ACCELERATED FINITE DIFFERENCE SCHEMES FOR LINEAR STOCHASTIC PARTIAL DIFFERENTIAL EQUATIONS IN THE WHOLE SPACE

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Abstract. We give sufficient conditions under which the convergence of finite difference approximations in the space variable of the solution to the Cauchy problem for linear stochastic PDEs of parabolic type can be accelerated to any given order of convergence by Richardson’s method.

1. Introduction

Stochastic partial differential equations (SPDEs) play important roles in many applied fields. Here we consider linear second order nondegenerate parabolic SPDEs. These equations arise, for example, in nonlinear filtering of partially observable diffusion processes. There are various methods developed in the literature to solve them numerically. In this paper we apply the method of finite differences in the space variable, while the time variable changes continuously. It is known that in general the error of the finite difference approximations in the space variable is proportional to the parameter $h$ of the finite difference, see, e.g., [22] or [23]. Our aim is to show that the convergence of these approximations can be accelerated by an implementation of Richardson’s idea to SPDEs. We prove that for linear parabolic stochastic PDEs driven by Wiener processes the finite difference approximations $u^h$ admit power series expansions in the parameter $h$. This is Theorem 2.2, one of the main results of the paper. Hence we get Theorem 2.4, our first result on acceleration of finite difference schemes for SPDEs. It says that if the coefficients and the data are sufficiently regular then the convergence of finite difference approximations can be accelerated to any high order by taking appropriate mixture of approximations with different step sizes. In the special case of symmetric finite difference schemes, Example 2.2 below, the coefficients of odd powers in the expansions vanish. Hence it follows, see Theorem 2.5, that the error of symmetric finite difference schemes is proportional to $h^2$ without acceleration, and we can accelerate more effectively.

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The SPDEs we consider in this paper are given in \([0, T] \times \mathbb{R}^d\). The finite difference schemes are given in \([0, T] \times G_h\), where \(G_h\) are grids in the space variable. The supremum in \(t \in [0, T]\) and \(x \in G_h\) of the remainder terms and of the approximation errors in the expansions in Theorem 2.2 and Theorems 2.4-2.5, respectively are estimated. To prove these results we consider the finite difference schemes given not only on the grids, but on the whole \(\mathbb{R}^d\), and obtain a more general theorem, Theorem 4.1, that establishes a power expansion in \(h\) for the \(L_2\)-solutions of the schemes on \([0, T] \times \mathbb{R}^d\), with the remainder estimated in terms of Sobolev norms in the whole \(\mathbb{R}^d\). Hence we estimate the sup norm and also discrete Sobolev norms of the remainder by Sobolev’s embedding theorems, and get our theorems on accelerated finite difference schemes, formulated in terms of supremum norm and also in discrete Sobolev norms of functions over \(G_h\).

In the special case when the stochastic terms in the equations vanish the above mentioned theorems are results on accelerated finite difference schemes for deterministic PDEs. Similar results on monotone finite difference schemes for parabolic and elliptic PDEs, which may degenerate, are proved in [9] on the basis of derivative estimates on the supremum norm obtained in [7]-[8] for solutions to monotone finite difference schemes. The finite difference schemes in the present article are not necessarily monotone.

The idea of accelerating the convergence of finite difference approximations to deterministic PDEs by suitable mixtures of approximations with different step-sizes is due to L.F. Richardson, see [18] and [19]. This method is often called Richardson’s method or extrapolation to the limit, and is applied to various types of approximations. It is used in [5]-[6] to accelerate splitting up approximations for a large class of deterministic evolution equations, including second order parabolic equations and symmetric hyperbolic system of first order PDEs. Richardson’s idea is implemented to the law of Euler’s approximations for stochastic differential equations in [21], [1] and [15]. There is a lot of other applications of Richardson’s method. The reader is referred to the survey papers [2] and [4] for a review on the method, and to textbooks (for instance, [16] and [17]) concerning finite difference methods and their accelerations. We note that previous extrapolation results for stochastic equations, i.e. in [21], and in its generalizations [15] and [12], are concerned with weak approximations of stochastic differential equations. In contrast our main results are error expansions for strong convergence of finite difference approximations in the space variable for stochastic parabolic equations, and as far as we know these are the first results in this direction.

In light of the results of the present paper it is natural to look for accelerated space and time discretized schemes, say by using time discretization to solve the systems of ordinary stochastic equations which we obtain after discretizing the space. However, one knows that if the values of the driving multidimensional Wiener process are available only at the grid points, then in general one cannot construct a scheme with (strong) rate of convergence better than \(\sqrt{\tau}\), where \(\tau\) is the mesh-size of the time grid. On
the other hand, in some particular cases, e.g., when the Wiener process is one-dimensional, or some special data, like iterated stochastic integrals of the components of the Wiener processes are available, then one can have accelerated fully discretised numerical schemes for SPDEs. (See, e.g., [11] for high order strong approximations of stochastic differential equations when appropriate iterated stochastic integrals of the Wiener processes are used in the numerical schemes.)

We did not try to make our results as sharp or as general as possible. The main goal of the article is to show a method of approximating. We plan to extend our results to the case of degenerate parabolic SPDEs in the continuation of this paper.

In conclusion we introduce some notation used everywhere below. Throughout the paper \( \mathbb{R}^d \) is a Euclidean space of points \( x = (x^1, \ldots, x^d) \), and \( T > 0 \) is a fixed finite constant. We set

\[
D_i = \partial / \partial x^i, \quad i = 1, \ldots, d.
\]

Also let \( D_0 \) be the unit operator.

Let \( (\Omega, \mathcal{F}, P) \) be a complete probability space, \( \mathcal{F}_t, t \geq 0, \) be an increasing filtration of sub \( \sigma \)-fields of \( \mathcal{F} \), such that \( \mathcal{F}_0 \) is complete with respect to \( (\mathcal{F}, P) \). By \( \mathcal{P} \) we denote the \( \sigma \)-field of predictable subsets of \( \Omega \times [0, \infty) \) generated by \( \mathcal{F}_t \), and \( \mathcal{B}(\mathbb{R}^d) \) is the \( \sigma \)-algebra of the Borel subsets of \( \mathbb{R}^d \). We assume that on \( \Omega \) we are given a sequence of \( \mathcal{F}_t \)-adapted independent Wiener processes \( \{w^\rho\}_{\rho=1}^\infty \) such that for every integer \( \rho \geq 1 \) and for all \( 0 \leq s \leq t \) the increments \( w^\rho_t - w^\rho_s \) are independent of \( \mathcal{F}_s \). Unless otherwise stated throughout the paper we use the summation convention over repeated integer valued indices. For functions \( u = u(\omega, t, x), \omega \in \Omega, t \in [0, T], x \in \mathbb{R}^d, \) we use the notation \( D^l u = D^l u(x) \) for the collection of \( l \)th order derivatives of \( u \) with respect to \( x \) and \( |D^l u|^2 = |D^l u(x)|^2 \) is the sum of squares of all \( l \)th order derivatives at \( x \). If \( u \) is an \( l_2 \)-valued function then the differentiability of it is understood in the sense of \( l_2 \)-valued functions and \( |D^l u(x)|^2 \) means the the sum of squares of the \( l_2 \)-norm of all \( l \)th order derivatives at \( x \). For basic notions and notation concerning the theory of linear stochastic partial differential equations we refer to [20].

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2. Formulation of the main results

We consider the equation
$$du_t = (\mathcal{L}_t u_t + f_t) dt + (\mathcal{M}_t^\rho u_t + g_t^\rho) dw_t^\rho,$$

for \((t,x) \in [0,T] \times \mathbb{R}^d =: H_T\) with some initial condition where

\[ \mathcal{L}_t \phi = a_t^{\alpha \beta} D_\alpha D_\beta \phi, \quad \mathcal{M}_t^\rho \phi = b_t^{\alpha \rho} D_\alpha \phi, \]

and \(\{w^\rho\}_{\rho=1}^\infty\) is a sequence of independent Wiener processes given on a probability space \((\Omega, \mathcal{F}, P)\) equipped with a filtration \((\mathcal{F}_t)_{t \geq 0}\) such that \(w_t^\rho\) is \(\mathcal{F}_t\)-measurable and \(w_t^\rho - w_s^\rho\) is independent of \(\mathcal{F}_s\) for all \(0 \leq s \leq t\) and integers \(\rho \geq 1\). Here and below the summation with respect to \(\alpha\) and \(\beta\) is performed over the set \(\{0,1,...,d\}\) and with respect to \(\rho\) in the range \(\{1,2,...\}\). Assume that, for \(\alpha, \beta \in \{0,1,...,d\}\), we have \(a_t^{\alpha \beta} = a_t^{\beta \alpha}\) and \(a_t^{\alpha \beta} = a_t^{\alpha \beta}(\omega)\) are real-valued and \(b_t^\rho = (b_t^{\alpha \rho})_{\rho=1}^\infty\) are \(l_2\)-valued \(\mathcal{P} \times \mathcal{B}(\mathbb{R}^d)\)-measurable functions on \(\Omega \times H_T\).

Let \(m \geq 1\) be an integer and let \(W_2^m\) be the usual Hilbert-Sobolev space of functions on \(\mathbb{R}^d\) with norm \(\| \cdot \|_{W_2^m}\).

