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Authors
Li, Jinkai
Titi, Edriss S

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THE PRIMITIVE EQUATIONS AS THE SMALL ASPECT RATIO LIMIT OF THE NAVIER-STOKES EQUATIONS: RIGOROUS JUSTIFICATION OF THE HYDROSTATIC APPROXIMATION

JINKAI LI AND EDRISS S. TITI

Abstract. An important feature of the planetary oceanic dynamics is that the aspect ratio (the ratio of the depth to horizontal width) is very small. As a result, the hydrostatic approximation (balance), derived by performing the formal small aspect ratio limit to the Navier-Stokes equations, is considered as a fundamental component in the primitive equations of the large-scale ocean. In this paper, we justify rigorously the small aspect ratio limit of the Navier-Stokes equations to the primitive equations. Specifically, we prove that the Navier-Stokes equations, after being scaled appropriately by the small aspect ratio parameter of the physical domain, converge strongly to the primitive equations, globally and uniformly in time, and the convergence rate is of the same order as the aspect ratio parameter. This result validates the hydrostatic approximation for the large-scale oceanic dynamics. Notably, only the weak convergence of this small aspect ratio limit was rigorously justified before.

1. Introduction

In the context of the geophysical flow concerning the large-scale oceanic dynamics, the ratio of the depth to the horizontal width is very small. With the aid of this fact, by scaling the incompressible Navier-Stokes equations with respect to the aspect ratio parameter and taking the small aspect ratio limit, one obtains formally the primitive equations for the large-scale oceanic dynamics. The primitive equations are nothing but the Navier-Stokes equations in which the vertical momentum equation is being replaced by the hydrostatic approximation (balance). Due to its high accuracy for the large-scale oceanic dynamics, the hydrostatic approximation forms a fundamental component in the primitive equations.

The rigorous mathematical justification of the small aspect ratio limit from the Navier-Stokes equations to the primitive equations was studied before by Azérad–Guillén [1], in which the weak convergence was established. Since only the weak convergence was obtained in [1], no convergence rate was provided. The aim of this paper is to show the strong convergence from the Navier-Stokes equations to the
primitive equations, as the aspect ratio parameter goes to zero. Moreover, it will be shown, the strong convergence is actually global and uniform in time, and that the convergence rate is of the same order as the aspect ratio parameter.

Let’s consider the anisotropic Navier-Stokes equations

\[
\partial_t u + (u \cdot \nabla) u - \mu H u - \nu \partial_z^2 u + \nabla p = 0,
\]

in the \( \varepsilon \)-dependent domain \( \Omega_\varepsilon := M \times (-\varepsilon, \varepsilon) \), where \( \varepsilon > 0 \) is a very small parameter, and \( M = (0, L_1) \times (0, L_2) \), for two positive constants \( L_1 \) and \( L_2 \) of order \( O(1) \) with respect to \( \varepsilon \). Here the vector field \( u = (v, w) \), with \( v = (v_1, v_2) \), is the velocity, and the scalar function \( p \) is the pressure. Similar to the case considered in Azérad–Guillén [1], we suppose that the horizontal viscous coefficient \( \mu \) and the vertical viscous coefficient \( \nu \) have different orders, that is \( \mu = O(1) \) and \( \nu = O(\varepsilon^2) \). We suppose, for simplicity, that \( \mu = 1 \) and \( \nu = \varepsilon^2 \). Note that it is necessary to consider the above anisotropic viscosities scaling in the horizontal and vertical directions, so that the Navier-Stokes equations converge to the primitive equations, as the aspect ratio \( \varepsilon \) goes to zero. In fact, for the case when \( (\mu, \nu) = O(1) \), it has been shown in Bresh–Lemoine–Simon [4] that the stationary Navier-Stokes equations converge to a linear system with only vertical dissipation.

We first transform the above anisotropic Navier-Stokes equations, defined on the \( \varepsilon \)-dependent domain \( \Omega_\varepsilon \), to a scaled Navier-Stokes equations defined on a fixed domain. To this end, we introduce the new unknowns

\[
\begin{align*}
  u_\varepsilon &= (v_\varepsilon, w_\varepsilon), \\
  v_\varepsilon(x, y, z, t) &= v(x, y, \varepsilon z, t), \\
  w_\varepsilon(x, y, z, t) &= \frac{1}{\varepsilon} w(x, y, \varepsilon z, t), \\
  p_\varepsilon(x, y, z, t) &= p(x, y, \varepsilon z, t),
\end{align*}
\]

for any \((x, y, z) \in \Omega := M \times (-1, 1)\), and for any \( t \in (0, \infty) \). Then, \( u_\varepsilon = (v_\varepsilon, w_\varepsilon) \) and \( p_\varepsilon \) satisfy the following scaled Navier-Stokes equations (SNS)

\[
(SNS) \quad \begin{cases}
  \partial_t v_\varepsilon + (u_\varepsilon \cdot \nabla) v_\varepsilon - \Delta v_\varepsilon + \nabla H p_\varepsilon = 0, \\
  \nabla H \cdot v_\varepsilon + \partial_z w_\varepsilon = 0, \\
  \varepsilon^2 (\partial_t w_\varepsilon + u_\varepsilon \cdot \nabla w_\varepsilon - \Delta w_\varepsilon) + \partial_z p_\varepsilon = 0,
\end{cases}
\]

defined in the fixed domain \( \Omega \). In addition, we consider the periodic boundary value problem to (SNS), and thus, complement it with the boundary and initial conditions

\[
\begin{align*}
  v_\varepsilon, w_\varepsilon \text{ and } p_\varepsilon \text{ are periodic in } x, y, z, \quad & (1.2) \\
  (v_\varepsilon, w_\varepsilon)|_{t=0} = (v_0, w_0), \quad & (1.3)
\end{align*}
\]

where \((v_0, w_0)\) is given. Furthermore, for simplicity, we suppose in addition that the following symmetry condition holds

\[
\begin{align*}
  v_\varepsilon, w_\varepsilon \text{ and } p_\varepsilon \text{ are even, odd and odd with respect to } z, \text{ respectively.} \quad & (1.4)
\end{align*}
\]

Note that this symmetry condition is preserved by the dynamics of (SNS), in other words, it is automatically satisfied as long as it is satisfied initially. For this reason,
throughout this paper, we always suppose, without any further mention, that the initial horizontal velocity \( v_0 \) satisfies

\[ v_0 \text{ is periodic in } x, y, z, \text{ and is even in } z. \]

Throughout this paper, we used \( \nabla_H \) and \( \Delta_H \) to denote the horizontal gradient and horizontal Laplacian, respectively, that is \( \nabla_H = (\partial_x, \partial_y) \) and \( \Delta_H = \partial_x^2 + \partial_y^2 \). For \( 1 \leq q \leq \infty \), and positive integer \( k \), we denote by \( L^q(\Omega) \) and \( H^k(\Omega) \), respectively, the standard Lebesgue and Sobolev spaces equipped with the standard norms. We use \( L^2(\sigma) \) to denote the space consisting of all divergence-free functions in \( L^2(\Omega) \). Note that since we consider the periodic boundary problems, all the functions considered in this paper are supposed to be periodic in the spatial variables. For simplicity, we use the notation \( \| \cdot \|_q \) and \( \| \cdot \|_{q,M} \) to denote the \( L^q(\Omega) \) and \( L^q(M) \) norms, respectively. Also, we will use the same notation to denote both a space itself and its finite product spaces.

Following the same arguments as those for the standard Navier-Stokes equations, see, e.g., Constantin–Foias [14] and Temam [35], one can prove that, for any initial data \( u_0 = (v_0, w_0) \in L^2(\Omega) \), with \( \nabla \cdot u_0 = 0 \), there is a global weak solution \( u \) to the scaled Navier-Stokes equations (1.1), subject to the boundary and initial conditions (1.2)–(1.3), and if moreover, the initial data \( u_0 \in H^1(\Omega) \), it has a unique local in time strong solution, where the weak solutions are defined as:

**Definition 1.1.** Given \( u_0 = (v_0, w_0) \in L^2(\Omega) \), with \( \nabla \cdot u_0 = 0 \). A space periodic function \( u \) is called a Leray-Hopf weak solution to (SNS), subject to (1.2)–(1.3), if

(i) it has the regularity that

\[ u \in C_w([0, \infty); L^2(\Omega)) \cap L^2_{loc}([0, \infty), H^1(\Omega)), \]

where the subscript \( w \) means weakly continuous,

(ii) satisfies the energy inequality

\[ \|v(t)\|_2^2 + \varepsilon^2\|w(t)\|_2^2 + 2 \int_0^t (\|\nabla v\|_2^2 + \varepsilon^2\|\nabla w\|_2^2)ds \leq \|v_0\|_2^2 + \varepsilon^2\|w_0\|_2^2, \]

for a.e. \( t \in [0, \infty) \),

(iii) and the following integral identity holds

\[ \int_Q \left[ -(v \cdot \partial_t \varphi_H + \varepsilon^2 w \partial_t \varphi_3) + ((u \cdot \nabla)v \cdot \varphi_H + \varepsilon^2 u \cdot \nabla w \varphi_3) + \nabla v : \nabla \varphi_H 
+ \varepsilon^2 \nabla w \cdot \nabla \varphi_3 \right]dxdydzdt = \int_{\Omega} (v_0 \cdot \varphi_H(\cdot, 0) + \varepsilon^2 w_0 \varphi_3(\cdot, 0))dxdydz, \]

for any spatially periodic function \( \varphi = (\varphi_H, \varphi_3) \), with \( \varphi_H = (\varphi_1, \varphi_2) \), such that \( \nabla \cdot \varphi = 0 \) and \( \varphi \in C^\infty(\mathbb{R} \times [0, \infty)) \), where \( Q := \Omega \times (0, \infty) \).
Formally, by taking the limit $\varepsilon \to 0$ in (SNS), one obtains the following primitive equations (PEs)

\[
\begin{align*}
\partial_t v + (u \cdot \nabla)v - \Delta v + \nabla_H p &= 0, \\
\nabla_H \cdot v + \partial_z w &= 0, \\
\partial_z p &= 0,
\end{align*}
\]  

(1.5)

where $u = (v, w)$.

The primitive equations form a corner stone in many global circulation models (GCM) and are used as the fundamental models for the weather prediction, see, e.g., Haltiner–Williams [15], Lewandowski [22], Majda [30], Pedlosky [31], Vallis [36], Washington–Parkinson [37], and Zeng [39]. During the last three decades, since the works Lions–Temam–Wang [27–29] in the 1990s, the primitive equations have been the subject of very intensive mathematical research. The current state of art concerning the primitive equations is that they have global weak solutions (but the general uniqueness is still unclear except for some special cases [3, 19, 25, 34]), see Lions–Temam–Wang [27, 29], and have a unique global strong solution, see Cao–Titi [12], Kukavica–Ziane [20, 21] and Kobelkov [18], and see Hieber–Kashiwabara [16] and Hieber–Hussien–Kashiwabara [17] for some generalizations in the $L^p$ settings.

Some recent developments concerning the global strong solutions to the primitive equations towards the direction of partial dissipation cases are made by Cao–Titi [13] and Cao–Li–Titi [6–10]. Notably, the works [8–10] show that the horizontal viscosity turns out to be more crucial than the vertical one for the global well-posedness, because the results there show that the merely horizontal viscosity is sufficient to guarantee the global well-posedness of strong solutions to the primitive equations, see Li–Titi [23, 24] for some related results and also a recent survey paper by Li–Titi [26] for more information. However, the invicid primitive equations may develop finite time singularities, see Cao et al. [5] and Wong [38].

Despite the important fact that the hydrostatic approximation plays a crucial role in the primitive equations, to the best of our knowledge, the only known mathematical justification of its derivation, via the small aspect ratio limit, is done in [1], where only the weak convergence is proved, and no convergence rate can be deduced there. Historically, the most possible reason that only the weak convergence can be established in [1] is that the global existence of strong solutions to the primitive equations was still an open question at that time. As it will be seen below in the proof of our results, the global well-posedness of strong solutions to the primitive equations plays a fundamental role in the strong convergence of the Navier-Stokes equations to the primitive equations. The aim of this paper is to rigorously justify the strong convergence from (SNS) to (PEs), subject to the same boundary and initial conditions (1.2)–(1.4).

