Compressed quantum metrology for the Ising Hamiltonian

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We show how quantum metrology protocols that seek to estimate the parameters of a Hamiltonian that exhibits a quantum phase transition can be efficiently simulated on an exponentially smaller quantum computer. Specifically, by exploiting the fact that the ground state of such a Hamiltonian changes drastically around its phase transition point, we construct a suitable observable from which one can estimate the relevant parameters of the Hamiltonian with Heisenberg scaling precision. We then show how, for the one-dimensional Ising Hamiltonian with transverse magnetic field acting on $N$ spins, such a metrology protocol can be efficiently simulated on an exponentially smaller quantum computer while maintaining the same Heisenberg scaling, i.e., $O(N^{-2})$ precision and derive the explicit circuit that accomplishes the simulation.

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I. INTRODUCTION

Determining the properties and parameters of physical systems is a central problem in many experiments. Quantum metrology deals with the question of how this can be achieved optimally using a given number of resources, counted in terms of number of systems or evolution time [1–4]. It is a key result that quantum mechanics offers a significant advantage for achieving this task. In fact, using entangled probe states one finds that a quadratic gain in precession as compared to any classical strategy can be achieved [2, 3], provided that one can estimate the relevant parameters of the Hamiltonian with Heisenberg scaling precision. We consider the problem of estimating some unknown parameter of a strongly coupled system, e.g., the interaction strength of a 1D chain of $N$ interacting spins. The physics of such strongly coupled systems is widely studied [9]. Recently it was realized that certain classes of such strongly interacting systems can be simulated by an exponentially smaller system in a compressed way, where relevant properties such as quantum phase transitions or two-point correlation functions can be determined efficiently [10–12].

Here we show that one can also perform quantum metrology on such a compressed system. In our approach, we assume that we have access to a family of Hamiltonians describing $N$ interacting spins for different system sizes $N$, and can switch the Hamiltonian on and off at will. We illustrate our approach with the one-dimensional Ising model with transversal magnetic field, where the goal is to determine the unknown coupling strength of the model. We remark that the estimation of the coupling strength does not fall into the widely studied class of problems where the unknown parameter is a multiplicative constant [2–8], but is of a more complicated type where the overall Hamiltonian is some function of the parameter [12]. Nevertheless, this problem has been fully solved in a standard metrology approach [14], where the Hamiltonian is applied to some optimal state which is subsequently measured, and an estimate of the parameter is determined from the measurement statistics.

We provide an alternative approach that is based on estimating a certain observable near the quantum phase transition of the system which is first driven to the ground state, similar as in [15–17]. We use the Hamiltonian to drive the system to its ground state via adiabatic evolution, and determine the unknown parameter from its ground state. We show that one can do this using an exponentially smaller system. While this does not imply a super-Heisenberg scaling when resources are properly counted, it might nevertheless be an interesting experimental alternative. We use that the Ising model—more precisely the measurement of certain observables in this model—can be efficiently simulated with an exponentially smaller number of spins using matchgate circuits, as demonstrated in [10–12]. This is due to the fact that the system can be mapped to non-interacting fermions, thereby reducing the effective dimension of the Hilbert space [18–21]. We show that there exist such an observable that, when estimated at the ground state of the model close to the quantum phase transition, allows one to determine the coupling strength with a precession that is super-classical.

We remark that with the assumed level of control, there are alternative methods to achieve Heisenberg scaling in precision for the estimation of the coupling strength with limited resources. In fact, a simple sequential scheme that operates with only two qubits suffices. This scheme uses standard quantum metrology techniques and imprints the parameter in question as a phase onto a single qubit (see Sec. II A). Nevertheless, our work shows that indirect methods concerned with the fast change of properties near to a quantum phase transition can be used and combined with techniques from compressed quantum computation [10–12, 22, 23]. This approach is not limited to the Ising model, or the estimation of the coupling strength, and might in fact have an advantage over standard metrological protocols when considering problems such as the estimation of two-point correlation functions or other ground state properties that might not be directly accessible by time evolution with respect to the Hamiltonian $H$.

The paper is organized as follows. In Sec. III, we describe the setting and give background information on matchgate circuits, compressed quantum computation and its relation to the Ising Hamiltonian, as well as quantum metrology. In Sec. IV, we show how compressed metrology of the Ising model can be achieved. We first recall...
how to drive the compressed system to the ground state via adiabatic evolution, and then provide a suitable observable that can be measured on the compressed system efficiently such that the coupling strength of the interaction can be determined with super-classical precision. Surprisingly, the magnetization as an obvious candidate fails to provide such a super-classical scaling. We summarize and conclude in Sec. [IV].

II. BACKGROUND

In this section we review the main ingredients utilized throughout this work in order to realize a compressed quantum metrology protocol for the one dimensional Ising Hamiltonian with transverse field. After establishing notation in Sec. [II A] and presenting the general setting considered here (Sec. [II B]), we review key properties of matchgates and matchgate circuits in Sec. [II C]. We then specialize to the application of matchgate circuits for the case of the one-dimensional Ising Hamiltonian with transverse magnetic field in Sec. [II D], where we briefly recall how one can explicitly construct the ground state of such a Hamiltonian using matchgate circuits [11, 11]. Finally, we review key concepts of quantum metrology, and in particular how the phase transition exhibited by the one-dimensional Ising Hamiltonian can be used to enhance estimation precision of its relevant parameters in Sec. [II E].

A. Notation

We denote by $X, Y, Z$ the Pauli matrices, and by $I$ the identity operator. The computational basis states will be denoted by $|k⟩$ for $k ∈ \{0, 1\}^N$. We will consider a spin chain of $N = 2^m$ qubits, for some integer $m$. We will also denote by $|0⟩$ the state of $N$ qubits $|0⟩^N$. Qubits, matrix components, and fermionic operators are counted starting from 0, in order to unify the indexing. Controlled operations are denoted by $A_{i_0,...,i_k}(A_j)$, representing that $A$ is applied on qubit $j$ in the exclusive case where each of the qubits $i_0,...,i_k$ are in the state $|1⟩$.

