A Non-Local Reality: Is there a Phase Uncertainty in Quantum Mechanics?

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A century after the advent of Quantum Mechanics and General Relativity, both theories enjoy incredible empirical success, constituting the cornerstones of modern physics. Yet, paradoxically, they suffer from deep-rooted, so far intractable, conflicts. Motivations for violations of the notion of relativistic locality include the Bell’s inequalities for hidden variable theories, the cosmological horizon problem, and Lorentz-violating approaches to quantum geometrodynamics, such as Horava-Lifshitz gravity. Here, we explore a recent proposal for a “real ensemble” non-local description of quantum mechanics, in which “particles” can copy each others’ observable values AND phases, independent of their spatial separation. We first specify the exact theory, ensuring that it is consistent and has (ordinary) quantum mechanics as a fixed point, where all particles with the same values for a given observable have the same phases. We then study the stability of this fixed point numerically, and analytically, for simple models. We provide evidence that most systems (in our study) are locally stable to small deviations from quantum mechanics, and furthermore, the phase variance per value of the observable, as well as systematic deviations from quantum mechanics, decay as $\sim (\text{Energy}\times\text{Time})^{-2n}$, where $n \geq 1$. Interestingly, this convergence is controlled by the absolute value of energy (and not energy difference), suggesting a possible connection to gravitational physics. Finally, we discuss different issues related to this theory, as well as potential novel applications for the spectrum of primordial cosmological perturbations and the cosmological constant problem.

I. INTRODUCTION

In his groundbreaking 1964 paper, John Bell demonstrated that the correlations predicted for quantum mechanical observables can never be fully replicated in local hidden variable theories [1]. The empirical success of quantum mechanics over the past 50 years would thus only be consistent with a hidden variable theory with superluminal (in fact, instantaneous) communication. However, experimental verification of Lorentz invariance (or equivalence principle) at extreme precisions (e.g. [2]) has nearly vanquished any (empirical) motivation for such a possibility.

Surprisingly though, a motivation for this possibility may come from cosmological observations: If quantum mechanics is given by a hidden variable theory, that theory could have a non quantum mechanical extension with quantum mechanics as an equilibrium fixed point. Then, non-local signalling [3] may be possible before the universe enters the quantum mechanical “equilibrium”, and could be imprinted in the initial conditions of the universe. Therefore, one might be able to replicate the correlations observed in the cosmic microwave background (CMB) (e.g. [4]) using the non-local signalling in the pre-quantum mechanical universe [3], as they cannot otherwise be explained in the standard Big Bang theory (so-called horizon problem).

Another motivation for instantaneous signalling comes from a power-counting renormalizable approach to 3+1d geometro-dynamics, known as Horava-Lifshitz gravity [5] which, violates foliation invariance (and thus relativistic locality) of general relativity. At high energies, the speed of propagation for excitations in this theory approaches infinity, amounting to non-local (though causal) instantaneous signalling.

A real ensemble model is a non-local hidden variable theory, as an alternative to quantum mechanics, and so can potentially possess this type of non-local signalling. In order for this theory to be viable, however, quantum mechanics must be an attractor, such that the non-quantum mechanical theory becomes quantum mechanics at later times, consistent with present-day experiments. Valentini shows this is the case for Bohmian mechanics [6, 7] using a coarse-grained H-theorem as in statistical mechanics, so that one can see there are regimes which approach quantum equilibrium [8]. The proof applies to the coarse-grained case for a model with a real wavefunction and independent probability.

In this paper, we focus on a different hidden variable model, the so-called "real ensemble" model recently introduced by Smolin [9]. The model focuses on an object described in quantum mechanics by a wavefunction $|\psi\rangle$, which could be a particle, field, composite system of many particles, etc. We will refer to this as the system. It puts all systems that would be in the same state in quantum mechanics into an ensemble. One would then examine this system in a given eigenbasis for the observable of interest. There are two beables for each such system - the value of the observable in question and the phase of the component of the wavefunction in the eigenstate corresponding to the observable value would possess in quantum mechanics. All these systems are spread out across the universe, interacting non-locally as governed by the rules of interaction of members of the ensemble. The systems then evolve according to two rules: $i)$ The continuous evolution rule states that the phase of the systems evolves according to some equa-
...tion, and ii) The copy rule states that there is a finite probability for one system in the ensemble to change its observable and phase values to match those of another system’s. This then can be used to determine the evolution of the probability that a system would be in a given state as well as the phase associated with that state. This model is called real since, presumably, all the systems exist in the real universe and their Hamiltonians which determine their local interactions are in some way at some point indicating interactions with each other.

Since in Smolin’s real ensemble model the phases (of the wave function) are the additional hidden variables, the non-equilibrium behaviour is different. While we do not have a coarse-grained H-theorem, we have examined the convergence numerically and analytically to determine not only that there are regimes for which the model converges, but also the rate of convergence is dependent on absolute energy.

The outline of the paper is as follows: We begin in Sec. II by developing a non-equilibrium real ensemble model, which admits quantum mechanics (Eqs. 1-2) as an equilibrium limit. We also study the dynamics close to the equilibrium. In Sec. III, we study the stability properties of the non-equilibrium model numerically for simple spin–1/2 systems, and in particular examine the stable parameter-space of the theory. In Sec. IV, we provide an analytic perturbative study of near-equilibrium behaviour, which is roughly consistent with the numerical results. Finally, Sec. V puts the real ensemble framework, along with our findings, into some physical context, and Sec. VI concludes the paper.

II. REAL ENSEMBLE THEORY: THE FRAMEWORK

We begin by introducing the equilibrium real ensemble model which reproduces quantum mechanics. In the case of equilibrium, there is one phase per observable value. For this case, the number of systems, N, is sufficiently large such that there is a large enough number of systems per distinct sets of beables (phases AND observable values) [10], so that they can be treated as continuous numbers. We define the probability for a system to have a given value a for the observable of interest as $\rho_a(t)$. The phase associated with this observable value is defined as $\phi_a(t)$. The equations which reproduce quantum mechanics are then [9]:

$$\dot{\phi}_a(t) = \sum_b \sqrt{\rho_b(t)} \frac{\rho_a(t)}{\rho_a(t)} R(a,b) \cos [\phi_a(t) - \phi_b(t) + \delta(a,b)] ,$$

(1)

$$\dot{\rho}_a(t) = \sum_b 2\sqrt{\rho_a(t) \rho_b(t)} R(a,b) \sin [\phi_a(t) - \phi_b(t) + \delta(a,b)] ,$$

