EXPONENTIAL DECAY OF COVARIANCES FOR THE SUPERCRITICAL MEMBRANE MODEL

ERWIN BOLTHAUSEN, ALESSANDRA CIPRIANI, AND NOEMI KURT

Abstract. We consider the membrane model, that is the centered Gaussian field on \(\mathbb{Z}^d\) whose covariance matrix is given by the inverse of the discrete Bilaplacian. We impose a \(\delta\)-pinning condition, giving a reward of strength \(\epsilon\) for the field to be 0 at any site of the lattice. In this paper we prove that in dimensions \(d \geq 5\) covariances of the pinned field decay at least exponentially, as opposed to the field without pinning, where the decay is polynomial. The proof is based on estimates for certain discrete weighted norms, a percolation argument and on a Bernoulli domination result.

1. Introduction

Effective interface models are well-studied real-valued random fields, defined for instance on the lattice \(\mathbb{Z}^d\), which predict the behavior of polymers and interfaces between two states of matter. The best known examples are the gradient models \(\varphi = \{\varphi_x\}_{x \in \mathbb{Z}^d}\) which (in formal notation) are of the form

\[
P(\mathrm{d}\varphi) := \frac{1}{\mathcal{Z}} \exp\left[-H(\varphi)\right] \prod_x \mathrm{d}\varphi_x,
\]

with the Hamiltonian

\[
H(\varphi) := \sum_{x, y \in \mathbb{Z}^d, \|x-y\|=1} V(\varphi_x - \varphi_y)
\]

where \(V : \mathbb{R} \to \mathbb{R}\) is the interaction function, satisfying \(V(x) \to \infty\) for \(\|x\| \to +\infty\). The measure has to be defined through a thermodynamic limit. In the case \(V(x) := \beta x^2\), the model is Gaussian, but it is defined on the whole of \(\mathbb{Z}^d\) only for \(d \geq 3\). For lower dimensions, one has to restrict \(x\) to a finite set, and put boundary conditions. This is the so-called Gaussian free field which has attracted tremendous attention recently for \(d = 2\). One simplifying feature of the free field is that the covariances of the model are given in terms of the Green’s function of a standard random walk on the lattice, and many properties of the field can be derived from properties of the random walk. This has led to powerful techniques for analysing the model. The case where \(V\) is not quadratic is much more complicated. If \(V\) is convex, there is still a random walk representation of the correlation, the Helffer-Sjöstrand representation, but in the case of non-convex \(V\), random walk techniques cannot be applied, and many of the very basic questions are still open. For a recent investigation, see Adams (2006), Adams et al. (2016).

The so-called massive free field has the Hamiltonian

\[
H(\varphi) := \beta \sum_{x, y, \|x-y\|=1} (\varphi_x - \varphi_y)^2 + m \sum_x \varphi_x^2, \quad \beta, m > 0,
\]

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and it is a Gaussian field which is well-defined on the full lattice in any dimension, and has exponentially decaying covariances. This just comes from the fact that the covariances are given by the Green’s function of a random walk with a positive killing rate (Friedli and Velenik, 2015, Theorem 8.46).

It is quite astonishing that an exponential decay of correlations, in physics jargon a positive mass, also appears when the free field Hamiltonian is perturbed by an arbitrary small attraction to the origin, for instance in the form

$$H(\phi) := \beta \sum_{x, y, \|x-y\|=1} (\phi_x - \phi_y)^2 + a \sum_x 1_{[-b,b]}(\phi_x)$$

with \(a, b > 0\) (see Velenik (2006, Section 5)). A somewhat simpler case is that of so-called \(\delta\)-pinning where the reference measure \(\prod_x d\phi_x\) is replaced by \(\prod_x (d\phi_x + \varepsilon \delta_0(d\phi_x))\), and which can be obtained from (1.1) by a suitable limiting procedure letting \(b \to 0, \ a \to +\infty\). All the proofs we are aware of rely heavily on random walk representations.

Our main object here is to discuss similar properties for the \(\delta\)-pinned membrane model which has the Hamiltonian

$$H(\phi) := \frac{1}{2} \sum_{x \in \mathbb{Z}^d} (\Delta \phi_x)^2$$

where \(\Delta\) is the discrete Laplace operator on functions \(f : \mathbb{Z}^d \to \mathbb{R}\), defined by

$$\Delta f(x) := \frac{1}{2d} \sum_{y : \|y-x\|=1} (f(y) - f(x)).$$

We leave out the temperature parameter \(\beta\) as it just leads to a trivial rescaling of the field.

While the free field (described for example in Friedli and Velenik (2015, Chapter 8)) is used to model polymers or interfaces with a tendency to maintain a constant mean height, the membrane model appears in physical and biological research to shape interfaces that tend to have constant curvature (Hiergeist and Lipowsky, 1997, Leibler, 1989, Lipowsky, 1995, Ruiz-Lorenzo et al., 2005). In solid state physics one often considers models with mixed gradient and Laplacian Hamiltonian, but we will not discuss such cases here. The two models share many common characteristics, for instance their variances are uniformly bounded in \(\mathbb{Z}^d\) if the dimension is large enough, that is \(d \geq 3\) for the gradient case resp. \(d \geq 5\) for the membrane model, and have variances growing logarithmically in \(d = 2\) resp. \(d = 4\).

The main topic of the present paper is an investigation of the decay of correlations for the membrane model in dimensions \(d \geq 5\). We restrict to the case of \(\delta\)-pinning for technical reasons. We prove that the field becomes “massive”, i.e. has exponentially decaying correlation for any positive pinning parameter.

The main difficulty when compared with the proofs of similar results for the free field is the absence of useful random walk representations for the covariances and correlation inequalities. Random walk representations for gradient fields have been very important since the celebrated work Brydges et al. (1982). There is a variant of a random walk representation in the case of the membrane model (Kurt, 2009, Section 2), but only in the presence of particular boundary conditions, or in the case of the field on the whole lattice in the absence of boundary conditions. Results on the membrane model with pinning were shown in \((1 + 1)\) dimensions by Caravenna and Deuschel (2008) using a renewal type of argument which, however, is not applicable in higher dimensions. We would like to mention also
the work Adams et al. (2016) on large deviation principles under a Laplacian interaction without using renewal type arguments.

Structure of the paper. The structure of the paper is as follows: in Section 2 we give precise definitions on the membrane model and the statement of our main theorem. We recall general results, including Bernoulli domination, in Section 3. In Section 4 we prove our main theorem.

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2. The model and main results

2.1. Basic notations. We will work on the \( d \)-dimensional integer lattice \( \mathbb{Z}^d \), and in the present paper our focus will be in \( d \geq 5 \), although the basic definition is well-posed in all dimensions. Also, some of the partial results which don’t rely on the dimension restriction will be stated and proved in generality.

For \( N \in \mathbb{N} \), let \( V_N := \{-N/2, N/2\}^d \cap \mathbb{Z}^d \) and \( V_N^c := \mathbb{Z}^d \setminus V_N \).

For \( x, y \in \mathbb{Z}^d \), \( d(x, y) \) is the graph distance between \( x \) and \( y \) on the lattice with nearest-neighbor bonds, i.e. the \( \ell_1 \)-norm of \( x - y \). With \( \| \cdot \| \), we denote the Euclidean norm.

We will use \( L \) as a generic positive constant which depends only on the dimension \( d \), not necessarily the same at different occurencies, and also not necessarily the same within the same formula. The dependence on \( d \) will not be mentioned, but dependence on other parameters will be noted by writing \( L(k) \) or \( L(\varepsilon) \), for instance.

We will consider real valued random fields \( \{ \varphi_x \}_{x \in \mathbb{Z}^d} \). For \( A \subset \mathbb{Z}^d \), we write \( \mathcal{F}_A \) for the \( \sigma \)-field generated by the random variables \( \{ \varphi_x, x \in A \} \). To be definite, we can of course have all the measures constructed on \( \mathbb{R}^{\mathbb{Z}^d} \), equipped with the product \( \sigma \)-field.

We will typically use \( x, y \) for points in \( \mathbb{Z}^d \). If we write \( \sum_x \), this means summation over all \( \mathbb{Z}^d \). We will use \( e \) exclusively for the \( 2d \) elements of \( \mathbb{Z}^d \) which are neighbors of 0. To keep notations less heavy, \( \sum_x \) means that we sum over all these elements, and similarly for other discrete differential operators we will introduce. For a function \( f \) on \( \mathbb{Z}^d \), we write

\[
D_{e} f \left( x \right):= f \left( x + e \right) - f \left( x \right).
\]

We write \( \nabla f \) for the vector \( \left( D_{e} f \right)_e \), and \( \nabla^2 f \) for the matrix \( \left( D_{e} D_{e'} f \right)_{e, e'} \), and similarly for the higher order derivatives which are denoted by \( \nabla^3, \nabla^4 \) etc. Remark that \( \nabla^k f (x) \) depends on all the values \( f (y) \) with \( d (y, x) \leq k \). We write

\[
\left\| \nabla^k f \left( x \right) \right\|^2 = \left\| \nabla^k f \left( x \right) \right\|^2_2 = \sum_{e_1, \ldots, e_k} |D_{e_1} D_{e_2} \cdots D_{e_k} f (x)|^2.
\]
We also define $\|\nabla^k f(x)\|_\infty := \sup_{e_1, \ldots, e_k} |D_{e_1} \cdots D_{e_k} f(x)|$. The Laplacian in (1.2) can be rewritten as

$$\Delta f(x) := \frac{1}{2d} \sum_e D_e f(x).$$

Remark that although the right hand side looks like being a first order discrete derivative, it is of course a second order one through the presence of $e$ and $-e$ in the summation. Namely, if we define only the positive coordinate directions as $\{e^{(1)}, \ldots, e^{(d)}\}$, then the alternative definition

$$\Delta f(x) = -\frac{1}{2d} \sum_{i=1}^d D_{e^{(i)}} D_{-e^{(i)}} f(x)$$

holds. For two square summable functions $f, g$ on $\mathbb{Z}^d$, we write

$$\langle f, g \rangle := \sum_{x \in \mathbb{Z}^d} f(x) g(x).$$

Summation by parts leads to the following properties:

**Lemma 2.1.** Let $f, g : \mathbb{Z}^d \to \mathbb{R}$ be square summable functions.

a) For any $e$

$$\langle D_e f, g \rangle = \langle f, D_e g \rangle. \tag{2.2}$$

b)

$$\langle \Delta f, g \rangle = \langle f, \Delta g \rangle. \tag{2.3}$$

c)

$$\sum_e \langle D_e f, D_e g \rangle = -4d \langle f, \Delta g \rangle. \tag{2.4}$$

2.2. The membrane model and statement of the main result.

**Definition 2.2** (Sakagawa (2003), Velenik (2006), Kurt (2008)). Let $W \neq \emptyset$ be a finite subset of $\mathbb{Z}^d$. The membrane model on $W$ is the random field $\{\varphi_x\}_{x \in \mathbb{Z}^d} \in \mathbb{R}^{\mathbb{Z}^d}$ with zero boundary conditions outside $W$, whose distribution is given by

$$P_W(d\varphi) = \frac{1}{Z_W} \exp \left( -\frac{1}{2} \langle \Delta \varphi, \Delta \varphi \rangle \right) \prod_{x \in W} d\varphi_x \prod_{x \in W^c} \delta_0(d\varphi_x), \tag{2.5}$$

where $Z_W$ is the normalizing constant.

In the case $W := V_N$, we simply write $P_N$ instead of $P_{V_N}$.

It is notationally convenient to define the field $\{\varphi_x\}$ for $x \in \mathbb{Z}^d$, but as $\varphi_x = 0$ for $x \notin W$, it is just a centered Gaussian random vector $\{\varphi_x\}_{x \in W}$. By (2.3), one has

$$\langle \Delta \varphi, \Delta \varphi \rangle = \langle \varphi, \Delta^2 \varphi \rangle.$$

Remark that in the inner product on the left hand side, one cannot restrict the sum to $W$ even if $\varphi$ is 0 outside $W$. There is in fact a contribution from the points at distance 1 to $W$. In contrast, in the inner product on the right hand side, the sum is only over $W$. $P_W$, when regarded as a law of a $\mathbb{R}^W$-valued vector, has density proportional to

$$\exp \left( -\frac{1}{2} \langle \varphi, \Delta^2_W \varphi \rangle \right)$$
where $\Delta_W^2 = (\Delta^2(x,y))_{(x,y) \in W}$ is the the restriction of the Bilaplacian to $W$. Actually, in order to make (2.5) meaningful, one needs that $\Delta_W^2$ is positive definite. This follows from the maximum principle for $\Delta$. In fact $\langle \Delta \varphi, \Delta \varphi \rangle > 0$ holds for all $\varphi$ which do not vanish identically, and are 0 on $W^c$. This proves the positive definiteness of $\Delta_W^2$.

The covariances of the membrane model are given as
\[
G_W(x,y) := \text{cov}_{P_W}(\varphi_x, \varphi_y) = (\Delta_W^2)^{-1}(x,y), \quad x, y \in W,
\]
(2.6)

It is convenient to extend $G_W$ to $x, y \in \mathbb{Z}^d$ by setting the entries to 0 outside $W \times W$. For $x \in W$, the function $\mathbb{Z}^d \ni y \mapsto G_W(x,y)$ is the unique solution of the boundary value problem (Kurt, 2009)
\[
\begin{cases}
\Delta^2 G_W(x,y) = \delta_{x,y}, & y \in W \\
G_W(x,y) = 0, & y \notin W.
\end{cases}
\]

For $d \geq 5$ the weak limit $P := \lim_{N \to \infty} P_N$ exits (Sakagawa, 2003, Section II). Under $P$, the canonical coordinates $\{\varphi_x\}_{x \in \mathbb{Z}^d}$ form a centered Gaussian random field with covariance given by
\[
G(x,y) = \Delta^{-2}(x,y) = \sum_{z \in \mathbb{Z}^d} \Delta^{-1}(x,z) \Delta^{-1}(z,y) = \sum_{z \in \mathbb{Z}^d} \Gamma(x,z) \Gamma(z,y),
\]
where $\Gamma$ is the Green’s function of the discrete Laplacian on $\mathbb{Z}^d$. In particular observe that
\[
G(0,0) < +\infty.
\]
(2.7)

The matrix $\Gamma$ has a representation in terms of the simple random walk $(S_m)_{m \geq 0}$ on $\mathbb{Z}^d$ given by
\[
\Gamma(x,y) = \sum_{m \geq 0} P_x[S_m = y]
\]
($P_x$ is the law of $S$ starting at $x$). This entails that
\[
G(x,y) = \sum_{m \geq 0} (m+1) P_x[S_m = y] = \mathbb{E}_{x,y} \left[ \sum_{\ell,m=0}^{\infty} 1\{S_m = \tilde{S}_\ell\} \right]
\]
where $S$ and $\tilde{S}$ are two independent simple random walks starting at $x$ and $y$ respectively. $\Gamma$ and $G$ are translation invariant. Using the above representation one can easily derive the following property of the covariance:

**Lemma 2.3** (Sakagawa (2003, Lemma 5.1)). For $d \geq 5$ there exists a constant $\kappa_d > 0$
\[
\lim_{\|x\| \to \infty \|x\|^{4-d}} \frac{G(0,x)}{\|x\|^{4-d}} = \kappa_d
\]

In other words, as $\|x - y\| \to +\infty$, the covariance between $\varphi_x$ and $\varphi_y$ decays like $\kappa_d\|x - y\|^{4-d}$ in the supercritical dimensions.

For $d = 4$, $\lim_{N \to +\infty} P_N$ does not exist, and in fact, $\text{var}_{P_N}(\varphi_0) \to +\infty$. It is known that $G_N(x,y)$ behaves in first order as $\gamma_4(\log N - \log \|x - y\|)$ for some $\gamma_4 \in (0, +\infty)$, if $x$ and $y$ are not too close to the boundary of $V_N$, see Cipriani (2013, Lemma 2.1).

**Definition 2.4** (Pinned membrane model). Let $\varepsilon > 0$. The membrane model on $W$ with pinning of strength $\varepsilon$ is defined as
\[
P_W^\varepsilon(\text{d}\varphi) = \frac{1}{Z_W^\varepsilon} \exp \left( -\frac{1}{2} \langle \Delta \varphi, \Delta \varphi \rangle \right) \prod_{x \in W} (\text{d}\varphi_x + \varepsilon \delta_0(\text{d}\varphi_x)) \prod_{x \in W^c} \delta_0(\text{d}\varphi_x),
\]
(2.8)
where $Z^e_W$ is the normalizing constant

$$Z^e_W := \int \exp \left( -\frac{1}{2} \langle \Delta \varphi, \Delta \varphi \rangle \right) \prod_{x \in W} (d\varphi_x + \epsilon \delta_0(d\varphi_x)) \prod_{x \in W^c} \delta_0(d\varphi_x).$$

In case $W = V_N$, we write $P^e_N$ and $Z^e_N$ instead.

Our main result shows that for any positive pinning strength $\epsilon$ the correlations between two points decay exponentially in the distance.

**Theorem 2.5** (Decay of covariances, supercritical case). Let $d \geq 5$ and $\epsilon > 0$. Then there exist $C, \eta > 0$ depending on $\epsilon$ and $d$, but not on $N$, such that

$$|E_N^e[\varphi_x \varphi_y]| \leq Ce^{-\eta \|x-y\|}$$

whenever $x, y \in V_N$.

**Remark 2.6.** Note that one can show that adding a mass to the membrane model implies exponential decay of correlations.

