A Review on Transformerless Step-Up Single-Phase Inverters with Different DC-Link Voltage for Photovoltaic Applications

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Abstract: Photovoltaic (PV) energy has been competitive in power generation as an alternative to fossil energy resources over the past decades. The installation of grid-connected solar energy systems is expected to increase rapidly with the fast development of the power electronics technology. As the key to the interface of the PV energy and the grid, power converters should be reliable, efficient and comply with the grid requirements. Considering the nature of PV energy, the power conversion should be flexible (e.g., high step-up DC-DC conversion and harmonic-free DC-AC conversion). Accordingly, many power electronic converters have been reported in literature. Compared with isolated inverters, transformerless inverters show great advantages. This paper thus presents an overview of the transformerless step-up single-phase inverters for PV applications based on the dc-link configurations. Grid-connected PV inverters are classified as constant dc-link voltage structures, pseudo-dc-link voltage structures, pulsating dc-link voltage structures and integrated dc-link voltage structures. The discussion on the composition of different dc-link structures is presented, which provides guidance to select appropriate transformerless inverter topologies for PV applications.

Keywords: photovoltaic (PV); dc-link voltage; step-up; transformerless; single-phase; PV inverters

1. Introduction

Environmental friendly sustainable energy is making new opportunities for the utilization of renewable energy resources. In the last decade, solar technology has become cheaper and more efficient, making it an attractive alternative to traditional energy sources, that is, fossil fuels and nuclear energy. Photovoltaic (PV) generation systems have become one of the most significant candidates among all the renewable energy sources because the energy that drives them is free and available in abundance [1–3]. Nowadays, PV panels are not only used in space applications but they are also present in everyday life such as powering wristwatches, small calculator and supplying loads in remote sites. In addition, they are also connected to the public grids. As reported in References [4,5], at the end of 2018 PV installations have reached a cumulative installed capacity of 509 GW worldwide.

However, the generated power from the PV panels is influenced by the variation of temperature, irradiation and shadow [6–9]. To deal with the low output voltage of the PV panels, a combination of series- and parallel-connected configurations of the PV panels are used to obtain the desired voltage and power level. In order to achieve the required bus voltage for grid-connected PV systems, a series-connected configuration is the conventional solution [10,11]. Power inverters are essential components that are required to inject the generated PV power into the utility grid. Based on the power level, the power configurations for a PV system can be classified as a centralized structure, multi-string structure, string structure and module structure [12,13], as shown in Figure 1. The centralized structure
combines all PV panels into a single PV array by series and parallel connections to generate a high DC voltage. Afterwards, a grid-connected inverter is adopted to deliver the power to the grid [14,15]. The centralized structure is simple and efficient but still has drawbacks like low system efficiency and redundancy, poor performance when hot spots and shadows are present and high cost [12,16]. The string structure provides energy to the grid-connected power generation system by connecting the PV panels in series. Compared with the centralized structure, the efficiency and redundancy of the string structure are increased but the increased number of the inverters increases the “per W” cost [17,18]. The multi-string structure is composed of several boost converters and an inverter, which combines the advantages of the centralized and string structure. There are two main types of multi-string PV inverters, which can be classified as parallel and series multi-string structures. The multi-string structure can realize the maximum power point tracking in different PV strings, which maximizes the performance of PV system [19]. The centralized grid-connected inverter design of the multi-string structure makes the inverter to operate with high efficiency, reliability and redundancy. The module structure provides great flexibility and plug-and-play for system expansion. Nevertheless, the cost is higher when compared with other structures [20]. Grid-connected PV generation systems can vary significantly from small scale PV panels to large scale PV power plants.

![Grid-connected photovoltaic (PV) systems](image)

**Figure 1.** Grid-connected photovoltaic (PV) systems with: (a) module structure, (b) string structure, (c) multi-string structure and (d) central structure.

Nowadays, researchers are focused on module integrated converters, such as the ac module technology and dc-dc optimizers. Some existing inverters with galvanic isolation can achieve a high-step up gain by increasing the turns ratio of the transformer. To reduce the cost and improve the efficiency, it is suitable to employ transformerless topologies [21]. Transformerless topologies are more efficient, lighter, less bulky and cheaper than topologies with galvanic isolation [22]. These transformerless topologies inherit all the advantages but the parasitic capacitance of the solar panel between the PV array terminals and the ground connection can cause safety issues. Due to the large parasitic capacitance between the ground and the PV panels, the leakage current in the transformerless PV grid-connected system is an important issue [23]. Several topologies, modulation methods and control algorithms have been proposed to minimize the leakage current effectively. Especially for ac module applications, many advanced topologies and innovations have been published in recent years with step-up capability and high efficiency.

