Mathematics and explanation in astronomy and astrophysics

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March 31, 2022

Abstract

The purpose of this paper is to expound and clarify the mathematics and explanations commonly employed in certain notable areas of astronomy and astrophysics. The first section concentrates upon the mathematics employed to represent and understand stellar structure and evolution. The second section analyses two different explanations for the structure of spiral galaxies.

1 Stellar structure and evolution

A star forms when a body of gas contracts under its own gravitational attraction, and the pressure and temperature created at the centre of the agglomerated mass is sufficient to ignite the nuclear fusion of atomic nuclei. The radiation released as a by-product of the nuclear fusion eventually reaches the surface of the star and becomes starlight.

Newtonian astrophysics represents the gaseous content of a star as a fluid which occupies a compact open subset \( \Omega \subset \mathbb{R}^3 \) of three-dimensional Euclidean space. The fluid is considered to possess a mass density scalar field \( \rho \) and a pressure scalar field \( p \). To study stellar structure in Newtonian astrophysics, it is common to assume that the star is spherically symmetric and static (time-independent). The requirement that the star be static is equivalent to the requirement that the star is in hydrostatic and thermal equilibrium. For a static spherically symmetric star, the fluid occupies a solid ball of radius \( r \), the mass density and pressure are time independent, and the velocity vector of the fluid vanishes. Using spherical polar coordinates, \( (r, \theta, \phi) \), the pressure and the density are independent of the angular coordinates \( (\theta, \phi) \), but vary as a function of the radius \( r \). The fluid is assumed to be self-gravitating and to satisfy the Poisson equation of Newtonian gravitation,

\[
\nabla^2 \Phi = -4\pi G \rho ,
\]

with respect to a gravitational potential scalar field \( \Phi \). \( \nabla^2 \) is the Laplacian, also denoted as \( \Delta \) in many texts.
There are four differential equations which govern the structure of a static, spherically symmetric star. The four equations taken together constitute a coupled (‘simultaneous’) set of ordinary first-order, non-linear differential equations. We now proceed to introduce and discuss these equations.

Assuming spherical symmetry and time-independence, the mass density is a function of radius alone \( \rho(r) \), and from the definition of mass density and Euclidean geometry, it follows that \( m(r) \), the mass enclosed within the surface of radius \( r \), is given by the expression:

\[
m(r) = \int_{0}^{r} 4\pi (r')^2 \rho(r') \, dr'.
\]

(The prime here simply indicates the use of a dummy variable for the integration.) This gives us our first differential equation for stellar structure, sometimes called the mass continuity equation:

\[
\frac{dm(r)}{dr} = 4\pi r^2 \rho(r).
\]

The Newtonian gravitational potential for a self-gravitating, spherically symmetric body satisfying the Poisson equation, is \( \Phi = -\frac{Gm(r)}{r} \). Given a gravitational potential \( \Phi \), the gravitational force exerted per unit mass is specified by the vector field \( -\text{grad} \Phi \), and the gravitational force per unit volume is specified by \( \mathbf{F} = -\rho \, \text{grad} \Phi \). Most texts denote the gradient operator as \( \nabla \), but this can be confused with the covariant derivative operator in differential geometry. Whilst the gradient of a scalar field is a contravariant vector field, the covariant derivative of a scalar field is a covariant vector field. Hence, to avoid confusion, we shall write ‘grad’ rather than \( \nabla \). Given a choice of coordinates \( (x_1, ..., x_n) \) on a manifold, and given a metric tensor field \( g_{ij} \, dx^i \otimes dx^j \) which specifies the geometry of space, the gradient of an arbitrary scalar field \( f \) can be expressed as

\[
\text{grad} f = g^{ij} \frac{\partial f}{\partial x_i} \frac{\partial}{\partial x_j},
\]

where \( g^{ij} \) is the inverse of the matrix \( g_{ij} \). In the spherical polar coordinates we have chosen, \( (x_1, x_2, x_3) = (r, \theta, \phi) \), the flat Euclidean metric takes the form

\[
ds^2 = dr \otimes dr + r^2 d\theta \otimes d\theta + r^2 \sin^2 \theta d\phi \otimes d\phi,
\]

hence the gradient of \( f \) takes the form

\[
\text{grad} f = \frac{\partial f}{\partial r} \frac{\partial}{\partial r} + r^2 \frac{\partial f}{\partial \theta} \frac{\partial}{\partial \theta} + r^2 \sin^2 \theta \frac{\partial f}{\partial \phi} \frac{\partial}{\partial \phi}.
\]

