PERFECT SAMPLING FOR INFINITE SERVER AND LOSS SYSTEMS

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Abstract
We present the first class of perfect sampling (also known as exact simulation) algorithms for the steady-state distribution of non-Markovian loss systems. We use a variation of dominated coupling from the past. We first simulate a stationary infinite server system backwards in time and analyze the running time in heavy traffic. In particular, we are able to simulate stationary renewal marked point processes in unbounded regions. We then use the infinite server system as an upper bound process to simulate the loss system. The running time analysis of our perfect sampling algorithm for loss systems is performed in the quality-driven (QD) and the quality-and-efficiency-driven regimes. In both cases, we show that our algorithm achieves subexponential complexity as both the number of servers and the arrival rate increase. Moreover, in the QD regime, our algorithm achieves a nearly optimal rate of complexity.

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1. Introduction
We present the first class of exact simulation algorithms for the steady-state distribution of non-Markovian loss systems. The running time of our algorithms is analyzed in the context of many-server queues in heavy traffic; corresponding both to the so-called quality-driven (QD) regime, and the quality-and-efficiency-driven (QED, also known as Halfin–Whitt) regime. In both cases, we show that our algorithm achieves subexponential complexity as the number of servers and the arrival rate increase. Moreover, in the QD regime, our algorithm achieves a nearly optimal rate of convergence. Our contributions are the first to provide an exact simulation methodology with satisfactory running time analysis in heavy traffic.

Exact simulation (or perfect sampling) consists in sampling without any bias from the steady-state distribution of a given ergodic process. Coupling from the past (CFTP), introduced in the groundbreaking paper [22], is the most common exact simulation protocol. In its canonical form, it applies only to uniformly ergodic Markov chains [15]. A variation of CFTP, called dominated CFTP (DCFTP) [17], allows one to apply CFTP-type ideas to obtain unbiased samples from the steady-state distribution of ergodic processes without requiring uniform ergodicity. A standard application of DCFTP involves constructing two stationary processes

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which serve as the upper and lower bounds for the process of interest and can be simulated backwards in time from time 0. When the bounds coincide at some instant in the past, we say that coalescence occurs. The process of interest is then reconstructed forward in time from the coalescence position up to time 0, using the same input sequence that drives the upper and lower bounds. The state of the process of interest at time 0 must then follow the corresponding steady-state distribution. More generally, a coalescence time is understood as an instant in the past from which reconstruction up to time 0 guarantees a stationary sample. A coalescence time might be detected without the need to simulate upper and lower bound processes or have them coincide. In fact, this is the type of strategy that we follow in this paper.

Generic DCFTP algorithms have been studied for suitably ergodic Harris chains (see, e.g. [10], [11], and [18]). None of these algorithms apply directly to our setting as one requires information that is not available in the models we consider (see, e.g. [10, p. 788]). The papers [14], [17], and [19] are close in spirit to the main ideas of our paper as we take a point process approach to the problem. However, their approach requires the use of spatial birth and death processes (generally of Poisson-type) as the dominating processes and, as pointed out in [3, Section 8], the complexity of the algorithms appear to increase significantly as the arrival rate increases.

In connection to queueing models, [20] applied the CFTP idea to simulate several queueing models, assuming either exponential or bounded service times. In [9], the authors developed a class of DCFTP algorithms for Jackson networks (Poisson arrival and exponential service time). Sigman [23], [24] constructed exact sampling algorithms for multi-server queues, assuming Poisson arrivals.

We provide a practical simulation procedure that works only under the assumption of renewal arrivals with a finite mean and service time distribution with a finite mean (in our running time analysis in heavy traffic we impose mild additional conditions for service times). We test our procedure numerically in Section 4.2.3; see also [4].

In order to implement our strategy for loss systems, we simulate a coupled stationary infinite server system backwards in time. We detect coalescence by observing a time interval on which all customers initially present in the infinite server system leave and no loss of customers occurs. This is an unconventional application of DCFTP in the sense that we use only the upper bound process to detect coalescence.

We summarize our contributions as follows.

(i) The design and analysis of the first exact sampling algorithm for the infinite server systems whose running time is shown to be basically linear in the arrival rate. This is essentially optimal, as the steady state of the infinite server systems, encoding the remaining service time of each customer, requires on average a vector which grows linearly in the arrival rate (see Theorem 1).

(ii) The design and analysis of the first exact sampling algorithm for many-server loss systems under non-Markovian arrivals and in a heavy-traffic environment. In the QD regime, where service utilization is strictly less than 100%, we show that our algorithm has sublinear coalescence time. In the QED regime, when the service utilization converges to 100% at a square root speed as a function of the arrival rate, we show that our algorithm has subexponential coalescence time (see Theorems 2 and 3).

We point out that our algorithms allow us to simulate stationary renewal processes with independent and identically distributed (i.i.d.) marks on unbounded but stable regions (having finitely many points almost surely (a.s.)). This connection was noted in [4] for a fixed region...
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(as opposed to a moving frame going backwards in time as we show here). Extensions of (ii) to loss networks with non-Markovian arrivals can also be easily obtained; see [12, Chapter 3].

In Section 2 we introduce our notation, describe the general strategy to simulate the infinite server system, and explain how to use it to detect coalescence for the loss system. In Section 3 we provide algorithmic details for the strategy explained in Section 2. In Section 4 we study the running time of our algorithms.

2. Basic strategy and main results

In this section we introduce the basic strategy to simulate the systems. We also present some results about the efficiency of our algorithms. We leave the details of the algorithms and proofs of the results to subsequent sections.

To facilitate our explanation, we start with a formal description of the infinite server (GI/GI/∞) system.

2.1. Description of the GI/GI/∞ system

We first introduce some notation and assumptions. Let \( N = \{N(t) : t \in (-\infty, 0]\} \) be a one-sided time stationary renewal point process. We write \( \{A_n : n \geq 1\} \) for the times at which the process \( N \) jumps, counting backwards in time from time 0 with \( A_{n+1} < A_n < 0 \). Furthermore, we define \( X_n = |A_{n+1} - A_n| \). Now let \( \{V_n : n \geq 1\} \) be a sequence of i.i.d. random variables (RVs) which are independent of the process \( N \). Define \( Z_n = (A_n, V_n) \) and consider the marked point process \( \mathcal{M} = \{Z_n : n \geq 1\} \in \mathbb{R}^2 \) which we call the 'arriving customer stream'. More specifically, we consider customers arriving to the system according to a renewal process with i.i.d. interarrival times \( X_n \). Independent of the arrival process, their service requirements \( V_n \) are also i.i.d.

In Figure 1 we elaborate on the point process description of the infinite server system, which is important for describing our simulation strategy. The point \( Z_n = (A_n, V_n) \) denotes the \( n \)th customer (counting backwards in time), whose arrival time is \( A_n \) and service requirement is \( V_n \), \( n = 1, \ldots, 4 \). One important feature of the infinite server system is that every customer starts a service immediately upon arrival (there is no queue). If we project \( Z_n \) to the horizontal axis by drawing a \( -45^\circ \) line, then the intersection of this diagonal line with the horizontal axis is the departure time of the \( n \)th customer. We follow the technical tradition that an arrival at time \( t \) is counted in the system (closed circle) while a departure at time \( t \) is not counted (open circle).

We can also draw a vertical line at any \( t \in \mathbb{R} \). The height of the intersection of the \( -45^\circ \) lines

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**Figure 1**: Point process description of an infinite server system.
emanating from the points $Z_n$ with $A_n \leq t$, and such a vertical line, if positive, represents the corresponding remaining service time of that customer at time $t$.

We write $G(\cdot) = \mathbb{P}(X_n \leq \cdot)$ for the cumulative distribution function (CDF) of $X_n$, where $\mathbb{P}(\cdot)$ is the nominal probability measure, and write $\bar{G}(\cdot) = 1 - G(\cdot)$ for its tail CDF. Similarly, we write $F(\cdot) = \mathbb{P}(V_n \leq \cdot)$ as the CDF of $V_n$ and $\bar{F}(\cdot) = 1 - F(\cdot)$ as its tail CDF.

The following assumption is imposed throughout our discussion.

**Assumption 1.** It holds that $\mathbb{E}X_n < \infty$ and $\mathbb{E}V_n < \infty$, where $\mathbb{E}$ is the expectation.

Next we introduce a Markovian description of the infinite server system. Let $Q(t, y)$ denote the number of people in the infinite server system at time $t$ with residual service time strictly greater than $y$. Note that for fixed $t$, $Q(t, \cdot)$ is a piecewise constant step function. If we denote $(r(1)(t), \ldots, r(m)(t))$ as the ordered (positive) remaining service times of customers in the system at time $t$, then $Q(t, 0) = m$ and $Q(t, y) = \sum_{i=1}^{m} 1_{\{r(i)(t) > y\}}$. We also let $E(t)$ denote the time elapsed since the previous arrival at time $t$ (i.e. $E(t) = t - \max\{A_n: A_n \leq t\}$) and $W(t) = (E(t), Q(t, \cdot)) \in \mathbb{R}^+ \times \mathcal{D}[0, \infty)$. Then $\{W(t): t \in R\}$ forms a Markov process which describes the infinite server system.

Similarly, we denote $W^L(t) = (E^L(t), Q^L(t, \cdot)) \in \mathbb{R}^+ \times \mathcal{D}[0, \infty)$ as the state of the loss system with $C$ servers at time $t$, where $E^L(t) = t - \max\{A_n: A_n \leq t\}$ denotes the time elapsed since the previous arrival, and $Q^L(t, y)$ counts the number of people in the loss system at time $t$ with residual service time strictly greater than $y$. Only customers who see less than $C$ servers busy at arrival are admitted to the system and all admitted customers start service immediately upon arrival. If we let $(r^L(1)(t), \ldots, r^L(m)(t))$ denote the ordered (positive) remaining service times of customers in the system at time $t$, then $Q^L(t, 0) = m^L$ and $Q^L(t, y) = \sum_{i=1}^{m^L} 1_{\{r^L(i)(t) > y\}}$.

We now provide a coupling between $W(\cdot)$ and $W^L(\cdot)$ such that $E^L(t) = E(t)$ and $Q^L(t, y) \leq Q(t, y)$ for all $y \geq 0$. In this sense, we say that $W^L(t) \leq W(t)$. The coupling proceeds as follows: we use same stream of customers, $\mathcal{M}$ (same arrival times and service requirements), to update both systems. One can label the servers in the infinite server system, assign customers to the empty server with the smallest label, and, by tracking only the state of the first $C$ servers in the infinite server system, one automatically tracks the state of the loss system. Based on this coupling, if $W^L(s) = W(s)$ then $W^L(t) \leq W(t)$ for $t \geq s$.

**Definition 1.** A coalescence time is a time $T < 0$ at which the state of the loss system is identified from the coupled infinite server system, i.e. $W^L(T) = W(T)$.

### 2.2. Coalescence time with a GI/GI/C/C system

As discussed earlier, the infinite server system imposes an upper bound on the coupled loss system. A natural way to construct the coalescence time would be to define it as the first time (going backwards in time) the infinite server system empties (assuming, say, an unbounded interarrival time distribution, this will occur). However, this coalescence time generally grows exponentially with the arrival rate [16]. So, instead we consider the following construction. Let $R(t)$ denote the maximum remaining service time among all customers in the system at time $t$. And consider a random time $\tau < 0$ satisfying

(i) $R(\tau) < |\tau| < \infty$;

(ii) $\inf_{t \leq \tau + R(\tau)}[C - Q(t, 0)] \geq 0$, where $C$ is the number of servers in the loss system.
As we shall show in Section 4.2, $\tau$ can be identified, and our coalescence time is $T := \tau + R(\tau)$. In words, everyone who was present at time $\tau$ in the infinite server system will have left at time $\tau + R(\tau)$. And since the infinite server system has less than $C$ customers on $[\tau, \tau + R(\tau)]$, the loss system is also operating below capacity $C$ on that interval. Thus, the infinite server system and the loss system must have the same set of customers present in the system at $\tau + R(\tau)$. From then on we can recover the state of the loss system at time 0, using the same stream of customers as for the infinite server system on $[\tau + R(\tau), 0]$.

