Critical Percolation Exploration Path and $SLE_6$: a Proof of Convergence

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Abstract

It was argued by Schramm and Smirnov that the critical site percolation exploration path on the triangular lattice converges in distribution to the trace of chordal $SLE_6$. We provide here a detailed proof, which relies on Smirnov’s theorem that crossing probabilities have a conformally invariant scaling limit (given by Cardy’s formula). The version of convergence to $SLE_6$ that we prove suffices for the Smirnov-Werner derivation of certain critical percolation crossing exponents and for our analysis of the critical percolation full scaling limit as a process of continuum nonsimple loops.

Keywords: continuum scaling limit, percolation, SLE, critical behavior, triangular lattice, conformal invariance.

AMS 2000 Subject Classification: 82B27, 60K35, 82B43, 60D05, 30C35.

1 Synopsis

The purpose of this paper is to present a detailed, self-contained proof of the convergence of the critical site percolation exploration path (on the triangular lattice) to the trace of chordal $SLE_6$ for Jordan domains. We will prove convergence in a strong sense: in the topology induced by the uniform metric on continuous curves (modulo monotonic reparametrization), and “locally uniformly” in the “shape” of the domain and the starting and ending points of the curve.

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The main technical difficulty (in the approach followed here) appears in a rather surprising way — to obtain a Markov property for any scaling limit of the percolation exploration path. The surprise is that an even stronger Markov property trivially holds for the exploration path itself. To show that an analogous property holds in the scaling limit (see Theorem 3 and Remark 7.1) is largely responsible for the length of the paper. Roughly, the difficulty is that in the scaling limit the exploration path touches itself and the boundary of the domain (infinitely many times). The touching of the domain boundary in particular requires a lengthy analysis (see Lemmas 7.1-7.4) since the standard percolation bound on multiple crossings of a “semi-annulus” only applies to the case of a “flat” boundary (see [32] and Appendix A of [21]). This issue is resolved here by using the continuity of Cardy’s formula with respect to changes in the domain. We remark that the results and methods developed here about touching of domain boundaries have other applications — e.g., to the existence and conformal invariance of the full scaling limit in general (non-flat) domains; these extensions of the results of [8, 9] will be discussed elsewhere [10].

The proof has two parts: a characterization for \( SLE_6 \) curves (Theorem 2), which is similar to Schramm’s argument identifying \( SLE_\kappa \) but only uses conformal invariance of hulls at special stopping times, and a series of results showing that any subsequential scaling limit of the exploration path satisfies the hypotheses of Theorem 2.

The theorem of Smirnov (Theorem 1 here) about convergence to Cardy’s formula [31] is a key tool throughout. It is used in the proof of Theorem 2 which follows roughly Smirnov’s sketch in [31,32] (but with one significant difference — see Remarks 5.2 and 5.3), and is also crucial, in its strengthened version, Theorem 3, in proving that the “filling” of the exploration path converges to a hull process having the Markov property necessary to apply Theorem 2. As mentioned, this step, implicitly assumed in Smirnov’s sketch [31, 32], turns out to be the most technically difficult one. Despite its length, we believe that a detailed proof is needed, since the result, beside its own interest, has important applications — notably the rigorous derivation of certain critical exponents [34], of Watt’s crossing formula [14] and Schramm’s percolation formula [28], and the derivation of the full scaling limit [8,9]. We note that Smirnov has recently sketched in [33] a proof different from that of [31,32].

2 Introduction

The percolation exploration path was introduced by Schramm in 1999 in a seminal paper [27] where it was used to give a precise formulation (beyond crossing probabilities) to the conjecture that the scaling limit of two-dimensional critical percolation is conformally invariant. Schramm’s formulation of the conjecture involves his Stochastic Loewner Evolution or Schramm-Loewner Evolution \( (SLE_\kappa) \), and can be expressed, roughly speaking, by saying that the percolation exploration path converges in distribution to \( SLE_6 \).

A simple and elegant argument, due again to Schramm, shows that if the scaling limit of the percolation exploration path exists and is conformally invariant, then it must
necessarily be an $SLE_\kappa$ curve; the value $\kappa = 6$ can be determined by looking at crossing probabilities, since $SLE_6$ is the only $SLE_\kappa$ that satisfies Cardy’s formula [12].

Shortly after Schramm’s paper appeared, Smirnov published a proof [31], for site percolation on the triangular lattice, of the conformal invariance of the scaling limit of crossing probabilities, opening the way to a complete proof of Schramm’s conjecture. In [31] (see also [32]) Smirnov also outlined a possible strategy for using the conformal invariance of crossing probabilities to prove Schramm’s conjecture. Roughly at the same time, convergence of the exploration path to $SLE_6$ was used by Smirnov and Werner [34] and by Lawler, Schramm and Werner [21] as a key step in a derivation of the values of various percolation critical exponents, most of which had been previously predicted in the physics literature (see the references in [34]). Later, it was used by the authors of this paper to obtain the full scaling limit of two-dimensional critical percolation (see [7, 8]).

However, a detailed proof of the convergence of the exploration path to $SLE_6$ did not appear until 2005, in an appendix of [8], where we followed a modified version of Smirnov’s strategy. The purpose of the present paper is to present essentially that proof in a self-contained form. (We note that Lemma A.3 in [8], whose proof had an error, has been replaced by Lemma 7.2 here.) Our proof roughly follows Smirnov’s outline of [31,32], based on the convergence to Cardy’s formula [31, 32] and on Markov properties (see Theorem 2 below and the discussion preceding it). But there are two significant modifications, which we found necessary for a proof. The first is to use a different sequence of stopping times, which results in a different geometry for the Markov chain approximation to $SLE_6$ (see Remark 5.3). The second is that “close encounters” by the exploration path to the domain boundary are not handled by general results for “three-arm” events at the boundary of a half-plane, but rather by a more complex argument based partly on continuity of crossing probabilities with respect to domain boundaries (see Lemmas 7.1-7.4).

We note (see Remark 5.2 below for more discussion) that our choice of stopping times is closer in spirit than is the choice in [31, 32] to the proofs of convergence of the loop erased random walk to $SLE_2$ [22] and of the harmonic explorer to $SLE_4$ [29]. It may also be applicable to other systems in which an $SLE_\kappa$ limit is expected, provided that sufficient information can be obtained about conformal invariance of the scaling limit of the analogues of exploration hitting distributions in those systems.

Schramm’s conjecture, as stated in Smirnov’s paper [31], concerns the convergence in distribution of the percolation exploration path to the trace of chordal $SLE_6$ in a fairly arbitrary fixed domain. Here (see Theorem 5) we will prove a version of convergence which is slightly stronger but somewhat less general: we will show that the distribution of the percolation exploration path converges to that of the trace of chordal $SLE_6$ “locally uniformly” in the “shape” of the domain and in the positions of the starting and ending points of the path, but we will restrict attention to Jordan domains (i.e., domains whose boundary is a simple closed curve). Our main motivation in this specific formulation is to provide the key tool needed in [9] to prove that the set of all critical percolation interfaces converges (in distribution) in the scaling limit to a certain countable collection of continuous, nonsimple, noncrossing, fractal loops in the plane. Our formulation of convergence to $SLE_6$ is also sufficient for a key step in the proof of certain critical exponents [34] –
namely for \( j(\geq 1) \) crossings of a semi-annulus and for \( j(\geq 2) \) crossings, not all of the same color, of an annulus. It does not appear to be sufficient, without at least also using some of [9], for the derivation in [21] of the “one-arm” exponent (i.e., for one crossing of an annulus) and thus not sufficient for proofs of other exponents based on the one-arm exponent (see [16] and Sect. 1 of [34]).

In the next section, we give some preliminary definitions. In Sect. 4 we define the percolation exploration path. In Sect. 5 we introduce Cardy’s formula, give a characterization result for \( SLE_6 \), and state an extended version of Smirnov’s result on the scaling limit of crossing probabilities. Sect. 6 contains results concerning the “envelope” of the hull of exploration paths and \( SLE_6 \) paths. Those results are needed in Sect. 7, which is devoted to the proof of the main convergence result (see Theorem 5). The paper ends with an appendix about sequences of conformal maps.

3 Preliminary Definitions

We identify the real plane \( \mathbb{R}^2 \) and the complex plane \( \mathbb{C} \) and use the open half-plane \( \mathbb{H} = \{ x + iy : y > 0 \} \) (and its closure \( \overline{\mathbb{H}} \)). \( \mathbb{D} \) denotes the open unit disc \( \mathbb{D} = \{ z \in \mathbb{C} : |z| < 1 \} \). A domain \( D \) of the complex plane \( \mathbb{C} \) is a nonempty, connected, open subset of \( \mathbb{C} \); a simply connected domain \( D \) is said to be Jordan if its (topological) boundary \( \partial D \) is a Jordan curve (i.e., a simple continuous loop).

We often use Riemann’s mapping theorem — that if \( D \) is any simply connected domain other than the entire plane \( \mathbb{C} \) and \( z_0 \in D \), then there is a unique conformal map \( \phi \) of \( \mathbb{D} \) onto \( D \) such that \( \phi(0) = z_0 \) and \( \phi'(0) > 0 \).

When taking the scaling limit \( \delta \to 0 \) one can focus on fixed bounded regions, \( \Lambda \subset \mathbb{R}^2 \), or consider the whole \( \mathbb{R}^2 \) at once. The second option avoids dealing with boundary conditions, but requires an appropriate choice of metric. A convenient way of dealing with the whole \( \mathbb{R}^2 \) is to replace the Euclidean metric with a distance function

\[
\Delta(u, v) = \inf_h \int (1 + |h|^2)^{-1} ds,
\]

where the infimum is over all smooth curves \( h(s) \) joining \( u \) with \( v \), parametrized by arclength \( s \), and where \( |\cdot| \) denotes the Euclidean norm. This metric is equivalent to the Euclidean metric in bounded regions, but it has the advantage of making \( \mathbb{R}^2 \) precompact. Adding a single point at infinity yields the compact space \( \hat{\mathbb{R}}^2 \) which is isometric, via stereographic projection, to the two-dimensional sphere.

3.1 The Space of Curves

In dealing with the scaling limit we use the approach of Aizenman-Burchard [2]. Denote by \( \mathcal{S}_\Lambda \) the complete separable metric space of continuous curves in a closed (bounded) subset \( \Lambda \subset \mathbb{R}^2 \) with the metric \( (2) \) defined below. Curves are regarded as equivalence classes of continuous functions from the unit interval to \( \mathbb{R}^2 \), modulo monotonic reparametrizations.
\(\gamma\) will represent a particular curve and \(\gamma(t)\) a parametrization of \(\gamma\); \(\mathcal{F}\) will represent a set of curves (more precisely, a closed subset of \(\mathcal{S}_\Lambda\)). We define a metric on curves by

\[
d(\gamma_1, \gamma_2) \equiv \inf_{t \in [0,1]} \sup |\gamma_1(t) - \gamma_2(t)|,
\]

where the infimum is over parametrizations of \(\gamma_1\) and \(\gamma_2\). The distance between two closed sets of curves is defined by the induced Hausdorff metric:

\[
\text{dist}(\mathcal{F}, \mathcal{F}') \leq \varepsilon \Leftrightarrow \forall \gamma \in \mathcal{F}, \exists \gamma' \in \mathcal{F}' \text{ with } d(\gamma, \gamma') \leq \varepsilon, \text{ and vice versa.} \tag{3}
\]

The space \(\Omega_\Lambda\) of closed subsets of \(\mathcal{S}_\Lambda\) (i.e., collections of curves in \(\Lambda\)) with the metric (3) is also a complete separable metric space. We denote by \(\mathcal{B}_\Lambda\) its Borel \(\sigma\)-algebra. For each \(\delta > 0\), the random curves we consider are polygonal paths on the edges of the hexagonal lattice \(\delta \mathcal{H}\), dual to the triangular lattice \(\delta \mathcal{T}\). A superscript \(\delta\) indicates that the curves correspond to a model with a “short distance cutoff” of magnitude \(\delta\). We also consider the complete separable metric space \(\mathcal{S}\) of continuous curves in \(\mathbb{R}^2\) with distance

\[
D(\gamma_1, \gamma_2) \equiv \inf_{t \in [0,1]} \sup |\Delta(\gamma_1(t), \gamma_2(t))|, \tag{4}
\]

where the infimum is again over parametrizations of \(\gamma_1\) and \(\gamma_2\). The distance between two closed sets of curves is again defined by the induced Hausdorff metric:

\[
\text{Dist}(\mathcal{F}, \mathcal{F}') \leq \varepsilon \Leftrightarrow \forall \gamma \in \mathcal{F}, \exists \gamma' \in \mathcal{F}' \text{ with } D(\gamma, \gamma') \leq \varepsilon, \text{ and vice versa.} \tag{5}
\]

The space \(\Omega\) of closed sets of \(\mathcal{S}\) (i.e., collections of curves in \(\mathbb{R}^2\)) with the metric (5) is also a complete separable metric space. We denote by \(\mathcal{B}\) its Borel \(\sigma\)-algebra. When we talk about convergence in distribution of random curves, we refer to the uniform metric (2), while for closed collections of curves, we refer to the metric (3) or (5).

**Remark 3.1.** In [7, 9], the space \(\Omega\) of closed sets of \(\mathcal{S}\) was used for collections of exploration paths and cluster boundary loops and their scaling limits, \(\text{SLE}_6\) paths and continuum nonsimple loops. Here, in the statements and proofs of Lemmas 7.1, 7.3 and 7.4, we apply \(\Omega\) in essentially the original setting of Aizenman and Burchard [1, 2], i.e., for collections of blue and yellow simple \(\mathcal{T}\)-paths (see Sect. 7) and their scaling limits. The slight modification needed to keep track of the colors is easily managed.

### 3.2 Chordal \(\text{SLE}_\kappa\)

The Stochastic Loewner Evolution (\(\text{SLE}_\kappa\)) was introduced by Schramm [27] to study two-dimensional probabilistic lattice models whose scaling limits are expected to be conformally invariant. Here we describe the chordal version of \(\text{SLE}_\kappa\); for more, see [27] as well as the fine reviews by Lawler [18], Kager and Nienhuis [15], and Werner [37], and Lawler’s book [19].

Let \(\mathbb{H}\) denote the upper half-plane. For all \(\kappa \geq 0\), chordal \(\text{SLE}_\kappa\) in \(\mathbb{H}\) is a certain random family \((K_t, t \geq 0)\) of bounded subsets of \(\overline{\mathbb{H}}\) that is generated by a continuous
random curve $\gamma$ (with $\gamma(0) = 0$) in the sense that, for all $t \geq 0$, $\mathbb{H}_t \equiv \mathbb{H} \setminus K_t$ is the unbounded connected component of $\mathbb{H} \setminus \gamma[0, t]$; $\gamma$ is called the trace of chordal $SLE_{\kappa}$.

Let $D \subset \mathbb{C}$ ($D \neq \mathbb{C}$) be a simply connected domain whose boundary is a continuous curve. Given two distinct points $a, b \in \partial D$ (or more accurately, two distinct prime ends), there exists a conformal map $f$ from $\mathbb{H}$ onto $D$ such that $f(0) = a$ and $f(\infty) = \lim_{|z| \to \infty} f(z) = b$. The choice of $a$ and $b$ only characterizes $f(\cdot)$ up to a scaling factor $\lambda > 0$, since $f(\lambda \cdot)$ would also do.

Suppose that $(K_t, t \geq 0)$ is a chordal $SLE_{\kappa}$ in $\mathbb{H}$; chordal $SLE_{\kappa}$ $(\tilde{K}_t, t \geq 0)$ in $D$ from $a$ to $b$ as the image of $(K_t, t \geq 0)$ under $f$. The law of $(\tilde{K}_t, t \geq 0)$ is unchanged, up to a linear time-change, if we replace $f(\cdot)$ by $f(\lambda \cdot)$. One considers $(\tilde{K}_t, t \geq 0)$ as a process from $a$ to $b$ in $D$, ignoring the role of $f$.

In the case $\kappa = 6$, $(K_t, t \geq 0)$ is generated by a continuous nonsimple curve $\gamma$ with Hausdorff dimension $7/4$. We will denote by $\gamma_{D,a,b}$ the image of $\gamma$ under $f$ and call it the trace of chordal $SLE_{\kappa}$ in $D$ from $a$ to $b$; $\gamma_{D,a,b}$ is a continuous nonsimple curve inside $\overline{D}$ from $a$ to $b$, and it can be given a parametrization $\gamma_{D,a,b}(t)$ such that $\gamma_{D,a,b}(0) = a$ and $\gamma_{D,a,b}(1) = b$, so that we are in the metric framework described in Section 3.1.

## 4 Lattices and Paths

We will denote by $\mathcal{T}$ the two-dimensional triangular lattice, whose sites we think of as the elementary cells of a regular hexagonal lattice $\mathcal{H}$ embedded in the plane as in Figure 1. We say that two hexagons are neighbors (or that they are adjacent) if they have a common edge. A sequence $(\xi_0, \ldots, \xi_n)$ of hexagons of $\mathcal{H}$ such that $\xi_{i-1}$ and $\xi_i$ are neighbors for all $i = 1, \ldots, n$ and $\xi_i \neq \xi_j$ whenever $i \neq j$ will be called a $\mathcal{T}$-path and denoted by $\pi$. If the first and last hexagons of the path are neighbors, the path will be called a $\mathcal{T}$-loop.

A set $D$ of hexagons is connected if any two hexagons in $D$ can be joined by a $\mathcal{T}$-path contained in $D$. We say that a finite set $D$ of hexagons is simply connected if both $D$ and $\mathcal{T} \setminus D$ are connected. For a simply connected set $D$ of hexagons, we denote by $\Delta D$ its external site boundary, or $s$-boundary (i.e., the set of hexagons that do not belong to $D$ but are adjacent to hexagons in $D$), and by $\partial D$ the topological boundary of $D$ when $D$ is considered as a domain of $\mathbb{C}$. We will call a bounded, simply connected subset $D$ of $\mathcal{T}$ a Jordan set if its $s$-boundary $\Delta D$ is a $\mathcal{T}$-loop.

For a Jordan set $D \subset \mathcal{T}$, a vertex $x \in \mathcal{H}$ that belongs to $\partial D$ can be either of two types, according to whether the edge incident on $x$ that is not in $\partial D$ belongs to a hexagon in $D$ or not. We call a vertex of the second type an exposed vertex (e for “external” or “exposed”).

Given a Jordan set $D$ and two e-vertices $x, y$ in $\partial D$, we denote by $\partial_{x,y} D$ the portion of $\partial D$ traversed counterclockwise from $x$ to $y$, and call it the right boundary; the remaining part of the boundary is denote by $\partial_{y,x} D$ and is called the left boundary. Analogously, the portion of $\Delta_{x,y} D$ of $\Delta D$ whose hexagons are adjacent to $\partial_{x,y} D$ is called the right $s$-boundary and the remaining part the left $s$-boundary.

A percolation configuration $\sigma = \{\sigma(\xi)\}_{\xi \in \mathcal{T}} \in \{-1, +1\}^\mathcal{T}$ on $\mathcal{T}$ is an assignment of $-1$ (equivalently, yellow) or $+1$ (blue) to each site of $\mathcal{T}$. For a domain $D$ of the
plane, the restriction to $D \cap \mathcal{T}$ of $\sigma$ is denoted by $\sigma_D$. On the space of configurations $\Sigma = \{-1, +1\}^T$, we consider the usual product topology and denote by $\mathbb{P}$ the uniform measure, corresponding to Bernoulli percolation with equal density of yellow (minus) and blue (plus) hexagons, which is critical percolation in the case of the triangular lattice.

A (percolation) cluster is a maximal, connected, monochromatic subset of $\mathcal{T}$; we will distinguish between blue (plus) and yellow (minus) clusters. The boundary of a cluster $D$ is the set of edges of $\mathcal{H}$ that surround the cluster (i.e., its Peierls contour); it coincides with the topological boundary of $D$ considered as a domain of $\mathbb{C}$. The set of all boundaries is a collection of “nested” simple loops along the edges of $\mathcal{H}$.

Given a percolation configuration $\sigma$, we associate an arrow to each edge of $\mathcal{H}$ belonging to the boundary of a cluster in such a way that the hexagon to the right of the edge with respect to the direction of the arrow is blue (plus). The set of all boundaries then becomes a collection of nested, oriented, simple loops. A boundary path (or b-path) $\gamma$ is a sequence $(e_0, \ldots, e_n)$ of distinct edges of $\mathcal{H}$ belonging to the boundary of a cluster and such that $e_{i-1}$ and $e_i$ meet at a vertex of $\mathcal{H}$ for all $i = 1, \ldots, n$. To each b-path, we can associate a direction according to the direction of the edges in the path.

Given a b-path $\gamma$, we denote by $\Gamma_B(\gamma)$ (respectively, $\Gamma_Y(\gamma)$) the set of blue (resp., yellow) hexagons (i.e., sites of $\mathcal{T}$) adjacent to $\gamma$; we also let $\Gamma(\gamma) \equiv \Gamma_B(\gamma) \cup \Gamma_Y(\gamma)$.

4.1 The Percolation Exploration Process and Path

For a Jordan set $D \subset \mathcal{T}$ and two e-vertices $x, y$ in $\partial D$, imagine coloring blue all the hexagons in $\Delta_{x,y}D$ and yellow all those in $\Delta_{y,x}D$. Then, for any percolation configuration $\sigma_D$ inside $D$, there is a unique b-path $\gamma$ from $x$ to $y$ which separates the blue cluster adjacent to $\Delta_{x,y}D$ from the yellow cluster adjacent to $\Delta_{y,x}D$. We call $\gamma = \gamma_{D,x,y}^1(\sigma_D)$ a percolation exploration path (see Figure 1) in $D$ from $x$ to $y$ with mesh size $\delta = 1$.

Notice that the exploration path $\gamma$ only depends on the percolation configuration $\sigma_D$ inside $D$ and the positions of the e-vertices $x$ and $y$; in particular, it does not depend on the color of the hexagons in $\Delta D$, since it is defined by imposing fictitious boundary conditions on $\Delta D$. To see this more clearly, we next show how to construct the percolation exploration path dynamically, via the percolation exploration process defined below.

