Error Estimates of a Continuous Galerkin Time Stepping Method for Subdiffusion Problem

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Abstract
A continuous Galerkin time stepping method is introduced and analyzed for subdiffusion problem in an abstract setting. The approximate solution will be sought as a continuous piecewise linear function in time \( t \) and the test space is based on the discontinuous piecewise constant functions. We prove that the proposed time stepping method has the convergence order \( O(\tau^{1+\alpha}) \), \( \alpha \in (0, 1) \) for general sectorial elliptic operators for nonsmooth data by using the Laplace transform method, where \( \tau \) is the time step size. This convergence order is higher than the convergence orders of the popular convolution quadrature methods (e.g., Lubich’s convolution methods) and L-type methods (e.g., L1 method), which have only \( O(\tau) \) convergence for the nonsmooth data. Numerical examples are given to verify the robustness of the time discretization schemes with respect to data regularity.

Keywords Subdiffusion problem · Continuous Galerkin time stepping method · Laplace transform · Caputo fractional derivative

Mathematics Subject Classification 65M15 · 65M60 · 65M12 · 45K05

1 Introduction

Consider the following subdiffusion problem, with \( \alpha \in (0, 1) \),
\[
\frac{C}{C_0} D_t^\alpha u(t) + Au(t) = f(t), \quad 0 < t \leq T,
\] (1)
where \( u_0 \) is the initial value and \( f \) is the source function which will be specified later and where \( \frac{C}{0}D_t^\alpha u(t) \) denotes the Caputo fractional derivative defined by, see [7],

\[
\frac{C}{0}D_t^\alpha u(t) = \frac{1}{\Gamma(1-\alpha)} \int_0^t (t-s)^{-\alpha} u'(s) \, ds,
\]

and \( A : \mathcal{D}(A) \subset \mathcal{H} \to \mathcal{H} \) denotes the elliptic operator satisfying the following resolvent estimate, with some \( \pi/2 < \theta < \pi \), see, e.g., [25,37],

\[
\|(z + A)^{-1}\| \leq C|z|^{-\alpha}, \quad \forall z \in \Sigma_\theta = \{z \in \mathbb{C}\setminus\{0\} : |\arg z| \leq \theta\}. \tag{3}
\]

Here \( \mathcal{H} \) denotes a suitable Hilbert space. For example, \( \mathcal{H} = L_2(\Omega) \) and \( A = -\Delta \) with definition domain \( \mathcal{D}(A) = H^2(\Omega) \cap H^1_0(\Omega) \). Here \( L_2(\Omega), H^1_0(\Omega) \) and \( H^2(\Omega) \) denote the standard Sobolev spaces and \( \Omega \subset \mathbb{R}^d \), \( d = 1, 2, 3 \) is a domain with smooth boundary \( \partial \Omega \).

Note that \( z^\alpha \in \Sigma_{\theta'} \) with \( \theta' = \alpha \theta < \pi \) for all \( z \in \Sigma_\theta \) which implies that, by (3), with some \( \pi/2 < \theta < \pi \),

\[
\|(z^\alpha + A)^{-1}\| \leq C|z|^{-\alpha}, \quad \forall z \in \Sigma_\theta = \{z \in \mathbb{C}\setminus\{0\} : |\arg z| \leq \theta\}. \tag{4}
\]

Let \( S_h \subset H^1_0(\Omega) \) denote the piecewise linear finite element space defined on the triangulation of \( \Omega \). The finite element method of (1), (2) is to find \( u_h(t) \in S_h \) such that for \( u_0 \in L_2(\Omega), f(t) \in L_2(\Omega) \) with \( f_h(t) = P_h f(t), \)

\[
\frac{C}{0}D_t^\alpha u_h(t) + A_h u_h(t) = f_h(t), \quad 0 < t \leq T, \tag{5}
\]

\[
u_h(0) = u_{0h} = P_h u_0, \tag{6}
\]

where \( A_h : S_h \to S_h \) denotes the discrete analogue of the elliptic operator \( A \) defined by, see Thomée [37, Chapter 12],

\[
(A_h \psi, \chi) = A(\psi, \chi), \quad \forall \psi, \chi \in S_h,
\]

where \( A(\cdot, \cdot) \) denotes the bilinear form associated with \( A \). Here \( P_h : L_2(\Omega) \to S_h \) denotes the \( L_2 \) projection operator defined by

\[
(P_h v, \chi) = (v, \chi), \quad \forall \chi \in S_h.
\]

Note that the minimal eigenvalue of \( A_h \) is bounded below by that of \( A \) since \( S_h \) is a subspace of \( L_2(\Omega) \), we have, with some \( \pi/2 < \theta < \pi \), see Lubich et al. [25, page 6],

\[
\|(z^\alpha + A)^{-1}\| \leq C|z|^{-\alpha}, \quad \forall z \in \Sigma_\theta = \{z \in \mathbb{C}\setminus\{0\} : |\arg z| \leq \theta\}. \tag{7}
\]

Let \( v_h(t) = u_h(t) - u_{0h} \). Then (5), (6) can be written equivalently as

\[
\frac{C}{0}D_t^\alpha v_h(t) + A_h v_h(t) = f_h(t) - A_h u_{0h}, \quad 0 < t \leq T, \tag{8}
\]

\[
v_h(0) = 0. \tag{9}
\]

In this work, we shall construct and analyze a continuous Galerkin time stepping method for solving (8), (9). It is more convenient for analyzing the time stepping method for (8), (9) than for (5), (6), see Lubich et al. [25].

Many application problems are modeled by using (1), (2), see, e.g., [1,9,10,32], etc. It is not possible to find the analytic solution of (1), (2). Therefore we need to design and analyze the numerical methods for solving (1), (2). Note that the Caputo fractional derivative is a nonlocal operator which makes the numerical analysis of the subdiffusion equation (1), (2) more difficult than the diffusion equation with the integer order derivative. There are two
popular ways to approximate the Caputo fractional derivative in literature. One way is to use the convolution quadrature formula to approximate the Caputo fractional derivative, see, e.g., [25,26,46]. Another way is to use the L-type schemes to approximate the Caputo fractional derivative, see, e.g., [16,20–23,34,45], etc. Under the assumptions that the solutions of (1), (2) are sufficiently smooth, the numerical methods constructed based on both convolution quadrature and L-type schemes have the optimal convergence orders, see [23,34], etc. However, Stynes et al. [36] and Stynes [35] showed that in general the solutions of (1), (2) have the limited regularities and the solutions behave as $O(t^\alpha)$ even for smooth initial data, which implies that the solutions of (1), (2) are not in $C^1[0, T]$, see also [33]. Hence the higher order numerical methods constructed by convolution quadrature and L-type schemes for solving (1), (2) have only first order $O(\tau)$ convergence for both smooth and nonsmooth data, see, e.g., [11,41], etc. To obtain the optimal convergence orders of the higher order numerical methods for solving (1), (2), one may use the corrected schemes to correct the weights of the starting steps of the numerical methods, see, e.g., [12,42], etc., or use the graded meshes to capture the singularities of the solutions of the subdiffusion problems, see, e.g., [16,36,45], etc. Discontinuous Galerkin methods are also well studied for solving fractional subdiffusion equations, see, e.g., [29–31] and the references therein. There are other numerical methods for solving fractional partial differential equations, see, e.g., [2–6,8,13–15,24,27,28,39,43,44,46], etc.

Recently, Li et al. [17] analyzed the L1 scheme for solving the superdiffusion problem with the fractional order $\alpha \in (1, 2)$ based on the Petrov–Galerkin method. This scheme is first proposed and analyzed by Sun and Wu [34] in the framework of finite difference method under the assumptions that the solution of the problem is sufficiently smooth. Li et al. [17] proved that, without any regularity assumptions for the solution of the problem and without using the corrections of the weights and the graded meshes, the L1 scheme has the convergence order $O(\tau^{3-\alpha})$, $\alpha \in (1, 2)$ for both smooth and nonsmooth data when the elliptic operator $A$ is assumed to be self-adjoint, positive semidefinite and densely defined in a suitable Hilbert space, see also [18,19], etc.

The purpose of this paper is to consider the continuous Galerkin method for solving the subdiffusion problem with $\alpha \in (0, 1)$ by using the similar argument as in Li et al. [17] for the superdiffusion problem with $\alpha \in (1, 2)$. We prove that, without any regularity assumptions for the solution of the problem and without using the corrections of the weights and the graded meshes, the proposed time stepping method has the convergence order $O(\tau^{1+\alpha})$, $\alpha \in (0, 1)$ for general sectorial elliptic operators satisfying the resolvent estimate (3).

The main contributions of this paper are the following:

1. A continuous Galerkin time stepping method for solving subdiffusion problem is introduced for general sectorial elliptic operators satisfying the resolvent estimate (3).
2. The convergence order $O(\tau^{1+\alpha})$, $\alpha \in (0, 1)$ of the proposed time stepping method for solving homogeneous subdiffusion problem is proved by using the Laplace transform method.
3. The convergence order $O(\tau^{1+\alpha})$, $\alpha \in (0, 1)$ of the proposed time stepping method for solving inhomogeneous subdiffusion problem is also proved by using the Laplace transform method.

The paper is organized as follows. In Sect. 2, we introduce the continuous Galerkin time stepping method for solving subdiffusion problem. In Sect. 3, the error estimates of the proposed time stepping methods are proved by using discrete Laplace transform method for the subdiffusion problems. In Sect. 4, some numerical examples for both fractional ordinary differential equations and subdiffusion problems are given to verify the theoretical results. An Appendix with three lemmas is given in Sect. 5.
2 A Continuous Galerkin Time Stepping Method for (8), (9)

In this section, we shall introduce a continuous Galerkin time stepping method for solving (8), (9).

Let \( 0 = t_0 < t_1 < \cdots < t_N = T \) be a partition of \([0, T]\) and \( \tau \) the time step size. We define the following trial space, with \( k \) \( (9) \). We shall show that the solutions and the test space \( R \) where the method for solving (8), (9) is of interest but not necessarily the same at different occurrences. We assume that \( \alpha \in (0, 1) \) in this paper and, for simplicity, we will not explicitly write this assumption in many places.

Let \( \beta_j \in \mathbb{R} \) respectively. We remark that the trial space \( W^1 \) is a discontinuous piecewise constant function space with respect to time \( t \). The trial space \( W^1 \) is, due to the continuous restriction, of one order higher than the test space \( W^0 \).

Let \( u_0 \in L^2(\Omega) \) and \( f \in L^2(0, T; L^2(\Omega)) \). The continuous Galerkin time stepping method for solving (8), (9) is to find \( V_h \in W^1 \) with \( V_h(0) = 0 \), such that

\[
\int_0^T \left( D_0^\alpha V_h(t), \chi \right) \, dt + \int_0^T A(\chi) \, dt = \int_0^T \left( f(t), \chi \right) \, dt - \int_0^T (A_h u_{0h}, \chi) \, dt, \quad \forall \chi \in W^0,
\]

where \( D_0^\alpha V_h(t) \) denotes the Riemann-Liouville fractional derivative and \( (\cdot, \cdot) \) denotes the inner product in \( \mathbb{L}^2(\Omega) \).