2.3. Basic strategy and main results for the GI/GI/$\infty$ system

Simulating the infinite server system in stationarity and backwards in time is not trivial, so we first need to explain how to perform this task. There are two cases to be considered.

Case 1. The interarrival time has finite exponential moments in a neighborhood of the origin. More specifically, define $\psi(\theta) = \log \mathbb{E} \exp(\theta X_n)$. There exists $\theta > 0$ such that $\psi(\theta) < \infty$.

Case 2. The interarrival time does not have a finite exponential moment, i.e. $\psi(\theta) = \infty$ for any $\theta > 0$.

As we shall explain, we can always reduce the second case to the first one by defining yet another coupled upper bound process via truncation. Specifically, denote $X_n \wedge b = \min\{X_n, b\}$. We then fix a suitably large constant $b$ and define a coupled infinite server system with truncated interarrival times $\{X_n \wedge b : n \geq 1\}$. The truncation essentially speeds up the arrival process, thus creating more congestion. By coupling, we mean that we use the same stream of customers to update both systems, i.e. we use $(X_n, V_n)$ to update the original system and $(X_n \wedge b, V_n)$ to update the truncated system. We also define the event times as the arrival times and the departure times of the customers. Then the infinite server system with truncated interarrival times imposes an upper bound, in terms of the number of customers in the system, on the original infinite server system at the corresponding event times. Precisely, the event times are defined as $A_n = \sum_{i=1}^n X_i$ and $A_n + V_n, n \geq 1$, for the infinite server system, and $A_n(b) := \sum_{i=1}^n (X_i \wedge b)$ and $A_n(b) + V_n$ for the truncated infinite server system.

In what follows, we shall first concentrate our discussion on case 1, which also includes the infinite server system with truncated interarrival times. We then explain how to carry out the simulation for case 2.

2.3.1. Simulating the stationary GI/GI/$\infty$ system at time 0. We first introduce the procedure to simulate the state of the stationary infinite server system at time 0. We note from Figure 2 that customer $Z_n = \{A_n, V_n\}$, with $V_n \leq |A_n|$ (outside the gray triangle region) will have left the system by time 0. Thus, if we can find a random number $\kappa$ such that $V_n \leq |A_n|$ for all $n \geq \kappa$, then we can simulate the customer stream backwards in time up to $\kappa$ (i.e. $\{Z_n : 1 \leq n \leq \kappa\}$) to recover the state of the system at time 0. The challenge here is that $\kappa$ defined above depends on an infinite amount of information, i.e. $\{Z_n : n > \kappa\}$, and simulating this information takes an infinite amount of time. We overcome this difficulty by defining a sequence of ‘record breakers’. Then, instead of simulating the whole sequence of $\{Z_n : n \geq 1\}$, we ask only a yes/no question defined as ‘are there any more record breakers’? In simulation, answering this yes/no question is equivalent to sampling a Bernoulli RV with probability of success $p$, which equals to the probability that there are no more record breakers. If the Bernoulli trial is a failure, we find the next record breaker, say at index $n_0$, and ask again whether there will be any other record breakers at indices larger than $n_0$. We repeat the above process until we obtain a successful
Bernoulli trial. Then we know that there are no more record breakers in the remaining infinite sequence. We also locate the position (index) of all the record breakers. In what follows, we explain how to use this ‘record breaker’ idea to simulate \( \kappa \).

We start by separating the simulation of the arrival and service time processes. We write \( \mu = \mathbb{E}X_n \) and fix an \( \varepsilon \in (0, \mu) \). Consider any random number \( \kappa \) finite with probability 1, but large enough such that

\[
A_{n+1} \geq n(\mu - \varepsilon), \quad V_{n+1} \leq n(\mu - \varepsilon) \quad \text{for all } n \geq \kappa.
\]

Let \( \kappa(A) \) be a random time satisfying \( A_{n+1} \geq n(\mu - \varepsilon) \) for \( n \geq \kappa(A) \), and \( \kappa(V) \) be a random time satisfying \( V_{n+1} \leq n(\mu - \varepsilon) \) for \( n \geq \kappa(V) \). Then we can set \( \kappa = \max\{\kappa(A), \kappa(V)\} \). The following proposition states that \( \kappa < \infty \) a.s. The proof is given in Appendix A.

**Proposition 1.** Under Assumption 1, the random number \( \kappa \) defined above is finite with probability 1.

As \( \{A_n : n \geq 1\} \) and \( \{V_n : n \geq 1\} \) are independent of each other, the above construction allows us to sample \( \{V_n : n \geq 1\} \) with \( \kappa(V) \) and \( \{A_n : n \geq 1\} \) with \( \kappa(A) \), separately. Next we explain the basic sampling strategies for the two processes.

For \( \{V_n\} \), we say a record is broken at \( n \) for \( n \geq 1 \) if \( V_{n+1} > n(\mu - \varepsilon) \). We then define

\[
J(0) := 0 \quad \text{and} \quad J(l) = \inf\{n > J(l - 1) : V_{n+1} > n(\mu - \varepsilon)\} \quad \text{for } l = 1, 2, \ldots.
\]

We also write \( \gamma := \inf\{l \geq 1 : J(l) = \infty\} \). Each \( J(l) \), for \( 1 \leq l \leq \gamma - 1 \), records the positions of the record breakers. We can set \( \kappa(V) = J(\gamma - 1) + 1 \). We first simulate the random time \( J(l) \) for \( l = 1, 2, \ldots, \gamma - 1 \), and then simulate \( V_n \) conditional on the \( J(l) \)’s (see Section 3.1 for details).

For \( \{A_n\} \), we first translate the process into a negative-drifted random walk. Specifically, we define \( \tilde{S}_n := n(\mu - \varepsilon) - (A_{n+1} - A_1) = \sum_{i=1}^{n} Y_i \), where \( Y_i = (\mu - \varepsilon) - X_{i+1} \). Note that each \( Y_i \) is i.i.d. with \( \mathbb{E}Y_i = -\varepsilon \). Denote \( A_{n+1} = A_1 - \tilde{S}_n + n(\mu - \varepsilon) \). If we can simulate some random time \( \kappa^* \) such that \( \tilde{S}_n \leq 0 \) for \( n \geq \kappa^* \), then \( |A_{n+1} - A_1| \leq n(\mu - \varepsilon) \) for \( n \geq \kappa^* \). Fix any \( m > 0 \). We ask the yes/no question whenever \( \tilde{S}_n < -m \), and we say that a record is broken at index \( n \) beyond \( k \) if for \( n > k \), \( S_n - S_k > m \). In particular, we define \( \Gamma(0) := 0 \), \( \Delta(l) := \inf\{n \geq \Gamma(l - 1) : \tilde{S}_n \leq -m\} \), and \( \Gamma(l) := \inf\{n \geq \Delta(l) : \tilde{S}_n - \tilde{S}_{\Delta(l)} \geq m\} \). Let \( \alpha := \inf\{l \geq 1 : \Gamma(l) = \infty\} \). We note that \( \alpha \) will never go above 0 from \( \Delta(\alpha) \) onwards, which implies that we can set \( \kappa(A) = \Delta(\alpha) \). As we assume the moment generating function (MGF) of \( X_n \) is finite in a neighborhood of the origin, the MGF of \( Y_n \) is also finite around 0. We simulate \( \tilde{S}_n \) jointly with \( \Delta(l) \) and \( \Gamma(l) \) until \( \alpha \) using exponential tilting and the acceptance/rejection method (see Section 3.2 for details).
Theorem 1. Assume that $\mathbb{E}[X_n] < \infty$, and

(i) if $\mathbb{E}V_n^q < \infty$ for some $q > 2$ then $\mathbb{E}^n \kappa = O(s^{q/(q-1)})$;

(ii) if we further assume $\mathbb{E}[\exp(\theta V_n)] < \infty$ for some $\theta > 0$ then $\mathbb{E}^n \kappa = O(s \log s)$.

We prove Theorem 1(i) and (ii) by establishing two bounds for $\kappa(A)$ and $\kappa(V)$, respectively. The details are given in Section 4.1.

2.3.2. Simulating the stationary GI/GI/∞ system backwards in time. Next we extend the procedure to simulate states of the stationary infinite server system backwards in time for time intervals of any specified length. The construction is very similar to the single time-point (i.e. time 0) case explained above.

Define $\kappa_n := 1$. We consider a sequence of random times $\kappa_j$, $j = 1, 2, \ldots$, finite with probability 1 but large enough such that

$$|A_n - A_{\kappa_j}| \geq (n - \kappa_j)(\mu - \varepsilon), \quad V_n \leq (n - \kappa_j)(\mu - \varepsilon) \quad \text{for all } n \geq \kappa_j. \quad (1)$$

Note that $V_n \leq |A_n - A_{\kappa_j}|$ for $n \geq \kappa_j$. This implies that a customer who arrives before $A_{\kappa_j}$ will not be in the system at time $A_{\kappa_j}$. Thus, using $\{Z_n: 1 \leq n \leq \kappa_j\}$, we can recover the system descriptor $W(t)$ for $t \in [A_{\kappa_j}, 0]$. See Figure 3 for more details about the construction. Every point $Z_n$, with $n > \kappa_j$, will not land in the upper triangle defined by the vertical line at $A_{\kappa_j}$ and the $-45^\circ$ line intersecting it at the time axis (x-axis).

The $\kappa_j$s give us some flexibility to separate the simulation of the two processes. We first simulate the service times and then, conditional on the sample path of the service time process, we simulate the arrival process jointly with $\kappa_j$.

Define $J_k(0) := 1$, and for $k = 1, 2, \ldots$ and $l = 1, 2, \ldots, \gamma_k$ let

$$J_k(l) := \inf\{n > J_k(l-1): V_n > (n - J_k(0))(\mu - \varepsilon)\}, \quad \gamma_k := \inf\{l \geq 0: J_k(l) = \infty\},$$

$$J_{k+1}(0) := J_k(\gamma_k - 1) \quad \text{for } k = 1, 2, \ldots, \quad l = 1, 2, \ldots, \gamma_k.$$

We first simulate the random time: $J_k(l)$’s for $k = 1, 2, \ldots$ and $l = 1, 2, \ldots, \gamma_k$, and then simulate $\{V_n: n \geq 1\}$ conditional on $J_k(l)$’s. See Algorithm 1 in Section 3.1 for details.