Before stating our main results, it is necessary to clarify some statements on the initial data $u_0 = (v_0, w_0)$. Recall that the solutions considered in this paper satisfy the symmetry condition (1.4), so does the initial datum $u_0 = (v_0, w_0)$. Since $w_0$ is
odd in \( z \), one has \( w_0|_{z=0} = 0 \). Thus, it follows from the incompressibility condition that \( w_0 \) can be uniquely determined as

\[
 w_0(x, y, z) = -\int_0^z \nabla_H \cdot v_0(x, y, z') dz',
\]

for any \((x, y) \in M\) and \( z \in (-1, 1) \). Due to this fact, throughout this paper, concerning the initial velocity \( u_0 \), we only need to specify the horizontal components \( v_0 \), while the vertical component \( w_0 \) is uniquely determined in terms of \( v_0 \) through (1.6).

Now, we are ready to state our main results. In case that the initial data \( v_0 \in H^1(\Omega) \), one can not generally expect that \( w_0 \), determined by (1.6), belongs to \( H^1(\Omega) \). Instead, one should consider \( u_0 = (v_0, w_0) \) as a function in \( L^2(\Omega) \), and thus can obtain a global weak solution \((v_\varepsilon, w_\varepsilon)\) to (SNS) subject to (1.2)–(1.4). For this case, we have the following theorem concerning the strong convergence:

**Theorem 1.1.** Given a periodic function \( v_0 \in H^1(\Omega) \), such that

\[
 \nabla_H \cdot \left( \int_{-1}^1 v_0(x, y, z) dz \right) = 0, \quad \int_{\Omega} v_0(x, y, z) dx dy dz = 0.
\]

Let \((v_\varepsilon, w_\varepsilon)\) and \((v, w)\), respectively, be an arbitrary Leray-Hopf weak solution to (SNS) and the unique global strong solution to (PEs), subject to (1.2)–(1.4). Denote by

\[
 (V_\varepsilon, W_\varepsilon) = (v_\varepsilon - v, w_\varepsilon - w).
\]

Then, we have the a priori estimate

\[
 \sup_{0 \leq t < \infty} \| (V_\varepsilon, \varepsilon W_\varepsilon) \|_2^2(t) + \int_0^\infty \| \nabla(V_\varepsilon, \varepsilon W_\varepsilon) \|_2^2(t) dt \leq C\varepsilon^2 (\| v_0 \|_2^2 + \varepsilon^2 \| w_0 \|_2^2 + 1)^2,
\]

for any \( \varepsilon \in (0, \infty) \), where \( C \) is a positive constant depending only on \( \| v_0 \|_{H^1}, L_1 \), and \( L_2 \). As a consequence, we have the following strong convergences

\[
 (v_\varepsilon, \varepsilon w_\varepsilon) \to (v, 0), \text{ in } L^\infty(0, \infty; L^2(\Omega)),
\]

\[
 (\nabla v_\varepsilon, \varepsilon \nabla w_\varepsilon, w_\varepsilon) \to (\nabla v, 0, w), \text{ in } L^2(0, \infty; L^2(\Omega)),
\]

and the convergence rate is of the order \( O(\varepsilon) \).

If we moreover suppose that \( v_0 \in H^2(\Omega) \), then \( u_0 = (v_0, w_0) \in H^1(\Omega) \), with \( w_0 \) given by (1.6). Then, by the same arguments as for the standard Navier-Stokes equations, see, e.g., [14, 35], one can obtain the unique local (in time) strong solution \((v_\varepsilon, w_\varepsilon)\) to (SNS), subject to (1.2)–(1.4). For this case, we have the following theorem concerning the strong convergence, in which the convergence is stronger than that in Theorem 1.1.
Theorem 1.2. Given a periodic function \( v_0 \in H^2(\Omega) \), such that
\[
\nabla_H \cdot \left( \int_{-1}^{1} v_0(x, y, z) dz \right) = 0, \quad \int_{\Omega} v_0(x, y, z) dx dy dz = 0.
\]
Let \((v_\varepsilon, w_\varepsilon)\) and \((v, w)\), respectively, be the unique local (in time) strong solution to (SNS) and the unique global strong solution to (PEs), subject to (1.2)–(1.4). Denote
\[
(V_\varepsilon, W_\varepsilon) = (v_\varepsilon - v, w_\varepsilon - w).
\]
Then, there is a positive constant \( \varepsilon_0 \) depending only on the initial norm \( \|v_0\|_{H^2}, L_1 \) and \( L_2 \), such that, for any \( \varepsilon \in (0, \varepsilon_0) \), the strong solution \((v_\varepsilon, w_\varepsilon)\) of (SNS) exists globally in time, and the following estimate holds
\[
\sup_{0 \leq t < \infty} \| (V_\varepsilon, \varepsilon W_\varepsilon) \|^2_{H^1} + \int_0^\infty \| \nabla (V_\varepsilon, \varepsilon W_\varepsilon) \|^2_{H^1} dt \leq C\varepsilon^2,
\]
for a constant \( C \) depending only on \( \|v_0\|_{H^2}, L_1 \) and \( L_2 \). As a consequence, the following strong convergences hold
\[
(v_\varepsilon, \varepsilon w_\varepsilon) \to (v, 0), \text{ in } L^\infty(0, \infty; H^1(\Omega)),
\]
\[
(\nabla v_\varepsilon, \varepsilon \nabla w_\varepsilon, w_\varepsilon) \to (\nabla v, 0, w), \text{ in } L^2(0, \infty; H^1(\Omega)),
\]
\[
w_\varepsilon \to w, \text{ in } L^\infty(0, \infty; L^2(\Omega)),
\]
and the convergence rate is of the order \( O(\varepsilon) \).

Remark 1.1. (i) Theorems 1.1 and 1.2 show that the strong convergence of solutions of (SNS) to the corresponding ones of (PEs) is global and uniform in time, and the convergence rate is of the same order to the aspect ratio parameter \( \varepsilon \). Moreover, the smoother the initial data is, the stronger the norms, in which the convergence takes place. This validates mathematically the accuracy of the hydrostatic approximation.

(ii) The assumption \( \int_\Omega v_0 dx dy dz = 0 \) is imposed only for the simplicity of the proof, and the same result still holds for the general case. One can follow the proof presented in this paper, and establish the relevant a priori estimates on \((v_\varepsilon - \bar{v}_0)\) and \((v - \bar{v}_0)\), instead of on \( v_\varepsilon \) and \( v \) themselves, where \( \bar{v}_0 = \int_\Omega v_0 dx dy dz \).

(iii) Generally, if \( v_0 \in H^k \), with \( k \geq 2 \), then one can show that
\[
\sup_{0 \leq t < \infty} \| (V_\varepsilon, \varepsilon W_\varepsilon) \|^2_{H^{k-1}}(t) + \int_0^\infty \| \nabla (V_\varepsilon, \varepsilon W_\varepsilon) \|^2_{H^{k-1}}(t) dt \leq C\varepsilon^2,
\]
for some positive constant \( C \) depending only on \( \|v_0\|_{H^k}, L_1 \) and \( L_2 \). This can be done by carrying out higher energy estimates to the difference system (5.1)–(5.3), below.

(iv) Observing the smoothing effects of the (SNS) and (PEs) to the unique strong solutions, one can also show, in Theorem 1.2 (but not in Theorem 1.1), the strong convergence in stronger norms, away from the initial time, in particular, \((v_\varepsilon, w_\varepsilon) \to (v, w)\), in \( C^k(\bar{\Omega} \times (T, \infty)) \), for any given positive time \( T \) and nonnegative integer \( k \).
The proofs of Theorems 1.1 and 1.2 consist of two main ingredients: the \textit{a priori} estimates on the global strong solution \((v, w)\) to (PEs), and the \textit{a priori} estimates on the difference \(U_\varepsilon = (V_\varepsilon, W_\varepsilon) := (v_\varepsilon, w_\varepsilon) - (v, w)\). Since the convergences stated in the theorems are global and uniform in time, the desired \textit{a priori} estimates mentioned above should be global and uniform in time. To this end, as it has been used in several works before, see, e.g., \cite{6, 10, 12, 13}, we use anisotropic treatments for (PEs) to get the \textit{a priori} estimates: we successively do the basic energy estimate, the \(L^\infty(0, \infty; L^4(\Omega))\) estimate on \(v\), the \(L^\infty(0, \infty; L^2(\Omega))\) estimate on \(\partial_z v, \nabla v\) and \(\Delta v\), respectively, where the hydrostatic approximation plays an essential role for obtaining the \(L^\infty(0, \infty; L^4(\Omega))\) estimate on \(v\), and the Ladyzhenskaya type inequality (see Lemma 2.1, below) is frequently used throughout the whole proof. For the case of Theorem 1.1 the \textit{a priori} estimates up to \(L^\infty(0, \infty; L^2(\Omega))\) of \(\nabla v\) are enough, while for Theorem 1.2 we need one order higher estimates, that is \(L^\infty(0, \infty; L^2(\Omega))\) of \(\Delta v\).

The treatments on the estimates of the difference function \(U_\varepsilon\) are different in the proofs of Theorem 1.1 and Theorem 1.2. For the case of Theorem 1.1 since \((v_\varepsilon, w_\varepsilon)\) is only a Leray-Hopf weak solution, one can not do the subtraction of (SNS) and (PEs) and preform the energy estimates to the system of difference, as it is usually done for the strong solutions. Instead, one can only perform the energy estimates in the framework of the weak solutions. To this end, we adopt the idea, which was introduced in Serrin \cite{33} (see also Bardos et al. \cite{2} and the reference therein) to prove the weak-strong uniqueness of the Navier-Stokes equations; however, the difference in our case is that, the role of “strong solutions” is now played by the solutions of the (PEs), while the role of “weak solutions” is now played by those of (SNS), or intuitively, we are somehow doing the weak-strong uniqueness between two different systems. Precisely, we will: (i) use \((v, w)\) as the testing functions for (SNS); (ii) test (PEs) by \(v_\varepsilon\); (iii) perform the basic energy identity of (PEs); (iv) use the energy inequality for (SNS). Noticing that we end up with (i)–(iv) only one inequality but three equalities, by manipulating these four formulas in a suitable way, we get the desired \textit{a priori} estimates for \(U_\varepsilon\). We remark that this argument can be viewed as the translation, to the language of weak solutions, of the approach of performing energy estimates (for the strong solution) to the system of \(U_\varepsilon\), below.

For the case of Theorem 1.2, since the solutions considered are strong ones, one can get the desired global in time estimates on \(U_\varepsilon\) by using standard energy approach to the system governing \((V_\varepsilon, W_\varepsilon)\), which reads as

\[
\partial_t V_\varepsilon + (U_\varepsilon \cdot \nabla)V_\varepsilon - \Delta V_\varepsilon + \nabla_H P_\varepsilon + (u \cdot \nabla)V_\varepsilon + (U_\varepsilon \cdot \nabla)v = 0,
\]

\[
\nabla_H \cdot V_\varepsilon + \partial_z W_\varepsilon = 0,
\]

\[
\varepsilon^2(\partial_t W_\varepsilon + U_\varepsilon \cdot \nabla W_\varepsilon - \Delta W_\varepsilon + U_\varepsilon \cdot \nabla w + u \cdot \nabla W_\varepsilon) + \partial_z P_\varepsilon = -\varepsilon^2(\partial_t w + u \cdot \nabla w - \Delta w).
\]

However, we will have to introduce some new ideas described in the following steps. First, since the initial value of \((V_\varepsilon, W_\varepsilon)\) vanishes, and there is a small coefficient \(\varepsilon^2\)
in the front of the “external forcing” terms in right-hand side of the above system, one can perform the energy approach and take advantage of the smallness argument to get the desired a priori estimate on \((V_\varepsilon, W_\varepsilon)\), and as a result, the strong solution \((v_\varepsilon, w_\varepsilon)\) can be extended to be a global one, for small \(\varepsilon\). Second, one has to observe that, when performing the energy estimates to the horizontal momentum equations for \(V_\varepsilon\), no more information about \(W_\varepsilon\) can be used other than that comes from the incompressibility condition; in other words, the term \(W_\varepsilon \partial_z V_\varepsilon\), in the horizontal momentum equations for \(V_\varepsilon\), can be only dealt with by expressing \(W_\varepsilon\) as
\[
W_\varepsilon(x, y, z, t) = - \int_0^z \nabla_H \cdot V_\varepsilon(x, y, z', t) dz'.
\]
This is because the explicit dynamical information of \(W_\varepsilon\), which comes from the vertical momentum equation, is always tied up with the parameter \(\varepsilon\) (see Propositions 4.2, 5.1 and 5.2, below), which will finally go to zero, in other words, the vertical momentum equation for \(W_\varepsilon\) provides no \(\varepsilon\)-independent dynamical information of \(W_\varepsilon\). After achieving the desired a priori estimates, the strong convergences follow immediately.

