Understanding of Grounded-Wire TEM Sounding with Near-Source Configuration

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Abstract

In order to understand the near-source TEM sounding method, the topic on the time domain electromagnetic exploration of deep targets is addressed using a grounded dipole source. At first, the development of the near source TEM is reviewed in this paper, then a new kind of technique capable of detecting geological targets located at deeper levels in the subsurface is proposed using the short-offset transient electromagnetic method (hereafter referred to as SOTEM). The detection abilities of this system, such as the feasibility of near-source detection for SOTEM, the investigation depth of SOTEM and the sensitivity of SOTEM, have been analyzed. The conclusion has been achieved that the proposed method is more applicable and convenient for exploration and could be used to obtain a greater detection depth with higher detection accuracy.

Keywords: NIR spectra; Rice; Lead; Copper

Introduction

TEM is more sensitive to the low resistive anomaly, which poses a pulse waveform with rich frequency-spectral component. Once emitted, it is able to cover all required frequency band with high working efficiency. Based on the classic TEM theory achievement described by famous scholars, such as Wait, Kaufman and Keller, Nabighian and Macnac, Spies, Poddar [1-5], central loop fixed loop and in-loop (with short offset) TEM has been popularly used during last two decades. It is a favorable choice in the geological survey; near-surface engineering exploration, hydrogeological exploration of coal mine and metal mine exploration [6-9]. Because the receiving mode of a loop center transmission is limited by transmission magnetic moment, it is usually able to detect targets buried at only tens to hundreds of meters in depth.

In contrast, the grounded electric source mode, i.e., long offset TEM (LOTEM) can potentially probe the depths of hundreds to thousands of meters. Since 1970, LTEM has been popularly used in America for deep structure exploration, geothermal investigation and ore prospecting [10-14]. However, the very wide separation between the transmitter and receiver in this configuration may lead to a greater influence on 2-D/3-D structures. Moreover, a larger sending and receiving separation leads to poor signal strength and signal to noise ratio, low the detection accuracy. Regarding grounded-wire source transient electromagnetic method, radiated filed and primary field can be separated. If suitable excited-wave form is adopted, the near-source zone deep soundingcan be realized, where field exploration cannot be carried out for the frequency-domain sounding. Although the study and application of short offset transient electro-magnetic has been addressed in Russia [15,16], less attention has been given to the use of Short Offset Transient Electromagnetic in the previous studies for a long time. The high-powered transmitter and short-offset receiving mode (hereafter referred to as SOTEM) is used, i.e., the short distance between transmitter and receiver position. It has become a kind of new developing orientation. Although this is not a new finding, it is more important to revisit the method for the coming deep ore detecting trend. It is still essential to conduct studies on the near-source response using electric source mode.

Comparisons of Three Kinds of Grounded Source TEM System

The geological surveys using TEM have different modes, such as LTEM, MTEM and SOTEM. In order to compare, they are introduced as follows, respectively.

Long offset grounded source mode TEM

One of the main features of LTEM is to have a long distance between transmitter and receiver, and its observation mode is similar to the controlled source audio frequency magnetotelluric method (CSAMT). The typical layout in the field work of LTEM is shown in Figure 1a. The segment AB denotes the electric dipole source with the wavelength from 1km to 3 km. R denotes the offset distance between the transmitter and receiver.

Figure 1a. The segment AB denotes the electric dipole source with the wavelength from 1km to 3 km. R denotes the offset distance between the transmitter and receiver.
the transmitter and receiver. Generally, \( R \) is greater than 3–5 km, often up to 20 km. However, because the offset distance is too greater, it may cross over multiple different geological structures sometimes, so that the received signal is always poor. Thus, this LOTEM is neither suitable to do the fine detection of geological structures, nor the exploration of complex geological structures.

**Multi-channel transient electromagnetic method**

Multi-channel Transient Electromagnetic method (MTEM) was proposed by Wright and Ziolkowski et al. \[21\]. The MTEM is different from traditional TEM method, because the MTEM work mode is to use the grounded wire source, send random code and do the observation based on multi-channel array, so as to synchronously measure receiving voltage and input sending-current. In addition, its pulse response is obtained through the de-convolution of receiving voltage and input sending-current \[20,21\]. The working diagram of MTEM is shown in Figure 1b. The main feature of MTEM is shown as the emission source and receiver located on the same measured 006 Cine. Its observation mode is similar to seismic exploration and the received pulse response data are processed as seismic data, which is a great development of data processing in TEM. In this method, the results are displayed using common offset section. The obtained high resistance can indicate the correct horizontal position of gas storage layer well.

