Multiplicity of positive periodic solutions in the superlinear indefinite case via coincidence degree

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Abstract
We study the periodic boundary value problem associated with the second order nonlinear differential equation

\[ u'' + cu' + (a^+(t) - \mu a^-(t))g(u) = 0, \]

where \( g(u) \) has superlinear growth at zero and at infinity, \( a(t) \) is a periodic sign-changing weight, \( c \in \mathbb{R} \) and \( \mu > 0 \) is a real parameter. We prove the existence of \( 2^m - 1 \) positive solutions when \( a(t) \) has \( m \) positive humps separated by \( m \) negative ones (in a periodicity interval) and \( \mu \) is sufficiently large. The proof is based on the extension of Mawhin’s coincidence degree defined in open (possibly unbounded) sets and applies also to Neumann boundary conditions. Our method also provides a topological approach to detect subharmonic solutions.

1 Introduction
Let \( \mathbb{R}^+ := [0, +\infty[ \) denote the set of non-negative real numbers and let \( g: \mathbb{R}^+ \to \mathbb{R}^+ \) be a continuous function such that

\[ (g, t) \quad g(0) = 0, \quad g(s) > 0 \quad \text{for } s > 0. \]

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In the present paper we study the problem of existence and multiplicity of positive $T$-periodic solutions to the second order nonlinear differential equation
\[ u'' + cu' + w(t)g(u) = 0, \] (1.1)
where $c \in \mathbb{R}$ and $w: \mathbb{R} \to \mathbb{R}$ is a $T$-periodic locally integrable weight function. Solutions to (1.1) are meant in the Carathéodory sense. A positive solution is a solution such that $u(t) > 0$ for all $t \in \mathbb{R}$. As is well known, solving the $T$-periodic problem for (1.1) is equivalent to find a solution of (1.1) satisfying the boundary conditions
\[ u(0) = u(T), \quad u'(0) = u'(T), \]
on $[0, T]$ (any other time-interval of length $T$ can be equivalently chosen).

Our aim is to consider a nonlinear vector field
\[ f(t, s) := w(t)g(s) \]
satisfying suitable assumptions which cover the classical superlinear indefinite case, namely $g(s) = s^p$, with $p > 1$, and $w(t)$ a sign-changing coefficient. Our main result guarantees the existence of at least $2m - 1$ positive $T$-periodic solutions provided that, in a time-interval of length $T$, the weight function presents $m$ positive humps separated by negative ones and the negative parts of $w(t)$ are sufficiently large. To be more precise, it is convenient to express $w(t)$ as depending on a parameter $\mu > 0$ in this manner:
\[ w(t) = a_\mu(t) := a^+(t) - \mu a^-(t), \]
where $a: \mathbb{R} \to \mathbb{R}$ is a $T$-periodic locally integrable function. As usual, we denote by
\[ a^+(t) := \frac{a(t) + |a(t)|}{2} \quad \text{and} \quad a^-(t) := \frac{-a(t) + |a(t)|}{2} \]
the positive part and the negative part of $a(t)$, respectively. Then, a typical corollary of our main result (cf. Theorem 4.1) reads as follows.

**Theorem 1.1.** Suppose that there exist $2m + 1$ points
\[ \sigma_1 < \tau_1 < \ldots < \sigma_i < \tau_i < \ldots < \sigma_m < \tau_m < \sigma_{m+1}, \quad \text{with} \quad \sigma_{m+1} - \sigma_1 = T, \]
such that $w(t) > 0$ on $[\sigma_i, \tau_i]$ and $w(t) < 0$ on $[\tau_i, \sigma_{i+1}]$. Let $g(s)$ be a continuous function satisfying $(g_*)$ and such that
\[ g_0 := \lim_{s \to 0^+} \frac{g(s)}{s} = 0 \quad \text{and} \quad g_\infty := \liminf_{s \to +\infty} \frac{g(s)}{s} > 0. \]
If $g_\infty$ is sufficiently large, then there exists $\mu^* > 0$ such that for each $\mu > \mu^*$ equation
\[ u'' + cu' + (a^+(t) - \mu a^-(t))g(u) = 0 \]
has at least $2^m - 1$ positive $T$-periodic solutions.

In the statement of the theorem we have employed the usual notation $w(t) > 0$ in a given interval, to express the fact that $w(t) \geq 0$ almost everywhere with $w \not\equiv 0$ on that interval. Moreover, $w(t) < 0$ stands for $-w(t) > 0$.  

Remark 1.1. For the application of Theorem 1.1, a lower bound for $g_\infty$ can be explicitly provided (see Theorem 4.1). It depends only on $a^+(t)$ (and not on $\mu$ or on $a^-(t)$). In any case, our result holds for

$$g_0 = 0 \quad \text{and} \quad g_\infty = +\infty,$$  

(1.2)

without any further assumption on $g(s)$ (see Corollary 5.2). Therefore the power nonlinearity $g(s) = s^p$, with $p > 1$, is covered. Regarding (1.2), Theorem 1.1 can be seen as an extension to the periodic case of the result by Erbe and Wang [30]. In [30] the authors considered the two-point boundary value problem with a sign-definite weight and proved the existence of at least one positive solution. In our situation, we allow the weight coefficient to change its sign and obtain a multiplicity result.

We underline that the condition $\mu > \mu^*$ implies

$$\int_0^T w(t) \, dt < 0,$$

which is a necessary condition for the existence of positive $T$-periodic solutions when $g'(s) > 0$ on $\mathbb{R}_0^+ := [0, +\infty[$ (cf. [10, 31]).

Concerning the condition at zero, we observe that it can be slightly improved to an hypothesis of the form

$$\limsup_{s \to 0^+} \frac{g(s)}{s} < \lambda^*,$$

where $\lambda^*$ is a positive constant which can be estimated from below (see Remark 4.2).

Besides the periodic problem, in the last part of our paper, we study also the Neumann boundary value problem for radially symmetric solutions of the Laplace equation and obtain the same multiplicity results. In this manner, we generalize [68], where the existence of radially symmetric solutions for the Dirichlet problem was obtained for a sign-definite weight.

A simple application of Theorem 1.1 is the following. The equation

$$u'' + cu' + \left( \sin^+(2t) - \mu \sin^-(2t) \right) u^p = 0, \quad p > 1,$$

has at least three positive $2\pi$-periodic solutions if $\mu > 0$ is sufficiently large. The same result obviously holds for

$$u'' + cu' + \left( \cos^+(2t) - \mu \cos^-(2t) \right) u^p = 0, \quad p > 1.$$  

Moreover, we can also prove that for an equation like

$$u'' + cu' + \left( \nu \sin^+(mt) - \mu \sin^-(mt) \right) u \arctan(u) = 0,$$

with $m$ a fixed positive integer, there are at least $2^m - 1$ positive $2\pi$-periodic solutions provided that $\nu > \nu^*$ and $\mu > \mu^*$ with $\mu^* = \mu^*(\nu)$ (see Corollary 5.1 for more details). In this latter example, $\nu$ large guarantees that $g_\infty$ (although finite) is large as well and Theorem 1.1 can be applied. A less immediate application of Theorem 1.1, presented in Section 6, ensures that in all the above three examples there are subharmonic solutions of an arbitrary order and also
bounded solutions which exhibit chaotic-like dynamics (in a sense that will be made more precise later).

Our proofs make use of a topological degree argument in the sense that we define some open sets where an operator associated with our boundary value problem has nonzero degree. Thus our results are stable with respect to small perturbations. In this manner, for example, we can also extend Theorem 1.1 to equations like

\[ u'' + cu' + \varepsilon u + \left(a^+(t) - \mu a^-(t)\right)g(u) = 0, \]

with |\varepsilon| < \varepsilon_0, where \varepsilon_0 is a sufficiently small constant depending on \mu. This latter equation is analogous to the one considered by Graef, Kong and Wang in [39] of the form

\[ u'' - \rho^2 u + \lambda w(t)g(u) = 0. \]

For this equation, the authors in [39, Theorem 2.1 (a)] obtained existence of positive periodic solutions, for \rho > 0 (arbitrary) and \lambda > 0 large, when \( w \gg 0 \). With our result we can ensure the multiplicity of solutions for a sign-changing weight when \rho is small.

The stability with respect to small perturbations is not generally guaranteed when using different approaches, such as variational or symplectic techniques which require some special structure (e.g. an Hamiltonian). Concerning this aspect, we stress that our results work equally well with respect to the presence or not of the friction term \( cu' \) (\( c \) can be zero or nonzero, indifferently).

The technique we employ in this paper exploits and combines the approaches introduced in our recent works [31, 32]. In [32] we provide existence and multiplicity of positive solutions to a Dirichlet boundary value problem of the form

\[
\begin{cases}
  u'' + f(t, u) = 0 \\
  u(0) = u(T) = 0,
\end{cases}
\]

using an extension of the classical Leray-Schauder degree to open and possibly unbounded sets (cf. [55, 56]). More in detail, since \( u \mapsto -u'' \) (with the Dirichlet boundary conditions) is invertible, following a standard procedure, we write (1.3) as an equivalent fixed point problem in a Banach space. Then we apply some degree theoretical arguments on suitably chosen open sets which are carefully selected in order to discriminate between the solutions we are looking for. With respect to the periodic (and Neumann) problem associated with (1.1), the linear differential operator \( u \mapsto -u'' - cu' \) has a nontrivial kernel made by constant functions, therefore it is not invertible and we can not operate as in [32]. For this reason, as in [31], we use the coincidence degree theory introduced by J. Mawhin to deal with a problem of the form \( Lu = Nu \), where \( L \) is a linear operator with nontrivial kernel and \( N \) is a nonlinear one. Unlike [31], where we prove the existence of at least a positive T-periodic solution to (1.1), in the present situation we need an extension of the coincidence degree to open not necessarily bounded sets (see Appendix A), in order to take advantage of the degree argument proposed in [32]. The possibility of obtaining the existence of solutions in some special open sets (via coincidence degree theory) allows us also to prove the presence of positive subharmonic solutions, a fact which appears rather new in this framework.

4
In the last twenty years the nonlinear indefinite problems received considerable attention, especially in connection to the study of existence and multiplicity of solutions to boundary value problems associated with equations of the form

$$-\Delta u = w(x)g(u). \quad (1.4)$$

Equations of this type arise in many models concerning population dynamics, differential geometry and mathematical physics.

The study of superlinear ODEs with a sign-changing weight was initiated in 1965 by Waltman (cf. [67]), considering oscillatory solutions for

$$u'' + w(t)u^{2n+1} = 0, \quad n \geq 1.$$  

Among the several authors who have continued this line of research, for the periodic problem, we recall the relevant contributions of Butler [16], Terracini and Verzini [66], and Papini [57], who proved the existence of periodic solutions with a large number of zeros to superlinear indefinite equations of the form

$$u'' + w(t)g(u) = 0. \quad (1.5)$$

The presence of chaotic dynamics for superlinear indefinite ODEs was discovered in [66] in the study of

$$u'' + Ku + w(t)u^3 = h(t)$$

(with the constant $K$ and the function $h(t)$ possibly equal to zero). In this framework we also mention [19], where a more general case of (1.5), adding the friction term $cu'$, has been considered (see [58 § 1] for a brief historical survey about this subject). A typical feature of these results lies on the fact that the solutions which have been obtained therein have a large number of zeros in the intervals where $w(t) > 0$. This fact was explicitly observed also by Butler in the proof of [16, Corollary], where the author pointed out that the equation

$$u'' + w(t)|u|^{p-1}u = 0, \quad p > 1,$$

has infinitely many $T$-periodic solutions, assuming that $w(t)$ is a continuous $T$-periodic function with only isolated zeros and which is somewhere positive. It was also noted that all these solutions oscillate (have arbitrarily large zeros) if $\int_0^T w(t) \, dt \geq 0$. Since condition

$$\int_0^T w(t) \, dt < 0 \quad (1.6)$$

implies the existence of non-oscillatory solutions (cf. [15]), it was raised the question (see [16, p. 477]) whether there can exist non-oscillatory periodic solutions if (1.6) holds. In the recent paper [31] we have provided a solution to Butler’s question, by showing the existence of positive (i.e. non-oscillatory) $T$-periodic solutions under the average condition (1.6). In this context, Theorem 1.1 can be seen as a further investigation about Butler’s problem, in the sense that we give evidence of the fact that if the weight is negative enough, multiple positive periodic solutions appear (depending on the number of positive humps in the weight function which are separated by negative ones).

In many applications, the solutions of (1.4) represent the steady states associated with reaction-diffusion equations. With this respect, a great deal of
importance was given to existence and multiplicity results of positive solutions in the superlinear indefinite case (cf. \cite{2,6,7}).

In \cite{34}, a shooting method was applied to prove the existence of at least three positive solutions for the two-point boundary value problem associated with

\[ u'' + a_\mu(t)u^p = 0, \quad p > 1, \quad (1.7) \]

due to existence and multiplicity results of positive solutions in the superlinear indefinite case (cf. \cite{2,6,7}).

This kind of results lies on a line of research initiated by Gómez-Reñasco and López-Gómez in \cite{38}, where the authors gave evidence of the fact that (for the Dirichlet problem) at least \(2^m - 1\) positive solutions (for \(\mu\) large) appear when \(a_\mu(t)\) has \(m\) positive humps separated by \(m - 1\) negative ones. For the Dirichlet problem, contributions in this direction have been achieved in \cite{9,32,35,37}. At the best of our knowledge, the first work addressing the same questions in the periodic setting is due to Barutello, Boscaggin and Verzini, who in \cite{5}, using a variational approach, achieved multiplicity of positive periodic solutions for \((1.7)\). In \cite{3} globally bounded solutions defined on the real line and exhibiting a chaotic behavior were also produced.

The plan of the paper is as follows. In Section 2 we list the hypotheses on \(a(t)\) and on \(g(s)\) that we assume for the rest of the paper and we introduce an useful notation. Section 3 is devoted to the application of coincidence degree theory to our problem. More in detail, we define an equivalent operator problem and we present three technical lemmas essential for the computation of the degree in the proof of our main result (Theorem 4.1), which is stated and proved in Section 4. In Section 5 we present various consequences and applications of the main theorem, as Theorem 1.1 and a nonexistence result (cf. Corollary 5.5). In Section 6 we deal with subharmonic solutions. In Theorem 6.1 we prove the
existence of infinitely many subharmonic solutions for (1.1) if the negative part of the weight is sufficiently strong (i.e. when $\mu > 0$ is large enough). This result follows from Theorem 1.1 applied to an interval of the form $[0, kT]$ and a careful verification that the constants needed for the proof are independent on $k$. In the same section we also discuss the number of subharmonics of a given order and we sketch how to produce bounded solutions on the real line which are not necessarily periodic. Even if we focus our main attention to the study of the periodic problem, in Section 7 we observe that variants of our main results can be given for the Neumann problem. Therein we also provide an application to radially symmetric solutions of PDEs on annular domains. Finally, in Appendix A we discuss some basic facts about the coincidence degree defined in open and possibly unbounded sets and we state some lemmas for the computation of the degree, while in Appendix B we present a combinatorial lemma which is of crucial importance both for the computation of the coincidence degree and for our main multiplicity results.

2 Setting and notation

In this section we present the main elements involved in the study of the positive $T$-periodic solutions of the equation

$$u'' + cu' + (a^+(t) - \mu a^-(t))g(u) = 0.$$  \hfill (2.1)

For $\mu > 0$, we set

$$a_\mu(t) := a^+(t) - \mu a^-(t).$$

The hypotheses that will follow will be assumed from now on in the paper.

Let $g: \mathbb{R}^+ \to \mathbb{R}^+$ be a continuous function such that

$$(g_0) \quad g(0) = 0, \quad g(s) > 0 \quad \text{for} \quad s > 0.$$  

Suppose also that

$$(g_1) \quad g_0 := \limsup_{s \to 0^+} \frac{g(s)}{s} < +\infty \quad \text{and} \quad g_{\infty} := \liminf_{s \to +\infty} \frac{g(s)}{s} > 0.$$  

The weight coefficient $a: \mathbb{R} \to \mathbb{R}$ is a locally integrable $T$-periodic function such that, in a time-interval of length $T$, there exists a finite number of closed pairwise disjoint intervals where $a(t) > 0$, separated by closed intervals where $a(t) < 0$. In this case, thanks to the periodicity of $a(t)$, we can suitably choose an interval $[t_0, t_0 + T]$, which we identify with $[0, T]$ for notational convenience, such that the following condition $(a_*)$ holds.

$(a_*)$ There exist $m \geq 2$ closed and pairwise disjoint intervals $I_1^+, \ldots, I_m^+$ separated by $m$ closed intervals $I_1^-, \ldots, I_m^-$ such that

$$a(t) > 0 \quad \text{on} \quad I_1^+, \quad a(t) < 0 \quad \text{on} \quad I_1^-,$$

and, moreover,

$$\bigcup_{i=1}^{m} I_i^+ \cup \bigcup_{i=1}^{m} I_i^- = [0, T].$$
To explain this fact with an example, suppose that we take \( a(t) = \cos(2t) \) as a 2\(\pi\)-periodic function. In this case, on \([0, 2\pi]\) we have three positive humps and two negative ones. However, in order to enter in the setting of \((a_*)\) and hence to look at the weight as a function with two positive humps separated by two negative ones in a time-interval of length 2\(\pi\), we can choose \([t_0, t_0 + 2\pi]\), for \(t_0 = 3\pi/4\), as interval of periodicity. When, for convenience in the exposition, we say that we work with the standard period interval \([0, 2\pi]\), we are in fact considering a shift of \(t_0\) of the weight function, e.g. taking \(\cos(2t + 2t_0)\) as effective coefficient. Clearly, this does not affect our considerations as long as we are interested in 2\(\pi\)-periodic solutions. In the same example, let us fix an integer \(k \geq 2\) and consider the coefficient \(\cos(2t + 2t_0) = \sin(2t)\) as a 2\(k\pi\)-periodic function. In the period interval \([0, 2k\pi]\) the weight has \(m = 2k\) intervals of positivity separated by \(2k\) intervals of negativity. We will consider again a similar example dealing with subharmonic solutions.

In the sequel, it will be not restrictive to label the intervals \(I_i^+\) and \(I_i^-\) following the natural order given by the standard orientation of the real line and thus determine \(2\pi\) + 1 points

\[ 0 = \sigma_1 < \tau_1 < \sigma_2 < \tau_2 < \ldots < \sigma_{m-1} < \tau_{m-1} < \sigma_m < \tau_m < \sigma_{m+1} = T, \]

so that, for \(i = 1, \ldots, m\),

\[ I_i^+ := [\sigma_i, \tau_i] \quad \text{and} \quad I_i^- := [\tau_i, \sigma_{i+1}]. \]

Finally, consistently with assumption \((a_*)\) and without loss of generality, we select the points \(\sigma_i\) and \(\tau_i\) in such a manner that \(a(t) \neq 0\) on all left neighborhoods of \(\sigma_i\) (for \(i > 1\)) and on all right neighborhoods of \(\tau_i\). In other words, if there is an interval \(J\) contained in \([0, T]\) where \(a(t) \equiv 0\), we choose the points \(\sigma_i\) and \(\tau_i\) so that \(J\) is contained in one of the \(I_i^+\) or \(J\) is contained in the interior of one of the \(I_i^-\).

We denote by \(\lambda_{i,1}^+\), \(i = 1, \ldots, m\), the first eigenvalue of the eigenvalue problem in \(I_i^+\)

\[ \varphi'' + c\varphi' + \lambda a(t)\varphi = 0, \quad \varphi|_{\partial I_i^+} = 0. \]

From the assumptions on \(a(t)\) in \(I_i^+\), it clearly follows that \(\lambda_{i,1}^+ > 0\) for each \(i = 1, \ldots, m\).

