Resolving Indeterminacy Approach to Solve Multi-criteria Zero-sum Matrix Games with Intuitionistic Fuzzy Goals

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Abstract: The intuitionistic fuzzy set (IFS) is applied in various decision-making problems to express vagueness and showed great success in realizing the day-to-day problems. The principal aim of this article is to develop an approach for solving multi-criteria matrix game with intuitionistic fuzzy (I-fuzzy) goals. The proposed approach introduces the indeterminacy resolving functions of I-fuzzy numbers and discusses the I-fuzzy inequalities concept. Then, an effective algorithm based on the indeterminacy resolving algorithm is developed to obtain Pareto optimal security strategies for both players through solving a pair of multi-objective linear programming problems constructed from two auxiliary I-fuzzy programming problems. It is shown that this multi-criteria matrix game with I-fuzzy goals is an extension of the multi-criteria matrix game with fuzzy goals. Moreover, two numerical simulations are conducted to demonstrate the applicability and implementation process of the proposed algorithm. Finally, the achieved numerical results are compared with the existing algorithms to show the advantages of our algorithm.

Keywords: intuitionistic fuzzy set; multi-criteria matrix games; intuitionistic fuzzy goals; game theory; multi-objective programming; indeterminacy resolving approach

1. Introduction

1.1. Background

Game theory is a mathematical tool to study the conflict and cooperation among intelligent, rational decision makers. So, decision making in competitive environments is known to be a critical process. Game theory has been extensively applied in several fields, such as behavioral science, economics [1], pattern recognizers, complex engineering, biology, business modeling, politics and investment management, etc. [2,3]. The zero sum multi-criteria matrix game is an extension of the standard zero sum two person game model. The zero sum multi-criteria game is also defined as the multi-objective matrix game as it involves two or more than two decision-makers and can be expressed by multiple payoffs. As conflicting interests appear not only between different decision-makers, but also within each individual, the study of multi-criteria matrix games becomes vital in recent years. Blackwell [4] was the first to introduce the multi-criteria game theory as a generalization of the two person game problem. Cook [5] presented a goal vector and formulated the multi-criteria matrix games as goal programming models. Kumar [6] considered max-min solution
algorithm for solving multi-criteria matrix game with fuzzy goals. Zeleny [7] studied the max-min and min-max values of multi-criteria zero-sum games by aggregating multiple payoffs through weighting coefficient. Fernandez et al. [8] investigated the equivalence between Pareto-optimal security strategies and efficient solutions of multi-objective linear optimization models. Ghose et al. [9] introduced the concepts of Pareto saddle points, Pareto-optimal, and security levels of the multi-objective zero-sum matrix game. Nishizaki et al. [10] developed a multi-criteria zero-sum two person matrix games with fuzzy goals and fuzzy payoffs. Corley [11] investigated the sufficient and necessary condition for optimal strategies for the zero sum multi-criteria matrix game. Fahem et al. [12] implemented the concept of efficient equilibrium solution to the multi-objective non-cooperative game. Shapely [13] discussed the concept of an equilibrium solution in multi-criteria zero-sum games by using the Pareto-optimality concept.

In order to make the multi-criteria matrix game more applicable to real competitive decision models, the fuzzy set has been applied to express uncertain and imprecise information appearing in multi-criteria games. The fuzzy set only uses a membership function to express the belongingness degree, and the non-belongingness degree is automatically the complement to one. In reality, players frequently do not represent the non-membership degree of a given value as the complement of the membership degree to one. In some situations, players represent their negative feelings, i.e., their dissatisfaction degrees about the payoffs of the game. Moreover, it is possible that both players are not sure about the payoffs of the game. In other words, players may have some uncertainty or hesitation degree about the selection of a strategy for each of the payoffs, so the fuzzy set has no means to incorporate the degree of hesitation. Thus, Atanassov [14,15] introduced the idea of IFS, which is a generalization of fuzzy set theory suitable to describe uncertainty and imprecision in decision making problems. The IFS is represented by two functions describing the non-memberships degree and the membership degree, the sum of both the non-membership degree and the membership degree is less than or equal to 1. The hesitation degree is equal to one minus the sum of both values. The IFS has been applied to some fields such as pattern recognitions, logic programming, decision analysis, and medical diagnosis [16,17].

1.2. Literature Review

Intuitionistic fuzziness in game theory is generally studied using two techniques: in the first technique, decision makings have I-fuzzy goals; in the second technique, the payoffs elements are expressed by I-fuzzy numbers. However, there exist few studies on multi-criteria matrix games using the I-fuzzy set. Li et al. [18] proposed a nonlinear programming algorithm for matrix games in which payoffs are expressed by I-fuzzy numbers. Nan et al. [19] developed a lexicographic approach to matrix games with payoffs of triangular I-fuzzy numbers. Seikh et al. [20] discussed matrix games in the I-fuzzy environment. Bandyopadhyay et al. [21] studied matrix games with I-fuzzy payoffs through a score function. Aggarwal et al. [22] applied a linear programming approach with IFSs to matrix games with I-fuzzy goals. Li et al. [23] presented a bi-objective programming technique for solving matrix games with payoffs of triangular I-fuzzy numbers. Nayak et al. [24] implemented an I-fuzzy optimization algorithm for the optimal solution of multi-objective bi-matrix game. Jana et al. [25] studied matrix games with generalized trapezoidal fuzzy payoffs. Nan et al. [26] described an algorithm for matrix games with payoffs of triangular I-fuzzy number. Seikh et al. [27] discussed matrix games with I-fuzzy payoffs. Nan et al. [28] proposed a linear programming algorithm for solving matrix games with I-fuzzy payoffs. Li et al. [29] introduced game theory and decision in management with IFS. Nan et al. [30] investigated I-fuzzy programming problems for matrix games with trapezoidal I-fuzzy payoffs. Verma et al. [31] proposed a methodology for solving matrix games with triangular I-fuzzy payoffs. Yumei et al. [32] applied an accuracy function technique for solving triangular I-fuzzy matrix game. Verma et al. [33] proposed an algorithm to solve matrix games with payoffs represented by trapezoidal I-fuzzy numbers. Roy et al. [34] discussed the type-2 triangular I-fuzzy matrix games algorithm for solving the water resources management problem. Jana et al. [35] solved dual hesitant fuzzy matrix games through using a similarity measure. Dejian et al. [36] studied a dual hesitant fuzzy group decision making approach. Donghai et al. [37] presented
a cosine distance measure between neutrosophic hesitant fuzzy linguistic sets. Faizi et al. [38] showed hesitant fuzzy sets for group decision-making problem by using characteristic objects algorithm. Joshi et al. [39] proposed multi-criteria group decision making problems with hesitant probabilistic fuzzy linguistic sets. Singh et al. [40] discussed multi criteria decision making model with symmetric triangular interval type-2 IFSs.

1.3. The Contribution and Structure of This article

Real-life problems usually entail imprecision and uncertainty in the decision-making process. Therefore, linguistic set, fuzzy set, and IFS are frequently applied to express uncertain and imprecise parameters appearing in decision making problems. The IFS helps to describe situations requiring negation, affirmation, and hesitation simultaneously. Thus, the IFS represent more information than the fuzzy set. In this article, we study multi-criteria zero-sum matrix games with IFSs goals in which the goals of players are represented with IFSs, and payoffs of both players are real numbers. As demonstrated by Aggarwal et al. [41], the multi-criteria matrix game with IFSs goals differs from the multi-criteria matrix game with fuzzy set goals. The IFSs use the membership degree and the non-membership degree to represent the goals of both players, while the fuzzy set uses only the membership degree to represent the goals of both players. Thus, the hesitation degree of the IFS goals is not equal to zero, while the hesitation degree of the fuzzy set goals is always equal to zero. Consequently, the conventional approaches and models of fuzzy multi criteria matrix games cannot be used directly to solve multi criteria matrix games with I-fuzzy goals. Thus, this article proposes a resolving indeterminacy approach to solve multi criteria matrix games with I-fuzzy goals. An I-fuzzy multi-objective linear programming problem is constructed to obtain the Pareto optimal security strategies of any multi criteria matrix game with I-fuzzy goals depending upon the pessimistic and optimistic attitude of the players. Utilizing the defined I-fuzzy inequality relations, resolving indeterminacy function, and Inuiguchi et al. [42] algorithms, the multi criteria matrix game with I-fuzzy goals is transformed into a crisp multi-objective linear programming model which can be solved by GAMS software [43]. Brikaa et al. [44] developed an effective fuzzy multi-objective programming approach to solve constraint matrix games with payoffs of fuzzy rough numbers through using Zimmermann’s fuzzy programming algorithm. However, the multi-criteria matrix game studied under the I-fuzzy set environment in this article is entirely different from that of Brikaa et al. [44].

The remainder of this article is organized as follows: Section 2 introduces some basic definitions and preliminary related to IFS. Section 3 discusses the classical multi-criteria zero sum matrix games. Then, Section 4 introduces the application of IFSs to the optimization problem. In Section 5, we formulate multi-criteria matrix games with I-fuzzy goals. Section 6 presents the resolving indeterminacy method to solve such game. Applicability and validity of the proposed algorithm and models are illustrated with two numerical experiments in Section 7. Finally, Section 8 concludes the work done and describes potential directions that may require further research.

2. Preliminaries

In this section, we provide some essential definitions of IFS used through our paper. The IFS discussed by Atanassov’s [15] is characterized by two functions that represent the membership degree and the non-membership degree.

**Definition 1** ([15]). Suppose \( Y = \{y_1, y_2, ..., y_n\} \) be a finite universal set. The IFS \( \tilde{B} \) in a universal set \( Y \) is described by

\[
\tilde{B} = \{(y, u_{\tilde{B}}(y), \mu_{\tilde{B}}(y))|y \in Y\}
\]

where the functions \( u_{\tilde{B}}: Y \rightarrow [0,1] \) and \( \mu_{\tilde{B}}: Y \rightarrow [0,1] \) are the membership degree and the non-membership degree of an element \( y \in Y \) to the set \( \tilde{B} \subseteq Y \), such that they satisfy the conditions:

\[
0 \leq u_{\tilde{B}}(y) + \mu_{\tilde{B}}(y) \leq 1, \ \forall y \in Y.
\]
which is known as intutionistic condition. The non-acceptance degree \( \mu_b(y) \) and the acceptance degree \( u_b(y) \) can be arbitrary.

**Definition 2** ([15]). For IFSs \( \tilde{B} \) in \( Y \), the intuitionistic index of the element \( y \) in the set \( \tilde{B} \) is defined by

\[
\pi_{\tilde{B}}(y) = 1 - u_{\tilde{B}}(y) - \mu_{\tilde{B}}(y), \quad y \in Y,
\]

(2)

Obviously,

\[
0 \leq \pi_{\tilde{B}}(y) \leq 1, \forall y \in Y.
\]

(3)

Obviously, when \( \pi_{\tilde{B}}(y) = 0, \forall y \in Y \), i.e., \( u_{\tilde{B}}(y) + \mu_{\tilde{B}}(y) = 1 \), the set \( \tilde{B} \) is a fuzzy set as follows: \( \tilde{B} = \{(y, u_{\tilde{B}}(y), 1 - u_{\tilde{B}}(y))|y \in Y\} = \{(y, u_{\tilde{B}}(y))|y \in Y\} \).

**Definition 3** ([15]). Suppose \( \tilde{B} \) and \( \tilde{D} \) are two IFSs in the universal set \( Y \). The operations over IFSs are given as follows:

1. \( \tilde{B} \cup \tilde{D} = \{(y, \max( u_{\tilde{B}}(y), u_{\tilde{D}}(y)), \min( \mu_{\tilde{B}}(y), \mu_{\tilde{D}}(y)))|y \in Y\} \),
2. \( \tilde{B} \cap \tilde{D} = \{(y, \min( u_{\tilde{B}}(y), u_{\tilde{D}}(y)), \max( \mu_{\tilde{B}}(y), \mu_{\tilde{D}}(y)))|y \in Y\} \),
3. \( \tilde{B} = \{(y, \mu_{\tilde{B}}(y), u_{\tilde{B}}(y))|y \in Y\} \),
4. \( \tilde{B} \subseteq \tilde{D} \) if and only if \( u_{\tilde{B}}(y) \leq u_{\tilde{D}}(y) \) and \( \mu_{\tilde{B}}(y) \geq \mu_{\tilde{D}}(y) \).

