Refined Heuristic Swarm Intelligence Algorithm

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Abstract

In this paper, a new metaheuristic algorithm named refined heuristic intelligence swarm (RHIS) algorithm is developed from an existing particle swarm optimization (PSO) algorithm by introducing a disturbing term to the velocity of PSO and modifying the inertia weight, in which the comparison between the two algorithms is also addressed.

1 Introduction

For the last decade, many researchers in this field have changed direction, leaving aside traditional optimization techniques based on linear and nonlinear programming and embarked in the implementation of the evolutionary algorithm: genetic algorithm; ant colony optimization; simulated annealing; and harmony search among others. Particle swarm optimization (PSO) algorithm was first introduced by Kennedy and Eberhart in 1995 by observing the behavior of animals, e.g., bird flocking and fish schooling. Their movements and communication mechanisms were thoroughly studied [1, 2, 4].

In comparison with several other population based stochastic optimization methods such as genetic algorithm (GA) and evolutionary programming (EP), PSO performs better in solving various optimization problems with fast and stable convergence rate [3, 4].
In this research work a new metaheuristic method is designed which performs better than the existing one.

2 Particle Swarm Optimization (PSO) Algorithm

The pseudo code for particle swarm algorithm (PSO) is as follows:

Step 1: Initialize the population size $N_p$, the dimension of the space $c_1, c_2, I_{\text{max}}, w_{\text{max}}, w_{\text{min}}$

Step 2: Set $P_{\text{best},i} = x_i$, $(i = 1, ..., N_p)$
      calculate the fitness of $x_i$
      Find $G_{\text{best}}$

Step 3: If $\text{iter} < I_{\text{max}}$

Step 4: Calculate the inertia weight
        $w = [w_{\text{max}} - \frac{w_{\text{max}} - w_{\text{min}}}{I_{\text{max}}} (\text{iter})]$

Step 5: Calculate the velocity of each particle by
        $v_{t+1} = w v_t + c_1 r_1 (P_{\text{best},i} - x_t) + c_2 r_2 (G_{\text{best}} - x_t) $

Step 6: Calculate the position of each particle by
        $x_{t+1} = x_t + v_{t+1}$

Step 7: Calculate the value of the objective function for each particle
        $f(x_{t+1})$

Step 8: Find $P_{\text{best},i}^{t+1}$ and $G_{\text{best}}$
        if $f_{t+1} > P_{\text{best},i}^t$ then $P_{\text{best},i}^{t+1} = P_{\text{best},i}^t$
        else
        $P_{\text{best},i}^{t+1} = x_{t+1}^{i}$

Step 9: Go to Step 3.
Table 2.1 shows the parameters used in the above PSO algorithm.

| Parameter | Definition                                      |
|-----------|-------------------------------------------------|
| $c_1, c_2$| PSO Constant, mostly given as 2                |
| $I_{\text{max}}$ | The maximum number of iteration               |
| $\text{iter}$ | The number of current iteration               |
| $w$      | Inertia weight                                  |
| $w_{\text{max}}$ | Maximum inertia weight                        |
| $w_{\text{min}}$ | Minimum inertia weight                        |
| $x_i$    | Position of particle $i$                       |
| $N_p$    | Total number of particle                       |
| $x_i^{t+1}$ | The position of particle $i$ at $(t+1)^{th}$ iteration |
| $x_i^t$  | The position of particle $i$ at $(t)^{th}$ iteration |
| $v_i^{t+1}$ | The velocity of particle $i$ at $(t+1)^{th}$ iteration |
| $P_{\text{best},i}^{t+1}$ | The personal best of particle $i$ at $(t+1)^{th}$ iteration |
| $G_{\text{best},i}$ | The global best                               |
| $r_1, r_2$ | Random variable, which is always between 0 and 1 |

Algorithm of Refined Heuristic Swarm Intelligence (RHSI)

Just like other global algorithm, PSO converges prematurely and being trapped into a local minimum. This leads to the modification of PSO algorithm called refined heuristic swarm intelligence (RHSI) algorithm which is the major concentration of this paper.
3 Refined Heuristic Swarm Intelligence (RHSI) Algorithm

RHSI algorithm was developed as a result of the premature convergence of PSO algorithm and being trapped by local minimum.

