On the use of Lyα emitters as probes of reionization

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ABSTRACT
We use numerical simulations to study the effects of the patchiness of a partly reionized intergalactic medium (IGM) on the observability of Lyα emitters (LAEs) at high redshifts (z ≥ 6). We present a new model that divides the Lyα radiative transfer into a (circum)galactic and an extragalactic (IGM) part, and investigate how the choice of intrinsic line model affects the IGM transmission results. We use our model to study the impact of neutral hydrogen on statistical observables such as the Lyα rest-frame equivalent width (REW) distribution, the LAE luminosity function and the two-point correlation function. We find that if the observed changes in LAE luminosity functions and equivalent width distributions between z ≈ 6 and 7 are to be explained by an increased IGM neutral fraction alone, we require an extremely late and rapid reionization scenario, where the Universe was ∼40 per cent ionized at z = 7, ∼50 per cent ionized at z = 6.5 and ∼100 per cent ionized at z = 6. This is in conflict with other observations, suggesting that intrinsic LAE evolution at z ≥ 6 cannot be completely neglected. We show how the two-point correlation function can provide more robust constraints once future observations obtain larger LAE samples, and provide predictions for the sample sizes needed to tell different reionization scenarios apart.

Key words: radiative transfer – methods: numerical – galaxies: high-redshift – galaxies: statistics.

1 INTRODUCTION

The epoch of reionization (EoR) is currently one of the major frontiers in observational cosmology. It marks the last big phase transition of the Universe, when the intergalactic medium (IGM) went from neutral to ionized. It is generally believed (e.g. Robertson et al. 2010) that the first stars and galaxies played a dominant role in ionizing the IGM, but the exact nature and timing of this important event in the history of the Universe have so far remained elusive.

Current observations of the EoR are all indirect, and do not provide very strong constraints. Spectra from high-redshift quasars show absorption bluewards of the Lyα wavelength – the so-called Gunn–Peterson troughs (Gunn & Peterson 1965) – implying that the Universe did not completely reionize until z ≈ 6 (Fan et al. 2006). Measurements of the Thompson scattering optical depth from the Wilkinson Microwave Anisotropy Probe (WMAP) satellite imply a reionization redshift of zre ≈ 10 (Komatsu et al. 2009), but are consistent also with various extended reionization scenarios.

Measurements of the IGM temperature suggest that reionization finished no earlier than z < 10 and no later than z ∼ 6.5 (Theuns et al. 2002; Hui & Haiman 2003; Raskutti et al. 2012). In the future, direct constraints on the EoR are expected to come from observations of the redshifted 21-cm line emitted by the (partly) neutral IGM. Radio telescopes such as LOw Frequency ARray (LOFAR)1, Precision Array to Probe Epoch of Reionization (PAPER)2, 21-cm Array (21CMA)3 and (Murchison Widefield Array (MWA)4 are just beginning observations that will measure statistical properties of the 21-cm radiation, and the planned Square Kilometre Array (SKA)5 will be able to image the process directly.

Meanwhile, galaxies with Lyα emission have started attracting attention as an additional indirect probe of the later stages of the EoR. The resonant nature of the Lyα line makes it sensitive to

1 http://www.lofar.org
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even small amounts of neutral hydrogen, and we thus expect the observed properties of Lyα emitters (LAEs) to change at higher redshifts, when the IGM was on average more neutral.

In the last few years, there have been many efforts to obtain large high-$z$ samples of LAEs (e.g. Malhotra & Rhoads 2004; Ouchi et al. 2010; Hu et al. 2010; Kashikawa et al. 2011), using narrow-band photometric observations and in some cases with spectroscopic confirmations. We are now starting to get sizable samples at redshifts where reionization might still be ongoing. So far, however, attempts to obtain constraints on the global IGM neutral fraction from these samples have produced somewhat different and contradictory results.

There are a number of ways one could potentially study the EoR using LAEs. Some studies (Dayal & Ferrara 2011; Dijkstra, Mesinger & Wyithe 2011) try to constrain the ionization state of the IGM based on individual detections of very high $z$ LAEs (Lehnert et al. 2010). The reasoning is that the mere observation of a single LAE would set an upper limit on the amount of neutral hydrogen present around the galaxy – were it too high, the galaxy would not have been observable.

A more common approach, and the one used in this paper, is to focus instead on the effects that an increasingly neutral IGM at higher redshifts will have on the statistical properties of the population of LAEs. Perhaps the most obvious effect is that the increased H I density at higher redshifts is expected to lead to a decrease in the fraction $x_{\text{Ly} \alpha}$ of ultraviolet (UV)-selected galaxies that also show Lyα emission (Kashikawa et al. 2006). While the observed LAE fraction increases with redshift up to $z \approx 6$ – likely due largely to the decreasing dust content in earlier galaxies (e.g. Stark et al. 2010) – there are some tantalising observational indications that $x_{\text{Ly} \alpha}$ might start to decrease for even higher $z$ (Ota et al. 2008; Stark et al. 2010; Pentericci et al. 2011; Ono et al. 2012; Schenker et al. 2012). Hayes et al. (2011) see a corresponding sharp drop in the global Lyα escape fraction. However, the uncertainties are large, and not everyone sees this effect (e.g. Tilvi et al. 2010).

An observable related to the LAE fraction is the LAE luminosity function (LF). Observations show very little evolution in the LAE LF up to $z \approx 6$ (Malhotra & Rhoads 2004; Ouchi et al. 2008; Tilvi et al. 2010). If Lyα radiation becomes attenuated by an increasingly neutral IGM at higher redshifts, we expect the LF to start dropping in amplitude. There are indeed some observations that indicate this (Ouchi et al. 2010; Kashikawa et al. 2011), although the data remain limited, especially at the faint and bright ends of the LF. If there is a connection between the Lyα luminosity of a galaxy and the transmitted fraction of Lyα photons, this could also change the shape of the LF.

A third potentially useful observable is the two-point correlation function (2PCF) of LAEs, which measures the clustering of these galaxies in the sky. The patchiness of the reionization process is expected to give rise to an increase in the clustering of galaxies (McQuinn et al. 2007; Iliev et al. 2008a; Tilvi et al. 2009; Ouchi et al. 2010). Since the Lyα transmission depends on the ionization state of the IGM in the vicinity of a galaxy, observations will favour galaxies located within large H I regions. Thus, the 2PCF will show a stronger clustering for a sample of LAEs than for a UV-selected sample with the same number density.

Accurate numerical modelling of observed LAE populations at very high redshifts is a computationally challenging task. It involves simulating the growth of structure in the early Universe, the patchy reionization of the IGM (where many essential parameters are still poorly constrained), star formation in the first galaxies and finally the complicated radiative transfer (RT) of Lyα photons. Most previous studies use simplified semi-analytical models of the IGM (Dayal, Ferrara & Gallerani 2008; Tilvi et al. 2009; Dijkstra et al. 2011), or very simple models of the LAEs themselves (McQuinn et al. 2007; Iliev et al. 2008a). Others use detailed models of both the IGM and the LAEs (Zheng et al. 2010), which comes at the cost of a higher computational complexity, resulting in a smaller part of parameter space being explored.

In this paper, we use numerical models of the IGM combined with a simple recipe for Lyα line shapes – based on detailed hydrodynamical simulations of galaxies – to obtain predictions for the statistical observables described in the introduction. Like Zheng et al. (2010), we only consider one specific reionization scenario, but by simplifying the RT of Lyα through the IGM (see Section 2.3) we are able to cover a large range of IGM-ionized fractions. This study is similar in nature to Iliev et al. (2008a), but uses an updated version of the reionization code, a bigger simulated box and a novel method for separating the complicated Lyα RT in the close vicinity of galaxies from the more straightforward calculations in the low-density IGM. Whereas Iliev et al. (2008a) simply assumed a Gaussian Lyα line shape for all emitters, we use a recipe for double-peaked profiles with little emission at the line centre, motivated by spectra from detailed RT in the vicinity of galaxies taken from cosmological smooth particle hydrodynamics (SPH) simulations. We compare the results from this line profile to the simple Gaussian model, and discuss some implications of various assumptions regarding the choice of line shape model.

The outline of the paper is as follows. In Section 2, we describe our simulations and the assumptions that went into the modelling. In Section 3, we present the results from the simulations. We discuss the line shape model used and the implications of using different line models, and the effect of the IGM on the observed line shapes. We show our simulated LFs, equivalent width distributions and correlation functions and compare these to observations where available. Finally, in Section 4, we summarize and discuss our results.