**Definition 4** ([15]). Suppose \( \tilde{B} \) and \( \tilde{D} \) are two IFSs in the universal set \( Y \). \( \tilde{B} = \tilde{D} \) iff \( u_{\tilde{B}}(y) = u_{\tilde{D}}(y) \) and \( \mu_{\tilde{B}}(y) = \mu_{\tilde{D}}(y), \forall y \in Y \).

**Definition 5** ([45]). The triangular L-fuzzy number \( \tilde{b} = ((b_l, b, b_r); v_b, \omega_b) \) on the \( \mathbb{R} \) real number set is a special form of IFS, whose membership function and non-membership function are given as follows:

\[
u_b(y) = \begin{cases} 
0 & \text{if } y < b_l \\
\frac{v_b(y - b_l)}{(b - b_l)} & \text{if } b_l \leq y < b \\
v_b & \text{if } y = b \\
\frac{v_b(b_r - y)}{(b_r - b)} & \text{if } b < y \leq b_r \\
0 & \text{if } y > b_r 
\end{cases}
\]

(4)

and

\[
\mu_b(y) = \begin{cases} 
1 & \text{if } y < b_l \\
\frac{b - y + \omega_b(y - b_l)}{(b - b_l)} & \text{if } b_l \leq y < b \\
\omega_b & \text{if } y = b \\
\frac{y - b + \omega_b(b_r - y)}{(b_r - b)} & \text{if } b < y \leq b_r \\
1 & \text{if } y > b_r 
\end{cases}
\]

(5)

respectively, where \( v_b \) and \( \omega_b \) describe the maximum degree of membership and the minimum degree of non-membership, respectively. Such that they satisfy the following conditions:

\[0 \leq v_b \leq 1, 0 \leq \omega_b \leq 1, \text{ and } 0 \leq v_b + \omega_b \leq 1.\]

**Definition 6** ([45]). Suppose \( \tilde{b} = ((b_l, b, b_r); v_b, \omega_b) \) and \( \tilde{d} = ((d_l, d, d_r); v_d, \omega_d) \) are two generalized triangular L-fuzzy numbers with \( v_b \neq v_d \) and \( \omega_b \neq \omega_d \). The arithmetic operations are given as follows:

1. \( \tilde{b} + \tilde{d} = ((b_l + d_l, b + d, b_r + d_r); \min(v_b, v_d), \max(\omega_b, \omega_d)) \),
2. \( \tilde{b} - \tilde{d} = ((b_l - d_r, b - d, b_r - d_l); \min(v_b, v_d), \max(\omega_b, \omega_d)) \),
3. \( h\tilde{b} = ((hb_l, hb, hb_r); v_b, \omega_b) \) if \( h \geq 0 \)

where \( h \) is any real number.
Definition 7 ([46]). For IFSs \( \tilde{B} \) in \( Y \), the score function \( f_{\tilde{B}} : Y \rightarrow [-1,1] \), is given by
\[
 f_{\tilde{B}}(y) = u_{\tilde{B}}(y) - \mu_{\tilde{B}}(y), \quad y \in Y. \tag{6}
\]

Definition 8 ([46]). Let \( \sigma \in [0,1] \) and \( \tilde{B} \) be IFSs in \( Y \). The resolving indeterminacy function \( g_{\tilde{B}}(\sigma, y) \), is defined by
\[
 g_{\tilde{B}}(\sigma, y) = (1 - \sigma) u_{\tilde{B}}(y) + \sigma \left( 1 - \mu_{\tilde{B}}(y) \right), \quad y \in Y. \tag{7}
\]

3. Zero-Sum Multi-Criteria Matrix Games

In this section, we begin to review the classical multiple objective zero sum matrix game in [41]. Let \( \mathbb{R}^\ell \) be the \( \ell \)-dimensional Euclidean space and \( \mathbb{R}_+^\ell \) be its positive orthant. Suppose \( B^n \in \mathbb{R}^{K \times \ell}, n = 1,2,\ldots,s \) be real \( K \times \ell \) matrices, \( e^T = (1,1,\ldots,1) \) be a vectors of ones and \( S^K = \{ y \in \mathbb{R}_+^K | e^T y = 1 \} \) and \( S^\ell = \{ y \in \mathbb{R}_+^\ell | e^T y = 1 \} \) are convex polytopes.

We mean by zero sum two person multi-objective matrix game (MOG)
\[
 \text{MOG} = (S^K, S^\ell, B^n, (n = 1,2,\ldots,s)). \tag{8}
\]

Definition 9. For \( y \in S^K, z \in S^\ell \), the expected payoff of player I is defined by
\[
 E(y, z) = y^T B z = [E_1(y, z), E_2(y, z), \ldots, E_s(y, z)] = [y^T B^1 z, y^T B^2 z, \ldots, y^T B^s z]. \tag{9}
\]

Since the multi-objective game is zero-sum, the expected payoff for Player II is \(-E(y, z)\).

Definition 10. For a strategy \( y \in S^K \), the player’s I security level corresponding to \( n \)th payoff matrix is defined by
\[
 V_n(y) = \min_{y \in S^K} E_n(y, z) = \min_{y \in S^K} y^T B^n_i. \tag{10}
\]

where \( B^n_i \) is the \( i \)th column of the matrix \( B^n \).

Definition 11. For a strategy \( z \in S^\ell \), the player’s II security level corresponding to \( n \)th payoff matrix is defined by
\[
 W_n(z) = \min_{y \in S^K} E_n(y, z) = \min_{y \in S^K} B^n_i z. \tag{11}
\]

where \( B^n_i \) is the \( i \)th row of the matrix \( B^n \).

Definition 12. The strategy \( y^* \in S^K \) is called Pareto optimal security strategy (POSS) of player I if there is no \( y \in S^K \) such that:
\[
 V(y) \geq V(y^*) \text{ and } V(y) \neq V(y^*). \tag{12}
\]

Definition 13. The strategy \( z^* \in S^\ell \) is called Pareto optimal security strategy (POSS) of player II if there is no \( z \in S^\ell \) such that:
\[
 W(z) \geq W(z^*) \text{ and } W(z) \neq W(z^*). \tag{13}
\]
Theorem 1. The vector $V^*$ and the strategy $y^*$ are security level and POSS for player I, respectively, if and only if $(y^*, V^*)$ is an optimal solution to the below multi-objective programming model:

$$\begin{align*}
\max \{V_1, V_2, \ldots, V_s\} \\
\text{s. t.} \quad \begin{cases}
y^T B^s \leq y^s_n, & n = 1, 2, \ldots, s, j = 1, 2, \ldots, \ell, \\
e^T y = 1, & y \geq 0.
\end{cases}
\end{align*}$$

(14)

Theorem 2. The vector $W^*$ and the strategy $z^*$ are security level and POSS for player II, respectively, if and only if $(z^*, W^*)$ is an optimal solution to the below multi-objective programming model:

$$\begin{align*}
\min \{W_1, W_2, \ldots, W_s\} \\
\text{s. t.} \quad \begin{cases}
B^i z \leq W_n, & n = 1, 2, \ldots, s, i = 1, 2, \ldots, r, \\
e^T y = 1, & y \geq 0.
\end{cases}
\end{align*}$$

(15)

4. Application of IFS to Optimization Problem

4.1. Decision Making Approaches with I-Fuzzy Environment

Angelov [47] discussed the model of decision making with I-fuzzy environment. Suppose $Y$ be the universal set. Let $Q_i$ $(i = 1, 2, \ldots, r)$ be the set of $r$ constraint and $P_i$ $(i = 1, 2, \ldots, m)$ be the set of $m$ goals, each of which can be expressed by IFS on $Y$. The I-fuzzy decision $H = (P_1 \cap P_2 \cap \ldots \cap P_m) \cap (Q_1 \cap Q_2 \cap \ldots \cap Q_r)$ is an IFS given as $H = \{(y, \delta_{H}(y), \gamma_{H}(y)) | y \in Y\}$, where

$$\delta_{H}(y) = \min_{i,j} \{\delta_{P_i}(y), \delta_{Q_j}(y)\}$$

and

$$\gamma_{H}(y) = \max_{i,j} \{\gamma_{P_i}(y), \gamma_{Q_j}(y)\}.$$

The optimal result of the decision making model is to obtain an $y^* \in Y$ such that $S_H(y^*) = \max_{y \in Y} S_H(y^*)$, which is,

$$S_H(y^*) = \max_{y \in Y} \{\min_{i,j} \{\delta_{P_i}(y), \delta_{Q_j}(y)\} - \max_{i,j} \{\gamma_{P_i}(y), \gamma_{Q_j}(y)\}\}.$$

According to the optimization theory of IFS, we can minimize the degree of rejection and also maximize the degree of acceptance of the I-fuzzy constraints and objectives. Let $\lambda = \max_{i,j} \{\gamma_{P_i}(y), \gamma_{Q_j}(y)\}$ and $\zeta = \min_{i,j} \{\delta_{P_i}(y), \delta_{Q_j}(y)\}$ represent the maximal degree of rejection and the minimal degree of acceptance, respectively. Therefore, the I-fuzzy decision model is converted to the following crisp optimization model [47] as follows:

$$\begin{align*}
\max \{\zeta - \lambda\} \\
\text{s. t.} \quad \begin{cases}
\delta_{P_i}(y) \geq \zeta; & i = 1, 2, \ldots, m, \\
\gamma_{P_i}(y) \leq \lambda; & i = 1, 2, \ldots, m, \\
\delta_{Q_j}(y) \geq \zeta; & j = 1, 2, \ldots, r, \\
\gamma_{Q_j}(y) \leq \lambda; & j = 1, 2, \ldots, r, \\
\zeta \geq \lambda \geq 0, & \\
\zeta + \lambda \leq 1, y \in Y.
\end{cases}
\end{align*}$$

(16)

Dubey et al. [48] implemented Yager’s [49] idea of using an indeterminacy resolving function in the optimization models with interval uncertainty described by IFSs. We briefly discuss Dubey et al. [48] approach for solving optimization models with I-fuzzy environment.

First, we obtain the resolving indeterminacy function for each IFS associated with each goal. Then, for $i = 1, 2, \ldots, m,$

$$g_{P_i}(\sigma, y) = (1 - \sigma) \delta_{P_i}(y) + \sigma \left(1 - \gamma_{P_i}(y)\right), y \in Y.$$

Then, we obtain the resolving indeterminacy function for each IFS associated with each constraint. Then, for $j = 1, 2, \ldots, r,$
\[
g_{\bar{q}}(\sigma, y) = (1 - \sigma) \delta_{\bar{q}}(y) + \sigma \left(1 - \gamma_{\bar{q}}(y)\right), y \in Y.
\]

The I-fuzzy decision set \( \bar{H} \) thus gets converted into a fuzzy set \( \bar{H} \) expressed as follows:
\[
\bar{H} = \{(y, g_{\bar{H}}(\sigma, y), 1 - g_{\bar{H}}(\sigma, y)) | y \in Y\},
\]
where,
\[
g_{\bar{H}}(\sigma, y) = \min_{i,j} \{g_{\bar{P}}(\sigma, y), g_{\bar{Q}}(\sigma, y) | y \in Y\}.
\]

Therefore, \( y^* \in Y \) is the optimal decision, when \( g_{\bar{H}}(\sigma, y^*) = \max_{y \in Y} g_{\bar{H}}(\sigma, y) \), which is \( g_{\bar{H}}(\sigma, y^*) \geq g_{\bar{H}}(\sigma, y), \forall y \in Y \).