Throughout this paper, we always suppose, as it is stated in Theorem 1.1 and Theorem 1.2, that the initial data \(v_0\) satisfies
\[
\int_\Omega v_0(x, y, z) dx dy dz = 0.
\]
As a result, by integrating the horizontal momentum equations of the (SNS) and (PEs) over \(\Omega\), respectively, one has
\[
\int_\Omega v_\varepsilon(x, y, z, t) dx dy dz = \int_\Omega v(x, y, z, t) dx dy dz = 0.
\]
Noticing that
\[
w_\varepsilon(x, y, z, t) = - \int_0^z \nabla_H \cdot v_\varepsilon dz', \quad w(x, y, z, t) = - \int_0^z \nabla_H \cdot v dz',
\]
for any \((x, y, z) \in \Omega\), we have
\[
\int_\Omega w_\varepsilon(x, y, z, t) dx dy dz = \int_\Omega w(x, y, z, t) dx dy dz = 0.
\]
Therefore, all the velocities encountered in this paper are of average zero. We will always, without any further mentions, recall this fact before using the Poincaré inequality, in the rest of this paper.

The rest of this paper is arranged as follows: some preliminary lemmas are collected in the next section, section 2. In section 3 we carry out the a priori estimates on the strong solutions to (PEs), while the proofs of Theorem 1.1 and Theorem 1.2 are given in section 4 and section 5, respectively.

Throughout this paper, if not specified, the \(C\) denotes a general positive constant depending only on \(L_1\) and \(L_2\).
2. Preliminaries

In this section, we state some Ladyzhenskaya-type inequalities for some kinds of three dimensional integrals, which will be frequently used in the rest of this paper.

**Lemma 2.1** (see [H]). The following inequalities hold true

\[
\int_M \left( \int_{-1}^1 f(x,y,z)dz \right) \left( \int_{-1}^1 g(x,y,z)h(x,y,z)dz \right) dxdy \leq C \|f\|_2^{1/2} \left( \|f\|_2^{1/2} + \|\nabla_H f\|_2^{1/2} \right) \|g\|_2 \|h\|_2 \left( \|h\|_2^{1/2} + \|\nabla_H h\|_2^{1/2} \right),
\]

and

\[
\int_M \left( \int_{-1}^1 f(x,y,z)dz \right) \left( \int_{-1}^1 g(x,y,z)h(x,y,z)dz \right) dxdy \leq C \|f\|_2 \|g\|_2^{1/2} \left( \|g\|_2^{1/2} + \|\nabla_H g\|_2^{1/2} \right) \|h\|_2 \left( \|h\|_2^{1/2} + \|\nabla_H h\|_2^{1/2} \right),
\]

for every \( f, g, h \) such that the right-hand sides make sense and are finite, where \( C \) is a positive constant depending only on \( L_1 \) and \( L_2 \).

As a corollary, we prove the following:

**Lemma 2.2.** Let \( \varphi = (\varphi_1, \varphi_2, \varphi_3), \phi \) and \( \psi \) be periodic functions with basic domain \( \Omega \). Suppose that \( \varphi \in H^1(\Omega) \), with \( \nabla \cdot \varphi = 0 \) in \( \Omega \), \( \int_{\Omega} \varphi dxdydz = 0 \), and \( \varphi_3 |_{z=0} = 0 \), \( \nabla \varphi \in H^1(\Omega) \) and \( \psi \in L^2(\Omega) \). Denote by \( \varphi_H = (\varphi_1, \varphi_2) \) the horizontal components of the function \( \varphi \). Then, we have the following estimate

\[
\left| \int_\Omega (\varphi \cdot \nabla \phi) \psi dxdydz \right| \leq C \|\nabla \varphi_H\|_2^{1/2} \|\Delta \varphi_H\|_2^{1/2} \|\nabla \phi\|_2^{1/2} \|\Delta \phi\|_2^{1/2} \|\psi\|_2,
\]

where \( C \) is a positive constant depending only on \( L_1 \) and \( L_2 \).

**Proof.** Since \( \varphi_3(x,y,0) = 0 \) and \( \nabla \cdot \varphi = 0 \), one has

\[
\varphi_3(x,y,z) = \int_0^z \partial_z \varphi_3(x,y,z')dz' = - \int_0^z \nabla_H \cdot \varphi_h(x,y,z')dz',
\]

from which, by the Hölder inequality, we have

\[
\|\varphi_3\|_2, \|\partial_z \varphi_3\|_2 \leq \|\nabla_H \varphi_H\|_2, \quad \|\nabla_H \varphi_3\|_2, \|\nabla_H \partial_z \varphi_3\|_2 \leq \|\Delta_H \varphi_H\|_2,
\]

and thus, recalling that \( \int_{\Omega} \varphi dxdydz = 0 \), it follows from the Poincaré inequality that

\[
\|\varphi\|_2 \leq \|\varphi_H\|_2 + \|\varphi_3\|_2 \leq \|\varphi_H\|_2 + \|\nabla_H \varphi_H\|_2 \leq C \|\nabla \varphi_H\|_2, \quad (2.1)
\]

\[
\|\nabla_H \varphi\|_2 \leq \|\nabla_H \varphi_H\|_2 + \|\nabla_H \varphi_3\|_2 \leq \|\nabla_H \varphi_H\|_2 + \|\Delta_H \varphi_H\|_2 \leq C \|\Delta \varphi_H\|_2, \quad (2.2)
\]

\[
\|\partial_z \varphi\|_2 \leq \|\partial_z \varphi_H\|_2 + \|\partial_z \varphi_3\|_2 \leq \|\partial_z \varphi_H\|_2 + \|\nabla_H \varphi_H\|_2 \leq C \|\nabla \varphi_H\|_2, \quad (2.3)
\]

\[
\|\partial_z \nabla_H \varphi\|_2 \leq \|\partial_z \nabla_H \varphi_H\|_2 + \|\partial_z \nabla_H \varphi_3\|_2
\]
\[ \leq \| \partial_z \nabla_H \varphi_H \|_2 + \| \Delta_H \varphi_H \|_2 \leq C \| \Delta \varphi \|_2. \]

Therefore, it follows from Lemma 2.1 and the Poincaré inequality that

\[ \left| \int_{\Omega} (\varphi \cdot \nabla \psi) dxdydz \right| \leq \int_M \left( \int_{-1}^1 (|\varphi| + |\partial_z \varphi|)dz \right) \left( \int_{-1}^1 |\nabla \psi| dz \right) dxdy \]

\[ \leq C \left[ \| \varphi \|_2 \left( \| \varphi \|_2 + \| \nabla_H \varphi \|_2 \right) \right]^\frac{1}{2} + \| \partial_z \varphi \|_2 \left( \| \partial_z \varphi \|_2 + \| \nabla_H \partial_z \varphi \|_2 \right) \]
\[ \times \| \nabla \psi \|_2 \left( \| \nabla \psi \|_2 + \| \nabla_H \nabla \psi \|_2 \right)^\frac{1}{2} \| \psi \|_2 \]

\[ \leq C \| \nabla \varphi_H \|_2 \| \Delta \varphi_H \|_2 \| \nabla \psi \|_2 \left( \| \nabla \psi \|_2 + \| \nabla_H \nabla \psi \|_2 \right)^\frac{1}{2} \| \psi \|_2, \]

proving the conclusion. \qed

3. A priori estimates on the primitive equations

As it was mentioned in the introduction, the global well-posedness (more precisely, the a priori estimates) of strong solutions to (PEs) plays a fundamental role in the proof of the strong convergences of the small aspect ratio limit of the Navier-Stoke equations to the primitive equations. In this section, we carry out the a priori estimates on the strong solutions to the primitive equations.

We rewrite the primitive equations (1.5) as

\[ \partial_t v + (v \cdot \nabla_H) v + w \partial_z v - \Delta v + \nabla_H p(x, y, t) = 0, \]

\[ \nabla_H \cdot v + \partial_z w = 0. \]

(3.1)

(3.2)

Note that, we have used here the fact that, due to the identity \( \partial_z p = 0 \) in (1.5), the pressure depends only on two spatial variables \( x \) and \( y \).

By the \( H^1 \) theory of the primitive equations, see [12], for any \( H^1 \) initial data \( v_0 \), such that

\[ \nabla_H \cdot \left( \int_{-1}^1 v_0(x, y, z) dz \right) = 0, \quad \text{for all} \ (x, y) \in M, \]

there is a unique global strong solution \( v \) to the primitive equations (3.1)–(3.2), subject to (1.2)–(1.4), such that \( v \in C([0, \infty); H^1(\Omega)) \cap L^2_{\text{loc}}([0, \infty); H^2(\Omega)) \) and \( \partial_t v \in L^2_{\text{loc}}([0, \infty); L^2(\Omega)) \). Generally, if the initial data \( v_0 \) has more regularities, then the solution \( v \) will have the corresponding higher regularities, see, e.g., Petcu–Wirotsoetisno [32]. Moreover, due to the smoothing effect of the primitive equations to the strong solutions, one can show that \( v \) is smooth away from the initial time, see Corollary 3.1 in Li–Titi [25]. This fact guarantees the validity of our arguments in the following proofs.
We are going to do several a priori estimates on $v$, the unique global strong solution to the primitive equations (3.1)–(3.2), subject to the boundary and initial conditions (1.2)–(1.4), with initial data $v_0$.

Let's start with the following basic energy estimate.

**Proposition 3.1** (Basic energy estimate). Suppose that $v_0 \in H^1(\Omega)$. Then, we have

$$
\|v(t)\|_2^2 + 2 \int_0^t \|\nabla v\|_2^2 ds = \|v_0\|_2^2,
$$

and

$$
\|v(t)\|_2^2 \leq e^{-2\lambda_1 t} \|v_0\|_2^2,
$$

for any $t \in [0, \infty)$, where $\lambda_1 > 0$ is the first eigenvalue of the following eigenvalue problem

$$
-\Delta \phi = \lambda \phi, \quad \int_\Omega \phi dxdydz = 0, \quad \phi \text{ is periodic}.
$$

**Proof.** Taking the $L^2(\Omega)$ inner product to equation (3.1) with $v$, then it follows from integration by parts that

$$
\frac{1}{2} \frac{d}{dt} \|v\|_2^2 + \|\nabla v\|_2^2 = 0,
$$

from which, integrating in $t$ yields the first conclusion. By the Poincaré inequality, one has $\|\nabla v\|_2^2 \geq \lambda_1 \|v\|_2^2$, and thus we have

$$
\frac{d}{dt} \|v\|_2^2 + 2\lambda_1 \|v\|_2^2 \leq 0,
$$

from which, by the Gronwall inequality, the second conclusion follows.

Since the high order estimates depend on the $L^\infty(0, \infty; L^4(\Omega))$ estimate of $v$, we first prove this estimate in the following lemma.