Given a Jordan set $D \subset \mathcal{T}$ and two e-vertices $x, y$ in $\partial D$, assign to $\partial_{x,y}D$ a counterclockwise orientation (i.e., from $x$ to $y$) and to $\partial_{y,x}D$ a clockwise orientation. The edge $e_x$ incident on $x$ that does not belong to $\partial D$ is oriented in the direction of $x$. From there one starts an exploration procedure that produces an oriented path inside $D$ along the edges of $\mathcal{H}$, together with two nonsimple monochromatic paths on $\mathcal{T}$, as follows. At each step there are two possible edges (left or right edge with respect to the current direction of exploration) to choose from, both belonging to the same hexagon $\xi$ contained in $D$ or $\Delta D$. If $\xi$ belongs to $D$ and has not been previously “explored,” its color is determined by flipping a fair coin and then the edge to the left (with respect to the direction in which the exploration is moving) is chosen if $\xi$ is blue (plus), or the edge to the right is chosen if $\xi$ is yellow (minus). If $\xi$ belongs to $D$ and has been previously explored, the color already assigned to it is used to choose an edge according to the rule above. If $\xi$ belongs to the
right external boundary $\Delta_{x,y}D$, the left edge is chosen. If $\xi$ belongs to the left external boundary $\Delta_{y,x}D$, the right edge is chosen. The exploration stops when it reaches $y$. 

Figure 1: Percolation exploration process in a portion of the hexagonal lattice with blue/yellow boundary conditions on the first column, corresponding to the boundary of the region where the exploration is carried out. The colored hexagons that do not belong to the first column have been “explored” during the exploration process. The heavy line between yellow (light) and blue (dark) hexagons is the exploration path produced by the exploration process.

Next, we introduce a class of domains of the plane which will appear later in Theorems 3 and 4 and various lemmas. Let $D$ be a bounded simply connected domain whose boundary $\partial D$ is a continuous curve. Let $\phi : \mathbb{D} \to D$ be the (unique) conformal map from the unit disc $\mathbb{D}$ to $D$ with $\phi(0) = z_0 \in D$ and $\phi'(0) > 0$; note that by Theorem 6 of Appendix A, $\phi$ has a continuous extension to $D$. Let $a, c, d$ be three points of $\partial D$ (or more accurately, three prime ends) in counterclockwise order — i.e., such that $a = \phi(a^*), c = \phi(c^*)$ and $d = \phi(d^*)$, with $a^*, c^*$ and $d^*$ three distinct points of $\partial \mathbb{D}$ in counterclockwise order. We will call $D$ admissible with respect to $(a, c, d)$ if the counterclockwise arcs $J_1 \equiv da$, $J_2 \equiv ac$ and $J_3 \equiv cd$ are simple curves, $J_3$ does not touch the interior of either $J_1$ or $J_2$, and from each point in $J_3$ there is a path to infinity that does not cross $\partial D$. (Note that a Jordan $D$ is admissible for any counterclockwise $a, c, d$ on $\partial D$.)

Notice that, according to our definition, the interiors of the arcs $J_1$ and $J_2$ can touch. If that happens, the double-points of the boundary (belonging to both arcs) are counted twice and considered as two distinct points (and are two different prime ends). The significance of the notion of admissible is that certain domains arising naturally in the proof of Theorem 4 are not Jordan but are admissible; this is because the hulls $K_t$ generated by chordal $SLE_6$ paths have cut-points [4] — see Figure 5.

With $D, J_1, J_2, J_3$ as just discussed, let now $\{D^\delta\}$ be a sequence of Jordan sets in $\delta \mathcal{T}$ (i.e., composed of the hexagons of the scaled hexagonal lattices $\delta \mathcal{H}$). If we can split $\partial D^\delta$ into three Jordan arcs, $J_1^\delta, J_2^\delta, J_3^\delta$, such that $d(J_i^\delta, J_i) \to 0$ for each $i = 1, 2, 3$ as $\delta \to 0$, we say that $\partial D^\delta$ converges to $\partial D$ as $\delta \to 0$ and write $\partial D^\delta \to \partial D$ or, equivalently, $D^\delta \to D$. 

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Let $a^\delta$ and $b^\delta$ be distinct $\epsilon$-vertices of $\partial D^\delta$ and let $\gamma$ be the exploration path in $D^\delta$ from $a^\delta$ to $b^\delta$. If, as $\delta \to 0$, $\partial D^\delta \to \partial D$, $a^\delta \to a$ and $b^\delta \to b$, where $D$ is a domain admissible with respect to $(a,c,d)$ and $b \in J_3 = \overline{cd}$, we say that $(D^\delta, a^\delta, b^\delta)$ is a $\delta$-approximation to $(D, a, b)$, write $(D^\delta, a^\delta, b^\delta) \to (D, a, b)$, and denote the exploration path $\gamma$ by $\gamma^\delta_{D,a,b}$. Note that $\gamma^\delta_{D,a,b}$ depends not only on $(D, a, b)$, but also on the $\delta$-approximation to $(D, a, b)$. For simplicity of notation, we do not make explicit this dependence.

For a fixed $\delta > 0$, the probability measure $\mathbb{P}$ on percolation configurations induces a probability measure $\mu^\delta_{D,a,b}$ on exploration paths $\gamma^\delta_{D,a,b}$. In the continuum scaling limit, $\delta \to 0$, one is interested in the weak convergence with respect to the uniform metric (2) of $\mu^\delta_{D,a,b}$ to a probability measure $\mu_{D,a,b}$ supported on continuous curves.

Before concluding this section, we give some more definitions. Consider the exploration path $\gamma = \gamma^\delta_{D,a,b}$ and the set $\Gamma(\gamma) = \Gamma_Y(\gamma) \cup \Gamma_B(\gamma)$. The set $D \setminus \Gamma(\gamma)$ is the union of its connected components (in the lattice sense), which are simply connected. For $\delta$ small and $a, b \in \partial D$ not too close to each other, with high probability the exploration process inside $D^\delta$ will make large excursions into $D^\delta$, so that $D^\delta \setminus \Gamma(\gamma)$ will have more than one component. Given a point $z \in \mathbb{C}$ contained in $D^\delta \setminus \Gamma(\gamma)$, we will denote by $D^\delta_{a,b}(z)$ the domain corresponding to the unique element of $D^\delta \setminus \Gamma(\gamma)$ that contains $z$ (notice that for a deterministic $z \in D$, $D^\delta_{a,b}(z)$ is well defined with high probability for $\delta$ small, i.e., when $z \in D^\delta$ and $z \notin \Gamma(\gamma)$).

There are four types of domains which may be usefully thought of in terms of their external site boundaries: (1) those components whose site boundary contains both sites in $\Gamma_Y(\gamma)$ and $\Delta^{\delta,a,b}D^\delta$, (2) the analogous components with $\Delta^{b,a,b}D^\delta$ replaced by $\Delta^{a,b,a}D^\delta$ and $\Gamma_Y(\gamma)$ by $\Gamma_B(\gamma)$, (3) those components whose site boundary only contains sites in $\Gamma_Y(\gamma)$, and finally (4) the analogous components with $\Gamma_Y(\gamma)$ replaced by $\Gamma_B(\gamma)$. These different types will appear in the proof of Lemma 6.2.

5 Cardy’s Formula and a Characterization of $SLE_6$

The existence of subsequential limits for the percolation exploration path, which follows from the work of Aizenman and Burchard [2], means that the proof of convergence to $SLE_6$ can be divided into two parts: first we will give a characterization of chordal $SLE_6$ in terms of two properties that determine it uniquely; then we will show that any subsequential scaling limit of the percolation exploration path satisfies these two properties.

The characterization part will follow from known properties of hulls and of $SLE_6$ (see [23] and [36]). The second part will follow from an extension of Smirnov’s result about the convergence of crossing probabilities to Cardy’s formula [12] (see Theorem 3 below) for sequences of Jordan domains $D_k$, with the domain $D_k$ changing together with the mesh $\delta_k$ of the lattice, combined with the proof of a certain spatial Markov property for subsequential limits of percolation exploration hulls (Theorem 4). We note that although Theorem 3 represents only a slight extension to Smirnov’s result on convergence of crossing probabilities, this extension and its proof play a major role in the technically important Lemmas 7.1, 7.3 and 7.4 which control the “close encounters” of exploration
paths to domain boundaries. The proof of Theorem 3 is modelled after a simpler geometric argument involving only rectangles used in [11].

Let $D$ be a bounded simply connected domain containing the origin whose boundary $\partial D$ is a continuous curve. Let $\phi : \mathbb{D} \to D$ be the (unique) conformal map from the unit disc to $D$ with $\phi(0) = 0$ and $\phi'(0) > 0$; note that by Theorem 6 of Appendix A, $\phi$ has a continuous extension to $\mathbb{D}$. Let $z_1, z_2, z_3, z_4$ be four points of $\partial D$ in counterclockwise order – i.e., such that $z_j = \phi(w_j), \ j = 1, 2, 3, 4$, with $w_1, \ldots, w_4$ in counterclockwise order. Also, let $\eta = \frac{(w_1-w_2)(w_3-w_4)}{(w_1-w_3)(w_2-w_4)}$. Cardy’s formula [12] for the probability $\Phi_D(z_1, z_2; z_3, z_4)$ of a “crossing” in $D$ from the counterclockwise arc $z_1 z_2$ to the counterclockwise arc $z_3 z_4$ is

$$\Phi_D(z_1, z_2; z_3, z_4) = \frac{\Gamma(2/3)}{\Gamma(4/3)\Gamma(1/3)} \eta^{1/3} \text{hypergeo}(1/3, 2/3, 4/3; \eta),$$

where $\text{hypergeo}(\cdot)$ is a hypergeometric function.

For a given mesh $\delta > 0$, the probability of a blue crossing inside $D$ from the counterclockwise arc $z_1 z_2$ to the counterclockwise arc $z_3 z_4$ is the probability of the existence of a blue $\mathcal{T}$-path $(\xi_0, \ldots, \xi_n)$ such that $\xi_0$ intersects the counterclockwise arc $z_1 z_2$, $\xi_n$ intersects the counterclockwise arc $z_3 z_4$ and $\xi_1, \ldots, \xi_n-1$ are all contained in $D$. Smirnov proved the following major theorem, concerning the conjectured behavior [12] of crossing probabilities in the scaling limit (see also [5]).

**Theorem 1.** (Smirnov [31]) Let $D$ be a Jordan domain whose boundary $\partial D$ is a finite union of smooth (e.g., $C^2$) curves. As $\delta \to 0$, the limit of the probability of a blue crossing inside $D$ from the counterclockwise arc $z_1 z_2$ to the counterclockwise arc $z_3 z_4$ exists, is a conformal invariant of $(D, z_1, z_2, z_3, z_4)$ and is given by Cardy’s formula (6).

**Remark 5.1.** We have stated Smirnov’s result in the form that will be used in this paper, but note that Smirnov does not restrict attention to Jordan domains with piecewise smooth boundary but rather allows for more general bounded domains (see [31, 32]). We also remark that Theorem 3 below extends Theorem 1 to a larger class of domains, including in particular all Jordan domains.

Let us now specify the objects that we are interested in. Suppose $D$ is a simply connected domain whose boundary $\partial D$ is a continuous curve, and $a, b$ are two distinct points in $\partial D$ (or more accurately, two distinct prime ends), and let $\tilde{\mu}_{D,a,b}$ be a probability measure on continuous curves $\tilde{\gamma} = \tilde{\gamma}_{D,a,b} : [0, \infty) \to \overline{D}$ with $\tilde{\gamma}(0) = a$, $\tilde{\gamma}(\infty) \equiv \lim_{t \to \infty} \tilde{\gamma}(t) = b$, and $\tilde{\gamma}(t) \neq b$ for $t$ finite (we remark that the use of $[0, \infty)$ instead of $[0, 1]$ for the time parametrization is purely for convenience). Let $D_t \equiv D \setminus \overline{K_t}$ denote the (unique) connected component of $D \setminus \overline{\tilde{\gamma}[0, t]}$ whose closure contains $b$, where $K_t$, the filling of $\overline{\tilde{\gamma}[0, t]}$, is a closed connected subset of $\overline{D}$. $K_t$ is called a hull if it satisfies the condition

$$\overline{K_t} \cap D = \overline{K_t}.$$  

We will consider curves $\tilde{\gamma}$ such that (i) $\tilde{\gamma}$ is the limit (in distribution using the metric (2)) of random simple curves and such that, for $0 < t_1 < t_2$ with $\tilde{\gamma}(t_1) \neq \tilde{\gamma}(t_2)$, (ii) $\tilde{\gamma}(t_2) \notin \overline{\tilde{\gamma}[0, t_1]}$.
\( \tilde{K}_{t_1} \setminus \partial \tilde{K}_{t_1} \) and (iii) \( \exists t' \in (t_1, t_2) \) with \( \tilde{\gamma}(t') \in D_{t_1} \equiv D \setminus \tilde{K}_{t_1} \). We note that an example of a curve satisfying these properties is the trace of chordal SLE_6.

Let \( C' \subset D \) be a closed subset of \( \overline{D} \) such that \( a \notin C' \), \( b \in C' \), and \( D' = D \setminus C' \) is a bounded simply connected domain whose boundary is a continuous curve containing the counterclockwise arc \( \overline{cd} \) that does not belong to \( \partial D \) (except for its endpoints \( c \) and \( d \) – see Figure 2). Let \( T' = \inf \{ t : \tilde{K}_t \cap C' \neq \emptyset \} \) be the first time that \( \tilde{\gamma}(t) \) hits \( C' \). We say that the hitting distribution of \( \tilde{\gamma}(t) \) at the stopping time \( T' \) is determined by Cardy’s formula if, for any \( C'' \) and any counterclockwise arc \( \overline{xy} \) of \( \overline{cd} \), the probability that \( \tilde{\gamma} \) hits \( C'' \) at time \( T' \) on \( \overline{xy} \) is given by

\[
\mathbb{P}^*(\tilde{\gamma}(T') \in \overline{xy}) = \Phi_{D'}(a, c; x, d) - \Phi_{D'}(a, c; y, d).
\]  

Assume that the filling \( \tilde{K}_{T'} \) of \( \tilde{\gamma}[0, T'] \) is a hull; we denote by \( \tilde{\nu}_{D', a, c, d} \) the distribution of \( \tilde{K}_{T'} \). To explain what we mean by the distribution of a hull, consider the set \( \tilde{A} \) of closed subsets \( \tilde{A} \) of \( \overline{D'} \) that do not contain \( a \) and such that \( \partial \tilde{A} \setminus \partial D' \) is a simple (continuous) curve contained in \( D' \) except for its endpoints, one of which is on \( \partial D' \cap \tilde{D} \) and the other is on \( \partial D \) (see Figure 3). Let \( \mathcal{A} \) be the set of closed subsets of \( \overline{D'} \) of the form \( \tilde{A}_1 \cup \tilde{A}_2 \), where \( \tilde{A}_1, \tilde{A}_2 \in \tilde{A} \) and \( \tilde{A}_1 \cap \tilde{A}_2 = \emptyset \).

Figure 2: \( D \) is the upper half-plane \( \mathbb{H} \) with the shaded portion removed, \( b = \infty \), \( C' \) is an unbounded subdomain, and \( D' = D \setminus C' \) is indicated in the figure. The counterclockwise arc \( \overline{cd} \) indicated in the figure belongs to \( \partial D' \).

Figure 3: Example of a hull \( K \) and a set \( \tilde{A}_1 \cup \tilde{A}_2 \) in \( \mathcal{A} \). Here, \( D = \mathbb{H} \) and \( D' \) is the semi-disc centered at \( a \).
For a given $C'$ and corresponding $T'$, let $\mathcal{K}$ be the set whose elements are possible hulls at time $T'$; we claim that the events $\{K \in \mathcal{K} : K \cap A = \emptyset\}$, for $A \in \mathcal{A}$, form a $\pi$-system $\Pi$ (i.e., they are closed under finite intersections; we also include the empty set in $\Pi$), and we consider the $\sigma$-algebra $\Sigma = \sigma(\Pi)$ generated by these events. To see that $\Pi$ is closed under pairwise intersections, notice that, if $A_1, A_2 \in \mathcal{A}$, then $\{K \in \mathcal{K} : K \cap A_1 = \emptyset\} \cap \{K \in \mathcal{K} : K \cap A_2 = \emptyset\} = \{K \in \mathcal{K} : K \cap \{A_1 \cup A_2\} = \emptyset\}$ and $A_1 \cup A_2 \in \mathcal{A}$ (or else $\{K \in \mathcal{K} : K \cap \{A_1 \cup A_2\} = \emptyset\}$ is empty). We are interested in probability spaces of the form $(\mathcal{K}, \Sigma, \mathbb{P}^*)$.

It is easy to see that if the hitting distribution of $\tilde{\gamma}(t)$ is determined by Cardy’s formula, then the probabilities of events in $\Pi$ are also determined by Cardy’s formula in the following way. Let $A \in \mathcal{A}$ be the union of $\tilde{A}_1, \tilde{A}_2 \in \tilde{\mathcal{A}}$, with $\partial \tilde{A}_1 \setminus \partial D'$ given by a curve from $u_1 \in \partial D' \cap D$ to $v_1 \in \partial D$ and $\partial \tilde{A}_2 \setminus \partial D'$ given by a curve from $u_2 \in \partial D' \cap D$ to $v_2 \in \partial D$; then, assuming that $a, v_1, u_1, u_2, v_2$ are ordered counterclockwise around $\partial D'$,

\[ \mathbb{P}^*(\tilde{K}_{T'} \cap A = \emptyset) = \frac{\Phi_{D' \setminus A}(a, v_1; u_1, v_2)}{\Phi_{D' \setminus A}(a, v_1; u_2, v_2)}. \tag{9} \]

Since $\Pi$ is a $\pi$-system, the probabilities of the events in $\Pi$ determine uniquely the distribution of the hull in the sense described above. Therefore, if we let $\gamma_{D,a,b}$ denote the trace of chordal SLE$_6$ inside $D$ from $a$ to $b$, $K_0$ its hull up to time $t$, and $\tau = \inf\{t : K_t \cap C' \neq \emptyset\}$ the first time that $\gamma_{D,a,b}$ hits $C'$, we have the following simple but useful lemma.

Lemma 5.1. With the notation introduced above, if $\tilde{K}_{T'}$ is a hull and the hitting distribution of $\tilde{\gamma}_{D,a,b}$ at the stopping time $T'$ is determined by Cardy’s formula, then $\tilde{K}_{T'}$ is distributed like the hull $K_\tau$ of chordal SLE$_6$.

Proof. It is enough to note that the hitting distribution for chordal SLE$_6$ is determined by Cardy’s formula [20].

Now let $\tilde{f}_0$ be a conformal map from the upper half-plane $\mathbb{H}$ to $D$ such that $\tilde{f}_0^{-1}(a) = 0$ and $\tilde{f}_0^{-1}(b) = \infty$. (Since $\partial D$ is a continuous curve, the map $\tilde{f}_0^{-1}$ has a continuous extension from $D$ to $D \cup \partial D$ – see Theorem 4 of Appendix A – and, by a slight abuse of notation, we do not distinguish between $\tilde{f}_0^{-1}$ and its extension; the same applies to $\tilde{f}_0$.) These two conditions determine $\tilde{f}_0$ only up to a scaling factor. For $\varepsilon > 0$ fixed, let $C(u, \varepsilon) = \{z : |u - z| < \varepsilon\} \cap \mathbb{H}$ denote the semi-ball of radius $\varepsilon$ centered at $u$ on the real line and let $\tilde{T}_1 = \tilde{T}_1(\varepsilon)$ denote the first time $\tilde{\gamma}(t)$ hits $D \setminus \tilde{G}_1$, where $\tilde{G}_1 \equiv \tilde{f}_0(C(0, \varepsilon))$. Define recursively $\tilde{T}_{j+1}$ as the first time $\tilde{\gamma}(\tilde{T}_j, \infty)$ hits $\tilde{D}_{\tilde{T}_j} \setminus \tilde{G}_{j+1}$, where $\tilde{D}_{\tilde{T}_j} \equiv D \setminus \tilde{K}_{\tilde{T}_j}$, $\tilde{G}_{j+1} \equiv \tilde{f}_{\tilde{T}_j}(C(0, \varepsilon))$, and $\tilde{f}_{\tilde{T}_j}$ is a conformal map from $\mathbb{H}$ to $\tilde{D}_{\tilde{T}_j}$ whose inverse maps $\tilde{\gamma}(\tilde{T}_j)$ to $0$ and $b$ to $\infty$. We also define $\tilde{\tau}_{j+1} \equiv \tilde{T}_{j+1} - \tilde{T}_j$, so that $\tilde{T}_j = \tilde{\tau}_1 + \ldots + \tilde{\tau}_j$. We choose $\tilde{f}_{\tilde{T}_j}$ so that its inverse is the composition of the restriction of $\tilde{f}_0^{-1}$ to $\tilde{D}_{\tilde{T}_j}$ with $\tilde{\varphi}_{\tilde{T}_j}$, where $\tilde{\varphi}_{\tilde{T}_j}$ is the unique conformal transformation from $\mathbb{H} \setminus \tilde{f}_0^{-1}(\tilde{K}_{\tilde{T}_j})$ to $\mathbb{H}$ that maps $\infty$ to $\infty$ and $\tilde{f}_0^{-1}(\tilde{\gamma}(\tilde{T}_j))$ to the origin of the real axis, and has derivative at $\infty$ equal to $1$.

Notice that $\tilde{G}_{j+1}$ is a bounded simply connected domain chosen so that the conformal transformation which maps $\tilde{D}_{\tilde{T}_j}$ to $\mathbb{H}$ maps $\tilde{G}_{j+1}$ to the semi-ball $C(0, \varepsilon)$ centered at the
We choose to parametrize \( \hat{\epsilon} \) process \( \tilde{\gamma} \) on the real line. With these definitions, consider the (discrete-time) stochastic process \( \tilde{X}_j \equiv (\tilde{K}_{T_j}, \tilde{\gamma}(T_j)) \) for \( j = 1, 2, \ldots \); we say that \( \tilde{K}_t \) satisfies the \textbf{spatial Markov property} if each \( \tilde{K}_{T_j} \) is a hull and \( \tilde{X}_j \) for \( j = 1, 2, \ldots \) is a Markov chain (for any choice of the map \( \tilde{f}_0 \)). Notice that the hull of chordal SLE\(_6\) satisfies the spatial Markov property, due to the conformal invariance and Markovian properties [27] of SLE\(_6\).

