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Existence and Ulam–Hyers Stability of a Fractional-Order Coupled System in the Frame of Generalized Hilfer Derivatives

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Abstract: In this research paper, we consider a class of a coupled system of fractional integro-differential equations in the frame of Hilfer fractional derivatives with respect to another function. The existence and uniqueness results are obtained in weighted spaces by applying Schauder’s and Banach’s fixed point theorems. The results reported here are more general than those found in the literature, and some special cases are presented. Furthermore, we discuss the Ulam–Hyers stability of the solution to the proposed system. Some examples are also constructed to illustrate and validate the main results.

Keywords: ϑ-Hilfer fractional derivative; fractional coupled system; existence and stability of solutions; fixed point theorem

MSC: 26A33; 34A08; 34A12; 34D20; 47H10

1. Introduction

Recently, the theory of fractional differential equations (FDEs) has become an active space of exploration. This is because of its accurate outcomes compared with the classical differential equations (DEs). Indeed, fractional calculus has been improving the mathematical modeling of sundry phenomena in science and engineering, for more details, refer to the monographs [1–5]. The fundamental benefit of using fractional-order derivatives (FODs) rather than integer-order derivatives (IODs) is that IODs are local in nature, whereas FODs are global in nature. Numerous physical phenomena cannot be modeled for a single DE. To overcome this challenge, these kinds of phenomena can be given the assistance of coupled systems of DEs. As of late, coupled systems of FDEs have been investigated with various methodologies, see [6–10].

The existence and uniqueness results play a significant part in the theory of FDEs. The previously mentioned region has been investigated well for classical DEs. However, for FDEs, there are many theoretical aspects that need further investigation and exploration. The existence and uniqueness results of FDEs have been very much concentrated up by using Riemann–Liouville (R-L), Caputo, and Hilfer FDs, see [11–14].

Recently, notable consideration has been given to the qualitative analysis of initial and boundary value problems for FDEs with ψ-Caputo and ψ-Hilfer FDs introduced by Almeda [15] and Sousa et al. [16], respectively, see [17–24]. By considering physical phenomena which are modeled by utilizing classical FDs, the importance of ψ-Hilfer FD can be discussed by redesigning and remodeling such models under ψ-Hilfer FD.

In this regard, the most relaxing technique for stability for functional equations was presented by Ulam [25] and Hyers [26] which is famous for Hyers–Ulam (in short H-U)
stability. The first investigation into H-U’s stability for DEs was presented by Obloza [27]. Moreover, Li and Zada in [28] provided connections between the stability of U-H and uniform exponential over Banach space. These types of stability have been very well-investigated for FDEs, see [29–34]. The existence and stability of solutions of the following \( \theta \)-Hilfer type FDE:

\[
\begin{aligned}
\mathbb{D}_t^{\rho_1, \rho_2} v(t) &= f(t, v(t), \mathbb{D}_t^{\rho_3} v(t)), \quad t \in (a, T], \\
0 < \rho_1 < 1, & \quad 0 \leq \rho_2 \leq 1, \\
I_{a^+}^{1-\gamma} v(t) \big|_{t=a} &= v_a, \quad \gamma = \rho_1 + \rho_2(1 - \rho_1)
\end{aligned}
\]

have been investigated by Vanterler et al. [35]. Abdo and Panchal in [36] proved the existence, uniqueness and Ulam-Hyers stability of the following \( \theta \)-Hilfer type fractional integro-differential equation:

\[
\begin{aligned}
\mathbb{D}_t^{\rho_1, \rho_2} v(t) &= f(t, v(t), \chi v(t)), \quad t \in (a, T], \\
0 < \rho_1 < 1, & \quad 0 \leq \rho_2 \leq 1, \\
I_{a^+}^{1-\gamma} v(t) \big|_{t=a} &= v_a, \quad \gamma = \rho_1 + \rho_2(1 - \rho_1)
\end{aligned}
\]

where \( \chi v(t) = \int_0^t h(t, s, v(s)) ds \), \( \mathbb{D}_t^{\rho_1, \rho_2} \) and \( I_{a^+}^{1-\gamma} \) represent \( \theta \)-Hilfer FD and \( \theta \)-Reimann-Liouville FI, respectively.

Motivated by the above discussion, we investigate the existence, uniqueness, and H-U stability of the solutions of a coupled system involving \( a^\theta \)-Hilfer FD of the type:

\[
\begin{aligned}
\mathbb{D}_t^{\rho_1, \rho_2} v(t) &= f(t, v(t), \mathbb{D}_t^{\rho_3} v(t), \mathbb{D}_t^{\rho_4} \omega(t)), \quad t \in J := (a, b], \\
\mathbb{D}_t^{\rho_1, \rho_2} \omega(t) &= g(t, \omega(t), v(t), \mathbb{D}_t^{\rho_5} v(t)), \quad t \in J := (a, b], \\
I_{a^+}^{1-\gamma} v(t) \big|_{t=a} &= v_a, \quad I_{a^+}^{1-\gamma} \omega(t) \big|_{t=a} = \omega_a
\end{aligned}
\]

where

(i) \( 0 < \rho_1 < 1, \quad 0 \leq \rho_2 \leq 1, \rho_3 > 0, \gamma = \rho_1 + \rho_2(1 - \rho_1), \) and \( v_a, \omega_a \in \mathbb{R}; \)

(ii) \( \mathbb{D}_t^{\rho_1, \rho_2} \) represents the \( \theta \)-Hilfer FD of order \( \rho_1 \) and type \( \rho_2 \).

(iii) \( \mathbb{D}_t^{\rho_3} \) and \( I_{a^+}^{1-\gamma} \) represent the \( \theta \)-R-L fractional integrals of order \( \rho_3 \) and \( 1 - \gamma \), respectively;

(iv) \( f, g : J \times C \times C \to \mathbb{R} \) are continuous and nonlinear functions on a Banach space \( C \);

(v) \( \theta \in \mathcal{C}(J, \mathbb{R}) \) are an increasing function with \( \theta'(x) \neq 0 \), for all \( x \in J \).

We pay attention to the topic of a novel operator with respect to another function, as it covers many fractional systems that are special cases for various values of \( \theta \). More precisely, the existence, uniqueness, and U-H stability of solutions to the system (1) are obtained in weighted spaces by using standard fixed point theorems (Banach-type and Schauder type) along with Arzelà–Ascoli’s theorem.

The content of this paper is organized as follows: Section 2 presents some required results and preliminaries about \( \theta \)-Hilfer FD. Our main results for the system (1) are addressed in Section 3. Some examples to explain the acquired results are given in Section 4. In the end, we epitomize our study in the Conclusion section.

2. Preliminaries

In this section, we recall the concept of advanced fractional calculus. Throughout the paper, we assume that \( J := (a, b] \subset \mathbb{R}, \) \( a < b \), \( \gamma = \rho_1 + \rho_2(1 - \rho_1), \) \( 0 < \rho_1 < 1, \) \( 0 \leq \rho_2 \leq 1, \) \( 0 \leq \rho_2 \leq 1, \) and \( \theta : J \to \mathbb{R} \) is an increasing linear function which satisfies \( \theta'(x) \neq 0 \), for all \( x \in J \). Let

\[
\mathcal{C} = \mathcal{C}(J, \mathbb{R}) = \left\{ \phi : J \to \mathbb{R}; \|\phi\|_{\infty} = \max_{x \in J}|\phi(x)| \right\}
\]
and
\[ C_{1-\gamma,\vartheta} = C_{1-\gamma,\vartheta}(\mathbb{J},\mathbb{R}) = \left\{ \phi : \mathbb{J} \to \mathbb{R}; \mathbb{D}^{\rho_1,\vartheta}_{\vartheta} \phi \in \mathcal{C}; \| \phi \|_{1-\gamma,\vartheta} = \left\| (\vartheta(x) - \vartheta(a))^{1-\gamma} \phi(x) \right\|_{\infty} \right\}. \]

where \( 0 \leq \gamma < 1 \). Obviously, \( \mathcal{C} \) and \( C_{1-\gamma,\vartheta} \) are Banach spaces under \( \| \phi \|_{\infty} \) and \( \| \phi \|_{1-\gamma,\vartheta} \), respectively. Hence the products \( \mathcal{C} \times \mathcal{C} \) and \( C_{1-\gamma,\vartheta} \times C_{1-\gamma,\vartheta} \) are also Banach spaces with norms
\[ \| (\phi_1, \phi_2) \|_{\infty} = \| \phi_1 \|_{\infty} + \| \phi_2 \|_{\infty} \]
and
\[ \| (\phi_1, \phi_2) \|_{1-\gamma,\vartheta} = \| \phi_1 \|_{1-\gamma,\vartheta} + \| \phi_2 \|_{1-\gamma,\vartheta} \]
respectively. Let \( z \in \mathbb{C} \) with \( \text{Re}(z) > 0 \). Then, the gamma function \( \Gamma(z) \) is defined by [37]
\[ \Gamma(z) = \int_{0}^{\infty} u^{z-1} e^{-u} du, \tag{2} \]
and let \( z_1, z_2 \in \mathbb{C} \) with \( \text{Re}(z_1), \text{Re}(z_2) > 0 \). Then, the beta function \( \mathcal{B}(z_1, z_2) \) is defined by [37]
\[ \mathcal{B}(z_1, z_2) = \int_{0}^{1} u^{z_1-1}(1-u)^{z_2-1} du. \tag{3} \]
Note that, beta function and gamma function have the following relation
\[ \mathcal{B}(z_1, z_2) = \frac{\Gamma(z_1)\Gamma(z_2)}{\Gamma(z_1 + z_2)}. \]

**Definition 1** ([2]). The \( \theta \)-R-L fractional integral of order \( \rho_1 > 0 \) for a function \( \varphi(x) \) is given by
\[ \mathbb{I}^{\rho_1}_{\vartheta,\varphi(x)} \varphi(x) = \frac{1}{\Gamma(\rho_1)} \int_{a}^{x} \vartheta(t)(\vartheta(x) - \vartheta(t))^{\rho_1-1} \varphi(t) dt, \]
where \( \Gamma(\cdot) \) is the gamma function defined by (2).

