A chemically fueled non-enzymatic bistable network

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One of the grand challenges in contemporary systems chemistry research is to mimic life-like functions using simple synthetic molecular networks. This is particularly true for systems that are out of chemical equilibrium and show complex dynamic behaviour, such as multi-stability, oscillations and chaos. We report here on thiodepsipeptide-based non-enzymatic networks propelled by reversible replication processes out of equilibrium, displaying bistability. Accordingly, we present quantitative analyses of the bistable behaviour, featuring a phase transition from the simple equilibration processes taking place in reversible dynamic chemistry into the bistable region. This behaviour is observed only when the system is continuously fueled by a reducing agent that keeps it far from equilibrium, and only when operating within a specifically defined parameter space. We propose that the development of biomimetic bistable systems will pave the way towards the study of more elaborate functions, such as information transfer and signalling.
Biotic systems, such as yeasts and bacteria, have long been used for manufacturing chemicals and materials. The macromolecular networks that control these miniaturised ‘factories’ can also be programmed—via the exploitation of synthetic biology tools—to perform complex functions foreign to the cell cycle, yielding, for example, oscillatory or chaotic behaviour. Remarkable developments in Systems Chemistry over the past decade offer alternative strategies for the bottom-up design of entirely synthetic molecular networks with life-like functions. While a systems chemistry approach may sometimes appear to be challenging with respect to design and synthesis, it often facilitates better control over a desired function and subtle manipulations, together with widening the range of experimental conditions. Significantly, recent progress in the systems chemistry research towards life-like behaviours has been achieved via the development of schemes for operating out of equilibrium, which have so far provided access to transient structures that form as a result of constant energy dissipation.

We now propose that the study of chemical networks out of equilibrium would further allow control over dynamical network-dependent functions. We thus report here thiodepsipeptide-based non-enzymatic networks propelled by reversible replication processes out of equilibrium, presenting bistable behaviour. Bistability is achieved due to a disparity between forward and backward processes and is accessible only as long as energy is supplied by a reducing agent. Using theory, simulation and experiments, we characterise the bistable behaviour of the networks under a wide range of conditions and establish the limits and requirements for phase transitions from ‘ordinary’ behaviour—leading to a single steady state—to bistable functionality. We envision that the development of biomimetic bistable systems will pave the way to the study of more elaborate functions in synthetic networks, such as information transfer and signalling.

Bistability is often manifested by cellular networks, in which bistable motifs yield long-term memory, converting transient signals or stimuli into sustained responses that control different processes, including cell division, apoptosis and differentiation. Sustained bistable responses can also form in self-organised chemical systems residing out of equilibrium, when two long-lived states, designated steady states (SSs), are alternately populated depending on the network rewiring in response to variations in a control parameter (Fig. 1). Despite recent progress in studying bistable (and multi-stable) systems by using small molecules, gel material, and synthetic biology, the de novo bottom-up design of such systems remains challenging, primarily because the kinetic characteristics and energy aspects yielding bistability have not been globally defined. After several research groups, including our own, have shown that synthetic replication networks can be wired and manipulated to perform simple functions observed in the biological context, we describe herein an exceptional non-enzymatic network presenting bistability, driven by a reversible autocatalytic reaction of coiled-coil thiodepsipeptides. We present here a quantitative analysis of the bistable behaviour, featuring a phase transition from the simple equilibrium processes taking place in reversible dynamic chemistry into the bistable behaviour observed only when the system is continuously fuelled (in this case by a reducing agent) to keep it far from equilibrium (see mechanism in Figs. 1b and 2) and when it operates under a specifically defined parameter space.

