Semiclassical strings in supergravity PFT

Aritra Banerjee\textsuperscript{a}, Sagar Biswas\textsuperscript{b}, Kamal L. Panigrahi\textsuperscript{c}

Department of Physics, Indian Institute of Technology Kharagpur, Kharagpur 721 302, India

Abstract

Puff field theory (PFT) is an example of a non-local field theory which arises from a novel embedding of D-branes in a Melvin universe. We study several rotating and pulsating string solutions of the F-string equations of motion in the supergravity dual of the PFT. Further, we find a PP-wave geometry from this non-local spacetime by applying a Penrose limit and comment on its similarity with the maximally supersymmetric PP-wave background.

1 Introduction and summary

It is not uncommon to find examples of quantum field theories (QFT) which violate Lorentz invariance in the high energy limit. These theories might play a crucial role in understanding physics beyond the standard model of particle physics. In the context of string theory, for example, a few Lorentz violating theories are constructed from the local deformation of the $\mathcal{N} = 4$ super Yang–Mills (SYM) theory. The UV-completeness of such theories are recovered by constraining the conformal dimensions of such deformation operators, although, in the IR limit, the action for these theories can approach that of $\mathcal{N} = 4$ SYM theory. An example of such a theory includes $\mathcal{N} = 4$, SYM on a space of non-commutative $\mathbb{R}^4$ [1], which in the IR limit looks like $\mathcal{N} = 4$ SYM deformed by an operator of conformal dimension $\Delta = 6$, breaking the Lorentz group $\text{SO}(3, 1)$ to $\text{SO}(2) \times \text{SO}(1, 1)$. The non-commutativity introduces a fundamental linear non-locality into the construction of such a theory. It is worth mentioning that in many of these theories the fundamental particles can become extended non-local objects, making them intriguing for string theorists. It is, therefore, interesting to explore such possible extensions of field theories that incorporate the violation of Lorentz invariance at some typical mass scales.

Puff field theory (PFT) [2] is an example of a Lorentz violating non-local field theory. The idea follows the construction of non-commutative SYM (NCSYM) by Douglas and Hull [3]. In NCSYM we consider $n$-coincident $D0$ branes in type IIA string theory compactified on a small $T^2$. This theory is T-dual to type IIA on a large $T^2$ with $n$ D2 branes. But this T-duality does not simply map the small $T^2$ to a large one if a NS NS 2-form flux $B_{\mu\nu}$ is turned on along $T^2$. It has been argued in [2] that in the low energy limit the Kaluza–Klein particle is described by a decoupled non-local field theory that breaks Lorentz symmetry $\text{SO}(3, 1)$ but preserves rotational invariant group in three dimensions, $\text{SO}(3)$. This conjectured field theory, where the particle carrying a R-charge now expands to occupy a D3 brane worldvolume proportional to the R-charge and the dimensionful deformation parameter, is termed PFT. Nothing is known about the explicit lagrangian form of PFT, but the supergravity description of PFT can be obtained from the non-trivial embedding of D-brane geometry in a Melvin universe, as done in [4].

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\textsuperscript{a}e-mail: aritra@phy.iitkgp.ernet.in
\textsuperscript{b}e-mail: sbiswas@phy.iitkgp.ernet.in
\textsuperscript{c}e-mail: panigrahi@phy.iitkgp.ernet.in
eter. This can in turn be fixed by choosing the geometrical twist accordingly.

Now we can see that the background dual to PFT looks incredibly complex. But in this work we find that the near horizon geometry of the background, in the Penrose limit, reduces to the PP-wave of AdS$_5 \times S^5$. This result prompts us to look for solutions of the F-string equations of motion in this background in the semiclassical limit. In the context of AdS/CFT duality, string solutions in the semiclassical limit have proved to be of key importance in exploring various aspects of the correspondence. According to the AdS/CFT correspondence [5–7] quantum closed string states in bulk should be dual to local operators on the boundary. This state-operator matching can be tractable only in the large angular momentum limit, on both sides of the duality [8–16], as both the string theory and the gauge theory are integrable in the semiclassical limit; see for example [17–21]. In this connection a large number of rotating and pulsating string solutions have been studied in various string theory backgrounds; see for example [22–50]. Here, we try to extract some simple solutions following results from these works.

In the case of our background, we expand it in the near horizon limit keeping only AdS$_5 \times S^5$ plus the leading order deformation terms, containing the mixing of coordinates from both AdS and sphere part. It has already been shown in [2] that this leading order term in the dual gauge theory corresponds to a deformation operator of conformal dimension $\Delta = 7$ to $N = 4$ SYM. That is, in the low energy limit the total Lagrangian can be written as

$$ L = L_{N=4} + \eta O^{(7)} + \ldots \quad (1.1) $$

Here $\eta$ is the dimensionful deformation parameter. Thus, we choose to ignore the higher order deformation terms in our metric and study a general class of rotating string solutions in some approximation. We find that the dispersion relations among various conserved quantities differ slightly from that of the general AdS$_n \times S^n$. Next we study a class of solutions both rotating and pulsating in this background. Such a kind of string states are expected to be dual to highly excited sigma model operators. As the oscillation number is a quantum adiabatic invariant, the series relation of the energy in terms of oscillation number and other conserved quantities is presented as the solution to characterize the dynamics of these string states.

The rest of the paper is organized as follows. In Sect. 2 we write down the supergravity description of PFT and take the appropriate near horizon limit for studying the rotating string solutions. In Sect. 3, we study the Penrose limit of the supergravity dual background of PFT. Section 4 is devoted to the study of rigidly rotating strings in this background. We present the regularized dispersion relations among various conserved charges corresponding to the string motion. We also present solutions for strings which are both rotating and pulsating in the above background. Finally, in Sect. 5 we conclude with some comments.

2 Supergravity description of PFT

Following [4] we know that the supergravity dual background of PFT is given by the following metric and 4-form field:

$$ \frac{dx^2}{\alpha'} = K^{1 \over 2} \left( -H^{-1} dr^2 + dU^2 + U^2 ds^2_2 + \sum_{i=8}^{9} dy_i^2 \right) $$

$$ + K^{-1 \over 2} \left( \sum_{i=1}^{3} dx_i^2 + H U^2 (d\phi + \mathcal{A} + \Delta^3 H^{-1} dt)^2 \right), $$

$$ \frac{A}{\alpha'^2} = K^{-1} (-dr + U^2 \Delta^3 (d\phi + \mathcal{A}) \wedge dx_1 \wedge dx_2 \wedge dx_3), $$

$$ e^\phi = g_{11B} = 2\pi g_{YM}, \quad (2.1) $$

where the harmonic functions $H$ and $K$ are

$$ H = \frac{4\pi g_{11B} N}{(U^2 + ||Y||^2)^2}, \quad K = \frac{4\pi g_{11B} N}{(U^2 + ||Y||^2)^2} + \Delta^6 U^2; \quad (2.2) $$

also $ds^2_2 = \frac{1}{2}(d\theta^2 + \sin^2 \theta d\varphi^2)$ is the “Fubini–Studiy” metric. Note that to obtain this background one needs to take the decoupling limit $\alpha' \rightarrow 0$. However, in this limit the value of $\Delta^3 = n\alpha'^2$ is fixed for large value of deformation parameter $n$.

