Soft gravitons in the BFSS matrix model

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ABSTRACT: BFSS proposed that asymptotically flat M-theory is dual to a large $N$ limit of the matrix quantum mechanics describing $N$ nonrelativistic D0-branes. Recent insights on the soft symmetries of any quantum theory of gravity in asymptotically flat space are applied to the BFSS matrix model. It is shown that soft gravitons are realized by submatrices whose rank is held fixed in the large $N$ M-theory limit, rather than the usual linear scaling with $N$ for hard gravitons. The soft expansion is identified with the large $N$ expansion and the soft theorem becomes a universal formula for the quantum mechanical scattering of such submatrix excitations. This formula is shown to be the Ward identity of large type IIA $U(1)_{RR}$ asymptotic gauge symmetry in the matrix model, whose asymptotic boundaries are at future and past timelike infinity.

KEYWORDS: $1/N$ Expansion, D-Branes, M-Theory, Scattering Amplitudes

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1 Introduction

The holographic principle has a concrete and well-understood realization in anti-deSitter space (AdS) [1]. One hopes that the principle extends in some form to (nearly) flat space-times like the one we inhabit. The basic fact that the ratio of the boundary to bulk volume goes to a constant at large radius in AdS and to zero in flat space suggests that flat space holography may differ qualitatively from its AdS counterpart. But exactly how is an outstanding open question.

Two seemingly different approaches to flat space holography are the Banks-Fischler-Shenker-Susskind (BFSS) matrix model [2–10] and celestial holography [11–16]. BFSS is a top-down construction equating the momentum-$N$ sector of discrete lightcone quantized (DLCQ) M-theory with a quantum mechanics of $N \times N$ hermitian matrices representing open strings stretching between $N$ D0-branes. Celestial holography is a bottom-up approach applicable to any quantum theory of gravity in flat space, including M-theory, in which the proposed dual field theory lives on the celestial sphere at null infinity. Since the two approaches are applicable to the same theory it is natural to explore their connection.

The starting point of celestial holography (as well as AdS holography) is that both sides of a dual pair must have the same symmetries. Given the bulk description, soft theorems provide an efficient route to finding these symmetries [14]. So the first question we ask in this paper is ‘Is the soft graviton theorem realized in BFSS?’ We answer this by showing that soft gravitons are matrix subblocks whose rank is held fixed (rather than scaling with
like the hard gravitons) in the large-$N$ limit which recovers the full uncompactified M-theory. The soft limit is then nontrivially identified with the M-theory limit. It would be illuminating to derive the soft theorem directly from the matrix model, and would provide a novel test of the latter.

Soft theorems are in general expected to be Ward identities of symmetries. Hence one asks if this expectation holds for the soft theorem in the matrix model. Using the known expression for the BFSS matrix model in a background $U(1)_{RR}$ gauge field [17] we show that the soft theorem is the Ward identity of ‘large’ $U(1)_{RR}$ gauge transformations [18] which do not die off at past or future timelike infinity.  

We hope the answers to these basic questions provide a jumping-off point for relating these two approaches to flat holography. Many further questions remain unanswered. We will begin by reviewing the BFSS matrix model in section 2. In section 3, we leverage the soft graviton theorem in M-theory into an analogous one in the matrix model dual. We demonstrate that the soft expansion in the matrix model is a $1/N$ expansion. In section 4, we discuss the interplay between soft theorems and supertranslation symmetry in M-theory arguing that the analog of supertranslation symmetry in the matrix model is a large gauge symmetry of the RR 1-form.

2 Matrix model review

In this section we briefly review the relevant features of the BFSS matrix theory [2–10], which conjectures that the compactification of M-theory on a lightlike circle $X^- \sim X^- + 2\pi R$ with momentum $P^+ = N/R$ is dual to the low-energy dynamics of $N$ D0-branes in 10 dimensions or, equivalently, a certain supersymmetric quantum mechanical theory of $N \times N$ Hermitian matrices. Readers familiar with BFSS may safely skip this section.