**Remark 5.2.** The next theorem, our main characterization result for SLE\(_6\), uses the choice of stopping times we have just discussed rather than that proposed by Smirnov [31, 32]. A technical reason for this revision of Smirnov’s strategy is discussed in Remark 5.3 below. But a conceptually more important reason is that it naturally gives rise (in the scaling limit) to a certain random walk on the real line (the sequence of points to which the tips of the hulls are conformally mapped at the stopping times) whose increments are i.i.d. random variables. As the stopping time parameter \( \varepsilon \to 0 \), this random walk converges to the driving Brownian motion of the SLE\(_6\).

**Theorem 2.** If the filling process \( \tilde{K}_t \) of \( \hat{\gamma}_{D,a,b} \) satisfies the spatial Markov property and its hitting distribution is determined by Cardy’s formula, then \( \hat{\gamma}_{D,a,b} \) is distributed like the trace \( \gamma_{D,a,b} \) of chordal SLE\(_6\) inside \( D \) started at \( a \) and aimed at \( b \).

**Proof.** Since the trace \( \gamma_{D,a,b} \) of chordal SLE\(_6\) in a Jordan domain \( D \) is defined (up to a linear time change) as \( f(\gamma) \), where \( \gamma = \gamma_{\mathbb{H},0,\infty} \) is the trace of chordal SLE\(_6\) in the upper half-plane started at 0 and \( f \) is any conformal map from the upper half-plane \( \mathbb{H} \) to \( D \) such that \( f^{-1}(a) = 0 \) and \( f^{-1}(b) = \infty \), it is enough to show that \( \hat{\gamma} = f^{-1}(\hat{\gamma}_{D,a,b}) \) is distributed like the trace of chordal SLE\(_6\) in the upper half-plane. Let \( \hat{K}_t \) denote the filling of \( \hat{\gamma}(t) \) at time \( t \) and let \( \hat{g}_t(z) \) be the unique conformal transformation that maps \( \mathbb{H} \setminus \hat{K}_t \) onto \( \mathbb{H} \) with the following expansion at infinity:

\[
\hat{g}_t(z) = z + \frac{\hat{a}(t)}{z} + o\left(\frac{1}{z}\right).
\]  

We choose to parametrize \( \hat{\gamma}(t) \) so that \( t = \hat{a}(t)/2 \) (this is often called parametrization by capacity, \( \hat{a}(t) \) being the half-plane capacity of the filling up to time \( t \)).

We want to compare \( \hat{\gamma}(t) \) with the trace \( \gamma(t) \) of chordal SLE\(_6\) in the upper half-plane parameterized in the same way (i.e., with \( a(t) = 2t \)), so that, if \( \hat{K}_t \) is the filling of \( \hat{\gamma} \) at time \( t \), \( \mathbb{H} \setminus K_t \) is mapped onto \( \mathbb{H} \) by a conformal \( g_t \) with the following expansion at infinity:

\[
g_t(z) = z + \frac{2t}{z} + o\left(\frac{1}{z}\right).
\]  

Our strategy, following [31, 32] but with modifications (see Remark 5.3), will be to construct suitable polygonal approximations \( \gamma_\varepsilon \) and \( \hat{\gamma}_\varepsilon \) of \( \hat{\gamma} \) and \( \gamma \) which converge, as \( \varepsilon \to 0 \), to the original curves (in the uniform metric on continuous curves (2)), and show that \( \hat{\gamma}_\varepsilon \) and \( \gamma_\varepsilon \) have the same distribution. This implies the equidistribution of \( \hat{\gamma} \) and \( \gamma \).

Let us describe first the construction for \( \gamma_\varepsilon(t) \); we do the same for \( \hat{\gamma}_\varepsilon(t) \). The important features in the construction of the polygonal approximations are the spatial Markov property of the fillings and Cardy’s formula, which are valid for both \( \gamma \) and \( \hat{\gamma} \).
For $\varepsilon > 0$ fixed, as above let $C(u, \varepsilon) = \{z : |u - z| < \varepsilon\} \cap \mathbb{H}$ denote the semi-ball of radius $\varepsilon$ centered at $u$ on the real line. Let $T_1 = T_1(\varepsilon)$ denote the first time $\gamma(t)$ hits $\mathbb{H} \setminus G_1$, where $G_1 \equiv C(0, \varepsilon)$, and define recursively $T_{j+1}$ as the first time $\gamma(t, \infty)$ hits $\mathbb{H} \setminus G_{j+1}$, where $\mathbb{H} = \mathbb{H} \setminus K_T$ and $G_{j+1} \equiv \gamma^{g_{T_j}}_1(C(g_{T_j}(\gamma(T_j)), \varepsilon))$. Notice that $G_{j+1}$ is a bounded simply connected domain chosen so that the conformal transformation which maps $\mathbb{H}$ to $\mathbb{H}$ maps $G_1$ to the semi-ball $C(g_{T_j}(\gamma(T_j)), \varepsilon)$ centered at the point of the real line where the “tip” $\gamma(T_j)$ of the hull $K_T$ is mapped. The spatial Markov property and the conformal invariance of the hull of $SLE_\kappa$ imply that if we write $T_j = \tau_1 + \ldots + \tau_j$, with $\tau_{j+1} \equiv T_{j+1} - T_j$, the $\tau_j$’s are i.i.d. random variables, and also that the distribution of $K_{T_{j+1}}$ is the same as that of $K_T \cup g_{T_j}^{-1}(K_{T_1} + g_{T_j}(\gamma(T_j)))$, where $K_{T_1}$ is a hull equidistributed with $K_T$, but also is independent of $K_T$, and “+” indicates that it is translated by $g_{T_j}(\gamma(T_j))$ along the real line. The polygonal approximation $\gamma_{\varepsilon}$ is obtained by joining, for all $j$, $\gamma(T_j)$ to $\gamma(T_{j+1})$ with a straight segment, where the speed $\gamma_{\varepsilon}'(t)$ is constant.

Now let $\hat{T}_1 = \hat{T}_1(\varepsilon)$ denote the first time $\hat{\gamma}(t)$ hits $\mathbb{H} \setminus \hat{G}_1$, where $\hat{G}_1 \equiv C(0, \hat{\varepsilon})$, and define recursively $\hat{T}_{j+1}$ as the first time $\hat{\gamma}(\hat{T}_j, \infty)$ hits $\mathbb{H} \setminus \hat{G}_{j+1}$, where $\mathbb{H} \setminus \hat{G}_1 \equiv \mathbb{H} \setminus \hat{K}_T$, and $\hat{G}_{j+1} \equiv \hat{g}_{T_j}^{-1}(\hat{C}(\hat{g}_{T_j}(\hat{\gamma}(\hat{T}_j)), \varepsilon))$. We also define $\hat{\tau}_{j+1} \equiv \hat{T}_{j+1} - \hat{T}_j$, so that $\hat{T}_j = \hat{\tau}_1 + \ldots + \hat{\tau}_j$. Once again, $\hat{G}_{j+1}$ is a bounded simply connected domain chosen so that the conformal transformation which maps $\mathbb{H} \setminus \hat{G}_1$ to $\mathbb{H}$ maps $\hat{G}_{j+1}$ to the semi-ball $C(\hat{g}_{T_j}(\hat{\gamma}(\hat{T}_j)), \varepsilon)$ centered at the point on the real line where the “tip” $\hat{\gamma}(\hat{T}_j)$ of the hull $\hat{K}_{T_j}$ is mapped. The polygonal approximation $\hat{\gamma}_{\varepsilon}$ is obtained by joining, for all $j$, $\hat{\gamma}(\hat{T}_j)$ to $\hat{\gamma}(\hat{T}_{j+1})$ with a straight segment, where the speed $\hat{\gamma}_{\varepsilon}'(t)$ is constant.

Consider the sequence of times $T_j$ defined in the natural way so that $\tilde{\gamma}(T_j) = f(\hat{\gamma}(\hat{T}_j))$ and the (discrete-time) stochastic processes $\hat{X}_j \equiv (\hat{K}_{T_j}, \hat{\gamma}(\hat{T}_j))$ and $\tilde{X}_j \equiv (\hat{K}_{T_j}, \hat{\gamma}(\hat{T}_j))$ related by $\hat{X}_j = f^{-1}(\tilde{X}_j)$. If for $x \in \mathbb{R}$ we let $\theta[x]$ denote the translation that maps $x$ to 0 and define the family of conformal maps $(f_{T_j})^{-1} = \theta[\hat{g}_{T_j}(\hat{\gamma}(\hat{T}_j))] \circ \hat{g}_{T_j} \circ f^{-1}$ from $D \setminus \hat{K}_{T_j}$ to $\mathbb{H}$, then $(\hat{f}_{T_j})^{-1}$ sends $\tilde{\gamma}(T_j)$ to 0 and $b$ to $\infty$, and $(\hat{T}_{j+1})$ is the first time $\hat{\gamma}(\hat{T}_j, \infty)$ hits $\mathbb{H} \setminus \hat{G}_{j+1}$, where $\mathbb{H} \setminus \hat{G}_1 \equiv \mathbb{H} \setminus \hat{K}_T$, and $\hat{G}_{j+1} = f_{T_j}(C(0, \varepsilon))$. Therefore, $\{\hat{T}_j\}$ is a sequence of stopping times like those used in the definition of the spatial Markov property and, thanks to the relation $\hat{X}_j = f^{-1}(\tilde{X}_j)$, the fact that $\hat{K}_T$ satisfies the spatial Markov property implies that $\hat{X}_j$ is a Markov chain. We also note that the fact that the hitting distribution of $\hat{\gamma}(t)$ is determined by Cardy’s formula implies the same for the hitting distribution of $\hat{\gamma}(t)$, thanks to the conformal invariance of Cardy’s formula. We next use these properties to show that $\hat{\gamma}_{\varepsilon}$ is distributed like $\gamma_{\varepsilon}$.

To do so, we first note that $g_{T_j}$ and $\hat{g}_{T_j}$ are random and their distributions are functionals of those of the hulls $K_{T_j}$ and $\hat{K}_{T_j}$, since there is a one-to-one correspondence between hulls and conformal maps (with the normalization we have chosen in (10)–(11)). Therefore, since $\hat{K}_{T_1}$ is distributed like $K_{T_1}$ (see Lemma 5.1), $g_{T_1}$ and $\hat{g}_{T_1}$ have the same distribution, which also implies that $\hat{T}_1$ is distributed like $T_1$ because, due to the parametrization by capacity of $\gamma$ and $\hat{\gamma}$, $2T_1$ is exactly the coefficient of the term $1/z$ in the expansion at infinity of $g_{T_1}$, and $2\hat{T}_1$ is exactly the coefficient of the term $1/z$ in the expansion at
infinity of \( \tilde{g}_{T_1} \). Moreover, it is also clear that \( \hat{\gamma}(T_1) \) is distributed like \( \gamma(T_1) \), because their distributions are both determined by Cardy’s formula, and so \( g_{T_1}(\gamma(T_1)) \) is distributed like \( g_{T_1}(\gamma(T_1)) \). Notice that the law of the hull \( \tilde{K}_{T_1} \) is conformally invariant because, by Lemma 5.1, it coincides with the law of the \( SLE_6 \) hull \( K_{T_1} \).

Using now the Markovian character of \( \hat{X}_j \), which implies that, conditioned on \( \hat{X}_1 = (\tilde{K}_{T_1}, \hat{\gamma}(T_1)) \), \( \tilde{K}_{T_2} \) and \( \hat{\gamma}(T_2) \) are determined by Cardy’s formula in \( \tilde{G}_2 \), from the fact that \( \tilde{K}_{T_1} \) is equidistributed with \( K_{T_1} \) and therefore \( \tilde{G}_2 \) equidistributed with \( G_2 \), we obtain that the hull \( \tilde{K}_{T_2} \) is distributed like \( K_{T_2} \) and its “tip” \( \hat{\gamma}(T_2) \) is distributed like the “tip” \( \gamma(T_2) \) of the hull \( K_{T_2} \). We can then conclude that the joint distribution of \( \{\hat{\gamma}(T_1), \hat{\gamma}(T_2)\} \) is the same as that of \( \{\gamma(T_1), \gamma(T_2)\} \). It also follows immediately that \( \tilde{g}_{T_2} \) is equidistributed with \( g_{T_2} \) and \( \hat{\tau}_2 \) is equidistributed with \( \tau_2 \) or indeed with \( \tau_1 \).

By repeating this recursively, using the Markovian character of the hulls and tips, we obtain that, for all \( j \), \( \{\hat{\gamma}(T_1), \ldots, \hat{\gamma}(T_j)\} \) is equidistributed with \( \{\gamma(T_1), \ldots, \gamma(T_j)\} \). This immediately implies that \( \hat{\tau}_\epsilon \) is equidistributed with \( \gamma_\epsilon \).

To conclude the proof, we just have to show that, as \( \epsilon \to 0 \), \( \hat{\tau}_\epsilon \) converges to \( \hat{\gamma} \) and \( \gamma_\epsilon \) to \( \gamma \) in the uniform metric (2) on continuous curves. This, however, follows easily from the properties of the continuous curves we are considering (see the discussion after (7)), if we can show that \( \hat{T}_{j+1} - \hat{T}_j = \hat{\tau}_{j+1} \) and \( T_{j+1} - T_j = \tau_{j+1} \) go to 0 as \( \epsilon \to 0 \). To see this, we recall that \( \hat{\tau}_{j+1} \) and \( \tau_{j+1} \) are distributed like \( \tau_1 \) and use Lemma 2.1 of [22], which implies the (deterministic) bound \( \tau_1(\epsilon) \leq \epsilon^2/2 \), which follows from the well-known bound \( a(t) \leq \epsilon^2 \) for the half-plane capacity \( a(t) = 2t \) of (11).

Remark 5.3. The procedure for constructing the polygonal approximations of \( \hat{\gamma} \) and \( \gamma \) and the recursive strategy for proving that they have the same distribution include significant modifications to the sketched argument for convergence of the percolation exploration process to chordal \( SLE_6 \) proposed by Smirnov in [31] and [32]. One modification is that we use “conformal semi-balls” instead of balls (see [31,32]) to define the sequences of stopping times \( \{\hat{T}_j\} \) and \( \{T_j\} \). Since the paths we are dealing with touch themselves (or almost do), if one were to use ordinary balls, some of them would intersect multiple disjoint pieces of the past hull, making it impossible to use Cardy’s formula in the “triangular setting” proposed by (Carleson and) Smirnov and used here. The use of conformally mapped semi-balls ensures, thanks to the choice of the conformal maps, that the domains used to define the stopping times intersect a single piece of the past hull. This is a natural choice (exploiting the conformal invariance) to obtain a good polygonal approximation of the paths while still being able to use Cardy’s formula to determine hitting distributions.

We will next prove a version of Smirnov’s result (Theorem 1 above) extended to cover the convergence of crossing probabilities to Cardy’s formula for the case of sequences of admissible domains (see the definition of admissible in Section 4.1). The statement of Theorem 3 below is certainly not optimal, but it is sufficient for our purposes. We remark that a weaker statement restricted, for instance, only to Jordan domains would not be sufficient – see Figure 5 and the discussion referring to it in the proof of Theorem 4 below.
Theorem 3. Consider a sequence \( \{ (D_k, a_k, c_k, b_k, d_k) \} \) of domains \( D_k \) containing the origin, admissible with respect to the points \( a_k, c_k, d_k \) on \( \partial D_k \), and with \( b_k \) belonging to the interior of the counterclockwise arc \( a_kb_k \) of \( \partial D_k \). Assume that, as \( k \to \infty \), \( b_k \to b \) and there is convergence in the metric (2) of the counterclockwise arcs corresponding to the counterclockwise arcs \( \overline{a_kc_k} \), \( \overline{c_kd_k} \) to the interior of \( \overline{cd} \). Then, for any sequence \( \delta_k \downarrow 0 \), the probability \( \Phi^{\delta_k}_k(=\Phi^{\delta_k}_{D_k}) \) of a blue crossing inside \( D_k \) from \( \overline{a_kc_k} \) to \( \overline{b_kb_k} \) converges, as \( k \to \infty \), to Cardy's formula \( \Phi_D \) (see (6)) for a blue crossing inside \( D \) from \( \overline{ac} \) to \( \overline{cd} \).

Proof. When \( D \) is Jordan, one can use essentially the same arguments as in Lemma 7.3 below (see also Theorem 1 of [11]) to construct for each \( \varepsilon > 0 \), \( \varepsilon \)-approximations, \( (\tilde{D}, \tilde{a}, \tilde{b}, \tilde{c}, \tilde{d}) \) and \( (\tilde{D}, \tilde{a}, \tilde{b}, \tilde{c}, \tilde{d}) \), to \( (D, a, b, c, d) \) so that \( \Phi_{\tilde{D}(\varepsilon)}, \Phi_{\tilde{D}(\varepsilon)} \xrightarrow{\varepsilon \to 0} \Phi_D \) while

\[
\Phi_{\tilde{D}(\varepsilon)} = \liminf_{k \to \infty} \Phi^{\delta_k}_{\tilde{D}(\varepsilon)} \leq \liminf_{k \to \infty} \Phi^{\delta_k}_{D_k} \leq \limsup_{k \to \infty} \Phi^{\delta_k}_{D_k} \leq \limsup_{k \to \infty} \Phi^{\delta_k}_{\tilde{D}(\varepsilon)} = \Phi_{\tilde{D}(\varepsilon)}.
\]

When \( D \) is not Jordan but admissible, one can do a similar construction on a Riemann surface with a cut starting from \( a \) to separate the touching arcs \( \overline{ac} \) and \( \overline{cd} \) of \( \partial D \). This is similar to an argument in [34] replacing an annulus in the plane by its universal cover.

Remark 5.4. A construction for the non-Jordan case of approximating \( \tilde{D} \) and \( \tilde{D} \) without the use of a cut surface may be found in the appendix of [8]. It has been suggested to us by a referee and by V. Beffara that existing proofs of convergence to Cardy’s formula for fixed domains (see, in particular, [5]) should also work in the context of Theorem 3.

6 Boundary of the Hull and the Scaling Limit

We give here some important results which are needed in the proofs of the main theorems. We start with two lemmas from [8, 9], which are consequences of [2], of standard bounds on the probability of events corresponding to having a certain number of disjoint monochromatic crossings of an annulus (see Lemma 5 of [17], Appendix A of [21], and also [3]). Afterwards we give two related lemmas that are more suited to this paper and whose proofs are modified revisions of those of the first two lemmas.

Lemma 6.1. Let \( \gamma^{\delta}_{\tilde{D}, -i,i} \) be the percolation exploration path on the edges of \( \delta \mathcal{H} \) inside (a \( \delta \)-approximation of) \( \tilde{D} \) between (\( e \)-vertices close to) \( -i \) and \( i \). For any fixed point \( z \in \mathbb{D} \), chosen independently of \( \gamma^{\delta}_{\tilde{D}, -i,i} \), as \( \delta \to 0 \), \( \gamma^{\delta}_{\tilde{D}, -i,i} \) and the boundary \( \partial \mathbb{D}^{\delta}_{-i,i}(z) \) of the domain \( \mathbb{D}^{\delta}_{-i,i}(z) \) that contains \( z \) jointly have limits in distribution along subsequences of \( \delta \) with respect to the uniform metric (2) on continuous curves. Moreover, any subsequence limit of \( \partial \mathbb{D}^{\delta}_{-i,i}(z) \) is almost surely a simple loop [3].

Proof. The first part of the lemma is a direct consequence of [2]; it is enough to notice that the (random) polygonal curves \( \gamma^{\delta}_{\tilde{D}, -i,i} \) and \( \partial \mathbb{D}^{\delta}_{-i,i}(z) \) satisfy the conditions in [2] and thus have a scaling limit in terms of continuous curves, at least along subsequences of \( \delta \).
To prove the second part, we use standard percolation bounds (see Lemma 5 of [17] and Appendix A of [21]) to show that, in the limit $\delta \to 0$, the loop $\partial \mathbb{D}_{-i,i}^\delta(z)$ does not collapse on itself but remains a simple loop [3].

Let us assume that this is not the case and that the limit $\tilde{\gamma}$ of $\partial \mathbb{D}_{-i,i}^\delta_k(z)$ along some subsequence $\{\delta_k\}_{k \in \mathbb{N}}$ touches itself, i.e., $\tilde{\gamma}(t_0) = \tilde{\gamma}(t_1)$ for $t_0 \neq t_1$ with positive probability. If so, we can take $\varepsilon > \varepsilon' > 0$ so small that the annulus $B(\tilde{\gamma}(t_1), \varepsilon) \setminus B(\tilde{\gamma}(t_1), \varepsilon')$ is crossed at least four times by $\tilde{\gamma}$ (here $B(u, r)$ is the ball of radius $r$ centered at $u$).

Because of the choice of topology, the convergence in distribution of $\partial \mathbb{D}_{-i,i}^\delta_k(z)$ to $\tilde{\gamma}$ implies that we can find coupled versions of $\partial \mathbb{D}_{-i,i}^\delta(z)$ and $\tilde{\gamma}$ on some $(\Omega', \mathcal{B}', \mathbb{P}')$ such that $d(\partial \mathbb{D}_{-i,i}^\delta(z), \tilde{\gamma}) \to 0$, for all $\omega' \in \Omega'$ as $k \to \infty$ (see, e.g., Corollary 1 of [6]).

Using this coupling, we can choose $k$ large enough (depending on $\omega'$) so that $\partial \mathbb{D}_{-i,i}^\delta(z)$ stays in an $\varepsilon'/2$-neighborhood $\mathcal{N}(\tilde{\gamma}, \varepsilon'/2) \equiv \bigcup_{u \in \tilde{\gamma}} B(u, \varepsilon'/2)$ of $\tilde{\gamma}$. This however would correspond to an event $\mathcal{A}_{\tilde{\gamma}(t_1)}(\varepsilon, \varepsilon')$ that (at least) four paths of one color (corresponding to the four crossings by $\partial \mathbb{D}_{-i,i}^\delta(z)$) and two of the other color cross the annulus $B(\tilde{\gamma}(t_1), \varepsilon - \varepsilon'/2) \setminus B(\tilde{\gamma}(t_1), 3 \varepsilon'/2)$. As $\delta_k \to 0$, we can let $\varepsilon' \to 0$ (keeping $\varepsilon$ fixed), in which case, we claim that the probability of seeing the event just described somewhere inside $\mathbb{D}$ goes to zero, leading to a contradiction. This is because a standard bound [17] on the probability of six disjoint crossings (not all of the same color) of an annulus gives that the probability of $\mathcal{A}_{w}(\varepsilon, \varepsilon')$ scales as $(\frac{\varepsilon}{\varepsilon'})^{2+\alpha}$ with $\alpha > 0$. As $\delta \to 0$, we can let $\varepsilon' \to 0$ (keeping $\varepsilon$ fixed); then the probability of $\mathcal{A}_{w}(\varepsilon, \varepsilon')$ goes to zero sufficiently rapidly with $\varepsilon'$ to conclude that the probability to see such an event anywhere in $\mathbb{D}$ goes to zero. $lacksquare$

The second lemma states that, for every subsequence limit, the discrete boundaries converge to the boundaries of the domains generated by the limiting continuous curve. In order to insure this, we need to show that whenever the discrete exploration path comes at distance of order $\delta$ from the boundary of the exploration domain or from its past filling, producing a “fjord” (see [3]) and causing touching in the limit $\delta \to 0$, with high probability the discrete path already closes the fjord by touching the boundary of the exploration domain or by “touching” itself (i.e., getting to distance $\delta$ of itself, just one hexagon away), so that no discrepancy arises, as $\delta \to 0$, between the limit of the discrete filling and the filling of the limiting continuous curve. This issue will come up in the proof of Theorem 4 below, and is one of the main technical issues of this paper.