Now, considering $U = V \cos \varphi$ and $||Y|| = V \sin \varphi$, i.e.

$$ Y_8 = V \sin \varphi \cos \psi \quad \text{and} \quad Y_9 = V \sin \varphi \sin \psi, $$

we can rewrite the metric and 4-form as follows [4]:

$$ \frac{dx^2}{\alpha'} = K^{1 \over 2} (-K^{-1} dr^2 + dV^2 + V^2 d\varphi^2 + V^2 \sin^2 \varphi d\psi^2) $$

$$ + \frac{1}{4} K^{1 \over 2} V^2 \cos^2 \varphi d\theta^2 $$

$$ + \frac{1}{4} K^{-1 \over 2} V^2 \cos^2 \varphi (K \sin^2 \theta + H(1 - \cos \theta)^2) d\varphi^2 $$

$$ + K^{-1 \over 2} V^2 \cos^2 \varphi d\phi^2 $$

$$ + K^{-1 \over 2} \sum_{i=1}^{3} dx_i^2 + 2K^{-1 \over 2} V^2 \cos^2 \varphi \Delta^3 dr d\phi $$

$$ - K^{-1 \over 2} V^2 \cos^2 \varphi (1 - \cos \theta) d\varphi d\psi $$

$$ - K^{-1 \over 2} V^2 \cos^2 \varphi \Delta^3 (1 - \cos \theta) d\varphi, $$

$$ \frac{A}{\alpha'^2} = K^{-1} \left( -dr + \Delta^3 V^2 \cos^2 \varphi \left( d\phi - \frac{1}{2}(1 - \cos \theta) d\varphi \right) \right) \wedge dx_1 \wedge dx_2 \wedge dx_3, $$

$$ e^\phi = 2\pi g_{YM}^2, \quad (2.3) $$

with $K = H + \Delta^6 V^2 \cos^2 \varphi$, $H = \frac{8\pi^2 g_{YM}^2 N}{V^2}$. Now we want to take the near horizon limit on this full generalized metric.
Note that in the near horizon limit (i.e. \( V \rightarrow 0 \)), \( H = \frac{C^2}{V^2} \propto K \), where \( C^2 = 8\pi^2 k_\gamma^2 M_N \), and we have kept terms up to \( V^4 \). The resulting metric and the 4-form field are

\[
\frac{ds^2}{\alpha^2} = \frac{V^2}{C} \left( -dr^2 + \sum_{i=1}^{3} d\xi_i^2 \right) + C \frac{dV^2}{V^2} + 2\Delta^2 V^4 \sin^2 \zeta d\tau \left( W - \sin^2 \left( \frac{\theta}{2} \right) d\phi \right) + C \left[ d\xi^2 + \cos^2 \xi d\psi^2 + \sin^2 \xi \left( \frac{d\theta^2}{2} + d\phi^2 \right) + \sin^2 \left( \frac{\theta}{2} \right) d\phi d\psi \right],
\]

\[
A = -\frac{V^4}{C^2} dr \land dx_1 \land dx_2 \land dx_3.
\] (2.4)

Now making the following change of variables:
\[
\theta = 2\theta, \quad \phi = \phi_1 - \phi_2, \quad \xi = \xi - \frac{\pi}{2},
\]
we get

\[
\frac{ds^2}{\alpha^2} = \frac{V^2}{C} \left( -dr^2 + \sum_{i=1}^{3} d\xi_i^2 \right) + C \frac{dV^2}{V^2} + 2\Delta^2 V^4 \sin^2 \zeta d\tau \left( W - \sin^2 \left( \frac{\theta}{2} \right) d\phi \right) + C \left[ d\xi^2 + \cos^2 \xi d\psi^2 + \sin^2 \xi \left( \frac{d\theta^2}{2} + d\phi^2 \right) + \sin^2 \left( \frac{\theta}{2} \right) d\phi d\psi \right],
\]

\[
A = -\frac{V^4}{C^2} dr \land dx_1 \land dx_2 \land dx_3.
\] (2.5)

This is the metric we are interested in on taking the Penrose limit.

### 3 Penrose limit

In this section we would like to find a PP-wave metric by applying a Penrose limit on the background (2.5). To take the Penrose limit on (2.5), we start with a null geodesic in \((t, V, \psi)\) plane following [51]. Keeping the other coordinates fixed, the metric becomes

\[
\frac{ds^2}{\alpha^2} = C \left[ -V^2 dr^2 + \frac{dV^2}{V^2} + d\psi^2 \right].
\] (3.1)

To change the coordinates from \((t, V, \psi)\) to \((u, v, y)\), which are more suitable to adapt the null geodesic, we use the following transformation:

\[
dV = \sqrt{1 - l^2 V^2} du,
\]
\[
dr = \frac{du}{V^2} + l dy - dv,
\]
\[
d\psi = l du + dy,
\] (3.2)

where \( l = \frac{d}{dV}, J, \) and \( E, \) respectively, are angular momentum and energy along the geodesic (3.1). Substituting (3.2) in (2.5), and making the change of coordinates
\[
u = u, \quad v = \frac{v}{C}, \quad y = \frac{y}{\sqrt{C}}, \quad x_i = \frac{x_i}{\sqrt{C}}.
\]
\[
\zeta = \frac{z}{\sqrt{C}}, \quad \Omega_3 = \Omega_3,
\]

followed by a large \( C \) limit, the metric and the field strength reduce to

\[
\frac{ds^2}{\alpha^2} = 2du dv - \zeta^2 l^2 du^2 + (1 - l^2 V^2) dy^2 + V^2 \sum_{i=1}^{3} dx_i^2 + dz^2 + \zeta^2 d\Omega_3^2,
\]
\[
F = dA = -4V^3 l\sqrt{1 - l^2 V^2} du \land dy \land dx_1 \land dx_2 \land dx_3.
\] (3.3)

Again rescaling \( u \rightarrow \mu u \) and \( v \rightarrow \frac{v}{\mu} \), we get

\[
\frac{ds^2}{\alpha^2} = 2du dv - \mu^2 \zeta^2 l^2 du^2 + (1 - l^2 V^2) dy^2 + V^2 \sum_{i=1}^{3} dx_i^2 + dz^2
\]
\[
F_{\mu y x_1 x_2 x_3} = -4\mu V^3 l\sqrt{1 - l^2 V^2},
\] (3.4)

where \( dz^2 = dz^2 + \zeta^2 d\Omega_3^2 \). This is the Rosen form of the PP-wave. To convert this into Brinkman form we make the following substitution:

\[
u = u, \quad y = \frac{y}{\sqrt{1 - l^2 V^2}}, \quad x_i = \frac{x_i}{V}, \quad \bar{z} = \bar{z},
\]
\[
v = v + \frac{1}{4} \left[ \frac{\partial_u (1 - l^2 V^2)}{V^2} y^2 + \frac{\partial_u (V^2)}{V^2} \sum_{i=1}^{3} x_i^2 \right].
\] (3.5)