B. General setting

We consider the situation where one has access to a general interaction, in our case the Ising interaction (see Eq. [8]), for an arbitrary number of qubits. Our aim is to estimate some parameter which defines this interaction, in our case the Ising interaction is $H_{\text{Ising}} \equiv J_1X_1 \otimes X_2$, thereby imprinting the information on $J$ directly onto the phase. The choice $|ψ⟩ = |0⟩_x$ is optimal and leads to Heisenberg scaling in precision, with respect to the total evolution time $T$, i.e., $δJ^2 ≥ (νT)^{-2}$ where $ν$ is the number of repetitions. Note that there is no dependence on the system size, $N$, here as the evolution applies sequentially on the two qubits [20].

However, our scheme is not restricted to the Ising model. It applies to any situation where the parameter of interest can be estimated using a matchgate circuit as long as the required interaction in the compressed model can be realized using the considered Hamiltonian. Moreover, our scheme can also be utilized to cases where the parameter can only be inferred by measuring for instance (staggered) correlation functions something which would be impossible using the scheme described above.

C. Matchgate circuits and compressed quantum simulation

Matchgates are a particular set of two qubit gates satisfying certain algebraic constraints with applications in the theory of perfect matchings of graphs [20, 21], fermionic linear optics [18, 19], as well as one-dimensional
spin chains [10, 12].

A matchgate, \( G(A, B) \), is a two qubit gate of the form

\[
G(A, B) = \begin{bmatrix}
A_{11} & 0 & 0 & A_{12} \\
0 & B_{11} & B_{12} & 0 \\
0 & B_{21} & B_{22} & 0 \\
A_{21} & 0 & 0 & A_{22}
\end{bmatrix},
\]

(1)

where \( A_{ij} \) are the matrix elements of \( A \) (and similarly for \( B \)). The unitary operators \( A \) and \( B \) act only on states belonging to the even and odd parity subspace of two qubits respectively and satisfy the condition \( \det(A) = \det(B) \).

In what follows we will only consider matchgates (or products of them) acting on nearest neighbors. Hence, we call nearest neighbor matchgates in the following simply matchgates.

Any matchgate, or product of matchgates, can be written as

\[
U = e^{-iH},
\]

(2)

where \( H \) is a Hermitian operator that can be written as

\[
H = i \sum_{j \neq k=0}^{2N-1} h_{jk} x_j x_k.
\]

(3)

Here the matrix \( h \) is a \( 2N \times 2N \) real anti-symmetric matrix [22], and we have introduced the set of \( 2N \) Hermitian operators \( \{x_j\}_{j=0,\ldots,2N-1} \) with (Jordan-Wigner representation)

\[
\begin{aligned}
x_{2j} &= \bigotimes_{k=0}^{j-1} Z_k \otimes X_j \bigotimes_{k=j+1}^{N} \mathbb{1}_k, \\
x_{2j+1} &= \bigotimes_{k=0}^{j-1} Z_k \otimes Y_j \bigotimes_{k=j+1}^{N} \mathbb{1}_k.
\end{aligned}
\]

(4)

Note that this set of operators generate the Clifford algebra, \( \mathcal{C}_N \), as they satisfy \( x_j^2 = 1 \) and the anti-commutation relations \( \{x_j, x_k\} = 2\delta_{jk} \forall j, k \). The important property of a matchgate, as given in Eq. (2), is that its action on any of the generators of \( \mathcal{C}_N \) can be shown to give [22]

\[
U^\dagger c_j U = \sum_{k=0}^{2N-1} R_{jk} c_k,
\]

(5)

where the matrix \( R \in SO(2N) \) is given explicitly by

\[
R = e^{Ah}.
\]

(6)

It has been demonstrated that any circuit of matchgates satisfying the constraints: (i) matchgates act only on nearest-neighbours, (ii) the input state of the \( N \) qubits is any computational basis state and, (iii) the output of the circuit is the result of measuring any single qubit in the computational basis, can be simulated classically efficiently [19, 20, 22]. Let us call in the following a circuit fulfilling constraints (i–iii) a matchgate circuit (MGC).

The reason why MGC can be classically simulated efficiently can be easily understood as follows. First, note that any MGC with input state \( |k_1, \ldots, k_N\rangle \) \( (k_i \in \{0, 1\}) \) and \( Z \)-measurement on qubit \( k \) can be mapped to an equivalent MGC with input state \( |0, \ldots, 0\rangle \) and \( Z \)-measurement on the first qubit [23]. Consider a MGC where the initial state, \( |0\rangle \), evolves under the action of a unitary \( U \) given in Eq. (2) followed by a measurement of the observable \( Z_0 = -i x_0 x_1 \) on the final state. Defining the \( 2N \times 2N \) matrix \( S \) with components \( S_{jk} = \langle 0 | (-i x_j x_k) | 0 \rangle \), the outcome of the aforementioned circuit can be written as

\[
\begin{aligned}
\langle Z_0 \rangle &= \langle 0 | U^\dagger (-i x_0 x_1) U | 0 \rangle \\
&= [RSR^\dagger]_{0,1}.
\end{aligned}
\]

(7)

As our MGC consists of a sequence of nearest neighbour matchgates, i.e., \( U = U_m \cdots U_1 \), the \( 2N \times 2N \) matrix \( R \) can be written as \( R_m \cdots R_1 \), where \( R_i \) is associated to \( U_i \) according to Eq. (6). Moreover, \( S = \mathbb{1} \otimes i Y \), where \( \mathbb{1} \) is the \( N \)-dimensional identity. Hence, the matrices as well as their product can be computed efficiently.