Assuming spherical symmetry of the gravitational potential \( \Phi \) entails that \( \partial \Phi / \partial \theta \) and \( \partial \Phi / \partial \phi \) vanish, hence
\[
\text{grad } \Phi = \frac{d\Phi}{dr} \frac{\partial}{\partial r} = \frac{d(-Gm(r)r^{-1})}{dr} \frac{\partial}{\partial r} = Gm(r)r^{-2} \frac{\partial}{\partial r}.
\]

The requirement of hydrostatic equilibrium corresponds to the requirement that the inward gravitational force \(-\rho \text{grad } \Phi\) is balanced at each point by the outward pressure gradient force \(-\text{grad } p\):

\[
\text{grad } p + \rho \text{grad } \Phi = 0.
\]

Spherical symmetry entails that \(\partial p/\partial \theta\) and \(\partial p/\partial \phi\) vanish, hence

\[
\text{grad } p = \frac{dp}{dr} \frac{\partial}{\partial r} = -Gm(r)\rho(r)r^{-2} \frac{\partial}{\partial r}.
\]

This gives us our second differential equation for stellar structure:

\[
\frac{dP(r)}{dr} = -\frac{Gm(r)\rho(r)}{r^2}.
\]

Let \(l(r)\) denote the amount of energy passing through the surface of radius \(r\) per unit time. Let \(\epsilon(r)\) denote the energy production coefficient, the amount of energy released at radius \(r\) in the star per unit time and per unit mass. It follows that \(4\pi r^2 \rho(r)\epsilon(r)\) is the energy released per unit time at radius \(r\). A star in thermal equilibrium is an open system for which there are large energy flows out of the system, and in which there are significant temperature and pressure gradients, but in which, nevertheless, the temperature and pressure profile of the star remain constant. For a star in thermal equilibrium, none of the energy released is used to heat up the star or change its volume. Hence, for such a star, the rate of energy flow at radius \(r\) is given by the expression:

\[
l(r) = \int_0^r 4\pi (r')^2 \rho(r')\epsilon(r')dr'.
\]

This gives us our third differential equation of stellar structure,

\[
\frac{dl(r)}{dr} = 4\pi r^2 \rho(r)\epsilon(r).
\]

For a star of radius \(R\) the luminosity is defined to be \(L = l(R)\), the amount of energy passing through the outer surface of the star per unit time. When a star resides in a state of thermal equilibrium, the total amount of energy produced by the star per unit time equals the amount of energy radiated from the outer surface per unit time. Hence, the luminosity \(L\) of such a star is given by the equation:

\[1\text{The pressure at each radius is a sum of the gas pressure and the radiation pressure.}\]
\[ L = \int_0^R 4\pi r^2 \rho(r) \kappa(r) dr . \]

The energy per unit time \( l(r) \) passing through the sphere of radius \( r \) can be expressed as

\[ l(r) = 4\pi r^2 F(r) , \]

where \( F \) is the energy flux, the energy flow per unit time per unit area. When there is a temperature gradient in a body, energy flow will occur by conduction and radiation at the very least. Assuming, for simplicity, the absence of convection, the energy flux in a star can be broken down into a conductive energy flux \( F_{\text{cond}}(r) \) and a radiative flux \( F_{\text{rad}}(r) \). In both cases, the energy flow is proportional to the temperature gradient as follows (Tayler 1994, p63):

\[ F_{\text{cond}}(r) = -\frac{4acT^3(r)}{3r^3\kappa_{\text{cond}}(r)\rho(r)} \frac{dT(r)}{dr} , \]

and

\[ F_{\text{rad}}(r) = -\frac{4acT^3(r)}{3r^3\kappa_{\text{rad}}(r)\rho(r)} \frac{dT(r)}{dr} . \]

\( \kappa_{\text{cond}} \), the coefficient of conductive opacity, measures the resistance to the flow of heat by conduction, and \( \kappa_{\text{rad}} \), the coefficient of radiative opacity, measures the resistance to the flow of heat by radiation. \( a \) is the radiation density constant, \( a = 7.57 \times 10^{-15} \text{ erg cm}^{-3} \text{K}^{-4} \).