**Short offset grounded source TEM**

A near-source exploration method, i.e., SOTEM, is proposed in this study, and its layout is shown in Figure 1c. The working procedure includes three contents. (a) After the transmitting wire source (line segment AB) is laid, the side-line measurement and exploration are implemented in a certain range of two sides of AB. The requirement of prospecting is the same as that of TEM, and the instruments can be V8, GDP32, PROTEM and so on. The magnetic field signal and electric field signal can be received using a probe and electrodes respectively. (b) Because the received signals are stronger in the near source and intermediate zone, the observation points should be arranged in the above-mentioned areas. On the other hand, the observation points should also be put in a certain offset distance from transmitting field source AB. (c) When the side-line scanning measurement is performed, the single-point measurement is taken with literal movement, or several points can be synchronously measured using multiple channels. Single or many times spatial coverage can all be done using single-point moving arrangement.

**Near-Source Exploration System**

In Figure 1c, a kind of SOTEM configuration is proposed by authors, and its setup is shown in Figure 2. The transmitter and receiver are separated with short offset (1000 m–1500 m), the transmitting wire source (line segment AB with a length of 500 m-1000 m) is grounded to earth, while a step-wave current is generated by a high-powered generator. The induced voltage data are collected by a magnetic core, whereas the electric field component (Ex) data are collected by an electrode. An observation area is selected around the near-area of electrical source for detecting underground target within the buried depth of 2000 m.

The V8 instrument made in Canada can be adopted in SOTEM system, and the SB-7K magnetic probe made in China is configured to collect induced transients electromagnetic signal. The effectively receiving area is 40000 m². After the experimental selection, a set of working parameters are determined. The current step can be used to emit to a transmitter with the transmitting current of 20 A. The range of time delay can be selected as 0.087 ms-100 ms. The measurement of each receiver point can be finished within 7 minutes.

The proposed SOTEM configuration has many advantages as followings:

1. **High work efficiency:** Compared with square loop source, the wire source can be easily laid, especially in mountainous areas, where a transmitting device is accompanied by two or more equipments used for simultaneous data acquisition with SOTEM; in addition, the survey can be carried out simultaneously on both right and left sides of the transmitter. It is very convenient and high efficient in the mountain...
geological exploration, because the wire can be laid through the ravine sidewalk in mountains. The shorter source-receiver offset in SOTEM method is employed, so that the measure points can be more focused on the anomaly below the source.

(2) High resolution: SOTEM has a smaller volume but higher resolution than LOTEM; furthermore, SOTEM excites not only the horizontal component of an electric field, but also the vertical component of the field on a geo-electric interface, whereas the loop source TEM excites only the horizontal component of electric field. Additionally, SOTEM has a high penetrability in the high-resistivity medium and a high resolution in the low-resistivity medium.

(3) Greater detection depth: The detection depth can be determined mainly by time and earth geo-electric structure. However, this is less related to the source-field point offset distance. In such a configuration, the near-area survey point can receive stronger signals than far area, which can subsequently yield field data characterized by higher signal-to-noise ratios and also provide deeper target information.

Feasibility of Near-Source Detection for SOTEM

In the uniform half-space, the responses of controlled source audio-frequency magnetotelluric method (CSAMT) in the near area are shown by the following mathematical relations [2]:

\[ E_x = \frac{I}{4\pi r} \left(3\cos 2\theta + 1\right) \]

\[ E_y = \frac{3I}{4\pi r} \sin 2\theta \]

\[ H_z = -\frac{I}{4\pi r} \sin 2\theta \]

\[ C_y = \frac{I}{2\pi r^2} \cos 2\theta \]

\[ H_z = \frac{I}{4\pi r^2} \sin \theta \]

where \( I \) is the dipole moment, \( I \) is the current, \( dl \) is the length of dipole, \( r \) is the separating distance, \( \theta \) is the angle between transmitter line direction and offset direction, and \( \sigma \) is the earth conductivity.

If the excitation wave form is similar to those in Figure 3a (Normal CSAMT bipolar square wave form), the primary and secondary fields cannot be separated, and there is no relationship between magnetic field component and earth conductivity in Equation 3-5, indicating that CSAMT cannot work well in the near-source area. On the other hand, if the excitation wave form is a step-wave type as shown in Figure 3b, the secondary field response is surveyed after turning off the primary field, which means that TEM near-source area sounding can be produced if a step-wave form is adopted.

The Investigation Depth of SOTEM

The downward diffusion depth \( (d) \) of TEM refers to the maximum depth travelled by TEM eddy current field at a given time, which can be expressed as follows [4]:

\[ d = \frac{4}{\sqrt{\pi \rho \mu_0 t}} \]  

where \( t \) is the time and \( \rho \) is the resistivity of investigated geological material. Apparently, the TEM diffusion depth is mainly related to the time and geological-electrical structure, rather than the transmitter-receiver separating distance.