Given the sample path of $\{V_n: n \geq 1\}$ and the $J_k(l)$’s, we next simulate $\{A_n: n \geq 1\}$ and the $\kappa_j$s. This is done by simulating the negative-drifted random walk $\tilde{S}_n$ jointly with its running
time maximum. Define $\Delta_1(0) := 0$ and $\Gamma_1(0) := 0$. Fix $m > 0$ and let

\[\Delta_j(l) := \inf\{n \geq \Gamma_j(l - 1): \tilde{S}_n - \tilde{S}_{\Delta_j(0)} \leq -m\},\]
\[\Gamma_j(l) := \inf\{n \geq \Delta_j(l): \tilde{S}_n - \tilde{S}_{\Delta_j(l)} \geq m\},\]
\[\alpha_j := \inf\{l \geq 1: \Gamma_j(l) = \infty\},\]
\[\kappa_j := \min\{J_k(0): J_k(0) \geq \Delta_j(\alpha_j) + 1\},\]
\[\Delta_{j+1}(0) := \Delta_j(\alpha_j) + 1\]

Note that the process $\tilde{S}_n$ will never go above $\tilde{S}_{\Delta_j(0)}$ from $\Delta_j(\alpha_j)$ onwards. This implies that $|A_n - A_{\kappa_j - 1}| \geq (n - \kappa_j - 1)(\mu - \varepsilon)$ for $n \geq \kappa_j$. Under the light-tail assumption (case 1), we simulate the random times $\Delta_j(l)$ and $\Gamma_j(l)$ for $j = 1, 2, \ldots, l = 1, 2, \ldots, \alpha_j$, and $\{\tilde{S}_n: n \geq 0\}$ by the exponential tilting and acceptance/rejection method; see Algorithm 2 in Section 3.2.

For the heavy-tailed case (case 2), we again simulate the infinite server system with truncated interarrival times first. We carefully choose the truncation parameter $b$ such that $\mathbb{E}[X_n \wedge b] - \varepsilon'$, where $\varepsilon' = \varepsilon/2$ coincides with $\mu - \varepsilon$. Then the $\kappa_j(b)$s we constructed for the truncated system must automatically satisfy the conditions characterizing the $\kappa_j$s in (1) for the original system as well.

2.4. Basic strategy and main results for the GI/GI/C/C system

Once we simulate the customer stream backwards in time and construct the dominating stationary infinite server system accordingly, we can check and find the coalescence time $T = \tau + R(\tau)$, where $\tau$ is defined in Section 2.2 backwards in time. We then use the state of the infinite server system at time $T < 0$ as the state of the many-server loss system at the same time, and go forwards in time using the same stream of customers to construct the state of the loss system up to time 0.

As in the infinite server system case, we again consider a sequence of systems indexed by $s \in \mathbb{N}^+$, where the arrival rate of the $s$th system is scaled by $s$ and the service rate is kept fixed. Let $\rho = \mathbb{E}[V_n]/\mathbb{E}[X_n]$ (the ratio of the mean service time and mean interarrival time of the base system). We analyze the system in two heavy-traffic asymptotic regimes. One is the QD regime where $\rho < 1$ and the number of servers in the $s$th system $C_s$ satisfies $C_s = s$. The other regime is the QED regime, where $\rho = 1$ and the number of servers in the $s$th system $C_s$ satisfies $s + \beta \sqrt{s}$ for some $\beta > 0$.

In Theorem 2 we summarize the performance of the coalescence time in the QD regime.

![Figure 3: Coupling times of the infinite server system.](image-url)
Theorem 2. Assume that $\mathbb{E}X_n < \infty$, and the $X_n$s are nonlattice and strictly positive. We also assume that $\mathbb{E}V_n^q < \infty$ for any $q > 0$ and the CDF of $V_n$ is continuous. Then $\mathbb{E}_n^s \tau = o(s^\delta)$ for any $\delta > 0$.

Remark 1. The assumption about the existence of all moments of the service time distribution covers a range of heavy-tailed distributions, such as Weibull and log-normal, which are known to fit well the data in applications [8].

In Theorem 3 we analyze the performance of the coalescence time in the QED regime.

Theorem 3. Assume that $\mathbb{E}X_n^2 < \infty$. We also assume that $\mathbb{E}V_n^q < \infty$ for any $q > 0$ and the CDF of $V_n$ is continuous. Then, for large enough $\beta$, we have $\log \mathbb{E}_n^s \tau = o(s^\delta)$ for any $\delta > 0$.

The main difficulty in the proof of Theorems 2 and 3 is that it involves tracking the state of the system on a time interval rather than a single time-point. In Section 4.2 we prove the results using a geometric trial construction. To control the variation of the path on a time interval, for Theorem 2, we use the sample path large deviation result [7] for infinite server queues; for Theorem 3, we apply the Borel–TIS (Borel–Tsirelson–Ibragimov–Sudakov) inequality [1] to the diffusion limit processes of infinite server queues [21].

3. Detailed simulation algorithms

In order to provide the details of our simulation algorithms outlined in Section 2.3, we shall first work under the light-tailed case (case 1), where we assume there exists $\theta > 0$ such that $\psi(\theta) < \infty$. The extension to the heavy-tailed case (case 2) was introduced in Section 2 and we shall provide more details in Section 3.3.

We further impose the following assumptions on our ability to simulate the service times and interarrival times.

Assumption 2. We assume that, for $x \geq 0$, $F(x)$ is easily computable, either in closed form or via efficient numerical procedures. Moreover, we can simulate $V_n$ conditional on $V_n \in (a, b]$ with $P(V_n \in (a, b]) > 0$. The sampling time of $V_n$ conditional on $V_n \in (a, b]$ is assumed to be independent of $a$ and $b$.

Assumption 3. Suppose that $G(\cdot)$ is known and that it is possible to simulate from $G_{eq}(\cdot) := \mu^{-1} \int_0^\infty G(t) \, dt$. Moreover, let $G_\theta(\cdot) = \mathbb{E} \exp(\theta X_n - \psi(\theta)) \mathbf{1}_{\{X_n \leq \cdot\}}$ be the associated exponentially tilted distribution with parameter $\theta$ for $\psi(\theta) < \infty$. We assume that we can simulate from $G_\theta(\cdot)$.

Remark 2. Assumption 2 can be applied to virtually any model used in practice, including distributions such as gamma, phase-type, Pareto, Weibull, Log-normal, and mixtures of them. Knowledge of the underlying distribution is required in Procedure 1 below. Note that the required simulation procedure is not restricted to the inversion method. One can use, for example, the acceptance/rejection method, but a good proposal distribution for the conditional distribution given $V_n \in (a, b]$ might have to be constructed based on knowledge of the density function to increase efficiency. Assumption 3 is applicable to models for which the MGF is finite, these include distributions such as gamma, phase-type, hyperexponential, and other mixtures of them.

Next we introduce our algorithm to simulate $\{V_n: n \geq 1\}$. Conditional on the sample path of $\{V_n: n \geq 1\}$, we then explain how to simulate $\{A_n: n \geq 1\}$ together with the $\kappa_j$s.
3.1. Simulation of \( \{V_n : n \geq 1\} \) and the \( J_k(l) \)s for \( k = 1, 2, \ldots, l = 1, 2, \ldots, \gamma_k \)

We shall first introduce the procedure to simulate \( J_1(l) \) for \( l = 1, 2, \ldots, \gamma_1 \). Recall that the \( J_1(l) \)s keep track of all the record breakers, \( \{n : V_n > n(\mu - \varepsilon)\} \). Let \( p(n) = \mathbb{P}(V_1 > n(\mu - \varepsilon)) \). Then \( \mathbb{P}(J_1(l) = \infty \mid J_1(l - 1) = k) = \prod_{n=k+1}^{\infty} (1 - p(n)) \), which is the probability that after \( k \) there are no more record breakers (i.e. a success of the Bernoulli trial occurs), and it is the product of infinitely many terms. We do not know how to evaluate the infinite product exactly. However, we can find a sequence of upper bounds and lower bounds of \( \mathbb{P}(J_1(l) = \infty \mid J_1(l - 1) = k) \) denoted by the \( g(h) \)s and \( f(h) \)s for \( h > k \), respectively, such that

\[
\begin{align*}
    f(h) < f(h + 1) < \cdots < \mathbb{P}(J_1(l) = \infty \mid J_1(l - 1) = k) < \cdots < g(h + 1) < g(h),
\end{align*}
\]

and \( \lim_{h \to \infty} f(h) = \lim_{h \to \infty} g(h) = \mathbb{P}(J_1(l) = \infty \mid J_1(l - 1) = k) \). For \( U \sim \text{uniform}[0, 1] \), we can then determine whether the Bernoulli trial is a success (\( U \leq \mathbb{P}(J_1(l) = \infty \mid J_1(l - 1) = k) \)) or a failure (\( U > \mathbb{P}(J_1(l) = \infty \mid J_1(l - 1) = k) \)) by checking if \( U < f(h) \) or \( U > g(h) \) for some \( h > k \). As

\[
\begin{align*}
    \prod_{n=k+1}^{h} (1 - p(n)) & \geq \mathbb{P}(J_1(l) = \infty \mid J_1(l - 1) = k) \\
    & \geq \prod_{n=k+1}^{h} (1 - p(n)) \exp \left( -\frac{2}{\mu - \varepsilon} \int_{\nu}^{\mu} \mathbb{P}(V_1 > v) \, dv \right),
\end{align*}
\]

the upper bound is easily obtained by truncating the infinite product up to finitely many terms, i.e. \( g(h) = \prod_{n=k+1}^{h} (1 - p(n)) \). For the lower bound, let

\[
    u(h) := \exp \left( -\frac{2}{\mu - \varepsilon} \int_{\nu}^{\mu} \mathbb{P}(V_1 > v) \, dv \right)
\]

then, we have \( f(h) = g(h)u(h) \). Moreover, it is easy to check that

\[
    g(h) - g(h - 1) = p(h) \prod_{i=k}^{h-1} (1 - p(i)) = \mathbb{P}(J_1(l) = h \mid J_1(l - 1) = k).
\]

Thus, if \( g(h + 1) < U < g(h) \), we can also claim that \( J_1(l) = h + 1 \). The ‘sandwiching’ idea just described is the key in Procedure 1 introduced below.

**Procedure 1.** (Simulate \( J_1(l) \) given \( J_1(l - 1) = k \).) 1. Initialize \( h = k + 1, g = 1 - p(h), \) and \( f = gu(h) \). Simulate \( U \sim \text{unif}[0, 1] \).

2. While \( f < U < g \), set \( h = h + 1, g = g(1 - p(h)) \) and \( f = gu(h) \).

3. If \( U \leq f \) then \( J_1(l) = \infty \). Otherwise, \( J_1(l) = h \).

The following lemma guarantees the finite termination of Procedure 1.

**Lemma 1.** If \( \mathbb{E}V_1 < \infty \) then

\[
    \mathbb{P}(J_1(1) = \infty) = \prod_{n=1}^{\infty} (1 - p(n)) \geq \exp \left( -\frac{c \mathbb{E}V_1}{\mu - \varepsilon} \right) > 0
\]

for some \( c > 0 \), depending on the value of \( p(1) \), thus, \( \mathbb{E}J_1 \leq \exp(c \mathbb{E}V_1/(\mu - \varepsilon)) < \infty \).
Proof. We have
\[
\mathbb{P}(J_1(1) = \infty) = \prod_{n=1}^{\infty} (1 - p(n)) \\
\geq \prod_{n=1}^{\infty} \exp(-cp(n)) \\
\geq \exp\left(-\frac{c}{\mu - \varepsilon} \int_0^{\infty} \mathbb{P}(V_1 > v) \, dv\right) \\
= \exp\left(-\frac{c \mathbb{E}V_1}{\mu - \varepsilon}\right).
\]

For \(l = 2, 3, \ldots\), conditional on \(J_1(l - 1) = k\),
\[
\mathbb{P}(J_1(l) = \infty \mid J_1(l - 1) = k) = \prod_{n=k+1}^{\infty} (1 - p(n)) \\
\geq \exp\left(-\frac{c}{\mu - \varepsilon} \int_k^{\infty} \mathbb{P}(V_1 > v) \, dv\right) \\
= \exp\left(-\frac{c \mathbb{E}V_1}{\mu - \varepsilon}\right).
\]

Thus, \(\gamma_1\) is stochastically dominated by a geometric RV with parameter
\[
p = \exp(-c \mathbb{E}V_1/(\mu - \varepsilon)).
\]

The result then follows.

