Probabilistic Analysis of the Dual Next-Fit Algorithm for Bin Covering

Carsten Fischer and Heiko Röglin

Department of Computer Science
University of Bonn, Germany
carsten.fischer@uni-bonn.de, roeglin@cs.uni-bonn.de

Abstract. In the bin covering problem, the goal is to fill as many bins as possible up to a certain minimal level with a given set of items of different sizes. Online variants, in which the items arrive one after another and have to be packed immediately on their arrival without knowledge about the future items, have been studied extensively in the literature. We study the simplest possible online algorithm Dual Next-Fit, which packs all arriving items into the same bin until it is filled and then proceeds with the next bin in the same manner. The competitive ratio of this and any other reasonable online algorithm is $1/2$.

We study Dual Next-Fit in a probabilistic setting where the item sizes are chosen i.i.d. according to a discrete distribution and we prove that, for every distribution, its expected competitive ratio is at least $1/2 + \epsilon$ for a constant $\epsilon > 0$ independent of the distribution. We also prove an upper bound of $2/3$ and better lower bounds for certain restricted classes of distributions. Finally, we prove that the expected competitive ratio equals, for a large class of distributions, the random-order ratio, which is the expected competitive ratio when adversarially chosen items arrive in uniformly random order.

1 Introduction

In the bin covering problem one is given a set of items with sizes $s_1, \ldots, s_n \in [0, 1]$ and the goal is to fill as many bins as possible with these items, where a bin is counted as filled if it contains items with a total size of at least 1. More precisely, we are interested in finding the maximal number $\ell$ of pairwise disjoint sets $X_1, \ldots, X_\ell \subseteq \{1, \ldots, n\}$ such that $\sum_{i \in X_j} s_i \geq 1$ for every $j$. We call the sets $X_j$ bins and we say that a bin is filled or covered if the total size of the items it contains is at least 1. Variants of the bin covering problem occur frequently in industrial applications, e.g., when packing food items with different weights into boxes that each need to have at least the advertised weight.

Bin covering is a well-studied NP-hard optimization problem. A straightforward reduction from the partition problem shows that it cannot be approximated within a factor of $1/2 + \epsilon$ for any $\epsilon > 0$. On the positive side, Jansen and Solis-Oba [9] presented an asymptotic fully polynomial-time approximation scheme. In many applications, it is natural to study online variants, in which items arrive one after another and have to be packed directly into one of the bins without knowing the future items. It is also often natural to restrict the number of open bins, i.e., bins that contain at least one item but are not yet covered, that an online algorithm may use.

We study the simple online algorithm Dual Next-Fit (DNF) that packs all arriving items into the same bin until it is filled. Then the next items are packed into a new bin until it is filled, and so on. The (asymptotic) competitive ratio of DNF is $1/2$ [2], which is best possible for deterministic online algorithms [7]. In fact, all deterministic online algorithms that do not add items to a bin that is already covered and have at most a constant number of open bins at any point in time have a competitive ratio of exactly $1/2$ [3]. Since competitive analysis does not yield much insight for bin covering, alternative measures have been suggested. Most notably are probabilistic models in which the item sizes are drawn at random from a fixed distribution [5] or in which the item sizes are adversarial but the items arrive in random order [8].

In this article, we study the asymptotic average performance ratio and the asymptotic random-order ratio of DNF. We give now an intuitive explanation of these measures (formal definitions are given in Section 1.1). In order to define the former, we allow an adversary to choose an arbitrary distribution $F$ on $[0, 1]$ with finite support. The asymptotic average performance ratio $\text{AAPR}(\text{DNF}, F)$

---

* This research was supported by ERC Starting Grant 306465 (BeyondWorstCase).
of DNF with respect to the distribution $F$ is then defined as the expected competitive ratio of DNF on instances with $n \to \infty$ items whose sizes are independently drawn according to $F$. Furthermore, let $\text{AAPR}(\text{DNF}) = \inf_F \text{AAPR}(\text{DNF}, F)$. In order to define the latter, we allow an adversary to choose $n \to \infty$ item sizes $s_1, \ldots, s_n \in [0, 1]$. The asymptotic random-order ratio $\text{RR}(\text{DNF})$ is then defined as the expected competitive ratio of DNF on instances in which these items arrive in uniformly random order. It is assumed that the adversary chooses item sizes that minimize this expected value.

We prove several new results on the asymptotic average performance ratio and the asymptotic random-order ratio of DNF and the relation between these two measures. First of all, observe that both $\text{RR}(\text{DNF})$ and $\text{AAPR}(\text{DNF})$ lie between $1/2$ and $1$ because even in the worst case DNF has a competitive ratio of $1/2$. Using ideas of Kenyon [11], it follows that $\text{AAPR}(\text{DNF}) \geq \text{RR}(\text{DNF})$. We show that $\text{RR}(\text{DNF}) \leq \text{AAPR}(\text{DNF}) \leq 2/3$, which improves a result by Christ et al. [3] who proved that $\text{RR}(\text{DNF}) \leq 4/5$. To the best of our knowledge the bound by Christ et al. is the only non-trivial result about the random-order ratio of DNF in the literature.

Csirik et al. [5] have proved that $\text{AAPR}(\text{DNF}, F) = 2/3$ if $F$ is the uniform distribution on $[0, 1]$. We are not aware, however, of any lower bound for $\text{AAPR}(\text{DNF}, F)$ that holds for any discrete distribution $F$, except for the trivial bound of $1/2$. We obtain the first such bound and prove that $\text{AAPR}(\text{DNF}) \geq 1/2 + \epsilon$ for a small but constant $\epsilon > 0$. We prove even better lower bounds for certain classes of distributions that we will describe in detail in Section 1.4. Finally we study the connection between the performance measures and prove that $\text{AAPR}(\text{DNF}) = \text{RR}(\text{DNF})$ if the adversary in the random-order model is restricted to inputs $s_1, \ldots, s_n$ with $\sum_i s_i = \omega(n^{2/3})$.

1.1 Performance Measures

Before we discuss our results in more detail and mention further related work, let us formally introduce the performance measures that we employ.

**Definition 1.** A discrete distribution $F$ is defined by a vector $s = (s_1, \ldots, s_m)$ of non-negative rational item sizes and an associated vector $p = (p_1, \ldots, p_m)$ of positive rational probabilities such that $\sum_{i=1}^m p_i = 1$.

We denote by $I_n(F) = (X_1, \ldots, X_n)$ a list of $n$ items, where the $X_i$ are drawn i.i.d. according to $F$. For an algorithm $A$ and a list of item sizes $L$ we denote by $A(L)$ the number of bins that $A$ fills on input $L$.

**Definition 2.** Let $A$ be an algorithm for the bin covering problem, and let $F$ be a discrete distribution. We define the asymptotic average performance ratio as

$$\text{AAPR}(A, F) = \lim_{n \to \infty} \inf_F \mathbb{E}\left[\frac{A(I_n(F))}{\text{OPT}(I_n(F))}\right]$$

and the asymptotic expected competitive ratio as

$$\text{AECR}(A, F) = \lim_{n \to \infty} \frac{\mathbb{E}[A(I_n(F))]}{\mathbb{E}[\text{OPT}(I_n(F))]}.$$ 

For a set $\mathcal{F}$ of discrete distributions, we define

$$\text{AAPR}(A, \mathcal{F}) = \inf_{F \in \mathcal{F}} \text{AAPR}(A, F) \quad \text{and} \quad \text{AECR}(A, \mathcal{F}) = \inf_{F \in \mathcal{F}} \text{AECR}(A, F).$$

We denote by $\mathcal{D}$ the set of all discrete distributions and we define

$$\text{AAPR}(A) = \text{AAPR}(A, \mathcal{D}) \quad \text{and} \quad \text{AECR}(A) = \text{AECR}(A, \mathcal{D}).$$

Both the asymptotic average performance ratio and the asymptotic expected competitive ratio have been studied in the literature (sometimes under different names). We will see later that for our purposes there is no need to distinguish between them because they coincide for DNF.

Let $L = (a_1, \ldots, a_N)$ be a list of length $N$, and let $\sigma \in S_N$ be a permutation of $N$ elements ($S_N$ denotes the symmetric group of order $N$). Then $\sigma(L)$ denotes a permutation of $L$. 
Definition 3. In bin covering, the asymptotic random-order ratio for an algorithm $A$ is defined as
\[
RR(A) = \liminf_{\text{OPT}(L) \to \infty} \frac{E_{\sigma}[A(\sigma(L))]}{\text{OPT}(L)},
\]
where $\sigma$ is drawn uniformly from $S_{|L|}$.

The asymptotic random-order ratio for bin covering and bin packing has been introduced in \cite{3} and \cite{11}, respectively. All definitions above can also be adapted to the bin packing problem; we only have to replace inf and lim inf by sup and lim sup, respectively.

1.2 Related Work

Csirik et al. \cite{6} presented an algorithm (which requires an unlimited number of open bins) whose asymptotic average performance ratio is $1$ for all discrete distributions. Csirik et al. \cite{5} have proved that the asymptotic expected competitive ratio of DNF is $\frac{2}{e}$ if $F$ is the uniform distribution on $[0,1]$. Kenyon \cite{11} introduced the notion of asymptotic random-order ratio for bin packing and proved that the asymptotic random-order ratio of the best-fit algorithm lies between 1.08 and 1.5. Coffman et al. \cite{10} showed that the random-order ratio of the next-fit algorithm is 2. Christ et al. \cite{3} adapted the asymptotic random-order ratio to bin covering and proved that $RR(DNF) \leq \frac{4}{5}$. The article of Kenyon \cite{11} contains in Section 3 an argument for $AECR(DNF) \geq RR(DNF)$ (even though this is not stated explicitly). Asgeirsson and Stein \cite{1} developed a heuristic for online bin covering based on Markov chains and demonstrated its good performance in experiments.

