TRANSFERENCE OF LOCAL TO GLOBAL $L^2$ MAXIMAL ESTIMATES FOR DISPERSIVE PARTIAL DIFFERENTIAL EQUATIONS

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Abstract. In this paper we give an elementary proof for transference of local to global maximal estimates for dispersive PDEs. This is done by transferring local $L^2$ estimates for certain oscillatory integrals with rough phase functions, to the corresponding global estimates. The elementary feature of our approach is that it entirely avoids the use of the wave packet techniques which are quite common in this context, and instead is based on scalings and classical oscillatory integral estimates.

1. Introduction

In the study of the Cauchy problem

$$
\begin{cases}
i\partial_t u(t, x) + \phi(D)u(t, x) = 0, \\ u(0, x) = u_0(x) \in H^s, \text{ for } s > 0,
\end{cases}
$$

for dispersive equations, oscillatory integral operators of the form

$$
T_t f(x) = \int_{\mathbb{R}^n} e^{i\xi \cdot x + it\phi(\xi)} \hat{f}(\xi) \, d\xi,
$$

play a crucial role. Here $\phi$ is a positively homogeneous phase function of degree $a$ that satisfies $|\partial^\alpha \phi(\xi)| \lesssim |\xi|^{a-|\alpha|}$ outside the origin and $\hat{\phi}(D)u(t, \xi) = \phi(\xi)\hat{u}(t, \xi)$. We denote by $H^s$ the usual $L^2$-based Sobolev spaces.

In the theory of dispersive partial differential equations it is a classical fact that a local maximal function estimate of the type

$$
\| \sup_{0 < t < 1} |T_t f| \|_{L^2(B(0, 1))} \leq C \| f \|_{H^s(\mathbb{R}^n)},
$$

would imply that the solution $u(x, t)$ of (1) (if it exists) converges pointwise almost everywhere to $u_0$ as $t \to 0$. The global counterpart of (2) i.e.

$$
\| \sup_{0 < t < 1} |T_t f| \|_{L^2(\mathbb{R}^n)} \leq C \| f \|_{H^s(\mathbb{R}^n)},
$$

is also important for the study of the well-posedness of the Cauchy problem (1).

It has been a considerable amount of activity regarding the validity of (2) and (3) for various dispersive equations. For example one should mention the works of M. Cowling [4], B. Walther [11] in the case of $\phi(\xi) = |\xi|$ (i.e. the wave operator $e^{it\sqrt{-\Delta}}$), papers by P. Sjölin [11], [12], [13], [14] concerning $\phi(\xi) = |\xi|^a$, with $a > 1$, and the papers by L. Carleson [7], L. Vega [15], S. Lee [5] and J. Bourgain [1] concerning $\phi(\xi) = |\xi|^s$ (i.e. the Schrödinger operator $e^{it\Delta}$). We should also mention the recent result of X. Du, L. Guth and X. Li in [6], where they establish the estimate (3) in the range $s > 1/3$ for the Schrödinger maximal operator in dimension 2. According to a result of Bourgain [2], for the Schrödinger operator in $n$ dimensions, (2) can be valid only if $s \geq \frac{n}{2(n+1)}$, and so the aforementioned result in [6] is sharp up to the end point. For the oscillatory integrals with $\phi(\xi) = \xi^3$, C. Kenig, G. Ponce, and L. Vega [7], in connection to their seminal work on

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Korteweg-de Vries equations, established estimates of the form \((3)\) for \(s > \frac{3}{4}\).

In [10], K. Rogers showed that in fact the local and global estimates \((2)\) and \((3)\) are equivalent in the following precise sense: if \((2)\) is valid for \(K\)orteweg-de Vries equations, established estimates of the form \((3)\) for oscillatory integrals are used. Thus no tools from the technical machinery of the wave-packet analysis one can prove this, just using elementary methods based on simple scalings and classical estimates for oscillatory integrals. Hence one is led to use other methods that ultimately stem from T. Wolff’s paper [18].

In this paper, we confine ourselves to the implication local to global and show that in this case, one can prove this, just using elementary methods based on simple scalings and classical estimates for oscillatory integrals. Thus no tools from the technical machinery of the wave-packet analysis are used.

Our main result is that the validity of \((2)\) for \(s > s_0\) yields the validity of \((3)\) for \(s > a s_0\), for oscillatory integrals \(T_t\) with \(\phi\) positively homogeneous of degree \(a\) with \(a \geq 1\) (i.e. \(\phi(r \xi) = r^a \phi(\xi)\), \(r > 0\)), and satisfying
\[
|\partial^\alpha \phi(\xi)| \lesssim |\xi|^{\alpha-a}\text{, }\xi \in \mathbb{R}^n \setminus \{0\}\text{ and all multi – indices } \alpha,
\]
and
\[
\min_{|\xi|=1} |\nabla \phi(\xi)| > 0.
\]

Moreover, this result is achieved via rather elementary means. Here it is important to mention that we actually manage to obtain endpoint results at all steps of the proof except the very last one, i.e. in the proof of Proposition 2.5 which is the source of the “\(\varepsilon\)-loss” in the final conclusion. However, we believe that removing the \(\varepsilon\) behoves one to use more advanced methods that won’t fall into the scope of an elementary proof.