The simulation of \(J_k(l)\) for \(k = 1, 2, \ldots\), \(l = 1, 2, \ldots\), \(\gamma_k\) is very similar to Procedure 1.

Let \(p_k(n) = \mathbb{P}(V_1 > n(\mu - \varepsilon) \mid V_1 \leq (n + J_k(0) - J_{k-1}(0))(\mu - \varepsilon))\). Then, following the same argument leading to (3) and (2), we have \(\mathbb{P}(J_k(1) = \infty) > 0\), and, for \(h > n\),
\[
\prod_{i=n+1}^{h} (1 - p_k(i)) \\
\geq \mathbb{P}(J_k(l) - J_k(0) = \infty \mid J_k(l - 1) - J_k(0) = n) \\
\geq \prod_{i=n+1}^{h} (1 - p_k(i)) \exp\left(-\frac{2 \int_{h}^{\infty} \mathbb{P}(V_1 > v \mid V_1 \leq v + (J_k(0) - J_{k-1}(0))(\mu - \varepsilon)) \, dv}{\mu - \varepsilon}\right).
\]

Let \(u_k(h) := \exp(-2 \int_{h}^{\infty} \mathbb{P}(V_1 > v \mid V_1 \leq v + (J_k(0) - J_{k-1}(0))(\mu - \varepsilon)) \, dv/(\mu - \varepsilon))\). We now propose a modification of Procedure 1 that allows us to simulate \(J_k(l)\) conditional on \(J_k(l - 1) - J_k(0) = n\).

Procedure 2. (Simulate \(J_k(l)\) given \(J_k(l - 1) - J_k(0) = n\).) 1. Initialize \(h = n + 1, g = 1 - p_k(h)\) and \(f = g u_k(h)\). Simulate \(U \sim \text{unif}[0, 1]\).
2. While \(f < U < g\), set \(h = h + 1, g = g(1 - p_k(h))\), and \(f = g u_k(h)\).
3. If \(U \leq f\) then \(J_k(l) = \infty\). Otherwise, \(J_k(l) = J_k(0) + h\).
Algorithm 1. (Sample the \( V_n \)s jointly with the \( J_k(l) \)s.)

**Step 0.** Set \( J_0(0) = -\infty \), \( J_1(0) = 1 \), \( k = 1 \), and \( l = 1 \). Simulate \( V_1 \) according to its nominal distribution.

**Step 1.** Simulate \( J_k(l) \) conditional on the value of \( J_k(l - 1) \) using Procedure 2.

**Step 2.** If \( J_k(l) = \infty \), set \( y_k = l \), \( J_{k+1}(0) = J_k(y_k - 1) \), \( k = k + 1 \), \( l = 1 \) and go back to step 1. Otherwise, go to step 3.

**Step 3.** Simulate \( V_n \) for \( J_k(l - 1) < n < J_k(l) \) by conditioning on \( V_n \leq (n - J_k(0))(\mu - \varepsilon) \) and simulate \( V_J(l) \) by conditioning on \( (J_k(l) - J_k(0))(\mu - \varepsilon) < V_J(l) \leq (J_k(l) - J_k-1(0))(\mu - \varepsilon) \). Set \( l = l + 1 \) and go back to step 1.

When running the above algorithm, we specify \( K \) as the number of intervals \( \{J_k(0), J_k(y_k - 1)\} \) we want to simulate. We then run Algorithm 1 from \( k = 1 \) until \( k = K \). The program will give us \( \{V_n : 1 \leq n \leq J_K(y_K - 1)\} \) and \( J_k(l) \) for \( k = 1, 2, \ldots, K \), and \( l = 1, 2, \ldots, y_k \).

3.2. Simulation of \( \{A_n : n \geq 1\} \) and the \( \Delta_j(l) \)s, \( \Gamma_j(l) \)s for \( j = 1, 2, \ldots, l = 1, 2, \ldots, \alpha_j \)

Given the sample path of \( \{V_n : n \geq 1\} \), we shall first explain how to simulate the \( \Delta_j(l) \)s and \( \Gamma_j(l) \)s sequentially and jointly with the underlying random walk \( \{\tilde{S}_n : n \geq 1\} \). We then simulate \( A_1 \) according to \( G_{\alpha_1}(\cdot) \) and set \( A_{n+1} = A_1 + n(\varepsilon - \mu) - \tilde{S}_n \). The methodology in this section follows closely those in [6] and [13]. The same procedure can be used to simulate a negative-drifted random walk \( \tilde{S}_n \), together with its running time maximum defined as \( \max_{k \geq n} \{\tilde{S}_k\} \).

Let \( \mathcal{F}_n = \sigma\{Y_1, Y_2, \ldots, Y_n\} \) denote the \( \sigma \)-field generated by the \( Y_j \)s up to time \( n \). Define \( T_\xi : = \inf\{n \geq 0 : \tilde{S}_n > \xi\} \) for \( \xi \geq 0 \). Then, by the strong Markov property, we have for \( 1 \leq l \leq \alpha_j \), \( \mathbb{P}(\Gamma_j(l) = \infty | \mathcal{F}_{\Delta_j(l)}) = \mathbb{P}(\Gamma_j(l) = \infty | \tilde{S}_{\Delta_j(l)}) = \mathbb{P}(T_m = \infty) > 0 \). It is important then to note that \( \mathbb{P}(\alpha_j = k) = \mathbb{P}(T_m < \infty)^{k-1}\mathbb{P}(T_m = \infty) \) for \( k \geq 1 \). In other words, \( \alpha_j \) is geometrically distributed. The procedure that we have in mind is to simulate each stage \( \Delta_j(\alpha_j) \) in time intervals, and the number of time intervals is precisely \( \alpha_j \).

Let \( \psi_Y(\theta) = \log \mathbb{E} \exp(\theta Y_1) \) be the log of the MGF of \( Y_1 \). As we assume \( \psi_X(\theta) \) is finite in a neighborhood of the origin, \( \psi_Y(\cdot) \) is also finite in a neighborhood of the origin. Moreover, \( \mathbb{E}Y_1 = \psi'_Y(0) = -\varepsilon \) and \( \text{var}(Y_1) = \psi''_Y(0) > 0 \). Then, by the convexity of \( \psi_Y(\cdot) \), one can always select \( \varepsilon > 0 \) sufficiently small so that there exists \( \eta > 0 \) with \( \psi_Y(\eta) = 0 \) and \( \psi'_Y(\eta) \in (0, \infty) \). The root \( \eta \) allows us to define a new measure \( \mathbb{P}_\eta \) based on exponential tilting so that

\[
\frac{d\mathbb{P}_\eta}{d\mathbb{P}}(Y_1) = \exp(\eta Y_1).
\]

Moreover, under \( \mathbb{P}_\eta \), \( \tilde{S}_n \) is a random walk with positive drift equal to \( \psi'_Y(\eta) \) [2]. Therefore, \( \mathbb{P}_\eta(T_\xi < \infty) = 1 \) and \( \eta(\xi) := \mathbb{P}(T_\xi < \infty) = \mathbb{E}_\eta \exp(-\eta \tilde{S}_\xi) \) for each \( \xi \geq 0 \).

Based on the above analysis, we now introduce a convenient representation to simulate a Bernoulli RV \( J(\xi) \) with probability of success \( \eta(\xi) \), namely,

\[
J(\xi) = 1_{U \leq \exp(-\eta \tilde{S}_{\xi})},
\]

where \( U \) is a uniform RV independent of everything else under \( \mathbb{P}_\eta \). Sampling \( \{\tilde{S}_1, \ldots, \tilde{S}_\xi\} \) conditional on \( T_\xi < \infty \), as we shall explain now, corresponds to basically the same procedure. First, let us write \( \mathbb{P}^* := \mathbb{P}(\cdot | T_\xi < \infty) \). The following result provides an expression for the likelihood ratio between \( \mathbb{P}^* \) and \( \mathbb{P}_\eta \).
Lemma 2. We have
\[ \frac{dP^*}{dP_\eta}(\tilde{S}_1, \ldots, \tilde{S}_{T_\xi}) = \exp(-\eta \tilde{S}_{T_\xi}) \leq \frac{1}{P(T_\xi < \infty)}. \]

Proof. We have
\[ \frac{P(\tilde{S}_1 \in H_1, \ldots, \tilde{S}_{T_\xi} \in H_{T_\xi} \mid T_\xi < \infty = \frac{P(\tilde{S}_1 \in H_1, \ldots, \tilde{S}_{T_\xi} \in H_{T_\xi}, T_\xi < \infty)}{P(T_\xi < \infty) = \frac{E_\eta[\exp(-\eta \tilde{S}_{T_\xi}) 1_{\tilde{S}_1 \in H_0, \ldots, \tilde{S}_{T_\xi} \in H_{T_\xi}}]}{P(T_\xi < \infty)} \]

The previous lemma provides the basis for a simple acceptance/rejection procedure to simulate \{\tilde{S}_1, \ldots, \tilde{S}_{T_\xi}\} conditional on \(T_\xi < \infty\). More precisely, we simulate \{\tilde{S}_1, \ldots, \tilde{S}_{T_\xi}\} from \(P_\eta()\). Then one generates a uniform RV \(U\) independent of everything else and accept the proposal if
\[ U \leq \frac{P(T_\xi < \infty)}{P^{*}(\tilde{S}_1, \ldots, \tilde{S}_{T_\xi}) = \exp(-\eta \tilde{S}_{T_\xi})}. \]

This criterion coincides with \(J(\xi)\) according to (4). So the procedure above simultaneously obtains both a Bernoulli RV \(J(\xi)\) with parameter \(q(\xi)\), and the corresponding path \{\tilde{S}_1, \ldots, \tilde{S}_{T_\xi}\} conditional on \(T_\xi < \infty\) under \(P()\) if \(J(\xi) = 1\).

As \(E[Y_i] = -\epsilon < 0\), by the strong law of large numbers, we have \(\Delta_j(l) < \infty \) a.s. for \(j = 1, 2, \ldots\) and \(l = 1, 2, \ldots, \alpha_j\). Next we define \(\hat{q}(\xi) := 1 - q(\xi) = P(T_\xi = \infty)\) and \(P'(\cdot) := P(\cdot \mid T_\xi = \infty)\). The following result provides an expression for the likelihood ratio between \(P'\) and \(P\).

Lemma 3. We have
\[ \frac{dP'}{dP_\eta}(\tilde{S}_1, \ldots, \tilde{S}_n) = \frac{1}{P(T_\xi = \infty)} \leq \frac{1}{P(T_\xi = \infty)}. \]

Proof. We have
\[ \frac{P'(\tilde{S}_1 \in H_1, \ldots, \tilde{S}_n \in H_n \mid T_\xi = \infty)}{P(T_\xi = \infty) = \frac{P(\tilde{S}_1 \in H_1, \ldots, \tilde{S}_n \in H_n, T_\xi = \infty)}{P(T_\xi = \infty) = \frac{E_\eta[1_{\tilde{S}_1 \in H_1, \ldots, \tilde{S}_n \in H_n}] P(T_\xi = \infty \mid \tilde{S}_1, \ldots, \tilde{S}_n]}{P(T_\xi = \infty)}}. \]

The result then follows from the strong Markov property and homogeneity of the random walk.

