INDIVIDUAL FAIRNESS IN PIPELINES

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ABSTRACT. It is well understood that a system built from individually fair components may not itself be individually fair. In this work, we investigate individual fairness under pipeline composition. Pipelines differ from ordinary sequential or repeated composition in that individuals may drop out at any stage, and classification in subsequent stages may depend on the remaining “cohort” of individuals. As an example, a company might hire a team for a new project and at a later point promote the highest performer on the team. Unlike other repeated classification settings, where the degree of unfairness degrades gracefully over multiple fair steps, the degree of unfairness in pipelines can be arbitrary, even in a pipeline with just two stages.

Guided by a panoply of real-world examples, we provide a rigorous framework for evaluating different types of fairness guarantees for pipelines. We show that naïve auditing is unable to uncover systematic unfairness and that, in order to ensure fairness, some form of dependence must exist between the design of algorithms at different stages in the pipeline. Finally, we provide constructions that permit flexibility at later stages, meaning that there is no need to lock in the entire pipeline at the time that the early stage is constructed.

1. INTRODUCTION

As algorithms reach ever more deeply into our daily lives, there is increasing concern that they be fair. The study of the theory of algorithmic fairness was initiated by Dwork et al. [5], who introduced the solution concept of individual fairness. Roughly speaking, individual fairness requires that similar individuals receive similar distributions on outcomes. Dwork and Ilvento [6] examined the behavior of individual fairness (and various group notions of fairness) under composition. They showed that although competitive composition, i.e. when two different tasks “compete” for individuals, can result in arbitrarily bad behavior under composition, fairness under simple repeated or sequential classifications (for the same task) degrades gracefully, similar to degradation of differential privacy loss under multiple computations. In this work we expand the investigation of individual fairness under sequential composition to the case of cohort pipelines. Cohort pipelines differ from ordinary sequential composition in that each stage of the pipeline considers only the remaining cohort of individuals and may change its classification strategy conditioned on the set of individuals remaining.

Cohort pipelines are common: many data-driven systems consist of a sequence of cohort selection or filtering steps, followed by decision or scoring steps. A running exemplary scenario in this work will be a two-stage cohort pipeline: a company hires a team (cohort) of individuals to work on a project and subsequently promotes the highest performer on the team to a leadership position. Although the team selection may be fair in the sense that similarly qualified candidates have similar chances of being chosen for the team, the selection of the highest performer critically depends on the other members of the team. As we will see, being compared fairly to other members of the cohort in each stage doesn’t imply fairness of the entire pipeline, as the competitive landscape can vary between similar individuals.

Indeed, a fair cohort selection mechanism [6] can exploit the “myopic” nature of the promotion stage to skew overall fairness. This can happen either through good intentions (e.g., choosing teams so that

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1 Note that although fairness degrades gracefully in these scenarios, it does not rule out the existence of feedback loops which arbitrarily amplify unfairness, see e.g. [12][20].
members of a minority group always have a mentor on the team) or malice (e.g., ensuring that minority candidates are almost always paired with a more qualified majority candidate): in both these cases minorities suffer significantly reduced chances of promotion. Unlike other repeated classification settings in which the degree of unfairness of multiple fair steps degrades gracefully, the degree of unfairness in cohort pipelines can be arbitrary, even in a pipeline with just two stages. Furthermore, we demonstrate that construction of malicious pipelines under naïve auditing of fairness is straightforward and both computationally and practically feasible.

In this work we examine the subtle issues that arise in cohort-based pipelines, focusing on short pipelines consisting of a single cohort selection step followed by a scoring step. We formalize fairness desiderata capturing the issues unique to pipelines (not shared by ordinary sequential composition), and give constructions for robust cohort selection mechanisms that behave well under (i.e., are robust to) pipeline composition with a variety of future scoring policies. In particular, we demonstrate that it is possible to design cohort selection mechanisms that are robust to a rich family of subsequent scoring functions given a simple description of a policy governing the behavior of the family. This provides, for example, a means for enabling a company to choose an individually fair hiring procedure that will be robust to many possible compensation functions (all adhering to the policy) chosen at a later date. Guided by a panoply of real-world examples, this work provides a rigorous framework for evaluating and ensuring different types of fairness guarantees for pipelines.

We now summarize our contributions. First, we formalize what it means for the outcomes of a pipeline, which include both the outcome of the initial cohort selection step and the score conditioned on being chosen, to be fair. We then extend this fairness notion to describe how a cohort selection mechanism can be robust to a scoring policy, i.e. to compose fairly with any cohort scoring function chosen from a permissible set. Although the choice of scoring function may not depend on the cohort, the scores assigned to any individual may be highly dependent on their cohort “context.” Second, we determine how the scoring policy imposes conditions on the cohort selection mechanism. In particular, we show that there is a natural way to describe the set of cohort contexts in which similar individuals are treated similarly by all functions permitted by the policy, and we demonstrate that assigning similar individuals to similar distributions over cohort contexts is sufficient (and sometimes necessary) to ensure pipeline robustness. Third, we provide constructions for cohort selection mechanisms which are both robust to a rich set of practical scoring policies and permit flexibility in selection of the original cohort.

2. Model and Definitions

2.1. Preliminaries. We base our model on individual fairness, as proposed in [5]. The intuition behind individual fairness is that “similar individuals should be treated similarly.” What constitutes similarity for a particular classification task is provided by a metric which captures society’s best understanding of who is similar to whom. Below we formally define individual fairness as in [5] with a natural Lipschitz relaxation.

**Definition 2.1 (α-Individual Fairness [5]).** Given a universe of individuals $U$, and a metric $\mathcal{D}: U \times U \rightarrow [0, 1]$ for a classification task with outcome set $O$, and a distance metric $d: \Delta(O) \times \Delta(O) \rightarrow [0, 1]$ over distributions over outcomes, a randomized classifier $C: U \rightarrow \Delta(O)$ is $\alpha-$individually fair if and only if for all $u, v \in U$, $d(C(u), C(v)) \leq \alpha \mathcal{D}(u, v)$.

We use the phrase “similar individuals are treated similarly” as a shorthand for the individual fairness Lipschitz condition. Individual fairness was originally proposed in the context of independent classification, i.e. each individual is classified exactly once, independently of all others. However, in many practical settings individuals cannot be classified independently, particularly when there are a limited number of positive classifications available (e.g. a university which can only accept a limited number of students

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2See Appendix A for additional examples.

3Formally, we can think of a policy as a description of a set of permitted scoring functions.

4Bower et al. consider fairness in pipelines for a group-based definition of fairness, and primarily consider the accuracy of the final pipeline decision [1].
**Definition 2.2** (Cohort Selection Problem [6]). Given a universe $U$ of individuals, an integer $n$, and a task with metric $\mathcal{D}$, select a cohort $C \subseteq U$ of exactly $n$ individuals such that $|\Pr[u \in C] - \Pr[v \in C]| \leq \mathcal{D}(u,v)$. We call such a mechanism an **individually fair cohort selection mechanism**.

Our work extends the investigation into fair composition by considering composition within a pipeline of cohort selection and scoring steps. We focus on the case of a two-step pipeline, and we assume for simplicity that the metric for the cohort selection and scoring functions are the same.

**Definition 2.3** (Two-stage Cohort pipeline). Given a universe of individuals $U$, a two-stage cohort pipeline consists of: a set of permissible cohorts $\mathcal{C} \subseteq \text{Pow}(U) \setminus \emptyset$ (where $\text{Pow}(U)$ indicates the power set of $U$), a single (randomized) cohort selection mechanism $A$ which outputs a single cohort $C \subseteq \mathcal{C}$, a set of scoring functions $\mathcal{F} : \mathcal{C} \times U \rightarrow [0,1]$, and a scoring function $f \in \mathcal{F}$. The two-stage cohort pipeline procedure is $A \circ f$.

We now briefly introduce supporting terminology (summarized in Table 1). For $C \in \mathcal{C}$, let $\lambda(C) \in [0,1]$ denote the probability that $A$ outputs $C$, where the probability is over the randomness in the cohort selection mechanism $A$ operating on the universe $U$. We denote the set of cohorts containing $u$ as $\mathcal{C}_u$, and the probability that $A$ selects $u$ can be expressed $p(u) = \sum_{C \in \mathcal{C}_u} \lambda(C)$. As initial constraints on $A$ and $\mathcal{F}$, we assume that $A$ is an individually fair cohort selection mechanism and that each $f \in \mathcal{F}$ is individually fair within the cohort it observes, i.e., it is **intra-cohort individually fair**:

**Definition 2.4** (Intra-cohort individual fairness). Given a cohort $C$, a scoring function $f : \mathcal{C} \times U \rightarrow [0,1]$ is **intra-cohort individually fair** if for all $C \in \mathcal{C}$, $\mathcal{D}(u,v) \geq |f(C,u) - f(C,v)|$ for all $u,v \in C$.

Although intra-cohort fairness constrains $f$ to be individually fair within a particular cohort, $f(C_1,u)$ can differ arbitrarily from $f(C_2,u)$ if $C_1 \neq C_2$. For ease of exposition we sometimes refer to $C$ as the “cohort context” or simply the “context” of $u$ for $u \in C$.

**Remark 2.5** (Intra-cohort individual fairness is insufficient.). A pipeline consisting of an individually fair cohort selection mechanism and intra-cohort individually fair scoring function may result in arbitrarily unfair treatment. For example, suppose $\mathcal{X} = \{X_1, X_2, \ldots\}$ is a partition of $U$, and $A$ chooses a cohort $X_i$ uniformly at random. Suppose $f$ assigns score 1 to all members of the cohort corresponding to $X_1$, and otherwise assigns score 0. $A$ is not only individually fair, it selects each element with an equal probability; $f$ is not only intra-cohort individually fair, it treats all members of a given cohort equally; yet the pipeline can result in arbitrarily large differences in scores for similar individuals. Furthermore, this observation holds for
any partition including adversarially chosen partitions. Although this abstract example suffices to prove the point, we include an extensive set of realistic pipeline examples, analogous to the “Catalog of Evils” of [5], in Appendix A. We also include a practical method for malicious pipeline construction in Appendix C.

An important part of the pipeline definition is the contextual behavior of \( f \), i.e., the behavior of the second stage of the pipeline may depend on the selected cohort \( C \). The simplistic solution to this problem is to design and evaluate the whole pipeline for fairness as a single unit, i.e. requiring that similar individuals have similar distributions over \( \Delta(O_{pipeline}) \). Although such evaluation would catch unfairness, it (1) doesn’t provide explicit guidance for designing any given component, (2) may miss certain pipeline-specific fairness issues (see Examples 2.7 and 2.9), and (3) “locks” the pipeline into a single monolithic strategy, which is highly impractical. For example, employers frequently need to change compensation policies due to changing market conditions. However, changing compensation policies due to disliking a particular member of a cohort, e.g. switching to equal bonuses for all team members if the company does not like the individual who would have received the largest bonus, is not permitted in our model. Indeed, later stages in the pipeline may be completely ignorant of the existence of prior stages, e.g. a manager deciding on employee compensation may be unaware of automated resume screening.

This motivates our design goal of robustness: designing the cohort selection mechanism \( A \) which composes well with every function in \( \mathcal{F} \), rather than expecting the scoring function to properly analyze and respond to the choices made in the original cohort selection mechanism design. As a result, the only communication necessary between the steps is the description of \( \mathcal{F} \). With this in mind, a deceptively(!) simple extension of Definition 2.1 gives our fairness desideratum for pipelines.

**Definition 2.6 (\( \alpha \)-Individual Fairness and Robustness for Pipelines (informal)).** Consider the pipeline consisting of \((\mathcal{C}, A, \mathcal{F})\), with outcome space \( O_{pipeline} \). For \( f \in \mathcal{F} \), the pipeline instantiated with \( f \) satisfies \( \alpha \)-individual fairness with respect to the similarity metric \( \mathcal{D} \) and a distance measure \( d : \Delta(O_{pipeline}) \times \Delta(O_{pipeline}) \to [0, 1] \) if \( \forall u, v \in U, d([f \circ A](u), [f \circ A](v)) \leq \alpha \mathcal{D}(u, v) \).

If the pipeline satisfies \( \alpha \)-individual fairness with respect to every \( f \in \mathcal{F} \), i.e., if \( \forall f \in \mathcal{F} \) and \( \forall u, v \in U, d([f \circ A](u), [f \circ A](v)) \leq \alpha \mathcal{D}(u, v) \), we say that \( A \) is \( \alpha \)-robust to \( \mathcal{F} \) with respect to \( d, \mathcal{D} \).

We model the contextual nature of the problem by allowing the behavior of each \( f \in \mathcal{F} \) to depend on the cohort, rather than allowing \( f \) to be chosen adaptively in response to the selected cohort. This modeling choice still allows us to capture the contextual nature of scoring policies, while keeping our abstractions clean.

2.2. **Fairness of pipelines.** Lurking in this informal definition are two subtle choices critical to pipeline fairness: (1) how should distributions over \( O_{pipeline} \) be interpreted, and (2) what distance measure \( d \) is appropriate for measuring differences in distributions over \( O_{pipeline} \). In the remainder of this section, we consider these two questions and frame the notion of robustness parametrized by the two axes: distribution and distance measure over distributions.

2.2.1. **Choosing the interpretation of the distribution.** To account for the fact that individuals not selected by \( A \) never receive a score from \( f \) the relevant outcome space is the union of possible scores and “not selected,” i.e. \( O_{pipeline} := [0, 1] \cup \{ \perp \} \). Thus conditioning on whether an individual was selected or not changes the interpretation of the distribution over the outcome space and, more importantly, changes the perception of fairness.

**Example 2.7 (Perception of conditional probability).** Suppose Alice (a) and Bob (b) are similar but not equal job candidates, i.e. \( \mathcal{D}(a, b) \in (0, 0.1) \). Consider an individually fair cohort selection mechanism, \( A \) which either selects a cohort containing one of Alice or Bob or neither and satisfies \( p(a) = p(b) = p^* \). Consider the fairness constraint on the scoring function \( f \) for the unconditional distribution over \( O_{pipeline} : |p(a)f(a) - p(b)f(b)| \leq \mathcal{D}(a, b) \), which simplifies to \( p^*|f(a) - f(b)| \leq \mathcal{D}(a, b) \). (Note: as Alice and

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\(^5\)See Appendix A for explicit examples of modeling adaptation to changing market conditions.
Bob never appeared together in a cohort, there is no intra-cohort fairness condition.) The constraint on the difference in treatment by $f$ is essentially diluted by a factor of $p^*$. Enforcing fairness on the unconditional distribution essentially allows the company to hand out job offers of the following form: “Congratulations you are being offered a position at Acme Corp., you can expect a promotion after one year with probability $x\%$.” Alice and Bob may receive offers will equal probability, but the values of $x$ printed on the offer may be wildly different, and as such they will perceive the value of the job offer differently.

The choice of conditional or unconditional distribution boils down to what perception of fairness is important. In the case of bonuses or promotions awarded long after hiring, the conditional perception may be particularly important. However, on shorter time frames or if the only consequential outcome is the final score, the unconditional distribution may be more appropriate (e.g. resume screening immediately followed by interviews).\footnote{Although in this work we consider pipelines with a single relevant metric, the conditional versus unconditional question is critically important when metrics differ between stages of the pipeline. For example, the metric for selecting qualified members of a team may be different than the metric for choosing an individual from the team to be promoted to a management role, as the two stages in the pipeline require different skillsets.}

We consider two approaches which capture these different perspectives: the unconditional distribution $S_{u}^{N,A,f}$, treats the $\perp$ outcome as a score of 0 and the conditional distribution $S_{u}^{C,A,f}$ conditions on $u$ being selected in the cohort. More formally:

**Definition 2.8 (Conditional and unconditional distributions).** Let $S_{u}^{A,f} \in \Delta(O_{\text{pipeline}})$ be the distribution over outcomes arising from the pipeline, i.e. $f \circ A$. $S_{u}^{N,A,f}$ places a probability of 1 $- p(u)$ on $\perp$, and for $s \in [0,1]$, $S_{u}^{A,f}$ places a probability of $\sum_{C \in \Theta} \Pr[f(C,u) = s | A(C)]$ on $s$.

- The unconditional distribution $S_{u}^{N,A,f}$ is identical to $S_{u}^{A,f}$ with the exception that it treats the $\perp$ outcome as if it had score 0. That is, for $0 < s \leq 1$, $S_{u}^{N,A,f}$ places a probability of $\sum_{C \in \Theta} \Pr[f(C,u) = s | A(C)]$ on $s$; at $s = 0$, $S_{u}^{N,A,f}$ has a probability of $1 - p(u) + \sum_{C \in \Theta} \Pr[f(C,u) = 0 | A(C)]$.
- The conditional distribution $S_{u}^{C,A,f}$ has probability $\frac{\sum_{C \in \Theta} \Pr[f(C,u) = s | A(C)]}{p(u)}$ for each score $s \in [0,1]$, i.e., it is $S_{u}^{A,d,f}$ conditioned on the positive outcome of $A(C)$.

Each of these approaches can be viewed as a method for converting a distribution $S_{u}^{A,f}$ over $O_{\text{pipeline}}$ to distributions $S_{u}^{C,A,f}$ and $S_{u}^{N,A,f}$ over $[0,1]$.

**2.2.2. Distance measures over distributions.** The natural approach for measuring distances between distributions would be to use expectation: that is, $d^{\text{uncond}}(S_{u}^{A,f},S_{v}^{A,f}) := \left| E[S_{u}^{N,A,f}] - E[S_{v}^{N,A,f}] \right|$ and $d^{\text{cond}}(S_{u}^{A,f},S_{v}^{A,f}) := \left| E[S_{u}^{C,A,f}] - E[S_{v}^{C,A,f}] \right|$. Difference in expectation generally captures the unfairness in the examples discussed thus far. However, a subtle issue can arise from the certainty of outcomes, which requires greater insight into the distribution of scores.

**Example 2.9 (Certainty of outcomes).** Consider two equally qualified job candidates, Charlie and Danielle. As these two candidates are equally qualified, they should clearly be offered jobs and promotions with equal probability. Recall the company’s pleasant form letter for job offers from Example 2.7, “Congratulations you are being offered a position at Acme Corp., you can expect a promotion after one year with probability $x\%$.” Danielle receives an offer with $x = 70\%$ (with probability $p^*$), but Charlie receives either an offer with $x = 100\%$ (with probability $0.7p^*$) or an offer with $x = 0\%$ (with probability $0.3p^*$). Although both are offered jobs with equal probability and their expectations of promotion are equal, Charlie’s offers have certainty of promotion (or no promotion) whereas Danielle’s promotion fate is uncertain.\footnote{This definition is not defined if $p(u) = 0$, since it does not make sense to consider a “conditional distribution” if $u$ is never selected to be in the cohort (and thus never receives a score). In defining robustness of a cohort selection mechanism, we should thus restrict to considering $u \in U$ where $p(u) > 0$ (and individual fairness of the cohort selection mechanism on its own would provide fairness guarantees over the probabilities $p(u)$). For simplicity, we do not explicitly mention this modification.}
As Example 2.9 illustrates, expected score does not entirely capture problems related to the distribution of scores rather than the average score. Although total-variation distance is a natural choice for evaluating such distributional differences, it is too strong for this setting. For example, if Charlie receives a score of 0.7 with probability 1 (over randomness of the entire pipeline), while Danielle receives a score of 0.7 – ε with probability 0.5 and a score of 0.7 + ε with probability 0.5, then the total variation distance would be 1, though these outcomes are intuitively very similar. We therefore introduce the notion of mass-moving distance over probability measures. Mass-moving distance combines total variation distance with earthmover distance to reflect that similar individuals should receive similar distributions over close (rather than identical) sets of scores.

**Definition 2.10 (Mass-moving distance).** Let γ1 and γ2 be probability mass functions over finite sets Ω1 ⊆ [0, 1] and Ω2 ⊆ [0, 1], respectively. Let V ⊆ [0, 1] be the set of real values v ∈ [0, 1] such that there exist probability mass functions ˜γ1 and ˜γ2 over [0, 1] with finite supports ˜Ω1 and ˜Ω2, respectively, where:

1. **Nothing moves far and mass is conserved.** For i = 1, 2, there is a function Zi : [0, 1] → Δ(˜Ωi) such that:
   - (a) **Nothing moves far.** For all x ∈ [0, 1] and y ∈ Supp(zi(x)), it holds that |x − y| ≤ 0.5v.
   - (b) **Mass is conserved.** For all y ∈ ˜Ωi, it holds that ˜γi(y) = Σx∈Ωi z∗i(y)γi(x), where z∗i is the probability mass function of the distribution Zi(x).

2. **Total variation distance is small.** It holds that 0.5v ≥ TV(γ1, γ2) := 1/2Σw∈Ω1∪Ω2 |γ1(w) − γ2(w)|.

Then we let MMD(γ1, γ2) = inf(V).

A simple way to think about mass-moving distance is to break the definition down into two steps: (1) transforming the original distributions over scores into distributions over a single shared set of adjusted scores and (2) moving mass between the distributions over adjusted scores.

Since there is a natural association between probability distributions over [0, 1] and probability mass functions over [0, 1], Definition 2.10 also gives a notion of distance between probability distributions.

In the example of Charlie and Danielle receiving scores of 0.7 or 0.7 ± ε described above, the mass-moving distance is at most 2ε since ˜γ1 and ˜γ2 can both be taken to be the probability measure that places the full mass of 1 on 0.7.

Using mass-moving distance, we specify two additional complementary distance measures:

\[ d_{\text{cond}, \text{MMD}}(s_u^{A,f}, s_v^{A,f}) := \text{MMD}(s_u^{A,f}, s_v^{A,f}) \text{ and } d_{\text{uncond}, \text{MMD}}(s_u^{A,f}, s_v^{A,f}) := \text{MMD}(s_u^{A,f}, s_v^{A,f}). \]

### 2.3. Robustly fair pipelines

Recall our informal notion that a cohort selection mechanism A is robust to a family of scoring functions F if the composition of A and any f ∈ F is individually fair. We can now formalize robustness as either conditional or unconditional with respect to either expected score or mass moving distance over score distributions. By evaluating the properties of each combination of distribution and distance measure, we can capture a range of subtle fairness desiderata in pipelines.

**Definition 2.11 (Robust pipeline fairness).** Given a universe U, a metric D, let A be an individually fair cohort-selection mechanism and let F be a collection of intra-cohort individually fair scoring functions C × U → [0, 1]. Choose \( d ∈ \{ d_{\text{cond}, E}, d_{\text{uncond}, E}, d_{\text{cond}, \text{MMD}}, d_{\text{uncond}, \text{MMD}} \} \), a distance measure over S_u^{A,f}. We say A is α-robust w.r.t F for \( d(S_u^{A,f}, S_v^{A,f}) ≤ αD(u, v) \) for all \( u, v ∈ U \) and for all \( f ∈ F \).