This paper presents a comprehensive review of single-phase transformerless grid-connected topologies with step-up capability. Based on the grid requirements, a detailed classification of the transformerless inverters for PV applications is established, which can provide an insightful overview of how to derive transformerless inverters for PV systems. Considering the working principles, the analyzed topologies are discussed in detail to provide recommendations for various
specifications of PV applications. Based on the analysis, some suggestions for choosing appropriate configurations are given.

2. Grid Requirements

The power range of the PV system could vary from hundreds of watts to thousands of megawatts, which need to comply with specific standards for different countries. The grid requirements are an important specification that has a big impact on the design and performance of the PV generation system. Grid requirements proposed by local grid companies in most countries are making efforts to come up with standard grid requirements that can be applied in most areas. Among these institutions, IEEE (Institute of Electrical and Electronic Engineers) in the US, IEC (International Electrotechnical Commission) in Switzerland and DKE (German Commission for Electrical, Electronic and Information Technologies of DIN and VDE) in Germany are the most popular ones that are developing worldwide standards for grid requirements in the PV market. Generally, commercial grid-connected inverters comply with harmonic levels, total harmonics distortion (THD), power factor, dc current level, frequency variation, islanding detection, leakage current and grounding issues. In this part, some typical standards are discussed with focus on harmonic requirements, dc current levels, voltage variations, frequency variations and leakage currents [24].

In Table 1, a summary of the grid requirement in three typical standards considering the harmonic levels, injected dc current, voltage variation and frequency variation is presented [25–27]. IEEE 1547 is most influential standard for interconnection of all forms to develop a single interconnection standard that applies to all technologies. IEC 61727 has done a great job in harmonizing the grid requirements. VDE 0126-1-1 has extended the thresholds for disconnection in the case of abrupt grid impedance changes and even allows an alternative method of an anti-islanding requirement similar to IEEE 1547 presents. Besides the issues listed in Table 1, VDE 0126-1-1 also provides a limit for the leakage current. VDE 0126-1-1 defines both averaged and peak ground current limitations, that is, 30 mA and 300 mA as well as disconnection times by 0.3 s [28].

| Table 1. Summary of the grid requirements in different standards. |
|-----------------|-----------------|-----------------|
| **Nominal power** | IEEE 1547 [25] | IEC 61727 [26] | VDE0126-1-1 [27] |
| Order % | Order % | Order A |
| 3–9 | 4.0 | 3–9 | 4.0 | 3 |
| 11–15 | 2.0 | 11–15 | 2.0 | 5 |
| 17–21 | 1.5 | 17–21 | 1.5 | 1 |
| >35 | 0.3 | >35 | 0.3 | 11 |

| Harmonic level | DC current | Voltage variation | Frequency variation |
|----------------|------------|-------------------|---------------------|
| Order | % | <1% of rated current | <0.5% of rated current | <0.22 A |
| 3–9 | 4.0 | 0.1 s | V < 50% | 1 s |
| 11–15 | 2.0 | V < 50% | 0.16 s | V < 85% | 0.2 s |
| 17–21 | 1.5 | 50% < V < 88% | 2 s | V > 110% | 0.2 s |
| >35 | 0.3 | 110% < V < 120% | 2 s | 47.5 Hz < f < 50.2 Hz | 0.2 s |

3. Transformerless Grid-Connected Topologies with Step-Up Ability

Grid-connected inverters can interface both the PV source and the grid side. On the PV side, it can extract the available maximum power from the PV panels, whereas it transfers sinusoidal current
to the grid side [29–31]. The power injected to the grid needs to fulfill the requirement of the grid, which is highly dependent on the performance of the grid-connected PV inverters. Thus, a lot of PV inverters have been proposed to resolve these issues. The conventional voltage source inverter is widely used as a grid-connected interface for PV power generation systems [12,32]. However, the voltage source inverters can only work as a buck converter, which introduces some limitations in case of low output voltage from the PV panels, e.g., low temperature and irradiance [33,34]. The isolation transformer is generally adopted for the boosting operation, which introduces a bulky, heavy component and increases the cost of the whole generation system [2,35,36]. Even though plenty of inverters have been proposed, some classifications for these inverters are essential for further research. Thus, comprehensive research on the configuration of transformerless step-up grid-connected inverter topologies is presented in this section. The reviewed topologies are classified into several different groups based on the type of dc link—constant dc-link voltage, pseudo-dc-link voltage, pulsating dc-link voltage and integrated dc-link voltage.