The paper is essentially self-contained and is organised as follows. In Section 2 we use the Kolmogorov-Silverstev-Plessner stopping time argument to “linearise” the problem and show in Theorem 2.2 that local estimates yield global ones. The proof of Theorem 2.2 is in turn divided into three propositions (Propositions 2.6, 2.7 and 2.8).

In what follows, we shall omit all the constants that appear in various estimates, unless otherwise stated. In doing that we will use the notation \(A \lesssim B\) which should be interpreted as \(A \leq CB\) where \(C\) is a constant. The dependence of \(C\) on various other parameters will be clear from the context.

2. LOCAL ESTIMATES IMPLY GLOBAL ESTIMATES

In what follows we shall denote by \(H^s\) the Sobolev space of all tempered distributions \(f\) for which \((\xi)^s \hat{f}(\xi) \in L^2(\mathbb{R}^n)\), where \((\xi) := (1 + |\xi|^2)^{1/2}\). We shall also denote the Schwartz class by \(S(\mathbb{R}^n)\) and the class of smooth compactly supported functions by \(C_0^\infty(\mathbb{R}^n)\).

We consider the operator
\[
T_t f(x) = \int_{\mathbb{R}^n} e^{ix \cdot \xi + it \phi(\xi)} \hat{f}(\xi) \, d\xi,
\]
defined a-priori for \(f \in \mathcal{S}(\mathbb{R}^n)\), where \(\phi\) is a function that is positively homogeneous of degree \(a\) with \(a \geq 1\), and satisfies
\[
|\partial^\alpha \phi(\xi)| \lesssim |\xi|^{\alpha-a}\text{, }\xi \in \mathbb{R}^n \setminus \{0\}\text{ and all multi – indices } \alpha,
\]
and
\[
\min_{|\xi|=1} |\nabla \phi(\xi)| > 0.
\]

The main goal of this paper is to establish the following result:

**Theorem 2.1.** Let \(s_0 > 0\), and \(T_t\) be defined as above with the phase function satisfying \((4)\) and \((5)\). Then the local bound
\[
\| \sup_{0 < t < 1} |T_t f| \|_{L^2(B(0,1))} \lesssim \| f \|_{H^s(\mathbb{R}^n)}, \quad s > s_0, \quad f \in \mathcal{S}(\mathbb{R}^n),
\]
implies the global bound
\[
\| f \|_{L^2(\mathbb{R}^n)} \lesssim \| f \|_{H^s(\mathbb{R}^n)}, \quad s > s_0, \quad f \in \mathcal{S}(\mathbb{R}^n).
\]
implies the global bound
\[ \| \sup_{0 < t < 1} |T_t f| \|_{L^2(\mathbb{R}^n)} \lesssim \| f \|_{H^s(\mathbb{R}^n)}, \quad s > a s_0, \quad f \in S(\mathbb{R}^n). \]

It is often more convenient to work instead with an equivalent “linearized version” of the maximal operator given by
\[ T_{t(x)} f(x) := \int_{\mathbb{R}^n} e^{ix \cdot \xi + it(x) \phi(\xi)} \hat{f}(\xi) d\xi, \quad x \in \mathbb{R}^n, \]
defined a-priori on Schwartz class of functions, for any measurable function \( 0 \leq t(x) \leq 1 \). Indeed it is well known that the linearized estimates imply sup-norm estimates by the classical Kolmogorov-Seliverstov-Plessner stopping time argument. On the other hand, trivially, for any measurable \( t(x) \in [0, 1] \) and any \( f \in S(\mathbb{R}^n) \) one has that for all \( x \),
\[ |T_{t(x)} f(x)| \leq \sup_{0 < t < 1} |T_t f(x)|. \]

Therefore, any norm estimate for the expression on the right hand side implies the one for term on the left hand side. Thus, from now on we shall put our efforts in proving the following theorem:

**Theorem 2.2.** Let \( s_0 > 0 \) and \( 0 \leq t(x) \leq 1 \) be a measurable function. Then, the linearized local bound
\[ \| T_{t(x)} f \|_{L^2(B(0,1))} \lesssim \| f \|_{H^s(\mathbb{R}^n)}, \quad s > s_0, \quad f \in S(\mathbb{R}^n), \]
implies the linearized global bound
\[ \| T_{t(x)} f \|_{L^2(\mathbb{R}^n)} \lesssim \| f \|_{H^s(\mathbb{R}^n)}, \quad s > a s_0, \quad f \in S(\mathbb{R}^n). \]

It is absolutely crucial to emphasize that in these estimates and all the forthcoming ones, the constants of the estimates are independent of the measurable functions that are involved in the definition of the operators.

The proof of Theorem 2.2 is divided in three steps, that we present below as separate results (Propositions 2.6, 2.7 and 2.8).