2.1 BFSS duality

Compactification of 11-dimensional M-theory on a spacelike circle gives type IIA string theory [21, 22]. The massless degrees of freedom in M-theory are the 11-dimensional supergraviton multiplet. The D0-branes in type IIA string theory are identified as the KK-modes of this supergraviton multiplet. The number of units $N$ of momentum around the circle corresponds to the number of D0-branes. The BFSS matrix model concerns a lightlike compactification of M-theory which can be defined as an infinitely large boost of a spacelike one [5].

Let us define the lightcone coordinates $X^\pm$, and lightcone momenta $P^\pm$ by

$$X^\pm = \frac{1}{\sqrt{2}}(X^0 \pm X^{10}), \quad P^\pm = \frac{1}{\sqrt{2}}(P^0 \pm P^{10}).$$  \hfill (2.1)

\footnote{This is reminiscent of the large-$N$ limit of QCD, where baryons have masses of order $N$ and mesons of order 1. It would be interesting to see how far this analogy can be pushed.}

\footnote{This is in accord with the fact that 11D supertranslations with non-zero momentum on the M-theory circle KK reduce to $U(1)_{RR}$ gauge transformations [19, 20].}
Lightcone quantization is performed on surfaces of constant $X^+$ which plays the role of time, with $P^−$ the Hamiltonian. The lightlike compactification of M-theory is

$$(X^+, X^-) \sim (X^+, X^- + 2\pi R).$$

(2.2)

$P^+$ is quantized according to

$$P^+ = N/R.$$  

(2.3)

BFSS argued that the sector of M-theory with total momentum $P^+ = N/R$ can be described by a rescaled version of the Hamiltonian encoding the low-energy dynamics of $N$ D0-branes in type IIA string theory \cite{2–4}

$$H = \frac{R}{2} \text{Tr} \left[ P^I P_I - \frac{1}{2(2\pi l_9^2)^2} [X^I, X^J][X^I, X^J] - \frac{1}{2\pi l_9^2} \Psi^T \Gamma^I [X^I, \Psi] \right]$$

(2.4)

subject to the constraint on physical states

$$f_{ABC} (X_B^I P^I_C - \frac{i}{2} \Psi^\alpha_B \Psi^\alpha_C) |\psi_{\text{phys}}\rangle = 0$$

(2.5)

which forces states to be invariant under $U(N)$ transformations. Here $X^I$ are $N \times N$ Hermitian matrices with the index $I = 1, \ldots, 9$ running over the directions transverse to the lightlike compactification. $P^I$ are their conjugate momenta. $\Psi^\alpha$ is an $N \times N$ Hermitian matrix-valued spinor of Spin$(9)$ with $\alpha = 1, \ldots, 16$ and gamma matrices $\Gamma^I_{\alpha\beta}$. One can decompose these matrices as

$$X^I = X^I_A T^A, \quad P^I = P^I_A T^A, \quad \Psi^\alpha = \Psi^\alpha_A T^A$$

(2.6)

where $T^A$ are generators of the Lie algebra of $U(N)$ in the adjoint representation normalized so that $\text{Tr}(T^A T^B) = \delta^{AB}$.

We now review some basic properties of this theory \cite{23–28}. The bosonic potential $V \sim \text{Tr} ([X^I, X^J]^2)$ is classically at a minimum $V = 0$ when $[X^I, X^J] = 0$ for all $I$ and $J$, which implies all matrices can be simultaneously diagonalized. The $N$ eigenvalues are then positions of the $N$ D0-branes. For example, $N$ non-interacting D0-branes travelling along trajectories $x^I_i(t)$ with $i = 1, \ldots, N$ are described by the diagonal matrices

$$X^I(t) = \begin{pmatrix} x^I_1(t) & 0 & \ldots & 0 \\ 0 & x^I_2(t) & \ldots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \ldots & x^I_N(t) \end{pmatrix}.$$  

(2.7)

The off-diagonal elements are open strings stretching between the D0-branes.