Then solving an I-fuzzy optimization model is equivalent to solving the following model:
\[
\max_{(\sigma, y)} \min_{i,j} \{g_{\bar{P}}(\sigma, y), g_{\bar{Q}}(\sigma, y) | y \in Y\},
\]
or
\[
\max\{\xi\}
\begin{align*}
&g_{\bar{P}}(\sigma, y) \geq \xi; \quad i = 1,2, \ldots, m, \\
&g_{\bar{Q}}(\sigma, y) \geq \xi; \quad j = 1,2, \ldots, r, \\
&0 \leq \xi, \sigma \leq 1, \\
&y \in Y.
\end{align*}
\]

(17)

4.2. Interpretation of I-Fuzzy Inequalities

Aggarwal et al. [22] discussed the inequality relations of IFSs in the optimistic and pessimistic sense. Suppose \( y, \ b \in \mathbb{R} \) and let \( c_0, d_0(>0) \in \mathbb{R} \), then the I-fuzzy sentence \( y \geq_{IF} c_0, d_0 b \) to be read as \( "y \) is greater than or equal to \( b \) with tolerances \( c_0 \) and \( d_0 \)“, and is represented in terms of the following membership function:
\[
\delta(y) = \begin{cases} 
1, & \text{if } y \geq b \\
1 - \frac{b - y}{c_0}, & \text{if } b - c_0 < y < b \\
0, & \text{if } y \leq b - c_0.
\end{cases}
\]

(18)

The non-membership functions in the optimistic and pessimistic sense are described as follows:
\[
\gamma_{\text{optimistic}}(y) = \begin{cases} 
0, & \text{if } y \geq b \\
1 - \frac{y - b + c_0 + d_0}{c_0 + d_0}, & \text{if } b - c_0 - d_0 \leq y \leq b \\
1, & \text{if } y \leq b - c_0 - d_0.
\end{cases}
\]

(19)

This function is depicted in Figure 1.
This function is depicted in Figure 2.

\[
Y_{\text{pessimistic}}(y) = \begin{cases} 
0, & \text{if } y \geq b - c_0 + d_0 \\
1 - \frac{y - b + c_0}{d_0}, & \text{if } b - c_0 < y < b - c_0 + d_0 \\
1, & \text{if } y \leq b - c_0
\end{cases}
\]  

(20)

This function is depicted in Figure 2.

The I-fuzzy inequality \( y \leq_{IF} c_0, d_0 \) \( b \) is equivalent to \((-) \leq_{IF} c_0, d_0 \) \((-) \) \( b \).

5. Mathematical Model of Multi-criteria Zero-sum Matrix Games with I-Fuzzy Goals

In this section, we consider a zero sum multi-objective game problem with I-fuzzy goals. We introduce I-fuzzy goals to describe imprecision of information in decision making problems.

Let us consider multi criteria zero sum matrix games with I-fuzzy goals as follows. Suppose that \( S^X \), \( S^Y \) be the strategy sets for player I and player II, respectively, and \( B^n = \left[ b^n_{ij}\right]_{i,j=1}^{m,n} \) \((i = 1,2, ..., \kappa, j = 1,2, ..., \ell )\) is the payoff matrix corresponding to the \( n^{th} \) criterion, \( n = 1,2, ..., s \). Let \( V^n_0 \) and \( W^n_0 \) express the levels of aspiration for player I and player II, respectively. Then, the multi criteria zero sum matrix games with I-fuzzy goals, denoted by \( \text{MOIFG} = (S^X, S^Y, B^n, V^n_0, \geq_{IF}; W^n_0, \leq_{IF}, (n = 1,2, ..., s)) \), where \( \geq_{IF} \) and \( \leq_{IF} \) are the I-fuzzy version of ' \( \geq \)' and ' \( \leq \)', respectively. The multi criteria zero sum matrix games with I-fuzzy goals is often said to be the I-fuzzy multi criteria matrix games for short.

Now player I problem is to obtain \( y \in S^X \) such that:

\[
y^T B^n_f z \geq_{IF} V^n_0, \forall z \in S^Y
\]

For player II problem is to obtain \( z \in S^Y \) such that:

\[
y^T B^n_f z^* \leq_{IF} W^n_0, \forall y \in S^X
\]
Since $S^X$ and $S^f$ are convex polytopes, it is necessary to use only the extreme points of $S^X$ and $S^f$. Then, solving multi-objective I-fuzzy games (MOIFG) is equivalent to solving the two multi-objective I-fuzzy programming models (MOIFG – I) and (MOIFG – II) for player I and player II, respectively.

\[(\text{MOIFG – I}) \quad \text{Find } y \in S^X \text{ such that} \]
\[y^T B^n_j \geq_\text{IF} v^n_0, \forall z \in S^f, \quad (j = 1, ..., \ell). \quad (21)\]

where $B^n_j$ represent the $j$th column of $B^n$.

\[(\text{MOIFG – II}) \quad \text{Find } z \in S^f \text{ such that} \]
\[B^n_iz^* \leq_\text{IF} w^n_0, \forall y \in S^X, \quad (i = 1, ..., \kappa). \quad (22)\]

where $B^n_i$ represent the $i$th row of $B^n$.

6. Resolving Indeterminacy Approach

In this section, we explain the optimistic and pessimistic approaches for solving multi-criteria zero-sum matrix games with I-fuzzy goals through using resolving indeterminacy functions and the Inuiguchi et al. [42] algorithm.

6.1. Optimistic Approach

The player in this approach has optimistic attitude which mean that the player has a hesitation for rejection. Let $c^n_0$ and $d^n_0$, respectively, express the tolerance level pre-specified by Player I for rejecting or accepting the level of aspiration $v_0^n$ related to $n$th criteria. Suppose $g^n_j(\sigma, B^n_0)$, $j = 1, ..., \ell$, $n = 1, ..., s$ be the resolving indeterminacy functions related to $n$th criteria. Similarly, $e^n_0$ and $r^n_0$ be the tolerance level pre-specified by Player II for rejecting or accepting the level of aspiration $w^n_0$ related to $n$th criteria. Suppose $h^n_0(\sigma, B^n_0 z^*), i = 1, ..., \kappa$, $n = 1, ..., s$ is the resolving indeterminacy functions related to $n$th criteria.

6.1.1. Optimization Model for Player I

The membership and non-membership functions for Player I for the I-fuzzy inequalities $y^T B^n_j \geq_\text{IF} c^n_0, d^n_0 v^n_0$ are described as follows:

\[u^n_j(y^T B^n) = \begin{cases} 0, & y^T B^n \leq v^n_0 - c^n_0, \\ 1 + \frac{y^T B^n - v^n_0}{c^n_0}, & v^n_0 - c^n_0 \leq y^T B^n \leq v^n_0, \\ 1, & y^T B^n \geq v^n_0, \end{cases} \]

and

\[\mu^n_j(y^T B^n) = \begin{cases} 1, & y^T B^n \leq v^n_0 - c^n_0 - d^n_0, \\ 1 - \frac{y^T B^n - (v^n_0 - c^n_0 - d^n_0)}{c^n_0 + d^n_0}, & v^n_0 - c^n_0 - d^n_0 \leq y^T B^n \leq v^n_0, \\ 0, & y^T B^n \geq v^n_0. \end{cases} \]

**Definition 14.** For a strategy $y \in S^X$, the player’s I-fuzzy security level corresponding to $n$th payoff matrix is given by:

\[\gamma^n(y) = \min_{15fse}(u^n_j(y^T B^n), \mu^n_j(y^T B^n)), \]

i.e.,

\[\gamma^n(y) = \left( \min_{15fse} u^n_j(y^T B^n), \max_{15fse} \mu^n_j(y^T B^n) \right). \]

**Definition 15.** The strategy $y^* \in S^X$ is called I-fuzzy Pareto optimal security strategy (IFPOSS) of player I if there is no $y \in S^X$ such that:
\( y(y) \geq y(y^*) \) and \( y(y) \neq y(y^*) \),

i.e.,

\[
[y_1(y), y_2(y), \ldots, y_s(y)] \geq [y_1(y^*), y_2(y^*), \ldots, y_s(y^*)],
\]

and

\[
[y_1(y), y_2(y), \ldots, y_s(y)] \neq [y_1(y^*), y_2(y^*), \ldots, y_s(y^*)].
\]

If \( y^* \) is an IFPOSS of player I, then his level of security is obtained by \( y^* = y(y^*) \). Then, the pair \((y^*, y^*)\) is defined as a solution of the given zero sum I-fuzzy multi criteria matrix games for player I.

The indeterminacy functions, for \( j = 1, \ldots, \ell \), \( n = 1, \ldots, s \), are given by

\[
g^n_j(y^n, y^n) = \begin{cases} 
0, & y^n J \leq v^n - c^n - d^n \\
\frac{\sigma(y^n J J^n - (v^n J - c^n J - d^n J))}{c^n J + d^n J}, & v^n J - c^n J - d^n J \leq y^n J J^n \leq v^n J - c^n J \\
g^n_{2j} = 1 + \left( y^n J J^n - v^n J \right) \frac{(1 - \sigma) d^n J}{c^n J (c^n J + d^n J)}, & v^n J - c^n J \leq y^n J J^n \leq v^n J \\
1, & y^n J J^n \geq v^n J 
\end{cases}
\]

It is obvious that \( g^n_j(y^n J J^n) \) \( j = 1, \ldots, \ell \), \( n = 1, \ldots, s \) are linear S-shaped piecewise functions with break points of convex type as shown in Figure 3. Using the methodology described in [42] to transform them into linear piecewise functions with break points of concave type (See Appendix A).

Then, using Yang et al. [50] technique for solving \((MOIFG-I)\) for player I is equivalent to the following multi-objective linear programming model.

\[
\max \{ y_1, y_2, \ldots, y_n \} \\
\text{s.t.} \begin{cases} 
g^n_j(y^n J J^n) \geq y_n, & j = 1, \ldots, \ell, \quad n = 1, \ldots, s, \\
e^T y = 1, & n = 1, \ldots, s, \end{cases}
\]

that is,

\[
\max \{ y_1, y_2, \ldots, y_n \} \\
\text{s.t.} \begin{cases} 
\frac{g^n_j}{W^n_{1j}}(y^n J J^n - W^n_{1j}) + g^n_j(W^n_{1j}) \geq y_n, & j = 1, \ldots, \ell, n = 1, \ldots, s, \\
e^T y = 1, & n = 1, \ldots, s, \end{cases}
\]

\[
\max \{ y_1, y_2, \ldots, y_n \} \\
\text{s.t.} \begin{cases} 
\frac{g^n_j}{W^n_{1j}}(y^n J J^n - W^n_{1j}) + g^n_j(W^n_{1j}) \geq y_n, & j = 1, \ldots, \ell, n = 1, \ldots, s, \\
e^T y = 1, & n = 1, \ldots, s, \end{cases}
\]

![Figure 3. Resolving indeterminacy function for player I: optimistic approach.](image-url)
6.1.2. Optimization Model for Player II

Likewise, the membership and non-membership functions for Player II for the I-fuzzy inequalities \( B^n_i z \leq e^n_0, r^n_0 \) \( W^n_0 \) are as follows:

\[
u^n_i(B^n_i z) = \begin{cases} 
1, & B^n_i z \leq W^n_0, \\
1 + \frac{W^n_0 - B^n_i z}{e^n_0}, & W^n_0 \leq B^n_i z \leq W^n_0 + e^n_0, \\
0, & B^n_i z \geq W^n_0 + e^n_0, 
\end{cases}
\]  
(30)

and

\[
\mu^n_i(B^n_i z) = \begin{cases} 
0, & B^n_i z \leq W^n_0, \\
1 + \frac{B^n_i z - (W^n_0 + e^n_0 + r^n_0)}{e^n_0 + r^n_0}, & W^n_0 \leq B^n_i z \leq W^n_0 + e^n_0 + r^n_0, \\
1, & B^n_i z \geq W^n_0 + e^n_0 + r^n_0. 
\end{cases}
\]  
(31)

**Definition 16.** For a strategy \( z \in S^I \), the player’s II I-fuzzy security level corresponding to \( n^{th} \) payoff matrix is given by:

\[
\delta_n(z) = \min_{1 \leq i \leq K} (\nu^n_i(B^n_i z), \mu^n_i(B^n_i z)),
\]

i.e.,

\[
\delta_n(z) = (\min_{1 \leq i \leq K} \nu^n_i(B^n_i z), \max_{1 \leq i \leq K} \mu^n_i(B^n_i z)).
\]

**Definition 17.** The strategy \( z^* \in S^I \) is called I-fuzzy Pareto optimal security strategy (IFPOSS) of player II if there is no \( z \in S^I \) such that:

\[
\delta(z) \geq \delta(z^*) \text{ and } \delta(z) \neq \delta(z^*),
\]

i.e.,

\[
[\delta_1(z), \delta_2(z), ..., \delta_s(z)] \geq [\delta_1(z^*), \delta_2(z^*), ..., \delta_s(z^*)],
\]

and

\[
[\delta_1(z), \delta_2(z), ..., \delta_s(z)] \neq [\delta_1(z^*), \delta_2(z^*), ..., \delta_s(z^*)].
\]

If \( z^* \) is a IFPOSS of player II, then his level of security is obtained by \( \delta^* = \delta(z^*) \). Then, the pair \((z^*, \delta^*)\) is defined as a solution of the given zero sum I-fuzzy multi criteria matrix games for player II.

