Abstract: We consider elliptic operators with measurable coefficients and Robin boundary conditions on a bounded domain $\Omega \subset \mathbb{R}^d$ and show that the first eigenfunction $v$ satisfies $v(x) \geq \delta > 0$ for all $x \in \overline{\Omega}$, even if the boundary $\partial \Omega$ is only Lipschitz continuous. Under such weak regularity assumptions the Hopf–Oleinik boundary lemma is not available; instead we use a new approach based on an abstract positivity improving condition for semigroups that map $L_p(\Omega)$ into $C(\overline{\Omega})$. The same tool also yields corresponding results for Dirichlet or mixed boundary conditions. Finally, we show that our results can be used to derive strong minimum and maximum principles for parabolic and elliptic equations.

Keywords: Maximum Principle, Irreducible Semigroup, Elliptic Operator

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1 Introduction

A frequent situation occurring in the study of elliptic but also parabolic boundary value problems with real coefficients on a bounded domain $\Omega \subset \mathbb{R}^d$ is the following. The solutions satisfy a weak maximum principle and there exists a principal eigenvalue with a principal eigenfunction $u_0$ satisfying $u_0(x) > 0$ a.e. on $\Omega$. By elliptic regularity one also shows that $u_0 \in C(\overline{\Omega})$. But what is not known is whether $u_0(x) \geq \delta > 0$ for all $x \in \overline{\Omega}$. We shall show this under very weak regularity assumptions. Such a result has applications for the construction of super- and subsolutions (see Daners–López-Gómez [14]), but also for the asymptotic behaviour of parabolic problems.

Let us describe a concrete situation. Let $\Omega \subset \mathbb{R}^d$ be a bounded Lipschitz domain and $\beta \in L_{\infty}(\partial \Omega)$. Given $u_0 \in C(\overline{\Omega})$ there exists a unique $u \in C([0, \infty) \times \overline{\Omega}) \cap C^\infty((0, \infty) \times \Omega)$ such that

$$\frac{\partial}{\partial t} u = \Delta u,$$

$$u(0, x) = u_0(x) \quad \text{for all } x \in \overline{\Omega},$$

$$(\partial_\nu u)(t, z) + \beta(z) u(t, z) = 0 \quad \text{for all } z \in \partial \Omega \text{ and } t > 0.$$
We shall show in Theorem 4.5 that if $u_0(x) \geq 0$ and $u_0 \not= 0$, then $u(t,x) > 0$ for all $x \in \bar{\Omega}$ and $t > 0$. This implies in particular that the principal eigenfunction $v \in C(\bar{\Omega})$ of the Robin Laplacian is strictly positive; that is, there exists a $\delta > 0$ such that $v(x) \geq \delta$ for all $x \in \Omega$. If $\partial \Omega$ and the eigenfunction are smooth enough, this property is known and can then be deduced from Hopf’s maximum principle [11, 21] (on the interior) and the Hopf–Ole˘ınik boundary lemma (see for instance [2]). We shall prove the result for Lipschitz domains and arbitrary elliptic operators in divergence form with bounded real measurable coefficients, without any assumptions on the smoothness of the eigenfunction. This new result is important for applications to non-linear problems (see for example [14]).

Our arguments are best placed in a more abstract situation. Let $S$ be a $C_0$-semigroup on $L_2(\Omega)$ which is positive and holomorphic. Then $S$ is irreducible (see below for the definition) if and only if $S$ is positivity improving in the sense that if $u \geq 0$ and $u \not= 0$, then for each $t > 0$ one has $(S_t u)(x) > 0$ for almost every $x \in \Omega$. Irreducibility on $L_2(\Omega)$ is very easy to prove by the use of the Beurling–Deny–Ouhabaz criterion [25, Theorem 2.10] and implies for the principal eigenfunction $v$ that $v(x) > 0$ almost everywhere. In contrast to this, irreducibility in $C(\bar{\Omega})$ is much stronger: it implies that $v(x) \geq \delta > 0$ for all $x \in \bar{\Omega}$ and some $\delta > 0$. Our main argument in Section 3 shows that irreducibility in $L_2(\Omega)$ already implies irreducibility in $C(\bar{\Omega})$ if $S_t L_2(\Omega) \subset C(\bar{\Omega})$ for all $t > 0$ and if $(S_t|_{C(\bar{\Omega})})_{t>0}$ is a $C_0$-semigroup on $C(\bar{\Omega})$ (see Theorem 3.1 and Corollary 3.2).

In Section 4 we will apply this result not only to elliptic problems with Robin boundary conditions, but also to mixed boundary conditions, where we impose Neumann boundary conditions on a relatively open subset $N$ of $\partial \Omega$ and where we prove that $(S_t u)(x) > 0$ for all $t > 0$ and $x \in \partial \Omega \cap N$ whenever $u \geq 0$ and $u \not= 0$.

In Section 5 we will also prove a strong minimum principle for the heat equation. Given a continuous function $\psi$ on the parabolic boundary $\partial^* \Omega_T$ of the cylinder $\Omega_T = (0, T) \times \Omega$, there is a unique solution $u \in C(\bar{\Omega}_T)$ of the heat equation $u_t - \Delta u = 0$ which coincides with $\psi$ on $\partial^* \Omega_T$. We shall show that if $\psi \geq 0$ and $u(t_0, x_0) = 0$ for some $(t_0, x_0) \in \Omega_T$, then $u(t, x) = 0$ for all $(t, x) \in \Omega_T$ such that $t < t_0$. Again, this also remains true if the Laplacian $\Delta$ is replaced with an elliptic operator (see Theorem 5.2). As a nice consequence, we also obtain a new proof of the strong parabolic maximum principle for elliptic operators in divergence form with bounded real measurable coefficients.

The paper is organised as follows. After a general introduction to irreducibility in Section 2, we establish our main abstract result in Section 3. Principal eigenvectors for elliptic problems with diverse boundary conditions are considered in Section 4 and the strong minimum principle is established in Section 5. For the parabolic operator we have two notions of solutions: mild and weak. For the mild solution we do not need any regularity on the coefficients of the operator, but in order to define the weak solutions we need some differentiability. Under these differentiability conditions we show that weak solutions and mild solutions are equivalent. For the latter equivalence we need a regularity result, for which we provide an elementary proof in the appendix.

2 Preliminaries: Irreducibility

In this section we recall the notions of positivity and irreducibility as well as some results which are used later. General references for this topic are [7] and [10].

Throughout the section, let $E$ be a Banach lattice over $K$, where the field $K$ is either $\mathbb{R}$ or $\mathbb{C}$. We are especially interested in the following cases.

**Example 2.1.** Let $\Omega \subset \mathbb{R}^d$ be an open non-empty set. The following spaces are examples of Banach lattices:

(a) $E = L_p(\Omega)$, where $p \in [1, \infty)$.
(b) $E = C(\bar{\Omega})$, if $\Omega$ is bounded.
(c) $E = C_0(\Omega)$, the closure in $L_{\infty}(\Omega)$ of the space $C_c(\Omega)$ of all continuous functions with compact support.

Let $E^\ast = \{u \in E : u \geq 0\}$ be the positive cone of $E$. An ideal of $E$ is a subspace $J$ of $E$ such that

(a) if $u \in J$, then $|u| \in J$ and
(b) if $u \in J$, $v \in E$ and $0 \leq v \leq u$, then $v \in J$. 

The closure of an ideal is again an ideal. The closed ideals can be characterised in the case of Example 2.1. Let \( \Omega \subset \mathbb{R}^d \) be an open set. If \( p \in [1, \infty) \) and \( E = L_p(\Omega) \), then \( J \subset E \) is a closed ideal if and only if there exists a measurable subset \( B \) of \( \Omega \) such that \( J = \{ u \in E : u|_B = 0 \text{ almost everywhere} \} \) (see [28, Section III.1, Example 1]). If \( \Omega \) is bounded, and \( E = C(\overline{\Omega}) \), then \( J \subset E \) is a closed ideal if and only if there exists a closed set \( B \subset \Omega \) such that \( J = \{ u \in C(\overline{\Omega}) : u|_B = 0 \} \) (see [28, Section III.1, Example 2]). Finally, if \( E = C_0(\Omega) \), then \( J \subset E \) is a closed ideal if and only if there exists a closed set \( B \subset \Omega \) such that \( J = \{ u \in C_0(\Omega) : u|_B = 0 \} \) (see [10, Proposition 10.14]).

Note that if \( u \geq 0 \) in \( L_p(\Omega) \) means that \( u(x) \in [0, \infty) \) for almost every \( x \in \Omega \), whilst \( u \geq 0 \) in \( C(\overline{\Omega}) \) means that \( u(x) \in [0, \infty) \) for all \( x \in \Omega \). We write \( u > 0 \) if \( u \geq 0 \) and \( u \neq 0 \). Note that \( u \neq 0 \) in \( L_p(\Omega) \) means that \( \{ x \in \Omega : u(x) = 0 \} \) is a null set.

If \( u \geq 0 \), then we denote by \( E_u = \{ v \in E : \text{there exists an } n \in \mathbb{N} \text{ such that } |v| \leq nu \} \) the principal ideal generated by \( u \). It is easy to verify that this is indeed an ideal. We write \( u \gg 0 \) if \( E_u = E \).

In the literature of Banach lattices, such an element \( u \) is called a quasi-interior point. As a remark, quasi-interior points can be characterized by an approximation condition. Schaefer [28, Theorem II.6.3] proved that a vector \( u \in E \), is a quasi-interior point if and only if \( \lim_{n \to \infty} v \wedge nu = v \) for every \( v \in E_+ \).

If \( E = L_p(\Omega) \), then \( u \gg 0 \) if and only if \( u(x) > 0 \) for almost every \( x \in \Omega \). If \( \Omega \) is bounded and \( E = C(\overline{\Omega}) \), then \( u \gg 0 \) if and only if there exists a \( \delta > 0 \) such that \( u(x) \geq \delta \) for all \( x \in \overline{\Omega} \), which is the case if and only if \( u \) is an interior point of the positive cone \( E_+ \).

If \( E = C_0(\Omega) \), then \( u \gg 0 \) if and only if \( u(x) > 0 \) for all \( x \in \Omega \). Note that the interior of \( E_+ \) is empty if \( E = C_0(\Omega) \) or \( E = L_p(\Omega) \).

Let also \( F \) be a Banach lattice. A linear map \( R: E \to F \) is called positive if \( RE_+ \subset F_+ \). Positivity implies that \( R \) is continuous by [28, Theorem II.5.3]. We write \( R \geq 0 \) to express that \( R \) is positive. The set of all positive linear functionals on \( E \) is denoted by \( E_+^* \). If \( E = L_p(\Omega) \), then \( E_+^* = L_p(\Omega)_+ \), where \( p' \in (1, \infty) \) is the dual exponent. If \( \Omega \) is bounded and \( E = C(\overline{\Omega}) \), then \( E_+^* \) is isomorphic to all finite (positive) Borel measures on \( \overline{\Omega} \). If \( E = C_0(\Omega) \), then \( E_+^* \) is isomorphic to all (positive) finite Borel measures on \( \Omega \). For a proof of the last two statements, see [19, Theorem 14.1].