A clump of $m < N$ coincident D0-branes corresponds to an $m \times m$ sub-block of this matrix for which all of the eigenvalues $x^I_i$ in the sub-block are equal. Quantum mechanically, these clumps are marginally bound states with complicated wave functions. They are dual to the higher KK-momentum supergraviton modes in the M-theory picture. Widely separated clumps are noninteracting because the strings stretched between them are very massive and forced into their ground states.
Table 1. Dictionary between momenta of gravitons in M-theory and momenta of D0-brane clumps in the BFSS matrix model. The final relation is determined using the mass-shell condition for M-theory gravitons \( 0 = -2k^+_j k^-_j + k^I_j k^I_j \).

| M-Theory | BFSS |
|----------|------|
| \( k^+_j \) | \( N_j/R \) |
| \( k^I_j \) | \( k^I_j \) |
| \( k^-_j \) | \( R(k^I_j)^2/2N_j \) |

2.2 Scattering

Consider a set of \( n \) gravitons in M-theory with individual momenta \( k^+_j = N_j/R \), with \( j = 1, \ldots, n \) and total momentum \( P^+_\text{tot} = (N_1 + \cdots + N_n)/R = N/R \). Each graviton is dual to a marginally bound clump labeled by the number of D0-branes \( N_j \), the transverse momentum \( k^I_j \), and the polarization information of the 11D supergraviton multiplet \( \epsilon_j \) which in the D0-brane description is encoded by the trace ‘center of mass’ fermions, with the explicit map given in [29–32]. The dictionary [3–5, 33] between clumps of D0-branes and a collection of M-theory gravitons is:

\[
\text{Widely separated multi-graviton ‘scattering states’ in M-theory with quantum numbers } k^\mu_1, \epsilon_1, \ldots, k^\mu_n, \epsilon_n \text{ correspond to widely-separated multi-clump states in the matrix model with D0-brane quantum numbers } N_1, k^I_1, \epsilon_1, \ldots, N_n, k^I_n, \epsilon_n. \text{ In order to formulate the scattering problem in BFSS, one should consider initial and final scattering states corresponding to widely separated wavepacket clumps of D0-branes, evolving past into future using the BFSS Hamiltonian (2.4) [34, 35]. The BFSS duality conjecture states that this scattering amplitude matches with the one that one would compute in (lightlike compactified) M-theory, namely }
\]

\[
A_M(k^\mu_1, \ldots, k^\mu_n) = A_{\text{BFSS}}(N_1, k^I_1, \ldots, N_n, k^I_n). \tag{2.8}
\]

2.3 The M-theory limit

The scattering amplitudes of uncompactified 11-dimensional M-theory are obtained by taking the radius large with external momenta held fixed

\[
R \to \infty, \quad k^\mu_j \text{ fixed.} \tag{2.9}
\]

From the expression for the momenta this is easily seen to be equivalent to

\[
N \sim N_j \sim R \to \infty, \quad k^I_j \text{ fixed,} \tag{2.10}
\]

and hence is a variety of large-\( N \) limit. In this limit, the discretuum of allowed values of external momentum approach a continuum and any scattering process can be studied.

3 Soft graviton theorem in the matrix model

In this section we show that the soft theorem is realized within BFSS duality and, moreover, that the soft limit is the same as the M-theory limit with external momenta/D0-charges suitably scaled.
3.1 The soft theorem in M-theory

Weinberg’s soft graviton theorem \cite{36} applies to essentially any gravitational theory in an asymptotically flat spacetime.\footnote{Of course Weinberg considered only four dimensions, but the extension to higher dimensions is straightforward \cite{19,37–40}.} In particular it must hold in 11-dimensional M-theory which contains gravitons as part of the low energy effective action.