Assuming that energy flow in a star is due to conduction and radiation\(^2\), one obtains (Tayler 1994, p64):

\[ l(r) = 4\pi r^2 (F_{\text{cond}}(r) + F_{\text{rad}}(r)) = -\frac{16\pi acr^2T^3(r)}{3\kappa(r)\rho(r)} \frac{dT(r)}{dr} , \]

where

\[ \frac{1}{\kappa(r)} = \frac{1}{\kappa_{\text{cond}}(r)} + \frac{1}{\kappa_{\text{rad}}(r)} . \]

Re-arranging, one obtains the following differential equation for the temperature gradient in a star, which is the fourth equation governing stellar structure:

\[ \frac{dT(r)}{dr} = -\frac{3\kappa(r)\rho(r) l(r)}{4acT^3(r) 4\pi r^2} . \]

The chemical composition of a spherically symmetric and static star can be specified by a set of functions \( X_i(r) \), which specify the fraction of unit mass consisting of nuclei of type \( i \), for \( i = 1, ..., I \). As such, \( \Sigma_i X_i(r) = 1 \)\(^3\).

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\(^1\)Conduction is only significant in ‘compact’ stars, i.e., white dwarf and neutron stars.

\(^2\)It is a common approximation to use only three fractions (\( X, Y, Z \)), which are such that \( X + Y + Z = 1 \), and which specify, respectively, the proportion of hydrogen, the proportion of helium, and the proportion of all other elements in the constitution of a star.
Before the equations of stellar structure can be solved, one must specify an equation of state for the pressure,

\[ P = P(\rho, T, X_1, ..., X_I), \]

an expression for the energy production coefficient

\[ \epsilon = \epsilon(\rho, T, X_1, ..., X_I), \]

and an expression for the opacity

\[ \kappa = \kappa(\rho, T, X_1, ..., X_I). \]

These expressions are sometimes called the constitutive equations.

If these three functions are specified, and four boundary conditions are specified, then one can solve the four differential equations of stellar structure. The four boundary conditions can be chosen to be:

\[ m = 0, \quad l = 0 \quad \text{at} \quad r = 0, \]

and

\[ \rho = 0, \quad T = 0 \quad \text{at} \quad r = R. \]

Note here that the star is idealised as an open solid ball of radius \( R \), hence the boundary of the star at radius \( R \) is not itself considered to be part of the star. Choosing \( \rho = 0 \) (or \( P = 0 \)) and \( T = 0 \) at a finite radius \( r = R \) is merely a simple idealisation. In reality, the density, pressure and temperature of a star gradually descend to the non-zero value of the interstellar medium in the neighbourhood of the star.

Solving the four differential equations for stellar structure then gives the mass, pressure, energy flow and temperature as a function of radius. However, in practical terms, one might wish to specify the total mass \( M \) and chemical composition of a star, and then obtain, amongst other things, the radius of such a star in hydrostatic and thermal equilibrium. It is therefore conventional to re-cast the differential equations with mass \( m \), rather than radius \( r \), as the independent variable. Doing so, one obtains (Tayler 1994, p70-71):

\[
\frac{dr(m)}{dm} = \frac{1}{4\pi r^2(m)\rho(m)},
\]

\[
\frac{dP(m)}{dm} = -\frac{Gm}{4\pi r^4(m)},
\]

\[
\frac{dl(m)}{dm} = \epsilon(m),
\]

\[
\frac{dT(m)}{dm} = -\frac{3\kappa(m)l(m)}{64\pi^2acr^4(m)T^3(m)}.
\]
The chemical composition of the star is then expressed in terms of functions \( \{ X_i(m) : i = 1, \ldots, I \} \).

One can then choose boundary conditions for the re-formulated equations of stellar structure, such as:

\[
\begin{align*}
  r &= 0, \quad l = 0 \quad \text{at} \quad m = 0, \\
  \rho &= 0, \quad T = 0 \quad \text{at} \quad m = M.
\end{align*}
\]

Again, one could choose \( P = 0 \) at \( m = M \) rather than \( \rho = 0 \), and, again, this is merely the simplest idealisation on offer.

Now consider the relationship between theory and observation. The observational state of a star at a moment in time can be specified by just two parameters: its luminosity and ‘surface’ temperature. Let us take these in turn:

1. If one calculates the distance to an observable star, say by parallax, then one can infer the luminosity of the star from its apparent luminosity.

2. Whilst the temperature of the surface of a star was idealised in the boundary conditions above to be zero, a more sophisticated model divides a star into its interior and atmosphere. The lowest level of the atmosphere is called the photosphere, and the ‘surface’ temperature of a star is deemed to be the temperature of the photosphere. The temperature of a star’s surface, in this sense, is intimately related to the spectral type of the star, defined by the absorption lines in the spectrum of light emitted by the photosphere. Given that the temperature of a star’s photosphere largely determines the type of its spectrum, the observational state of a star can be specified by its luminosity and spectral type. There are ten spectral types which, in order of decreasing temperature, are referred to as O, B, A, F, G, K, M, R, N, and S.

