Research Article

Some Improved Ratio, Product, and Regression Estimators of Finite Population Mean When Using Minimum and Maximum Values

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Efficient estimation of finite population mean is carried out by using the auxiliary information meaningfully. In this paper we have suggested some modified ratio, product, and regression type estimators when using minimum and maximum values. Expressions for biases and mean squared errors of the suggested estimators have been derived up to the first order of approximation. The performances of the suggested estimators, relative to their usual counterparts, have been studied, and improved performance has been established. The improvement in efficiency by making use of maximum and minimum values has been verified numerically.

1. Introduction

Supplementary information in form of the auxiliary variable is rigorously used for the estimation of finite population mean for the study variable. Ratio and product estimators due to Cochran [1] and Murthy [2], respectively, are good examples when information on the auxiliary variable is incorporated for improved estimation of finite population mean of the study variable. When correlation between the study variable \( y \) and the auxiliary variable \( x \) is positive, ratio method of estimation is effective and when correlation is negative, product method of estimation is used. There are a lot of improvements and advancements in the construction of ratio, product, and regression estimators using the auxiliary information. For recent details, see Haq et al. [3], Haq and Shabbir [4], Yadav and Kadilar [5], Kadilar and Cingi [6], and Koyuncu and Kadilar [7] and the references cited therein.

The ratio method of estimation is at its best when the relationship between \( y \) and \( x \) is linear and the line of regression passes through the origin but as the line departs from origin, the efficiency of this method decreases. In practice, the condition that the line of regression passes through the origin is rarely satisfied and regression estimator is used for estimation of population mean.

Let \( U = (U_1, U_2, \ldots, U_N) \) be a population of size \( N \). Let \((y_i, x_i)\) be the values of the study and the auxiliary variables, respectively, on the \( i \)th unit of a finite population.

Let us assume that a simple random sample of size \( n \) is drawn without replacement from \( U \) for estimating the population mean \( \bar{Y} = \frac{1}{N} \sum_{i=1}^{N} y_i \). It is further assumed that the population mean \( \bar{X} = \frac{1}{N} \sum_{i=1}^{N} x_i \) of the auxiliary variable \( x \) is known. The minimum say \((x_{\text{min}})\) and maximum say \((x_{\text{max}})\) values of the auxiliary variables are also assumed to be known.

The variance of mean per unit estimator \( \bar{Y} = \frac{1}{n} \sum_{i=1}^{n} y_i/n \) is given by

\[
V(\bar{Y}) = n^2 \lambda^2 S^2_y,
\]

where \( \lambda = ((1/n) - (1/N)) \) and \( S^2_y = (1/(N-1)) \sum_{i=1}^{N} (y_i - \bar{Y})^2 \).

Some time there exists unusually very large (say \( y_{\text{max}} \)) and very small (say \( y_{\text{min}} \)) units in the population. The mean per unit estimator is very sensitive to these unusual observations and as a result population mean will be either underestimated (in case the sample contains \( y_{\text{min}} \)) or overestimated...
(in case the sample contains \( y_{ \text{max}} \)). To overcome the situation Sarndal [8] suggested the following unbiased estimator:

\[
\bar{y}_s = \begin{cases} 
\bar{y} + c & \text{if sample contains } y_{\text{min}} \text{ but not } y_{\text{max}}, \\
\bar{y} - c & \text{if sample contains } y_{\text{max}} \text{ but not } y_{\text{min}}, \\
\bar{y} & \text{for all other samples,}
\end{cases}
\]  

where \( c \) is a constant.

The variance of \( \bar{y}_s \) is given by

\[
V(\bar{y}_s) = \frac{\lambda S^2_y}{N - 1} \left( y_{\text{max}} - y_{\text{min}} - nc \right). 
\]  

Further, \( V(\bar{y}_s) < V(\bar{y}) \) if \( 0 < c < (y_{\text{max}} - y_{\text{min}})/n \).

For, \( c_{\text{opt}} = (y_{\text{max}} - y_{\text{min}})/2n \), variance of \( \bar{y}_s \) is given by

\[
V(\bar{y}_s)_{\text{opt}} = V(\bar{y}) - \frac{\lambda (y_{\text{max}} - y_{\text{min}})^2}{2(N - 1)},
\]

which is always smaller than \( V(\bar{y}) \).