Consider a generic scattering amplitude $A_M(k_1^\mu, \ldots, k_n^\mu)$ involving external particles with future-directed momenta $k_j^\mu$. These external particles may be ingoing or outgoing gravitons or some other particles. Momenta are parameterized by a vector $v^I \in \mathbb{R}^d$ and a scale $\omega \in \mathbb{R}_{>0}$ according to

$$k_j^\mu = \omega_j k_0^j = \frac{\omega_j}{2} (1 + v^2_j, 2v_j^I, 1 - v^2_j), \quad q_s^\mu = \omega_s q_0^s = \frac{\omega_s}{2} (1 + v^2_s, 2v_s^I, 1 - v^2_s).$$

(3.1)

where we denote the momentum of the soft graviton by $q_s^\mu$. The soft graviton theorem states:

$$A_M(q_s^\mu, \epsilon_s^{\mu\nu}; k_1^\mu, \ldots, k_n^\mu) = \left[ \frac{\kappa}{2} \epsilon_s^{\mu\nu} \sum_{j=1}^n \eta_j \frac{k_j k_0^j}{q_s \cdot k_j} \right] A_M(k_1^\mu, \ldots, k_n^\mu) + O\left(\frac{\omega_s}{\omega_j}\right)^0$$

(3.2)

where $\eta_j = +1 (-1)$ if the $j^{th}$ particle is outgoing (incoming), $\epsilon_s^{\mu\nu}$ is the polarization tensor of the soft graviton, and $\kappa = \sqrt{32\pi G_N}$ \cite{36}.

In the soft limit, the ratios $\omega_s/\omega_j \rightarrow 0$. The coefficient of the leading soft divergence $(\omega_s/\omega_j)^{-1}$ is universal. This leading soft term has corrections which are a power series in $(\omega_s/\omega_j)$.
3.2 Soft limit in the matrix model

In this subsection we show the soft limit in the BFSS matrix model is the M-theory limit with hard gravitons represented by subblocks whose size grows like $N$ and soft gravitons by subblocks of fixed finite size.

Both soft and hard gravitons are parameterized as in equation (3.1) with $q_s^+ = \omega_s/\sqrt{2}$ and $k_j^+ = \omega_j/\sqrt{2}$. This expression implies

$$\frac{n_s}{R} = \frac{\omega_s}{\sqrt{2}}, \quad q_s^I = \omega_s v_s^I \sim \omega_s \quad \text{and} \quad \frac{N_j}{R} = \frac{\omega_j}{\sqrt{2}}, \quad k_j^I = \omega_j v_j^I \sim \omega_j \quad (3.3)$$

where we have used the dictionary provided in table 1 with $N_j$, the block sizes, corresponding to the hard M-theory gravitons, and $n_s$ to the soft ones. Thus, the momentum $k_j^I$ for a particular graviton dictates the size of the corresponding block in the matrix model. In the matrix model, the soft limit then reads

$$\text{Soft Limit:} \quad \frac{n_s}{N_j} = \frac{\omega_s}{\omega_j} \to 0. \quad (3.4)$$

Scattering amplitudes with a soft external particle in the BFSS matrix model, thus, correspond to situations where a block of size $n_s$ is dwarfed by the other blocks of size $N_j$. This happens automatically in the M-theory limit (2.10) as long as we keep $n_s$ fixed! Hence the soft limit is the same as the M-theory limit, but with a new type of external state constructed from a finite number $n_s$ of D0-branes.\footnote{It is also possible to take $n_s \sim N^\alpha$ for any $\alpha \in (0, 1]$ such that $n_s/N_j \sim N^{\alpha-1} \ll 1$. This is permitted because the soft expansion is a series expansion in the ratio $n_s/N_j$, and it does not matter how the ratio scales with $N$. However, in the remainder of this work, we take $n_s \sim O(1)$ for simplicity.}

In the M-theory limit, the difference between scattering a graviton with $(N_j, k_j^I)$ versus $(N_j-1, k_j^I)$ with one fewer D0-branes vanishes. This might have led to the naive conclusion that submatrices with sizes or order one don’t matter and that the scattering of a single D0-brane $(1, k_1^I)$ vanishes altogether. This is not the case because of the soft pole. Note also the leading term in the scattering amplitude for a bound state with a fixed finite number $n_s$ of D0s differs only by the multiplicative factor $1/n_s$.