We introduce some other useful notations. Let \(I \subset \{1, \ldots, m\}\) be a subset of indices (possibly empty) and let \(d, D\) be two fixed positive real numbers with \(d < D\). We define two families of open unbounded sets

\[ \Omega_{d,D}^I := \left\{ u \in C([0,T]): \max_{t \in I_i^+} |u(t)| < D, \ i \in I; \right\} \]

\[ \max_{t \in I_i^-} |u(t)| < d, \ i \in \{1, \ldots, m\} \setminus I \right\} \] \hspace{1cm} (2.2)

and

\[ \Lambda_{d,D}^I := \left\{ u \in C([0,T]): d < \max_{t \in I_i^+} |u(t)| < D, \ i \in I; \right\} \]

\[ \max_{t \in I_i^-} |u(t)| < d, \ i \in \{1, \ldots, m\} \setminus I \right\}. \] \hspace{1cm} (2.3)
We note that, for each \( I \subseteq \{1, \ldots, m \} \), we have
\[
\Omega_{d,D}^I = \bigcup_{J \subseteq I} \Lambda_{d,D}^J,
\]
and the union is disjoint, since \( \Lambda_{d,D}^J \cap \Lambda_{d,D}^{J'} = \emptyset \), for \( J \neq J' \).

In the sequel, once the constants \( d \) and \( D \) are fixed, we simply use the symbols \( \Omega^I \) and \( \Lambda^I \) to denote \( \Omega_{d,D}^I \) and \( \Lambda_{d,D}^I \), respectively.

3 The abstract setting of the coincidence degree

In this section we apply the coincidence degree theory, that we will present in Appendix A, to study the periodic problem associated with equation (2.1). We follow the same approach presented in [47].

Let \( X := C([0,T]) \) be the Banach space of continuous functions \( u : [0, T] \rightarrow \mathbb{R} \), endowed with the sup-norm
\[
\|u\|_\infty := \max_{t \in [0,T]} |u(t)|,
\]
and let \( Z := L^1([0,T]) \) be the space of integrable functions \( w : [0, T] \rightarrow \mathbb{R} \), endowed with the norm
\[
\|w\|_{L^1} := \int_0^T |w(t)| \, dt.
\]
We consider the linear differential operator \( L : \text{dom} L \rightarrow Z \) defined as
\[
(Lu)(t) := -u''(t) - cu'(t), \quad t \in [0, T],
\]
where \( \text{dom} L \) is determined by the functions of \( X \) which are continuously differentiable with absolutely continuous derivative and satisfying the periodic boundary condition
\[
u(0) = u(T), \quad u'(0) = u'(T).
\]
Therefore, \( L \) is a Fredholm map of index zero, \( \ker L \) and \( \text{coker} L \) are made by the constant functions and
\[
\text{Im} L = \left\{ w \in Z : \int_0^T w(t) \, dt = 0 \right\}.
\]
As projectors \( P : X \rightarrow \ker L \) and \( Q : Z \rightarrow \text{coker} L \) associated with \( L \) we choose the average operators
\[
P u = Qu := \frac{1}{T} \int_0^T u(t) \, dt.
\]
Notice that \( \ker P \) is given by the continuous functions with mean value zero. Finally, let \( K_P : \text{Im} L \rightarrow \text{dom} L \cap \ker P \) be the right inverse of \( L \), which is the operator that at any function \( w \in Z \) with \( \int_0^T w(t) \, dt = 0 \) associates the unique solution \( u \) of
\[
u'' + cu' + w(t) = 0, \quad \text{with} \quad \int_0^T u(t) \, dt = 0,
\]
and satisfying the boundary condition (3.1).

Thereafter, on $\mathbb{R}^2$ we define the $L^1$-Carathéodory function
\[ \tilde{f}(t, s) := \begin{cases} a_\mu(t)g(s), & \text{if } s \geq 0; \\ -s, & \text{if } s \leq 0; \end{cases} \]
and observe that $\tilde{f}(t + T, s) = \tilde{f}(t, s)$ for a.e. $t \in \mathbb{R}$ and for all $s \in \mathbb{R}$. Let $N: X \to Z$ be the Nemytskii operator induced by $\tilde{f}$, that is
\[ (Nu)(t) := \tilde{f}(t, u(t)), \quad t \in [0, T]. \]

According to the above positions, if $u$ is a $T$-periodic solution of
\[ u'' + cu' + \tilde{f}(t, u) = 0, \tag{3.2} \]
then $u|_{[0, T]}$ is a solution of the coincidence equation
\[ Lu = Nu, \quad u \in \text{dom } L. \tag{3.3} \]

Conversely, any solution $u$ of (3.3) can be extended by $T$-periodicity to a $T$-periodic solution of (3.2). Moreover, from the definition of $\tilde{f}$ and conditions $(g_*)$ and $(g_1)$, one can easily verify by a maximum principle argument (cf. [31, Lemma 6.1]) that if $u \not\equiv 0$ is a solution of (3.3), then $u(t)$ is strictly positive and hence a positive $T$-periodic solution of (2.1) (once extended by $T$-periodicity to the whole real line).

As remarked in Appendix A, the operator equation (3.3) is equivalent to the fixed point problem
\[ u = \Phi u := Pu + QNu + K_P(Id - Q)Nu, \quad u \in X, \]
where we have chosen the identity on $\mathbb{R}$ as linear orientation-preserving isomorphism $J$ from $\text{coker } L$ to $\ker L$ (both identified with $\mathbb{R}$).

Now we are interested in computing the coincidence degree of $L$ and $N$ in some open domains. For this purpose, we will consider some modifications of (3.2) which correspond to operator equations of the form (3.3) for the associated Nemytskii operators $N$. In the sequel we will also identify the $T$-periodic solutions with solutions defined on $[0, T]$ and satisfying the boundary condition (3.1). We also denote by $L^1_T$ the space of locally integrable and $T$-periodic functions $w: \mathbb{R} \to \mathbb{R}$ (which can be identified with $Z$).

The subsequent two lemmas are direct applications of Lemma A.1 and Lemma A.2 respectively. They give conditions for the computation of the degree on some open balls. The standard proofs are omitted (see [11, Lemma 2.2] and [31, Theorem 2.1] for the details).

**Lemma 3.1.** Let $\mu > 0$ be such that $\int_0^T a_\mu(t) \, dt < 0$. Assume that there exists a constant $d > 0$ such that the following property holds.

$(H_d)$ If $\vartheta \in [0, 1]$ and $u(t)$ is any non-negative $T$-periodic solution of
\[ u'' + cu' + \vartheta a_\mu(t)g(u) = 0, \tag{3.4} \]
then $\max_{t \in [0, T]} u(t) \neq d$. 

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Then
\[ D_L(L - N, B(0, d)) = 1. \]

**Lemma 3.2.** Assume that there exists a constant \( D > 0 \) such that the following property holds.

\((H^D)\) There exist a non-negative function \( v \in L^1_T \) with \( v \not\equiv 0 \) and a constant \( \alpha_0 > 0 \), such that every \( T \)-periodic solution \( u(t) \geq 0 \) of the boundary value problem
\[ u'' + cu' + a_\mu(t)g(u) + \alpha v(t) = 0, \tag{3.5} \]
for \( \alpha \in [0, \alpha_0] \), satisfies \( \|u\|_\infty \not= D \). Moreover, there are no solutions \( u(t) \) of (3.5) for \( \alpha = \alpha_0 \) with \( 0 \leq u(t) \leq D \), for all \( t \in \mathbb{R} \).

Then
\[ D_L(L - N, B(0, D)) = 0. \]

In order to achieve our multiplicity result, in Section 4 we will fix \( d, D > 0 \) satisfying (\(H_d\)) and (\(H^D\)), respectively, and compute the coincidence degree in the open and unbounded sets \( \Lambda_{d,D} \), for \( I \subseteq \{1, \ldots, m\} \). To this aim the following lemma is of utmost importance (see [11, Lemma 2.1] for a similar statement). In the next result we consider again equation (3.5) of the previous lemma.

**Lemma 3.3.** Let \( J \subseteq \{1, \ldots, m\} \) be a nonempty subset of indices, let \( d > 0 \) be a constant and \( v \in L^1_T \) a non-negative nontrivial function, such that the following properties hold.

\((A_d,J)\) If \( \alpha \geq 0 \), then any non-negative \( T \)-periodic solution \( u(t) \) of (3.5) satisfies \( \max_{t \in I^+_j} u(t) \not= d \), for all \( j \in J \).

\((B_d,J)\) For every \( \beta \geq 0 \) there exists a constant \( D_\beta > d \) such that if \( \alpha \in [0, \beta] \) and \( u(t) \) is any non-negative \( T \)-periodic solution of (3.5) with \( \max_{t \in I^+_j} u(t) \leq d \), for all \( j \in J \), then \( \max_{t \in [0,T]} u(t) \leq D_\beta \).

\((C_d,J)\) There exists \( \alpha_0 > 0 \) such that equation (3.5), with \( \alpha = \alpha_0 \), does not possess any non-negative \( T \)-periodic solution \( u(t) \) with \( \max_{t \in I^+_j} u(t) \leq d \), for all \( j \in J \).

Then
\[ D_L(L - N, \Gamma_{d,J}) = 0, \]
where
\[ \Gamma_{d,J} := \left\{ u \in C([0,T]): \max_{t \in I^+_j} |u(t)| < d, j \in J \right\}. \tag{3.6} \]

**Proof.** According to the setting presented in this section, conditions (\(A_d,J\)), (\(B_d,J\)) and (\(C_d,J\)) are equivalent to conditions (a), (b) and (c) of Lemma 3.3 with respect to the open set \( \Omega := \Gamma_{d,J} \). Therefore, the thesis of Lemma 3.3 follows.

**Remark 3.1.** From a theoretical point of view, the choice of the set of indices \( J \) with \( \emptyset \neq J \subseteq \{1, \ldots, m\} \) is arbitrary. However, as we will see in the next section, in the actual applications of Lemma 3.3 we shall take \( J \subsetneq \{1, \ldots, m\} \) because, in our setting, the case \( J = \{1, \ldots, m\} \) will be discussed in the frame of Lemma 3.1. 

\[ \Box \]
4 The main multiplicity result

In this section we use all the tools just presented in the previous sections to prove the following main result.

**Theorem 4.1.** Let \( g : \mathbb{R}^+ \to \mathbb{R}^+ \) be a continuous function satisfying \((g_*)\),
\[ g_0 = 0 \quad \text{and} \quad g_\infty > \max_{i=1, \ldots, m} \lambda_i^1. \]

Let \( a : \mathbb{R} \to \mathbb{R} \) be a \( T \)-periodic locally integrable function satisfying \((a_*)\). Then there exists \( \mu^* > 0 \) such that for all \( \mu > \mu^* \) equation \((2.1)\) has at least \( 2^m - 1 \) positive \( T \)-periodic solutions.

**Remark 4.1.** The \( 2^m - 1 \) positive \( T \)-periodic solutions are obtained as follows. Along the proof we provide two constants \( 0 < r < R \) (with \( r \) small and \( R \) large) such that if \( \mu > \mu^* \), given any nonempty set of indices \( I \subseteq \{1, \ldots, m\} \), there exists at least one positive \( T \)-periodic solution \( u_I \in \Lambda_{R, r} \) such that \( u_I(t) \) is small for all \( t \in I^+ \) when \( i \notin I \), and, on the other hand, \( r < u_I(t) < R \) for some \( t \in I^+ \) when \( i \in I \). We will also prove that, when \( \mu \) is sufficiently large, all these solutions are small in the \( I_i^- \) intervals (see Section 4.5).

**Remark 4.2.** The assumption \( g_0 = 0 \) in Theorem 4.1 can be slightly improved to a condition of the form
\[ 0 < \lambda_* < \min_{i=1, \ldots, m} \lambda_i^1. \]
where \( \lambda_* \) is a positive constant which satisfies
\[ 0 < \lambda_* < \min_{i=1, \ldots, m} \lambda_i^1. \]
A lower bound for \( \lambda_* \) (although not sharp) is explicitly given by the constant \( 1/K_0 \) provided in (4.16) in Section 4.2 (see also Remark 4.5 for more details). When \( c = 0 \) it is easy to check that \( 1/K_0 \) is strictly less than \( 4/(|I^+_i| \int_{I^+_i} a^+(t) \, dt) \) (for all \( i = 1, \ldots, m \)), which are the constants corresponding to the application of Lyapunov inequality to each of the intervals of positivity (cf. [41, ch. XI]).

4.1 General strategy and proof of Theorem 4.1

In this section, we describe the main steps that define the proof of Theorem 4.1. The details can be found in the following three sections.

First of all, in Section 4.2 from \( g_0 = 0 \) we fix a (small) constant \( r > 0 \) such that
\[ \eta(r) := \sup_{0 < s \leq r} \frac{g(s)}{s} \quad (4.1) \]
is sufficiently small (cf. condition (4.16)). For this fixed \( r \), we determine a constant \( \mu_r \), with
\[ \mu_r > \mu^\#: = \frac{\int_0^T a^+(t) \, dt}{\int_0^T a^-(t) \, dt} \quad (4.2) \]
such that condition \((H_r)\) of Lemma 3.1 is satisfied for every \( \mu \geq \mu_r \) and therefore
\[ D_L(L - N, B(0, r)) = 1. \quad (4.3) \]
It is important to notice that, for the validity of (4.3), it is necessary to take \( \mu > \mu^# \) in order to have \( \int_0^T a_\mu(t) \, dt < 0 \).

As a second step, in Section 4.3, we show that there exists a constant \( R^* \), with \( 0 < r < R^* \), such that, for any nontrivial function \( v \in L^1([0,T]) \) satisfying

\[
v(t) \geq 0 \quad \text{on} \quad \bigcup_{i=1}^m I_i^+, \quad v(t) = 0 \quad \text{on} \quad \bigcup_{i=1}^m I_i^- ,
\]

(4.4)

and for all \( \alpha \geq 0 \), it holds that any non-negative solution \( u(t) \) of (3.5) is bounded by \( R^* \), namely

\[
\max_{t \in [0,T]} u(t) < R^*.
\]

(4.5)

This result is proved using the lower bound of \( g_\infty \) and the constant \( R^* \) can be chosen independently on the functions \( v(t) \) satisfying (4.4).

In this manner (for \( \alpha = 0 \)) we obtain also a priori bound for all non-negative \( T \)-periodic solutions of (2.1). Then, we verify that condition \( (H^R) \) of Lemma 3.2 is satisfied for all \( R \geq R^* \). Hence, we have

\[
D_L(L - N, B(0, R)) = 0, \quad \forall R \geq R^*.
\]

(4.6)

It is important to notice that, in order to prove (4.5) and consequently (4.6), we only use information about \( a^+(t) \). Hence \( R^* \) can be chosen independently on \( \mu > 0 \).

**Remark 4.3.** Using the additivity property of the coincidence degree, from (4.3) and (4.6), we reach the following equality

\[
D_L(L - N, B(0, R^*) \setminus B[0, r]) = -1.
\]

Then, we obtain the existence of at least a nontrivial solution \( u \) of (3.3), provided that \( \mu > \mu_r \). Using a standard maximum principle argument, it is easy to prove that \( u \) is a positive \( T \)-periodic solution of (2.1) (cf. [31, Theorem 3.1 and Theorem 3.2] and see also Remark 4.6). \(<\)

At this point, we fix a constant \( R \) with

\[
0 < r < R^* \leq R
\]

and, for all sets of indices \( \mathcal{I} \subseteq \{1, \ldots, m\} \), we consider the open and unbounded sets

\[
\Omega^\mathcal{I} := \Omega^\mathcal{I}_{r,R} \quad \text{and} \quad \Lambda^\mathcal{I} := \Lambda^\mathcal{I}_{r,R}
\]

introduced in (2.2) and in (2.3), respectively.

As a third step, we will prove that

\[
D_L(L - N, \Lambda^\mathcal{I}) \neq 0, \quad \text{for all} \quad \mathcal{I} \subseteq \{1, \ldots, m\}.
\]

(4.7)

Before the proof of (4.7), we make the following observation which plays a crucial role in various subsequent steps.
Remark 4.4. Writing equation (2.1) as
\[(e^{ct}u')' + e^{ct}a_\mu(t)g(u) = 0,\]
we find that \((e^{ct}u'(t))' \leq 0\) for almost every \(t \in I_i^+\) and \((e^{ct}u'(t))' \geq 0\) for almost every \(t \in I_i^-\) (where \(u(t) \geq 0\) is any solution). Then, the map
\[t \mapsto e^{ct}u'(t)\]
is non-increasing on each \(I_i^+\) and non-decreasing on each \(I_i^-\). This property replaces the convexity of \(u(t)\) on \(I_i^-\), which is an obvious fact when \(c = 0\). For an arbitrary \(c \in \mathbb{R}\) we can still preserve some convexity type properties. In particular, for all \(i = 1, \ldots, m\) we have that
\[
\max_{t \in I_i^-} u(t) = \max_{t \in \partial I_i^-} u(t) = \max\{u(\tau_i), u(\sigma_{i+1})\},
\]
which is nothing but a one-dimensional form of a maximum principle for the differential operator \(L\). We verify now this fact since this property, although elementary, will be used several times in the sequel. Indeed, observe that if \(u'(t^*) \geq 0\), for some \(t^* \in [\tau_i, \sigma_{i+1}]\), then \(u'(t) \geq 0\) for all \(t \in [t^*, \sigma_{i+1}]\), hence \(u(t^*) \leq u(\sigma_{i+1})\). Similarly, if \(u'(t^*) \leq 0\), for some \(t^* \in [\tau_i, \sigma_{i+1}]\), then \(u'(t) \leq 0\) for all \(t \in [\tau_i, t^*]\), hence \(u(t^*) \leq u(\tau_i)\). From these remarks, (4.8) follows immediately.

In order to prove (4.7), first of all we consider \(\mathcal{I} = \emptyset\). Accordingly, we have that
\[
D_L(L - N; \Omega^\emptyset) = D_L(L - N, \Lambda^\emptyset) = D_L(L - N, B(0, r)) = 1.
\]
The first identity in (4.9) is trivial from the definitions of the sets, since \(\Omega^\emptyset = \Lambda^\emptyset\). It is also obvious that \(B(0, r) \subseteq \Omega^\emptyset\). Conversely, let \(u\) be a \(T\)-periodic solution of (2.1), belonging to \(\Omega^\emptyset\). By the maximum principle, we know that \(u\) is a (non-negative) \(T\)-periodic solution of (2.1). Moreover, \(u(t) < r\) for all \(t \in I_i^+, i = 1, \ldots, m\). Then, from (4.8) we have that \(u(t) < r\) for all \(t \in [0, T]\).

In (the application of formula (4.8) we have considered the interval \(I_m^+\), as an interval between \(I_m^+\) and \(I_1^+\), by virtue of the \(T\)-periodicity of the solution.) Finally, by the excision property of the coincidence degree and (4.3), formula (4.9) follows.

Next, we consider a nonempty subset of indices \(\mathcal{I} \subseteq \{1, \ldots, m\}\). In Section 4.4, choosing \(d = r\), \(J := \{1, \ldots, m\} \setminus \mathcal{I} \neq \emptyset\) and a nontrivial function \(v \in L^1([0, T])\) such that
\[
v(t) > 0 \text{ on } \bigcup_{i \in \mathcal{I}} I_i^+, \quad v(t) = 0 \text{ otherwise},
\]
we verify that the three conditions of Lemma 3.3 hold, for \(\mu\) sufficiently large. More in detail, we provide a lower bound \(\mu^\alpha_2 > 0\), with \(\mu^\alpha_2\) independent on \(\alpha\), such that condition (\(A_\mathcal{I}, \mathcal{J}\)) is satisfied for all \(\mu > \mu^\alpha_2\). Then, we fix an arbitrary \(\mu > \mu^\alpha_2\) and show that conditions (\(B_{\mathcal{I}, \mathcal{J}}\)) and (\(C_{\mathcal{I}, \mathcal{J}}\)) are satisfied as well.