An operator \( R: E \to F \) is called positivity improving if \( Ru \gg 0 \) in \( F \) for all \( u \in E \) with \( u > 0 \). Positivity improving operators will be of great interest in this paper.

By a semigroup on \( E \) we mean a map \( S: (0, \infty) \to \mathcal{L}(E) \) such that \( S_{s+t} = S_s S_t \) for all \( s, t \in (0, \infty) \), where we write \( S_t = S(t) \). We say that \( S \) is a \( C_0 \)-semigroup if in addition \( \lim_{t \to 0} S_t u = u \) for all \( u \in E \). A semigroup \( S \) is called positive if \( S_t \geq 0 \) for all \( t > 0 \) and \( S \) is called positivity improving if \( S_t \) is positivity improving for all \( t > 0 \).

A semigroup \( S \) is called irreducible if it does not leave invariant any non-trivial closed ideal; that is, if \( J \subset E \) is a closed ideal and \( S_t J \subset J \) for all \( t > 0 \), then \( J = E \) or \( J = \{0\} \).

Irreducibility is independent of \( p \) for compatible semigroups.

**Lemma 2.2.** Let \( \Omega \subset \mathbb{R}^d \) be open and \( p_1, p_2 \in [1, \infty) \). Let \( S^{(1)} \) and \( S^{(2)} \) be semigroups on \( L_{p_1}(\Omega) \) and \( L_{p_2}(\Omega) \). Suppose that \( S^{(1)} \) and \( S^{(2)} \) are compatible, that is, we have \( S^{(1)}_t u = S^{(2)}_t u \) almost everywhere for all \( t > 0 \) and \( u \in L_{p_1}(\Omega) \cap L_{p_2}(\Omega) \). Then \( S^{(1)}_t \) is irreducible if and only if \( S^{(2)}_t \) is irreducible.

**Proof.** Suppose that \( S^{(1)}_t \) is irreducible. Let \( B \subset \Omega \) be measurable and set \( J_2 = \{ u \in L_{p_2}(\Omega) : u|_B = 0 \} \). Furthermore, suppose that \( S^{(2)}_t J_2 \subset J_2 \) for all \( t > 0 \). Let \( J_1 = \{ u \in L_{p_1}(\Omega) : u|_B = 0 \} \). Let \( t > 0 \) and \( u \in J_1 \). For all \( n \in \mathbb{N} \) let \( V_n = \{ x \in \Omega : |x| \leq n \text{ and } u(x) \leq n \} \). Then \( \overline{\cup V_n} \subset J_2 \cap L_{p_2}(\Omega) \). So \( S^{(1)}_t \overline{\cup V_n} = S^{(2)}_t \overline{\cup V_n} \subset J_2 \). Therefore \( (S^{(1)}_t u |_{\cup V_n})|_B = 0 \) and \( S^{(2)}_t u |_{\cup V_n} \in J_1 \). Then \( S^{(1)}_t u = \lim_{n \to \infty} S^{(1)}_t (u |_{\cup V_n}) \in J_1 \) since \( J_1 \) is closed. So \( S^{(1)}_t J_1 \subset J_1 \). Because \( S^{(1)}_t \) is irreducible, one concludes that \( |B| = 0 \) or \( |\Omega \setminus B| = 0 \) and \( S^{(2)}_t \) is irreducible. \( \square \)

In general, a positive and irreducible \( C_0 \)-semigroup does not need to be positivity improving. An counterexample is the rotation semigroup on \( L_2(\mathbb{T}) \), where \( \mathbb{T} \) is the unit circle in \( \mathbb{C} \). The situation changes, however, if the semigroup is also holomorphic.

**Theorem 2.3.** Let \( S \) be a positive irreducible holomorphic \( C_0 \)-semigroup on \( E \). Then \( S \) is positivity improving.

**Proof.** See Majewski–Robinson [23, Theorem 3]. \( \square \)
In the following proposition we collect a number of known spectral theoretic properties of positive semigroups.

**Proposition 2.4.** Let $S$ be a positive irreducible $C_0$-semigroup in $E$ and suppose that its generator $-A$ has compact resolvent. Then one has the following:

(a) $\sigma(A) \neq \emptyset$.

(b) The number $\lambda_1 := \inf\{\Re\lambda : \lambda \in \sigma(A)\}$ is an eigenvalue of $A$ (and consequently, the infimum is actually a minimum).

(c) There exists a $u \in D(A)$ such that $Au = \lambda_1 u$ and $u \not\equiv 0$.

(d) The algebraic multiplicity of the eigenvalue $\lambda_1$ is one.

**Proof.** (a) We may assume that $\dim E \geq 2$. Then by a result of de Pagter [26, Theorem 3] every compact, positive and irreducible operator on $E$ has non-zero spectral radius. If we apply this to the resolvent of $A$, the assertion follows.

(b) See [10, Corollary 12.9].

(c) It follows from the Krein–Rutman theorem, see for example [10, Theorem 12.15], that there exists a $u \in D(A)$ with $Au = \lambda_1 u$ and $u > 0$. Then the statement follows from [10, Proposition 14.12 (a)].

(d) This follows from [7, Proposition C-III.3.5].

Note that since $A$ has compact resolvent, $\lambda_1$ is an isolated point of the spectrum. Therefore Proposition 2.4 (d) means that the spectral projection for $\lambda_1$ has rank one.

If $S$ is a positive irreducible $C_0$-semigroup whose generator $-A$ has compact resolvent, then we call $\min\{\Re\lambda : \lambda \in \sigma(A)\}$ the principal eigenvalue of $A$. It follows from Proposition 2.4 that the principal eigenvalue has a unique eigenvector $u$ such that $u \geq 0$ and $\|u\| = 1$. We call $u$ the principal eigenvector of $A$. One has $u \not\equiv 0$.

### 3 Irreducibility on $C(\overline{\Omega})$ and $C_0(\Omega)$

In this section we consider a positive irreducible holomorphic $C_0$-semigroup on $L_p(\Omega)$ which maps $L_p(\Omega)$ into $C(\overline{\Omega})$ or $C_0(\Omega)$. Under a mild additional condition we shall prove that the semigroup obtained by restriction to $C(\overline{\Omega})$ or $C_0(\Omega)$ is again irreducible.

In Subsection 3.1 we prove a not too difficult but very powerful abstract result that is the basis of everything that follows. In Subsections 3.2 and 3.3 we consider the special cases $C(\overline{\Omega})$ and $C_0(\Omega)$, respectively. We close the section with a brief remark on the long-term behaviour of positive semigroups in Subsection 3.4.

#### 3.1 An Abstract Positivity Improvement Result

We start with a general theorem about positivity in a single point. It is the main ingredient for our proofs of strict positivity in Section 4. Let $\Omega \subset \mathbb{R}^d$ be an open non-empty set and $X$ a set such that $\Omega \subset X \subset \overline{\Omega}$. If $p \in [1, \infty)$ and $u \in L_p(\Omega)$, then we say that $u \in C(X)$ if there exists a (necessarily unique) $\hat{u} \in C(X)$ such that $\hat{u}|_\Omega = u$ almost everywhere on $\Omega$. Note that $\partial\Omega$ might have positive Lebesgue measure. In the sequel we will identify $u$ and $\hat{u}$. For example, in the next theorem we identify $Su$ and $(S_t u)^-$.  

**Theorem 3.1.** Let $\Omega \subset \mathbb{R}^d$ be an open non-empty set and $p \in [1, \infty)$. Let $S$ be a positive irreducible holomorphic $C_0$-semigroup on $L_p(\Omega)$. Next let $X$ be a set such that $\Omega \subset X \subset \overline{\Omega}$. Finally, let $x \in X$. Suppose

(I) $S_tL_p(\Omega) \subset C(X)$ for all $t > 0$ and

(II) there are $t > 0$ and $w \in L_p(\Omega)$ such that $(S_t w)(x) \neq 0$.

Then $(S_t u)(x) > 0$ for all $t > 0$ and $u \in L_p(\Omega)$ with $u \geq 0$ and $u \not\equiv 0$.

In what follows, typical choices for $X$ are $X = \Omega$ or $X = \overline{\Omega}$. We also have, however, an application in Theorem 4.10 for elliptic operators with mixed boundary conditions, where $X$ is chosen strictly between $\Omega$ and $\overline{\Omega}$.
Let us also remark that, while Theorem 3.1 works pointwise, we are in fact most interested in the case where condition (II), and then also the conclusion of the theorem, is valid for all \( x \in X \) instead of merely a single point.

Proof of Theorem 3.1. The map \( u \mapsto (S_t u)(x) \) from \( L_p(\Omega) \) into \( \mathbb{C} \) is positive, hence by [28, Theorem II.5.3] it is continuous. By assumption (II) there exist \( s > 0 \) and \( w \in L_p(\Omega) \) such that \( (S_s w)(x) \neq 0 \). Without loss of generality we may assume that \( w \geq 0 \). Therefore \( (S_s w)(x) > 0 \).

Let \( t \in (0, \infty) \) and \( u \in L_p(\Omega) \) with \( u > 0 \). There are \( t_1, t_2 \in (0, \infty) \) such that \( t = t_1 + t_2 \) and \( t_1 < s \). According to Theorem 2.3 we have \( S_{t_2} u \geq 0 \) in \( L_p(\Omega) \), so it follows from the Lebesgue dominated convergence theorem that

\[
\lim_{n \to \infty} S_{n(t-t_1)} w \wedge nS_{t_1} u = S_{t-t_1} w
\]

with respect to the norm in \( L_p(\Omega) \). By the continuity that we established in the beginning, it follows that

\[
\lim_{n \to \infty} (S_{t_1}(S_{n(t-t_1)} w \wedge nS_{t_1} u))(x) = (S_s w)(x) > 0.
\]

Consequently, there exists an \( n \in \mathbb{N} \) such that \( (S_{t_1}(S_{n(t-t_1)} w \wedge nS_{t_1} u))(x) > 0 \). But then

\[
0 < (S_{t_1}(S_{n(t-t_1)} w \wedge nS_{t_1} u))(x) \leq (S_{t_1}(nS_{t_1} u))(x) = n(S_{t_1+t_1} u)(x) = n(S_t u)(x)
\]

and the theorem follows. \( \square \)

For the convenience of the reader, as well as for the sake of later reference, we explicitly state a few consequences of Theorem 3.1 in the following subsections.

### 3.2 Irreducibility on \( C(\overline{\Omega}) \)

As a special case of Theorem 3.1 one obtains the following result for \( X = \overline{\Omega} \) if \( \Omega \) is bounded.

