On properties of the Wang–Landau algorithm

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Abstract. We review recent advances in the analysis of the Wang–Landau algorithm, which is designed for the direct Monte Carlo estimation of the density of states (DOS). In the case of a discrete energy spectrum, we present an approach based on introducing the transition matrix in the energy space (TMES). The TMES fully describes a random walk in the energy space biased with the Wang–Landau probability. Properties of the TMES can explain some features of the Wang–Landau algorithm, for example, the flatness of the histogram. We show that the Wang–Landau probability with the true DOS generates a Markov process in the energy space and the inverse spectral gap of the TMES can estimate the mixing time of this Markov process. We argue that an efficient implementation of the Wang–Landau algorithm consists of two simulation stages: the original Wang–Landau procedure for the first stage and a $1/t$ modification for the second stage. The mixing time determines the characteristic time for convergence to the true DOS in the second simulation stage. The parameter of the convergence of the estimated DOS to the true DOS is the difference of the largest TMES eigenvalue from unity. The characteristic time of the first stage is the tunneling time, i.e., the time needed for the system to visit all energy levels.

1. Introduction

The history of Monte Carlo simulations begins in the early years of computing. The method was developed in one of the most cited papers in computational physics and chemistry [1], where both the Monte Carlo method and the molecular dynamics approach were introduced. Many algorithms for Monte Carlo simulations have since been developed. In statistical mechanics, different Monte Carlo algorithms are based on different partition function representations.

A general partition function representation is

$$Z = \sum_{\{i\}} e^{-E_i/k_B T},$$

where $E_i$ is the energy of the configuration $\{i\}$ of the system in the phase space, $T$ is the temperature, and $k_B$ is the Boltzmann constant. Representation (1) can be associated, for example, with the Metropolis algorithm [1], which is based on the local updates taking energy changes $\Delta E_{kl} = E_l - E_k$ with moves in the phase space from state $\{k\}$ to state $\{l\}$ into account. The probability of accepting the move is given by the Metropolis probabilities

$$P = \min \left[1, e^{-\Delta E_{kl}/k_B T}\right].$$

Modifications of the Metropolis algorithm are based on variations of local updates, as well as more complicated algorithms, which in any event use local update rules and probabilities (see book [2] for references). All of them use partition function (1) as the basic representation.
A more sophisticated algorithm named the MuMC algorithm (multi-canonical Monte Carlo) is based on another representation of the partition function [3, 4],

\[
Z = \sum_{k=1}^{N_E} g(E_k)W(E_k),
\]

where \(N_E\) is the number of energy levels, \(g(E_k)\) is the number of states with the energy \(E_k\), and \(W(E)\) is an a priori unknown weight function, which is estimated in the simulations. The condition to stop is that all \(g(E_k)W(E_k)\) are approximately equal to each other. It is successfully used in polymer simulations [5].

Another famous example is based on a cluster representation [6] of the Potts model,

\[
Z = \sum_{\text{bonds}} p^b(1-p)^n q^N_c,
\]

where \(p = 1 - \exp(-J/k_BT)\), \(J\) is a constant measured in energy units, \(b\) is the number of bonds connecting spins, \(n\) is the number of bonds not connecting spins, \(q\) is the number of spin components, and \(N_c\) is the number of clusters in the configuration. The cluster representation leads to several efficient algorithms for simulating the Potts model; the two most famous are the Swendsen–Wang cluster algorithm [7] and the Wolf one-cluster algorithm [8].

The abovementioned algorithms are extensively used in simulations. We do not discuss the pros and cons of the algorithms and refer our readers to the book [2].

A common property of all the mentioned algorithms is that simulations depend explicitly on the temperature \(T\). The algorithm that we review and analyze here is quite different: simulations are independent of the temperature.

The Wang–Landau (WL) algorithm is a way to estimate the density of states (DOS) directly [9, 10]. It can be applied to any system with a defined partition function. Its idea is based on representing the partition function as a sum over the energy levels (somewhat similar to representations used for the MuMC algorithm),

\[
Z = \sum_{k=1}^{N_E} g(E_k)e^{-E_k/k_BT}.
\]

It has proved to work quite well for many systems, with applications in different areas of statistical physics and mechanics. There are more than 1500 papers on the application of the algorithm and its improvements. At the same time, not all properties of the algorithm are well understood. For example, it is unclear how auxiliary histogram flatness is related to the convergence of the algorithm and how accuracy of the DOS estimation evolves with the simulation time.

