Programmable Input for Nanomagnetic Logic Devices

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Abstract. A programmable magnetic input, based on the magnetic interaction of a soft and hard magnetic layer is presented for the first time. Therefore, a single-domain Co/Pt nanomagnet is placed on top of one end of a permalloy bar, separated by a thin dielectric layer. The permalloy bar of the introduced input structure is magnetized by weak easy-axis in-plane fields. Acting like a ‘magnetic amplifier’, the generated fringing fields of the permalloy pole are strong enough to control the magnetization of the superimposed Co/Pt nanomagnets, which have high crystalline perpendicular magnetic anisotropy. This magnetostatic interaction results in a shift of the hysteresis curve of the Co/Pt nanomagnet, measured by magneto-optical Kerr microscopy. The Co/Pt nanomagnet is fixed by the fringing field of the permalloy and thereby not affected by the magnetic power clock of the Nanomagnetic Logic system. MFM measurements verify the functionality of the programmable magnetic input structure. The fringing fields are extracted from micromagnetic simulations and are in good agreement with experimental results. The introduced input structure enables switching the logic functionality of the majority gate from NAND to NOR during runtime, offering programmable Nanomagnetic Logic.

1 Introduction

Nanomagnetic Logic (NML) is envisioned to complement state-of-the-art CMOS technology by providing non-volatile computing states for low power applications [1]. Basic elements of these systems are ferromagnetic, single-domain nanomagnets with either in-plane [2] or perpendicular magnetization [3] [4]. In this work, Co/Pt multilayer magnets with perpendicular crystalline anisotropy are favored, due to their higher thermal stability and larger design space in shape and switching field modification by focused ion beam (FIB) irradiation [5].

Fig. 1 demonstrates the assembly of a nanomagnetic computing system. The bistable magnets interact with their next neighbors by magnetic field-coupling. The information is transmitted between the logic elements by magnetic inverter chains [6], in which well-defined local FIB irradiation is used to generate artificial nucleation centers. These weakest links govern the reversal process of the magnets and thereby ensure the directed signal flow. Logic functionality is implemented in the system by majority gates, as illustrated in Fig 1. The computing dot C perceives the fringing fields of its three left input neighbors D₁, D₂ and P. The superposition of these magnetic fields forces the magnetization of the computing dot in antiparallel direction of the majority of its input magnets[7]. Due to the strong crystalline anisotropy, an additional magnetic clocking field is necessary to overcome the switching threshold of the magnets and to enable the fringing fields to govern the magnetization direction of their following magnets.

The complex logic functionality of the majority gate can be constricted to NAND or NOR by implementing one input with fixed magnetization. This enables the exploitation of standard CMOS design tools for NML. The coercivity of this programmable magnet must be sufficiently high, that its magnetization state is not affected by the magnetic power clock. By integrating a feature, that enables controlled switching of the programmable dot during runtime without influencing any other logic component, NML can be expanded to reconfigurable logic.

Investigations on the interaction between magnetic layers offer new opportunities for NML devices [8]. In this work, this magnetic interaction is used to experimentally demonstrate a programmable hard-magnetic nanodot suitable for on-chip programmable magnetic inputs in NML systems.

2 Theory

As all magnets of the envisioned NML system are patterned from the same magnetic thin film, they have about

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the same switching fields, neglecting fabrication variations and thermal fluctuations [9] [10]. The fabrication of a magnet with higher coercivity can be realized by using a lower ion dose when the artificial nucleation center is created by FIB irradiation [11]. This harder magnet must be programmed at the beginning of operation of the system and its magnetization state can not be changed during runtime. In this paper, we present an advanced method to create a hard magnetic dot that allows to be programmed during runtime.

Fig. 2a) shows a schematic of the investigated input structure. A permalloy bar is located below the layer with Co/Pt magnets. The perpendicular component of the fringing fields of the permalloy pole \( B_{\text{fringing}} \) act on the Co/Pt magnet, especially in the artificial nucleation center and thereby support or prevent its switching. The direction of the fringing field is conditioned by the magnetization direction of the permalloy bar. It can be programmed by a magnetic field pulse in in-plane direction, which is the hard-magnetic axis of the Co/Pt and is therefore not influencing the magnetization states of the Co/Pt logic. Due to a reduced switching threshold of Co/Pt magnets by applying in-plane magnetic fields, it is beneficial to synchronize the magnetic power clock and the programming in-plane pulse by applying it at almost zero out-of-plane magnetic field.