**Proposition 3.2** ($L^\infty(0, \infty; L^4(\Omega))$ estimate for $v$). Suppose that $v_0 \in H^1(\Omega)$. Then, we have the following estimate

$$
\sup_{0 \leq s \leq t} \|v\|_4^4(s) + 2 \int_0^t \|\nabla v\|_2^2(s) ds \leq e^{C(\|v_0\|_4^4 + \|v_0\|_2^2)} \|v_0\|_4^4,
$$

for any $t \in [0, \infty)$, where $C$ is a positive constant depending only on $L_1$ and $L_2$.

**Proof.** Multiplying equation (3.1) by $|v|^2 v$, integrating the resultant over $\Omega$, then it follows from integration by parts that

$$
\frac{1}{4} \frac{d}{dt} \|v\|_4^4 + \int_\Omega |v|^2 (|\nabla v|^2 + 2|\nabla |v||^2) dxdydz = -\int_\Omega |v|^2 v \cdot \nabla_{HP}(x,y,t) dxdydz.
$$

By Lemma 2.1 and using the Poincaré inequality, we have

$$
-\int_\Omega |v|^2 v \cdot \nabla_{HP}(x,y,t) dxdydz
$$
Applying the Gronwall inequality to the above inequality, it follows from the Hölder elliptic estimates, we have
\[ \leq \int_M \left( \int_{-1}^1 |v|^3 dz \right) |\nabla_H p(x, y, t)| dxdy \]
\[ \leq C \|\nabla_H p\|_{2,M} \|v\|_4^2 \left( \|v\|_4^2 + \|\nabla_H |v|^2\|_2 \right)^\frac{1}{2} \|v\|_2 \|\nabla v\|_2 \]
\[ \leq C \|\nabla_H p\|_{2,M} \|v\|_4 \left( \|v\|_4^2 + \|\nabla_H |v|^2\|_2 \right)^\frac{1}{2} \|v\|_2^\frac{1}{2} \|\nabla v\|_2^\frac{1}{2}. \] (3.4)

Applying the operator \( \int_{-1}^1 \text{div}_H (\cdot) dz \) to equation (3.1), one obtains
\[ -\Delta_H p(x, y, t) = \int_{-1}^1 \nabla_H \cdot \left( \nabla_H \cdot (v(x, y, z, t) \otimes v(x, y, z, t)) \right) dz. \]

Note that \( p \) can be uniquely determined by requiring \( \int_\Omega p dx dy = 0 \), and thus, by the elliptic estimates, we have
\[ \|\nabla_H p\|_{2,M} \leq C \left\| \int_{-1}^1 \nabla_H \cdot \left( \nabla_H \cdot (v \otimes v) \right) \right\|_{2,M} \leq C \|v\|_4 \|\nabla_H v\|_2. \]

Thanks to the above estimate, it follows from (3.4) and the Young inequality that
\[ -\int_\Omega |v|^2 v \cdot \nabla_H p(x, y, t) dx dy \]
\[ \leq C \|v\|_4 \|\nabla_H v\|_2 \|v\|_4 \left( \|v\|_4^2 + \|\nabla_H |v|^2\|_2 \right)^\frac{1}{2} \|v\|_2 \|\nabla v\|_2 \]
\[ \leq C(\|v\|_4 \|\nabla_H v\|_2 + \|v\|_4 \|\nabla_H v\|_2 + \|v\|_4 \|\nabla v\|_2) \|v\|_4 \]
\[ \leq \frac{1}{2} \|v\|_2 \|\nabla v\|_2 + C(\|v\|_2 \|\nabla v\|_2 + \|v\|_2 \|\nabla v\|_2) \|v\|_4, \]

which, substituted into (3.3), gives
\[ \frac{d}{dt} \|v\|_4^4 + 2 \|v\|_2 \|\nabla v\|_2^2 \leq C(\|v\|_2 \|\nabla v\|_2 + \|v\|_2 \|\nabla v\|_2) \|v\|_4^4. \]

Applying the Gronwall inequality to the above inequality, it follows from the Hölder inequality and Proposition 3.1 that
\[ \sup_{0 \leq s \leq t} \|v\|_4^4(s) + 2 \int_0^t \|v\|_2 \|\nabla v\|_2^2 ds \leq e^{C \int_0^t \left( f_0^2 \|\nabla v\|_2 + f_0^2 \|\nabla v\|_2^2 \right) ds} \|v_0\|_4^4 \]
\[ \leq e^{C \left( \left( f_0^2 \|\nabla v\|_2 ds \right)^{1/2} + f_0^2 \|\nabla v\|_2 ds \right)^{1/2} + f_0^2 \|\nabla v\|_2 ds} \|v_0\|_4^4 \]
\[ \leq \exp \{ C(t^{1/2} e^{-\lambda t} \|v_0\|_2^2 + \|v_0\|_4^2) \} \|v_0\|_4^4 \]
\[ \leq \exp \{ C(\|v_0\|_2^2 + \|v_0\|_4^2) \} \|v_0\|_4^4, \]
proving the conclusion. \( \square \)

Next, we work on the \( L^\infty(0, \infty; L^2(\Omega)) \) estimate for \( \partial_x v \).
Proposition 3.3 \((L^\infty(0, \infty; L^2(\Omega))\) estimate on \(\partial_z v\)). Suppose that \(v_0 \in H^1(\Omega)\). Then, we have the following estimate
\[
\sup_{0 \leq s \leq t} \|\partial_z v\|_{L^2}^2(s) + \int_0^t \|\nabla \partial_z v\|_{L^2}^2 ds \leq \|\partial_z v_0\|_{L^2}^2 + C\|v_0\|_{L^4}^2 \|v_0\|_{L^d}^8 e^{C(\|v_0\|_{L^2}^2 + \|v_0\|_{L^d}^2)},
\]
for any \(t \in [0, \infty)\), where \(C\) is a positive constant depending only on \(L_1\) and \(L_2\).

Proof. Taking the \(L^2(\Omega)\) inner product of equation (3.1) with \(-\partial_z^2 v\), it follows from integration by parts that
\[
\frac{1}{2} \frac{d}{dt} \|\partial_z v\|_{L^2}^2 + \|\nabla \partial_z v\|_{L^2}^2 = -\int_\Omega \left[ (\partial_z v \cdot \nabla H) v - \nabla H \cdot v \partial_z v \right] \partial_z v dxdydz \\
\leq 4 \int_\Omega |\partial_z v| |\nabla H \partial_z v| |v| dxdydz.
\]
By the Hölder, Sobolev, Poincaré and Young inequalities, we have
\[
4 \int_\Omega |\partial_z v| |\nabla H \partial_z v| |v| dxdydz \leq 4 \|\partial_z v\|_{L^4} \|v\|_{L^4} \|\nabla H \partial_z v\|_{L^2} \\
\leq C \|v\|_{L^4} \|\partial_z v\|_{L^2} \|\nabla \partial_z v\|_{L^2} \leq \frac{1}{2} \|\nabla \partial_z v\|_{L^2}^2 + C \|v\|_{L^4}^2 \|\partial_z v\|_{L^2}^2.
\]
Therefore, one obtains
\[
\frac{d}{dt} \|\partial_z v\|_{L^2}^2 + \|\nabla \partial_z v\|_{L^2}^2 \leq C \|v\|_{L^4}^2 \|\partial_z v\|_{L^2}^2,
\]
from which, integrating in \(t\) and using Propositions 3.1–3.2, we have
\[
\sup_{0 \leq s \leq t} \|\partial_z v\|_{L^2}^2(s) + \int_0^t \|\nabla \partial_z v\|_{L^2}^2 ds \leq \|\partial_z v_0\|_{L^2}^2 + C \sup_{0 \leq s \leq t} \|v\|_{L^4}^2 \int_0^t \|\partial_z v\|_{L^2}^2 ds \\
\leq \|\partial_z v_0\|_{L^2}^2 + C \|v_0\|_{L^2}^2 \|v_0\|_{L^d}^8 e^{C(\|v_0\|_{L^2}^2 + \|v_0\|_{L^d}^2)},
\]
proving the conclusion. \(\square\)

Then, we can establish the \(L^\infty(0, \infty; H^1(\Omega))\) estimate on \(v\).

Proposition 3.4 (First order energy estimate). Suppose that \(v_0 \in H^1(\Omega)\). Then, we have the following estimate
\[
\sup_{0 \leq s \leq t} \|\nabla v\|_{L^2}^2(s) + \frac{1}{2} \int_0^t (\|\Delta v\|_{L^2}^2 + \|\partial_t v\|_{L^2}^2) ds \\
\leq \|\nabla v_0\|_{L^2}^2 \exp \left\{ C \left( \|v_0\|_{L^2}^4 + \|\partial_z v_0\|_{L^2}^2 + \|v_0\|_{L^2}^2 \|v_0\|_{L^d}^8 \right. \right. \\
\left. \left. + \|v_0\|_{L^2}^4 \|v_0\|_{L^d}^8 e^{C(\|v_0\|_{L^2}^2 + \|v_0\|_{L^d}^2)} \right) \right\},
\]
for any \(t \in [0, \infty)\), where \(C\) is a positive constant depending only on \(L_1\) and \(L_2\).
Proof. Taking the $L^2(\Omega)$ inner product to equation (3.1) with $\partial_t v - \Delta v$, then it follows from integration by parts that
\[
\frac{d}{dt} \| \nabla v \|_2^2 + \| \Delta v \|_2^2 + \| \partial_t v \|_2^2 = \int_{\Omega} [(v \cdot \nabla_H) v + w \partial_z v] \cdot (\Delta v - \partial_t v) dxdydz. \tag{3.5}
\]
By Lemma 2.1 it follows from the Poincaré and Young inequalities that
\[
\int_{\Omega} (v \cdot \nabla_H) v \cdot (\Delta v - \partial_t v) dxdydz \\
\leq \int_{M} \left( \int_{-1}^{1} (|v| + |\partial_z v|) dz \right) \left( \int_{-1}^{1} |\nabla_H v|(|\Delta v| + |\partial_t v|) dz \right) dxdy \\
\leq C \left[ \|v\|_{L^2}^\frac{3}{2} (\|v\|_2 + \|\nabla_H v\|_2) \frac{3}{2} + \|\partial_z v\|_2 \|\nabla_H \partial_z v\|_2 \right] \\
\times \|\nabla_H v\|_2^\frac{3}{2} (\|\nabla_H v\|_2 + \|\nabla^2_H v\|_2) \frac{3}{2} (\|\Delta v\|_2 + \|\partial_t v\|_2) \\
\leq C (\|v\|_{L^2}^\frac{3}{2} \|\nabla v\|_2^\frac{3}{2} + \|\partial_z v\|_2 \|\nabla \partial_z v\|_2^\frac{3}{2} \|\nabla_H \partial_z v\|_2 \frac{3}{2} (\|\Delta v\|_2 + \|\partial_t v\|_2) \\
\leq \frac{1}{4} (\|\Delta v\|_2^2 + \|\partial_t v\|_2^2) + C (\|v\|_{L^2}^2 \|\nabla v\|_2^2 + \|\partial_z v\|_2^2 \|\nabla \partial_z v\|_2^2) \|\nabla v\|_2^2. \tag{3.6}
\]
Since $w$ is odd in $z$, it has $w|_{z=0} = 0$, and thus
\[
w(x, y, z, t) = \int_{0}^{z} \partial_z w(x, y, z', t)dz' = -\int_{0}^{z} \nabla_H \cdot v(x, y, z', t)dz'.
\]
Thanks to this, it follows from Lemma 2.1, the Poincaré and Young inequalities that
\[
\int_{\Omega} w \partial_z v \cdot (\Delta v - \partial_t v) dxdydz \\
\leq \int_{M} \left( \int_{-1}^{1} |\nabla_H \cdot v| dz \right) \left( \int_{-1}^{1} |\partial_z v|(|\Delta v| + |\partial_t v|) dz \right) dxdy \\
\leq C \|\nabla_H v\|_2^\frac{3}{2} (\|\nabla_H v\|_2 + \|\nabla^2_H v\|_2) \frac{3}{2} \|\partial_z v\|_2 \frac{3}{2} \\
\times (\|\partial_z v\|_2 + \|\nabla_H \partial_z v\|_2) \frac{3}{2} (\|\Delta v\|_2 + \|\partial_t v\|_2) \\
\leq C (\|v\|_{L^2}^\frac{3}{2} \|\nabla v\|_2^\frac{3}{2} \|\partial_z v\|_2^\frac{3}{2} \|\nabla \partial_z v\|_2^\frac{3}{2} (\|\Delta v\|_2 + \|\partial_t v\|_2) \\
\leq \frac{1}{4} (\|\Delta v\|_2^2 + \|\partial_t v\|_2^2) + C (\|\partial_z v\|_2^2 \|\nabla \partial_z v\|_2^2 \|\nabla v\|_2^2. \tag{3.7}
\]
Substituting (3.6)–(3.7) into (3.5) yields
\[
\frac{d}{dt} \| \nabla v \|_2^2 + \frac{1}{4} (\|\Delta v\|_2^2 + \|\partial_t v\|_2^2) \leq C (\|v\|_{L^2}^2 \|\nabla v\|_2^2 + \|\partial_z v\|_2^2 \|\nabla \partial_z v\|_2^2) \|\nabla v\|_2^2,
\]
from which, by the Gronwall inequality, it follows from Propositions 3.1 and 3.3 that
\[
\sup_{0 \leq s \leq t} \| \nabla v \|_2^2(s) + \frac{1}{2} \int_{0}^{t} (\|\Delta v\|_2^2 + \|\partial_t v\|_2^2) ds
\]
Applying the Gronwall inequality to the above inequality, it follows from Proposition and thus
\[
\leq \|\nabla v_0\|^2 \exp \left\{ C \int_0^t \left( \|v\|^2 \|\nabla v\|^2 + \|\partial_x v\|^2 \|\nabla \partial_x v\|^2 \right) ds \right\} \|\nabla v_0\|^2
\]
proving the conclusion. ∎

And finally, in case that \( v_0 \in H^2(\Omega) \), we can obtain the second order energy estimate on \( v \).

