial_t v_h, \omega^2 \partial_t v_h - \eta_h) + (\nabla v_h, \nabla (\omega^2 \partial_t v_h - \eta_h))] \\
+ (2\omega^3 \partial_t \omega \nabla v_h, \nabla v_h) - (4\partial_t \omega \nabla \omega, \nabla v_h) \\
\leq [C\|\partial_t v_h\|_{L^2(\Omega)}d_j^{-1} + C\|\nabla v_h\|_{L^2(\Omega)}\|\partial_t v_h\|_{L^2(\Omega)}d_j^{-1} \\
+ C\|\nabla v_h\|^2_{L^2(\Omega)}d_j^{-2} + C\|\omega^2 \partial_t v_h\|_{L^2(\Omega)}\|\nabla v_h\|_{L^2(\Omega)}d_j^{-1} \\
\leq (Chd_j^{-1} + \epsilon)\|\partial_t v_h\|^2_{L^2(\Omega)} + \epsilon^2 \|\omega^2 \partial_t v_h\|^2_{L^2(\Omega)} + C\epsilon^{-2} \|\nabla v_h\|^2_{L^2(\Omega)}d_j^{-2}.
\]

which implies (by integrating the last inequality in time for \( t \in (d_j^2/2, 4d_j^2) \))

\[
\|\omega^2 \partial_t v_h\|^2_{L^2([d_j^2/2, 4d_j^2]; L^2(\Omega))} \leq (Chd_j^{-1} + \epsilon^2)\|\partial_t v_h\|^2_{L^2([d_j^2/2, 4d_j^2]; L^2(\Omega))} \\
+ C\epsilon^{-2} \|\nabla v_h\|^2_{L^2([d_j^2/2, 4d_j^2]; L^2(\Omega))}d_j^{-2}.
\]

By using (A.10) + (A.11), the last inequality further implies

\[
(A.14) \quad \|\partial_t \phi_h\|_{L^2([d_j^2/2, 4d_j^2]; L^2(D_j))} \\
\leq (Ch^{1/2}d_j^{-1/2} + \epsilon)\|\partial_t \phi_h\|_{L^2([d_j^2/2, 4d_j^2]; L^2(D_j))} \\
+ C\epsilon^{-1}(\|\phi_h\|_{L^\infty([d_j^2/2, 4d_j^2]; L^2(D_j))}d_j^{-2} + \|\nabla \phi_h\|_{L^2([d_j^2/2, 4d_j^2]; L^2(D_j))}d_j^{-1}) \\
\leq (Ch^{1/2}d_j^{-1/2} + \epsilon)\|\partial_t \phi_h\|_{L^2([d_j^2/2, 4d_j^2]; L^2(D_j))} \\
+ C\epsilon^{-1}(\|\phi_h\|_{L^\infty([d_j^2/2, 4d_j^2]; L^2(D_j))}d_j^{-1} + \|\nabla \phi_h\|_{L^2([d_j^2/2, 4d_j^2]; L^2(D_j))}d_j^{-1}).
\]

With an obvious change of domains, (A.13) and (A.14) imply

\[
(A.15) \quad \|\phi_h\|_{L^\infty([d_j^2/2, 4d_j^2]; L^2(D_j))} + \|\nabla \phi_h\|_{L^2([d_j^2/2, 4d_j^2]; L^2(D_j))} \\
\leq C\|\partial_t \phi_h\|_{L^2([d_j^2/2, 4d_j^2]; L^2(D_j))} + \epsilon^2 \|\nabla \phi_h\|_{L^2([d_j^2/2, 4d_j^2]; L^2(D_j))} \\
+ C\epsilon^{-2} \|\phi_h\|_{L^2([d_j^2/2, 4d_j^2]; L^2(D_j))}d_j^{-1}
\]

and

\[
(A.16) \quad \|\partial_t \phi_h\|_{L^2([d_j^2/2, 4d_j^2]; L^2(D_j))} \leq (Ch^{1/2}d_j^{-1/2} + \epsilon)\|\partial_t \phi_h\|_{L^2([d_j^2/2, 4d_j^2]; L^2(D_j))} \\
+ C\epsilon^{-1}(\|\phi_h\|_{L^\infty([d_j^2/2, 4d_j^2]; L^2(D_j))}d_j^{-1} + \|\nabla \phi_h\|_{L^2([d_j^2/2, 4d_j^2]; L^2(D_j))}d_j^{-1}).
\]
respectively. The last two inequalities further imply