**Assumption 2.1.** (i) For each \((\omega,t)\) the functions \(a_t^{\alpha \beta}\) are \(m\) times and the functions \(b_t^\rho\) are \(m+1\) times continuously differentiable in \(x\). There exist constants \(K_l, l = 0,...,m+1\), such that for all values of indices and arguments we have

\[ |D^l a_t^{\alpha \beta}| \leq K_l, \quad l \leq m, \quad |D^l b_t^\alpha|_{l_2} \leq K_l, \quad l \leq m+1.\]

(ii) There is a constant \(\kappa > 0\) such that for all \((\omega,t) \in \Omega \times H_T\) and \(z \in \mathbb{R}^d\)

\[ \sum_{i,j=1}^d (2a_t^{ij} - b_t^{i \rho} b_t^{j \rho}) z^i z^j \geq \kappa |z|^2. \]

**Assumption 2.2.** We have \(u_0 \in L_2(\Omega, \mathcal{F}_0, W_2^{m+1})\). The function \(f_t\) is \(W_2^m\)-valued, \(g_t^\rho, \rho = 1,2,...,\) are \(W_2^{m+1}\)-valued functions given on \(\Omega \times [0,T]\) and they are predictable. Moreover, for \(g_t := (g_t^\rho)_{\rho=1}^\infty\) and

\[ \|g_t\|^2_{W_2^m} := \sum_{\rho=1}^\infty \|g_t^\rho\|^2_{W_2} \]

we have

\[ E \int_0^T (\|f_t\|^2_{W_2^m} + \|g_t\|^2_{W_2^{m+1}}) \, dt + E\|u_0\|^2_{W_2^{m+1}} =: K_m < \infty. \]

**Remark 2.1.** If Assumption 2.2 holds with \(m > d/2\), then by Sobolev’s embedding of \(W_2^m\) into \(C_b\), the space of bounded continuous functions, for almost all \(\omega\) we can find a continuous function of \(x\) which equals to \(u_0\) almost everywhere. Furthermore, for each \(t\) and \(\omega\) we have continuous functions of \(x\) which coincide with \(f_t\) and \(g_t\), for almost every \(x \in \mathbb{R}^d\). Therefore when Assumption 2.2 holds with \(m > d/2\), we always assume that \(u_0, f_t\) and \(g_t\) are continuous in \(x\) for all \(t\).
The solutions of (2.1) will be looked for in the Hilbert space
\[ W^{m+2}_2(T) = L_2(\Omega \times [0, T], P, W^{m+2}_2). \]
One knows, see e.g., [14] or [20], how to define stochastic integrals of Hilbert-space valued processes and equation (2.1) is understood accordingly. Observe that since \( u_0 \in L_2(\Omega, F_0, W^m_2) \) the solutions of (2.1) automatically are continuous \( W^m_2 \)-valued processes (a.s.).

We are going to use the following classical result (see, for instance, Theorem 5.1, Remark 5.6, and Theorem 7.1 of [13]).

**Theorem 2.1.** Under the above assumptions there exists a unique solution \( u \in W^{m+2}_2(T) \) of (2.1) with initial condition \( u_0 \). Furthermore, with probability one the function \( u_t \) is a continuous \( W^{m+1}_2 \)-valued function and there exists a constant \( N \) depending only on \( T, d, \kappa, m, \) and \( K_l, l \leq m + 1 \), such that
\[
E \sup_{t \leq T} \| u_t \|^2_{W^{m+1}_2} + E \int_0^T \| u_t \|^2_{W^{m+2}_2} dt \leq NK_m^2.
\]

**Remark 2.2.** In the future we are going to assume that \( m + 1 > d/2 \). Then by Sobolev embedding theorems the solution \( u_t(x) \) from Theorem 2.1 is a continuous function of \((t, x)\) (a.s). More precisely, with probability one, for any \( t \) one can find a continuous function of \( x \) which equals \( u_t(x) \) for almost all \( x \) and, in addition, the so constructed modification is continuous with respect to the couple \((t, x)\).

We are interested in approximating the solution by means of solving a semidiscretized version of (2.1) when partial derivatives are replaced with finite differences. For \( \lambda = 0 \) set \( \delta_{h,\lambda} \) to be the unit operator and for the other values of \( \lambda \in \mathbb{R}^d \) let
\[
\delta_{h,\lambda} u(x) = \frac{u(x + h\lambda) - u(x)}{h} \quad \text{for } h \in \mathbb{R} \setminus \{0\}.
\]
We draw the reader’s attention to the fact that \( h \) can be of any sign. This will be important in the future.

To introduce difference equations we take a finite set \( \Lambda \subset \mathbb{R}^d \) containing the origin, and consider the equation
\[
\frac{du_t^h}{dt} = (L_t^h u_t^h + f_t) dt + (M_t^{h,\rho} u_t^h + g_t^\rho) dw_t^\rho,
\]
with
\[
L_t^h \phi = a_t^{\lambda\mu} \delta_{h,\lambda} \delta_{-h,\mu} \phi, \quad M_t^{h,\rho} \phi = b_t^{\lambda\rho} \delta_{h,\lambda} \phi,
\]
where the summation is performed over \( \lambda, \mu \in \Lambda \) and in (2.2) also with respect to \( \rho = 1, 2, \ldots \). Assume that, for \( \lambda, \mu \in \Lambda \), \( a_t^{\lambda\mu} = a_t^{\mu\lambda}(x) \) are real-valued and \( b_t^\lambda = b_t^\lambda(x) = (b_t^{\lambda\rho}(x))_{\rho=1}^\infty \) are \( l_2 \)-valued functions on \( \Omega \times H_T \), measurable with respect to \( P \times \mathcal{B}(\mathbb{R}^d) \).

Set \( \Lambda_0 := \Lambda \setminus \{0\} \). Let \( m \geq 0 \) be an integer. Set \( \bar{m} = \max(m, 1) \), and let \( A_0, A_1, \ldots, A_{\bar{m}} \) be some constants. The functions \( a \) and \( b \) are supposed to possess the following properties.
Assumption 2.3. (i) For each \((\omega, t)\) and \(\lambda, \mu \in \Lambda_0\) and \(\nu \in \Lambda\), \(a_{t}^{\lambda \mu}\) are \(m\) times continuously differentiable in \(x\), \(a_{t}^{0 \nu}, a_{t}^{\nu 0}\) are \(m\) times continuously differentiable in \(x\) and \(b_{t}^{\nu}\) are \(m\) times continuously differentiable in \(x\) as \(l_2\)-valued functions. For all values of arguments we have
\[
|D^j a_{t}^{\lambda \mu}| \leq A_j, \quad \lambda, \mu \in \Lambda_0, \quad j \leq m,
\]
\[
|D^j a_{t}^{0 \nu}| \leq A_j, \quad |D^j a_{t}^{\nu 0}| \leq A_j, \quad |D^j b_{t}^{\lambda}|_{L^2} \leq A_j, \quad \lambda \in \Lambda, \quad j \leq m.
\]
(ii) For all \((\omega, t, x) \in \Omega \times H_T\) and numbers \(z_{\lambda}, \lambda \in \Lambda_0\), we have
\[
\sum_{\lambda, \mu \in \Lambda_0} (2a_{t}^{\lambda \mu} - b_{t}^{\lambda \nu} b_{t}^{\nu \mu}) z_{\lambda} z_{\mu} \geq \kappa \sum_{\lambda \in \Lambda_0} z_{\lambda}^2.
\]
Introduce
\[
G_h = \{\lambda_1 h + \ldots + \lambda_n h : n = 1, 2, \ldots, \lambda_i \in \Lambda \cup (-\Lambda)\}
\]
and let \(l_2(G_h)\) be the set of real-valued functions \(u\) on \(G_h\) such that
\[
|u|_{l_2(G_h)}^2 := |h|^d \sum_{x \in G_h} |u(x)|^2 < \infty.
\]
The notation \(l_2(G_h)\) will also be used for \(l_2\)-valued functions like \(g\).

Remark 2.3. Observe that, under Assumption 2.3 (i), equation (2.2) is an ordinary Itô equation with Lipschitz continuous coefficients for \(l_2(G_h)\)-valued processes. Therefore if, for instance, (a.s.)
\[
\int_0^T (|f_t|_{l_2(G_h)}^2 + |g_t|_{l_2(G_h)}^2) \, dt < \infty,
\]
and Assumption 2.3 (i) holds then equation (2.2) has a unique solution with continuous trajectories in \(l_2(G_h)\) provided that the initial data \(u_0^h \in l_2(G_h)\) (a.s.).

For equation (2.2) to be consistent with (2.1) we impose the following.

Assumption 2.4. For all \(i, j = 1, 2, \ldots, d\) and \(\rho = 1, 2, \ldots\)
\[
\sum_{\lambda, \mu \in \Lambda_0} a_{t}^{\lambda \mu} \lambda^i \mu^j = a_{t}^{ij}, \quad \sum_{\lambda, \mu \in \Lambda_0} a_{t}^{\lambda 0} \lambda^i + \sum_{\mu \in \Lambda_0} a_{t}^{0 \mu} \mu^i = \bar{a}_{t}^{i0} + a_{t}^{0}, \quad a_{t}^{0 0} = \bar{a}_{t}^{0 0},
\]
\[
\sum_{\lambda \in \Lambda_0} b_{t}^{\lambda \rho} \lambda^i = \bar{b}_{t}^{i \rho}, \quad b_{t}^{0 \rho} = b_{t}^{0 \rho}.
\]

Remark 2.4. Clearly, if
\[
a_{t}^{ij} = \sum_{\lambda, \mu \in \Lambda_0} a_{t}^{\lambda \mu} \lambda^i \mu^j, \quad i, j = 1, 2, \ldots
\]
is an invertible matrix for some \(\omega, t, x\), then \(\Lambda_0\) spans the whole \(\mathbb{R}^d\). On the other hand, if \(\Lambda_0\) spans \(\mathbb{R}^d\), then clearly a constant \(\kappa' > 0\) exists such that
\[
\sum_{\lambda \in \Lambda_0} |\sum_{i} z^i \lambda^i|^2 \geq \kappa' |z|^2, \quad \text{for all } z = (z^1, \ldots, z^d) \in \mathbb{R}^d,
\]
and therefore Assumptions 2.3 (ii) and 2.4 imply Assumption 2.1 (ii). It is not hard to see that Assumptions 2.1 (ii) and 2.4 do not imply Assumption 2.3 (ii), in general, unless \( \Lambda_0 \) is a basis in \( \mathbb{R}^d \).

There are several ways to construct appropriate \( a \) and \( b \).

