Improving Sinkhole Attack Detection Rate through Knowledge-Based Specification Rule for a Sinkhole Attack Intrusion Detection Technique of IoT

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Received: 11 January 2022 / Revised: 23 February 2022 / Accepted: 01 March 2022 / Published: 30 April 2022

Abstract – The Internet of Things (IoT) is a technology that enables various IoT devices to collect data through sensors or sensor networks and to allow devices to share the collected data in an internet environment. Therefore, most communication is made wirelessly, and it is very vulnerable to a blackhole, selective forwarding, and sinkhole attacks that can occur in the network. One of the destructive attacks is the sinkhole attack, which compromises the integrity and reliability of data in a network. In general, the sinkhole attack detection method used by ad hoc networks and WSNs is less effective than the method used for IoT because of environmental differences. Therefore, the Intrusion detection of Sinkhole attack on 6LoWPAN for Internet of Things (INTI) method can detect sinkhole attacks occurring in IoT. In this study, rules are defined using a specification-based approach of intrusion detection technology based on the number of input/output transmissions collected in the monitoring phase of INTI. Knowledge base rules were defined to thresholds of normal operation, and different rules were defined according to the role each node plays in improving sinkhole attack detection rates.

Index Terms – Wireless Sensor Network, Internet of Things, Sinkhole, Intrusion Detection, Artificial Intelligence, Rule Based System, Forward Chaining.

1. INTRODUCTION
1.1. Internet of Things and Attack

As shown in Figure 1, the Internet of things (IoT) collects data through sensors built into various IoT devices or wireless sensor networks that exist outside and communicate unattended through the internet without human intervention. It is also a technology that allows each IoT device to share the collected data [1]. The main goal of IoT is to connect things, such as sensors, computers, refrigerators, and automobiles, to the internet anytime, anywhere, and not just in everyday life [2]. However, with the widespread development of IoT, problems related to information protection and security have arisen and must be addressed [3, 4].
hello flood attacks, black hole attacks, sinkhole attacks, and spoofing as shown in Figure 3 [5]. Among them, the sinkhole attack is one of the destructive attacks that occur in the network and damage the integrity and reliability of data [6]. An attack is in which an attacker lures a packet through a malicious node to route the packet to the wrong path or drop the packet in the middle [3].

There are various existing sinkhole attack detection methods used in ad hoc networks or WSNs. However, these methods are not suitable for use in IoT in terms of security and energy [7]. Therefore, methods such as VeRA [8], SVELTE [9], SOS-RPL [10], and INTI [11] have been proposed to detect sinkhole attacks on the Internet of things.

In a sinkhole attack, as shown in Figure 4, an attacker starts an attack by compromising a node inside the network and turning it into a compromised node. Then, it creates sinkholes around the malicious node created by the attacker by enticing traffic through the malicious node [5].

A sinkhole attack works by making malicious nodes look attractive. For example, it can broadcast to neighboring nodes, which is the fastest route to send a packet using an attacking node [12].

As mentioned above, the sinkhole, in which a compromised node induces packets, is a destructive attack that damages the integrity and reliability of data by routing packets to the wrong path or dropping packets in the middle. Additionally, selective forwarding attacks can also occur through sinkhole attacks, and more serious attacks can occur when sinkhole attacks combine with other attacks [13].

Various methods were used to detect sinkholes in the IoT. SVELTE [7] uses a hybrid approach of signature and anomaly-based detection of intrusion detection to target attacks such as sinkholes, selective forwarding, spoofing, or altered routing information. It is a lightweight yet effective IoT intrusion detection system with an RPL routing protocol within the 6LoWPAN system [14].

VeRA [8] requires security precautions when updating the version number in the RPL, where a destination-oriented directed acyclic graph (DODAG) [2] route can initiate a reconfiguration of its routing topology [15]. Security precautions must also be taken to prevent the compromised DODAG nodes from publishing reduced rank values. This allows many parts of the DODAG to connect to the DODAG root through an attacker and many parts to eavesdrop. The way to have a malfunctioning node detected is based on the version number and rank value. INTI [11] consists of four phases: cluster configuration phase, monitoring node phase, attack detection phase, and attack isolation phase. It is an IDS for identifying sinkhole attacks and evaluating the behavior of

2. RELATED WORK

The IoT combines with the Internet, mobile networks, and intelligent devices to provide useful services to users. However, it has not yet been fully developed in terms of security, and it is unstable. The most important part of IoT security today is protecting personal data. Various attacks [7] can occur in networks, and it is important to detect attacks through a defense technique that can only be used in the IoT, besides the defense technique used in the ad hoc network or WSN.