**Proposition 3.5** (Second order energy estimate). Suppose that \( v_0 \in H^2(\Omega) \). Then, we have
\[
\sup_{0 \leq s \leq t} \|\Delta v\|^2(s) + \frac{1}{2} \int_0^t \left( \|\nabla \Delta v\|^2 + \|\nabla \partial_t v\|^2 \right) ds
\]
\[
\leq \exp \left\{ C \|\nabla v_0\|^2 e^C \left( \|v_0\|^2 + \|\partial_x v_0\|^2 + \|\partial_t v_0\|^2 \right) \right\} \|\Delta v_0\|^2,
\]
for any \( t \in [0, \infty) \), where \( C \) is a positive constant depending only on \( L_1 \) and \( L_2 \).

**Proof.** Taking the \( L^2(\Omega) \) inner product to equation (3.1) with \( \Delta (\Delta v - \partial_t v) \) and integration by parts, then it follows from Lemma 2.2 and the Young inequality that
\[
\frac{d}{dt} \|\Delta v\|^2 + \|\nabla \Delta v\|^2 + \|\nabla \partial_t v\|^2
\]
\[
= \int_\Omega \nabla [(u \cdot \nabla)v] : \nabla(\Delta v - \partial_t v) dxdydz
\]
\[
= \int_\Omega \left[ (\partial_x u \cdot \nabla)v + (u \cdot \partial_x \nabla)v \right] \cdot \partial_t (\Delta v - \partial_t v) dxdydz
\]
\[
\leq C \left( \|\partial_x \nabla v\|^2 + \|\partial_t \Delta v\|^2 + \|\partial_t \partial_t v\|^2 \right) \left( \|\nabla \Delta v\|^2 + \|\nabla \partial_t v\|^2 \right)
\]
\[
\leq \frac{1}{2} \left( \|\nabla \Delta v\|^2 + \|\nabla \partial_t v\|^2 \right) + C \|\nabla v_0\|^2 \|\Delta v\|^4,
\]
and thus
\[
\frac{d}{dt} \|\Delta v\|^2 + \frac{1}{2} \left( \|\nabla \Delta v\|^2 + \|\nabla \partial_t v\|^2 \right) \leq C \|\nabla v_0\|^2 \|\Delta v\|^4.
\]
Applying the Gronwall inequality to the above inequality, it follows from Proposition 3.4 that
\[
\sup_{0 \leq s \leq t} \|\Delta v\|^2(s) + \frac{1}{2} \int_0^t \left( \|\nabla \Delta v\|^2 + \|\nabla \partial_t v\|^2 \right) ds
\]
\[
\leq \exp \left\{ C \int_0^t \|\nabla v\|^2 \|\Delta v\|^2 ds \right\} \|\Delta v_0\|^2
\]
\[ \leq \exp \left\{ C \| \nabla v_0 \|_2^4 e^{C(\| v_0 \|_2^2 + \| \partial_z v_0 \|_2^2 + \| v_0 \|_4^{16} e^{C(\| v_0 \|_2^2 + \| v_0 \|_4^2)})} \right\} \| \Delta v_0 \|_2^2, \]

proving the conclusion. \qed

As a direct corollary of Propositions 3.1–3.5, we have the following:

**Corollary 3.1.** Suppose that \( v_0 \in H^m \), with \( m = 1 \) or \( m = 2 \). Let \((v, w)\) be the unique global strong solution to the primitive equations \((3.1)-(3.2)\), subject to \((1.2)-(1.4)\). Then, we have the following:

(i) If \( v_0 \in H^1(\Omega) \), then we have the estimate

\[ \sup_{0 \leq t < \infty} \| v \|_{H^1}^2(t) + \int_0^\infty (\| \nabla v \|_{H^1}^2 + \| \partial_t v \|_{L^2}^2) dt \leq C(\| v_0 \|_{H^1}, L_1, L_2); \]

(ii) If \( v_0 \in H^2(\Omega) \), then we have the estimate

\[ \sup_{0 \leq t < \infty} \| v \|_{H^2}^2(t) + \int_0^\infty (\| \nabla v \|_{H^2}^2 + \| \partial_t v \|_{H^1}^2) dt \leq C(\| v_0 \|_{H^2}, L_1, L_2). \]

4. **Strong convergence I: the \( H^1 \) initial data case**

This section is devoted to the strong convergence of (SNS) to (PEs), with initial data \( v_0 \in H^1(\Omega) \), in other words, we give the proof of Theorem 1.1.

Let the initial data \( v_0 \in H^1(\Omega) \), and assume

\[ \nabla \cdot \left( \int_{-1}^1 v_0(x, y, z) dz \right) = 0, \quad \text{for all } (x, y) \in M, \quad (4.1) \]

by the \( H^1 \) theory of the primitive equations, see [12], there is a unique global strong solution \((v, w)\) to (PEs), subject to the boundary and initial conditions \((1.2)-(1.4)\), such that

\[ v \in C([0, \infty); H^1(\Omega)) \cap L^2_{\text{loc}}([0, \infty); H^2(\Omega)), \quad \partial_t v \in L^2_{\text{loc}}([0, \infty); L^2(\Omega)). \quad (4.2) \]

Then, using the boundary condition \((1.2)\) and the symmetry condition \((1.4)\), the vertical component \( w \) of the velocity can be uniquely determined as

\[ w(x, y, z, t) = -\int_0^z \nabla \cdot v(x, y, z', t) dz'. \quad (4.3) \]

Set \( u_0 = (v_0, w_0) \), with \( w_0 \) given by \((1.6)\). Then, it is obviously that \( u_0 \in L^2(\Omega) \) and \( \nabla \cdot u_0 = 0 \). Therefore, following the same arguments as those for the standard Navier-Stokes equations, see, e.g., [14, 35], one can prove that there is a global weak solution, denoted by \( u_\varepsilon = (v_\varepsilon, w_\varepsilon) \), to the scaled Navier-Stokes equations \((1.1)\), subject to the boundary and initial conditions \((1.2)-(1.4)\).

We are going to estimate the difference between \((v_\varepsilon, w_\varepsilon)\) and \((v, w)\). As a preparation, we need the following proposition, which, as it will be shown in the proof, is essentially obtained by testing the (SNS) against \((v, w)\).
Proposition 4.1. Let \((v_\varepsilon, w_\varepsilon)\) and \((v, w)\) be the solutions of \((SNS)\) and \((PEs)\), with initial data \((v_0, w_0)\), \(v_0 \in H^1(\Omega)\) satisfying \((4.1)\) and
\[
 w_0(x, y, z) = -\int_0^z \nabla_H \cdot v_0(x, y, z')dz'.
\]
Then, the following integral equality holds
\[
-\frac{\varepsilon^2}{2} \|w(t)\|^2_2 + \left( \int_{\Omega} v_\varepsilon \cdot v + \varepsilon^2 w_\varepsilon w \right) dx dy dz (t)
+ \int_{Q_t} (-v_\varepsilon \cdot \partial_t v + \nabla v_\varepsilon : \nabla v + \varepsilon^2 \nabla w_\varepsilon \cdot \nabla w) dx dy dz ds
\]
\[
= \frac{\varepsilon^2}{2} \|w_0\|^2_2 + \|v_0\|^2_2 + \varepsilon^2 \int_{Q_t} \left( \int_0^z \partial_t v dz' \right) \cdot \nabla_H W_\varepsilon dx dy dz ds
- \int_{Q_t} [(u_\varepsilon \cdot \nabla) v_\varepsilon \cdot v + \varepsilon^2 u_\varepsilon \cdot \nabla w_\varepsilon w] dx dy dz ds,
\]
\]
for any \(t \in [0, \infty)\), where \(Q_t = \Omega \times (0, t)\).

Proof. We will follow the argument of Serrin [33] (see also [2] and the references therein). Recalling the definition of weak solutions to \((SNS)\), the following integral identity holds
\[
\int_{Q} \left[-(v_\varepsilon \cdot \partial_t \varphi_H + \varepsilon^2 w_\varepsilon \partial_t \varphi_3) + ((u_\varepsilon \cdot \nabla) v_\varepsilon \cdot \varphi_H + \varepsilon^2 u_\varepsilon \cdot \nabla w_\varepsilon \varphi_3) + \nabla v_\varepsilon : \nabla \varphi_H
+ \varepsilon^2 \nabla w_\varepsilon \cdot \nabla \varphi_3 \right] dx dy dz dt
= \int_{\Omega} (v_0 \cdot \varphi_H(\cdot, 0) + \varepsilon^2 w_0 \varphi_3(\cdot, 0)) dx dy dz,
\]
for any periodic function \(\varphi = (\varphi_H, \varphi_3)\), with \(\varphi_H = (\varphi_1, \varphi_2)\), such that \(\nabla \cdot \varphi = 0\) and \(\varphi \in C^\infty_0(\overline{\Omega} \times [0, \infty))\), where \(Q := \Omega \times (0, \infty)\).

Let \(\chi \in C^\infty_0([0, \infty))\), with \(0 \leq \chi \leq 1\) and \(\chi(0) = 1\), and set \(\varphi = (v, w)\chi(t)\). We remark that, by the density argument, we can choose \(\varphi\) as the testing function in the above integral identity, with modifying the term \(\int_{Q} w \partial_t \varphi_3 dx dy dz dt\) as
\[
\int_{Q} w_\varepsilon \partial_t (w \chi) dx dy dz dt = \int_{0}^{\infty} \langle \partial_t (w \chi), w_\varepsilon \rangle_{H^{-1} \times H^1} dt.
\]
This is valid, because, recalling the regularities of \(v\), and using \((4.3)\), we only have the regularity that \(\partial_t w \in L^2_{\text{loc}}(0, \infty); H^{-1}(\Omega)\). The validity of the integrals involving the terms \(v_\varepsilon \cdot \partial_t (v \chi), \nabla v_\varepsilon : \nabla (v \chi), \nabla w_\varepsilon \cdot \nabla (w \chi)\) is obviously guaranteed by the regularities of \(u_\varepsilon\) and \((v, w)\), stated in the definition of the weak solutions and \((4.2)\), respectively. The validity of the integral of the term \((u_\varepsilon \cdot \nabla) v_\varepsilon \cdot v \chi\) follows from utilizing the Hölder inequality and noticing that \(u_\varepsilon \in L^{10/3}_{\text{loc}}(\overline{\Omega} \times [0, \infty))\) and \(v \in L^\infty_{\text{loc}}([0, \infty); L^6(\Omega))\), which are easily verified by the interpolation and the embedding inequalities. While the validity of the integral of the term \(u_\varepsilon \cdot \nabla w_\varepsilon w \chi\) follows from the following calculation:
Let's rewrite the term
\[\left(F, \partial_t \varphi \right) + \left(\varphi, \nabla \cdot \nabla \varphi \right)\]
which, substituted in the previous identity, gives
\[
\int_Q \left[\langle \nabla \varphi, \nabla \varphi \rangle + \varepsilon^2 \langle \nabla \varphi, \nabla^2 \varphi \rangle \right] dxdydzdt = \int_0^T \left(\int_Q \nabla \varphi \cdot \nabla^2 \varphi \right) dxdydzdt + \int_0^T \left(\int_Q \nabla \varphi \cdot \nabla \varphi \right) dxdydzdt
\]
for any \( \varphi \in C_0^\infty([0,\infty)) \), with \( 0 \leq \varphi \leq 1 \) and \( \varphi(0) = 1 \).

