New Construction of Algebro-Geometric Solutions to the Modified Kadomtsev-Petviashvili Hierarchy

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Abstract
We extend Gesztesy-Holden’s method to 2+1 dimensional case to obtain a unified construction to the algebro-geometric solutions of the whole modified Kadomtsev-Petviashvili (mKP) hierarchy. Our tools include the relations between solutions of the Gerdjikov-Ivanov (GI) and mKP hierarchy, the Baker-Akhiezer functions in 2+1 dimensions, a special function $\psi_1(P)\psi_2(P^*)$ on $X \times \mathbb{R}^3$ and Dubrovin-type equations for auxiliary divisors.

Key words: modified Kadomtsev-Petviashvili hierarchy, Baker-Akhiezer function, algebro-geometric method, Riemann theta function, algebro-geometric solutions.

1 Introduction
The KP hierarchy and its counterpart, for example, the mKP hierarchy, plays an important role in a variety of different fields including modern string theory and in connection with the solution of the Schottky problem of compact Riemann surfaces [10], [47]. It is generally believed that all integrable hierarchies of (1+1)-dimensional equations by means of the inverse scattering method can be represented as certain reductions of a universal Kadomtsev-Petviashvili (KP) hierarchy of (2+1)-dimensional equations and/or of its extensions to modified and multicomponent cases [20], [45]. This hypothesis originates from a unifying Sato theory that describes the KP hierarchy in terms of the pseudodifferential operator

$$\mathcal{L} = \frac{\partial}{\partial x} + \sum_{j=1}^{\infty} u_{j+1}(\frac{\partial}{\partial x})^{-j}$$

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with functions \( u_j = u_j(t_1, t_2, \ldots) \) that depends on an infinite number of independent variables \( t_j, j \in \mathbb{N} \) \([6], [7], [23], [46]\), which indicates that by introducing an infinite set of time variables one can also treat the integrable equations as flows on infinite-dimensional Grassmannian manifolds [23]. Based on the treatment of partial differential KP equations as dynamical systems on the infinite-dimensional algebra of pseudo-differential operators [1], the KP equation [7], [23]

\[
u_t = \frac{1}{4} u_{xxx} + 3 u u_x + \frac{3}{4} \partial_x^{-1} u_{yy}, \quad (1.1)
\]

is considered as the simplest member of a hierarchy of equations that can be brought to bilinear form and solved by the \( \tau \)-function approach. This theory reveals deep interrelations between the Hamiltonian structures of the KP hierarchy and two-dimensional conformal field theory as well as \( W_{1+\infty} \) algebras [49].

The problem of constructing the quasiperiodic solutions (QPS) is one of the most challenging problems of the theory of integrable systems, and many mathematicians and physicists spent much efforts to obtain the QPS for almost all equations that are known to be integrable. Among the most powerful solution generating methods are techniques from algebraic geometry which lead to solutions in terms of Riemann theta functions on certain Riemann surfaces, that is, the so-called algebro-geometric solutions. This kinds of solutions were originally studied on the KdV equation based on the inverse spectral theory and algebro-geometric method developed by pioneers such as Novikov [10], Dubrovin et al. [11], [12], Its & Matveev [21], [22], Lax [36], and McKean & van Moerbeke [38] for \( 1 + 1 \) systems, and extended by Krichever in 1976 for \( 2 + 1 \) systems like KP [32], [33] in the late 1970s. Later this theory has been developed to the whole hierarchies of nonlinear integrable equations by Gesztesy, Holden et al. using polynomial recursion method [8], [16], [17], [18]. Another breakthrough in this area was made by Mumford [41] in early 1980s, who observed that integrable equations like KdV, KP or sine-Gordon, are hidden in Fay’s trisecant formula. Mumford’s approach are based on degenerated versions of Fay’s identity, which reveals the relations between algebro-geometric solutions of integrable equations and a purely algebro-geometric identity [24], [26], [27]. A detailed introduction and recent development about this subject can be found in the survey article [37].

The study of higher dimensional integrable equations is usually considered a more difficult problem than \((1+1)\)-dimensional equations and by now, much work has been done on KP and mKP equation. An important
development of the algebro-geometric method was the passage from 1+1 systems to the integration of 2+1 KP-like systems, realized by Krichever in 1976 [32], who constructed algebro-geometric solutions of the KP equation on a basis of a purely algebraic formulation of algebro-geometric approach. A generalized Miura transformation between the KP equation and mKP equation was discussed in [14]. Later it has been shown that the mKP hierarchy can be constructed on the basis of the Sato approach by means of the gauge transformation of the KP hierarchy which results in modification of the pseudo-differential operator $\mathcal{L}$ [43]. In ref. [19], the authors obtain new Bäcklund transformations for the KP hierarchy and the possibility of transferring classes of KP solutions into those of mKP solutions. A explicit theta function solution of the mKP equation is derived by the technique of nonlinearization of Lax pairs and Abel inversion [4]. However, within the knowledge of the authors, the algebro-geometric solutions of the entire mKP hierarchy has not been considered so far.

In this paper, using inherent relations between the mKP hierarchy and GI hierarchy, we shall improve the method in [18] to obtain a unified construction to the algebro-geometric solutions of the whole hierarchy. We extend the concepts the Baker-Akhiezer function to the mKP hierarchy and find a class of quasiperiodic solutions by algebro-geometric method. The construction exploits explicit form of the Baker-Akhiezer function and involve also a fundamental meromorphic function, which allows for the analytic properties of the Baker-Akhiezer function. The theta function representation for algebro-geometric solutions of the mKP hierarchy are then verified directly using formulae for the Baker-Akhiezer function and its $x$-derivative. In our construction, theoretical analysis of algebro-geometric solution for the whole mKP hierarchy are carried out from a different angle of view and the whole approach discussed in the present paper is a general one and gives similar results for other 2+1 dimensional and higher dimensional soliton equations.

This paper is organized as follows. In section 2, we first introduce the GI hierarchy and mKP hierarchy and then discuss the Burchnall-Chaundy polynomial in connection with a basic initial value problem and underlying hyperelliptic curve. In section 3, the dynamics of auxiliary spectral points $\{\mu_j\}_{j=1}^n$, $\{\nu_j\}_{j=1}^n$ and corresponding trace formula is considered. In section 4, we present explicit representation for the Baker-Akhiezer functions $\psi_1(P), \psi_2(P)$, whose analytic properties can be derived by studying an important function $\psi_1(P)\psi_2(P^*)$. In section 5, we shall obtain Riemann theta function representation for $\psi_1(P), \psi_2(P), \psi_1(P)\psi_2(P^*)$, and especially for the algebro-geometric solutions $q, r$ of the whole mKP hierarchy.
2 mKP Hierarchy, GI Hierarchy, Burchnall-Chaundy Polynomial and Basic Initial Value Problem

To make this paper self-contained, we shall first introduce the mKP hierarchy in standard literature and then provide the construction of the GI hierarchy and derive the associated sequence of Lax pairs using a polynomial recursion formalism. Moreover, we obtain the Burchnall-Chaundy polynomial in connection with the modified KP hierarchy and underlying hyperelliptic curve.

Throughout this section we make the following hypothesis.

**Hypothesis 2.1.** Suppose that $q, r : \mathbb{R}^3 \to \mathbb{C}$ satisfy

$$q(\cdot, y, t_p) \in C^\infty(\mathbb{R}), \quad t_p \in \mathbb{R},$$

$$q(x, y, \cdot), r(x, y, \cdot), q(x, \cdot, t_p), r(x, \cdot, t_p) \in C^1(\mathbb{R}), \quad x, y \in \mathbb{R},$$

$$q(x, y, t_p) \neq 0, \quad r(x, y, t_p) \neq 0, \quad (x, y, t_p) \in \mathbb{R}^3. \quad (2.1)$$

The KP and mKP equation, e.g. \cite{23, 28, 29, 30} and the algebraic framework of the KP and mKP hierarchy can be found in \cite{1, 2, 9, 15, 39, 44, 35, 48}. In Sato theory, the mKP hierarchy is described by the isospectral deformations of the eigenvalue problem

$$L\psi = \lambda \psi, \quad \lambda \in \mathbb{C}, \quad (2.2)$$

where the pseudodifferential operator $L$ is given by

$$L = \partial + \sum_{j=0}^{\infty} u_{j+1} \partial^{-j}, \quad \partial = \frac{\partial}{\partial x}, \quad (2.3)$$

and $u_j$ are functions in infinitely many variables $(x, t_1, t_2 \ldots)$ with $t_1 = y$. We denote by $B_m$ the differential part of $L^m$:

$$B_m = (L^m)_+ = \sum_{j=1}^{m} b_{m,j} \partial^j. \quad (2.4)$$

The coefficients $b_{m,j}$ in (2.4) can be uniquely determined by the coordinates $u_j$, and their $x$ derivatives. Explicitly,

$$B_1 = \partial,$$

$$B_2 = \partial^2 + 2u_1 \partial,$$

$$B_3 = \partial^3 + 3u_1 \partial^2 + 3(u_2 + u_{1,x} + u_{1}^2) \partial,$$

$$B_4 = \partial^4 + 4u_1 \partial^3 + (4u_2 + 6u_{1,x} + 6u_1^2) \partial^2 + (4u_3 + 6u_{2,x} + 4u_{1,xx} + 12u_1 u_2 + 12u_1 u_{1,x} + 4u_1^3) \partial, \quad \text{etc.}$$
From the compatibility conditions of \((2.2)\) and
\[
\phi_{tm} = B_m \phi, \tag{2.5}
\]
we have
\[
L_{tm} = [B_m, L], \tag{2.6}
\]
or equivalently,
\[
(B_m)_{tn} - (B_n)_{tm} = [B_n, B_m]. \tag{2.7}
\]
The mKP hierarchy is obtained from \((2.6)\) or \((2.7)\) for infinite coordinates \(\{u_j\}_{j=2}^{\infty}\). For example, from \((2.6)\), one obtains
\[
u_{1,t} = 2u_{2,x} + u_{1,xx} + 2u_1 u_{1,x}, \tag{2.8}
\]
\[
u_{2,t} = 2u_{3,x} + u_{2,xx} + 2(u_1 u_2)_x, \tag{2.9}
\]
\[
u_{3,t} = 2u_{4,x} + u_{3,xx} + 2u_1 u_{3,x} + 4u_1 u_3 - 2u_{1,xx} u_2, \tag{2.10}
\]
\[
\vdots \nonumber
\]
\[
u_{1,t} = 3u_{3,x} + 3u_{2,xx} + u_{1,xxx} + 6(u_1 u_2)_x + 3(u_1 u_{1,x})_x + 3u_1^2 u_{1,x}, \tag{2.11}
\]
\[
u_{2,t} = 3u_{4,x} + u_{3,xxx} + u_{2,xxx} + 6(u_1 u_3)_x + 3(u_1 u_{2,x})_x + 6u_2 u_{2,x} \nonumber \\
+ 3(u_1^2 u_2)_x, \tag{2.12}
\]
\[
\vdots \nonumber
\]
\[
u_{1,t} = 4u_{4,x} + 6u_{3,xx} + 4u_{2,xxx} + u_{1,xxxx} + 12(u_1 u_3)_x + 12u_2 u_{2,x} \nonumber \\
+ 12(u_1 u_{2,x})_x + 6(u_1 u_{1,x})_x + 6u_1 u_{1,xx} \nonumber \\
+ 12(u_1^2 u_2)_x + 6(u_1^2 u_1)_x + 4u_1^3 u_1, \tag{2.13}
\]
\[
\vdots \nonumber
\]
Eliminating \(u_2, u_3, u_4\) from \((2.8), (2.9), (2.10)\) and taking into account \((2.11), (2.13)\), one obtains
\[
u_{t} = \frac{1}{4} u_{xxx} - \frac{3}{2} u_x^2 u_x + \frac{3}{2} u_x \partial^{-1} u_y + \frac{3}{4} \partial^{-1} u_{yy} \tag{2.14}
\]
\[
u_{t} = \frac{1}{2} u_{xxy} - 2u_x^2 u_y + u \partial^{-1} u_{yy} + 2u_y \partial^{-1} u_y - \partial^{-1}(u u_y)_y - 2u_x \partial^{-1} u u_y \nonumber \\
+ u_x \partial^{-2} u_{yy} + \frac{1}{2} \partial^{-2} u_{yyy}. \tag{2.15}
\]
where we denote by \(u = u_1\). Equation \((2.14)\) is the mKP equation and equation \((2.15)\) is the first higher order flows of the mKP hierarchy. Similarly, the mKP and higher-order mKP equation can also be derived from \((2.7)\) with \(n = 2, m = 3\) and \(n = 2, m > 3\), respectively.
Next we construct the GI hierarchy. To this end one has to consider the following one-dimensional $2 \times 2$ matrix-valued differential expression

$$M = \begin{pmatrix} -\partial + \frac{1}{4} qr & -qz \\ rz & \partial - \frac{1}{4} qr \end{pmatrix},$$

(2.16)

and another $2 \times 2$ matrix-valued differential expression of order $2n+2$ with respect to $z$, denoted by $Q_{2n+2}$, $n \in \mathbb{N}_0$, which is defined recursively in the following. Defines the sequences of differential polynomials \{f_\ell\}_{\ell \in \mathbb{N}_0}, \{g_\ell\}_{\ell \in \mathbb{N}_0}, \{h_\ell\}_{\ell \in \mathbb{N}_0}$, recursively by

$$g_{2\ell+1} = f_{2\ell} = h_{2\ell} = 0, \quad \ell \in \mathbb{N}_0,$$  

(2.17)

$$f_1 = 2q, \quad g_0 = 2, \quad h_1 = -2r,$$  

(2.18)

$$2f_{2\ell+1} = -f_{2\ell-1,x} + 2qg_{2\ell} + (1/2)qrf_{2\ell-1}, \quad \ell \in \mathbb{N}_0,$$  

(2.19)

$$2h_{2\ell+1} = h_{2\ell-1,x} - 2rg_{2\ell} + (1/2)qrh_{2\ell-1}, \quad \ell \in \mathbb{N}_0,$$  

(2.20)

g_{2\ell,x} = r f_{2\ell+1} + q h_{2\ell+1}, \quad \ell \in \mathbb{N}_0. \quad (2.21)