The indeterminacy functions, for \( i = 1, ..., K, n = 1, ..., s \) are given by

\[
h_i^n(\sigma, B^n_i z) = \begin{cases} 
1, & B^n_i z \leq W^n_0, \\
h_{11} = \frac{1}{1 + (B^n_i z - W^n_0)(e^n_0 + (1 - \sigma)r^n_0/e^n_0 + r^n_0)}, & W^n_0 \leq B^n_i z \leq W^n_0 + e^n_0, \\
h_{12} = \frac{\sigma(W^n_0 + e^n_0 + r^n_0 - B^n_i z)}{e^n_0 + r^n_0}, & W^n_0 + e^n_0 \leq B^n_i z \leq W^n_0 + e^n_0 + r^n_0, \\
0, & B^n_i z \geq W^n_0 + e^n_0 + r^n_0. 
\end{cases}
\]  
(34)

It is obvious that \( h_i^n(B^n_i z) i = 1, ..., K, n = 1, ..., s \) are linear S-shaped piecewise functions with break points of convex type as shown in Figure 4. Using the methodology described in [42] to transform them into linear piecewise functions with break points of concave type (See Appendix B). Then, using the technique of Yang et al. [50] for solving (MOIFG-II) for player II is equivalent to the following multi-objective linear programming model.
that is,

\[
\max \{\delta_1, \delta_2, \ldots, \delta_n\}
\]

\[
\begin{align*}
\text{s.t.} \quad & \left\{ \begin{array}{l}
h_1^n(B^*_1 z) \geq \delta_n, \quad i = 1, \ldots, K, \quad n = 1, \ldots, s, \\
\rho^n_{11}(B^n_1 z - v^n_{1,1}) + h_1^n(v^n_{1,1}) \geq \delta_n, \quad i = 1, \ldots, K, \quad n = 1, \ldots, s, \\
e^T z = 1, \\
z \geq 0, \delta_n \in [0,1], \quad n = 1, \ldots, s,
\end{array} \right.
\end{align*}
\]

(35)

\[
\max \{\delta_1, \delta_2, \ldots, \delta_n\}
\]

\[
\begin{align*}
\text{s.t.} \quad & \left\{ \begin{array}{l}
\rho^n_{11}(B^n_1 z - v^n_{1,1}) + h_1^n(v^n_{1,1}) \geq \delta_n, \quad i = 1, \ldots, K, \quad n = 1, \ldots, s, \\
\rho^n_{22}(B^n_2 z - v^n_{2,2}) + h_2^n(v^n_{2,2}) \geq \delta_n, \quad i = 1, \ldots, K, \quad n = 1, \ldots, s, \\
e^T z = 1, \\
z \geq 0, \delta_n \in [0,1], \quad n = 1, \ldots, s.
\end{array} \right.
\end{align*}
\]

(36)

6.2. Pessimistic Approach

The player in this approach has a pessimistic attitude toward acceptance amounting to saying that a complete rejection of a criterion does not mean its full acceptance. Let \(c^n\) and \(d^n\) respectively, express the tolerance level pre-specified by Player I for rejecting or accepting the level of aspiration \(V_0^n\) related to \(n^{th}\) criteria. Suppose \(g^n_{ij}(\sigma, B^n_1 y), i = 1, \ldots, \ell, n = 1, \ldots, s\) be the resolving indeterminacy functions related to \(n^{th}\) criteria. Similarly, let \(e^n\) and \(r^n\) be the tolerance level pre-specified by Player II for rejecting or accepting the level of aspiration \(W^n_0\) related to \(n^{th}\) criteria. Suppose \(h^n_{ij}(\sigma, B^n z), i = 1, \ldots, K, n = 1, \ldots, s\) is the resolving indeterminacy functions related to \(n^{th}\) criteria.

6.2.1. Optimization Model for Player I

The membership and non- membership functions for Player I for the I-fuzzy inequalities \(y^T B^n_j \geq c^n_{\alpha_0, d^n_0} V^n_0\) are as follows:

\[
u^n_{\alpha}(y^T B^n_j) = \begin{cases} 
0, & y^T B^n_j \leq V^n_0 - c^n, \\
1 + \frac{y^T B^n_j - V^n_0}{c^n_0 - c^n}, & V^n_0 - c^n \leq y^T B^n_j \leq V^n_0, \\
1, & y^T B^n_j \geq V^n_0,
\end{cases}
\]

(37)

and
\[ \mu^n_i(y^TB^n_i) = \begin{cases} 
1, & y^TB^n_i \leq V^n_0 - c^n_0, \\
1 - \frac{y^TB^n_i - (V^n_0 - c^n_0)}{d^n_0}, & V^n_0 - c^n_0 \leq y^TB^n_i \leq V^n_0 - c^n_0 + d^n_0, \\
0, & y^TB^n_i \geq V^n_0 - c^n_0 + d^n_0. 
\end{cases} \] 

The indeterminacy functions, for \( j = 1, \ldots, \ell, n = 1, \ldots, s \), are given by

\[ g^n_j(\sigma, y^TB^n) = \begin{cases} 
0, & y^TB^n_j \leq V^n_0 - c^n_0, \\
\sigma c^n_j + (1 - \sigma) d^n_0 \left( 1 + \frac{y^TB^n_j - V^n_0}{c^n_0} \right), & V^n_0 - c^n_0 \leq y^TB^n_j \leq V^n_0 - c^n_0 + d^n_0, \\
g^n_{2j} = 1 + (1 - \sigma) \frac{y^TB^n_j - V^n_0}{c^n_0}, & V^n_0 - c^n_0 + d^n_0 \leq y^TB^n_j \leq V^n_0, \\
1, & y^TB^n_j \geq V^n_0. 
\end{cases} \] 

It is clear that \( g^n_j(y^TB^n) \) \( j = 1, \ldots, \ell, n = 1, \ldots, s \) are linear piecewise functions with break points of concave type as shown in Figure 5. Then, using Yang et al. [50] technique for solving (MOIFG-I) for player I is equivalent to the following multi-objective linear programming model.

\[
\begin{align*}
\max \{ y_1, y_2, \ldots, y_n \} \\
s.t. \quad \min \left\{ \sigma c^n_j + (1 - \sigma) d^n_0 \left( 1 + \frac{y^TB^n_j - V^n_0}{c^n_0} \right) \right\} \geq y_n, \quad j = 1, \ldots, \ell, n = 1, \ldots, s, \\
\quad 1 + (1 - \sigma) \frac{y^TB^n_j - V^n_0}{c^n_0} \geq y_n, \quad j = 1, \ldots, \ell, n = 1, \ldots, s, \\
\quad e^T y = 1, \\
\quad y \geq 0, y_n \in [0,1], \quad n = 1, \ldots, s.
\end{align*}
\]

**Figure 5.** Resolving indeterminacy function for player I: pessimistic approach.

### 6.2.2. Optimization Model for Player II

Likewise, the membership and non-membership functions for Player II for the I-fuzzy inequalities \( B^n_i z \leq e^n_i, r^n_i \ W^n_0 \) are as follows:

\[ u^n_i(B^n_i z) = \begin{cases} 
1, & B^n_i z \leq W^n_0, \\
1 + \frac{W^n_0 - B^n_i z}{e^n_0}, & W^n_0 \leq B^n_i z \leq W^n_0 + e^n_0, \\
0, & B^n_i z \geq W^n_0 + e^n_0. 
\end{cases} \] 

and

\[ \mu^n_i(B^n_i z) = \begin{cases} 
0, & B^n_i z \leq W^n_0 + e^n_0 - r^n_0, \\
1 + \frac{B^n_i z - (W^n_0 + e^n_0)}{r^n_0}, & W^n_0 + e^n_0 - r^n_0 \leq B^n_i z \leq W^n_0 + e^n_0, \\
1, & B^n_i z \geq W^n_0 + e^n_0. 
\end{cases} \]
The indeterminacy functions, for \( i = 1, \ldots, K, \ n = 1, \ldots, s \) are given by

\[
h_i^n(B^n z) = \begin{cases} 
1, & B^n z \leq W^n_0, \\
1 + (1 - \sigma) \frac{W^n_0 - B^n z}{e^n_0}, & W^n_0 \leq B^n z \leq W^n_0 + e^n_0 - r^n_0, \\
\sigma \frac{e^n_0 + (1 - \sigma) r^n_0}{r^n_0} \left( 1 + \frac{W^n_0 - B^n z}{e^n_0} \right), & W^n_0 + e^n_0 - r^n_0 \leq B^n z \leq W^n_0 + e^n_0, \\
0, & B^n z \geq W^n_0 + e^n_0. 
\end{cases}
\] (43)

It is clear that \( h_i^n(B^n z) \ i = 1, \ldots, K, \ n = 1, \ldots, s \) are linear piecewise functions with break points of concave type as shown in Figure 6. Then, using Yang et al. [50] technique for solving (MOIFG-II) for player II is equivalent to the following multi-objective linear programming model.

\[
\max \{\delta_1, \delta_2, \ldots, \delta_n\} \quad \begin{cases} 
1 + (1 - \sigma) \frac{W^n_0 - B^n z}{e^n_0} \geq \delta_n, & i = 1, \ldots, K, \ n = 1, \ldots, s, \\
\sigma \frac{e^n_0 + (1 - \sigma) r^n_0}{r^n_0} \left( 1 + \frac{W^n_0 - B^n z}{e^n_0} \right) \geq \delta_n, & i = 1, \ldots, K, \ n = 1, \ldots, s, \\
z \geq 0, \delta_n \in [0,1], & n = 1, \ldots, s. 
\end{cases}
\] (44)

**Figure 6.** Resolving indeterminacy function for player II: pessimistic approach.

Figure 7 presents a flowchart of the proposed approach, i.e., resolving indeterminacy approach for solving multi-criteria zero-sum matrix games with I-fuzzy goals.
Figure 7. The flowchart of the proposed algorithm.

7. Numerical Examples and Computational Result Comparison

To illustrate the validity and applicability of the proposed approach, we present two practical numerical experiments. First of all, we consider the market share competition problem of Campos [51]. We use GAMS software [43] for solving all the multi-objective linear programming models.

7.1. Example 1

Suppose that there are two companies Q1 and Q2 aiming to enhance the sales amount and market share of a product in a targeted market under the circumstance that the demand amount of the product in the targeted market basically is fixed. In other words, the sales amount and market share of one company are increased while the sales amount and market share of another company are decreased. The two companies consider two different strategies to increase the sales amount and market share: strategy I (to reduce the price), strategy II (advertisement).
The above problem may be regarded as I-fuzzy multi-objective matrix game. Namely, the companies Q1 and Q2 are considered as Players I and II, respectively. Due to a lack of information or the imprecision of the available information, the managers of the two companies usually are not able to exactly forecast the sales amount of the companies. They can estimate the sales amount with a certain confidence degree, but it is possible that they are not so sure about it. Thus, there may be hesitation about the estimation of the sales amount. In order to handle the uncertain situation the I-fuzzy numbers are used. The marketing research department of company Q1 establishes the following payoff matrices.

\[ B^1 = \begin{pmatrix} 175 & 150 \\ 80 & 175 \end{pmatrix}, \quad B^2 = \begin{pmatrix} 125 & 120 \\ 120 & 150 \end{pmatrix}. \]

Let the level of aspiration for player I and player II related to \( n \)th criteria be \( W_0^1 = 164, W_0^2 = 100 \) and \( W_1^1 = 159, W_1^2 = 135 \), respectively. Suppose tolerances for player I and player II related to \( n \)th criteria be \( d_1^1 = 16, c_2^1 = 10, d_2^1 = 11, d_2^2 = 5 \) and \( e_1^2 = 19, e_2^2 = 13, r_1^1 = 11, r_2^2 = 7 \), respectively. We will solve the multi criteria zero-sum matrix games with I-fuzzy goals by both pessimistic and optimistic approaches when \( \sigma = \frac{1}{2} \).