At this point we shall introduce the space \( S_A(\mathbb{R}^n) \) consisting of all those functions in the Schwartz class whose frequency is supported in the unit annulus; that is,\n\[ S_A(\mathbb{R}^n) := \left\{ f \in S(\mathbb{R}^n) : \text{supp} \hat{f} \subset A(1) \right\}, \]
where \( A(R) := \{ R/2 \leq |\xi| \leq 2R \}, R > 0 \). In the proofs of the next results it will be crucial to use the following partition of the unity. We start by choosing a radial function \( \chi \in C_c^\infty(\mathbb{R}^n) \) such that \( 0 < \chi \leq 1 \) in \( B(0,2) \), \( \chi \equiv 1 \) in \( B(0,1) \) and \( \chi \equiv 0 \) in \( \mathbb{R}^n \setminus B(0,2) \). Next, we set
\[ \lambda(\xi) := \chi(\xi) - \chi(2\xi), \quad \xi \in \mathbb{R}^n, \]
which is radial and supported in the annulus \( \{ 1/2 \leq |\xi| \leq 2 \} \) and does not vanish at any isolated point inside its support. Finally, we define
\[ \psi_0(\xi) := \chi(\xi), \quad \psi_k(\xi) := \lambda(2^{-k} \xi), \quad k \geq 1, \]
Observe that \( \text{supp} \psi_k \subset \{ 2^{k-1} \leq |\xi| \leq 2^{k+1} \}, k \geq 1, \)
\[ \text{supp} \psi_k \cap \text{supp} \psi_j = \emptyset, \quad |k - j| > 1, \]
and
\[ \sum_{k \geq 0} \psi_k(\xi) = 1, \quad \xi \in \mathbb{R}^n. \]

In dealing with the low frequency portions of the oscillatory integral operators \( T_{t(x)} f(x) \) the following lemma will be useful.

**Lemma 2.3.** Assume that \( t(x) \) is a measurable function with \( 0 \leq t(x) \leq 1 \), \( \chi(\xi) \in C_c^\infty(\mathbb{R}^n) \) is a smooth cut-off function supported in a neighborhood of the origin, and let \( \phi \) be a positively homogeneous of degree \( a \geq 1 \) phase function satisfying (4). Consider the operator
\[ R_{t(x)} f(x) := \int_{\mathbb{R}^n} \chi(\xi) e^{ix \cdot \xi + it(x) \phi(\xi)} \hat{f}(\xi) d\xi, \quad x \in \mathbb{R}^n. \]
Then for \( 1 \leq p \leq \infty \) one has
\[ \| R_{t(x)} f \|_{L^p(\mathbb{R}^n)} \lesssim \| f \|_{L^p(\mathbb{R}^n)}. \]
Proof. Since
\[ R_t(x)f(x) = \int_{\mathbb{R}^n} K(x,y) f(y) \, dy \]
with
\[ K(x,y) := \frac{1}{(2\pi)^n} \int_{\mathbb{R}^n} \chi(\xi) e^{i(x-y) \cdot \xi + it(x) \phi(\xi)} \, d\xi, \]
the result would follow from Schur’s lemma, if we manage to show that
\[ \sup_{x \in \mathbb{R}^n} \|K(x,\cdot)\|_{L^1(\mathbb{R}^n)} < \infty \quad \text{and} \quad \sup_{y \in \mathbb{R}^n} \|K(\cdot,y)\|_{L^1(\mathbb{R}^n)} < \infty. \]

The proof is divided into two cases. First consider the case when \( a \) (the degree of homogeneity of \( \phi \)) is equal to one. In this case we have for any multi-index \( \alpha \) with \( |\alpha| = n \) and \( |\alpha| = n + 1 \)
\[ \sup_{\xi \in \mathbb{R}^n \setminus \{0\}} |\xi|^{|\alpha|-1} \|\partial_\xi^\alpha (e^{it(x) \phi(\xi)} \chi(\xi))\|_{L^\infty(\mathbb{R}^n)} < +\infty. \]
Therefore \[ \text{Lemma 1.17} \] (actually its proof) yields that for all \( 0 \leq \varepsilon < 1 \) one has \( |K(x,y)| \lesssim \langle x-y \rangle^{-n-\varepsilon} \), where the hidden constant on the right hand side of this estimate doesn’t depend on \( t(x) \). This kernel estimate obviously implies the Schur-type estimates above.

For the case \( a > 1 \) we claim that \( |K(x,y)| \lesssim \langle x-y \rangle^{-n-1} \), where once again the hidden constant on the right hand side of this estimate doesn’t depend on \( t(x) \). Since \( |K(x,y)| \lesssim 1 \), it is enough to show that that \( |K(x,y)| \lesssim |x-y|^{-n-1} \). To this end we split the kernel into \( K(x,y) = K_1(x,y) + K_2(x,y) \) where
\[ K_1(x,y) := \frac{1}{(2\pi)^n} \int_{\mathbb{R}^n} e^{i(x-y) \cdot \xi} \chi(\xi) \, d\xi, \]
and
\[ K_2(x,y) := \frac{1}{(2\pi)^n} \int_{\mathbb{R}^n} e^{i(x-y) \cdot \xi} \chi(\xi) (e^{it(x) \phi(\xi)} - 1) \, d\xi. \]
Since \( \chi \in C_c^\infty(\mathbb{R}^n) \), we have that \( |K_1(x,y)| \lesssim |x-y|^{-N} \), for all \( N \geq 0 \).

Given \( 0 < \delta < 1 \), we introduce a smooth function \( \rho \) with \( 0 \leq \rho \leq 1 \) such that \( \rho(\xi) = 1 \) when \( |\xi| \geq 2 \) and \( \rho(\xi) = 0 \) when \( |\xi| \leq 1 \). Now setting
\[ K_{2,\delta}(x,y) := \frac{1}{(2\pi)^n} \int_{\mathbb{R}^n} e^{i(x-y) \cdot \xi} \chi(\xi) \rho(\xi) \chi(\xi/\delta) (e^{it(\xi) \phi(\xi)} - 1) \, d\xi, \]
Lebesgue’s dominated convergence theorem yields that \( K_2(x,y) = \lim_{\delta \to 0} K_{2,\delta}(x,y) \).