Substituting these we get the Brinkman form of the PP-wave as

\[
\frac{ds^2}{\alpha^2} = 2du dv + (F_1 y^2 + F_2 x_i^2 - \mu^2 \zeta^2 l^2) du^2 + dy^2 + \sum_{i=1}^{3} dx_i^2 + d\bar{z}^2,
\]
\[
F_{\mu y x_1 x_2 x_3} = -4\mu l,
\] (3.6)
where
\[
F_1 = \frac{1}{2} \left[ \partial_u \left\{ \frac{\partial_u(1-\ell^2 V^2)}{1-\ell^2 V^2} \right\} + \frac{1}{2} \left\{ \partial_u(1-\ell^2 V^2) \right\} \right]^2,
\]
\[
F_2 = \frac{1}{2} \left[ \partial_u \left\{ \frac{\partial_u V^2}{V^2} \right\} + \frac{1}{2} \left\{ \frac{\partial_u (V^2)}{V^2} \right\} \right]^2.
\] (3.7)

This form is similar to the form that is obtained by taking a Penrose limit on the geometry of a stack of N D3-branes in the near horizon limit. String propagation in this background has been studied in detail [8]. The main output of this section is that the very complicated metric (2.5) reduces to a well known form in the Penrose limit. That signifies that when we consider the deformation term to be small, the local geometry will behave like AdS$_5 \times S^5$ to a local observer on the geodesic mentioned in this section. In the next section we will be interested in finding solutions of the string equation of motion in the semiclassical limit in the background (2.5).

4 Semiclassical string solutions

If we neglect $V^4$ term in (2.5), then the metric simply takes the form of AdS$_5 \times S^5$, for which the rigidly rotating string solutions are well studied. It would be interesting if we can find string solutions by keeping the first order term in $V^4$. By rescaling, $t \to \Delta C \frac{1}{2} t$, $x_i \to \Delta C \frac{1}{2} x_i$ and substituting $V = \frac{1}{\Delta} W C^2$, we get
\[
\frac{ds^2}{\alpha'} = C \left[ W^2 \left( -dr^2 + \sum_{i=1}^{3} dx_i^2 \right) + \frac{dW^2}{W^2} \right.
\]
\[
+ 2 W^4 \sin^2 \theta \csc^2 \phi \left( \cos^2 \phi \, d\phi_1 + \sin^2 \phi \, d\phi_2 \right) \right.
\]
\[
+ d\theta^2 + \cos^2 \phi \left( \sin^2 \phi \, d\phi_1^2 + \sin^2 \phi \, d\phi_2^2 \right), \]
\[
A_{\alpha''} = -C W^4 \, dt \wedge dx_1 \wedge dx_2 \wedge dx_3. \] (4.1)

It is very hard to solve the equations of motion for the fundamental string in the above background (4.1), since they lead to highly non-linear coupled differential equations. However, we can simplify and consider a less general geometry than (4.1) by putting $W = W_0$ and $\theta = \theta_0$. For these values, the metric (4.1) becomes
\[
\frac{ds^2}{\alpha''} = C \left[ W_0^2 \left( -dr^2 + \sum_{i=1}^{3} dx_i^2 \right) + 2 W_0^4 \sin^2 \phi \left( \cos^2 \phi \, d\phi_1^2 + \sin^2 \phi \, d\phi_2^2 \right) \right.
\]
\[
\times \left( \cos^2 \theta_0 \, d\phi_1 + \sin^2 \theta_0 \, d\phi_2 \right) \right.
\]
\[
+ \sin^2 \phi \left( \cos^2 \theta_0 \, d\phi_1^2 + \sin^2 \theta_0 \, d\phi_2^2 \right), \] (4.2)

where $W_0$ and $\theta_0$ are constants. In the following analysis we will keep the terms up to $O(W_0^4)$ only. It can be noted that making the coordinates $W$ and $\theta$ constant will certainly impose some non-trivial constraints on the string solutions in this background. We will, however, show that these constraints merely reduce to some relations between the various constants mentioned in the worksheet embedding of our choice.

4.1 Rigidly rotating strings

We start our analysis by writing down the Polyakov action of the F-string in the background (4.2),
\[
S = -\frac{1}{4\pi \alpha'} \int d\sigma d\tau \left( \sqrt{-\gamma} \gamma^{\alpha \beta} g_{MN} \partial_\alpha X^M \partial_\beta X^N \right), \] (4.3)

where $\gamma^{\alpha \beta}$ is the world-sheet metric. In a conformal gauge (i.e. $\sqrt{-\gamma} \gamma^{\alpha \beta} = \eta^{\alpha \beta}$) with $\eta^{\tau \tau} = -1$, $\eta^{\sigma \sigma} = 1$ and $\eta^{i j} = 0$, the Polyakov action in the above background takes the form
\[
S = -\frac{\sqrt{\lambda}}{4\pi} \int d\sigma d\tau \left[ W_0^2 \left( -(t'^2 - i^2) + x_1^2 - x_2^2 \right) \right.
\]
\[
+ \left. \sin^2 \theta \csc^2 \phi \left( \sin^2 \phi \, d\phi_1^2 + \sin^2 \phi \, d\phi_2^2 \right) \right], \] (4.4)

where ‘dots’ and ‘primes’ denote the derivative with respect to $\tau$ and $\sigma$, respectively; also we have ‘t’ Hooft coupling $\sqrt{\lambda} = C$. For studying the rigidly rotating strings in this background we choose the following ansatz:
\[
\tau = \tau + h_0(y), \quad x_i = x_i(\tau + h_i(y)), \quad \phi_1 = \omega_1(\tau + g_1(y)), \quad \phi_2 = \omega_2(\tau + g_2(y)),
\]
\[
\psi = \omega_3(\tau + g_3(y)), \] (4.5)

where $y = \sigma - \nu \tau$. Variation of the action with respect to $X^M$ gives us the following equation of motion:
\[
2\partial_M (\eta^{\alpha \beta} \partial_\beta X^N g_{KN}) - \eta^{\alpha \beta} \partial_\alpha X^M \partial_\beta X^N \partial_\gamma g_{MN} = 0, \] (4.6)

and variation with respect to the metric gives the two Virasoro constraints,
\[
g_{MN}(\partial_\tau X^M \partial_\tau X^N + \partial_\sigma X^M \partial_\sigma X^N) = 0,
\]
\[
g_{MN}(\partial_\tau X^M \partial_\sigma X^N) = 0. \] (4.7)