1.3 Definitions and Notation

Let $L = (a_1, \ldots, a_N) \in [0,1]^N$ be a list of items. We denote by $s(L) := \sum_{i=1}^{N} a_i$ the total size of the items in $L$ and by $N(L) := N$ the length of $L$. For an algorithm $A$, we define $W^A(L) := s(L) - A(L)$ as the \textit{waste of algorithm $A$ on list $L$}. We denote by OPT an optimal offline algorithm. Of particular interest are distributions that an optimal offline algorithm can pack with sublinear waste.

Definition 4. We say that a discrete distribution $F$ is a \textit{perfect-packing distribution}, if it satisfies the \textit{perfect-packing property}, i.e.,
\[
E[W^{\text{OPT}}(I_n(F))] = o(n).
\]

We denote the set of all perfect-packing distributions by $\mathcal{P}$.

Let $F$ be a discrete distribution with associated item sizes $s = (s_1, \ldots, s_m)$ and probabilities $p = (p_1, \ldots, p_m)$. We say that $b = (b_1, \ldots, b_m) \in \mathbb{N}_0^m$ is a \textit{perfect-packing configuration}, if $\sum_{i=1}^{m} b_i s_i = 1$. Let $A_F$ denote the closure under convex combinations and positive scalar multiplication of the set of perfect-packing configurations. Courcoubetis and Weber \cite{4} found out, that $F$ is a perfect-packing distribution if and only if $p \in A_F$.

Let $L = (a_1, \ldots, a_N)$ be a list. We say that a discrete distribution $F$ is induced by $L$, if the vector of item sizes $(s_1, \ldots, s_m)$ contains exactly all the item sizes arising in $L$, and the vector of probabilities $p$ is given by $p_i := p(s_i) = |\{1 \leq j \leq N : a_j = s_i\}|/N$. Vice versa we can find for every discrete distribution $F$ a list $L$, such that $F$ is induced by $L$.

1.4 Outline and Our Results

In Section \ref{2} we discuss how DNF can be interpreted as a Markov chain and we prove some properties using this interpretation. We investigate how the different performance measures are related and we point out that $AECR(DNF, F) = AAPR(DNF, F)$ for any discrete distribution $F$. Since the asymptotic expected competitive ratio and the asymptotic average performance ratio coincide for all discrete distributions, we will only consider the former in the following even though all mentioned results are also true for the latter. The main result of Section \ref{3} is a proof that $AECR(DNF) = RR(DNF)$ if the adversary in the random-order model is restricted to inputs $s_1, \ldots, s_n$ with $\sum s_i = \omega(n^{2/3})$. 
We start Section 4 by showing that perfect-packing distributions are the worst distributions for the considered measures, i.e., $\text{AECR(DNF, } \mathcal{P}) = \text{AECR(DNF)}$. Similarly we show that for proving a lower bound on the random order ratio of DNF it suffices to consider sequences of items that can be packed with waste zero. Then we show that $\text{AECR(DNF)} \leq \frac{2}{3}$, which implies $\text{RR(DNF)} \leq \frac{2}{3}$.

The main contribution of Section 4 are various new lower bounds on the asymptotic expected competitive ratio of DNF. We first prove that $\text{AECR(DNF)} \geq \frac{1}{2} + \epsilon$ for a small but constant $\epsilon > 0$. Then we consider the following special cases for which we show better lower bounds.

- Let $\mathcal{P}_x$ be the set of all perfect packing distributions, where the maximum item size is bounded from above by $x$. For $x \in [1/2, 1]$, we prove by an application of Lorden's inequality for the overshoot of a stopped sum of random variables that $\text{AECR(DNF, } \mathcal{P}_x) \geq \frac{2}{3} x^2 + \frac{1}{2} (1 - x^2)$.

- Let $F$ be a discrete perfect-packing distribution with associated item sizes $s = (s_1, \ldots, s_m)$ and probabilities $p = (p_1, \ldots, p_m)$. According to our discussion after Definition 3 the vector $p$ lies in $A_F$. Hence, there exist perfect-packing configurations $b^1, \ldots, b^N$ and coefficients $\alpha_1, \ldots, \alpha_N \geq 0$ with $p = \alpha_1 b^1 + \ldots + \alpha_N b^N$. We denote the smallest $N$ for which such $b^i$ and $\alpha_i$ exist the degree of $p$. Let $\mathcal{P}(N)$ denote all discrete perfect-packing distributions with degree $N$. We prove that

$$\frac{2}{3} \leq \text{AECR(DNF, } \mathcal{P}(1)) \leq \left(1 + \sum_{i=2}^{\infty} \frac{1}{2} \cdot (1 - \frac{1}{2})^{i-2}\right)^{-1} \approx 0.686.$$ 

If the maximum item size is greater than or equal to $\frac{1}{2}$ the lower bound can be improved to $(1 + \sum_{i=2}^{\infty} \frac{1}{2} \cdot (1 - \frac{1}{2})^{i-2})^{-1} \approx 0.686$.

- Let $F$ be a discrete perfect-packing distribution with items $s = (s_1, \ldots, s_m)$ and probabilities $p = (p_1, \ldots, p_m)$ and let $p = \alpha_1 b^1 + \ldots + \alpha_N b^N$ for perfect-packing configurations $b^1, \ldots, b^N$ and coefficients $\alpha_1, \ldots, \alpha_N \geq 0$. Let $\mathcal{P}_\text{two}$ denote all discrete perfect-packing distributions for which there exists such a representation in which every perfect-packing configuration $b^i$ contains at most two non-zero entries. We show that $\text{AECR(DNF, } \mathcal{P}_\text{two}) = \frac{2}{3}$.

In Section 5 we give some conclusions and present open problems. Appendix A contains some basics about Markov chains, and Appendix B the proofs of two statements that we skipped in the main part.

2 Basic Statements

Let $L_1$ and $L_2$ be two lists and let $L_1L_2$ denote the concatenation of them. At first, we want to point out that OPT as well as DNF are superadditive, i.e., it holds $\text{OPT}(L_1) + \text{OPT}(L_2) \leq \text{OPT}(L_1L_2)$ and $\text{DNF}(L_1) + \text{DNF}(L_2) \leq \text{DNF}(L_1L_2)$. Now let $F$ be a fixed discrete distribution. The limits $\gamma'(F) := \lim_{n \rightarrow \infty} \mathbb{E}[\text{OPT}(I_n(F))] / n$ and $\lim_{n \rightarrow \infty} \mathbb{E}[\text{DNF}(I_n(F))] / n$ exist due to Fekete’s lemma. This guarantees that the liminf in the definition of $\text{AECR(DNF, F)}$ is in fact a limit.

Furthermore, the performance measures mentioned in Definition 2 coincide in our case:

**Lemma 5.** Let $F$ be a discrete distribution. It holds

$$\text{AAPR(DNF, } F) = \text{AECR(DNF, } F).$$

A proof of a similar statement can be found in the extended version of [10]. For our purposes it is easier to deal with $\text{AECR(DNF, } F)$, so we will only mention this measure in the following.

In order to study $\mathbb{E}[\text{DNF}(I_n(F))]$, it will be useful to think of $\text{DNF}(I_n(F))$ as a Markov chain. We will give a brief introduction to Markov chains in Section A in the appendix. A comprehensive overview can be found in [13]. The state space is given by the possible arising bin levels, where we subsume all bin levels greater than or equal to 1 and the bin level 0 to a special state, which we call the closed state. This Markov chain is irreducible.

Sometimes it will be necessary that the Markov chain does not start in the closed state, but with bin level $\ell$. $\text{DNF}(\ell, L)$ denotes the number of bins that DNF closes on input $L$, starting with bin level $\ell$. We set $\text{DNF}(L) := \text{DNF}(c, L)$, where $c$ denotes the closed state.

A first important observation is that we can restrict ourselves to discrete distributions $F$, such that the Markov chain induced by $F$ and DNF is aperiodic.
Lemma 6. Let $F$ be a discrete distribution and $d \in \mathbb{N}_{\geq 2}$. If the Markov chain induced by $F$ and DNF is $d$-periodic then AECR(DNF, $F$) = 1.

Proof. We show that if the Markov chain, induced by $F$ and DNF is $d$-periodic with $d \geq 2$, then all item sizes lie in the interval $[d^{-1}, (d-1)^{-1})$. In this case we cannot perform better than putting $d$ arbitrary items in a bin.

Let $(s_1, \ldots, s_m)$ be the vector of item sizes corresponding to $F$. We assume that $s_1$ is the largest item size, and $s_m$ the smallest. W.l.o.g. we can assume that $s_m > 0$. Since the Markov chain is $d$-periodic, it is clear that $(d-1) \cdot s_1 < 1$ and $d \cdot s_1 \geq 1$. Therefore $s_1 \in [d^{-1}, (d-1)^{-1})$. Let $b \in \mathbb{N}$ such that $(b-1)\cdot s_m < 1$ and $b \cdot s_m \geq 1$. It follows from the $d$-periodicity that $b = kd$, where $k \in \mathbb{N}$.

Then $s_m \in [b^{-1}, (b-1)^{-1}) = [(kd)^{-1}, (kd-1)^{-1})$. Now look at the sequence consisting of $kd - 2$ times item $s_m$ and finally one time item $s_1$. Then

$$(kd - 2) \cdot \frac{1}{kd} + \frac{1}{d} \geq 1,$$

if and only if $k \geq 2$. That means, if $k \geq 2$, there exists a sequence of items, which closes a bin using $(kd-1)$ items, which is a contradiction to $d$-periodicity. Hence, $k = 1$ and $s_m \in [d^{-1}, (d-1)^{-1})$. \(\square\)

Therefore, we will assume in the following that the Markov chain induced by a discrete distribution $F$ and DNF is aperiodic, and so it converges to a unique stationary distribution $\pi$. It holds $\pi_F(c) = \mathbb{E} \left[ T_{\text{DNF}}^{F} \right]^{-1}$, where $T_{\text{DNF}}^{F}$ denotes the number of items we need to close a bin, starting with bin level zero.