The switching field of the permalloy bar is lower than the coercivity of the Co/Pt magnets due to pure shape anisotropy. This enables low power programming of the magnet and reconfiguration of the magnetization state of the programmable Co/Pt dot during runtime. The permalloy bar behaves like a ‘magnetic amplifier’, which is controlled by weak magnetic field pulses and provides strong fringing fields for the Co/Pt magnet.

The effect of the fringing field of the permalloy pole on the Co/Pt magnet is visualized in Fig. 2b). NML systems are clocked by a sinusoidal magnetic power clock with a maximum flux density \( B_{\text{max}} \) equal to the coercivity of the magnets. This power clock is necessary to overcome the switching threshold of the Co/Pt magnets. At maximum flux density, the Co/Pt magnets are in metastable state and the coupling fields from neighboring dots govern their magnetization state, enabling logic computation and information transport. The fringing field of the permalloy pole acts continuously on the input Co/Pt magnet. This magnetic bias is shifting the hysteresis curve of the Co/Pt input magnet by \( \Delta \mu_0 H_c \). It results in an asymmetric hysteresis curve with one-side increased coercivity \( \mu_0 H_{c1,\text{bias}} \), which will not be overcome by the magnetic power clock. Thereby, the magnetization state of the Co/Pt input magnet is fixed as long as the magnetization state of the permalloy bar is in a steady state.

The fringing fields of a permalloy bar bias a Co/Pt magnet in the layer above and thereby govern its magnetization state during magnetic clocking. The biased Co/Pt magnet fulfills all demands for a programmable input in NML devices. The following modification extends the range of applications. By fabricating the permalloy bars with their magnetic easy-axis in different directions, the magnets can be programmed separately. Areas on a chip can be united by identical orientation of the permalloy bars. The functionality of those logic blocks can be switched by applying an aligned in-plane field pulse, without influencing other blocks with tilted easy-axis direction.

## 3 Simulation

Micromagnetic simulations with OOMMF are performed on the proposed programmable input. The fringing fields of a 20 nm thick permalloy bar are simulated to estimate the interaction with the Co/Pt. The size of the permalloy bar is 140 nm by 2.1 \( \mu \)m to ensure single domain state. Note, both poles of the permalloy bar may be used for the Co/Pt logic. In the simulation, the permalloy bar is magnetized in easy-axis direction and subsequently relaxed before the designated data is extracted.

Fig. 3a) shows the perpendicular magnetic flux density in a plane 68 nm above the permalloy bar, where the Co/Pt magnets are located in the experiment. The contour of the permalloy is marked by the dashed line. Micromagnetic simulations showed, that rounded edges are focusing the fringing field in the center of the end of the bar. Fig 3b) shows the simulated perpendicular flux density, generated by the permalloy pole at the center line \( y = 0 \) nm at different planes above the pole. Increasing the distance from 23 nm to 68 nm reduces the maximum flux density clearly from 91 mT to 29 mT. By increasing the width of the permalloy bar, the width of the pole increases simultaneously with almost constant maximum flux density. Simulations on a 250 nm long bar verified, that reducing the length does not affect the amplitude of the fringing field as long as the shape anisotropy guarantees the poles on the
left and right end of the bar. Enlarging the thickness of the permalloy bar increases the fringing fields almost linearly.

Micromagnetic simulations including the permalloy bar and a Co/Pt magnet visualized negligible reverse interaction from the Co/Pt back to the permalloy if both magnetic layers are separated by a dielectric layer. These forces are considerably weak and thereby not affecting the magnetization state of the permalloy bar. In contrast, the micromagnetic simulation showed a fringing field of the permalloy bar, that is strong enough to control the magnetization of the superimposed Co/Pt nanomagnet.

4 Experiment

4.1 Sample fabrication

Co/Pt nanomagnets are placed on top of one end of a permalloy bar, separated by a thin dielectric layer. The 20 nm thick permalloy is evaporated on a silicon substrate, using a 2 nm Ti adhesion layer and it is structured in a lift-off process. 75 nm of hydrogen silsesquioxanes (HSQ) are spin coated as dielectric interlayer to adjust the distance of the permalloy pole to the Co/Pt nanomagnet in the way of planarizing the permalloy bar and to provide a smooth surface for the overlying Co/Pt layer. The Ti$_{14}$nm/Pt$_{3.5}$nm/[Co$_{0.6}$nm+Pt$_{1.0}$nm]/Pt$_{0.5}$nm multilayer stack is magnetron sputtered at room temperature. A 4 nm Ti layer is evaporated and structured in a lift-off process, serving as hard mask in the dry-etching process. The Co/Pt nanomagnets are patterned by Ar-ion beam etching stopping in the HSQ layer. The artificial nucleation center in the Co/Pt nanomagnet is generated by local FIB irradiation at a dose of 1·10$^{14}$ ions/cm$^2$, using a Micron 9500 system with a gallium source and an acceleration voltage of 50 kV. The size of the artificial nucleation center is 50 nm by 50 nm.