(2)

where the evolution $\dot{\phi}$ comes from the continuous evolution rule and the evolution $\dot{\rho}$ from the copy rule [11]. This case is identical to the quantum mechanical system with the wavefunction given by

$$|\Psi\rangle = \sum_a \sqrt{\rho_a(t)} e^{-i\phi_a} |a\rangle ,$$

(3)

and Hamiltonian given by

$$H = \hbar \sum_{a,b} R(a,b) e^{\delta(a,b)} |a\rangle \langle b| .$$

(4)

In order to determine the non-equilibrium forms of the equations, we need to remember that the calculation of the two Equations 1 and 2 starts with the assumption that $\phi$ is a function of the value of the observable rather than the system, defined as the equilibrium condition. The goal is to extrapolate these equations to non-equilibrium equations, one which has $\phi$ different for different systems even if the value of the observable is the same, using the known equilibrium equations. $\phi$ and $\dot{\rho}$ must reduce to those shown in Equations 1 and 2 when there is only one potential phase per value of the observable, as this will reproduce quantum mechanics when the function achieves equilibrium. We will retain the large N limit assumption.

A. Allowing for Multiple Phases per Value of Observable

The number of cases for a given value of the observable can be represented as a sum of the number of systems with a given set of beables for all beable sets with the given observable value $a$. Working in probabilities since the number of systems $N$ is large, this can be replaced by a weight function $w$ which determines the probability of the system with a given value of an observable having a given phase. As a probability function, $1 = \sum w(a, \phi, t)$ for every $a$ and $t$. We will label a system type - all systems which share phase and observable value - by the labels $i, j, k$, etc., rewriting $a$ as $a_i$, $\rho_a$ as $\rho_a$, and $\phi_a$ as $\phi_a$. In the non-equilibrium case, $\rho_{a_1}$ becomes $\rho_i$ and $\phi_{a_1}$ becomes $\phi_i$. Note that $\rho_{a_1}$ still has meaning out of equilibrium as $\sum_j \rho_j \delta_{a_1,a_j}$. Using $w$, $\rho_i = \rho_{a_1} w_i$. Since $a_i$ is no longer the only quantity the terms in the sum are dependent on, $\sum_{a_j}$ becomes
\[ \sum_{a_j} \sum_{j} w(a_j, \phi_j, t) = \sum_{j} w_j. \]

However, there is a less obvious place in which this weight function is needed. Underneath the square roots \( \rho_{a_j} \) may not be independent of phase anymore. It is uncertain if it only depends on the probability of a value of the observable or on the probability of a given beable pair. This is dealt with by adding in a function \( F(a, \phi_1, \phi_2) \) for which \( F(a, \phi_1, \phi_1) = 1 \) and \( F(a, \phi_1, \phi_2) > 0 \) everywhere. This function determines the contribution to the density functions under the square root of systems with different phases but the same value of the observable. We must then replace \( \rho_{a_j} \) by

\[ \tilde{\rho}_{a_i} \equiv \rho_{a_i} \sum_{j} w_j \delta_{a_i a_j} F(a_i, \phi_i, \phi_j) \]

(5)

\[ \equiv \sum_{j} \rho j \delta_{a_i a_j} F(a_i, \phi_i, \phi_j). \]  

(6)

\( F \) must be periodic with respect to \( \phi_1 - \phi_2 \), but might have additional dependence on \( a \) and \( \phi_1 \). A \( \phi_1 \) dependence could introduce a dependence on absolute phase, while a dependence on \( a \) may remove certain quantum mechanical symmetries from some systems when leaving equilibrium. These additional dependencies will not be considered here since there is no reason to believe that such dependencies exist nor any need to consider them. In addition, only the case for which \( F(\phi_1 - \phi_2) = F(\phi_2 - \phi_1) \) will be considered. If this does not hold, time reversal invariance will no longer hold: Since under time reversal in this model, \( \phi \rightarrow -\phi, t \rightarrow -t, \rho \rightarrow \rho, R \rightarrow R, \) and \( \delta \rightarrow -\delta \), applying time reversal to Equations 9 and 10 (the final equations, later) will only give \( \dot{\rho} \rightarrow -\dot{\rho} \) and \( \dot{\phi} \rightarrow \dot{\phi} \) for all \( a, \phi, \) and \( \rho (a, \phi, t) \) if \( F(\phi_1 - \phi_2) = F(\phi_2 - \phi_1) \).

We further exclude the possibility that \( F \) is 1 when \( \phi_1 = \phi_2 \) and 0 otherwise, because then transferring a large number of systems from \( \phi_1 \neq \phi_2 \) to \( \phi_1 = \phi_2 \) continuously will result in a discontinuity in the function \( \phi \) and \( \dot{\rho} \) from the discontinuity in \( \rho(a, t) \sum w(a, \phi_j, t) F(a, \phi_i, \phi_j) \). Other functions which similarly produce a discontinuity when going to equilibrium will be problematic.

The resulting evolution equations are

\[ \dot{\phi}_i (t) = \sum_{j} w_j (t) \sqrt{\frac{\rho_{a_j} (t) \sum_{k} w_k (t) \delta_{a_j a_k} F(\phi_j - \phi_k)}{\rho_{a_i} (t) \sum_{k} w_k (t) \delta_{a_i a_k} F(\phi_i - \phi_k)}} \times R(a_i, a_j) \cos [\phi_i (t) - \phi_j (t) + \delta (a_i, a_j)] \]  

and (7)

\[ \dot{\rho}_i (t) = w_i (t) \sum_{j} w_j (t) \sqrt{\frac{\rho_{a_j} (t) \sum_{k} w_k (t) \delta_{a_j a_k} F(\phi_1 - \phi_k)}{\rho_{a_i} (t) \sum_{k} w_k (t) \delta_{a_i a_k} F(\phi_i - \phi_k)}} \times 2R(a_i, a_j) \sin [\phi_i (t) - \phi_j (t) + \delta (a_i, a_j)]. \]  

(8)

Equivalently, we can define the probability for a given value of the observable and phase, \( \rho_i \equiv \rho_{a_i} w_i \), yielding:

\[ \dot{\phi}_i = \sum_{j} \frac{\rho_j}{\rho_{a_j} \delta_{a_j a_k}} \sqrt{\frac{\rho_j}{\rho_{a_i}}} \times R(a_i, a_j) \cos [\phi_i - \phi_j + \delta (a_i, a_j)], \]  

(9)

\[ \dot{\rho}_i = \sum_{k} \frac{\rho_k}{\rho_{a_k} \delta_{a_k a_i}} \sum_{j} \frac{\rho_j}{\rho_{a_j} \delta_{a_j a_k}} \times 2R(a_i, a_j) \sin [\phi_i - \phi_j + \delta (a_i, a_j)]. \]  

(10)

Here, as in equation 6,

\[ \tilde{\rho}_{a_i} \equiv \sum_{k} \rho_k \delta_{a_i a_k} F(\phi_j - \phi_k). \]  

(11)

First note that \( R(a, b) \) and \( \delta(a, b) \) are symmetric and anti-symmetric, respectively, due to the hermiticity of the Hamiltonian. Therefore, summing Eq. (10) above over \( a_i \) and \( \phi_i \), we end up with terms that are completely symmetric under \( i \leftrightarrow j \), with the exception of the sine factor, which is anti-symmetric. As a result, the sum vanishes and thus the total probability remains conserved.

