Fast Large-Scale Approximate Graph Construction for NLP

Amit Goyal and Hal Daumé III
Dept. of Computer Science
University of Maryland
College Park, MD
{amit,hal}@umiacs.umd.edu

Raul Guerra
Dept. of Computer Science
University of Maryland
College Park, MD
rguerra@cs.umd.edu

Abstract

Many natural language processing problems involve constructing large nearest-neighbor graphs. We propose a system called FLAG to construct such graphs approximately from large data sets. To handle the large amount of data, our algorithm maintains approximate counts based on sketching algorithms. To find the approximate nearest neighbors, our algorithm pairs a new distributed online-PMI algorithm with novel fast approximate nearest neighbor search algorithms (variants of PLEB). These algorithms return the approximate nearest neighbors quickly. We show our system’s efficiency in both intrinsic and extrinsic experiments. We further evaluate our fast search algorithms both quantitatively and qualitatively on two NLP applications.

1 Introduction

Many natural language processing (NLP) problems involve graph construction. Examples include constructing polarity lexicons based on lexical graphs from WordNet (Rao and Ravichandran, 2009), constructing polarity lexicons from web data (Velikovich et al., 2010) and unsupervised part-of-speech tagging using label propagation (Das and Petrov, 2011). The later two approaches construct nearest-neighbor graphs between word pairs by computing nearest neighbors between word pairs from large corpora. These nearest neighbors form the edges of the graph, with weights given by the distributional similarity (Turney and Pantel, 2010) between terms. Unfortunately, computing the distributional similarity between all words in a large vocabulary is computationally and memory intensive when working with large amounts of data (Pantel et al., 2009). This bottleneck is typically addressed by means of commodity clusters. For example, Pantel et al. (2009) compute distributional similarity between 500 million terms over a 200 billion words in 50 hours using 100 quad-core nodes, explicitly storing a similarity matrix between 500 million terms.

In this work, we propose Fast Large-Scale Approximate Graph (FLAG) construction, a system that constructs a fast large-scale approximate nearest-neighbor graph from a large text corpus. To build this system, we exploit recent developments in the area of approximation, randomization and streaming for large-scale NLP problems (Ravichandran et al., 2005; Goyal et al., 2009; Levenberg et al., 2010). More specifically we exploit work on Locality Sensitive Hashing (LSH) (Charikar, 2002) for computing word-pair similarities from large text collections (Ravichandran et al., 2005; Van Durme and Lall, 2010). However, Ravichandran et al. (2005) approach stored an enormous matrix of all unique words and their contexts in main memory, which is infeasible for very large data sets. A more efficient online framework to locality sensitive hashing (Van Durme and Lall, 2010; Van Durme and Lall, 2011) computes distributional similarity in a streaming setting. Unfortunately, their approach can handle only additive features like raw-counts, and not non-linear association scores like pointwise mutual information (PMI), which generates better context vectors for distributional similarity (Ravichandran et al., 2005; Pantel et al., 2009; Turney and Pantel, 2010).

In FLAG, we first propose a novel distributed online-PMI algorithm (Section 3.1). It is a streaming method that processes large data sets in one pass while distributing the data over commodity clusters.
and returns context vectors weighted by pointwise mutual information (PMI) for all the words. Our distributed online-PMI algorithm makes use of the Count-Min (CM) sketch algorithm (Cormode and Muthukrishnan, 2004) (previously shown effective for computing distributional similarity in our earlier work (Goyal and Daumé III, 2011)) to store the counts of all words, contexts and word-context pairs using only $8GB$ of main memory. The main motivation for using the CM sketch comes from its linearity property (see last paragraph of Section 2) which makes CM sketch to be implemented in distributed setting for large data sets. In our implementation, FLAG scaled up to 110 GB of web data with 866 million sentences in less than 2 days using 100 quad-core nodes. Our intrinsic and extrinsic experiments demonstrate the effectiveness of distributed online-PMI.

After generating context vectors from distributed online-PMI algorithm, our goal is to use them to find fast approximate nearest neighbors for all words. To achieve this goal, we exploit recent developments in the area of existing randomized algorithms for random projections (Achlioptas, 2003; Li et al., 2006), Locality Sensitive Hashing (LSH) (Charikar, 2002) and improve on previous work done on PLEB (Point Location in Equal Balls) (Indyk and Motwani, 1998; Charikar, 2002). We propose novel variants of PLEB to address the issue of reducing the pre-processing time for PLEB. One of the variants of PLEB (FAST-PLEB) with considerably less pre-processing time has effectiveness comparable to PLEB. We evaluate these variants of PLEB both quantitatively and qualitatively on large data sets. Finally, we show the applicability of large-scale graphs built from FLAG on two applications: the Google-Sets problem (Ghahramani and Heller, 2005), and learning concrete and abstract words (Turney et al., 2011).