The usual ratio and product estimators of population mean \( \bar{Y} \) are given by

\[
\bar{Y}_R = \bar{y} \left( \frac{\bar{x}}{\bar{X}} \right),
\]

\[
\bar{Y}_P = \bar{y} \left( \frac{\bar{x}}{\bar{X}} \right),
\]

where \( \bar{y} = \frac{1}{n} \sum_{i=1}^{n} y_i/n \) and \( \bar{x} = \frac{1}{n} \sum_{i=1}^{n} x_i/n \) are the sample means of variables \( y \) and \( x \), respectively.

The expressions for biases \( (B(\cdot)) \), and mean square errors \( (M(\cdot)) \), of the conventional ratio and product estimators, are given by

\[
B(\bar{Y}_R) \equiv \bar{y} \lambda \left( C_x^2 - \rho_{yx} C_y C_x \right),
\]

\[
B(\bar{Y}_P) \equiv \bar{y} \lambda \rho_{yx} C_y C_x,
\]

\[
M(\bar{Y}_R) \equiv \bar{y}^2 \lambda \left( C_y^2 + C_x^2 - 2 \rho_{yx} C_x C_x \right),
\]

\[
M(\bar{Y}_P) \equiv \bar{y}^2 \lambda \left( C_y^2 + C_x^2 + 2 \rho_{yx} C_x C_x \right),
\]

where \( C_y = S_y/\bar{Y} \) and \( C_x = S_x/\bar{X} \) are the coefficients of variation of \( y \) and \( x \), respectively, \( \rho_{yx} = S_{yx}/S_y S_x \) is the correlation coefficient between \( y \) and \( x \), \( S_y^2 = \sum_{i=1}^{N} (y_i - \bar{Y})^2/(N - 1) \), and \( S_{yx} = \sum_{i=1}^{N} (y_i - \bar{Y})(x_i - \bar{X})/(N - 1) \) are the population variance and population covariance, respectively.

Usual regression estimator is given by

\[
\bar{Y}_{lR} = \bar{y} + b \left( \bar{X} - \bar{x} \right),
\]

where \( b \) is the sample regression coefficient.

The variance of the estimator \( \bar{Y}_{lR} \) is given by

\[
V(\bar{Y}_{lR}) = \lambda S^2_y (1 - \rho_{yx}^2).
\]

### 2. Proposed Estimators

Motivated by Sarndal [8], we extend this idea to estimators which make use of the auxiliary information for increased precision. It is well known that ratio and product estimators are used when \( y \) and \( x \) are positively and negatively correlated, respectively. We suggest estimator for each case separately as follows.

**Case I** (positive correlation between \( y \) and \( x \)). When \( y \) and \( x \) are positively correlated, then with selection of a larger value of \( x \), a larger value of \( y \) is expected to be selected and when smaller value of \( x \) is selected, selection of a smaller value of \( y \) is expected. So we define the following estimators:

\[
\bar{Y}_{RC} = \frac{\bar{Y}_{c_{11}}}{\bar{X}_{c_{12}}} X = \left( \frac{\bar{y} + c_1}{\bar{x} + c_2} \right) \bar{X}
\]

and similarly

\[
\bar{Y}_{bC1} = \bar{y}_{c_{11}} + b \left( \bar{X} - \bar{x}_{c_{12}} \right),
\]

where \( (\bar{Y}_{c_{11}} = \bar{y} + c_1, \bar{X}_{c_{21}} = \bar{x} + c_2) \) if the sample contains \( y_{\text{min}} \) and \( x_{\text{min}} \); \( (\bar{Y}_{c_{11}} = \bar{y} - c_1, \bar{X}_{c_{21}} = \bar{x} - c_2) \) if the sample contains \( y_{\text{max}} \) and \( x_{\text{max}} \), and \( (\bar{Y}_{c_{11}} = \bar{y}, \bar{X}_{c_{21}} = \bar{x}) \) for all other combinations of samples.