Here $q, r$ should be considered as functions of infinitely many variables $(t_1, t_2, t_3, \ldots)$. Explicitly, one computes

$$f_1 = 2q,$$

$$f_3 = - (1/2) q^2 r - q_x + c_1(2q),$$

$$f_5 = (1/8) q^3 r^2 + (3/4) q q_x r - (1/4) q^2 r_x + (1/2) q_{xx}$$

$$+ c_1(-q^2 r/2 - q_x) + c_2(2q),$$

$$\ldots,$$

$$g_0 = 2,$$

$$g_2 = - qr + 2c_1,$$

$$g_4 = (1/4) q^2 r^2 + (1/2)(q_x r - qr_x) + c_1(-qr) + 2c_2,$$

$$g_6 = - q^3 r^3 + 3 q^2 r r_x - 3 q q_x r^2 - q_{xx} r - qr_{xx} + q_x r_x$$

$$+ ((1/4) q^2 r^2 + (1/2)(q_x r - qr_x)) c_1 + c_2(-qr) + 2c_3,$$

$$\ldots,$$

$$h_1 = - 2r,$$

$$h_3 = (1/2) qr^2 - r_x + c_1(-2r),$$

$$h_5 = - (1/8) q^2 r^3 + (3/4) q r r_x - (1/4) q_x r^2 - (1/2) r_{xx}$$

$$+ c_1(q r^2/2 - r_x) + c_2(-2r), \quad \text{etc.},$$

where $\{c_\ell\}_{\ell=0}^\infty \subset \mathbb{C}$ are integration constants. Subsequently, we also introduce the corresponding homogeneous coefficients $\hat{f}_\ell, \hat{g}_\ell, \text{ and } \hat{h}_\ell$, defined by
vanishing of the integration constants \( c_k \), for \( k = 1, \ldots, \ell \),
\[
\begin{align*}
\hat{f}_1 &= 2q, \quad \hat{f}_{2\ell+1} = f_{2\ell+1}|_{c_k=0, k=1,\ldots,\ell}, \quad \ell \in \mathbb{N}, \quad (2.22) \\
\hat{g}_0 &= 2, \quad \hat{g}_{2\ell} = g_{2\ell}|_{c_k=0, k=1,\ldots,\ell}, \quad \ell \in \mathbb{N}, \quad (2.23) \\
\hat{h}_1 &= -2r, \quad \hat{h}_{2\ell+1} = h_{2\ell+1}|_{c_k=0, k=1,\ldots,\ell}, \quad \ell \in \mathbb{N}. \quad (2.24)
\end{align*}
\]
Hence,
\[
\begin{align*}
f_{2\ell+1} &= \sum_{k=0}^\ell c_{\ell-k} \hat{f}_{2k+1}, \quad g_{2\ell} = \sum_{k=0}^\ell c_{\ell-k} \hat{g}_k, \quad (2.25) \\
h_{2\ell+1} &= \sum_{k=0}^\ell c_{\ell-k} \hat{h}_{2k+1}, \quad n \in \mathbb{N}_0.
\end{align*}
\]
introducing \( c_0 = 1 \). Next we construct the stationary GI hierarchy. Now \( q, r \) are considered as functions of the variable \( x \) and the \( 2 \times 2 \) matrix-valued differential expression \( Q_{2n+2} \) is introduced by
\[
Q_{2n+2} = \sum_{j=0}^n \left( \begin{array}{cc} -g_{2j+2} & f_{2j+1} \\ -h_{2j+1} & g_{2j+2} \end{array} \right) M^{n-j} + \left( \begin{array}{cc} \frac{1}{2}g_{2n+2} & 0 \\ 0 & -\frac{1}{2}g_{2n+2} \end{array} \right), \quad n \in \mathbb{N}_0, \quad (2.26)
\]
Using the recursion relations (2.17)-(2.21), we rewrite the commutator of \( Q_{2n+2} \) and \( M \) as
\[
[Q_{2n+2}, M] = [Q_{2n+2}, M]|_{\ker(M-z^2)} = \left( \begin{array}{cc} -\frac{1}{2}g_{2n+2,x} & -2f_{2n+3} + qg_{2n+2} \\ -2h_{2n+3} - rg_{2n+2} & \frac{1}{2}g_{2n+2,x} \end{array} \right), \quad n \in \mathbb{N}_0, \quad (2.27)
\]
where
\[
\ker(M-z^2) = \{ \Psi = \left( \begin{array}{c} \psi_1 \\ \psi_2 \end{array} \right) : \mathbb{R} \to \mathbb{C}_\infty^2 | (M-z^2)\Psi = 0 \}, \quad z \in \mathbb{C}, \quad (2.28)
\]
denotes the two-dimensional kernel of \( M-z^2 \). The stationary GI hierarchy can be constructed in terms of the vanishing of the commutator of \( Q_{2n+2} \) and \( M \) in (2.27), that is,
\[
[Q_{2n+2}, M] = 0, \quad n \in \mathbb{N}_0, \quad (2.29)
\]
or equivalently,
\[
\left( \begin{array}{cc} -\frac{1}{2}g_{2n+2,x} & -2f_{2n+3} + qg_{2n+2} \\ -2h_{2n+3} - rg_{2n+2} & \frac{1}{2}g_{2n+2,x} \end{array} \right) = 0, \quad n \in \mathbb{N}_0. \quad (2.30)
\]
From $2f_{2n+3} - qg_{2n+2} = 0$ and $2h_{2n+3} + rg_{2n+2} = 0$, we get

$$2rf_{2n+3} - qrg_{2n+2} = 0, \quad 2qh_{2n+3} + qrg_{2n+2} = 0,$$

(2.31)

that is,

$$2(rf_{2n+3} +qh_{2n+3}) = 0,$$

(2.32)

which implies $\frac{1}{2}g_{2n+2,x} = 0$. Thus, varying $n \in \mathbb{N}_0$, stationary GI hierarchy (2.30) can be written as

$$s\text{-GI}_n(q,r) = \left( \frac{2f_{2n+3} - qg_{2n+2}}{2h_{2n+3} - rg_{2n+2}} \right) = 0, \quad n \in \mathbb{N}_0.$$

(2.33)

Explicitly,

$$s\text{-GI}_0(q,r) = \left( \frac{-2q_x + 2c_1 q}{2r_x + 2c_1 r} \right) = 0,$$

$$s\text{-GI}_1(q,r) = \left( \frac{q_{xx} + q_{xx}r + c_1(-2q_x) + 2c_2 q}{r_{xx} - q r r_x + 2c_1 r_x + 2c_2 r} \right) = 0,$$

$$s\text{-GI}_2(q,r) = \left( \frac{-\frac{1}{2}q_{xxx} - \frac{3}{2} q_{xxx}r - \frac{3}{4} q^2 r^2 q_x - \frac{9}{4} q^2 r^2}{2r_{xxx} - 4 q r_{xx} + \frac{4}{3} q^2 r^2 x - \frac{9}{2} q^2 r^2} \right) + c_1 \left( \frac{q_{xx} + q_{xx}r}{r_{xx} - 2 q r r_x} \right) + c_2 \left( \frac{-2q_x}{2r_x} \right) + c_3 \left( \frac{2q}{2r} \right) = 0, \quad \text{etc.},$$

represent the first few equations of the stationary GI hierarchy.

In the following we shall frequently make the assumption that $q, r$ satisfy the $n$th stationary GI equations, that is, they satisfy one of the $n$th stationary GI equations after a particular choice of integration constants $c_\ell \in \mathbb{C}, \ell = 1, \ldots, n + 1, n \in \mathbb{N}_0$.

Next we introduce polynomials $F_{2n+1}$, $G_{2n+2}$ and $H_{2n+1}$ with respect to the spectral parameter $z \in \mathbb{C},$

$$F_{2n+1}(z) = \sum_{\ell=0}^{n} f_{2\ell+1} z^{2(n-\ell)+1},$$

(2.34)

$$G_{2n+2}(z) = \sum_{\ell=0}^{n} g_{2\ell} z^{2(n-\ell)+2} + \frac{1}{2} g_{2n+2},$$

(2.35)

$$H_{2n+1}(z) = \sum_{\ell=0}^{n} h_{2\ell+1} z^{2(n-\ell)+1},$$

(2.36)
and corresponding homogeneous polynomials
\[
\hat{F}_0(z) = F_0(z) = 2q,
\]
\[
\hat{F}_{2\ell+1}(z) = F_{2\ell+1}(z)|_{c_k = 0, k = 1, \ldots, \ell} = \sum_{k=0}^{\ell} \hat{f}_{2k+1} z^{2(\ell-k)+1}, \quad \ell \in \mathbb{N},
\]
\[
\hat{G}_0(z) = G_0(z) = 2,
\]
\[
\hat{G}_{2\ell+2}(z) = G_{2\ell+2}(z)|_{c_k = 0, k = 1, \ldots, \ell+1} = \sum_{k=0}^{\ell} \hat{g}_{2k} z^{2(\ell-k)+2} + \frac{1}{2} \hat{g}_{2n+2}, \quad \ell \in \mathbb{N},
\]
\[
\hat{H}_0(z) = H_0(z) = -2r,
\]
\[
\hat{H}_{2\ell+1}(z) = H_{2\ell+1}(z)|_{c_k = 0, k = 1, \ldots, \ell} = \sum_{k=0}^{\ell} \hat{h}_{2k+1} z^{2(\ell-k)+1}, \quad \ell \in \mathbb{N}.
\]

Noting (2.17)-(2.21), one finds (2.29), or equivalently, (2.33) becomes
\[
\tilde{G}_{2n+2} = r \tilde{F}_{2n+1} + q \tilde{H}_{2n+1}, \quad (2.37)
\]
\[
\tilde{F}_{2n+1} = 2q z \tilde{G}_{2n+2} - (2z^2 - \frac{1}{2} \tilde{g} \tilde{r}) \tilde{F}_{2n+1}, \quad (2.38)
\]
\[
\tilde{H}_{2n+1} = 2r z \tilde{G}_{2n+2} + (2z^2 - \frac{1}{2} \tilde{g} \tilde{r}) \tilde{H}_{2n+1}, \quad (2.39)
\]

if we identifying \( \tilde{q}, \tilde{r} \) with \(-q, -r\), respectively. Here
\[
\tilde{F}_{2n+1}(z) = \sum_{\ell=0}^{n} \tilde{f}_{2\ell+1} z^{2(\ell-n)+1}, \quad (2.40)
\]
\[
\tilde{G}_{2n+2}(z) = \sum_{\ell=0}^{n} \tilde{g}_{2\ell} z^{2(\ell-n)+2} + \frac{1}{2} \tilde{g}_{2n+2}, \quad (2.41)
\]
\[
\tilde{H}_{2n+1}(z) = \sum_{\ell=0}^{n} \tilde{h}_{2\ell+1} z^{2(\ell-n)+1}, \quad (2.42)
\]

and \( \{ \tilde{f}_{2\ell+1} \}_{\ell=0, \ldots, n}, \{ \tilde{g}_{2\ell} \}_{\ell=0, \ldots, n+1}, \{ \tilde{h}_{2\ell+1} \}_{\ell=0, \ldots, n} \) satisfy the same recursion relations as \( \{ f_{2\ell+1} \}_{\ell=0, \ldots, n}, \{ g_{2\ell} \}_{\ell=0, \ldots, n+1}, \{ h_{2\ell+1} \}_{\ell=0, \ldots, n} \) in (2.17)-(2.21), that
is,
\[ \tilde{g}_{2 \ell + 1} = \tilde{f}_{2 \ell} = \tilde{h}_{2 \ell} = 0, \quad \ell \in \mathbb{N}_0, \quad (2.43) \]
\[ f_1 = 2 \tilde{q}, \quad \tilde{g}_0 = 2, \quad \tilde{h}_1 = -2 \tilde{r}, \quad (2.44) \]
\[ 2 \tilde{f}_{2 \ell + 1} = -\tilde{f}_{2 \ell - 1} + x + 2 \tilde{q} \tilde{g}_{2 \ell} + (1/2) \tilde{q} \tilde{r} \tilde{f}_{2 \ell - 1}, \quad \ell \in \mathbb{N}_0, \quad (2.45) \]
\[ 2 \tilde{h}_{2 \ell + 1} = \tilde{h}_{2 \ell - 1} - 2 \tilde{r} \tilde{g}_{2 \ell} + (1/2) \tilde{q} \tilde{r} \tilde{h}_{2 \ell - 1}, \quad \ell \in \mathbb{N}_0, \quad (2.46) \]
\[ \tilde{g}_{2 \ell} \tilde{x} = \tilde{r} \tilde{f}_{2 \ell + 1} + \tilde{q} \tilde{h}_{2 \ell + 1}, \quad \ell \in \mathbb{N}_0. \quad (2.47) \]

Moreover, (2.37)-(2.39) yield
\[ (\tilde{G}_{2n+2}^2 - \tilde{F}_{2n+1} \tilde{H}_{2n+1}) x = 0, \quad (2.48) \]
which implies \( \tilde{G}_{2n+2}^2 - \tilde{F}_{2n+1} \tilde{H}_{2n+1} \) is \( x \)-independent and hence
\[ \tilde{G}_{2n+2}^2 - \tilde{F}_{2n+1} \tilde{H}_{2n+1} = R_{4n+4}, \quad (2.49) \]
where the integration constant \( R_{4n+4} \) is a polynomial of degree \( 4n + 4 \) with respect to \( z \). Let \( \{ E_m^2 \}_{m=0,\ldots,2n+1} \) be its zeros, then
\[ R_{4n+4}(z) = 4 \prod_{m=0}^{2n+1} (z^2 - E_m^2), \quad \{ E_m^2 \}_{m=0,\ldots,2n+1} \in \mathbb{C}. \quad (2.50) \]

Next we study the restriction of the differential expression (2.28) to the two-dimensional kernel of \( M - z^2 \). More precisely, (2.26) implies
\[ Q_{2n+2}|_{\ker(M-z^2)} = \left( \begin{array}{cc} -G_{2n+2} & F_{2n+1} \\ -H_{2n+2} & G_{2n+2} \end{array} \right) \bigg|_{\ker(M-z^2)}. \quad (2.51) \]

We emphasize that the result (2.51) is valid independently of whether or not \( Q_{2n+2} \) and \( M \) commute. However, if one makes the additional assumption \( Q_{2n+2} \) and \( M \) commute, we can prove that there exists an algebraic relationship between \( Q_{2n+2} \) and \( M \) and this relation will be shown in the following results.

