All-to-All Encode in Synchronous Systems

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Abstract—We define all-to-all encode, a collective communication operation serving as a primitive in decentralized computation and storage systems. Consider a scenario where every processor initially has a data packet and requires a linear combination of all data packets; the linear combinations are distinct from one processor to another, and are specified by a generator matrix of an error correcting code. We use a linear network model, in which processors transmit linear combinations of their data and previously received packets, and adopt a standard synchronous system setting to analyze its communication cost. We provide a universal algorithm which computes any matrix in this model by only varying intermediate coefficients, and prove its optimality. When the generator matrix is of the Vandermonde or Lagrange type, we further optimize the communication efficiency of the proposed algorithm.

I. INTRODUCTION

The interest in coding for decentralized systems has increased lately, due to emerging applications in blockchains [2–4], sensor networks [5], and the internet of things [6]. In such systems, raw data is generated independently in distributed source nodes, and then encoded and delivered to distributed sink nodes, without a central authority which orchestrates the operation. Examples include encoding for reliable distributed storage (e.g., with a Reed-Solomon or a random code [7]) or for straggler-resilient distributed computation [8]. To study the communication cost of this setting, we focus on the following fundamental collective communication operation.

Definition 1. (All-to-all encode) Consider a distributed system with $K$ processors and no master processor. Every processor $k \in [0, K-1]$ initially possesses an initial packet $x_k \in \mathbb{F}_q$, where $\mathbb{F}_q$ is a finite field with $q$ elements, and obtains a coded packet $\bar{x}_k \in \mathbb{F}_q$ after the communication operation. For $A \in \mathbb{F}_q^{K \times K}$ that is known a priori to all processors, the coded packets are defined as

$$(\bar{x}_0, \ldots, \bar{x}_{K-1}) = (x_0, \ldots, x_{K-1}) \cdot A.$$ 

That is, in an all-to-all encode operation, every node has its own data packet, and wishes to obtain a linear combination of all other packets in the system. An algorithm which successfully achieves all-to-all encode for a given $A$ and every $x_0, \ldots, x_{K-1} \in \mathbb{F}_q$ is said to compute $A$. Computing matrices in this context emerges during the encoding phase in coded decentralized systems, as described shortly.

We adopt the popular communication model of [9], in which the processors are connected by a synchronous network, and messages can pass between any two of them. The system operates in consecutive communication rounds, during each a processor can simultaneously send and receive 1 message, which might contain multiple field elements, through each one of its $p < K$ ports. Inspired by the well-familiar network-coding literature [10, 11], we adopt a linear network model in which processors transmit linear combinations of their own data and previously received packets.

Similar to [9], to capture the communication cost we consider the time to pass a message containing $d$ field elements as $\beta + d \cdot \tau$, where $\beta$ and $\tau$ are system parameters; $\beta$ is the startup time of each message delivery, and $\tau$ refers to the per-element cost. We focus on two measures of communication:

- $C_1$: the number of rounds incurred by the algorithm.
- $C_2$: the total number of field elements transferred in a sequence during the operation. That is, $C_2 = \sum_{t \in [T]} d_t$ in a $T$-round algorithm, where $d_t$ is the size of message containing the largest number of field elements transferred in round $t$, among all ports of all processors.

Our main goal in this paper is optimizing the total communication cost, given by $C_1 \cdot \beta + C_2 \cdot \tau$. Note that since each round includes sending at least one element from one node to another, it follows that $C_2 \geq C_1$.

Clearly, all-to-all encode strongly depends on the properties of the underlying matrix $A$. Moreover, any algorithm for this problem contains two separate components, scheduling and coding scheme. The former determines which processor communicates with which other processors at each round, and the latter determines the coefficients in the linear combinations that processors transmit to one another. Motivated by this distinction, we address the all-to-all encode problem on two levels, the universal and the specific.

