Weston-Watkins Hinge Loss and Ordered Partitions

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Abstract

Multiclass extensions of the support vector machine (SVM) have been formulated in a variety of ways. A recent empirical comparison of nine such formulations [1] recommends the variant proposed by Weston and Watkins (WW), despite the fact that the WW-hinge loss is not calibrated with respect to the 0-1 loss. In this work we introduce a novel discrete loss function for multiclass classification, the ordered partition loss, and prove that the WW-hinge loss is calibrated with respect to this loss. We also argue that the ordered partition loss is maximally informative among discrete losses satisfying this property. Finally, we apply our theory to justify the empirical observation made by Doğan et al. [1] that the WW-SVM can work well even under massive label noise, a challenging setting for multiclass SVMs.

1 Introduction

Classification is the task of assigning labels to instances, and a common approach is to minimize misclassification error corresponding to the 0-1 loss. However, the 0-1 loss is discrete and typically cannot be optimized efficiently. To address this, the 0-1 loss is often replaced by a surrogate loss during training. If the surrogate is calibrated with respect to the 0-1 loss, then a classifier minimizing the expected surrogate loss will also minimize the expected 0-1 loss in the infinite sample limit.

For multiclass classification, several different multiclass extensions of the support vector machine (SVM) have been proposed, including the Weston-Watkins (WW) [2], Crammer-Singer (CS) [3], and Lee-Lin-Wahba (LLW) [4] SVMs. The pertinent difference between these multiclass SVMs is the multiclass generalization of the hinge loss. Below, we refer to the hinge loss from WW-SVM as the WW hinge loss and so on. It is well-known that the LLW-hinge is calibrated with respect to the 0-1 loss, while the WW- and CS-hinge losses are not [3, 4].

Despite this result, the LLW-SVM is not more widely accepted than the WW-, CS-, and other SVMs. The first reason for this is that while the LLW-SVM is calibrated with respect to the 0-1 loss, this did not lead to superior performance empirically. In particular, Doğan et al. [1] found that the LLW-SVM fails in low dimensional feature space even under the noiseless setting. On the other hand, Doğan et al. [1] observed that the WW-SVM is the only multiclass SVM that succeeded in both the noiseless and noisy setting in their simulations. Indeed, Doğan et al. [1] concluded that, among 9 different competing multiclass SVMs, the WW-SVM offers the best overall performance when considering accuracy and computation. The second reason is that the calibration framework is not limited to the 0-1 loss. There could be other discrete losses with respect to which a surrogate is calibrated, and which help to explain its performance. Indeed, Ramaswamy et al. [7] recently showed that the CS-hinge loss is calibrated with respect to a discrete loss for classification with abstention.

In a vein similar to [7], we show that the WW-hinge loss is calibrated with respect to a novel discrete loss that we call the ordered partition loss. Our results leverage the embedding framework for analyzing discrete losses and convex piecewise linear surrogates, introduced recently by Finocchiaro et al. [8]. We also give theoretical justification for the empirical performance of the WW-SVM observed by Doğan et al. [1].
1.1 Related work

Cortes and Vapnik [9] introduced the support vector machine for learning a binary classifier, using the hinge loss as a surrogate for the 0-1 loss. Steinwart [10] showed that the binary SVM is universally consistent, a desirable property of a classification algorithm that ensures its convergence to the Bayes optimal classifier in the large sample limit. Steinwart [11] later used calibration to give a more general proof of SVM consistency with respect to the 0-1 loss. Around that time, more general theories of when a loss is calibrated with respect to 0-1 loss, or “classification calibrated,” began to emerge [12, 13, 14], and since then a proliferation of papers have extended these ideas to a variety of learning settings (see Bao et al. [15] for a recent review).

Several natural extensions of the binary SVM exist, including the Weston-Watkins (WW) [2], Crammer-Singer (CS) [3], and Lee-Lin-Wahba (LLW) [4] SVMs. Tewari and Bartlett [6] extended the definition of calibration with respect to the 0-1 loss to the multiclass setting. Liu [5] and Tewari and Bartlett [6] analyzed these hinge losses and showed that WW and CS hinge losses are not calibrated with respect to the 0-1 loss while the LLW hinge loss is. Doğan et al. [1] introduced a framework that unified existing multiclass SVMs, proved the 0-1 loss consistency of several multiclass SVMs when the kernel is allowed to change, and also conducted extensive experiments. Despite not being calibrated with respect to the 0-1 loss, Zhang [12] showed that the Crammer-Singer SVM is consistent given the “majority assumption”, i.e., the most probable class has greater than $1/2$ probability. When the majority assumption is violated, experiments conducted by Doğan et al. [1] suggested that the CS-SVM fails, while the WW-SVM continues to perform well.

Ramaswamy and Agarwal [16] extended the notion of calibration to an arbitrary discrete loss used in general multiclass learning. The general multiclass learning framework unifies several learning problems, including cost-sensitive classification [17], classification with abstain option [7], ranking [18], and partial label learning [19]. Furthermore, Ramaswamy and Agarwal [16] introduced the concept of convex calibration dimension which is defined for a discrete loss to be the minimum dimension required for the domain of a convex surrogate loss to be calibrated with respect to the given discrete loss. Ramaswamy et al. [7] proved the consistency of CS-SVM with respect to the abstention loss where the cost of abstaining is 1/2 by showing that the CS hinge is calibrated with respect to this abstention loss. They also proposed a new calibrated convex surrogate loss in dimension $\lceil \log_2 k \rceil$ for the abstention loss, implying that the CS hinge is suboptimal from the CC-dimension perspective.

Recently, several new multiclass hinge-like losses have been proposed, as well as frameworks for constructing convex losses. Doğan et al. [1] used their framework to devise two new multiclass hinge losses, and using ideas from adversarial multiclass classification, Fathony et al. [20] proposed a new multiclass hinge-like loss; all three are calibrated with respect to the 0-1 loss. Blondel et al. [21] introduced a class of losses known as Fenchel-Young losses which contains non-smooth losses such as the CS hinge loss as well as smooth losses such as the logistic loss. Tan and Zhang [22] proposed an approach for constructing hinge-like losses using generalized entropies. Finocchiaro et al. [8] studied the calibration properties of polyhedral losses using the embedding framework that they developed. They analyzed several polyhedral losses in the literature including the CS hinge, the Lovász hinge [23], and the top-n loss [24].

1.2 Our contributions

We introduce a novel discrete loss $\ell$, the ordered partition loss. We show in Theorem 3.1 that the Weston-Watkins hinge loss $L$ embeds the ordered partition loss $\ell$. Our embedding result together with results of [8] imply that $L$ is calibrated with respect to $\ell$ (Corollary 3.2). To the best of our knowledge, this is the first calibration-theoretic result for the WW-hinge loss. We also introduce the notion of the maximally informative discrete loss that a polyhedral loss can embed and argue that the ordered partition loss is maximally informative for the WW-hinge loss. In Section 5 we use properties of the ordered partition loss to give theoretical support for the empirical observations made by Doğan et al. [1] on the success of WW-SVM in the massive label noise setting.
1.3 Notations

Let \( k \geq 3 \) be an integer which denotes the number of classes. For a positive integer \( n \), we let \([n] = \{1, \ldots, n\}\). If \( v = (v_1, \ldots, v_k) \in \mathbb{R}^k\) and \( i \in [k] \) is an index, then let \([v]_i := v_i\). Define \( \max v = \max_{i \in [k]} v_i \) and \( \arg \max v = \{i \in [k] : v_i = \max v\} \).

Let \( S_k \) denote the set of permutations on \([k]\), i.e., elements of \( S_k \) are bijections \( \sigma : [k] \to [k]\). Given \( \sigma \in S_k \) and \( v \in \mathbb{R}^k\), the vector \( \sigma v \in \mathbb{R}^k \) is defined entrywise where the \( i \)-th entry is \([\sigma v]_i = v_{\sigma(i)}\). Equivalently, we view \( S_k \) as the set of permutation matrices in \( \mathbb{R}^{k \times k}\).

Let \( \mathbb{R}_+ \) denote the set of nonnegative reals. Denote \( \Delta^k = \{(p_1, \ldots, p_k) \in \mathbb{R}_+^k : p_1 + \cdots + p_k = 1\} \) the probability simplex. For \( \psi : \mathbb{R} \to \mathbb{R} \) an indicator function which returns \( 1 \) if \( \psi \) is true and \( 0 \) otherwise.

1.4 Background

Recall the general multiclass learning framework as described in \cite{16}: \( \mathcal{X} \) is a sample space and \( P \) is a joint distribution over \( \mathcal{X} \times [k] \). A multiclass classification loss is a function \( \ell : \mathcal{R} \to \mathbb{R}_+^k \) where \( \mathcal{R} \) is called the prediction space and \( [\ell(r)]_y \in \mathbb{R}_+ \) is the penalty incurred for predicting \( r \in \mathcal{R} \) when the label is \( y \in [k] \). If \( \mathcal{R} \) is finite, we refer to \( \ell \) as a discrete loss. For example, a common setting for classification is \( \mathcal{R} = [k] \) and \( \ell \) is the 0-1 loss. The \( \ell \)-risk of a hypothesis function \( f : \mathcal{X} \to \mathcal{R} \) is

\[
\text{er}_f^\ell := \mathbb{E}_{X,Y \sim \mathcal{P}}[\langle \ell(f(X)), Y \rangle].
\]

The goal is to design \( \ell \)-consistent algorithms, i.e., procedures that output a hypothesis \( f_n \) based on an input of \( n \) training samples sampled i.i.d from \( P \) such that \( \text{er}_f^\ell(f_n) \to \text{er}^\ell \) as \( n \to \infty \). Since \( \ell \) is discrete, eq. (1) is difficult to directly minimize. To circumvent this difficulty, we consider a convex surrogate loss \( L : \mathbb{R}^d \to \mathbb{R}^k \) for some positive integer \( d \). The following property relates the surrogate loss \( L \) and the discrete loss \( \ell \).

**Definition 1.1** (Calibration). For each \( p \in \Delta^k \), define \( \gamma_\ell(p) := \arg \min_{r \in \mathcal{R}} \langle p, \ell(r) \rangle \). We say that \( L \) is calibrated with respect to \( \ell \) if there exists a function \( \psi : \mathbb{R}^d \to \mathcal{R} \) such that for all \( p \in \Delta^k \)

\[
\inf_{u \in \mathbb{R}^d : \psi(u) \notin \gamma_\ell(p)} \langle p, L(u) \rangle > \inf_{v \in \mathbb{R}^k} \langle p, L(v) \rangle.
\]

By Ramaswamy and Agarwal \cite[Theorem 3]{16}, \( L \) being calibrated with respect to \( \ell \) is equivalent to the following: there exists \( \psi : \mathbb{R}^d \to \mathcal{R} \) such that for all joint distributions \( P \) on \( \mathcal{X} \times [k] \) and all sequences of functions \( g_n : \mathcal{X} \to \mathbb{R}^d \), we have

\[
\text{er}^\ell(g_n) \to \text{er}^{L_*} \implies \text{er}^\ell(\psi \circ g_n) \to \text{er}^{L_*}
\]

where \( \text{er}^{L_*} = \inf_{g : \mathcal{X} \to \mathbb{R}^d} \text{er}^L(g) \). Thus, the calibration property allows us to focus on finding \( L \)-consistent algorithms. In general it can be difficult to check that a given \( L \) is calibrated with respect to \( \ell \). Finocchiaro et al. \cite{8} introduced the following definition:

**Definition 1.2** (Finocchiaro et al. \cite{8}). The loss \( L : \mathbb{R}^d \to \mathbb{R}^k \) embeds \( \ell : \mathcal{R} \to \mathbb{R}^k \) if there exists an injection \( \varphi : \mathcal{R} \to \mathbb{R}^d \) called an embedding such that

1. \( L(\varphi(r)) = \ell(r) \) for all \( r \in \mathcal{R} \)
2. \( r \in \arg \min_{r \in \mathcal{R}} \langle p, \ell(r) \rangle \) if and only if \( \varphi(r) \in \arg \min_{u \in \mathbb{R}^d} \langle p, L(u) \rangle \).

The notion of embedding is important due to the following result from \cite[Theorem 3]{8}:

**Theorem 1.3** (Finocchiaro et al. \cite{8}). Let \( L \) be convex piecewise-linear and \( \ell \) be discrete. If \( L \) embeds \( \ell \), then \( L \) is calibrated with respect to \( \ell \).
Finocchiaro et al. [8] also provide an explicit construction for \( \psi \) given \( L, \ell \) and \( \varphi \).

In this work, we are interested in the case when \( L \) is the WW-hinge loss:

**Definition 1.4.** For \( v \in \mathbb{R}^k \), define the Weston-Watkins hinge loss \[ L(v) \in \mathbb{R}_+^k \] entrywise by

\[
[L(v)]_y = \sum_{i \in [k] : i \neq y} h(v_i - v_y), \quad y \in [k]
\]

where \( h : \mathbb{R} \to \mathbb{R}_+ \) is the hinge function defined by \( h(x) = \max\{0, 1 - x\} \).

By Theorem [13] to prove that \( L \) is calibrated with respect to \( \ell \), it suffices to show that \( L \) embeds \( \ell \). Going forward, \( L \) will refer to the WW-hinge loss. We now work toward showing that \( L \) embeds the ordered partition loss \( \ell \), which we introduce next.

## 2 The ordered partition loss

The prediction space \( \mathcal{R} \) that we use is the set of ordered partitions, which we now define:

**Definition 2.1.** An ordered partition on \([k]\) of length \( l \) is an ordered list \( S = (S_1, \ldots, S_l) \) of nonempty, pairwise disjoint subsets of \([k]\) such that \( S_1 \cup \cdots \cup S_l = [k] \). Denote by \( \mathcal{OP}_k \) the set of all ordered partitions on \([k]\) with length \( \geq 2 \). We write the length of \( S \) as \( l_S \) to be precise when working with multiple ordered partitions.

Ordered partitions can be thought of as a complete ranking of \( k \) items where ties are allowed. They are widely studied in combinatorics [23, 26, 27]. In the ranking literature, ordered partitions are called bucket orders [28] and the \( S_i \)s are called the buckets. The first bucket \( S_1 \) contains the highest ranked items, and so on. There is only one ordered partition with \( l_S = 1 \), namely the trivial partition \( S = ([k]) \). Thus, \( \mathcal{OP}_k \) is the set of nontrivial ordered partitions.

We now define the following discrete loss over the ordered partitions:

**Definition 2.2.** The ordered partition loss \( \ell : \mathcal{OP}_k \to \mathbb{R}_+^k \) is defined, for \( i \in [k] \) and \( S = (S_1, \ldots, S_i) \in \mathcal{OP}_k \), as \( [\ell(S)]_i = |S_1| - 1 + \sum_{j=1}^{l_S-1} |S_1 \cup \cdots \cup S_j+1| : \mathbb{I}\{i \notin S_1 \cup \cdots \cup S_j\} \).

To build intuitions about \( \ell \), let \( Y \sim p \) and consider the random variable \( [\ell(S)]_Y \) whose expectation is

\[
\mathbb{E}_{Y \sim p} \{[\ell(S)]_Y\} = |S_1| - 1 + \sum_{j=1}^{l_S-1} |S_1 \cup \cdots \cup S_j+1| \cdot \mathbb{P}_{Y \sim p} \{Y \notin S_1 \cup \cdots \cup S_j\}.
\] (2)
Note that \( E_{Y \sim p} \{ |\ell(S)| \} = \langle p, \ell(S) \rangle \). In Figure 1 we visualize the decision rule for the Bayes optimal classifier in the \( k = 3 \) case by plotting the function \( p \mapsto \arg \min_{S \in \mathcal{OP}_k} \langle p, \ell(S) \rangle \). When \( l_S = 2 \), we have

\[
E_{Y \sim p} \{ |\ell(S)| \} = |S_1| - 1 + k \Pr_{Y \sim p} \{ Y \notin S_1 \}.
\]

Thus, we have a trade-off where adding elements to \( S_1 \) increases the \( |S_1| - 1 \) term but decreases the \( k \Pr_{Y \sim p} \{ Y \notin S_1 \} \) term. More generally, when \( l_S \geq 2 \), the ordered partition loss requires the predictor to associate each test instance \( x \) with a nested sequence of sets \( S_1, S_1 \cup S_2, \ldots \) where these sets are designed to balance the probability of containing \( x \)'s label with the size of the set. In the learning with partial labels settings \([29, 19]\), for each training instance the learner observes a set of labels, one of which is the true label. The sets \( S_1, S_1 \cup S_2, \ldots \) might be called **progressive partial labels** in the spirit of partial label learning \([29, 19]\).