7.1.1. Optimistic Approach

The resolving indeterminacy functions in optimistic framework of (MOIFG-I) for player I are defined as follows:

\[
g_1^1(175y_1 + 80y_2) = \begin{cases} 0, & 175y_1 + 80y_2 \leq 137, \\ \frac{1}{54} (175y_1 + 80y_2 - 137), & 137 \leq 175y_1 + 80y_2 \leq 148, \\ 1 + \frac{43}{864} (175y_1 + 80y_2 - 164), & 148 \leq 175y_1 + 80y_2 \leq 164, \\ 175y_1 + 80y_2 \geq 164, \end{cases} \tag{45}
\]

\[
g_2^1(150y_1 + 175y_2) = \begin{cases} 0, & 150y_1 + 175y_2 \leq 137, \\ \frac{1}{54} (150y_1 + 175y_2 - 137), & 137 \leq 150y_1 + 175y_2 \leq 148, \\ 1 + \frac{43}{864} (150y_1 + 175y_2 - 164), & 148 \leq 150y_1 + 175y_2 \leq 164, \\ 150y_1 + 175y_2 \geq 164, \end{cases} \tag{46}
\]

\[
g_1^2(125y_1 + 120y_2) = \begin{cases} 0, & 125y_1 + 120y_2 \leq 85, \\ \frac{1}{30} (125y_1 + 120y_2 - 85), & 85 \leq 125y_1 + 120y_2 \leq 90, \\ 1 + \frac{25}{300} (125y_1 + 120y_2 - 100), & 90 \leq 125y_1 + 120y_2 \leq 100, \\ 125y_1 + 120y_2 \geq 100, \end{cases} \tag{47}
\]

\[
g_2^2(120y_1 + 150y_2) = \begin{cases} 0, & 120y_1 + 150y_2 \leq 85, \\ \frac{1}{30} (120y_1 + 150y_2 - 85), & 85 \leq 120y_1 + 150y_2 \leq 90, \\ 1 + \frac{25}{300} (120y_1 + 150y_2 - 100), & 90 \leq 120y_1 + 150y_2 \leq 100, \\ 120y_1 + 150y_2 \geq 100, \end{cases} \tag{48}
\]

Here, the resolving indeterminacy functions \( g_1^1(175y_1 + 80y_2), g_2^1(150y_1 + 175y_2), g_1^2(125y_1 + 120y_2) \) and \( g_2^2(120y_1 + 150y_2) \) are linear S-shaped piecewise function with break points of convex type. We follow the methodology of Inuiguichi et al. [42] (See Appendix C) to transform them into linear piecewise function with break points of concave type as follows:

\[
g_1^{1'}(175y_1 + 80y_2) = \begin{cases} 0, & 175y_1 + 80y_2 \leq 137, \\ \frac{1}{27} (175y_1 + 80y_2 - 137), & 137 \leq 175y_1 + 80y_2 \leq 164, \\ 175y_1 + 80y_2 \geq 164, \end{cases} \tag{49}
\]
The equivalent multi-objective linear programming model of player I is:

\[
\max \{y_1, y_2\} \\
\begin{align*}
175y_1 + 80y_2 - 137 &\geq 27y_1, \\
150y_1 + 175y_2 - 137 &\geq 27y_1, \\
125y_1 + 120y_2 - 85 &\geq 15y_2, \\
120y_1 + 150y_2 - 85 &\geq 15y_2, \\
y_1 + y_2 &\leq 1, \\
0 &\leq y_1, y_2 \leq 1, \\
y_1, y_2 &\geq 0.
\end{align*}
\]

Solving the above model yields a good payoff for Player I by using the optimistic approach as shown in Table 1.

| #   | \(y_1^*\) | \(y_2^*\) | \(Y_1\) | \(Y_2\) |
|-----|----------|----------|----------|----------|
| 1   | 0.7917   | 0.2083   | 0.6743   | 1        |
| 2   | 0.8147   | 0.1803   | 0.6626   | 1.0249   |
| 3   | 0.925    | 0.1443   | 0.6408   | 1.041    |
| 4   | 0.983    | 0.1163   | 0.6259   | 1.0695   |

In the same analysis to that of player I, the resolving indeterminacy functions with break points of concave type for player II are obtained as follows:

\[
h^1_1(175z_1 + 150z_2) = \begin{cases} 
0, & 175z_1 + 150z_2 \geq 189, \\
\frac{-1}{30}(175z_1 + 150z_2 - 189), & 159 \leq 175z_1 + 150z_2 \leq 189, \\
1, & 175z_1 + 150z_2 \leq 159,
\end{cases}
\]

\[
h^1_2(80z_1 + 175z_2) = \begin{cases} 
0, & 80z_1 + 175z_2 \geq 189, \\
\frac{-1}{30}(80z_1 + 175z_2 - 189), & 159 \leq 80z_1 + 175z_2 \leq 189, \\
1, & 80z_1 + 175z_2 \leq 159,
\end{cases}
\]

\[
h^2_1(125z_1 + 120z_2) = \begin{cases} 
0, & 125z_1 + 120z_2 \geq 155, \\
\frac{-1}{20}(125z_1 + 120z_2 - 155), & 135 \leq 125z_1 + 120z_2 \leq 155, \\
1, & 125z_1 + 120z_2 \leq 135,
\end{cases}
\]

\[
h^2_2(120z_1 + 150z_2) = \begin{cases} 
0, & 120z_1 + 150z_2 \geq 155, \\
\frac{-1}{20}(120z_1 + 150z_2 - 155), & 135 \leq 120z_1 + 150z_2 \leq 155, \\
1, & 120z_1 + 150z_2 \leq 135.
\end{cases}
\]
The equivalent multi-objective linear programming model of player II is

\[
\begin{align*}
\max \{ \delta_1, \delta_2 \} \\
\text{s. t.} & \\
-80z_1 - 175z_2 + 189 & \geq 30\delta_1, \\
-175z_1 - 150z_2 + 189 & \geq 30\delta_1, \\
-125z_1 - 120z_2 + 155 & \geq 20\delta_2, \\
-120z_1 - 150z_2 + 155 & \geq 20\delta_2, \\
z_1 + z_2 &= 1, \\
0 & \leq \delta_1, \delta_2 \leq 1, \\
z_1, z_2 & \geq 0.
\end{align*}
\]  

(58)

Solving the above model yields a good payoff for Player II by using the optimistic approach as shown in Table 2.

**Table 2.** I-fuzzy optimal securities and strategies for player II using optimistic approach.

| # | \(z_1^*\) | \(z_2^*\) | \(\delta_1\) | \(\delta_2\) |
|---|---|---|---|---|
| 1 | 0.36 | 0.64 | 1 | 0.79 |
| 2 | 0.374 | 0.626 | 0.9883 | 0.811 |
| 3 | 0.388 | 0.612 | 0.976 | 0.832 |
| 4 | 0.402 | 0.598 | 0.965 | 0.853 |

7.1.2. Pessimistic Approach

The equivalent multi-objective linear programming model of player I is

\[
\begin{align*}
\max \{ y_1, y_2 \} \\
\text{s. t.} & \\
4725y_1 + 2160y_2 - 3996 & \geq 352y_1, \\
4050y_1 + 4725y_2 - 3996 & \geq 352y_1, \\
1875y_1 + 1800y_2 - 1350 & \geq 100y_2, \\
1800y_1 + 2250y_2 - 1350 & \geq 100y_2, \\
175y_1 + 80y_2 - 132 & \geq 32y_1, \\
150y_1 + 175y_2 - 132 & \geq 32y_1, \\
125y_1 + 120y_2 - 80 & \geq 20y_2, \\
120y_1 + 150y_2 - 80 & \geq 20y_2, \\
y_1 + y_2 &= 1, \\
0 & \leq y_1, y_2 \leq 1, \\
y_1, y_2 & \geq 0.
\end{align*}
\]  

(59)

Solving the above model yields a good payoff for Player I by using the pessimistic approach as shown in Table 3.

**Table 3.** I-fuzzy optimal securities and strategies for player I using pessimistic approach.

| # | \(y_1^*\) | \(y_2^*\) | \(Y_1\) | \(Y_2\) |
|---|---|---|---|---|
| 1 | 0.8316 | 0.3291 | 0.5529 | 1 |
| 2 | 0.941 | 0.3011 | 0.541 | 1.0359 |
| 3 | 0.962 | 0.2621 | 0.5157 | 1.0526 |
| 4 | 0.991 | 0.2331 | 0.4874 | 1.0955 |

The equivalent multi-objective linear programming model of player II is
\[
\begin{align*}
\text{max } \{\delta_1, \delta_2\} \\
-175z_1 - 150z_2 + 197 \geq 38\delta_1, \\
-80z_1 - 175z_2 + 197 \geq 38\delta_1, \\
-125z_1 - 120z_2 + 161 \geq 26\delta_2, \\
-120z_1 - 150z_2 + 161 \geq 26\delta_2, \\
-5250z_1 - 4500z_2 + 5340 \geq 418\delta_1, \\
-2400z_1 - 5250z_2 + 5340 \geq 418\delta_1, \\
-2500z_1 - 2400z_2 + 2960 \geq 182\delta_2, \\
-2400z_1 - 3000z_2 + 2960 \geq 182\delta_2, \\
z_1 + z_2 = 1, \\
0 \leq \delta_1, \delta_2 \leq 1, \\
z_1, z_2 \geq 0.
\end{align*}
\]

Solving the above model yields a good payoff for Player II by using the pessimistic approach as shown in Table 4.

### Table 4. I-fuzzy optimal securities and strategies for player II using pessimistic approach.

| z | \(z_1^*\) | \(z_2^*\) | \(\delta_1\) | \(\delta_2\) |
|---|---|---|---|---|
| 1 | 0.472 | 0.556 | 0.9447 | 0.9354 |
| 2 | 0.458 | 0.542 | 0.9355 | 0.9515 |
| 3 | 0.472 | 0.528 | 0.9263 | 0.9676 |
| 4 | 0.486 | 0.514 | 0.9171 | 0.9838 |

Next, we introduce another important real-life example, which was discussed by Cook [5] and also examined by Nishizaki et al. [10]. It is suitably modified to illustrate the proposed algorithm.

#### 7.2. Example 2

Consider the payoff matrices for the multi criteria zero-sum matrix games as follows:

\[
B^1 = \begin{pmatrix} 2 & 5 & 1 \\ -1 & -2 & 6 \end{pmatrix}, B^2 = \begin{pmatrix} -3 & 7 & 2 \\ 0 & -2 & 0 \end{pmatrix}, B^3 = \begin{pmatrix} 8 & 2 & 3 \\ -5 & 6 & 0 \end{pmatrix}
\]

as the productivity matrix, the cost matrix and the time matrix, respectively. Let the level of aspiration for player I and player II related to \(n^{th}\) criteria be \(V^0_1 = 6, V^0_2 = 7, V^0_3 = 8\) and \(W^0_1 = -2, W^0_2 = -3, W^0_3 = -5\), respectively. Suppose tolerances for player I and player II related to \(n^{th}\) criteria be \(c^1_0 = 8, c^2_0 = 10, c^3_0 = 13, d^1_0 = 1, d^2_0 = 4, d^3_0 = 10\) and \(e^1_0 = 8, e^2_0 = 10, e^3_0 = 13, r^1_0 = 6, r^2_0 = 4, r^3_0 = 7\), respectively. We will solve the multi criteria zero-sum matrix games with I-fuzzy goals by both pessimistic and optimistic approaches when \(\sigma = \frac{1}{2}\).