Since \(R\) is an upper bound for all the solutions of (4.3) (cf. (4.5)), comparing the definitions (2.2) and (4.6), we see that \(u \in \Omega^\mathcal{I}\) if and only if \(u \in \Gamma_{\mathcal{I}, \mathcal{J}}\), for
each solution $u$. Hence, applying the excision property of the coincidence degree and Lemma [3.3] we obtain
\[ D_L(L - N, \Omega^I) = 0, \quad \text{for all } \emptyset \neq I \subseteq \{1, \ldots, m\}. \] (4.11)

Using again (4.8) in Remark [4.4] and arguing as above for $r$, we can check that $R$ is an a priori bound for the solutions on the whole domain. In this manner, by (4.6), if $I = \{1, \ldots, m\}$ we obtain
\[ D_L(L - N, \Omega^I) = 0, \quad \text{for all } \emptyset \neq I \subseteq \{1, \ldots, m\}. \] (4.12)

Finally, we define
\[ \mu^* := \mu_r \vee \max \{\mu^*_I : \emptyset \neq I \subseteq \{1, \ldots, m\}\}, \]
where, as usual, "$\vee$" denotes the maximum between two numbers. As a byproduct of the proof of (A$_{\mathcal{J}, r}$) in Section 4.4 (for $\alpha = 0$) we also have that for each $\mu > \mu^*$ the degree $D_L(L - N, \Lambda^I)$ is well defined for all $I \subseteq \{1, \ldots, m\}$ (technically, the matter is to observe that for $\mu$ sufficiently large the are no $T$-periodic solutions touching the level $r$ on some intervals $I^+\}$. At this point, following the same inductive argument as in [32, Lemma 4.1] and using (4.9) and (4.12), it is possible to prove that
\[ D_L(L - N, \Lambda^I) = (-1)^{#I}, \quad \text{for all } I \subseteq \{1, \ldots, m\}. \] (4.13)
holds for each $\mu > \mu^*$. In this manner, (4.7) is verified. Since formula (4.13) is crucial to prove our multiplicity result, we give the details of the proof in Appendix [B].

In conclusion, since the coincidence degree is nonzero in each $\Lambda^I$, there exists a solution $u \in \Lambda^I$ of (3.3), for all $I \subseteq \{1, \ldots, m\}$. Notice that $0 \notin \Lambda^I$ for all $\emptyset \neq I \subseteq \{1, \ldots, m\}$. As remarked in Section 3 by a maximum principle argument, for $I \neq \emptyset$ the solution $u \in \Lambda^I$ of (3.3) is a positive $T$-periodic solution of (2.1). Moreover, by (4.8), we also deduce that $\|u\|_\infty < R$. At this moment, we can summarize what we have proved as follows.

For each nonempty set of indices $I \subseteq \{1, \ldots, m\}$, there exists at least one $T$-periodic solution $u_I$ of (2.1) with $u_I \in \Lambda^I$ and such that $0 < u_I(t) < R$ for all $t \in \mathbb{R}$.

Finally, since the number of nonempty subsets of a set with $m$ elements is $2^m - 1$ and the sets $\Lambda^I$ are pairwise disjoint, we conclude that there are at least $2^m - 1$ positive $T$-periodic solutions of (2.1). The thesis of Theorem 4.1 follows. \(\square\)

Having already outlined the scheme of the proof, we provide now all the missing technical details.
4.2 Proof of \((H_r)\) for \(r\) small

In this section we find a sufficiently small real number \(r > 0\) such that \((H_r)\) is satisfied for all \(\mu\) large enough.

Let us start by introducing some constants that are crucial for our next estimates. Define

\[
K_i := \|a^+\|_{L^1(I_j^+)} e^{|\theta_i^{+}|}, \quad i = 1, \ldots, m, \tag{4.14}
\]

and

\[
K_0 := 2 \max_{i=1, \ldots, m} \left( |I_i^+| + e^{\theta_i^+} |I_i^-| \right). \tag{4.15}
\]

By \((g_4)\) and \(g_0 = 0\), we know that \(\eta(s) \to 0^+\) as \(s \to 0^+\) (where \(\eta(s)\) is defined in \((4.1)\)). So, we fix \(r > 0\) such that

\[
\eta(r) < \frac{1}{K_0}. \tag{4.16}
\]

Then, we fix a positive constant \(\mu_r > \mu^\#\) such that

\[
\mu_r > \frac{K_0 e^{\theta_i^-} \eta(r)}{\int_{\tau_i}^{\tau_i + 1} \int_{\tau_i}^1 a^{-}(\xi) d\xi dt \gamma(r)}, \quad \text{for all } i = 1, \ldots, m, \tag{4.17}
\]

where we have set

\[
\gamma(r) := \min_{\frac{r}{2} \leq s \leq r} g(s). \tag{4.18}
\]

We verify that condition \((H_d)\) of Lemma 3.1 is satisfied for \(d = r\), chosen as in \((4.16)\), and for all \(\mu \geq \mu_r\). Accordingly, we claim that there is no non-negative solution \(u(t)\) of \((3.4)\), for some \(\theta \in [0, 1]\) and \(\mu \geq \mu_r\), with \(\|u\|_{\infty} = r\).

Arguing by contradiction, let us suppose that, for some \(\theta\) and \(\mu\) with \(0 < \theta \leq 1\) and \(\mu \geq \mu_r\), there exists a \(T\)-periodic solution \(u(t)\) of

\[
u''(t) + cu'(t) + \partial a\mu(t) g(u(t)) = 0, \tag{4.19}
\]

with \(0 \leq u(t) \leq \max_{t \in [0, T]} u(t) = r\). Reasoning as in Remark 4.4, we observe that the solution \(u(t)\) in the interval of non-positivity attains its maximum at an end-point. Thus, there is an index \(j \in \{1, \ldots, m\}\) such that

\[
r = \max_{t \in [0, T]} u(t) = \max_{t \in I_j^+} u(t) = u(\hat{t}_j), \quad \text{for some } \hat{t}_j \in I_j^+ = [\sigma_j, \tau_j].
\]

Next, we notice that \(u'(\hat{t}_j) = 0\). Indeed, if \(u'(t) \neq 0\) for all \(t \in I_j^+\) such that \(u(t) = r\), then \(t = \sigma_j\) or \(t = \tau_j\). If \(t = \tau_j\), then \(u'(t) > 0\) and, since the map \(t \mapsto e^{ct} u'(t)\) is non-decreasing on \(I_j^-\) (cf. Remark 4.4), we have \(u'(t) \geq u'(\tau_j) e^{c(\tau_j-t)} > 0\), for all \(t \in I_j^-\). Then we obtain \(r = u(\tau_j) < u(\tau_{j+1})\), a contradiction with respect to \(\|u\|_{\infty} = r\). If \(t = \sigma_j\), one can obtain an analogous contradiction considering the interval \(I_{j-1}^-\) (if \(j = 1\), we deal with \(I_m^- - \tau\), by \(T\)-periodicity).

Writing \((4.18)\) on \(I_j^+\) as

\[
\left( e^{ct} u'(t) \right)' = -\theta a^+(t) g(u(t)) e^{ct},
\]

Next, we notice that \(u'(\hat{t}_j) = 0\). Indeed, if \(u'(t) \neq 0\) for all \(t \in I_j^+\) such that \(u(t) = r\), then \(t = \sigma_j\) or \(t = \tau_j\). If \(t = \tau_j\), then \(u'(t) > 0\) and, since the map \(t \mapsto e^{ct} u'(t)\) is non-decreasing on \(I_j^-\) (cf. Remark 4.4), we have \(u'(t) \geq u'(\tau_j) e^{c(\tau_j-t)} > 0\), for all \(t \in I_j^-\). Then we obtain \(r = u(\tau_j) < u(\tau_{j+1})\), a contradiction with respect to \(\|u\|_{\infty} = r\). If \(t = \sigma_j\), one can obtain an analogous contradiction considering the interval \(I_{j-1}^-\) (if \(j = 1\), we deal with \(I_m^- - \tau\), by \(T\)-periodicity).

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Writing \((4.18)\) on \(I_j^+\) as

\[
\left( e^{ct} u'(t) \right)' = -\theta a^+(t) g(u(t)) e^{ct},
\]
integrating between \( t_j \) and \( t \) and using \( u'(t_j) = 0 \), we obtain
\[
u'(t) = -\vartheta \int_{t_j}^{t} a^+(\zeta) g(u(\zeta)) e^{c(\zeta - t)} \, d\zeta, \quad \forall t \in I_j^+.
\]
Hence,
\[
\|u'\|_{L^\infty(I_j^+)} \leq \vartheta \|a^+\|_{L^1(I_j^+)} \eta(r) r e^{c|I_j^+|} = \varrho K_j \eta(r) r.
\] (4.19)

We conclude that
\[
r \geq u(t_j) = u(t_j) + \int_{t_j}^{t} u'(\zeta) \, d\zeta \geq r \left( 1 - \varrho K_j \eta(r) |I_j^+| \right).
\] (4.20)

Now we consider the subsequent (adjacent) interval \( I_{j-} = [\tau_j, \sigma_{j+1}] \) where the weight is non-positive. Since (as just remarked) the map \( t \mapsto e^{ct} u'(t) \) is non-decreasing on \( I_{j-} \), we have \( e^{ct} u'(t) \geq e^{ct} u'(t_j) \) for all \( t \in I_{j-} \). Therefore, recalling also (4.19), we get
\[
u'(t) \geq e^{c(t_j-t)} u'(t_j) \geq -e^{c|I_j^-|} \varrho K_j \eta(r) r, \quad \forall t \in I_{j-}.
\]
Integrating on \( [\tau_j, t] \subseteq I_{j-} \) and using (4.20), we have that
\[
r \geq u(t) \geq u(t_j) - |I_j^-| e^{c|I_j^-|} \varrho K_j \eta(r) r
\]
\[
\geq r \left( 1 - \varrho K_j (|I_j^+| + |I_j^-| e^{c|I_j^-|}) \eta(r) \right)
\]
\[
\geq r \left( 1 - \varrho \frac{K_0}{2} \eta(r) \right) \geq r \left( 1 - \frac{\varrho}{2} \right) \geq \frac{r}{2}
\] (4.21)
holds for all \( t \in I_{j-} \). Writing (4.18) on \( I_{j-} \) as
\[
(e^{ct} u'(t))' = \mu \vartheta a^-(t) g(u(t)) e^{ct}
\]
and integrating on \([\tau_j, t] \subseteq I_{j-} \), we have
\[
u'(t) = e^{c(t_j-t)} u'(t_j) + \mu \vartheta \int_{\tau_j}^{t} a^-(\xi) g(u(\xi)) e^{c(\xi - t)} \, d\xi, \quad \forall t \in I_{j-}.
\]
Then, using (4.19) and recalling the definition of \( \gamma(r) \), we find
\[
u'(t) \geq \varrho r \left( -e^{c|I_j^-|} K_j \eta(r) + \frac{1}{2} \mu \gamma(r) e^{-c|I_j^-|} \int_{\tau_j}^{t} a^-(\xi) \, d\xi \right), \quad \forall t \in I_{j-}.
\]
Finally, integrating on \( I_{j-} \), we obtain
\[
u(\sigma_{j+1}) = u(t_j) + \int_{\tau_j}^{\sigma_{j+1}} u'(\xi) \, d\xi
\]
\[
\geq r \left( 1 - \varrho K_j \eta(r) |I_{j+}^-| - \varrho |I_{j-}^-| e^{c|I_{j-}^-|} K_j \eta(r) \right
\]
\[
+ \mu \frac{\varrho}{2} \gamma(r) e^{-c|I_{j-}^-|} \int_{\tau_j}^{\sigma_{j+1}} \int_{\tau_j}^{t} a^-(\xi) \, d\xi \, dt \right)
\]
\[
> r,
\]
a contradiction with respect to the choice of \( \mu \geq \mu_r \) (cf. (4.17)). \( \square \)
Remark 4.5. From the proof it is clear that we do not really need that \(g_0 = 0\), but we only use the fact that \(r > 0\) can be chosen so that \((4.16)\) is satisfied. Accordingly, our result is still valid if we assume that \(g_0\) is sufficiently small. Clearly, some smallness condition on \(g_0\) has to be required for the validity of our estimates. Indeed, the same argument of the proof (if applied to \(g(s) = \lambda s\)) shows that \(1/K_0\) must be strictly less to all the first eigenvalues \(\lambda_1^+\) as well as to all the first eigenvalues of the Dirichlet-Neumann problems (or focal point problems) relative to the intervals \(I_i^+\). As a consequence, we could slightly improve condition \(g_0 = 0\) of Theorem 4.1 to an assumption of the form \(g_0 < \lambda^*\), where the optimal choice for \(\lambda^*\) would be that of a suitable positive constant satisfying \(\lambda^* < \min_i \lambda_1^+\) (as well as other similar conditions). The constant \(1/K_0\) found in the proof could be improved by choosing a smaller value for \(K_0\) in \((4.15)\). Indeed, note that the factor 2 in \((4.15)\) corresponds to the lower bound \(u(t) \geq r/2\) in \((4.21)\). We do not investigate further this aspect as it is not prominent for our results. Technical estimates related to Lyapunov type inequalities and lower bounds for the first eigenvalue of Dirichlet-Neumann problems with weights have been studied, for instance, in [14, 29, 59].

Remark 4.6. We stress that in the above proof we have used only the continuity of \(g(s)\) (near \(s = 0\)), condition \((g_*)\) and the hypothesis \(g_0 = 0\). In our recent work [31], to obtain the existence of at least a \(T\)-periodic solution of equation \((2.1)\), we have proved the existence of an \(r > 0\) small such that \((H_d)\) holds for all \(0 < d \leq r\), provided that the mean value of the weight is negative. In our case, such condition on the weight is equivalent to \(\mu > \mu^#\), which is a better condition than \(\mu \geq \mu_r\) given here in our proof. However, in order to use a weaker assumption on the weight, in [31] we have to require a stronger hypothesis on the nonlinearity \(g(s)\) near zero. In particular, we have to suppose that \(g(s)\) is continuously differentiable on a right neighborhood of \(s = 0\) (cf. [31, Theorem 3.2]) or that \(g(s)\) is regularly oscillating at zero, i.e.

\[
\lim_{s \to 0^+} \frac{g(\omega s)}{g(s)} = 1
\]

(cf. [31, Theorem 3.1] and the references listed at the end of [31, § 1] for more information about regularly oscillating functions).

With regard to this topic, we observe that even if we have proved the existence of a sufficiently small \(r\) such that \((H_\infty)\) holds, we can also verify that \((H_d)\) holds for all \(0 < d \leq r\) under supplementary assumptions on \(g(s)\) near zero. For instance, this claim can be proved if we suppose that \(g(s)\) satisfies

\[
\liminf_{s \to 0^+} \frac{g(\sigma s)}{g(s)} > 0, \quad \text{for all } \sigma > 1,
\]

(cf. \((4.17)\)). The above hypothesis is also called a lower \(\sigma\)-condition at zero and it is dual with respect to the more classical \(\Delta_2\)-condition at infinity considered in the theory of Orlicz-Sobolev spaces (cf. [11, ch. VIII]). We refer to [3, 26] for a discussion about these ones and related growth assumptions at infinity, as well as for a comparison between different Karamata type conditions.
4.3 The a priori bound $R^*$

Consider an arbitrary function $v \in L^1([0,T])$ as in (4.4). For example, as $v(t)$ we can take the characteristic function of the set

$$A := \bigcup_{i=1}^m I_i^+.$$  

We will show that there exists $R^* > 0$ such that, for each $\alpha \geq 0$, every non-negative $T$-periodic solution $u(t)$ of (3.5) satisfies $\max_{t \in A} u(t) < R^*$.

First of all, for all $i = 1, \ldots, m$, we look for a bound $R_i^* > 0$ such that any non-negative $T$-periodic solution $u(t)$ of (3.5), with $\alpha \geq 0$, satisfies

$$\max_{t \in I_i^+} u(t) < R_i.$$  

(4.22)

Let us fix $i \in \{1, \ldots, m\}$. Let $0 < \varepsilon < (\tau_i - \sigma_i)/2$ be fixed such that $a(t) \not\equiv 0$ on $[\sigma_i + \varepsilon, \tau_i - \varepsilon] \subseteq I_i^+$ and the first (positive) eigenvalue $\hat{\lambda}$ of the eigenvalue problem

$$\begin{cases}
\varphi'' + c\varphi' + \lambda a(t)\varphi = 0 \\
\varphi(\sigma_i + \varepsilon) = \varphi(\tau_i - \varepsilon) = 0
\end{cases}$$

satisfies $g_\infty > \hat{\lambda}$.

For notational convenience, we set $\sigma_\varepsilon := \sigma_i + \varepsilon$ and $\tau_\varepsilon := \tau_i - \varepsilon$. The existence of $\varepsilon$ is ensured by the continuity of the first eigenvalue as a function of the boundary points and by hypothesis $g_\infty > \lambda_1$.

We fix a constant $M > 0$ such that

$$g_\infty > M > \hat{\lambda}.$$  

It follows that there exists a constant $\tilde{R} = \tilde{R}(M) > 0$ such that

$$g(s) > Ms, \quad \forall s \geq \tilde{R}.$$  

Arguing as in [11, § 3.1], we can prove that

$$u'(t) \leq u(t) \frac{e^{cT}}{\varepsilon}, \quad \text{for all } t \in [\sigma_\varepsilon, \tau_\varepsilon] \text{ such that } u'(t) \geq 0;$$

$$|u'(t)| \leq u(t) \frac{e^{cT}}{\varepsilon}, \quad \text{for all } t \in [\sigma_i, \tau_\varepsilon] \text{ such that } u'(t) \leq 0.$$  

(4.23)

To understand how to get these inequalities, we note that the result is trivial if $u'(t) = 0$. Then, we deal separately with the cases $u'(t) > 0$ and $u'(t) < 0$. In the former case, since the map $t \mapsto e^{ct}u'(t)$ is non-increasing on $I_i^+$ we find that $u'(\xi) \leq e^{c(t-\xi)}u'(t)$ for all $\sigma_i \leq \xi \leq t$. Therefore the first inequality in (4.23) is obtained after an integration on $[\sigma_i, t]$ and observing that $t - \sigma_i \geq \varepsilon$. A symmetric argument works if $u'(t) < 0$, integrating on $[t, \tau_i]$. This yields to the second inequality in (4.23).
We are ready now to prove (4.22). By contradiction, suppose there is not a constant \( R_0 > 0 \) with the properties listed above. So, for each integer \( n > 0 \) there exists a solution \( u_n \geq 0 \) of (5.5) with \( \max_{t \in I^+_n} u_n(t) =: \tilde{R}_n > n \). For each \( n > \tilde{R} \) we take \( \tilde{t}_n \in I^+_n \) such that \( u_n(\tilde{t}_n) = \tilde{R}_n \) and let \( [\varsigma_n, \omega_n[ \subseteq I^+_n \) be the intersection with \([\varsigma, \tau[\) of the maximal open interval containing \( \tilde{t}_n \) and such that \( u_n(t) > \tilde{R} \) for all \( t \in [\varsigma_n, \omega_n[ \). We fix an integer \( N \) such that

\[
N > \tilde{R} + \frac{\tilde{R}Te^{2|\epsilon|T}}{\epsilon}
\]

and we claim that \([\varsigma_n, \omega_n[ \supseteq [\varsigma, \tau[\), for each \( n \geq N \). Suppose by contradiction that \( \varsigma \leq \varsigma_n \). In this case, we find that \( u_n(\varsigma_n) = \tilde{R} \) and \( u'_n(\varsigma_n) \geq 0 \). Moreover, \( u'_n(\varsigma_n) \leq \tilde{R}e^{2|\epsilon|T} / \epsilon \). Using the monotonicity of \( t \mapsto e^{\epsilon}u'(t) \), we get \( e^{\epsilon}u'(t) \leq e^{\epsilon}u'(\varsigma_n) \) for every \( t \in [\varsigma_n, \tilde{t}_n] \) and therefore we find \( u'(t) \leq \tilde{R}e^{2|\epsilon|T}/\epsilon \) for every \( t \in [\varsigma_n, \tilde{t}_n] \). Finally, an integration on \([\varsigma_n, \tilde{t}_n]\) yields

\[
n < \tilde{R}_n = u_n(\tilde{t}_n) \leq \tilde{R} + \frac{\tilde{R}Te^{2|\epsilon|T}}{\epsilon},
\]

hence a contradiction, since \( n \geq N \). A symmetric argument provides a contradiction if we suppose that \( \omega_n \leq \tau \). This proves the claim.