2 Count-Min sketch

The Count-Min (CM) sketch (Cormode and Muthukrishnan, 2004) belongs to a class of ‘sketch’ algorithms that represents a large data set with a compact summary, typically much smaller than the full size of the input by processing the data in one pass. The following surveys comprehensively review the streaming literature (Rusu and Dobra, 2007; Cormode and Hadjieleftheriou, 2008) and sketch techniques (Charikar et al., 2004; Li et al., 2008; Cormode and Muthukrishnan, 2004; Rusu and Dobra, 2007). In our another recent paper (Goyal et al., 2012), we conducted a systematic study and compare many sketch techniques which answer point queries with focus on large-scale NLP tasks. In that paper, we empirically demonstrated that CM sketch performs the best among all the sketches on three large-scale NLP tasks.

CM sketch uses hashing to store the approximate frequencies of all items from the large data set onto a small sketch vector that can be updated and queried in constant time. CM has two parameters $\epsilon$ and $\delta$: $\epsilon$ controls the amount of tolerable error in the returned count and $\delta$ controls the probability with which the error exceeds the bound $\epsilon$.

CM sketch with parameters $(\epsilon, \delta)$ is represented as a two-dimensional array with width $w$ and depth $d$; where $w$ and $d$ depends on $\epsilon$ and $\delta$ respectively. We set $w=\frac{2}{\epsilon}$ and $d=\log(\frac{1}{\delta})$. The depth $d$ denotes the number of pairwise-independent hash functions employed by the CM sketch; and the width $w$ denotes the range of the hash functions. Given an input stream of items of length $N$ ($x_1, x_2 \ldots x_N$), each of the hash functions $h_k: \{x_1, x_2 \ldots x_N\} \rightarrow \{1 \ldots w\}$, $\forall 1 \leq k \leq d$, takes an item from the input stream and maps it into a position indexed by the corresponding hash function.

UPDATE: For each new item “x” with count $c$, the sketch is updated as:

$$\text{sketch}[k, h_k(x)] \leftarrow \text{sketch}[k, h_k(x)] + c, \ \forall 1 \leq k \leq d.$$  

QUERY: Since multiple items can be hashed to the same index for each row of the array, hence the stored frequency in each row is guaranteed to overestimate the true count, which makes it a biased estimator. Therefore, to answer the point query (QUERY (x)), CM returns the minimum over all the $d$ positions indexed by the hash functions.

$$\hat{c}(x) = \min_k \text{sketch}[k, h_k(x)], \ \forall 1 \leq k \leq d.$$  

All reported frequencies by CM exceed the true frequencies by at most $\epsilon N$ with probability of at least $1 - \delta$. The space used by the algorithm is $O(\frac{2}{\epsilon} \log \frac{1}{\delta})$. Constant time of $O(\log(\frac{1}{\delta}))$ per each update and query operation.

CM sketch has a linearity property which states that: Given two sketches $s_1$ and $s_2$ computed (us-
where c co-occur with the word “z”. We compute this ef-

sic, syntactic, and/or dependency units that

PMI (strength of association) between the context
text vector (⟨every word “z”, our system generates a sparse con-
graph. Our system operates in four steps. First, for
mate nearest neighbors, which implicitly defines the
above equation. This heuristic avoids the

unnecessary updating of counter values to reduce
the over-estimation error.

The idea of conservative update (Estan and Vargh-
es, 2002) is to only increase counts in the sketch
by the minimum amount needed to ensure that the
estimate remains accurate. We (Goyal and Daumé
III, 2011) used CM sketch with conservative update
(CM-CU sketch) to show that the update reduces
the amount of over-estimation error by a factor of
at least 1.5 on NLP data and showed the effective-
ness of CM-CU on three important NLP tasks. The
QUERY procedure for CM-CU is identical to Count-
Min. However, to UPDATE an item “x” with fre-
quency c, first we compute the frequency ĝ(x) of this
item from the existing data structure:

∀V 1 ≤ k ≤ d, ĝ(x) = mink sketch[k, h_k(x)]

and the counts are updated according to:

sketch[k, h_k(x)] ← max{sketch[k, h_k(x)], ĝ(x) + c}.

The intuition is that, since the point query returns
the minimum of all the d values, we will update
a counter only if it is necessary as indicated by
the above equation. This heuristic avoids the
unnecessary updating of counter values to reduce
the over-estimation error.