**Theorem 2.2.** Assume that \( Q_{2n+2} \) and \( M \) commute, \( [Q_{2n+2}, M] = 0 \), or equivalently, suppose \( sGI_n(q, r) = 0 \) for some fixed \( n \in \mathbb{N}_0 \). Then \( M \) and \( Q_{2n+2} \) satisfy an algebraic relationship of type
\[ F_n(M, Q_{2n+2}) = Q_{2n+2}^2 - R_{4n+4}(M) = 0, \]
\[ R_{4n+4} = 4 \prod_{m=0}^{2n+1} (z^2 - E_m^2), \quad z \in \mathbb{C}. \quad (2.52) \]

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Proof. From the commutativity of $Q_{2n+2}$ and $M$, the definition of $R_{4n+4}$ \eqref{2.49} and the relations
\[
\tilde{G}_{2n+2} = G_{2n+2}, \quad \tilde{F}_{2n+1} = -F_{2n+1}, \quad \tilde{H}_{2n+1} = -H_{2n+1},
\]
as well as the expression for $Q_{2n+2}$ on the kernel of $M - z^2 \ 	ext{\eqref{2.51}}$, one infers
\[
Q^2_{2n+2}|_{\ker(M - z^2)} = \begin{pmatrix} 0 & G^2_{2n+2} - F_{2n+1}H_{2n+1} \\ G^2_{2n+2} - F_{2n+1}H_{2n+1} & 0 \end{pmatrix}|_{\ker(M - z^2)}
\]
\[
= \begin{pmatrix} R_{4n+4} & 0 \\ 0 & R_{4n+4} \end{pmatrix}|_{\ker(M - z^2)}
\]
\[
= R_{4n+4}(M)|_{\ker(M - z^2)}. 
\]
Thus, $Q^2_{2n+2}$ and $R_{4n+4}$ coincide on $\ker(M - z^2)$. Since $z^2 \in \mathbb{C}^2$ is arbitrary, we finally obtain \eqref{2.52}. 

One calls $\mathcal{F}_n(M, Q_{2n+2})$ the Burchnall-Chaundy polynomial of the pair $[M, Q_{2n+2}]$. The relation \eqref{2.52} naturally leads to the hyperelliptic curve $\mathcal{K}_n$, where
\[
\mathcal{K}_n : \mathcal{F}_n(z, y) = y^2 - R_{4n+4}(z) = 0,
\]
\[
R_{4n+4}(z) = \prod_{m=0}^{2n+1} (z^2 - E_m^2), \quad \{E_m^2\}_{m=0,...,2n+1} \in \mathbb{C}. \tag{2.53}
\]

Next section we introduce the notations $\eta = z^2$, $\tilde{E}_m = E_m^2$, \eqref{2.53} changes to the hyperelliptic curve of arithmetic genus $n \in \mathbb{N}_0$ (possibly with a singular affine part), where
\[
\mathcal{K}_n : \mathcal{F}_n(\eta, y) = y^2 - R_{4n+4}(\eta) = 0,
\]
\[
R_{4n+4}(\eta) = \prod_{m=0}^{2n+1} (\eta - \tilde{E}_m), \quad \{\tilde{E}_m\}_{m=0,...,2n+1} \in \mathbb{C}. \tag{2.54}
\]

Next we introduce the time-dependent GI hierarchy. This means that $q, r$ are now considered an functions of both space and time. For each equation in the hierarchy, that is, for each $n$, we introduce a deformation parameter $t_n \in \mathbb{R}$ in $q$ and $r$, replacing $q(x), r(x)$ by $q(x, t_n)$, $r(x, t_n)$. The matrix differential expression $M$ now becomes
\[
M = \begin{pmatrix} \partial + \frac{1}{4}q(\cdot, t_n)r(\cdot, t_n) & -zq(\cdot, t_n) \\ -zr(\cdot, t_n) & -\partial + \frac{1}{4}q(\cdot, t_n)r(\cdot, t_n) \end{pmatrix}. \tag{2.55}
\]
The quantities \( \{f_{2\ell+1}\}_{\ell \in \mathbb{N}_0}, \{g_{2\ell}\}_{\ell \in \mathbb{N}_0} \) and \( \{h_{2\ell+1}\}_{\ell \in \mathbb{N}_0} \) and \( Q_{2n+2}, n \in \mathbb{N} \), are still defined by (2.17)-(2.21) and (2.26), respectively. The time-dependent GI hierarchy is obtained by imposing the Lax commutator equations

\[
\frac{d}{dt}(-M) - [-Q_{2n+2}, -M] = 0, \quad t_n \in \mathbb{R},
\]

or equivalently,

\[
\begin{pmatrix}
-\frac{1}{4}(qr)_{t_n} + \frac{1}{2}g_{2n+2,x} & q_{t_n} - 2f_{2n+3} + qg_{2n+2} \\
-r_{t_n} + 2h_{2n+3} + rg_{2n+2} & \frac{1}{4}(qr)_{t_n} + \frac{1}{2}g_{2n+2,x}
\end{pmatrix} = 0. \tag{2.57}
\]

From (2.57), we obtain

\[
\frac{1}{4}(qr)_{t_n} = \frac{1}{4}(rq_{t_n} + qr_{t_n}) = \frac{1}{4}r(2f_{2n+3} - qg_{2n+2}) + q(2h_{2n+3} + rg_{2n+2}) = \frac{1}{4}g_{2n+2,x},
\]

that is,

\[
\frac{1}{2}g_{2n+2,x} - \frac{1}{4}(qr)_{t_n} = 0. \tag{2.58}
\]

Thus, varying \( n \), the time-dependent GI hierarchy can be written as

\[
\text{GI}_n(q,r) = \begin{pmatrix}
q_{t_n} - 2f_{2n+3} + qg_{2n+2} \\
r_{t_n} - 2h_{2n+3} - rg_{2n+2}
\end{pmatrix} = 0, \quad t_n \in \mathbb{R}, \quad n \in \mathbb{N}_0. \tag{2.59}
\]

Explicitly,

\[
\begin{align*}
\text{GI}_0(q,r) &= \begin{pmatrix}
q_0 + 2q_x - 2c_1 q \\
r_0 + 2r_x + 2c_1 r
\end{pmatrix} = 0, \\
\text{GI}_1(q,r) &= \begin{pmatrix}
q_1 - q_{xx} - q_{xx}r + 2c_1 q_x - 2c_2 q \\
r_1 + r_{xx} - qr_{xx} + 2c_1 r_x + 2c_2 r
\end{pmatrix} = 0, \\
\text{GI}_2(q,r) &= \begin{pmatrix}
q_2 + \frac{1}{2}q_{xxx} + \frac{3}{2}q_{xx}r + \frac{3}{2}q_{x}r^2 - \frac{3}{2}q_{x}r^2 + \frac{3}{2}q_{x}r^2 \\
r_2 + \frac{1}{2}r_{xxx} - \frac{3}{2}q_{xx}r + \frac{3}{2}q_{x}r^2 - \frac{3}{2}q_{x}r^2
\end{pmatrix} + c_1 \begin{pmatrix}
-q_{xx} - q_{xx}r \\
r_{xx} - 2q_{xx}r
\end{pmatrix} + c_2 \begin{pmatrix}
2q_x \\
2r_x
\end{pmatrix} + c_3 \begin{pmatrix}
-2q \\
2r
\end{pmatrix} = 0, \quad \text{etc.,}
\end{align*}
\]

are the first few equations of the time-dependent GI hierarchy. The system of equation \( \text{GI}_1(q,r) = 0 \) with \( c_1 = c_2 = 0 \) represents the GI system.
Remark 2.3. An alternative construction of the GI hierarchy can be introduced by developing its zero-curvature formalism. One defines

\[ U(z) = \begin{pmatrix} -z^2 + \frac{1}{4}qr & qz \\ rz & z^2 - \frac{1}{4}qr \end{pmatrix}, \quad z \in \mathbb{C}, \quad (2.60) \]

\[ V_{2n+2}(z) = \begin{pmatrix} -G_{2n+2}(z) & F_{2n+1}(z) \\ -H_{2n+2}(z) & G_{2n+2}(z) \end{pmatrix}, \quad n \in \mathbb{N}_0, \quad (2.61) \]

where \( G_{n+1}, F_n, H_n \) are polynomials defined in \((2.34)-(2.36)\). Hence, the stationary part of this section, being a consequence of \([Q_{2n+2}, M] = 0\), can equivalently be based on the stationary zero-curvature equation

\[ 0 = -V_{2n+2, x}(z) + [U(z), V_{2n+2}(z)] \]

\[ = \begin{pmatrix} G_{2n+2, x} - zG_{2n+1, x} - qrH_{2n+1} & F_{2n+1, x} + 2rzG_{2n+2} + (-2z^2 + \frac{1}{4}qr)H_{2n+1} \\ H_{2n+1, x} - 2rzG_{2n+2} + (-2z^2 + \frac{1}{4}qr)H_{2n+1} & -G_{2n+2, x} + qrF_{2n+1} + qzH_{2n+1} \end{pmatrix} \]

\[ = \begin{pmatrix} \frac{1}{2}g_{2n+2, x} & (-qg_{2n+2} + 2f_{2n+2})z \\ (rg_{2n+2} + 2h_{2n+3})z & -\frac{1}{2}g_{2n+2, x} \end{pmatrix} \quad (2.62) \]

In particular, the hyperelliptic curve \( K_n \) can also be obtained from the characteristic equation of \( V_{2n+2} \) by

\[ \det(yI_2 - V_{2n+2}(z)) = y^2 - \det(V_{2n+2}) \]

\[ = y^2 - G_{2n+2}(z) + F_{2n+1}(z)H_{2n+1}(z) \]

\[ = y^2 - \mathcal{R}_{4n+4}(z) = 0. \quad (2.63) \]

Similarly, the time-dependent part \((2.56), (2.57), (2.59)\), being based on the Lax equation \((2.50)\), can equivalently developed from the zero-curvature equation

\[ 0 = U_{tn} - V_{2n+2, x} + [U, V_{2n+2}] \]

\[ = \begin{pmatrix} (qr)_{tn} + G_{2n+2, x} - zrF_{2n+1, x} - qzH_{2n+1} & qz_{tn} - F_{2n+1, x} + 2rzG_{2n+2} + (-2z^2 + \frac{1}{4}qr)H_{2n+1} \\ r_{tn} + H_{2n+1, x} - 2rzG_{2n+2} + (-2z^2 + \frac{1}{4}qr)H_{2n+1} & -(qr)_{tn} - G_{2n+2, x} + qrF_{2n+1} + qzH_{2n+1} \end{pmatrix} \]

\[ = \begin{pmatrix} (qr)_{tn} + \frac{1}{2}g_{2n+2, x} & (q_{tn} - qg_{2n+2} + 2f_{2n+2})z \\ (r_{tn} + rg_{2n+2} + 2h_{2n+3})z & -(qr)_{tn} - \frac{1}{2}g_{2n+2, x} \end{pmatrix}. \quad (2.64) \]

Relations between the mKP hierarchy and the GI hierarchy can be summarized as follows.

**Theorem 2.1** (see \([5]\) or \([31]\)). Assume \( q, r \) is a compatible solution of the system

\[ \widehat{GI}_1(q, r) = 0, \quad (2.65) \]

\[ \widehat{GI}_p(q, r) = 0, \quad p \geq 2, \quad (2.66) \]
where we denote by
\[ \hat{G}_n(q, r) = G_n(q, r)|_{c_k=0, k=1, \ldots, n+1}, \quad n \in \mathbb{N}_0, \] (2.67)
the corresponding homogeneous GI equations. Then
\[ u(x, y, t) = -2^{p-1}q(-2x, y, (-2)^{p-1}t) \]
yields a solution of the pth KP equation.

Given these preparations, next we shall study the algebro-geometric solutions of the KP hierarchy. Now \( q, r \) are considered as functions of variables \( x, y, t_1, t_p \) with \( t_1 = y \). Then we introduce the following auxiliary linear problem
\[
\begin{align*}
\psi_x(z) &= U(z) \psi(z), \\
\psi_y(z) &= \hat{V}_4(z) \psi(z), \\
\psi_{t_2}(z) &= \hat{V}_{2p+2}(z) \psi(z), \quad z \in \mathbb{C}, \quad p \geq 2,
\end{align*}
\] (2.69)
where
\[ \hat{V}_{2k+2}(z) = V_{2k+2}(z)|_{c_\ell=0, \ell=1, \ldots, k+1}, \]
and \( \psi(z) = (\psi_1(z, x, y, t_p), \psi_2(z, x, y, t_p))^T \). Let
\[ \psi^\pm(z) = (\psi^\pm_1(z, x, y, t_p), \psi^\pm_2(z, x, y, t_p)) \]
be two fundamental solutions of linear system (2.69) and three squared basis functions \( \mathcal{G}, \mathcal{F}, \mathcal{H} \) can be defined in term of \( \psi^\pm_1(z), \psi^\pm_2(z) \) by
\[
\begin{align*}
\mathcal{G}(z, x, y, t_p) &= \frac{1}{2}(\psi^+_1(z, x, y, t_p)\psi^-_2(z, x, y, t_p) \\
&\quad + \psi^-_1(z, x, y, t_p)\psi^+_2(z, x, y, t_p)), \\
\mathcal{F}(z, x, y, t_p) &= \psi^+_1(z, x, y, t_p)\psi^-_1(z, x, y, t_p), \\
\mathcal{H}(z, x, y, t_p) &= \psi^+_2(z, x, y, t_p)\psi^-_2(z, x, y, t_p).
\end{align*}
\]

\[ ^1 \text{One can also start from the following linear problems} \]
\[
\begin{align*}
\psi_x(z) &= U(z) \psi(z), \\
\psi_{t_m}(z) &= \hat{V}_{2m+2}(z) \psi(z), \quad z \in \mathbb{C}, \quad m = 1, 2, 3, \ldots
\end{align*}
\] (2.68)
where \( q, r \) are considered as functions of \( x, y, t_2, \ldots \) and obtain similar results.
Using (2.60), (2.61) and (2.69), we derive the following linear system

\begin{align}
G_x &= rz \mathcal{F} + qz \mathcal{H}, \quad (2.70) \\
G_y &= \hat{F}_3 \mathcal{H} - \hat{H}_3 \mathcal{F}, \quad (2.71) \\
G_{tp} &= \hat{F}_{2p+1} \mathcal{H} - \hat{H}_{2p+1} \mathcal{F}, \quad (2.72) \\
F_x &= 2qz \mathcal{G} + \left( -2z^2 + \frac{1}{2}qr \right) \mathcal{F}, \quad (2.73) \\
F_y &= 2\hat{F}_3 \mathcal{G} - 2\hat{G}_4 \mathcal{F}, \quad (2.74) \\
F_{tp} &= 2\hat{F}_{2p+1} \mathcal{G} - 2\hat{G}_{2p+2} \mathcal{F}, \quad (2.75) \\
H_x &= 2rz \mathcal{G} + \left( 2z^2 - \frac{1}{2}qr \right) \mathcal{H}, \quad (2.76) \\
H_y &= 2\hat{G}_4 \mathcal{G} - 2\hat{H}_3 \mathcal{F}, \quad (2.77) \\
H_{tp} &= 2\hat{G}_{2p+2} \mathcal{H} - 2\hat{H}_{2p+1} \mathcal{F}. \quad (2.78)
\end{align}

For each fixed \( p \), solutions of linear system (2.70)-(2.78) are connected with the following basic initial value problem of GI system (2.80).