**Corollary 3.2.** Let \( \Omega \subset \mathbb{R}^d \) be a bounded open set and \( p \in [1, \infty) \). Let \( S \) be a positive irreducible holomorphic \( C_0 \)-semigroup on \( L_p(\Omega) \). Suppose

(I) \( S_t L_p(\Omega) \subset C(\overline{\Omega}) \) for all \( t > 0 \) and

(II) for all \( x \in \overline{\Omega} \) there are \( t > 0 \) and \( w \in L_p(\Omega) \) such that \( (S_t w)(x) \neq 0 \).

Then the following holds:

(a) For all \( t > 0 \) the operator \( S_t : L_p(\Omega) \to C(\overline{\Omega}) \) is positivity improving. This means \( (S_t u)(x) > 0 \) for all \( x \in \overline{\Omega} \), \( t > 0 \) and \( u \in L_p(\Omega) \) with \( u \geq 0 \) and \( u \neq 0 \).

(b) For all \( t > 0 \) define \( T_t = S_t |C(\overline{\Omega}) : C(\overline{\Omega}) \to C(\overline{\Omega}) \). Then the semigroup \( T \) is irreducible on \( C(\overline{\Omega}) \).

**Proof.** (a) This is a special case of Theorem 3.1.

(b) This follows immediately from the characterisation of closed ideals in \( C(\overline{\Omega}) \) and statement (a). \( \square \)

Note that Condition (II) in Corollary 3.2 is satisfied if Condition (I) is valid and \( T \) is a \( C_0 \)-semigroup on \( C(\overline{\Omega}) \), where \( T \) is as in statement (b). It is also satisfied if there exists a \( t > 0 \) such that \( S_t \equiv \mathbf{1}_{\overline{\Omega}} \).

It is a consequence of Corollary 3.2 that the semigroup has a strictly positive kernel if \( \Omega \) is bounded.

**Corollary 3.3.** Let \( \Omega \subset \mathbb{R}^d \) be a bounded open set and \( S \) a semigroup on \( L_2(\Omega) \). Let \( p \in [2, \infty) \). Suppose that

(I) \( S_t L_2(\Omega) \subset C(\overline{\Omega}) \) and \( S_{t_1} L_2(\Omega) \subset C(\overline{\Omega}) \) for all \( t > 0 \),

(II) for all \( x \in \overline{\Omega} \) there are \( t > 0 \) and \( w \in L_2(\Omega) \) such that \( (S_t w)(x) \neq 0 \), and

(III) for all \( x \in \overline{\Omega} \) there are \( t > 0 \) and \( w \in L_2(\Omega) \) such that \( (S_t^* w)(x) \neq 0 \).

Further suppose that \( (S_t L_2(\Omega))_{t>0} \) is a positive irreducible holomorphic \( C_0 \)-semigroup on \( L_p(\Omega) \). Then for \( t > 0 \) there exists a function \( K_t \in C(\overline{\Omega} \times \overline{\Omega}) \) such that

\[
(S_t u)(x) = \int_{\overline{\Omega}} K_t(x, y) u(y) \, dy
\]

for all \( u \in L_2(\Omega) \) and \( x \in \overline{\Omega} \). Moreover, \( K_t(x, y) > 0 \) for all \( x, y \in \overline{\Omega} \) and \( t > 0 \).
Proof. We would like to apply [8, Theorem 2.1]. To do so, we need a semigroup on an $L_2$-space over $\overline{\Omega}$, which needs a bit of care since the boundary $\partial \Omega$ might have non-zero Lebesgue measure. Let $\lambda$ denote the Lebesgue measure on $\Omega$ and define the Borel measure $\mu$ on $\overline{\Omega}$ given by

$$\mu(B) = \lambda(B \cap \Omega)$$

for each Borel set $B \subset \overline{\Omega}$. Then $\mu$ is strictly positive on each non-empty open subset of $\overline{\Omega}$. Moreover, for each $q \in [1, \infty)$, the embedding $L_q(\Omega) \hookrightarrow L_q(\overline{\Omega}, \mu)$, given by extending functions on $\Omega$ by $0$ on $\partial \Omega$, is an isomorphism. Hence we can transport the semigroup $S$ on $L_2(\Omega)$ to a semigroup $T$ on $L_2(\overline{\Omega})$. Then assumption (I) implies that $T_t L_p(\overline{\Omega}, \mu) \subset C(\overline{\Omega})$ and $T_t^* L_p(\overline{\Omega}, \mu) \subset C(\overline{\Omega})$ for all $t > 0$. It follows from [8, Theorem 2.1] that the operator $T_t$ has a continuous kernel $K_t \in C(\overline{\Omega} \times \overline{\Omega})$ for all $t > 0$. Then

$$(S_tu)(x) = \int_{\Omega} K_t(x, y)u(y) \, dy$$

for all $t > 0$, $u \in L_2(\Omega)$ and $x \in \overline{\Omega}$. If $t > 0$, then $K_t \geq 0$ almost everywhere on $\Omega \times \Omega$ since $S_t$ is a positive operator. Hence by continuity $K_t(x, y) \geq 0$ for all $t > 0$ and $x, y \in \overline{\Omega}$.

Finally, let $t > 0$ and $x, y \in \overline{\Omega}$. By assumption (III) there exist $s > 0$ and $w \in L_p(\Omega)$ such that $(S_t^s w)(y) \neq 0$. There are $t_1, t_2 \in (0, \infty)$ such that $t = t_1 + t_2$ and $t_1 < s$. Define $v: \overline{\Omega} \to \mathbb{R}$ by $v(z) = K_{t_1}(z, y)$. Then $v \neq 0$ since

$$0 \neq (S_t^s w)(y) = (S_{t_1}^s S_{t_2}^s w)(y) = \int_{\Omega} v(z)(S_{t_2}^s w)(z) \, dz.$$ 

Therefore, $K_t(x, y) = (S_t^s v)(x) > 0$ by Corollary 3.2 (a), where we use assumptions (II) and (I).

3.3 Irreducibility on $C_0(\Omega)$

Analogously to Corollary 3.2 one can use Theorem 3.1 to derive irreducibility for semigroups on $C_0(\Omega)$. This yields the following corollary. Note that $\Omega$ does not have to be bounded in this subsection.

Corollary 3.4. Let $\Omega \subset \mathbb{R}^d$ be an open set and $p \in [1, \infty)$. Let $S$ be a positive irreducible holomorphic $C_0$-semigroup on $L_p(\Omega)$. Suppose

(I) $S_t L_p(\Omega) \subset C_0(\Omega)$ for all $t > 0$ and

(II) for all $x \in \Omega$ there are $t > 0$ and $w \in L_p(\Omega)$ such that $(S_t w)(x) \neq 0$.

Then one has the following:

(a) For all $t > 0$ the operator $S_t: L_p(\Omega) \to C_0(\Omega)$ is positivity improving. This means $(S_t u)(x) > 0$ for all $x \in \Omega, t > 0$ and $u \in L_p(\Omega)$ with $u \geq 0$ and $u \neq 0$.

(b) Suppose that for all $t > 0$ the operator $S_{1 | C_0(\Omega) \cap L_p(\Omega)}$ extends to a continuous operator $T_t$ from $C_0(\Omega)$ into $C_0(\Omega)$. Then the semigroup $T$ is irreducible on $C_0(\Omega)$.

Note that if $\Omega$ is bounded, then $C_0(\Omega) \subset L_p(\Omega)$ and the operator $S_{1 | C_0(\Omega)}$ is indeed a continuous operator from $C_0(\Omega)$ into $C_0(\Omega)$. Moreover, condition (II) in Corollary 3.4 is satisfied if $\Omega$ is bounded, condition (I) is valid and $T$ is a $C_0$-semigroup on $C_0(\Omega)$, where $T$ is defined as in (b).

Similarly as in the proof of Corollary 3.3 we obtain a kernel for the semigroup in case $\Omega$ is bounded.

Corollary 3.5. Let $\Omega \subset \mathbb{R}^d$ be a bounded open set and $S$ a semigroup on $L_2(\Omega)$. Let $p \in [2, \infty)$. Suppose that $S_t L_p(\Omega) \subset C_0(\Omega)$ and $S_{t_1}^* L_p(\Omega) \subset C_0(\Omega)$ for all $t > 0$, and

(II) for all $x \in \Omega$ there are $t > 0$ and $w \in L_p(\Omega)$ such that $(S_t w)(x) \neq 0$,

(III) for all $x \in \Omega$ there are $t > 0$ and $w \in L_p(\Omega)$ such that $(S_t^* w)(x) \neq 0$.

Further suppose that $(S_{1 | L_2(\Omega)})_{t>0}$ is a positive irreducible holomorphic $C_0$-semigroup on $L_p(\Omega)$. Then for $t > 0$ there exists a function $K_t \in C_0(\Omega \times \Omega)$ such that

$$(S_t u)(x) = \int_{\Omega} K_t(x, y)u(y) \, dy$$

for all $u \in L_2(\Omega)$ and $x \in \Omega$. Moreover, $K_t(x, y) > 0$ for all $x, y \in \Omega$ and $t > 0$. 

Proof. All is similar as in the proof of Corollary 3.3, but one obtains that \( K_t \in C_0(\Omega \times \Omega) \). It remains to show that \( K_t \in C_0(\Omega \times \Omega) \). Let \( t > 0 \) and \( x \in \partial \Omega \). Since \( S_tL_p(\Omega) \subset C_0(\Omega) \), it follows that
\[
0 = (S_tu)(x) = \int_\Omega K_t(x, z)u(z) \, dz
\]
for all \( u \in C_c(\Omega) \). Hence \( K_t(x, z) = 0 \) for almost all \( z \in \Omega \) and by continuity for all \( z \in \Omega \). By duality \( K_t(z, y) = 0 \) for all \( z \in \Omega \) and \( y \in \partial \Omega \). Because
\[
K_{2t}(x, y) = \int_\Omega K_t(x, z)K_t(z, y) \, dz,
\]
one deduces that \( K_t(x, y) = 0 \) if \( x \in \partial \Omega \) or \( y \in \partial \Omega \). So \( K_{2t} \in C_0(\Omega \times \Omega) \).

3.4 A Note on the Long-Time Behaviour

It is worthwhile to say a few sentences on how the properties that we discussed above are related to the long-time behaviour of the semigroup.

Remark 3.6. In the situation of Corollary 3.2, and for bounded \( \Omega \) in the situation of Corollary 3.4, the semigroup on \( L_p(\Omega) \) consists of compact operators. Let \( -A \) be the generator and let \( \lambda_1 \) be the principal eigenvalue of \( A \). Then by [7, Corollary C-III.3.16] there is a spectral gap in the sense that there exists an \( \varepsilon > 0 \) such that \( \{ \lambda \in \sigma(A) : \text{Re}A \leq \lambda_1 + \varepsilon \} = \{ \lambda_1 \} \). Moreover, if \( \lambda_1 = 0 \), then \( S_t \) converges in \( \mathcal{L}(L_p(\Omega)) \) to a rank-one projection if \( t \to \infty \) (see [7, Proposition C-III.3.5]).