If one knows both the luminosity and temperature of a star, then one can calculate the radius of the star. The luminosity of a star is a function of the radius \( R \) of the star and the effective\(^4\) surface temperature \( T_e \) of the star, according to the following expression,

\[
L = 4\pi R^2 \sigma T_e^4,
\]

where \( \sigma \) is the Stefan-Boltzmann constant, related to the radiation density constant \( a \) by \( \sigma = ac/4 \). Given \( L \) and \( T_e \), one can obviously use this expression to calculate \( R \).

The observational state of a star can be represented by a point on the Hertzsprung-Russell diagram, a two-dimensional rectangle, coordinatized by luminosity on the vertical axis, and either spectral type or temperature on the

\(^4\)Strictly, the effective surface temperature \( T_e \) is defined as the temperature of a black body with the same radius and luminosity as the star.
horizontal axis. The observational history of a star traces out a path on the Hertzsprung-Russell diagram.

The luminosity and temperature of a star in hydrostatic and thermal equilibrium are the observational properties which can be explained by solving the differential equations of stellar structure. This explanation falls under the aegis of the deductive-nomological (D-N) account of scientific explanation. In such explanations, one explains certain phenomenal facts by logically deriving them from the conjunction of general laws and particular specified circumstances. In this case, the mass and chemical composition of a star are the specified circumstances, and given a specification of the constitutive equations, one can explain the luminosity and temperature of a star from the conjunction of the equations of stellar structure and the given mass and chemical composition.

The initial mass and chemical composition of different stars vary, and these are the characteristics which determine the history and lifetime of a star on the Hertzsprung-Russell diagram. Stars which are burning hydrogen into helium, in a state of hydrostatic and thermal equilibrium, occupy a roughly diagonal channel, running from the top left to the bottom right of the Hertzsprung-Russell diagram, called the main sequence. The initial mass, and to a lesser extent, the initial chemical composition of a star, determine its initial location in the main sequence. Stars with greater initial mass are more luminous, and occupy positions further up the main sequence slope. The larger the mass and luminosity of a star, the shorter the length of time it will spend on the main sequence until its hydrogen fuel is expended.

The Vogt-Russell ‘theorem’, conjectured independently by Heinrich Vogt (1926) and Henry Norris Russell (Russell et al 1927, p910), states that with the total mass and chemical composition specified, the equations of stellar structure admit a unique solution. If true, the Vogt-Russell theorem would entail that each mass and chemical composition corresponds to a unique equilibrium configuration. This, of course, is consistent with the fact that stars of the same mass but different chemical profile, can possess different equilibrium states. The chemical composition of a star will change during its lifetime as nuclear fusion converts lighter elements into heavier elements, and a star will tend to pass through a sequence of different equilibrium configurations.

However, whilst the Vogt-Russell theorem is essentially true, it is not strictly true, and it is certainly no theorem. A system of four coupled, non-linear, ordinary differential equations, with boundary conditions specified at two different points, does not necessarily admit a unique solution. Whilst there is usually a unique equilibrium configuration for a given mass and chemical composition, for some combinations of mass and chemical composition there are multiple solutions to the equations of stellar structure. The notion that there was actually a ‘theorem’ was promulgated in textbooks, and never given a rigorous proof. As a conjecture, it is now known to be false. In fact, both the existence and uniqueness parts of the conjecture fail. For example, there is no solution composed of helium with a mass less than about 0.3 solar masses, and Cox and Salpeter (1964) demonstrated that there are two different solutions for stars of the same mass, burning purely helium, close to this minimum mass. This is referred to
as the double-valued helium main sequence, in the sense that, for some range of masses, two values of radius \( R \) are possible for each value of mass. Kähler (1978) tracked the post main sequence evolution of the helium core of a star of two solar masses, and found different equilibrium configurations of different radius, but with the same mass. Gabriel and Noels-Grötsch (1968) demonstrated that the minimum mass of a solution composed entirely of carbon is about 0.9 solar masses, and that, once again, there are two possible solutions for each mass value greater than the minimum mass. In one branch of such double-valued main sequences, the radius and luminosity increase with increasing mass, whilst in the other branch, there are smaller radii, and the luminosity decreases with increasing mass (Hansen 1978, p23). The latter, anomalous branches, correspond physically to the presence of electron degeneracy. It is therefore not strictly true to say that the mass and chemical composition of a star in equilibrium uniquely determine its structure. However, as Hansen et al point out, “the idea of uniqueness is still useful in that among a set of models all having the same mass and run of composition, usually only one seems to correspond to a real star or to have come from some realistic line of stellar evolution. The others are unstable in some fundamental way (as far as we know),” (2004, p331).