Throughout the rest of this work, we will examine robustness properties in terms of particular settings of d. As one might expect, mass moving distance over score distributions is a stronger condition than expected score, and conditional robustness implies unconditional robustness up to a Lipschitz relaxation.

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8We slightly abuse notation and use MMD(Ξ1, Ξ2) for probability distributions Ξ1 and Ξ2, to denote MMD(γ1, γ2) where γ1 is the probability mass function associated to Ξ1 and γ2 is the probability mass function associated to Ξ2.

9Note that these choices for d are not the only possible choices, and the framework can be extended to different choices of distribution and distance measure to address other fairness concerns.

10See Propositions E.2 and E.4. Interestingly, we show in Theorem B.6 that for some classes of score functions, guaranteeing individual fairness w.r.t. mass-mover distance fairness is “equivalent” to guaranteeing individual fairness w.r.t expected score.
3. CONDITIONS FOR SUCCESS

In this section, we describe conditions on \( A \) that will result in our desired robustness properties with respect to a class of scoring functions \( \mathcal{F} \). We first consider the description of \( \mathcal{F} \) available to \( A \), i.e. the policy. The simplest method of specifying the policy by describing all \( f \in \mathcal{F} \) prohibits adding \( f \) with similar or identical fairness properties to \( \mathcal{F} \) at a later point and is highly unrealistic (and potentially intractable). In practice, we expect policies to govern how differently the policy will treat individuals within different contexts, rather than enumerating the permitted functions. To that end, we propose policies in the form of a distance function over \((\text{cohort}, \text{individual})\) pairs, \( \delta^\mathcal{F} : (\mathcal{C} \times U) \times (\mathcal{C} \times U) \rightarrow [0,1] \). This distance function specifies the maximum difference in score between two (cohort, individual) pairs \( \delta^\mathcal{F}((C_1,u),(C_2,v)) := \sup_{f \in \mathcal{F}} |f(C_1,u) - f(C_2,v)| \). \( \delta^\mathcal{F} \) captures the salient fairness behavior of the family of scoring functions, while being succinct in comparison to maintaining a list of all supported \( f \) directly. In fact, as we will show in Lemma 3.2, a partial description or an overestimate of \( \delta^\mathcal{F} \) will also suffice. To illustrate our policy descriptions, consider the following two families:

1. \( \mathcal{F}_1 \) ignores the cohort context entirely, and treats each \( u \in U \) the same regardless of the cohort, i.e. \( \mathcal{F}_1 = \{ f \mid \exists g : U \rightarrow [0,1] \text{ s.t. } f(C,u) = g(u) \text{ for all } (C,u) \in \mathcal{C} \times U \} \).
2. \( \mathcal{F}_2 \) treats \( u \) and \( v \) similarly within the same context, but has no constraint on treatment in different contexts, i.e. \( \mathcal{F}_2 = \{ f \mid f((C\setminus\{u\}) \cup \{v\},v) - f(C,u) \leq D(u,v) \text{ for all } u,v \in U \text{ and } \forall C \in \mathcal{C} \text{ s.t. } u \in C, v \notin C \} \).

Recall that intra-cohort individual fairness requires that the scoring functions in both families must treat similarly within the same context, but has no constraint on treatment in different contexts, i.e. \( \mathcal{F}_2 = \{ f \mid f((C\setminus\{u\}) \cup \{v\},v) - f(C,u) \leq D(u,v) \text{ for all } u,v \in U \text{ and } \forall C \in \mathcal{C} \text{ s.t. } u \in C, v \notin C \} \).

For the family \( \mathcal{F}_1 \), we observe that \( \delta^{\mathcal{F}_1}((C_1,u),(C_2,v)) = D(u,v) \), and, intuitively, the designers of \( A \) will not need to consider the behavior of \( \mathcal{F} \) in their design of \( A \). On the other hand, for \( \mathcal{F}_2 \), we observe that \( \delta^{\mathcal{F}_2}((C,u),(C,v)) = D(u,v) \) for any cohort \( C \), but \( \delta^{\mathcal{F}_2}((C,u),(C',v)) \) can be much greater than \( D(u,v) \) for \( C' \neq C \). For this reason, composition planning for \( A \) is non-trivial. As one would expect, \( \delta^\mathcal{F} \) heavily influences the strength of conditions on \( A \).

3.1. \( A \)’s Task: Designing Mechanisms Compatible with \( \delta^\mathcal{F} \). We now describe how to design \( A \) to guarantee robustness with respect to \( \mathcal{F} \), given (possibly overestimates of) the distance function \( \delta^\mathcal{F} \) over (cohort, individual) pairs describing \( \mathcal{F} \). The conditions on \( A \) will roughly consist of making sure that \( A \) assigns similar individuals to similar distributions over cohort contexts, where similarity of (cohort, individual) pairs is defined with respect to \( \delta^\mathcal{F} \).

Although \( \delta^\mathcal{F} \) is a succinct description of a policy, it is more intuitive when designing with composition in mind to translate \( \delta^\mathcal{F} \) into a set of “mappings” specifying which (cohort, individual) pairs will be treated similarly by \( f \in \mathcal{F} \). That is, for each pair \( u,v \in U \), we can describe \( \delta^\mathcal{F} \) as a partitioning \( \mathcal{P}_{u,v} \) of \((\mathcal{C} \times u) \cup (\mathcal{C} \times v)\) such that each partition or “cluster” has small diameter with respect \( \delta^\mathcal{F} \), i.e. within a cluster \( \delta^\mathcal{F}((C_1,u),(C_2,v)) \leq D(u,v) \). The collection of partitions over all pairs of individuals then defines the mapping.

**Definition 3.1** (Mapping based on \( \delta \)). For each pair of distinct individuals \( u \) and \( v \), consider the subset \( \mathcal{P}_{u,v} := (\mathcal{C} \times \{u\}) \cup (\mathcal{C} \times \{v\}) \) of (cohort, individual) pairs. Consider a partition of \( \mathcal{P}_{u,v} \) into clusters that respects \( \delta \), i.e. that satisfies the following condition: if \( (C_1,x),(C_2,y) \) are in the same cluster, then \( \delta((C_1,x),(C_2,y)) \leq D(u,v) \). Let \( n_{u,v} \) and \( n_{u,v} \) be the number of clusters of the partition. We call a collection of such partitions for each pair \( u,v \neq U \) a mapping of \( \mathcal{C} \) that respects \( \delta \).

Mappings interact well with distance functions \( \delta' \) that overestimate \( \delta^\mathcal{F} \), as larger distances between (cohort, individual) pairs imposes more strict conditions on cluster membership. Lemma 3.2 states that a mapping that respects \( \delta' \) will also respect \( \delta^\mathcal{F} \), although the resulting conditions on the mapping might be more restrictive.

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Note that \( x,y \in \{u,v\} \). Recall that \( (C_1,u) \) and \( (C_2,u) \) may appear in the same cluster, and thus it is possible that \( x = y \).
Lemma 3.2. Let $\delta': (\mathcal{C} \times U) \times (\mathcal{C} \times U) \to [0,1]$ be a distance function. Suppose that $\delta'$ has the property that for all pairs of cohort contexts $(C_1,x),(C_2,y) \in \mathcal{C} \times U$, it holds that $\delta'((C_1,x),(C_2,y)) \geq \delta''((C_1,x),(C_2,y))$. If a mapping respects $\delta'$, then the mapping also respects $\delta''$. 

Proof. Consider any pair of individuals $u$ and $v$, and consider any mapping that respects $\delta'$. In the partition corresponding to $u$ and $v$, if $(C_1,x)$ and $(C_2,y)$ are in the same cluster, then it holds that $\delta''((C_1,x),(C_2,y)) \leq \delta'((C_1,x),(C_2,y)) \leq D(u,v)$. Thus, the mapping respects $\delta''$, as desired. □

We now briefly introduce supporting terminology for policies and mappings (summarized in Table 2). To succinctly refer to the clusters in a mapping, we define label functions $M_{u,v}: \mathcal{C}_u \to \mathbb{N}$ and $M_{v,u}: \mathcal{C}_v \to \mathbb{N}$ such that $M_{u,v}(C)$ is the label of the cluster containing $(C,u)$ and $M_{v,u}(C)$ is the label of the cluster containing $(C,v)$. We use $n_{u,v}$ (or $n_{v,u}$) to denote the number of clusters in a mapping. We also refer to the set of functions $(M_{u,v})_{u \neq v \in U}$, which entirely specify the partitions, as a mapping. Valid mappings for $\delta$ are not necessarily unique, as there may be more than one way to partition $\mathcal{P}_{u,v}$ into clusters with diameter bounded by $D(u,v)$. We let $\mathcal{M}_\delta$ be the set of mappings that respect $\delta$.

Given a mapping of $\delta''$ (or of an overestimate $\delta'$), we can now interpret “distributions over cohorts” induced by $A$ as “distributions over clusters” induced by $A$. Formally, we convert the distributions over cohorts into measures over $[n_{u,v}]$ for each pair $(u,v) \in U \times U$. As a result, “similar distributions over cohorts” will turn out to mean “similar measures over $[n_{u,v}]$.”

Definition 3.3. Let $(M_{u,v})_{u \neq v \in U}$ be a mapping of $\mathcal{C}$. For $u,v \in U$, we define measures $q_{u,v}^1$ and $q_{u,v}^2$ over the sample space $[n_{u,v}]$ as follows:

1. The unconditional measure over cohorts $q_{u,v}^1$ on the sample space $[n_{u,v}]$ for each $(u,v)$ ordered pair is defined as follows. For $i \in [n_{u,v}]$, we let $q_{u,v}^1(i) = \sum_{C \in \mathcal{C}, M_{u,v}(C) = i} A(C)$.

2. The conditional measure over cohorts $q_{u,v}^2$ on the sample space $[n_{u,v}]$ for each $(u,v)$ ordered pair is defined as follows. For $i \in [n_{u,v}]$, we let $q_{u,v}^2(i) = \sum_{C \in \mathcal{C}, M_{u,v}(C) = i} A(C) / \sum_{C \in \mathcal{C}, M_{u,v}(C) = i} A(C)$. □

We now specify sufficient conditions for robustness in terms of distances between these measures over $[n_{u,v}]$. The conditions require that for each pair $u,v \in U$, $A$ assigns similar probabilities to cohorts containing $u$ and cohorts containing $v$ within each cluster.

Definition 3.4 (α-Notions 1 and 2). Let $(M_{u,v})_{u \neq v \in U}$ be a mapping of $\mathcal{C}$. For $u,v \in U$, let $q_{u,v}^1$ and $q_{u,v}^2$ be defined as in Definition 3.3. We define α-Notions 1 and 2 as follows:

12This is not necessarily a probability measure, since the total sum on the sample space is $p(u) \leq 1$, but it is finite.
13Observe that this is in fact a probability measure since $p(u) = \sum_{C \in \mathcal{C}, A(C) = i} M_{u,v}(C) = \sum_{i=1}^{M_{u,v}(C)} \sum_{C \in \mathcal{C}, M_{u,v}(C) = i} A(C)$.
14Like in Definition 2.3 this definition is not defined if $p(u) = 0$, since it does not make sense to consider a “conditional distribution” if $u$ is never selected to be in the cohort (and thus never receives a score). We should thus restrict to considering $u \in U$ where $p(u) > 0$ (and individual fairness of the cohort selection mechanism on its own would provide fairness guarantees over the probabilities $p(u)$). For simplicity, in this extended abstract, we do not explicitly mention this modification.
(1) For $\alpha \geq 0.5$, we say that $A$ satisfies $\alpha$-Notion 1 if for all $u, v \in U$ such that $\mathcal{D}(u, v) < 1$, $\text{TV}(q^1_{u,v}, q^1_{v,u}) \leq (\alpha - 0.5)\mathcal{D}(u, v)$. (The 0.5 arising in Notion 1 comes from having to “smooth out” $q^1_{u,v}$ to a probability measure in a later step.)

(2) For $\alpha \geq 0$, we say that $A$ satisfies $\alpha$-Notion 2 if for all $u, v \in U$ such that $\mathcal{D}(u, v) < 1$, $\text{TV}(q^2_{u,v}, q^2_{v,u}) \leq \alpha\mathcal{D}(u, v)$.

Our main result is that these conditions guarantee pipeline robustness for composition with any $f \in \mathcal{F}$ with respect to mass-moving distance (and thus expected score). Theorem 3.5 states that so long as $A$ satisfies Notion 1 (resp. 2) for the mappings associated with $F$, then $A$ will be robust with respect to $\mathcal{F}$.

**Theorem 3.5** (Robustness to Post-Processing). Let $\mathcal{F}$ be a class of scoring functions, let $\alpha \geq 0.5$ be a constant. Suppose that $(M_{u,v})_{u \neq v \in U}$ is in $\mathcal{M}$. If $A$ is individually fair and satisfies $\alpha$-Notion 1 (resp. $\alpha$-Notion 2) for $(M_{u,v})_{u \neq v \in U}$, then $A$ is $2\alpha$-robust w.r.t. $\mathcal{F}$ for $d^{\text{uncond,MMD}}$ (resp. $d^{\text{cond,MMD}}$).

The proof of Theorem 3.5 appears in Appendix [B.1](#).

Furthermore, these conditions are necessary for any mass-moving distance and the weaker condition of expected score for certain rich classes of scoring functions.

**Theorem 3.6** (Informal). Let $d$ be any metric in $\{d^{\text{uncond,MMD}}, d^{\text{cond,MMD}}, d^{\text{cond,E}}, d^{\text{uncond,E}}\}$. Loosely speaking, given $\mathcal{F}$ described by mappings such that inter-cluster distances are much larger than intra-cluster distances, the requirements on $A$ in Theorem 3.5 are necessary for achieving robustness w.r.t. $d$.

We formalize Theorem 3.6 in Appendix [B.4](#).

## 4. Robust Mechanisms

Although the conditions specified in the previous section are quite strict, and indeed some pathological scoring function families admit no robust solutions, we can nonetheless construct robust cohort selection mechanisms for rich classes of scoring policies. We exhibit mechanisms robust to two broad classes of policies:

1. **Individual interchangeability**: replacing a single individual in the cohort does not change treatment of the cohort too much, i.e. policies like $\delta^{\mathcal{F}}$.

2. **Quality-based treatment**: cohorts with similar quality “profiles” are treated similarly. That is, the scoring function only considers the set of qualifications represented within a cohort and is agnostic to the specific individual(s) exhibiting a given qualification.

These policies cover a wide range of realistic scenarios and allow for significant flexibility and adaptability in the choice of $f$. In this section, we demonstrate that these policies also admit a variety of efficient and expressive constructions for $A$, i.e. $A$ that may assign a wide range of probabilities $p(u)$ to individuals.

**Remark 4.1.** As previously noted, robustness is trivial for the class of scoring functions which ignore the cohort context ($\mathcal{F}_1$). We formalize this observation in the following proposition:

**Proposition 4.2.** Consider the mapping that, for each pair of individuals $u$ and $v$, places all of the cohort contexts in $(\mathcal{C}_u \times \{u\}) \cup (\mathcal{C}_v \times \{v\})$ into the same cluster. If $A$ is individually fair, then $A$ satisfies 0.5-Notion 1 and 0.5-Notion 2 w.r.t. this mapping.

### 4.1. Individual interchangeability

To describe the interchangeability policy, we specify a distance function $\delta^{\text{int}} : (\mathcal{C} \times U) \times (\mathcal{C} \times U) \rightarrow [0, 1]$ that requires that “swapping” any individual in a cohort does not result in significantly different treatment. More formally:

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13See Corollary [B.1](#) for a formal statement of the relationship between MMD and expected score.
14See Theorem [B.3](#) and Theorem [B.6](#)
15See Appendix [D.1](#) for an example of $\mathcal{F}$ which admits no robust $A$. 

Definition 4.3 (Individual interchangeability policy).

\[
\delta^{\text{int}}(((C,u),(C',v)) = \begin{cases} 
\mathcal{D}(u,v) & \text{if } C = C' \\
\mathcal{D}(u,v) & \text{if } C' = (C \setminus \{u\}) \cup \{v\} \\
1 & \text{otherwise.}
\end{cases}
\]

\(\delta^{\text{int}}\) can be viewed as an overestimate of \(\delta^P\), or as a partial specification of the distance function on a subset of \((\mathcal{C} \times U) \times (\mathcal{C} \times U)\), trivially counted to 1 on other pairs of cohort context pairs. \(\delta^{\text{int}}\) is naturally translated into a simple mapping: for any pair of individuals \(u\) and \(v\), the partition corresponding to \(u\) and \(v\) in the mapping consists of clusters of size 2 consisting of “corresponding” (cohort, individual) pairs. This follows from observing that if an individual \(u\) receives some score \(f(C, u)\) in a cohort \(C\), if \(u\) were replaced by \(v \not\in C\), then \(v\) would receive a score in \([f(C, u) - \mathcal{D}(u, v), f(C, u) + \mathcal{D}(u, v)]\). More formally:

Definition 4.4 (Swapping Mapping). Let \(\mathcal{C}\) be the set of all subsets of \(U\) with exactly \(k\) individuals. The swapping mapping is defined as follows. For each pair of individuals \(u, v \in C\):

1. For \(C \in \mathcal{C}\) such that \(u, v \in C\), the partition includes the cluster \(\{(C, u), (C, v)\}\).
2. For \(C \in \mathcal{C}\) such that \(u \in C\) and \(v \not\in C\), the partition includes the cluster \(\{(C, u), (C' \setminus \{u\}) \cup \{v\}, v\}\).

It is straightforward to verify that the swapping mapping respects \(\delta^{\text{int}}\).

For the swapping mapping, there is a simple condition under which cohort selection mechanisms satisfy unconditional robustness (Notion 1): monotonicity.

Definition 4.5 (Monotonic cohort selection). Suppose that \(\mathcal{C}\) is the set of cohorts of size \(k\). A cohort selection mechanism \(A\) is monotonic if for all pairs of individuals \(u, v \in U\), for any \(C' \subseteq C\) such that \(|C'| = k - 1\) and \(u, v \not\in C'\), if \(p(u) \leq p(v)\) then \(\mathbb{A}(C' \cup \{u\}) \leq \mathbb{A}(C' \cup \{v\})\).

The intuition for the link between the monotonicity property and the swapping mapping is that the probability masses on a cohort containing \(u\) and a cohort containing \(v\) that are paired in the swapping mapping are directionally aligned and cannot diverge by more than \(\mathcal{D}(u, v)\).

Lemma 4.6. Suppose that \(\mathcal{C}\) is the set of cohorts of size \(k\). If \(A\) is monotonic, then \(A\) satisfies 0.5-Notion 1 for the swapping mapping.

Both PermuteThenClassify and WeightedSampling, cohort selection mechanisms proposed in [6], are monotonic, efficient and have a high degree of expressivity.

However, monotonicity alone is not sufficient to guarantee conditional robustness (Notion 2) for the swapping mapping (see Appendix C). Borrowing intuition from PermuteThenClassify, we give a novel, efficient, individually fair cohort selection mechanism that achieves conditional robustness (Notion 2) for the swapping mapping:

Mechanism 4.7 (Conditioning Mechanism). Given a target cohort size \(k\), a universe \(U\) and a distance metric \(\mathcal{D}\), initialize an empty set \(S\). For each individual \(u \in U\):

1. Assign a weight \(w(u)\) such that \(|w(u) - w(v)| \leq \mathcal{D}(u, v)\), i.e., the weights are individually fair.
2. Draw from \(1_u \sim \text{Bern}(w(u))\), i.e., flip a biased coin with weight \(w(u)\). If \(1_u\), add \(u\) to \(S\).

If \(|S| \geq k\), return a uniformly random subset of \(S\) of size \(k\). Otherwise, repeat the mechanism.

We show that under mild conditions, the Conditioning Mechanism is satisfies Notion 2, concludes in a small number of rounds, and allows for a high degree of expressivity. (See Lemma D.5 in Appendix D for a formal statement and proof details.)

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\(^{18}\)See Appendix C for detailed descriptions of these mechanisms and formal proofs of the monotonicity property.

\(^{19}\)One might imagine a mechanism that conditions on exactly \(k\) individuals being chosen, but this mechanism can be arbitrarily far from individually fair. Consider \(k - 1\) individuals with weight 1 and \(|U| - k - 1\) individuals with weight 0.9. Conditioning exactly \(k\) individuals would cause \(|p(u) - p(v)|\) to diverge arbitrarily for \(w(u) = .9\) and \(w(v) = 1\).
4.2. **Quality-based treatment.** One downside of the monotonic mechanisms proposed for $\delta^{\text{int}}$ is that they require that any cohort with a single individual swapped is considered with nearly the same probability as the original cohort. In practice, this is problematic when $A$ needs to ensure that each cohort has a certain structure. For example, when hiring a team of software engineers, designers and product managers, the proportion of each type of team member is important, and arbitrary swaps are not desirable from the perspective of team structure. By restricting to scoring functions that only consider the quality profile of a cohort, i.e., how many individuals from each quality group are represented in a cohort, $A$ can construct highly structured cohorts, so long as the structure of the cohort is valid with respect to the fairness metric $\mathcal{D}$.

We now consider robust mechanisms for policies predicated on additional structure within the metric over $U$. In particular, we assume the existence of a partition of the universe $U$ into one or more “quality groups” $q_1, \ldots, q_n$. These quality groups satisfy the property that the distances within a quality group are smaller than distances between quality groups. How much smaller is determined by a parameter $\beta$. More formally,

**Definition 4.8.** Let $\beta \leq 1$ be a constant and $n \geq 1$ be an integer. Consider a partitioning of a $U$ into subsets $q_1, \ldots, q_n$, i.e., “quality groups”, and let $\mathcal{D}$ be a metric on $U$. Now, we define metrics $D$ on $\{1, \ldots, n\}$ and $\mathcal{D}^i$ for $1 \leq i \leq n$ on $q_i$ as follows: we let $D(i, j) = \inf_{u \in q_i, v \in q_j} \mathcal{D}^i(u, v)$ and $\mathcal{D}^i$ be the restriction of $\mathcal{D}$ to $q_i$. We call the metric $\mathcal{D}$ endowed with quality groups $q_1, \ldots, q_n$ $\beta$-quality-clustered if for all $1 \leq i \leq n$, we have that

$$\max_{u, v \in q_i} \mathcal{D}^i(u, v) \leq \beta \min_{j \neq i} D(i, j).$$

Notice that any metric $\mathcal{D}$ is trivially 1-clustered with respect to the trivial quality group $q_1 = U$. The benefit of endowing $\mathcal{D}$ with a greater number of quality groups is to exploit additional structure of the metric, when any exists.

