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Provided by the author(s) and the Los Alamos National Laboratory (2018-06-18).

To be published in: Journal of Mathematical Physics

DOI to publisher’s version: 10.1063/1.4974018

Permalink to record: http://permalink.lanl.gov/object/view?what=info:lanl-repo/lareport/LA-UR-15-27441

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Complete integrability of Nonlocal Nonlinear Schrödinger equation

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Based on the completeness relation for the squared solutions of the Lax operator \( L \) we show that a subset of nonlocal equations from the hierarchy of nonlocal nonlinear Schrödinger equations (NLS) is a completely integrable system. The spectral properties of the Lax operator indicate that there are two types of soliton solutions. The relevant action-angle variables are parametrized by the scattering data of the Lax operator. The notion of the symplectic basis, which directly maps the variations of the potential of \( L \) to the variations of the action-angle variables has been generalized to the nonlocal case. We also show that the inverse scattering method can be viewed as a generalized Fourier transform. Using the trace identities and the symplectic basis we construct the hierarchy Hamiltonian structures for the nonlocal NLS equations.

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I. INTRODUCTION

Nonlocal, nonlinear equations arise in a variety of physical contexts ranging from hydrodynamics to optics to condensed matter and high energy physics. The integrability of such equations is an important issue not only for the physical properties and soliton solutions but also in its own right, see Refs. [1, 3–5, 16–18, 21] and the numerous references therein. We note that the nonlocal NLS and its associated symmetry reductions are contained in [3] and its inverse scattering transform is given in [4].

In this context, first we shall consider the generic AKNS system [2]
\[ L\psi = i\frac{d\psi}{dx} + U(x,t,\lambda)\psi(x,t,\lambda) = 0, \]
\[ U(x,t,\lambda) = q(x,t) - \lambda\sigma_3, \quad q(x,t) = \begin{pmatrix} 0 & q_+ \\ q_- & 0 \end{pmatrix}. \] (I.1)

The potential \( q(x,t) \) belongs to the class of smooth functions vanishing fast enough for \( x \to \pm \infty \). By generic here
The two operators $L$ and $M$ commute identically with respect to $\lambda$ provided $q_{\pm}(x, t)$ satisfy the nonlinear evolution equations (NLEE):

\[
\begin{align*}
\frac{i}{\hbar} \frac{\partial q_{\pm}}{\partial t} + \frac{1}{2} \frac{\partial^2 q_{\pm}}{\partial x^2} + q_{\pm}^2 q_{\mp}(x, t) &= 0, \\
-\frac{i}{\hbar} \frac{\partial q_{\mp}}{\partial t} - \frac{1}{2} \frac{\partial^2 q_{\mp}}{\partial x^2} + q_{\pm} q_{\mp}^2(x, t) &= 0.
\end{align*}
\]  

This system, which we will call a generalized nonlinear Schrödinger (NLS) equation system, can be simplified by applying one of the next reductions:

A): $q_{+}(x, t) = \epsilon_1 q_{-}^*(x, t)$, $\epsilon_1^2 = 1$

B): $q_{+}(x, t) = \epsilon_2 q_{-}(x, t)$, $\epsilon_2^3 = 1$

C): $q_{+}(x, t) = \epsilon_2 q_{-}^*(-x, t)$, $\epsilon_2^3 = 1$

The class A) NLEE contains the famous NLS equation

\[\hbar \frac{\partial u}{\partial t} + \frac{1}{2} \frac{\partial^2 u}{\partial x^2} + |u|^2 u(x, t) = 0,\]  

whose integrability was discovered by Zakharov and Shabat [24, 25]. The class B) reduction allowed AKNS to integrate the sine-Gordon and the mKdV equations [2, 6]. Here we just note that the $M$-operators for the sine-Gordon and mKdV equations have different $\lambda$-dependence.

The last reduction C) has been used recently to analyze the class containing the nonlocal NLS eq.

\[\hbar \frac{\partial u}{\partial t} + \frac{1}{2} \frac{\partial^2 u}{\partial x^2} + u^2(x, t)u^*(x, t) = 0,\]  

which recently became physically important [3, 4].

The paper is organized as follows. Section II contains some well known facts about the spectral theory of $L$ such as a) the construction of the fundamental analytic solutions (FAS); b) the mappings between the potential $q(x, t)$ (resp. the variation of the potential $\delta q(x, t)$) and the scattering data (resp. the variation of the scattering data) based on the Wronskian relations. In Section III we prove the completeness relation for the ‘squared solutions’ of $L$ and derive the expansions of $q(x, t)$ and $\sigma_3 \delta q(x, t)$ over them. We also introduce the recursion operators for which the ‘squared solutions’ are complete sets of eigenfunctions. In Section IV we use the results of Section III to derive the fundamental properties of the generic NLEE. These include description of the class of NLEE related to $L$ and their integrals of motion, trace identities and the action-angle variables for the generic NLEE related to $L$ (I.1). In the next Section V we construct the hierarchy of Hamiltonian structures. We demonstrate that the symplectic basis of squared solutions is a very convenient tool in this analysis. It allows one to prove effectively the compatibility of the hierarchy of Poisson brackets (subsection V.1) and the compatibility of the hierarchy of symplectic forms $\Omega_{(m)}$. The symplectic basis allows us to give a simple proof of the fact that all $\Omega_{(m)}$ acquire canonical form in terms of the action-angle variables. In Section VI we analyze the effects of the local (subsection VI.1) and non-local involutions (subsection VI.2) on the Hamiltonian hierarchies and on the action-angle variables. In both cases we derive the action-angle variables in terms of the scattering data of the corresponding reduced Lax operator. In the case of local involutions we reproduce the well known results [2, 8, 9, 12, 15]. In the case of non-local involutions the results are new and provide us with the action-angle variables for the nonlocal NLS. In the last Section VII we discuss the results and draw conclusions.

II. PRELIMINARIES

II.1. Direct and Inverse Scattering Problem for the Generic AKNS system

We start by briefly outlining the main results from the direct and inverse scattering problems for the generic AKNS system on the class of potentials $q(x, t)$ that are smooth functions vanishing fast enough for $x \to \pm \infty$. The basic tools in this theory are the Jost solutions, which are introduced by:

\[
\begin{align*}
\lim_{x \to -\infty} e^{-i\lambda \sigma_3 x} \phi(x, t, \lambda) &= 1, \\
\lim_{x \to \infty} e^{-i\lambda \sigma_3 x} \psi(x, t, \lambda) &= 1,
\end{align*}
\]  

and the scattering matrix

\[
T(\lambda, t) \equiv \psi(x, t, \lambda) \phi(x, t, \lambda) = \begin{pmatrix} a^+ & b^- \\ b^+ & a^- \end{pmatrix}.
\]  

Time dependence of $T(\lambda, t)$ is given by

\[\frac{\partial T}{\partial t} - \lambda^2 [\sigma_3, T(\lambda, t)] = 0.\]

The analyticity properties of the Jost solutions and the FAS of $L$ are given as follows:

\[
\begin{align*}
\psi(x, t, \lambda) &= |\psi^-, \psi^+|, \\
\phi(x, t, \lambda) &= |\phi^+, \phi^-|, \\
\chi^+(x, t, \lambda) &= |\phi^+, \psi^+|, \\
\chi^-(x, t, \lambda) &= |\psi^-, \phi^-|,
\end{align*}
\]

\[\det \chi^2(x, t, \lambda) = a^2(\lambda).\]
where the superscript \(+\) (resp. \(-\)) means that the corresponding column or function allows an analytic extension to \( \mathbb{C}_+ \) (resp. for \( \lambda \in \mathbb{C}_- \)).

In what follows we will also need the asymptotics of \( \chi^\pm(x,\lambda) \) for \( x \to \pm \infty \). From (II.2) and (II.4) we find

\[
\lim_{x \to -\infty} e^{i\lambda \sigma_3 x} \chi^+(x,\lambda) = S^+(\lambda), \quad \lim_{x \to -\infty} e^{i\lambda \sigma_3 x} \chi^-(x,\lambda) = S^-(\lambda),
\]

\[
\lim_{x \to \infty} e^{i\lambda \sigma_3 x} \chi^+(x,\lambda) = T^+(\lambda), \quad \lim_{x \to \infty} e^{i\lambda \sigma_3 x} \chi^-(x,\lambda) = T^-(\lambda),
\]

where

\[
S^+(x,\lambda) = \begin{pmatrix} b_- & 0 \\ 0 & a_+ \end{pmatrix}, \quad S^-(x,\lambda) = \begin{pmatrix} a_- & 0 \\ -b_+ & 1 \end{pmatrix},
\]

\[
T^+(x,\lambda) = \begin{pmatrix} 1 & -b_- \\ 0 & a_- \end{pmatrix}, \quad T^-(x,\lambda) = \begin{pmatrix} a_+ & 0 \\ b_+ & 1 \end{pmatrix}.
\]

We will also need the asymptotics of the FAS for \( \lambda \to \infty \):

\[
\lim_{\lambda \to \infty} \chi^\pm(x,\lambda)e^{i\lambda \sigma_3 x} = 1.
\]

As an immediate consequence of (II.7) and the last line of eq. (II.4) there follows:

\[
\lim_{\lambda \to \infty} a_\pm(\lambda) = 1.
\]

### II.2. The Wronskian relations

The analysis of the mapping \( \mathcal{F}: \mathcal{M} \to \mathcal{T} \) between the class of the allowed potentials \( \mathcal{M} \) and the scattering data of \( L \) starts with the so-called Wronskian relations. As we shall see, they would allow us to:

1. formulate the idea that the ISM is a generalized Fourier transform (GFT);
2. determine explicitly the proper generalizations of the usual exponents;
3. introduce the skew-scalar product on \( \mathcal{M} \) which endows it with a symplectic structure.

All these ideas will be worked out for the generic Zakharov-Shabat system (I.1). Along with it, we will need also

\[
i \frac{d\psi}{dx} - \psi(x,t,\lambda)U(x,t,\lambda) = 0,
\]

\[
i \frac{d\delta\psi}{dx} + \delta U(x,t,\lambda)\psi(x,t,\lambda) + U(x,t,\lambda)\delta\psi(x,t,\lambda) = 0,
\]

\[
i \frac{d\hat{\psi}}{dx} + \hat{U}(x,t,\lambda)\psi(x,t,\lambda)
\]

which one can associate with (I.1). By \( \hat{\psi} \) above we denote \( \psi^{-1} \); \( \delta \psi \) is the variation of the Jost solution which corresponds to a given variation \( \delta q(x,t) \) of the potential; by \( \dot{\psi} \) we denote the derivative with respect to the spectral parameter; for example \( \dot{U}(x,t,\lambda) = -\sigma_3 \).

### II.3. The mapping from \( q \) to \( \mathcal{T} \)

The first Wronskian identity reads:

\[
(\hat{\chi} \sigma_3 \chi(x,\lambda) - \sigma_3)\bigg|_{-\infty}^{\infty} = -i \int_{-\infty}^{\infty} dx \hat{\chi}[q(x),\sigma_3]\chi(x,\lambda),
\]

where \( \chi(x,\lambda) \) can be any fundamental solution of \( L \). For convenience we choose them to be the FAS introduced earlier.

Skipping the details we obtain the following relations between the reflection coefficients and the potential:

\[
E^\pm(\lambda) \equiv \frac{b_\pm}{a_\pm} = \frac{i}{(a_\pm(\lambda))^2} \left[ q(x), \Phi^\pm(x,\lambda) \right],
\]

\[
\tau^\pm(\lambda) \equiv \frac{b_\mp}{a_\pm} = \frac{i}{(a_\pm(\lambda))^2} \left[ q(x), \Psi^\pm(x,\lambda) \right],
\]

where \( E^\pm(x,\lambda) \) are the ‘squared solutions’

\[
E^\pm(x,\lambda) = \chi^+(x,\lambda)\sigma_+ \chi^+(x,\lambda).
\]

By \( \left[ X, Y \right] \) we denote the skew-scalar product.

\[
\left[ X, Y \right] \equiv \frac{1}{2} \int_{-\infty}^{\infty} dx \operatorname{tr} (X(x), [\sigma_3, Y(x)])
\]

\[
= -\left[ Y, X \right].
\]

The “squared” solutions \( \Phi^\pm(x,\lambda) \) and \( \Psi^\pm(x,\lambda) \) are defined by:

\[
\Phi^\pm(x,\lambda) = a_\pm(E^\pm(x,\lambda))^f
\]

\[
= \begin{pmatrix} 0 & \pm (\phi_\pm(x,\lambda))^2 \\ \mp (\phi_\pm(x,\lambda))^2 & 0 \end{pmatrix}
\]

\[
\Psi^\pm(x,\lambda) = a_\pm(E^\mp(x,\lambda))^f
\]

\[
= \begin{pmatrix} 0 & \pm (\psi_\pm(x,\lambda))^2 \\ \mp (\psi_\pm(x,\lambda))^2 & 0 \end{pmatrix}.
\]

Here and below by \( X^f \) we mean the off-diagonal part of the matrix \( X \).

These “squared” solutions effectively coincide with the ones that appeared originally in [2, 8, 9, 14, 15]; the difference is that here we have used the gauge covariant formulation proposed in [13], see also [12].
II.4. The mapping from $\delta q$ to $\delta T$

The second type of Wronskian relations, relates the variation of the potential $\delta q(x)$ to the corresponding variations of the scattering data. To this purpose we start with the identity:

$$
\delta \chi(x, \lambda) \bigg|_{-\infty}^{\infty} = i \int_{-\infty}^{\infty} dx \, \hat{\chi} \delta q(x) \chi(x, \lambda), \quad (II.18)
$$

which gives:

$$
\delta \rho^\pm(\lambda) = \frac{-i}{2(a^\pm(\lambda))^2} \left[ [\sigma_3, \delta q(x)], \Phi^\pm(x, \lambda) \right], \quad (II.19)
$$

$$
\delta \sigma^\pm(\lambda) = \frac{i}{2(a^\pm(\lambda))^2} \left[ [\sigma_3, \delta q(x)], \Psi^\pm(x, \lambda) \right], \quad (II.20)
$$

and

$$
\delta A(\lambda) = -\frac{\hat{\chi}}{4a^\pm(\lambda)} \left[ [\sigma_3, \delta q(x)], \Theta^\pm(x, \lambda) \right]. \quad (II.21)
$$

Here $\Psi^\pm(x, \lambda)$ and $\Phi^\pm(x, \lambda)$ are the same "squared" solutions as in (II.16), (II.17)

$$
\Theta^\pm(x, \lambda) = a^\pm(\lambda) \chi^\pm(x, \lambda) \sigma_3 \chi^\pm(x, \lambda),
$$

$$
= \begin{pmatrix}
0 & -2(\phi_1^+ \psi_1^-(x, \lambda)) \\
2(\phi_2^- \psi_2^-)(x, \lambda) & 0
\end{pmatrix}, \quad (II.22)
$$

and $A(\lambda) = \pm \ln a^\pm(\lambda)$ for $\lambda \in \mathbb{C}_\pm$.