3 FLAG: Fast Large-Scale Approximate
Graph Construction

We describe a system, FLAG, for generating a near-
est neighbor graph from a large corpus. For ev-
ev node (word), our system returns top l approxi-
nate nearest neighbors, which implicitly defines the
graph. Our system operates in four steps. First, for
every word “z”, our system generates a sparse con-
context vector (⟨(c_1, v_1); (c_2, v_2) . . . ; (c_d, v_d)⟩) of size
d where c_d denotes the context and v_d denotes the
PMI (strength of association) between the context
c_d and the word “z”. The context can be lexical,
semantic, syntactic, and/or dependency units that
c-occur with the word “z”. We compute this ef-
ciently using a new distributed online Pointwise
Mutual Information algorithm (Section 3.1). Sec-
ond, we project all the words with context vector
size d onto k random vectors and then binarize these
random projection vectors (Section 3.2). Third, we
propose novel variants of PLEB (Section 3.3) with
less pre-processing time to represent data for fast
query retrieval. Fourth, using the output of vari-
ants of PLEB, we generate a small set of potential
nearest neighbors for every word “z” (Section 3.4).
From this small set, we can compute the Hamming
distance between every word “z” and its potential
nearest neighbors to return the l nearest-neighbors
for all unique words.

3.1 Distributed online-PMI

We propose a new distributed online Pointwise Mu-

tual Information (PMI) algorithm motivated by the
online-PMI algorithm (Van Durme and Lall, 2009b)
(page 5). This is a streaming algorithm which pro-
cesses the input corpus in one pass. After one
pass over the data set, it returns the context vec-
tors for all query words. The original online-PMI
algorithm was used to find the top-d verbs for a
query verb using the highest approximate online-
PMI values using a Talbot-Osborne-Morris-Bloom
(TOMB) Counter (Van Durme and Lall, 2009a).
Unfortunately, this algorithm is prohibitively slow
when computing contexts for all words, rather than
just a small query set. This motivates us to propose
a distributed variant that enables us to scale to large
data and large vocabularies.1

We make three modifications to the original
online-PMI algorithm and refer to it as the “modified
online-PMI algorithm” shown in Algorithm 1. First,
we use Count-Min with conservative update (CM-
CU sketch) (Goyal and Daumé III, 2011) instead of
TOMB. We prefer CM because it enables distribu-
tion due to its linearity property (Section 2) and foot-
note #1. Distribution using TOMB is not known in
literature and we will like to explore that direction in
future. Second, we store the counts of words (“z”),
contexts (“v”) and word-context pairs all together in

1TOMB is a variant of CM sketch which focuses on reduc-
ing the bit size of each counter (in addition to the number of
counters) at the cost of incurring more error in the counters.

2The serialized online-PMI algorithm took a week to generate
context vectors for all the words from GW (Section 4.1).
Algorithm 1 Modified online-PMI

Require: Data set \( D \), buffer size \( B \)
Ensure: context vectors \( V \), mapping word \( z \) to \( d \)-best contexts in priority queues \( \langle y, \text{PMI}(z, y) \rangle \)

1: initialize CM-CU sketch to store approximate counts of words, context and word-context pairs
2: for each buffer \( B \) in the data set \( D \) do
3: initialize \( S \) to store \( \langle z, y \rangle \) observed in \( B \)
4: for \( \langle z, y \rangle \) in \( B \) do
5: set \( S \langle(z, y) \rangle = 1 \)
6: insert \( z \), \( y \) and pair \( \langle z, y \rangle \) in sketch
7: end for
8: for \( x \) in set \( S \) do
9: recomputed vectors \( V(x) \) using current contexts in priority queue and \( \{y | S(\langle z, y \rangle) = 1 \} \)
10: end for
11: end for
12: return context vectors \( V \)

the CM-CU sketch (in the original online-PMI algorithm, exact counts of words and contexts were stored in a hash table; only the pairs were stored in the TOMB data structure). Third, in the original algorithm, for each “\( z \)” a vector of top-\( d \) contexts are modified at the end of each buffer (refer Algorithm 1). However, in our algorithm, we only modify the list of those “\( z \)”s which appeared in the recent buffer rather than modifying for all the “\( z \)”s (Note, if “\( z \)” does not appear in the recent buffer, then its top-\( d \) contexts cannot be changed. Hence, we only modify those “\( z \)”s which appear in the recent buffer).

In our distributed online-PMI algorithm, first we split the data into chunks of 10 million sentences. Second, we run the modified online-PMI algorithm on each chunk in distributed setting. This stores counts of all words (“\( z \)”s), contexts (“\( y \)”s) and word-context pairs in the CM-CU sketch, and store top-\( d \) contexts for each word in priority queues. In third step, we merge all the sketches using linearity property to sum the counts of the words, contexts and word-context pairs. Additionally we merge the lists of top-\( d \) contexts for each word. In the last step, we use the single merged sketch and merged top-\( d \) contexts list to generate the final distributed online-PMI top-\( d \) contexts list.

It takes around one day to compute context vectors for all the words from a chunk of 10 million sentences using first step of distributed online-PMI. We generated context vectors for all the 87 chunks (110 GB data with 866 million sentences: see Table 1) in one day by running one process per chunk over a cluster. The first step of the algorithm involves traversing the data set and is the most time intensive step. For the second step, the merging of sketches is fast, since sketches are two dimensional array data structures (we used the sketch of size 2 billion counters with 3 hash functions). Merging the lists of top-\( d \) contexts for each word is embarrassingly parallel and fast. The last step to generate the final top-\( d \) contexts list is again embarrassingly parallel and fast and takes couple of hours to generate the top-\( d \) contexts for all the words from all the chunks. If implemented serially the “modified online-PMI algorithm” on 110 GB data with 866 million sentences would take approximately 3 months.