Lemma 7. Let $F$ be a perfect-packing distribution and $X$ be distributed according to $F$. Then

$$\lim_{n \to \infty} \frac{\mathbb{E} \left[ \text{OPT}(I_n(F)) \right]}{n} = \mathbb{E} \left[ X \right].$$

For every discrete distribution $F$, it holds

$$\lim_{n \to \infty} \frac{\mathbb{E} \left[ \text{DNF}(I_n(F)) \right]}{n} = \frac{1}{\mathbb{E} \left[ T_{\text{DNF}}^{F} \right]}.$$

Proof. We start proving the first equation. It holds

$$n \cdot \mathbb{E} \left[ X \right] = \mathbb{E} \left[ s(I_n(F)) \right] = \mathbb{E} \left[ \text{OPT}(I_n(F)) \right] + \mathbb{E} \left[ W^{\text{OPT}}(I_n(F)) \right].$$

Since $F$ is a perfect-packing distribution, it follows that

$$|n \cdot \mathbb{E} \left[ X \right] - \mathbb{E} \left[ \text{OPT}(I_n(F)) \right]| = o(n).$$

Hence,

$$\lim_{n \to \infty} \frac{\mathbb{E} \left[ \text{OPT}(I_n(F)) \right]}{n} = \mathbb{E} \left[ X \right].$$

To prove the second equation we distinguish two cases. At first we assume that the Markov chain induced by DNF and $F$ is $d$-periodic, where $d \geq 2$. We know from the proof of Lemma 6 that in this case $T_{\text{DNF}}^{F} = d$. Therefore $\mathbb{E} \left[ \text{DNF}(I_n(F)) \right] = \left\lfloor \frac{4}{d} \right\rfloor$. Hence

$$\lim_{n \to \infty} \frac{\mathbb{E} \left[ \text{DNF}(I_n(F)) \right]}{n} = \frac{1}{d} = \frac{1}{\mathbb{E} \left[ T_{\text{DNF}}^{F} \right]}.$$ 

If the induced Markov chain is aperiodic, then

$$|\mathbb{E} \left[ \text{DNF}(0, I_n(F)) \right] - \mathbb{E}_{s \sim \pi_F} \left[ \text{DNF}(s, I_n(F)) \right]| \leq 1.$$ 

It holds $\mathbb{E}_{s \sim \pi_F} \left[ \text{DNF}(s, I_n(F)) \right] = n \cdot \pi_F(c)$ and $\pi_F(c) = \mathbb{E} \left[ T_{\text{DNF}}^{F} \right]^{-1}$, so

$$\lim_{n \to \infty} \frac{\mathbb{E} \left[ \text{DNF}(I_n(F)) \right]}{n} = \lim_{n \to \infty} \frac{n \cdot \pi_F(c)}{n} = \frac{1}{\mathbb{E} \left[ T_{\text{DNF}}^{F} \right]},$$

\(\square\)

So, if $F$ is a perfect-packing distribution, it holds

$$\text{AECR}(\text{DNF}, F) = \frac{1}{\mathbb{E} \left[ X \right] \cdot \mathbb{E} \left[ T_{\text{DNF}}^{F} \right]}, \quad (1)$$

Probabilistic Analysis of the Dual Next-Fit Algorithm for Bin Covering 5
3 Connection between Asymptotic Expected Competitive Ratio and Random-order Ratio

In this section we want to examine the connection between the asymptotic expected competitive ratio and the random-order ratio. At first we want to mention a result, which follows from [9].

**Lemma 8.** It holds

\[
\text{RR}(\text{DNF}) \leq \text{AECR}(\text{DNF}).
\]

**Proof.** Let \( L_n = \{L = (a_1, \ldots, a_n) : \mathbb{P}[I_n(F) = L] > 0\} \). Then there exists a set of lists \( \mathcal{L}_n \), such that \( L_n = \bigcup_{H \in \mathcal{L}_n} \{L : \exists \sigma \in S_n \text{ s.t. } L = \sigma(H)\} \). Using the inequality \( (\sum_{i=1}^{n} b_i)/(\sum_{i=1}^{n} c_i) \geq \min_{1 \leq i \leq n} (b_i/c_i) \), it follows

\[
\frac{\mathbb{E}[\text{DNF}(I_n(F))]}{\mathbb{E}[\text{OPT}(I_n(F))]} \geq \min_{H \in \mathcal{L}_n} \frac{\mathbb{E}_\sigma[\text{DNF}(\sigma(H))]}{\mathbb{E}_\sigma[\text{OPT}(\sigma(H))]} = \min_{H \in \mathcal{L}_n} \frac{\mathbb{E}_\sigma[\text{DNF}(\sigma(H))]}{\text{OPT}(H)}.
\]

We will show that the performance measures coincide if the sum of the items increases fast enough in terms of the number of items. A side product of the results of this section is the following: In [8] the authors noted that in bin packing for the algorithm Next-fit and a certain list \( L \), the following relationship holds:

\[
\lim_{j \to \infty} \frac{\mathbb{E}_\sigma[\text{NF}(\sigma(L^j))] - \mathbb{E}_\sigma[\text{OPT}(\sigma(L^j))]}{\mathbb{E}_\sigma[\text{OPT}(\sigma(L^j))]} = \text{AECR}(\text{NF}, F),
\]

where \( L^j \) denotes the concatenation of \( j \) copies of \( L \) and \( F \) is the discrete distribution induced by \( L \). They asked if this result holds for arbitrary lists \( L \). We can show that the answer is true in the context of DNF.

In the following let \( K \) denote a universal constant, which does not depend on the considered list \( L \). We establish the following two bounds:

**Theorem 9.** Let \( L \) be an arbitrary instance and let \( F \) be the induced discrete distribution. Then it holds

\[
|\text{OPT}(L) - N(L) \cdot \gamma(F)| \leq K \cdot N(L)^{2/3}.
\]

**Theorem 10.** Let \( L \) be an arbitrary instance and let \( F \) be the induced discrete distribution. We assume that the Markov chain induced by DNF and \( F \) possesses a unique stationary measure \( \pi_F \). Then it holds

\[
|\mathbb{E}_\sigma[\text{DNF}(\sigma(L))] - N(L) \cdot \pi_F(c)| \leq K \cdot N(L)^{2/3}.
\]

The first step of the proofs is to split up \( I_{N(L)}(F) \) or \( \sigma(L) \) into smaller sublists, an idea which was brought up in [8]. The following lemma shows that the difference between sampling with and without replacement can be controlled if the length of the sublists is sufficiently small compared to \( N(L) \).

**Lemma 11.** Let \( L = (a_1, \ldots, a_N) \), \( F \) be the corresponding induced discrete distribution, and \( b \in \mathbb{N} \). We set \( \sigma(L)_{[1:b]} = (a_{\sigma(1)}, \ldots, a_{\sigma(b)}) \), where \( \sigma \) is an arbitrary permutation of \( L \). Then for \( A \in \{\text{DNF, OPT}\} \) it holds

\[
|\mathbb{E}[A(\sigma(L)_{[1:b]})] - \mathbb{E}[A(b_0(F))]| \leq \frac{b^3}{N}.
\]

The proof of the lemma is based on estimates of the total variation distance. For the sake of readability, we skip here the proof and refer to the appendix. The proofs of Theorem 9 and 10 are somehow similar. Since the proof of the second is more compact, we present here only this one and defer the first one also to the appendix.
Proof (Theorem 11). Let \( L = (a_1, \ldots, a_N) \). For sake of readability we write \( N \) instead of \( N(L) \), and set \( L^o := \sigma(L) \). We divide \( L^o \) into \( \left\lceil \frac{N}{b} \right\rceil \) sublists \( L_i^o, \ldots, L_{\left\lceil \frac{N}{b} \right\rceil}^o \). Here, for \( 1 \leq i \leq \left\lceil \frac{N}{b} \right\rceil - 1 \), it is \( L_i^o = (a_{(i-1)b+1}, \ldots, a_{ib}) \), and \( L_{\left\lceil \frac{N}{b} \right\rceil}^o = (a_{(\left\lceil \frac{N}{b} \right\rceil)b+1}, \ldots, a_N) \). By \( \mu_i \), we denote the distribution of the bin level of DNF after inserting the first \((i-1)b\) items from a random permutation of \( L \).