We shall apply acceptance/rejection to a sample from \(P'\). According to Lemma 3, to sample \{\tilde{S}_1, \ldots, \tilde{S}_n\} given \(T_\xi = \infty\), we propose from the original (nominal) distribution and accept with probability \(\hat{q}(\xi - \tilde{S}_n)\) as long as \(\tilde{S}_j \leq \xi\) for all \(0 \leq j \leq n\). In order to perform the acceptance/rejection step we need to sample a Bernoulli with parameter \(\hat{q}(\xi - \tilde{S}_n)\), but this can be easily done using (4).

Consider \(0 \leq \xi_1 < \xi_2\). We define \(P'^o() := P(\cdot \mid T_{\xi_1} < \infty, T_{\xi_2} = \infty)\). The following result provides an expression for the likelihood ratio between \(P'^o\) and \(P_\eta\).
Algorithm 2. Given the 
and go back to step 1. Otherwise
If \( \gamma \neq 0 \), let
Let
Step 3. If \( \xi < S_{T_{\gamma}} \), go back to step 1. Otherwise \( J(\xi - S_{T_{\gamma}}) = 0 \), let
Step 4. Simulate \( S_{T_{\gamma}} \) from \( \mathbb{P}_\eta(\cdot) \). Sample a Bernoulli
with parameter \( q(\xi - S_{T_{\gamma}}) \) using (4) and continue to step 5. Otherwise (i.e. \( S_i > \xi \) for some \( 1 \leq i \leq T_{\gamma} \)) go back to step 1.
Step 5. If \( J^* = 1 \), let
Step 6. Let \( h = \Delta_{j+1}(0) - \Delta_j(\alpha_j) \). Sample \( S_1, \ldots, S_h \) from the original distribution. 
Step 7. If \( S_i \leq \xi \) for all \( 1 \leq i \leq h \), then sample a Bernoulli \( J(\xi - S_h) \) with parameter \( q(\xi - S_h) \) using (4) and continue to step 8. Otherwise (i.e. \( S_i > \xi \) for some \( 1 \leq i \leq h \)), go back to step 6.
Step 8. If \( J(\xi - S_h) = 0 \), let \( \tilde{S}_{\Delta_j(\alpha_j) + i} = \tilde{S}_{\Delta_j(\alpha_j)} + S_i \) for \( i = 1, \ldots, h \). Set
When applying Algorithm 2, we must specify \( K \) as the number of intervals \( \{\kappa_{j-1}, \kappa_j\} \) we want to simulate. We then run Algorithm 2 from \( j = 1 \) until \( j = K \), and obtain \( \{A_n : 1 \leq n \leq \kappa_K\} \) and \( \{\kappa_j : 1 \leq j \leq K\} \).
3.3. Coupled infinite server system with truncated interarrival times

In this section we provide some additional details for simulating the coupled truncated infinite server system with the original infinite server system.

We first explain how to simulate $A_1$ jointly with $A_1(b)$. The equilibrium distribution of $X_n$ is $G_{eq}(x) = \int_0^x \overline{G}(u) \, du / \overline{E} X_n$ and the equilibrium distribution of $X_n \wedge b$ is $G_{eq}^b(x) = \int_0^x \overline{G}(u) \, du \, \mathbf{1}_{x \leq b} / \overline{E} [X_n \wedge b]$. Thus, we simulate $A_1$ with CDF $G_{eq}(x)$. If $A_1 \leq b$, we set $A_1(b) = A_1$. Otherwise if $A_1 > b$, we keep simulating $X_e$ with CDF $G_{eq}(x)$ until $X_e \leq b$ and set $A_1(b) = X_e$. In particular, we have $A_1(b) \leq A_1$.

When simulating the $X_n \wedge bs$ from the nominal distribution, we first simulate $X_n$ with CDF $G(\cdot)$ and set $X_n \wedge b = \min\{X_n, b\}$. Denote $Y_n(b) = (\overline{E}[X_n \wedge b] - \varepsilon') - X_n \wedge b$ and let $\eta_b > 0$ be chosen such that $\log \overline{E} \exp(\eta_b Y_n(b)) = 0$. When simulating the $X_n \wedge bs$ under exponential tilting $\overline{P}_{\eta_b}(\cdot)$, we first simulate $Y_n(b)$ under $\overline{P}_{\eta_b}(\cdot)$ and set $X_n \wedge b = (\overline{E}[X_n \wedge b] - \varepsilon') - Y_n(b)$. If $X_n \wedge b < b$, set $X_n = X_n \wedge b$. Otherwise $(X_n \wedge b = b)$ and sample $X_n$ conditional on $X_n \geq b$ under the nominal distribution $\overline{P}(\cdot)$.

4. Performance analysis

In this section we analyze the running time of our algorithms. We start with the infinite server system and then analyze the coalescence time of the many-server loss system.

4.1. Termination time for the infinite server system (proof of Theorem 1)

Theorem 1 provides the relationship between the moment of the service times and $\mathbb{E}_s \kappa$. Next, we provide a proof of Theorem 1. We shall omit the subscripts $\pi$ and $s$ when there is no confusion for notational convenience. We first provide a proof of the light-tailed case. Recall that $\kappa = \max\{\kappa(V) , \kappa(A)\}$, where $\kappa(V) = \inf\{k > 1 : V_{n+1} \leq n(\mu - \varepsilon) / s \text{ for all } n \geq k\}$ and $\kappa(A) = \inf\{k > 1 : A_{n+1} \geq n(\mu - \varepsilon) / s \text{ for all } n \geq k\}$. We prove the theorem by establishing the bounds for $\kappa(V)$ (see Lemma 5) and $\kappa(A)$ (see Lemma 6) separately.

**Lemma 5.** If $\mathbb{E} V_n^q < \infty$ for some $q > 2$, then $\mathbb{E} \kappa(V) = O(s^{q/(q-1)})$.

**Proof.** Let $p(n) = \mathbb{P}(V_1 > n(\mu - \varepsilon) / s)$. For sufficiently large $k$, we have

$$
\mathbb{P}(\kappa(V) > k) = 1 - \prod_{n=k+1}^{\infty} (1 - p(n)) \leq 1 - \exp\left( - \frac{2s}{\mu - \varepsilon} \int_{k(\mu - \varepsilon)/s}^{\infty} \mathbb{P}(V > v) \, dv \right).
$$

By Chebyshev’s inequality, $\mathbb{P}(V_n > v) \leq \mathbb{E} V_n^q / v^q$. Let $\delta = 1/(q - 1)$, then for sufficiently large $s$, we have

$$
\sum_{k=\delta^{q+1}/s}^{\infty} \mathbb{P}(\kappa(V) > k) \leq \sum_{k=\delta^{q+1}/s}^{\infty} \frac{2s}{\mu - \varepsilon} \int_{k(\mu - \varepsilon)/s}^{\infty} \mathbb{P}(V > v) \, dv \\
\leq \frac{2\mathbb{E} V_n^q s^q}{(q - 1)(q - 2)(\mu - \varepsilon)^q} \sum_{k=\delta^{q+1}/s}^{\infty} \frac{1}{k^{q-1}} \\
= O(s^{q - (1+\delta)(q-2)}).
$$
As $q - (1 + \delta)(q - 2) = 1 + \delta$,

$$E_k(V) = \sum_{k=0}^{\infty} P(k(V) > k)$$

$$= \sum_{k=0}^{s^{1+\delta} - 1} P(k(V) > k) + \sum_{k=s^{1+\delta}}^{\infty} P(k(V) > k)$$

$$\leq s^{1+\delta} + O(s^{1+\delta}).$$

Note that when $E \exp(\theta V_n) < \infty$ for some $\theta > 0$, $P(V_n > v) \leq E \exp(\theta (V_n - v)) = E \exp(\theta V_n) \exp(-\theta v)$. Similarly, as above, for sufficiently large $s$, we have

$$\sum_{k=\lceil (2/\theta(\mu-\varepsilon))s \log s \rceil}^{\infty} P(k(V) > k) \leq 2E \exp(\theta V_n) \sum_{k=0}^{s \log s - 1} P(k(V) > k) \leq 2E \exp(\theta V_n) \sum_{k=0}^{\infty} P(k(V) > k) \leq 2E \exp(\theta V_n) \sum_{k=0}^{\infty} P(k(V) > k) \leq s \log s + O(1).$$

Thus, if $E \exp(\theta V) < \infty$ for some $\theta > 0$ then $E_k(V) = O(s \log s)$.

**Lemma 6.** Assume there exist $\theta > 0$, such that $\psi(\theta) < \infty$, then $E_k(A) = O(s)$.

**Proof.** Based on Algorithm 2, we divide the proof into two parts. We first prove that the expected number of iterations is $O(1)$. We then prove that the expected number of steps to pass $-m$ or $m$ from $0$ is $O(s)$.

Let $T_{\xi} = \inf\{n \geq 0 : \tilde{S}_n > \xi\}$. Recall that for the base system there exist $\eta > 0$ with $\psi_Y(\eta) = 0$ and $\psi_Y(\eta) > 0$. The number of iterations is distributed as a geometric RV with probability of success $P(T_m = \infty) = 1 - E_\eta \exp(-\eta \tilde{S}_m)$.

Then for the $s$th system with $Y_s = Y/s$, we have $S_n/s > m$ is equivalent to $\tilde{S}_n > sm$. Thus, the number of iterations is a geometric RV with probability of success $P(T_{sm} = \infty) = 1 - E_\eta \exp(-\eta \tilde{S}_m)$.

Similarly, let $T'_{\xi} = \inf\{n \geq 0 : \tilde{S}_n < \xi\}$. Define $M_n = \tilde{S}_n - n \varepsilon$, then $M_n$ is a martingale with respect to the filtration generated by $\{Y_1, Y_2, \ldots, Y_n\}$. As $E_{\tilde{S}_n} = 0$, we have $P(\tilde{T}_{\tilde{S}_n} < \infty) = 1$.

By the optional sampling theorem, $E_{M_{T'_{\tilde{S}_n}}} = E_{\tilde{S}_{T'_{\tilde{S}_n}}} + \varepsilon E_{T'_{\tilde{S}_n}} = m/\varepsilon - E[m - S_{T_{\tilde{S}_n}}] / \varepsilon$. Then for the $s$th system, we have $E_{T'_{sm}} = sm/\varepsilon - E[sm - S_{T_{sm}}] / \varepsilon$. As $(sm - S_{T_{sm}})$ converges to the ladder height distribution as $s \to \infty$ [2] and $sup_m E[(sm - S_{T_{sm}})^p] < \infty$ for $p > 1$, $E_{T'_{sm}} = O(s)$.

For the heavy-tailed case, we select the truncation parameter $b$ such that $E[X_n \wedge b] = \mu - 1/2\varepsilon$. Then we set $\varepsilon' = 1/2\varepsilon$ and define $k(A(b))$ as a random time satisfying

$$|A_{n+1}| \geq n[(E[X_n \wedge b] - \varepsilon') = n(\mu - \varepsilon) \quad \text{for } n \geq k(A(b)).$$

As $|A_{n+1}| \geq |A_{n+1}(b)|$ under our coupling scheme, we can set $k(A) = k(A(b))$. By Lemma 6, we have $E_k(A) = E_k(A(b)) = O(s)$.