On the universal level, we seek a scheduling by which any matrix $A$ could be computed by only varying the coding scheme, i.e., the coefficients in the transmitted packets throughout the algorithm (see Fig. 1). That is, a universal algorithm is a series of instructions which indicate which processor communicates with which other processors at each round, alongside a mechanism that for every given $A$ determines the coefficients that are used by each processor in order to linearly combine previously received packets in each transmission. Universal algorithms are important in cases where the scheduling must either be determined prior to knowing $A$, must apply in several consecutive computations of different matrices, or its simplicity or uniformity are paramount (see Remark 1 below). Further, universal algorithms can be used as primitives in specific algorithms, as we show in the sequel.

On the specific level, we seek both scheduling and coding scheme that are uniquely tailored towards a specific matrix.

$1$Since the operation proceeds in rounds, the largest message in an individual round determines the time duration of this round.
of interest. Clearly, such specific algorithms are important only if they outperform universal ones, since by definition, every universal algorithm subsumes a specific algorithm for all matrices. We are particularly interested in Vandermonde and Lagrange coded systems, respectively.

Finally, we emphasize that in either the specific or the universal setting, neither the scheduling nor the coding scheme depend on the input packets $x_i$, but are exclusively determined by the matrix $A$, that is known to all processors.

**Our Contributions**

- We provide lower bounds for $C_1$ and $C_2$ in a universal algorithm, and propose prepare-and-shoot, a universal algorithm which is optimal in $C_1$ and achieves the lower bound of $C_2$ within a factor of $\sqrt{2}$.
- We propose draw-and-loose, a family of specific algorithms for Vandermonde matrices, which optimize the aforementioned universal algorithm in terms of $C_2$, and provide similar gains for Lagrange matrices.

**Remark 1** (All-to-all encode for decentralized encoding). Apart from its independent interest, the all-to-all encode operation can be used as a primitive in decentralized coded systems. For integers $N$ and $K$ such that $K[N]$ consider a system with $N$ processors in which processor $i \in [K]$ holds $x_i$, where $[K] \triangleq \{1, 2, \ldots, K\}$. Each processor $j \in [N]$ requires a different linear combination of the $x_i$'s, defined by the $j$'th column of a predetermined generator matrix $G \in \mathbb{F}_q^{K \times N}$. The all-to-all encode operation defined herein is applicable to this setting as follows. Partition the processors to $N/K$ subsets of size $K$ each: $\{1, \ldots, K\}, \{(K+1, \ldots, 2K\}$, and so on. First, each processor $i \in [K]$ disseminates its $x_i$ to the processors $\{iK+i,i+1,\ldots,i+K-1\}$ using a simple tree-structured broadcast protocol with $\log_{p+1}(N/K)$ rounds. Then, each subset runs an all-to-all encode operation to compute the respective $K \times K$ submatrix of $G$.

Due space constraints, some proofs, remarks, and illustrative figures are omitted, and given in the full version [1] of this paper.

**II. RELATED WORKS**

Collective communication operations (e.g., one/all-to-all broadcast, one/all-to-all reduce, scatter, gather, etc.) have been studied extensively due to their importance in parallel algorithms, see [13] for a thorough introduction to the topic. Yet, to the best of the authors’ knowledge, an encompassing treatment of the all-to-all encode operation defined above is conspicuously absent from the literature, and several special cases have been scanty studied in recent years.

Jeong et al. [14] studies the decentralized encoding process of an $[N,K]$ systematic code as part of a coded FFT algorithm, but did not study the all-to-all encode problem. Decentralized encoding has also been studied by [7], in which processors pass on a random linear combination of packets to their neighbors, resulting in an MDS code with high probability. Similar problems have been studied in the signal processing literature under the title Graph Signal Processing [12], with a few substantial differences—a graph structure dictates the network connections, communication proceeds in so called graph-shift operations, and computations are over the real or complex fields.

**III. LOWER BOUNDS**

We now propose the lower bounds for $C_1$ and $C_2$ which apply to any universal algorithm. The proof of the following lemma is simple, and given in [1]. The subsequent lemma is proved using counting arguments, and also proved in [1].