4 Strict Positivity of Principal Eigenvectors and Other Applications

In this section we use the theorems from Section 3 to establish strict positivity of the principal eigenfunction of an elliptic operator for three types of boundary conditions: Dirichlet (Subsection 4.1), Robin (Subsection 4.2) and mixed (Subsection 4.4). For each of these boundary conditions we prove, besides strict positivity of the principal eigenvector, also irreducibility of the corresponding semigroup on a suitable space of continuous functions and a positivity improving property for the corresponding elliptic problem. Moreover, in Subsection 4.3 we shall show that our results have a surprising consequence for elliptic problems with complex Robin boundary conditions.

Throughout this section, let \( \Omega \subset \mathbb{R}^d \) be a bounded non-empty, open and connected set with boundary \( \Gamma = \partial \Omega \). For all \( k, l \in \{1, \ldots, d\} \) let \( a_{kl}, b_k, c_k, c_0 \in L_\infty(\Omega, \mathbb{R}) \). We assume that the coefficients \( a_{kl} \) satisfy a uniform ellipticity condition, namely that there exists a \( \mu > 0 \) such that, for almost all \( x \in \Omega \), the inequality
\[
\text{Re} \sum_{k,l=1}^d a_{kl}(x) \xi_k \xi_l \geq \mu |\xi|^2
\]
holds for all \( \xi \in \mathbb{C}^d \). In the following subsections we will define elliptic operators with the coefficients \( a_{kl}, b_k, c_k, c_0 \) by means of form methods. Loosely speaking, the operator is equal to
\[
u \mapsto - \sum_{k,l=1}^d \partial_l a_{kl} \partial_k u - \sum_{k=1}^d \partial_k b_k u + \sum_{k=1}^d c_k \partial_k u + c_0 u
\]
with boundary conditions. Moreover, depending on the boundary conditions, we will impose different regularity assumptions on the boundary of \( \Omega \) in each subsection.

Most results in this section are a combination of theorems from the literature with Theorem 3.1 and its corollaries. For each type of boundary conditions we state a theorem which describes a positivity improving property of the parabolic equation, and a corollary which yields a similar result for the corresponding elliptic equation.
4.1 Dirichlet Boundary Conditions

In this subsection we assume that $\Omega$ is Wiener regular. This means that for all $\varphi \in C(\Gamma)$ there exists a function $u \in C(\overline{\Omega}) \cap C^2(\Omega)$ such that $\Delta u = 0$ on $\Omega$ and $u|_\Gamma = \varphi$. For instance, $\Omega$ is Wiener regular if it has Lipschitz boundary.

Define the form $a: H^2_0(\Omega) \times H^1_0(\Omega) \to \mathbb{C}$ by

$$a(u, v) = \frac{1}{\Omega} \sum_{k=1}^d a_k(\partial_k u) \overline{\partial_k v} + \frac{1}{\Omega} \sum_{k=1}^d b_k u \partial_k \overline{v} + \frac{1}{\Omega} \sum_{k=1}^d c_k(\partial_k u) \overline{v} + \frac{1}{\Omega} \sum_{k=1}^d c_k(\partial_k u) \overline{v}.$$

Then $a$ is a closed sectorial form. Let $A$ be the $m$-sectorial operator on $L_2(\Omega)$ associated with $a$ and let $S$ be the semigroup generated by $-A$ on $L_2(\Omega)$. Then $S$ is a positive semigroup by [25, Theorem 2.6 or Corollary 4.3] and irreducibility of $S$ follows from [25, Theorem 4.5]. Since the embedding $H^2_0(\Omega) \subset L_2(\Omega)$ is compact, the operator $A$ has compact resolvent. If $t > 0$, then $S(t) \subset C_0(\Omega)$ by [9, (8)], where we used that $\Omega$ is Wiener regular. For all $t > 0$ let $T_t = \mathcal{S}(t) \subset C_0(\Omega)$, then $T_t$ is holomorphic $C_0$-semigroup by [9, Theorem 1.3]. Clearly $T_t$ is positive. The following result shows that $T_t$ is also irreducible.

**Theorem 4.1.** The operator $A$ on $L_2(\Omega)$ and the semigroup $T$ on $C_0(\Omega)$ have the following properties:

(a) For all $t > 0$ the operator $T_t$ is positivity improving. In particular, the semigroup $T$ is irreducible.

(b) Let $u$ be the principal eigenfunction of $A$. Then $u \in C_0(\Omega)$ and $u(x) > 0$ for all $x \in \Omega$.

**Proof.** Statement (a) follows from Corollary 3.4 and statement (b) from Proposition 2.4 (c).

**Remark 4.2.** Theorem 4.1 can also be derived from known, but much less elementary results from PDE. Statement (b) follows from the Harnack inequality (see for instance [18, Theorem 8.20]). Next, let $t > 0$ and let $K_t$ be the kernel of the operator $S_t$. The De Giorgi–Nash theorem implies that $K_t$ is continuous. Then the Harnack inequality shows that $K_t$ is strictly positive on $\Omega \times \Omega$. Therefore $T_t$ is positivity improving and $T$ is irreducible.

**Remark 4.3.** For the special case of the Laplacian, the strict parabolic maximum principle of Evans [17, Section 2.3.3] was used in [4, Theorem 3.3] to prove Theorem 4.1. The proof in Evans, however, is based on a mean value property which is not valid for operators with variable coefficients.

We conclude this subsection with a positivity improving property for the corresponding elliptic problem. Since the semigroup $S$ has Gaussian kernel bounds it follows that the semigroup extends to a $C_0$-semigroup on $L^p(\Omega)$ for all $p \in [1, \infty)$. We denote its generator by $-A_p$. As $A$ has compact resolvent, it follows that $A_p$ has compact resolvent too and that the spectrum of $A_p$ coincides with the spectrum of $A$ by [27]. We obtain from Theorem 4.1 the following corollary about regularity of the corresponding elliptic problem.

**Corollary 4.4.** Let $\lambda \in \mathbb{R}$ be smaller than the first eigenvalue of $A$; let $p \in (\frac{d}{2}, \infty)$. If $u \in D(A_p)$ and $(-\lambda I + A_p)u > 0$, then $u \in C_0(\Omega)$ and $u(x) > 0$ for all $x \in \Omega$.

**Proof.** Denote the generator of $T$ by $-A_\lambda$ and choose $\mu \in \mathbb{R}$ such that $\mu < \lambda$ and $\mu < \inf\{\text{Re} v : v \in \sigma(A_\lambda)\}$. The semigroup $T$ is irreducible according to Theorem 4.1 (a). Hence it follows from [7, Definition C-III.3.1] that the resolvent $(-\mu I + A_\lambda)^{-1}$ is positivity improving on $C_0(\Omega)$. Note that the operator $(-\mu I + A_\lambda)^{-1}$ coincides with the restriction of $(-\mu I + A_p)^{-1}$ to $C_0(\Omega)$.

One deduces from [9, Corollary 2.10] that the range of the resolvents $(-\lambda + A_p)^{-1}$ and $(-\mu + A_p)^{-1}$ are contained in $C_0(\Omega)$, where we use that $p > \frac{d}{2}$. Set $f = (-\lambda I + A_p)u$. Then the resolvent identity implies that

$$u = (-\lambda I + A_p)^{-1}f = (\lambda - \mu)(-\lambda I + A_p)^{-1}(-\lambda I + A_p)^{-1}f + (-\mu I + A_p)^{-1}f \geq (\lambda - \mu)(-\mu I + A_p)^{-1}(-\lambda I + A_p)^{-1}f \gg 0,$$

where $\gg$ is to be understood in $C_0(\Omega)$. This proves the corollary.

Note that $\sigma(A_\lambda) = \sigma(A_2)$ by [5, Proposition 3.10.3].
4.2 Robin Boundary Conditions

In this subsection we assume in addition that $\Omega$ has Lipschitz boundary. Further let $\beta \in L_{\infty}(\Gamma, \mathbb{R})$. Define the form $a: H^1(\Omega) \times H^1(\Omega) \to \mathbb{C}$ by

$$a(u, v) = \sum_{k=1}^{d} a_k(\partial_k u)\overline{\partial_k v} + \int_{\Gamma} b_k(\partial_k u)\overline{v} + \int_{\Gamma} c_k(\partial_k u)\overline{v} + \int_{\Gamma} \beta(\text{Tr} u)\overline{\text{Tr} v}.$$ 

Then $a$ is a closed sectorial form. Let $A$ be the $m$-sectorial operator on $L_2(\Omega)$ associated with $a$ and let $S$ be the semigroup generated by $-A$ on $L_2(\Omega)$. Then $S$ is a positive semigroup by [25, Theorem 2.6]. Moreover, $S$ is irreducible on $L_2(\Omega)$ by [25, Corollary 2.11] together with the discussion in [25, p. 106]. Since $\Omega$ is bounded and Lipschitz, the operator $A$ has compact resolvent. If $t > 0$, then $S_t L_2(\Omega) \subset C(\overline{\Omega})$ by [8, Remark 6.2]. Let $T_t = S_t|_{C(\overline{\Omega})}: C(\overline{\Omega}) \to C(\overline{\Omega})$ for all $t > 0$. Then $T$ is a $C_0$-semigroup by [8, Remark 6.2].

**Theorem 4.5.** The operator $A$ on $L_2(\Omega)$ and the semigroup $T$ on $C(\overline{\Omega})$ have the following properties:

(a) For all $t > 0$ the operator $T_t$ is positivity improving. In particular, the semigroup $T$ is irreducible.

(b) Let $u$ be the principal eigenvalue of $A$. Then $u \in C(\overline{\Omega})$ and $u(x) > 0$ for all $x \in \overline{\Omega}$.

**Proof.** Statement (a) follows from Corollary 3.2 and statement (b) from Proposition 2.4 (c).

Note that it follows again from the Harnack inequality that $u(x) > 0$ for all $x \in \Omega$. The above theorem, however, says much more, namely that $u$ is also strictly positive on the boundary of $\Omega$ and hence, bounded away from 0. This is of interest in the study of non-linear equations, and is new under such general conditions as we have here. Under much stronger regularity conditions, for instance if $\Omega$ has a $C^1$-boundary and all coefficients are smooth, one can of course deduce Theorem 4.5 from Hopf's minimum principle, see for example [22, Theorem 1.2].

Again, we also derive a corresponding elliptic result. By the Gaussian kernel bounds of [13, Theorem 2.2] and [12] the semigroup $S$ on $L_2(\Omega)$ extrapolates to a $C_0$-semigroup on $L_p(\Omega)$ for all $p \in [1, \infty)$, whose generator we denote by $-A_p$. If $p > \frac{d}{2}$, the resolvent operators of $A_p$ map $L_p(\Omega)$ into $C(\overline{\Omega})$ by [24, Theorem 3.14 (iv)]. Hence by exactly the same arguments as in the proof of Corollary 4.4 we can obtain the following consequence of Theorem 4.5.