Given a fixed mass and chemical composition, each solution to the differential equations of stellar structure corresponds to a pair of values \((P_c, T_c) = (P(0), T(0))\) for the central pressure and temperature of the star, or, equivalently, to a pair of values \((R, L) = (r(M), L(M))\) for the surface radius and luminosity. The significance of this is that the radius \( R \) and luminosity \( L \) of a star are both inferable from observation. If the mass and chemical composition determined a unique solution, then the mass and chemical composition of a star in equilibrium would uniquely determine its radius and luminosity \((R, L)\). If, on the contrary, there is no unique solution for a particular combination of mass and chemical composition, then there are multiple corresponding pairs \(\{(R, L)_i : i = 1, ..., n\}\).

If one drops the requirements of hydrostatic and thermal equilibrium, then one can obtain the equations of stellar structure and evolution which govern the history of a Newtonian star. Assuming spherical symmetry, the equations are (Kippenhahn and Weigert 1990, p64):

\[
\frac{\partial r(m, t)}{\partial m} = \frac{1}{4\pi r^2(m, t)\rho(m, t)},
\]

\[
\frac{\partial P(m, t)}{\partial m} = -\frac{Gm}{4\pi r^4(m, t)} - \frac{1}{4\pi r^2(m, t)} \frac{\partial^2 r(m, t)}{\partial t^2},
\]

\[
\frac{\partial l(m, t)}{\partial m} = \epsilon(m) - c_P \frac{\partial T(m, t)}{\partial t} + \frac{\delta(m, t)}{\rho(m, t)} \frac{\partial P(m, t)}{\partial t},
\]

\[
\frac{\partial T(m, t)}{\partial m} = -\frac{3\kappa(m, t)l(m, t)}{64\pi^2 a c r^4(m, t)T^3(m, t)}.
\]

Notice that these are partial differential equations, whilst the equations of stellar structure are ordinary differential equations. \(c_P\) is the specific heat at constant
pressure and \( \delta \equiv -(\partial \ln \rho/\partial \ln T)_P \), (see Kippenhahn and Weigert, p19). The fourth equation here continues to assume that energy transport is due to radiation and conduction alone, but this equation can be generalized.

Time-dependence requires one to introduce additional equations for the time-dependence of the mass fractions \( X_i \):

\[
\frac{\partial X_i(m, t)}{\partial t} = \frac{m_i}{\rho(m, t)} \left( \Sigma_j r_{ji} - \Sigma_k r_{ik} \right), \quad i = 1, ..., I.
\]

\( m_i \) is the mass of the nuclei of type \( i \), and \( r_{ij} \) is the rate at which nuclei of type \( i \) are transformed into nuclei of type \( j \) per unit volume.

Solving these equations of stellar structure and evolution requires the specification of initial conditions as well as boundary conditions.

The histories of different star types can intersect when plotted as paths on the Hertzsprung-Russell diagram. For example, after a star of around one solar mass has expended all the hydrogen in its core, it leaves the main sequence, increasing in radius and decreasing in temperature, to the effect of a net increase in luminosity. This evolutionary path takes the star up the Hertzsprung-Russell diagram to become a red giant. It then subsequently increases in temperature, crossing the main sequence itself from right to left, before it sheds its outer layers in the form of a so-called planetary nebula. Where this path crosses the main sequence, the mass of the star is considerably below the mass of stars at that point on the main sequence. If two different types of star can occupy the same point on the Hertzsprung-Russell diagram, it entails that knowledge of the luminosity and temperature of a star alone is not sufficient to determine the unique evolutionary history of a star. The Hertzsprung-Russell diagram does not provide a state space for stars in the sense of a state space (‘phase space’) in Hamiltonian mechanics.

Nuclear fusion inside stars is responsible for creating almost all of the atoms in our universe which are heavier than hydrogen or helium. These heavier elements are generically called ‘metals’ by astrophysicists. During their lifetime, and particularly at the end of their lifetime, stars will eject a proportion of their mass into the interstellar medium, and this mass will contain, in some proportion, the metallic elements created by fusion. The mass returned into the interstellar medium is re-cycled in the formation of subsequent generations of stars.