Next, we define the embedding that satisfies Definition 1.2 when \( L \) is the WW-hinge loss and \( \ell \) is the ordered partition loss:

**Definition 2.3.** The embedding \( \varphi : \mathcal{OP}_k \rightarrow \mathbb{R}^k \) is defined as follows: Let \( S = (S_1, \ldots, S_l) \in \mathcal{OP}_k \). Define \( \varphi(S) \in \mathbb{R}^k \) entrywise so that for all \( i \in [l] \) and all \( j \in S_l \), we have \( [\varphi(S)]_j = -(i - 1) \).

With the discrete loss \( \ell \) and the embedding map \( \varphi \) defined, we now proceed to the main results.

### 3 Main results

In this work, we establish that the WW-hinge loss embeds the ordered partition loss:

**Theorem 3.1.** The Weston-Watkins hinge loss \( L : \mathbb{R}^k \rightarrow \mathbb{R}^k \) embeds the ordered partition loss \( \ell : \mathcal{OP}_k \rightarrow \mathbb{R}^k \) with embedding \( \varphi \) as in Definition 2.3.

In light of Theorem 1.3 Theorem 3.1 implies

**Corollary 3.2.** \( L \) is calibrated with respect to \( \ell \).

In the remainder of this section, we develop the tools necessary to prove Theorem 3.1.

#### 3.1 Vectorial representation of ordered partitions

First, we define the set \( \mathcal{S}_k \mathcal{C}_Z \) whose elements serve as realizations of ordered partitions inside \( \mathbb{R}^k \).

**Definition 3.3.** Define the following sets:

\[
\mathcal{C} := \{ v \in \mathbb{R}^k : v_1 = 0, v_k \leq -1, v_i - v_{i+1} \in [0, 1], \forall i \in [k-1] \}, \quad \mathcal{C}_Z := \mathcal{C} \cap \mathbb{Z}^k
\]

and finally \( \mathcal{S}_k \mathcal{C}_Z := \bigcup_{\sigma \in \mathcal{S}_k} \sigma \mathcal{C}_Z \) where \( \sigma \mathcal{C}_Z = \{ \sigma v : v \in \mathcal{C}_Z \} \).

A vector \( v \in \mathbb{R}^k \) is **monotonic non-increasing** if \( v_1 \geq v_2 \geq \cdots \geq v_k \). Note that vectors in \( \mathcal{C}_Z \) are nonconstant, integer-valued monotonic non-increasing such that consecutive entries decrease at most by 1. Furthermore, by construction, \( \mathcal{S}_k \mathcal{C}_Z \) consists of all possible permutations of elements in \( \mathcal{C}_Z \). Therefore, the entries of an element \( v \in \mathcal{S}_k \mathcal{C}_Z \) take on every value in \( 0, -1, \ldots, -(l - 1) \) for some integer \( l \in \{2, \ldots, k\} \). Thus, \( v \in \mathcal{S}_k \mathcal{C}_Z \) can be thought of as vectorial representation of the ordered partition \( S = (S_1, \ldots, S_l) \) where \( S_i = \{ j : v_j = -(i - 1) \} \) for each \( i \in [l] \). In Proposition 3.6 below, we make this notion precise.

**Lemma 3.4.** The image of \( \varphi \) is contained in \( \mathcal{S}_k \mathcal{C}_Z \).

**Proof.** Let \( S \in \mathcal{OP}_k \). It suffices to prove that there exists some \( \sigma \in \mathcal{S}_k \) such that \( \sigma \varphi(S) \in \mathcal{C}_Z \). Note that by definition, we have the set of unique values of \( \varphi(S) \) is

\[
\{ [\varphi(S)]_j : j \in [k] \} = \{ 0, -1, -2, \ldots, -(l_S - 1) \}.
\]

Thus, let \( \sigma \in \mathcal{S}_k \) be such that \( \sigma \varphi(S) \) is monotonic non-increasing. Then \( \sigma \varphi(S) \in \mathcal{C}_Z \). \( \square \)
Next, we define the inverse of $\varphi$.

**Definition 3.5.** The quasi-link map $\tilde{\psi} : \mathcal{S}_k \mathbb{C}_Z \rightarrow \mathcal{O} \mathcal{P}_k$ is defined as follows: Given $v \in \mathcal{S}_k \mathbb{C}_Z$, let $l = 1 - \min_{j \in [k]} v_j$. Define $S_i = \{j \in [k] : v_j = -(i - 1)\}$ for each $i \in [l]$. Finally, define $\tilde{\psi}(v) = (S_1, \ldots, S_l)$.

The tilde in $\tilde{\psi}$ is to differentiate the quasi-link from $\psi$ in Definition 1.1.

**Proposition 3.6.** The embedding map $\varphi : \mathcal{O} \mathcal{P}_k \rightarrow \mathcal{S}_k \mathbb{C}_Z$ given in Definition 2.3 is a bijection with inverse given by the quasi-link map $\tilde{\psi}$ from Definition 3.5.

**Proof.** We first show that for all $\tilde{\psi}(\varphi(S)) = S$ for all $S = (S_1, \ldots, S_l) \in \mathcal{O} \mathcal{P}_k$. Observe that $S_i = \{j \in [k] : [\varphi(S)]_j = -(i - 1)\}$ for all $i = 1, 2, \ldots, l$. This implies that $\tilde{\psi}(\varphi(S)) = S$.

Next, we show that $\varphi(\tilde{\psi}(v)) = v$ for all $v \in \mathcal{S}_k \mathbb{C}_Z$. Let $S = (S_1, \ldots, S_l) = \tilde{\psi}(v)$. Then $[\varphi(S)]_j = -(i - 1)$ if and only if $j \in S_i$. By definition $S_i = \{j \in [k] : v_j = -(i - 1)\}$. Hence, $[\varphi(S)]_j = -(i - 1)$ if and only if $v_j = -(i - 1)$ which implies that $\varphi(S) = v$, as desired.

In the next section, using $\varphi$, we prove a relationship between the inner risk functions of $L$ and $\ell$.

### 3.2 Inner risk functions

Define the inner risk functions $L : \Delta^k \rightarrow \mathbb{R}_+$ and $\ell : \Delta^k \rightarrow \mathbb{R}_+$ as follows:

$$L(p) = \inf_{v \in \mathbb{R}^k} \langle p, L(v) \rangle, \quad \text{and} \quad \ell(p) = \inf_{S \in \mathcal{O} \mathcal{P}_k} \langle p, \ell(S) \rangle. \quad (5)$$

Note that these functions appear in the second part of Definition 1.2 although here we have $\inf$ instead of $\min$. Since $\mathcal{O} \mathcal{P}_k$ is finite, the infimum in the definition of $\ell$ is attained. Later, we will argue that the infimum in the definition of $L$ is also attained.

We now state the main structural result regarding $L$:

**Theorem 3.7.** For all $p \in \Delta^k$, we have

$$L(p) = \min_{v \in \mathcal{S}_k \mathbb{C}_Z} \langle p, L(v) \rangle.$$

**Sketch of proof.** Note that $L$ is invariant under translation by any scalar multiple of the all ones vector. Thus, $L$ has an extra degree of freedom. We introduce a loss function $L : \mathbb{R}^{k-1} \rightarrow \mathbb{R}^k$ called the reduced WW-hinge loss, which removes this extra degree freedom. Furthermore, there exists a mapping $\pi : \mathbb{R}^k \rightarrow \mathbb{R}^{k-1}$ such that $\langle p, L(v) \rangle = \langle p, L(\pi(v)) \rangle$ for all $p \in \Delta^k$ and $v \in \mathbb{R}^k$. Letting $z = \pi(v) \in \mathbb{R}^{k-1}$, we show that for a fixed $p$, the function $F_p(z) := \langle p, L(z) \rangle$ is convex and piecewise-linear and the minimization of which can be formulated as a linear program [30]. Furthermore, since $F_p$ is nonnegative, the infimum $\inf_{z \in \mathbb{R}^{k-1}} F_p(z)$ is attained [31, Corollary 3.2], which implies that the infimum in the definition of $L$ in eq. (5) is attained as well. The linear program is shown to be totally unimodular, which implies that an integral solution exists [31], i.e., $\min_{z \in \mathbb{Z}^{k-1}} F_p(z) = F_p(z^*)$ for some $z^* \in \mathbb{Z}^{k-1}$. From $z^*$, we obtain an integral $v^* \in \mathbb{Z}^k$ such that $L(p) = \langle p, L(v^*) \rangle$. Finally, we construct an element $v^1 \in \mathcal{S}_k \mathbb{C}_Z$ from $v^*$ in such a way that the objective does not increase, i.e., $\langle p, L(v^*) \rangle \geq \langle p, L(v^1) \rangle$, which implies that $L(p) = \langle p, L(v^1) \rangle$ by the optimality of $v^*$.

The ordered partition loss $\ell$ and the WW-hinge loss $L$ are related by the following:

**Theorem 3.8.** For all $p \in \Delta^k$ and all $S \in \mathcal{O} \mathcal{P}_k$, we have

$$\langle p, \ell(S) \rangle = \langle p, L(\varphi(S)) \rangle,$$

where $\varphi$ is the embedding map as in Definition 2.3.
We check that the two conditions in Definition 1.2 holds. The first condition is that \(\ell\) is a discrete loss where \(\ell(a, v)\) follows from definition of \(\ell\), and the 0-1 loss by Corollary 3.9. For all \(i\), \([DL(\varphi(S))]_i = 0\) (in which case the value of \([T^p]_i\) is irrelevant).

From this, we deduce that \((T^p, DL(\varphi(S)))\) is equal to eq. \(\ref{eq:main_result}\).

Next, we show that the inner risks of \(L\) and \(\ell\) from eq. \(\ref{eq:main_result}\) are in fact identical:

**Corollary 3.9.** For all \(p \in \Delta^k\), we have \(\mathcal{L}(p) = \ell(p)\).

**Proof.** Observe that

\[
\mathcal{L}(p) \overset{(a)}{=} \min_{S \in \mathcal{OP}_k} \langle p, \ell(S) \rangle \overset{(b)}{=} \min_{S \in \mathcal{OP}_k} \langle p, L(\varphi(S)) \rangle \overset{(c)}{=} \min_{v \in \mathcal{S}^k} \langle p, L(v) \rangle \overset{(d)}{=} L(p)
\]

where \((a)\) follows from definition of \(\mathcal{L}\), \((b)\) from Theorem 3.3, \((c)\) from the fact that \(\varphi : \mathcal{OP}_k \to \mathcal{S}^k\) is a bijection (Proposition 3.6), and \((d)\) from Theorem 3.7.

Having developed all the tools necessary, we turn toward the proof of our main result Theorem 3.1.

### 3.3 Proof of Theorem 3.1

We check that the two conditions in Definition 1.2 holds. The first condition is that \(L(\varphi(S)) = \ell(S)\) for all \(S \in \mathcal{OP}_k\), which follows from Theorem 3.3. To see this, note that for all \(i \in [k]\) the \(i\)-th elementary basis vector \(e_i \in \Delta^k\). Thus, we have

\[
[L(\varphi(S))]_i = \langle e_i, L(\varphi(S)) \rangle = \langle e_i, \ell(S) \rangle = [\ell(S)]_i
\]

for all \(i \in [k]\). This implies that \(L(\varphi(S)) = \ell(S)\), which is the first condition of Definition 1.2.

Next, we check the second condition. Let \(p \in \Delta^k\). Define \(\gamma(p) := \arg \min_{S \in \mathcal{OP}_k} \langle p, \ell(S) \rangle\), and \(\Gamma(p) := \arg \min_{v \in \mathcal{S}^k} \langle p, L(v) \rangle\). Furthermore, by the definition of \(\gamma\), \(S \in \gamma(p)\) if and only if \(\langle p, \ell(S) \rangle = \mathcal{L}(p)\). Likewise, \(\varphi(S) \in \Gamma(p)\) if and only if \(\langle p, L(\varphi(S)) \rangle = L(p)\). By Corollary 3.9 and Theorem 3.8, we have \(\langle p, \ell(S) \rangle = \mathcal{L}(p)\) if and only if \(\langle p, L(\varphi(S)) \rangle = L(p)\). Putting it all together, we get \(S \in \gamma(p)\) if and only if \(\varphi(S) \in \Gamma(p)\), which is the second condition of Definition 1.2.

### 4 Maximally informative losses

Going forward, let \(L : \mathbb{R}^d \to \mathbb{R}^k_+\) be a generic surrogate loss. The WW-hinge loss is denoted by \(L^{WW}\) and the CS-hinge loss by \(L^{CS}\). Likewise, let \(\ell : \mathcal{R} \to \mathbb{R}^k_+\) be a generic discrete loss. The ordered partition loss is denoted by \(\ell^{OP}\) and the 0-1 loss by \(\ell^{01}\).

We define the “dual” notion to the convex calibration dimension \(\ell^{D}\):

**Definition 4.1.** Let \(L : \mathbb{R}^d \to \mathbb{R}^k_+\) be a loss. Define the embedding cardinality of \(L\) as

\[
\text{emb.card}(L) := \min \left\{ n \in \{2, 3, \ldots\} \mid \text{there exists a discrete loss } \ell : \mathcal{N} \to \mathbb{R}^k \text{ such that } L \text{ embeds } \ell \right\}.
\]

A discrete loss \(\ell : \mathcal{R} \to \mathbb{R}^k_+\) is said to be maximally informative for \(L\) if \(|\mathcal{R}| = \text{emb.card}(L)\) and \(L\) embeds \(\ell\).
For each $k \in \{3, \ldots, 7\}$, we showed that by a computer search that for all $S \in OP_k$, there exists $p \in \Delta^k$ such that $S$ is the unique minimizer of $\min_{T \in OP_k} \langle p, \ell(T) \rangle$. A consequence of this is that

**Proposition 4.2.** For $k \in \{3, \ldots, 7\}$, $\text{emb.card}(L^{WW}) = |OP_k|$. In other words, the ordered partition loss is maximally informative for the WW-hinge loss.

## 5 The argmax link

Define $\gamma_\ell(p) := \arg\min_{r \in \mathbb{R}} \langle p, \ell(r) \rangle$ and $\Gamma_\ell(p) := \arg\min_{v \in \mathbb{R}^k} \langle p, L(v) \rangle$. For multiclass classification into $k$ classes, most multiclass SVMs typically output a vector of scores $v \in \mathbb{R}^k$ which is converted to a class label by taking arg max $v$. In this section, we analyze the arg max as a “link” function. Recall from Section 1.3, arg max is a set-valued function. Define

$$\Omega_L := \{p \in \Delta^k : |\arg\max p| = 1, \arg\max v = \arg\max p, \forall v \in \Gamma_L(p)\}.$$  

When $L$ is calibrated with respect to $\ell^{\text{zo}}$, we have that $\Omega_L = \{p \in \Delta^k : |\arg\max p| = 1\}$. Hence, $\Delta^k \setminus \Omega_L$ has measure zero. For other $L$ not necessarily calibrated with respect to $\ell^{\text{zo}}$, it is desirable that $\Omega_L$ be as large as possible. Below, we will prove that $\Omega_L$ is a proper subset of $\Omega_{L^{WW}}$.

Recall that $X$ is a sample space and $P$ is a distribution on $X \times [k]$. For each $x \in X$, define the class conditional distribution $\eta_P(x) \in \Delta^k$ by $[\eta_P(x)]_y = \Pr_{X,Y \sim P} (Y = y | X = x)$.

**Proposition 5.1.** Let $P$ be a joint distribution on $X \times [k]$ such that $\eta_P(x) \in \Omega_L$ for all $x$ and $L : \mathbb{R}^d \rightarrow \mathbb{R}^k_+$ be a loss. Let $g^* : X \rightarrow \mathbb{R}^k$ be such that $g^*(x) \in \Gamma_L(\eta_P(x))$ for all $x \in X$. Then $\arg\max \circ g^*$ is Bayes optimal with respect to the 0-1 loss.

**Proof.** By definition of $\Omega_L$, we have $\arg\max \circ g^*(x) = \arg\max \eta_P(x)$ for all $x \in X$. \hfill \square

The following theorem asserts that for any $v \in \Gamma_{L^{WW}}(p)$, the arg max $v$ is contained in the top bucket $S_1$ for some $S \in \gamma_{\ell^{\text{zo}}}(p)$.

**Theorem 5.2.** Let $p \in \Delta^k$ be such that $\max v > \frac{1}{k}$ and $v \in \Gamma_{L^{WW}}(p)$. Then there exists $S = (S_1, \ldots, S_i) \in \gamma_{\ell^{\text{zo}}}(p)$ such that $\arg\max v \subseteq S_1$.