So, we can fix an integer \( \tilde{N} > \tilde{R} \) such that \( u_n(t) > \tilde{R} \) for every \( t \in [\varsigma, \tau[\) and \( n \geq \tilde{N} \). The function \( u_n(t) \), being a solution of equation (5.5) or equivalently of

\[
(e^{\epsilon}u')' + e^{\epsilon}(a_n(t)g(u) + \alpha v(t)) = 0,
\]

satisfies

\[
\begin{align*}
u_n'(t) &= e^{-et}y_n(t) \\
\tilde{y}_n'(t) &= -e^{-et}(a_n(t)g(u_n(t)) + \alpha v(t)).
\end{align*}
\]

Via a Prüfer transformation, we pass to the polar coordinates

\[
e^{\epsilon}u_n'(t) = r_n(t) \cos \vartheta_n(t), \quad u_n(t) = r_n(t) \sin \vartheta_n(t),
\]

and obtain, for every \( t \in [\varsigma, \tau[\), that

\[
\vartheta_n'(t) = e^{-\epsilon} \cos^2 \vartheta_n(t) + \frac{e^{\epsilon}(a_n(t)g(u_n(t)) + \alpha v(t))}{u_n(t)} \sin^2 \vartheta_n(t)
\]

\[
\geq e^{-\epsilon} \cos^2 \vartheta_n(t) + e^{\epsilon}Ma(t) \sin^2 \vartheta_n(t).
\]

We also consider the linear equation

\[(e^{\epsilon}u')' + e^{\epsilon}Ma^+(t)u = 0\tag{4.24}\]

and its associated angular coordinate \( \vartheta(t) \) (via the Prüfer transformation), which satisfies

\[
\vartheta'(t) = e^{-\epsilon} \cos^2 \vartheta(t) + e^{\epsilon}Ma^+(t) \sin^2 \vartheta(t).
\]

Note also that the angular functions \( \vartheta_n \) and \( \vartheta \) are non-decreasing in \([\varsigma, \tau[\). Using a classical comparison result in the frame of Sturm’s theory (cf. [22], ch. 8, Theorem 1.2]), we find that

\[
\vartheta_n(t) \geq \vartheta(t), \quad \forall t \in [\varsigma, \tau[,
\]

\[
(4.25)
\]
if we choose \( \vartheta(\sigma_z) = \vartheta_n(\sigma_z) \). Consider now a fixed \( n \geq N \). Since \( u_n(t) \geq \tilde{R} \) for every \( t \in [\sigma_z, \tau_z] \), we must have

\[
\vartheta_n(t) \in [0, \pi], \quad \forall t \in [\sigma_z, \tau_z].
\]

(4.26)

On the other hand, by the choice of \( M > 0 \), we know that any non-negative solution \( u(t) \) of (4.24) with \( u(\sigma_z) > 0 \) must vanish at some point in \([\sigma_z, \tau_z]\) (see [22, ch. 8, Theorem 1.1]). Therefore, from (4.25) we have that any non-negative solution \( u(t) \) of (3.5), with \( \alpha \geq 0 \), satisfies \( \max_{t \in I^+} u(t) < R_i \) for each \( i = 1, \ldots, m \). We conclude that for each \( i = 1, \ldots, m \) there is a constant \( R_i > 0 \) such that any non-negative \( T \)-periodic solution \( u(t) \) of (3.5), with \( \alpha \geq 0 \), satisfies \( \max_{t \in I^+} u(t) < R_i \).

Now we can take as \( R^* \) any constant such that \( R^* > r \) (with \( r \) as in Section 1.2) and

\[
R^* \geq R_i, \quad \text{for all } i = 1, \ldots, m.
\]

(4.27)

Thus \( \max_{t \in I^+} u(t) < R^* \) is proved. Notice that \( R^* \) does not depend on \( v(t) \) and on \( \mu \), since for the constants \( R_i \) we have used only information about \( a^+(t) \).

Finally, using (4.8) in Remark 4.4 and reasoning as in the proof of (4.9) (we just need to repeat verbatim the same argument, by replacing \( r \) with \( R^* \)), we can check that \( R^* \) is an a priori bound for the solutions on the whole domain. In this manner (4.5) is proved.

Remark 4.7. If \( c = 0 \) in equation (3.5), the existence of the upper bound \( R^* \) can be obtained in a different manner, still using a Sturm comparison argument (see [31, Lemma 6.2] for the details).

Remark 4.8. A careful reading of the proof of the a priori bound shows that the inequality \( u(t) < R^* \) for all \( t \in [0, T] \) has been proved independently on the assumption of \( T \)-periodicity of \( u(t) \). Hence, the same a priori bound on \([0, T]\) is valid for any non-negative solution \( u(t) \) of (2.1), with \( u(t) \) defined on an interval containing \([0, T]\). We claim now that the following stronger property holds.

If \( u(t) \) is a non-negative solution of (2.1) (not necessarily periodic), then

\[
w(t) < R^*, \quad \forall t \in \mathbb{R}.
\]

To check this assertion, suppose by contradiction that there exists \( t^* \in \mathbb{R} \) such that \( u(t^*) \geq R^* \). Let also \( \ell \in \mathbb{Z} \) be such that \( t^* \in \left[ T, (\ell + 1)T \right) \). In this case, thanks to the \( T \)-periodicity of the weight coefficient \( a_\mu(t) \), the function \( u(t) := w(t + \ell T) \) is still a (non-negative) solution of (2.1) with \( \max_{t \in [0, T]} u(t) \geq u(t^* - \ell T) = w(t^*) \geq R^* \), a contradiction with respect to the previous established a priori bound of \( u(t) \) on \([0, T]\).

Verification of \((H^R)\) for \( R \geq R^* \). We have found a constant \( R^* > r \) such that any non-negative solution \( u(t) \) of (3.5), with \( \alpha \geq 0 \), satisfies \( \|u\|_\infty < R^* \). Then, for \( R \geq R^* \), the first part of \((H^R)\) is valid independently of the choice of \( \alpha_0 \).

Let \( \alpha_0 > 0 \) be fixed such that

\[
\alpha_0 > \mu \|a^-\|_{L^1} \max_{0 \leq s \leq R} g(s) \frac{\|v\|_{L^1}}{\|v\|_{L^1}}.
\]
We verify that for $\alpha = \alpha_0$ there are no $T$-periodic solutions $u(t)$ of (3.5) with $0 \leq u(t) \leq R$ on $[0, T]$. Indeed, if there were, integrating on $[0, T]$ the differential equation and using the boundary conditions, we obtain

$$\alpha \|v\|_{L^1} = \alpha \int_0^T v(t) \, dt = -\int_0^T a_\mu(t) g(u(t)) \, dt \leq \mu \|a^-\|_{L^1} \max_{0 \leq s \leq R} g(s),$$

which leads to a contradiction with respect to the choice of $\alpha_0$. Thus $(H^R)$ is verified for all $R \geq R^*$. \hfill \qed

4.4 Checking the assumptions of Lemma 3.3 for $\mu$ large

Let $I \subseteq \{1, \ldots, m\}$ be a nonempty subset of indices and let $r > 0$ be as in Section 4.2 in particular $r$ satisfies (4.16). Set $d = r$, $\mathcal{J} := \{1, \ldots, m\} \setminus I$ and let $v \in L^1([0, T])$ be an arbitrary nontrivial function satisfying (4.10). For example, as $v(t)$ we can take the characteristic function of the set $\bigcup_{i \in I} \hat{I}^+_i$.

In this section we verify that $(A_{\mathcal{J}, r})$, $(B_{\mathcal{J}, r})$ and $(C_{\mathcal{J}, r})$ (of Lemma 3.3) hold for $\mu$ sufficiently large.

**Verification of $(A_{\mathcal{J}, r})$.** Let $\alpha \geq 0$. We claim that there exists $\mu^* > 0$ such that for $\mu > \mu^*$ any non-negative $T$-periodic solution $u$ of (3.5), or equivalently of (4.28)

$$\left(e^{ct}u'\right)' + e^{ct}(a_\mu(t)g(u) + \alpha v(t)) = 0,$$

is such that $\max_{t \in \hat{I}^+_i} u(t) \neq r$, for all $i \notin I$.

By contradiction, suppose that there is a solution $u(t)$ of (3.5) with

$$\max_{t \in \hat{I}^+_i} u(t) = r, \quad \text{for some index } j \in \mathcal{J}. \quad (4.29)$$

Let $\hat{t}_j \in \hat{I}^+_j = [\sigma_j, \tau_j]$ be such that $u(\hat{t}_j) = r$. If $\hat{t}_j = \tau_j$, then clearly $u(\tau_j) = r$ and $u'(\tau_j) \geq 0$. If $\hat{t}_j = \sigma_j$, then $u(\sigma_j) = r$ and $u'(\sigma_j) \leq 0$. Suppose now that $\sigma_j < \hat{t}_j < \tau_j$. By conditions (a) and (4.10), the solution $u(t)$ satisfies the following initial value problem on $\hat{I}^+_j$:

$$\begin{cases}
\left(e^{ct}u'\right)' + e^{ct}a^+(t)g(u) = 0 \\
u(\hat{t}_j) = r \\
u'(\hat{t}_j) = 0.
\end{cases}$$

Then, we have

$$u'(t) = -\int_{\hat{t}_j}^t e^{c(t-\xi)}a^+(\xi)g(u(\xi)) \, d\xi, \quad \forall t \in \hat{I}^+_j,$$

and hence, recalling (4.14) and (4.16), we obtain this a priori bound for $|u'(t)|$ on $\hat{I}^+_j$:

$$|u'(t)| \leq e^{c|\hat{I}^+_j|}a^+\|_{L^1(\hat{I}^+_j)}|\eta(r)|r \leq K_j \frac{r}{2K_j|\hat{I}^+_j|} = \frac{r}{2|\hat{I}^+_j|}, \quad \forall t \in \hat{I}^+_j.$$

Therefore, the following inequality holds

$$u(\tau_j) = u(\hat{t}_j) + \int_{\hat{t}_j}^{\tau_j} u'(t) \, dt \geq r - |\hat{I}^+_j| \frac{r}{2|\hat{I}^+_j|} = \frac{r}{2}.$$
Thus we have a lower bound for $u(\tau_j)$.

As a first case, suppose that $\sigma_j < \hat{t}_j \leq \tau_j$. Above, we have proved that

$$u(\tau_j) \geq \frac{r}{2} \quad \text{and} \quad u'(\tau_j) \geq -\frac{r}{2|I_j^+|} \quad (4.30)$$

(this is also true in a trivial manner if $\hat{t}_j = \tau_j$). By the initial convention in Section 2 about the selection of the points $\sigma_i$ and $\tau_i$ in order to separate the intervals of positivity and negativity, we know that $a(t) < 0$ on every right neighborhood of $\tau_j$. Accordingly, we can fix $\delta_j^+ > 0$, with $0 < \delta_j^+ < \sigma_{j+1} - \tau_j$, such that

$$\delta_j^+ e^{c|\delta_j^+|} < \frac{|I_j^+|}{2} \quad (4.31)$$

and $a(t) < 0$ on $[\tau_j, \tau_j + \delta_j^+] \subseteq I_j^-$. Since $t \mapsto e^{ct} u'(t)$ is non-decreasing on $I_j^-$, we have

$$u'(t) \geq e^{c(\tau_j - t)} u'(\tau_j) \geq -e^{c|\delta_j^+|} \frac{r}{2|I_j^+|}, \quad \forall \ t \in [\tau_j, \tau_j + \delta_j^+],$$

then

$$u(t) = u(\tau_j) + \int_{\tau_j}^{t} u'(\xi) \, d\xi \geq \frac{r}{2} - \delta_j^+ e^{c|\delta_j^+|} \frac{r}{2|I_j^+|} > \frac{r}{4}, \quad \forall \ t \in [\tau_j, \tau_j + \delta_j^+] .$$

We deduce that

$$\frac{r}{4} < u(t) \leq R^* \quad \text{on} \quad [\tau_j, \tau_j + \delta_j^+] ,$$

where $R^*$ is the upper bound defined in Section 4.3.

Let us fix

$$\gamma := \min_{\frac{r}{4} \leq s \leq R^*} g(s) > 0 . \quad (4.32)$$

We prove that for $\mu > 0$ sufficiently large max$_{t \in [\tau_j, \tau_j + \delta_j^+]}$ $u(t) > R^*$ (which is a contradiction to the upper bound for $u(t)$).

Note that for $t \in [\tau_j, \tau_j + \delta_j^+] \subseteq I_j^-$, equation (4.28) reads as

$$(e^{ct} u'(t)')' = \mu e^{ct} a^-(t) g(u(t)) .$$

Hence, for all $t \in [\tau_j, \tau_j + \delta_j^+]$ we have

$$u'(t) = e^{c(\tau_j - t)} u'(\tau_j) + \int_{\tau_j}^{t} \mu e^{c(\xi - t)} a^-(\xi) g(u(\xi)) \, d\xi$$

$$\geq -e^{c|\delta_j^+|} \frac{r}{2|I_j^+|} + \mu e^{-|c|\delta_j^+} \gamma \int_{\tau_j}^{t} a^-(\xi) \, d\xi ,$$

then

$$u(t) = u(\tau_j) + \int_{\tau_j}^{t} u'(\xi) \, d\xi$$

$$\geq \frac{r}{2} - \delta_j^+ e^{c|\delta_j^+|} \frac{r}{2|I_j^+|} + \mu e^{-|c|\delta_j^+} \gamma \int_{\tau_j}^{t} \left( \int_{\tau_j}^{s} a^-(\xi) \, d\xi \right) ds$$

$$> \frac{r}{4} + \mu e^{-|c|\delta_j^+} \gamma \int_{\tau_j}^{t} \left( \int_{\tau_j}^{s} a^-(\xi) \, d\xi \right) ds .$$

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Therefore, for $t = \tau_j + \delta_j^+$ we get
\[
R^* \geq u(\tau_j + \delta_j^+) \geq \mu e^{-|c|\delta_j^+} \gamma \int_{\tau_j}^{\tau_j + \delta_j^+} \left( \int_{\tau_j}^{a^-} (\xi) d\xi \right) ds.
\]
This gives a contradiction if $\mu$ is sufficiently large, say
\[
\mu > \mu_j^+ := \frac{R^* e^{|c|\delta_j^+}}{\gamma \int_{\tau_j}^{\tau_j + \delta_j^+} \left( \int_{\tau_j}^{a^-} (\xi) d\xi \right) ds}, \tag{4.33}
\]
recalling that $\int_{\tau_j}^{a^-} (\xi) d\xi > 0$ for each $t \in [\tau_j, \tau_{j+1}]$.

As a second case, if $\delta_j = \sigma_j$, we consider the interval $I_{\delta_j}^-$ (if $j = 1$, we deal with $I_{m-1}^-$ by $T$-periodicity). We define $\delta_j^-$ in a similar manner, by the fact that $a(t)$ is not identically zero on all left neighborhoods of $\sigma_j$. We obtain a contradiction for
\[
\mu > \mu_j^- := \frac{R^* e^{|c|\delta_j^-}}{\gamma \int_{\sigma_j - \delta_j^-}^{\sigma_j} \left( \int_{\sigma_j}^{a^-} (\xi) d\xi \right) ds}. \tag{4.34}
\]
At the end, we define
\[
\mu^*_j := \max_{\mu \in \mathbb{Z}} \mu_j^\pm
\]
and we obtain a contradiction if $\mu > \mu^*_j$. Hence condition $(A_{\mathcal{J}, r})$ is verified.

**Remark 4.9.** We emphasize the fact that the constant $\mu^*_j$ is chosen independently on the solution $u(t)$ for which we have made the estimates. In fact, the numbers $\mu_j^\pm$ depend only on absolute constants, like $R^*$, $\gamma$ (depending only on $g(s)$), the constants $\delta_j^\pm$ defined as in (4.31) and, finally, the integrals of the negative part of the weight function. Observe also that, in order to have non-vanishing denominators in the definition of the $\mu_j^\pm$, we had to be sure that $a(t) < 0$ on each right neighborhood of $\tau_j$ as well as on each left neighborhood of $\sigma_j$, consistently with the choice we made at the beginning. $\triangleright$

**Remark 4.10.** A careful reading of the above proof shows that the result does not involve the periodicity of the function $u(t)$, since we have only analyzed the behavior of the solution on an interval of positivity of the weight and on the adjacent intervals of negativity. Indeed, we claim that the following result holds.

There exists a constant $\mu^* > 0$ such that, for every $\mu > \mu^*$, any non-negative solution $w(t)$ of (2.1) (not necessarily periodic), with $w(t) < R^*$ for all $t \in \mathbb{R}$, is such that

$$
\max\{w(t): t \in I_i^+ + \ell T\} \neq r, \quad \forall i \in \{1, \ldots, m\}, \forall \ell \in \mathbb{Z}.
$$

To check this assertion, suppose by contradiction that there exist $i \in \{1, \ldots, m\}$ and $\ell \in \mathbb{Z}$ such that $\max\{w(t): t \in I_i^+ + \ell T\} = r$. Thanks to the $T$-periodicity of the weight coefficient $a_i(t)$, the function $u(t) := w(t + \ell T)$ is still a (non-negative) solution of (2.1) with $\max_{t \in I_i^+} u(t) = r$. So, we are in the same situation like at the beginning of the Verification of $(A_{\mathcal{J}, r})$ (cf. (4.29)). From now on, we proceed exactly the same as in that proof and obtain a contradiction with respect to the bound $u(t) < R^*$ (for all $t$) taking $\mu > \max\{\mu_j^+, \mu_j^-\}$. Hence the result is proved for $\mu$ sufficiently large, namely $\mu > \max_i \mu_i^+$.
Now, we fix $\mu > \mu^*_I$ and we prove that conditions $(B_{J,r})$ and $(C_{J,r})$ hold (independently of the coefficient $\mu$ previously fixed).

Verification of $(B_{J,r})$. Let $u(t)$ be any non-negative $T$-periodic solution of $(3.5)$ with $\max_{t \in I^+_j} u(t) \leq r$, for all $j \in J$. Notice that $R^*$ is an upper bound for all the solutions of $(3.5)$ and $R^*$ is independent on the functions $v \in L^1([0,T])$ satisfying $(4.4)$ (and hence $(4.10)$). So condition $(B_{J,r})$ is verified with $D_\beta = R^*$, for every $\beta \geq 0$.

Verification of $(C_{J,r})$. Recalling the choice of $v(t)$ in $(4.10)$, we take an index $i \in I = \{1, \ldots, m\} \setminus J$ such that $v \not\equiv 0$ on $I^+_i$ and we also fix $\varepsilon > 0$ such that $v(t) \not\equiv 0$ on $[\sigma_i + \varepsilon, \tau_i - \varepsilon]$. We claim that $(C_{J,r})$ is satisfied for $\alpha_0$ such that

$$\alpha_0 > \frac{R^*}{\int_{\sigma_i+\varepsilon}^{\tau_i+\varepsilon} v(t) \, dt} \left( \frac{2e^{|c|T}}{\varepsilon} + |c| \right).$$

To prove our assertion, first of all we observe that if $u(t)$ is any non-negative solution of $(3.5)$, then

$$|u'(t)| \leq u(t) \frac{e^{|c|T}}{\varepsilon}, \quad \forall \ t \in [\sigma_i + \varepsilon, \tau_i - \varepsilon].$$

Such inequality can be found in [11, § 3.1] and has been already proved and used in Section 4.3 (see the inequalities in $(4.23)$).