As $\kappa = \max(k(V), k(A(b)))$, we have $E_k = O(s \log s)$. This concludes the proof of Theorem 1.
4.2. Coalescence time for the many-server loss system (proof of Theorems 2 and 3)

As we are simulating the process backwards in time, it is natural to define the filtration \( \mathcal{H}_t = \sigma \{ W(u) : 0 \leq u \leq t \} \), for which \( \mathcal{H}_u \subset \mathcal{H}_t \) for \( 0 \leq u \leq t \). We have \( \tau \) as a stopping time with respect to \( \mathcal{H}_t \). Next we try to draw connections between the backward process and some forward process. Define \( \tau^* := \inf \{ t + R(t) : \sup_{t \leq u \leq t + R(t)} \{ Q(u, 0) \} < s, t \geq 0 \} \). We have that \( \tau^* \) is a stopping time with respect to \( \mathcal{H}_t \), where \( \mathcal{H}_t = \sigma \{ M(u) : 0 \leq u \leq t \} \). The stochastic process \( \{ Q(t, 0) : t \in \mathbb{R} \} \) has a piecewise constant sample path with finitely many points of discontinuity on any finite length intervals a.s. Thus, for any fixed \( T > 0 \), we have

\[
\mathbb{P}(\pi \tau > T) = \mathbb{P}(\pi \tau > T = \mathbb{P}(\pi \tau > T \cap \{ R(t) > \delta \}) \mathbb{P}(\pi \tau > T \cap \{ R(t) > \delta \}).
\]

The second equality holds by stationarity. We have \( \mathbb{E}(\tau) = \mathbb{E}(\tau^*) \).

Next we use a special construction similar to that in [5, Section 4] to prove the results for \( \mathbb{E}(\tau^*) \). The idea is to use a geometric trial argument. We divide the time frame into blocks that are roughly independent. If the process is well behaved (staying around its measure-valued fluid limit) on one block, then \( \tau^* \) is reached before the end of that block.

Let \( \bar{Q}(t, y) \) denote the number of customers in the infinite server system that starts empty at time 0 with remaining service time greater than \( y \) at time \( t \geq 0 \). For convenience, we also define \( \bar{Q}(t, y) = \bar{Q}(u + t, y) = \bar{Q}(u, t + y) \) as the number of customers who arrive after \( u \) with remaining service time larger than \( y \) at time \( u + t \).

4.2.1. Proof of Theorem 2. We first prove the theorem for the light-tailed case. The heavy-tailed case proceeds by selecting the truncation parameter for sufficiently large \( b \).

For the QD regime, by ‘well behaved’, we mean that the process does not deviate by \( \delta s \) for some \( \delta > 0 \), from its fluid limit. In the following lemma we state that the probability of not being ‘well behaved’ decays exponentially fast with the system scale.

Lemma 7. Assume \( \psi(\theta) < \infty \) for some \( \theta > 0 \) and that the \( \mathcal{X}_n \)s are nonlattice and strictly positive. We also assume the CDF of \( \mathcal{V}_n \) is continuous. Then, for any \( \delta > 0 \), there exist \( \mathbb{I}_{\delta} > 0 \) such that

\[
\mathbb{P}(\bar{Q}(t, y) > (1 + \delta)\lambda s \int_0^{t+y} \bar{F}(u) \, du \text{ for some } t \in [0, 1], y \in [0, \infty)) = \exp(-s\mathbb{I}_{\delta} + o(s)).
\]

The proof of Lemma 7 follows from the two-parameter sample path large deviation result for infinite server queues in [7]. We omit it here.

Next we introduce our construction of ‘blocks’. Let \( l(s) = \inf \{ y : (1 + \delta)\lambda s \int_y^\infty \bar{F}(u) \, du \leq \frac{1}{2} \} \). We define the following sequence of random times \( \mathcal{E}_j \)s: \( \mathcal{E}_0 := 0 \). Given \( \mathcal{E}_i \) for \( i = 1, 2, \ldots \), define

\[
\begin{align*}
r_i &:= \inf \{ k : k \geq R(\mathcal{E}_{i-1}), k = 1, 2, \ldots \}, \\
z &:= \inf \{ k : k \geq l(s), k = 1, 2, \ldots \}, \\
\mathcal{E}_i &:= \mathcal{E}_{i-1} + r_i + z.
\end{align*}
\]
We define a Bernoulli RV $\xi_i$, with $\xi_i = 1$ if and only if
\[
\hat{Q}_{\Xi_{i-1}+(k-1)f_0(t, y)} \leq (1 + \delta)\lambda s \int_y^{t+y} \bar{F}(u) \, du \quad \text{for all } t \in [0, 1], \ y \in [0, \infty)
\]
and every $k = 1, 2, \ldots, r_i + z$.

Choose $\delta < 1/\rho - 1$. We first check that $\xi_i = 1$ implies that $\tau^*$ is reached before $\Xi_i$. Since $r_i \geq R(\Xi_{i-1})$, all the customers in the system at time $\Xi_{i-1} + r_i$ will be those who arrive after $\Xi_i$. Then $\xi_i = 1$ implies that
\[
Q(\Xi_{i-1} + r_i, y) \leq \sum_{k=1}^{r_i/(\lambda s)} \int_{(k-1)f_0+y}^{k+\lambda s+y} \bar{F}(u) \, du
\]
\[
= (1 + \delta)\lambda s \int_y^{r_i+y} \bar{F}(u) \, du
\]
\[
\leq (1 + \delta)\lambda s \int_y^{\infty} \bar{F}(u) \, du,
\]
thus, $R(\Xi_{i-1} + r_i) \leq l(s)$.

For every $t \in (k-1, k], k = 1, 2, \ldots, z$,
\[
Q(\Xi_{i-1} + r_i + t, y) \leq (1 + \delta)\lambda s \int_y^{r_i+t+y} \bar{F}(u) \, du \leq (1 + \delta)\lambda s \int_y^{\infty} \bar{F}(u) \, du.
\]
Thus,
\[
Q(\Xi_{i-1} + r_i + t, 0) \leq (1 + \delta)\lambda s \leq s \quad \text{for } t \in [0, R(\Xi_{i-1} + r_i)].
\]

Now let $N = \inf\{i \geq 1 : \xi_i = 1\}$, then $\mathbb{E} \tau^* \leq \mathbb{E} \sum_{i=1}^N (r_i + z)$.

We now provide a bound for $\mathbb{E}[\sum_{i=1}^N (r_i + z)]$. The proof is given in Appendix B.

**Lemma 8.** Assume $\psi_N(\theta) < \infty$ for some $\theta > 0$ and that $\psi_N(\theta)$ is continuously differentiable throughout $\mathbb{R}$. We also assume that the CDF of $V_n$ is continuous and $\mathbb{E} V_n^q < \infty$ for any $q > 0$. Then $\mathbb{E}[\sum_{i=1}^N (r_i + z)] = o(s^4)$ for any $\delta > 0$.

This concludes the proof of the light-tailed case. Next we extend the theorem to the heavy-tailed case. We prove it by drawing a connection to the truncated system. Here, we carefully choose the truncation parameter $b$ so that the truncated systems is still operating in the QD regime. More specifically, we choose $b$ such that $\int_b^\infty \bar{G}(x) \, dx < 1/\rho - 1$. This can be achieved since $\mathbb{E} X_n = \int_0^\infty \bar{G}(x) \, dx < \infty$. Then, for fixed $b$, we have
\[
\rho_b = \frac{\mathbb{E}[V_n]}{\mathbb{E} [X_n \wedge b]} = \frac{\mathbb{E} V_n}{\mathbb{E} X_n - \int_b^\infty \bar{G}(x) \, dx} < 1
\]
and $\mathbb{E} \tau(b) = o(s^4)$, for any $\delta > 0$, where $\tau(b)$ denote the coalescence time of the truncated system.

Next we prove by contradiction that the coalescence in the truncated system implies the coalescence in the original system with the same amount of information simulated. Recall that $\tau(b)$ is a random time satisfying that the system has less than $s$ customers at $\tau(b)$. The maximum remaining service time among all customers in the system at time $\tau$ is denoted by $R(\tau(b))$. We have $R(\tau(b)) \leq |\tau(b)|$ and during $R(\tau(b))$ units of time from $\tau(b)$ on the system always has less than $s$ customers. We can look for $\tau(b)$ at the departure times of customers.
We assume that the process $Q(t, y)$ is right-continuous with left limit, so customers departure at time $t$ will not be counted in $Q(t, 0)$. Suppose that $\tau(b)$ equals the departure time of the $n$th customer. Then every customer arriving between $\tau(b)$ and $\tau(b) + R(\tau(b))$ sees strictly less than $s$ customers (excluding him/herself) when he/she enters the system. We set $\tau$ equal to the departure time of the $n$th customer in the original system, and $R(\tau)$, by definition, equals the maximum remaining service time among all customers in the system at time $\tau$. We have $R(\tau) \leq R(\tau(b))$. We claim that every customer arriving between $\tau$ and $\tau + R(\tau)$ must see less than $s$ customers (excluding him/herself) when he/she enters the system. Suppose this is not the case. Then there exists a customer $m$, $1 \leq m \leq n$ who arrives between $\tau$ and $\tau + R(\tau)$ and finds at least $s$ customers in the system already. The customer with the same index $m$ must have arrived between $\tau(b)$ and $\tau(b) + R(\tau(b))$ in the truncated system and $Q(\lambda_m(b)\sim) \geq Q(\lambda_m\sim) \geq s$. We have a contradiction. Therefore, we must have seen the coalescence in the original system as well with the same amount of information simulated.

4.2.2. Proof of Theorem 3. For the QED regime, by ‘well behaved’, we mean that the process does not deviate $C\sqrt{s}$, for some $C > 0$, from its fluid limit. In the following lemma we state that the probability of both being ‘well behaved’ and not ‘well behaved’ are bounded away from 0.

Lemma 9. Fix any $\eta > 0$. Let $v(y) = \left(\int_y^\infty F(u)\,du\right)^{1/(2+\eta)}$. Assume that $EX^2 n < \infty$ and $EV_n^q < \infty$ for any $q > 0$. Then, for any large enough $C$, there exists $\zeta_1(C) > 0$ and $\zeta_2(C) > 0$ such that

$$\mathbb{P}(\bar{Q}(t, y) \leq \lambda s \int_y^{t+y} \bar{F}(u)\,du + C\sqrt{s}v(y) \text{ for all } t \in [0, 1], y \in [0, \infty)) \geq \zeta_1(C)$$

and

$$\mathbb{P}(\bar{Q}(t, y) > \lambda s \int_y^{t+y} \bar{F}(u)\,du + C\sqrt{s}v(y) \text{ for some } t \in [0, 1], y \in [0, \infty)) \geq \zeta_2(C).$$

The proof of Lemma 9 follows from the proof of [5, Lemma 9]. Our case is actually simpler, as we are dealing with a one-sided bound (upper bound) as opposed to the two-sided bound in [5]. This simplification allows us to remove the light-tail assumption on the interarrival time distribution required in [5]. We shall provide only an outline of the procedure here.

For (5), the idea is to consider the diffusion limit of $Q(t, y)$ as a two-dimensional Gaussian random field [21], and then invoke the Borel–TIS inequality [1].

Assume $EX^2 n < \infty$, $EV_n < \infty$, and the CDF of $V_n$ is continuous. Pang and Whitt [21] proved that for GI/GI/$\infty$ queues with any initial age $\mathbb{E}(0)$,

$$\frac{Q(t, y) - \lambda s \int_0^{t+y} \bar{F}(u)\,du}{\sqrt{s}} \Rightarrow R(t, y) \text{ in } D_{[0, \infty]}[0, \infty),$$

where $R(t, y) = R_1(t, y) + R_2(t, y)$ is a Gaussian random field with

$$R_1(t, y) = \lambda \int_0^t \int_{u+x>y+y} I_{[u+x\sim t+y]}\,dK(u, x), \quad R_2(t, y) = \lambda \xi_0^2 \int_0^t \bar{F}(t + y - u)\,dB(u),$$

where $K(u, x) = W(\lambda u, F(x)) - F(x)W(\lambda, 1)$ in which $W(\cdot, \cdot)$ is a standard Brownian sheet on $[0, \infty) \times [0, 1]$ and $B(\cdot)$ is a standard Brownian motion independent of $W(\cdot, \cdot)$. 

