Uncertainty Relation and Probability

Numerical Illustration

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The uncertainty relation and the probability interpretation of quantum mechanics are intrinsically connected, as is evidenced by the evaluation of standard deviations. It is thus natural to ask if one can associate a very small uncertainty product of suitably sampled events with a very small probability. We have shown elsewhere that some examples of the evasion of the uncertainty relation noted in the past are in fact understood in this way. We here numerically illustrate that a very small uncertainty product is realized if one performs a suitable sampling of measured data that occur with a very small probability. We introduce a notion of cyclic measurements. It is also shown that our analysis is consistent with the Landau-Pollak-type uncertainty relation. It is suggested that the present analysis may help reconcile the contradicting views about the “standard quantum limit” in the detection of gravitational waves.

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§1. Introduction

The uncertainty relation of Heisenberg and an associated detailed analysis of measurement process have been subjects of main interest for many years. See, for example, Refs. 3–6) for the recent analyses of this basic issue. On the other hand, the formulation of the uncertainty relation in the manner of Kennard and Robertson, which is based only on the commutation relations and the positive metric in the Hilbert space, is straightforward. The uncertainty relation of Kennard evaluates the standard deviations of the coordinate and momentum for a given quantum state and thus it is exact, although no direct reference to measurement. In this paper, we study an interrelation between uncertainty and probability in quantum mechanics by taking the Kennard relation as a basis of the analysis.

Following Heisenberg, it is customary to take the uncertainty relation as a principle, namely, the uncertainty principle that defines the quantum theory at the deepest level. From this point of view, it is impossible to evade the uncertainty relation in the framework of quantum theory. However, several authors argued in the past that the evasion of the uncertainty relation to an arbitrary degree is possible. For example, Ballentine gave a simple example of the evasion in the diffraction process and Ozawa gave two simple gedanken experiments that exhibit the evasion of the uncertainty relation.

The uncertainty relation and the probability interpretation of quantum mechan-
ics are intrinsically intertwined, as is evidenced by the evaluation of the standard deviation. It may thus be natural to incorporate the notion of probability in the study of the uncertainty relation. In fact, we have recently analyzed the basic mechanism involved in the evasion of the uncertainty relation suggested by the above authors\cite{4,9,10} from the point of view of probability and uncertainty. We have clarified several characteristic features of the evasion of the uncertainty relation, and have shown that the evasion of the uncertainty relation noted by these authors takes place with a very small probability.\cite{11}

The sampling of partial events with preferred properties or a biased measurement of preferred events is important in our analysis. The expectation is that a suitable sampling of the events with preferred properties for an ensemble of similarly prepared states can give a very small uncertainty product $\tilde{\Delta}x \tilde{\Delta}p$, where $\tilde{\Delta}x$ and $\tilde{\Delta}p$ are the standard deviations evaluated for the suitably sampled events, although the probability of sampling such events is very small. Classically, this kind of analysis is straightforward. However, in quantum mechanics, where the notion of reduction plays an essential role, this analysis is more involved. If one measures the momentum in the preferred range, for example, the quantum state makes a transition to a new state and thus the original information on the coordinate is lost. This aspect is often described as follows: “measurement creates a quantum state”.

Two aspects of reduction are important in our analysis. In the measurement in quantum mechanics, it is natural to presume an ensemble of similarly prepared states. When one measures the momentum, for example, each measurement gives a definite value of the momentum but the repeated measurement of the momentum gives the distribution predicted by quantum mechanics. Similarly, the measurement of the coordinate, and the product of the standard deviations of the momentum and coordinate thus constructed satisfies the Kennard relation. From the point of view of the prepared state, one can assign a definite probability to each measured value of the momentum, for example. One may collect only those partial events that occur with a very small probability and form an uncertainty product. The uncertainty product may then turn out to be very small compared with the lower bound of the Kennard relation. From our point of view, the evasion of the uncertainty relation noted in Refs. 4), 9) and 10) is an attempt to give a physical meaning to this class of analysis.

Another aspect of reduction that plays an important role in our analysis is the creation of a new quantum state by measurement. If one measures a specific value of the coordinate with high accuracy, the initial state makes a transition to a new state. One may then imagine an immediately subsequent measurement of a specific momentum in the range characteristic of the initial state. By this method, one returns very close to the initial state with a net outcome of the measured values of the coordinate and momentum whose uncertainty product is much smaller than the lower bound of the Kennard relation.

From the above discussion, it is clear that we assume the standard interpretation of quantum mechanics. Our attempt is to see if one can find a new aspect in the interplay of uncertainty and probability in quantum mechanics. In the present paper, we present a numerical illustration of the analysis outlined above. As a possible
practical implication of our analysis, it is suggested that our analysis may help reconcile the contradicting views on the issue on the standard quantum limit in the detection of gravitational waves.\textsuperscript{12)}

§2. Uncertainty relation and probability

We start with a more quantitative analysis of the uncertainty relation and probability. Suppose that we have a suitable localized wave packet $\psi(t, x)$ defined in the one-dimensional space $-\frac{L}{2} \leq x \leq \frac{L}{2}$. We then evaluate the standard deviations of the coordinate $\Delta x$ and the momentum $\Delta p$ using the localized wave packet $\psi(t, x)$. We have the Kennard relation

$$\Delta x \Delta p \geq \frac{1}{2} \hbar, \quad (2.1)$$

which is exact. We take the Kennard relation as a basis of our analysis. To assign an operational meaning to the Kennard relation, we assume a large ensemble of similarly prepared systems. We then understand $\Delta x$, for example, as the standard deviation of the coordinate measured by an ideal position detector for an ensemble of states represented by $\psi(t, x)$. Similarly, we construct $\Delta p$, and the product of $\Delta x$ and $\Delta p$ thus constructed satisfies the Kennard relation. See, for example, Ref. 9).

To introduce the notion of probability, we expand the above state as

$$\psi(t, x) = \sum_{k=1}^{N} c_k \phi_k(t, x), \quad (2.2)$$

in terms of an orthonormal basis set $\{\phi_k(t, x)\}$ where each $\phi_k(t, x)$ has a support in $-\frac{L}{2} + (k-1)(L/N) \leq x \leq -\frac{L}{2} + k(L/N)$ with $k = 1, 2, ..., N$. By choosing large $N$, one may regard each $\phi_k(t, x)$ as an approximate eigenstate of the coordinate. We now repeat the measurement of the standard deviation for the state $\psi(t, x)$, but with $N$ small coordinate detectors (of size $L/N$) placed at the positions of each state $\phi_k(t, x)$. The coordinate detector is triggered only when the particle arrives at the detector. If one collects all the data measured by any of the detectors, one recovers the original $\Delta x$. We assign a unit probability to this sampling of the data since we have the same number of measured data as the number of similarly prepared states.