Next we have to solve these equations by the ansatz we have proposed above in (4.5). Solving for $t$, $\phi_1$, and $\phi_2$ we get
\[-\frac{\partial h_0}{\partial y} + \omega_1 W_0^2 \cos^2 \theta_0 \sin^2 \xi \frac{\partial g_1}{\partial y} + \omega_2 W_0^2 \sin^2 \theta_0 \sin^2 \xi \frac{\partial g_2}{\partial y} \]
\[= \frac{1}{1 - u^2} \{ c_4 - v W_0^2 \sin^2 \xi \{ \omega_1 \cos^2 \theta_0 + \omega_2 \sin^2 \theta_0 \} \}, \]
\[W_0^4 \sin^2 \xi \frac{\partial h_0}{\partial y} + \omega_1 \sin^2 \xi \frac{\partial g_1}{\partial y} \]
\[= \frac{1}{1 - u^2} \{ c_5 - v \sin^2 \xi (\omega_1 + W_0^4) \}, \]
\[W_0^4 \sin^2 \xi \frac{\partial h_0}{\partial y} + \omega_2 \sin^2 \xi \frac{\partial g_2}{\partial y} \]
\[= \frac{1}{1 - u^2} \{ c_6 - v \sin^2 \xi (\omega_2 + W_0^4) \}, \quad (4.8) \]
where \( c_4, c_5, \) and \( c_6 \) are integration constants. Solving (4.8), we get
\[
\frac{\partial h_0}{\partial y} = \frac{1}{1 - u^2} \{ W_0^2 (c_5 \cos^2 \theta_0 + c_6 \sin^2 \theta_0) - c_4 \},
\]
\[
\frac{\partial g_1}{\partial y} = \frac{1}{1 - u^2} \left[ \frac{1}{\omega_1} \left\{ \frac{c_5}{\sin^2 \xi} - W_0^4 (v - c_4) \right\} - v \right],
\]
\[
\frac{\partial g_2}{\partial y} = \frac{1}{1 - u^2} \left[ \frac{1}{\omega_2} \left\{ \frac{c_6}{\sin^2 \xi} - W_0^4 (v - c_4) \right\} - v \right]. \quad (4.9) \]
Solving for \( \psi \) and \( \chi_i \), respectively, we get
\[
\frac{\partial g_3}{\partial y} = \frac{1}{1 - u^2} \left[ \frac{c_7}{\cos^2 \xi} - v \right], \quad \frac{\partial h_1}{\partial y} = c_i, \quad (4.10) \]
where \( c_7 \) and \( c_i \) (\( i = 1, 2, 3 \)) are integration constants. As discussed before, putting \( W \) and \( \theta \) as constants generates some confining constraint equations from the equations of motion for \( W \) and \( \theta \). These constraint equations in this case can be written as
\[W_0^2 \sin^2 \xi (\omega_1 \cos^2 \theta_0 + \omega_2 \sin^2 \theta_0) \]
\[= (W_0^2 d_1 + v - c_4) (3 W_0^2 d_1 - v + c_4) \]
\[+ 1 - (1 - v^2) v_i^2 (1 - v c_i) \]
\[= \sin^2 \xi (\omega_1 \cos^2 \theta_0 + \omega_2 \sin^2 \theta_0) \]
\[= c_i^2 - 0^2 = 2 W_0^4 (v - c_i), \quad (4.11) \]
where \( d_1 = c_5 \cos^2 \theta_0 + c_6 \sin^2 \theta_0 \). These constraints (4.11) will imply \( \xi = \text{constant} \), which is a trivial solution. To have a non-trivial solution for strings in this supergravity PFT background, we must put
\[\omega_1 \cos^2 \theta_0 + \omega_2 \sin^2 \theta_0 = 0, \quad c_5 = c_6. \quad (4.12) \]
Using (4.12), (4.11) can be put in the form
\[W_0^2 c_5 + v - c_4) (3 W_0^2 c_5 - v + c_4) + 1 \]
\[= (1 - v^2) v_i^2 (1 - v c_i) \]
\[\omega_1 + \omega_2 = -2 W_0^4. \quad (4.13) \]
Since the above equations confine our parameter space non-trivially, we have to be careful in our approach for analyzing string solutions. As a check we can see that using the conditions mentioned in (4.12) and solving for \( \xi \) we get
\[(1 - v^2)^2 \frac{\partial^2 \xi}{\partial y^2} = \sin \xi \cos \xi \left[ \frac{c_5^2}{\sin^4 \xi} - \frac{2 \omega_1^2}{\cos^2 \xi} - \omega_2^2 \right]. \quad (4.14) \]
where \( \omega_2^2 = \omega_1^2 \cos^2 \theta_0 + \omega_2^2 \sin^2 \theta_0 - \omega_3^2 \). Integrating (4.14), we get
\[(1 - v^2)^2 \left( \frac{\partial \xi}{\partial y} \right)^2 = -\frac{c_5^2}{\sin^2 \xi} - \frac{2 \omega_1^2}{\cos^2 \xi} - \omega_2^2 \sin^2 \xi + c_8. \quad (4.15) \]
where \( c_8 \) is integration constant. For self consistency of the solution, (4.15) will have to be properly supplemented by the two Virasoro constraints.
The Virasoro constraint \( g_{MN} (\partial_t X^M \partial_\sigma X^N) = 0 \) in this case will become
\[(1 - v^2)^2 \left( \frac{\partial \xi}{\partial y} \right)^2 = W_0^2 (W_0 c_5 - c_4)^2 \]
\[+ \frac{1 - v^2}{v} W_0^2 (W_0 c_5 - c_4) + (1 - v^2)^2 W_0^2 v_i^2 c_i \]
\[+ (1 - v^2)^2 W_0^2 v_i^2 c_i^2 - \omega_3^2 \cos^2 \xi \]
\[= \sin^2 \xi (\omega_1 \cos^2 \theta_0 + \omega_2 \sin^2 \theta_0) - \frac{c_5^2}{\sin^2 \xi} - \frac{2 \omega_1^2}{\cos^2 \xi} - \omega_2^2 \]
\[+ 2 W_0^4 (v - c_4) c_5 + \frac{1 - v^2}{v} W_0^4 c_5 \]
\[+ 2 W_0^4 c_4 c_5 + \left( \frac{1 - v^2}{v} \right) c_7 \omega_3^2. \quad (4.16) \]
Again the Virasoro \( g_{MN} (\partial_t X^M \partial_\sigma X^N + \partial_\sigma X^M \partial_t X^N) = 0 \) becomes
\[(1 - v^2)^2 \left( \frac{\partial \xi}{\partial y} \right)^2 = W_0^2 (W_0 c_5 - c_4)^2 \]
\[+ \frac{1 - v^2}{1 + v^2} W_0^2 [1 - v^2 - 2 v (W_0 c_5 - c_4)] \]
\[+ (1 - v^2)^2 W_0^2 v_i^2 c_i^2 - \frac{(1 - v^2)^2}{1 + v^2} W_0^2 v_i^2 (1 - v c_i) \]
\[- \omega_3^2 \cos^2 \xi - \sin^2 \xi (\omega_1 \cos^2 \theta_0 + \omega_2 \sin^2 \theta_0) \]
\[= \frac{c_5^2}{\sin^2 \xi} - \frac{2 \omega_1^2}{\cos^2 \xi} - \omega_2^2 \]
\[+ 2 W_0^4 (v - c_4) c_5 + v (1 - v^2) W_0^4 c_5 \]
\[+ W_0^4 c_4 c_5 + \left( \frac{4 v}{1 + v^2} \right) c_7 \omega_3^2. \quad (4.17) \]
Subtracting these two Virasoro constraints we get another relation between the constants:
\[c_7 \omega_3^2 + W_0^2 v_i^2 (1 - v^2) c_i + v - W_0^2 (v - c_4) \]
\[+ W_0^4 v^2 (1 - v^2)^2 + c_4 v (1 + v^2) \]
\[= 0. \quad (4.18) \]
Note that from (4.16), if we identify
\[
c_8 = W_0^2(W_0^2c_5 - c_4)^2 + 2W_0^4vc_5 + \frac{1 - v^2}{v}W_0^2c_4 + (1 - v^2)^2W_0^2v_i \left( \frac{c_i}{v} - c_i^2 \right) - \omega_3^2 + \frac{1 + v^2}{v}\omega_2^2c_7,\]
(4.19)
then (4.16) is consistent with the equation of motion (4.15). To summarize, (4.13) and (4.18) give the desired constraint equations for the string solutions in the background (4.2). Since these constraints are highly non-linear in the parameters, it can be clearly stated that our rotating string solutions are valid only in a highly confined parameter space.