**Example 2.1.** The most natural, albeit sometimes not optimal, way to choose \( a \) and \( b \) is to set \( \Lambda = \{ e_0, e_1, ..., e_d \} \), where \( e_0 = 0 \) and \( e_i \) is the \( i \)th basis vector in \( \mathbb{R}^d \) and let

\[
a_t^{\alpha e_i} = a_t^{i\beta} = a_t^{\alpha\beta}, \quad b_t^{\alpha \rho} = b_t^{i\alpha \rho}, \quad \alpha, \beta = 0, 1, ..., d.
\]

Thus, in (2.2) the first order derivatives in (2.1) are approximated by usual finite differences and

\[
\sum_{\lambda, \mu \in \Lambda_0} a_t^{\lambda \mu} \delta_{h, \lambda} \delta_{-h, \mu} u = -a_t^{ij} \delta_{h, e_i} \delta_{h, -e_j} u, \tag{2.3}
\]

which is a standard finite-difference approximation of \( a_t^{ij} D_i D_j u \). Also notice that

\[
\sum_{\lambda, \mu \in \Lambda_0} a_t^{\lambda \mu} \delta_{h, \lambda} \delta_{-h, \mu} u = a_t^{ij} z_{e_i} z_{e_j}, \quad \sum_{\lambda \in \Lambda_0} b_t^{\lambda \rho} \delta_{h, \lambda} = b_t^{ij} z_{e_i}.
\]

It follows that \( a \) and \( b \) satisfy the above assumptions as long as \( a \) and \( b \) do.

**Example 2.2.** The second choice is to use symmetric finite differences to approximate the first-order derivatives. Namely, we take \( \Lambda_0 = \{ \pm e_1, ..., \pm e_d \} \) and

\[
a_t^{0 \pm e_i} = a_t^{\pm e_i, 0} = \pm (1/4)(a_t^{0i} + a_t^{i0}), \quad b_t^{0 \pm e_i, \rho} = \pm (1/2)b_t^{i \rho},
\]

so that, for instance,

\[
\sum_{\lambda \in \Lambda_0} b_t^{\lambda \rho} \delta_{h, \lambda} u(x) = \frac{d}{2h} \sum_{i=1}^d b_t^{ij} u(x + he_i) - u(x - he_i).
\]

For \( \lambda, \mu \in \Lambda_0 \) we define \( a_t^{\lambda \mu} \) by

\[
a_t^{\pm \epsilon_i, \pm \epsilon_j} = \frac{1}{2} a_t^{ij}, \quad a_t^{\pm \epsilon_i, \varepsilon_j} = 0.
\]

Then Assumption 2.4 is satisfied and formula (2.3) holds again \( (a^{ij} = a^{ji}) \).

If Assumption 2.1 (ii) is satisfied, then for any numbers \( z \)

\[
\sum_{\lambda, \mu \in \Lambda_0} (2a_t^{\lambda \mu} - b_t^{\lambda \rho} b_t^{i \rho}) z_{\lambda} z_{\mu} = \sum_{i,j=1}^d a_t^{ij} z_{e_i} z_{e_j} + \sum_{i,j=1}^d a_t^{ij} z_{-e_i} z_{-e_j}
\]

\[
-(1/4) \sum_{\rho} \sum_{i=1}^d b_t^{i \rho} z_{e_i} - \sum_{i=1}^d b_t^{i \rho} z_{-e_i} \geq \sum_{i,j=1}^d a_t^{ij} z_{e_i} z_{e_j} - (1/2) \sum_{\rho} \sum_{i=1}^d b_t^{i \rho} z_{e_i} \geq
\]

\[
+ \sum_{i,j=1}^d a_t^{ij} z_{-e_i} z_{-e_j} - (1/2) \sum_{\rho} \sum_{i=1}^d b_t^{i \rho} z_{-e_i} \geq
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\[ \geq \kappa \sum_{i=1}^{d} z_{e_i}^2 + \kappa \sum_{i=1}^{d} z_{c_i}^2 = \kappa \sum_{\lambda \in \Lambda_0} z_{\lambda}^2, \]

so that Assumption 2.3 (ii) is also satisfied. By comparing Theorems 2.4 and 2.5 and also definitions (2.6) and (2.9) for approximations \( \tilde{u}^h \) and \( \tilde{u}^h \) below, notice that the above choice of \( a \) and \( b \) is better than that of the previous example, in the sense that for \( \tilde{u}^h \) we have fewer terms to calculate than for \( \tilde{u}^h \) to get the same order of accuracy of the approximations.

Our results revolve about the possibility to prove the existence of random processes \( u^{(j)}(t) \), \( t \in [0,T], x \in \mathbb{R}^d, j = 0, \ldots, k \), for some integer \( k \geq 0 \) such that they are independent of \( h \), \( u^{(0)} \) is the solution of (2.1) with initial value \( u_0 \) and almost surely we have

\[ u^h_t(x) = \sum_{j=0}^{k} h^j j! u^{(j)}(x) + R^h_t(x) \]  

for \( h \neq 0 \) and for all \( t \in [0,T] \) and \( x \in G_h \), where \( u^h_t \) is the solution to (2.2) with initial data \( u_0 \) and \( R^h_t \) is a continuous \( l_2(G_h) \)-valued adapted process, such that

\[ E \sup_{t \in [0,T]} \sup_{x \in G_h} |R^h_t(x)|^2 \leq N h^{2(k+1)} \kappa_m^2 \]  

with a constant \( N \) independent of \( h \).

### Theorem 2.2

Let Assumptions 2.1, 2.2, 2.3 and 2.4 hold with

\[ m = m > k + 1 + d/2, \]

where \( k \geq 0 \) is an integer. Then expansion (2.4) and estimate (2.5) hold with a constant \( N \) depending only on \( \Lambda, d, m, K_0, \ldots, K_{m+1}, A_0, \ldots, A_m, \kappa, \) and \( T \).

### Remark 2.5

Actually \( u^h_t(x) \) is defined for all \( x \in \mathbb{R}^d \) rather than only on \( G_h \) and, as we will see from the proof of Theorem 2.2, one can replace \( G_h \) in (2.5) with \( \mathbb{R}^d \).

### Remark 2.6

Let \( \Lambda_0 \) be a basis in \( \mathbb{R}^d \) such that Assumption 2.4 holds. Then Assumption 2.1 (i) implies Assumption 2.3 (i), and Assumption 2.1 (ii) implies Assumption 2.3 (ii) with \( m = m \). Thus if Assumptions 2.1 and 2.2 hold with

\[ m > k + 1 + d/2, \]

then the conditions of Theorem 2.2 are satisfied.

Equality (2.4) clearly yields

\[ \delta_{h,\lambda} u^h_t(x) = \sum_{j=0}^{k} \frac{h^j}{j!} \delta_{h,\lambda} u^{(j)}(x) + \delta_{h,\lambda} R^h_t(x) \]
for any \( \lambda = (\lambda_1, ..., \lambda_n) \in \Lambda^n \) and integer \( n \geq 0 \), where \( \Lambda^0 = \{0\} \) and

\[
\delta_{h,\lambda} := \delta_{h,\lambda_1} \cdot ... \cdot \delta_{h,\lambda_n}.
\]

Theorem 2.2 can be generalised as follows.

**Theorem 2.3.** Let the conditions of Theorem 2.2 hold with

\[
m = m > k + n + 1 + d/2
\]

for some integers \( k \geq 0 \) and \( n \geq 0 \). Then expansion (2.4) holds and for \( \lambda = (\lambda_1, ..., \lambda_n) \in \Lambda^n \)

\[
E \sup_{t \in [0,T]} \sup_{x \in G_h} |\delta_{h,\lambda} R_t^h(x)|^2 + E \sup_{t \in [0,T]} \sum_{x \in G_h} |\delta_{h,\lambda} R_t^h(x)|^2 |h|^d \leq N h^{2(k+1)} K_m^2,
\]

where \( N \) depends only on \( \Lambda, d, m, K_0, ..., K_{m+1}, A_0, ..., A_m, \kappa \) and \( T \).

We prove Theorem 2.3 in Section 4 after some preliminaries presented in Section 3. To discuss the method of acceleration we fix an integer \( k \geq 0 \) and set

\[
\bar{u}^h = \sum_{j=0}^{k} b_j u^{2^{-j}h}, \tag{2.6}
\]

where, naturally, \( u^{2^{-j}h} \) are the solutions to (2.2), with \( 2^{-j}h \) in place of \( h \),

\[
(b_0, b_1, ..., b_k) := (1, 0, 0, ..., 0) V^{-1} \tag{2.7}
\]

and \( V^{-1} \) is the inverse of the Vandermonde matrix with entries

\[
V^ij := 2^{-(i-1)(j-1)}, \quad i, j = 1, ..., k + 1.
\]

The following consequence of Theorem 2.2 is the first main result of the paper on accelerated convergence. Its generalisation is presented in Section 4.

**Theorem 2.4.** Under the assumptions of Theorem 2.2 we have

\[
E \sup_{t \leq T} \sup_{x \in G_h} |\bar{u}^h_t(x) - u^{(0)}_t(x)|^2 \leq N |h|^{2(k+1)} K_m^2, \tag{2.8}
\]

where \( N \) depends only on \( \Lambda, d, m, K_0, ..., K_{m+1}, \kappa, A_0, ..., A_m, \) and \( T \).

**Proof.** By Theorem 2.2

\[
u^{2^{-j}h} = u^{(0)} + \sum_{i=1}^{k} \frac{h^i}{i!2^j} u^{(i)} + \bar{r}^{2^{-j}h} h^{k+1}, \quad j = 0, 1, ..., k,
\]

with \( \bar{r}^{2^{-j}h} := h^{-j(k+1)} R^{2^{-j}h} \), which gives

\[
\bar{u}^h = \sum_{j=0}^{k} b_j u^{2^{-j}h} = \left( \sum_{j=0}^{k} b_j u^{(0)} \right) + \sum_{j=0}^{k} \sum_{i=1}^{k} \frac{h^i}{i!2^j} u^{(i)} + \sum_{j=0}^{k} b_j \bar{r}^{2^{-j}h} h^{k+1}
\]

\[
= u^{(0)} + \sum_{i=1}^{k} \frac{h^i}{i!} u^{(i)} \sum_{j=0}^{k} b_j 2^j + \sum_{j=0}^{k} b_j \bar{r}^{2^{-j}h} h^{k+1} = u^{(0)} + \sum_{j=0}^{k} b_j \bar{r}^{2^{-j}h} h^{k+1},
\]
since
\[ \sum_{j=0}^{k} b_j = 1, \quad \sum_{j=0}^{k} b_j 2^{-ij} = 0, \quad i = 1, 2, \ldots, k \]
by the definition of \((b_0, \ldots, b_k)\). This and (2.5) yield the result and the theorem is proved. \(\square\)

Remark 2.7. Let the conditions of Theorem 2.2 hold with
\[ m = m > k + 1 + n + d/2, \]
where \(k\) and \(n\) are nonnegative integers. Then (2.8) holds with \(\delta_{h,\lambda}\tilde{u}^h\) and \(\delta_{h,\lambda}u^{(0)}\) in place of \(\tilde{u}^h\) and \(u^{(0)}\), respectively, for \(\lambda \in \Lambda^n\).