For simplicity in the specification of the relevant policy and family of scoring functions we introduce a quality profile function $P$ to count the number of individuals in each quality group in a cohort: that is, $P : 2^U \to \{(x_1, \ldots, x_n) \mid x_i \in \mathbb{Z}^{\geq 0}\}$, and the $i$th coordinate of $P(C)$ is $|C \cap q_i|$. Loosely speaking, the quality-based treatment policy requires that the only information about a cohort utilized by the scoring functions is its quality profile. We now formally define $\mathcal{F}_3$ and an associated policy $\delta^{\text{quality}}$:

**Definition 4.9.** Let $\beta \leq 1$ be a constant. Suppose that $\mathcal{D}$ is endowed with quality groups $q_1, \ldots, q_n$ and $\mathcal{D}$ is $\beta$-quality-clustered. We define $\mathcal{F}_3$ to be the set of intra-cohort individually fair score functions $f : \mathcal{C} \times U \to [0, 1]$ satisfying the following conditions:

1. For $C, C' \in \mathcal{C}$ satisfying $P(C) = P(C')$, if $u$ and $v$ that are in the same quality group, then $f(C, u) = f(C', v)$.
2. For integers $1 \leq i \neq j \leq n$, $C, C' \in \mathcal{C}$ satisfying $P(C) = P(C')$, and any individuals $u \in q_j$ and $v \in q_j$, it holds that $|f(C, u) - f(C', v)| \leq D(i, j)$.

When each quality group is homogeneous in terms of individual “quality”, this corresponds to score functions that are determined purely by “quality”\footnote{In this case, $\mathcal{F}_3$ includes Equal Treatment, Promotion, Stack Rank, and Fixed Bonus (discussed in Appendix A) when scores are based on the “quality” of “performance” of individuals.}. As in Section 4.1 we specify a distance function $\delta^{\text{quality}} : (\mathcal{C} \times U) \times (\mathcal{C} \times U) \to [0, 1]$ that overestimates $\delta^{\mathcal{F}_3}$, but still preserves enough of the fairness structure to construct the desired mapping.

**Definition 4.10 (Quality-based treatment policy).** Given a universe $U$, a set of permissible cohorts $\mathcal{C}$ and distance metrics and quality groups as in Definition 4.9

1. For $C, C' \in \mathcal{C}$ satisfying $P(C) = P(C')$, if $u \in q_j$ and $v \in q_j$, then $\delta^{\text{quality}}((C, u), (C', v)) = 0$.
2. For integers $1 \leq i \neq j \leq n$, $C, C' \in \mathcal{C}$ satisfying $P(C) = P(C')$, and any individuals $u \in q_j$ and $v \in q_j$, we set $\delta^{\text{quality}}((C, u), (C', v)) = D(i, j)$.

The core intuition is that a nice mapping exists when $\mathcal{C}$ is “symmetric with respect to individuals in each quality group.” It is helpful here to consider a bipartite graph $G = (A, B, E)$, where $A$ has one vertex for each
subset of the universe $U$, $B$ has one vertex for each possible profile of a subset of $U$, and there is an edge $(a, b) \in E$ precisely when $b$ is the profile of $a$, that is $b = P(a)$.

Fix any $\mathcal{C}$, and consider the subgraph $G' = (A', B', E')$ of $G$ induced by the vertices in $A$ corresponding to members of $\mathcal{C}$, the edges incident on these vertices, and the subset of $B$ induced by these edges. We say that $\mathcal{C}$ is quality-symmetric if for all $b' \in B'$ it is the case that $E'$ contains all the edges in $E$ (in the original graph) incident on $b'$.

That is, $\mathcal{C}$ contains all cohorts obtained by swapping out individuals from the same quality group. If $\mathcal{C}$ is quality-symmetric, then consider the following mapping.

**Definition 4.11** (Quality-Based Mapping). Let $\beta \leq 1$ be a constant. Suppose that $\mathcal{D}$ is endowed with quality groups $q_1, \ldots, q_n$ and $\mathcal{D}$ is $\beta$-quality-clustered. Suppose $\mathcal{C}$ is quality-symmetric. The quality-based mapping is defined as follows. For each pair of individuals $u, v \in C$, let $\mathcal{D}_{u,v} = (\mathcal{C}_{u} \times \{u\}) \cup (\mathcal{C}_{v} \times \{v\})$. For each $(x_1, \ldots, x_n) \in P(\mathcal{C}_u \cup \mathcal{C}_v)$, the partitioning of $\mathcal{D}_{u,v}$ contains a cluster of the form $\{(C, x) \in \mathcal{D}_{u,v} \mid P(C) = (x_1, \ldots, x_n)\}$.

We verify that the quality-based mapping indeed respects $\delta^{\text{quality}}$ (and thus respects $\delta^{\mathcal{D}_3}$ by Lemma 4.2). If $u$ and $v$ are in the same quality group, then the diameter of each cluster under $\delta^{\text{quality}}$ is 0, which is trivially upper bounded by $\mathcal{D}(u, v)$. On the other hand, if $u$ and $v$ are in different quality groups $q_i$ and $q_j$ respectively, then the diameter of each cluster is no more than $D(i, j) \leq \mathcal{D}(u, v)$. Thus, the properties of a mapping are satisfied by the quality-based mapping.

In this scenario, the quality-based mapping captures the intuition for the fairness structure of $\mathcal{F}_3$ much better than $\delta^{\text{quality}}$. The mapping groups together all cohorts with the same quality profile (i.e. the same number of individuals in each quality group), capturing the intuition that the only information that a score function in $\mathcal{F}_3$ utilizes about a cohort is the quality profile.

As the score function behavior does not depend on the specific individuals in a quality group, $A$ should have significant freedom to choose individuals within each quality group while still satisfying robustness w.r.t. $\mathcal{F}_3$. We will show that once the number of members of each quality group in the cohort is decided, utilizing any individually fair cohort selection mechanism within each quality group will satisfy our conditions. Moreover, our mechanisms have some flexibility in deciding the quality profile as well.

**Mechanism 4.12** (Quality Compositional Mechanisms). Let $\beta \leq 1$ be a constant, and suppose that $\mathcal{D}$ endowed with quality groups $q_1, \ldots, q_n$ is $\beta$-quality-clustered. Suppose also that $\mathcal{C}$ is quality-symmetric. For each $1 \leq i \leq n$ and each $1 \leq x_i \leq |q_i|$, let $A_{i,x_i}$ be a $\mathcal{D}^i$-individually fair mechanism selecting $x_i$ individuals in $q_i$. We define the quality compositional mechanism for $\{A_{i,x_i}\}$ as follows. Let $\mathcal{X}^r$ be any distribution over $n$-tuples of nonnegative integers $(x_1, \ldots, x_n) \in P(\mathcal{C})$.

1. Draw $(x_1, \ldots, x_n) \sim \mathcal{X}^r$.
2. Independently run $A_{i,x_i}$ for each $1 \leq i \leq n$, and return the union of the outputs of all of these mechanisms.

In the next lemma, we show that when a quality composition mechanism only selects cohorts whose quality projection vectors $(x_1, \ldots, x_n)$ are “close” to an inter-quality group distance multiple of $(|q_1|, \ldots, |q_n|)$, Notion 1 is achieved. (This requirement essentially says that the relative proportion of selected individuals in each quality group needs to be approximately reflective of the relative proportion of individuals in each quality group in the universe, scaled by the difference between the quality groups in the original metric. This type of requirement turns out to be necessary for basic individual fairness guarantees, by the constrained cohort impossibility result in [6].) Moreover, under stronger conditions, we show that Notion 2 is also achieved.

**Lemma 4.13.** Let $\beta \leq 0.5$ be a constant, and suppose that $\mathcal{D}$ endowed with quality groups $q_1, \ldots, q_n$ is $\beta$-quality-clustered. Suppose also that $\mathcal{C}$ is quality-symmetric, and let $\mathcal{X}^r$ be any distribution over $(x_1, \ldots, x_n) \in P(\mathcal{C})$ such that $\frac{1}{|q_i|} \frac{x_i}{|q_i|} \leq (1 - 2\beta)D(i, j)$. If $A$ is a quality compositional mechanism, then:

1. $A$ is always individually fair.
(2) A always satisfies 0.5-Notion 1.

(3) A satisfies 0.5-Notion 2 for $\mathcal{D}$ and $\mathcal{F}_\delta$ if either of the following conditions hold:

(a) (One set) $|\text{Supp}(X)| = 1$ (i.e. one “canonical” $(x_1, \ldots, x_n)$), or

(b) (0-1 metric) $D(i, j) = 1$ for $1 \leq i \neq j \leq n$ and $\mathcal{D}(u, v) = 0$ for $1 \leq i \leq n$.

The quality compositional mechanisms provide a greater degree of structure in cohort selection than the monotone mechanisms giving in Section 4.1. The Conditioning Mechanism and similar monotone mechanisms are forced to select individuals essentially independently, with the only dependence stemming from the cohort size constraint. However, structured cohorts are necessary in a number of practical applications, as previously noted. Although $\delta_{\text{quality}}$ imposes more constraints on the permitted $\mathcal{F}$ than $\delta_{\text{int}}$, the basis for these constraints is likely to be tolerated well in legitimate use cases in which structure is important.

Moreover, the company has flexibility in selecting individuals within each experience group, as any individually fair mechanism can be utilized. This offers significantly more flexibility than selecting members in each quality group uniformly at random. Such flexibility is particularly crucial, for example, if a company further wants to ensure that tech company teams have a mixture of software engineers and product managers. The individually fair mechanisms within each quality group can help achieve this balance through selecting balanced subsets of engineers and product managers. In essence, the quality compositional mechanisms allow flexibility in cohort selection while still satisfying robustness for $\mathcal{F}_3$, due to restrictions on the behavior of scoring functions in $\mathcal{F}_3$.

5. Discussion and Future Work

We have presented a framework for evaluating the robustness of cohort selection as part of a pipeline. We’ve demonstrated that naive auditing strategies concerning average cohort quality or score are unable to uncover significant fairness problems. We’ve also shown that many reasonable policies for cohort selection and subsequent scoring can conflict with each other resulting in very poor fairness outcomes. Furthermore, we’ve demonstrated that a malicious pipeline designer can easily use composition problems to disguise bad behavior. Despite these hurdles, we’ve shown that it is possible to construct pipelines that are fair. In particular we’ve shown that constructing cohort selection mechanisms that are robust to composition with a family of scoring functions is possible. By framing the problem in terms of robustness, we address the concern that placing requirements on future designs is nearly unenforceable, whereas designing the current stage to be robust to a large class of potential future policies can give much better practical guarantees. Finally, we’ve shown robust cohort selection mechanisms that compose well with reasonable scoring function families.

In the process of exploring robustness and fairness in pipelines, we uncovered a number of interesting questions for future work. Policy complexity: we have considered a set of concise and practical policies in this work, but the trade-off between policy complexity and the expressiveness of cohort selection has not been fully characterized. Fair Matching: choosing a cohort is very similar to the problem of assigning an individual to an existing cohort. However, in the traditional matching literature, significant emphasis is placed on individuals’ and teams’ preferences over placements, rather than external fairness criteria. Is it possible to simultaneously achieve a good matching, in the sense of satisfying preferences or stability, and individual fairness? Quantifying the tradeoff: There are significant differences in the difficulty for constructing mechanisms which satisfy the conditional, versus unconditional, notion of robustness. Is it possible to more directly quantify the tradeoff in mechanism expressivity between these two settings? Different metrics: Handling different metrics in the pipeline: we considered just one metric throughout the entire pipeline, but using different metrics for different stages of the pipeline may be valid. For example, in the case of promoting an individual contributor to a management position, the metric for “manager” may be different. Ranking instead of scoring: although ranking with hard cutoffs does not satisfy individual fairness, it is frequently used in practice. Can the model we have outlined with respect to scoring be translated to ranking, e.g., incorporating the results of [7]?
6. RELATED WORK

There is a wide variety of work concerning fairness in machine learning [9, 14, 25, 17, 8, 18, 26, 22, 10, 16, 15, 11, 12, 20, 19, 4, 24, 5]. Individual fairness was introduced by Dwork et al. [5]. Dwork and Ilvento studied composition of combination of individually fair and group fair classifiers [6]. Two other recent lines of work have also considered composition problems and fair systems. First, several works have studied the problem of feedback loops, in which decisions that previous time steps, such as where to send law enforcement officers, influence outcomes at later time steps potentially unrelated to the original decision [12, 8, 21]. Bower et al. study fairness in a pipeline of decisions under a group-based notion of fairness [1]. They primarily consider the combination of multiple non-adaptive sequential decisions, evaluating fairness at the end of the pipeline. Second, several works have considered competitive scenarios, such as advertising, in which many (potentially fair or unfair) classifiers compete for individuals [2, 13]. Although not explicitly addressing composition, recent work considering fairness in rankings, e.g. [7], also address fairness in a setting in which outcomes, in this case rankings, naturally depend on the outcomes of others.

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APPENDIX A. EXTENDED MOTIVATING EXAMPLES

To complement the motivating examples included throughout the text, we include a “Catalog of Evils” relevant to pipelines.

In each example, we consider a universe $U$ comprised of individuals belonging to two groups, a majority group $S$ and a minority group $T$, such that the majority group is $k$ times as large as the minority group (i.e. $k|T| = |S|$). For the particular employment task in question, there is a known metric $D$ which specifies who is similar to whom for the purposes of this task. For simplicity, we assume that $D$ is one-dimensional, i.e. each individual $u$ has a qualification $q_u \in [0, 1]$, and $D(u,v) := |q_u - q_v|$. We assume that $S$ and $T$ have an equal distribution of talents: more specifically, for every qualification level $q$, there are exactly $k$ times as many individuals with qualification $q$ in $S$ as there are in $T$. We assume that there is a nontrivial range of qualifications in $[0, 1]$, and we will generally assume that the company prefers to hire the most highly qualified candidates, but in order to fill the number of positions open cannot hire only maximally qualified candidates. We use $Q_H$ to refer to the subset of individuals who are highly qualified.

Our examples are based on a set of facially neutral company compensation policies. We now give precise descriptions of these policies in the form of a scoring function, and indicate where the scoring policies must be adjusted to give intra-cohort individual fairness. (As we will see later, even adjusting the policies to be intra-cohort individually fair won’t be enough to prevent bad behavior under composition.)

(1) **Fixed Bonus Pool:** A fixed pool of bonus money $B$ is assigned to each team and is split between the members of each team, with the highest achieving members receiving larger portions of the pool. More formally, given a cohort of individuals $C = \{x_1, \ldots, x_c\}$ of size $c$ with qualifications $\{q_{x_1}, \ldots, q_{x_c}\}$, the scoring function $f_B$ assigns a bonus share $b_i$ to each individual $x_i$ such that $\Sigma_{i \in C} b_i = 1$, optimized to ensure that individuals with higher qualification receive larger bonuses.

In particular, $f_B$ can either be a simple proportional mechanism, e.g. $f_B(u) \propto q_u$, or it can be optimized for specific goals, e.g. maximizing the difference in compensation between the most and least qualified individuals, creating an even spread of compensations, etc. For example, the company could choose $f_B$ using the following optimization to choose the largest “weighted spread” to maximize the objective of
increasing the difference in compensation based on difference in qualification:

\[
\text{argmax}_{\{b_u \in [0,1]\}} \left\{ \sum_{u,v \in C} (b_u - b_v)(q_u - q_v) \right\}
\]

subject to

\[
|b_u - b_v| \leq |q_u - q_v| \text{ for all } u, v \in C
\]

\[
\sum_{u \in C} b_u = 1
\]

This optimization will tend to choose bonus shares that maximize the differences in bonuses between individuals with significantly different qualifications within the cohort. Notice that the scoring function has no way of knowing what other cohorts may or may not appear and with what probabilities, and so it only optimizes within the particular cohort \(C\).

(2) **Stack Rank**: The bottom 10% of each team may be fired or put on “performance plans”. Formally,

\[
f(C,u) := \begin{cases} 
1 & \text{if } \frac{|\{v \mid q_u > q_v\}|}{|C|} \leq 0.1, \\
0 & \text{otherwise}
\end{cases}
\]

However, this strict cut off violates intra-cohort individual fairness, as two nearly equally qualified individuals might find themselves on opposite sides of the cutoff. Alternatively, we can construct a scoring function which closely approximates the desired policy but still satisfies intra-cohort individual fairness, by optimizing subject to the intra-cohort fairness constraints. For example, taking \(\emptyset_u\) to be the indicator that \(u\) is in the bottom 10% of the cohort, one could use the following optimization to maximize the probability that only the bottom 10% are placed on performance plans

\[
\text{argmax}_f \sum_{u \in C} f(C,u) \emptyset_u + (1 - f(C,u))(1 - \emptyset_u)
\]

subject to

\[
|f(C,u) - f(C,v)| \leq |q_u - q_v| \text{ for all } u, v \in C
\]

Alternatively, if exactly 10% of the cohort should be put on performance plans, Permute-Then-Classify can be applied or an additional constraint on the expected number of employees placed on performance plans could be added to the optimization above in order to satisfy *intra-cohort* individual fairness.

(3) **Equal Treatment**: Each team’s bonus is determined by average performance of the team (assumed to be proportional to average quality) and awarded equally to each member. Formally, the scoring function \(f\) first chooses the total bonus amount \(B_C \propto B \sum_{u \in C} q_u\), and then assigns \(b_u = \frac{B_u}{|C|}\) for all \(u \in C\). Intra-cohort individual fairness for \(f\) is trivial, as every individual is treated equally.

(4) **Promotion**: Choose the single most qualified person on the team to promote, based on performance. As in the case of stack ranking, strictly implementing this policy will violate intra-cohort individual fairness, as nearly equal individuals may be treated very differently. As above we can satisfy *intra-cohort* individual fairness by posing the relevant optimization question, and Permute-then-Classify (see Appendix C) can be used to select exactly one individual for promotion.

We now show that these compensation policies can cause significant unfairness for \(T\) when combined with simple hiring protocols. In each case, we state the set of cohorts the company intends to select from, and we assume that the company uses a method similar to the one described in Appendix C.3 to derive a fair set of weights to use to sample a single cohort in an individually fair way\[21\] First, we consider the “packing” hiring protocol.

\[21\] We omit the details of the method and the particulars of the conditions on the set of cohorts specified as they are easy to fulfill in these settings. In particular, each set of cohorts we specify can clearly be used to form a partition of \(U\), fulfilling the requirements of Theorem C.3.
Example A.1 (Packing). Suppose that in the past, the company had a particular problem retaining employees from the minority group $T$ and in order to address this problem, the company ensures that individuals with high potential from $T$ are always hired together into the same team for mutual support. On the other hand, talented members of $S$ are spread out between the other teams, to make sure that there is at least one highly talented individual on each team. Formally, the company specifies the set of cohorts $\mathcal{C}_{\text{packing}} = \{ C \in \mathcal{C} \mid (|C \cap T \cap Q_H| > 1 \land |C \cap S \cap Q_H| = 0) \lor ((|C \cap T \cap Q_H| = 0 \land |C \cap S \cap Q_H| = 1) \}$. where $Q_H$ is the set of highly qualified candidates, and samples a single cohort from the set such that individual fairness is satisfied.

“Packing” results in lower compensation for $T$ for Fixed Bonus Pool, Stack Rank, and Promotion compensation policies. “Packing” causes talented members of $T$ to be on teams of higher average quality than those with talented members of $S$. As a result, members of $T$ will receive lower bonuses and promoted less often than members of $S$. Thus, this seemingly beneficial practice can backfire when composed with certain compensation policies.

One may imagine that utilizing a “splitting” strategy, where qualified members of $T$ are separated from other qualified members to increase their chance of “standing out” on teams, would solve this issue.

Example A.2 (Splitting). The company chooses teams where highly qualified members of $T$ are always the only highly qualified member of their team, giving them the opportunity to stand out and be recognized for their talent. More formally, the company chooses from the set of cohorts $\mathcal{C}_{\text{splitting}} = \{ C \in \mathcal{C} \mid (|C \cap T \cap Q_H| = 1 \land |C \cap S \cap Q_H| = 0) \lor ((|C \cap T \cap Q_H| = 0 \land |C \cap S \cap Q_H| \geq 1) \}$. In each cohort containing a highly qualified member of $T$, there are no other highly qualified individuals (from either $T$ or $S$).

Though this policy no longer leads to lower compensation for $T$ for Stack Rank, Fixed Bonus Pool, and Promotion, “Splitting” results in lower compensation for $T$ for Equal Treatment, because the practice causes talented members of $T$ to be on teams of lower average quality than talented members of $S$. As a result, with Equal Treatment, qualified $S$ will receive greater compensation than qualified $T$. Splitting can also occur when members of $T$ are primarily hired via outreach. For example, suppose that a company has been trying to form a team to work on a difficult or low prestige task (e.g. Fortran code maintenance). All of the talented candidates in $S$ pass on the job offer because they are confident they can do better, so HR reaches out more aggressively to candidates in $T$. These candidates may be more willing to take the job because they are less confident about their other options. Thus, even without an explicit policy in place to choose minority candidates to be the singular most qualified member on a less qualified team, these situations can still arise from the interactions between the hiring procedure and the job market.

Remark A.3. The motivation for both of these policies could be malicious, and determining whether the stated goals or justifications were legitimate aims of the policy would be difficult.

One may imagine that these issues could be addressed by ensuring that qualified members of $T$ and qualified members of $S$ appearing on teams with similar average quality. However, a malicious company can still cause members of $T$ to receive lower compensation.

Example A.4 (Adversarial ranking). Suppose that the company did not want any member of the $T$ to be chosen for promotion or wished to depress their compensation relative to the members of $S$. The company decides to choose teams such that, for each team, there is a correspondence between the members of $T$ and $S$ included in the team, such that the members of $S$ are almost always more talented than their counterparts in $T$. (Given the equal distribution of talents of $T$ and $S$, there may be an excess member of $T$ that is allowed to be the most qualified, but this is a singular case.) More formally, the company chooses from $\mathcal{C}_{\text{adv-ranking}} = \{ C \in \mathcal{C} \mid \exists G : C \cap T \rightarrow C \cap S \text{ s.t. } \forall u \in C \cap T, q_u < q_{G(u)} \}$. 