3.1. Constant DC-Link Voltage

Since conventional voltage source inverters can only work in buck mode, thus, a front-end dc-dc converter that steps up the low output voltage of the PV panels to a required constant dc-link voltage is necessary. Figure 2a shows the schematic diagrams of a two-stage inverter with constant dc-link voltage. The two-stage inverter consists of one dc-dc boost converter and a single-phase inverter. The cascaded inverter contains more dc-dc converters to get the necessary dc-link voltage. Generally, there is a dc-link capacitor between the output of the dc-dc converter and the input of the inverter [37]. The dc-link capacitor can decouple the dc side and the ac side, thus they can be controlled separately. In this part, some typical single-phase inverters with constant dc-link voltage are presented.

Figure 3 presents some general single-phase inverters, which can be connected to front-end dc-dc converters. Most of these single-phase inverters are derived from the basic half-bridge inverter and full-bridge inverter. Compared with the full-bridge inverter, the half-bridge inverter in Figure 3a has reduced number of semiconductors. However, the dc-link voltage of the half-bridge inverter needs to be double than the peak value of the grid voltage, which in turn increases the voltage stress on the semiconductors [38]. Meanwhile, there are higher requirements for the filter design as the output voltage of the half-bridge inverter becomes bipolar.

To reduce the leakage current, lots of transformerless inverters have been proposed. As is presented in Figure 3c [39], H5 prevents the reactive power exchange during the zero voltage state, which disconnects the PV panel from the grid during the freewheeling period. Hence, the high-frequency content of the common-mode voltage is eliminated. The H5 inherits all the advantages of full-bridge, thus this topology is very suitable for PV applications where high efficiency and low leakage current are required. By adding one diode paralleled to the dc-link of the full-bridge inverter, an auxiliary freewheeling current path is added, which is called as H6D1, as shown in Figure 3d [40]. In comparison with the full-bridge inverter, there are more losses with the additional conduction during freewheeling. By adding two auxiliary freewheeling diodes, the H6D2 inverter is presented in Figure 3e [20]. The blocking voltage across the DC switches can be reduced to half of the dc-link voltage. There are four switches conducting during the active state, leading to higher conduction losses but without affecting the overall high efficiency. The HERIC inverter is presented in Figure 3f [41] with the features similar to H5 inverter that realizes the decoupling of the PV panels during the zero voltage state between the ac side and dc side. Hence the HERIC inverter is therefore very suitable for PV applications having high efficiency, low leakage current and EMI. The HERIC topology can be modified by implementing the bidirectional switch with a diode bridge and one switch as shown in Figure 3g [42]. The FB-ZVR inherits the advantages of high efficiency and low leakage current. However, the efficiency is lower than the HERIC inverter but it can work at any power factor, without modifying the modulation technique. In order to reduce the voltage stress and filter size, the neutral-point-clamped (NPC) inverter is proposed in 1981 [43]. Figure 3h,i show...
the neutral-point-clamped half-bridge inverter and full-bridge inverter [44]. Since the middle point of the dc-link is connected to the grid neutral, the leakage current can be reduced drastically. The NPC topologies have similar features with the topologies mentioned before, thus they are also suitable for transformerless PV applications.