Given \( t_0 \in (0,\infty) \), and take a sufficient small positive number \( \delta \in (0, t_0) \). Choose \( \varphi_\delta \in C_0^\infty([0, t_0]) \), such that \( \varphi_\delta \equiv 1 \) on \( [0, t_0 - \delta] \), \( 0 \leq \varphi_\delta \leq 1 \) on \( [t_0 - \delta, t_0] \), and \( |\varphi_\delta'| \leq \frac{2}{\delta} \).
on $[0, t_0]$. We claim that, as $\delta \to 0$, we have
\[
\int_Q (v_\varepsilon \cdot v + \varepsilon^2 w_\varepsilon w)\chi'_\delta dx dy dz dt \to - \left( \int_{\Omega} (v_\varepsilon \cdot v + \varepsilon^2 w_\varepsilon w) dx dy dz \right)(t_0), \quad (4.6)
\]
\[
\int_0^\infty \langle \partial_t w, w_\varepsilon \rangle_{H^{-1} \times H^1} dt \to \int_0^{t_0} \langle \partial_t w, w_\varepsilon \rangle_{H^{-1} \times H^1} dt. \quad (4.7)
\]
The validity of (4.7) follows from the dominant convergence theorem for the integrals, thanks to the observation
\[
\langle \partial_t w, w_\varepsilon \rangle = - \left( \nabla_H \cdot \left( \int_0^z \partial_t vz' \right), w_\varepsilon \right) = \int_{\Omega} \left( \int_0^z \partial_t vz' \right) \cdot \nabla_H w_\varepsilon dx dy dz,
\]
which implies $\langle \partial_t w, w_\varepsilon \rangle \in L^1((0, t_0))$, here, for simplicity, we have dropped the subscript $H^{-1} \times H^1$. While for (4.6), by defining
\[
f(t) := \left( \int_{\Omega} (v_\varepsilon \cdot v + \varepsilon^2 w_\varepsilon w) dx dy dz \right)(t)
\]
it is equivalent to show $\int_{t_0-\delta}^{t_0} f(t) \chi'_\delta(t) dt \to -f(t_0)$. Recalling the regularities that $u_\varepsilon \in C_w([0, \infty); L^2(\Omega))$ and $v \in C([0, \infty); H^1(\Omega))$, hence one has $w \in C([0, \infty); L^2(\Omega))$, and thus $f$ is a continuous function on $[0, \infty)$. For any $\sigma > 0$, by the continuity of $f$, there is a positive number $\rho$, such that $|f(t) - f(t_0)| \leq \sigma$, for any $t \in [t_0 - \rho, t_0]$. Now, for any $\delta \in (0, \rho)$, recalling that $\chi_\delta \equiv 1$ on $[0, t_0 - \delta]$, $\chi_\delta(t_0) = 0$, and $|\chi'_\delta| \leq \frac{2}{\delta}$ on $[0, \infty)$, we deduce
\[
\left| \int_{t_0-\delta}^{t_0} f(t) \chi'_\delta(t) dt + f(t_0) \right| = \left| \int_{t_0-\delta}^{t_0} (f(t) - f(t_0)) \chi'_\delta(t) dt \right| \\
\leq \int_{t_0-\delta}^{t_0} |f(t) - f(t_0)||\chi'_\delta(t)| dt \leq 2\sigma,
\]
which proves (4.6).

Recalling $w = -\int_0^z \nabla_H \cdot vz'$, and noticing that $w \in L^2_{\text{loc}}([0, \infty); H^1(\Omega))$ and $\partial_t w \in L^2_{\text{loc}}([0, \infty); H^{-1}(\Omega))$, we deduce
\[
\langle \partial_t w, w_\varepsilon \rangle = \langle \partial_t w, w_\varepsilon - w \rangle + \langle \partial_t w, w \rangle \\
= \left\langle -\nabla_H \cdot \left( \int_0^z \partial_t vz' \right), w_\varepsilon - w \right\rangle + \langle \partial_t w, w \rangle \\
= \int_{\Omega} \left( \int_0^z \partial_t vz' \right) \cdot \nabla_H W_\varepsilon dx dy dz + \frac{1}{2} \frac{d}{dt} \|w\|^2,
\]
where the Lions–Magenes Lemma (see, e.g., pages 260–261 of [35]) has been used, and thus
\[
\int_0^{t_0} \langle \partial_t w, w_\varepsilon \rangle dt = \int_{Q_{t_0}} \left( \int_0^z \partial_t vz' \right) \cdot \nabla_H W_\varepsilon dx dy dz dt + \frac{1}{2} \|w(t_0)\|^2 - \|w_0\|^2.
\]
where \( Q_{t_0} = \Omega \times (0, t_0) \). Thanks to the above equality and (4.6)–(4.7), one can choose \( \chi = \chi_\delta \) in (4.5), as in the previous paragraph, and let \( \delta \) goes to zero to get

\[
- \frac{\varepsilon^2}{2} \| w(t_0) \|^2_2 + \left( \int_{\Omega} v_\varepsilon \cdot v + \varepsilon^2 w_\varepsilon w \, dx\,dy\,dz \right)(t_0)
\]

\[
+ \int_{Q_{t_0}} (-v_\varepsilon \cdot \partial_t v + \nabla v_\varepsilon : \nabla v + \varepsilon^2 \nabla w_\varepsilon \cdot \nabla w) \, dx\,dy\,dz\,dt
\]

\[
= \frac{\varepsilon^2}{2} \| w_0 \|^2_2 + \| v_0 \|^2_2 + \varepsilon^2 \int_{Q_{t_0}} \left( \int_0^t \partial_t v dz' \right) \cdot \nabla H \, dx\,dy\,dz\,dt
\]

\[
- \int_{Q_{t_0}} [(u_\varepsilon \cdot \nabla)v_\varepsilon \cdot v + \varepsilon^2 u_\varepsilon \cdot \nabla w_\varepsilon w] \, dx\,dy\,dz\,dt,
\]

for any \( t_0 \in [0, \infty) \). This completes the proof. \( \square \)

Now, we can estimate the difference between \((v_\varepsilon, w_\varepsilon)\) and \((v, w)\).

**Proposition 4.2.** Under the same assumptions as in Proposition 4.1 and denoting \((V_\varepsilon, W_\varepsilon) := (v_\varepsilon - v, w_\varepsilon - w)\), the following holds

\[
\sup_{0 \leq t < \infty} (\| V_\varepsilon \|^2_2 + \varepsilon^2 \| W_\varepsilon \|^2_2)(t) + \int_0^\infty (\| \nabla V_\varepsilon \|^2_2 + \varepsilon^2 \| \nabla W_\varepsilon \|^2_2) \, ds
\]

\[
\leq C(\| v_0 \|_{H^1}, L_1, L_2) \varepsilon^2 (\| v_0 \|^2_2 + \varepsilon^2 \| w_0 \|^2_2 + 1)^2,
\]

where \( C(\| v_0 \|_{H^1}, L_1, L_2) \) denotes a constant depending only on \( \| v_0 \|_{H^1}, L_1 \) and \( L_2 \).

**Proof.** Multiplying equation (4.5) by \( v_\varepsilon \), integrating the resultant over \( Q_{t_0} \), it follows from integration by parts that

\[
\int_{Q_{t_0}} (\partial_t v \cdot v_\varepsilon + \nabla v : \nabla v_\varepsilon) \, dx\,dy\,dz\,dt = -\int_{Q_{t_0}} (u \cdot \nabla)v_\varepsilon \cdot v_\varepsilon \, dx\,dy\,dz\,dt,
\]

(4.8)

for any \( t_0 \in [0, \infty) \). Multiplying equation (4.5) by \( v \), integrating the resultant over \( Q_{t_0} \), the it follows from integration by parts that

\[
\frac{1}{2} \| v(t_0) \|^2_2 + \int_{0}^{t_0} \| \nabla v \|^2_2 \, dt = \frac{1}{2} \| v_0 \|^2_2,
\]

(4.9)

for any \( t_0 \in [0, \infty) \). By the definition of Leray-Hopf weak solutions, one has

\[
\frac{1}{2}(\| v_\varepsilon(t_0) \|^2_2 + \varepsilon^2 \| w_\varepsilon(t_0) \|^2_2) + \int_{0}^{t_0} (\| \nabla v_\varepsilon \|^2_2 + \varepsilon^2 \| \nabla w_\varepsilon \|^2_2) \, ds
\]

\[
\leq \frac{1}{2}(\| v_0 \|^2_2 + \varepsilon^2 \| w_0 \|^2_2),
\]

(4.10)

for a.e. \( t_0 \in [0, \infty) \).
Summing (4.9) and (4.10), then subtracting from the resultant (4.4) (choose \( t = t_0 \) there) and (4.8) yields

\[
\frac{1}{2}(\|V\|_2^2 + \varepsilon^2\|W\|_2^2)(t_0) + \int_0^{t_0} (\|\nabla V\|_2^2 + \varepsilon^2\|\nabla W\|_2^2)dt
\leq -\varepsilon^2 \int_{Q_{t_0}} [(\int_0^z \partial_t v dz') \cdot \nabla H w + \nabla v \cdot \nabla W] dx dy dz dt
+ \int_{Q_{t_0}} [(u_r \cdot \nabla) v_r \cdot v + (u \cdot \nabla)v \cdot v] dx dy dz dt
+ \varepsilon^2 \int_{Q_{t_0}} u_r \cdot \nabla w w dx dy dz dt =: I_1 + I_2 + I_3,
\] (4.11)

for a.e. \( t_0 \in [0, \infty) \). It follows from the Hölder and Cauchy-Schwarz inequalities, and using Corollary 3.1 that

\[
I_1 \leq \varepsilon^2 (\|\partial_t v\|_{L^2(Q_{t_0})} + \|\nabla w\|_{L^2(Q_{t_0})}) \|\nabla W\|_{L^2(Q_{t_0})} \\
\leq \frac{\varepsilon^2}{6} \|\nabla W\|_{L^2(Q_{t_0})}^2 + C(\|v_0\|_{H^1}, L_1, L_2)\varepsilon^2.
\] (4.12)

We are going to estimate the quantities \( I_2 \) and \( I_3 \) on the right-hand side of (4.11). Using the incompressibility conditions, it follows from integration by parts that

\[
I_2 := \int_{Q_{t_0}} [(u_r \cdot \nabla) v_r \cdot v + (u \cdot \nabla)v \cdot v] dx dy dz dt
= \int_{Q_{t_0}} [(u_r \cdot \nabla) v_r \cdot v - (u \cdot \nabla)v_r \cdot v] dx dy dz dt
= \int_{Q_{t_0}} [(u_r - u) \cdot \nabla] v_r \cdot v dx dy dz dt
= \int_{Q_{t_0}} [(u_r - u) \cdot \nabla] V_r \cdot v dxdydz dt.
\]

