CHRISTOFFEL TRANSFORMATIONS FOR
MATRIX ORTHOGONAL POLYNOMIALS IN THE REAL LINE AND
THE NON-ABELIAN 2D TODA LATTICE HIERARCHY

CARLOS ÁLVAREZ-FERNÁNDEZ, GERARDO ARIZNABARRETA, JUAN CARLOS GARCÍA-ARDILA, MANUEL MAÑAS,
AND FRANCISCO MARCELLÁN

ABSTRACT. Given a matrix polynomial \( W(x) \), matrix bi-orthogonal polynomials with respect to the sesquilinear form
\[
\langle P(x), Q(x) \rangle_W = \int P(x)W(x) \, d \mu(x) (Q(x))^\top, \quad P, Q \in \mathbb{R}^{p \times p}[x],
\]
where \( \mu(x) \) is a matrix of Borel measures supported in some infinite subset of the real line, are considered. Connection formulas between the sequences of matrix bi-orthogonal polynomials with respect to \( \langle \cdot, \cdot \rangle_W \) and matrix polynomials orthogonal with respect to \( \mu(x) \) are presented. In particular, for the case of nonsingular leading coefficients of the perturbation matrix polynomial \( W(x) \) we present a generalization of the Christoffel formula constructed in terms of the Jordan chains of \( W(x) \). For perturbations with a singular leading coefficient several examples by Durán et al are revisited. Finally, we extend these results to the non-Abelian 2D Toda lattice hierarchy.

CONTENTS

1. Introduction 1
1.1. Historical background and state of the art 2
1.2. Objectives, results and layout of the paper 4
1.3. On spectral theory of matrix polynomials 5
1.4. On orthogonal matrix polynomials 8
2. Connection formulas for Darboux transformations of Christoffel type 11
2.1. Connection formulas for bi-orthogonal polynomials 12
2.2. Connection formulas for the Christoffel–Darboux kernel 12
3. Monic matrix polynomial perturbations 14
3.1. The Christoffel formula for matrix bi-orthogonal polynomials 14
3.2. Degree one monic matrix polynomial perturbations 16
3.3. Examples 20
4. Singular leading coefficient matrix polynomial perturbations 25
5. Extension to non-Abelian 2D Toda hierarchies 27
5.1. Block Hankel moment matrices vs multi-component Toda hierarchies 27
5.2. The Christoffel transformation for the non-Abelian 2D Toda hierarchy 31
References 32

1. INTRODUCTION

This paper is devoted to the extension of the Christoffel formula to the Matrix Orthogonal Polynomials on the Real Line (MOPRL) and the non-Abelian 2D Toda lattice hierarchy.

1991 Mathematics Subject Classification. 42C05,15A23.

Key words and phrases. Matrix orthogonal polynomials, Block Jacobi matrices, Darboux–Christoffel transformation, Block Cholesky decomposition, Block LU decomposition, quasi-determinants, non-Abelian Toda hierarchy.

GA thanks financial support from the Universidad Complutense de Madrid Program “Ayudas para Becas y Contratos Complutenses Predoctorales en España 2011”.

MM & FM thanks financial support from the Spanish “Ministerio de Economía y Competitividad” research project MTM2012-36732-C03-01, Ortogonalidad y aproximación; teoría y aplicaciones.
1.1. Historical background and state of the art. In 1858 the German mathematician Elwin Christoffel [32] was interested, in the framework of Gaussian quadrature rules, in finding explicit formulas relating the corresponding sequences of orthogonal polynomials with respect to two measures \( d\mu \) (in the Christoffel’s discussion was just the Lebesgue measure \( d\mu = dx \)) and \( d\hat{\mu}(x) = p(x) d\mu(x) \), with \( p(x) = (x - q_1) \cdots (x - q_N) \) a signed polynomial in the support of \( d\mu \), as well as the distribution of their zeros as nodes in such quadrature rules, see [101]. The so called Christoffel formula is a very elegant formula from a mathematical point of view, and is a classical result which can be found in a number of orthogonal polynomials textbooks, see for example [29, 95, 51]. Despite these facts, we must mention that for computational and numerical purposes it is not so practical, see [51]. These transformations have been extended from measures to the more general setting of linear functionals. In the theory of orthogonal polynomials with respect to a moment linear functional \( u \in (\mathbb{R}[x])' \), an element of the algebraic dual (which coincides with the topological dual) of the linear space \( \mathbb{R}[x] \) of polynomials with real coefficients. Given a positive definite linear moment functional, i.e. \( \left| \langle u, x^{n+m} \rangle \right| > 0 \), \( \forall k \in \mathbb{Z}_+ := \{0, 1.2, \ldots \} \), there exists a nontrivial probability measure \( \mu \) such that (see [9], [29], [95]) \( \langle u, x^n \rangle = \int x^m d\mu(x) \). Given a moment linear functional \( u \), its canonical or elementary Christoffel transformation is a new moment functional given by \( \hat{u} = (x-a)u \) with \( a \in \mathbb{R} \), see [24, 29, 97]. The right inverse of a Christoffel transformation is called the Geronimus transformation. In other words, if you have a moment linear functional \( u \), its elementary or canonical Geronimus transformation is a new moment linear functional \( \tilde{u} \) such that \((x-a)\tilde{u} = u \). Notice that in this case \( \tilde{u} \) depends on a free parameter, see [54, 78]. The right inverse of a general Christoffel transformation is said to be a multiple Geronimus transformation, see [40]. All these transformations are referred as Darboux transformations, a name that was first given in the context of integrable systems in [77]. In 1878 the French mathematician Gaston Darboux, when studying the Sturm–Liouville theory in [35], explicitly treated these transformations, which appeared for the first time in [82]. In the framework of orthogonal polynomials on the real line, such a factorization of Jacobi matrices has been studied in [24] and [97]. They also play an important role in the analysis of bispectral problems, see [58] and [57].

An important aspect of canonical Christoffel transformations is its relations with LU factorization (and its flipped version, an UL factorization) of the Jacobi matrix. A sequence of monic polynomials \( \{P_n(x)\}_{n=0}^\infty \) associated with a nontrivial probability measure \( \mu \) satisfies a three term recurrence relation (TTRR, in short) \( xP_n(x) = P_{n+1}(x) + b_n P_n(x) + a_n^2 P_{n-1}(x) \), \( n \geq 0 \), with the convention \( P_{-1}(x) = 0 \). If we denote by \( P(x) = [P_0(x), P_1(x), \ldots]^T \), then the matrix representation of the multiplication operator by \( x \) is directly deduced from the TTRR and reads \( xP(x) = JP(x) \), where \( J \) is a tridiagonal semi-infinite matrix such that the entries in the upper diagonal are the unity. Assuming that \( a \) is a real number off the support of \( \mu \), then you have a factorization \( J - aI = LU \), where \( L \) and \( U \) are, respectively, lower unitriangular and upper triangular matrices. The important observation is that the matrix \( J \) defined by \( J - aI = UL \) is again a Jacobi matrix and the corresponding sequence of monic polynomials \( \{P_n(x)\}_{n=0}^\infty \) associated with the multiplication operator defined by \( J \) is orthogonal with respect to the canonical Christoffel transformation of the measure \( \mu \) defined as above.

For a moment linear functional \( u \), the Stieltjes function \( S(x) := \sum_{n=0}^\infty \frac{\langle u, x^n \rangle}{x^{n+1}} \) plays an important role in the theory of orthogonal polynomials, due to its close relation with the measure associated to \( u \) as well as its (rational) Padé Approximation, see [23, 63]. If you consider the canonical Christoffel transformation \( \hat{u} \) of the linear functional \( u \), then its Stieltjes function is \( \hat{S}(x) = (x-a)S(x) - u_0 \). This is a particular case of the spectral linear transformations studied in [102].

Given a bilinear form \( L : \mathbb{R}[x] \times \mathbb{R}[x] \rightarrow \mathbb{R} \) one could consider the following non-symmetric and symmetric bilinear perturbations

\[
\tilde{L}_1(p, q) = L(wp, q), \\
\tilde{L}_2(p, q) = L(p, wq), \\
\tilde{L}(p, q) = L(wp, wq),
\]

where \( w(x) \) is a polynomial. The study of these perturbations can be found in [25]. Taking into account the matrix representation of the multiplication operator by \( z \) is a Hessenberg matrix, the authors establish a relation between the Hessenberg matrices associated with the initial and the perturbed functional by using LU and QR factorization. They also give some algebraic relations between the sequences of orthogonal polynomials associated with these bilinear forms. The above perturbations can be seen as an extension of the Christoffel transformation for bilinear forms. When the bilinear form is defined by a nontrivial probability measure supported on the unit
circle, Christoffel transformations have been studied in [26] in the framework of CMV matrices, i.e. the matrix representation of the multiplication operator by $z$ in terms of an orthonormal Laurent polynomial basis. Therein, the authors state the explicit relation between the sequences of orthonormal Laurent polynomials associated with a measure and its Christoffel transformation, as well as its link with QR factorizations of such CMV matrices.

The theory of scalar orthogonal polynomials with respect to probability measures supported either on the real line or the unit circle is a standard and classic topic in approximation theory and it also has remarkable applications in many domains as discrete mathematics, spectral theory of linear differential operators, numerical integration, integrable systems, among others. Some extensions of such a theory have been developed more recently. One of the most exciting generalizations appears when you consider non-negative Hermitian-valued matrix of measures of size $p \times p$ on an $\sigma$-algebra of subsets of a space $\Omega$ such that each entry is countably additive and you are interested in the analysis of the Hilbert space of matrix valued functions of size $p \times p$ under the inner product associated with such a matrix of measures. This question appears in the framework of weakly stationary processes, see [89]. Notice that such an inner product pays the penalty of the non-commutativity of matrices as well as the existence of singular matrices with respect to the scalar case. By using the standard Gram-Schmidt method for the canonical linear basis of the linear space of polynomials with matrix coefficients a theory of matrix orthogonal polynomials can be studied. The paper by M. G. Krein [69] is credited as the first contribution in this topic. Despite they have been sporadically studied during the last half century, there is an exhaustive bibliography focused on inner products defined on the linear space of polynomials with matrix coefficients as well as on the existence and analytic properties of the corresponding sequences of matrix orthogonal polynomials in the real line (see [43], [42], [80], [88], [94]) and their applications in Gaussian quadrature for matrix-valued functions ([93]), scattering theory ([14], [53]) and system theory ([50]). The work [33] constitutes an updated overview on these topics.

But, more recently, an intensive attention was paid to the spectral analysis of second order linear differential operators with matrix polynomials as coefficients. This work was motivated by the Bochner’s characterization of classical orthogonal polynomials (Hermite, Laguerre and Jacobi) as eigenfunctions of second order linear differential equations with polynomial coefficients. The matrix case gives a more rich set of solutions. From the pioneering work [44] some substantial progress has been done in the study of families of matrix orthogonal polynomials associated to second order linear differential operators as eigenfunctions and their structural properties (see [13], [59], [60] as well as the survey [45]). Moreover, in [27] the authors showed that there exist sequences of orthogonal polynomials satisfying a first order linear matrix differential equation that constitutes a remarkable difference with the scalar case where such a situation does not appear. The spectral problem for second order linear difference operators with polynomial coefficients has been considered in [13] as a first step in the general approach. Therein four families of matrix orthogonal polynomials (as matrix relatives of Charlier, Meixner, Krawtchouk scalar polynomials and another one that seems not have any scalar relative) are obtained as illustrative examples of the method described therein.

It is also a remarkable fact that matrix orthogonal polynomials appear in the analysis of non standard inner products in the scalar case. Indeed, from the study of higher order recurrence relations that some sequences of orthogonal polynomials satisfy (see [44] where the corresponding inner product is analyzed as an extension of the Favard’s theorem and [48], where the connection with matrix orthogonal polynomials is stated), to the relation between standard scalar polynomials associated with measures supported on harmonic algebraic curves and matrix orthogonal polynomials deduced by a splitting process of the first ones (see [74]) you get an extra motivation for the study of matrix orthogonal polynomials. Matrix orthogonal polynomials appear in the framework of orthogonal polynomials in several variables when the lexicographical order is introduced. Notice that in such a case, the moment matrix has a Hankel block matrix where each block is a Hankel matrix i.e. it has a doubly Hankel structure, see [39].

Concerning spectral transformations, in [40] the authors show that the so called multiple Geronimus transformations of a measure supported in the real line yield a simple Geronimus transformation for a matrix of measures. This approach is based on the analysis of general inner products $\langle \cdot, \cdot \rangle$ such that the multiplication by a polynomial operator $h$ is symmetric and satisfies an extra condition $\langle h(x)p(x), q(x) \rangle = \int p(x)q(x)\,d\mu(x)$, where $\mu$ is a nontrivial probability measure supported on the real line. The connection between the Jacobi matrix associated to the sequence of scalar polynomials with respect to $\mu$ and the Hessenberg matrix associated with
the multiplication operator by \( h \) is given in terms of the so called UL factorizations. Notice that the connection between the Darboux process and the noncommutative bispectral problem has been discussed in [56]. The analysis of perturbations on the entries of the matrix of moments from the point of view of the relations between the corresponding sequences of matrix orthogonal polynomials was done in [30].

The seminal work of the Japanese mathematician Mikio Sato [91, 92] and later on of the Kyoto school [36, 37, 38] settled the basis for a Grassmannian and Lie group theoretical description of integrable hierarchies. Not much later Motohico Mulase [83] gave a mathematical description of factorization problems, dressing procedure, and linear systems as the keys for integrability. It was not necessary to wait too long, in the development of integrable systems theory, to find multicomponent versions of the integrable Toda equations, [98, 99, 100] which later on played a prominent role in the connection with orthogonal polynomials and differential geometry. The multicomponent versions of the KP hierarchy were analyzed in [21, 22] and [52, 70, 71] and in [72, 73] we can find a further study of the multi-component Toda lattice hierarchy, block Hankel/Toeplitz reductions, discrete flows, additional symmetries and dispersionless limits. For the relation with multiple orthogonal polynomials see [8, 11].

The work of Mark Adler and Pierre van Moerbeke was fundamental to the connection between integrable systems and orthogonal polynomials. They showed that the Gauss–Borel factorization problem is the keystone for this connection. In particular, their studies in the papers on the 2D Toda hierarchy and what they called the discrete KP hierarchy [3, 4, 5, 6, 7] clearly established –from a group-theoretical setup– why standard orthogonality of polynomials and integrability of nonlinear equations of Toda type where so close.

The relation of multicomponent Toda systems or non-Abelian versions of Toda equations with matrix orthogonal polynomials was studied, for example, in [80, 11] (on the real line) and in [81, 17] (on the unit circle).

The approach to the Christoffel transformations in this paper, which is based on the Gauss–Borel factorization problem, has been used before in different contexts. It has been applied for the construction of discrete integrable systems connected with orthogonal polynomials of diverse types,

i) The case of multiple orthogonal polynomials and multicomponent Toda was analyzed in [12].

ii) In [15] we dealt with the case of matrix orthogonal Laurent polynomials on the circle and CMV orderings.

iii) For orthogonal polynomials in several real variables see [16, 17] and [18] for orthogonal polynomials on the unit torus and the multivariate extension of the CMV ordering.

It is well known that there is a deep connection between discrete integrable systems and Darboux transformations of continuous integrable systems, see for example [41]. Finally, let us comment that, in the realm of several variables, in [17, 18, 19] one can find extensions of the Christoffel formula to the multivariate scenario with real variables and on the unit torus, respectively.

1.2. Objectives, results and layout of the paper. In this contribution, we focus our attention on the study of Christoffel transformations (Darboux transformations in the language of integrable systems [77], or Lévy transformations in the language of differential geometry [49]) for matrix sesquilinear forms. More precisely, given a matrix of measures \( \mu(x) \) and a matrix polynomial \( W(x) \) we are going to deal with the following matrix sesquilinear forms

\[
\langle P(x), Q(x) \rangle_W = \int P(x)W(x) \, d \mu(x)(Q(x))^\top.
\]

We will first focus our attention on the existence of matrix bi-orthogonal polynomials with respect to the sesquilinear form \( \langle \cdot, \cdot \rangle_W \) under some assumptions about the matrix polynomial \( W \). Once this is done, the next step will be to find an explicit representation of such bi-orthogonal polynomials in terms of the matrix orthogonal polynomials with respect to the matrix of measures \( d \mu(x) \). We start with what we call connection formulas in Proposition [18].

One of the main achievements of this paper is Theorem [2] where we extend the Christoffel formula to MOPRL with a perturbation given by an arbitrary degree monic matrix polynomial. For that aim we use the rich spectral theory available today for these type of polynomials, in particular tools like root polynomials and Jordan chains will be extremely useful, see [88, 76]. Following [59, 60, 27], some applications to the analysis of matrix orthogonal polynomials which are eigenfunctions of second order linear differential operators and related to polynomial perturbations of diagonal matrix of measures \( d \mu(x) \) leading to sesquilinear forms as \( \langle \cdot, \cdot \rangle_W \) will be considered.
Next, to have a better understanding of the singular leading coefficient case we concentrate on the study of some cases which generalize important examples given by Alberto Grünbaum and Antonio Durán in [45], in relation again with second order linear differential operators.

Finally, we see that these Christoffel transformations extend to more general scenarios in Integrable Systems Theory. In these cases we find the non-Abelian Toda hierarchy which is relevant in string theory. In general, we have lost the block Hankel condition, and we do not have anymore a matrix of measures but only a sesquilinear form. We show that Theorem 2 also holds in this general situation. At this point we must stress that for the non-Abelian Toda equation we can find Darboux transformations (or Christoffel transformations) in [90], see also [84], which contemplate only what it are called elementary transformations and their iteration. Evidently, their constructions do not cover by far what Theorem 2 does. There are many matrix polynomials that do not factor in terms of linear matrix polynomials and, therefore, they cannot be studied by means of the results in [90, 84]. We have been fortunate to have at our disposal the spectral theory of [88, 76] that at the moment of the publication of [90] was not so well known and under construction.