\begin{align}
(A.17)
\|\partial_t \phi_h\|_{L^2(\Omega^0(\partial^2_d,4d^2_d;L^2(\partial_t D))} + d_j^{-1}\|\nabla \phi_h\|_{L^2(\partial^2_d,4d^2_d;L^2(\partial_t D))} \\
\leq (C h^{1/2}d_j^{-1/2} + C \varepsilon^{-1} h d_j^{-1} + \varepsilon)(\|\partial_t \phi_h\|_{L^2(\partial^2_d/4,4d^2_d;L^2(\partial_t D))} \\
+ d_j^{-1}\|\nabla \phi_h\|_{L^2(\partial^2_d/4,4d^2_d;L^2(\partial_t D))}) \\
+ C \varepsilon^{-3}\|\phi_h\|_{L^2(\partial^2_d/4,4d^2_d;L^2(\partial_t D))}d_j^{-2}.
\end{align}

Finally, combining (A.9) and (A.17) yields

\begin{align}
(A.18)
\|\partial_t \phi_h\|_{L^2(\Omega^0)} + d_j^{-1}\|\nabla \phi_h\|_{L^2(\Omega^0)} \\
\leq (C h^{1/2}d_j^{-1/2} + C \varepsilon^{-1} h d_j^{-1} + \varepsilon)(\|\partial_t \phi_h\|_{L^2(\Omega^0')} + d_j^{-1}\|\nabla \phi_h\|_{L^2(\Omega^0')}) \\
+ C \varepsilon^{-3}\|\phi_h\|_{L^2(\partial^2_d/4,4d^2_d;L^2(\partial_t D))}d_j^{-2}.
\end{align}

Replacing \(\Omega^0\) by \(\Omega_j^0\) and replacing \(Q''\) by \(Q_j'\) in the last inequality, we obtain (A.1) and complete the proof of Lemma A.11.

\begin{proof}[Proof of Lemma 5.1]
Let \(\widetilde{\omega}(t, x)\) be a smooth cut-off function which equals 1 in \(Q_j'\) and vanishes outside \(Q_j'\), and let \(\widetilde{\phi} = \widetilde{\omega}\phi\). Then \(\widetilde{\phi} = \phi\) in \(Q_j'\), which implies that

\begin{align*}
(\partial_t (\widetilde{\phi} - \phi_h), \chi_h) + (\nabla (\widetilde{\phi} - \phi_h), \nabla \chi_h) = 0 & \text{ for } \chi_h \in S^0_h(\Omega_j''), \ t \in (0, d_j^2), \\
(\partial_t (\widetilde{\phi} - \phi_h), \chi_h) + (\nabla (\widetilde{\phi} - \phi_h), \nabla \chi_h) = 0 & \text{ for } \chi_h \in S^0_h(D_j'), \ t \in (d_j^2/4, 4d_j^2).
\end{align*}

Let \(\widetilde{\phi}_h \in S_h\) be the solution of

\begin{align}
(A.19)
(\partial_t (\widetilde{\phi} - \widetilde{\phi}_h), \chi_h) + (\nabla (\widetilde{\phi} - \widetilde{\phi}_h), \nabla \chi_h) = 0 & \forall \chi_h \in S_h,
\end{align}

with \(\widetilde{\phi}_h(0) = \widetilde{\phi}(0) = 0\) so that

\begin{align}
(A.20)
(\partial_t (\widetilde{\phi}_h - \phi_h), \chi_h) + (\nabla (\widetilde{\phi}_h - \phi_h), \nabla \chi_h) = 0 & \text{ for } \chi_h \in S^0_h(\Omega_j''), \ t \in (0, d_j^2), \\
(A.21)
(\partial_t (\widetilde{\phi}_h - \phi_h), \chi_h) + (\nabla (\widetilde{\phi}_h - \phi_h), \nabla \chi_h) = 0 & \text{ for } \chi_h \in S^0_h(D_j'), \ t \in (d_j^2/4, 4d_j^2).
\end{align}