On the other hand, if one collects only the data measured by the specific detector corresponding to $\phi_{k_0}(t, x)$, one obtains the standard deviation

$$\tilde{\Delta} x \sim \frac{1}{N} \Delta x, \quad (2.3)$$

which is evaluated using the state $\phi_{k_0}(t, x)$ for a sufficiently large $N$. The quantum mechanical probability for the occurrence of these events is

$$|c_{k_0}|^2 \sim \frac{1}{N}, \quad (2.4)$$

if one normalizes the state $\psi(t, x)$ by $\int_{-L/2}^{L/2} |\psi(t, x)|^2 dx = \sum_k |c_k|^2 = 1$. We thus assign the notion of probability to each data set. From this definition, one sees that
our probability is a relative probability rather than an absolute probability. We can consider a similar construction for the momentum measurement of the state $\psi(t,x)$.

If one considers the case where all the momentum measurements are accepted but only the coordinate measured by the specific detector corresponding to $\phi_{k_0}(t,x)$ is accepted for the prepared state $\psi(t,x)$, one has an analogue of the Kennard relation

$$\Delta p \Delta x \sim \frac{1}{N} \Delta x \Delta p \sim \frac{1}{N} \hbar \ll \hbar.$$  \hspace{1cm} \text{(2.5)}

The quantum mechanical probability for this sampling of events for the ensemble of states represented by $\psi(t,x)$ is given by Eq. (2.4), which is very small.

It is important to realize that the above uncertainty product (2.5) is also a natural product when one measures only the coordinate by the above specific detector but performs no measurement of the momentum for the given initial state $\psi(t,x)$. This is the typical situation of the partial (i.e., only the coordinate or momentum is directly measured) or indirect (i.e., either the momentum or coordinate distribution is theoretically guessed) measurement. If one knows the prepared initial state, one may guess the uncertainty in the momentum as the standard deviation as in Eq. (2.5), without a direct measurement of the momentum.

It is shown in the Appendix that a small detector limit in the analysis of the evasion of the uncertainty relation in the diffraction process discussed by Ballentine,\textsuperscript{9)} which is based on a partial measurement, precisely corresponds to Eqs. (2.4) and (2.5). It is also shown in the Appendix that one of the gedanken experiments of Ozawa (see §9 in Ref. 10)), which evades the uncertainty relation in the form $\eta(p)\epsilon(x) \ll \hbar$ with the measurement error $\epsilon(x)$ and the disturbance $\eta(p)$, is described by the expansion (2.3) and the probability (2.4). The gedanken experiment of Ozawa is also based on a partial measurement. These facts suggest that one might call Eqs. (2.4) and (2.5) as “an evasion of the uncertainty relation to an arbitrary degree with a very small probability”, although we operate in the framework of standard quantum mechanics and thus do not evade the standard Kennard relation.

As for the interpretation of Eq. (2.5) as a result of the partial measurement of the prepared state $\psi(t,x)$ by a specific coordinate detector, one may notice that, once the state is reduced to $\phi_{k_0}(t,x)$, the standard deviations of coordinate and momentum evaluated for $\phi_{k_0}(t,x)$ precisely satisfy the ordinary Kennard relation. One may thus ask what is the use of Eq. (2.5). As an answer to this question, we propose a specific subsequent measurement of the momentum by expanding $\phi_{k_0}(t,x)$ in the form

$$\phi_{k_0}(t,x) = \sum_l a_{k_0,l} \varphi_l(t,x),$$ \hspace{1cm} \text{(2.6)}

where an orthonormal set $\{\varphi_l(t,x)\}$ consists of localized wave packets (approximate momentum eigenstates) at the original interval $-L/2 \leq x \leq L/2$.

Our next gedanken experiment is to collect only the data corresponding to the momentum belonging to a specific state $\varphi_{l_0}(t,x)$ in Eq. (2.6) in the measurement of the reduced state $\phi_{k_0}(t,x)$, which is performed immediately after the measurement of initial $\psi(t,x)$ by the above specific coordinate detector. The above specific coordinate
measurement may now be regarded as a preparation of the state \( \phi_{k_0}(t, x) \), and thus the present momentum measurement is also a partial measurement. We choose the state \( \varphi_{l_0}(t, x) \), which is close to the starting state \( \psi(t, x) \); it will be shown later that this is possible by choosing the starting state \( \psi(t, x) \) suitably. In this sampling of the data of the momentum measurement, the standard deviation of the momentum \( \tilde{\Delta}p \), which is actually evaluated using the state \( \varphi_{l_0}(t, x) \), is given by

\[
\tilde{\Delta}p \sim \Delta p, \tag{2.7}
\]

where \( \Delta p \) is the standard deviation for the state \( \psi(t, x) \) in Eq. (2.1). The uncertainty product of the standard deviation of coordinate in the preparation process of \( \phi_{k_0}(t, x) \) and the standard deviation of momentum in the immediately subsequent measurement of the momentum corresponding to the state \( \varphi_{l_0}(t, x) \) is then given by

\[
\tilde{\Delta}x \tilde{\Delta}p \sim \frac{1}{N} \Delta x \Delta p \sim \frac{\hbar}{N} \ll \hbar. \tag{2.8}
\]

The above specific measurement (or sampling) of momentum creates the state \( \varphi_{l_0}(t, x) \), and the probability of finding \( \varphi_{l_0}(t, x) \) in the state \( \phi_{k_0}(t, x) \) in Eq. (2.6) is

\[
|a_{k_0,l_0}|^2 \sim \frac{1}{N}. \tag{2.9}
\]

The net outcome of this approximate “cyclic measurements” \( \psi(t, x) \to \phi_{k_0}(t, x) \to \varphi_{l_0}(t, x) \) with \( \varphi_{l_0}(t, x) \sim \psi(t, x) \) is Eq. (2.8), although such a probability is very small; the intrinsic quantum probability for the occurrence of Eq. (2.8) is \( \sim 1/N \) as is seen in Eq. (2.9), but if one recalls that one started with an ensemble of states represented by \( \psi(t, x) \), the probability to arrive at the final state \( \varphi_{l_0}(t, x) \) by two steps is \( \sim 1/N^2 \).

Clearly, this “cyclic measurements” differs from the “simultaneous measurements” of the coordinate and momentum for the state \( \psi(t, x) \), but one can extract the information on the coordinate and momentum, that gives a very small uncertainty product in Eq. (2.8) by restoring the state \( \psi(t, x) \) approximately to its original form.

Our suggestion is that Eqs. (2.8) and (2.9) have some bearing on the analysis of the “standard quantum limit” in the detection of gravitational waves. The basic issue in the detection of gravitational waves is the accurate measurement of the coordinate and the control of the subsequent time development of the system. This time development of the system is controlled by the fluctuation in the momentum after the coordinate measurement. We further comment on this issue in §5.