The layout of the paper is as follows. We continue this introduction with two subsections that give the necessary background material regarding the spectral theory of matrix polynomials and also of matrix orthogonal polynomials. Then, in §2, we give the connection formulas for bi-orthogonal polynomials and for the Christoffel–Darboux kernel, being this last result relevant to find the dual polynomials in the family of bi-orthogonal polynomials. We continue in §3 discussing the non singular leading coefficient case, i.e., the monic matrix polynomial perturbation. We find the Christoffel formula for matrix bi-orthogonal polynomials and, as an example, we consider the degree one monic matrix polynomial perturbations. We dedicate the rest of this section to discuss some examples. In §4 we start the exploration of the singular leading coefficient matrix polynomial perturbations and, despite we do not give a general theory, we have been able to successfully discuss some relevant examples. Finally, §5 is devoted to the study of the extension of the previous results to the non-Abelian 2D Toda lattice hierarchy.

1.3. On spectral theory of matrix polynomials. Here we give some background material regarding matrix polynomials. For further reading we refer the reader to [55].

**Definition 1.** Let $A_0, A_1, \ldots, A_N \in \mathbb{R}^{p \times p}$ be square matrices with real entries. Then

$$W(x) = A_N x^N + A_{N-1} x^{N-1} + \cdots + A_1 x + A_0$$

is said to be a matrix polynomial of degree $N$, $\deg W = N$. The matrix polynomial is said to be monic when $A_N = I_p$, where $I_p \in \mathbb{R}^{p \times p}$ denotes the identity matrix. The linear space of matrix polynomials with coefficients in $\mathbb{R}^{p \times p}$ will be denoted by $\mathbb{R}^{p \times p}[x]$.

**Definition 2.** We say that a matrix polynomial $W$ as in (2) is monic normalizable if $\det A_N \neq 0$ and say that $\tilde{W}(x) := A_N^{-1} W(x)$ is its monic normalization.

**Definition 3.** The spectrum, or the set of eigenvalues, $\sigma(W)$ of a matrix polynomial $W$ is the zero set of $\det W(x)$, i.e.,

$$\sigma(W) := Z(W) = \{a \in \mathbb{C} : \det W(a) = 0\}.$$

**Proposition 1.** A monic normalizable matrix polynomial $W(x)$, $\deg W = N$, has $N_p$ (counting multiplicities) eigenvalues or zeros; i.e., we can write

$$\det W(x) = \prod_{i=1}^{q} (x - \lambda_i)^{\alpha_i}$$

with $N_p = \alpha_1 + \cdots + \alpha_q$.

**Remark 1.** In contrast with the scalar case, there exist matrix polynomials which do not have a unique factorization in terms of degree one factors or even it could happen that the factorization does not exist. For example, the matrix polynomial

$$W(x) = I_2 x^2 - \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix} x$$
can be written as
\[
W(x) = (I_2x - \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}) (I_2x - \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}) \quad \text{or} \quad W(x) = (I_2x - \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix}) I_2x,
\]
but the polynomial
\[
W(x) = I_2x^2 - \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}
\]
cannot be factorized in terms of degree one matrix polynomials.

**Definition 4.**

i) Two matrix polynomials \(W_1, W_2 \in \mathbb{R}^{m \times m}[x]\) are said to be equivalent \(W_1 \sim W_2\) if there exist two matrix polynomials \(E, F \in \mathbb{R}^{m \times m}[x]\), with constant determinants (not depending on \(x\)), such that \(W_1(x) = E(x)W_2(x)F(x)\).

ii) A degree one matrix polynomial \(I_{Np}x - A \in \mathbb{R}^{Np \times Np}\) is called a linearization of a monic matrix polynomial \(W \in \mathbb{R}^{p \times p}[x]\) if
\[
I_{Np}x - A \sim \begin{bmatrix} W(x) & 0 \\ 0 & I_{(N-1)p} \end{bmatrix}
\]

**Definition 5.** Given a matrix polynomial \(W(x) = I_px^N + A_{N-1}x^{N-1} + \cdots + A_0\) its companion matrix \(C_1 \in \mathbb{R}^{Np \times Np}\) is
\[
C_1 := \begin{bmatrix} 0 & I_p & 0 & \ldots & 0 \\ 0 & 0 & I_p & \ldots & 0 \\ \vdots & \vdots & \ddots & \ddots & \vdots \\ 0 & 0 & 0 & \ldots & I_p \\ -A_0 & -A_1 & -A_2 & \ldots & -A_{N-1} \end{bmatrix}
\]

The companion matrix plays an important role in the study of the spectral properties of a matrix polynomial \(W(x)\), see for example [55, 75] and [76].

**Proposition 2.** Given a monic matrix polynomial \(W(x) = I_px^N + A_{N-1}x^{N-1} + \cdots + A_0\) its companion matrix \(C_1\) provides a linearization
\[
I_{Np}x - C_1 \sim \begin{bmatrix} W(x) & 0 \\ 0 & I_{(N-1)p} \end{bmatrix}
\]
where
\[
E(x) = \begin{bmatrix} B_{N-1}(x) & B_{N-2}(x) & B_{N-3}(x) & \ldots & B_1(x) & B_0(x) \\ -I_p & 0 & 0 & \ldots & 0 & 0 \\ 0 & -I_p & 0 & \ldots & 0 & 0 \\ 0 & 0 & -I_p & 0 & \ldots & 0 \\ \vdots & \vdots & \ddots & \ddots & \ddots & \vdots \\ 0 & 0 & 0 & \ldots & I_p & -I_p \end{bmatrix},
\]
\[
F(x) = \begin{bmatrix} I_p & 0 & 0 & \ldots & 0 & 0 \\ -I_p x & I_p & 0 & \ldots & 0 & 0 \\ 0 & -I_p x & I_p & \ldots & 0 & 0 \\ \vdots & \vdots & \ddots & \ddots & \ddots & \vdots \\ 0 & 0 & 0 & \ldots & I_p & 0 \\ 0 & 0 & 0 & \ldots & -I_p x & I_p \end{bmatrix},
\]

with \(B_0(x) := I_p, B_{r+1}(x) = xB_r(x) + A_{N-r-1}, \text{for } r \in \{0, 1, \ldots, N-2\}\).

From here one deduces the important
Proposition 3. The eigenvalues with multiplicities of a monic matrix polynomial coincide with those of its companion matrix.

Proposition 4. Any nonsingular monic matrix polynomial \( W(x) \in \mathbb{C}^{m \times m} \), \( \det W(x) \neq 0 \), can be represented
\[
W(x) = E(x_0) \text{diag}((x - x_0)^{\kappa_1}, \ldots, (x - x_0)^{\kappa_m}) F(x_0)
\]
at \( x = x_0 \in \mathbb{C} \), where \( E(x_0) \) and \( F(x_0) \) are nonsingular matrices and \( \kappa_1 \leq \cdots \leq \kappa_m \) are nonnegative integers. Moreover, \( \{\kappa_1, \ldots, \kappa_m\} \) are uniquely determined by \( W \) and they are known as partial multiplicities of \( W(x_0) \).

Definition 6. i) Given a monic matrix polynomial \( W(x) \in \mathbb{R}^{P \times P}[x] \) with eigenvalues and multiplicities \( \{\alpha_k, \kappa_k\}_{k=1}^q \), a non-zero vector \( v_{k,0} \in \mathbb{C}^P \) is said to be an eigenvector with eigenvalue \( \alpha_k \) whenever \( W(x_k)v_{k,0} = 0 \), \( v_{k,0} \in \text{Ker} W(x_k) \neq \{0\} \).

ii) A sequence of vectors \( \{v_{0,0}, v_{1,0}, \ldots, v_{1,m_i-1}\} \) is said to be a Jordan chain of length \( m_i \) corresponding to \( x_1 \in \sigma(W) \) if \( v_{0,0} \) is an eigenvector of \( W(x_1) \) and
\[
\left. \frac{1}{r!} \frac{d^r W}{dx^r} \right|_{x=x_1} v_{1,j-r} = 0, \quad j = 0, \ldots, m_i - 1.
\]

iii) A root polynomial at an eigenvalue \( x_0 \in \sigma(W) \) of \( W(x) \) is a non-zero vector polynomial \( v(x) \in \mathbb{C}^P[x] \) such that \( W(x_0)v(x_0) = 0 \). The multiplicity of this zero will be denoted by \( \kappa \).

iv) The maximal length of a Jordan chain corresponding to the eigenvalue \( \alpha_k \) is called the multiplicity of the eigenvector \( v_{0,0} \) and is denoted by \( m(\alpha_k) \).

The above definition generalizes the concept of Jordan chain for degree one matrix polynomials [1].

Proposition 5. The Taylor expansion of a root polynomial at a given eigenvalue \( x_0 \in \sigma(W) \)
\[
v(x) = \sum_{j=0}^{q} v_j (x - x_0)^j
\]
provides a Jordan chain \( \{v_0, v_1, \ldots, v_{k-1}\} \).

Proposition 6. Given an eigenvalue \( x_0 \in \sigma(W) \), with multiplicity \( s = \dim \text{Ker} W(x_0) \), we can construct \( s \) root polynomials
\[
v_i(x) = \sum_{j=0}^{\kappa_i - 1} v_{i,j} (x - x_0)^j, \quad i \in \{1, \ldots, s\},
\]
where \( v_i(x) \) is a root polynomial with the largest order \( \kappa_i \) among all root polynomials whose eigenvector does not belong to \( \mathbb{C}\{v_{1,0}, \ldots, v_{1-1,0}\} \).

Definition 7. A canonical set of Jordan chains of the monic matrix polynomial \( W(x) \) corresponding to the eigenvalue \( x_0 \in \sigma(W) \), in terms of the root polynomials described in Proposition 6, is the set of vectors
\[
\{v_{1,0}, v_{1,1}, \ldots, v_{s,0}, \ldots, v_{s,\kappa_r-1}\}
\]

Proposition 7. For a monic matrix polynomial \( W(x) \), the lengths \( \{\kappa_1, \ldots, \kappa_r\} \) of the Jordan chains in a canonical set of Jordan chains of \( W(x) \) corresponding to the eigenvalue \( x_0 \), see Definition 7, are the nonzero partial multiplicities of \( W(x) \) at \( x = x_0 \) described in Proposition 4.

Definition 8. For each eigenvalue \( x_i \in \sigma(W) \), with multiplicity \( \alpha_i \) and \( s_i = \dim \text{Ker} W(x_i) \), we choose a canonical set of Jordan chains
\[
\{v_{i,0}^{(j)}, \ldots, v_{i,\kappa_i-1}^{(j)}\}, \quad j = 1, \ldots, s_i,
\]
where
and, consequently, with partial multiplicities satisfying \( \sum_{j=1}^{s_i} \kappa_j^{(i)} = \alpha_i \). Thus, we can consider the following adapted root polynomials

\[
v_j^{(i)}(x) = \sum_{r=0}^{\kappa_j^{(i)}-1} v_{j,r}(x - x_i)^T.
\]

**Proposition 8.** Given a monic matrix polynomial \( W(x) \) the adapted root polynomials given in Definition 8 satisfy

\[
\frac{d^r}{dx^r} \bigg|_{x=x_i} (W(x)v_j^{(i)}(x)) = 0, \quad r = 0, \ldots, \kappa_j^{(i)} - 1, \quad j = 1, \ldots, s_i.
\]

### 1.4. On orthogonal matrix polynomials.

Recall that a sesquilinear form \( \langle \cdot, \cdot \rangle \) on the linear space \( \mathbb{R}^{p \times p}[x] \) is a map

\[
\langle \cdot, \cdot \rangle : \mathbb{R}^{p \times p}[x] \times \mathbb{R}^{p \times p}[x] \rightarrow \mathbb{R}^{p \times p},
\]

such that for any triple \( P, Q, R \in \mathbb{R}^{p \times p}[x] \) of matrix polynomials we have

1. (AP(x) + BQ(x), R(x)) = A \langle P(x), R(x) \rangle + B \langle Q(x), R(x) \rangle, \quad \forall A, B \in \mathbb{R}^{p \times p}.
2. \langle P(x), AQ(x) + BR(x) \rangle = \langle P(x), Q(x) \rangle A^T + \langle P(x), R(x) \rangle B^T, \quad \forall A, B \in \mathbb{R}^{p \times p}.

Here \( A^T \) denotes the transpose of \( A \), an antiautomorphism of order two in the ring of matrices.

**Definition 9.** A sesquilinear form \( \langle \cdot, \cdot \rangle \) is said to be non degenerate if the leading principal sub-matrices of the corresponding Hankel matrix of moments \( M := ((I_{p} x^j I_{p} x^k))_{j=0}^{\infty} \) are nonsingular, and nontrivial if \( \langle \cdot, \cdot \rangle \) is a symmetric matrix sesquilinear form and \( \langle P(x), P(x) \rangle \) is a positive definite matrix for all \( P(x) \in \mathbb{R}^{p \times p}[x] \) with nonsingular leading coefficient.

Given a sesquilinear form \( \langle \cdot, \cdot \rangle \), two sequences of polynomials \( \{P_n^{[1]}(x)\}_{n=0}^{\infty} \) and \( \{P_n^{[2]}(x)\}_{n=0}^{\infty} \) are said to be bi-orthogonal with respect to \( \langle \cdot, \cdot \rangle \) if

1. \( \deg(P_n^{[1]}(x)) = \deg(P_n^{[2]}(x)) = n \) for all \( n \in \mathbb{Z}_+ \).
2. \( \langle P_n^{[1]}(x), P_m^{[2]}(x) \rangle = \delta_{n,m} H_n \) for all \( n, m \in \mathbb{Z}_+ \)

where \( H_n \neq 0 \) and \( \delta_{n,m} \) is the Kronecker delta. Here, it is important to notice the order of the polynomials in the sesquilinear form; i.e., if \( n \neq m \) then \( \langle P_n^{[2]}(x), P_m^{[1]}(x) \rangle \) could be different from 0.

**Remark 2.** Recall that if \( A \) is a positive semidefinite (resp. definite) matrix, then there exists a unique positive semidefinite (resp. definite) matrix \( B \) such that \( B^2 = A \). \( B \) is said to be the square root of \( A \) (see [61], Theorem 7.2.6) and we denote it by \( B := A^{1/2} \). As in the scalar case, when \( \langle \cdot, \cdot \rangle \) is a sesquilinear form, we will write the matrix \( \langle P, P \rangle^{1/2} := \|P\| \).

Let

\[
\mu = \begin{bmatrix} \mu_{1,1} & \cdots & \mu_{1,p} \\ \vdots & \ddots & \vdots \\ \mu_{p,1} & \cdots & \mu_{p,p} \end{bmatrix}
\]

be a \( p \times p \) matrix of Borel measures in \( \mathbb{R} \). Given any pair of matrix polynomials \( P(x), Q(x) \in \mathbb{R}^{p \times p}[x] \) we introduce the following sesquilinear form

\[
\langle P(x), Q(x) \rangle = \int_{\mathbb{R}} P(x) \, d\mu(x)(Q(x))^T.
\]

In terms of the moments of the matrix of measures \( \mu \) we define the matrix moments as

\[
m_n := \int_{\mathbb{R}} x^n \, d\mu(x) \in \mathbb{R}^{p \times p}
\]

and arrange them in the semi-infinite block matrix and its k-th truncation

\[
M := \begin{bmatrix} m_0 & m_1 & m_2 & \cdots \\ m_1 & m_2 & m_3 & \cdots \\ m_2 & m_3 & m_4 & \cdots \\ \vdots & \vdots & \vdots & \ddots \end{bmatrix}, \quad M_{[k]} := \begin{bmatrix} m_0 & \cdots & m_{k-1} \\ \vdots & \ddots & \vdots \\ m_{k-1} & \cdots & m_{2k-2} \end{bmatrix}.
\]
Following [15], we can prove

**Proposition 9.** If \( \det M_{[k]} \neq 0 \) for \( k \in \{1, 2, \ldots \} \), then there exists a unique Gaussian factorization of the moment matrix \( M \) given by

\[
M = S_1^{-1} H (S_2)^{-\top},
\]

where \( S_1, S_2 \) are lower unitriangular block matrices and \( H \) is a diagonal block matrix

\[
S_i = \begin{bmatrix} I_p & 0 & 0 & \ldots \\ (S_i)_{1,0} & I_p & 0 & \ldots \\ (S_i)_{2,0} & (S_i)_{2,1} & I_p & \ldots \\ & & & \ddots \end{bmatrix}, \quad H = \begin{bmatrix} H_0 & 0 & 0 & \ldots \\ 0 & H_1 & 0 & \ddots \\ 0 & 0 & H_2 & \ddots \\ \vdots & \vdots & \ddots & \ddots \end{bmatrix}, \quad i = 1, 2,
\]

with \( (S_i)_{n,m}, H_n \in \mathbb{R}^{p \times p}, \forall n, m \in \{0, 1, \ldots \} \). If \( \mu = \mu^\top \), then we are dealing with a Cholesky block factorization with \( S_1 = S_2 \) and \( H = H^\top \).

