The calculation problem of thermodynamic processes in a steam turbine

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Abstract. This paper covers the calculation of aerodynamic processes in a steam turbine using the modern information technologies and computational methods, that are contributed to the increasing the accuracy of the calculations. The practical significance is the development and application of the model of aerodynamic processes in a steam turbine, and determination of limits and prospects with using of proposed model. The aerodynamic processes in a turbine are characterized by the air and heat flow non-uniformity, significantly affect the reliability and efficiency of the turbine. The calculation was performed taking into account the complex geometry of the turbine, and can be applied to any turbine of similar design with minor changes.

1 Introduction

At present, the question about the optimization problem of installation and exploitation of steam turbines is the actual. With the development of modern technology and industry needs to the exploitation of turbines, requirements are the more stringent associated with the reliability and efficiency of their operation. A large number of existing turbines is practically close to the elaboration its resource. Therefore, the introduction of more modern units is required. The fundamentals of the theory of heat transfer and analysis results of transfer processes are required to assess the reliability and efficiency of the facility. Therefore, these data should be taken into account in designing of steam turbines. Thermal systems modelling include the problems of optimal control of thermal modes, due to which we can choose the best from different implementations. The optimization of thermal modes is reduced to the solution of heat conduction problem. Mathematical modelling of thermal processes in technogenic systems is relevant at the present. Due to it, we can check the correctness of engineering ideas and correct errors at the stage of designing by the simple, low-cost means. The mathematical model is represented by the scheme «model – algorithm – program», and must contain the structure, characteristic features of the process and should be described by the equation system or functional relations. After the designing, it is necessary to determine the real values of temperature at significant points of the steam facility and analyze the compliance with required values.

2 Problem statement

The main equations of air dynamics are:

− Navier-Stokes motion equations

\[
\begin{align*}
\frac{\partial v_x}{\partial t} + v_x \frac{\partial v_x}{\partial x} + v_y \frac{\partial v_y}{\partial y} + v_z \frac{\partial v_z}{\partial z} &= -\frac{1}{\rho} \frac{\partial P}{\partial x} + \frac{\mu}{\rho} \left( \frac{\partial^2 v_x}{\partial x^2} + \frac{\partial^2 v_x}{\partial y^2} + \frac{\partial^2 v_x}{\partial z^2} \right) + f_x, \\
\frac{\partial v_y}{\partial t} + v_x \frac{\partial v_y}{\partial x} + v_y \frac{\partial v_y}{\partial y} + v_z \frac{\partial v_z}{\partial z} &= -\frac{1}{\rho} \frac{\partial P}{\partial y} + \frac{\mu}{\rho} \left( \frac{\partial^2 v_y}{\partial x^2} + \frac{\partial^2 v_y}{\partial y^2} + \frac{\partial^2 v_y}{\partial z^2} \right) + f_y, \\
\frac{\partial v_z}{\partial t} + v_x \frac{\partial v_z}{\partial x} + v_y \frac{\partial v_z}{\partial y} + v_z \frac{\partial v_z}{\partial z} &= -\frac{1}{\rho} \frac{\partial P}{\partial z} + \frac{\mu}{\rho} \left( \frac{\partial^2 v_z}{\partial x^2} + \frac{\partial^2 v_z}{\partial y^2} + \frac{\partial^2 v_z}{\partial z^2} \right) + f_z,
\end{align*}
\]

− continuity equation

\[\rho' + (\rho v_x)' + (\rho v_y)' + (\rho v_z)' = 0.\]

− state equation

\[P = \epsilon \frac{\rho RT}{M},\]

where \( V = \{v_x, v_y, v_z\} \) are velocity vector components; \( P \) is a pressure; \( \rho \) is a density; \( M \) is the molar mass; \( R \) is the universal gas constant; \( \mu \) is the turbulent exchange coefficient; \( T \) is the temperature, \( \epsilon \) is the coefficient describing the deviation of pressure superheated steam from the ideal gas.
We assume that the air environment is initially in quiescence. Therefore, the initial conditions have the form:

\[
    u = 0, \quad w = 0, \quad P = P_a,
\]

where \( P_a \) is the initial pressure.