We shall estimate \(\widetilde{\phi} - \widetilde{\phi}_h\) and \(\widetilde{\phi}_h - \phi_h\) separately.
The basic global energy estimates of (A.19) are (substituting \( \chi_h = P_h \tilde{\phi} - \tilde{\phi}_h \) and \( \chi_h = \partial_t (P_h \tilde{\phi} - \tilde{\phi}_h) \), respectively)

\[
\|\nabla (\tilde{\phi} - \tilde{\phi}_h)\|^2_{L^2(\Omega)} + \|\tilde{\phi} - \tilde{\phi}_h\|^2_{L^\infty(0,T;L^2(\Omega))} \\
\leq C \|\partial_t (\tilde{\phi} - \tilde{\phi}_h)\|_{L^2(\Omega)} \|\tilde{\phi}\|_{L^2(\Omega)} + C \|\nabla \tilde{\phi}\|_{L^2(\Omega)}^2,
\]

\[
\|\partial_t (\tilde{\phi} - \tilde{\phi}_h)\|^2_{L^2(\Omega)} \leq C \|\partial_t \tilde{\phi}\|^2_{L^2(\Omega)} + C \|\nabla (\tilde{\phi} - \tilde{\phi}_h)\|_{L^2(\Omega)} \|\nabla \partial_t \tilde{\phi}\|_{L^2(\Omega)},
\]

which imply

\[
\|\partial_t (\tilde{\phi} - \tilde{\phi}_h)\|^2_{L^2(\Omega)} + d_j^{-2} \|\nabla \tilde{\phi} - \tilde{\phi}_h\|^2_{L^2(\Omega)} + d_j^{-2} \|\tilde{\phi} - \tilde{\phi}_h\|^2_{L^\infty(0,T;L^2(\Omega))} \\
\leq C d_j^{-2} \|\partial_t (\tilde{\phi} - \tilde{\phi}_h)\|_{L^2(\Omega)} \|\tilde{\phi}\|_{L^2(\Omega)} + C d_j^{-2} \|\nabla \tilde{\phi}\|_{L^2(\Omega)}^2, \\
+ C \|\partial_t \tilde{\phi}\|^2_{L^2(\Omega)} + C \|\nabla (\tilde{\phi} - \tilde{\phi}_h)\|_{L^2(\Omega)} \|\nabla \partial_t \tilde{\phi}\|_{L^2(\Omega)} \\
\leq \frac{1}{2} \|\partial_t (\tilde{\phi} - \tilde{\phi}_h)\|^2_{L^2(\Omega)} + C d_j^{-4} \|\tilde{\phi}\|_{L^2(\Omega)}^2 + C d_j^{-2} \|\nabla \tilde{\phi}\|_{L^2(\Omega)}^2, \\
+ C \|\partial_t \tilde{\phi}\|^2_{L^2(\Omega)} + \frac{1}{2} d_j^{-2} \|\nabla (\tilde{\phi} - \tilde{\phi}_h)\|^2_{L^2(\Omega)} + C d_j^2 \|\nabla \partial_t \tilde{\phi}\|_{L^2(\Omega)}^2.
\]

The first and fifth terms on the right-hand side above can be absorbed by the left-hand side, and the last inequality further reduces to

(A.22) \[
\|\partial_t (\tilde{\phi} - \tilde{\phi}_h)\|_{L^2(\Omega)} + d_j^{-1} \|\nabla (\tilde{\phi} - \tilde{\phi}_h)\|_{L^2(\Omega)} + d_j^{-1} \|\tilde{\phi} - \tilde{\phi}_h\|_{L^\infty(0,T;L^2(\Omega))} \\
\leq C d_j^{-2} \|\tilde{\phi}\|_{L^2(\Omega)} + C d_j^{-1} \|\nabla \tilde{\phi}\|_{L^2(\Omega)} + C \|\partial_t \tilde{\phi}\|_{L^2(\Omega)} + C d_j \|\nabla \partial_t \tilde{\phi}\|_{L^2(\Omega)} \\
\leq C d_j^{-2} \|\tilde{\phi}\|_{L^2(\Omega_j')} + C d_j^{-1} \|\nabla \tilde{\phi}\|_{L^2(\Omega_j')} + C \|\partial_t \tilde{\phi}\|_{L^2(\Omega_j')} + C d_j \|\nabla \partial_t \tilde{\phi}\|_{L^2(\Omega_j')}.
\]