“Adversarial Ranking” is particularly catastrophic for $T$ for Promotion or Stack Ranking if the hard cutoff (not intra-cohort individually fair) versions are used. Although ensuring intra-cohort individual fairness helps, members of $T$ will always be seeing depressed levels of promotion, higher levels of firing, and lower
levels of compensation except in the case of Equal Treatment. Thus “Adversarial Ranking” keenly illustrates that average team quality is not sufficient to ensure that individuals are truly being treated fairly in cohort-based pipelines. We stress that Adversarial Ranking can also be efficiently achieved using the procedure in Theorem C.7.

A.1. Sample Cohorts. To illustrate these issues, we include Figures 1a and 1b to compare the example scoring functions for a pair of cohorts, demonstrating the issues outlined above.

| Qualification | Fixed Pool Bonus | Equal Bonus |
|---------------|-----------------|-------------|
| Cohort 1      |                 |             |
| Alice         | 0.8             | 35          | 60          |
| Bob           | 0.7             | 25          | 60          |
| Charlie       | 0.5             | 5           | 60          |
| Dan           | 0.2             | 0           | 60          |
| Eve           | 0.8             | 35          | 60          |
| Cohort 2      |                 |             |
| Frank         | 0.8             | 57          | 40          |
| George        | 0.6             | 36          | 40          |
| Harriet       | 0.1             | 0           | 40          |
| Ivan          | 0.2             | 0           | 40          |
| Julia         | 0.3             | 7           | 40          |

(A) Bonus score function comparisons for two cohorts, each containing five individuals of varying qualifications. Cohort 1 has an average qualification of 0.6, and Cohort 2 has an average qualification of 0.4. In the fixed pool bonus, a total pool of 100 is split between the members of the cohorts. The same optimization is used for both cohorts, that is according the maximum possible bonus to the most qualified individual(s). Notice that in Cohort 1, Alice and Eve have to share the top bonus (35 each), but in Cohort 2, Frank doesn’t have to split the top bonus (57). Notice also that George and Julia receive higher bonuses than Bob and Charlie, even though they are (much) less qualified. On the other hand, in the equal bonus setting Frank receives a lower bonus than both Alice and Eve, even though he’s equally qualified.

| Qualification | Promotion | Stack Rank (IF) | Stack Rank (exact, not IF) |
|---------------|-----------|-----------------|-----------------------------|
| Cohort 1      |           |                 |                             |
| Alice         | 0.8       | 35%             | 0                           | 0                           |
| Bob           | 0.7       | 25%             | 10%                         | 0                           |
| Charlie       | 0.5       | 5%              | 30%                         | 0                           |
| Dan           | 0.2       | 0%              | 60%                         | 1                           |
| Eve           | 0.8       | 35%             | 0                           | 0                           |
| Cohort 2      |           |                 |                             |
| Frank         | 0.8       | 57%             | 0                           | 0                           |
| George        | 0.6       | 36%             | 0                           | 0                           |
| Harriet       | 0.1       | 0%              | 43%                         | 1                           |
| Ivan          | 0.2       | 0%              | 33%                         | 0                           |
| Julia         | 0.3       | 7%              | 24%                         | 0                           |

(B) Promotion score function comparison of the cohorts from Figure 1a. The promotion policy attempts to maximize the probability of promotion for the most qualified individuals, subject to the individual fairness constraints and that the expected number of promotions is 1. In this case, essentially the same observations apply as in the fixed pool bonus setting. In the case of Stack rank, both cohorts are optimized to maximize the probability of placing the least qualified person on a performance plan. Notice that Dan is much more likely to be placed on a performance plan than the equally qualified Ivan, due to the larger number of less qualified individuals in Cohort 2. Although it might seem that the exact stack rank policy, rather than the individually fair version, would be less likely to have this problem, in fact in this case Dan is still treated differently than Ivan.
APPENDIX B. EXTENDED DETAILS ON CONDITIONS

In this section, we provide proofs and some additional results mentioned in Section 3. In proving results, we consider the mass-moving distance between probability distributions over scores. That is, for every pair of individuals \( u \) and \( v \) and every score function \( f \in \mathcal{F} \), we consider the mass-moving distance between \( S_u^{N,A,f} \) and \( S_v^{N,A,f} \) (resp. \( S_u^{C,A,f} \) and \( S_v^{C,A,f} \)).

A simple way to think about our notion of mass-moving distance is to break the definition down into two steps: (1) transforming the original distributions over scores into distributions over a single shared set of adjusted scores and (2) moving mass between the distributions over adjusted scores. By introducing the transformation in step (1), we take the two distributions over scores (which may have disjoint supports) and transform them into distributions over a single support of adjusted scores so that similar scores are mapped to similar adjusted scores.

The next consideration is how we can choose adjusted scores and write distributions over adjusted scores in a way that takes advantage of what we know about the mapping and similar treatment of similar cohort contexts by \( f \). To do this, we write the distributions over adjusted scores \( S_u^{N,A,f} \) and \( S_v^{N,A,f} \) (resp. \( S_u^{C,A,f} \) and \( S_v^{C,A,f} \)) in terms of the distributions over clusters induced by \( A \) (\( q_u^1 \) (resp. \( q_v^2 \)).

Why does this help? Given a cluster, we can propose an adjusted score based on its extreme behavior under \( f \), i.e. the highest and lowest possible scores in the cluster. More formally, given a mapping, we define a function \( Q : \{1, \ldots, n_u \} \rightarrow [0,1] \) to transform the cluster labels that form the sample space of \( q_u^1 \) (resp. \( q_v^2 \)) into adjusted scores in \([0,1]\) that form the sample space of \( S_u^{N,A,f} \) (resp. \( S_v^{C,A,f} \)). \( Q \) will map each cluster in the partition corresponding to \( u \) and \( v \) to an adjusted score given by an “average” score in the cluster. Let \( S(i) = \{(C, u) \mid C \in M_u^{-1}(i) \} \cup \{(C, v) \mid C \in M_v^{-1}(i) \} \) be the (cohort, individual) pairs appearing in the cluster \( i \). Let \( a_i \) and \( b_i \) be the minimum and maximum scores in \( \{f(C, x) \mid (C, x) \in S(i)\} \). Now, we let \( Q(i) = \frac{a_i + b_i}{2} \), which can be viewed as an “average” score in the cluster. Briefly, this choice of definition for \( Q \) will guarantee that intra-cluster differences in treatment are bounded by \( \mathcal{D}(u, v) \), and thus mapping scores within a cluster to this “average” will conform to the requirement that the transformation to adjusted scores doesn’t move any score “too far.” (See Definition 2.10)

We can now write the distributions \( S_u^{C,A,f} \) and \( S_u^{N,A,f} \) in terms of clusters. For each \( j \in [0,1] \), notice that \( Q^{-1}(j) \) gives the set of clusters which correspond to that score (if such a cluster exists). \( q_{u,v}(Q^{-1}(j)) \) then yields the probability assigned to each cluster corresponding to the score \( j \) by \( A \). More formally, we define \( S_u^{C,A,f}(j) \) as follows:

\[
S_u^{C,A,f}(j) = \begin{cases} 
q_{u,v}(Q^{-1}(j)) & \text{if } j \in Q([n_{u,v}]) \\
0 & \text{if } j \notin Q([n_{u,v}]).
\end{cases}
\]

We define \( S_u^{N,A,f}(j) \) similarly, with the slight modification that we place an additional \( 1 - p(u) \) mass at 0 to account for the fact that not being selected in a cohort corresponds to a score of 0.

\[
S_u^{N,A,f}(j) = \begin{cases} 
q_{u,v}(Q^{-1}(j)) & \text{if } j \in Q([n_{u,v}]), j \neq 0 \\
q_{u,v}(Q^{-1}(0)) + 1 - p(u) & \text{if } j = 0 \\
0 & \text{otherwise}.
\end{cases}
\]

We analogously define these quantities for \( v \).

B.1. Proofs for Section 3

Using the distributions over adjusted scores, we can now prove Theorem 3.5.

**Theorem B.1 (Restatement of Theorem 3.5).** Let \( \mathcal{F} \) be a class of scoring functions, let \( \alpha \geq 0.5 \) be a constant. Suppose that \( (M_u)_{u \neq v \in U} \) is in \( \mathcal{A}^{\alpha} \). If \( A \) is individually fair and satisfies \( \alpha \)-Notion 1 (resp. \( \alpha \)-Notion 2) for \( (M_u)_{u \neq v \in U} \), then we have that \( A \) is \( 2\alpha \)-robust w.r.t. \( \mathcal{D} \) for \( d^{\text{uncond.MMD}} \) (resp. \( d^{\text{cond.MMD}} \)).

**Proof of Theorem B.1** Pick a pair of individuals \( u \neq v \in U \). Pick any \( \alpha \geq 0.5 \). Assuming that \( A \) satisfies \( \alpha \)-Notion 1 (i.e. Definition 3.4), we construct measures in the mass-moving definition that achieve a distance
of no more than $\alpha D(u,v)$. We use $\tilde{S}^{N,A,f}_u$ and $\tilde{S}^{N,A,f}_v$ (resp. $\tilde{S}^{C,A,f}_u$ and $\tilde{S}^{C,A,f}_v$) as defined above as our finite support measures in the mass-moving distance definition.

The proof consists of three steps: First, we take as given that $\tilde{S}^{N,A,f}_u$ and $\tilde{S}^{N,A,f}_v$ (resp. $\tilde{S}^{C,A,f}_u$ and $\tilde{S}^{C,A,f}_v$) satisfy Definition 2.10.1 (i.e., that there exists some $Z$ satisfying the first condition) and we show that $\tilde{S}^{2.10.2}$ is satisfied. This follows from a straightforward computation of total variation distance. Next, we exhibit the appropriate $Z$ for 2.10.1 by linking the adjusted scores given by $Q(i)$ to the original scores and showing: (A) no score moves too far when adjusted and (B) mass is conserved. Both arguments follow from the construction of the function $Z$.

First, we consider Condition 2.10.2 (i.e. “total variation distance is small”) for the distributions over adjusted scores. We use the fact that

$$TV(\tilde{S}^{C,A,f}_u, \tilde{S}^{C,A,f}_v) = \sum_{j \in \text{Supp}(\tilde{S}^{C,A,f}_u)} \left| \sum_{i \in Q^{-1}(j)} (q_{u,v}^j(i) - q_{v,u}^j(i)) \right| \leq \sum_{i=1}^{n_{u,v}} |q_{u,v}^j(i) - q_{v,u}^j(i)| = TV(q_{u,v}^j, q_{v,u}^j) \leq \alpha D(u,v),$$

where the last step follows from $\alpha$-Notion 2. A similar argument shows that:

$$TV(\tilde{S}^{N,A,f}_u, \tilde{S}^{N,A,f}_v) \leq TV(q_{u,v}^1, q_{v,u}^1) + 0.5 |(1 - p(u)) - (1 - p(v))| \leq \alpha D(u,v),$$

where the last step follows from $\alpha$-Notion 1 and individual fairness of $A$.

Now, we show Condition 2.10.1 (i.e. “nothing moves far and mass is conserved”) for the conversion of distributions over scores to distributions over adjusted scores. We handle the unconditional case (and a very similar argument works for the conditional case). We show condition 1 for $\tilde{S}^{C,A,f}_u$, since an analogous argument shows condition 1 for $\tilde{S}^{C,A,f}_v$. We use the following approach to move from the distribution over scores $\tilde{S}^{C,A,f}_u$ to the distribution over adjusted scores $\tilde{S}^{C,A,f}_u$. First, we couple the distributions over scores and over adjusted scores into a carefully chosen joint distribution $\mathcal{X}_u \in \Delta([0,1] \times \text{Supp}(\tilde{S}^{N,A,f}_u))$, where the $x$-coordinate can be thought of as the score and $y$-coordinate can be thought of as the adjusted score. Then, we implicitly specify the function $Z : [0,1] \rightarrow \Delta(\text{Supp}(\tilde{S}^{C,A,f}_u))$ using the joint distribution $\mathcal{X}_u$.

We define $\mathcal{X}_u$ as follows. We link the $x$-coordinate (score) and $y$-coordinate (adjusted score) through cohorts: that is, for each cohort $C$, we place probability of $\mathcal{X}(C)$ on the $(score, adjusted\ score)$ ordered pair given by $(f(C,u), Q(M_{u,v}(C)))$. More formally, for $x \in [0,1]$ and $y \in \text{Supp}(\tilde{S}^{C,A,f}_u)$ such that $(x,y) \neq (0,0)$, we define:

$$\mathcal{X}_u((x,y)) = \begin{cases} \frac{\sum_{C \in \mathcal{G}, f(C,u)=x, Q(M_{u,v}(C))=y} \mathcal{X}(C)}{1 - p(u) + \sum_{C \in \mathcal{G}, f(C,u)=0, Q(M_{u,v}(C))=0} \mathcal{X}(C)} & \text{if } (x,y) \neq (0,0) \\ 0 & \text{if } (x,y) = (0,0) \end{cases}$$

It is straightforward to observe that the marginal distribution of the $x$-coordinates of $\mathcal{X}_u$ is $\tilde{S}^{N,A,f}_u$, and the marginal distribution of the $y$-coordinates of $\mathcal{X}_u$ is $\tilde{S}^{C,A,f}_u$.

Now, we are ready to define the function $Z : [0,1] \rightarrow \Delta(\text{Supp}(\tilde{S}^{C,A,f}_u))$. For each $x \in [0,1]$, we define $Z(x)$, which is a probability measure on $\text{Supp}(\tilde{S}^{C,A,f}_u)$, as follows. First, we define the distribution $\mathcal{X}_x^y \in \Delta(\{x\} \times \text{Supp}(\tilde{S}^{N,A,f}_u))$ to be $\mathcal{X}_u$ conditioned on the $x$-coordinate being $x$. Then, $Z(x)$ is given by the marginal distribution of the $y$-coordinates of $\mathcal{X}_x^y$.

First, we show that the first sub-condition (i.e. that “nothing moves far”) is satisfied. It suffices to show that for all $C \in \mathcal{G}$, it holds that $|f(C,u) - Q(M_{u,v}(C))| \leq \alpha D(u,v)$. Suppose that $(C,u)$ is in cluster $i$. We know that

$$\frac{1}{|C|} |f(C,u) - Q(M_{u,v}(C))| \leq \frac{1}{|C|} 0.5(b_i - a_i) \leq 0.5 D(u,v),$$

since scores in cluster $i$ have small diameter by the conditions required for a mapping respecting $\frac{1}{2\alpha} \delta^\varphi$. This means that $|f(C,u) - Q(M_{u,v}(C))| \leq (0.5)(2\alpha) D(u,v)$.

Now, we show that the second sub-condition on $\text{Supp}(\tilde{S}^{C,A,f}_u)$ (i.e. that “mass is conserved”) is satisfied. Let $\gamma$ be the probability mass function associated with $\mathcal{X}_u$. Moreover, for each $x \in [0,1]$, $Z(x)$ is a probability distribution over $\text{Supp}(\tilde{S}^{C,A,f}_u)$, and we let $z^x$ be its probability mass function. For each $y^x \in \text{Supp}(\tilde{S}^{C,A,f}_u)$,
we wish to show that:
\[
\tilde{S}^{CA,f}_u(y^*) = \sum_{x \in \text{Supp}(S^{CA,f}_u)} \tilde{z}^x(y^*) S^{CA,f}_u(x).
\]
Using the fact that the marginal distribution of \( \mathcal{X}_u \) on the x-coordinates is \( S^{CA,f}_u \), along with the fact that \( Z(x) \) is the distribution on the y-coordinates conditional on the x-coordinate being x, we can deduce that \( S^{CA,f}_u(x) z^x(y^*) = \gamma((x,y^*)) \). Thus, we have that
\[
\sum_{x \in \text{Supp}S^{CA,f}_u} \tilde{z}^x(y^*) S^{CA,f}_u(x) = \sum_{(x,y^*) \in \text{Supp} \mathcal{X}_u} \gamma((x,y^*)).
\]
This is the probability mass at \( y^* \) of the marginal distribution of the y-coordinates of \( \mathcal{X}_u \). Using that the marginal distribution of the y-coordinates of \( \mathcal{X}_u \) is \( S^{CA,f}_u \), we know that \( \sum_{(x,y^*) \in \text{Supp} \mathcal{X}_u} \gamma((x,y^*)) = \tilde{S}^{CA,f}_u(y^*) \) as desired.

**B.2. Additional results.** First, we state a corollary of Theorem 3.5 that gives conditions for robustness w.r.t. expected score, using the fact that the weaker notion of expected score robustness follows from the stronger notion of mass-moving distance robustness.

**Corollary B.1.1** (Robustness to Post-Processing w.r.t Expected Score). Let \( \mathcal{F} \) be a class of scoring functions, and let \( \alpha \geq 0.5 \) be a constant. Suppose that \( (M_{u,v})_{u \neq v \in U} \) is in \( \mathcal{M}_{\beta} \). If A satisfies \( \alpha \)-Notion 1 (resp. \( \alpha \)-Notion 2) for \( (M_{u,v})_{u \neq v \in U} \), then we have that A is \( 6\alpha \)-robust w.r.t. \( \mathcal{F} \) for \( \mathcal{d}_{\text{uncond,}E} \) (resp. \( \mathcal{d}_{\text{cond,}E} \)).

**Proof of Corollary B.1.1** This is implied by Theorem 3.5 and the using the relationship between mass-moving distance and expected score in Proposition E.2.

Now, we show that Notion 1 is a “weaker” notion than Notion 2, which aligns with our result in Proposition E.1 that unconditional fairness guarantees are “weaker” than conditional fairness guarantees. More specifically, we show in Proposition B.2 that for a given mapping and individually fair A, Notion 2 is stronger than Notion 1 up to Lipschitz factors.

**Proposition B.2.** Let \( \alpha \geq 0.5 \) be a constant, and suppose that \( (M_{u,v})_{u \neq v \in U} \) is a mapping and A is an individually fair cohort selection mechanism. If A satisfies \( \alpha \)-Notion 2, then A satisfies \( \alpha \)-Notion 1.

**Proof of Proposition B.2** Notion 2 (i.e. Definition 3.4.2) and individual fairness tell us that:
\[
\frac{1}{2} \sum_{i=1}^{n_{u,v}} |q_{u,v}^2(i) - q_{u,v}^2(i)| \leq (\alpha - 0.5) \mathcal{D}(u,v),
\]
\[
|p(u) - p(v)| \leq \mathcal{D}(u,v).
\]
We want to show that:
\[
\frac{1}{2} \sum_{i=1}^{n_{u,v}} |q_{u,v}^1(i) - q_{u,v}^1(i)| \leq \alpha \mathcal{D}(u,v).
\]
We can write the first condition as:
\[
\frac{1}{2} \sum_{i=1}^{n_{u,v}} \left| \frac{q_{u,v}^1(i)}{p(v)} - \frac{q_{u,v}^1(i)}{p(u)} \right| \leq (\alpha - 0.5) \mathcal{D}(u,v)
\]
\[
\frac{1}{2} \sum_{i=1}^{n_{u,v}} \left| \frac{p(u)q_{u,v}^1(i)}{p(u)p(v)} - \frac{p(v)q_{u,v}^1(i)}{p(u)p(v)} \right| \leq \alpha \mathcal{D}(u,v)
\]
\[
\frac{1}{2} \sum_{i=1}^{n_{u,v}} \left| p(u)q_{u,v}^1(i) - p(v)q_{u,v}^1(i) \right| \leq p(u)p(v)(\alpha - 0.5) \mathcal{D}(u,v)
\]
\[
\frac{1}{2} \sum_{i=1}^{n_{u,v}} \left| p(u)q_{u,v}^1(i) - p(v)q_{u,v}^1(i) \right| \leq p(u)p(v)(\alpha - 0.5) \mathcal{D}(u,v).
\]
Now, we use the fact that $|A| - |B| = |A| - | - B| \leq |A + B|$. We see that this means that

$$\frac{1}{2} \sum_{i=1}^{n_u} |p(u)q_{u,v}^1(i) - p(u)q_{u,v}^1(i)| - \frac{1}{2} \sum_{i=1}^{n_v} |p(v)q_{u,v}^1(i) - p(v)q_{u,v}^1(i)| \leq p(u)p(v)(\alpha - 0.5)\mathcal{D}(u,v).$$

This means that:

$$\frac{1}{2} p(u) \sum_{i=1}^{n_u} |q_{u,v}^1(i) - q_{u,v}^1(i)| \leq p(u)p(v)(\alpha - 0.5)\mathcal{D}(u,v) + \frac{1}{2} |p(u) - p(v)| \sum_{i=1}^{n_v} q_{u,v}^1(i)$$

$$\frac{1}{2} \sum_{i=1}^{n_v} |q_{u,v}^1(i) - q_{u,v}^1(i)| \leq \frac{p(u)p(v)(\alpha - 0.5)\mathcal{D}(u,v) + \frac{1}{2} |p(u) - p(v)| p(u)}{p(u)}$$

$$\leq (p(v)(\alpha - 0.5) + \frac{1}{2})\mathcal{D}(u,v)$$

$$\leq \alpha \mathcal{D}(u,v).$$

□

We now show that satisfying $\alpha$-Notion 1 (or $\alpha$-Notion 2) is required for pipeline fairness when the metric $\delta^F$ is of a certain form. That is, we consider metrics $\delta$ on (cohort, individual) pairs with the following structure. For each pair of individuals $u$ and $v$, consider the metric $\delta_{u,v}$ defined by $\delta$ restricted to the set $\mathcal{U}_{u,v} = \{U_u \times \{u\}\} \times \{V_v \times \{v\}\}$. We focus on the case in which $\mathcal{U}_{u,v}$ has a partitioning into clusters s.t. $\delta_{u,v}$ is large across clusters and small within clusters. (In fact, the condition that we place on each cluster bears some resemblance to the standard requirements of an $(\alpha, \beta)$-cluster of a graph [23], though our condition is adapted to metric spaces.) We formally define “$(\alpha, \beta)$ metrics” as follows:

**Definition B.3** (($\alpha, \beta$)-Metrics). Let $d$ be a metric over some finite set $S$, and let $\beta > \alpha \geq 0$ be constants. Suppose that there exists a partition of $S$ into clusters that satisfies the following conditions: if $s_1, s_2 \in S$ are in the same cluster, then $d(s_1, s_2) \leq \alpha$; if $s_1, s_2 \in S$ are in different clusters, then $d(s_1, s_2) \geq \beta$. Then, we say that $d$ is an ($\alpha, \beta$)-metric, and we call the partition into clusters the induced partition [23].