These relations are basic in the analysis of the NLEE related to the Zakharov-Shabat system and their Hamiltonian structures. We shall use them later assuming that the variation of $q(x)$ is due to its time evolution. In this case $q(x, t)$ depends on $t$ in such a way, that it satisfies certain NLEE. Then we consider variations of the type:

$$
\delta q(x, t) = \frac{\partial q}{\partial t} \delta t + \mathcal{O}(\delta t^2). \quad (II.23)
$$

Keeping only the first order terms with respect to $\delta t$ we find:

$$
\rho^\pm_t(\lambda) = \frac{-i}{2(a^\pm(\lambda))^2} \left[ [\sigma_3, q_t(x)], \Phi^\pm(x, \lambda) \right], \quad (II.24)
$$

$$
\sigma^\pm_t(\lambda) = \frac{i}{2(a^\pm(\lambda))^2} \left[ [\sigma_3, q_t(x)], \Psi^\pm(x, \lambda) \right]. \quad (II.25)
$$

There is one more type of Wronskian relations, namely:

$$
\hat{\chi} \chi(x, \lambda) + i x \sigma_3 \bigg|_{-\infty}^{\infty} = -i \int_{-\infty}^{\infty} dx \left( \hat{\chi} \sigma_3 \chi(x, \lambda) - \sigma_3 \right). \quad (II.26)
$$

Treating it analogously to the above cases we obtain:

$$
\frac{\partial A}{\partial \lambda} = -i \int_{-\infty}^{\infty} dx \left( \frac{1}{2} \text{tr} \left( \chi^\pm \sigma_3 \chi^\pm(x, \lambda) \sigma_3 \right) - 1 \right), \quad (II.27)
$$

where

$$
A(\lambda) = \begin{cases}
\ln a^+(\lambda) & \lambda \in \mathbb{C}_+, \\
\frac{1}{2} \ln (a^+(\lambda)/a^-(\lambda)) & \lambda \in \mathbb{R}, \\
-\ln a^-(\lambda) & \lambda \in \mathbb{C}_-.
\end{cases} \quad (II.28)
$$

As we shall see below, this Wronskian relation is useful in analyzing the conservation laws of the NLEE.

III. GENERALIZED FOURIER TRANSFORMS

Following AKNS [2, 14] here we shall prove first that their ideas of interpreting the ISM as a GFT hold true for the generic Zakharov-Shabat system (I.1) in which $q_+$ and $q_-$ are unrelated complex-valued functions.

In what follows we assume that the potential $q(x, t)$ of the Lax operator satisfies the conditions:

**C1:** The potential $q(x, t)$ is a $2 \times 2$ off-diagonal matrix (see (I.1)) whose matrix elements are complex-valued Schwartz-type functions of $x$ and $t$;

**C2:** The potential $q(x, t)$ such that the corresponding transition coefficients $a^+(\lambda)$ and $a^-(\lambda)$ have finite number of zeroes in their regions of analyticity located at $\lambda_k^\pm \in \mathbb{C}_\pm$ and $\lambda_k^- \in \mathbb{C}_-$, $k = 1, \ldots, N$.

More specifically, from condition **C1** it follows [2] that the matrix elements $a^\pm(\lambda)$ and $b^\pm(\lambda, t)$ are Schwartz-type functions on the real axis of the complex $\lambda$-plane $\mathbb{C}$.

From condition **C2** it follows that $a^\pm(\lambda)$ in the vicinity of its zeroes behave like:

$$
a^+(\lambda) = (\lambda - \lambda_j^+) a^+_j + \frac{1}{2} (\lambda - \lambda_j^+)^2 a^+_j + \mathcal{O}((\lambda - \lambda_j^+)^3),
$$

$$
a^-(\lambda) = (\lambda - \lambda_j^-) a^-_j + \frac{1}{2} (\lambda - \lambda_j^-)^2 a^-_j + \mathcal{O}((\lambda - \lambda_j^-)^3),
$$

(III.1)

where $j = 1, \ldots, N_+$ for the first of the above equations and $j = 1, \ldots, N_-$ for the second.

**Remark 1.** The condition **C2** requires in addition that $N_+ < N_-$ which ensures that $\lim_{\lambda \to \infty} a^\pm(\lambda) = 1$ (see [12, 14]).

Effectively, condition **C2** means that the discrete spectrum of $L$ consists of a finite number of simple discrete eigenvalues. The FAS $\chi^\pm(x, \lambda)$ become degenerate at the points $\lambda_k^\pm$; more specifically

$$
\phi_k^\pm(x) = b_k^\pm \psi_k^\pm(x), \quad \phi_k^\pm(x) = -b_k^- \psi_k^-(-x), \quad (III.2)
$$

where $\phi_k^\pm(x) = \phi^\pm(x, \lambda_k^\pm)$, $\psi_k^\pm(x) = \psi^\pm(x, \lambda_k^\pm)$ and $b_k^\pm$ are some (time-dependent) constants.

**Remark 2.** In the special case, when the potential $q(x, t)$ is on a finite support one can prove that the Jost solutions, as well as the scattering matrix $T(\lambda, t)$ are meromorphic functions of $\lambda$. Then one can extend the functions $b^\pm(\lambda)$ in $\mathbb{C}_+$ (resp. $b^-\lambda$ in $\mathbb{C}_-$) with the result:

$$
b_k^\pm(\lambda) = b_k^\pm + \mathcal{O}\left( (\lambda - \lambda_k^\pm) \right), \quad (III.3)
$$

i.e., the constants $b_k^\pm = b^\pm(\lambda_k^\pm)$ can be understood as the values of $b^\pm(\lambda)$ at the points $\lambda_k^\pm$. 
II.1. Completeness of the “squared” solutions

In this Subsection we prove that the ‘squared solutions’ satisfy a completeness relation, thus generalizing the results of [8, 9, 14].

**Theorem 1.** Let the potential $q(x)$ of $L$ satisfy the conditions C1 and C2. Then the squared solutions $\Psi^\pm(x, \lambda)$ and $\Phi^\pm(x, \lambda)$ satisfy the following completeness relation

$$\delta(x-y)\Pi_0 = \frac{1}{\pi} \int_{-\infty}^{\infty} d\lambda \left( Z^+(x,y,\lambda) - Z^-(x,y,\lambda) \right)$$

$$+ 2i \sum_{k=1}^{N_+} X^+_k(x,y) + 2i \sum_{k=1}^{N_-} X^-_k(x,y), \quad (III.4)$$

where

$$\Pi_0 = \sigma_+ \otimes \sigma_- - \sigma_- \otimes \sigma_+, \quad Z^\pm(x,y,\lambda) = \frac{\Psi^\pm(x,\lambda) \otimes \Phi^\pm(y,\lambda)}{(a^\pm(\lambda))^2}, \quad (III.5)$$

and $X^\pm_k(x,y)$ are defined by:

$$X^+_k(x,y) = \frac{1}{(a^+_k)^2} \left( \Psi^+_k(x) \otimes \Phi^+_k(y) \right.$$

$$+ \Psi^+_k(x) \otimes \Phi^+_k(y) - \frac{a^+_k}{a^+_k} \Psi^+_k(x) \otimes \Phi^+_k(y) \left. \right) \quad (III.6)$$

*The idea of the proof.* Following [8, 9, 12] we consider the piece-wise analytic function:

$$G(x,y,\lambda) = \left\{ \begin{array}{ll} G^+(x,y,\lambda), & \text{for } \lambda \in \mathbb{C}_+, \\ G^-(x,y,\lambda), & \text{for } \lambda \in \mathbb{C}_- \end{array} \right. \quad (III.7)$$

and $G(x,y,\lambda) = 1/2(G^+(x,y,\lambda) + G^-(x,y,\lambda))$ for $\lambda \in \mathbb{R}$, where

$$G^\pm(x,y,\lambda) = Z^\pm(x,y,\lambda)\theta(x-y) - G^\pm_0(x,y,\lambda)\theta(y-x),$$

$$G^\pm_0(x,y,\lambda) = \frac{1}{(a^\pm(\lambda))^2} \left( \Phi^\pm(x,\lambda) \otimes \Psi^\pm(y,\lambda) \right.$$\n
$$+ \frac{1}{2} \Theta^\pm(x,\lambda) \otimes \Theta^\pm(y,\lambda) \right), \quad (III.8)$$

Next we consider the integral

$$\mathcal{J}_G(x,y) = \frac{1}{2\pi i} \left( \int_{C^+} d\lambda \ G^+(x,y,\lambda) - \int_{C^-} d\lambda \ G^-(x,y,\lambda) \right)$$

$$= \sum_{k=1}^{N} \left( \text{Res}_{\lambda = \lambda_k^+} \ G^+(x,y,\lambda) + \text{Res}_{\lambda = \lambda_k^-} \ G^-(x,y,\lambda) \right), \quad (III.9)$$

where the contours $C^\pm = \mathbb{R} \cup \gamma^\pm,\infty$ are shown in Figure 1.

The integration along the contours gives rise to two terms: i) the integral along the real axis in eq. (III.4) which is the contribution from the continuous spectrum of $L$ to the completeness relation (CR); ii) the integrals along the infinite semicircles can be evaluated explicitly giving rise to the term $\delta(x-y)\Pi_0$ in eq. (III.4). Evaluating the integral $\mathcal{J}_G(x,y)$ by Cauchy residue theorem gives rise to the contribution from the discrete spectrum of $L$ to the CR. Indeed, the poles of $G^\pm$ coincide with $\lambda_k^\pm$. Since $a^\pm(\lambda)$ have first order zeroes at $\lambda_k^\pm$, then $G^\pm$ would have second order poles at these points.

III.2. The symplectic basis

In this Subsection we derive an alternative form of the completeness relation (III.4) and introduce the so-called symplectic basis of ‘squared solutions’, see [8, 9, 12]. To this end, we apply to both sides of (III.4) the operator $1 - p$, where $p$ acts on any tensor product $X \otimes Y$ as follows: $p(X \otimes Y) = Y \otimes X$. It is easy to check that $(1 - p)\Pi_0 = 2\Pi_0$.

The same operation applied to the right hand side of (III.4) can be simplified and cast into the form

$$\delta(x-y)\Pi_0 = \int_{-\infty}^{\infty} d\lambda \ (\mathcal{P}(x,\lambda) \otimes \mathcal{Q}(y,\lambda) - \mathcal{Q}(x,\lambda) \otimes \mathcal{P}(y,\lambda))$$

$$+ \sum_{k=1}^{N} \left( Z^+_k(x,y) + Z^-_k(x,y) \right),$$

$$Z^+_k(x,y) = \left( \mathcal{P}^+_k(x) \otimes \mathcal{Q}^+_k(y) - \mathcal{Q}^+_k(x) \otimes \mathcal{P}^+_k(y) \right), \quad (III.10)$$

where we have introduced the so-called symplectic basis, which will be extensively used in the analysis of the Hamiltonian structures of the NLEE. The elements of this basis are linear combinations of the “squared” solu-
The expansion of $X^1$ produced in eqs. (II.13) and (II.14) is:

$$\mathcal{P}^\pm_k(x) = 2iC^\pm_k \Psi^\pm_k(x),$$

where

$$\mathcal{Q}(x, \lambda) = \frac{\tau^+(\lambda)\Phi^+(x, \lambda) + \rho^+(\lambda)\Psi^+(x, \lambda)}{2b^+(\lambda)b^-(\lambda)} - \frac{\rho^-(\lambda)\Psi^-(x, \lambda) + \tau^-(\lambda)\Phi^-(x, \lambda)}{2b^+(\lambda)b^-(\lambda)},$$

$$\mathcal{Q}_k^\pm(x) = \frac{1}{2} \left( C^\pm_k \Psi^\pm_k(x) + M^\pm_k \Phi^\pm_k(x) \right),$$

where we must recall that $\rho^+(\lambda)$ and $\tau^+(\lambda)$ were introduced in eqs. (III.13) and (III.14).

### III.3. Expansions over the ‘squared’ solutions

Using the completeness relations one can expand any generic element $X(x)$ of the phase space $\mathcal{M}$ over each of the three complete sets of ‘squared solutions’. In this section we explain how this can be done. We remind that

$$X(x) = X_+(x) \sigma_+ + X_-(x) \sigma_-,$$

(III.14)

From (III.5) we get:

$$\frac{1}{2} \text{tr}_2 (\Pi_0[\sigma_3, X(x)] \otimes 1) = -\frac{1}{2} \text{tr}_1 \left( (1 \otimes [\sigma_3, X(x)]) \Pi_0 = X(x) \right),$$

(III.15)

where $\text{tr}_1$ (and $\text{tr}_2$) mean that we are taking the trace of the elements in the first (or the second) position of the tensor product.

Now, we multiply (III.4) on the right by $\frac{1}{2} [\sigma_3, X(x)] \otimes 1$, take $\text{tr}_1$ and integrate over $dx$. This leads to the expansion of $X(x)$ over the system $\Phi^\pm$:

$$X(x) = \frac{1}{\pi} \int_{-\infty}^{\infty} d\lambda \left( \psi^+_X(\lambda)\Phi^+_X(x, \lambda) - \psi^-_X(\lambda)\Phi^-(x, \lambda) \right)$$

$$+ 2i \sum_{k=1}^{N} \left( \psi^+_X, k \Phi^+_k + \psi^-_X, k \Phi^-_k \right),$$

(III.16)

where

$$\psi^+_X(\lambda) = \frac{[\Psi^+_X(x, \lambda), X(x)]}{(a^+(\lambda))^2},$$

$$\psi^-_X(\lambda) = \frac{[\Psi^-_X(x, \lambda), X(x)]}{(a^-\lambda))^2},$$

$$\psi^+_X, k = \frac{1}{(a^+_k)^2} \left( \Phi^+_k(x) - \frac{\bar{a}^+_k}{a^+_k} \Phi^+_k(x), X(x) \right).$$

Analogously, we can multiply (III.4) on the left by $\frac{1}{2} [\sigma_3, X(x)]$, take $\text{tr}_2$ and integrate over $dx$. This leads to the expansion of $X(x)$ over the system $\Phi^\pm$:

$$X(x) = -\frac{1}{\pi} \int_{-\infty}^{\infty} d\lambda \left( \phi^+_X(\lambda)\Psi^+_X(x, \lambda) - \phi^-_X(\lambda)\Psi^-(x, \lambda) \right)$$

$$- 2i \sum_{k=1}^{N} \left( \phi^+_X, k \Psi^+_k + \phi^-_X, k \Psi^-_k \right),$$

(III.17)

$$\phi^+_X(\lambda) = \frac{[\Phi^+_X(x, \lambda), X(x)]}{(a^+\lambda))^2},$$

$$\phi^-_X(\lambda) = \frac{[\Phi^-_X(x, \lambda), X(x)]}{(a^-\lambda))^2},$$

$$\phi^+_X, k = \frac{1}{(a^+_k)^2} \left( \Phi^+_k(x) - \frac{\bar{a}^+_k}{a^+_k} \Phi^+_k(x), X(x) \right).$$

The same procedure, applied to the completeness relation (III.10) for the symplectic basis leads to:

$$X(x) = \int_{-\infty}^{\infty} d\lambda \left( \kappa_X(\lambda)\mathcal{P}(x, \lambda) - \eta_X(\lambda)\mathcal{Q}(x, \lambda) \right)$$

$$+ \sum_{k=1}^{N} \left( \kappa^+_X, k \mathcal{P}^+_k(x, \lambda) - \eta^+_X, k \mathcal{Q}^+_k(x, \lambda) \right),$$

(III.19)

$$\kappa_X(\lambda) = [\mathcal{Q}(x, \lambda), X(x)],$$

$$\kappa^+_X, k = [\mathcal{P}^+_k(x, \lambda), X(x)],$$

$$\eta_X(\lambda) = [\mathcal{P}(x, \lambda), X(x)],$$

$$\eta^+_X, k = [\mathcal{Q}^+_k(x, \lambda), X(x)].$$

(III.20)

where $\sum_{k=1}^{N} W^\pm = \sum_{k=1}^{N} (W^+ + W^-)$.

The completeness relations derived above allow us to establish a one-to-one correspondence between the element $X(x) \in \mathcal{M}$ and its expansion coefficients. Indeed, from (III.4) and (III.10) we derived the expansions (III.16), (III.17) and (III.21) with the inversion formulae (III.17), (III.19) and (III.21) respectively. Using them we prove the following:

**Proposition 1.** The function $X(x) \equiv 0$ if and only if one of the following sets of relations holds:

$$\psi^+_X(\lambda) = \psi^-_X(\lambda) \equiv 0, \quad \psi^+_X, k = \psi^-_X, k \equiv 0,$$

(III.22)

$$\phi^+_X(\lambda) = \phi^-_X(\lambda) \equiv 0, \quad \phi^+_X, k = \phi^-_X, k \equiv 0,$$

(III.23)

$$\kappa_X(\lambda) = \eta_X(\lambda) \equiv 0, \quad \kappa^+_X, k = \eta^+_X, k \equiv 0,$$

(III.24)

where $\lambda \in \mathbb{R}$ and $k = 1, \ldots, N$. 