Let \( V_h^k = V_h(t_k) \), \( k = 0, 1, 2, \ldots, N \) denote the approximate solution of \( v_h(t_k) \) in (8), (9). We shall show that the solutions \( V_h^k, k = 0, 1, 2, \ldots, N \) of (10) satisfy the following abstract operator form: with \( V_h^0 = V_h(0) = 0 \),

\[
V_h^1(b_{k+1} - b_k) + \frac{1}{2} \tau^\alpha A_h(V_h^k + V_h^{k+1}) = \tau^{\alpha-1} \int_{t_k}^{t_{k+1}} f_h(t) \, dt + \tau^\alpha (-A_h u_{0h}), \quad \text{for } k = 0,
\]

(11)

\[
V_h^1(b_{k+1} - b_k) + \sum_{j=1}^{k} \left( V_h^{j+1} - 2V_h^j + V_h^{j-1} \right) (b_{k-j+1} - b_{k-j}) + \frac{1}{2} \tau^\alpha A_h(V_h^k + V_h^{k+1}) = \tau^{\alpha-1} \int_{t_k}^{t_{k+1}} f_h(t) \, dt + \tau^\alpha (-A_h u_{0h}), \quad \text{for } k = 1, 2, \ldots, N - 1,
\]

(12)

where

\[
b_j = \frac{j^{2-\alpha}}{\Gamma(3 - \alpha)}, \quad j = 0, 1, 2, \ldots, N.
\]

(13)
In fact, we have, on each \((t_k, t_{k+1})\), \(k = 0, 1, 2, \ldots, N-1\),
\[
\int_{t_k}^{t_{k+1}} \left( \frac{\partial}{\partial t} V_h(t), \chi \right) dt + \int_{t_k}^{t_{k+1}} A(V_h(t), \chi) dt \\
= \int_{t_k}^{t_{k+1}} (f_h(t), \chi) dt + \int_{t_k}^{t_{k+1}} (A_h u_{0h}, \chi) dt. \quad \forall \chi \in W^0.
\]

On each subinterval \((t_k, t_{k+1})\), \(k = 1, 2, \ldots, N-1\), (similarly we may consider the subinterval \((t_0, t_1)\)), we may write, for \(\forall \chi \in W^0\),
\[
\int_{t_k}^{t_{k+1}} \left( \frac{\partial}{\partial t} V_h(t), \chi \right) dt = \int_{t_k}^{t_{k+1}} \left( D^1 \frac{\partial}{\partial t} V_h(t), \chi \right) dt \\
= \int_{t_k}^{t_{k+1}} \left( \frac{1}{\Gamma(1-\alpha)} \left[ \int_{t_0}^{t_1} (t-s)^{-\alpha} V_h(s) ds \right]' , \chi \right) dt.
\]

Note that \(V_h \in W^1\) and therefore \(V_h(t) = V_h(t_k) + (V_h(t_{k+1}) - V_h(t_k)) \frac{t-t_k}{t_{k+1}-t_k}\) on \(t \in (t_k, t_{k+1})\), \(k = 0, 1, \ldots, N-1\). Hence we have, for \(\forall \chi \in W^0\), with \(k = 1, 2, \ldots, N-1\),
\[
\int_{t_k}^{t_{k+1}} \frac{1}{\Gamma(1-\alpha)} \left[ \int_{t_0}^{t_1} (t-s)^{-\alpha} V_h(s) ds \right]' , \chi \right) dt \\
= \frac{(V_h^1, \chi)}{\tau} \frac{\tau^{1-\alpha}}{\Gamma(2-\alpha)} \left[ (k+1)^{-\alpha} - 2k^{-\alpha} + (k-1)^{-\alpha} \right] \\
- \frac{\tau^{2-\alpha}}{\Gamma(3-\alpha)} \frac{1}{(k-l+1)^{-\alpha} - (k-l-1)^{-\alpha}},
\]
and, with \(l = 2, 3, \ldots, k\),
\[
\int_{t_k}^{t_{k+1}} \frac{1}{\Gamma(1-\alpha)} \left[ \int_{t_0}^{t_l} (t-s)^{-\alpha} V_h(s) ds \right]' , \chi \right) dt \\
= \frac{(V_h^{l-1}, \chi)}{\tau} \frac{\tau^{1-\alpha}}{\Gamma(2-\alpha)} \left[ (k-l+2)^{-\alpha} - 2(k-l+1)^{-\alpha} + (k-l)^{-\alpha} \right] \\
+ \frac{(V_h^l - V_h^{l-1}, \chi)}{\tau} \frac{\tau^{2-\alpha}}{\Gamma(3-\alpha)} \left[ (k-l+2)^{-\alpha} - 2(k-l+1)^{-\alpha} + (k-l)^{-\alpha} \right] \\
- \frac{\tau^{2-\alpha}}{\Gamma(2-\alpha)} \left[ (k-l+1)^{-\alpha} - (k-l)^{-\alpha} \right],
\]
and
\[
\int_{t_k}^{t_{k+1}} \frac{1}{\Gamma(1-\alpha)} \left[ \int_{t_0}^{t_l} (t-s)^{-\alpha} V_h(s) ds \right]' , \chi \right) dt \\
= \frac{(V_h^k, \chi)}{\tau} \frac{\tau^{1-\alpha}}{\Gamma(2-\alpha)} \left[ 0^{-\alpha} - 0^{-\alpha} \right] + \frac{(V_h^{k+1} - V_h^k, \chi)}{\tau} \frac{\tau^{2-\alpha}}{\Gamma(3-\alpha)} \left[ 1^{-\alpha} - 0^{-\alpha} \right].
\]

Hence we have
\[
\int_{t_k}^{t_{k+1}} \left( \frac{\partial}{\partial t} V_h(t), \chi \right) dt \\
\tau^{1-\alpha} [(V_h^1, \chi)(b_{k+1} - b_k) + (V_h^2 - 2V_h^1 + V_h^0, \chi)(b_k - b_{k-1}) \\
+ \cdots + (V_h^{k+1} - 2V_h^k + V_h^{k-1}, \chi)(b_1 - b_0)], \quad \forall \chi \in W^0,
\]
where \( b_k, k = 0, 1, 2, \ldots, N \) are defined in (13).

Further we have, with \( k = 0, 1, 2, \ldots, N - 1, \)
\[
\int_{t_k}^{t_{k+1}} A(V_h(t), \chi) \, dt = \frac{1}{2} \tau A(V^k_h + V^{k+1}_h, \chi), \quad \forall \chi \in W^0.
\]

Together these estimates we obtain the time stepping method (11), (12).

**Remark 1** The time stepping method (11), (12) has the similar form as the time discretization scheme introduced in [17, (4)] for the superdiffusion problem with \( 1 < \alpha < 2. \)

### 3 Error Estimates of the Time Stepping Method (11), (12)

In this section, we will show the error estimates of the abstract time stepping method (11), (12) by using the Laplace transform method proposed originally by Lubich et al. [25] and developed by Jin et al. [11, 12], Yan et al. [42] and Wang et al. [38], etc.

#### 3.1 The Homogeneous Case with \( f = 0 \) and \( u_0 \neq 0 \)

In this subsection, we will consider the error estimates of the time stepping method (11), (12) with \( f = 0 \) and \( u_0 \neq 0. \) We thus consider the following homogeneous problem, with \( v_h(0) = 0 \) and \( u_{0h} = P_h u_0, \) \( u_0 \in L^2(\Omega), \)
\[
C_0^{D^\alpha_t} v_h(t) + A_h v_h(t) = -A_h u_{0h}, \quad 0 < t \leq T. \tag{14}
\]

The abstract time stepping method (11), (12) for solving (14) is now reduced to, with \( V^0_h = 0, \)
\[
\begin{align*}
V^1_h(b_{k+1} - b_k) + \frac{1}{2} \tau^\alpha A_h(v^k_h + v^{k+1}_h) &= \tau^\alpha (-A_h u_{0h}), \quad \text{for } k = 0, \\
V^1_h(b_{k+1} - b_k) + \sum_{j=1}^{k} (v^{j+1}_h - 2v^j_h + v^{j-1}_h)(b_{k-j+1} - b_{k-j}) &+ \frac{1}{2} \tau^\alpha A_h(v^k_h + v^{k+1}_h) = \tau^\alpha (-A_h u_{0h}), \quad \text{for } k = 1, 2, \ldots.
\end{align*}
\]

We then have the following theorem:

**Theorem 1** Let \( v_h(t_n) \) and \( V^n_h, \) \( n = 0, 1, 2, \ldots, \) be the solutions of (14) and (15), (16), respectively. Assume that \( u_{0h} = P_h u_0, \) \( u_0 \in L^2(\Omega). \) Then we have
\[
\| V^n_h - v_h(t_n) \| \leq C\left( \tau^{1+\alpha} t_n^{1-\alpha} + \tau^2 t_n^{-2} \right) \| u_0 \|.
\]

**Proof** Step 1: Find the exact solution of (14). Let \( \hat{v}_h(z) \) denote the Laplace transform of \( v_h(t). \) Taking the Laplace transform in (14), we have
\[
\hat{v}_h(z) = (z^\alpha + A_h)^{-1}(-A_h u_{0h})z^{-1},
\]
which implies that, by using the inverse Laplace transform, with \( n = 1, 2, \ldots, \)
\[
v_h(t_n) = \frac{1}{2\pi i} \int_{\Gamma} e^{\ln z} (z^\alpha + A_h)^{-1}(-A_h u_{0h})z^{-1} \, dz, \tag{17}
\]
where, with some \( \pi/2 < \theta < \pi, \)
\[
\Gamma = \{ z \in \mathbb{C} : |\arg z| = \theta \} \cup \{0\},
\]
with $\Im z$ running from $-\infty$ to $\infty$.

Taking the variable change $z = \tilde{z}/\tau$, we may write (17) as

$$
\psi_h(t_n) = \frac{1}{2\pi i} \int_{\Gamma} e^{\tilde{z}^n} (\tilde{z}^\alpha + \tau^\alpha A_h)^{-1} (-\tau^\alpha A_h) u_{0h} \tilde{z}^{-1} d\tilde{z}.
$$

(19)

For simplicity of the notations, we replace $\tilde{z}$ by $z$ in (19), then (17) can be written as

$$
\psi_h(t_n) = \frac{1}{2\pi i} \int_{\Gamma} e^{zn} (z^\alpha + \tau^\alpha A_h)^{-1} (-\tau^\alpha A_h) u_{0h} z^{-1} dz.
$$

(20)

Step 2: Find the approximate solutions $V_h^n$, $n = 1, 2, \ldots$ of (15), (16).

Denote

$$
\hat{z}_\tau^\alpha = \frac{2}{e^\epsilon + 1} \psi(z), \quad \text{or} \quad z_\tau = \left( \frac{2}{e^\epsilon + 1} \psi(z) \right)^{1/\alpha},
$$

(21)

where

$$
\psi(z) = e^{-\tau}(e^\epsilon - 1)^3 \tilde{b}(z).
$$

(22)

Here $\tilde{b}(z) = \sum_{j=0}^{\infty} b_j e^{-jz}$ with $b_j$, $j = 0, 1, 2, \ldots$, defined by (13), denotes the discrete Laplacian transform of $\{b_j\}_{j=0}^{\infty}$.