**Lemma 6.2.** Using the notation of Lemma 6.1, let $\gamma_{D,-i,i}^\delta$ be the limit in distribution of $\gamma_{D,-i,i}^\delta_k$ as $\delta \to 0$ along some convergent subsequence $\{\delta_k\}$ and $\partial \mathbb{D}_{-i,i}(z)$ be the boundary of the domain $\mathbb{D}_{-i,i}(z)$ of $\mathbb{D} \setminus \gamma_{D,-i,i}^\delta[0,1]$ that contains $z$. Then, as $k \to \infty$, $(\gamma_{D,-i,i}^\delta_k, \partial \mathbb{D}_{-i,i}^\delta_k(z))$ converges in distribution to $(\gamma_{D,-i,i}, \partial \mathbb{D}_{-i,i}(z))$.

**Proof.** Let $\{\delta_k\}_{k \in \mathbb{N}}$ be a convergent subsequence for $\gamma_{D,-i,i}^\delta_k$ and $\gamma \equiv \gamma_{D,-i,i}$ the limit in distribution of $\gamma_{D,-i,i}^\delta_k$ as $k \to \infty$. For simplicity of notation, we now drop the $k$ and write $\delta$ instead of $\delta_k$. Because of the choice of topology, the convergence in distribution of $\gamma_{-i,i}^\delta_k$ to $\gamma$ implies that we can find coupled versions of $\gamma_{-i,i}^\delta$ and $\gamma$ on some probability space $(\Omega', \mathcal{B}', \mathbb{P}')$ such that $d(\gamma_{-i,i}^\delta(\omega'), \gamma(\omega')) \to 0$, for all $\omega' \in \Omega'$ as $k \to \infty$ (see, for example,
Corollary 1 of [6]). Using this coupling, our first task will be to prove the following claim:

(C) For two (deterministic) points \( u, v \in \mathbb{D} \), the probability that \( \mathbb{D}_{-i,i}(u) = \mathbb{D}_{-i,i}(v) \) but \( \mathbb{D}^\delta_{-i,i}(u) \neq \mathbb{D}^\delta_{-i,i}(v) \) or vice versa goes to zero as \( \delta \to 0 \).

Let us consider first the case of \( u, v \) such that \( \mathbb{D}_{-i,i}(u) = \mathbb{D}_{-i,i}(v) \) but \( \mathbb{D}^\delta_{-i,i}(u) \neq \mathbb{D}^\delta_{-i,i}(v) \). Since \( \mathbb{D}_{-i,i}(u) \) is an open subset of \( \mathbb{C} \), there exists a continuous curve \( \gamma_{u,v} \) joining \( u \) and \( v \) and a constant \( \varepsilon > 0 \) such that the \( \varepsilon \)-neighborhood \( \mathcal{N}(\gamma_{u,v}, \varepsilon) \) of the curve is contained in \( \mathbb{D}_{-i,i}(u) \), which implies that \( \gamma \) does not intersect \( \mathcal{N}(\gamma_{u,v}, \varepsilon) \). Now, if \( \gamma^\delta \) does not intersect \( \mathcal{N}(\gamma_{u,v}, \varepsilon/2) \), for \( \delta \) small enough, then there is a \( \mathcal{T} \)-path \( \pi \) of unexplored hexagons connecting the hexagon that contains \( u \) with the hexagon that contains \( v \), and we conclude that \( \mathbb{D}^\delta_{-i,i}(u) = \mathbb{D}^\delta_{-i,i}(v) \).

This shows that the existence of a curve \( \gamma_{u,v} \) whose \( \varepsilon \)-neighborhood \( \mathcal{N}(\gamma_{u,v}, \varepsilon) \) is not intersected by \( \gamma \) but whose \( \varepsilon/2 \)-neighborhood \( \mathcal{N}(\gamma_{u,v}, \varepsilon/2) \) is intersected by \( \gamma^\delta \). This implies that \( \forall u, v \in \mathbb{D}, \exists \varepsilon > 0 \) such that \( \mathbb{P}(\mathbb{D}_{-i,i}(u) = \mathbb{D}_{-i,i}(v) \text{ but } \mathbb{D}^\delta_{-i,i}(u) \neq \mathbb{D}^\delta_{-i,i}(v)) \leq \mathbb{P}(d(\gamma^\delta, \gamma) \geq \varepsilon/2) \). But the right hand side goes to zero for every \( \varepsilon > 0 \) as \( \delta \to 0 \), which concludes the proof of one direction of the claim.

To prove the other direction, we consider two points \( u, v \in \mathbb{D} \) such that \( \mathbb{D}_{-i,i}(u) \neq \mathbb{D}_{-i,i}(v) \) but \( \mathbb{D}^\delta_{-i,i}(u) = \mathbb{D}^\delta_{-i,i}(v) \). Assume that \( u \) is trapped before \( v \) by \( \gamma \) and suppose for the moment that \( \mathbb{D}_{-i,i}(u) \) is a domain of type 3 or 4 (as defined at the end of Section 4); the case of a domain of type 1 or 2 is analogous and will be treated later. Let \( t_1 \) be the first time \( u \) is trapped by \( \gamma \) with \( \gamma(t_0) = \gamma(t_1) \) the double point of \( \gamma \) where the domain \( \mathbb{D}_{-i,i}(u) \) containing \( u \) is “sealed off.” At time \( t_1 \), a new domain containing \( u \) is created and \( v \) is disconnected from \( u \).

Choose \( \varepsilon > 0 \) small enough so that neither \( u \) nor \( v \) is contained in the ball \( B(\gamma(t_1), \varepsilon) \) of radius \( \varepsilon \) centered at \( \gamma(t_1) \), nor in the \( \varepsilon \)-neighborhood \( \mathcal{N}(\gamma[t_0, t_1], \varepsilon) \) of the portion of \( \gamma \) which surrounds \( u \). Then it follows from the coupling that, for \( \delta \) small enough, there are appropriate parameterizations of \( \gamma \) and \( \gamma^\delta \) such that the portion \( \gamma^\delta[t_0, t_1] \) of \( \gamma^\delta(t) \) is inside \( \mathcal{N}(\gamma[t_0, t_1], \varepsilon) \), and \( \gamma^\delta(t_0) \) and \( \gamma^\delta(t_1) \) are contained in \( B(\gamma(t_1), \varepsilon) \).

For \( u \) and \( v \) to be contained in the same domain in the discrete construction, there must be a \( \mathcal{T} \)-path \( \pi \) of unexplored hexagons connecting the hexagon that contains \( u \) to the hexagon that contains \( v \). From what we said in the previous paragraph, any such \( \mathcal{T} \)-path connecting \( u \) and \( v \) would have to go through a “bottleneck” in \( B(\gamma(t_1), \varepsilon) \).

Assume now, for concreteness but without loss of generality, that \( \mathbb{D}_{-i,i}(u) \) is a domain of type 3, which means that \( \gamma \) winds around \( u \) counterclockwise, and consider the hexagons to the “left” of \( \gamma^\delta[t_0, t_1] \). Those hexagons form a “quasi-loop” around \( u \) since they wind around it (counterclockwise) and the first and last hexagons are both contained in \( B(\gamma(t_1), \varepsilon) \). The hexagons to the left of \( \gamma^\delta[t_0, t_1] \) belong to the set \( \Gamma_Y(\gamma^\delta) \), which can be seen as a (nonsimple) path by connecting the centers of the hexagons in \( \Gamma_Y(\gamma^\delta) \) by straight segments. Such a path shadows \( \gamma^\delta \), with the difference that it can have double (or even triple) points, since the same hexagon can be visited more than once. Consider \( \Gamma_Y(\gamma^\delta) \) as a path \( \hat{\gamma}^\delta \) with a given parametrization \( \hat{\gamma}^\delta(t) \), chosen so that \( \hat{\gamma}^\delta(t) \) is inside \( B(\gamma(t_1), \varepsilon) \) when \( \gamma^\delta(t) \) is, and it winds around \( u \) together with \( \gamma^\delta(t) \).
Now suppose that there were two times, \( \hat{t}_0 \) and \( \hat{t}_1 \), such that \( \hat{\gamma}^\delta(\hat{t}_1) = \hat{\gamma}^\delta(\hat{t}_0) \in B(\gamma(t_1), \varepsilon) \) and \( \hat{\gamma}^\delta[\hat{t}_0, \hat{t}_1] \) winds around \( u \). This would imply that the “quasi-loop” of explored yellow hexagons around \( u \) is actually completed, and that \( D_{\delta-i,i}(v) \neq D_{\delta-i,i}(u) \). Thus, for \( u \) and \( v \) to belong to the same discrete domain, this cannot happen.

For any \( 0 < \varepsilon' < \varepsilon \), if we take \( \delta \) small enough, \( \hat{\gamma}^\delta \) will be contained inside \( \mathcal{N}(\gamma, \varepsilon') \), due to the coupling. Following the considerations above, the fact that \( u \) and \( v \) belong to the same domain in the discrete construction but to different domains in the continuum construction implies, for \( \delta \) small enough, that there are four disjoint yellow \( \mathcal{T} \)-paths crossing the annulus \( B(\gamma(t_1), \varepsilon) \setminus B(\gamma(t_1), \varepsilon') \) (the paths have to be disjoint because, as we said, \( \hat{\gamma}^\delta \) cannot, when coming back to \( B(\gamma(t_1), \varepsilon) \) after winding around \( u \), touch itself inside \( B(\gamma(t_1), \varepsilon) \)). Since \( B(\gamma(t_1), \varepsilon) \setminus B(\gamma(t_1), \varepsilon') \) is also crossed by at least two blue \( \mathcal{T} \)-paths from \( \Gamma_B(\gamma^\delta) \), there is a total of at least six \( \mathcal{T} \)-paths, not all of the same color, crossing the annulus \( B(\gamma(t_1), \varepsilon) \setminus B(\gamma(t_1), \varepsilon') \). As \( \delta \to 0 \), we can let \( \varepsilon' \to 0 \) (keeping \( \varepsilon \) fixed) and conclude, like in the proof of Lemma [6.1], that the probability to see such an event anywhere in \( \mathbb{D} \) goes to zero.

In the case in which \( u \) belongs to a domain of type 1 or 2, let \( \mathcal{E} \) be the excursion that traps \( u \) and \( \gamma(t_0) \in \partial \mathbb{D} \) be the point on the boundary of \( \mathbb{D} \) where \( \mathcal{E} \) starts and \( \gamma(t_1) \in \partial \mathbb{D} \) the point where it ends. Choose \( \varepsilon > 0 \) small enough so that neither \( u \) nor \( v \) is contained in the balls \( B(\gamma(t_0), \varepsilon) \) and \( B(\gamma(t_1), \varepsilon) \) of radius \( \varepsilon \) centered at \( \gamma(t_0) \) and \( \gamma(t_1) \), nor in the \( \varepsilon \)-neighborhood \( \mathcal{N}(\mathcal{E}, \varepsilon) \) of the excursion \( \mathcal{E} \). Because of the coupling, for \( \delta \) small enough (depending on \( \varepsilon \)), \( \gamma^\delta \) shadows \( \gamma \) along \( \mathcal{E} \), staying within \( \mathcal{N}(\mathcal{E}, \varepsilon) \). If this is the case, any \( \mathcal{T} \)-path of unexplored hexagons connecting the hexagon that contains \( u \) with the hexagon that contains \( v \) would have to go through one of two “bottlenecks,” one contained in \( B(\gamma(t_0), \varepsilon) \) and the other in \( B(\gamma(t_1), \varepsilon) \).

Assume for concreteness (but without loss of generality) that \( u \) is in a domain of type 1, which means that \( \gamma \) winds around \( u \) counterclockwise. If we parameterize \( \gamma \) and \( \gamma^\delta \) so that \( \gamma^\delta(t_0) \in B(\gamma(t_0), \varepsilon) \) and \( \gamma^\delta(t_1) \in B(\gamma(t_1), \varepsilon) \), \( \gamma^\delta[t_0, t_1] \) forms a “quasi-excursion” around \( u \) since it winds around it (counterclockwise) and it starts inside \( B_{\varepsilon}(\gamma(t_0)) \) and ends inside \( B_{\varepsilon}(\gamma(t_1)) \). Notice that if \( \gamma^\delta \) touched \( \partial \mathbb{D}^\delta \), inside both \( B_{\varepsilon}(\gamma(t_0)) \) and \( B_{\varepsilon}(\gamma(t_1)) \), this would imply that the “quasi-excursion” is a real excursion and that \( D^\delta_{\delta-i,i}(v) \neq D^\delta_{\delta-i,i}(u) \).

For any \( 0 < \varepsilon' < \varepsilon \), if we take \( \delta \) small enough, \( \gamma^\delta \) will be contained inside \( \mathcal{N}(\gamma, \varepsilon') \), due to the coupling. Therefore, the fact that \( \mathbb{D}^\delta_{\delta-i,i}(v) = \mathbb{D}^\delta_{\delta-i,i}(u) \) implies, with probability going to one as \( \delta \to 0 \), that for \( \varepsilon > 0 \) fixed and any \( 0 < \varepsilon' < \varepsilon \), \( \gamma^\delta \) enters the ball \( B(\gamma(t_i), \varepsilon') \) and does not touch \( \partial \mathbb{D}^\delta \) inside the larger ball \( B(\gamma(t_i), \varepsilon) \), for \( i = 0 \) or 1. This is equivalent to having at least two yellow and one blue \( \mathcal{T} \)-paths (contained in \( \mathbb{D}^\delta \)) crossing the annulus \( B(\gamma(t_i), \varepsilon) \setminus B(\gamma(t_i), \varepsilon') \). Let us call \( \mathcal{B}_w(\varepsilon, \varepsilon') \) the event described above, where \( \gamma(t_i) = w \); a standard bound [21] (this bound can also be derived from the one obtained in [17]) on the probability of disjoint crossings (not all of the same color) of a semi-annulus in the upper half-plane gives that the probability of \( \mathcal{B}_w(\varepsilon, \varepsilon') \) scales as \( (\frac{\varepsilon'}{\varepsilon})^{1+\beta} \) with \( \beta > 0 \). (We can apply the bound to our case because the unit disc is a convex subset of the half-plane \( \{x + iy : y > -1\} \) and therefore the intersection of an annulus centered at say \( -i \) with the unit disc is a subset of the intersection of the same annulus with the half-plane \( \{x + iy : y > -1\} \).) As \( \delta \to 0 \), we can let \( \varepsilon' \to 0 \) (keeping \( \varepsilon \) fixed),
concluding that the probability that such an event occurs anywhere on the boundary of the disc goes to zero.

We have shown that, for two fixed points \( u, v \in \mathbb{D} \), having \( \partial \mathbb{D}_{-i,i}(u) \neq \partial \mathbb{D}_{-i,i}(v) \) but \( \mathbb{D}_{-i,i}(u) = \mathbb{D}_{-i,i}(v) \) or vice versa implies the occurrence of an event whose probability goes to zero as \( \delta \to 0 \), and the proof of the claim is concluded.

The Hausdorff distance between two closed nonempty subsets of \( \overline{\mathbb{D}} \) is

\[
d_H(A, B) \equiv \inf\{ \ell \geq 0 : B \subset \bigcup_{a \in A} B(a, \ell), A \subset \bigcup_{b \in B} B(b, \ell) \}. \tag{13}
\]

With this metric, the collection of closed subsets of \( \overline{\mathbb{D}} \) is a compact space. We will next prove that \( \partial \mathbb{D}_{-i,i}(z) \) converges in distribution to \( \partial \mathbb{D}_{-i,i}(z) \) as \( \delta \to 0 \), in the topology induced by \( \mathbb{D}_{-i,i}(z) \). (Notice that the coupling between \( \gamma^\delta \) and \( \gamma \) provides a coupling between \( \partial \mathbb{D}_{-i,i}(z) \) and \( \partial \mathbb{D}_{-i,i}(z) \), seen as boundaries of domains produced by the two paths.)

We will now use Lemma 6.1 and take a further subsequence \( k_n \) of the \( \delta \)'s that for simplicity of notation we denote by \( \{ \delta_n \}_{n \in \mathbb{N}} \) such that, as \( n \to \infty \), \( \{ \gamma^\delta_n, \partial \mathbb{D}_{-i,i}(z) \} \) converge jointly in distribution to \( \{ \gamma, \partial \mathbb{D}_{-i,i}(z) \} \), where \( \gamma \) is a simple loop. For any \( \varepsilon > 0 \), since \( \tilde{\gamma} \) is a compact set, we can find a covering of \( \tilde{\gamma} \) by a finite number of balls of radius \( \varepsilon/2 \) centered at points on \( \tilde{\gamma} \). Each ball contains both points in the interior \( \text{int}(\tilde{\gamma}) \) of \( \tilde{\gamma} \) and in the exterior \( \text{ext}(\tilde{\gamma}) \) of \( \tilde{\gamma} \), and we can choose (independently of \( n \)) one point from \( \text{int}(\tilde{\gamma}) \) and one from \( \text{ext}(\tilde{\gamma}) \) inside each ball.

Once again, the convergence in distribution of \( \partial \mathbb{D}_{-i,i}(z) \) to \( \tilde{\gamma} \) implies the existence of a coupling such that, for \( n \) large enough, the selected points that are in \( \text{int}(\tilde{\gamma}) \) are contained in \( \mathbb{D}_{-i,i}(z) \), and those that are in \( \text{ext}(\tilde{\gamma}) \) are contained in the complement of \( \mathbb{D}_{-i,i}(z) \). But by claim (C), each one of the selected points that is contained in \( \mathbb{D}_{-i,i}(z) \) is also contained in \( \mathbb{D}_{-i,i}(z) \) with probability going to 1 as \( n \to \infty \); analogously, each one of the selected points contained in the complement of \( \mathbb{D}_{-i,i}(z) \) is also contained in the complement of \( \mathbb{D}_{-i,i}(z) \) with probability going to 1 as \( n \to \infty \). This implies that \( \partial \mathbb{D}_{-i,i}(z) \) crosses each one of the balls in the covering of \( \tilde{\gamma} \), and therefore \( \tilde{\gamma} \subset \bigcup_{u \in \partial \mathbb{D}_{-i,i}(z)} B(u, \varepsilon) \). From this and the coupling between \( \partial \mathbb{D}_{-i,i}(z) \) and \( \tilde{\gamma} \), it follows immediately that, for \( n \) large enough, \( \partial \mathbb{D}_{-i,i}(z) \subset \bigcup_{u \in \partial \mathbb{D}_{-i,i}(z)} B(u, \varepsilon) \) with probability close to one.

A similar argument (analogous to the previous one but simpler, since it does not require the use of \( \tilde{\gamma} \), with the roles of \( \mathbb{D}_{-i,i}(z) \) and \( \mathbb{D}_{-i,i}(z) \) inverted, shows that \( \partial \mathbb{D}_{-i,i}(z) \subset \bigcup_{u \in \partial \mathbb{D}_{-i,i}(z)} B(u, \varepsilon) \) with probability going to 1 as \( n \to \infty \). Therefore, for all \( \varepsilon > 0 \),

\[
\mathbb{P}(d_H(\partial \mathbb{D}_{-i,i}(z), \partial \mathbb{D}_{-i,i}(z)) > \varepsilon) \to 0 \quad \text{as} \quad n \to \infty,
\]

which implies convergence in distribution of \( \partial \mathbb{D}_{-i,i}(z) \) to \( \partial \mathbb{D}_{-i,i}(z) \), as \( \delta_n \to 0 \), in the topology of \( \mathbb{D}_{-i,i}(z) \). But Lemma 6.1 implies that \( \partial \mathbb{D}_{-i,i}(z) \) converges in distribution (using (2)) to a simple loop; therefore \( \partial \mathbb{D}_{-i,i}(z) \) must also be simple and we have convergence in the topology of (2).

It is also clear that the argument above is independent of the subsequence \( \{ \delta_n \} \), so the limit of \( \partial \mathbb{D}_{-i,i}(z) \) is unique and coincides with \( \partial \mathbb{D}_{-i,i}(z) \). Hence, we have convergence in distribution of \( \partial \mathbb{D}_{-i,i}(z) \) to \( \partial \mathbb{D}_{-i,i}(z) \), as \( \delta \to 0 \), in the topology of (2), and indeed joint convergence of \( (\gamma^\delta, \partial \mathbb{D}_{-i,i}(z)) \) to \( (\gamma, \partial \mathbb{D}_{-i,i}(z)) \).
We next give two new lemmas which mostly follow from the previous ones (or their proofs) but are more suitable for the purposes of this paper. Let $D$ be a Jordan domain, with $a$ and $b$ two distinct points on $\partial D$, and consider Jordan sets $D^\delta$, for $\delta > 0$, from $\delta \mathcal{H}$ such that $(D^\delta, a^\delta, b^\delta) \to (D, a, b)$, as $\delta \to 0$, where $a^\delta, b^\delta \in \partial D^\delta$ are two distinct e-vertices on $\partial D^\delta$. This means that $(D^\delta, a^\delta, b^\delta)$ is a $\delta$-approximation of $(D, a, b)$. Denote by $\gamma^\delta_{D,a,b}$ the percolation exploration path inside $D^\delta$ from $a^\delta$ to $b^\delta$.