2.1. Comparison with the Landau-Pollak-type uncertainty relation

We here show that our analysis is consistent with the Landau-Pollak-type uncertainty relation that states that

\[
\langle \eta | E | \eta \rangle + \langle \eta | P | \eta \rangle \leq 1 + ||EP|| \tag{2.10}
\]

for two projection operators, \( E \) and \( P \), and any normalized state, \( | \eta \rangle \). The Landau-Pollak type relation also emphasizes the probability aspect of the uncertainty rela-
tion. If one chooses
\[ E = \int_{x_0 - \frac{1}{2} \Delta x}^{x_0 + \frac{1}{2} \Delta x} dx |x\rangle \langle x|, \quad P = \int_{p_0 - \frac{1}{2} \Delta p}^{p_0 + \frac{1}{2} \Delta p} \frac{dp}{2\pi\hbar} |p\rangle \langle p|, \quad (2.11) \]
one has
\[ ||EP||^2 = ||EPE|| \leq \text{Tr}(EPE) = \text{Tr}(PEP) \quad (2.12) \]
and
\[ \text{Tr}(EPE) = \int_{x_0 - \frac{1}{2} \Delta x}^{x_0 + \frac{1}{2} \Delta x} dx \int_{p_0 - \frac{1}{2} \Delta p}^{p_0 + \frac{1}{2} \Delta p} \frac{dp}{2\pi\hbar} \int_{x_0 - \frac{1}{2} \Delta x}^{x_0 + \frac{1}{2} \Delta x} dx \langle x'|x\rangle \langle x|p|p'\rangle \]
\[ = \int_{x_0 - \frac{1}{2} \Delta x}^{x_0 + \frac{1}{2} \Delta x} dx \int_{p_0 - \frac{1}{2} \Delta p}^{p_0 + \frac{1}{2} \Delta p} \frac{dp}{2\pi\hbar} \langle x|p\rangle \langle p|x\rangle \]
\[ = \int_{x_0 - \frac{1}{2} \Delta x}^{x_0 + \frac{1}{2} \Delta x} dx \int_{p_0 - \frac{1}{2} \Delta p}^{p_0 + \frac{1}{2} \Delta p} \frac{dp}{2\pi\hbar} e^{ipx/\hbar} e^{-ipx/\hbar} \]
\[ = \frac{\delta x \delta p}{2\pi\hbar} \quad (2.13) \]
The inequality (2.10) implies that either \(|\eta|E|\eta\rangle\) or \(|\eta|P|\eta\rangle\) (or both) is forced to be significantly smaller than unity when
\[ \frac{\delta x \delta p}{2\pi\hbar} \ll 1. \quad (2.14) \]

From this point of view, Eqs. (2.4) and (2.5) in our analysis are regarded to correspond to the choice of a specific wave packet \(\psi(x) = \langle x|\psi\rangle = \int_{p_0 - \frac{1}{2} \Delta p}^{p_0 + \frac{1}{2} \Delta p} \frac{dp}{2\pi\hbar} \langle x|p\rangle \langle p|\psi\rangle = \int_{p_0 - \frac{1}{2} \Delta p}^{p_0 + \frac{1}{2} \Delta p} \frac{dp}{2\pi\hbar} e^{ipx/\hbar} \langle p|\psi\rangle\) with \(P|\psi\rangle = |\psi\rangle\) and \(\langle \psi|P|\psi\rangle = \langle \psi|\psi\rangle = 1\), namely, \(P = \int_{p_0 - \frac{1}{2} \Delta p}^{p_0 + \frac{1}{2} \Delta p} \frac{dp}{2\pi\hbar} |p\rangle \langle p|\). Then
\[ \langle \psi|E|\psi\rangle = \langle \psi|PEP|\psi\rangle \leq \||PEP|| \leq \text{Tr}(PEP) \simeq \frac{\Delta x \Delta p}{2\pi\hbar}, \quad (2.15) \]
and the small probability \(\langle \psi|E|\psi\rangle\) with \(E = \int_{x_0 - \frac{1}{2} \Delta x}^{x_0 + \frac{1}{2} \Delta x} dx |x\rangle \langle x|\) corresponds to Eq. (2.4).

This inequality (2.15) is more stringent than the weak version of the Landau-Poljak-type uncertainty relation (2.10) formulated by Miyadera and Imai,\(^{13}\) which contains the square root of Eq. (2.14) as the upper bound.

Similarly, Eqs. (2.8) and (2.9) are regarded to correspond to the choice of the specific state \(\langle \phi|E|\phi\rangle = \langle \phi|\phi\rangle = 1\) with \(E = \int_{x_0 - \frac{1}{2} \Delta x}^{x_0 + \frac{1}{2} \Delta x} dx |x\rangle \langle x|\) and
\[ \langle \phi|P|\phi\rangle = \langle \phi|EPE|\phi\rangle \leq \||EPE|| \leq \text{Tr}(EPE) \simeq \frac{\Delta x \Delta p}{2\pi\hbar} \quad (2.16) \]
for \( P = \int_{p_0 - \frac{1}{2} \Delta p}^{p_0 + \frac{1}{2} \Delta p} dp \Delta \Phi(p)^2 \). The left-hand side \( \langle \phi | P | \phi \rangle \) of this inequality gives the small probability corresponding to Eq. (2.9) when the upper bound in Eq. (2.16) is small. See also Eqs. (3.31) and (3.32) in §3.

In reality, the actual spreads of the coordinate and momentum in the projection operators in Eq. (2.11) are larger than the standard deviations to satisfy the conditions such as \( P | \psi \rangle = | \psi \rangle \) for a given \( | \psi \rangle \), and thus the precise upper bound is expected to be larger than the values in Eqs. (2.15) and (2.16) by some finite factors. These inequalities (2.15) and (2.16) are useful when the upper bound is significantly smaller than unity.

§3. Procedure of the numerical calculation

In this section, we describe the procedure of the numerical calculation, and the detailed numerical evaluation itself is presented in §4.

For the numerical illustration of a very small uncertainty product for a suitably sampled date set, we consider the simplest Schrödinger equation

\[
i \hbar \frac{\partial}{\partial t} \psi(x, t) = H \psi(x, t)
\]  

(3.1)

with

\[
H = \frac{\hat{p}^2}{2m} = -\frac{\hbar^2}{2m} \frac{\partial^2}{\partial x^2}
\]  

(3.2)

in a one-dimensional box with a size \( L \) (\( 0 \leq x \leq L \)) and with the periodic boundary condition. Then the basic solution is

\[
\psi_n(x, t) = \frac{1}{\sqrt{L}} \exp \left[ i \frac{p_n x}{\hbar} - i \frac{p_n^2}{2m \hbar} t \right],
\]  

(3.3)

with \( p_n = 2\pi \hbar n/L, \quad n = 0, \pm 1, \pm 2, \ldots \), but the pure plane wave, which is an eigenstate of momentum, causes complications in the analysis of the standard form of the Kennard relation since it leads to \( \Delta p \Delta x \geq 0 \). To ensure the standard Kennard relation, we exploit the fact that any free particle created in the laboratory is localized in space. The readers are asked to refer to Ref. 14) for the technical details of the procedure used in the present study. We thus consider wave packets, which are actually the superposition of two plane wave solutions, given as\(^{14}\)

\[
\psi_{n,k}(x, t) \equiv \exp \left[ i \frac{p_n x}{\hbar} - i \frac{p_n^2}{2m \hbar} t \right] \times \frac{2i}{\sqrt{2}L} \exp \left[ -i \frac{p_k^2}{2m \hbar} t \right] \sin \left( \frac{p_k}{\hbar} (x - (p_n/m)t) \right),
\]  

(3.4)

defined at the interval \( 0 \leq x \leq L \) at \( t = 0 \), where

\[
p_n \equiv \frac{\pi \hbar}{L} n,
\]  

(3.5)
with integer \( n \). This construction, when observed at \( t = 0 \), is analogous to the Bloch wave with the Bloch momentum \( p_n \) and a complete set of sine functions at the interval \( 0 \leq x \leq L \) if one considers all positive integers \( k \): To be precise, we have periodic wave packets at the extended interval \(-L \leq x \leq L \) due to the presence of periodic (even \( k \)) and anti-periodic (odd \( k \)) waves at the interval \( 0 \leq x \leq L \), but we use only half of them defined at the interval \( 0 \leq x \leq L \) at \( t = 0 \). This construction, which is analogous to the Bloch wave, allows us to introduce zero in the wave function (i.e., locality) to ensure an ordinary Kennard relation and at the same time to retain the notion of momentum related to the plane wave.