Suppose that a metric $\delta$ over (cohort, individual) pairs has the property that for all pairs of individuals $u$ and $v$, $\delta_{u,v}$ is a ($\mathcal{D}(u,v), 1$)-metric. The collection of induced partitions for each $\delta_{u,v}$ gives a mapping. We call this mapping a coarsest mapping for $\delta$, because for every pair $u$ and $v$, it is not possible for the partition to merge two clusters and still respect $\delta$ (as per the requirements of Definition B.1). Moreover, it is straightforward to verify that this mapping is the unique coarsest mapping, using the fact that $\delta_{u,v}$ is a ($\mathcal{D}(u,v), 1$)-metric.

Now, suppose that $\delta^F$ is such that for all pairs of individuals $u$ and $v$, $\frac{1}{\alpha} \delta_{u,v}^F$ is a ($\mathcal{D}(u,v), \frac{1}{\alpha}$)-metric. For metrics of this form, we show that satisfying $\alpha$-Notion 1 (resp. $\alpha$-Notion 2) is necessary for pipeline fairness: the intuition for necessity is that the conversion of $\frac{1}{\alpha} \delta_{u,v}^F$ into a coarsest mapping is not lossy from a fairness perspective. That is, if $A$ does not satisfy $\alpha$-Notion 1 (resp. $\alpha$-Notion 2), we can construct a scoring function violating pipeline fairness: this scoring function can take advantage of similar individuals having different distributions of cohorts across clusters.

Our proofs will rely on a standard lemma about extensions of functions on metric spaces and we present a proof for the sake of being self-contained.

**Lemma B.4.** Let $\alpha > 0$ be a constant, and let $d$ be a pseudo-metric over $U$ and let $U' \subseteq U$. If $f : U' \rightarrow [0, 1]$ is $\alpha$-Lipschitz w.r.t. $d|U'$, then there exists a function $g : U \rightarrow [0, 1]$ such that $g|U' = f$ and that is $\alpha$-Lipschitz w.r.t. $d$.

**Proof.** Let $g' : U \rightarrow \mathbb{R}$ be defined by $g'(x) = \inf_{u \in U'} \{ f(u) + \alpha d(x, u) \}$. Observe that $g'|U' = f$. Moreover, $\forall x \in U$, observe that for every $\varepsilon > 0$, there exists $u' \in U'$ such that $g'(x) \leq f(u') + \alpha d(x, u') - \varepsilon$. Moreover, we have by definition that $g'(y) \leq f(u') + \alpha d(y, u')$. Thus: $g'(y) - g'(x) \leq f(u') + \alpha d(y, u') - (f(u') + $
\[ \alpha d(x, u^*) + \varepsilon \leq \alpha (d(y, u^*) - d(x, u^*)) + \varepsilon \leq \alpha d(x, y) + \varepsilon. \] Thus, \( g' \) is \( \alpha \)-Lipschitz w.r.t. \( d \). Now, we let \( g(x) = \min(1, g'(x)) \). We see that \( g|_{U'} = g'|_{U'} = f \) and \( g \) is \( \alpha \)-Lipschitz w.r.t. \( d \) since \( |g(y) - g(x)| \leq |g'(y) - g'(x)| \).

We first prove that the conditions in Theorem 3.5 are necessary for mass-moving distance, using the structure of \((\mathcal{D}(u, v), \frac{1}{\alpha})\)-metrics.

**Theorem 3.5** (Necessity for mass-moving-distance). Let \( \mathcal{F} \) be a family of scoring functions, and let \( \alpha \geq 1 \) be a constant. Suppose that \( \delta_\mathcal{F} \) has the property that for all pairs of individuals \( u \) and \( v \), \( \frac{1}{\alpha} d_{\mathcal{F}}^\alpha \) is a \((\mathcal{D}(u, v), \frac{1}{\alpha})\)-metric. Let \( (M_{u,v})_{u \neq \varepsilon \in U} \) be the coarsest mapping for \( \frac{1}{\alpha} \delta_\mathcal{F} \). Suppose that \( \mathcal{D}(u, v) < \frac{1}{\alpha} d_{\mathcal{F}}^\alpha \).

Suppose that \( A \) does not satisfy \( \alpha \)-Notion 1 (resp. \( \alpha \)-Notion 2) is not satisfied for \( (M_{u,v})_{u \neq \varepsilon \in U} \). Moreover, suppose that \( |p(u) - p(v)| = \mathcal{D}(u, v) \). Then, \( A \) is not \( \alpha \)-robust w.r.t. \( \mathcal{F} \) for \( d_{\alpha \text{-cond.MMD}} \) (resp. \( d_{\alpha \text{-cond.E}} \)).

**Proof of Theorem 3.5** Suppose that \( A \) does not satisfy \( \alpha \)-Notion 1 (resp. \( \alpha \)-Notion 2) for \( (M_{u,v})_{u \neq \varepsilon \in U} \). Then, there exists some pair of individuals \( u \) and \( v \) such that \( TV(q^1_{u,v}, q^1_{v,u}) > (\alpha - 0.5) \mathcal{D}(u, v) \) (resp. \( TV(q^2_{u,v}, q^2_{v,u}) > \alpha \mathcal{D}(u, v) \)). We construct a scoring function \( g \) where the mass-moving distance between \( S^u_{A|g} \) and \( S^v_{A|g} \) (resp. \( S^u_{C|A,g} \) and \( S^v_{C|A,g} \)) is larger than \( \alpha \mathcal{D}(u, v) \).

Fix \( \varepsilon > 0 \) sufficiently small. As before, let \( \Gamma_u \equiv (\mathcal{U} \times \{u\}) \cup (\mathcal{V} \times \{v\}) \) be the set of all (cohort, individual) pairs involving \( u \) or \( v \). We define a scoring function \( f : \Gamma_u \rightarrow [0, 1] \). As before, for every \( 1 \leq i \leq n_{u,v} \), let \( S(i) = \{(C, u) \in M^{-1}_{u,v}(i)\} \cup \{(C, v) \in M_{u,v}^{-1}(i)\} \) be the (cohort, individual) pairs appearing in cluster \( i \). For \( (C, x) \in S(i) \), we take \( f(C, x) = i(\alpha + \varepsilon) \mathcal{D}(u, v) \). Since \( \mathcal{D}(u, v) < \frac{1}{\alpha d_{\mathcal{F}}^\alpha} \), we can make \( \varepsilon \) small enough so that all of the scores are in \([0, 1] \).

Now, we show that \( f \) is \( 1 \)-Lipschitz with respect to \( \delta_\mathcal{F} \) restricted to the domain \( \Gamma_u \), for sufficiently small \( \varepsilon \). Within each cluster, \( f \) is constant, so clearly it is \( 1 \)-Lipschitz within each cluster. Now, consider (cohort, individual) pairs in different clusters. If \( (C, x), (C', y) \) are in different clusters, we know that \( \delta_\mathcal{F}((C, x), (C', y)) \geq 1 \) based on the fact that \( \frac{1}{\alpha} d_{\mathcal{F}}^\alpha \) is a \((\mathcal{D}(u, v), \frac{1}{\alpha})\)-metric, so \( d_{\mathcal{F}}^\alpha \) is a \((\alpha \mathcal{D}(u, v), 1)\)-metric.

Thus, \( f \) is \( 1 \)-Lipschitz.

We apply Lemma 3.4 to complete \( f \) into a function \( g : \mathcal{U} \times \mathcal{V} \rightarrow [0, 1] \) that is \( 1 \)-Lipschitz w.r.t. \( \delta_\mathcal{F} \).

We now show that the mass moving distance between \( S^u_{A|g} \) and \( S^v_{A|g} \) (resp. \( S^u_{C|A,g} \) and \( S^v_{C|A,g} \)) is larger than \( \alpha \mathcal{D}(u, v) \). Assume for sake of contradiction that the mass moving distance is \( \leq \alpha \mathcal{D}(u, v) \). That would mean that there exist \( \tilde{f}_1 \) and \( \tilde{f}_2 \), along with functions \( Z_1 \) and \( Z_2 \), that satisfy conditions 1 and 2 in the mass moving distance definition for \( (\alpha + \varepsilon/2) \mathcal{D}(u, v) \). By the “mass does not move far” condition, we know that for \( l \) = 1, 2, the support of the probability measure \( Z_i(\alpha + \varepsilon) \) is disjoint from the support of the probability measure \( Z_l(j(\alpha + \varepsilon)) \) for any \( 0 \leq i \leq j \leq n_{u,v} \). Thus, \( TV(\tilde{f}_1, \tilde{f}_2) \) must be at least \( TV(S^u_{A|g}, S^v_{A|g}) \) (resp. \( TV(S^u_{C|A,g}, S^v_{C|A,g}) \)). We see that \( TV(S^u_{A|g}, S^v_{A|g}) = TV(q^1_{u,v}, q^1_{v,u}) + 0.5\{1 - p(u) - (1 - p(v))\} = (\alpha + \varepsilon) \mathcal{D}(u, v) \) (resp. \( TV(S^u_{C|A,g}, S^v_{C|A,g}) = TV(q^2_{u,v}, q^2_{v,u}) = (\alpha + \varepsilon) \mathcal{D}(u, v) \)), which is a contradiction. This proves the desired statement.

When are our condition in Theorem 3.5 also “tight” for expected score fairness? We prove that our definition is necessary (up to Lipschitz constants) for expected score, again using the structure of \((\mathcal{D}(u, v), \frac{1}{\alpha})\)-metrics.

**Theorem 3.6** (Necessity for expected score). Let \( \mathcal{F} \) be a family of scoring functions, and suppose that \( \delta_\mathcal{F} \) has the property that for all pairs of individuals \( u \) and \( v \), \( \frac{1}{\alpha} d_{\mathcal{F}}^\alpha \) is a \((\mathcal{D}(u, v), \frac{1}{\alpha})\)-metric. Let \( (M_{u,v})_{u \neq \varepsilon \in U} \) be the coarsest mapping for \( \frac{1}{\alpha} \delta_\mathcal{F} \). Suppose that \( (\alpha + 0.5)\text{-Notion 1} \) (resp. \( \alpha \text{-Notion 2} \)) is not satisfied for \( (M_{u,v})_{u \neq \varepsilon \in U} \). Moreover, suppose that \( |p(u) - p(v)| = \mathcal{D}(u, v) \). Then, \( A \) is not \( \alpha \)-robust w.r.t. \( \mathcal{F} \) for \( d_{\alpha \text{-cond.MMD}} \) (resp. \( d_{\alpha \text{-cond.E}} \)).

**Proof of Theorem 3.6** Suppose that \( A \) does not satisfy \( \alpha \)-Notion 1 (resp. \( \alpha \)-Notion 2) for \( (M_{u,v})_{u \neq \varepsilon \in U} \). (See Definition 3.4) Then, there exists some pair of individuals \( u \) and \( v \) such that \( TV(q^1_{u,v}, q^1_{v,u}) > (\alpha + 0.5) \mathcal{D}(u, v) \) (resp. \( TV(q^2_{u,v}, q^2_{v,u}) > (\alpha + 0.5) \mathcal{D}(u, v) \)).
We construct a scoring function $f$ where $|\mathbb{E}[S^\text{NA,u}] - \mathbb{E}[S^\text{NA,v}]| > \alpha \mathcal{D}(u,v)$ (resp. $|\mathbb{E}[S^\text{CA,u}] - \mathbb{E}[S^\text{CA,v}]| > \alpha \mathcal{D}(u,v)$).

As before, let $\mathcal{P}_{u,v} = \{(u \times \{u\}) \cup (v \times \{v\}\}$ be the set of all (cohort, individual) pairs involving $u$ or $v$. We define a scoring function $f : \mathcal{P}_{u,v} \to \{0, 1\}$. As before, for every $1 \leq i \leq n_{u,v}$, let $S(i) = \{(C, u) \in M^{-1}_u(i)\} \cup \{(C, v) \in M^{-1}_v(i)\}$ be the (cohort, individual) pairs appearing in cluster $i$. Let’s partition $\{1, \ldots, n_{u,v}\}$ into two groups $P_1$ and $P_2$ as follows. WLOG, suppose that $p(u) \geq p(v)$. We define $P_1$ such that $q_{1,u}(i) \geq q_{1,v}(i)$ (resp. $q_{2,u}(i) \geq q_{2,v}(i)$) and define $P_2$ such that $q_{1,u}(i) < q_{1,v}(i)$ (resp. $q_{2,u}(i) < q_{2,v}(i)$).

Now, we show that $f$ is 1-Lipschitz with respect to $\delta^\mathcal{P}$ restricted to the domain $\mathcal{P}_{u,v}$, for sufficiently small $\epsilon$. Within each cluster, $f$ is constant, so clearly it is 1-Lipschitz within each cluster. Now, consider (cohort, individual) pairs in different clusters. If $(C, x), (C', y)$ are in different clusters, we know that $\delta^\mathcal{P}((C, x), (C', y)) = 1$ based on the fact that $\frac{1}{\alpha} d_{u,v}^\mathcal{P}$ is a $\mathcal{D}(u,v)$, $\frac{1}{\alpha}$-metric, so $d_{u,v}^\mathcal{P}$ is a $(\alpha \mathcal{D}(u,v), 1)$-metric. Thus, $f$ is 1-Lipschitz.

We apply Lemma 3.6 to complete $f$ into a function $g : \mathcal{C} \times U \to \{0, 1\}$ that is 1-Lipschitz w.r.t. $\delta^\mathcal{C}$. We now show that $|\mathbb{E}[S^\text{NA,u}] - \mathbb{E}[S^\text{NA,v}]| > \alpha \mathcal{D}(u,v)$ (resp. $|\mathbb{E}[S^\text{CA,u}] - \mathbb{E}[S^\text{CA,v}]| > \alpha \mathcal{D}(u,v)$). We see that $|\mathbb{E}[S^\text{NA,u}] - \mathbb{E}[S^\text{NA,v}]| = |\sum_{i \in P_1} q_{1,u}(i) - \sum_{i \in P_1} q_{1,v}(i)| = TV(q_{1,u}, q_{1,v}) > \alpha \mathcal{D}(u,v)$. (Similarly, we see that $|\mathbb{E}[S^\text{CA,u}] - \mathbb{E}[S^\text{CA,v}]| = |\sum_{i \in P_1} q_{2,u}(i) - \sum_{i \in P_1} q_{2,v}(i)| = TV(q_{2,u}, q_{2,v}) > \alpha \mathcal{D}(u,v)$.)

Theorem 3.6 is somewhat surprising for the following reason: by Theorem 3.5 Notion 1 (resp. Notion 2) in the theorem statement actually gives the stronger notion of mass-moving distance fairness, but we actually show that it is necessary even for the weaker notion of expected score. We can view this result as telling us that for certain classes of post-processing functions, we get the robustness w.r.t mass-moving distance “for free” as a consequence of robustness w.r.t expected score.

**APPENDIX C. EXTENDED DETAILS ON COHORT SELECTION MECHANISMS**

Two mechanisms for fair cohort selection were given in [6] based on converting an individually fair classifier for independent classification into a mechanism to select exactly $n$ individuals. The first, “Permute Then Classify” applies the fair classifier to each element in random order and either (1) stops when $n$ elements are selected or (2) chooses the remaining unclassified elements to get a total of $n$. The second, “Weighted Sampling” samples from the set of all cohorts of size $n$ where each cohort is assigned a probability proportional to the sum of the “weights” assigned to each element in the cohort by the fair classifier.

In this appendix, we give the formal specifications for each of these mechanisms, show that they satisfy the monotonicity property required in Lemma 3.6 and give an extension of weighted sampling to allow individually fair selection from an arbitrary set of cohorts.

**C.1. Permute then Classify.**

**Mechanism C.1 (PermuteThenClassify [6])**. Given a universe $U$, a cohort size $n \leq |U|$ and an individually fair classifier $C : U \to \{0, 1\}$, first choose a permutation $\pi \sim S_{|U|}$ uniformly at random from the symmetric group on $|U|$. Initialize an empty cohort $l$. Evaluating the elements of $U$ in the order specified by $\pi$, apply $C$ to each element. If $C(u) = 1$ and there are fewer than $n$ elements in the cohort, add $u$ to the cohort. If there are no more than $n - |l|$ elements left to be evaluated (i.e., the only way to select $n$ total is to accept all remaining elements), then add all remaining elements in the permutation to $l$.

**Theorem C.2 (Permute then Classify is individually fair [6])**. PermuteThenClassify is a solution to the Cohort Selection Problem for any $C$ that is individually fair when operating on all elements of the universe.

To satisfy the requirements of Lemma 4.6, it suffices to show that the Permute then Classify mechanism is monotone, i.e. if an individual $u$ is preferred to $v$, then the probability of choosing any cohort with $u$ swapped for $v$ is larger than the probability of selecting the original cohort.
Lemma C.3 (PermuteThenClassify is monotone). The permute then classify mechanism is monotone, i.e.,
\[
\Pr[\mathcal{P}_{C,n,N} \cap \mathcal{X} = l \cup x] \geq \Pr[\mathcal{P}_{C,n,N} = l \cup y] \text{ if } \Pr[C(x) = 1] \geq \Pr[C(y) = 1],
\]
where \(\mathcal{P}_{C,n,N}\) is the permute then classify mechanism instantiated with a randomized classifier \(C : U \times r \to \{0, 1\}\) choosing \(n\) elements from a set of \(N\).

Proof. Recall that Permute then Classify first chooses a permutation uniformly at random from the symmetric group on \(|N|\), \(\pi \sim \mathcal{S}(\{N\})\) for an input of size \(N\). It then runs \(C\) on each element until either there are \(n\) elements ”accepted” by \(C\), or there only enough elements left in the permutation to make \(n\), in which case all remaining elements are selected.

Fix a pair of elements \(x\) and \(y\). Consider any permutation \(\pi\) and any set of elements \(l\) such that \(|l| = n - 1\) and \(x \notin l\) and \(y \notin l\). Without loss of generality, suppose that \(x\) appears before \(y\) in \(\pi\). Call the permutation with \(x\) and \(y\) swapped \(\pi'\).

Call the elements of \(l\) that appear before \(x\), \(l_1\), those that appear in between \(x\) and \(y\), \(l_2\) and those that appear after \(y\), \(l_3\).

Given \(\pi\), the probability of choosing \(C \cup x = \Pr[l_1] \ast \Pr[C(x) | l_1] \ast \Pr[l_2 | l_1, C(x)] \ast \Pr[l_3 | l_1, l_2, C(x), C(y)]\). Notice that this statement is equivalent with \(x\) and \(y\) switched under \(\pi'\).

Given \(\pi\), the probability of choosing \(C \cup y = \Pr[l_1] \ast \Pr[C(x) | l_1] \ast \Pr[l_2 | l_1, C(x)] \ast \Pr[l_3 | l_1, l_2, C(y)]\). As above, this statement is equivalent with \(x\) and \(y\) switched under \(\pi'\).

Notice that \(\Pr[l_3 | l_1, l_2, C(x), C(y)] = \Pr[l_3 | l_1, l_2, C(y), C(x)]\), etc as the probability is only dependent on having a sufficient number of slots left.

Thus, we can relate the probability of \(C \cup x\) chosen under \(\pi\) or \(\pi'\) to the probability of choosing \(C \cup y\):
\[
\begin{align*}
\Pr[C \cup x | \pi \vee \pi'] - \Pr[C \cup y | \pi \vee \pi'] &= \Pr[l_1, l_2, l_3]|(1 - C(y)) C(x) - (1 - C(x)) C(y)| \ast 2 \\
\Pr[C \cup x | \pi \vee \pi'] - \Pr[C \cup y | \pi \vee \pi'] &\geq 0
\end{align*}
\]

Thus, we conclude that Permute then Classify is monotone.

\(\square\)

C.2. Weighted Sampling

First we introduce the weighted sampling mechanism, as described in [6].

Mechanism C.4 (Weighted Sampling [6]). Given an individually fair classifier \(C : U \to \{0, 1\}\), and a cohort size \(n\), define the \(L\) to be the set of subsets of \(U\) of size \(n\). Assign each subset \(l \in L\) weight \(w(l) \leftarrow \sum_{u \in l} \mathbb{E}[C(u)]\). Define a distribution over sets of size \(n\), \(\mathcal{X}\) such that the weight of \(l\) under \(\mathcal{X}\) is \(\frac{w(l)}{\sum_{l' \in \mathcal{X}} w(l')}\). Choose a set according to \(\mathcal{X}\) as output.

Theorem C.5 (Weighted sampling is individually fair [6]). For any individually fair classifier \(C\) such that the \(\Pr_{\sim U}[C(u) = 1] \geq 1 / |U|\), weighted sampling is individually fair.

Notice that the specification of the weighted sampling mechanism immediately implies that the mechanism is monotone, as \(w(C) = w(\{C \setminus \{u\}\} \cup \{v\}) + C(u) - C(v)\). Despite this monotonicity property, WeightedSampling still runs into issues with Notion 2.

Proposition C.6. Suppose that WeightedSampling is run with \(\sum_{u \in U} \frac{w(u)}{\mathbb{E}} = 1\). It does not satisfy \(\alpha_1\)-Notion 2 (Definition 3.4.2) for any constant \(\alpha_1\) that is independent of \(|U|\), \(k\) (the size of the cohort), \(\{w(u)\}_{u \in U}\).

Proof. To show this counter-example, we take the (realistic) infinite sequence of \((k, U)\) pairs where \(k << U\) and choose weights in terms of these quantities, and show that no such constant \(\alpha_1\) independent of \(k\) and \(U\) exists. Let \(S = \sum_{u \in U} \frac{w(u)}{\mathbb{E}}\), which we set to 1. Suppose that \(w(y) = 0.5\) for some \(y \in U\). Suppose that \(w(0) = 0\) and \(w(1) = S\left(\frac{k \log k}{k - 1} - \frac{k - 1}{k - 1}\right)\left(\frac{|U| - 1}{|U| - 1}\right)\). A straightforward calculation using the expression for sampling probability in Weighted Sampling and simplifying shows that \(p(x) = \frac{w(x)}{S|U| - k} + \frac{k - 1}{|U| - 1}\) for all \(x \in X\). Plugging this in, we obtain that \(p(u) = \frac{k - 1}{|U| - 1}\) and \(p(v) = \frac{k \log k}{|U| - 1}\).