The stars in our galaxy are classified, in a coarse-grained fashion, as either Population I or Population II. The Population II stars were the first generation of stars formed in our galaxy, and as such, are metal-poor stars. Population I stars were formed from an interstellar medium which already contained the metallic elements created by the first generation of stars, hence the Population I stars have a greater proportion of metallic elements in their chemical constitution.
2 Galaxies

A galaxy is a collection of $\sim 10^{11}$ stars, which is gravitationally bound together, and which is $\sim 10^5$ light years in diameter. Stars within a galaxy are separated by distances of $\sim 10$ light years, (Rindler 2001, p350). There are two main types of galaxy: spiral and elliptical. Most of the stars in a spiral galaxy are concentrated in a flattened disk, which rotates about its center. The rotation, however, is not rigid, and the angular velocity of the rotation decreases as a function of radius. The average rotation period in a spiral galaxy is about 100 million years, (ibid.). The disk of a spiral galaxy is surrounded by a more diffuse ‘halo’ of stars, distributed in a spherically symmetric fashion. The halo is populated only by Population II stars. Whilst successive generations of stars form throughout most of the disk in a spiral galaxy, there is typically a bulge at the center of the disk, and this bulge also tends to contain Population II stars. At the very center of the disk there is typically a supermassive black hole. A spiral galaxy possesses an interstellar medium which consists of gas and dust.\footnote{In relativistic cosmology, ‘dust’ means a pressure-less fluid. In astronomy and astrophysics, however, dust means tiny grains of solid matter (Nicolson 1999, p157).}

The stars in the disk of a spiral galaxy are not actually distributed in spiral
patterns. Rather, the spirals trace the brightest regions in the disk of the galaxy. The brightest regions are those which contain both the O- and B-type stars and the HII regions of ionized hydrogen, created by the ultraviolet radiation from those high-temperature O and B-type stars. Because the brightest (high mass) stars are also the stars with the shortest lifetimes, the bright high-mass stars can only be found in regions of recent star formation, and these regions happen to be the spiral arms.

In an elliptical galaxy, the stars are uniformly distributed within a 3-dimensional ellipsoid, and there is no overall rotation. In fact, the velocities of the stars in an elliptical galaxy are randomly distributed in all directions. Much like the halo of a spiral galaxy, there appears to be only one generation of star formation in an elliptical galaxy.

Our own galaxy, the Milky Way, is a so-called barred-spiral, in which the spiral arms emanate from the ends of an apparently rigid bar of luminous matter, (Nicolson 1999, p206). There appear to be two main spiral arms in the Milky Way: the Norma arm and the Sagittarius arm. In addition, there are a number of smaller arms, and the Sun can be found within the Orion arm or ‘spur’, which lies outside the Sagittarius arm, and inside the Perseus arm (Nicolson p202). The Sun resides inside a ‘bubble’ three-hundred light years in diameter, in which the interstellar medium has been cleared by a supernova explosion (Smolin 1997, p124). From this perspective, of the $10^{11}$ stars in our galaxy, only about 7000 can be seen with the naked eye, (Rindler p350). Moreover, only 1% of the light which falls upon the Earth comes from beyond our galaxy, (Disney 2000, p4).

The mutual gravitation of the stars in a galaxy define an escape velocity, and, at any one time, most of the stars in a galaxy will be moving with a velocity less than the escape velocity. In this sense alone, a galaxy cannot be treated as a collection of isolated, independent entities. Rather, a galaxy must be represented as a system, in the sense that it constitutes a collection of mutually interacting parts. In a spiral galaxy in particular, one can treat the stars as the members of a population, and the interstellar medium as the environment with which that population interacts, via feedback loops. In this sense, it has been suggested that a spiral galaxy can be treated as an ecological system, (Smolin 1997, Chapter 9). Perhaps, however, it would be more accurate to say that biological ecosystems and spiral galaxies are both instances of the same type of formal system. In other words, there is a type of formal system which contains a population, an environment, and a set of feedback loops between the population and the environment, and spiral galaxies provide instances of this system-type just as much as biological ecosystems do.

Smolin asserts that “There are processes by which the matter of the interstellar medium is converted into stars and there are processes by which matter is returned from the stars to the interstellar medium. To understand what a galaxy is, and especially to understand it as a system, is then primarily to understand the processes that govern the flow of matter and energy between the stars and the interstellar medium,” (1997 p118). He points out (p124) that the interstellar medium is a system far from thermodynamic equilibrium, consisting of a number of different components of different densities, temperatures, and
compositions. The different components include normal atomic gas; cold, dense Giant Molecular Clouds (GMCs); and regions of hot, dilute plasma, otherwise known as HII regions, denoting ionized hydrogen. The relative amount of matter in these different components remains approximately constant over time. Smolin asserts that for a system to be in such a stable, but far-from-equilibrium state, there must be processes which cycle the material among the different components, and the rates of these processes must be controlled by feedback mechanisms.

