Directed follow-up strategy of low-cadence photometric surveys in search of transiting exoplanets – I. Bayesian approach for adaptive scheduling

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ABSTRACT

We propose a novel approach to utilize low-cadence photometric surveys for exoplanetary transit search. Even if transits are undetectable in the survey data base alone, it can still be useful for finding preferred times for directed follow-up observations that will maximize the chances to detect transits. We demonstrate this approach through a few simulated cases. These simulations are based on the Hipparcos Epoch Photometry data base and on the transiting planets whose transits were already detected there. In principle, the approach we propose will be suitable for the directed follow-up of the photometry from the planned Gaia mission, and it can hopefully significantly increase the yield of exoplanetary transits detected, thanks to Gaia.

Key words: methods: data analysis – methods: observational – methods: statistical – techniques: photometric – surveys – planetary systems.

1 INTRODUCTION

The idea to detect transits of exoplanets in the Hipparcos Epoch Photometry (ESA 1997) triggered several studies that checked the feasibility of such an attempt. Hébrard & Lecavelier Des Etangs (2006) concluded that Hipparcos photometry did not look like an efficient tool for transit detection, without using any prior information. Indeed, some teams have made posterior detections of the transits of HD 209458 (Soderhjelm 1999; Castellano et al. 2000; Robichon & Arenou 2000), and of HD 189733 (Bouchy et al. 2005), a detection that Hébrard & Lecavelier Des Etangs (2006) confirmed. Those teams used the previously available knowledge of the orbital elements of the exoplanets (especially the period and the transit phase), in order to phase the Hipparcos data of those stars. Using the large time-span that had elapsed since the Hipparcos observations (for example, about 830 orbital periods between Hipparcos observations and the observations that Castellano et al. 2000) used for HD 209458), the teams managed to drastically reduce the uncertainties of the known period. The posterior detections of both transits prove that information about the transits does exist in the data, although it is obviously futile to try to detect the transits in the naive Box Least Squares (BLS) approach. Thus the posterior detections motivated us to re-examine Hipparcos Epoch Photometry data and to look for a way to utilize this survey and similar low-cadence photometric surveys to detect exoplanets. The approach we propose here is to use the data to maximize the chances to detect transits during hypothetical follow-up campaigns, i.e. instead of attempting to detect a transit, we use the data to schedule follow-up observations that together with the old data set may enable its detection.

In order to maximize the probability of sampling a transit in those surveys, and in order to predict the best possible future observing times, we chose to use Bayesian inference methods.

Bayesian analysis is based on Bayes theorem and can be written as

\[ p(H_i|D, I) = \frac{p(D|H_i) p(H_i|I)}{p(D|I)} \]

(1)

where \( p(H_i|D, I) \) is the posterior probability of the Hypothesis \( H_i \), given the prior information, \( I \), and the data \( D \).

\( p(D|H_i, I) \) is the probability of obtaining the data \( D \), given that \( H_i \) and \( I \) are true. It is also known as the likelihood function \( L(H_i) \).

\( p(D|I) = \sum_i p(D|H_i) p(H_i|I) \) is a normalization factor that ensures that \( \sum_i p(H_i|D, I) = 1 \). It is usually referred to as the prior predictive probability for \( D \), or the global likelihood for the entire class of hypotheses.

In the Bayesian framework we start from a prior knowledge we introduce into the prior probability distribution, \( p(H_0|I) \). The choice of prior distribution can affect the posterior distribution, especially if our observed data do not strongly constrain the model parameters. If our prior knowledge is poor, \( p(H_0|I) \) can spread over a wide range of possible values for the model parameters. Whenever new data are available, it is possible to incorporate the new data in our model through the likelihood function, combined with the prior, to obtain a new posterior density probability, \( p(H_0|D_1, I) \), for the parameter. As soon as we obtain another set of data, \( D_2 \), we recalculate the posterior density probability in order for it to reflect our new state of knowledge. The possibility of combining new data sets into the original data we have will allow us to accomplish our goal of detecting transiting exoplanets using scheduled follow-up observations.
Gregory (2005a), Ford (2006) and others have already shown that Bayesian inference is a useful tool for analysing precise radial-velocity (RV) data of planet-hosting stars. Gregory (2007) used Bayesian inference model selection for the problem of multiple planets, and Gregory (2005a) used it to construct posterior probability density functions of the light-curve parameters. Defay, Deleuil & Barge (2001) and Aigrain & Favata (2002) demonstrated the use of the Bayesian approach to study planetary transits.