Let $f$ be a conformal map from the upper half-plane $\mathbb{H}$ to the Jordan domain $D$ and assume that $f^{-1}(a) = 0$ and $f^{-1}(b) = \infty$. (Since $D$ is a Jordan domain, the map $f^{-1}$ has a continuous extension from $D$ to $D \cup \partial D$ – see Theorem 7 of Appendix A – and, by a slight abuse of notation, we do not distinguish between $f^{-1}$ and its extension; the same applies to $f$.) Denote by $C(0, \varepsilon) = \{z : |z| < \varepsilon\} \cap \mathbb{H}$ the semi-ball of radius $\varepsilon$ centered at the origin of the real line. Let $G \equiv f(C(0, \varepsilon))$, $c' \equiv f(\varepsilon)$, $d' \equiv f(-\varepsilon)$. Also denote by $\partial^*G$ the following subset of the boundary of $G$: $\partial^*G \equiv f(\{z : |z| = \varepsilon\} \cap \mathbb{H})$.

Analogously, let $f^\delta$ be a conformal map from the upper half-plane $\mathbb{H}$ to the Jordan set $D^\delta$, assume that $(f^\delta)^{-1}(a^\delta) = 0$ and $(f^\delta)^{-1}(b^\delta) = \infty$, and define $G^\delta \equiv f^\delta(C'(0, \varepsilon))$ and $\partial^*G^\delta \equiv f^\delta(\{z : |z| = \varepsilon\} \cap \mathbb{H})$. Note that since $\partial D^\delta \to \partial D$, by an application of Corollary A.2 of Appendix A, we can and do choose $f^\delta$ so that it converges to $f$ uniformly in $\mathbb{H}$. (We remark that the full strength of Corollary A.2 is not needed here since we are dealing with Jordan domains). With this choice, $\partial^*G^\delta \to \partial^*G$ in the metric (2).

Let $T^\delta$ be the first time that $\gamma^\delta_{D,a,b}$ intersects $\partial^*G^\delta$, and let $K^\delta_{T^\delta}$ be the (discrete) filling of $\gamma^\delta_{D,a,b}[0, T^\delta]$, i.e., the union of the hexagons explored up to time $T^\delta$ and those unexplored hexagons from which it is not possible to reach $b$ without crossing an explored hexagon or $\partial D$ (in other words, this is the set of hexagons that at time $T^\delta$ have been explored or are disconnected from $b$ by the exploration path). Notice that even though time variables appear explicitly in the next two lemmas, the time parametrizations of the curves are irrelevant and do not need to be specified.

**Lemma 6.3.** With the above notation, as $\delta \to 0$, $\gamma^\delta_{D,a,b}$ and the boundary of $K^\delta_{T^\delta}$ jointly have limits in distribution along subsequences of $\delta$ with respect to the uniform metric (2) on continuous curves. Moreover, any subsequence limit of $K^\delta_{T^\delta}$ is almost surely a hull that touches $\partial^*G$ at a single point.

**Proof.** As in Lemma 6.1 the first part of this lemma is a direct consequence of [2]. The fact that the scaling limit of $K^\delta_{T^\delta}$ along any convergent subsequence $\delta_k \downarrow 0$ touches $\partial^*G$ at a single point, is a consequence of Lemma 7.1 of Section 7 below. (For any fixed $k$, the statement that $K^\delta_{T^\delta}$ touches $\partial^*G^\delta_k$ at a single point is a consequence of the definition of the stopping time $T^\delta_k$, but a priori, this could fail to be true in the limit $k \to \infty$.) Therefore, if we remove that single point, the scaling limit of the boundary of $K^\delta_{T^\delta_k}$ splits into a left and a right part (corresponding to the scaling limit of the leftmost yellow and the rightmost blue $T$-paths of hexagons explored by $\gamma^\delta_{D,a,b}$, respectively) each of which does not touch $\partial^*G$ (like in Figure 4).

Moreover, Lemmas 7.1 and 7.2 below (with $\tilde{D} = D$, $\tilde{D} = G$ and in the limit where the target region $J' = \partial^*G$ is fixed while $J \to \partial D \setminus \{a\}$) imply that if $\gamma^\delta_{D,a,b}$ has a “close encounter” with $\partial D^\delta_k$, then the fjord produced by $\gamma^\delta_{D,a,b}$ is closed nearby with probability
going to 1. Analogously, the standard bound on the probability of six crossings of an annulus [17], used repeatedly before, implies that wherever \( \gamma_{D,a,b} \) has a “close encounter” with itself, there is “touching” (see the proof of Lemma 6.1). These two observations assure that the complement of the scaling limit of \( K_{T^{\delta_k}} \) is almost surely connected, which means that the scaling limit of \( K_{T^{\delta_k}} \) has (almost surely) the properties of a filling. From the same bound on the probability of six crossings of an annulus, we can also conclude that the scaling limits of the left and right boundaries of \( K_{T^{\delta_k}} \) are almost surely simple, as in the proof of Lemma 6.1.

It is also possible to conclude that the intersection of the scaling limit of the left and right boundaries of \( K_{T^{\delta_k}} \) with the boundary of \( D \) almost surely does not contain arcs of positive length. In fact, if that were the case, one could find a subdomain \( D' \) with three points \( z_1, z_2, z_3 \) in counterclockwise order on \( \partial D' \) such that the probability that an exploration path started at \( z_1 \) and stopped when it first hits the arc \( z_2 z_3 \) of \( \partial D' \) has a positive probability, in the scaling limit, of hitting at \( z_2 \) or \( z_3 \), contradicting Cardy’s formula (which, by Theorem 3, holds for all subsequential scaling limits). Thus the scaling limit of \( K_{T^{\delta_k}} \) almost surely satisfies the condition in (7) and is therefore a hull. \( \Box \)

**Lemma 6.4.** Using the notation of Lemma 6.3, let \( \gamma_{D,a,b} \) be the limit in distribution of \( \gamma_{D,a,b}^{\delta_k} \) as \( \delta \to 0 \) along some convergent subsequence \( \{\delta_k\} \). Denote by \( T \) the first time that \( \gamma_{D,a,b} \) exits \( G \) and by \( K_T \) the filling of \( \gamma_{D,a,b}[0,T] \). Then, as \( k \to \infty \), \( (\gamma_{D,a,b}^{\delta_k}, K_{T^{\delta_k}}) \) converges in distribution to \( (\gamma_{D,a,b}, K_T) \). Moreover, \( \gamma_{D,a,b} \) satisfies the properties (i)–(iii) stated after (7) above, and its hull \( K_T \) is equidistributed with that of chordal SLE\(_6\) at the corresponding stopping time.

**Proof.** Let \( A_1^{\delta_k} \) and \( A_2^{\delta_k} \) be the two domains of \( G^{\delta_k} \backslash K_{T^{\delta_k}}^{\delta_k} \), and \( A_1 \) and \( A_2 \) the two domains of \( G \backslash K_T \) (see Figure 4). Since hulls are characterized by their “envelope” (see Lemma 5.1 and the discussion preceding it), the joint convergence in distribution of \( \{\partial A_1^{\delta_k}, \partial A_2^{\delta_k}\} \) to \( \{\partial A_1, \partial A_2\} \) would be enough to conclude that \( K_{T^{\delta_k}}^{\delta_k} \) converges to \( K_T \) as \( k \to \infty \), and in fact that \( (\gamma_{D,a,b}^{\delta_k}, K_{T^{\delta_k}}^{\delta_k}) \) converges in distribution to \( (\gamma_{D,a,b}, K_T) \).

In order to obtain the convergence of \( \{\partial A_1^{\delta_k}, \partial A_2^{\delta_k}\} \), we can use the convergence in distribution of \( \gamma_{D,a,b}^{\delta_k} \) to \( \gamma_{D,a,b} \) and apply almost the same arguments as used in the proof of Lemma 6.2. In fact, the domains \( A_1^{\delta_k}, A_2^{\delta_k} \) and \( A_1, A_2 \) are of the same type as those
treated in Lemma 6.2. We just need to extend the definitions of the domains \( D^\delta_{a,b}(z) \) and \( D_{a,b}(z) \), as at the end of Section 4 and in Lemma 6.2 (where \((D, a, b)\) was taken to be \((\mathbb{D}, -i, i)\)), to cover the case in which the domain \( D \) is replaced by a subset \( G \) of \( D \) and the target point \( b \) on the boundary of \( D \) by an arc \( \partial^* G \) of the boundary of \( G \). In our case, the subdomain \( G \) and the arc \( \partial^* G \) are defined just before Lemma 6.3.

The definitions are as before but with a deterministic target point replaced by the random hitting point at the stopping time, i.e., we define \( G^\delta_{a,\partial^* G}(z) \equiv G^\delta_{a,\gamma_{D,a,b}(T)}(z) \) and \( G_{a,\partial^* G}(z) \equiv G_{a,\gamma_{D,a,b}(T)}(z) \). \( A^\delta_i \) (resp., \( A_i \)) for \( i = 1, 2 \) is a domain of type \( G^\delta_{a,\partial^* G}(z_i) \) (resp., \( G_{a,\partial^* G}(z_i) \)) for some \( z_i \in G \). With these definitions, we need to prove the following claim.

\((C')\) For two (deterministic) points \( u, v \in G \), the probability that \( D_{a,\partial^* G}(u) = D_{a,\partial^* G}(v) \) but \( D^\delta_{a,\partial^* G}(u) \neq D^\delta_{a,\partial^* G}(v) \) or vice versa goes to zero as \( \delta \to 0 \).

The proof is the same as that of claim \((C)\) in Lemma 6.2 except that here we cannot use the bound on the probability of three crossings of an annulus centered at a boundary point because we may not have a convex domain. To replace that bound we use once again Lemmas 7.1 and 7.2 below (as in the proof of Lemma 6.3).

We have proved the convergence in distribution of \( (\gamma^\delta_{D,a,b}, K^\delta_{a,b}) \) to \( (\gamma_{D,a,b}, K_T) \). As a consequence of that and Smirnov’s result on the convergence of crossing probabilities (see Theorem 3), the hitting distribution of \( \gamma_{D,a,b} \) at the stopping time \( T \) is determined by Cardy’s formula, which allows us to apply Lemma 5.1 to conclude that \( K_T \) is equidistributed with the hull of chordal SLE\(_6\) at the corresponding stopping time.

It remains to prove (i)–(iii) stated after (7). Property (i) is immediate in our case. Properties (ii) and (iii) are consequences of Lemmas 7.1 and 7.2 and six arm estimates. □

7 Convergence of the Exploration Path

Next we show that the filling of any subsequential scaling limit of the percolation exploration process satisfies the spatial Markov property. Let us start with some notation. First, suppose that \( D \) is Jordan, with \( a \) and \( b \) distinct points on \( \partial D \), and consider a sequence \( D^\delta \) of Jordan sets from \( \delta \mathcal{H} \) such that \((D^\delta, a^\delta, b^\delta) \to (D, a, b)\), as \( \delta \to 0 \), where \((a^\delta, b^\delta) \in \partial D^\delta \) are two distinct e-vertices on \( \partial D^\delta \). This means that \((D^\delta, a^\delta, b^\delta)\) is a \( \delta \)-approximation of \((D, a, b)\). As before, denote by \( \gamma^\delta_{D,a,b} \) the percolation exploration path inside \( D^\delta \) from \( a^\delta \) to \( b^\delta \).

We can apply the results of [2] to conclude that there exist subsequences \( \delta_k \downarrow 0 \) such that the law of \( \gamma^\delta_k \equiv \gamma^\delta_{D,a,b} \) (i.e., the percolation exploration path inside \( D^\delta_k \) from \( a^\delta_k \) to \( b^\delta_k \)) converges to some limiting law for a process \( \bar{\gamma} \) supported on (Hölder) continuous curves inside \( D \) from \( a \) to \( b \). The curves are defined up to (monotonic) reparametrizations; in the next theorem and its proof, even where the time variable appears explicitly, we do not specify a parametrization since it is irrelevant. The filling \( \bar{K}_t \) of \( \bar{\gamma}[0, t] \), appearing in the next theorem, is defined just above (7).

**Theorem 4.** For any subsequential limit \( \bar{\gamma} \) of the percolation exploration path \( \gamma^\delta_{D,a,b} \) defined above, the filling \( \bar{K}_t \) of \( \bar{\gamma}[0, t] \), as a process, satisfies the spatial Markov property.
Proof. Let $\delta_k \downarrow 0$ be a subsequence such that the law of $\gamma_k^{\delta_k}$ converges to some limiting law supported on continuous curves $\tilde{\gamma}$ in $D$ from $a$ to $b$. We will prove the spatial Markov property by showing that $(\tilde{K}_{\tilde{T}_j}, \tilde{\gamma}(\tilde{T}_j))$ as defined in the proof of Theorem 2 are jointly distributed like the corresponding $SLE_6$ hull variables, which do have the spatial Markov property. Since $\gamma_k^{\delta_k}$ converges in distribution to $\tilde{\gamma}$, we can find coupled versions of $\gamma_k^{\delta_k}$ and $\tilde{\gamma}$ on some probability space $(\Omega', \mathcal{B}', \mathbb{P}')$ such that $\gamma_k^{\delta_k}$ converges to $\tilde{\gamma}$ for all $\omega' \in \Omega'$; in the rest of the proof we work with these new versions which, with a slight abuse of notation, we denote with the same names as the original ones.

Let $\tilde{f}_0$ be a conformal transformation that maps $\mathbb{H}$ to $D$ such that $\tilde{f}_0^{-1}(a) = 0$ and $\tilde{f}_0^{-1}(b) = \infty$ and let $\tilde{T}_1 = \tilde{T}_1(\varepsilon)$ denote the first time $\tilde{\gamma}(t)$ hits $D \backslash \tilde{G}_1$, with $\tilde{G}_1 \equiv \tilde{f}_0(C(0, \varepsilon))$ and (as in the proof of Lemma 6.2) $C(0, \varepsilon) = \{ z : \lvert z \rvert < \varepsilon \} \cap \mathbb{H}$. Define recursively $\tilde{T}_j+1$ as the first time $\tilde{\gamma}(t)$ hits $D_{\tilde{T}_j} \backslash \tilde{G}_{j+1}$, with $\tilde{G}_{j+1} \equiv \tilde{f}_0^{-1}(C(0, \varepsilon))$ and $D_{\tilde{T}_j} \equiv D \backslash \tilde{K}_{\tilde{T}_j}$, where $\tilde{f}_{\tilde{T}_j}$ is a conformal map from $\mathbb{H}$ to $D_{\tilde{T}_j}$ whose inverse maps $\tilde{\gamma}(\tilde{T}_j)$ to $0$ and $b$ to $\infty$, chosen as in the definition (before Theorem 2 above) of the spatial Markov property. We also define $\tau_j \equiv \tilde{T}_{j+1} - \tilde{T}_j$, so that $\tilde{T}_j = \tau_1 + \ldots + \tau_j$, and the (discrete-time) stochastic process $X_j \equiv (K_{\tilde{T}_j}, \tilde{\gamma}(\tilde{T}_j))$.

Analogous quantities can be defined for the trace of chordal $SLE_6$. For clarity, they will be indicated here by the superscript $SLE_6$; e.g., $f^{SLE_6}_{T_j}, K^{SLE_6}_{T_j}, G^{SLE_6}_{T_j}$ and $X^{SLE_6}_{T_j}$. We choose $f^{SLE_6}_0 = \tilde{f}_0$, so that $G^{SLE_6}_1 = \tilde{G}_1$.

For each $k$, let $K^k_j$ denote the filling at time $t$ of $\gamma^k_j$ (see the definition of discrete filling just before Lemma 6.3). It follows from the Markovian character of the percolation exploration process that, for all $k$, the filling $K^k_j$ satisfies a suitably adapted (to the discrete setting) spatial Markov property. (In fact, the percolation exploration path satisfies a stronger property – roughly speaking, that for all $t$ the future of the path given the filling of the past is distributed as a percolation exploration path in the original domain from which the filling up to time $t$ has been removed.)

Let now $f^k_0$ be a conformal transformation that maps $\mathbb{H}$ to $D_k \equiv D^{k}_\delta$ such that $(f^k_0)^{-1}(a_k) = 0$ and $(f^k_0)^{-1}(b_k) = \infty$ and let $T^k_1 = T^k_1(\varepsilon)$ denote the first exit time of $\gamma^k_j(t)$ from $G^k_1 \equiv f^k_0(C(0, \varepsilon))$ defined as the first time that $\gamma^k_j$ intersects the image under $f^k_0$ of the semi-circle $\{ z : \lvert z \rvert = \varepsilon \} \cap \mathbb{H}$. Define recursively $T^k_{j+1}$ as the first exit time of $\gamma^k_j(T^k_j, \infty)$ from $G^k_{j+1} \equiv f^k_0^{-1}(C(0, \varepsilon))$, where $f^k_{T^k_j}$ is a conformal map from $\mathbb{H}$ to $D_k \backslash K^k_{T^k_j}$ whose inverse maps $\gamma^k_j(T^k_j)$ to $0$ and $b_k$ to $\infty$. The maps $f^k_{T^k_j}$, for $j \geq 1$, are defined only up to a scaling factor. We also define $\tau^k_{j+1} \equiv T^k_{j+1} - T^k_j$, so that $T^k_j = \tau^k_1 + \ldots + \tau^k_j$, and the (discrete-time) stochastic process $X^k_j \equiv (K^k_{T^k_j}, \gamma^k_j(T^k_j))$ for $j = 1, 2, \ldots$. The Markovian character of the percolation exploration process implies that, for every $k$, $X^k_j$ is a Markov chain (in $j$).

We want to show recursively that, for any $j$, as $k \to \infty$, $\{X^k_1, \ldots, X^k_j\}$ converge jointly in distribution to $\{\tilde{X}_1, \ldots, \tilde{X}_j\}$. By recursively applying Theorem 3 and Lemma 5.1 we will then be able to conclude that $\{\tilde{X}_1, \ldots, \tilde{X}_j\}$ are jointly equidistributed with the corresponding $SLE_6$ hull variables (at the corresponding stopping times) $\{X^{SLE_6}_1, \ldots, X^{SLE_6}_j\}$. Since the latter do satisfy the spatial Markov property, so will the former, as desired.
The zeroth step consists in noticing that the convergence of \((D_k, a_k, b_k)\) to \((D, a, b)\) as \(k \to \infty\) allows us to use Corollary \ref{cor:boundary} to select a sequence of conformal maps \(f_{\theta_k}^k\) that converge to \(f_{\theta_0}^\infty\) uniformly in \(\mathbb{H}\) as \(k \to \infty\), which implies that the boundary \(\partial C_{\theta_k}^k\) of \(C_{\theta_k}^k = f_{\theta_k}^k(\mathbb{C}(0, \varepsilon))\) converges to the boundary \(\partial \tilde{G}_1\) of \(\tilde{G}_1 = f_{\theta_0}(\mathbb{C}(0, \varepsilon))\) in the uniform metric on continuous curves.

Starting from there, the first step of our recursion argument is organized as follows, where all limits and equalities are in distribution:

(i) \(K_{T_t^k}^k \to \tilde{K}_{T_t^1} = K_{T_t^1}^{\text{SLE}_6}\) by Lemma \ref{lem:boundary}.

(ii) \(D_k \setminus K_{T_t^k}^k \to D \setminus \tilde{K}_{T_t^1} = D \setminus K_{T_t^1}^{\text{SLE}_6}\).

(iii) \(f_{T_t^1}^k = f_{T_t^n}^k\) and by Corollary \ref{cor:boundary} of Appendix \ref{app:boundary} we can select a sequence \(f_{T_t^n}^k \to f_{T_t^n} = f_{T_t^n}^{\text{SLE}_6}\).

(iv) \(G_k^k \to G_2 = G_2^{\text{SLE}_6}\).

We remark that Lemmas \ref{lem:boundary} and \ref{lem:boundary} imply that the filling \(\tilde{K}_{T_t^1}\) is a hull, and its “envelope” is therefore composed of two simple curves. It follows that \(D \setminus \tilde{K}_{T_t^1}\) and \(\tilde{G}_2\) are admissible, since the part of the boundary of either \(D \setminus \tilde{K}_{T_t^1}\) or \(\tilde{G}_2\) that belongs to the boundary of \(\tilde{K}_{T_t^1}\) can be split up, by removing the single point \(\tilde{\gamma}(\tilde{T}_1)\), into two simple curves, while the remaining part of the boundary of either \(D \setminus \tilde{K}_{T_t^1}\) or \(\tilde{G}_2\) is a Jordan arc whose interior does not touch the hull \(\tilde{K}_{T_t^1}\). This allows us to use Theorem \ref{thm:boundary} (and therefore Lemma \ref{lem:boundary}, Corollary \ref{cor:boundary} and Lemmas \ref{lem:boundary} and \ref{lem:boundary}). (Note that \(D \setminus \tilde{K}_{T_t^1}\) and \(\tilde{G}_2\) need not be Jordan because \(\tilde{K}_{T_t^1}\) has cut-points with positive probability – see Fig. \ref{fig:boundary}).

At this point, we are in the same situation as at the zeroth step, but with \(G_{\theta_k}^k\), \(\tilde{G}_1\) and \(G_1^{\text{SLE}_6}\) replaced by \(G_2^k\), \(\tilde{G}_2\) and \(G_2^{\text{SLE}_6}\) respectively, and we can proceed by induction, as follows. (As explained above, the theorem will then follow from the fact that the \text{SLE}_6 hull variables do possess the spatial Markov property.)