The quantity \( I_2 \) will be divided into two parts \( I_2' \) and \( I_2'' \), below. It follows from the Hölder, Sobolev and Young inequalities that

\[
I_2' := \int_{Q_{t_0}} (V_r \cdot \nabla H) V_r \cdot v dx dy dz dt
\leq \int_0^{t_0} \|V\|_2 \|\nabla V\|_2 \|v\|_6 dt \leq C \int_0^{t_0} \|V\|_2^\frac{1}{2} \|\nabla V\|_2^\frac{3}{2} \|\nabla v\|_2 dt
\leq \frac{1}{18} \|\nabla V\|_{L^2(Q_{t_0})}^2 + C \int_0^{t_0} \|\nabla v\|_2^4 \|V\|_2^2 dt.
\]
Integration by parts yields

\[ I''_2 := \int_{Q_{t0}} W_\varepsilon \partial_z V_\varepsilon \cdot v dxdydzdt \]
\[ = - \int_{Q_{t0}} [\partial_z W_\varepsilon V_\varepsilon \cdot v + W_\varepsilon V_\varepsilon \cdot \partial_z v] dxdydzdt \]
\[ = \int_{Q_{t0}} [\nabla_H \cdot V_\varepsilon V_\varepsilon \cdot v - W_\varepsilon V_\varepsilon \cdot \partial_z v] dxdydzdt \]

For the first term of \( I''_2 \), denoted by \( I''_{21} \), the same arguments as for \( I'_2 \) yield

\[ I''_{21} := \int_{Q_{t0}} (\nabla_H \cdot V_\varepsilon) (V_\varepsilon \cdot v) dxdydzdt \]
\[ \leq \frac{1}{18} \| \nabla V_\varepsilon \|_{L^2(Q_{t0})}^2 + C \int_0^{t_0} \| \nabla v \|_2 \| V_\varepsilon \|_2^2 dt. \]

For the second term of \( I''_2 \), denoted by \( I''_{22} \), by Lemma 2.1, it follows from the Poincaré and Young inequalities that

\[ I''_{22} := - \int_{Q_{t0}} W_\varepsilon V_\varepsilon \cdot \partial_z v dxdydzdt \]
\[ = \int_0^t \int_{\Omega} \left( \int_0^z \nabla_H \cdot V_\varepsilon dz' \right) (V_\varepsilon \cdot \partial_z v) dxdydzdt \]
\[ \leq \int_0^t \int_M \left( \int_{z=1}^z |\nabla_H V_\varepsilon| dz \right) \left( \int_{z=1}^1 |V_\varepsilon| \| \partial_z v \| dz \right) dxdydzdt \]
\[ \leq C \int_0^t \| \nabla V_\varepsilon \|_2^2 \| V_\varepsilon \|_2^2 \| \nabla v \|_2^2 \| \Delta v \|_2^2 dt \]
\[ \leq \frac{1}{18} \| \nabla V_\varepsilon \|_{L^2(Q_{t0})}^2 + C \int_0^{t_0} \| \nabla v \|_2^2 \| \Delta v \|_2^2 \| V_\varepsilon \|_2^2 dt. \]

Thanks to the estimates for \( I'_2 \), \( I''_{21} \) and \( I''_{22} \), we can bound \( I_2 \) as

\[ I_2 \leq \frac{1}{6} \| \nabla V_\varepsilon \|_{L^2(Q_{t0})}^2 + C \int_0^{t_0} \| \nabla v \|_2^2 \| \Delta v \|_2^2 \| V_\varepsilon \|_2^2 dt, \]  \hspace{1cm} (4.13)

note that the Poincaré inequality has been used.

We still need to estimate the last term \( I_3 \) in (4.11). Using the incompressibility conditions, we deduce that

\[ I_3 := \varepsilon^2 \int_{Q_{t0}} u_\varepsilon \cdot \nabla w_\varepsilon w dxdydzdt = \varepsilon^2 \int_{Q_{t0}} u_\varepsilon \cdot \nabla W_\varepsilon w dxdydzdt \]
Thus, it follows from Lemma 2.1, the Poincaré and Young inequalities that
from which, recalling (4.10) and by Corollary 3.1, we have

\[\leq C\varepsilon^{2} \int_{0}^{t} \left( f_{0} + \int_{0}^{t} \left( \|v\|_{H^{1}} \right)^{2} ds \right) + C \int_{0}^{t} \|\nabla v\|_{2} \|\Delta v\|_{2} ds =: F(t), \]

for a.e. \( t \in [0, \infty) \). Thus, we have

\[ F'(t) = C \|\nabla v\|_{2}^{2} \|\Delta v\|_{2} \|V_{\varepsilon}\|_{2}^{2}, \]

which implies the conclusion.

With the aid of Proposition 4.2, we can now give the proof of Theorem 1.1.

**Proof of Theorem 1.1.** The estimate in Theorem 1.1 follows from Proposition 4.2, while the convergence is a direct consequence of that estimate.
5. Strong convergence II: the $H^2$ initial data case

In this section, we prove the strong convergence of (SNS) to (PEs), with initial data $v_0 \in H^2(\Omega)$, as the aspect ration parameter $\varepsilon$ goes to zero. In other words, we give the proof of Theorem 1.2.

Let $v_0 \in H^2(\Omega)$, and suppose that
\[
\nabla_H \cdot \left( \int_{-1}^{1} v_0(x,y,z) \, dz \right) = 0,
\]
for all $(x,y) \in M$.

Set $u_0 = (v_0, w_0)$, with $w_0$ given by (1.6), then $u_0 \in H^1(\Omega)$ and $\nabla \cdot u_0 = 0$. By the same arguments as those for the standard Navier-Stokes equations, see, e.g., Constantin–Foias [14] and Temam [35], one can prove that, there is a unique local (in time) strong solution $u_\varepsilon = (v_\varepsilon, w_\varepsilon)$ to (SNS), subject to (1.2)–(1.4). Denote by $T^*_{\varepsilon}$ the maximal existence time of the strong solution $(v_\varepsilon, w_\varepsilon)$. Let $u = (v, w)$ be the unique solutions to (PEs), subject to (1.2)–(1.4).

Denote, as before, $U_\varepsilon$ the difference between $u_\varepsilon$ and $u$, that is $U_\varepsilon = (V_\varepsilon, W_\varepsilon)$, $V_\varepsilon = v_\varepsilon - v$, $W_\varepsilon = w_\varepsilon - w$.

Then, one can easily verify that $U_\varepsilon = (V_\varepsilon, W_\varepsilon)$ satisfies the following system
\[
\begin{align*}
\partial_t V_\varepsilon + (U_\varepsilon \cdot \nabla) V_\varepsilon - \Delta V_\varepsilon + \nabla_H P_\varepsilon + (u \cdot \nabla) V_\varepsilon + (U_\varepsilon \cdot \nabla) v &= 0, \\
\nabla_H \cdot V_\varepsilon + \partial_z W_\varepsilon &= 0, \\
\varepsilon^2 (\partial_t W_\varepsilon + U_\varepsilon \cdot \nabla W_\varepsilon - \Delta W_\varepsilon + U_\varepsilon \cdot \nabla w + u \cdot \nabla w_\varepsilon) + \partial_z P_\varepsilon &= -\varepsilon^2 (\partial_t w + u \cdot \nabla w - \Delta w),
\end{align*}
\]
in $\Omega \times (0, T^*_{\varepsilon})$. Due to the smoothing effect of (SNS) to the unique strong solutions, one can show that the strong solution $(v_\varepsilon, w_\varepsilon)$ is smooth in the time interval $(0, T^*_{\varepsilon})$, and thus, recalling that $(v, w)$ is smooth away from the initial time, so is $(V_\varepsilon, W_\varepsilon)$. This guarantees the validity of the arguments in the proof below.

We are going to do the a priori estimates on $(V_\varepsilon, W_\varepsilon)$. We start with the basic energy estimate stated in the following proposition.

**Proposition 5.1** (Basic $L^2$ energy estimate). The following basic energy estimate holds
\[
\sup_{0 \leq s \leq t} (\|V_\varepsilon\|_2^2 + \varepsilon^2 \|W_\varepsilon\|_2^2) + \int_0^t (\|\nabla V_\varepsilon\|_2^2 + \varepsilon^2 \|\nabla W_\varepsilon\|_2^2) \, ds \\ \leq C \varepsilon^2 (\|v_0\|_2^2 + \varepsilon^2 \|w_0\|_2^2 + 1)^2,
\]
for any $t \in [0, T^*_{\varepsilon})$, where $C$ is a constant depending only on $\|v_0\|_{H^1}$, $L_1$ and $L_2$.

**Proof.** This is a direction consequence of Proposition 4.2. □

The first order energy estimate is stated in the following proposition.
Proposition 5.2 \((H^1)\) energy estimates. There exists a positive constant \(\delta_0\) depending only on \(L_1\) and \(L_2\), such that, the following estimate holds
\[
\sup_{0 \leq s \leq t} (\|\nabla V_\epsilon\|_2^2 + \epsilon^2 \|\nabla W_\epsilon\|_2^2) + \int_0^t (\|\Delta V_\epsilon\|_2^2 + \epsilon^2 \|\Delta W_\epsilon\|_2^2)ds \\
\leq C\epsilon^2 e^{C(1+\epsilon^4)} \int_0^t \|\Delta v\|_2^2 \|\nabla \Delta v\|_2^2 ds \\
(1 + \|\Delta v\|_2^2)(\|\nabla \partial_t v\|_2^2 + \|\nabla \Delta v\|_2^2)ds,
\]
for any \(t \in [0, T_\epsilon^*]\), as long as
\[
\sup_{0 \leq t \leq t} (\|\nabla V_\epsilon\|_2^2 + \epsilon^2 \|\nabla W_\epsilon\|_2^2) \leq \delta_0^2,
\]
where \(C\) is a positive constant depending only on \(L_1\) and \(L_2\).

Proof. For simplicity of the notations, we drop the subscript index \(\epsilon\) of \((V_\epsilon, W_\epsilon)\) in the following proof, in other words, we use \((V, W)\) to replace \((V_\epsilon, W_\epsilon)\).

Taking the \(L^2(\Omega)\) inner products to equations (5.1) and (5.3) with \(-\Delta V\) and \(-\Delta W\), respectively, summing the resultant equations up and integration by parts yield
\[
\frac{1}{2} \frac{d}{dt} (\|\nabla V\|_2^2 + \|\epsilon \nabla W\|_2^2) + \|\Delta V\|_2^2 + \|\epsilon \Delta W\|_2^2 \\
= \int_\Omega [(U \cdot \nabla) V + (u \cdot \nabla) V + (U \cdot \nabla)v] \cdot \Delta V dxdydz \\
+ \epsilon^2 \int_\Omega (U \cdot \nabla W + u \cdot \nabla W + U \cdot \nabla w) \Delta W dxdydz \\
+ \epsilon^2 \int_\Omega (\partial_t w + u \cdot \nabla w - \Delta w) \Delta W dxdydz. \tag{5.4}
\]