For \( l \geq k \) we will also use the following bordered truncated moment matrix

\[
M_{[k,l]}^{[1]} := \begin{bmatrix} m_0 & \cdots & m_{k-1} \\ \vdots & \ddots & \vdots \\ m_{k-2} & \cdots & m_{2k-3} \\ m_l & \cdots & m_{l+k-1} \end{bmatrix},
\]

where we have replaced the last row of blocks, \([m_{k-1} \ldots m_{2k-2}]\), of the truncated moment matrix \( M_k \) by the row of blocks \([m_l \ldots m_{l+k-1}]\). We also need a similar matrix but replacing the last block column of \( M_k \) by a column of blocks as indicated

\[
M_{[k,l]}^{[2]} := \begin{bmatrix} m_0 & \cdots & m_{k-2} & m_l \\ \vdots & \ddots & \vdots & \vdots \\ m_{k-1} & \cdots & m_{2k-3} & m_{k+l-1} \end{bmatrix}.
\]

Using last quasi-determinants, see [52, 85], we find

**Proposition 10.** If the last quasi-determinants of the truncated moment matrices are nonsingular, i.e.,

\[
\det \Theta_*(M_{[k,1]}) \neq 0, \quad k = 1, 2, \ldots,
\]

then the Gauss–Borel factorization can be performed and the following expressions

\[
H_k = \Theta_*(M_{[k,1]}), \quad (S_1^{-1})_{k,1} = \Theta_*(M_{[k+1,1]})(\Theta_*(M_{[k+1,1]})^{-1}, \quad (S_2^{-1})_{k,1} = (\Theta_*(M_{[k+1,1]})^{-1}\Theta_*(M_{[k+1,1]})^\top,
\]

hold.

**Definition 10.** We define \( \chi(x) := [I_p, I_p x, I_p x^2, \ldots]^\top \) and the vectors of matrix polynomials \( P_1^{[1]} = [P_0^{[1]}, P_1^{[1]}, \ldots]^\top \) and \( P_1^{[2]} = [P_0^{[2]}, P_1^{[2]}, \ldots]^\top \), where

\[
P_1^{[1]} := S_1 \chi(x), \quad P_1^{[2]} := S_2 \chi(x).
\]

**Proposition 11.** The matrix polynomials \( P_n^{[1]}(x) \) are monic and \( \deg P_n^{[1]} = n, i = 1, 2 \).

Observe that the moment matrix can be expressed as

\[
M = \int_{\mathbb{R}} \chi(x) d\mu(x)(\chi(x))^\top.
\]

**Proposition 12.** The families of monic matrix polynomials \( \{P_n^{[1]}(x)\}_{n=0}^{\infty} \) and \( \{P_n^{[2]}(x)\}_{n=0}^{\infty} \) are bi-orthogonal

\[
\left\langle P_n^{[1]}(x), P_m^{[2]}(x) \right\rangle = \delta_{n,m} H_n, \quad n, m \in \mathbb{Z}_+.
\]
If \( \mu = \mu^\top \) then \( P_n^{[1]} = P_n^{[2]} =: P_n \) which in turn conform an orthogonal set of monic matrix polynomials
\[
(P_n(x), P_m(x)) = \delta_{n,m} H_n, \quad n, m \in \mathbb{Z}_+,
\]
and we can write \( \|P_n\| = H_n^{1/2} \). These bi-orthogonal relations can be recasted as
\[
\int \mathbb{R} P_n^{[1]}(x) \, d\mu(x)x^m = \int \mathbb{R} x^m \, d\mu(x)(P_n^{[2]}(x))^\top = H_n \delta_{n,m}, \quad m \leq n.
\]

**Proof.** From the definition of the polynomials and the factorization problem we get
\[
\int \mathbb{R} P_n^{[1]}(x) \, d\mu(x)x^m = \int \mathbb{R} x^m \, d\mu(x)(P_n^{[2]}(x))^\top = H_n \delta_{n,m}.
\]

**Remark 3.** The matrix of measures \( d\mu(x) \) may undergo a similarity transformation, \( d\mu(x) \mapsto d\mu_c(x) \), and be conjugate to \( d\mu(x) = B^{-1} d\mu_c(x) B \), where \( B \in \mathbb{R}^{p \times p} \) is a nonsingular matrix. The relation between the orthogonal polynomials given by these two measures is easily seen to be
\[
M = B^{-1} M_c B, \quad S_1 = B^{-1} S_{c,1} B, \quad H = B^{-1} H_c B, \quad (S_2)^\top = B^{-1} (S_{c,2})^\top B,
\]
\[
P_n^{[1]} = B^{-1} P_{c,n}^{[1]} B, \quad (P_n^{[2]})^\top = B^{-1} (P_{c,n}^{[2]})^\top B.
\]

The shift matrix is the following semi-infinite block matrix
\[
\Lambda := \begin{bmatrix}
0 & I_p & 0 & 0 & \ldots \\
0 & 0 & I_p & 0 & \ldots \\
0 & 0 & 0 & I_p & \ldots \\
\vdots & \ddots & \ddots & \ddots & \ddots \\
\end{bmatrix}
\]
which satisfies the important spectral property
\[
\Lambda \chi(x) = x \chi(x).
\]

**Proposition 13.** The block Hankel symmetry of the moment matrix can be written as
\[
\Lambda M = M \Lambda^\top.
\]

Notice that this symmetry completely characterizes Hankel block matrices.

**Proposition 14.** We have the following last quasi-determinantal expressions
\[
P_n^{[1]}(x) = \Theta_* \begin{bmatrix}
m_0 & m_1 & \cdots & m_{n-1} & I_p \\
m_1 & m_2 & \cdots & m_n & I_p x \\
\vdots & \vdots & & \vdots & \vdots \\
m_{n-1} & m_n & \cdots & m_{2n-2} & I_p x^{n-1} \\
m_n & m_{n+1} & \cdots & m_{2n-1} & I_p x^n
\end{bmatrix},
\]
\[
(P_n^{[2]}(x))^\top = \Theta_* \begin{bmatrix}
m_0 & m_1 & \cdots & m_{n-1} & m_n \\
m_1 & m_2 & \cdots & m_n & m_{n+1} \\
\vdots & \vdots & & \vdots & \vdots \\
m_{n-1} & m_n & \cdots & m_{2n-2} & m_{2n-1} \\
I_p & I_p x & \cdots & I_p x^{n-1} & I_p x^n
\end{bmatrix}.
\]

Given two sequences of matrix bi-orthonormal polynomials \( \{P_k^{[1]}(x)\}_{k=0}^\infty \) and \( \{P_k^{[2]}(x)\}_{k=0}^\infty \) with respect to \( \langle \cdot, \cdot \rangle \), we define the n-th Christoffel–Darboux kernel matrix polynomial
\[
K_n(x, y) := \sum_{k=0}^n (P_k^{[2]}(y))^\top H_k^{-1} P_k^{[1]}(x).
\]

Named after \([32, 34]\) see also \([33]\).
Then, we have the corresponding perturbed bi-orthogonal matrix polynomials of degree $\tilde{N}$ introduced. Let us assume that the perturbed moment matrix admits a Gaussian factorization

$$\tilde{M} = \tilde{S}_1^{-1} \tilde{H}(\tilde{S}_2)^{-\top},$$

where $\tilde{S}_1, \tilde{S}_2$ are lower unitriangular block matrices and $\tilde{H}$ is a diagonal block matrix

$$\tilde{S}_i = \begin{bmatrix} I_p & 0 & 0 & \cdots \\ (\tilde{S}_i)_{1,0} & I_p & 0 & \cdots \\ (\tilde{S}_i)_{2,0} & (\tilde{S}_i)_{2,1} & I_p & \cdots \\ & & & \ddots \end{bmatrix}, \quad \tilde{H} = \begin{bmatrix} \tilde{H}_0 & 0 & 0 & \cdots \\ 0 & \tilde{H}_1 & 0 & \cdots \\ 0 & 0 & \tilde{H}_2 & \cdots \\ & & & \ddots \end{bmatrix}, \quad i = 1, 2.$$

Then, we have the corresponding perturbed bi-orthogonal matrix polynomials

$$\tilde{p}^{[i]}(x) = \tilde{S}_i(x), \quad i = 1, 2,$$

with respect to the perturbed sesquilinear form $\langle \cdot, \cdot \rangle_W$.

**Remark 4.** The discussion for monic matrix polynomial perturbations and perturbations with a matrix polynomial with non singular leading coefficients are equivalent. Indeed, if instead of a monic matrix polynomial we have a matrix polynomial $\tilde{W}(x) = A_N x^n + \cdots + A_0$ with a nonsingular leading coefficient, $\det A_N \neq 0$, then we could factor out $A_N$, $\tilde{W}(x) = A_N W(x)$, where $W$ is monic. The moment matrices are related by $\tilde{M} = A_N \tilde{M}$ and, moreover, $\tilde{S}_1 = A_N \tilde{S}_1 (A_N)^{-1}$, $\tilde{H} = A_N \tilde{H}$, $\tilde{S}_2 = \tilde{S}_2$, and $\tilde{p}^{[1]}_k(x) = A_N p^{[1]}_k(x)(A_N)^{-1}$ as well as $\tilde{p}^{[2]}_k(x) = \tilde{p}^{[2]}_k(x)$.
2.1. Connection formulas for bi-orthogonal polynomials.

**Proposition 17.** The moment matrix $M$ and the $W$ perturbed moment matrix $\hat{M}$ satisfy

$$\hat{M} = W(\Lambda)M.$$

**Definition 11.** Let us introduce the following semi-infinite matrices

$$\omega^{[1]} := \hat{S}_1 W(\Lambda)S_1^{-1}, \quad \omega^{[2]} := (S_2 \hat{S}_2^{-1})^T,$$

which we call resolvent or connection matrices.

**Proposition 18** (Connection formulas). Perturbed and non perturbed bi-orthogonal polynomials are subject to the following linear connection formulas

$$(5) \quad \omega^{[1]} p^{[1]}(x) = \hat{p}^{[1]}(x)W(x),$$

$$(6) \quad p^{[2]}(x) = (\omega^{[2]})^T \hat{p}^{[2]}(x).$$

**Proposition 19.** The following relations hold

$$\hat{H}\omega^{[2]} = \omega^{[1]}H.$$

**Proof.** From Proposition 17 and the LU factorization we get

$$\hat{S}_1^{-1}\hat{S}_2^{-T} = W(\Lambda)S_1^{-1}HS_2^{-T},$$

so that

$$\hat{H}(S_2 \hat{S}_2^{-1})^T = \hat{S}_1 W(\Lambda)S_1^{-1}H$$

and the result follows. \(\square\)

From this result we easily get that

**Proposition 20.** The resolvent matrix $\omega$ is a band upper triangular block matrix with all the block superdiagonals above the $N$-th one equal to zero.

$$(7) \quad \omega^{[1]} = \begin{bmatrix}
\omega^{[1]}_{0,0} & \omega^{[1]}_{0,1} & \omega^{[1]}_{0,2} & \ldots & \omega^{[1]}_{0,N-1} & I_p & 0 & 0 & \ldots \\
0 & \omega^{[1]}_{1,1} & \omega^{[1]}_{1,2} & \ldots & \omega^{[1]}_{1,N-1} & \omega^{[1]}_{1,N} & I_p & 0 & \ldots \\
0 & 0 & \omega^{[1]}_{2,2} & \ldots & \omega^{[1]}_{2,N-1} & \omega^{[1]}_{2,N} & \omega^{[1]}_{2,N+1} & I_p & \ldots \\
\vdots & \vdots & \vdots & \ddots & \ddots & \ddots & \ddots & \ddots & \ddots \\
\end{bmatrix}
$$

with

$$(7) \quad \omega^{[1]}_{k,k} = \hat{H}_k(H_k)^{-1}.$$

2.2. Connection formulas for the Christoffel–Darboux kernel. In order to relate the perturbed and non perturbed kernel matrix polynomials let us introduce the following truncation of the connection matrix $\omega$. 
Definition 12. We introduce the lower unitriangular matrix $\omega_{(n,N)} \in \mathbb{R}^{Np \times Np}$ with

$$
\omega_{(n,N)} := \begin{cases}
0 \ldots 0 0 \ldots 0 \\
\vdots \\
0 \ldots 0 0 \ldots 0 \\
\omega_0^{[1]} \ldots \omega_{0,N-1}^1 \ I_p \\
\vdots \\
\omega_{n,n+1}^1 \ldots \omega_{n,n+N-1}^1 \ I_p \\
I_p \ 0 \ldots 0 0 \\
\omega_{n-N+2,n+1}^1 \ I_p \\
\vdots \\
\omega_{n,n+1}^1 \ldots \omega_{n,n+N-1}^1 \ I_p
\end{cases}, \quad n < N,
$$

and the diagonal block matrix

$$
\hat{H}_{n,N} = \text{diag}(\hat{H}_{n-N+1}, \ldots, \hat{H}_n).
$$

Then, we can write the important

Theorem 1. The perturbed and original Christoffel-Darboux kernels are related by the following connection formulas

$$
K_n(x,y) + \left((\hat{P}_n^{[2]}(y))_{N+1}^\top, \ldots, (\hat{P}_n^{[2]}(y))^\top\right) (\hat{H}_{(n,N)})^{-1} \omega_{(n,N)} \begin{bmatrix} p_{n+1}^1(x) \\ \vdots \\ p_{n+N}^1(x) \end{bmatrix} = \hat{K}_n(x,y)W(x),
$$

by convention $\hat{P}_j^{[2]} = 0$ whenever $j < 0$.

Proof. Consider the truncation

$$
(\omega^{[2]}|_{n+1}) := \begin{bmatrix} I_p \ldots \omega_{0,N-1}^{[2]} \omega_{0,N}^{[2]} \ 0 \ldots 0 \\
0 \ I_p \ldots \omega_{1,N+1}^{[2]} \omega_{1,N+2}^{[2]} \ 0 \ldots 0 \\
\vdots \\
0 \ 0 \ I_p \ldots \omega_{n-N,n}^{[2]} \\
\vdots \\
0 \ 0 \ \ I_p \omega_{n-1,n}^{[2]} \\
0 \ 0 \ 0 \ I_p
\end{bmatrix}.
$$

Recalling (3) in the form $(P^{[2]}(y))^\top = (\hat{P}^{[2]}(y))^\top \omega^{[2]}$ we see that $((\hat{P}^{[2]}(y))|_{n+1})^\top (\omega^{[2]}|_{n+1}) = ((P^{[2]}(y))|_{n+1})^\top$ holds for the n-th truncations of $P^{[2]}(y)$ and $\hat{P}^{[2]}(y)$. Therefore,

$$
((\hat{P}^{[2]}(y))|_{n+1})^\top (\omega^{[2]}|_{n+1})(H|_{n+1})^{-1}(P^{[1]}(x)|_{n+1}) = ((P^{[2]}(y))|_{n+1})^\top (H|_{n+1})^{-1}(P^{[1]}(x)|_{n+1}) = K_n(x,y).
$$

Now, we consider $(\omega^{[2]}|_{n+1})(H|_{n+1})^{-1}(P^{[1]}(x)|_{n+1})$ and recall Proposition 19 in the form

$$
(\omega^{[2]}|_{n+1})(H|_{n+1})^{-1} = (\hat{H}|_{n+1})^{-1}(\omega^{[1]}|_{n+1})
$$

which leads to

$$
(\omega^{[2]}|_{n+1}(H|_{n+1})^{-1}(P^{[1]}(x)|_{n+1} = (\hat{H}|_{n+1})^{-1}(\omega^{[1]}|_{n+1})(P^{[1]}(x)|_{n+1}.
$$
Observe also that
\[(\omega^{[1]})(n+1)(P^{[1]}(x))_{n+1} = (\omega^{[1]}P^{[1]}(x))_{n+1} - \left[0_{(n-N)p \times p}\right] V_N(x)\]
with
\[V_N(x) = \omega_{(n,N)} \left[\begin{array}{c} P^{[1]}_{n+1}(x) \\ \vdots \\ P^{[1]}_{n+N}(x) \end{array} \right].\]
Hence, recalling (5) we get
\[(\omega^{[1]})(n+1)(P^{[1]}(x))_{n+1} = (\hat{P}^{[1]}(x))_{n+1}W(x) - \left[0_{(n-N)p \times p}\right] V_N(x),\]
and consequently
\[
\left(\left(\hat{P}^{[2]}(y)\right)_{n+1}\right)^{T} \left(\omega^{[2]}\right)_{n+1}\left(H_{n+1}\right)^{-1}(P^{[1]}(x))_{n+1}
= \left(\left(\hat{P}^{[2]}(y)\right)_{n+1}\right)^{T} \left(H_{n+1}\right)^{-1}(P^{[1]}(x)_{n+1}W(x) - \left(\left(\hat{P}^{[2]}(y)\right)_{n+1}\right)^{T} \left(H_{n+1}\right)^{-1} \left[0_{(n-N)p \times p}\right] V_N(x)\right).
\]

\[\square\]

3. Monic matrix polynomial perturbations

In this section we study the case of perturbations by monic matrix polynomials \(W(x)\), which is equivalent to matrix polynomials with nonsingular leading coefficients. Using the theory given in \(\S\) we are able to extend the celebrated Christoffel formula to this context.

3.1. The Christoffel formula for matrix bi-orthogonal polynomials. We are now ready to show how the perturbed set of matrix bi-orthogonal polynomials \(\{\hat{P}^{[1]}_n(x), \hat{P}^{[2]}_n(x)\}_{n=0}^{\infty}\) is related to the original set \(\{P^{[1]}_n(x), P^{[2]}_n(x)\}_{n=0}^{\infty}\).

**Proposition 21.** Let \(v^{(i)}_{j}(x)\) be the adapted root polynomials of the monic matrix polynomial \(W(x)\) given in (3). Then, for each eigenvalue \(x_i \in \sigma(W), i \in \{1, \ldots, q\},\)

\[
\omega^{[1]}_{k,k} \frac{d^r P^{[1]}_k v^{(i)}_j}{dx^r} \big|_{x=x_i} + \cdots + \omega^{[1]}_{k,k+N-1} \frac{d^r (P^{[1]}_{k+N-1}v^{(i)}_j)}{dx^r} \big|_{x=x_i} = - \frac{d^r P^{[1]}_k v^{(i)}_j}{dx^r} \big|_{x=x_i},
\]
for \(r = 0, \ldots, k_j^{(i)} - 1\), and \(j = 1, \ldots, s_i\).