The cosmological parameters used in the simulations were for a flat Λ cold dark matter (ΛCDM) model with $(\Omega_m, \Omega_b, h, n, \sigma_8) = (0.27, 0.044, 0.7, 0.96, 0.8)$, consistent with the 5-year WMAP results (Komatsu et al. 2009).

## 2 SIMULATIONS

Our simulations were carried out in four separate steps. First, a cosmological N-body simulation was performed to obtain a time evolving density field and DM halo lists. The density field was then used to simulate the transfer of ionizing radiation and the growth of the H I regions surrounding the haloes. Separately from this, a number of galaxies were simulated in detail with a hydrodynamical code, modelling the complicated Lyα RT in the close vicinity of the galaxies. We used the spectra derived from the hydrodynamical simulations to get a picture of what the Lyα line looks like at the edge of the galaxies, and how it varies in shape with halo mass in order to devise a simplified line model. Finally, after assigning Lyα spectra to the DM haloes from our N-body simulations, we calculated the optical depth, $\tau(\lambda)$, through the IGM by tracing a large number of sightlines from each galaxy through our simulation box, taking into account the variations in density, ionized fraction and gas peculiar velocities.
2.1 N-body simulations

The N-body structure formation simulations were performed with the massively parallel, hybrid (MPI+OpenMP) code CUBEP3M (Iliev et al. 2008b; Harnois-Deraps et al. 2012), developed from the PMFAST code (Merz, Pen & Trac 2005). CUBEP3M is a particle–particle–particle–mesh code which calculates gravitational force interactions by combining long-range forces calculated on a mesh with short-range direct forces between particles. For efficiency reasons the long-range forces are calculated on two grids: a fine grid covering the local domain and a global coarse grid.

A spherical overdensity method was used to identify DM haloes. This method starts by identifying local maxima in the fine grid density distribution, and proceeds by enclosing these in successively larger spheres until the average density inside the sphere is below 178 times the global mean density. The N-body code was run on a cube with a side of 163 comoving Mpc (hereafter cMpc) with a fine grid of 6144^3 points using 3072^3 particles, and finally regridded on to a grid with 512^3 cells. This box size is large enough that cosmic variance effects are small (Barkana & Loeb 2004). The smallest resolved haloes consisted of 20 particles, which gives a minimum halo mass of 10^5 M⊙, corresponding to the mass at which atomic cooling becomes important (see Iliev et al. 2012 for details).

2.2 Radiative transfer of ionizing radiation

For the simulation of the RT of ionizing radiation from the galaxies identified in the previous step, we used the code c^2-RAY – conservative, causal ray-tracing method (Mellema et al. 2006). In c^2-RAY, each source – taken from the N-body runs described above – is given a flux proportional to its mass, M_g, so that the photoionization rate from each source at a distance r is

$$\Gamma(r) = \frac{1}{4\pi} \int \frac{M_g \Omega_H}{10^5 m_p} \sigma_r e^{-\tau_g} d\nu (\text{Myr}^{-1}),$$

where \(\sigma_r\) is the ionization cross-section for hydrogen, \(\tau_g\) is the optical depth, \(m_p\) is the proton mass and \(\Omega_H\) is the threshold energy for ionization of hydrogen. The factor \(g_g\) is a model parameter which determines the halo mass–ionizing flux relation. More precisely, it is the number of ionizing photons escaping the galaxy per halo baryon per 10 Myr, which depends on assumptions about the initial mass function, star formation efficiency and escape fraction of the radiation escaping from galaxies and more efficient sources would reionize the Universe earlier. Given these uncertainties, we will refer to our simulated IGM boxes by mass-weighted ionized fraction, \(\langle x \rangle_m\), rather than redshift. Effectively, we are assuming that the curve in Fig. 2 could in reality be translated slightly along the x-axis, i.e. reionization could be taking place somewhat earlier or later in our simulations. We believe that this is reasonable if the actual topology of reionization is not substantially different from our model (Friedrich et al. 2011; Iliev et al. 2012).

The simulation used here does not include the effects of gas clumping and Lyman limit systems and therefore likely overestimates the redshift of the end of reionization. On the other hand, there is considerable uncertainty in the luminosity of ionizing radiation escaping from galaxies and more efficient sources would reionize the Universe earlier. Given these uncertainties, we refer to our simulated IGM boxes by mass-weighted ionized fraction, \(\langle x \rangle_m\), rather than redshift. Effectively, we are assuming that the curve in Fig. 2 could in reality be translated slightly along the x-axis, i.e. reionization could be taking place somewhere earlier than it is in our simulations.

2.3 Lyα radiative transfer through the IGM

While the general problem of Lyα RT is complex and computationally demanding (e.g. Zheng et al. 2010), it can be greatly simplified in the low-density IGM far away from the galaxy where the radiation was emitted. In the high-density region close to the galaxy, photons are scattered in and out of the line of sight, undergoing frequency changes on the way. Simulating this process requires very high resolution and many assumptions regarding, for instance, dust content and star formation. However, as was shown in Laursen, Sommer-Larsen & Razoumov (2011), after a distance of ~1.5 times the virial radius of the galaxy, very few photons are scattered into the line of sight, and therefore it is justified to divide the RT into two regimes: a galaxy part where photons diffuse out of the optically thick gas around the halo (discussed in Section 2.4) and an IGM part where we consider only scatterings out of the line of sight (effectively absorption). We set the boundary between these two regimes to be at 1.5 r_h. This division is schematically outlined in Fig. 3.
Probing reionization with Ly\(\alpha\) emitters

Figure 1. Output from our IGM simulations at a global ionized fraction \(\langle x \rangle_m = 0.67\). The figures show a 1-cell thick (=0.64 cMpc) slice of the IGM. All figures are 163 cMpc across. Top left: ionized fraction (white is ionized, black is neutral). Top right: H\(\text{I}\) + H\(\text{II}\) density. Bottom left: halo positions for \(M_h > 10^{10}\) M\(_\odot\). Bottom right: neutral hydrogen density.

Figure 2. Evolution of the ionization state of the IGM during the late stages of our simulations. The dotted line shows the mean ionized fraction by volume, and the dashed line shows the mean ionized fraction by mass. The (circum) galactic part will be discussed in the next section. For the extragalactic part, we use a modified version of the code IGMTRANSFER (Laursen et al. 2011). IGMTRANSFER calculates the Ly\(\alpha\) transmission function \(F(\lambda)\) for a given wavelength interval, i.e. the transmitted fraction of radiation as a function of wavelength. Note that this is independent of the shape of the emission line.

The transmission function is given by

\[ F(\lambda) = e^{-\tau(\lambda)}, \]

(3)

Figure 3. The two different radiative transfer regimes in our model. In the dense medium inside and close to the halo, the line – initially with a Voigt profile – can become broadened and shifted and typically obtains an absorption feature at the Ly\(\alpha\) line centre. In this optically thick regime, photons scatter both into and out of the line of sight. As the radiation enters the less dense IGM, scatterings into the line of sight become extremely rare, and it becomes justified to consider only scatterings out of the sightline. Figure adapted from Laursen (2010). Note that the colours are only for telling different photons apart; they are not related to photon wavelengths.
where the optical depth, \( \tau \), is calculated by stepping through the box along a line of sight, while summing the \( \tau \) from each cell:

\[
\tau(\lambda) = \sum_{i} n_{II} \sigma_{II} \alpha(\lambda + \lambda_{II,i}/c) \Delta r.
\]

(4)

Here, \( \Delta r \) is the length of each step, \( n_{II,i} \) is the neutral hydrogen density, \( \sigma_{II} \) is the neutral hydrogen cross-section to Ly\( \alpha \) scattering and \( \lambda_{II,i} \) is the gas velocity component of the cell along the line of sight, including the Hubble flow. The sightline is traced until photons at 1190 Å well outside the Ly\( \alpha \) line profile considered here - have redshifted into resonance. The IGM temperature was assumed to be \( 10^4 \) K everywhere.

In the original version of IGMTRANSFER, photons are emitted in random directions and bounce randomly as they hit the edge of the box. Since our simulated box uses periodic boundary conditions, we modified the code so that sightlines travel through the periodic box instead of bouncing. We also added the possibility to more finely sample the IGM box. While the original version of IGMTRANSFER is limited to sampling each cell only once, we now divide each cell into many smaller subdivisions (\( \Delta r \) in equation 4), which gives more reliable results for \( F(\lambda) \).