By Lemma 1, we see that $(z_\tau^\alpha + \tau^\alpha A_h)^{-1}$ is well defined. Further we shall prove that the solutions $V_h^n$, $n = 1, 2, \ldots$ of (15), (16) take the following forms:

$$
V_h^n = \frac{1}{2\pi i} \int_{\Gamma} e^{zn} (z_\tau^\alpha + \tau^\alpha A_h)^{-1} (-\tau^\alpha A_h) u_{0h} \left( \frac{2}{e^\epsilon + 1} \right) \left( \sum_{j=0}^{\infty} e^{-jz} \right) dz,
$$

(23)

where, with $\Gamma$ defined by (18),

$$
\Gamma_\epsilon = \{ z \in \Gamma : |\Im z| \leq \pi \}.
$$

(24)

In fact, multiplying the $(k + 1)$th equation in (15), (16) by $e^{-kz}$, $k = 0, 1, 2, \ldots$, we obtain

$$
V_h^1 (b_{k+1} - b_k) e^{-kz} + \frac{1}{2} \tau^\alpha A_h (V_h^k + V_h^{k+1}) e^{-kz} = \tau^\alpha (-A_h u_{0h}) e^{-kz}, \quad \text{for } k = 0,
$$

(25)

$$
V_h^1 (b_{k+1} - b_k) e^{-kz} + \sum_{j=1}^{k} \left( V_h^{j+1} - 2V_h^j + V_h^{j-1} \right) (b_{k-j+1} - b_{k-j}) e^{-kz} + \frac{1}{2} \tau^\alpha A_h (V_h^k + V_h^{k+1}) e^{-kz} = \tau^\alpha (-A_h u_{0h}) e^{-kz}, \quad \text{for } k = 1, 2, \ldots.
$$

(26)

Summing the equations in (25), (26) from $k = 0$ to $k = \infty$, we get

$$
\sum_{k=0}^{\infty} V_h^1 (b_{k+1} - b_k) e^{-kz} + \sum_{k=1}^{\infty} \left[ \sum_{j=1}^{k} \left( V_h^{j+1} - 2V_h^j + V_h^{j-1} \right) (b_{k-j+1} - b_{k-j}) \right] e^{-kz} + \sum_{k=0}^{\infty} \frac{1}{2} \tau^\alpha A_h (V_h^k + V_h^{k+1}) e^{-kz} = \sum_{k=0}^{\infty} \tau^\alpha (-A_h u_{0h}) e^{-kz}.
$$

(27)

We remark that the second summation in (27) starts from $k = 1$ since the left hand side of (25) only has two terms. Note that, since $b_0 = 0$,

$$
\sum_{k=0}^{\infty} (V_h^1)(b_{k+1} - b_k) e^{-kz} = V_h^1 \left( \sum_{k=0}^{\infty} b_{k+1} e^{-kz} - \sum_{k=0}^{\infty} b_k e^{-kz} \right) = V_h^1 \tilde{b}(z)(e^\epsilon - 1).
$$
Let \( \tilde{V}_h(z) = \sum_{n=0}^{\infty} V^n_h e^{-nz} \) denote the discrete Laplace transform of \( \{V^n_h\}_{n=0}^{\infty} \). We have, after some simple calculations,

\[
\begin{align*}
\sum_{k=1}^{\infty} \left( \sum_{j=1}^{k} V^{j+1}_h b_{k-j+1} \right) e^{-kz} &= \tilde{b}(z) e^{2z} \left( \tilde{V}_h(z) - V^1_h e^{-z} \right), \\
\sum_{k=1}^{\infty} \left( \sum_{j=1}^{k} V^{j+1}_h b_{k-j} \right) e^{-kz} &= \tilde{b}(z) e^z \left( \tilde{V}_h(z) - V^1_h e^{-z} \right), \\
\sum_{k=1}^{\infty} \left( \sum_{j=1}^{k} V^j_h b_{k-j+1} \right) e^{-kz} &= \tilde{b}(z) \tilde{V}_h(z), \\
\sum_{k=1}^{\infty} \left( \sum_{j=1}^{k} V^j_h b_{k-j} \right) e^{-kz} &= \tilde{b}(z) \tilde{V}_h(z), \\
\sum_{k=1}^{\infty} \left( \sum_{j=1}^{k} V^{j-1}_h b_{k-j+1} \right) e^{-kz} &= \tilde{b}(z) \tilde{V}_h(z), \\
\sum_{k=1}^{\infty} \left( \sum_{j=1}^{k} V^{j-1}_h b_{k-j} \right) e^{-kz} &= \tilde{b}(z) e^{-z} \tilde{V}_h(z).
\end{align*}
\]

Further we have

\[
\sum_{k=0}^{\infty} \left( \frac{1}{2} \tau^\alpha A_h (V^k_h + V^{k+1}_h) e^{-kz} \right) = \frac{1}{2} \tau^\alpha A_h (e^z + 1) \tilde{V}_h(z).
\]

Thus we get

\[
\begin{align*}
V^1_h \tilde{b}(z) (e^z - 1) + \tilde{b}(z) e^{2z} \left( \tilde{V}_h(z) - V^1_h e^{-z} \right) - \tilde{b}(z) e^z \left( \tilde{V}_h(z) - V^1_h e^{-z} \right) \\
- 2\tilde{b}(z) e^z \tilde{V}_h(z) + 2\tilde{b}(z) \tilde{V}_h(z) + \tilde{b}(z) \tilde{V}_h(z) - \tilde{b}(z) e^{-z} \tilde{V}_h(z) + \frac{1}{2} \tau^\alpha A_h (e^z + 1) \tilde{V}_h(z)
\end{align*}
\]

\[
= \sum_{k=0}^{\infty} \tau^\alpha (-A_h u_{0h}) e^{-kz},
\]

which implies that, with \( z_\tau \) defined by (21),

\[
\tilde{V}_h(z) = \left( \psi(z) + \frac{\tau^\alpha}{2} A_h (e^z + 1) \right)^{-1} \sum_{k=0}^{\infty} \tau^\alpha (-A_h u_{0h}) e^{-kz} = (\xi^\alpha + \tau^\alpha A_h)^{-1} (-\tau^\alpha A_h) u_0 \left( \frac{2}{e^z + 1} \right) \left( \sum_{j=0}^{\infty} e^{-jz} \right).
\]

With \( \zeta = e^{-z} \), we may write \( \tilde{V}_h(z) = \sum_{n=0}^{\infty} V^n_h e^{-nz} = \sum_{n=0}^{\infty} V^n_h \zeta^n \). Using the Taylor expansion of the analytic function around the origin, we have, for \( \rho \) small enough, see Lubich et al. [25, (3.9)] and Jin et al. [11],

\[
V^n_h = \frac{1}{2\pi i} \int_{|\zeta| = \rho} \left( \sum_{n=0}^{\infty} V^n_h \zeta^n \right) d\zeta = -\frac{1}{2\pi i} \int_{\rho} e^{zn} \tilde{V}_h(z) \, dz, \tag{28}
\]
where the contour \( \Gamma^0 := \{ z = -\ln(\rho) + iy : |y| \leq \pi \} \) is oriented counterclockwise. By deforming the contour \( \Gamma^0 \) to \( \Gamma_\tau \) defined by \( (24) \) and using the periodicity of the exponential function, we obtain \( (23) \).

Subtracting \( (23) \) from \( (19) \), we have

\[
v_h(t_n) - V^n_h = I_1 + I_2,
\]

where

\[
I_1 = \frac{1}{2\pi i} \int_{\Gamma_\tau} e^{nz} (z^\alpha + \tau^\alpha A_h)^{-1} (-\tau^\alpha A_h) u_{0h} z^{-1} \, dz,
\]

\[
I_2 = \frac{1}{2\pi i} \int_{\Gamma_\tau} e^{nz} \left[ (z^\alpha + \tau^\alpha A_h)^{-1} (-\tau^\alpha A_h) u_{0h} z^{-1} - (z^\alpha + \tau^\alpha A_h)^{-1} (-\tau^\alpha A_h) u_{0h} \left( \frac{2}{e^z + 1} \right) \left( \sum_{j=0}^{\infty} e^{-jz} \right) \right] \, dz.
\]

For \( I_1 \), we have, by the resolvent estimate \( (7) \), with some constant \( c > 0 \),

\[
\| I_1 \| = \left\| \frac{1}{2\pi i} \int_{\Gamma_\tau} e^{nz} (z^\alpha + \tau^\alpha A_h)^{-1} (-\tau^\alpha A_h) u_{0h} z^{-1} \, dz \right\| \\
\leq C \int_{\Gamma_\tau} |e^{nz}| |u_0| |z|^{-1} \, dz \leq C \int_{\pi}^{\infty} e^{-cnr} \| u_0 \| r^{-1} \, dr \\
\leq C \int_{\pi}^{\infty} e^{-cnr} r \, dr \| u_0 \| \leq C n^{-1-a} \| u_0 \| \leq C \tau^{1+a} n^{-1-a} \| u_0 \|,
\]

where we use the variable change \( z = re^{i\theta} \) in the second inequality above.

For \( I_2 \), we have, by Lemma \( 2 \),

\[
\| I_2 \| = \left\| \frac{u_0}{2\pi i} \int_{\Gamma_\tau} e^{nz} \left[ (z^\alpha + \tau^\alpha A_h)^{-1} (-\tau^\alpha A_h) z^{-1} - (z^\alpha + \tau^\alpha A_h)^{-1} (-\tau^\alpha A_h) \left( \frac{2}{e^z + 1} \right) \left( \sum_{j=0}^{\infty} e^{-jz} \right) \right] \, dz \right\| \\
\leq C \int_{\Gamma_\tau} |e^{nz}| \left\| (z^\alpha + \tau^\alpha A_h)^{-1} (-\tau^\alpha A_h) z^{-1} - (z^\alpha + \tau^\alpha A_h)^{-1} (-\tau^\alpha A_h) \left( \frac{2}{e^z + 1} \right) \left( \sum_{j=0}^{\infty} e^{-jz} \right) \right\| \, dz \| u_0 \| \\
\leq C \| u_0 \| \int_{\Gamma_\tau} |e^{nz}| \left| (z^\alpha + |z|) \right| |dz| \leq C \| u_0 \| \int_{0}^{\pi} e^{-cnr} (r^\alpha + r) \, dr \\
\leq C \| u_0 \| \int_{0}^{\pi} e^{-cnr} (nr^\alpha n^{-1-a} + (nr)n^{-2}) \, dr \\
\leq C (n^{-1-a} + n^{-2}) \| u_0 \| \leq C (\tau^{1+a} n^{-1-a} + C \tau^2 n^{-2}) \| u_0 \|.
\]

Together these estimates complete the proof of Theorem \( 1 \). \( \square \)

**Remark 2** In \( (28) \), we follow the approach in Lubich et al. \[25, (3.9)\] and Jin et al. \[11\] and obtain the formula for \( V^n_h \) by using the Laplace transform method. By Lemma \( 1 \), we may
show that $V^n_h$ is well defined since $z^\alpha_\tau \in \Sigma_\theta$ for some $\theta \in (\pi/2, \pi)$. An alternative approach for obtaining the formula of $V^n_h$ is given in Xie et al. [17], where the authors do not apply the Taylor expansion of the analytic function around the origin, and instead directly calculate the inverse Laplace transform $V^n_h = \frac{1}{2\pi i} \int_{a-\pi i}^{a+\pi i} \tilde{V}_h(z) \, dz$ for some $a > 0$, see [17, Lemma 3.6]. In particular, they obtain the stability estimate of $V^n_h$, i.e., [17, Lemma 3.1], which implies that $\tilde{V}_h(z) = \sum_{n=0}^{\infty} V^n_h e^{-nz}$ is well defined for $z \in \mathbb{C}^+$. 

**Remark 3** In the above estimates for $\|I_1\|$ and $\|I_2\|$, the constants $c$ and $C$ depend on the angle $\theta$ of the integral path $\Gamma$. Moreover, the constant $C$ will tend to $\infty$ as $\theta \to \pi/2$. In our proof of Lemma 1, we require that $\theta$ is sufficiently close to $\pi/2$, so that the constant in Theorem 1 could be very large. The similar remark is also valid for the error estimates in Theorem 2 in the inhomogeneous case in the next section.