Since we are interested in infinite angular momenta solutions we can consider the limit \(\frac{\partial \varphi}{\partial y} \to 0\) as \(\zeta \to \frac{\pi}{2}\), which in (4.15) implies \(c_7 = 0\) and \(c_8 = c_5^2 + \omega^2\). Substituting this in the above equation we get
\[
\frac{\partial \zeta}{\partial y} = \frac{\omega \cot \zeta}{1 - v^2}\sqrt{\sin^2 \zeta - \sin^2 \zeta_0},
\]
(4.20)
where \(\sin \zeta_0 = \frac{c_5}{\omega}\). Looking at the symmetry of the background (4.2), a number of conserved charges can be constructed as follows:
\[
E = -\int \frac{\partial L}{\partial \dot{\varphi}} d\sigma = \frac{\sqrt{\lambda}}{2\pi} \frac{W_0^2}{1 - v^2} \left[ (1 - v^2 + vc_4) \right] \int d\sigma,
\]
\[
P_l = \int \frac{\partial L}{\partial \dot{x}_l} d\sigma = \frac{\sqrt{\lambda}}{2\pi} v_i W_0^2 \int \cos^2 \zeta d\sigma,
\]
\[
J_\varphi = \int \frac{\partial L}{\partial \dot{\varphi}} d\sigma = \frac{\sqrt{\lambda}}{2\pi} \frac{\omega_3}{1 - v^2} \int \cos^2 \zeta d\sigma,
\]
\[
J_{\varphi_1} = \int \frac{\partial L}{\partial \dot{\varphi}_1} d\sigma = \frac{\sqrt{\lambda}}{2\pi} \frac{\cos^2 \theta_0}{1 - v^2} \int \left[ (\omega_1 + W_0^4) \sin^2 \zeta - vc_5 \right] d\sigma,
\]
\[
J_{\varphi_2} = \int \frac{\partial L}{\partial \dot{\varphi}_2} d\sigma = \frac{\sqrt{\lambda}}{2\pi} \frac{\sin^2 \theta_0}{1 - v^2} \int \left[ (\omega_2 + W_0^4) \sin^2 \zeta - vc_5 \right] d\sigma.
\]
(4.21)
Also the deficit angles are given by
\[
\Delta \varphi_1 = \omega_1 \int \frac{\partial g_1}{\partial y} d\sigma = \frac{1}{1 - v^2} \int \left[ \frac{-c_5}{\sin^2 \zeta} - W_0^4(v - c_4) - vc_1 \right] d\sigma,
\]
\[
\Delta \varphi_2 = \omega_2 \int \frac{\partial g_2}{\partial y} d\sigma = \frac{1}{1 - v^2} \int \left[ \frac{-c_5}{\sin^2 \zeta} - W_0^4(v - c_4) - vc_2 \right] d\sigma.
\]
(4.22)
For our convenience, we will use the combined angular momenta and deficit angles as
\[
J_\varphi = J_{\varphi_1} + J_{\varphi_2} = \frac{\sqrt{\lambda}}{2\pi} \frac{1}{1 - v^2} \int \left( W_0^4 \sin^2 \zeta - vc_5 \right) d\sigma
\]
\[
\Delta \varphi = \frac{\Delta \varphi_1 + \Delta \varphi_2}{2} = \frac{1}{1 - v^2} \int \left[ \frac{c_5}{\sin^2 \zeta} - \frac{c_4(\omega_1 + \omega_2)}{2} \right] d\sigma.
\]
(4.23)
In what follows, we will find relations among various charges in different limiting cases. Since some of the charges in 4.21 are divergent, we will use a particular type of regularization technique to extract the relations.

4.1.1 Case I: giant magnons
For this case, we choose \(c_5 = \frac{c_4(\omega_1 + \omega_2)}{2}\), and the angle deficit becomes
\[
\Delta \varphi = \frac{2c_5}{\omega} \int_{\zeta_0}^{\frac{\pi}{2}} \frac{\cos \zeta d\zeta}{\sin \zeta \sqrt{\sin^2 \zeta - \sin^2 \zeta_0}} = 2 \arccos(\sin \zeta_0),
\]
(4.24)
which implies \(\sin \zeta_0 = \cos \left( \frac{\Delta \varphi}{2} \right) \). In this condition the expression of energy and linear momenta \(P_i\) can be written as
\[
E = \frac{\sqrt{\lambda}}{\pi} \frac{W_0^2}{\omega} \left[ 1 - v^2 + vc_4 \right] \int_{\zeta_0}^{\frac{\pi}{2}} \frac{\sin \zeta d\zeta}{\cos \zeta \sqrt{\sin^2 \zeta - \sin^2 \zeta_0}},
\]
\[
P_i = \frac{\sqrt{\lambda}}{\pi} \frac{W_0^2 v_i}{\omega} (1 - v^2)(1 - vc_4) \int_{\zeta_0}^{\frac{\pi}{2}} \frac{\sin \zeta d\zeta}{\cos \zeta \sqrt{\sin^2 \zeta - \sin^2 \zeta_0}}.
\]
(4.25)
It can be seen that these expressions are divergent. But looking at the other charges in this case we find that
\[
J_\varphi = \frac{\sqrt{\lambda}}{\pi} \frac{\omega_3}{\omega} \cos \zeta_0
\]
(4.26)
is finite, while the combined angular momentum can be written as
\[
J_\varphi = \frac{\sqrt{\lambda}}{\pi} \frac{W_0^4 - vc_5}{\omega} \int_{\zeta_0}^{\frac{\pi}{2}} \frac{\sin \zeta d\zeta}{\cos \zeta \sqrt{\sin^2 \zeta - \sin^2 \zeta_0}} - \frac{\sqrt{\lambda}}{\pi} \frac{W_0^4}{\omega} \int_{\zeta_0}^{\frac{\pi}{2}} \frac{\sin \zeta \cos \zeta d\zeta}{\sqrt{\sin^2 \zeta - \sin^2 \zeta_0}}.
\]
(4.27)
It is clear that \(J_\varphi\) also diverges due to the first integral. Now we follow the regularization scheme outlined in [34], for example. Let us define the divergent quantity
\[
\tilde{E} = \frac{W_0^4}{W_0^2 \left[ 1 - v^2 + vc_4 + v_i (1 - v^2)(1 - vc_i) \right]} \times \left( E + \frac{1}{3} \sum P_i \right).
\]
(4.28)
Thus we can write
\[
E - J_\phi = \sqrt{\frac{\lambda}{\pi}} \frac{W_0^4}{\omega} \cos \zeta_0, \tag{4.29}
\]
which is a finite quantity. It can easily be shown that the above mentioned conserved charges obey a dispersion relation among them of the form
\[
E - J_\phi = \sqrt{\frac{\Delta}{\pi}} f(\zeta) \sin^2 \left( \frac{\Delta \phi}{2} \right), \tag{4.30}
\]
where \( f(\zeta) = \frac{\lambda}{\pi} \frac{W_0^4 - \omega_0^2}{\omega^2} \). The above relation is analogous to the two spin giant magnon dispersion relation.