In [23] it has been shown that any MGC on \( N \) qubits can be compressed to a universal quantum computation running on \( \log(m) + 3 \) qubits. This simulation is efficient as the size of the compressed computation, i.e., the number of single and two-qubit gates, is \( \mathcal{O}[M \log(N)] \), if \( M \) denotes the size of the MGC. The main idea here is to apply the controlled gate, \( A_1(U) = |0\rangle \langle 0| \otimes [1 + |1\rangle \langle 1|] U \), with \( U = S^{-1}RSR^\dagger \), to the input state \( |+\rangle |0\rangle ^\otimes \log(N) \). Measuring the operator \( X \) on the first system leads to the desired result, \( |0\rangle SRSR^\dagger |1\rangle \). Due to the fact that the required classical side-computation can be performed on log-space, the computation is performed by the exponentially smaller quantum computer.

D. Ising Hamiltonian and matchgates

We now focus our attention on the one-dimensional Ising Hamiltonian with transverse magnetic field, and recall how the ground state of this Hamiltonian for various values of its parameters can be obtained via a product of matchgates acting on \( |0\rangle \) [10, 11, 21, 27].

The one-dimensional Ising Hamiltonian with transverse magnetic field,

\[
H(J, B) = -J \sum_{j=0}^{N-1} X_j X_{j+1} - B \sum_{j=0}^{N-1} Z_j
\]

\( \equiv -JH_1 - BH_0 \)

(8)

describes a one-dimensional chain of spins with nearest-neighbour coupling interaction of strength \( J \), and a global magnetic field \( B \). Here, \( X_N \equiv Z_0 \), with \( Z \equiv \otimes_{j=0}^{N-1} Z_j \), which corresponds to Jordan-Wigner (JW) boundary conditions. Using the JW representation, Eq. (4), and defining the fermionic operators \( c_j \equiv \frac{1}{2} (x_{2j} + ix_{2j+1}) \) satisfying the fermionic commutation relations \( \{c_j, c_k^\dagger\} = \delta_{jk} \), the Hamiltonian of Eq. (8), can be explicitly diagonalized to [27]

\[
H[a] = \sum_{j=0}^{N-1} c_j \left( a_j^\dagger a_j - \frac{1}{2} \right),
\]

(9)
It will be convenient to write the vacuum state, presented above [27] or use an adiabatic evolution, starting of the coupling strength [28]. Clearly the ground state depends on the values latter into the ground state for any value of an adiabatic evolution can indeed be given as a product modes [qubits] as 0 ≤ \( g \) ≤ 1 and odd parity for \( g < 1 \). However, as we will see, the adiabatic evolution is a product of matchgates which by construction preserves the parity. Hence, preparing the system initially in \( |0\rangle \), which has even parity, the adiabatic evolution will always result in a ground state belonging to the even parity subspace.

One way to construct the ground state for a given value of \( g \) is to start with an easily preparable ground state for some value \( g_0 \) and use the adiabatic theorem [29–31] to prepare the ground state for the desired value of \( g \) by slowly varying this parameter form \( g_0 \) to \( g \). For example, the ground state for \( H(B, J = 0) \) is simply \( |0\rangle \), and it has been shown that an adiabatic evolution from \( |0\rangle \) to the ground state \( |G\rangle = |\Psi(B, J)\rangle \) corresponding to a non-zero value of \( J \) can be described in terms of a MGC [11], up to an error due to the Trotter approximation. Furthermore, the resulting MGC can be compressed efficiently, and without additional error, onto a logarithmically smaller quantum computer [10] as we briefly now explain.

Let us now use the notation

\[
H(B, J, t, T) = -B H_0 - J \left( \frac{t}{T} \right) H_1,
\]

(19)

for the Ising Hamiltonian (see Eq. (8)). Here, \( t \) and \( T \) are some real positive coefficients. Note that \( H(B, J, T, T) = H(B, J) \) and \( H(B, J, 0, T) = -B H_0 \) whose ground state is the state \( |0\rangle \). Due to the adiabatic theorem, evolving the state \( |0\rangle \) under the action of the Hamiltonian \( H(B, J, t, T) \), with a parameter \( t \) (interpreted as the time) varying from 0 to \( T \), would yield the ground state \( |\Psi(B, J)\rangle \) of \( H(B, J) \) as long as the ground state energy is non-degenerate and \( T \) is large enough. For this model, a rough condition on the duration \( T \) that guarantees that the total probability of a transition to any excited state is negligible reads \( T \gg N^2 \) (see [32] and references therein). The time evolution operator is given by

\[
\tilde{U}(B, J, T) = T \left[ \exp \left( \int_0^T H(B, J, t, T) \, dt \right) \right],
\]

(20)

where \( T \) is the time ordering operator. It was shown that this unitary can be discretized by a Trotter decomposition into the unitary [27]

\[
U(B, J, T) = \prod_{t=0}^{L} U_0(B) \cdot U_1(J, t),
\]

(21)
where
\[
U_0(B) = e^{iB\Delta(T,L)H_0},
\]
and \(\Delta(T, L) = T/L + 1\). The unitary \(U(B, J, T)\) equals \(\tilde{U}(B, J, T)\) up to an error which scales as \(O[\Delta(T, L)^2]\). Note that these unitaries can be written in the form given in Eq. (2), with a quadratic Hamiltonian of the form given in Eq. (3). The ground state of \(H(B, J)\) (with even parity) is then given by
\[
|\Psi(B, J)\rangle = U(B, J, T)|0\rangle
\] (24)
up to the error aforementioned. Another method to prepare the ground state would be to use the exact diagonalization presented before (see also [12, 27]). As this diagonalization is achieved via matchgates, the ground state can be generated by applying the corresponding unitary to the initial state \(|0\rangle\).

E. Metrology

In this subsection we review the main tools and results of quantum metrology. Here, and throughout, we will adopt the frequentist (local) estimation scenario, where the parameter of interest is known to lie within a very narrow range of parameter values.

In local quantum metrology a sensing system, or systems, is initialized in a known state, \(|\psi\rangle\), and undergoes some dynamical evolution that imprints the parameter \(g\) onto its state. The sensing system is then measured. Repeating this procedure a large number of times allows one to obtain the requisite statistics from the measurement outcomes which are then used to extract an estimate \(\hat{g}\) of the parameter.