**Proof.** From (5) we get
\[\omega^{[1]}_{k,k} P^{[1]}_k(x) + \cdots + \omega^{[1]}_{k,k+N-1} P^{[1]}_{k+N-1}(x) + P_{k+N}(x) = \hat{P}^{[1]}_k(x)W(x).\]

Now, according to Proposition 8 we have
\[
\frac{d^r}{dx^r} \big|_{x=x_i} (\hat{P}^{[1]}_k W v^{(i)}_j) = \sum_{s=0}^{r} \binom{r}{s} \frac{d^{r-s} \hat{P}^{[1]}_k}{dx^{r-s}} \big|_{x=x_i} \frac{d^s (W v^{(i)}_j)}{dx^s} \big|_{x=x_i} = 0,
\]
for \(r = 0, \ldots, k_j^{(i)} - 1\) and \(j = 1, \ldots, s_i\).

Recall that \(\sum_{j=1}^{s_i} k_j^{(i)} = \alpha_i\) and that the sum of all multiplicities \(\alpha_i\) is \(Np = \sum_{i=1}^{q} \alpha_i, q = \# \sigma(W)\).
**Definition 13.**

i) For each eigenvalue \( x_i \in \sigma(W) \), in terms of the adapted root polynomials \( p_j^{(i)}(x) \) of the monic matrix polynomial \( W(x) \) given in (3), we introduce the vectors

\[
\tau_{j,k}^{(r),(1)} := \frac{d^r (p_k^{(1)} v_j^{(1)}(x))}{dx^r} \bigg|_{x=x_i} \in \mathbb{C}^p
\]

and arrange them in the partial row matrices \( \tau_k^{(i)} \in \mathbb{C}^{p \times \alpha_i} \) given by

\[
\tau_k^{(i)} = \left[ \tau_{1,k}^{(i)}, \ldots, \tau_{s_i,k}^{(i)}, \ldots, \tau_{s_i,k}^{(i)-1} \right].
\]

We collect all them as

\[
\tau_k := [\tau_k^{(1)}, \ldots, \tau_k^{(q)}] \in \mathbb{C}^{p \times N p}.
\]

Finally, we have

\[
\Pi_{k,N} := \begin{bmatrix} \tau_k & \vdots & \tau_{k+N-1} \end{bmatrix} \in \mathbb{C}^{N p \times N p}.
\]

ii) In a similar manner, we define

\[
\gamma_{j,n}^{(r),(i)}(y) := \frac{d^r (K_n(x,y)v_j^{(i)}(x))}{dy^r} \bigg|_{x=x_i} \in \mathbb{C}^p[y],
\]

\[
\gamma_n^{(i)}(y) := \left[ \gamma_{1,n}^{(0),(i)}(y), \ldots, \gamma_{s_i,n}^{(0),(i)}(y), \ldots, \gamma_{s_i,n}^{(0),(i)-1} \right] \in \mathbb{C}^{p \times \alpha_i}[y],
\]

and, as above, collect all of them in

\[
\gamma_n(y) = [\gamma_n^{(1)}, \ldots, \gamma_n^{(q)}] \in \mathbb{C}^{p \times N p}[y].
\]

**Theorem 2 (The Christoffel formula for matrix bi-orthogonal polynomials).** The perturbed set of matrix bi-orthogonal polynomials \( \{ \hat{p}_k^{[1]}(x), \hat{p}_k^{[2]}(x) \}_{k=0}^\infty \), whenever \( \det \Pi_{k,N} \neq 0 \), can be written as the following last quasideterminant

\[
(10) \quad \hat{p}_k^{[1]}(x) W(x) = \Theta_s \begin{bmatrix} \Pi_{k,N} & \hat{p}_k^{[1]}(x) \\ \vdots & \vdots \\ \tau_{k+N} & \hat{p}_k^{[1]}(x) \end{bmatrix},
\]

\[
(11) \quad (\hat{p}_k^{[2]}(x))^\top (\hat{H}_k)^{-1} = \Theta_s \begin{bmatrix} \Pi_{k+1,N} & 0 \\ \vdots & \vdots \\ \gamma_{k}(x) & 0 \end{bmatrix}.
\]

Moreover, the new matrix squared norms are

\[
(12) \quad \hat{H}_k = \Theta_s \begin{bmatrix} \Pi_{k,N} & H_k \\
\vdots & \vdots \\ \tau_{k+N} & 0 \end{bmatrix}.
\]

**Proof.** We assume that \( p_j^{[2]} = 0 \) whenever \( j < 0 \). To prove (10) notice that from (8) one deduces for the rows of the connection matrix that

\[
(13) \quad [\omega_{k,k}^{[1]}, \ldots, \omega_{k,k+n-1}^{[1]}] = -\pi_{k+N}(\Pi_{k,N})^{-1}.
\]
Now, using (5) we get
\[
[\omega_{k,k}, \ldots, \omega_{k,k+N-1}^1 \ldots, \omega_{k,k+N-1}^{N-1}]
\begin{pmatrix}
p_1^1(x) \\
p_2^1(x) \\
\vdots \\
p_{k+N-1}^1(x)
\end{pmatrix} + P_{k+N}^1(x) = \hat{P}_k^1(x) W(x).
\]
and (10) follows immediately.

To deduce (11) for \( k \geq N \) notice that Theorem 6 together with (9) yields
\[
(\gamma_{j,k}^{(r),(i)}(x) + \left( (\hat{P}_k^{[2]}(x))^\top, \ldots, (\hat{P}_k^{[2]}(x))^\top \right) (\hat{H}_{(k,N)})^{-1} \omega_{(k,N)} \begin{pmatrix}
\tau_{j,k+1}^{(r),(i)} \\
\vdots \\
\tau_{j,k+N}^{(r),(i)}
\end{pmatrix} = 0
\]
for \( r = 0, \ldots, \kappa_j^{(1)} - 1 \) and \( j = 1, \ldots, s_i \). We arrange these equations in a matrix form to get
\[
\gamma_k(x) + \left( (\hat{P}_k^{[2]}(x))^\top, \ldots, (\hat{P}_k^{[2]}(x))^\top \right) (\hat{H}_{(k,N)})^{-1} \omega_{(k,N)} - \gamma_k(x)(\Pi_{k+1,N})^{-1} = 0,
\]
which, in particular, gives
\[
(\hat{P}_k^{[2]}(x))^\top (\hat{H}_k)^{-1} = -\gamma_k(x)(\Pi_{k+1,N})^{-1}.
\]
Finally, (12) is a consequence of (7) and (13). \( \square \)

3.2. Degree one monic matrix polynomial perturbations. Let us illustrate the situation with the most simple case of a perturbation of degree one monic polynomial matrix
\[
W(x) = I_p x - A.
\]
The spectrum \( \sigma(I_p x - A) = \sigma(A) = \{x_1, \ldots, x_q\} \) is determined by the zeroes of the characteristic polynomial of \( A \)
\[
\det(I_p x - A) = (x - x_1)^{\alpha_1} \cdots (x - x_q)^{\alpha_q},
\]
and for each eigenvalue let \( s_i = \dim \ker(I_p x_i - A) \) be the corresponding geometric multiplicity, and \( \kappa_j^{(1)}, j = 1, \ldots, s_i \), its partial multiplicities, so that \( \alpha_i = \sum_{j=1}^{s_i} \kappa_j^{(1)} \) is the algebraic multiplicity (the order of the eigenvalue as a zero of the characteristic polynomial of \( A \)). After a similarity transformation of \( A \) we will get its canonical Jordan form. With no lack of generality we assume that \( A \) is already given in Jordan canonical form
\[
\begin{pmatrix}
\mathcal{J}_{\kappa_1^{(1)}}(x_1) & 0 & \cdots & 0 \\
0 & \mathcal{J}_{\kappa_2^{(1)}}(x_1) & \cdots & 0 \\
0 & \cdots & \cdots & 0 \\
0 & \cdots & \cdots & \mathcal{J}_{\kappa_q^{(1)}}(x_q)
\end{pmatrix},
\]

where the Jordan blocks corresponding to each eigenvalue are given by

\[ J_{k_j}^{(i)}(x_i) := \begin{bmatrix} x_i & 1 & 0 \\ 0 & x_i & 1 \\ & \ddots & \ddots \\ & & x_i & 1 \\ & & 0 & x_i \end{bmatrix} \in \mathbb{R}^{s_i \times s_i}, \quad j = 1, \ldots, s_i. \]

For each eigenvalue \( x_i \) we pick a basis \( \{v_{0,j}^{(i)}\}_{j=1}^{s_i} \) of \( \text{Ker}(I_p x_i - A) \), then look for vectors \( \{v_{r,j}^{(i)}\}_{r=1}^{\kappa_j^{(i)} - 1} \) such that

\[ (I_p x_i - A)v_{r,j}^{(i)} = -v_{r-1,j}^{(i)}, \quad r = 1, \ldots, \kappa_j^{(i)} - 1, \]

so that \( \{v_{r,j}^{(i)}\}_{r=0}^{\kappa_j^{(i)}} \) is a Jordan chain. As we are dealing with \( A \) in its canonical form the vectors \( v_{r,j}^{(i)} \) can be identified with those of the canonical basis \( \{e_i\}_{i=1}^p \) of \( \mathbb{R}^p \) with \( e_i = (0, \ldots, 1_i, \ldots, 0)^T \). Indeed, we have

\[ v_{r,j}^{(i)} = e_{\alpha_1 + \ldots + \alpha_{i-1} + \kappa_j^{(i)} + \cdots + \kappa_{j-1}^{(i)} + r + 1}. \]

Then, consider the polynomial vectors

\[ v_j^{(i)}(x) = \sum_{r=0}^{\kappa_j^{(i)} - 1} v_{r,j}^{(i)}(x - x_i)^r, \quad j = 1, \ldots, s_i, \quad i = 1, \ldots, q, \]

which satisfy

\[ \frac{d^r}{dx^r} \bigg|_{x = x_i} ((I_p x - A)v_j^{(i)}) = 0, \quad r = 0, \ldots, \kappa_j^{(i)} - 1, \quad j = 1, \ldots, s_i, \quad i = 1, \ldots, q. \]

Consequently,

\[ \frac{d^r}{dx^r} \bigg|_{x = x_i} \left( \hat{p}^{[1]}(x)(I_p x - A)v_j^{(i)} \right) = 0, \quad r = 0, \ldots, \kappa_j^{(i)} - 1, \quad j = 1, \ldots, s_i, \quad i = 1, \ldots, q. \]

Now, let us notice the following simple fact

**Proposition 22.** For a given matrix \( A \in \mathbb{R}^{p \times p} \) any matrix polynomial \( P(x) = \sum_{k=0}^n P_k x^k \in \mathbb{R}^{p \times p}[x] \), \( \deg P = n \), can be written as

\[ P = \sum_{k=0}^n P_k^{(A)}(I_p x - A)^k. \]

In particular, we have \( P_0^{(A)} = P(A) := \sum_{k=0}^n P_k A^k \).

**Proposition 23.** We can write

\[ \frac{1}{r!} \frac{d^r}{dx^r} \bigg|_{x = x_i} (P v_j^{(i)}) = P(A)v_{r,j}^{(i)}, \quad r = 0, \ldots, \kappa_j^{(i)} - 1, \quad j = 1, \ldots, s_i, \quad i = 1, \ldots, q. \]

**Proof.** Observe that

\[ \frac{d^s}{dx^s} \bigg|_{x = x_i} v_{r-s,j}^{(i)} = \sum_{l=1}^k \frac{l!}{(l-s)!} P_l^{(A)}(I_p x_i - A)^{1-s} v_{r-s,j}^{(i)} \]

\[ = \sum_{l=1}^r (-1)^{1-s} \frac{l!}{(l-s)!} P_l^{(A)} v_{r-l,j}^{(i)}, \quad s = 1, \ldots, r, \quad j = 1, \ldots, s_i, \quad i = 1, \ldots, q. \]
and, consequently,

\[
\frac{d^r(P_{j}^{(i)})}{dx^r}|_{x=x_i} = \sum_{s=0}^{r} \frac{r!}{s!} \sum_{l=s}^{r} (-1)^{l-s} \frac{l!}{(l-s)!} p_{l}^{(A)} v_{r-l,j}^{(i)}
\]

\[
= r! \sum_{s=0}^{r} (-1)^{r-s} \binom{r}{s} p_{l}^{(A)} v_{r-l,j}^{(i)}
\]

\[
= r! \sum_{m=0}^{r} (-1)^{r-m} \left[ \sum_{s=0}^{r-m} (-1)^{s} \binom{r-m}{s} \right] p_{r-m}^{(A)} v_{m,j}^{(i)}
\]

\[
= r! P(A) v_{r,j}^{(i)},
\]

for \( r = 0, \ldots, \kappa_{j}^{(i)} - 1, j = 1, \ldots, s_i \) and \( i = 1, \ldots, q \).

In the following we’ll use

\[
K_n(y, A) := \sum_{m=0}^{n} P_m^2(y) H_m^{-1} P_m(A).
\]

**Proposition 24** (Degree one Christoffel formula). If \( W(x) = I_p x - A \) and \( \det P_n^{(1)}(A) \neq 0 \) for \( n \in \mathbb{Z}_+ \), then the Christoffel formulas can be written as

\[
\hat{p}_n^{(1)}(x)(I_p x - A) = \Theta_n \begin{bmatrix}
P_n^{(1)}(A) & P_n^{(1)}(x) \\
P_{n+1}^{(1)}(A) & P_{n+1}^{(1)}(x)
\end{bmatrix}
\]

\[
= P_{n+1}^{(1)}(x) - P_{n+1}^{(1)}(A) P_{n+1}^{(1)}(A)^{-1} P_{n+1}^{(1)}(x),
\]

\[
= -K_n(y, A) [P_n^{(1)}(A)]^{-1}.
\]

For the perturbed matrix squared norms we have

\[
\hat{\bar{H}}_n = \Theta_n \begin{bmatrix}
P_n^{(1)}(A) & H_n \\
P_{n+1}^{(1)}(A) & 0
\end{bmatrix}
\]

\[
= -P_{n+1}^{(1)}(A) [P_n^{(1)}(A)]^{-1} H_n.
\]

**Proof.** According to (5) and Theorem 1

\[
\omega_{n,n} P_n^{(1)}(x) + P_{n+1}^{(1)}(x) = \hat{p}_n^{(1)}(x)(I_p x - A),
\]

\[
K_n(x,y) + (\hat{p}_n^{(2)}(y))^T P^{(1)}_{n+1}(x) = \tilde{K}_n(x,y)(I_p x - A),
\]

and using (14) we conclude

\[
\frac{d^r(P_k^{(1)} v_{j}^{(i)})}{dx^r}|_{x=x_i} + \frac{d^r(P_{n+1}^{(1)} v_{j}^{(i)})}{dx^r}|_{x=x_i} = 0,
\]

\[
\frac{d^r}{dx^r}|_{x=x_i} ((K_n(x,y)v_{j}^{(i)}(x)) + (\hat{p}_n^{(2)}(y))^T P^{(1)}_{n+1}(x) = 0,
\]

for \( r = 0, \ldots, \kappa_{j}^{(i)} - 1, j = 1, \ldots, s_i \) and \( i = 1, \ldots, q \). From Proposition 23 and the fact that the ordered arrangement of the Jordan chain vectors \( v_{r,j}^{(i)} \) gives the identity matrix \( I_p \) we conclude

\[
\omega_{n,n} P_n^{(1)}(A) + P_{n+1}^{(1)}(A) = 0,
\]

\[
K_n(y, A) + (\hat{p}_n^{(2)}(y))^T P_{n+1}^{(1)}(A) = 0.
\]

We now illustrate the Christoffel formula in the matrix orthogonal polynomial context with a simple case. We will study what is the effect of the Christoffel transformation on a positive Borel scalar measure \( d \mu(x) \), thus the
perturbed matrix of measures is \((I_2x - A) d \mu(x)\). The perturbed monic orthogonal polynomials will be expressed, see Proposition 24.

\[
\hat{P}_n^{[1]}(x) = (I_2p_{n+1}(x) - p_{n+1}(A)(p_n(A))^{-1}p_n(x))(I_2x - A)^{-1},
\]

\[
\hat{P}_n^{[2]}(x) = -K_n(x, A)[P_n^{[1]}(A)]^{-1}
\]

where \(p_n(x), K_n(x, y)\) are the scalar orthogonal polynomials and kernel polynomials associated with the original scalar positive Borel measure \(d \mu(x)\). Observe that despite starting with a set of orthogonal polynomials the perturbation generates a set of bi-orthogonal matrix polynomials. As the original measure is scalar, if we ensure that \(A = A^\top\) is symmetric, we will get \(\hat{P}_n(x) := P_n^{[1]}(x) = P_n^{[2]}(x)\), a new set of orthogonal matrix polynomials.

However, this will be a very trivial situation as we have

**Proposition 25.** The matrix orthogonal polynomials \((\hat{P}_n(x)|_{n=0}^\infty)\) of the matrix of measures \((I_2x - A) d \mu(x)\), where \(A = A^\top\) is symmetric and \(d \mu\) is a positive Borel scalar measure are similar to diagonal matrix orthogonal polynomials.

**Proof.** Being the matrix \(A\) symmetric it will be always diagonalizable

\[A = QDQ^\top,\]

where \(Q\) is an orthogonal matrix \(Q^\top = Q^{-1}\) and \(D = \text{diag}(x_1, \ldots, x_p)\), is a diagonal matrix that collects the eigenvalues, not necessarily different, of \(A\).

