A Task-Oriented Dialogue Architecture via Transformer Neural Language Models and Symbolic Injection

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Abstract

Recently, transformer language models have been applied to build both task- and non-task-oriented dialogue systems. Although transformers perform well on most of the NLP tasks, they perform poorly on context retrieval and symbolic reasoning. Our work aims to address this limitation by embedding the model in an operational loop that blends both natural language generation and symbolic injection. We evaluated our system on the multi-domain DSTC8 data set and reported joint goal accuracy of 75.8% (ranked among the first half positions), intent accuracy of 97.4% (which is higher than the reported literature), and a 15% improvement for success rate compared to a baseline with no symbolic injection. These promising results suggest that transformer language models can not only generate proper system responses but also symbolic representations that can further be used to enhance the overall quality of the dialogue management as well as serving as scaffolding for complex conversational reasoning.

1 Introduction

Building task-oriented dialogue systems using a conventional pipeline approach, where modules are optimized separately, increases the fine control for dialogue management, but it does not necessarily improve overall performance (Madotto et al., 2018; Liu and Lane, 2018). In contrast, end-to-end neural models employ a straightforward training approach to generating system responses; however, this approach is impractical for goal-oriented dialogues where the system needs to interact with external systems or generate an explanation that supports its decisions (Ham et al., 2020).

Recently, the use of transformer models for building end-to-end dialogue systems has attracted considerable attention (Budzianowski and Vulic, 2019; Yang et al., 2020); however, as far as we know, current approaches operate solely at the text (word) level. We extend this approach to utilize transformer model’s versatility to generate more complex constructs such as symbol representations.

In this paper, we propose a hybrid approach. We first apply a fine-tuned, end-to-end transformer model for multi-domain task-oriented dialogue. Then, during inference, we decouple the execution into expert modules that collaboratively process the content of a common knowledge base (resembling the blackboard architecture (Erman et al., 1980)).

In our experiments, we empirically demonstrate that the transformer model can be fine-tuned to generate not only text from a given input but also symbolic representations (e.g., utterances → dialogue states), manipulate those symbolic representations to generate new ones (e.g., dialogue states → system actions), and generate natural language from symbols (e.g., system actions → system response).

This work led us to a new generic reasoning architecture that leverages the ability of a transformer model to effectively manipulate representations that are mixtures of natural and symbolic language. The result is a simple architecture that uses a uniform representation to blend together dialogue aspects of interpretation, language understanding and generation, and behavior.

2 Method

Architecture: Our system resembles a blackboard architecture (Erman et al., 1980) (Figure 1) with a central memory blackboard and seven modules that implement different steps of the dialogue.

Blackboard: It provides a global memory where pieces of knowledge (history, user’s intents and goals, system actions, etc.) are continuously updated by modules to maintain the dialogue context.

Forget: This module shortens sequence inputs that surpass the maximum limit of tokens that a transformer model can process at a time (in our case, 1,024 tokens for GPT-2). Additional input tokens beyond this limit are truncated, potentially
discarding relevant symbols needed for dialogue processing. Instead, this module discards only the oldest (non-symbolic) elements in dialogue history to keep the input token size within the limit. A more sophisticated component that is more selective in discarding irrelevant information, chunking information, etc., is left as future work.

**Word-level Dialogue State Tracking (DST):** The transformer model takes the dialogue history as input and generates a symbolic dialogue state as output. Since the dialogue state’s symbols (i.e., intent, service, and slot values) can be directly mapped into a service call, the model also outputs a call signature when all the required slots are met. Then, generated symbols are injected into the blackboard.

**Slot-Values Validator:** It checks whether the dialogue state’s symbols were correctly predicted and, if so, they are injected back into the blackboard.

**Service Executor:** given a generated service call, the service executor queries the database and publishes the results on the blackboard.

**Dialogue Policy (POL):** Based on the current context, this module uses the transformer model to generate the next system actions (symbolic constructs that contain acts, slots, and values).

**Natural Language Generation (NLG):** Taking the current context as input, this module uses the transformer model to generate a natural language system response.

Finally, we implemented a control component that orchestrates modules’ activation, allowing them to manipulate back and forth the content of the blackboard (a mixture of multi-domain, multi-intent symbols and natural language – see Alg. 1).

**Fine-tuning:** During training, we fine-tuned a pretrained GPT-2 transformer model using 16,548 dialogues from the DSTC8 dataset described in section 3. To this purpose, we first pre-processed the data by encoding dialogue annotations into sequences of symbolic representation segments (for convenience, we used a Prolog-like syntax), intermixed with natural language. Then, we encoded a set of 9 special tokens, added them to our vocabulary for delimiters and segment indicators, and concatenated the segments as follows:

<bos><usr>...<sys>...<usr>...<dst>...<svc>...<svr>...<sac>...<sut>...<eos>

Where <bos> and <eos> demarcate the beginning and end of an example; <usr> and <sys> represent the history of both user and system utterances; <dst> is the symbolic segment for the dialogue state tracker; <svc> and <svr> correspond to the service call and service result segments, respectively; <sac> are the system actions; and <sut> is the system utterance. Then, the forget module truncated each example as we describe before.

