Characterizing topological orders by the information convex

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Motivated by previous efforts in detecting topological orders from the ground state(s) wave function, we introduce a new quantum information tool, coined the information convex, to capture the bulk and boundary topological excitations of a 2D topological order. Defined as a set of reduced density matrices that minimizes the energy in a subsystem, the information convex encodes not only the bulk anyons but also the gapped boundaries of 2D topological orders. Using untwisted gapped boundaries of non-Abelian quantum doubles as an example, we show how the information convex reveal and characterize deconfined bulk and boundary topological excitations, and the condensation rule relating them. Interference experiments in cold atoms provide potential measurements for the invariant structure of information convex.

Introduction Topological orders\textsuperscript{1,2} represent a large class of gapped quantum phases characterized by long-range entanglement\textsuperscript{3,4}. Unlike symmetry breaking orders, they support topological excitations (anyons) created by (deformable) string operators, which obey fractional braiding statistics\textsuperscript{5}. Topological orders have locally indistinguishable states robust to decoherence\textsuperscript{6}, making them excellent candidates for quantum computation\textsuperscript{7,8}. Enormous theoretical progress has been made in understanding 2D topological orders from topological quantum field theories\textsuperscript{2,9,11}, exactly solved models\textsuperscript{12–14} and tensor category theory\textsuperscript{12–15}.

Given a topologically ordered system, one important question is how to detect its topological properties? It has been shown that using the ground state(s) one can compute many invariants that characterize the topological order, such as the topological entanglement entropy (TEE)\textsuperscript{10,16} and modular matrices\textsuperscript{4,17,18}. In reality, however, any experimental measurement is performed at a finite temperature, which probes a thermal density matrix rather than the ground state(s). Can one instead extract the topological order from the density matrix?

Moreover, although many theoretical efforts study topological orders on a closed manifold such as the torus, most experiments are performed on systems with open boundaries. 2D nonchiral topological orders may have gapped boundaries, where one bulk phase can have more than one boundary types\textsuperscript{19–27}. How to extract this rich structure of boundary excitations in a topologically ordered system?

In this work, we develop a quantum informational tool: the information convex $\Sigma(\Omega)$ to characterize the topological excitations in the bulk and on the gapped boundary of a 2D topological order. Mostly conveniently defined for any frustration-free local Hamiltonian\textsuperscript{28}, $\Sigma(\Omega)$ is the (convex) set of reduced density matrices on a region $\Omega$, obtained from states which minimize all terms overlapping with region $\Omega$ in the Hamiltonian (see Supplemental Material (SM) for details). The element $\sigma_{\Omega} = \langle \varphi | \langle \alpha | \varphi \rangle | \varphi \rangle$ of the convex set $\Sigma(\Omega)$ can be obtained from states $| \varphi \rangle$ with no excitations within $\Omega$, where $\Omega$ is the complement of $\Omega$. The information convex can be obtained numerically by performing imaginary time evolution in region $\Omega$, or experimentally by cooling down the subsystem $\Omega$ below the finite energy gap.

First, for a 2D topological order on a closed manifold, we show that the information convex $\Sigma(\Omega)$ naturally captures previously known topological invariant characterizations like TEE\textsuperscript{10,16} and the minimal entangled (ground) states\textsuperscript{17}. To study bulk properties, we choose the subsystem $\Omega$ away from the boundary of the system, as illustrated by $\omega_1$ and $\Omega_1$ in FIG. 2. The annulus $\Omega_1$ in FIG. 2 leads to extremal points $| 1 \rangle$ labeled by different bulk anyon types (or bulk superselection sectors).

Moreover, for a 2D nonchiral topological order with open boundaries, the information convex $\Sigma(\Omega)$ allows us to reveal the structure of boundary topological excitations, which are generally different from the bulk anyons\textsuperscript{21–25}. For this purpose, we choose the subsystem $\Omega$ containing a part of the open boundary, illustrated by $\omega_2$, $\Omega_2$ and $\Omega_3$ in FIG. 2. For example, choosing strip $\Omega_2$ as the subsystem leads to information convex $\Sigma(\Omega_2)$, whose extremal points correspond to distinct boundary topological excitations (or boundary superselection sectors).

While bulk anyons (red dots in FIG. 1) of a 2D topological order are created by deformable strings within the bulk (grey lines in FIG. 1), with open boundaries there are also deformable strings which cannot detach from the boundary (green lines in FIG. 1). Boundary topological excitations (purple dots in FIG. 1) are created by these non-detachable strings. We discuss how the topological invariants of $\Sigma(\Omega)$ capture boundary superselection sectors $\{ \alpha \}$, their corresponding quantum dimensions $\{ d_\alpha \}$, and the condensing process from a bulk anyon $a$ to boundary excitations $\sum \alpha$. We also discuss an interesting peculiarity of certain non-Abelian topological orders, where information convex has an infinite number of extremal points.

The Models To demonstrate our main results, we perform explicit calculations on the quantum double models (with finite group $G$) with an untwisted boundary labeled...
by a subgroup $K \subseteq G$\cite{7, 13, 20}. We focus on a simple example $G = S_3$, $K = \{1\}$, where most of the nontrivial intuitions can be seen (see SM for details and generalizations). For simplicity, we put the model on a disk $D^2$ with a single open boundary. The Hilbert space is defined on a lattice within the disk, and there is a unique ground state $|\psi\rangle$.

$S_3 = \{1, r, r^2, s, sr, sr^2\}$ with $r^3 = s^2 = 1$, $sr = r^2 s$ is the simplest non-Abelian finite group. The $G = S_3$ quantum double has 8 bulk anyon types (bulk superselection sectors) labeled by a pair $a = (c, R)$ with quantum dimension $d_a$. Where $c$ is a conjugacy class of $G$ and $R$ is an irreducible representation of the centralizer group. We list only useful information for later discussions, while more details can be found in \cite{7, 13, 29} and SM. Note that for $S_3$ quantum double model, each bulk anyon is its own antiparticle.

| Conjugacy class $c$ | $c_1 = \{1\}$ | $c_2 = \{r, r^2\}$ | $c_3 = \{s, sr, sr^2\}$ |
|---------------------|------------|----------------|----------------|
| $a$                 | 1          | $J^w$          | $J^y$          |
| $d_a$               | 1          | 2              | 2              |
|                     |            | 3              | 3              |

"global" ground state $|\psi\rangle$. For a topologically trivial subsystem $\omega$ (e.g. $\omega_1$ and $\omega_2$ in FIG.2), we have $\Sigma(\omega) = \{\sigma_1^\omega\}$. In other words, states locally minimizing energy of subsystem $\omega$ are indistinguishable from the ground state on the subsystem. Though simple, $\Sigma(\omega)$ determines the possible types of deformable strings in $\Sigma(\omega)$ and that the string operators can be unitary (see SM for details).

On the other hand, information convex of a bulk annulus $\Omega_1$ has a richer structure:

$$\Sigma(\Omega_1) = \{\sigma_{\Omega_1} | \sigma_{\Omega_1} = \sum_{a} p_a \sigma_{\Omega_1}^a\}.$$  (1)

where $a$ labels bulk superselection sectors (bulk anyon types), with $a = 1$ for the vacuum sector. $\{p_a | \sum_a p_a = 1\}$ is a probability distribution. Clearly $\Sigma(\Omega_1)$ is a convex set and $\sigma_{\Omega_1}^a$ are its extremal points. Under continuous deformations of $\Omega_1$ and the Hamiltonian, $\Sigma(\Omega_1)$ exhibits the following topological invariant structure:

$$\frac{tr[\sigma_{\Omega_1}^a \cdot \sigma_{\Omega_1}^b]}{tr[\sigma_{\Omega_1}^a \cdot \sigma_{\Omega_1}^b]} = \frac{1}{d_a}; \quad \sigma_{\Omega_1}^a \cdot \sigma_{\Omega_1}^b = 0 \quad \text{for} \ a \neq b;$$  (2)

$$S(\sigma_{\Omega_1}^a) = S(\sigma_{\Omega_1}^b) + \ln d_a.$$  (3)

where $S(\sigma) = -tr(\sigma \ln \sigma)$ is the von Neumann entropy. One can further show the extremal point $\sigma_{\Omega_1}^a = tr_{\Omega_1}|\varphi^a\rangle \langle \varphi^a|$ can be obtained from an excited state $|\varphi^a\rangle$ with an anyon pair $(a, \bar{a})$ created by a bulk string shown in FIG.2(b). When $\Omega_1$ is a noncontractible annulus on a torus $\mathbb{T}^2$, each extremal point can be obtained from the corresponding minimal entangled state on torus $\mathbb{T}^2$.

In the example of $S^3$ quantum double, there are 8 extremal points (8 anyons), leading to a 7-dimensional information convex set.

**Characterizing Bulk Topology** $\Sigma(\Omega)$ always contains the reduced density matrix $\sigma_{\Omega}^1 \equiv \text{tr}_{\Omega} |\psi\rangle \langle \psi|$ of the ground state $|\psi\rangle$. For a topologically trivial subsystem $\omega$ (e.g. $\omega_1$ and $\omega_2$ in FIG.2), we have $\Sigma(\omega) = \{\sigma_1^\omega\}$. In other words, states locally minimizing energy of subsystem $\omega$ are indistinguishable from the ground state on the subsystem. Though simple, $\Sigma(\omega)$ determines the possible types of deformable strings in $\Sigma(\omega)$ and that the string operators can be unitary (see SM for details).

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In the example of $S^3$ quantum double, there are 8 extremal points (8 anyons), leading to a 7-dimensional information convex set.
in $\Sigma(\Omega_1)$ with the largest entanglement entropy, saturates this lower bound [30] and leads to $S_{\text{topo}} = \ln D^2$, where $D \equiv \sqrt{\sum_a d_a^2}$ is the total quantum dimension. This recovers the celebrated TEE.

**Characterizing Boundary Topology** The topological excitations on the gapped boundary can be extracted by choosing subsystem $\Omega_2$ in FIG. 2. 

\[ \Sigma(\Omega_2) = \{ \sigma_{\Omega_2} \sigma_{\Omega_2} = \sum_\alpha p_\alpha \sigma^\alpha_{\Omega_2} \} \]  

(4)

\[ \frac{tr[\sigma^\alpha_{\Omega_2} \cdot \sigma^\beta_{\Omega_2}]}{tr[\sigma^\alpha_{\Omega_2} \cdot \sigma^\alpha_{\Omega_2}]} = \frac{1}{d_\alpha}, \quad \sigma^\alpha_{\Omega_2} \cdot \sigma^\beta_{\Omega_2} = 0 \quad \text{for} \ \alpha \neq \beta; \]  

(5)

\[ S(\sigma^\alpha_{\Omega_2}) = S(\sigma^1_{\Omega_2}) + \ln d_\alpha. \]  

(6)

where \( \{ p_\alpha \} \) is a probability distribution. The structure of $\Sigma(\Omega_2)$ is very similar to that of $\Sigma(\Omega_1)$, except that the $\alpha, \beta$ label the boundary superselection sectors instead of the bulk ones. The name comes from the fact that every extremal point $\sigma^\alpha_{\Omega_2}$ can be obtained from an excited state with a unitary string operator acting along the boundary, which creates a pair of boundary topological excitations $(\alpha, \tilde{\alpha})$ as shown in FIG. 4(b).

For a $K = \{ 1 \}$ boundary of $G$ quantum double, $\alpha \in G$ labels the “flux” type and $d_\alpha = 1$, $\forall \alpha \in G$. For $G = S_3$:

| $\alpha$ | 1 | r | r$^2$ | s | sr | sr$^2$ |
|------|---|---|---|---|---|---|
| $d_\alpha$ | 1 | 1 | 1 | 1 | 1 | 1 |

For a general quantum double model with a untwisted $K \subseteq G$ boundary, we use the information convex to identify deconfined topological excitations along the boundary, in contrast to the confined boundary excitations discussed in Ref. [27]. However, our calculations show that they share the same algebraic structure as in [27].

We use $\Sigma(\Omega_2)$ to demonstrate the relation between bulk anyons and boundary topological excitations, focusing on non-Abelian topological orders. For quantum double with Abelian group $G$ and any untwisted $K \subseteq G$ boundary, all extremal point of $\Sigma(\Omega_2)$ can be obtained by creating a bulk anyon pair $(a, \tilde{a})$ with a bulk string crossing $\Omega_2$, see FIG. 4(c). On the other hand, for a non-Abelian $G$ with a $K = \{ 1 \}$ boundary, bulk excitations in FIG. 4(c) can only explore a (convex) subset $\Sigma(\Omega_2)_{\text{bulk}} \subseteq \Sigma(\Omega_2)$ of the information convex $\Sigma(\Omega_2)$.

For $G = S_3$, $K = \{ 1 \}$ case, we find:

\[ \Sigma(\Omega_2)_{\text{bulk}} = \{ \sigma_{\Omega_2} \sigma_{\Omega_2} = p_1 \sigma^1_{\Omega_2} + p_c \sigma^c_{\Omega_2} + p_c \sigma^c_{\Omega_2} \} \]  

(7)

where \( \{ p_1, p_c, p_c \} \) is a probability distribution, and

\[ \sigma^c_{\Omega_2} \equiv \frac{1}{2} (\sigma^1_{\Omega_2} + \sigma^2_{\Omega_2}), \quad \sigma^c_{\Omega_2} \equiv \frac{1}{3} (\sigma^1_{\Omega_2} + \sigma^2_{\Omega_2} + \sigma^s_{\Omega_2}). \]  

(8)

The bulk anyon pair $(a, \tilde{a})$ associated with extremal points of $\Sigma(\Omega_2)_{\text{bulk}}$ are $a \in \{ 1, A, J^w \}$ for $\sigma^1_{\Omega_2}$, $a \in \{ J^x, J^y, J^z \}$ for $\sigma^c_{\Omega_2}$ and $a \in \{ K^a, K^b \}$ for $\sigma^c_{\Omega_2}$. In this case, while boundary topological excitations can lead to all extremal points in $\Sigma(\Omega_2)$, only one extremal point $\sigma^1_{\Omega_2}$ can be obtained by pure bulk excitations.

What are the relation and distinction between bulk and boundary topological excitations? First of all, each boundary topological excitation as in FIG. 4(b) can be deformed into the bulk as in FIG. 4(d) by local unitary operators, although the string may not completely detach from the boundary. However, such a bulk pair $(a, \tilde{a})$ connected by a boundary string in FIG. 4(d) should not be identified with a pair connected by a pure bulk string in FIG. 4(c), since they may correspond to different elements in the information convex.

In $G = S_3$, $K = \{ 1 \}$ quantum double, boundary excitation pair $(\alpha = r, \tilde{\alpha} = r^2)$ in FIG. 4(c) can be deformed into a bulk pair $(\alpha = J^x, \tilde{\alpha} = J^x)$ connected by a boundary string in FIG. 4(d), and they both lead to extremal point $\sigma^R_{\Omega_2} = \sigma^R_{\Omega_2}$ in FIG. 4(a). In contrast, a pair of bulk anyons $(J^x, J^y)$ in FIG. 4(c) only gives rise to $\sigma^c_{\Omega_2}$ in FIG. 4(a).

Secondly, each bulk anyon $a$ in FIG. 4(c) can be “moved” to the boundary in FIG. 4(c) by local unitary operators, and generally deformed into a superposition $\sum \alpha$ of boundary topological excitations. This process is governed by certain condensation rules $a \to \sum \alpha$ [20] [21] [27], which manifests in the information convex.

Specifically in $G = S_3$, $K = \{ 1 \}$ case, relation [8] of the information convex $\Sigma(\Omega_2)$ determines the anyon condensation rules of $K = \{ 1 \}$ boundary of $G = S_3$ quantum double, summarized below.

Here each of the bulk anyons $\{ J^x, J^y, J^z, K^a, K^b \}$ becomes a superposition of boundary topological excita-
Characterizing Anyon Condensation on the Boundary

Previously, $\Sigma(\Omega_3)$ already demonstrates the anyon condensation on the gapped boundary $\Omega_3$. Here we discuss a unique consequence of boundary anyon condensation on the gapped boundary $\Omega_3$. However this bulk anyon $a = J^w$ cannot turn into a single boundary superselection sector by any local unitary: instead it “condenses into” a superposition of boundary topological excitations $J_x \to r + r^2$, in accordance to relation (8).

**Summary**

We first notice that braiding a $(\alpha, \bar{a})$ pair around the boundary before annihilation, implemented by a unitary operator $W(\alpha)$ supported on the closed loop in Fig.5(c), do not change the energy density anywhere. Therefore this operation generates a (structure preserving) bijective map $\sigma_{\Omega_3} \in \Sigma(\Omega_3) \to W(\alpha)\sigma_{\Omega_3}W^\dagger(\alpha) \in \Sigma(\Omega_3)$. Explicitly, each $W(\alpha)$ keeps the extremal points $\sigma_{\Omega_3}$ and $\sigma_{\Omega_3}$ fixed but rotates on the sphere of $\sigma_{\Omega_3}(\theta, \phi)$. The set of rotations are generated by $W(r): (\theta, \phi) \to (\theta, \phi + 2\pi/3)$ and $W(s): (\theta, \phi) \to (\pi - \theta, -\phi)$, and they realizes the $S_3$ group action on sphere $S^2$.

While $\sigma_{\Omega_3}$ is obtained from the global ground state, the extremal point $\sigma_{\Omega_3}^A$ (or $\sigma_{\Omega_3}^J(\theta, \phi)$) is prepared by an excited state with a single anyon $A$ (or $J^w$) in the bulk, created by a string attached to the boundary as in Fig.5(b). The $(\theta, \phi)$ dependence for $\sigma_{\Omega_3}^J$ comes from the condensation multiplicity 2 in $J^w \to 2 \cdot 1$. The two ways to condense $J^w$ into the boundary leads to a 2-dimensional Hilbert space, and hence a set of reduced density matrices $\{\sigma_{\Omega_3}^J(\theta, \phi)\}$ parametrized by $(\theta, \phi) \in S^2$. Such condensation multiplicity and infinite extremal points are unique to non-Abelian topological orders.

Though $\sigma_{\Omega_3}^J$ with different $(\theta, \phi)$ share the same entanglement entropy and entanglement spectrum, their “interference pattern” in $\sigma_{\Omega_3}^J$ leaves a clear signature for the infinite extremal points $\sigma_{\Omega_3}^J(\theta, \phi)$. Moreover, recent progress in cold atoms allows to measure $tr[\sigma_{\Omega_3}^J(1) \cdot \sigma_{\Omega_3}^J(2)]$ in interference experiments, making the detection of information convex a potential possibility.

Consider annulus $\Omega_3$ covering the boundary in Fig.5 for $K = \{1\}$ gapped boundary of $G = S_3$ quantum double, the information convex $\Sigma(\Omega_3)$ has the following extremal points: $\sigma_{\Omega_3}^J$, $\sigma_{\Omega_3}^A$, and $\sigma_{\Omega_3}^J(\theta, \phi)$, where $(\theta, \phi)$ parameterize a sphere $S^2$ as shown in Fig.5(a)

$$
\Sigma(\Omega_3) = \{\sigma_{\Omega_3}|\sigma_{\Omega_3} = p_1\sigma_{\Omega_3}^J + p_A\sigma_{\Omega_3}^A + \int d\theta d\phi p(\theta, \phi) \sigma_{\Omega_3}^J(\theta, \phi)\}, \quad (9)
$$

with nonnegative $p_1$, $p_A$, $p(\theta, \phi)$ satisfying $p_1 + p_A + \int d\theta d\phi p(\theta, \phi) = 1$. Moreover $\Sigma(\Omega_3)$ has the following structure:

$$
\sigma_{\Omega_3}^J \cdot \sigma_{\Omega_3}^J = \sigma_{\Omega_3}^J \cdot \sigma_{\Omega_3}^J(\theta, \phi) = \sigma_{\Omega_3}^J(\theta, \phi) = 0; \quad (10)
$$

$$
S(\sigma_{\Omega_3}^J) = S(\sigma_{\Omega_3}^J) + \ln d_A, \quad \frac{tr[\sigma_{\Omega_3}^J(1) \cdot \sigma_{\Omega_3}^J(2)\}]}{tr[\sigma_{\Omega_3}^J(1) \cdot \sigma_{\Omega_3}^J(2)\}]} = \frac{1}{d_{J^x}} \cdot \frac{1 + \hat{n} \cdot \hat{n}'}{2}. \quad (13)
$$

Where unit vector $\hat{n} = (\sin \theta \cos \phi, \sin \theta \sin \phi, \cos \theta)$, and similarly for $\hat{n}'$ in terms of $(\theta', \phi').$

We now first notice that braiding a $(\alpha, \bar{\alpha})$ pair around the boundary before annihilation, implemented by a unitary operator $W(\alpha)$ supported on the closed loop in Fig.5(c), do not change the energy density anywhere. Therefore this operation generates a (structure preserving) bijective map $\sigma_{\Omega_3} \in \Sigma(\Omega_3) \to W(\alpha)\sigma_{\Omega_3}W^\dagger(\alpha) \in \Sigma(\Omega_3)$. Explicitly, each $W(\alpha)$ keeps the extremal points $\sigma_{\Omega_3}$ and $\sigma_{\Omega_3}$ fixed but rotates on the sphere of $\sigma_{\Omega_3}(\theta, \phi)$. The set of rotations are generated by $W(r): (\theta, \phi) \to (\theta, \phi + 2\pi/3)$ and $W(s): (\theta, \phi) \to (\pi - \theta, -\phi)$, and they realizes the $S_3$ group action on sphere $S^2$.