The downside of the distributed online-PMI is that it splits the data into small chunks and loses information about the global best contexts for a word over all the chunks. The algorithm locally computes the best contexts for each chunk, that can be bad if the algorithm misses out globally good contexts and that can affect the accuracy of downstream application. We will demonstrate in our experiments (Section 4.2) by using distributed online-PMI, we do not lose any significant information about global contexts and perform comparable to offline-PMI over an intrinsic and extrinsic evaluation.

3.2 Dimensionality Reduction from \( \mathbb{R}^D \) to \( \mathbb{R}^k \)

We are given context vectors for \( Z \) words, our goal is to use \( k \) random projections to project the context vectors from \( \mathbb{R}^D \) to \( \mathbb{R}^k \). There are total \( D \) unique contexts (\( D >> k \)) for all \( Z \) words. Let \( \{(c_1, v_1); (c_2, v_2)\ldots (c_d, v_d)\} \) be sparse context vectors of size \( d \) for \( Z \) words. For each word, we use hashing to project the context vectors onto \( k \) directions. We use \( k \) pairwise independent hash functions that maps each of the \( d \) context \( (c_d) \) dimensions onto \( \beta_{d,k} \in \{-1, +1\} \); and compute inner product between \( \beta_{d,k} \) and \( v_d \). Next, \( \forall k; \sum d \beta_{d,k} v_d \) returns the \( k \) random projections for each word “\( z \)”. We store the \( k \) random projections for all words (mapped to integers) as a matrix \( A \) of size of \( k \times Z \).

The mechanism described above generates random projections by implicitly creating a random projection matrix from a set of \( \{-1, +1\} \). This idea of creating implicit random projection matrix
is motivated by the work on stable random projections (Li et al., 2006; Li et al., 2008), Count sketch (Charikar et al., 2004), feature hashing (Weinberger et al., 2009) and online Locality Sensitive Hashing (LSH) (Van Durme and Lall, 2010). The idea of generating random projections from the set \{-1, +1\} was originally proposed by Achlioptas (2003).

Next we create a binary matrix \(B\) using matrix \(A\) by taking sign of each of the entries of the matrix \(A\). If \(A(i, j) \geq 0\), then \(B(i, j) = 1\); else \(B(i, j) = 0\). This binarization creates Locality Sensitive Hash (LSH) function that preserves the cosine similarity between every pair of word vectors. This idea was first proposed by Charikar (2002) and used in NLP for large-scale noun clustering (Ravichandran et al., 2005). However, in large-scale noun clustering work, their approach had to store the random projection matrix of size \(D \times k\); where \(D\) denotes the number of all unique contexts (which is generally large and \(D \gg Z\)) and in this paper, we do not explicitly require storing a random projection matrix.

### 3.3 Representation for Fast-Search

We describe three approaches to represent the data (matrix \(A\) and \(B\) from Section 3.2) in such a manner that finding nearest neighbors is fast. These three approaches differ in amount of pre-processing time. First, we propose a naive baseline approach using random projections independently with the best pre-processing time. Second, we describe PLEB (Point Location in Equal Balls) (Indyk and Motwani, 1998; Charikar, 2002) with the worst pre-processing time. Third, we propose a variant of PLEB to reduce its pre-processing time.

#### 3.3.1 Independent Random Projections (IRP)

Here, we describe a naive baseline approach to arrange nearest neighbors next to each other by using Independent Random Projections (IRP). In this approach, we pre-process the matrix \(A\). First for matrix \(A\), we pair the words \(z_1 \cdots z_Z\) and their random projection values as shown in Fig. 1(a). Second, we sort the elements of each row of matrix \(A\) by their random projection values from smallest to largest (shown in Fig. 1(b)). The sorting step takes \(O(Z \log Z)\) time (We can assume \(k\) to be a constant). The sorting operation puts all the nearest neighbor words (for each \(k\) independent projections) next to each other. After sorting the matrix \(A\), we throw away the projection values leaving only the words (see Fig. 1(c)). To search for a word in matrix \(A\) in constant time, we create another matrix \(C\) of size \((k \times Z)\) (see Fig. 1(d)). Matrix \(C\) maps the words \(z_1 \cdots z_Z\) to their sorted position in the matrix \(A\) (see Fig. 1(c)) for each \(k\).