### 4.1.2 Case II: Single Spike solution

For this case, choosing \( c_s = \frac{c_s(\omega_0 + \omega_2)}{2\pi^2} \), we see that the deficit angle
\[
\Delta \phi = \frac{2c_s}{\omega} \left[ (1 - v^2) \int_x^{\zeta_0} \frac{\sin \zeta d\zeta}{\cos \zeta \sqrt{\sin^2 \zeta - \sin^2 \zeta_0}} + \int_x^{\zeta_0} \cos \zeta \sqrt{\sin^2 \zeta - \sin^2 \zeta_0} \right] \tag{4.31}
\]
diverges due to the first integral. The energy \( E \) and linear momenta \( P_i \) also diverge as in the previous case. Here again we will use the divergent combination of the form
\[
E + \frac{1}{3} \sum P_i = \sqrt{\frac{\lambda}{\pi}} \frac{W_0^4}{\omega} \left[ 1 - v^2 + \nu c_i + v_i (1 - v^2)(1 - v c_i) \right] \int_x^{\zeta_0} \frac{\sin \zeta d\zeta}{\cos \zeta \sqrt{\sin^2 \zeta - \sin^2 \zeta_0}}. \tag{4.32}
\]
The other conserved charges are given by
\[
J_\phi = \sqrt{\frac{\lambda}{\pi}} \frac{W_0^4}{\omega} - \nu c_5 \int_x^{\zeta_0} \frac{\sin \zeta d\zeta}{\cos \zeta \sqrt{\sin^2 \zeta - \sin^2 \zeta_0}} - \frac{\sqrt{\lambda}}{\pi} \omega_0 \int_x^{\zeta_0} \frac{\sin \zeta \cos \zeta d\zeta}{\sin^2 \zeta - \sin^2 \zeta_0}, \tag{4.33}
\]
which also are diverging due to the first integral and
\[
J_\psi = -\frac{\sqrt{\lambda}}{\pi} \frac{\omega_0}{\omega} \cos \zeta_0 \tag{4.34}
\]
is finite as before. Now we can regularize the value of \( \Delta \phi \) by subtracting out the divergent part,
\[
(\Delta \phi)_{\text{reg}} = \Delta \phi - \frac{2\pi c_5 (1 - v^2)}{\sqrt{\lambda} W_0^2} \left[ 1 - v^2 + \nu c_i + v_i (1 - v^2)(1 - v c_i) \right] \times \left( E + \frac{1}{3} \sum P_i \right)
\]
\[
= -2 \arccos(\sin \zeta_0), \tag{4.35}
\]
which implies \( \sin \zeta_0 = \cos \left( \frac{\Delta \phi_{\text{reg}}}{2} \right) \). Again we write the regularized value of \( J_\phi \) as
\[
(\lambda_\phi)_{\text{reg}} = J_\phi - \frac{W_0^4}{\omega} \left[ 1 - v^2 + \nu c_5 + v_i (1 - v^2)(1 - v c_i) \right] \times \left( E + \frac{1}{3} \sum P_i \right),
\]
\[
= \sqrt{\frac{\lambda}{\pi}} \frac{W_0^4}{\omega} \cos \zeta_0. \tag{4.36}
\]
We can see that the constants of motion satisfy the following dispersion relation:
\[
(\lambda_\phi)_{\text{reg}} = \sqrt{\frac{J_\psi^2 + f(\zeta) \sin^2 \left( \frac{\Delta \phi_{\text{reg}}}{2} \right)}{2}}, \tag{4.37}
\]
where \( f(\zeta) = \frac{\lambda}{\pi} \frac{W_0^4 - \omega_0^2}{\omega^2} \). This looks like the spiky string dispersion relation presented in [37].

### 4.2 Rotating and pulsating strings with two equal spins

In this section we will focus on a class of ‘long’ semiclassical strings which are both pulsating and rotating in the background (2.5). Here we follow a simple procedure for our analysis as in [52] for example. We again put \( W = W_0 \) and \( \theta = \frac{\pi}{2} \) for simplicity in the metric and keep terms up to \( W_0^4 \) in keeping with our approximation as before. The resulting metric is
\[
\frac{ds^2}{\sigma^2} = C \left[ \frac{W_0^2}{2} \left( -dt^2 + \sum (dx^i)^2 \right) + d\sigma^2 + \cos^2 \zeta d\psi^2 \right.
\]
\[
+ \frac{1}{2} \sin^2 \zeta (d\phi_1^2 + d\phi_2^2) + W_0^4 \sin^2 \zeta dt (d\phi_1 + d\phi_2) \right]. \tag{4.38}
\]
We shall look for string propagation in this background using the following ansatz:
\[
\tau = \tau(\tau), \quad x_i = x_i(\tau), \quad \psi = \psi(\tau), \quad \zeta = \zeta(\tau),
\]
\[
\phi_1 = \phi_1(\tau) + m_1 \sigma, \quad \phi_2 = \phi_2(\tau) + m_2 \sigma. \tag{4.39}
\]
Again we have to show that the above embedding is self-consistent with the constraint equations as in the case before. To check this, we start by solving the equations of motion using the ansatz above. Solving the \( \tau \) equation of motion we get
\[
\ddot{\tau} = \frac{W_0^2}{2} \partial_\tau \{ (\phi_1 + \phi_2) \sin^2 \zeta \}. \tag{4.40}
\]

\[1\] Recently more generalized rotating and pulsating strings have been studied in [53].
Solving for $\phi_1$ and $\phi_2$, respectively, we get

$$\dot{\phi}_1 = \frac{c_5}{\sin^2\zeta} - W_0^4 i,$$

$$\dot{\phi}_2 = \frac{c_6}{\sin^2\zeta} - W_0^4 i,$$  \hfill (4.41)

where $c_5$ and $c_6$ are integration constants. Substituting the values of $\dot{\phi}_1$ and $\dot{\phi}_2$ from (4.41) into (4.40) we get

$$\dot{i} = 0 \Rightarrow i = c_4,$$  \hfill (4.42)

where $c_4$ is the integration constant. Solving for $x_i$ and $\psi$ we get

$$\dot{x}_i = c_i, \quad \dot{\psi} = \frac{c_7}{\cos^3\zeta}.$$  \hfill (4.43)