Let us show that from \( X(x) \equiv 0 \) there follows (III.22). To this end we insert \( X(x) \equiv 0 \) into the right hand sides of the inversion formulae (III.17) and immediately get (III.22). The fact that from (III.22) there follows \( X(x) \equiv 0 \) is readily obtained by inserting (III.22) into the right hand side of (III.16).

The equivalence of \( X(x) \equiv 0 \) to (III.23) and (III.24) is proved analogously using the inversion formulae (III.17), (III.19) and the expansions (III.18) and (III.20). The proposition is proved.

We shall see, that only half of the elements in the symplectic basis contribute to the r.h.side of (III.10). As the reader may have guessed already, their evaluation will be based on the Wronskian relations (II.19), (II.20) which we derived above. From them we have:

\[
\psi_q^\pm (\lambda) = \frac{1}{(a^\pm(\lambda))^2} \left[ \Psi^\pm(x, \lambda), q(x) \right] = i \tau^\pm(\lambda),
\]

\[
\psi_{q,k}^\pm = \frac{1}{(a_k^\pm)^2} \left[ \Psi^\pm_k(x), q(x) \right] = 0,
\]

\[
\psi_{q,k}^{\pm,1} = \frac{1}{(a_k^\pm)^2} \left[ \Psi^\pm_k(x) - \frac{\delta \pm}{\delta x} \Psi^\pm_k(x), q(x) \right] = i M_k^\pm.
\]

Similarly, we evaluate all skew-scalar products between the ‘squared solutions’ and \( q(x, t) \), \( \sigma_3 \delta q(x) \) and \( \sigma_3 \frac{\partial q}{\partial t} \), see the Tables I, II. This means that we know the expansion coefficients of \( q(x, t) \), \( \sigma_3 \delta q(x) \) and \( \sigma_3 \frac{\partial q}{\partial t} \) over each of the complete sets of ‘squared solutions’.

As a result we get the following expansions:

\[
q(x) = \frac{i}{\pi} \int_{-\infty}^{\infty} d\lambda \left( \tau^+(\lambda) \Psi^+(x, \lambda) - \tau^-(\lambda) \Psi^-(x, \lambda) \right) + 2 \sum_{k=1}^{N} \left( M_k^+ \Phi_k^+(x) + M_k^- \Phi_k^-(x) \right),
\]

\[
q(x) = -\frac{i}{\pi} \int_{-\infty}^{\infty} d\lambda \left( \rho^+(\lambda) \Psi^+(x, \lambda) - \rho^-(\lambda) \Psi^-(x, \lambda) \right) - 2 \sum_{k=1}^{N} \left( C_k^+ \Psi_k^+(x) + C_k^- \Psi_k^-(x) \right),
\]

\[
q(x) = i \int_{-\infty}^{\infty} d\lambda \left( \rho^+(\lambda) \Psi^+(x, \lambda) - \rho^-(\lambda) \Psi^-(x, \lambda) \right) + i \sum_{k=1}^{N} \left( P_k^+ + P_k^- \right).
\]

The expansions over the ‘squared’ solutions of the time derivative \( \sigma_3 \delta q \) are obtained by considering a special type of variation \( \delta q(x, t) \), namely:

\[
\sigma_3 \delta q(x, t) = \sigma_3 q \delta t + O((\delta t)^2).
\]

Keeping only the terms of order \( \delta t \), from (III.29), (III.30) and (III.31) we find:

\[
\sigma_3 \delta q(x, t) = \frac{i}{\pi} \int_{-\infty}^{\infty} d\lambda \left( \rho^+_t(t, \lambda) \Psi^+(x, t, \lambda) + \rho^-_t(t, \lambda) \Psi^-(x, t, \lambda) \right) + 2 \sum_{k=1}^{N} \left( C_k^+_t(t) \Phi_k^+(x, t) + C_k^-_t \Phi_k^-(x, t) \right),
\]

\[
\sigma_3 \frac{\partial q}{\partial t} = \frac{i}{\pi} \int_{-\infty}^{\infty} d\lambda \left( \tau^+_t(t, \lambda) \Phi^+(x, t, \lambda) + \tau^-_t(t, \lambda) \Phi^-(x, t, \lambda) \right) + 2 \sum_{k=1}^{N} \left( M_k^+_t(t) \Phi_k^+(x, t) + M_k^-_t \Phi_k^-(x, t) \right),
\]

\[
\sigma_3 \frac{\partial q}{\partial t} = i \int_{-\infty}^{\infty} d\lambda \left( \eta_1(t, \lambda) \Phi^+(x, t, \lambda) - \kappa_1(t, \lambda) \Phi^-(x, t, \lambda) \right) + i \sum_{k=1}^{N} \left( \eta_k^+(t, \lambda) \Phi_k^+(x, t) - \kappa_k^+ \Phi_k^+(x, t) \right).
\]
TABLE I. The expansion coefficients of $q(x,t)$, $\sigma_3 \delta q(x)$ and $\sigma_3 \frac{\partial q(x)}{\partial t}$ over the sets of squared solutions $\Psi(x,t,\lambda)$ and $\Phi(x,t,\lambda)$.

| $X(x,t)$ | $\eta_X(\lambda)$ | $\kappa_X(\lambda)$ |
|----------|------------------|------------------|
| $q(x,t)$ | 0                | 0                |
| $\sigma_3 \delta q(x)$ | $i \delta \eta(\lambda)$ | $-i \delta \kappa(\lambda)$ |
| $\sigma_3 \frac{\partial q(x)}{\partial t}$ | $\frac{\partial \eta(\lambda)}{\partial t}$ | $-\frac{\partial \kappa(\lambda)}{\partial t}$ |

TABLE II. The expansion coefficients of $q(x,t)$, $\sigma_3 \delta q(x)$ and $\sigma_3 \frac{\partial q(x)}{\partial t}$ over the symplectic basis.

III.4. The recursion operators

The recursion operators $\Lambda_{\pm}$ were introduced by AKNS [2] as the operators that resolve the recursion relations that follow the compatibility condition $[L, M] = 0$ of the Lax operators. Here we will use an alternative definition which is equivalent. Namely, we will introduce $\Lambda_{\pm}$ as the operators for which the ‘squared solutions’ $\Psi^{\pm}(x,\lambda)$ and $\Phi^{\pm}(x,\lambda)$ are eigenfunctions.

We start their derivation by noting that the ‘full’ squared solutions (see eq. (II.14)), $\Psi^{\pm}(x,\lambda) = a^{\pm}(\lambda) \chi^{\pm} \sigma_a \chi^{\pm}(x,\lambda)$, where $a$ - the index of the Pauli matrices - takes values $\pm$ and 3, satisfy the equation:

$$i \frac{\partial \Psi^{\pm}}{\partial x} + [q(x,t) - \lambda \sigma_3, \Psi^{\pm}(x,\lambda)] = 0.$$ (III.37)

In view of the explicit form of the Wronskian relations we have to split the ‘squared solutions’ into diagonal and off-diagonal parts $\Psi^{d}_{a}(x,\lambda) = \Psi^{d,\pm}_{a}(x,\lambda) + \Psi^{d,\pm}_{a}(x,\lambda)$:

$$\Psi^{d,\pm}_{a}(x,\lambda) = e^{d,\pm}_{a}(x,\lambda) \sigma_3 + \Phi^{d,\pm}(x,\lambda),$$

$$\Psi^{\pm}_{a}(x,\lambda) = e^{\pm}_{a}(x,\lambda) \sigma_3 + \Phi^{\pm}(x,\lambda),$$

where $e^{d,\pm}_{a}(x,\lambda) = \frac{1}{2} \sigma_a \chi^{\pm}(x,\lambda)$. Inserting these splittings into eq. (III.37) we find:

$$i \frac{\partial \Psi^{d,\pm}_{a}}{\partial x} + [q(x), \Psi^{d,\pm}_{a}(x,\lambda)] = 0,$$

$$i \frac{\partial \Psi^{\pm}_{a}}{\partial x} + [q(x), \Psi^{\pm}_{a}(x,\lambda)] = \lambda [\sigma_3, \Psi^{\pm}_{a}(x,\lambda)].$$ (III.39)

Note that the first of the above equations does not involve $\lambda$ explicitly, so we can integrate it directly with the result:

$$\Psi^{d,\pm}_{a}(x,\lambda) = i \sigma_3 \int_{x}^{x} dy \ tr (\sigma_3 q(y), \Psi^{d,\pm}_{a}(y,\lambda))$$

where $\varepsilon = \pm$. The second of the equations (III.39) can be converted into an eigenvalue-type problem by acting on both sides by $\frac{1}{2} \sigma_3 [\sigma_3, Z]$. Indeed, noting, that $\frac{1}{2} [\sigma_3, Z] = Z$ for any off-diagonal matrix $Z$ we find:

$$\frac{i}{4} \left[ \sigma_3, \frac{\partial \Psi^{\pm}_{a}}{\partial x} \right] - q(x) e^{\pm}_{a} = \lambda Z e^{\pm}_{a}.$$ (III.40)

It remains to insert eq. (III.40) into (III.41) to obtain

$$\Lambda_{\pm} X = \frac{i}{4} \left[ \sigma_3, \frac{\partial X}{\partial x} \right] - q(x) e^{\pm}_{a} \int_{x}^{f} tr (\sigma_3 q(y) X(y)).$$ (III.43)

Obviously, in the cases when the limits in the right hand side of eq. (III.42) vanish, we obtain an eigenvalue equation for the recursion operator. Skipping the details we formulate the results:

$$(\Lambda_{\pm} - \lambda) \Psi^{\pm}_{a}(x,\lambda) = 0, \quad (\Lambda_{\pm} - \lambda) \Phi^{\pm}_{a}(x,\lambda) = 0,$$

$$(\Lambda_{\pm} - \lambda^k_{\pm}) \Phi^{\pm}_{k}(x) = 0, \quad (\Lambda_{\pm} - \lambda^k_{\pm}) \Psi^{\pm}_{k}(x) = 0,$$

where $\lambda^k_{\pm}$ is evaluated at the corresponding point $\lambda^k_{\pm}$.

Note that the elements of the symplectic basis are eigenfunctions of $\Lambda = \frac{i}{4} (\Lambda_{+} + \Lambda_{-})$, namely:

$$(\Lambda - \lambda) P(x,\lambda) = 0, \quad (\Lambda - \lambda) Q(x,\lambda) = 0,$$

$$(\Lambda - \lambda^k_{\pm}) P^k(x) = 0, \quad (\Lambda - \lambda^k_{\pm}) Q^k(x) = 0.$$ (III.46)

We will also need the ‘conjugation’ properties of the recursion operators with respect to the skew-scalar product:

$$[X, \Lambda_{\pm} Y] = [\Lambda_{\pm} X, Y], \quad [X, \Lambda Y] = [\Lambda X, Y],$$

which are easily verified with integration by parts.
A generic potential \( q(x, t) \in \mathcal{M}_C \) is determined by two complex-valued functions \( q_+(x, t) \) and \( q_-(x, t) \). Solving the direct scattering problem for \( L \) we find that \( q(x, t) \) uniquely determines the scattering matrix \( T(\lambda, t) \) which has four matrix elements \( a^\pm(\lambda) \) and \( b^\pm(\lambda, t) \) related by the condition:

\[
\det T(\lambda, t) \equiv a^+ a^- (\lambda) + b^+ b^- (\lambda, t) = 1. \tag{III.48}
\]

Next we have to take into account the analyticity properties of \( a^\pm(\lambda) \). We do this by considering the integral

\[
\mathcal{J}_a(\lambda) = \frac{1}{2\pi i} \left( \int_{\gamma_+} \frac{d\mu}{\mu - \lambda} \ln \hat{a}^+(\mu) - \int_{\gamma_-} \frac{d\mu}{\mu - \lambda} \ln \hat{a}^-(\mu) \right),
\]

where

\[
\hat{a}^+(\lambda) = a^+(\lambda) \prod_{k=1}^N \frac{\lambda - \lambda_k^-}{\lambda - \lambda_k^+},
\]

\[
\hat{a}^-(\lambda) = a^-(\lambda) \prod_{k=1}^N \frac{\lambda - \lambda_k^+}{\lambda - \lambda_k^-},
\]

and the contours \( \gamma_\pm \) are shown in Figure 1. Note that condition \( C_2 \) ensures that \( \hat{a}^+(\lambda) \) (resp. \( \hat{a}^-(\lambda) \)) is an analytic function for \( \lambda \in \mathbb{C}_+ \) (resp. for \( \lambda \in \mathbb{C}_- \)) that has no zeroes in \( \mathbb{C}_+ \) (resp. in \( \mathbb{C}_- \)). Therefore, the function \( \ln \hat{a}^+(\lambda) \) (resp. \( \ln \hat{a}^-(\lambda) \)) is analytic for \( \lambda \in \mathbb{C}_+ \) (resp. for \( \lambda \in \mathbb{C}_- \)). Let us now assume that \( \lambda \in \mathbb{C}_+ \) and apply the Cauchy residue theorem. Thus we get:

\[
\mathcal{J}_a(\lambda) = \ln \hat{a}^-(\lambda). \tag{III.51}
\]

Evaluating \( \mathcal{J}_a(\lambda) \) by integrating along the contours splits into two terms. The first consists of integrating along the real axis \( \lambda \in \mathbb{R} \). The second term contains the integrals along the infinite semicircles \( \gamma_\pm \). However the second term vanishes because both \( a^\pm(\lambda) \) and \( \hat{a}^\pm(\lambda) \) tend to 1 for \( \lambda \rightarrow \infty \), see eq. (II.8). Equating both results for \( \mathcal{J}_a \) we obtain:

\[
\ln a^+(\lambda) = \frac{1}{2\pi i} \int_{-\infty}^{\infty} \frac{d\mu}{\mu - \lambda} \ln (a^+(\mu) a^-(\mu)) + \sum_{k=1}^N \ln \frac{\lambda - \lambda_k^+}{\lambda - \lambda_k^-}. \tag{III.52}
\]

Similarly we can consider \( \lambda \in \mathbb{R} \) and \( \lambda \in \mathbb{C}_- \). Then by Cauchy theorem we find that \( \mathcal{J}_a(\lambda) = \mathcal{A}(\lambda) \), where \( \mathcal{A}(\lambda) \) is introduced in eq. (II.28). Taking into account that from \( \det T(\lambda, t) = 1 \) there follows \( 1/(a^+ a^- (\lambda)) = 1 + \rho^+ \rho^- (\lambda, t); \) and we obtain:

\[
\mathcal{A}(\lambda) = -\frac{1}{2\pi i} \int_{-\infty}^{\infty} \frac{d\mu}{\mu - \lambda} \ln (1 + \rho^+(\lambda) \rho^- (\lambda))
+ \sum_{k=1}^N \ln \frac{\lambda - \lambda_k^+}{\lambda - \lambda_k^-}. \tag{III.53}
\]

Now we are ready to construct the minimal sets of scattering data for \( L \) which determine uniquely both the potential \( q(x, t) \) and the scattering matrix.

**Lemma 1.** Let the potential \( q(x, t) \in \mathcal{M}_C \) and is such that the conditions \( C_1 \) and \( C_2 \) are satisfied and the corresponding scattering matrix \( T(\lambda, t) \) is defined by eqs. (II.1) and (II.2). Then each of the sets

\[
\mathcal{T}_0 = \{ \eta(\lambda), \eta(\lambda), \lambda \in \mathbb{R}, \eta_k^\pm, \kappa_k^\pm(t) \},
\]

\[
\mathcal{T}_1 = \{ \rho^+(\lambda), \rho^-(\lambda), \lambda \in \mathbb{R}, \lambda_k^\pm, C_k^\pm(t) \},
\]

\[
\mathcal{T}_2 = \{ \tau^+(\lambda), \tau^-(\lambda), \lambda \in \mathbb{R}, \lambda_k^\pm, M_k^\pm(t) \},
\]

\[
\mathcal{T}_3 = \{ \kappa(\lambda), \kappa(\lambda), \lambda \in \mathbb{R}, \kappa_k^\pm, \kappa_k^\pm(t) \},
\]

\[
\mathcal{T}_4 = \{ \rho^+(\lambda), \rho^-(\lambda), \lambda \in \mathbb{R}, \kappa_k^\pm, \kappa_k^\pm(t) \},
\]

\[
\mathcal{T}_5 = \{ \rho^+(\lambda), \rho^-(\lambda), \lambda \in \mathbb{R}, \kappa_k^\pm, \kappa_k^\pm(t) \}
\]

determines uniquely both the potential and the scattering matrix \( T(\lambda, t) \) of \( L \).