For unbiased estimators, the precision in estimation of a local metrology protocol is quantified by the mean squared error, \(\delta g^2 \equiv (\hat{g} - g)^2\). The goal is to minimize this quantity for a fixed number of resources of a given metrology protocol. If the dynamical evolution is “digitalized”, i.e., consists of accessing a fixed dynamical evolution a given number of \(N\) times, then the total resources for the protocol are the total number of calls \(N\). This situation corresponds to the well studied case of phase estimation, where \(g \in [0, 2\pi]\) [2, 3]. Notice that sequential protocols, where \(N\) sequential calls to the evolution are made with a single sensing system, and a parallel protocol, where the \(N\) calls are made in parallel by employing \(N\) probes each of which senses the evolution once, use the same total number of resources.

For “analog” dynamical evolutions, where the “number of calls” is a continuous parameter \(t\) corresponding to the time each sensing system is subjected to the evolution, the total resources of a given metrology protocol are \(T = Nt\), where \(N\) is the number of probes used. This corresponds to the case of frequency estimation, where \(g = \omega\) and \(T\) can be controlled by the experimenter [11]. Observe now that in order for a sequential and parallel strategy to utilize the same amount of resources, the single sensing system has to undergo the dynamical evolution for a time \(T = \sum_{n=1}^{N} \tau(n)\), where \(\tau(n)\) is the time probe system \(n\) undergoes the evolution in the parallel strategy.

In the absence of noise, which will be the assumption throughout this work, the dynamical evolution is given by the unitary operator \(U_g \equiv e^{ixtH}\), for the case of digital (analog) evolution respectively. For local Hamiltonians, \(H = \sum_{i=1}^{N} h^{(i)}\), the use of entanglement allows for a quadratic improvement in precision, \(\delta g^2 = (\nu N^2)^{-1} (\delta \tilde{g}^2) \geq (\nu(N))^{-1} = (\nu T^2)^{-1}\), over the best known classical strategy, \(\delta g^2 = (\nu N^2)^{-1} (\delta g)^2 \geq (\nu(N))^{-1} = (\nu T)^{-1}\) where \(\nu\) denotes the number of repetitions of the experiment. These are known as the Heisenberg and Standard quantum limits respectively. Both limits can also be achieve by a sequential strategy as well.

In order to achieve the aforementioned limits, one must optimize over all possible initial states of the sensing system as well as over all possible measurements. This is done as follows; by the quantum [33, 34] Cramér-Rao inequality [35], the mean squared error is lower bounded by
\[
\delta g^2 \geq \frac{1}{\mathcal{I}[^g\rho(g)]},
\] (25)
where
\[
\mathcal{I}[^g\rho(g)] = \text{tr}[\rho(g)L_g],
\] (26)
is the quantum Fisher information of the state \(\rho(g)\) and \(L_g\) is the operator satisfying \(\frac{\partial \langle \psi | g \rangle}{\partial g} = \frac{1}{\nu} (L_g \rho(g) + \rho(g)L_g)\) known as the symmetric logarithmic derivative. For a given initial state, \(\rho\), the measurement maximizing the quantum Fisher information has the eigenprojectors of \(L_g\) as its measurement operators. Thus, all that remains is to maximize over all possible initial states of the probe. In the noiseless case, it can be shown that the optimal states are of the form \(|\psi\rangle = \frac{1}{\sqrt{\nu}} (|\lambda_{\text{min}}\rangle + |\lambda_{\text{max}}\rangle)\), where \(|\lambda_{\text{max(min)}}\rangle\) are the eigenstates of \(\hat{H}\) corresponding to the maximal (minimal) eigenvalue.

However, the optimal states and corresponding optimal measurement given above do not satisfy the conditions needed for MGC. Indeed, even if the state is a computational basis state, the corresponding optimal measurement, given by the symmetric logarithmic derivative, for the case of the Ising Hamiltonian cannot be compressed. In order for the entire metrology protocol to be a MGC (and hence compressible) we require a suitable Hermitian operator, \(A\) whose expectation value allows us to infer the parameter of interest with Heisenberg limited precision. To that end, we will find it more convenient to compute the mean square error in our estimation in a different way: using standard error-propagation.

The error propagation formulae relates the variance of the operator \(A\) with respect to the state \(|\psi(g)\rangle\), \(\Delta^2 A(g) \equiv \langle \psi(g)|A^2|\psi(g)\rangle - \langle \psi(g)|A|\psi(g)\rangle^2\), to the squared error in the estimation of the parameter, \(\delta g^2\) as (see Appendix A)
\[
\delta g^2 = \frac{\Delta^2 A(g)}{|\partial_t \langle A(g')\rangle |g' = g|^2},
\] (27)
It is this formula that will be most useful to us throughout the remainder of this work.
For the the particular case of the Ising Hamiltonian it has been demonstrated that in the absence of noise the best quantum mechanical strategy, indeed offers a quadratic improvement over the best classical strategy [13]. Moreover, as the Ising Hamiltonian exhibits a phase transition, an alternative approach, based on the ground state overlap between two ground states near the phase transition point [15, 16, 21, 25, 36] has also been shown to yield super-classical scaling, even at non-zero temperature [17]. As the ground states near the phase transition change drastically, this implies that there exists a measurement for which one can estimate either $J$ or $B$ (assuming the other is known) with high precision around the phase transition point. Note that, whilst in general one still needs to perform a complicated measurement, a scheme employing a much more experimentally friendly measurement that still achieves Heisenberg limited precision has been proposed [16].

In the next section we use the ideas [15, 16, 21, 25, 36] and construct an observable such that the entire protocol can be simulated on an exponentially smaller quantum computer.