We are going to estimate the terms on the right-hand side of (5.4). First, by Lemma 2.2 it follows from the Young and Poincaré inequalities that
\[
\int_\Omega [(U \cdot \nabla) V + (u \cdot \nabla) V + (U \cdot \nabla)v] \cdot \Delta V dxdydz \\
\leq C(\|\nabla V\|_2 \|\Delta V\|_2 + \|\nabla v\|_2 \|\Delta v\|_2 \|\nabla V\|_2 \|\Delta V\|_2) \\
\leq \frac{1}{10} \|\Delta V\|_2^2 + C(\|\nabla V\|_2^2 \|\Delta V\|_2^2 + \|\nabla v\|_2^2 \|\Delta v\|_2^2 \|\nabla V\|_2^2) \\
\leq \frac{1}{10} \|\Delta V\|_2^2 + C(\|\nabla V\|_2^2 \|\Delta V\|_2^2 + \|\Delta v\|_2^2 \|\nabla \Delta v\|_2 \|\nabla V\|_2^2) \tag{5.5}
\]
and
\[
\epsilon^2 \int_\Omega (U \cdot \nabla W + u \cdot \nabla W + U \cdot \nabla w) \Delta W dxdydz \\
\leq C\epsilon^2 [\|\nabla V\|_2^2 \|\Delta V\|_2^2 + \|\nabla v\|_2^2 \|\Delta v\|_2^2 \|\nabla W\|_2^2 \|\Delta W\|_2^2] \\
+ \|\nabla V\|_2 \|\Delta V\|_2 \|\nabla w\|_2 \|\Delta w\|_2 \|\nabla W\|_2 \|\Delta W\|_2.
\[
\leq \frac{1}{10} \left( \| \Delta V \|^2_2 + \| \varepsilon \Delta W \|^2_2 \right) + C \left( \| \nabla V \|^2_2 \| \Delta V \|^2_2 + \| \varepsilon \nabla W \|^2_2 \| \varepsilon \Delta W \|^2_2 \right)
\]
\[+ C \| \nabla v \|^2_2 \| \Delta v \|^2_2 + \varepsilon \nabla W \|^2_2 + C \varepsilon^4 \| \nabla \Delta w \|^2_2 \| \Delta W \|^2_2 \| \nabla \|^2_2 \nabla W \]
\[\leq \frac{1}{10} \left( \| \Delta V \|^2_2 + \| \varepsilon \Delta W \|^2_2 \right) + C \left( \| \nabla V \|^2_2 + \| \varepsilon \nabla W \|^2_2 \right)
\]
\[\times \left[ \left( \| \Delta V \|^2_2 + \| \varepsilon \Delta W \|^2_2 + (1 + \varepsilon^4) \| \Delta w \|^2_2 \| \Delta W \|^2_2 \right) \right],
\]
(5.6)
where in the last step we have used the fact that
\[
\| \nabla w \|_2 \leq C \| \Delta v \|_2, \quad \| \Delta w \|_2 \leq C \| \nabla \Delta v \|_2,
\]
which can be easily verified by recalling \( w(x, y, z, t) = -\int_0^z \nabla_H \cdot v(x, y, z', t)dz' \) and using the Poincaré inequality. Next, using again Lemma 2.2, it follows from the Hölder, Young and Poincaré inequalities that
\[
\varepsilon^2 \int_\Omega (\partial_t w + u \cdot \nabla w - \Delta w) \Delta W dxdydz
\]
\[\leq \varepsilon^2 \left( \| \partial_t w \|_2 + \| \Delta w \|_2 \right) \| \Delta w \|_2 + C \varepsilon^2 \| \nabla v \|_2 \| \Delta v \|_2 \| \nabla w \|_2 \| \Delta w \|_2
\]
\[\leq \frac{1}{5} \| \varepsilon \Delta W \|^2_2 + C \varepsilon^2 \left( \| \partial_t w \|_2^2 + \| \Delta w \|_2^2 + \| \nabla v \|_2^2 \| \Delta v \|_2 + \| \nabla w \|_2^2 \| \Delta w \|_2 \right)
\]
\[\leq \frac{1}{5} \| \varepsilon \Delta W \|^2_2 + C \varepsilon^2 \left( \| \nabla \partial_t v \|_2^2 + \| \nabla \Delta v \|_2^2 + \| \Delta \partial_t v \|_2^2 \| \Delta W \|_2 \right).
\]
(5.7)
Substituting the estimates (5.5)–(5.7) into (5.4) yields
\[
\frac{1}{2} \frac{d}{dt} \left( \| \nabla V \|^2_2 + \| \varepsilon \nabla W \|^2_2 \right) + \frac{3}{5} \left( \| \Delta V \|^2_2 + \| \varepsilon \Delta W \|^2_2 \right)
\]
\[\leq C_1 \left( \| \nabla V \|^2_2 + \| \varepsilon \nabla W \|^2_2 \right) \left( \| \Delta V \|^2_2 + \| \varepsilon \Delta W \|^2_2 \right)
\]
\[+ C_1 \varepsilon^2 \left( \| \nabla \partial_t v \|^2_2 + \| \nabla \Delta v \|^2_2 \right),
\]
for a positive constant \( C_1 \) depending only on \( L_1 \) and \( L_2 \).

By the assumption \( \sup_{0 \leq t \leq L} \left( \| \nabla V \|^2_2 + \| \varepsilon \nabla W \|^2_2 \right) \leq \delta_0^2 \). Choosing \( \delta_0 = \sqrt{\frac{1}{10 C_1}} \), it follows from the above inequality that
\[
\frac{d}{dt} \left( \| \nabla V \|^2_2 + \| \varepsilon \nabla W \|^2_2 \right) + \| \Delta V \|^2_2 + \| \varepsilon \Delta W \|^2_2
\]
\[\leq 2 C_1 (1 + \varepsilon^4) \| \Delta v \|^2_2 \| \nabla \Delta v \|^2_2 \left( \| \nabla V \|^2_2 + \| \varepsilon \nabla W \|^2_2 \right)
\]
\[+ 2 C_1 \varepsilon^2 \left( 1 + \| \Delta v \|^2_2 \right) \left( \| \nabla \partial_t v \|^2_2 + \| \nabla \Delta v \|^2_2 \right),
\]
from which, recalling \( (V, W)|_{t=0} = 0 \), it follows from the Gronwall inequality that
\[
\sup_{0 \leq t \leq t} \left( \| \nabla V \|^2_2 + \varepsilon^2 \| \nabla W \|^2_2 \right) + \int_0^t \left( \| \Delta V \|^2_2 + \varepsilon^2 \| \Delta W \|^2_2 \right) ds
\]
\[\leq 2 C_1 \varepsilon^2 e^{2 C_1 (1+\varepsilon^4) \int_0^t \| \Delta v \|^2_2 \| \nabla \Delta v \|^2_2 ds} \int_0^t \left( 1 + \| \Delta v \|^2_2 \right) \left( \| \nabla \partial_t v \|^2_2 + \| \nabla \Delta v \|^2_2 \right) ds,
\]
proving the conclusion.

Thanks to Propositions 5.1–5.2 as well as Corollary 3.1, we can prove the following:

**Proposition 5.3.** There is a positive constant $\varepsilon_0$ depending only on $\|v_0\|_{H^2}, L_1$ and $L_2$, such that for any $\varepsilon \in (0, \varepsilon_0)$, there is a unique global strong solution $(v_\varepsilon, w_\varepsilon)$ to (SNS), subject to (1.2)–(1.4). Moreover, the following estimate holds

$$\sup_{0 \leq t < \infty} \left( \|V_\varepsilon\|_{H^1}^2 + \varepsilon^2 \|W_\varepsilon\|_{H^1}^2 \right) + \int_0^\infty \left( \|\nabla V_\varepsilon\|_{H^1}^2 + \varepsilon^2 \|\nabla W_\varepsilon\|_{H^1}^2 \right) dt \leq C \varepsilon^2,$$

where $C$ is a positive constant depending only on $\|v_0\|_{H^2}, L_1$ and $L_2$.

**Proof.** Recall that $T^{*}_\varepsilon$ is the maximal existence time of the strong solutions $(v_\varepsilon, w_\varepsilon)$ to (SNS), subject to the boundary and initial conditions (1.2)–(1.4). By Corollary 3.1 and Proposition 5.1, we have the estimate

$$\sup_{0 \leq t < T^*_\varepsilon} \left( \|V_\varepsilon\|_2^2 + \varepsilon^2 \|W_\varepsilon\|_2^2 \right) + \int_0^{T^*_\varepsilon} \left( \|\nabla V_\varepsilon\|_2^2 + \varepsilon^2 \|\nabla W_\varepsilon\|_2^2 \right) dt \leq K_1 \varepsilon^2,$$

where $K_1$ is a positive constant depending only on $\|v_0\|_{H^1}, L_1$ and $L_2$.

Let $\delta_0$ be the constant in Proposition 5.2, which depends only on $L_1$ and $L_2$. Define

$$t^*_\varepsilon := \sup \left\{ t \in (0, T^*_\varepsilon) \mid \sup_{0 \leq s \leq t} \left( \|\nabla V_\varepsilon\|_2^2 + \varepsilon^2 \|\nabla W_\varepsilon\|_2^2 \right) \leq \delta_0^2 \right\}.$$

By Proposition 5.2 and Corollary 3.1, we have the estimate

$$\sup_{0 \leq s \leq t} \left( \|\nabla V_\varepsilon\|_2^2 + \varepsilon^2 \|\nabla W_\varepsilon\|_2^2 \right) + \int_0^t \left( \|\nabla V_\varepsilon\|_2^2 + \varepsilon^2 \|\nabla W_\varepsilon\|_2^2 \right) ds \leq K_2 \varepsilon^2,$$

for any $t \in [0, t^*_\varepsilon)$, where $K_2$ is a positive constant depending only on $\|v_0\|_{H^2}, L_1$ and $L_2$. Setting $\varepsilon_0 = \sqrt{\frac{\delta_0}{2K_2}}$, then the above inequality implies

$$\sup_{0 \leq s \leq t} \left( \|\nabla V_\varepsilon\|_2^2 + \varepsilon^2 \|\nabla W_\varepsilon\|_2^2 \right) + \int_0^t \left( \|\Delta V_\varepsilon\|_2^2 + \varepsilon^2 \|\Delta W_\varepsilon\|_2^2 \right) ds \leq \frac{\delta_0}{2},$$

for any $\varepsilon \in (0, \varepsilon_0)$, and for any $t \in [0, t^*_\varepsilon)$, which, in particular, gives

$$\sup_{0 \leq t < t^*_\varepsilon} \left( \|\nabla V_\varepsilon\|_2^2 + \varepsilon^2 \|\nabla W_\varepsilon\|_2^2 \right) \leq \frac{\delta_0}{2}.$$

Thus, by the definition of $t^*_\varepsilon$, we must have $t^*_\varepsilon = T^*_\varepsilon$. Thanks to this, it is clear that (5.9) holds for any $t \in [0, T^*_\varepsilon)$.

We claim that it must has $T^*_\varepsilon = \infty$, otherwise, if $T^*_\varepsilon < \infty$, then, recalling that (5.9) holds for any $t \in [0, T^*_\varepsilon)$, by the local well-posedness result of the (SNS), one can extend the strong solution $(w_\varepsilon, v_\varepsilon)$ beyond $T^*_\varepsilon$, which contradicts to the definition of $T^*_\varepsilon$. Therefore, the conclusion follows by combining (5.8) with (5.9). \qed

Based on Proposition 5.3, we can now give the proof of Theorem 1.2 as follows:
Proof of Theorem 1.2. Let $\varepsilon_0$ be the constant in Proposition 5.3, which depends only on $\|v_0\|_{H^2}$, $L_1$ and $L_2$. Then, by Proposition 5.3, for any $\varepsilon \in (0, \varepsilon_0)$, there is a unique global strong solution $(v_\varepsilon, w_\varepsilon)$ to (SNS), subject to the boundary and initial conditions (1.2)–(1.4). Moreover, the following estimate holds

$$
\sup_{0 \leq t < \infty} \left( \|V_\varepsilon\|_{H^1}^2 + \varepsilon^2 \|W_\varepsilon\|_{H^1}^2 \right) + \int_0^\infty \left( \|\nabla V_\varepsilon\|_{H^1}^2 + \varepsilon^2 \|\nabla W_\varepsilon\|_{H^1}^2 \right) dt \leq C \varepsilon^2,
$$

where $(V_\varepsilon, W_\varepsilon) = (v_\varepsilon, w_\varepsilon) - (v, w)$, and $C$ is a positive constant depending only on $\|v_0\|_{H^2}$, $L_1$ and $L_2$. This proves the estimates stated in the theorem, while the strong convergence stated there are just the direct corollaries of this estimate. This completes the proof of Theorem 1.2. □

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(Jinkai Li) Department of Mathematics, The Chinese University of Hong Kong, Hong Kong, P.R.China
E-mail address: jklimath@gmail.com

(Edriss S. Titi) Department of Mathematics, Texas A&M University, 3368-TAMU, College Station, TX 77843-3368, USA. ALSO, Department of Computer Science and Applied Mathematics, Weizmann Institute of Science, Rehovot 76100, Israel.
E-mail address: titi@math.tamu.edu and edriss.titi@weizmann.ac.il