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**B. Other Changes When Leaving Equilibrium**

While they will not be covered here, there are a few other additions to this equation which might be examined. The first is the addition of terms which go to zero for large \( N \) equilibrium limit. There is nothing to indicate what form these terms might take, except that they must go to zero for either the large \( N \) limit or the quantum mechanical limit, and they can’t cause any probabilities to not behave as probabilities. Other possibilities include adding a \( \phi \) dependence into \( R \) and \( \delta \). This would have to take a form in which the quantum
III. DISCRETE SYSTEMS: SPIN-$\frac{1}{2}$ WITH FINITE NUMBER OF PHASES PER VALUE OF OBSERVABLE

In this section, we numerically study the evolution of simplest possible systems, i.e. spin-$\frac{1}{2}$’s or qubits, and investigate whether/how their evolution approaches the quantum mechanical equilibrium.

The function $F$ will have one of a few predefined values. The first possibility is a constant $F$, $F(d\phi) = 1$. This corresponds to the case when the densities under the square roots are independent of phase.

The smooth cosine type function is a simple solution to account for the phase differences as being important while still creating an influence from the variation in the phases of the different systems. This would appear as

$$F(d\phi) \equiv \frac{1}{2} + \frac{1}{2} \cos (d\phi) = \cos^2 \left( \frac{d\phi}{2} \right). \quad (14)$$

This definition can be generalized to model a sharper dependence on phase difference. One such function is

$$F_c(d\phi) \equiv \cos^2 \left( \frac{c \ d\phi}{2} \right) \Theta[\cos(d\phi) - \cos(\pi/c)], \quad (15)$$

for a constant $c$, where $\Theta[x]$ is the step function that vanishes for $x < 0$ and is 1 otherwise. We note that $F_1 = F$ defined in Eq. (14). Moreover, for completeness, we define $F_0(d\phi) \equiv 1$.

For our numerical studies below, unless noted otherwise, we focus on three possibilities: $F(d\phi) = F_0, F_1,$ and $F_{100}$.

B. Results and Plots

We numerically evolve Eqs. (9-10) with either two or three different phases per each potential value of $s_z$. The results can be seen in Table I, as well as in the appendix. In the plots, spin up is represented by the blue colours (black, blue, purple), while spin down by the red colours (red, orange, pink). The plots in Table I are representative of all the cases run with similar initial differences in the phases of the same value of $s_z$. In each case, the sum of the probabilities of measuring a specific value of $s_z$ follow an evolution indistinguishable within the expected error from the quantum mechanical case.

For both the $F_0$ and $F_1$ cases, the very low probabilities could approach the levels in which the discreteness of the set are relevant and the large $N$ approximation breaks down for that particular beable pair. This possibility could alter the evolution of these beable pairs, and more interestingly potentially cause one of the potential pairs of beables to completely empty, removing it from the ensemble. This could possibly cause the $F_0$ case to become quantum mechanical, despite the instability, or the $F_1$ case to become exactly equilibrium.

For the two cases of functions which are flat or close to flat within this region, they start with the same behaviour, but the kernel that slightly deviates from flat (i.e. $F_1$) is stable and fully approaches equilibrium, while the other case, $F_0$ does not and diverges from equilibrium. The third case, $F_{100}$, which has the narrowest domain causes the system to approach equilibrium in a different way: Instead of the probability for certain pairs of beables to be present dropping to zero, the difference between the phases of the beable pairs with the same observable value goes to zero.

One subtlety to note for the $F_0$ case is that the values given do go below the expected error threshold for the numerical simulation. This, however, does not nullify the results which are seen - the fact that this is unstable remains, but the values after the point in which the model decreases below the error threshold can not be trusted.

For both the $F_0$ and $F_1$ cases, the very low probabilities could approach the levels in which the discreteness of the set are relevant and the large $N$ approximation breaks down for that particular beable pair. This possibility could alter the evolution of these beable pairs, and more interestingly potentially cause one of the potential pairs of beables to completely empty, removing it from the ensemble. This could possibly cause the $F_0$ case to become quantum mechanical, despite the instability, or the $F_1$ case to become exactly equilibrium.

For the evolution with greater initial difference in the phases, the cases with a phase difference of 0.1 still go to equilibrium for those $F$ functions which approached equilibrium for smaller initial angle difference, while the cases with a relatively large phase difference do not. At the start, however, the evolution of the sum of all probabilities of measuring one of the two values of $s_z$ is not
TABLE I. Plots of the evolution of spin-$\frac{1}{2}$ systems in the non-equilibrium real ensemble model. Each case has three different phases for each of the two potential values of $s_z$. The initial conditions are $\rho(0) = \{\{0.16, 0.08, 0.06\}, \{0.23, 0.3, 0.17\}\}$ and $\phi(0) = \{\{0.001\pi, 0.002\pi\}, \{\frac{\pi}{2} + 0.001\pi, \frac{\pi}{2} + 0.0005\pi\}\}$. The Hamiltonian is $H = \omega_0\hbar(2\sigma_z)$, $\hbar \equiv 1$ and $\omega_0$ determines the units for $t$. From top to bottom, the functions $F$ within equations 9 and 10 for the plots are $F = 1$, $F = \cos^2 (\frac{\phi}{\omega})$, and $F$ given by equation 15 with $c = 100$.

| Probability vs Time | Phase Difference vs Time |
|---------------------|--------------------------|
| ![Plot](image1.png) | ![Plot](image2.png) |
| ![Plot](image3.png) | ![Plot](image4.png) |
| ![Plot](image5.png) | ![Plot](image6.png) |

necessarily quantum mechanical for even the moderate phase difference. Sample plots for the $F_1$ and $F_{100}$ cases are given in Tables III and IV in the Appendix.