**Case 2** (negative correlation between \( y \) and \( x \)). When \( y \) and \( x \) are negatively correlated then with selection of a larger value of \( x \), a smaller value of \( y \) is expected to be selected and when smaller value of \( x \) is selected, a larger value of \( y \) is expected to be selected. Keeping these points in view, the following estimators are therefore suggested:

\[
\bar{Y}_{RC} = \frac{\bar{Y}_{c_{12}}}{\bar{X}_{c_{11}}} X = \left( \frac{(\bar{y} - c_1)(\bar{x} + c_2)}{\bar{x}} \right)
\]

and similarly

\[
\bar{Y}_{bC2} = \bar{y}_{c_{11}} + b \left( \bar{X} - \bar{x}_{c_{22}} \right),
\]

where \( (\bar{Y}_{c_{12}} = \bar{y} + c_1, \bar{X}_{c_{22}} = \bar{x} - c_2) \) if sample contains \( y_{\text{min}} \) and \( x_{\text{max}} \); \( (\bar{Y}_{c_{12}} = \bar{y} - c_1, \bar{X}_{c_{22}} = \bar{x} - c_2) \), if sample contains \( y_{\text{max}} \) and \( x_{\text{min}} \), and \( (\bar{Y}_{c_{12}} = \bar{y}, \bar{X}_{c_{22}} = \bar{x}) \) for all other combinations of samples.

To find the bias and mean square error of these suggested estimators, we first prove two theorems which will be used in subsequent derivations.
**Theorem 1.** If a sample of size \( n \) units is drawn from a population of size \( N \) units, then the covariance between \( \bar{y}_{c_{11}} \) and \( \bar{x}_{c_{11}} \), when they are positively correlated, is given by

\[
\text{Cov}(\bar{y}_{c_{11}}, \bar{x}_{c_{11}}) = \lambda S_{yx} - \frac{n\lambda}{N-1} 
\times \left[ c_1 (x_{\text{max}} - x_{\text{min}}) + c_2 (y_{\text{max}} - y_{\text{min}}) 
- 2nc_1c_2 \right].
\]

(16)

**Proof.** Let us assume that \( n \) units have been drawn without replacement from a population of size \( N \). Let \( S_n \) denote a sample space. We partition the whole sample space into three mutually exclusive and collectively exhaustive sets, that is, \( S_1, S_2, \) and \( S_3 \) such that \( S_n = S_1 \cup S_2 \cup S_3 \). Further \( S_1 \) is the set of all possible samples which contains \( y_{\text{min}} \) and \( x_{\text{min}} \), and \( S_3 \) consists of all samples which contains \( y_{\text{max}} \) and \( x_{\text{max}} \), and \( S_3 = S - S_1 - S_2 \). The number of sample points in \( S_1, S_2, \) and \( S_3 \) is given by \( (\frac{N-2}{n}) \), \( (\frac{N-2}{n}) \), and \( (\frac{N}{n}) - 2(\frac{N-2}{n-1}) \), respectively.

By definition of covariance, we have

\[
\text{Cov}(\bar{y}_{c_{11}}, \bar{x}_{c_{11}}) = \left(\frac{N}{n}\right)^{-1} \left[ \sum_{s \in S_1} (\bar{y} - \bar{c}_1 - \bar{y}) (\bar{x} + \bar{c}_2 - \bar{x}) 
+ \sum_{s \in S_2} (\bar{y} - \bar{c}_1 - \bar{y}) (\bar{x} - \bar{c}_2 - \bar{x}) 
+ \sum_{s \in S_3} (\bar{y} - \bar{c}_1 - \bar{y}) (\bar{x} - \bar{c}_2 - \bar{x}) \right] 
= \left(\frac{N}{n}\right)^{-1} \left[ \sum_{s \in S_1} (\bar{y} - \bar{c}_1 - \bar{y}) (\bar{x} - \bar{x}) 
+ \sum_{s \in S_2} (\bar{y} - \bar{c}_1 - \bar{y}) (\bar{x} - \bar{x}) 
+ \sum_{s \in S_3} (\bar{y} - \bar{c}_1 - \bar{y}) (\bar{x} - \bar{x}) \right] 
- c_1 \left[ \sum_{s \in S_1} (\bar{x} - \bar{x}) - \sum_{s \in S_1} (\bar{x} - \bar{x}) \right] 
- c_2 \left[ \sum_{s \in S_2} (\bar{y} - \bar{y}) - \sum_{s \in S_1} (\bar{y} - \bar{y}) \right] 
+ c_1c_2 \left[ \sum_{s \in S_1} + \sum_{s \in S_2} \right].
\]

(17)

**Theorem 2.** If a sample of size \( n \) units is drawn from a population of size \( N \) units, then the covariance between \( \bar{y}_{c_{12}} \) and \( \bar{x}_{c_{22}} \), when they are negatively correlated, is given by

\[
\text{Cov}(\bar{y}_{c_{12}}, \bar{x}_{c_{22}}) = \lambda S_{yx} + \frac{n\lambda}{N-1} 
\times \left[ c_1 (x_{\text{max}} - x_{\text{min}}) + c_2 (y_{\text{max}} - y_{\text{min}}) 
- 2nc_1c_2 \right].
\]

(18)

The above **Theorem 2** can be proved similarly as Theorem 1.