### 3.2 The Inhomogeneous Case with $f \neq 0$ and $u_0 = 0$

In this subsection, we will consider the error estimates of the time stepping method (11), (12) with $f \neq 0$ and $u_0 = 0$. We thus consider the following inhomogeneous problem, with $v_h(0) = 0$,

$$\frac{C}{6} D^\alpha_t v_h(t) + A_h v_h(t) = f_h(t), \quad 0 < t \leq T. \tag{29}$$

The abstract time stepping method (11), (12) for solving (29) is now reduced to, with $V^n_h = 0$,

$$V^n_h(b_{k+1} - b_k) + \frac{1}{2} \tau^\alpha A_h(V^k_h + V^{k+1}_h) = \tau^{\alpha-1} \int_{t_k}^{t_{k+1}} f_h(t) \, dt, \quad \text{for } k = 0, \tag{30}$$

$$V^n_h(b_{k+1} - b_k) + \sum_{j=1}^{k} \left(V^j_h - 2V^j_h + V^{j-1}_h\right)(b_{k-j+1} - b_{k-j}) \tag{31}$$

$$+ \frac{1}{2} \tau^\alpha A_h(V^k_h + V^{k+1}_h) = \tau^{\alpha-1} \int_{t_k}^{t_{k+1}} f_h(t) \, dt, \quad \text{for } k = 1, 2, \ldots.$$

We then have the following theorem:

**Theorem 2** Let $v_h(t_n)$ and $V^n_h$, $n = 0, 1, 2, \ldots$, be the solutions of (29) and (30), (31), respectively. Assume that $\int_0^t (t-s)^{-1+\epsilon} \|f'(s)\| \, ds < \infty$ for any $t > 0$ and $\epsilon > 0$. Then we have

$$\|V^n_h - v_h(t_n)\| \leq C \tau^{1+\alpha} \|f(0)\| + C \tau^{1+\alpha-\epsilon} \int_0^{t_n} (t_n - s)^{-1+\epsilon} \|f'(s)\| \, ds.$$

**Proof** Step 1: Find the exact solution of (29). Taking the Laplace transform in (29), we have

$$\hat{v}_h(z) = (z^\alpha + A_h)^{-1} \hat{f}_h(z),$$

which implies that, by using the inverse Laplace transform, with $n = 1, 2, \ldots$,

$$v_h(t_n) = \int_0^{t_n} E_h(t_n - t) f_h(t) \, dt, \tag{32}$$

where, with $\Gamma$ defined by (18),

$$E_h(t_n) = \frac{\tau^{\alpha-1}}{2\pi i} \int_{\Gamma} e^{nz} (z^\alpha + \tau^\alpha A_h)^{-1} \, dz. \tag{33}$$
Step 2: Find the approximate solutions $V^n_h$, $n = 1, 2, \ldots$ of (30), (31). Denote, with $\tau^\alpha$ and $\Gamma_{\tau}$ defined by (21) and (24), respectively,

$$E_j^\tau = \frac{\tau_\alpha - 1}{2\pi i} \int_{\Gamma_{\tau}} e^{\tau z} (\tau^\alpha + \tau^\alpha A_h)^{-1} \left( \frac{2}{e^z + 1} \right) dz, \quad j = 1, 2, \ldots,$$

we shall show that the solutions $V^n_h$, $n = 1, 2, \ldots$ of (30), (31) have the following form:

$$V^n_h = \int_0^{t_n} \tilde{E}_h(t_n - t) f_h(t) \, dt,$$

where

$$\tilde{E}_h(t) = \begin{cases} 
E_1^\tau, & t_0 < t < t_1, \\
E_2^\tau, & t_1 < t < t_2, \\
\vdots & \\
E_n^\tau, & t_{n-1} < t \leq t_n.
\end{cases}$$

In fact, multiplying the $(k + 1)$th equation in (30), (31) by $e^{-kz}$, $k = 0, 1, 2, \ldots$, we have

$$V^1_h(b_{k+1} - b_k)e^{-kz} + \frac{1}{2} \tau^\alpha A_h (V^k_h + V^{k+1}_h) e^{-kz} = \left( \tau^\alpha - 1 \int_{t_k}^{t_{k+1}} f_h(t) \, dt \right) e^{-kz}, \quad \text{for } k = 0,$$

$$V^1_h(b_{k+1} - b_k)e^{-kz} + \sum_{j=1}^k \left( V^{j+1}_h - 2V^j_h + V^{j-1}_h \right) (b_{j+1} - b_j)e^{-kz}$$

$$+ \frac{1}{2} \tau^\alpha A_h (V^k_h + V^{k+1}_h) e^{-kz} = \left( \tau^\alpha - 1 \int_{t_k}^{t_{k+1}} f_h(t) \, dt \right) e^{-kz}, \quad \text{for } k = 1, 2, \ldots$$

Summing the equations in (36), (37) from $k = 0$ to $k = \infty$, we get

$$\sum_{k=0}^{\infty} V^1_h(b_{k+1} - b_k)e^{-kz} + \sum_{k=1}^{\infty} \left[ \sum_{j=1}^k \left( V^{j+1}_h - 2V^j_h + V^{j-1}_h \right) (b_{j+1} - b_j) \right] e^{-kz}$$

$$+ \sum_{k=0}^{\infty} \frac{1}{2} \tau^\alpha A_h (V^k_h + V^{k+1}_h) e^{-kz} = \sum_{k=0}^{\infty} \left( \tau^\alpha - 1 \int_{t_k}^{t_{k+1}} f_h(t) \, dt \right) e^{-kz}.$$
We shall prove that, for \(j \geq n\) with any fixed \(n = 1, 2, \ldots\),
\[
\int_{I_\tau} e^{(n-j)z} (z^\alpha + \tau^\alpha A_h)^{-1}\left(\frac{2}{e^z + 1}\right) \, dz = 0. \tag{39}
\]
Assuming (39) holds at the moment, we then have, by (38),
\[
V^n_h = \sum_{j=0}^{n-1} \int_{t_j}^{t_{j+1}} f_h(t) \left[ \frac{\tau^\alpha - 1}{2\pi i} \int_{I_\tau} e^{(n-j)z} (z^\alpha + \tau^\alpha A_h)^{-1}\left(\frac{2}{e^z + 1}\right) \, dz \right] \, dt.
\]
which shows (34).

It remains to prove (39). We shall follow the idea of the proof for [17, Lemma 3.6]. By Cauchy integral formula, for any real number \(a \geq 0\), we have
\[
\int_{I_\tau} e^{(n-j)z} (z^\alpha + \tau^\alpha A_h)^{-1}\left(\frac{2}{e^z + 1}\right) \, dz
\]
\[
= \int_{a-i\pi}^{a+i\pi} e^{(n-j)z} (z^\alpha + \tau^\alpha A_h)^{-1}\left(\frac{2}{e^z + 1}\right) \, dz. \tag{40}
\]
To estimate the integral, we need to consider the bound of \(\left\| (z^\alpha + \tau^\alpha A_h)^{-1}\left(\frac{2}{e^z + 1}\right) \right\|\). We have, by the resolvent estimate (7),
\[
\left\| (z^\alpha + \tau^\alpha A_h)^{-1}\left(\frac{2}{e^z + 1}\right) \right\| \leq |z^\alpha|^{-1} \left|\frac{2}{e^z + 1}\right| \leq C|\psi(z)|^{-1}, \quad \forall z \in \Sigma_\theta, \tag{41}
\]
where \(z^\alpha\) and \(\psi\) are defined in (21) and (22), respectively.

Note that, by (22)
\[
\psi(z) = e^{-z}(e^z - 1)^3 \bar{b}(z) = e^{-z}(e^z - 1)^3 \left( \sum_{j=1}^{\infty} \frac{j^{2-\alpha}}{\Gamma(3-\alpha)} e^{-jz} \right)
\]
\[
= \frac{1}{\Gamma(3-\alpha)} e^{-z}(e^z - 1)^3 Li_{\alpha-2}(e^{-z}),
\]
where \(Li_{\alpha-2}(z)\) denotes the polylogarithm function. By the singular expansion of the function \(Li_p(e^{-z})\), \(p \in \mathbb{C}, \ p \neq 1, 2, \ldots\), we have, see Jin et al. [11, Lemma 3.2],
\[
Li_p(e^{-z}) \sim \Gamma(1-p)z^{p-1} + \sum_{k=0}^{\infty} (-1)^k \xi(p-k) z^k = \frac{1}{\Gamma(p)} e^{-z}(e^z - 1)^3 Li_{\alpha-2}(e^{-z})
\]
as \(z \to 0\), where \(\xi\) is the Riemann zeta function. Thus we have, with some suitable constants \(c_0, c_1, \ldots\),
\[
\psi(z) = \frac{1}{\Gamma(3-\alpha)} e^{-z}(e^z - 1)^3 Li_{\alpha-2}(e^{-z})
\]
\[
= e^{-z}(e^z - 1)^3 (z^{\alpha-3} + c_0 + c_1 z + \ldots)
\]
\[
= z^\alpha + \frac{1}{2} z^{\alpha+1} + \ldots, \quad \text{as } z \to 0,
\]
which implies that \(\lim_{z \to 0} \frac{z^\alpha}{\psi(z)} = 1\).
Further we observe that \( \lim_{z \to \infty} \frac{z^\alpha}{\psi(z)} = 0 \). Hence we get

\[
\left| \frac{z^\alpha}{\psi(z)} \right| \leq C, \quad \forall z \in \Sigma_\theta,
\]

which implies that, by (41),

\[
\left\| (z^\alpha + \tau^\alpha A_h)^{-1} \left( \frac{2}{e^z + 1} \right) \right\| \leq C|\psi(z)|^{-1} \leq C|z|^{-\alpha}, \quad \forall z \in \Sigma_\theta.
\]  

(42)

Therefore, by (40),

\[
\int_{a-i\pi}^{a+i\pi} e^{(n-j)z} (z^\alpha + \tau^\alpha A_h)^{-1} \left( \frac{2}{e^z + 1} \right) \frac{dz}{2\pi i} \leq C \int_{-\pi}^\pi e^{(n-j)a} a^{-\alpha} \, dy \leq C e^{(n-j)a} a^{-\alpha}.
\]  

(43)

Note that \( \lim_{a \to \infty} e^{(n-j)a} a^{-\alpha} = 0 \) for \( j \geq n \) with any fixed \( n = 1, 2, \ldots \), which implies that (39) holds.

We next consider the error estimates \( v_h(t_n) - V^n_h \). Subtracting (34) from (32), we have

\[
v_h(t_n) - V^n_h = \int_0^{t_n} (E_h - \tilde{E}_h)(t_n - t) f_h(t) \, dt
\]

\[
= \int_0^{t_n} (E_h - \tilde{E}_h)(t_n - t) [ f_h(0) + \int_0^t f'_h(s) \, ds ] \, dt
\]

\[
= f_h(0) \left[ \int_0^{t_n} (E_h - \tilde{E}_h)(s) \, ds \right] + \int_0^{t_n} \left[ \int_0^{t_n - t} (E_h - \tilde{E}_h)(s) \, ds \right] f'_h(t) \, dt
\]

\[
= f_h(0) \mathcal{E}_h(t_n) + \int_0^{t_n} \mathcal{E}_h(t_n - t) f'_h(t) \, dt,
\]

where

\[
\mathcal{E}_h(t) = \int_0^t (E_h - \tilde{E}_h)(s) \, ds, \quad 0 < t \leq T.
\]  

(44)

By Lemma 3, we have, with any small \( \epsilon > 0 \),
\[ \| v_h(t_n) - V_h^n \| \leq \| f_h(0) \| \| \mathcal{E}_h(t_n) \| + \int_0^{t_n} \| \mathcal{E}_h(t_n - t) \| \| f'_h(t) \| \, dt \]
\[ \leq C \tau^{1+\alpha} t_n^{-1} \| f_h(0) \| + C \int_0^{t_n} \tau^{1+\alpha-(t_n - t)^{-1+\epsilon}} \| f'_h(t) \| \, dt. \]  
(45)

Together these estimates complete the proof of Theorem 1. \(\square\)

4 Numerical Simulations

In this section, we will consider some numerical examples for solving both fractional ordinary differential equations and subdiffusion problems by using the time stepping method (11), (12).

4.1 Fractional Ordinary Differential Equation

In this subsection, we shall consider the numerical simulations for solving the following fractional ordinary differential equation, with \(0 < \alpha < 1\),
\[ \frac{C}{6} D_t^\alpha y(t) + \lambda y(t) = g(t), \quad 0 < t \leq T, \]  
(46)
\[ y(0) = y_0, \]  
(47)
where \(g : \mathbb{R} \to \mathbb{R}\) is a suitable function, \(y_0 \in \mathbb{R}\) is the initial value and \(\lambda > 0\).

Let \(0 = t_0 < t_1 < \cdots < t_N = T\) be a partition of \([0, T]\) and \(\tau\) the step size. Let \(Y^j \approx y(t_j), j = 0, 1, \ldots, N\) denote the approximations of \(y(t_j)\). The time stepping method (12) for solving (46), (47) can be written as
\[ \sum_{j=0}^{n} w_j Y^{n-j} + \frac{\tau^\alpha \lambda}{2} (Y^{n-1} + Y^n) = \tau^{\alpha-1} \int_{t_{n-1}}^{t_n} g(t) \, dt, \quad n = 1, 2, \ldots, N, \]  
(48)
\[ Y^0 = y_0, \]  
(49)
where the weights \(w_j, j = 0, 1, 2, \ldots, N\) are defined as below.