C. RATE OF CONVERGENCE

In an examination of the small phase difference for which shape converges fastest, one must first develop a measure for the rate of convergence. A simple such definition would be to use the standard deviation, as it approaches zero for either method of approaching equilibrium. Table II shows the distance from quantum mechanics using this measure vs. time. Note that the $F_{100}$ case here is log-log, showing an approximate $\sim t^{-1}$ decay, while the $F_1$ case is logarithmic only on the $y$-axis, showing an exponential decay/convergence.

It can be seen that with this measure of convergence, the $F$ function given by a spike ($c = 100$) converges to quantum mechanics faster within the given time, than that given by a cosine function ($c = 1$). This indicates a faster rate of convergence at early times, for a sharper F-kernel. The flat $F$ function ($c = 0$) approaches equilibrium in a similar rate as the cosine function, until it jumps away from equilibrium.

For the case of $H = 2\sigma_z$, Figure 2 shows if the distribution converges to quantum mechanics for a given width $c$ of the $F$ function in equation 15 and initial phase separation $\Delta \phi_0$ for $\rho(0) = \{\{0.16, 0.08, 0.06\}, \{0.23, 0.3, 0.17\}\}$ and $\phi(0) = \{\{0, \pi, 2\alpha\}, \{\pi + \alpha, \frac{3\pi}{2}, \frac{\pi}{2} + \frac{\pi}{2}\}\}$. The case for $c = 0$, equivalent to $F = 1$, is not shown on the plot, and does not converge. The convergence can be seen for an initial phase separation less than $\frac{\pi}{4}$, while for values above $\Delta \phi_0 \sim 1$, the system does not approach quantum mechanics. Convergence here is defined as having the variance decrease faster than approximately $t^{-0.2}$ by $t = 1000$, however most cases are obvious with a variance either oscillating around unity, or decreasing as $t^{-n}$ with $n > 1$ (or exponentially for $c = 1$) by $t = 1000$ (see Fig. 1). The cases which converge slowly (slower than $t^{-0.5}$) as well as those that converge late (after $t = 500$) are in the purple zone.
Taylor expand both mechanics we can assume more, as we saw above, in the regime close to quantum brevity, and chosen where we have suppressed the dependence on \( a \) exponentially \( n \to -\infty \). The case \( c = 1 \) is not plotted here, as it decays exponentially.

\[ n = \frac{d \ln \sigma_f}{d \ln t}. \]

The colours red, orange, yellow, green, blue and purple correspond to \( c = 2.5, 25, 100, 250 \) and 1000 respectively. We see that convergence is always faster than \( \sigma_f \propto t^{-1} \).

**IV. PERTURBATION THEORY NEAR EQUILIBRIUM**

As we saw above, by construction, the quantum mechanical equations are approximately recovered, when the spread in phases, specified by \( w(a, \phi, t) \) for a given value of the observable \( a, \Delta \phi_a \), satisfies:

\[ \Delta \phi_a \ll \pi, \text{ and } \Delta \phi_a \ll \Delta \phi_F, \tag{16} \]

where \( \Delta \phi_F \) characterizes the phase spread/width of the kernel \( F \). These conditions ensure that different coefficients in the sums: \( \sum_{\phi} w(a, \phi) \) in Eqs. (7-8) factor out, which then let us replace the sums with unity. In other words, for narrowly-spread phases per observable value, one can combine Eqs. 7-8 (or 9-10) for systems, to evolution equations for mean phase and total probability per observable value to approximately recover quantum mechanics (1-2).

In order to examine the next order approximation to compare this evolution to quantum mechanics, we examine the analytical case for a diagonal Hamiltonian. The reason for this choice is that the diagonal case is simple enough to do this calculation analytically, and still can represent any quantum mechanical system (assuming unitary equivalence, which we discuss in the next section). For a diagonal Hamiltonian, Eqs. (7)-(8) separates for different observable values, and can be written as:

\[
\dot{\phi}_i = \sum_j w_j \cos(\phi_i - \phi_j) \sqrt{\frac{\sum_k w_j F(\phi_j - \phi_k)}{\sum_k w_k F(\phi_i - \phi_k)}}, \tag{17}
\]

\[
\dot{w}_i = 2w_i \sum_j w_j \sin(\phi_i - \phi_j) \sqrt{\frac{\sum_k w_j F(\phi_j - \phi_k)}{\sum_k w_k F(\phi_i - \phi_k)}}, \tag{18}
\]

where we have suppressed the dependence on \( a \) for brevity, and chosen \( R^{-1}(a, a) \) as unit of time. Furthermore, as we saw above, in the regime close to quantum mechanics we can assume \( \Delta \phi \ll \pi, \Delta \phi_F \), thus we can Taylor expand both \( F \) and cosine:

\[
\cos(\phi - \phi') \simeq 1 - \frac{(\phi - \phi')^2}{2}, \tag{19}
\]

\[
F(\Delta \phi) \simeq 1 - \frac{\Delta \phi^2}{\Delta \phi_F^2}, \tag{20}
\]

where \( \Delta \phi_F^{-2} = -\frac{1}{2} F''(0) \) here. For example, \( \Delta \phi_F = 2e^{-1} \) for systems studied in the last section (Eq. 15). In this limit, the evolution for \( \dot{\phi}_i \) and \( \dot{w}_i \) can be approximated as:

\[
\dot{\phi}_m = \frac{\lambda}{2} \left[(\phi_i - \langle \phi \rangle)^2 - (\phi_m - \langle \phi \rangle)^2\right] + O(\Delta \phi^4), \tag{21}
\]

\[
\dot{w}_i = 2w_i(\phi_i - \langle \phi \rangle) + O(\Delta \phi^3), \tag{22}
\]

where

\[
\lambda \equiv \Delta \phi_F^{-2} - 1, \tag{23}
\]

\[
\phi_{im} \equiv \phi_i - \phi_m, \tag{24}
\]

\[
\langle \phi \rangle \equiv \sum_i w_i \phi_i. \tag{25}
\]

We now notice that Eq. (21) can be written as:

\[
\frac{d}{dt}(\phi_i - \langle \phi \rangle) - \frac{\lambda}{2}(\phi_i - \langle \phi \rangle)^2 = G(t), \tag{26}
\]

where \( G(t) \) is a yet to be determined function of time. In particular, combining Eqs. (25-26) yields:

\[
G(t) = -\frac{(\lambda + 4)}{2}(\Delta \phi^2) = -\frac{(\lambda + 4)}{2} \sum_i w_i(\phi_i - \langle \phi \rangle)^2. \tag{27}
\]

The advantage of Eq. (26) is that it decouples the evolution for different phases, and thus reduces to a first order ODE for a given \( G(t) \). Unfortunately, the solution cannot be written in closed form for arbitrary \( G(t) \).
A. Power Law Convergence: $\lambda > 0$

We first introduce an ansatz, which, as we see below, is applicable for $\lambda > 0$, or equivalently $\Delta\phi_F < 1$ (implying $c > 2$ for the models of Sec. III).