Proof. This follows from Theorem 2.3 in the same way as Theorem 2.4 follows from Theorem 2.2. \(\square\)

By the above remark one can construct fast approximations for the derivatives of \(u^{(0)}\) via suitable linear combinations of finite differences of \(\tilde{u}^h\).

Sometimes it suffices to combine fewer terms \(u^{2-jh}\) to get accuracy of order \(k + 1\). For integers \(k \geq 0\) define
\[ \tilde{u}^h = \sum_{j=0}^{\tilde{k}} \tilde{b}_j u^{2-jh}, \tag{2.9} \]
where
\[ (\tilde{b}_0, \tilde{b}_1, \ldots, \tilde{b}_{\tilde{k}}) := (1, 0, 0, \ldots, 0)\tilde{V}^{-1}, \quad \tilde{k} = \lceil k/2 \rceil, \]
and \(\tilde{V}^{-1}\) is the inverse of the Vandermonde matrix with entries
\[ \tilde{V}^{ij} := 4^{-(i-1)(j-1)}, \quad i, j = 1, \ldots, \tilde{k} + 1. \]

Theorem 2.5. Let the conditions of Theorem 2.2 hold. Then in the situation of Example 2.2 we have
\[ E \sup_{t \leq T} \sup_{x \in \bar{G}_h} |\tilde{u}^h_t(x) - u_t^{(0)}(x)|^2 \leq N|h|^{2(k+1)}K_m^2, \tag{2.10} \]
where \(N\) is a constant depending only on \(d, m, \kappa, K_0, \ldots, K_{m+1}, A_0, \ldots, A_m,\) and \(T\).

To prove this result we need only repeat the proof of Theorem 2.4 taking into account that in (2.4) we have \(u_t^{(j)} = 0\) for odd \(j \leq k\) since \(u_t^h = u_t^{-h}\) owing to the fact that in the case of Example 2.2 equation (2.2) does not change if we replace \(h\) with \(-h\).

Remark 2.8. Notice that without acceleration, i.e., when \(k = 1\) in the above theorem, the mean square norm of the supremum in \(t\) and \(x\) of the error of the finite difference approximations in Example 2.2 is proportional to \(h^2\). This is a sharp result see, e.g., Remark 2.21 in [3] on finite difference approximations for deterministic parabolic PDEs.
Example 2.3. Assume that in the situation of Example 2.2 we have $d = 2$ and $m = 7$. Then

$$\tilde{u}^h := \frac{4}{3} u^{h/2} - \frac{1}{3} u^h$$

satisfies

$$E \sup_{t \leq T} \sup_{x \in \mathcal{G}_h} |u_t^0(x) - \tilde{u}_t^h(x)| \leq N h^4.$$  

Example 2.4. Take $d = 1$ and consider the following SPDE:

$$du_t = 3D^2 u_t \, dt + 2D u_t \, dw_t$$

with initial data $u_0(x) = \cos x$, where $w_t$ is a one-dimensional Wiener process. Then a unique bounded solution is $u_t(x) = e^{-t} \cos (x + 2w_t)$. Example 2.2 suggests the following version of (2.2):

$$du_t^h(x) = 3 \frac{u_t^h(x + h) - 2u_t^h(x) + u_t^h(x - h)}{h^2} \, dt + \frac{u_t^h(x + h) - u_t^h(x - h)}{h} \, dw_t,$$

the unique bounded solution of which with initial condition $\cos x$ is given by

$$u_t^h(x) = e^{-c h^2} \cos (x + 2\phi h w_t), \quad h^2 c_h = 12 \sin^2 \frac{h}{2} - 2 \sin^2 h, \quad \phi_h = \sin \frac{h}{h}.$$  

For $t = 1$, $h = 0.1$, and $w_t = 0$ we have

$$u_1(0) \approx 0.3678794412, \quad u_1^h(0) \approx 0.366352748, \quad u_1^{h/2}(0) \approx 0.3674966179,$$

$$\tilde{u}_1^h(0) = \frac{4}{3} u_1^{h/2}(0) - \frac{1}{3} u_1^h(0) \approx 0.3678779079.$$  

It is instructive to observe that such a level of accuracy is achieved for $u_1^h(0)$ with $h = 0.00316$, which is more than 15 times smaller than $h/2$.

Actually, this example does not quite fit into our scheme because $u_0$ is not square summable over $\mathbb{R}$. In connection with this we reiterate that the main goal of the present article was to introduce a method and not to prove the most general results. Without much trouble our approach can be extended to a class of SPDEs with growing data by the help of weighted Sobolev spaces (see [10]), and then the above example can be included formally.

3. Auxiliary facts

The following fact is easily obtained by Young’s inequality owing to Assumption 2.3.

Lemma 3.1. Let Assumption 2.3 hold. Then for all $\varphi \in L_2$ we have

$$Q_t(\varphi) := \int_{\mathbb{R}^d} \left[ 2 \varphi(x) L_t^h \varphi(x) + \sum_{\rho = 1}^{\infty} |M_t^{h, \rho, \varphi}(x)|^2 \right] \, dx$$

$$\leq -\frac{\kappa}{2} \sum_{\lambda \in \Lambda_0} \| \delta_{h, \lambda} \varphi \|_{L_2}^2 + N \| \varphi \|_{L_2}^2,$$

where $N$ depends only on $\kappa, A_0, A_1$, and the number of vectors in $\Lambda$.  

Proof. First observe that for \( \mu \in \Lambda_0 \) the conjugate operator in \( L^2 \) to \( \delta_{-h,\mu} \) is \( \delta_{h,\mu} \). Notice also that
\[
\delta_{h,\mu}(\phi \psi) = \phi \delta_{h,\mu} \psi + (T_{h,\mu} \psi) \delta_{h,\mu} \phi,
\]
where \( T_{h,\mu} \psi(x) = \psi(x + h\mu) \). Thus by simple calculations we get
\[
Q_t(\varphi) = \sum_{i=1}^{4} Q_t^{(i)}(\varphi)
\]
with
\[
Q_t^{(1)}(\varphi) = -\int_{\mathbb{R}^d} \sum_{\lambda, \mu \in \Lambda_0} ((2a_{\lambda}^\mu - b_{\lambda}^\mu b_{\lambda}^{\mu \rho})(\delta_{h,\lambda} \varphi)(x) dx
\]
\[
Q_t^{(2)}(\varphi) = 2 \int_{\mathbb{R}^d} \sum_{\lambda, \mu \in \Lambda_0} ((T_{h,\mu} \varphi)(\delta_{h,\lambda} \varphi)(x) dx
\]
\[
Q_t^{(3)}(\varphi) = \int_{\mathbb{R}^d} 2a_{\lambda}^{00} \varphi^2(x) + 2\varphi(x) \sum_{\lambda \in \Lambda_0} (a_{\lambda}^{00} \delta_{h,\lambda} \varphi + a_{\lambda}^{00} \delta_{-h,\lambda} \varphi)(x) dx
\]
\[
Q_t^{(4)}(\varphi) = \int_{\mathbb{R}^d} b_{\lambda}^{00} \varphi^2(x) + 2 \sum_{\lambda \in \Lambda_0} b_{\lambda}^{00} \varphi \delta_{h,\lambda} \varphi(x) dx.
\]
Due to Assumption 2.3 (ii)
\[
Q_t^{(1)}(\varphi) \leq -\kappa \sum_{\lambda \in \Lambda_0} \| \delta_{h,\lambda} \varphi \|_{L^2}^2.
\]
By Assumption 2.3(i), Young’s inequality and the shift invariance of Lebesgue measure
\[
Q_t^{(i)}(\varphi) \leq \frac{\kappa}{6} \sum_{\lambda \in \Lambda_0} \| \delta_{h,\lambda} \varphi \|_{L^2}^2 + N \| \varphi \|_2^2, \quad i = 2, 3, 4,
\]
with a constant \( N \) depending only on the number of elements of \( \Lambda \), \( \kappa \), \( A_0 \) and, for \( i = 2 \) also on \( A_1 \). We finish the proof by summing up these estimates. \( \square \)

Recall the notation \( \mathbb{W}_m^m(T) = L_2(\Omega \times [0,T], \mathcal{P}, W_2^m) \). Remember that \( W_2^m \) denotes the Hilbert-Sobolev space of real-valued and also that of \( l_2 \)-valued functions on \( \mathbb{R}^d \). Thus \( \mathbb{W}_2^m(T) \) denotes the Hilbert space of predictable functions \( \phi = \phi_t \) on \( \Omega \times [0,T] \) with values in the \( W_2^m \) space of real-valued functions, and \( \mathbb{W}_2^m(T) = \mathbb{W}_2^m(T, l_2) \) denotes the Hilbert space of functions \( g = (g_{\rho})_{\rho=1}^\infty \) with values in the \( W_2^m \) space of \( l_2 \)-valued functions on \( \mathbb{R}^d \), with norm defined by
\[
\| \phi \|_{\mathbb{W}_2^m(T)}^2 = E \int_0^T \| \phi_t \|_{W_2^m}^2 dt < \infty \quad \text{and}
\]
\[
\| g \|_{\mathbb{W}_2^m(T)}^2 = E \int_0^T \sum_{\rho=1}^\infty \| g_{\rho}^\rho \|_{W_2^m}^2 dt < \infty,
\]
respectively.
Theorem 3.2. Let Assumption 2.3 (i) hold. Let \( f^\mu \in \mathcal{W}_2^m(T), \mu \in \Lambda, \) and \((g^\rho)^{\infty}_{\rho=1} \in \mathcal{W}_2^m(T)\) be some functions. Then for each \( h \neq 0 \) there exists a unique continuous \( L_2 \)-valued solution \( u_t^h \) of
\[
du_t^h = (\alpha^\mu_t \delta_{h,\lambda} \delta_{-h,\mu} u_t^h + \delta_{-h,\mu} f_t^\mu) dt + (\beta^\rho_t \delta_{h,\lambda} u_t^h + g_t^\rho) dw_t^\rho
\]
for any \( \mathcal{W}_2^m \)-valued \( \mathcal{F}_0 \)-measurable initial condition \( u_0 \). This solution is a \( \mathcal{W}_2^m \)-valued continuous process. Moreover, if Assumption 2.3 (ii) is also satisfied, then
\[
E \sup_{t \leq T} \| u_t^h \|_{\mathcal{W}_2^m}^2 + E \int_0^T \sum_{\lambda \in \Lambda} \| \delta_{h,\lambda} u_t^h \|_{\mathcal{W}_2^m}^2 dt
\]
\[
\leq NE \int_0^T \left( \sum_{\mu \in \Lambda} \| f_t^\mu \|_{\mathcal{W}_2^m}^2 + \| g_t \|_{\mathcal{W}_2^m}^2 \right) dt + NE \| u_0 \|_{\mathcal{W}_2^m}^2,
\]
where \( N \) depends only on \( d, m, \Lambda, \kappa, A_0, \ldots, A_m, \) and \( T \).