2.1. Sinkhole Attack

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each node. The details of the INTI are described in Section 2.2.

Figure 4 Sinkhole Attack

2.2. Intrusion Detection of Sinkhole Attack on 6LoWPAN for Internet of Things (INTI)

As described in Section 2.1, there are several defense techniques against sinkhole attacks that occur in the IoT. INTI is explained here.

As shown in Figure 5, INTI [11] consists of four stages: cluster configuration, monitoring node, attack detection, and attack isolation. The initial network consists of only free nodes. Initially, the clustering configuration stage and free nodes exchange control messages through message broadcasting to estimate the number of neighboring nodes. Based on the estimated number of neighbor nodes, the node with the largest number of neighbor nodes compared to other nodes is selected as the leader node, the free node receiving the message from the leader node becomes the member node, and two or more leader nodes among the member nodes designate the node that receives the message as the related node. A cluster consists of a leader node, member nodes, and related nodes. Member nodes are responsible for detecting events that occur within a cluster and delivering messages to the leader node. The leader node is responsible for delivering the message received from the member node to the related node. A related node is a node that receives messages from two leader nodes and plays a role in delivering the message received from one leader node and information on the cluster in which the node exists to the other leader node. The network configuration of INTI is shown in Figure 6. In the second stage, the monitoring node stage defines a monitoring module that counts the number of I/O transmissions performed by the node in charge of message delivery. In the third stage, the attack detection stage, the number of monitored input/output transmissions are defined using the $\beta(\alpha, \beta)$ distribution to define reputation and confidence, and through this, a sinkhole attack is detected. In the final attack isolation stage, all nodes are notified of the detected sinkhole, and the cluster is reconfigured after isolating the sinkhole node.

Figure 5 The INTI System Architecture

Figure 6 The INTI Network

2.3. Intrusion Detection

Intrusion is caused by a user who does not have access to a network system, a user who attempts to gain additional privileges besides the access privilege, or a user who misuses these access privileges. Such intrusions are accepted as attempts to compromise or circumvent the availability, confidentiality, or integrity of network security mechanisms [16], which detect and monitor events that occur inside a network or computer system and to identify security breaches by tracing abnormal systems usage patterns.

Intrusion detection technology can be classified into four types: specification, anomaly, signature, and hybrid approach according to the detection technology used in the network or system [17].

- The Signature-Based Approach
The signature-based approach detects attacks when events originating inside networks and computer systems match the attack signatures stored in internal storage systems. An alert is triggered when an event matches a pattern/signature stored in an internal database.

The signature-based approach is highly accurate and effective in detecting attacks that our internal database knows in advance. However, it is not effective in detecting recent attacks that are modified from existing or unknown attacks [16].

- The Anomaly-Based Approach

The anomaly-based approach immediately compares the original behavior with the behavior that occurs inside the system and raises a warning alarm when deviations from existing behavior exceed certain thresholds. Unlike signature-based methods, this method is effective in detecting recent attacks that are unknown or unmodified in existing attacks.

However, it is very difficult to set a threshold for normal behavior because any inconsistency with normal behavior is recognized as an attack. Additionally, this method has a very high false-positive rate, which recognizes non-attack behaviors as attacks [18].

- The Specification-Based Approach

The specification-based approach is a way in which users or experts define rules based on thresholds and expected behaviors from network components (protocols, routing tables, nodes, etc.) [15]. This method detects attacks when the behavior inside a network deviates from a set of user-defined thresholds and rules created.

This approach serves the same purpose as the anomaly-based approach discussed above to identify differences from the original behavior. However, unlike the anomaly-based approach, this method requires an expert or user to manually define each rule and threshold. As a result, it generally provides a lower false-positive rate than an anomaly-based approach [19]. However, manually defined rules and thresholds may not apply to other environments and are error-prone [18].