To proceed, we next notice a scaling symmetry of the Equations (21-22), which remain invariant under:

$$\phi_{in} \rightarrow A \times \phi_{in}, \quad t \rightarrow A^{-1} \times t, \quad (28)$$

for arbitrary $A$. Therefore, we postulate an ansatz: $G(t) \propto \langle \Delta \phi^2 \rangle \sim t^{-2}$. With this assumption, it is convenient to define:

$$\tilde{\phi}_i \equiv \lambda t (\phi_i - \langle \phi \rangle), \quad \tau \equiv \ln(t), \quad G(t) = - \frac{\sigma^2 - 1}{2\lambda^2}, \quad (29)$$

which let us write Eq. (26) as

$$\tilde{\phi}_i' = \tilde{\phi}_i + \frac{1}{2} \tilde{\phi}_i^2 - \frac{\sigma^2 - 1}{2} = \frac{1}{2} (\tilde{\phi}_i + \sigma + 1) (\tilde{\phi}_i - \sigma + 1). \quad (30)$$

$$w_i' = 2\lambda^{-1} w_i \tilde{\phi} \quad (31)$$

Note that $\sigma$ is an arbitrary constant, with $\sigma > 1$ for $\lambda > 0$ and $0 < \sigma < 1$ for $\lambda < 0$, which is set by the variance of $\phi$, by combining Eqs. (29) and (27):

$$\langle \tilde{\phi}^2 \rangle = \frac{\sigma^2 - 1}{1 + 4/\lambda}. \quad (32)$$

Moreover, $'$ denotes derivative with respect to $\tau$.

Interestingly, both the variance of $\tilde{\phi}$ (Eq. 32) and its equations of motion (30-31) become time-independent, which potentially admit steady state distributions. In particular, Eq. (30) has two fixed points at

$$\tilde{\phi}_\pm = -1 \pm \sigma. \quad (33)$$

The fixed point $\tilde{\phi}_+$ is an unstable fixed point, while $\tilde{\phi}_-$ is stable. For positive $\lambda$, it turns out that phases approach infinity (in the perturbative eq’s) within a finite time in the interval $(\tilde{\phi}_+, \infty)$, which given the periodic nature of phase, puts them within $(-\infty, \tilde{\phi}_-)$. For negative $\lambda$, the stability and evolution for $\tilde{\phi}$ is identical to that for positive $\lambda$, but this is not the case for $\phi$. Since $\frac{\partial \tilde{\phi}_i}{\partial \phi} = 1 + \tilde{\phi}_i = \pm \sigma$, near the fixed point $\tilde{\phi}_i = \tilde{\phi}_\pm \propto t^{\pm \sigma}$ which is equivalent to $\Delta \phi \propto t^{\frac{\sigma}{\lambda} - 1} + C t^{-1}$, where $C$ is an unknown constant. Since $\sigma < 1$ for negative $\lambda$, this is stable for both fixed points. Therefore, given that we would like to study small phase variances, it stands to reason that we focus on the $(\tilde{\phi}_-, \tilde{\phi}_+)$ interval. Now, defining $w(\tilde{\phi})$ as the weight (or probability) density in the $\tilde{\phi}$ space, we can write the steady-state continuity equation:

$$\frac{\partial w (\tilde{\phi})}{\partial \tau} + \frac{\partial}{\partial \tilde{\phi}} \left[ w(\tilde{\phi}) \tilde{\phi}' \right] = w(\tilde{\phi}), \quad (34)$$

which, plugging from Eqs. (30-31), becomes:

$$\frac{\partial}{\partial \tilde{\phi}} \left[ w(\tilde{\phi}) \left( \tilde{\phi}' + \frac{1}{2} \tilde{\phi}^2 - \frac{\sigma^2 - 1}{2} \right) \right] = 2\lambda^{-1} w(\tilde{\phi}) \tilde{\phi}. \quad (35)$$

which can be integrated to give:

$$w(\tilde{\phi}) \propto (\tilde{\phi}^+ - \tilde{\phi})^{\alpha_+} (\tilde{\phi} - \tilde{\phi}^-)^{-\alpha_-},$$

$$\alpha_\pm = -1 + \frac{2}{\lambda} \mp \frac{2}{\lambda \sigma}. \quad (36)$$

We notice a few interesting properties of this solution:

1. For $\lambda > 0, \alpha_+ > -1$, which ensures that the probability $= \int w(\tilde{\phi}) d\tilde{\phi}$ is finite. This is not the case for $\lambda < 0,$ implying that the steady-state solution is non-existent. We can thus consider:

$$\lambda = \Delta \phi F^2 - 1 = -\frac{1}{2} F''(0) - 1 > 0, \quad \Rightarrow - F''(0) > 2 \quad (37)$$

as a necessary condition to approach equilibrium, at least within the above scaling ansatz: $G(t) \propto t^{-2}$.

2. We further notice that integrating the continuity equation (35) over our domain $(\tilde{\phi}_-, \tilde{\phi}_+), as the left hand side is a total derivative, and its argument $w(\tilde{\phi}) \tilde{\phi}'$ vanishes at the boundaries (since $\alpha_+ > -1$). Therefore, the right hand side $\propto \int \tilde{\phi} w(\tilde{\phi}) d\tilde{\phi} = \langle \tilde{\phi} \rangle = 0$, which is consistent with our definition of $\tilde{\phi}$ (Eq. 29).

We note that the condition $\lambda > 0$ is equivalent to $c > 2$, where we see a power law decay of the standard deviation $\sigma \propto t^{-1}$ in our numerical simulations (e.g. third row in Table II). Therefore, in spite of the fact that the analysis above is for continuum distributions, it roughly predicts the correct asymptotic behaviour of simple discrete simulations.