**Definition 2** ([16]). The \( \theta \)-Hilfer FD of a function \( \varphi(x) \) of order \( \rho_1 \) and type \( \rho_2 \) is defined by
\[ \mathbb{D}^{\rho_1,\rho_2}_{\vartheta,\varphi(x)} \varphi(x) = \mathbb{I}^{\rho_1}_{\vartheta,\varphi(x)} \mathbb{D}^{\rho_2}_{\vartheta,\varphi(x)} \varphi(x) = \mathbb{I}^{\rho_1\rho_2}_{\vartheta,\varphi(x)} \varphi(x), \]
where \( 0 < \rho_1 < 1, 0 \leq \rho_2 \leq 1, \) and \( x > a. \)

**Lemma 1** ([2,16]). Let \( \rho_1, \eta, \delta > 0 \). Then
1. \( \mathbb{I}^{\rho_1 \eta}_{\vartheta,\varphi(x)} \mathbb{I}^{\eta}_{\vartheta,\varphi(x)} \varphi(x) = \mathbb{I}^{\rho_1}_{\vartheta,\varphi(x)} \varphi(x) \).
2. \( \mathbb{I}^{\rho_1}_{\vartheta,\varphi(x)} (\vartheta(x) - \vartheta(a))^{\delta-1} = \frac{\Gamma(\delta)}{\Gamma(\rho_1 + \delta)} (\vartheta(x) - \vartheta(a))^{\rho_1 + \delta-1}. \)

We note also that \( \mathbb{D}^{\rho_1\rho_2}_{\vartheta,\varphi(x)} (\vartheta(x) - \vartheta(a))^{\gamma-1} = 0, \) where \( \gamma = \rho_1 + \rho_2(1-\rho_1). \)

**Lemma 2** ([16]). Let \( \varphi \in \mathcal{C}, \rho_1 \in (0,1) \) and \( \rho_2 \in [0,1], \) then
\[ \left( \mathbb{I}^{\rho_1}_{\vartheta,\varphi(x)} \mathbb{D}^{\rho_1,\rho_2}_{\vartheta,\varphi(x)} \varphi(x) \right)(x) = \varphi(x) - \frac{(\vartheta(x) - \vartheta(a))^{\gamma-1}}{\Gamma(\gamma)} \lim_{x \to a} \left( \mathbb{I}^{\rho_1,\rho_2}_{\vartheta,\varphi(x)} (\vartheta(x) - \vartheta(a))^{\rho_1 + \rho_2(1-\rho_1)} \varphi(x) \right), \]
where \( \varphi^{[n-k]}(x) = \left( \frac{d}{d\vartheta} \right)^{[n-k]} \varphi(x) \) and \( \gamma = \rho_1 + \rho_2(1-\rho_1). \)

**Theorem 1** ([38] (Banach’s Theorem)). Let \( \Omega \neq \emptyset \) be a closed subset of a Banach space \( \mathcal{X}. \) Then any contraction mapping \( \mathcal{T} : \Omega \to \Omega \) has a unique fixed point.
Theorem 2 ([39] (Schauder’s Theorem)). Let $\Omega$ be a non-empty closed and convex subset of a Banach space $\mathcal{X}$. If $T : \Omega \to \Omega$ is a continuous such that $T(\Omega)$ is a relatively compact subset of $\mathcal{X}$, then $T$ has at least one fixed point in $\Omega$.

3. Main Results

In this section, we establish the existence, uniqueness, and U-H stability results for the system (1). To obtain our principle results, we consider the following assumptions:

$(\text{Hy}_1)$ $f, g : \mathbb{I} \times \mathbb{C} \times \mathbb{C} \to \mathbb{R}$ are continuous such that for each $(\varkappa, \varphi, \omega), (\zeta, \varphi^*, \omega^*) \in \mathbb{I} \times \mathbb{C} \times \mathbb{C}$ there exist $\kappa_f, \kappa_g, \kappa_f, \kappa_g > 0$ with

$$|f(\varkappa, \varphi, \omega) - f(\zeta, \varphi^*, \omega^*)| \leq \kappa_f|\varphi - \varphi^*| + \kappa_f|\omega - \omega^*|,$$

$$|g(\varkappa, \varphi, \omega) - g(\zeta, \varphi^*, \omega^*)| \leq \kappa_g|\varphi - \varphi^*| + \kappa_g|\omega - \omega^*|.$$  

$(\text{Hy}_2)$ $f, g : \mathbb{I} \times \mathbb{C} \times \mathbb{C} \to \mathbb{R}$ are completely continuous such that for each $(\varkappa, \varphi, \omega) \in \mathbb{I} \times \mathbb{C} \times \mathbb{C}$ there exist $\varphi_f, \varphi_g, \overline{\varphi}_f, \overline{\varphi}_g > 0$ with

$$|f(\varkappa, \varphi, \omega)| \leq \varphi_f|\varphi| + \overline{\varphi}_f|\omega|,$$

$$|g(\varkappa, \varphi, \omega)| \leq \varphi_g|\varphi| + \overline{\varphi}_g|\omega|.$$  

Theorem 3. Let $0 < \rho_1 < 1, 0 \leq \rho_2 \leq 1$ and $\gamma = \rho_1 + \rho_2(1 - \rho_1)$. If $(\vartheta, \omega) \in C_{1-\gamma, a} \times C_{1-\gamma, a}$ satisfies

$$\begin{align*}
\mathbb{D}^\rho_1 \varphi_2^\rho_2 a^+, \vartheta(\varkappa)\varphi(\varkappa) = h_1(\varkappa), & \quad \varkappa \in \mathbb{I}, \\
\mathbb{D}^\rho_1 \varphi_2^\rho_2 \omega(\varkappa) = h_2(\varkappa), & \quad \varkappa \in \mathbb{I},
\end{align*}$$

then

$$\begin{align*}
v(\varkappa) &= \left(\frac{\vartheta(\varkappa) - \vartheta(a)}{\Gamma(\gamma)}\right)^{-1} \frac{\mathbb{I}^{1-\gamma)}_{a^+, \vartheta(\varkappa)} v(a)}{\Gamma(\gamma)} + \varphi_1^\rho_1 a^+, \vartheta(\varkappa) h_1(\varkappa), \quad \varkappa \in \mathbb{I}, \\
\omega(\varkappa) &= \left(\frac{\vartheta(\varkappa) - \vartheta(a)}{\Gamma(\gamma)}\right)^{-1} \frac{\mathbb{I}^{1-\gamma)}_{a^+, \vartheta(\varkappa)} \omega(a)}{\Gamma(\gamma)} + \varphi_1^\rho_1 a^+, \vartheta(\varkappa) h_2(\varkappa), \quad \varkappa \in \mathbb{I}.
\end{align*}$$

Proof. Let

$$\begin{align*}
\mathbb{D}^\rho_1 \varphi_2^\rho_2 a^+, \vartheta(\varkappa)\varphi(\varkappa) = h_1(\varkappa), & \quad \varkappa \in \mathbb{I}, \\
\mathbb{I}^{1-\gamma)}_{a^+, \vartheta(\varkappa)} v(\varkappa) &= v(a), \quad \varkappa \in \mathbb{I}.
\end{align*}$$

Applying the integral $\mathbb{I}^{\rho_1)}_{a^+, \vartheta(\varkappa)}$ on the equation $\mathbb{D}^\rho_1 \varphi_2^\rho_2 a^+, \vartheta(\varkappa)\varphi(\varkappa) = h_1(\varkappa)$ and using Lemma 2, we have

$$v(\varkappa) = \left(\frac{\vartheta(\varkappa) - \vartheta(a)}{\Gamma(\gamma)}\right)^{-1} \mathbb{I}^{1-\gamma)}_{a^+, \vartheta(\varkappa)}(1 - \rho_2)(1 - \rho_1) v(a) = \varphi_1^\rho_1 a^+, \vartheta(\varkappa) h_1(\varkappa),$$

which implies

$$v(\varkappa) = \left(\frac{\vartheta(\varkappa) - \vartheta(a)}{\Gamma(\gamma)}\right)^{-1} \mathbb{I}^{1-\gamma)}_{a^+, \vartheta(\varkappa)} v(a) + \varphi_1^\rho_1 a^+, \vartheta(\varkappa) h_1(\varkappa) = \frac{\vartheta(\varkappa) - \vartheta(a)}{\Gamma(\gamma)} v(a) + \varphi_1^\rho_1 a^+, \vartheta(\varkappa) h_1(\varkappa).$$

Similarly,

$$\omega(\varkappa) = \left(\frac{\vartheta(\varkappa) - \vartheta(a)}{\Gamma(\gamma)}\right)^{-1} \omega(a) + \varphi_1^\rho_1 a^+, \vartheta(\varkappa) h_2(\varkappa).$$
3.1. Existence Result

**Theorem 4.** Assume that \((H_{y_1})\) and \((H_{y_2})\) hold. If \(\mathcal{B} := \frac{\Lambda}{2}(\theta(b) - \theta(a))^{p_1 + p_3} < 1\), then system \((1)\) has at least one solution, where \(\Lambda := \left(\frac{\varphi_f + \varphi_g}{\Gamma(p_1)} + \frac{\varphi_f}{\Gamma(p_1 + p_3)}\right)^{\mathcal{B}(\gamma, p_1 + p_3)},\) and \(\mathcal{B}(\cdot, \cdot)\) is a beta function defined by \((3)\).