Furthermore, we added the possibility to specify sightline directions, rather than having photons emitted in random directions.

A cosmological simulation unavoidably involves a trade-off between resolution and volume. Bolton & Becker (2009) studied the impact of resolution and box size on various observables in cosmological hydro simulations at \( 2 \lesssim z \lesssim 5 \) and found that a gas particle mass resolution of \( M \sim 10^4 - 10^5 M_\odot \) is needed for the simulations to converge. However, at the high redshifts that we have been studying, the neutral fraction in the lowest density regions, i.e. far from the galaxies, first of all is still sufficiently high that virtually no radiation is transmitted, and secondly corresponds to wavelengths in the transmitted spectra very far from the Ly\( \alpha \) line centre. Conversely, the regions that do affect the line are so close to the galaxies that they typically are much better resolved in the underlying N-body simulations.

In general, a lower resolution will smear out the underlying density field and give a higher optical depth, as seen in Bolton & Becker (2009). However, a higher resolution may also start to resolve very dense, self-shielded objects that give rise to damping wings and actually lower the transmission, as shown recently by Bolton & Haehnelt (2012). Both of these studies use a spatially uniform UV background (UVB), and it remains to be seen exactly how the results will be affected by a more realistic, fluctuating ionizing flux.

### 2.4 Ly\( \alpha \) line model

From the previous steps we have snapshots of the IGM and DM density, gas peculiar velocities, halo lists and a method for calculating the transmission of Ly\( \alpha \) in the low-density IGM regime. The only missing piece of the puzzle is the emitted spectra \( J_{\text{em}}(\lambda) \), i.e. the Ly\( \alpha \) spectra as they look as they emerge from the galaxies, here taken to be at a distance of 1.5 \( r_{\text{vir}} \) from the galaxy centre, as discussed earlier. These are to be multiplied by \( F(\lambda) \) to get the observed spectra.

Some previous studies (Dijkstra, Lidz & Wyithe 2007; McQuinn et al. 2007; Iliev et al. 2008a) simply assume a Gaussian line shape, and apply equation (3) directly to this. While this may give a rough picture of the effects of the IGM, it ignores the fact that equation (3) is only valid in the very low density IGM. For the (circum)galactic part (within 1.5 \( r_{\text{vir}} \)), full RT is required, along with a detailed model of the structure of the galaxies.

We will use the term intrinsic line to mean the Ly\( \alpha \) line at the border between the interstellar medium (ISM) and the IGM. For our fiducial line model (introduced below), this is taken to be 1.5 \( r_{\text{vir}} \). However, when we compare to the Gaussian line results, we will start the sightlines at the halo centres, essentially treating the halo as part of the IGM. This is done to facilitate fair comparisons to earlier studies, such as Iliev et al. (2008a).

In the case of a spherically symmetric, homogeneous \( H_I \) distribution, the problem of Ly\( \alpha \) RT can be solved analytically (Dijkstra, Haiman & Spaans 2006a). The resulting line shape emerging from the galaxy has the form:

\[
J_{\text{em}}(x) = \frac{\sqrt{x}}{24 \alpha \tau_0} \left( 1 + \cosh(\sqrt{27/\pi} |x/a\tau_0|) \right),
\]

(5)

where \( x \) is the frequency shifted to the Ly\( \alpha \) line centre and divided by the Doppler width of the line, \( a \) is the Voigt parameter and \( \tau_0 \) is the optical depth to the surface of the galaxy. This line is plotted in Fig. 4 for some typical galaxy parameters (dotted red line in the bottom part of the figure).

Observed Ly\( \alpha \) lines will deviate significantly from equation (5) since real galaxies are neither homogeneous nor spherical but disc-like and clumpy and may have complicated outflows and inflows. To investigate how these factors complicate the spectra, we isolated a smaller, high-resolution, sample of \( \sim 2000 \) galaxies from a separate cosmological SPH simulation at four different redshift epochs (\( z = [6.0, 7.0, 7.8, 8.8] \)) and ran detailed Ly\( \alpha \) RT calculations on these.

The cosmological simulation is similar to the ones outlined in Laursen et al. (2011), which themselves are a significant improvement on the ones described in Sommer-Larsen, Götz & Portinari (2003) and Sommer-Larsen (2006). The reader is referred to these papers for a detailed description of the code; in short, it is a TreeSPH code using self-consistent, ab initio hydro/gravity simulations to calculate the structure in a spherical region of linear dimension \( 10 h^{-1} \) cMpc. The masses of the SPH and DM particles were \( 7.0 \times 10^9 \) and \( 3.9 \times 10^8 \) \( M_\odot \), respectively, and the minimum smoothing length \( \sim 100 \) pc. A simplified ionizing UV RT scheme is invoked, modelling the metagalactic UVB after Haardt & Madau (1996).

The galaxies span several orders of magnitude in stellar mass, from \( 10^9 \) to \( 10^{10} M_\odot \). Before the Ly\( \alpha \) RT, the physical parameters

![Figure 4. Some examples of simulated intrinsic Ly\( \alpha \) line profiles (top), and the various simplified models discussed in the text (bottom). All line profiles are normalized with arbitrary units on the y-axis.](https://example.com/fig4.png)
of the gas particles (neutral hydrogen density, temperature, bulk velocity, dust density and Lyα emissivity from both cooling radiation and recombinations following ionization; at these high redshifts, the two processes contribute roughly equally to the total Lyα luminosity) are first interpolated on to a mesh of adaptively refined cells, using their original kernel function. The resulting galaxies then each consist of $10^2-10^3\, M_\odot$. However, although the physical size of the smallest cells is $\sim 10\, \text{pc}$, typically the best resolution is in fact some 100 pc. Finally, the full RT is conducted using the Monte Carlo code MOCALATA (Laursen, Razoumov & Sommer-Larsen 2009a; Laursen, Sommer-Larsen & Andersen 2009b), calculating the spectra emerging at a distance of 1.5 virial radii from the centre of the galaxies by tracing individual photon packets as they scatter out through the ISM.

Simulating Lyα production and RT in very high $z$ galaxies involves many poorly constrained parameters such as star formation rates, dust content, ISM ionization structure and gas clumpiness. While the simulations in our high-resolution galaxy sample give a fairly detailed picture of the Lyα line, the resolution is still too low to fully trust all aspects of the results as-is. For instance, we find that the values of the Lyα luminosities are somewhat too low to match observations. However, we assume that the general shapes of the emerging Lyα lines and their dependence on halo mass are reasonable.

A small number of the simulated lines are plotted in the top panel of Fig. 4. We find that the lines in general have a double-peaked structure, with close to zero emission at the line centre, in agreement with equation (5). However, the two peaks are generally asymmetric, falling off more slowly away from the line centre. We also find that the lines tend to become broader for higher mass galaxies. This general line shape is familiar from both observations and other simulations (e.g. Tapken et al. 2007; Verhamme et al. 2008; Yamada et al. 2012). The presence of neutral hydrogen in the ISM makes it difficult for Lyα photons to escape before they have scattered and become red- or blueshifted away from the line centre. While not all observed lines show the double-peaked line profile, they typically have most of the emission at wavelengths away from the line centre. This is in contrast to the Gaussian model, where the peak of the emission is exactly at the line centre. As we shall see in Section 3, this difference has a significant effect on the Lyα transmission through the IGM.

To model the line shapes from our high-resolution galaxy sample, we adopt a Gaussian-minus-a-Gaussian (GmG) line shape with a width that depends on the halo mass:

$$J_{\text{em}}(\lambda) \propto e^{-\left(\frac{\lambda - \lambda_0}{\sigma_1}\right)^2/2\sigma_1^2} - e^{-\left(\frac{\lambda - \lambda_0}{\sigma_2}\right)^2/2\sigma_2^2}.$$  \hspace{1cm} (6)

By fitting such lines to all the spectra in our high-resolution galaxy sample, we find that $\sigma_1$ and $\sigma_2$ both increase with halo mass, roughly as

$$\sigma_1 = -6.5 + 0.75 \log M_\odot/M_\odot$$  \hspace{1cm} (7)

$$\sigma_2 = -3.2 + 0.35 \log M_\odot/M_\odot,$$  \hspace{1cm} (8)

i.e. the line shapes tend to become broader for more massive galaxies.