Moreover, NPC topologies show great advantages in high power and voltage applications where the multilevel inverters perform much better than the standard full-bridge 2-level topologies [43]. The constant dc-link is the output of the dc-dc converter, with the development of novel dc-dc converter topologies more constant dc-link PV inverters can be implemented. dc-dc converters are used to step up the PV output voltage to the required voltage level in order to inject power into the grid [45]. There is a dc-link capacitor between the dc part and the ac part, which decouples these two sides [29]. Afterward, these two sides can be controlled separately. The decoupling capacitor is used to limit the voltage ripple. A bigger dc-link capacitor gives a smoother dc-link voltage, which is usually controlled to be constant. Meanwhile, the bigger capacitor costs more and also occupies more space. The conventional two-stage configuration consists of a boost converter and a full-bridge inverter, which is presented in Figure 4a [46]. Figure 4b,c present the quadratic boost converter with the full-bridge inverter and three-level boost converter with a full-bridge inverter, respectively [47,48]. However, the conventional boost converters can only operate in a limited duty ratio, which makes it inappropriate for applications where a high step-up ratio is needed. Moreover, the voltage stress of the switches is high, which increases the cost of the switches. To deal with these issues, parallel technology, interleaved technology and coupled-circuit technology are also used to construct novel dc converters. Figure 4d presents an interleaved boost converter with a full-bridge inverter. To improve the efficiency of the constant dc-link topologies, soft switching technology is also applied. Besides the soft switching technology, some new configurations are proposed according to the input features of PV panels. The time-sharing dual-mode inverter is presented in Figure 4e [49,50]. In this configuration, when the input is higher than the dc-link voltage, the diode bypasses the boost converter, which in turn reduces the switching and conduction losses. To achieve a higher constant dc-link voltage, a cascaded
technology is also applied, as shown in Figure 4f [51,52], however, this kind of topology has higher cost. Most of the configurations using constant dc-link are focused on the improvement of dc-dc converters.

Figure 3. (a) Half-bridge inverter, (b) full-bridge inverter, (c) H5 inverter, (d) H6D1 inverter, (e) H6D2 inverter, (f) HERIC inverter, (g) HB-ZVR and (h) half-bridge three-level NPC inverter, (i) full-bridge five-level NPC inverter.
Figure 4. Two-stage grid-connected single-phase PV inverter with constant dc-link voltage consisting of—(a) a boost converter and a full-bridge inverter with an LCL filter, (b) a quadratic boost converter and a full-bridge inverter with an LCL filter, (c) a three-level boost converter and a full-bridge inverter with an LCL filter, (d) an interleaved boost converter and a full-bridge inverter with an LCL filter, (e) a time-sharing boost converter and a full-bridge inverter with an LCL filter and (f) cascaded boost converters and a full-bridge inverter with an LCL filter.

3.2. Pseudo-DC-Link Voltage

The basic configuration of the pseudo-dc-link inverter is presented in Figure 2b. There is also a front-end dc-ac converter, which generates a rectified sinusoidal voltage at the pseudo-dc-link. The dc-ac converter can implement the MPPT algorithm like the constant dc-link inverter by adjusting the duty ratio or phase difference between different switches. The front-end converter can be the same as the constant dc-link inverter by modifying the modulation wave as an ac reference. The operation of this kind of inverter can be divided into buck mode and boost mode. When the PV output is smaller than the peak value of the grid voltage, the front-end dc-ac converter will operate as a boost converter to step up the input voltage to fulfill the grid requirements with both voltage amplitude and frequency [41,53]. However, if the PV output is larger than the peak value of the grid voltage, the front-end dc-ac converter will operate as a buck converter to step down the input voltage. From the analysis, the pseudo-dc-link inverter can also be regarded as a buck-boost inverter. The pseudo sinusoidal dc-link voltage is unfolded by the full-bridge controlled at line-frequency to obtain a sinusoidal grid voltage. This way the switching losses on the inverter side are decreased considerably [20]. The cost of these topologies is similar to the related constant dc-link inverter but with increased efficiency and power density. However, when the operation modes change between the buck mode and the boost mode, the modulation reference needs to be calculated differently, which might result in a distortion in the output voltage as well as the current. There is no apparent decoupling capacitor in this configuration, thus the parallel capacitor at the input should be large enough to ensure low voltage ripple. However, this electrolytic capacitor reduces the life span of these topologies.
The performance of the pseudo-dc-link inverter also depends on the performance of the front-end dc-ac converter. The front-end dc-ac converter should be able to operate in a large input voltage range, especially for PV application [54].

Figure 5a presents a boost converter with an unfolding circuit [19]. By defining a pseudo-sinusoidal as a reference, this configuration can operate as a step-up inverter with an unfolding circuit. Figure 5b,c are two buck-boost converters operated in discontinuous conduction mode (DCM). When the input is lower than the reference, the front-end dc-dc operates in a boost mode [55]. These two converters are the most frequently used topologies for the buck-boost capability to handle the input variation. Figure 5d shows a tapped buck-boost converter with an unfolding circuit, which can operate with larger input range, especially when the input is extremely low [49]. The tapped buck-boost converter can operate with high boosting gain for PV applications. The pseudo-step-up dc-link inverter can also be derived as a constant dc-link inverter by adding a front-end step-up dc-dc converter with a buck converter to get the desired pseudo-dc-link voltage, which can be treated as a special two-stage constant dc-link inverter when the original pseudo-dc-link inverter is considered as an entirety [56].