Below, we consider two conditions on $p \in \Delta^k$ such that for all $S \in \gamma_{\ell^{\text{zo}}}(p)$, the top bucket $S_1 = \arg\max p$. By Theorem 5.2, for such $p \in \Delta^k$, we can recover $\arg\max p$ from any $v \in \Gamma_{L^{WW}}(p)$. The first condition covers $p \in \Delta^k$ such that the top class has a majority:

**Proposition 5.3.** Let $p \in \Delta^k$ satisfy the “majority condition”: $\max p > 1/2$. Then for all $S = (S_1, \ldots, S_i) \in \gamma_{\ell^{\text{zo}}}(p)$, we have $|S_1| = 1$ and $S_1 = \arg\max p$. 

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While Proposition 5.3 does not guarantee that $\gamma_{OP}(p)$ is a singleton, all $S \in \gamma_{OP}(p)$ have the same top bucket. The second condition covers $p \in \Delta^k$ whose top class may not have a majority, yet arg max $p$ can still be recovered from any $v \in \Gamma_{LWW}(v)$ by taking arg max $v$:

Proposition 5.4. Fix a number $\alpha$ such that $1 > \alpha > \frac{1}{k}$. Let $p \in \Delta^k$ satisfy the “symmetric label noise (SLN) condition”: there exists $j^* \in [k]$ so that $p_{j^*} = \alpha$ and $p_j = \frac{1-\alpha}{k-1}$ for all $j \neq j^*$. Then $(\{j^*\}, [k] \setminus \{j^*\})$ is the unique element of $\gamma_{OP}(p)$.

In particular, when $\alpha < 1/2$, $p$ violates the majority condition. Under SLN, we have $\text{arg max } p = \{j^*\}$ since $\alpha - \frac{1-\alpha}{k-1} = \frac{(k-1)\alpha - 1 + \alpha}{k-1} = \frac{k\alpha - 1}{k-1} > \frac{1-1}{k-1} = 0$. In light of Theorem 5.2, we have

Corollary 5.5. If $p \in \Delta^k$ satisfies the majority or the SLN condition, then $p \in \Omega_{LWW}$.

This supports the observation by Doğan et al. [1] that the WW-SVM performs well even without the majority condition. For the CS-hinge loss, it is known that $\Omega_{LCS} = \{p \in \Delta^k : p \text{ satisfies the majority condition}\}$ [5, Lemma 4]. In particular, $\Omega_{LCS}$ is a proper subset of $\Omega_{LWW}$. For $k = 3$, we show in Figure 2 the regions $\Omega_{LWW}$ and $\Omega_{LCS}$.

6 Conclusion and future work

We proved that the Weston-Watkins hinge loss is calibrated with respect to the ordered partition loss, which we argue is maximally informative for the WW-hinge loss. Furthermore, we showed the advantage of WW-hinge loss over the Crammer-Singer hinge loss when the popular “argmax” link is used. An interesting direction is to apply the ordered partition loss to other multiclass learning problems such as partial label and multilabel learning.
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Appendices

A Organization of contents

In Appendix A, we introduce notations in addition to those already defined in the main article’s Section 1.3.

In Appendices B to E, we present the proofs and supporting theory for all results from Sections 3 to 5, respectively.

In Appendix F, we discuss how Figures 1 and 2 are obtained.

B Additional notations

- Below, $L$ always denotes the WW-hinge loss (Definition 1.4) and $\ell$ always denotes the ordered partition loss (Definition 2.2).
- All vectors are column vectors unless stated otherwise.
- $\mathbb{R}_+$ and $\mathbb{Z}_+$ denotes the set of non-negative reals and integers, respectively.
- Define $\mathbb{R}^k_+ = \{ v \in \mathbb{R}^k : v_1 \leq v_2 \leq \cdots \leq v_k \}$. Likewise, define $\mathbb{R}^k_-$. 
- For a positive integer $n$, we let $[n] := \{1, \ldots, n\}$. By convention, $[0] = \emptyset$.
- Let $1_k \in \mathbb{R}^k$ denote the vector all ones.
- For a number $t \in \mathbb{R}$, let $[t]_+ = \max\{0, t\}$. For a vector $v$, we denote by $[v]_+$ the vector resulting from applying $[\cdot]_+$ entrywise to $v$. The hinge loss $h : \mathbb{R} \to \mathbb{R}_+$ is defined by $h(x) = [1 - x]_+$.
- For a vector $v \in \mathbb{R}^k$, we use $[v]_i$ to denote the $i$-th entry of $v$ in conjunction with the usual notation $v_i$.
- Given a vector $v \in \mathbb{R}^k$, we define $\max v := \max_{i \in [k]} v_i$ and $\arg \max v := \{ i \in [k] : v_i = \max v \}$.
- Probability simplex $\Delta^k = \{ p = (p_1, \ldots, p_k) \in \mathbb{R}^k_+ : p_1 + \cdots + p_k = 1 \}$ and non-increasing probability simplex $\Delta^k_+ = \{ p \in \Delta^k_+ : p_1 \geq p_2 \geq \cdots \geq p_k \} = \Delta^k \cap \mathbb{R}^k_+$.
- For $p \in \Delta^k$, we write $Y \sim p$ to denote a discrete random variable $Y \in [k]$ whose probability mass function is $p$.
- For each $i, j \in [k]$, $\sigma_{(i,j)} \in \mathbb{R}^{k \times k}$ is the permutation matrix that switches the $i$-th and $j$-th index. By convention, if $i = j$, then $\sigma_{(i,i)}$ is the identity. Also, for brevity, define $\sigma_i = \sigma_{(1,i)}$.
- According to the definition above, $\sigma_{(i,j)}$ acts on $\mathbb{R}^k$. However, we abuse notation and allow $\sigma_{(i,j)}$ to act on $[k]$ in the obvious way. In such cases, we write $\sigma_{(i,j)}(\ell)$ for $\ell \in [k]$. 

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C Main results

Lemma C.1. For all \( v \in \mathbb{R}^k \) and \( c \in \mathbb{R} \), we have \( L(v) = L(v + c \mathbf{1}^k) \).

Proof. For all \( y \in [k] \), we have that
\[
[L(v + c \mathbf{1})]_y = \sum_{i \in [k] : i \neq y} h(v_y + c - (v_i - c)) = \sum_{i \in [k] : i \neq y} h(v_y - v_i) = [L(v)]_y.
\]
\[\square\]

Lemma C.2. For all \( j \in [k] \), we have \( L(\sigma_j v) = \sigma_j L(v) \).

Proof. If \( j = 1 \), then the result is trivial. Hence, let \( j > 1 \). We prove
\[
[L(\sigma_j v)]_y = [L(v)]_{\sigma_j(y)}
\]
for the following three cases: \( y \notin \{1, j\} \), \( y = 1 \) and \( y = j \). Before we go through the cases, note that
\[
[L(\sigma_j v)]_y = \sum_{i \in [k] : i \neq y} h([\sigma_j v]_y - [\sigma_j v]_i) = \sum_{i \in [k] : i \neq y} h(v_{\sigma_j(y)} - v_{\sigma_j(i)}).
\]

Now, for the first case, suppose that \( y \notin \{1, j\} \). Then \( \sigma_j(y) = y \) and so
\[
[L(\sigma_j v)]_y = \sum_{i \in [k] : i \neq y} h(v_y - v_{\sigma_j(i)})
\]
\[
= h(v_y - v_{\sigma_j(1)}) + h(v_y - v_{\sigma_j(j)}) + \sum_{i \in [k] : i \notin \{1, j\}} h(v_y - v_{\sigma_j(i)})
\]
\[
= h(v_y - v_j) + h(v_y - v_1) + \sum_{i \in [k] : i \notin \{1, j\}} h(v_y - v_i)
\]
\[
= \sum_{i \in [k] : i \neq y} h(v_y - v_i)
\]
\[
= [L(v)]_y = [L(v)]_{\sigma_j(y)}.
\]

Next, suppose that \( y = 1 \). Thus, we have \( \sigma_j(y) = \sigma_j(1) = j \). So
\[
[L(\sigma_j v)]_y = [L(\sigma_j v)]_1 = \sum_{i \in [k] : i \neq 1} h(v_j - v_{\sigma_j(i)})
\]
\[
= \sum_{i \in [k] : i \neq j} h(v_j - v_i)
\]
\[
= [L(v)]_j = [L(v)]_{\sigma_j(y)}.
\]

Finally, if \( y = j \), \( \sigma_j(y) = 1 \)
\[
[L(\sigma_j v)]_y = [L(\sigma_j v)]_j = \sum_{i \in [k] : i \neq j} h(v_1 - v_{\sigma_j(i)})
\]
\[
= \sum_{i \in [k] : i \neq 1} h(v_1 - v_i)
\]
\[
= [L(v)]_1 = [L(v)]_{\sigma_j(j)} = [L(v)]_{\sigma_j(y)}.
\]
\[\square\]
Lemma C.3. Let $i, j \in \{2, \ldots, k\}$ be distinct. Then $\sigma_i \sigma_j \sigma_i = \sigma_{(i,j)}$.

Proof. This is simply an exhaustive case-by-case proof over all inputs $y \in [k]$. First, let $y = 1$. Then $\sigma_{(i,j)}(1) = 1$ since $1 \notin \{i, j\}$. On the other hand $\sigma_i \sigma_j \sigma_i(1) = \sigma_i \sigma_j(i) = \sigma_i(i) = 1$. Now, let $y \in \{2, \ldots, k\}$. If $y \notin \{i, j\}$, then $\sigma_{(i,j)}(y) = y$ and $\sigma_i \sigma_j \sigma_i(y) = \sigma_i \sigma_j(y) = \sigma_i(y) = y$. If $y = i$, then $\sigma_{(i,j)}(i) = j$ and $\sigma_i \sigma_j \sigma_i(i) = \sigma_i \sigma_j(1) = \sigma_i(j) = j$. If $y = j$, then $\sigma_{(i,j)}(j) = i$ and $\sigma_i \sigma_j \sigma_i(j) = \sigma_i \sigma_j(j) = \sigma_i(1) = i$. □

Corollary C.4. Every $\sigma \in S_k$ can be written as a product $\sigma = \sigma_{i_1} \sigma_{i_2} \cdots \sigma_{i_m}$.

Proof. We prove the equivalent statement that the set $S := \{\sigma_i : i \in \{2, \ldots, k\}\}$ generates the group $S_k$. A standard result in group theory states that the set of transpositions $T$ generates $S_k$. By Lemma C.3, transpositions between labels in $\{2, \ldots, k\}$ can be generated by $S$. Furthermore, $\sigma_i = \sigma_{(1,i)}$ by definition, so transposition between 1 and elements of $\{2, \ldots, k\}$ can be generated by $S$ as well. Hence, all of $T$ can be generated by $S$. □

Corollary C.5. For all $v \in \mathbb{R}^k$ and $\sigma \in S_k$, we have

$$L(\sigma v) = \sigma L(v).$$

Proof. By Corollary C.4 we may write $\sigma = \sigma_{i_1} \sigma_{i_2} \cdots \sigma_{i_m}$. Hence,

$$L(\sigma v) = L(\sigma_{i_1} \sigma_{i_2} \cdots \sigma_{i_m} v) = \sigma_{i_1} L(\sigma_{i_2} \cdots \sigma_{i_m} v) = \cdots = \sigma_{i_1} \sigma_{i_2} \cdots \sigma_{i_m} L(v) = \sigma L(v),$$

where for eq. (7) to eq. (8) we used Lemma C.2. □

Lemma C.6. Let $v \in \mathbb{R}^k$ and $j, j' \in [k]$ be distinct such that $v_j \geq v_{j'}$. Then $[L(v)]_j \leq [L(v)]_{j'}$. Furthermore, if $v_j > v_{j'}$, then $[L(v)]_j < [L(v)]_{j'}$.

Proof. We have

$$[L(v)]_j - [L(v)]_{j'} = \sum_{i \in [k] : i \neq j} h(v_j - v_i) - \sum_{i \in [k] : i \neq j'} h(v_{j'} - v_i)$$

$$= h(v_j - v_{j'}) + \sum_{i \in [k] : i \notin \{j, j'\}} h(v_j - v_i) - h(v_{j'} - v_j) - \sum_{i \in [k] : i \notin \{j, j'\}} h(v_{j'} - v_i)$$

$$= h(v_j - v_{j'}) - h(v_{j'} - v_j) + \sum_{i \in [k] : i \notin \{j, j'\}} h(v_j - v_i) - h(v_{j'} - v_i).$$

Since and $h$ is monotonically non-increasing, we have

$$v_j - v_{j'} \geq 0 \geq v_{j'} - v_j \implies h(v_j - v_{j'}) - h(v_{j'} - v_j) \leq 0$$

(10)
Proof. Define \( u \) as in step 2 above. Let \( \tau \) be such that \( \tau d = \tau c \). Hence, we have 
\[
\tau v = \tau p, \quad \tau p = \tau v, \quad \tau v = \tau q.
\]

Thus, we have 
\[
\tau v \leq \tau q = \tau q.
\]

For reasons that will become clear later, we define for each \( n \in [k - 1] \)
\[
\L_n(p) := \inf_{v \in \mathbb{R}^k : |\arg \max v| \geq n} \langle p, L(v) \rangle.
\]

Since \( \arg \max v \) is always nonempty, the condition that \( |\arg \max v| \geq n \) is always true. Thus, we have \( \L_1 = L \).

Lemma C.7. For all \( n \in [k - 1] \), \( p \in \Delta^k \) and \( \sigma \in \mathcal{S}_k \), we have \( \L_n(p) = \L_n(\sigma p) \).

Proof. Define \( \mathcal{R}^{k,n} := \{ v \in \mathbb{R}^k : |\arg \max v| \geq n \} \). Since \( |\arg \max v| = |\arg \max \sigma v| \), we have \( \sigma \mathcal{R}^{k,n} = \mathcal{R}^{k,n} \).

Introducing the change of variables \( u = \sigma v \), we have
\[
\L_n(p) = \inf_{v \in \mathbb{R}^k} \langle p, L(v) \rangle = \inf_{\sigma' \in \sigma \mathcal{S}_k} \inf_{\sigma' \in \mathcal{R}^{k,n}} \langle p, L(\sigma' u) \rangle = \inf_{\sigma' \in \mathcal{R}^{k,n}} \langle p, L(\sigma' u) \rangle = \inf_{\sigma' \in \mathcal{R}^{k,n}} \langle \sigma p, L(u) \rangle = \L_n(\sigma p).
\]

Lemma C.8. Let \( p \in \mathbb{R}^k_+ \), \( q \in \mathbb{R}^k \) be arbitrary and \( \sigma \in \mathcal{S}_k \) be such that \( \sigma q \in \mathbb{R}^k_+ \). Then \( \langle p, q \rangle \geq \langle p, \sigma q \rangle \).