2.3. **Proof outline.** To motivate our approach, consider the following PDE problem in continuous space. Let

$$\Omega := \mathbb{R}^n \setminus \bigcup_i B_r(x_i),$$

where $\{B_r(x_i)\}_i$ is a collection of closed non-overlapping balls of radius $r$ which is sufficiently dense. For instance, assume to take $\{x_i\}_i := \mathbb{Z}^d$, and $r \leq 1/4$. The function $u : \Omega \to \mathbb{R}$ is assumed to be smooth and to satisfy $\Delta^2 u = f$, where $f$ is a smooth function on $\Omega$ of compact support, $\Delta^2$ is the continuum bilaplacian, and $u$ and $\nabla u$ have 0-boundary conditions at $\partial \Omega$. Is it true that $u$ is exponentially decaying at infinity, assuming only some mild growth condition? One can answer positively to this question as follows (the authors learned this argument from Vladimir Maz’ya): the key observation is that if $u$ on $\Omega$ satisfies 0-boundary conditions, one can obtain the equivalence of the standard second order Sobolev norm $\|u\|_{H^2(\Omega)}$ with the $L^2$-norm of the second derivative; in other words, the $L^2$-norm of $u$ and of $\nabla u$ can be estimated by the $L^2$-norm of the second derivatives. In our case, this follows by selecting a linear path from every point $x \in \Omega$ to the boundary $\partial \Omega$, and then using the 0-boundary conditions and partial integration along the path to estimate $f$ and $\nabla f$ in terms of the second derivative. Such equivalences are discussed in much greater generality in Maz’ya (2011). Choose now a sequence of concentric balls $C_n := B_n(0) \cap \Omega$, starting with $n$ such that $C_n$ contains the support of $f$, and choose smooth functions $\eta_n : \to [0,1]$, interpolating between 1 outside $C_{n+1}$ and 0 on $C_n$. Then

$$\|u\|_{H^2(C_{n+1})} = \|\eta_n u\|_{H^2(C_{n+1})} \leq \|\eta_n u\|_{H^2(\Omega)} \leq \text{const} \times \|\nabla^2(\eta_n u)\|_{L^2(\Omega)} = \text{const} \times \|\nabla^2(\eta_n u)\|_{L^2(C_{n+1}\setminus C_n)} \leq \text{const} \times \|u\|_{H^2(\Omega)} \leq \text{const} \times \left[ \|u\|_{H^2(C_n)} - \|u\|_{H^2(C_{n+1})} \right],$$

which proves the exponential decay of the Sobolev norms. In the second inequality, we have used the equivalence of the norms. In the second line, we have used that $\eta_n = 1$ outside $C_{n+1}$ and that $u$ is biharmonic. Of course, we have always assumed as an input that the above Sobolev norms are finite, but in our problem this will not be a difficulty.

The application to our setting requires a number of modifications. The first step is to notice that the environment $A$ of pinned points, corresponding to the “holes” $B_r(x_i)$ above,
can be dominated stochastically by a Bernoulli site percolation measure. The boundary conditions for the discrete derivative on the pinned sites $A$ is however not easily computable, and in general it is not 0. For that reason we work with the inner points $\hat{A}$, and use the fact that the law of this set is dominated by a Bernoulli measure, too. However the key difficulty is that there is certainly not an upper bound to the distance between any point in $\mathbb{Z}^d$ to any trapping points in $\hat{A}$, in contrast to the continuum situation sketched above, and therefore there is no equivalence of norms (with discrete derivatives, of course). The way to solve this problem is to introduce random Sobolev norms which depend on the random set $\hat{A}$, and then prove that, in an appropriate sense, the Sobolev norm involving randomly weighted discrete derivatives up to the second order is equivalent to one coming from the second derivative only. This however makes it necessary to adapt the choice of the the sequence $C_n$ to the random trapping set $A$. Indeed, it is necessary to choose the interpolating functions $\eta_n$ in such a way that the derivatives are small in regions where there are few points in $\hat{A}$. This leads to a random choice of the $C_n$’s, and in the end, one has to use a percolation argument to prove that the radius of the $C_n$’s still grows linearly in $n$ with overwhelming probability. This would not be possible choosing the $C_n$’s as concentric balls.

**Remark 2.7.** A more natural statement would be that $P^\epsilon := \lim_{N \to \infty} P^\epsilon_N$ has exponentially decaying covariances. Unfortunately, we do not know if this limit exists. The proof in Bolthausen and Velenik (2001) of the existence of the weak limit in the gradient case uses correlation inequalities which are not valid in the membrane case.

**Remark 2.8 (Outlook on the case $d = 4$).** The restriction to $d \geq 5$ is coming from a domination of the measure $\nu^\epsilon_N$ defined in (3.1) from below by a Bernoulli measure which is true in a strong sense only for $d \geq 5$. The other steps of the proof do not depend on this dimension restriction in an essential way. The method we apply here would give for $d = 4$ an estimate of $|E_{\nu^\epsilon_N}[\varphi_x \varphi_y]|$ in the form $\exp[-\eta \|x - y\| (\log N)^{-\alpha}]$ with some $\eta, \alpha > 0$. This is of course disappointing as for fixed $x, y$, one would not get decay properties which are uniformly in $N$, and one would also not get boundedness of the variances $\text{var}_{\nu^\epsilon_N}(\varphi_0)$. We remark also that with techniques similar to those of the present paper Bolthausen et al. (2016) show stretched exponential decay of covariances in $d \geq 4$.

We however expect that with some weaker domination properties, as the one used in Bolthausen and Velenik (2001) for $d = 2$, one could prove exponential decay also for the membrane model in $d = 4$. However, the proofs used in Bolthausen and Velenik (2001) rely again on correlation inequalities, so a proof eludes us.

It is well possible that exponential decay of correlations is true also for lower dimensions $d = 2, 3$, but we do not know of a method which could successfully be applied.

### 3. General results on the membrane model

Let $B \subset A \subset \mathbb{Z}^d$. As the Hamiltonian of the membrane model is represented through an interaction of range 2, the conditional distribution of $\{\varphi_x\}_{x \in B}$ under $P^\epsilon_A$ given $F_{A \setminus B}$ depends only on $\{\varphi_y\}_{y \in \partial_2 B \cap \hat{A}}$, where $\partial_2 B := \{y \notin B : d(y, B) \leq 2\}$. As the measures are Gaussian, for $x \in B$ one has that $E_{A}[\varphi_x|F_{A \setminus B}]$ is a linear combination of the variables $\{\varphi_y\}_{y \in \partial_2 B \cap \hat{A}}$.

From general properties of Gaussian distributions, one easily gets the following result.
Proposition 3.1 (Cipriani (2013, Lemma 2.2)). Let \( A \) be a finite subset of \( \mathbb{Z}^d \), and \( B \subset A \), and let \( \{ \varphi_x \}_{x \in \mathbb{Z}^d} \) be the membrane model under the measure \( P_A \). Let further \( \{ \varphi'_x \}_{x \in B} \) be independent of \( \{ \varphi_x \}_{x \in B} \) and distributed according to \( P_B \), i.e. with 0-boundary conditions outside \( B \). Then \( \{ \varphi_x \}_{x \in B} \) has the same distribution under \( P_A \).

Corollary 3.2. Let \( B \subset A \) be finite subsets of \( \mathbb{Z}^d \), and \( x_1, \ldots, x_k \in B \), \( \lambda_1, \ldots, \lambda_k \in \mathbb{R} \), then

\[
\var{\sum_{i=1}^k \lambda_i \varphi_{x_i}} \leq \var{\sum_{i=1}^k \lambda_i \varphi_{x_i}}.
\]

Proof. By the previous proposition, \( \sum_{i=1}^k \lambda_i \varphi_{x_i} \) has under \( P_A \) the same law as

\[
E_A \left[ \sum_{i=1}^k \lambda_i \varphi_{x_i} \right] = \sum_{i=1}^k \lambda_i \varphi_{x_i},
\]

where \( \{ \varphi'_x \}_{x \in B} \) is independent of the first summand and distributed according to \( P_B \). From that, the claim follows.

For \( A \subset W \subset \mathbb{Z}^d \) we write \( P^A_W := P_{W \setminus A} \), i.e. the membrane model with 0-boundary conditions on both \( W^c \) and on \( A \). We use \( E^A_W \) to denote the average with respect to \( P^A_W \). We also write \( G^A_W \) for the corresponding covariance matrix. If \( A = \emptyset \), then \( P^\emptyset_W = P_W \). Again, we just use the index \( N \) if \( W = V_N \).

Corollary 3.3. Let \( A \subset \mathbb{Z}^d \), and \( d \geq 5 \). Then the weak limit \( P^A := \lim_{N \to +\infty} P^A_N \) exists, and it is a centered Gaussian field, with covariances

\[
G^A (x, y) = \lim_{N \to +\infty} G^x_N (x, y), \quad x, y \in \mathbb{Z}^d.
\]

Proof. By Corollary 3.2, \( G^A_N (x, x) \uparrow G^A (x, x) < +\infty \) for all \( x \), as \( N \to +\infty \). The finiteness comes from \( G^A_N (x, x) \leq G_N (x, x) \leq G (x, x) < +\infty \) (recall (2.7)). So \( \{ P^A_N \}_N \) is a tight sequence. But for \( x, y \in \mathbb{Z}^d \), also \( \lim_{N \to +\infty} \var{\varphi_x + \varphi_y} \) exists, and therefore \( \lim_{N \to +\infty} G^A_N (x, y) \) exists. This implies the statement of the corollary.