We define the following relative error terms.

Let \( e_0 = (\bar{y}_{c_1} - \bar{y})/\bar{y} \) and \( e_1 = (\bar{x}_{c_1} - \bar{x})/\bar{x} \), such that

\[
E(e_0) = E(e_1) = 0,
\]

(19)

\[
E(e_0^2) = \frac{\lambda}{\bar{y}^2} \left[ S_y^2 - \frac{2nc_1}{N-1} \left( y_{\text{max}} - y_{\text{min}} - nc_1 \right) \right],
\]

(20)

\[
E(e_1^2) = \frac{\lambda}{\bar{x}^2} \left[ S_x^2 - \frac{2nc_2}{N-1} \left( x_{\text{max}} - x_{\text{min}} - nc_2 \right) \right],
\]

(21)

\[
E(e_0e_1) = \frac{\lambda}{\bar{y}\bar{x}} \left[ S_{yx} - \frac{n}{N-1} \right] 
\times \left[ c_2 (y_{\text{max}} - y_{\text{min}}) + c_1 (x_{\text{max}} - x_{\text{min}}) 
- 2nc_1c_2 \right].
\]

(22)
Expressing $\tilde{Y}_{RC}$ in terms of $e$'s, we have

$$\tilde{Y}_{RC} = Y (1 + e_0) (1 + e_1)^{-1}. \tag{23}$$

Expanding and rearranging right-hand side of (23), to first degree of approximation, we have

$$\left( \tilde{Y}_{RC} - Y \right) \approx Y (e_0 + e_1 - e_0 e_1 + e_1^2). \tag{24}$$

Using (24), the bias of $\tilde{Y}_{RC}$ is given by

$$M(\tilde{Y}_{RC}) \equiv M(Y_\rho) - \frac{\lambda}{2} \left( \frac{N-1}{n} \right) \lambda \left[ \frac{\lambda}{2} \right]. \tag{29}$$

Similarly the bias and mean square error or optimum mean square error of $\tilde{Y}_{PC}$ are, respectively, given by

$$M(\tilde{Y}_{PC})_\text{opt} \equiv M(Y_p) - \frac{2\lambda n}{N-1} \left[ \left( e_1 + R e_2 \right) \left( y_{\text{max}} - y_{\text{min}} \right) - R \left( x_{\text{max}} - x_{\text{min}} \right) \right]. \tag{31}$$

For optimum values of $c_1$ and $c_2$, the optimum mean square error of $\tilde{Y}_{PC}$ is given by

$$M(\tilde{Y}_{PC})_\text{opt} \equiv M(Y_p) - \frac{2\lambda n}{N-1} \left[ \left( e_1 + R e_2 \right) \left( y_{\text{max}} - y_{\text{min}} \right) - R \left( x_{\text{max}} - x_{\text{min}} \right) \right]. \tag{32}$$

The variance of regression estimator $\tilde{Y}_{t_RC}$ in case of positive correlation is given by

$$V(\tilde{Y}_{t_RC}) = V(Y_t) - \frac{2\lambda n}{N-1} \left[ \left( e_1 + R e_2 \right) \left( y_{\text{max}} - y_{\text{min}} \right) - R \left( x_{\text{max}} - x_{\text{min}} \right) \right]. \tag{33}$$

where $\beta = \rho_{yx}(S_{yx}/S_{xx})$ is the population regression coefficient of $y$ on $x$.

For $c_2 = (x_{\text{max}} - x_{\text{min}})/2n$ and $c_1 = (y_{\text{max}} - y_{\text{min}})/2n$, optimum variance of $\tilde{Y}_{t_RC}$ is given by

$$V(\tilde{Y}_{t_RC})_\text{opt} = V(Y_t) - \frac{\lambda}{2} \left( \frac{N-1}{n} \right) \lambda \left[ \frac{\lambda}{2} \right]. \tag{34}$$
For negative correlation, variance of the regression estimator \( \bar{y}_{\text{RC}} \) is given by

\[
V(\bar{y}_{\text{RC}}) = V(\bar{y}) - \frac{2\lambda n}{N-1} \\
\times \left[ (c_1 + \beta c_2) \left( \left( y_{\text{max}} - y_{\text{min}} \right) + \beta \left( x_{\text{max}} - x_{\text{min}} \right) \\
-2n \left( c_1 + \beta c_2 \right) \right) \right].
\] 