We illustrate a $2 \to 3$ scattering process with soft emission diagrammatically from the M-theory perspective, the D0-brane perspective, and the block diagonal matrix perspective explicitly in figure 1.

We now write the leading soft graviton theorem of M-theory (3.2) in terms of BFSS variables. If we define a convenient basis for graviton polarization tensors

$$\epsilon_{IJ}^{\mu\nu}(v) \equiv \frac{1}{2} (\epsilon_I^I \epsilon_J^\nu + \epsilon_J^I \epsilon_I^\nu) - \frac{1}{9} \delta_{IJ} \epsilon^\mu_R \epsilon^{K\nu} \quad \text{with} \quad \epsilon_J^I(v) \equiv \partial_J \delta^I_\mu = (v_j, \delta^I_j, -v_j) \quad (3.5)$$

and write the soft graviton polarization as

$$\epsilon_s^{\mu\nu} = \epsilon^{IJ} \epsilon_s^{\mu\nu}_{IJ} \quad (3.6)$$
then after some algebra and using the dictionary \text{1}, the soft theorem becomes\textsuperscript{5}

\[ A_{\text{BFSS}}(n_s, q_s^I, \epsilon_s, \text{out}; \text{in}) = \left[ -2\kappa \sum_{j=1}^{n} \eta_j \frac{N_j}{n_s} e_{IJ}(v_s - v_j)^J(v_s - v_j)^J}{(v_s - v_j)^2} + \cdots \right] A_{\text{BFSS}}(\text{out}; \text{in}). \]  

\[ \text{(3.7)} \]

Finally, we define the inversion tensor in 9 spatial dimensions as\textsuperscript{6}

\[ I^{IJ}(v) = \delta^{IJ} - 2\frac{v^I v^J}{v^2}. \]  

\[ \text{(3.8)} \]

In terms of this inversion tensor, the leading soft graviton theorem in the BFSS matrix model reads

\[ A_{\text{BFSS}}(n_s, q_s^I, \epsilon_s, \text{out}; \text{in}) = \left[ \kappa \sum_{j=1}^{n} \eta_j \frac{N_j}{n_s} I^{IJ}(v_s - v_j) + \cdots \right] A_{\text{BFSS}}(\text{out}; \text{in}). \]  

\[ \text{(3.9)} \]

Note that the soft pole \( \omega_j/\omega_s \) gets recast into the ratio of block sizes \( N_j/n_s \), which diverges in the soft limit according to equation (3.4).

Sub-leading corrections to this expression are given by an expansion in \( n_s/N_j \). Because \( n_s \sim O(1) \) and \( N_j \sim O(N) \), we can identify the subleading terms in the soft expansion on the gravity side with a \( 1/N \) expansion on the gauge theory side.

It would be illuminating to derive the soft theorem directly from the matrix model. It is not obvious to us even how the factor of \( N_j/n_s \) would emerge.

\section{Asymptotic symmetries in the matrix model}

In this section, we use the soft graviton theorem in 11D to show that the insertion of a single D0-brane in a 10D BFSS scattering amplitude generates a large gauge transformation on the background RR 1-form gauge potential \( C_\mu \) in the matrix model.\textsuperscript{7} Since this is a quantum-mechanical model the relevant asymptotic regions are at \( t = \pm \infty \). The RR 1-form is of the form \( C_\mu = \partial_\mu \theta_{e,v_s} \), for some particular gauge parameter \( \theta_{e,v_s} \) given in (4.9) depending on the polarization \( e_{IJ} \) and velocity \( v_s \) of the soft D0-brane. This is summarized in equation (4.10), which is the main result of this section. This large U(1) gauge symmetry arises in the KK reduction of the 11D supertranslation symmetry.\textsuperscript{8}