Both of Eqs. (3.3) and (3.4) satisfy the Schrödinger equation (3.1), but the difference is that the wave packet in Eq. (3.4) is actually moving with a velocity \( \tilde{p}_n/m \).

Any free particle with an initial momentum \( \langle p \rangle = \tilde{p}_n \) localized in the subdomain of \([0, L] \) at \( t = 0 \) is expanded as

\[
\psi(x, t) = \sum_{k=1}^{n} c_k \psi_{\tilde{n}, k}(x, t),
\]

where \( \psi_{\tilde{n}, k}(x, t) \) stands for the wave packet in Eq. (3.4) with \( p_n \) replaced by \( \tilde{p}_n \), and for a general \( \tilde{p}_n \),

\[
\psi(x + 2L, t) = \exp \left[ i \frac{2\tilde{p}_n L}{\hbar} \right] \psi(x, t),
\]

which is a Bloch-like periodicity condition. Equation (3.6) is written as

\[
\psi(x, t) = \exp \left[ i \frac{\tilde{p}_n x}{\hbar} - i \frac{\tilde{p}_n^2}{2m\hbar} t \right] \phi \left( x - (\tilde{p}_n/m)t, t \right),
\]

where \( \phi(x, t) \) formally corresponds to the solution of a free particle confined in a deep potential well with a width \( 0 \leq x \leq L \), expressed as

\[
\phi(x, t) = \sum_{k=1}^{n} c_k \frac{2i}{\sqrt{2L}} \exp \left[ -i \frac{\tilde{p}_n^2}{2m\hbar} t \right] \sin \left( \frac{k\pi}{L} x \right).
\]

In our case, however, the deep potential well is moving with a velocity \( (\tilde{p}_n/m) \). Not only each wave in Eq. (3.4) but also any superposition of the waves such as those in Eq. (3.6) satisfies the condition on the circle \( S^1 \) with a circumference \( 2L \) (which is a natural domain for the periodic boundary condition) given as

\[
\min_{x \in S^1} |\psi(x, t)|^2 = 0
\]

for any \( t \), namely, at \( x = (\tilde{p}_n/m)t \) and \( x = L + (\tilde{p}_n/m)t \) up to a multiple of \( 2L \). Equation (3.10) is the locality requirement in our formulation. One can thus define the Kennard relation

\[
\Delta p \Delta x \geq \frac{\hbar}{2}
\]

\(^{14}\) This is consistent since the probability flow at the points \( x = (p_n/m)t \) and \( x = L + (p_n/m)t \) up to a multiple of \( 2L \) is always zero for any time \( t \).
where the integration domain for evaluating $\Delta p$ and $\Delta x$ is taken to be $((p_n/m)t, L + (p_n/m)t)$. This construction may appear to be a technical detail, but it is essential for a reliable analysis of the magnitude of the uncertainty product in connection with the Kennard relation.

For the elementary solution $\psi_{n,k}(x, t)$ in Eq. (3.4) we have

\[
\langle p \rangle = \int_{(p_n/m)t}^{L+(p_n/m)t} \psi_{n,k}^*(x, t) \left( \frac{\hbar}{i} \frac{\partial}{\partial x} \right) \psi_{n,k}(x, t) dx = p_n,
\]

\[
\langle p^2 \rangle = \int_{(p_n/m)t}^{L+(p_n/m)t} \psi_{n,k}^*(x, t) \left( \frac{\hbar}{i} \frac{\partial}{\partial x} \right)^2 \psi_{n,k}(x, t) dx = \frac{1}{2} [(p_n + p_k)^2 + (p_n - p_k)^2],
\]

\[
\Delta p = \sqrt{\langle p^2 \rangle - \langle p \rangle^2} = k \frac{\pi \hbar}{L},
\]

and

\[
\langle x \rangle = \frac{2}{L} \int_{(p_n/m)t}^{L+(p_n/m)t} x \sin^2 \left( k \frac{\pi}{L} [x - (p_n/m)t] \right) dx = \frac{L}{2} + \frac{p_n}{m} t,
\]

\[
\langle x^2 \rangle = \frac{2}{L} \int_{(p_n/m)t}^{L+(p_n/m)t} x^2 \sin^2 \left( k \frac{\pi}{L} [x - (p_n/m)t] \right) dx = \frac{L^2}{3} - \frac{2L^2}{(2\pi k)^2} + 2 \left( \frac{L}{2} \right) \left( \frac{p_n}{m} t \right) + \left( \frac{p_n}{m} t \right)^2,
\]

\[
\Delta x = \frac{L}{2\sqrt{3}} \sqrt{1 - \frac{24}{(2\pi k)^2}}.
\]

Thus,

\[
\Delta x \Delta p = \frac{\pi \hbar}{\sqrt{3}} \sqrt{k^2 - \frac{24}{(2\pi)^2}}.
\]

The choice $k = 1$ gives the minimum uncertainty state in our construction, and we have

\[
\Delta x \Delta p = \frac{\pi \hbar}{2\sqrt{3}} \sqrt{1 - \frac{24}{(2\pi)^2}} > \frac{\hbar}{2}.
\]

The numerical value of the uncertainty product $\Delta x \Delta p$ in Eq. (3.15) is close to the lower bound $\frac{\hbar}{2}$.

We thus choose our initial state to analyze the uncertainty relation as

\[
\psi_{n,1}(x, t) = \frac{2i}{\sqrt{2L}} \exp \left[ i \frac{p_n x}{\hbar} - i \frac{p_n^2 + p_k^2}{2m \hbar} t \right] \times \sin \left( \frac{\pi}{L} [x - (p_n/m)t] \right).
\]
To perform a numerical analysis, we define the following dimensionless quantities:

\[ \bar{x} = \frac{x}{L}, \quad 0 \leq \bar{x} \leq 1, \]
\[ \bar{p}_n = \frac{\pi \hbar n}{L} = \pi n, \]
\[ \lambda = \lambda_c / L = \left( \frac{\hbar}{mc} \right) / L, \]
\[ T = ct / L. \]  
(3.17)

Then the above wave packet (3.16) is written as

\[ \psi_{n,1}(\bar{x}, T) = \frac{2i}{\sqrt{2}} \exp \left[ i\bar{p}_n \bar{x} - i\frac{\bar{p}_n^2 + \bar{p}_2^2}{2} \lambda T \right] \times \sin \left( \pi [\bar{x} - \bar{p}_n \lambda T] \right), \]  
(3.18)

and the standard Kennard relation is given by

\[ \Delta \bar{x} \Delta \bar{p} \geq \frac{1}{2}. \]  
(3.19)

We now describe 4 steps in our numerical analysis of the measurement process:

For notational simplicity, we choose the time of our measurements to be \( T = 0 \).