Results

Design principles of the bistable system. The second-order autocatalysis operating in this reaction constitutes the positive feedback that leads to the non-linear growth of a full-length thioester replicator (R), reversibly synthesised from its precursors, a thioester electrophile (E) and a thiol-containing nucleophile (N; Fig. 1b–d). The bistable behaviour is manifested in two distinct SSs of the obtained product distribution, either high or low, depending on the initial relative concentrations of R, E, and N (Fig. 1d). Mechanistically, we explain the bistable behaviour by the disparity between the fast interconversion of (unfolded) R to E and N molecules in a template-free reaction, versus the slow interconversion in a template-assisted reaction in which R is assembled into a well-folded trimeric coiled-coil nanostructure, which can react only slowly with incoming thiols (Fig. 1b). The observed SSs are described quantitatively using an apparent constant (analogous to the equilibrium constant Kapp) designated as [R] [S]/[E] [N], where S is a small molecule thiol released during the ligation process. In addition, the (average) measured differences between the two SSs are characterised using the term ΔKapp, which signifies the extent of the bistability (ΔKapp = Kapp - Kapplow). This bistable dynamic space. We note that these values can also be useful for future design of functional systems with meaningful signalling.

Energy-dissipating nature of the bistable network. Bistable behaviour is a functional product of the network and not a simple reflection of conformational changes of the replicator R along the reaction coordinate. Therefore, the network reaches either one of the two resting states upon rewiring, depending on the initial concentrations of its components and the environmental conditions applied. At the outset of this study, we realised that a continuously fuelled reducing environment (Fig. 2) is crucial for preventing the bistable system from falling into less defined states, arguably multiple kinetic traps. The ‘engine’ driving the fuelled network is a redox cycle maintained by excess tris(2-carboxyethyl)phosphine hydrochloride (TCEP), which reduces all the unreactive disulphide species into active thiols (N or S) that, in turn, drive several reversible reactions within the autocatalytic network (Fig. 2). To directly study this behaviour, we conducted a set of comparative experiments that revealed the network kinetics and steady-state positions under reduced and oxidised conditions. In the presence of TCEP as the reducing agent, the network reached one of two clearly distinct SSs (+Fuel, Fig. 3a), whereas in the absence of TCEP (−Fuel, Fig. 3b) the same network did not show bistability, but rather the reaction came to an end at multiple resting states, each apparently in linear correlation with the initial set of concentrations.

Further analysis revealed the typical characteristics associated with networks that are kept far from equilibrium by continuous energy consumption. The early-time regimes in Fig. 3c–e (and Supplementary Figs. 5–7) show replication reactions that were initiated under aerobic conditions without TCEP and reached resting states after ~24 h. Disulphide species (N–N and N–S) were formed during this period (Fig. 3c and Supplementary Fig. 5), abolishing their capability to function as nucleophiles (Supplementary Fig. 8). Remarkably, refreshing each of these ‘non-interested’ resting states with TCEP (after 60–96 h) with the consequent reduction of the disulphides to thiols (see Supplementary Fig. 5) reactivated the replication process, yielding an appreciable quantity of replicator R and reaching the expected low (Fig. 3d) and high (Fig. 3e) SS concentrations.

The transient profile of the system’s SSs—a crucial characteristic of the energy-dissipation dependent behaviour—was also clearly established via the following set of control experiments. (i) Network reactions were seeded with TCEP only one time at the initiation (Supplementary Fig. 9). The data shows that after >24 h these reactions reached flat regions in products...
distribution (supposedly close to the SSs), while later on they reacted to reach other long-lived states. Based on the above discussed data (Fig. 3b), we conclude that after TCEP was exhausted, the network reactions stopped at kinetic traps. (ii) A network reaction was twice seeded with TCEP over the first 24 h (Supplementary Fig. 10), and consequently also reached a resting state close to the SS. At this point, the reaction was followed for a longer time (up to 120 h) without re-fuelling by TCEP, resulting in its halt in a different state, arguably a kinetic trap. Remarkably, re-fuelling with TCEP at 120 h again facilitated reaching the SS position (Supplementary Fig. 10b). (iii) A network reaction was repeatedly seeded with small amounts of TCEP (2 mM; Supplementary Fig. 11). Due to incomplete thiol reduction at each stage, the reaction stopped at different kinetic traps, each
time closer to the expected SS. The result of the final (3rd) TCEP seeding step indeed allowed the system to reach a long-lived state very close to the expected SS, as calculated from the respective 'regular' experiment with continuous TCEP seeding (Supplementary Table 2, Entry #3).

