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Thermomechanics of DNA: Theory of Thermal Stability under Load.

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A theory for thermomechanical behavior of homogeneous DNA at thermal equilibrium predicts critical temperatures for denaturation under torque and stretch, phase diagrams for stable B-DNA, supercoiling, optimally stable torque, and the overstretching transition as force-induced DNA melting. Agreement with available single molecule manipulation experiments is excellent.

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DNA is a sophisticated nanomechanical object. The interplay between strong covalent bonds of the backbone and weak hydrogen interactions between bases [1], the thermal bath in which it is immersed, and the proximity of physiological conditions to the denaturation temperature, make DNA highly and non-linearly responsive to mechanical and thermal changes, and render any solely mechanical approach incomplete. This is critical for nanotechnology, where DNA is the basis for novel materials [2], but understanding double helix thermomechanics would also illuminate biology, where, e.g., enzymes involved in replication and repair are viewed as molecular motors.

In the past twenty years, direct single molecule manipulation [3] has revolutionized our understanding of key aspects of DNA, revealing new couplings and transitions between different structures, whose nature and forms, however, are still speculative. When a few micrometer long strand of DNA is stretched to a tension of the order of pico-Newton (pN) at zero torque [3–5]. Tentative tension–torque phase diagrams for the stability of B-DNA [4], and various phenomenological theories, some of which highly parametrized, have been proposed to explain these effects [5–11]. The robustness of the Peyrard-Bishop-Dauxois approach (PBD) [12–14] has been corroborated by Cocco and Barbi [15, 16]: they incorporated torque and successfully reproduced denaturation by unwinding. However, these recent studies do not include tension, do not explain denaturation at overwinding, and do not provide phase diagrams in the tension-torque plane. Also, although much simpler than the molecular structure they describe, their complexity cannot offer analytic equations to more easily guide experiments.

We address these issues by modeling the pitch dependence of the base bond and therefore the effect of tension and torque in a way suitable for elimination of the angular degrees of freedom via integration of the partition function, and obtain an effective energy for a PBD model which incorporates temperature and external loads. We compute the phase diagram for B–DNA and the dependence of supercoiling on torque, tension and temperature at criticality. Finally, we propose simple algebraic formulæ for the observables. Although here we neglect bending modes [17, 18], we will show elsewhere [19] how to incorporate them into our framework.

In our model $i$ labels nucleotides separated by a distance $a$ along the DNA backbone (Fig. 1), $x_i$ is the length of the $i^{th}$ base's bond, $\omega_i = (\theta_{i+1} - \theta_{i-1})/2 - \Omega$ is the angular shift between nucleotides along the backbone, and $\theta_i$ is their angular coordinate. As in the Cocco–Barbi models [15, 16], the two strands of DNA are assumed symmetrical, with a fixed rigid center line, and infinitely long. $\Omega$ denotes the natural pitch of the helix, and $\omega_i$ describes deviations from equilibrium. The potential energy of the system is $E = a \sum_i E_i$ with

$$E_i = \frac{k}{2} \Delta x_i^2 + \frac{\nu}{2} (\omega_i + \Omega)^2 + \chi(x_i - 1) V(\omega_i) \quad (1)$$

the sum of: a stacking potential ($\Delta x_i = x_{i+1} - x_i$), in harmonic approximation for simplicity (see discussion later); an elastic term which restores the $\theta_{i+1} = \theta_i$ angular configuration for open strands; and a square well potential for the hydrogen bond between bases $\chi(x)$ is a step function which is 0 for $0 \leq x \leq x_c$, and 1 for $x_c < x$, where $x_c$ is a length associated with the hydrogen bond, whose depth $V$ depends on the angle $\omega_i$. Because of a complex combination of hydrophobic, $\pi$–$\pi$, and dipolar interactions, the bonding of opposite bases is responsible for DNA's pitch. Therefore $V(\omega)$ is not symmetric but rather $V'(0) = \nu \Omega$, since DNA is in equilibrium at $\omega_i = 0$. Also, $\mu = -V''(0)$ must be positive: indeed, $\nu + \mu$ being the torsional rigidity of the joined double helix and $\nu$ of the (much softer) open strands, we have $\mu \gg \nu > 0$ (we shall see that $\mu/\nu \sim 10^3$). We can now expand $V$ as

$$V(\omega) \simeq V_0 + \nu \Omega \omega - \frac{1}{2} \mu \omega^2. \quad (2)$$