An approach based on constructing the transition matrix in the energy space (TMES) was recently proposed [11]. It answers the above questions and can be used for a deeper analysis of the algorithm and for modifications of the WL algorithm. We present a summary of the approach to the analysis of the WL algorithm. We regard the WL algorithm as a random walk in the energy space as soon as the WL probabilities of moves between energies are based purely on the ratios of the corresponding densities \(g(E)\) of the energy states. We explain some properties of the WL algorithm, including the flatness criteria and the characteristic time scales, and discuss the control parameter for estimating the accuracy of the DOS estimate and for the convergence of the DOS to the true values.

In section 2, we briefly review the WL algorithm. In section 3, we introduce the TMES. In section 4, we define and discuss the characteristics time of the WL algorithm. The discussion in section 5 finishes our review.
2. Wang–Landau algorithm
We briefly describe the WL algorithm here. We take a configuration of the system, compute the energy value $E_k$, randomly choose an update to a new configuration with the energy $E_m$, and accept this configuration with the WL probability

$$\tilde{P}_{wl} = \min\left[1, \frac{\tilde{g}(E_k)}{\tilde{g}(E_m)}\right],$$

where $\tilde{g}(E)$ is the current DOS approximation. The approximation is obtained recursively by multiplying $\tilde{g}(E_m)$ by a factor $f$ at each step of the random walk in the energy space. Each time that the auxiliary histogram $H(E)$ becomes sufficiently flat, the parameter $f$ is modified by taking the square root, $f := \sqrt{f}$. Each histogram value $H(E_m)$ counts the number of moves to the energy level $E_m$. The histogram is filled with zeros after each modification of the refinement parameter $f$. It is convenient to work with the logarithms of the values, $S(E_k) := \ln \tilde{g}(E_k)$ and $F := \ln f$, and to replace the multiplication $\tilde{g}(E_m) := f \cdot \tilde{g}(E_m)$ with the addition $S(E_m) := S(E_m) + F$. At the end of the simulation, the algorithm provides only a relative DOS. Either the total number of states or the number of ground states can be used to determine the absolute DOS.

3. Transition matrix in the energy space
The central idea of the WL algorithms is the WL probability, which generates a random walk in the energy space. We first argue that random walk in the energy space with the WL probability calculated using the true DOS is a Markov chain and satisfies the detailed balance condition \[11\]. The WL probability in this case is given by

$$P_{wl} = \min\left[1, \frac{g(E_k)}{g(E_m)}\right],$$

where $g(E)$ is the true DOS (cf. WL probability \[6\]).

It is useful to consider a TMES whose elements show the frequency of transitions between energy levels during the WL random walk in the energy space \[11\]. Its elements are influenced by both the random process of choosing a new configurational state and the WL probability of accepting the new energy,

$$T(E_k, E_m) = \min\left[1, \frac{g(E_k)}{g(E_m)}\right] P(E_k, E_m),$$

which represents nondiagonal elements of the TMES of the WL random walk in the energy space. Here, $P(E_k, E_m)$ is the probability of one step of the random walk to move from a configuration with the energy $E_k$ to any configuration with the energy $E_m$.

The random walk in the configuration space is a Markov chain. Its invariant distribution is uniform, i.e., the probabilities of all states of the physical system are equal to each other. For any pair of configurations $\Omega_A$ and $\Omega_B$, the probability of an update from $\Omega_A$ to $\Omega_B$ is equal to the probability of an update from $\Omega_B$ to $\Omega_A$. Hence, the detailed balance condition is satisfied. Therefore,

$$g(E_k)P(E_k, E_m) = g(E_m)P(E_m, E_k),$$

where $g(E)$ is the true DOS. It follows from \[8\] and \[9\] that

$$T(E_k, E_m) = T(E_m, E_k).$$

Therefore, the TMES of the WL random walk on the true DOS is a symmetric matrix. Because the matrix is both symmetric and right stochastic, it is also left stochastic. Therefore, the sum
over rows (columns) is equal to unity, and the rates of visiting of all energy levels are equal to each other. The corresponding auxiliary histogram of energy visits in the WL algorithm is indeed flat! (See the discussion in section 5.)

We therefore observe [11] that the flatness of the histogram in the WL algorithm is just the proximity of the corresponding random walk in the energy space to the Markov process. The closer the estimated DOS is to the true DOS, the closer the TMES is to the fully stochastic matrix. This property can be used to connect control of DOS convergence to the property of TMES convergence to the stochastic matrix.