In this algorithm the natural log of the inertial weight \((w)\) of PSO is being considered as the inertia weight of the algorithm, i.e.,

\[
w = \ln[w_{\text{max}} - \frac{w_{\text{max}} - w_{\text{min}}}{I_{\text{max}}}(\text{iter})].
\] (3.1)

Also a disturbing term is introduced to the velocity of PSO which makes the method more efficient. This disturbing term \(|b(r_3 - 0.5)|\) is introduced to the velocity, where \(b\) is a small number and \(r\) is a random number in the range (0, 1). We take \(b = 0.05\) in this paper. Therefore the velocity of each particle is being updated with

\[
v^{t+1} = wv^{t} + c_1 r_1(P_{\text{best},i}^{t} - x^{t}_i) + c_2 r_2(G_{\text{best}} - x^{t}_i) + |b(r_3 - 0.5)|.
\] (3.2)

The pseudo code for algorithm of refined heuristic swarm intelligence (RHSI) is as follows:

Step 1: Initialize the population size \(N_p\), the dimension of the space \(c_1, c_2, I_{\text{max}}, w_{\text{max}}, w_{\text{min}}\)

Step 2: Set \(P_{\text{best},i} = x_i\), \((i = 1, ..., N_p)\)

\[\text{calculate the fitness of } x_i\]

Find \(G_{\text{best}}\)

Step 3: If \(\text{iter} < I_{\text{max}}\)

Step 4: Calculate the inertia weight

\[
w = \ln([w_{\text{max}} - \frac{w_{\text{max}} - w_{\text{min}}}{I_{\text{max}}}(\text{iter})])
\]

Step 5: Calculate the velocity of each particle by

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Step 6: Calculate the position of each particle by
\[ x_{i}^{t+1} = x_{i}^{t} + v_{i}^{t+1} \]
Step 7: Calculate the value of the objective function for each particle
\[ f(x^{t+1}) \]
Step 8: Find \( P_{t}^{t+1},i \) and \( G_{t}^{best} \)
if \( f_{i}^{t+1} > P_{t}^{t, best,i} \) then \( P_{t}^{t+1, best,i} = P_{t}^{t, best,i} \)
else
\[ P_{t}^{t+1, best,i} = x_{i}^{t+1} \]
Step 9: Go to step 3.

4 Experiment and Discussion

4.1 Computational Consideration
In this paper we will take the following values for the PSO and RHSI parameters:
\[ w_{\text{max}} = 0.9, \quad w_{\text{min}} = 0.4, \quad I_{\text{max}} = 1000, \quad b = 0.05, \quad \text{number of particles}=10. \]
The numerical results are presented in Tables 4.1 and it was obtained from the solution of some test problems are presented in this section using MATLAB R2010a (7.10.499) run on the PC Intel(R) samsung, a 32 bit Os Laptop windows 7 operating system.

The following standard problems from [5], were used to test the performance of the new algorithm (RHSI):

Problem 1 (Extended Rosenbrock Function) [5]

\[ f(x) = \sum_{i=1}^{n/2} c(x_{2i} - x_{2i-1}^2)^2 + (1 - x_{2i-1})^2, \quad x_{0} = [-1.2, 1, ..., -1.2, 1], \quad c = 100. \]

(4.1)
Problem 2 (Extended Himmelblau Function) [5]
\[
f(x) = \sum_{i=1}^{n/2} \left( x_{2i-1}^2 + x_{2i} - 11 \right)^2 + (x_{2i-1} - x_{2i}^2 - 7)^2, \quad x_0 = [1, 1, \ldots, 1]. \tag{4.2}
\]

Problem 3 (Extended White & Holst Function) [5]
\[
f(x) = \sum_{i=1}^{n/2} c(x_{2i} - x_{2i-1}^3)^2 + (1 - x_{2i-1})^2, \quad x_0 = [-1.2, 1, \ldots, -1.2, 1], \quad c = 100. \tag{4.3}
\]

Problem 4 (Generalized Tridiagonal-1 Function) [5]
\[
f(x) = \sum_{i=1}^{n-1} (x_i + x_{i+1} - 3)^2 + (x_i + x_{i+1} + 1)^4, \quad x_0 = [2, 2, \ldots, 2]. \tag{4.4}
\]

Problem 5 (Extended Tridiagonal-1) [5]
\[
f(x) = \sum_{i=1}^{n/2} (x_{2i-1}^2 + x_{2i} - 3)^2 + (x_{2i-1} - x_{2i} + 1)^4, \quad x_0 = [2, 2, \ldots, 2]. \tag{4.5}
\]