Our implementation of Bayesian inference is based on the Metropolis–Hastings (MH) algorithm, which is a version of the more general Markov chain Monte Carlo (MCMC) approach (Gregory 2005b).

A Markov chain is calculated using an initial set of parameter values, \( X_0 \), and a transition probability, \( p(X_{n+1} | X_n, t) \), that describes the probability of moving from the current state to the next one. The transition probability depends on the acceptance probability, described later in Section 3, and if properly constructed, then after excluding the so-called ‘burning time’, we can use the chain as a sample from the desired distribution. MH algorithm is an implementation of the MCMC that is used for obtaining a sequence of random samples from a probability distribution.

The MH algorithm does not require good initial guess of the parameter values in order to estimate the posterior distribution. This is one of the most important advantages of the algorithm. The algorithm is capable of exploring all regions of the parameter space having significant probabilities (assuming it meets several basic requirements). The analysis also yields the marginal posterior probability distribution functions for each of the model parameters and their uncertainties.

In Section 2 we describe the follow-up approach we developed to detect transiting exoplanets, based on observations from low-cadence surveys. In Section 3 we give a brief review of Bayesian inference and its applications for our follow-up strategy. Sections 4 and 5 demonstrate the approach by applying it on two stars that are known to harbour hot Jupiters, HD 209458 and HD 189733, using the *Hipparcos* data base. Section 6 shows some ‘sanity checks’ we performed on data that do not contain the transit signal at all. We conclude and describe future applications of the strategy in Section 7.

## 2 DIRECTED FOLLOW-UP

Our ultimate goal is to detect transiting exoplanets using follow-up observations, which will be carefully scheduled to increase the chances to capture transits, should they exist. Thus, our approach does not focus on obtaining a detailed transit model that best fits the available data, but on building a probability distribution function of the parameters of a simple model, based on these data. The transit model that we use in this work is a very simplistic one, based on the BLS philosophy (Kovács, Zucker & Mazeh 2002). Thus, we model a transit light curve as a box-shaped transit with two phases, in and out of transit, and ignore the duration of the ingress and egress phases, as well as the details of the limb darkening. These details are less relevant in low-precision, low-cadence surveys, and using fewer parameters makes the model more robust. We use the Bayesian MH algorithm to obtain a posterior probability distribution for the model parameters, and then use this distribution to prioritize the timing of the observations of the chosen stars for follow-up observations.

The directed follow-up approach is not suitable for space missions like *COROT* or *Kepler*. Such missions, due to their high cadence, will not benefit from the approach since their phase and period coverage are already quite complete. Instead, we aim for all-sky surveys like *Hipparcos* (van Leeuwen et al. 1997), or its successor, *Gaia* (Jordi et al. 2006), in order to use their extensive low-cadence photometric databases for exoplanets search.

A simplified (BLS-like) transit light curve is parametrized by five quantities, e.g. the period, phase and width of the transit, and the flux levels in-transit and ex-transit. The first step in our proposed procedure is to apply the MH algorithm to the *Hipparcos* measurements of a target star. This results in five Markov chains that include the successful iterations for each one of the parameters. A successful iteration is one that was accepted by the MH algorithm. After removing the ‘burning time’, each chain represents the stationary distribution of the parameters, which we use as our estimated posterior distributions, for our current state of knowledge (Gregory 2005b). Unlike the case of precise high-cadence surveys, even if the star does host a transiting exoplanet, due to the low precision and low cadence of the observations we do not expect the distribution to concentrate around a single solution, but rather show different periods that might fit the data, besides the unknown correct one.

The next step of our procedure is to assign each point in time the probability that a transit will occur at that time. Calculating this probability is easy using the posterior distributions we found in the first stage. Basically for time \( t \), we count the number of MCMC successful iterations whose values of \( P, T_0 \) and \( w \) predict a transit in time \( t \). Normalizing this number by the number of total iterations yield the Instantaneous Transit Probability (ITP) for time \( t \). If the ITP has significantly high values for certain times, then a follow-up observation is worthwhile at those preferred times.

When we examine the ITP function of different observations and simulations we performed, it is clear that the shape of this function when a transit signal exists contains sharp peaks, where the probability of transit is relatively high. This behaviour is crucial for defining preferred times for follow-up observations. If we sample the values of the predicted probabilities, we can test for this behaviour by the skewness of this sample. The skewness of a random variable is generally defined as

\[
S = \frac{\langle (x - \langle x \rangle)^3 \rangle}{\sigma^3},
\]

where \( \langle \cdot \rangle \) denotes the operation of averaging over the sample values. The skewness of the ITP is actually a measure of the amount of outliers, where the term outliers actually refers to peaks with significantly high values. The absence of such ‘outliers’ means that there are no preferred times for follow-up observation; thus the ITP values will be more symmetrically distributed, with a skewness value close to zero (\( S = 0 \) for a normal distribution).

