Application of Statistical Methods of Time-Series for Estimating and Forecasting the Wheat Series in Yemen (Production and Import)

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Abstract: Due to the importance of the wheat crop which represents 90% of the grain consumed, In this papers, we compared between the following statistical methods : Box and Jenkins model, exponential smoothing models (with trend and without seasonal) and Simple regression for estimating and forecasting to two time series of wheat(production and import). We reached to the following results: 1. Brown exponential smoothing model for modeling the imported wheat series. 2. ARIMA (1, 1, 1) model for modeling the product wheat series. For the wheat crop, the ratio of production to consumption is expected to reach 6.3% in 2015 and continues to decline even up to 5.4% in 2020. This means that the problem of food security well be worse in Yemen.

Keywords: Time Series, Wheat Crop, Forecasting, Box and Jenkins, Exponential Smoothing

1. Introduction

The human needs to know the past in order to predict the future to find optimal solutions of many problems which face humanity in this century. Yemen is one of the Arab countries where local demand for food is growing exponentially. Therefore, it suffers from a huge lack to cover all the population needs of foodstuffs especially wheat which represents staple food of most the population. Although in recent years the amount production of wheat compared with imported wheat reach in 2010 to 92%. According to what has mention above we compered these statistical methods of time series: Box and Jenkins methodology ,exponential smoothing model nd Simple regression to estimate and forecast the two wheat time series (import,product) from 1961 to 2010 of the Organization’s site of Food and Agriculture (FAO) and the Central Bureau of Statistics in Yemen. We used these programmes SPSS, EVIEWS and EXCLE.

2. Theoretical Formulation

2.1. Holt and Brown’s Exponential Smoothing Method

In the case where the series has a trend, we can adopt the following prediction formula:

\[ \hat{y}_{t+h} = a_t + b_t h \]

The values \( a_t \) and \( b_t \) are constantly updated by the following equations:

\[ a_t = \alpha y_t + (1-\alpha)(a_{t-1} + b_{t-1}) \]

and

\[ b_t = \alpha (a_t - a_{t-1}) + (1-\alpha)b_{t-1} \]

This forecast model is known as the model name of HOLT. A special case of model HOLT, called model BROWN or dual exponential smoothing is obtained when the smoothing
constants $\alpha_1$ and $\alpha_2$ are related to the same parameter $\alpha$, by the relations: $\alpha_1 = \alpha(2-\alpha)$ et $\alpha_2 = \frac{\alpha}{2-\alpha}$. For these two models, we need to give initial values $a_0$ and $b_0$ to produce forecasts. Thus we take $b_0$ which equals the coefficient simple linear regression calculated on the basis of the first five values of the series. Thereafter, $a_0$ is deduced by the relation: $a_0 = y_1 - b_0$, as the smoothing constants they are set by the user. In practice often gives a value to $\alpha$ between 0.01 and 0.30. [3]

2.2. Stationary Process

A second process is stationary if:

- $\forall t \in Z, E(X_i^2) < \infty$
- $\forall t \in Z, E(X_i) = m$
- $\forall t \in Z, \forall h \in Z, Cov(X_i, X_{i+h}) = \gamma(h)$

2.3. White Noise

White noise is a stationary process such that:

- $E(\varepsilon_i) = m, \forall t$
- $Var(\varepsilon_i) = \sigma^2, \forall t$
- $Cov(\varepsilon_i, \varepsilon_{i+h}) = \gamma(h), \forall t, \forall h > 0$

This notion of white noise corresponds to the usual assumptions on residues in multiple regression. Random variables $\varepsilon_i$ are also called random shocks. We implicitly assumes that random shocks $\varepsilon_i$ follow a normal distribution $N(0, \sigma^2)$

2.4. Autocorrelation

The autocorrelation function is the application $\rho$ of $Z$ in $R$ defined by:

$$\rho(h) = \frac{\gamma(h)}{\gamma(0)}, h \in Z$$

$\rho(h)$ Measuring the correlation between $X_i$ and $X_{i+h}$ because:

$$\frac{Cov(X_i, X_{i+h})}{\sqrt{V(X_i)\sqrt{V(X_{i+h})}}} = \frac{\gamma(h)}{\sqrt{\gamma(0)\sqrt{\gamma(0)}}}, h \in Z$$

2.5. Autocorrelation Partial

The partial autocorrelation function with delay $k$ is defined as the partial correlation coefficient between $X_i$ et $X_{i-k}$ the influence of other variables shifted by $k$ periods $X_{i-1}, X_{i-2}, ..., X_{i-k+1}$ have been withdrawn.