By applying Lemma \([A.1]\) to \((A.20)-(A.21)\), we obtain

(A.23) \[
\|\partial_t (\tilde{\phi}_h - \phi_h)\|_{L^2(\Omega_j')} + d_j^{-1} \|\nabla (\tilde{\phi}_h - \phi_h)\|_{L^2(\Omega_j')} \\
\leq C \epsilon^{-1} \left( \|\nabla (\tilde{\phi}_h - \phi_h)(0)\|_{L^2(\Omega_j')} + d_j^{-1} \| (\tilde{\phi}_h - \phi_h)(0)\|_{L^2(\Omega_j')} \right) \\
+ C \epsilon^{-3} d_j^{-2} \|\tilde{\phi}_h - \phi_h\|_{L^2(\Omega_j')} \\
+ \left( C h^{1/2} d_j^{-1/2} + C \epsilon^{-1} h d_j^{-1} + \epsilon \right) \\
\times \left( \|\partial_t (\tilde{\phi}_h - \phi_h)\|_{L^2(\Omega_j')} + d_j^{-1} \|\nabla (\tilde{\phi}_h - \phi_h)\|_{L^2(\Omega_j')} \right) \\
= C \epsilon^{-1} \left( \|\nabla \phi_h(0)\|_{L^2(\Omega_j')} + d_j^{-1} \| \phi_h(0)\|_{L^2(\Omega_j')} \right) \\
+ C \epsilon^{-3} d_j^{-2} \|\tilde{\phi}_h - \phi_h\|_{L^2(\Omega_j')} \\
+ \left( C h^{1/2} d_j^{-1/2} + C \epsilon^{-1} h d_j^{-1} + \epsilon \right) \left( \|\partial_t (\tilde{\phi}_h - \phi_h)\|_{L^2(\Omega_j')} \right) \\
+ d_j^{-1} \|\nabla (\tilde{\phi}_h - \phi_h)\|_{L^2(\Omega_j')} .
\]
where we have used the identity $\tilde{\phi}_h(0) = 0$ in the last step. Splitting $\tilde{\phi}_h - \phi_h$ into $(\tilde{\phi} - \phi_h) + (\phi_h - \phi)$ in the right-hand side of the last inequality yields

\begin{align}
(A.24) \quad & \|\partial_t(\tilde{\phi}_h - \phi_h)\|_{L^2(Q_j)} + d_j^{-1}\|\nabla(\tilde{\phi}_h - \phi_h)\|_{L^2(Q_j)} \\
& \leq C\epsilon^{-1} \left( \|\nabla\phi_h(0)\|_{L^2(\Omega_j')} + d_j^{-1}\|\phi_h(0)\|_{L^2(\Omega_j')} \right) \\
& \quad + C\epsilon^{-3}d_j^{-2}\|\tilde{\phi} - \phi_h\|_{L^2(Q_j')} \\
& \quad + (Ch^{1/2}d_j^{-1/2} + C\epsilon^{-1}h\epsilon^{-3}d_j^{-1} + \epsilon)(\|\partial_t(\tilde{\phi} - \phi_h)\|_{L^2(Q_j')} + d_j^{-1}\|\nabla(\tilde{\phi} - \phi_h)\|_{L^2(Q_j')}) \\
& \quad + C\epsilon^{-3}d_j^{-2}\|\tilde{\phi}_h - \tilde{\phi}\|_{L^2(Q_j')} \\
& \quad + (Ch^{1/2}d_j^{-1/2} + C\epsilon^{-1}h\epsilon^{-3}d_j^{-1} + \epsilon)(\|\partial_t(\tilde{\phi}_h - \tilde{\phi})\|_{L^2(Q_j')} + d_j^{-1}\|\nabla(\tilde{\phi}_h - \tilde{\phi})\|_{L^2(Q_j')}) \\
& \leq C\epsilon^{-1} \left( \|\nabla\phi_h(0)\|_{L^2(\Omega_j')} + d_j^{-1}\|\phi_h(0)\|_{L^2(\Omega_j')} \right) + C\epsilon^{-3}d_j^{-2}\|\tilde{\phi} - \phi_h\|_{L^2(Q_j')} \\
& \quad + (Ch^{1/2}d_j^{-1/2} + C\epsilon^{-1}h\epsilon^{-3}d_j^{-1} + \epsilon)(\|\partial_t(\tilde{\phi} - \phi_h)\|_{L^2(Q_j')} + d_j^{-1}\|\nabla(\tilde{\phi} - \phi_h)\|_{L^2(Q_j')}) \\
& \quad + \left( Ch^{1/2}d_j^{-1/2} + C\epsilon^{-1}h\epsilon^{-3}d_j^{-1} + C\epsilon + C\epsilon^{-3} \right) d_j^{-2}\|\tilde{\phi}\|_{L^2(Q_j''')} \\
& \quad + \left( Ch^{1/2}d_j^{-1/2} + C\epsilon^{-1}h\epsilon^{-3}d_j^{-1} + C\epsilon + C\epsilon^{-3} \right) \\
& \times \left( d_j^{-1}\|\nabla\phi\|_{L^2(Q_j''')} + \|\partial_t\phi\|_{L^2(Q_j''')} + d_j\|\nabla\partial_t\phi\|_{L^2(Q_j''')} \right)
\end{align}