If we integrate by parts \( n + 1 \) times in the integral defining \( K_{2,\delta}(x,y) \) we obtain
\[ |K_{2,\delta}(x,y)| \lesssim |x-y|^{-n-1} \sum_{|\alpha| + |\beta| + |\gamma| = n+1} \delta^{-|\gamma|} \int_{\mathbb{R}^n} |\partial_\xi^\alpha (e^{it(\xi) \phi(\xi)} - 1) | |\partial_\xi^\beta \chi(\xi)|| |\partial_\xi^\gamma (\rho(\xi/\delta))| \, d\xi. \]

At this point we observe that by the conditions on \( t(x) \) and \( \phi \), we have for all multi-indices \( \alpha \)
\[ |\partial_\xi^\alpha (e^{it(\xi) \phi(\xi)} - 1) | \lesssim |\xi|^{n-|\alpha|} \]
uniformly in \( t(x) \), for \( \xi \) in the support of \( \chi \). Therefore since \( a > 1 \), if
\( \gamma = 0 \) then the corresponding term in the sum above is bounded by
\[ |x-y|^{-n-1} \sum_{|\alpha| + |\beta| + |\gamma| = n+1} \int_{\text{supp} \chi} |\xi|^{n-|\alpha|} \, d\xi \lesssim |x-y|^{-n-1}. \]
On the other hand, those terms with \( |\gamma| \geq 1 \), are bounded by
\[ |x-y|^{-n-1} \sum_{|\alpha| + |\beta| + |\gamma| = n+1} \int_{|\xi| \leq 2\delta} |\xi|^{a-|\alpha|} \delta^{-|\gamma|} \, d\xi \lesssim |x-y|^{-n-1} \delta^{-a-1}. \]
Taking the limit as \( \delta \) goes to zero, we obtain
\[ |K_2(x,y)| \lesssim |x-y|^{-n-1}. \]

This establishes the desired kernel estimate, and once again Schur’s lemma, enable us to deduce the \( L^p \) boundedness of operator \( R_t(x) \).
Remark 2.4. As a matter of fact, the case $a > 1$ could also be dealt with, following the same argument as in the case of $a = 1$. However, since the argument presented above, which is similar to that in [12], yields a better decay, we provided a separate proof in order to maintain a more self-contained presentation.

For our forthcoming estimates we would also need the following version of the non-stationary phase lemma, whose proof can be found in [9] Lemma 3.2.

Lemma 2.5. Let $K \subset \mathbb{R}^n$ be a compact set and $U \supset K$ an open set. Assume that $\Phi$ is a real valued function in $C^\infty(U)$ such that $|\nabla \Phi| > 0$ and
\[
|\partial^\alpha \Phi| \leq |\nabla \Phi|, \quad |\partial^\alpha (|\nabla \Phi|^2)| \leq |\nabla \Phi|^2,
\]
for all multi-indices $\alpha$ with $|\alpha| \geq 1$. Then, for any $F \in C^\infty_c(K)$ and any integer $k \geq 0$,
\[
\left| \int_{\mathbb{R}^n} F(\xi) e^{i\Phi(\xi)} d\xi \right| \leq C_{k,n,K} \sum_{|\alpha| \leq k} \int_K |\partial^\alpha F(\xi)||\nabla \Phi(\xi)|^{-k} d\xi.
\]

Now we shall proceed with our chain of propositions.

Proposition 2.6. For $s > 0$, if for all measurable functions $0 \leq t(x) \leq 1$, the estimate
\[
\|T_t(x)f\|_{L^2(B(0,1))} \lesssim \|f\|_{H^s(\mathbb{R}^n)}, \quad f \in \mathcal{S}(\mathbb{R}^n),
\]
holds, then one has
\[
\|T_{\tau(x)}f\|_{L^2(B(0,1))} \lesssim R^n \|f\|_{L^2(\mathbb{R}^n)}, \quad f \in \mathcal{S}(\mathbb{R}^n), \quad R \geq 1,
\]
for all measurable functions $0 \leq \tau(x) \leq R^a$.

Proof. Let $f \in \mathcal{S}(\mathbb{R}^n)$, $R \geq 1$ and $0 \leq \tau(x) \leq R^a$ a measurable function. Take $t(x) := \tau(x)/R^n$. A change of variables yields
\[
T_{\tau(x)}f(x) = R^{-n} \int_{\mathbb{R}^n} e^{i\frac{4\pi}{R} \eta + i t(x) \phi(\eta)} f\left(\frac{\eta}{R}\right) d\eta.
\]
Setting $f_R(z) := f(Rz)$ and using (9) it follows that
\[
\|T_{\tau(x)}f\|_{L^2(B(0,1))} \lesssim R^{n/2} \|T_{\tau(x)}f_R\|_{L^2(B(0,1))} \lesssim R^{n/2} \|f\|_{H^s(\mathbb{R}^n)} \lesssim R^n \|f\|_{L^2(\mathbb{R}^n)},
\]
because supp$(f_R) \subset A(R)$ and $0 \leq t(Rx) = \tau(Rx)/R^n \leq 1$, $x \in \mathbb{R}^n$.