The arms of a spiral galaxy trail behind with respect to the direction of galactic rotation, hence the obvious explanation for their shape is simply the fact that the angular rotation velocity decreases with radial distance from the centre of a galaxy. However, at the very least, this differential rotation cannot be the sole explanation because spiral galaxies have existed for at least 10 billion years, and given a typical rotation period of 100 million years, this means that a typical spiral galaxy has completed at least 100 rotations, and “would long ago have wrapped its arms to extinction if they had been created early in its history and had not been sustained by some ongoing process,” (Nicolson 1999, p208). Observations also suggest that the spiral arms do not rotate with the galaxy, but at a slightly slower rate. Note carefully, however, that an explanation which uses differential rotation in part is not excluded; it may still be possible to explain the spiral arms by invoking differential rotation and an ongoing process which continually creates the arms. What cannot be done is to explain spiral arms simply in terms of differential rotation acting upon the initial conditions under which galaxies are created. The burden of explanation has been shifted from the initial conditions under which a spiral galaxy is created to the ongoing processes which continually operate within such a galaxy.

There are two processes which have been suggested to explain the ongoing formation of spiral arms: density-waves and self-propagating star formation. As Nicolson (p208) points out, both processes may participate in spiral arm formation, and may be of differing importance in different types of spiral galaxy. There are so-called ‘grand-design’ spirals, which possess thin, long and well-defined spiral arms (see Figure 2); there are flocculent spirals, which possess many fluffy, poorly-defined spiral arms (see Figure 3); and there is a continuum of intermediate cases, of which the Milky Way is one such. Karttunen et al point out that “in multiarmed galaxies the spiral arms may be short-lived, constantly forming and disappearing, but extensive, regular, two-armed patterns have to be more long-lived,” (2003 p359). As Nicolson suggests, density-wave mechanisms are more appropriate for grand-design spirals, and self-propagating star formation is more appropriate for flocculent spirals.

It was Bertil Lindblad who suggested in the 1920s that spiral arms could be produced by density waves propagating in a galaxy. The peaks and troughs of a density wave are independent of any particular elements from the medium through which the density wave is propagating. Thus, the density-wave explanation accepts that stars pass in and out of the spiral arms. However, it also accepts that spiral arms are genuine indicators of higher-than-average stellar density. The postulated density wave travels faster than the speed of sound in
the interstellar medium, and the shock wave purportedly triggers compression of the interstellar medium, and the observed star formation in the spiral arms. The spiral arms therefore trace the brightest regions in the disk of a galaxy because the brightest regions are those which contain the shortlived O- and B-type stars. As Tayler states, “the most massive stars have such a short lifetime that, by the time they have ceased to be luminous, the spiral pattern has hardly changed its position. They should therefore only be found in the spiral regions...Stars of lower mass, such as the Sun, have a main sequence lifetime which is equal to many rotation periods of the pattern. Such stars should therefore be observed throughout the disk with no significant correlation with the present position of the spiral arms,” (1993, p145).

C.C. Lin and Frank Shu developed the density-wave idea further in 1964 by postulating that the stars in a spiral galaxy travel in slightly elliptical orbits which precess with the passage of time. This postulate was complemented by the suggestion of J. Kalnajs in 1973 that if the orientation of the major axis of these ellipses varies by a small angular increment at increasing distance from the galactic centre, then the ellipses fail to be uniformly separated, and where

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See Pasha (2004) for a detailed history of these ideas.
they come close together, they produce the appearance of grand-design spiral arms.

Kalnaj's explanation of spiral arms can be seen as a structural explanation, in the sense that the spiral arms are represented as structural elements in a geometrical model, and these structural elements are linked to other structural elements in the model, namely the precessing elliptical orbits, each aligned at a small angle to the one inside it.

Figure 3: Flocculent spiral galaxy NGC4414.

Nicolson suggests that density-wave spiral arms "are probably sustained either by the asymmetric gravitational field associated with a central bar structure (typical of grand-design spirals) or by gravitational disturbances caused by neighboring galaxies, or by a combination of both," (1999, p208).

In the 1970s Mueller and Arnett suggested an alternative explanation for spiral arms, which rejects the idea that all spiral arms are density waves, and postulates instead that at least some are self-propagating waves of star formation. Unlike density waves, these waves purportedly do not require one to postulate external mechanisms, such as the asymmetric gravitational field of the central bar, or the tidal forces caused by other galaxies. Let us, then, examine star formation processes in a little more detail.