#### 7.2.1. Optimistic Approach

The resolving indeterminacy functions in optimistic framework of (MOIFG-I) for player I are defined as follows:

\[
g^1_1(2y_1 - y_2) = \begin{cases} 
0, & 2y_1 - y_2 \leq -3, \\
\frac{1}{18}(2y_1 - y_2 + 3), & -3 \leq 2y_1 - y_2 \leq -2, \\
1 + \frac{17}{144}(2y_1 - y_2 - 6), & -2 \leq 2y_1 - y_2 \leq 6, \\
2y_1 - y_2 \geq 6, & \end{cases}
\]

\[
g^1_2(5y_1 - 2y_2 + 3y_3) = \begin{cases} 
0, & 5y_1 - 2y_2 + 3y_3 \leq -3, \\
\frac{1}{18}(5y_1 - 2y_2 + 3y_3 + 3), & -3 \leq 5y_1 - 2y_2 + 3y_3 \leq -2, \\
1 + \frac{17}{144}(5y_1 - 2y_2 + 3y_3 - 6), & -2 \leq 5y_1 - 2y_2 + 3y_3 \leq 6, \\
5y_1 - 2y_2 + 3y_3 \geq 6, & \end{cases}
\]
\[
g_1^3(y_1 + 6y_2 - y_3) = \begin{cases} 
0, & y_1 + 6y_2 - y_3 \leq -3, \\
\frac{1}{18}(y_1 + 6y_2 - y_3 + 3), & -3 \leq y_1 + 6y_2 - y_3 \leq -2, \\
\frac{17}{144}(y_1 + 6y_2 - y_3 - 6), & -2 \leq y_1 + 6y_2 - y_3 \leq 6, \\
y_1 + 6y_2 - y_3 \geq 6,
\end{cases}
\]
\[
g_2^3(-3y_1 + 3y_3) = \begin{cases} 
0, & -3y_1 + 3y_3 \leq -7, \\
\frac{1}{28}(-3y_1 + 3y_3 + 7), & -7 \leq -3y_1 + 3y_3 \leq -3, \\
\frac{24}{280}(-3y_1 + 3y_3 - 7), & -3 \leq -3y_1 + 3y_3 \leq 7, \\
y_1 + 3y_3 \geq 7,
\end{cases}
\]
\[
g_3^2(7y_1 - 2y_2 - y_3) = \begin{cases} 
0, & 7y_1 - 2y_2 - y_3 \leq -7, \\
\frac{1}{28}(7y_1 - 2y_2 - y_3 + 7), & -7 \leq 7y_1 - 2y_2 - y_3 \leq -3, \\
\frac{24}{280}(7y_1 - 2y_2 - y_3 - 7), & -3 \leq 7y_1 - 2y_2 - y_3 \leq 7, \\
y_1 - 2y_2 - y_3 \geq 7,
\end{cases}
\]
\[
g_3^2(2y_1 + 6y_3) = \begin{cases} 
0, & 2y_1 + 6y_3 \leq -7, \\
\frac{1}{28}(2y_1 + 6y_3 + 7), & -7 \leq 2y_1 + 6y_3 \leq -3, \\
\frac{24}{280}(2y_1 + 6y_3 - 7), & -3 \leq 2y_1 + 6y_3 \leq 7, \\
y_1 + 6y_3 \geq 7,
\end{cases}
\]
\[
g_3^3(8y_1 - 5y_2 - 3y_3) = \begin{cases} 
0, & 8y_1 - 5y_2 - 3y_3 \leq -15, \\
\frac{1}{46}(8y_1 - 5y_2 - 3y_3 + 15), & -15 \leq 8y_1 - 5y_2 - 3y_3 \leq -5, \\
\frac{36}{598}(8y_1 - 5y_2 - 3y_3 - 8), & -5 \leq 8y_1 - 5y_2 - 3y_3 \leq 8, \\
y_1 - 5y_2 - 3y_3 \geq 8,
\end{cases}
\]
\[
g_3^3(2y_1 + 6y_2+y_3) = \begin{cases} 
0, & 2y_1 + 6y_2+y_3 \leq -15, \\
\frac{1}{46}(2y_1 + 6y_2+y_3 + 15), & -15 \leq 2y_1 + 6y_2+y_3 \leq -5, \\
\frac{36}{598}(2y_1 + 6y_2+y_3 - 8), & -5 \leq 2y_1 + 6y_2+y_3 \leq 8, \\
y_1 + 6y_2+y_3 \geq 8,
\end{cases}
\]
\[
g_3^3(3y_1+6y_3) = \begin{cases} 
0, & 3y_1+6y_3 \leq -15, \\
\frac{1}{46}(3y_1+6y_3 + 15), & -15 \leq 3y_1+6y_3 \leq -5, \\
\frac{36}{598}(3y_1+6y_3 - 8), & -5 \leq 3y_1+6y_3 \leq 8, \\
y_1 + 6y_3 \geq 8.
\end{cases}
\]

Here the resolving indeterminacy functions \(g_1^1(2y_1 - y_2), g_1^1(5y_1 - 2y_2 + 3y_3), g_3^1(y_1 + 6y_2 - y_3), g_2^1(-3y_1 + 3y_3), g_2^2(7y_1 - 2y_2 - y_3), g_3^2(2y_1 + 6y_3), g_3^3(8y_1 - 5y_2 - 3y_3), g_3^2(2y_1 + 6y_2+y_3)\) and \(g_3^3(3y_1+6y_3)\) are linear S-shaped piecewise function with break points of convex type.

We follow Inuiuchi et al.’s methodology [42] (See Appendix D) to transform them into linear piecewise function with break points of concave type as follows:
\[
g_1^3(2y_1 - y_2) = \begin{cases} 
0, & 2y_1 - y_2 \leq -3, \\
\frac{1}{9}(2y_1 - y_2 + 3), & -3 \leq 2y_1 - y_2 \leq 6, \\
y_1 - y_2 \geq 6,
\end{cases}
\]
The equivalent multi-objective linear programming model of player I is

\[
\begin{align*}
\text{max } \{y_1, y_2, y_3\} \\
\begin{cases}
2y_1 - y_2 + 3 \geq 9y_1, \\
5y_1 - 2y_2 + 3y_3 + 3 \geq 9y_1, \\
y_1 + 6y_2 - y_3 + 3 \geq 9y_1, \\
-3y_1 + 3y_3 + 7 \geq 14y_1, \\
7y_1 - 2y_2 - y_3 + 7 \geq 14y_2, \\
2y_1 + 6y_3 + 7 \geq 14y_2, \\
8y_1 - 5y_2 - 3y_3 + 15 \geq 23y_3, \\
2y_1 + 6y_2 + y_3 + 15 \geq 23y_3, \\
3y_1 + 6y_3 + 15 \geq 23y_3, \\
y_1 + y_2 + y_3 = 1, \\
0 \leq y_1, y_2, y_3 \leq 1, \\
y_1, y_2, y_3 \geq 0.
\end{cases}
\end{align*}
\]  

(79)

In the same analysis to that of player I, the resolving indeterminacy functions with break points of concave type for player II are obtained as follows:

\[
\begin{align*}
g_2^1(5y_1 - 2y_2 + 3y_3) &= \begin{cases}
0, & 5y_1 - 2y_2 + 3y_3 \leq -3, \\
\frac{1}{9}(5y_1 - 2y_2 + 3y_3 + 3), & -3 \leq 5y_1 - 2y_2 + 3y_3 \leq 6, \\
1, & 5y_1 - 2y_2 + 3y_3 \geq 6,
\end{cases} \\
g_2^1(y_1 + 6y_2 - y_3) &= \begin{cases}
0, & y_1 + 6y_2 - y_3 \leq -3, \\
\frac{1}{9}(y_1 + 6y_2 - y_3 + 3), & -3 \leq y_1 + 6y_2 - y_3 \leq 6, \\
1, & y_1 + 6y_2 - y_3 \geq 6,
\end{cases} \\
g_2^1(-3y_1 + 3y_3) &= \begin{cases}
0, & -3y_1 + 3y_3 \leq -7, \\
\frac{1}{14}(-3y_1 + 3y_3 + 7), & -7 \leq -3y_1 + 3y_3 \leq 7, \\
1, & -3y_1 + 3y_3 \geq 7,
\end{cases} \\
g_2(7y_1 - 2y_2 - y_3) &= \begin{cases}
0, & 7y_1 - 2y_2 - y_3 \leq -7, \\
\frac{1}{14}(7y_1 - 2y_2 - y_3 + 7), & -7 \leq 7y_1 - 2y_2 - y_3 \leq 7, \\
1, & 7y_1 - 2y_2 - y_3 \geq 7,
\end{cases} \\
g_3^2(2y_1 + 6y_3) &= \begin{cases}
0, & 2y_1 + 6y_3 \leq -7, \\
\frac{1}{14}(2y_1 + 6y_3 + 7), & -7 \leq 2y_1 + 6y_3 \leq 7, \\
1, & 2y_1 + 6y_3 \geq 7,
\end{cases} \\
g_3^3(8y_1 - 5y_2 - 3y_3) &= \begin{cases}
0, & 8y_1 - 5y_2 - 3y_3 \leq -15, \\
\frac{1}{23}(8y_1 - 5y_2 - 3y_3 + 15), & -15 \leq 8y_1 - 5y_2 - 3y_3 \leq 8, \\
1, & 8y_1 - 5y_2 - 3y_3 \geq 8,
\end{cases} \\
g_3^3(2y_1 + 6y_2 + y_3) &= \begin{cases}
0, & 2y_1 + 6y_2 + y_3 \leq -15, \\
\frac{1}{23}(2y_1 + 6y_2 + y_3 + 15), & -15 \leq 2y_1 + 6y_2 + y_3 \leq 8, \\
1, & 2y_1 + 6y_2 + y_3 \geq 8,
\end{cases} \\
g_3^3(3y_1 + 6y_3) &= \begin{cases}
0, & 3y_1 + 6y_3 \leq -15, \\
\frac{1}{23}(3y_1 + 6y_3 + 15), & -15 \leq 3y_1 + 6y_3 \leq 8, \\
1, & 3y_1 + 6y_3 \geq 8.
\end{cases}
\end{align*}
\]  

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\[
\begin{align*}
  h'_1(2z_1 + 5z_2 + z_3) &= \begin{cases}
  0, & 2z_1 + 5z_2 + z_3 \geq 12, \\
  \frac{-1}{14} (2z_1 + 5z_2 + z_3 - 12), & -2 \leq 2z_1 + 5z_2 + z_3 \leq 12, \\
  1, & 2z_1 + 5z_2 + z_3 \leq -2,
\end{cases} \\
  h'_2(-z_1 - 2z_2 + 6z_3) &= \begin{cases}
  0, & -z_1 - 2z_2 + 6z_3 \geq 12, \\
  \frac{-1}{14} (-z_1 - 2z_2 + 6z_3 - 12), & -2 \leq -z_1 - 2z_2 + 6z_3 \leq 12, \\
  1, & -z_1 - 2z_2 + 6z_3 \leq -2,
\end{cases} \\
  h'_3(3z_2 - z_3) &= \begin{cases}
  0, & 3z_2 - z_3 \geq 12, \\
  \frac{-1}{14} (3z_2 - z_3 - 12), & -2 \leq 3z_2 - z_3 \leq 12, \\
  1, & 3z_2 - z_3 \leq -2,
\end{cases} \\
  h''_1(-3z_1 + 7z_2 + 2z_3) &= \begin{cases}
  0, & -3z_1 + 7z_2 + 2z_3 \geq 11, \\
  \frac{-1}{14} (-3z_1 + 7z_2 + 2z_3 - 11), & -3 \leq -3z_1 + 7z_2 + 2z_3 \leq 11, \\
  1, & -3z_1 + 7z_2 + 2z_3 \leq -3,
\end{cases} \\
  h''_2(-2z_2) &= \begin{cases}
  0, & -2z_2 \geq 11, \\
  \frac{-1}{14} (-2z_2 - 11), & -3 \leq -2z_2 \leq 11, \\
  1, & -2z_2 \leq -3,
\end{cases} \\
  h''_3(3z_1 - z_2 + 6z_3) &= \begin{cases}
  0, & 3z_1 - z_2 + 6z_3 \geq 11, \\
  \frac{-1}{14} (3z_1 - z_2 + 6z_3 - 11), & -3 \leq 3z_1 - z_2 + 6z_3 \leq 11, \\
  1, & 3z_1 - z_2 + 6z_3 \leq -3,
\end{cases} \\
  h''_3(8z_1 + 2z_2 + 3z_3) &= \begin{cases}
  0, & 8z_1 + 2z_2 + 3z_3 \geq 15, \\
  \frac{-1}{20} (8z_1 + 2z_2 + 3z_3 - 15), & -5 \leq 8z_1 + 2z_2 + 3z_3 \leq 15, \\
  1, & -8z_1 + 2z_2 + 3z_3 \leq -5,
\end{cases} \\
  h'''_2(-5z_1 + 6z_2) &= \begin{cases}
  0, & -5z_1 + 6z_2 \geq 15, \\
  \frac{-1}{20} (-5z_1 + 6z_2 - 15), & -5 \leq -5z_1 + 6z_2 \leq 15, \\
  1, & -5z_1 + 6z_2 \leq -5,
\end{cases} \\
  h'''_3(-3z_1 + z_2 + 6z_3) &= \begin{cases}
  0, & -3z_1 + z_2 + 6z_3 \geq 15, \\
  \frac{-1}{20} (-3z_1 + z_2 + 6z_3 - 15), & -5 \leq -3z_1 + z_2 + 6z_3 \leq 15, \\
  1, & -3z_1 + z_2 + 6z_3 \leq -5.
\end{cases}
\]