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Though $\sigma_{\Omega_3}^J$ with different $(\theta, \phi)$ share the same entanglement entropy and entanglement spectrum, their “interference pattern” in $\sigma_{\Omega_3}^J$ leaves a clear signature for the infinite extremal points $\sigma_{\Omega_3}^J(\theta, \phi)$. Moreover, recent progress in cold atoms allows to measure $tr[\sigma_{\Omega_3}^J(1) \cdot \sigma_{\Omega_3}^J(2)]$ in interference experiments, making the detection of information convex a potential possibility.

**Summary**

We have introduced the information convex $\Sigma(\Omega)$, the set of reduced density matrices that minimize energy in subsystem $\Omega$, to capture the topological invariants of a 2D topological order both in the bulk and on the gapped boundaries. Using quantum double models and their gapped boundaries as an example, we show how the information convex reveals and characterizes (i) bulk anyons (or bulk superselection sectors); (ii) boundary topological excitations (or boundary superselection sectors); (iii) the condensation rules from bulk anyons to boundary topological excitations. Recent progress in cold atoms provides a potential measurement for the information convex structure in interference experiments. As a powerful tool to study topological phases, the infor-
Information convex can also be generalized to topological orders in higher spatial dimensions and fracton orders\cite{36}.

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Supplemental Material for “Characterizing topological orders by the information convex”

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I. THE INFORMATION CONVEX

We provide a definition of information convex $\Sigma(\Omega, \Omega')$ and $\Sigma(\Omega)$ for frustration-free local Hamiltonians and discuss some basic properties. Generalizations beyond frustration-free local Hamiltonians are briefly discussed.

A. Frustration-free local Hamiltonians

We use the following definition of frustration-free local Hamiltonians in the context of lattice models. This definition of frustration-free local Hamiltonian is similar to the definition in [1].

**Definition I.1** (Frustration-free local Hamiltonians). A frustration-free local Hamiltonian is a Hamiltonian written as $H = \sum_i h_i$, which satisfies:
1) Each $h_i$ is a Hermitian operator acting on links within a local region of finite size $R$. To simplify our notations below, we will assume the minimal eigenvalue of each $h_i$ to be 0.
2) $h_i P_0 = 0$, $\forall i$, where $P_0$ is the projector onto the subspace of ground states of $H$. In other words, every $h_i$ obtains its minimal eigenvalue 0 on a ground state $|\psi\rangle$, i.e. $h_i |\psi\rangle = 0$, $\forall i$.

Let $H_{\Omega'}$ be the Hamiltonian of subsystem $\Omega'$, i.e. keeping terms of $H$ which are supported on the subsystem $\Omega'$. One can easily check the ground state $|\psi\rangle$ minimize the Hamiltonian $H_{\Omega'}$, i.e. $H_{\Omega'} \otimes 1_{\bar{\Omega}} |\psi\rangle = 0$. Where $\bar{\Omega}'$ is the complement of $\Omega'$.

B. The information convex for frustration-free local Hamiltonians

Let us define the information convex for a general frustration-free local Hamiltonian satisfying definition I.1 and study a few basic properties. Note that frustration-free local Hamiltonians include commuting projector Hamiltonians has a subset. Therefore, the definition applies to many exactly solved models of topological orders in 2D, 3D, exactly solved SET models and models related to these exactly solved models by a finite depth quantum circuit.

**Definition I.2** (The information convex). For a frustration-free local Hamiltonian, define the information convex $\Sigma(\Omega, \Omega')$ to be the set of reduced density matrices on subsystem $\Omega$ obtained from reduced density matrices on a larger subsystem $\Omega'$ ($\Omega \subseteq \Omega' \subseteq S$, $S$ is the whole system) which minimize the Hamiltonian $H_{\Omega'}$, i.e.:

$$\Sigma(\Omega, \Omega') \equiv \{ \sigma_\Omega \mid \sigma_\Omega = \text{tr}_{[\Omega']\setminus\Omega} \rho_{\Omega'} \text{ where } \text{tr}[H_{\Omega'} \rho_{\Omega'}] = 0 \}. \tag{1}$$

For the set to be interesting, we require $\Omega'$ to contain all terms in $H$ which overlap with $\Omega$. We use a simpler notation $\Sigma(\Omega)$ when we choose the minimal $\Omega'$.

The definition of $\Sigma(\Omega, \Omega')$ may be motivated by the consideration that while the set of general reduced density matrices on $\Omega$ has a complicated structure due to the large number of possible excitations, the set of reduced density matrices which locally minimalize the energy around $\Omega$ should have much simpler structure. Another motivation is that, as we will see, for topological orders $\Sigma(\Omega, \Omega')$ is a small dimensional convex set whose structures contain information about the phase.

![FIG. 1: An illustration of subsystem $\Omega$ and $\Omega'$. Where $\Omega \subseteq \Omega'$.](image)

**Theorem I.1.** $\Sigma(\Omega, \Omega')$ is a convex set.

Here, the set $\Sigma(\Omega, \Omega')$ being a convex set means the condition that for any two reduced density matrices $\sigma^{(1)}_\Omega, \sigma^{(2)}_\Omega \in \Sigma(\Omega, \Omega')$ and arbitrary $p \in [0, 1]$, we always have $p \sigma^{(1)}_\Omega + (1-p)\sigma^{(2)}_\Omega \in \Sigma(\Omega, \Omega')$. 


Proof. For \( \sigma_1^{(1)}, \sigma_2^{(2)} \in \Sigma(\Omega, \Omega') \), by definition, there exist \( \rho_1^{(1)} \) and \( \rho_2^{(2)} \) such that:

\[
\sigma_1^{(1)} = \text{tr}_{[\Omega \setminus \Omega]} \rho_1^{(1)}, \quad \sigma_2^{(2)} = \text{tr}_{[\Omega \setminus \Omega]} \rho_2^{(2)}, \quad \text{tr}[\rho_1^{(1)} H_{\Omega'}] = \text{tr}[\rho_2^{(2)} H_{\Omega'}] = 0.
\]

(2)

Therefore, \( p \rho_1^{(1)} + (1 - p) \rho_2^{(2)} \) with \( p \in [0, 1] \) is also a density matrix that minimize the Hamiltonian \( H_{\Omega'} \), and:

\[
p \sigma_1^{(1)} + (1 - p) \sigma_2^{(2)} = \text{tr}_{[\Omega \setminus \Omega']} [p \rho_1^{(1)} + (1 - p) \rho_2^{(2)}] \Rightarrow p \sigma_1^{(1)} + (1 - p) \sigma_2^{(2)} \in \Sigma(\Omega, \Omega').
\]

(3)

\[\square\]

**Theorem I.2.** \( \Sigma(\Omega, \Omega') \) is a compact subset of \( R^N \). Where \( N \) is a finite number which could depend on the choice of \( \Omega \) and \( \Omega' \).

Proof. The set of all reduced density matrices on \( \Omega \) is a compact (closed and bounded) subset of \( R^M^2 \). Where \( M = \dim \mathcal{H}(\Omega) \), the dimension of the Hilbert space on subsystem \( \Omega \). \( M \) is finite for a lattice model with \( \Omega \) contains a finite number of links (or sites) and each link (or site) has a corresponding finite dimensional Hilbert space. \( \Sigma(\Omega, \Omega') \) is a subset of the set of all reduced density matrices on \( \Omega \) and therefore it is a bounded subset of \( R^M^2 \). Furthermore, \( \Sigma(\Omega, \Omega') \) is closed. Therefore, \( \Sigma(\Omega, \Omega') \) is a compact subset of \( R^N \) with finite \( N \).

\[\square\]

Remark. Theorem I.1 and Theorem I.2 shows that \( \Sigma(\Omega, \Omega') \) is a compact convex subset of \( R^N \) for some finite \( N \). This applies to all the convex sets we will discuss in this paper. We will call them convex sets for short and it is understood that they are compact convex sets for some \( R^N \) for some finite \( N \).

**Definition I.3** (Extremal point). An extremal point of \( \Sigma(\Omega, \Omega') \) is a reduced density matrix \( \sigma_\Omega \in \Sigma(\Omega, \Omega') \) such that if \( \sigma_\Omega = p \sigma^{(1)}_\Omega + (1 - p) \sigma^{(2)}_\Omega \) with \( \sigma^{(1)}_\Omega, \sigma^{(2)}_\Omega \in \Sigma(\Omega, \Omega') \) and \( p \in (0, 1) \), then \( \sigma^{(1)}_\Omega = \sigma^{(2)}_\Omega = \sigma_\Omega \).

In other words, an extremal point is a point (reduced density matrix) in \( \Sigma(\Omega, \Omega') \) which could not be prepared by other points in \( \Sigma(\Omega, \Omega') \) with a probability distribution.

**Proposition I.3.** \( \Sigma(\Omega, \Omega') \) is uniquely determined by the set of extremal points. Furthermore, if \( \Sigma(\Omega, \Omega') \) is n-dimensional, then any point in \( \Sigma(\Omega, \Omega') \) can be written as a convex combination of at most \( n + 1 \) extremal points.

Here, convex combination is a combination with a probability distribution \( \{p_i\}_{i=1}^{n+1} \). In other words, for any \( \sigma_\Omega \in \Sigma(\Omega, \Omega') \) it is possible to find a (sub)set of extremal points \( \{\sigma^{(1)}_\Omega\}_{i=1}^{n+1} \) and a probability distribution \( \{p_i\}_{i=1}^{n+1} \) such that \( \sigma_\Omega = \sum_{i=1}^{n+1} p_i \sigma^{(1)}_\Omega \).

Proof. First, notice that \( \Sigma(\Omega, \Omega') \) is a compact convex subset of \( R^N \) for some finite \( N \), i.e. the result of Theorem I.1 and Theorem I.2. Then, use the Minkowski-Caratheodory Theorem [18], which says that, for \( \Sigma \), a compact convex subset of dimension \( n \) (\( n \) is finite and \( \Sigma \) is a subset of \( R^N \) for some finite \( N \)), any point in \( \Sigma \) can be written as a convex combination of at most \( n + 1 \) extremal points.

\[\square\]

**Proposition I.4.** Every extremal point of \( \Sigma(\Omega, \Omega') \) has a purification in \( \Omega' \). In other words, there exists a pure state \( |\varphi\rangle_{\Omega'} \) such that \( \sigma_\Omega = \text{tr}_{[\Omega \setminus \omega]} |\varphi\rangle_{\Omega'} \langle \varphi| \), if \( \sigma_\Omega \) is an extremal point of \( \Sigma(\Omega, \Omega') \).

In the following, we discuss a few properties of \( \Sigma(\Omega, \Omega') \) when one tries to change \( \Omega \) or \( \Omega' \).

**Theorem I.5.** One obtains a convex subset of \( \Sigma(\Omega, \Omega') \) when one replaces \( \Omega' \) by a larger subsystem \( \Omega'' \), i.e.:

\[
\Sigma(\Omega, \Omega') \subseteq \Sigma(\Omega, \Omega'') \text{ for } \Omega' \subseteq \Omega''.
\]

\[\square\]

**Corollary I.5.1.** Let \( |\psi\rangle \) be a ground state of frustration-free local Hamiltonian \( H \). Then, the corresponding reduced density matrix \( \sigma_\Omega^{(1)} \equiv \text{tr}_{[\omega]} |\psi\rangle \langle \psi| \) satisfies \( \sigma_\Omega^{(1)} \in \Sigma(\Omega, \Omega') \).

**Theorem I.6.** The mapping \( \Gamma : \Sigma(\Omega, \Omega') \to \Sigma(\omega, \Omega') \) defined by \( \Gamma[\sigma_\Omega] = \text{tr}_{[\Omega \setminus \omega]} \sigma_\Omega \) is surjective and it preserves the convex structure. Where \( \omega \subseteq \Omega \).

Proof. The mapping \( \Gamma \) is surjective. This follows from \( \text{tr}_{[\Omega \setminus \omega]} = \text{tr}_{[\Omega \setminus \omega]} \text{tr}_{[\Omega \setminus \Omega]} \). The following is about the convex structure. Let \( \sigma^{(1)}_\Omega, \sigma^{(2)}_\Omega \in \Sigma(\Omega, \Omega') \), and \( p \in [0, 1] \). From the linearity of the \( \text{tr}_{[\Omega \setminus \omega]} \) operation, we have:

\[
\Gamma[p \sigma^{(1)}_\Omega + (1 - p) \sigma^{(2)}_\Omega] = p \Gamma[\sigma^{(1)}_\Omega] + (1 - p) \Gamma[\sigma^{(2)}_\Omega].
\]

This result shows (by definition) that the mapping \( \Gamma \) preserves the convex structure.

\[\square\]

Theorem I.6 gives constraints for number of extremal points.
Corollary I.6.1. If the number of extremal points of \( \Sigma(\Omega, \Omega') \) is a finite number \( N_\Omega \), then the number of extremal points of \( \Sigma(\omega, \Omega') \) is a finite number \( N_\omega \) satisfying \( N_\omega \leq N_\Omega \). Furthermore, an extremal point of \( \Sigma(\omega, \Omega') \) must be the image of some extremal point of \( \Sigma(\Omega, \Omega') \) under the mapping \( \Gamma \). Where \( \omega \subseteq \Omega \).

Proof. This result follows from the fact that the image of a nonextremal point of \( \Sigma(\Omega, \Omega') \) cannot be an extremal point of \( \Sigma(\omega, \Omega') \) unless it is also the image of an extremal point of \( \Sigma(\Omega, \Omega') \).

Remark. Constraints for the case with infinite number of extremal points may also be deduced from Theorem I.6.

C. Beyond frustration-free local Hamiltonians

In this section, we briefly discuss what we expect for generalizations of information convex to models beyond frustration-free local Hamiltonians and hope that more rigorous results will be available in the future.

Let us first consider a frustration-free local Hamiltonian \( H \) with \( H_{\Omega'} \) having a finite energy gap \( \Delta \) (between the ground states and the 1st excited state) and consider a generalization of \( \Sigma(\Omega, \Omega') \) into \( \Sigma(\Omega, \Omega'|\epsilon) \). Where \( 0 \leq \epsilon \ll \Delta \).

\[
\Sigma(\Omega, \Omega'|\epsilon) \equiv \{ \sigma_\Omega(\epsilon) \mid \sigma_\Omega(\epsilon) = tr_{[\Omega'}[\rho_{\Omega'}] \} \quad \text{where} \quad tr[H_{\Omega'}\rho_{\Omega'}] \in [0, \epsilon] \}.
\] (6)

It is straightforward to show that \( \Sigma(\Omega, \Omega'|\epsilon) \) is a convex set. Comparing with Eq.(1), if \( \epsilon > 0 \), then \( \rho_{\Omega'} \) can have small mixture of excited states. Due to the large number of excited states, the convex set \( \Sigma(\Omega, \Omega'|\epsilon) \) with \( \epsilon > 0 \) will be of a large dimension even if \( \Sigma(\Omega, \Omega') \) is a small dimensional convex set. Nevertheless, \( \Sigma(\Omega, \Omega'|\epsilon) \) stretches out in the directions of excited states by a “distance” suppressed by \( \epsilon/\Delta \). Here, the distance could be measured by the minimal deviation of the fidelity (between \( \sigma_\Omega(\epsilon) \in \Sigma(\Omega, \Omega'|\epsilon) \) and \( \sigma_\Omega \in \Sigma(\Omega, \Omega') \)) from 1:

\[
l(\sigma_\Omega(\epsilon)) \equiv [1 - F(\sigma_\Omega(\epsilon), \sigma_\Omega)]_{\text{min}}, \quad \text{with} \quad \sigma_\Omega(\epsilon) \in \Sigma(\Omega, \Omega'|\epsilon) \quad \text{and} \quad \sigma_\Omega \in \Sigma(\Omega, \Omega').
\] (7)

Where the fidelity \( F(\rho, \sigma) \equiv \left( tr\sqrt{\rho^{1/2}\sigma\rho^{1/2}} \right)^2 \). One can show that:

\[
l(\sigma_\Omega(\epsilon)) \leq \frac{\epsilon}{\Delta} \quad \text{for} \quad \forall \sigma_\Omega(\epsilon) \in \Sigma(\Omega, \Omega'|\epsilon).
\] (8)

For \( 0 \leq \epsilon \ll \Delta \), we could still approximately treat the convex set \( \Sigma(\Omega, \Omega'|\epsilon) \) as small dimensional with the same structures as \( \Sigma(\Omega, \Omega') \).

Now let us consider the case beyond frustration-free local Hamiltonians. We focus on the the case that local perturbations are added to a gapped frustration-free local Hamiltonians (with energy gap \( \Delta \)), the case discussed in [1, 2]. Note that, we do need to generalize \( \Sigma(\Omega, \Omega') \) into \( \Sigma(\Omega, \Omega'|\epsilon) \) with some \( 0 \leq \epsilon \ll \Delta \) in order to get meaningful structures. Consider a model with topological order and the system is defined on a torus \( S = T^2 \) with length \( L \) and a correlation length \( \xi \ll L \). For the unperturbed model, the ground state degeneracy is exact and \( \Sigma(S, S) \) is a convex set with (an infinite number of) extremal points in one to one correspondence with the (pure) ground states. However, local perturbations will split the ground state energies by the order \( \Delta \exp(-L/\xi) \), for a more rigorous bound of the energy splitting see [1, 2]. Therefore, in order to construct a convex set with similar structure as the \( \Sigma(S, S) \) of the unperturbed model, \( \Sigma(S, S) \) is no longer a good choice. Since it does not keep all the low energy states corresponds to the degenerate ground states of the unperturbed model. We need to choose \( \Sigma(S, S'|\epsilon) \) with \( \epsilon \sim \Delta \exp(-L/\xi) \) for the perturbed theory.

More generally, we expect the \( \Sigma(\Omega, \Omega') \) for the unperturbed model, with \( \Omega' \) thicker than \( \Omega \) by length \( L' \gg \xi \) be generalized into \( \Sigma(\Omega, \Omega'|\epsilon) \) with \( \epsilon \sim \Delta \exp(-L'/\xi) \). Since \( \exp(-L'/\xi) \ll 1 \), the convex set \( \Sigma(\Omega, \Omega'|\epsilon) \) is approximately small dimensional and it should have very similar structure to the \( \Sigma(\Omega, \Omega') \) in the unperturbed model.

II. SOME USEFUL GROUP THEORY

We collect some results useful in the study of quantum double models in Sec.III which could be appreciated at the level of finite group.
A. Finite groups and representations - some basics

We summarize some basic results about finite groups and representations. Our notation is adapted from [3–5].

Let $G$ be a finite group. $|G|$ is the number of group elements in $G$. We use $(G)_{ir}$ to denote the set of irreducible representations of $G$ and $(G)_{cj}$ to denote the set of conjugacy classes of $G$. For a group element $g \in G$, we use $\bar{g}$ to denote its inverse element.

For a (unitary) representation $R$ of $G$, we denote its dimension using $n_R$ and $\Gamma_R(g)$ is a $n_R \times n_R$ dimensional unitary matrix associated with representation $R$ (in a chosen basis) and $\Gamma_R^{jj'} (g)$ with $j, j'=1, \ldots, n_R$ is the components of the matrix. $\Gamma_R^{jj'}$ is the complex conjugate of $\Gamma_R^{jj'}$.

The following results are useful:

\[
\sum_{g\in (G)_{ir}} n_R^2 = |G|,
\]

\[
\sum_{g \in G} \Gamma_R^{ab} (g) \Gamma_R^{a'b'} (g) = \delta_{R,R} \frac{|G|}{n_R} \delta_{a,a'} \delta_{b,b'} \text{ for } R, R' \in (G)_{ir}.
\]

Let $c \in (G)_{cj}$ be a conjugacy class, i.e. $c \equiv \{grg|g \in G\}$, where $r_c \in G$ is a representative of $c$. For a finite group, the number of conjugacy classes $c \in (G)_{cj}$ equals the number of irreducible representations $R \in (G)_{ir}$. Given a conjugacy class $c$ and a representative $r_c \in c$, a centralizer group $E(c) = \{ g \in G | gr_c = r_c g \}$ can be defined. Note that, $E(c)$ depends on the choice of $r_c$ in general. Let $|c|$ be the number of elements in $c$, one can check $|c| \cdot |E(c)| = |G|$.

Let $P(c) = \{ p_i \}_{i=1}^{[c]}$ be a set of representatives of $G/E(c)$. It satisfies:

1) $p_i E(c) \bigcap p_j E(c) = \emptyset$ for $i \neq j$ and $\bigcup_{i=1}^{[c]} p_i E(c) = G$. It implies that there is a unique decomposition of a group element $g \in G$ as $p_i m$, with $m \in E(c)$.

2) $c = \{ c_i \}_{i=1}^{[c]}$, where $c_i \equiv p_r p_b$.