The following proposition gives us a means of transferring local to global estimates for frequency localised functions.

Proposition 2.7. For $s > 0$, if for all measurable functions $0 \leq t(x) \leq R^a$, the estimate
\[
\|T_{\tau(x)}f\|_{L^2(B(0,1))} \lesssim R^a \|f\|_{L^2(\mathbb{R}^n)}, \quad f \in \mathcal{S}(\mathbb{R}^n), \quad R \geq 1,
\]
holds, then one has
\[
\|T_{\tau(x)}f\|_{L^2(\mathbb{R}^n)} \lesssim R^{as} \|f\|_{L^2(\mathbb{R}^n)}, \quad f \in \mathcal{S}(\mathbb{R}^n), \quad R \geq 1,
\]
for all measurable functions $0 \leq \tau(x) \leq R^a$.

Proof. First observe that [9] trivially yields that for $0 \leq \tau(x) \leq R$ one has
\[
\|T_{\tau(x)}f\|_{L^2(\mathbb{R}^n)} \lesssim R^a \|f\|_{L^2(\mathbb{R}^n)}, \quad f \in \mathcal{S}(\mathbb{R}^n), \quad R \geq 1.
\]
Let $\theta$ be a smooth function that is equal to one on $A(1)$ and supported in $\{1/4 < |\xi| < 4\}$. We partition $\mathbb{R}^n$ into finitely overlapping balls $\{B(x_j, R^a)\}_{j \in \mathbb{Z}}$. Let $M := \sup_{|\xi|=1} |\nabla \phi(\xi)|$ and set $\kappa := 4^n M$. Then
\[
\|T_{\tau(x)}f\|_{L^2(\mathbb{R}^n)}^2 \lesssim \sum_{j \in \mathbb{Z}} \int_{B(x_j, R^a)} \left| \int_{\mathbb{R}^n} e^{i(x-y) \cdot \xi + ip(x) \phi(\xi)} \theta(\xi) f(y) \, dy \right|^2 \, dx
\]
\[
\lesssim \sum_{j \in \mathbb{Z}} \int_{B(x_j, R^a)} \left| \int_{\mathbb{R}^n} e^{i(x-y) \cdot \xi + ip(x) \phi(\xi)} \theta(\xi) \psi_j(y) f(y) \, dy \right|^2 \, dx
\]
\[
+ \sum_{j \in \mathbb{Z}} \int_{B(x_j, R^a)} \left| \int_{\mathbb{R}^n} e^{i(x-y) \cdot \xi + ip(x) \phi(\xi)} \theta(\xi) \left(1 - \psi_{j,R}(y)\right) f(y) \, dy \right|^2 \, dx,
\]
where \( \psi_{j,R} \) is a bump function equal to 1 on the ball \( B(x_j, \kappa + 1) R^n \) and supported in the ball \( B(x_j, \kappa + 2) R^n \). For the first term above, we decompose \( \theta \) as

\[
\theta =: \theta_1 + \theta_2 + \theta_3,
\]

where \( \theta_1 \) is supported in \( \{1/4 \leq |\xi| \leq 1\} \), \( \theta_2 \) is supported in \( \{1/2 \leq |\xi| \leq 2\} \) and \( \theta_3 \) is supported in \( \{1 \leq |\xi| \leq 4\} \). For instance, we could take \( \theta_1(\xi) := \lambda(2 \xi), \theta_2(\xi) := \lambda(\xi) \) and \( \theta_3(\xi) := \lambda(\xi/2) \), where \( \lambda \) is the function introduced in \([6]\).

Then we have that

\[
\sum_{j \in \mathbb{Z}} \int_{B(x_j, R^n)} \left| \int_{\mathbb{R}^n} e^{i(x-y) \cdot \xi + i \rho(y) \phi(\xi)} \theta(\xi) \psi_{j,R}(y) f(y) \, dy \right|^2 dx 
\]

\[
\lesssim \sum_{k=1}^{3} \sum_{j \in \mathbb{Z}} \int_{B(x_j, R^n)} \left| \int_{\mathbb{R}^n} e^{i(x-y) \cdot \xi + i \rho(y) \phi(\xi)} \theta_k(\xi) \psi_{j,R}(y) f(y) \, dy \right|^2 dx.
\]

We first analyze the term that contains \( \theta_2 \) since \( \text{supp} \theta_2 \subset A(1) \). Using the fact that 0 \( \leq \rho(x + x_j) \leq R^n \), and setting \( \hat{g}_{j,R}(\xi) := \theta_2(\xi) \psi_{j,R} f(\xi) \), \( \tau_0 f(x) := f(x + h) \), estimate \([11]\) yields

\[
\sum_{j \in \mathbb{Z}} \int_{B(x_j, R^n)} \left| \left\{ \int_{\mathbb{R}^n} e^{i(x-y) \cdot \xi + i \rho(y) \phi(\xi)} \theta_2(\xi) d\xi \right\} \psi_{j,R}(y) f(y) \right|^2 dx 
\]

\[
= \sum_{j \in \mathbb{Z}} \int_{B(x_j, R^n)} \left| \int_{\mathbb{R}^n} e^{i(x-y) \cdot \xi + i \rho(y) \phi(\xi)} g_{j,R}(\xi) d\xi \right|^2 dx 
\]

\[
= \sum_{j \in \mathbb{Z}} \int_{B(x_j, R^n)} |T_\rho(x + x_j) g_{j,R}(x)|^2 dx = \sum_{j \in \mathbb{Z}} \int_{B(0, R^n)} |T_\rho(x + x_j)(\tau_0 g_{j,R}(x)|^2 dx 
\]

\[
\lesssim R^{2a} \sum_{j \in \mathbb{Z}} \left\| \tau_{x_j/2} g_{j,R} \right\|_{L^2(\mathbb{R}^n)}^2 \lesssim R^{2a} \|f\|_{L^2(\mathbb{R}^n)}^2,
\]

where in the last estimate, we have used the translation invariance of the \( L^2 \) norm, Plancherel’s formula and the finite overlapping property of the dilations of the supports.

