This paper introduces an improved reranking method for the Bag-of-Words (BoW) based image search. Built on [1], a directed image graph robust to outlier distraction is proposed. In our approach, the relevance among images is encoded in the image graph, based on which the initial rank list is refined. Moreover, we show that the rank-level feature fusion can be adopted in this reranking method as well. Taking advantage of the complementary nature of various features, the reranking performance is further enhanced. Particularly, we exploit the reranking method combining the BoW and color information. Experiments on two benchmark datasets demonstrate that our method yields significant improvements and the reranking results are competitive to the state-of-the-art methods.

1. INTRODUCTION

This paper considers the task of the Bag-of-Words (BoW) based image search, especially on the visual reranking. In BoW model, visual words are generated using unsupervised clustering algorithms [2, 3] on local features such as SIFT descriptor [4, 5]. Then an image is represented as a histogram of visual words. Basically, each visual word is weighted using the \textit{tf-idf} scheme [6, 7], and the fast search is achieved through an inverted file.

Nevertheless, traditional BoW model is not satisfying due to many reasons, e.g., the lack of spatial information [8, 9, 10, 11], the information loss due to feature quantization [12, 9, 13], etc. Furthermore, BoW model is limited when facing the challenges of occlusions, or viewpoint and illumination changes.

Besides, the BoW based image search aims to find the query’s nearest neighbors in SIFT space. However, SIFT only describes the local texture feature, and the image search system built on a single feature suffers from low recall, \textit{i.e.}, images similar in other feature spaces are not considered, such as color [14, 15] and semantics [16, 17]. For example, although images containing the same object are distant in SIFT space due to the change of viewpoint, they may be adjacent in color space (see Fig. 1 for an illustration).

In this paper, we tackle these problems using a graph-based method. We construct a directed image graph connecting each image with its potential relevant images. In this way, true matched images, \textit{e.g.}, images containing the same object but with different viewpoints, would be linked together. Then, through the graph analysis, the initial results are reranked. What is more, feature fusion at rank-level can be adopted in the graph-based reranking as well. Complementary nature of various features further boosts the performance.

Our work relates to the recent study of visual reranking using image-level cues. To name a few, \textit{k-NN} reranking [8] refines the initial rank list automatically using the \textit{k}-nearest neighbors. Alternatively, Qin \textit{et al.} [18] take advantage of \textit{k}-reciprocal nearest neighbors to identify the image set for reranking. In addition, a lot of works conduct the reranking based on graph theory [1, 19, 20, 21], which have shown promising performance.

Due to the limitation of single feature, some works explore the reranking using complementary features in graph-based scheme. Particularly, Zhang \textit{et al.} [1] propose a fusion method for a specific query to combine the strengths of holistic and local features at rank level. Similarly, Deng \textit{et al.} [22] introduce a weakly supervised multi-graph learning framework for visual reranking.

Our work is built on [1], which achieves the state-of-the-art performance by the fusion of different features using undirected graph. However, we find [1] is sensitive to outlier dis-
Fig. 2: Difference of graph construction between original and improved methods. Image 1 and 2 are relevant and they satisfy \( R_5(1, 2) \). Although Image 2 and 3 are relevant, they do not satisfy \( R_5(2, 3) \) for obvious viewpoint change. Thus, the original image graph only contains image 1 and 2. In comparison, since image 3 is included in \( N_5(2) \), the improved image graph would also contain image 3. As a result, the improved method preserves more potential relevant images.

Fig. 3: Difference of edge weight between original and improved methods. Let decay coefficient be 1 for observation convenience. If \( k \) is 3, we can get \( w(1, 2)=1 \) and \( w(1, 3)=0 \) according to Eq. 2. However, if \( k \) is 5, we have \( w(1, 2)=2/3 \) but \( w(1, 3)=1 \). It illustrates edge weight in Eq. 2 is sensitive to \( k \). Besides, when \( k \) is inappropriate, the edge linking irrelevant images may have larger weight than relevant images. In comparison, we get \( w(1, 2)=1/4 \) no matter \( k \) is 3 or 5 according to Eq. 3. When \( k \) is 5, \( w(1, 3) \) becomes 1/8 smaller than the weight \( w(1, 2) \) of relevant images.

is determined by neighborhood consistency of the connected images, and can be written as:

\[
w(i, i') = \begin{cases} 
\alpha(|q, i, i'|) & \text{if } (i, i') \in R_k(i, i') \\
0 & \text{otherwise}
\end{cases}
\]

where \(| \cdot |\) represents the cardinality of the set and \( \alpha(q, i, i') \) is a decay coefficient. Let \( \delta(q, i) \) denote the length of shortest path between \( q \) and \( i \) in \( G \), and the decay coefficient can be defined as \( \alpha(q, i, i') = \alpha_0^{\max(\delta(q, i), \delta(q, i'))} \). Usually, the \( \alpha_0 \) is set as 0.8.