While somewhat ad hoc, the GmG model appears to reproduce the simulated line shapes rather well. As we will show in Section 3, the important distinction when it comes to IGM transmission is whether most of the emission is at the line centre (as in the Gaussian model) or offset from the line centre (as in the GmG model), and not in the exact shape of the peaks. Since low-$z$ observations, analytical models and simulations all tend to show line shapes with either double peaks or a single peak on the blue side of the line centre (e.g. Wilman et al. 2005; Dijkstra et al. 2006a; Dijkstra, Haiman & Spaans 2006b; Verhamme et al. 2008), we adopt equations (6)–(8) as our fiducial model.

Observed Lyα line profiles – in contrast to our model spectra – often have one peak that is stronger than the other. Gas that is falling into the galaxy may cause the red peak to become weaker than the blue one, and outflows will have the opposite effect (e.g. Dijkstra et al. 2011). Such asymmetries can have a large effect on the absolute value of the fraction of Lyα photons that are transmitted through the IGM. However, in this paper we calibrate our intrinsic luminosities against observations (see Section 3.2.1), which means that the absolute values of the transmitted fractions have little or no effect on our results. What we are interested in is mainly the dependence of the transmission on quantities such as the local H i density and halo mass. These dependencies will be largely unaffected by asymmetries in the peaks.

In our analyses, we generally make the assumption that the intrinsic properties of LAEs (i.e. luminosities and Lyα line shapes) do not change during the time interval we are studying. This is a strong assumption, and one that is widely debated. Kashikawa et al. (2011) argue that it is probably reasonable at least up to $z = 6.5$ given that observations of the UV LF – which is insensitive to the IGM – stay the same between $z = 5.7$ and 6.5 within the error bars. Others, such as Ouchi et al. (2010), do observe evolution in the UV LF, implying that the changes in LAE populations are due at least in part to intrinsic source evolution. In Section 4, we discuss the implications of the no-intrinsic-evolution assumption on our results.

3 RESULTS

3.1 General effects of the IGM

Using the methods described above, we assign spectra according to equations (6)–(8) to all haloes in our box with $M_\odot > 10^{10}\, M_\odot$. We then trace 50 sightlines per halo in different directions through the IGM box and calculate the IGM transmission function for each one.

Even a very small amount of neutral hydrogen is enough to absorb virtually all radiation bluewards of Lyα. For a highly ionized IGM, with only some very small amount of residual H i, the transmission $F(\lambda)$ resembles a step function. At higher neutral fractions (and for certain individual sightlines in the more ionized cases), the transmissions begin showing damping wings that absorb some flux on the red side of the line centre, as illustrated in the top panel of Fig. 5.

The middle panel of Fig. 5 shows the evolution of the probability density function (PDF) of the transmitted fraction, $T_\alpha$, defined as

$$T_\alpha = \frac{\int J_{\text{em}}(\lambda) F(\lambda) \, d\lambda}{\int J_{\text{em}}(\lambda) \, d\lambda}.$$  \hspace{1cm} (9)

The PDFs were calculated over all the simulated sightlines, using the GmG line shape model (for comparison, we also show the results from the Gaussian line model). Note that $T_\alpha$ depends only on the shape of the intrinsic line, and not on the value of the Lyα luminosity (we will discuss luminosities later on). Furthermore, since the blue peak is usually completely absorbed, only the red peak has an effect on the variation in $T_\alpha$ with damping wing strength. The blue peak only affects the absolute value of $T_\alpha$.

In a more neutral IGM, the strength of the damping wing is the most important factor for determining $T_\alpha$. For low ionized fractions, the damping wings are strong enough to absorb almost all the
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Figure 5. Top: median IGM transmission functions for varying ionized fractions. Middle: probability density functions of the transmitted fraction of Ly$\alpha$ photons for all our simulated sightlines, i.e. 50 sightlines each for all haloes with $M_h > 10^{10}$ $M_\odot$. The solid lines are for the GmG line profile and the dotted lines are for the Gaussian profile. The colour coding is the same as for the top figure. Bottom: examples of observed line shapes for a $10^{10}$ $M_\odot$ halo. The grey line shows the intrinsic line.

emitted photons, and the PDF peaks at only a few per cent transmission. For intermediate $(x)_m$, the large variation in damping wing strength among different sightlines becomes apparent as the PDF becomes very broad.

As we approach $(x)_m = 1$, the distribution of $T_\alpha$ clusters very strongly around 50 per cent. This effect is made stronger by the double-peaked nature of the line profile. At this point, any damping wings will be weak, and mostly affect the transmission close to the line centre. But since most of the emission is in the wings, a couple of Å away from the centre, the transmitted line will consist of most of the red wing and nothing more.

A single-peaked line profile centred on the Ly$\alpha$ line centre is more sensitive to damping wing strength than a line profile with most of the emission offset from the line centre, such as our GmG model. This results in wider $T_\alpha$ PDFs, as seen in the middle panel of Fig. 5. It also affects the average value of $T_\alpha$ as a function of $(x)_m$, as we show in Fig. 6. The GmG model has a somewhat flatter relation between $(T_\alpha)$ and $(x)_m$, especially at the later stages of the EoR. In other words, using a simplified model such as the single-peaked Gaussian may result in an overprediction of the IGM absorption.

3.1.1 $T_\alpha$ dependence on halo mass

While the global mean value of $T_\alpha$ at a given redshift is the most important factor in determining the change in LAE LF and the decrease in the LAE fraction, the relationship between halo mass and $T_\alpha$ can affect a number of second-order effects, such as the shape of the LF and the IGM-induced boost of the correlation function. This relationship is complex and depends on a number of factors.

The strength of the damping wing depends on the density of neutral hydrogen in the close vicinity of the source, and the transmitted fraction of Ly$\alpha$ will be a tracer of the size of the H II region around the source. Since massive haloes tend to produce more ionizing photons, one would expect their surrounding H II regions to be larger, leading to higher values for $T_\alpha$. Furthermore, massive haloes predominantly form in highly biased regions with many smaller mass neighbours. These all contribute to enlarge the H II region and, again, lead to larger $T_\alpha$. On the other hand, more massive haloes will tend to have more infalling gas, which tends to quench the blue portion of the Ly$\alpha$ spectrum and give a lower IGM transmission. Also, the biased regions with the most massive haloes will typically have a higher gas density, which – if not highly ionized – will lower the transmission.

Earlier studies have approached this problem in different ways, and come to different conclusions about the halo mass–$T_\alpha$ relation. Iliev et al. (2008a) use a simple Gaussian model and find that infalling gas gives a lower transmitted fraction for more massive haloes. McQuinn et al. (2007) perform similar simulations, but find almost no trend at all in two of their models, and an opposite trend in their model with the largest H II regions. Zheng et al. (2010) perform full RT calculations, and find a weak trend with lower $T_\alpha$ for higher mass haloes, which they attribute to the higher density in the regions around these objects.

In Fig. 7 we show the relation between $(T_\alpha)$ and halo mass for four different line models. The two single Gaussian models refer to the models used in Iliev et al. (2008a) – one with a constant line width of 150 km s$^{-1}$ and one with a width of 150 km s$^{-1} \times [M_h/(10^{10} M_\odot)]^{1/3}$. The analytical solution refers to the line shape given in equation (5). In addition, we show the results of using the single-width Gaussian line, but starting the sightlines 1.5 virial radii outside the galaxies.

For our GmG model, there is a clear trend of higher $(T_\alpha)$ for higher halo mass. This seems to contradict the results of Iliev et al. (2008a), who found a negative correlation. This discrepancy is most likely due to the fact that they did not divide the Ly$\alpha$ RT into two regimes, as we discussed in Section 2.3. Since the amount of infall is largest close to the galaxies, this cannot be studied with the exp($-\tau$) model, but needs full RT. In our model, where we start the IGM RT at 1.5 $r_{200}$, we implicitly compensate for most of the infall effects when we fit the mass-to-light ratio in Section 3.2.1.

The green and yellow lines of Fig. 7 show the results from using the Gaussian model, starting sightlines at the halo centres. Here, we do indeed see the same trends as Iliev et al. (2008a), with lower transmission for high-mass haloes at high $(x)_m$, especially for the single-width line model. However, if we start the Gaussian lines at...
Probing reionization with Lyα emitters

The effect of the galaxies (grey dash–dotted lines), the infall trends disappear completely, indicating that the regions very close to the galaxies have a large effect on the transmission. Since these regions are not properly resolved in our large-scale simulation, one should be careful to draw any firm conclusions on the effects of infall based on these results. In our high-resolution galaxy sample, we saw no strong effects from infall, but higher resolution and better knowledge of input parameters are likely needed to properly study this. Also, different reionization models can give different results, as seen in McQuinn et al. (2007). The reionization scenario used in Iliev et al. (2008a) did not include self-regulation effects, and so one should be careful when comparing their results to the ones presented here.