\textsuperscript{5}There is a small technical subtlety in equation (3.7). The BFSS matrix model describes M-theory in a sector with momentum \( P^+ = N/R \), so all amplitudes must be manifestly momentum conserving in \( P^+ \) and cannot be off-shell in \( P^+ \). Equivalently, the number of D0-branes \( N \) is always conserved. Therefore, we cannot simply append a small block of size \( n_s \) to the matrix, but we must shrink the size of the other blocks slightly. Assuming that the amplitudes are analytic in \( N_j \) (in the large \( N \) limit, this follows from the analyticity of the M-theory S-matrix) one may perform a first order Taylor expansion to see that the expression will only be corrected at subleading terms.

\textsuperscript{6}This is the same inversion tensor familiar from conformal field theory.

\textsuperscript{7}The result easily generalizes to finite bound clumps of D0-branes by dividing by \( n_s \).

\textsuperscript{8}Symmetries associated to 10D supertranslations would have to come from modes independent of the \( X^+ \) circle and hence involve \( n_s = 0 \). It is not clear to us how to describe these in the matrix model.
4.1 Background RR gauge potentials

The standard BFSS matrix model, with the Hamiltonian given by equation (2.4), describes a system of D0-branes living in a world where all background fields are turned off. The effect of coupling the D0-branes to external background fields can be incorporated by adding terms to the Lagrangian. In particular, the interaction term coupling the D0-branes to the $U(1)_{RR}$ gauge field $C_\mu$ generalizes the usual electromagnetic interaction $Q \int dt \dot{x}^\mu C_\mu(x)$ between a charge $Q$ particle and the gauge field, where $x^\mu$ is the worldline of the particle.

In the matrix model, the precise interaction term was found in [17] to be

$$S_{RR}[C_\mu] = \int dt \sum_{n=0}^{\infty} \frac{1}{n!} (\partial_{I_1} \cdots \partial_{I_n} C_\mu(t, \vec{0})) I^\mu(I_1 \cdots I_n)$$  \hspace{1cm} (4.1)$$

where $\mu = 0, \ldots, 9$ and $x^\mu = (t, x^I) = (t, \vec{x})$. The ‘multipole moments’ of the current $I^\mu$ are defined by

$$I^\mu(I_1 \cdots I_n) = \text{Tr} \left( \text{Sym}(I^\mu, X^{I_1}, \cdots, X^{I_n}) \right) + I_F^{\mu(I_1 \cdots I_n)}$$  \hspace{1cm} (4.2)$$

where

$$I^\mu = (1/R, \dot{X}^I/R).$$ \hspace{1cm} (4.3)$$

Here, $\text{Sym}$ is a symmetrized average over all orderings of the input matrices. $I_F^{\mu(I_1 \cdots I_n)}$ are terms involving at least two fermionic matrices, $\Psi$, which will not be relevant to this paper for reasons discussed in section 4.2. If one takes the matrices $X^I$ to be diagonal, as in equation (2.7), then the action reduces to the electromagnetic form, as expected.

4.2 Large $U(1)_{RR}$ gauge transformations

If the RR 1-form is pure gauge, then the interaction term (4.1) becomes a total derivative. Plugging $C_\mu = \partial_\mu \theta$ into equation (4.1), one can show that\(^9\)

$$S_{RR}[\partial_\mu \theta] = \int dt \partial_t \left[ \sum_{n=0}^{\infty} \frac{1}{n!} (\partial_{I_1} \cdots \partial_{I_n} \theta(t, \vec{0})) I^{0(I_1 \cdots I_n)}(t) \right]$$

\hspace{1cm} (4.4)$$

$$= \sum_{n=0}^{\infty} \frac{1}{n!} \left( \partial_{I_1} \cdots \partial_{I_n} \theta(t, \vec{0}) \right) I^{0(I_1 \cdots I_n)}(t) \Bigg|_{t=+\infty}^{t=-\infty}.$$

Therefore, a pure gauge background field affects amplitudes by a position-dependent phase acting on the initial and final states.