In order to prioritize the stars for follow-up observations, we need to rank them. We propose to use the skewness of the ITP as a criterion for prioritizing stars for follow-up observations, together with the actual ITP values for follow-up time predictions.

Another criterion we propose for the prioritization process is to use the Wald test for the posterior probability distribution of the transit depth, which is a measure of the ‘strength’ of the signal we are looking for. The Wald test, named after Abraham Wald, is the most simplistic statistical test designed to examine the acceptance of a hypothesis (e.g. Lyons & Karagoz Ünel 2006). The Wald statistic for a random variable \( x \) is defined by the simple expression

\[
W = \frac{E(x) - x_0}{\text{std}(x)},
\]

where \( E(x) \) and \( \text{std}(x) \) are the expected value and standard deviation correspondingly of the variable \( x \), and \( x_0 \) is the nominal value of \( x \) according to the null hypothesis. In our case, \( x \)
is the transit depth, and the moments (E and std) are calculated
based on the posterior probability distribution. \( x_0 \) is simply zero,
since our null hypothesis is the absence of any transit. In a sense,
the Wald statistic for the transit depth quantifies the degree to
which we believe that there is a periodic transit-like dimming of
the star, based on the available photometry. A high value of
the Wald statistic indicates a relatively narrow posterior distribution
of the transit depth. This may indicate that there are periods ac-
cording to which the low-flux measurements, corresponding to a
transit-like dimming, are relatively concentrated in a short phase.
This short phase can be the hypothetical transit which we look for.

Performing the follow-up observations at the times directed by
the previous step is the final step of the strategy. A combination
of both the ‘old’ data from the survey and the new observations at
the directed time eliminates periods that do not fit our new state of
knowledge. The procedure is repeated until we detect a transiting
planet or exclude its existence.

In Sections 4 and 5, we examine the strategy for two known tran-
siting planets, HD 209458b and HD 189733b, using the Hipparcos
photometric catalogue. The promising results show that the strategy
is efficient in utilizing low-cadence low-precision surveys for
exoplanets transit search.

3 BAYESIAN APPROACH – SIMPLIFIED
TRANSIT MODEL

Inspired by the BLS (Kovács et al. 2002), our model is a simple box-
shaped transit light curve, with five parameters that characterize it:
\( X = \{ P, T_e, w, d, m \} \), where \( P \) is the orbital period, \( T_e \) is the
time of mid-transit, \( w \) is the transit duration, \( d \) is the depth of the
eclipse and \( m \) is the mean magnitude out of transit.

Let \( v_k \) and \( \sigma_k \) denote the observed magnitude and its associ-
atd uncertainty at time \( t_k \), respectively. Let \( m \) denote the magnitude out
of transit, which is assumed to be constant.

Assuming a simple ‘white’ Gaussian model for the observations,
we can write down the likelihood function explicitly:

\[
p(D|X) = \prod_k \frac{1}{\sqrt{2\pi\sigma_k}} \exp \left( -\frac{(v_k - \mu_k)^2}{2\sigma_k^2} \right)
\]

\[
= \frac{1}{(2\pi)^K/2} \prod_k \frac{1}{\sigma_k} \exp \left( -\sum \frac{(v_k - \mu_k)^2}{2\sigma_k^2} \right),
\]

where

\[
\mu_k = \begin{cases} 
m & \text{if } t_k \text{ is out of transit}, 
m + d & \text{if } t_k \text{ is in transit}, 
\end{cases}
\]

and \( K \) is the number of observations. (Note that the magnitude
during transit is defined as \( m + d \), since we use magnitude units
and not flux units.) The exponent in equation (4) is actually half the
well-known \( \chi^2 \) statistic.

The MH algorithm can now be summarized by the following
description.

(1) Initialize \( X_0 \) – the initial guess for the set of model param-
eters; set \( n = 0 \).

(2) Draw a sample \( Y \) (trial state) from a proposal distribution
\( q(Y|X_0) \). This distribution can be a Gaussian distribution, centred
around \( X_0 \) – the current set of model parameter values.