2.4. Forward Chaining

The expert system, which has been extensively used in artificial intelligence and is a system that allows the decision-making ability of an expert to be utilized in a computer. The expert system can be broadly divided into two systems: a knowledge base and an inference engine [20, 21]. The knowledge-based represents facts and rules, and rules connect logical information; it has an If... Then structure [22]. An inference engine is a method of applying existing or new facts to a rule so that new facts can be inferred from the rule. In addition to the knowledge base and inference engine, there is working memory. Working memory contains facts (information) provided by the user and the facts inferred by an inference engine.

Among the various inference engines, forward chaining is a method to draw a reasonable conclusion using the facts (information) given in the rule consisting of If...Then, or to establish additional hypotheses to infer the conclusion when additional facts (information) are drawn. That is, the facts (information) that exist in the working memory are If... Then, refers to the process of inferring a new fact by applying a rule consisting of it and storing it in the working memory or inferring a conclusion [23].

Forward chaining is illustrated in Figures 7 and 8, which illustrate the simple rules.

![Figure 7 Example of Forward Chaining Rule](image)

As part of working memory, there is the fact that “The fever is above 37 degrees, one loses their sense of smell. “The condition of rule 1 matches the fact that "The fever is above 37 degrees" in working memory. So, rule 1 fire and an additional fact of "Have a fever" is inferred. If so, the new facts are updated in the working memory. The new fact "Have a fever" updated in working memory matches the conditions of Rules 4 and 5. In this situation, a rule is triggered. If more than one rule is triggered in this way, conflict resolution is used to resolve it, and specificity ordering is used to resolve it. The conflict resolution is discussed in the following. rule 5, which is conditional on the fact that "Have a fever and lose one's sense of smell" exists in the working memory, is fired, and it is possible to infer the conclusion that "COVID-19 confirmed" Figure 7 shows a pictorial representation of what is described above.

Conflict resolution is a conflict resolution strategy for deciding which rules to fire because you only want to fire one rule when over one rule is triggered. Below is a description of the various conflict resolutions [23, 24].

- Rule Ordering: Fires the rule with the higher priority of the triggered rule by sorting all the rules into a priority list.
RESEARCH ARTICLE

- Context Limiting: Reduces the likelihood of collisions by breaking rules into groups, only some of which are active at any time.
- Specificity Ordering: Among the triggered rules, the rule that satisfies the most conditions of the rule is fired first.
- Recency Ordering: Fires the most recently used rule.

![Diagram of Forward Chaining](image)

**Figure 8 Forward Chaining**

### 3. Proposed Modelling

In this section, the simulation environment of the proposed technique and the proposed technique are explained with figures.

#### 3.1. Problem Statement

As mentioned above, a sinkhole attack is one of the destructive attacks that compromise the reliability and integrity of data, and an attacker can compromise a node inside the network and lure the packet through this node to route the packet to the wrong path or drop the packet in the middle. This is an attack that makes it happen. IoT is vulnerable to attacks such as sinkholes because data collected through sensors or sensor networks are communicated and shared unattended. Therefore, a defense technique that can detect sinkhole attacks is required. Additionally, using a specification-based approach to define rules or thresholds can reduce false-positive rates. With the existing INTI method for detecting sinkhole attacks, the number of input/output transmissions calculated in the monitoring node stage was used for the $\beta (\alpha, \beta)$ distribution to define the reputation and confidence, and through this, a sinkhole attack was detected. We use the specification-based approach of intrusion detection in this study for defining thresholds and deviations in the attack detection stage, and we propose a technique for detecting sinkhole attacks by using the forward chaining inference engine of the expert system.

#### 3.2. Environment Assumptions

The environmental assumptions of the proposed technique are as follows.