**Corollary 4.6.** Let $\lambda \in \mathbb{R}$ be smaller than the first eigenvalue of $A$, let $p \in (\frac{d}{2}, \infty)$ and $u \in D(A_p)$. Suppose that $(-\lambda I + A_p)u > 0$. Then $u \in C(\overline{\Omega})$ and $u(x) > 0$ for all $x \in \overline{\Omega}$.

4.3 The Bottom of the Spectrum for Complex Robin Boundary Conditions

In this subsection we consider complex Robin boundary conditions and show that Theorem 4.5 has surprising consequences for this situation. Note that in Theorem 4.5 the function $\beta$ is real valued.

As in Subsection 4.2 we assume that $\Omega$ has Lipschitz boundary $\Gamma$. For the coefficients of the differential operator we assume that $a_{kl} = a_{lk}$ and $b_k = c_k$ for all $k, l \in \{1, \ldots, d\}$. For all $\beta \in L_\infty(\Gamma)$ define the form $a_\beta : H^1(\Omega) \times H^1(\Omega) \to \mathbb{C}$ by

$$a_\beta(u, v) = \sum_{k,l=1}^{d} a_{kl}(\partial_k u)\overline{\partial_l v} + \int_{\Gamma} b_k(\partial_k u)\overline{v} + \int_{\Gamma} c_k(\partial_k u)\overline{v} + \int_{\Gamma} \beta(\text{Tr} u)\overline{\text{Tr} v}.$$ 

Then $a_\beta$ is a closed sectorial form. Let $A_\beta$ be the $m$-sectorial operator associated with $a$. Since $\Omega$ is bounded and Lipschitz, the operator $A_\beta$ has compact resolvent. Note that $a_\beta$ is symmetric if $\beta$ is real valued.

**Proposition 4.7.** Let $\beta \in L_\infty(\Gamma)$ with $\text{Im} \beta \neq 0$. Then $\min \{\text{Re} \lambda : \lambda \in \sigma(A_\beta)\} > \min \sigma(A_{\text{Re} \beta})$.

**Proof.** Let $\lambda \in \sigma(A_\beta)$. There exists a $u \in D(A_\beta)$ such that $A_\beta u = \lambda u$ and $\|u\|_{L_2(\Omega)} = 1$. Then

$$\text{Re} \lambda = \text{Re} (A_\beta u, u)_{L_2(\Omega)} = \text{Re} a_\beta(u) = a_{\text{Re} \beta}(u) \geq \min \sigma(A_{\text{Re} \beta}),$$
where we used that $a_{Re} \beta$ is symmetric. If $Re \lambda = \min \sigma (A_{Re} \beta)$, then $a_{Re} \beta (u) = \min \sigma (A_{Re} \beta)$. So $u \in D (A_{Re} \beta)$ and $A_{Re} \beta u = \lambda_{1} u$, where $\lambda_{1} = \min \sigma (A_{Re} \beta)$ and we used Proposition 2.4 (d). Using Theorem 4.5, one deduces that $u \in C (\bar{\Omega})$ and $u (x) \neq 0$ for all $x \in \Gamma$ (even for all $x \in \bar{\Omega}$). Let $\partial_{\nu} u$ denote the (weak) co-normal derivative of $u$. Then $\partial_{\nu} u + \beta u |_{\Gamma} = 0$ in $L_{2} (\Gamma)$ since $u \in D (A_{\beta})$. But also $\partial_{\nu} u + (Re \beta) u |_{\Gamma} = 0$ in $L_{2} (\Gamma)$ since $u \in D (A_{Re} \beta)$. So $(Im \beta) u |_{\Gamma} = 0$ in $L_{2} (\Gamma)$ and hence $Im \beta = 0$ almost everywhere. This is a contradiction. 

\[ \square \]

### 4.4 Mixed Boundary Conditions

In this subsection we assume that $\Omega$ has Lipschitz boundary. Further, let $D \subset \partial \Omega$ be a closed set and define $N = \partial \Omega \setminus D$. We consider elliptic differential operators with mixed boundary conditions where, roughly speaking, we wish to have Dirichlet boundary conditions on $D$ and Neumann boundary conditions on $N$. This yields an example where we apply Theorem 3.1 with a set $\partial D = \partial D \setminus \partial \Omega \setminus D$.

In contrast to the previous sections, we restrict ourselves to differential operators with second order coefficients only, i.e. we assume that $b_{k} = c_{k} = c_{0} = 0$ for all $k \in \{1, \ldots, d\}$.

Since the pure Dirichlet and pure Neumann case have been considered in the previous subsections, we assume that $D \neq \emptyset$ and $N \neq \emptyset$. Let $\partial D$ be the boundary of $D$ in the relative topology of $\partial \Omega$. We need a technical assumption which states that the set of points from the Dirichlet boundary part is large enough with respect to the boundary measure (see [15]). Precisely, we suppose that there exists a $\delta > 0$ such that for all $x \in \partial D$ and $r \in (0, 1)$ there exists a $y \in D \cap B (x, r)$ such that

\[ N \cap B (y, \delta r) = \emptyset. \quad (4.1) \]

Next we introduce the generator. Let

\[ C_{D}^{\infty} (\Omega) = \{ \chi |_{\Omega} : \chi \in C_{D}^{\infty} (\mathbb{R}^{d}) \text{ and } D \cap \text{supp} \chi = \emptyset \} \]

and let $W^{1,2} (\Omega)$ be the closure of $C_{D}^{\infty} (\Omega)$ in $W^{1,2} (\Omega)$. Define the form $\alpha : W^{1,2} (\Omega) \times W^{1,2} (\Omega) \rightarrow \mathbb{C}$ by

\[ \alpha (u, v) = \int_{\Omega} \sum_{k,l=1}^{d} a_{kl} (\partial_{k} u) \overline{\partial_{l} v}. \]

Then $\alpha$ is a closed sectorial form.

Let $A$ be the operator associated with $\alpha$ on $L^{2} (\Omega)$ and let $S$ be the semigroup generated by $-A$ on $L^{2} (\Omega)$. Finally, let $C_{D} (\bar{\Omega}) = \{ u \in C (\bar{\Omega}) : u |_{\partial \Omega} = 0 \}$. We shall first show that $S$ leaves the space $C_{D} (\bar{\Omega})$ invariant and that the restriction to $C_{D} (\bar{\Omega})$ is a $C_{0}$-semigroup. Note that in Subsections 4.1 and 4.2 we could quote the literature to have a $C_{0}$-semigroup on $C_{0} (\Omega)$ and $C (\bar{\Omega})$.

**Theorem 4.8.** Adopt the above notation and assumptions.

(a) The semigroup $S$ is positive and irreducible.

(b) If $t > 0$, then $S_{t} (L^{2} (\Omega)) \subset C_{D} (\bar{\Omega})$. In particular, the semigroup $S$ leaves $C_{D} (\bar{\Omega})$ invariant. For all $t > 0$ define $T_{t} = S_{t} |_{C_{D} (\bar{\Omega})} : C_{D} (\bar{\Omega}) \rightarrow C_{D} (\bar{\Omega})$.

(c) The semigroup $T$ is a $C_{0}$-semigroup on $C_{D} (\bar{\Omega})$.

**Proof.** (a) This follows from [25, Corollary 4.3 and Theorem 4.5].

(b) We first show that $C (\bar{\Omega}) \cap W^{1,2} (\Omega) \subset C_{D} (\bar{\Omega})$. Let $v \in C (\bar{\Omega}) \cap W^{1,2} (\Omega)$. Since $(Tr w) |_{D} = 0$ $3(d-1)$-almost everywhere for all $w \in C_{D}^{\infty} (\Omega)$, it follows by density that $(Tr w) |_{D} = 0$ $3(d-1)$-almost everywhere for all functions $w \in W^{1,2} (\Omega)$. In particular, $(Tr v) |_{D} = 0$ $3(d-1)$-almost everywhere. Let $z \in D$. Suppose that $v (z) \neq 0$. Since $v$ is continuous, there exists an $s \in (0, 1)$ such that $v (x) \neq 0$ for all $x \in \bar{\Omega} \cap B (z, s)$. If $z$ is in the interior of $D$ in the relative topology of $\partial \Omega$, then this contradicts $(Tr v) |_{D} = 0$ $3(d-1)$-almost everywhere. Alternatively, if $z \in \partial D$, then (4.1) gives a contradiction. So $v (z) = 0$. Therefore $v \in C_{D} (\bar{\Omega})$ and the inclusion $C (\bar{\Omega}) \cap W^{1,2} (\Omega) \subset C_{D} (\bar{\Omega})$ follows.

It is a consequence of [15, Theorem 1.1] that $S$ maps into the (globally) H"{o}lder continuous functions on $\bar{\Omega}$.

Let $t > 0$ and $u \in L^{2} (\Omega)$. Then $S_{t} u \subset C (\bar{\Omega}) \cap W^{1,2} (\Omega) \subset C_{D} (\bar{\Omega})$ and statement (b) follows.
(c) The proof is inspired by [24, proof of Lemma 4.2]. Let $A_{C_0}$ be the part of $A$ in $C_D(\Omega)$. So
\[ D(A_{C_0}) = \{ u \in C_D(\Omega) \cap D(A) : Au \in C_D(\Omega) \} \]
and $A_{C_0}u = Au$ for all $u \in D(A_{C_0})$.

First we shall show that $D(A_{C_0})$ is dense in $C_D(\Omega)$. We shall do this in two steps. If $u \in C_D(\Omega)^+ \cap \Delta \epsilon > 0$, then $D \cap \text{supp}((u - \epsilon)^+) = 0$. Regularising $(u - \epsilon)^+$ it follows that $C_D(\Omega)^+$ is contained in the $C_D(\Omega)$-closure of $\{ \chi \in C^\infty_c(\mathbb{R}^d) : D \cap \text{supp} \chi = 0 \}$. Hence by linearity $\{ \chi \in C^\infty_c(\mathbb{R}^d) : D \cap \text{supp} \chi = 0 \}$ is dense in $C_D(\Omega)$.