3.1. Exact TMES for 1D Ising model
It is instructive to seek an exact solution of TMES elements. This can be easily done for the 1D Ising model [11]. In the case of a chain of $L$ spins with periodic boundary conditions, the probability to change the energy from $E_k$ to $E_m$ in a WL random move is

$$T(E_k, E_m) = \min \left[ 1, \frac{g(E_k)}{g(E_m)} \right] \sum_{i=0}^{2k} \frac{N_i Q_{E_k \rightarrow E_m}^i}{g(E_k)},$$

(11)

where $k \neq m$. Here, $k$ is the number of couples of domain walls in the configuration, which determines the energy level $E_k = -\sum_{j=1}^{L} \sigma_j \sigma_{j+1} = -L + 4k$, $N_i(k, L)$ is the number of configurations where $i$ domains consist of only one spin and $2k-i$ domains consist of more than one spin, and $Q_{E_k \rightarrow E_m}^i(L)$ is the probability that a single spin flip moves system to the energy $E_m$ from such configurations.

The structure of expression (11) shows that TMES elements are composed of three probabilities: the probability of the particular configuration, the probability that the move in the configuration space changes the system energy to some value, and the WL probability $P_{wl}$ to accept the proposed move between energy levels. It reflects the inside of the WL algorithm and explicitly shows how the combination of choosing the site in the configuration space and of the corresponding change in the phase space generates a random walk in the energy space.

Occupations of energy levels of the chain are expressed in terms of binomial coefficients as $g(E_k) = 2C_{2k}^k$ because there are exactly $C_{2k}^k$ ways to arrange $2k$ domain walls. Therefore, partition function (5) is

$$Z_L = 2 \sum_{k=0}^{L/2} C_{2k}^k e^{(L-4k)/(k_B T)},$$

(12)

and the TMES for the 1D Ising model is

$$T(E_k, E_{k+1}) = T(E_{k+1}, E_k) = \frac{C_{2k}^{2k}}{\max \left( C_{2k}^{2k}, C_{2k}^{2k+2} \right)}.$$  

(13)

The TMES is indeed symmetric and stochastic.

3.2. Estimation of TMES elements during simulation
We estimate the TMES elements in simulations as follows [11]. The auxiliary matrix $U(E_k, E_m)$ is initially filled with zeros. The element $U(E_k, E_m)$ is increased by unity after every WL move from a configuration with the energy $E_k$ to a configuration with the energy $E_m$. During the simulations, we compute the normalized matrix

$$\tilde{T}(E_k, E_m) = U(E_k, E_m) / \bar{H},$$

(14)
where

\[ \tilde{H} = \sum_{k,m} U(E_k, E_m)/N_E. \]  

(15)

The obtained matrix \( \tilde{T} \) is expected to approach the stochastic matrix \( T \) in the final stage of correct calculation.

4. Two characteristic times in WL algorithm

Results of simulations [11, 12] demonstrate that there are two time scales in the WL simulations (although this point is not discussed in the texts). It is well known that the WL algorithm drives the estimated DOS to the vicinity of the true DOS at the beginning of simulations, at least for systems with a discrete energy spectrum and a not very complicated energy landscape. This is a positive feature of the WL algorithm, although still unexplained. The time scale of this stage can be associated with the tunneling time. The second stage is the stage of convergence of the estimated DOS to the true DOS. In this section, we argue that the time scale of the second stage is given by the inverse value of the spectral gap of the TMES.

4.1. Tunneling time

It is known from the beginning of WL simulations [13] that the finite value of the desired histogram flatness leads to saturation of the estimates, and saturation was found for systems with a known DOS. The first stage of the WL algorithm drives the estimated DOS close to the true DOS in the first simulation stage, although not very close. Analysis of Figures 1 and 3–5 in paper [11] shows that there is a characteristic time of the first stage; we suggest that it is the tunneling time of the random walk in the energy space. There are several definitions leading to the same scaling behavior of the tunneling time with system size (more precisely, with the number of energy levels), \( T_t \propto L^z \). A useful practical definition is that it is the time needed for the WL random walk to reach the highest energy level starting from the lowest one [14].

The modification of the WL algorithm called the \( 1/t \)-WL algorithm [15, 16] defines the time when the \( 1/t \) regime of the WL algorithm starts as the time when all energy levels have been visited at least once. Clearly, it is practically the same as the tunneling time.