2.6. Autoregressive Process AR($p$)

Let a process $(X_i, t \in Z), X_i$ is said autoregressive process of order $p$ (AR($p$)) if

$$X_i = \phi_1X_{i-1} + \phi_2X_{i-2} + ... + \phi_pX_{i-p} + \varepsilon_i$$

Where $\varepsilon_i , \text{white noise and } \phi_1, \phi_2, ..., \phi_p$ are constants.

2.7. Moving Average Process (MA($q$))

Let a process $(\varepsilon_i, t \in Z), X_i$ is said autoregressive process of order $q$ (MA($q$)) if

$$X_i = \varepsilon_i + \theta_1\varepsilon_{i-1} + \theta_2\varepsilon_{i-2} + ... + \theta_q\varepsilon_{i-q}$$

Where $\varepsilon_i , \text{white noise and } \theta_1, \theta_2, ..., \theta_q$ are constants.

2.8. Moving Average Processes Autoregressive

A stationary process $X$ has an ARMA representation $(p,q)$ Minimum if it satisfies:

$$\Phi(L)X_i = \Theta(L)\varepsilon_i,$$

$$\Phi(L)X_i = X_i + \phi_1X_{i-1} + ... + \phi_pX_{i-p}$$

$$\Theta(X_i) = \varepsilon_i + \theta_1\varepsilon_{i-1} + ... + \theta_q\varepsilon_{i-q}$$

where $\phi \neq 0, \theta \neq 0$ and $L(X_i) = X_{i-1}$

the polynomials $\Theta$ and $\Phi$ have their upper modules strictly roots to 1.

$\Theta$ and $\Phi$ have not common roots.

$\varepsilon = (\varepsilon_i, t \in Z)$ is a white noise of variance $V(\varepsilon_i) = \sigma^2 \neq 0$

2.9. Process ARIMA

A process $X = (X_i, t \geq 0)$ is a process ARIMA($p,d,q$) [Autoregressive integrated moving average] if it satisfies an equation of type :

$$(1-\sum_{i=1}^{p}\phi_iL^i)(1-L^q)X_i = \delta(1+\sum_{i=1}^{q}\theta_iL^i)\varepsilon_i, t \geq 0$$

where $\delta$ constant $L(X_i) = X_{i-1}$ and $\varepsilon_i$ is white noise.

2.10. Augmented Dickey–Fuller Test

The Augmented Dickey–Fuller test (ADF) is a unit root test of the null hypothesis of unit root (or non stationarity). The ADF test estimated three models:

$$\Delta X_i = \alpha_1 X_{i-1} + \sum_{j=1}^{c} \beta_j \Delta X_{i-j} + \varepsilon_i$$

$$\Delta X_i = \alpha_0 + \alpha_1 X_{i-1} + \sum_{j=1}^{c} \beta_j \Delta X_{i-j} + \varepsilon_i$$
\[ \Delta X_t = \alpha_0 + \alpha_1 X_{t-1} + \sum_{j=1}^{\infty} \beta_j \Delta X_{t-j} + \delta_t + \epsilon_t \]

The null hypothesis of the ADF test is the unit root hypothesis of the variable \( X_t \) is the hypothesis \( H_0 : \alpha_1 = 0 \). The ADF test consists of comparing the estimated value Student \( t \) associated with the parameter \( \alpha_1 \) to the tabulated values of this statistic. The values tabulated for different test however tabulated values of Student test. The critical values of this statistic, ADF denoted in the following, are given by MacKinnon (1996). The null hypothesis \( H_0 \) of non-stationary of the time series is rejected at the 5% level when the observed value of the Student’s \( t \)-test is less than the critical value tabulated by MacKinnon (1996) or \( t_{abs} < ADF_{0.05} \).