Our choice of a square well potential and separation of variables $x_i$, $\omega_i$ in (1) keeps the model analytically solvable: no substantial changes in the thermodynamics arise from surrendering it in favor of, e.g., the Morse potential [14]. We show elsewhere how to introduce a smooth potential, desirable for dynamics and other studies [19].

Now consider the external loads. The torque $\Gamma$ is incorporated in (1) via a term $-\sum_i \tau \omega_i a$ (for dimensional
The term $\Delta = -\frac{T}{2\pi} \ln \frac{2\pi T}{a} - \frac{1}{2} \tilde{\nu} \Omega^2 - vf - \Omega \tau - \frac{1}{2} \tau^2$ from (3), while irrelevant for the phase diagram, must be kept when computing supercoiling. $L = Na$ is the length of the DNA. There are then purely geometrical parameters: $m = \frac{R^2}{ah_0^2} + \frac{R^4}{ah_0^3} \omega_0^2 - n$, $n = \frac{\tau^2}{2\pi}$, $o = \frac{R^2}{ah_0} \Omega$, $v = 1 - \frac{h_0}{a}$, where $R$ (\approx 10 Å) is the radius of the DNA molecule, $h_0$ (\approx 3.4 Å) the elevation between consecutive nucleotides, $a$ (\approx 7 Å) their distance along the backbone, and $\Omega = 2\pi/10$ the pitch of DNA: these are established geometrical values for B-DNA, but our formalism works, mutatis mutandis, for A- and Z-forms.

The expression for $Z$ in (3) is exact within our model, and the resulting PB problem (or PBD if anharmonicity is included) is amenable to numerical transfer matrix treatment. Here we will proceed analytically. In the continuum limit, neglecting an irrelevant equipartition factor, and taking $L$ large, $Z$ in (3) can be written as

$$Z \propto e^{-\beta L \Delta} \text{Tr} e^{-\mathcal{L} T},$$

proportional to the trace of the operator

$$\hat{H} = -\frac{1}{2k\beta} \Omega^2 + \beta \mathcal{V}(x_1).$$

Torque, tension and temperature enter the potential (4), and the critical surface corresponds [12] to the disappearance of the bound state for $\hat{H}$, or

$$\hat{\Omega} T - \frac{1}{2} \left( \tilde{\mu} \tau^2 + \nu f + \frac{\sigma^2 j^2}{\nu + \tilde{\mu}} + \frac{T_B^2 - T^2}{e\epsilon c} \right) + \frac{1}{2a} \left( T_{D} l - T \right) = 0,$$

where $\epsilon = 8k_{\text{ex}}/\pi^2$ has the dimension of an energy, $l = \ln[(\nu + \mu)/\nu]$ and $l = \ln[(\tilde{\nu} + \tilde{\mu})/\tilde{\nu}]$ are pure numbers, and $T_B^2 = e\epsilon c (V_0 - \frac{T_B}{2} \ln \frac{T_B}{T} - \frac{1}{2} \nu \Omega^2)$ is the denaturation temperature in the absence of torque or tension. There are only a few parameters to fit: a typical value for the denaturation temperature used in theoretical treatments [15, 16] is $T_B = 350$ K [20]; we show below from data on torque-winding experiments that $\mu = 10^3$ pN. Choosing the remaining three parameters as $e\epsilon c = 45$ pNÅ, $\nu = 24$ pN and $n = 0.3$, provides a remarkably good fit for 10 experimental data points (20 numbers) [4] in the $f$ vs. $\Gamma$ phase diagram of Fig. 2. The skewness of the critical lines can be quantified: from (7) one finds for $\Gamma_m = (\Gamma^+_m + \Gamma^-_m)/2$, the middle point between critical torques at given tension,