By Proposition 4.9 (b) below there exists a $c > 0$ such that $u \in C(\Omega)$ and $\|u\|_{C(\Omega)} \leq c \sum_{k=1}^d \|f_k\|_{L^1(\Omega)}$ for all $u \in W^{1,2}_D(\Omega)$ and $f_1, \ldots, f_d \in L^p(\Omega)$ such that
\[ a(u, v) = \sum_{k=1}^d (f_k, \partial_k v)_{L^2(\Omega)} \]
for all $v \in W^{1,2}_D(\Omega)$. Now let $\chi \in C^\infty_c(\mathbb{R}^d)$ and suppose that $D \cap \text{supp} \chi = 0$. Let $\Delta \epsilon > 0$. Since $C^\infty_c(\Omega)$ is dense in $L^1(\Omega)$, for all $k \in \{1, \ldots, d\}$ there exists a $\omega_k \in C^\infty_c(\Omega)$ such that
\[ \left\| \omega_k - \sum_{l=1}^d a_{lk} \partial l \chi \right\|_{L^1(\Omega)} < \epsilon. \]
Define $f = -\sum_{k=1}^d \partial_k w_k \in C^\infty_c(\Omega)$. There exists a unique $u \in W^{1,2}_D(\Omega)$ such that $a(u, v) = (f, v)_{L^2(\Omega)}$ for all $v \in W^{1,2}_D(\Omega)$. Then $u \in C(\Omega)$ by Proposition 4.9 (a) below. So $u \in C(\Omega) \cap W^{1,2}_D(\Omega) \subset C_D(\Omega)$ by the first step in the proof of statement (b). Clearly $u \in D(A)$ and $Au = f$. Obviously, $f \in C_D(\Omega)$. Hence $u \in D(A_{C_0})$. Moreover, if $v \in W^{1,2}_D(\Omega)$, then
\begin{align*}
\|u - \chi\|_{C(\Omega)} &\leq c \sum_{k=1}^d \left\| \omega_k - \sum_{l=1}^d a_{lk} \partial l \chi \right\|_{L^1(\Omega)} \leq c \epsilon.
\end{align*}
We showed that $\chi \in C(\Omega)$ and
\[ \|u - \chi\|_{C(\Omega)} \leq c \sum_{k=1}^d \left\| \omega_k - \sum_{l=1}^d a_{lk} \partial l \chi \right\|_{L^1(\Omega)} \leq c \epsilon. \]
Now we are able to complete the proof of statement (c). By [15, Theorem 7.5] the semigroup $S$ has Gaussian kernel bounds. Hence there exists an $M > 0$ such that $\|S_t\|_{\infty - \infty} \leq M$ for all $t \in (0, 1]$. Then $\|T_t\|_{\infty - \infty} \leq M$ for all $t \in (0, 1]$. If $u \in D(A_{C_0})$, then
\[ \|S_t A_{C_0} u\|_{\infty} \leq M t \|A_{C_0} u\|_{\infty} \]
for all $t \in (0, 1]$. Hence we have $\lim_{t \to 0} T_t u = u$ in $C_D(\Omega)$. Since $D(A_{C_0})$ is dense in $C_D(\Omega)$ the semigroup $T$ is a $C_0$-semigroup. 

In the proof Theorem 4.8 we needed the following regularity results of [15].

**Proposition 4.9.** Let $p \in (d, \infty)$.

(a) If $u \in W^{1,2}_D(\Omega)$ and $f \in L^p(\Omega)$ with $a(u, v) = (f, v)_{L^2(\Omega)}$ for all $v \in W^{1,2}_D(\Omega)$, then $u \in C(\Omega)$.

(b) There exists a constant $c > 0$ such that $\|u\|_{C^m(\Omega)} \leq c \sum_{k=1}^d \|f_k\|_{L^p(\Omega)}$ for all $u \in W^{1,2}_D(\Omega)$ and $f_1, \ldots, f_d \in L^p(\Omega)$ such that $a(u, v) = \sum_{k=1}^d (f_k, \partial_k v)_{L^2(\Omega)}$ for all $v \in W^{1,2}_D(\Omega)$. 


Proof. This follows as in [15, proof of Theorem 6.8]. Since θ ≠ D ≠ ∂Ω, the form a is coercive. Hence the identity operator in [15, Theorem 6.8] is not needed.

Similar to the case of Dirichlet and Robin boundary conditions, we obtain irreducibility of the semigroup on the space $C_D(\overline{Ω})$.

**Theorem 4.10.** The operator $A$ on $L^2(Ω)$ and the semigroup $T$ on $C_D(\overline{Ω})$ have the following properties:

(a) For all $t > 0$ the operator $T_t$ is positivity improving. In particular, the semigroup $T$ is irreducible.

(b) Let $u$ be the principal eigenvector of $A$. Then $u(x) > 0$ for all $x ∈ Ω ∪ N$.

**Proof.** (a) Choose $p = 2$. Let $X = Ω ∪ N$. Then $Ω ⊂ X ⊂ \overline{Ω}$. It follows from Theorem 4.8 (b) that condition (I) in Theorem 3.1 is valid and condition (II) follows from Theorem 4.8 (c) for every $x ∈ X$. Hence Theorem 3.1 implies that $(S_t u)(x) > 0$ for all $x ∈ X$, $t > 0$ and $u ∈ L^2(Ω)$ with $u ≥ 0$ and $u ≠ 0$. So $T$ is positivity improving and consequently irreducible.

(b) This follows immediately from the proof of statement (a).

**Remark 4.11.** Note that $C_D(\overline{Ω}) = C_0(Ω ∪ N)$, the closure of $C_c(Ω ∪ N)$ in $C(\overline{Ω})$. It follows that $u ∈ C_0(Ω ∪ N)$ is a quasi-interior point if and only if $u(x) > 0$ for all $x ∈ Ω ∪ N$.

By [15, Theorem 7.5] the semigroup $S$ has Gaussian kernel bounds. Hence the semigroup extends consistently to $L^p(Ω)$ for all $p ∈ [1, \infty)$. We denote the generator by $−A_p$. If $p ∈ (\frac{d}{2}, \infty)$, then a Laplace transform gives that the resolvent of $A_p$ maps $L^p(Ω)$ into $C_D(\overline{Ω})$. By the same arguments as in the proof of Corollary 4.4 we obtain the following consequence of Theorem 4.10.

**Corollary 4.12.** Let $λ ∈ \mathbb{R}$ be smaller than the first eigenvalue of $A$ and let $p ∈ (\frac{d}{2}, \infty)$. If $u ∈ D(A_p)$ and $(−λI + A_p)u > 0$, then $u ∈ C_D(\overline{Ω})$ and $u(x) > 0$ for all $x ∈ Ω ∪ N$.

5 The Strong Maximum Principle for Parabolic Equations

In this section we show how our results, in particular Corollary 3.4 and Theorem 4.1, can be employed to prove strong minimum and maximum principles for parabolic and elliptic differential operators. Throughout this section let $Ω ⊂ \mathbb{R}^d$ be a bounded non-empty open set with boundary $Γ$. For all $k, l ∈ \{1, \ldots, d\}$ let $a_{kl}, b_k, c_k, c_0 ∈ L_{co}(Ω, \mathbb{R})$. We assume that there exists a $μ > 0$ such that

$$\text{Re} \sum_{k,l=1}^{d} a_{kl}(x) ξ_k ξ_l ≥ μ|ξ|^2$$

for all $ξ ∈ \mathbb{C}^d$ and almost every $x ∈ Ω$. Define $A : H^1_{loc}(Ω) → D'(Ω)$ by

$$\langle Au, v \rangle_{D'((Ω) × D(Ω))} = \sum_{k,l=1}^{d} \int_{Ω} a_{kl}(\partial_k u)(\partial_l v) + \sum_{k=1}^{d} \int_{Ω} b_k u \overline{\partial_k v} + \sum_{k=1}^{d} \int_{Ω} c_k(\partial_k u)v + \int_{Ω} c_0 u \overline{v}$$

for all $u ∈ H^1_{loc}(Ω)$ and $v ∈ C^∞_{c}(Ω)$. Define the operator $A_{c,\max}$ in $C(\overline{Ω})$ by

$$D(A_{c,\max}) = \{ u ∈ H^1_{loc}(Ω) ∩ C(\overline{Ω}) : Au ∈ C(\overline{Ω}) \}$$

and $A_{c,\max} = A|_{D(A_{c,\max})}$. In this section we shall prove a maximum principle for parabolic equations involving the operator $A_{c,\max}$.

The maximum and minimum principles in this section are not completely novel. For operators in non-divergence form they are classical. For operators in divergence form as we consider them here, there are results in [20, Theorem 6.25], with a slightly different notion of solution and domain of the operator. Still, we find it worthwhile to include this section since it shows that our approach from the previous sections yields a new short and elementary proof for strong parabolic and elliptic maximum principles under very general assumptions on the coefficients of the operator.
5.1 The Strong Maximum Principle for Mild Solutions

In this subsection, we assume in addition that \( \Omega \) is connected and Wiener regular (see the beginning of Subsection 4.1 for a definition). Moreover, we assume that the coefficients satisfy

\[
\int_{\Omega} c_0 v + \sum_{k=1}^{d} b_k \partial_k v \geq 0
\]

for all \( v \in C_0^\infty(\Omega)^+ \). Fix \( T \in (0, \infty) \). Let \( \varphi \in C([0, T), C(\Gamma)) \) and \( u_0 \in C(\overline{\Omega}) \). Formally we consider the problem

\[
\begin{align*}
    u(t) &= -A_{c,\text{max}} u(t) \quad \text{for all } t \in [0, T], \\
    u(t)|_{\Gamma} &= \varphi(t) \quad \text{for all } t \in [0, T], \\
    u(0) &= u_0.
\end{align*}
\]

(5.1)

As in [3] we say that \( u \in C([0, T], C(\overline{\Omega})) \) is a mild solution of (5.1) if

\[
\int_0^t u(s) \, ds \in D(A_{c,\text{max}}), \quad u(t) = u_0 - A_{c,\text{max}} \int_0^t u(s) \, ds \quad \text{and} \quad u(t)|_{\Gamma} = \varphi(t)
\]

for all \( t \in [0, T] \). Arendt [3, Theorem 6.5] proved the following theorem.

**Theorem 5.1.** Let \( \varphi \in C([0, T], C(\Gamma)) \) and \( u_0 \in C(\overline{\Omega}) \) with \( u_0|_{\Gamma} = \varphi(0) \). Then there exists a unique function \( u \in C([0, T], C(\overline{\Omega})) \) such that \( u \) is a mild solution of (5.1). Moreover, if \( \varphi \geq 0 \) and \( u_0 \geq 0 \), then \( u \geq 0 \).

The last part can be improved with the aid of Corollary 3.4. This is the main result of this subsection.

**Theorem 5.2.** Let \( \varphi \in C([0, T], C(\Gamma)) \) and \( u_0 \in C(\overline{\Omega}) \) with \( u_0|_{\Gamma} = \varphi(0) \), \( \varphi \geq 0 \) and \( u_0 \geq 0 \). Let \( u \in C([0, T], C(\overline{\Omega})) \) be the mild solution of (5.1).

(a) If \( u_0 \neq 0 \), then \( u(t, x) > 0 \) for all \( t \in (0, T) \) and \( x \in \Omega \).

(b) If \( t_0 \in (0, T) \) and \( \varphi(t_0) \neq 0 \), then \( u(t, x) > 0 \) for all \( t \in (t_0, T) \) and \( x \in \Omega \).