![Grid-connected single-phase PV inverter with pseudo-dc-link voltage consisting of: (a) a boost converter and a unfolding inverter with an LCL filter, (b) a buck-boost converter and a unfolding inverter with an LCL filter, (c) a noninverting buck-boost converter and a unfolding inverter with an LCL filter and (d) a switched-inductor buck-boost and a unfolding inverter with an LCL filter.](image)

3.3. Pulsating DC-Link Voltage

The basic configuration of the pulsating dc-link inverter is presented in Figure 2c. These kinds of configurations are generally called impedance-source inverters [57,58]. Basic impedance-source inverters can be generalized as a two-port network with a general inverter. The impedance-source network was originally invented to overcome the limitations of the voltage-source inverter and current-source inverter topologies [59]. Considering the operating process of the impedance-source converter, the pulsating dc-link inverter can be regarded as a single-stage inverter. The input source of these kind of converters can be a voltage source or current source. As the PV curve can be separated into the current and voltage zone, the pulsating dc-link inverter can transfer between these operating zones without any modification of the topology and with similar operating characteristics. By inserting the shoot-through states into the conventional modulation method, the impedance-source inverter can achieve boost capability. Compared with the constant dc-link inverter, the system cost decreases and the efficiency increases. The inverter working in active mode is similar to the constant dc-link inverter. All the shoot-through states are inserted into the original zero states, thus the original operation will not be affected. During the shoot-through states, the impedance-source network is
“disconnected” from the inverter, which makes the dc-link voltage equal to zero [60,61]. The modulation methods for impedance-source inverters are derived from the conventional methods for voltage source inverters by modifying the reference [62]. Thus, these configurations show great potential for renewable applications. However, the introduction of the shoot-through states might deteriorate the common-mode voltage harmonics. Thus, special modulation methods and control techniques are essential for PV applications.

Figure 6a shows the first proposed Z-source inverter [63]. The Z-source network consists of two capacitors, two inductors and one diode. There is a diode in the positive part of the input, which makes the input current discontinuous. The dc-link voltage is pulsating, which increases the complexity of the controller design process. The control of the dc-link voltage can be divided into direct control and indirect control. If the Z-source inverter is controlled directly, some special measuring circuits are needed for detecting the peak value of the dc-link voltage, which is costly. Considering the indirect control, a variable can be chosen to be controlled constant, such as the voltage of the capacitor \( C_1 \). However, the peak value of the dc-link voltage will vary as the input changes, which implies a high requirement for the switches. Figure 6b shows a T-source inverter with a coupled inductor, which can realize a higher boost gain by arranging the winding ratios [58]. A lot of boosting technologies can also be applied to modify the topology of the impedance-source inverter, for example, coupled inductors, voltage multiplier, switched inductor and so forth. In Figure 6c,d, two quasi-Z-source inverters are shown, which consist of the same components as the Z-source inverter [60,64]. The quasi-Z-source inverter inherits all the advantages of the Z-source inverter and can also operate with continuous input current. There is another advantage that the voltage stress on capacitor \( C_2 \) can be decreased dramatically. It can be observed that in the T-source network, two quasi-Z-source networks share the same ground as the input source, which introduces new issues for the common-mode voltage and leakage current when the shoot-through states are adopted in PV systems. These issues can also be mitigated by modifying the topology, for example, inserting a diode in the negative side of the input source, or symmetrical structure. Without additional control signals for the impedance-source network, the pulsating dc-link inverter can also save much cost and become a strong alternative of the conventional two-stage inverter.