Proof. The first assertion is a simple consequence of the fact that (2.2) is an ordinary Itô equation with Lipschitz continuous coefficients for \( L_2 \)-valued processes. Similarly, (2.2) has a unique \( \mathcal{W}_2^m \)-valued solution and, since \( \mathcal{W}_2^m \subset L_2 \), this proves that the \( L_2 \)-valued solution is actually \( \mathcal{W}_2^m \)-valued. Moreover, we can easily get estimate (3.2) with a constant \( N \) which depends on \( h \). In particular we have that the solution is in \( \mathcal{W}_2^m(T) \).

The proof of estimate (3.2) with \( N \) independent of \( h \) is rather standard but still contains a point which usually does not appear. This concerns the treatment of \( \tilde{a}^\lambda \delta_{h,\lambda} \delta_{-h,\mu} u_t^h \) after (3.8) without assuming that 2 derivatives of \( \tilde{a} \) are bounded.

By Itô’s formula for \( L_2 \)-valued processes we find
\[
d\| u_t^h \|_{L_2}^2 = \left\{ Q_t(u_t^h) + 2(u_t^h, f_t^\mu) + 2(b_t^\rho \delta_{h,\lambda} u_t^h, g_t^\rho) + \| g_t^\rho \|_{L_2}^2 \right\} dt
\]
\[
+ 2(u_t^h, b_t^\rho \delta_{h,\lambda} u_t^h + g_t^\rho) dw_t^\rho.
\]

We use Lemma 3.1, the inequalities like \(|ab| \leq \varepsilon a^2 + \varepsilon^{-1} b^2\), and Assumption 2.3 (i) to conclude that
\[
E \| u_t^h \|_{L_2}^2 + \frac{\kappa}{2} E \int_0^T \sum_{\lambda \in \Lambda_0} \| \delta_{h,\lambda} u_s^h \|_{L_2}^2 ds \leq E \| u_0 \|_{L_2}^2
\]
\[
+ NE \int_0^T \left( \| u_s^h \|_{L_2}^2 + \sum_{\lambda \in \Lambda} \| f_s^\lambda \|_{L_2}^2 + \| g_s \|_{L_2}^2 \right) ds < \infty.
\]

By Gronwall’s lemma we can eliminated the first term in the integral on the right in (3.4) and get that
\[
E \int_0^T \sum_{\lambda \in \Lambda} \| \delta_{h,\lambda} u_s^h \|_{L_2}^2 ds \leq NE \| u_0 \|_{L_2}^2
\]
\[
+ NE \int_0^T \left( \sum_{\lambda \in \Lambda} \| f_s^\lambda \|_{L_2}^2 + \| g_s \|_{L_2}^2 \right) ds.
\]
Remark 3.1 below). Then we come to the following counterpart of (3.4)

$$\frac{\partial}{\partial \tau}$$

where we use the inequality (cf. Remark 3.1)

$$\phi_x x$$

in $\phi$. This and (3.5) allow us to drop the last term in (3.6) which again combined with (3.5) yields

$$E \sup_{t \leq T} \|u_t^h\|^2_{L_2} \leq NE \|u_0\|^2_{L_2}$$

+ $NE \int_0^T \left( \sum_{\lambda \in \Lambda} \|f_t^h\|^2_{L_2} + \|g_t\|^2_{L_2} \right) dt + N_1 J,$

(3.6)

where

$$J = E \left( \int_0^T \sum_{\mu=1}^\infty \left( \int_{\mathbb{R}^d} |u_t^h (b^{\lambda \rho} \delta_{h,\lambda} u_t^h + g_t^\rho) |dx \right)^2 dt \right)^{1/2}$$

$$\leq E \left( \int_0^T \|u_t^h\|^2_{L_2} \|b^{\lambda \rho} \delta_{h,\lambda} u_t^h + g_t^\rho\|_{L_2} dt \right)^{1/2}$$

$$\leq E \sup_{t \leq T} \|u_t^h\|_{L_2} \left( \int_0^T \|b^{\lambda \rho} \delta_{h,\lambda} u_t^h + g_t^\rho\|^2_{L_2} dt \right)^{1/2}$$

$$\leq (2N_1)^{-1} E \sup_{t \leq T} \|u_t^h\|^2_{L_2} + NE \int_0^T \left( \sum_{\lambda \in \Lambda} \|\delta_{h,\lambda} u_t^h\|^2_{L_2} + \|g_t\|^2_{L_2} \right) dt.$$  

This and (3.5) allow us to drop the last term in (3.6) which again combined with (3.5) yields

$$E \sup_{t \leq T} \|u_t^h\|^2_{L_2} + E \int_0^T \sum_{\lambda \in \Lambda} \|\delta_{h,\lambda} u_t^h\|^2_{L_2} dt$$

$$\leq NE \|u_0\|^2_{L_2} + NE \int_0^T \left( \sum_{\lambda \in \Lambda} \|f_t^h\|^2_{L_2} + \|g_t\|^2_{L_2} \right) dt.$$  

(3.7)

This proves the theorem if $m = 0$. If $m \geq 1$, we differentiate (3.1) with respect to $x^i$, and introduce the notation $\tilde{\phi}$ for the derivative of a function $\phi$ in $x^i$. Then we obtain

$$d\tilde{u}_t^h = (a^{\lambda \rho} \delta_{h,\lambda} \tilde{u}_t^h + \delta_{h,\mu} \tilde{f}_t^\mu) dt + (b^{\lambda \rho} \delta_{h,\lambda} \tilde{u}_t^h + \tilde{g}_t^\rho) dw^\rho,$$

(3.8)

where

$$\tilde{f}_t^\mu = \tilde{f}_t^\mu, \quad \mu \neq 0, \quad \tilde{f}_t^0 = \tilde{f}_t^0 + \tilde{a}^{\lambda \rho} \delta_{h,\lambda} \tilde{u}_t^h, \quad \tilde{g}_t^\rho = \tilde{g}_t^\rho + \tilde{b}^{\lambda \rho} \delta_{h,\lambda} u_t^h.$$  

We proceed with (3.8) as above with (3.1) with one exception that for $\mu \in \Lambda_0$ we use the inequality (cf. Remark 3.1)

$$E \int_0^t \int_{\mathbb{R}^d} |\tilde{u}_s^h \delta_{h,\lambda} \tilde{u}_s^h| dx ds \leq \int_0^t E \|\tilde{u}_s^h\|_{L_2} \|\delta_{h,\lambda} \partial_\mu \tilde{u}_s^h\|_{L_2} ds$$

$$\leq \varepsilon \int_0^t E \|D\delta_{h,\lambda} u_s^h\|^2_{L_2} ds + N\varepsilon^{-1} \int_0^t E \|\tilde{u}_s^h\|^2_{L_2} ds,$$

where $\partial_\mu = \mu^i D_i$ and $\varepsilon > 0$ is arbitrary and $N$ depends only on $|\mu|$ (cf. Remark 3.1 below). Then we come to the following counterpart of (3.4)

$$E \|\tilde{u}_t^h\|^2_{L_2} + E \int_0^t \sum_{\lambda \in \Lambda} \|\delta_{h,\lambda} \tilde{u}_s^h\|^2_{L_2} ds$$
\[ \leq NE\|\tilde{u}_0\|_{L_2}^2 + (2d)^{-1}E\int_0^t \sum_{\lambda \in \Lambda} \|D_{\delta_{h,\lambda}}u_{s}^h\|_{L_2}^2 \, ds \]

\[ + NE\int_0^t (\|\tilde{u}_s^h\|_{L_2}^2 + \sum_{\lambda \in \Lambda} \|f_s^\lambda\|_{W_2^1}^2 + \|g_s\|_{W_2^1}^2) \, ds. \] \tag{3.9}

Recall that here \( \tilde{u}_i^h \) is the derivative of \( u_i^h \) with respect to \( x^i \). By writing (3.9) for all \( i = 1, \ldots, d \) and summing them up we see that the term with the factor \((2d)^{-1}\) is estimated by other terms on the right-hand side of (3.9) and, hence, can be dropped. After that the already familiar procedure yields

\[ E \sup_{t \leq T} \|Du_t^h\|_{L_2}^2 + E\int_0^T \sum_{\lambda \in \Lambda} \|D_{\delta_{h,\lambda}}u_t^h\|_{L_2}^2 \, dt \]

\[ \leq NE\|u_0\|_{W_2^1}^2 + NE\int_0^T (\sum_{\lambda \in \Lambda} \|f_t^\lambda\|_{W_2^1}^2 + \|g_t\|_{W_2^1}^2) \, dt, \] \tag{3.10}

which along with (3.7) proves (3.2) with 1 in place of \( m \).