(i) We start with the normalized wave packet (3.18) that satisfies the standard Kennard relation (3.19). We accept all the measured events in the evaluation of the standard deviations in Eq. (3.19). This sampling of events takes place with a unit probability (by our definition of probability) for an ensemble of similarly prepared states represented by the wave packet \( \psi_{n,1}(\bar{x}, 0) \).

(ii) Next suppose to sample only those events measured by the specific position detector, whose size \( a \) is much smaller than the size of the wave packet (and also the size of the box) \( L \), for an ensemble of similarly prepared states represented by the above wave packet \( \psi_{n,1}(\bar{x}, 0) \). Namely,

\[ N \equiv \frac{L}{a} \gg 1, \]  
(3.20)

and we choose \( N \) to be an integer.

We introduce a set of normalized step functions \( \{ u_l(\bar{x}) \} \) using

\[ u_l(\bar{x}) = \sqrt{N}, \quad (l - 1)/N \leq \bar{x} \leq l/N \]  
(3.21)

and \( u_l(\bar{x}) = 0 \) otherwise, for \( l = 1, 2, \ldots, N \). One may then note that the original wave packet in Eq. (3.18) is written as

\[ \psi_{n,1}(\bar{x}, 0) = \left[ \frac{1}{\sqrt{N}} \sum_{l=1}^{N} u_l(\bar{x}) \right] \psi_{n,1}(\bar{x}, 0) = \sum_{l=1}^{N} c_l \phi_l(\bar{x}, 0), \]  
(3.22)
where
\[ \phi_l(\bar{x}, 0) \equiv \psi_{n,1}(\bar{x}, 0) u_l(\bar{x})/\sqrt{B_l}, \]
\[ c_l = \sqrt{\frac{B_l}{N}}, \tag{3.23} \]
with
\[ B_l = \int_0^1 d\bar{x}|\psi_{n,1}(\bar{x}, 0) u_l(\bar{x})|^2. \tag{3.24} \]

The set \{\phi_l(\bar{x}, 0)\} forms an orthonormal set at the interval \(0 \leq \bar{x} \leq 1\), and each \(\phi_l(\bar{x}, 0)\) has a support in \((l-1)/N \leq \bar{x} \leq l/N\).

We now regard that the measurement of coordinate by the small position detector described above corresponds to picking up a specific state \(\phi_{l_0}(\bar{x}, 0)\). This means that we perform a very specific sampling of events corresponding to the state \(\phi_{l_0}(\bar{x}, 0)\) for the prepared state \(\psi_{n,1}(\bar{x}, 0)\). The standard deviation of the coordinate in this sampling is given by
\[ \tilde{\Delta} \bar{x} \sim \Delta \bar{x}_{l_0} \ll \Delta \bar{x}, \tag{3.25} \]
where \(\Delta \bar{x}_{l_0}\) is evaluated using the state \(\phi_{l_0}(\bar{x}, 0)\). We assign the probability
\[ |c_{l_0}|^2 = \frac{B_{l_0}}{N} \ll 1 \tag{3.26} \]
to this specific sampling of the measured coordinate, which corresponds to the reduction probability of the state \(\psi_{n,1}(\bar{x}, 0)\) to \(\phi_{l_0}(\bar{x}, 0)\) in the expansion (3.22). This probability is also written as
\[ |c_{l_0}|^2 = \int_{(l_0-1)/N}^{l_0/N} d\bar{x}|\psi_{n,1}(\bar{x}, 0)|^2. \tag{3.27} \]

The state \(\phi_{l_0}(\bar{x}, 0)\) after the specific measurement generally depends on the initial state \(\psi_{n,1}(\bar{x}, 0)\), but this dependence diminishes when one chooses \(N \gg 1\).

If one assumes that all the events in the momentum measurement of the original wave packet \(\psi_{n,1}(\bar{x}, 0)\) are accepted, then the standard deviation of the momentum is given by \(\Delta \bar{p}\) in Eq. (3.19). The uncertainty product for this specific sampling of events then becomes
\[ \Delta \bar{p} \tilde{\Delta} \bar{x} \sim \Delta \bar{p} \Delta \bar{x}_{l_0} \ll \frac{1}{2}, \tag{3.28} \]
while the probability for this sampling of events is given by Eq. (3.26).

(iii) We next suppose to collect all the measured data of momentum for the above reduced state \(\phi_{l_0}(\bar{x}, 0)\) without any restriction on the value of momentum. It is then confirmed that the Kennard relation
\[ \Delta \bar{p}_{l_0} \Delta \bar{x}_{l_0} \geq \frac{1}{2}, \tag{3.29} \]
holds, where $\Delta p_{l_0}$ is calculated using the localized state $\phi_{l_0}(\bar{x}, 0)$. We assign a unit probability to this sampling of data for the prepared states represented by $\phi_{l_0}(\bar{x}, 0)$. Equation (3.29) is what one naively expects; the precise measurement of coordinate leads to the spread momentum.

(iv) For the reduced wave function $\phi_{l_0}(\bar{x}, 0)$, we next suppose to selectively measure the specific momentum, namely, we sample only the events with a momentum that approximately corresponds to the original wave packet $\psi_{n,1}(\bar{x}, 0)$ in Eq. (3.18) in the expansion (see the expansion in Eq. (3.6))

$$\phi_{l_0}(\bar{x}, 0) = \sum_{k=1} a_{l_0,k} \psi_{n,k}(\bar{x}, 0),$$

$$a_{l_0,k} = \int_0^1 \psi_{n,k}^\dagger(\bar{x}, 0) \phi_{l_0}(\bar{x}, 0) d\bar{x}.$$  (3.30)

In this procedure, one may regard the specific coordinate measurement in analysis (ii) as a preparation of the state $\phi_{l_0}(\bar{x}, 0)$ with the standard deviation $\Delta \bar{x}_{l_0}$, and the present immediately subsequent measurement as the analysis of the state $\phi_{l_0}(\bar{x}, T)$ by a specific momentum analyzer. The expected standard deviation in momentum in this specific measurement (or sampling) is $\Delta \bar{p}$, which is the standard deviation for the original wave packet in Eq. (3.18), and the uncertainty product is

$$\Delta \bar{p} \Delta \bar{x}_{l_0} \ll \frac{1}{2},$$  (3.31)

which is identical to the uncertainty product in case (ii) above. By taking Eq. (3.30) into account, we assign the probability

$$|a_{l_0,1}|^2 = |\int_0^1 \psi_{n,1}^\dagger(\bar{x}, 0) \phi_{l_0}(\bar{x}, 0) d\bar{x}|^2 = |c_{l_0}|^2$$  (3.32)

to the specific sampling of events in Eq. (3.31), when it is assumed to be feasible at least approximately. This probability agrees with the probability in Eq. (3.26).