Let $K \subseteq G$ be a subgroup of $G$. Let $T \in K \setminus G/K$ be a double coset, i.e. $T \equiv \{ k_1 r_T k_2 | k_1, k_2 \in K \} = K r_T K$, where $r_T \in G$ is a representative of $T$. Given $T$ and $r_T$, one can define $K r_T = K \bigcap K r_T$ which is a subgroup of $K$. Note that, $K r_T$ depends on the choice of $r_T$ in general.

Let $Q = \{ q_{i} \}_{i=1}^{[Q]}$ be a set of representatives of $K / K r_T$. It satisfies:

1) $|Q| = |K| / |K r_T| = |T| / |K|$. Where $|T|$ is the number of elements in $T$.

2) $q_i K r_T \bigcap q_j K r_T = \emptyset$ for $i \neq j$ and $\bigcup_{i=1}^{[Q]} q_i K r_T = K$.

3) $q_i r_T K \bigcap q_j r_T K = \emptyset$ for $i \neq j$ and $T = \bigcup_{i=1}^{[Q]} q_i r_T K$. It implies that there is a unique decomposition of $g \in T$ as $g = q_i r_T k$, where $q_i \in Q$ and $k \in K$.

B. Invariant operators and invariant density matrices on the group Hilbert space $\mathcal{H}_G$

**Definition II.1** (The group Hilbert space). The group Hilbert space for a finite group $G$ is defined as $\mathcal{H}_G \equiv \text{span}\{ |g\rangle | g \in G \}$. Where $\langle g|h \rangle = \delta_{g,h}$ with $g, h \in G$. In other words, $\{ |g\rangle | g \in G \}$ is an orthonormal basis and the dimension of $\mathcal{H}_G$ is $\dim \mathcal{H}_G = |G|$.

Consider the following mappings which take an operator acting on $\mathcal{H}_G$ to another operator acting on $\mathcal{H}_G$:

1) $L_g$-mapping is defined by $O \rightarrow L_g O L_g^\dagger$. Where $L_g$ is an unitary operator such that $L_g |h\rangle = |gh\rangle$.

2) $\bar{L}_g$-mapping is defined by $O \rightarrow \bar{L}_g O \bar{L}_g^\dagger$, where $\bar{L}_g$ is an unitary operator such that $\bar{L}_g |h\rangle = \bar{|h\rangle}$. Where $\bar{g}$ is the inverse of $g$.

**Definition II.2** ($L_K$-invariant and $\bar{L}_K$ invariant). An operator acting on $\mathcal{H}_G$ is said to be:

1) $L_K$-invariant if it is invariant under $L_k$-mapping for $\forall k \in K$. Where $K \subseteq G$ is a subgroup.

2) $\bar{L}_K$-invariant if it is invariant under $\bar{L}_k$-mapping for $\forall k \in K$. Where $K \subseteq G$ is a subgroup.

Our next task is to find the general form of certain invariant operators. In order to do so, the following basis will be useful.

**Proposition II.1.** $\mathcal{H}_G$ has an orthonormal basis $\{ |a,b; R\rangle \}$, with $a,b = 1, \ldots, n_R$ and $R \in (G)_{ir}$. Where

\[
|a,b; R\rangle \equiv \sqrt{\frac{n_R}{|G|}} \sum_{g \in G} \Gamma_R^{ab} (g) |g\rangle.
\]

**Proof.** First, check $\langle a,b; R|a',b'; R' \rangle = \delta_{R,R'} \delta_{a,a'} \delta_{b,b'}$ using Eq.(10). Then, check that the dimension of the vector space spanned by $\{ |a,b; R\rangle \}$ is $|G|$ using Eq.(9). \qed
Proposition II.2. The space of $L_G$-invariant operators acting on $\mathcal{H}_G$ is the complex vector space $\text{span}\{\sum_{a=1}^{n_R} |a, b; \cdots \rangle \langle a, b; \cdots | \} \quad \text{for } G \text{ quantum double with } a K \subseteq G \text{ boundary is }$

$$H = \sum_{v} (1 - A_v) + \sum_{f} (1 - B_f) + \sum_{v'} (1 - A_{v'}^k).$$

Proof. First, note that the space of all operators acting on $\mathcal{H}_G$ is a complex vector space spanned by $\{ |a, b; \cdots \rangle \langle a', b', \cdots | \}$. Second, show that space of $L_G$-invariant operators is spanned by $\{ \sum_{h \in G} L_h |a, b; R \rangle \langle a', b', R' | L_h^\dagger \}$. Then, show that

$$\text{span}\{ \sum_{h \in G} L_h |a, b; R \rangle \langle a', b', R' | L_h^\dagger \} = \text{span}\{ \sum_{a=1}^{n_R} |a, b; R \rangle \langle a, b; R | \}. \quad (12)$$

In this step, $L_h |a, b; R \rangle = \sum_{c=1}^{n_R} \Gamma_{R}^c (h) |c, b; R \rangle$ and Eq.(10) is used. □

Proposition II.3. The set of $L_G$-invariant density matrices is a convex set $\Sigma_G(L_G)$ with extremal points parameterized by a manifold $S^{2n_R-1}/S^1$ for each $R \in (G)_{ir}$. The manifold $S^{2n_R-1}/S^1$ is parameterized by complex numbers $\{ z_b \}$ under equivalence $\{ z_b \} \sim \{ z_b e^{i\theta} \}$. Where $b = 1, \cdots, n_R$ and $\sum_{b=1}^{n_R} |z_b|^2 = 1$. The corresponding density matrix is

$$\rho_R(z) \equiv \frac{1}{n_R} \sum_{a=1}^{n_R} |z(a; R)\rangle \langle z(a; R)| \quad \text{with} \quad |z(a; R)\rangle \equiv \sum_{b=1}^{n_R} z_b |a, b; R \rangle, \quad R \in (G)_{ir}. \quad (13)$$

Proposition II.4. The space of $L_G$-invariant and $\tilde{L}_G$-invariant operators acting on $\mathcal{H}_G$ is the complex vector space $\text{span}\{ \sum_{a,b=1}^{n_R} |a, b; R \rangle \langle a, b; R | \} \quad \text{with } R \in (G)_{ir}$. Proof. First, notice the result in proposition II.2 that the space of $L_G$-invariant operators is spanned by $\{ \sum_{a=1}^{n_R} |a, b; R \rangle \langle a, b; R' | \}$ with $b' = 1, \cdots, n_R$ and $R \in (G)_{ir}$. Second, show that the space of $L_G$-invariant and $L_G$-invariant operators is spanned by $\{ \sum_{h \in G} \sum_{a=1}^{n_R} \tilde{L}_h |a, b; R \rangle \langle a, b; R | \tilde{L}_h^\dagger \}$. Finally, show that

$$\text{span}\{ \sum_{h \in G} \sum_{a=1}^{n_R} \tilde{L}_h |a, b; R \rangle \langle a, b; R | \tilde{L}_h^\dagger \} = \text{span}\{ \sum_{a,b=1}^{n_R} |a, b; R \rangle \langle a, b; R | \}. \quad (14)$$

In this step, $\tilde{L}_h |a, b; R \rangle = \sum_{c=1}^{n_R} \tilde{\Gamma}_{R}^c (h) |c, b; R \rangle$ and Eq.(10) is used. □

Proposition II.5. The set of $L_G$-invariant and $\tilde{L}_G$-invariant density matrices is a convex set $\Sigma_G(L_G, \tilde{L}_G)$ with extremal points

$$\rho_R \equiv \frac{1}{n_R} \sum_{a,b=1}^{n_R} |a, b; R \rangle \langle a, b; R |, \quad R \in (G)_{ir}. \quad (15)$$

III. $G$ QUANTUM DOUBLE WITH $K \subseteq G$ BOUNDARY

A. The Hamiltonian of $G$ quantum double with $K \subseteq G$ boundary

A quantum double model on an orientable 2D lattice without boundary is defined for any finite group $G$ [3, 6]. Let us consider a square lattice shown in Fig.2, generalization to other lattices is straightforward. On a lattice with boundary, a gapped boundary can be defined for each subgroup $K \subseteq G$ [5, 7]. In addition to the subgroup $K$, the boundary can depend on a 2-cocycle of $K$ [7]. In the current work, we focus on the untwisted boundaries, i.e. those with trivial 2-cocycles.

The total Hilbert space is a tensor product of the Hilbert space on each link. The Hilbert space for each bulk link (labeled by $e$) is $|G|$ dimensional: $\mathcal{H}_e = \text{span}\{|g,e\rangle \quad |g \in G \}$, where $\{ |g,e\rangle \quad |g \in G \}$ is an orthonormal basis. The Hilbert space for each boundary link (labeled by $e'$, thicker links in Fig.2) is $|K|$ dimensional: $\mathcal{H}_{e'} = \text{span}\{|k,e'\rangle \quad |k \in K \}$, where $\{ |k,e'\rangle \quad |k \in K \}$ is an orthonormal basis. We denote a vertex in the bulk (bulk vertex) as $v$ and a vertex on the boundary (boundary vertex) as $v'$ and denote a face as $f$. A bulk site $s = (v, f)$ is a pair contain a face $f$ and an adjacent bulk vertex $v$, a boundary site $s' = (v', f)$ is a pair contain a face $f$ and an adjacent boundary vertex $v'$. Our Hamiltonian for $G$ quantum double with a $K \subseteq G$ boundary is

$$H = \sum_v (1 - A_v) + \sum_f (1 - B_f) + \sum_{v'} (1 - A_{v'}^k). \quad (16)$$
FIG. 2: A square lattice with a boundary, generalization to other lattices is straightforward. Labels are: bulk link $e$, boundary link $e'$, bulk vertex $v$, boundary vertex $v'$ and face $f$. Note that in our model, $e'$, $v'$ only lie in the 1D boundary lattice shown in thicker line.

Constants are added into the Hamiltonian simply to keep the minimal eigenvalue to be zero. Where

$$A_v \equiv \frac{1}{|G|} \sum_{g \in G} A^2_{vg}; \quad B_f \equiv B^2_s; \quad A^K_{v'} \equiv \frac{1}{|K|} \sum_{k \in K} A^K_{vk}.$$ (17)

The operators $A^2_{vg}, B^2_s, A^K_{vk}$ with $g, h \in G$ and $k \in K$ each acts on a few links around a vertex or a face. They are defined in Fig.3.

FIG. 3: The diagram shows the definitions of the operators $A^2_{vg}, B^2_s, A^K_{vk}$ with $g, h \in G$ and $k \in K$.

One can easily check that all terms in the Hamiltonian commute, and that $A_v, B_f, A^K_{v'}$ are projectors (so do $1 - A_v, 1 - B_f, 1 - A^K_{v'}$), i.e. $A^2_v = A_v, B^2_f = B_f, (A^K_{v'})^2 = A^K_{v'}$. A state $|\psi\rangle$ is a ground state if and only if it satisfies:

$$A_v |\psi\rangle = B_f |\psi\rangle = A^K_{v'} |\psi\rangle = |\psi\rangle, \quad \forall v, f, v'.$$ (18)

For a system with $D^2$ topology (i.e. cover a disk $D^2$ with lattice), it can be shown that there is a unique ground state $|\psi\rangle$ which can be written as (up to normalization):

$$|\psi\rangle = \prod_v A_v \cdot \prod_{v'} A^K_{v'} |1, 1, \cdots, 1\rangle.$$ (19)

Here, 1 represents the identity of group $G$ (or $K$). This ground state is an equal weight superposition of all “zero flux” configurations. Let us define the reduced density matrix on subsystem $\Omega$ calculated from the unique ground state $|\psi\rangle$ as $\sigma_\Omega^1$, i.e. $\sigma_\Omega^1 \equiv tr_{\bar{\Omega}}|\psi\rangle\langle\psi|$, where $\bar{\Omega}$ is the complement of $\Omega$. It will appear many times in later sections.

Remark. Our Hilbert space and Hamiltonian is closely related to the ones in previous works [5, 7], but there are differences. Our Hilbert space is “smaller” than both [7] and [5]. It is the effective Hilbert space when certain terms in the Hamiltonians [5, 7] are not excited. Our Hamiltonian is the effective Hamiltonian of the models [5, 7] when no excitations of the types discussed above. The excitations which could be created in our model also appear in the models in [5, 7], but some of excitations which could be created in [7] or [5] may not be created in our model.
Especially, the confined excitations inside a boundary [5] do not exist in our model. On the other hand, as will be
discussed below, our model allows a set of deconfined topological excitations carry boundary superselection sectors α
and quantum dimension $d_α$. The set of $(α, d_α)$ is coincident with what has been discussed in [5] for confined boundary
excitations. See Eq.(45) and Sec.III C,III F,III H for more details.

B. The calculation of the information convex for $G$ quantum double with $K \subseteq G$ boundary

The $G$ quantum double with $K \subseteq G$ boundary is a model with commuting projector Hamiltonian Eq.(16), and on a
ground state, each projector obtains its minimal eigenvalue 0. Therefore, it is an example of frustration-free local
Hamiltonian. The information convex $Σ(Ω,Ω′)$ is a convex set uniquely determined by the set of extremal points, see
Theorem I.3. Therefore, our task here is to find the set of extremal points.

Consider reduced density matrix $ρ_{Ω′}$ which minimize the Hamiltonian $H_{Ω′}$. Let us write $ρ_{Ω′}$ in its diagonal form
$ρ_{Ω′} = \sum_\alpha λ_\alpha |α⟩_{Ω′} ⟨α|$, with $⟨α|β⟩_{Ω′} = δ_{α,β}$.

$$tr(H_{Ω′} ρ_{Ω′}) = 0 \iff H_{Ω′} |α⟩_{Ω′} = 0 \forall α.$$  (20)

In other words, each $|α⟩_{Ω′}$ is a ground state of $H_{Ω′}$. According to proposition I.4, to find the extremal points
of $Σ(Ω,Ω′)$ it is enough to consider the set of reduced density matrices $σ_Ω = tr_{Ω′\setminus Ω}|α⟩_{Ω′} ⟨α|, for f ∈ Ω′.$

Let us take the minimal $Ω′$, i.e. consider $Σ(Ω)$. In this case, $H_{Ω′} |α⟩_{Ω′} = 0$ is equivalent to the following conditions:

(a) $B_f|α⟩_{Ω′} = |α⟩_{Ω′}$, for $f \in \partial Ω$.

(b) $B_f|α⟩_{Ω′} = |α⟩_{Ω′}$, for $f \in Ω$.

(c) $A^B_α|α⟩_{Ω′} = |α⟩_{Ω′}$ and $A^A_α|α⟩_{Ω′} = |α⟩_{Ω′}$, for $v, v′ ∈ Ω$ and $g ∈ G, k ∈ K$.

(d) $A^B_α|α⟩_{Ω′}$ and $A^A_α|α⟩_{Ω′} = |α⟩_{Ω′}$, for $v, v′ ∈ \partial Ω$ and $g ∈ G, k ∈ K$.

Where, we say $f ∈ Ω$ if $B_f$ is supported on $Ω$; we say $f ∈ Ω′ \setminus Ω$ if $B_f$ has support overlap with $Ω$ but not supported
on $Ω$: we say $v, v′ ∈ Ω$ if $A^A_α$ and $A^B_α$ are supported on $Ω$: we say $v, v′ ∈ \partial Ω$ if $A^A_α$ and $A^B_α$ have support overlap with $Ω$
but not supported on $Ω$.

Then, one can show it is possible to write $|α⟩_{Ω′}$ in the following Schmidt basis:

$$|α⟩_{Ω′} = \sum_{\{h^I_{v,λ}\}_λ} \sqrt{p^λ_{\{h^I_{v,λ}\}}}|h^I_{v,λ}\rangle_Ω ⊗ |\{h^I_{v,λ}\}_Ω⟩_{Ω′\setminus Ω} \Rightarrow σ_Ω = \sum_{\{h^I_{v,λ}\}_λ} p^λ_{\{h^I_{v,λ}\}}|\{h^I_{v,λ}\}_Ω⟩_Ω ⊗ |\{h^I_{v,λ}\}_Ω⟩_{Ω′\setminus Ω}.  (21)$$

Where $I = 1, \cdots, M$ labels the number of disconnected pieces of $Δ \cap Δ′$ ($Δ′$ is the complement of $Δ$). $\{h^I_v\}_λ$ is a set
of link values $h^I_v ∈ G$, [19] with $a = 1, \cdots, N_I$ labels the links along the $I$th piece and $h^I_v h^I_{v′} \cdots h^I_{v_N} = h^I$. Each $h^I_v$
is obtained from a product of group elements on one or more links connecting $v, v′ ∈ Δ′$, and it is important to notice
that those vertices $v, v′ ∈ Ω$ do not count even if they are near $Δ′$. The same set of $h^I_v$ appears in $|\{h^I_v\}_Ω⟩_Ω$ and
$|\{h^I_v\}_Ω⟩_{Ω′\setminus Ω}$, this is due to condition (a).

Condition (b) and (c) is equivalent to the following:

$$B_f|\{h^I_v\}_Ω⟩_Ω = A^A_α|\{h^I_v\}_Ω⟩_Ω = A^A_α|\{h^I_v\}_Ω⟩_Ω = |\{h^I_v\}_Ω⟩_Ω \forall f, v, v′ ∈ Ω.  (22)$$

This requires $|\{h^I_v\}_Ω⟩_Ω$ be an equal weight superposition of all configurations with “zero flux” which could be related
by a product of $A^A_α$ and $A^A_α$ operators, $v, v′ ∈ Ω$. Note that, $A^A_α$ or $A^B_α$ with $v, v′ ∈ Ω$ does not mix different $\{h^I_v\}_λ$
sectors. Here, “zero flux” stands for the condition that a configuration has eigenvalue $B_f = 1 \forall f ∈ Δ′$. It may happen that two “zero flux”
configurations could not be related by a product of $A^A_α$ and $A^A_α$ operators, and the index $λ$ labels exactly those additional degrees of freedom. Note that, the number of additional degrees of freedom $λ$
depends on $\{h^I_v\}_λ$ in general.

Finally, the operators $A^A_α, A^B_α$ with $v, v′ ∈ Δ′$ mix different $\{h^I_v\}_λ$ sectors. Condition (d) gives constraint for the
probability distribution $\{p^λ_{\{h^I_v\}_λ}\}$. Each of the $A^A_α, A^B_α$ operators with $v, v′ ∈ Δ′$ is a unitary operator which could be
written as products of unitary operators on each link. Define $A^A_α(Ω), A^B_α(Ω)$ be the “truncation” of the operators $A^A_α,
A^B_α$, (with $v, v′ ∈ Δ′$) onto $Ω$ in the fashion that $U_{Ω′}(Ω) = U_Ω$ for $U_{Ω′} = U_Ω ⊗ U_{Ω′\setminus Ω}$. And define a group of operators
$A(Ω)$ as following:

$$A(Ω) \equiv \{A(g, k) | A(g, k) \equiv \prod_{v ∈ Δ} \left[ A^A_{g(v)}(Ω) \right] \cdot \prod_{v′ ∈ Δ′} \left[ A^B_{g(v′)}(Ω) \right] with g(v) ∈ G, k(v′) ∈ K\}.  (23)$$

Now, we can write down the constraint on $σ_Ω$ caused by (d):

$$A(g, k)σ_Ω A(g, k)^\dagger = σ_Ω \forall A(g, k) ∈ A(Ω) \iff A^A_α(Ω)σ_Ω A^A_α(Ω) = A^B_α(Ω)σ_Ω A^B_α(Ω) \forall v, v′ ∈ Δ′, g ∈ G, k ∈ K.$$
Next, let us go to some examples. First recall the subsystem choices $\omega_1, \Omega_1, \omega_2, \Omega_2, \Omega_3$ discussed in the paper, see Fig.4. We will see below that the structures of the information convex of these choices of subsystem all have simple physical meaning.

![Diagram](image)

**FIG. 4:** An illustration of topologically distinct subsystem types: $\omega_1, \Omega_1, \omega_2, \Omega_2$ and $\Omega_3$. The $G$ quantum double model lives on a disk $D^2$ with a single gapped $K \subseteq G$ boundary. Note that, the relation to the boundary is considered as part of the topological data.

Our strategy for solving a information convex $\Sigma(\Omega)$ is to apply the method developed above, i.e. follow Eq.(21,22,23). In practice we find that, the problem is reduced to a problem for some minimal diagram, a simplified lattice with less links and a corresponding Hilbert space $\mathcal{H}(\Omega)$. The problem is to solve $\Sigma^*(\Omega)$, a suitably defined set of density matrices on $\mathcal{H}(\Omega)$, which satisfies a set of requirements very similar to Eq.(21,22,23).

$\Sigma(\Omega)$ and $\Sigma^*(\Omega)$ have identical convex structures, i.e. there is a naturally defined bijective mapping $\pi : \Sigma(\Omega) \rightarrow \Sigma^*(\Omega)$ which preserves the convex structure (maps a line segment to a line segment). The number of extremal points does not change under this mapping. Furthermore, there are physical properties (properties of the density matrices) of $\Sigma(\Omega)$ which are invariant under continuous deformations of $\Omega$, e.g. the entanglement entropy difference between two extremal points (in the case with more than one extremal point). We call these properties *topological invariant structures* (or *structures* for short) of the information convex $\Sigma(\Omega)$. $\Sigma^*(\Omega)$ captures all the topological invariant structures of $\Sigma(\Omega)$.