Problem 6 (Generalized White & Holst Function) [5]
\[
f(x) = \sum_{i=1}^{n-1} c(x_{i+1} - x_i^3)^2 + (1 - x_i)^2, \quad x_0 = [-1.2, 1, \ldots, -1.2, 1], \quad c = 100. \tag{4.6}
\]

Problem 7 (Generalized PSC1 Function) [5]
\[
f(x) = \sum_{i=1}^{n-1} \left( x_i^2 + x_{i+1}^2 + x_i x_{i+1} \right)^2 + \sin^2(x_i) + \cos^2(x_i), \quad x_0 = [3, 0.1, \ldots, 3, 0.1]. \tag{4.7}
\]

Problem 8 (Extended Cliff Function) [5]
\[
f(x) = \sum_{i=1}^{n/2} \left( \frac{x_{2i} - 3}{100} \right)^2 - (x_{2i-1} - x_{2i}) + \exp(20(x_{2i-1} - x_{2i})), \quad x_0 = [0, -1, \ldots, 0, -1]. \tag{4.8}
\]
Problem 9 (Extended Hiebert Function) \[5\]
\[
f(x) = \sum_{i=1}^{n/2} (x_{2i-1} - 10)^2 + (x_{2i-1}x_{2i} - 50000)^2, \quad x_0 = [0, 0, \ldots, 0]. \tag{4.9}
\]

Problem 10 (Extended Quadratic Penalty QP1 Function) \[5\]
\[
f(x) = \sum_{i=1}^{n-1} (x_i^2 - 2)^2 + (\sum_{i=1}^{n} x_i^2 - 0.5)^2, \quad x_0 = [1, 1, \ldots, 1]. \tag{4.10}
\]

Problem 11 (Extended Quadratic Penalty QP2 Function) \[5\]
\[
f(x) = \sum_{i=1}^{n-1} (x_i^2 - \sin x_i)^2 + (\sum_{i=1}^{n} x_i^2 - 100)^2, \quad x_0 = [1, 1, \ldots, 1]. \tag{4.11}
\]

Problem 12 (Extended Exponential EP1 Function) \[5\]
\[
f(x) = \sum_{i=1}^{n/2} (\exp(x_{2i-1} - x_{2i}) - 5)^2 + (x_{2i-1} - x_{2i} - 11)^2, \quad x_0 = [1.5, 1.5, \ldots, 1.5]. \tag{4.12}
\]

Problem 13 (Diagonal 8 Function) \[5\]
\[
f(x) = \sum_{i=1}^{n} \sin(2x_i)x_i - 2x_i - x_i^2, \quad x_0 = [1, 1, \ldots, 1]. \tag{4.13}
\]

Problem 14 (GENHUMPS Function) \[5\]
\[
f(x) = \sum_{i=1}^{n-1} \sin(2x_i)^2\sin(2x_{i+1})^2 + 0.05(x_i^2 + x_{i+1}^2), \quad x_0 = [-506.2, 506.2, \ldots, 506.2]. \tag{4.14}
\]

4.2 Computational Results

The computational result is given in Table 4.1.
Table 4.1: Result obtained with RHSI and PSO.

| Problem | DIM(n) | RHSI  | PSO   |
|---------|--------|-------|-------|
| 1       | 10     | 1.1398| 7.9799|
| 2       | 10     | 530.0000| 554.0000|
| 3       | 10     | 0.0000| 0.0000|
| 4       | 10     | 11.9504| 7.5922|
| 5       | 10     | 0.7128| 100.4064|
| 6       | 10     | 0.0045| 0.6551|
| 7       | 10     | 7.9907| 8.9901|
| 8       | 10     | 1.7063| 1.0034|
| 9       | 10     | 1249500000.0000| 1249950410.0000|
| 10      | 10     | 33.7192| 33.6128|
| 11      | 10     | 72000.2262| 72910.3238|
| 12      | 10     | 33.7192| 33.6128|
| 13      | 10     | -4.0214| -4.8045|
| 14      | 10     | -2.531| -1.3745|

4.3 Discussion on Numerical Results

From the result tabulated in Table 4.1, it can be seen that RHSI proposed in this paper performs better than PSO in terms of value of the objective function.

5 Conclusion

To improve the performance of PSO algorithm, a modified PSO algorithm (RHSI algorithm) based on disturbing term is introduced in this paper. Two improvement strategies are proposed to generate a new position for each particle, which the strategies are modifying the inertia weight and the velocity of the particle of which it performs better than PSO algorithm. Therefore RHSI algorithm is recommended for solving optimization problems.
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