At the end, the new orthogonal polynomials will be

\[
\hat{P}_n(x) = Q
\begin{bmatrix}
\frac{p_{n+1}(x) - p_{n+1}(x_1)}{p_n(x_1)} & 0 & \ldots & 0 \\
0 & \frac{p_{n+1}(x) - p_{n+1}(x_2)}{p_n(x_2)} & 0 & \ldots & 0 \\
\vdots & \ddots & \ddots & \ddots & \ddots \\
0 & \ldots & 0 & \frac{p_{n+1}(x) - p_{n+1}(x_p)}{p_n(x_p)}
\end{bmatrix}Q^\top,
\]

and the result is proven.

Thus, we have a diagonal bunch of elementary Darboux transformations of the original scalar orthogonal polynomials associated to the scalar measure \(d \mu\). This situation reappears even when the matrix is not symmetric but diagonalizable, as we will have again that the perturbed matrix orthogonal polynomials will be similar to a similar bunch of elementary Darboux transformations of the original scalar orthogonal polynomials.

\[
\hat{P}_n^{[1]}(x) = Q
\begin{bmatrix}
\frac{p_{n+1}(x) - p_{n+1}(x_1)}{p_n(x_1)} & 0 & \ldots & 0 \\
0 & \frac{p_{n+1}(x) - p_{n+1}(x_2)}{p_n(x_2)} & 0 & \ldots & 0 \\
\vdots & \ddots & \ddots & \ddots & \ddots \\
0 & \ldots & 0 & \frac{p_{n+1}(x) - p_{n+1}(x_p)}{p_n(x_p)}
\end{bmatrix}Q^{-1},
\]

\[
\hat{P}_n^{[2]}(x) = -Q
\begin{bmatrix}
\frac{K_n(x, x_1)}{P_n(x_1)} & 0 & \ldots & 0 \\
0 & \frac{K_n(x, x_2)}{P_n(x_2)} & 0 & \ldots & 0 \\
\vdots & \ddots & \ddots & \ddots & \ddots \\
0 & \ldots & 0 & \frac{K_n(x, x_p)}{P_n(x_p)}
\end{bmatrix}Q^{-1},
\]

where \(Q\) does not need to be an orthogonal matrix.
If the matrix is not diagonalizable and has nontrivial Jordan blocks the situation is different. Let us explore this case when \( p = 2 \). Hence, we consider
\[
W(x) = I_2 x - A,
\]
with
\[
A = M \begin{bmatrix} x_1 & 1 \\ 0 & x_1 \end{bmatrix} M^{-1}.
\]

Now we have only one eigenvalue \( \sigma(A) = \{x_1\} \), with a length 2 Jordan chain. Thus, there is a linear basis \( \{v_1, v_2\} \subset \mathbb{R}^2, (A - x_1)v_1 = v_2, (A - x_1)v_2 = 0 \), with \( v_i = [v_{i,1} \ v_{i,2}]^\top, i \in \{1, 2\} \), such that
\[
M = \begin{bmatrix} v_{1,1} & v_{2,1} \\ v_{1,2} & v_{2,2} \end{bmatrix}.
\]

Therefore,
\[
p_{n+1}(A)(p_n(A))^{-1} = M \begin{bmatrix} p_{n+1}(x) - \frac{p_{n+1}(x)}{p_n(x_1)} p_n(x) & W(p_n, p_{n+1})(x) \\ 0 & \frac{W(p_n, p_{n+1})(x)}{p_n(x_1)} \end{bmatrix} M^{-1}, \quad (I_2 x - A)^{-1} = M \begin{bmatrix} 1 & \frac{1}{x-x_1} \\ 0 & 1 \end{bmatrix} M^{-1},
\]
where
\[
W(p_n, p_{n+1})(x) = p_n(x)p'_{n+1} - p_{n+1}(x)p_n'(x)
\]
is the Wronskian of two consecutive orthogonal polynomials.

Hence,
\[
\hat{p}_n^{[1]}(x) = M \begin{bmatrix} \frac{p_{n+1}(x)}{p_n(x_1)} & \frac{p_{n+1}(x)}{p_n(x_1)} - \frac{p_{n+1}(x)}{p_n(x_1)} p_n(x) - \frac{W(p_n, p_{n+1})(x)}{p_n(x_1)} (x-x_1) p_n(x) \\ 0 & \frac{W(p_n, p_{n+1})(x)}{p_n(x_1)} \end{bmatrix} M^{-1},
\]
\[
\hat{p}_n^{[2]}(x) = -M \begin{bmatrix} -\frac{K_n(x, x_1)}{p_n(x_1)} & -\frac{K_n(x, x_1)}{p_n(x_1)} + \frac{1}{p_n(x_1)} \frac{\partial K_n(x, y)}{\partial y} \big|_{y=x_1} \\ 0 & \frac{K_n(x, x_1)}{p_n(x_1)} \end{bmatrix} M^{-1}
\]

Observe that the polynomials
\[
p_{n+1}(x) - \frac{p_{n+1}(x_1)}{p_n(x_1)} p_n(x), \quad p_{n+1}(x) - \frac{p_{n+1}(x_1)}{p_n(x_1)} p_n(x) - \frac{W(p_n, p_{n+1})(x_1)}{p_n(x_1)^2} (x-x_1) p_n(x)
\]
have a zero at \( x = x_1 \) of order 1 and 2, respectively.

### 3.3. Examples.

**Example 1.** In [59] the authors define the notion of a classical pair \( \{w(x), D\} \), where \( w(x) \) is a symmetric matrix valued weight function and \( D \) is a second order linear ordinary differential operator. In that paper a weight function is said to be classical if there exists a second order linear ordinary differential operator \( D \) with matrix valued polynomial coefficients \( A_j(t) \), deg \( A_j \leq j \), of the form
\[
D = A_0(x) \frac{d^2}{dx^2} + A_1(x) \frac{d}{dx} + A_0(x),
\]
such that \( \langle DP, Q \rangle = \langle P, DQ \rangle \) for all matrix valued polynomial functions \( P(x) \) and \( Q(x) \). Then, the pair \( \{w, D\} \) is called a classical pair. In example 5.1 in [59] they present a family of Jacobi type classical pairs that contains, up to equivalence, all classical pairs of size two where \( w(x) = x^\alpha(1-x)^\beta F(x) \), with \( \alpha, \beta > -1 \) and \( 0 < x < 1 \), and such that \( F(x) \) is of degree one and which are irreducible (in the sense that they are not equivalent to a direct sum of classical pairs of size one). As we will show they are a direct sum of orthogonal polynomials of size 1 produced by two degree one Christoffel transformations of the scalar Jacobi polynomials with zeros at \( x = 0, 1 \). Thus, we are faced with two scalar monic Jacobi polynomials with each of the two parameters \( \alpha \) and \( \beta \) shifted by one, respectively. In [96] an analysis of the reducibility of matrix weights is given. In particular, in Example 2.4 they consider the case \( \alpha = \beta \). We must stress that, as was pointed in [59], reducibility of the matrix of weights \( w(x) \) do not imply the reducibility of the classical pair \( \{w(x), D\} \). Indeed, despite that the matrix of weights in this example is reducible the corresponding second order linear differential operator is not.
The classical pair \( \{w(x) = x^\alpha (1-x)^\beta \hat{F}(x), D\} \) is given by

\[
F(x) = F_1 x + F_0, \quad F_1 = \begin{bmatrix} 0 & -a \\ -a & \frac{\beta - \alpha}{\alpha + 1} \end{bmatrix}, \quad F_0 = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}, \quad \text{with } a = \frac{\alpha + \beta + 2}{\alpha + 1},
\]

and a second order matrix linear ordinary differential operator

\[
D = x(1-x) \frac{d^2}{dx^2} + (X-xU) \frac{d}{dx} + V
\]

where \( U, V, X \) are constant matrices depending on a parameter \( u \). The sequence of orthogonal polynomials \( \{\hat{P}_n^{(\alpha,\beta)}(x)\}_{n=0}^\infty \) associated with the classical pair is not given in [59]. Here an explicit representation of \( \hat{P}_n^{(\alpha,\beta)}(x) \) using Darboux transformations is deduced. In order to do it we consider that we have an initial alternative Jacobi measure \( d\mu(x) = x^n(1-x)^{\beta} I_2 \), with \( \alpha, \beta > -1 \) and \( 0 < x < 1 \), which is perturbed by a degree one matrix polynomial \( F \). This matrix polynomial is not monic but its leading coefficient is non singular and we can write

\[
F(x) = F_1 W(x), \quad W(x) = I_2 x - A, \quad A := -F_1^{-1} F_0 = \frac{1}{a} \begin{bmatrix} \frac{\beta + 1}{\alpha + 1} & \frac{\beta + 1}{\alpha + 1} \\ \frac{\beta + 1}{\alpha + 1} & \frac{\beta + 1}{\alpha + 1} \end{bmatrix},
\]

in terms of a degree one monic matrix polynomial \( W(x) \). We have that \( A \) has two different eigenvalues \( \sigma(A) = \{0,1\} \) with corresponding eigenvectors \( [1,-1]^T \) and \( \begin{bmatrix} \frac{\beta + 1}{\alpha + 1} \\ 1 \end{bmatrix}^T \), the matrix \( M := \begin{bmatrix} 1 \\ -1 \end{bmatrix} \) allows to write \( A = M \text{diag}(0,1) M^{-1} \).

Remember, as was noticed in Remark 4, that from the monic orthogonal polynomials \( \tilde{p}_n^{(\alpha,\beta),[1]}(x) \) with respect to \( W \), we get

\[
\hat{p}_n^{(\alpha,\beta)}(x) = F_1 \tilde{p}_n^{(\alpha,\beta),[1]}(x) F_1^{-1},
\]

which are the monic orthogonal polynomials with respect to \( w(x) \). As the matrix of measures \( F(x) d\mu(x) \) is symmetric, the bi-orthogonality collapses to orthogonality and the super-indexes \([1]\) and \([2]\) can be omitted. We will do the same with \( p_n^{(\alpha,\beta),[1]} = \tilde{p}_n^{(\alpha,\beta)} \).

Following [28, 29] we conclude that the set of monic matrix orthogonal polynomials \( \{p_n^{(\alpha,\beta)}(x)\}_{n=0}^\infty \) with respect to \( d\mu(x) \) are \( p_n^{(\alpha,\beta)}(x) = p_n^{(\alpha,\beta)}(x) I_2 \) with the alternative Jacobi polynomials \( p_n^{(\alpha,\beta)}(x) \) given by

\[
p_n^{(\alpha,\beta)}(x) = \frac{1}{S_n(\alpha, \beta)} \sum_{k=0}^n \begin{pmatrix} n + \alpha \\ n - k \end{pmatrix} \begin{pmatrix} n + \beta \\ k \end{pmatrix} x^{n-k}(x-1)^k, \quad \text{with} \quad S_n(\alpha, \beta) = \begin{pmatrix} 2n + \beta + \alpha \\ n \end{pmatrix}.
\]

We easily see that

\[
p_n^{(\alpha,\beta)}(0) = \frac{1}{S_n(\alpha, \beta)} \begin{pmatrix} n + \alpha \\ n \end{pmatrix}, \quad p_n^{(\alpha,\beta)}(1) = \frac{1}{S_n(\alpha, \beta)} \begin{pmatrix} n + \beta \\ n \end{pmatrix},
\]

so that

\[
\frac{p_{n+1}^{(\alpha,\beta)}(0)}{p_n^{(\alpha,\beta)}(0)} = (n + 1 + \alpha) \rho_n^{(\alpha,\beta)}, \quad \frac{p_{n+1}^{(\alpha,\beta)}(1)}{p_n^{(\alpha,\beta)}(1)} = (n + 1 + \beta) \rho_n^{(\alpha,\beta)},
\]

where

\[
\rho_n^{(\alpha,\beta)} := \frac{(n + \beta + \alpha + 1)}{2(n + \beta + \alpha + 1)(2n + \beta + \alpha + 1)}.
\]

From [17] we conclude

\[
\hat{p}_n^{(\alpha,\beta)}(x) = M \begin{bmatrix} \frac{p_{n+1}^{(\alpha,\beta)}(x)-(n+1+\alpha)\rho_{n}^{(\alpha,\beta)}p_{n}^{(\alpha,\beta)}(x)}{x} \\ 0 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & x-1 \end{bmatrix} M^{-1}.
\]
However, we must notice that these two Darboux transformations correspond to the following transformations of the Jacobi measure

\[ x^\alpha (x - 1)^\beta \mapsto x(x^\alpha (x - 1)^\beta) = x^{\alpha + 1}(x - 1)^\beta, \quad x^\alpha (x - 1)^\beta \mapsto (x - 1)(x^\alpha (x - 1)^\beta) = x^\alpha (x - 1)^{\beta + 1}, \]

i.e. the transformations correspond to the shifts \( \alpha \mapsto \alpha + 1 \) and \( \beta \mapsto \beta + 1 \), respectively. Consequently,

\[
\hat{p}_n^{(\alpha, \beta)}(x) = M \begin{bmatrix} p_n^{(\alpha+1, \beta)}(x) & 0 \\ 0 & p_n^{(\alpha, \beta+1)}(x) \end{bmatrix} M^{-1}.
\]

With the matrix

\[
\tilde{M} := \begin{bmatrix} -1 \\ 1+\alpha \\ 1+\beta \end{bmatrix}
\]

we can write \( F_1 M = -a\tilde{M} \). We finally get the monic matrix orthogonal polynomials

\[
\hat{p}_n^{(\alpha, \beta)}(x) = \tilde{M} \begin{bmatrix} p_n^{(\alpha+1, \beta)}(x) & 0 \\ 0 & p_n^{(\alpha, \beta+1)}(x) \end{bmatrix} \tilde{M}^{-1},
\]

for the matrix of measures \( \tilde{W}(x) \, d\mu(x) \) in example 5.1 of [59] which are explicitly expressed in terms of scalar Jacobi polynomials as follows

\[
\hat{\phi}_n^{(\alpha, \beta)}(x) = \frac{1}{2 + \alpha + \beta} \begin{bmatrix} (\alpha + 1)p_n^{(\alpha+1, \beta)}(x) + (\beta + 1)p_n^{(\alpha, \beta+1)}(x) \\ -(\alpha + 1)(p_n^{(\alpha+1, \beta)}(x) - p_n^{(\alpha, \beta+1)}(x)) \\ (\beta + 1)p_n^{(\alpha, \beta+1)}(x) + (\alpha + 1)p_n^{(\alpha, \beta+1)}(x) \end{bmatrix}.
\]

To conclude with this example let us mention that in [27] it was found that these matrix orthogonal polynomials also obey a first order ordinary differential equation. From our point of view this is just a consequence of a remarkable fact regarding the Darboux transformations \( p^{(\alpha+1, \beta)}(x), p^{(\alpha, \beta+1)}(x) \) of the original alternative Jacobi polynomials. Under the hypergeometric function description of the Jacobi polynomials one gets recurrences for arbitrary diagonal matrices

\[
\left( x \frac{d}{dx} + \alpha + 1 \right)p_n^{(\alpha+1, \beta)}(x) = (\alpha + 1 + n)p_n^{(\alpha, \beta+1)}(x),
\]

\[
\left( x - 1 \frac{d}{dx} + \beta + 1 \right)p_n^{(\alpha, \beta+1)}(x) = (\beta + 1 + n)p_n^{(\alpha+1, \beta)}(x).
\]

This first order linear ordinary differential system can be re-casted as a matrix linear differential equation as follows

\[
(19) \quad \left( \begin{bmatrix} 0 & 1 - 1 \\ x & 0 \end{bmatrix} \frac{d}{dx} + \begin{bmatrix} a_1 & \beta + 1 \\ \alpha + 1 & a_2 \end{bmatrix} \right) \begin{bmatrix} p_n^{(\alpha+1, \beta)}(x) & 0 \\ 0 & p_n^{(\alpha, \beta+1)}(x) \end{bmatrix} = \begin{bmatrix} p_n^{(\alpha+1, \beta)}(x) & 0 \\ 0 & p_n^{(\alpha, \beta+1)}(x) \end{bmatrix} \begin{bmatrix} a_1 & n + \beta + 1 \\ n + \alpha + 1 & a_2 \end{bmatrix},
\]

where \( a_1, a_2 \in \mathbb{R} \). This equation is invariant under multiplication on the right and on the left hand side by arbitrary diagonal matrices

\[
\begin{bmatrix} l_1 & 0 \\ 0 & l_2 \end{bmatrix} \left( \begin{bmatrix} 0 & 1 - 1 \\ x & 0 \end{bmatrix} \frac{d}{dx} + \begin{bmatrix} a_1 & \beta + 1 \\ \alpha + 1 & a_2 \end{bmatrix} \right) \begin{bmatrix} r_1 & 0 \\ 0 & r_2 \end{bmatrix} \begin{bmatrix} p_n^{(\alpha+1, \beta)}(x) & 0 \\ 0 & p_n^{(\alpha, \beta+1)}(x) \end{bmatrix} = \begin{bmatrix} p_n^{(\alpha+1, \beta)}(x) & 0 \\ 0 & p_n^{(\alpha, \beta+1)}(x) \end{bmatrix} \begin{bmatrix} l_1 & 0 \\ 0 & l_2 \end{bmatrix} \begin{bmatrix} a_1 & n + \beta + 1 \\ n + \alpha + 1 & a_2 \end{bmatrix} \begin{bmatrix} r_1 & 0 \\ 0 & r_2 \end{bmatrix}.
\]
After the similarity transformation, \( \Lambda \mapsto \hat{M}^{-\top} \Lambda \hat{M}^\top \) we find out that the orthogonal polynomial \( \hat{P}_n \) satisfies
\[
\left( \begin{array}{c}
A_1(x) \frac{d}{dx} + A_0
\end{array} \right) \hat{P}_n = (\hat{P}_n)^\top \Lambda_n
\]
where
\[
A_1(x) = \frac{\alpha + 1}{\alpha + \beta + 2} \left[ \begin{array}{cc}
-\delta & \delta \\
\delta_+ & \delta_-
\end{array} \right] x^2 + d \left[ \begin{array}{cc}
1 & 1 \\
-1 & -1
\end{array} \right],
\]
\[
\Lambda_n = \frac{\alpha + 1}{\alpha + \beta + 2} \left[ \begin{array}{cc}
-\delta & \delta \\
\delta_+ & \delta_-
\end{array} \right] n + A_0,
\]
with \( d = l_1 r_2 \) and
\[
\delta = l_1 r_2 + \frac{\beta + 1}{\alpha + 1} l_2 r_1, \quad \delta_- = -l_1 r_2 + \left( \frac{\beta + 1}{\alpha + 1} \right)^2 l_2 r_1, \quad \delta_+ = l_1 r_2 - l_2 r_1,
\]
\[
\Delta = (\beta + 1)(l_1 r_2 + l_2 r_1), \quad \Delta_- = -l_1 r_2(\alpha + 1) + l_2 r_1(\beta + 1), \quad \Delta_+ = l_1 r_2(\beta + 1) - l_2 r_1(\alpha + 1),
\]
\[
C = -l_1 r_1 a_1 + l_2 r_2 a_2, \quad C_- = \frac{\beta + 1}{\alpha + 1} l_1 r_1 a_1 + l_2 r_2 a_2, \quad C_+ = l_1 r_1 a_1 + \frac{\beta + 1}{\alpha + 1} l_2 r_2 a_2.
\]

When we take \( l_1 = l_2 = -1, r_1 = r_2 = 1 \) and \( a_1 = \beta + 1 \) and \( a_2 = \alpha + 1 \) we get the first order ordinary differential system in §4 of [27].