1. The calculation of $\Sigma(\omega_1)$

For subsystem $\omega_1$, i.e. a disk in the bulk, $\partial \omega_1 \cap \partial \omega_1 = \partial \omega_1$ contains one piece. Therefore, $M = 1$. Let us relabel $h_a^1 \rightarrow h_a$ and $N_1 \rightarrow n$. It is well known that $\Sigma(\omega_1)$ contains a single element, i.e. the reduced density matrix calculated from the ground state $|\psi\rangle$.

$$\Sigma(\omega_1) = \{\sigma^1_{\omega_1}\} \quad \text{with} \quad \sigma^1_{\omega_1} = tr_{\omega_1}|\psi\rangle\langle\psi|.$$  

This result is consistent with the fact that topological orders have locally indistinguishable ground states. The reduced density matrix $\sigma^1_{\omega_1}$ can be found in a number of references, for example [8, 9]. Simple as it is, this result is a powerful statement for the study of local perturbations (known as the TQO-2 condition) [2]. Also, it strongly constraint the possible form of operators which create excitations on a ground state once combined with the HJW theorem, see Sec.III C. Let us briefly recall that $\sigma^1_{\omega_1}$ can be written as:

$$\sigma^1_{\omega_1} = \frac{1}{|G|^{n-1}} \sum_{\{h_a\}} \langle\{h_a\}\rangle_{\omega_1} \omega_1 \langle\{h_a\}\rangle.$$  

(25)

Here, the sum of $\{h_a\}$ is the shorthand notation for the sum of different $\{h_1, \cdots, h_n\}$ and $\langle\{h_a\}\rangle_{\omega_1}$ is a unique state fixed by the two requirements:

1) The set of values on $\partial \omega_1$ are $\{h_a\}$, $a = 1, \cdots, n$ with $h_a \in G$.

2) The requirement in Eq.(22), i.e. $Bf|\{h_a\}\rangle_{\omega_1} = A_v|\{h_a\}\rangle_{\omega_1} = \langle\{h_a\}\rangle_{\omega_1}$ for $\forall f, v \in \omega_1$.

The 2nd requirement implies $h_1 h_2 \cdots h_n = 1$, and end up with $|G|^{n-1}$ choices for $\{h_a\}$. Also, it guarantees $\langle\{h_a\}\rangle_{\omega_1}$ to be an equal weight superposition of all “zero flux” configurations with fixed $\{h_a\}$ at $\partial \omega_1$.

Use the fact that $\langle\{h_a\}|\langle\{h_a\}\rangle = \delta_{\{h_a\},\{h_a\}}$, one can derive the following properties:

$$\sigma^1_{\omega_1} \cdot \sigma^1_{\omega_1} = \frac{1}{|G|^{n-1}} \sigma^1_{\omega_1} \Rightarrow \quad S(\sigma^1_{\omega_1}) = (n-1) \ln |G|, \quad \quad tr[\sigma^1_{\omega_1} \cdot \sigma^1_{\omega_1}] = \frac{1}{|G|^{n-1}}.$$  

(26)
FIG. 5: An illustration of the subsystem $\omega_1$ and the corresponding minimal diagram.

Here, $S(\sigma_{\omega_1}^n)$ is the von Neumann entropy. Note that these results depend on $n$ the number of link values around $\partial\omega_1$.

On the other hand, as is mentioned above, there are properties invariant under topological deformations of $\omega_1$. Such as the number of extremal points and the entanglement entropy difference between two extremal points (in the case with more than one extremal point). We call these properties topological invariant structures (or structures for short) of a information convex. Also note that, we need to be careful when talking about “topological deformations”.

The relation to boundaries must be treated as topological data. $\omega_1$, $\omega_2$ and $\Omega_2$ in Fig.4 are all simply connected in the usual sense, but here they are treated as topologically distinct due to their different relation to the boundary.

The information convex $\Sigma(\omega_1)$ may also be calculated following Eq.(21,22,23). We find that, the problem is reduced to a problem for some minimal diagram which realize the same topological invariant structures as $\Sigma(\omega_1)$. One may solve the problem for the minimal diagram first and then go back to the original problem.

Consider the minimal diagram in Fig.5. Define the corresponding Hilbert space $H^* (\omega_1) = \text{span}\{\{h\}| h \in G\}$, where $\{|h\rangle\}$ with $h \in G$ is an orthonormal basis. Define $\Sigma^*(\omega_1)$ be the set of density matrices $\sigma^*_\omega_1$ on $H^* (\omega_1)$ satisfying the requirements:

1) $\sigma^*_\omega_1 = \sum_{h \in G} p_h |h\rangle\langle h|$. Where $\{p_h\}$ is a probability distribution.

2) $B^t \sigma^*_\omega_1 = \sigma^*_\omega_1$. Where $B|h\rangle = \delta_{1,h}|h\rangle$.

3) $A^t_1 \sigma^*_\omega_1 A^0_1 = \sigma^*_\omega_1$ for $\forall g \in G$. Where $A^0_1|h\rangle = |g h\rangle$.

Then, it is easy to verify that

$$\Sigma^*(\omega_1) = \{\sigma^*_1\}, \quad \sigma^*_1 \equiv |1\rangle\langle 1|.$$  \hfill (27)

It has the same structures as $\Sigma(\omega_1)$. And there is a naturally defined mapping $\pi : \Sigma(\omega_1) \rightarrow \Sigma^*(\omega_1)$, such that $\pi(\sigma^*_1) = \sigma^*_1$. Intuitively, what the mapping $\pi$ does is to map a state $|\{h_a\}\rangle_{\omega_1}$ into a configuration eigenstate $|h\rangle \in H^* (\omega_1)$ with $h = h_1 h_2 \cdots h_n$. Trivial as the minimal diagram for $\omega_1$ is, similar constructions will be very useful in the more involved examples below.

2. The calculation of $\Sigma(\Omega_1)$

For $\Omega_1$ topology, i.e. an annulus in the bulk, $M = 2$, let us relabel $h_1^a \rightarrow h_a$ with $a = 1, \cdots, n$ and $h_2^b \rightarrow H_b$ with $b = 1, \cdots, N$ and $h \equiv h_1 \cdots h_n$, $H = H_1 \cdots H_N$. As is discussed above, the calculation of $\Sigma(\Omega_1)$ can be done following Eq.(21,22,23), but a simpler way is to consider a minimal diagram, see Fig.6.

FIG. 6: An illustration of the subsystem $\Omega_1$ and the corresponding minimal diagram.

Define $H^* (\Omega_1) = \text{span}\{|h,H,t\rangle| h, H, t \in G\}$ be the Hilbert space for the minimal diagram. Where $\{|h,H,t\rangle| h, H, t \in G\}$ is an orthonormal basis. Define $\Sigma^*(\Omega_1)$ to be the set of density matrices $\sigma^*_\Omega_1$ on $H^* (\Omega_1)$ satisfying the requirements:
1) $\sigma^*_{\Omega_1} = \sum_{h,H \in G} \sum_{\lambda} p^h_{(h,H)} |\{h,H\}; \lambda\rangle\langle\{h,H\}; \lambda|$. Where, $\{p^h_{(h,H)}\}$ is a probability distribution and $|\{h,H\}; \lambda\rangle \equiv \sum_{t \in G} c_{\lambda}(t)|h,H,t\rangle$ with complex coefficients $c_{\lambda}(t)$ satisfying $\sum_{t \in G} |c_{\lambda}(t)|^2 = 1$.

2) $B \sigma^*_{\Omega_1} = \sigma^*_{\Omega_1}$. Where $B |h,H,t\rangle = \delta_{h,H} |h,H,t\rangle$.

3) $A^1 \sigma^*_{\Omega_1}, A_2^0 = A_2^0 \sigma^*_{\Omega_1}, A_2^0 = \sigma^*_{\Omega_1}$ for $\forall g \in G$. Where $A^1 |h,H,t\rangle = |ghg, H, gt\rangle$ and $A^0_2 |h,H,t\rangle = |h, gHg, t\rangle$.

From these requirements, on can verify:

$$\Sigma^* (\Omega_1) = \{ \sigma^*_{\Omega_1} | \sigma^*_{\Omega_1} = \sum_{(c,R)} p_{(c,R)} \sigma_{\Omega_1}^{(c,R)} \}, \quad c \in (R)_{c,j}, \quad R \in (E(c))_{ir}. \quad (28)$$

Where $\{p_{(c,R)}\}$ is a probability distribution and therefore $\Sigma^* (\Omega_1)$ is a convex set. $\sigma_{\Omega_1}^{(c,R)}$ is an extremal point with the following expression:

$$\sigma_{\Omega_1}^{(c,R)} = \frac{1}{|c|^2 \cdot n_R^2} \sum_{u} \sum_{v} |(c,R)(u,v)) (\langle c,R)(u,v)|$$

and the state $|(c,R)(u,v))$ is defined as (note the similarity of the following result with the results in Sec.II.B):

$$|\langle c,R)(u,v)| (\langle c',R')(u',v') = \delta_{c,c'} \delta_{R,R'} \delta_{u,u'} \delta_{v,v'}.$$  

Where:

1) $c \in (G)_{c,j}$, i.e. $c = \{g r_c g | g \in G\}$. Where $r_c$ is a representative of $c$.

2) $E(c)$ is the centralizer group of $c$, defined as $E(c) \equiv \{g \in G | g r_c = r_c g\}$.

3) $R \in (E(c))_{ir}$ and $n_R$ is the dimension of $R$. $\Gamma_R$ is the unitary $n_R \times n_R$ matrix associated with $R$, with components $\Gamma_R^{ij}$. $\Gamma_R^{ij}$ is the complex conjugate of $\Gamma_R^{ij}$.

4) $P(c) = \{ p_i \}_{i=1}^{c}$ is a set of representatives of $G/E(c)$. $c = \{ c_i \}_{i=1}^{c}$ with $c_i = p_i r_c \tilde{p}_i$.

5) $u = (i,j)$, $v = (i',j')$ with $i, i' = 1, \ldots, |c|$ and $j, j' = 1, \ldots, n_R$.

For more explanations of the notation, see Sec.II.A.

Now, introduce the label $a = (c,R)$ for $c \in (G)_{c,j}$ and $R \in (E(c))_{ir}$, which will be identified as the label of bulk superselection sector (bulk anyon type). $d_a = |c| \cdot n_R$ is the quantum dimension for bulk anyons in quantum double models. One easily check $\sum_a d^2_a = |G|^2 = D^2$ with $D \equiv \sqrt{\sum_a d^2_a} = |G|$. Where $D$ is the total quantum dimension. We have the following results about $\Sigma^* (\Omega_1)$:

$$\sigma^a_{\Omega_1} \cdot \sigma^b_{\Omega_1} = \frac{\delta_{a,b}}{d_a} \sigma^a_{\Omega_1} \Rightarrow S(\sigma^a_{\Omega_1}) = \ln d^2_a, \quad tr[\sigma^a_{\Omega_1} \cdot \sigma^b_{\Omega_1}] = \frac{\delta_{a,b}}{d^2_a}. \quad (32)$$

Knowing the similarities between $\Sigma (\Omega_1)$ and $\Sigma^* (\Omega_1)$, we conclude that, the set $\Sigma (\Omega_1)$ has extremal points $\sigma^a_{\Omega_1}$, with $a = (c,R)$:

$$\Sigma (\Omega_1) = \{ \sigma_{\Omega_1} | \sigma_{\Omega_1} = \sum_a p_a \sigma^a_{\Omega_1} \}, \quad \{ p_a \} \text{ is a probability distribution.} \quad (33)$$

The extremal points of $\Sigma (\Omega_1)$ have the following properties:

$$\sigma^a_{\Omega_1} \cdot \sigma^b_{\Omega_1} = \frac{\delta_{a,b}}{d^2_a \cdot |G|^{n+N-2}} \sigma^a_{\Omega_1} \Rightarrow S(\sigma^a_{\Omega_1}) = \ln d^2_a + (n+N-2) \ln |G|, \quad tr[\sigma^a_{\Omega_1} \cdot \sigma^b_{\Omega_1}] = \frac{\delta_{a,b}}{d^2_a \cdot |G|^{n+N-2}}. \quad (34)$$

We will use $a = 1$ as a shorthand notation for $c$ being the conjugacy class contain the identity element $1 \in G$, i.e. $c = \{ 1 \}$ with the one dimensional identity representation $R = 1d$. One could verify, $\sigma^1_{\Omega_1}$ is the reduced density matrix calculated from the ground state $|\psi\rangle$, i.e. $\sigma^1_{\Omega_1} = tr_{\Omega_1} |\psi\rangle\langle \psi|$, and that $d_1 = 1$.

The following structures of $\Sigma (\Omega_1)$ are invariant under topological deformations of $\Omega_1$:

$$S(\sigma^a_{\Omega_1}) = S(\sigma^1_{\Omega_1}) + \ln d^2_a, \quad \sigma^a_{\Omega_1} \cdot \sigma^b_{\Omega_1} = 0 = tr[\sigma^a_{\Omega_1} \cdot \sigma^b_{\Omega_1}] \quad \text{for} \ a \neq b, \quad \frac{tr[\sigma^a_{\Omega_1} \cdot \sigma^1_{\Omega_1}]}{tr[\sigma^a_{\Omega_1} \cdot \sigma^1_{\Omega_1}]} = \frac{1}{d^2_a}. \quad (35)$$
FIG. 7: An illustration of the subsystem $\omega_2$ and the corresponding minimal diagram.

3. The calculation of $\Sigma(\omega_2)$

A subsystem with $\omega_2$ topology attaches to the boundary at one piece, see Fig.4. $\partial \omega_2 \cap \partial \bar{\omega}_2$ has a single piece, $M = 1$. Relabel $h_1^0 \rightarrow h_a$ with $a = 1, \ldots, n$.

Again, in order to find $\Sigma(\omega_2)$, we consider a corresponding minimal diagram in Fig.7. Define the Hilbert space for the minimal diagram to be $H^*(\omega_2) = \text{span}\{|(h, H, t_1, t_2)\mid h, H \in G, t \in K\}$, where $\{(h, t)\mid h \in G, t \in K\}$ is an orthonormal basis. Define $\Sigma^*(\omega_2)$ to be the set of density matrices $\sigma^*_2$ on $H^*(\omega_2)$ satisfying the following requirements:

1) $\sigma^*_2 = \sum_{h \in G} \sum_{\lambda} p^h_\lambda |(h); \lambda\rangle\langle(h); \lambda|$ where $\{p^h_\lambda\}$ is a probability distribution and $\{|(h); \lambda\rangle\equiv \sum_{t \in K} c_\lambda(t)|h, t\rangle$ with complex coefficients $c_\lambda(t)$ satisfying $\sum_{t \in K} |c_\lambda(t)|^2 = 1$.

2) $B \sigma^*_2 = \sigma^*_2$, where $B|h, t\rangle = \delta_{h_1^0, h}|h, t\rangle$.

3) $A^k_1 \sigma^*_2 A^k_1 = A^k_2 \sigma^*_2 A^k_2 = \sigma^*_2$, for $\forall k \in K$. Where, $A^k_1|h, t\rangle = |kh, tk\rangle$ and $A^k_2|h, k\rangle = |hk, kt\rangle$.

Then, it is easy to verify that:

$$\Sigma^*(\omega_2) = \{\sigma^*_2\} \quad \text{with} \quad \sigma^*_2 = \frac{1}{|K|} \sum_{k \in K} |k, k\rangle\langle k, k|.$$  
(36)

with properties of the extremal point:

$$\sigma^*_2 \cdot \sigma^*_2 = \frac{1}{|K|} \sigma^*_2 = S(\sigma^*_2) = \ln |K|, \quad tr[\sigma^*_2 \cdot \sigma^*_2] = \frac{1}{|K|}.$$  
(37)

From the similarity of $\Sigma^*(\omega_2)$ and $\Sigma(\omega_2)$, one can show that $\Sigma(\omega_2)$ contains a single element, i.e. the reduced density matrix calculated from the ground state $|\psi\rangle$:

$$\Sigma(\omega_2) = \{\sigma^1_2\}, \quad \sigma^1_2 = tr_{\omega_2}|\psi\rangle\langle\psi|$$  
(38)

with properties:

$$\sigma^1_2 \cdot \sigma^1_2 = \frac{1}{|K| \cdot |G|^{n-1}} \sigma^1_2 = S(\sigma^1_2) = (n - 1) \ln |G| + \ln |K|, \quad tr[\sigma^1_2 \cdot \sigma^1_2] = \frac{1}{|K| \cdot |G|^{n-1}}.$$  
(39)

4. The calculation of $\Sigma(\Omega_2)$

Now consider a subsystem with $\Omega_2$ topology, see Fig.4. It attaches to the boundary at two pieces. $\partial \Omega_2 \cap \partial \bar{\Omega}_2$ contain two pieces, $M = 2$. Relabel $h_0^1 \rightarrow h_a$ with $a = 1, \ldots, n$ and $h_0^2 \rightarrow H_b$ with $b = 1, \ldots, N$.

FIG. 8: An illustration of the subsystem $\Omega_2$ and the corresponding minimal diagram.

Again, to calculate $\Sigma(\Omega_2)$, we consider a minimal diagram in Fig.8. Define the Hilbert space for the minimal diagram $H^*(\Omega_2) = \text{span}\{|(h, H, t_1, t_2)\mid h, H \in G, t_1, t_2 \in K\}$. Define $\Sigma^*(\Omega_2)$ to be the set of density matrices $\sigma^*_2$ on $H^*(\Omega_2)$ satisfying the following requirements:

1) $\sigma^*_2 = \sum_{h \in G} \sum_{\lambda} p^h_\lambda |(h); \lambda\rangle\langle(h); \lambda|$ where $\{p^h_\lambda\}$ is a probability distribution and $\{|(h); \lambda\rangle\equiv \sum_{t_1 \in K} c_\lambda(t_1)|h, t_1\rangle$ with complex coefficients $c_\lambda(t_1)$ satisfying $\sum_{t_1 \in K} |c_\lambda(t_1)|^2 = 1$.

2) $B \sigma^*_2 = \sigma^*_2$, where $B|h, t_1\rangle = \delta_{h_1^0, h}|h, t_1\rangle$.

3) $A^k_1 \sigma^*_2 A^k_1 = A^k_2 \sigma^*_2 A^k_2 = \sigma^*_2$, for $\forall k \in K$. Where, $A^k_1|h, t_1\rangle = |kh, tk_1\rangle$ and $A^k_2|h, k\rangle = |hk, tk_1\rangle$.