Proof. Consider the “bubble sort” algorithm applied to \( q \):

1. Initialize \( q^{(0)} = q \), \( t \leftarrow 0 \)
2. While there exists \( i \in [k - 1] \) such that \( q_i^{(t)} > q_{i+1}^{(t)} \), do:
   a. \( q_i^{(t+1)} \leftarrow \sigma_i^{(t+1)} q_i^{(t)} \)
   b. \( t \leftarrow t + 1 \)
3. Output monotone non-decreasing vector \( q^{(t)} \)

We claim that at every step, we have \( \langle p, q^{(t)} \rangle \geq \langle p, q^{(t+1)} \rangle \). Let \( a = q_i^{(t)} \) and \( b = q_{i+1}^{(t)} \) as in step 2 above. Let \( c = p_i \) and \( d = p_{i+1} \). Hence, we have \( a > b \) and \( c \geq d \). Observe that
\[
\langle p, q^{(t)} \rangle - \langle p, q^{(t+1)} \rangle = ac + bd - (ad + bc) = (a - b)(c - d) \geq 0
\]
which proves the claim. Thus, we have
\[
\langle p, q \rangle = \langle p, q^{(0)} \rangle \geq \langle p, q^{(1)} \rangle \geq \cdots \geq \langle p, q^{(t)} \rangle.
\]

By construction, there exists \( \tau \in \mathcal{S}_k \) such that \( \tau q = q^{(t)} \). We must have \( \tau q = \sigma q \) since both vectors are monotone non-increasing, although \( \tau \) may not equal \( \sigma \).
Define the matrix $T \in \mathbb{R}^{k \times k}$

$$T_{ij} = \begin{cases} 1 & i \geq j \\ 0 & \text{otherwise} \end{cases}$$ (12)

Also, define $D \in \mathbb{R}^{k \times k}$

$$D_{ij} = \begin{cases} 1 & i = j \\ -1 & i = j + 1 \\ 0 & \text{otherwise} \end{cases}$$

In other words, $D$ is the matrix with 1s on the main diagonal, $-1$s on the subdiagonal below the main diagonal, and 0 everywhere else. We have

$$[Dv]_i = \begin{cases} v_i & : i = 1 \\ v_i - v_{i-1} & : i > 1. \end{cases}$$

**Lemma C.9.** $D^{-1} = T$.

**Proof.** Using Gaussian elimination for inverting a matrix, it is easy to see that $D'T'$ is the identity. \qed

**Definition C.10.** Define the following sets:

$$\mathcal{M} = \{ v \in \mathbb{R}^k : v_1 = 0 \text{ and } 0 \leq v_i - v_{i+1}, \forall [k - 1] \},$$

$$\mathcal{C} = \{ v \in \mathbb{R}^k : v_1 = 0, v_k \leq -1, \text{ and } 0 \leq v_i - v_{i+1} \leq 1, \forall [k - 1] \},$$

$$\mathcal{M}_z = \mathcal{M} \cap \mathbb{Z}^k \text{ and } \mathcal{C}_z = \mathcal{C} \cap \mathbb{Z}^k.$$

**Lemma C.11.** We have the following equality of sets:

$$\mathcal{M}_z = \{-Ts : c \in \mathbb{Z}_+^k, c_1 = 0\}$$

$$\mathcal{C}_z = \{-Ts : s \in \{0, 1\}^k, s_1 = 0, \text{ and } \exists i \in \{2, \ldots, k\} : s_i = 1\}$$

**Proof.** If $v \in \mathcal{C}_z$, then we have $v_i \in \mathbb{Z}_+$ and $v_i - v_{i+1} \in [0, 1]$. These two conditions together imply that $v_i - v_{i+1} \in \{0, 1\}$ for all $i \in [k - 1]$. Hence, $-Dv \in \{0, 1\}^{k-1}$ with $[Dv]_1 = -v_1 = 0$. Let $-Dv = s$. Then Lemma C.9 implies that $-Ts = TDv = v$. By construction, $s_1 = 0$. Furthermore, if $s_i = 0$ for all $i \in [k]$, then we would have $v = 0$ as well, which contradicts the fact that $v_k \leq -1$. Hence, there must exist $i \in \{2, \ldots, k\}$ such that $s_i = 1$. Clearly, all $v \in \mathcal{C}_z$ arise this way. The statement about $\mathcal{M}_z$ is similar. \qed

**Lemma C.12.** Let $c \in \mathbb{Z}_+^k$ and define $s \in \{0, 1\}^k$ entrywise where for each $i \in [k], s_i = \mathbb{I}\{c_i \geq 1\}$. Then we have $[L(-Tc)]_y \geq [L(-Ts)]_y$ for all $y \in [k]$.

**Proof.** By definition, we have

$$[L(-Tc)]_y - [L(-Ts)]_y = \sum_{i \in [k] : i \neq y} h([Tc]_y - [-Tc]_i) - h([-Ts]_y - [-Ts]_i)$$

$$= \sum_{i \in [k] : i \neq y} h([Tc]_i - [Tc]_y) - h([Ts]_i - [Ts]_y)$$

It suffices to show that $h([Tc]_i - [Tc]_y) - h([Ts]_i - [Ts]_y) \geq 0$ for all $i \in [k]$ such that $i \neq y$.

First, consider when $i > y$. We have

$$[Tc]_i - [Tc]_y = \sum_{j=y+1}^{i} c_j$$

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Similarly, we have

\[ [Ts]_i - [Ts]_y = \sum_{j=y+1}^{i} s_j = \sum_{j=y+1}^{i} I(c_j \geq 1). \]

From this, we see that

\[ [Ts]_i - [Ts]_y \geq 1 \implies [Tc]_i - [Tc]_y \geq 1 \]
\[ [Ts]_i - [Ts]_y = 0 \implies [Tc]_i - [Tc]_y = 0. \]

For \( i > y \), we have \( h([Ts]_i - [Ts]_y) = h([Tc]_i - [Tc]_y). \)

Next, let \( i < y \). We have

\[ [Tc]_i - [Tc]_y = \sum_{j=i+1}^{y} -c_j. \]

Similarly, we have

\[ [Ts]_i - [Ts]_y = \sum_{j=i+1}^{y} -I(c_j \geq 1). \]

Since \( c_j \geq I\{c_j \geq 1\} \), we have \([Ts]_i - [Ts]_y \geq [Tc]_i - [Tc]_y\) which implies that \( h([Ts]_i - [Ts]_y) \leq h([Tc]_i - [Tc]_y) \). \( \square \)

**Definition C.13.** Let \( v = (v_1, \ldots, v_k) \in \mathbb{R}^k \). Define the linear map \( \pi : \mathbb{R}^k \to \mathbb{R}^{k-1} \)

\[ \pi(v) = (v_1 - v_2, v_1 - v_3, \ldots, v_1 - v_k). \]

We observe that for each \( i \in [k-1] \), we have

\[ [\pi v]_i = v_1 - v_{i+1}. \]

**Definition C.14.** Given \( k \geq 2 \), define the following \((k-1)\)-by-\((k-1)\) square matrices \( \rho_1, \rho_2, \ldots, \rho_k \in \mathbb{R}^{(k-1) \times (k-1)} \):

1. \( \rho_1 \) is the identity,

2. Let \( z = (z_1, \ldots, z_{k-1}) \in \mathbb{R}^{k-1} \) be a vector. For each \( i > 1 \), define \( \rho_i(z) \in \mathbb{R}^{k-1} \) entrywise for each \( j \in [k-1] \) by

\[ \rho_i(z)_{i-1} = \begin{cases} z_j - z_{i-1} : j \neq i - 1 \\ -z_{i-1} : j = i - 1. \end{cases} \] (13)

**Lemma C.15** (Commuting relations). For all \( i \in [k] \), we have \( \pi \sigma_i = \rho_i \pi \).

**Proof.** If \( i = 1 \), then \( \sigma_i \) and \( \rho_i \) are both identity matrices and there is nothing to show. Otherwise, suppose that \( i > 1 \). Consider \( v \in \mathbb{R}^k \). We first calculate \( \pi \sigma_i v \). For each \( j \in [k-1] \), we have

\[ [\pi \sigma_i v]_j = [\sigma_i v]_1 - [\sigma_i v]_{j+1} = v_1 - v_{\sigma_i(j+1)} = \begin{cases} v_i - v_{j+1} : i \neq j + 1 \\ v_i - v_1 : i = j + 1. \end{cases} \] (14)

Now, we compute \( \rho_i \pi v \). Likewise, for each \( j \in [k-1] \),

\[ [\rho_i \pi v]_j = \begin{cases} [\pi v]_j - [\pi v]_{i-1} : j \neq i - 1 \\ -[\pi v]_{i-1} : j = i - 1. \end{cases} \]

Consider the two cases above separately: for \( j \neq i - 1 \), we have

\[ [\pi v]_j - [\pi v]_{i-1} = (v_1 - v_{j+1}) - (v_i - v_i) = v_i - v_{j+1}. \]
On the other hand, for $i = j + 1$, we have

$$-[\pi v]_{i-1} = -(v_1 - v_i) = v_i - v_1.$$ 

Thus, we have $[\pi \sigma_i v]_j = \rho_i v_j$ for all $j$ which implies that $\pi \sigma_i v = \rho_i v$. Since $v$ was arbitrary, we have $\pi \sigma_i = \rho_i \pi$.

**Definition C.16.** The reduced WW hinge function $H : \mathbb{R}^{k-1} \to \mathbb{R}_{\geq 0}$ is defined as

$$H(z) = \sum_{i=1}^{k-1} h(z_i).$$

**Definition C.17.** For $z \in \mathbb{R}^{k-1}$, the reduced WW hinge loss $L(z) \in \mathbb{R}^k$ is defined entrywise for each $y \in [k]$ by

$$[L(z)]_y = H(\rho_y z).$$

**Lemma C.18.** For all $v \in \mathbb{R}^k$, we have $L(\pi v) = L(v)$.

**Proof.** We first check for all $y \in [k]$ that

$$\sum_{i \in [k] : i \neq y} h(v_y - v_i) = H(\pi \sigma_i v).$$

Unpacking the definition, we have $H(\pi \sigma_y v) = \sum_{i \in [k-1]} h([\pi \sigma_y v]_i)$. Now, if $y = 1$, then $[\pi v]_i = v_1 - v_{i+1}$ for all $i \in [k-1]$. Hence, eq. (16) holds. If $y > 1$, then eq. (17) follows from the expression for $[\pi \sigma_y v]_i$ computed in eq. (13). Thus, we have proven eq. (16) for all $y \in [k]$. To conclude, we have

$$[L(v)]_y = \sum_{i \in [k] : i \neq y} h(v_y - v_i) = H(\pi \sigma_y v) = H(\rho_y \pi v) = [L(\pi v)]_y$$

where in eq. (18), we applied Lemma C.15.

**Lemma C.19.** Let $n \in [k - 1]$. If $p \in \Delta_k^n$, then

$$L^n(p) = \min_{v \in \mathbb{R}^k : v_1 = \cdots = v_n = 0, v_i \leq 0, \forall i \in [k]} \langle p, L(v) \rangle.$$ 

**Proof.** Define

$$\mathcal{N}^n = \{v \in \mathbb{R}^k : v_1 = \cdots = v_n = 0, v_i \leq 0, \forall i \in [k] \}.$$ 

We first claim that

$$L^n(p) = \inf_{v \in \mathcal{N}_n} \langle p, L(v) \rangle.$$ 

Since $\mathcal{N}^n \subseteq \{v \in \mathbb{R}^k : |\arg \max v| \geq n \}$, the “$\leq$” part of eq. (20) is obvious. For the “$\geq$” part, let $v \in \mathbb{R}^k$ be such that $|\arg \max v| \geq n$. Then $w = v - 1^k \max_{i \in [k]} v_i$ is such that $w \in \mathcal{N}^n$. Furthermore, by Lemma C.1, we have $\langle p, L(w) \rangle = \langle p, L(v) \rangle$. Thus, we have proven the claim.

Next, observe that if $v \in \mathcal{N}^n$, then

$$[\pi v]_i = v_1 - v_{i+1} \begin{cases} = 0 & : i \leq n - 1 \\ \geq 0 & : i \geq n. \end{cases}$$
Therefore, we have
\[ \pi(\mathcal{N}^n) = \{ z \in \mathbb{R}^{k-1} : z \geq 0, z_i = 0, \forall i \in [n-1] \} \]
where \( [0] = \emptyset \). Introducing the change of variable \( z = \pi v \in \mathbb{R}^{k-1} \), we have
\[
\inf_{v \in \mathcal{N}^n} \langle p, L(v) \rangle = \inf_{v \in \mathcal{N}^n} \langle p, L(\pi v) \rangle \quad \therefore \text{Lemma C.18} \tag{21}
\]
\[
= \inf_{z \in \pi(\mathcal{N})} \langle p, L(z) \rangle \tag{22}
\]
\[
= \inf_{z \in \mathbb{R}^{k-1} : z \geq 0, z_i = 0, \forall i \in [n-1]} \langle p, L(z) \rangle \tag{23}
\]

Below, let \[ 1 := 1^{k-1} \]. Unwinding the definition, we have
\[
\langle p, L(z) \rangle = \sum_{i \in [k]} p_i H(\rho_i z) = \sum_{i \in [k]} p_i 1^\prime [1 - \rho_i z]_+ .
\]

Using slack variables \( \xi_i \geq [1 - \rho_i z]_+ \), we can rewrite eq. (23) as the following linear program:
\[
\min_{z \in \mathbb{R}^{k-1}} \min_{(\xi_1, \ldots, \xi_k) : \xi_i \in \mathbb{R}^{k-1}} \sum_{i \in [k]} p_i 1^\prime \xi_i \\
\text{s.t. } \begin{align*}
\xi_i &\geq 1 - \rho_i z \\
\xi_i &\geq 0, \quad \forall i \in [k] \\
z &\geq 0, \\
z_i = 0, \forall i \in [n-1].
\end{align*} \tag{24}
\]

By Bertsimas and Tsitsiklis [30] Corollary 3.2, for a linear programming minimization problem over a nonempty polyhedron, one of the following must be true: 1) the optimal cost is \(-\infty \) or 2) a feasible minimum exists. Since eq. (24) is nonnegative and the feasible region is nonempty, a feasible minimum exists. Let
\[
R = \begin{bmatrix} \rho_1 \\ \rho_2 \\ \vdots \\ \rho_k \end{bmatrix} \in \mathbb{R}^{k(k-1) \times (k-1)}, \\ X = \begin{bmatrix} \xi_1 \\ \xi_2 \\ \vdots \\ \xi_k \end{bmatrix} \in \mathbb{R}^{k(k-1)}, \\ p \otimes 1 = \begin{bmatrix} p_1 1 \\ p_2 1 \\ \vdots \\ p_k 1 \end{bmatrix} \in \mathbb{R}^{k(k-1)}.
\]

We claim that
\[
L^n(p) = \min_{z \in \mathbb{R}^{k-1} : z_i = 0, \forall i \in [n-1]} \langle p, L(z) \rangle . \tag{29}
\]

We first consider the case when \( n = 1 \) where we have \( L^1 = L_1 \). In this case, the linear program eq. (24) can be rewritten as
\[
L(p) = \min_{z \in \mathbb{R}^{k-1}} \min_{X \in \mathbb{R}^{k(k-1)}} \langle p \otimes 1 \rangle^\prime X \\
\text{s.t. } \begin{align*}
X + Rz &\geq 1 \\
X &\geq 0 \\
z &\geq 0.
\end{align*}
\]

For a positive integer \( m \), let \( I_m \) denote the \( m \times m \) identity matrix. Thus,
\[
\min_{z \in \mathbb{R}^{k-1}, X \in \mathbb{R}^{k(k-1)}} \langle p \otimes 1 \rangle^\prime X \\
\text{s.t. } \begin{bmatrix} R & I_{k(k-1)} \\ I_{k-1} & 0 \\ 0 & I_{k(k-1)} \end{bmatrix} \begin{bmatrix} z \\ X \end{bmatrix} \geq \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}. \tag{30}
\]

\[
\begin{bmatrix} R & I_{k(k-1)} \\ I_{k-1} & 0 \\ 0 & I_{k(k-1)} \end{bmatrix} \begin{bmatrix} z \\ X \end{bmatrix} \geq \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}. \tag{31}
\]
We prove that $A$ is totally unimodular (TUM). The matrix $R$ has the property that every row has at most one 1 and at most one $-1$, with all other entries being zeros. Hence, $R$ is TUM by the Hoffman’s sufficient condition Lawler [31]. Thus, (horizontally) concatenating $R$ with an identity matrix, i.e., $R_0 := \begin{bmatrix} R & I_{k(k-1)} \end{bmatrix}$ results in another TUM matrix $R_0$. Finally, $A$ is the (vertical) concatenation of $R_0$ with another identity matrix, i.e., $A = \begin{bmatrix} R_0 \\ I_{k(k-1)} \end{bmatrix}$. Hence, $A$ is also TUM.

By a well-known result in combinatorial optimization Lawler [31], there exists an integral solution $(X^*, z^*)$ to eq. (29). In particular, $z^* \in \mathbb{Z}_+^{k-1}$. Thus, we have

$$L(p) = \langle p, L(z^*) \rangle = \min_{z \in \mathbb{Z}_+^{k-1}} \langle p, L(z) \rangle.$$  

This proves eq. (29) for the case when $n=1$. For $n > 1$, we define the matrix $J \in \mathbb{R}^{(n-1) \times (k-1)}$ to be the first $n-1$ rows of the $(k-1)$-by-$(k-1)$ identity matrix. In other words, for $i \in [n-1]$ and $j \in [k-1]$,

$$J_{ij} = \begin{cases} 1 & : i = j \\ 0 & : i \neq j \end{cases}.$$  

Thus, we have

$$L^n(p) = \min_{z \in \mathbb{Z}^{k-1}, X \in \mathbb{R}^{k-1 \times (k-1)}} \langle p \otimes 1 \rangle' X \quad s.t. \quad \begin{bmatrix} R & I_{k(k-1)} \\ I_{k-1} & 0 \\ 0 & I_{k(k-1)} \\ -J & 0 \end{bmatrix} \begin{bmatrix} z \\ X \end{bmatrix} \geq \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}.$$  

The matrix $B$ is formed by duplicating rows of $A$ and multiplying the duplicated row by $-1$. Thus, $B$ is also TUM. This proves eq. (29).