**Proof.** Consider a closed ball

\[
S_\beta = \left\{(v, \omega) \in C_{1-\delta, \delta} \times C_{1-\delta, \delta} : \|v\|_{C_{1-\delta, \delta}} \leq \beta, \|\omega\|_{C_{1-\delta, \delta}} \leq \beta, \|\omega\|_{C_{1-\delta, \delta}} \leq \frac{\beta}{2}\right\},
\]

where \(\beta \geq \frac{\mathcal{B}}{1 - \mathcal{B}}\) with \(\mathcal{B} := \frac{|v_1| + |w_1|}{\Gamma(\gamma)}\). In view of Theorem 3, we transform system \((1)\) into a fixed point system. Define the operator \(\Pi = (\Pi_1, \Pi_2)\) on \(S_\beta\), where

\[
\Pi_1(v(\omega), \omega(\omega)) = \frac{(\theta(\omega) - \theta(\omega))^{\gamma-1}}{\Gamma(\gamma)}[v_u + \frac{\varphi_f}{\Gamma(\gamma)}f(\omega, v(\omega), \varphi_{p_3}^3) \omega(\omega)] - \frac{\mathcal{B}^{\gamma-1}}{\Gamma(\gamma)}[v_u + \frac{\varphi_f}{\Gamma(\gamma)}f(\omega, v(\omega), \varphi_{p_3}^3) \omega(\omega)],
\]

\[
\Pi_2(\omega(\omega), v(\omega)) = \frac{(\theta(\omega) - \theta(\omega))^{\gamma-1}}{\Gamma(\gamma)}[\omega_u + \frac{\varphi_f}{\Gamma(\gamma)}f(\omega, v(\omega), \varphi_{p_3}^3) v(\omega)] - \frac{\mathcal{B}^{\gamma-1}}{\Gamma(\gamma)}[\omega_u + \frac{\varphi_f}{\Gamma(\gamma)}f(\omega, v(\omega), \varphi_{p_3}^3) v(\omega)].
\]

(4)

For any \((v, \omega) \in S_\beta\), we have

\[
\|\Pi(v, \omega)\|_{C_{1-\delta, \delta}} \leq \|\Pi_1(v, \omega)\|_{C_{1-\delta, \delta}} + \|\Pi_2(\omega, v)\|_{C_{1-\delta, \delta}}.
\]

(5)

From \((4)\), we obtain

\[
\|\Pi_1(v(\omega), \omega(\omega))\| \leq \frac{(\theta(\omega) - \theta(\omega))^{\gamma-1}}{\Gamma(\gamma)}[v_u + \frac{\varphi_f}{\Gamma(\gamma)}f(\omega, v(\omega), \varphi_{p_3}^3) \omega(\omega)] + \frac{\mathcal{B}^{\gamma-1}}{\Gamma(\gamma)}[v_u + \frac{\varphi_f}{\Gamma(\gamma)}f(\omega, v(\omega), \varphi_{p_3}^3) \omega(\omega)]
\]

\[
\leq \frac{(\theta(\omega) - \theta(\omega))^{\gamma-1}}{\Gamma(\gamma)}[v_u + \varphi_f(\varphi_{p_3}^3) \omega(\omega)] + \frac{\mathcal{B}^{\gamma-1}}{\Gamma(\gamma)}[v_u + \varphi_f(\varphi_{p_3}^3) \omega(\omega)]
\]

\[
\leq \frac{(\theta(\omega) - \theta(\omega))^{\gamma-1}}{\Gamma(\gamma)}[v_u + \varphi_f(\varphi_{p_3}^3) \omega(\omega)] + \frac{\mathcal{B}^{\gamma-1}}{\Gamma(\gamma)}[v_u + \varphi_f(\varphi_{p_3}^3) \omega(\omega)]
\]

which implies

\[
\|\Pi_1(v, \omega)\|_{C_{1-\delta, \delta}} \leq \frac{|v_u|}{\Gamma(\gamma)} + \frac{\varphi_f}{\Gamma(\gamma)}(\theta(b) - \theta(a))^{p_1 + p_3}
\]

\[
+ \frac{\varphi_f}{\Gamma(\gamma)}(\theta(b) - \theta(a))^{p_1 + p_3}
\]

\[
\leq \frac{|v_u|}{\Gamma(\gamma)} + \frac{\varphi_f}{\Gamma(\gamma)}(\theta(b) - \theta(a))^{p_1 + p_3}.
\]

(6)

Similarly, we obtain

\[
\|\Pi_2(\omega, v)\|_{C_{1-\delta, \delta}} \leq \frac{|\omega_u|}{\Gamma(\gamma)} + \frac{\varphi_f}{\Gamma(\gamma)}(\theta(b) - \theta(a))^{p_1 + p_3}.
\]

(7)
In Equations (6) and (7) along with (5), give
\[
\left\| \Pi(v, \omega) \right\|_{C_{1, \gamma, \theta}} \leq \frac{|v_n| + |\omega_n|}{\Gamma(\gamma)} + \frac{\beta}{2} \Lambda(\theta(b) - \theta(a))^{\rho_1 + \rho_3} \\
\leq \beta S_1 + \beta S_1 \leq \beta(1 - S_1) + \beta S_1 = \beta. \tag{8}
\]

Hence \(\Pi(S_\beta) \subset S_\beta\).

Now, we prove that \(\Pi\) is continuous and compact. Let a sequence \((v_n, \omega_n)\) in \(S_\beta\) such that \((v_n, \omega_n) \to (v, \omega)\) in \(S_\beta\) as \(n \to \infty\), so, we have
\[
\left\| \Pi(v_n, \omega_n)(x) - \Pi(v, \omega)(x) \right\|_{C_{1, \gamma, \theta}} \\
= \left\| \Pi \big( (v_n, \omega_n)(x) + \Pi_2(\omega_n, v_n)(x) - \Pi_1(v_n, \omega_n)(x) - \Pi_2(\omega, v)(x) \big) \right\|_{C_{1, \gamma, \theta}} \\
\leq \left\| \Pi \big( (v_n, \omega_n)(x) - \Pi_1(v, \omega)(x) \big) \right\|_{C_{1, \gamma, \theta}} + \left\| \Pi_2(\omega_n, v_n) - \Pi_2(\omega, v) \right\|_{C_{1, \gamma, \theta}} \\
\leq (\theta(x) - \theta(a))^{1 - \gamma} \left\| \Pi^1_{a, \theta}(\omega_n)(x) - \Pi^1_{a, \theta}(\omega)(x) \right\|_{C_{1, \gamma, \theta}} \\
+ (\theta(x) - \theta(a))^{1 - \gamma} \left\| \Pi^3_{a, \theta}(\omega_n)(x) - \Pi^3_{a, \theta}(\omega)(x) \right\|_{C_{1, \gamma, \theta}} \\
\leq (\theta(x) - \theta(a))^{1 - \gamma} \left( \kappa_f \left\| v_n - v \right\|_{C_{1, \gamma, \theta}} \right) \left( \theta(x) - \theta(a) \right)^{\gamma - 1} \\
+ \kappa_\beta \left\| \omega_n - \omega \right\|_{C_{1, \gamma, \theta}} \left( \theta(x) - \theta(a) \right)^{\gamma - 1} \\
+ \kappa_\beta \left\| v_n - v \right\|_{C_{1, \gamma, \theta}} \left( \theta(x) - \theta(a) \right)^{\gamma - 1} \\
\leq \left( \kappa_f \frac{\Gamma(\gamma)(\theta(b) - \theta(a))^{\rho_1}}{\Gamma(\rho_1 + \gamma)} + \kappa_\beta \frac{\Gamma(\gamma)(\theta(b) - \theta(a))^{\rho_1 + \rho_3}}{\Gamma(\rho_1 + \rho_3 + \gamma)} \right) \left\| v_n - v \right\|_{C_{1, \gamma, \theta}} \\
+ \frac{\kappa_\beta \Gamma(\gamma)(\theta(b) - \theta(a))^{\rho_1}}{\Gamma(\rho_1 + \gamma)} \left\| \omega_n - \omega \right\|_{C_{1, \gamma, \theta}} \\
+ \frac{\kappa_\beta \Gamma(\gamma)(\theta(b) - \theta(a))^{\rho_1 + \rho_3}}{\Gamma(\rho_1 + \rho_3 + \gamma)} \left\| v_n - v \right\|_{C_{1, \gamma, \theta}}.
\]

This implies that \(\left\| \Pi(v_n, \omega_n) - \Pi(v, \omega) \right\|_{C_{1, \gamma, \theta}} \to 0\) as \(n \to \infty\). So, \(\Pi\) is continuous. Moreover, \(\Pi\) is bounded on \(S_\beta\). Therefore, \(\Pi\) is uniformly bounded on \(S_\beta\).