The next step consists in proving that \(((K_{T_t^1}^k, \gamma_{T_t^1}^k(T_1^k)), (K_{T_t^2}^k, \gamma_{T_t^2}^k(T_2^k)))\) converges in distribution to \(((\tilde{K}_{T_t^1}, \tilde{\gamma}(\tilde{T}_1)), (\tilde{K}_{T_t^2}, \tilde{\gamma}(\tilde{T}_2)))\). Since we have already proved the convergence of \((K_{T_t^1}^k, \gamma_{T_t^1}^k(T_1^k))\) to \((\tilde{K}_{T_t^1}, \tilde{\gamma}(\tilde{T}_1))\), we claim that all we really need to prove is the convergence of \((K_{T_t^2}^k, \gamma_{T_t^2}^k(T_2^k))\) to \((\tilde{K}_{T_t^2} \setminus \tilde{K}_{T_t^1}, \tilde{\gamma}(\tilde{T}_2))\). To do this, notice that \(K_{T_t^2}^k \setminus K_{T_t^1}^k\) is distributed like the filling of a percolation exploration path inside \(D_k \setminus K_{T_t^1}^k\). Besides, the convergence in distribution of \((K_{T_t^2}^k, \gamma_{T_t^2}^k(T_2^k))\) to \((\tilde{K}_{T_t^1}, \tilde{\gamma}(\tilde{T}_1))\) implies that we can find versions of \((\gamma_{T_t^2}^k, K_{T_t^2}^k)\) and \((\tilde{\gamma}, \tilde{K}_{T_t^1})\) on some probability space \((\Omega', \mathcal{B}', \mathbb{P}')\) such that \(\gamma_{T_t^2}^k(\omega')\) converges to \(\tilde{\gamma}(\omega')\) and \((K_{T_t^2}^k, \gamma_{T_t^2}^k(T_2^k))\) converges to \((\tilde{K}_{T_t^1}, \tilde{\gamma}(\tilde{T}_1))\) for all \(\omega' \in \Omega'\). These two observations imply that, if we work with the coupled versions of \((\gamma_{T_t^2}^k, K_{T_t^2}^k)\) and \((\tilde{\gamma}, \tilde{K}_{T_t^1})\), we are in the same situation as before, but with \(D_k\) (resp., \(D\)) replaced by \(D_k \setminus K_{T_t^2}^k\) (resp., \(D \setminus \tilde{K}_{T_t^1}\)) and \(a_k\) (resp., \(a\)) by \(\gamma_{T_t^2}^k(T_2^k)\) (resp., \(\tilde{\gamma}(\tilde{T}_1)\)).
Then, the conclusion that \((K^k_{T_2} \setminus K^k_{T_1}, \gamma^d_k(T^k_2))\) converges in distribution to \((\tilde{K}_{T_2} \setminus \tilde{K}_{T_1}, \tilde{\gamma}(T_2))\) follows, as before, by arguments like those used for Lemma 6.4 – i.e., by using a standard bound on the probability of six disjoint monochromatic crossings [17] and Lemmas 7.1 and 7.2 as we now explain. \(G^k_2\) (resp., \(\tilde{G}_2\)) is a domain admissible with respect to \((\gamma^d_k(T^k_1), c'_k, d'_k)\) (resp., \((\tilde{\gamma}(T^k_1), c', d')\)), where \(c'_k\) and \(d'_k\) (resp., \(c'\) and \(d'\)) are the unique points where the image of \(\partial D \cap \mathbb{H}\) under \(f^k_{T_1}\) (resp., \(\tilde{f}_{T_1}\)) meets either the envelope of \(K^k_{T_1}\) (resp., \(\tilde{K}_{T_1}\)) or \(\partial D_k\) (resp., \(\partial D\)) – see Figure 5. The envelope of the filling \(K^k_{T_1}\) (resp., \(\tilde{K}_{T_1}\)) is part of the boundary of the domain explored by \(\gamma^d_k[T^k_1, T^k_2]\) (resp., \(\tilde{\gamma}[\tilde{T}_1, \tilde{T}_2]\)). Close encounters of \(\gamma^d_k[T^k_1, T^k_2]\) (resp., \(\tilde{\gamma}[\tilde{T}_1, \tilde{T}_2]\)) with this part of the boundary can be dealt with using again a standard bound [17] on the probability of six disjoint monochromatic crossings, as explained in the proofs of Lemmas 6.1-6.2 (see also [3]). If part of the boundary of \(G^k_2\) (resp., \(\tilde{G}_2\)) coincides with part of \(\partial D_k\) (resp., \(\partial D\)), we can use Lemmas 7.1 and 7.2 as in Lemmas 6.3 and 6.4, to obtain the same conclusions. Notice that Lemmas 7.1 and 7.2 are adapted to the situation we encounter here, with the boundary of the exploration domain divided in three parts (corresponding here to the envelope of the past filling, part of the boundary of the original domain, and the semi-circle conformally mapped from the upper half-plane – see Figures 5 and 6).

![Figure 5: Schematic figure representing a hull (shaded) with a cut-point e, resulting in a non-Jordan, but admissible, \(\tilde{G}_2\).](image)

We can now iterate the above arguments \(j\) times, for any \(j > 1\). It is in fact easy to see by induction that the domains \(D \setminus \tilde{K}_{T_j}\) and \(\tilde{G}_j\) that appear in the successive steps are admissible for all \(j\). Therefore we can keep using Theorem 3 (and Lemma 5.1), Corollary A.2 and Lemmas 7.1 and 7.2. If we keep track at each step of the previous ones, this provides the joint convergence of all the curves and fillings involved at each step, and concludes the proof of Theorem 4.

**Remark 7.1.** The key technical problem in proving Theorem 4 is showing that for the exploration path \(\gamma^d_k\), one can interchange the limit \(\delta_k \to 0\) with the process of filling. This
requires showing two things about the exploration path: (1) the return of a (macroscopic) segment of the path close to an earlier segment (and away from \( \partial D_k \)) without nearby (microscopic) touching does not occur (probably), and (2) the close approach of a (macroscopic) segment to \( \partial D_k \) without nearby (microscopic) touching either of \( \partial D_k \) itself or else of another segment that touches \( \partial D_k \) does not occur (probably). In the related proof of Lemma 6.3 where \( D \) was just the unit disk, these were controlled by known estimates on probabilities of six-arm events in the full plane for (1) and of three-arm events in the half-plane for (2). When \( D \) is not necessarily convex, as in Theorem 4, the three-arm event argument for (2) appears to break down. Our replacement is the use of Lemmas 7.1-7.4. Basically, these control (2) by a novel argument about “mushroom events” on \( \partial D \) (see Lemma 7.4), which is based on continuity of Cardy’s formula with respect to changes in \( \partial D \).

The situation described in the next lemma is depicted in Figure 6 and corresponds to those in the proof of Theorem 1 and in Lemmas 6.3-6.4. In the next lemmas and their proofs, when we write that a percolation exploration path in \( \partial D \) touches itself we mean that it gets to distance \( \delta \) of itself, just one hexagon away.

**Lemma 7.1.** Let \( \{ (\hat{D}_k, a_k, c_k, c'_k, d'_k, d_k) \} \) be a sequence of Jordan domains with five points (not necessarily all distinct) on their boundaries in counterclockwise order. Assume that \( \hat{D}_k \subset D_k \), where \( D_k \) is a Jordan set from \( \delta_k \mathcal{H} \), that \( a_k, c_k, c'_k, d'_k, d_k \in \partial D_k \), that the counterclockwise arcs \( \hat{d}_k c'_k \) of \( \hat{D}_k \) and \( D_k \) coincide, and that \( a_k \) is an e-vertex of \( \partial D_k \).

Consider a second e-vertex \( b_k \in \partial D_k, b_k \notin \partial \hat{D}_k \), and denote by \( \gamma_k^\delta \) the percolation exploration path in \( D_k \) started at \( a_k \), aimed at \( b_k \), and stopped when it first hits the counterclockwise arc \( J'_k = \bar{c'_k d'_k} \) of \( \partial D_k \). Assume that, as \( k \to \infty, \delta_k \to 0 \) and \( (\hat{D}_k, a_k, c_k, d_k) \to (\hat{D}, a, c, d), (D_k, a_k, c_k, d_k) \to (D, a, c, d), \) where \( \hat{D} \) and \( D \) are domains admissible with respect to \( (a, c, d) \). Also assume that \( J'_k \) converges in the metric \( \| \cdot \| \) to the counterclockwise arc \( J' = \bar{c d} \) of \( \partial \hat{D} \), a subset of the counterclockwise arc \( J = \bar{c d} \) of \( \partial D \), and that \( b_k \to b \in \partial \hat{D}, b \notin \partial D \).

Let \( E_k(J_k; \varepsilon, \varepsilon') = \left\{ \bigcup_{v \in \mathcal{J}_k \setminus J'_k} B_k(v; \varepsilon, \varepsilon') \right\} \cup \left\{ \bigcup_{v \in \mathcal{J}_k} A_k(v; \varepsilon, \varepsilon') \right\} \), where \( A_k(v; \varepsilon, \varepsilon') \) is the event that \( \gamma_k^\delta \) contains a segment that stays within \( B(v, \varepsilon) \) and has a double crossing of the annulus \( B(v, \varepsilon) \setminus B(v, \varepsilon') \) without that segment touching \( \partial \hat{D}_k \), and \( B_k(v; \varepsilon, \varepsilon') \) is the event that \( \gamma_k^\delta \) enters \( B(v, \varepsilon') \), but is stopped outside \( B(v, \varepsilon) \) and does not touch \( \partial \hat{D}_k \cap B(v, \varepsilon) \).

Then, for any \( \varepsilon > 0 \),

\[
\lim_{\varepsilon' \to 0} \limsup_{k \to \infty} \mathbb{P}(E_k(J_k; \varepsilon, \varepsilon')) = 0. \tag{14}
\]

Our next result is a lemma in which the part of Lemma 7.1 concerning \( J \setminus J' \) can be strengthened to conclude that if \( \hat{\gamma} \) touches \( J \setminus J' \) somewhere, then for \( k \) large enough, \( \gamma_k^\delta \) touches either \( J_k \setminus J'_k \) or its past hull “nearby.” Lemmas 7.1 and 7.2 are used in the proof of Theorem 4 to show that in the limit there is no discrepancy between the hull generated by \( \hat{\gamma} \) and the limit as \( k \to \infty \) of the hull generated by \( \gamma_k^\delta \).

**Lemma 7.2.** With the notation of Lemma 7.1, let \( C_k(v; \varepsilon, \varepsilon') \) be the event that \( \gamma_k^\delta \) contains a segment that stays within \( B(v, \varepsilon) \) and has a double crossing of the annulus \( B(v, \varepsilon) \setminus \)
Figure 6: Schematic figure representing the situation described in Lemma 7.1. Note that the shaded region is not part of the domains $\tilde{D}$ and $\hat{D}$ and that $\tilde{D}$ contains $\hat{D}$. In the application to Theorem 4, the shaded region represents the hull of the past (which may have cut-points, as in Figure 5) and the counterclockwise arc $c'd'$ of $\partial \hat{D}$ represents the conformal image of a semicircle. Notice that $c$ and $c'$ (resp., $d$ and $d'$) coincide if the right (resp., left) endpoint of the conformal image of the semicircle lies on the boundary of the shaded region (see, e.g., Figure 5). In the application to Lemmas 6.3-6.4, $D = \tilde{D}$, $G = \hat{D}$ and $\partial^* G$ corresponds to the counterclockwise arc $c'd'$ of $\partial D$.

$B(v, \varepsilon')$ without that segment touching either $\partial \hat{D}_k$ or any other segment of the $\gamma^k$ that stays within $B(v, \varepsilon)$ and touches $\partial \hat{D}_k$. Then, for any $\varepsilon > 0$,

$$\lim_{\varepsilon' \rightarrow 0} \limsup_{k \rightarrow \infty} P\left( \bigcup_{v \in \mathcal{J}_k \setminus \mathcal{J}'_k} C_k(v; \varepsilon, \varepsilon') \right) = 0.$$  \hspace{1cm} (15)

The proofs of Lemmas 7.1 and 7.2 are partly based on relating the failure of (14) or (15) to the occurrence with strictly positive probability of certain continuum limit “mushroom” events (see Lemma 7.4) that we will show must have zero probability because otherwise there would be a contradiction to Lemma 7.3, which itself is a consequence of the continuity of Cardy’s formula with respect to the domain boundary (see Lemma A.2 of Appendix A). In both of the next two lemmas, we denote by $\mu$ any subsequence limit as $\delta = \delta_k \rightarrow 0$ of the probability measures for the collection of all colored (blue and yellow) $\mathcal{T}$-paths on all of $\mathbb{R}^2$, in the Aizenman-Burchard sense (see Remark 3.1). We recall that in our notation, $D$ represents an open domain and $z_1 z_2, z_3 z_4$ represent closed segments of its boundary. In Lemma 7.3 below, we restrict attention to a Jordan domain $D$ since that case suffices for the use of Lemma 7.3 in the proofs of Lemmas 7.1 and 7.2.

**Lemma 7.3.** For $(D, z_1, z_2, z_3, z_4)$, with $D$ a Jordan domain, consider the following crossing events, $C_i^* = C_i^*(D, z_1, z_2, z_3, z_4)$, where $*$ denotes either blue or yellow, a $*$ path denotes a segment of a $*$ curve, and $i = 1, 2, 3$:

$$C_1^* = \{ \exists \text{ a } * \text{ path in the closure } \overline{D} \text{ from } z_1 z_2 \text{ to } z_3 z_4 \},$$

$$C_2^* = \{ \exists \text{ a } * \text{ path in } D \text{ from the interior of } z_1 z_2 \text{ to the interior of } z_3 z_4 \},$$

$$C_3^* = \{ \exists \text{ a } * \text{ path in } D \text{ from the closure of } z_1 z_2 \text{ to the closure of } z_3 z_4 \},$$

$$C_4^* = \{ \exists \text{ a } * \text{ path in } D \text{ from the interior of } z_1 z_2 \text{ to the interior of } z_3 z_4 \},$$

$$C_5^* = \{ \exists \text{ a } * \text{ path in the closure of } D \text{ from the closure of } z_1 z_2 \text{ to the closure of } z_3 z_4 \},$$

$$C_6^* = \{ \exists \text{ a } * \text{ path in } \overline{D} \text{ from the interior of } z_1 z_2 \text{ to the interior of } z_3 z_4 \}.$$
\[ C_3^* = \{ \exists \text{ a } \ast \text{ path starting and ending outside } \overline{D} \text{ whose restriction to } D \text{ is as in } C_2^* \} \]

Then \( \mu(C_3^*) = \mu(C_2^*) = \mu(C_1^*) = \Phi_D(z_1, z_2; z_3, z_4). \)

**Proof.** Recall that convergence to \( \mu \) implies a coupling of the lattice and continuum processes on some \( (\Omega', \mathcal{B}', \mathbb{P}') \) such that the distance between the set of \( \mathcal{T}_\varepsilon \)-paths and the set of continuum paths tends to zero as \( \delta_k \to 0 \) for all \( \omega' \in \Omega' \) (see, e.g., Corollary 1 of [6]).

We will construct for each small \( \varepsilon > 0 \), two domains with boundary points, denoted by \( (\tilde{D}, \tilde{z}_1, \tilde{z}_2, \tilde{z}_3, \tilde{z}_4) \) and \( (\bar{D}, \bar{z}_1, \bar{z}_2, \bar{z}_3, \bar{z}_4) \), approximating \( (D, z_1, z_2, z_3, z_4) \) in such a way that \( \tilde{\Phi}_\varepsilon \equiv \tilde{\Phi}_D(\tilde{z}_1, \tilde{z}_2; \tilde{z}_3, \tilde{z}_4) \xrightarrow{\varepsilon \to 0} \Phi \equiv \Phi_D(z_1, z_2; z_3, z_4) \) and the same for \( \bar{\Phi}_\varepsilon \), and with the property that \( \tilde{\Phi}_\varepsilon \leq \mu(C_1^*) \leq \bar{\Phi}_\varepsilon \) for \( i = 1, 2, 3 \). This will yield the desired result. The construction of the approximating domains uses fairly straightforward conformal mapping arguments. We provide details for \( \tilde{D} \); the construction of \( \bar{D} \) is analogous.

To construct \( \tilde{D} \) we will need continuous simple loops, \( \tilde{E}(D, \varepsilon) \) and \( \tilde{E}(D, \varepsilon) \), that are inner and outer approximations to \( \partial D \) in the sense that \( \tilde{E} \) is surrounded by \( \partial D \) which is surrounded by \( \tilde{E} \) with

\[ d(\partial D, \tilde{E}) \leq \varepsilon, \quad d(\partial D, \tilde{E}) \leq \varepsilon. \] (16)

We will also need four simple curves \{\tilde{\partial}_1, \tilde{\partial}_2, \tilde{\partial}_3, \tilde{\partial}_4\} in the interior of the (topological) annulus between \( \tilde{E} \) and \( \tilde{E} \) and connecting their endpoints \{(\tilde{z}_1, \tilde{z}_1), (\tilde{z}_2, \tilde{z}_2), (\tilde{z}_3, \tilde{z}_3), (\tilde{z}_4, \tilde{z}_4)\} \) on \( \tilde{E} \) and \( \tilde{E} \) with each touching \( \partial D \) at exactly one point which is either in the interior of the counterclockwise segment \( \tilde{z}_1 \tilde{z}_2 \) (for \( \tilde{\partial}_1 \) and \( \tilde{\partial}_2 \)) or else the counterclockwise segment \( \tilde{z}_3 \tilde{z}_4 \) (for \( \tilde{\partial}_3 \) and \( \tilde{\partial}_4 \)). Furthermore each of these connecting curves is close to its corresponding point \( z_1, z_2, z_3, \) or \( z_4 \); i.e., \( d(\tilde{\partial}_1, z_1) \leq \varepsilon \), etc. In the special case where \( D \) is a rectangle, the construction of \( \tilde{E}, \tilde{E}, \tilde{D} \) (and \( \bar{D} \)) is easily done — see Figure 7.

![Figure 7: Here, the middle rectangle is the domain D while the boundaries of the two rectangles outside and inside D are \( \tilde{E} \) and \( \tilde{E} \) respectively. \( \tilde{D} \) is the domain with a dashed boundary.](image)

Returning to a general Jordan domain \( D \), we will take \( \tilde{z}_1 = \bar{z}_1, \tilde{z}_2 = \bar{z}_2, \tilde{z}_3 = \bar{z}_3, \) and \( \tilde{z}_4 = \bar{z}_4 \) with \( \partial \tilde{D} \) the concatenation of: \( \tilde{\partial}_1 \) from \( \tilde{z}_1 \) to \( \bar{z}_1 \), the portion of \( \tilde{E} \) from \( \bar{z}_1 \) to \( \tilde{z}_2 \) counterclockwise, \( \tilde{\partial}_2 \) from \( \tilde{z}_2 \) to \( \bar{z}_2 \), the portion of \( \tilde{E} \) from \( \bar{z}_2 \) to \( \tilde{z}_3 \) counterclockwise, \( \tilde{\partial}_3 \) from \( \tilde{z}_3 \) to \( \bar{z}_3 \), the portion of \( \tilde{E} \) from \( \bar{z}_3 \) to \( \tilde{z}_4 \) counterclockwise, \( \tilde{\partial}_4 \) from \( \tilde{z}_4 \) to \( \bar{z}_4 \), and the portion of \( \tilde{E} \) from \( \bar{z}_4 \) to \( \tilde{z}_1 \) counterclockwise. It is important that (for fixed \( \varepsilon \) and \( \tilde{D} \)) there
is a strictly positive minimal distance between $E \cup \overline{E}$ and $\partial D$, and between $\partial \tilde{D}$ and the union of the two counterclockwise segments $\overline{z_2 z_3}$ and $\overline{z_4 z_1}$ of $\partial D$ (see Figure 7). These features will guarantee that for fixed $\varepsilon$, once $k$ is large enough, a $\delta_k$-lattice crossing within $\tilde{D}$ that corresponds to the crossing event whose (limiting) probability is $\Phi_{\tilde{D}}(\tilde{z}_1, \tilde{z}_2; \tilde{z}_3, \tilde{z}_4)$ must have a subsegment that satisfies the conditions defining $C^*_i$ (in $D$).

We construct the parts of $\partial \tilde{D}$ that are inside and outside $\partial D$ separately and then paste them together (with some care to make sure that they “match up”). Let $\phi$ be the conformal map from $D$ onto $\tilde{D}$ with $\phi(0) = 0$ and $\phi'(0) > 0$, and consider the image $\phi(\partial D_{1-\varepsilon'})$ of the circle $\partial D_{1-\varepsilon'} = \{ z : |z| = 1 - \varepsilon' \}$ under $\phi$ and the inverse images $z_1^*, z_2^*, z_3^*, z_4^*$ under $\phi^{-1}$ of $z_1, z_2, z_3, z_4$. Let $\partial_i^*(\varepsilon', \varepsilon_1)$ be the straight line between $e^{-i\varepsilon_1} z_1$ on the unit circle $\partial D$, and $(1 - \varepsilon') e^{-i\varepsilon_1} z_1$ on the circle $\partial D_{1-\varepsilon'}$, and define $\partial_2^*, \partial_3^*$, and $\partial_4^*$ similarly, but using clockwise rotations by $e^{+i\varepsilon_2}$ and $e^{+i\varepsilon_4}$ for $z_2$ and $z_4$ (see Figure 8). $\phi(\partial D_{1-\varepsilon'})$ is a candidate for $E(D, \varepsilon)$ and $\phi(\partial_i^*(\varepsilon', \varepsilon_1))$ is a candidate for half of $\partial_i$ (where $i = 1$ or 2 or 3 or 4), so we must choose $\varepsilon'$ and the $\varepsilon_i$’s small enough so that $d(\partial D, \phi(\partial D_{1-\varepsilon'})) \leq \varepsilon$, $d(\phi(\partial_i^*(\varepsilon', \varepsilon_1)), z_1) \leq \varepsilon$, etc. We do an analogous construction using a conformal mapping from the exterior of $D$ onto the exterior of $\tilde{D}$, to obtain candidates for $\overline{E}(D, \varepsilon)$ and for the exterior half of the $\partial_i$’s. Finally we use the freedom to choose the exterior values for $\varepsilon'$ and the $\varepsilon_i$’s differently from the interior ones to make sure that the interior and exterior halves of the $\varepsilon_i$’s match up.

It should be clear that for a given approximation $\partial \tilde{D}$ of $\partial D$ constructed as described above there is a strictly positive $\tilde{\varepsilon}$ such that the distance between $\partial D$ and the portions of $\partial \tilde{D}$ that belong to $E$ and $\overline{E}$ is not smaller than $\tilde{\varepsilon}$, and the distance between the union $\overline{\overline{z_2 z_3} \cup \overline{z_4 z_1}}$ of two counterclockwise segments of $\partial D$ and $\partial_1 \cup \partial_2 \cup \partial_3 \cup \partial_4$ is also not smaller than $\tilde{\varepsilon}$. This implies (see the definition of blue crossing just before Theorem 1) that for $k$ large enough, any (lattice) blue path crossing inside $\tilde{D}$ from the counterclockwise segment $\overline{z_1 z_2}$ of $\partial \tilde{D}$ to the counterclockwise segment $\overline{z_3 z_4}$ of $\partial \tilde{D}$ (and thanks to the coupling, any limiting continuum counterpart) must (with high probability) have a subpath that satisfies

![Figure 8](image-url)
the conditions of $C_i^\ast$. Thus, for $i = 1, 2, 3$,

$$
\mu(C_i^\ast) \geq \lim_{k \to \infty} \hat{\Phi}_{\bar{d}_k}^{\ast} = \hat{\Phi}_\varepsilon
$$

(17)
as desired (the equality uses Theorem 11 for the Jordan domain $\hat{D}(\varepsilon)$).