Assessment of the bistability parameter space via theory and simulations. A multi-dimensional energy space dictates the network behaviour far from equilibrium. Similar to previously studied dynamical systems, we found that the non-linear function characterised here, i.e., bistability, became effective only in sections of this space satisfied by a certain set of parameters (Fig. 4). Within this confined space, bistability is established by non-zero separation between the SSs ($\Delta K_{\text{app}} > 0$), while at the regime edges a sharp phase transition leads to 'ordinary' behaviour, in which the system reaches only one SS (Fig. 4). Using the reaction network shown in Fig. 2, we constructed a minimal network reaction model that contains the complete set of respective equations and includes both positive and negative feedback loops (see Section 2, Supplementary Methods). We employed several approaches towards investigating this model. In the first, we deconstructed...
the model into its two minimal feedback loops and showed mathematically how this leads to either one single SS or three physical SSs (Section 2.1, Supplementary Methods). In the latter case, one of the SSs is unstable, while the other two account for the bistable SSs. A second approach was to run our numerical network simulation, in which we used mass-action kinetics, for specific environmental conditions and specific initial concentrations with the aim to follow the time dependence of the various concentrations. This method has previously been applied by us to observe specific cases leading to bistability. The third approach was to analytically solve for the SSs by mathematically locating the concentrations at which the net process rates were zero. While the first approach gave us a mathematical overview of bistability, and the second approach allowed us to pinpoint...
individual cases and observe how they lead to bistability, the third approach enabled us to map all the SSs over the entire parameter space and to locate the boundaries of the bistable regime. We therefore followed this approach and computed the rate of each process in Supplementary Equations 2.1–2.8 using mass-action kinetics. We thereby found the global (quadratic) expression for the production of \( R \) (Eq. 1; for definitions of \( g \), \( c \), and \( T \), see Supplementary Methods section 2.2). The SS was reached when the rate of this reaction was equal to zero.

\[
\frac{d[R]}{dt} = g[E][N] - g(T)[S] + c[E][N][T]^2
\]  

Figure 4a–d show a selection of computed steady-state \( K_{app} \) values for the replication network obtained by each time altering one of the critical control parameters, namely, total peptide concentration, thiol concentration, temperature, or denaturant level. Remarkably, triggering the system by changing any one of these factors gave a typical bifurcation diagram, consisting of a middle bistable zone with low (blue) and high (red) SSs, and clear bifurcation points for the phase transitions to regimes of single-low and single-high SSs.

To quantitatively describe the multifaceted space of control parameters affording bistability (Fig. 4e), we constructed a combined two-dimensional bar graph for \( \Delta K_{app} \), as a function of changes in each one of the individual parameters (Fig. 4f). To simplify the data presentation, we selected a multi-colour bar pertaining to a network containing 100 \( \mu \)M total peptide and 10 \( \mu \)M thiol concentrations and operating under ambient conditions (\( T = 22^\circ \text{C} \), and denaturant level = 0). The network response to changes in the environment is thus shown with respect to this reference. In addition, we prepared multi-dimensional contour maps of \( \Delta K_{app} \) as a function of several parameters together (Fig. 4g–j). Each contour map displays our numerical results over a three-dimensional parameter space and contains a bistable region. To demonstrate our ability to precisely trace bistability within these parameter space maps, the \( \Delta K_{app} \) heights in the bistable zones (Fig. 4g–j) are emphasised by using colours (scaled from blue to red), while the \( K_{app} \) values in the single-SS zones are given in grey scale.