**Figure 6.** Grid-connected single-phase impedance-source inverter with pulsating dc-link voltage consisting of: (a) a Z-source network and a full-bridge inverter with an LCL filter, (b) a T-source network converter and a full-bridge inverter with an LCL filter, (c) a input continuous Z-source network and a full-bridge inverter with an LCL filter, (d) a quasi-Z-source network and a full-bridge inverter with an LCL filter.
3.4. Integrated DC-Link Voltage

To improve the efficiency of the whole system and reduce the number of the components, the step-up ability can be integrated into the inverter side, which presents no separate dc-link [65]. Thus, in this part, the integrated dc-link inverters are discussed. The integrated dc-link inverter can be separated into two inverters that share the same input and the same output [66,67]. The outputs of these two inverters have the same amplitudes but are in anti-phase. The output of the integrated dc-link inverter is the difference between these two inverters. Figure 7a presents a differential boost inverter, which generates a high voltage by connecting two boost converters differentially with output filters [68,69]. The two boost converters generate a unipolar sinusoidal voltage with a dc-bias. Figure 7b presents a buck-boost differential inverter with the same differential configuration. A universal single-stage buck-boost inverter is presented in Figure 7c, which can operate in a large range of input voltage. Figure 7d presents a simpler configuration of the single-stage buck-boost inverter to improve efficiency. Figure 7e,f present inverters that have two dc converters operate alternatively for the positive and negative grid voltage with the same input source [70].

![Figure 7](image_url)

Figure 7. Grid-connected single-phase single-stage inverter with integrated dc-link voltage: (a) a universal single-stage inverter with an LCL filter, (b) an integrated boost inverter with an LCL filter, (c) an improved integrated boost inverter with an LCL filter, (d) a full-bridge buck-boost inverter with an LCL filter, (e) a differential buck-boost inverter with an LCL filter and (f) a differential boost inverter with an LCL filter.

4. Comparison of the Four Types of Topologies

In this part, some main challenges of the inverter configurations for PV applications, such as the boosting capability, number of semiconductor devices and passive components, power density, output quality, leakage current and switch voltage stress, are summarized for these four types of
dc-link inverters. Compared with isolated high-step-up inverters, transformerless configurations can reduce the system cost and improve efficiency but also introduce the leakage current issue [71]. No conclusions can be drawn from these summaries which type is the best since these topologies are designed for different grid or residential requirements. Considering the general performance of these four dc-link types of inverters and some special topologies, the comparison between constant dc-link inverter, pseudo-dc-link inverter, pulsating dc-link inverter and integrated dc-link inverters are presented in Table 2 [72–77].

**Table 2. Comparisons of these four dc-link types of step-up transformerless inverters.**

| DC-Link   | Advantage                                                                 | Disadvantage                                                                 |
|-----------|---------------------------------------------------------------------------|------------------------------------------------------------------------------|
| Constant  | High voltage level; High power capability; Reliable output; Modularity structure; Easy to control with dc and ac decoupled. | Large amount of components; Heavy, bulky and costly; Low efficiency; Multi-level needed for higher boosting gain; Leakage current depends on the topologies; Limited operation regions. |
| Pseudo    | Low switching frequency; High power density; Less hardware cost; Buck-boost capability; High efficiency; Low leakage current. | Output distortion when input varies; Zero-crossing distortion; Limited boosting capability; Higher requirements for modulation; High requirements for front-end converters; More semiconductor devices needed. |
| Pulsating | Invulnerable to EMI; High power density; High boosting capability; High efficiency; Less hardware cost; Buck-boost capability. | Control complexity; Higher requirements for modulation; Large leakage current; Higher common-mode voltage harmonics; Vulnerable to input variations; Voltage sag between switching states. |
| Integrated| High power density; Switch multiplexing; Less hardware cost; Less semiconductor devices; Smaller leakage current. | Distortion from the parameter mismatch; Large injected dc current; Small power applications; Zero-crossing distortion in some topologies; Higher operation stress on the components. |