2.11. Box Jenkins Methodology

This is the technique for select the most appropriate ARMA or ARIMA model for a given variable. It comprises four steps:

1. Identification of the model, this involves selecting the most appropriate lags for the AR and MA parts, as well as selecting if the variable requires first-differencing to become stationarity. The ACF and PACF are used to identify the best model. (Information criteria can also be used)
2. Estimation, this usually involves the use of a least squares estimation process.
3. Diagnostic testing, which usually is the test for autocorrelation. If this part is failed then the process returns to the identification section and begins again, usually by the addition of extra variables.
4. Forecasting, the ARIMA models are particularly useful for forecasting due to the use of lagged variables.

3. Application

3.1. Graph Series

Through the graph figure, we observed a general upward trend over the period, this means that the series is not stationary.

3.2. Autocorrelation and Autocorrelation Partial
We examine the autocorrelation and partial autocorrelation function in figures 2 and 3 we observed that the estimated autocorrelation parameter decreases exponentially towards zero while that only the first partial autocorrelation parameter is not significant. To confirm the previous results we execute the Dickey-Fuller test and observed in Figure 4 and 5 that the series is not stationary.
When we execute the first differences, we note of figure 6 and 7 that a stationary series.

**Figure 5.** Dickey-Fuller test of time series of wheat import.

**Figure 6.** Dickey-Fuller test of first differences of wheat product.
we note that the series is stationary. We deduce that $d = 1$ in the ARIMA model $(p, d, q)$.

### 3.3. Identification and Selection of Model for Wheat Production Series

Although it appears that each partial autocorrelation parameter after the second parameter is not significantly different from zero at $\alpha = 0.05$ but the autocorrelation function is gradually decreasing towards zero, this may be sufficient evidence that the random process is AR (1). For ensure we test the following statistical hypothesis:

$$
\begin{align*}
H_0 & : \phi_1 = 0; \\
H_A & : \phi_1 \neq 0,
\end{align*}
$$

$SE(\phi_1) = \frac{1}{\sqrt{n}} = \frac{1}{\sqrt{50}} = 0.141$ ,  $Z = \frac{\phi_1 }{ (SE(\phi_1)) } = \frac{0.929}{0.141} = 6.5 > 2$ ,

we deduce that the first partial autocorrelation parameter is not significantly different from zero at $\alpha = 0.05$. We examining the autocorrelation partial parameters, we find that $\phi_k < 0.282 = 2, 3, \ldots, k$ that supports the possibility of using the AR (1) and therefore ARIMA$(1,1,0)$.

For import wheat series we get the same results. And then we compared between ARIMA models with the exponential smoothing(Holt,Brown)and simple regression. We get the following results.

**Figure 8. Comparison of models.**
We take 40 observation of the original series and forecast for the next ten years, then compare between models by MAPE and choose the best model. The results were as follows:

1. Brown’s exponential smoothing model for predict the series of wheat production.
2. The ARIMA(1,1,1) model for predict the series of wheat exports.

3.4. Tests of Residues

We test the best model:

- Graphic residues confidence limits, $ACF, PACF$
- Graphic dispersion of points in parallel form residuals around zero $ACF, PACF$
- Ljung-Box value is significant
- If the model realizes the previous tests, we use it to forecast.

3.5. Forecasting

Then we use the previous models to calculate the forecast from 2011 to 2020 and the results were as follows:

![Figure 9. Forecasting of series of the wheat (product and import).](image9)

![Figure 10. Graph forecasting of series of the wheat (product and import).](image10)
4. Conclusion

Wheat imports will increase from 2.9 million tonnes in 2011 to 4 million tonnes in 2020, where the proportion of imports was 92% in 2010 and it is expect that the wheat import proportion will increase to 94% in 2020 whereas, wheat production will drop by 6% during this decade.

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