**Theorem 2.1.** Assume \( q, r \in C^\infty(\mathbb{R}^{2+1}) \). Moreover, if \((q, r)\) solves (2.65), (2.66), then the set

\[ \mathcal{E} = \text{span}\{(G, F, H) | (G_{2j+2}, F_{2j+1}, H_{2j+1}), \; j \in \mathbb{N}_0\} \quad (2.79) \]

forms a vector space on \( \mathbb{C} \) for solutions of the system (2.70)-(2.78). In particular, the functions \( q, r \) which constituting \((G_{2n+2}, F_{2n+1}, H_{2n+1}), \; n \in \mathbb{N}_0\), are connected with solutions of the following initial problem

\[
\begin{align*}
q_y &= -2f_5 + qg_4, \\
r_y &= -2h_5 - rg_4, \\
q_{tp} &= -2f_{2p+3} + qg_{2p+2}, \\
r_{tp} &= -rg_{2p+2} - 2h_{2p+3}, \\
2f_{2n+3} - qg_{2n+2} &= 0, \\
r_{2n+2} + 2h_{2n+3} &= 0, \quad p \geq 2.
\end{align*}
\]

**Proof.** It is not difficult to verify that (2.80) is equivalent to the following zero curvature representation

\[
\frac{\partial}{\partial x} V_{2j+2}(z) - \frac{\partial}{\partial t_j} U(z) = [U(z), V_{2j+2}(z)], \; j = 2, p, n, \quad (2.81)
\]
from remark 2.3. Next we shall show

\[
[V_{2j+2}(z) + \frac{\partial}{\partial t_j}, V_{2k+2}(z) + \frac{\partial}{\partial t_k}] = 0, \quad j, k = 2, p,
\]

\[
[V_{2j+2}(z) + \frac{\partial}{\partial t_j}, V_{2n+2}(z)] = 0, \quad j = 2,
\]

which can be proved as follows. First, taking into account the \(2 \times 2\) matrix-valued differential expression

\[
M = \begin{pmatrix}
\partial + \frac{1}{4} qr & -z q \\
z r & -\partial + \frac{1}{4} qr
\end{pmatrix},
\]

\[
Q_{2n+2} = \sum_{j=0}^{n} \begin{pmatrix}
-g_{2\ell} z^2 & f_{2\ell+1} z \\
-h_{2\ell+1} z & g_{2\ell+2} z^2
\end{pmatrix} M^{n-\ell} + \begin{pmatrix}
\frac{1}{2} g_{2n+2} & 0 \\
0 & -\frac{1}{2} g_{2n+2}
\end{pmatrix},
\]

\(n \in \mathbb{N}_0, \quad f_{-1} = h_{-1} = 0\),

one infers (2.81) is also equivalent to

\[
[Q_{2j+2} + \frac{\partial}{\partial t_j}, M] = 0, \quad j = 2, p,
\]

\[
[Q_{2n+2}, M] = 0.
\]

Then by Corollary 2 of Theorem 4.2 in [34] it follows

\[
[Q_{2j+2} + \frac{\partial}{\partial t_j}, Q_{2k+2} + \frac{\partial}{\partial t_k}] = 0, \quad j, k = 2, p,
\]

\[
[Q_{2j+2} + \frac{\partial}{\partial t_j}, Q_{2n+2}] = 0, \quad j = 2, p,
\]

and hence

\[
[V_{2j+2}(z) + \frac{\partial}{\partial t_j}, V_{2k+2}(z) + \frac{\partial}{\partial t_k}] = [Q_{2j+2} + \frac{\partial}{\partial t_j}, Q_{2k+2} + \frac{\partial}{\partial t_k}]|_{\ker(M - z)} = 0, \quad j, k = 2, p,
\]

\[
[V_{2j+2}(z) + \frac{\partial}{\partial t_j}, V_{2n+2}(z)] = [Q_{2j+2} + \frac{\partial}{\partial t_j}, Q_{2n+2}]|_{\ker(M - z)} = 0, \quad j = 2, p,
\]

holds, where

\[
\ker(M - z) = \{ \Psi = \begin{pmatrix} \psi_1 \\ \psi_2 \end{pmatrix} : \mathbb{R}^{2+1} \to \mathbb{C}^2 | (M - z)\Psi = 0 \}, \quad z \in \mathbb{C}.
\]

**Remark 2.2.** This proposition can also be proved by introducing a meromorphic function \(\phi\) and considering \(q, r\) as functions of three variables \(x, y, t_p\) (see [50], Lemma 5.3).
3 Spectral Curve, Dubrovin-type Equations and Trace Formula

In the following, we shall introduce the spectral curve associated with mKP hierarchy. To emphasize the difference between different solutions in (2.79), we add a subscript in each of $G$, $F$, $H$, that is,

$$(G_{2n+2}, F_{2n+1}, H_{2n+1}) = (G_{2n+2}, F_{2n+1}, H_{2n+1}), \ n \in \mathbb{N}.$$ 

Then using (2.70)-(2.78) and theorem 2.1, we have

$$(G_{2n+2}^2 - F_{2n+1} H_{2n+1})_{t_j} = 0, \ n \in \mathbb{N}, \ j = 1, 2, p, \quad (3.1)$$

and hence $G_{n+1}^2 - F_n H_n$ is $x, y, t_p$-independent implying

$$G_{2n+2}^2 - F_{2n+1} H_{2n+1} = R_{4n+4}, \ n \in \mathbb{N}, \quad (3.2)$$

where integration constant $R_{4n+4}$ is a polynomial of degree $4n+4$ in $z$. Let

$$R_{4n+4}(z) = \sum_{j=0}^{2n+2-j} (-1)^j s_j z^{2n+2-j},$$

$$s_0 = 4, \ s_j \in \mathbb{C}, \ j = 1, \ldots, 2n, \quad (3.3)$$

and hyperelliptic curve associated with the $p$th mKP equation is then introduced as follows:

$$X : \mathcal{P}(\eta, y) = y^2 - \frac{1}{4} R_{4n+4}(\sqrt{\eta}) = y^2 - \frac{1}{4} G_{2n+2}^2(\sqrt{\eta}) + \frac{1}{4} F_{2n+1}(\sqrt{\eta}) H_{2n+1}(\sqrt{\eta}) = 0. \quad (3.4)$$

The curve $X$ is compactified by joining two points $P_{\infty \pm}$ at infinity but for notational simplicity the compactification is also denoted by $X$. Points $P$ on $X \setminus \{P_{\infty \pm}\}$ are denote by pairs $(\eta, y)$, where $y(\cdot)$ is the meromorphic function on $X$ satisfying $\mathcal{P}(\eta, y) = 0$. The complex structure on $X$ is defined in the usual way. Hence, $X$ becomes a two-sheeted hyperelliptic Riemann surface of (arithmetic) genus $n$ in a standard manner. Moreover, we denote the upper and lower sheets $\Pi_{\pm}$ by

$$\Pi_{\pm} = \{(\eta, \pm \frac{1}{2} \sqrt{R_{4n+4}(\sqrt{\eta})}) \in X| \eta \in \Pi\},$$
where $\Pi$ denotes the cut plane $\mathbb{C}\setminus \mathcal{C}$ and $\mathcal{C}$ is the union of $n$ nonintersecting cuts joining two different branches of $\sqrt{\mathbb{R}_{4n+4}(\sqrt{\eta})}$. The holomorphic sheet exchange map on $X$ is defined by

$$
*: \quad X \rightarrow X,
$$

$$
P = (\eta, \frac{1}{2}\sqrt{\mathbb{R}_{4n+4}(\eta)}) \mapsto P^* = (\eta, -\frac{1}{2}\sqrt{\mathbb{R}_{4n+4}(\sqrt{\eta})}),
$$

$$
P_{\infty \pm} \mapsto P_{\infty \pm}^* = P_{\infty \mp}.
$$

Moreover, positive divisors on $X$ of degree $n$ are denoted by

$$
\mathcal{D}_{P_1, \ldots, P_n}: \quad \begin{cases} 
X \rightarrow \mathbb{N}_0, \\
P \rightarrow \mathcal{D}_{P_1, \ldots, P_n}(P) = \begin{cases} 
k & \text{if } P \text{ occurs } k \text{ times in } \{P_1, \ldots, P_n\}, \\
0 & \text{if } P \notin \{P_1, \ldots, P_n\}.
\end{cases}
\end{cases}
$$

(3.5)

In particular, the divisor $(\phi(\cdot))$ of a meromorphic function $\phi(\cdot)$ on $X$ is defined by

$$
(\phi(\cdot)): \quad X \rightarrow \mathbb{Z}, \quad P \mapsto \omega_\phi(P),
$$

(3.6)

where $\omega_\phi(P) = m_0 \in \mathbb{Z}$ if $(\phi \circ \zeta_P^{-1})(\zeta) = \sum_{n=m_0}^{\infty} c_n(P)\zeta^n$ for some $m_0 \in \mathbb{Z}$ by using a chart $(U_P, \zeta_P)$ near $P \in X$. Finally, we introduce symmetric functions of $x_1, \ldots, x_n$

$$
\Psi_0(\underline{x}) = 1, \quad \Psi_1(\underline{x}) = \sum_{j=1}^{n} x_j, \quad \Psi_2(\underline{x}) = \sum_{j,k=1, j<k}^{n} x_jx_k, \quad \Psi_3(\underline{x}) = \sum_{j,k,\ell=1, j<k<\ell}^{n} x_jx_kx_\ell, \quad \text{etc.,}
$$

(3.7)

where

$$
\underline{x} = (x_1, \ldots, x_n).
$$

Now we turn to the parameter representations of $\mathcal{G}_{2n+2}, \mathcal{F}_{2n+1}, \mathcal{H}_{2n+1}$, which are described by the evolution of auxiliary spectrum points $\mu_j(x, y, t_p)$, $\nu_j(x, y, t_p), j = 1, \ldots, n$. This procedure is standard, which is similar with 1+1 dimensional case.
Theorem 3.1. Solutions of (2.70)-(2.78) can also be expressed as

\[ G_{2n+2} = \sum_{j=0}^{n+1} (-1)^j \dot{g}_j(x, y, t_p) z^{2n+2-2j}, \]

\[ F_{2n+1} = 2q(x, y, t_p) z \prod_{j=1}^{n} (z^2 - \mu_j(x, y, t_p)), \quad (3.8) \]

\[ H_{2n+1} = -2r(x, y, t_p) z \prod_{j=1}^{n} (z^2 - \nu_j(x, y, t_p)), \]

where

\[ \dot{g}_0 = 2, \]

\[ \dot{g}_2 = qr + \frac{s_1}{4}, \quad (3.9) \]

\[ \dot{g}_{2j} = \frac{1}{4} \left[ -\sum_{\nu=1}^{j-1} \dot{g}_\nu \dot{g}_{j-\nu} - 4qr \sum_{\alpha+\beta=j} \Psi_\alpha(\mu) \Psi_{j-\beta}(\nu) + s_j \right], \quad s = 2, \ldots, n+1, \]

and \( \{\mu_j(x, y, t_p)\}_{j=1}^{n} \), \( \{\nu_j(x, y, t_p)\}_{j=1}^{n} \) are \( n \) roots of \( F_{2n+1}, H_{2n+1} \), respectively. Moreover, if \( \{\mu_j(x, y, t_p)\}_{j=1}^{n} \) are mutually distinct and finite, then they satisfy the Dubrovin-type equations

\[ \mu_{j,x} = \frac{\sqrt{\mu_j} \mathcal{R}_{4n+4}(\sqrt{\mu_j})}{\prod_{k \neq j}(\mu_j - \mu_k)}, \quad (3.10) \]

\[ \mu_{j,y} = -\frac{\hat{F}_5(\sqrt{\mu_j}) \sqrt{\mathcal{R}_{4n+4}(\sqrt{\mu_j})}}{q \prod_{k \neq j}(\mu_j - \mu_k)}, \quad (3.11) \]

\[ \mu_{j,t_p} = -\frac{\hat{F}_{2p+1}(\sqrt{\mu_j}) \sqrt{\mathcal{R}_{4n+4}(\sqrt{\mu_j})}}{q \prod_{k \neq j}(\mu_j - \mu_k)}, \quad (3.12) \]

and similar statement is also true for \( \{\nu_j(x, y, t_p)\}_{j=1}^{n} \), where (3.10)-(3.12)
Finally, \( q, r \) and \( \mu_j, \nu_j \) are connected by the following trace formula

\[
\sum_{j=1}^{n} \mu_j = \frac{1}{4} qr + \frac{1}{2} q_x + \frac{s_1}{8},
\]

\[
\sum_{j=1}^{n} \nu_j = \frac{1}{4} qr - \frac{1}{2} r_x + \frac{s_1}{8}.
\]

(3.16)

**Proof.** First, insertion of (3.8) into (3.2), (3.3) and a comparison powers of \( z \) yields (3.9). Then by (2.73), (2.74), (2.75), (2.76), (2.77) and (2.78), taking into account (3.4), (3.8), one derives (3.10)-(3.15). Moreover, combining (2.35) with (3.9) yields

\[
c_1 = -\frac{1}{8} s_1.
\]

(3.17)

Finally, the formula (3.16) is the direct result of (3.8), (3.17) and theorem 2.1.