Once this step is done the rest is routine. Assume that \( m \geq 2 \) and (3.2) is true with \( m \) in place of \( n \) for an integer \( n \in [1, m-1] \). Then we differentiate (3.1) \( n + 1 \) times and now use the notation \( \bar{\phi} \) for certain \( n + 1 \)-th order derivative of \( \phi \) with respect to \( x \). Then we will obtain (3.8) with slightly modified \( \bar{f}_0 \) and \( \bar{g}^\rho \). Namely, the \( \bar{f}_0 \) will be the sum of \( \bar{f}_0 \) and the linear combination with constant coefficients of certain \( i \)-th derivatives of \( \bar{a}_{h}^{\mu} \) times certain \( n + 1 - i \)-th derivatives of \( \delta_{h,\lambda} \delta_{-h,\mu} u_{i}^h \). Here \( i \) should be restricted to \([1, n + 1]\). As above, the \( L_2 \)-norms of the \( n + 1 - i \)-th derivatives of \( \delta_{h,\lambda} \delta_{-h,\mu} u_{i}^h \) are dominated by the \( L_2 \)-norms of the \( n + 2 - i \)-th derivatives of \( \delta_{h,\lambda} u_{i}^h \) which are less than the \( W_2^{n+1} \)-norm of \( \delta_{h,\lambda} u_{i}^h \) an estimate of which is contained in (3.2) with \( n \) in place of \( l \). Similar changes should be made in \( \bar{g}^\rho \). After that we obtain the corresponding counterpart of (3.10) which yields (3.2) with \( n + 1 \) in place of \( m \). This obviously brings the proof of the theorem to an end. \( \Box \)

**Lemma 3.3.** Let \( n \geq 0 \) be an integer, let \( \phi \in W_2^{n+1}, \psi \in W_2^{n+2}, \) and \( \lambda, \mu \in \Lambda_0 \). Set

\[ \partial_{\lambda} \phi = \lambda^i D_i \phi, \quad \partial_{\lambda \mu} = \partial_{\lambda} \partial_{\mu}. \]

Then we have

\[ \frac{\partial^n}{(\partial h)^n} \delta_{h,\lambda} \phi(x) = \int_0^1 \theta^n \partial_{\lambda}^{n+1} \phi(x + h \theta \lambda) \, d\theta, \] \tag{3.11}

\[ \frac{\partial^n}{(\partial h)^n} \delta_{h,\lambda} \delta_{-h,\mu} \psi(x) \]

\[ = \int_0^1 \int_0^1 (\theta_1 \partial_{\lambda} - \theta_2 \partial_{\mu})^n \partial_{\lambda \mu} \psi(x + h (\theta_1 \lambda - \theta_2 \mu)) \, d\theta_1 d\theta_2, \] \tag{3.12}
for almost all $x \in \mathbb{R}^d$, for each $h \in \mathbb{R}$. Furthermore, if $l \geq 0$ is an integer and $\phi \in W^{n+2+l}_2$ and $\psi \in W^{n+3+l}_2$, then

$$\left\| \delta_{h,\lambda} \phi - \sum_{i=0}^{n+1} \frac{h^i}{(i+1)!} \partial^{i+1}_\lambda \phi \right\|_{W^2_2} \leq \frac{|h|^{n+1}}{(n+2)!} \left\| \partial^{n+2}_\lambda \phi \right\|_{W^2_2}, \quad (3.13)$$

$$\left\| \delta_{h,\lambda} \delta_{-h,\mu} \psi - \sum_{i=0}^{n+1} h^i \sum_{r=0}^{n+2} A_{i,r} \partial^{i+1}_\lambda \partial^{r+1}_\mu \psi \right\|_{W^2_2} \leq N|h|^{n+1} \left\| \psi \right\|_{W^2_{2+n+3}}, \quad (3.14)$$

where $N = N(|\lambda|, |\mu|, d, n)$ and

$$A_{i,r} = \frac{(-1)^{i-r}}{(r+1)!(i-r+1)!}. \quad (3.15)$$

Proof. Clearly, it suffices to prove the lemma for $\phi, \psi \in C^\infty_0(\mathbb{R}^d)$. For $n = 0$ formula (3.11) is obtained by applying the Newton-Leibnitz formula to $\phi(x + \theta h \lambda)$ as a function of $\theta \in [0, 1]$. Applying it one more time derives (3.12) from (3.11) for $n = 0$. After that for $n \geq 1$ one obtains (3.11) and (3.12) by differentiating both parts of these equations written with $n = 1$.

Next by Taylor’s formula for smooth $f(h)$ we have

$$f(h) = \sum_{i=0}^{n} \frac{h^i}{i!} \frac{d^i}{(dh)^i} f(0) + \frac{1}{n!} \int_0^h (h-\theta)^n \frac{d^{n+1}}{(dh)^{n+1}} f(\theta) \, d\theta.$$

By applying this to

$$\delta_{h,\lambda} \phi(x) = \int_0^1 \partial_{\theta} \phi(x + h\theta \lambda) \, d\theta$$

as a function of $h$ we see that

$$\delta_{h,\lambda} \phi(x) = \sum_{i=0}^{n+1} \frac{h^i}{(i+1)!} \partial^{i+1}_\lambda \phi(x) + \frac{h^{n+1}}{n!} \int_0^1 \int_0^1 (1-\theta_2)^n \theta_1^{n+1} \partial^{n+2}_\lambda \phi(x + h\theta_1 \theta_2 \lambda) \, d\theta_1 d\theta_2.$$

Now to prove (3.13) it only remains to use that by Minkowski’s inequality the $W^2_2$-norm of the last term is less than the $W^2_2$-norm of $\partial^{n+2}_\lambda \phi$ times

$$\frac{|h|^{n+1}}{n!} \int_0^1 \int_0^1 (1-\theta_2)^n \theta_1^{n+1} \, d\theta_1 d\theta_2 = \frac{|h|^{n+1}}{(n+2)!}.$$ 

Similarly, by observing that the value at $h = 0$ of the right-hand side of (3.12) is

$$n! \sum_{r=0}^{n} A_{n,r} \partial^{r+1}_\lambda \partial^{n-r+1}_\mu \psi(x)$$

we see that the left-hand side of (3.14) is the $W^2_2$-norm of

$$\frac{h^{n+1}}{n!} \int_0^1 \int_0^1 \int_0^1 (1-\theta_3)^n \theta_1 \partial_{\lambda_1} \partial_{\lambda_2} \partial_{\mu} \psi(x + h\theta_3 (\theta_1 \lambda - \theta_2 \mu)) \, d\theta_1 d\theta_2 d\theta_3.$$
This yields (3.14) in an obvious way.

Remark 3.1. Formula (3.11) with \( n = 1 \) and Minkowski’s inequality imply that
\[
\| \delta_{h,\lambda} \|_{L^2} \leq \| \partial_{\lambda} \phi \|_{L^2}.
\]
By applying this inequality to finite differences of \( \phi \) and using induction we easily conclude that \( W^{l+r}_2 \subset W^{l}_2 \), where for integers \( l \geq 0 \) and \( r \geq 1 \) we denote by \( W^{l,r}_h \) the Hilbert space of functions \( \varphi \) on \( \mathbb{R}^d \) with the norm \( \| \varphi \|_{i,r,h} \) defined by
\[
\| \varphi \|^2_{i,r,h} = \sum_{\lambda_1,\ldots,\lambda_r \in \Lambda} \| \delta_{h,\lambda_1} \cdots \delta_{h,\lambda_r} \varphi \|^2_{W^i_2}.
\]
(3.16)
We also set \( W^{l,0}_h = W^l_2 \). Then for any \( \phi \in W^{l+r}_2 \) we have
\[
\| \varphi \|_{l,h,r} \leq N \| \varphi \|_{W^{l+r}_2},
\]
where \( N \) depends only on \( |\Lambda_0|^2 := \sum_{\lambda \in \Lambda_0} |\lambda|^2 \) and \( r \).

Set
\[
\mathcal{L}_t^{(0)} = \sum_{\lambda,\mu \in \Lambda} a_{t}^{\lambda \mu} \partial_{\lambda} \partial_{\mu}, \quad \mathcal{M}_t^{(0)\rho} = \sum_{\lambda \in \Lambda} b_{t}^{\lambda \rho} \partial_{\lambda}
\]
and for integers \( n \geq 1 \) introduce the operators
\[
\mathcal{L}_t^{(n)} = n! \sum_{\lambda,\mu \in \Lambda_0} a_{t}^{\lambda \mu} \sum_{r=0}^{n} A_{n,r} \partial_{\lambda}^{r+1} \partial_{\mu}^{n-r+1} + (n+1)^{-1} \sum_{\lambda \in \Lambda_0} a_{t}^{\lambda 0} \partial_{\lambda}^{n+1}
\]
\[
+ (n+1)^{-1} \sum_{\mu \in \Lambda_0} b_{t}^{\mu 0} \partial_{\mu}^{n+1},
\]
\[
\mathcal{M}_t^{(n)\rho} = (n+1)^{-1} \sum_{\lambda \in \Lambda_0} b_{t}^{\lambda \rho} \partial_{\lambda}^{n+1},
\]
\[
\mathcal{O}_t^{h(n)} = L_t^h - \sum_{i=0}^{n} \frac{h^i}{i!} \mathcal{L}_t^{(i)}, \quad \mathcal{R}_t^{h(n)\rho} = M_t^{h,\rho} - \sum_{i=0}^{n} \frac{h^i}{i!} \mathcal{M}_t^{(i)\rho},
\]
where \( A_{n,r} \) are defined by (3.15).

Remark 3.2. Formally, for \( n \geq 1 \) the values \( \mathcal{L}_t^{(n)} \phi \) and \( \mathcal{M}_t^{(n)\rho} \phi \) are obtained as the values at \( h = 0 \) of the \( n \)-th derivatives in \( h \) of \( L_t^h \phi \) and \( M_t^{h,\rho} \phi \).