**Proof.** 1. First we prove that from each \( \mathcal{T}_k \) one can recover the scattering matrix \( T(\lambda, t) \). Indeed, \( \mathcal{T}_1 \) determines uniquely the right hand side of eq. (III.53), i.e. one can recover both \( a^+(\lambda) \) and \( a^- (\lambda) \) as piecewise analytic functions of \( \lambda \). Then we can easily find \( b^+(\lambda) \) and \( b^- (\lambda) \) since \( b^+(\lambda, t) = \rho^+(\lambda, t) a^+(\lambda) \). Similar arguments work out for \( \mathcal{T}_2 \) and \( \mathcal{T}_0 \). For \( \mathcal{T}_2 \) it is enough to check that \( \rho^+ \rho^- (\lambda, t) = \tau^+ \tau^- (\lambda, t) \) and that \( b^+(\lambda, t) = \tau^+(\lambda) a^-(\lambda) \). For \( \mathcal{T}_0 \) we need the relations:

\[
\tau^+(\lambda) = e^{\pm \kappa(\lambda)} \sqrt{1 - e^{-\pi \eta(\lambda)}} \tag{III.55}
\]

2. The fact that each of the sets \( \mathcal{T}_k \) (III.54) determines uniquely the potential \( q(x, t) \) is an immediate consequence of the expansions (III.26)–(III.27) and Proposition 1. Indeed, the elements of \( \mathcal{T}_1 \) and \( \mathcal{T}_2 \) are in fact the expansion coefficients of \( q(x, t) \).

\[
\square
\]

**IV. THE FUNDAMENTAL PROPERTIES OF THE GENERIC NLEE**

In the next Section we shall see how this set of variables is related to the action–angle variables of the corresponding NLEE.

The expansion (III.31) allows us to introduce one more minimal set of scattering data:

\[
\mathcal{T} \equiv \{ \eta(\lambda), \kappa(\lambda), \lambda \in \mathbb{R}, \eta_k^\pm, \kappa_k^\pm \}, \tag{IV.1}
\]
Then the NLEEs:

For C1 equations for the scattering data:

are pairwise equivalent to the following linear evolution

Theorem 2. The potential q(x, t) satisfy conditions C1 and C2 and let the function f(λ) be meromorphic for λ ∈ C and has no singularities on the spectrum of L. Then the NLEEs:

\[ i\sigma_3 q_\pm + 2f(\Lambda)q(x, t) = 0, \]  
\[ i\sigma_3 q_\pm + 2f(\Lambda_+)q(x, t) = 0, \]  
\[ i\sigma_3 q_\pm + 2f(\Lambda_-)q(x, t) = 0, \]

are pairwise equivalent to the following linear evolution equations for the scattering data:

\[ \frac{\partial \eta}{\partial t} = 0, \quad i\frac{\partial \kappa}{\partial t} = 2f(\lambda), \]  
\[ \frac{\partial \eta^\pm}{\partial t} = 0, \quad i\frac{\partial \kappa^\pm}{\partial t} = 2f_k^\pm, \]  
\[ i\frac{\partial \rho^\pm}{\partial t} = 2f(\lambda)\rho^\pm(\lambda, t) = 0, \quad \frac{\partial \Lambda^\pm_k}{\partial t}C_k^\pm(t) = 0, \]  
\[ i\frac{\partial C_k^\pm}{\partial t} = 2f_k^\pm C_k^\pm(t) = 0, \]

where \( f_k^\pm = f(\lambda_k^\pm) \).

Proof. Inserting the expansions over the symplectic basis (see equations (III.36) and (III.28)) into the left hand side of (IV.4) we get:

\[ i\int_{-\infty}^{\infty} d\lambda \{i\eta_k^\pm Q_k(x, t, \lambda) - (i\kappa_k^\pm - 2f_k^\pm)P_k(x, t, \lambda)\} + \]
\[ + i\sum_{k=1}^{N} \{i\eta_{k,t}^\pm Q_k(x, t) - (i\kappa_{k,t}^\pm - 2f_{k,t}^\pm)P_k(x, t)\} = 0. \]

Using again proposition 1 we establish the equivalence of (IV.3) and (IV.9).

To complete the proof of the theorem it is necessary to invoke proposition 1 and equation (III.55), from which it follows that the l.h. sides of the NLEEs (IV.5) – (IV.4) coincide. The theorem is proved.

Remark 3. Note the special role of the symplectic basis and related scattering data (IV.1) From (IV.7) we see that half of these data namely, \( \eta(\lambda) \), \( \eta^\pm \) are time-independent, while the other half \( \kappa(\lambda) \), \( \kappa^\pm \) depend linearly on time. This implies that \( T \) in fact provides us with global action–angle variables for the NLEEs (IV.4) – (IV.6). We shall return to this question in Section IV.2 below.

IV.2. Examples of NLEEs with polynomial dispersion laws

Here we list several examples of physically important NLEEs which fall into the above scheme. Theorem 2 shows, that each NLEEs is specified by the corresponding function \( f(\lambda) \). In physics this function is known as the dispersion law of the NLEEs; clearly \( f(\lambda) \) fixes up uniquely both the explicit form of the NLEEs and the evolution of the scattering data. Below we list a few examples of NLEE with ‘polynomial in \( \lambda \)’ dispersion laws.

In order to find the explicit form of the NLEEs we shall need to calculate \( \Lambda^p_k q(x, t) \) for \( p = 1, 2, 3 \). The calculation shows that:

\[ \Lambda^1_k q(x, t) = \frac{i}{4}[\sigma_3, q_{xx}], \]  
\[ (\Lambda^2_k)^2 q(x, t) = -\frac{1}{4}(q_{xx} + 2q_+ q_-(q(x, t))), \]  
\[ (\Lambda^3_k)^3 q(x, t) = -\frac{i}{16}[\sigma_3, q_{xxx} + 6q_+ q_-.q_2]. \]
These expressions illustrate two important facts. The first one was actually introduced by (III.55); the second, which will be analyzed below, is that \( A^k q(x,t) \) are local in \( q(x,t) \) for positive \( k \), i.e., \( A^k q(x,t) \) depend only on \( q \) and its \( x \)-derivatives.

The generic NLEEs will be systems of equations for the two complex-valued functions \( q_+(x,t) \) and \( q_-(x,t) \), which parametrize the potential \( q(x,t) \). Next, we shall show how these systems of NLEEs can be simplified by additional algebraic restrictions on \( q(x,t) \). Let us consider some examples.

**Example 1** (The GNLS equation.). This generalization of the NLS equation is obtained by choosing \( f(\lambda) = -c_2 \lambda^2 \). Then (IV.5) and (IV.12) lead to the following system:

\[
\begin{align*}
\frac{\partial q_+}{\partial t} + c_2 \frac{\partial^2 q_+}{\partial x^2} + 2c_2(q_+)^2 q_-(x,t) &= 0, \\
\frac{\partial q_-}{\partial t} - c_2 \frac{\partial^2 q_-}{\partial x^2} + 2c_2(q_-)^2 q_+(x,t) &= 0.
\end{align*}
\]  

(IV.14)

**Example 2** (The GmKdV equation.). The dispersion law for the generalized mKdV equation is given by \( f(\lambda) = -4c_3 \lambda^3 \). Then (IV.5) and (IV.13) lead to:

\[
\begin{align*}
\frac{\partial q_+}{\partial t} + c_2 \frac{\partial^2 q_+}{\partial x^2} + 6c_3 q_+ \frac{\partial q_+}{\partial x} q_-(x,t) &= 0, \\
\frac{\partial q_-}{\partial t} + c_2 \frac{\partial^2 q_-}{\partial x^2} + 6c_3 q_- \frac{\partial q_-}{\partial x} q_+(x,t) &= 0.
\end{align*}
\]  

(IV.15)

**Example 3** (Mixed GNLS–GmKdV equation.). The last example here is a generalization of the NLEEs with a dispersion law \( f(\lambda) = -c_2 \lambda^2 - 4c_3 \lambda^3 \), where \( c_2 \) and \( c_3 \) are some real constants. The corresponding system of NLEEs is:

\[
\begin{align*}
\frac{i}{2} \frac{\partial q_+}{\partial t} + c_2 \frac{\partial^2 q_+}{\partial x^2} + c_2(q_+)^2 q_-(x,t) + i c_3 \left( \frac{\partial q_+}{\partial x} q_+(x,t) - 2q_+ \frac{\partial q_+}{\partial x} q_-(x,t) \right) &= 0, \\
\frac{i}{2} \frac{\partial q_-}{\partial t} + c_2 \frac{\partial^2 q_-}{\partial x^2} + c_2(q_-)^2 q_+(x,t) - i c_3 \left( \frac{\partial q_-}{\partial x} q_-(x,t) + 2q_- \frac{\partial q_-}{\partial x} q_+(x,t) \right) &= 0.
\end{align*}
\]  

(IV.16)

It is well known, that each of these equations can be further simplified by imposing algebraic constraints on \( q_\pm \). For example, putting \( c_2 = 1 \) and \( q_\pm(x,t) = q_\pm(x,t) = u(x,t) \) eq. (IV.14) goes into the famous NLS eq. [25]. Similarly, putting \( q_\pm(x,t) = q_\pm(x,t) = v(x,t) \) eq. (IV.16) becomes the modified KdV for \( v(x,t) \). We will return to this point later.

**IV.3. The Integrals of motion and trace identities**

Here we start with the generating functional of the integrals of motion \( \mathcal{A}(\lambda) \) (II.27). Using the contour integration method, see [2, 8, 9, 12] we find that it can be expressed in terms of the minimal set of scattering data as follows (see Remark 1 and eq. (II.8)):

\[
\mathcal{A}(\lambda) = \frac{1}{2\pi i} \int_{-\infty}^{\infty} \frac{d\mu}{\mu - \lambda} \ln(a^+(\mu)a^-(\mu)) + \sum_{k=1}^{N} \ln \left( \frac{\lambda - \lambda_k^+}{\lambda - \lambda_k^-} \right).
\]  

(IV.17)

As integrals of motion we will consider the expansion coefficients of \( \mathcal{A} \) over the inverse powers of \( \lambda \):

\[
\mathcal{A}(\lambda) = \sum_{p=1}^{\infty} C_p \frac{1}{\lambda^p}.
\]  

(IV.18)

From (IV.17) and (IV.18) it follows that

\[
C_p = \frac{1}{2\pi} \int_{-\infty}^{\infty} d\mu \mu^{p-1} \ln(a^+(\mu)a^-(\mu)) - \frac{1}{2} \int_{-\infty}^{\infty} d\mu \mu^{p-1} \eta(\mu) - \frac{i\pi}{2p} \sum_{k=1}^{N} ((\eta_k^+)^p - (\eta_k^-)^p).
\]  

(IV.19)

Besides, from the Wronskian relation (II.26) we derive their dependence on the potential \( q(x,t) \) and its \( x \)-derivatives. Indeed, using eqs. (II.27) and the last line of (III.45) we obtain:

\[
\frac{\partial \mathcal{A}}{\partial \lambda} = -i \int_{-\infty}^{\infty} dx \left( \frac{1}{a^+(\lambda)} \mathrm{tr} \left( \Theta^+(x,\lambda)\sigma_3 \right) - 1 \right)
= \int_{-\infty}^{\infty} dx \left( \mathrm{tr} \left( (A_k - \lambda)^{-1} q(x)\sigma_3 \right) + i \right).
\]  

(IV.20)

It remains to compare the expansions of the right hand sides of (IV.20) and (IV.17) over the inverse powers of \( \lambda \). As a result we obtain the following compact expression for \( C_p \) in terms of \( q \) and its derivatives

\[
C_p = \frac{1}{ip} \int_{-\infty}^{\infty} dx \mathrm{tr} \left( A_p q(x)\sigma_3 \right).
\]  

(IV.21)

The well known trace identities [2, 6, 9] follow immediately by equating the right hand sides of eqs. (IV.19) and (IV.21). Let us list the first few nontrivial conserved quantities in terms of \( q(x) \)

\[
\begin{align*}
C_1 &= -\frac{1}{2} \int_{-\infty}^{\infty} dx q_+ q_-(x,t), \\
&= -\frac{1}{2} \int_{-\infty}^{\infty} d\mu \eta(\mu) + \frac{1}{2} \sum_{k=1}^{N} (\eta_k^+ + \eta_k^-),
\end{align*}
\]  

(IV.22)

\[
C_2 = -\frac{i}{8} \int_{-\infty}^{\infty} dx \left( q_+ \frac{\partial q_-}{\partial x} - q_- \frac{\partial q_+}{\partial x} \right)
\]
where both $F$ and $G$ are complex-valued functionals on $\mathcal{M}^C$ depending analytically on $q^\pm(x)$. Then the corresponding canonical symplectic form can be written as:

$$\Omega^C_{(0)} = \frac{1}{i} \int_{-\infty}^{\infty} dx \left( \delta q^-(x) \wedge \delta q^+(x) \right).$$

Next we need to specify the Hamiltonian $H^C$ as a functional over $\mathcal{M}^C$. Skipping the details (see [7, 10, 12]) we note that $H^C$ must depend analytically on the fields $q^\pm(x, t)$ and their $x$-derivatives.

The generic Hamiltonian equations of motion generated by $H^C$ and the Poisson brackets (IV.26) are the following:

$$\frac{\partial q^+}{\partial t} = \{H^C, q^+(x, t)\}_{(0)} = i \frac{\delta H^C}{\delta q^-(x)},$$

$$\frac{\partial q^-}{\partial t} = -\{H^C, q^-(x, t)\}_{(0)} = i \frac{\delta H^C}{\delta q^+(x)}.$$  (IV.28)

They are equivalent to a standard Hamiltonian system (with twice more real dynamical variables and degrees of freedom), provided $H^C$ is analytic with respect to $q^+_a$ and $q^-_b$. The analyticity of $H^C$ means that its real and imaginary parts $H^C_0$ and $H^C_1$ satisfy the analog of Cauchy-Riemann equations:

$$\frac{\delta H^C_0}{\delta q^+_0(x)} = \frac{\delta H^C_1}{\delta q^+_1(x)}, \quad \frac{\delta H^C_0}{\delta q^-_0(x)} = -\frac{\delta H^C_1}{\delta q^-_1(x)},$$

(IV.29)

where $q^0_a, a = 0, 1$ are the real and imaginary parts of $q^\pm(x)$:

$$q^\pm(x, t) = q^0(x, t) + iq^1(x, t).$$

(IV.30)

Then eqs. (IV.28) go into:

$$\frac{\partial q^0_0}{\partial t} = \frac{\delta H^C_0}{\delta q^+_0(x)}, \quad \frac{\partial q^0_1}{\partial t} = \frac{\delta H^C_0}{\delta q^+_1(x)},$$

$$\frac{\partial q^1_0}{\partial t} = \frac{\delta H^C_1}{\delta q^+_0(x)}, \quad \frac{\partial q^1_1}{\partial t} = -\frac{\delta H^C_1}{\delta q^+_1(x)}.$$  (IV.31)

which can be viewed as the equation of motion of an infinite-dimensional Hamiltonian system with real-valued Hamiltonian $H^C_{(0)}$. The elements of the phase space $\mathcal{M}^C$ can be viewed also as the 4-tuples of real functions $(q^0_a, q^1_a, q^0_b, q^1_b)$ vanishing fast enough for $x \to \pm \infty$. We designate the space of such 4-tuples by $\mathcal{M}_R$. The Poisson brackets on $\mathcal{M}_R$ correspond to the canonical symplectic form on $\mathcal{M}_R$ defined by the real part of $\Omega^C_{(0)}$:

$$\text{Re} \Omega^C_{(0)} = \int_{-\infty}^{\infty} dx \left( \delta q^0_\pm \wedge \delta q^1_\pm + \delta q^0_\mp \wedge \delta q^1_\mp \right).$$

(IV.32)

In what follows we shall use the formal Hamiltonian formulation of the generic NLEEs with complex-valued Hamiltonian $H^C$ and complex valued dynamical fields $q^\pm(x)$ as in eq. (IV.28). Those who prefer the standard Hamiltonian formulations using real-valued Hamiltonians and dynamical fields can always rewrite the generic NLEEs in their equivalent form (IV.31).