## 4 Baker-Akhiezer Function

It is well known that the Baker-Akhiezer function plays a very important role in finite gap integration of soliton equations and it permits us to obtain the Riemann theta function representation for solutions of a given equation and there are numerous articles have been devoted to this subject [3], [8], [17], [25]. This section aims to provide the explicit form of "Baker-Akhiezer function" associated with the \( p \)th mKP equation, which consists of spectral parameter \( z \), potentials \( q, r \), and then study its analytic properties. Moreover, we will find the conservation relations of soliton equations.
play a key role in the construction of Baker-Akhiezer function, which reveals symmetry is the intrinsic character of classical integrable system.

Let us first study the Baker-Akhiezer function

\[ \psi(P) = (\psi_1(P, x, y, t_p), \psi_2(P, x, y, t_p)), \quad P \in X, \]

which satisfies

\[ \psi_x(P) = U(z)\psi(P), \quad \psi_y(P) = \hat{V}_4(z)\psi(P), \]

\[ \psi_{t_p}(P) = \hat{V}_{2p+2}(z)\psi(P), \quad p > 2, \]

\[ \psi_1(P, x_0, y_0, t_{p,0}) = 1, \quad (P, x_0, y_0, t_{p,0}) \in X \times \mathbb{R}^3. \]

To find its explicit form, we need some preparations.

**Lemma 4.1.** Suppose \( q, r \in C^\infty(\mathbb{R}^{2+1}) \) and \( z \in \mathbb{C} \). Then \( \mathcal{G}_{2n+2}, \mathcal{F}_{2n+1}, \mathcal{H}_{2n+1} \) and basic fundamental solutions \( (\psi_1^+, \psi_2^+) \) of linear system (4.1) have the following algebraic relation:

\[ (\psi_1^+(z)\psi_2^+(z) - \psi_1^-(z)\psi_2^-(z))^2 = 4\mathcal{R}_{4n+4}(z). \]  

(4.2)

If we take \( \psi_1^+(z)\psi_2^-(z) - \psi_1^-(z)\psi_2^+(z) = 2\sqrt{\mathcal{R}_{4n+4}(z)} \), then

\[ \psi_1^+(z)\psi_2^-(z) = \mathcal{G}_{2n+2}(z) + \sqrt{\mathcal{R}_{4n+4}(z)}, \]

(4.3)

\[ \psi_1^-(z)\psi_2^+(z) = \mathcal{G}_{2n+2}(z) - \sqrt{\mathcal{R}_{4n+4}(z)}, \]

(4.4)

\[ \frac{\psi_2^+(z)}{\psi_1^+(z)} = \frac{\mathcal{H}_{2n+1}(z)}{\mathcal{G}_{2n+2}(z) \pm \sqrt{\mathcal{R}_{4n+4}(z)}} = \frac{\mathcal{G}_{2n+2} \mp \sqrt{\mathcal{R}_{4n+4}(z)}}{\mathcal{F}_{2n+1}}. \]

(4.5)

**Proof.** Expressions (4.2)-(4.5) can easily be verified by (2.70), (3.2). \( \square \)

**Lemma 4.2.** Suppose \( q, r \in C^\infty(\mathbb{R}^{2+1}) \). Then we have the following relations

\[ \bigg[ \frac{q(x, y, t_p)z}{\mathcal{F}_{2n+1}(z, x, y, t_p)} \bigg]_{t_j} = \bigg[ \frac{\hat{F}_{2j+1}(z, x, y, t_p)}{\mathcal{F}_{2n+1}(z, x, y, t_p)} \bigg]_x, \]

(4.6)

\[ \bigg[ \frac{r(x, y, t_p)z}{\mathcal{H}_{2n+1}(z, x, y, t_p)} \bigg]_{t_j} = \bigg[ \frac{\hat{H}_{2j+1}(z, x, y, t_p)}{\mathcal{F}_{2n+1}(z, x, y, t_p)} \bigg]_x, \quad j = 2, p, \]

(4.7)

\[ \bigg[ \frac{\hat{F}_3(z, x, y, t_p)}{\mathcal{F}_{2n+1}(z, x, y, t_p)} \bigg]_{t_p} = \bigg[ \frac{\hat{F}_{2p+1}(z, x, y, t_p)}{\mathcal{F}_{2n+1}(z, x, y, t_p)} \bigg]_y, \]

(4.8)

\[ \bigg[ \frac{\hat{H}_3(z, x, y, t_p)}{\mathcal{F}_{2n+1}(z, x, y, t_p)} \bigg]_{t_p} = \bigg[ \frac{\hat{H}_{2p+1}(z, x, y, t_p)}{\mathcal{F}_{2n+1}(z, x, y, t_p)} \bigg]_y. \]

(4.9)
Moreover, let \( \psi \). \( \phi \) follows by the relations

\[ X \]

\[ \psi \]

Based on above preparations, we shall study explicit forms of Baker-Akhiezer function by

\[ \psi_j(P, x, y, t_p) = \psi_j^+(z, x, y, t_p), \quad j = 1, 2 \] \[ \psi_j(P, x, y, t_p) = \psi_j^-(z, x, y, t_p), \quad j = 1, 2 \] \[ y(P) = \frac{1}{2} \sqrt{R_{4n+4}(z)}, \quad \text{for} \ P \in \Pi_+ \] \[ y(P) = -\frac{1}{2} \sqrt{R_{4n+4}(z)}, \quad \text{for} \ P \in \Pi_- \] \[ \lim_{P \to P_0} \psi_j(P, x, t_p) = \lim_{P \to P_0} \psi_j(P^*, x, t_p), \quad \text{for} \ j = 1, 2, \quad P \in \Pi_\pm, \quad P_0 \in \mathbb{C} \]

where we choose the branches of \( \sqrt{R_{2n+2}(\cdot)} \) satisfying

\[ \lim_{z \to \infty} \frac{\mathcal{R}_{n+1}}{\sqrt{R_{2n+2}(z)}} = 1. \]

Moreover, let

\[ \phi_j(x, y, t_p) = \left( \phi_j(x, y, t_p), -2 \sqrt{R_{4n+4}(\phi_j(x, y, t_p))} \right) \in \Pi_- \] \[ \nu_j(x, y, t_p) = \left( \nu_j(x, y, t_p), 2 \sqrt{R_{4n+4}(\phi_j(x, y, t_p))} \right) \in \Pi_+, \quad j = 1, \ldots, n. \]

Based on above preparations, we shall study explicit forms of Baker-Akhiezer function \( \psi_j(P), j = 1, 2 \).
Theorem 4.3. Suppose $q, r \in C^\infty(\mathbb{R}^{2+1})$. Then Baker-Akhiezer function satisfying condition (4.1) can be expressed as

$$
\psi_1(P, x, y, t_p) = \sqrt{\mathcal{F}_{2n+1}(\sqrt{\eta}, x, y, t_p)} \exp\left(-2 \int_{x_0}^{x} \frac{q(x', y, t_p) \sqrt{\eta y}(P)}{\mathcal{F}_{2n+1}(\sqrt{\eta}, x', y, t_p)} dx'\right) - 2 \int_{y_0}^{y} \frac{y(P) F_3(\sqrt{\eta}, x, y', t_p)}{\mathcal{F}_{2n+1}(\sqrt{\eta}, x, y', t_p)} dy' - 2 \int_{t_{p,0}}^{t_p} \frac{y(P) F_{2p+1}(\sqrt{\eta}, x_0, y_0, t')}{\mathcal{F}_{2n+1}(\sqrt{\eta}, x_0, y_0, t')} dt',
$$

(4.12)

$$
\psi_2(P, x, y, t_p) = \sqrt{\mathcal{H}_{2n+1}(\sqrt{\eta}, x, y, t_p)} \exp\left(2 \int_{x_0}^{x} \frac{r(x', y, t_p) \sqrt{\eta y}(P)}{\mathcal{F}_{2n+1}(\sqrt{\eta}, x', y, t_p)} dx'\right) - 2 \int_{y_0}^{y} \frac{y(P) H_3(\sqrt{\eta}, x, y', t_p)}{\mathcal{F}_{2n+1}(\sqrt{\eta}, x, y', t_p)} dy' - 2 \int_{t_{p,0}}^{t_p} \frac{y(P) H_{2p+1}(\sqrt{\eta}, x_0, y_0, t')}{\mathcal{F}_{2n+1}(\sqrt{\eta}, x_0, y_0, t')} dt',
$$

(4.13)

where $\eta = z^2$ denotes the projection of $P$ to complex sphere.

Proof. By (2.69), (2.73)-(2.78), (4.5), one obtains

$$
\psi_1^{\pm}(z) = - \left(z^2 - \frac{1}{4} q^2\right) \psi_1^+(z) + q z \psi_2^+(z)
= \left[\left(-\frac{qz G_{2n+2}(z)}{\mathcal{F}_{2n+1}(z)} + \frac{1}{2} \frac{\mathcal{F}_{2n+1, x}(z)}{\mathcal{F}_{2n+1}(z)}\right) + qz \frac{\psi_2^+(z)}{\psi_1^+(z)}\right] \psi_1^+(z)
= \left[\left(-\frac{qz G_{2n+2}(z)}{\mathcal{F}_{2n+1}(z)} + \frac{1}{2} \frac{\mathcal{F}_{2n+1, x}(z)}{\mathcal{F}_{2n+1}(z)}\right) + qz \frac{\mathcal{H}_{2n+1}(z)}{\mathcal{F}_{2n+1}(z) \pm \mathcal{R}_{4n+4}(z)}\right] \psi_1^+(z)
= \pm qz \frac{\mathcal{R}_{4n+4}(z) + \frac{1}{2} \mathcal{F}_{2n+1, x}(z)}{\mathcal{F}_{2n+1}(z)} \psi_1^+(z),
$$

(4.14)

$$
\psi_1^{\pm}(z) = - \tilde{G}_{2j+2}(z) \psi_1^+(z) + \tilde{F}_{2j+1}(z) \psi_2^+(z)
= \left[\left(-\frac{\tilde{F}_{2j+1}(z) G_{2n+2}(z)}{\mathcal{F}_{2n+1}(z)} + \frac{1}{2} \frac{\mathcal{F}_{2n+1, t_j}(z)}{\mathcal{F}_{2n+1}(z)}\right) + \frac{\tilde{F}_{2j+1}(z) \psi_2^+(z)}{\psi_1^+(z)}\right] \psi_1^+(z)
= \left[\left(-\frac{\tilde{F}_{2j+1}(z) G_{2n+2}(z)}{\mathcal{F}_{2n+1}(z)} + \frac{1}{2} \frac{\mathcal{F}_{2n+1, t_j}(z)}{\mathcal{F}_{2n+1}(z)}\right) + \frac{\tilde{F}_{2j+1}(z) \mathcal{H}_{2n+1}(z)}{\mathcal{F}_{2n+1}(z) \pm \mathcal{R}_{4n+4}(z)}\right] \psi_1^+(z)
= \pm \frac{\tilde{F}_{2j+1}(z) \mathcal{R}_{4n+4}(z) + \frac{1}{2} \mathcal{F}_{2n+1, t_j}(z)}{\mathcal{F}_{2n+1}(z)} \psi_1^+(z), \quad j = 2, p,
$$

(4.15)
and similarly

$$
\psi_{2,ax}^{\pm}(z) = rz \psi_{1}^{\pm}(z) + \left( z^2 - \frac{1}{4} qr \right) \psi_2^{\pm}(z)
$$

$$
= \left[ rz \frac{\psi_1^{\pm}(z)}{\psi_2^{\pm}(z)} + \left( \frac{\mathcal{H}_{2n+1,x}(z)}{2 \mathcal{H}_{2n+1}(z)} \right) - \frac{rz \mathcal{G}_{2n+2}(z)}{\mathcal{H}_{2n+1}(z)} \right] \psi_2^{\pm}(z)
$$

$$
= \left[ rz \frac{\mathcal{G}_{2n+2}(z) \pm \sqrt{\mathcal{R}_{4n+4}(z)}}{\mathcal{H}_{2n+1}(z)} + \left( \frac{\mathcal{H}_{2n+1,x}(z)}{2 \mathcal{H}_{2n+1}(z)} \right) - \frac{rz \mathcal{G}_{2n+2}(z)}{\mathcal{H}_{2n+1}(z)} \right] \psi_2^{\pm}(z)
$$

$$
= \pm rz \sqrt{\mathcal{R}_{4n+4}(z)} + \frac{\mathcal{H}_{2n+1,x}(z)}{\mathcal{H}_{2n+1}(z)} \psi_2^{\pm}(z), \quad (4.16)
$$

$$
\psi_{2,tj}^{\pm}(z) = \bar{H}_{2j+1}(z) \psi_{1}^{\pm}(z) + \mathcal{G}_{2j+2}(z) \psi_{2}^{\pm}(z)
$$

$$
= \left[ \bar{H}_{2j+1}(z) \psi_{1}^{\pm}(z) + \left( \frac{\mathcal{H}_{2n+1,t_j}(z)}{\mathcal{H}_{2n+1}(z)} \right) + \bar{H}_{2j+1}(z) \frac{\mathcal{G}_{2n+2}(z)}{\mathcal{H}_{2n+1}(z)} \right] \psi_2^{\pm}(z)
$$

$$
= \left[ \bar{H}_{2j+1}(z) \frac{\mathcal{G}_{2n+2}(z) \pm \sqrt{\mathcal{R}_{4n+4}(z)}}{\mathcal{H}_{2n+1}(z)} + \left( \frac{\mathcal{H}_{2n+1,t_j}(z)}{2 \mathcal{H}_{2n+1}(z)} \right) + \bar{H}_{2j+1}(z) \frac{\mathcal{G}_{2n+2}(z)}{\mathcal{H}_{2n+1}(z)} \right] \psi_2^{\pm}(z)
$$

$$
= \pm \bar{H}_{2j+1}(z) \sqrt{\mathcal{R}_{4n+4}(z)} + \frac{\mathcal{H}_{2n+1,t_j}(z)}{2 \mathcal{H}_{2n+1}(z)} \psi_2^{\pm}(z), \quad j = 2, p. \quad (4.17)
$$