**Lemma 1.** Any universal algorithm has $C_1 \geq \left\lceil \log_{p+1} K \right\rceil$.

**Lemma 2.** Any universal algorithm has $C_2 \geq \sqrt{\frac{NK}{p}} - O(1)$.

**Remark 2** (Lower bound for specific algorithms). Clearly, specific algorithms can perform at least as good as universal ones in a any figure of merit; this is since any universal algorithm subsumes specific algorithms for all matrices by definition. Providing bound pertaining to specific algorithms proved to be a difficult task, and several such bounds will appear in future versions of this paper. Yet, it is readily verified that any matrix which contains a non-zero row cannot be computed with $C_1 < \log_{p+1} K$; this is due to the simple fact that a given packet $x_k$ cannot be disseminated to all $K$ processors in less than this many rounds.

**IV. PREPARE AND SHOOT: AN OPTIMAL UNIVERSAL ALGORITHM**

In this section, we propose a universal algorithm that computes any matrix $A$. The proposed algorithm consists of two phases, prepare ($T_p$ rounds) and shoot ($T_s$ rounds). Let $L$ be the maximum integer such that $(p+1)^L < K$. If $L$ is odd let $T_p = L/2 + 1$ and $T_s = L/2$. If $L$ is odd let $T_p = T_s = (L+1)/2$. In either case, the proposed algorithm has the optimal $C_1 = T_s + T_p = \lfloor \log_{p+1} K \rfloor$ (see Lemma 1).
To describe the phases, let $m = (p+1)^{2r}, n = (p+1)^{2r}$, and hence $(n-1)m < K \leq nm$. For every $k \in [0, K-1]$, let

$$R_k^+ = \{k + \ell | \ell \in [0, m-1]\},$$
$$R_k^- = \{k - \ell | \ell \in [0, m-1]\},$$
$$S_k^+ = \{k + \ell \cdot m | \ell \in [0, n-1]\},$$
$$S_k^- = \{k - \ell \cdot m | \ell \in [0, n-1]\}.$$

For convenience of notation, subscripts are computed $\mod m$.

**Prepare phase:** This phase consists of $K$ one-to-$m$ broadcasts happening in parallel; each disseminates $x_k$ from processor $k \in [0, K-1]$ to processors in $R_k^+$. In round $t$, for every $k, r \in [0, K-1], k$ forwards $x_r$ to processor $s$, if present in its internal storage) to processor $k + \rho \cdot \frac{(p+1)^{2r}-1}{p}$ through its $\rho$-th port, for every $\rho \in [p].$

**Lemma 3.** After $C_{1, \text{prepare}} = T_p$ rounds, every processor $k$ has obtained $x_r$ for every $r \in R_k^-$, with $C_{2, \text{prepare}} = \frac{(p+1)^{2r-1}}{p} - 1$.

**Shoot phase:** This phase consists of $K$ $n$-to-one reduce operations happening in parallel, each intended to communicate the correct linear combination of packets to every processor. At the beginning of the phase, every processor defines $n$ variables $w_{k, 1}, w_{k, k+1}, \ldots, w_{k, k+(n-1)m}$ using the information received in the prepare phase (i.e., $x_r$ for $r \in R_k^-$), and the coefficients of the matrix $A$. Intuitively, the variable $w_{k, s}$ contains a linear combination of $x_r$'s at processor $k$, whose final destination is processor $s$; more and more packets will be added to $w_{k, s}$ as the algorithm progresses. Specifically, for $\ell \in [0, n-1]$, initialize $w_{k, k+\ell \cdot m}$ with $x_k \cdot A_{k+\ell \cdot m}$, where $A_{k+\ell \cdot m}$ is the $(k + \ell \cdot m)$-th column of $A$ and the non-zero entries of $x_k \in \mathbb{F}_p^n$ are indexed by elements in $R_k^+$. The goal of this phase is to allow every processor $k$ to obtain $y_k = \sum_{r \in S_k} w_{s, k} = \sum_{r \in S_k} x_s \cdot A_k$, where $w_{s, k}$ refers to the content of that variable at the beginning of this phase.