**Remark 4.** Similarly we can use an equivalent Hamiltonian formulation with $H = H^C_{(1)}$ and

$$\text{Im} \Omega^C_{(0)} = \int_{-\infty}^{\infty} dx \left( \delta q^0_\pm \wedge \delta q^1_\mp - \delta q^0_\mp \wedge \delta q^1_\pm \right).$$

(IV.33)

In what follows we will use the previous formulation with the Poisson brackets:

$$\{q^0_a(x, t), q^0_b(y, t)\}_{(0)} = 0, \quad \{q^1_a(x, t), q^1_b(y, t)\}_{(0)} = 0,$$

$$\{q^0_a(x, t), q^1_b(y, t)\}_{(0)} = 0, \quad \{q^1_a(x, t), q^0_b(y, t)\}_{(0)} = 0,$$

(IV.34a)

where $a, b = 1, 2$, and

$$\{q^0_a(x, t), q^1_b(y, t)\}_{(0)} = \frac{1}{2} \delta(x - y),$$

$$\{q^1_a(x, t), q^0_b(y, t)\}_{(0)} = \frac{1}{2} \delta(x - y).$$

(IV.34b)
Then if we choose

\[ f(x) = \begin{pmatrix} 0 & q_+ \\ q_- & 0 \end{pmatrix}. \]

The variational derivatives (or the ‘gradients’) of the functional \( H^C \) then will be written as:

\[ \nabla_q H^C \equiv \frac{\delta H^C}{\delta q^T(x)} = \begin{pmatrix} \frac{\delta H^C}{\delta q_+(x)} & 0 \\ 0 & \frac{\delta H^C}{\delta q_-(x)} \end{pmatrix}. \]  

(IV.35)

It remains to recall the definition of the skew-scalar product \([, ,] \) and after simple calculation one is able to write down the canonical Poisson brackets (IV.26) as follows:

\[ \{ F, G \}^C_{(0)} = \frac{i}{2} \int_{-\infty}^{\infty} \text{tr} \left( \nabla_q F, [\sigma_3, \nabla_q G] \right) dx \]

\[ = i \left[ \nabla_q F, \nabla_q G \right]. \]  

(IV.36)

The corresponding canonical symplectic form \( \Omega^C_0 \) becomes:

\[ \Omega^C_0 = i \int_{-\infty}^{\infty} dx \left( \delta q_+(x) \land \delta q_-(x) \right) \]

\[ = i \frac{1}{2} \left[ \sigma_3 \delta q \land \sigma_3 \delta q \right]. \]  

(IV.37)

By the symbol \( \land \) above we mean that we first perform the matrix multiplication keeping the order of the factors, and then replace the standard multiplication by an exterior product \( \land \). With all these notations we can write down (IV.28) in the form:

\[ i\sigma_3 \frac{\partial q}{\partial t} + \nabla_q H = 0. \]  

(IV.38)

The system (IV.14) generalizing the NLSE can be written down as a complex Hamiltonian system (IV.38) with \( H^C \) chosen to be:

\[ H^C = \int_{-\infty}^{\infty} dx \left[ q_+^2 - (q_+ q_-)^2 \right] = -8C_3. \]  

(IV.39)

Quite analogously one may check that all the other examples of NLEE also allow complex Hamiltonian structures with the symplectic structure introduced on \( \mathcal{M}_C \) by (IV.35).

Each of the generic NLEE (IV.4) with dispersion law \( f(\lambda) \) can be written down in the form (IV.38). It is only natural to expect that the corresponding Hamiltonian \( H \) should be expressed in terms of the integrals of motion \( C_p \). Indeed, eq. (II.21) can be written down in the form:

\[ \nabla_q C_p = -\frac{1}{2} \lambda^{p-1} q(x). \]  

(IV.40)

Then if we choose

\[ H^C = \sum_{k \geq 0} 4f_k C_{k+1}. \]  

(IV.41)

we get:

\[ \nabla_q H^C = -2f(\lambda)q(x). \]  

(IV.42)

Thus Eq. (IV.38) coincides with the NLEE (IV.4) with the dispersion law \( f(\lambda) = \sum_{k \geq 0} f_k \lambda^k \).

### IV.5. Action-angle variables of the generic NLEE

The most straightforward way to derive the action–angle variables of the NLEE (IV.38) is to insert into the r.h. side of (IV.37) the expansion (III.31) for \( \sigma_3 \delta q(x) \). This gives:

\[ \Omega^C_{(0)} = \int_{-\infty}^{\infty} dx \left[ \delta q_+(x) \land \delta q_-(x) \right] \]

\[ = \frac{1}{2} \left[ \sigma_3 \delta q(x) \land \left( \int_{-\infty}^{\infty} d\lambda \left( \delta \eta(\lambda) Q(x, \lambda) - \delta \kappa(t, \lambda) P(x, \lambda) \right) \right) \right] \]

\[ = i \int_{-\infty}^{\infty} d\lambda \, \delta \eta(\lambda) \land \delta \kappa(t, \lambda) + i \sum_{k=1}^{\infty} \delta \kappa_+^k \land \delta \kappa_-^k, \]  

(IV.43)

where \( \kappa(\lambda), \eta(\lambda), \kappa_+^k \) and \( \eta_-^k \) are given in eq. (III.55).

In the above calculation we made use of the inversion formulae for the symplectic basis (III.20) and identified the skew-symmetric scalar products of \( \sigma_3 \delta q(x) \) with the elements of the symplectic basis with the variations of \( \delta \eta(\lambda), \delta \kappa(t, \lambda) \), etc.

From (IV.43) we see also, that the 2-form \( \Omega^C_0 \) expressed by the variables \( \eta(\lambda), \kappa(\lambda), \eta_+^k \) and \( \kappa_-^k \) has a canonical form. Recall now the trace identities (IV.19). From them it follows, that the Hamiltonian \( H^C \) of the NLEE depends only on the variables \( \eta(\lambda), \eta_+^k \):

\[ H^C = -2 \int_{-\infty}^{\infty} d\mu f(\mu)\eta(\mu) + 4i \sum_{k=1}^{N} (F_k^+ - F_k^-), \]

\[ f(\mu) = \sum_{k \geq 0} f_k \mu^{p-1}, \]  

(IV.44)

where

\[ F_k^+ = F(i\eta_+^k / 2), \quad F_k^- = F(-i\eta_-^k / 2), \]

(IV.45)

\[ F(\lambda) = \int d\lambda' f(\lambda'). \]

Obviously \( H^C \) depends only on the action variables \( \eta(\lambda) \) and \( \eta_+^k \). Let us now recall one of the results of Theorem 2, stating that if \( q(x, t) \) satisfies the NLEE (IV.38) then...
The variables $\eta(\lambda), \kappa(\lambda, t), \eta_k^\pm$ and $\kappa_k^\pm(t)$ satisfy:

$$\begin{align*}
\frac{d\eta}{dt} &= 0, \\
\frac{d\kappa}{dt} &= 0, \\
\frac{d\eta_k^\pm}{dt} &= 0, \\
\frac{d\kappa_k^\pm(t)}{dt} &= 2f(\lambda), \\
\frac{d\kappa_k^\pm}{dt} &= 2f(\lambda^\pm).
\end{align*}$$

Thus

**AA1**: the variables $\eta(\lambda), \kappa(\lambda, t), \eta_k^\pm$ and $\kappa_k^\pm(t)$ form a canonical basis in $\mathcal{M}^C$;

**AA2**: Hamiltonian $H^C$ depends only on ‘half’ of them: $\eta(\lambda)$ and $\eta_k^\pm$, $k = 1, \ldots, N$;

**AA3**: The variables $\eta(\lambda)$ and $\eta_k^\pm$, $k = 1, \ldots, N$ are time independent, while $\kappa(\lambda, t)$ and $\kappa_k^\pm(t)$ depend linearly on $t$.

Thus we conclude that these variables are generalized action-angle variables of the generic NLEE (IV.38). Another reason to use the term generalized is in the fact, that these variables are complex-valued.

Of course, they can be written as:

$$\begin{align*}
\eta(\lambda) &= \eta_0(\lambda) + i\eta_1(\lambda), \\
\kappa(\lambda, t) &= \kappa_0(\lambda, t) + i\kappa_1(\lambda, t), \\
\eta_k^\pm &= \eta_k^{0,\pm} + i\eta_k^{1,\pm}, \\
\kappa_k^\pm(t) &= \kappa_k^{0,\pm} + i\kappa_k^{1,\pm},
\end{align*}$$

where

$$\begin{align*}
\eta_0(\lambda, t) &= -\frac{1}{2} \ln |a^+a^- (\lambda)|, \\
\eta_1(\lambda, t) &= -\frac{1}{\pi} \left( \text{arg}(a^+ (\lambda)) + \text{arg}(a^- (\lambda)) \right), \\
\kappa_0(\lambda, t) &= \frac{1}{2} \ln \left| \frac{b^+(\lambda, t)}{b^-(\lambda, t)} \right|, \\
\kappa_1(\lambda, t) &= \frac{1}{2} \left( \text{arg}(b^+(\lambda, t)) + \text{arg}(b^- (\lambda, t)) \right), \\
\eta_k^{0,\pm} &= \mp 2\lambda_k^{1,\pm}, \\
\kappa_k^{0,\pm} &= \pm 2\lambda_k^{1,\pm}, \\
\kappa_k^{1,\pm} &= \pm \text{arg}(\lambda_k^{0,\pm}) + \text{arg}(\lambda_k^{0,\pm}).
\end{align*}$$

Note that the derivation of this result is based on the completeness relation of the symplectic basis. This ensures: (i) the uniqueness and the invertibility of the mapping from $\{q^\pm(x)\}$ to $\mathcal{T}$; (ii) the nondegeneracy of the 2-form $\Omega^C$ on $\mathcal{M}^C$.

One can view $g^\pm(x)$ as local coordinates on $\mathcal{M}^C$; any functional $F$ or $G$ on $\mathcal{M}^C$ can be expressed in terms of $q^\pm(x)$. The variations $\delta F$ and $\delta G$ of the functionals $F$ and $G$ are the analogs of 1-forms over $\mathcal{M}^C$. They can be expressed in terms of ‘gradients’ by:

$$\delta F = \left[ \nabla_q F, \sigma_3 \delta q \right], \quad \delta G = \left[ \nabla_q G, \sigma_3 \delta q \right].$$

The ‘gradients’ $\nabla_q F$ and $\nabla_q G$ are elements of the space $T_q \mathcal{M}^C$ tangential to $\mathcal{M}^C$.

At the same time the mapping to $\mathcal{T}$ is one-to-one, therefore it is possible to express $F$ and $G$ in terms of the scattering data. To this end we consider the expansions of $\nabla_q F$ and $\nabla_q G$ over the symplectic basis:

$$\begin{align*}
\nabla_q F &= i \int_{-\infty}^{\infty} (\eta_{F,\lambda} Q(x, \lambda) - \kappa_{F,\lambda} P(x, \lambda)) d\lambda \\
&+ i \sum_{k=1}^{N} \left( \eta_{F,k}^\pm Q_k^\pm(x) - \kappa_{F,k}^\pm P_k^\pm(x) \right),
\end{align*}$$

$$\begin{align*}
\eta_{F,\lambda} &= i \left[ [P(x, \lambda), \nabla_q F], \nabla_q F \right], \\
\kappa_{F,\lambda} &= i \left[ [Q(x, \lambda), \nabla_q F], \nabla_q F \right], \\
\eta_{F,k}^\pm &= i \left[ [P_k^\pm(x), \nabla_q F], \nabla_q F \right], \\
\kappa_{F,k}^\pm &= i \left[ [Q_k^\pm(x), \nabla_q F], \nabla_q F \right].
\end{align*}$$

Similar expansion for $\nabla_q G$ is obtained from (IV.50) by changing $F$ to $G$. Such expansions will hold true provided $F$ and $G$ are restricted in such a way that the expansion coefficients $\eta_{F,\lambda}$ and $\kappa_{F,\lambda}$ are smooth and fall off fast enough for $\lambda \to \pm \infty$. In what follows we shall assume that the functionals $F$ and $G$ satisfy the following:

**Condition C3.** The functionals $F$ and $G$ are restricted by the following implicit condition: the expansion coefficients $\eta_{F,\lambda}$ and $\kappa_{F,\lambda}$ and $\eta_{G,\lambda}$ and $\kappa_{G,\lambda}$ are Schwartz-type functions of $\lambda$ for real $\lambda$.

Using the bi-quadratic relations satisfied by the elements of the symplectic basis [12] we can express the Poisson brackets between $F$ and $G$ in terms of their expansion coefficients as follows:

$$\begin{align*}
\{F, G\}^C_{(0)} &= -i \left[ \nabla_q F, \nabla_q G \right] = \int_{-\infty}^{\infty} d\lambda \ (\eta_{F,\kappa} G - \kappa_{F,\eta} G) (\lambda) \\
&+ \sum_{k=1}^{N} \left( \eta_{F,k}^\pm \kappa_{G,k}^\pm - \kappa_{F,k}^\pm \eta_{G,k}^\pm \right). \\
\{F, G\}^C_{(0)} &= 2 \int_{-\infty}^{\infty} d\lambda \ f(\lambda) \eta_{G,\lambda} (\lambda) \\
&+ 2 \sum_{k=1}^{N} (f(\lambda_k^\pm) \eta_{G,k}^\pm + f(\lambda_k) \eta_{G,k}^\pm) = 0.
\end{align*}$$

In particular, if we choose $F = H^C$ then from eq. (IV.44) we find that $\eta_{H^C,\lambda} = 0$, $\eta_{H^C,k}^\pm = 0$ and

$$\kappa_{H^C,k}^\pm(\lambda) = -2f(\lambda), \quad \kappa_{H^C,k}^\pm = -2f(\lambda_k^\pm),$$

which gives:

$$\{H, G\}^C_{(0)} = 2 \int_{-\infty}^{\infty} d\lambda \ f(\lambda) \eta_{G,\lambda} (\lambda) \\
&+ 2 \sum_{k=1}^{N} (f(\lambda_k^\pm) \eta_{G,k}^\pm + f(\lambda_k) \eta_{G,k}^\pm).$$

Eq. (IV.54) allows us to describe implicitly the set of functionals $G$ that are in involution with all integrals of motion of the generic NLEE. Indeed, the right hand side of (IV.54) will vanish identically for all choices of the dispersion law $f(\lambda)$ only if the expansion coefficients of $\nabla_q G$ satisfy:

$$\eta_g(\lambda) = 0, \quad \lambda \in \mathbb{R}; \quad \eta_{G,k}^\pm = 0, \quad k = 1, \ldots, N.$$
We end this subsection by noting the special role of the subspace \( \mathcal{L}^C \subset \mathcal{M}^C \) spanned by \( P(x,\lambda) \) and \( P_k^\pm (x) \), \( \kappa \in \mathbb{Z}, \, 1 \leq k \leq N \), i.e. by ‘half’ of the elements of the symplectic basis. Obviously all Hamiltonian vector fields with Hamiltonians of the form (IV.41) induce dynamics which is tangent to \( \mathcal{L}^C \). This is a maximal subspace of \( \mathcal{M}^C \) on which the symplectic form \( \Omega^C_0 \) is degenerate. Therefore \( \mathcal{L}^C \) is the Lagrange submanifold of \( \mathcal{M}^C \). Dynamics defined by the Hamiltonian vector fields that are not tangential violate the complete integrability.

