STRUCTURAL ANALYSES OF GLARE-GFRP TRANSITION FOR INTEGRATED VHF ANTENNA ON A FUSELAGE PANEL

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Abstract. The objective of this paper is to describe the numerical simulation of the transition zones in the multifunctional fuselage panel design to integrate a VHF (Very High Frequency) antenna. The panel is made of GLARE (Glass Laminate Aluminium Reinforced Epoxy) with a central window of GFRP (Glass Fibre Reinforced Polymer). The structural analyses of the transition GLARE/GFRP is presented along with its experimental validation. The numerical simulations showed a very high level of correlation with the experimental tests, both in the longitudinal load vs displacement curves and deformations captured with strain gauges and DIC (Digital Image Correlations).

1 INTRODUCTION

Providing composite structures with new functionalities often involve merging different material configurations, including layups and components, into a single continuous structure. This can produce transition zones with complex interactions between layers that must be studied in detail by simulations. Moreover, numerical simulations can also assist in the design process of this new composites structures.

This approach is put in practice during the procedure exposed on this paper, from the initial phase of assisted design to the experimental verification. The resultant GLARE/GFRP transition archived is broadly analysed with both, an experimental campaign and its equivalent numerical analysis. Most relevant results for the two representative orientations of final layout are presented. These are, the optimal and more demanded layout properly oriented i.e. Section BB in Figure 1, which is referred as MST-B (Mechanical Static Test) and secondly its complementary orientation MST-C in which the fibres are rotated 90 degrees.

This second configuration is placed in less demanded direction.
Design procedure.

The design procedure carried out to find the best transition to join the GLARE laminate with the GFRP windows located at the centre of the fuselage panel (shown in yellow at Figure 1) began with the numerical simulation of a predesign. The procedure shows some critical spots between the end of the aluminium sheets, proceeding from the GLARE laminate, and the beginning of the GFRP layers replacing them.

A better response was achieved when orientating the fibres of these GFRP layers following (parallel) the edge of the aluminium sheets as shown in Figure 2. Otherwise the high rigidity of the glass caused a sudden separation between the GFRP layers and the aluminium sheets that resulted in a quicker expansion of the damage to the surrounding layers. Despite not being structurally critical, the prevention of this micro damage could improve the structural long-term performance.

Finally the long fibres are placed just above and below the aluminium sheets, in addition a small resin gap is added between the parallel GFRP and the aluminium layers next to them leading to an optimal layout shown in Figure 2.

In this way the stresses of the aluminium sheets are transferred to the surrounding long fibres across its whole upper and lower contact surfaces and the epoxy matrix of the parallel layers benefits from the high stiffness and low deformation of these. The resulting transition geometry manage to stream the stresses between its ends gradually, minimizing the areas of stress concentrations. Therefore, reducing the critical points that can lead to intralaminar fracture and delamination phenomena. The whole final layup of the transition are confidential and can not be shown on this publication.
1.1 GEOMETRY AND TEST SETUP OF THE SPECIMEN

The dimensions of the tested specimens are 700 mm length and 100 mm width, the free length between jaws is 580 mm (See Figure 3). In Figure 3 the location of the strain gauges i.e. 1 and 3 on the inner side and 2 and 4 on the outer side (see red cross points) are shown.

In the experimental test, a displacement is imposed by means of a piston that slowly displaces one jaw meanwhile the other remains steady. The reaction of the specimen and the imposed displacement are recorded. Moreover, deformations are measured using the four strain gauges together with a Digital Image Correlation (DIC) equipment.

1.2 NUMERICAL MODEL

The numerical model developed reproduces the geometry of the laminate layer by layer along the whole specimen, including the small resin gaps located between layers. Each GFRP layer is discretized with an element in the direction of thickness, while two elements are used in the aluminium sheets. Then, it allows to analyse the stress-strain state of each layer individually. The finite element mesh has approximately 250,000 hexahedral linear elements with 8 nodes and 8 Gauss points.