Then, it is easy to verify that:

$$\Sigma^*(\Omega_2) = \{\sigma^*_2\} \quad \text{with} \quad \sigma^*_2 = \frac{1}{|K|} \sum_{k \in K} |k, k\rangle\langle k, k|.$$  
(36)

with properties of the extremal point:

$$\sigma^*_2 \cdot \sigma^*_2 = \frac{1}{|K|} \sigma^*_2 = S(\sigma^*_2) = \ln |K|, \quad tr[\sigma^*_2 \cdot \sigma^*_2] = \frac{1}{|K|}.$$  
(37)

From the similarity of $\Sigma^*(\Omega_2)$ and $\Sigma(\Omega_2)$, one can show that $\Sigma(\Omega_2)$ contains a single element, i.e. the reduced density matrix calculated from the ground state $|\psi\rangle$:

$$\Sigma(\Omega_2) = \{\sigma^1_2\}, \quad \sigma^1_2 = tr_{\Omega_2}|\psi\rangle\langle\psi|$$  
(38)

with properties:

$$\sigma^1_2 \cdot \sigma^1_2 = \frac{1}{|K| \cdot |G|^{n-1}} \sigma^1_2 = S(\sigma^1_2) = (n - 1) \ln |G| + \ln |K|, \quad tr[\sigma^1_2 \cdot \sigma^1_2] = \frac{1}{|K| \cdot |G|^{n-1}}.$$  
(39)
$\mathcal{H}^*(\Omega_2)$ satisfying the requirements:
1) $\sigma_{\Omega_2}^\ast = \sum_{h,H \in G} p(h,H) |\{h,H\}; \lambda\rangle\langle\{h,H\}; \lambda|$. Where $\{p(h,H)\}$ is a probability distribution and the state $|\{h,H\}; \lambda\rangle \equiv \sum_{t_1,t_2 \in K} c(t_1,t_2) |h,H,t_1,t_2\rangle$ with complex coefficients $c(t_1,t_2)$ satisfying $\sum_{t_1,t_2 \in K} |c(t_1,t_2)|^2 = 1$.
2) $B_{\sigma_{\Omega_2}^\ast} = B_{\sigma_{\Omega_2}^\ast}$. Where $B(h,H,t_1,t_2) = \delta_{h,I} \delta_{t_1,t_2} |h,H,t_1,t_2\rangle$.
3) $A_{k}^\prime \sigma_{\Omega_2}^\ast A_{k}^\dagger = A_{k}^\prime \sigma_{\Omega_2}^\ast A_{k}^\dagger = A_{k}^\prime \sigma_{\Omega_2}^\ast A_{k}^\dagger = A_{k}^\prime \sigma_{\Omega_2}^\ast A_{k}^\dagger = \sigma_{\Omega_2}^\ast$, for $\forall k \in K$. Where

$$A_{k}^\prime |h,H,t_1,t_2\rangle = |kh,H,kt_1,t_2\rangle, \quad A_{k}^\prime |h,H,t_1,t_2\rangle = |h,kH,t_1,k_2\rangle, \quad A_{k}^\prime |h,H,t_1,t_2\rangle = |h,kH,t_1,k_2\rangle.$$

From these requirements, on can verify:

$$\Sigma^\ast(\Omega_2) = \{\sigma_{\Omega_2}^\ast, \sigma_{\Omega_2}^\ast = \sum_{(T,R)} p(T,R) \sigma_{\Omega_2}^{+(T,R)}\}, \quad T \in K \setminus G/K, \quad R \in (K^{\tau R})^{ir}. \quad (40)$$

Where $\{p(T,R)\}$ is a probability distribution and $\sigma_{\Omega_2}^{+(T,R)}$ is an extremal point with the following expression:

$$\sigma_{\Omega_2}^{+(T,R)} = \frac{1}{|T| \cdot n_R} \sum_{k_3,k_4 \in K} |(T,R)(u,v)(k_3,k_4)\rangle \langle (T,R)(u,v)(k_3,k_4)| \quad (41)$$

with

$$|(T,R)(u,v)(k_3,k_4)\rangle = A_{k_3}^\dagger A_{k_4}^\prime A_{k_3}^\prime A_{k_4} \sqrt{\frac{n_R}{|K^{\tau R}|}} \sum_{t_1 \in K^{\tau R}} \tilde{\Gamma}_{\tau T}^{i't'}(t_1) |r_T, r_T, t_1, \bar{r}_{T'}l_{T'}r_{T'}\rangle \quad (42)$$

$$= \sqrt{\frac{n_R}{|K^{\tau R}|}} \sum_{t_1 \in K^{\tau R}} \tilde{\Gamma}_{\tau T}^{i't'}(t_1) |q_{t_1} r_T k_3, q_{t_1} r_T k_4, q_{t_1} q_{t_1} r_{T'} l_{T'} r_{T'} k_3\rangle$$

with $k_3, k_4 \in K$. One can verify that:

$$|(T,R)(u,v)(k_3,k_4)\rangle |(T',R')(u',v')(k_3',k_4')\rangle = \delta_{T,T'} \delta_{R,R'} \delta_{u,u'} \delta_{v,v'} \delta_{k_3,k'_3} \delta_{k_4,k'_4}. \quad (44)$$

Where:
1) $T \in K \setminus G/K$ is a double coset, i.e. $T = \{k_1 t_1 k_2 \mid k_1,k_2 \in K\}$. $r_T \in G$ is a representative of $T$.
2) $K^{\tau R} = K \cap r_T K^{\tau R}$ is a subgroup of $K$, and it depends on the choice of $r_T$ in general.
3) $R \in (K^{\tau R})^{ir}$ and $n_R$ is the dimension of $R$. $\Gamma_R$ is the unitary $n_R \times n_R$ matrix associated with $R$, with components $\Gamma_{R}^{i'j'}$. $\Gamma_{R}^{i'j'}$ is the complex conjugate of $\Gamma_{R}^{i'j'}$.
4) $Q = \{q_i\}, \, i = 1, \cdots, |Q|$ is a set of representatives of $K/K^{\tau R}$. $|Q| = |K|/|K^{\tau R}| = |T|/|K|$. $s_i \equiv q_{t_1} r_{T'} q_{t_1}$.
5) $u = (i,j), \quad v = (i',j')$ with $i,i' = 1, \cdots, |Q|$ and $j,j' = 1, \cdots, n_R$.

For more explanations of the notation, see Sec.II.A.

Now, let us introduce label $\alpha = (T,R)$ for $T \in K \setminus G/K$ and $R \in (K^{\tau R})^{ir}$, which will be identified to the label of boundary superselection sector and the corresponding quantum dimension:

$$d_\alpha = \frac{|T| \cdot n_R}{|K|} = \frac{|K| \cdot n_R}{|K^{\tau R}|} = \alpha = (T,R). \quad (45)$$

One can easily check that $\sum_\alpha d_\alpha^2 = \sqrt{\sum_\alpha d_\alpha^2} = |G| = D$. We note that, the quantum dimension $d_\alpha$ has been discovered algebraically in [5] in a different physical context. One could verify the following properties of $\Sigma^\ast(\Omega_2)$:

$$\sigma_{\Omega_2}^\alpha \cdot \sigma_{\Omega_2}^\beta = \frac{\delta_{\alpha,\beta}}{d_\alpha^2 |K|^2} \sigma_{\Omega_2}^\alpha \Rightarrow S(\sigma_{\Omega_2}^\alpha) = \ln d_\alpha^2 + 2 \ln |K|, \quad tr[\sigma_{\Omega_2}^\alpha \cdot \sigma_{\Omega_2}^\beta] = \frac{\delta_{\alpha,\beta}}{d_\alpha^2 |K|^2}. \quad (46)$$

One can obtain $\Sigma(\Omega_2)$ from its similarity to $\Sigma^\ast(\Omega_2)$:

$$\Sigma(\Omega_2) = \{\sigma_{\Omega_2} \sigma_{\Omega_2} = \sum_\alpha p_\alpha \sigma_{\Omega_2}^\alpha, \quad \{p_\alpha\} \text{ is a probability distribution.} \quad (47)$$

The extremal points has the following properties:

$$\sigma_{\Omega_2}^\alpha \cdot \sigma_{\Omega_2}^\beta = \frac{\delta_{\alpha,\beta}}{d_\alpha^2 |K|^2} \cdot |G|^{n+N-2} \sigma_{\Omega_2}^\alpha \Rightarrow S(\sigma_{\Omega_2}^\alpha) = \ln d_\alpha^2 + 2 \ln |K| + (n + N - 2) \ln |G|, \quad (48)$$

$$tr[\sigma_{\Omega_2}^\alpha \cdot \sigma_{\Omega_2}^\beta] = \frac{\delta_{\alpha,\beta}}{d_\alpha^2 |K|^2} \cdot |G|^{n+N-2}. \quad (49)$$
Let us use the notation $\alpha = 1$ for $T = K$ and $R = Id$ the one dimensional identity representation of $K^{\tau}$ (in fact $K^{\tau} = K$ for $T = K$). $\sigma^1_{\Omega_2}$ is the reduced density matrix calculated from the ground state $|\psi\rangle$, i.e. $\sigma^1_{\Omega_2} = tr_{\Omega_2}|\psi\rangle\langle\psi|$ and the quantum dimension $d_1 = 1$.

The information convex $\Sigma(\Omega_2)$ have the following topological invariant structures:

$$S(\sigma^\alpha_{\Omega_2}) = S(\sigma^1_{\Omega_2}) + \ln d^\alpha_{\Omega_2}, \quad \sigma^\alpha_{\Omega_2} \cdot \sigma^\beta_{\Omega_2} = 0 \quad \text{for} \quad \alpha \neq \beta, \quad \frac{tr[\sigma^\alpha_{\Omega_2} \cdot \sigma^\beta_{\Omega_2}]}{tr[\sigma^1_{\Omega_2} \cdot \sigma^1_{\Omega_2}]} = \frac{1}{d^\alpha_{\Omega_2}}.$$ \hspace{1cm} (50)

C. Topological excitations, unitary string operators and superselection sectors

Perhaps, the most well-known examples of topological excitations are anyons in 2D topological orders on a system without boundaries. They could not be created by local unitary operators supported around the excitations but could be created (usually need to create more than one) by unitary operators supported on a deformable string. Different excitations which could be related by a local unitary operation (acting around the excitations) are in the same superselection sector. Superselection sector is the label of anyon type (let us denote the vacuum superselection sector as $a = 1$).

In this section, we discuss a way to establish possible deformable unitary string operator types for 2D topological orders with a gapped boundary (for both excitations inside the bulk and excitations along the boundary). The method makes use of the structure of $\Sigma(\omega_1)$, $\Sigma(\omega_2)$ and the HJW theorem. Then, we give a definition of bulk superselection sectors and boundary superselection sectors using the results of $\Sigma(\Omega_1)$ and $\Sigma(\Omega_2)$ and discuss what type of unitary string operators could realize topological excitations of each bulk/boundary superselection sector.

1. Deformable unitary string operators from the HJW theorem

For Abelian models it is usually straightforward to construct the unitary operators creating $(a, \bar{a})$ for each anyon type $a$. The unitary operators has string-like support and the strings are deformable. For non-Abelian models, like a non-Abelian quantum double model, the proof of the existence of such unitary operators are less well-known but conceptionally important [10]. Things which make the story complicated for non-Abelian models are (1) the ribbon operators (see Sec.III E, III F) though deformable are no unitary in general; (2) the support of the unitary operators can be slightly “fatter” than the ribbon operators.

Here, we provide a prove of the existence of the unitary string operators for both quantum double model on a sphere $S^2$ and quantum double model on $D^2$ with a single boundary making use of the result of $\Sigma(\omega_1)$ and $\Sigma(\omega_2)$ in Sec.III B 1, Sec.III B 3 and the HJW theorem. The proof is quite general and it is generalizable to system on other manifold topologies. Given suitable structure of information convex the proof can be generalized to other topological orders in 2D and topological orders in higher dimensions.

First, let us review the HJW theorem [11]. Consider the Hilbert space of system $AB$, which can be written as a tensor product of Hilbert spaces of subsystems $A$ and $B$, i.e. $\mathcal{H}_{AB} = \mathcal{H}_A \otimes \mathcal{H}_B$. For $|\psi\rangle, |\varphi\rangle \in \mathcal{H}_{AB}$, the HJW theorem implies (which could be verified easily using Schmidt decomposition):

$$tr_A |\varphi\rangle \langle \varphi| = tr_A |\psi\rangle \langle \psi| \Leftrightarrow |\varphi\rangle = U_A \otimes 1_B |\psi\rangle.$$ \hspace{1cm} (51)

Where $U_A$ is a unitary operator acting on $\mathcal{H}_A$ and $1_B$ is the identity operator acting on $\mathcal{H}_B$.

\[\begin{array}{ccc}
\bar{\omega}_1 & \alpha_1 & \omega_1 \\
S^2 & S^2 & S^2
\end{array}\]

FIG. 9: A system on a sphere $S^2$. Excitations are in the red area, which is a subset of the yellow region $\bar{\omega}_1$. Use the HJW theorem, one can show there must be a unitary operator supported on $\omega_1$, which creates the excitations.

Now let us consider a system defined on a sphere $S^2$. We have $\Sigma(\omega_1) = \{|\sigma^1_{\omega_1} \equiv tr_{\omega_1}|\psi\rangle\langle\psi|\}$. Here $|\psi\rangle$ is the unique ground state on $S^2$ and $\omega_1$ is any simply connected subsystem in the bulk (need to look at a scale bigger than a few
lattice spacing for “topology” to make sense). Consider a few examples of excitations in the red areas of Fig.9, and let us call the corresponding excited state $|\varphi\rangle$. Since only the topological of $\omega_1$ matters, we may choose $\omega_1$ as large as possible, but it does not overlap with the excitations. From the HJW theorem:

$$tr_{\omega_1}|\varphi\rangle\langle\varphi| \in \Sigma(\omega_1) \Rightarrow tr_{\omega_1}|\varphi\rangle\langle\varphi| = tr_{\omega_1}|\psi\rangle\langle\psi| \Rightarrow |\varphi\rangle = U_{\omega_1} \otimes 1_{\omega_1}|\psi\rangle. \quad (52)$$

In other words, there exists a unitary operator supported on the yellow region $\bar{\omega}_1$ which could create the excitations (when acting on the ground state). Since $\omega_1$ can be topologically deformed, the yellow region and therefore the support of the string operators can be topologically deformed also.

 Explicitly:

 A single excitation on $S^2$ can always be created using a local unitary operator acting around the excitation. Therefore, it carries the trivial superselection sector. The method we used is an alternative way to proof a statement in [3]. Be aware that, on torus $T^2$ it is possible (for non-Abelian models) to have a single excitation carry non-trivial superselection sector [3]. This result is also suggested by our method. A pair of excitations separated by arbitrary distance on $S^2$ can be created using a unitary operator supported on a deformable string connecting the pair. The thickness of the string does not grow with the distance between the excitations, and for the exactly solved quantum double model, it is just a few lattice spacing. Three excitations on $S^2$ can always be created by unitary operator supported on a deformable tree-like string.

![FIG. 10: A system on a disk $D^2$. Excitations are in the red area, which is a subset of the yellow region $\bar{\omega}_2$ (or $\bar{\omega}_2 \cap \bar{\omega}_2$ for the last diagram). Use the HJW theorem, one can show there must be a unitary operator supported on the yellow region $\bar{\omega}_2$ (or $\bar{\omega}_2 \cap \bar{\omega}_2$) which creates the excitations.](image)

Now let us consider a system on a disk $D^2$. The results are illustrated in Fig.10. The proofs are quite similar to that discussed above, the only difference is that we now need the result $\Sigma(\omega_2) = \{\sigma_{\omega_2}^{a} \equiv tr_{\omega_2} |\psi\rangle\langle\psi| \}$. Where $\omega_2$ is a simply connected subsystem attached to the boundary at one piece, see Fig.4 and Sec.III B.3. $|\psi\rangle$ now represents the unique ground state on $D^2$. (For the last diagram, $\Sigma(\omega_2 \cup \bar{\omega}_2) = \{\sigma_{\omega_2 \cup \bar{\omega}_2} \equiv tr_{\omega_2 \cap \bar{\omega}_2} |\psi\rangle\langle\psi| \}$ is needed, where $\bar{\omega}_2$ has the same topology as $\omega_2$.)

A new feature is that now a generic excited state with localized excitations need to be created using process involve the boundary, i.e. $|\varphi\rangle \neq U_{\text{bulk}}|\psi\rangle$ in general. Where $U_{\text{bulk}}$ is a unitary operator supported on a bulk subsystem. Explicitly:

 A single excitation away from the boundary of $D^2$ can be created by a unitary operator supported on a string attached to the boundary. The string could be deformed, and the string can end at anywhere of the boundary. Unlike a single excitation on $S^2$, this single excitation on $D^2$ may carry nontrivial bulk superselection sector. On the other hand, a single excitation located along the boundary can always be created by a local unitary operator acting around the excitation and therefore it carries a trivial boundary superselection sector. A pair of excitations away from the boundary of $D^2$ could be created by a unitary operator supported on a string-like region attached to the boundary. Note that there is no guarantee that the pair of excitations could be created by a unitary operator supported on a bulk string. Indeed, for some non-Abelian models, there can be excited state $|\varphi\rangle$ with a bulk anyon pair $(a, \bar{a})$ located away from the boundary, but $|\varphi\rangle \neq U_{\text{bulk}}|\psi\rangle$, see Sec.IV E for more details. A pair of excitations around the boundary could be created by a unitary operator supported on a string along the boundary. The middle part of the string can be deformed into the bulk.
2. Unitary string operators which create excitations of all possible superselection sectors

We have identified possible string types which connect point-like excitations. Here we discuss what type of string operators could guarantee the excitations to have all possible superselection sectors. One way is to do explicit calculation using ribbon operators, see Sec.III E and Sec.III F. Here, we discuss an alternative way which is applicable to models whose ribbon operators are hard (if not impossible) to be written down.

![Diagram of subsystems](image)

**Theorem III.1.** For a quantum double on $S^2$ and an annulus subsystem $\Omega_1$, every extremal point of $\Sigma(\Omega_1)$ can be written as $\text{tr}_{\Omega_2} |\varphi\rangle\langle\varphi|$. Where $|\varphi\rangle$ is an excited state with a pair of point-like excitations, created by a unitary operator supported on a deformable bulk string crossing $\Omega_1$.

**Proof.** We have shown that an excited state with a pair of excitations could be written as $|\varphi\rangle = U|\psi\rangle$. Where $|\psi\rangle$ is the unique ground state on $S^2$ and $U$ is supported on a deformable string. Also, one can always make a “thicker” annulus $\Omega'_1$ on $S^2$ which covers the entire $S^2$ except for two localized regions, see Fig.11. Then, one can show:

1) $\Sigma(\Omega_1, \Omega'_1) = \Sigma(\Omega_1)$ using the explicit reduced density matrix in Sec.III B 2 and trace out some suitable subsystems.
2) Each extremal point of $\Sigma(\Omega_1, \Omega'_1)$ have purification on the system. This can be deduced from Proposition I.4.

Therefore, there exists an excited state $|\varphi^a\rangle$ with a pair of point-like excitations in $\Omega'_1$ which could be created using a unitary string operator and it prepare an extremal point $\sigma^a_{\Omega_1} \in \Sigma(\Omega_1)$, i.e. $\sigma^a_{\Omega_1} = \text{tr}_{\Omega_1} |\varphi^a\rangle\langle\varphi^a|$. 

This also gives a natural way to define the superselection sector of point-like excitations, i.e. by looking at what reduced density matrix of $\Sigma(\Omega_1)$ it prepares. If it prepares an extremal point $\sigma^a_{\Omega_1}$, then the excitation circled by the annulus is in the $a$ superselection sector. If it prepares a nonextremal point, then it carries a superposition (or mixture) of superselection sectors.

**Theorem III.2.** For a quantum double on $D^2$ and a subsystem $\Omega_2$, every extremal point of $\Sigma(\Omega_2)$ can be written as $\text{tr}_{\Omega_1} |\varphi\rangle\langle\varphi|$. Where $|\varphi\rangle$ is an excited state with a pair of point-like excitations along the boundary, created by a unitary operator supported on a string along the boundary crossing $\Omega_2$. The middle part of the string can be deformed into the bulk.

**Proof.** We have shown that an excited state with a pair of excitations along the boundary could be written as $|\varphi\rangle = U|\psi\rangle$. Where $|\psi\rangle$ is the unique ground state on $D^2$ and $U$ is supported on a string along the boundary, the middle part of which could be deformed into the bulk. Also, one can always make a “thicker” annulus $\Omega'_2$ on $D^2$ which covers the entire $D^2$ except for two localized regions along the boundary, see Fig.11. Then, one can show:

1) $\Sigma(\Omega_2, \Omega'_2) = \Sigma(\Omega_2)$ using the explicit reduced density matrix in Sec.III B 2 and trace out some suitable subsystems.
2) Each extremal point of $\Sigma(\Omega_2, \Omega'_2)$ have purification on the system. This can be deduced from Proposition I.4.

Therefore, there exists an excited state $|\varphi^a\rangle$ with a pair of point-like excitations in $\Omega'_2$ which could be created using a unitary string operator along the boundary and it prepare an extremal point $\sigma^a_{\Omega_2} \in \Sigma(\Omega_2)$, i.e. $\sigma^a_{\Omega_2} = \text{tr}_{\Omega_2} |\varphi^a\rangle\langle\varphi^a|$. 

Similar to the bulk case, one could define boundary superselection sector of the excitations using the element of $\Sigma(\Omega_2)$ they prepare.

**Theorem III.3.** For a quantum double on $D^2$ and a bulk annulus $\Omega_1$, every extremal point of $\Sigma(\Omega_1)$ can be written as $\text{tr}_{\Omega_2} |\varphi\rangle\langle\varphi|$. Where $|\varphi\rangle$ is an excited state with a pair of point-like excitations in the bulk, created by a unitary operator supported on a bulk string crossing $\Omega_1$.

**Proof.** First, note the fact that the ground state of $S^2$ or $D^2$ have the same reduced density matrix on a disk-like subsystem in the bulk. In other words, a disk in the bulk could not tell whether it lives on $S^2$ or $D^2$. One can choose a disk-like subsystem containing the annulus $\Omega_1$ and apply a bulk string operator inside the disk-like subsystem. Then, use Theorem III.1 to finish the proof.
D. Topological entanglement entropy from topological invariant structures of information convex

Topological entanglement entropy (TEE) \([12, 13]\) is an important topological invariant characterization of the ground state. In the middle steps of our derivation of \(\Sigma(\omega_1)\), one could see the topological contribution explicitly, e.g. the \(-\ln |G|\) in Eq.(26) for the bulk \([20]\). However, in the final step, when we keep only topological invariant structures of \(\Sigma(\omega_1)\), the important constant is lost.

Nevertheless, we show that TEE can be recovered as a lower bound (which appears to be saturated), given the topological invariant structures of \(\Sigma(\omega_1)\) and \(\Sigma(\Omega_1)\). In fact, the lower bound always saturates given a few simple assumptions \([14]\). In this sense, TEE retains in the topological invariant structures of information convex.