Below, let $z^*$ be a solution to eq. (29). Define $v^* = \begin{pmatrix} 0 \\ -z^* \end{pmatrix}$. Furthermore, $\pi(v^*) = z^*$ and so

$$L^n(p) = \langle p, L(z^*) \rangle = \langle p, L(\pi(v^*)) \rangle = \langle p, L(v^*) \rangle.$$  

Pick $\sigma \in \mathcal{G}_k$ such that $\sigma v^* \in \mathbb{R}_+^k$. First we note that $L(\sigma v^*) \in \mathbb{R}_+^k$ by Lemma C.6 Next, by Corollary C.5 $L(\sigma v^*) = \sigma L(v^*)$. Hence, by Lemma C.8

$$\langle p, L(v^*) \rangle \geq \langle p, \sigma L(v^*) \rangle = \langle p, L(\sigma v^*) \rangle$$  

which implies that $\sigma v^*$ is optimal. Also, we observe that $\sigma v^* \in \mathcal{M}_Z$. By Lemma C.11 we can write $\sigma v^* = -Tc$ for some $c \in \mathbb{Z}_+^k$. Note that since $z^*_1 = \cdots = z^*_{n-1} = 0$, the vector $v^*$ has at least $n$ entries equal to 0. Since $v^* \leq 0$, we must have that $v_1 = \cdots = v_n = 0$. Thus, $c_1 = \cdots = c_n = 0$ as well. Let $s \in \{0,1\}^k$ be as defined in Lemma C.12 Then we have

$$L^n(p) \geq \langle p, L(\sigma v^*) \rangle = \langle p, L(-Tc) \rangle \geq \langle p, L(-Ts) \rangle.$$  

Hence, we have $L(p) = \langle p, L(Ts) \rangle$. Since $s_i = I\{c_i \geq 1\}$, we have $s_1 = \cdots = s_n = 0$ which implies that $[-Ts]_1 = \cdots = [-Ts]_n = 0$. Consider the case when there exists some $i \in \{n+1, \ldots, k\}$ such that $s_i = 1$, then we have $-Ts \in \mathcal{C}_Z$ which completes the proof of Lemma C.19 Now, consider the case where there does
not exists such \( i \). Then we must have \( s = 0 \) and also \(-T s = 0\). Therefore, we have \( L(p) = \langle p, L(0) \rangle \). Define \( \tilde{v} \in \mathbb{R}^k \) entrywise by

\[
[v]_i = \begin{cases} 
0 & : i \neq k \\
-1 & : i = k 
\end{cases}
\]

Noting that \( k \in \arg \min_{i \in [k]} p_i \) by the assumption that \( p \in \Delta^k_1 \). By Lemma C.20 below, we get that \( \langle p, L(\tilde{v}) \rangle \leq \langle p, L(0) \rangle \), which implies that \( \langle p, L(\tilde{v}) \rangle = L^(n)(v) \). Clearly, \( \tilde{v} \in C_2 \) and \( \tilde{v}_n = 0 \), which implies that \( \tilde{v} \) is feasible for the optimization in Lemma C.19.

**Lemma C.20.** Let \( p \in \Delta^k \) and \( i^* \in \arg \min_{i \in [k]} p_i \). Consider the vector \( \tilde{v} \in \mathbb{R}^k \) defined by

\[
[v]_i = \begin{cases} 
0 & : i \neq i^* \\
-1 & : i = i^* 
\end{cases}
\]

Then

1. \( p_{i^*} \leq \frac{1}{k} \)
2. \( p_i = \frac{1}{k} \) for all \( i \) if and only if \( p_{i^*} = \frac{1}{k} \)
3. \( \langle p, L(0) \rangle \geq \langle p, L(\tilde{v}) \rangle \) with equality if and only if \( p_{i^*} = \frac{1}{k} \).

**Proof.** If \( p_{i^*} > \frac{1}{k} \), then we would have \( \sum_i p_i \geq kp_{i^*} \geq 1 \), a contradiction. This proves that \( p_{i^*} \leq \frac{1}{k} \). For the second item, the “only if” direction is obvious. For the “if” direction, note that if \( p_i > \frac{1}{k} \) for any \( i \), then we again obtain \( \sum_i p_i > 1 \), a contradiction. For the third item, first observe that

\[
[L(0)]_i = \sum_{j \in [k] : j \neq i} h(0) = k - 1.
\]

Thus, \( L(0) = (k - 1)1^k \) and \( \langle p, L(0) \rangle = k - 1 \). Next, we only \( L(\tilde{v}) \). For \( i \neq i^* \), we have

\[
[L(\tilde{v})]_i = \sum_{j \in [k] : j \neq i} h(\tilde{v}_i - \tilde{v}_j) = h(1) + \sum_{j \in [k] : j \neq i, j \neq i^*} h(0) = k - 2.
\]

When \( i = i^* \), we have

\[
[L(\tilde{v})]_{i^*} = \sum_{j \in [k] : j \neq i^*} h(\tilde{v}_{i^*} - \tilde{v}_j) = \sum_{j \in [k] : j \neq i^*} h(-1) = 2(k - 1) = k - 2 + k.
\]

From this, we deduce that

\[
\langle p, L(\tilde{v}) \rangle = k - 2 + kp_{i^*}.
\]

Therefore, we have \( p_{i^*} \leq \frac{1}{k} \) and so

\[
\langle p, L(\tilde{v}) \rangle = k - 2 + kp_{i^*} \leq k - 2 + 1 = k - 1 = \langle p, L(0) \rangle.
\]

Note if \( p_{i^*} < \frac{1}{k} \), then the inequality above is strict.

**C.1 Proof of Theorem 3.7**

**Proof of Theorem 3.7**. Recall that \( L(p) = \min_{v \in \mathbb{R}^k} \langle p, L(v) \rangle \). Since \( \mathbb{R}^k \supseteq \mathbb{S}_k C_2 \), we immediately have \( L(p) \leq \min_{v \in \mathbb{S}_k C_2} \langle p, L(v) \rangle \). Below, we focus on the other inequality.

Pick \( \sigma \in \mathbb{S}_k \) such that \( \sigma p \in \Delta^k_1 \). By Lemma C.19 where \( n = 1 \), we have

\[
L(\sigma p) = \min_{v \in C_2} \langle \sigma p, L(v) \rangle.
\]
Now, by Corollary C.5 we have
\[
\langle \sigma p, L(v) \rangle = \langle p, \sigma' L(v) \rangle = \langle p, L(\sigma' v) \rangle.
\]
Thus,
\[
L(p) = L(\sigma p) \quad \because \text{Lemma C.7}
\]
\[
= \min_{v \in C_2} \langle p, L(\sigma' v) \rangle \\
= \min_{v \in \sigma' C_2} \langle p, L(\sigma' v) \rangle \quad \because \text{change of variables}
\]
\[
\geq \min_{v \in \sigma' C_2} \langle p, L(v) \rangle
\]
where for the last equality, we used the fact that $\sigma' C_2 \subseteq \sigma_2 C_2$.

\begin{lemma}
Let $s \in \{0,1 \}^k$ be such that $s_1 = 0$. Then
\[
[DL(-Ts)]_y = \begin{cases} 
\min \{ i \in [k] : s_i = 1 \} - 2 & : y = 1 \\
\min \{ i \in [k] : s_i = 1, i > y \} - 1 & : s_y = 1, y > 1 \\
0 & : s_y = 0, y > 1
\end{cases}
\]
\end{lemma}

\begin{proof}
By the definition of $T$, we have
\[
[Ts]_j = \sum_{i=1}^j s_i. \tag{33}
\]
First, consider the case when $y = 1$. Then by eq. (33) we have $[-Ts]_1 = 0$. Furthermore,
\[
[DL(-Ts)]_1 = [L(-Ts)]_1
\]
\[
= \sum_{i \in [k] : i \neq 1} h([-Ts]_1 - [-Ts]_i)
\]
\[
= \sum_{i \in [k] : i \neq 1} h([-Ts]_i)
\]
Note that by eq. (33), we have $[Ts]_i \geq 1$ if $i \geq \min \{ j : s_j = 1 \}$ and $[Ts]_i = 0$ otherwise. Hence, we get
\[
[DL(-Ts)]_1 = \sum_{i \in [k] : 1 < i < \min \{ j : s_j = 1 \}} h([Ts]_i)
\]
\[
= \sum_{i \in [k] : 1 < i < \min \{ j : s_j = 1 \}} 1
\]
\[
= \min \{ j \in [k] : s_j = 1 \} - 2.
\]
This proves the first case of eq. (32). Below, let $y > 1$. We have
\[
[DL(-Ts)]_y
\]
\[
= \sum_{i \in [k] : i \neq y} h([-Ts]_y - [-Ts]_i) - \sum_{i \in [k] : i \neq y-1} h([-Ts]_{y-1} - [-Ts]_i) \tag{35}
\]
\[
= \sum_{i \in [k] : i \neq y} h([Ts]_i - [Ts]_y) - \sum_{i \in [k] : i \neq y-1} h([Ts]_{i-1} - [Ts]_{y-1}) \tag{36}
\]
\[
= \sum_{i \in [k] : i < y-1} h([Ts]_y - [Ts]_i) - h([Ts]_{i-1} - [Ts]_{y-1}) \tag{37}
\]
\[
+ h([Ts]_{y-1} - [Ts]_y) - h([Ts]_y - [Ts]_{y-1}) \tag{38}
\]
\[
+ \sum_{i \in [k] : i > y} h([Ts]_i - [Ts]_y) - h([Ts]_i - [Ts]_{y-1}) \tag{39}
\]
If \(s_y = 0\), then \([Ts]_y = [Ts]_{y-1}\) and so we have \([DL(-Ts)]_y = 0\). This proves the last case of eq. \(32\).

Below, assume the setting of the second case, i.e., \(y > 1\) and \(s_y = 1\). We first evaluate eq. \(37\). Since \(i < y - 1\), we have

\[
([Ts]_i - [Ts]_y) - ([Ts]_i - [Ts]_{y-1}) = [Ts]_{y-1} - [Ts]_y = -1
\]

and

\[
([Ts]_i - [Ts]_{y-1}) \leq 0.
\]

The two preceding facts together imply that

\[
h([Ts]_i - [Ts]_y) - h([Ts]_i - [Ts]_{y-1}) = 1
\]

and so

\[
\sum_{i \in [k]: i < y-1} h([Ts]_i - [Ts]_y) - h([Ts]_i - [Ts]_{y-1}) = y - 2.
\]

Next, we evaluate eq. \(38\).

\[
h([Ts]_{y-1} - [Ts]_y) - h([Ts]_{y} - [Ts]_{y-1}) = h(-1) - h(1) = 2.
\]

Finally, we evaluate eq. \(39\). Since \(i > y\), we have

\[
[Ts]_i - [Ts]_y = \sum_{j=y+1}^{i} s_i.
\]

From this, we see that

\[
[Ts]_i - [Ts]_y = \begin{cases} 0 & : i < \min\{j \in [k]: j > y, s_j = 1\} \\ \geq 1 & : \text{otherwise}. \end{cases}
\]

Hence,

\[
h([Ts]_i - [Ts]_y) = \begin{cases} 1 & : i < \min\{j \in [k]: j > y, s_j = 1\} \\ 0 & : \text{otherwise}. \end{cases}
\]

On the other hand, \([Ts]_i - [Ts]_{y-1} = \sum_{j=y}^{i} s_i \geq s_y = 1\) and so \(h([Ts]_i - [Ts]_{y-1}) = 0\). Therefore,

\[
\sum_{i \in [k]: i > y} h([Ts]_i - [Ts]_y) - h([Ts]_i - [Ts]_{y-1}) = \min\{j \in [k]: j > y, s_j = 1\} - y - 1
\]

Putting it all together, we have

\[
[DL(-Ts)]_y = y - 2 + 2 + \min\{j \in [k]: j > y, s_j = 1\} - y - 1 = \min\{j \in [k]: j > y, s_j = 1\} - 1.
\]

\[\square\]

### C.2 Proof of Theorem 3.8

**Proof of Theorem 3.8** Let \(S = (S_1, \ldots, S_l) \in \mathcal{OP}_k\). Pick \(\sigma\) such that \(\sigma\varphi(S)\) is monotonic non-increasing. Hence, we have

\[
\sigma\varphi(S) = -[\underbrace{0, \ldots, 0}_{|S_1|\text{-times}}, \underbrace{1, \ldots, 1}_{|S_2|\text{-times}}, \ldots, \underbrace{l-1, \ldots, l-1}_{|S_l|\text{-times}}].
\]

For each \(i = 1, \ldots, l - 1\), define \(c_i(S) = |S_1| + \cdots + |S_i|\).
Note that
\[ S_1 \cup \cdots \cup S_i = \{ j \in [k] : 0 \geq \varphi(S)_j \geq -(i - 1) \} = \{ \sigma(1), \sigma(2), \ldots, \sigma(c_i(S)) \}. \]

Also, note that by definition, \( c_i(S) \) is precisely the index in \([k - 1]\) such that
\[
\begin{cases}
[\sigma \varphi(S)]_{c_i(S)} = -(i - 1) \\
[\sigma \varphi(S)]_{c_i(S) + 1} = -i.
\end{cases}
\]

Motivated by this, we define \( \zeta(S) \in \{0, 1\}^k \) where
\[
[\zeta(S)]_j = \begin{cases}
1 & : j = c_i(S) + 1 \text{ for some } i = 1, \ldots, l - 1 \\
0 & : \text{otherwise}.
\end{cases}
\]

Then
\[ \sigma \varphi(S) = -T \zeta(S). \]

Next, note that
\[
\langle p, L(\varphi(S)) \rangle = \langle p, L(\sigma' \sigma \varphi(S)) \rangle = \langle p, \sigma' L(\sigma \varphi(S)) \rangle = \langle \sigma' p, L(\sigma \varphi(S)) \rangle = \langle T'(\sigma p), DL(\sigma \varphi(S)) \rangle = \langle T'(\sigma p), DL(-T \zeta(S)) \rangle
\]

where eq. (43) is by \( \sigma' = \sigma^{-1} \), eq. (44) is by Corollary \( \text{Cor} C.5 \), eq. (45) is by Lemma \( \text{Lem} C.9 \), eq. (46) is by eq. (42).

We first calculate \( DL(-T \zeta(S)) \) by applying eq. (32) from Lemma \( \text{Lem} C.21 \) to \( s = \zeta(S) \). For the case \( y = 1 \) of eq. (32), we have
\[
[DL(-T \zeta(S))]_1 = \min\{j \in [k - 1] : [\zeta(S)]_j = 1\} - 2 = c_1(S) + 1 - 2 = |S_1| - 1.
\]

By definition, for \( y > 1 \), we note that \( [\zeta(S)]_y = 1 \) if and only if \( y = c_i(S) + 1 \) for some \( i \in \{1, \ldots, l - 1\} \).
Thus,
\[
[DL(-T \zeta(S))]_{c_i(S)+1} = \min\{j \in [k] : [\zeta(S)]_j = 1, j > c_i(S) + 1\} - 1 = (c_{i+1}(S) + 1) - 1 = c_{i+1}(S).
\]

We summarize the above as follows:
\[
[DL(-T \zeta(S))]_y = \begin{cases}
|S_1| - 1 & : y = 1 \\
c_{i+1}(S) & : y = c_i(S) + 1 \text{ for some } i \in [l - 1] \\
0 & : \text{otherwise}.
\end{cases}
\]

Next, we calculate \( T'(\sigma p) \). Note that
\[
[T'(\sigma p)]_y = p_{\sigma(y)} + p_{\sigma(y+1)} + \cdots + p_{\sigma(k)} = 1 - (p_{\sigma(1)} + \cdots + p_{\sigma(y-1)}).
\]
In particular, \([T'(\sigma p)]_1 = 1\). Hence,
\[
\langle p, L(\varphi(S)) \rangle \\
= \langle T'(\sigma p), DL(-T\zeta(S)) \rangle \\
= [T'(\sigma p)]_1 (|S_1| - 1) \\
+ \sum_{i=1}^{l-1} ([T'(\sigma p)]_{c_i(S)+1}) c_{i+1}(S) \\
= |S_1| - 1 \\
+ \sum_{i=1}^{l-1} (1 - (p_{\sigma(1)} + \cdots + p_{\sigma(c_i(S))})) c_{i+1}(S).
\]
Recall from eq. (41)
\[
\{\sigma(1), \sigma(2), \ldots, \sigma(c_i(S))\} = S_1 \cup \cdots \cup S_i.
\]
Hence,
\[
(1 - (p_{\sigma(1)} + \cdots + p_{\sigma(c_i(S))})) = \Pr_{Y \sim p} (Y \notin S_1 \cup \cdots \cup S_i).
\]
Putting it all together, we have
\[
\langle p, L(\varphi(S)) \rangle = |S_1| - 1 + \sum_{i=1}^{l-1} |S_1 \cup \cdots \cup S_{i+1}| \Pr_{Y \sim p} (Y \notin S_1 \cup \cdots \cup S_i) \\
= E_{Y \sim p} [\ell(S|Y)] \\
= \langle p, \ell(S) \rangle.
\]
This concludes the proof of Theorem 3.8.