Perfect sampling for infinite server and loss systems
We then invoke the Borel–TIS inequality. We shall skip the verification of the conditions for such an invocation here as it is tedious; see [5] for a detailed proof. Let \( S = [0, 1] \times [0, \infty) \). It is shown in [5] that there exist constants \( M_{i, 1} > 0 \) and \( M_{i, 2} > 0 \) such that \( \mathbb{E}[\sup_S \tilde{R}_i(t, y)] \leq M_{i, 1} \) and \( \sup_S \mathbb{E}[\tilde{R}_i(t, y)^2] \leq M_{i, 2} \). For \( C_i \geq \mathbb{E}[\sup_S \tilde{R}_i(t, y)] \) for \( i = 1, 2 \), it follows that

\[
\Pr(\sup_S \tilde{R}_i(t, y) \geq C_i) \leq \exp\left(-\frac{1}{2 \sup_S \mathbb{E}[\tilde{R}_i(t, y)^2]}\right) \left(C_i - \mathbb{E}\left[\sup_S \tilde{R}_i(t, y)\right]\right)^2.
\]

Let \( C \geq 2 \max\{\mathbb{E}[\sup_S \tilde{R}_1(t, y)], \mathbb{E}[\sup_S \tilde{R}_2(t, y)]\} \). Then

\[
\mathbb{P}(R(t, y) \leq C_v(y) \text{ for all } t \in [0, 1], y \in [0, \infty)) \\
\geq \mathbb{P}\left(\sup_S \tilde{R}_1(t, y) + \sup_S \tilde{R}_2(t, y) \leq C\right) \\
\geq \mathbb{P}\left(\sup_S \tilde{R}_1(t, y) \leq \frac{C}{2}\right) \mathbb{P}\left(\sup_S \tilde{R}_2(t, y) \leq \frac{C}{2}\right) \\
> 0.
\]

Let \( X_0 \) denote the interarrival time of the first customer and \( V_0 \) denote its service time. We also denote \( \tilde{Q}^0(t, y) \) as an independent infinite server process starting empty and with \( \mathbb{E}(0) = 0 \). Then, for large enough \( s \), we have

\[
\mathbb{P}\left(\tilde{Q}(t, y) \leq \lambda s \int_y^{t+y} \tilde{F}(u) du + C \sqrt{s} v(y) \text{ for all } t \in [0, 1], y \in [0, \infty)\right) \\
= \mathbb{P}\left(\tilde{Q}^0(t - X_0, y) + 1_{\{V_0 > t + y\}} \leq \lambda s \int_y^{t+y} \tilde{F}(u) du + C \sqrt{s} v(y) \text{ for all } t \in [X_0, 1], y \in [0, \infty)\right) \\
\geq \mathbb{P}\left(\tilde{Q}^0(t, y) + 1_{\{V_0 > t + X_0 + y\}} \leq \lambda s \int_y^{t+X_0+y} \tilde{F}(u) du + C \sqrt{s} v(y) \text{ for all } t \in [0, 1 - X_0], y \in [0, \infty)\right) \\
\geq \mathbb{P}\left(\tilde{Q}^0(t, y) \leq \lambda s \int_y^{t+y} \tilde{F}(u) du + C \sqrt{s} v(y) \text{ for all } t \in [0, 1], y \in [0, \infty)\right) \\
= \mathbb{P}\left(\tilde{Q}^0(t, y) - \frac{\lambda s \int_y^{t+y} \tilde{F}(u) du}{\sqrt{s}} \leq C v(y) \text{ for all } t \in [0, 1], y \in [0, \infty)\right).
\]
As we introduce a Bernoulli RV customers at time \( t \) for the QD regime, we define the sequence of random times

\[
\{\tau_i\}_{i=1}^{\infty}
\]

It is easy to check that the set \( \{ f: |f(t, y)| \leq C v(y) \text{ for all } t \in [0, 1], y \in [0, \infty) \} \) is a continuity set. Thus, by the functional central limit theorem result in [21], we have

\[
\mathbb{P}\left( \frac{\bar{Q}(t, y) - \lambda s \int_y^{t+y} \bar{F}(u) \, du}{\sqrt{s}} \leq C v(y) \text{ for all } t \in [0, 1], y \in [0, \infty) \right) \implies \mathbb{P}(R(t, y) \leq C v(y) \text{ for all } t \in [0, 1], y \in [0, \infty)) > 0.
\]

Inequality (6) is easy to prove as we can always isolate a point \((t^*, y^*)\) inside \( S \). The projection of the process on that point possesses a Gaussian distribution. More specifically,

\[
\mathbb{P}\left( \bar{Q}(t, y) > \lambda s \int_y^{t+y} \bar{F}(u) \, du + C\sqrt{s} v(y) \text{ for some } t \in [0, 1], y \in [0, \infty) \right) \geq \mathbb{P}\left( \bar{Q}(t^*, y^*) > \lambda s \int_y^{t+y^*} \bar{F}(u) \, du + C\sqrt{s} v(y^*) \right)
\]

and by Fatou’s lemma

\[
\liminf_{s \to \infty} \mathbb{P}\left( \frac{\bar{Q}(t^*, y^*) - \lambda s \int_y^{t+y^*} \bar{F}(u) \, du}{\sqrt{s}} > C v(y^*) \right) \geq \mathbb{P}(R(t^*, y^*) > C v(y^*)) > 0.
\]

Let \( m(s) = \inf\{ y: C \sqrt{s}(v(y) + \int_y^\infty v(s) \, ds) \leq \frac{1}{2} \} \). Following the same construction as for the QD regime, we define the sequence of random times \( \Xi_i \) as \( \Xi_0 := 0 \). Define \( \Xi_i, i = 1, 2, \ldots \),

\[
\tau_i := \inf\{ k: k \geq R(\Xi_{i-1}), k = 1, 2, \ldots, \}
\]

and every \( k = 1, 2, \ldots, r_i + z \).

We introduce a Bernoulli RV \( \xi_i \) with \( \xi_i = 1 \) if and only if

\[
\bar{Q}(\Xi_{i-1} + (k-1) z, y) \leq \lambda s \int_y^{t+y} \bar{F}(u) \, du + C\sqrt{s} v(y) \text{ for all } t \in [0, 1], y \in [0, \infty),
\]

and every \( k = 1, 2, \ldots, r_i + z \).

Next we show that \( \xi_i = 1 \) implies that \( \tau^* \) is reached before \( \Xi_i \). Since \( r_i \geq R(\Xi_{i-1}) \), all the customers at time \( \Xi_{i-1} + r_i \) will be those who arrive after \( \Xi_i \). Thus, we have \( \xi_i = 1 \) implies that

\[
\bar{Q}(\Xi_{i-1} + r_i, y) \leq \sum_{k=1}^{r_i} \{ \lambda s \int_{(k-1) z + y}^{k z + y} \bar{F}(u) \, du + C\sqrt{s} v((k-1) + y) \}
\]

As \( \int_y^\infty \bar{F}(u) \, du \) decays faster than \( v(y) \) as \( y \) grows large, for large enough \( s \), we have

\[
R(\Xi_{i-1} + r_i) < m(s).
\]
Likewise for every \( t \in (k-1, k) \) and \( k = 1, 2, \ldots, z, \)

\[
Q(\Xi_{i-1} + r_i + t, y) \leq \lambda s \int_y^\infty \tilde{F}(u) \, du + C \sqrt{s} \left( v(y) + \int_y^\infty v(u) \, du \right).
\]

Thus, when \( \beta > C(v(0) + \int_0^\infty v(u) \, du) \) for \( t \in [0, R(\Xi_{i-1} + r_i)], \) we have

\[
Q(\Xi_{i-1} + r_i + t, 0) \leq s + C \left( v(0) + \int_0^\infty v(u) \, du \right) \sqrt{s} \leq s + \beta \sqrt{s}.
\]

Now let \( N = \inf\{i \geq 1 : \xi_i = 1\}. \) Then \( E\tau^* \leq E[\sum_{i=1}^N (r_i + z)]. \)

Next we show a bound for \( E[\sum_{i=1}^N (r_i + z)]. \) The proof is given in Appendix B.

**Lemma 10.** Assume \( E X_n^2 < \infty \) and \( EV_n^q < \infty \) for any \( q > 0. \) Then \( \log E[\sum_{i=1}^N (r_i + z)] = o(s^\delta) \) for any \( \delta > 0. \)

Note that our proof of Theorem 3 requires only the existence of the second moment of the interarrival time distribution. We thus conclude the proof of Theorem 3.

4.2.3. Numerical experiment. In this section we perform some simulation experiments aimed at verifying the running time of our algorithm measured by \( E_n^\tau [\tau] \) for different values of \( s. \) The algorithms appear to have a substantially better performance in practice. In the QD regime, our numerical experiments suggest that \( E_n^\tau [\tau] \) is almost bounded as apposed to growing sublinearly with \( s \) as indicated by Theorem 2. This is because in the QD regime the stationary probability that the queue length process is above \( C_\delta \) decays exponentially with the system scale \( s. \) In the QED regime, our numerical experiments suggest a growth rate of \( O(\sqrt{s}) \) as apposed to the subexponentially growth rate in Theorem 3. This empirical bound is intuitive, as in the QED regime the situation when coalescence occurs is similar to the case when a mean 0 random walk spends \( s \) units of time below 0. If the increments of the random walk have finite variance then this situation occurs with probability \( O(1/\sqrt{s}). \)

The performance was tested using a wide range of distributions and the overall conclusions are similar. Our results (see Tables 1 and 2) are obtained assuming that a generic base interarrival time \( X_\gamma \) follows a gamma distribution with shape parameter \( 2 \) and rate parameter \( 2 (\Gamma(2, 2)). \) For the \( s \)th system, the interarrival is distributed as \( X_\gamma / s, \) and a generic service time, \( V_\gamma, \) follows a log-normal distribution, where \( \log V_\gamma \sim N(-\frac{1}{2}, \frac{1}{2}). \) We use \( 10^3 \) replications for each value of \( s. \)

We tested our code in the case of Poisson arrivals and exponential service time distributions. In this case, \( \mathbb{E}[Q^L(\infty, 0)] \) can be computed analytically. We tried (a) \( \lambda = 100, \mu = 1, \) and \( C = 105; \) in this case, \( \mathbb{E}[Q^L(\infty, 0)] = 95.1739; \) (b) \( \lambda = 100, \mu = 1, \) and \( C = 105; \) in this case, \( \mathbb{E}[Q^L(\infty, 0)] = 97.2537; \) (c) \( \lambda = 500, \mu = 1, \) and \( C = 511; \) in this case, \( \mathbb{E}[Q^L(\infty, 0)] = 488.7970; \) (d) \( \lambda = 500, \mu = 1, \) and \( C = 550; \) in this case, \( \mathbb{E}[Q^L(\infty, 0)] = 499.2344. \) In all these cases, we simulated \( 10^3 \) replications. The corresponding 95% confidence interval contains the true value in each case.
Table 2: Simulation results for τ (QED: \( \lambda = s, C_s = s + 2\sqrt{s} \)).

| s     | Mean   | 95% confidence interval |
|-------|--------|-------------------------|
| 100   | 22.6297| [21.3381, 23.9213]      |
| 500   | 37.0449| [32.7770, 41.3128]      |
| 1000  | 42.0704| [37.9622, 46.1786]      |

Appendix A. Proof of Proposition 1

By Chebyshev’s inequality,
\[
P(A_{n+1} < n(\mu - \varepsilon)) \leq \frac{\text{var}(X)}{n^2} \leq \frac{\text{var}(X)}{n^2} = \frac{\text{var}(X)}{n^2} < \frac{\text{var}(X)}{n^2}.
\]

for any \( \theta \geq 0 \).