The system of equations (1) and (2) are considered with the following boundary conditions:

- on an impervious boundary

\[
    \rho, \eta \frac{\partial v_z}{\partial n} = \tau_x(t), \quad \rho, \eta \frac{\partial v_x}{\partial \theta} = \tau_y(t), \quad \rho, \eta \frac{\partial v_y}{\partial n} = \tau_y(t),
\]

\[
    v_z = 0, \quad v_x = 0, \quad v_y = 0, \quad \frac{\partial P}{\partial n} = 0;
\]

- on the lateral permeable borders

\[
    \frac{\partial v_z}{\partial n} = 0, \quad \frac{\partial v_x}{\partial n} = 0, \quad \frac{\partial v_y}{\partial n} = 0, \quad \frac{\partial P}{\partial n} = 0;
\]

- on the source

\[
    v_z = U, \quad v_x = V, \quad v_y = W, \quad \frac{\partial P}{\partial n} = 0;
\]

where \( U, V, W \) are components of velocity vector on the source; \( \tau_x, \tau_y \) are components of tangential shear stress.

The system of Navier-Stokes’ equations in the cylindrical coordinate system has the form:

\[
    \frac{\partial v_z}{\partial t} + v_r \frac{\partial v_z}{\partial r} + v_x \frac{\partial v_z}{\partial x} + v_y \frac{\partial v_z}{\partial y} + \frac{v_z^2}{r} + v_z \frac{\partial v_z}{\partial z} = -\frac{1}{\rho} \frac{\partial P}{\partial r} + \mu \left( \frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial v_z}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 v_z}{\partial \theta^2} - \frac{2}{r} \frac{\partial v_x}{\partial \theta} + \frac{3}{r^2} \frac{\partial^2 v_z}{\partial z^2} \right) + f_z,
\]

\[
    \frac{\partial v_x}{\partial t} + v_r \frac{\partial v_x}{\partial r} + v_x \frac{\partial v_x}{\partial x} + v_y \frac{\partial v_x}{\partial y} + \frac{v_x^2}{r} + v_x \frac{\partial v_x}{\partial z} = -\frac{1}{\rho} \frac{\partial P}{\partial \theta} + \mu \left( \frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial v_x}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 v_x}{\partial \theta^2} + \frac{2}{r} \frac{\partial v_y}{\partial \theta} + \frac{3}{r^2} \frac{\partial^2 v_x}{\partial z^2} \right) + f_x,
\]

\[
    \frac{\partial v_y}{\partial t} + v_r \frac{\partial v_y}{\partial r} + v_x \frac{\partial v_y}{\partial x} + v_y \frac{\partial v_y}{\partial y} + \frac{v_y^2}{r} + v_y \frac{\partial v_y}{\partial z} = -\frac{1}{\rho} \frac{\partial P}{\partial z} + \mu \left( \frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial v_y}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 v_y}{\partial \theta^2} + \frac{2}{r} \frac{\partial v_x}{\partial \theta} + \frac{3}{r^2} \frac{\partial^2 v_y}{\partial z^2} \right) + f_y.
\]

The continuity equation (2) in the cylindrical coordinate system has the form:

\[
    \frac{\partial \rho}{\partial t} + \frac{\partial (\rho v_z)}{\partial r} + \frac{\partial (\rho v_x)}{\partial x} + \frac{\partial (\rho v_y)}{\partial y} + \frac{\partial (\rho v_z)}{\partial z} = 0,
\]

where \( \tau_x, \tau_y \) are components of the stress tensor.

The equation (5) in the case of axial symmetry has the form:

\[
    \frac{\partial \rho}{\partial t} + \frac{1}{r} \frac{\partial (\rho v_z)}{\partial r} + \frac{\partial (\rho v_z)}{\partial z} = 0.
\]

3 The state equation

The main equation for the superheated steam is the equation for the specific Gibbs energy, consisting of two parts – relating to idealization as \( \gamma^0 \) and describing real component \( \gamma^r \):

\[
    g(p, T) / RT = \gamma(\pi, \tau) = \gamma(\pi, \tau)^0 + \gamma(\pi, \tau)^r
\]

where \( \pi = p / p^* \) and \( \tau = T^* / T \), \( p^* = 1 MPa \), \( T^* = 540 K \).