where we have used the identity $\tilde{\phi} = \phi$ on $Q_j'$ and \[A.22\] in the last step. Since

\[ (Ch^{1/2}d_j^{-1/2} + C\epsilon^{-1}h\epsilon^{-3}d_j^{-1} + C\epsilon + C\epsilon^{-3} ) \leq C\epsilon^{-3}, \]

the last inequality reduces to

\begin{align}
(A.25) \quad & \|\partial_t(\tilde{\phi}_h - \phi_h)\|_{L^2(Q_j)} + d_j^{-1}\|\nabla(\tilde{\phi}_h - \phi_h)\|_{L^2(Q_j)} \\
& \leq C\epsilon^{-1} \left( \|\nabla\phi_h(0)\|_{L^2(\Omega_j')} + d_j^{-1}\|\phi_h(0)\|_{L^2(\Omega_j')} \right) + C\epsilon^{-3}d_j^{-2}\|\tilde{\phi} - \phi_h\|_{L^2(Q_j')} \\
& \quad + (Ch^{1/2}d_j^{-1/2} + C\epsilon^{-1}h\epsilon^{-3}d_j^{-1} + \epsilon)(\|\partial_t(\tilde{\phi} - \phi_h)\|_{L^2(Q_j')} + d_j^{-1}\|\nabla(\tilde{\phi} - \phi_h)\|_{L^2(Q_j')}) \\
& \quad + C\epsilon^{-3}d_j^{-2}\|\tilde{\phi}\|_{L^2(Q_j''')} + d_j^{-1}\|\nabla\phi\|_{L^2(Q_j''')} + \|\partial_t\phi\|_{L^2(Q_j''')} \\
& \quad + d_j\|\nabla\partial_t\phi\|_{L^2(Q_j''')},
\end{align}
The estimates (A.22) and (A.25) imply
\[
\|\partial_i (\phi - \phi_h)\|_{L^2(Q_j)} + d_j^{-1} \|\nabla (\phi - \phi_h)\|_{L^2(Q_j)}
= \|\partial_i (\tilde{\phi} - \phi_h)\|_{L^2(Q_j)} + d_j^{-1} \|\nabla (\tilde{\phi} - \phi_h)\|_{L^2(Q_j)}
\leq \|\partial_i (\tilde{\phi}_h - \phi_h)\|_{L^2(Q_j)} + d_j^{-1} \|\nabla (\tilde{\phi}_h - \phi_h)\|_{L^2(Q_j)}
\]
(here we use triangle inequality)
\[
+ \|\partial_i (\tilde{\phi} - \phi_h)\|_{L^2(Q_j)} + d_j^{-1} \|\nabla (\tilde{\phi} - \phi_h)\|_{L^2(Q_j)}
\leq C \varepsilon^{-1} (\|\nabla \phi_h(0)\|_{L^2(\Omega''')} + d_j^{-1} \|\phi_h(0)\|_{L^2(\Omega''')}) + C \varepsilon^{-3} d_j^{-2} \|\phi - \phi_h\|_{L^2(\Omega''')}
+ (C h^{1/2} d_j^{-1/2} + C \varepsilon^{-1} h d_j^{-1} + \varepsilon) (\|\partial_i (\phi - \phi_h)\|_{L^2(\Omega''')} + d_j^{-1} \|\nabla (\phi - \phi_h)\|_{L^2(\Omega''')})
+ C \varepsilon^{-3} d_j^{-2} \|\phi\|_{L^2(\Omega''')} + d_j^{-1} \|\nabla \phi\|_{L^2(\Omega''')} + \|\partial_i \phi\|_{L^2(\Omega''')} + d_j \|\nabla \partial_i \phi\|_{L^2(\Omega''')}
\]
Replacing \(\phi\) by \(\phi - I_h \phi\), replacing \(\Omega''\) by \(\Omega\), and replacing \(Q''\) by \(Q\) in the last inequality, we obtain (5.2) and complete the proof of Lemma 5.1. \(\square\)