B. Exponential Convergence: $\lambda < 0$

As we saw above, for $\lambda < 0$ (or $\Delta \phi_F > 1$), the power-law ansatz does not lead to a sensible asymptotic steady state distribution. Let us now propose a different ansatz, i.e. that asymptotically $w(\Delta \phi)$ becomes time-independent, without additional time re-scaling, where $\Delta \phi \equiv \phi - \langle \phi \rangle$. Moreover, we assume $G(t) = \langle \Delta \phi^2 \rangle = 0$. Again, since there is no explicit time-dependence left in the evolution equations, the continuity equation (34) now reads:

$$\frac{\partial w(\Delta \phi)}{\partial \tau} + \frac{\partial}{\partial \Delta \phi} \left[ w(\Delta \phi) \right] = 2w(\Delta \phi) \Delta \phi, \quad (38)$$

which can be integrated to give:

$$w(\Delta \phi) \propto (\Delta \phi)^{4/\lambda - 2}. \quad (39)$$

Since the integrals over $w(\Delta \phi)$ are divergent for $\lambda < 0$, we have to use a cut-off $\Delta \phi_{min} \rightarrow 0$. After properly normalizing $w(\Delta \phi)$, this yields:

$$\langle \Delta \phi^2 \rangle = \left( \frac{\lambda - 1}{-\lambda - 4} \right) \Delta \phi_{min}^2 \rightarrow 0, \text{ for } -1 < \lambda < 0, \quad (40)$$
consistent with $G(t) = 0$ ansatz above.

Given that this static solution has zero variance, it appears that it cannot have any discrete counterpart. However, one may consider any initial condition $w(\Delta \phi)$ as a perturbation around this static solution, which could be expanded into exponentially decaying modes [12]. While not entirely rigorous, this analytic argument provides an intuitive understanding of why convergence to quantum mechanics is exponential, rather than power-law, for $\lambda < 0$, or $c < 2$, e.g. in the second row in Table II.

C. Approaching Quantum Mechanics

How does this deviation from quantum mechanics affect physical observable values? Simple manipulations yield:

$$\langle \phi \rangle^{\ddagger} = \frac{d}{dt} \sum_{i} w_i \phi_i = 1 + (\Delta \phi^2) + O(\Delta \phi^4), \quad (41)$$

More generally, we can write a hierarchy of equations for all the moments of $\Delta \phi$:

$$\langle \Delta \phi^m \rangle = (2 + \frac{m \lambda}{2})(\Delta \phi^{m+1}) - \frac{m(\lambda + 4)}{2}(\Delta \phi^2)\langle \Delta \phi^{m-1} \rangle, \quad (42)$$

which can provide an alternative approach to numerically study convergence to quantum mechanics. Instead, here we simply wrap up by making some observations about potential smoking guns of this theory. After reintroducing physical units, Eq. 41 reads:

$$\langle \phi \rangle^{\ddagger} - \phi_{QM} = (\Delta \phi^2) \times \phi_{QM}, \quad (43)$$

which represents a deviation from quantum mechanics proportional to the variance of phases. This correction can be absorbed into the Hamiltonian eigenvalues,

$$\hat{H}_{ii} = H_{ii} \left( 1 + \langle \Delta \phi^2 \rangle \right), \quad (44)$$

giving an evolving effective Hamiltonian close to the true Hamiltonian. As we saw above (Secs. IV A-IV B):

$$\langle \Delta \phi^2 \rangle \propto (Et)^{-2n}, n \geq 1. \quad (45)$$

Therefore, one expects a time-dependent part of the energy levels of e.g. atoms/nuclei, that decays as $(Et)^{-2}$ or faster asymptotically.

V. DISCUSSIONS

Many of the issues with the original real ensemble model, presented in Section VI of [5], still remain open. The only exception is the stability of the quantum mechanical equilibrium, which we have demonstrated for a certain class of the non-equilibrium equations. Here, we discuss some of the other conceptual challenges (or features) in Smolin’s real ensemble extension of the quantum theory:

A. Zero Occupancy States

An interesting aspect of this model is the fact that if $\rho_a = 0$, $\dot{\rho_a} = 0$ and this potential observable value is effectively non-existent. This is necessary as Equation 1 breaks down when $\rho_a = 0$. In the non-equilibrium extension, this becomes $\rho_i = 0$ meaning $\rho_i = 0$. Despite the $\sum_{k} \rho_k \delta_{a_ia_b}$ term in the denominator of Equation 10, it can be seen that this remains true even if all $\rho_i$ terms are zero for a given value of $a_i$. This will effectively eliminate a set of beables from being possible if at any time in its evolution, that set of beables has a zero probability. This ensures the quantum mechanical case is a fixed point, as if each value of the observable only has one potential phase, no other potential phases will be able to become non-zero, and the condition of one phase per value of the observable is maintained. This also causes a non-quantum mechanical issue at the nodes of a quantum mechanical system in the cases where in quantum mechanics a node ceases to be a node at later times due to the evolution.

This model is also by nature discrete. This implies two things for the property above. First is the finiteness of the number of sets of beables, which will cause issues with the examination of continuous and infinite systems as will be examined in the next section. The second is what happens in a large $N$ system for pairs of beables or times with small enough probability such that $N$ is no longer large enough to prevent the discreteness from effecting the system and its behaviour. This is not just at a node of exactly zero probability, but near one of very small probability. In this case finite behaviours become important, and there is a potential for complete loss of a beable pair by chance, even if the continuous probability dictates that the probability is never exactly
TABLE II. Plots of the standard deviation of the phases for the cases in Figure I. From top to bottom, the functions $F$ within equations 9 and 10 for the plots are $F = 1$, $F = \cos^2 \left(\frac{\theta}{c}\right)$, and $F$ given by equation 15 with $c = 100$. The first two plots have a logarithmic scaling for the y-axis, while the scaling of both axes are logarithmic for the third plot.

| $\Delta \phi_0$ | Standard Deviation of Phase vs Time |
|----------------|-----------------------------------|
| $H = 2\gamma_2$ | ![Plot](image1.png) |
| $H = 2\gamma_z$ | ![Plot](image2.png) |
| $H = 2\gamma_x$ | ![Plot](image3.png) |

The most obvious choice is to take the Hamiltonian eigenspace as preferred, as it exists in all cases and is native to the equations. Of course, this doesn’t make it the correct, but rather the simplest possible choice. It is also discrete for finite systems. An issue remains for degeneracies in the eigenstates of this basis, where the Hamiltonian fails to single out a basis, unless the degeneracies are only an idealization/approximation of the system. This choice has both the advantage and disadvantage of simplifying the equations. The advantage being that the simplified system is easy to work with and understand. The disadvantage being that no equilibrium evolution is seen and parts of the equations remain unused - parts that match quantum mechanics in equilibrium and enabled the conclusion that this set of equations matches quantum mechanics.