There is a bulky electrolytic input capacitor in parallel with the PV panels to smooth out the input voltage for pseudo-dc-link inverters and integrated dc-link inverters [13,78]. A small capacitor is generally placed in the dc-link of the constant dc-link inverter to decouple the dc and ac parts, which can extend the lifetime of the inverter. Since the dc-link of the impedance-source inverter is pulsating, there will be no capacitor at the dc-link. Similar to integrated dc-link inverters and pseudo-dc-link inverters, an input capacitor can be placed in parallel with the PV panels. Considering the cost and boosting capability, pulsating dc-link inverters show advantages over the other three types. No additional control signals needed for the front-end part and the modification of the modulation methods can achieve the boosting functions. Meanwhile, the front-end parts of the constant dc-link inverter and pseudo-dc-link inverter require additional modulators [79]. Even though there is no control part for the integrated dc-link inverter, the operation stress on the components are bigger, which increases the design cost of the system. The pulsating dc-link inverter can achieve much higher power density with the same cost. The number of the components in the constant dc-link inverter and pseudo-dc-link inverter can be the same. Thus, the cost and size of these two configurations are similar. The pulsating dc-link inverter and integrated dc-link inverter have a much smaller number of both passive and active components, which makes them cheaper than the constant dc-link inverter and pseudo-dc-link inverter. By switch multiplexing, the integrated dc-link inverter can achieve rather high power density. The pulsating dc-link inverters are strong nonlinear converters, thus, the boosting gain can be very high. In order to achieve the same boosting gain in case of the constant dc-link
inverter, multi-level stages are generally necessary [80]. Meanwhile, both pulsating dc-link inverters and pseudo-dc-link inverters can operate as buck-boost inverters according to the input variations. When the input is larger than the peak value of the grid voltage, the pulsating dc-link inverters will operate as a normal H-bridge inverter and the pseudo-dc-link inverters will operate as a buck converter. For some special structures of the integrated dc-link inverters, such as the differential buck-boost inverter, the same operation process can be derived just like the pseudo-dc-link inverters.

The modulation methods for the constant dc-link inverters can be implemented in a simple way by comparing the reference with carrier wave. However, for the pseudo-dc-link inverter, the input voltage is compared with the grid voltage and then the reference will be calculated according to the operating mode of the inverter in either boost mode or buck mode. The reference of the pulsating dc-link inverter is calculated in a similar way compared to the constant dc-link inverter, however, adding the shoot-through duty ratio is complex by modifying the sinusoidal pulse width modulation (SPWM) or space vector pulse width modulation (SVPWM). The modulation of the integrated dc-link inverter needs two sets of conventional modulators. Even though in case of constant dc-link inverters, the whole system is heavy, bulky and costly, the control process of this type of inverters is rather simple. The dc part and the ac part of the constant dc-link inverters are decoupled, which make these kind of inverters expendable with more multi-level stages to obtain the desired output dc-link voltage [81]. However, the pulsating dc-link inverters are vulnerable to input variations, which affect the dynamics of the system. The operation regions of the pseudo-dc-link inverters and integrated dc-link inverters are limited by the adopted dc-ac inverters, which in turn limit the operation power level.

For the pulsating dc-link inverter, the voltage sag might appear in the peak dc-link voltage when the switching state changes. Especially when the dc-link current cannot support the grid current, there will be distortion in the output current. The pseudo-dc-link inverter operates with low switching frequency, distortion appears in the output current during the zero crossing of the grid voltage. As for the integrated dc-link inverter, the parameter mismatch of the two separated inverters can also result in distortion and large dc current injection. Figure 8 shows the simulation results of the dc-link voltage and grid voltage waveform of the discussed PV inverters.

![Figure 8. Typical dc-link voltage and grid voltage waveform of: (a) constant dc-link inverters, (b) pseudo-dc-link inverters, (c) pulsating dc-link inverters and (d) integrated dc-link inverters.](image_url)

5. Conclusions

In this paper, transformerless step-up grid-connected single-phase inverters for PV applications were reviewed based on the type of the dc-link. Grid requirements from typical standards were summarized and compared in terms of harmonic level, injected dc current, voltage variations and frequency variations. The characteristics of the constant dc-link inverter, pseudo-dc-link inverter,
pulsating dc-link inverter and integrated dc-link inverter were discussed. Future topologies can also be included based on the discussions. In addition, their features and effects on the performance of the generation system were also presented. In terms of the comparisons, the constant dc-link inverters cost more but have the advantages of modularity in structure and better output performance. Moreover, the pseudo-dc-link inverters can be a replacement when considering the size and cost compared constant dc-link inverters. Furthermore, leakage currents are expected to be lower in pseudo-dc-link inverters due to the low-frequency unfolding circuit. The pulsating dc-link inverter shows almost the same operating features as the constant dc-link inverter but no additional dc part control signal is needed. The integrated dc-link inverters show higher requirements for the semiconductor devices and control process. Meanwhile, the injected dc currents are hard to eliminate. The pseudo-dc-link inverter and pulsating dc-link inverter on the other hand can be alternatives for conventional constant dc-link inverters in most applications but the special features of these inverters should be considered carefully. The integrated dc-link inverters are especially suitable for low power applications. Based on the presented classification of the different dc-link inverters, the selection or modification of certain kinds of PV inverters for special applications can be more straightforward.

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