\section*{D Maximally informative losses}

We first introduce some basic properties of hyperplane arrangements that will be needed later.

\begin{definition}
A hyperplane in \(\mathbb{R}^d\) is a subset \(H \subseteq \mathbb{R}^d\) of the form \(H = \{v \in \mathbb{R}^k : b - \langle a, v \rangle = 0\}\) for some (column) vector \(a \in \mathbb{R}^k\) and \(b \in \mathbb{R}\).
\end{definition}

\begin{definition}
A hyperplane arrangement is a set of hyperplanes \(\{H_n\}_{n \in I}\) indexed by a finite set \(I\). Let the hyperplanes be written as \(H_n = \{v \in \mathbb{R}^k : b^{(n)} - \langle a^{(n)}, v \rangle = 0\}\) for each \(n \in I\).
\end{definition}

\begin{definition}
Define \(s : \mathbb{R}^k \to \{-1, 0, 1\}^I\) entrywise by
\[
[s(v)]_n = \text{sgn} \left( b^{(n)} - \langle a^{(n)}, v \rangle \right), \text{ where } \forall t \in \mathbb{R}, \text{sgn}(t) = \begin{cases} 
1 & : t > 0 \\
0 & : t = 0 \\
-1 & : t < 0
\end{cases}.
\]
3. Define the set \(\Theta := s(\mathbb{R}^k) \subseteq \{-1, 0, 1\}^I\).
4. For each \(\theta \in \Theta\), define
\[
\tilde{P}_\theta := s^{-1}(\theta) = \{v \in \mathbb{R}^k : s(v) = \theta\} \text{ and } P_\theta := \text{cl}(\tilde{P}_\theta)
\]
where \(\text{cl}\) denotes the closure of a set in \(\mathbb{R}^k\) with the Euclidean topology.
The following are true:

1. For all \( \theta \in \Theta \), \( \tilde{P}_\theta = \left\{ v \in \mathbb{R}^k : \theta_n (b^{(n)} - \langle a^{(n)}, v \rangle) > 0 : \theta_n \neq 0 \right\} \),

2. For all \( \theta \in \Theta \), \( P_\theta = \left\{ v \in \mathbb{R}^k : \theta_n (b^{(n)} - \langle a^{(n)}, v \rangle) \geq 0 : \theta_n = 0 \right\} \),

3. For all \( \theta \in \Theta \), \( \text{relint}(P_\theta) = \tilde{P}_\theta \),

4. \( \bigsqcup_{\theta \in \Theta} \text{relint}(P_\theta) = \mathbb{R}^k \) as a disjoint union.

**Proof.** First, we note that item 1 follows directly from definition.

For item 2, let \( Q_\theta \) denote the set on the right hand side of the identity. We want to show that \( P_\theta = Q_\theta \). Recall that \( P_\theta = \text{cl}(\tilde{P}_\theta) \) is by definition the smallest closed set containing \( \tilde{P}_\theta \). Clearly, \( Q_\theta \) is a closed set. Furthermore, by item 1 we have \( \tilde{P}_\theta \subseteq Q_\theta \). Thus, we have the \( P_\theta \subseteq Q_\theta \).

Conversely, let \( v \in Q_\theta \) and \( w \in \tilde{P}_\theta \). Then by item 1 we have that \( (1-\lambda)w + \lambda v \in \tilde{P}_\theta \) for all \( \lambda \in [0,1] \). Now, \( \lim_{\lambda \to 1} (1-\lambda)w + \lambda v = v \). Since \( \text{cl}(\tilde{P}_\theta) \) is closed, it contains all limits. Hence \( v \in \text{cl}(\tilde{P}_\theta) = P_\theta \), as desired. This proves that \( Q_\theta \subseteq P_\theta \), as desired.

Next, we prove item 3. From the first paragraph of Ben-Tal and Nemirovski [32, Section 1.1.6.D], we have \( \text{relint}(P_\theta) \subseteq \tilde{P}_\theta \subseteq \text{cl}(\tilde{P}_\theta) \). By Ben-Tal and Nemirovski [32, Theorem 1.1.1 (iv)], we have \( \text{relint}(P_\theta) = \text{relint}(\text{cl}(\tilde{P}_\theta)) \). By definition \( P_\theta = \text{cl}(\tilde{P}_\theta) \). Putting it all together, we get \( \text{relint}(P_\theta) \subseteq P_\theta \).

For the other inclusion, let \( v \in \tilde{P}_\theta \). Let

\[ W = \left\{ v \in \mathbb{R}^k : b^{(n)} - \langle a^{(n)}, v \rangle = 0, \ \forall n \in I \text{ such that } \theta_n = 0 \right\}. \]

Then by item 2 \( W \) is an affine subspace containing \( P_\theta \). Thus, by definition of the affine hull, we have \( W \supseteq \text{Aff}(P_\theta) \). Furthermore, by item 1 we have, for all \( \epsilon > 0 \) sufficiently small, that \( W \cap \{ w \in \mathbb{R}^k : \| w - v \| < \epsilon \} \subseteq P_\theta \). This proves that \( v \in \text{relint}(P_\theta) \) and so \( \tilde{P}_\theta \subseteq \text{relint}(P_\theta) \).

Finally, we prove item 4

\[ \bigsqcup_{\theta \in \Theta} \text{relint}(P_\theta) = \bigsqcup_{\theta \in \Theta} \tilde{P}_\theta = \bigsqcup_{\theta \in \mathbb{R}^k} s^{-1}(\theta) = \mathbb{R}^k, \]

where for the middle equality, we recall that \( \Theta = s(\mathbb{R}^k) \) by definition. \( \square \)

### D.1 Semiordered hyperplane arrangement

Below, we apply the results of Lemma [D.4] to the “semiorder hyperplane arrangement”, which is closely connected to the WW-hinge loss.

**Definition D.5.** The semiorder hyperplane arrangement is the hyperplane arrangement in \( \mathbb{R}^k \) indexed by the finite set \( I = \{ (i,j) \in [k] \times [k] : i \neq j \} \) with the \( (i,j) \)-th hyperplane given by \( H_{(i,j)} = \{ v \in \mathbb{R}^k : 1 - (v_i - v_j) = 0 \} \).
Lemma D.6. Let $L : \mathbb{R}^k \rightarrow \mathbb{R}^k$ be the WW-hinge loss and $\mathfrak{S}_kC_Z$ be as in Definition D.3. Let $\{H_{(i,j)}\}_{(i,j) \in I}$ be the semiorder hyperplane arrangement as in Definition D.5. Adopt all notations from Definition D.2.

Then we have for all $\theta$ that

1. the restriction of $L$ to $P_\theta$, denoted $L|_{P_\theta}$, is an affine function,

2. $P_\theta \cap \mathfrak{S}_kC_Z$ is nonempty.

Proof. For the first item, fix some $i \in [k]$ and note that

$$[L(v)]_i = \sum_{j \in [k]: j \neq i} \max\{0, 1 - (v_i - v_j)\}.$$ 

Fix $(i, j) \in I$ where $I$ is as in Definition D.5. Then by Lemma D.4 item 2, for all $v \in P_\theta$, we have

$$\max\{0, 1 - (v_i - v_j)\} = \begin{cases} 1 - (v_i - v_j) & : \theta_{(i,j)} = 1 \\ 0 & : \text{otherwise.} \end{cases}$$

In either case, $\max\{0, 1 - (v_i - v_j)\}$ is affine over $P_\theta$.

Next, we prove the second item. Define $H_0 = \{v \in \mathbb{R}^k : \sum_{i \in [k]} v_i = 0\}$. Then $H_0 \cap P_\theta$ is nonempty for all $\theta \in \Theta$. To see this, first note that $P_\theta$ is nonempty by construction. Furthermore, if $v \in P_\theta$ then $v + c1^k \in P_\theta$ as well for any $c \in \mathbb{R}$. Thus, $v + (-1/k) \sum_{i \in [k]} v_i 1^k \in H_0 \cap P_\theta$.

Lemma D.7. $H_0 \cap P_\theta$ does not contain any line.

Proof. Suppose that this is false, i.e., $l \subseteq H_0 \cap P_\theta$ where $l \subseteq \mathbb{R}^k$ is a line. In particular, $l \subseteq H_0$. This means that $l = \{cw : c \in \mathbb{R}\}$ where $w \in H_0$ is a nonzero vector. Thus, there exists $i \neq j$ such that $w_i > 0$ and $w_j < 0$. Recall from Definition D.2 that $[s(cw)]_{(i,j)} = \text{sgn}(1 - c(w_i - w_j))$. Thus, as $c$ ranges over $\mathbb{R}$, we have that $[s(cw)]_{(i,j)}$ takes on all three values in $\{-1, 0, 1\}$. However, by Lemma D.4 item 2, $[s(cw)]_{(i,j)}$ can only take on at most two distinct values in $\{-1, 0, 1\}$.

Before proceeding, we recall a definition:

Definition D.8. A polyhedron $P$ in $\mathbb{R}^k$ is a set of the form $P = \{x \in \mathbb{R}^k : \langle a^{(n)}, x \rangle \leq b^{(n)}, \forall n \in [m]\}$ where $m$ is a positive integer, $a^{(n)} \in \mathbb{R}^k$ and $b^{(n)} \in \mathbb{R}$ for all $n \in [m]$. For each $n \in [m]$, the tuple $(a^{(n)}, b^{(n)})$ is called a constraint of $P$. A point $x \in P$ is a basic feasible solution (BFS) if there exists $n_1, \ldots, n_k \in [m]$ such that

1. $\langle a^{(n_i)}, x \rangle = b^{(n_i)}$ for all $i \in [k]$, and

2. $\mathcal{A} := \{a^{(n_1)}, \ldots, a^{(n_k)}\}$ is a basis for $\mathbb{R}^k$.

By Bertsimas and Tsitsiklis [30, Theorem 2.6] and [30, Theorem 2.3], a polyhedron which does not contain any line always has a BFS. Earlier, we proved that $H_0 \cap P_\theta$ does not contain any line. Hence, $H_0 \cap P_\theta$ contains a BFS. For the remainder of this proof, let $x \in \mathbb{R}^k$ be such a BFS with associated basis $\mathcal{A} = \{a^{(n_1)}, \ldots, a^{(n_k)}\}$ as in Definition D.8.

Let $e^i \in \mathbb{R}^k$ be the $i$-th elementary basis vector in $\mathbb{R}^k$. By definition of $P_\theta \cap H_0$, we have

$$\mathcal{A} \subseteq \{e^i - e^j : (i, j) \in I\} \cup \{1^k\}$$

where we recall that $I$ is as in Definition D.5. Observe that $\langle 1^k, e^i - e^j \rangle = 0$ for all $(i, j) \in I$. Hence, we must have that $1^k \in \mathcal{A}$, since otherwise $\mathcal{A}$ cannot span $\mathbb{R}^k$. This implies that we necessarily have $1^k \in \mathcal{A}$. Without the loss of generality, let $a^{(n_k)} = 1^k$. Since $\mathcal{A}$ is linearly independent, we have

$$\mathcal{B} := \mathcal{A} \setminus \{a^{(n_k)}\} = \{a^{(n_1)}, \ldots, a^{(n_{k-1})}\} \subseteq \{e^i - e^j : (i, j) \in I\}.$$
Now, for each \( i \in [k-1] \), let \( (t_i, h_i) \in I \) be such that \( a^{(n_i)} = e^{t_i} - e^{h_i} \). By the definition of \( P_\theta \), we have \( \langle a^{(n_i)}, x \rangle = x_{t_i} - x_{h_i} = \pm 1 \). Note that this implies that \( x \) is not a scalar multiple of \( 1^k \).

Next, consider the directed graph \( G \) with vertices \( V(G) = [k] \) and edges are \( E(G) = \{(t_i, h_i) : i \in [k-1]\} \). Since \( B \) is linearly independent, we observe that if \((t_i, h_i) \in E(G)\), then \((h_i, t_i) \not\in E(G)\). Let \( G^u \) be the undirected graph obtained from \( G \) by forgetting the edge orientations. By the preceding observation, we have \(|E(G^u)| = k - 1\). An undirected edge is denoted as \( \{\alpha, \beta\} \in E(G^u) \).

Observe that if \( \{\alpha, \beta\} \in E(G^u) \), then \( x_\alpha - x_\beta = \pm 1 \).

**Lemma D.9.** \( G^u \) is a tree, i.e., a connected graph without cycles.

**Proof.** Note that \( G^u \) does not contain any cycles. To see this, note that if \( G^u \) had a cycle, then \( A \) cannot be linearly independent. Thus, \( G^u \) is a disjoint union of trees \( \{T_1, \ldots, T_f\} \) where \( f \) is a positive integer. Since each \( T_i \) is a tree, we have \(|E(T_i)| = |V(T_i)| - 1\). On the other hand, we have

\[
\begin{align*}
k - 1 &= |E(G^u)| \\
&= |E(T_1)| + \cdots + |E(T_f)| \\
&= |V(T_1)| + \cdots + |V(T_f)| - f \\
&= |V(G^u)| - f \\
&= k - f
\end{align*}
\]

which implies that \( f = 1 \). In other words, \( G^u \) is a tree to begin with. \( \square \)

Although we know that \( G^u \) is a tree, we only need the fact that \( G^u \) is connected.

Let \( \alpha, \beta \in V(G^u) \). A path of length \( l \) from \( \alpha \) to \( \beta \) is a sequence \( \phi_1, \ldots, \phi_l \in V(G^u) \) such that

1. \( \phi_1 = \alpha \) and \( \phi_l = \beta \)
2. \( \{\phi_i, \phi_{i+1}\} \in E(G^u) \) for all \( i \in [m-1] \).

The fact that \( G^u \) is connected implies that there exists a path between any two vertices \( \alpha, \beta \in V(G^u) \). Define \( \overline{x} := \max x \) and \( \underline{x} := \min x \).

**Lemma D.10.** For all \( \beta \in [k] \), we have \( \overline{x} - x_\beta \in Z \).

**Proof.** Let \( \alpha \in \arg \max x \) and consider a path \( \phi_1, \ldots, \phi_l \in V(G^u) \) from \( \alpha \) to \( \beta \). Observe that \( x_\alpha - x_\beta = \sum_{i \in [l-1]} x_{\phi_i} - x_{\phi_{i+1}} \). Since \( \{\phi_i, \phi_{i+1}\} \in E(G^u) \), we have \( x_{\phi_i} - x_{\phi_{i+1}} = \pm 1 \). This proves that \( x_\alpha - x_\beta \in Z \). \( \square \)

Let \( D := \overline{x} - x_\beta \). Since \( x_\beta \geq \underline{x} \), we have \( 0 \leq \overline{x} - x_\beta \leq D \). Apply Lemma \[ \text{D.10} \] with \( \beta \in \arg \min x \), we get \( \overline{x} - \underline{x} = D \in Z \). In summarize, we have proven that

\[
\{x_\beta - \overline{x} : \beta \in [k]\} \subseteq \{-D, -D + 1, \ldots, -1, 0\}. \tag{48}
\]

Below, we will show that the inclusion in eq. (48) is in fact an equality.

Next, let \( \overline{x} \in \arg \max x \) and \( \underline{x} \in \arg \min x \). Let \( \phi_1, \ldots, \phi_l \in V(G^u) \) be a path between \( \overline{x} \) and \( \underline{x} \). Note that by definition we have

1. \( x_{\phi_1} = \overline{x} \) and \( x_{\phi_l} = \underline{x} \).
2. \( x_{\phi_i} - x_{\phi_{i+1}} = \pm 1 \) for all \( i \in [l-1] \).

Consider the sequence of numbers

\[
S := (x_{\phi_2} - \overline{x}, x_{\phi_2} - \overline{x}, \ldots, x_{\phi_{l-1}} - \overline{x}, x_{\phi_l} - \overline{x}).
\]
where the second equality is by Corollary 3.9.