B. Unitary Equivalence vs Preferred Basis

Technically, our current model chooses a preferred basis of the Hilbert space, defined by the eigenstates of the observable that is realized in the real ensemble theory. However, this would imply that, e.g. only spin in one direction can be measured - it does not account/allow for choice of non-commuting observables, which is part of what contrasts quantum and classical mechanics. Since we would like to account for the existence of non-commuting observables, we need to ask what the model would give if one were to measure a different observable. To do this, the model would either have to define a preferred basis for the theory from which other measurements could be determined or one has to have a definite observable value for many bases. Both proposals have flaws. Since this model is discrete by nature (only continuous by approximation), taking position, or even momentum in a continuous spacetime would suffer from the “node” problem mentioned above - the probabilities would be spread too thin, exposing the discreteness of the model, causing certain observable values to be unrepresented, and therefore never represented. In order to take one of these as the preferred basis as might be desired, a discrete space-time is required.

Taking space-time discrete and position space, momentum space, Hamiltonian, or all three together as the preferred basis/bases, might help if $N$ is large enough. Any discrete eigen-space would work - e.g. that of the Hamiltonian. A discrete but infinite system would not be able to have all eigenstates represented though, for a finite $N$.

Even for a finite system, however, if we choose to maintain unitarity, the fact that the system is finite is again a problem. There is an infinite number of unitary transformations, unless somehow we discretize this, for instance by having discreteness in angles for the case of the spin-1/2 system. So we must take a finite set of preferred bases, something which in this case, unlike the infinite case, does create a finite number of types of members of the ensemble in the equilibrium model.

In continuing with this, a finite number of represented phases per value of each observable is also required to maintain the fact the system is finite.

The most obvious choice is to take the Hamiltonian eigenspace as preferred, as it exists in all cases and is native to the equations. Of course, this doesn’t make it the correct, but rather the simplest possible choice. It is also discrete for finite systems. An issue remains for degeneracies in the eigenstates of this basis, where the Hamiltonian fails to single out a basis, unless the degeneracies are only an idealization/approximation of the system. This choice has both the advantage and disadvantage of simplifying the equations. The advantage being that the simplified system is easy to work with and understand. The disadvantage being that no equilibrium evolution is seen and parts of the equations remain unused - parts that match quantum mechanics in equilibrium and enabled the conclusion that this set of equations matches quantum mechanics.

C. Real Ensemble Model and Early Universe

Given the experimental success of quantum mechanics in explaining microscopic phenomena, any phenomenologically viable real ensemble theory must be stable to perturbations away from quantum mechanics, at least within the tested regimes. Indeed, as we have demonstrated in this paper, this is possible for a large space of parameters in our formulation. Therefore, any smoking gun for this theory should be sought beyond the current empirical regime, i.e. very high (or possibly very low) energies, or prior to convergence to quantum mechanics. Both these conditions are met in the early universe, which implies that one could potentially search for signatures of deviations from quantum equilibrium in cosmological observations.

As we pointed out in the introduction, indeed one of the motivations for studying hidden variable theories
away from quantum equilibrium, is non-local signalling that could provide a resolution to the cosmological horizon problem [3], as well as observed super-horizon correlations in the CMB. Let us see how this could happen in our framework:

The spectrum curvature fluctuations in the radiation era is given by (e.g., see [13]):

\[ P_\zeta(k) = \left( \frac{1 + 2n_k}{(4\pi)^2 \sqrt{3}} \right) \left( \frac{k}{M_p} \right)^2, \quad (46) \]

where \( n_k \) is the mean occupation number of the mode \( k \), and \( M_p \) is the Planck mass. In the ground state of quantum mechanics \( n_k = 0 \). However, as we saw in Eq. (44) the phase variance introduces a correction to the effective energy of all the energy eigenstates, including the ground state. Given that energy of a harmonic oscillator scales as \( n_k + \frac{1}{2} \), we may interpret this correction as:

\[ n_k = \frac{1}{2} \langle \Delta \phi^2 \rangle \simeq \frac{1}{2} \langle \Delta \phi^2 \rangle_0, \quad (47) \]

where we used the results of Sec. IV (e.g., Eq. 45) for the asymptotic scaling of the phase variance. Furthermore, for the ground state:

\[ E_k = \frac{1}{2} \omega_k = \frac{c_s^2 k}{2} = \frac{k}{2 \sqrt{3}}, \quad (48) \]

where we used \( c_s^2 = 1/3 \) for the radiation fluid. Plugging this into Eq. (46) yields:

\[ P_\zeta(k) = \left( \frac{k}{M_p} \right)^2 \left( \frac{\sqrt{3} \langle \Delta \phi^2 \rangle_0}{8\pi^2 (M_p t)^2} \right). \quad (49) \]

We thus see that the correction term to the \( \zeta \) power spectrum is indeed scale-invariant, and assuming \( t \sim 10^4 \sqrt{\langle \Delta \phi^2 \rangle_0 M_p^{-1}} \), yields \( P_\zeta \sim 10^{-9} \), which is roughly consistent with cosmological observations.

Of course, the interpretation of the result in Eq. (49) is far from straightforward. For example, \( P_\zeta \) should become independent of time on superhorizon scales in standard cosmology. So, at what time, \( t \), should we expect the evolution of \( \zeta \) to freeze, if at all? This will be a necessary condition for the scale-invariant term to not be negligible at late times.

A more serious problem with interpreting Eq. (49) as the origin of cosmological primordial power spectrum, is that it requires \( \langle \Delta \phi^2 \rangle \gg 1 \) to match the amplitude of CMB anisotropies, thus invalidating the near-equilibrium approximation. Therefore, we should only consider this result as a suggestive direction for further exploration of the implications of the real ensemble theory for early universe, pending a deeper understanding of its physics.

D. Real Ensemble Model, Quantum Gravity, and Cosmological Constant Problem

A surprising feature of the real ensemble theory that was discovered here, is that the rate of convergence to quantum mechanics depends on the absolute (and not relative) energy. This suggests a possible connection to gravitational physics, as gravity is the only interaction that is sensitive to the total energy of a system. In other words, total energy of a system sources both its gravity, AND its convergence to quantum mechanics.

As an example, let us consider the expectation for the vacuum energy, or the cosmological constant. In Eq. (44), we saw that the effective energies of eigenstates receive corrections as:

\[ E = E_{QM} + \frac{\langle \Delta \phi^2 \rangle_0}{E_{QM} t^2}, \quad (50) \]

if we interpret \( \langle \phi \rangle \) as energy, \( E \). Now, this energy has a minimum:

\[ E_{min} \sim 2\sqrt{\langle \Delta \phi^2 \rangle_0 t}. \quad (51) \]

Now, if we interpret this as vacuum energy within a Hubble patch of the universe:

\[ \rho_{vac} \sim E_{min} H^3 \sim (14 \text{ meV})^4 \sqrt{\langle \Delta \phi^2 \rangle_0} T(\text{TeV})^8, \quad (52) \]

which is comparable to the observed dark energy density, if we set \( t \) to the time of electroweak phase transition, or temperature \( T \sim \text{TeV} \) (and \( \langle \Delta \phi^2 \rangle_0 \sim 1 \)):

This might be a reasonable scale to plug in here, as quantum field theory is not well probed beyond TeV scale.