**Algorithm 1 Shoot Phase (for processor $k$)**

1. Initialize $w_{k, k}, w_{k, k+m}, \ldots, w_{k, k+(n-1)m}$.
2. For $t \leftarrow 1, 2, \ldots, T_p$ do
   3. For $p = 1$ to $p$ do $\triangleright$ As a sender
      4. $s_{\text{out}} = k + \rho m^t$
      5. Send $w_{k, r}$ to processor $s_{\text{out}}$ for every $r \in T_k^{(t)}$
   6. For $p = 1$ to $p$ do $\triangleright$ As a receiver
      7. $s_{\text{in}} = k - \rho m^t$
      8. For $r \in T_k^{(t)}$ do
         9. Receive $w_{s, r}$ from processor $s_{\text{in}}$
   10. Assign $w_{k, r} \leftarrow w_{k, r} + w_{s, r}$
3. Output $w_{k, k}$ as $y_k$

**Lemma 4.** After $C_{1, \text{shoot}} = T_s$ rounds, every processor $k$ has obtained $y_k = \sum_{r \in S_k} x_r \cdot A_k$, with $C_{2, \text{shoot}} = \frac{(p+1)^{2r} - 1}{p}$.

Finally, in the most general case where $K < nm$, some overlap of indices need to be resolved, as some computation results have been summed up twice. In particular, observe that $R_k^+ \cap R_{k+(n-1)m}^+ = [k-nm+1, k]$, which is an empty set only if $nm = K$, as we assumed that $(n-1)m < K \leq nm$, and since indices are computed $\mod K$. Therefore, $y_k = \bar{x}_k + \sum_{r \in [k-nm+1, k]} A_{r, k} x_r$, from which processor $k$ can individually compute $\bar{x}_k$ with no communication, by computing the r.h.s sum and subtracting from $y_k$. This concludes the prepare-and-shoot algorithm, and provides the following by Lemma 3 and Lemma 4.

**Theorem 1.** The prepare-and-shoot algorithm has $C_1 = T_p + T_s = \lfloor \log_{p+1} K \rfloor$ and

$$C_2 = \begin{cases} \frac{2(p+1)(k+1)^2-2}{(p+1)^{2}k^2-2} & \text{if } L \text{ is odd} \\ \frac{(p+1)^{2}k^2-2}{p} & \text{if } L \text{ is even} \end{cases}$$

**Remark 3.** According to Lemma 1, the prepare-and-shoot algorithm is strictly optimal in terms of $C_1$. In addition, since $(p+1)^k < K$, by Lemma 2 the algorithm is asymptotically optimal in terms of $C_2$.

**V. Draw and Loose: An Algorithm for Computing Vandermonde Matrices**

In this section, we shift our attention to specific algorithms for computing Vandermonde matrices, i.e., matrices $A$ that $A_{i,j} = \alpha_j^i$ for $i, j \in [0, K-1]$, where $\alpha_0, \ldots, \alpha_{K-1}$ are distinct elements of $\mathbb{F}_q$. That is, every processor wishes to obtain $\bar{x}_i = f(\alpha_k)$, an evaluation of the polynomial $f(z) = \sum_{k \in [0, K-1]} x_k z^k$ at $\alpha_k$. Inspired by the Fast Fourier Transform algorithm, we show a method that computes the Discrete Fourier Transform (DFT) matrix with the optimal $C_1 = C_2 = \log_{p+1} K$ (see Remark 2). Later, this method serves as a primitive for computation of general Vandermonde matrices,
and brings a significant gain in $C_2$ compared with the universal algorithm described earlier.