Recall from right before eq. (50), we have that \( \ell \) is monotonic non-increasing. Earlier, we argued that \( x \) is not a scalar multiple of \( 1^k \). Thus, eq. (49) implies that \( \sigma x - 1^k \in C_\ell \). Consequently, we have \( x - 1^k \in S \). Since \( x \in P_\theta \), we have \( x - 1^k \in P_\theta \) as well. This proves that \( P_\theta \cap C_\ell \) is nonempty, which concludes the proof of Lemma D.4.

D.2 Proof of Proposition 4.2

Proof of Proposition 4.2. Let \( m = |\mathcal{OP}_k| \). Index the elements of \( \mathcal{OP}_k \) by \( [m] \), i.e.,

\[
\mathcal{OP}_k = \{S^1, \ldots, S^m\}.
\]

For each \( i \in [m] \), let \( p^{(i)} \in \Delta_k \) be such that \( \{S^i\} = \arg\min_{S \in \mathcal{OP}_k} \langle p, \ell(S) \rangle \). The existence of such \( p^{(i)} \)'s was confirmed by computer search for \( k \in \{3, \ldots, 7\} \). Equivalently, \( S^i \) is the unique element such that

\[
\langle p^{(i)}, \ell(S^i) \rangle = \min_{S \in \mathcal{OP}_k} \langle p, \ell(S) \rangle = L(p^{(i)})
\]

where the second equality is by Corollary 3.9.

Next, suppose \( L \) embeds another discrete loss \( \lambda : \mathcal{R} \rightarrow \mathbb{R}^k \) with embedding map \( \chi : \mathcal{R} \rightarrow \mathbb{R}^k \). Our goal is to show that \( |\mathcal{R}| \geq |\mathcal{OP}_k| \). To this end, let \( \mathcal{R} = \{i^1, \ldots, i^n\} \). Since \( L \) embeds \( \chi \) via \( v \), we have by definition that \( L(p^{(i)}) = \lambda(p) = \min_{v \in \mathcal{R}} \langle p, L(v) \rangle \). In particular, for a fixed \( i \in [m] \), there exists \( i(i) \in [n] \) such that \( \langle p^{(i)}, L(\chi(i(i))) \rangle = \min_{v \in \mathcal{R}} \langle p^{(i)}, L(v) \rangle \). Note that this defines a mapping

\[
i : [m] \rightarrow [n].
\]

Let \( v^{(i)} := \chi(i^{(i)}) \). Combined with eq. (50), we have

\[
\langle p^{(i)}, L(v^{(i)}) \rangle = L(p^{(i)}) = \ell(p^{(i)}).
\]

Consider \( \{P_{\theta}\}_{\theta \in \Theta} \) as in Lemma D.6. For each \( v \in \mathbb{R}^k \), let \( \theta(v) \in \Theta \) be the unique element such that \( v \in \Theta(v) \). The existence and uniqueness of \( \theta(v) \) is guaranteed by Lemma D.4 and item 4.

By eq. (52), we have \( v^{(i)} = \arg\min_{v \in \mathcal{R}} \langle p^{(i)}, L(v) \rangle \). By Lemma D.6 the function \( v \mapsto \langle p^{(i)}, L(v) \rangle \) is affine over the domain \( \Theta(v^{(i)}) \). Furthermore, it is minimized at \( v^{(i)} \in \Theta(v^{(i)}) \). Thus, by Ben-Tal and Nemirovski [32, Lemma 1.2.1], the function \( v \mapsto \langle p^{(i)}, L(v) \rangle \) is constant over the domain \( v \in \Theta(v^{(i)}) \). Since \( v^{(i)} \in \Theta(v^{(i)}) \) and \( \langle p^{(i)}, L(v^{(i)}) \rangle = L(p^{(i)}) \) by eq. (52), we have

\[
\langle p^{(i)}, L(v) \rangle = L(p^{(i)}), \quad \forall v \in \Theta(v^{(i)}). \tag{53}
\]

Next, recall that \( P_{\theta} \cap C_\ell \) is nonempty for all \( \theta \in \Theta \). In particular, \( P_{\theta(v^{(i)})} \cap C_\ell \) is nonempty. By Proposition 3.6, we have \( C_\ell \) consists of the form \( \varphi(S) \) for some \( S \in \mathcal{OP}_k \). Fix such an \( S \) so that \( \varphi(S) \in P_{\theta(v^{(i)})} \cap C_\ell \). Now,

\[
\langle p^{(i)}, L(\varphi(S)) \rangle \quad \overset{[50]}{=} \quad L(p^{(i)}) \quad \overset{[52]}{=} \quad \ell(p^{(i)}).
\]

Recall from right before eq. (50), we have that \( S^i \) is the unique element of \( \mathcal{OP}_k \) such that \( \langle p^{(i)}, L(\varphi(S^{(i)})) \rangle = \ell(p^{(i)}) \). This proves that \( S = S^i \). Thus, we have shown that

\[
P_{\theta(v^{(i)})} \cap C_\ell = \{\varphi(S^i)\}. \tag{54}
\]
Finally, we are now ready to prove that \( n = |R| \geq |\mathcal{OP}_k| = m \). It suffices to show that the mapping \( \iota : [m] \to [n] \) defined at eq. (51) is injective. Suppose that there exists distinct \( i, j \in [m] \) such that \( \iota(i) = \iota(j) \). Then

\[
\rho^{\iota(i)} = \rho^{\iota(j)}
\]

\[
\implies v^{\iota(i)} = v^{\iota(j)} \quad \therefore \text{definition of } v^{\iota} := \chi(r^{\iota(i)})
\]

\[
\implies \theta(v^{\iota(i)}) = \theta(v^{\iota(j)})
\]

\[
\implies P_{\theta(v^{\iota(i)})} \cap \mathcal{E}_k C_Z = P_{\theta(v^{\iota(j)})} \cap \mathcal{E}_k C_Z
\]

\[
\implies \{ \varphi(S^i) \} = \{ \varphi(S^j) \} \quad \therefore \text{eq. (54)}
\]

\[
\implies \varphi(S^i) = \varphi(S^j)
\]

\[
\implies S^i = S^j \quad \therefore \varphi \text{ is a bijection}
\]

which contradicts \( i \neq j \). Thus, we have that \( \iota : [m] \to [n] \) is injective which implies that \( n \geq m \).  

\[\square\]

### E  The argmax link

**Definition E.1.** For \( \sigma \in \mathcal{E}_k \) and \( S = (S_1, \ldots, S_l) \in \mathcal{OP}_k \), define \( \sigma(S) \in \mathcal{OP}_k \) by

\[
\sigma(S) = (\sigma(S_1), \ldots, \sigma(S_l))
\]

where \( \sigma(S_i) = \{ \sigma(j) : j \in S_i \} \) for each \( i \in [l] \).

**Lemma E.2.** For \( \sigma \in \mathcal{E}_k \) and \( S = (S_1, \ldots, S_l) \in \mathcal{OP}_k \), we have

\[
\sigma' \varphi(S) = \varphi(\sigma(S)).
\]

**Proof.** By definition, we have

\[
[\varphi(\sigma(S))]_j = -(i - 1), \quad \forall j \in \sigma(S_i).
\]

Since \( j \in \sigma(S_i) \iff \sigma^{-1}(j) \in S_i \), we have

\[
[\varphi(\sigma(S))]_j = -(i - 1), \quad \forall j \in [k] : \sigma^{-1}(j) \in S_i.
\]

Introduce the change of variable \( m = \sigma^{-1}(j) \), we have

\[
[\varphi(\sigma(S))]_{\sigma(m)} = -(i - 1), \quad \forall m \in S_i.
\]

On the other hand, we have

\[
[\sigma' \varphi(S)]_{\sigma(m)} = [\varphi(S)]_{\sigma' \sigma(m)} = [\varphi(S)]_m = -(i - 1), \quad \forall m \in S_i.
\]

This proves that \( \sigma' \varphi(S) = \varphi(\sigma(S)) \).

\[\square\]

**Corollary E.3.** For all \( S \in \mathcal{OP}_k \) and \( \sigma \in \mathcal{E}_k \), we have \( \sigma \ell(S) = \ell(\sigma' S) \).

**Proof.** Since \( \Delta^k \) spans \( \mathbb{R}^k \), it suffices to check that \( \langle p, \sigma \ell(S) \rangle = \langle p, \ell(\sigma' S) \rangle \) for all \( p \in \Delta^k \). To this end, we have

\[
\langle p, \ell(\sigma' S) \rangle = \langle p, L(\varphi(\sigma' S)) \rangle \quad \therefore \text{Theorem E.8}
\]

\[
= \langle p, L(\varphi(S)) \rangle \quad \therefore \text{Lemma E.2}
\]

\[
= \langle p, \sigma L(\varphi(S)) \rangle \quad \therefore \text{Corollary E.5}
\]

\[
= \langle \sigma' p, L(\varphi(S)) \rangle
\]

\[
= \langle \sigma' p, \ell(S) \rangle \quad \therefore \text{Theorem E.8}
\]

\[
= \langle p, \sigma \ell(S) \rangle
\]

as desired.  

\[\square\]
For $p \in \Delta^k$, define
\[
\gamma(p) := \arg\min_{s \in \mathcal{O}_p} \langle p, \ell(s) \rangle, \tag{55}
\]
\[
\Gamma(p) := \arg\min_{v \in \mathbb{R}^k} \langle p, L(v) \rangle. \tag{56}
\]

**Lemma E.4.** Let $p \in \Delta^k_+$, $v \in \Gamma(p)$, and $\sigma$ be such that $\sigma v \in \mathbb{R}^k_+$. Then $\sigma p = p$ and $\sigma v \in \Gamma(p)$.

**Proof.** Let $i \in [k-1]$ be such that $v_i < v_{i+1}$. We first prove that $p_i = p_{i+1}$. Let $\tau = \sigma(i,i+1)$. Since $\tau$ is a transposition, we have $\tau' = \tau$. Now,
\[
0 \leq \langle p, L(\tau v) \rangle - \langle p, L(v) \rangle \quad \because \text{Optimality of } v
\]
\[
= \langle p, \tau L(v) \rangle - \langle p, L(v) \rangle \quad \because \text{Corollary C.5}
\]
\[
= \langle \tau p, L(v) \rangle - \langle p, L(v) \rangle \quad \because \tau' = \tau.
\]
\[
= (p_{i+1} - p_i)[L(v)]_{i} + (p_i - p_{i+1})[L(v)]_{i+1}
\]
\[
= (p_{i+1} - p_i)[L(v)]_{i} - [L(v)]_{i+1}
\]
By Lemma C.6, we have $[L(v)]_{i} - [L(v)]_{i+1} > 0$. By assumption, we have $p_i \geq p_{i+1}$. If we have $p_i > p_{i+1}$, then
\[
\underbrace{(p_{i+1} - p_i)}_{<0} \underbrace{([L(v)]_{i} - [L(v)]_{i+1})}_{>0} < 0
\]
which is a contradiction. Hence, we must have $p_i = p_{i+1}$. Repeating the proof with the update $v \leftarrow \tau v$, we obtain a composition of transpositions
\[
\sigma := \sigma(i_1,i_1+1)\sigma(i_2,i_2+1) \cdots \sigma(i_m,i_m+1)
\]
such that $\sigma v \in \mathbb{R}^k_+$ and $\sigma p = p$. Finally,
\[
\sigma^* \mathcal{L}(p) = \langle p, L(v) \rangle = \langle p, \sigma' \sigma L(v) \rangle = \langle \sigma p, L(\sigma v) \rangle = \langle p, L(\sigma v) \rangle
\]
implies that $\sigma v \in \Gamma(p)$. \qed

**Lemma E.5.** Let $\sigma \in \mathfrak{S}_k$ and $v \in \mathbb{R}^k$. Then $\arg\max \sigma v = \sigma^{-1}(\arg\max v)$.

**Proof.** Let $M = \max v = \max \sigma v$.
\[
\arg\max \sigma v = \{ j \in [k] : [\sigma v]_j = M \}
\]
\[
= \{ j \in [k] : [v]_{\sigma(j)} = M \}.
\]
On the other hand,
\[
\sigma^{-1}(\arg\max v) = \{ j \in [k] : \sigma(j) \in \arg\max v \}
\]
\[
= \{ j \in [k] : [v]_{\sigma(j)} = M \}
\]
\[
= \arg\max \sigma v
\]
as desired. \qed

**Lemma E.6.** Let $p \in \Delta^k_+$ be such that $\max p > \frac{1}{k}$. Let $v \in \Gamma(p)$, then there exists $S = (S_1, \ldots, S_l) \in \gamma(p)$ such that $\arg\max v \subseteq S_1$.
Proof. Recall by definition, $v \in \Gamma(p)$ if and only if $\ell(p) = \langle p, L(v) \rangle$. We first claim that $v$ is not a scalar multiple of the all ones vector. Suppose it is, then $\ell(p) = \langle p, L(v) \rangle = \langle p, L(0) \rangle$ by Lemma C.1, which implies that $0 \in \Gamma(p)$. Now, by Lemma C.20, we have $0 \notin \Gamma(p)$ since $\min p < \frac{1}{k}$ by the assumption that $\max p > \frac{1}{k}$. This is a contradiction. Hence, the claim is proved.

Next, let $n = \lfloor \arg \max v \rfloor$. By our claim that $v$ is non-constant, we have that $n \in [k - 1]$. Let $\sigma \in \mathcal{S}_k$ be such that $\sigma v \in \mathbb{R}^k$. Thus, by construction, we have $\arg \max v = [n]$. Hence, we have, by Lemma E.5

$$[n] = \arg \max \sigma v = \sigma^{-1}(\arg \max v)$$

or, equivalently, $\arg \max v = \sigma([n])$. Since $n = \lfloor \arg \max v \rfloor \in [k - 1]$, $v$ is feasible for the right hand side of eq. (11). Thus, we have

$$\ell(p) = \ell^n(p).$$

By Lemma C.19

$$\ell^n(p) = \min_{w \in C_2 : w_n = 0} \langle p, L(w) \rangle. \tag{57}$$

Let $w^*$ be a minimizer of the above optimization. Since $w^* \in C_2$, consider $S = (S_1, \ldots, S_k) := \tilde{\psi}(w^*)$. Hence, by the definition of $\tilde{\psi}$, we have that $S_1 = \arg \max w^*$. Note that

$$\ell(p) = \ell^n(p) = \langle p, L(w^*) \rangle = \langle p, L(\varphi(S)) \rangle \quad \because \text{Proposition 3.6}$$

$$= \langle p, \ell(S) \rangle \quad \because \text{Theorem 3.8}$$

$$= \langle \sigma p, \ell(S) \rangle \quad \because \sigma p = p \text{ by Lemma E.4}$$

$$= \langle p, \sigma' \ell(S) \rangle$$

Putting it all together, we have

$$\langle p, \ell(\sigma S) \rangle = \ell(p) = \ell(p)$$

where the second equality follows from Corollary 3.9. This proves that $\sigma S \in \gamma(p)$. Note that since $w^*$ is feasible for the optimization on the right hand side of eq. (57), we have $\arg \max w^* = \{i \in [k] : w_i^* = 0 \} \supseteq [n]$. Furthermore, recall that $S_1 = \arg \max w^*$. Putting it all together, we have $\sigma(S_1) \supseteq \sigma([n]) = \arg \max v$. Thus, $\sigma(S)$ satisfies the desired conditions. \qed

Lemma E.7. For all $p \in \Delta^k$ and $\sigma \in \mathcal{S}_k$, we have

$$S \in \gamma(\sigma p) \iff \sigma S \in \gamma(p), \quad \tag{58}$$

$$v \in \Gamma(\sigma p) \iff \sigma' v \in \Gamma(p). \quad \tag{59}$$

Proof. We first prove eq. (58). Let $S \in \gamma(\sigma p)$. Then

$$\ell(\sigma p) = \langle \sigma p, \ell(S) \rangle$$

$$= \langle p, \sigma' \ell(S) \rangle$$

$$= \langle p, \ell(\sigma S) \rangle \quad \because \text{Corollary E.3}$$

$$\geq \ell(p).$$

By the same argument, we have $\ell(p) \geq \ell(\sigma p)$. Thus, $\ell(p) = \ell(\sigma p)$ and $\sigma S \in \gamma(p)$. This proves the $\implies$ direction eq. (58). To prove the other direction, we first write $p = \sigma' \sigma p$ and note that

$$\sigma S \in \gamma(\sigma' \sigma p) \implies \sigma' \sigma S \in \gamma(\sigma p) \iff S \in \gamma(\sigma p).$$
Next, we prove eq. (69). By Lemma C.7 we have $L(p) = L(\sigma p)$. Let $v \in \Gamma(\sigma p)$, then

\[
L(p) = L(\sigma p) = \langle \sigma p, L(v) \rangle \\
= \langle p, \sigma' L(v) \rangle \\
= \langle p, L(\sigma' v) \rangle \quad : \text{Corollary C.5}
\]

Thus, $\sigma' v \in \Gamma(p)$. This proves the $\implies$ direction of eq. (69). For the other direction, $\sigma' v \in \Gamma(\sigma' \sigma p) \implies \sigma \sigma' v \in \Gamma(p) \iff v \in \Gamma(\sigma p)$.

\[\square\]

E.1 Proof of Theorem 5.2

Proof of Theorem 5.2. Let $\sigma \in \mathcal{S}_k$ be such that $\sigma p \in \Delta^k_\gamma$. By Lemma E.7 we have $\sigma v \in \Gamma(\sigma p)$. Then by Lemma E.6 there exists $S = (S_1, \ldots, S_l) \in \gamma(p)$ such that $S_1 \supseteq \arg \max \sigma v = \sigma^{-1}(\arg \max v)$, where the equality is due to Lemma E.5. Applying $\sigma$, to both sides, we have $\sigma S_1 \supseteq \arg \max v$. By Lemma E.7 we have $\sigma S \in \gamma(p)$. Hence, we are done.

\[\square\]

Lemma E.8. Let $p \in \Delta^k_\gamma$ be such that $\arg \max p = \{1\}$ and $S = (S_1, \ldots, S_l) \in \gamma(p)$. Then $1 \in S_1$.