**Proof.** (a) There exists an \( x_0 \in \Omega \) such that \( u_0(x_0) \neq 0 \). Let \( \chi \in C_0^\infty(\Omega) \) be such that \( 0 \leq \chi \leq 1 \) and \( \chi(x_0) = 1 \). Consider \( v_0 = \chi u_0 \in C_0(\Omega) \). By Theorem 5.1 there exists a unique \( v \in C([0, T], C(\overline{\Omega})) \) such that

\[
\int_0^t v(s) \, ds \in D(A_{c,\text{max}}), \quad v(t) = v_0 - A_{c,\text{max}} \int_0^t v(s) \, ds \quad \text{and} \quad v(t)|_{\Gamma} = 0
\]

(5.2)

for all \( t \in [0, T] \). The function \( v \) can be described via a semigroup. Let \( A_c \) be the part of \( A_{c,\text{max}} \) in \( C_0(\Omega) \). So

\[
D(A_c) = \{ u \in H_0^1(\Omega) \cap C_0(\Omega) : A u \in C_0(\Omega) \}
\]

and \( A_c = A|_{D(A_c)} \). Then \( -A_c \) generates a \( C_0 \)-semigroup on \( C_0(\Omega) \) by [9, Theorem 1.3] (see also Subsection 4.1 or [6, Section 4]). Let \( T \) be the semigroup generated by \( -A_c \). Then \( T \) is positive and irreducible by Theorem 4.1. Define \( w : [0, T] \to C(\overline{\Omega}) \) by \( w(t) = T_tv_0 \). Then it is easy to see that \( w \in C([0, T], C(\overline{\Omega})) \) and that \( w \) satisfies (5.2) with \( v \) replaced by \( w \). So \( v(t) = w(t) = T_tv_0 \) for all \( t \in (0, T) \) by the uniqueness property. The semigroup \( T \) also extends to a positive irreducible holomorphic \( C_0 \)-semigroup on \( L_1(\Omega) \) and this semigroup maps \( L_1(\Omega) \) into \( C_0(\Omega) \). Hence we can apply Corollary 3.4 (a) and conclude that \( v(t, x) > 0 \) for all \( t \in (0, T) \) and \( x \in \Omega \).

Finally, consider \( u - v \in C([0, T], C(\overline{\Omega})) \). Then

\[
\int_0^t (u-v)(s) \, ds \in D(A_{c,\text{max}}), \quad (u-v)(t) = (u_0-v_0) - A_{c,\text{max}} \int_0^t (u-v)(s) \, ds \quad \text{and} \quad (u-v)(t)|_{\Gamma} = \varphi(t)
\]

for all \( t \in [0, T] \). So \( u - v \geq 0 \) by the last part of Theorem 5.1. In particular, \( u(t, x) \geq v(t, x) > 0 \) for all \( t \in (0, T) \) and \( x \in \Omega \).

(b) Apply statement (a) to \( \tilde{u}_0 = u(t_0, \cdot) \), \( \tilde{u}(t, x) = u(t-t_0, x) \) and \( \tilde{\varphi}(t) = \varphi(t-t_0) \), where \( t \in [0, T-t_0] \) and \( x \in \overline{\Omega} \). \( \square \)
In the following corollary we show how a strong parabolic maximum principle can be derived from Theorem 5.2.

**Corollary 5.3.** Assume that $A1_Ω = 0$. Let $φ ∈ C([0, T], C(Γ))$ and $u_0 ∈ C(Ω)$. Let $u ∈ C([0, T], C(Ω))$ be the mild solution of (5.1). Moreover, let $t_0 ∈ (0, T]$ and $x_0 ∈ Ω$. If $u(t_0, x_0) ≥ u(t, x)$ for all $t ∈ [0, t_0]$ and $x ∈ Ω$, then $u$ is constant on $[0, t_0] × Ω$.

**Proof.** Define $v ∈ C([0, t_0], C(Ω))$ by $v(t, x) = u(t_0, x_0) - u(t, x)$. Define $v_0 ∈ C(Ω)$ by $v_0(x) = u(t_0, x_0) - u_0(x)$ and define $ψ ∈ C([0, t_0], C(Γ))$ by $ψ(t, x) = u(t_0, x_0) - φ(t, x)$. Then $v_{0|Γ} = ψ(0)$ and $v_0 ≥ 0$. Then $ψ ≥ 0$ and $v_0 ≥ 0$. Also

$$\int_0^t v(s) \, ds \in D(A_{c,max}) \quad ∀t ∈ [0, t_0] \quad v(t) = v_0 - A_{c,max} \int_0^t v(s) \, ds \quad ∀t ∈ [0, t_0],$$

for all $t ∈ [0, t_0]$. Since $v(t_0, x_0) = 0$, it follows from Theorem 5.2 that $v_0 = 0$ and $ψ = 0$. Then the uniqueness part of Theorem 5.1 implies that $v = 0$. Hence $u$ is constant on $[0, t_0] × Ω$.

In the next two corollaries we deduce a strong elliptic maximum principle from the parabolic result in Corollary 5.3.

**Corollary 5.4.** Let $u ∈ H^1_{loc}(Ω) ∩ C(Ω)$ and suppose that $Au = 0$. If $u ≥ 0$ and $u|Γ ≠ 0$, then $u(x) > 0$ for all $x ∈ Ω$.

**Proof.** Define $v_0 = u$, $φ(t) = u|Γ$ and $v(t) = u$ for all $t ∈ [0, T]$. Then $v$ is a mild solution of (5.1) with $u_0$ replaced by $v_0$. Now apply Theorem 5.2 (a).

**Corollary 5.5.** Suppose that $A1_Ω = 0$. Let $u ∈ H^1_{loc}(Ω) ∩ C(Ω)$ and suppose that $Au = 0$. If there exists an $x_0 ∈ Ω$ such that $u(x_0) = max_Ω u$, then $u$ is constant.

**Proof.** Consider $v = u(x_0)1_Ω - u$. Then $v ≥ 0$ and $Av = 0$. Since $v(x_0) = 0$, it follows from Corollary 5.4 that $v = 0$. Hence $u = u(x_0)1_Ω$ and $u$ is constant.

### 5.2 Mild and Very Weak Solutions

Theorem 5.2 and the parabolic maximum principle in Corollary 5.3 used the concept of a mild solution of (5.1). In this subsection we show under a differentiability condition that mild solutions are the same as very weak solutions.

Throughout this subsection we assume that the coefficients $a_{kl}, c_k$ satisfy $a_{kl}, c_k ∈ L^∞(Ω, R) ∩ C^1(Ω)$ for all $k, l ∈ \{1, \ldots, d\}$.

Fix a time $T ∈ (0, \infty)$. For all $u ∈ C([0, T] × Ω)$ define $u ∈ C([0, T], C(Ω))$ by $(u(t)) (x) = u(t, x)$. If $ψ ∈ C^2_{c}(Ω)$, define $A^*ψ ∈ C_{c}(Ω)$ by

$$A^*ψ = -\sum_{k,l=1}^d \partial_k(a_{kl}∂lψ) + \sum_{k=1}^d b_k∂kψ - \sum_{k=1}^d \partial_k(c_kψ) + c_0ψ.$$

If $φ ∈ C^0_c((0, T) × Ω)$ define $A^*φ ∈ C([0, T] × Ω)$ by

$$(A^*φ)(t, x) = (A^*(φ(t)))(x).$$

Moreover, we define $φ_1 ∈ C^0_c((0, T) × Ω)$ by

$$φ_1(t, x) = \left(\frac{∂}{∂t}φ\right)(t, x).$$

The second condition in the next theorem states that $u$ is a very weak solution.

**Theorem 5.6.** Let $u ∈ C([0, T] × Ω)$. Then the following are equivalent:

(i) $\int_0^T \int_Ω \tilde{u}(s) \, ds \in D(A_{c,max})$ and $\tilde{u}(t) = u(0) - A_{c,max} \int_0^t \tilde{u}(s) \, ds$ for all $t ∈ [0, T]$.

(ii) If $φ ∈ C^0_c((0, T) × Ω)$, then $\int_0^T \int_Ω u(t, x)(φ_1 - A^*φ)(t, x) \, dx \, dt = 0$. 

Proof. (i) ⇒ (ii) Let $\varphi \in C^\infty_c((0, T) \times \Omega)$. Define $\psi \in C([0, T] \times \overline{\Omega})$ by $\psi(t, x) = \int_0^t u(s, x) \, ds$. Then $\bar{\psi}(t) = \int_0^t \bar{u}(s) \, ds$ for all $t \in [0, T]$. Therefore

$$\int_0^T \int_\Omega u(t, x)(A^* \varphi)(t, x) \, dx \, dt = \int_0^T \int_\Omega \left( \frac{\partial}{\partial t} \psi(t, x) \right)(A^* \varphi)(t, x) \, dt \, dx$$

$$= -\int_0^T \int_\Omega \psi(t, x)(A^* \varphi)(t, x) \, dt \, dx$$

$$= -\int_0^T \left( \bar{\psi}(t), A^* \varphi(t) \right)_{L^2(\Omega)} \, dt$$

$$= \int_0^T \left( \bar{u}(t) - \bar{\psi}(0), \varphi(t) \right)_{L^2(\Omega)} \, dt$$

$$= \int_0^T \int_\Omega u(t, x) \varphi(t, x) \, dx \, dt - \int_\Omega u(0, x) \int_0^T \varphi(t, x) \, dt \, dx.$$

Since $\int_0^T \varphi(t, x) \, dt = \varphi(T, x) - \varphi(0, x) = 0$ for all $x \in \Omega$, the implication follows.

(ii) ⇒ (i) Let $\psi \in C^\infty_c(\Omega)$, and define $f, g \in C([0, T] \times \Omega)$ by $f(t) = (\bar{u}(t), \psi)_{L^2(\Omega)}$ and $g(t) = (\bar{u}(t), A^* \psi)_{L^2(\Omega)}$. Let $\tau \in C^\infty_c((0, T) \times \Omega)$. Then $\tau \circ \psi \in C^\infty_c((0, T) \times \Omega)$. So by assumption

$$\int_0^T \int_\Omega u(t, x)((\tau \circ \psi)t - A^* (\tau \circ \psi))(t, x) \, dx \, dt = 0.$$  

Hence

$$\int_0^T \tau'(t)f(t) \, dt = \int_0^T \int_\Omega u(t, x) \tau'(t)\psi(x) \, dx \, dt$$

$$= \int_0^T \int_\Omega u(t, x) \tau(t)(A^* \psi)(x) \, dx \, dt$$

$$= \int_0^T \tau(t)g(t) \, dt$$

and $f' = -g$ weakly. Since $f$ and $g$ are continuous the lemma of du Bois–Reymond implies that $f$ is differentiable and $f' = -g$ in the classical sense. Let $t \in [0, T]$. Then

$$(\bar{u}(t), \psi)_{L^2(\Omega)} = f(t) = f(0) - \int_0^t g(s) \, ds = (\bar{u}(0), \psi)_{L^2(\Omega)} - \int_0^t (\bar{u}(s), A^* \psi)_{L^2(\Omega)} \, ds.$$  

So

$$\left( \int_0^t \bar{u}(s) \, ds, A^* \psi \right)_{L^2(\Omega)} = (\bar{u}(0) - \bar{u}(t), \psi)_{L^2(\Omega)}.$$  

This is for all $\psi \in C^\infty_c(\Omega)$. It follows from elliptic regularity, see Proposition A.1 in the appendix, that $\int_0^t \bar{u}(s) \, ds \in H^1_{loc}(\Omega)$. Hence (i) is valid.