By this specific measurement (or sampling) of the momentum, we return close to the original wave function $\psi_{n,1}(\bar{x}, 0)$ in Eq. (3.18). The net outcome in this approximate cycle is the measurements of the coordinate in analysis (ii) and the momentum in analysis (iv), which give an uncertainty product much smaller than the lower bound of the Kennard relation as in Eq. (3.31). The importance of analysis (iv) is to show that analysis (iii), which is the commonly expected result of the precise measurement of the coordinate, is not the end of the story. The approximate restoration to the original state $\psi_{n,1}(\bar{x}, 0)$ is an application of the creation of a quantum state by measurement.

§ 4. Actual numerical calculation

In this section, we explain some details of the numerical calculation. We fix the parameter $T = 0$ in our analysis for simplicity, and thus the parameter $\lambda$ in Eq. (3.17)
does not appear in our analysis. For analysis at \( T \neq 0 \), one may choose, for example, \( \lambda = 10^{-5} \), which means that the size of the box is \( 10^5 \) times the Compton wavelength of the particle involved.

We choose the starting wave function \( \psi_{n,1}(\bar{x},0) \) in Eq. (3.18) with \( n = 10 \). To achieve a very small uncertainty product, we choose the detector parameter defined in Eq. (3.20) at \( N = 100 \) or \( N = 200 \), and a position of the detector slightly away from the center of the box, namely, \( l_0 = 40 \) and \( l_0 = 80 \), respectively.

For those parameters, we repeat analyses (i) to (iv) in §3. In each case, we checked \( |\phi_l(\bar{x})| \) and the (momentum space) distribution \( |a_{l_0,k}|^2 \) of \( \phi_{l_0}(\bar{x},0) \). The distribution \( |\psi_{n,1}(\bar{x},0)|^2 \) in the case \( n = 10 \), which is actually independent of \( n \), is shown in Fig. 1.

For illustration, we will show the details of the numerical calculation in the case \( n = 10 \) and \( N = 200 \) later. The expansion (3.30) is used to evaluate the standard distribution of the momentum for \( \phi_{l_0}(\bar{x},0) \):

\[
\langle \hat{p} \rangle_{l_0} = \int_0^1 d\bar{x} \psi_{l_0}^\dagger(\bar{x},0) \frac{1}{i} \frac{\partial}{\partial \bar{x}} \psi_{l_0}(\bar{x},0) \\
= \bar{p}_n + \int_0^1 \varphi^\dagger(\bar{x},0) \frac{1}{i} \frac{\partial}{\partial \bar{x}} \varphi(\bar{x},0) d\bar{x} \\
= \bar{p}_n + \langle \hat{p} \varphi \rangle,
\]

\[
\langle \hat{p}^2 \rangle_{l_0} = \int_0^1 d\bar{x} \psi_{l_0}^\dagger(\bar{x},0) \left( \frac{1}{i} \frac{\partial}{\partial \bar{x}} \right)^2 \psi_{l_0}(\bar{x},0) \\
= \bar{p}_n^2 + 2\bar{p}_n \langle \hat{p} \varphi \rangle + \int_0^1 \varphi^\dagger(\bar{x},0) \left( \frac{1}{i} \frac{\partial}{\partial \bar{x}} \right)^2 \varphi(\bar{x},0) d\bar{x} \\
= \bar{p}_n^2 + 2\bar{p}_n \langle \hat{p} \varphi \rangle + \langle \hat{p}^2 \rangle \varphi, \\
(\Delta \bar{p}_{l_0})^2 = \langle \hat{p}^2 \rangle \varphi - (\langle \hat{p} \rangle \varphi)^2 ,
\]

where we defined

\[
\phi_{l_0}(\bar{x},0) = \sum_{k=1} a_{l_0,k} \psi_{n,k}(\bar{x},0)
\]
\[ \varphi(\bar{x}, 0) \equiv \sum_{k=1} a_{l_0,k} \frac{2i}{\sqrt{2}} \sin(k\pi \bar{x}), \]

\[ \langle \bar{p} \rangle_\varphi = \frac{1}{2i} \left[ \int_0^1 \varphi^\dagger(\bar{x}, 0) \frac{\partial}{\partial \bar{x}} \varphi(\bar{x}, 0) d\bar{x} - \text{h.c.} \right], \]

\[ \langle \bar{p}^2 \rangle_\varphi = -\frac{1}{2} \left[ \int_0^1 \varphi^\dagger(\bar{x}, 0) \left( \frac{\partial}{\partial \bar{x}} \right)^2 \varphi(\bar{x}, 0) d\bar{x} + \text{h.c.} \right]. \] (4.2)

This procedure is convenient to ensure the hermiticity of the momentum operator \( \hat{\bar{p}} \). However, owing to the \( \delta \)-functional singularity in the derivative of the step function, the coefficient \( a_{l_0,k} \) contains an arbitrary large frequency \( k \) and it causes a divergence in the above summation such as \( \langle \bar{p}^2 \rangle_{l_0} \) in Eq. (4.1). To remedy this divergence introduced by the (artificial) sharp step function \( \phi_{l_0}(\bar{x}, 0) \), we cut off the summation in Eq. (4.2) at \( k = 4N \) in the momentum space, which means a smoothing of the spatial function \( \phi_{l_0}(\bar{x}, 0) \). In the actual calculation, we first plot the distribution \( |a_{l_0,k}|^2 \) and confirm that this cutoff in \( k \) is reasonable.

From the uncertainty product

\[ U = \Delta \bar{p} \Delta \bar{x} \] (4.3)

together with the quantum mechanical (relative) probability \( P \) for each case, one can confirm our statements in §3. Note that the standard deviations \( \Delta \bar{p} \) and \( \Delta \bar{x} \) in Eq. (4.3) are generally defined for a specific sampling of measured events and thus generally differ from those appearing in the standard Kennard relation, as is explained in §§2 and 3.

The results are as follows:

(1) Wave function with the parameter \( n = 10 \) in Eq. (3.18) and the detector with the parameter \( N = 100 \) in Eq. (3.20):

\[ U_{(i)} = 0.567862, \quad P_{(i)} = 1, \]
\[ U_{(ii)} = 0.00906856, \quad P_{(ii)} = 0.0179003, \]
\[ U_{(iii)} = 0.826994, \quad P_{(iii)} = 1, \]
\[ U_{(iv)} = 0.00906856, \quad P_{(iv)} \simeq 0.0179003. \] (4.4)

(2) Wave function with the parameter \( n = 10 \) in Eq. (3.18) and the detector with the parameter with \( N = 200 \) in Eq. (3.20):

\[ U_{(i)} = 0.567862, \quad P_{(i)} = 1, \]
\[ U_{(ii)} = 0.00453444, \quad P_{(ii)} = 0.00899826, \]
\[ U_{(iii)} = 0.827034, \quad P_{(iii)} = 1, \]
\[ U_{(iv)} = 0.00453444, \quad P_{(iv)} \simeq 0.00899826. \] (4.5)

Note that the uncertainty product and the probability in case (iv) in Eqs. (4.4) and (4.5) are approximate ones.
The uncertainty product $U$ satisfies the Kennard relation $U \geq \frac{1}{2}$ in cases (i) and (iii), for which the quantum mechanical probability $P = 1$. On the other hand, the uncertainty product $U$ is clearly smaller than the lower bound of the Kennard relation $U \ll \frac{1}{2}$ for the specific samplings of the data in cases (ii) and (iv), for which the quantum mechanical probability is also very small $P \ll 1$.