Bernoulli domination. A key step of our proof is that the environment of pinned points can be compared with Bernoulli site percolation. Expanding \( \prod_{x \in W} (d \varphi_x + \varepsilon \delta_0(d \varphi_x)) \) in (2.8), one has, for any measurable function \( f : \mathbb{R}^{\mathbb{Z}^d} \to \mathbb{R} \),

\[
E^\varepsilon_W (f) = \frac{1}{Z^W_{\varepsilon}} \int f(\varphi) \exp \left( -\frac{1}{2} \langle \Delta \varphi, \Delta \varphi \rangle \right) \prod_{x \in W} (d \varphi_x + \varepsilon \delta_0(d \varphi_x)) \prod_{x \in W^c} \delta_0(d \varphi_x) = \sum_{A \subset W} \varepsilon^{|A|} \frac{Z^A_W}{Z^W_{\varepsilon}} E^A_W (f),
\]

where \( Z^A_W := Z_{W \setminus A} \) i.e.

\[
P^\varepsilon_W = \sum_{A \subset W} \xi^\varepsilon_W (A) P^A_W,
\]

with

\[
\xi^\varepsilon_W (A) := \varepsilon^{|A|} \frac{Z^A_W}{Z^W_{\varepsilon}}.
\]
which is a probability measure on $\mathcal{P}(W)$, the set of subsets of $W$. We will often use $A$ or $A_W$ to denote a $\mathcal{P}(W)$-valued random variable with this distribution, so that we can write

$$E_W^\varepsilon(x,y) = \sum_{A \subseteq W} \varepsilon^\varepsilon_W(A) G^A_W(x,y) = E^\varepsilon_W \left( G^A_W(x,y) \right).$$

(3.2)

**Lemma 3.4.** In $d \geq 5$ there exist constants $0 < C_-, C_+ < \infty$ depending only on the dimension such that for every $w \in W$ and $E \subseteq W \setminus \{w\}$

$$C_- \leq \frac{Z^E_{W \cup \{w\}}}{Z^E_W} \leq C_+.$$  

(3.3)

**Proof.** The proof follows the ideas of Velenik (2006, Section 5.3). $Z^E_{W \cup \{w\}} / Z^E_W$ is the density at 0 of the distribution of $\varphi_w$ under the law $P^E_W$, i.e.

$$\frac{Z^E_{W \cup \{w\}}}{Z^E_W} = \frac{1}{\sqrt{2\pi G^E_W(w,w)}}.$$

As $0 < G^E_w(w,w) \leq G^E_w(w,w) \leq G(w,w) = G(0,0) < +\infty,$

the claim follows. □

**Remark 3.5.** For $d = 2, 3, 4$, one has a similar upper bound for $Z^E_{W \cup \{w\}} / Z^E_W$, but the lower bound depends on $W$, as $G(0,0) = +\infty$. For $d = 4$, one has, for $W := V_N$,

$$\frac{Z^E_{N \cup \{w\}}}{Z^E_N} \geq \frac{C_-}{\sqrt{\log N}}.$$

We control now the pinning measure $\xi^\varepsilon_W$ through dominations by Bernoulli product measures.

**Definition 3.6** (Strong stochastic domination). Given two probability measures $\mu$ and $\nu$ on the set $\mathcal{P}(W)$, $|W| < +\infty$, we say that $\mu$ dominates $\nu$ strongly stochastically if for all $x \in W$, $E \subseteq W \setminus \{x\}$,

$$\mu(A) : x \in A | A \setminus \{x\} = E \geq \nu(A) : x \in A | A \setminus \{x\} = E).$$

(3.4)

When this holds we write $\mu > \nu$.

Let $P^\rho_W$ be the Bernoulli site percolation measure on $W$ with intensity $\rho \in [0,1]$. We regard this as a probability measure on $\mathcal{P}(W)$.

**Proposition 3.7.** Let $d \geq 5$ and $\varepsilon > 0$. Then

$$P^{\rho_-(d,\varepsilon)}_W < \xi^\varepsilon_W < P^{\rho_+(d,\varepsilon)}_W$$

with

$$\rho_\pm(d,\varepsilon) := \frac{C_\pm(d) \varepsilon}{1 + C_\pm(d) \varepsilon} \in (0,1)$$

(3.5)

where $C_-, C_+$ are defined in Lemma 3.4.
Proof. For \( x, E \) as in Definition 3.6

\[
\zeta^E_W(A : x \in A | A \setminus \{x\} = E) = \left[ 1 + \frac{1}{\varepsilon} \frac{Z^E_W}{Z^E_W + 1} \right]^{-1}.
\]

This proves the claim.

\[ \square \]

4. Proof of the main result

4.1. Sobolev norms. A crucial role of the proof uses a Sobolev-type norm \( || \cdot ||_{A,E} \) depending on subsets \( A \subset E \subset \mathbb{Z}^d \). Given \( A \), let

\[ \hat{A} := \{ x \in A : x + e \in A, \text{for all } e \} . \]

\( \hat{A} \) is the subset of “interior” points of \( A \). For \( f : \mathbb{Z}^d \to \mathbb{R} \) and \( A \subset E \subset \mathbb{Z}^d \), let

\[
||f||^2_{A,E} := \sum_{x \in E} \frac{f(x)^2}{1 + d(x, A)^{2d+3}} + \sum_{x \in E} \frac{||\nabla^2 f(x)||^2}{1 + d(x, A)^{2d+3}} + \sum_{x \in E} ||\nabla^2 f(x)||^2 .
\]

If \( \hat{A} = \emptyset \), then we put \( d(x, \hat{A}) = +\infty \) by convention, and \( ||f||^2_{\hat{A},E} = \sum_{x \in E} ||\nabla^2 f(x)||^2 \). We note the following two facts:

1. \( ||f||^2_{\hat{A},E} \) is defined for \( f : E \cup \partial_2 E \to \mathbb{R} \).
2. If \( E_1 \) and \( E_2 \) are disjoint then

\[
||f||^2_{\hat{A},E_1 \cup E_2} = ||f||^2_{\hat{A},E_1} + ||f||^2_{\hat{A},E_2} .
\]

When \( E := \mathbb{Z}^d \) and we randomize \( A \) thinking of it as the set of pinned points, we will use this norm as the random Sobolev norm equivalent to \( ||\nabla^2 \cdot ||_{L^2} \). We now bound the \( || \cdot ||^2_{\hat{A},\mathbb{Z}^d} \) norm of a function vanishing on \( A \) by second derivates only.

Lemma 4.1. Let \( f \) be a function which is identically zero on \( A \). Then

\[
||f||^2_{\hat{A},\mathbb{Z}^d} \leq L \sum_{x \in \mathbb{Z}^d} ||\nabla^2 f(x)||^2 .
\]

Proof. There is nothing to prove when \( \hat{A} = \emptyset \), so we assume \( \hat{A} \neq \emptyset \).

We first show that the first summand on the right hand side of (4.1) is dominated by a multiple of the second, and afterwards that the second is dominated by the third.

If \( x \in \mathbb{Z}^d \), we choose a nearest-neighbor path \( \psi_x \) of shortest length \( |\psi_x| := k + 1 \) to \( \hat{A} \), that is, \( \psi_x = (x_0 = x, x_1, \ldots, x_k) \) with \( x_k \in \hat{A} \). As \( f \) is 0 on \( A \), one has

\[
f(x) = \sum_{l=1}^k (f(x_l-1) - f(x_l)).
\]

We can choose the collection \( \{\psi_x\} \) of paths in such a way that the same bond is not used for two different end points in \( \hat{A} \). More formally: if \( x, x' \in \mathbb{Z}^d \) with paths \( \psi_x = (x, x_1, \ldots, x_k) \), \( \psi_{x'} = (x', x'_1, \ldots, x'_{k'}) \) have the property that there exists a bond \( b \) which belongs to both paths, then \( x_k = x'_{k'} \). This can be achieved by choosing an enumeration \( \{x_n\} \) of \( \mathbb{Z}^d \), and constructing the paths recursively with this property.
By Cauchy-Schwarz,
\[ f(x)^2 \leq |\psi_x| \sum_{l=1}^{k} (f(x_l) - f(x_{l-1}))^2 = d(x, \hat{A}) \sum_{l=1}^{d(x, \hat{A})} (f(x_l) - f(x_{l-1}))^2, \]
and thus, exchanging the order of summation between points \( x \) and paths \( \psi_x \),
\[
\sum_{x} \frac{f(x)^2}{1 + d(x, A)^{2d+3}} \leq \sum_{x} \frac{d(x, \hat{A})}{1 + d(x, A)^{2d+3}} \sum_{l=1}^{d(x, \hat{A})} (f(x_l) - f(x_{l-1}))^2 \\
\leq \sum_{z} \|\nabla f(z)\|^2 \sum_{x \in \psi_x} \frac{d(x, \hat{A})}{1 + d(x, A)^{2d+3}}. \quad (4.2)
\]
For \( z \in \mathbb{Z}^d \) write \( R_{z,k} := \{ x \in \mathbb{Z}^d : d(x, \hat{A}) = k \} \) and \( z \in \psi_x \). Observe that every \( x \in \mathbb{Z}^d \) with \( z \in \psi_x \) satisfies \( d(x, \hat{A}) \geq d(z, \hat{A}) \). Notice also that if \( z \in \psi_x \), the path \( \psi_x \) cannot take less than \( d(z, \hat{A}) \) steps to reach \( \hat{A} \) from \( z \) (otherwise \( d(z, \hat{A}) \) would not be minimal). Thus \( R_{z,k} \) can be bounded by the volume of a ball around \( z \), namely, there exists a constant \( c_1 = c_1(d) \) such that \( |R_{z,k}| \leq c_1(k - d(z, \hat{A}))^{d-1} \leq c_1k^{d-1} \). Therefore
\[
\sum_{x \in \psi_x} \frac{d(x, \hat{A})}{1 + d(x, A)^{2d+3}} \leq \sum_{k=d(z, \hat{A})}^{\infty} \frac{|R_{z,k}|}{1 + k^{2d+2}} \\
\leq L \sum_{k=d(z, \hat{A})}^{\infty} \frac{1}{1 + k^{d+2}} \leq L \frac{1}{1 + d(z, A)^{d+2}}. \quad (4.3)
\]
Thus we have, plugging (4.3) in (4.2),
\[
\sum_{x} \frac{f(x)^2}{1 + d(x, A)^{2d+3}} \leq L \sum_{x} \frac{1}{1 + d(x, A)^{d+2}} \|\nabla f(x)\|^2.
\]
It remains to prove that the right hand side is bounded by some multiple of \( \sum_x \|\nabla^2 f(x)\|^2 \). If \( \psi_x \) is the same as above, we have
\[
\nabla f(x) = \sum_{l=1}^{k} (\nabla f(x_{l-1}) - \nabla f(x_l)),
\]
because \( \nabla f(x_k) = 0 \) component-wise for \( x_k \in \hat{A} \). By the same arguments as above we get
\[
\|\nabla f(x)\|^2 \leq d(x, \hat{A}) \sum_{l=1}^{d(x, \hat{A})} |\nabla [f(x_l) - f(x_{l-1})]|^2,
\]
and
\[
\sum_{x} \frac{\|\nabla f(x)\|^2}{1 + d(x, A)^{d+2}} \leq \sum_{x \in \mathbb{Z}^d} \frac{d(x, \hat{A})}{1 + d(x, A)^{d+2}} \sum_{l=1}^{k} \|\nabla [f(x_l) - f(x_{l-1})]|^2 \\
\leq L \sum_{z} \|\nabla^2 f(z)\|^2 \sum_{x \in \psi_x} \frac{1}{1 + d(x, A)^{d+1}} \leq L \sum_{z} \|\nabla^2 f(z)\|^2 \left[ \sup_{y \in \hat{A}} \sum_{x} \frac{1}{1 + d(x, y)^{d+1}} \right] \\
\leq L \sum_{z} \|\nabla^2 f(z)\|^2.
\]
For \( k \geq 0 \) and \( E \subset \mathbb{Z}^d \) let
\[
\nu_k(E) := \{ x : d(x, E) \leq k \}.
\]
For \( x, y \in \mathbb{Z}^d \) let \( \Gamma_{x,y} \) be the set of non-intersecting nearest-neighbor paths
\[
\psi = (x_0 = x, x_1, \ldots, x_n = y),
\]
and we write \( \ell(\psi) \) for the length \( n \). For such a \( \psi \) we define
\[
\phi_A(\psi) := \sum_{i=0}^n q_A(x_i),
\]
where
\[
q_A(x) := \frac{1}{1 + d(x, \hat{A})^{2d+3}}, \quad x \in \mathbb{Z}^d.
\]
Define
\[
\hat{d}_A(x, y) := \min \{ \phi_A(\psi) : \psi \in \Gamma_{x,y} \},
\]
\[
\hat{d}_A(0, 0) := 0.
\]
\( \hat{d}_A \) is defined in such a way that the shortest weight \( \phi_A \) is achieved by staying far off pinned points. See Figure 1 for a 2-dimensional example of \( \phi_A \) for paths between a point \( y \) and the origin.