Although we fine-tuned the neural model end-to-end, during the test phase, we broke down the generation process into 3 main steps resembling the execution of a pipelined dialogue system (except that inputs to each module are composite structures of symbols and natural language that are assembled incrementally), as we described above (i.e., DST, POL, and NLG). This architectural breakdown allowed us to add new experts that intercept each module’s outputs, manipulate the corresponding symbols, and inject the updates into the context maintained by the blackboard.

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**Figure 1:** Dialogue System Architecture. Arrows illustrate retrieving/updating information from/to the blackboard. Boxes labeled GPT-2 (DST, POL, NLG) represent the same neural module which is invoked multiple times using different aggregated inputs. Dotted boxes contain symbols and double-line boxes contain natural language.
Example: consider the following snippet of a dialogue from the DSTC8 data set (in json format):

```
"turns": [
  {
    "speaker": "USER",
    "utterance": "I need to take a bus from Las Vegas to San Francisco",
    "user_acts": ...
  },
  {
    "speaker": "SYSTEM",
    "utterance": "sure, I found 3 buses. One departs tomorrow at 10am...",
    "sys_acts": ...
  },
  {
    "service_call": {
      "method": "FindBus",
      "parameters": {
        "from_location": "Las Vegas",
      }
    },
    "service_results": [
      {
        "category": "direct",
        "departure_date": "2019-03-13",
      }
    ]
  }
],

While user/system utterances do not require any change before being encoded as part of the fine-tuning data set (e.g., `<usr>I need to take...`), annotations for dialogue state, service calls and results, and system actions are encoded as Prolog-like compound terms (atoms followed by a comma-separated list of argument terms with variable arity). For instance, the dialogue state contains argument terms for the type of service, user’s intent, and the slot values provided by the user:

```
<dst>
has(
state,[
service(Buses),
intent(FindBus),
slot_values(
  from_location,['Las Vegas'],
)]]
```

Likewise, the symbolic representation of the service call contains argument terms that correspond to mappings between active intent and service method, and slot values and call parameters:

```
<svc>
call(
  Buses, [method(FindBus),
           parameters(
             from_location,['Las Vegas'],
           ...
         )])
```

The service results are encoded as a list of compound terms, as follows:

```
<svr>
results([idx1(slots,[
    category('direct'),
    ...
  ]),
  idx2(slots,[
    ...
 ])}
```

Finally, the system action contains argument terms for the type of dialogue act, the slots, and their corresponding values:

```
<sac>
action(
  act(INFORM),
  slot(departure_time),
  value('10am'))
...
```

3 Experiment Framework

We used the open-source implementation of GPT-2-small transformer model\(^1\) with values for Adam learning rate (5.75e-5), epsilon for Adam optimizer (1e-8), and batch size (4). To generate more coherent text as proposed by Welleck et al. (2020), we set parameters top-p nucleus sampling (0.95) and top-k sampling (50) using grid search.

We utilized the Schema-Guided data set proposed at the Dialogue System Technology Challenge DSTC8-Task2\(^2\). We chose this data set due to: 1) its rich annotations across the whole dialogue pipeline; 2) its size that exceeds the existing dialogue corpora in scale (with over 20K multi-domain, task-oriented dialogues spanning 45 APIs over 20 domains); and 3) it contains a significant amount of dialogues for the transportation domain\(^3\).

In this work, we only tested dialogues containing domains/services shown during training although unseen slot values were allowed (the evaluation of unseen domains is left as future work).

\(^1\)https://github.com/huggingface/transformers

\(^2\)github.com/google-research-datasets/dstc8-schema-guided-dialogue

\(^3\)Our long-term goal is to explore the limits of the proposed hybrid approach in the context of mitigating accessibility barriers when accessing transportation information, e.g., (National Council on Disability, 2015; Steinfeld et al., 2017)
Since the DSTC8 challenge does not provide SQL scripts or equivalent, we reverse-engineered the database results from the data set and implemented our own services database.

We carried out automatic evaluation of our system on 2,361 dialogues using diverse metrics. For DST, we used the metrics provided with the data set, measuring: average goal accuracy (accuracy of predicting the value of a slot correctly), joint goal accuracy (average accuracy of predicting all slot assignments for a turn correctly), active intent accuracy (a fraction of user turns for which the intent was rightly predicted), and requested slot F1 (the macro-averaged F1 score for requested slots over all eligible user turns). In addition, we extended these metrics to measure system actions in a similar way: service call accuracy, joint parameter accuracy, and joint system action accuracy. Also, we used success rate for system performance, and BLEU for fluency of the generated response. Human evaluation is left as future work.

Finally, post hoc, we ran an error analysis that let us identify the kind of error that affected system performance the most, allowing us to build a simple heuristic-based expert that focused on measuring particular kinds of modeling errors to identify areas for improving overall performance.

4 Results

We ran 3 different experiments as follows: Exp$_o$: in order to ensure a fair comparison between the results reported in Rastogi et al. (2020) and our system’s performance results, this experiment uses the ground truth values (oracle) of both user and system utterances. This experiment uses DSTC8 metrics and data, so our results can be compared directly to published results (26 approaches).

Exp$_g$: history is composed of gold user utterances and system utterances generated by our system. As opposed to the oracle experiment above, this experiment captures cascading errors that propagate from earlier steps to later steps in a dialogue.

Exp$_h$: a heuristic-based slot-value validator is added to Exp$_o$ to improve performance. For illustrative purposes only, this experiment measured the impact of mitigating the most critical errors (from error analysis) by manipulating symbols generated by GPT-2 (Exp$_g$). These results precisely identify weaknesses in the current model.

DST Evaluation Results: overall, when compared to the seen-services results reported in Rastogi et al. (2020), our system outperformed other models on intent accuracy (see Table 1). Correctly predicting the intent demonstrates the ability of our system to track user’s intentions and effectively detect domain switches. In addition, if we consider the 26 teams who participated in DSTC8-T4, our system ranks among the first half positions in Exp$_o$ and the first 2/3 positions in Exp$_g$. Finally, Exp$_o$ made an improvement in JGA of 21% and 43% over Exp$_o$ and Exp$_g$, respectively. Details of the heuristic-based module are described in the next section.

Error Analysis: from all the reported metrics, we focused on the results obtained for the Joint Goal Accuracy (JGA) for two reasons: 1) JGA is the primary evaluation metric used for ranking approaches submitted to DSTC8-Task4; and 2) this metric got the lowest scores for Exp$_o$ and Exp$_g$ among all the evaluation metrics (see Table 1).

From the error analysis, we found 3 main kinds of errors that affect JGA: 1) slot names were correctly predicted but slot values were not (10.5% of errors); 2) slot names that appeared in the gold DST but were not predicted by the system (29.1%); and 3) slot names that were predicted but did not appear in the gold DST (60.4%).

Given its significant presence, we focus on the third kind of error. The main causes for this error to occur are: 1) the slot value is predicted but not mentioned by either the user or the system in the dialogue history (over-fitting); and 2) the slot value is mentioned/offered by the system but not accepted by the user (e.g., the system says “There is a direct bus that departs at 9:50 am and costs $36.”, where the slot trip_fare was unsolicited by the user, and then the user says “hmm any buses departing in the

| Approach | JGA | AGA | IA | RSF1 |
|----------|-----|-----|----|------|
| Team 9   | 0.924 | 0.979 | 0.957 | 0.993 |
| Team 10  | 0.920 | 0.978 | 0.956 | 0.847 |
| Exp$_o$  | 0.917 | 0.956 | **0.974** | 0.985 |
| Team 8   | 0.910 | 0.970 | N.A. | 0.847 |
| Team 14  | 0.900 | 0.960 | 0.957 | **0.996** |
| Team 5   | 0.893 | 0.966 | 0.959 | 0.992 |
| Exp$_o$  | 0.758 | 0.939 | **0.974** | 0.985 |
| Exp$_g$  | 0.639 | 0.892 | 0.935 | 0.974 |
| Baseline | 0.412 | 0.677 | 0.950 | 0.995 |