For \(n = 1\), the time stepping method (48), (49) is reduced to
\[ w_0 Y^1 + w_1 Y^0 + \frac{\tau^\alpha \lambda}{2} (Y^0 + Y^1) = \tau^{\alpha-1} \int_{t_0}^{t_1} g(t) \, dt, \]
where, with \(b_j, j = 0, 1\) defined by (13),
\[ w_0 = -b_0 + b_1, \]
\[ w_1 = b_0 - b_1. \]

For \(n = 2\), the time stepping method (48), (49) is reduced to
\[ w_0 Y^2 + w_1 Y^1 + w_2 Y^0 + \frac{\tau^\alpha \lambda}{2} (Y^1 + Y^2) = \tau^{\alpha-1} \int_{t_1}^{t_2} g(t) \, dt, \]
where, with \(b_j, j = 0, 1, 2\) defined by (13),
\[ w_0 = -b_0 + b_1, \]
\[ w_1 = 2b_0 - 3b_1 + b_2, \]
\[ w_2 = -b_0 + 2b_1 - b_2. \]
For $n = 3$, the time stepping method (48), (49) is reduced to
\[
 w_0 Y^3 + w_1 Y^2 + w_2 Y^1 + w_3 Y^0 + \frac{\tau^\alpha}{2} (Y^2 + Y^3) = \tau^{\alpha-1} \int_{t_2}^{t_3} g(t) \, dt,
\]
where, with $b_j$, $j = 0, 1, 2, 3$ defined by (13),
\[
 w_0 = -b_0 + b_1,
 w_1 = 2b_0 - 3b_1 + b_2,
 w_2 = -b_0 + 3b_1 - 3b_2 + b_3,
 w_3 = -b_1 + 2b_2 - b_3.
\]

For $n \geq 4$, the time stepping method (48), (49) is reduced to
\[
 w_0 Y^n + w_1 Y^{n-1} + \cdots + w_n Y^0 + \frac{\tau^\alpha}{2} (Y^{n-1} + Y^n) = \tau^{\alpha-1} \int_{t_{n-1}}^{t_n} g(t) \, dt,
\]
where, with $b_j$, $j = 0, 1, 2, \ldots, n$ defined by (13),
\[
 w_0 = -b_0 + b_1,
 w_1 = 2b_0 - 3b_1 + b_2,
 w_l = -b_{l-2} + 3b_{l-1} - 3b_l + b_{l+1}, \quad l = 2, 3, \ldots, n-1,
 w_n = -b_{n-2} + 2b_{n-1} - b_n.
\]

**Example 1** Our first example is a homogeneous problem. Choose $g(t) = 0$ in (46) and the initial value $y_0 = 1$ in (47). In this case the problem has the following exact solution, with $\alpha \in (0, 1)$,
\[
 y(t) = E_{\alpha,1}(-\lambda t^\alpha) y_0 = E_{\alpha,1}(-\lambda t^\alpha),
\]
where $E_{\alpha,1}(z)$ denotes the Mittag–Leffler function.

We choose $T = 2$ and $\lambda = 1$. The exact solution can be calculated by using the MATLAB function `mlf.m`. We obtain the approximate solutions with the different step sizes $\tau = 1/20, 1/40, 1/80, 1/160$. In Table 1, we observe that the experimentally determined convergence order of the time stepping method (48), (49) is about $O(\tau^2)$ which is better than theoretical convergence order $O(\tau^{1+\alpha})$ for small $\alpha \in (0, 1)$. In Table 1, we also compare the errors and convergence orders of the time stepping method (48), (49) with the popular L1 scheme [11] and the modified L1 scheme [42]. It is well known that the L1 scheme has only $O(\tau)$ convergence due to the singularity of the solution of the fractional differential equation [11]. After correcting the starting step, the modified L1 scheme has the optimal convergence order $O(\tau^{2-\alpha})$ [42]. We observe that the time stepping method (48), (49) indeed captures the singularities of the problem more accurately than the L1 and modified L1 schemes. We remark that the modified L1 scheme has the convergence order $O(\tau^{2-\alpha})$, $\alpha \in (0, 1)$, however in order to observe this convergence order for small $\alpha$, we need to consider the error at sufficiently large $T$. For example, we indeed observe the convergence order $O(\tau^{2-\alpha})$ of the modified L1 scheme for $\alpha = 0.3$ when we choose $T \geq 10$. In Table 1, the convergence order of the modified L1 scheme is not close to $O(\tau^{2-\alpha})$ for $\alpha = 0.3$ since $T = 2$ is not big enough to observe the required convergence order. Since the purpose of this paper is to show the convergence orders of the time stepping method (48), (49), we will not study further the numerical behaviors of the modified L1 scheme.
Table 1  Time convergence orders in Example 1 at $T = 2$

| $\alpha$ | $\tau$ | L1 scheme [11] | Modified L2 scheme [42] | The method (48), (49) |
|---|---|---|---|---|
|   |   | Errors | Orders | Errors | Orders | Errors | Orders |
| 0.3 | 1/20 | 9.62e-4 | 1.66e-6 | 8.29e-6 | 1.66e-6 | | |
|   | 1/40 | 4.61e-4 | 1.06 | 0.64 | 5.09e-7 | 2.01 | |
|   | 1/80 | 2.13e-4 | 1.24 | 1.51 | 1.21e-7 | 2.07 | |
|   | 1/160 | 9.12e-5 | 1.22 | 2.06e-6 | 2.00 | |
| 0.6 | 1/20 | 2.29e-3 | 9.81e-5 | 1.99e-5 | 9.42e-6 | 2.01 | |
|   | 1/40 | 1.08e-3 | 3.96e-5 | 1.30 | 1.21e-6 | 2.02 | |
|   | 1/80 | 4.97e-4 | 1.51e-5 | 1.38 | 1.21e-6 | 2.02 | |
|   | 1/160 | 2.10e-4 | 1.24 | 5.35e-6 | 1.50 | |
| 0.9 | 1/20 | 4.28e-3 | 3.21e-4 | 2.86e-7 | 2.05 | |
|   | 1/40 | 2.06e-3 | 1.05 | 1.65e-4 | 1.04 | |
|   | 1/80 | 9.56e-4 | 1.10 | 7.10e-5 | 1.13 | |
|   | 1/160 | 4.07e-4 | 1.23 | 2.93e-5 | 1.27 | |

Table 2  Time convergence orders in Example 2 at $T = 1$

| $\alpha$ | $\tau = 1/10$ | $\tau = 1/20$ | $\tau = 1/40$ | $\tau = 1/80$ | $\tau = 1/160$ |
|---|---|---|---|---|---|
| 0.2 | 2.15e-4 | 1.27e-5 | 5.69e-6 | 1.41e-6 | 3.36e-7 |
|   | 4.07 | 1.16 | 2.01 | 2.07 | |
| 0.4 | 8.83e-5 | 2.34e-5 | 5.79e-6 | 1.42e-6 | 3.38e-7 |
|   | 1.91 | 2.01 | 2.02 | 2.07 | |
| 0.6 | 1.03e-4 | 2.52e-5 | 6.17e-6 | 1.50e-6 | 3.53e-7 |
|   | 2.03 | 2.03 | 2.03 | 2.08 | |
| 0.8 | 1.28e-4 | 3.16e-5 | 7.75e-6 | 1.88e-6 | 4.40e-7 |
|   | 2.02 | 2.02 | 2.04 | 2.09 | |

Example 2  Our second example is an inhomogeneous problem with initial value $y_0 = 0$. We choose $\lambda = 1$ and assume that the exact solution of (46) is $y(t) = t^\beta, \beta > 0$ and

$$g(t) = \frac{\Gamma(\beta + 1)}{\Gamma(\beta + 1 - \alpha)} t^{\beta - \alpha} + t^\beta.$$  

We choose $T = 1$ and obtain the approximate solutions with the different step sizes $\tau = 1/10, 1/20, 1/40, 1/80, 1/160$. In Table 2, we show the experimentally determined orders of convergences with $\beta = 1.1$ for the time stepping method (48), (49). We also observe that the convergence orders are about $O(\tau^2)$ which are better than the theoretical convergence order $O(\tau^{1+\alpha})$ for small $\alpha \in (0, 1)$.

Example 3  The final example for the fractional ordinary differential equation is an inhomogeneous problem with nonzero initial value. We choose $\lambda = 1$ and assume that the exact solution of (46) is $y(t) = t^\beta + 1, \beta > 0$. The initial value $y_0 = 1$ and

$$g(t) = \frac{\Gamma(\beta + 1)}{\Gamma(\beta + 1 - \alpha)} t^{\beta - \alpha} + t^\beta + 1.$$
We choose $T = 1$ and obtain the approximate solutions with the different step sizes $\tau = 1/10, 1/20, 1/40, 1/80, 1/160$. In Table 3, we show the experimentally determined orders of convergences with $\beta = 1.1$ for the time stepping method (48), (49). We also observe that the convergence orders are about $O(\tau^2)$ which are better than the theoretical convergence order $O(\tau^{1+\alpha})$ for small $\alpha \in (0, 1)$.

### 4.2 Subdiffusion Problem

Now we turn to the numerical examples for solving the following subdiffusion problem, with $0 < \alpha < 1$,

$$\frac{C}{0} D_t^\alpha u(t, x) - \frac{\partial^2 u(t, x)}{\partial x^2} = f(t, x), \quad 0 \leq t \leq T, \quad 0 < x < 1,$$

$$u(0, x) = u_0(x),$$

$$u(t, 0) = u(t, 1) = 0.$$

Let $0 = t_0 < t_1 < \ldots < t_N = T$ be a partition of the time interval $[0, T]$ and $\tau$ the time step size. Let $0 = x_0 < x_1 \ldots < x_M = 1$ be a partition of the space interval $[0, 1]$ and $h$ the space step size. Let $S_h \subset H^1_0(0, 1)$ be the piecewise linear finite element space defined by

$$S_h = \{ \chi \in C[0, 1] : \chi \text{ is the piecewise linear function defined on } [0, 1] \text{ and } \chi(0) = \chi(1) = 0 \}.$$

The finite element method of (50), (52) is to find $u_h(t) \in S_h$ such that

$$\left( \frac{C}{0} D_t^\alpha u_h(t), \chi \right) + (\nabla u_h(t), \nabla \chi) = (f_h(t), \chi), \quad \forall \chi \in S_h,$$

$$u_h(0) = P_h u_0,$$

where $P_h : L_2(0, 1) \to S_h$ denotes the $L_2$ projection operator.

Let $U^n \approx u_h(t_n), n = 0, 1, \ldots, N$ be the approximation of $u_h(t_n)$. We define the following time discretization scheme for solving $U^n \in S_h$, with $n = 1, 2, \ldots, N$, and for $\forall \chi \in S_h$,

$$\left( \sum_{j=0}^{n} w_j U^{n-j}, \chi \right) + \tau^\alpha \left( \nabla \frac{U^{n-1} + U^n}{2}, \nabla \chi \right) = \left( \tau^{\alpha - 1} \int_{t_{n-1}}^{t_n} f_h(t) \, dt, \chi \right),$$

### Table 3: Time convergence orders in Example 3 at $T = 1$

| $\alpha$ | $\tau = 1/10$ | $\tau = 1/20$ | $1/40$ | $1/80$ | $1/160$ |
|----------|----------------|----------------|--------|--------|--------|
| 0.2      | 1.64e-4        | 6.71e-5        | 2.02e-5| 5.00e-6| 1.19e-6|
|          | 1.29           | 1.73           | 2.01   | 2.07   |
| 0.4      | 3.21e-4        | 8.21e-5        | 2.04e-5| 5.03e-6| 1.19e-6|
|          | 1.96           | 2.00           | 2.02   | 2.07   |
| 0.6      | 3.46e-4        | 8.53e-5        | 2.10e-5| 5.15e-6| 1.22e-6|
|          | 2.01           | 2.01           | 2.02   | 2.08   |
| 0.8      | 3.86e-4        | 9.51e-5        | 2.34e-5| 5.71e-6| 1.34e-6|
|          | 2.02           | 2.02           | 2.03   | 2.08   |
where \( w_j, j = 0, 1, 2, \ldots, N \) are defined as in Sect. 4.1.