\( \hat{d}_A \) may well be bounded, for instance if \( A \) is a finite set. In the cases we are interested in, it will however be unbounded. We will often just write \( \hat{d} \) if it is clear from the context what set \( A \) is considered. Since \( q_A(x) \leq 1 \) for any \( x \), note also the bound \( \hat{d}(x, y) \leq d(x, y) \) for all \( x, y \in \mathbb{Z}^d \).

**Figure 1.** Crosses represent pinned points. Note that \( \psi_1 \) is smaller in graph distance than \( \psi_2 \). However, since \( \psi_1 \) is closer to pinned points, \( 1.015 \approx \phi_A(\psi_1) > \phi_A(\psi_2) \approx 0.032 \). The \( \hat{d}_A \)-distance between \( y \) and \( O \) is then achieved minimizing \( \phi_A \) over all paths.
We define
\[ C_n := \left\{ x : \hat{d}(0, x) \leq 10n \right\}. \] (4.5)

\( C_n \) is connected in the usual graph structure of \( \mathbb{Z}^d \), but the complement may be disconnected. If we want to emphasize the dependence of \( C_n \) on \( A \), we write \( C_{n,A} \).

**Remark 4.2.** Remark that \( v_2(C_n) \cap v_2(C_{n+1}) = \emptyset \). In fact, assuming that there is a \( w \in v_2(C_n) \cap v_2(C_{n+1}) \), then there exist
\[ w_1 \in C_n, \quad w_2 \in C_{n+1} \] (4.6)
with \( d(w, w_i) \leq 2 \) for \( i = 1, 2 \). Hence \( \hat{d}(w_1, w_2) \leq d(w_1, w_2) \leq 4 \) by the triangle inequality for the graph distance, which contradicts (4.6).

We will need a monotonicity property in the dependence on \( A \). First remark that if \( A \subset A' \) then \( \hat{d}(x, \hat{A}) \geq \hat{d}(x, \hat{A}') \) for all \( x \), and therefore
\[ \hat{d}_{A} \leq \hat{d}_{A'}. \] (4.7)

**Lemma 4.3.** For every \( n \), there exists a function \( \eta_n : \mathbb{Z}^d \rightarrow [0, 1] \) with the following properties:
\[ \eta_n = 0 \text{ on } v_2(C_n), \quad \eta_n = 1 \text{ on } v_2(C_{n+1}), \] (4.8)
\[ \| \nabla \eta_n (x) \|_\infty \leq \frac{L}{1 + d(x, \hat{A})^{2d+3}}, \quad \forall x \in \mathbb{Z}^d. \] (4.9)

**Proof.** Let \( f_1(x) := \hat{d}(x, v_2(C_n)) \) and \( f_2(x) := \hat{d}(x, v_2(C_{n+1})) \). We define
\[ \eta_n(x) := \frac{f_1(x)}{f_1(x) + f_2(x)}. \]
which evidently satisfies (4.8).

To prove (4.9), notice first that one can find an \( L \) large uniformly for all \( x \) with \( d(x, \hat{A}) \leq 4 \), so let us consider \( x \) such that \( d(x, \hat{A}) \geq 5 \). We have from Remark 4.2 that
\[ f_1(x) + f_2(x) \geq 1. \]
Then
\[ |D_x \eta_n (x)| \leq \frac{|D_x f_1 (x)|}{f_1 (x) + f_2 (x)} + f_1 (x + e) \left| \frac{1}{f_1 (x) + f_2 (x)} - \frac{1}{f_1 (x + e) + f_2 (x + e)} \right|. \] (4.10)

We see that
\[ |D_x f_1 (x)| \leq q_A(x) + q_A(x + e) \]
\[ \leq \frac{2}{1 + \min \left\{ d \left( x, \hat{A} \right), d \left( x + e, \hat{A} \right) \right\}^{2d+3}} \]
\[ \leq \frac{L}{1 + d \left( x, \hat{A} \right)^{2d+3}}, \]
as we assumed \( d(x, \hat{A}) \geq 5 \). The same estimate is true also for \(|D_{c}f_{2}(x)|\).

The second summand in (4.10) is bounded above by \(|D_{c}f_{1}(x)| + |D_{c}f_{2}(x)|\), so the claim follows. \( \square \)

**Corollary 4.4.** For all \( x \in \mathbb{Z}^{d} \) it holds that

a) for all \( k \geq 2 \) there exists \( L = L(k) > 0 \) such that

\[
\left\| \nabla^{k} \eta_{n}(x) \right\|_{\infty} \leq \frac{L}{1 + d(x, \hat{A})^{2d+3}}. \tag{4.11}
\]

b) For all \( e \) neighbors of the origin and \( k \geq 1 \) there exists \( L = L(k) > 0 \) such that

\[
\left\| \nabla^{k} \eta_{n}(x + e) \right\|_{\infty} \leq \frac{L}{1 + d(x, \hat{A})^{2d+3}}, \forall x \in \mathbb{Z}^{d}, \forall e. \tag{4.12}
\]

**Proof.**

a) (4.9) implies that also higher order derivatives can be estimated by the same bound with a changed \( L \) because the supremum norm of higher order discrete derivatives can be estimated by the first order ones.

b) Again this holds by an estimate with first order derivatives and the fact that

\[
|d(x + e, \hat{A}) - d(x, \hat{A})| \leq 1.
\]

\( \square \)

Consider now an infinite set \( A \) with the property that \( C_{n,A} \) is finite for all \( n \). Given \( A \) with \( A^{c} \) finite, and \( 0 \notin A \), we consider the unique function \( h_{A} \) which satisfies \( h_{A}(x) = 0 \) on \( A \), and for all \( x \in A^{c} \)

\[
\Delta^{2} h_{A}(x) = \delta_{0}(x).
\]

**Lemma 4.5.** With the above notation, we have for \( n \geq 1 \)

\[
\left\| h_{A} \right\|_{A_{n+1}}^{2} \leq L \left\| h_{A} \right\|_{A_{n+1}}^{2} \leq L \left\| h_{A} \right\|_{A_{n+1}}^{2} \leq L \sum_{e, \epsilon} \langle D_{e} D_{\epsilon} \eta_{n} h, D_{e} D_{\epsilon} \eta_{n} h \rangle.
\]

It is important to emphasize that \( L \) depends neither on \( A \) nor on \( n \).