To deal with the integral containing \( \theta_1 \), we set \( \hat{g}_{1,j,R}(\xi) := \theta_1(\xi/2) \psi_{j,R} f(\xi/2) \), and follow a similar line of calculations as in the case of \( \theta_2 \), with the difference that here we make changes of variables and use the homogeneity of \( \phi \). This leads to

\[
\sum_{j \in \mathbb{Z}} \int_{B(x_j, R^n)} \left| \int_{\mathbb{R}^n} e^{i(x-y) \cdot \xi + i \rho(y) \phi(\xi)} \theta_1(\xi) d\xi \right| \psi_{j,R}(y) f(y) \, dy \right|^2 dx 
\]

\[
= 2^{-n} \sum_{j \in \mathbb{Z}} \int_{B(0, R^n)} \left| \int_{\mathbb{R}^n} e^{i(x-x_j) \cdot \xi + i \rho(y) \phi(\xi)} e^{i\xi/2} \xi g_{1,j,R}(\xi) d\xi \right|^2 dx 
\]

\[
\leq 2^{-n} \sum_{j \in \mathbb{Z}} \int_{B(0, R^n)} |T_{\rho(x+x_j)}(\tau_{-i\xi/2} g_{1,j,R}(x)|^2 dx 
\]

\[
\lesssim 2^{-n} R^{2a} \sum_{j \in \mathbb{Z}} \left\| \tau_{x_j/2} g_{1,j,R} \right\|_{L^2(\mathbb{R}^n)}^2 \lesssim R^{2a} \|f\|_{L^2(\mathbb{R}^n)}^2,
\]

where we have used the facts that \( \text{supp} \hat{g}_{1,j,R} \subset A(1) \) and \( 0 \leq \rho(2x + x_j)/2^n \leq R^n/2^n < R^n \).

To deal with the integral containing \( \theta_3 \), we set \( \hat{g}_{3,j,R}(\xi) := \theta_3(\xi) \psi_{j,R} f(\xi) \), and once again use a suitable change of variables and the homogeneity of \( \phi \). This yields

\[
\sum_{j \in \mathbb{Z}} \int_{B(x_j, R^n)} \left| \int_{\mathbb{R}^n} e^{i(x-y) \cdot \xi + i \rho(y) \phi(\xi)} \theta_3(\xi) d\xi \right| \psi_{j,R}(y) f(y) \, dy \right|^2 dx 
\]

\[
= 2^n \sum_{j \in \mathbb{Z}} \int_{B(0, R^n)} \left| \int_{\mathbb{R}^n} e^{i(x-x_j) \cdot \xi + i \rho(y) \phi(\xi)} e^{i\xi/2} \xi g_{3,j,R}(\xi) d\xi \right|^2 dx 
\]

\[
\leq 2^n \sum_{j \in \mathbb{Z}} \int_{B(0, R^n)} |T_{2^{n}\rho(x+x_j)}(\tau_{2x_j} g_{3,j,R}(x)|^2 dx 
\]
(15) \[ \|a_{y,2,2}\|_{L^2(\mathbb{R}^n)}^2 \lesssim R^{2a} \|f\|_{L^2(\mathbb{R}^n)}^2, \]

where we have used the facts that \( \text{supp}\ a_{y,2,2} \subset A(1) \) and \( 0 \leq 2^a \rho(x/2 + x_j) \leq (2R)^a \).

To estimate the term containing \( 1 - \psi_j \) in (12), we set \( F := \theta(\xi), \Phi := (x - y) \cdot \xi + \rho(x) \varphi(\xi) \), and observe that \( \nabla_x \Phi = x - y + \rho(x) \nabla \varphi(\xi) \) verifies all the assumptions of Lemma 2.5. Indeed, as a first step we have that, for \( 0 \leq \rho(x) \leq R^a \), \( |y - x_j| \geq (\kappa + 1) R^n \) and \( x \in B(x_j, R^n) \), the estimate \( |x - y| \geq \kappa R^a \geq \kappa \rho(x) \) holds true.