III. COMPRESSED METROLOGY OF THE ISING MODEL

In this section we shall show how to combine the ideas of compressed simulation for the Ising Hamiltonian, in order to perform a quantum metrology protocol for the precise estimation (i.e., at the Heisenberg limit) of the interaction strength $J$. Specifically, by starting from the ground state of the Ising Hamiltonian for $B = 0$, we will adiabatically evolve the ground state until $B \approx J$, and then measure the expectation value of an adequate observable such that the entire circuit is a MGC. We will show that with just two probe qubits which are interacting with each other via the Ising interaction and log $N$ additional qubits we are able to infer a precise estimate of $J$ as if we had used the Ising Hamiltonian for $N$ system probes.

A natural candidate for inferring the information about the coupling parameter $J$ would be the magnetization. However, as we show in Appendix B, measuring the magnetization would only lead to a suboptimal scaling in the uncertainty. We stress that this result is not in contradiction with the results of [16] as here we are attempting to infer the value of $J$ from the expectation value of the magnetization. In contrast [16] measures in the eigenbasis of the magnetization to obtain the corresponding probability distribution from which an efficient estimator is constructed. Note that such a circuit could not be compressed as all qubits need to be measured at the end.

We will show now that the expectation value $\langle B(g) \rangle$, where here and in the following we use the notation $g = (B, J)$, with

$$B \equiv b_1^* b_1,$$

estimates $J$ with optimal scaling (see also Appendix B). In order to do so, let us compute the scaling of the derivative and the variance of $B$ as a function of $N$ around the phase transition. Using the scaling of these two functions and Eq. (27) we calculate the scaling of the uncertainty $\Delta g$.

The expectation value $\langle B(g) \rangle$ can be computed in an analogous way as in Appendix B. We find that

$$\langle B(g) \rangle = \frac{1}{2} \left[ 1 + \frac{\cos \left( \frac{2 \pi}{N} g \right) - g}{\sqrt{1 + g^2 - 2g \cos \left( \frac{2 \pi}{N} g \right)}} \right].$$

Computing the derivative with respect to $g$ leads to

$$\langle B(g) \rangle' = -\frac{\sin \left( \frac{2 \pi}{N} g \right)^2}{2 [1 + g^2 - 2g \cos \left( \frac{2 \pi}{N} g \right)]^2}.\quad (30)$$

Using $\sin(x) = x$ and $\cos(x) = 1 - x^2/2$ for small $x$, one can verify that $\langle B(g) \rangle' \big|_{g=1} \sim O(N)$ for large $N$. Moreover, as $\langle B^2 \rangle = \langle B \rangle$ it follows that

$$\text{Var}[B(g)] = \frac{\sin \left( \frac{2 \pi}{N} g \right)^2}{4 [1 + g^2 - 2g \cos \left( \frac{2 \pi}{N} g \right)]},\quad (31)$$

and making the same approximations as above for $g = 1$ one obtains $\text{Var}[B(g)] \big|_{g=1} \sim 1/4$.

From the scaling of the derivative and the variance of $B$ at $g = 1$, we can then conclude that using $\langle B(g) \rangle$ in order to estimate $g$ around the phase transition, yields an uncertainty

$$(\Delta g) \big|_{B=g=1}^2 = \frac{\text{Var}[B(g)] \big|_{g=1}}{[\langle B(g) \rangle']^2} \sim O(N^{-2}),$$

meaning that an optimal scaling in the estimation of $g$ is achievable with this operator.

One might wonder whether it is also possible to compress the metrological protocol if we perform the optimal measurement obtained from the eigenbasis of the symmetric logarithmic derivative (see Sec. II E). To see that it cannot simply observe that this measurements requires to project the final state onto the computational basis of all $N$ qubits, which cannot be done in a compressed way. In the next subsection we discuss how a compressible matchgate circuit can be constructed to measure $\langle B(g) \rangle$.

A. Compressed circuit to measure $\langle B(B, J) \rangle$

We use here the results recalled in Sec. II to compress an $N$-qubit matchgate circuit whose output is $\langle B(g) \rangle$. In order to make sure that this compressed circuit can be realized, we must ensure that the whole computation can be done employing only the Ising interaction (acting only on two qubits), and local operations, as we have only this interaction at our disposal.

As recalled in Sec. II (see also [10, 11]), the ground state of the even-parity subspace of the Hamiltonian, is given by $|\Psi(B, J)\rangle = U(B, J) |0\rangle$, where the unitary $U(B, J)$ is given in Eq. (21) [37]. Hence, the expectation value of $\langle B(B, J) \rangle$ is given be

$$\langle B(B, J) \rangle = \langle 0 | U^\dagger(B, J) B U(B, J) |0\rangle.$$

In order to derive now a compressed circuit leading to this expectation value, we need to express $B$ in terms of
the Majorana operators \( x_j \). Using the mapping between \( b \) and \( c \) operators given in Eq. (10) and the mapping between \( c \) operators and Majorana operators we find

\[
B[x] = \frac{1}{4N} \sum_{j,k=0}^{N-1} e^{i \frac{2\pi}{N} (k-j)} (x_{2j} x_{2k} + x_{2j+1} x_{2k+1} + i x_{2j} x_{2k+1} - i x_{2j+1} x_{2k})
\]

where

\[
b_{l,m} = \begin{cases} \\
\frac{1}{2} e^{i \frac{2\pi}{N} (k-j)} & (l, m) = (2j, 2k), \\
\frac{1}{2} e^{i \frac{2\pi}{N} (k-j)} & (l, m) = (2j, 2k+1), \\
0 & \text{otherwise}, \\
\end{cases}
\]

for \( j, k \in [0, N-1] \). Using this expression of \( B \) it is straightforward to see that

\[
\langle B(B, J) \rangle = \sum_{j,k=0}^{2N-1} b_{j,k} \langle 0 | U^l (B, J) x_j x_k U (B, J) | 0 \rangle = -\frac{1}{2} \langle \Phi | R(B, J) Y_m R^T(B, J) | \Phi \rangle,
\]