(35)

For \( c_2 = (x_{\text{max}} - x_{\text{min}})/2n \) and \( c_1 = (y_{\text{max}} - y_{\text{min}})/2n \), optimum variance of \( \bar{y}_{\text{RC}} \) is given by

\[
V(\bar{y}_{\text{RC}})^{\text{opt}} = V(\bar{y}) - \frac{\lambda}{2(N-1)} \\
\times \left[ \left( y_{\text{max}} - y_{\text{min}} \right) + \beta \left( x_{\text{max}} - x_{\text{min}} \right) \right]^2.
\] 

(36)

So in general we can write \( V(\bar{y}_{\text{RC}})^{\text{opt}} \) as

\[
V(\bar{y}_{\text{RC}})^{\text{opt}} = V(\bar{y}) - \frac{\lambda}{2(N-1)} \\
\times \left[ \left( y_{\text{max}} - y_{\text{min}} \right) - \beta \left( x_{\text{max}} - x_{\text{min}} \right) \right]^2.
\] 

(37)

3. Comparison

The conditions under which the suggested estimators \( \bar{y}_{\text{RC}}, \bar{y}_{\text{PC}}, \) and \( \bar{y}_{\text{RC}} \) perform better than the usual mean per unit estimator and their usual counterpart is given below.

(a) Comparison of Proposed Ratio Type Estimator. A proposed estimator \( \bar{y}_{\text{RC}} \) will perform better than

(i) mean per unit estimator (by (1) and (27)) if \( V(\bar{y}) - M(\bar{y}_{\text{RC}}) > 0 \) or if

\[
\rho_{yx} < \frac{R_{x} \sqrt{S_y}}{2S_y} + \frac{n}{R_{s} S_x(N-1)} \\
\times \left[ (c_1 + Rc_2) \left( y_{\text{max}} - y_{\text{min}} \right) - R \left( x_{\text{max}} - x_{\text{min}} \right) \\
-2n \left( c_1 + Rc_2 \right) \right];
\]

(38)

(ii) usual ratio estimator (by (8) and (27)) if \( M(\bar{y}_r) - M(\bar{y}_{\text{RC}}) > 0 \) or if

\[
\min \left[ Rc_2, Rc_2 - \left( \frac{R(x_{\text{max}} - x_{\text{min}}) - (y_{\text{max}} - y_{\text{min}})}{n} \right) \right] < c_1
\]

< \max \left[ Rc_2, Rc_2 - \left( \frac{R(x_{\text{max}} - x_{\text{min}}) - (y_{\text{max}} - y_{\text{min}})}{n} \right) \right].
\] 

(39)

(b) Comparison of Proposed Product Type Estimator. A proposed product type estimator will perform better than

(iii) mean per unit estimator if \( V(\bar{y}) - M(\bar{y}_{\text{PC}}) > 0 \) (by (1) and (31)) or if

\[
\rho_{yx} < -\frac{R_{x} \sqrt{S_y}}{2S_y} + \frac{n}{R_{s} S_x(N-1)} \\
\times \left[ (c_1 + Rc_2) \left( y_{\text{max}} - y_{\text{min}} \right) + R \left( x_{\text{max}} - x_{\text{min}} \right) \\
-2n \left( c_1 + Rc_2 \right) \right];
\]

(40)

(iv) usual product estimator if \( M(\bar{y}_p) - M(\bar{y}_{\text{PC}}) > 0 \) (by (9) and (31)) or if

\[
\min \left[ -Rc_2, -Rc_2 + \frac{R(x_{\text{max}} - x_{\text{min}}) + (y_{\text{max}} - y_{\text{min}})}{n} \right] < c_1
\]< \max \left[ -Rc_2, -Rc_2 + \frac{R(x_{\text{max}} - x_{\text{min}}) + (y_{\text{max}} - y_{\text{min}})}{n} \right].
\]

(41)

(c) Comparison of Proposed Regression Type Estimator. A proposed regression type estimator (positive correlation) will perform better than