APPENDIX B: PROPERTY (P3) AND THE OPERATOR \(I_h\)

Let \(\Phi_i\) be the basis function of the finite element space \(S_h\) corresponding to the finite element nodes \(x_i \in \Omega, i = 1, \ldots, M\). In other words, we have \(\Phi_j(x_i) = \delta_{ij}\) (the Kronecker symbol). Let \(\tau_i\) denote the union of triangles (or tetrahedra in \(\mathbb{R}^3\)) whose closure contain the node \(x_i\). For any function \(v \in L^2(\Omega)\), we denote by \(P_h^{(i)} v\) the local \(L^2\) projection onto \(S_h(\tau_i)\) (the space of finite element functions defined on the region \(\tau_i\)). The operator \(I_h : L^2(\Omega) \to S_h\) is defined as (in the spirit of Clément’s interpolation operator, cf. [4])

\[
(I_h v)(x) = \sum_{i=1}^{M} (P_h^{(i)} v)(x_i)\Phi_i(x) \quad \text{for} \ x \in \Omega,
\]

which equals zero on the boundary \(\partial \Omega\) (as every \(\Phi_i\) equals zero on \(\partial \Omega\)).

Now we prove that the operator \(I_h\) defined in (B.1) satisfies property (P3) of Section 3. To this end, we let \(S_h'\) be the finite element space subject to the same mesh as \(S_h\), with the same order of finite elements, but not necessarily zero on the boundary \(\partial \Omega\). We denote by \(x_j', j = 1, \ldots, m\), the finite element nodes on the boundary \(\partial \Omega\), and we denote by \(\Phi_j'\) the basis function corresponding to the node \(x_j\). The notation \(\tau_j\) will denote the union of triangles (or tetrahedra in \(\mathbb{R}^3\)) whose closure contain \(x_j\). With these notations, the space \(S_h'\) is spanned by the basis functions \(\Phi_i, i = 1, \ldots, M\), and \(\Phi_j', j = 1, \ldots, m\). We define an auxiliary operator \(\widetilde{I}_h : H^1(\Omega) \to S_h'\) by setting

\[
(\widetilde{I}_h \phi)(x) = (I_h \phi)(x) + \sum_{j=1}^{m} (\widetilde{P}_h^{(j)} \phi)(x_j')\Phi_j'(x) \quad \text{for} \ x \in \Omega,
\]

where \(\widetilde{P}_h^{(j)} \phi\) is the \(L^2\) projection of \(\phi|_{\partial \Omega}\) (trace of \(\phi\) on the boundary) onto \(S_h(\partial \Omega \cap \tau_j)\) (the space of finite element functions on \(\partial \Omega \cap \tau_j\), a piece of the boundary). The definition (B.2) implies

\[
I_h \phi = \widetilde{I}_h \phi \quad \forall \phi \in H^1_0(\Omega).
\]
Hence, in order to prove property (P3)-(1), we only need to prove the corresponding error estimate for the operator $I_h$.

In fact, the definition (B.2) guarantees the following local stability:

$$
\|I_h \phi\|_{L^2(\tau'_j)} + h^{\frac{1}{2}}\|I_h \phi\|_{L^2(\partial \Omega \cap \tau'_j)} + h\|\nabla I_h \phi\|_{L^2(\tau'_j)} \leq C(\|\phi\|_{L^2(\tau'_j)} + h^{\frac{1}{2}}\|\phi\|_{L^2(\partial \Omega \cap \tau'_j)}),
$$

where $\tau'_j$ is the union of triangles (or tetrahedra in $\mathbb{R}^3$) whose closure intersect the closure of $\tau'_j$ (boundary triangle/tetrahedron), and $\tau_i$ is the union of triangles (or tetrahedra in $\mathbb{R}^3$) whose closure intersect the closure of $\tau_i$ (interior triangle/tetrahedron). Let $P_h'$ denote the $L^2$ projection from $L^2(\Omega)$ onto the finite element space $S_h'$. Then substituting $\phi = v - P_h'v$ into the two inequalities above yields

$$
\|v - I_h v\|_{L^2(\tau'_j)} + h^{\frac{1}{2}}\|v - I_h v\|_{L^2(\partial \Omega \cap \tau'_j)} + h\|\nabla (v - I_h v)\|_{L^2(\tau'_j)} \leq C(\|v - P_h'v\|_{L^2(\tau_i)} + h\|\nabla (v - P_h'v)\|_{L^2(\tau_i)}),
$$

and

$$
\|v - I_h v\|_{L^2(\tau_i)} + h\|\nabla (v - I_h v)\|_{L^2(\tau_i)} \leq C(\|v - P_h'v\|_{L^2(\tau_i)} + h\|\nabla (v - P_h'v)\|_{L^2(\tau_i)}).
$$