Let $u(t)$ be a non-negative $T$-periodic solution of $(3.5)$, which reads as

$$\alpha v(t) = -u'' - cu' - a^+(t)g(u)$$

on the interval $I^+_i$. Recall also that $\|u\|_\infty < R^*$ (cf. $(4.5)$). Integrating the equation on $[\sigma_i + \varepsilon, \tau_i - \varepsilon]$, for $\alpha = \alpha_0$, we obtain

$$\alpha_0 \int_{\sigma_i+\varepsilon}^{\tau_i+\varepsilon} v(t) \, dt = u'(\sigma_i + \varepsilon) - u'(\tau_i - \varepsilon) + c(u(\sigma_i + \varepsilon) - u(\tau_i - \varepsilon)) - \int_{\sigma_i+\varepsilon}^{\tau_i+\varepsilon} a^+(t)g(u(t)) \, dt$$

$$\leq 2R^* e^{|c|T} + |c|R^* < \alpha_0 \int_{\sigma_i+\varepsilon}^{\tau_i+\varepsilon} v(t) \, dt,$$

a contradiction. Hence $(C_{J,r})$ is verified.

Remark 4.11. Note that for the verification of $(B_{J,r})$ and $(C_{J,r})$ the small constant $r$ has no played any relevant role. In fact, we used only the information about the existence of the a priori bound $R^*$ obtained in Section 4.3.

In conclusion, all the assumptions of Lemma 3.3 have been verified for a fixed $r$ and for $\mu > \mu^*_I$. \hfill $\Box$
4.5 A posteriori bounds

Let $I \subseteq \{1, \ldots, m\}$ be a nonempty subset of indices and let $r$ and $R$ be fixed as explained in Section 4.1. Theorem 4.11 ensures the existence of at least a $T$-periodic positive solution $u(t)$ of (2.1) with $u \in \Lambda_{R,R}^i$. More in details, the solution $u(t)$ is such that $r < u(\hat{t}_i) < R$ for some $\hat{t}_i \in I_i^+$, if $i \in I$, and $0 < u(t) < r$ for all $t \in I_i^+$, if $i \notin I$.

As premised in Remark 4.1, in this section we prove that, for $\mu$ sufficiently large, it holds that $0 < u(t) < r$ also on the non-positivity intervals $I_i^-$. First of all, by (4.8), we observe that the solution $u(t)$ in the interval of non-positivity attains its maximum at an end-point. Therefore it is sufficient to show that

$$u(\sigma_i) < r \quad \text{and} \quad u(\tau_i) < r, \quad \text{for all} \ i = 1, \ldots, m.$$

If $i \notin I$, there is nothing to prove, because $u(t) < r$ on $I_i^+ = [\sigma_i, \tau_i]$. Let us deal with the case $i \in I$ and, by contradiction, suppose that

$$u(\tau_i) \geq r.$$

Proceeding as in Section 4.4, one can prove that

$$u'(\tau_i) \geq -K_i \max_{0 \leq s \leq R^*} g(s)$$

and hence (using estimates analogous to those following after (4.30)) that there exists $\delta^*_i > 0$ such that, for $t = \tau_i + \delta^*_i \in I_i^-$ and $\mu$ sufficiently large, we obtain

$$u(\tau_i + \delta^*_i) \geq R^*,$$

a contradiction.

A similar argument generates a contradiction also assuming $u(\sigma_i) \geq r$, for $i \in I$.

Finally, repeating again the argument in Section 4.4, we can also check that if $u(t) = u_\mu(t)$ is a positive $T$-periodic solution of (2.1) (belonging to a set of the form $\Lambda_{R,R}^i$), then, for $\mu \to +\infty$, $u_\mu$ tends uniformly to zero on the intervals $I_i^-$.

Remark 4.12. Notice that the same arguments work for any arbitrary non-negative solution which is upper bounded by $R^*$ (at any effect this observation is analogous to Remark 4.10, since it only involves the behavior of the solution in the intervals where the weight is negative, without requiring the periodicity of the solution). Indeed, the following result holds.

There exists a constant $\mu^{**} > 0$ such that, for every $\mu > \mu^{**}$, any non-negative solution $w(t)$ of (2.1) (not necessarily periodic), with $w(t) < R^*$ for all $t \in \mathbb{R}$, is such that

$$\max\{w(t) : t \in I_i^- + \ell T\} < r, \quad \forall i \in \{1, \ldots, m\}, \forall \ell \in \mathbb{Z}.$$

To check this assertion, suppose by contradiction that there exist $i \in \{1, \ldots, m\}$ and $\ell \in \mathbb{Z}$ such that $\max\{w(t) : t \in I_i^- + \ell T\} \geq r$. Thanks to the $T$-periodicity of the weight coefficient $\alpha_{u}(t)$, the function $u(t) := w(t + \ell T)$ is still a (non-negative) solution of (2.1) with $\max_{t \in I_i^-} u(t) \geq r$. This means that $u(\sigma_i) \geq r$ or $u(\tau_i) \geq r$. At this point we achieve a contradiction exactly as above. <
5 Related results

In this section we deal with corollaries, variants and applications of Theorem 4.1. We also analyze the case of a nonlinearity \( g(s) \) which is smooth in order to give a nonexistence result, too.

The following corollaries are obtained as direct applications of Theorem 4.1.

**Corollary 5.1.** Let \( g: \mathbb{R}^+ \to \mathbb{R}^+ \) be a continuous function satisfying \( (g) \),

\[
g_0 = 0 \quad \text{and} \quad g_\infty > 0.
\]

Let \( a: \mathbb{R} \to \mathbb{R} \) be a \( T \)-periodic locally integrable function satisfying \( (a) \). Then there exists \( \nu^* > 0 \) such that for all \( \nu > \nu^* \) there exists \( \mu^* = \mu^*(\nu) \) such that for \( \mu > \mu^* \) there exist at least \( 2^m - 1 \) positive \( T \)-periodic solutions of

\[
u'' + cu' + \left( \nu a^+(t) - \mu a^-(t) \right) g(u) = 0.
\]

(5.1)

The constant \( \nu^* \) will be chosen so that \( \nu^* g_\infty > \max_i \lambda_i \). The lower bound for \( g_\infty \) in the main theorem is automatically satisfied when \( g_\infty = +\infty \). Accordingly, we have.

**Corollary 5.2.** Let \( g: \mathbb{R}^+ \to \mathbb{R}^+ \) be a continuous function satisfying \( (g) \),

\[
g_0 = 0 \quad \text{and} \quad g_\infty = +\infty.
\]

Let \( a: \mathbb{R} \to \mathbb{R} \) be a \( T \)-periodic locally integrable function satisfying \( (a) \). Then there exists \( \mu^* > 0 \) such that for all \( \mu > \mu^* \) equation (2.1) has at least \( 2^m - 1 \) positive \( T \)-periodic solutions.

A typical case in which the above corollary applies is for the power nonlinearity \( g(s) = s^p \) (for \( p > 1 \)), so that the next result holds.

**Corollary 5.3.** Let \( a: \mathbb{R} \to \mathbb{R} \) be a \( T \)-periodic locally integrable function satisfying \( (a) \). Then there exists \( \mu^* > 0 \) such that for all \( \mu > \mu^* \) there exist at least \( 2^m - 1 \) positive \( T \)-periodic solutions of

\[
u'' + cu' + \left( a^+(t) - \mu a^-(t) \right) u^p = 0, \quad p > 1.
\]

Using Remark 4.2 we can also obtain the following result which, in some sense, is dual with respect to Corollary 5.1.

**Corollary 5.4.** Let \( g: \mathbb{R}^+ \to \mathbb{R}^+ \) be a continuous function satisfying \( (g) \),

\[
g_0 > 0 \quad \text{and} \quad g_\infty = +\infty.
\]

Let \( a: \mathbb{R} \to \mathbb{R} \) be a \( T \)-periodic locally integrable function satisfying \( (a) \). Then there exists \( \nu_*> 0 \) such that for all \( 0 < \nu < \nu_* \) there exists \( \mu^* = \mu^*(\nu) \) such that for \( \mu > \mu^* \) there exist at least \( 2^m - 1 \) positive \( T \)-periodic solutions of equation (5.1).

Combining Theorem 4.1 with [11, Lemma 4.1] (or [31, Proposition 3.1]), the following result can be obtained.
Corollary 5.5. Let $g: \mathbb{R}^+ \to \mathbb{R}^+$ be a continuously differentiable function satisfying $(g_*)$, $g_0 = 0$ and $g_\infty > 0$.

Let $a: \mathbb{R} \to \mathbb{R}$ be a $T$-periodic locally integrable function satisfying $(a_*)$. Then for all $\mu > 0$ such that $\int_0^T a_\mu(t) \, dt < 0$ there exist two constants $0 < \omega_* \leq \omega^*$ (depending on $\mu$) such that equation

$$u'' + cu' + \nu(a^+(t) - \mu a^-(t))g(u) = 0$$

(5.2)

has no positive $T$-periodic solutions for $0 < \nu < \omega_*$ and at least one positive $T$-periodic solution for $\nu > \omega_*$. Moreover there exists $\nu^* > 0$ such that for all $\nu > \nu^*$ there exists $\mu^* = \mu^*(\nu)$ such that for $\mu > \mu^*$ equation (5.2) has at least $2^m - 1$ positive $T$-periodic solutions.

Equation (5.2) is substantially equivalent to (5.1). We have preferred to write it in a slightly different form for sake of convenience in stating Corollary 5.5.

6 Subharmonic solutions and complex dynamics

Our next goal is to apply the preceding results concerning the existence and multiplicity of periodic solutions to the search of subharmonic solutions. Then, we shall use the information obtained on the subharmonics to produce bounded positive solutions which are not necessarily periodic and can reproduce an arbitrary coin-tossing sequence.

6.1 Subharmonic solutions

In the previous sections we have studied the existence and multiplicity of $T$-periodic solutions, assuming that the weight coefficient is a $T$-period function. Since any $T$-periodic coefficient can be though as a $kT$-periodic function, with the same technique we can look for the existence of $kT$-periodic solutions (with $k$ an integer). In this context, a typical problem which occurs is that of proving the minimality of the period, that is, to ensure the presence of subharmonic solutions of order $k$, according to the standard definition that we recall now for the reader’s convenience. A subharmonic solution of order $k$, with $k \geq 2$ an integer, is a $kT$-periodic solution which is not $lT$-periodic, for any integer $l = 1, \ldots, k - 1$. Throughout this section, for the sake of simplicity in the exposition, when not explicitly stated we assume that $k$ is an integer such that $k \geq 2$.

Generally speaking, if $x(t)$ is a $kT$-periodic solution of a differential system $x' = f(t,x)$ in $\mathbb{R}^N$, with $f(t + T,x) = f(t,x)$ for all $t \in \mathbb{R}$ and $x \in \mathbb{R}^N$, the information that $x(t)$ is not $lT$-periodic, for any integer $l = 1, \ldots, k - 1$, is not enough to conclude that $kT$ is actually the minimal positive period of the solution. However, in many significant situations, it is possible to derive such a conclusion, under suitable conditions on the vector field $f(t,x)$. For instance, in case of (1.1) and for $g(s)$ satisfying $(g_*)$, it is easy to check that any positive subharmonic solution of order $k$ is a solution of minimal period $kT$ provided that $T$ is the minimal period of the weight function. The problem of minimality of the period in the study of subharmonic solutions is a topic of considerable
importance in this area of research and different approaches have been proposed depending also on the nature of the techniques adopted to obtain the solutions. See for instance [12, 18, 25, 51, 60] for some pertinent remarks. It may be also interesting to observe that equations of the form (1.1), with \(w(t)\) a non-constant \(T\)-periodic coefficient, do not possess exceptional solutions, i.e. solutions having a minimal period which has an irrational ratio with \(T\) (cf. [61, ch. I, § 4]). In view of all these premises, throughout the section we suppose that the function \(a(t)\) is a periodic function having \(T > 0\) as a minimal period.

As a final remark, we observe that if \(u(t)\) is a \(kT\)-periodic solution of (1.1) then, for any integer \(\ell\) with \(1 \leq \ell \leq k - 1\), also the function \(v_\ell(t) := u(t + \ell T)\) is a \(kT\)-periodic solution and it has \(kT\) as a minimal period if and only if \(kT\) is the minimal period for \(u(t)\). Accordingly, whenever it happens that we find a subharmonic solution of order \(k\), we also find other \(k - 1\) subharmonic solutions (of the same order). These solutions, even if formally distinct, will be considered as belonging to the same periodicity class and for the purposes of counting the number of solutions will count only once.

In order to present in a simplified manner our main multiplicity results for subharmonic solutions, we first take a class of weights of special form, namely we suppose that

\[a: \mathbb{R} \to \mathbb{R} \text{ is a continuous periodic sign-changing function with simple zeros and with minimal period } T, \text{ such that there exist two consecutive zeros } \alpha < \beta \text{ so that } a(t) > 0 \text{ for all } t \in [\alpha, \beta] \text{ and } a(t) < 0 \text{ for all } t \in (\beta, \alpha + T].\]

That is \(a(t)\) has only one positive hump and one negative one in a period interval. In such a simplified situation, the following result holds.

**Theorem 6.1.** Let \(g: \mathbb{R}^+ \to \mathbb{R}^+\) be a continuous function satisfying \((g_\ast)\),

\[g_0 = 0 \quad \text{and} \quad g_\infty = +\infty.\]

Then there exists \(\mu^* > 0\) such that, for all \(\mu > \mu^*\) and for every integer \(k \geq 2\), equation (2.1) has a subharmonic solution of order \(k\).

**Proof.** Without loss of generality (if necessary, we can make a shift by \(\alpha\) in the time variable), we suppose that

\[a(t) > 0, \quad \text{for all } 0 < t < \tau := \beta - \alpha, \quad \text{and} \quad a(t) < 0, \quad \text{for all } \tau < t < T.\]

Let us fix an integer \(k \geq 2\) and consider the \(T\)-periodic function \(a(t)\) as a \(kT\)-periodic weight on the interval \([0, kT]\). In such an interval we have condition \((a_\ast)\) satisfied with

\[I_i^+ = [(i - 1)T, \tau + (i - 1)T] \quad \text{and} \quad I_i^- = [\tau + (i - 1)T, iT],\]

for \(i = 1, \ldots, k\). With respect to the notation introduced in Section 2 we also have \(m = k\), \(\sigma_1 = 0\), \(\sigma_{k+1} = kT\) and

\[0 < \tau_1 < \tau_2 = T < \ldots < \tau_k = (k - 1)T < \tau_k = \tau + (k - 1)T < kT.\]

In this setting we can apply Corollary 5.2 which ensures the existence of \(2^k - 1\) positive solutions which are also \(kT\)-periodic, provided that \(\mu\) is sufficiently large.
Even if we have found $kT$-periodic solutions, our proof is not yet complete. In fact we still have to verify that $\mu^*$ (found in the proof of Theorem 4.1) is independent on $k$ and, moreover, that among the $2^k - 1$ periodic solutions there is at least one subharmonic of order $k$.

For the first question, we need to check how the bounds obtained in the proof of Theorem 4.1 depend on the weight function. First of all we underline that, by the $T$-periodicity of $a(t)$, the constants $K_i$ defined in (4.14) are all equal for $i = 1, \ldots, k$; then $K_0$ does not depend on $k$ (cf. (4.15)). Consequently condition (4.16) reads as

$$
\eta(r) 2 \| a^+ \|_{L^1([0, r])} e^{c|r|} \left( \tau + e |\tau - T| (T - \tau) \right) < 1
$$

and so the small constant $r > 0$ is absolute and depends only on $c$, $\| a^+ \|_{L^1([0, \tau])}$, $T$ and $\tau$, but it does not depend on $k$.

Once that we have fixed $r > 0$, using again the $T$-periodicity of the weight, we notice also that the lower bounds $\mu^\#_i$ and $\mu_\tau$ do not depend on $k$ (cf. (4.2) and (4.17)).

The constant $R^*$ is chosen in (4.27) and depends on the a priori bounds $R_i$, which in turn depend on the properties of $a(t)$ restricted to the interval $I^+_i$. In our case, by the $T$-periodicity of the coefficient $a(t)$, we can choose $R_i$ as constant with respect to $i$. Therefore, $R^*$ is independent on $k$ and then also the constant $\gamma$ defined in (4.32) does not depend on $k$. By the periodicity of $a(t)$, the constants $\delta^+_i$ introduced in Section 4.4 (see (4.31)) can be also taken all equal to a common value $\delta^+ = \delta$ such that $0 < \delta < T - \tau$ and $\delta e^{|\delta|} < \tau / 2$. The same choice can be made for $\delta^-_j$ in order to have $\delta^-_j = \delta$ for all $j$. From these choices of the constants $R^*$, $\gamma$ and $\delta$, for all $j = 1, \ldots, k$ we take $\mu_j^\pm$, according to (4.33) and (4.34), as

$$
\mu_j^+ = \mu^+ := \frac{R^* e^{c|\delta|}}{\gamma \int_{T-\delta}^{T} \left( \int_s^T a^-(\xi) \, d\xi \right) \, ds}
$$

and

$$
\mu_j^- = \mu^- := \frac{R^* e^{c|\delta|}}{\gamma \int_{T-\delta}^{T} \left( \int_s^T a^-(\xi) \, d\xi \right) \, ds},
$$

respectively. Therefore, setting

$$
\mu^* := \mu_\tau \vee \max \{ \mu^+, \mu^- \},
$$

we have found an absolute constant which is independent on $k$ and also does not depend on the set of indices $I$. This solves the first question.

To complete the proof, we show how to produce at least one subharmonic solution. It is sufficient to take $I := \{ 1 \}$. As explained in Remark 4.1 and also at the end of Section 4.1 there exists a positive $kT$-periodic solution $u(t)$ for (2.1) such that $u \in \Lambda_{r, R}^{(i)}$. This implies that there exists $I_1^+ \subseteq [0, \tau]$ such that $r < u(t_1) < R$ and, if $i \neq 1$, $0 < u(t) < r$ for all $t \in I_i^+$. Then $u(t_1) \neq u(t)$ for all $t \in I_1$ with $i \neq 1$, and hence $u$ is not $IT$-periodic for all $l = 1, \ldots, k - 1$. We conclude that $u$ is a subharmonic solution of order $k$.

**Remark 6.1.** The fact that the weight coefficient has simple zeros has been assumed only for convenience in the exposition. The same result holds true if we
suppose that there are $\alpha < \beta$ such that $a(t) > 0$ on $[\alpha, \beta]$, $a(t) < 0$ on $[\beta, \alpha + T]$ and $a(t)$ is not identically zero on all left neighborhoods of $\alpha$ and on all right neighborhoods of $\beta$. The possibility of more changes of sign of $a(t)$ in a period can be considered as well.

Remark 6.2. We stress the fact that $\mu^*$ is chosen independent on $k$ and also independent on the set of indices $I$. This is a crucial observation if one wants to prove the existence of bounded solutions defined on the whole real line and with any prescribed behavior as a limit of subharmonic solutions (see Section 6.3 and [5]).

6.2 Counting the subharmonic solutions

Theorem 6.1 guarantees the existence of at least a subharmonic solution of order $k$ for (2.1), but, in general, there are many solutions of this kind. Even if in the statement we have not described the number of subharmonics and their behavior, this can be achieved (with the same proof) just exploiting more deeply the content of Theorem 4.1. In this section, given an integer $k \geq 2$, we look for an estimate on the number of subharmonic solutions of order $k$. To this purpose, we adapt to our setting some considerations which are typical in the area of dynamical systems, combinatorics and graph theory.

First of all, we need to introduce a notation, which is borrowed from [5]. We start with an alphabet of two symbols, conventionally indicated as $\{0, 1\}$, and denote by $\{0, 1\}^k$ the set of the $k$-tuples of $\{0, 1\}$, that is the set of finite words of length $k$. We also denote by $0^k$ the 0-string in $\{0, 1\}^k$.

For simplicity, we still consider the special weight coefficient as in the setting of Theorem 6.1. Recalling the definitions of $I^+_i$, $I^-_i$ for $i = 1, \ldots, k$, given by

$$I^+_i = [(i - 1)T, \tau + (i - 1)T] \quad \text{and} \quad I^-_i = [\tau + (i - 1)T, iT],$$

and reworking as in the proof of Theorem 6.1, we have the following result.