The acceptance probability, \( \alpha \), is defined by

\[
\alpha = \min \left( 1, \frac{p(Y)p(D|Y)q(X_0|Y)}{p(X_0)p(D|X_0)q(Y|X_0)} \right)
\]

\[
(5)
\]

is the Metropolis ratio, which is composed of the prior \( \times \) likeli-
hood and the proposal distributions. If the proposal distribution is
symmetric, then the second factor in the Metropolis ratio is equal
to 1.

(3) Sample a random variable, \( u \), from a uniform distribution, in
the interval 0–1.

(4) If \( u < \alpha \), set \( X_{n+1} = Y \) (a successful iteration), else set
\( X_{n+1} = X_n \).

This last step results in accepting the new trial state \( Y \) with
probability \( \alpha \).

(5) \( n = n + 1 \).

(6) Go back to step 2.

Steps 2–6 are repeated \( N - 1 \) times to produce a Markov chain of
length \( N \).

For a wide range of proposal distributions, \( q(Y|X_0) \), after an
initial burn-in period (which is discarded), the algorithm creates
samples of \( X_n \) with a probability density function that covers the
desired range, the posterior distribution, \( p(X|D) \).

3.1 Choice of priors

The choice of prior distributions is important in Bayesian analysis,
as a non-educated choice can produce misleading results (Balan &
Lahav 2009).

For the orbital period, we adopt the approach proposed by Ford
(2006) and use a uniform prior in log \( P \),

\[
p(P) = \frac{1}{P \ln \left( \frac{P_{\text{max}}}{P_{\text{min}}} \right)}.
\]

The theoretical lower limit of the orbital period according to the
Roche limit (\( d \approx 2.423 \times R_s \sqrt{m/m_s} \)) for a planet with
\( m_p \sim 10 M_{\text{Jup}} \), orbiting a star with a solar mass, is approximately
0.2 d (Ford & Gregory 2007), while the upper limit can be set at around
10^3 d or about three times the duration of the data (Gregory 2005a).
The time-span of the data is long (for example, Hipparcos data span
more than 1000 d), we choose an upper limit of the order of the
time-span of the data, which is much longer than the period of any
known transiting exoplanet.

We use the same form of prior for the transit duration

\[
p(w) = \frac{1}{w \ln \left( \frac{w_{\text{max}}}{w_{\text{min}}} \right)},
\]

where we chose, somewhat arbitrarily, a lower limit of \( w = 0.001 \) d
and an upper limit of 1 d. This range includes all known exoplanetary
transit durations. The other three parameters of the transit model (\( T_e \),
\( d, m \) were assigned a uniform prior, where \( T_e \) and \( m \) have the range
of the data as their upper and lower limits, and the transit depth, \( d \),
is uniformly distributed between 0 and 1. The prior distribution in
our problem, assuming that the parameters are independent, can be
described by

\[
p(X_0) = p(P)p(T_e)p(w)p(d)p(m).
\]

The most significant dependence expected between the orbital pa-
rameters is between \( P \) and \( w \), since the maximum value of \( w \) can
be related to \( P \). The strong dependence of \( w \) on the orbital in-
clination ‘masks out’ this correlation which is why we chose to
ignore it in this work. In future applications, we may use more complicated priors, which might include dependence among the parameters.

3.2 The proposal distribution

We choose the proposal distribution for each parameter individually. For \( T_c \), \( d \) and \( m \), we use Gaussian proposal distributions centred around the last value in the Markov chain. For the transit duration, \( w \), which has to be between 0 and around a few hours, we choose a lognormal distribution for the proposal distribution in order to avoid negative values.

The period, \( P \), requires special considerations. The structure of many kinds of periodograms shows that the likelihood function, when seen as a function of the period, has a very complex structure of sharp local maxima and minima. Even for good-quality data, we expect the likelihood to have sharp peaks in harmonics and subharmonics of the correct period. We propose to use this shortcoming to our advantage, by using a ‘jumping’ proposal distribution for \( \log P \). Thus, besides the small steps around the previous value of the Markov chain, we propose to allow, in some specified probabilities, jumps to a period which is a multiple or a divisor of the current period. The probability of moving to an integer multiple or divisor of the current value of the period is \( \text{Prob} = 1/10 \), while in random probability of 9/10, the moves are the usual ones around the current value of the Markov chain. This should allow a more efficient exploration of the parameter space.