The main reason for the positive correlation seen when splitting the RT into two parts is that higher mass haloes are usually located in larger H II regions. This is due partly to the fact that large galaxies emit more ionizing radiation than smaller ones, and thus ionize the gas around them to a larger extent. However, it is likely more dependent on the fact that high-mass haloes tend to be located in biased regions with many neighbouring haloes surrounding them. These neighbours all help create large H II regions, as was also discussed in Iliev et al. (2008a). In Fig. 8, we show the correlation between \( \langle T_\alpha \rangle \) and the number of close neighbour haloes (here defined as haloes within 5 cMpc, a distance which typically puts neighbours within the same H II region) for haloes with \( \log M_h/M_\odot \approx 10 \). Since all these haloes have the same mass, they all ionize the IGM to the same extent, and have similar amounts of infall. Still there is a fairly strong correlation between number of neighbours and \( \langle T_\alpha \rangle \).

The second thing to note in Fig. 7 is that even if we fix the starting point of the sightlines to 1.5 \( r_{\text{vir}} \), the choice of line model has an appreciable effect on the results. As we discussed above, lines with a lot of emission at the line centre are more sensitive to damping wing strength, while the double-peaked models (GmG, analytical) tend to give somewhat flatter relations between \( T_\alpha \) and halo mass.

In summary, the exact nature of the halo mass–\( T_\alpha \) relation is complicated, and will depend on the definition of \( T_\alpha \) and assumptions about the Lyα line shape. Here, we are interested in the effects of the IGM, and define \( T_\alpha \) as the transmission through the IGM after the photons leave the galaxies. For this definition, we see a fairly weak trend with higher transmission for higher mass haloes. In our model, any infall effects that are taking place close to the galaxies will be calibrated away when we fit the luminosities later on.

### 3.2 LAE luminosity functions

Observing the evolution of the LAE LF with redshift can provide information about both the change in intrinsic properties of the galaxies and the changing state of the surrounding IGM. Unfortunately, it is far from straightforward to disentangle these effects. For example, a decrease in the LF could come from a decrease in star formation, a higher dust content, a denser and/or more neutral IGM or a combination of all three.

The LAE LF appears to change very little, if at all, up to around \( z = 6 \) (Malhotra & Rhoades 2004; Ouchi et al. 2008; Tilvi et al. 2010). In other words, if the reionization of the Universe is still ongoing at these redshifts, the decrease in observability of LAEs...
due to the neutral IGM must be counteracted by an intrinsic change of the galaxy properties, such as a lower dust content.

However, at higher redshifts there is an observed change in the LF. Ouchi et al. (2010, hereafter Ou10) observe a sample of 207 LAEs at $z = 6.5$ in the Subaru/XMM-Newton Deep Survey (SXDS) field, and find that the LF at $z = 6.5$ is different from the observations at $z = 5.7$ with a fairly high degree of certainty. By comparing to simulations by McQuinn et al. (2007), Iliev et al. (2008a), Dijkstra et al. (2007) and Furlanetto, Zaldarriaga & Hernquist (2006), they conclude that this suggests a change in neutral fraction of the IGM of $\Delta(x)_m \approx 0.2$. This value assumes a model for the intrinsic evolution of LAEs based on observed changes in the UV LF.

Kashikawa et al. (2006) and Kashikawa et al. (2011, hereafter Ka11) also observe the LAE LF at $z = 6.5$ in the Subaru Deep Field (which is separate from the SXDS field of Ou10) and see a difference compared to $z = 5.7$. Comparing their results to models both by McQuinn et al. (2007) – who do not include any intrinsic galaxy evolution – and Kobayashi, Totani & Nagashima (2010) – who do model intrinsic evolution – they require $\Delta(x)_m \sim 0.4$ at $z = 6.5$. This assumption is motivated by the fact that, in contrast to Ou10, do not see any evolution in the UV LF during the same time interval. Dayal et al. (2008) are able to reproduce the LF evolution between $z = 6$ and $6.5$ with only galaxy mass evolution, but this then requires a very sharp drop in Ly$\alpha$ escape fraction to explain the absence of change in the LF at $z < 6$.

### 3.2.1 Intrinsic luminosity model

We now investigate for which ionized fraction our models best reproduce the observed LFs by Ou10 and Ka11. For this we need a model for the Ly$\alpha$ luminosity of our simulated haloes. Iliev et al. (2008a) and McQuinn et al. (2007) assume a constant ratio between DM halo mass and Ly$\alpha$ luminosity, and fit this to the observations. In reality, however, we expect there to be some variation in luminosity among haloes of the same mass, which is also what we see in the detailed simulations of our high-resolution galaxy sample. Not only is there not a direct one-to-one relation between halo mass and production of Ly$\alpha$ photons, but the escape fraction can vary a lot between different sightlines (Laursen & Sommer-Larsen 2007). While a constant mass-to-light ratio will give a LAE LF with a shape very similar to the mass function (the difference coming only from the dependence of $T_e$ on halo mass), adding some random scatter to this relation will tend to flatten the LF and give a higher bright end and a lower faint end.

We attempt to find a good model for the Ly$\alpha$ luminosity by fitting our results to the observed LF at $z = 5.7$ from Ou10. Our IGM simulation does not go down to such low redshifts, so we take our lowest redshift halo sample, from $z = 0.6$, and make the assumption that $(T_e) = 0.5$ for all haloes at this redshift. This is motivated by Fig. 5, where it is shown that the $T_e$ distribution becomes very narrow and centred on 0.5 for low neutral fractions (as is shown in Songaila 2004, there is still enough residual H i to remove the blue part of the spectrum completely).

In Fig. 9 we show our best fit to the observations, assuming a model where the Ly$\alpha$ luminosities of haloes of a given mass follow a log-normal probability distribution with a mean that is proportional to the halo mass, and a fixed width. When fitting this relation to the observations, we fixed the scatter to $\sigma = 0.4$ (see equation 10). This value and the log-normal distribution were motivated by the simulations of the high-resolution galaxy sample discussed in Section 2.4, and are similar to the model used by Muñoz & Loeb (2011). The constant mass-to-light model is roughly consistent with the data, but appears to give slightly too steep a bright end. The log-normal-scatter model, however, matches the observations very well. By $\chi^2$ minimization on a grid, we find that the best fit to the observations is

$$\log L_\alpha [\text{erg s}^{-1}] = \log(M_*/M_\odot) + \text{norm}(\mu = 31.7, \sigma = 0.4),$$

where $\text{norm}(\sigma, \mu)$ denotes a random variable distributed according to a normal distribution with mean value $\mu$ and width $\sigma$.

We would like to point out that the value of $\mu$ in equation (10) should not be interpreted too strictly. As we discussed earlier, there is a degeneracy between the absolute value of $T_e$ and the intrinsic luminosity. Had we used a line model with a stronger red peak, our $T_e$ values would be higher, and, consequently, the intrinsic luminosities lower. In this study, we are only concerned with the dependence of $T_e$ on, for instance, IGM neutral fraction and halo mass, and so this degeneracy has little effect on our results.

### 3.2.2 Comparison to observations at $z = 6.5$

In Fig. 10, we show simulated LFs for different IGM ionization states, compared to observations at $z \sim 6.5$ by Ou10 and Ka11. It is evident from this figure that the uncertainties in the observations are too large to put any robust constraints on $(x)_m$ at $z = 6.5$. Nevertheless, we still investigate for which $(x)_m$ our simulations best fit the data.

To do this, we make the simplifying assumption that the underlying intrinsic LAE LF does not change between $z = 6$ and 6.5, in accordance with the observations at lower redshifts discussed above. For this purpose, in producing Fig. 10, we have scaled the underlying halo masses in such a way as to give a constant LAE mass function at all ionization states. This ensures that all the evolution in the LF comes from the changing ionization state of the IGM. We then go on to calculate the $\chi^2$ goodness of fit, comparing the LFs in Fig. 10 to the observations by Ou10 and Ka11. The best fit is for an IGM-ionized fraction of around $(x)_m \sim 0.5$, but the errors in the data are still too large to get a robust constraint. However, it is interesting to note that both the Ou10 and Ka11 samples, which come from different fields, give the same best-fitting value.