Remark 3.3. Owing to Assumption 2.4 we have
\[
\mathcal{L}_t^{(0)} = \mathcal{L}_t, \quad \mathcal{M}_t^{(0)\rho} = \mathcal{M}_t^{\rho}.
\]
(3.17)
Also observe that in light of Lemma 3.3, under Assumption 2.3, for \( \phi \in W_2^{n+2+l} \) and \( \psi \in W_2^{n+3+l} \) we have
\[
\| \mathcal{O}_t^{h(n)} \psi \|_{W^2_2} \leq N |h|^{n+1} \| \psi \|_{W^{l+n+3}_2},
\]
\[
\| \mathcal{R}_t^{h(n)} \phi \|_{W^2_2} \leq N |h|^{n+1} \| \phi \|_{W^{l+n+2}_2},
\]
(3.18)
where \( N \) denotes constants depending only on \( n, d, l, A_0, \ldots, A_l, \) and \( \Lambda. \)
Let $k \in [1,m]$ be an integer. The functions $u_t^{(1)}, \ldots, u_t^{(k)}$ we need in (2.4) will be obtained as the result of embedding of certain functions $v^{(i)}$ taking values in certain Sobolev spaces. Define $v_t^{(0)}$ as the solution of (2.1) from Theorem 2.1 and for finding $v^{(1)}, \ldots, v^{(k)}$ introduce the following system of stochastic PDEs:

$$
\begin{align*}
    dv_t^{(n)} &= (\mathcal{L}_t v_t^{(n)}) + \sum_{l=1}^{n} C_n^l \mathcal{M}_t^l v_t^{(n-l)} \, dt \\
    &\quad + (\mathcal{M}_t^\rho v_t^{(n)} + \sum_{l=1}^{n} C_n^l \mathcal{M}_t^l v_t^{(n-l)}) \, dw_t^\rho, \quad n = 1, \ldots, k, \\
\end{align*}
$$

(3.19)

where $C_n^l = n(n-1) \cdots (n-l+1)/l!$ is the binomial coefficient.

**Theorem 3.4.** Let Assumptions 2.1, 2.2, and 2.3 (i) hold, $m = m$, and let $1 \leq k \leq m$. Then there exists a unique set $v_t^{(1)}, \ldots, v_t^{(k)}$ of solutions of (3.19) with initial condition $v_0^{(1)} = \ldots = v_0^{(k)} = 0$ and such that $v_t^{(n)} \in \mathbb{W}^{2n+2-n}_{m}(T)$, $n = 1, \ldots, k$. Furthermore, with probability one $v_t^{(n)}$ are continuous $W^{2n+1-n}_{m}$-valued functions and there exists a constant $N$ depending only on $T$, $d$, $\kappa$, $\Lambda$, $m$, and $K_0, \ldots, K_{m+1}, A_0, \ldots, A_m$ such that for $n = 1, \ldots, k$

$$
E \sup_{t \leq T} \|v_t^{(n)}\|^2_{W^{2n+1-n}_{m}} + E \int_0^T \|v_t^{(n)}\|^2_{W^{m+2-n}_{m}} \, dt \leq NK_m^2. 
$$

(3.20)

**Proof.** Notice that for each $n = 1, \ldots, k$ the equation for $v_t^{(n)}$ does not involve the unknown functions $v_t^{(l)}$ with indices $l > n$. Therefore we can prove the solvability of (3.19) and the stated properties of $v_t^{(n)}$ recursively on $n$.

Denote

$$
S^{(n)} = \sum_{i=1}^{n} C_n^i \mathcal{L}_t^{(i)} v_t^{(n-i)}, \quad R^{(n)} = \sum_{i=1}^{n} C_n^i \mathcal{M}_t^{(i)} v_t^{(n-i)},
$$

and first let $n = 1$. By Theorem 2.1 we have $v_0^{(0)} \in \mathbb{W}^{m+2}_{m}(T)$, which owing to Assumption 2.3(i) yields that $S^{(1)} \in \mathbb{W}^{m-1}_{m}(T)$ and $R^{(1)} = (R^{(1)} v_t) \in \mathbb{W}^{m}_{m}(T)$ (here we need the assumption that $m = m$). Hence, it follows again by Theorem 2.1 that there exists a unique $v_t^{(1)} \in \mathbb{W}^{m+1}_{m}(T)$ satisfying (3.19) with zero initial condition. Furthermore, $v_t^{(1)}$ is a continuous $\mathbb{W}^{m}_{m}$-valued function (a.s.) and (3.20) holds with $n = 1$.

Passing to higher $n$ we assume that $m \geq k \geq 2$ and for an $n \in \{2, \ldots, k\}$ we have found $v_t^{(1)}, \ldots, v_t^{(n-1)}$ with the asserted properties. Observe that for $i = 1, \ldots, n$

$$
\|\mathcal{L}_t^{(i)} v_t^{(n-i)}\|_{\mathbb{W}^{m-n}_{m}(T)} \leq N \|v_t^{(n-i)}\|_{\mathbb{W}^{m-n+(i+2)}_{m}(T)} \\
= N \|v_t^{(n-i)}\|_{\mathbb{W}^{m+2-(n-i)}_{m}(T)}, 
$$

(3.21)
\[ \sum_{k=1}^{\infty} \| M^{(i)} v^{(n-i)} \|_{W_2^{m-n+1}(T)}^2 \leq N \| v^{(n-i)} \|_{W_2^{m-n+1+(i+1)}(T)}^2 \]

\[ = N \| v^{(n-i)} \|_{W_2^{m+2-(n-i)}(T)}^2. \]  \hfill (3.22)

It follows by the induction hypothesis that \( S^{(n)} \in W_2^{m-n}(T) \) and \( R^{(n)} \in W_2^{m-n+1}(T) \). By applying Theorem 2.1 we see that there exists a unique \( v^{(n)} \in W_2^{m-n+2}(T) \) satisfying (3.19) with zero initial condition. This theorem also yields the continuity property of \( v^{(n)} \) and an estimate, that combined with (3.21) and (3.22) and the induction hypothesis yields (3.20). This proves the existence. Uniqueness is obtained by inspecting the above proof in which each \( v^{(n)} \) was found uniquely. \( \square \)

**Lemma 3.5.** Let Assumptions 2.1, 2.2, and 2.3 (i) hold and \( m = m \). Let \( l, k \geq 0 \) be integers such that \( l + k + 1 = m \), and let \( v^{(0)}, \ldots, v^{(k)} \) be the functions from Theorem 3.4. Set

\[ r^h_t = v^h_t - v^{(0)}_t - \sum_{1 \leq j \leq k} \frac{h^j}{j!} v^{(j)}_t, \]  \hfill (3.23)

where \( v^h \) is the unique \( L_2 \)-valued solution of (3.1) with initial condition \( u_0 \), \( f^0 = f \) and \( f^\mu = 0 \) for \( \mu \in \Lambda_0 \). Then \( r^h_0 = 0 \), \( r^h \in W_2^{m-k}(T) \), and

\[ dr^h_t = (L^h_t r^h_t + F^h_t) dt + (M^h v^h_t + G^h v^h_t) dw^\rho. \]  \hfill (3.24)

where

\[ F^h_t := \sum_{j=0}^{k} \frac{h^j}{j!} O^{(k-j)} v^{(j)}_t, \quad G^h v^h_t := \sum_{j=0}^{k} \frac{h^j}{j!} R^{(k-j)} v^{(j)}_t. \]

Finally, \( F^h \in W_2^h(T) \) and \( G^h v^h \in W_2^{l+1}(T) \).

**Proof.** Due to Assumptions 2.2 and 2.3(i) we have \( v^h \in W_2^m(T) \), and owing to Assumptions 2.1 and 2.2, by Theorem 2.1 we have \( v^{(0)} \in W_2^{m+2}(T) \). Hence clearly \( r^h \in W_2^m(T) \) when \( k = 0 \), and \( r^h \in W_2^{m-k}(T) \) follows from Theorem 3.4 when \( k \geq 1 \). A direct computation shows that (3.24) holds with \( \hat{F} \) and \( \hat{G} \) in place of \( F \) and \( G \), respectively, where

\[ \hat{F}^h = L^h v^{(0)} - L v^{(0)} + \sum_{1 \leq j \leq k} L^h v^{(j)} \frac{h^j}{j!} - \sum_{1 \leq j \leq k} L v^{(j)} \frac{h^j}{j!} - I^h, \]

\[ G^h v^h = M^h v^h + M v^h + \sum_{1 \leq j \leq k} M^h v^{(j)} \frac{h^j}{j!} - \sum_{1 \leq j \leq k} M v^{(j)} \frac{h^j}{j!} - J^h v^h, \]

with

\[ I^h = \sum_{1 \leq j \leq k} \sum_{i=1}^{j} \frac{1}{i!(j-i)!} L^{(i)} v^{(j-i)} h^i. \]
to estimate (4.2) we observe that for

where, as usual, summations over an empty set mean zero. Notice that

Finally, the last assertion of the lemma immediately follows from Remark 3.3 and Theorem 3.4 (see however the proof of Theorem 4.1).

4. Proof of Theorem 2.3

In this section we suppose that \( m = m \). We start with a result which, as will be seen later, is more general than Theorem 2.3.

**Theorem 4.1.** Let \( m = l + k + 1 \) for some integers \( l, k \geq 0 \), and let Assumptions 2.1, 2.2, 2.3, and 2.4 hold. Then for \( r_t^k \), defined as in Lemma 3.5, we have

\[
E \sup_{t \leq T} \| r_t^k \|_{W_2^l}^2 + E \int_0^T \sum_{\lambda \in \Lambda} \| \delta_h \lambda r_t^h \|_{W_2^l}^2 \, dt \leq N|h|^{2(k+1)}k_m^{-2},
\]  

(4.1)

where \( N \) depends only on \( T, d, \kappa, \Lambda, m \) and \( K_0, \ldots, K_{m+1}, A_0, \ldots, A_m \). Moreover, in the situation of Example 2.2 we have \( v(j) = 0 \) in (3.23) for odd \( j \leq k \).