The equivalent multi-objective linear programming model of player II is

\[
\begin{align*}
\max & \{\delta_1, \delta_2, \delta_3\} \\
\text{s.t.} & \begin{cases}
-2z_1 - 5z_2 - z_3 + 12 \geq 14\delta_1, \\
z_1 + 2z_2 + 6z_3 + 12 \geq 14\delta_1, \\
-3z_1 + 3z_2 + 12 \geq 14\delta_1, \\
3z_1 - 7z_2 - 2z_3 + 11 \geq 14\delta_2, \\
2z_2 + 11 \geq 14\delta_2, \\
-3z_1 + z_2 + 6z_3 + 11 \geq 14\delta_2, \\
-8z_1 - 2z_2 - 3z_3 + 15 \geq 20\delta_3, \\
5z_1 - 6z_2 + 15 \geq 20\delta_3, \\
3z_1 - z_2 - 6z_3 + 15 \geq 20\delta_3, \\
z_1 + z_2 + z_3 = 1, \\
0 \leq \delta_1, \delta_2, \delta_3 \leq 1, \\
z_1, z_2, z_3 \geq 0.
\end{cases}
\end{align*}
\]
7.2.2. Pessimistic Approach

The equivalent multi-objective linear programming model of player I is

\[
\begin{align*}
\text{max } & \{ y_1, y_2, y_3 \} \\
\text{s.t. } & \\
18y_1 - 9y_2 + 18 & \geq 16y_1, \\
45y_1 - 18y_2 + 27y_3 & + 18 \geq 16y_1, \\
9y_1 + 54y_2 - 9y_3 & + 18 \geq 16y_1, \\
-42y_1 + 42y_2 + 42 & \geq 80y_2, \\
98y_1 - 28y_2 - 14y_3 & + 42 \geq 80y_2, \\
28y_1 + 84y_3 & + 42 \geq 80y_2, \\
184y_1 - 115y_2 - 69y_3 & + 115 \geq 260y_3, \\
46y_1 + 138y_2 + 23y_3 & + 115 \geq 260y_3, \\
69y_1 + 138y_3 & + 115 \geq 260y_3, \\
2y_1 - y_2 + 10 & \geq 16y_1, \\
5y_1 - 2y_2 + 3y_3 & + 10 \geq 16y_1, \\
y_1 + 6y_2 - y_3 & + 10 \geq 16y_1, \\
-3y_1 + 3y_3 & + 13 \geq 20y_2, \\
7y_1 - 2y_2 - y_3 & + 13 \geq 20y_2, \\
2y_1 + 6y_3 & + 13 \geq 20y_2, \\
8y_1 - 5y_2 - 3y_3 & + 18 \geq 26y_3, \\
2y_1 + 6y_2 + y_3 & + 18 \geq 26y_3, \\
3y_1 + 6y_3 & + 18 \geq 26y_3, \\
y_1 + y_2 + y_3 & = 1, \\
0 & \leq y_1, y_2, y_3 \leq 1, \\
y_1, y_2, y_3 & \geq 0.
\end{align*}
\]

The equivalent multi-objective linear programming model of player II is

\[
\begin{align*}
\text{max } & \{ \delta_1, \delta_2, \delta_3 \} \\
\text{s.t. } & \\
-2z_1 - 5z_2 - z_3 & + 14 \geq 16\delta_1, \\
z_1 + 2z_2 - 6z_3 & + 14 \geq 16\delta_1, \\
-3z_2 + z_3 & + 14 \geq 16\delta_1, \\
3z_1 - 7z_2 - 2z_3 & + 17 \geq 20\delta_2, \\
2z_2 & + 17 \geq 20\delta_2, \\
-3z_1 + z_2 - 6z_3 & + 17 \geq 20\delta_2, \\
-8z_1 - 2z_2 - 3z_3 & + 21 \geq 26\delta_3, \\
5z_1 - 6z_2 & + 21 \geq 26\delta_3, \\
3z_2 - z_3 - 6z_3 & + 21 \geq 26\delta_3, \\
-28z_1 - 70z_2 - 14z_3 & + 94 \geq 96\delta_1, \\
14z_1 + 28z_2 - 84z_3 & + 94 \geq 96\delta_1, \\
-42z_1 + 14z_2 & + 84 \geq 96\delta_1, \\
42z_1 - 98z_2 - 28z_3 & + 98 \geq 985\delta_2, \\
28z_2 & + 98 \geq 985\delta_2, \\
-42z_1 + 14z_2 - 84z_3 & + 98 \geq 80\delta_3, \\
-160z_1 - 40z_2 - 60z_3 & + 160 \geq 182\delta_3, \\
100z_1 - 120z_2 & + 160 \geq 182\delta_3, \\
60z_1 - 20z_2 - 120z_3 & + 160 \geq 182\delta_3, \\
z_1 + z_2 + z_3 & = 1, \\
0 & \leq \delta_1, \delta_2, \delta_3 \leq 1, \\
z_1, z_2, z_3 & \geq 0.
\end{align*}
\]

7.3. Results and Discussion

Nishizaki et al. [10] and Aggarwal et al. [41] discussed the multi criteria matrix game with fuzzy goals. However, the fuzzy set can express the achieving degree of the intended goal for each player in a situation. Due to the subjective uncertainty of players, each player has a certain hesitation degree in achieving the degree of the intended goal. The IFS can simultaneously indicate the degree to which a player has reached the intended goal in a situation and the inability degree to reach the intended goal and the hesitation degree to achieve the intended goal. The advantages of the proposed algorithm can be summarized as follows:
• The proposed approach is based on IFS, and it is evident that IFS suitably reflects the hesitation and uncertainty of human thinking; so, it provides more flexibility to the decision makers while expressing their decision.

• By comparing our results, as in Tables 5–8, with Nishizaki et al. [10] and Aggarwal et al. [41], as in Tables 9–11, it can be easily seen that our proposed model produces much better optimal strategies with higher securities as, for player I, $\max(y_1, y_2, y_3) \geq 0.749534$ in our model, as opposed to $\max(y_1, y_2, y_3) = \gamma = 0.33088$ and $\max(y_1, y_2, y_3) < 0.58$ in case of Nishizaki's and Aggarwal's, respectively. Additionally, for player II, $\max(\delta_1, \delta_2, \delta_3) \geq 0.68814354$ in our model, but $\max(\delta_1, \delta_2, \delta_3) = 1 - \delta = 0.4196$, and $\max(\delta_1, \delta_2, \delta_3) < 0.5$ in Nishizaki and Aggarwal models, respectively.

• The disadvantages of Nishizaki et al. [10] approach are clear from Table 11, and it does not provide any information about the individual criteria strategies and fuzzy goals.

### Table 5. I-fuzzy optimal securities and strategies for player I using optimistic approach.

| #  | $y_1^*$ | $y_2^*$ | $y_3^*$ | $y_1$ | $y_2$ | $y_3$ |
|----|---------|---------|---------|-------|-------|-------|
| 1  | 0.5724637 | 0.2463768 | 0.1811594 | 0.4331723 | 0.4161490 | 0.7741020 |
| 2  | 0.875 | 0.125 | 0.00058216 | 0.5138888 | 0.3125 | 0.7608695 |
| 3  | 0.8098214 | 0.125 | 0.0651785 | 0.4994047 | 0.3404336 | 0.7580357 |
| 4  | 0.7446428 | 0.125 | 0.1303371 | 0.4849206 | 0.3683673 | 0.7552018 |
| 5  | 0.6794642 | 0.125 | 0.1955357 | 0.4704365 | 0.396301 | 0.752368 |
| 6  | 0.6142857 | 0.125 | 0.2607142 | 0.4559523 | 0.4242346 | 0.749534 |

### Table 6. I-fuzzy optimal securities and strategies for player II using optimistic approach.

| #  | $z_1^*$ | $z_2^*$ | $z_3^*$ | $\delta_1$ | $\delta_2$ | $\delta_3$ |
|----|---------|---------|---------|------------|------------|------------|
| 1  | 0.625 | 0.00000683 | 0.375 | 0.7410714 | 0.4910714 | 0.44375 |
| 2  | 0.6287389 | 0.0186948 | 0.3525662 | 0.7354629 | 0.50122 | 0.44375 |
| 3  | 0.6366255 | 0.0581276 | 0.3052468 | 0.7236331 | 0.5226264 | 0.44375 |
| 4  | 0.6445121 | 0.0975604 | 0.2579274 | 0.7118032 | 0.5440328 | 0.44375 |
| 5  | 0.6523986 | 0.130933 | 0.2100608 | 0.6999734 | 0.5654392 | 0.44375 |
| 6  | 0.6602852 | 0.1764261 | 0.1632886 | 0.6881435 | 0.5868456 | 0.44375 |

### Table 7. I-fuzzy optimal securities and strategies for player I using pessimistic approach.

| #  | $y_1^*$ | $y_2^*$ | $y_3^*$ | $y_1$ | $y_2$ | $y_3$ |
|----|---------|---------|---------|-------|-------|-------|
| 1  | 0.875 | 0.125 | 0.00000416 | 0.7265625 | 0.065625 | 0.6634615 |
| 2  | 0.8132227 | 0.125 | 0.0617772 | 0.7188403 | 0.130491 | 0.6579966 |
| 3  | 0.7514455 | 0.125 | 0.1235544 | 0.7111182 | 0.1953571 | 0.652537 |
| 4  | 0.6896682 | 0.125 | 0.1853316 | 0.703396 | 0.2602232 | 0.6470668 |
| 5  | 0.6278911 | 0.125 | 0.2471088 | 0.6956738 | 0.3250892 | 0.6416019 |
| 6  | 0.5661139 | 0.125 | 0.308886 | 0.6879517 | 0.3899553 | 0.636137 |

### Table 8. I-fuzzy optimal securities and strategies for player II using pessimistic approach.

| #  | $z_1^*$ | $z_2^*$ | $z_3^*$ | $\delta_1$ | $\delta_2$ | $\delta_3$ |
|----|---------|---------|---------|------------|------------|------------|
| 1  | 0.625 | 0.00000629 | 0.375 | 0.6380208 | 0.503125 | 0.2060439 |
| 2  | 0.6301808 | 0.0250942 | 0.3439149 | 0.6221544 | 0.5375776 | 0.2060439 |
| 3  | 0.634845 | 0.0492253 | 0.3159295 | 0.6078703 | 0.5685947 | 0.2060439 |
| 4  | 0.6395092 | 0.0725464 | 0.2879442 | 0.5935861 | 0.5996118 | 0.2060439 |
| 5  | 0.6441735 | 0.0958675 | 0.2599589 | 0.5793019 | 0.6306288 | 0.2060439 |
| 6  | 0.6488377 | 0.1191886 | 0.2319735 | 0.5650177 | 0.6616459 | 0.2060439 |
Table 9. Aggarwal et al. [41] optimal solutions for player I.

| #  | \(y_1^*\) | \(y_2^*\) | \(y_3^*\) | \(Y_1\)  | \(Y_2\)  | \(Y_3\)  |
|----|------------|------------|------------|----------|----------|----------|
| 1  | 0.875      | 0.125      | 0.0        | 0.4531   | 0.0375   | 0.5769   |
| 2  | 0.8098     | 0.125      | 0.0651     | 0.4368   | 0.0766   | 0.5719   |
| 3  | 0.7446     | 0.125      | 0.1303     | 0.4205   | 0.1157   | 0.5668   |
| 4  | 0.6794     | 0.125      | 0.1955     | 0.4042   | 0.1548   | 0.5618   |
| 5  | 0.6142     | 0.125      | 0.2607     | 0.3879   | 0.1939   | 0.5568   |
| 6  | 0.5491     | 0.125      | 0.3258     | 0.3716   | 0.2330   | 0.5518   |

Table 10. Aggarwal et al. [41] optimal solutions for player II.

| #  | \(z_1^*\) | \(z_2^*\) | \(z_3^*\) | \(\delta_1\) | \(\delta_2\) | \(\delta_3\) |
|----|------------|------------|------------|--------------|--------------|--------------|
| 1  | 0.625      | 0.0        | 0.375      | 0.5468       | 0.2875       | 0.1442       |
| 2  | 0.6299     | 0.0249     | 0.3451     | 0.5337       | 0.3064       | 0.1442       |
| 3  | 0.6349     | 0.0498     | 0.3152     | 0.5207       | 0.3253       | 0.1442       |
| 4  | 0.6399     | 0.0747     | 0.2853     | 0.5076       | 0.3442       | 0.1442       |
| 5  | 0.6449     | 0.0996     | 0.2554     | 0.4945       | 0.3632       | 0.1442       |
| 6  | 0.6499     | 0.1245     | 0.2255     | 0.4814       | 0.3821       | 0.1442       |

Table 11. Nishizaki et al. [10] optimal solutions for player I and player II.

| Player I | Player II |
|----------|-----------|
| \(y_1^*\) | 0.3860    |
| \(y_2^*\) | 0.1250    |
| \(y_3^*\) | 0.48897   |
| \(\gamma\) | 0.33088   |
| \(z_1^*\) | 0.25595   |
| \(z_2^*\) | 0.3469    |
| \(z_3^*\) | 0.3972    |
| \(\delta\) | 0.5804    |

8. Conclusions and Future Work

This article demonstrated the multi-criteria matrix games with I-fuzzy goals and proposed a solution methodology for such games. The main contributions of this article are summarized as follows:

- Outlining the arithmetic operations and indeterminacy resolving functions of Atanassov’s I-fuzzy number.
- Proposing an effective algorithm based on the indeterminacy resolving function, I-fuzzy inequality relations, and Inuiguchi et al. [42] algorithm.
- Generalizing the multi-criteria matrix game problem with fuzzy goals of those discussed by Nishizaki et al. [10] and Aggarwal et al. [41].
- Constructing crisp models from the proposed I-fuzzy models.
- Solving the reduced crisp multi-objective linear programming models using the GAMS software [43].
- Conducting two numerical simulations to evaluate the applicability and effectiveness of the proposed approach.
- The numerical results confirm that the IFS outperform fuzzy set when studying uncertainty in game theory.