We take a particular set of cohorts where the contribution to total variation distance will blow-up. Let’s consider all cohorts \(C\) with \(y, u\) and \(k - 2\) elements not including \(v\). Let’s also consider their corresponding
mapped sets using the swapping mapping. Observe that the probability that \( C = C' \cup \{ u \} \) is chosen is \( \frac{w(u)+\sum_{x \in C} w(x)}{N} \) and the probability that \( C' \cup \{ v \} \) is chosen is \( \frac{w(v)+\sum_{x \in C} w(x)}{N} \) where \( N = (|U|-1)S \). Thus the contribution to the total variation distance of \( C \) is:

\[
Q = \left| \frac{w(u)+\sum_{x \in C} w(x)}{Np(u)} - \frac{w(v)+\sum_{x \in C} w(x)}{Np(v)} \right| = \left| \frac{1}{\binom{|U|-1}{k-1}} \left( \frac{w(u)/S}{p(u)} - \frac{w(v)/S}{p(v)} + \frac{k-1}{|U|-k} \left( \frac{1}{p(u)} - \frac{1}{p(v)} \right) \right) \right|.
\]

Now, observe that

\[
\frac{w(u)/S}{p(u)} = \frac{w(u)/S}{(w(u)/S) \left( \frac{|U|-k}{|U|-1} \right) + \frac{k-1}{|U|-1}} = \frac{|U|-1}{|U|-k} \frac{w(u)/S}{|U|-k} \left( \frac{1}{p(v)} - \frac{1}{p(u)} \right).
\]

This is equal to:

\[
\frac{|U|-1}{|U|-k} \left( 1 - \frac{k-1}{|U|-1} p(u) \right).
\]

Now, this means that

\[
\frac{w(u)/S}{p(u)} - \frac{w(v)/S}{p(v)} = \frac{k-1}{|U|-k} \left( \frac{1}{p(v)} - \frac{1}{p(u)} \right).
\]

Thus, we know that

\[
Q = \left| \frac{1}{p(u)} - \frac{1}{p(v)} \right| \left \lfloor \frac{1}{\binom{|U|-1}{k-1}} \sum_{x \in C} w(x) \right \rfloor S - \frac{k-1}{|U|-k}.
\]

Using the fact that \( y \in C \), we can rewrite this as:

\[
Q = \left| \frac{1}{p(u)} - \frac{1}{p(v)} \right| \left \lfloor \frac{1}{\binom{|U|-1}{k-1}} \frac{w(v)+\sum_{x \in C \setminus \{ y \}} w(x)}{S} - \frac{k-1}{|U|-k} \right \rfloor.
\]

Observe that \( \frac{w(v)+\sum_{x \in C \setminus \{ y \}} w(x)}{S} \geq \frac{0.5}{S} = 0.5. \) If \( |U| >> k \), then this is bigger than \( \frac{k-1}{|U|-k} \). Thus, we see that:

\[
Q \geq \left| \frac{1}{p(u)} - \frac{1}{p(v)} \right| \left \lfloor \frac{1}{\binom{|U|-1}{k-1}} \right \rfloor 0.5 - \frac{k-1}{|U|-k}.
\]

When \( |U| >> k \), we see that:

\[
Q \geq \left| \frac{1}{p(u)} - \frac{1}{p(v)} \right| \left \lfloor \frac{1}{\binom{|U|-1}{k-1}} \right \rfloor 0.4.
\]

Now, let’s sum over all cohorts \( C \) containing \( y, u \) and \( k-2 \) elements not including \( v \). Thus, there are \( \binom{|U|-3}{k-2} \) cohorts to sum over, so we obtain:

\[
\left| \frac{1}{p(u)} - \frac{1}{p(v)} \right| \frac{\binom{|U|-3}{k-2}}{\binom{|U|-1}{k-1}} 0.25 = \left| \frac{1}{p(u)} - \frac{1}{p(v)} \right| \frac{0.4(k-1)}{|U|-k}.
\]

When \( |U| >> k \), this can be lower bounded by:

\[
\left| \frac{1}{p(u)} - \frac{1}{p(v)} \right| 0.25 \frac{(k-1)}{|U|-1}.
\]

Using our settings for \( p(u) \) and \( p(v) \), we see that \( \frac{1}{p(u)} - \frac{1}{p(v)} = \frac{|U|-1}{k-1} - \frac{|U|-1}{k \log k} \). When \( k \) is sufficiently large, the distance becomes roughly 0.25 instead of \( \frac{k \log k}{|U|-1} \), so there is no such constant \( c_1 \) since \( \frac{|U|-1}{k \log k} \) is unbounded as \( |U| \to \infty \) when \( k << |U| \).

delimiter
C.3. **Adapting weighted sampling for structured cohort sets.** Permute then Classify and Weighted Sampling behave *almost* as if individuals are classified independently, i.e., the probability of selecting an individual depends only on their independent classification probability and whether there is space left in the cohort. However, these solutions have a considerable drawback in practice: they are unstructured. For example, a college admitting a class of 70% female students or 90% athletes would cause significant churn in the resources and facilities needed year over year. To best utilize its resources, and perhaps more importantly to expose students to classmates with a variety of backgrounds and interests, the college would naturally want to impose some structure on the classes admitted.

Fortunately, weighted sampling can be adapted to select cohorts with some underlying structure in an individually fair way. Given a set of “acceptable” cohorts \( C \), i.e., cohorts satisfying some property like a diverse set of student interests, weighted sampling (with weights based on a solution to a linear program constraining differences in selection probability for each individual, as in the original linear program in [5]) can be used to select a single cohort. Roughly speaking, the constraints for solving this linear program concern the number of cohorts in \( C \) in which each individual appears, not their relative qualification or distances within these cohorts. While we can imagine such a setup being used for good reason, it can also be abused to construct cohorts that justify discrimination in later stages. Returning to the malicious example from the introduction, notice that a set of “acceptable cohorts” could be the set of cohorts which mostly satisfy the property that the most talented person in the cohort is not a minority candidate, giving the veneer of individual fairness to a pipeline explicitly constructed to unfairly discriminate.

**Theorem C.7.** Given a universe \( U \) and a distance metric \( \mathcal{D} \) and a set of permissible cohorts \( C \), such that the subset of permissible cohorts \( C^u \) containing an individual \( u \) and the subset of permissible cohorts \( C^v \) containing an individual \( v \) satisfy \( \frac{|C^u| - |C^v|}{|C|} \leq \mathcal{D}(u, v) \) and there exists a subset of cohorts \( C^p \subseteq C \) such that no element appears in more than one cohort in \( C^p \) and \( C^p \) forms a partition of \( U \), then there exists a set of weights for the cohorts in \( C \) such that choosing a single cohort by sampling proportional to these weights results in individual fairness.

**Proof.** First, we translate the requirements for individual fairness and constructing the set of weights into a linear program with variables \( w_i \) for each cohort in \( C \).

\[
\{w_i | i \in [|C|]\} \text{ s.t.} \begin{cases} w_i \geq 0, & \sum_i w_i = 1 \\
|\sum_{i \in C^u} w_i - \sum_{i \in C^v} w_i| \leq D(u, v) & \forall u, v \in U \\
|\sum_{i \in C^u} w_i - \sum_{i \in C^v} w_i| \leq D(u, v) & \forall u, v \in U \\
\end{cases}
\]

To solve the system, we take the following steps:

1. Solve the system without the non-negativity constraint.
2. Determine the maximum magnitude negative weight, and call the magnitude \( w_* \).
3. Add \( w_* \) to all weights in the original solution.
4. Take \( y = \sum w_i = 1 + |C|w_* \).
5. Divide all weights by \( y \).

Notice that Steps 3-5 ensure that all weights are positive in the total sum of the weights is equal to 1. Thus it remains to characterize under what conditions the distance constraints are also satisfied after the adjustments in Steps 3-5. Given the requirement that a subset of \( C \) exactly partition \( U \), there always exists a solution to the system which is to place equal weight on each of the cohorts in the partition subset.

Notice that the adjustments do not violate the distance constraints when each element appears an equal number of sets. To handle the more general case, take \( y_{u,v} = ||C^u| - |C^v|| \), i.e. the difference in the number of cohorts \( u \) and \( v \) appear in. Without loss of generality, assume that \( u \) participates in more cohorts than \( v \). To satisfy the distance constraints we need

\[
(y_{u,v} w_* + \sum_{i \in C^u} w_i - \sum_{i \in C^v} w_i) \frac{1}{y} \leq \mathcal{D}(u, v)
\]
which follows from applying the steps above.

In the worst case, the original solution took on the maximum distance between $u$ and $v$. Substituting $\sum_{i \in C^u} w_i - \sum_{i \in C^v} w_i = \mathcal{D}(u,v)$,

$$(y_{u,v}w_s + \mathcal{D}(u,v)) \frac{1}{y} \leq \mathcal{D}(u,v)$$

$$y_{u,v}w_s \leq \mathcal{D}(u,v)(y-1)$$

Substituting for the value of $y$:

$$y_{u,v}w_s \leq \mathcal{D}(u,v) |C| w_s$$

$$\frac{y_{u,v}}{|C|} \leq \mathcal{D}(u,v)$$

Thus, so long as the condition requiring that every pair of individuals participate in a similar number of cohorts is satisfied, the theorem statement holds. \qed

Thus, as long as the difference in number of sets participated in for each pair as a fraction of the total number of sets is less than the distance between the pairs and the permissible cohorts and for partition of the universe, a solution can be found. Such requirements are reasonably easy to check before attempting to solve the system and in specifying the cohorts.

APPENDIX D. DETAILS FOR SECTION 4

D.1. A pathological scoring function family. Unfortunately, it is not possible to achieve robustness with respect to arbitrary families of intra-cohort individually fair mechanisms: there are pathological classes of scoring functions in which there is no robust cohort selection mechanism. Example D.1 below illustrates a set of permissible cohorts $C$ and scoring function $f$ for which there is no robust, individually fair cohort selection mechanism.

Example D.1. Consider a universe $U = \{a, b, c\}$ of three equivalent individuals, and a fairness metric such that $\mathcal{D}(x,y) = 0$ for all $x, y \in U$. Suppose that $C = \{a, b\}, \{a, c\}, \{b, c\}$ and $f$ is a scoring function defined so that: $f(\{a, b\}, a) = f(\{a, b\}, b) = 0$, $f(\{a, c\}, a) = f(\{a, c\}, c) = 1$, and $f(\{b, c\}, b) = f(\{b, c\}, c) = 0.5$.

If $A$ is an individually fair cohort selection mechanism, then $A(\{a, b\}) = A(\{a, c\}) = A(\{b, c\})$. The unconditional expected scores are $E[S_a^{N,A,f}] = 1/3$, $E[S_b^{N,A,f}] = 1/6$, and $E[S_c^{N,A,f}] = 1/2$, and the conditional scores are $E[S_a^{N,A,f}] = 1/2$, $E[S_b^{N,A,f}] = 1/4$, and $E[S_c^{N,A,f}] = 3/4$. Thus, no individually fair cohort selection mechanism $A$ is robust with respect to $f$.

The fundamental issue in Example D.1 is that $f$ is permitted to deviate wildly between cohorts, and as a result $d^{(f)}$ is large on cohort contexts that look intuitively identical. In practice, if the original cohort selection mechanism has some control over the determination of $C$, such pathological cases may be avoidable.

D.2. Proofs for Section 4. We prove Proposition 4.2 restated here.

Proposition D.2 (Restatement of Proposition 4.2). Consider the mapping that, for each pair of individuals $u$ and $v$, places all of the cohort contexts in $(C_u \times \{u\}) \cup (C_v \times \{v\})$ into the same cluster. If $A$ is individually fair, then $A$ satisfies 0.5-Notion 1 and 0.5-Notion 2 w.r.t. this mapping.

Proof. Pick any pair of individuals $u$ and $v$. Using the mapping described in the proposition statement, we know that $TV(q_{u,v}^1, q_{v,u}^1) = 0.5|p(u) - p(v)| \leq 0.5\mathcal{D}(u,v)$, and $TV(q_{u,v}^2, q_{v,u}^2) = 0$, as desired. \qed
D.3. **Proofs for Section 4.1** We prove Lemma 4.6 restated here. The intuition for the link between the monotonicity property and the swapping mapping is that the probability masses on a cohort containing $u$ and a cohort containing $v$ that are paired in the swapping mapping are directionally aligned.

**Lemma D.3** (Restatement of Lemma D.8). Suppose that $\mathcal{C} \subseteq 2^U$ is the set of cohorts of size $k$. If $A$ is monotonic, then $A$ satisfies 0.5-Notion 1 for the swapping mapping.

*Proof.* Pick any pair of individuals $u$ and $v$. WLOG assume that $p(u) \geq p(v)$. Since $A$ is monotonic, we see that

\[
TV(q^1_{u,v}, q^1_{v,u}) = 0.5 \sum_{C \subseteq U, |C| = k-1, u, v \notin C} |A(C \cup \{u\}) - A(C \cup \{v\})| \\
= 0.5 \sum_{C \subseteq U, |C| = k-1, u, v \notin C} (A(C \cup \{u\}) - A(C \cup \{v\})) \\
= 0.5 \left( \sum_{C \subseteq U, |C| = k-1, u, v \notin C} A(C \cup \{u\}) \right) - 0.5 \left( \sum_{C \subseteq U, |C| = k-1, u, v \notin C} A(C \cup \{v\}) \right) \\
= 0.5 \left( \sum_{C \subseteq U, |C| = k-1, u, v \notin C} A(C) \right) - 0.5 \left( \sum_{C \subseteq U, |C| = k-1, u, v \notin C} A(C) \right) \\
= 0.5 |p(u) - 0.5p(v)| \leq 0.5\mathbb{D}(u,v). 
\]

We now analyze the Conditioning Mechanism (Mechanism 4.7), restated here:

**Mechanism D.4** (Conditioning Mechanism). Given a weight function $w : U \rightarrow [0, 1]$, for each $u \in U$, independently draw from $\mathbb{1}_u \sim \text{Bern}(w(u))$. Denote the set of individuals with $\mathbb{1}_u = 1$ as $S$. If $|S| \geq k$, choose a cohort of $k$ individuals uniformly at random from $S$. Otherwise, repeat.

We show that under mild conditions, the Conditioning Mechanism is individually fair, robust, and allows for a degree of mechanism expressiveness.

**Lemma D.5.** Let $k$ be the size of the cohorts in $\mathcal{C}$, and assume that $k \geq 2$. Let $\alpha_1$, $\alpha_2$, and $\alpha_3$ be constants defined as follows: $\alpha_1 = 1.6$ when $k \geq 12$ and $\alpha_1 = 13$ when $2 \leq k \leq 12$, $\alpha_2 = 12$, and $\alpha_3 = 0$ when $k < 54$ and $\alpha_3 = 0.2$ when $k \geq 54$ and $\alpha_3 = 0.485$ when $k \geq 180$. Consider the Conditioning Mechanism with $1/\alpha_1$-individually fair weights satisfying $\sum_{x \in U} w(x) \geq 3k/2$. The mechanism is individually fair, satisfies $\alpha_2$-Notion 2, and concludes in expectation within $\alpha_1$ rounds. Moreover, if $\sum_{x \in U} w(x) = 3k/2$, then $|p(u) - p(v)| \geq \alpha_3 |w(u) - w(v)|$ and $\alpha_3 w(u) \leq p(u) \leq \alpha_1 w(u)$.

Thus, with a lower bound on the total sum of weights, the Conditioning Mechanism satisfies Notion 2. Moreover, if the sum of weights is tuned exactly to $3k/2$, then the resulting mechanism is also expressive: the difference between $|p(u) - p(v)| \geq 0.485 |w(u) - w(v)|$ for sufficiently large $k$, so dissimilar people have dissimilar probabilities of being selected. Moreover, by setting $w(x) = 0$, the mechanism will make $x$ never appear, and by setting $w(x) = 1$, the mechanism will make $p(x) \geq 0.485$ for sufficiently large $k$.

Now, we prove Lemma D.5 We first prove the following helpful Proposition.
Proposition D.6. The Conditioning Mechanism run with individually fair weights \( w(x) \) (i.e. \(|w(x) - w(y)| \leq \phi(x,y)\)) is \( \eta_1 \)-individually fair and satisfies \( \eta_2 \)-Notion 2 for \( \eta_1 \) and \( \eta_2 \) defined as follows. For subsets \( S \subseteq S' \subseteq U \), let:

\[
P^{S'}[S] = \left( \prod_{x \in S} w(x) \right) \left( \prod_{x \notin S, x \in S'} (1 - w(x)) \right).
\]

Let:

\[
\eta_1 = \left( \sum_{S \subseteq U, |S| \geq k} p^U[S] \right)^{-1}.
\]

\[
\eta_2 = 4 \left( 1 + \max \left( \frac{1}{k} \sum_{S \subseteq U, u,v \notin S, |S| = k-2} (p^U \setminus \{u,v\})[S] \right) \right).
\]

Moreover, the following equalities are true:

\[
p(u) = \frac{w(u) \sum_{S \subseteq U, u \notin S, |S| \geq k-1} (p^U \setminus \{u\})[S] \cdot \frac{k}{|S|+1}}{\sum_{S \subseteq U, |S| \geq k} p^U[S]}.
\]

\[
|p(u) - p(v)| = \frac{|w(u) - w(v)| \sum_{S \subseteq U, |S| \geq k} p^U \setminus \{u,v\}[S] \cdot \frac{k}{|S|+1}}{\sum_{S \subseteq U, |S| \geq k} p^U[S]}.
\]

Proof. The proof consists of two main parts. First, we derive the appropriate expressions for \( p(u) \) and \( p(v) \) to show that the conditioning mechanism is \( \eta_1 \)-individually fair. Second, we prove that the conditioning mechanism satisfies \( \eta_2 \)-Notion 2 (Definition 3.4): we do this by analyzing the total variation distance between the distributions for \( u \) and \( v \) by breaking into three cases depending on whether \( u \) or \( v \) both are in the initial set selected by the mechanism.

**Part 1.** Observe that \( P^{S'}[S] \) is the probability that the set \( S \) is initially chosen when the Conditioning Mechanism were to run on the universe \( S' \). Although the actual universe is \( U \), we introduce this quantity since it turns out to be convenient in the analysis. Observe the probability of having \( \geq k \) elements in the set initially chosen by the Conditioning Mechanism is \( \sum_{S \subseteq U, |S| \geq k} p^U[S] = \eta_1^{-1} \). (Note: for convenience, we will write \( \sum_S \) to mean \( \sum_{S \subseteq U} \) in subsequent formulae for brevity.)

First, we compute \( p(u) \). Suppose a set \( S' \) of \( \geq k \) elements is initially drawn by the Conditioning Mechanism. If \( u \notin S' \), then \( u \) is not in the cohort. Otherwise, there is a \( \frac{k}{|S'|} \) probability that \( u \) is in the cohort. In this case, let \( S = S' \setminus \{u\} \). We see that this means that:

\[
p(u) = \eta_1 \sum_{S \subseteq S', |S| \geq k} (p^U[S']) \cdot \frac{k}{|S'|} = \frac{w(u) \sum_{S \subseteq U, |S| \geq k-1} (p^U \setminus \{u\})[S] \cdot \frac{k}{|S|+1}}{\sum_{S \subseteq U, |S| \geq k} p^U[S]}.
\]

We can also write

\[
p(u) = \frac{w(u)w(v) \sum_{u,v \notin S, |S| \geq k-2} (p^U \setminus \{u,v\})[S] \cdot \frac{k}{|S|+2} + w(u)(1 - w(v)) \sum_{u,v \notin S, |S| \geq k-1} (p^U \setminus \{u,v\})[S] \cdot \frac{k}{|S|+1}}{\sum_{S \subseteq U, |S| \geq k} p^U[S]}.
\]

\[
p(v) = \frac{w(u)w(v) \sum_{u,v \notin S, |S| \geq k-2} (p^U \setminus \{u,v\})[S] \cdot \frac{k}{|S|+2} + w(v)(1 - w(u)) \sum_{u,v \notin S, |S| \geq k-1} (p^U \setminus \{u,v\})[S] \cdot \frac{k}{|S|+1}}{\sum_{S \subseteq U, |S| \geq k} p^U[S]}.
\]
This implies that

\[
|p(u) - p(v)| = \frac{|w(u) - w(v)| \sum_{u,v \in S, |S| \geq k} (p_{U}^{k-1} \cdot \frac{k}{|S| + 1})}{\sum_{S, |S| \geq k} p_{U}^{k}}
\]

\[
\leq \frac{|w(u) - w(v)| \sum_{u,v \in S, |S| \geq k} (p_{U}^{k-1} |S|)}{\sum_{S, |S| \geq k} p_{U}^{k}}
\]

\[
\leq \frac{|w(u) - w(v)|}{\sum_{S, |S| \geq k} p_{U}^{k}} = \eta_1 |w(u) - w(v)|.
\]

Thus, the conditioning mechanism is $\eta_1$-individually fair.

**Part 2.** Now, we compute the TV distance to show the Notion 2 (Definition 3.4.2) properties. Let $S$ be the set of elements initially selected by the Conditioning Mechanism. We condition on the event $|S| \geq k$ and compute the total variation distance. There are three relevant cases:

1. $u$ and $v$ are both in $S$
2. $u$ is in $S$ and $v$ is not in $S$
3. $v$ is in $S$ and $u$ is not in $S$

We define:

\[
\kappa_1 = \sum_{u,v \in S, |S| \geq k} (p_{U}^{k-1} |S| \cdot \frac{k}{|S| + 1})
\]

\[
\kappa_2 = \sum_{u,v \in S, |S| \geq k-2} (p_{U}^{k-1} |S| \cdot \frac{k}{|S| + 2}).
\]

In this notation, we have that:

\[
p(u) = \eta_1 w(u)(w(v) \kappa_2 + (1 - w(v)) \kappa_1)
\]

and

\[
p(v) = \eta_1 w(v)(w(u) \kappa_2 + (1 - w(u)) \kappa_1).
\]

Let $S$ be a subset of size of at least $k$ that is initially chosen by the mechanism, and let $R \subseteq S$ be the size $k$ subset that is finally chosen. We see that the probability $R$ is chosen given $S$ is $\frac{1}{\binom{v}{k}}$, and the probability that $S$ is chosen is $\eta_1 p_{U}^{k} |S|$, where the $\eta_1$ comes from the fact that if the mechanism starts over if it chooses a set of size $< k$. We now consider (1), (2), and (3) separately, and do a triangle inequality between the contributions to the total variation distance of these three cases. For each of these cases, there are three possible states for $R$. Either

(a) $R$ contains $u$ and $v$,
(b) $R$ contains one of $u$ and $v$, or
(c) $R$ contains neither.

First, we consider case (1). Here, case (c) contributes nothing to the TV distance.

