A Novel Video Hiding Method for Biometric Identification

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Abstract: In this study, a novel video hiding method is proposed for protecting the transmitted biometric information. Different from the most of existing information hiding methods, the hiding content is an image set rather than a single image or feature vector. For the sake of making the hiding result more invisible and robust, human visual model is adopted by considering both inter-frame and intra-frame motion information. Moreover, the biometric image set is hidden into the video sequence discretely by using discrete wavelet transform method. In particular, in order to detect the integrity of stego-video and guarantee the exactly extraction, the frame number is embedded into the corresponding frame as one watermark. Finally, the extracted image set is used for biometric identification. The identification accuracy is used to verify the performance of hiding method. Experiments show that the proposed hiding method can reach good invisibility and robustness, and ensure the effectiveness of biometrics simultaneously.

1. Introduction

In computer vision, biometrics has been regarded as an efficient and reliable identification technique, such as face [1], palmprint [2]. However, the digital biometrical information is unsecure and easily intercepted or attacked in the remote recognition, since it is extremely convenient for hackers to copy or process multimedia data. For the sake of solving the security problem, watermarking techniques have been studied to protect the digital information and some biometric watermarking methods have been described [3-4]. In this work, a novel and effective image set hiding method based video is presented to secure biometrics. Different from most of the existing biometric information hiding methods, the hiding content is an image set rather than a single image or some features, aiming to make the method more robust. For improving the invisibility and robustness, the biometric data is discretely hidden into the image sequence by considering the motion information of objects adequately. It is worth noting that the frame number as a watermark is embedded into the corresponding frame to ensure the extraction accurately.

2. The Proposed Hiding Method

Palmprint images have been proved to be one reliable feature for personal verification and studied widely [5]. In this study, the palmprint image set is employed as the secret information for remote identification. Several public video sequences are used as the cover database. Given a palmprint image set, a video is selected randomly from the cover database as the transmission carrier. First, as a watermark, the frame number is embedded into the corresponding frame. Then, two motion analysis methods are used to locate the embedding frames and positions. Finally, the image set is embedded into the fast motion frames with fast motion regions, aiming to increasing the invisibility.

In general, the secret information is hidden into the regions with fast moving. So without loss of generality, the palmprint image set is embedded into the moving fast regions in this study. The temporal difference is a simple and effective method for motion detection, which takes consecutive
video frames to determine the absolute difference. Suppose \( I_n \) represents the nth frame, the difference image \( D_n \) of \( I_n \) can be calculated:

\[
D_n = I_n - I_{n-1}
\]

where \( I_{n-1} \) is the former frame of \( I_n \).

The greater \( D_n \) is, motion variations are more significant and the motion activity is higher. The method based on adjacent frames difference is available. The blocks which include moving objects in these frames are located for biometric data embedding. In this paper, we adopt the robust real-time multiresolution algorithm which is available to detect moving objects in the presence of camera movement. The 2D affine model is used here to describe the camera motion. This model can deal with many kinds of motion such as translation, rotation, scaling and deformation.

\[
\begin{align*}
\begin{cases}
u(X_i) = a_1 + a_2x_i + a_3y_i \\
u(X_i) = a_4 + a_5x_i + a_6y_i
\end{cases}
\end{align*}
\]

where \( X_i = (x_i, y_i) \) is the position of a pixel point.

This model can also be expressed in the matrix form as follows:

\[
V_i(A) = [u(X_i), v(X_i)] = B(X_i)A,
\]

where \( A = (a_1, a_2, a_3, a_4, a_5, a_6) \) denotes motion parameters which need to be estimated, \( V_i(X_i) \) is the motion vector at point \( X_i \).

To estimate motion parameter vector \( \Theta = (A', \xi) \), the minimization is done between two consecutive frames \( I_{t-1} \) and \( I_t \) [6].

\[
\hat{\Theta} = \arg \min_{\Theta} \sum_{X_i} DFD_\Theta(X_i) = I(X_i + B(X_i)A, t + 1) - I(X_i, t) + \xi
\]

where \( \xi \) is an intensity variation parameter which is used when global illumination changes occur. The minimization is solved through iteratively reweighted least squares. If the weight of \( X_i \) is more close to 1, the possibility that the pixel belongs to the background is bigger. Otherwise, it is almost considered as a foreground pixel.

\[
M_i(X_i) = \begin{cases}
1 & \text{if } W_i(X_i) < \tau \\
0 & \text{otherwise}
\end{cases}
\]

where \( W_i \) is the weight map obtained after the last iteration of IRLS and \( \tau \) is the binary threshold.

Fig.1 shows the examples of motion analysis for the video ‘News’. Fig. 1(a1) and (b1) are two adjacent frames (352 x 288), (c1) gives the absolute difference results of (a1) and (b1), and (d1) is the block based motion probability image magnified by a factor 255, the size of each block is 8 x 8. (e1) is the corresponding block based motion probability image.

![Fig. 1. The motion analysis of the video ‘News’](image)

Taken a video sequence as a carrier, the frame number is embedded into related frame to ensure
accurate extraction of biometric image set. In this study, LSB method is employed for embedding the watermark. DWT is adopted to embed the palmprint image set. The embedding processes can be depicted as follows:

Step 1: Converting images. First, each pixel value of palmprint image is converted eight bits. Then, the binary stream is got by linking all pixel values sequentially. It is that the $N$ transmitted images with the size of $m \times n$ can be converted to a binary stream $B = B(s) \in \{0, 1\}^s = 1, 2, \ldots, N \times m \times n \times 8$.