Let \( \varphi_1(x), \varphi_2(x), \ldots, \varphi_{M-1}(x) \) be the linear finite element basis functions defined by, with \( j = 1, 2, \ldots, M - 1, \)

\[
\varphi_j(x) = \begin{cases} 
\frac{x - x_{j-1}}{x_j - x_{j-1}}, & x_{j-1} < x < x_j, \\
\frac{x - x_{j+1}}{x_j - x_{j+1}}, & x_j < x < x_{j+1}, \\
0, & \text{otherwise.}
\end{cases}
\]

To find the solution \( U^n \in S_h, \ n = 0, 1, \ldots, N, \) we assume that

\[
U^n = \sum_{k=1}^{M-1} \alpha^n_k \varphi_k,
\]

for some coefficients \( \alpha^n_k, k = 1, 2, \ldots, M - 1. \) Choose \( \chi = \varphi_l, l = 1, 2, \ldots, M - 1 \) in (55), we have

\[
\sum_{j=0}^{n} w_j \left( \sum_{k=1}^{M-1} \alpha^n_k (\varphi_k, \varphi_l) \right) + \tau^n \sum_{k=1}^{M-1} \frac{\alpha^n_{k-1} + \alpha^n_k}{2} (\nabla \varphi_k, \nabla \varphi_l) \\
= \left( \tau^{n-1} \int_{t_{n-1}}^{t_n} f_h(t) \, dt, \varphi_l \right), \quad \forall \chi \in S_h,
\]

\[
U^0 = P_h u_0 = \sum_{k=1}^{M-1} \alpha^0_k \varphi_k,
\]

Denote

\[
\alpha^n = \begin{pmatrix} \alpha^n_1 \\ \alpha^n_2 \\ \vdots \\ \alpha^n_{M-1} \end{pmatrix}_{(M-1) \times 1}, \quad \mathbf{u}^0 = \begin{pmatrix} (u_0, \varphi_1) \\ (u_0, \varphi_2) \\ \vdots \\ (u_0, \varphi_{M-1}) \end{pmatrix}_{(M-1) \times 1},
\]

and

\[
F^n = \begin{pmatrix} 
\left( \tau^{n-1} \int_{t_{n-1}}^{t_n} f_h(t) \, dt, \varphi_1 \right) \\
\left( \tau^{n-1} \int_{t_{n-1}}^{t_n} f_h(t) \, dt, \varphi_2 \right) \\
\vdots \\
\left( \tau^{n-1} \int_{t_{n-1}}^{t_n} f_h(t) \, dt, \varphi_{M-1} \right) 
\end{pmatrix}_{(M-1) \times 1}.
\]

Further we denote the mass and stiffness metrics by

\[
M = \left( \varphi_k, \varphi_l \right)_{k,l=1}^{M-1} = \begin{pmatrix} 
\frac{2}{3} & 1 & 0 \\
0 & 1 & \frac{1}{6} \\
0 & \frac{1}{6} & \frac{1}{2} \\
\end{pmatrix}_{(M-1) \times (M-1)}
\]

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and
\[ S = \left((\nabla \varphi_k, \nabla \varphi_l)\right)_{k,l=1}^{M-1} = \begin{pmatrix} 2 & -1 & 0 \\ -1 & \ddots & \ddots \\ \vdots & \ddots & -1 \\ 0 & -1 & 2 \end{pmatrix}_{(M-1)\times(M-1)}, \]

respectively. Then the scheme (57), (58) can be written into the following matrix form
\[
\begin{align*}
\sum_{j=0}^{n} w_j n^{-j} + \tau^\alpha (M^{-1}S)^{n-1} + n \cdot 2 = M^{-1}F^n, \\
0 = M^{-1}u^0,
\end{align*}
\]
which can be solved by using the similar MATLAB programs as for solving (48), (49).

**Example 4** In this example, we shall consider a homogeneous subdiffusion problem. We choose \( f(t, x) = 0 \) and the initial value \( u_0(x) = x(1 - x) \) in (50), (52). In this case, the exact solution is
\[ u(t) = E_{\alpha,1}(-\tau^\alpha A)u_0, \]
where \( E_{\alpha,1}(z) \) is the Mittag–Leffler function and \( A = \frac{\hat{a}^2}{\partial x^2} \) with \( D(A) = H_0^1(0, 1) \cap H^2(0, 1) \).

In our numerical simulation, we let \( T = 2 \). Choose the space step size \( h = 2^{-10} \) and the different time step sizes \( \tau = 1/10, 1/20, 1/40, 1/80, 1/160 \), we get the different approximate solutions. The exact solution is calculated by using the MATLAB function `mlf.m`.

We observe that, in Table 4, the experimentally determined convergence orders are better than the theoretical convergence orders \( O(\tau^{1+\alpha}) \). For \( \alpha > 0.5 \), the table shows a second order convergence rate. We also compare the errors and convergence orders of the method (48), (49) with the popular L1 scheme [11] and the modified L1 scheme [42]. We see that the time stepping method (48), (49) captures the singularities of the problem more accurately than the L1 and modified L1 schemes.

**Example 5** Consider an inhomogeneous subdiffusion problem. Assume that the exact solution of (50)–(52) is \( u(t, x) = t^\beta x(1 - x), \ \beta > 0 \) and
\[ f(t, x) = x(1 - x)(\frac{\Gamma(\beta + 1)}{\Gamma(\beta + 1 - \alpha)} t^{\beta - \alpha}) + 2t^\beta. \]
The initial value \( u_0(x) = 0 \).

We choose \( T = 2 \) and \( \beta = \alpha \) which implies that the solution \( u(\cdot, x) \in C[0, T] \), but \( u(\cdot, x) \notin C^1[0, T] \) for any fixed \( x \). We choose the space step size \( h = 2^{-10} \) and the different time step sizes \( \tau = 1/10, 1/20, 1/40, 1/80, 1/160 \) to get the approximate solutions. In Table 5, we observe that the experimentally determined convergence orders are higher than the theoretical convergence orders \( O(\tau^{1+\alpha}) \).

**Example 6** Consider an inhomogeneous subdiffusion problem with nonzero initial value. Assume that the exact solution of (50)–(52) is \( u(t, x) = (t^\beta + 1)x(1 - x), \ \beta > 0 \) and
\[ f(t, x) = x(1 - x)(\frac{\Gamma(\beta + 1)}{\Gamma(\beta + 1 - \alpha)} t^{\beta - \alpha}) + 2t^\beta + 2. \]
Table 4 Time convergence orders in Example 4 at $T = 2$

| $\alpha$ | $\tau$ | $L_1$ scheme [11] | Modified $L_2$ scheme [42] | The method $((48), (49))$ |
|----------|--------|------------------|----------------------------|-----------------------------|
|          |        | Errors | Orders | Errors | Orders | Errors | Orders | Errors | Orders |
| 0.3      | 1/20   | 2.30e-4 | 4.59e-7 |        |        | 2.81e-3 |        |        |        |
|          | 1/40   | 1.10e-4 | 1.10e-7 | 1.76   | 1.80   | 9.96e-4 | 1.50   |        |        |
|          | 1/80   | 5.14e-5 | 2.61e-8 | 1.80   | 1.67   | 3.12e-4 |        |        |        |
|          | 1/160  | 2.20e-5 | 5.95e-9 | 1.93   |        | 9.74e-5 | 1.68   |        |        |
| 0.6      | 1/20   | 3.36e-4 |          | 2.44e-6 |        | 2.26e-4 |        |        |        |
|          | 1/40   | 1.60e-4 | 1.09e-6 | 1.30   | 2.00   | 5.62e-5 |        |        |        |
|          | 1/80   | 7.39e-5 | 4.42e-7 | 1.38   | 1.99   | 1.41e-5 |        |        |        |
|          | 1/160  | 3.14e-5 | 1.61e-7 | 1.45   | 1.99   | 3.60e-6 |        |        |        |
| 0.9      | 1/20   | 2.40e-4 |          | 2.43e-5 |        | 2.64e-5 |        |        |        |
|          | 1/40   | 1.11e-4 | 1.11e-5 | 1.12   | 2.33   | 5.25e-6 |        |        |        |
|          | 1/80   | 5.02e-5 | 4.90e-6 | 1.18   | 2.23   | 1.12e-6 |        |        |        |
|          | 1/160  | 2.11e-5 | 1.99e-6 | 1.29   | 2.07   | 2.66e-7 |        |        |        |

Table 5 Time convergence orders in Example 5 at $T = 2$

| $\alpha$ | $\tau = 1/10$ | 1/20 | 1/40 | 1/80 | 1/160 |
|----------|----------------|------|------|------|-------|
| 0.2      | 1.84e-2        | 3.49e-3 | 8.23e-4 | 2.82e-4 | 7.88e-5 |
|          | 2.39           | 2.08 | 1.54 | 1.83 |       |
| 0.4      | 4.58e-4        | 1.22e-4 | 2.53e-5 | 5.61e-6 | 1.23e-6 |
|          | 1.91           | 2.26 | 2.17 | 2.18 |       |
| 0.6      | 3.94e-5        | 6.38e-6 | 1.12e-6 | 2.13e-7 | 4.29e-8 |
|          | 2.62           | 2.50 | 2.39 | 2.31 |       |
| 0.8      | 6.87e-6        | 1.63e-6 | 4.01e-7 | 9.85e-8 | 2.33e-8 |
|          | 2.07           | 2.02 | 2.02 | 2.07 |       |

The initial value $u_0(x) = x(1-x)$.

We observe that the experimentally determined convergence orders depend on the smoothness of the solution with respect to the time variable $t$. In our numerical simulation, we choose $\beta \in (1, 2)$ which implies that $u(\cdot, x) \in C^1[0, T]$, but $u(\cdot, x) \notin C^2[0, T]$ for any fixed $x$. We choose $T = 2$ and the space step size $h = 2^{-10}$ and the different time step sizes $\tau = 1/10, 1/20, 1/40, 1/80, 1/160$ to get the approximate solutions. In Table 6, we show the experimentally determined orders of convergence with $\beta = 1.1$, and we see that the convergence orders are consistent with our theoretical results.

**Example 7** Consider an inhomogeneous subdiffusion problem in two-dimensional case. With $x = (x_1, x_2), x_1 \in [0, 1], x_2 \in [0, 1]$, assume that the exact solution of (50)-(52) is $u(t, x) = (t^\beta + 1) x_1(1-x_1)x_2(1-x_2), \beta > 0$ and

$$f(t, x) = x_1(1-x_1)x_2(1-x_2) \left( \frac{\Gamma(\beta + 1)}{\Gamma(\beta + 1 - \alpha)} t^{\beta - \alpha} + (2t^\beta + 2)(x_1(1-x_1) + x_2(1-x_2)) \right).$$

The initial value $u_0(x) = x_1(1-x_1)x_2(1-x_2)$.

We use the same parameters and the time and space step sizes as in Example 6 except in this example we need space partitions in both $x_1$ and $x_2$ directions. In Table 7, we show...
the experimentally determined convergence orders with $\beta = 1.1$. We see that the numerical results are consistent with the theoretical results for this example.

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Data Availability Data sharing not applicable to this article as no datasets were generated or analyzed during the current study.

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5 Appendix

In this Appendix, we shall prove the following three lemmas.
Lemma 1 Let \( \theta > \frac{\pi}{2} \) be close to \( \frac{\pi}{2} \). Let \( z_\tau \) be defined by (21), that is
\[
z_\tau = \frac{2}{e^z + 1} \psi(z), \quad z \in \Gamma_\tau,
\]
where \( \psi(z) \) is defined by (22) and \( \Gamma_\tau \) is defined by (24). Then there exists some \( \theta_0 \in \left( \frac{\pi}{2}, \pi \right) \), such that
\[
z_\tau^{\theta_0} \in \Sigma_{\theta_0} = \{ z : | \arg z | \leq \theta_0, \pi/2 < \theta_0 < \pi \}.
\]

Proof We first note that, after a direct calculation, with \( \zeta = e^{-z} \),
\[
z_\tau^{\alpha} = \frac{2}{e^z + 1} \psi(z) = 2 \left( \frac{1 - \zeta}{\zeta} \right) \left( \frac{1 - \zeta}{1 + \zeta} \right) \text{Li}_{\alpha-2}(\zeta),
\]
where \( \text{Li}_{\alpha-2} \) is the polylogarithm function, see Jin et al. [11].