**Remark 5.** The discussion in this example, regarding the Jacobi polynomials \( p^{(\alpha+1, \beta)}(x) \) and \( p^{(\alpha, \beta+1)}(x) \) and the use of the Gauss’ contiguous relations, connects with the results in [66], Remark 2.8., see also [64] [65].

**Example 2.** Here we analyze the Chebyshev example taken from [27], that gives an example of a family of matrix orthogonal polynomials which satisfy a first order linear ordinary differential equation. In §3 of [27] we find a set of MOPS related with the measure \( W(x) \) where
\[
W(x) := \begin{bmatrix} 1 & x \\
1 & 0
\end{bmatrix}, \quad d \mu(x) = \frac{1}{\sqrt{1 - x^2}}.
\]
We have a nonsingular leading coefficient \( c^0 = \begin{bmatrix} 0 & 1 \\
1 & 0
\end{bmatrix} \) so that
\[
\hat{W}(x) = \begin{bmatrix} 0 & 1 \\
1 & 0
\end{bmatrix} W(x), \quad W(x) := I_2 x - \begin{bmatrix} 0 & -1 \\
-1 & 0
\end{bmatrix}.
\]
Following Remark 4 we shall analyze the Darboux transformations \( d \mu(x) \mapsto W(x) d \mu(x) \).

Thus, using (17) we can write the perturbed monic matrix orthogonal polynomials as follows
\[
\hat{P}_n(x) = Q \begin{bmatrix}
t_{n+1}(x) & t_{n+1}(-1) \\
\frac{t_{n+1}(x) - t_{n+1}(-1)}{x+1} & 0
\end{bmatrix} Q^\top, \quad Q := \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\
1 & -1
\end{bmatrix},
\]
where \( \{t_n(x)\}_{n=0}^\infty \) are the monic Chebyshev polynomials of first kind, i.e., \( t_n(x) = 2^{-n+1} T_n(x) \) with \( T_n \) the first kind Chebyshev polynomial of degree \( n \). Therefore, recalling that \( T_n(\pm 1) = (\pm 1)^n \) we get
\[
\frac{t_{n+1}(\mp 1)}{t_n(\mp 1)} = \pm \frac{1}{2}, \quad \frac{t_{n+1}(\mp 1)}{t_n(\mp 1)} t_{n+1}(x) \mp t_{n+1}(\mp 1) t_n(x) = \frac{1}{2^n} (T_{n+1}(x) \mp T_n(x)).
\]
Now, recalling the mutual recurrence relation satisfied by Chebyshev polynomials of the first and second kind, denoted these last ones by \( U_n \),
\[
T_{n+1}(x) = x T_n(x) - (1 - x^2) U_{n-1}(x), \quad T_n(x) = U_n(x) - x U_{n-1}(x),
\]
which implies \( T_{n+1}(x) = x U_n(x) - U_{n-1}(x) \), we deduce
\[
T_{n+1}(x) \mp T_n(x) = (x \mp 1) (U_n(x) \mp U_{n-1}(x)).
\]
Consequently,
\[
\hat{P}_n(x) = \frac{1}{2^n} Q \begin{bmatrix} U_n(x) - U_{n-1}(x) & 0 \\
0 & U_n(x) + U_{n-1}(x)
\end{bmatrix} Q^\top, \quad Q := \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\
1 & -1
\end{bmatrix}.
\]
The matrix orthogonal polynomials associated with the original measure \( \tilde{W}(x) \, d\mu(x) \) can be recovered from this by a similarity transformation with \([1 \, 0]^T\) so that
\[
\tilde{p}_n(x) = \frac{1}{2^{n+1}} \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} U_n(x) - U_{n-1}(x) & 0 \\ 0 & U_n(x) + U_{n-1}(x) \end{bmatrix} \begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix} = \frac{1}{2^n} \begin{bmatrix} U_n(x) & -U_{n-1}(x) \\ -U_{n-1}(x) & U_n(x) \end{bmatrix}.
\]

**Remark 6.** The polynomials \( \{U_n = U_{n-1}\}_{n=0}^{\infty} \) with \( U_1 = 0 \), which are orthogonal with respect to the measures \( \frac{x+1}{\sqrt{1-x^2}} \), are the well known Chebyshev polynomials of the third and fourth kind, respectively.

**Remark 7.** The symmetric structure of the MOPS can be encoded in the equation
\[
\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \tilde{p}_n(x) = \tilde{p}_n(x) \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}.
\]

As in the Jacobi case, the new two scalar families of orthogonal polynomials are related through
\[
(x + 1) (U_n'(x) - U_{n-1}(x)) = (n + \frac{1}{2}) (U_n(x) + U_{n-1}(x)).
\]

This follows from
\[
(x + 1)(U_n'(x) - U_{n-1}(x)) = (x + 1) \frac{d}{dx} \left( \frac{T_{n+1}(x) + T_n(x)}{x + 1} \right)
= T_n'(x) \mp T'(x) - \frac{T_{n+1}(x) + T_n(x)}{x + 1}
= (n + 1) U_n(x) - n U_{n-1}(x) - U_n(x) \mp U_{n-1}(x).
\]

Here we have used that \( T_n' = n U_{n-1} \).

Differential equation (20) can be written in matrix form
\[
\begin{bmatrix} 0 & x - 1 \\ x + 1 & 0 \end{bmatrix} \frac{d}{dx} + \begin{bmatrix} a_1 & \frac{1}{2} \\ \frac{1}{2} & a_2 \end{bmatrix} \begin{bmatrix} U_n(x) - U_{n-1}(x) & 0 \\ 0 & U_n(x) + U_{n-1}(x) \end{bmatrix}
= \begin{bmatrix} U_n(x) - U_{n-1}(x) & 0 \\ 0 & U_n(x) + U_{n-1}(x) \end{bmatrix} \begin{bmatrix} a_1 & n + \frac{1}{2} \\ n + \frac{1}{2} & a_2 \end{bmatrix}
\]
where \( a_1, a_2 \in \mathbb{R} \) are arbitrary constants. Notice also that this matrix equation is invariant under multiplication on the right and on the left hand sides by arbitrary diagonal matrices \( L = \text{diag}(l_1, l_2) \) and \( R = \text{diag}(r_1, r_2) \),
\[
\begin{bmatrix} l_1 & 0 \\ 0 & l_2 \end{bmatrix} \begin{bmatrix} 0 & x - 1 \\ x + 1 & 0 \end{bmatrix} \frac{d}{dx} + \begin{bmatrix} a_1 & \frac{1}{2} \\ \frac{1}{2} & a_2 \end{bmatrix} \begin{bmatrix} r_1 & 0 \\ 0 & r_2 \end{bmatrix} \begin{bmatrix} U_n(x) - U_{n-1}(x) & 0 \\ 0 & U_n(x) + U_{n-1}(x) \end{bmatrix}
= \begin{bmatrix} U_n(x) - U_{n-1}(x) & 0 \\ 0 & U_n(x) + U_{n-1}(x) \end{bmatrix} \begin{bmatrix} l_1 & 0 \\ 0 & l_2 \end{bmatrix} \begin{bmatrix} a_1 & n + \frac{1}{2} \\ n + \frac{1}{2} & a_2 \end{bmatrix} \begin{bmatrix} r_1 & 0 \\ 0 & r_2 \end{bmatrix}.
\]

After the similarity transformation we find out that the orthogonal polynomial \( \tilde{p}_n(x) \) satisfies
\[
\left( A_1(x) \frac{d}{dx} + A_0 \right) \tilde{p}_n(x) = \tilde{p}_n(x) \Lambda_n,
\]
where
\[
A_1(x) = \begin{bmatrix} -\delta_+ x + \delta_- & \delta_- x - \delta_+ \\ -\delta_+ x + \delta_+ & \delta_- x - \delta_- \end{bmatrix}, \\
\Lambda_n = \begin{bmatrix} \Lambda_+ - \delta_+ \left( n + \frac{1}{2} \right) & \Lambda_- + \delta_- \left( n + \frac{1}{2} \right) \\
\Lambda_- - \delta_- \left( n + \frac{1}{2} \right) & \Lambda_+ + \delta_+ \left( n + \frac{1}{2} \right) \end{bmatrix},
\]
and \( A_0 = \Lambda_n = 0 \) with
\[
\delta_\pm = l_1 r_2 \pm l_2 r_1, \\
\Lambda_\pm = l_1 r_1 a_1 \pm l_2 r_2 a_2.
\]
Equations (3.1) and (3.2) of §3 of [27] can be recovered choosing \( \left( \delta_+ = A_+ = 0, \delta_- = 1, A_- = -\frac{1}{2} \right) \) and \( \left( \delta_- = A_- = 0, \delta_+ = 1, A_+ = \frac{1}{2} \right) \), respectively.

However, they are all equivalent to (21), another form of writing (20). It is in fact this last equation (20) a quite interesting one. Indeed, we have two families of Darboux transformed orthogonal polynomials interconnected by two first order differential equations. Moreover, we conclude

\[
\left( (x^2 - 1) \frac{d^2}{dx^2} + (2x + 1) \frac{d}{dx} + \frac{1}{4} \right) \left( U_n(x) \mp U_{n-1}(x) \right) = \left( n + \frac{1}{2} \right)^2 \left( U_n(x) \mp U_{n-1}(x) \right).
\]

**Example 3.** Here we comment on the matrix Gegenbauer matrix valued polynomials discussed in [66]. In this case the matrix of weights is a symmetric matrix, \( W^{(\nu)} : [-1, 1] \to \mathbb{R}^{N \times N} \), with matrix coefficients of the form

\[
(W^{(\nu)}(x))_{i,j} := (1 - x^2)^{-\nu-1/2} \sum_{k=\max(0,i+j-1)-N}^{\min(i,j)+1-N} \alpha_k^{(\nu)}(i,j) C_n^{(\nu)}(x), \quad i \geq j,
\]

where \( \alpha_k^{(\nu)}(i,j) \) are some coefficients and \( C_n^{(\nu)}(x) \) stands for the Gegenbauer or ultraspherical polynomials. Erik Koelink and Pablo Román kindly communicated us a nice feature of the matrix Christoffel transformation discussed in this paper when acting on this reach family of MOPS: two families of Gegenbauer MOPS associated with matrices of weights \( W^{(\nu_1)}(x) \) and \( W^{(\nu_2)}(x) \), such that \( \nu_1 - \nu_2 = m \in \mathbb{Z} \), are linked by a matrix Christoffel transformation. Now, the perturbing polynomial \( W(x) \) has deg \( W = 2m \). These examples are, in general, reducible to two irreducible blocks of sizes \( N/2 \), for \( N \) even, and \( (N + 1)/2 \) and \( (N - 1)/2 \) for odd \( N \). For a discussion on the orthogonal and non orthogonal reducibility of these examples see [66, 67].

4. **Singular leading coefficient matrix polynomial perturbations**

After studying some examples that the literature provides us with, one may realize that, even thought it is generic to assume the perturbing matrix polynomial \( W(x) \) to have a nonsingular leading coefficient, many examples do have a singular matrix as its leading coefficient. This situation is a special feature of the matrix case setting since in the scalar case, having a singular leading term would mean that this coefficient is just zero (affecting, of course, to the degree of the polynomial). For this reason, when dealing with this kind of matrix polynomials talking about their degree should make no sense. The effect that this fact has on our reasoning is that since \( \deg(\text{det } W(x)) \leq Np \) the information encoded in the zeroes (and corresponding adapted polynomials) of \( \text{det } W(x) \) is no longer enough to make the matrices \( \Pi_{kN} \) of the needed size. Therefore, there will be no way to express the perturbed polynomials just in terms of the initial ones evaluated at the zeroes of \( \text{det } W(x) \) and the method to find a Christoffel type formula fails. However, the information that seems to be missing in these cases may actually not be necessary due to the singular character of the leading coefficient of the perturbing polynomial. Let us consider the following example to take a glimpse of this scenario.

Let us pick up some scalar measure \( d \mu(x) \) and its associated monic OPs \( \{ p_k(x) \}_{k=0}^{\infty} \) together with their norms and three term recurrence relation

\[
h_k \delta_{kj} := \langle p_k, p_j \rangle, \quad x p_k(x) = J_{k,k-1} p_{k-1}(x) + J_{k,k} p_k(x) + p_{k+1}(x), \quad J_{k,k-1} = \frac{h_k}{h_{k-1}} > 0.
\]

Now, consider its \( 2q \times 2q \) matrix diagonal extension \( \in \mathbb{R}^{2q \times 2q}[x] \)

\[
P_k(x) := p_k(x) I_{2q}, \quad H_k := h_k I_{2q}.
\]

Our aim is to consider the following matrix polynomial (with singular leading coefficient)

\[
W(x) := \begin{bmatrix} I_q + A A^T x^2 & A x \\ A^T x & I_q \end{bmatrix}, \quad A \in \mathbb{R}^{q \times q},
\]

which is inspired by the \( q = 1 \) case \( \begin{bmatrix} 1 + a x^2 & a x \\ \frac{a}{x} & 1 \end{bmatrix} \) (see [45], and references therein) and study the corresponding perturbations of our initial scalar measure; i.e., \( d \hat{\mu}(x) := W(x) d \mu(x) \) in order to obtain the transformed matrix
orthogonal polynomials
\[
\hat{p}_k(x) := \begin{bmatrix} (\hat{P}_k)_{1,1} & (\hat{P}_k)_{1,2} \\ (\hat{P}_k)_{2,1} & (\hat{P}_k)_{2,2} \end{bmatrix}, \quad \hat{P}_k(x) \in \mathbb{R}^{2q \times 2q}[x], (\hat{P}_k)_{i,j} \in \mathbb{R}^{q \times q}[x],
\]
\[
\langle \hat{p}_k, \hat{p}_j \rangle_W := \delta_{k,j} \hat{H}_k = \delta_{k,j} \begin{bmatrix} (\hat{H}_k)_{1,1} & (\hat{H}_k)_{1,2} \\ (\hat{H}_k)_{2,1} & (\hat{H}_k)_{2,2} \end{bmatrix}, \quad \hat{H}_k \in \mathbb{R}^{2q \times 2q}, (\hat{H}_k)_{i,j} \in \mathbb{R}^{q \times q}.
\]

We have splitted them up this way for computational purposes. Notice that since \( W(x) = W(x)^T \) we have
\[
\hat{M} = \hat{M}^T := \hat{S}^{-1}\hat{H}[\hat{S}^{-1}]^T
\]
and, therefore, \( \hat{p}^{[1]} = \hat{p}^{[2]} := \hat{p} \) and \( \hat{H}_k = (\hat{H}_k)^T \).

Let us point out that
\[
W(x) = W(x)W(x)^T, \quad \omega := \begin{bmatrix} I_q & Ax \\ 0 & I_q \end{bmatrix}, \quad \omega^{-1} = \begin{bmatrix} I_q & -Ax \\ 0 & I_q \end{bmatrix}.
\]
This implies that \( \det W = \det W = 1 \) and, consequently, there is no spectral analysis to perform as there are non eigenvalues at all. Thus, the relation between the original and perturbed measures and moment matrices is
\[
[W(x)]^{-1} d \hat{\mu} = d \mu [W(x)]^T, \quad [W(\Lambda)]^{-1} \hat{M} = M[\Lambda W(\Lambda)]^T.
\]

**Definition 14.** We introduce the resolvent or connection matrix
\[
\omega := \hat{S}W(\Lambda)S^{-1}.
\]

**Proposition 26.** The matrix \( \omega \) is block tridiagonal, having only its diagonal and first superdiagonal and subdiagonal nonzero, and satisfies
\[
\omega^{-1} = H[\omega]^T \hat{H}^{-1}.
\]

Moreover, we have the important connection formula
\[
\omega P = \hat{P}W(x).
\]

**Proof.** The first relation is a consequence of the LU factorization of the moment matrices and the connection formula is a straightforward consequence of the definition of \( \omega \). \( \square \)

**Proposition 27.**

i) The matrices
\[
\rho_{k+1} := \left( I_q + J_{k+1,k}A^T A \right)^{-1},
\]
exist.

ii) The perturbed MOPS can be written in terms of the original OPS as follows
\[
\hat{p}_{k+1}(x)W(x) = -\begin{bmatrix} J_{k+1,k}^1J_{k+1,k}A^T \rho_{k+1} & 0 \\ J_{k+1,k}^1\rho_{k+1}A^T & 0 \end{bmatrix} p_k(x) + \begin{bmatrix} I_q & J_{k+1,k+1}^1A^T \rho_{k+1} \end{bmatrix} p_{k+1}(x) + \begin{bmatrix} 0 & A \\ 0 & 0 \end{bmatrix} p_{k+2}(x),
\]
for \( k \in \{-1,0,1,\ldots\} \).