#### 3.3.2 PLEB

PLEB (Point Location in Equal Balls) was first proposed by Indyk and Motwani (1998) and further improved by Charikar (2002). The improved PLEB algorithm puts in operation all \(k\) random projections together. It randomly permutes the ordering of \(k\) binary LSH bits (stored in matrix \(B\)) for all the words \(p\) times. For each permutation it sorts all the words lexicographically based on their permuted LSH representation of size \(k\). The sorting operation puts all the nearest neighbor words (using \(k\) projections together) next to each other for all the permutations. In practice \(p\) is generally large, Ravichandran et al. (2005) used \(p = 1000\) in their work.

In our implementation of PLEB, we have a matrix \(A\) of size \((p \times Z)\) similar to the first matrix in Fig. 1(a). The main difference to the first matrix in Fig. 1(a) is that bit vectors of size \(k\) are used for sorting rather than using scalar projection values. Similar to Fig. 1(c) after sorting, bit vectors are discarded and...
a matrix $C$ of size $(p \times Z)$ is used to map the words $1 \cdots Z$ to their sorted position in the matrix $A$. Note, in IRP approach, the size of $A$ and $C$ matrix is $(k \times Z)$. In PLEB generating random permutations and sorting the bit vectors of size $k$ involves worse pre-processing time than using IRP. However, spending more time in pre-processing leads to finding better approximate nearest neighbors.

3.3.3 Fast-PLEB

To reduce the pre-processing time for PLEB, we propose a variant of PLEB (Fast-PLEB). In PLEB, while generating random permutations, it uses all the $k$ bits. In this variant, for each random permutation we randomly sample without replacement $q$ ($q << k$) bits out of $k$. We use $q$ bits to represent each permutation and sort based on these $q$ bits. This makes pre-processing faster for PLEB. Section 4.3 shows that Fast-PLEB only needs $q = 10$ to perform comparable to PLEB with $q = 3000$ (that makes Fast-PLEB 300 times faster than PLEB). Here, again we store matrices $A$ and $C$ of size $(p \times Z)$.

3.4 Finding Approximate Nearest Neighbors

The goal here is to exploit three representations discussed in Section 3.3 to find approximate nearest neighbors quickly. For all the three methods (IRP, PLEB, Fast-PLEB), we can use the same fast approximate search which is simple and fast. To search a word “$z$”, first, we can look up matrix $C$ to locate the $k$ positions where “$z$” is stored in matrix $A$. This can be done in constant time (Again assuming $k$ (for IRP) and $p$ (for PLEB and Fast-PLEB) to be a constant.). Once, we find “$z$” in each row, we can select $b$ (beam parameter) neighbors ($b/2$ neighbors from left and $b/2$ neighbors from right of the query word.) for all the $k$ or $p$ rows. This can be done in constant time (Assuming $k$, $p$ and $b$ to be constants.). This search procedure produces a set of $bk$ (IRP) or $bp$ (PLEB and Fast-PLEB) potential nearest neighbors for a query word “$z$”. Next, we compute Hamming distance between query word “$z$” and the set of potential nearest neighbors from matrix $B$ to return $l$ closest nearest neighbors. For computing hamming distance, all the approaches discussed in Section 3.3 require all $k$ random projection bits.

4 Experiments

We evaluate our system FLAG for fast large-scale approximate graph construction. First, we show that using distributed online-PMI algorithm is as effective as offline-PMI. Second, we compare the approximate nearest neighbors lists generated by FLAG against the exact nearest neighbor lists. Finally, we show the quality of our approximate similarity lists generated by FLAG from the web corpus.

4.1 Experimental Setup

Data sets: We use two data sets: Gigaword (Graff, 2003) and a copy of news web (Ravichandran et al., 2005). For both the corpora, we split the text into sentences, tokenize and convert into lower-case. To evaluate our approximate graph construction, we evaluate on three data sets: Gigaword (GW), Gigaword + 50% of web data (GWB50) and Gigaword + 100% (GWB100) of web data. Corpus statistics are shown in Table 1. We define the context for a given word “$z$” as the surrounding words appearing in a window of 2 words to the left and 2 words to the right. The context words are concatenated along with their positions -2, -1, +1, and +2.

| Corpus    | GWB50 | GWB100 |
|-----------|-------|--------|
| Unzipped Size (GB) | 12    | 60     | 110    |
| # of sentences (Million) | 57    | 463    | 866    |
| # of tokens (Billion)    | 2.1   | 10.9   | 20.0   |

Table 1: Corpus Description

4.2 Evaluating Distributed online-PMI

Experimental Setup: First we do an intrinsic evaluation to quantitatively evaluate the distributed online-PMI vectors against the offline-PMI vectors computed from Gigaword (GW). Offline-PMI computed from the sketches have been shown as effective as exact PMI by Goyal and Daumé III (2011). To compute offline-PMI vectors, we do two passes over the corpus. In the first pass, we store the counts of words, contexts and word-context pairs computed from GW in the Count-Min with conservative update (CM-CU) sketch. We use the CM-CU sketch of size 2 billion counters (bounded 8 GB memory).
with 3 hash functions. In second pass, using the aggregated counts from the sketch, we generate the offline-PMI vectors of size \(d = 1000\) for every word. For rest of this paper for distributed online-PMI, we set \(d = 1000\) and the size of the buffer=10,000 and we split the data sets into small chunks of 10 million sentences.