Summing up the two inequalities above for $i = 1, \ldots, M$ and $j = 1, \ldots, m$ yields

$$
\|v - I_h v\|_{L^2(\Omega)} + h^{\frac{1}{2}}\|v - I_h v\|_{L^2(\partial \Omega)} + h\|\nabla (v - I_h v)\|_{L^2(\Omega)} \leq C(\|v - P_h'v\|_{L^2(\Omega)} + h^{\frac{1}{2}}\|v - P_h'v\|_{L^2(\partial \Omega)} + h\|\nabla (v - P_h'v)\|_{L^2(\Omega)}).
$$

$$
\leq C(\|v - P_h'v\|_{L^2(\Omega)} + h^{\frac{1}{2}}\|v - P_h'v\|_{L^2(\partial \Omega)} + h\|\nabla (v - P_h'v)\|_{L^2(\Omega)}) + h\|\nabla (v - P_h'v)\|_{L^2(\Omega)}
$$

(\text{interpolation inequality})

$$
\leq C(\|v - P_h'v\|_{L^2(\Omega)} + h\|v - P_h'v\|_{H^1(\Omega)}).
$$

(Hölder’s inequality)

$$
\leq \begin{cases} 
Ch\|v\|_{H^1(\Omega)} & \text{if } v \in H^1(\Omega), \\
Ch^2\|v\|_{H^2(\Omega)} & \text{if } v \in H^2(\Omega),
\end{cases}
$$

where the last inequality is the basic estimate of the $L^2$ projection $P_h' : L^2(\Omega) \to S_h'$ (without imposing boundary condition). By the complex interpolation method, we have

$$
\|v - I_h v\|_{L^2(\Omega)} + h^{\frac{1}{2}}\|v - I_h v\|_{L^2(\partial \Omega)} + h\|\nabla (v - I_h v)\|_{L^2(\Omega)} \leq C h^{1+\alpha}\|v\|_{H^{1+\alpha}(\Omega)}.
$$

Hence, for $v \in H^{1+\alpha}(\Omega) \cap H_0^1(\Omega)$, we have $I_h v = \tilde{I}_h v = 0$ on $\partial \Omega$ and

$$
(B.4) \quad \|v - I_h v\|_{L^2(\Omega)} + h\|\nabla (v - I_h v)\|_{L^2(\Omega)} = \|v - \tilde{I}_h v\|_{L^2(\Omega)} + h^{\frac{1}{2}}\|v - \tilde{I}_h v\|_{L^2(\partial \Omega)} + h\|\nabla (v - \tilde{I}_h v)\|_{L^2(\Omega)} \leq C h^{1+\alpha}\|v\|_{H^{1+\alpha}(\Omega)}.
$$

This proves property (P3)-(1) in Section 3. The other properties in (P3) are simple consequences of the definition of the operator $I_h$. \qed
APPENDIX C: PROOF OF (2.15)

The proof of (2.15) requires some properties of the finite element space described in Section 3.2.

It suffices to prove that the solution \( w_h \in S_h \) of the finite element equation \( \Delta h w_h = f_h \) satisfies

\[
\|w_h\|_{L^\infty} \leq C\|f_h\|_{L^\infty}.
\]

To this end, we define \( w \in H^1_0(\Omega) \) as the solution of the following PDE problem:

\[
\left\{ \begin{array}{l}
\Delta w = f_h \quad \text{in } \Omega, \\
w = 0 \quad \text{on } \partial \Omega.
\end{array} \right.
\]