(v) mean per unit estimator if \( V(\bar{y}) - V(\bar{y}_{\text{RC}}) > 0 \) (by (1) and (33)) or if

\[
\rho_{yx} > \frac{2n}{S_y^2 (N-1)} \\
\times \left[ (c_1 - \beta c_2) \left( y_{\text{max}} - y_{\text{min}} \right) - \beta \left( x_{\text{max}} - x_{\text{min}} \right) \\
-2n \left( c_1 - \beta c_2 \right) \right];
\]

(42)

(vi) usual regression estimator if \( V(\bar{y}_r) - V(\bar{y}_{\text{RC}}) > 0 \) (by (11) and (33)) or if

\[
\min \left[ \beta c_2, \beta c_2 - \left( \frac{\beta(x_{\text{max}} - x_{\text{min}}) - (y_{\text{max}} - y_{\text{min}})}{n} \right) \right] < c_1
\]< \max \left[ \beta c_2, \beta c_2 - \left( \frac{\beta(x_{\text{max}} - x_{\text{min}}) - (y_{\text{max}} - y_{\text{min}})}{n} \right) \right].
\]

(43)

A proposed regression type estimator (negative correlation) will perform better than

(vii) mean per unit estimator if \( V(\bar{y}) - V(\bar{y}_{\text{RC}}) > 0 \) (by (1) and (35)) or if

\[
\rho_{yx} > \frac{2n}{S_y^2 (N-1)} \\
\times \left[ (c_1 + \beta c_2) \left( y_{\text{max}} - y_{\text{min}} \right) + \beta \left( x_{\text{max}} - x_{\text{min}} \right) \\
-2n \left( c_1 - \beta c_2 \right) \right];
\]

(44)
We consider the following datasets for numerical comparison.

**Population 1** (Singh and Mangat [9, page 193]). Let \( y \) be the milk yield in kg after new food and let \( x \) be the yield in kg before new yield. \( N = 27, n = 12, \bar{X} = 10.41111, \bar{Y} = 11.25185, y_{\text{max}} = 14.8, y_{\text{min}} = 7.9, x_{\text{max}} = 14.5, x_{\text{min}} = 6.5, S^2_y = 4.103, S^2_x = 4.931, S_{xy} = 4.454, \) and \( \rho_{xy} = 0.990. \)

**Population 2** (Singh and Mangat [9, page 195]). Let \( y \) be the weekly time (hours) spent in nonacademic activities and let \( x \) be the overall grade point average (4.0 bases). \( N = 36, n = 12, \bar{X} = 2.798333, \bar{Y} = 14.77778, y_{\text{max}} = 33, y_{\text{min}} = 6, x_{\text{max}} = 3.82, x_{\text{min}} = 1.81, S^2_y = 38.178, S^2_x = 0.3504, S_{xy} = -2.477, \) and \( \rho_{xy} = -0.6772. \)

**Population 3** (Murthy [10, page 399]). Let \( y \) be the area under wheat crop in 1963 and \( x \) be the area under wheat crop in 1964. \( N = 34, n = 12, \bar{X} = 208.882, \bar{Y} = 199.441, y_{\text{max}} = 634, y_{\text{min}} = 6, x_{\text{max}} = 564, x_{\text{min}} = 5, S^2_y = 22564.56, S^2_x = 22652.05, S_{xy} = 22158.83, \) and \( \rho_{xy} = 0.980. \)

**Population 4** (Cochran [11, page 152]). Let \( y \) be population size in 1930 (in 1000) and \( x \) be the population size in 1920 (in 1000). \( N = 49, n = 12, \bar{X} = 103.1429, \bar{Y} = 127.7959, y_{\text{max}} = 634, y_{\text{min}} = 46, x_{\text{max}} = 507, x_{\text{min}} = 2, S^2_y = 15158.83, S^2_x = 10900.42, S_{xy} = 12619.78, \) and \( \rho_{xy} = 0.98. \)

The conditional values and results are given in Tables 1 and 2, respectively.

For percentage relative efficiency (PRE), we use the following expression:

\[
\text{PRE}(\bar{y}_i, \bar{y}) = \frac{V(\bar{y}_i)}{V(\bar{y})} \times 100 \quad \text{for} \quad i = R, P, RC, PC, l_r, l_rC.
\] (46)
of positive correlation. The product estimator $\widehat{Y}_{PC}$ is better than $\widehat{Y}_p$ just in Population 2 because of negative correlation. The regression estimator $\widehat{Y}_{PC}$ outperforms than all other considered estimators and is preferable.

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