where \( R(B, J) \) denotes the “compressed gate” corresponding to \( U(B, J) \) (see Eq. (6)) and \( | \Phi \rangle = \bigotimes_{j=0}^{m-1} \left( |0\rangle + e^{2\pi j x_{-m}} |1\rangle \right) \otimes |+\rangle \). This expression represents the outcome of a quantum circuit like the one depicted in Fig. 1, where the initial \((m + 1)\)-qubit state \(|\Phi\rangle\) is transformed by the real orthogonal matrix \( R^T(B, J) \) and the operator \( Y_m \) (last qubit) is measured on the output state. In \([11, 23]\) the gate \( R(B, J) \) has been shown to be of the form

\[
R(B, J) = \prod_{l=0}^{L} R_0(B) R_1(J, l),
\]

where \( R_0(B) = e^{-4iB\Delta h_0} \) and \( R_1(J, l) = e^{-4iJ \Delta h_1} \) correspond to \( U_0(B) \) and \( U_1(J, l) \) given in Eq. (22) respectively. Here, \( \Delta = T/L + 1 \) (see Sec. [11]), \( h_0 = \frac{i\pi}{2} (\mathbb{1} \otimes Y_m) \), and \( h_1 = Ah_0 A^\dagger \), where

\[
A = \sum_{j=0}^{2N-2} |j+1\rangle \langle j| + |0\rangle \langle 2N-1|.
\]

B. Implementation of the compressed circuit using the Ising interaction between two qubits and local operations

In order to implement now the compressed circuit presented above with the interactions we have at our disposal, we need to decompose the gates \( R_0(B) \) and \( R_1(J, l) \) into local gates and unitary evolutions corresponding to the Ising interaction. We will show that this can be achieved employing the Ising interaction at \( B = 0 \) acting only on two qubits.

Using that \( h_0 = -i/2 (\mathbb{1} \otimes Y_m) \) we have \( R_0^T(B) = \mathbb{1} \otimes S_0(B) \), where \( S_0(B) = e^{-2iB \Delta Y} \) is a single qubit gate acting on qubit \( m \). It can be easily seen that \( R_1^T(J, l) = A(1 \otimes S_1(J, l)) A^\dagger \), where

\[
S_1(J, l) = e^{-i \tau (l) Y} \tag{39}
\]

with \( \tau(l) = 2L\Delta/|J| \). It is important to note here that the operator \( A \) does not depend on any parameters of the Hamiltonian. Hence, the gate \( R^T(B, J) \) can be decomposed into a product of terms of the form depicted in Fig. 2.

Let us remark here that the operator \( A \), which corresponds to the operation that maps \(|j\rangle \) to \(|j+1 \mod (N)| \) for any \( j \), is decomposable into the simple product of controlled operations

\[
A = \prod_{l=0}^{N-1} A_{l+1, \ldots, m}(X_l),
\]

which can then be implemented by a product of \( m + 1 \) controlling operations, as is depicted in Fig. 3. Furthermore, the single qubit gate \( S_1 \), depends on the unknown parameter \( J \), which we wish to estimate. In Fig. 4 we show how this single qubit gate can be implemented as a time evolution under the action of a two qubit Ising Hamiltonian.
is, if the auxiliary qubit is prepared in the state $|\psi\rangle$ for which $|\psi\rangle$ holds, we have

$$S_1 |j\rangle \equiv e^{-i\tau(l)X_{XX}} |j\rangle \equiv \left(\tilde{H} \otimes I_a\right) e^{-i\tau(l)X_{XX}} \left(\tilde{H} \otimes I_a\right) |j\rangle \equiv +\rangle_a$$

for $j = 0, 1$, where $a$ denotes the auxiliary system. That is, if the auxiliary qubit is prepared in the state $|+\rangle$, then the gate $S_1(J,l)$ can be substituted by the two-qubit gate

$$\tilde{S}_1(J,l) \equiv \left(\tilde{H} \otimes I_a\right) R_{XX}(J,l) \left(\tilde{H} \otimes I_a\right)$$

as also depicted in Fig. 3.

In summary, we have that the expectation value of $\langle B(J) \rangle$ can be measured using the following circuit.

1) The system is prepared in the $(m+2)$-qubit state

$$|\Phi\rangle = \bigotimes_{i=0}^{m-1} \frac{1}{\sqrt{2}} (|0\rangle + e^{2\pi i a_{i,m}} |1\rangle) \otimes |+_a\rangle |+_a\rangle,$$

where $a$ denotes the auxiliary system.

2) The system evolves for a particular value of $J$ according to the operator $R^T(B,J)$ (see Eq. (37)), where $R_0^T$ is replaced by $R_0^T \otimes I_a$ and in $R_1 = A[I \otimes S_1(J,l)]A^\dagger$, $S_1(J,l)$ is replaced by the two-qubit gate $\tilde{S}_1(J,l)$, given in Eq. (43). This is achieved by sequentially applying the gates which do not depend on the Hamiltonian parameters to the system and then letting the $m$-th qubit and the auxiliary qubit interact due to the Ising interaction (for $B = 0$) and for a time $\tau(l) = 2l\Delta/L$.

3) Finally the operator $Y_m$ is measured (on qubit $m$) to retrieve the expectation value of $B$ at the value $J$.

As shown above, this expectation value can be used to estimate the parameter $J$ optimally.

Let us now review the resources required in order to measure $\langle B(B,J) \rangle$ using the above compressed circuit. The latter utilizes $m + 2$ qubits upon which a sequence of gates simulating $L + 1$ Trotter steps of an adiabatic evolution runs for a duration $T$. Each Trotter step $t$, for $0 \leq t \leq L$, can be implemented using $O(m^2)$ elementary gates and an infinitesimal time evolution step, governed by the 2-qubit Ising Hamiltonian, for a time $\tau(l) = 2l\Delta/L$, where $\Delta = T(L + 1)$. Notice that the $O(m^2)$ control gates do not involve the interaction Hamiltonian in any way and are thus not part of the available resources. The latter are simply the total time the Ising Hamiltonian has to be used and is given by $\sum_{l=0}^{L} \tau(l) = T$. As already mentioned in Sec. II B there exists a simpler strategy that also achieves the Heisenberg limit with the same resources $T$. This strategy consists of preparing the two qubit state $|0_a\rangle |0\rangle$ and sequentially subjecting it to the modified Ising interaction $e^{i\frac{\pi}{4} Y_a} (JX_a \otimes X_a) e^{i\frac{\pi}{4} Y_a}$ applied on the first system.