The above extensive data set allows us to precisely detect the operational bistable zone and furthermore to draw important conclusions regarding the effect of different parameters and their combinations on the bistability phenomenon. First, we showed that bistability forms under a wide range of parameter combinations. Then, as could be expected (vide infra), we found an increase in the nominal \( \Delta K_{app} \) values for increasing total amounts of peptides in the system. In addition, the vital need for a threshold concentration of thiols as a fuel to drive bistability was evident in all the studied cases, supporting our above-described observation that the system requires a continuous supply of energy. Furthermore, the decrease in \( \Delta K_{app} \) values observed upon raising the temperature or increasing the denaturant concentration demonstrates the need for maintaining the structural integrity of the replicator \( R \) coiled coils, thus facilitating the replication process as a positive feedback that produces the disparity in forward and backward rates leading to bistability. Remarkably, by following the trends in the series of contour maps, e.g., in Fig. 4g–h, we found that changes in several parameters together either compensated for one another, thereby retaining the system’s bistable behaviour, or cancelled one another out, leading to the rapid abolition of bistability.

Experimental characterisation of the bistability parameter space. Using the above quantitative theoretical and simulation analysis as a guide, we then sought to uncover the experimentally operative parameter space. In particular, we probed the effects of changing the system’s inherent parameters, such as total peptide concentration and the type of replicator employed, or manipulating the environmental conditions through changes in temperature or thiol or denaturant (GnHCl) concentrations (Fig. 5 and Supplementary Figs. 16–33). This part of the study again started from the analysis of bistability in a (TCPF fuelled) far-from-equilibrium network under a reasonable ‘native’ set of conditions (Fig. 5a and multi-colour bar in Fig. 5g). Bistability was clearly observed, displaying a switch point from the low state to the high state at about 90 \( \mu \)M (i.e., 90%) of the replicator \( R \). Additional experiments (Fig. 5b–f) revealed several characteristic features of the bistable network, in agreement with the simulated data. Increased separation between the low and high SSs, as reflected in an increase in \( \Delta K_{app} \) values, was observed upon an increase in the total peptide concentration (Fig. 5b). A decrease in the \( \Delta K_{app} \) values was observed upon heating the mixture to 30 °C (Fig. 5c) or after adding 0.5 M of GnHCl, the denaturation agent (Fig. 5e). Subsequently, bistability was significantly decreased by employing a full-length mutant thiodesipeptide that cannot replicate (\( R_g \); sequence given in SI)\(^{35}\) or by further heating the mixture to 35 °C, yielding a single low SS (Fig. 5d). Furthermore, remarkably, stabilising the coiled-coil assemblies through the addition of a kosmotropic salt ([Na\(_2\)SO\(_4\)] = 0.5 M) led to a single high SS (Fig. 5f). We note that in some cases (e.g., in Fig. 5a, b) a 3rd ‘intermediate’ cluster of SS \( K_{app} \) values is observed for a narrow range of concentrations residing in both the low and high SSs. In this region, the system is very sensitive to small perturbations in the starting material concentrations and is (evidently) usually slow in reaching the steady state. This behaviour, reflecting a shallower transition between the low and high SSs, has been previously observed in the hysteresis of related experimental bistable systems\(^{22,37}\).

A two-dimensional bar graph shows the \( \Delta K_{app} \) values as a function of changes in each of the studied parameters (Fig. 5g), all with high similarity to the simulated network (Fig. 4f). Note that this similarity was applied for a somewhat narrower parameter space than the space we analysed by the simulation, due to obvious physical constraints, such as water freezing at 0 °C, the limited solubility of the peptide and small molecule components.
of the network, etc. Nevertheless, in addition to finding the $\Delta K_{\text{app}}$ for the network under each of the studied conditions, we were able to experimentally detect the hysteresis (Supplementary Figs. 34, 35), and non-linear phase transition from bistability to a single SS when reaching the temperature limit (Fig. 5h) or the limiting GnHCl concentration (Fig. 5i).