To prove that \(\Pi\) is equicontinuous, we take \(x_1, x_2 \in J\) with \(x_1 < x_2\) and for any \((v, \omega) \in S_\beta\), we obtain
\[
\left\| \Pi(v, \omega)(x_2) - \Pi(v, \omega)(x_1) \right\| \\
\leq \left\| \Pi \big( (v, \omega)(x_2) - \Pi_1(v, \omega)(x_1) \big) \right\| + \left\| \Pi_2(v, \omega)(x_2) - \Pi_2(v, \omega)(x_1) \right\| \\
\leq \left( \frac{\Gamma(\gamma)(\theta(b) - \theta(a))^{\rho_1}}{\Gamma(\rho_1 + \gamma)} \left\| v_n - v \right\|_{C_{1, \gamma, \theta}} + \frac{\Gamma(\gamma)(\theta(b) - \theta(a))^{\rho_1 + \rho_3}}{\Gamma(\rho_1 + \rho_3 + \gamma)} \left\| \omega_n - \omega \right\|_{C_{1, \gamma, \theta}} \right) \left| x_2 - x_1 \right| \\
+ \frac{\Gamma(\gamma)(\theta(b) - \theta(a))^{\rho_1}}{\Gamma(\rho_1 + \gamma)} \left\| v_n - v \right\|_{C_{1, \gamma, \theta}} \left| x_2 - x_1 \right| \\
+ \frac{\Gamma(\gamma)(\theta(b) - \theta(a))^{\rho_1 + \rho_3}}{\Gamma(\rho_1 + \rho_3 + \gamma)} \left\| \omega_n - \omega \right\|_{C_{1, \gamma, \theta}} \left| x_2 - x_1 \right|.
\]

Since \(f(\cdot, \omega(\cdot), \Pi^1_{a, \theta}(\omega(\cdot)))\) and \(g(\cdot, \omega(\cdot), \Pi^3_{a, \theta}(\omega(\cdot)))\) are continuous on \(J\). Therefore, there exist \(\xi_f, \xi_\beta \in \mathbb{R}\) such that
\[
\left| f(\cdot, \omega(\cdot), \Pi^3_{a, \theta}(\omega(\cdot))) \right| \leq \xi_f, \quad \text{and} \quad \left| g(\cdot, \omega(\cdot), \Pi^3_{a, \theta}(\omega(\cdot))) \right| \leq \xi_\beta.
\]
Hence
\[
\left| \mathcal{T}_{a,b}(\xi_2, v) - \mathcal{T}_{a,b}(\xi_1, v) \right| \\
\leq \frac{1}{\Gamma(\rho_1 + 1)} \int_{\Omega} \left| \left( \theta (\xi_1) - \theta (t) \right)^{\rho_1 - 1} - \left( \theta (\xi_2) - \theta (t) \right)^{\rho_1 - 1} \right| f(t, v(t), \mathcal{P}_{a,b}(\theta(t)) \omega(t)) dt \\
+ \frac{1}{\Gamma(\rho_1 + 1)} \int_{\Omega} \left| \left( \theta (\xi_1) - \theta (t) \right)^{\rho_1 - 1} - \left( \theta (\xi_2) - \theta (t) \right)^{\rho_1 - 1} \right| f(t, v(t), \mathcal{P}_{a,b}(\theta(t)) \omega(t)) dt \\
\leq \frac{\xi_f}{\Gamma(\rho_1 + 1)} \left| \left( \theta (\xi_1) - \theta (a) \right)^{\rho_1} - \left( \theta (\xi_2) - \theta (a) \right)^{\rho_1} \right| \\
+ \frac{\xi_f}{\Gamma(\rho_1 + 1)} \left| \left( \theta (\xi_1) - \theta (a) \right)^{\rho_1} - \left( \theta (\xi_2) - \theta (a) \right)^{\rho_1} \right| \\
= \frac{2 \xi_f}{\Gamma(\rho_1 + 1)} \left| \theta (\xi_2) - \theta (\xi_1) \right|^{\rho_1}. \tag{10}
\]

Similarly,
\[
\left| \mathcal{G}_{a,b}(\xi_2, \omega) - \mathcal{G}_{a,b}(\xi_1, \omega) \right| \\
\leq \frac{2 \xi_g}{\Gamma(\rho_1 + 1)} \left| \theta (\xi_2) - \theta (\xi_1) \right|^{\rho_1}. \tag{11}
\]

Substituting (10) and (11) into (9), we obtain
\[
\left| \Pi(v, \omega)(\xi_2) - \Pi(v, \omega)(\xi_1) \right| \\
\leq \frac{(\theta (\xi_2) - \theta (a))^{\gamma - 1} - (\theta (\xi_1) - \theta (a))^{\gamma - 1}}{\Gamma(\gamma)} (v_a + \omega_a) \\
+ \frac{2 \xi_f + \xi_g}{\Gamma(\rho_1 + 1)} \left| \theta (\xi_2) - \theta (\xi_1) \right|^{\rho_1}.
\]

Thus, $\left| \Pi(v, \omega)(\xi_2) - \Pi(v, \omega)(\xi_1) \right| \to 0$, as $\xi_1 \to \xi_2$. Thus, $\Pi$ is relatively compact on $S_{b}$. It follows that $\Pi$ is completely continuous due to the Arzela–Ascoli theorem. An application Theorem 2 shows that system (1) has at least one solution. □

3.2. Uniqueness Result

**Theorem 5.** Assume that (H$y_1$) holds. If $\max_{x \in \mathbb{J}} \{\xi_1, \xi_2\} = \xi < 1$, then the system (1) has a unique solution on $\mathbb{J}$, where

\[
\xi_1 : = \frac{(\theta(b) - \theta(a))^{\rho_1}}{\Gamma(\rho_1 + 1)} \xi_f + \frac{(\theta(b) - \theta(a))^{\rho_1 + \rho_3}}{\Gamma(\rho_1 + \rho_3 + 1)} \xi_g, \\
\xi_2 : = \frac{(\theta(b) - \theta(a))^{\rho_1}}{\Gamma(\rho_1 + 1)} \xi_f + \frac{(\theta(b) - \theta(a))^{\rho_1 + \rho_3}}{\Gamma(\rho_1 + \rho_3 + 1)} \xi_g.
\]

**Proof.** To demonstrate the desired result, we show that $\Pi$ is a contraction. For each $x \in \mathbb{J}$ and $(v, \omega), (v^*, \omega^*) \in S_{b}$, we have

\[
\left| \Pi(v, \omega)(x) - \Pi(v^*, \omega^*)(x) \right| \\
\leq \frac{2 \xi_f + \xi_g}{\Gamma(\rho_1 + 1)} \left| \theta(x_2) - \theta(x_1) \right|^{\rho_1},
\]

where $x_i \in \mathbb{J}$. □
\[ \|\Pi(v, \omega) - \Pi(v^*, \omega^*)\|_{C_{1-\gamma, \theta}} \leq \|\Pi_1(v, \omega) - \Pi_1(v^*, \omega^*)\|_{C_{1-\gamma, \theta}} + \|\Pi_2(\omega, v) - \Pi_2(\omega^*, v^*)\|_{C_{1-\gamma, \theta}} \]
\[ \leq \max_{\theta \in \mathbb{J}} \left\{ \frac{(\theta(b) - \theta(a))^p_1}{1 + p_1 + 1} \phi_1\|v - v^*\|_{C_{1-\gamma, \theta}} + \frac{(\theta(b) - \theta(a))^{p_1 + p_3}}{1 + p_1 + p_3 + 1} \phi_2\|\omega - \omega^*\|_{C_{1-\gamma, \theta}} \right\} \]
\[ \leq \zeta_1\|v - v^*\|_{C_{1-\gamma, \theta}} + \zeta_2\|\omega - \omega^*\|_{C_{1-\gamma, \theta}}, \]

which implies
\[ \|\Pi(v, \omega) - \Pi(v^*, \omega^*)\|_{C_{1-\gamma, \theta}} \leq \zeta \|(v, \omega) - (v^*, \omega^*)\|_{C_{1-\gamma, \theta}}. \]

Since \( \zeta < 1 \), \( \Pi \) is a contraction map. Thus, a unique solution exists on \( \mathbb{J} \) for system (1) in view of Theorem 1, and this completes the proof. \( \square \)

3.3. Special Cases

In this subsection, we present some special cases according to our previous findings:

Case 1: If \( \theta(x) = x \), then the system (1) is reduced to a Hilfer type coupled system of FIDE of the form

\[ \begin{align*}
\mathbb{D}_{a^+, x}^{p_1, p_2} v(x) &= f(x, v(x), \mathbb{P}_{a^+, x}^{p_1} \omega(x)), \quad x \in \mathbb{J}, \\
\mathbb{D}_{a^+, x}^{\gamma, p_1} \omega(x) &= g(x, \omega(x), \mathbb{P}_{a^+, x}^{p_1} v(x)), \quad x \in \mathbb{J},
\end{align*} \tag{12} \]

where \( \mathbb{D}_{a^+, x}^{p_1, p_2} \) and \( \mathbb{D}_{a^+, x}^{\gamma, p_1} \) represent the Hilfer FD of order \( (p_1, p_2) \) and the R-L fractional integral of order \( 1 - \gamma \), respectively (see [5]). Therefore, the results in Theorems 4 and 5 can be presented by

\[ \left\{ \begin{array}{l}
v(x) = \frac{(x-a)^{1-\gamma}}{1(\gamma)} v_a + p_{a^+, x} f(x, v(x), \mathbb{P}_{a^+, x}^{p_1} \omega(x)), \quad x \in \mathbb{J}, \\
\omega(x) = \frac{(x-a)^{1-\gamma}}{1(\gamma)} \omega_a + p_{a^+, x} g(x, \omega(x), \mathbb{P}_{a^+, x}^{p_1} v(x)), \quad x \in \mathbb{J},
\end{array} \right. \]

Let \( \mathcal{C}_{1-\gamma} = \{ \phi : \mathbb{J} \to \mathbb{R}; \mathbb{D}_{a^+, x}^{p_1, p_2} \phi \in \mathcal{C}; \phi|_{1-\gamma} = \| (x-a)^{1-\gamma} \phi(x) \|_{\infty}, 0 \leq \gamma < 1. \]

Then the next two corollaries are a special case of the Theorems 4 and 5.
Corollary 1. Assume that (Hy₁) and (Hy₂) are satisfied. If \( \frac{1}{\Lambda} (b - a)^{p_1 + p_3} < 1 \), then system (12) has at least one solution \((v, \omega)\) ∈ \(C_{1-\gamma} \times C_{1-\gamma}\), where \(\Lambda\) as in Theorem 4.