Below is the derivation of the lower bound. First, recall some properties of \(\Sigma(\Omega_1)\):

\[
\Sigma(\Omega_1) = \{\sigma_{\Omega_1}| \sigma_{\Omega_1} = \sum_a p_a \sigma_{\Omega_1}^a \} \quad \text{with} \quad S(\sigma_{\Omega_1}^a) = S(\sigma_{\Omega_1}^1) + \ln d_2^a, \quad \sigma_{\Omega_1}^a \cdot \sigma_{\Omega_1}^b = 0 \quad \text{for} \quad a \neq b. \quad (53)
\]

From these properties, one could calculate the entanglement entropy for any \(\sigma_{\Omega_1} \in \Sigma(\Omega_1)\) and find the element \(\sigma_{\Omega_1} \in \Sigma(\Omega_1)\) with the maximal entanglement entropy:

\[
S\left(\sum_a p_a \sigma_{\Omega_1}^a\right) = \sum_a \left(p_a S(\sigma_{\Omega_1}^a) - p_a \ln p_a \right)
= S(\sigma_{\Omega_1}^1) + \sum_a p_a \ln \left(\frac{d_2^a}{p_a}\right)
\leq S(\sigma_{\Omega_1}^1) + \ln D^2 \quad \text{“=” iff} \quad p_a = \frac{d_2^a}{D^2} \quad (54)
\Rightarrow \quad \sigma_{\Omega_1} = \sum_a \frac{d_2^a}{D^2} \sigma_{\Omega_1}^a. \quad (55)
\]

Where \(D = \sqrt{\sum_a d_2^a}\) is the total quantum dimension. It is obviously that \(S(\sigma_{\Omega_1}) - S(\sigma_{\Omega_1}^1) = \ln D^2\) is a topological invariance. Similar constructions apply to other subsystem topologies.

\[\text{FIG. 12: Divide } \Omega_1 \text{ into } A, B, C.\]

Now, let us divide \(\Omega_1\) in to subsystem \(A, B, C\) shown in Fig.12 and take the Levin-Wen definition of topological entanglement entropy \([13]\) (an overall minus sign is added):

\[
S_{\text{ topo}} = (S_{AB} + S_{BC} - S_B - S_{ABC})|_{\sigma^i} = I(A : C|B)|_{\sigma^i}. \quad (56)
\]

Where \(\sigma^i = |\psi\rangle\langle\psi|\) is the ground state density matrix, \(I(A : C|B) \equiv S_{AB} + S_{BC} - S_B - S_{ABC}\) is the conditional mutual information. According to the strong subadditivity \(I(A : C|B) \geq 0\) is true in general. Also, all reduced density matrices in \(\Sigma(\Omega_1)\) have the same reduced density matrix on \(AB, BC\) (for a proof, use the structure of \(\Sigma(\omega_1)\), and that \(AB \) and \(BC\) are of the same topology type as \(\omega_1\)). Therefore:

\[
\begin{align*}
\sigma_{AB} &= \sigma_{AB}^1 \\
\sigma_{BC} &= \sigma_{BC}^1
\end{align*} \quad \Rightarrow \quad I(A : C|B)|_{\sigma^i} = I(A : C|B)|_{\sigma^i} + S(\sigma_{\Omega_1}) - S(\sigma_{\Omega_1}^1)
&= I(A : C|B)|_{\sigma} + \ln D^2 \\
&\geq \ln D^2 \\
\Rightarrow \quad S_{\text{ topo}} &\geq \ln D^2 \quad \text{“=” iff} \quad I(A : C|B)|_{\sigma} = 0. \quad (57)
\]

Compare with the knowledge of TEE, the lower bound appears to be saturated and therefore $I(A : C|B)|\bar{\sigma} = 0$. This result may be treated as a generalization of our previous lower bound [15] into non-Abelian case. We aware that the reduced density matrix with maximal entanglement entropy $\sigma_{\Omega_1} \in \Sigma(\Omega_1)$ has zero conditional mutual information if simple assumptions (I) (II) in [14] are satisfied. The assumptions do satisfy for the ground states of exactly solved models for topological orders. On the other hand, given arbitrary $\rho_{ABC}$, it is in general not possible [16] to find a $\sigma_{ABC}$ such that: (1) $\sigma_{AB} = \rho_{AB}$; (2) $\sigma_{BC} = \rho_{BC}$; (3) $I(A : C|B)|\bar{\sigma} = 0$.

To summarize:

$$S_{\text{topo}} = S(\sigma_{\Omega_1}) - S(\sigma_{\Omega_2}) = \ln D^2.$$  \hfill (58)

This is true for exactly solved models satisfying (I) (II) assumption in [14]. There are evidences and believes that $S_{\text{topo}}$ is robust under generic local perturbations (which could be treated as finite depth quantum circuits), although very special examples like the Bravyi’s counterexample [17] could change $S_{\text{topo}}$. It might be interesting to study the stability of $S(\sigma_{\Omega_1}) - S(\sigma_{\Omega_2})$, $\sigma_{\Omega_1}$ and their generalizations.

### E. Bulk ribbon operators

Let us review bulk ribbon operators and the bulk topological excitations (bulk anyons) it creates. The review is brief and focusing on properties useful in our calculations. For more details we refer to [3, 6, 7].

A bulk ribbon operator $F_{\xi}^{h,g}$ is defined for an open ribbon $\xi$ in the bulk (bulk ribbon) and $h, g \in G$. See Fig.13 for a bulk ribbon connecting bulk sites $s_0$ and $s_1$. Let $|\varphi_{\xi}^{h,g}\rangle \equiv F_{\xi}^{h,g}|\psi\rangle$ (not normalized). One can show $|\varphi_{\xi}^{h,g}\rangle$ has eigenvalues $B_f = 1$, $A_v = 1$, $A_{\xi}^s = 1$ for all $f, v$ which are not contained in $s_0, s_1$ and for all $\xi'$. In other words, $F_{\xi}^{h,g}$ (when acting on a ground state or a state locally minimize energy) could create excitations only on $s_0$ and $s_1$. It is known that $\xi$ can be topologically deformed, in the sense that two ribbons $\xi$ both connecting $s_0$ and $s_1$, we have corresponding ribbon operators $F_{\xi'}^{h,g}$ and $F_{\xi'}^{h',g'}$ which are different operators, but $F_{\xi'}^{h,g}|\psi\rangle = F_{\xi'}^{h',g'}|\psi\rangle$.

The bulk ribbon operators have basic properties:

$$\langle F_{\xi}^{h,g}\rangle^\dagger = F_{\xi}^{h,g}, \quad F_{\xi}^{h,g} F_{\xi}^{h',g'} = \delta_{g,g'} F_{\xi}^{hh',g'}.$$  \hfill (59)

For $\xi = \xi_1\xi_2$, we have the “gluing relation”:

$$F_{\xi_1\xi_2}^{h,g} = \sum_{l \in G} F_{\xi_1}^{h_l} F_{\xi_2}^{l^{-1}g_l^{-1}}.$$  \hfill (60)

Change of basis: $\{F_{\xi}^{h,g}\} \to \{F_{\xi}^{(e,R)(u,v)}\}$:

$$F_{\xi}^{h,g} = \delta_{g,x_1x_2x_3x_4}, \quad F_{\xi}^{h,g} = \delta_{k,x_1x_2x_3x_4}.$$  \hfill (61)

**FIG. 13:** Bulk ribbon operators and boundary ribbon operators. (a) $F_{\xi}^{h,g}$, $h, g \in G$ is a bulk ribbon operator. $\xi$ is a bulk ribbon consist of bulk links and $x_1, x_2, x_3, x_4, y_1, y_2, y_3 \in G$. (b) $F_\xi^{h,k}$, $h \in G$ and $k \in K$ is a boundary ribbon operator. $\xi$ is a boundary ribbon (for $K$ boundary), consist of both boundary links with $x_1, x_2, x_3, x_4 \in K$ and bulk links with $y_1, y_2, y_3 \in G$. 

$$F_{\xi}^{(e,R)(u,v)} = \sum_{t \in E(e)} \Gamma_{R}^{\xi,j_1}(t) F_{\xi}^{\ell u,\ell v,i_1}.$$  \hfill (61)
Where:
1) \( c ∈ (G)_c j, \) i.e. \( c = \{ g r_c \bar{g} \mid g ∈ G \}. \) Where \( r_c \) is a representative of \( c. \)
2) \( E(c) \) is the centralizer group of \( c, \) defined as \( E(c) \equiv \{ g ∈ G \mid g r_c = r_c g \}. \)
3) \( R ∈ (E(c))_{ir} \) and \( n_R \) is the dimension of \( R. \) \( \Gamma_R \) is the unitary \( n_R \times n_R \) matrix associated with \( R, \) with components \( \Gamma_R^{ij}. \) \( \bar{\Gamma}_R^{ij} \) is the complex conjugate of \( \Gamma_R^{ij}. \)
4) \( P(c) = \{ p_i \}_{i=1}^{c |c|} \) is a set of representatives of \( G/E(c). \) \( c = \{ c_i \}_{i=1}^{c |c|} \) with \( c_i = p_i r_c \bar{p}_i. \)
5) \( u = (i, j), v = (i', j') \) with \( i, j = 1, \ldots, |c| \) and \( i', j' = 1, \ldots, n_R. \)

For more explanations of the notation, see Sec.IIA.

Note that we picked a normalization such that the "gluing relation" in this basis looks simple:

\[
F^c,R(\xi,\xi') = \sum_w F_{\xi,\xi'}^c,R(u,v) F_{\xi',\xi}^c,R(v,w),
\]

where \( w = (i'', j''). \) For an (open) bulk ribbon \( \xi: \)

\[
tr \left( F_{\xi}^{h,\varnothing} \sigma_{\xi} \right) = \frac{1}{|G|} \delta_{h,0} \Rightarrow tr \left( F_{\xi,\xi'}^{c,R}(u,v) F_{\xi'}^{c',R'}(u',v') \sigma_{\xi} \right) = \delta_{c,c'} \delta_{R,R'} \delta_{u,v} \delta_{u',v'} \frac{1}{|c| \cdot n_R}.
\]

Where \( \sigma^1_\xi \) is the ground state reduced density matrix on the ribbon \( \xi. \) \( \sigma^1_\xi \) is proportional to the identity unless there are \( A_{n}^{p} \) or \( B_{r} \) supported on \( \xi. \) Eq.(63) is true for both cases. This formula will be useful in the calculation of reduced density matrix.

For non-Abelian \( G, \) the ribbon operators \( F^c,R(\xi,\xi') \) are not unitary in general, but there are corresponding unitary operators. In addition to the theorems in Sec.III.C, explicit ribbon calculations can be done. From Eq.(63), the explicit wavefunction of the ground state \( |\psi\rangle \) and the HJW theorem one can show:

\[
|\psi|^c,R(\xi,\xi') \equiv \sqrt{|c| \cdot n_R} F_{\xi,\xi'}^{c,R}(u,v) |\psi\rangle = U(\xi)|\psi\rangle.
\]

Where \( U(\xi) \) is a unitary operator supported on a string-like region within a few lattice spacing to \( \xi. \) Note that the support of \( U(\xi) \) can be slightly fatter than \( \xi. \) This result is independent from whether the system has boundaries or not, the only requirement is that \( \xi \) can be contained in a disk-like subsystem in the bulk.

F. Boundary Ribbon operators

Let us consider a new type of ribbon operator \( I_{\xi}^{h,k} \) with \( h ∈ G, k ∈ K \) defined for open ribbon \( \xi \) lies along the boundary (boundary ribbon). See Fig.13 for a boundary ribbon connecting boundary sites \( s'_0 \) and \( s'_1. \) Very similar to bulk ribbon operators, \( I_{\xi}^{h,k} \) can create excitations only at \( s'_0 \) and \( s'_1 \) (when acting on a ground state or a state locally minimize energy). The boundary ribbon operators have the basic properties:

\[
(I_{\xi}^{h,k})^\dagger = I_{\xi}^{h,k}, \quad I_{\xi}^{h,k} I_{\xi}^{h',k'} = \delta_{k,k'} I_{\xi}^{h',h}. \tag{65}
\]

The "gluing relation" can be written as:

\[
I_{\xi}^{h,k}_{\xi,\xi'} = \sum_{l ∈ K} I_{\xi}^{h,l}_{\xi,\xi'} I_{\xi}^{l,k}_{\xi,\xi'}.
\]

Let us consider a linear combination:

\[
(I_{\xi}^{(\xi)T,R}(\xi,\xi')) = \sum_{t ∈ K^{TT}} \Gamma_{\xi}^{ij}_R(t) I_{\xi}^{t;q_i;\bar{q}_j}. \tag{67}
\]

Where:
1) \( T ∈ K/G/K \) is a double coset, i.e. \( T = \{ k_1 t_k k_2 \mid k_1, k_2 ∈ K \}. \) \( t_k ∈ G \) is a representative of \( T. \)
2) \( K^{TT} ≡ K \cap t_k K t_k^{−1} \) is a subgroup of \( K, \) and it depends on the choice of \( t_k \) in general.
3) \( R ∈ (K^{TT})_{ir} \) and \( n_R \) is the dimension of \( R. \) \( \Gamma_R \) is the unitary \( n_R \times n_R \) matrix associated with \( R, \) with components \( \Gamma_R^{ij} \) is the complex conjugate of \( \Gamma_R^{ij}. \)
4) \( Q = \{ q_i \}, i = 1, \ldots, |Q| \) is a set of representatives of \( K/K^{TT}. \) \( |Q| = |K|/|K^{TT}| = |T|/|K|. \) \( s_i ≡ q_i t_k \bar{q}_j. \)
5) \(u = (i, j), v = (i', j')\) with \(i, i' = 1, \ldots, |Q|\) and \(j, j' = 1, \ldots, n_R\).
For more explanations of the notation, see Sec.II A.

Note that, for a set of chosen \(r_T\), the set \(\{I^{(T,R)}(u,v)\}\) may contain less number of elements than \(\{I^{h,k}_\zeta\}\). We need to be careful to say it is a change of basis. For \(K = \{1\}\), it is a change of basis.

**Remark.** Our boundary ribbon operators \(I^{(T,R)}(u,v)\) are fundamentally different from the \(Y^c(T,R)(u,v)\) operators considered in [5]. The operator \(I^{(T,R)}(u,v)\) is defined for ribbon \(\zeta\) lies along the boundary, while the operator \(Y^c(T,R)(u,v)\) is defined for ribbon \(\rho\) inside the boundary. Unlike the model in [5], our model do not have Hilbert space for the interior of a boundary. Therefore, the excitations created by \(Y^c(T,R)(u,v)\) operator are not defined in our model. On the other hand, the excitation created by \(I^{(T,R)}(u,v)\) can be defined for not only in our model but also in models [5, 7].

The excitations created by \(I^{(T,R)}(u,v)\) are deconfined topological excitations (parallel to the topological excitations created by \(F^c(T,R)(u,v)\)) in the bulk. The middle part of the boundary ribbon \(\zeta\) can be deformed into the bulk. The excitations created by \(Y^c(T,R)(u,v)\) are confined, and the energy cost is proportional to the length of the ribbon \(\rho\). The ribbon operator \(Y^c(T,R)(u,v)\) cannot be deformed.

One could verify:

\[
tr \left( h_{\zeta} k_{\zeta} \sigma^1 \right) = \frac{1}{|K|} \delta_{1,h} \Rightarrow tr \left( I^{(T,R)}(u,v) I^{(T',R')}(u',v') \sigma^1 \right) = \frac{|K^{r_T}|}{n_R|R|} K_{T,T'} K_{R,R'} \delta_{u,u'} \delta_{v,v'}. \tag{68}
\]

Where \(\sigma^1\) is the ground state reduced density matrix on \(\zeta\), \(\sigma^1\) is generally not proportional to the identity unless \(K = \{1\}\) since for \(K \neq \{1\}\), and for a \(\zeta\) not too short, it must contain some \(A^k\) with \(k \neq 1\).

It turns out that the nice “gluing relation” parallel to Eq.(62) only appears for boundary ribbon operators with one additional constraint of \(T\) and \(r_T\), i.e. if there is a choice of \(r_T \in T\) such that \(r_T m = m r_T \) for \(\forall m \in K^{r_T}\). When choosing this \(r_T\), using Eq.(66,67) one derives:

\[
I^{(T,R)}(u,v) = \sum_w I^{(T,R)}(u,w) I^{(T,R)}(w,v) \quad \text{if} \quad r_T m = m r_T \quad \forall m \in K^{r_T}, \tag{69}
\]

where \(w = (i'', j'')\). This condition (and therefore Eq.(69)) holds for a large class of boundaries including:

1) \(K = \{1\}\) boundary for a general \(G\) quantum double.
2) \(K = G\) boundary for a general \(G\) quantum double.

The operators \(I^{(T,R)}(u,v)\) are not unitary in general, but there exist corresponding unitary operators.

\[
|\varphi^{(T,R)}(u,v)\rangle \equiv \sqrt{\frac{n_R}{|K|}} I^{(T,R)}(u,v) |\psi\rangle = U(\zeta) |\psi\rangle. \tag{70}
\]

Where \(U(\zeta)\) is a unitary operator supported on a string-like region within a few lattice spacing to \(\zeta\). Note that the support of \(U(\zeta)\) can be slightly farther than \(\zeta\). This result has been proved (up to normalization) in Sec.III C 1, and it can be shown by explicit calculation using Eq.(68), the explicit wavefunction of the ground state \(|\psi\rangle\) and the HJW theorem. This calculation also determines the overall normalization.

**G. Bulk ribbon operators and the extremal points of \(\Sigma(\Omega_1)\)**

Let us consider the \(\Omega_1\) subsystem discussed earlier, in Sec.III B. We show (with explicit calculation) that a pair of topological excitations (here are bulk anyons) \(\{a, \bar{a}\}\) created by a bulk process prepare the extremal point \(\sigma^0_{\Omega_1} \in \Sigma(\Omega_1)\).

This construction confirms that the extremal points of \(\Sigma(\Omega_1)\) are in one to one correspondence with bulk superselection sectors (bulk anyon types). Also see theorem III.3, for a powerful but less explicit way.

Consider the process and bulk ribbon shown in Fig.14, the bulk ribbon \(\xi = \xi_1 \xi_2 \xi_3\) connects bulk sites \(s_0\) and \(s_1\) which are separated by \(\Omega_1\). Define the excited state (normalized) \(|\varphi^{(c,R)}(u,v)\rangle \equiv \sqrt{|c|} F^{c,R}(u,v) |\psi\rangle\). From our knowledge about bulk ribbon operators, \(|\varphi^{(c,R)}(u,v)\rangle\) has excitations only at the two ends of \(\xi\), i.e. \(s_0\) and \(s_1\). Since \(s_0\) and \(s_1\) are away from \(\Omega_1\), it is clear that \(tr_{\Omega_1}|\varphi^{(c,R)}(u,v)\rangle \langle \varphi^{(c,R)}(u,v)| \in \Sigma(\Omega_1)\).

Now let us calculate \(tr_{\Omega_1}\langle \varphi^{(c,R)}(u,v)\rangle \langle \varphi^{(c,R)}(u,v)|\) from the “gluing relation” Eq.(62), one obtains

\[
F^{c,R}_{\xi_1 \xi_2 \xi_3}(u,v) = \sum_{w_1,w_2} F^{c,R}(u,w_1) F^{c,R}(w_1,w_2) F^{c,R}(w_2,v). \tag{71}
\]
And write the ground state $|\psi\rangle$ as:

$$|\psi\rangle = \sum_{h_a, h_b} \langle h_a \rangle_A \langle h_a \rangle_{\Omega_1} \langle h_b \rangle_B.$$  \hspace{2cm} (72)

Here, $\{h_a\}$ with $a = 1, \cdots, n$ is a set of link configurations, $h_a \in G$. Similarly, $\{h_b\}$ with $b = 1, \cdots, N$ is a set of link configurations, $h_b \in G$. The state $\{h_a\}_A$ is the unique equal weight superposition of all zero flux configurations determined by a set of $\{h_a\}$ on $\partial A$. The zero flux requirement tells us that $h_1 h_2 \cdots h_n = 1$. Similarly, the states $\{h_a\}_A \{h_b\}_B$ are the unique equal weight superposition of all zero flux configurations with fixed link values $h_a$ and $h_b$ satisfying $h_1 h_2 \cdots h_n = H_1 H_2 \cdots H_N = 1$.

Then one can calculate $\sigma_{\Omega_1}(c, R) \equiv \text{tr}_{\Omega_1} \varphi^\dagger \varphi(c, R)(u,w_1) \varphi^\dagger(c, R)(w_1,w_2)$. In other words, every extremal point of $\Sigma(\Omega_2)$ can be obtained by an anyon process in the bulk shown in Fig.14.

H. Boundary ribbon operators and the extremal points of $\Sigma(\Omega_2)$

Now consider the $\Omega_2$ subsystem discussed in Sec.III.B. As is shown in theorem III.2, it is possible to create a pair of excitations along the boundary by a unitary string operator along the boundary and the excitations could carry any boundary superselection sector. On the other hand, it is nice to have explicit constructions. In practice, we find that explicit constructions are challenging beyond models with the additional requirement: \textit{for every $T \in K \backslash G/K$, there exists $r_T \in T$ such that $r_T m = m r_T$ for all $m \in K^+$}, the same requirement for the “gluing relation” Eq.(69) to apply. The following constructions are restricted to models satisfying this requirement.