4 HD 209458

We first apply the strategy on the *Hipparcos* Epoch Photometry of HD 209458. *Hipparcos* observed HD 209458 (HIP 108859) in non-uniformly distributed 89 epochs, in a time-span of about 1084 d. We use all the data points since they all have a quality flag \( \leq 2 \), which means that they were accepted by at least one of the two data reduction consortia (Perryman & ESA 1997). The estimated standard errors of the individual \( H_r \) magnitudes are around 0.015 mag, which is of the order of the transit depth (the signal we are looking for).

In the Bayesian framework, we choose priors for the parameters as described in Section 3 and allow the algorithm to explore the parameter space in order to find the different solutions that fit the data. The resulting posterior distributions for the relevant parameters are shown in Fig. 1. As can be seen from the period histogram, the distribution does not favour any single period, but rather has several distinctive peaks. The most likely period is \( P \approx 3.52 \) d, which is consistent with the known period of HD 209458 (Castellano et al. 2000), while the other probable periods are different periods that fit the data as well.

We performed the Wald test to test the hypothesis of the presence of a planet that is transiting the star and found that the expected value of the transit-depth posterior distribution in our analysis is \( E(d) = 0.02 \) mag, and the value of the Wald test (equation 3) is \( W = 4.22 \), a result with a 4\( \sigma \) significance.

We continue with the second part of the strategy – examining the most probable time to observe the star in a follow-up observation. Our simulated directed follow-up explores one year that began a month after the last observation of *Hipparcos* and found the best times to observe the star in order to sample the transit. The follow-up predictions are shown on the bottom-right panel of Fig. 1 (the ITP function). We add the known transit light curve (based on the orbital parameters derived by Castellano et al. 2000) to the figure for comparison between the predictions and the actual transits. The time that was most preferred by our predictions indeed fits inside a transit, meaning it would have been possible to detect the transit with only one follow-up observation conducted after *Hipparcos* using our proposed strategy. We examined the skewness of the ITP for prioritization purposes and found it to be \( S = 1.4 \). As will be shown in Section 5, and also by Table 1, the ITP we obtained from *Hipparcos* data of HD 209458 is an exception, with a relatively low skewness, while other ITP skewness values for data that contain a transit signal are usually higher. We can understand this anomaly by looking at the ITP of the star in question: there are many peaks of the follow-up probability, and they are distributed over the entire range we examined (one year post-*Hipparcos*), with significant values for follow-up (above 0.1). The relatively symmetric distribution of the ITP is the cause of the low-skewness value. The significance of the ITP for the *Hipparcos* data of HD 209458 is still high enough for a follow-up observation to be worthwhile, and together with the Wald statistic, the star would have gotten a high priority for follow-up observations, despite the relatively low skewness.

We also check the follow-up predictions for 10 yr after *Hipparcos*, as shown in Fig. 2. Long after the last observation, the ITP decreases, although some peaks remain, and when looking carefully, we can
Table 1. Wald statistic of the transit-depth posterior probability distribution function and skewness of the ITP.

| Data/simulation                               | Wald statistic of the transit depth | Skewness of the ITP |
|-----------------------------------------------|-------------------------------------|---------------------|
| First simulation of transit                   | 5.5                                 | 5.5                 |
| Second simulation of transit                  | 5.7                                 | 5.6                 |
| HD 209458 – Hipparcos                         | 4.2                                 | 1.4                 |
| HD 189733 – Hipparcos                         | 3.6                                 | 4.7                 |
| HD 209458 – Hipparcos one and simulated observation | 18.1                                | 4.8                 |
| HD 189733 – Hipparcos and one simulated observation | 2.9                                 | 2.5                 |
| HD 189733 – Hipparcos and two simulated observations | 3.4                                 | 2.7                 |
| HD 189733 – Hipparcos and three simulated observations | 1.7                                 | 2.3                 |
| HD 189733 – Hipparcos and four simulated observations | 4.3                                 | 2.2                 |
| HD 189733 – Hipparcos and five simulated observations | 21.1                                | 7.7                 |
| Noise alone                                    | 1.3                                 | 0.07                |
| First permutation of transit simulation       | 1.5                                 | 0.87                |
| Second permutation of transit simulation      | 2.2                                 | 0.001               |
| Third permutation of transit simulation       | 2.1                                 | 0.6                 |
| HD 209458 – Hipparcos permutation             | 1.4                                 | 0.5                 |
| HD 189733 – Hipparcos permutation             | 1.5                                 | 1.0                 |
| HD 86081 (no transit) – Hipparcos             | 1.3                                 | 0.47                |
| HD 212301 (no transit) – Hipparcos            | 1.4                                 | 0.43                |

Figure 2. HD 209458: ITP function for 10 yr after Hipparcos observations. The probability of sampling a transit smears as the time elapsed from the observations, but even three years after Hipparcos observations, a transit detection was possible.

see that even three years after Hipparcos, we could have detected the transit using our follow-up predictions.