Corollary 2. Assume that (Hy₁) and (Hy₂) are satisfied. If \(\max_{(\xi^*, \zeta^*)} (\xi^*, \zeta^*) < 1\), then the system (12) has a unique solution \((v, \omega)\) ∈ \(C_{1-\gamma} \times C_{1-\gamma}\), where

\[
\xi^*_1 = \frac{(b - a)^{p_1}}{\Gamma(p_1 + 1)} \kappa f + \frac{(b - a)^{p_1 + p_3}}{\Gamma(p_1 + p_3 + 1)} \varphi g, \\
\xi^*_2 = \frac{(b - a)^{p_1}}{\Gamma(p_1 + 1)} \kappa g + \frac{(b - a)^{p_1 + p_3}}{\Gamma(p_1 + p_3 + 1)} \varphi f.
\]

Case 2: Let \(a > 0\), and \(\theta(\omega) = \log \omega\), then the system (1) is reduced to a Hilfer–Hadamard type coupled system of FIDE of the form

\[
\begin{align*}
\mathbb{D}^{\alpha, q}_{a^+, \log \omega} v(\omega) &= f(\omega, v(\omega), \rho^a_{\alpha^+, \log \omega} \omega(\omega)), \quad \omega \in \mathbb{J}, \\
\mathbb{D}^{\alpha, q}_{a^+, \log \omega} \omega(\omega) &= g(\omega, \omega(\omega), \rho^a_{\alpha^+, \log \omega} v(\omega)), \quad \omega \in \mathbb{J}, \\
\end{align*}
\]

where \(\mathbb{D}^{\alpha, q}_{a^+, \log \omega}\) and \(\mathbb{D}^{\alpha, q}_{a^+, \log \omega}\) represent the Hilfer–Hadamard FD of order \((p_1, p_2)\) and the Hadamard fractional integral of order \(1 - \gamma\), respectively, (see [40,41]). Consequently, the results in Theorems 4 and 5 can be offered by

\[
\begin{align*}
v(\omega) &= \left(\frac{\log \omega}{1(\gamma)}\right)^{-1} v_a + \rho^{p_1}_{a^+, \log \omega} f(\omega, v(\omega), \rho^a_{\alpha^+, \log \omega} \omega(\omega)), \quad \omega \in \mathbb{J}, \\
\omega(\omega) &= \left(\frac{\log \omega}{1(\gamma)}\right)^{-1} \omega_a + \rho^{p_1}_{a^+, \log \omega} g(\omega, \omega(\omega), \rho^a_{\alpha^+, \log \omega} v(\omega)), \quad \omega \in \mathbb{J}.
\end{align*}
\]

Let

\[C_{1-\gamma, \log \omega} = \left\{ \phi : \mathbb{J} \to \mathbb{R} ; \mathbb{D}^{\alpha, q}_{a^+, \log \omega} \phi \in \mathcal{C} ; \| \phi \|_{1-\gamma, \log \omega} = \|\left(\frac{\log \omega}{a}\right)^{1-\gamma} \phi(\omega)\|_{\infty} \right\}, 0 \leq \gamma < 1.
\]

Then the following two results are a special case of the Theorems 4 and 5.

Corollary 3. Assume that (Hy₁) and (Hy₂) hold. If \(\frac{1}{\Lambda} (\log \frac{b}{a})^{p_1 + p_3} < 1\), then system (13) has at least one solution \((v, \omega)\) ∈ \(C_{1-\gamma, \log \omega} \times C_{1-\gamma, \log \omega}\), where \(\Lambda\) as in Theorem 4.

Corollary 4. Assume that (Hy₁) and (Hy₂) are satisfied. If \(\max_{(\xi^*_3, \xi^*_4)} (\xi^*_3, \xi^*_4) < \zeta\), then the system (13) has a unique solution in \(C_{1-\gamma, \log \omega} \times C_{1-\gamma, \log \omega}\), where

\[
\begin{align*}
\xi^*_3 &= \frac{(\log \frac{b}{a})^{p_1}}{\Gamma(p_1 + 1)} \kappa f + \frac{(\log \frac{b}{a})^{p_1 + p_3}}{\Gamma(p_1 + p_3 + 1)} \varphi g, \\
\xi^*_4 &= \frac{(\log \frac{b}{a})^{p_1 + p_3}}{\Gamma(p_1 + p_3 + 1)} \kappa g + \frac{(\log \frac{b}{a})^{p_1}}{\Gamma(p_1 + 1)} \varphi f.
\end{align*}
\]

Case 3: If \(\theta(\omega) = \omega^p\), for \(p > 0\), then the system (1) is reduced to a Hilfer–Katugumpola type coupled system of FIDE of the form

\[
\begin{align*}
\mathbb{D}^{\alpha, q}_{a^+, \omega} v(\omega) &= f(\omega, v(\omega), \rho^a_{\alpha^+, \omega} \omega(\omega)), \quad \omega \in \mathbb{J}, \\
\mathbb{D}^{\alpha, q}_{a^+, \omega} \omega(\omega) &= g(\omega, \omega(\omega), \rho^a_{\alpha^+, \omega} v(\omega)), \quad \omega \in \mathbb{J}, \\
\end{align*}
\]

where \(\mathbb{D}^{\alpha, q}_{a^+, \omega}\) and \(\mathbb{D}^{\alpha, q}_{a^+, \omega}\) represent the Hilfer–Katugumpola FD of order \((p_1, p_2)\) and the fractional integral of order \(1 - \gamma\), respectively.
where $D_{a^+}^{\rho_1,\rho_2}$ and $I_{a^+}^{1-\gamma}$ represent the Hilfer–Katugampola FD of order $(\rho_1, \rho_2)$ and the Katugampola fractional integral of order $1 - \gamma$, respectively, (see [42,43]). So, the results in Theorems 4 and 5 can be given by

$$
\begin{align*}
\frac{D_{a^+}^{\rho_1,\rho_2}}{\Gamma(\gamma)} (x, \nu(x), \nu(x), \nu(x)) = \frac{D_{a^+}^{\rho_1,\rho_2}}{\Gamma(\gamma)} (x, \nu(x), \nu(x), \nu(x)) \\
\phi(x) = \frac{D_{a^+}^{\rho_1,\rho_2}}{\Gamma(\gamma)} (x, \nu(x), \nu(x), \nu(x)) \\
(\nu(x)) = \frac{D_{a^+}^{\rho_1,\rho_2}}{\Gamma(\gamma)} (x, \nu(x), \nu(x), \nu(x))
\end{align*}
$$

Let

$$
C_{1-\gamma,\rho} = \left\{ \phi : J \to \mathbb{R} ; D_{a^+}^{\rho_1,\rho_2} \phi \in C ; \| \phi \|_{1-\gamma,\rho} = \left\| (\nu(x) - a^x)^{1-\gamma} \phi(x) \right\|_{\infty} \right\}, 0 \leq \gamma < 1.
$$

Then the following results are a special case of the Theorems 4 and 5.

**Corollary 5.** Assume that (H1) and (H2) hold. If $\frac{1}{2} (b^x - a^x)^{\rho_1 + \rho_3} < 1$, then system (14) has at least one solution $(\nu, \omega) \in C_{1-\gamma,\rho} \times C_{1-\gamma,\rho}$, where $\Lambda$ as in Theorem 4.

**Corollary 6.** Assume that (H1) and (H2) are satisfied. If $\max_{x \in J} \{ \xi_5, \xi_6 \} = \tilde{\xi} < 1$, then the system (14) has a unique solution in $C_{1-\gamma,\rho} \times C_{1-\gamma,\rho}$, where

$$
\begin{align*}
\xi_5 & : \frac{(b^x - a^x)^{\rho_1} \Gamma(\rho_1 + 1) \pi_f^x}{\Gamma(\rho_1 + 1) \pi_f^x} + \frac{(b^x - a^x)^{\rho_1 + \rho_3} \Gamma(\rho_1 + \rho_3 + 1) \pi_g^x}{\Gamma(\rho_1 + \rho_3 + 1) \pi_g^x}, \\
\xi_6 & : \frac{(b^x - a^x)^{\rho_1 + \rho_3} \pi_f^x}{\Gamma(\rho_1 + \rho_3 + 1) \pi_f^x} + \frac{(b^x - a^x)^{\rho_1} \Gamma(\rho_1 + 1) \pi_g^x}{\Gamma(\rho_1 + 1) \pi_g^x}.
\end{align*}
$$

**Remark 1.** Many other special cases of function $\theta$ and parameter $\rho_2$ generate similar problems and systems some of them addressed in the literature, to name a few, the $\theta$-Hilfer type system (1) reduces to

1. The R-L type system, for $\theta(x) = x$, and $\rho_2 = 0$ (see [2]);
2. The Caputo type system, for $\theta(x) = x$, and $\rho_2 = 1$ (see [2]);
3. The Hilfer type system, for $\theta(x) = x$ (see [5]);
4. The Katugampola type system, for $\theta(x) = x$, and $\rho_2 = 0$ (see [42]);
5. The Caputo–Katugampola type system, for $\theta(x) = x$, and $\rho_2 = 1$ (see [44]);
6. The Hilfer–Katugampola type system, for $\theta(x) = x$ (see [43]);
7. The Hadamard type system, for $\theta(x) = \log x$, and $\rho_2 = 0$ (see [40]);
8. The Caputo–Hadamard type system, for $\theta(x) = \log x$, and $\rho_2 = 1$ (see [45]);
9. The Hilfer–Hadamard type system, for $\theta(x) = \log x$ (see [41]).