**Proof.** Fix \( n \), and let \( \eta_{n} \) be as in Lemma 4.3. We also drop the subscript \( A \) in \( h_{A} \). We have with Lemma 4.1 and Lemma 2.1

\[
\left\| h \right\|_{A_{n+1}}^{2} = \left\| \eta_{n} h \right\|_{A_{n+1}}^{2} \leq \left\| \eta_{n} h \right\|_{A_{n+1}}^{2} \leq L \sum_{e, \epsilon} \langle D_{e} D_{\epsilon} \eta_{n} h, D_{e} D_{\epsilon} \eta_{n} h \rangle
\]

\[
= L \left\langle \eta_{n} h, \Delta^{2} (\eta_{n} h) \right\rangle. \tag{4.13}
\]

By an elementary computation, one has for any \( f, g : \mathbb{Z}^{d} \rightarrow \mathbb{R} \) and \( x \in \mathbb{Z}^{d} \)

\[
\Delta (fg)(x) = f(x) \Delta g(x) + \Delta f(x) g(x) + \frac{1}{2d} \sum_{e} f(x) D_{e} g(x). \tag{4.14}
\]
Applying this twice gives
\[
\Delta^2(\eta_n h) = \eta_n \Delta^2 h + (\Delta^2 \eta_n) h + 2\Delta \eta_n \Delta h + \frac{1}{d} \sum_e (D_e \Delta \eta_n) D_e h \\
+ \frac{1}{d} \sum_e (D_e \eta_n) (D_e \Delta h) + \frac{1}{4d^2} \sum_{e,e'} (D_{e'} D_e \eta_n) D_{e'} D_e h
\]
\[
= F_1 + F_2 + 2F_3 + \frac{1}{d} F_4 + \frac{1}{4d^2} F_5.
\]
Note that
\[
\langle \eta_n h, F_1 \rangle = \langle \eta_n h, \eta_n \Delta^2 h \rangle = 0,
\]
for \( x \neq 0 \) we have \( \Delta^2 h(x) = 0 \) and for \( x = 0 \) we have \( \eta_n(0) = 0 \). All other terms contain derivatives of \( \eta_n \). Therefore, every derivative of the function \( \eta_n \) will be non-zero only for points in \( C_{n+1} \setminus C_n \). Since we have (4.13), we need to estimate \( \langle \eta_n h, F_i \rangle \) for \( i = 2, \ldots, 6 \). Let us begin with \( i = 2 \): by Corollary 4.4
\[
|\langle \eta_n h, F_2 \rangle| \leq \sum_x |\Delta^2 \eta_n(x)| h(x)^2 = \sum_{x \in C_{n+1} \setminus C_n} |\Delta^2 \eta_n(x)| h(x)^2
\]
\[
\leq \sum_{x \in C_{n+1} \setminus C_n} \frac{L}{1 + d(x, \bar{A})^{2d+3}} h(x)^2 \leq L ||h||^2_{A,C_{n+1} \setminus C_n}. \tag{4.16}
\]
Let us see now \( i = 3 \). With the Cauchy-Schwarz inequality we get
\[
|\langle \eta_n h, F_3 \rangle| \leq L \sqrt{\sum_{x \in C_{n+1} \setminus C_n} \eta_n(x) h(x) \Delta \eta_n(x) \Delta h(x)}
\]
\[
\leq L \sqrt{\sum_{x \in C_{n+1} \setminus C_n} (\Delta h(x))^2} \sqrt{\sum_{x \in C_{n+1} \setminus C_n} (\Delta \eta_n(x))^2} h(x)^2
\]
\[
\leq L ||h||^2_{A,C_{n+1} \setminus C_n}. \tag{4.17}
\]
using Corollary 4.4, (2.1) and the arithmetic-geometric mean inequality.
To estimate the part with \( F_4 \), we first observe that \( D_e \Delta \eta_n(x) \) is 0 outside \( C_{n+1} \setminus C_n \), and by Remark 4.4
\[
|D_e \Delta \eta_n(x)| \leq \frac{L}{1 + d(x, \bar{A})^{2d+3}}.
\]
Therefore, using the inequality of arithmetic and geometric means,
\[
|\langle \eta_n h, F_4 \rangle| \leq L \sum_e \sqrt{\sum_{x \in C_{n+1} \setminus C_n} \frac{h(x)^2}{1 + d(x, \bar{A})^{2d+3}}} \sqrt{\sum_{x \in C_{n+1} \setminus C_n} \frac{D_e h(x)^2}{1 + d(x, \bar{A})^{2d+3}}}
\]
\[
\leq L \sum_e \sqrt{\sum_{x \in C_{n+1} \setminus C_n} \frac{h(x)^2}{1 + d(x, \bar{A})^{2d+3}}} \sqrt{\sum_{x \in C_{n+1} \setminus C_n} \frac{D_e h(x)^2}{1 + d(x, \bar{A})^{d+2}}}
\]
\[
\leq L ||h||^2_{A,C_{n+1} \setminus C_n}. \tag{4.18}
\]
For the estimate of \( \langle \eta_n h, F_5 \rangle \) we can use Lemma 4.3 and (2.1) again to say that, for a fixed direction \( e \),

\[
|\langle \eta_n h, (D_e \eta_n) (D_e \Delta h) \rangle| \\
\leq \sum_{\mathbf{x} \in \mathbb{C}_{n+1} \setminus \mathbb{C}_n} \eta_n (\mathbf{x}) h (\mathbf{x}) D_e \eta_n (\mathbf{x}) \Delta h (\mathbf{x}) + \sum_{\mathbf{x} \in \mathbb{C}_{n+1} \setminus \mathbb{C}_n} \eta_n (\mathbf{x}) h (\mathbf{x}) D_e \eta_n (\mathbf{x}) \Delta h (\mathbf{x} + e) \\
\leq \sqrt{\sum_{\mathbf{x} \in \mathbb{C}_{n+1} \setminus \mathbb{C}_n} h (\mathbf{x})^2 D_e \eta_n (\mathbf{x})^2} \left[ \sqrt{\sum_{\mathbf{x} \in \mathbb{C}_{n+1} \setminus \mathbb{C}_n} \Delta h (\mathbf{x})^2} + \sqrt{\sum_{\mathbf{x} \in \mathbb{C}_{n+1} \setminus \mathbb{C}_n} \Delta h (\mathbf{x} + e)^2} \right] \\
\leq L \| h \|_{A, \mathbb{C}_{n+1} \setminus \mathbb{C}_n}^2.
\]

Summing over \( e \) yields

\[
|\langle \eta_n h, F_5 \rangle| \leq L \| h \|_{A, \mathbb{C}_{n+1} \setminus \mathbb{C}_n}^2 \quad (4.19)
\]

It finally remains to show

\[
|\langle \eta_n h, F_5 \rangle| \leq L \| h \|_{A, \mathbb{C}_{n+1} \setminus \mathbb{C}_n}^2 \quad (4.20)
\]

which follows in the same way as (4.17).

Combining (4.15)-(4.20) proves the lemma. \( \square \)

With these preparations, we can now prove that \( \| h \|_{A, \mathbb{C}_{n+1}}^2 \) decays exponentially.

**Lemma 4.6.** Let \( d \geq 1 \), and let \( A \subset \mathbb{Z}^d \setminus \{0\} \) be such that \( A^c \) is finite. There exist constants \( c_1 (d) > 0 \) and \( \delta (d) > 0 \), independent of \( A \), such that, for all \( n \in \mathbb{N} \),

\[
\| h \|_{A, \mathbb{C}_{n+1}}^2 \leq c_1 e^{-\delta n} \| h \|_{A, \mathbb{Z}^d}^2.
\]

**Proof.** From Lemma 4.5 we get

\[
\| h \|_{A, \mathbb{C}_{n+1}}^2 \leq L \| h \|_{A, \mathbb{C}_{n+1} \setminus \mathbb{C}_n}^2 = L \left( \| h \|_{A, \mathbb{C}_n}^2 - \| h \|_{A, \mathbb{C}_{n+1}}^2 \right),
\]

that is, iterating the argument,

\[
\| h \|_{A, \mathbb{C}_{n+1}}^2 \leq \frac{L}{1 + L} \| h \|_{A, \mathbb{C}_n}^2 \leq \left( \frac{L}{1 + L} \right)^{n-1} \| h \|_{A, \mathbb{C}_1}^2 \\
\leq \frac{1 + L}{L} \left( \frac{L}{1 + L} \right)^n \| h \|_{A, \mathbb{Z}^d}^2,
\]

proving the claim. \( \square \)

**Corollary 4.7.** If \( d \geq 5 \), then, under the same conditions and notation as above

\[
\| h \|_{A, \mathbb{C}_n}^2 \leq c_1 e^{-\delta n}.
\]

**Proof.** By Lemma 4.1

\[
\| h \|_{A, \mathbb{Z}^d}^2 \leq L \sum_{\mathbf{x} \in \mathbb{Z}^d} \| \nabla^2 h (\mathbf{x}) \|^2 = L \langle h, \Delta^2 h \rangle = L h (0) \leq L G (0, 0) < +\infty.
\]

Plugging this in Lemma 4.6 concludes the proof. \( \square \)
4.2. **Trapping configurations under the Bernoulli law.** In order to prove our main theorem, we have to obtain probabilistic properties of the sequence \( \{C_n, \mathcal{A}\}_n \) where \( \mathcal{A} \) is random and distributed according to \( \zeta^p \). Using the Bernoulli domination, the key probabilistic estimates have to be done only for a Bernoulli measure instead of \( \zeta^p \). Therefore, let \( p \in (0, 1) \) and \( \mathbb{P}^p \) be the Bernoulli site percolation measure on the set of subsets of \( \mathbb{Z}^d \) with parameter \( p \). As \( p \) is fixed in this section, we leave it out in the notation. We write \( \mathcal{A} \) for the set of interior points. Let \( B_m(x) := \{ y : d(x, y) \leq m \} \).