It is worth pointing out here that while we look for the best-fitting ionized fraction at $z = 6.5$, this value for $(x)_m$ occurs already at
proceeding from earlier, and the comparison is still reasonable, since the equations in our IGM simulations were not significantly altered by the assumptions above.

The value of $\langle x \rangle_m \sim 0.5$ at $z = 6.5$ is in conflict with other measurements as we will discuss in Section 4, which casts some doubt on the assumption that the drop in LF is due only to an increasingly neutral IGM. If we drop this assumption and allow the mass of the DM haloes to evolve according to our N-body simulations while assuming that equation (10) holds at all times (i.e. there is no change in dust content, star formation efficiency, etc.), then we find that the drop in LF can be explained with an IGM that is completely neutral already at $z > 6.5$. This, however, would imply that the LF continues to grow in amplitude at $z < 6$, which is incompatible with observations. It would seem most likely that the LF drop is due to a combination of IGM and intrinsic evolution, but observations of LAEs alone cannot break this degeneracy.

3.2.3 Sample variance

In the figures below, we illustrate the effect of cosmic variance and statistical fluctuations when observing in a limited field. We do this by considering three different observational boxes.

(i) The full box. This is our entire simulated 163 cMpc box, where we assume that we have the full 3D positions of all the haloes.

(ii) A deep box. An optimistic approximation of what might be observed in a future space-based survey, e.g. with the James Webb Space Telescope (JWST). Such a survey will have trouble achieving a large field of view, but is unconstrained by atmospheric effects and so can, given enough time, obtain spectroscopy over a large redshift range. We assume that this box is 60 arcmin$^2$, $\sim 1/6$ the side of the full box, with the depth set to the whole box depth. We also assume, optimistically, that we have spectroscopic data, i.e. 3D positions, of all the galaxies in the box.

(iii) A thin box. This approximates a large ground-based photometric survey with a large field of view but limited redshift range. We assume a field of 1 deg$^2$ which is approximately the size of our full box, with $\Delta z = 0.1$, i.e. 1/5 the depth of the full box. Here we assume that we only know the 2D positions of the haloes. This is roughly equivalent to the Subaru Deep Field (Ka11).

Fig. 11 shows the field-to-field variation in LAE LFs. The figure was produced by splitting our simulation box into many small sub-boxes, and calculating the LAE LF for each sub-box. It is clear that sample variance becomes a major issue in a small field such as our deep box. Here, the field-to-field variation is very large compared to the change in LF due to an increasing neutral fraction, as seen in Fig. 10, and in many cases the higher luminosity bins end up empty, making the bright end very difficult to study. However, for the thin box, the field-to-field variation is of the same order as a $\sim 10$ per cent change in $\langle x \rangle_m$, at least at the faint and intermediate parts of the LF. In Fig. 12, we show the number of LAEs above a given luminosity in the full box and the sub-boxes.

3.3 LAE fraction

Several observers report a sharp decrease in the fraction $x_{L\alpha}$ of dropout-selected galaxies that show Ly$\alpha$ emission between redshifts 6 and 7 (Ota et al. 2008; Stark et al. 2010; Pentericci et al. 2011; Ono et al. 2012; Schenker et al. 2012). For example, Pentericci et al. (2011) observe a sample of 20 dropout-selected galaxies, and find Ly$\alpha$ emission in only three, and Schenker et al. (2012) find only two LAEs (plus one possible) in a sample of 19 dropout. While there are a number of effects that could explain this, probably the most obvious one would be an increase in the IGM neutral fraction, as noted by e.g. Forero-Romero et al. (2012).

Here, we follow the procedure of Dijkstra et al. (2011) to estimate the decrease in $x_{L\alpha}$ for an increasing neutral fraction, using the distribution of observed Ly$\alpha$ rest-frame equivalent widths (REWs). We begin by assuming that the REWs at $z = 6$ are distributed according to an exponential distribution $P_{\text{cum}}(\text{REW}) \propto \exp(-\text{REW}/\text{REW}_c)$ and setting $\text{REW}_c = 50$ Å to match the observations at this redshift (Stark et al. 2010). Making again the simplifying assumption of no intrinsic LAE evolution, the distribution at some other redshift $z$ can be written as

$$P_z(\text{REW}) = N \int_0^{1/\alpha_z} P_{\text{cum}}(\text{REW}/T_z) P_z(T_z) \, dT_z,$$

(11)
where $P_z(T_\alpha)$ is the PDF of the Ly$\alpha$ transmitted fraction, shown in Fig. 5, $N$ is a normalization constant and $P_{\text{intr}}$ is the REW distribution for $T_\alpha = 1$.

Dijkstra et al. (2011) assume, conservatively, that the IGM transmission is 100 per cent at $z = 6$, i.e. that $P_{\text{abs}}(T_\alpha) = P_{\text{intr}}$(REW). Since observations show close to zero transmission on the blue side (Songaila 2004), this assumption is only valid if the intrinsic lines are very heavily biased towards the red wing, which is true in the model of Dijkstra et al. (2011), but not for our GmG model.

To keep consistency with our previous discussion in Section 3.2.1, we assume that the IGM is very close to fully ionized at $z = 6$, but still retains a small amount of residual H i that absorbs the blue wing of the Ly$\alpha$ line, so that the $T_\alpha$ PDF takes the form $P_{\text{abs}}(T_\alpha) = \delta(T_\alpha - 0.5)$. This assumption is actually very similar to that of Dijkstra et al. (2011), since their emission is mostly at the red side of the line centre. Inserting this into equation (11) gives the intrinsic equivalent width distribution:

$$P_{\text{c-abs}}(\text{REW}) = N \int_0^1 P_{\text{intr}}(\text{REW}/T_\alpha) \delta(T_\alpha - 0.5) dT_\alpha = NP_{\text{intr}}(\text{REW}/0.5),$$

so that

$$P_{\text{intr}}(\text{REW}) \propto \exp \left( \frac{0.5 \text{REW}}{\text{REW}_c} \right).$$

Using this expression for $P_{\text{intr}}$(REW) we can calculate the REW distribution at higher redshifts using equation (11). Fig. 13 shows the expected number of LAEs above a given REW along with data points from a number of observations. Pentericci et al. (2011) claim that they need a change in neutral fraction of $\Delta x_{\text{Ly} \alpha} \sim 0.6$ between $z = 6$ and 7 to explain the drop in $x_{\text{Ly} \alpha}$, and Fig. 13 seems consistent in requiring such an extremely fast ionization of the IGM. Even
at \( (x)_m \) as low as 0.3, the IGM absorption is just barely enough to be consistent with the observations. However, just as the LFs, interpretation of the REW distribution is strongly dependent on the (possible) intrinsic galaxy evolution.

Another reason that we require that such a low ionized fraction is our GmG line model. The fact that the Ly\( \alpha \) photons mainly escape their host galaxies away from the line centre means that changes in the IGM damping wings have a smaller effect on \( T_\alpha \) than for a line profile with emission at the line centre, as previously discussed. For reference, we show the REW cumulative distribution function (CDF) for the simple Gaussian model in Fig. 14. While not radically different from Fig. 13, the Gaussian model does give a greater change in the CDF when adjusting the ionized fraction of the IGM.

**3.4 Correlation functions**

The clustering of LAEs has been proposed as a potential probe of the ionization state of the IGM (McQuinn et al. 2007). The reasoning is that on top of the intrinsic clustering of galaxies, the presence of large neutral patches of hydrogen which absorb the Ly\( \alpha \) emission in some areas will cause the LAEs to appear more clustered.

This is illustrated in Fig. 15, which shows the positions of the most luminous halos with and without the IGM RT applied. Since the ionized bubbles will be located around clusters of galaxies, the IGM acts as a kind of filter, obscuring haloes in non-biased regions and showing only the most densely clustered regions. Thus, by comparing the clustering from a sample of LAEs to a sample of galaxies selected by some other method that is not sensitive to the IGM, it should be possible to say something about the ionized state of the IGM. This method has the advantage of not requiring any assumptions regarding the intrinsic evolution of LAEs, only that any such evolution is independent of environment.

The quantitative effects of the IGM on the correlation function was studied by McQuinn et al. (2007), who found that the effect should be large enough to be measurable in future large LAE surveys, using a simple Gaussian line model. Iliev et al. (2008a), however, concluded that the difference between the IGM and non-IGM case is very small and difficult to detect. In the preparation of this paper, we discovered that due to a data handling error the correlation functions shown in figs 27 and 28 of Iliev et al. (2008a) incorrectly showed a much smaller difference than was actually the case. When plotting the correct data we find that the results in Iliev et al. (2008a) were qualitatively consistent with those of McQuinn et al. (2007) and those shown in this paper.