3.4. U-H Stability Analysis

In this subsection, we discuss the U-H Stability of the considered system.

**Definition 3.** System (1) is said to be U-H stable if there exists a constant $Y_{1,2} = \max\{Y_1, Y_2\} > 0$ ($Y_1, Y_2 > 0$) such that for each $\epsilon = \max\{\epsilon_1, \epsilon_2\}$, where $\epsilon_1, \epsilon_2 > 0$, and every solution $(\nu, \omega) \in C_{1-\gamma,\rho} \times C_{1-\gamma,\rho}$ of the inequalities

$$
\begin{align*}
\left| D_{a^+}^{\rho_1,\rho_2} (\nu(x)) - f(x, \nu(x), \nu(x), \nu(x)) \right| & \leq \epsilon_1, \quad x \in J, \\
\left| D_{a^+}^{\rho_1,\rho_2} (\omega(x)) - g(x, \omega(x), \omega(x), \omega(x)) \right| & \leq \epsilon_2, \quad x \in J,
\end{align*}
$$

there exists a solution $(\nu, \omega) \in C_{1-\gamma,\rho} \times C_{1-\gamma,\rho}$ of system (1) which satisfies

$$
\| (\nu, \omega) \|_{C_{1-\gamma,\rho}} \leq Y_{1,2}\epsilon.
$$
Remark 2. \((\tilde{\nu}, \tilde{\omega}) \in C_{1-\gamma, \theta} \times C_{1-\gamma, \theta}\) satisfies (15) if and only if there exist functions \(\sigma_1, \sigma_2 \in C_{1-\gamma, \theta}\) such that:

(i) \(|\sigma_1(\chi)| \leq \varepsilon_1\), and \(|\sigma_2(\chi)| \leq \varepsilon_2\), \(\chi \in \mathbb{J}\);

(ii) For all \(\chi \in \mathbb{J}\),

\[
\begin{align*}
\begin{cases}
\sum_{a^1, \delta(\chi)} \tilde{\nu}(\chi) = f(\chi, \tilde{\nu}(\chi), \frac{\theta(\chi)}{\Gamma(\gamma)} \tilde{\nu}(\chi)) + \sigma_1(\chi), & \chi \in \mathbb{J}, \\
\sum_{a^1, \delta(\chi)} \tilde{\omega}(\chi) = g(\chi, \tilde{\omega}(\chi), \frac{\theta(\chi)}{\Gamma(\gamma)} \tilde{\omega}(\chi)) + \sigma_2(\chi), & \chi \in \mathbb{J},
\end{cases}
\end{align*}
\]

(17)

Lemma 3. If \((\tilde{\nu}, \tilde{\omega}) \in C_{1-\gamma, \theta} \times C_{1-\gamma, \theta}\) satisfies (15), then \((\tilde{\nu}, \tilde{\omega})\) is the solution of the inequalities

\[
\begin{align*}
\begin{cases}
\left| \tilde{\nu}(\chi) - \frac{(\theta(\chi) - \theta(a))^{\gamma-1}}{\Gamma(\gamma)} \frac{\theta(\chi)}{\Gamma(\gamma)} \frac{\theta(\chi)}{\Gamma(\gamma)} \tilde{\nu}(\chi) \right| \leq \varepsilon_1 \frac{(\theta(\chi) - \theta(a))^{\rho_1}}{\Gamma(\rho_1+1)}, \\
\left| \tilde{\omega}(\chi) - \frac{(\theta(\chi) - \theta(a))^{\gamma-1}}{\Gamma(\gamma)} \frac{\theta(\chi)}{\Gamma(\gamma)} \frac{\theta(\chi)}{\Gamma(\gamma)} \tilde{\omega}(\chi) \right| \leq \varepsilon_2 \frac{(\theta(\chi) - \theta(a))^{\rho_1}}{\Gamma(\rho_1+1)}.
\end{cases}
\end{align*}
\]

(18)

Proof. By virtue of Theorem 3 and Remark 2 (ii) the solution of (17) with

\[
\left. \begin{array}{l}
\tilde{\nu}(\chi) \bigg|_{\chi=a} = v_a, \\
\tilde{\omega}(\chi) \bigg|_{\chi=a} = \omega_a,
\end{array} \right\}
\]

is equivalent to:

\[
\begin{align*}
\begin{cases}
\tilde{\nu}(\chi) = \frac{(\theta(\chi) - \theta(a))^{\gamma-1}}{\Gamma(\gamma)} v_a + \sum_{a^1, \delta(\chi)} f(\chi, \tilde{\nu}(\chi), \frac{\theta(\chi)}{\Gamma(\gamma)} \tilde{\nu}(\chi)) + \frac{\theta(\chi)}{\Gamma(\gamma)} \tilde{\nu}(\chi) \sigma_1(\chi), \\
\tilde{\omega}(\chi) = \frac{(\theta(\chi) - \theta(a))^{\gamma-1}}{\Gamma(\gamma)} \omega_a + \sum_{a^1, \delta(\chi)} g(\chi, \tilde{\omega}(\chi), \frac{\theta(\chi)}{\Gamma(\gamma)} \tilde{\omega}(\chi)) + \frac{\theta(\chi)}{\Gamma(\gamma)} \tilde{\omega}(\chi) \sigma_2(\chi).
\end{cases}
\end{align*}
\]

(19)

Hence,

\[
\begin{align*}
\left| \tilde{\nu}(\chi) - \frac{(\theta(\chi) - \theta(a))^{\gamma-1}}{\Gamma(\gamma)} v_a + \sum_{a^1, \delta(\chi)} f(\chi, \tilde{\nu}(\chi), \frac{\theta(\chi)}{\Gamma(\gamma)} \tilde{\nu}(\chi)) \right| \\
\leq \sum_{a^1, \delta(\chi)} c_1(\chi) \\
\leq \varepsilon_1 \frac{(\theta(\chi) - \theta(a))^{\rho_1}}{\Gamma(\rho_1+1)}.
\end{align*}
\]

Similarly, we obtain

\[
\begin{align*}
\left| \tilde{\omega}(\chi) - \frac{(\theta(\chi) - \theta(a))^{\gamma-1}}{\Gamma(\gamma)} \omega_a + \sum_{a^1, \delta(\chi)} g(\chi, \tilde{\omega}(\chi), \frac{\theta(\chi)}{\Gamma(\gamma)} \tilde{\omega}(\chi)) \right| \\
\leq \varepsilon_2 \frac{(\theta(\chi) - \theta(a))^{\rho_1}}{\Gamma(\rho_1+1)}.
\end{align*}
\]

\[]

Theorem 6. Under the hypothesis (Hy1), if \((1 - L_f)(1 - L_g) - K_fK_g \neq 0\), then the solution of the coupled system (1) is H-U stable, where

\[
\begin{align*}
&L_f := \frac{B(\rho_1, \gamma)}{\Gamma(\rho_1)} (\theta(b) - \theta(a))^{\rho_1}, \quad K_f := \frac{B(\rho_1 + \rho_3, \gamma)}{\Gamma(\rho_1 + \rho_3)} (\theta(b) - \theta(a))^{\rho_1 + \rho_3}, \\
&L_g := \frac{B(\rho_1, \gamma)}{\Gamma(\rho_1)} (\theta(b) - \theta(a))^{\rho_1}, \quad K_g := \frac{B(\rho_1 + \rho_3, \gamma)}{\Gamma(\rho_1 + \rho_3)} (\theta(b) - \theta(a))^{\rho_1 + \rho_3}.
\end{align*}
\]
Proof. Let \((\tilde{v}, \tilde{\omega}) \in \mathcal{C}_{1-\gamma, \partial} \times \mathcal{C}_{1-\gamma, \partial}\) satisfies \((15)\), and let \((v, \omega) \in \mathcal{C}_{1-\gamma, \partial} \times \mathcal{C}_{1-\gamma, \partial}\) the unique solution of the system

\[
\begin{cases}
\mathcal{D}_{a^+}^{\rho_1, \partial} v(x) = f(x, v(x), \mathcal{P}_{\partial}^{\rho_1, \partial} \omega(x)), & x \in \mathbb{J}, \\
\mathcal{D}_{a^+}^{\rho_2, \partial} \omega(x) = g(x, \omega(x), \mathcal{P}_{\partial}^{\rho_2, \partial} v(x)), & x \in \mathbb{J}, \\
\mathcal{I}_{a^+}^{1-\gamma} \tilde{v}(x)|_{x = a} = \mathcal{I}_{a^+}^{1-\gamma} \tilde{\omega}(x)|_{x = a} = v_a, \\
\mathcal{I}_{a^+}^{1-\gamma} \tilde{\omega}(x)|_{x = a} = \mathcal{I}_{a^+}^{1-\gamma} \tilde{v}(x)|_{x = a} = \omega_a.
\end{cases}
\]