For a single graph or a fused graph combining multiple features, ranking is achieved by searching a subgraph \( G' \) with maximum weighted density.

2.2. Construction of improved image graph

It is mentioned in [23] that reciprocal neighbor relation is a reliable indicator for two images being visually similar. Therefore, Eq. 1 is a relatively strict constraint for relevant images, and could filter out many potential irrelevant images during graph construction. However, some relevant images with obvious visual difference may not satisfy Eq. 1. Consequently, the graph constructed using reciprocal neighbor relation tends to lose potential candidates.

To further preserve the possible candidates or relevant images when constructing graph, we propose a directed image graph to encode the relevance among images. In this method, there is a directed edge from image \( i \) to image \( i' \) if \( i' \) appears in the \( N_k(i) \). And the “directed” means \( i \) may point to \( i' \) when \( i' \) does not point to \( i \). As a result, more relevant cues among

2. OUR APPROACH

In this section, we first introduce the original image graph in Section 2.1. After that we illustrate our algorithms in Section 2.2, 2.3 and 2.4. We show that our method aims to select more candidates to improve recall when constructing graph. Furthermore, the discriminative edge weight and robust ranking algorithm ensure the precision.

2.1. Original image graph

Zhang et al. [1] propose an undirected image graph for merging global and local features. This method finds potential relevant images based on reciprocal neighbor relation. Let \( N_k(i) \) be the set of \( k \) nearest neighbors of image \( i \), then the reciprocal neighbor relation is defined as follows:

\[
R_k(i, i') = i \in N_k(i') \land i' \in N_k(i)
\]

The image graph can be represented as \( G=\{V, E, w\} \), where \( V \) is the set of images containing query \( q \) and \( E \) is the set of edges linking images. There is an undirected edge linking images \( i \) and \( i' \) if they satisfy Eq. 1. The edge weight \( w \)
images, e.g., the relevant images filtered out by Eq. 1 are preserved in the directed graph (see the example in Fig. 2).

Since the directed graph improves the recall, many outliers are also introduced. Therefore, it is a critical issue how to define discriminative edge weight.

Edge weight \( w \) in Eq. 2 is defined by consistency among top candidates. However, as can be observed in Fig. 3 the weight heavily depends on \( k \). Besides, when \( k \) is inappropriate, irrelevant images may have more common nearest neighbors compared to relevant ones. It leads to the fact that edge linking irrelevant images obtains larger weight than relevant images. Hence, the discriminative power of the edge weight is limited.

To alleviate the impact of parameter \( k \), we propose to define the weight using retrieval ranks. Let \( \text{Rank}(i, i') \) be the rank of image \( i' \) when using image \( i \) as the query. In consideration of the reciprocal relation, image \( i \) and its neighbor \( i' \) are close to each other if \( \text{Rank}(i, i') \) and \( \text{Rank}(i', i) \) are both high.

Therefore, the edge weight is determined by:

\[
 w(i, i') = \begin{cases} 
 \frac{\alpha(q, i,i')}{\text{Rank}(i, i') + \text{Rank}(i', i)} & \text{if } i' \in N_k(i) \\
 0 & \text{otherwise}
\end{cases} \quad \text{(3)}
\]

The edge weight defined by Eq. 3 is less dependent on \( k \), as it only considers the reciprocal ranks instead of neighborhood consistency. Thus, when \( k \) is not chosen properly, the edge weight is still discriminative compared to the original method (see Fig. 3).

2.3. Fusion

Following the basic criterion, it is easy to construct directed image graphs \( G_n = \{V_n, E_n, w_n\} \) for different retrieval results. Then we fuse multiple graphs into one graph \( G = \{V, E, w\} \) without supervision [1], which can be written as:

\[
 E = \bigcup_n E_n, V = \bigcup_n V_n \quad \text{(4)}
\]

\[
 w(i, i') = \sum_n w_n(i, i') \quad \text{(5)}
\]

The fusion of various features based on graph can bring many benefits. First, more candidates are provided to improve the recall by combining the advantages of different features.

Besides, positive images visually similar to query are easier to search, no matter in color or texture space. Graph fusion prompts these images to link the query with larger weighted edge. On the other hand, usually negative images cannot be searched in both feature space, hence these images may get smaller edge weight. In this way, multi-graph fusion insures the precision.

2.4. Ranking

For a graph obtained by single feature or multiple features, the relevant probability of the connected images is encoded into the edge weight. Intuitively, we aim to find the subgraph \( G' \) containing \( q \) in \( G \), which satisfies the following condition:

\[
 G' = \arg \max_{G' = \{V', E', w\}, q \in V'} \sum_{(i,i') \in E'} w(i, i') \quad \text{(6)}
\]

To solve Eq. 6 we first define the node set \( S = \{q\} \) and \( C \) containing nodes \( S \) points to. The node linked by the largest weighted edge in \( C \) is introduced into \( S \). After that the node sets \( S \) and \( C \) are updated. This procedure continues until cardinality of \( S \) satisfies user’s requirement. The nodes are ranked according to their order of insertion into \( S \).