Fig 4a) shows an SEM image of the fabricated structure. The 1 µm by 1 µm Co/Pt nanomagnets are clearly visible. The 140 nm by 2.1 µm permalloy bar with rounded edges, framed by the dashed line, provides a weak contrast to the surrounding, because it is buried under the HSQ layer. Fig 4b) visualizes a schematic cross-section of the fabricated programmable input structure. Atomic force microscopy illustrates that the HSQ planarizes the sharp 20 nm thick edge of the permalloy bar to a 7 nm smooth passage for the Co/Pt film. The distance of the center of the Co/Pt magnet and the top of the permalloy bar is calculated to be 68 nm, as used in the micromagnetic simulation. Due to the concentrated fringing fields of the permalloy bar in a small area (see Fig 3) the adjustment of the artificial nucleation center on top of the permalloy pole is the vital step in the fabrication process.

4.2 Magnetic force microscopy

Magnetic force microscopy (MFM) is performed to visualize the magnetization orientation of the permalloy and the Co/Pt. First, the permalloy bar is magnetized by a 300 mT in-plane field to definitely align the magnetization in easy-axis. Afterwards a decreasing oscillating out-of-plane magnetic field with max amplitude of 120 mT is used to drive the Co/Pt nanomagnets to ground state.

Fig 5a) shows the MFM topography image of the programmable input structure. The Co/Pt nanomagnets are clearly visible as bright, square areas. Due to the not complete planarization of the HSQ, the buried permalloy bar is also visible in the topography. Fig 3b) shows the MFM phase image. The fringing fields of the permalloy poles are visible as bright and dark spot at the ends of the permalloy bar. Their size is in good agreement with the simulation (in Fig 5a). The Co/Pt magnets appear bright and dark in the image, representing their perpendicular magnetization state. During driving the Co/Pt into ground state, the fringing field of the permalloy acts as bias field and thereby governs the magnetization direction of the Co/Pt magnet in ground state. In the MFM measurement, the direction of the fringing fields of the permalloy corresponds to the magnetization direction of the Co/Pt magnets, verifying the functionality of the fabricated programmable input device.

4.3 Hysteresis curve measurements

Hysteresis curve measurements are used to quantify the interaction between the two magnetic layers. A magneto optical Kerr microscope (MOKE) is employed for fast and contactless hysteresis measurements. In the experiment, the permalloy bar is magnetized by an in-plane magnetic field pulse. Subsequently, the hysteresis curves of the Co/Pt nanomagnets on top of both poles of the permalloy bar are measured by applying an out-of-plane field with maximum amplitude of 150 mT. Afterwards, the magnetization of the permalloy is reversed and the hysteresis measurements of the Co/Pt magnets are repeated.

In Fig 6 the distribution of the coercivity of 30 hysteresis curves of one Co/Pt magnet is plotted for both magnetization states of the permalloy. Regarding the black distributions, the fringing fields of the permalloy pole are oriented out of the plane. This bias field supports the switching of the Co/Pt magnet at positive external magnetic fields.
Coercivity measurements by MOKE show a shift \( \Delta H_c \) in the hysteresis curve of the Co/Pt nanomagnet, depending on the bias field generated by the permalloy pole. Simulations also confirm stronger interaction at reduced distance between the magnetic layers and at a thicker permalloy layer. Magnetic force microscopy measurements verified the functionality of the proposed programmable input device. The magnetization of the Co/Pt magnets in ground state appeared correctly oriented by the fringing fields of the permalloy poles in the MFM image. Hysteresis curve measurements quantify the magnetic bias field of the permalloy pole at the Co/Pt magnet. Its coercivity is shifted by \( \Delta H_c = \pm 10.6 \text{ mT} \), depending on the orientation of the fringing fields. The measured value corresponds to the micromagnetic simulation, if an inaccuracy in the alignment of the artificial nucleation center of the Co/Pt magnet is considered. This emphasizes the necessity of the accurate alignment of the artificial nucleation center for maximum interaction. The introduced magnetic input structure is used to switch the logic functionality of majority gates during runtime and envisions programmable Nanomagnetic Logic.

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