Thus the equations for $W$ and $\theta$ generate the constraints

$$c_4^2 - \sum c_i^2 = 2W_0^2c_4(c_5 + c_6),$$

$$\frac{c_5^2 - c_6^2}{\sin^4\zeta} = m_1^2 - m_2^2.$$  \hfill (4.44)

For the same reason as discussed in the previous section we must impose the constraint $c_5 = c_6$, which implies $m_1^2 = m_2^2$. These conditions merely point out that $\phi_1 = \phi_2$ (i.e. the corresponding angular momenta are equal) and fix the values of $c_5$ and $c_6$ from the above equations. Substituting these conditions into the $\zeta$ equation we get

$$\frac{d^2\zeta}{dt^2} = \sin \zeta \cos \zeta \left[ -\frac{c_7^2}{\cos^4\zeta} + \frac{c_5^2}{\sin^4\zeta} - m_1^2 \right].$$  \hfill (4.45)

Integrating the above we arrive at

$$\left( \frac{d\zeta}{dt} \right)^2 = -\frac{c_7^2}{\cos^2\zeta} - \frac{c_5^2}{\sin^2\zeta} - m_1^2 \sin^2 \zeta + c_8,$$  \hfill (4.46)

where $c_8$ is an integration constant. Now looking at the isometries of the background, we can evaluate the constants of motion from the action as

$$E = \sqrt{\lambda}E = \sqrt{\lambda} \left[ W_0^2 i - \frac{1}{2} W_0^4 \sin^2 \zeta (\phi_1 + \phi_2) \right],$$

$$P_i = \sqrt{\lambda}P_i = \sqrt{\lambda} W_0^2 \dot{x}_i,$$

$$J_{\phi_1} = \sqrt{\lambda} J_{\phi_1} = \sqrt{\lambda} \sin^2 \zeta \left[ \dot{\phi}_1 + W_0^4 i \right],$$

$$J_{\phi_2} = \sqrt{\lambda} J_{\phi_2} = \sqrt{\lambda} \sin^2 \zeta \left[ \dot{\phi}_2 + W_0^4 i \right],$$

$$J_{\psi} = \sqrt{\lambda} J_{\psi} = \sqrt{\lambda} \cos^2 \zeta \dot{\psi}.$$  \hfill (4.47)

Also we can see that the second Virasoro constraint in this case implies that

$$m_1 J_{\phi_1} + m_2 J_{\phi_2} = 0.$$  \hfill (4.48)

Since in this calculation we will be interested in the subset of solutions which have two equal spins i.e.

$$J_{\phi_1} = J_{\phi_2}, \quad \Rightarrow m_1 = -m_2 = m.$$  \hfill (4.49)

We can see that this is in perfect agreement with (4.44), thus making our solutions completely consistent. The first Virasoro constraint gives the evolution equation for $\zeta$

$$\dot{\zeta}^2 = W_0^4 (i^2 - \dot{x}_i^2) - \cos^2 \zeta \dot{\psi}^2 - \frac{1}{2} \sin^2 \zeta \left[ \dot{\phi}_1^2 + \dot{\phi}_2^2 + 2W_0^4 (\phi_1 + \phi_2) i + 2m_1^2 \right],$$  \hfill (4.50)

which can be shown to be exactly equivalent to (4.46) with putting in the values and the identification $c_8 = W_0^4 (i^2 - \dot{x}_i^2) = W_0^4 (c_4^2 - \sum c_i^2)$. So, in this case we note that the constraint equations (4.44) are satisfied completely without restricting our parameter space non-trivially as before.

Putting in the values from (4.47) into (4.50), we get

$$\dot{\zeta}^2 = \frac{\tilde{E}^2}{W_0^2} - \frac{\tilde{J}_{\psi}^2}{\cos^2 \zeta} - \frac{\tilde{J}_0^2}{\sin^2 \zeta} - m_1^2 \sin^2 \zeta,$$  \hfill (4.51)

where $\tilde{E}^2 = E^2 - \sum P_i^2 + 2W_0^6 (J_{\phi_1} + J_{\phi_2})$ and $\tilde{J}_0^2 = 2(\tilde{J}_{\phi_1}^2 + \tilde{J}_{\phi_2}^2)$, so that $\tilde{J}$ is a real quantity. Now the equation of motion for $\zeta$ looks like the classical equation for a particle moving in a potential. Notice that the potential here grows to infinity at both $\zeta = 0$ as well as $\zeta = \frac{\pi}{2}$. So the functional form suggests an infinite potential well with a minimum in between the extrema. The $\zeta$ coordinate must then oscillate in this well between a maximum and minimum value. We define the oscillation number for the system as

$$\mathcal{N} = \frac{1}{2\pi} \int d\zeta \dot{\zeta},$$

\[ \begin{align*}
= \frac{1}{\pi} \int_{\zeta_{\text{min}}}^{\zeta_{\text{max}}} d\zeta \sqrt{\frac{\tilde{E}^2}{W_0^2} - \frac{\tilde{J}_{\psi}^2}{\cos^2 \zeta} - \frac{\tilde{J}_0^2}{\sin^2 \zeta} - m_1^2 \sin^2 \zeta},
\end{align*} \]

(4.52)

with $\mathcal{N} = \frac{\mathcal{N}}{\sqrt{\lambda}}$ being an adiabatic invariant, which should have integer values in the usual quantum theory. Putting $\sin \zeta = x$ into the integral for the oscillation number, we get

$$\mathcal{N} = \frac{1}{\pi} \int_{\sqrt{\lambda}}^{\sqrt{\lambda}} \frac{dx}{1 - x^2} \times \sqrt{\frac{\tilde{E}^2}{W_0^2}(1 - x^2) - \frac{\tilde{J}_{\psi}^2}{x^2} - \frac{\tilde{J}_0^2(1 - x^2)}{x^2} - m_1^2 x^2 (1 - x^2)},$$  \hfill (4.53)
where $R_1$ and $R_2$ are two positive appropriate roots of the polynomial
\[
g(z) = m^2 z^3 + \left( -\frac{E^2}{W_0^2} - m^2 \right) z^2 \\
+ \left( \frac{E^2}{W_0^2} + \mathcal{J}^2 - \mathcal{J}_\psi^2 \right) z - \mathcal{J}^2, \quad z = x^2.
\] (4.54)