Theorem 6.2. Let $g: \mathbb{R}^+ \to \mathbb{R}^+$ be a continuous function satisfying $(g_*)$,

$$g_0 = 0 \quad \text{and} \quad g_\infty = +\infty.$$  

Then there exist $0 < r < R$ and $\mu^{**} > 0$ such that, for all $\mu > \mu^{**}$ and for every integer $k \geq 2$, given any $k$-tuple $L^k = (s_i)_{i=1}^k$ with $L^k \neq 0^k$, there exists at least one $kT$-periodic positive solution of equation (2.1) such that $\|u\|_\infty < R$ and

- $0 < u(t) < r$ on $I^+_i$, if $s_i = 0$;
- $r < u(t) < R$ for some $\hat{t}_i \in I^+_i$, if $s_i = 1$;
- $0 < u(t) < r$ on $I^-_i$, for all $i = 1, \ldots, k$.

Proof. We proceed exactly as in the proof of Theorem 6.1 till to the final step where we chose the set of indices $I$. At this moment $r$, $R$ and $\mu^*$ are determined and we are free to take any $\mu > \mu^*$. Let us consider an arbitrary integer $k \geq 2$. Observe that we took $I = \{1\}$ in order to be sure to have a subharmonic, however, Theorem 4.1 provides the existence of a positive $kT$-periodic solution in $A^2_{r,R}$ for any nonempty subset $I$ of $\{1, \ldots, k\}$.
Given an arbitrary $k$-tuple $L^{[k]} = (s_i)_{i=1}^k$ with $L^{[k]} \neq 0^{[k]}$, using a typical bijection between $\{0, 1\}^k$ and the power set $\mathcal{P}([1, \ldots, k])$, we associate to $L^{[k]}$ the set $\mathcal{I}_{L^{[k]}} := \{ i \in \{1, \ldots, k\} : s_i = 1 \}$. Now, applying Theorem 4.1, we have guaranteed the existence of at least one $kT$-periodic solution $u(t)$ which is positive and belongs to the set $\Lambda^{T}_{\mathcal{I}_{L^{[k]}}}$. Recalling the definition of $\Lambda^{T}_{\mathcal{I}_{r,R}}$ in (2.3), we find that $u(t)$ satisfies the first two conditions in the statement of the theorem. The latter condition, concerning the smallness of $u(t)$ on the intervals $I^{-i}$, follows from the result in Section 4.5 provided that $\mu$ is sufficiently large, say $\mu > \mu^{**}$. Arguing as in the proof of Theorem 6.1, it is easy to note that $\mu^{**}$ does not depend on $k$.

The above theorem provides the existence of $2^k - 1$ distinct $kT$-periodic solutions of (2.1) which are positive and uniformly bounded in $\mathbb{R}$. Our goal now is to detect among these solutions the “true” subharmonics of order $k$ which do not belong to the same periodicity class. Figure 2 gives an explanation of what we are looking for.

![Figure 2](image)

Figure 2: At the top we have shown the graph of the function $a_\mu(t)$, where $a(t) = \sin(2\pi t)$ and $\mu = 7$. Using a numerical simulation we have studied the subharmonic solutions of order $k = 2$ of equation (2.1) with $g(s) = \max\{0, 100 \arctan |s|\}$. Clearly, $T = 1$. In the lower part, the figure shows the graphs of three 2-periodic positive solutions, whose existence is consistent with Theorem 6.2. The first two solutions are subharmonic solutions of order 2 and the third one is a 1-periodic solution. As subharmonic solutions of order 2, we consider only the first one, since the second one is a translation by 1 of the first solution.

In order to count the $k$-tuples corresponding to subharmonic solutions of order $k$ which are not equal up to translation (geometrically distinct), we notice that the number we are looking for coincides with the number of binary Lyndon words of length $k$, that is the number of binary strings inequivalent modulo rotation (cyclic permutation) of the digits and not having a period smaller than $k$. Usually, in each equivalent class one selects the minimal element in the lexicographic ordering. For instance, for the alphabet $\mathcal{A} = \{a, b\}$ and $k = 4$, the corresponding binary Lyndon words of length 4 are $aaab$, $aabb$, $abb$. Note that the string $abab$ is not acceptable as it represents a sequence of period 2 and
the string \textit{bbaa} is already counted as \textit{aabb}. To give a formal definition, consider an alphabet \( \mathcal{A} \) which, in our context, is a nonempty totally ordered set of \( n \geq 2 \) symbols. A \textit{n-ary Lyndon word of length k} is a string of \( k \) digits of \( \mathcal{A} \) which is strictly smaller in the lexicographic ordering than all of its nontrivial rotations.

The number of \( n \)-ary Lyndon words of length \( k \) is given by Witt’s formula

\[
S_n(k) = \frac{1}{k} \sum_{l \mid k} \mu(l) n^{rac{k}{l}},
\]

(6.1)

where \( \mu(\cdot) \) is the Möbius function, defined on \( \mathbb{N} \setminus \{0\} \) by \( \mu(1) = 1, \mu(l) = (-1)^s \) if \( l \) is the product of \( s \) distinct primes and \( \mu(l) = 0 \) otherwise (cf. [45, § 5.1]). Formula (6.1) can be obtained by the Möbius inversion formula, which is strictly related with the classical inclusion-exclusion principle.

For instance, the values of \( S_2(k) \) (number of binary Lyndon words of length \( k \)) for \( k = 2, \ldots, 10 \) are 1, 2, 3, 6, 9, 18, 30, 56, 99.

The following proposition provides an explicit formula of \( S_n(k) \) (for arbitrary integers \( n, k \geq 2 \)), depending on the prime factorization of \( k \).

\textbf{Proposition 6.1.} Let \( n, k \geq 2 \) be two integers. If the prime factorization of \( k \) is

\[
k = p_1^{\alpha_1} \cdot p_2^{\alpha_2} \cdot p_3^{\alpha_3} \cdot \ldots \cdot p_s^{\alpha_s} = \prod_{i=1}^{s} p_i^{\alpha_i},
\]

where \( s \) is the number of distinct prime factors of \( k \), then the following formula holds

\[
S_n(k) = \frac{1}{k} n^k + \frac{1}{k} \sum_{i=1}^{s} (-1)^i \sum_{j_d \in \{1, \ldots, s\}} \sum_{j_1 < j_2 < \ldots < j_i} n^{\frac{k}{p_{j_1} \cdots p_{j_i}}}. 
\]

\textbf{Proof.} First of all, we observe that the divisors \( l \) of the integer \( k \) such that \( \mu(l) \neq 0 \) are the square-free factors of \( k \), hence \( l = 1 \) (with \( \mu(1) = 1 \)) and the integers of the form \( l = p_{j_1} \cdot \ldots \cdot p_{j_i} \) for \( j_d \in \{1, \ldots, s\} \) (with \( \mu(l) = (-1)^i \)). The above formula immediately follows from (6.1).

\textbf{Remark 6.3.} Although in this context formula (6.1) and the more explicit one in Proposition 6.1 are related to the number of Lyndon words of length \( k \) in an alphabet of size \( n \), these formulas come out in different areas of mathematics. Now we provide an overview of the several meanings of \( S_n(k) \).

Still in combinatorics, it is not difficult to see that \( S_n(k) \) is also the number of \textit{aperiodic necklaces} that can be made by arranging \( k \) beads whose color is chosen from a list of \( n \) colors. The notions of \textit{Lyndon words} and \textit{necklaces} are also strictly related to \textit{de Bruijn sequences}. We recall that a \textit{n-ary de Bruijn sequence of order k} is a circular string of characters chosen in an alphabet of size \( n \), for which every possible subsequence of length \( k \) appears as a substring of consecutive characters exactly once. For more details about these concepts and other aspects of the formula in the context of combinatorics on words, we refer to [45, 46] and the very interesting historical survey [8, § 4].

The number \( S_n(k) \) has several meanings even outside combinatorics. For instance, the integer \( S_2(k) \) (of binary Lyndon words of length \( k \)) corresponds to the number of periodic points with minimal period \( k \) in the iteration of the tent map \( f(x) := 2 \min\{x, 1-x\} \) on the unit interval (cf. [27], also for more

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general formulas) and to the number of distinct cycles of minimal period $k$
 in a shift dynamical system associated with a totally disconnected hyperbolic
iterated function system (cf. [4, Lemma 1, p. 171]). Concerning the more general
formula for $S_n(k)$, we just mention two other meanings. The classical Witt’s
formula (proved in 1937), which is still widely studied in algebra, gives the
dimensions of the homogeneous components of degree $k$ of the free Lie algebra
over a finite set with $n$ elements (cf. [45, Corollary 5.3.5]). Moreover, in Galois
theory, $S_n(k)$ is also the number of monic irreducible polynomials of degree $k$
over the finite field $F_n$, when $n$ is a prime power (in this context (6.1) is also
known as Gauss formula; we refer to [28, ch. 14, p. 588] for a possible proof).

It is not possible to mention here all the other several implications of for-
mula (6.1), for example in symbolic dynamics, algebra, number theory and chaos
theory. For this latter topic, we only recall the recent paper [42] where such
numbers appear in connection with the study of period-doubling cascades.

Further information and references can be found in [36, 43, 63].

Using the above discussion, we achieve the following result.

**Theorem 6.3.** Let $g : \mathbb{R}^+ \rightarrow \mathbb{R}^+$ be a continuous function satisfying $(g_*)$,

$$g_0 = 0 \quad \text{and} \quad g_\infty = +\infty.$$  

Let $a : \mathbb{R} \rightarrow \mathbb{R}$ be a $T$-periodic continuous function with minimal period $T$ such
that there exist two consecutive zeros $\alpha < \beta$ so that $a(t) > 0$ for all $t \in [\alpha, \beta]$ and
$a(t) < 0$ for all $t \in [\beta, \alpha + T]$. Then there exists $\mu^* > 0$ such that, for all $\mu > \mu^*$
and for every $k \geq 2$, equation (2.1) has at least $S_2(k)$ positive subharmonic
solutions of order $k$.

**Proof.** We have to detect the subharmonic solutions of order $k$ among the $2^k - 1$
distinct $kT$-periodic positive solutions of (2.1) provided by Theorem 6.2. As
remarked above, the number we are looking for is $S_2(k)$. Therefore the thesis
immediately follows.

For the sake of simplicity, above we have considered only the particular case
of a continuous periodic sign-changing function $a(t)$ with minimal period $T$
and such that it has only one positive hump and one negative one in a period interval.
Moreover, we have taken a superlinear function $g(s)$. We conclude this section
by stating the analogous result for more general functions $a(t)$ and $g(s)$.

**Theorem 6.4.** Let $g : \mathbb{R}^+ \rightarrow \mathbb{R}^+$ be a continuous function satisfying $(g_*)$,

$$g_0 = 0 \quad \text{and} \quad g_\infty > \max_{i=1,\ldots,m} \lambda_i.$$  

Let $a : \mathbb{R} \rightarrow \mathbb{R}$ be a $T$-periodic locally integrable function satisfying $(a_*)$
with minimal period $T$. Then there exists $\mu^* > 0$ such that, for all $\mu > \mu^*$
and for every $k \geq 2$, equation (2.1) has at least $S_2^m(k)$ positive subharmonic
solutions of order $k$.

**Proof.** We only sketch the proof which is mimicked from those of Theorem 6.1
and of Theorem 6.2, using Theorem 4.1. To start, we need to be careful with
the notation. For this reason, we call $J_1^+, \ldots, J_m^+$ the $m$ intervals of positivity
for $a(t)$ in the interval $[0, T]$ and $J_1^-, \ldots, J_m^-$ the $m$ intervals of negativity for

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a(t), according to assumption (a*). Consider an arbitrary integer \( k \geq 2 \). The function \( a(t) \) restricted to the interval \([0, kT]\) satisfies again an assumption of the form (a*), with respect to \( mk \) intervals of positivity/negativity that we denote now with \( I_1^\pm, \ldots, I_{mk}^\pm \), defined as

\[
I_{j+\ell m}^\pm = J_j^\pm + \ell T, \quad j = 1, \ldots, m, \quad \ell = 0, \ldots, k-1.
\]

In other terms, in the interval \([0, kT]\) there are \( mk \) closed subintervals where \( a(t) \succ 0 \), separated by closed subintervals where \( a(t) \prec 0 \). Then we can apply Theorem 4.1, looking for \( kT \)-periodic solutions. In fact, by our main result, we have at least \( 2^{mk} - 1 \) positive periodic solutions of period \( kT \) (which up to now is not necessarily the minimal period for the solutions). More precisely, as in Theorem 6.2, there exist \( 0 < r < R \) and \( \mu^{**} > 0 \) (depending on \( m \) but not on \( k \)) such that, for all \( \mu > \mu^{**} \), given any nontrivial \( k \)-tuple \( L = (s_{\ell})_{\ell=1}^{k-1} \) in the alphabet \( \{0,1\}^m \) of size \( 2^m \) (hence, for \( \ell = 0, \ldots, k-1, s_\ell = (s_{j\ell})_{j=1}^{m} \)), there exists at least one \( kT \)-periodic positive solution

\[
u(t) = u_{L[n]}(t)
\]

of equation (2.1) such that \( \|u\|_\infty < R \) and

- \( 0 < u(t) < r \) on \( I_{j+\ell m}^+ \), if \( s_{j\ell} = 0 \);
- \( r < u(\hat{t}) < R \) for some \( \hat{t} \in I_{j+\ell m}^+ \), if \( s_{j\ell} = 1 \);
- \( 0 < u(t) < r \) on \( I_{i}^- \), for all \( i = 1, \ldots, mk \).

It remains to see whether, on the basis of the information we have on \( u(t) \), we are able first to determine the minimality of the period and next to distinguish among solutions do not belonging to the same periodicity class. In view of the above listed properties of the solution \( u(t) \), our first problem is equivalent to choosing a string \( L^{[k]} \) having \( k \) as a minimal period (when repeated cyclically). For the second question, given any string of this kind, we count as the same all those strings (of length \( k \)) which are equivalent by cyclic permutations. To choose exactly one string in each of these equivalent classes, we can take the minimal one in the lexicographic order. As a consequence, we can conclude that there are so many nonequivalent \( kT \)-periodic solutions which are not \( pT \)-periodic for every \( p = 1, \ldots, k-1 \), how many \( 2^m \)-ary Lyndon words of length \( k \).

Since we know that the equation does not possess exceptional solutions, we find that for these subharmonic solutions \( kT \) is precisely the minimal period.

We have listed before some values of \( S_2(k) \) which give the number of subharmonic solutions in the setting of Theorem 6.3. Concerning the general case addressed in Theorem 6.4, we observe that the number \( S_{2^m}(k) \), with \( m \geq 2 \), grows very fast with \( k \). For instance, the values of \( S_{2^2}(k) \) (number of quaternary Lyndon words of length \( k \)) for \( k = 2, \ldots, 10 \) are 6, 20, 60, 204, 670, 2340, 8160, 29120, 104754.

### 6.3 Positive solutions with complex behavior

In this section we just outline a possible procedure in order to obtain the existence of solutions which follow any preassigned coding described by two
symbols, say 0 and 1, that in our context will be interpreted as “small” and, respectively, “large” in the intervals where the weight is positive. In other terms we are looking for the presence of a Bernoulli shift as a factor within the set of positive and bounded solutions. Results in this direction are classical in the theory of dynamical systems (cf. [24] [53] [64]) and have been achieved in the variational setting as well (see, for instance, [13] [17] [62]). Even if the obtention of chaotic dynamics using topological degree or index theories is an established technique (see [21] [65] and the references therein), the achievement of similar results with our approach seems new in the literature.

Our proof is based on the above results about subharmonic solutions and on the following diagonal lemma, which is typical in this context. Lemma 6.1 is adapted from [44, Lemma 8.1] and [49, Lemma 4].

**Lemma 6.1.** Let \( f : \mathbb{R} \times \mathbb{R}^d \to \mathbb{R}^d \) be an \( L^1 \)-Carathéodory function. Let \((t_n)_{n \in \mathbb{N}}\) be an increasing sequence of positive numbers and \((x_n)_{n \in \mathbb{N}}\) be a sequence of functions from \( \mathbb{R} \) to \( \mathbb{R}^d \) with the following properties:

(i) \( t_n \to +\infty \) as \( n \to \infty \);

(ii) for each \( n \in \mathbb{N} \), \( x_n(t) \) is a solution of

\[
x' = f(t, x)
\]

(6.2)

defined on \([-t_n, t_n]\);

(iii) for every \( N \in \mathbb{N} \) there exists a bounded set \( B_N \subseteq \mathbb{R}^d \) such that, for each \( n \geq N \), it holds that \( x_n(t) \in B_N \) for every \( t \in [-t_N, t_N] \).

Then there exists a subsequence \((\tilde{x}_n)_{n \in \mathbb{N}}\) of \((x_n)_{n \in \mathbb{N}}\) which converges uniformly on the compact subsets of \( \mathbb{R} \) to a solution \( \tilde{x}(t) \) of system (6.2); in particular \( \tilde{x}(t) \) is defined on \( \mathbb{R} \) and, for each \( N \in \mathbb{N} \), it holds that \( \tilde{x}(t) \in B_N \) for all \( t \in [-t_N, t_N] \).

**Proof.** This result is classical and perhaps a proof is not needed. We give a sketch of the proof for the reader’s convenience, following [49, Lemma 4].

First of all we observe that, by the Carathéodory assumption, for each \( N \in \mathbb{N} \) there exists a measurable function \( \rho_N \in L^1([-t_N, t_N], \mathbb{R}^+) \) such that

\[
\|f(t, x)\| \leq \rho_N(t), \quad \text{for a.e. } t \in [-t_N, t_N] \text{ and for all } x \in B_N.
\]

For every \( N \in \mathbb{N} \) we also introduce the absolutely continuous function

\[
\mathcal{M}_N(t) := \int_0^t \rho_N(\xi) \, d\xi, \quad t \in [-t_N, t_N].
\]

By hypothesis (ii), we have that

\[
x_n(t) = x_n(0) + \int_0^t f(\xi, x_n(\xi)) \, d\xi, \quad \forall t \in [-t_n, t_n], \forall n \in \mathbb{N},
\]

and, by hypothesis (iii), for every \( N \in \mathbb{N} \) it follows that

\[
|x_n(t') - x_n(t'')| \leq |\mathcal{M}_N(t') - \mathcal{M}_N(t'')|, \quad \forall t', t'' \in [-t_N, t_N], \forall n \geq N,
\]

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(cf. [40] p. 29). Consequently, the sequence \((x_n)_{n \in \mathbb{N}}\) restricted to the interval \([-t_0, t_0]\) is uniformly bounded (by any constant which bounds in the Euclidean norm the set \(B_0\)) and equicontinuous. By Ascoli-Arzela theorem, it has a subsequence \((x_n^0)_{n \in \mathbb{N}}\) which converges uniformly on \([-t_0, t_0]\) to a continuous function named \(\tilde{x}_0\). Similarly, the sequence \((x_n^0)_{n \geq 1}\) restricted to \([-t_1, t_1]\) is a uniformly bounded and equicontinuous sequence and has a subsequence \((x_n^1)_{n \geq 1}\) which converges uniformly on \([-t_1, t_1]\) to a continuous function \(\tilde{x}_1\) such that \(\tilde{x}_1(t) = \tilde{x}_0(t)\) for all \(t \in [-t_0, t_0]\). Proceeding inductively in this way, we construct a sequence of sequences \((x_n^N)_{n \geq N}\) so that \((x_n^N)_{n \geq N}\) is a subsequence of \((x_n^{N-1})_{n \geq N-1}\) and converges uniformly on \([-t_{N-1}, t_{N-1}]\) to a continuous function \(\tilde{x}_N\) such that \(\tilde{x}_N(t) = \tilde{x}_{N-1}(t)\) for all \(t \in [-t_{N-1}, t_{N-1}]\). By construction, we have that \(\tilde{x}_N(t) \in B_N\) for all \(t \in [-t_N, t_N]\). The diagonal sequence \((\tilde{x}_n)_{n \in \mathbb{N}} := (x_n^N)_{n \in \mathbb{N}}\) converges uniformly on every compact interval to a function \(\tilde{x}\) defined on \(\mathbb{R}\) and such that \(\tilde{x}(t) = \tilde{x}_N(t)\) for all \(t \in [-t_N, t_N]\) and therefore, \(\tilde{x}(t) \in B_N\) for all \(t \in [-t_N, t_N]\). It remains to prove that \(\tilde{x}(t)\) is a solution of (6.2) on \(\mathbb{R}\). Indeed, let \(t \in \mathbb{R}\) be arbitrary but fixed and let us fix \(N \in \mathbb{N}\) such that \(t \in [-t_N, t_N]\). Passing to the limit as \(n \to \infty\) in the identity

\[
\tilde{x}_n(t) = \tilde{x}_n(0) + \int_0^t f(\xi, \tilde{x}_n(\xi)) \, d\xi, \quad \forall n \geq N,
\]

via the Lebesgue dominated convergence theorem, we obtain

\[
\tilde{x}(t) = \tilde{x}(0) + \int_0^t f(\xi, \tilde{x}(\xi)) \, d\xi.
\]

For the arbitrariness of \(t \in \mathbb{R}\) and the above integral relation, we conclude that \(\tilde{x}(t)\) is absolutely continuous and a solution of (6.2) (in the Carathéodory sense).