In practice, considering the performance of equipment, receiver sensitivity, accuracy of measurement, noise intensity and geological-electrical parameters, the detection depth \( (d_n) \) of far-area mode (i.e., LOTEM) is often estimated using the following equation [4]:

\[ d_n = 0.28 \left( \frac{L_d I}{\rho L} \right)^{1/4} \eta \]  

Similarly, the detection depth \( (d_n) \) of the near-area mode (e.g., SOTEM) is estimated using the mathematical relation below:

\[ d_n = 0.48 \left( \frac{L_d I}{\rho L} \right)^{1/5} \eta \]  

In Equation (4) and (5), \( \eta \) is the voltage resolution precision of measuring instrument, \( \rho \) is the resistivity of detected geological structure, \( L \) is the length of transmitting source line AB, and \( r \) is the transmitter-receiver separation. The depth values calculated using Equation (7) and (8) are listed in Table 1. Where, \( d_f(m) \) denotes the detection depth using a far-area mode, and \( d_n(m) \) denotes that using a near-area mode. It can be seen from the table that the detection depth using a near-area mode is generally deeper compared with the depth obtained using the far-area mode.

Sensitivity of SOTEM

It is well known that the resistance structure is difficult to be delineated by the conventional loop TEM methods [23]. The main reason is that the response of TEM methods relies on the inductive effect of horizontal source fields. Even though the LOTEM method can generate both horizontal and vertical transient magnetic fields using grounded electric dipole source, its magnetic field responses are also not strongly induced by underground thin resistors structure [13]. This is because the response magnetic fields are mainly from the horizontal...
current flow. Obviously, the horizontal current flow cannot penetrate the ground objects through inductive coupling well.

In order to compare the sensitivity of SOTEM and LOTEM to the geological structure with the thin thickness and high resistance, a survey example of the underground geological structure, of which the thickness of geological model is 5 m and the apparent resistivity is 300 \( \Omega \cdot m \), is numerically carried out. The apparent resistivity of the rock around the thin geological structure is 100 \( \Omega \cdot m \). The length of source wire in LOTEM is 200 m and the transmitting line length in SOTEM is also 200 m. In the both, the transmitting electric currents are 10A, the frequency is 30 Hz, and the range of time sampling is 0.1087-7.1015 ms.

The apparent resistivity sensitivity of geological model with and without the geological layer of the thin thickness and high electric resistor are calculated using SOTEM and LOTEM respectively, and the results are shown in Figure 4.

Solid line is the error between apparent resistivity of geological model with and without thin thickness, high resistor for SOTEM method. Dash line is the error between apparent resistivity of geological model with and without thin thickness, and high resistor for LOTEM method. It is found in Figure 4 that the sensitivity of SOTEM is greater than that of LOTEM at late time. It is indicated that the resolution of SOTEM is better than that of LOTEM. This kind of the phenomenon can be explained as follows. The electric current source in SOTEM can lead to the vertical and horizontal currents in geological structures, and the interaction between the vertical current and horizontal geological anomaly will produce the cumulative charge along the boundary of the object with high resistivity. Because the response to the electric current source is sensitive to the cumulative charge, the mode of SOTEM has a better resolution to the thin and resistance geological layer.

In fact, the application of LOTEM can only detect the conductive layer and is not sensitive to resistance structure. In contrast, SOTEM can not only detect the thin high resistivity geological structure, but also detect the thin low resistivity geological structure.

**Discussion and Conclusions**

Because the receiving mode of a loop center transmission is limited by the transmission magnetic moment of loop, the several tens to several hundred meters of earth depth can only be detected generally. But the application of TEM with grounded electric source can detect rather greater depth than the former, so, TEM with the grounded-wire source has become a hot developing technology in geological exploration. However, the LOTEM technique its magnetic field responses cannot be strongly excited by underground thin resistors because the magnetic field only depends on the horizontal electric current penetrating into the ground through inductive coupling, in addition, a large distance between transmitter (Tx) and receiver (Rx) may lead to the reliability decrease on geological interpretation of 2-D or 3-D structures. Therefore, it is an important basic issue to study the detection ability of TEM with the short offset.

Theoretically, if step-wave form is adopted as the excitation wave, the secondary field response is surveyed after turning off the primary field, then, TEM near-source area sounding that can be produced. Thus the weak signal disadvantage of LOTEM can be well overcome. SOTEM has few additional effects, bigger exploration earth’s depth and stronger exploration ability to geological section and limited conductor. This not only realizes multiple time cover measures of the detected ground geological unit, but also the 3-D exploration of TEM.

Totally, this study presents a kind of the strategy detecting the geological targets in the deeper stratum using the sophisticated detection methods and treatment technologies of the TEM, and it is also fast, efficient and easy to implement. The main contents are to do the transient electromagnetic detection in the near source as well as make the processing and explanation of the observational data with the whole field area theory. Because the observation point is closed to emission source, the non-dipole effect must be adjusted, i.e., the emission wire is considered as the sum of numerous dipoles, and the field response of the observation point equals the sum of those field response induced by each dipole of emission source wire. The proposed method is helpful to obtain more accurate information of the shape, size and location of an underground target body and possess the important significance to the detailed study of geological structures. This innovative approach can be potentially employed in a broader scientific study such as engineering and geological exploration projects.

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