Proof. Let $v = \varphi(S)$. Since $S$ is nontrivial, we have $\max v > \min v$. By construction, we have $\arg \max v = S_1$. Hence, if $1 \notin S_1$, then there exists some $j \in \{2, \ldots, k\}$ such that $v_j > v_1$. Then Lemma E.6 implies that $[L(v)]_1 > [L(v)]_j$, and so

\[
\langle p, L(v) \rangle - \langle p, \sigma_j L(v) \rangle = (p_1 - p_j)([L(v)]_1 - [L(v)]_j) > 0.
\]

But $\ell(p) = \langle p, \ell(S) \rangle = \langle p, L(v) \rangle$ and

\[
\langle p, \sigma_j L(v) \rangle = \langle p, L(\sigma_j v) \rangle = \langle p, L(\sigma_j \varphi(S)) \rangle = \langle p, L(\varphi(\sigma_j S)) \rangle = \langle p, \ell(\sigma_j S) \rangle
\]

Thus, we have

\[
\langle p, \ell(S) \rangle - \langle p, \ell(\sigma_j S) \rangle > 0
\]

which contradicts that $S \in \gamma(p)$.

\[\square\]

Definition E.9. A $\mathcal{S}_k$-invariant property is a boolean function

\[
B : \Delta^k \rightarrow \{\text{true, false}\}
\]

such that $B(p) \implies B(\sigma p)$ for all $\sigma \in \mathcal{S}_k$ and $p \in \Delta^k$. Here, “$\implies$” denotes logical implication.

Lemma E.10. Let $B$ and $C$ be $\mathcal{S}_k$-invariant properties. Suppose that for all $p \in \Delta^k_\gamma$, $B(p)$ implies $C(p)$. Then for all $p \in \Delta^k$, we have $B(p)$ implies $C(p)$.

Proof. Let $p \in \Delta^k$ be arbitrary. Pick $\sigma$ such that $\sigma p \in \Delta^k_\gamma$. Then

\[
B(p) \implies B(\sigma p) \implies C(\sigma p) \implies C(p)
\]

where for the first and last implications we used the $\mathcal{S}_k$-invariance property of $B$ and $C$, and for the implication in the middle we used the assumption in the lemma.

\[\square\]

Lemma E.11. Let $p \in \Delta^k$. Consider the statement $B_1(p)$ which returns true if and only if

\[
\text{for all } S \in \gamma(p), \ |S_1| = 1 \text{ and } S_1 = \arg \max p.
\]

Then $B_1$ is a $\mathcal{S}_k$-invariant property.

Proof. Let $p \in \Delta^k$ and $\sigma \in \mathcal{S}_k$. Suppose $B_1(p)$ is true. We need to show that $B_1(\sigma p)$ is true. Let $S \in \gamma(\sigma p)$. By Lemma E.7 we have $\sigma S \in \gamma(p)$. Since $B_1(p)$ is true, we have $|\sigma(S_1)| = 1$ and $\sigma(S_1) = \arg \max p$. Thus, we immediately get that $|S_1| = 1$. By Lemma E.5 we have $S_1 = \sigma^{-1}(\arg \max p) = \arg \max \sigma p$. The two preceding facts is equivalent to $B_1(p)$ being true, by definition.

\[\square\]
E.2 Proof of Proposition 5.3

Proof of Proposition 5.3. By Lemma E.11 and Lemma E.10, we may assume \( p \in \Delta_k \). Lemma E.8 implies that \( 1 \in S_1 \). If \(|S_1| = 1\), then \( S_1 = \{1\} \) and the result is proven. Below, suppose \(|S_1| > 1\). We define

\[
S'_1 = \{1\}, \quad S''_1 = S_1 \setminus \{1\}.
\]

Define

\[
S' = (S'_1, S''_1, S_2, \ldots, S_l) \in \mathcal{OP}_k.
\]

We claim that \( \langle p, \ell(S') \rangle < \langle p, \ell(S) \rangle \). Given the claim, we would have a contradiction that \( S \in \gamma(p) \) and so \(|S_1| = 1\) must be true. Let \( Y \sim p \) and define

\[
\beta := \sum_{j=1}^{l-1} |S_1 \cup \cdots \cup S_{j+1}| \Pr(Y \notin S_1 \cup \cdots \cup S_j)
\]

Observe that

\[
\langle p, \ell(S') \rangle = |S'_1| - 1 + |S'_1 \cup S''_1| \Pr(Y \notin S'_1) + \beta \\
< \frac{1}{2} |S_1| + \beta.
\]

On the other hand, we have

\[
\langle p, \ell(S) \rangle = |S_1| - 1 + \beta.
\]

Hence, we have

\[
\langle p, \ell(S) \rangle - \langle p, \ell(S') \rangle = |S_1| - 1 - |S_1| \Pr(Y \neq 1) \\
> |S_1| - 1 - \frac{1}{2} |S_1| \\
= \frac{1}{2} |S_1| - 1 \\
\geq \frac{2}{2} - 1 \\
= 0.
\]

which proves the claim.

E.3 Proof of Proposition 5.4

Proof of Proposition 5.4. Since \( \arg\max p = \{j^*\} \), we have \( (\{j^*\}, [k] \setminus \{j^*\}) = (\arg\max p, [k] \setminus \arg\max p) \). We check that the statement below defines a \( \mathcal{G}_k \)-invariant property:

\[
\text{"}p \text{ satisfies } (\arg\max p, [k] \setminus \arg\max p) \text{ is the unique element of } \gamma(p).\text{"} \tag{62}
\]

Let \( p \) satisfy eq. (62). By Lemma E.7, we have \( \sigma^{-1}(\arg\max p, [k] \setminus \arg\max p) \) is the unique element of \( \gamma(\sigma p) \). By definition,

\[
\sigma^{-1}(\arg\max p, [k] \setminus \arg\max p) = (\sigma^{-1}(\arg\max p), \sigma^{-1}([k] \setminus \arg\max p)).
\]

By Lemma E.5, we have \( \sigma^{-1} \arg\max p = \arg\max \sigma p \). Thus, we have

\[
\sigma^{-1}(\arg\max p, [k] \setminus \arg\max p) = (\arg\max \sigma p, [k] \setminus \arg\max \sigma^{-1} p)
\]

is the unique element of \( \gamma(\sigma p) \). In other words, \( \sigma p \) satisfies eq. (62), as desired.
Furthermore, "\( p \) satisfies the symmetric noise condition." is obviously \( \mathcal{G}_\kappa \)-invariant. Hence, by Lemma \[E.11\] and Lemma \[E.10\] we may assume \( p \in \Delta^k_\kappa \). Pick \( S = (S_1, \ldots, S_l) \in \gamma(p) \). Lemma \[E.8\] implies that \( 1 \in S_1 \). By Definition \[2.4\] of \( \mathcal{OP}_\kappa \), we have \( l \geq 2 \). We first show that \( l = 2 \) by contradiction. Suppose that \( l > 2 \). Define \( S' = (S'_1, \ldots, S'_{l-1}) \) where

\[
S'_1 := S_1, \quad S'_2 := S_2 \cup S_3, \quad S'_j := S_{j+1}, \forall j \in \{3, \ldots, l-1\}.
\]

Let \( Y \sim p \) and

\[
\beta := \sum_{j=3}^{l-1} |S_1 \cup \cdots \cup S_{j+1}| \Pr(Y \notin S_1 \cup \cdots \cup S_j).
\]

Then we have

\[
\langle p, \ell(S) \rangle = |S_1| - 1 + |S_1 \cup S_2| \Pr(Y \notin S_1) + |S_1 \cup S_2 \cup S_3| \Pr(Y \notin S_1 \cup S_2) + \beta
\]

and

\[
\langle p, \ell(S') \rangle = |S'_1| - 1 + |S'_1 \cup S'_2| \Pr(Y \notin S'_1) + \sum_{j=2}^{l-2} |S'_1 \cup \cdots \cup S'_{j+1}| \Pr(Y \notin S'_1 \cup \cdots \cup S'_j) = |S_1| - 1 + |S_1 \cup S_2 \cup S_3| \Pr(Y \notin S_1) + |S_1 \cup S_2 \cup S_3| \Pr(Y \notin S_1 \cup S_2) + \beta
\]

Putting it all together, we have

\[
\langle p, \ell(S) \rangle - \langle p, \ell(S') \rangle = |S_1 \cup S_2| \Pr(Y \notin S_1) + |S_1 \cup S_2 \cup S_3| \Pr(Y \notin S_1 \cup S_2) - |S_1 \cup S_2 \cup S_3| \Pr(Y \notin S_1) = |S_1 \cup S_2 \cup S_3| \Pr(Y \notin S_1 \cup S_2) - |S_3| \Pr(Y \notin S_1).
\]

Define \( s_i := |S_i| \) for each \( i \in [l] \). Then

\[
|S_1 \cup S_2 \cup S_3| \Pr(Y \notin S_1 \cup S_2) = (s_1 + s_2 + s_3)(k - s_1 - s_2) \frac{1 - \alpha}{k - 1}
\]

and

\[
|S_3| \Pr(Y \notin S_1) = s_3(k - s_1) \frac{1 - \alpha}{k - 1}.
\]
Now, we have
\[(s_1 + s_2 + s_3)(k - s_1 - s_2) - s_3(k - s_1)\]
\[= ((s_1 + s_2) + s_3)((k - s_1) - s_2) - s_3(k - s_1)\]
\[= (s_1 + s_2)(k - s_1) - s_2(s_1 + s_2) - s_3s_2\]
\[= (s_1 + s_2)k - (s_1 + s_2)^2 - s_2s_3\]
\[\geq (s_1 + s_2)(s_1 + s_2 + s_3) - (s_1 + s_2)^2 - s_2s_3\]
\[= s_1s_3\]

where for the inequality, we used the fact that \(k \geq s_1 + s_2 + s_3\). Finally, we now get a contradiction of the optimality of \(S\):
\[|S_1 \cup S_2 \cup S_3| \Pr(Y \not\in S_1 \cup S_2) - |S_3| \Pr(Y \not\in S_1) \geq s_1s_3 \frac{1-\alpha}{k-1} > 0\]
implies
\[\langle p, \ell(S)\rangle - \langle p, \ell(S')\rangle > 0.\]
This proves the claim that if \(S = (S_1, \ldots, S_l) \in \gamma(p)\), then \(l = 2\) and so \(S = (S_1, [k] \setminus S_1)\). Next, we show that \(S_1 = \{1\}\). We already have shown that \(1 \in S_1\). We calculate
\[\langle p, \ell((S_1, [k] \setminus S_1))\rangle = |S_1| - 1 + k \Pr(Y \not\in S_1)\]
\[= |S_1| - 1 + k(|S_1| - |S_1|) \left(\frac{1-\alpha}{k-1}\right)\]
\[= |S_1| \left(1 - k \left(\frac{1-\alpha}{k-1}\right)\right) + C\]
where \(C = -1 + k^2 \left(\frac{1-\alpha}{k-1}\right)\) does not depend on \(|S_1|\). To prove that \(|S_1| = 1\), by minimality of \(S\) it suffices to show that
\[1 - k \left(\frac{1-\alpha}{k-1}\right) > 0.\]
To see this, note that
\[1 > k \left(\frac{1-\alpha}{k-1}\right) \iff \frac{1}{k} > \frac{1-\alpha}{k-1}\]
\[\iff \frac{k-1}{k} = 1 - \frac{1}{k} > 1 - \alpha\]
\[\iff \alpha > \frac{1}{k}\]
where the last line is part of our assumption in the lemma statement. \(\square\)
F Derivation of the figures

We discuss how Figures 1 and 2 are obtained.

F.1 Figure 1
When \( k = 3 \), there are 12 nontrivial ordered partitions. Below, we represent \( \mathcal{OP}_3 \) vectorially in \( \mathbb{R}^3 \) using Proposition 3.6:

\[
\mathcal{OP}_k = \begin{bmatrix}
-2 & -2 & -1 & -1 & -1 & 0 & 0 & 0 & 0 \\
0 & -1 & 0 & 0 & 0 & -2 & -1 & -1 & -1 \\
-1 & 0 & 0 & -2 & 0 & -1 & 0 & 0 & -2 & -1
\end{bmatrix}
\]

Every column of the matrix \( \mathcal{OP}_k \) is a nontrivial ordered partition, e.g., the first column \( \begin{bmatrix} -2 \\ 0 \\ -1 \end{bmatrix} \rightarrow 2|3|1 \).

Consider the following matrix whose columns are \( \ell(S) = L^W(W(S)) \in \mathbb{R}_+^3 \) where \( \ell \) is the ordered partition loss and \( S \in \mathcal{OP}_3 \).

\[
e_{11} = \begin{bmatrix} 5 & 5 & 4 & 3 & 2 & 3 & 1 & 2 & 1 & 0 & 0 & 0 \\
0 & 2 & 1 & 0 & 0 & 3 & 1 & 5 & 4 & 3 & 2 & 5 \\
2 & 0 & 1 & 3 & 5 & 0 & 4 & 0 & 1 & 3 & 5 & 2
\end{bmatrix}
\]

For example, the first column of \( e_{11} \) is the result of applying \( L^W : \mathbb{R}^k \rightarrow \mathbb{R}_+^k \) to the first column of \( \mathcal{OP}_k \), i.e., \( \begin{bmatrix} 5 \\ 0 \\ 2 \end{bmatrix} = L^W \begin{bmatrix} -2 \\ 0 \\ -1 \end{bmatrix} = \ell^{OP}(2|3|1) \). Finally, to get the region in Figure 3 labelled by “2|3|1”, we plot the \((p_2, p_3)\) coordinates of the following polytope:

\[
\text{Reg}(2|3|1) := \{ p \in \Delta^3 : \langle p, \ell(2|3|1) - \ell(S) \rangle \leq 0, \forall S \in \mathcal{OP}_3, S \neq 2|3|1 \}.
\]

Repeat this procedure for all of \( \mathcal{OP}_3 \), we obtain Figure 3.
Figure 3: Each polygonal region is the polytope $\text{Reg}(S)$ projected onto its last two coordinates overall $S \in \mathcal{OP}_3$.

F.2 Figure 2

For the left panel of Figure 2, we compute $\Omega_{LWW}$

$$\Omega_{LWW} := \{ p \in \Delta^k : |\arg \max p| = 1, \arg \max v = \arg \max p, \forall v \in \Gamma_{LWW}(p) \}.$$ 

Thus, the region in light gray in the left panel of Figure 2 is the union of the polygons of Figure 1 labelled by an ordered partition whose the top bucket has 2 elements. This characterize $\Omega_{LWW}$ up to a set of Lebesgue measure zero.

For the right panel, consider $v \in \Gamma_{LCS}(p)$. Liu [5, Lemma 4] states that if $\max p < 1/2$, then $v = (0,0,0)$. Furthermore, if $\max p > 1/2$, then $\arg \max v = \arg \max p$. This characterize $\Omega_{LCS}$ up to a set of Lebesgue measure zero.