To conclude, the algorithm proposed in this article is applicable to general decision-making problems with I-fuzzy environments. As a potential future research direction, we will investigate the application of the proposed algorithm to solve n-person matrix games, Stackelberg matrix games, nonzero-sum matrix games, constrained bi-matrix matrix games, and non-cooperative matrix games with I-fuzzy goals. Moreover, the adoption of the proposed algorithm and models for solving competitive decision-making problems can apply in other fields, such as supply chain management and advertising.

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**Appendix**

**Appendix A**

Step 1: Suppose the break points are \( a_1^n = 0, a_2^n = \frac{-\sigma d_0^n}{c_0^n + d_0^n}, a_3^n = 1 \).

Compute \((g^n)_{ij}^{-1}(a_1^n), (g^n)_{ij}^{-1}(a_2^n)\) and \((g^n)_{ij}^{-1}(a_3^n)\) and give them as \( W^n_{1,ij}, W^n_{2,ij} \) and \( W^n_{3,ij} \), respectively, for \( j = 1, ..., \ell, n = 1, ..., s \). Then, \( W^n_{1,ij} = (g^n)_{ij}^{-1}(a_1^n) = y^n_i - c^n_0 - d^n_0 \), \( W^n_{2,ij} = (g^n)_{ij}^{-1}(a_2^n) = y^n_i - c^n_0 \) and \( W^n_{3,ij} = (g^n)_{ij}^{-1}(a_3^n) = y^n_i \), for \( j = 1, ..., \ell, n = 1, ..., s \).

Step 2: Let \( \zeta_i^n = 1 \) and then obtain the value of \( \zeta_i^n = \zeta_i^n \min_{1 \leq j \leq \ell} \left( \frac{W^n_{1,ij} - W^n_{2,ij}}{W^n_{2,ij} - W^n_{1,ij}} \right) \).

Step 3: Calculate \( \zeta^n_i = \frac{\zeta^n_i}{\zeta^n_i + \zeta^n_{i+1}} \) and \( \zeta^n_i = \frac{\zeta^n_i}{\zeta^n_i + \zeta^n_{i+1}} \).

Step 4: For \( j = 1, ..., \ell, n = 1, ..., s \) and \( m=1,2 \), find

\[
g^n_{ij}(\psi^n_{mj}) = \begin{cases} 0 & m = 1, \\ \zeta^n_i & m = 2, \end{cases}
\]

and

\[
a^n_{m,j} = \frac{\zeta^n_m}{\psi^n_{m+1,j} - \psi^n_{m,j}}.
\]

Then compute

\[
g^n_{ij}(y^n T^n_i) = \begin{cases} 0, & y^n T^n_i \leq W^n_{1,ij}, \\ \min_{1 \leq j \leq \ell} (a^n_{m,j} (y^n T^n_i - \psi^n_{mj}) + g^n_{ij}(\psi^n_{mj})), & y^n T^n_i \in [W^n_{1,ij}, W^n_{2,ij}], \\ 1, & y^n T^n_i \geq W^n_{3,ij}.
\end{cases}
\]

**Appendix B**

Step 1: Suppose the break points are \( a_1^n = 0, a_2^n = \frac{-\sigma_1^n x^n_1}{c_0^n + d_0^n}, a_3^n = 1 \).

Compute \((h^n)_{i}^{-1}(a_1^n), (h^n)_{i}^{-1}(a_2^n)\) and \((h^n)_{i}^{-1}(a_3^n)\) and give them as \( \psi^n_{1,ij}, \psi^n_{2,ij} \) and \( \psi^n_{3,ij} \), respectively, for \( i = 1, ..., \mathcal{K}, n = 1, ..., s \). Then, \( \psi^n_{1,ij} = (h^n)_{i}^{-1}(a_1^n) = W^n_0 + e_0^n + r_0^n \), \( \psi^n_{2,ij} = (h^n)_{i}^{-1}(a_2^n) = W^n_0 + e_0^n \) and \( \psi^n_{3,ij} = (h^n)_{i}^{-1}(a_3^n) = W^n_0 \), for \( i = 1, ..., \mathcal{K}, n = 1, ..., s \).

Step 2: Let \( \rho_i^n = 1 \) and then obtain the value of \( \rho_i^n = \rho_i^n \min_{1 \leq i \leq \mathcal{K}} \left( \frac{\psi^n_{1,ij} - \psi^n_{2,ij}}{\psi^n_{2,ij} - \psi^n_{3,ij}} \right) \).

Step 3: Calculate \( \rho^n_1 = \frac{\rho_i^n}{\rho_i^n + \rho_i^n} \) and \( \rho^n_2 = \frac{\rho_i^n}{\rho_i^n + \rho_i^n} \).

Step 4: For \( i = 1, ..., \mathcal{K}, n = 1, ..., s \) and \( m=1,2 \), find

\[
h^n_{i}(\psi^n_{mi}) = \begin{cases} 0 & m = 1, \\ \rho^n_i & m = 2, \end{cases}
\]
\[
\beta_{m,i}^n = \frac{\rho_{m}^n}{\gamma_{m+1}^n - \gamma_{m,i}^n}.
\]

Then compute
\[
h_i^n(B_i^n z) = \begin{cases} 
0, & B_i^n z \leq \nu_{i,j}^n; \\
\min_{m=1,2} \left( \beta_{m,i}^n (B_i^n z - \nu_{m,i}^n) + h_i^n(\nu_{m,i}^n) \right), & B_i^n z \leq \nu_{i,j}^n, B_i^n z \geq \nu_{3,j}^n.
\end{cases}
\]

**Appendix C**

**Step 1:** We have
\[
a_1^1 = 0, a_2^1 = \frac{11}{54}, a_3^1 = 1,
a_2^2 = 0, a_2^2 = \frac{1}{6}, a_3^2 = 1,
\]

and
\[
\mathbb{W}_1^1 = 137, \mathbb{W}_1^2 = 148, \mathbb{W}_1^3 = \mathbb{W}_3^1 = 164,
\]
\[
\mathbb{W}_2^1 = 85, \mathbb{W}_2^2 = 90, \mathbb{W}_3^2 = 100.
\]

**Step 2:** Set \( \zeta_1^1 = \zeta_1^2 = 1 \) and compute
\[
\zeta_2^1 = \zeta_1^1 \min_{1 \leq |z|} \left( \frac{\mathbb{W}_1^1 - \mathbb{W}_1^1}{\mathbb{W}_1^1 - \mathbb{W}_1^1} \right) = \frac{16}{11},
\]
\[
\zeta_2^2 = \zeta_1^2 \min_{1 \leq |z|} \left( \frac{\mathbb{W}_2^2 - \mathbb{W}_2^2}{\mathbb{W}_2^2 - \mathbb{W}_2^2} \right) = 2.
\]

**Step 3:** Normalizing \( \zeta_1^1, \zeta_1^2, \zeta_2^1, \text{ and } \zeta_2^2 \), we obtain
\[
\zeta_1^1 = \frac{11}{27}, \zeta_2^1 = \frac{16}{27}, \zeta_1^2 = \frac{1}{3}, \zeta_2^2 = \frac{2}{3}.
\]

**Step 4:** Then for \( j = 1,2, \ n = 1,2 \text{ and } m = 1,2 \)
\[
g_j^1(\mathbb{W}_{m,j}^1) = \begin{cases} 
0 & m = 1, \\
\frac{11}{27} & m = 2,
\end{cases} \quad \text{and} \quad g_j^2(\mathbb{W}_{m,j}^2) = \begin{cases} 
0 & m = 1, \\
\frac{1}{3} & m = 2,
\end{cases}
\]

and
\[
\alpha_1^2 = \frac{1}{27}, \alpha_2^1 = \frac{1}{27}, \alpha_1^2 = \frac{1}{27}, \alpha_2^2 = \frac{1}{27},
\]
\[
\alpha_1^1 = \frac{1}{15}, \alpha_2^1 = \frac{1}{15}, \alpha_1^2 = \frac{1}{15}, \alpha_2^2 = \frac{1}{15}.
\]

**Appendix D**

**Step 1:** We have
\[
a_1^1 = 0, a_2^1 = \frac{1}{18}, a_3^1 = 1,
a_2^2 = 0, a_2^2 = \frac{1}{7}, a_3^2 = 1,
\]
Step 1. Set \( \xi_1 = \xi_2 = \xi_3 = 1 \) and compute

\[
\begin{align*}
\xi_2^1 &= \xi_1^1 \min_{1 \leq j \leq 3} \frac{(w_{3,j}^1 - w_{2,j}^1)}{(w_{2,j}^1 - w_{1,j}^1)} = 8, \\
\xi_2^2 &= \xi_1^2 \min_{1 \leq j \leq 3} \frac{(w_{3,j}^2 - w_{2,j}^2)}{(w_{2,j}^2 - w_{1,j}^2)} = \frac{10}{4}, \\
\xi_2^3 &= \xi_1^3 \min_{1 \leq j \leq 3} \frac{(w_{3,j}^3 - w_{2,j}^3)}{(w_{2,j}^3 - w_{1,j}^3)} = \frac{13}{10}.
\end{align*}
\]

Step 2: Normalizing \( \xi_1^1, \xi_1^2, \xi_1^3, \xi_2^1, \xi_2^2, \) and \( \xi_2^3 \), we obtain

\[
\xi_1^1 = \frac{1}{9}, \xi_2^1 = \frac{8}{9}, \xi_1^2 = \frac{4}{14}, \xi_2^2 = \frac{10}{14}, \xi_1^3 = \frac{10}{23}, \text{and} \xi_2^3 = \frac{13}{23}.
\]

Step 4: Then for \( j = 1, 2, 3, n = 1, 2, 3 \) and \( m=1,2 \)

\[
g_j^{-1}(w_{3,m}^j) = \begin{cases} 0 & m = 1, \\
\frac{1}{9} & m = 2, 
\end{cases} \quad g_j^{-2}(w_{2,m}^j) = \begin{cases} 0 & m = 1, \\
\frac{4}{14} & m = 2, 
\end{cases} \quad \text{and} \quad g_j^{-3}(w_{1,m}^j) = \begin{cases} 0 & m = 1, \\
\frac{10}{23} & m = 2, 
\end{cases}
\]

and

\[
\begin{align*}
\alpha_{1,1} &= \alpha_{2,1} = \frac{1}{9}, \quad \alpha_{1,2} = \alpha_{2,2} = \frac{1}{9}, \quad \text{and} \quad \alpha_{1,3} = \alpha_{2,3} = \frac{1}{9}, \\
\alpha_{1,1} &= \alpha_{2,2} = \frac{1}{14}, \quad \alpha_{1,2} = \alpha_{2,2} = \frac{1}{14}, \quad \text{and} \quad \alpha_{1,3} = \alpha_{2,3} = \frac{1}{14}, \\
\alpha_{1,1} &= \alpha_{2,1} = \frac{1}{23}, \quad \alpha_{1,2} = \alpha_{2,2} = \frac{1}{23}, \quad \text{and} \quad \alpha_{1,3} = \alpha_{2,3} = \frac{1}{23}.
\end{align*}
\]

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