The asymptotic symmetry group of gauge theories is typically defined as the set of ‘large’ gauge transformations which satisfy some set of boundary conditions modulo ‘small’ gauge transformations which vanish at the boundary. For the remainder of this section, we will consider the case where $C_\mu = \partial_\mu \theta$ is pure gauge and given by such a large gauge transformation $\theta$ which is non-vanishing as $t \to \pm \infty$. The boundary conditions which $\theta$

\(^9\)To demonstrate this, one must use that the multipole moments satisfy the conservation law $\partial_t I^{0(I_1 \cdots I_n)} = I^{I_1(I_2 \cdots I_n)} + \cdots + I^{I_n(I_1 \cdots I_{n-1})}$.\)
must satisfy near past and future timelike infinity [14, 41–44] specify that as $t \to \pm \infty$, the gauge parameter $\theta(t, \vec{x})$ can only depend on the ratio $\vec{x}/t$

$$\theta(t, \vec{x}) \xrightarrow{t \to \pm \infty} \theta(\vec{x}/t)$$  \hspace{1cm} (4.5)

implying that these large gauge transformations are parameterized by a single function on $\mathbb{R}^9$.\footnote{This is the limit relevant for nonrelativistic charged massive scattering states of the more general formula for large U(1) gauge transformations.}

Outside of the above specification, the gauge parameter is arbitrary.

Now we show that the boundary term (4.4) reduces to a very simple expression on asymptotic scattering states. As functions of $X^I$, asymptotic scattering wavefunctions are sharply peaked in momentum space and non-trivially supported only on matrices of the form

$$X^I = \left( \begin{array}{ccc} x^I_1(t) \\ \vdots \\ x^I_N(t) \end{array} \right) + \Delta X^I, \quad \Delta X^I \sim O(t^0)$$  \hspace{1cm} (4.6)

where $\vec{x}_i(t) = \vec{v}_i + \vec{x}_{i,0}$ tracks the position of the $i^{th}$ D0-brane. Note that $\vec{x}_i(t) = \vec{x}_j(t)$ when the $i^{th}$ and $j^{th}$ D0-branes share a bound state. $\Delta X^I$ is a matrix whose values do not grow with time as $t \to \pm \infty$. The entries within the blocks on the diagonal of $\Delta X^I$ correspond to the degrees of freedom of the bound states modulo their center of mass motion. As such, these entries can take values on the order of the spatial size of these bound states.

The off block-diagonal components of $\Delta X^I$ describe strings stretched between distant D0-brane bound states. The mass of the string is proportional to its length, so these strings have mass scaling like $t$. When the string excitations become heavy, the wavefunction for these components gets frozen to the ground state of a quantum (super)harmonic oscillator with frequency $\omega \sim t$. The width of such a wavefunction shrinks as $\sim t^{-1/2}$. This situation is summarized in figure 2.