Thus, we have

$$
d \ln(\psi_{1}^{\pm}(z, x, y, t_p)) = \left( \frac{\mp qz \sqrt{\mathcal{R}_{4n+4}(z)} + \frac{1}{2} \mathcal{P}_{2n+1, x}(z)}{\mathcal{P}_{2n+1}(z)} \right) dx
$$

$$
+ \left( \frac{\mp F_{3}(z) \sqrt{\mathcal{R}_{4n+4}(z)} + \frac{1}{2} \mathcal{P}_{2n+1, y}(z)}{\mathcal{P}_{2n+1}(z)} \right) dy
$$

$$
+ \left( \frac{\mp F_{2p+1}(z) \sqrt{\mathcal{R}_{4n+4}(z)} + \frac{1}{2} \mathcal{P}_{2n+1, t_p}(z)}{\mathcal{P}_{2n+1}(z)} \right) dt_p
$$

$$
\quad (4.18)
$$
and
\[ d\ln(\psi_{2}^{\pm}(z,x,y,t_p)) = \left( \frac{\pm rz\sqrt{\mathcal{R}_{n+4}(z)} + \frac{1}{2}\mathcal{K}_{2n+1,x}(z)}{\mathcal{K}_{2n+1}(z)} \right) dx \\
+ \left( \frac{\pm \hat{H}_{3}(z)\sqrt{\mathcal{R}_{n+4}(z)} + \frac{1}{2}\mathcal{K}_{2n+1,y}(z)}{\mathcal{K}_{2n+1}(z)} \right) dy \\
+ \left( \frac{\pm \hat{H}_{p+1}(z)\sqrt{\mathcal{R}_{n+4}(z)} + \frac{1}{2}\mathcal{K}_{2n+1,y}(z)}{\mathcal{K}_{2n+1}(z)} \right) dt_p. \]

(4.19)

According to relations (4.7)-(4.9), it follows that the integrals
\[ \int_{(x_0,y_0,t_p,0)}^{(x,y,t_p)} d\ln\left( \frac{\psi_{j}^{\pm}(z,x,y,t_p)}{\sqrt{\mathcal{F}_{2n+1}(z,x,y,t_p)}} \right), \quad j = 1,2 \]

is independent of the path. Therefore taking into account the normalization condition \( \psi_{1}(P,x_0,y_0,t_p,0) = 1 \), and choosing a special path
\[(x_0,y_0,t_p,0) \rightarrow (x_0,y_0,t_p) \rightarrow (x_0,y,t_p) \rightarrow (x,y,t_p)\]
in (4.20), we finally obtain (4.12) and (4.13).

Basic properties of Baker-Akhiezer functions \( \psi_{j}(P) \), \( j = 1,2 \) are summarized in the following result.

**Lemma 4.4.** Suppose \( q,r \in C^{\infty}(\mathbb{R}^{2+1}) \) and \( P \in X \setminus \{P_{\infty} \} \). Then the Baker-Akhiezer function derived in (4.12), (4.13) satisfy

\[
\psi_{1}(P,x,y,t_p)\psi_{1}(P^*,x,y,t_p) = \frac{\mathcal{F}_{2n+1}(\sqrt{\eta},x,y,t_p)}{\mathcal{F}_{2n+1}(\sqrt{\eta},x_0,y_0,t_p,0)}, \quad (4.21)
\]

\[
\psi_{2}(P,x,y,t_p)\psi_{2}(P^*,x,y,t_p) = \frac{\mathcal{H}_{2n+1}(\sqrt{\eta},x,y,t_p)}{\mathcal{F}_{2n+1}(\sqrt{\eta},x_0,y_0,t_p,0)}, \quad (4.22)
\]

\[
\psi_{1}(P,x,y,t_p)\psi_{2}(P^*,x,y,t_p) = \frac{\mathcal{G}_{2n+2}(\sqrt{\eta},x,y,t_p) + \sqrt{\mathcal{R}_{n+4}(\sqrt{\eta})}}{\mathcal{F}_{2n+1}(\sqrt{\eta},x_0,y_0,t_p,0)}, \quad (4.23)
\]

\[
\psi_{1}(P,x,y,t_p)\psi_{2}(P^*,x,y,t_p) + \psi_{1}(P^*,x,y,t_p)\psi_{2}(P,x,y,t_p) = \frac{2\mathcal{G}_{2n+2}(\sqrt{\eta},x,y,t_p)}{\mathcal{F}_{2n+1}(\sqrt{\eta},x_0,y_0,t_p,0)}, \quad (4.24)
\]

\[
\psi_{1}(P,x,y,t_p)\psi_{2}(P^*,x,y,t_p) - \psi_{1}(P^*,x,y,t_p)\psi_{2}(P,x,y,t_p) = \frac{2\sqrt{\mathcal{R}_{n+4}(\sqrt{\eta})}}{\mathcal{F}_{2n+1}(\sqrt{\eta},x_0,y_0,t_p,0)}. \quad (4.25)
\]
Proof. It can be easily seen that (4.21) and (4.22) hold by (4.12) and (4.13), respectively. Then from (4.21), (4.22) and the fact that
\[
\left( \frac{1}{2}(\psi_1(P)\psi_2(P^*) + \psi_1(P^*)\psi_2(P)), \psi_1(P)\psi_1(P^*), \psi_2(P)\psi_2(P^*) \right)
\]
and
\[
\left( \frac{G_{2n+2}(\sqrt{\eta}, x, y, t_p)}{\mathcal{F}_{2n+1}(\sqrt{\eta}, x, y, t_p)}, \frac{\mathcal{H}_{2n+1}(\sqrt{\eta}, x, y, t_p)}{\mathcal{F}_{2n+1}(\sqrt{\eta}, x, y, t_p)} \right)
\]
are both solutions of linear system (2.70)-(2.78) satisfying the same initial condition, one gets (4.24). Using (4.21), (4.22) and (4.24), we have
\[
\psi_1(P, x, y, t_p)\psi_2(P^*, x, y, t_p) - \psi_1(P^*, x, y, t_p)\psi_2(P, x, y, t_p)
= \sqrt{(\psi_1(P)\psi_2(P^*) + \psi_1(P^*)\psi_2(P))^2 - 4\psi_1(P)\psi_1(P^*)\psi_2(P)\psi_2(P^*)}
= \frac{2\sqrt{\mathcal{F}_{4n+1}(\sqrt{\eta})}}{\mathcal{F}_{2n+1}(\sqrt{\eta}, x_0, y_0, t_p, 0)}.
\]
Finally, (4.23) is the direct result of (4.24), (4.25). □

Next we shall study the analytic property and asymptotic behavior of \(\psi_1(P)\psi_2(P^*)\), and \(\psi_j(P), j = 1, 2\).

**Lemma 4.5.** The function \(\psi_1(P)\psi_2(P^*)\) is a meromorphic function on \(X\) with divisor
\[
(\psi_1(P)\psi_2(P^*)) = D_{\hat{\mu}}(x, y, t_p)\hat{\mu}(x, y, t_p)P_{\infty^+} - D_{\hat{\nu}}(x_0, y_0, t_0)\hat{\nu}(x_0, y_0, t_0)P_{\infty^-},
\]
where we abbreviate \(\hat{\mu} = (\hat{\mu}_1, \ldots, \hat{\mu}_n), \hat{\nu} = (\hat{\nu}_1, \ldots, \hat{\nu}_n)\). Moreover, using the local coordinate \(\zeta = z^{-1}\) near \(P_{\infty^\pm}\), we have
\[
\psi_1(P, x, y, t_p)\psi_2(P^*, x, y, t_p) \xrightarrow{\zeta \to 0} \begin{cases} 
2 \frac{\partial}{\partial(x_0, y_0, t_p, 0)} \zeta^{-1} + O(1), & \text{as } P \to P_{\infty^+}, \\
- \frac{\partial}{\partial(2, (x_0, y_0, t_p, 0))} \zeta + O(\zeta^2), & \text{as } P \to P_{\infty^-}.
\end{cases}
\]

**Proof.** Noticing (3.2), (3.4), (4.23) and
\[
\psi_1(P, x, y, t_p)\psi_2(P^*, x, y, t_p) = \frac{G_{2n+2}(\sqrt{\eta}, x, y, t_p)}{\mathcal{F}_{2n+1}(\sqrt{\eta}, x, y, t_p)} + \sqrt{\mathcal{H}_{4n+4}(\sqrt{\eta})} \frac{\mathcal{F}_{2n+1}(\sqrt{\eta}, x, y, t_p)}{\mathcal{F}_{2n+1}(\sqrt{\eta}, x, y, t_p)}
\]
and
\[
\frac{G_{2n+2}(\sqrt{\eta}, x, y, t_p)}{\mathcal{F}_{2n+1}(\sqrt{\eta}, x, y, t_p)} + \sqrt{\mathcal{H}_{4n+4}(\sqrt{\eta})} \frac{\mathcal{F}_{2n+1}(\sqrt{\eta}, x, y, t_p)}{\mathcal{F}_{2n+1}(\sqrt{\eta}, x, y, t_p)}
\]
we have
\[
\psi_1(P, x, y, t_p)\psi_2(P^*, x, y, t_p) = \left( \frac{G_{2n+2}(\sqrt{\eta}, x, y, t_p)}{\mathcal{F}_{2n+1}(\sqrt{\eta}, x, y, t_p)} + \sqrt{\mathcal{H}_{4n+4}(\sqrt{\eta})} \frac{\mathcal{F}_{2n+1}(\sqrt{\eta}, x, y, t_p)}{\mathcal{F}_{2n+1}(\sqrt{\eta}, x, y, t_p)} \right).
\]
one easily proves \([4.27]\) and \([4.28]\).

Now we turn to study the analytic structure of \(\psi_j(P, x, y, t_p)\) on \(X\backslash\{P_{\infty}\}\).

**Theorem 4.6.** Assume auxiliary spectrum points \(\mu_j(x, y, t_p), \nu_j(x, y, t_p)\), \(j = 1, \ldots, n\), are mutually distinct and finite for all \((x, y, t_p) \in \Omega\), where \(\Omega \subset \mathbb{R}^3\) is an open interval. Moreover, let \(P \in X\backslash\{P_{\infty}\}\). Then

**I.** \(\psi_1(P, x, y, t_p)\) and \(\psi_2(P, x, y, t_p)\) are meromorphic on \(P \in X\backslash\{P_{\infty}\}\).

Their divisor of poles coincides with \(D_\hat{\mu}(x_0, y_0, t_{p0})\).

**II.** The divisor of zeros for \(\psi_1(P, x, y, t_p)\) and \(\psi_2(P, x, y, t_p)\) coincides with \(D_\hat{\nu}(x_0, y_0, t_{p0})\) and \(D_\hat{\nu}(x_0, y_0, t_{p0})\), respectively.

**III.** As \(P \to P_{\infty}\), the asymptotic behavior of \((\psi_1(P, x, y, t_p), \psi_2(P, x, y, t_p))^T\) is given by the equations,

\[
\begin{pmatrix}
\psi_1(P, x, y, t_p) \\
\psi_2(P, x, y, t_p)
\end{pmatrix} = \left(\frac{q(x, y, t_p)}{q(x_0, y_0, t_{p0})} + O(\zeta) + O(\zeta^2)\right) \times \exp\left(-(x - x_0)\zeta^{-1}ight)
- (y - y_0)\zeta^{-2} - (t_p - t_{p0})\zeta^{-(p+1)}
+ \left(-\frac{1}{4} \int_{x_0}^{x} q(x', y, t_p) r(x', y, t_p) dx' + \frac{1}{2} \int_{y_0}^{y} g_4(x_0, y', t_p) dy'
+ \frac{1}{2} \int_{t_{p0}}^{t_p} g_{2p+2}(x_0, y_0, t') dt'ight), \quad \text{at} \quad P \to P_{\infty+},
\]

(4.29)

and

\[
\begin{pmatrix}
\psi_1(P, x, y, t_p) \\
\psi_2(P, x, y, t_p)
\end{pmatrix} = \left(\frac{1 + O(\zeta)}{q(x, y, t_p)}\zeta^{-1} + O(1)\right) \times \exp\left((x - x_0)\zeta^{-1}ight)
+ (y - y_0)\zeta^{-2} + (t_p - t_{p0})\zeta^{-(p+1)}
+ \left(\frac{1}{4} \int_{x_0}^{x} q(x', y, t_p) r(x', y, t_p) dx' - \frac{1}{2} \int_{y_0}^{y} g_4(x_0, y', t_p) dy'
- \frac{1}{2} \int_{t_{p0}}^{t_p} g_{2p+2}(x_0, y_0, t') dt'ight), \quad \text{at} \quad P \to P_{\infty-}.
\]

(4.30)
Proof. First we study the function \( \psi_1 \). By (3.11), (3.11), (3.12) it follows

\[
-2 \frac{\partial_j \ln \sqrt{\eta_j(P)}}{\mathcal{F}_{2n+1}(\sqrt{\eta_j(x', y', t_p)})} = \partial_{x'} \ln \sqrt{\eta_j(x', y, t_p)}, \quad (4.31)
\]

and hence one obtains

\[
\exp \left( -2 \int_{t_o}^{t_p} \frac{\partial_{x'} \ln \sqrt{\eta_j(x', y, t_p)}}{\mathcal{F}_{2n+1}(\sqrt{\eta_j(x', y, t_p)})} dx' - 2 \int_{y_0}^{y} \frac{\partial_{y'} \ln \sqrt{\eta_j(x, y', t_p)}}{\mathcal{F}_{2n+1}(\sqrt{\eta_j(x, y', t_p)})} dy' \right)
\]

\[
\exp \left( \int_{t_o}^{t_p} \partial_{t'} \ln \sqrt{\eta_j(x, y, t_p)} dt' + O(1) \right)
\]

\[
\begin{cases}
\sqrt{\eta_j(x, y, t_p)}^{-1}, & P \to \hat{\mu}_j(x, y, t_p), \\
\sqrt{\eta_j(x, y, t_p)}^{-1}, & P \to \hat{\mu}_j(x, y, t_p), \\
O(1), & P \to \hat{\mu}_j(x, y, t_p) = \hat{\mu}_j(x, y, t_p), \\
O(1), & P \to \hat{\mu}_j(x, y, t_p) = \hat{\mu}_j(x, y, t_p). 
\end{cases}
\]