V. HAMILTONIAN HIERARCHIES AND ACTION-ANGLE VARIABLES

V.1. The Hierarchy of Poisson brackets

The complete integrability of the generic NLEE makes them rather special. They have an infinite number of integrals of motion \( C_n \) which are in involution and moreover satisfy the relation:

\[
\nabla_q C_{n+m} = \Lambda^m \nabla_q C_n, \tag{V.1}
\]

which generalizes the Lenard relation (IV.40). The important fact here is that the recursion operator \( \Lambda \) is universal one and does not depend on either \( n \) or \( m \). This has far reaching consequences which we outline below.

The first one consists in the possibility to introduce a hierarchy of Poisson brackets:

\[
\{F,G\}_m^C = \frac{1}{i} \left[ \nabla_q F, \Lambda^m \nabla_q G \right]. \tag{V.2}
\]

Below we shall show that these Poisson brackets satisfy all the necessary properties.

First, using the fact that \( \Lambda \) is ‘self-adjoint’ with respect to the skew-symmetric scalar product (III.47) we easily check that the Poisson bracket defined by (V.2) is skew-symmetric. Indeed:

\[
\{F,G\}_m^C = \frac{1}{i} \left[ \nabla_q F, \Lambda^m \nabla_q G \right] = -\frac{1}{i} \left[ \nabla_q G, \Lambda^m \nabla_q F \right] = -\{G,F\}_m^C. \tag{V.3}
\]

We have also the Leibnitz rule:

\[
\{FG,H\}_m^C = \frac{1}{i} \left[ \nabla_q (FG), \Lambda^m \nabla_q H \right] = \frac{1}{i} \left[ \nabla_q F, \Lambda^m \nabla_q G \right] G + \frac{1}{i} \left[ \nabla_q G, \Lambda^m \nabla_q H \right] F = \{F,G\}_m^C \{G,H\}_m^C + \{F,H\}_m^C \{G,F\}_m^C, \tag{VA}
\]

since \( \nabla_q (FG) = F \nabla_q G + (\nabla_q F)G \).

Using the expansion (IV.50) of \( \nabla_q F \), an analogous one for \( \nabla_q G \) and the fact that the elements \( P(x,\lambda) \) and \( Q(x,\lambda) \) are eigenfunctions of \( \Lambda \) (see eq. (III.46)) we find:

\[
\{F,G\}_m^C = -i \left[ \nabla_q F, \Lambda^m \nabla_q G \right]
\]

\[
= \int_{-\infty}^\infty d\lambda \lambda^m \left( \eta_F \kappa_G - \kappa_F \eta_G \right)(\lambda) \\
+ \sum_{k=1}^N \pm \left( \lambda_k^\pm \right)^m \left( \eta_{F,k}^\pm \kappa_G^\pm - \kappa_F^\pm \eta_G^\pm \right). \tag{V.5}
\]

The Jacobi identity is far from trivial to check in these terms. This will be done using the corresponding symplectic form and for that reason we postpone the proof until later.

The existence of a hierarchy of Poisson brackets entails that there must exist also hierarchy of vector fields, symplectic forms, etc.

V.2. The Hierarchy of symplectic forms

Let us define:

\[
\Omega^C_{(m)} = \frac{i}{2} \left[ \sigma_3 \delta q(x) \wedge \Lambda^m \sigma_3 \delta q(x) \right]. \tag{V.6}
\]

These 2-forms are not canonical. The proof of the fact that \( \delta \Omega^C_{(m)} = 0 \) is performed by recalculating them in terms of the ‘action-angle’ variables. For this we follow the same idea as in the calculation of \( \Omega^C_0 \), see eq. (IV.43). We insert the expansion for \( \sigma_3 \delta q(x) \) over the symplectic basis and then act on this expansion by \( \Lambda^m \).

This is easy to do because of (III.46) and the result is:

\[
\Lambda^m \sigma_3 \delta q(x) \\
= i \int_{-\infty}^\infty d\lambda \lambda^m (\delta \eta(\lambda) Q(x,\lambda) - \delta \kappa(t,\lambda) P(x,\lambda)) \\
+ i \sum_{k=1}^N \pm (\pm \lambda_k^\pm \delta \eta_{k^\pm}^\pm Q_k^\pm (x) - \delta \kappa_{k^\pm}^\pm P_k^\pm (x)), \tag{V.7}
\]

where \( \kappa(\lambda), \eta(\lambda), \kappa_{k^\pm}^\pm \) and \( \eta_{k^\pm}^\pm \) are given in eq. (III.55).

Calculating the skew-symmetric scalar products of \( \sigma_3 \delta q(x) \) with the r.h. side of (V.7), we again obtain the variations of the \( \eta \) and \( \kappa \)-variables. Finally we get:

\[
\Omega^C_{(m)} = i \int_{-\infty}^\infty d\lambda \lambda^m \delta \kappa(t,\lambda) \wedge \delta \eta(\lambda) \\
+ i \sum_{k=1}^N \pm (\pm \lambda_k^\pm \delta \kappa_{k^\pm}^\pm + (\lambda_k^-)^m \delta \kappa_{k^-}^\pm + \delta \eta_{k^-}^\pm) \\
= i \int_{-\infty}^\infty d\lambda \lambda^m \delta \kappa(t,\lambda) \wedge \delta \eta(\lambda) \\
+ c_{0,m} \sum_{k=1}^N \left( \delta \kappa_{k^-}^\pm \wedge \delta (\eta_{k^-}^\pm)^{m+1} + (-1)^m \delta \kappa_{k^-}^\pm \wedge \delta (\eta_{k^-}^\pm)^{m+1} \right), \tag{V.8}
\]

where \( c_{0,m} = i^{m+1} 2^{-m(m+1)} \).

Remark 5. The right hand sides of (V.8) are well defined for all \( m \geq 0 \) for potentials \( q(x) \) satisfying condition C1. This condition ensures that \( \kappa(t,\lambda) \) and \( \eta(\lambda) \) are Schwartz-type functions of \( \lambda \).
Remark 6. For negative values of \( m \) the existence of 
the integrals in (V.8) is ensured only, provided we put 
additional restrictions on \( q(x) \) which would ensure that 
\( \min_{\lambda \to 0} \lambda^{-m} \delta \kappa(t, \lambda) \wedge \delta \eta(\lambda) \) exists for all \( m < 0 \).

Now it is easy to prove

**Proposition 2.** Let the potential \( q(x) \) satisfy condition 
\( C_1 \). Then each of the symplectic forms \( \Omega_C^m \) for \( m \geq 0 \) 
is closed, i.e.
\[
\delta \Omega_C^m = 0, \quad m = 0, 1, 2, \ldots
\] (V.9)

If in addition \( q(x) \) satisfies the condition in remark 6 
then each of the symplectic forms \( \Omega_C^m \) is closed also for 
\( m < 0 \).

**Proof.** Indeed, the condition in proposition 2 is such that 
the integral in the right hand side of (V.8) is well defined 
so we can interchange the integration with the operation 
of taking the external differential \( \delta \). Therefore we have:
\[
\delta \Omega_C^m = i \int_{-\infty}^{\infty} d \lambda \lambda^{-m} \delta (\delta k(t, \lambda) \wedge \delta \eta(\lambda))
\]
\[
+ \sum_{k \in \mathbb{Z}} \int_{-\infty}^{\infty} d \lambda \lambda^{-m} \delta (\delta k_+ \wedge \delta (\eta_+)^{m+1} + \delta (\eta_-)^{m+1} \wedge \delta \eta_-)
\]
\[\text{where we used the simple fact that } \delta(\delta g(\lambda)) = 0 \text{ for any } g(\lambda). \square \]

**Corollary 1.** Direct consequence of Proposition 2 is that 
the Poisson brackets \( \{ \cdot, \cdot \}_C^m \) satisfy Jacobi identity.

Therefore we have shown that each generic NLEE allows a hierarchy of Hamiltonian formulations:
\[
\frac{\partial q_+}{\partial t} = \{ H_C^m, q_+(x) \}_C^{m+1},
\]
\[
-\frac{\partial q_-}{\partial t} = -\{ H_C^m, q_-(x) \}_C^{m+1},
\]
\[
\frac{\partial H_C^m}{\partial t} = \sum_{k \in \mathbb{Z}} 4 f_k C_{k+n+1}, \quad \frac{\partial H_C^m}{\partial \lambda} = -2 \Lambda^p f(\Lambda) q(x, t)
\]
(V.11)

\[
\text{where}
\]
\[
H_C^m = \sum_{k \geq 0} 4 f_k C_{k+n+1}, \quad \nabla q H_C^m = -2 \Lambda^p f(\Lambda) q(x, t)
\]
see eqs. (IV.41), (IV.42).

One can relate the existence of the hierarchy of Hamiltonian structures to the simple fact that the generic 
NLEE:
\[
\Lambda^m \left( i \sigma_3 \frac{\partial q}{\partial t} + 2 f(\Lambda) q(x, t) \right) = 0
\]
are equivalent to the NLEE (IV.38), (IV.41). In terms of the ‘action–angle’ variables
\[
i \lambda^m \eta_\lambda = 0, \quad \lambda^m (i \kappa_\lambda - 2 f(\Lambda)) = 0,
\]
\[
i (\lambda_\lambda^+)^m \eta_\lambda^+ = 0, \quad (\lambda_\lambda^-)^m (i \kappa_\lambda^+ - 2 f(\Lambda^+)) = 0
\]
(V.14)

For \( m = 0 \) we recover the equations from section 4.

VI. LOCAL AND NONLOCAL INVOLUTIONS 
OF THE ZAKHAROV–SHABAT SYSTEM

VI.1. The (local) involution
\[
q_-(x, t) = (q_+(x, t))^* = u(x, t)
\]

It is well known that one can impose on the generic 
Zakharov-Shabat system \( L \) additional constraints. These 
are achieved with the help of Cartan-like involutions. In 
this way one can derive different real Hamiltonian forms 
of the generic NLEE, see [7, 10, 11].

We will outline this procedure for the best known involutions which allowed Zakharov and Shabat to solve the 
NLS equation.

The involution \( q_+(x, t) = (q_-(x, t))^* = u(x, t) \) is a consequence of the following symmetry of \( L \) and, 
consequently on \( U(x, t, \lambda) \):
\[
U^*(x, t, \lambda^*) = -\sigma^{-1} U(x, t, \lambda) \sigma, \quad \sigma = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}
\]
(VI.1)

As a consequence of this symmetry we obtain constraints 
on the FAS and on the scattering matrix as follows:
\[
\chi^+(x, t, \lambda^*) = \sigma^{-1} \chi^-(x, t, \lambda) \sigma, \quad T^*(\lambda^*, t) = \sigma^{-1} T(\lambda, t) \sigma
\]
(VI.2)
or in components:
\[
a^- (\lambda) = (a^+(\lambda^*))^*, \quad b^- (\lambda, t) = (b^+(\lambda^*, t))^*.
\]
(VI.3)

Thus if \( \lambda_k^+ \) is a zero of \( a^+ (\lambda) \) then \( \lambda_k^-^* \) is a zero of \( a^- (\lambda) \).
In other words, the discrete eigenvalues of \( L \) satisfying 
this reduction come in complex conjugate pairs \( \lambda_k^+ = \lambda_k^-^* \).

More specifically, for the action-angle variables we get:
\[
\eta(\lambda) = \eta^*(\lambda) = -\frac{1}{\pi} \ln |a^+(\lambda)|^2, \quad \kappa(\lambda, t) = -k^*(\lambda, t) = i \arg b^+(\lambda)
\]
(VI.4a)

\[
\eta_k^+ = (\eta_k^-)^* = -2i \lambda_k^+, \quad b_k^- = b_k^+^*, \quad \kappa_k^+ = -(\kappa_k^-)^* = \ln |b_k^+| + i \arg b_k^+, \quad \hat{a}_k^+ = (\hat{a}_k^-)^*
\]
(VI.4b)

where \( \lambda \in \mathbb{R} \) and \( k = 1, \ldots, N \). Thus we conclude that 
\( \Omega(0) \) becomes purely real and has the form:
\[
\Omega(0) = \int_{-\infty}^{\infty} d \lambda \delta \eta(\lambda) \wedge \delta \arg b^+(t, \lambda)
\]
\[
+ \sum_{k \in \mathbb{Z}} (\delta \eta_k^+ \wedge \delta \kappa_k^+(t) - \delta \eta_k^- \wedge \delta \kappa_k^- \wedge \delta \kappa_k^+(t)).
\]
(VI.5)

As regards the integrals of motion, they also become 
real valued:
are real: admits only dispersion laws whose expansion coefficients
of the NLEE. In other words the reduction (VI.1)
\[ \ln |k| \]
three types of action variables: \( \arg \psi \) on the continuous and discrete spectrum. Now two of the
functions of the hierarchy \( \Omega_{(m)} \):
\[ \Omega_{(m)} = \int_{-\infty}^{\infty} d\lambda \lambda^m \delta \eta(\lambda) \wedge \delta \arg b^+(t, \lambda) \]
\[ + c_0 \sum_{k=1}^{N} (\delta(\eta_+^{*})^{m+1} \wedge \delta \kappa_k^+ - (\delta(\eta_-^{*})^{m+1} \wedge \delta \kappa_k^-) \].

The hierarchy of Hamiltonians is provided by:
\[ H_{(m)} = 4 \int_{-\infty}^{\infty} \mu^m f(\mu) \eta(\mu) + 4i \sum_{k=1}^{N} (F_{(m),k}^+ F_{(m),k}^-), \]
where
\[ F^{(m)}(\lambda) = \int_{-\infty}^{\lambda} d\lambda' f(\lambda') \lambda'^{m-1}, \quad F_{(m),k}^+ F_{(m),k}^- = F_{(m)} \left( \pm i \eta_+^{\pm} \right) \frac{2}{2}. \]

Thus we see that the overall effect of the reduction is to
decrease ‘twice’ the number of dynamical variables both
on the continuous and discrete spectrum. Now two of the
three types of action variables: \( \arg b^+(t, \lambda) \) and \( \arg b_k^* \) are
real and take values in the interval \([0, 2\pi]\); the third type
\( \ln |b_k^*| \) is also real, but may take arbitrary values.