1. Monitoring node uses associated nodes existing in each cluster.
2. When forwarding a message, a node uses the shortest path routing.
3. When a member node detects an event, it sends a count to the monitoring node.
4. Whenever the leader node receives a message, it sends a count to the monitoring node.
5. Attacks do not occur simultaneously in multiple types of nodes.

| Event Count | Message Count | Miss Count | Message List |
|-------------|---------------|------------|--------------|
| 4           | 4             | 4          | OK           |
| 9           | 7             | 4          | BS $\rightarrow$ Normal [116 115 104 105], Mess(17), 2022.02.16 20:40:36 Cluster(11) |
| 14          | 2             | 2          | BS $\rightarrow$ Normal [125 125 105 105], Mess(15), 2022.02.16 20:40:35 Cluster(11) |
| 19          | 2             | 1          | BS $\rightarrow$ Normal [153 125 125 109 105], Mess(13), 2022.02.16 20:40:32 Cluster(15) |
| 24          | 4             | 1          | BS $\rightarrow$ Normal [102 105], Mess(12), 2022.02.16 20:40:31 Cluster(10) |
| 29          | 4             | 3          | BS $\rightarrow$ Normal [125 125 109 105], Mess(9), 2022.02.16 20:40:27 Cluster(12) |
| 39          | 0             | 0          | BS $\rightarrow$ Normal [136 114 115 104 105], Mess(10), 2022.02.16 20:40:28 Cluster(13) |
| 59          | 3             | 3          | BS $\rightarrow$ Normal [117 125 109 105], Mess(6), 2022.02.16 20:40:22 Cluster(12) |
| 69          | 0             | 0          | BS $\rightarrow$ Normal [177 125 109 105], Mess(6), 2022.02.16 20:40:22 Cluster(12) |
| 79          | 0             | 0          | BS $\rightarrow$ Normal [102 105], Mess(3), 2022.02.16 20:40:12 Cluster(10) |
| 89          | 0             | 0          | BS $\rightarrow$ Normal [102 105], Mess(2), 2022.02.16 20:40:11 Cluster(13) |
| 99          | 0             | 0          | BS $\rightarrow$ Normal [102 105], Mess(0), 2022.02.16 20:40:09 Cluster(14) |

![Diagram of Proposed Technique Simulation](image)

**Figure 9 Proposed Technique Simulation**
Figure 9 shows the proposed technique simulation and Figure 10 represents the various simulation parameters used.

3.3. Proposed Technique

In this study, the proposed method for detecting a sinkhole attack is constructed in the attack detection stage, which is the third stage of INTI, as shown in Figure 11. After selecting a monitoring node in the monitoring node stage, which is the second stage of INTI, the monitoring node counts the number of messages input/output of member nodes and leader nodes existing in the cluster. Subsequently, in the attack detection stage, the threshold value and deviation are defined as rules of the knowledge base using the specification-based approach of intrusion detection. The roles of the associated node, member node, and leader node in the cluster are different, and a sinkhole attack may occur for each node. Therefore, when defining a rule as a knowledge base using the specification-based approach of intrusion detection, it should be applied differently to each node.

The application of the rule is: First, we need to define a threshold value for normal operation in which a node normally delivers a message in the network. Second, the threshold and deviation of the node's normal operation in the network are defined as the rule of the knowledge base through the number of I/O transmissions of the monitored message. Because it is a rule of the knowledge base, it is defined using the If…Then structure. Finally, the defined rule is executed
using forward chaining, which is an inference engine of the expert system. There may be cases where two or more rules are triggered depending on the condition, and a conflict may occur. To resolve this situation, a conflict resolution method, the specificity rule ordering method, is used to resolve the conflict. The normal path of message transmission is shown in Figure 12.

As shown in Figure 13, if a sinkhole attack has occurred in A2, the difference between the number of event counts and message count is four or more, and if node id is the associated node, the sinkhole has occurred in the associated node. Additionally, if it is assumed that a sinkhole attack has occurred in M2, the message count increases; if the node id is a member node, a sinkhole has occurred in the member node. Thus, different rules were applied to each node.

4. RESULTS AND DISCUSSIONS

The simulation environment was as follows: events occurred randomly, there were 100 nodes inside the sensor network, and there was a total of 10 clusters.

4.1. Proposed Technique Result

This is the result of detecting a sinkhole attack according to the number of events of 100, 200, and 300 in the simulation environment.

In Figure 14, node M is a member node, node L is a leader node, and node A is a related node. Figure A shows that the sinkhole was detected in the order of member node, leader node, and related node, respectively, according to the number of sinkhole attack detections per node according to the number of event occurrences in the existing technique.