Then it holds

\[
\mathbb{E}_\sigma [\text{DNF}(\sigma(L))] = \sum_{i=1}^{\left\lceil \frac{N}{b} \right\rceil} \mathbb{E}_{\ell \sim \mu_i} [\text{DNF}(\ell, L_i^o)] 
\]

\[
= \left( \left\lceil \frac{N}{b} \right\rceil - 1 \right) \mathbb{E}_{\ell \sim \pi_F} [\text{DNF}(\ell, I_b(F))] 
\]

\[
+ \sum_{i=1}^{\left\lceil \frac{N}{b} \right\rceil - 1} (\mathbb{E}_{\ell \sim \mu_i} [\text{DNF}(\ell, L_i^o)] - \mathbb{E}_{\ell \sim \pi_F} [\text{DNF}(\ell, I_b(F))]) 
\]

\[
+ \sum_{i=1}^{\left\lceil \frac{N}{b} \right\rceil} (\mathbb{E}_{\ell \sim \mu_i} [\text{DNF}(\ell, I_b(F))] - \mathbb{E}_{\ell \sim \pi_F} [\text{DNF}(\ell, I_b(F))]) 
\]

\[
+ \mathbb{E}_{\ell \sim \mu_{\left\lceil \frac{N}{b} \right\rceil}} [\text{DNF}(\ell, L_{\left\lceil \frac{N}{b} \right\rceil}^o)]. 
\]

We now have to bound the differences, which stem from different underlying probability measures and different starting points. According to Lemma 11 it is

\[
|\mathbb{E}_{\ell \sim \mu_i} [\text{DNF}(\ell, L_i^o)] - \mathbb{E}_{\ell \sim \mu_i} [\text{DNF}(\ell, I_b(F))]| \leq \frac{b^2}{N}. \tag{3}
\]

Furthermore, it is easy to show, that for DNF

\[
|\mathbb{E}_{\ell \sim \mu_i} [\text{DNF}(\ell, I_b(F))] - \mathbb{E}_{\ell \sim \pi_F} [\text{DNF}(\ell, I_b(F))]| \leq 1. \tag{4}
\]

Using (3) and (4) we achieve the upper bound

\[
\mathbb{E}_\sigma [\text{DNF}(\sigma(L))] \leq \frac{N}{b} \cdot \mathbb{E}_{\ell \sim \pi_F} [\text{DNF}(\ell, I_b(F))] + \frac{N}{b} \cdot \frac{b^2}{N} + \frac{N}{b} \cdot 1 + b 
\]

\[
= \frac{N}{b} \cdot b \cdot \pi_F(c) + b^2 + \frac{N}{b} \cdot b 
\]

\[
\leq N \cdot \pi_F(c) + K \cdot N^{2/3}. 
\]

In the same way, we could derive the lower bound. \( \square \)

As a consequence of both bounds, we can give a non-trivial condition, which guarantees that the random-order ratio and the asymptotic expected competitive ratio coincide.

**Theorem 12.** If there exists a sequence of lists \( L^{(i)} \) such that

\[
\lim_{i \to \infty} \frac{\mathbb{E}_\sigma [\text{DNF}(\sigma(L^{(i)}))]}{\text{OPT}(L^{(i)})} = \text{RR}(\text{DNF}),
\]

and \( s(L^{(i)}) \in \omega(N(L^{(i)})^{2/3}) \), then \( \text{RR}(\text{DNF}) = \text{AECR}(\text{DNF}) \).

**Proof.** Let \( \epsilon > 0 \) be arbitrary. Since \( s(L^{(i)}) \geq \text{OPT}(L^{(i)}) \geq \text{DNF}(L^{(i)}) \geq s(L^{(i)})/2 \), it also holds \( \text{OPT}(L^{(i)}) \in \omega(N(L^{(i)})^{2/3}) \). Let \( F^c \) denote the discrete distribution induced by \( L^{(i)} \). Using that \( \text{AECR}(\text{DNF}, F^c) = \pi_F(c)/\gamma(F^c) \) and the basic inequality \(|a/b - a'/b'| \leq |(a-a')/b| + |a'/b'| \cdot |b-b'|/b| \), we obtain

\[
\left| \frac{\mathbb{E}_\sigma [\text{DNF}(L^{(i)})]}{\text{OPT}(L^{(i)})} - \text{AECR}(\text{DNF}, F^c) \right| \leq K \cdot \frac{N(L^{(i)})^{2/3}}{\text{OPT}(L^{(i)})},
\]
Hence, if we choose $i$ large enough, we can find a distribution $F^i$, such that $\text{AECR}(\text{DNF}, F^i) \leq \text{RR}(\text{DNF}) + \epsilon$. Then

$$\text{RR}(\text{DNF}) + \epsilon \geq \text{AECR}(\text{DNF}, F^i) \geq \text{AECR}(\text{DNF}) \geq \text{RR}(\text{DNF}),$$

i.e., both performance measures would coincide. $\square$

The following corollary follows from the proof of Theorem 12.

**Corollary 13.** Let $\text{RR}'(\text{DNF})$ denote the random-order ratio of DNF restricted to instances $L$ with $s(L) \in \omega(N(L)^{2/3})$. It holds $\text{RR}'(\text{DNF}) = \text{AECR}(\text{DNF})$.

Using the same method as in the proof we can also show that (2) holds true for the dual next-fit algorithm.

## 4 Upper and Lower Bounds for Dual Next-Fit on Perfect-packing Distributions

At first we show that we can restrict ourselves to studying perfect-packing distributions. They represent the worst-case with respect to the investigated performance measures.

**Lemma 14.** Let $L = (a_1, \ldots, a_N)$ be a list for bin covering. Then there exists a list $H$ that can be packed perfectly, i.e., $W_{\text{OPT}}(H) = 0$, such that

$$\frac{\mathbb{E}_\sigma [\text{DNF}(\sigma(L))]}{\text{OPT}(L)} \geq \frac{\mathbb{E}_\sigma [\text{DNF}(\sigma(H))]}{\text{OPT}(H)}.$$

Furthermore, for each distribution $F$ there exists a perfect-packing distribution $G$ such that

$$\lim_{n \to \infty} \frac{\mathbb{E}[\text{DNF}(I_n(F))]}{\mathbb{E}[\text{OPT}(I_n(F))]} \geq \lim_{n \to \infty} \frac{\mathbb{E}[\text{DNF}(I_n(G))]}{\mathbb{E}[\text{OPT}(I_n(G))]}.$$

**Proof.** Let $L = (a_1, \ldots, a_N)$ be a list. Then we can modify the items in such a way that we obtain a new list $H = (\tilde{a}_1, \ldots, \tilde{a}_N)$, such that $a_i \geq \tilde{a}_i$ for all $i \in [N]$, $W_{\text{OPT}}(H) = 0$, and $\text{OPT}(L) = \text{OPT}(H)$. Due to the monotonicity properties of DNF, it holds $\text{DNF}(\sigma(L)) \geq \text{DNF}(\sigma(H))$ for an arbitrary permutation $\sigma$. Hence,

$$\frac{\mathbb{E}_\sigma [\text{DNF}(\sigma(L))]}{\text{OPT}(L)} \geq \frac{\mathbb{E}_\sigma [\text{DNF}(\sigma(H))]}{\text{OPT}(H)}.$$

Now let $F$ be a discrete distribution and $L = (a_1, \ldots, a_N)$ be a list, which induces $F$ and minimizes $W_{\text{OPT}}(L)/N(L)$. We modify $L$ in the same way as in the previous case, and let $H$ denote the modified list. We denote by $L^j$ (or $H^j$) the concatenation of $j$ copies of $L$ (or $H$), and $G$ denotes the perfect-packing distribution induced by $H$. For each $j \in \mathbb{N}$ it holds $\text{OPT}(L^j) = \text{OPT}(H^j)$, otherwise there is a contradiction to the choice of $L$.

Furthermore, each $L^j$ induces $F$, and each $H^j$ induces $G$. Therefore, we know from Lemma 30 and 31 that

$$|\mathbb{E}[\text{OPT}(I_{jN}(F))] - \mathbb{E}[\text{OPT}(I_{jN}(G))]| \leq K \cdot N^{2/3} \cdot j^{2/3}.$$

$\mathbb{E}[\text{OPT}(I_{jN}(F))]$ grows linearly in $j$, and $\text{DNF}(I_{jN}(F)) \geq \text{DNF}(I_{jN}(G))$. Hence,

$$\lim_{n \to \infty} \frac{\mathbb{E}[\text{DNF}(I_n(F))]}{\mathbb{E}[\text{OPT}(I_n(F))]} \geq \lim_{j \to \infty} \frac{\mathbb{E}[\text{DNF}(I_{jN}(G))]}{\mathbb{E}[\text{OPT}(I_{jN}(G))]} = \lim_{n \to \infty} \frac{\mathbb{E}[\text{DNF}(I_n(G))]}{\mathbb{E}[\text{OPT}(I_n(G))]}$$

$\square$
4.1 Upper and Lower Bounds for Arbitrary Perfect-packing Distributions

We begin presenting an upper bound for the considered performance measures, which improves a result in [3].

**Theorem 15.** It holds

\[ \text{RR}(\text{DNF}) \leq \text{AECR}(\text{DNF}) \leq \frac{2}{3}. \]

**Proof.** Let \( F(m, k) \) be the uniform distribution on the item sizes

\[
\left( \frac{1}{k} - 1 \right)^2, 1 - \left( \frac{1}{k} \right)^2, \ldots, \left( \frac{1}{k} \right)^m, 1 - \left( \frac{1}{k} \right)^m. \]

It is clear, that \( F(m, k) \) is a perfect-packing distribution. We show that for every \( \epsilon > 0 \) there are parameters \( m \) and \( k \), such that \( \mathbb{E} \left[ T_{\text{DNF}}^{F(m,k)} \right] \geq 3 - \epsilon \).

It holds

\[
\mathbb{E} \left[ T_{\text{DNF}}^{F(m,k)} \right] = \sum_{i=0}^{\infty} \mathbb{P} \left[ T_{\text{DNF}}^{F(m,k)} > i \right] \geq 2 + \sum_{i=2}^{k-1} \mathbb{P} \left[ T_{\text{DNF}}^{F(m,k)} > i \right].
\]

Simple counting yields for \( i \geq 2 \)

\[
\mathbb{P} \left[ T_{\text{DNF}}^{F(m,k)} > i \right] = \frac{m^i}{(2m)^i} + \frac{1}{(2m)^i} \sum_{j=2}^{m} j \cdot (j-1)^{i-1} = \frac{1}{2^i} + \frac{i}{2m^i} \sum_{j=1}^{m-1} j^{i-1}
\]

\[
\geq \frac{1}{2^i} + \frac{i}{2m^i} \cdot \int_{0}^{m-1} x^{i-1} \, dx = \frac{1}{2^i} \cdot \left[ 1 + \left( 1 - \frac{1}{m} \right)^i \right].
\]

Therefore, if we choose at first \( k \), and then \( m \) large enough

\[
\mathbb{E} \left[ T_{\text{DNF}}^{F(m,k)} \right] \geq 2 + \sum_{i=2}^{k-1} \frac{1}{2^i} \cdot \left[ 1 + \left( 1 - \frac{1}{m} \right)^i \right] \geq 3 - \epsilon.
\]

Using Lemma [7] the statement follows. \( \square \)

Now we show, that in a probabilistic setting, we behave better than in the worst-case.