Then taking into account (4.12), one proves I. and II. for \( \psi_1 \). Next we study the asymptotic behaviour of \( \psi_1 \) near \( P_{\infty} \pm \). Again using (4.12) and
local coordinate $\eta = z^{-1}$ near $P_{\infty \pm}$, one infers

$$
\psi_1(P, x, y, t_p) = \sqrt{\frac{\mathcal{F}_{2n+1}(\sqrt{\eta}, x, y, t_p)}{\mathcal{F}_{2n+1}(\sqrt{\eta}, x', y, t_p)}} \exp \left( -2 \int_{x_0}^x q(x', y, t_p)y(P)\,dx' - 2 \int_{y_0}^y \frac{y(P)\hat{F}_3(\sqrt{\eta}, x', y, t_p)}{\mathcal{F}_{2n+1}(\sqrt{\eta}, x', y, t_p)}\,dy' - 2 \int_{t_{p_0}}^{t_p} \frac{y(P)\hat{F}_{2p+1}(z, x_0, y_0, t')}{\mathcal{F}_{2n+1}(\sqrt{\eta}, x_0, y_0, t')}\,dt' \right)
$$

$$
= \exp \left( \int_{x_0}^x \left( -2 \sum_{j=0}^{\hat{n}} \hat{F}_{2j+1}(x, x', y, t_p)\zeta_{j+1} + \frac{q(x', y, t_p)}{2q(x, y, t_p)} \right)\,dx' + \int_{y_0}^y \left( -2 \sum_{j=0}^{\hat{n}} \hat{F}_3(x_0, y, t_p)\zeta_{j+1} + \frac{q(x, y, t_p)}{2q(x, y, t_p)} \right)\,dy' + \int_{t_{p_0}}^{t_p} \left( -2 \sum_{j=0}^{\hat{n}} \hat{F}_{2j+1}(x, x_0, y_0, t')\zeta_{j+1} + \frac{q(x, y_0, t')}{2q(x, y_0, t')} \right)\,dt' \right), \quad \text{as} \quad P \to P_{\infty -},
$$

$$
= \frac{q(x, y, t_p)}{q(x_0, y_0, t_p)} \exp \left( - (x - x_0)\zeta_{-1} - (y - y_0)\zeta_{-2} - (t_p - t_{p_0})\zeta_{-(p+1)} + (-\frac{1}{2} \int_{x_0}^x q(x', y, t_p)\,dx' + \frac{1}{2} \int_{y_0}^y g_4(x_0, y, t_p)\,dy' + \frac{1}{2} \int_{t_{p_0}}^{t_p} g_{2p+2}(x_0, y_0, t')\,dt') + O(\zeta) \right), \quad \text{as} \quad P \to P_{\infty -},
$$

$$
= \frac{\mathcal{F}_{2n+1}(\sqrt{\eta}, x, y, t_p)}{y(P)} = \pm \sum_{j=0}^{\hat{n}} \hat{f}_{2j+1}(x, y, t_p)\zeta_{j+\frac{3}{2}}, \quad \text{as} \quad P \to P_{\infty \pm}, \quad (4.36)
$$

Here we have used asymptotic spectral expansion

$$
\frac{\mathcal{F}_{2n+1}(\sqrt{\eta}, x, y, t_p)}{y(P)} = \pm \sum_{j=0}^{\hat{n}} \hat{f}_{2j+1}(x, y, t_p)\zeta_{j+\frac{3}{2}}, \quad \text{as} \quad P \to P_{\infty \pm}, \quad (4.36)
$$

(4.35)
in the last equality of (4.35), and the expression (4.36) can be obtained by induction. Finally, the statements for $\psi_2$ follows by Lemma 4.5 and (4.35).

5 Algebro-Geometric Solutions

In this section, we shall study the theta function representation of Baker-Akhiezer functions $\psi_1(P), \psi_2(P)$ and algebro-geometric solutions of the whole mKP hierarchy. For more details about Riemann surfaces and theta functions we recommend the reference [13].

First, choosing a convenient base point $Q_0 \in X \setminus \{P_{\infty \pm}\}$, the Abel maps $A_{Q_0} : X \to J(X) = \mathbb{C}^n/L_n,$

$$P \mapsto A_{Q_0}(P) = (A_{Q_0,1}(P), \ldots, A_{Q_0,n}(P)) = (\int_{Q_0}^P \omega_1, \ldots, \int_{Q_0}^P \omega_n) \pmod{L_n},$$

and

$$\alpha_{Q_0} : \text{Div}(X) \to J(X), \quad D \mapsto \alpha_{Q_0}(D) = \sum_{P \in \mathcal{K}_n} D(P) A_{Q_0}(P),$$

where $L_n = \{z \in \mathbb{C}^n | z = N + \Gamma M, N, M \in \mathbb{Z}^n\}$, and $\Gamma, \Xi_{Q_0}$ are the Riemann matrix and the vector of Riemann constants, respectively. Moreover, we choose a homology basis $\{a_j, b_j\}_{j=1}^n$ on $X$ in such a way that the intersection matrix of the cycles satisfies

$$a_j \circ b_k = \delta_{j,k}, \quad a_j \circ a_k = 0, \quad b_j \circ b_k = 0, \quad j, k = 1, \ldots, n. \quad (5.1)$$

For brevity, define the function $\bar{z} : X \times \sigma^n X \to \mathbb{C}^n$ by

$$\bar{z}(P, Q) = \Xi_{Q_0} - A_{Q_0}(P) + \alpha_{Q_0}(D_0), \quad P \in \mathcal{K}_n, \quad Q = (Q_1, \ldots, Q_n) \in \sigma^n \mathcal{K}_n, \quad (5.2)$$

$2\sigma^n X = \underbrace{X \times \ldots \times X}_{n}$. 

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here \( \zeta(\cdot, Q) \) is independent of the choice of base point \( Q_0 \). The Riemann theta function \( \theta(\zeta) \) associated with \( X \) and the homology is defined by

\[
\theta(\zeta) = \sum_{n \in \mathbb{Z}} \exp \left( 2\pi i < n, \zeta > + \pi i < n, nG > \right), \quad \zeta \in \mathbb{C}^n,
\]

where \( < P, C > = \overline{P} \cdot C' = \sum_{j=1}^{N} \overline{B}_j C_j \) denotes the scalar product in \( \mathbb{C}^{n-1} \).

Let \( \omega_{P_{\infty \pm}^q}^{(2)} \) be the normalized differentials of the second kind with a unique pole at \( P_{\infty \pm} \), respectively, and principal parts

\[
\omega_{P_{\infty \pm}^q}^{(2)} = (\zeta^{-2q} + O(1)) \, d\zeta, \quad P \to P_{\infty \pm}, \quad \zeta = z^{-1}, \quad q \in \mathbb{N}_0 \quad (5.3)
\]

with vanishing \( a \)-periods,

\[
\int_{a_j} \omega_{P_{\infty \pm}^q}^{(2)} = 0, \quad j = 1, \ldots, n,
\]

and \( \omega_{P_{\infty}^+P_{\infty}^-} \) be normalized differential of third kind satisfying

\[
\int_{Q_0}^{P} \omega_{P_{\infty}^-P_{\infty}^+} = \zeta^{-1} + c_{\infty+} + O(\zeta), \quad P \to P_{\infty+}, \quad \zeta = z^{-1}, \quad c_{\infty+} \in \mathbb{C},
\]

and

\[
\int_{a_j} \omega_{P_{\infty}^+P_{\infty}^-} = 0 \quad j = 1, \ldots, n.
\]

Moreover, we introduce the notation

\[
\Omega_r^{(2)} = \frac{1}{2} (r + 1)(\omega_{P_{\infty}^+r}^{(2)} - \omega_{P_{\infty}^-r}^{(2)}), \quad r \in \mathbb{N}_0. \quad (5.4)
\]

and

\[
\omega_1^{(2)} = \lim_{P \to P_{\infty}^+} \int_{Q_0}^{P} \Omega_r^{(2)}. \quad (5.5)
\]

Next we study the theta function representation for \( \psi_1(P)\psi_2(P^*) \).

Lemma 5.1. Assume spectral curve defined in (3.4) is nonsingular and \( q, r \) satisfy (2.80). Moreover, let \( P \in X \backslash \{P_{\infty \pm} \} \) and suppose the divisors
$D_{\hat{\psi}(x,y,t_p)}, \ D_{\hat{\mu}(x,y,t_p)}$ are nonspecial. Then

\[
\psi_1(P, x, y, t_p) \psi_2(P^*, x, y, t_p) = 2 \frac{\theta(z(P^{\infty+}, \hat{\mu}(x_0, y_0, t_p, 0))) \theta(z(P^{\infty-}, \hat{\nu}(x_0, y_0, t_p, 0)))}{q(x_0, y_0, t_{p,0}) \theta(z(P^{\infty+}, \hat{\nu}(x, y, t_p))) \theta(z(P^{\infty-}, \hat{\nu}(x, y, t_p)))} \times \frac{\theta(z(P^*, \hat{\mu}(x_0, y_0, t_p, 0))) \theta(z(P, \hat{\mu}(x, y, t_p)))}{\theta(z(P^*, \hat{\mu}(x_0, y_0, t_p, 0))) \theta(z(P, \hat{\mu}(x, y, t_p)))} \times \exp \left( \int_{Q_0}^{P} \omega_{P^{\infty-}P^{\infty+} - c^{\infty+}} \right). \tag{5.6}
\]

Proof. Let

\[
\mathcal{R}(P, x, t_p) = \frac{2}{q(x_0, y_0, t_{p,0})} \frac{\theta(z(P^{\infty+}, \hat{\mu}(x_0, y_0, t_p, 0))) \theta(z(P^{\infty-}, \hat{\nu}(x_0, y_0, t_p, 0)))}{\theta(z(P^{\infty+}, \hat{\nu}(x, y, t_p))) \theta(z(P^{\infty-}, \hat{\nu}(x, y, t_p)))} \times \frac{\theta(z(P^*, \hat{\mu}(x_0, y_0, t_p, 0))) \theta(z(P, \hat{\mu}(x, y, t_p)))}{\theta(z(P^*, \hat{\mu}(x_0, y_0, t_p, 0))) \theta(z(P, \hat{\mu}(x, y, t_p)))} \times \exp \left( \int_{Q_0}^{P} \omega_{P^{\infty-}P^{\infty+} - c^{\infty+}} \right). \tag{5.7}
\]

Then it is not difficult to know divisors of $\psi_1(P, x, y, t_p) \psi_2(P^*, x, y, t_p)$ coincides with that of $\mathcal{R}(P, x, t_p)$ on $X$. Therefore, the function $\psi_1(P, x, y, t_p) \psi_2(P^*, x, y, t_p)$ is a constant independent of $P$ and we denote it by $C(x, y, t_p)$. Taking $P \rightarrow P^{\infty+}$ and using Lemma 4.5, one finally obtains

\[
C(x, y, t_p) = \lim_{P \rightarrow P^{\infty+}} \frac{\psi_1(P, x, y, t_p) \psi_2(P^*, x, y, t_p)}{\mathcal{R}(P, x, t_p)} = 1,
\]

and the relation

\[
\psi_1(P, x, y, t_p) \psi_2(P^*, x, y, t_p) = \mathcal{R}(P, x, y, t_p)
\]

for any $P \in X$. \hfill \Box

Given these preparations, one finally derives the following theta function representation for Baker-Akhiezer functions $\psi_j(P, x, y, t_p), j = 1, 2$, and algebro-geometric solutions $q(x, y, t_p), r(x, y, t_p)$. 

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Theorem 5.2. Assume spectral curve defined in (3.4) is nonsingular and \( q, p \) satisfy (2.50). Moreover, let \( P \in X \setminus \{ P_{\infty, \pm} \} \) and suppose the divisors \( D_{\omega(x,y,t_p)}, D_{\hat{\mu}(x,y,t_p)} \) are nonspecial. Then functions \( \psi_1, \psi_2, q, r \) have the following theta function representations

\[
\psi_1(P, x, y, t_p) = C_1(x, y, t_p) \frac{\theta(z(P, \hat{\mu}(x, y, t_p)))}{\theta(z(P, \hat{\mu}(x_0, y_0, t_0,p)))} \exp \left( - (x - x_0) \int_{Q_0}^P \Omega_0^{(2)} \right)
- (y - y_0) \int_{Q_0}^P \Omega_1^{(2)} - (t_p - t_{p,0}) \int_{Q_0}^P \Omega_0^{(2)} ) \right),
\]

(5.8)

\[
\psi_2(P, x, y, t_p) = C_2(x, y, t_p) \frac{\theta(z(P, \hat{\mu}(x, y, t_p)))}{\theta(z(P, \hat{\mu}(x_0, y_0, t_0,p)))} \exp \left( - (x - x_0) \int_{Q_0}^P \Omega_0^{(2)} \right)
- (y - y_0) \int_{Q_0}^P \Omega_1^{(2)} - (t_p - t_{p,0}) \int_{Q_0}^P \Omega_0^{(2)} + \sqrt{\int_{Q_0}^P \omega_{P_{\infty} + P_{\infty}^-} } \right),
\]

(5.9)

and

\[
q(x, y, t_p) = q(x_0, y_0, t_0,p) \frac{\theta(z(P_{\infty, +}, \hat{\mu}(x_0, y_0, t_0,p)))}{\theta(z(P_{\infty, -}, \hat{\mu}(x, y, t_p)))} \frac{\theta(z(P_{\infty, +}, \hat{\mu}(x_0, y_0, t_0,p)))}{\theta(z(P_{\infty, -}, \hat{\mu}(x, y, t_p)))} \exp \left( c_0 \int_{x_0}^x \frac{\theta(z(P_{\infty, +}, \hat{\mu}(x', y, t_p)))}{\theta(z(P_{\infty, -}, \hat{\mu}(x', y, t_p)))} \frac{\theta(z(P_{\infty, +}, \hat{\mu}(x', y, t_p)))}{\theta(z(P_{\infty, -}, \hat{\mu}(x', y, t_p)))} dx' \right),
\]