$$\Gamma_m = \frac{a \tilde{\mu} + \tilde{\nu}}{\mu} \tilde{\Omega} \simeq a \nu \Omega + \frac{n \Omega - \frac{av}{\mu}}{\mu},$$

independent of temperature. As (8) reveals, skewness results from backbones twisting under torque: it would be erroneously negative for $r = 0$. With our parameters,

$$\Gamma_m/(\text{pN} \times \text{nm}) = 11 + 92 \times 10^{-3} f/(\text{pN}).$$
Equations (8, 9) along with experimental data for DNA that place melting at \( f = 15 \) pN, for \( \Gamma_c = 34 \) pN\( \times \)nm, \( \Gamma_c = -10 \) pN\( \times \)nm and at \( f = 60 \) pN, for \( \Gamma_c = 33 \) pN\( \times \)nm [4], predict melting at zero torque and tension \( f = 60 \) pN (blue square in Fig. 2) in good agreement with the observed overstretching transition (if no effective torque is exerted by the experimental apparatus, otherwise higher critical force is reported, consistent with Fig. 2 [19, 21]. Our analysis implies a force-induced melting [21] rather than a transition to a double helix with distortions [22]. A positive torque stabilizes DNA even at temperatures above denaturation (Fig 2, inset), a property exploited by thermophile bacteria living at high temperatures [1]. As expected, negative torque destabilizes DNA, a mechanism exploited in biology for DNA opening and replication.

Under a given stretch, the critical temperature increases (decreases) under positive (negative) torque, as shown in Fig. 3. From (7) we see that \( T_c \) is maximized at \( \Gamma = \Gamma_m(f) \), which therefore induces the most stable configuration at any temperature, for a certain tension \( f \). The highest temperature B–DNA can withstand is achieved under zero tension and positive torque \( \Gamma_m = a\nu\Omega = 11 \) pN\( \times \)nm, and corresponds to \( T_c = 91 \) °C. 

![Fig. 2: Predicted critical lines for denaturation at different temperatures. The region enclosed by each line corresponds to stable B–DNA at that temperature. Points are experimental data from single molecule manipulation [4], square corresponds to the well known overstretching transition (\( \Gamma = 0, f = 60 \) pN), \( T_D = 350 \) K = 77 °C, the denaturation temperature, is critical at zero external load: but even at temperatures of \( T_D \) or higher (inset), B–DNA can be stable in an interval of applied positive torque. Solid (dotted) straight line indicates \( \Gamma_m = a\nu\Omega \) (its approximation \( \Gamma_m = 11 + 0.092f \)), the middle point between critical torques, which also corresponds to the highest critical temperature at given tension.](image1)

![Fig. 3: Predicted critical temperature as function of torque for stretched DNA at different tensions (0, 15, 30, 45, 60, 75, 80, 85, 90 pN). Points are experimental data from single molecule manipulation [4] performed at 23 °C. Squares correspond to the overstretching transition (\( \Gamma = 0, f = 60 \) pN) at 23°C and denaturation (\( \Gamma = 0, f = 60 \) pN) at \( T_D = 77 \) °C. The maximal critical temperature for a given stretch is achieved under external torque \( \Gamma_m(f) \) given by (8), and is 91 °C at zero tension and \( \Gamma_m = 11 \) pN\( \times \)nm.](image2)