**Theorem 16.** There exists an \( \epsilon > 0 \) such that

\[ \text{AECR}(\text{DNF}) \geq \frac{1}{2} + \epsilon. \]

**Proof.** Let \( X_1, X_2, \ldots \) denote i.i.d. random variables distributed according to \( F \), and \( S_n = \sum_{i=1}^{n} X_i \). The waste, which occurs closing the bin, is given by \( R = S_{T_{\text{DNF}}} - 1 \). We will denote \( R \) also as overshoot. Due to Wald’s equation it holds that \( 1 + \mathbb{E} [R] = \mathbb{E} \left[ S_{T_{\text{DNF}}} \right] = \mathbb{E} \left[ T_{\text{DNF}}^{F} \right] \cdot \mathbb{E} \left[ X \right] \). From [11] it follows that \( \text{AECR}(\text{DNF}, F) = (1 + \mathbb{E} [R])^{-1} \). We show that there exists an \( \epsilon > 0 \), independent of the perfect-packing distribution \( F \), such that \( \mathbb{E} [R] \leq 1 - \epsilon \).

We assume that \( F \) is induced by \( \ell^* \) perfectly packed bins and a uniform distribution on the items. Otherwise we could copy bins to achieve such a setting. We call an item large if it is strictly larger than 1/2. Otherwise we call the item small. Our goal is to show that we will close a bin with a small item with a constant probability, independent of \( F \).

We denote by \( \ell \leq \ell^* \) the number of large items and by \( n \) the number of small items. We assume that \( n \geq \ell \) and that \( n \) is a multiple of \( \ell \). If this is not the case, we add an appropriate number of items of size 0. This will not change the probability of closing a bin with a small item.

Let \( b_0, \ldots, b_{\ell} \) denote the large items and assume that \( b_1 \geq b_2 \geq \ldots \geq b_{\ell} > 1/2 \). Let \( b^* := b_{\lceil \ell/2 \rceil} \) and \( s^* = 1 - b^* \).
Let $T$ denote the time step at which we draw for the first time a large item, and let $\mathcal{E}_F$ denote the event \( \{ T \geq 15n/\ell + 1 \} \cap \{ \sum_{i=1}^{15n/\ell} X_i \geq s^* \} \). We will show after finishing this proof that for an arbitrary discrete distribution, it is \( \mathbb{P}[\mathcal{E}_F] \geq 1.1 \cdot 10^{-12} \). Let \( A := \{ \sum_{i=1}^{n-1} X_i < 1/2 \} \). We set \( q := \mathbb{P}[\mathcal{E}_F], p_1 := \mathbb{P}[\mathcal{E}_F \cap A], \) and \( p_2 := \mathbb{P}[\mathcal{E}_F \cap A^c] \). Then, the following inequalities hold:

\[
\mathbb{E}[R] \leq (1/2) \cdot p_2^2 + 1 \cdot (1 - p_2^2) = 1 - p_2^2/2 \\
\mathbb{E}[R] \leq (1/2) \cdot p_1/2 + 1 \cdot (p_1/2 + p_2 + q) = 1 - p_1/4.
\]

The first inequality follows from the observation that \( \mathbb{P}[A^c] \geq p_2^2 \) is a lower bound on the probability that the bin gets filled with only small items, in which case the waste is at most 1/2. The second inequality follows because if the event \( \mathcal{E}_F \cap A \) occurs then the small items that arrive before the first large item have a total size of at least \( s^* \) and at most 1/2. If the first large item has size at least \( b^* \), which happens with probability at least 1/2, then it closes the bin with waste at most 1/2. Since \( p_1 + p_2 \geq 1.1 \cdot 10^{-12} \), it follows that \( \mathbb{E}[R] < 1 \). \( \square \)

In the proof we have used a lower bound for the probability of \( \mathbb{P}[\mathcal{E}_F] \):

**Lemma 17.** For every discrete distribution \( F \) it is

\[ \mathbb{P}[\mathcal{E}_F] \geq 1.1 \cdot 10^{-12}. \]

The interesting part in the proof of the lemma is to show that the sum of the small items exceeds the barrier \( s^* \) with positive probability. In order to prove this we reduce the summation to a kind of coupon-collectors problem. We assume that the coupons have numbers from 1 to \( n \), and we can use for an coupon with number \( i \), also a coupon with a higher number.

Let \( m \geq n \) and \( v \in \{1, \ldots, n\}^m \). We denote by \( v^* \) the vector with the same entries as \( v \) except that the entries are ordered in non-increasing order. We say that \( v \) covers the vector \( (n, \ldots, 1) \) if \( v_i^* \geq n - i + 1 \) for all \( i \in [n] \).

**Lemma 18.** Let \( a \in \{5, 6, 7, \ldots\} \) and let \( n \in \mathbb{N} \) be arbitrary. Let \( v \) be chosen uniformly at random from \( \{1, \ldots, n\}^an \). Then the probability that \( v \) does not cover the vector \( (n, \ldots, 1) \) is bounded from above by

\[
\frac{1}{e^a - 1} + \frac{1}{ea} \left( \frac{1}{e^{a-2}/(2a)} - 1 - \frac{2a}{e^{a-2}} \right) - a.
\]

**Proof.** For \( i \in [n] \), let \( U_i \) denote the event that \( v_i^* < n - i + 1 \). The event \( U_i \) occurs if and only if the number of entries from \( \{n - i + 1, \ldots, n\} \) in \( v \) is at most \( i - 1 \). Hence,

\[
\mathbb{P}[U_i] = \mathbb{P}[\forall i \in [n] : v_i < n] = \left( 1 - \frac{1}{n} \right)^{an} \leq e^{-a}.
\]

For \( i \in \{2, \ldots, n\} \),

\[
\mathbb{P}[U_i] = \mathbb{P}[\text{at most } i - 1 \text{ entries of } v \text{ from } \{n - i + 1, \ldots, n\}]
\]

\[
= \sum_{j=0}^{i-1} \binom{an}{j} \cdot \left( 1 - \frac{i}{n} \right)^{an-j} \cdot \left( \frac{i}{n} \right)^j
\]

\[
= \left( 1 - \frac{i}{n} \right)^{an} + \sum_{j=1}^{i-1} \binom{an}{j} \cdot \left( 1 - \frac{i}{n} \right)^{an-j} \cdot \left( \frac{i}{n} \right)^j
\]

\[
\leq e^{-ia} + \sum_{j=1}^{i-1} \left( ean/j \right)^j \cdot \left( 1 - \frac{i}{n} \right)^{(a-1)n} \cdot \left( \frac{i}{n} \right)^j
\]

\[
= e^{-ia} + \left( 1 - \frac{i}{n} \right)^{(a-1)n} \sum_{j=1}^{i-1} \left( eai/j \right)^j
\]

\[
\leq e^{-ia} + e^{-i(a-1)} \cdot (ea)^{i-1} \sum_{j=1}^{i-1} \left( i/j \right)^j
\]
\[ \leq e^{-ia} + e^{-i(a-1)} \cdot (ea)^{i-1} \sum_{j=1}^{i-1} \binom{i}{j} \]

\[ \leq e^{-ia} + e^{-i(a-1)} \cdot (ea)^{i-1} \cdot 2^i. \]

The probability that \( v \) does not cover the vector \((n, \ldots, 1)\) can be bounded from above as follows:

\[ \mathbb{P}[U_1 \cup \ldots \cup U_n] \leq \sum_{i=1}^{n} \mathbb{P}[U_i] \]

\[ \leq e^{-a} + \sum_{i=2}^{n} \left( e^{-ia} + e^{-i(a-1)} \cdot (ea)^{i-1} \cdot 2^i \right) \]

\[ \leq \left( \frac{1}{1 - e^{-a}} - 1 \right) + \frac{1}{ea} \sum_{i=2}^{n} \left( \frac{2a}{e^{a-2}} \right)^i \]

\[ \leq \frac{e^{-a}}{1 - e^{-a}} + \frac{1}{ea} \left( \frac{1}{1 - 2a/e^{a-2}} - \frac{2a}{e^{a-2}} - 1 \right) \]

\[ = \frac{1}{e^a - 1} + \frac{1}{ea} \left( \frac{1}{e^{a-2}/(2a) - 1} - \frac{2a}{e^{a-2}} \right). \]

In the calculation we used that \( \frac{2a}{e^a} < 1 \) for \( a \geq 5 \). \( \square \)

**Corollary 19.** The probability that a uniform random vector from \( \{1, \ldots, n\}^5n \) does not cover the vector \((n, \ldots, 1)\) is bounded from above by 0.044.