![Figure 14](https://example.com/figure14.png)

**Figure 14.** Same as Fig. 13, but using the simple Gaussian model.

![Figure 15](https://example.com/figure15.png)

**Figure 15.** Projected positions for the 200 brightest haloes in our sample without (left) and with (right) IGM effects included. At a global ionization fraction of \( (x)_m = 0.7 \), there is barely any noticeable increase in clustering. For \( (x)_m = 0.3 \), however, the extra clustering starts to become visible.

Kashikawa et al. (2006) calculate the two-point angular correlation function of 58 LAEs observed at \( z = 6.5 \) in the Subaru Deep Field, but find no evidence of even intrinsic galaxy clustering, although they note that the small sample size and the relatively small surveyed area introduce large uncertainties. Also McQuinn et al. (2007) study the same sample and find it to be consistent with a fully ionized IGM. Ou10 measure the correlation function of 207 LAEs at \( z = 6.5 \), but while they do detect a clustering in their sample, the signal is not strong enough to be attributed to the IGM.

In this section we investigate the potential of future observations to constrain the ionized fraction of the IGM using clustering measurements. We use the spatial 2PCF \( \xi(r) \), which is the excess probability of finding two galaxies in two volume elements \( dv_1 \) and \( dv_2 \) separated by a distance \( r \):

\[
dP = n^2[1 + \xi(r)]\,dV_1dV_2,
\]

where \( n \) is the number density of galaxies. We calculate \( \xi(r) \) using the method described in Martel (1991). The projected version of \( \xi(r) \) – the two-point angular correlation function, usually denoted \( w(\theta) \) – is defined as

\[
dP = n^2[1 + w(\theta)]\,d\Omega_1d\Omega_2,
\]

where \( d\Omega_1 \) and \( d\Omega_2 \) are two solid angle elements separated by an angle \( \theta \) on the sky. This function can be calculated from \( \xi(r) \) using the Limber relation (Limber 1953), or directly using, for instance, the Landy–Szalay estimator (Landy & Szalay 1993), which is the approach we use here. The 3D 2PCF obviously contains more information than the 2D version, but it requires knowledge of the line-of-sight positions of the galaxies, which at these redshifts can only be obtained from spectroscopy.

Let us assume that a future hypothetical survey observed \( N \) LAEs in a region the same size as our simulation box. Would it be possible to say something about the ionized state of the IGM from the correlation function of the galaxies alone? In other words, is the correlation function in our model with the IGM included significantly different from the same model without the IGM taken into account?

It might appear most intuitive at first to simply compare two samples (with and without IGM) with the same detection limit.
This does indeed give a significantly higher correlation for the IGM case, but the difference in correlation comes only partly from the patchiness of the IGM, but mostly from the fact that the non-IGM sample will be much larger and include also some lower mass haloes, which are less intrinsically clustered (illustrated in Fig. 16).

In this study, we do not focus on the detection limits of our hypothetical surveys. Instead, we take the same approach as Iliev et al. (2008a), and simply assume that we observe a given number $N$ LAEs in each field. We then compare the 2PCF of this sample to that of a sample of equal size, but without the effects of the IGM taken into account (such a sample could be obtained by observing in a wavelength range that is not affected by the IGM). This way, we isolate the extra clustering that is due to the topology of the IGM, and not related to the decreased number density of sources.

### 3.4.1 Simulation results

Fig. 17 shows the 3D 2PCFs calculated from the 500 intrinsically brightest LAEs (averaged over all 50 sightlines per source) in our full simulation box compared to the 500 brightest with IGM effects included, assuming the GmG line model and the log-normal luminosity relation, equation (10). The solid line shows the mean correlation function over 50 sightlines and the error bars show the $1\sigma$ spread among sightlines.

In Fig. 18 we estimate the size of the LAE sample that would be needed to tell a partly neutral IGM apart from a completely ionized one for some different global ionized fractions. This is done by calculating the correlation functions for a number of samples of different sizes and for each sample fitting a power law of the form:

$$\xi(r) = \left(\frac{r}{r_0}\right)^{-\gamma}.$$  

(16)

For every ionized fraction and sample size, we estimate the uncertainty $\sigma$ in the correlation length $r_0$ for the IGM case using the bootstrap method (Efron 1979). In Fig. 18 we show the difference between $r_0$ with and without IGM in terms of $\sigma$. As was hinted at already in Fig. 17, the correlation method becomes much more effective at lower ionized fractions. For example, at $\langle x \rangle_m = 0.2$, already a sample size of 150–200 LAEs would be enough for a 2$\sigma$ detection of IGM-boosted galaxy clustering. However, at $\langle x \rangle_m = 0.7$ a sample size of up to 500–600 would be needed.

Fig. 18 appears a bit more pessimistic than, for instance, McQuinn et al. (2007), who concluded that a sample size of 250 would be enough to distinguish $\langle x \rangle_m = 0.7$ from $\langle x \rangle_m = 1$. There are two reasons for this. The first is our assumed intrinsic line model. With the Gaussian intrinsic line, used by McQuinn et al. (2007), the IGM transmission becomes more dependent on the size of the surrounding H II bubble, as we saw in Section 3.1.1, which is exactly the effect that causes the correlation to become stronger in a neutral IGM. With the more realistic, double-peaked, line the IGM absorption is more similar across different haloes, especially at higher $\langle x \rangle_m$ (see Fig. 5), and the extra clustering is weaker. The second reason is the fact that we have included some random scatter in the mass-to-light relation, which further reduces the clustering signal.

As we saw in Fig. 12, to get a sample of several hundreds of LAEs at $\langle x \rangle_m = 0.4$ from the deep box, one would need to detect objects down to a detection limit of at least $10^{42}$ erg s$^{-1}$. While obtaining spectra for hundreds of targets is unrealistic with today’s ground-based observatories, it may well be possible for a telescope such as the JWST. Using the NIRSpec spectrograph on the JWST, an exposure time of $\sim 30$ h would be enough to obtain Ly$\alpha$ spectra (and thus 3D positions) with reasonable signal-to-noise ratio (S/N) for sources down to $10^{42}$ erg s$^{-1}$ (E. Zackrisson, private...
emitters = 0.62 \langle z = 0.8 \rangle, the largest samples will have an artificial lower bubble. 0.4 at \sim z = 6.5 and 7, but this hinges on the assumption that \langle z \rangle \approx 0.5 at LF at \sim z = 6.5. Even with a sample size of 500, we need about 70 per cent neutral fraction to reliably distinguish the IGM case from the non-IGM case.

This is quantified further in Fig. 20, which shows the same thing as Fig. 18, but for the 2D 2PCF. As expected, a bit of information is lost when throwing away one of the coordinates. Nevertheless, if the IGM is only 40 per cent ionized at \sim z = 6.5 and 7, a sample of 300 LAEs might very well be enough to detect the IGM clustering at this redshift. Fig. 12 suggests that a detection limit of 10^{42} \text{erg s}^{-1} would be sufficient, which is only a factor of 2.5 lower than the detection limit of Ou10 at \sim z = 6.5. In fact, the rightmost parts of Figs 18 and 20 may be somewhat conservative. Since we only consider haloes down to 10^{10} \odot, the largest samples will have an artificial lower mass cut-off which makes the IGM and non-IGM samples more similar than if even lower mass haloes had been included. Thus, the difference in correlation functions could actually be slightly larger than shown here.

4 SUMMARY AND DISCUSSION

4.1 Summary

We have presented results from simulations of LAEs during the EoR and compared these to observations in order to investigate to what extent we may learn something about the global ionized fraction of the IGM at different redshifts. To simulate the observed properties of LAEs, we devised a model that splits the RT of Ly\alpha photons into two regimes: one (circum)galactic and one extragalactic part. For the (circum)galactic part, we approximate the emerging line shape as a double-peaked GmG, while for the extragalactic part we carry out RT through our cosmological IGM box. We take the Ly\alpha luminosity to be proportional to halo mass, with a log-normal random scatter, and we fit the mass-to-light ratio to the Ly\alpha LF at \sim z = 6, measured by Ou10.

We have shown that a double-peaked model such as our GmG produces some significant differences in results compared to assuming a single Gaussian, as was done in e.g. Iliev et al. (2008a), McQuinn et al. (2007) and Dijkstra et al. (2007). In general, our double-peaked model makes the transmitted fraction of Ly\alpha, T_\alpha, less sensitive to damping wing strength. This is because in this model, most of the emission is offset from the line centre as it enters the IGM, and (T_\alpha) will be closer to 50 per cent, with less dependence on the size of the surrounding H\alpha bubble.