![Fig. 4: Predicted critical temperature as a function of tension for DNA twisted under different torque. Numbers on curves denote the external torque in pN nm. The maximum critical temperature at any given tension (dotted curve) is reached at external torque \( \Gamma_m(f) \) from (8). While for negative torque the curves show a monotonic and linear decrease (inset), for positive torque larger than 32 pN\( \times \)nm (dashed curve) curves become non-monotonic: for low temperatures and large applied torque, B–DNA is stabilized by tension.](image3)
DNA supercoils for packaging inside cells [1]. This corresponds to small positive or negative torques; in that biological regime, the critical temperature decreases monotonically with an applied tension, in fact linearly, with slope independent of the applied torque or degree of supercoiling. Yet, for torques larger than about 32 pN×nm, a regime accessible to single molecule manipulation experiments and potentially useful in nanotechnology, the maximal critical temperature corresponds to a non-zero tension, suggesting that at low temperatures and large torques DNA can be stabilized by tension (Fig. 4).

The average change in pitch is given by $\langle \omega \rangle = L^{-1} \beta^{-1} \partial_\tau \ln Z = \tau / \tilde{\nu} - \epsilon_B$ ($\epsilon_B$ is the bound eigenvalue of the hamiltonian (6), whereas the remainder comes from $\Delta$). At the critical point, we find

$$\langle \tilde{\omega} \rangle = \omega_D - \frac{\omega_D}{\Omega} \frac{\Gamma_c}{a \tilde{\nu}} + \left( 1 + \frac{\omega_D}{\Omega} \right) \frac{a^{-1} \Gamma_c - c \epsilon}{\tilde{\nu} \mu} \approx \frac{\Gamma_c}{a \tilde{\nu}}, \quad (10)$$

where $\omega_D$ is the small negative unwinding (typically $\omega_D \approx -10^{-4}$ rad) at denaturation ($T = T_D$, $\Gamma = 0$, $f = 0$). Equation (10) can be used to fit, from experimental data [4], $\mu = 10^3$ pN. When neglecting small nonlinear corrections, (10) is also a good approximation for the torque vs. pitch curve away from criticality. While the derivation of (10) will be presented elsewhere [19], we note here that a well potential on an infinite half line in (6) would generate no contribution from the bound eigenvalue $\epsilon_B$ to $\langle \tilde{\omega} \rangle$ at criticality, and thus give $\langle \tilde{\omega} \rangle = \frac{\Gamma_c}{a \tilde{\nu}} - \Omega$, the expected behavior for separated strands. The discontinuity at criticality in $\langle \tilde{\omega} \rangle$ seen in experiments therefore comes from the finiteness of lateral entropy: when bases open in a bubble, they cannot separate infinitely far from each other: as tension and torque are applied and backbones twist, the radius of DNA provides a natural barrier for large $x$. This suggests that in biology, where, unlike in manipulations under tension, larger distances are available between bases in larger openings, the average change in pitch $\langle \omega \rangle$ might access larger values before complete strand separation occurs.

Equation (10) does not predict the tiny anomalous overwinding under tension [23]. We believe this is a consequence of neglecting the bending modes, whose thermal fluctuation weakens the base’s bonds. As tension straightens DNA, it might reduce this effect by collapsing openings and thus overwinding the structure. Conversely, torque-induced overwinding reduces the fraction of open bases, thereby stiffening the bending modes and reducing the amplitude of their thermal fluctuations, resulting in elongation. Essential to fully predict elongation under external loads, bending modes also perturb our phase diagrams at low and medium tension and at temperatures close to denaturation. We will show elsewhere [19] how to incorporate them into our formalism. Finally, a transfer integral numerical study [19] of the anharmonic version of (3) is needed to augment our predictions at temperatures closer to denaturation, where the effect of nonlinearity in the stacking potential is important for the transition order and precursors [24].

In summary, a range of predictions and phenomena for DNA thermomechanics (critical lines, phase diagrams, supercoiling under loads, optimally stable torque, tension-induced stability at high torque) that were inaccessible to previous models, or were covered partially and numerically, have been explained here within a unifying framework amenable to analytical treatment and further extensions and applications. It will be interesting to test experimentally our predictions at higher then room temperatures, and also at different ionic strength.

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