**Lemma 4.8.** For \( m \in \mathbb{N}, x \in \mathbb{Z}^d \),

\[
\mathbb{P}\left( B_m(x) \cap \mathcal{A} = \emptyset \right) \leq \left( 1 - p^{2d+1} \right)^{\lfloor \frac{2m+1}{3} \rfloor^d}.
\]

**Proof.** It suffices to take \( x = 0 \) and write \( B_m \) for \( B_m(0) \). Note that \( B_m \) is a hypercube of side length \( 2m + 1 \). Put \( n := \lfloor (2m + 1)/3 \rfloor \). We can place \( n^d \) pairwise disjoint boxes \( B_j(x_j), 1 \leq j \leq n^d \) in \( B_m \). As these boxes are disjoint, the events \( \{ x_j \in \mathcal{A} \} \) are independent and they have probability \( p^{2d+1} \). Therefore

\[
\mathbb{P}\left( B_m \cap \mathcal{A} = \emptyset \right) \leq \mathbb{P}\left( x_j \notin \mathcal{A}, \forall j \leq n^d \right) = \left( 1 - p^{2d+1} \right)^{\lfloor \frac{2m+1}{3} \rfloor^d}.
\]

\( \square \)

**Lemma 4.9.** There exist \( \lambda, K > 0 \) and \( n_0 \in \mathbb{N} \) depending only on the dimension \( d \) and \( p \) such that for all \( n \geq n_0 \) and all \( N \geq Kn \)

\[
\mathbb{P}\left( \sup_{x \in C_n, \mathcal{A}} d(0, x) > Kn \right) = \mathbb{P}\left( \inf_{x : d(x, 0) > Kn} \hat{d}(0, x) \leq 10n \right) \leq e^{-\lambda n} \quad (4.21)
\]

**Proof.** The equality in (4.21) holds by the definition of \( C_n \). Let us prove the inequality on the right-hand side of the above formula.

For \( M \in \mathbb{N} \) we subdivide \( \mathbb{Z}^d \) in boxes \( B_i, i \in \mathbb{Z}^d \), of side-length \( M \):

\[
B_i := (\lfloor (i_1 - 1) M + 1, i_1 M \rfloor \times \cdots \times [\lfloor (i_d - 1) M + 1, i_d M \rfloor) \cap \mathbb{Z}^d,
\]

and

\[
B_i^0 := (\lfloor (i_1 - 1) M + 2, i_1 M - 1 \rfloor \times \cdots \times [\lfloor (i_d - 1) M + 2, i_d M - 1 \rfloor) \cap \mathbb{Z}^d,
\]

which is a box contained in \( B_i \). We define

\[
\eta(i) = \begin{cases} 1 & \text{if } B_i^0 \cap \mathcal{A} \neq \emptyset, \\ 0 & \text{if } B_i^0 \cap \mathcal{A} = \emptyset. \end{cases}
\]

The \( \eta(i) \) are i.i.d. In order to estimate \( \mathbb{P}(\eta(i) = 0) \), we subdivide the box \( B_i^0 \) into boxes \( Q_j \) of side-length 3, with possibly some small part remaining close to the boundary of \( B_i^0 \). As the \( B_i^0 \) have side-length \( M - 2 \), we can place \( [(M - 2)/3]^d \) of the \( Q \)-boxes without overlaps into \( B_i^0 \). For a \( Q \)-box, the probability that the middle point and all its neighbors belong to \( \mathcal{A} \) is \( p^{2d+1} \). Therefore

\[
\mathbb{P}(\eta(i) = 0) \leq \left( 1 - p^{2d+1} \right)^{\lfloor \frac{M+2}{3} \rfloor^d}.
\]
We choose $M = M(p,d)$ such that
\[
\mathbb{P}(\eta(i) = 0) \leq \frac{1}{64d^2}.
\] (4.22)

For $x \in \mathbb{Z}^d$, we write $i(x)$ for the index $i$ such that $x \in B_i$. Remark that $i(0) = 0$. Remark that $M$ depends on $d$ and $p$ only.

Given any self-avoiding nearest-neighbor path connecting $x$ with 0, that is, $\psi = (x_0 = x, x_1, \ldots, x_k = 0)$ we attach to it a renormalized nearest neighbor path $\tilde{\psi} = (i(x_0), i_1, \ldots, i_\ell = 0)$ for some $\ell \leq k$ in the following way. $\psi$ starts at $x$ which is inside a box $B_i(x)$. Put $i_0 := i(x)$. When $\psi$ for the first time leaves $B_{i_0}$, it enters a box $B_{i_1}$ with $i_1$ being a neighbor of $i_0$ in $\mathbb{Z}^d$. Then we wait for the next time in which $\psi$ leaves $B_{i_1}$ and enters a neighbor box $B_{i_2}$. This path is not yet self-avoiding, but we can make it so by erasing successively all the loops. See Figure 2 for an example.

![Figure 2](image)

**Figure 2.** The lattice boxes have side length one, while the renormalised $M$-boxes have side length 4 (one is highlighted in green). The path $\psi = (x_0, \ldots, x_8)$ is dashed while $\tilde{\psi} = (i(x_0), i_1 i_2)$ is solid.

In this way, we proceed and obtain a path from $i_0$ to 0, which we indicate as $i_0 \to 0$, of the form $(i_0, i_1, \ldots, i_\ell = 0)$. Evidently, we can define an injective mapping $\{0, \ldots, \ell\} \ni j \mapsto t_j \in \{0, \ldots, k\}$ with $x_{t_j} \in B_{i_j}$ (for example letting $t_j$ be the first entrance time of $\psi$ in the box $B_{i_j}$). As this mapping is injective and the path $\psi$ is self-avoiding, the $x_{t_j}$’s are different.

We attach to $\tilde{\psi}$ a weight
\[
\overline{\phi}(\tilde{\psi}) = |\{j \leq \ell : \eta(i_j) = 1\}|
\]
that counts the number of large boxes in which a pinned point lies. From the construction
one obtains that
\[ \phi(\psi) = \sum_{j=0}^{\ell} \eta(i_j) \leq \sum_{j=0}^{\ell} \eta(i_j) \leq \frac{2 + 2M^{2d+3}}{2 + 2d(x_t, \hat{A})^{2d+3}} \]
as \( d(x, \hat{A}) \leq M \) whenever \( x \in B_i \) with \( B_i \cap \hat{A} \neq \emptyset \). Moreover, recalling (4.4), we can say that
\[ \sum_{j=0}^{\ell} \eta(i_j) \leq \frac{1}{2 + 2d(x_t, \hat{A})^{2d+3}} \leq \Phi(\psi) \]
and so
\[ \Phi(\psi) \leq \left(2 + 2M^{2d+3}\right) \Phi(\psi). \]  
(4.23)

We have already fixed \( M \) above (depending only on \( d \) and \( p \)), and we choose now \( K \) as
\[ K := \left\lfloor 20M \left(2 + 2M^{2d+3}\right) \right\rfloor. \]  
(4.24)

If there exists \( x \) with \( d(0, x) > Kn \) and \( \hat{d}(0, x) \leq 10n \), then there exists a \( \psi \) from \( x \) to \( 0 \) with \( \Phi(\psi) \leq 10n \), implying by means of (4.23) that there exists a path \( \psi \) from \( i(x) \) to \( 0 \) with weight
\[ \Phi(\psi) \leq 10 \left(2 + 2M^{2d+3}\right)n \]
and
\[ d(0, i) > \frac{Kn}{M}. \]

Setting
\[ m := \left\lfloor \frac{Kn}{M} \right\rfloor, \]
we see that by our choice (4.24)
\[ \bigcup_{x: d(0, x) > Kn} \{d(0, x) \leq 10n\} \subset \bigcup_{i: d(0, i) > m} \Phi(\psi) \leq \frac{m}{2}. \]  
(4.25)

Fix \( i \) with \( d(0, i) = l > m \). A path \( \overline{\psi} = (i_0 = i, i_1, \ldots, i_r = 0) \) has length \( r := |\overline{\psi}| \geq l \), hence
\[ \left\{ \overline{\Phi}(\overline{\psi}) \leq \frac{m}{2} \right\} \subset \left\{ \overline{\Phi}(\overline{\psi}) \leq \frac{|\overline{\psi}|}{2} \right\}. \]

The number of paths of length \( r \geq l \) on the lattice is bounded by \( (2d)^r \). For every such path \( \overline{\psi} \) the \( \eta(i_j) \) are i.i.d. with success probability (cf. (4.22))
\[ P(\eta(i) = 1) =: \tau \geq 1 - \frac{1}{64d^2} > \frac{1}{2}, \]
and therefore
\[ P\left(\Phi(\overline{\psi}) \leq \frac{m}{2}\right) = P\left(\left\{ \Phi(\overline{\psi}) \leq \frac{m}{2}\right\} \cap \{\hat{A} \neq \emptyset\}\right). \]
Therefore, for a fixed $\overline{v}$, the right-hand side above is bounded by the probability that a Bernoulli sequence of length $r$ with success probability $1 - \tau$ has at least $r/2$ successes. This probability is bounded above by (see Arratia and Gordon (1989))

$$\exp \left[ -r l \left( \frac{1}{2} \left| 1 - \tau \right| \right) \right],$$

where for $p_1, p_2 \in (0, 1)$ one defines

$$I (p_1 | p_2) := p_1 \log \frac{p_1}{p_2} + (1 - p_1) \log \frac{1 - p_1}{1 - p_2}.$$