Step 2: Locating embedding positions. DWT with one level is carried on each watermarked frame. On the basis of the length of binary sequence $B$, the video frames with larger motion activity of approximations sub-band are chosen as embedded frames based on temporal difference. Then, some blocks with higher motion activity are chosen for embedding palmprint image set based on real-time multiresolution algorithm.

Step 3: Embedding binary sequence $B$. Inspiring by literature [7], we embed the the binary sequence $B$ into the approximation coefficients of DWT in the regions with larger motion activity. The embedding rule can be written as

$$V_{k,i} = V_{k,i} + \alpha \times B(s), \quad 1 \leq k \leq 300$$

where $V_{k,i}$ is the approximation coefficient of $k$th frame, $\alpha$ is the embedding parameter.

For one received stego-video, we first extract watermarks from the video and determine whether the stego-video is changed during the transfer. Then, the binary sequence $B'$ is extracted in terms of the motion activity by combing the watermarks

$$B'(s) = (V_{k,i} - V_{k,i}) / \alpha, i, j = 1, 2, \ldots, m / 2$$

where $V_{i,j}$ and $V$ are the corresponding low-frequency coefficients of the stego-image and cover image with one-level wavelet transform respectively. If $B'(s) > T$, then $B'(s) = 1$, otherwise $B'(s) = 0$, where $T$ is the decision threshold.

3. Experimental Results and Analysis

For the sake of evaluating the performance of our proposed method, four public video sequences are utilized as carriers. Fig. 2 exhibits the first frames of the four videos.

![Fig. 2. The first frames of the four video sequences](image)

The palmprint database from Hong Kong Polytechnic University is used as the transmitted biometric data. In experiments, Five images of each individual are used for training and the others for transmitted testing set. So, N is equal to 5. The size of each image is $128 \times 128$. It is worth noting that the length of binary sequence $B$ is $5 \times 128 \times 128 \times 8 = 655360$ bits. In the method of block-based motion analysis, the binary threshold $\tau$ is set 0.3, the size of each block is $16 \times 8$ and the embedding capacity is 128 bits. Besides, the first 32 blocks with the larger activity is selected to embed the binary sequence. Therefore, the embedding capacity is $4 \times 4 \times 8 \times 32 = 4094$ bits per frame. That is, the whole binary sequence needs 160 frames for embedding. The embedding parameter is set $\alpha = 8$ and the extracted threshold is set $T = 0.2$.

Imperceptibility Evaluation: Table1 gives the averaged PSNR values of the four video. Generally, the image quality is acceptable if the PSNR value is larger than 35 dB. Therefore, these results
indicate that our method can reach good stego-video quality.

Table 1. PSNR values of four stego-videos

| Video sequences | News | Foreman | HandballC | Highway |
|-----------------|------|---------|-----------|---------|
| PSNR (dB)       | 46.60| 46.62   | 46.56     | 44.38   |

Robustness Evaluation: Table 2 shows the identification accuracy in terms of various attacks with different attack factors.

Table 2. Identification results under various attacks

| Attack Type       | Parameter               | 0.35 | 0.40 | 0.45 | 0.50 | 0.55 |
|-------------------|-------------------------|------|------|------|------|------|
| Spatial filtering | Standard deviation      | 97%  | 84%  | 56%  | 44%  | 31%  |
|                   | Identification accuracy |      |      |      |      |      |
| Noise addition    | Noise density           | 0.01 | 0.02 | 0.03 | 0.04 | 0.05 |
|                   | Identification accuracy | 99%  | 98%  | 90%  | 64%  | 48%  |
| Scaling           | Scaling factor          | 1.1  | 1.2  | 1.3  | 1.4  | 1.5  |
|                   | Identification accuracy | 91%  | 97%  | 93%  | 83%  | 48%  |
| Frame dropping    | Number of dropped frames| 4    | 6    | 8    | 10   | 12   |
|                   | Identification accuracy | 99%  | 98%  | 98%  | 99%  | 99%  |
| Frame averaging   | Number of averaged frames| 4    | 6    | 8    | 10   | 12   |
|                   | Identification accuracy | 98%  | 99%  | 98%  | 98%  | 98%  |

Seen from type of spatial attack, the method is robust against attacks with small factors. Even the number of dropped frames is equal to 12, the identification rate still can keep 99%. The reason of these good results can be analyzed that since we attack some frames from the video randomly and the embedded frames might not be chosen for attacking. For the attack of frame swapping, we can extract the palmprint set completely since the extracted watermarks can judge and recover the swapped frames. So, the identification rate will not be affected by this kind of attack.

4. Conclusion and Future Work

A novel and effective video hiding method has been presented for protecting the biometric data in this paper. This method differs with most of existing biometric data hiding methods, an image set rather than a single image or feature is embedded into the unrelated video to increase the validity of biometric identification. For the sake of obtaining better invisibility and robustness, the motion analysis is adequately considered and the biometric data is discretely hidden into the frequency coefficients of transform domain. Specifically, the watermarks are embedded into the video for detecting the integrity of stego-video. A large number of experiments indicate that our proposed method can protect the biometric data efficiently and further ensure the effectiveness of biometrics.

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