Unlike the above strategy, in order for our simulation to work we need to ensure that the digital-adiabatic evolution which we are using [see Eq. (21)] equals the true adiabatic evolution up to a small enough error which scales as $O(L\Delta^2)$. It was shown that the choice $T \gg O(N^2)$ guarantees that the simulated adiabatic evolution generates the ground state of the Ising model with probability $1$. As a result the number of Trotter steps, $L$, has to be chosen such that the error in the discretization of the adiabatic evolution is negligible. Moreover, this error must not exceed the error in the estimation of $\langle B(B,J) \rangle$. We find that $L = O(N^5)$ Trotter steps are needed to satisfy both these conditions.

We stress that even though our digital-adiabatic evolution requires $L$ calls to the Ising interaction, the duration of each call is such that the total time the Ising interaction is used is $T$. This is to make sure that our simulation of the adiabatic evolution of the ground state followed by the measurement of $B$ is as faithful as possible.

IV. Conclusion

We have shown how compressed quantum computation can be used to simulate a quantum metrology protocol for the estimation of the interaction strength of a one-dimensional Ising chain of $N$ spins. Specifically, we have
shown how a specific metrology protocol utilizing $N$ spins can be simulated on a quantum computer that uses only $\log(N)$ qubits and still achieves optimal precision scaling, namely $O(N^{-2})$. The protocol simulated consists of preparing the $N$ systems in the ground state of the Ising Hamiltonian with zero magnetic field and adiabatically evolving the system to the phase transition point $B \approx J$ before measuring the single fermionic mode observable $B$ of Eq. (25). As such a circuit is a match gate circuit, it can be efficiently compressed onto an exponentially smaller quantum computer.

While for the example considered here a simpler strategy yielding the same optimal precision exists, we believe that the idea of running a compressed metrology protocol, as outlined in this paper, can be useful when the parameter of interest has to be estimated from the measurement outcomes of staggered correlation functions, or for instances where the exotic states and measurements (and intermediate control operations) are difficult to physically implement.

Finally, an interesting direction for future work would be the study of how different types of noise processes manifest themselves in the compressed protocol and whether the inclusion of additional techniques [5] can be utilized to combat noise more efficiently in the compressed protocol.

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Appendix A: Precision estimation using a Hermitian operator

In this section we use standard error-propagation to determine the error in our estimate, $\hat{g}$, of the true parameter $g$, when our measurement operator is equal to the Hermitian operator $A = \sum_x x |x\rangle \langle x|$ and the measurement outcome is the expectation value of $A$ with respect to the state pure state $|\psi(g)\rangle$, i.e.,

$$\langle A(g) \rangle = \langle \psi(g) | A | \psi(g) \rangle = \sum_x x |\langle \psi(g) | x \rangle|^2. \quad (A1)$$

Now let us denote the prior probability distribution over the parameter $g$ as $p(g)$. Then the average value of $\langle A(g) \rangle$

$$E_g(\langle A(g) \rangle) = \int dg p(g) \langle A(g) \rangle \quad (A2)$$

Now consider $E_g(\langle A(g') \rangle)$, where $g' \equiv g + \delta g \in \mathbb{R}$. Taylor expanding the operator $A(g)$ to first order in $\delta g$,

$$A(g') = A(g) + \frac{dA(g')}{dg'}|_{g'=g} \delta g, \quad (A3)$$

one obtains

$$E_g(\langle A(g') \rangle) = E_g(\langle A(g) \rangle) + \frac{dA(g')}{dg'}|_{g'=g} \epsilon, \quad (A4)$$

where $\epsilon \equiv \int p(g) \delta g dg$. It therefore follows that the average error of the expectation value $\langle A(g) \rangle$,

$$\Delta^2 \langle A(g) \rangle \equiv \int p(g) \left( \langle A(g) \rangle - A(g + \delta g) \right)^2 dg \quad \Delta^2 \langle A(g) \rangle = \left( \frac{dA(g')}{dg'}|_{g'=g} \right)^2 \sigma^2,$ \quad (A5)$$

where $\sigma^2 \equiv \int p(g) \delta g^2 dg$ is the mean square error of our estimation. Hence

$$\sigma^2 = \frac{\Delta^2 \langle A(g) \rangle}{\left( \frac{dA(g')}{dg'}|_{g'=g} \right)^2}. \quad (A6)$$

Observe that for a sufficiently narrow prior, i.e., $p(g) = \delta(g_0 - g)$, which is the case considered in local estimation one obtains

$$\delta g^2 = \frac{\Delta^2 A(g)}{\left( \frac{dA(g')}{dg'}|_{g'=g} \right)^2} \quad (A7)$$

where

$$\Delta^2 A(g) = \sum_x (x - \langle A(g) \rangle)^2 |\langle x | \psi(g) \rangle|^2 \quad \Delta^2 A(g) = \langle \psi(g) | A^2 | \psi(g) \rangle - \langle \psi(g) | A | \psi(g) \rangle^2,$ \quad (A8)$$

which is the result of Eq. (27).

Appendix B: Using the magnetization as an estimator of $g$

In this section we discuss the use of the magnetization of the state $|\Psi\rangle$ as an estimator of the parameter $J$ of the Ising Hamiltonian, i.e., the expectation value $\langle M(B, J) \rangle$ with $M = \frac{1}{N} \sum_{j=1}^{N-1} \sum_i z_i$. We compute the scaling of the error in the estimation of $J$ as a function of $N$. For simplicity, in this section and in the following, we are going to use the variable $g = B/J$. As we assume full control of parameter $B$, estimating $g$ is equivalent to estimating $J$. Furthermore, we are always going to consider measurement of observables on the state $|\Psi\rangle$ defined in Sec. [11D]. Therefore, we are going to use the simplified notation $\langle A(B, J) \rangle \equiv \langle \Psi | A | \Psi \rangle$ and $\text{Var}(A) \equiv \langle A^2 \rangle - \langle A \rangle^2$ to refer to the expectation value and the variance of an operator $A$ measured over the state $|\Psi\rangle$.