A. Computing a DFT Matrix

Assume that $K = (p + 1)^H$ for some positive integer $H$, that $K|q - 1$, and let $\beta = g^{\frac{q - 1}{K}}$ be a primitive $K$-th root of unity, where $g$ is a generator of $\mathbb{F}_q$. A DFT matrix $D_K$ is a Vandermonde one with $\alpha_k = \beta^k$. The proposed method relies on two complete $(p + 1)$-ary trees, a tree of field elements and a tree of polynomials. Each tree is of height $H$, and there are $(p + 1)$ nodes at level $h \in [0, H]$. Therefore, a node at level $h$ can be represented by $h$ digits (using $(p + 1)$-radix).

The tree of field elements is defined as follows. A node at level $h \in [0, H]$ is identified by $h$ digits $k_{h-1}\ldots k_0$ in $[0, p]$ ($k_{h-1}$ being the most significant), and contains the element $\gamma_{k_{h-1}\ldots k_0} \triangleq (\beta^{k_{h-1}(p+1)^{h-1} + \cdots + k_0}(p+1)^{h-h})$. (3)

It is readily verified that for each of the leaves (at level $H$), we have that $\gamma_{k_{h-1}\ldots k_0} = \beta^h$ is the evaluation point of the processor indexed by $k = k_{h-1}(p+1)^{h-1} + \cdots + k_0$. For the root (at level $0$), which is represented by $0$ digits, we have $\gamma = 1$. Indices of sibling nodes differ only in the most significant (leftmost) digit, and index of a parent node is given by omitting the most significant digit of its child. That is, nodes $\gamma_{k_{h-1}\ldots k_0}$, $\gamma_{\rho k_{h-1}\ldots k_0}$ are the children of the same parent node $\gamma_{k_{h-1}\ldots k_0}$. By Equation (3), every child is a distinct $(p + 1)$-th root of its parent, i.e., for every $\rho \in [0, p]$,

$$\gamma_{\rho k_{h-1}\ldots k_0} = \gamma_{k_{h-1}\ldots k_0} \cdot \left(g^{\frac{q - 1}{K}}\right)^\rho K = \gamma_{k_{h-1}\ldots k_0}. \tag{4}$$

The tree of polynomials is defined recursively from the root labelled by $f(z)$. For a non-leaf node labelled by $f_{k_0\ldots k_{h-1}}(z) = b_{0}z^{0} + \cdots + b_{D_{h-1}}z^{D_{h-1}}$ at level $h$, its $\rho$-th child node is defined as

$$f_{k_0\ldots k_{h-1}, \rho}(z) = \sum_{d=\rho \mod (p+1)} d_{\rho}z^{d \rho K}. \tag{5}$$

Therefore, every non-leaf node is a combination of its children evaluated at $z^{p+1}$, i.e.,

$$f_{k_0\ldots k_{h-1}}(z) = \sum_{\rho \in [0, p]} \gamma_{k_0\ldots k_{h-1}, \rho}(z^{p+1}). \tag{6}$$

Note that the leaf node $f_{k_0\ldots k_{H-1}} = x_{k'}$ is the initial packet of the processor indexed by $k' = k_{H-1} + \cdots + k_0(p+1)^{H-1}$. That is, the $(p + 1)$-radix representations of $k = k_{H-1}(p+1)^{H-1} + \cdots + k_0$ (defined above) and $k'$ have reversed order. See Figure 2 for illustrations of both trees.

The proposed algorithm is defined recursively using the above trees. Define $Q(k, t) = f_{k_{H-1}\ldots k_0}(\gamma_{k_{H-1}\ldots k_0})$, and hence every processor $k$ initially has $Q(k, 0) = f_{k_{H-1}\ldots k_0}(\gamma) = f_{k_0\ldots k_{H-1}1}(x_k)$ at the beginning of the algorithm, and wishes to obtain $Q(k, H) = f(\gamma_{k_{H-1}\ldots k_0}) = f(\beta^{H}) = x_k$.