**Proof (Lemma 17).** Using that \( n \geq \ell \), and so \( \ell/(n + \ell) \leq 1/2 \), we obtain

\[ \mathbb{P} \left[ T \geq \frac{15n}{\ell} + 1 \right] = \left( 1 - \frac{\ell}{n + \ell} \right)^{15n/\ell} \geq \left( 1 - \frac{\ell}{n + \ell} \right)^{15(n+\ell)/\ell} \geq \frac{1}{415}. \]

Let us condition in the following on the event that \( T \geq \frac{15n}{\ell} + 1 \). We now want to show, that the event, that the sum of the first \( 15n/\ell \) small items is at least \( s^* \), occurs with positive probability independent of \( F \). Thereto we partition the small items according to their size into \( n/\ell \) groups with \( \ell \) items each. The \( \ell \) smallest items are in the first group and so on. We denote by \( h \) the total size of items in the last group and \( Z \) the total size of all small items. Let \( v = (m_1, \ldots, m_{15n/\ell}) \), where \( m_i \) denotes the number of the group the \( i \)-th drawn item belongs to. We say that \( v \) covers all groups three times, if there exists a permutation \( v^* \) of \( v \) s.t. \((v_1^*, \ldots, v_{15n/\ell}^*), (v_{15n/\ell}^*, \ldots, v_{30n/\ell}^*) \) and \((v_{30n/\ell}^*, \ldots, v_{45n/\ell}^*)\) cover \((n, \ldots, 1)\) respectively. Under the condition that \( T \geq 15n/\ell + 1 \), \( v \) covers all groups three times with probability at least 0.956\(^3\) \( \geq 0.873 \) according to Corollary 13.

For \( i \in [n/\ell] \) let \( g_i \) denote the largest item in group \( i \). If all groups are covered three times, the sum of the small items drawn is at least

\[ 3 \sum_{i=1}^{n/\ell-1} g_i \geq \frac{3(Z - h)}{\ell}. \]

Furthermore, the total weight of all small items is at least

\[ Z \geq (\ell - \lfloor \ell/2 \rfloor + 1)s^* \geq \ell s^*/2. \]

For the following argument we can assume w.l.o.g. that there is no small item with size larger than \( s^* \) because we are only interested in the probability that the small items drawn add up to at least \( s^* \). If all groups are covered three times, the sum of the small items is at least

\[ 3 \sum_{i=1}^{n/\ell-1} g_i \geq \frac{3(Z - h)}{\ell} \geq \frac{3(\ell s^*/2 - h)}{\ell} = 3s^*/2 - 3h/\ell. \]
If \( h \leq \ell s^*/6 \), then the sum of the small items drawn is at least \( s^* \). Hence, in this case

\[
P[E] \geq 0.873 \cdot \frac{1}{4^{15}} \geq 8 \cdot 10^{-10}.
\]

If \( h > \ell s^*/6 \) then at least \( \ell/11 \) small items have size at least \( s^*/12 \). We can see this as follows: Let \( x \) denote the number of items in group 1, which have size at least \( s^*/12 \). Then \( h \) is bounded from above by \( xs^*/12 \). Since \( h > \ell s^*/6 \), it follows

\[
(\ell s^*/6 < h \leq xs^*/12 + (\ell - x)s^*/12).
\]

A simple computation then yields \( x > \ell/11 \). The probability that exactly 12 of these items are drawn under the condition \( T \geq 15n/\ell + 1 \) is at least

\[
\left( \frac{15n/\ell}{12} \right) \cdot \left( 1 - \frac{\ell/11}{n} \right)^{15n/\ell - 12} \cdot \left( \frac{\ell/11}{n} \right)^{12} \geq \left( \frac{15}{11 \cdot 12} \right)^{12} \cdot 0.239 \geq 1.1 \cdot 10^{-12}.
\]

\[\square\]

### 4.2 Improved Lower Bounds for Certain Classes of Perfect-packing Distributions

At first we look at the case that the maximum item size in the perfect-packing distribution is bounded from above by \( x \). Let \( \mathcal{P}_x \) denote the set of all such distributions.

**Theorem 20.** If \( x \geq \frac{1}{2} \), then

\[
\text{ACR(DNF, } \mathcal{P}_x \text{)} \geq \frac{1}{1 + x^2 + (1 - x)^2}.
\]

The given lower bound slightly improves the worst-case bound \((1 + x)^{-1}\) in the case that the maximum item size is greater than \( \frac{1}{2} \). Csirik et al. pointed out in [3] that in the case of DNF there is a connection between the bin covering problem and renewal theory, and so it is obvious to use tools from this field. The proof is based on an estimate of the overshoot, given by Lorden:

**Lemma 21 (Lorden’s inequality, [15]).** Suppose \( X_1, X_2, \ldots \) are non-negative i.i.d. random variables with \( \mathbb{E}[X_1] > 0 \) and \( \mathbb{E}[X_1^2] < \infty \). Let \( S_n = X_1 + \ldots + X_n \), \( T = \inf\{n \in \mathbb{N} : S_n \geq 1\} \), and \( R = S_T - 1 \). Then

\[
\mathbb{E}[R] \leq \mathbb{E}[X_1^2] / \mathbb{E}[X_1].
\]

**Proof (Theorem 20).** Let \( F \in \mathcal{P}_x \). We have already shown in the proof of Theorem 16 that \( \text{ACR(DNF, } F \text{)} = (1 + \mathbb{E}[R])^{-1} \). Plugging in the estimate from Lorden’s inequality yields

\[
\text{ACR(DNF, } F \text{)} \geq \left( 1 + \frac{\mathbb{E}[X_1^2]}{\mathbb{E}[X]} \right)^{-1}.
\]

Let \( \mathcal{C}(F) \) denote all perfect-packing configurations of \( F \). Since \( F \) is a perfect-packing distribution, we could write \( p_F \) as \( \sum_{b \in \mathcal{C}(F)} \lambda_b \cdot c \). Therefore,

\[
\frac{\mathbb{E}[X^2]}{\mathbb{E}[X]} = \frac{\sum_{b \in \mathcal{C}(F)} \lambda_b \sum_{i=1}^m s_i^2 b_i}{\sum_{b \in \mathcal{C}(F)} \lambda_b \sum_{i=1}^m s_i b_i} \leq \max_{b \in \mathcal{C}(F)} \frac{\sum_{i=1}^m s_i^2 b_i}{\sum_{i=1}^m s_i b_i}.
\]

Since \( c \) are perfect-packing configurations, the denominator is equal to 1 and the numerator is bounded from above by \( x^2 + (1 - x)^2 \). Plugging this into (5) yields the lower bound. \[\square\]
Now we want to look at the case $F \in \mathcal{P}^{(1)}$, i.e., we have a vector of item sizes $s$, and the vector of probabilities $p_F$ is given by $p_F = b/|b|_1$, where $b$ is a perfect-packing configuration.

**Theorem 22.** It holds

\[
\frac{2}{3} \leq \text{AECR}(\text{DNF}, \mathcal{P}^{(1)}) \leq \left( \sum_{i=1}^{\infty} \frac{(i-1)!}{i^i} \right)^{-1} \approx 0.736.
\]

If the maximum item size is greater than or equal to $\frac{1}{2}$ the lower bound can be improved to

\[
\left( 1 + \sum_{i=2}^{\infty} \frac{1}{i^2} \cdot (1 - \frac{1}{i})^{i-2} \right)^{-1} \approx 0.686.
\]

To prove this statement, we use again the coupon-collector ansatz, already used in the proof of the lower bound for arbitrary discrete distributions.

**Lemma 23.** There are $(n+1)^{n-1}$ vectors in $\{1,\ldots,n\}^n$, which cover $(n,\ldots,1)$.

**Proof.** Our covering relationship is just a reformulation of parking functions. Every vector in $\{1,\ldots,n\}^n$, which covers $(n,\ldots,1)$ is a parking function. Konheim and Weiss showed in [12] that there are $(n+1)^{n-1}$ parking functions of length $n$. \hfill \Box

**Proof (Theorem 22).** We want to look at first at the lower bound. If the maximum item size is bounded from above by $\frac{1}{2}$, then the lower bound is just the worst-case result: The total size of the items in one bin is bounded from above by $3/2$. Therefore, $(3/2) \cdot \text{DNF}(L) \geq s(L) \geq \text{OPT}(L)$. So we assume that there is an item with size greater than or equal to $1/2$.

For our construction we could assume w.l.o.g. that $F = F(m)$ is represented by $s = (s_1,\ldots,s_m)$, where $s_1 < \ldots < s_m$ and $p_F$ is the uniform distribution on $s$. We draw items i.i.d. according to $F$, and let $Y_i$ denote the index of the size of the $i$-th drawn item. Let $T(m)$ denote the first time, that $Y_1 = m$ and $Y_u = m$, where $u < t$, or that $(Y_1,\ldots,Y_t)$ covers $(m,\ldots,1)$. In both cases the sum of the items drawn is at least $1$. It is clear that $\mathbb{E} \left[ p^{(m)}_F \right] \leq \mathbb{E} \left[ T(m) \right]$, and $\mathbb{E} \left[ T(1) \right] = 1$.

Furthermore, it holds the following recursion for $m \geq 2$:

\[
\mathbb{E} \left[ T(m) \right] = \frac{m}{m-1} \mathbb{E} \left[ T(m-1) \right] + \frac{(m-1)^{m-2}}{m^{m-1}}.
\]

Let us explain this: Assume that we draw the $Y_i$ uniformly from $\{1,\ldots,m\}$, until we cover $(m,\ldots,2)$ or draw $m$ the second time. If we stop, because we have drawn $m$ the second time, then the bin is filled. If we need more than $m-1$ items to cover $(m,\ldots,2)$, then we also cover $(m,\ldots,1)$. If we have covered $(m,\ldots,2)$ with exactly $m-1$ draws, then we have to draw one more item to cover $(m,\ldots,1)$. The previous lemma reveals that there are $(m-1) \cdot (m-2 + 1)^{m-2}$ possibilities to cover $(m,\ldots,2)$ with exactly $m-1$ items, using the largest item only once. This yields the recursion.