Hence

$$\mathbb{P} \left( \left\{ \overline{\varphi} (\overline{v}) \leq \frac{m}{2} \right\} \cap \left\{ \hat{A} \neq \emptyset \right\} \right) \leq \exp \left[ -r l \left( \frac{1}{2} \left| 1 - \tau \right| \right) \right]$$

$$= \exp \left[ -\frac{r}{2} \left( \log \frac{1}{2 (1 - \tau)} + \log \frac{1}{2 \tau} \right) \right] \leq (2 (1 - \tau))^{r/2} (2 \tau)^{r/2} \leq (4 (1 - \tau))^{r/2}.$$ Therefore, for $l > m$,

$$\mathbb{P} \left( \bigcup_{\overline{v} \in (0,1) \rightarrow 0} \left\{ \overline{\varphi} (\overline{v}) \leq \frac{m}{2} \right\} \cap \left\{ \hat{A} \neq \emptyset \right\} \right) \leq \sum_{r = l}^{\infty} (2d)^r (4 (1 - \tau))^{r/2} \leq \sum_{r = l}^{\infty} (2d)^r \left( 4 \frac{1}{64d^2} \right)^{r/2}$$

$$= \sum_{r = l}^{\infty} \frac{1}{2^r} = \frac{1}{2^{l-1}},$$

and

$$\mathbb{P} \left( \bigcup_{i : d \in (0,1)}> m} \overline{\varphi} (\overline{v}) \leq \frac{m}{2} \right\} \cap \left\{ \hat{A} \neq \emptyset \right\} \right) \leq \sum_{l \geq m+1} \frac{|\{i : d (i,0) = l\}|}{2^{l-1}}$$

$$\leq c_5(d) \sum_{l \geq m+1} \frac{l^{d-1}}{2^{l-1}} \leq \left( \frac{2}{3} \right)^m$$

for large enough $m$. Together with (4.25), this gives

$$\mathbb{P} \left( \bigcup_{x : d (x,0)} > Kn} \hat{d} (0, x) \leq 10n \right) \leq \left( \frac{2}{3} \right)^{Kn/m}.$$

This concludes the proof of the lemma choosing $\lambda = \lambda (p, d) := -(K/M) \log (2/3)$. \hfill \qed

4.3. **Proof of Theorem 2.5.** We assume now $d \geq 5$. Let $x, y \in \mathbb{Z}^d$. We have to estimate $E_0^x \left[ \varphi_x \varphi_y \right]$. We may assume that $x, y \in V_N$, as otherwise the expression is 0. It is convenient to shift everything by $x$:

$$E_0^x \left[ \varphi_x \varphi_y \right] = E_{V_N+x}^0 \left[ \varphi_0 \varphi_{y-x} \right] = E_{V_N+x}^0 \left( G^A_{N+x} (0, y-x) \mathbf{1}_{\{0 \notin \mathcal{A}\}} \right)$$

where $\mathcal{A} \subset V_N + x$ is distributed according to $\xi_{V_N+x}$. Substituting $z := y - x$, we see that we have to estimate

$$\left| E_{V_N+x}^0 \left( G^A_{V_N+x} (0, z) \mathbf{1}_{\{0 \notin \mathcal{A}\}} \right) \right| \leq E_{V_N+x}^0 \left( \left| G_{\mathcal{A}, V_N+x} (0, z) \right| \mathbf{1}_{\{0 \notin \mathcal{A}\}} \right).$$
Let $\overline{A} := \mathcal{A} \cup (V_N + x)^c$. For a fixed realization of $\mathcal{A}$ with $0 \notin \mathcal{A}$, $G_{V_N + x}^A(0, \cdot)$ is $h_{\mathcal{A}}$ restricted to $V_N + x$. Outside this set, $h_{\mathcal{A}}$ is of course 0.

By Proposition 3.7, the distribution of $\overline{A}$ under $\xi_{V_N + x}$ strongly dominates the Bernoulli law $\mathbb{P}^\epsilon_-$ where $\rho_- = \rho_-(d, \epsilon)$ is defined by (3.5). The Bernoulli domination is proved there only for the configuration inside $V_N + x$, but as $\overline{A}$ contains all the points outside $V_N + x$, the domination trivially extends to the measures on $\mathcal{P}(\mathbb{Z}^d)$.

Let $K = K(d, \epsilon)$ be as defined in Lemma 4.9 with $p$ there equal to $\rho_-$. Set

$$R_n := \left\{ x \in \mathbb{Z}^d : Kn \leq d(0, x) < K(n + 1) \right\}.$$ 

We want to show that we can choose $\delta > 0$, depending on $d, \epsilon$ only, such that

$$\sup_{N, x} \zeta_{V_N + x}^e \left( \sup_{z \in R_n} \left| G_{V_N + x}^A(0, z) \right| \geq \epsilon^{-\delta n} \right) \leq L(\epsilon) \epsilon^{-\delta n}. \tag{4.26}$$

Having proved this, Theorem 2.5 follows, as $\sup_{z, x, N, A} \left| G_{V_N + x}^A(0, z) \right| \leq G(0, 0) < +\infty$ for $d \geq 5$ (cf. (2.7)) and therefore, if $z \in R_n$ for some $n$, by the law of total probability we get

$$\sup_{N, x} \left| E_{N} [q_x q_{x+z}] \right| \leq \sup_{N, x} E_{N} \left[ \left| G_{V_N + x}^A(0, z) \right| 1_{\{0 \notin A\}} \right] \leq L(\epsilon) \epsilon^{-\delta n}.$$

In order to prove (4.26), set

$$X_n := \sup_{z \in R_n} \left| G_{V_N + x}^A(0, z) \right|, \quad Y_n := \left\| G_{V_N + x}^A(0, \cdot) \right\|_{R_n} \mathcal{A}, \quad \zeta_n := \sqrt{1 + \sup_{x \in R_n} d(x, \overline{A})^{2d+3}}.$$

Then

$$X_n \leq \sqrt{\sum_{z \in R_n} \left( G_{V_N + x}^A(0, z) \right)^2} \leq \zeta_n Y_n. \tag{4.27}$$

To prove (4.26), we observe that for any $\delta' > 0$ and $n \geq n_0(\delta')$

$$\sup_{N, x} \zeta_{V_N + x}^e \left( \zeta_n Y_n \geq \epsilon^{-\delta' n} \right) = \sup_{N, x} \zeta_{V_N + x}^e \left( \zeta_n Y_n \geq \epsilon^{-\delta' n}, \zeta_n < n^{2(d+2)} \right) + \sup_{N, x} \zeta_{V_N + x}^e \left( \zeta_n Y_n \geq \epsilon^{-\delta' n}, \zeta_n \geq n^{2(d+2)} \right) \leq \sup_{N, x} \zeta_{V_N + x}^e \left( Y_n \geq \epsilon^{-2\delta' n} \right) + \sup_{N, x} \zeta_{V_N + x}^e \left( \zeta_n \geq n^{2(d+2)} \right). \tag{4.28}$$

Now define $2\delta' := \delta$ where $\delta$ appears in Corollary 4.7: Notice that

$$\zeta_{V_N + x} \left( Y_n \geq \epsilon^{-\delta n} \right) = \zeta_{V_N + x} \left( Y_n \geq \epsilon^{-\delta n}, R_n \subset C_n^c \right) + \zeta_{V_N + x} \left( Y_n \geq \epsilon^{-\delta n}, R_n \cap C_n \neq \emptyset \right) \leq \zeta_{V_N + x} \left( \overline{A} = \emptyset \right) + \zeta_{V_N + x} \left( \inf_{x : d(x, 0) > Kn} d_{\mathcal{A}}(0, x) \leq 10n \right). \tag{4.29}$$
In the last inequality we have used Corollary 4.7. By means of the monotonicity property (4.7) and Bernoulli domination, the right-hand side above is dominated by

\[ P^{\rho^-} (\mathcal{A} = \emptyset) + P^{\rho^-} \left( \inf_{x,d(x,0)>Kn} d_\mathcal{A} (0, x) \leq 10n \right), \]

where \( \rho^- := \rho^-(d, \epsilon) \). With \( \lambda \) as of Lemma 4.9 we can find \( n = n(\lambda) \) large enough such that \( P^{\rho^-} (\mathcal{A} = \emptyset) \leq \exp(-\lambda n) \) applying Lemma 4.8. We plug the result of Lemma 4.9 in (4.29) to get

\[ \zeta_{V_N+x}^\epsilon (Y_n \geq e^{-\delta n}) \leq e^{-\lambda n}. \] (4.30)

We now look at the second summand of (4.28). For large enough \( n \) (depending on \( d, \epsilon \) only)

\[ \left\{ \zeta_n \geq n^{2(d+2)} \right\} \subset \left\{ \sup_{x \in \mathcal{R}_n} d(x, \mathcal{A}) > n^2 \right\}. \]

Using the monotonicity property (4.7), one has

\[ \sup_{N,x} \zeta_{V_N+x}^\epsilon \left( \sup_{x \in \mathcal{R}_n} d(x, \mathcal{A}) > n^2 \right) \leq P^{\rho^-} \left( \sup_{x \in \mathcal{R}_n} d(x, \mathcal{A}) > n^2 \right) \]

which evidently is of order \( \exp \left( -L \times n^2 \right) \) for large \( n \). This, (4.30), (4.29) and (4.27) prove (4.26).

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