**Proof.** From the \((k+1)-th\) row of the connection formula we have that
\[
\omega_{k+1,k}p_k(x) + \omega_{k+1,k+1}p_{k+1}(x) + \omega_{k+1,k+2}p_{k+2}(x) = \hat{p}_{k+1}(x)W(x),
\]
but from the Definition 14 and Proposition 26 one realizes that the previous expression reads
\[
\hat{p}_{k+1}(x)W(x) = \hat{H}_{k+1} \begin{bmatrix} 0 & -A^T \\ 0 & 0 \end{bmatrix} h_k^{-1} p_k(x) + \begin{bmatrix} \omega_{k+1,k+2} \end{bmatrix}_{11} p_{k+1}(x) + \begin{bmatrix} \omega_{k+1,k+2} \end{bmatrix}_{12} p_{k+2}(x).
\]
Now, taking into account that both \((\hat{P}_{k+1})_{11}, (\hat{P}_{k+1})_{22}\) are monic \( q \times q \) polynomials of degree \( k+1 \), while \((\hat{P}_{k+1})_{12}, (\hat{P}_{k+1})_{21}\) are \( q \times q \) polynomials of degree less than \( k+1 \), it is not hard to see (after using the three term recurrence relation of the initial polynomials) that
\[
(\omega_{k+1,k+2})_{11} = I_q, \quad (\omega_{k+1,k+2})_{12} = J_{k+1,k+1}A - h_k^{-1}(\hat{H}_{k+1})_{12}A^T A,
\]
\[
(\omega_{k+1,k+2})_{21} = 0, \quad (\omega_{k+1,k+2})_{22} = I_q - h_k^{-1}(\hat{H}_{k+1})_{22}A^T A.
\]
Hence, we have every coefficient that appears in the connection formula in terms of the still unknown norms of the MOPs. Therefore, we just need to compute the second block column of the following integral

\[
\int [\omega_{k+1,k}p_k(x) + \omega_{k+1,k+1}p_{k+1}(x) + \omega_{k+1,k+2}p_{k+2}(x)] \left[ (W(x))^T x^{k+1} \right] d\mu(x)
\]

\[
= \int \hat{p}_{k+1}(x) W(x) \left[ (W(x))^T x^{k+1} \right] d\mu(x)
\]

\[
= \int \hat{p}_{k+1}(x) d\hat{\mu}(x) x^{k+1}
\]

which yields

\[
(\hat{H}_{k+1})_{12} = J_{k+1,k+1} h_{k+1} A \left( I_q + J_{k+1,k} A^T A \right)^{-1},
\]

\[
(\hat{H}_{k+1})_{22} = h_{k+1} \left( I_q + J_{k+1,k} A^T A \right)^{-1}.
\]

Therefore,

\[
(\omega_{k+1,k+2})_{12} = J_{k+1,k+1} A \left( I_q + J_{k+1,k} A^T A \right)^{-1},
\]

\[
(\omega_{k+1,k+2})_{22} = \left( I_q + J_{k+1,k} A^T A \right)^{-1},
\]

and the stated result follows.

For \( q = 1 \) and the classical measures we have, see \([47]\),

**Corollary 1. Starting from the classical measures**

i) Hermite monic polynomials \( \{ \mathcal{H}(x) \} \) with norm \( h_k = \pi \frac{k!}{2^k} \)

\[
J_{k+1,k} = \frac{k+1}{2}, \quad J_{k+1,k+1} = 0, \quad \rho_{k+1} := \frac{2}{2 + \alpha^2(k+1)}.
\]

ii) Laguerre monic polynomials \( \{ \mathcal{L}(x) \} \) with norm \( h_k = k! \Gamma(k+1) \alpha \)

\[
J_{k+1,k} = (k+1)(k+\alpha+2), \quad J_{k+1,k+1} = (2k+\alpha+3), \quad \rho_{k+1} := \frac{1}{1 + \alpha^2(k+1)(k+1+\alpha)}.
\]

and perturbing them by the matrix polynomial

\[
W(x) = W(x) \left( W(x) \right)^T, \quad W(x) = \begin{pmatrix} 1 & a \alpha \\ 0 & 1 \end{pmatrix},
\]

one obtains the perturbed MOPs related to the classical OPS as follows

\[
\hat{H}(k+1) W(x) = \begin{pmatrix} \rho_{k+1}^{-1} - 1 & 0 \\ 0 & 0 \end{pmatrix} \mathcal{H}(x) + \begin{pmatrix} 1 & 0 \\ 0 & \rho_{k+1} \end{pmatrix} \mathcal{H}(k+1)(x) + \begin{pmatrix} 0 & a \\ 0 & 0 \end{pmatrix} \mathcal{H}(2)(x),
\]

\[
\hat{L}_{k+1}^\alpha W(x) = \begin{pmatrix} \rho_{k+1}^{-1} - 1 & 0 \\ 0 & \rho_{k+1} \end{pmatrix} \alpha \mathcal{L}_{k+1}^\alpha(x) + \begin{pmatrix} 1 & a \alpha + \rho_{k+1} \rho_{k+1}^{-1} - 1 \\ 0 \end{pmatrix} \mathcal{L}_{k+1}^\alpha(x) + \begin{pmatrix} 0 & a \\ 0 & 0 \end{pmatrix} \mathcal{L}_{k+1}^\alpha(x).
\]

5. **Extension to non-Abelian 2D Toda hierarchies**

Matrix orthogonal polynomials are connected with non-Abelian Toda lattices, see \([80,11]\).

5.1. **Block Hankel moment matrices vs multi-component Toda hierarchies.** Let us take \( M = (m_{i,j})_{i,j=0}^\infty, m_{i,j} \in \mathbb{R}^{p \times p} \) a semi-infinite block matrix having a Gaussian factorization

\[
M = (S_1)^{-1} H(S_2)^{-T},
\]

where \( S_1, S_2 \) are lower uni-triangular block matrices and \( H \) is block diagonal. Notice that conditions for this factorization to hold were given in Proposition \([10]\).
Definition 15. We introduce some continuous flows or perturbations of this semi-infinite matrix. For that aim we first consider the diagonal matrices
\[ t_{i,j} = \text{diag}(t_{i,j,1}, \ldots, t_{i,j,p}) \in \mathbb{R}^{p \times p}, \quad i = 1, 2, \quad j \in \mathbb{Z}_+, \]
the semi-infinite undressed wave matrices
\[ V_i^{(0)} := \exp \left( \sum_{j=0}^{\infty} t_{i,j} \Lambda^j \right), \quad i = 1, 2, \]
and the perturbed matrix \( M(t), t = (t_1, t_2), t_i = (t_{i,j,a})_{j \in \mathbb{Z}_+, a \in \{1, \ldots, p\}} \)
\[ M(t) = V_1^{(0)}(t_1) M(0) V_2^{(0)}(t_2)^{-\top}. \]

Observe that we do not require any Hankel form for the matrix \( M \), modelled by \( \Lambda M = M \Lambda^\top \). However, if \( M(0) \) is a Hankel matrix \( M(t) \) is also a Hankel matrix taking into account \( \Lambda M(t) = M(t) \Lambda^\top \). Hence, if \( d \mu(x) \) is the initial matrix of measures, then the new matrix of measures \( d \mu(x, t) \) will be
\[ d \mu(x, t) = \exp \left( \sum_{j=0}^{\infty} t_{i,j} x^j \right) d \mu(x) \exp \left( - \sum_{j=0}^{\infty} t_{2,j} x^j \right). \]
Here \( M(t) \) will be the moment matrix of the matrix of measures. Moreover, if at any time the matrix of measures is block Hankel then it was and it will be a Hankel block matrix at any time. If we assume that we can perform the Gaussian factorization again we can write
\[ M(t) = (S_1(t))^{-1} H(t) (S_2(t))^{-\top}. \]

As we know, for the block Hankel case we are dealing with bi-orthogonal or orthogonal polynomials with respect to the associated matrix of measures. What happens in the general case? Following [3] and [71] we can understand the Gaussian factorization also as a bi-orthogonality condition. The semi-infinite vectors of polynomials will be
\[ p^{[1]}(x) := S_1(t) \chi(x), \quad p^{[2]}(x) := S_2(t) \chi(x), \]
and we consider a sesquilinear form in \( \mathbb{R}^{p \times p}[x] \), see §1.4, that for any couple of matrix polynomials \( P = \sum_{k=0}^{\deg P} p_k x^k \) and \( Q(x) = \sum_{i=0}^{\deg Q} q_i x^i \) is defined by
\[ \langle P(x), Q(x) \rangle = \sum_{k=1, \ldots, \deg P, l=1, \ldots, \deg Q} p_k M_{k,l}(q_l)^\top, \]
where we can interpret
\[ M_{k,l} = \langle x^k 1_p, x^l 1_p \rangle \]
as the Gram matrix of the sesquilinear form. With respect to this sesquilinear form we have the bi-orthogonality condition
\[ \langle p^{[1]}_k(x), p^{[2]}_l(x) \rangle = H_k \delta_{k,l}. \]

For a block Hankel initial condition this sesquilinear form is just the sequilinear product associated with a linear functional of a measure. In [10] different examples are discussed for the matrix orthogonal polynomials scenario. For example, multigraded Hankel matrices \( M \) fulfilling
\[ \left( \sum_{a=1}^{p} \Lambda^n e_{a,a} \right) M = M \left( \sum_{a=1}^{p} (\Lambda^\top)^m e_{a,a} \right), \]
where \( n_1, \ldots, n_p, m_1, \ldots, m_p \) are positive integers, can be realized as
\[ M_{k,l} = \int x^k d \mu^{[1]}(x) \]
in terms of matrices of measures $d \mu^{(1)}(x)$ which satisfy the following periodicity condition
\begin{equation}
 d \mu^{(l+m_a)}_{a,b}(x) = x^{n_a} d \mu^{(1)}_{a,b}(x).
\end{equation}
Therefore, given the measures $d \mu^{(0)}_{a,b}, \ldots, d \mu^{(m_b-1)}_{a,b}$ we can recover all the others from (22). In this case, we have generalized orthogonality conditions like
\begin{equation}
 \int p_k^{(l)}(x) d \mu^{(1)}(x) = 0, \quad l = 0, \ldots, k - 1.
\end{equation}

Coming back to the Gaussian factorization, we consider the wave matrices
\begin{align*}
 V_1(t) &:= S_1(t) V_j^{(0)}(t_1), \\
 \tilde{V}_2(t) &:= \tilde{S}_2(t)(V_2^{(0)}(t_2))^T,
\end{align*}
where $\tilde{S}_2(t) := H(t)(S_2(t))^{-T}$.

**Proposition 28.** The wave matrices satisfy
\begin{equation}
(V_1(t))^{-1}\tilde{V}_2(t) = M.
\end{equation}
**Proof.** It is a consequence of the Gaussian factorization.

Given a semi-infinite matrix $A$ we have unique splitting $A = A_+ + A_-$ where $A_+$ is an upper triangular block matrix while $A_-$ a strictly lower triangular block matrix.

**Proposition 29.** The following equations hold
\begin{align*}
 \frac{\partial S_1}{\partial t_{1,j,a}} (S_1)^{-1} & = - \left( S_1 E_{a,a} \Lambda^j (S_1)^{-1} \right)_-, & \frac{\partial S_2}{\partial t_{2,j,a}} (S_2)^{-1} & = - \left( S_2 E_{a,a} (\Lambda^T)^j (S_2)^{-1} \right)_+,

 \frac{\partial S_1}{\partial t_{1,j,a}} (S_1)^{-1} & = \left( S_1 E_{a,a} \Lambda^j (S_1)^{-1} \right)_+, & \frac{\partial S_2}{\partial t_{2,j,a}} (S_2)^{-1} & = \left( S_2 E_{a,a} (\Lambda^T)^j (S_2)^{-1} \right)_+.
\end{align*}
**Proof.** Taking right derivatives of (23) yields
\begin{align*}
 \frac{\partial V_1}{\partial t_{i,j,a}} (V_1)^{-1} & = \frac{\partial V_2}{\partial t_{i,j,a}} (V_2)^{-1}, & i \in \{1, 2\}, & j \in \mathbb{Z}_+,
\end{align*}
where
\begin{align*}
 \frac{\partial V_1}{\partial t_{1,j,a}} (V_1)^{-1} & = \frac{\partial S_1}{\partial t_{1,j,a}} (S_1)^{-1} + S_1 E_{a,a} \Lambda^j (S_1)^{-1}, & \frac{\partial V_1}{\partial t_{2,j,a}} (V_1)^{-1} & = \frac{\partial S_1}{\partial t_{2,j,a}} (S_1)^{-1},

 \frac{\partial V_2}{\partial t_{1,j,a}} (V_2)^{-1} & = \frac{\partial S_2}{\partial t_{1,j,a}} (S_2)^{-1}, & \frac{\partial V_2}{\partial t_{2,j,a}} (V_2)^{-1} & = \frac{\partial S_2}{\partial t_{2,j,a}} (S_2)^{-1} + S_2 E_{a,a} (\Lambda^T)^j (S_2)^{-1},
\end{align*}
and the result follows immediately.

As a consequence, we derive

**Proposition 30.** The multicomponent 2D Toda lattice equations
\begin{equation}
 \frac{\partial}{\partial t_{2,i,b}} \left( \frac{\partial H_k}{\partial t_{1,i,a}} (H_k)^{-1} \right) + E_{a,a} H_{k+1} E_{b,b} (H_k)^{-1} - H_k E_{b,b} (H_{k-1})^{-1} E_{a,a} = 0.
\end{equation}
**Proof.** From Proposition 29 we get
\begin{align*}
 \frac{\partial H_k}{\partial t_{1,i,a}} (H_k)^{-1} & = \beta_k E_{a,a} - E_{a,a} \beta_{k+1}, & \frac{\partial \beta_k}{\partial t_{2,i,b}} & = H_k E_{b,b} (H_{k-1})^{-1},
\end{align*}
where $\beta_k \in \mathbb{R}^{P \times P}$, $k = 1, 2, \ldots$, are the first subdiagonal coefficients in $S_1$. 

\[ \square \]
The multi-component Toda and KP hierarchies were introduced in [100]. In [70,71] its relevance in integrable aspects of differential geometry was emphasized, and in [62] a representation approach was developed, while in [2,11] it was used in relation with multiple orthogonality. A comprehensive approach to multi-component 2D Toda hierarchy with applications in dispersionless integrability or generalized orthogonal polynomials can be found in [72,73,10].

If we introduce the total flows given by the derivatives

\[ \partial_{t_{i,j}} := \sum_{a=1}^{p} \frac{\partial}{\partial t_{i,j,a}} \]

we get the non-Abelian 2D Toda lattice

\[ \partial_{2,1}(\partial_{1,1}(H_k) \cdot (H_k)^{-1}) + H_{k+1}(H_k)^{-1} - H_k(H_{k-1})^{-1} = 0. \]

The non-Abelian Toda lattice was introduced in the context of string theory by Polyakov, [86,87], and then studied under the inverse spectral transform by Mikhailov [79] and Riemann surface theory by Krichever [69].

The non-Abelian 2D Toda lattice hierarchy is a reduction of the multicomponent hierarchy by taking the diagonal time matrices \( t_{i,j} = \text{diag}(t_{i,j,1}, \ldots, t_{i,j,p}) \) proportional to the identity; i.e.,

\[ t_{i,j} \mapsto t_{i,j}I_p, \quad t_{i,j} \in \mathbb{R}. \]

These equations are just the first members of an infinite set of nonlinear partial differential equations, an integrable hierarchy. Its elements are given by

**Definition 16.** The partial, Lax and Zakharov–Shabat matrices are given by

\[
\begin{align*}
\Pi_{1,a} &:= S_1E_{a,a}(S_1)^{-1}, & \Pi_{2,a} &:= \tilde{S}_2E_{a,a}(\tilde{S}_2)^{-1}, \\
L_1 &:= S_1\Lambda(S_1)^{-1}, & L_2 &:= \tilde{S}_2\Lambda^\top(\tilde{S}_2)^{-1}, \\
B_{1,j,a} &:= (\Pi_{1,a}(L_1)^{j})^+, & B_{2,j,a} &:= (\Pi_{2,a}(L_2)^{j})_.
\end{align*}
\]

**Proposition 31** (The integrable hierarchy). The wave matrices obey the evolutionary linear systems

\[
\begin{align*}
\frac{\partial V_1}{\partial t_{i,j,a}} &= B_{i,j,a}V_1, & \frac{\partial V_1}{\partial t_{2,j,a}} &= B_{2,j,a}V_1, \\
\frac{\partial V_2}{\partial t_{i,j,a}} &= B_{i,j,a}\tilde{V}_2, & \frac{\partial \tilde{V}_2}{\partial t_{2,j,a}} &= B_{2,j,a}\tilde{V}_2,
\end{align*}
\]

the partial and Lax matrices are subject to the following Lax equations

\[
\frac{\partial \Pi_{i,a'}}{\partial t_{i,j,a}} = [B_{i,j,a}, \Pi_{i,a'}], & \quad \frac{\partial L_{i'}}{\partial t_{i,j,a}} = [B_{i,j,a}, L_{i'}],
\]

and Zakharov–Sabat matrices fulfill the following Zakharov–Shabat equations

\[
\frac{\partial B_{i,j,a'}}{\partial t_{i,j,a}} - \frac{\partial B_{i,j,a}}{\partial t_{i,j,a'}} + [B_{i,j,a}, B_{i,j,a'}] = 0.
\]

**Proof.** Follows from Proposition 29. □

Given two semi-infinite block matrices \( A, B \) the notation \([A, B] = AB - BA\) stands for the usual commutator of matrices.