Assume that processor $k$ has $Q(k, t)$ after round $t$, and we show how it can obtain $Q(k, t + 1)$ in one round. By Equation (6) and Equation (3) we have

$$Q(k, t + 1) = \sum_{\rho \in [0, p]} \gamma_{k_0\ldots k_0} \gamma_{k_{h-1}\ldots k_0} \rho Q(k_{\rho}, t), \tag{7}$$

where $k_{\rho}$ is represented by $k_{H-1} \cdots k_{t} + 1\rho k_{t-1} \cdots k_0$ in $(p + 1)$-radix, i.e., it differs from $k$ only in the $t$-th digit. Therefore, the desired $Q(k, t + 1)$ is a linear combination of $Q(k_{0}, t), \ldots, Q(k_{p-1}, t)$. Written in matrix form we have

$$\begin{bmatrix} Q(k_{0}, t + 1) \\ \vdots \\ Q(k_{p-1}, t + 1) \end{bmatrix} = A_{k}^{(t)} \begin{bmatrix} Q(k_{0}, t) \\ \vdots \\ Q(k_{p}, t) \end{bmatrix}, \tag{8}$$

where

$$A_{k}^{(t)} = \begin{bmatrix} \gamma_{0k_{h-1}\ldots k_0}^{p} & \cdots & \gamma_{0k_{h-1}\ldots k_0}^{p} \\ \vdots & \ddots & \vdots \\ \gamma_{pk_{h-1}\ldots k_0}^{p} & \cdots & \gamma_{pk_{h-1}\ldots k_0}^{p} \end{bmatrix}. \tag{9}$$

At round $t + 1$ of the proposed algorithm, every processor $k$ broadcasts $Q(k, t)$ to the $p$ processors having the same index except for the $t$-th digit. In the same round, processor $k$ receives $Q(k_{\rho}, t)$ for every $\rho \in [0, p]$ from these processors (including itself). Then, processor $k$ obtains $Q(k, t + 1)$ by linearly combining the received packets based on Equation (7).

Recall that every processor $k$ has $Q(k, 0)$ at beginning, it obtains the coded packet $\bar{x}_k = Q(k, H)$ after $H$ rounds by repeating the above operation $H$ times. Since exactly one packet is transmitted through each of the $p$ ports during each operation, we have the following theorem.

**Theorem 2.** The above algorithm for computing a DFT matrix has $C_1 = C_2 = H = \log_{p+1} K$, which is strictly optimal.

**Remark 4.** As shown in Remark 2, the proposed algorithm has the strictly optimal $C_1$ value. Further, the $C_2$ value is also optimal, since during each round only 1 packet is communicated through each port.

Next, we emphasize the invertibility of the presented algorithm in the following lemma; this will be useful in the sequel.

**Lemma 5.** The above algorithm can be used to compute the inverse of a DFT matrix, with the same $C_1$ and $C_2$. 

Fig. 2. Illustration of the trees with $K = 9$ and $p = 2$. (Left) The polynomial tree rooted at $f(z) = x_0 + x_1 z + \cdots + x_{8} z^8$. The polynomials in the first level are $f_0(z) = x_0 + x_2 z + x_6 z^3$, $f_1(z) = x_1 + x_4 z + x_7 z^3$, etc. (right) The tree of field elements rooted at $\gamma = 1$, with $\gamma_1 = g^3$, $\gamma_{10} = g$, etc, where $g$ is a generator of $\mathbb{F}_q$, see (3).
B. Generalization

The aforementioned algorithm computes a unique Vandermonde matrix with strictly optimal $C_1$ and $C_2$, but requires that $K = (p+1)^H$ for some $H$ and that $K \parallel q - 1$. In cases where $K \nmid q - 1$ and $K \leq q - 1$, let $H$ be the maximum integer such that $(p+1)^H$ divides $gcd(K, q-1)$, and denote $K = M \cdot (p+1)^H$. We use the above DFT algorithm as a primitive for improved $C_2$ with respect to prepare-and-shoot in the computation of multiple other Vandermonde matrices.