Applying \ref{eq:recursion} several times, we achieve

\[
\mathbb{E} \left[ T(m) \right] = m \cdot \mathbb{E} \left[ T(1) \right] + \sum_{i=2}^{m} \frac{m \cdot (i-1)^{i-2}}{i^i-1} = m \cdot \left( 1 + \sum_{i=2}^{m} \frac{1}{i^2} (1 - \frac{1}{i})^{i-2} \right) \leq m \cdot \left( 1 + \sum_{i=2}^{\infty} \frac{1}{i^2} (1 - \frac{1}{i})^{i-2} \right).
\]

Plugging this into \ref{eq:lower_bound} yields the lower bound.

Now we want to show the upper bound. Assume $s_i \geq \sum_{j=i+1}^{m} s_j$ for $1 \leq i \leq m$. We use the same argumentation as before. This time we only need an extra item, if we draw a permutation of $(m,\ldots,2)$ in the first $m-1$ draws. This yields the recursion formula

\[
\mathbb{E} \left[ T(m) \right] = \frac{m}{m-1} \mathbb{E} \left[ T(m-1) \right] + \frac{(m-1)!}{m^{m-1}}.
\]
Hence
\[ E[\tilde{T}(m)] = m \cdot \sum_{i=1}^{m} \frac{(i-1)!}{i}. \]

Let \( s = \frac{1}{Z(m, \epsilon)} (1 - \epsilon, (1 - \epsilon) \cdot \epsilon, (1 - \epsilon) \cdot \epsilon^2, \ldots, (1 - \epsilon) \cdot \epsilon^{m-1}) \), where \( Z(m, \epsilon) \) is a normalisation constant. If we choose \( \epsilon \) small enough, we achieve \( E[\tilde{T}(m)] \). This yields the upper bound. \( \square \)

We see that even in the analysis of this simple case there is room for improvement. Based on simulations, we suppose that the upper bound represents the truth. Furthermore we were not able to improve the worst-case bound \( (1 + x)^{-1} \) in the case that the maximum item size is bounded from above by \( \frac{1}{2} \).

Finally, let \( P_{\text{two}} \) denote all discrete perfect-packing distributions for which there exists a representation in which every perfect-packing configuration \( b^i \) contains at most two non-zero entries.

**Theorem 24.** Let \( F \in P_{\text{two}} \), then
\[ \text{AECR}(\text{DNF}, F) \geq \frac{2}{3}. \]

**Proof.** Since every perfect-packing configurations contains only two item sizes, we can assume that \( F \) is given by the uniform distribution on the vector of item sizes \( (g_1, \ldots, g_m, s_m, \ldots, s_1) \), where \( g_1 \geq \ldots \geq g_m \geq s_m \geq \ldots \geq s_1 \), and \( g_i + s_i = 1 \) for \( 1 \leq i \leq m \). The items \( g_i \) have size at least \( \frac{1}{2} \).

Let \( \tilde{T} \) denote the first time, we have drawn two items with size at least \( \frac{1}{2} \) or a large item and a small item, such that their sum is greater than or equal to \( \frac{1}{2} \). We can compute \( \mathbb{P}[\tilde{T} > i] \) via easy counting. Using an estimate of the sum of powers of integers we achieve
\[
\mathbb{E}[T_{\text{DNF}}^F] = \sum_{i=0}^{\infty} \mathbb{P}[T_{\text{DNF}}^F > i] = 2 + \sum_{i=2}^{\infty} \mathbb{P}[\tilde{T} > i]
= 2 + \sum_{i=2}^{\infty} \left( \frac{m^i}{(2m)^i} + \frac{1}{(2m)^i} \sum_{j=2}^{m} j \cdot (j-1)^{i-1} \right)
= 2 + \frac{1}{2} + \sum_{i=2}^{\infty} \frac{1}{2^i} \cdot i \cdot \left( \frac{1}{m^i} \sum_{j=1}^{m-1} j^{i-1} \right)
\leq \frac{5}{2} + \sum_{i=2}^{\infty} \frac{1}{2^i} = 3.
\]

Plugging this into (1) yields the desired bound. \( \square \)

Combining this with the proof of Theorem 15 we obtain \( \text{AECR}(\text{DNF}, P_{\text{two}}) = 2/3 \).

## 5 Conclusions and Further Research

We have proven the first lower bound better than \( 1/2 \) for the asymptotic expected competitive ratio of DNF that holds for any discrete distribution. Our lower bound is only slightly better than \( 1/2 \) and there is still a considerable gap to the best known upper bound of \( 2/3 \), which we also proved in this article. It is an interesting problem to close the gap between the lower and the upper bound. We conjecture that the lower bound can be improved to \( 2/3 \). Furthermore, we have shown that the asymptotic random-order ratio coincides with the asymptotic expected competitive ratio under the mild assumption that the adversary is not allowed to add too many too small items. We believe that this assumption is not needed and we conjecture that also for arbitrary inputs the asymptotic random-order ratio coincides with the asymptotic expected competitive ratio for DNF.

Our analysis in Section 3 that shows the connection between the asymptotic random-order ratio and the asymptotic expected competitive ratio under the previously mentioned assumption can easily be adapted to the next-fit algorithm for bin packing. We expect that it can also be generalized to more sophisticated algorithms for bin packing (e.g., to all bounded-space algorithms with only a constant number of open bins).
References

1. Eyjolfur Ingi Asgeirsson and Cliff Stein. Bounded-space online bin cover. *Journal of Scheduling*, 12(5):461–474, 2009.
2. S. F. Assmann, David S. Johnson, Daniel J. Kleitman, and Joseph Y.-T. Leung. On a dual version of the one-dimensional bin packing problem. *Journal of Algorithms*, 5(4):502–525, 1984.
3. Marie G. Christ, Lene M. Favrholdt, and Kim S. Larsen. Online bin covering: Expectations vs. guarantees. *Theoretical Computer Science*, 556:71–84, 2014.
4. Costas Courcoubetis and Richard R. Weber. Stability of on-line bin packing with random arrivals and long-run average constraints. *Probability in the Engineering and Informational Sciences*, 4(4):447–460, 1990.
5. János Csirik, J. B. G. Frenk, Gábor Galambos, and A. H. G. Rinnooy Kan. Probabilistic analysis of algorithms for dual bin packing problems. *Journal of Algorithms*, 12(2):189–203, 1991.
6. János Csirik, David S. Johnson, and Claire Kenyon. Better approximation algorithms for bin covering. In *Proceedings of the 12th ACM-SIAM Symposium on Discrete Algorithms (SODA)*, pages 557–566, 2001.
7. János Csirik and V. Totik. Online algorithms for a dual version of bin packing. *Discrete Applied Mathematics*, 21(2):163–167, 1988.
8. J Edward G. Coffman Jr., János Csirik, Lajos Rónyai, and Ambrus Zsbán. Random-order bin packing. *Discrete Applied Mathematics*, 156(6):2810–2816, 2008.
9. Klaus Jansen and Roberto Solis-Oba. An asymptotic fully polynomial time approximation scheme for bin covering. *Theoretical Computer Science*, 306(1-3):543–551, 2003.
10. Edward G. Coffman Jr., János Csirik, Lajos Rónyai, and Ambrus Zsbán. Random-order bin packing. *Discrete Applied Mathematics*, 156(14):2810–2816, 2008.
11. Claire Kenyon. Best-fit bin-packing with random order. In *Proceedings of the 17th ACM-SIAM Symposium on Discrete Algorithms (SODA)*, pages 359–364, 1996.
12. Alan G. Konheim and Benjamin Weiss. An occupancy discipline and applications. *SIAM Journal on Applied Mathematics*, 14(6):1266–1274, 1966.
13. David A. Levin, Yuval Peres, and Elizabeth L. Wilmer. *Markov Chains and Mixing Times*. AMS, 2009.
14. Wei-Liem Loh. Stein’s method and multinomial approximation. *The Annals of Applied Probability*, 2(3):536–554, 1992.
15. Gary Lorden. On excess over the boundary. *Annals of Mathematical Statistics*, 41(2):520–527, 1970.
16. Nir Naaman and Raphael Rom. Average case analysis of bounded space bin packing algorithms. *Algorithmica*, 50:72–97, 2008.
17. Wansoo T. Rhee and Michel Talagrand. Optimal bin covering with items of random size. *SIAM Journal on Computing*, 18(3):487–498, 1989.
A Basics in Markov chains

A detailed introduction to the field of Markov chains can be found in [13]. We want to repeat here the basics, which are relevant for this paper.

Let $\Omega$ be a finite set and $P$ be a transition matrix on $\Omega$, i.e., for each $x \in \Omega$ $P(x, \cdot)$ is a probability distribution on $\Omega$.

A sequence of random variables $(X_0, X_1, \ldots)$ is a Markov chain with state space $\Omega$ and transition matrix $P$, if it holds

$$\mathbb{P} \left[ X_{t+1} = x_{t+1} \mid X_{[0:t]} = x_{[0:t]} \right] = P(x_t, x_{t+1}),$$

for all $t \in \mathbb{N}_0$ and $x_{[0:t]} \in \Omega^{t+1}$, such that $\mathbb{P} \left[ X_{[0:t]} = x_{[0:t]} \right] > 0$.

Two important properties of Markov chains are irreducibility and aperiodicity. We say that a Markov chain is irreducible, if for all $x, y \in \Omega$ there exists an $t \in \mathbb{N}$, such that $P^t(x, y) > 0$, i.e., it is possible to reach state $y$ beginning in state $x$. For each state $x \in \Omega$, we define its period as the greatest common divisor of the set $\{ t \in \mathbb{N} : P^t(x, x) > 0 \}$. We say that a Markov chain is aperiodic, if the period of every state is equal to 1. Otherwise, we say it is periodic. Furthermore, we can show that irreducibility implies that the periods of all states coincide.