We will divide the proof of this lemma into the following 3 steps.

Step 1. Choose \( z : \arg z = \frac{\pi}{2} \), \( 0 < |\Im z| < \pi \). We will only consider the case with \( 0 < \Im z < \pi \). Similarly we may consider the case with \( -\pi < \Im z < 0 \). Thus we have, with \( 0 < \Im z < \pi \),
\[
\zeta = e^{-z} = e^{-i\psi} = \cos \psi - i \sin \psi, \quad \text{for any } \psi \in (0, \pi).
\]

Step 2. We shall prove that \( z_\tau^{\alpha} \) satisfies
\[
0 < |\arg(z_\tau^{\alpha})| < \pi, \quad \text{for } z : \arg z = \frac{\pi}{2}, \quad 0 < \Im z < \pi,
\]
which implies that, there exists \( \theta_0 \in \left( \frac{\pi}{2}, \pi \right) \) such that
\[
z_\tau^{\theta_0} \in \Sigma_{\theta_0}, \quad \text{for } z : \arg z = \frac{\pi}{2}, \quad 0 < \Im z < \pi.
\]

To prove this we shall find the arguments of the terms \( \frac{(1-\zeta)^2}{\zeta} \), \( \frac{1-\zeta}{1+\zeta} \), and \( \text{Li}_{\alpha-2}(\zeta) \) in (62) for \( \zeta = e^{-z} \) with \( z : \arg z = \frac{\pi}{2} \), \( 0 < \Im z < \pi \), respectively.

Note that, with \( \psi \in (0, \pi) \),
\[
\frac{(1-\zeta)^2}{\zeta} = \frac{1}{\zeta} + \zeta - 2 = e^{i\psi} + e^{-i\psi} - 2 = 2 \cos \psi - 2,
\]
which implies that
\[
\arg \left( \frac{(1-\zeta)^2}{\zeta} \right) = \pi.
\]

Further we note that, with \( \psi \in (0, \pi) \),
\[
\frac{1-\zeta}{1+\zeta} = \frac{1-\cos \psi + i \sin \psi}{1+\cos \psi - i \sin \psi} = \frac{2i \sin \psi}{(1+\cos \psi)^2 + \sin^2 \psi},
\]
which implies that
\[
\arg \left( \frac{1-\zeta}{1+\zeta} \right) = \frac{\pi}{2}.
\]

Now we consider the argument of the term \( \text{Li}_{\alpha-2}(\zeta) \). By Wood [40, (13.1)], we have, with \( p \neq 1,2,\ldots, \)
\[
\frac{\text{Li}_p(\zeta)}{\Gamma(1-p)} = (-2\pi i)^{p-1} \sum_{k=0}^{\infty} \left( k+1 - \frac{\psi}{2\pi} \right)^{p-1} + (2\pi i)^{p-1} \sum_{k=0}^{\infty} (k+\frac{\psi}{2\pi})^{p-1}.
\]
Choose $p = \alpha - 2$ in (65), we have, with $\zeta = e^{-i\psi}$, $\psi \in (0, \pi)$, see Wang et al. [38],

$$\frac{Li_{\alpha-2}(\zeta)}{\Gamma(3-\alpha)} = (-2\pi i)^{\alpha-3} \sum_{k=0}^{\infty} \left( k + 1 - \frac{\psi}{2\pi} \right)^{\alpha-3}$$

$$+ (2\pi i)^{\alpha-3} \sum_{k=0}^{\infty} \left( k + \frac{\psi}{2\pi} \right)^{\alpha-3}$$

$$= (2\pi)^{\alpha-3} e^{-(\alpha-3)i} \sum_{k=0}^{\infty} \left( k + 1 - \frac{\psi}{2\pi} \right)^{\alpha-3}$$

$$+ (2\pi)^{\alpha-3} e^{-(\alpha-3)\frac{\psi}{2\pi}} \sum_{k=0}^{\infty} \left( k + 1 - \frac{\psi}{2\pi} \right)^{\alpha-3}$$

$$= (2\pi)^{\alpha-3} \left[ \cos \left( (3 - \alpha) \frac{\pi}{2} \right) (A(\psi)$$

$$+ B(\psi)) - i \sin \left( (3 - \alpha) \frac{\pi}{2} \right) (A(\psi) + B(\psi)) \right], \quad (66)$$

where

$$A(\psi) = \sum_{k=0}^{\infty} \left( k + \frac{\psi}{2\pi} \right)^{\alpha-3}, \quad B(\psi) = \sum_{k=0}^{\infty} \left( k + 1 - \frac{\psi}{2\pi} \right)^{\alpha-3}.$$ 

Both series converge for $\alpha \in (0, 1)$. Since for $\psi \in (0, \pi)$, we have $\left( k + \frac{\psi}{2\pi} \right)^{\alpha-3} > \left( k + 1 - \frac{\psi}{2\pi} \right)^{\alpha-3} > 0$, there holds

$$\frac{A(\psi) - B(\psi)}{A(\psi) + B(\psi)} \in (0, 1).$$

Note that $\cos \left( (3 - \alpha) \frac{\pi}{2} \right) < 0$ and $\sin \left( (3 - \alpha) \frac{\pi}{2} \right) > 0$ for $\alpha \in (0, 1)$, we have

$$\arg \left( Li_{\alpha-2}(\zeta) \right) = \frac{\pi}{2} + \arctan \left( \frac{A(\psi) - B(\psi)}{A(\psi) + B(\psi)} \left| \tan \left( \frac{3\pi}{2} - \alpha\frac{\pi}{2} \right) \right| \right)$$

$$= \frac{\pi}{2} + \arctan \left( \frac{A(\psi) - B(\psi)}{A(\psi) + B(\psi)} \tan \left( \frac{\pi}{2} - \alpha\frac{\pi}{2} \right) \right),$$

which implies that, since $\arctan(x)$ is increasing on $x \in (-\infty, \infty)$,

$$\frac{\pi}{2} < \arg \left( Li_{\alpha-2}(\zeta) \right) < \frac{\pi}{2} + \left( \frac{\pi}{2} - \frac{\pi\alpha}{2} \right). \quad (67)$$

Hence we get, by (63), (64), (67),

$$\arg(z_{\alpha}^{\tau}) = \arg \left[ \frac{2(1-\zeta)^2}{\zeta} \left( \frac{1-\zeta}{1+\zeta} \right) Li_{\alpha-2}(\zeta) \right]$$

$$\in \left( \frac{\pi}{2} + \frac{\pi}{2} + \frac{\pi}{2} + \frac{\pi}{2} + \frac{\pi}{2} + \left( \frac{\pi}{2} - \frac{\pi\alpha}{2} \right) \right)$$

$$= \left( 2\pi, 2\pi + \left( \frac{\pi}{2} - \frac{\pi\alpha}{2} \right) \right),$$

that is,

$$\arg(z_{\alpha}^{\tau}) \in (0, \frac{\pi}{2} - \frac{\alpha\pi}{2}).$$
which implies that, for some $\theta_0 \in \left(\frac{\pi}{2}, \pi\right)$,
\[ z_\alpha^\tau \in \Sigma_{\theta_0}, \quad \text{for } z : \arg z = \frac{\pi}{2}, \; 0 < \Im z < \pi. \]

Step 3. By continuity of $z_\alpha^\tau$ with respect to $z$, we see that, there exists $\theta_0 \in \left(\frac{\pi}{2}, \pi\right)$, such that
\[ z_\alpha^\tau \in \Sigma_{\theta_0}, \quad \text{for } z \in \Gamma_\tau, \]
where $\Gamma_\tau$ is defined by (24) with $\theta > \frac{\pi}{2}$ sufficiently close to $\frac{\pi}{2}$.

The proof of Lemma 1 is complete. \hfill \Box

**Lemma 2** Let $z_\tau$ be defined by (21), that is
\[ z_\tau = \frac{2}{e^z + 1} \psi(z), \quad z \in \Gamma_\tau, \]
where $\psi(z)$ is defined by (22) and $\Gamma_\tau$ is defined by (24). Then we have, with $z \in \Gamma_\tau$,
\[ |z^\alpha - z_\tau^\alpha| \leq C |z|^{\alpha + 2}, \quad (68) \]
and
\[ \| (z^\alpha + \tau^\alpha A_h)^{-1} (\tau^\alpha A_h) z^{-1} - (z_\tau^\alpha + \tau^\alpha A_h)^{-1} (\tau^\alpha A_h) \frac{2}{e^z + 1} \sum_{j=0}^{\infty} e^{-jz} \| \leq C |z|^{\alpha} + C |z|. \]

**Proof** For (68), we have
\[ z_\tau^\alpha - z^\alpha = \frac{2}{e^z + 1} \psi(z) - z^\alpha. \]
Note that
\[ \psi(z) = e^{-z} (e^z - 1)^3 \tilde{b}(z) = z^\alpha + \frac{1}{2} z^{\alpha + 1} + \ldots, \quad \text{as } z \to 0. \]
We then have
\[ z_\tau^\alpha - z^\alpha = \left( z^\alpha + \frac{1}{2} z^{\alpha + 1} + \ldots \right) \frac{2}{e^z + 1} - z^\alpha = c_1 z^{\alpha + 2} + \ldots, \quad \text{as } z \to 0, \]
which implies that, for small $\epsilon > 0$,
\[ |z^\alpha - z_\tau^\alpha| \leq C |z|^{\alpha + 2}, \quad \text{for } |z| \leq \epsilon. \]
For large $z$ with $z \in \Gamma_\tau$, by continuity of $\frac{z^\alpha - z_\tau^\alpha}{z^{\alpha + 2}} = \left( \frac{2 \psi(z)}{e^z + 1} - z^\alpha \right) \frac{1}{z^{\alpha + 2}}$, we see that
\[ |z^\alpha - z_\tau^\alpha| \leq C, \quad \text{for } |z| \geq \epsilon, \quad z \in \Gamma_\tau. \]
Thus we show that
\[ |z^\alpha - z_\tau^\alpha| \leq C |z|^{\alpha + 2}, \quad \forall \; z \in \Gamma_\tau. \]

Now we turn to (69). We have
\[ \left\| (z^\alpha + \tau^\alpha A_h)^{-1} (\tau^\alpha A_h) z^{-1} - (z_\tau^\alpha + \tau^\alpha A_h)^{-1} (\tau^\alpha A_h) \frac{2}{e^z + 1} \sum_{j=0}^{\infty} e^{-jz} \right\| \]
and, with $\epsilon > 0$,

$$
\|\mathcal{E}_h(t)\| \leq \begin{cases} 
C \tau^{1+\alpha} t_n^{-1}, & n = 1, 2, \ldots, \\
C \tau^{1+\alpha-\epsilon} t^{-1+\epsilon}, & \text{for } t \in (t_n, t_{n+1}), n = 1, 2, \ldots, \\
C \tau^\alpha, & \text{for } t \in (0, t_1).
\end{cases}
$$

Together these estimates complete the proof of Lemma 2.