If there exists a bounded set \(B\) such that \(B_N \subseteq B\) for all \(N \in \mathbb{N}\), then we have the stronger conclusion that \(\tilde{x}(t) \in B\) for all \(t \in \mathbb{R}\) (which is precisely the result of [44] Lemma 8.1 and [49] Lemma 4).

An application of Lemma 6.1 to the planar system

\[
\begin{align*}
\begin{cases}
  u' &= y \\
y' &= -cy - (a^+(t) - \mu a^-(t))g(u)
\end{cases} 
\end{align*}
\]

(6.3)

will produce bounded solutions with any prescribed complex behavior. In order to simplify the exposition, we suppose that the coefficient \(a(t)\) is a continuous \(T\)-periodic function of minimal period \(T\) having a positive hump followed by a negative one in a period interval (these are the same assumptions for the weight coefficient as in Theorem 6.1). In this framework, the next result follows.

**Theorem 6.5.** Let \(g: \mathbb{R}^+ \to \mathbb{R}^+\) be a continuous function satisfying \((g_1)\),

\[
g_0 = 0 \quad \text{and} \quad g_\infty = +\infty.
\]

Let \(a: \mathbb{R} \to \mathbb{R}\) be a \(T\)-periodic continuous function with minimal period \(T\) such that there exist two consecutive zeros \(\alpha < \beta\) so that \(a(t) > 0\) for all \(t \in [\alpha, \beta]\) and \(a(t) < 0\) for all \(t \in [\beta, \alpha + T]\). Then there exist \(0 < r < R\) and \(\mu^* > 0\) such that, for all \(\mu > \mu^*\), given any two-sided sequence \(L = (s_i)_{i \in \mathbb{Z}} \in \{0, 1\}^\mathbb{Z}\) which is not identically zero, there exists at least one positive solution \(u(t) = u_L(t)\) of equation (2.1) such that \(\|u\|_\infty < R\) and

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• $0 < u(t) < r$ on $[\alpha + iT, \beta + iT]$, if $s_i = 0$;
• $r < u(t_i) < R$ for some $t_i \in [\alpha + iT, \beta + iT]$, if $s_i = 1$;
• $0 < u(t) < r$ on $[\beta + iT, \alpha + (i+1)T]$, for all $i \in \mathbb{Z}$.

Proof. Without loss of generality, we suppose that $\alpha = 0$ and set $\tau := \beta - \alpha$, so that $a(t) > 0$ on $[0, \tau]$ and $a(t) < 0$ on $[\tau, T]$. We also introduce the intervals

$$I^+_i := [iT, \tau + iT], \quad I^-_i := [\tau + iT, (i+1)T], \quad i \in \mathbb{Z}. \quad (6.4)$$

Let $0 < r < R$ and $\mu^{**} > 0$ as in Theorem 6.1 and Theorem 6.2. One more time, we wish to emphasize the fact that, once we have fixed $r, R \mu^{**}$, we can produce $kT$-periodic solutions following any $k$-periodic sequence of two symbols, independently on $k$. Accordingly, from this moment to the end of the proof, $r, R$ and $\mu > \mu^{**}$ are fixed.

Consider now an arbitrary sequence $L = (s_i)_{i \in \mathbb{Z}} \in \{0,1\}^\mathbb{Z}$ which is not identically zero. We fix a positive integer $n_0$ such that there is at least an index $i \in \{-n_0, \ldots, n_0\}$ such that $s_i = 1$. Then, for each $n \geq n_0$ we consider the $(2n+1)$-periodic sequence $L'' = (s'_i)_{i \in \{0,1\}^\mathbb{Z}}$ which is obtained by truncating $L$ between $-n$ and $n$, and then repeating that string by periodicity. An application of Theorem 6.2 on the periodicity interval $[-nT,(n+1)T]$ ensures the existence of a positive periodic solution $u_n(t)$ such that $u_n(t + (2n+1)T) = u_n(t)$ for all $t \in \mathbb{R}$ and $\|u_n\|_{\infty} < R$. According to Theorem 6.2, we also know that $u_n(t) < r$ for all $t \in I^+_i$, if $s'_i = 0$, $u_n(t) > r$ for some $t \in I^-_i$, if $s'_i = 1$, and $\max_{t \in I^-_i} u_n(t) < r$ (for each $i \in \mathbb{Z}$).

Notice that, for $C := \max_{0 \leq s \leq R} g(s)$, we have that

$$|u''_n(t)| \leq |c||u'_n(t)| + (|a^+(t)| + \mu|a^-(t)|)C, \quad \forall t \in \mathbb{R},$$

and hence,

$$\frac{|u''_n(t)|}{1 + |u'_n(t)|} \leq \psi_{\mu}(t), \quad \forall t \in \mathbb{R}, \quad (6.5)$$

where we have set $\psi_{\mu}(t) := |c| + (|a^+(t)| + \mu|a^-(t)|)C$.

Since the truncated string $L''$ contains at least one $s'_i = s_i = 1$, with $i \in \{-n_0, \ldots, n_0\}$, we know that each periodic function $u_n(t)$ has at least a local maximum point $\hat{t}_n \in [-nT, n_0T + \tau[$ and then $u''_n(\hat{t}_n) = 0$. Suppose now that $N \geq n_0$ is fixed and define the constant

$$K_N := \exp \left( (2N+1) \int_0^T \psi_{\mu}(t) \, dt \right).$$

We claim that

$$|u'_n(t)| \leq K_N, \quad \forall t \in [-NT, (N+1)T], \quad \forall n \geq N. \quad (6.6)$$

Our claim follows from a Nagumo type argument as in [23, ch. I, § 4]. Suppose, by contradiction, that (6.6) is not true. Hence, there exist some $n \geq N$ and a point $t^*_n \in [-NT, (N+1)T]$ such that $u'_n(t^*_n) > K_N$ or $u'_n(t^*_n) < -K_N$. In the first case there exists a maximal interval $J \subseteq [-NT, (N+1)T]$ such that one of the following two possibilities occurs:

• $J = [\xi_0, \xi_1]$ and $u'_n(\xi_0) = 0$, $u'_n(\xi_1) > K_N$ with $u'_n(t) > 0$ for all $t \in [\xi_0, \xi_1]$;
Integrating \( u'(\xi_0) = 0, u'(\xi_1) > K_N \) with \( u'(t) > 0 \) for all \( t \in [\xi_1, \xi_0] \). Integrating \( u'(\xi)/\sqrt{1 + |u'|} \) on \( J \) and using (6.5), we obtain
\[
\log(1 + K_N) < \log(1 + |u'(\xi_1)|) \leq \int_J \psi(t) \, dt
\]
\[
\leq \int_{-NT}^{(N+1)T} \psi(t) \, dt = (2N + 1) \int_0^T \psi(t) \, dt = \log(K_N),
\]
a contradiction. We have achieved a contradiction by assuming \( u_n(t^*_n) > K_N \). A similar argument gives a contradiction if \( u_n(t^*_n) < -K_N \).

Now we write equation (2.1) as a planar system (6.5). From the above remarks, one can see that (up to a reparametrization of indices, counting from \( n_0 \)) assumptions (i), (ii), (iii) of Lemma 6.1 are satisfied, taking \( t_n := nT, f(t, x) = (y, -cy - (a^+(t) - ma^-(t))g(u)) \), with \( x = (u, y) \), and
\[
B_N := \{ x \in \mathbb{R}^2 : 0 < x_1 < R, |x_2| \leq K_N \}, \quad N \in \mathbb{N},
\]
as bounded set in \( \mathbb{R}^2 \). By Lemma 6.1 there is a solution \( \tilde{u}(t) \) of equation (2.1) which is defined on \( \mathbb{R} \) and such that \( 0 \leq \tilde{u}(t) \leq R \) for all \( t \in [-NT, NT] \), for each \( N \in \mathbb{N} \). Then \( ||\tilde{u}||_{\infty} \leq R \). Moreover, such a solution \( \tilde{u}(t) \) is the limit of a subsequence \( (\tilde{u}_n)_n \) of the sequence of the periodic solutions \( u_n(t) \).

We claim that
\[
\bullet \quad 0 < \tilde{u}(t) < r \text{ on } I^+_i, \text{ if } s_i = 0;
\]
\[
\bullet \quad r < \tilde{u}(\tilde{t}_i) < R \text{ for some } \tilde{t}_i \in I^+_i, \text{ if } s_i = 1;
\]
\[
\bullet \quad 0 < \tilde{u}(t) < r \text{ on } I^-_i, \text{ for all } i \in \mathbb{Z}.
\]

To prove our claim, let us fix \( i \in \mathbb{Z} \) and consider the interval \( I^+_i \) introduced in (6.4). For each \( n \geq |i| \) (and \( n \geq n_0 \)) the periodic solution \( u_n(t) \) is defined on \( \mathbb{R} \) and such that \( 0 < u_n(t) < r \) for all \( t \in I^+_i \), if \( s_i = 0 \), or \( \max_{t \in I^+_i} u_n(t) > r \), if \( s_i = 1 \). Passing to the limit on the subsequence \( (\tilde{u}_n)_n \), we obtain that
\[
0 \leq \tilde{u}(t) \leq r, \quad \forall t \in I^+_i, \quad \text{if } s_i = 0,
\]
or
\[
\max_{t \in I^+_i} \tilde{u}(t) \geq r, \quad \text{if } s_i = 1,
\]
respectively. With the same argument we also prove that
\[
0 \leq \tilde{u}(t) \leq r, \quad \forall t \in I^-_i, \quad \forall i \in \mathbb{Z}.
\]
By Remark 4.8 we get that \( \tilde{u}(t) < R^* \leq R \), for all \( t \in \mathbb{R} \). Moreover, since there exists at least one index \( i \in \mathbb{Z} \) such that \( s_i = 1 \), we know that \( \tilde{u} \) is not identically zero. Hence, a maximum principle argument shows that \( \tilde{u}(t) \) never vanishes. In conclusion, we have proved that
\[
0 < \tilde{u}(t) < R, \quad \forall t \in \mathbb{R}.
\]
Next, we observe that
\[
\max_{t \in I^+_i} \tilde{u}(t) \neq r, \quad \forall i \in \mathbb{Z}.
\]
Indeed, this is a consequence of Remark 4.10, using the fact that the solution \( \tilde{u}(t) \) is upper bounded by \( R^* \) and, at the beginning, \( \mu \) has been chosen large enough (note also that we apply that result in the case \( m = 1 \) and therefore the sets \( I_y^+ + \ell T \) of Remark 4.10 reduce, in our case, to the intervals \( [0, \tau] + \ell T \)). Finally, using Remark 4.12 we also deduce that

\[
\tilde{u}(t) < r, \quad \forall \ t \in I^-, \ \forall \ i \in \mathbb{Z}.
\]

Our claim is thus verified and this completes the proof of the theorem.

For the equation

\[
u'' + (a^+(t) - \mu a^- (t)) u^3 = 0,
\]
a version of Theorem 6.5 has been recently obtained in [5], under the supplementary condition that in the strings of symbols the consecutive sequences of zeros are bounded in length. The proof of [5, Theorem 2.1] and ours are completely different (the former one relies on variational techniques, ours on degree theory).

Our new contribution is twofold: on one side, we can deal with non Hamiltonian systems (indeed we can consider also a term of the form \( cu' \)) and with a nonlinearity \( g(s) \) which is not positively homogeneous; on the other hand, our approach allows to remove the condition on bounded sequences of consecutive zeros. In any case, the two results are not completely comparable since the way to associate a solution to a given string of symbols is different: the symbols 0 and 1 in our case are associated to the maximum of a solution on \( I^+ i + \ell T \), while in [5, Theorem 2.1] are associated to an integral norm on the same interval.

We remark that Theorem 6.5 can be generalized at the same extent like Theorem 6.4 generalizes Theorem 6.3. Indeed, combining the proofs of Theorem 6.4 and Theorem 6.5 we can obtain the following result (the proof is omitted).

**Theorem 6.6.** Let \( g: \mathbb{R}^+ \to \mathbb{R}^+ \) be a continuous function satisfying \((g_*)\),

\[
g_0 = 0 \quad \text{and} \quad g_\infty > \max_{i=1, \ldots, m} \lambda_i^1.
\]

Let \( a: \mathbb{R} \to \mathbb{R} \) be a \( T \)-periodic locally integrable function satisfying \((a_*)\) with minimal period \( T \). Then there exist \( 0 < r < R \) and \( \mu^{**} > 0 \) such that, for all \( \mu > \mu^{**} \), given any two-sided sequence \( \mathcal{L} = (s_\ell)_{\ell \in \mathbb{Z}} \) in the alphabet \( A^m = \{0, 1\}^m \) and not identically zero, there exists at least one positive solution \( u(t) = u_\mathcal{L}(t) \) of equation \((2.1)\) such that \( \|u\|_\infty < R \) and the following properties hold (where we set \( s_\ell = (s_\ell^i)_{i=1, \ldots, m} \), for each \( \ell \in \mathbb{Z} \)):

- \( 0 < u(t) < r \) on \( I^+_{i} + \ell T \), if \( s^i_\ell = 0 \);
- \( r < u(\hat{t}) < R \) for some \( \hat{t} \in I^+_{i} + \ell T \), if \( s^i_\ell = 1 \);
- \( 0 < u(t) < r \) on \( I^-_{i} + \ell T \), for all \( i \in \{1, \ldots, m\} \) and for all \( \ell \in \mathbb{Z} \).

## 7 The Neumann boundary value problem

In this section we briefly describe how to obtain the results of Section [4] and Section [5] for the Neumann boundary value problem. For the sake of simplicity,
we deal with the case \( c = 0 \). If \( c \neq 0 \), we can produce analogous results writing equation (2.1) as

\[
(u' e^{ct})' + \tilde{a}_\mu(t)g(u) = 0, \quad \text{with } \tilde{a}_\mu(t) := a_\mu(t)e^{ct},
\]

and entering in the setting of coincidence degree theory for the linear operator \( L: u \mapsto -(u' e^{ct})' \). For the abstract framework, we refer to [31], where the existence of positive solutions is analyzed. Accordingly, we consider the BVP

\[
\begin{aligned}
\frac{d^2u}{dt^2} + a_\mu(t)g(u) &= 0, \\
\frac{du}{dt}(0) &= u(T) = 0,
\end{aligned}
\]

(7.1)

where \( a: [0, T] \rightarrow \mathbb{R} \) is an integrable function satisfying condition \((a_*)\) and \( g(s) \) fulfills the same conditions as in the previous sections. In particular, when we assume \((a_*)\) we suppose that there exist \( m \geq 2 \) subintervals of \([0, T]\) where the weight is non-negative separated by \( m - 1 \) subintervals where the weight is non-positive, namely there are \( 2m + 2 \) points

\[
0 = \tau_0 < \sigma_1 < \tau_1 < \ldots < \sigma_i < \tau_i < \ldots < \sigma_m < \tau_m \leq \sigma_{m+1} = T
\]

such that \( a(t) > 0 \) on \([\sigma_i, \tau_i]\) and \( a(t) < 0 \) on \([\tau_i, \sigma_{i+1}]\).

In this case, the abstract setting of Section 3 can be reproduced almost verbatim with \( X := C([0, T]), \ Z := L^1([0, T]) \) and \( L: u \mapsto -u'' \), by taking in dom \( L \) the functions of \( X \) which are continuously differentiable with absolutely continuous derivative and such that \( u'(0) = u'(T) = 0 \). With the above positions ker \( L \cong \mathbb{R} \), Im \( L \), as well as the projectors \( P \) and \( Q \) are exactly the same as in Section 3. Then Theorem 4.1 can be restated as follows.

**Theorem 7.1.** Let \( g: \mathbb{R}^+ \rightarrow \mathbb{R}^+ \) be a continuous function satisfying \((g_*)\),

\[
g_0 = 0 \quad \text{and} \quad g_\infty > \max_{i=1, \ldots, m} \lambda_1^i.
\]

Let \( a: [0, T] \rightarrow \mathbb{R} \) be an integrable function satisfying \((a_*)\). Then there exists \( \mu^* > 0 \) such that for all \( \mu > \mu^* \) problem (7.1) has at least \( 2^m - 1 \) positive solutions.

As in Theorem 4.1, the \( 2^m - 1 \) positive solutions are discriminated by the fact that \( \max_{t \in I_i^+} u(t) < r \) or \( r < \max_{t \in I_i^+} u(t) < R \), where \( I_i^+ = [\sigma_i, \tau_i] \) is the \( i \)-th interval where the weight is non-negative (cf. Remark 4.1). The constants \( \lambda_1^i \) (for \( i = 1, \ldots, m \)) are the first eigenvalues of the eigenvalue problems in \( I_i^+ \)

\[
\varphi'' + \lambda a(t)\varphi = 0, \quad \varphi|_{\partial I_i^+} = 0.
\]

If \( \sigma_1 = \tau_0 = 0 \) (that is \( a(t) \) starts with a first interval of non-negativity), we can take \( \lambda_1^1 \) as the first eigenvalue of the eigenvalue problem

\[
\varphi'' + \lambda a(t)\varphi = 0, \quad \varphi'(0) = \varphi(\tau_1) = 0,
\]

while if \( \tau_m = \sigma_{m+1} = T \) (that is \( a(t) \) ends with a last interval of non-negativity), we can take \( \lambda_1^m \) as the first eigenvalue of the eigenvalue problem

\[
\varphi'' + \lambda a(t)\varphi = 0, \quad \varphi(\sigma_m) = \varphi'(T) = 0.
\]

Clearly, for the Neumann problem (7.1) we can also reestablish the corollaries in Section 5. In particular, Corollary 5.2 reads as follows.
Corollary 7.1. Let \( g : \mathbb{R}^+ \to \mathbb{R}^+ \) be a continuous function satisfying (\( g_* \)),
\[
g_0 = 0 \quad \text{and} \quad g_\infty = +\infty.
\]
Let \( a : [0,T] \to \mathbb{R} \) be an integrable function satisfying (\( a_* \)). Then there exists \( \mu^* > 0 \) such that for all \( \mu > \mu^* \) problem (7.1) has at least \( 2^m - 1 \) positive solutions.

In the sequel we are going to use also a variant for the Neumann problem of Corollary 5.5 that we do not state here explicitly.

7.1 Radially symmetric solutions

We show now a consequence of the above results to the study of a PDE in an annular domain. In order to simplify the exposition, we assume the continuity of the weight function. In this manner, the solutions we find are the “classical” ones (at least two times continuously differentiable). The first part of the following presentation is essentially borrowed from [31, § 4.1]; however, the multiplicity result is a new contribution.