Comparing to observed LAE LFs at \sim z = 6.5 by Ou10 and Ka11, and assuming that the evolution in the LAE LF is due only to the ionization of the IGM, we have seen that our simulations best match the observations for an IGM-ionized fraction of \langle x \rangle_m \sim 0.5 at \sim z = 6.5. This is lower than the value of \langle x \rangle \geq 0.8 \pm 0.2, claimed by Ou10 (who modelled part of the change in LF as due to intrinsic LAE evolution) but roughly consistent with the value of \langle x \rangle \sim 0.62 given by Ka11. We note that both the LFs given in Ka11 and that in Ou10 give us the same value for \langle x \rangle_m, despite the fact that these samples are from two fields that are well separated from each other, suggesting that the change is truly global and not due to sample variance.

Furthermore, we compared our simulations to observed equivalent width distributions, and again found that a very neutral IGM is required if the changes between \sim z = 6 and 7 are to be explained by IGM evolution only. Finally, we have given predictions for the sample sizes needed to measure the increase in LAE clustering due to a partly neutral IGM. The 2PCF does not require as strong assumptions about the intrinsic evolution of LAEs, and could thus serve as a valuable independent probe of the ionized state of the IGM.

4.2 How reliable are constraints from LFs and REW distributions?

Our comparisons to observed LAE LFs and equivalent width distributions seem to be in rough agreement with other studies such as Ka11 and Pentericci et al. (2011) in requiring a very high neutral fraction at \sim z = 6.5 and 7, but this hinges on the assumption that the evolution in these observables is due to the IGM only and that intrinsic galaxy evolution is negligible. If we set aside the many caveats for a moment and take the values of \langle x \rangle_m = 0.5 at \sim z = 6.5 and \langle x \rangle_m = 0.4 at \sim z = 7 at face value, this would mean a somewhat later reionization than the scenario we used to produce our IGM
boxes (Fig. 2). In the reionization scenario used in our simulations, the IGM is ionized only by galaxies, with small sources turned off as their environment becomes sufficiently ionized. By adjusting the assumptions regarding star formation and escape fraction of ionizing photons, it is possible to obtain scenarios in which reionization finished later (Iliev et al. 2012).

In the scenario used to produce our IGM boxes, the IGM goes from \(\langle x \rangle_m \sim 0.4\) to \(\langle x \rangle_m \sim 1\) between \(z = 7.7\) and 6.5. This corresponds to a time interval of approximately 170 Myr, which is almost exactly the same as the time interval between \(z = 7\) and 6 – the redshift range for which the \(\langle x \rangle_m = 0.4\) to \(\langle x \rangle_m \sim 1\) transition implied by our comparisons to observations. So while the particular reionization scenario used here does not perfectly match the observations in terms of when reionization took place, it seems that the implied rapid change in ionized fraction is not unreasonable. It may also be objected that a late reionization will result in an electron optical depth too low to match the observations by WMAP (Komatsu et al. 2009). However, a fair comparison would require a knowledge of the earlier stages of reionization as well. If, for instance, reionization starts early with small sources there may be time to build up a sufficient electron density before galaxies start rapidly reionizing the IGM at lower redshifts (Ahn et al. 2010).

A more serious problem is that these high neutral fractions are incompatible with other observational results. For instance, Raskutti et al. (2012) study the IGM temperature in quasar near-zones and find that reionization must have been completed by \(z > 6.5\) at high confidence, and Hu et al. (2010), Ka11 and Ou10 study the Ly\(\alpha\) line shapes of LAEs at \(z = 6.5\) and find no evidence of damping wings.

One way to resolve this conflict would be to drop the no-intrinsic-evolution assumption, and allow part of the change in the IAE LFs between \(z = 6\) and 6.5 to be explained by intrinsic galaxy evolutions, as argued by, for instance, Dayal et al. (2008) and Ou10. As we noted in Section 3.2.2, we can reproduce the drop in LF by galaxy mass evolution only, although we then run into problems at lower redshifts.

A second solution was recently suggested by Bolton & Haehnelt (2012) who showed that dense small-scale H\(\text{I}\) structures, below the resolution of our study, may play an important role in limiting the observability of LAEs even when the global neutral fraction is low. However, their results assume a constant UVB and it is not yet clear how this translates to the more realistic case of a fluctuating ionizing rate which is higher in the denser regions close to sources.

In conclusion, it would seem that any constraints on the global IGM-ionized fraction obtained from LFs or REW distributions will remain uncertain at best until more is known about the intrinsic evolution of LAEs at \(z > 6\) and the role and prevalence of small-scale \(\text{H}\)\(\text{I}\) structures. The degeneracy between intrinsic evolution and IGM ionization could possibly be broken with better observations of the UV LF evolution of LAEs (Ou10), or by 21-cm experiments such as LOFAR and SKA.

In addition to the uncertainties related to intrinsic LAE evolution, we have shown in this paper that simplifying assumptions regarding Ly\(\alpha\) line shapes can have significant effects on the results of simulations. Line shapes with most of the emission to the sides of the line centre require more neutral hydrogen to obtain a given drop in transmitted fraction. As an example, if we redo our LF calculations shown in Fig. 10 using the Gaussian line profile, we get a best fit to the observations for \(\langle x \rangle_m \sim 0.7\) as compared to 0.5 with the GmG model. While few spectroscopic observations of sufficient resolution exist at high redshift, lower redshift observations (e.g. Tapken et al. 2007; Verhamme et al. 2008; Yamada et al. 2012) show that most lines are either double peaked or with a single peak that is offset from the line centre. For our purposes, these offset single-peaked lines are equivalent to the double-peaked ones – the important distinction is between the Gaussian lines with the emission centred at the line centre and those where it is offset from the line centre. While we believe our GmG model to be more realistic that a single Gaussian, lower \(z\) observations do show that most LAEs have some emission at the line centre (e.g. Tapken et al. 2007), even when a large part of the emission is shifted away from the centre. If this is true also at higher \(z\), it would mean that the GmG model (which has zero emission at the line centre) tends to slightly underpredict the effect of a neutral IGM.

4.3 Future prospects

While both the LFs and equivalent width distributions suffer from degeneracies and model dependencies, the 2PCF could be used to put some of the model assumptions to the test. After correctly plotting the results from Iliev et al. (2008a), it seems that all theoretical models now agree that a significant neutral fraction should give an appreciable boost to the correlation function. While our line model and the fact that we allow some random scatter in the mass-to-light ratio make our predictions for the 2PCF method as a means for constraining the IGM-ionized fraction somewhat more pessimistic than McQuinn et al. (2007), it still seems that the method could be useful once observed LAE samples grow by a factor of 2 or 3. Our analysis here has been focused only on the amplification of the clustering induced by the patchiness of the reionization process. Other effects such as intrinsic LAE bias (Orsi et al. 2008) and environment-dependent selection effects (Zheng et al. 2011) may cause LAEs to become more clustered than dropout-selected galaxies, but it is hard to imagine that these effects would change rapidly with redshift.

As we show in Fig. 20, if only 2D positions are available, a sample size of many hundreds of LAEs is required for any meaningful constraints on \(\langle x \rangle_m\). It is thus not very surprising that Ou10 do not measure any IGM-induced boost in clustering with their sample of 207 galaxies. Using our model, their non-detection gives only a weak lower limit of \(\langle x \rangle_m \gtrsim 0.4\). With future, larger, samples it may be possible to put more meaningful constraints on \(\langle x \rangle_m\) using LAE clustering. With a sample of \(\sim 700\) LAEs, we would expect a \(2\sigma\) detection of IGM-amplified clustering if the IGM is \(\gtrsim 50\) per cent neutral, which could be used to test the predictions from LFs and equivalent width distributions assuming no intrinsic galaxy evolution. With 1000 LAEs, even a neutral fraction of 30 per cent should give a strong clustering signal. With the new Hyper Suprime-Cam at the Subaru telescope, it is expected that future surveys will detect up to 10 000 LAEs at \(z = 6.5\) over a 30 deg\(^2\) area on the sky (M. Ouchi, private communication). A detailed theoretical investigation of such a survey would require much larger scale simulations than the ones presented here, but simple extrapolation of Fig. 20 would suggest that 10 000 detected LAEs can put strong constraints on the global ionized fraction.

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