The reduction imposes also restrictions on the dispersion
law of the NLEE. In other words the reduction (VI.1)
admits only dispersion laws whose expansion coefficients are real:
\[ f(\lambda) = \sum_p f_p \lambda^p, \quad f_p = f_p^*. \] (VI.11)

Some of the most important examples of NLEE obtained
by this reduction \( (u = q_+(x, t) = q_-(x, t)) \) are the NLS
NLS and complex mKdV:
\[ \text{NLS} \quad iu_t + u_{xx} + 2u|u|^2u(x, t) = 0, \]
\[ \text{cmKdV} \quad u_t + u_{xxx} + 6|u|^2u_x(x, t) = 0, \]
\[ \text{NLS-cmKdV} \quad iu_t + u_{xx} + 2u|u|^2u(x, t) + ic\alpha(u_{xx} + 6u^2u_x) = 0. \] (VI.12)

Their dispersion laws are given by:
\[ f_{\text{NLS}}(\lambda) = -\lambda^2, \quad f_{\text{cmKdV}}(\lambda) = -4\lambda^3, \]
\[ f_{\text{NLS-cmKdV}}(\lambda) = -\lambda^2 - 4\alpha \lambda^3. \] (VI.13)

VI.2. The nonlocal involution \( A \):
\( q_-(x, t) = (q_+)^*(x, t) = u(x, t) \)

The involution stated in the title of this Subsection is
one of the simplest nonlocal involution compatible with our Lax pair. If we assume that \( q_-(x, t) = q_+(x, t)^* \)
then one can check that \( U(x, t, \lambda) = q(x, t) - \lambda \sigma_3 \) satisfies:
\[ U(x, t, \lambda) = \sigma_1 (U(-x, t, -\lambda^*)^*) \sigma_1^{-1}, \quad \sigma_1 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}. \] (VI.14)

In other words the involution on the potential \( q(x, t) \)
can be extended to an involutive automorphism of the
affine Lie algebra in which \( U(x, t, \lambda) \) and \( V(x, t, \lambda) \) take
values. Obviously this involutive automorphism extends
to all fundamental solutions of \( L \). For example, the Jost
solutions must satisfy [3]:
\[ \psi^-(x, t, \lambda) = \sigma_1^{-1} (\phi^-(x, t, -\lambda^*)^*)^*, \]
\[ \psi^+(x, t, \lambda) = \sigma_1 (\phi^+(x, t, -\lambda^*)^*)^*. \] (VI.15)

This relation can be written in compact form:
\[ \psi(x, t, \lambda) = \sigma_1 (\phi(x, t, -\lambda^*)^*)^* \sigma_1^{-1}. \] (VI.16)

Taking into account eq. (II.2) we derive the following
constraint for the scattering matrix:
\[ T(\lambda, t) = \sigma_1 T(-\lambda^*, t)^* \sigma_1^{-1}; \] (VI.17)
similarly from eq. (II.4) for the FAS we find:
\[ \chi^+(x, t, \lambda) = \sigma_1 (\chi^+(x, t, -\lambda^*)^*)^{-1}, \]
\[ \chi^-(x, t, \lambda) = \sigma_1 (\chi^-(x, t, -\lambda^*)^*)^{-1}. \] (VI.18)

The involution imposes a condition also on the dispersion
law of the NLEE; in our case this is:
\[ f(\lambda) = (f(-\lambda^*)^*), \quad \text{i.e.} \quad f(\lambda) = \sum_{k=0}^{\infty} f_{2k} \lambda^{2k}, \] (VI.19)
which means that \( f(\lambda) \) must be an even polynomial of
\( \lambda \) with real coefficients. In particular, this nonlocal
involution \( A \) is compatible with the NLS equation, be-
cause its dispersion law is \( f_{\text{NLS}}(\lambda) = -2\lambda^2 \) but can not
Lemma 2. The functions $a^\pm(\lambda)$ satisfy the dispersion relations:

$$
\lambda^+ = (\lambda + \lambda^+)^*, \quad a^-(\lambda) = (\lambda - \lambda^-)^*.
$$

(VI.20)

The scattering data on the discrete spectrum is also subject to constraints. For example, the constraints on $a^\pm(\lambda)$ (VI.20) mean that, if $\lambda_k$ is a zero of $a^+(\lambda)$ (resp. $\lambda_k$ is a zero of $a^-(\lambda)$) then $-(\lambda_k)^*$ is also a zero of $a^+(\lambda)$ (resp. $-(\lambda_k)^*$ is also a zero of $a^-(\lambda)$). In other words, the discrete eigenvalues of $L$ must be symmetrically situated around the imaginary axis in the complex $\lambda$-plane.

Corollary 2. The above statement means that $L$ must have two different types of discrete eigenvalues; a) purely imaginary ones

$$
\lambda^+_s = - (\lambda^+_s)^* = - \ln^+_t, \quad \lambda^-_s = -(\lambda^-_s)^* = - \ln^-_t;
$$

(VI.21)

with $n^+_s$ real and positive and $s = 1, \ldots, N_1$; b) pairs of complex conjugated ones

$$
\lambda^+_r = p_r + \lambda^+_r, \quad \lambda^-_r + N_2 = - \lambda^-_r = - p_r + \lambda^-_r,
$$

\begin{align*}
\lambda^+_s &= r, \quad \lambda^-_s = - \lambda^-_s, \quad s = 1, \ldots, N_1 + N_2, p^+_r > 0 \text{ and } s^+_r > 0.
\end{align*}

(VI.22)

In what follows without restrictions we assume that $n^+_s$ for $s = 1, \ldots, N_1$ and $p_r$, $s_r$ for $r = N_1 + 1, \ldots, N_2$ are all real and positive. Then the number of discrete eigenvalues of $L$ will be $N = 2N_1 + N_2$. In particular, the two different types of eigenvalues mean that the non-local NLS, like the sine-Gordon equation must have two different types of soliton solutions.

Remark 7. The simplest one-soliton solution for the nonlocal NLS was calculated in [3] and shown to be a singular function which does not vanish for $t \to \pm \infty$, see also [20]. The solution in [3] however was derived assuming that $a^+(\lambda)$ has only one simple zero which is purely imaginary, thus violating condition C2. Our hypothesis is that one may be able to construct regular soliton solutions if we take configurations of the zeros $\lambda^+_k$ satisfying condition C2. In particular this means, that the simplest regular solution will be a two-soliton one.

The discrete spectrum of $L$ satisfying the non-local reduction consists of all the zeroes of $a^\pm(\lambda)$ which can be of two sorts, see Corollary 2 above.

Lemma 2. The functions $a^\pm(\lambda)$ satisfy the dispersion relations

$$
\mathcal{A}(\lambda) = \frac{1}{2\pi i} \int_{-\infty}^{\infty} \frac{d\mu}{\mu - \lambda} \ln (a^+ a^- (\mu))
$$

(VI.23)

where

$$
\mathcal{A}(\lambda) = \begin{cases} 
\ln a^+(\lambda) & \text{for } \lambda \in \mathbb{C}_+ \\
\frac{1}{2} \ln (a^+(\lambda)/a^- (\lambda)) & \text{for } \lambda \in \mathbb{R} \\
- \ln a^- (\lambda) & \text{for } \lambda \in \mathbb{C}_-.
\end{cases}
$$

(VI.24)

Proof. The proof goes in analogy with one of the generic cases in Subsection IV.3. Only now we need a different definition of $\tilde{a}^\pm(\lambda)$ as follows:

$$
\tilde{a}^+(\lambda) = a^+(\lambda) \prod_{s=1}^{N_1} \frac{\lambda + \lambda^+_s}{\lambda - \ln^+_t} \prod_{r=1}^{N_2} \frac{\lambda - \lambda^-_r}{\lambda - \lambda^+_r} (\lambda + \lambda^-_r)^{-1},
$$

$$
\tilde{a}^-(\lambda) = a^- (\lambda) \prod_{s=1}^{N_1} \frac{\lambda - \lambda^- s}{\lambda + \ln^+_t} \prod_{r=1}^{N_2} \frac{\lambda + \lambda^-_r}{\lambda + \lambda^-_r} (\lambda + \lambda^-_r)^{-1},
$$

(VI.25)

where $\tilde{a}^\pm$ are analytic functions for $\lambda \in \mathbb{C}_+$ and have no zeroes in their regions of analyticity. We can again evaluate the integral $\mathcal{J}_s(\lambda)$ as in (III.49) and derive dispersion relations for the analytic functions $a^\pm(\lambda)$. Due to the different reduction we get a new result given by (VI.23) above.

Taking into account that

$$
a^+ a^- (\mu) = (1 + \rho^+ \rho^- (\mu))^{-1} = (1 + \tau^+ \tau^- (\mu))^{-1}
$$

(VI.26)

one easily concludes that the analytic functions $a^+ a^- (\mu)$ can be recovered easily from each of the minimal sets of scattering data (III.54): again we have to take into account the different structure of the set of discrete eigenvalues.

We will need also the behavior of $a^\pm(\lambda)$ in the neighborhood of the discrete eigenvalues:

$$
a^\pm(\lambda) \simeq \lambda^\pm (\lambda \mp \ln^+_t)^a_{s}\pm \frac{1}{2} (\lambda \mp \ln^+_t)^2 \tilde{a}_{s}\pm + O ((\lambda \mp \ln^+_t)^3),
$$

$$
a^\pm(\lambda) \simeq \lambda^\pm (\lambda \mp \lambda^-_r)^a_{r}\pm \frac{1}{2} (\lambda \mp \lambda^-_r)^2 \tilde{a}_{r}\pm + O ((\lambda \mp \lambda^-_r)^3),
$$

$$
a^\pm(\lambda) \simeq \lambda^\pm (\lambda \mp \lambda^+_r)^a_{r}^+ + \frac{1}{2} (\lambda \mp \lambda^+_r)^2 \tilde{a}_{r}^+ + O ((\lambda \mp \lambda^+_r)^3).
$$

(VI.27)

The reduction conditions (VI.20) impose constraints on the coefficients of eq. (VI.27) which read:

$$
\dot{a}_{s}^\pm = - \ddot{a}_{s}^\pm, \quad \ddot{a}_{s}^\pm = \dot{a}_{s}^\pm, \quad \dot{a}_{r}^\pm = - \ddot{a}_{r}^\pm, \quad \ddot{a}_{r}^\pm = \dot{a}_{r}^\pm,
$$

(VI.28)

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The constants $a_{\pm}^\pm$ and $\tilde{a}_{\pm}^\pm$ are not enough to characterize the discrete spectrum. Indeed, the FAS $\chi_\pm(x,\lambda)$ become degenerate for $\lambda = \lambda_0^\pm$, which means that if $\psi_k^\pm(x,t) = \psi^\pm(x,t,\lambda_0^\pm)$ and $\phi_k^\pm(x,t) = \phi^\pm(x,t,\lambda_0^\pm)$ then

$$
\phi_s^\pm(x,t) = \pm b_s^\pm(t)\psi_s^\pm(x,t),
\phi_k^\pm(x,t) = \pm b_k^\pm(t)\psi_k^\pm(x,t),
$$

and, as we shall see below, the constants $b_k^\pm(t)$ determine the angle variables.

The easiest way to find their properties is to assume that the potential $q(x,t)$ is on a finite support, see Remark 2. Then all the matrix elements of the scattering matrix $a_{\pm}^\pm(\lambda)$ and $b_{\pm}(\lambda)$ allow analytic extension for any $\lambda \in \mathbb{C}$. Consider now the functions $b_{\pm}(\lambda)$ in the vicinity of $\lambda_k^\pm$:

$$
b_{\pm}(\lambda, t) \simeq b_k^\pm(t) + \mathcal{O}((\lambda - \lambda_k^\pm)),
$$

i.e., we have denoted by $b_k^\pm = b_{\pm}(\lambda_k^\pm)$ and $\tilde{b}_k^\pm = b_{\pm}(\lambda_k^\mp)$. In addition the relation $b^-(\lambda, t) = (b^+(\lambda, t))^*$ gives:

$$
b^-(\lambda^+, t) = (b^+(\lambda^+, t))^*,
$$

or with the notations just introduced:

$$
b_k^\pm(t) = \tilde{b}_k^\pm(t),
\tilde{b}_k^\pm(t) = b^*_{k+N_2}(t),
$$

where $s = 1, \ldots, N_1$ and $r = N_1 + \ldots, N_1 + N_2$.

Now we can consider the fact that:

$$
det T(\lambda, t) \equiv a^+(\lambda)a^-(\lambda) + b^+(\lambda, t)b^-(\lambda, t) = 1,
$$

which for finite support potentials holds true for all $\lambda$. Putting $\lambda = \lambda_k^\pm$ into the left hand side of eq. (VI.33) we immediately find that:

$$
b_k^\pm(t)b_k^\pm(t) = 1,
\tilde{b}_k^\pm(t)b_k^\pm(t) = 1,
$$

or

$$
b_k^\mp(t) = \frac{1}{b_k^\pm(t)},
\tilde{b}_k^\mp(t) = \frac{1}{b_k^\pm(t)},
$$

$$
b_k^\pm(t) = \frac{1}{\tilde{b}_k^\pm(t)},
\tilde{b}_k^\pm(t) = \frac{1}{\tilde{b}_k^\pm(t)}.
$$

Now we have to take the limit when the support of the potential goes to infinity. In this case the functions $b_{\pm}(\lambda)$ cannot be extended off the real axis and $b_k^\pm$ and $\tilde{b}_k^\pm$ are just some constants. However the relations (VI.32), (VI.34) and (VI.35) still remain valid.

Let us now analyze the effect of the nonlocal involution $A$ on the trace identities, see Subsection IV.3. Our first remark is that the involution will not change the formal expressions of the integrals of motion $C_k$ in terms of $q_\pm(x,t)$. Indeed, we just have to replace in them $q_\pm(x,t)$ by $u(x,t)$ and $q_\pm(x,t)$ by $u^*(x,t)$. However, the expressions for $C_k$ in terms of the scattering data (or the action-angle variables) will change substantially in view of Lemma 2. Skipping the details we obtain:

$$
C_{2m} = -\int_0^\infty d\mu \mu^{2m-1}\eta_0(\mu) + \frac{(-1)^m}{4m^2m} \sum_{s=1}^{N_1} \pm (\eta^\pm_s)^{2m},
$$

or with the notations just introduced:

$$
C_{2m} = -\int_0^\infty d\mu \mu^{2m-1}\eta_0(\mu) + \frac{(-1)^m}{4m^2m} \sum_{s=1}^{N_1} \pm (\eta^\pm_s)^{2m-1} + \frac{(-1)^m}{4m^2m} \sum_{r=1}^{N_1} \pm (\eta^\pm_r)^{2m-1}.
$$

Note that all ‘even’ conserved quantities $C_{2m}$ are purely imaginary, while all ‘odd’ ones $C_{2m-1}$ take real values.

**Theorem 3.** The set of the action-angle variables for the nonlocal NLS in the case of involution $A$ is given by:

$$
\kappa(\lambda, t) = \frac{1}{2} \ln \frac{b_0^+(\lambda, t)}{b_0^-(\lambda, t)},
\eta(\lambda) = \frac{1}{\pi} \ln \left( (a^+a^-)(\lambda) \right) = \eta^*(\lambda),
$$

$$
\eta^\pm_s = \mp 2i\lambda^\pm_s = 2n^\pm_s, \quad \kappa^\pm_s(t) = \pm i \arg b^\pm_s(t),
$$

$$
\eta^\pm_r = \mp 2i\lambda^\pm_r = 2n^\pm_r, \quad \kappa^\pm_r(t) = \pm \ln |b^\pm_r(t)| \pm i \arg b^\pm_r(t),
$$

$$
\kappa^\pm_{r+N_2}(t) = \mp \ln |b^\pm_r(t)| \pm i \arg b^\pm_r(t) = -\kappa^\mp_r(t),
$$

where $\lambda \in \mathbb{R}$ runs over the continuous spectrum of $L$, $s = 1, \ldots, N_1$ and $r = N_1 + 1, \ldots, N_1 + N_2$. 