Now we can reformulate the results of the previous subsection using the notion of very weak solutions. We consider the parabolic cylinder $\Omega_T = (0, T) \times \Omega$ with parabolic boundary $\partial^+ \Omega_T = (0) \times \overline{\Omega} \cup ((0, T) \times \partial \Omega)$.  

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W. Arendt et al., Strict Positivity for the Principal Eigenfunction of Elliptic Operators
Given $\psi \in C(\partial^* \Omega_T)$, we formally consider the Dirichlet problem for the heat equation

$$
\begin{aligned}
&u \in C(\overline{\Omega_T}), \\
&\partial_t u - \Delta u = 0 \quad \text{on } \Omega_T, \\
&u|_{\partial^* \Omega_T} = \psi.
\end{aligned}
$$

We say that $u \in C(\overline{\Omega_T})$ is a very weak solution of $D(\psi)$ if

$$
\int_0^T \int_\Omega u(t, x)(\varphi_t - \Delta^* \varphi)(t, x) \, dx \, dt = 0
$$

for all $\varphi \in C^\infty_c((0, T) \times \Omega)$ and $u|_{\partial^* \Omega_T} = \psi$. Then the following holds.

**Theorem 5.7.** Assume $\Omega$ is connected and Wiener regular. Then for all $\psi \in C(\partial^* \Omega_T)$ there exists a unique very weak solution of $D(\psi)$.

For this solution of $D(\psi)$ the following maximum principles are valid.

**Theorem 5.8.** Assume $\Omega$ is connected and Wiener regular. Let $\psi \in C(\partial^* \Omega)$ and let $u \in C(\overline{\Omega_T})$ be the very weak solution $D(\psi)$. Then one has the following:

(a) If $\psi \geq 0$, then $u \geq 0$.

(b) Let $t_0 \in (0, T)$ and $x_0 \in \overline{\Omega}$. Suppose that $u(t_0, x_0) > 0$ and $\psi \geq 0$. Then $u(t, x) > 0$ for all $t \in (t_0, T]$ and $x \in \Omega$.

(c) Suppose $\forall t \in (0, T]$ and $x_0 \in \Omega$. If $u(t, x) \leq u(t_0, x_0)$ for all $t \in [0, t_0]$ and $x \in \overline{\Omega}$, then $u$ is constant on $[0, t_0] \times \overline{\Omega}$.

The maximum principle for elliptic operators has been proved before in [18, Theorem 8.19].

## A Regularity

In the proof of Theorem 5.6 we used the following regularity result for very weak solutions.

**Proposition A.1.** Let $\Omega \subset \mathbb{R}^d$ be open. For all $k, l \in \{1, \ldots, d\}$ let $a_{kl}, c_k \in W^{1,\infty}(\Omega)$ and $b_k, c_0 \in L_{\text{loc}}(\Omega)$. Assume that there exists a $\mu > 0$ such that

$$
\text{Re} \sum_{k,l=1}^d a_{kl}(x)\xi_k \xi_l \geq \mu |\xi|^2
$$

(A.1)

for all $\xi \in C^d$ and almost every $x \in \Omega$. For all $\varphi \in C^\infty_c(\Omega)$ define $A^* \varphi \in L_{\text{loc},c}(\Omega)$ by

$$
A^* \varphi = -\sum_{k,l=1}^d \partial_k (a_{kl} \partial_l \varphi) + \sum_{k=1}^d b_k \partial_k \varphi - \sum_{k=1}^d \partial_k (c_k \varphi) + c_0 \varphi.
$$

Let $u, f, f_1, \ldots, f_d \in L_2(\Omega)$ and suppose that

$$(u, A^* \varphi)_{L^2(\Omega)} = (f, \varphi)_{L^2(\Omega)} - \sum_{j=1}^d (f_j, \partial_j \varphi)_{L^2(\Omega)}$$

for all $\varphi \in C^\infty_c(\Omega)$. Then $u \in W^{1,2}_{\text{loc}}(\Omega)$.

**Proof.** Fix $\chi \in C^\infty_c(\Omega)$. We shall show that $\chi u \in W^{1,2}(\Omega)$. Without loss of generality we may assume that $a_{kl}, c_k \in W^{1,\infty}(\mathbb{R}^d)$ and $b_k, c_0 \in L_{\text{loc}}(\mathbb{R}^d)$, and that (A.1) is valid for all $\xi \in C^d$ and almost every $x \in \mathbb{R}^d$.

Define the form $a : W^{1,2}(\mathbb{R}^d) \times W^{1,2}(\mathbb{R}^d) \to \mathbb{C}$ by

$$
a(v, w) = \int_{\mathbb{R}^d} \sum_{k,l=1}^d a_{kl}(\partial_k v) \overline{\partial_l w} + \int_{\mathbb{R}^d} \sum_{k=1}^d b_k v \partial_k w + \int_{\mathbb{R}^d} \sum_{k=1}^d c_k (\partial_k v) \overline{w} + \int_{\mathbb{R}^d} c_0 v \overline{w}.
$$

Then $a$ is a closed sectorial form. Let $A$ be the $m$-sectorial operator associated with $a$. Note that we have $C^\infty_c(\mathbb{R}^d) \subset D(A^*)$ and that $A^* \varphi = A^* \varphi$ for all $\varphi \in C^\infty_c(\Omega)$. 


Define
\[ g = \chi f - \sum_{j=1}^{d} (\partial_j \chi) f_j + \sum_{k,l=1}^{d} u \partial_k (a_{kl} \partial_l \chi) - \sum_{k=1}^{d} b_k u \partial_k \chi + \sum_{k=1}^{d} c_k u \partial_k \chi \]
and for all \( j \in \{1, \ldots, d\} \) define
\[ g_j = \chi f_j - \sum_{l=1}^{d} a_{lj} u \partial_l \chi - \sum_{k=1}^{d} a_{kj} u \partial_k \chi. \]
Then \( g, g_2 \in L_{2,c}(\Omega) \subset L_2(\mathbb{R}^d) \). It is a tedious elementary exercise to show that
\[ (\chi u, A^* \varphi)_{L_2(\mathbb{R}^d)} = (g, \varphi)_{L_2(\mathbb{R}^d)} - \sum_{j=1}^{d} (g_j, \partial_j \varphi)_{L_2(\mathbb{R}^d)} \quad (A.2) \]
for all \( \varphi \in C_0^\infty(\mathbb{R}^d) \). It follows from [1, Theorem 9.8] that \( C_0^\infty(\mathbb{R}^d) \) is a core for \( A^* \). Obviously, \( D(A^*) \subset W^{1,2}(\mathbb{R}^d) \). Hence (A.2) is valid for all \( \varphi \in D(A^*) \).

Without loss of generality we may assume that that \( \text{Re } c_0 \) is large enough such that \( A^* \) is invertible. Then
\[ (\chi u, w)_{L_2(\mathbb{R}^d)} = (g, (A^*)^{-1} w)_{L_2(\mathbb{R}^d)} - \sum_{j=1}^{d} (g_j, (A^*)^{-1} \partial_j w)_{L_2(\mathbb{R}^d)} \]
for all \( w \in L_2(\mathbb{R}^d) \). Let \( m \in \{1, \ldots, d\} \). Then
\[ (\chi u, \partial_m v)_{L_2(\mathbb{R}^d)} = (g, (A^*)^{-1} \partial_m v)_{L_2(\mathbb{R}^d)} - \sum_{j=1}^{d} (g_j, (A^*)^{-1} \partial_m \partial_j v)_{L_2(\mathbb{R}^d)} \]
for all \( v \in W^{1,2}(\mathbb{R}^d) \). It follows from the ellipticity condition that the operator \( \partial_j (A^*)^{-1} \partial_m \) from \( W^{1,2}(\mathbb{R}^d) \) into \( L_2(\mathbb{R}^d) \) has a bounded extension from \( L_2(\mathbb{R}^d) \) into \( L_2(\mathbb{R}^d) \) for all \( j \in \{1, \ldots, d\} \). Since \( D(A) \subset W^{1,2}(\mathbb{R}^d) \), it follows by duality that there is an \( M > 0 \) such that \( \| (\chi u, (A^*)^{-1} \partial_m v)_{L_2(\mathbb{R}^d)} \| \leq M \| v \|_{L_2(\mathbb{R}^d)} \) for all \( v \in W^{1,2}(\mathbb{R}^d) \). Hence \( \chi u \in W^{1,2}(\mathbb{R}^d) \), as required.

We emphasise that all the coefficients of the operator in Proposition A.1 may be complex valued, including the second-order coefficients.

**Remark A.2.** Suppose in addition to the conditions of the coefficients in Proposition A.1 that \( b_k \in W^{1,\infty}(\mathbb{R}^d) \) for all \( k \in \{1, \ldots, d\} \). Let \( p \in (1, \infty) \), \( u, f_1, \ldots, f_d \in L_p(\Omega) \) and suppose
\[ \int_{\Omega} u A^* \varphi = \int_{\Omega} f \varphi - \sum_{j=1}^{d} \int_{\Omega} f_j \partial_j \varphi \]
for all \( \varphi \in C_0^\infty(\Omega) \). Then \( u \in W^{1,p}_{\text{loc}}(\Omega) \). The proof is almost the same. The operator \( A \) is consistent with an operator \( A_p \) in \( L_p(\mathbb{R}^d) \) such that the semigroups generated by \( -A \) and \( -A_p \) are consistent. Let \( q \in (1, \infty) \) be the dual exponent of \( p \). The inclusions \( D(A^*) \subset W^{1,q}(\mathbb{R}^d) \) and \( D(A_p) \subset W^{1,p}(\mathbb{R}^d) \) are in [16, Corollary 3.8]. The bounded extension of \( \partial_j (A^*)^{-1} \partial_m \) follows from [16, Theorem 1A].

If in addition \( f_1 = \cdots = f_d = 0 \), then one can deduce as in the proof of Proposition A.1 that \( \chi u \in D(A^{**}_{p}) \).

For real coefficients a slightly more generally version of Remark A.2 has been proved by Zhang and Bao in [29, Theorem 1.5], where \( f \) is even allowed to be an element of a larger \( L_q \)-space if \( d \geq 3 \) and a Lorentz space if \( d = 2 \). We refer to [29] for an account on known regularity results for very weak solutions of elliptic operators.

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