As stated in Section 1, the mass and chemical composition of stars vary, and these are the characteristics which determine the history and lifetime of a star. New stars are continually born in a spiral galaxy, but they are not born from other stars, and consequently the mass of a new star is not in any sense inherited. The first generation of stars must have formed from clouds of almost pure hydrogen and helium. Subsequent generations of stars are observed to form from the cold, dense Giant Molecular Clouds of the interstellar medium. Given an environment which already contains surrounding stars, GMCs are only able
to remain cool because they contain dust, which acts as a shield to starlight, and
because they contain organic molecules, which are able to radiate excess heat
(Smolin p110). Organic molecules contain carbon, a by-product of the nuclear
fusion processes in previous generations of stars.

The star-formation processes within GMCs are thought to be triggered by
the shock-waves from the supernovae explosions of nearby high-mass stars,
formed within neighbouring GMCs 10 million years previously, or less. The
shock-waves purportedly compress the interstellar medium, and instigate star
formation. Because one spell of star-formation is triggered by the death of high-
mass stars from a previous spell of star-formation, this process is referred to as
self-propagating star-formation (Smolin p128). Indeed, the inner lanes of spiral
arms are often observed to be dark and dusty, while the outer sides contain the
star-forming regions. This suggests the star formation is directed against the
direction of rotation, which would explain why spiral arms rotate slightly slower
than a host galaxy.

Nicolson (p208) suggests that after a burst of such self-propagating star for-
amation, differential rotation stretches the region into a spiral arm. He suggests
that in a flocculent spiral, random bursts of star formation produce numerous
spiral arms by this mechanism, each of which fades away after star formation has
ceased. Subsequent star formation elsewhere in the galaxy then creates more
spiral arms. This differs somewhat from Smolin’s notion of self-propagating star
formation, in which he states that “the waves of star formation neither die out,
nor grow uncontrollably, but propagate at exactly the right rate to persist in
the galaxy indefinitely,” (1997 p135).

The debate between the two different theories which attempt to explain
spiral structure is particularly interesting when one appreciates that they take
opposite stances on the basic cause and effect relationships which operate in
a spiral galaxy. The density wave theory represents a spiral to be a spiral of
density waves, and explains star formation as the consequence of the density
waves. In contrast, the theory of self-propagating star formation represents
spiral structure to be the consequence of waves of star formation, (Tayler 1993,
p145).

It would not be correct to say that the chemical composition of a new star is
independent of the chemical composition of previous generations of stars. The
chemical composition of the interstellar medium in a spiral galaxy is changing
with the passage of time. The material expelled from one generation of stars
provides a high-metallicity contribution to the medium from which the next
generation of stars is composed. High metallicity purportedly inhibits the for-
mation of higher-mass stars, hence the relative birthrate of lower-mass stars in
a spiral galaxy increases with the passage of time. Accordingly, the birthrate
of stars in the solar neighbourhood is claimed to be inversely proportional to
mass $m$ according to the Salpeter form, $m^{-7/3}$, (Tayler 1993, p149). It is also
suggested that the formation rate of high-mass stars is less than the formation
rate of low-mass stars because the energy from a newly-created high-mass star
heats up the medium from which it was born to such an extent that the star
formation process halts, (Smolin p127). In general statistical terms, the number
density $N_m$ of type-$m$ objects in such a population is the product $N_m = B_m \cdot l_m$ of the type-$m$ birthrate $B_m$ with the type-$m$ life-time $l_m$. If we let $N_m$ denote the number density of mass-$m$ stars, then it follows that because small mass stars have a greater lifetime, even if they have the same birth-rate as high-mass stars, they will come to dominate the population. The eventual domination of lower-mass stars is therefore the consequence of both statistics and the physics of star formation processes. In a spiral galaxy, however, where the birthrates are far from being spatially homogeneous, and the majority of star formation occurs in the spiral arms, one cannot infer birthrates from the known lifetimes of stars and the observed number densities in regions which are remote from the star formation in spiral arms.

The population of stars in a spiral galaxy is therefore a type of population in which: (i) there are variable characteristics distributed within the population, and a small subset of these characteristics define different types within the population; (ii) each member of the population has a finite lifetime, determined by the values of the type-defining characteristics; and (iii) new members of the population are not reproduced from existing members of the population, i.e., new members of the population are born without having any parent(s) in the existing population. Suppose in addition that (iv) population members of each type are created at approximately the same rate, or short-lifetime members are created at a lower rate than long-lifetime members. Such a population evolves to be dominated by the long-lifetime objects. Such a population is neither evolving randomly, nor is it evolving by natural selection.

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