(5.10)

\[
r(x, y, t_p) = - q(x_0, y_0, t_0,p) \frac{\theta(z(P_{\infty, +}, \hat{\mu}(x_0, y_0, t_0,p)))}{\theta(z(P_{\infty, -}, \hat{\mu}(x, y, t_p)))} \frac{\theta(z(P_{\infty, +}, \hat{\mu}(x_0, y_0, t_0,p)))}{\theta(z(P_{\infty, -}, \hat{\mu}(x, y, t_p)))} \exp \left( - c_0 \int_{x_0}^x \frac{\theta(z(P_{\infty, +}, \hat{\mu}(x', y, t_p)))}{\theta(z(P_{\infty, -}, \hat{\mu}(x', y, t_p)))} \frac{\theta(z(P_{\infty, +}, \hat{\mu}(x', y, t_p)))}{\theta(z(P_{\infty, -}, \hat{\mu}(x', y, t_p)))} dx' \right),
\]

(5.11)

\[
q(x, y, t_p)r(x, y, t_p) = -2 c_0 \frac{\theta(z(P_{\infty, +}, \hat{\mu}(x, y, t_p)))}{\theta(z(P_{\infty, -}, \hat{\mu}(x, y, t_p)))} \frac{\theta(z(P_{\infty, +}, \hat{\mu}(x, y, t_p)))}{\theta(z(P_{\infty, -}, \hat{\mu}(x, y, t_p)))}.
\]

(5.12)
where \( c_0 = 2e^{c_- - c_+} \) and

\[
C_1(x, y, t_p) = \frac{\theta(z(P_{\infty+}, \hat{\mu}(x, y, t_p)))}{\theta(z(P_{\infty+}, \bar{\mu}(x, y, t_p)))} \times \exp \left( \frac{c_0}{2} \int_{x_0}^{x} \frac{\theta(z(P_{\infty-}, \hat{\mu}(x', y, t_p)))}{\theta(z(P_{\infty-}, \bar{\mu}(x', y, t_p)))} \, dx' \right),
\]

\[
C_2(x, y, t_p) = \frac{\theta(z(P_{\infty-}, \hat{\mu}(x, y, t_p)))}{\theta(z(P_{\infty-}, \bar{\mu}(x, y, t_p)))} \times \exp \left( -\frac{c_0}{2} \int_{x_0}^{x} \frac{\theta(z(P_{\infty-}, \hat{\mu}(x', y, t_p)))}{\theta(z(P_{\infty-}, \bar{\mu}(x', y, t_p)))} \, dx' \right).
\]

(5.13)  (5.14)

Here we emphasize that the initial values \( q(x_0, y_0, t_{p,0}) \) and \( r(x_0, y_0, t_{p,0}) \) should satisfy

\[
r(x_0, y_0, t_{p,0}) = -q(x_0, y_0, t_{p,0}) \frac{\theta(z(P_{\infty-}, \hat{\mu}(x_0, y_0, t_{p,0})))}{\theta(z(P_{\infty-}, \bar{\mu}(x_0, y_0, t_{p,0})))} \times \frac{\theta(z(P_{\infty+}, \hat{\mu}(x_0, y_0, t_{p,0})))}{\theta(z(P_{\infty+}, \bar{\mu}(x_0, y_0, t_{p,0})))}.
\]

(5.15)

Moreover, the Abel map linearizes the auxiliary divisors \( \mathcal{D}_{\hat{\mu}(x,y,t_p)}, \mathcal{D}_{\bar{\mu}(x,y,t_p)} \) in the sense that

\[
\alpha_{Q_0}(\mathcal{D}_{\hat{\mu}(x,y,t_p)}) = \alpha_{Q_0}(\mathcal{D}_{\bar{\mu}(x_0,y_0,t_{p,0})}) + U_{1}^{(2)}(x-x_0) + U_{1}^{(2)}(y-y_0) + U_{1}^{(2)}(t_p-t_{p,0}),
\]

(5.16)

\[
\alpha_{Q_0}(\mathcal{D}_{\bar{\mu}(x,y,t_p)}) = \alpha_{Q_0}(\mathcal{D}_{\bar{\mu}(x_0,y_0,t_{p,0})}) + U_{0}^{(2)}(x-x_0) + U_{1}^{(2)}(y-y_0) + U_{1}^{(2)}(t_p-t_{p,0}) + \frac{1}{2} \left( A_{Q_0}(P_{\infty-}) - A_{Q_0}(P_{\infty+}) \right).
\]

(5.17)

**Proof.** First, we prove expression (5.8). Denote the right hand of (5.8) by \( \tilde{\psi}_1 \), and then one finds \( \tilde{\psi}_1 \) is meromorphic on \( X \setminus \{P_{\infty}\} \) with simple zeros at \( \hat{\mu}_j(x, y, t_p), j = 1, \ldots, n \), and simple poles at \( \hat{\mu}_j(x, y, t_{p,0}), j = 1, \ldots, n \), by Riemann vanishing theorem. Comparing (1.29), (3.30), (5.8) for \( \psi_1 \), and taking into account (5.3), (5.1), one infers \( \psi_1 \) and \( \tilde{\psi}_1 \) have identical exponential behavior up to order \( O(1) \) near \( P_{\infty} \). Thus, \( \psi_1 \) and \( \tilde{\psi}_1 \) share the same singularities and zeros and the Riemann-Roch-type uniqueness result then proves that \( \psi_1 \) and \( \tilde{\psi}_1 \) coincide up to normalization and we denote this normalization constant by \( C_1(x, y, t_p) \). Hence \( \psi_1(P, x, y, t_p) \) has the form of
Then by Theorem 4.6 and Lemma 5.1, one infers

\[
\ln \psi_1(P, x, y, t_p) = -\eta + \frac{1}{4} q(x, y, t_p) r(x, y, t_p)
+ q(x, y, t_p) \sqrt{\eta \psi_2(P, x, y, t_p)} \psi_1(P, x, y, t_p)
\]

\[
(5.18)
\]

and

\[
-\frac{q(x, y, t_p) r(x, y, t_p)}{4} = \left( \ln C_1(x, y, t_p) + \ln \frac{\theta(z(P_{\infty+}, \hat{\mu}(x, y, t_p)))}{\theta(z(P_{\infty+}, \hat{\mu}(x, y, t_p)))} \right) x
\]

\[
\text{as } P \to P_{\infty+},
\]

\[
(5.19)
\]

\[
q(x, y, t_p) r(x, y, t_p) = \left( \ln C_2(x, y, t_p) + \ln \frac{\theta(z(P_{\infty-}, \hat{\mu}(x, y, t_p)))}{\theta(z(P_{\infty-}, \hat{\mu}(x, y, t_p)))} \right) x
\]

\[
\text{as } P \to P_{\infty-}.
\]

Then by Theorem 4.6 and Lemma 5.1, one infers

\[
q(x, y, t_p) r(x, y, t_p) = -4e^{c_{\infty}-c_{\infty+}} \frac{\theta(z(P_{\infty+}, \hat{\mu}(x, y, t_p)))}{\theta(z(P_{\infty+}, \hat{\mu}(x, y, t_p)))} \frac{\theta(z(P_{\infty-}, \hat{\nu}(x, y, t_p)))}{\theta(z(P_{\infty-}, \hat{\nu}(x, y, t_p)))}
\]

\[
(5.21)
\]

Thus, from (5.19), (5.20) and (5.9), one gets

\[
C_1(x, y, t_p) = \frac{\theta(z(P_{\infty+}, \hat{\mu}(x, y, t_p)))}{\theta(z(P_{\infty+}, \hat{\mu}(x, y, t_p)))} \times \exp \left( -\frac{1}{4} \int_{x_0}^{x} q(x', y, t_p) r(x', y, t_p) dx' \right)
\]

\[
= \frac{\theta(z(P_{\infty+}, \hat{\mu}(x, y, t_p)))}{\theta(z(P_{\infty+}, \hat{\mu}(x, y, t_p)))} \times \exp \left( e^{c_{\infty}-c_{\infty+}} \int_{x_0}^{x} \frac{q(x', y, t_p) r(x', y, t_p) dx'}{\theta(z(P_{\infty+}, \hat{\nu}(x', y, t_p))) \theta(z(P_{\infty-}, \hat{\nu}(x', y, t_p)))} \right),
\]

\[
(5.22)
\]

\[
C_2(x, y, t_p) = \frac{\theta(z(P_{\infty-}, \hat{\mu}(x, y, t_p)))}{\theta(z(P_{\infty-}, \hat{\mu}(x, y, t_p)))} \times \exp \left( \frac{1}{4} \int_{x_0}^{x} q(x', y, t_p) r(x', y, t_p) dx' \right)
\]

\[
= \frac{\theta(z(P_{\infty-}, \hat{\mu}(x, y, t_p)))}{\theta(z(P_{\infty-}, \hat{\mu}(x, y, t_p)))} \times \exp \left( -e^{c_{\infty}-c_{\infty+}} \int_{x_0}^{x} \frac{q(x', y, t_p) r(x', y, t_p) dx'}{\theta(z(P_{\infty+}, \hat{\nu}(x', y, t_p))) \theta(z(P_{\infty-}, \hat{\nu}(x', y, t_p)))} \right),
\]

\[
(5.23)
\]
On the other hand, taking into account the asymptotic behavior of both sides in (5.21) and (5.22) for \( P \to P_{\infty^+} \), one infers

\[
q(x, y, t_p) = q(x_0, y_0, t_p, 0)C_1(x, y, t_p)^2 \frac{\theta(z(P_{\infty^-}, \hat{\mu}(x, y, t_p)))}{\theta(z(P_{\infty^-}, \hat{\mu}(x_0, y_0, t_p)))} \\
\times \frac{\theta(z(P_{\infty^+}, \hat{\mu}(x, y, t_p)))}{\theta(z(P_{\infty^+}, \hat{\mu}(x_0, y_0, t_p)))} \\
= q(x_0, y_0, t_p, 0)\frac{\theta(z(P_{\infty^-}, \hat{\mu}(x_0, y_0, t_p)))}{\theta(z(P_{\infty^+}, \hat{\mu}(x_0, y_0, t_p)))} \\
\times \frac{\theta(z(P_{\infty^+}, \hat{\mu}(x, y, t_p)))}{\theta(z(P_{\infty^-}, \hat{\mu}(x, y, t_p)))} \times \exp \left( 2e^{c_{\infty^-}-c_{\infty^+}} \right) \\
\int_{x_0}^x \frac{\theta(z(P_{\infty^-}, \hat{\mu}(x', y, t_p))) \theta(z(P_{\infty^+}, \hat{\mu}(x', y, t_p)))}{\theta(z(P_{\infty^-}, \hat{\mu}(x', y, t_p)))} \, dx', \quad (5.24)
\]

and

\[
r(x, y, t_p) = -q(x_0, y_0, t_p, 0)C_2(x, y, t_p)^2 \frac{\theta(z(P_{\infty^-}, \hat{\nu}(x, y, t_p)))}{\theta(z(P_{\infty^-}, \hat{\mu}(x_0, y_0, t_p)))} \\
\times \frac{\theta(z(P_{\infty^+}, \hat{\nu}(x, y, t_p)))}{\theta(z(P_{\infty^-}, \hat{\mu}(x_0, y_0, t_p)))} \\
= -q(x_0, y_0, t_p, 0)\frac{\theta(z(P_{\infty^-}, \hat{\nu}(x_0, y_0, t_p)))}{\theta(z(P_{\infty^-}, \hat{\mu}(x_0, y_0, t_p)))} \times \frac{\theta(z(P_{\infty^-}, \hat{\nu}(x, y, t_p)))}{\theta(z(P_{\infty^-}, \hat{\mu}(x, y, t_p)))} \\
\times \exp \left( -2e^{c_{\infty^-}-c_{\infty^+}} \int_{x_0}^x \frac{\theta(z(P_{\infty^-}, \hat{\nu}(x', y, t_p))) \theta(z(P_{\infty^+}, \hat{\nu}(x', y, t_p)))}{\theta(z(P_{\infty^-}, \hat{\nu}(x', y, t_p)))} \, dx' \right), \quad (5.25)
\]

Moreover, (5.15) follows from (5.24) and (5.25) by taking \((x, y, t_p) = (x_0, y_0, t_p, 0)\).

Finally, the linearization property of the Abel map in (5.21) and (5.17) is a standard investigation of the differentials

\[
\Omega_i(x, y, t_p) = d \ln(\psi_i(\cdot, x, y, t_p)), \quad i = 1, 2,
\]

or standard Lagrange interpolation procedure (see \[18\], \[42\]).

Thus, the results of theorem 2.1 and theorem 5.2 enable us to construct the algebro-geometric solutions of the whole mKP hierarchy.

**Theorem 5.3.** Assume spectral curve defined in (5.3) is nonsingular and \( q, r \) satisfy (2.50). Moreover, let \( P \in X \setminus \{P_{\infty^-}\} \) and the divisors \( D_{\hat{\nu}(x,y,t_p)} \).
\[ D_{\hat{\mu}(x,y,t_p)} \] are nonspecial. The algebro-geometric solutions of \( p \)th mKP equation \((p \geq 2)\) possess the following theta function representation

\[
u(x,y,t_p) = 2^p c_0 \frac{\theta(\zeta(P_{\infty}, \hat{\mu}(2x, -y, -(-2)^{p-1}t_p)))}{\theta(\zeta(P_{\infty}, \hat{\mu}(2x, -y, -(-2)^{p}t_p)))} \frac{\theta(\zeta(P_{\infty}, \hat{\nu}(2x, -y, -(-2)^{p}t_p)))}{\theta(\zeta(P_{\infty}, \hat{\nu}(2x, -y, -(-2)^{p-1}t_p)))}.
\]

(5.26)

where the constant \( c_0 \in \mathbb{C} \) is the same with that in theorem 5.2.

**Remark 5.4.** Here we consider the special case \( p = 2 \).

(i) In the case \( p = 2 \), the expression (5.26) yields algebro-geometric solutions of the mKP equation and real algebro-geometric solutions of the mKP equation can easily obtained from (5.10) and (5.11) by studying reduction condition \( q = \pm \bar{r} \).

(ii) The spectral curve of the mKP equation (1.1) is hyperelliptic which compactified by two different points \( P_{\infty} \) at infinity. Similarly we can discuss algebro-geometric solution of the mKP hierarchy on some specific trigonal curves following this way. Moreover, if the solution (5.26) is independent of \( y \), then we can derive theta function representations for algebro-geometric solutions of modified KdV equation.

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