We now note that as $\varepsilon \to 0$, $(\hat{D}, \hat{z}_1, \hat{z}_2, \hat{z}_3) \to (D, z_1, z_2, z_3, z_4)$. This allows us to use the continuity of Cardy’s formula (Lemma A.2 in Appendix A) to obtain

$$
\lim_{\varepsilon \to 0} \hat{\Phi}_\varepsilon = \Phi.
$$

(18)

From this and (17) it follows that for $i = 1, 2, 3$,

$$
\mu(C_i^\ast) \geq \Phi.
$$

(19)

The remaining part of the proof involves defining a domain $\hat{D}$ analogous to $\hat{D}$ (i.e., such that $\lim_{\varepsilon \to 0} \lim_{k \to \infty} \hat{\Phi}_{\bar{d}_k}^{\ast} = \Phi$) but with the property that any blue $\delta_k$-lattice path crossing inside $D$ from the counterclockwise segment $\overline{z_1z_2}$ to the counterclockwise segment $\overline{z_3z_4}$ of $\partial D$ must have a subpath in $\hat{D}$ that crosses between the counterclockwise segment $\overline{z_1z_2}$ and the counterclockwise segment $\overline{z_3z_4}$ of $\partial \hat{D}$. (The details of the construction of $\hat{D}$ are analogous to those of $\hat{D}$; we leave them to the reader.) Then, for $i = 1, 2, 3$,

$$
\mu(C_i^\ast) \leq \Phi,
$$

(20)

which, combined with (19), implies $\mu(C_i^\ast) = \Phi$ and concludes the proof. \(\blacksquare\)

**Lemma 7.4.** For $(\hat{D}, a, c, d)$ as in Lemma 7.1, $v \in J \equiv \overline{cd}$, and $\varepsilon > 0$, we define $U_{\text{yellow}}(\hat{D}, \varepsilon, v)$, the yellow “mushroom” event (at $v$), to be the event that there is a yellow path in the closure of $\hat{D}$ from $v$ to $\partial B(v, \varepsilon)$ and a blue path in the closure of $\hat{D}$, between some pair of distinct points $v_1, v_2$ in $\partial \hat{D} \cap \{B(v, \varepsilon/3) \setminus B(v, \varepsilon/8)\}$, that passes through $v$ and such that this blue path is between $\partial \hat{D}$ and the yellow path (see Figure 3). We similarly define $U_{\text{blue}}(\hat{D}, \varepsilon, v)$ with the colors interchanged and $U^\ast(\hat{D}, \varepsilon, J) = \cup_{v \in J} U^\ast(\hat{D}, \varepsilon, v)$ where $\ast$ denotes blue or yellow. Then for any deterministic domain $\hat{D}$ and any $0 < \varepsilon < \min\{|a-c|, |a-d|\}$, $\mu(U^\ast(\hat{D}, \varepsilon, J)) = 0$.

**Proof.** If $\mu(U^\ast(\hat{D}, \varepsilon, J)) > 0$ for some $\varepsilon > 0$, then there is some segment $\overline{z_1z_2} \subset J$ of $\partial \hat{D}$ of diameter not larger than $\varepsilon/10$ such that

$$
\mu(\cup_{v \in \overline{z_1z_2}} U^\ast(\hat{D}, \varepsilon, v)) > 0.
$$

(21)

Choose any point $v_0 \in \overline{z_1z_2}$ and consider the new domain $D'$ whose boundary consists of the correctly chosen (as we explain below) segment of the circle $\partial B(v_0, \varepsilon/2)$ between the two points $z_3, z_4$ where $\partial \hat{D}$ first hits $\partial B(v_0, \varepsilon/2)$ on either side of $v_0$, together with the segment from $z_4$ to $z_3$ of $\partial \hat{D}$ (see Figure 10). The correct circle segment between $z_3$ and $z_4$ is the (counter)clockwise one if $v_0$ comes after $z_4$ and before $z_3$ along $\partial \hat{D}$ when $\partial \hat{D}$ is
oriented (counter)clockwise. It is also not hard to see that since \( \varepsilon < \min \{ |a - c|, |a - d| \} \), \( D' \) is a Jordan domain, so that Lemma 7.3 can be applied. In the new domain \( D' \), \( z_1 z_2 \) is the same curve segment as it was in the old domain \( \hat{D} \), but \( z_3 z_4 \) is now a segment of the circle \( \partial B(v_0, \varepsilon/2) \). It should be clear that

\[
\bigcup_{v \in \mathbb{Z}^d} U^*(\hat{D}, \varepsilon, v) \subset C_1^*(D', z_1, z_2, z_3, z_4) \setminus C_3^*(D', z_1, z_2, z_3, z_4)
\]

which yields a contradiction of Lemma 7.3 if \( \mu(U^*(\hat{D}, \varepsilon, J)) > 0 \). \( \square \)

**Proof of Lemma 7.1** Let us first consider the simpler case of \( A_k(v; \varepsilon, \varepsilon') \) in which \( v \in J'_k \). For \( \varepsilon > 0 \), let \( J'_k(\varepsilon) \equiv J'_k \setminus \{ B(c'_k, \varepsilon) \cup B(d'_k, \varepsilon) \} \) and \( \hat{D}_k(\varepsilon) \equiv \hat{D}_k \setminus \{ B(c'_k, \varepsilon) \cup B(d'_k, \varepsilon) \} \). With this notation, we have

\[
\mathbb{P}\left( \bigcup_{v \in J'_k} A_k(v; \varepsilon, \varepsilon') \right) \leq \mathbb{P}\left( \bigcup_{v \in J'_k(\varepsilon)} A_k(v; \varepsilon, \varepsilon') \right) + F(\varepsilon; \hat{D}_k, c'_k, d'_k),
\]

(23)
where $F_\varepsilon(\hat{D}_k, c'_k, d'_k)$ is the probability that $\gamma^k_\varepsilon$ enters $B(c'_k, \varepsilon)$ or $B(d'_k, \varepsilon)$ before touching $J'_k$. $F_\varepsilon(\hat{D}_k, c'_k, d'_k)$ can be expressed as the sum of two crossing probabilities in $\hat{D}_k(\varepsilon)$:

1. the probability of a blue crossing from the (portion of the) counterclockwise arc $\partial B$ to the “first exposed” arc of $B(d', \varepsilon)$ contained in $\hat{D}_k(\varepsilon)$ and

2. the analogous probability of a yellow crossing from the (portion of the) counterclockwise arc $\partial B$ to the “first exposed” arc of $B(c', \varepsilon)$ contained in $\hat{D}_k(\varepsilon)$. Since crossing probabilities converge to Cardy’s formula, we easily conclude that

$$\lim_{\varepsilon \to 0} \lim_{k \to \infty} F((\varepsilon; \hat{D}_k, c'_k, d'_k)) = 0.$$ \hspace{1cm} \text{(24)}$$

Noting that the probability in the left hand side of (23) is nonincreasing in $\varepsilon$, we see that in order to obtain

$$\lim_{\varepsilon' \to 0} \lim_{k \to \infty} \mathbb{P}(\bigcup_{v \in J'_k} \mathcal{A}_k(v; \varepsilon, \varepsilon')) = 0,$$ \hspace{1cm} \text{(25)}$$ it is enough to show that the limit as $\varepsilon \to 0$ of the left hand side of (25) is zero. Therefore, thanks to (23) and (24), it suffices to prove that for every $\varepsilon > 0$

$$\lim_{\varepsilon' \to 0} \lim_{k \to \infty} \mathbb{P}(\bigcup_{v \in J'_k(\varepsilon)} \mathcal{A}_k(v; \varepsilon, \varepsilon')) = 0.$$ \hspace{1cm} \text{(26)}$$

To do so, we follow the exploration process until time $T$, when it first touches $\partial B(v, \varepsilon')$ for some $v \in J'_k(\varepsilon)$, and consider the annulus $B(v, \varepsilon) \setminus B(v, \varepsilon')$. Let $\pi_Y$ be the leftmost yellow $\mathcal{T}$-path and $\pi_B$ the rightmost blue $\mathcal{T}$-path in $\Gamma(\gamma^k_\varepsilon)$ at time $T$ that cross $B(v, \varepsilon) \setminus B(v, \varepsilon')$. $\pi_Y$ and $\pi_B$ split the annulus $B(v, \varepsilon) \setminus B(v, \varepsilon')$ into three sectors that, for simplicity, we will call the central sector, containing the crossing segment of the exploration path, the yellow (left) sector, with $\pi_Y$ as part of its boundary, and the blue (right) sector, the remaining one, with $\pi_B$ as part of its boundary.

We then look for a yellow “lateral” crossing within the yellow sector from $\pi_Y$ to $\partial \hat{D}_k$ and a blue lateral crossing within the blue sector from $\pi_B$ to $\partial \hat{D}_k$. Notice that the yellow sector may contain “excursions” of the exploration path coming off $\partial B(v, \varepsilon)$, producing nested yellow and blue excursions off $\partial B(v, \varepsilon)$, and the same for the blue sector. But for topological reasons, those excursions are such that for every group of nested excursions, the outermost one is always yellow in the yellow sector and blue in the blue sector. Therefore, by standard percolation theory arguments, the conditional probability (conditioned on $\Gamma(\gamma^k_\varepsilon)$ at time $T$) to find a yellow lateral crossing of the yellow sector from $\pi_Y$ to $\partial \hat{D}_k$ is bounded below by the probability to find a yellow circuit in an annulus with inner radius $\varepsilon'$ and outer radius $\varepsilon$. An analogous statement holds for the conditional probability (conditioned on $\Gamma(\gamma^k_\varepsilon)$ at time $T$ and on the entire percolation configuration in the yellow sector) to find a blue lateral crossing of the blue sector from $\pi_B$ to $\partial \hat{D}_k$. Thus for any fixed $\varepsilon > 0$, by the Russo-Seymour-Welsh lemma [26,30], the conditional probability to find both a yellow lateral crossing within the yellow sector from $\pi_Y$ to $\partial \hat{D}_k$ and a blue lateral crossing within the blue sector from $\pi_B$ to $\partial \hat{D}_k$ goes to one as $\varepsilon' \to 0$.

But if such yellow and blue crossings are present, the exploration path is forced to touch $J'_k$ before exiting $B(v, \varepsilon)$, and if that happens, the exploration process is stopped,
so that it will never exit \( B(v, \varepsilon) \) and the union over \( v \in J'_k(\varepsilon) \) of \( A_k(v; \varepsilon, \varepsilon') \) cannot occur. This concludes the proof of this case.

Let us now consider the remaining case in which \( v \notin J'_k \). The basic idea of the proof is then that by straightforward weak convergence and related coupling arguments, the failure of (14) would imply that some subsequence limit \( \mu \) would satisfy \( \mu(U_{\text{yellow}}(D, \varepsilon, J) \cup U_{\text{blue}}(D, \varepsilon, J)) > 0 \), which would contradict Lemma 7.4. This is essentially because the close approach of an exploration path on the \( \delta_k \)-lattice to \( J_k \setminus J'_k \) without quickly touching nearby yields one two-sided colored \( T \)-path (the “perimeter” of the portion of the hull of the exploration path seen from a boundary point of close approach) and a one-sided \( T \)-path of the other color belonging to the percolation cluster not seen from the boundary point (i.e., shielded by the two-sided path). Both the two-sided path and the one-sided one are subsets of \( \Gamma(\gamma^k_{\delta_k}) \).

We first note that since the probability in (14) is nonincreasing in \( \varepsilon \), we may assume that \( \varepsilon < \min\{|a - c|, |a - d|\} \), as requested by Lemma 7.4. Assume by contradiction that (14) is false, so that close encounters without touching happen with bounded away from zero probability. Consider for concreteness an exploration path \( \gamma^k_{\delta_k} \) that has a close approach to a point \( v \) in the counterclockwise arc \( d'_k d_k \). The exploration path may have multiple close approaches to \( v \) with differing colors of the perimeter as seen from \( v \), but for topological reasons, the last time the exploration path comes close to \( v \), it must do so in such a way as to produce a yellow \( T \)-path \( \pi_Y \) (seen from \( v \)) that crosses \( B(v, \varepsilon) \setminus B(v, \varepsilon') \) twice, and a blue path \( \pi_B \) that crosses it once (see Figure 11). This is so because the exploration process that produced \( \gamma^k_{\delta_k} \) ended somewhere on \( J'_k \) (and outside \( B(v, \varepsilon) \)), which is to the right of (i.e., clockwise to) \( v \).

![Figure 11: The event consisting of a yellow double crossing and a blue crossing used as a first step for obtaining a blue mushroom event in the proof of Lemma 7.1. The dashed crossing is blue and the dotted crossing is yellow.](image)

The portion of \( \pi_Y \) inside \( B(v, \varepsilon) \setminus B(v, \varepsilon') \) contains at least two yellow \( T \)-paths crossing the annulus. We denote by \( \pi_L \) the leftmost (looking at \( v \) from inside \( \hat{D}_k \)) such path and denote by \( \pi_R \) the rightmost one. The paths \( \pi_L \) and \( \pi_R \) split \( B(v, \varepsilon) \setminus B(v, \varepsilon') \) into three
sectors, that we will call the central sector, containing \( \pi_B \), the left sector, with \( \pi_L \) as part of its boundary, and the right sector, with \( \pi_R \) as part of its boundary. Again for topological reasons, all other monochromatic crossings of the annulus associated with \( \gamma_k^\delta \) are contained in the central sector, including at least one blue path \( \pi_B \). As in the previous case, the left and right sectors can contain nested monochromat ic excursions off \( \partial B(v, \varepsilon) \) (and in this case also excursions off \( \partial B(v, \varepsilon') \)), but this time for every group of excursions, the outermost one is yellow in both sectors.

Now consider the annulus \( B(v, \varepsilon/3) \setminus B(v, \varepsilon/3) \). We look for a yellow lateral crossing within the left sector from \( \pi_L \) to \( \partial \mathcal{D}_k \) and a yellow lateral crossing within the right sector from \( \pi_R \) to \( \partial \mathcal{D}_k \). Since the outermost excursions in both sectors are yellow, the conditional probability to find a yellow lateral crossing within the left sector from \( \pi_L \) to \( \partial \mathcal{D}_k \) is bounded below by the probability to find a yellow circuit in an annulus with inner radius \( \varepsilon/8 \) and outer radius \( \varepsilon/3 \), and an analogous statement holds for the conditional probability to find a yellow lateral crossing within the right sector from \( \pi_R \) to \( \partial \mathcal{D}_k \). Thus for any fixed \( \varepsilon > 0 \), by an application of the Russo-Seymour-Welsh lemma [26, 30], the conditional probability to find both yellow lateral crossings remains bounded away from zero as \( k \to \infty \) and \( \varepsilon' \to 0 \). But the presence of such yellow crossings would produce a (blue) mushroom event, leading to a contradiction with Lemma 7.4. □

**Proof of Lemma 7.2.** First of all, notice that

\[
\bigcup_{v \in J_k \setminus J_k'} B_k(v; \varepsilon, \varepsilon') \subset \bigcup_{v \in J_k \setminus J_k'} C_k(v; \varepsilon, \varepsilon') \subset \bigcup_{v \in J_k \setminus J_k'} A_k(v; \varepsilon, \varepsilon').
\]  

(27)

By lemma 7.1, we only need consider events in \( \bigcup_{v \in J_k \setminus J_k'} \{ C_k(v; \varepsilon, \varepsilon') \ \setminus B_k(v; \varepsilon, \varepsilon') \} \), since

\[
\lim_{\varepsilon' \to 0} \limsup_{k \to \infty} \mathbb{P}(\bigcup_{v \in J_k \setminus J_k'} B_k(v; \varepsilon, \varepsilon')) = 0.
\]  

(28)

These are events such that \( \gamma_k^\delta \) touches \( \partial \mathcal{D}_k \) inside \( B(v, \varepsilon) \), but it also contains a segment that stays within \( B(v, \varepsilon) \), does not touch \( \partial \mathcal{D}_k \) (or any segment that touches \( \partial \mathcal{D}_k \) inside \( B(v, \varepsilon) \)), and has a double crossing of the annulus \( B(v, \varepsilon) \setminus B(v, \varepsilon') \).

Let us assume by contradiction that, for some fixed \( \hat{\varepsilon} > 0 \),

\[
\limsup_{\varepsilon' \to 0} \limsup_{k \to \infty} \mathbb{P}(\bigcup_{v \in J_k \setminus J_k'} C_k(v; \hat{\varepsilon}, \varepsilon')) > 0.
\]  

(29)

This implies (by using a coupling argument) that we can find a subsequence \( \{n\} \) of \( \{k\} \) and sequences \( \delta_n \to 0 \) and \( \varepsilon_n \to 0 \) such that (with strictly positive probability), as \( n \to \infty \), \( \gamma_n^\delta \) converges to a curve \( \hat{\gamma} \) that, for some \( \hat{v} \in \partial \mathcal{D} \) (in fact, in \( J \setminus J' \)), contains a segment that stays in \( B(\hat{v}, \hat{\varepsilon}) \), touches \( \partial \mathcal{D} \) at \( \hat{v} \), and makes a double crossing of \( B(\hat{v}, \hat{\varepsilon}) \setminus \{\hat{v}\} \). Since the events that we are considering are in \( \bigcup_{v \in J_n \setminus J_n'} \{ A_n(v; \hat{\varepsilon}, \varepsilon_n) \ \setminus B_n(v; \hat{\varepsilon}, \varepsilon_n) \} \), before the limit \( n \to \infty \) is taken, \( \gamma_n^\delta \) has a segment that stays in \( B(\hat{v}, \hat{\varepsilon}) \), does not touch \( \partial \mathcal{D}_n \) and
makes a double crossing of the annulus \( B(\tilde{v}_n, \hat{\varepsilon}) \setminus B(\tilde{v}_n, \varepsilon_n) \) for some \( \tilde{v}_n \in \partial \hat{D}_n \) converging to \( \tilde{v} \). Moreover, \( \gamma_\delta^m \) must touch \( \partial \hat{D}_n \) inside \( B(\tilde{v}_n, \hat{\varepsilon}) \).

Consider first whether there exist \( 0 < \tilde{\varepsilon} < \hat{\varepsilon} \) and \( n_0 < \infty \) such that the point \( v_n \), closest to \( \tilde{v}_n \), where \( \gamma_\delta^m \) touches \( \partial \hat{D}_n \) inside \( B(\tilde{v}_n, \hat{\varepsilon}) \) is outside \( B(\tilde{v}, \tilde{\varepsilon}) \) for all \( n \geq n_0 \). If this occurred with strictly positive probability, it would imply that for all \( \varepsilon < \tilde{\varepsilon} \),

\[
\limsup_{n \to \infty} \mathbb{P}( \bigcup_{v \in J_n \setminus J'_n} B_n(v; \varepsilon, \varepsilon_n)) > 0, \tag{30}
\]

which would contradict (14).

This leaves the case in which the point \( v_n \), closest to \( \tilde{v}_n \), where \( \gamma_\delta^m \) touches \( \partial \hat{D}_n \) inside \( B(\tilde{v}_n, \hat{\varepsilon}) \) converges to \( \tilde{v} \) (with strictly positive probability). Our assumption (29) implies that, as \( n \to \infty \), the segment of \( \gamma_\delta^m \) that stays in \( B(\tilde{v}_n, \hat{\varepsilon}) \) and gets to within distance \( \varepsilon_n \) of \( \partial \hat{D}_n \) without touching it, also does not touch the segment of \( \gamma_\delta^m \) contained in \( B(\tilde{v}_n, \hat{\varepsilon}) \) that touches \( \partial \hat{D}_n \) at \( v_n \). In that case, one can choose a subsequence \( \{m\} \) of \( \{n\} \) such that, for all \( m \) large enough, \( |\tilde{v}_m - v_m| \leq \varepsilon_m \) and there are five disjoint monochromatic crossings, not all of the same color, of the annulus \( B(\tilde{v}_m, \hat{\varepsilon}/2) \setminus B(\tilde{v}_m, \varepsilon_m) \). Three crossings of alternating colors are associated with the segment of \( \gamma_\delta^m \) contained in \( B(\tilde{v}_m, \hat{\varepsilon}/2) \) which does not touch \( \partial \hat{D}_m \) and makes a double crossing of the annulus \( B(\tilde{v}_m, \hat{\varepsilon}/2) \setminus B(\tilde{v}_m, \varepsilon_m) \), while two more crossings are associated with another segment which does touch \( \partial \hat{D}_m \) and makes either a single or a double crossing of the annulus (see Figures 12, 13 and 14). This assures that \( \gamma_\delta^m \) can have yet another segment that crosses the annulus \( B(\tilde{v}_m, \hat{\varepsilon}/2) \setminus B(\tilde{v}_m, \varepsilon_m) \) (which would add at least one more disjoint monochromatic crossing to the existing five) for at most finitely many \( m \)'s, since otherwise the standard six-arm bound proved in [17] would be violated. Therefore, we can choose \( 0 < \varepsilon < \hat{\varepsilon}/2 \) such that for all \( m \) large enough, \( \gamma_\delta^m \) has at most two segments that stay in \( B(\tilde{v}_m, \varepsilon) \) and cross \( B(\tilde{v}_m, \varepsilon) \setminus B(\tilde{v}_m, \varepsilon_m) \), one of which does not touch \( \partial D_m \) and makes a double crossing, while the other touches \( \partial D_m \).

![Figure 12](image-url)
Since \( \{m\} \) is a subsequence of \( \{k\} \), it follows from (29) that

\[
\limsup_{m \to \infty} \mathbb{P}(\bigcup_{v \in J_m \setminus J'_m} C_m(v; \bar{\varepsilon}, \varepsilon_m)) > 0.
\] (31)

When the event \( C_m(v; \bar{\varepsilon}, \varepsilon_m) \) happens, it follows from the above observations that \( \gamma^\delta_m \) cannot touch \( \partial \hat{D}_m \) inside \( B(\hat{v}_m, \bar{\varepsilon}) \) both before and after the segment that makes a double crossing of \( B(\hat{v}_m, \varepsilon) \setminus B(\hat{v}_m, \varepsilon_m) \) without touching \( \partial \hat{D}_m \). We will assume that, following the exploration path \( \gamma^\delta_m \) from \( a_m \) to the target region \( J'_m \), with positive probability \( v_m \) is encountered after the segment that makes a double crossing of \( B(\hat{v}_m, \varepsilon) \setminus B(\hat{v}_m, \varepsilon_m) \) without touching \( \partial \hat{D}_m \). To see that this assumption can be made without loss of generality, we note that we may consider the case where the target area \( J'_m \) is a single point \( b_m \) and then
consider the “time-reversed” exploration path in \( \hat{D}_m \) that starts at \( b_m \) and ends at \( a_m \).