**Lemma 3** Let $0 = t_0 < t_1 < \cdots < t_n < \cdots$ be the time partition of $[0, \infty)$ and $\tau$ the time step size. Let $\mathcal{E}_h(t)$ be defined by (44). We then have

$$
\|\mathcal{E}_h(t_n)\| \leq C \tau^{1+\alpha} t_n^{-1}, \quad n = 1, 2, \ldots,
$$

and, with $\epsilon > 0$,

$$
\|\mathcal{E}_h(t)\| \leq \begin{cases} 
C \tau^{1+\alpha-\epsilon} t^{-1+\epsilon}, & \text{for } t \in (t_n, t_{n+1}), n = 1, 2, \ldots, \\
C \tau^\alpha, & \text{for } t \in (0, t_1).
\end{cases}
$$
Proof We follow the idea of the proof for [17, Lemma 3.9]. We first show (72). By (33) and (35), we have

\begin{align}
   E_h(t_n) &= \int_{t_0}^{t_n} (E_h - \tilde{E}_h)(t) \, dt \\
   &= \int_{t_0}^{t_n} \left[ \frac{\tau^{\alpha - 1}}{2\pi i} \int_{\Gamma} e^{\frac{z^\alpha}{\tau} + \tau^\alpha A_h}^{-1} \, dz \right] \, dt \\
   &\quad - \sum_{j=1}^{n} \int_{t_{j-1}}^{t_j} \left[ \frac{\tau^{\alpha - 1}}{2\pi i} \int_{\Gamma} e^{\frac{z^\alpha}{\tau} + \tau^\alpha A_h}^{-1} \left( \frac{2}{e^z + 1} \right) \, dz \right] \, dt \\
   &= \frac{\tau^{\alpha}}{2\pi i} \int_{\Gamma} (e^{nz} - 1) z^{-1} (z^\alpha + \tau^\alpha A_h)^{-1} \, dz \\
   &\quad - \frac{\tau^{\alpha}}{2\pi i} \int_{\Gamma} (e^{nz} - 1)(1 - e^{-z})^{-1} (z^\alpha + \tau^\alpha A_h)^{-1} \left( \frac{2}{e^z + 1} \right) \, dz.
\end{align}

(74)

Note that, see [17, Lemma 3.9],

\begin{align}
   \int_{\Gamma} z^{-1} (z^\alpha + \tau^\alpha A_h)^{-1} \, dz &= 0, \\
\end{align}

(75)

and

\begin{align}
   \int_{\Gamma} (1 - e^{-z})^{-1} (z^\alpha + \tau^\alpha A_h)^{-1} \left( \frac{2}{e^z + 1} \right) \, dz &= 0,
\end{align}

(76)

where \( \Gamma \) and \( \Gamma_t \) are defined by (18) and (24), respectively. We remark that if the integral over \( \Gamma \) is divergent, caused by the singularity of the underlying integrand near the origin, then \( \Gamma \) should be deformed so that the origin lies at its left side. We then have

\begin{align*}
   E_h(t_n) &= \frac{\tau^{\alpha}}{2\pi i} \int_{\Gamma/\Gamma_t} e^{nz} \left( z^\alpha + \tau^\alpha A_h \right)^{-1} \, dz \\
   &\quad + \frac{\tau^{\alpha}}{2\pi i} \int_{\Gamma_t} e^{nz} \left[ z^{-1} (z^\alpha + \tau^\alpha A_h)^{-1} \\
   &\quad - (1 - e^{-z})^{-1} (z^\alpha + \tau^\alpha A_h)^{-1} \left( \frac{2}{e^z + 1} \right) \right] \, dz \\
   &= I_1 + I_2.
\end{align*}

For \( I_1 \), we have, by the resolvent estimate (7), with some constant \( c > 0 \),

\begin{align}
   \| I_1 \| &\leq C \tau^\alpha \int_{\pi}^{\infty} e^{-cnr} r^{-\alpha} \, dr \leq C \tau^\alpha \int_{\pi}^{\infty} e^{-cnr} \, dr \leq C \tau^\alpha n^{-1} \leq C \tau^{1+\alpha} t_n^{-1}.
\end{align}

For \( I_2 \), we have, with some constant \( c > 0 \),

\begin{align}
   \| I_2 \| &\leq C \tau^\alpha \int_{\Gamma_t} e^{nz} \left[ z^{-1} (z^\alpha + \tau^\alpha A_h)^{-1} \\
   &\quad - (1 - e^{-z})^{-1} (z^\alpha + \tau^\alpha A_h)^{-1} \left( \frac{2}{e^z + 1} \right) \right] \, dz \\
   &\leq C \tau^\alpha \int_{\Gamma_t} |e^{nz}| |dz| \leq C \tau^\alpha \int_{0}^{\pi} e^{-cnr} \, dr \leq C \tau^\alpha n^{-1} \leq C \tau^{1+\alpha} t_n^{-1},
\end{align}

\( \Box \)
where we have used the following estimate
\[
\left\| z^{-1}(z^\alpha + \tau^\alpha A_h)^{-1} - (1 - e^{-z})^{-1}(z^\alpha + \tau^\alpha A_h)^{-1}\left(\frac{2}{e^z + 1}\right) \right\| \leq C, \quad z \in \Sigma_\theta, \tag{77}
\]
which can be proved similarly as for the proof of (69). Thus we get
\[
\|E_h(t_n)\| \leq \|I_1\| + \|I_2\| \leq C\tau^{1+\alpha}t_n^{-1}, \quad n = 1, 2, \ldots,
\]
which shows (72).

We now turn to the proof of (73). We first consider the case with \( t \in (t_n, t_{n+1}) \), \( n = 1, 2, \ldots \). By (33) and (35), we have
\[
E_h(t) = \int_0^t (E_h(s) - \tilde{E}_h(s)) \, ds
= \int_0^{t_n} E_h(s) \, ds + \int_{t_n}^t E_h(s) \, ds - \int_0^{t_n} \tilde{E}_h(s) \, ds - \int_{t_n}^t \tilde{E}_h(s) \, ds
= \frac{\tau^\alpha - 1}{2\pi i} \int_f \left[ \int_0^{t_n} e^{tz} \, dz \right] (z^\alpha + \tau^\alpha A_h)^{-1} \, dz
+ \frac{\tau^\alpha - 1}{2\pi i} \int_f \left[ \int_{t_n}^t e^{tz} \, dz \right] (z^\alpha + \tau^\alpha A_h)^{-1} \, dz
- \sum_{j=1}^n \frac{\tau^\alpha - 1}{2\pi i} \int_{f_{j-1}}^{f_j} e^{(n+1)z} (z^\alpha + \tau^\alpha A_h)^{-1} \left(\frac{2}{e^z + 1}\right) \, dz \, ds
- \int_{t_n}^t \frac{\tau^\alpha - 1}{2\pi i} \int_{f_{j-1}}^{f_j} e^{(n+1)z} (z^\alpha + \tau^\alpha A_h)^{-1} \left(\frac{2}{e^z + 1}\right) \, dz \, ds
= \frac{\tau^\alpha}{2\pi i} \int_f \left[ e^{nz} - 1 \right] (z^\alpha + \tau^\alpha A_h)^{-1} \, dz + \frac{\tau^\alpha}{2\pi i} \int_f \left[ e^{\frac{tz}{\tau}} - e^{nz} \right] (z^\alpha + \tau^\alpha A_h)^{-1} \, dz
- \frac{\tau^\alpha}{2\pi i} \int_{f_{j-1}}^{f_j} \left( \sum_{j=1}^n e^{jz} \right) (z^\alpha + \tau^\alpha A_h)^{-1} \left(\frac{2}{e^z + 1}\right) \, dz
- \frac{\tau^\alpha}{2\pi i} \int_{f_{j-1}}^{f_j} \left(\frac{t}{\tau} - n\right) e^{(n+1)z} (z^\alpha + \tau^\alpha A_h)^{-1} \left(\frac{2}{e^z + 1}\right) \, dz.
\tag{78}
\]
Hence we have, by (75) and (76),
\[
E_h(t) = \int_0^t (E_h(s) - \tilde{E}_h(s)) \, ds
= \frac{\tau^\alpha}{2\pi i} \int_f e^{nz} (z^\alpha + \tau^\alpha A_h)^{-1} \, dz + \frac{\tau^\alpha}{2\pi i} \int_f \left[ e^{\frac{tz}{\tau}} - e^{nz} \right] (z^\alpha + \tau^\alpha A_h)^{-1} \, dz
- \frac{\tau^\alpha}{2\pi i} \int_{f_{j-1}}^{f_j} e^{nz} (z^\alpha + \tau^\alpha A_h)^{-1} \left(\frac{2}{e^z + 1}\right) \, dz
- \frac{\tau^\alpha}{2\pi i} \int_{f_{j-1}}^{f_j} \left(\frac{t}{\tau} - n\right) e^{(n+1)z} (z^\alpha + \tau^\alpha A_h)^{-1} \left(\frac{2}{e^z + 1}\right) \, dz
= \frac{\tau^\alpha}{2\pi i} \int_{f_{j-1}}^{f_j} e^{\frac{tz}{\tau} - 1} (z^\alpha + \tau^\alpha A_h)^{-1} \, dz.
\]
Thus we get
\[
\|II_1\| = \left\| \frac{\tau^a}{2\pi i} \int_{\Gamma_{r}} e^{\frac{t}{\tau}z} \left( z^\alpha (z^\alpha + \tau^\alpha A_h)^{-1} (z^\alpha + \tau^\alpha A_h)^{-1} \frac{2}{e^z + 1} \right) \right\| = C \tau^a \int_{\pi}^{\infty} e^{-c_\tau \tau t}\left| r^{-1} - \alpha \right| dr \\
\leq C \tau^a \int_{\pi}^{\infty} e^{-c_\tau \tau t} dr \leq C \tau^a \frac{T}{t} \leq C \tau^{1+\alpha} t^{-1} \leq C \tau^{1+\alpha} t^{-1} + \epsilon.
\]

For $II_2$, by (77), we have, with some constants $c > 0$ and $\epsilon > 0$, noting that $t \in (t_n, t_{n+1})$, $n = 1, 2, \ldots$,
\[
\|II_2\| \leq C \tau^a \int_{0}^{\pi} e^{-cnr} dr \leq C \tau^a n^{-1} \leq C \tau^{1+\alpha} t^{-1} \leq C \tau^{1+\alpha} t^{-1} + \epsilon.
\]

For $II_3$, we have
\[
II_3 = \frac{\tau^a}{2\pi i} \int_{\Gamma_{r}} e^{\frac{t}{\tau}z} \left( z^\alpha (z^\alpha + \tau^\alpha A_h)^{-1} (z^\alpha + \tau^\alpha A_h)^{-1} \frac{2}{e^z + 1} \right) \right\| = C \tau^a \int_{\pi}^{\infty} e^{-c_\tau \tau t}\left| r^{-1} - \alpha \right| dr \\
\leq C \tau^a \frac{T}{t} \leq C \tau^{1+\alpha} t^{-1} \leq C \tau^{1+\alpha} t^{-1} + \epsilon.
\]

Following the proof of (69), we may show that, with $z \in \Gamma_{r}$,
\[
\left\| e^{(\frac{t}{\tau}-n)z} - 1 \right\| \leq C \left( \frac{t}{\tau} - n \right) \left\| z \right\|.
\]

Combining this estimate with (79) and using the similar argument as for the estimate of $II_2$, we get, noting that $t \in (t_n, t_{n+1})$, $n = 1, 2, \ldots$,
\[
\|II_3\| \leq C \tau^a \int_{0}^{\pi} e^{-cnr} \left( \frac{t}{\tau} - n \right) r dr \leq C \tau^a \int_{0}^{\pi} e^{-cnr} r dr \\
\leq C \tau^a n^{-2} \leq C \tau^{1+\alpha} t^{-1} + \epsilon.
\]

Thus we get
\[
\|E_h(t)\| \leq \|II_1\| + \|II_2\| + \|II_3\| \leq C \tau^{1+\alpha} t^{-1} + \epsilon,
\]

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which shows (73) for the case $t \in (t_n, t_{n+1})$, $n = 1, 2, \ldots$.

Finally we show (73) for the case $t \in (0, t_1]$. In this case, the estimate of $\|II_3\|$ is reduced to, noting that $t \in (0, t_1] = (0, \tau]$,

$$\|II_3\| \leq C \tau^\alpha \int_0^\pi e^{0r} \left( \frac{t}{\tau} - 0 \right) r \, dr = C \tau^\alpha \int_0^\pi r \, dr \leq C \tau^\alpha.$$

Together these estimates complete the proof of Lemma 3. \hfill \Box

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