(20)

By virtue of Theorem 3, we obtain

\[
\begin{cases}
v(x) = \mathcal{X}_v = V^0 + \mathcal{P}_{\partial}^{\rho_1, \partial} f(x, v(x), \mathcal{P}_{\partial}^{\rho_2, \partial} \omega(x)), \\
\omega(x) = \mathcal{X}_\omega = V^0 + \mathcal{P}_{\partial}^{\rho_2, \partial} g(x, \omega(x), \mathcal{P}_{\partial}^{\rho_1, \partial} v(x)),
\end{cases}
\]

(21)

where

\[
\mathcal{X}_v = \frac{(\theta(x) - \theta(a))^{\gamma-1}}{\Gamma(\gamma)} v_a, \quad \mathcal{X}_\omega = \frac{(\theta(x) - \theta(a))^{\gamma-1}}{\Gamma(\gamma)} \omega_a.
\]

If \(\mathcal{I}_{a^+}^{1-\gamma} \tilde{v}(x)|_{x = a} = \mathcal{I}_{a^+}^{1-\gamma} \tilde{\omega}(x)|_{x = a}\), then \(\mathcal{X}_v = \mathcal{X}_\omega\). Consequently, we have

\[
\begin{cases}
v(x) = \mathcal{X}_v + \mathcal{P}_{\partial}^{\rho_1, \partial} f(x, v(x), \mathcal{P}_{\partial}^{\rho_2, \partial} \omega(x)), \\
\omega(x) = \mathcal{X}_\omega + \mathcal{P}_{\partial}^{\rho_2, \partial} g(x, \omega(x), \mathcal{P}_{\partial}^{\rho_1, \partial} v(x)),
\end{cases}
\]

(22)

Therefore, by (22), Lemma 3 and \((\text{Hy}_1)\), we obtain

\[
|\tilde{v}(x) - v(x)| \leq \left| \tilde{v}(x) - \mathcal{X}_v + \mathcal{P}_{\partial}^{\rho_1, \partial} f(x, \tilde{v}(x), \mathcal{P}_{\partial}^{\rho_2, \partial} \tilde{\omega}(x)) \right| + \mathcal{P}_{\partial}^{\rho_1, \partial} f(x, \tilde{v}(x), \mathcal{P}_{\partial}^{\rho_2, \partial} \tilde{\omega}(x)) - f(x, v(x), \mathcal{P}_{\partial}^{\rho_2, \partial} \omega(x)) \right|
\]

\[
\leq \frac{\epsilon_1 (\theta(x) - \theta(a))^{\rho_1}}{\Gamma(\rho_1 + 1)} + \mathcal{P}_{\partial}^{\rho_1, \partial} \frac{\epsilon_1 f(\tilde{v}(x) - v(x), \mathcal{P}_{\partial}^{\rho_2, \partial} \omega(x))}{\Gamma(\rho_1 + 1)}
\]

\[
\leq \frac{\epsilon_1 (\theta(x) - \theta(a))^{\rho_1}}{\Gamma(\rho_1 + 1)} + \mathcal{P}_{\partial}^{\rho_1, \partial} \frac{\epsilon_1 f(\tilde{v}(x) - v(x), \mathcal{P}_{\partial}^{\rho_2, \partial} \omega(x))}{\Gamma(\rho_1 + 1)}
\]

\[
\leq \frac{\epsilon_1 (\theta(x) - \theta(a))^{\rho_1}}{\Gamma(\rho_1 + 1)} + \mathcal{P}_{\partial}^{\rho_2, \partial} \frac{\epsilon_1 f(\tilde{v}(x) - v(x), \mathcal{P}_{\partial}^{\rho_1, \partial} \omega(x))}{\Gamma(\rho_1 + 1)}
\]

\[
|\tilde{\omega}(x) - \omega(x)| \leq \frac{\epsilon_1 (\theta(x) - \theta(a))^{\rho_1}}{\Gamma(\rho_1 + 1)} + \mathcal{P}_{\partial}^{\rho_1, \partial} \frac{\epsilon_1 f(\tilde{v}(x) - v(x), \mathcal{P}_{\partial}^{\rho_2, \partial} \omega(x))}{\Gamma(\rho_1 + 1)}
\]

Thus

\[
\|\tilde{v} - v\|_{\mathcal{C}_{1-\gamma, \partial}} \leq \frac{\epsilon_1 (\theta(b) - \theta(a))^{\rho_1 - \gamma + 1}}{\Gamma(\rho_1 + 1)} + \mathcal{P}_{\partial}^{\rho_2, \partial} \frac{\epsilon_1 f(\tilde{v}(x) - v(x), \mathcal{P}_{\partial}^{\rho_1, \partial} \omega(x))}{\Gamma(\rho_1 + 1)}
\]

\[
\|\tilde{\omega} - \omega\|_{\mathcal{C}_{1-\gamma, \partial}} \leq \frac{\epsilon_1 (\theta(b) - \theta(a))^{\rho_1 - \gamma + 1}}{\Gamma(\rho_1 + 1)} + \mathcal{P}_{\partial}^{\rho_2, \partial} \frac{\epsilon_1 f(\tilde{v}(x) - v(x), \mathcal{P}_{\partial}^{\rho_1, \partial} \omega(x))}{\Gamma(\rho_1 + 1)}
\]

which implies

\[
(1 - L_\ell) \|\tilde{v} - v\|_{\mathcal{C}_{1-\gamma, \partial}} \leq Y_1 \epsilon_1 + K_f \|\tilde{\omega} - \omega\|_{\mathcal{C}_{1-\gamma, \partial}}.
\]

(23)

Similarly

\[
(1 - L_\ell) \|\tilde{\omega} - \omega\|_{\mathcal{C}_{1-\gamma, \partial}} \leq Y_2 \epsilon_1 + K_g \|\tilde{v} - v\|_{\mathcal{C}_{1-\gamma, \partial}}.
\]

(24)
where
\[ Y_1 = Y_2 := \frac{(\vartheta(b) - \vartheta(a))\rho_1 - \gamma + 1}{\Gamma(\rho_1 + 1)}. \]

Now, we can express (23) and (24) by
\[
(1 - \mathcal{L}_f)\|\o - v\|_{C^{1-\gamma,\theta}} - K_f\|\o - \omega\|_{C^{1-\gamma,\theta}} \leq Y_1\varepsilon_1, \tag{25}
\]
\[ - K_g\|\o - v\|_{C^{1-\gamma,\theta}} + (1 - \mathcal{L}_g)\|\o - \omega\|_{C^{1-\gamma,\theta}} \leq Y_2\varepsilon_2. \tag{26} \]

The matrix formula of (25) and (26) is
\[
\begin{pmatrix}
1 - \mathcal{L}_f & -K_f \\
-K_g & 1 - \mathcal{L}_g
\end{pmatrix}
\begin{pmatrix}
\|\o - v\|_{C^{1-\gamma,\theta}} \\
\|\o - \omega\|_{C^{1-\gamma,\theta}}
\end{pmatrix}
\leq
\begin{pmatrix}
Y_1\varepsilon_1 \\
Y_2\varepsilon_2
\end{pmatrix}.
\]
It follows that
\[
\begin{pmatrix}
\|\o - v\|_{C^{1-\gamma,\theta}} \\
\|\o - \omega\|_{C^{1-\gamma,\theta}}
\end{pmatrix}
\leq
\frac{1}{\Delta}
\begin{pmatrix}
1 - \mathcal{L}_g & K_f \\
K_g & 1 - \mathcal{L}_f
\end{pmatrix}
\begin{pmatrix}
Y_1\varepsilon_1 \\
Y_2\varepsilon_2
\end{pmatrix},
\]
where \( \Delta = (1 - \mathcal{L}_f)(1 - \mathcal{L}_g) - K_fK_g \neq 0 \). Hence
\[
\|\o - v\|_{C^{1-\gamma,\theta}} \leq \frac{(1 - \mathcal{L}_g)Y_1\varepsilon_1}{\Delta} + \frac{K_fY_2\varepsilon_2}{\Delta}, \tag{27}
\]
and
\[
\|\o - \omega\|_{C^{1-\gamma,\theta}} \leq \frac{K_gY_1\varepsilon_1}{\Delta} + \frac{(1 - \mathcal{L}_f)Y_2\varepsilon_2}{\Delta}. \tag{28}
\]

By (27) and (28), we find that
\[
\|(\o, \o) - (v, \omega)\|_{C^{1-\gamma,\theta}} \leq \|\o - v\|_{C^{1-\gamma,\theta}} + \|\o - \omega\|_{C^{1-\gamma,\theta}} \leq \frac{(1 - \mathcal{L}_g)Y_1\varepsilon_1}{\Delta} + \frac{K_fY_2\varepsilon_2}{\Delta}
\leq \frac{K_gY_1\varepsilon_1}{\Delta} + \frac{(1 - \mathcal{L}_f)Y_2\varepsilon_2}{\Delta}
\leq Y\varepsilon,
\]
where \( Y = \frac{2L_1 + K_f + K_g - \mathcal{L}_f}{\Delta} \), and \( \varepsilon = \max\{\varepsilon_1, \varepsilon_2\} \).}\]