Now let \( \gamma_{b_m}^m(t) \) be a parametrization of the exploration path \( \gamma_{a_m}^m \) from \( a_m \) to \( J_m \) and consider the stopping time \( T \) (where the dependence on \( m \) has been suppressed) defined as the first time such that there is a point \( v \) on \( J_m \) with the property that \( \gamma_{b_m}^m \) up to time \( T \) has never touched \( \partial \hat{D}_m \cap B(v, \varepsilon) \) and has a segment that makes a double crossing of \( B(v, \varepsilon) \setminus B(v, \varepsilon_m) \). It follows from (31) and the observation and assumption made right after it that such a \( T \) occurs with probability bounded away from zero as \( m \to \infty \).

If this is the case, we can use the partial percolation configuration produced inside \( B(v, \varepsilon) \setminus B(v, \varepsilon_m) \) by the exploration process stopped at the stopping time \( T \) to construct a mushroom event with positive probability, as in the proof of Lemma 7.1. Notice, in fact, that the partial percolation configuration produced inside \( B(v, \varepsilon) \setminus B(v, \varepsilon_m) \) by the exploration process stopped at time \( T \) has exactly the same properties as the partial percolation configuration of the proof of Lemma 7.1 produced by the exploration process considered there inside the annulus \( B(v, \varepsilon) \setminus B(v, \varepsilon') \) – see the second part of the proof of Lemma 7.1. It follows that (31) implies positive probability of a mushroom event, contradicting Lemma 7.4.

We are finally ready to prove the main result.

**Theorem 5.** Let \((D, a, b)\) be a Jordan domain with two distinct selected points on its boundary \( \partial D \). Then, for Jordan sets \( D^\delta \) from \( \delta \mathcal{H} \) with two distinct selected e-vertices \( a^\delta, b^\delta \) on their boundaries \( \partial D^\delta \), such that \((D^\delta, a^\delta, b^\delta) \to (D, a, b)\) as \( \delta \to 0 \), the percolation exploration path \( \gamma_{D,a,b}^\delta \) inside \( D^\delta \) from \( a^\delta \) to \( b^\delta \) converges in distribution to the trace \( \gamma_{D,a,b} \) of chordal SLE\(_6\) inside \( D \) from \( a \) to \( b \), as \( \delta \to 0 \).

**Proof.** It follows from [2] that \( \gamma_{D,a,b}^\delta \) converges in distribution along subsequence limits \( \delta_k \downarrow 0 \). Since we have proved that the filling of any such subsequence limit \( \gamma \) satisfies the spatial Markov property (Theorem 1) and the hitting distribution of \( \gamma \) is determined by Cardy’s formula (Theorem 3), we can deduce from Theorem 2 that the limit is unique and that the law of \( \gamma_{D,a,b}^\delta \) converges, as \( \delta \to 0 \), to the law of the trace \( \gamma_{D,a,b} \) of chordal SLE\(_6\) inside \( D \) from \( a \) to \( b \).

**Appendix A: Sequences of Conformal Maps**

In this appendix, we give some results about sequences of conformal maps. A standard reference with more details is [24]. There is a theorem attributed to both Courant [13] (see Theorem IX.14 of [35]) and to Rado [25] (see Theorem 2.11 of [24]) that provides conditions under which conformal maps \( \phi_n \) from \( \mathbb{D} \) onto Jordan domains \( G_n \) converge uniformly on all of \( \overline{\mathbb{D}} \). One of the purposes of this appendix is to provide in Corollary A.1 an extension of the Courant-Rado theorem to admissible domains (which are not necessarily Jordan — see the definition in Section 4.1). Although this suffices here, it appears that there is a wider extension (S. Rohde, private communication) in which the domains \( G_n \) have boundaries given by continuous loops, without requiring admissibility.
To proceed, we need the next definition, in which a **continuum** denotes a compact connected set with more than one point.

**Definition A.1.** (Sect. 2.2 of [24]) The closed set $A \subset \mathbb{C}$ is called **locally connected** if for every $\varepsilon > 0$ there is $\delta > 0$ such that, for any two points $a, b \in A$ with $|a - b| < \delta$, we can find a continuum $B$ with diameter smaller than $\varepsilon$ and with $a, b \in B \subset A$.

We remark that every continuous curve (with more than one point) is a locally connected continuum (the converse is also true: every locally connected continuum is a curve). The concept of local connectedness gives a topological answer to the problem of continuous extension of a conformal map to the domain boundary, as follows.

**Theorem 6.** (Sect. 2.1 of [24]) Let $\phi$ map the unit disk $D$ conformally onto $G \subset \mathbb{C} \cup \{\infty\}$. Then $\phi$ has a continuous extension to $D$ if and only if $\partial G$ is locally connected.

When $\phi$ has a continuous extension to $\overline{D}$, we do not distinguish between $\phi$ and its extension. This is the case for the conformal maps considered in this paper. The problem of whether this extension is injective on $D$ has also a topological answer, as follows.

**Theorem 7.** (Sect. 2.1 of [24]) In the notation of Theorem 6, the function $\phi$ has a continuous and injective extension if and only if $\partial G$ is a Jordan curve.

When considering sequences of domains whose boundaries are locally connected the following definition is useful.

**Definition A.2.** (Sect. 2.2 of [24]) The closed sets $A_n \subset \mathbb{C}$ are **uniformly locally connected** if, for every $\varepsilon > 0$, there exists $\delta > 0$ independent of $n$ such that any two points $a_n, b_n \in A_n$ with $|a_n - b_n| < \delta$ can be joined by continua $B_n \subset A_n$ of diameter smaller than $\varepsilon$.

The convergence of domains used in this paper (i.e., $G_n \to G$ if $\partial G_n \to \partial G$ in the uniform metric [24] on continuous curves) allows us to use Carathéodory’s kernel convergence theorem (Theorem 1.8 of [24]). However, we need uniform convergence in $\overline{D}$. This is guaranteed by the Courant-Radó theorem in the case of Jordan domains; in the non-Jordan case, sufficient conditions to have uniform convergence are stated in the next theorem.

**Theorem 8.** (Corollary 2.4 of [24]) Let $\{G_n\}$ be a sequence of bounded domains such that, for some $0 < r < R < \infty$, $B(0, r) \subset G_n \subset B(0, R)$ for all $n$ and such that $\{\mathbb{C} \setminus G_n\}$ is uniformly locally connected. Let $\phi_n$ map $D$ conformally onto $G_n$ with $\phi_n(0) = 0$. If $\phi_n(z) \to \phi(z)$ as $n \to \infty$ for each $z \in D$, then the convergence is uniform in $D$.

To use Theorem 8 we need the following lemma. The definition of admissible and the related notion of convergence are given respectively in Sect. 4.1 and in Theorem 3.

**Lemma A.1.** Let $\{(G_n, a_n, c_n, d_n)\}$ be a sequence of domains admissible with respect to $(a_n, c_n, d_n)$ and assume that, as $n \to \infty$, $(G_n, a_n, c_n, d_n) \to (G, a, c, d)$, where $G$ is a domain admissible with respect to $(a, c, d)$. Then the sequence of closed sets $\{\mathbb{C} \setminus G_n\}$ is uniformly locally connected.
Proof. If the conclusion of the theorem is not valid, then for some \( \varepsilon > 0 \), there are indices \( k \) (actually \( n_k \), but we abuse notation a bit) and points \( u_k, v_k \in \mathbb{C} \setminus G_k \) with \( |u_k - v_k| \to 0 \) that cannot be joined by a continuum of diameter \( \leq \varepsilon \) in \( \mathbb{C} \setminus G_k \). We assume this and search for a contradiction. By compactness, we may also assume that \( u_k \to u, v_k \to v \), with \( u = v \). There is an easy contradiction (using a small disc around \( u = v \) as the connecting continuum) unless \( u = v \) is on \( \partial G \), and so we also assume that. Further, by considering points on \( \partial G_k \) near to \( u_k, v_k \), we can also assume that \( u_k, v_k \in \partial G_k \).

Splitting \( \partial G \) into three Jordan arcs, \( J_1 = \overline{da}, J_2 = \overline{ac}, J_3 = \overline{cd} \), and \( \partial G_k \) into the corresponding \( J_{1,k}, J_{2,k}, J_{3,k} \), we note that there is an easy contradiction (using arcs along \( \partial G_k \) as the continua) if \( u_k \) and \( v_k \) both belong to \( J_{1,k} \cup J_{3,k} \) or both belong to \( J_{2,k} \cup J_{3,k} \) for all \( k \) large enough, since the concatenation of \( J_{1,k} \) with \( J_{3,k} \) or of \( J_{2,k} \) with \( J_{3,k} \) is a Jordan arc. The above reasoning does not apply if \( u = v \) is on both \( J_1 \) and \( J_2 \). But when \( u = v = a \), one can paste together small Jordan arcs on \( J_{1,k} \) and \( J_{2,k} \) to get a suitable continuum leading again to a contradiction. The sole remaining case is when, for all \( k \) large enough, \( u_k \) belongs to the interior of \( J_{1,k} \) and \( v_k \) belongs to the interior of \( J_{2,k} \).

(Notice that we are ignoring the “degenerate” case in which \( c = d \) coincides with the “last” [from \( a \)] double-point on \( \partial G \), and \( J_3 \) is a simple loop. In that case \( u_k \) and \( v_k \) could converge to \( u = v = c = d \in J_1 \cap J_2 \) and \( u_k \) or \( v_k \) could still belong to \( J_{3,k} \) for arbitrarily large \( k \)’s. However, in that case one can find two distinct points on \( J_3 \), \( c’ \) and \( d’ \), such that \( D \) is admissible with respect to \((a, c’, d’)\), and points \( c_k’ \) and \( d_k’ \) on \( J_{3,k} \) converging to \( c’ \) and \( d’ \) respectively, and define accordingly new Jordan arcs, \( J_1’, J_2’, J_3’ \) and \( J_{1,k}’, J_{2,k}’, J_{3,k}’ \), so that \( u_k \in J_{1,k}’ \) and \( v_k \in J_{2,k}’ \) for \( k \) large enough. We assume that this has been done if necessary, and for simplicity of notation drop the primes.)

In this case let \([u_k, v_k]\) denote the closed straight line segment in the plane between \( u_k \) and \( v_k \). Imagine that \([u_k, v_k]\) is oriented from \( u_k \) to \( v_k \) and let \( v_k’ \) be the first point of \( J_{2,k} \) intersected by \([u_k, v_k]\) and \( u_k’ \) be the previous intersection of \([u_k, v_k]\) with \( \partial G_k \). Clearly, \( u_k’ \notin J_{2,k} \). For \( k \) large enough, \( u_k’ \) cannot belong to \( J_{3,k} \) either, or otherwise in the limit \( k \to \infty \), \( J_3 \) would touch the interior of \( J_1 \) and \( J_2 \). We deduce that for all \( k \) large enough, \( u_k’ \in J_{1,k} \). Since \( J_{1,k} \) and \( J_{2,k} \) are continuous curves and therefore locally connected, \( u_k \) and \( u_k’ \) belong to a continuum \( B_{1,k} \) contained in \( J_{1,k} \) whose diameter goes to zero as \( k \to \infty \), and the same for \( v_k \) and \( v_k’ \) (with \( B_{1,k} \) and \( J_{1,k} \) replaced by \( B_{2,k} \) and \( J_{2,k} \)).

Since the interior of \([u_k’v_k’]\) does not intersect any portion of \( \partial G_k \), it is either contained in \( G_k \) or in its complement \( \mathbb{C} \setminus G_k \). If \([u_k’v_k’] \subset \mathbb{C} \setminus G_k \), we have a contradiction since the union of \([u_k’v_k’]\) with \( B_{1,k} \) and \( B_{2,k} \) is contained in \( \mathbb{C} \setminus G_k \) and is a continuum containing \( u_k \) and \( v_k \) whose diameter goes to zero as \( k \to \infty \).

If the interior of \([u_k’v_k’]\) is contained in \( G_k \), let us consider a conformal map \( \phi_k \) from \( \mathbb{D} \) onto \( G_k \). Since \( \partial G_k \) is locally connected, the conformal map \( \phi_k \) extends continuously to the boundary of the unit disc. Let \( u_k’ = \phi_k(u_k), v_k’ = \phi_k(v_k), a_k = \phi_k(a_k^*), c_k = \phi_k(c_k^*) \) and \( d_k = \phi_k(d_k^*) \). The points \( c_k^*, d_k^*, u_k^*, v_k^* \) are in counterclockwise order on \( \partial \mathbb{D} \), so that any curve in \( \mathbb{D} \) from \( a_k^* \) to \( c_k^* \) to the counterclockwise arch \( c_k^*d_k^* \) must cross the curve from \( u_k^* \) to \( v_k^* \) whose image under \( \phi_k \) is \([u_k’v_k’]\). This implies that any curve in \( G_k \) going from \( a_k \) to the counterclockwise arc \( c_kd_k \) of \( \partial G_k \) must cross the (interior of the) line segment \([u_k’v_k’]\).

Then, in the limit \( k \to \infty \), any curve in \( G \) from \( a \) to the counterclockwise arc \( cd \) must
contain the limit point \( u = \lim_{k \to \infty} u_k' = \lim_{k \to \infty} v_k' = v \). On the other hand, except for its starting and ending point, any such curve is completely contained in \( G \), which implies that either \( u = v = a \) or else that (in the limit \( k \to \infty \)) the counterclockwise arc \( cd \) is the single point at \( u = v = c = d \). We have already dealt with the former case. In the latter case, one can paste together small Jordan arcs from \( u_k' \) to \( d_k \), from \( d_k \) to \( c_k \), and from \( c_k \) to \( v_k' \), and take the union with \( B_{1,k} \) and \( B_{2,k} \) (defined above) to get a suitable continuum in \( \mathbb{C} \setminus G_k \) containing \( u_k \) and \( v_k \), leading to a contradiction. This concludes the proof. \( \square \)

Theorem 8 together with Carathéodory’s kernel convergence theorem (Theorem 1.8 of [24]) and Lemma A.1 implies the following result.

**Corollary A.1.** With the notation and assumptions of Lemma A.1 (and also assuming that \( G_n \) and \( G \) contain the origin), let \( \phi_n \) map \( \mathbb{D} \) conformally onto \( G_n \) with \( \phi_n(0) = 0 \) and \( \phi_n'(0) > 0 \), and \( \phi \) map \( \mathbb{D} \) conformally onto \( G \) with \( \phi(0) = 0 \) and \( \phi'(0) > 0 \). Then, as \( n \to \infty \), \( \phi_n \to \phi \) uniformly in \( \mathbb{D} \).

**Proof.** As already remarked, the convergence of \( \partial G_n \) to \( \partial G \) in the uniform metric (2) on continuous curves (which is part of the definition of \( (G_n, a_n, c_n, d_n) \to (G, a, c, d) \)) easily implies that the conditions in Carathéodory’s kernel theorem (Theorem 8.1 of [24]) are satisfied and therefore that \( \phi_n \) converges to \( \phi \) locally uniformly in \( \mathbb{D} \), as \( n \to \infty \). By an application of Lemma A.1, the sequence \( \{ \mathbb{C} \setminus D_n \} \) is uniformly locally connected, so that we can apply Theorem 8 to conclude that, as \( n \to \infty \), \( \phi_n \) converges to \( \phi \) uniformly in \( \overline{\mathbb{D}} \). \( \square \)

The next result is a corollary of the previous one and is used in the proof of Theorem 4.

**Corollary A.2.** Let \( \{(G_n, a_n, c_n, d_n)\} \) be a sequence of domains admissible with respect to \( (a_n, c_n, d_n) \) with \( b_n \) in the interior of \( c_n d_n \), and assume that, as \( n \to \infty \), \( (G_n, a_n, c_n, d_n) \to (G, a, c, d) \) and \( b_n \to b \), where \( G \) is a domain admissible with respect to \( (a, c, d) \) and \( b \) is in the interior of \( \overline{cd} \). Let \( f \) be a conformal map from \( \mathbb{H} \) to \( G \) such that \( f^{-1}(a) = 0 \) and \( f^{-1}(b) = \infty \). Then, there exists a sequence \( \{ f_n \} \) of conformal maps from \( \mathbb{H} \) to \( G_n \) with \( f_n^{-1}(a_n) = 0 \) and \( f_n^{-1}(b_n) = \infty \) and such that \( f_n \) converges to \( f \) uniformly in \( \overline{\mathbb{H}} \).

**Proof.** The conformal transformation \( f(\cdot) \) can be written as \( \phi \circ \psi(\lambda \cdot) \), where \( \lambda \) is a positive constant, \( \phi \) is the unique conformal transformation that maps \( \mathbb{D} \) onto \( G \) with \( \phi(0) = 0 \) and \( \phi'(0) > 0 \) (we are assuming for simplicity that \( G \) contains the origin; if that is not the case, one can use a translated domain that does contain the origin), and

\[
\psi(z) = e^{i\theta_0} \frac{(z + 1) - z_0}{(z + 1) - \overline{z_0}} \tag{32}
\]

maps \( \mathbb{H} \) onto \( \overline{\mathbb{D}} \). \( \theta_0 \) is chosen so that \( e^{i\theta_0} = \phi^{-1}(b) \) and \( z_0 \) so that \( |1 - z_0| = 1 \), \( \text{Im}(z_0) > 0 \) and \( \phi^{-1}(b)(1 + z_0) = \phi^{-1}(a) \), which implies that \( f^{-1} \) indeed maps \( a \) to \( 0 \) and \( b \) to \( \infty \).

We now take \( f_n(\cdot) \) of the form \( \phi_n \circ \psi_n(\lambda \cdot) \), where \( \phi_n \) is the unique conformal transformation that maps \( \mathbb{D} \) onto \( G_n \) with \( \phi_n(0) = 0 \) and \( \phi'_n(0) > 0 \) (the assumption that \( G \)
contains the origin implies that \(G_n\) also contains the origin, for large \(n\), and

\[
\psi_n(z) = e^{i\theta_n} \frac{(z + 1) - z_n}{(z + 1) - \bar{z}_n}
\]

maps \(\mathbb{H}\) onto \(\overline{D}\). Note that the same \(\lambda\) is used as appeared in the expression \(\phi \circ \psi(\lambda)\) for \(f(\cdot)\). \(\theta_n\) is chosen so that \(e^{i\theta_n} = \phi_n^{-1}(b_n)\) and \(z_n\) is chosen so that \(|1 - z_n| = 1, \text{Im}(z_n) > 0\) and \(\phi_n^{-1}(b_n)(\frac{1 - z_n}{1 - \bar{z}_n}) = \phi_n^{-1}(a_n)\), which implies that \(f_n^{-1}\) indeed maps \(a_n\) to 0 and \(b_n\) to \(\infty\).

Corollary [A.1] implies that, as \(n \to \infty\), \(\phi_n\) converges to \(\phi\) uniformly in \(\overline{D}\). This, together with the convergence of \(a_n\) to \(a\) and \(b_n\) to \(b\), implies that \(\phi_n^{-1}(a_n)\) converges to \(\phi^{-1}(a)\) and \(\phi_n^{-1}(b_n)\) to \(\phi^{-1}(b)\). Therefore, we also have the convergence of \(\psi_n\) to \(\psi\) uniformly in \(\mathbb{H}\), which implies that \(f_n\) converges to \(f\) uniformly in \(\mathbb{H}\). \(\Box\)

We conclude this appendix with a simple lemma, used in the proof of Theorem 3, about the continuity of Cardy’s formula with respect to the shape of the domain and the positions of the four points on the boundary.

**Lemma A.2.** For \([[D_n, a_n, c_n, b_n, d_n]]\) and \(\{D, a, c, b, d\}\) as in Theorem 3, let \(\Phi_n\) denote Cardy’s formula (see (3)) for a crossing inside \(D_n\) from the counterclockwise segment \(a_n c_n\) of \(\partial D_n\) to the counterclockwise segment \(b_n d_n\) of \(\partial D_n\) and \(\Phi\) the corresponding Cardy’s formula for the limiting domain \(D\). Then, as \(n \to \infty\), \(\Phi_n \to \Phi\).

**Proof.** Let \(\phi_n\) be the conformal map that takes \(\mathbb{D}\) onto \(D_n\) with \(\phi_n(0) = 0\) and \(\phi_n'(0) > 0\), and let \(\phi\) denote the conformal map from \(\mathbb{D}\) onto \(D\) with \(\phi(0) = 0\) and \(\phi'(0) > 0\); let \(z_1 = \phi^{-1}(a)\), \(z_2 = \phi^{-1}(c)\), \(z_3 = \phi^{-1}(b)\), \(z_4 = \phi^{-1}(d)\), \(z_1^n = \phi_n^{-1}(a_n)\), \(z_2^n = \phi_n^{-1}(c_n)\), \(z_3^n = \phi_n^{-1}(b_n)\), and \(z_4^n = \phi_n^{-1}(d_n)\). We can apply Corollary [A.1] to conclude that, as \(n \to \infty\), \(\phi_n\) converges to \(\phi\) uniformly in \(\overline{D}\). This, in turn, implies that, as \(n \to \infty\), \(z_1^n \to z_1\), \(z_2^n \to z_2\), \(z_3^n \to z_3\) and \(z_4^n \to z_4\).

Cardy’s formula for a crossing inside \(D_n\) from the counterclockwise segment \(a_n c_n\) of \(\partial D_n\) to the counterclockwise segment \(b_n d_n\) of \(\partial D_n\) is given by

\[
\Phi_n = \frac{\Gamma(2/3)}{\Gamma(4/3)\Gamma(1/3)} \eta_n^{1/3} 2F_1(1/3, 2/3; 4/3; \eta_n),
\]

where

\[
\eta_n = \frac{(z_1^n - z_2^n)(z_3^n - z_4^n)}{(z_1^n - z_3^n)(z_2^n - z_4^n)}.
\]

Because of the continuity of \(\eta_n\) in \(z_1^n, z_2^n, z_3^n, z_4^n\), and the continuity of Cardy’s formula (34) in \(\eta_n\), the convergence of \(z_1^n \to z_1\), \(z_2^n \to z_2\), \(z_3^n \to z_3\) and \(z_4^n \to z_4\) immediately implies the convergence of \(\Phi_n\) to \(\Phi\). \(\Box\)

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