Let \( I_{[-\varepsilon]} := \max_{\theta \geq 0}(-\theta(\mu - \varepsilon) - \psi(-\theta)). \) As \( \psi(0) = 0, \psi'(0) = \mu, \) and \( \psi''(0) = \text{var}(X) > 0, \) \( I_{[-\varepsilon]} > 0. \) Then \( P(A_{n+1} < n(\mu - \varepsilon)) \leq \exp(-nI_{[-\varepsilon]}), \) and
\[
\sum_{n=1}^{\infty} P(A_{n+1} < n(\mu - \varepsilon)) \leq \frac{\exp(-nI_{[-\varepsilon]})}{1 - \exp(-nI_{[-\varepsilon]})} < \infty.
\]

By the Borel–Cantelli lemma, \( \{A_{n+1} \geq n(\mu - \varepsilon)\} \) eventually, a.s.

Similarly and independently, we have
\[
\sum_{n=1}^{\infty} P(|V_n + 1| > n(\mu - \varepsilon))^{\alpha} = \sum_{n=1}^{\infty} P(|V_1|^{1/\alpha} > n(\mu - \varepsilon)) \leq \frac{1}{\mu - \varepsilon} \int_0^\infty P(|V_1|^{1/\alpha} > \nu) d\nu < \infty.
\]

Thus, again by the Borel–Cantelli lemma, \( \{|V_n + 1| \leq (n(\mu - \varepsilon))^{\alpha}\} \) eventually, a.s. Therefore, \( P(\kappa < \infty) = 1. \)

Appendix B. Proof of Lemma 8 and Lemma 10

We first prove the following two lemmas as a preparation.

**Lemma 11.** If \( \mathbb{E} V_n^q < \infty \) for any \( q > 0, \) then for any fixed \( p > 0, \) \( \mathbb{E}[(\max_{k=1,2,...,n} V_k)^p] = o(n^p) \) for any \( \delta > 0. \)

**Proof.** For any fixed \( \delta > 0, \) we can find \( \delta' \in (0, \delta). \) Let \( q = 1/\delta' + p. \) By Chebyshev’s inequality, we have \( \bar{F}(u) \leq \mathbb{E}[V^q]/u^q. \) Let \( \bar{F}_n(u) = \mathbb{P}((\max_{k=1,2,...,n} V_k > u), \) then
\[
\mathbb{E}[(\max_{k=1,2,...,n} V_k)^p] = p \int_0^\infty u^{p-1} \bar{F}_n(u) \, du
\leq n^{1/(q-p)} + np \int_0^\infty u^{p-1} \bar{F}(u) \, du
\leq n^{1/(q-p)} + np \int_0^\infty \mathbb{E} V^q u^{p-1} \, du
= n^{\delta'} + \frac{p}{q-p} \mathbb{E} V^q.
\]
Now we turn to Lemma 12 below. First note that by Holder’s inequality, we have

\[ \mathbb{E}\left[ \sum_{i=1}^{N} (r_i + z) \right] = \mathbb{E}\left[ \sum_{i=1}^{\infty} (r_i + z) \mathbf{1}_{\{N \geq i\}} \right] \leq \sum_{i=1}^{\infty} \mathbb{E}[(r_i + z)^2]^{1/2} \mathbb{P}(N \geq i)^{1/2}. \]

**Lemma 12.** If \( \mathbb{E}X_n < \infty \) and \( \mathbb{E}V_n^p < \infty \) for any \( p > 0 \), then for any \( p \geq 1 \), we have \( \mathbb{E}(r_i + z)^p = o(s^\delta) \) for any \( \delta > 0 \).

**Proof.** By Minkowski inequality, \( \mathbb{E}[(r_i + z)^p]^{1/p} \leq \mathbb{E}[r_i^p]^{1/p} + z. \) Using similar argument as in the proof of Lemma 11, we can show that \( l(s) = o(s^\delta) \) for any \( \delta > 0 \), thus \( z = o(s^\delta) \) for any \( \delta > 0 \).

For fixed \( \delta > 0 \), we can find \( \delta' \in (0, p\delta/(1 + p\delta)) \) such that

\[ \mathbb{E}[r_i^p] \leq \mathbb{E}\left[ \left( \sum_{k=1}^{N_i} \mathbf{1}_{\{\xi_{i-1} - \xi_{i-2} \}} \right)^p \right] \leq C_0 \mathbb{E}[(N_{i-1} - N_{i-2})^\delta] \]

(Lemma 11)

\[ \leq C_1 \mathbb{E}[(N_{i-1} - N_{i-2})^\delta] \quad \text{(Jensen’s inequality for concave function)} \]

\[ \leq C_2 s^\delta \mathbb{E}[r_{i-1} + z]^\delta \quad \text{(key renewal theorem)}. \]

Let \( w_i = r_i + z \) for \( i = 1, 2, \ldots \). As \( z \) is a constant that only depends on \( s \) and \( z = o(s^\delta) \),

then \( \mathbb{E}w_i \geq z \geq 1 \) and \( \mathbb{E}w_i = \mathbb{E}r_i + z \leq C s^\delta \mathbb{E}w_i^{1/\delta} + z \leq C s^\delta (\mathbb{E}w_i - 1)^{\delta/\delta'} \), where \( C = C_2 s^\delta \). As \( \mathbb{E}[r_i^p] = \mathbb{E} \exp(o(s)) \). By iteration, we have \( \mathbb{E}w_i \leq \tilde{C}^{1/(1-\delta')} s^{\delta/(1-\delta')} \) for \( i = 1, 2, \ldots \). Thus, \( \mathbb{E}r_i^p = o(s^\delta) \) and \( \mathbb{E}(r_i + z)^p = o(s^\delta) \).

**Proof of Lemma 8.** We first note that \( \mathbb{P}(\xi_i = 0) \leq \mathbb{E}[w_1] \exp(-s I_{[\delta]}^* + o(s)) \) by Lemma 7. We have \( \mathbb{P}(N \geq 1) = 1 \) and \( \mathbb{P}(N \geq 2) = \mathbb{P}(\xi_1 = 0) \leq \mathbb{E}[w_1] \exp(-s I_{[\delta]}^* + o(s)) \). Recall that \( w_i = r_i + z \) for \( i = 1, 2, \ldots \). It holds that

\[ \mathbb{P}(N \geq 3) = \mathbb{P}(N \geq 1)\mathbb{P}(N \geq 2 | N \geq 2) \]

\[ = \mathbb{P}(\xi_1 = 0)\mathbb{P}(\xi_2 = 0 | \xi_1 = 0) \]

\[ \leq \mathbb{P}(\xi_1 = 0) \mathbb{P}[w_2 \mid \xi_1 = 0] \exp(-s I_{[\delta]}^* + o(s)) \]

\[ \leq \mathbb{E}[w_1] \mathbb{P}[w_2 \mid \xi_1 = 0] \exp(-s I_{[\delta]}^* + o(s)). \]

Next we prove that \( \mathbb{E}[w_2 \mid \xi_1 = 0] = \exp(o(s)). \) Note that \( \mathbb{P}(\xi_i = 0) \geq \exp(-s I_{[\delta]}^* + o(s)) \) by Lemma 7. Then for any \( p > 0, q > 0 \), and \( 1/p + 1/q = 1 \),

\[ \mathbb{E}[w_2 \mid \xi_1 = 0] = \frac{\mathbb{E}[w_2 \mathbf{1}_{\{\xi_1 = 0\}}]}{\mathbb{P}(\xi_1 = 0)} \]

\[ \leq \frac{\mathbb{E}[w_2]^{1/p} \mathbb{P}(\xi_1 = 0)^{1/q}}{\mathbb{P}(\xi_1 = 0)} \quad \text{(Holder’s inequality)} \]

\[ \leq \mathbb{E}[w_2]^{1/p} \mathbb{E}[w_1]^{1/q} \exp\left(\frac{1}{p} s I_{[\delta]}^* + o(s)\right). \]

Thus, \( 1/s \log \mathbb{E}[w_2 | \xi_1 = 0] \leq 1/s (1/p \log \mathbb{E}[w_2] + 1/q \log \mathbb{E}[w_1] + o(s)) + 1/p I_{[\delta]}^* \). By sending \( p \) to \( \infty \), we have \( \mathbb{E}[w_2 | \xi_1 = 0] = \exp(o(s)) \).

Similarly by iteration, \( \mathbb{P}(N \geq k) = \exp(-k s I_{[\delta]}^* + o(s)) \) for \( k = 4, 5, \ldots \). Then

\[ \sum_{i=1}^{\infty} \mathbb{P}(N \geq i)^{1/2} = O(1). \]
As $E[\sum_{i=1}^{N}(r_i + z)] \leq \sum_{i=1}^{\infty} E[(r_i + z)^2]^{1/2}P(N \geq i)^{1/2}$ and $E[(r_i + z)^2]^{1/2} = o(s^\delta)$ for any $\delta > 0$, we have $E[\sum_{i=1}^{N}(r_i + z)] = o(s^\delta)$.

**Proof of Lemma 10.** We have $P(N \geq 1) = 1$. It holds that

$$P(N \geq 2) = P(\xi_1 = 0) \leq 1 - E[\xi_1(C)^{\eta_1}] \quad \text{(Lemma 9)}$$

$$\leq 1 - \xi_1(C) \mathbb{E}[w_1] \quad \text{(Jensen’s inequality)}$$

$$= 1 - b \exp(-o(s^\delta)).$$

Moreover,

$$P(N \geq 3) = P(N > 2 | N > 1)P(N > 1)$$

$$= P(\xi_2 = 0 | \xi_1 = 0)P(\xi_1 = 0)$$

$$\leq E[1 - \xi_1(C)^{\eta_1} | \xi_1 = 0]P(\xi_1 = 0)$$

$$\leq (1 - \xi_1(C) \mathbb{E}[w_2 | \xi_1 = 0])P(\xi_1 = 0).$$

Next we show that $E[w_2 | \xi_1 = 0] = o(s^\delta)$ for any $\delta > 0$. Note that $P(\xi_1 = 0) \geq \xi_2(C)$ by Lemma 9. Then $E[w_2 | \xi_1 = 0] = E[w_2 | \xi_1 = 0]P(\xi_1 = 0) \leq E[w_2] / \xi_2(C)$.

Similarly by iteration, we have $P(N \geq k) \leq (1 - b \exp(-o(s^\delta)))^k$ for any $\delta > 0$ and $k = 4, 5, \ldots$. Then, for any $\delta > 0$, $\log \sum_{i=1}^{\infty} P(N \geq i)^{1/2} = o(s^\delta)$. As

$$\mathbb{E}\left[\sum_{i=1}^{N}(r_i + z)\right] \leq \sum_{i=1}^{\infty} \mathbb{E}[(r_i + z)^2]^{1/2}P(N \geq i)^{1/2}$$

and $\mathbb{E}[(r_i + z)^2]^{1/2} = o(s^\delta)$ for any $\delta > 0$, we have

$$\log \mathbb{E}\left[\sum_{i=1}^{N}(r_i + z)\right] = o(s^\delta).$$

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