**Proof.** By Lemma 3.5 we have \( F^h \in W_2^l(T) \) and \( G^h \cdot \in W_2^{l+1}(T) \), which by Lemma 3.5 and Theorem 3.2 yields that the left-hand side of (4.1) is dominated by

\[
NE \int_0^T (\| F_t^h \|_{W_2^l}^2 + \| G_t^h \|_{W_2^l}^2) \, dt.
\]

(4.2)

To estimate (4.2) we observe that for \( j \leq k \) by Remark 3.3 we have

\[
\| O_t^{(k-j)} u_t^{(j)} \|_{W_2^l} \leq N|h|^{k-j+1} \| u_t^{(j)} \|_{W_2^{l+k-j+3}} = N|h|^{k-j+1} \| u_t^{(j)} \|_{W_2^{m+2-j}}.
\]
Upon combining this result with Theorem 3.4 we see that
\[ E \int_0^T \| F_t^h \|^2_{W^2_1} dt \leq N |h|^{2(k+1)} K_m^2. \]
Similarly one can estimate the remaining part of (4.2) thus proving estimate (4.1). Finally, observe that in Example 2.2 we have \( v^h = v^{-h} \) due to the uniqueness of the \( L_2 \)-valued solution for equation (2.2) with initial condition \( u_0 \). Hence (4.1) yields \( v^{(j)} = 0 \) for odd \( j \leq k \). \( \Box \)

By Sobolev’s theorem on embedding of \( W^2_2 \) into \( C_0 \) for \( l > d/2 \) there exists a linear operator \( I : W^2_2 \rightarrow C_0 \) such that \( I \varphi (x) = \varphi (x) \) for almost every \( x \in \mathbb{R}^d \) and
\[
\sup_{\mathbb{R}^d} |I \varphi| \leq N \| \varphi \|_{W^2_2}
\]
for all \( \varphi \in W^2_2 \), where \( N \) is a constant depending only on \( d \) and \( l \). One has also the following lemma on the embedding \( W^2_2 \subset L_2(\mathbb{G}_h) \), that we have already referred to, when we used Remark 2.3 on the existence of a unique \( L_2(\mathbb{G}_h) \)-valued continuous solution \( \{ u_t(x) : x \in \mathbb{G}_h \} \) to equation (2.2).

**Lemma 4.2.** For all \( \varphi \in W^2_2(\mathbb{R}^d) \), \( l > d/2 \), \( |h| \in (0,1) \)
\[
\sum_{x \in \mathbb{G}_h} |I \varphi(x)|^2 h^d \leq N \| \varphi \|^2_{W^2_2},
\]
(4.3)
where \( N \) is a constant depending only on \( d \) and \( l \).

**Proof.** By Sobolev’s embedding of \( W^2_2 \) into \( C_0 \), for \( z \in \mathbb{R}^d \) and smooth \( \varphi \) we have
\[
| \varphi(z) |^2 \leq \sup_{x \in B_1(z)} \varphi^2(z + hx) \leq N \sum_{|\alpha| \leq l} h^{2|\alpha|} \int_{B_1(0)} |(D^\alpha \varphi)(z + hx)|^2 dx
\]
\[
= N \sum_{|\alpha| \leq l} |h|^{2|\alpha| - d} \int_{B_h(z)} |(D^\alpha \varphi)(x)|^2 dx \leq N |h|^{-d} \sum_{|\alpha| \leq l} \int_{B_h(z)} |(D^\alpha \varphi)(x)|^2 dx,
\]
with a constant \( N = N(d,l) \), where \( B_r(z) = \{ x \in \mathbb{R}^d : |x - z| < r \} \). Thus
\[
\sum_{x \in \mathbb{G}_h} |\varphi(z)|^2 h^d \leq N \sum_{|\alpha| \leq l} \sum_{x \in \mathbb{G}_h} \int_{B_h(z)} |(D^\alpha \varphi)(x)|^2 dx
\]
that yields (4.3). \( \Box \)

Set \( R^h_1 = I \varphi_I^h \). Recall that \( \Lambda^0 = \{ 0 \} \), \( \delta_{h,0} \) is the identity operator and \( \delta_{h,\lambda} = \delta_{h,\lambda_1} \cdots \delta_{h,\lambda_n} \) for \( (\lambda_1, \ldots, \lambda_n) \in \Lambda^n, n \geq 1 \). Then we have the following corollary of Theorem 4.1

**Corollary 4.3.** Let the assumptions of Theorem 4.1 hold with \( l > n + d/2 \) for some integer \( n \geq 0 \). Then for \( \lambda \in \Lambda^n \) we have
\[
E \sup_{t \in [0,T]} \sup_{x \in \mathbb{R}^d} |\delta_{h,\lambda} R^h_1(x)|^2 \leq N h^{2(k+1)} K_m^2
\]
with a constant $N$ depending only on $\Lambda$, $d$, $m$, $K_0$, $\ldots$, $K_m$, $A_0$, $\ldots$, $A_m$, $\kappa$, and $T$.

Proof. Set $j = n - l$. Then $j > d/2$ and using Sobolev’s theorem on embedding $W^2_2$ into $C_b$ and taking into account Remark 3.1, from Theorem 4.1 we get

$$E \sup_{t \in [0,T]} \sup_{x \in \mathbb{R}^d} |\delta_{h,\lambda} R^h_t(x)|^2 \leq C_1 E \sup_{t \in [0,T]} \|R^h_t\|^2_{L^2_h},$$

$$\leq C_2 E \sup_{t \in [0,T]} \|R^h_t\|^2_{W^2_2} \leq N h^{2(k+1)} K_m^2,$$

where $C_1$ and $C_2$ are constants depending only on $m$ and $d$, and $N$ is a constant depending only on $m$, $d$, $T$, $\kappa$, $\Lambda$ and $K_i$ for $i \leq m + 1$. Similarly, by Lemma 4.2 and Remark 3.1

$$E \sup_{t \in [0,T]} \sum_{x \in \mathcal{G}_k} |\delta_{h,\lambda} R^h_t(x)|^2 \leq C_1 E \sup_{t \in [0,T]} \|\delta_{h,\lambda} R^h_t\|^2_{W^2_2},$$

$$\leq C_2 E \sup_{t \in [0,T]} \|R^h_t\|^2_{W^2_2} \leq N h^{2(k+1)} K_m^2.$$

\[\square\]

Now we show that Theorem 2.3 follows from the above corollary. We define

$$\hat{u}^h = Iv^h, \quad u^{(j)} = Iv^{(j)}, \quad j = 0, \ldots, k,$$

where $v^h$ is the unique $\mathcal{F}_t$-adapted continuous $L^2(\mathbb{R}^d)$-valued solution of equation (2.2) with initial condition $u_0$, the processes $v^{(0)}, \ldots, v^{(k)}$ are given by Theorem 3.4, and $I$ is the embedding operator from $W^2_2$ into $C_b$. By virtue of Theorem 3.2, $v^h$ is a continuous $W^2_2$-valued process, and by Theorem 3.4 $v^{(j)}, \ j = 1, 2, \ldots, k$, are $W^{2+1-k}_2$-valued continuous processes. Since $l > d/2$ and $n + 1 - k > d/2$, the processes $\hat{u}^h$ and $u^{(j)}$ are well-defined and clearly (3.23) implies (2.4) with $\hat{u}^h$ in place of $u^h$. To show that Corollary 4.3 yields Theorem 2.3 we need only show that almost surely

$$\hat{u}^h_t(x) = u^h_t(x) \quad \text{for all } t \in [0,T] \quad (4.4)$$

for each $x \in \mathcal{G}_h$, where $u^h$ is the unique $\mathcal{F}_t$-adapted $L^2$-valued continuous solution of (2.2). To see this let $\varphi$ be a compactly supported nonnegative smooth function on $\mathbb{R}^d$ with unit integral, and for a fixed $x \in \mathcal{G}_h$ set

$$\varphi_\varepsilon(y) = \varphi((y - x)/\varepsilon)$$

for $y \in \mathbb{R}^d$ and $\varepsilon > 0$. Since $\hat{u}^h$ is a continuous $L^2$-valued solution of (2.2), for each $\varepsilon$ almost surely

$$\int_{\mathbb{R}^d} \hat{u}^h_t(y) \varphi_\varepsilon(y) \, dy = \int_{\mathbb{R}^d} \hat{u}_t(y) \varphi_\varepsilon(y) \, dy + \int_0^t \int_{\mathbb{R}^d} (L^h_s \hat{u}^h_s(y) + f_s(y)) \varphi_\varepsilon(y) \, dy \, ds$$
for all \( t \in [0, T] \). Letting here \( \varepsilon \to 0 \) we see that both sides converge in probability, uniformly in \( t \in [0, T] \), and thus we get that almost surely
\[
\hat{u}_t^h(x) = u_0(x) + \int_0^t \left[ L^h_s \hat{u}_s^h(x) + f_s(x) \right] ds + \int_0^t \left[ M^h_s \hat{u}_s^h(x) + g^s(x) \right] dw^s_s
\]
for all \( t \in [0, T] \). (Remember that \( u_0, f \) and \( g \) are continuous in \( x \) by virtue of Remark 2.1.) Moreover, owing to Lemma 4.2 the restriction of \( \hat{u}_t \) onto \( G_h \) is a continuous \( l^2(G_h) \)-valued process. Hence, because of the uniqueness of the \( l^2(G_h) \)-valued continuous \( \mathcal{F}_t \)-adapted solution of (2.2) for any \( l^2 \)-valued \( \mathcal{F}_0 \)-measurable initial condition, we have (4.4), that finishes the proof Theorem 2.3.

Theorem 2.3 yields the following generalisation of Theorem 2.4.

**Theorem 4.4.** Let the conditions of Theorem 2.3 hold with \( n = 0 \). Then
\[
E \sup_{t \leq T} \sup_{x \in G_h} |\hat{u}_t^h(x) - u_t^0(x)|^2 + E \sup_{t \leq T} \sum_{x \in G_h} |\hat{u}_t^h(x) - u_t^0(x)|^2 |h|^d \leq N |h|^{2(k+1)} K_m^2,
\]
where \( \hat{u}_t^h \) is defined by (2.9) and \( N \) depends only on \( \Lambda, d, m, K_0, \ldots, K_{m+1}, A_1, \ldots, A_m, \kappa, \) and \( T \). In the situation of Example 2.2 estimate (4.5) holds also for \( \tilde{u}_t^h \), defined by (2.9), in place of \( \hat{u}_t^h \).

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