In Figure 15, node M is a member node, node L is a leader node, and node A is a related node. In Figure 14 showing the sinkhole detection of the proposed technique, similar to the result of Figure A, the number of sinkhole detections according to the number of events was detected well in the order of member nodes, leader nodes, and related nodes. As a result, the number of sinkhole attacks is inevitably large because the number of member nodes is the largest among the nodes in each cluster. Therefore, Figure 16 shows the sinkhole attack detection ratio for each node according to the attack ratio for accurate results.
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Figure 15 The Number of Sinkhole Attack Detections per Node in the Proposed Technique According to the Number of Event Occurrences

Figure 16 The Sinkhole Attack Detection Ratio Detected by Each Node by the Number of Event Occurrences

As shown in Figure 17, according to the number of event occurrences from 100 to 300, the sinkhole attacks detected by the member node for each node are 72.5% on average, and the sinkhole attacks detected by the leader node are, on average, 100% detected by the associated node. The average sinkhole attack ratio is 90.4%. As a result, because the leader node detects all sinkhole attacks, the knowledge-based rule using the expert system is applied well. In addition, the rule is being applied well because the ratio of detecting sinkhole attacks in member nodes also increases. However, in the case of the associated node, the detection ratio at 200 and 300 decreased compared to 100, but the ratio was maintained at 200 and 300.

4.2. Proposed Technique and INTI

Figure 18 The Sinkhole Attack Detection Ratio Detected by the Proposed Technique and INTI According to the Number of Event Occurrences

As shown in Figure 18, the proposed technique detected sinkhole attacks with higher accuracy compared to INTI. The proposed technique detected 90.4% of sinkhole attacks at 100, 93.5% at 200, and 92.6% at 300 event occurrences. INTI, on the other hand, detected 70.6% at 100, 67.8% at 200, and 65.2% at 300 event occurrences. This indicates that the proposed technique is more effective in detecting sinkhole attacks than INTI.
This is a comparison of the sinkhole attack detection ratio results in the proposed technique and the existing technique INTI, according to the number of events of 100, 200, and 300 in the same simulation environment.

As shown in Figure 18, according to the number of event occurrences from 100 to 300, the existing method, INTI, showed an average sinkhole attack detection ratio of 74.8%, and the proposed method showed an average sinkhole attack detection ratio of 81.63%. The proposed method showed an average sinkhole attack detection ratio of approximately 7% higher than that of the existing method, and the proposed technique escalates the sinkhole attack detection ratio as the number of events increases.

5. CONCLUSION

In this study, using a specification-based approach of intrusion detection, we define thresholds and deviations as rules of the knowledge base, and propose a technique to detect sinkhole attacks using a forward chaining inference engine. The proposed method improved the sinkhole attack detection ratio by approximately 7% on average compared with the existing method. However, when looking at the sinkhole detection ratio for each node of the proposed method, the knowledge-based rules were well applied in the member nodes and leader nodes but relatively less applied in associated nodes. If the rule was developed using the specification-based approach of intrusion detection, it may not be applied to an environment different from the existing one if it was developed in a different environment. Therefore, we plan to supplement the rules so that the proposed technique can be applied in various environments. Also, as mentioned above, a sinkhole attack is difficult to detect as it is a destructive attack that damages the reliability and integrity of data. The proposed method is based on the specification-based intrusion detection approach and creates rules based on the knowledge base of the expert system so that only sinkhole attacks can be detected. In future research, we plan to write additional rules to detect even selective forwarding attacks, which are one of the most common attacks through sinkhole attacks.

ACKNOWLEDGEMENT

This work was supported by the National Research Foundation of Korea (NRF) grant funded by the Korea government (MSIT) (No. NRF-2021R1A2C2005480).

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How to cite this article:

Ga Hyeon An, Tae Ho Cho, “Improving Sinkhole Attack Detection Rate through Knowledge-Based Specification Rule for a Sinkhole Attack Intrusion Detection Technique of IoT”, International Journal of Computer Networks and Applications (IJCNA), 9(2), PP: 169-178, 2022, DOI: 10.22247/ijcna/2022/212333.