**Intrinsic Evaluation:** We use four kinds of measures: precision (P), recall (R), f-measure (F1) and Pearson’s correlation (\(\rho\)) to measure the overlap in the context vectors obtained using online and offline PMI. \(\rho\) is computed between contexts that are found in offline and online context vectors. We do this evaluation on 447 words selected from the concatenation of four test-sets mentioned in the next paragraph. On these 447 words, we achieve an average P of .97, average R of .96 and average F1 of .97 and a perfect average \(\rho\) of 1. This evaluation show that the vectors obtained using online-PMI are as effective as offline-PMI.

**Extrinsic Evaluation:** We also compare online-PMI effectiveness on four test sets which consist of word pairs, and their corresponding human rankings. We generate the word pair rankings using online-PMI and offline-PMI strategies. We report the Pearson’s correlation (\(\rho\)) between the human and system generated similarity rankings. The four test sets are: **WS-353** (Finkelstein et al., 2002) is a set of 353 word pairs. **WS-203:** A subset of WS-353 with 203 word pairs (Agrirre et al., 2009). **RG-65:** (Rubenstein and Goodenough, 1965) has 65 word pairs. **MC-30:** A subset of RG-65 dataset with 30 word pairs (Miller and Charles, 1991).

The results in Table 2 shows that by using distributed online-PMI (by making a single pass over the corpus) is comparable to offline-PMI (which is computed by making two passes over the corpus).

For generating context vectors from **GW**, for both offline-PMI and online-PMI, we use a frequency cutoff of 5 for word-context pairs to throw away the rare terms as they are sensitive to PMI (Church and Hanks, 1989). Next, **FLAG** generates online-PMI vectors from **GWB50** and **GWB100** and uses frequency cutoffs of 15 and 25. The higher frequency cutoffs are selected based on the intuition that, with more data, we get more noise, and hence not considering word-context pairs with frequency less than 25 will be better for the system. As **FLAG** is going to use the context vectors to find nearest neighbors, we also throw away all those words which have \(\leq 50\) contexts associated with them. This generates context vectors for 57,930 words from **GW**: 95,626 from **GWB50** and 106,733 from **GWB100**.

**Table 2:** Evaluating word pairs ranking with online and offline PMI. Scores are evaluated using \(\rho\) metric.

| Test Set | WS-353 | WS-203 | RG-65 | MC-30 |
|----------|--------|--------|-------|-------|
| Offline-PMI | .41 | .55 | .40 | .52 |
| Online-PMI | .41 | .56 | .39 | .51 |

**Table 4:** Varying parameter \(q\) for FAST-PLEB with fixed \(p = 1000\), \(k = 3000\) and \(b = 40\). Results reported on recall and \(\rho\).

| \(q\) | 10 | 25 | 50 | 100 |
|------|----|----|----|-----|
| IRP  | .40 | .53 | .38 | .51 |
| \(q=1\) | .24 | .62 | .20 | .63 |
| \(q=5\) | .47 | .60 | .43 | .57 |
| \(q=10\) | .53 | .58 | .49 | .56 |
| \(q=100\) | .53 | .60 | .50 | .59 |

\(q=3000\) | .54 | .58 | .50 | .59 |

\(p=3000\) | .54 | .58 | .50 | .59 |

\(q=3000\) | .46 | .56 | .43 | .53 |

\(q=3000\) | .43 | .54 |

**4.3 Evaluating Approximate Nearest Neighbor**

**Experimental Setup:** To evaluate approximate nearest neighbor similarity lists generated by **FLAG**, we conduct three experiments. We evaluate all the three experiments on 447 words (test set) as used in Section 4.2. For each word, both exact and approximate methods return \(l = 100\) nearest neighbors. The exact similarity lists for 447 test words is computed by calculating cosine similarity between 447 test words with respect to all other words. We also compare the LSH (computed using Hamming distance between all words and test set.) approximate nearest neighbor similarity lists against the exact similarity lists. LSH provides an upper bound on the performance of our approximate search representations (IRP, PLEB, and FAST-PLEB) for fast-search from Section 3.3. We set the number of projections \(k = 3000\) for all three methods and for PLEB and FAST-PLEB, we set number of permutations \(p = 1000\) as used in large-scale noun clustering work (Ravichandran et al., 2005).

**Evaluation Metric:** We use two kinds of measures, recall and Pearson’s correlation to measure the overlap in the approximate and exact similarity lists. Intuitively, recall (R) captures the number of
nearest neighbors that are found in both the lists and then Pearson’s ($\rho$) correlation captures if the relative order of these lists is preserved in both the similarity lists. We also compute $R$ and $\rho$ at various $l = \{10, 25, 50, 100\}$.