Using the data from the entire set of experiments (Supplementary Table 2), we also addressed the challenging goal of reconstructing the entire operative bifurcation diagram—a goal that, to the best of our knowledge, has not been accomplished before. Towards this aim, we followed the network dynamical behaviour in response to changes in various parameters that directly affect the self-assembly process, namely, the amount of denaturant added, the inherent stability of the coiled-coil assembly, and the enhanced assembly effected by adding the kosmotropic salt (see CD data and helix content calculation in Supplementary Fig. 36). Figure 6 follows such a trajectory, displaying a single low SS at unfolding conditions, passing through the middle bistable zone when folding affords efficient replication, and finally again reaching a single state when a too well-folded assembly affords only a single high-concentration SS.

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**Fig. 5** Experimentally investigated bistability parameter space. a–f $K_{\text{app}}$ values as a function of the initial concentration of $R$ for the network studied under various selected conditions, where the reaction initiated with a total peptide concentration $[\text{pep}]$ of 100 $\mu$M and 500 $\mu$M of a small molecule thiol, at room temperature (22 °C), but without a denaturant ($\text{GnHCl} = 0 \text{ M}$) was considered ‘native’ (a); the conditions were changed as follows: increased [pep], i.e., $[R + E] = 200 \mu$M (b); elevated temperature, $T = 30 ^\circ \text{C}$ (c); high temperature, $T = 35 ^\circ \text{C}$ (d); addition of denaturant, $[\text{GnHCl}] = 0.5 \text{ M}$ (e); addition of a kosmotropic salt, $[\text{Na}_2\text{SO}_4] = 0.5 \text{ M}$ (f). g Bar graph presenting $\Delta K_{\text{app}}$ as a function of perturbations in the different parameters. The numbers above the bars indicate the experimental conditions specified in Supplementary Table 2. h and i Quantitative description of $\Delta K_{\text{app}}$ as a function of changes in temperature or GnHCl concentrations. The results show a sharp transition from bistability ($\Delta K_{\text{app}} >0$; coloured data points) to ‘ordinary’ single state (grey points) behaviour. Note that the temperature-dependent and GnHCl-dependent $K_{\text{app}}$ results are also shown in the supplementary Figs. 34, 35, allowing the detection of hysteresis associated with changing each one of these parameters. All SS concentration results are given in the Supplementary Tables 1 and 2.
Fig. 6 Experimentally derived bifurcation diagram. $K_{\text{app}}$ values as a function of the thiodepsipeptide coiled-coil propensity coordinate influenced by the type of peptide employed and the added amounts of GnHCl as a denaturant, or of Na$_2$SO$_4$ as a kosmotropic salt that promotes folding (see Supplementary Fig. 36). Numbers above the data points indicate the experimental conditions specified in Supplementary Table 2; the expanded presentation for data points 11–13 emphasises bistability with small separation between the high and low SSSs.

Discussion

The bistable behaviour demonstrated in this paper expands the repertoire of functions that can be driven by non-enzymatic self-replication, revealing again the potential role of replication for developing smart materials for use in synthetic cells. While assembly of the coiled-coil nanostructure was found to be crucial for driving the replication process, the overall bistability function depended on the delicate interaction between the multiple components of the network. Our combination of theory, simulation and experiment pinpoints the parameters that lead to bistability, including the vital necessity to operate out of chemical equilibrium. Such an analytical approach makes the concept of bistability feasible for previously unreachable reactions, as it can unravel the design rules governing other dynamical synthetic systems, for which information on system kinetics and feedback components is already available. We further propose that quantitative control over bistability, as reflected in our system by $\Delta K_{\text{app}}$, would provide tools to design switchable materials and to devise signal transduction schemes.

Data availability

The data that support the findings of this study are available from the corresponding author upon request.

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Author contributions
I.M., R.M. and D.D. conceived, designed, and performed the experiments. N.W. and E.P.-L. performed the theoretical and dynamic simulation analysis. G.A. supervised the overall project. I.M., N.W., R.C.-L. and G.A. co-wrote the paper. All the authors discussed the results and commented on the paper.

Competing interests
The authors declare no competing interests.

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