Case (a) contributes $\eta_1 \frac{p_{U}^{k-1} |S|}{\binom{v}{k}} \cdot \frac{1}{\binom{v}{k}}$ by construction. Summing over possible $R$ and $S$ for this case, we see that the contribution to TV distance is:

\[
\frac{1}{2} \eta_1 \sum_{u,v \in S, |S| \geq k} P_{U}^{k} |S| \left( \sum_{u,v \in S, |S| = k} \left| \frac{1}{p(u)} - \frac{1}{p(v)} \right| \right).
\]
Case (b), due to the swapping mapping (Definition 4.4) and symmetry, contributes \( \eta_1 \frac{P^U[S]}{\mu_1} - \frac{P^U[S]}{\mu_2} \).

For case (b), if \( u \in R \), we let \( R' = R \setminus \{u\} \) and if \( v \in R \), we let \( R' = R \setminus \{v\} \). Summing over possible \( R \) and \( S \) for this case, we see that the contribution to TV distance is:

\[
\frac{1}{2} \eta_1 \sum_{u,v \in S, |S| \geq k} P^U[S] \left( \frac{1}{|S|^k} \left( \sum_{R \subseteq S, |R| = k-1, u \in R} \left| \frac{1}{p(u)} - \frac{1}{p(v)} \right| + \sum_{R' \subseteq S, |R'| = k-1, u \in R'} \left| \frac{1}{p(u)} - \frac{1}{p(v)} \right| \right) \right).
\]

Thus, the total contribution to the total variation distance for (1) is:

\[
\frac{1}{2} \eta_1 \left( \sum_{u,v \in S, |S| \geq k} P^U[S] \left( \frac{1}{|S|^k} \left( \sum_{R \subseteq S, |R| = k} \left| \frac{1}{p(u)} - \frac{1}{p(v)} \right| \right) \right) \right).
\]

We can write this as:

\[
\frac{1}{2} \eta_1 \left| \frac{1}{p(u)} - \frac{1}{p(v)} \right| \sum_{u,v \in S, |S| \geq k} P^U[S] \left( \frac{|S|^k}{|S|^k} \left( \sum_{R \subseteq S, |R| = k} 1 \right) \right) \sum_{u,v \in R, |S| \geq k} P^U[S] \left( \frac{|S|^k}{|S|^k} \right),
\]

which is equal to:

\[
\frac{1}{2} \eta_1 \left| \frac{1}{p(u)} - \frac{1}{p(v)} \right| \sum_{u,v \in S, |S| \geq k} P^U[S] \left( \frac{|S|^k}{|S|^k} \right) \sum_{u,v \in S, |S| \geq k} P^U[S] \left( \frac{|S|^k}{|S|^k} \right),
\]

which is equal to:

\[
\frac{1}{2} \eta_1 \left| \frac{1}{p(u)} - \frac{1}{p(v)} \right| \sum_{u,v \in S, |S| \geq k} P^U[S] \left( \frac{|S|^k}{|S|^k} \right) = \frac{1}{2} \eta_1 \left| \frac{1}{p(u)} - \frac{1}{p(v)} \right| \sum_{u,v \in S, |S| \geq k} P^U[S] \left( \frac{|S|^k}{|S|^k} \right),
\]

This can be written as:

\[
\frac{1}{2} \left| \frac{w(v) \kappa_2}{w(v) \kappa_2 + (1 - w(v)) \kappa_1} - \frac{w(u) \kappa_2}{w(u) \kappa_2 + (1 - w(u)) \kappa_1} \right| = \frac{1}{2} \frac{\kappa_1 \kappa_2 |w(v) - w(u)|}{(w(v) \kappa_2 + (1 - w(v)) \kappa_1)(w(u) \kappa_2 + (1 - w(u)) \kappa_1)}.
\]

Now we consider cases (2) and (3), which follow symmetric arguments. Of the three possible states for \( R \), (a) is not possible for cases (2) and (3) and (c) contributes nothing to TV distance. Thus, we only need to consider (b). With the swapping mapping, we can match \( u \in R \subseteq S \) with \( v \in \{R \setminus \{u\} \cup \{v\} \subseteq (S \setminus \{u\}) \cup \{v\} \).

Let \( S' = S \setminus \{u\} \) and \( R' = R \setminus \{u\} \). This contributes \( \eta_1 \frac{P^U[S', u, v]}{\mu_1} \left| \frac{w(u) - w(v)}{p(u)} - \frac{w(v) - w(u)}{p(v)} \right| \) to the total variation distance. Summing over \( S \) and \( R \) for this case, the total contribution to the total variation distance is:

\[
\frac{1}{2} \eta_1 \sum_{u,v \notin S', |S'| \geq k-1} P^U[S', u, v] \left( \frac{1}{|S'|^{k-1}} \left( \sum_{R' \subseteq S', |R'| = k-1} \left| \frac{w(u) - w(v)}{p(u)} - \frac{w(v) - w(u)}{p(v)} \right| \right) \right).
\]

This can be written as:

\[
\frac{1}{2} \sum_{u,v \notin S', |S'| \geq k-1} P^U[S', u, v] \left( \frac{1}{|S'|^{k-1}} \left( \sum_{R' \subseteq S', |R'| = k-1} \left| \frac{1 - w(v)}{w(v) \kappa_2 + (1 - w(v)) \kappa_1} - \frac{1 - w(u)}{w(u) \kappa_2 + (1 - w(u)) \kappa_1} \right| \right) \right),
\]

which can be simplified

\[
\frac{1}{2} \left| \frac{1 - w(v)}{w(v) \kappa_2 + (1 - w(v)) \kappa_1} - \frac{1 - w(u)}{w(u) \kappa_2 + (1 - w(u)) \kappa_1} \right| \sum_{u,v \notin S', |S'| \geq k-1} P^U[S', u, v] \left( \frac{1}{|S'|^{k-1}} \left( \sum_{R' \subseteq S', |R'| = k-1} 1 \right) \right),
\]

which is equal to:

\[
\frac{1}{2} \left| \frac{1 - w(v)}{w(v) \kappa_2 + (1 - w(v)) \kappa_1} - \frac{1 - w(u)}{w(u) \kappa_2 + (1 - w(u)) \kappa_1} \right| \sum_{u,v \notin S', |S'| \geq k-1} P^U[S', u, v] \left( \frac{1}{|S'|^{k-1}} \right),
\]
Hence, the total variation distance is upper bounded by 4.

Thus,

\[ \frac{1}{2} \left| \frac{(1 - w(v))(1 - w(u))}{w(v)K_2 + (1 - w(v))K_1} - \frac{(1 - w(u))}{w(u)K_2 + (1 - w(u))K_1} \right| \sum_{u,v \in S, |S| \geq k-1} p^U \{u,v\} |S| \cdot \frac{k}{|S| + 1} \]

\[ \frac{1}{2} \left| \frac{(1 - w(v))(1 - w(u))}{w(v)K_2 + (1 - w(v))K_1} - \frac{(1 - w(u))}{w(u)K_2 + (1 - w(u))K_1} \right|, \]

\[ \frac{1}{2} \left( \frac{w(v)K_2 + (1 - w(v))K_1}{w(v)K_2 + (1 - w(v))K_1} \right) \cdot \frac{w(v) - w(u)}{w(v)K_2 + (1 - w(v))K_1}. \]

We wish to upper bound this by \( \eta_2 |w(v) - w(u)| \). Equivalently, we wish to lower bound its reciprocal is lower bounded. Taking the reciprocal and simplifying yield:

\[ \frac{w(v)K_2 + (1 - w(v))K_1}{w(v)K_2 + (1 - w(v))K_1} \cdot \frac{w(v) - w(u)}{\kappa_1} = \frac{(w(v)K_2 + (1 - w(v))K_1)w(v) - w(u)}{w(v)K_2 + (1 - w(v))K_1}. \]

\[ = \frac{k_2}{k_1} \frac{w(v) - w(u)}{w(v)K_2 + (1 - w(v))K_1}. \]

Notice that \( \max \left( \frac{(w(v)w(u), w(v)(1 - w(v)), (1 - w(u))(1 - w(v)))}{0.25} \right) \). The numerator is lower bounded by 0.25 \( \min \left( \frac{k_2}{k_1}, \frac{k_5}{k_4} \right) \). Thus, the whole expression is \( \geq \frac{1}{4|w(v) - w(u)|} \). Now, it suffices to show that \( \max \left( \frac{k_2}{k_5}, \frac{k_2}{k_1} \right) \) \( \leq \left( 1 + \max \left( \frac{1}{k}, \frac{\sum_{S \subseteq U, u,v \in S, |S| = k-2} (P^U \{u,v\} |S| \cdot \frac{k}{|S| + 1})}{\sum_{S \subseteq U, u,v \in S, |S| = k-1} (P^U \{u,v\} |S| \cdot \frac{k}{|S| + 1})} \right) \) \( \leq 1 + \frac{\sum_{u,v \in S, |S| = k-2} (P^U \{u,v\} |S| \cdot \frac{k}{|S| + 1})}{\sum_{u,v \in S, |S| = k-1} (P^U \{u,v\} |S| \cdot \frac{k}{|S| + 1})}. \)

Observe that

\[ k_2 = \sum_{u,v \in S, |S| = k-2} (P^U \{u,v\} |S| \cdot \frac{k}{|S| + 1}) \]

\[ = \sum_{u,v \in S, |S| = k-2} (P^U \{u,v\} |S| \cdot \frac{k}{|S| + 1}) + \sum_{u,v \in S, |S| = k-1} (P^U \{u,v\} |S| \cdot \frac{k}{|S| + 1}) \]

\[ \leq \sum_{u,v \in S, |S| = k-2} (P^U \{u,v\} |S| \cdot \frac{k}{|S| + 1}) + \sum_{u,v \in S, |S| = k-1} (P^U \{u,v\} |S| \cdot \frac{k}{|S| + 1}). \]

Thus,

\[ \frac{k_2}{k_1} \leq 1 + \frac{\sum_{u,v \in S, |S| = k-2} (P^U \{u,v\} |S| \cdot \frac{k}{|S| + 1})}{\sum_{u,v \in S, |S| = k-1} (P^U \{u,v\} |S| \cdot \frac{k}{|S| + 1})} \]

\[ \leq 1 + \frac{\sum_{u,v \in S, |S| = k-2} (P^U \{u,v\} |S| \cdot \frac{k}{|S| + 1})}{\sum_{u,v \in S, |S| = k-1} (P^U \{u,v\} |S| \cdot \frac{k}{|S| + 1})}. \]

Also, observe that

\[ k_1 = \sum_{u,v \in S, |S| = k-1} (P^U \{u,v\} |S| \cdot \frac{k}{|S| + 1}) \]

\[ \leq \frac{k+1}{k} \sum_{u,v \in S, |S| = k-1} (P^U \{u,v\} |S| \cdot \frac{k}{|S| + 2}) \]

\[ \leq \frac{k+1}{k} \sum_{u,v \in S, |S| = k-2} (P^U \{u,v\} |S| \cdot \frac{k}{|S| + 2}). \]

so \( \frac{k_2}{k_1} \leq \frac{k+1}{k} \). This proves the desired result.
Now, we are ready to prove Lemma D.5. To show tail bounds, we use the standard multiplicative Chernoff bound, which we recall here for sake of completeness:

**Theorem D.7.** Let $X = \sum_{i=1}^{n} X_i$, where $X_i = 1$ with probability $p_i$ and $X_i = 0$ with probability $1 - p_i$, and all $X_i$ are independent. Let $\mu = \mathbb{E}[X] = \sum_{i=1}^{n} p_i$. Then the following bounds hold:

1. **Upper tail:** $\Pr[X \geq (1 + \delta)\mu] \leq e^{-\frac{\delta^2 \mu}{2}}$ for all $0 < \delta < 1$.
2. **Lower tail:** $\Pr[X \leq (1 - \delta)\mu] \leq e^{-\frac{\delta^2 \mu}{2}}$ for all $0 < \delta < 1$.

(At $\delta = 1/3$, these bounds become $e^{-\frac{\mu}{3}}$ and $e^{-\frac{\mu}{3}}$.)

We use Theorem D.7 to prove Lemma D.5.

**Proof of Lemma D.5.** The main ingredient of our proof is Proposition D.6. First, we prove some upper bounds on the values $\eta_1$ and $\eta_2$ in Proposition D.6 for the case of $\sum_{v \in U} w(x) \geq 3k/2$.

**Bounding $\eta_1$:** We wish to bound $\eta_1 = (\mathbb{P}[|S| \geq k])^{-1}$. We use Theorem D.7(a) (a Chernoff bound), since $S$ is a sum of independent indicator random variables with weights according to $w(x)$. Here the mean is $\mu = \sum_{v \in U} w(x) \geq 3k/2$, and we take $\delta = 1/3$, to obtain that $\Pr[|S| \leq k] \leq e^{-\frac{2\mu}{9k}} = e^{-\frac{k}{3k}}$. Thus, we know that $\Pr[|S| \geq k] \geq 1 - e^{-\frac{k}{3k}}$, so $\eta_1 \leq \frac{1}{1 - e^{-\frac{k}{3k}}}$. When $k \geq 12$, we can upper bound $\eta_1$ by 1.6, and when $1 \leq k \leq 12$, we can upper bound $\eta_1$ by 13. We define $\alpha_1$ in the theorem statement based on these values.

**Bounding $\eta_2$:** We give an upper bound on $\sum_{u,v \in U, |S| = k-1} p_{U \setminus \{u,v\}}[S]$ in terms of $\sum_{u,v \in S, |S| = k-2} p_{U \setminus \{u,v\}}[S]$. Consider an association between sets of size $k-1$ and sets of size $k-2$, where each set of size $k-1$ is mapped to the $k-1$ subsets of size $k-2$. We consider the probability to be equidistributed between the associated sets of size $k-2$. For a set $|S| = k-1$ and subset $|S'| = k-2$, the associated probability on $S'$ is $p_{U \setminus \{u,v\}}[S'] \frac{1}{k-1} = p_{U \setminus \{u,v\}}[S'] \frac{1}{k-1} \frac{w(x)}{1-w(x)}$, where $x = S \setminus S'$. Let’s assume we perform this process for all $S$ such that $u,v \notin S$ and $|S| = k-1$, and aggregate the probabilities defined above on sets of size $k-2$ across all of the different $S$. Then, for a set $S'$ of size $k-1$ such that $u,v \notin S'$, the probability is $x \notin S'$ to obtain $\sum_{x \notin S', x \neq u,v} p_{U \setminus \{u,v\}}[S'] \frac{1}{k-1} \frac{w(x)}{1-w(x)} = p_{U \setminus \{u,v\}}[S'] \frac{1}{k-1} \sum_{x \notin S', x \neq u,v} \frac{w(x)}{1-w(x)}$. This means that

$$\sum_{u,v \in U, |S| = k-1} p_{U \setminus \{u,v\}}[S] = \sum_{u,v \in S, |S| = k-2} p_{U \setminus \{u,v\}}[S'] \frac{1}{k-1} \sum_{x \notin S', x \neq u,v} \frac{w(x)}{1-w(x)} \geq \sum_{u,v \in S, |S| = k-2} \sum_{x \notin S', x \neq u,v} w(x) \geq \sum_{u,v \in S, |S| = k-2} p_{U \setminus \{u,v\}}[S'] \frac{k}{2(k-1)} \geq 0.5.$$  

Thus, we have that $\sum_{u,v \in S, |S| = k-1} p_{U \setminus \{u,v\}}[S] \leq 2$. Thus, we have that $\eta_2 \leq 12$. We define $\alpha_2$ in the theorem statement based on this value.

Now, there are four components we must prove: (1) the conditioning mechanism is $\alpha_1$-individually fair, (2) the mechanism terminates quickly, (3) the mechanism satisfies $\alpha_2$-Notion 2 and (4) when $\sum_{x \in U} w(x) = 3k/2$, then $\mathbb{P}[p(u) \leq p(v)] \geq |w(u) - w(v)|$ and $0.5(1 - e^{-k/30} - e^{-k/54}) w(u) \leq p(u) \leq \alpha_1 w(u)$.

1. **$\alpha_1$-Individual Fairness:** We apply Proposition D.6 and obtain that the mechanism is $\eta_1$-individually fair. We set $\alpha_1$ to be the bounds on $\eta_1$ given above.

2. **Bounding the number of rounds in expectation:** Let $T$ be the expected number of rounds. In (1), we showed that the probability of success is at least $\Pr[|S| \geq k] \geq 1 - e^{-\frac{k}{3k}}$. Thus, we know that the expected number of rounds, $T = \frac{1}{\Pr[|S| \geq k]} = \eta_1$. We thus know that $T \geq \alpha_1$.

3. **$\alpha_2$-Notion 2:** We apply Proposition D.6 and obtain that the mechanism satisfies $\eta_2$-Notion 2. Using the bounds on $\eta_2$ from above yields the desired result.
Thus, we have that $\sum_{u,v \in S,|S| \geq k} \frac{p(U,\{u,v\})}{|S|+1} \leq \frac{k}{|S|+1}$ and $|p(u) - p(v)| = \frac{|w(u) - w(v)| \sum_{u \in S,|S| \geq k} (P^U\{u\}[S])}{\sum_{u \in S,|S| \geq k} P^U[S]}$.

First, we bound $p(u)$. Observe that $\sum_{u \in S,|S| \geq k} (P^U\{u\}[S]) \leq \sum_{u \in S,|S| \geq k} (P^U[S]) \leq 1$, so $p(u) \leq \eta_1 w(u)$. We now show that when $\sum_{v \in S} w(v) = 3k/2$, it holds that $p(u) \geq 0.5(1 - e^{-k/36} - e^{-k/54})$. We observe that

$$\sum_{u \not\in S,|S| \geq k-1} \frac{p(U\setminus\{u\})[S]}{|S|+1} \geq 0.5 \sum_{u \not\in S,|S| \geq k-1,|S| \leq 2k-1} (P^U\{u\}[S])$$

$$\geq 0.5 \left(1 - \left(\sum_{u \not\in S,|S| \geq k-2} p(U\setminus\{u\})[S]\right) - \left(\sum_{u \not\in S,|S| \geq 2k} p(U\setminus\{u\})[S]\right)\right).$$

Thus, it suffices to lower bound

$$0.5 \left(1 - \left(\sum_{u \not\in S,|S| \leq k-2} p(U\setminus\{u\})[S]\right) - \left(\sum_{u \not\in S,|S| \geq 2k} p(U\setminus\{u\})[S]\right)\right),$$

for which we just need to upper bound $\sum_{u \not\in S,|S| \leq k-2} p(U\setminus\{u\})[S]$ and $\sum_{u \not\in S,|S| \geq 2k} p(U\setminus\{u\})[S]$. Our main tool is Theorem D.7 (a multiplicative Chernoff bound) with $\delta = 1/3$. Here, $\mu = \sum_{x \in U, y \neq u} w(x)$. We use that $k/2 \leq 3k/2 - 1 \leq \mu \leq 3k/2$. We see that

$$\sum_{u \not\in S,|S| \leq k-2} p(U\setminus\{u\})[S] \leq \sum_{u \not\in S,|S| \leq k-2/3} p(U\setminus\{u\})[S] \leq \sum_{u \not\in S,|S| \leq 2\mu/3} p(U\setminus\{u\})[S] \leq e^{-\frac{k}{3}}.$$

Using that $k/2 \leq \mu \leq 3k/2$, we see that

$$\sum_{u \not\in S,|S| \geq 2k} p(U\setminus\{u\})[S] \leq \sum_{u \not\in S,|S| \geq 4\mu/3} p(U\setminus\{u\})[S] \leq e^{-\frac{k}{3}}.$$}

Thus, we have that $p(u) \geq 0.5 \sum_{u \not\in S,|S| \geq k-1} (P^U\{u\}[S] \cdot \frac{k}{|S|+1}) \geq 0.5(1 - e^{-k/36} - e^{-k/54}) w(u)$.

Now, we bound $|p(u) - p(v)|$. We show that when $\sum_{v \in S} w(v) = 3k/2$, it holds that $|p(u) - p(v)| \geq |w(u) - w(v)| 0.5(1 - e^{-k/36} - e^{-k/54})$. We observe that

$$\sum_{u \not\in S,|S| \geq k-1} \frac{p(u,\{u,v\})}{|S|+1} \geq 0.5 \sum_{u \not\in S,|S| \geq k-1,|S| \leq 2k-1} (P^U\{u,v\}[S])$$

$$\geq 0.5 \left(1 - \left(\sum_{u \not\in S,|S| \geq k-2} p(U\setminus\{u,v\})[S]\right) - \left(\sum_{u \not\in S,|S| \geq 2k} p(U\setminus\{u,v\})[S]\right)\right).$$

Thus, it suffices to lower bound

$$0.5 \left(1 - \left(\sum_{u \not\in S,|S| \leq k-2} p(U\setminus\{u,v\})[S]\right) - \left(\sum_{u \not\in S,|S| \geq 2k} p(U\setminus\{u,v\})[S]\right)\right),$$

for which we just need to upper bound $\sum_{u \not\in S,|S| \leq k-2} p(U\setminus\{u,v\})[S]$ and $\sum_{u \not\in S,|S| \geq 2k} p(U\setminus\{u,v\})[S]$. Our main tool is Theorem D.7 (a multiplicative Chernoff bound) with $\delta = 1/3$. Here, $\mu = \sum_{x \in U, y \neq u} w(x)$. We use that $k/2 \leq 3k/2 - 2 \leq \mu \leq 3k/2$. We see that

$$\sum_{u \not\in S,|S| \leq k-2} p(U\setminus\{u,v\})[S] \leq \sum_{u \not\in S,|S| \leq k-4/3} p(U\setminus\{u,v\})[S] \leq \sum_{u \not\in S,|S| \leq 2\mu/3} p(U\setminus\{u,v\})[S] \leq e^{-\frac{k}{3}}.$$}

Using that $k/2 \leq \mu \leq 3k/2$, we see that

$$\sum_{u \not\in S,|S| \geq 2k} p(U\setminus\{u,v\})[S] \leq \sum_{u \not\in S,|S| \geq 4\mu/3} p(U\setminus\{u,v\})[S] \leq e^{-\frac{k}{3}}.$$
Thus, we have that \(|p(u) - p(v)| \geq \|w(u) - w(v)\| \sum_{\mu \in \mathcal{S}, |\mu| \geq k-1} (P^\mu \setminus \{u\}) \cdot \frac{k}{(|\mu| + 1)} \geq 0.5(1 - e^{-k/36} - e^{-k/54})
.

We can bound 0.5(1 - e^{-k/36} - e^{-k/54}). We define \(\alpha_3\) in the theorem statement based on such bounds.

D.4. Proofs for Section 4.2 For convenience, we restate the quality composition mechanism (Mechanism 4.12).