The stochastic approximation Monte Carlo (SAMC) algorithm [17, 18] does specify how to choose the time \( t_0 \) when the \( 1/t \) regime starts. Our preliminary analysis shows that the optimal choice of \( t_0 \) is indeed the tunneling time.

There is a natural lower limit for the exponent \( z \). It can be understood in terms of the random walk. We first consider the classical problem of the 1D unbiased random walk: the position \( i \) of the random walk changes with equal probability to \( i - 1 \) or \( i + 1 \). The point 0 is the reflecting point of the random walk, and the point \( N \) is the absorbing point. The first-passage time of the random walk is known to scale as \( N^2 \). The number of levels \( N_E \) for the 2D Ising model scales as \( L^2 \), and the number of random walk jumps necessary to cross all energy spectrum hence scales as \( L^4 \). Therefore, \( z = 4 \) is the minimum value for any type of random walk in the energy space of the 2D Ising model.

For a random walk with bias, which is the WL probability \( P_{wl} \), the growth of the tunneling time should be faster, \( z > 4 \). There is a worse message, which can be learned from the properties of a random walk in a random potential. It states that localization of the random walker occurs in one dimension [19]. This probably explains the difficulties in applying the WL algorithm to systems with complex energy landscapes: the random walker can be temporarily trapped near a global minimum of the probability profile in the simulated DOS.

Positions of the vertical dashed line in Figures 1 and 3–5 in paper [11] can be associated with the tunneling time. During the first simulation stage, the effective tunneling time exponent grows from \( z = 4 \) to a value that depends on the investigated system. Reported estimated
exponents for the scaling of the tunneling time are \( z = 4.743(7) \) for the 2D Ising model on a square lattice of linear size \( L \) and approximately \( z = 5.7 \) for the fully frustrated 2D Ising model \([14]\).

4.2. Mixing time
The spectral gap \( G \) of the TMES determines the mixing time of the Markov chain \([20]\):

\[
T_m = \frac{1}{G},
\]

\[
G = \lambda_1 - \lambda_2,
\]

where \( \lambda_1 \) and \( \lambda_2 \) are the two largest eigenvalues of the TMES.

In the second phase of the \( 1/t \)-WL (or SAMC) algorithm, the DOS is very close to the true DOS, and the characteristic time of convergence is therefore just the mixing time \( T_m \) of the Markov chain.

The exact solution for the 1D Ising model \([11]\) can be used to construct the TMES for varying lattice sizes, and fitting to the inverse spectral gap yields an estimate \([12]\) for the mixing time exponent \( T_m \propto L^{2.19} \). Numerically estimating the mixing time for the 2D Ising model \([12]\) leads to the result \( T_m \propto L^{4.37(2)} \).

5. Discussion
Using our approach, we can calculate the normalized histogram \( H = H(E_m)/\sum_m H(E_m) \) from the TMES \( H = \sum_k \tilde{T}(E_k, E_m) \). It is obvious that the histogram flatness condition is equivalent to the property that the matrix \( \tilde{T} \) is close to the stochastic matrix. The histogram flatness in the second simulation stage is closely related to the stochastic properties of the TMES because the estimated DOS is very close to the true DOS.

We have argued that the time \( t_c \) in the \( 1/t \)-WL algorithm \([15, 16]\) and the time \( t_0 \) in the SAMC algorithm \([17, 18]\) is of the order of the tunneling time \([14]\). Therefore, in the first simulation stage, the optimal choice is the original WL algorithm, which drives the estimated DOS close to the true DOS, at least for systems with a not very complicated free energy landscape. In the second simulation stage, the \( 1/t \)-WL algorithm drives the estimated DOS to the true DOS, and the characteristic time is the mixing time \( T_m \). The accuracy of estimating the DOS is given by the deviation of the largest eigenvalue of the estimated TMES from unity \([11]\).

Future research should be done to understand properties of the WL algorithm when applied to more complicated systems and to systems with a continuous energy spectrum. In systems with a complex energy landscape, the variation of the transition matrix elements can be huge, and this can lead to a large increase of the tunneling time. It follows from the theory of a random walk in a random potential \([19]\) that the random walker can be localized in an extremal valley of the potential. It is important to understand under which conditions this can happen with the WL algorithm.

Partitioning a continuous energy spectrum into bins (done in simulations) allows using the TMES approach to analyze simulations. It would be instructive to understand how the bin size influences TMES properties, from which we might understand some properties of simulations, the behavior of the control parameter, and also the tunneling and mixing time values.

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