The motivation to choose the magnetization as an estimator of the parameter $g$ is twofold. On the one hand, a matchgate circuit to measure $\langle M(g) \rangle$ can be easily constructed, and compressed in the way discussed in Sec. [11C]. On the other hand the magnetization shows an abrupt behavior at the phase transition, which is reflected by its derivative reaching its maximum value at $g = 1$. Due to the dependency of $\Delta g$ on the derivative, a large value of $\langle M(g) \rangle$ allows for an estimation of $g$ with better precision about $g = 1$.

In the following we compute $\langle M(g) \rangle$, $\langle M(g) \rangle'$ and $\text{Var}(M(g))$. Using these functions, the error $\Delta g$ can be computed according to Eq. (27). As we will see, although the scaling of $\Delta g$ is relatively better at the phase transition, it remains sub-optimal, in the way discussed in
Recalling that above expression can be written explicitly as a function \( g \) from which one can estimate can be used instead of the magnetization operator, and from which one can estimate \( g \) with optimal scaling.

Using the Jordan-Wigner transformation given in Eq. (4) and the Fourier transformation given in Eq. (10), the magnetization operator \( M \) can be written in term of the \( b \) operators as

\[
M[b] = \frac{1}{N} \sum_{j=0}^{N-1} \left( b_j b_j^\dagger - b_j^\dagger b_j \right). \tag{B1}
\]

Combining this equation with the expression of the state \(|G[b]\rangle\), Eq. (18), we have that

\[
M[b] |G[b]\rangle = \frac{1}{N} \left[ 2 |\tilde{\Psi}[b]\rangle + \sum_{j=1}^{N-1} |\Omega_0[b]\rangle \otimes |\zeta_j[b]\rangle \right], \tag{B2}
\]

where \(|\zeta_j[b]\rangle = \left( b_j b_j^\dagger - b_j^\dagger b_j \right) |\tilde{\Psi}[b]\rangle\). It follows that the expectation value of the magnetization is given by

\[
\langle M \rangle = \frac{1}{N} \left[ 2 + \sum_{j=1}^{N-1} \langle \tilde{\Psi}_j|b\rangle \langle \zeta_j|b\rangle \right] = \frac{2}{N} \left[ 1 + \sum_{j=1}^{N-1} (1 - 2v_j^2) \right]. \tag{B3}
\]

Recalling that \( 1 - 2v_j^2 = \cos(\theta_j) \), given in Eq. (12), the above expression can be written explicitly as a function of \( g \) as

\[
\langle M(g) \rangle = \frac{2}{N} \left[ 1 + \sum_{j=1}^{N-1} \frac{g - \cos(\xi_j)}{\sqrt{1 + g^2 - 2g \cos(\xi_j)}} \right]. \tag{B4}
\]

Consequently, the derivative of the magnetization with respect to \( g \) leads to the expression

\[
\langle M(g) \rangle' = \frac{2}{N} \sum_{j=1}^{N-1} \frac{\sin^2(\xi_j)}{\left[ 1 + g^2 - 2g \cos(\xi_j) \right]^2}. \tag{B5}
\]

Evaluating numerically for \( g = 1 \), one can see that for large \( N \) the function \( \langle M(g) \rangle' / \log(N) \) tends asymptotically to a constant value. Therefore we conclude that the derivative about the phase transition scales as \( \langle M(g) \rangle'_{|g=1} \sim \mathcal{O}(\log(N)) \).

The variance of the magnetization, given by \( \text{Var}[M(g)] = \langle M^2(g) \rangle - \langle M(g) \rangle^2 \) can be computed in a similar way to \( \langle M(g) \rangle \), to obtain

\[
\text{Var}[M(g)] = \frac{4}{N^2} \left[ 1 + \sum_{j=1}^{N-1} \frac{\sin^2(\xi_j)}{\left[ 1 + g^2 - 2g \cos(\xi_j) \right]} \right]. \tag{B6}
\]

For large \( N \) the sum in the previous expression can be approximated by an integral which for \( g = 1 \) scales as \( \mathcal{O}(N) \). Therefore, the variance scales as \( \text{Var}[M(g)]_{|g=1} \sim \mathcal{O}(N^{-1}) \).

In conclusion we have that using \( \langle M(g) \rangle \) as a way to estimate the parameter \( g \), yields an error in the estimation, which close to the phase transition is given by (see Eq. (27))

\[
\Delta g_{|g=1}^2 = \frac{\text{Var}[M(g)]_{|g=1}}{\langle M(g) \rangle'^2_{|g=1}} \sim \mathcal{O}(N \log(N))^{-1}. \tag{B7}
\]

Hence, using the magnetization as an estimator, \( g \) can be estimated only with a suboptimal scaling on its uncertainty.

One can notice that although \( \langle M(g) \rangle' \) scales as \( N \), some of the terms in the sum in Eq. (B5) scale more rapidly (e.g. the term with \( j = 1 \)), but they are averaged down by the global factor \( 2N^{-1} \). This suggest that a different observable than \( M \), where only the term with \( j = 1 \) is considered in Eq. (B1), could be used to estimate \( g \) with a better scaling than the one achieved with the magnetization, as we show in the main text.

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We note that this strategy yields the exact same precision as the standard parallel scheme, where $N$ suitably entangled probe systems sense the evolution in parallel for a short time $\delta t$ before they are measured. Moreover, the resources used are the same $N\delta t \equiv T$.

Recall that the ground state satisfies $a_j \langle \Omega| a_j \rangle = 0$, $\forall j$. 

Note that here and in the following we omit to write the dependency on $T$ and $L$, keeping in mind that all the results are an approximation which holds for large values of $T$ and $L$ (see Sec. II).

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