The agreement of the uncertainty product $U_{(iii)}$ in the above two cases with $N = 100$ and $N = 200$ indicates that the state after the measurement, namely, the step-function-type wave function is universal to good accuracy, as it should be. In our simple examples, the ratio $P/U$ is always on the order of unity. See also Eqs. (2.4) and (2.5).

4.1. Details of the numerical calculation for $n = 10$ and $N = 200$

We now explain the details of the numerical calculation in the specific case with the parameters $n = 10$ and $N = 200$.

In Fig. 1, we have shown the distribution $|\psi_{n,1}(\bar{x},0)|^2$ for $n = 10$. For this wave function, we have

\[
(\Delta \bar{x})_{(i)} = 0.180756, \quad (\Delta \bar{p})_{(i)} = 3.14159, \\
U_{(i)} = (\Delta \bar{x})_{(i)}(\Delta \bar{p})_{(i)} = 0.567862,
\]

and $P_{(i)} = 1$ since we accept all the measured results without any bias.

In Fig. 2, we show $|\phi_{l_0}(\bar{x},0)|^2$ for $l_0 = 80$.

In Fig. 3, we show $|a_{l_0,k}|^2$ for $l_0 = 80$, which shows that the cutoff at $k = 4N = 800$ is reasonable. To check this cutoff, we show

\[
|\sum_{k=1}^{800} a_{l_0,k} \psi_{n,k}(\bar{x},0)|^2
\]

in Fig. 4, which is to be compared with $|\phi_{l_0}(\bar{x},0)|^2$. These two should agree with good accuracy if our approximation is valid.

From Fig. 2, we have

\[
(\Delta \bar{x}_{l_0})_{(ii)} = 0.00144336.
\]

![Fig. 2. Distribution $|\phi_{l_0}(\bar{x},0)|^2$ with $l_0 = 80$ for $n = 10$.](https://academic.oup.com/ptp/article-abstract/125/2/205/1855494)
Fig. 3. \(|a_{l_0,k}|^2\) for \(l_0 = 80\).

In comparison, we have \((\Delta \bar{x}_{l_0})_{(ii)} = 0.0013598\), which is close to the value in Eq. (4.8), from the series cutoff at \(k = 800\)

\[
\sum_{k=1}^{800} a_{l_0,k} \psi_{n,k}(\bar{x}, 0),
\]

shown in Fig. 4. To be precise, we use the normalized function in our numerical evaluation,

\[
\frac{\sum_{k=1}^{800} a_{l_0,k} \psi_{n,k}(\bar{x}, 0)}{\sqrt{\int_0^1 \left( \sum_{k=1}^{800} a_{l_0,k} \psi_{n,k}(\bar{x}, 0) \right)^2 d\bar{x}}} = \frac{\sum_{k=1}^{800} a_{l_0,k} \psi_{n,k}(\bar{x}, 0)}{\sqrt{\sum_{k=1}^{800} |a_{l_0,k}|^2}},
\]

as well as in Fig. 4.

We thus have the uncertainty product and probability for analysis (ii)

\[
U_{(ii)} = (\Delta \bar{x}_{l_0})_{(ii)} (\Delta \bar{p})_{(i)} = 0.00453444,
\]

\[
P_{(ii)} = B_{l_0}/N = 0.00899826,
\]

using

\[
B_{l_0} = \int_0^1 d\bar{x} |\psi_{n,1}(\bar{x}, 0) u_{l_0}|^2 = 1.79965
\]
for \( l_0 = 80 \) and \( n = 10 \).

From Fig. 3, the cutoff at \( k = 800 \) is reasonable. We then have

\[
(\Delta \bar{p}_{l_0})_{(iii)} = 572.993
\]

from Eqs. (4·1) and (4·2) with the cutoff at \( k = 800 \). We then have the uncertainty product for analysis (iii),

\[
U_{(iii)} = (\Delta \bar{x}_{l_0})_{(ii)}(\Delta \bar{p}_{l_0})_{(iii)} = 0.827034,
\]

and \( P_{(iii)} = 1 \) since we accept all the events without any bias.

Finally, we have the uncertainty product and probability for analysis (iv):

\[
U_{(iv)} = (\Delta \bar{x}_{l_0})_{(ii)}(\Delta \bar{p})_{(i)} = 0.00453444,
\]

\[
P_{(iv)} = |a_{l_0,1}|^2 = P_{(ii)}.
\]

\( U_{(iv)} \) is the same as \( U_{(ii)} \) by definition.

In this way, we reproduce the numerical results in Eq. (4·5).

**§ 5. Discussion and conclusion**

We have studied the interplay of uncertainty and probability in quantum mechanics. If one samples a suitable set of measured data, one can realize a very small uncertainty product, but the probability of such a sampling of preferred events is very small. This mechanism provides a consistent explanation of the evasion of the uncertainty relation noted in 4), 9) and 10) in the framework of quantum mechanics; such a probability is simply very small (see the Appendix). If one measures events that are realized almost with certainty for a given state vector, then the standard Kennard relation is satisfied. We have also presented an example of cyclic measurements where the state vector is restored approximately to its original state while a product of measured standard deviations of coordinate and momentum is much smaller than the lower bound of the Kennard relation. Again, the probability of such a sampling of events is very small.

The present analysis shows that it is indispensable to examine the quantum mechanical probability when a possible very small uncertainty product is discussed. The consistency of our analysis with the Landau-Pollak type uncertainty relation,\(^{13} \) which also emphasizes the probability aspect, was also noted.

We now briefly comment on a possible practical implication of our analysis. The detection of gravitational waves involves very weak signals, and thus the precise analysis of the detection limit provided by quantum mechanics (and possibly the evasion of the “standard quantum limit”) is important.\(^{12} \) Some of the authors argued that such an evasion of the standard quantum limit is impossible,\(^{15}, 16, 18 \) while others argued that the evasion of the standard quantum limit is possible.\(^{17}, 19 \) Our analysis operates entirely within the framework of quantum mechanics and thus no notion such as “the evasion of the standard quantum limit” appears. Nevertheless, our analysis shows that one needs to examine the quantum mechanical probability to
observe the gravitational waves in a specific setting of the detector when one analyzes the evasion or observance of the standard quantum limit. Further refinement of our analysis, which emphasizes the role of quantum probability in the analysis of the uncertainty relation, may help reconcile the contradicting views about the standard quantum limit in the detection of gravitational waves.\textsuperscript{*}

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Appendix A

Implications on the past Analyses of the Uncertainty Relation

We here briefly mention the implications of the analyses in §3 on the past analyses of the “evasion of the uncertainty relation to an arbitrary degree with a very small probability”.\textsuperscript{11}