We show that a pair of topological excitations $(\alpha, \tilde{a})$ created by a process involve the boundary prepare the extremal point $\sigma^2_{\Omega_2} \in \Sigma(\Omega_2)$, with $\alpha = (T, R)$. This construction confirms the fact that the extremal points of $\Sigma(\Omega_2)$ have the same label as boundary superselection sector. The discussion here is very similar to that in Sec.III.G, and therefore will be brief. We have the “gluing relation”:

$$I_{\zeta_1 \zeta_2 \zeta_3}^{(T,R)}(u,v) = \sum_{w_1,w_2} I_{\zeta_1}^{(T,R)}(u,w_1) I_{\zeta_2}^{(T,R)}(w_1,w_2) I_{\zeta_3}^{(T,R)}(w_2,v).$$  \hspace{2cm} (75)
FIG. 15: The whole system is a disk $D^2$ and it is divided into subsystems $A, \Omega_2, B$. The bulk ribbon $\zeta$ connects bulk sites $s'_0$ and $s'_1$. $s'_0$ is in $A$ and $s'_1$ is in $C$. The ribbon $\zeta = \zeta_3\zeta_2\zeta_1$ with $\zeta_1 \in A, \zeta_2 \in \Omega_1$ and $\zeta_3 \in B$.

Define a state (normalized) with excitations created by a boundary ribbon operator and the corresponding reduced density matrix:

$$|\varphi^{(T,R)(u,v)}_\zeta\rangle \equiv \sqrt{\frac{n_R \cdot |K|}{|K^{rr}|}} I^{(T,R)(u,v)}_\zeta |\psi\rangle, \quad \sigma^{(T,R)}_{\Omega_2} \equiv \text{tr}_{\Omega_2} |\varphi^{(T,R)(u,v)}_\zeta\rangle\langle \varphi^{(T,R)(u,v)}_\zeta|.$$  \hfill (76)

One can show (up to normalization):

$$\sigma_\alpha(T,R) = \sum_{w_1, w_2} I^{(T,R)(w_1, w_2)}_{\zeta_2} \sigma_{\Omega_2} I^{(T,R)(w_1, w_2)_\dagger}_{\zeta_2}, \quad \sigma_\alpha^1 = \text{tr}_{\Omega_2} |\psi\rangle\langle \psi|.$$  \hfill (77)

From this expression, one can show $\sigma_\alpha(T,R)$ is identical to the extremal point $\sigma_{\Omega_2}^\alpha \in \Sigma(\Omega_2)$, with $\alpha = (T,R)$. Therefore, $\alpha = (T,R)$ labels both the boundary superselection sector and the extremal points of $\Sigma(\Omega_2)$. This further shows that $\Sigma(\Omega_2) = \Sigma(\Omega_2, \Omega_2^*)$ as long as $\Omega_2'$ contains $s'_0$ and $s'_1$. Using Eq.(68,69), the ground state wavefunction and the HJW theorem one can show boundary topological excitations $(\alpha, \hat{\alpha})$ at $s'_0$ and $s'_1$ can be moves by local unitary operators acting around $s'_0$ and $s'_1$ respectively.

IV. \textbf{$G$ QUANTUM DOUBLE WITH $K = \{1\}$ BOUNDARY}

The $K = \{1\}$ boundary ($K = \{1\}$ is the subgroup of $G$ which contains only the identity element) is particular simple, but it already have many nontrivial features. We take the opportunity to discuss $K = \{1\}$ in some details, and also discuss some additional things like $\Sigma(\Omega_2)_{\text{bulk}}, \Sigma(\Omega_2)$ etc.

A. \textbf{Boundary superselection sectors for a $K = \{1\}$ boundary}

For a $K = \{1\}$ boundary, each double superselection $T$ contains just one group element $T = \{g\}, g \in G$, so $r_T = g$. $K^{rr} = \{1\}$ and there is a unique irreducible representation of $K^{rr}$, i.e. the one dimensional identity representation $Id$. $(T,R) \rightarrow (\{g\}, Id)$, and the label $i, j$ can only take one possible value $i, j = 1$. Therefore, we will drop the $i, j$ indices.

The boundary superselection sectors $\alpha = (T,R) = (\{g\}, Id)$ are in one to one correspondence to the group elements. Because of this, we will use the simplified notation $\alpha \in G$. The quantum dimension of each boundary topological excitation is $d_\alpha = 1$ for $\forall \alpha \in G$.

B. \textbf{The information convex $\Sigma(\Omega_2)$ for a $K = \{1\}$ boundary}

Here, we repeat some calculation and result of Sec.III B 4 in the simple example $K = \{1\}$. Start with the minimal diagram. For a $K = \{1\}$ boundary, the Hilbert space for the minimal diagram is $\mathcal{H}^*(\Omega_2) = \text{span}\{|h, H\rangle | h, H \in G\}$. Where $\{h,H\} | h, H \in G \}$ is an orthonormal basis. The set $\Sigma^*(\Omega_2)$ is the set of density matrices $\sigma_{\Omega_2}$ on $\mathcal{H}^*(\Omega_2)$ satisfying the requirements:

1) $\sigma_{\Omega_2}^* = \sum_{h, H \in G} p(h,H) |h, H\rangle\langle h, H|$. Where $\{p(h,H)\}$ is a probability distribution.

2) $B\sigma_{\Omega_2} = \sigma_{\Omega_2} B$. Where $B|h, H\rangle = \delta_{h, H}|h, H\rangle$. 

From these requirements, it is straightforward to write down a general density matrix \( \sigma^\ast_{\Omega_2} \in \Sigma^\ast(\Omega_2) \):

\[
\sigma^\ast_{\Omega_2} = \sum_{h \in G} p_h |h, h\rangle \langle h, h|,
\]

\( \{p_h\} \) is a probability distribution. (78)

From this expression, it is obvious that each extremal point of \( \Sigma^\ast(\Omega_2) \) is labeled by a group element:

\[
\sigma^\ast_{\Omega_2} \equiv |\alpha, \alpha\rangle \langle \alpha, \alpha| \quad \text{with} \quad \alpha \in G.
\]

(79)

The quantum dimensions \( d_{\alpha} = 1 \) for \( \forall \alpha \in G \). The following properties of the extremal points can be easily checked:

\[
\sigma^\alpha_{\Omega_2} \cdot \sigma^\beta_{\Omega_2} = \delta_{\alpha, \beta} \sigma^\alpha_{\Omega_2} \quad \Rightarrow \quad S(\sigma^\alpha_{\Omega_2}) = 0, \quad \text{tr}[\sigma^\alpha_{\Omega_2} \cdot \sigma^\beta_{\Omega_2}] = \delta_{\alpha, \beta}.
\]

(80)

Now go back to \( \Sigma(\Omega_2) \). It has extremal points \( \sigma^\alpha_{\Omega_2} \) for \( \alpha \in G \) with \( \pi(\sigma^\alpha_{\Omega_2}) = \sigma^\alpha_{\Omega_2} \) and the following properties:

\[
\sigma^\alpha_{\Omega_2} \cdot \sigma^\beta_{\Omega_2} = \frac{\delta_{\alpha, \beta}}{G^{nN-2}} \sigma^\alpha_{\Omega_2} \quad \Rightarrow \quad S(\sigma^\alpha_{\Omega_2}) = (n + N - 2) \ln |G|, \quad \text{tr}[\sigma^\alpha_{\Omega_2} \cdot \sigma^\beta_{\Omega_2}] = \frac{\delta_{\alpha, \beta}}{G^{nN-2}}.
\]

(81)

From the properties of the extremal points one verifies the following topological invariant structures of \( \Sigma(\Omega_2) \):

\[
S(\sigma^\alpha_{\Omega_2}) = S(\sigma^\beta_{\Omega_2}), \quad \sigma^\alpha_{\Omega_2} \cdot \sigma^\beta_{\Omega_2} = 0 \quad \text{for} \quad \alpha \neq \beta, \quad \text{tr}[\sigma^\alpha_{\Omega_2} \cdot \sigma^\beta_{\Omega_2}] = \text{tr}[\sigma^\alpha_{\Omega_2} \cdot \sigma^\beta_{\Omega_2}].
\]

(82)

C. Boundary strings and the extremal points of \( \Sigma(\Omega_2) \)

For a \( K = \{1\} \) boundary, the boundary operators in the basis \( \{I^h_{\xi}\} \) with \( h \in G \) and \( k \in K \) now becomes \( \{I^\alpha_{\xi,1}\} \), with \( \alpha \in G \). The Hilbert space on each boundary link \( e' \) is one dimensional, and therefore any state in the total Hilbert space has a direct product on all boundary links \( e' \). We could neglect the boundary links and get an effect theory with a “rough boundary”. We will not do so, in order to keep it looks similar to \( K \neq \{1\} \) cases.

The basis \( \{I^\alpha_{\xi, (u,v)}\} \) now becomes \( \{I^\alpha_{\xi}\} \) with \( \alpha \in G \) since for \( K = \{1\} \) we could neglect the \( u,v \) labels and that \( R = Id \). One could verify the following change of basis \( \{I^\alpha_{\xi}\} \to \{I^\alpha_{\xi,1}\} \):

\[
I^\alpha_{\xi} = I^\alpha_{\xi,1}, \quad \forall \alpha \in G.
\]

(83)

Therefore, each \( I^\alpha_{\xi} \) is a product of local unitary operators each acting on a bulk link \( e \in \zeta \). It is easy to verify the following properties:

\[
(I^\alpha_{\xi})^\dagger = I^\alpha_{\xi}, \quad I^\alpha_{\xi} I^\beta_{\xi} = I^\beta_{\xi} I^\alpha_{\xi}, \quad \text{tr}(I^\alpha_{\xi} I^\beta_{\xi}) = \delta_{\alpha, \beta} \text{tr}(1), \quad I^\alpha_{\zeta_{2}} = I^\alpha_{\zeta_1}, \quad I^\alpha_{\zeta_1} = I^\alpha_{\zeta_2}, \quad I^\alpha_{\zeta} = I^\alpha_{\zeta}.
\]

(84)

Define \( |\psi^\alpha_{\xi}\rangle \equiv I^\alpha_{\xi}|\psi\rangle \). The middle part of the operator \( I^\alpha_{\xi} \) can be deformed into the bulk. For \( K = \{1\} \), the excitation type \( \alpha \in G \) has simple interpretation as “flux” type, see Fig.16. One may also consider the “fusion” of two fluxes \( \alpha \) and \( \beta \). The “fusion” result depends on the ordering: one obtains a flux \( \alpha \beta \) if \( \alpha \) was on the right of \( \beta \) and one obtains a flux \( \beta \alpha \) if \( \alpha \) was on the left of \( \beta \). \( \alpha \beta \neq \beta \alpha \) unless \( \alpha, \beta \) commute, even though \( d_{\alpha} = 1 \) for \( \forall \alpha \in G \). This process is more intricate than the fusion of two Abelian anyons in the bulk.

Let us reconsider the process in Fig.15. Let \( \zeta = \zeta_1 \zeta_2 \zeta_3 \), one can show that \( |\psi^\alpha_{\zeta}\rangle \) prepares an extremal point \( \sigma^\alpha_{\zeta_2} \in \Sigma(\Omega_2) \):

\[
\sigma_{\zeta_2}^\alpha = \text{tr}_{\zeta_2} |\psi^\alpha_{\zeta_2}\rangle \langle \psi^\alpha_{\zeta_2}| = \sigma_{\zeta_2}^\alpha \quad \text{with} \quad \pi(\sigma^\alpha_{\zeta_2}) = |\alpha, \alpha\rangle \langle \alpha, \alpha|.
\]

(85)

Therefore, the boundary operators \( \{I^\alpha_{\zeta}\} \) could prepare all the extremal points of \( \Sigma(\Omega_2) \). In this case, it is straightforward to verify that excitations \( (\alpha, \bar{\alpha}) \) at \( s_0^\alpha \) and \( s_1^\alpha \) can be moved by unitary operators acting around \( s_0^\alpha \) and \( s_1^\alpha \) respectively, since \( I^\alpha_{\zeta} \) itself is a product of local unitary operators each acting on a link.

D. Bulk processes and \( \Sigma(\Omega_2)_{\text{bulk}} \)

Let us consider what element of \( \Sigma(\Omega_2) \) could be produced by a bulk process. Define \( \Sigma(\Omega_2)_{\text{bulk}} \) to be a subset of \( \Sigma(\Omega_2) \) which could be explored by bulk processes. Explicitly:

\[
\Sigma(\Omega_2)_{\text{bulk}} \equiv \{\sigma_{\Omega_2} \in \Sigma(\Omega_2) | \sigma_{\Omega_2} = \text{tr}_{\Omega_2} |\varphi_{\text{bulk}}\rangle \langle \varphi_{\text{bulk}}| \} \quad \text{with} \quad |\varphi_{\text{bulk}}\rangle = U_{\text{bulk}}|\psi\rangle.
\]

(86)
Along the $K = \{1\}$ boundary, a $(\alpha, \bar{\alpha})$ pair is created by a unitary operator $I_\alpha \zeta$ which acting nontrivially on the green links. In this case, the $\alpha \in G$ labels the flux type of a single face, $abc = \alpha$. Where the link configurations $a, b, c \in G$ and $d = 1 \in K$.

A bulk unitary process creating a $(a, \bar{a})$ pair which can be explicitly constructed using a bulk ribbon operator. Where $U_{\text{bulk}}$ is a unitary operator supported on a bulk subsystem (a subsystem away from the boundary). For the quantum double model, it is enough to have $U_{\text{bulk}} = U_\bar{\Omega}_2 \otimes 1_{\Omega_2}$. Where $\Omega_2$ is an annulus covering a few layers of lattice around the boundary, see Fig.20.

For a $K = \{1\}$ boundary, consider a process involve a ribbon operators in the bulk, bulk anyon pair $(a, \bar{a})$ are separated by $\bar{\Omega}_2$, see Fig.17. According to the discussion in Sec.III E, it is a unitary process in the bulk. Calculations using similar method as Sec.III G shows:

$$|\varphi_{\xi}^{(c,R)(u,v)}\rangle = \sqrt{n_R \cdot |c|} \varphi_{\xi}^{(c,R)(u,v)} |\psi\rangle \Rightarrow \text{tr}_{\bar{\Omega}_2} |\varphi_{\xi}^{(c,R)(u,v)}\rangle \langle \varphi_{\xi}^{(c,R)(u,v)}| = \frac{1}{|c|} \sum_{i=1}^{|c|} \sigma_{\Omega_i}^{c_i}.$$  (87)

Recall, $c_i \in c$ is a group element in conjugacy class $c$ and $\sigma_{\Omega_i}^{c_i}$ is an extremal point of $\Sigma(\Omega_2)$.

Observe that, for a bulk process creating a $(a, \bar{a})$ pair, with $a = (c, R)$, if $|c| > 1$ then it does not prepare an extremal point of $\Sigma(\Omega_2)$. On the other hand, it can be shown (see Sec.IV F) that the bulk processes which create $(a, \bar{a})$ pairs do prepare all the extremal points of $\Sigma(\Omega_2)_{\text{bulk}}$. Therefore, $\Sigma(\Omega_2)_{\text{bulk}}$ is:

$$\Sigma(\Omega_2)_{\text{bulk}} = \{\sigma_{\Omega_2} | \sigma_{\Omega_2} = \sum_c p_c \sigma_{\Omega_i}^{c_i} \} \quad \text{with} \quad \sigma_{\Omega_2}^{c_i} = \frac{1}{|c|} \sum_{i=1}^{|c|} \sigma_{\Omega_i}^{c_i}.$$  (88)

Where $\{p_c\}$ is a probability distribution and $c \in (G)_{c,j}$.

In other words, for a $K = \{1\}$ boundary:

1) When $G$ is Abelian we always have $\Sigma(\Omega_2)_{\text{bulk}} = \Sigma(\Omega_2)$.

2) When $G$ is non-Abelian, we always have $\Sigma(\Omega_2)_{\text{bulk}} \subset \Sigma(\Omega_2)$.

Therefore, for non-Abelian models the boundary superselection sectors could not be identified as a subset of bulk superselection sectors and they need to be treated as fundamental.

### E. Some other boundary processes

In this section, we discuss a few more unitary processes which involve the boundary, see Fig.18 and Fig.19.
FIG. 18: (a) A unitary string operator creating a $(\bar{a}, \alpha)$ pair. (b) Extending a bulk ribbon in the bulk $\xi \to \bar{\xi}$ can be done by a local unitary operator $U(s_1)$ acting around $s_1$. (c) Extending a bulk ribbon to the boundary $\xi \to \xi'$ may not be achievable using local unitary operator $U(s_1)$ around $s_1$. The unitary process in Fig.18a creates a $(\bar{a}, \alpha)$ pair with $\bar{a} = (\bar{c}, \bar{R})$ (so that $a = (c, R)$) and $\alpha = c_i$. Where $c$ is the conjugacy class contain $\bar{c}$, and $\bar{R}$ is the complex conjugate of $R$ and $R \in (E(c))_\nu$ (note that $E(c) = E(\bar{c})$).

It is possible to write down explicit ribbon operator $F_{\xi}(c, R)(u, v)$ which realize this process. Where the ribbon $\xi'$ connects a bulk site $s_0$ and a boundary site $s'_1$, see Fig.18c. The corresponding excited state (normalized):

$$|\phi_{\xi}(c, R)(u, v)\rangle \equiv \sqrt{|c| \cdot n_R} F_{\xi}(c, R)(u, v)|\psi\rangle = U(\xi')|\psi\rangle.$$  

(89)

Where $u = (i, j)$, $v = (i', j')$ where $i, j = 1, \cdots, |c|$ and $j, j' = 1, \cdots, n_R$. It is straightforward to check that:

$$U_{\Omega_{1}}|\phi_{\xi}(c, R)(u, v)\rangle \langle \phi_{\xi'}(c, R)(u, v)| = s_{\Omega_{1}}^{\alpha} \quad \text{with} \quad \alpha = c_{i'}.$$  

(90)

It prepares an extremal point of $\Sigma(\Omega_{1}).$ The result depends only on the flux type $\alpha = c_{i'}$.

One may interpret this diagram as condensing a bulk anyon $a = (c, R)$ into a boundary topological excitation: $a \in c$ i.e. $a \to n_R \sum_{i=1}^{|c|} c_i$ for $a = (c, R)$. The condensation multiplicity equals $n_R$ and it matches the possible values of $j'$ (unlike the case for a bulk site, different $j'$ could not be changed by a local unitary process for $s'_1$ being a boundary site) [21].

The ribbon $\xi'$ is not a bulk ribbon, since we require a bulk ribbon to be away from the boundary. But it is not difficult to do an extension $\xi \to \xi'$ at the level of ribbon operator, in the same manner as extending a bulk ribbon into a longer bulk ribbon $\xi \to \bar{\xi}$. However, one important difference should be aware of, see Fig.18b,c.

As is already discussed in Sec.III G, the extension in Fig.18b, which correspond to move a bulk anyon $a$ from $s_1$ to $s_1$ can be done by a local unitary operation around $s_1$.

$$F_{\xi}(c, R)(u, v)|\psi\rangle = U(s_1)F_{\xi}(c, R)(u, v)|\psi\rangle.$$  

(91)

Now consider the extension $\xi \to \xi'$, i.e. go from the state $F_{\xi}(c, R)(u, v)|\psi\rangle$ to $F_{\xi'}(c, R)(u, v)|\psi\rangle$:

For $|c| = 1$, we have:

$$F_{\xi'}(c, R)(u, v)|\psi\rangle = U_{AB} \otimes 1_{\Omega_{2}} F_{\xi}(c, R)(u, v)|\psi\rangle \quad \text{for} \quad |c| > 1.$$  

(92)

This result follows from Eq.(87,90) and the HJW theorem. For the case $|c| = 1$, $n_R = 1$ explicit construction shows $F_{\xi}(c, R)(u, v)|\psi\rangle = U(s_1)F_{\xi}(c, R)(u, v)|\psi\rangle$. On the other hand, even for the simple case $c = \{1\}$, $n_R > 1$, i.e. condense into the vacuum $\alpha = 1$, Eq.(92) holds only for $U_{AB} \neq U_{A} \otimes U_{B}$. Therefore $F_{\xi'}(c, R)(u, v)|\psi\rangle \neq U(s_1)F_{\xi}(c, R)(u, v)|\psi\rangle$.

For $|c| > 1$:

$$F_{\xi'}(c, R)(u, v)|\psi\rangle \neq U_{AB} \otimes 1_{\Omega_{2}} F_{\xi}(c, R)(u, v)|\psi\rangle \Rightarrow F_{\xi'}(c, R)(u, v)|\psi\rangle \neq U(s_1)F_{\xi}(c, R)(u, v)|\psi\rangle \quad \text{for} \quad |c| > 1.$$  

(93)

This result follows from Eq.(87,90) and the HJW theorem. For $|c| > 1$, $n_R = 1$, one can use $U(s_1)$ to push the bulk anyon $a = (c, R)$ into an equal weight superposition of boundary topological excitations with $\alpha = c_i$, $i = 1, \cdots, |c|$. Only after a measurement of boundary topological excitation type can we obtain a state with fixed $\alpha$. For $|c| > 1$,
\( n_R > 1 \), one need to use \( U_{AB} \otimes 1_{\Omega_2} \) instead of \( U(s_1) \), to push \( \alpha = (c, R) \) into an equal weight superposition of boundary topological excitations with \( \alpha = c_i, i = 1, \cdots, |c| \). Here \( U_{AB} \neq U_A \otimes U_B \).