Different from [1], we only consider maximizing local weighted instead of maximizing weighted density. As a consequence, the ranking method is less affected by outlier distraction and guarantees the precision of reranking.

3. EXPERIMENTS

3.1. Datasets

In this paper, we evaluate our proposed method on two public datasets, INRIA Holidays [9] and UKBench [3]. The Holidays dataset consists of 1491 images and 500 of them are queries. Most queries have less than 4 ground truth images undergoing various changes. Retrieval accuracy is measured by mAP (mean average precision). The UKBench dataset contains 10200 images. Every 4 images are taken from the same object with different viewpoints and illuminations. The N-S score is calculated to measure retrieval accuracy, which refers to the average recall of the top four ranked images.

3.2. Experiment settings

This paper exploits three baselines, which are denoted as BoW, HE and HSV (see Table 1).

BoW We adopt approach proposed in [2] as BoW baseline. Following [5], rootSIFT is used on every point. A codebook of size 20K is trained by approximate kmeans [2].

HE We incorporate the weighted Hamming Embedding (HE) [24] into the baseline of BoW to enhance performance.

HSV We make use of global HSV feature for complementary information. For each image, we compute the 1000 dimension HSV color histogram. Following [14], \( L_1 \) normalization and square scaling are performed for each color histogram. Retrieval is based on nearest neighbor search using Euclidean distance.

3.3. Experimental Results

We apply our approach to three baselines and obtain the reranking results: BoW Graph, HE Graph and HSV Graph,
Methods & Holidays(mAP%) & UKBench(N-S) \\
--- & --- & --- \\
BoW & 49.16 & 3.013 \\
HE & 76.60 & 3.491 \\
HSV & 63.90 & 3.398 \\
BoW Graph & 57.20 & 3.342 \\
HE Graph & 80.97 & 3.612 \\
HSV Graph & 68.16 & 3.697 \\
HSV+BoW & 75.44 & 3.768 \\
HSV+HE & 84.60 & 3.802 \\

| Methods | ours | [1] | [24] | [22] | [8] |
|---|---|---|---|---|---|
| Holidays(mAP%) | 84.6 | 84.6 | 84.8 | 84.7 | - |
| UKBench (N-S) | 3.80 | 3.77 | 3.64 | 3.75 | 3.52 |

Table 1: The performance of reranking.

Table 2: Comparison with the state-of-the-arts.

respectively. The performance of our method on Holidays is illustrated in Fig. 4. Considering the trade-off between efficacy and efficiency, we set the number of nearest neighbors $k$ to 10. After reranking, large improvements over the baseline can be observed from Table 1.

Moreover, we fuse HSV cues with BoW and HE separately to further enhance the performance. The reranking using complementary features improves the baseline significantly (see Table 1). For Holidays, combination of multiple features boosts the baselines of BoW and HE by 26.28% and 8% in mAP, respectively. Similar phenomena are observed on UKBench. The gain in N-S score over the BoW and HE are 0.755 and 0.311, respectively. Notably, we achieve a mAP of 84.6% on Holidays and an N-S score of 3.80 on UKBench, which are comparable to the state-of-the-arts (see Table 2).

Besides, as we can see in Fig. 4(a), our method is robust to outlier. There are many irrelevant images or outliers in the graph when $k$ is large, since most queries have less than 4 relevant images. But the accuracy is not affected even if $k$ reaches 60. It demonstrates the robustness of this reranking method to outlier distribution.

A comparison with [1] is presented in Fig. 5. When the parameter $k$ is chosen properly, [1] can achieve satisfying performance. However, [1] is very sensitive to parameter $k$ or the outlier distribution. When $k$ becomes large, the performance of [1] decreases. In comparison, our method is robust to outlier distribution and yields better fusion results.

3.4. Complexity

For graph construction, each image is used as query in our search system. Then, we compute and store their relevant relationships. The memory complexity is $O(Nk)$, where $N$ is the database size. The running time depends on parameter $k$, and Fig. 4(b) shows the time cost of this reranking using Matlab on a server with 3.46 GHz CPU and 64 GB memory.

4. CONCLUSION

In this paper, we propose an improved image graph for visual reranking, which is robust to outlier distraction. The graph encodes the relevance among images and the initial rank list is refined based on the graph. Moreover, this reranking could adopt multiple features to further enhance the performance. We have achieved an mAP of 84.6% on Holidays and an N-S score of 3.80 on UKBench using reranking combining BoW and color information. Our future work involves experimenting our method on more datasets and exploring more features such as attribute and GIST.

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