Now define \( m := \min_{|\xi|=1} |\nabla \varphi(\xi)| \), and observe that \( m > 0 \) by the assumption (5) on the phase. We claim that

(16) \[ |\nabla \xi \Phi(\xi)| \geq \max \left( \frac{|x - y|}{4}, 3 \rho(x)|\nabla \varphi(\xi)| \right) \geq \max \left( \frac{|x - y|}{4}, 3 \rho(x) |\nabla \varphi(\xi)|^{a-1} \right), \]

where the second lower bounds above follow from the homogeneity of \( \varphi \). Therefore it remains to prove the first lower bounds. To this end, we have for \( \xi \in \text{supp} \theta \) i.e. for \( \{1/4 < |\xi| < 4\} \),

(17) \[ |\nabla \varphi(\xi)| \leq M |\xi|^{a-1} \leq 4^{a-1} M = \frac{\kappa}{4}. \]

Thus,

\[ |\nabla \xi \Phi(\xi)| \geq |x - y| - \rho(x) |\nabla \varphi(\xi)| > |x - y| - \frac{|x - y| \kappa}{4} = \frac{3|x - y|}{4}. \]

Now since \( |x - y| > \kappa \rho(x) \), we have

\[ |\nabla \xi \Phi(\xi)| \geq |x - y| - \rho(x) |\nabla \varphi(\xi)| \geq \rho(x) |\nabla \varphi(\xi)| \left( \frac{\kappa}{|\nabla \varphi(\xi)|} - 1 \right). \]

Moreover, (17) implies that

(18) \[ |\nabla \xi \Phi(\xi)| \geq 3 \rho(x) |\nabla \varphi(\xi)| \geq 3 m \rho(x) |\xi|^{a-1}. \]

Trivially, for any \( |\alpha| = 1 \), \( |\partial_\xi^\alpha \Phi(\xi)| \leq |\nabla \xi \Phi(\xi)| \). For \( |\alpha| \geq 2 \) and \( \{1/4 < |\xi| < 4\} \), (16) and (18) imply that

\[ |\partial_\xi^\alpha \Phi(\xi)| = \rho(x) |\partial_\xi^\alpha \varphi(\xi)| \leq c_\alpha \rho(x) |\xi|^{a-1+|\alpha|} = c_\alpha |\xi|^{a-1} |\xi|^{a-1} \]

\[ \leq \frac{1}{3^m} c_\alpha |\xi|^{a-1} |\nabla \xi \Phi(\xi)| \lesssim |\nabla \xi \Phi(\xi)|, \]

which verifies the first condition (on the phase) of Lemma 2.5. To check the validity of the second condition on the phase in Lemma 2.5, we observe that since

\[ |\nabla \nabla \Phi(\xi)|^2 = |x - y|^2 + \rho(x)^2 |\nabla \varphi(\xi)|^2 + 2 \rho(x) (x - y) \cdot \nabla \varphi(\xi), \]

we have that for any \( |\alpha| \geq 1 \),

(19) \[ \partial_\xi^\alpha |\nabla \xi \Phi(\xi)|^2 = \rho(x)^2 |\partial_\xi^\alpha \varphi(\xi)|^2 + 2 \rho(x) (x - y) \cdot \nabla |\partial_\xi^\alpha \varphi(\xi)|. \]

For the second term on the RHS of (19), estimate (18) yields

\[ 2 |\partial_\xi^\alpha \varphi(\xi)| \leq 2 c_\alpha \rho(x) |x - y| |\xi|^{a-1} \lesssim \frac{2}{3^m} c_\alpha |\xi|^{a-1} |\xi|^{a-1} \lesssim |\nabla \xi \Phi(\xi)|^2, \]

where the last inequality follows from (10). For the first term on the RHS of (19), Leibniz’s rule follows from (16). Therefore, Lemma 2.5 implies that for \( 0 < \rho(x) < R^a \), \( |y - x_j| > (\kappa + 1) R^n \), \( x \in B(x_j, R^n) \) and all \( N \geq 0 \)

\[ \left| \int_{\mathbb{R}^n} e^{i(x - y) \cdot \xi + i\rho(x) \varphi(\xi)} \theta(\xi) \, d\xi \right| \lesssim R^{-a N} (1 + |x - y|)^{-N}. \]

Now if \( M f(x) \) denotes the Hardy-Littlewood maximal function of \( f \), then for any \( N \geq 0 \) one has

\[ \sum_{j \in \mathbb{Z}} \int_{B(x_j, R^n)} \left| \int_{\mathbb{R}^n} e^{i(x - y) \cdot \xi + i\rho(x) \varphi(\xi)} \theta(\xi) \, d\xi \right| \left( 1 - \psi_{j,R}(y) \right) f(y) \, dy \right|^2 \, dx \]
Let \( \hat{\rho} \) and \( \hat{g} \) be the kernel estimates of Lemma 2.3. Then

\[
\| \mathcal{T}_t(f) \|_{L^2(\mathbb{R}^n)} \lesssim R^{as} \| f \|_{L^2(\mathbb{R}^n)}, \quad f \in \mathcal{S}(\mathbb{R}^n), \quad R \geq 1,
\]

for all measurable functions \( 0 \leq \rho(x) \leq R \), then

\[
\| \mathcal{T}_t(f) \|_{L^2(\mathbb{R}^n)} \lesssim \| f \|_{H^{a+s}(\mathbb{R}^n)}, \quad f \in \mathcal{S}(\mathbb{R}^n),
\]

for all measurable functions \( t(x) \) with \( 0 \leq t(x) \leq 1 \).