In comparison, the following can always be done by local unitary operations:

1) Creating a \((\alpha, \alpha)\) pair separated by a small distance. Where \( \alpha = (c, R) \) and \( \alpha = c' \) are fixed. Then one may also move \( \bar{a} \) away from \( \alpha \) step by step using a sequence of local unitary operations. The support of the local unitary operators in the sequence may overlap with each other.

2) Start from an excited state with a \((\bar{a}, \alpha)\) pair, where \( \alpha = (c, R) \) and \( \alpha = c' \), see Fig.18a. Push \( \bar{a} \) towards the boundary, and then condense \( \bar{a} \) into a boundary topological excitation. In this case, the \( \bar{a} \) will condense into \( \bar{a} \) instead of a superposition.

Another intriguing process is to have a pair of bulk anyon \((\bar{a}, \alpha)\) created using a string attaches to the boundary (which could not be deformed into the bulk completely), see Fig.19. This could not happen for a quantum double model with Abelian \( G \). On the other hand, this type of boundary process exist for all quantum double models with non-Abelian \( G \) and \( K = \{1\} \) boundary.

One can write down explicit ribbon operators with support on Fig.19b for this unitary process:

\[
|\varphi^{(a,\bar{a})}_{\xi'_1,\xi'_2}\rangle \equiv |c\rangle \cdot n_R \cdot F_{\xi'_1}^{(c,R)(u_1,v_1)} \cdot F_{\xi'_2}^{(c,R)(u_2,v_2)} \cdot |\psi\rangle = U(\xi'_1,\xi'_2) |\psi\rangle.
\] (94)

Where \( u_1 = (i_1, j_1) \), \( v_1 = (i'_1, j'_1) \), \( u_2 = (i_2, j_2) \) and \( v_2 = (i'_2, j'_2) \), with the requirement \( c'_i = c_i \). \( U(\xi'_1,\xi'_2) \) is a unitary operator supported on a string-like region within a few lattice spacing to \( \xi'_1,\xi'_2 \). Explicit calculation shows:

\[
tr_{\Omega_2} |\varphi^{(a,\bar{a})}_{\xi'_1,\xi'_2}\rangle \langle \varphi^{(a,\bar{a})}_{\xi'_1,\xi'_2} | = \sigma^a_{\Omega_2}.
\] (95)

For \(|c| > 1 \), \( |\varphi^{(a,\bar{a})}_{\xi'_1,\xi'_2}\rangle \neq U_{bulk} |\psi\rangle \) since \( \sigma^a_{\Omega_2} \notin \Sigma(\Omega_2)_{bulk} \) for \( \alpha = c_i \) with \(|c| > 1 \) and therefore the string could not be deformed into the bulk [22]. Furthermore, it can be shown this process is related to the process in Fig.15 and Fig.18 by unitary operations in \( A \) and \( B \), i.e.:

\[
|\varphi^{(a,\bar{a})}_{\xi'_1,\xi'_2}\rangle = U_A \otimes U_B \otimes 1_{\Omega_2} |\varphi^a_{\xi'_1}\rangle = \bar{U}_A \otimes 1_B \otimes 1_{\Omega_2} |\varphi^{(c,R)(u,v)}_{\xi'_1}\rangle.
\] (96)

Therefore, it is possible to pull the pair \((\alpha, \bar{a})\) into the bulk using local unitary process around \( \alpha \) and \( \bar{a} \) to get a state with an \((\alpha, \bar{a})\) pair.

**F. A new subsystem \( \Omega_3 \): infinite extremal points of \( \Sigma(\Omega_3) \) from condensation multiplicity**

Now consider a subsystem of \( \Omega_3 \) topology, see Fig.20. It is an annulus with one edge identified with the boundary (recall that the relation to the boundary is part of the topological data). A natural motivation of considering \( \Omega_3 \) is that excitations in the bulk may be created by a string operator attaches to the boundary. If so, it leaves footprints on \( \Omega_3 \). We will also see that the structure of \( \Sigma(\Omega_3) \) is closed related to condensing of bulk anyons into the vacuum \((\alpha = 1)\) of the \( K = \{1\} \) boundary and there is infinite number of extremal points for non-Abelian \( G \).

Define \( \mathcal{H}^*(\Omega_3) = span\{\{h, t\}| h, t \in G\} \) be the Hilbert space for the minimal diagram in Fig.20, where \( \{\{h, t\}| h, t \in G\} \) is an orthonormal basis. Define \( \Sigma^*(\Omega_3) \) be a set of density matrices \( \sigma^*_\Omega \) on \( \mathcal{H}^*(\Omega_3) \) satisfying the following requirements:
FIG. 20: An illustration of the subsystem $\Omega_3$ and the corresponding minimal diagram.

1) $\sigma_3^\ast = \sum_{h \in G} \sum_{\lambda} p_h^\ast |\{h\}; \lambda \rangle \langle \{h\}; \lambda |$ Where $\{p_h^\ast\}$ is a probability distribution and $|\{h\}; \lambda \rangle = \sum_{t \in G} c_\lambda(t)|h,t \rangle$ with complex coefficients $c_\lambda(t)$ satisfying $\sum_{t \in G} |c_\lambda(t)|^2 = 1$.

2) $B\sigma_3^\ast = \sigma_3^\ast$. Where $B|h,t \rangle = \delta_1|h,t \rangle$.

3) $A^g_1\sigma_3^\ast A^g_1 = \sigma_3^\ast$ for $\forall g \in G$. Where, $A^g_1|h,t \rangle = |gh,gt \rangle$.

We find the problem of finding $\Sigma^\ast(\Omega_3)$ maps exactly to a problem solved in proposition II.3. The result is that $\Sigma^\ast(\Omega_3)$ has a set of extremal points $\sigma_{\Omega_3}^{s(R,z)}$:

$$\sigma_{\Omega_3}^{s(R,z)} = \frac{1}{n_R} \sum_{j=1}^{n_R} |z(j,R)| \langle z(j,R)|, \quad |z(j,R)| = \sum_{j'} z_{j'} \sqrt{\frac{n_R}{|G|}} \sum_{g \in G} \Gamma_{j,j'}^R(g)|1,g\rangle.$$

(97)

Where the complex numbers $z_j$ satisfy $\sum_{j=1}^{n_R} |z_j|^2 = 1$. $R \in (G)_{ir}$. The parameter $\{z_j\}$ has equivalence (redundancy) $\{z_{j'} \sim \{z_j e^{i\theta}\}$ and $\sigma_{\Omega_3}^{s(R,z)}$ is really parameterized by points on the manifold $S^{2n_R-1}/S^1$.

Let us use the notation $\langle z'|z\rangle \equiv \sum_{j=1}^{n_R} z_j z_{j'}$. One can show:

$$\langle z(j,R)|z'(j',R') \rangle = \delta_{R,R'} \delta_{j,j'} \langle z|z'\rangle \Rightarrow tr[\sigma_{\Omega_3}^{s(R,z)} \cdot \sigma_{\Omega_3}^{s(R',z)}] = \delta_{R,R'} \frac{1}{n_R} |\langle z|z'\rangle|^2, \quad S(\sigma_{\Omega_3}^{s(R,z)}) = \ln n_R.$$

(98)

From the similarity between $\Sigma(\Omega_3)$ and $\Sigma^\ast(\Omega_3)$ we find the extremal points of $\Sigma(\Omega_3)$ have the same parameterization, i.e. $\sigma_{\Omega_3}^{(R,z)}$, with the properties:

$$tr[\sigma_{\Omega_3}^{s(R,z)} \cdot \sigma_{\Omega_3}^{s(R',z')}] = \delta_{R,R'} \frac{1}{n_R} |\langle z|z'\rangle|^2, \quad S(\sigma_{\Omega_3}^{s(R,z)}) = \ln n_R + (n-1) \ln |G|.$$

(99)

The following structures of $\Sigma(\Omega_3)$ are topological invariants (note that $\sigma_{\Omega_3}^{\ast(1,d,z)} \equiv tr_{\Omega_3}|\psi\rangle\langle \psi| = \sigma_{\Omega_3}^{(1,d,z)}$):

$$\frac{tr[\sigma_{\Omega_3}^{s(R,z)} \cdot \sigma_{\Omega_3}^{s(R',z')}]}{tr[\sigma_{\Omega_3}^{s(R,z)} \cdot \sigma_{\Omega_3}^{s(R',z')}] = \delta_{R,R'} \frac{1}{d_a} |\langle z|z'\rangle|^2, \quad S(\sigma_{\Omega_3}^{s(R,z)}) = S(\sigma_{\Omega_3}^{s(R,z)}) + \ln d_a.$$

(100)

Where we have used $d_a = n_R$ for $a = (\{1\},R)$.

A string operator attaches to the boundary which creates a single anyon $a$ in the bulk could prepare extremal points of $\Sigma(\Omega_3)$. This process can be thought of as creating a pair $(a,\alpha)$ with $a = (\{1\},R)$ and $\alpha = 1$, a special case of the string operator in Fig.18.

$$|\varphi^{(1,R)}_{\xi}(u,v)\rangle = \sqrt{c} \cdot n_R F_{\xi}^{(1,R)}(u,v)|\psi\rangle, \quad |\varphi^{(R,z)u}_{\xi'}\rangle = \sum_{j'=1}^{n} z_{j'} |\varphi^{(1,R)}_{\xi}(u,v=1,j')\rangle.$$

(101)

Calculation shows:

$$tr_{\Omega_3}|\varphi^{(R,z)u}_{\xi'}\rangle\langle \varphi^{(R,z)u}_{\xi'}| = \sigma_{\Omega_3}^{(R,z)}.$$

(102)

Let us consider braiding an $(\alpha,\alpha)$ pair around the boundary, assuming there are no other excitations along the boundary. It corresponds to a unitary operator $W(\alpha)$ acting on a closed loop along the boundary (a closed string version of $F_{\xi}^{(\alpha)}$). $W(\alpha)W(\beta) = W(\alpha\beta), W(\alpha)^\dagger = W(\bar{\alpha})$. One can check:

$$W(\alpha)|\psi\rangle = |\psi\rangle \quad \forall \alpha \in G.$$

(103)
FIG. 21: (a) A unitary string operator attaches to the boundary. It creates an anyon \( a \) in the bulk. (b) The unitary operator \( W(\alpha) \) is supported on the yellow loop along the boundary. It represent a braiding of \( (\alpha, \bar{\alpha}) \) pair around the boundary.

The braiding \( W(\alpha) \) generates a structure preserving bijective mapping \( W(\alpha): \Sigma(\Omega_3) \to \Sigma(\Omega_3) \) such that \( \sigma_{\Omega_3} \to W(\alpha)\sigma_{\Omega_3}W(\bar{\alpha}). \) One can check the mapping on extremal points:

\[
W(\alpha)\sigma_{\Omega_3}^{(R,\bar{R})}W(\bar{\alpha}) = \sigma_{\Omega_3}^{(R,\bar{R})} \quad \text{with} \quad \bar{z}_b = \sum_{c=1}^{n_n} \Gamma_{bc}^{R}(\alpha)z_c. \tag{104}
\]

The mapping does not mix different \( R \), and on each manifold \( S^{2n_n-1}/S^1 \) it realize a group action of \( G \).

Furthermore, \( W(\alpha) \) provides a simple proof of the structure of \( \Sigma(\Omega_2)_{bulk} \) claimed in Sec.IV D. Consider a unitary operator \( U_{bulk} \) supported on a bulk subsystem and \( |\varphi_{bulk}\rangle \equiv U_{bulk}|\psi\rangle \).

\[
W(\alpha)|\psi\rangle = |\psi\rangle, \quad [W(\alpha), U_{bulk}] = 0 \quad \Rightarrow \quad W(\alpha)|\varphi_{bulk}\rangle = |\varphi_{bulk}\rangle. \tag{105}
\]

Let us assume it prepares an element of \( \Sigma(\Omega_2) \), i.e. \( \rho_{\Omega_2} \equiv \rho_{\Omega_2} |\varphi_{bulk}\rangle\langle\varphi_{bulk}| \in \Sigma(\Omega_2) \) then, by definition \( \rho_{\Omega_2} \in \Sigma(\Omega_2)_{bulk} \). Any extremal point of \( \Sigma(\Omega_2)_{bulk} \) can be written in this form since purification exists. From Eq.(105) and that \( W(\alpha) \) can be written as a product of unitary operators on \( \Omega_2 \) and \( \Omega_2 \), i.e. \( W(\alpha) = W_{\Omega_2}(\alpha) \otimes W_{\Omega_2}(\bar{\alpha}) \) one derives:

\[
\rho_{\Omega_2} = W_{\Omega_2}(\alpha)\rho_{\Omega_2}W_{\Omega_2}(\bar{\alpha}) \quad \forall \alpha \in G. \tag{106}
\]

Writing \( \rho_{\Omega_2} = \sum_h p_h \sigma_{\Omega_2}^h \) and notice that \( W_{\Omega_2}(\alpha)\sigma_{\Omega_2}^hW_{\Omega_2}(\bar{\alpha}) = \sigma_{\Omega_2}^{h^2\alpha} \), one finds \( p_h = p_{h'} \) for \( h \) and \( h' \) belong to the same conjugacy class. Therefore, \( \Sigma(\Omega_2)_{bulk} \) can only be a subset of the result claimed in Eq.(88). Finally, due to the explicitly constructed extremal points, \( \Sigma(\Omega_2)_{bulk} \) is no smaller than what is claimed in Eq.(88), so the result in Eq.(88) is proved.

V. THE \( S_3 \) QUANTUM DOUBLE WITH \( K = \{1\} \) BOUNDARY

In this section, we provide some additional details for the \( S_3 \) quantum double with \( K = \{1\} \) boundary i.e. explain our notations and point to some references.

\( S_3 \) is the simplest non-Abelian finite group and the \( S_3 \) quantum double model is discussed as examples by many references. For example, [7] contains detailed anyon types, fusion rules and \( S \)-matrix of the \( S_3 \) quantum double. On the other hand, our notation for bulk anyons \( \{1, A, J^u, J^f, J^v, J^s, K^a, K^b\} \) is similar with [4]. The condensation rules for the \( S_3 \) quantum double with \( K = \{1\} \) boundary is discussed in [5] in a different physical context. The following is some details of our notation.

A. Bulk superselection sectors

Given that the bulk superselection sectors (or bulk anyon types) are labeled by \( a = (c, R) \) with \( c \in (G)_{cR} \) and \( R \in (E(c))_{sr} \), the 8 superselection sectors for the \( S_3 \) quantum double model \( \{1, A, J^u, J^f, J^v, J^s, K^a, K^b\} \) can be worked out. Where \( S_3 = \{1, r, r^2, s, sr, sr^2\} \) with \( r^3 = s^3 = 1 \) and \( sr = r^2s \). See the following table for more details:

| Representations | \( \Gamma_{Jd}(g) \) | \( \Gamma_A(r) \) | \( \Gamma_A(s) \) |
|----------------|------------------|-----------------|-----------------|
| For \( R \in (S_3)_{sr} \) | 1 | 1 | -1 |

1) \( \Gamma_{Jd}(g) = 1 \) for \( \forall g \in S_3 \).
2) \( \Gamma_A(r) = 1 \) and \( \Gamma_A(s) = -1 \). Other \( \Gamma_A(g) \) for \( g \in S_3 \) can be obtained using \( \Gamma_A(r) \) and \( \Gamma_A(s) \).
3) $\Gamma_B(r) = \begin{pmatrix} \omega & 0 \\ 0 & \omega^2 \end{pmatrix}$ and $\Gamma_B(s) = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$. Where $\omega \equiv e^{i\pi/3}$. Other $\Gamma_B(g)$ for $g \in S_3$ can be obtained using $\Gamma_B(r)$ and $\Gamma_B(s)$.

For $R \in (Z_3)_\text{ir}$, $Z_3 = \{1, r, r^2\}$, the corresponding unitary matrices $\Gamma_B(g)$ with $g \in Z_3$ are:
1) $\Gamma_R(g) = 1$ for $\forall g \in Z_3$.
2) $\Gamma_\omega(1) = 1, \Gamma_\omega(r) = \omega, \Gamma_\omega(r^2) = \omega^2$. Where $\omega \equiv e^{i\pi/3}$.
3) $\Gamma_\omega(1) = 1, \Gamma_\omega(r) = \omega^2, \Gamma_\omega(r^2) = \omega$. Where $\omega \equiv e^{i\pi/3}$.

For $R \in (Z_2)_\text{ir}$, $Z_2 = \{1, s\}$, the corresponding unitary matrices $\Gamma_B(g)$ with $g \in Z_2$ are:
1) $\Gamma_R(g) = 1$ for $\forall g \in Z_2$.
2) $\Gamma_\alpha(1) = 1, \Gamma_\alpha(s) = -1$.

### B. The fusion rules of $S_3$ quantum double

The following fusion rules of the $S_3$ quantum double model can be found in [4].

\[
\begin{align*}
A \times A &= 1 \\
A \times K^a/b &= K^{b/a} \\
A \times J^a &= J^a \\
J^a \times J^a &= 1 + A + J^a \\
J^a \times J^b &= J^a + J^b \\
J^a \times K^b &= K^a + K^b \\
K^a \times K^b &= 1 + J^w + J^x + J^y + J^z \\
K^a \times K^b &= A + J^w + J^x + J^y + J^z
\end{align*}
\]

(107)

Where $\alpha, \beta, \gamma$ and $\delta$ are running indices. $\alpha, \beta, \gamma$ and $\delta$ with values different from each other in the equation which has all of them, i.e. in $J^a \times J^b = J^a + J^b$. The fusion rules (in a different notation) together with the calculation method for a general quantum double model can be found in [7].

### C. $K = \{1\}$ boundary superselection sectors and condensation rules

According to Sec.IV, the boundary superselection sectors (boundary topological excitation types) of a $K = \{1\}$ boundary are labeled by the group element $\alpha \in G$. Therefore, for $G = S_3$ we have 6 types $\{1, r, r^2, s, sr, sr^2\}$. $\alpha \in S_3$ correspond to $(T, R) = (\{\alpha\}, \text{Id})$.

\[
\begin{array}{|c|c|c|c|c|c|c|}
\hline
T & \{1\}/S_3/\{1\} & \{1\} & \{r\} & \{r^2\} & \{s\} & \{sr\} & \{sr^2\} \\
\hline
\tau_T & 1 & r & r^2 & s & sr & sr^2 \\
\hline
K^{\tau_T} & \{1\} & \{1\} & \{1\} & \{1\} & \{1\} & \{1\} \\
\hline
Q = K^{\tau_T} & \{1\} & \{1\} & \{1\} & \{1\} & \{1\} & \{1\} \\
\hline
\{\alpha\}^{Q_1} & \{1\} & \{1\} & \{1\} & \{1\} & \{1\} & \{1\} \\
\hline
R \in (K^{\tau_T})_\text{ir} & \text{Id} & \text{Id} & \text{Id} & \text{Id} & \text{Id} & \text{Id} \\
\hline
n_R & 1 & 1 & 1 & 1 & 1 & 1 \\
\hline
\alpha & 1 & r & r^2 & s & sr & sr^2 \\
\hline
d_\alpha & 1 & 1 & 1 & 1 & 1 & 1 \\
\hline
\end{array}
\]

The following condensation rules are discussed [5] in the physical context of confined boundary excitations.

The same condensation rules also apply to our case, i.e. condense a bulk anyon into a deconfined boundary topological excitation. This is suggested by the construction of ribbon operators and the results of $\Sigma(\Omega_2)$. $\Sigma(\Omega_2)_{\text{bulk}}$
\( c \in (S_3)_c \) | \( c_1 = \{1\} \) | \( c_r = \{r, r^2\} \) | \( c_s = \{s, sr, sr^2\} \)

| \( a \) | \( 1 \) | \( A \) | \( J^w \) | \( J^x \) | \( J^y \) | \( K^\alpha \) | \( K^\beta \) |
|-----|-----|-----|-----|-----|-----|-----|-----|
| \( \alpha \) | 1 | 1 | 2 | 1 | \( r \) | \( r^2 \) | \( s \) | \( sr \) | \( sr^2 \) |

and \( \Sigma(\Omega_3) \), see Sec.IV. The condensation rules may also be extracted from the information convex \( \Sigma(\Omega) \) of a single subsystem \( \Omega \) with a different topology.

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[18] The Minkowski-Caratheodory Theorem together with its generalization to infinite dimension i.e. the Krein-Milman Theorem can be found in the following link: http://math.caltech.edu/Simon_Chp8.pdf.
[19] Or \( h_s^I \in K \) for the case involve boundary links in the Ith piece. This will not happen in this paper.
[20] The \(- \ln |G| + \ln |K| \) in Eq.(39) may also be regarded as a topological contribution for a system attached to a boundary, but in order to extract this contribution using a linear combination cancels out local contributions of entanglement entropy, one needs more than one boundary type.
[21] These condensation multiplicity can be seen from \( \Sigma(\Omega) \) of some suitable \( \Omega \).
[22] The type of process in Fig.19 which could not be deformed into the bulk completely actually beyond the \(|c| > 1 \) case.