Let $Z = (p+1)^H$, and denote processor $P_{i,j} = j + Z \cdot i$ by two indices $j \in [0, Z - 1]$ and $i \in [0, M - 1]$. We define the evaluation point of processor $P_{i,j}$ as $\alpha_{i,j} = \alpha_i \cdot \beta_j$, where $\alpha_i = g^{r(i)}$ and $\beta_j = g^{\frac{Z - j}{Z}}$, with $g$ being a generator of $\mathbb{F}_q$ and $\varphi$ being any injective map from $[0, M - 1]$ to $[0, (q-1)/Z - 1]$, which exists since $q-1 \geq ZM = K$. In addition, since there exists $\varphi$ for all possible choices for $\varphi$, it follows that the proposed algorithm computes this many different Vandermonde matrices up to permutation of columns.

Recall that the coded packet $\bar{x}_{i,j}$ desired by processor $P_{i,j}$ is an evaluation of $f(z)$ at $\alpha_{i,j}$. Moreover, we have

$$f(\alpha_{i,j}) = \sum_{k=0}^{K-1} x_k \alpha_i^k \beta_j^k = \sum_{\ell=0}^{Z-1} \beta_j^\ell \sum_{k=\ell \mod Z} x_k \alpha_i^k \beta_j^{-\ell}. \quad (10)$$

Since $g^{q-1} = 1$, it follows that $\beta_j^{-\ell} = g^{\frac{Z}{Z} - \frac{j}{Z} \ell} = 1$ whenever $k = \ell \mod Z$, and hence

$$\bar{x}_{i,j} = \sum_{\ell=0}^{Z-1} \beta_j^\ell \sum_{k=\ell \mod Z} x_k \alpha_i^k \beta_j^{-\ell} = \sum_{\ell=0}^{Z-1} f(\alpha_i) \beta_j^\ell \in \mathbb{F}_q[z]. \quad (11)$$

where $f(z) = \sum_{w=0}^{M-1} x_{w,t} z^t + Z \cdot w$. In matrix form,

$$\begin{bmatrix} \bar{x}_{0,0} & \cdots & \bar{x}_{0,Z-1} \\ \vdots & \ddots & \vdots \\ \bar{x}_{M-1,0} & \cdots & \bar{x}_{M-1,Z-1} \end{bmatrix} = F \cdot D_L. \quad (12)$$

where $D_L$ is an $Z \times Z$ DFT matrix, and $F_{i,j} = f_j(\alpha_i)$. Notice that the $j$-th column of $F$ satisfies

$$[f_j(\alpha_0), \ldots, f_j(\alpha_{M-1})]^T = \begin{bmatrix} \alpha_j^0 & \cdots & \alpha_j^{Z-1} \\ \vdots & \ddots & \vdots \\ \alpha_j^{M-1} \end{bmatrix} \begin{bmatrix} \alpha_0^0 & \cdots & \alpha_0^{Z-1} \\ \vdots & \ddots & \vdots \\ \alpha_0^{M-1} \end{bmatrix}. \quad (13)$$

The protocol proceeds in two phases.

**Draw Phase:** The objective of this phase is for every processor $P_{i,j}$ to obtain $f_j(\alpha_i)$. As shown above (13), $f_j(\alpha_0), \ldots, f_j(\alpha_{M-1})$ are given by multiplying $[x_{0,j}, \ldots, x_{M-1,j}]^T$ by a Vandermonde matrix, denoted by $V$, and a diagonal matrix $\text{diag}(\alpha_0^0, \ldots, \alpha_0^{M-1})$. Therefore, this problem can be solved in parallel by $Z$ all-to-all encode operations. For every $j \in [0, Z - 1]$, processors $P_{0,j}, \ldots, P_{M-1,j}$ collectively compute the matrix $V$ using prepare-and-shoot (Section IV). Once completed, every processor $P_{i,j}$ locally multiplies the resulting matrix with $\alpha_i^j$ and obtains $f_j(\alpha_i)$.