Proof. Let \( f \in \mathcal{S}(\mathbb{R}^n) \) and \( 0 \leq t(x) \leq 1 \) measurable. It is enough to prove that

\[
\| \mathcal{T}_t(f) \|_{L^2(\mathbb{R}^n)} \lesssim \| f \|_{L^2(\mathbb{R}^n)},
\]

where

\[
\mathcal{T}_t(f)(x) := \int_{\mathbb{R}^n} \langle \xi \rangle^{-(a + s)} e^{ix \cdot \xi + it(x) \phi(\xi)} \hat{f}(\xi) d\xi, \quad x \in \mathbb{R}^n.
\]

In association to the partition of the unity defined in [7] we consider the standard Littlewood-Paley decomposition,

\[
f = \sum_{k \geq 0} \mathcal{P}_k f, \quad \mathcal{P}_k f(\xi) = \psi_k(\xi) \hat{f}(\xi), \quad k \geq 0.
\]

By the triangle inequality we can write

\[
\| \mathcal{T}_t(f) \|_{L^2(\mathbb{R}^n)} \leq \| \mathcal{T}_t(\mathcal{P}_0 f) \|_{L^2(\mathbb{R}^n)} + \sum_{k \geq 1} \| \mathcal{T}_t(\mathcal{P}_k f) \|_{L^2(\mathbb{R}^n)}.
\]

First we claim that

\[
\| \mathcal{T}_t(\mathcal{P}_0 f) \|_{L^2(\mathbb{R}^n)} \lesssim \| f \|_{L^2(\mathbb{R}^n)}.
\]

To see this we just observe that the integral kernel of \( \mathcal{T}_t(\mathcal{P}_0 f) \) is given by

\[
\int_{\mathbb{R}^n} \langle \xi \rangle^{-(a + s)} \psi_0(\xi) e^{i(x \cdot y) - i \xi \cdot \xi + it(x) \phi(\xi)} d\xi,
\]

to which the kernel estimate of Lemma 2.3 is applicable.

Second, in order to be able to use assumption (21), we observe that if \( g \in \mathcal{S}(\mathbb{R}^n) \) with \( \text{supp}(\hat{g}) \subset A(R) \). Taking \( \rho(x) := R^a t(x) \) and changing variables yield

\[
\mathcal{T}_t(g)(x) = \int_{\mathbb{R}^n} e^{ix \cdot \xi + ip(x) \phi(\xi)} \hat{g}(\xi) (\xi)^{-(a + s)} d\xi
\]

\[
= \int_{\mathbb{R}^n} e^{iR x \cdot \xi + ip(x) \phi(\xi)} \hat{g}(R \xi) (R \xi)^{-(a + s)} d\xi.
\]

Define \( \hat{h}_{1/R}(\eta) := \hat{g}_{1/R}(\eta)^{-(a + s)} \), where \( g_{1/R}(z) := g(z/R) \) and observe that \( \text{supp}(h_{1/R}) = \text{supp}(\hat{g}_{1/R}) \subset A(1) \). Therefore, (24) and (21) give us

\[
\| \mathcal{T}_t(g) \|_{L^2(\mathbb{R}^n)} = R^{-n/2} \left( \int_{\mathbb{R}^n} \left| e^{i x \cdot \xi + i p(x) \phi(\xi)} \hat{g}(R \xi) R^n d\xi \right|^2 d\xi \right)^{1/2}
\]

\[
\lesssim R^{as} R^{-n/2} \| h_{1/R} \|_{L^2(\mathbb{R}^n)} = R^{as} R^{-n/2} \| h_{1/R} \|_{L^2(\mathbb{R}^n)}
\]

\[
= R^{as} R^{-n/2} \left( \int_{\mathbb{R}^n} |\hat{g}_{1/R}(\eta)|^2 R^{-2(a + s)} (R^{-2} + |\eta|^2)^{-(a + s)} d\eta \right)^{1/2}
\]

(25)

\[
\lesssim R^{-\xi} R^{-n/2} \| g_{1/R} \|_{L^2(\mathbb{R}^n)} = R^{-\xi} \| g \|_{L^2(\mathbb{R}^n)} ,
\]

where we have also used the fact that \( 0 \leq \rho(x/R) = R^a t(x/R) \leq R^a \), \( x \in \mathbb{R}^n \).
Finally, putting together (22), (23) and taking $g = \mathcal{P}_k f$, $R = 2^k$, $k \geq 1$, in (25) we conclude
\[
\|T_{\ell(z)} f\|_{L^2(\mathbb{R}^n)} \lesssim \|f\|_{L^2(\mathbb{R}^n)} + \sum_{k \geq 1} 2^{-k\epsilon} \|\mathcal{P}_k f\|_{L^2(\mathbb{R}^n)} \lesssim \|f\|_{L^2(\mathbb{R}^n)}.
\]

We should also mention that when the homogeneity degree $a$ of the phase $\phi$ is larger than 1, then it is possible to prove Theorem 2.1 for phases that verify the two conditions
\[
|\partial^a \phi(\xi)| \lesssim |\xi|^{a-\alpha} \text{ and } |\nabla \phi(\xi)| \gtrsim |\xi|^{a-1}, \text{ for } |\alpha| \leq 2 \text{ and } |\xi| \neq 0.
\]
For $a = 1$, one can replace these two conditions by
\[
|\partial^a \phi(\xi)| \lesssim |\xi|^{1-\alpha} \text{ for } |\alpha| \leq 2 \text{ and } |\xi| \neq 0
\]
(e.g., the case of the Klein-Gordon equation).

Though, for the sake of clarity and brevity of the exposition, we will not pursue these generalizations here and the details for the modifications of our arguments for inhomogeneous phases will appear elsewhere.

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