**Results:** For the first experiment, we evaluate IRP, PLEB, and FAST-PLEB against the exact nearest neighbor similarity lists. For IRP, we sample first $p$ rows and only use $p$ rather than $k$, this ensures that all the three methods (IRP, PLEB, and FAST-PLEB) take the same query time. We vary the approximate nearest neighbor beam parameter $b = \{20, 30, 40, 50, 100\}$ that controls the number of closest neighbors for a word with respect to each independent random projection. Note, with increasing $b$, our algorithm approaches towards LSH (computing Hamming distance with respect to all the words). For FAST-PLEB, we set $q = 10$ ($q < k$) that is the number of random bits selected out of $k$ to generate $p$ permuted bit vectors of size $q$. The results are reported in Table 3, where the first row compares the LSH approach against the exact similarity list for test set words. Across three columns we compare IRP, PLEB, and FAST-PLEB. For all methods, increasing $b$ means better recall. If we move down the table, with $b = 100$, IRP, PLEB, and FAST-PLEB get results comparable to LSH (reaches an upper bound). However, using large $b$ implies generating a long potential nearest neighbor list close to the size of the unique context vectors. If we focus on the gray color row with $b = 40$ (This will have comparatively small potential list and return nearest neighbors in less time), IRP has worse recall with best pre-processing time. FAST-PLEB ($q = 10$) is comparable to PLEB (using all bits $q = 3000$) with pre-processing time 300 times faster than PLEB. For rest of this work, $\text{FLAG}$ will use FAST-PLEB as it has best recall and pre-processing time with fixed $b = 40$.

For the second experiment, we vary parameter $q = \{1, 5, 10, 100, 3000\}$ for FAST-PLEB in Table 4. Table 4 demonstrates using $q = \{1, 5\}$ result in worse recall, however using $q = 5$ for FAST-PLEB is better than IRP. $q = 10$ has comparable recall to $q = \{100, 3000\}$. For rest of this work, we fix $q = 10$ as it has best recall and pre-processing time.

For the third experiment, we increase the size of the data set across the Table 5. With the increase in size of the data set, LSH, IRP, PLEB, and FAST-PLEB ($q = 10$) have worse recall. The reason for such a behavior is that the number of unique context vectors is greater for big data sets. Across all the

|                | IRP          | PLEB         | FAST-PLEB   |
|----------------|--------------|--------------|-------------|
| $b$            | $\rho$       | $\rho$       | $\rho$      |
| 10             | .55 .57      | .52 .56      | .49 .54     |
| 25             | .51 .55      | .46 .54      | .44 .52     |
| 50             | .53 .56      | .48 .54      | .45 .52     |
| 100            | .54 .57      | .50 .56      | .46 .54     |

Table 3: Evaluation results on comparing LSH, IRP, PLEB, and FAST-PLEB with $k = 3000$ and $b = \{20, 30, 40, 50, 100\}$ with exact nearest neighbors over GW data set. For PLEB and FAST-PLEB, we set $p = 1000$ and for FAST-PLEB, we set $q = 10$. We report results on recall ($R$) and $\rho$ metric. For IRP, we sample first $p$ rows and only use $p$ rows rather than $k$.

|                | GW          | GW50         | GWB100      |
|----------------|-------------|--------------|-------------|
| $b$            | $\rho$      | $\rho$       | $\rho$      |
| 10             | .55 .57      | .52 .56      | .49 .54     |
| 25             | .51 .55      | .46 .54      | .44 .52     |
| 50             | .53 .56      | .48 .54      | .45 .52     |
| 100            | .54 .57      | .50 .56      | .46 .54     |

Table 5: Evaluation results on comparing LSH, IRP, PLEB, and FAST-PLEB with $k = 3000$, $b = 40$, $p = 1000$ and $q = 10$ with exact nearest neighbors across three different data sets: GW, GWB50, and GWB100. We report results on recall ($R$) and $\rho$ metric. The gray color row is the system that we use for further evaluations.
three data sets, FAST-PLEB has recall comparable to PLEB with best pre-processing time. Hence, for the next evaluation to show the quality of final lists we use FAST-PLEB with \( q = 10 \) for GWB100 data set.

In Table 6, we list the top 10 most similar words for some words found by our system FLAG using GWB100 data set. Even though FLAG’s approximate nearest neighbor algorithm has less recall with respect to exact but still the quality of these nearest neighbor lists is excellent.

For the final experiment, we demonstrate the pre-processing and query time results comparing LSH, IRP, PLEB, and FAST-PLEB with \( k = 3000, p = 1000, b = 40 \) and \( q = 10 \) parameter settings. For pre-processing timing results, we perform all the experiments (averaged over 5 runs) on GWB100 data set with 106, 733 words. The second pre-processing step of the system FLAG (Section 3.2) that is dimensionality reduction from \( \mathbb{R}^D \) to \( \mathbb{R}^k \) took 8.8 hours. The pre-processing time differences among IRP, PLEB, and FAST-PLEB from third step (Section 3.3) are shown in second column of Table 7. Experimental results show that the naive baseline IRP is the fastest and FAST-PLEB has 120 times faster pre-processing time compared to PLEB.