The final step of the strategy described in Section 2 is to perform follow-up observations according to the most significant peak of the ITP. Since the time that has elapsed since Hipparcos cause the ITP peaks to be smeared, we cannot perform current follow-up observations for significant ITP peaks found using the algorithm, so we simulated such observations, and then combined them with the Hipparcos data, to recalculate the ITP.

The simulation generated four observations (four single data points) inside and outside the predicted time of the transit (the significant peak of the ITP), with a typical error of 0.001 mag. In the simulation we used the known transit light curve to generate the observation. The new histograms for the combined data sets are presented on the top panel of Fig. 3. It is clear that the first observation that could have been performed using the directed follow-up would have been enough to detect the transit, since the histograms are centred around the parameters of the planetary transit of HD 209458b. The simulated new observation excludes all the spurious periods which the MH algorithm proposed based on the Hipparcos data alone. The Wald statistic for the transit depth now increased to $W = 13.46$. As can be seen from Fig. 3 (bottom panel), the new directed follow-up that relies on both Hipparcos and the new simulated observation fits perfectly with the planetary transit of HD 209458b, with a high ITP value, which is close to 1, and with skewness of $S = 4.8$.

Figure 3. HD 209458: combined data sets of Hipparcos and the simulated observation. The simulation generated four single measurements at the directed time by the ITP most significant peak. According to the known light curve of the transit this peak fits mid-transit time. Top: histograms of the orbital parameters found using the MH algorithm for the combination of the data sets. Bottom: ITP for the first year after the simulation, compared with the known light curve of the transit. The transit detection was feasible, since all histograms are centred around the values of the orbital elements of the transiting planet: $P = 3.5247$ d, $w = 0.1$ d and $d = 0.022$ mag (Castellano et al. 2000).
HD 189733: Hipparcos – parameters histograms

Figure 4. HD 189733. Top: histograms of the orbital parameters found using the MH algorithm for the Hipparcos data: the period, time of mid-transit, transit duration and the depth of the transit. The periods that are most probable using the MH algorithm differs from the planetary period ($P \sim 2.218$ d) (Hébrard & Lecavelier Des Etangs 2006). Bottom: ITP for the first year after Hipparcos observations, according to the procedure described in Section 5, compared with the transit light curve, derived using the known orbital parameters (Hébrard & Lecavelier Des Etangs 2006). The significant peaks do not fit mid-transit time, hence a single follow-up would not be sufficient for transit detection.

5 HD 189733

We next applied the procedure to the Hipparcos data for HD 189733. Hipparcos observed HD 189733 (HIP 98505) in non-uniformly distributed 185 epochs, over a time-span of 1083 d. We chose to use only 176 measurements that were accepted by at least one of the two data reduction consortia. The estimated standard errors of each individual $H_P$ magnitude are around 0.012 mag, which is of the order of the transit depth, similar to HD 209458.

The posterior distributions of the model parameters are shown on the top panel of Fig. 4. As can be seen from the figure, the correct orbital period of the planet, $P = 2.2185$ d (Hébrard & Lecavelier Des Etangs 2006), is not detected, and instead other periods fit the data. The preferred mid-transit time is $T_c - 2440000 = 8460.21$ JD, while the actual time of mid-transit according to Bouchy et al. (2005) is $T_c - 2440000 = 8460.11$ JD.

Again, we used the posterior distribution to perform the Wald test to test the hypothesis of the presence of a planet that is transiting the star, although we obviously did not detect the correct period. The expected value of the transit-depth posterior distribution is $E(d) = 0.024$ mag, and the value of the Wald test is $W = 3.63$, which indicates that follow-up observations are worthwhile since a transit is highly probable for this star.

The follow-up predictions we have for a year that starts one month after the Hipparcos observations are shown at the bottom panel of Fig. 4, compared with the known transit light curve of HD 189733b. This time a single follow-up observation would not have been enough to detect the transit, since the significant peaks in the follow-up do not match the mid-transit time. These results for HD 189733 might have been caused by the star microvariability which Hébrard & Lecavelier Des Etangs (2006) described. In their posterior detection of HD 189733b in Hipparcos they checked for long-term periodicity, and found several significant periods, that when removed improved the $\chi^2$ statistic they got for the known orbital period of the planet. From the high ITP of the follow-up predictions, its skewness ($S = 4.7$), and the result of the Wald test, this star would get high priority for follow-up observations, and although the observing time would not fit at the middle of the transit, as soon as a new observation in the preferred time would have been obtained, it would be added to the previous data we already have, and the procedure would be repeated, this time hopefully excluding the false periods.