Mechanism D.8 (Restatement of the Quality Compositional Mechanisms). Let \(\beta \leq 1\) be a constant, and suppose that \(\mathcal{D}\) endowed with quality groups \(q_1, \ldots, q_n\) is \(\beta\)-quality-clustered. Suppose also that \(\mathcal{C}\) is quality-symmetric. For each \(1 \leq i \leq n\) and \(1 \leq x_i \leq |q_i|\), let \(A_{i,x_i}\) be a \(\mathcal{D}\)-individually fair mechanism selecting \(x_i\) individuals in \(q_i\). We define the quality compositional mechanism for \(\{A_{i,x_i}\}\) as follows. Let \(\mathcal{X}\) be any distribution over \(n\)-tuples of nonnegative integers \((x_1, \ldots, x_n)\) in \(P(\mathcal{C})\).

1. Draw \((x_1, \ldots, x_n) \sim \mathcal{X}\).
2. Independently run \(A_{i,x_i}\) for each \(1 \leq i \leq n\), and return the union of the outputs of all of these mechanisms.

We prove Lemma 4.13 also restated here:

Lemma D.9 (Restatement of Lemma 4.13). Let \(\beta \leq 0.5\) be a constant, and suppose that \(\mathcal{D}\) endowed with quality groups \(q_1, \ldots, q_n\) is \(\beta\)-quality-clustered. Suppose also that \(\mathcal{C}\) is quality-symmetric, and let \(\mathcal{X}\) be any distribution over \((x_1, \ldots, x_n)\) in \(P(\mathcal{C})\) such that \(|\frac{x_i}{|q_i|} - \frac{x_j}{|q_j|}| \leq (1 - 2\beta)D(i, j)\). If \(A\) is a quality compositional mechanism, then:

1. \(A\) is always individually fair.
2. \(A\) always satisfies 0.5-Notion 1.
3. \(A\) satisfies 0.5-Notion 2 for \(\mathcal{D}\) and \(\delta\mathcal{D}\) if either of the following conditions hold:
   1. (One set) \(|\text{Supp}(\mathcal{X})| = 1\) (i.e. one “canonical” \((x_1, \ldots, x_n)\)), or
   2. (0-1 metric) \(D(i, j) = 1\) for \(1 \leq i \neq j \leq n\) and \(\mathcal{D}(u, v) = 0\) for \(1 \leq i \leq n\).

Proof. First, we handle a single quality profile vector. Then, we show (1) and (2). Lastly, we show (3).

Handling a single quality profile vector. For \((x_1, \ldots, x_n) \in \text{Supp}(\mathcal{X})\), let \(p^{(x_1, \ldots, x_n)}(u)\) be the probability that \(u\) is assigned to a cohort if a quality compositional mechanism is run on the distribution \(\mathcal{X}\) with probability 1 at \((x_1, \ldots, x_n)\). We claim that \(|p^{(x_1, \ldots, x_n)}(u) - p^{(x_1, \ldots, x_n)}(v)| \leq \mathcal{D}(u, v)\). If \(u\) and \(v\) are in the same quality group, then individual fairness follows from the individual fairness of \(M_{i,x_i}\).

Suppose that \(u\) and \(v\) are in different quality groups, say \(q_i\) and \(q_j\). Note that \(\sum_{x \in \mathcal{Q}_i} p^{(x_1, \ldots, x_n)}(x) = x_i\) and \(\sum_{x \in \mathcal{Q}_j} p^{(x_1, \ldots, x_n)}(x) = x_j\). WLOG suppose that \(p^{(x_1, \ldots, x_n)}(u) \geq p^{(x_1, \ldots, x_n)}(i)\). Let \(u'\) be an individual in \(q_i\) and \(v'\) be an individual in \(q_j\) maximally distant from \(u\) and let \(v'\) be an individual in \(q_j\) maximally distant from \(v\). Then, we know that for each \(x \in q_i\), it holds that \(p^{(x_1, \ldots, x_n)}(u) \geq p^{(x_1, \ldots, x_n)}(u')\). Similarly, for each \(x \in q_j\), it holds that \(p(x) \leq p^{(x_1, \ldots, x_n)}(v) + \mathcal{D}(v, u')\).

Thus, we know that \(x_i = \sum_{x \in \mathcal{Q}_i} p^{(x_1, \ldots, x_n)}(x) \geq |q_i| |p^{(x_1, \ldots, x_n)}(u) - \mathcal{D}(u, u')|\). This means that

\[
x_i \geq p^{(x_1, \ldots, x_n)}(u) - \mathcal{D}(u, u'),
\]

and so:

\[
p^{(x_1, \ldots, x_n)}(u) \leq \frac{x_i}{|q_i|} + \mathcal{D}(u, u').
\]

Similarly, note that \(x_j = \sum_{x \in q_j} p^{(x_1, \ldots, x_n)}(x) \leq |q_j| |p(v) + \mathcal{D}(v, v')|\). Thus we have \(\frac{x_j}{|q_j|} \leq p^{(x_1, \ldots, x_n)}(v) + \mathcal{D}(v, v')\), and so:

\[
p^{(x_1, \ldots, x_n)}(v) \geq \frac{x_j}{|q_j|} - \mathcal{D}(v, v').
\]

Putting these facts together, we obtain that:

\[
p^{(x_1, \ldots, x_n)}(u) - p^{(x_1, \ldots, x_n)}(v) \leq \frac{x_i}{|q_i|} + \mathcal{D}(u, u') - \left(\frac{x_j}{|q_j|} - \mathcal{D}(v, v')\right) = \frac{x_i}{|q_i|} - \frac{x_j}{|q_j|} + \mathcal{D}(u, u') + \mathcal{D}(v, v').
\]
We know that \( \frac{x_i}{|W_i|} - \frac{x_j}{|W_j|} \leq (1 - 2\beta) \) since this is given in the theorem statement. Since \( \mathcal{D} \) is \( \beta \)-quality-clustered, we know that \( \mathcal{D}(u, u') \leq \beta D(i, j) \) and \( \mathcal{D}(v, v') \leq \beta D(i, j) \). Thus, the whole expression is bounded by \( \mathcal{D}(u, v) \).

**Showing (1) and (2).** Now to show (1) and (2), we essentially combine this with the fact that the quality compositional mechanism borrows features of RandomizeThenClassify in [6]. Let \( \gamma \) be the probability measure corresponding to \( \mathcal{D}^- \). Pick a pair of individuals \( u \) and \( v \). Let the cluster label of the cluster corresponding to \( (x_1, \ldots, x_n) \in P(\mathcal{C}_i \cup \mathcal{C}_j) \) be \( i((x_1, \ldots, x_n)) \). First, we let \( C = \sum_{(x_1, \ldots, x_n) \in P(\mathcal{C}_i \cup \mathcal{C}_j)} |\gamma((x_1, \ldots, x_n))p^{(x_1, \ldots, x_n)}(u) - \gamma((x_1, \ldots, x_n))p^{(x_1, \ldots, x_n)}(v)| \) and observe that:

\[
C = \sum_{(x_1, \ldots, x_n) \in P(\mathcal{C}_i \cup \mathcal{C}_j)} |\gamma((x_1, \ldots, x_n))p^{(x_1, \ldots, x_n)}(u) - \gamma((x_1, \ldots, x_n))p^{(x_1, \ldots, x_n)}(v)| \\
= \sum_{(x_1, \ldots, x_n) \in P(\mathcal{C}_i \cup \mathcal{C}_j)} \gamma((x_1, \ldots, x_n))|p^{(x_1, \ldots, x_n)}(u) - p^{(x_1, \ldots, x_n)}(v)| \\
\leq \sum_{(x_1, \ldots, x_n) \in P(\mathcal{C}_i \cup \mathcal{C}_j)} \gamma((x_1, \ldots, x_n))\mathcal{D}(u, v) \\
\leq \mathcal{D}(u, v),
\]

We use this to show that

\[
TV(q_{u,v}, q_{v,u}) = 0.5 \sum_{i=1}^{n_{u,v}} |q_{u,v}^2(i) - q_{v,u}^2(i)| \\
= \sum_{(x_1, \ldots, x_n) \in P(\mathcal{C}_i \cup \mathcal{C}_j)} |q_{u,v}(i((x_1, \ldots, x_n))) - q_{v,u}(i((x_1, \ldots, x_n)))| \\
= \sum_{(x_1, \ldots, x_n) \in P(\mathcal{C}_i \cup \mathcal{C}_j)} \gamma((x_1, \ldots, x_n))|p^{(x_1, \ldots, x_n)}(u) - p^{(x_1, \ldots, x_n)}(v)| \\
= C \\
\leq \mathcal{D}(u, v),
\]

proving (2). We similarly see that:

\[
|p(u) - p(v)| = \left| \sum_{(x_1, \ldots, x_n) \in P(\mathcal{C}_i \cup \mathcal{C}_j)} \gamma((x_1, \ldots, x_n))p^{(x_1, \ldots, x_n)}(u) - \gamma((x_1, \ldots, x_n))p^{(x_1, \ldots, x_n)}(v) \right| \\
\leq \sum_{(x_1, \ldots, x_n) \in P(\mathcal{C}_i \cup \mathcal{C}_j)} \gamma((x_1, \ldots, x_n))|p^{(x_1, \ldots, x_n)}(u) - p^{(x_1, \ldots, x_n)}(v)| \\
= C \\
\leq \mathcal{D}(u, v),
\]

thus proving (1).

**Showing (3).** We now show (3). For (3a), pick any pair of individuals \( u \) and \( v \). Observe that the partition corresponding to \( u \) and \( v \) in the mapping has a single cluster. Thus, \( TV(q_{u,v}^1, q_{v,u}^1) = 0.5|p(u) - p(v)| \leq \mathcal{D}(u, v) \), using the individual fairness of a quality compositional mechanism given by (1). For (3b), pick any pair of individuals \( u \) and \( v \). If \( \mathcal{D}(u, v) = 1 \), then there is no condition on \( u \) and \( v \) in 0.5-Notion 2, so it trivially holds. If \( \mathcal{D}(u, v) < 1 \), then we know that \( u \) and \( v \) are in the same quality group (say \( q_i \)) and \( \mathcal{D}(u, v) = 0 \). By (1), we know that the quality compositional mechanism is individually fair so \( p(u) = p(v) \). Consider an arbitrary cluster, say cluster \( j \). Since the mechanisms \( A_{i,xi} \) are individually fair, and since \( \mathcal{C} \) is quality-symmetric, we know that it must true that \( q_{u,v}^2(i) = \frac{\sum_{x_1, \ldots, x_n \in \mathcal{C}_i \cup \mathcal{C}_j} \gamma((x_1, \ldots, x_n)) A(C)}{p(u)} = \frac{\sum_{x_1, \ldots, x_n \in \mathcal{C}_i \cup \mathcal{C}_j} \gamma((x_1, \ldots, x_n)) A(C)}{p(v)} = q_{v,u}^2(j) \).

Thus, \( TV(q_{u,v}^2, q_{v,u}^2) = 0 \) as desired.
PROPOSITION E.1. Suppose that \( f \) is an individually fair post-processing function and \( A \) is an individually fair cohort-selection mechanism.

1. If \( \left\{ S_{u}^{A,f} \right\}_{u \in \mathcal{U}} \) is \( \alpha \)-Lipschitz individually fair w.r.t \( d^{\text{cond,E}} \), then \( \left\{ S_{u}^{A,f} \right\}_{u \in \mathcal{U}} \) is \( (\alpha + 1) \)-Lipschitz individually fair w.r.t \( d^{\text{uncond,E}} \).

2. If \( \left\{ S_{u}^{A,f} \right\}_{u \in \mathcal{U}} \) is \( \alpha \)-Lipschitz individually fair w.r.t \( d^{\text{cond,MMD}} \), then \( \left\{ S_{u}^{A,f} \right\}_{u \in \mathcal{U}} \) is \( (\alpha + 1) \)-Lipschitz individually fair w.r.t \( d^{\text{uncond,MMD}} \).

Proof. First, we prove (1). Since \( \left\{ S_{u}^{A,f} \right\}_{u \in \mathcal{U}} \) is \( \alpha \)-Lipschitz individually fair w.r.t \( d^{\text{cond,E}} \), we know that

\[
\left| \sum_{C \in \mathcal{E}, u \in \mathcal{C}} \frac{A(C)}{p(u)} f(C,u) - \sum_{C \in \mathcal{E}, v \in \mathcal{C}} \frac{A(C)}{p(v)} f(C,v) \right| \leq \alpha \mathcal{D}(u,v)
\]

and

\[
|p(u) - p(v)| \leq \mathcal{D}(u,v).
\]

It suffices to show that

\[
\left| \sum_{C \in \mathcal{E}, u \in \mathcal{C}} A(C) f(C,u) - \sum_{C \in \mathcal{E}, v \in \mathcal{C}} A(C) f(C,v) \right| \leq (\alpha + 1) \mathcal{D}(u,v).
\]

Notice that the first condition is equivalent to

\[
\left| \sum_{C \in \mathcal{E}, u \in \mathcal{C}} \frac{p(v)A(C)}{p(u)p(v)} f(C,u) - \sum_{C \in \mathcal{E}, v \in \mathcal{C}} \frac{A(C)p(u)}{p(u)p(v)} f(C,v) \right| \leq \alpha \mathcal{D}(u,v)
\]

\[
\left| \sum_{C \in \mathcal{E}, u \in \mathcal{C}} p(v)A(C) f(C,u) - \sum_{C \in \mathcal{E}, v \in \mathcal{C}} p(u)A(C) f(C,v) \right| \leq \alpha p(u)p(v) \mathcal{D}(u,v)
\]

\[
\left| \sum_{C \in \mathcal{E}, u \in \mathcal{C}} p(v)A(C) f(C,u) - \sum_{C \in \mathcal{E}, v \in \mathcal{C}} p(v)A(C) f(C,v) + \sum_{C \in \mathcal{E}, v \in \mathcal{C}} p(v)A(C) f(C,v) - \sum_{C \in \mathcal{E}, v \in \mathcal{C}} p(u)A(C) f(C,v) \right| \leq \alpha p(u)p(v) \mathcal{D}(u,v)
\]

In the previous line we added and subtracted the term \( \sum_{C \in \mathcal{E}, v \in \mathcal{C}} p(v)A(C) f(C,v) \). Now, we use the fact that \( |A| - |B| = |A| - | - B| \leq |A + B| \) by the triangle inequality. This implies that

\[
\left| \sum_{C \in \mathcal{E}, u \in \mathcal{C}} p(v)A(C) f(C,u) - \sum_{C \in \mathcal{E}, v \in \mathcal{C}} A(C) f(C,v) \right| - \sum_{C \in \mathcal{E}, v \in \mathcal{C}} p(v)A(C) f(C,v) + \sum_{C \in \mathcal{E}, v \in \mathcal{C}} p(v)A(C) f(C,v) \right| \leq \alpha p(u)p(v) \mathcal{D}(u,v)
\]

\[
p(v) \left| \sum_{C \in \mathcal{E}, u \in \mathcal{C}} A(C) F(C,u) - \sum_{C \in \mathcal{E}, v \in \mathcal{C}} A(C) f(C,v) \right| \leq \alpha p(u)p(v) \mathcal{D}(u,v) + |p(v) - p(u)| \left( \sum_{C \in \mathcal{E}, v \in \mathcal{C}} f(C,v)A(C) \right)
\]

\[
\leq \alpha p(u)p(v) \mathcal{D}(u,v) + p(v) \mathcal{D}(u,v)
\]

\[
\leq \alpha p(u)p(v) \mathcal{D}(u,v) + p(v) \mathcal{D}(u,v)
\]

\[
\leq \alpha p(u)p(v) \mathcal{D}(u,v) + p(v) \mathcal{D}(u,v)
\]

\[
\leq (\alpha + 1) \mathcal{D}(u,v).
\]
Now, we prove (2). Recall that we have mass-moving guarantees for the conditional case, i.e. that $\text{MMD}(S_u^\alpha, S_v^\alpha) = d'$ for some $d'$. Pick $\epsilon > 0$ and let $d = d' + \epsilon$. By the definition of mass-moving distance, we know that there exist probability measures with finite support $\hat{\nu}_u^\epsilon$ and $\hat{\nu}_v^\epsilon$ over $[0, 1]$ that achieve the value of $d$ in the mass-moving distance definition. The problem that we now need to solve boils down to the devices that carry the extra mass at 0 in the unconditional distributions. We let $\hat{\gamma}_u^\epsilon(x) = p(u) \hat{\nu}_{u}^\epsilon(x)$ for $x \neq 0$ and we let $\hat{\gamma}_u^\epsilon(0) = (1 - p(u)) + p(u) \hat{\nu}_{v}^\epsilon(0)$. We define $\hat{\gamma}_v^\epsilon(x)$ analogously. Now, we use $\hat{\gamma}_u^\epsilon$ and $\hat{\gamma}_v^\epsilon$ to upper bound $\text{MMD}(S_u^{\alpha'}, S_v^{\alpha'})$. First, we see that $\hat{\gamma}_u^\epsilon$ and $\hat{\gamma}_v^\epsilon$ have finite support. For condition (2), we let $Z'_u(i) = Z_u(i)$ for $i \neq 0$. If $p(u) = 1$, we let $Z'_u(0) = Z_u(0)$ and otherwise, we let $Z'_u(0)$ have a mass of $\frac{\hat{\gamma}_u^\epsilon(0)}{1 - p(u) + p(u) S_u^{\alpha'}}$ at 0 and have a mass of $\frac{\hat{\gamma}_u^\epsilon(i)}{1 - p(u) + p(u) S_u^{\alpha'}}$ at $i \neq 0 \in \text{Supp}(\gamma_u^\alpha)$, where $\gamma_u^\alpha$ is the pmf of the distribution $Z_u(0)$. It is straightforward to verify that condition (2) is satisfied.

Thus, we just need to verify condition (1). First, we consider modified measures (not probability measures), where $\hat{\gamma}_u^\epsilon(x) = p(u) \hat{\nu}_u^\epsilon(x)$ for all $x$. We see that the only difference is that there is no extra mass of $1 - p(u)$ on 0 (analogously for $\hat{\nu}_v^\epsilon$). Observe that $\text{TV}(\gamma_u^\epsilon, \gamma_u^\epsilon) \leq \text{TV}(\gamma_u^\epsilon, \gamma_u^\epsilon) + 0.5|1 - p(u) - (1 - p(v))| \leq \text{TV}(\gamma_u^\epsilon, \gamma_u^\epsilon) + 0.5 \mathcal{D}(u, v)$.

We now show that $\text{TV}(\gamma_u^\epsilon, \gamma_u^\epsilon) \leq d + 0.5 \mathcal{D}(u, v)$. We know that

$$0.5 \sum |\gamma_u^\epsilon(s) - \gamma_v^\epsilon(s)| \leq d$$
$$0.5 \sum \frac{|\gamma_u^\epsilon(s) - \gamma_v^\epsilon(s)|}{p(u)} \leq d$$
$$0.5 \sum \frac{|p(v) \gamma_u^\epsilon(s) - p(u) \gamma_v^\epsilon(s)|}{p(u) p(v)} \leq d$$
$$0.5 \sum |p(v) \gamma_u^\epsilon(s) - p(u) \gamma_v^\epsilon(s)| \leq d p(u) p(v)$$
$$0.5 \sum |p(v) \gamma_u^\epsilon(s) - p(v) \gamma_v^\epsilon(s) - p(u) \gamma_v^\epsilon(s)| \leq d p(u) p(v)$$

Now, we use the fact that $|A| - |B| = |A| + |B| - |A + B|$ by the triangle inequality. This implies that

$$0.5 \sum |p(v) \gamma_u^\epsilon(s) - p(v) \gamma_v^\epsilon(s)| - |p(v) \gamma_u^\epsilon(s) - p(u) \gamma_v^\epsilon(s)| \leq d p(u) p(v)$$
$$0.5 \sum (p(v) |\gamma_u^\epsilon(s) - \gamma_v^\epsilon(s)| - p(u) |p(v) - p(u)|) \leq d p(u) p(v)$$
$$0.5 \sum p(v) |\gamma_u^\epsilon(s) - \gamma_v^\epsilon(s)| \leq d p(u) p(v)$$
$$0.5 \mathcal{D}(u, v) \sum |\gamma_u^\epsilon(s) - \gamma_v^\epsilon(s)| \leq d p(u) p(v) + 0.5 \mathcal{D}(u, v) \sum |\gamma_u^\epsilon(s) - \gamma_v^\epsilon(s)|$$

Since $\{S_u^{\alpha'}\}_{u \in U}$ is $\alpha$-Lipschitz individually fair w.r.t $d^{\text{cond-MMD}}$, we know that $d' \leq \alpha \mathcal{D}(u, v)$. Thus, we know that for every $\epsilon > 0$, we can set $v$ equal to $\mathcal{D}(u, v) + (d' + \epsilon)$ and $\mathcal{D}(u, v) \leq (\alpha + 1)(\mathcal{D}(u, v) + \epsilon)$. This gives the desired statement.

Next, we show that mass moving distance is at least as strong as expected score (up to Lipschitz constants).

**Proposition E.2.** Consider distributions $\mathcal{X}_1, \mathcal{X}_2 \in \Delta([0, 1])$. Then, $|E[\mathcal{X}_1] - E[\mathcal{X}_2]| \leq 3 \text{MMD}(\mathcal{X}_1, \mathcal{X}_2)$.

**Proof.** We know that

$$|E[\mathcal{X}_1] - E[\mathcal{X}_2]| \leq |E[\mathcal{X}_1] - E[\mathcal{X}_1]| + |E[\mathcal{X}_1] - E[\mathcal{X}_2]| + |E[\mathcal{X}_2] - E[\mathcal{X}_2]|.$$
Let \( d' = MMD(\mathcal{X}_1, \mathcal{X}_2) \). For \( \epsilon > 0 \), let \( d = d' + \epsilon \). Then, by the definition of mass-moving distance, we know that there exist probability measures (can be viewed as distributions) \( \tilde{\mathcal{X}}_1 \) and \( \tilde{\mathcal{X}}_2 \) that achieve \( d \). By condition (2) in the mass-moving distance definition, we know that \( TV(\tilde{\mathcal{X}}_1, \tilde{\mathcal{X}}_2) \leq d \). This means that the \( \ell_1 \) distance is at most \( 2d \). Since scores are in \([0, 1]\), this implies that \( |E[D_1] - E[D_2]| \leq 2d \). For the first and last terms, we use condition (3) in the definition of mass-moving distance. We see that \( |E[X_i] - E[\tilde{X}_i]| \leq 0.5d \), and this means that \( |E[X_1] - E[X_2]| \leq 3(d' + \epsilon) \). Taking the limit as \( \epsilon \to 0 \), this gives the desired answer. \( \square \)