Then \( w_h \) is the Ritz projection of \( w \), and the following standard \( H^1 \)-norm error estimate holds for some \( \alpha \in (\frac{1}{2}, 1) \):

\[
\|I_h w - w_h\|_{H^1} \leq C\|I_h w - w\|_{H^1} \leq Ch^\alpha\|w\|_{H^{1+\alpha}} \leq Ch^\alpha\|f_h\|_{H^{-1+\alpha}},
\]

where the first inequality above is due to \( H^1 \)-stability of the Ritz projection, the second inequality due to (B.4), and the last inequality due to Lemma 4.2. Consequently, we have

\[
\|I_h w - w_h\|_{L^\infty} \leq Ch^{-\frac{\alpha}{2}}\|I_h w - w_h\|_{L^6} \quad \text{(inverse inequality)}
\]

\[
\leq Ch^{-\frac{1}{2}}\|I_h w - w_h\|_{H^1} \quad \text{(Sobolev embedding, } N = 2, 3)\)
\]

\[
\leq Ch^{\alpha - \frac{1}{2}}\|f_h\|_{H^{-1+\alpha}} \quad \text{(use (C.3))}
\]

\[
\leq Ch^{\alpha - \frac{1}{2}}\|f_h\|_{L^2} \quad \text{\( (L^2 \hookrightarrow H^{-1+\alpha})\)}
\]

\[
\leq Ch^{\alpha - \frac{1}{2}}\|f_h\|_{L^\infty},
\]

\[
\|w - I_h w\|_{L^\infty} \leq \|w - P_h w\|_{L^\infty} + \|P_h w - I_h w\|_{L^\infty} \quad \text{(triangle inequality)}
\]

\[
\leq Ch^{1+\alpha - \frac{\alpha}{2}}\|w\|_{C^{1+\alpha - \frac{\alpha}{2}}} + Ch^{\frac{\alpha}{2}}\|P_h w - I_h w\|_{L^2} \quad \text{(inverse inequality)}
\]

\[
\leq Ch^{1+\alpha - \frac{\alpha}{2}}\|w\|_{C^{1+\alpha - \frac{\alpha}{2}}} + Ch^{\frac{\alpha}{2}}\|w - I_h w\|_{L^2} \quad \text{\( (L^2\text{-stability of } P_h)\)}
\]

\[
\leq Ch^{1+\alpha - \frac{\alpha}{2}}\|w\|_{H^{1+\alpha}} + Ch^{1+\alpha - \frac{\alpha}{2}}\|w\|_{H^{1+\alpha}} \quad \text{(\( H^{1+\alpha} \hookrightarrow C^{1+\alpha - \frac{\alpha}{2}} \text{ and (B.4)}\))}
\]

\[
\leq Ch^{\alpha - \frac{1}{2}}\|f_h\|_{H^{-1+\alpha}} \quad \text{(use Lemma 4.2 and } N = 2, 3)\)
\]

\[
\leq Ch^{\alpha - \frac{1}{2}}\|f_h\|_{L^2} \quad \text{\( (L^2 \hookrightarrow H^{-1+\alpha} \text{ for } \alpha \in (\frac{1}{2}, 1))\)}
\]

\[
\leq Ch^{\alpha - \frac{1}{2}}\|f_h\|_{L^\infty}.
\]

\[
\|w - I_h w\|_{L^\infty} \leq Ch^{\alpha - \frac{1}{2}}\|f_h\|_{L^\infty}.
\]
Consequently, the triangle inequality implies

\[(C.6)\]

\[
\left\| w_h \right\|_{L^\infty} \leq \left\| w \right\|_{L^\infty} + \left\| w - I_h w \right\|_{L^\infty} + \left\| I_h w - w_h \right\|_{L^\infty} \\
\leq \left\| w \right\|_{L^\infty} + C h^{\alpha - \frac{1}{2}} \left\| f_h \right\|_{L^\infty} + C h^{\alpha - \frac{1}{2}} \left\| f_h \right\|_{L^\infty} \\
\leq C \left\| f_h \right\|_{H^{1+\alpha}} + C h^{\alpha - \frac{1}{2}} \left\| f_h \right\|_{L^\infty} + C h^{\alpha - \frac{1}{2}} \left\| f_h \right\|_{L^\infty} \\
\leq C \left\| f_h \right\|_{H^{1+\alpha}} + C h^{\alpha - \frac{1}{2}} \left\| f_h \right\|_{L^\infty} \\
\leq C \left\| f_h \right\|_{L^2} + C h^{\alpha - \frac{1}{2}} \left\| f_h \right\|_{L^\infty} \\
\leq C \left\| f_h \right\|_{L^\infty}.
\]

This proves \((C.1)\). The proof of \((2.15)\) is complete. \(\square\)

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