In order to check this claim we simulated a follow-up observation at the time the algorithm directed. Recall that in this case (as opposed to the case of HD 209458), the directed time was not in transit. We then added it to the Hipparcos observation to recalculate the parameters posterior distributions, as well as to propose a new time for the next observation. We had to simulate a total of five follow-up observations, each containing four ‘exposures’ with an error of 0.001 mag, in order to finally detect the transit itself. In Figs 5–9 we present the changes in the posterior distribution, as well as the directed follow-up predictions, as more simulated observations are added to the original data. Each observation eliminates some of the periods,
making room for other periods to emerge, until an actual transit is observed at the final observation. By the fifth follow-up observation, the only probable periods left were the transit period and its multiples. Table 1 summarizes the Wald statistics and the skewness of the ITP for the original Hipparcos data, together with the simulated observations.

6 SANITY CHECKS

As we demonstrated above, it was possible to detect the transiting exoplanets orbiting both HD 209458 and HD 189733 using the follow-up strategy we proposed. We now want to demonstrate cases where no transit signal is supposed to exist.

6.1 HD 209458 – permuted data

We perform the first test by randomly permuting the Hipparcos data of HD 209458 and repeating the simulated follow-up procedure described above. The result of the Wald test, \( W = 1.45 \), shows that the likelihood of a transit for the permuted data is low. The predicted ITP for the directed follow-up is small for all the time-span that we checked, with a skewness value of \( S = 0.5 \), which again implied that there were no preferred time to observe a transit. This means that it is unlikely that there is a transit signal in the permuted data.

6.2 HD 189733 – permuted data

As for HD 209458, we randomly permuted the data of HD 189733 in order to test our procedure. The Wald statistic for the permuted data is \( W = 1.5 \), which means that it is not likely to find a transit based on the permuted data. Although not as low as for the permuted data of HD 209458 the computed ITP in the directed follow-up, its skewness (\( S = 1.0 \)), combined with the small value of the Wald statistic, means that it is not worthwhile to preform follow-up observations

6.3 HD 86081 and HD 212301

Besides examining the randomly permuted data of HD 209458 and HD 189733, we also applied our procedure on two stars for which we have reasons to believe there is no transit signal. We chose the two stars HD 86081 and HD 212301, which are known to harbour short-period planets. Since the planets are known to have short orbital periods, the fact that no transits were detected (Johnson et al. 2006; Lo Curto et al. 2006) means it is very unlikely that the stars have other hot Jupiters orbiting them, thus making them perfect targets for testing our procedure, as negative test cases.

Hipparcos observed HD 86081 for 71 reliable epochs, and HD 212301 for 123, during the operation time of the satellite, numbers which are similar to the number of Hipparcos measurements of HD 209458. We applied the strategy on both data sets. Fig. 11 shows the corresponding depth histograms and the ITP function for both stars. HD 86081 and HD 212301 did not show any significant value for the ITP, and the highest value was at least one order of magnitude below the predictions for HD 209458 and HD 189733. As a result, the skewness values of the ITP of both stars were low as well (smaller than 0.5), which indicates that a follow-up observation is not worthwhile for those stars. The transit-depth Wald statistics for
the two stars were $W = 1.2$ for HD 86081 and $W = 1.4$ for HD 212301, which again indicates that transits are unlikely.

7 CONCLUDING REMARKS

In this paper we proposed a novel approach to the design of follow-up observations of low-cadence photometric surveys, in a way that will maximize the chances to detect planetary transits. Examples of such surveys are Hipparcos, ASAS, and Gaia as Hipparcos successor. The strategy may also be beneficial for the Large Synoptic Survey Telescope (Jurić & Ivezić 2011), and for Pan-STARRS ground-based survey, especially for directing follow-up observations of hot Jupiters transiting M-dwarf stars in the Medium Deep Survey (Ford et al. 2008; Dupuy & Liu 2009).

We tested our proposed procedure on two stars with transiting planets that were observed by Hipparcos during transits: HD 209458 and HD 189733. We showed that without any prior information regarding the orbital elements of the planets, it was possible to use the available data base of Hipparcos to direct follow-up observations for both stars and thus detect the planetary transits in minimal observational effort. This makes use of the fact that the Bayesian approach allows the inclusion of new data, which reflect new state of knowledge, in an easy and straightforward fashion.