For comparing query time among several methods, we evaluate over 447 words (Section 4.2). We report average timing results (averaged over 10 runs and 447 words) to find top 100 nearest neighbors for single query word. The results are shown in third column of Table 7. Comparing first and second rows show that LSH is 87 times faster than computing exact top-100 (cosine similarity) nearest neighbors. Comparing second, third, fourth and fifth rows of the table demonstrate that IRP, PLEB and FAST-PLEB methods are twice as fast as LSH.

### 5 Applications

We use the graph constructed by FLAG from GWB100 data set (110 GB) by applying FAST-PLEB with parameters \( k = 3000, p = 1000, q = 10 \) and \( b = 40 \). The graph has 106, 733 nodes (words), with each node having 100 edges that denote the top \( l = 100 \) approximate nearest neighbors associated with each node. However, FLAG applied FAST-PLEB (approximate search) to find these neighbors. Therefore many of these edges can be noisy for our applications. Hence for each node, we only consider top 10 edges. In general for graph-based NLP problems; for example, constructing web-derived polarity lexicons (Velikovich et al., 2010), top 25 edges were used, and for unsupervised part-of-speech tagging using label propagation (Das and Petrov, 2011), top 5 edges were used.

#### 5.1 Google Sets Problem

Google Sets problem (Ghahramani and Heller, 2005) can be defined as: given a set of query words, return top \( t \) similar words with respect to query words. To evaluate the quality of our approximate large-scale graph, we return top 25 words which have best aggregated similarity scores with respect to query words. We take 5 classes and their query terms (McIntosh and Curran, 2008) shown in Table 8 and our goal is to learn 25 new words which are similar with these 5 query words.
**Table 9: Learned terms for Google Sets Problem**

| Concrete seeds | Abstract seeds |
|----------------|----------------|
| car, house, tree, horse, animal | idea, bravery, deceit, trust, dedication |
| man, table, bottle, woman, computer | anger, humour, luck, inflation, honesty |

**Table 10: Example seeds for bootstrapping.**

We conduct a manual evaluation to directly measure the quality of returned words. We recruited 1 annotator and developed annotation guidelines that instructed each recruiter to judge whether learned values are similar to query words or not. Overall the annotator found almost all the learned words to be similar to the query words. However, the algorithm can not differentiate between different senses of the word. For example, “French” can be a language and a nationality. Table 9 shows the top ranked words with respect to query words.

### 5.2 Learning Concrete and Abstract Words

Our goal is to automatically learn concrete and abstract words (Turney et al., 2011). We apply bootstrapping (Kozareva et al., 2008) on the word graphs by manually selecting 10 seeds for concrete and abstract words (see Table 10). We use in-degree (sum of weights of incoming edges) to compute the score for each node which has connections with known (seeds) or automatically labeled nodes, previously exploited to learn hyponymy relations from the web (Kozareva et al., 2008). We learn concrete and abstract words together (known as mutual exclusion principle in bootstrapping (Thelen and Riloff, 2002; McIntosh and Curran, 2008)), and each word is assigned to only one class. Moreover, after each iteration, we harmonically decrease the weight of the in-degree associated with instances learned in later iterations. We add 25 new instances at each iteration and ran 100 iterations of bootstrapping, yielding 2506 concrete nouns and 2498 abstract nouns. To evaluate our learned words, we searched in WordNet whether they had ‘abstraction’ or ‘physical’ as their hypernym. Out of 2506 learned concrete nouns, 1655 were found in WordNet. According to WordNet, 74% of those are concrete and 26% are abstract. Out of 2498 learned abstract nouns, 942 were found in WordNet. According to WordNet, 5% of those are concrete and 95% are abstract. Table 11 shows the top ranked concrete and abstract words.

### 6 Conclusion

We proposed a system, **FLAG** which constructs fast large-scale approximate graphs from large data sets. To build this system we proposed a distributed online-PMI algorithm that scaled up to 110 GB of web data with 866 million sentences in less than 2 days using 100 quad-core nodes. Our both intrinsic and extrinsic experiments demonstrated that online-PMI algorithm not at all loses globally good contexts and perform comparable to offline-PMI. Next, we proposed **FAST-PLEB** (a variant of PLEB) and empirically demonstrated that it has recall comparable to PLEB with 120 times faster pre-processing time. Finally, we show the applicability of **FLAG** on two applications: Google-Sets problem and learning concrete and abstract words.

In future, we will apply **FLAG** to construct graphs using several kinds of contexts like lexical, semantic, syntactic and dependency relations or a combination of them. Moreover, we will apply graph theoretic models on graphs constructed using **FLAG** for solving a large variety of NLP applications.

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