4. Examples

Consider the \( \vartheta \)-Hilfer type system
\[
\begin{align*}
\mathcal{D}_{0^+}^{\gamma, \vartheta} u(x) &= f(x, v(x), \|v\|_{L^1}^\varphi, \vartheta(x), \omega(x)), \quad x \in (0, 1], \\
\mathcal{D}_{0^+}^{\gamma, \vartheta} \omega(x) &= g(x, \omega(x), \|\omega\|_{L^1}^\varphi, \vartheta(x), \omega(x)), \quad x \in (0, 1], \\
\|v\|_{L^1}^\varphi|_{x=0} &= 1, \quad \|\omega\|_{L^1}^\varphi|_{x=0} = 2,
\end{align*}
\]
where \( \rho_1 = \frac{1}{\vartheta}, \rho_2 = \frac{1}{\vartheta}, \rho_3 = \frac{1}{\vartheta}, \gamma = \frac{1}{\vartheta}, v_0 = 1, \) and \( \omega_0 = 2 \).
1. In order to illustrate Theorem 5, we take \( \vartheta(x) = \frac{\pi}{4} \) and

\[
\begin{align*}
  f(x, v(x), \varphi^{0}_{\alpha^+, \beta(x)} \omega(x)) &= \frac{8}{20} \left( \sin v(x) + \sin \left( \frac{1}{0^+, \frac{\pi}{4}} \omega(x) \right) + 1 \right), \\
  g(x, \omega(x), \varphi^{0}_{\alpha^+, \beta(x)} v(x)) &= \frac{1}{30} \left( \cos x + \omega(x) + \sin \left( \frac{1}{0^+, \frac{\pi}{4}} v(x) \right) \right).
\end{align*}
\]

(30)

Then we have

\[
\begin{align*}
  \left| f(x, v(x), \varphi^{0}_{\alpha^+, \beta(x)} \omega(x)) - f(x, \omega(x), \varphi^{0}_{\alpha^+, \beta(x)} \omega(x)) \right| &\leq \frac{8}{20} \left( \left| \sin v(x) - \sin \omega(x) \right| + \left| \sin \left( \frac{1}{0^+, \frac{\pi}{4}} \omega(x) \right) - \sin \left( \frac{1}{0^+, \frac{\pi}{4}} \omega(x) \right) \right| \right) \\
  &\leq \frac{8}{20} \left( |v(x) - \omega(x)| + \left| \frac{1}{0^+, \frac{\pi}{4}} \omega(x) - \frac{1}{0^+, \frac{\pi}{4}} \omega(x) \right| \right)
\end{align*}
\]

and

\[
\begin{align*}
  \left| g(x, \omega(x), \varphi^{0}_{\alpha^+, \beta(x)} v(x)) - g(x, \omega(x), \varphi^{0}_{\alpha^+, \beta(x)} \omega(x)) \right| &\leq \frac{1}{30} \left( \left| \omega(x) - \omega(x) \right| + \left| \sin \left( \frac{1}{0^+, \frac{\pi}{4}} v(x) \right) - \sin \left( \frac{1}{0^+, \frac{\pi}{4}} \omega(x) \right) \right| \right) \\
  &\leq \frac{1}{30} \left( |\omega(x) - \omega(x)| + \left| \frac{1}{0^+, \frac{\pi}{4}} v(x) - \frac{1}{0^+, \frac{\pi}{4}} \omega(x) \right| \right)
\end{align*}
\]

Thus, (H\(_y\)) holds with \( \kappa_f = \pi_f = \frac{8}{20} \) and \( \kappa_g = \pi_g = \frac{1}{30} \). From the above data, we obtain \( \zeta_1 \approx 0.33 \) and \( \zeta_2 \approx 0.26 \). Hence \( \max_{x \in [0,1]} \{ \zeta_1, \zeta_2 \} = \zeta \approx 0.33 < 1 \). Thus, with the assistance of Theorem 5, the system (29) with \( f \) and \( g \) given by (30) has a unique solution \((v(x), \omega(x))\) on \([0,1]\).

2. In order to illustrate Theorem 4, we take

\[
\begin{align*}
  f(x, v(x), \varphi^{0}_{\alpha^+, \beta(x)} \omega(x)) &= \frac{1}{30} v(x) \sin \omega(x) + \frac{3}{20} \cos v(x) \left( \frac{1}{0^+, \frac{\pi}{4}} \omega(x) \right), \\
  g(x, \omega(x), \varphi^{0}_{\alpha^+, \beta(x)} v(x)) &= \frac{1}{1000} \sin \left( \frac{1}{0^+, \frac{\pi}{4}} v(x) \right) + \frac{3}{100} \left( e^{-\frac{\pi}{4}} \omega(x) \right).
\end{align*}
\]

(31)

It is easy to see that

\[
\begin{align*}
  \left| f(x, v(x), \varphi^{0}_{\alpha^+, \beta(x)} \omega(x)) \right| &\leq \frac{1}{40} |v(x)| + \frac{3}{20} |\frac{1}{0^+, \frac{\pi}{4}} \omega(x)|, \\
  \left| g(x, \omega(x), \varphi^{0}_{\alpha^+, \beta(x)} v(x)) \right| &\leq \frac{1}{10} \left( \left| \frac{1}{0^+, \frac{\pi}{4}} v(x) \right| + \frac{3}{100} |\omega(x)| \right).
\end{align*}
\]

So, condition (H\(_{\bar{y}}\)) is satisfied with \( \vartheta_f = \frac{1}{40}, \vartheta_f = \frac{3}{20}, \vartheta_g = \frac{1}{10}, \vartheta_g = \frac{3}{100} \). Moreover, \( \Lambda = \frac{\sqrt{7}}{81(\frac{\pi}{4})} + \frac{9\sqrt{7}}{50(\frac{\pi}{4})} > 0 \) and \( \eta_1 \approx 0.14 < 1 \). Thus, Theorem 4 is applied to system (29) with \( f \) and \( g \) given by (31).

3. In order to illustrate Theorem 6, we have from case 1 that (H\(_y\)) is satisfied. As has been shown in Theorem 6, for \( \epsilon_1 = \frac{1}{2} \) and \( \epsilon_2 = \frac{1}{4} \), if \((\bar{v}, \bar{\omega}) \in C_{\frac{1}{2}, \frac{\pi}{4}}([0,1], \mathbb{R}) \times C_{\frac{1}{2}, \frac{\pi}{4}}([0,1], \mathbb{R})\) satisfies

\[
\begin{align*}
  \left| \frac{1}{0^+, \frac{\pi}{4}} \bar{v}(x) - \frac{8}{20} \left( \sin \bar{v}(x) + \sin \left( \frac{1}{0^+, \frac{\pi}{4}} \bar{\omega}(x) \right) + 1 \right) \right| &\leq \frac{1}{2}, \quad x \in (0,1), \\
  \left| \frac{1}{0^+, \frac{\pi}{4}} \bar{\omega}(x) - \frac{1}{30} \left( \cos x + \bar{\omega}(x) + \sin \left( \frac{1}{0^+, \frac{\pi}{4}} \bar{v}(x) \right) \right) \right| &\leq \frac{1}{4}, \quad x \in (0,1),
\end{align*}
\]
there exists a unique solution \((v, \omega) \in C_{\frac{1}{2}, \frac{3}{4}}([0, 1], \mathbb{R}) \times C_{\frac{1}{2}, \frac{3}{4}}([0, 1], \mathbb{R})\) of the problem (29) with \(f\) and \(g\) given by (30) such that

\[
\|((\tilde{v}, \tilde{\omega}) - (v, \omega))\|_{C_{\frac{1}{2}, \frac{3}{4}}} \leq \frac{1}{2} Y.
\]

where

\[
Y = \frac{2 - \mathcal{L}_g + \mathcal{K}_f + \mathcal{K}_g - \mathcal{L}_f}{\Delta} \quad \text{and} \quad \mathcal{L}_f = \frac{2\sqrt{\pi}}{5\sqrt{3}\Gamma\left(\frac{5}{6}\right)}, \quad \mathcal{K}_f = \frac{2\sqrt{\pi}}{5\sqrt{3}\Gamma\left(\frac{13}{12}\right)},
\]

\[
\mathcal{L}_g = \frac{\sqrt{\pi}}{30\sqrt{3}\Gamma\left(\frac{7}{6}\right)}, \quad \mathcal{K}_g = \frac{\sqrt{\pi}}{30\sqrt{3}\Gamma\left(\frac{13}{12}\right)}.
\]

Hence \(\Delta = \left(1 - \mathcal{L}_f\right)\left(1 - \mathcal{L}_g\right) - \mathcal{K}_f \mathcal{K}_g = 0.88 \neq 0\), which implies that system (29) is H-U stable.

5. Conclusions

Recently, FDEs have attracted the interest of several researchers with prosperous applications, especially those involving generalized fractional operators. It is important that we investigate the fractional systems with generalized Hilfer derivatives since these derivatives cover many systems in the literature and they contain a kernel with different values that generates many special cases. As an additional contribution in this topic, existence, uniqueness, and U-H stability results of a coupled system for a new class of fractional integrodifferential equations in the generalized Hilfer sense are examined. The analysis of obtained results is based on applying Schauder’s and Banach’s fixed point theorems, and Arzelà-Ascoli’s theorem.

It should be noted that in light of our obtained results, our use of the generalized Hilfer operator covers many systems associated with different values of the function \(\vartheta\) and the parameter \(\rho_2\), as is the case in the Special Cases section.

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