**Loose Phase:** As shown in Equation (12), the coded packets $\bar{x}_{i,0}, \ldots, \bar{x}_{i,Z-1}$ are linear combinations, defined by the DFT matrix $D_L$, of the elements $f_0(\alpha_i), \ldots, f_{Z-1}(\alpha_i)$ in the $i$-th row of the matrix $F$. For every $j \in [0, Z - 1]$, processors $P_{i,0}, \ldots, P_{i,Z-1}$ collectively compute $D_L$ using the specialized algorithm a for DFT matrix (Section V-A). After $H$ rounds, every processor $P_{i,j}$ obtains the coded packet $\bar{x}_{i,j}$.

Let $\Psi(M)$ be the $C_2$ in the prepare-and-shoot algorithm to compute any $M \times M$ matrix. Observe that the draw phase takes $C_1 = \lceil \log_{p+1} M \rceil$ rounds and $C_2 = \Psi(M)$ communication, and the loose phase takes $C_1 = H$ rounds and $C_2 = H$ communication. Therefore, we have the following.

**Theorem 3.** The draw-and-loose algorithm can compute $\left(\frac{(q-1)/Z}{M}\right)$ different Vandermonde matrices (up to permutation of columns) with $C_1 = \lceil \log_{p+1} K \rceil$ and $C_2 = H + \Psi(M)$. In particular, if $M \leq p+1$ then $\Psi(M) = 1$, i.e., $C_1 = C_2 = \lceil \log_{p+1} K \rceil$.

**Remark 5.** Note that draw-and-loose can compute any Vandermonde matrix. Yet, significant gains w.r.t prepare-and-shoot will be possible in cases where $H$ is large.

**Lemma 6.** Similar to Lemma 5, the above algorithm can be used to compute the inverse of a Vandermonde matrix, with the same $C_1$ and $C_2$.

**VI. COMPUTING LAGRANGE MATRICES WITH INVERTIBLE DRAW-AND-LOSE**

Lagrange matrices were recently popularized for their use in coded computing [8]. For sets $\{\alpha_i\}_{i=1}^K$ and $\{\omega_i\}_{i=1}^K$, each with $K$ distinct elements in $\mathbb{F}_q$, let $A_{i,j} = \Phi_i(\omega_j)$, where $\Phi_k(z) = \sum_{j \neq k} \frac{z - \omega_j}{\omega_k - \omega_j}$. In this section we sketch an extension of draw-and-loose which computes Lagrange matrices. Evidently, computing a Lagrange matrix can be described as follows. Every processor $k$ has $x_k = f(\omega_k)$; they together form a point-value representation of a polynomial $f(z) = \sum_{k \in [0, K-1]} f_k z^k$ of degree $K - 1$ at $\omega_0, \ldots, \omega_{K-1}$. Every processor $k$ wants $\bar{x}_k = f(\omega_k)$, i.e., another point-value representation of $f(z)$ on $\alpha_0, \ldots, \alpha_{K-1}$.

Therefore, computing a Lagrange matrix is possible by two consecutive computations. First, compute the inverse of a Vandermonde matrix $V(\omega_1, \ldots, \omega_K)$ (Lemma 6) in order to obtain the coefficients of the polynomial $f$. Second, compute the Vandermonde matrix $V(\alpha_1, \ldots, \alpha_K)$ in order to evaluate $f$ at $\alpha_k$ for every $k \in [K]$. This yields the following, in which $C_1(x)$ is the $C_1$ measure of draw-and-loose over $V(x_1, \ldots, x_K)$, for $i \in \{1, 2\}$ and $x \in \{\alpha, \omega\}$.

**Theorem 4.** The above algorithm computes a Lagrange matrix with $C_1 = C_1(\omega) + C_1(\alpha)$ and $C_2 = C_2(\omega) + C_2(\alpha)$.

**VII. DISCUSSION AND FUTURE WORK**

Directions for future work include extending the results to other specific matrices, e.g., Cauchy matrices and Moore matrices, and to further study algorithms and lower bounds for Vandermonde and Lagrange matrices. Also, incorporating computation and storage constraints of processors is an interesting direction for future research.
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