GFRP is simulated using the mixing theory Serial-Parallel [1][2][3] already used in the analysis of a multifunctional Orthogrid Panel [4]. It together with the non-linear constitutive models used in the fibres and matrix, it is able to monitor the onset and evolution of damage and plasticity. On the other hand, the aluminium material is characterized with a plastic constitutive law, which reproduces accurately the non-linear behaviour of GLARE.

The numerical simulation takes advantage of the symmetry of the specimen and its layout and only a quarter of the total geometry is simulated. The effect of the clamp is implemented by imposing a displacement in the Y direction and restricting movement also in the X direction on all nodes under the grip area.

Experimentally it was proved that the displacements out of the plane were low and their impact could be neglected. For these reasons the analysis were made within the small deformations paradigm, but in order to prevent fictitious bending was necessary restrict movement in the Z direction on the entire outer face of the panel.
3 NUMERICAL RESULTS

In the present section the comparison of the numerical vs experimental results is presented for the two configurations studied. The loads and displacement from the piston test machine, as well as the strains measured with the strain gauges and captured with the DIC are used for the comparison.

3.1 LAYOUT CONFIGURATION MST-B

Figure 4 shows the load vs displacement curve for configuration MST-B.

The initial stiffness obtained in the experimental test is very similar in comparison with the numerical analysis. When one-millimetre displacement is reached, the experimental results show a progressive loss of stiffness. The numerical simulation also shows accurately this stiffness loss. However, the overall stiffness is slightly higher.

The load vs strain curves obtained with the strain gauges and DIC show a good correlation between the experimental and numerical results (See Figure 5). It can be seen in both graphs how the rigidity of the central zone (SG2) is constant with a very good approximation by the numerical analysis. The response in the GLARE is not that high and it suffers a loss of stiffness between 4000 and 5000 micro strains. This drop is more abrupt in the numerical analysis although the two graphs behave similarly.

Figure 4: MST-B Load vs Displacement

Figure 5: Resultant Load vs Strain curves of B configuration (strain gauges - DIC)
3.2 LAYOUT CONFIGURATION MST-C

Despite being poorly oriented the experimental overall response of configuration MST-C is almost identical to that measured in configuration MST-B. In addition the numerical analysis shows a extremely similar behaviour (see Figure 6).

The numerical analysis also shows a good correlation with the deformation recorded in the central strain gauge as well as in the GLARE sections as can be seen in Figure 7.

However, due to the non-optimal orientation of the fibres adjacent to the aluminium sheets, more and more damage zones are registered in the resin that joins them, as well as in the resin of the perpendicular GFRP layers located immediately above and below.

These small matrix micro damage zones do not impact globally the performance of the structure in comparison to the optimally oriented configuration, but it is still necessary to reduce their occurrence in order to prevent future delamination.

Figure 6: MST-B Load vs Displacement

Figure 7: Load vs strain of Test MST, for Layout C
Finally, it can be observed in Figure 8 how the breakage zone in the experimental test coincides with the zone with the highest stresses found in both numerical simulation, configuration B and C. In this area, the stresses in the fibres orientated in longitudinal direction reach the ultimate tensile strength causing the overall failure of the sample.

4 CONCLUSIONS AND FINAL REMARKS

- The numerical simulation shows a predicted initial stiffness in good agreement with the experimental results. The global response of both configurations tested starts with a non-linear behaviour around 0.8 mm of piston displacement as it can be observed in the load vs displacement experimental curves (see Figures 4 and 6). The numerical results follow a very similar behaviour but with a slightly higher stiffness. After that, both curves, i.e. experimental and numerical, remain parallel with the same slope.
- The load vs strain curves of the both configurations reflect a good simulation at the microscopic level, with deformation curves that are very close to the experimental ones. It can therefore conclude that the constitutive level is simulated correctly.
- The great similarity in the behaviour of both configurations indicates a good balance in the orientation of layers which reaches to a laminate with correct orthotopic behaviour.
- The failure zone in the experimental test coincides with the point with the highest stress concentration in the numerical simulations. The strain recorded just before the break agrees well with the constitutive behaviour of the glass fibres.

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