We may now insert the matrices describing the asymptotic states (equation (4.6)) into the boundary term (equation (4.4)). We find that the only terms that survive at $t = \pm \infty$ are\footnote{In this footnote we demonstrate why the fermionic term $I^{0(t_1 \cdots t_n)}_F$ in equation (4.2) doesn’t contribute to our analysis. First, we notice that the couplings $\partial_{t_1} \cdots \partial_{t_n} \theta(\vec{x}/t)$ contains $n$ spatial derivatives, each pulling down a factor of $1/t$. So, for the term $(\partial_{t_1} \cdots \partial_{t_n} \theta)I^{0(t_1 \cdots t_n)}_F$ to be non-vanishing at $t = \pm \infty$, $I^{0(t_1 \cdots t_n)}_F \sim t^n$ at asymptotic times. The bosonic moments, $I^{0(t_1 \cdots t_n)}_B = \text{Tr}(\text{Sym}(X^{t_1} \cdots X^{t_n}))$, scale as $t^n$, since every bosonic matrix has entries growing as $t$. In fact, only the entries linear in $t$, which are $v^t t$, survive in this limit. Next, we use the fact that the BFSS action is invariant under $R \to \lambda R, X \to \lambda^{1/3} X, \Psi \to \lambda^{1/2} \Psi, t \to \lambda^{-1/3} t$ [45]. This invariance must persist when coupled to a background field if we map $\theta \to \lambda \theta$, which implies that each multipole term $I^{0(t_1 \cdots t_n)}_F$ must have a constant scaling dimension in $\lambda$ for the action to be invariant. Therefore, if two $\Psi$’s are added, three $X$’s must be removed, making the whole term scale three lower powers of $t$ and vanish at the boundary.}

$$S_{RR}[\partial_{\mu} \theta] = \sum_{j=1}^{n} \frac{N_{j}}{R} \sum_{n=0}^{\infty} \frac{1}{n!} \left( \partial_{t_1} \cdots \partial_{t_n} \theta(0) \right) x_{j_1}^{I_1} \cdots x_{j_n}^{I_n} \Big|_{t=+\infty} - \sum_{j=1}^{n} \frac{N_{j}}{R} \theta(\vec{v}_j)$$  \hspace{1cm} (4.7)
Figure 2. (a) How different parts of the matrix $X^J$ scale with $t$ for scattering states. (b) The scattering of non-relativistic D0-brane bound state Gaussian wavepackets, which can be taken to have an arbitrarily small angular width. A gauge function $\theta(t, \vec{x})$ which only depends on the ratio $\vec{x}/t$ will take a well-defined value on these wave packets, depending only on their velocity.

where we noticed that the middle expression is just a Taylor expansion of $\theta(t, \vec{x})$ and used $\theta(t, \vec{x}_j) = \theta(\vec{x}_j/t)$ according to our earlier considerations.

In a quantum amplitude, this addition to the action becomes an overall phase. Therefore, placing BFSS in such a background gauge field modifies the amplitude via

$$ A_{\text{BFSS}}(\text{out; in}) \bigg|_{C_\mu = \partial_\mu \theta} = \exp \left( i \sum_{j=1}^n \eta_j \frac{N_j}{R} \theta(\vec{v}_j) \right) A_{\text{BFSS}}(\text{out; in}) \bigg|_{C_\mu = 0}. \quad (4.8) $$

From the soft graviton theorem (3.9), if we define the gauge parameter $\theta_{e, v_s}$ by

$$ \theta_{e, v_s}(\vec{x}/t) \equiv -2\kappa \frac{e_{IJ}(v_s - x/t)^I(v_s - x/t)^J}{|\vec{v}_s - \vec{x}/t|^2} \quad (4.9) $$

which depends on the velocity $\vec{v}_s$ and polarization structure $e_{IJ}$ of the soft D0-brane, then by combining (4.8) and (3.7), we see that

$$ \lim_{n_s/R \to 0} \frac{n_s}{R} A_{\text{BFSS}}(n_s, k_s^I, \epsilon_s, \text{out; in}) \bigg|_{C_\mu = 0} = -i \frac{d}{d\epsilon} \bigg|_{\epsilon = 0} A_{\text{BFSS}}(\text{out; in}) \bigg|_{C_\mu = \partial_\mu \theta_{e, v_s}}. \quad (4.10) $$

Therefore, the insertion of a single D0-brane in a momentum eigenstate in the amplitude generates the action of a large $U(1)_{RR}$ gauge transformation (4.9) on the asymptotic scattering state. A general gauge transformation can be generated by an appropriate coherent superposition of a momentum-eigenstate D0-brane.

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