From the relation for the specific volume

\[
    \frac{v P}{RT} = \pi \gamma_a, \quad \gamma_a = \left( \frac{\partial \gamma}{\partial \pi} \right)
\]

follows the next:

\[
    \frac{\partial \gamma_a}{\partial \pi} = \left( \frac{\partial \gamma}{\partial \pi} \right)^0 = \left( \frac{\partial \gamma}{\partial \pi} \right)^r.
\]

4 Turbulence model

We used the model of Abramovich-Sekundow, which takes into account very important factors such as the presence of hard walls, the prehistory of the flow, convective and diffusion turbulent pulsation transfer:

\[
    \frac{\partial v_{\text{mep}}}{\partial t} + \frac{\partial v_{\text{mep}}}{\partial x_j} = \sum_{i=1}^k \left( \delta \frac{v_{\text{mep}}}{\partial x_i} \frac{\partial v_{\text{mep}}}{\partial x_i} \right),
\]

\[
    D = \left( \sum_{i=1}^k \frac{\partial v_{\text{mep}}}{\partial x_i} \frac{\partial v_{\text{mep}}}{\partial x_i} \right),
\]

\[
    f(z) = 0.2 \frac{z^2 + 1.47z + 0.2}{z^2 - 1.47z + 1},
\]

where \( k = 2, \gamma = 50, \beta = 0.06 \), \( L_{\text{min}} \) is the minimum distance to a solid wall; \( v_{\text{mep}} \) is the molecular viscosity, \( v_{\text{mep}} \) is the turbulent viscosity.

Turbulence model (10) is considered with the boundary condition \( v_{\text{mep}} \) at \( t, x, y, z \) \( \left| v_{\text{mep}} \right| = \left( \frac{\partial v_{\text{mep}}}{\partial x_i} \right) = 0 \).

Complete model (10) with initial condition:

\[
    \left( \begin{array}{l} v_{\text{mep}} \end{array} \right) = \left( \begin{array}{l} v_0 \end{array} \right).
\]
The next equation is used to calculate values of dynamic viscosity $\nu_{\text{max}}$:

$$\nu_{\text{max}} = \nu_0(\tau)I^r(\tau, \delta)\nu^r,$$  \hspace{1cm} (11)

where $\nu^r = 55,071 \times 10^{-6}$ Pa s; $\tau = T/T^*$; $T$ is the temperature, [K]; $T^* = 647,226$ K; $\delta = \rho/\rho^*$; $\rho$ is a density, [kg/m$^3$]; $\rho^* = 317,763$ kg/m$^3$; $\nu_0 = \nu_0/v$; $\nu_0$ is the dynamic viscosity of water vapor in the vapor density

$$\nu_0(\tau) = \nu_{0.5}^{-1}(\sum_{i=0}^{\infty} H_{1,i})(1/\tau J^{-1})^{(\delta-1)^{1/2}},$$  \hspace{1cm} (12)

where $H_0 = 1$, $H_1 = 0.978197$, $H_2 = 0.579829$, $H_4 = -0.202354$.

The function $\lambda_1(\delta)$ is defined:

$$\lambda_1(\delta) = b_0 + b_1\delta + b_2 \exp\left[ B_1(1 + B_2)^{1/2} \right],$$

where $b_0 = -0.39707$; $b_1 = 0.4$; $b_2 = 1.06$; $B_1 = -0.171$; $B_2 = 2.392$, and the function $\lambda_2(\tau, \delta)$ is defined:

$$\lambda_2(\tau, \delta) = \left[ \frac{d_1}{10} + d_2 \right] \delta^{0.5} \exp\left[ C_1(1 - \delta^{0.5}) \right] + d_3 \delta \exp\left[ \frac{Q}{(1 + Q)} \left( 1 - \delta^{0.5} \right) \right] + d_4 \exp\left[ C_2 \delta^{0.5} + C_3 \delta \right],$$

where $Q$ and $S$ are functions of the magnitude $\Delta r = |r - l|$: $C_i$:

$$Q = 2 + C_3/\Delta r^{0.6}; S = \left[ \frac{1}{\Delta r} \right] \text{for } \tau \geq 1;$$

$$S = C_4/\Delta r^{0.6} \text{for } \tau < 1.$$

The coefficients $d_i$ and $C_i$ have the next values:

$$d_1 = 0.0701309; \quad d_2 = 0.0118520; \quad d_3 = 0.00169937;$$

$$d_4 = -1.0200; \quad C_1 = 0.642857;$$

$$C_2 = -4.11717; \quad C_3 = -6.17937; \quad C_4 = 0.00308976;$$

$$C_5 = 0.0822994; \quad C_6 = 10.0932.$$

The equation (14) is applicable with the following values of the temperature and pressure: $p \leq 100$ MPa for $0 \leq T \leq 500°C$; $p \leq 70$ MPa for $500°C \leq T \leq 650°C$; $p \leq 40$ MPa for $650°C \leq T \leq 800°C$.

The error values in the liquid field at the temperatures 25-200 °C and pressures up to 5 MPa is equaled to 1.5 % at higher temperatures up to 300°C - 2 %. For the water steam at temperatures up to 550 °C under pressure 0.1 MPa error is equal to 1.5 %, under pressures up to 40 MPa – 3 %. The equation (18), in contrast to the theoretical conclusions, determines not infinite, but finite conductivity value at the critical point, which does not allow to estimate the error values near its critical point.

6 Splitting schemes into physical processes

The initial aerodynamic model is divided into three subtasks according to the of the pressure amendment method [1–4]. The first subtask is representative by the diffusion-convection problem on the basis of which the velocity field are calculated at the intermediate time step:

$$\frac{\frac{\bar{v}_1 - v_1}{\tau}}{v_1} + \frac{\frac{\bar{v}_2 - v_2}{\tau}}{v_2} + \frac{\frac{\bar{v}_3 - v_3}{\tau}}{v_3} = \mu \left[ \frac{1}{\bar{r}} \frac{\partial^2 (v_1)}{\partial \bar{r}^2} + \frac{\partial^2 (v_2)}{\partial \bar{e}^2} \right] + f_r;$$

$$\frac{\frac{\bar{v}_1 - v_1}{\tau}}{v_1} + \frac{\frac{\bar{v}_2 - v_2}{\tau}}{v_2} + \frac{\frac{\bar{v}_3 - v_3}{\tau}}{v_3} = \mu \left[ \frac{1}{\bar{r}} \frac{\partial^2 (v_1)}{\partial \bar{r}^2} + \frac{\partial^2 (v_2)}{\partial \bar{e}^2} \right] + f_r;$$

$$\frac{\frac{\bar{v}_1 - v_1}{\tau}}{v_1} + \frac{\frac{\bar{v}_2 - v_2}{\tau}}{v_2} + \frac{\frac{\bar{v}_3 - v_3}{\tau}}{v_3} = \mu \left[ \frac{1}{\bar{r}} \frac{\partial^2 (v_1)}{\partial \bar{r}^2} + \frac{\partial^2 (v_2)}{\partial \bar{e}^2} \right] + f_r.$$
Calculation of pressure distribution (the second subtask):
\[ \frac{\partial P}{\partial t} + \frac{1}{r} \frac{\partial}{\partial r} \left( r \rho v_r \right) + \frac{\partial}{\partial z} \left( \rho v_z \right) = \frac{\tau}{r} \frac{\partial}{\partial r} \left( r \frac{\partial P}{\partial r} \right) + \frac{\tau}{\rho} \frac{\partial^2 P}{\partial z^2} \]

or with consideration the state equation
\[ \frac{\partial}{\partial t} \left( \rho v_r \right) + \frac{r}{\rho} \frac{\partial}{\partial r} \left( r \frac{\partial P}{\partial r} \right) = \tau \frac{\partial}{\partial z} \left( \rho v_z \right) = \frac{\tau}{\rho} \frac{\partial^2 P}{\partial z^2} \]

The simplified hydrostatic model of water motion is used as the initial approximation for this problem. It is significantly decreased the calculation time.