Let \( \| \cdot \| \) be the Euclidean norm in \( \mathbb{R}^N \) (for \( N \geq 2 \)) and let
\[
\Omega := B(0,R_2) \setminus B[0,R_1] = \{ x \in \mathbb{R}^N : R_1 < \| x \| < R_2 \}
\]
be an open annular domain, with \( 0 < R_1 < R_2 \).

We deal with the Neumann boundary value problem
\[
\begin{aligned}
\begin{cases}
-\Delta u &= q_\mu(x) \, g(u) \quad \text{in } \Omega \\
\frac{\partial u}{\partial n} &= 0 \quad \text{on } \partial \Omega,
\end{cases}
\end{aligned}
\tag{7.2}
\]
where \( q : \overline{\Omega} \to \mathbb{R} \) is a continuous function which is radially symmetric, namely there exists a continuous scalar function \( Q : [R_1,R_2] \to \mathbb{R} \) such that
\[
q(x) = Q(\| x \|), \quad \forall \, x \in \overline{\Omega},
\]
and
\[
q_\mu(x) := q^+(x) - \mu q^- (x), \quad Q_\mu(r) := Q^+(r) - \mu Q^- (r)
\]
We look for existence/nonexistence and multiplicity of radially symmetric positive solutions of (7.2), that are classical solutions such that \( u(x) > 0 \) for all \( x \in \Omega \) and also \( u(x) = \mathcal{U}(\| x \|) \), where \( \mathcal{U} \) is a scalar function defined on \( [R_1,R_2] \).

Accordingly, our study can be reduced to the search of positive solutions of the Neumann boundary value problem
\[
\mathcal{U}''(r) + \frac{N-1}{r} \, \mathcal{U}'(r) + Q_\mu(r) g(\mathcal{U}(r)) = 0, \quad \mathcal{U}'(R_1) = \mathcal{U}'(R_2) = 0. \tag{7.3}
\]
Using the standard change of variable
\[
t = h(r) := \int_{R_1}^r \xi^{1-N} \, d\xi
\]
and defining
\[
T := \int_{R_1}^{R_2} \xi^{1-N} \, d\xi, \quad r(t) := h^{-1}(t) \quad \text{and} \quad v(t) = \mathcal{U}(r(t)),
\]

we transform (7.3) into the equivalent problem
\[ v'' + a_\mu(t)g(v) = 0, \quad v'(0) = v'(T) = 0, \]  
(7.4)
with
\[ a(t) := r(t)^{2(N-1)}Q(r(t)). \]
Consequently, the Neumann boundary value problem (7.4) is of the same form of (7.1) and we can apply the previous results.

Accordingly, suppose also that
\[(q_*) \text{ there exist } 2m + 2 \text{ points } R_1 = \tau_0 \leq \sigma_1 < \tau_1 < \ldots < \sigma_m < \tau_m \leq \sigma_{m+1} = R_2 \text{ such that }\]
\[ Q(r) > 0 \text{ on } [\sigma_i, \tau_i], \; i = 1, \ldots, m; \]
\[ Q(r) < 0 \text{ on } [\tau_i, \sigma_{i+1}], \; i = 0, \ldots, m. \]
Notice that condition
\[ \int_0^T a_\mu(t) \, dt < 0 \]  
(7.5)
reads as
\[ 0 > \int_0^T r(t)^{2(N-1)}Q_\mu(r(t)) \, dt = \int_{R_1}^{R_2} r^{-N-1}Q_\mu(r) \, dr. \]
Up to a multiplicative constant, the latter integral is the integral of \(q(x)\) on \(\Omega\), using the change of variable formula for radially symmetric functions. Thus, \(\mu > 0\) satisfies (7.5) if and only if \(\mu\) satisfies
\[(q_*+) \int_\Omega q_\mu(x) \, dx < 0. \]
Similarly, the integral in (7.5) is sufficiently negative (depending on \(\mu\)) if and only if the integral in \((q_*+)\) is negative enough (depending on \(\mu\)). With these premises, Corollary 7.1 yields to the following result.

**Theorem 7.2.** Let \(g : \mathbb{R}^+ \to \mathbb{R}^+\) be a continuous function satisfying \((g_*)\),
\[ g_0 = 0 \quad \text{and} \quad g_\infty = +\infty. \]
Let \(q(x)\) be a continuous (radial) weight function as above. Then there exists \(\mu^* > 0\) such that for each \(\mu > \mu^*\) problem (7.2) has at least \(2^m - 1\) positive radially symmetric solutions.

Corollary 7.1 and Theorem 7.2 represent an extension of [10], where the same result was obtained (with a shooting type approach) for \(m = 2\). Another extension of [10], for an arbitrary \(m \geq 2\), has been recently achieved in [5] (using a variational approach) for a power type nonlinearity \(g(s)\).

Adding the smoothness of \(g(s)\), from Corollary 5.5 we obtain the next result.

**Theorem 7.3.** Let \(g : \mathbb{R}^+ \to \mathbb{R}^+\) be a continuously differentiable function satisfying \((g_*)\),
\[ g_0 = 0 \quad \text{and} \quad g_\infty = +\infty. \]
Let \(q(x)\) be a continuous (radial) weight function as above. Then, for all \(\mu > 0\) such that \((q_*)\) holds, there exist two constants \(0 < \omega_* \leq \omega^*\) (depending on \(\mu\)) such that the Neumann boundary value problem

\[
\begin{cases}
-\Delta u = \nu q_\mu(x) g(u) & \text{in } \Omega \\
\frac{\partial u}{\partial n} = 0 & \text{on } \partial \Omega
\end{cases}
\]  

(7.6)

has no positive solutions for \(0 < \nu < \omega_*\) and at least one positive solution for \(\nu > \omega^*\). Moreover there exists \(\nu^* > 0\) such that for all \(\nu > \nu^*\) there exists \(\mu^* = \mu^*(\nu)\) such that for \(\mu > \mu^*\) problem (7.6) has at least \(2^n - 1\) positive solutions.

A Mawhin’s coincidence degree

This appendix is devoted to recalling some basic facts about a version of Mawhin’s coincidence degree for open and possibly unbounded sets that is used in the present paper. For more details about the coincidence degree, proofs and applications, we refer to [33, 47, 48] and the references therein.

Let \(X\) and \(Z\) be real Banach spaces and let \(L : \text{dom } L \subseteq X \to Z\) be a linear Fredholm mapping of index zero, i.e. \(\text{Im } L\) is a closed subspace of \(Z\) and \(\dim(\ker L) = \text{codim}(\text{Im } L)\) are finite. We denote by \(\ker L = L^{-1}(0)\) the kernel of \(L\), by \(\text{Im } L \subseteq Z\) the image of \(L\) and by \(\text{coker } L \cong Z/\text{Im } L\) the complementary subspace of \(\text{Im } L\) in \(Z\). Consider the linear continuous projections

\[P : X \to \ker L, \quad Q : Z \to \text{coker } L.\]

so that

\[X = \ker L \oplus \ker P, \quad Z = \text{Im } L \oplus \text{Im } Q.\]

We denote by

\[K_P : \text{Im } L \to \text{dom } L \cap \ker P\]

the right inverse of \(L\), i.e. \(LK_P(w) = w\) for each \(w \in \text{Im } L\). Since \(\ker L\) and \(\text{coker } L\) are finite dimensional vector spaces of the same dimension, once an orientation on both spaces is fixed, we choose a linear orientation-preserving isomorphism \(J : \text{coker } L \to \ker L\).

Let

\[N : X \to Z\]

be a nonlinear \(L\)-completely continuous operator, namely \(N\) is continuous and \(QN(B)\) and \(K_P(Id - Q)\) are relatively compact sets, for each bounded set \(B \subseteq X\). For example, \(N\) is \(L\)-completely continuous when \(N\) is continuous, maps bounded sets into bounded sets and \(K_P\) is a compact linear operator. Consider the coincidence equation

\[Lu = Nu, \quad u \in \text{dom } L.\]  

(A.1)

One can easily prove that equation [A.1] is equivalent to the fixed point problem

\[u = \Phi(u) := Pu + JQNu + K_P(Id - Q)Nu, \quad u \in X.\]  

(A.2)
Notice that, under the above assumptions, $\Phi: X \to X$ is a completely continuous operator. Therefore, applying Leray-Schauder degree theory to the operator equation (A.2), it is possible to solve equation (A.1) when $L$ is not invertible.

Let $O \subseteq X$ be an open and bounded set such that

\[ Lu \neq Nu, \quad \forall u \in \text{dom} \, L \cap \partial O. \]

In this case, the coincidence degree of $L$ and $N$ in $O$ is defined as

\[ D_L(L - N, O) := \text{deg}_{LS}(Id - \Phi, O, 0), \]

where “deg$_{LS}$” denotes the Leray-Schauder degree. We underline that $D_L$ is independent on the choice of the linear orientation-preserving isomorphism $J$ and of the projectors $P$ and $Q$.

Now we present an extension of the coincidence degree to open (possibly unbounded) sets, following the standard approach used in the theory of fixed point index to define the Leray-Schauder degree for locally compact maps on arbitrary open sets (cf. [55, 56]). Extensions of coincidence degree to the case of general open sets have been already considered in previous articles (see for instance [20, 50, 52]).

Consider an open set $\Omega \subseteq X$ and suppose that the solution set

\[ \text{Fix}(\Phi, \Omega) := \{ u \in \Omega: u = \Phi u \} = \{ u \in \Omega \cap \text{dom} \, L: Lu = Nu \} \]

is compact. According to the extension of Leray-Schauder degree, we can define

\[ \text{deg}_{LS}(Id - \Phi, \Omega, 0) := \text{deg}_{LS}(Id - \Phi, \mathcal{V}, 0), \]

where $\mathcal{V}$ is an open and bounded set with $\text{Fix}(\Phi, \Omega) \subseteq \mathcal{V} \subseteq \mathcal{V} \subseteq \Omega$. The definition is independent of the choice of $\mathcal{V}$. In this case the coincidence degree of $L$ and $N$ in $\Omega$ is defined as

\[ D_L(L - N, \Omega) := D_L(L - N, \mathcal{V}) = \text{deg}_{LS}(Id - \Phi, \mathcal{V}, 0), \]

with $\mathcal{V}$ as above. Using the excision property of the Leray-Schauder degree, it is easy to check that if $\Omega$ is an open and bounded set satisfying $Lu \neq Nu$, for all $u \in \partial \Omega \cap \text{dom} \, L$, this definition is the usual definition of coincidence degree described above.

The main properties of the coincidence degree are the following.

- **Additivity.** Let $\Omega_1$, $\Omega_2$ be open and disjoint subsets of $\Omega$ such that $\text{Fix}(\Phi, \Omega) \subseteq \Omega_1 \cup \Omega_2$. Then

  \[ D_L(L - N, \Omega) = D_L(L - N, \Omega_1) + D_L(L - N, \Omega_2). \]

- **Excision.** Let $\Omega_0$ be an open subset of $\Omega$ such that $\text{Fix}(\Phi, \Omega) \subseteq \Omega_0$. Then

  \[ D_L(L - N, \Omega) = D_L(L - N, \Omega_0). \]

- **Existence theorem.** If $D_L(L - N, \Omega) \neq 0$, then $\text{Fix}(\Phi, \Omega) \neq \emptyset$, hence there exists $u \in \Omega \cap \text{dom} \, L$ such that $Lu = Nu$. 

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• Homotopic invariance. Let $H: [0, 1] \times \Omega \to X$, $H_\partial(u) := H(\partial, u)$, be a continuous homotopy such that

$$S := \bigcup_{\vartheta \in [0, 1]} \{ u \in \Omega \cap \text{dom } L : Lu = H_\vartheta u \}$$

is a compact set and there exists an open neighborhood $W$ of $S$ such that $W \subseteq \Omega$ and $(K_P(Id - Q)H)|_{[0,1] \times W}$ is a compact map. Then the map $\vartheta \mapsto D_L(L - H_\vartheta, \Omega)$ is constant on $[0, 1]$.

The following two results are of crucial importance in the computation of the coincidence degree in open and bounded sets. The proofs are omitted. Lemma A.1 is taken from [33, Theorem IV.1] and [48, Theorem 2.4], while Lemma A.2 is a classical result (see [54]) adapted to the present setting as in [31, Lemma 2.2, Lemma 2.3]. By “deg$_B$” we denote the Brouwer degree.

Lemma A.1. Let $L$ and $N$ be as above and let $\Omega \subseteq X$ be an open and bounded set. Suppose that

$$Lu \neq \vartheta Nu, \quad \forall u \in \text{dom } L \cap \partial \Omega, \quad \forall \vartheta \in [0, 1],$$

and

$$QN(u) \neq 0, \quad \forall u \in \partial \Omega \cap \ker L.$$

Then

$$D_L(L - N, \Omega) = \text{deg}_B(-JQN|_{\ker L}, \Omega \cap \ker L, 0).$$

Lemma A.2. Let $L$ and $N$ be as above and let $\Omega \subseteq X$ be an open and bounded set. Suppose that there exist a vector $v \neq 0$ and a constant $\alpha_0 > 0$ such that

$$Lu \neq Nu + \alpha v, \quad \forall u \in \text{dom } L \cap \partial \Omega, \quad \forall \alpha \in [0, \alpha_0],$$

and

$$Lu \neq Nu + \alpha_0 v, \quad \forall u \in \text{dom } L \cap \Omega.$$

Then

$$D_L(L - N, \Omega) = 0.$$

Finally we state and prove a key lemma for the computation of the degree in open and unbounded sets. This result is a more general version of Lemma A.2.

Lemma A.3. Let $L$ and $N$ be as above and let $\Omega \subseteq X$ be an open set. Suppose that there exist a vector $v \neq 0$ and a constant $\alpha_0 > 0$ such that

(a) $Lu \neq Nu + \alpha v$, for all $u \in \text{dom } L \cap \partial \Omega$ and for all $\alpha \geq 0$;

(b) for all $\beta \geq 0$ there exists $R_\beta > 0$ such that if there exist $u \in \overline{\Omega} \cap \text{dom } L$ and $\alpha \in [0, \beta]$ with $Lu = Nu + \alpha v$, then $\|u\|_X \leq R_\beta$;

(c) there exists $\alpha_0 > 0$ such that $Lu \neq Nu + \alpha v$, for all $u \in \text{dom } L \cap \Omega$ and $\alpha \geq \alpha_0$.

Then

$$D_L(L - N, \Omega) = 0.$$
Proof. For $\alpha \geq 0$, let us consider the set
\[ R_\alpha := \{ u \in \Omega \cap \text{dom} L: Lu = Nu + \alpha \nu\}. \]
where $\nu^* := \int \nu + K_P(\text{Id} - Q)v$. Without loss of generality, we assume that $R_{\alpha'} < R_{\alpha''}$ for $\alpha' < \alpha''$. By conditions (a), for all $\alpha \geq 0$, the solution set $R_\alpha$ is disjoint from $\partial \Omega$. Moreover, by conditions (b) and (c), $R_\alpha$ is contained in $\Omega \cap B(0, R_{\alpha}+1)$. So $R_\alpha$ is bounded, and hence compact. In this manner we have proved that the coincidence degree $D_L(L - N - \alpha \nu, \Omega)$ is well defined for any $\alpha \geq 0$.

Now, condition (c), together with the property of existence of solutions when the degree $D_L$ is nonzero, implies that there exists $\alpha_0 \geq 0$ such that $D_L(L - N - \alpha_0 \nu, \Omega) = 0$.

On the other hand, from condition (b) applied to $\beta = \alpha_0$, repeating the same argument as above, we find that the set
\[ S := \bigcup_{\alpha \in [0, \alpha_0]} R_\alpha = \bigcup_{\alpha \in [0, \alpha_0]} \{ u \in \Omega \cap \text{dom} L: Lu = Nu + \alpha \nu\} \]
is a compact subset of $\Omega$. Hence, by the homotopic invariance of the coincidence degree, we have that
\[ D_L(L - N, \Omega) = D_L(L - N - \alpha_0 \nu, \Omega) = 0. \]
This concludes the proof.

\section{A combinatorial lemma}

In this final appendix we present the key lemma for the proof of our main multiplicity result. The proof is based on the same inductive argument of [32, Lemma 4.1].

Lemma B.1. Let $\mathcal{I} \subseteq \{1, \ldots, n\}$ be a set of indices. Suppose that for all $\mathcal{J} \subseteq \mathcal{I}$ the coincidence degree is defined on the sets $\Lambda^\mathcal{J}$ and $\Omega^\mathcal{J}$, with
\[ D_L(L - N, \Omega^\emptyset) = D_L(L - N, \Lambda^\emptyset) = 1 \quad (B.1) \]
and
\[ D_L(L - N, \Omega^\mathcal{J}) = 0, \quad \forall \emptyset \neq \mathcal{J} \subseteq \mathcal{I}. \quad (B.2) \]
Then
\[ D_L(L - N, \Lambda^\mathcal{I}) = (-1)^{\# \mathcal{I}}. \quad (B.3) \]

Proof. First of all, we notice that, in view of (B.1), the conclusion is trivially satisfied when $\mathcal{I} = \emptyset$. Suppose now that $m := \# \mathcal{I} \geq 1$. We are going to prove our claim by using an inductive argument. More precisely, for every integer $k$ with $0 \leq k \leq m$, we introduce the property $\mathcal{P}(k)$ which reads as follows: the formula
\[ D_L(L - N, \Lambda^\mathcal{J}) = (-1)^{\# \mathcal{J}} \]
holds for each subset $\mathcal{J}$ of $\mathcal{I}$ having at most $k$ elements. In this manner, if we are able to prove $\mathcal{P}(m)$, then (B.3) follows.
Verification of $\mathcal{P}(0)$. It follows by hypothesis [B.1].

Verification of $\mathcal{P}(1)$. Condition [B.1] covers the case $\mathcal{J} = \emptyset$. For $\mathcal{J} = \{j\}$, with $j \in \mathcal{I}$, we have

$$DL(L - N, \Lambda^j) = DL(L - N, \Lambda^{\{j\}}) = DL(L - N, \Omega^{\{j\}} \setminus \Lambda^\emptyset) = 0 - 1 = -1 = (-1)^\#J.$$

Verification of $\mathcal{P}(k - 1) \Rightarrow \mathcal{P}(k)$, for $1 \leq k \leq m$. Assuming the validity of $\mathcal{P}(k - 1)$ we have that the formula is true for every subset of $\mathcal{I}$ having at most $k - 1$ elements. Therefore, in order to prove $\mathcal{P}(k)$, we have only to check that the formula is true for an arbitrary subset $\mathcal{J}$ of $\mathcal{I}$ with $\#J = k$. Writing $\Omega^J$ as the disjoint union

$$\Omega^J = \Lambda^J \cup \bigcup_{\mathcal{K} \subseteq \mathcal{J}} \Lambda^\mathcal{K},$$

by the inductive hypothesis and assumption [B.2], we obtain

$$DL(L - N, \Lambda^J) = DL(L - N, \Omega^J) - \sum_{\mathcal{K} \subseteq \mathcal{J}} DL(L - N, \Lambda^\mathcal{K}) =
= 0 - \sum_{\mathcal{K} \subseteq \mathcal{J}} (-1)^\#\mathcal{K} = - \sum_{\mathcal{K} \subseteq \mathcal{J}} (-1)^\#\mathcal{K} + (-1)^\#J.$$

Observe now that

$$\sum_{\mathcal{K} \subseteq \mathcal{J}} (-1)^\#\mathcal{K} = 0,$$

due to the fact that in a finite set there are so many subsets of even cardinality as many subsets of odd cardinality. Thus we conclude that

$$DL(L - N, \Lambda^J) = (-1)^\#J.$$

Therefore $\mathcal{P}(k)$ is proved. \qed

In Section 4.1 we have proved (4.9) and (4.12), which correspond to the hypotheses [B.1] and [B.2] in the above combinatorial lemma. The conclusion given by [B.3] guarantees the validity of (4.13).

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