Table 1: Overall results of DST evaluation. JGA: joint goal accuracy, AGA: average goal accuracy, IA: intent accuracy, and RSF1: requested slot F1 score. Due to space constraints, we only include the top-5 results reported in Rastogi et al. (2020).
We implemented a heuristic-based slot-value validator to mitigate the error above. First, we extracted and classified all the slot values from the training data set and store them in a dictionary. Then, a set of heuristic rules based on fuzzy string matching determine whether a slot value is present in the dialogue history by calculating its similarity with the values in the dictionary, fixing the first cause of the error. Next, if the slot value is mentioned only by the system, the value is retained only if the system offered the value at any prior turn (i.e., sys_act: ‘‘OFFER’’) and the user accepted the offered slot value in the next turn (i.e., user_act: ‘‘SELECT’’ | ‘‘AFFIRM’’).

### 5 Related Work

In comparison with traditional pipelined dialogue architectures (Chen et al., 2017; Bohus and Rudnicky, 2009) where NLU (Lee et al., 2019), DST (Williams et al., 2013), and POL/NLG (Wen et al., 2015) modules are optimized separately; our architecture is simpler and less prone to cascading failures due to the folding of multiple NLP tasks into a single transformer model and the exposure of symbolic representation directly to the model.

More recently, pre-trained language models similar to GPT-2 have been used for building end-to-end dialogue systems. Our approach is similar in nature to the work proposed by (Hosseini-Asl et al., 2020; Peng et al., 2020) in that we use a single causal language model to generate all outputs given a dialogue context. However, unlike these approaches, our model not only encodes DST and database results (which shows a labeling cost reduction) but also encodes dialogue policy and service call templates, allowing the system to be able to monitor errors and manipulate symbolic representations at different stages of turn processing.

Similar to other transformer dialog systems (Wolf et al., 2019; Ramadan et al., 2018), our model learns from text; however, our model also learns and generates complex structures that intermix natural and symbolic language. In particular, the work described by Budzianowski and Vulić (2019) and Yang et al. (2020) encodes both belief state and knowledge base constructs into simple text representations and generates text-only outputs. In contrast, our approach encodes, manipulates, and generates more sophisticated knowledge representations, roughly first-order logic constant terms that are implicitly learned and which could be used to communicate with external sources and expert components such as a symbolic reasoner.

Dialogue systems have many similarities to conversational workflow systems. The Virtual Information Officer (Tomasic et al., 2007) required more than thirty individual models performing task classification, entity resolution, and information extraction. Moreover, (Romero et al., 2019) discuss the challenges found when directly translating natural language inputs into symbolic API calls in a service composition system. Both systems would benefit from the architecture and method presented here.

### 6 Conclusions

In this paper, we empirically demonstrated that several capabilities of transformer language models can be leveraged to construct a new dialogue architecture that is more flexible and simpler (resulting in much lower engineering costs) and extensible (allowing symbolic injection and manipulation), while retaining reasonable performance.

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| Appr. | SCA | JPA | JSA | SR | BLEU |
|-------|-----|-----|-----|----|------|
| Exp0  | 0.927 | 0.891 | 0.786 | 82.21% | 2.14 |
| Exp0  | 0.927 | 0.828 | 0.786 | 80.45% | 2.05 |
| Exp0  | 0.873 | 0.703 | 0.748 | 71.25% | 1.63 |

Table 2: Overall results of the System Actions evaluation. SCA: service call accuracy, JPA: joint service call’s parameter accuracy, JSA: joint system action accuracy, and SR: success rate.

‘‘afternoon?’’ only confirming departure_time).
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Algorithm 1 Main Flow of Control
dialogue_control():
Input: signal = start
1: while signal != end do
2: usr_utt ← get_user_input().
3: sys_utt ← process_response(usr_utt).
4: return sys_utt.
5: end while

process_response():
Input: usr_utt
Output: sys_utt
1: bb ← update_blackboard(usr_utt).
2: dst, serv_call ← exec_gpt2("DST", bb).
3: bb ← update_blackboard(dst, serv_call).
4: dst ← validate_slots(bb).
5: bb ← update_blackboard(dst).
6: results ← exec_serv_call(serv_call).
7: bb ← update_blackboard(results).
8: sys_act ← exec_gpt2("POL", bb).
9: bb ← update_blackboard(sys_act).
10: sys_utt ← exec_gpt2("NLG", bb).
11: bb ← update_blackboard(sys_utt).
12: return sys_utt.

exec_gpt2():
Input: id, bb # bb: blackboard
Output: outputs
1: if id = "DST" then
2: input ← encode(bb.hist).
3: else if id = "POL" then
4: input ← encode(bb.hist, bb.dst, bb.results).
5: else if id = "NLG" then
6: input ← encode(bb.hist, bb.dst, bb.results, bb.sys_act).
7: end if
8: if length of input > max_token_length then
9: input ← forget(input). # truncation
10: end if
11: outputs ← predict_gpt2(input).
12: return outputs

update_blackboard():
Input: updates
Output: blackboard
1: for element in updates do
2: update(blackboard, element).
3: end for
4: return blackboard

| Turn | Speaker | Utterance |
|------|---------|-----------|
| 1    | user (gold): | I am in a plan to visit some nice and attractive places for which I need your help. Please search some nice places in LA. |
| 2    | sys (gen): | Do you have any particular category in your mind to search for and which is your selective city to search for the attractions? |
| 3    | sys (gold): | I found 10 places those are most attractive places. Among them Angels Flight Railway is the best one and which is also a Historical Landmark. Hope you like it. |
| 4    | user (gold): | Thank you for your help. |
| 5    | sys (gen): | Have a good day |
| 6    | sys (gen): | Have a great day |

Figure 2: Sample of a multi-domain dialogue. For each gold user utterance, we provide both the gold system utterance and the utterance generated by our system.