The third subtask is determined the distribution of the steam velocity at the upper time layer by the explicit formulas:
\[ \frac{\dot{v}_r - \ddot{v}_r}{\tau} = -1 \frac{\partial P}{\rho \partial r}, \quad \frac{\dot{v}_z - \ddot{v}_z}{\tau} = -1 \frac{\partial P}{\rho \partial z} \]

where \( \tau \) is a time step; \( \dot{v} \) is a value of velocity field on the previous time layer; \( \ddot{v} \) is a value of velocity field on the intermediate time layer; \( \dot{v} \) is on the current time layer.

7 Software description

The input model parameters are the next: rotation frequency of the turbine, the range of output speeds at the turbine blades, number of blades, the number of nozzle channels, the width of the nozzle channel to the impeller, the vapor pressure of the working wheels. The calculations were performed in three functional areas 1 – 3. The location of areas which were determined by the velocity field is given in Fig. 1.

Fig. 1. The geometry of turbine housing and the nozzle grid.
Calculation of pressure distribution (the second subtask):

\[
\rho \frac{\partial^2 P}{\partial r^2} + \rho \frac{\partial^2 P}{\partial \theta^2} + \rho g = \frac{\partial \rho}{\partial z} 
\]

or with consideration the state equation

\[
\frac{\partial P}{\partial r} = \frac{\partial \rho}{\partial z} 
\]

The simplified hydrostatic model of water motion is used as the initial approximation for this problem. It is significantly decreased the calculation time.

The third subtask is determined the distribution of the steam velocity at the upper time layer by the explicit formulas:

\[
\hat{v}_r = v_r - \tau \frac{\partial v_r}{\partial t}, \quad \hat{v}_z = v_z - \tau \frac{\partial v_z}{\partial t}
\]

where \( \tau \) is a time step; \( v \) is a value of velocity field on the previous time layer; \( \hat{v} \) is a value of velocity field on the intermediate time layer; \( \hat{v} \) is on the current time layer.

8 Software description

The input model parameters are the next: rotation frequency of the turbine, the range of output speeds at the turbine blades, number of blades, the number of nozzle channels, the width of the nozzle channel to the impeller, the vapor pressure of the working wheels. The calculations were performed in three functional areas 1–3. The location of areas which were determined by the velocity field is given in Fig. 1.

Fig. 1. The geometry of turbine housing and the nozzle grid.

The flow pattern inside a pair of working chambers (shown in a longitudinal and radial component of the velocity vector) is given in Fig. 2.

Fig. 2. The velocity of steam movement in working chamber.

The flow pattern inside a pair of working chambers is given in Fig. 2.

Fig. 3. Distribution fields of the main calculated physical quantities inside for the first working chamber.

8 Conclusion

The mathematical model of aerodynamic processes in the steam turbine was developed. The main equations are the next: the Navier-Stokes equations, continuity equations and state equations. The initial system of equations was determined in cylindrical coordinate system taking into account the axial symmetry of steam flow field in the turbine. The splitting schemes into physical processes (the pressure amendment method) was used for approximation of problem at the temporary variable. According to this method, the solution problem is calculated in three steps. The solution of diffusion-convection problem with high Peclet numbers is required in calculation of velocity field components without pressure. New difference schemes were obtained on the basis of the modification of the "cabaret" scheme and used for this problem solution. Owning to these difference schemes, the accuracy of diffusion-convection problem solution is increased in 2.5–3 times, compared to the traditional "cabaret" schemes, which are effective for solution such problems. The software implementation was performed on the basis of the developed algorithms. Results of numerical calculations of aerodynamics processes in the steam turbine were obtained.

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