The Hipparcos examples we analysed are only test cases to demonstrate the algorithm capabilities. Using Hipparcos in such fashion to detect planets is already impractical, due to the long time that elapsed since the completion of the mission. The effect of the elapsing time is clearly seen in the way the ITP decreases during 10 yr (Fig. 2). We have shown that one year after Hipparcos, it was possible to use its data to direct photometric follow-up observations that could have detected the planetary transits in only one follow-up observation for HD 209458 and in five observations for HD 189733.

In cases where only the Wald statistic has high significance, but the ITP is relatively low, we might recommend performing spectroscopic follow-up instead of photometric one, since RV search is less dependent on precise knowledge of the transit phase, because the goal is then to sample all phases of the orbit. Since Hipparcos observations were performed almost two decades ago, and due to the fact that the ITP lost its significance, it may be more productive to perform RV follow-up observation for potential stars found in Hipparcos alone. We will explore this option in future work.

Obviously, the procedure suggested here should not only be confined to the search for transiting planets, but can also be applied for searching other kinds of periodic variables, such as eclipsing binaries and Cepheids. This will probably require some modifications of the procedure and algorithm. In this context, it is important to mention a similar approach of adaptive scheduling, which Tom Loredo proposed for the purpose of optimizing RV observations. The approach, adaptive Bayesian exploration (ABE; Loredo 2004), is much more general, attempting to optimize the information obtained by every additional observation for the purpose of estimating the parameters of the model behind the observations. The formulation of our problem is much more specific and simple – we want to optimize our chances to ‘catch’ the transit using well-scheduled follow-up observations. While every RV measurement contributes in some way to the orbital solution, the contribution of an individual photometric measurement to the transit solution boils down to the binary question whether it is in the transit or not. Thus, ABE uses an elaborate merit function that quantifies the amount of information in

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Follow-up strategy of low-cadence photometry

Figure 10. HD 209458 and HD 189733. Top: comparison between the transit-depth histograms for the Hipparcos data and for the permuted data, with the associated values of the Wald test. Bottom: ITP function for the permuted data sets.

the RV measurements. ABE can probably be applied to our problem as well, but we feel that it would be redundant due to the simpler nature of the problem. We speculate that the two approaches would yield very similar results.

Our experience shows that the MH algorithm and the ITP tend to find all possible periods that fit the data. Because of the low cadence of Hipparcos measurements, some hypothetical models may fit the data simply because the ‘transits’ occur during ‘gap’ intervals, when no observations were made. Thus, the follow-up prediction function, when generalized to a broader model space of periodic variables, will allow constructing a follow-up strategy that will complement the low-cadence observations in a way that will optimize the period coverage.

MCMC methods, such as the MH algorithm, can be very demanding in terms of processing time. Therefore, improving the efficiency and automatizing the strategy in order to explore large data bases is crucial to its usefulness. Thus, we are examining the idea of reducing the amount of model parameters that the MH algorithm explores to three main parameters: the transit period, duration and mid-transit epoch, while marginalizing over the other two parameters: the transit depth and mean magnitude out of transit. The marginalization will hopefully shorten the computing time. Another idea worth examining is using a BLS-like algorithm, which will scan the \((P, T_c, w)\) space and calculate the likelihood of each configuration, from which it will build, in a Bayesian fashion, the ITP function. Such scanning is obviously a compromise, since it is discrete and finite by nature, and the coverage of the parameter space may be lacking. However, the gain in computation time compared to a Monte Carlo approach might be worth the price.

At this stage the simulations we have presented in this paper are a feasibility test, based on Hipparcos Epoch Photometry. The encouraging preliminary results we present here lead us to believe that the strategy can be beneficial for the Hipparcos successor, Gaia (Eyer et al. 2009). Gaia, whose expected launch is planned to 2012, will measure about a billion stars in our Galaxy and in the Local Group, and will perform, besides ultraprecise astrometry, also spectral and photometric observations. Gaia is supposed to improve on the accuracy of Hipparcos using larger mirrors, more efficient cameras and detectors and better software to reduce the data. In its photometric mission, Gaia will scan the whole sky, with a photometric precision of 1 mmag for the brightest stars, and up to 20 mmag at a magnitude of 20 (Eyer et al. 2009). Gaia main exoplanet search programme is focused on detection through astrometric motion measurements. The strategy we propose here may be generalized to direct follow-up efforts of Gaia’s photometry, aimed to detect transiting exoplanets.

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