We are especially interested in the long time behaviour of Markov chains. There, stationary distributions play an important role. A distribution $\pi$ on $\Omega$ is said to be stationary, if it fulfills the condition $\pi = \pi P$. We will utilize the following statement: If a Markov chain is irreducible and aperiodic, then the Markov chain possesses a unique stationary measure $\pi$, and the distribution of $X_n$ converges (exponentially) to $\pi$.

Finally, there exists an interesting connection between $\pi$ and the first return time $\tau_x$. $\tau_x$ is defined as $\inf \{ t \in \mathbb{N} : X_t = x \}$, where $X_0 = x$. Then, it holds $\pi(x) = \mathbb{E}_x [\tau_x]^{-1}$.

B Proofs of statements in Section 3

As already mentioned, $K$ denotes a universal constant, which does not depend on the considered list $L$, and could differ from line to line.

B.1 Proof of Lemma [11]

The proof of the lemma relies on the total variation distance. The total variation distance is a distance measure between two probability distributions. We will introduce the important statements for our purposes, a more thorough overview could be found in [13].

Let $\Omega$ be a discrete set.

Definition 25. The total variation distance between two probability distributions $\mu$ and $\nu$ on $\Omega$ is defined by

$$\|\mu - \nu\|_{TV} = \max_{A \subseteq \Omega} |\mu(A) - \nu(A)|.$$ 

We will work with two useful alternative characterizations of the total variation distance. One of them relies on couplings.

Definition 26. A coupling of two probability distributions $\mu$ and $\nu$ is a pair of random variables $(X, Y)$ defined on a single probability space such that the marginal distribution of $X$ is $\mu$ and the marginal distribution of $Y$ is $\nu$.

Lemma 27 (Proposition 4.2 and Proposition 4.7 in [13]). Let $\mu$ and $\nu$ be two probability distributions on $\Omega$. Then it holds

$$\|\mu - \nu\|_{TV} = \frac{1}{2} \sum_{x \in \Omega} |\mu(x) - \nu(x)|,$$

and

$$\|\mu - \nu\|_{TV} = \inf \{ \mathbb{P}[X \neq Y] : (X, Y) \text{ is a coupling of } \mu \text{ and } \nu \}.$$
A key ingredient is, that we are able to bound the difference between the expectations of $f(X)$ and $f(Y)$, where $X$ and $Y$ are random variables, in terms of the total variation distance and the infinity norm of $f$.

**Lemma 28.** Let $\mu, \nu$ be two probability distributions on $\Omega$, $X, Y : \Omega \to \mathbb{R}$ random variables with $X \sim \mu$ and $Y \sim \nu$, and $f : \Omega \to \mathbb{R}$. Then it holds

$$|\mathbb{E}[f(X)] - \mathbb{E}[f(Y)]| \leq 2\|\mu - \nu\|_{TV} \cdot \|f\|_{\infty}.$$

**Proof.** It holds

$$|\mathbb{E}[f(X)] - \mathbb{E}[f(Y)]| = \left| \sum_{x \in \Omega} (\mu(x) - \nu(x)) \cdot f(x) \right| \leq 2\|f\|_{\infty} \cdot \frac{1}{2} \sum_{x \in \Omega} |\mu(x) - \nu(x)| = 2\|f\|_{\infty} \cdot \|\mu - \nu\|_{TV}.$$

$\square$

Now we want to show that the difference between sampling with and without replacement is small, if the sample size is small compared to the universe.

**Lemma 29 (Theorem 6 in [14]).** Let $L = (a_1, \ldots, a_N)$ and let $F$ be the induced discrete distribution. We assume that $\sigma \sim \text{Unif}(S^N)$.

Let $\mu$ be the distribution of $(a_{\sigma(1)}, \ldots, a_{\sigma(n)})$, and $\nu$ the distribution of $I_n(F)$. Then

$$\|\mu - \nu\|_{TV} \leq \frac{n^2}{2N}.$$

**Proof.** We use the following coupling: Let $X$ be drawn according to $\nu$. We set

$$Y = \begin{cases} X, & \text{if } X \text{ is a legal sample w.r.t. sampling without replacement} \\ \tilde{Y}, & \tilde{Y} \sim \mu, \text{otherwise.} \end{cases}$$

Let $A$ be the event, that we draw $n$ different balls from an urn containing $N$ different balls, w.r.t. sampling with replacement. Furthermore let $A_i$ denote the event, that in the $i$-th trial, we draw a ball, which was not drawn in one of the $i-1$ trials before. Then it holds

$$\|\mu - \nu\|_{TV} \leq 1 - \mathbb{P}[X = Y] = 1 - \mathbb{P}[X \text{ is a legal sample w.r.t. sampling without replacement}] \leq 1 - \mathbb{P}[A] = 1 - \mathbb{P}\left[ \bigcap_{i=1}^{n} A_i \right] = \mathbb{P}\left[ \bigcup_{i=1}^{n} A_i^c \right] \leq \sum_{i=1}^{n} \mathbb{P}[A_i^c] = \sum_{i=1}^{n} \frac{i}{N} \leq \frac{n^2}{2N}.$$

$\square$

Since $\text{DNF}(L)$ and $\text{OPT}(L)$ are bounded from above by $N(L)$, the proof of Lemma 11 follows by applying the previous lemma and Lemma 28.

**B.2 Proof of Theorem 9**

We divide the proof of the theorem into three lemmas.

**Lemma 30.** Let $L$ be an arbitrary instance, $F$ the induced discrete distribution, and $b := \lceil N(L)^{1/3} \rceil$. Then it holds

$$\left| \text{OPT}(L) - \frac{N(L)}{b} \cdot \mathbb{E}[\text{OPT}(I_b(F))] \right| \leq K \cdot N(L)^{2/3}.$$
Proof. The first step of the proof is splitting up the list into smaller sublists, and using that \( \text{OPT} \) satisfies

\[
\text{OPT}(L_1) + \text{OPT}(L_2) - 1 \leq \text{OPT}(L_1L_2) \leq \text{OPT}(L_1) + \text{OPT}(L_2) + 1,
\]

where \( L_1 \) and \( L_2 \) are two lists, and \( L_1L_2 \) denotes the concatenation of them. This idea was brought up in [8]. Afterwards we will apply Lemma 11.

Let \( L = (a_1, \ldots, a_N) \). To ease notation, we will write \( N \) instead of \( N(L) \). Let \( b = \lceil N^{1/3} \rceil \). Since \( \text{OPT} \) does not depend on the order of the items it holds \( \text{OPT}(L) = \mathbb{E}_\sigma [\text{OPT}(\sigma(L))] \). Therefore we show instead

\[
\left| \mathbb{E} [\text{OPT}(\sigma(L))] - \frac{N}{b} \mathbb{E} [\text{OPT}(I_b(F))] \right| \leq K \cdot N^{2/3}.
\]

To simplify the notation, let \( L^\sigma := \sigma(L) \). We divide \( L^\sigma \) into \( \lceil \frac{N}{b} \rceil \) sublists \( L_1^\sigma, \ldots, L_{\lceil \frac{N}{b} \rceil}^\sigma \). Here, for \( 1 \leq i \leq \lceil \frac{N}{b} \rceil - 1 \), it is \( L_i^\sigma = (a_{(i-1)b+1}, \ldots, a_{ib}) \), and \( L_{\lceil \frac{N}{b} \rceil}^\sigma = (a_{(\lceil \frac{N}{b} \rceil-1)b+1}, \ldots, a_N) \). Then for \( 1 \leq i \leq \lceil \frac{N}{b} \rceil - 1 \), \( \text{OPT}(L_i^\sigma) \) are identically distributed random variables, and \( \text{OPT}(L_{\lceil \frac{N}{b} \rceil}^\sigma) \leq b \). So, using the estimate from Lemma 11, we get

\[
\mathbb{E}_\sigma [\text{OPT}(\sigma(L))] \leq \left( \left\lceil \frac{N}{b} \right\rceil - 1 \right) \mathbb{E} [\text{OPT}(L_1^\sigma)] + b + \left( \left\lceil \frac{N}{b} \right\rceil - 1 \right) \leq \frac{N}{b} \mathbb{E} [\text{OPT}(L_1^\sigma)] + b + \frac{N}{b} \left( \mathbb{E} [\text{OPT}(I_b(F))] + \frac{b^3}{N} \right) + b + \frac{N}{b} \leq \frac{N}{b} \mathbb{E} [\text{OPT}(I_b(F))] + b^2 + b + \frac{N}{b}.
\]

In the same way we achieve

\[
\mathbb{E}_\sigma [\text{OPT}(\sigma(L))] \geq \frac{N}{b} \mathbb{E} [\text{OPT}(I_b(F))] - b^2 - b - \frac{N}{b},
\]

which shows the statement.

\[\square\]

**Lemma 31.** Let \( L = (a_1, \ldots, a_N) \), \( F \) be the induced discrete distribution, and \( b := \lceil N(L)^{1/3} \rceil \). It holds

\[
\left| \mathbb{E} [\text{OPT}(I_N(F))] - \frac{N(L)}{b} \cdot \mathbb{E} [\text{OPT}(I_b(F))] \right| \leq K \cdot N(L)^{2/3}.
\]

This lemma can be proved in the same way as the previous one.

**Lemma 32.** Let \( L = (a_1, \ldots, a_N) \) be a list, and \( F \) the induced discrete distribution. It holds

\[
| \mathbb{E} [\text{OPT}(I_{N(L)}(F))] - N(L) \cdot \gamma(F) | \leq K \cdot N(L)^{2/3}.
\]

The proof of this lemma can be found in [17].

Finally, a simple application of the triangle inequality yields the proof of the theorem.