A crucial observation, regarding orthogonal polynomials, must be pointed out. When orthogonal polynomials are involved, and the matrices to factorize are block Hankel, equivalently \( \Lambda M = M\Lambda^\top \), we get \( L_1 = S_1\Lambda S_1^{-1} = \tilde{S}_2\Lambda^\top \tilde{S}_2^{-1} = L_2 \). As the reader may have noticed the Lax matrices \( L_1 \) and \( L_2 \) are, by construction, lower and upper Hessenberg block matrices, respectively. However, when the Hankel property holds both Lax matrices are equal,

\[ L_1 = L_2, \]
and, therefore, we are faced to a tridiagonal block matrix; i.e., a Jacobi block matrix. Moreover, this Hankel condition implies an invariance property under the flows introduced, as we have that $M(t) = V_1^{(0)}(t_1 - t_2)M$, i.e., there are only one type of flows. This condition also implies that for the total flows we have

\[
(\partial_{t,j} + \partial_{2,j})V_1 = V_1\Lambda^j,
\]

\[
(\partial_{t,j} + \partial_{2,j})L_1 = 0,
\]

\[
(\partial_{t,j} + \partial_{2,j})\tilde{V}_2 = \tilde{V}_2(\Lambda^T)^j,
\]

\[
(\partial_{t,j} + \partial_{2,j})L_2 = 0.
\]

Therefore, in the block Hankel case we are dealing with the multicomponent 1D Toda hierarchy.

5.2. **The Christoffel transformation for the non-Abelian 2D Toda hierarchy.** The idea is to follow what we did in §2.1 and consider an initial condition $\hat{M}$ at $t = 0$, this is

\[
\hat{M} = W(\Lambda)M
\]

for a matrix polynomial $W(x) \in \mathbb{R}^{P \times P}[x]$. Observe that the scalar times $t_{i,j} \in \mathbb{R}$ of the non-Abelian flows determined by

\[
V_i^{(0)} := \exp \left( \sum_{j=0}^{\infty} t_{i,j}\Lambda^j \right),
\]

the perturbed matrix is given by

\[
\hat{M}(t) = V_1^{(0)}(t_1)\hat{M}(V_2^{(0)}(t_2))^{-T}
\]

\[
= W(\Lambda)M(t).
\]

Here we have used that $[W(\Lambda), V_1^{(0)}(t)] = 0$, $\forall t_{i,j} \in \mathbb{R}$. Let us stress that we could request only $t_{i,j}$ to be scalars an let $t_{2,j}$ to be diagonal matrices. Despite this is a more general situation, we prefer to show how the method works in this simpler scenario.

Assuming that the block Gauss factorization hold, we proceed as in §2.1 and introduce the resolvents

\[
\omega^{[1]}(t) := \hat{S}_1(t)W(\Lambda)(S_1(t))^{-1},
\]

\[
\omega^{[2]}(t) := (S_2(t)(\hat{S}_2(t))^{-1})^T.
\]

From the LU factorization we get

\[
(\hat{S}_1(t))^{-1}\hat{H}(t)(\hat{S}_2(t))^{-T} = W(\Lambda)(S_1(t))^{-1}H(t)(S_2(t))^{-T},
\]

so that

\[
\hat{H}(t)(S_2(t)(\hat{S}_2(t))^{-1})^T = \hat{S}_1(t)W(\Lambda)(S_1(t))^{-1}H(t),
\]

and, consequently,

\[
\hat{H}(t)\omega^{[2]}(t) = \omega^{[1]}(t)H(t)
\]

holds. Hence, as in the static case where the variable $t$ does not appear, we have that this $t$-dependent resolvent matrix has a band block upper triangular structure

\[
\omega^{[1]} = \begin{bmatrix}
\omega_{0,0} & \omega_{0,1} & \omega_{0,2} & \ldots & \omega_{0,N-1} & I_p & 0 & 0 & \ldots \\
0 & \omega_{1,1} & \omega_{1,2} & \ldots & \omega_{1,N-1} & \omega_{1,N} & I_p & 0 & \ldots \\
0 & 0 & \omega_{2,2} & \ldots & \omega_{2,N-1} & \omega_{2,N} & \omega_{2,N+1} & I_p & \ldots \\
\vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \ddots & \ddots & \ddots \\
\end{bmatrix}
\]

with

\[
\hat{H}_k(t) = \omega_{k,k}^{[1]}(t)H_k(t),
\]

and the connection formulas described in Proposition 19 hold in this wider context.

Moreover, if $W(x)$ is a monic polynomial we can ensure that the Christoffel formula is also fulfilled for the non-Abelian 2D Toda and Theorem 2 remains valid also in this scenario. Formulas (10) and (12) hold directly and need no further explanation. However, (11) needs the following brief discussion. The Christoffel–Darboux kernel is defined exactly as we did in (4) but very probably there is no such a formula as the CD formula given in
Proposition 16 is present in this scenario. However, as was shown in [12], there are cases, such as the multigraded reductions, where one has a generalized CD formula.

**References**

[1] K. Abadir and J. Magnus, *Matrix Algebra*, Cambridge University Press, Cambridge 2005.

[2] M. Adler and P. van Moerbeke, *Group factorization, moment matrices and Toda lattices*, Int. Math. Res. Notices 12 (1997) 556-572.

[3] M. Adler and P. van Moerbeke, *Generalized orthogonal polynomials, discrete KP and Riemann–Hilbert problems*, Commun. Math. Phys. 207 (1999) 589-620.

[4] M. Adler and P. van Moerbeke, *Vertex operator solutions to the discrete KP hierarchy*, Commun. Math. Phys. 203 (1999) 185-210.

[5] M. Adler and P. van Moerbeke, *The spectrum of coupled random matrices*, Ann. Math. 149 (1999) 921-976.

[6] M. Adler and P. van Moerbeke, *Hermitian, symmetric and symplectic random ensembles: PDEs for the distribution of the spectrum*, Ann. Math. 153 (2001) 149-189.

[7] M. Adler and P. van Moerbeke, *Darboux transforms on band matrices, weights and associated polynomials*, Int. Math. Res. Notices 18 (2001) 935-984.

[8] M. Adler, P. van Moerbeke, and P. Vanhaecke, *Moment matrices and multi-component KP, with applications to random matrix theory*, Commun. Math. Phys. 286 (2009) 1-38.

[9] N. I. Akhiezer, *Classical moment problem and some related questions in analysis*, Translated by N. Kemmer Hafner Publishing Co., New York 1965.

[10] C. Álvarez-Fernández, M. Mañas and U. Fidalgo Prieto, *The multicomponent 2D Toda hierarchy: generalized matrix orthogonal polynomials, multiple orthogonal polynomials and Riemann–Hilbert problems*, Inverse Probl. 26 (2010) 055009 (15pp).

[11] C. Álvarez-Fernández, U. Fidalgo Prieto, and M. Mañas, *Multiple orthogonal polynomials of mixed type: Gauss-Borel factorization and the multi-component 2D Toda hierarchy*, Adv. Math. 227 (2011) 1451-1525.

[12] C. Álvarez-Fernández and M. Mañas, *On the Christoffel–Darboux formula for generalized matrix orthogonal polynomials*, J. Math. Anal. Appl. 418 (2014) 238-247.

[13] R. Álvarez-Nodarse, A. J. Durán, and A. M. de los Ríos, *Orthogonal matrix polynomials satisfying second order difference equation*, J. Approx. Theory 169 (2013) 40-55.

[14] A. I. Aptekarev and E. M. Nikishin, *The scattering problem for a discrete Sturm-Liouville operator*, Mat. Sb 121 (163): 327-358 (1983); Math. USSR Sb. 49 (1984) 325-355.

[15] G. Ariznabarreta and M. Mañas, *Matrix orthogonal Laurent polynomials on the unit circle and Toda type integrable systems*, Adv. Math. 264 (2014) 396-463.

[16] G. Ariznabarreta and M. Mañas, *Multivariate orthogonal polynomials and integrable systems*, arXiv:1409.0570.

[17] G. Ariznabarreta and M. Mañas, *Darboux transformations for multivariate orthogonal polynomials*, arXiv:1503.04786.

[18] G. Ariznabarreta and M. Mañas, *Multivariate orthogonal Laurent polynomials and integrable systems*, arXiv:1506.08708.

[19] G. Ariznabarreta and M. Mañas, *Linear spectral transformations for multivariate orthogonal polynomials and multispectral Toda hierarchies*, arXiv:1511.09129.

[20] C. Berg, *Fibonacci numbers and orthogonal polynomials*, J. Comput. Appl. Math. 17 (2011) 75–88.

[21] M. J. Bergvelt and A. P. E. ten Kroode, *Tau-functions and zero-curvature equations of Toda-AKNS type*, Int. Math. Res. Notices 18 (1999) 589-620.

[22] M. J. Bergvelt and A. P. E. ten Kroode, *Partitions, Vertex Operators Constructions and Multi-Component KP Equations*, Pac. J. Math. 171 (1995) 23-88.

[23] C. Brezinski, *Padé-type approximation and general orthogonal polynomials*, Int. S. Num. M. 50. Birkhäuser Verlag, Basel-Boston, Mass. 1980.

[24] M. I. Bueno and F. Marcellán, *Darboux transformations and perturbation of linear functionals*, Linear Algebra Appl. 384 (2004) 215-242.

[25] M. I. Bueno and F. Marcellán, *Polynomial perturbations of bilinear functionals and Hessenberg matrices*, Linear Algebra Appl. 414 (2006) 64-83.

[26] M. J. Cantero, F. Marcellán, L. Moral, and L. Velázquez, *Darboux transformations for CMV matrices*, arXiv:1503.05003.

[27] M. M. Castro and F. A. Grünbaum, *Orthogonal matrix polynomials satisfying first order differential equations: a collection of instructive examples*, J. Nonlinear Math. Phys. 4 (2005) 63-76.

[28] V. S. Chelyshkov, *Alternative Jacobi polynomials and orthogonal exponentials*, arXiv:1105.1838.

[29] T. S. Chihara, *An Introduction to Orthogonal Polynomials*. In : Mathematics and its Applications Series, Vol. 13. Gordon and Breach Science Publishers, New York-London-Paris, 1978.

[30] A. E. Choque-Rivero and L. E. Garza, *Moment perturbation of matrix polynomials*, Integr. Transf. Spec. F. 26 (2015) 177-191.

[31] A. R. Collar, *On the reciprocation of certain matrices*, P. Roy. Soc. Edinb. A 59 (1939) 195-206.

[32] E. B. Christoffel, *Über die Gaussische Quadratur und eine Verallgemeinerung derselben*, J. Reine Angew. Math. 55 (1858) 61–82.

[33] D. Damanik, A. Pushnitski, and B. Simon, *The analytic theory of matrix orthogonal polynomials*, Surveys in Approximation Theory 4 (2008) 1-85.

[34] G. Darboux, *Mémoire sur l’approximation des fonctions de très-grands nombres, et sur une classe étendue de développements en série*, J. Math. Pura. Appl. (3) 4 (1878) 5–56; 377–416.

[35] G. Darboux, *Sur une proposition relative aux équations linéaires*, Comptes Rendus hebd. séances Acad. Sci. Paris 94 (1882) 1456-1459.
A. Doliwa, P. M. Santini, and M. Mañas, A. J. Durán, Markov’s theorem for orthogonal matrix polynomials, M. Derevyagin, J. C. García-Ardila, and F. Marcellán, Operator approach to the Kadomtsev-Petviashvili equation. Transformation groups for soliton equations. Euclidean Lie algebras and reduction of the KP hierarchy, Publ. Res. I. Math. Sci. 18 (1982) 1077-1110.

A. Doliwa, M. Mañas, and T. Miwa, Transformation groups for soliton equations in Nonlinear Integrable Systems-Classical Theory and Quantum Theory M. Jimbo and T. Miwa (eds.). World Scientific, Singapore, 1983.

A. M. Delgado, J. S. Geronimo, P. Iliev, and F. Marcellán, Two variable orthogonal polynomials and structured matrices, SIAM J. Matrix Anal. A. 28 (2006) 118-147.

M. Derevyagin, J. C. García-Ardila, and F. Marcellán, Multiple Geronimus transformations, Linear Algebra Appl. 454 (2014) 158-183.

A. Doliwa, P. M. Santini, and M. Mañas, Transformations of Quadrilateral Lattices, J. Math. Phys. 41 (2000) 944-990.

A. J. Durán, On matrix polynomials with respect to a definite positive matrix of measures, Canad. J. Math. 47 (1995) 88-112.

A. J. Durán, Matrix inner product having a matrix symmetric second order differential operator, Rocky Mt. J. Math. 27 (1997) 585-600.

A. J. Durán and F. A. Grünbaum, A survey on orthogonal matrix polynomials satisfying second order differential equations, J. Comput. Appl. Math. 178 (2005) 169-190.

A. J. Durán and F. A. Grünbaum, Structural formulas for orthogonal matrix polynomials satisfying second order differential equations, Constr. Approx. 22 (2005) 255-271.

A. J. Durán and P. López-Rodríguez, Structural formulas for orthogonal matrix polynomials satisfying second order differential equations II, Constr. Approx. 26 (2007) 29-47.

A. J. Durán and W. Van Assche, Orthogonal matrix polynomials and higher-order recurrence relations, Linear Algebra Appl. 219 (1995) 261-280.

L. P. Eisenhart, Transformations of Surfaces, Princeton University Press, Hamburg, 1923.

P. A. Fuhrmann, Orthogonal matrix polynomials and system theory, Rend. Sem. Mat. Univ. Politec. Torino 1987, Special Issue, 68-124.

W. Gautschi, An algorithmic implementation of the generalized Christoffel theorem in Numerical Integration, edited by G. Hämmerlin, Int. S. Num. M. 57, Birkhäuser, Basel, 1982. 89-106.

I. M. Gelfand, S. Gelfand, V. S. Retakh, and R. Wilson, Quasideterminants, Adv. Math. 193 (2005) 56-141.

J. S. Geronimo, Scattering theory and matrix orthogonal polynomials on the real line, Circ. Syst. Signal Pr. 1 (1982) 471-495.

J. Geronimus, On polynomials orthogonal with regard to a given sequence of numbers, Comm. Inst. Sci. Math. Mec. Univ. Kharkoff (Zapiski Inst. Mat. Mech.) (4) 17 (1940) 3-18.

I. Gohberg, P. Lancaster, and L. Rodman, Matrix Polynomials, Computer Science and Applied Mathematics. Academic Press, Inc. Harcourt Brace Jovanovich, Publishers, New York-London, 1982.

F. A. Grünbaum, The Darboux process and a noncommutative bispectral problem: some explorations and challenges, Comm. Pure Appl. Math. 25 (2002) 353-366.

F. A. Grünbaum, I. Pacharoni, and J. Tirao, Matrix valued orthogonal polynomials of the Jacobi type, Indagat. Math. New Ser. 14 (2003) 353-366.

F. A. Grünbaum, I. Pacharoni, and J. Tirao, Matrix valued orthogonal polynomials of the Jacobi type: The role of group representation theory, Ann. I. Fourier 55 (2005) 2051-2068.

R. A. Horn and C. R. Johnson, Matrix Analysis, Second Edition, Cambridge University Press, Cambridge, 2013.

V. G. Kac and J. W. van de Leur, Matrix valued orthogonal polynomials related to theta functions and non-linear equations, Russ. Math. Surv. 36 (1981) 11-92.

M. Mañas, L. Martínez Alonso, and E. Medina, Dressing methods for geometric nets: I. Conjugate nets, J. Phys. A: Math. Gen. 33 (2000) 2871-2894.

M. Mañas, L. Martínez Alonso, and E. Medina, Dressing methods for geometric nets: II. Orthogonal and Egorov nets, J. Phys. A: Math. Gen. 33 (2000) 7181-7206.

M. Mañas, L. Martínez Alonso, and C. Álvarez-Fernández, The multicomponent 2D Toda hierarchy: discrete flows and string equations, Inverse Probl. 25 (2009) 0650077 (31pp).
DEPARTAMENTO DE MÉTODOS CUANTITATIVOS, UNIVERSIDAD PONTIFICIA COMILLAS, CALLE DE ALBERTO AGUILERA 23, 28015-MADRID, SPAIN
E-mail address: calvarez@comillas.edu

DEPARTAMENTO DE FÍSICA TEÓRICA II (MÉTODOS MATEMÁTICOS DE LA FÍSICA), UNIVERSIDAD COMPLUTENSE DE MADRID, CIUDAD UNIVERSITARIA, PLAZA DE CIENCIAS 1, 28040-MADRID, SPAIN
E-mail address: gariznab@ucm.es

DEPARTAMENTO DE MATEMÁTICAS, UNIVERSIDAD CARLOS III DE MADRID, AVENIDA UNIVERSIDAD 30, 28911 LEGANÉS, SPAIN
E-mail address: jugarcia@math.uc3m.es

DEPARTAMENTO DE FÍSICA TEÓRICA II (MÉTODOS MATEMÁTICOS DE LA FÍSICA), UNIVERSIDAD COMPLUTENSE DE MADRID, CIUDAD UNIVERSITARIA, PLAZA DE CIENCIAS 1, 28040 MADRID, SPAIN
E-mail address: manuel.manas@ucm.es

DEPARTAMENTO DE MATEMÁTICAS, UNIVERSIDAD CARLOS III DE MADRID AND INSTITUTO DE CIENCIAS MATEMÁTICAS (ICMAT), AVENIDA UNIVERSIDAD 30, 28911 LEGANÉS, SPAIN
E-mail address: pacomarc@ing.uc3m.es