Naturally, we will be interested in the region of parameter space where the roots to the above polynomial are real. Now taking the partial derivative of $\mathcal{N}$ w.r.t. $m$ we get
\[
\frac{\partial \mathcal{N}}{\partial m} = -\frac{m}{\pi} \int_{\sqrt{R_1}}^{\sqrt{R_2}} \frac{x^3}{\sqrt{E^2 (1 - x^2) - \mathcal{J}^2 + \mathcal{J}_\psi^2 - \mathcal{J}^2 (1 - x^2)}} dx.
\] (4.55)

Now, to find the roots of the polynomial $g(z)$ we do an approximate analysis. In the large $\tilde{E}$ but small $\mathcal{J}$ and $\mathcal{J}_\psi$ limit, we can find the three distinct roots:
\[
\alpha_1 = -\frac{E^2}{m W_0^2} + \frac{W_0^2 \mathcal{J}^2 - \mathcal{J}^2}{E^2} + \mathcal{O} \left[ W_0^4 \tilde{E}^-4 \right], \\
\alpha_2 = \frac{W_0^2 \mathcal{J}^2}{E^2} + \mathcal{O} \left[ W_0^4 \tilde{E}^-4 \right], \\
\alpha_3 = 1 - \frac{W_0^2 \mathcal{J}^2}{E^2} + \mathcal{O} \left[ W_0^4 \tilde{E}^-4 \right].
\] (4.56)

Clearly we can see that $0 \leq x^2 \leq 1$, so in the large $\tilde{E}$ limit, we choose the appropriate upper and lower limit to the integral accordingly. Putting $x^2 = z$ we write the integral as
\[
\frac{\partial \mathcal{N}}{\partial m} = -\frac{m}{\pi} \int_{\sqrt{\alpha_1}}^{\sqrt{\alpha_2}} \frac{z}{\sqrt{m^2 z^3 + \left( -\frac{E^2}{W_0^2} - m^2 \right) z^2 + \left( \frac{E^2}{W_0^2} + \mathcal{J}^2 - \mathcal{J}_\psi^2 \right) z - \mathcal{J}^2}} dz.
\] (4.57)

Using standard integral tables we can transform this into a combination of the usual elliptic integrals of the first and second kind as
\[
\frac{\partial \mathcal{N}}{\partial m} = -\frac{m}{\pi} \frac{1}{\sqrt{\alpha_1 - \alpha_2}} \times \left[ \alpha_1 \mathbf{K} \left( \frac{\alpha_3 - \alpha_2}{\alpha_1 - \alpha_2} \right) - \left( \alpha_1 - \alpha_2 \right) \mathbf{E} \left( \frac{\alpha_3 - \alpha_2}{\alpha_1 - \alpha_2} \right) \right].
\] (4.58)

We expand the equation again in the large $\tilde{E}$ but small $\mathcal{J}$ and $\mathcal{J}_\psi$ limits to get
\[
\frac{1}{W_0} \frac{\partial \mathcal{N}}{\partial m} = c_1 m^2 \tilde{E}^{-1} + c_2 m^4 \tilde{E}^{-3} \\
\times \left[ c_3 + \frac{\mathcal{J}^2 - \mathcal{J}_\psi^2}{m^2} \right],
\] (4.59)

where the numerical constants are given by $c_1 = c_2 = -0.25$ and $c_3 = 0.375$. Integrating this equation we get a series for $\mathcal{N}$,
\[
\mathcal{N} = \mathcal{N}_0 + \frac{c_1}{3} m^2 W_0 \tilde{E}^{-1} + \frac{c_2}{5} m^5 W_0 \tilde{E}^{-3} \\
\times \left[ c_3 + \frac{5}{3} \frac{\mathcal{J}^2 - \mathcal{J}_\psi^2}{m^2} \right] + \mathcal{O} \left[ W_0^5 \tilde{E}^{-5} \right].
\] (4.60)

The integration constant $\mathcal{N}_0$ can be evaluated by considering the integral for $m = 0$, i.e.
\[
\mathcal{N}_0 = \frac{1}{\pi} \int_{\beta_1}^{\beta_2} \frac{dx}{1 - x^2} \\
\times \frac{\sqrt{\frac{E^2}{W_0^2} \left( 1 - x^2 \right) + \mathcal{J}^2 \left( 1 - \frac{1}{x^2} \right)} - \mathcal{J}_\psi^2}{-2 \frac{E^2}{W_0^2} \mathcal{J}_\psi^2},
\] (4.61)

where the limits are given by
\[
\beta_2^2 = \beta_1^2 + \left( \frac{E^2}{W_0^2} + \mathcal{J}^2 - \mathcal{J}_\psi^2 \right) \pm \sqrt{\left( \frac{E^2}{W_0^2} + \mathcal{J}^2 - \mathcal{J}_\psi^2 \right)^2 - 4 \frac{E^2}{W_0^2} \mathcal{J}^2}.
\] (4.62)

Now using $\frac{E^2}{W_0^2} + \mathcal{J}^2 - \mathcal{J}_\psi^2$ and changing the variable, we transform the integral to
\[
\mathcal{N}_0 = \frac{\beta_1}{\pi} \int_{\beta_1}^{\beta_2} \frac{dx}{1 - \beta_1^2 x^2} \\
\times \frac{\sqrt{\frac{E^2}{W_0^2} \mathcal{J}_\psi^2 \left( 1 - x^2 \right) + \mathcal{J}_\psi^2 \left( 1 - \frac{1}{x^2} \right)}} = \frac{1}{2} \left( \frac{\tilde{E}}{W_0} - \mathcal{J} + \mathcal{J}_\psi \right).
\] (4.63)

We put back this value and then, by reverting the series, we get
\[
\frac{\tilde{E}}{W_0} = 2 \mathcal{N} + \left( \mathcal{J} - \mathcal{J}_\psi \right) + a_1 m^2 \mathcal{N}^{-1} - a_2 m^3 \mathcal{N}^{-2} \left( \mathcal{J} - \mathcal{J}_\psi \right) \\
+ a_3 m^6 \mathcal{N}^{-3} A(m, \mathcal{J}, \mathcal{J}_\psi) - a_4 m^6 \mathcal{N}^{-4} \left( \mathcal{J} - \mathcal{J}_\psi \right) \\
\times B(m, \mathcal{J}, \mathcal{J}_\psi) + \mathcal{O}[\mathcal{N}^{-5}],
\] (4.64)

which reduces to the usual linear scaling relation of energy with spins and oscillation number in the large $\mathcal{N}$ limit. Here
analysis of the string states might give us hints about the possible nature of dual gauge theory operators next to leading order. Furthermore it will be interesting to study the Wilson loops in this background to have a better understanding of this. We hope to come back to some of these issues in the future.

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