E. Alternative Non-Equilibrium Real Ensemble Model

In converting from equations 7 and 8 to equations 9 and 10, we note an additional possible extension of the model outside of the quantum mechanical case. This case comes from factoring out a \( \rho_0 \) term from the square root to remove this term from the denominator of the weight function before taking the equation out of equilibrium. It is equivalent to the case when all instances of \( \sum_k \delta_{a,k} \rho_{a,k} \) are replaced with \( \rho_{a} \). The resulting equations governing the model are:

\[ \dot{\phi}_i = \sum_j \frac{\rho_j}{\sqrt{\rho_{a,j} \rho_{a,i}}} \times R(a_i, a_j) \cos [\phi_i - \phi_j + \delta(a_i, a_j)], \quad (53) \]
\[ \dot{\rho}_i = \sum_j \frac{\rho_i \rho_j}{\sqrt{\rho_{a_j} \rho_{a_i}}} \times 2R(a_i, a_j) \sin [\phi_i - \phi_j + \delta(a_i, a_j)]. \] (54)

Several aspects make this model appear simpler. The square root denominator is the same for both \( \dot{\phi} \) and \( \dot{\rho} \). There is only one type of \( \dot{\rho} \) term. In addition, the weighting based on \( \rho_i \) is obvious and separate from the square root terms. This change comes from acknowledging this implicit weighting from the equilibrium model, and separating it from the square roots.

Numerically, the new model gives results close to, if not effectively identical to, the original model when analyzing for convergence. This means that although the exact evolution may differ, all result obtained for the original non-equilibrium model remain valid. The convergence is invariant to this change in extrapolation.

Both models are identical when \( F = 1 \).

VI. CONCLUSIONS

Inspired by theoretical and observational motivations for violating relativistic locality, we explored the non-local real ensemble model, in the context proposed by Smolin [9]. In particular, the theory generalizes quantum mechanics by allowing a range of (or uncertainty in) quantum phase per value of an observable.

We first developed the generalized evolution for the real ensemble, which consist of continuous phase evolution, and copy rules. We then provided both numerical and analytic evidence for why quantum mechanics (with one phase per observable value) is a local stable fixed point for most of the parameter space of the theory. Moreover, the phase variance, as well as deviations from quantum mechanical frequencies decay faster than \((Et)^{-2n}\), with \( n \geq 1 \), for stable models. The energy scale of this decay is the absolute energy rather than relative energy of the system, which suggests a possible connection to gravitational physics.

Finally, we discussed different conceptual aspects of the real ensemble theory. This includes the need for a preferred basis in the Hilbert space (and/or further interpretation), as well as potential novel applications for the spectrum of primordial cosmological perturbations and the cosmological constant problem.

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Appendix A: Various Plots of Numerical Simulations

Here are given additional plots of the numerical simulations for those that wish to confirm certain aspects covered in the paper.
TABLE III. Plots of the evolution of spin-$\frac{1}{2}$ systems in the non-equilibrium real ensemble model for the case with a moderate initial separation of phases. Each case has three different phases for each of the two potential values of $s_z$. The initial conditions are $\rho(0) = \{(0.16, 0.08, 0.06), (0.23, 0.3, 0.17)\}$ if marked as uneven or $\rho(0) = \{(0.2, 0.1, 0.2), (0.2, 0.1, 0.2)\}$ if marked as even and $\phi(0) = \{0, 0.1\pi, 0.2\pi\}, \{\frac{\pi}{2}, 0.1\pi, \frac{\pi}{2}, 0.05\pi\}$. The Hamiltonian is $H = \sigma_x + \sigma_z$ for the first two plots and $H = 2\sigma_z$ for the third. The functions $F$ within equations 9 and 10 for the plots are $F = \cos^2(\frac{d\phi}{2})$ for the top plot and $F$ given by equation 15 with $c = 100$ for the other two.
TABLE IV. Plots of the evolution of spin-$\frac{1}{2}$ systems in the non-equilibrium real ensemble model for the case of large initial separation of phases. Each case has three different phases for each of the two potential values of $s_z$. The initial conditions are $\rho(0) = \{\{0.16, 0.08, 0.06\}, \{0.23, 0.3, 0.17\}\}$ and $\phi(0) = \{\{0, 1, 2\}, \{\frac{\pi}{2} + 1, \frac{\pi}{2}, \frac{\pi}{2} + 0.5\}\}$. The Hamiltonian is $H = \sigma_x + \sigma_z$ for the top plot and $H = 2\sigma_z$ for the bottom plot. From top to bottom, the functions $F$ within equations 9 and 10 for the plots are $F = \cos^2(\frac{2\pi}{5})$ and $F$ given by equation 15 with $c = 100$.

| Probability vs Time | Total Probability vs Time | Phase Difference vs Time |
|---------------------|---------------------------|--------------------------|
| ![Probability vs Time](image1.png) | ![Total Probability vs Time](image2.png) | ![Phase Difference vs Time](image3.png) |

TABLE V. Plots of the evolution of spin-$\frac{1}{2}$ systems in the non-equilibrium real ensemble model for the case with a Hamiltonian proportional to the identity. Each case has three different phases for each of the two potential values of $s_z$. The initial conditions are $\rho(0) = \{\{0.16, 0.08, 0.06\}, \{0.23, 0.3, 0.17\}\}$ and $\phi(0) = \{\{0, 0.001\pi, 0.002\pi\}, \{\frac{\pi}{2} + 0.001\pi, \frac{\pi}{2}, \frac{\pi}{2} + 0.0005\pi\}\}$. The Hamiltonian is $H = 2I$. From top to bottom, the functions $F$ within equations 9 and 10 for the plots are $F = \cos^2(\frac{2\pi}{5})$ and $F$ given by equation 15 with $c = 100$. Note that the standard deviation plots are logarithmic in scale on the $y$-axis, with the second such plot being logarithmic in scale on both axes.

| Probability vs Time | Phase Difference vs Time | Standard Deviation vs Time |
|---------------------|--------------------------|---------------------------|
| ![Probability vs Time](image4.png) | ![Phase Difference vs Time](image5.png) | ![Standard Deviation vs Time](image6.png) |