In order to express the canonical symplectic form $\Omega_0$ in terms of the action-angle variables it is enough to take 
\begin{equation}
\kappa(\lambda, t) = \kappa_0(\lambda, t) + i \kappa_1(\lambda, t), \quad \eta(\lambda) = \eta_0(\lambda) + i \eta_1(\lambda),
\end{equation}
with
\begin{align*}
\kappa_0(\lambda, t) &= \frac{1}{2} \ln \left| \frac{b^+(\lambda, t)}{b^-(\lambda, t)} \right|, \\
\kappa_1(\lambda, t) &= \frac{1}{2} \left( \arg \left( b^+(\lambda, t) \right) - \arg \left( b^-(\lambda, t) \right) \right), \\
\eta_0(\lambda) &= -\frac{1}{\pi} \ln \left| a^+ a^- (\lambda) \right|, \\
\eta_1(\lambda) &= -\frac{1}{\pi} \left( \arg(a^+(\lambda)) + \arg(a^- (\lambda)) \right).
\end{align*}

For the expansion of $\sigma_3 \delta q(x)$ we obtain:
\begin{equation}
\sigma_3 \delta q(x) = \int_{-\infty}^{\infty} d\lambda \left( Q(x, \lambda) \delta \eta(\lambda) - P(x, \lambda) \delta \kappa(\lambda) \right)
\end{equation}
\begin{align*}
&+ i \sum_{r=N_1+1}^{N_1+N_2} \left( Q_r^+(x) \delta \eta_r^+ - P_r^+(x) \delta \kappa_r^+ \right) \\
&+ \sum_{r=N_1+1}^{N_1+N_2} \left( Q_{r+N_2}^-(x) \delta \eta_{r+N_2}^- - P_{r+N_2}^-(x) \delta \kappa_{r+N_2}^- \right) \\
&+ i \sum_{s=1}^{N_1} \left( Q_s^{+\prime}(x) \delta \eta_s^+ - P_s^{+\prime}(x) \delta \kappa_s^+ \right). \tag{VI.42}
\end{align*}

In order to express the canonical symplectic form $\Omega_0$ in terms of the action-angle variables it is enough to take 
the skew-scalar product of $\frac{i}{2} \sigma_3 \delta q$ with both sides of eq. (VI.42) and take into account the second line of Table II. The result is
\begin{equation}
\Omega(\lambda) = \frac{i}{2} \left[ \sigma_3 \delta q \wedge \sigma_3 \delta q \right]
\end{equation}
\begin{align*}
&= i \int_{-\infty}^{\infty} d\lambda \delta \eta(\lambda) \wedge \delta \kappa(\lambda) + i \sum_{s=1}^{N_1} \delta \eta_s^+ \wedge \delta \kappa_s^+ \\
&+ \sum_{r=N_1+1}^{N_1+N_2} \delta \eta_r^+ \wedge \delta \kappa_r^+ + \delta \eta_{r+N_1}^\pm \wedge \delta \kappa_{r+N_1}^\pm \\
&- 2 \int_{-\infty}^{\infty} d\lambda \left( \delta \eta_0(\lambda) \wedge \delta \kappa_1(\lambda) + \delta \eta_1(\lambda) \wedge \delta \kappa_0(\lambda) \right)
\end{align*}
\begin{align*}
&= -i \sum_{s=1}^{N_1} \delta \eta_s^+ \wedge \delta \arg b_s \\
&+ \sum_{r=N_1+1}^{N_1+N_2} \left( \delta \eta_r^+ \wedge \delta \kappa_r^+ - \delta \eta_s^+ \wedge \delta \kappa_s^+ \right), \tag{VI.43}
\end{align*}
where we made use of eqs. (VI.39).

Now the proof follows from the following easy observations:
\begin{enumerate}
\item i) the equation:
\begin{equation}
\Omega(\lambda)(i\sigma_3 q_0, \cdot) = \delta H_0 \tag{VI.44}
\end{equation}
where $H_0 = -2Cq$ reproduces the time-dependence of the scattering data, see eq. (IV.7);
\item ii) The symplectic form $\Omega_0$ is canonical with respect to the set of action-angle variables $\{\eta(\lambda), \kappa(\lambda)\}$;
\item iii) $H_{\text{NLNS}}$ depends only on the action-type variables $\eta(\lambda)$.
\end{enumerate}

This facts can be viewed as natural generalization of the notion of AA variables to the infinite-dimensional case.
\begin{proof}
\end{proof}

The ‘even’ hierarchy of symplectic forms is:
\begin{align*}
\Omega(2m) &= \frac{i}{2} \left[ \sigma_3 \delta q \wedge \Lambda^{2m} \sigma_3 \delta q \right] \\
&= 2 \int_0^\infty d\lambda \lambda^{2m} \left( \delta \eta(\lambda) \wedge \delta \kappa(\lambda) \right)
\end{align*}
\begin{align*}
&+ c_{1,m} \sum_{r=N_1+1}^{N_1+N_2} \left( 2m+1 \delta \kappa_r^+ \delta \kappa_r^+ - \delta \eta_r^+ \delta \eta_r^+ \right) \\
&+ i \sum_{s=1}^{N_1} \left( \delta \eta_s^+ \delta \eta_s^+ \right) \tag{VI.45}
\end{align*}
where $c_{1,m} = (-1)^m 4^{-m} (2m+1)$. We end with the examples of the simplest NLEE satisfying the nonlocal reduction. Their dispersion laws are given by even functions of $\lambda$ with real coefficients.
\begin{equation}
f_{\text{nLNS}}(\lambda) = -\lambda^2, \quad f_{\text{nLNS4}}(\lambda) = -4\lambda^4.
\end{equation}

\textbf{VI.3. The nonlocal involution B:}
\begin{equation}
q_-(x, -t) = (q_+)^*(x, t) = v(x, t)
\end{equation}

As mentioned above, the involution $A)$ is compatible with the NLS equation and also with all higher NLS equations whose dispersion law $f(\lambda)$ is an even function of $\lambda$. However the involution $A)$ is not compatible with the cmKdV equation
\begin{equation}
\frac{\partial v}{\partial t} + \frac{\partial^3 v}{\partial x^3} + 6v(x, t)v(-x, -t) \frac{\partial v}{\partial x} = 0
\end{equation}
and all higher cmKdV-like equations whose dispersion law $f(\lambda)$ is an odd function of $\lambda$. These equations allow reduction $B)$
\begin{equation}
q_-(x, -t) = (q_+)^*(x, t) = v(x, t),
\end{equation}
which requires simultaneous change of the sign of both $x$ and $t$. This involution leads to:
\begin{equation}
U(x, t, \lambda) = \sigma_1 \left( U(-x, -t, -\lambda^*) \right)^* \sigma_1^{-1}, \quad \sigma_1 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}. \tag{VI.48}
\end{equation}

Again the involution on the potential $q(x, t)$ can be extended to an involutive automorphism of the affine Lie
a) In the algebra in which $U(x, t, \lambda)$ and $V(x, t, \lambda)$ are taking values, all fundamental solutions of $L$ are also restricted by $\det T(t, \lambda) = 1$. The Jost solutions must satisfy \[ \psi^-(x, t, \lambda) = \sigma_1^{-1} \left( \phi^-(x, -t, -\lambda^*) \right)^*, \] \[ \psi^+(x, t, \lambda) = \sigma_1 \left( \phi^+(x, -t, -\lambda^*) \right)^*, \] (VI.49) or in compact form:
\[ \psi(x, t, \lambda) = \sigma_1 \left( \phi(-x, -t, -\lambda^*) \right)^* \sigma_1^{-1}. \] (VI.50)

From eq. (II.2) we derive the following constraint for the scattering matrix:
\[ T(\lambda, t) = \sigma_1 \left( \tilde{T}(-\lambda^*, -t) \right)^* \sigma_1^{-1}; \] (VI.51)
similarly from eq. (II.4) for the FAS we find:
\[ \chi^+(x, t, \lambda) = \sigma_1 \left( \chi^+(x, -t, -\lambda^*) \right)^* \sigma_1^{-1}, \] \[ \chi^-(x, t, \lambda) = \sigma_1 \left( \chi^-(x, -t, -\lambda^*) \right)^* \sigma_1^{-1}. \] (VI.52)

Under this involution the dispersion law of the NLEIs must satisfy:
\[ f(\lambda) = -(f(-\lambda^*))^*, \quad f(\lambda) = \sum_{k>0} f_{2k+1} \lambda^{2k+1}, \] (VI.53)
which means that $f(\lambda)$ must be an odd polynomial of $\lambda$ with real coefficients. In particular, the involution $A$ is compatible with the mKdV eq., because its dispersion law is $f_{\text{mKdV}}(\lambda) = -4 \lambda^3$. The eq. (VI.51) in components reads:
\[ a^+(\lambda) = (a^+(\lambda^*)^*)^*, \quad a^-(\lambda) = (a^-(\lambda^*)^*)^*, \] \[ b^-(t, \lambda) = (b^+(t, -\lambda^*)^*)^*. \] (VI.54)

Note that for $a^+(\lambda)$ and $a^-(\lambda)$ the constraints are the same as for the involution $A$ – indeed $a^-(\lambda)$ are time-independent. That is why of the considerations in the previous Subsection are directly applicable also for involution $B$). In particular this involves Corollary 2, Remark 7 and Lemma 2). Of course the restrictions on $\tilde{b}_k^\pm(t)$ and $\tilde{b}_k^\pm(t)$ must be modified into:
\[ b^-(\lambda^*, t) = (\tilde{b}^+(\lambda^*, -, t)^*), \] \[ b^+(\lambda^*, t) = (\tilde{b}^+(\lambda^*, -, t)^*), \] \[ b^-(\lambda^*, t) = (\tilde{b}^+(\lambda^*, -, t)^*), \] \[ b^+(\lambda^*, t) = (\tilde{b}^+(\lambda^*, -, t)^*), \] (VI.55)
or with the above notations:
\[ b^+_s(t) = \tilde{b}^+_s(-t), \] \[ b^-_s(t) = \tilde{b}^-_s(-t), \] \[ \tilde{b}^+_s(t) = \tilde{b}^-_s(-t), \] \[ \tilde{b}^-_s(t) = \tilde{b}^+_s(-t), \] (VI.56)
where $s = 1, \ldots, N_1$ and $r = N_1 + 1, \ldots, N_1 + N_2$. In addition, from the fact that $\det T(t, \lambda) = 1$ we get: that:
\[ b^+_s(t)\tilde{b}^+_s(t) = 1, \quad b^-_s(t)\tilde{b}^-_s(t) = 1, \] (VI.57)
and
\[ b^+_s(t) = \frac{1}{b^+_s(-t)}, \quad \tilde{b}^+_s(t) = \frac{1}{\tilde{b}^+_{s+}(t)}, \] (VI.58)

**Theorem 4.** In the case of involution $B$ the set of action-angle variables for the nonlinear cmKdV-like equations is given by:
\[ \kappa(\lambda, t) = \frac{1}{2} \ln \frac{b^+(\lambda, t)}{b^-(-\lambda, -t)} = \kappa^*(-\lambda, -t), \] (VI.59a)
\[ \eta(\lambda) = -\frac{1}{\pi} \ln (a^+(\lambda^*)) = \eta^*(-\lambda), \] (VI.59b)
\[ \eta^*_s = \pm 2i \lambda^*_r = \pm 2i \delta q^*_s, \quad \kappa^*_s(t) = \pm i \arg b^*_s(t), \] (VI.59c)
\[ \kappa^*_s(t) = \mp \lambda^*_r \arg \tilde{b}^*_s(t) \pm i \arg b^*_s(t) = \kappa^*_s(-t), \] (VI.59d)
where $\lambda \in \mathbb{R}$ runs over the continuous spectrum of $L$, $s = 1, \ldots, N_1$ and $r = N_1 + 1, \ldots, N_1 + N_2$.

**Proof.** The proof is similar to the one of Theorem 3. The only difference is that now we have to apply involution $B$ on the symplectic forms $\Omega_{in}$ and on the scattering data. The expressions for the action variables are $t$-independent, so they are the same as in (VI.41). Again we will split $\kappa(\lambda)$ and $\eta(\lambda)$ into real and imaginary parts:
\[ \kappa(\lambda) = \kappa_0(\lambda) + i \kappa_1(\lambda), \quad \eta(\lambda) = \eta_0(\lambda) + i \eta_1(\lambda), \] (VI.60)
with
\[ \kappa_0(\lambda) = \frac{1}{2} \ln \left| \frac{b^+(\lambda, t)}{b^-(\lambda, -t)} \right| = \frac{1}{2} \ln \left| \frac{b^+(\lambda^*, t)}{b^-(\lambda^*, -t)} \right|, \] \[ \kappa_1(\lambda) = \frac{1}{2} \left( \arg(b^+(\lambda, t)) - \arg(b^-(\lambda, -t)) \right), \] (VI.61)
\[ = \frac{1}{2} \left( \arg(b^+(\lambda, t)) + \arg(b^+(\lambda^*, -t)) \right). \]

Similarly as above we express the canonical symplectic form $\Omega_0$ in terms of the action-angle variables as follows:
\[ \Omega_{in} = \frac{i}{2} \left[ \sigma_3 \delta q \wedge \sigma_3 \delta q \right] \] \[ = -\frac{1}{2} \int_0^\infty d\lambda \left( \delta \eta_0(\lambda) \wedge \delta \kappa_1(\lambda) + \delta \eta_1(\lambda) \wedge \delta \kappa_0(\lambda) \right) \] \[ - \sum_{s=1}^{N_1} \delta \eta^s \wedge \delta \arg b^s \] \[ + \frac{N_1+N_2}{r(N_1+1)} \left( \delta \kappa^s_r \wedge \delta \kappa^s_r \wedge \delta \kappa^s_r \wedge \delta \kappa^s_r \right), \] (VI.62)
where we made use of eqs. (VI.39).

Now, the complete integrability follows from the easy observations:

i) the equation:
\[ \Omega(0)(i\sigma_3q_0, \cdot) = \delta H(0) \]  \hspace{1cm} (VI.63)

where \( H(0) = 16iC_4 \) coincides with the cmKdV;

ii) The symplectic form \( \Omega(0) \) is canonical with respect to the set of action-angle variables \( \{ \eta(\lambda), \kappa(\lambda) \} \);

\( H(0) \) depends only on the action-type variables \( \eta(\lambda) \).

iv) The set of symplectic basis is complete.

We end by expressing also the ‘odd’ hierarchy of symplectic forms in terms of the action-angle variables:

\[ \Omega(2m-1) \equiv \frac{i}{2} \left[ [\sigma_3 \delta q \wedge \Lambda^{2m-1} \sigma_3 \delta q] \right] \]

\[ \begin{align*}
= 2i \int_0^\infty d\lambda \lambda^{2m-1} \left( \delta \delta_0(\lambda) \wedge \delta \eta_0(\lambda) - \delta \kappa_2(\lambda) \wedge \delta \eta_1(\lambda) \right) \\
+ ic_m \sum_{s=1}^{N_1} \left( \pm \delta (\arg b_{r}^s) \wedge \delta \eta_{2s+1}^r \right) \\
+ 2ic_m \sum_{r=N_1+1}^{N_1+N_2} \left( \delta (|b_r^s|) \wedge \delta q_{1,r}^+ + \delta (arg b_r^s) \wedge \delta \eta_{0,r}^+ \right), \\
\end{align*} \]

(VI.64)

where

\[ c_{1,m} = \frac{(-1)^m}{4^m m!} \quad y_{0,m}^\pm + iy_{1,m}^\pm = (2s_m^+ + 2ip_r^+)^{2m}. \]

\[ \Delta \]

VII. DISCUSSION AND CONCLUSIONS

We have proved that the nonlocal equations from the hierarchy of the nonlocal NLS equations are infinite-dimensional, completely integrable systems. The proof is based on the so-called completeness relation for the squared solutions of the Lax operator and the symplectic basis, which allows one to map directly the variation of the potential \( \sigma_3 \delta q(x) \) into the variations of the action-angle variables.

The spectral properties of the Lax operator (see Corollary 2 and Remark 7) allow us to conclude that the hierarchy of non-local equations has two types of soliton solutions, see [4, 20]. Their properties and interactions will be analyzed elsewhere.

The corresponding action-angle variables are parametrized by the scattering data of \( L \). More specifically we have complex-valued action variables \( \eta(\lambda) \) and \( \kappa(\lambda) \), related to the continuous spectrum of \( L \) (i.e., for \( \lambda \notin \mathbb{R} \)) and two finite sets of action-angle variables: \( \eta_2^\pm \) and \( \kappa_2^\pm \) related to the solitons of first type (\( s = 1, \ldots, N_1 \)) and \( \eta_3^\pm \), \( \eta_3^\pm* \) and \( \kappa_3^\pm \), \( \kappa_3^\pm* \) related to the solitons of second type (\( r = N_1 + 1, \ldots, N_1 + N_2 \)).

These action-angle variables are universal in the sense that they render canonical each of the symplectic forms in the hierarchy \( \Omega(m) \). The action-angle variables here are understood in the sense that the action variables are \( t \)-independent, while the angle variables depend linearly on \( t \). The requirement that the angle variables are in the interval \([0, 2\pi]\) cannot be ensured for all \( \kappa(\lambda) \) and \( \kappa_2^\pm \).

ACKNOWLEDGEMENTS

This work was supported in part by the U.S. Department of Energy. We thank an anonymous referee for careful reading of the manuscript and for useful suggestions.
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