A.1. Diffraction process

In the context of the diffraction process of Ballentine,\textsuperscript{9} the detector placed on the screen corresponds to a very small detector in analysis (ii) in §3. The momentum uncertainty in the diffraction process was theoretically estimated in Ref. 9),

\begin{equation}
\delta p \sim p_0 \frac{\delta q}{L} \tag{A.1}
\end{equation}

for a given uncertainty \(\delta q\) of the coordinate measured by a small detector with a size \(\delta q\) placed on the screen at a distance \(q\) from its center; \(p_0\) is the momentum of the incoming particle and \(L\) is the distance between the pinhole and the screen in the diffraction process. A characteristic feature of Eq. (A.1) is that the momentum uncertainty does not increase for smaller \(\delta q\) but rather decreases. In the mathematical limit \(\delta q \rightarrow 0\) with a fixed \(L\), the above momentum uncertainty is eventually overtaken by the intrinsic uncertainty in the incoming momentum

\begin{equation}
\delta p \simeq p_0 \frac{\delta q}{L} + \delta p_0 \frac{q}{L} \approx \delta p_0 \frac{q}{L} \tag{A.2}
\end{equation}

and the uncertainty product is given by

\begin{equation}
\delta p \delta q \simeq \delta p_0 \frac{q}{L} \delta q \tag{A.3}
\end{equation}

\textsuperscript{*} In the detection of gravitational waves, the precise measurement of the position and the control of the subsequent time development of the system are essential. In this respect, our analysis (ii) of the position measurement and the (immediately) subsequent specification of the momentum distribution in analysis (iv) in §3 may be relevant. In fact, Caves, who defends the existence of the standard quantum limit against the criticism by Yuen,\textsuperscript{17} comments that “The measurements suggested by Yuen are among those for which no realization is known” in 18). This comment might have some connection with the present analysis of a possible construction of a very small uncertainty product, but with a very small probability of realizing such a product.
by choosing a sufficiently small $\delta q$. Since the uncertainty of the momentum in the preparation process that ensures the presence of a particle in between the pinhole and the screen with a unit probability is estimated at $\delta p_0 \sim \frac{\hbar}{L}$ (note that we assume the Kennard relation $\delta p_0 L \sim \hbar$ for events with a unit probability), the uncertainty product (A.3) is written as

$$\delta p_0 \frac{q}{L} \delta q \sim \frac{q}{L} \frac{\delta q}{L} \sim \frac{\hbar}{L} \ll \hbar.$$

(A.4)

One may understand that a transition from the “classical” domain (A · 1) without $\hbar$ to the quantum domain $\delta p \simeq \delta p_0 \sim \hbar/L$ with $\hbar$ takes place.

On the other hand, the quantum mechanical probability to find the diffracted particle at the interval $\delta q$ on the screen is

$$|\psi(q)|^2 \frac{2\pi q}{L} \delta q \sim \frac{q}{L} \frac{\delta q}{L} \sim \frac{\hbar}{L},$$

(A.5)

where $\psi(q)$ is the two-dimensional wave function on the screen. We assumed an annulus-shaped detector for simplicity. We note that $|\psi(q)|^2 \sim 1/L^2$ when one normalizes the wave function on the entire screen. To justify the estimate of the (relative) probability in Eq. (A.5), one may imagine to send $N_0$ collimated particles (one particle at a time) through the pinhole toward the screen. All the $N_0$ particles will eventually arrive at the screen, but only the tiny fraction $\sim N_0(q\delta q/L^2)$ will arrive at the specific detector we consider; this fraction agrees with the probability (A.5). If one should cover the screen by many small detectors and accept all the events detected by any of the small detectors, one would detect all $N_0$ particles, but the standard deviation $\delta q$ of the measured coordinate would then be $\delta q \sim L$, for consistency with the Kennard relation $\delta p_0 \delta q \sim \hbar$.

If one identifies $\delta q/L \sim 1/N$, Eqs. (A.4) and (A.5) precisely correspond to Eqs. (3·28) and (3·26) in analysis (ii) in §3, respectively, including the form of the uncertainty product (A·4) in terms of the guessed uncertainty in the prepared momentum $\delta p_0$ and the uncertainty $\delta q$ in the measured coordinate. (One can confirm that $\delta p_0 \sim h/\delta q$ if one wants to have a unit probability $|\psi(q)|^2 2\pi q \delta q \sim 1$ by choosing $\psi(q)$ suitably, and in this case the uncertainty product becomes $\delta p_0 \delta q \sim \hbar$.)

A.2. Measurement-disturbance relation $\epsilon(x)\eta(p) \ll \hbar$

In the context of the gedanken experiment of Ozawa (see §9 in Ref. 10)) of a two-particle system, which is specified by $(x_1,p_1)$ and $(x_2,p_2)$, the result of analysis (i) in §3 may be used to confirm that particle 1 existed in the state represented by $\psi_{n,1}(x,0)$ in Eq. (3·18) at the interval $0 \leq x_1 \leq 1$. One may next assume that particle 1 of a two-particle system in Ref. 10) in fact belonged to a specific state, $\phi_{n_0}(x,0)$, in the expansion in Eq. (3·22)

$$\psi_{n,1}(x,0) = \sum_{l=1}^{N} c_l \phi_l(x,0)$$

(A.6)

without measurement, in the sense that the detector parameter $N$ is arbitrary. The precise measurement of position $x_2$ of particle 2 in Ref. 10), for which the momentum
of particle 1 is not disturbed $\eta(p_1) = 0$ (or more realistically $\eta(p_1) \sim \hbar/L$ if one puts a particle in a box with size $L^{14}$), may be regarded as the specification of the position of the very small detector in the analysis (ii) in §3. The choice of the wave function of the particle 1, for which $\langle(x_1 - x_2)^2\rangle < \alpha$ with an arbitrarily small $\alpha$, is then regarded to correspond to the precise overlap of a very narrow state, $\phi_{l_0}(\bar{x}, 0)$, and a very small position detector in analysis (ii) in §3. Note that $\langle(x_1 - M)^2\rangle = \langle(x_1 - x_2)^2\rangle < \alpha$ with $M$ being the meter observable of the measuring apparatus in Ref. 10) thus, our model represents the essence of the precise measurement of the position of particle 1 in Ref. 10). The a priori probability of the coincidence of the state picked up by the small detector, whose position is specified by the precisely measured value of $x_2$, with the assumed narrow state $\phi_{l_0}(\bar{x}, 0)$ of the particle 1, is then $1/N$; this probability agrees with our quantum mechanical probability of finding the assumed $\phi_{l_0}(\bar{x}, 0)$ in Eq. (A-6) when the prepared wave function $\psi_{\phi_{l_1}}(\bar{x}, 0)$ of particle 1 spreads over the domain $0 \leq \bar{x} \leq 1$. In this case, the condition $\eta(p_1) = 0$ is naturally preserved even when the position of particle 1 is specified by the detector with an arbitrary accuracy $\epsilon(\bar{x}_1) \sim 1/N$ by choosing a large $N$, although such a probability is very small $\sim 1/N$.

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