Do Walking Muscle Synergies Influence Propensity of Severe Slipping?

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Slipping is frequently responsible for falling injuries. Preventing slips, and more importantly severe slips, is of importance in fall prevention. Our previous study characterized mild slipping and severe slipping by the analysis of muscle synergies. Significant discrepancies in motor control of slipping have been observed between mild and severe slippers. We are further interested in whether differences exist in baseline motor control patterns between persons who experience mild and severe slips when exposed to a slippery contaminant. This study investigated walking with a muscle synergy approach to detect if walking muscle synergies differ between groups experiencing different slip severities. Twenty healthy young adults (eight mild slippers and 12 severe slippers) participated in this study and their muscle synergies of walking were extracted. Muscle synergy analysis showed that mild slippers had a higher contribution of hamstring and quadriceps during walking while severe slippers had increased contribution of the tibialis group. This study provides novel information that may contribute to identifying diagnostic techniques for identifying persons or populations with a high risk of fall based on their walking patterns.

Keywords: motor control, muscle synergy, slip, gait, fall

INTRODUCTION

In 2015, 17% of the fatal injuries were caused by slips, trips, and falls (Bureau of Labor Statistics US Department of Labor, 2016a). Also, 27% of the total non-fatal occupational injuries in 2015 were caused by slips, trips, and falls, emphasizing the adverse consequences of the slipping and falling. Most importantly, “fall on the same level” was identified as the leading event contributing to days-away-from-work cases during 2015 (Bureau of Labor Statistics US Department of Labor, 2016b). Slips are the main trigger to falling, and considering the detrimental effect of the falls,

Abbreviations: CNS, central nervous system; SD, standard deviation; PHS, peak heel speed (during a slip); PVC, polyvinyl chloride; L, leading; T, trailing; MH, medial hamstring; TA, tibialis anterior; VL, vastus lateralis; MG, medial gastrocnemius; VAF, variance accounted for; FFA, foot-floor angle.
confronting slips, as the main contributors to falling, should be a priority. Additionally, not all slips impose the same risk. “Severe slips” are more prone to result in a fall compared to “mild slips.” Hence, studying “severe slips” (in order to prevent them) is a necessary step toward fall prevention.

Numerous research articles have argued that motor control of the body’s complex muscular system is reduced to a lower-dimensional modular control by the central nervous system (CNS; d’Avella et al., 2003; Ting and Macpherson, 2005; Tresch and Jarc, 2009). These modules, also known as muscle synergies, have been extracted for various motor tasks [e.g., walking, slipping, swimming (d’Avella and Bizzi, 2005; Clark et al., 2010; Nazifi et al., 2017a,b)] and can potentially represent physical subtasks of the original motor task (Neptune et al., 2009; Nazifi et al., 2017b). On the other hand, prior research has indicated the potential influence of motor control during gait on an individual’s risk of falling. Moyer et al. (2006) used kinematic metrics of human gait (e.g., cadence) to evaluate an individual’s risk of experiencing a severe slip, indicating the link between gait parameters and slip severity. Given that muscle activations can imperatively affect the resulting kinematics, one may suspect that a similar link might relate slip severity to the lower extremity muscle activation patterns during walking. This speculation is also substantiated by our previous study claiming that the CNS muscle activation patterns during walking represent the neural control of the gait, the observed discrepancies in different severity groups may potentially show the effect of the neural control of the gait on slip severity. Such knowledge is valuable as it may potentially result in a novel diagnosis method that only relies on walking behavior of subjects to eventually predict their slip severity.

In sum, this study intends to understand how muscle synergies observed during walking differ for the individuals who were classified as severe slippers compared to those who were classified as mild slippers. We hypothesize that muscle synergies of walking will differ between mild and severe slippers. Since the walking muscle synergies represent the neural control of the gait, the observed discrepancies in different severity groups may potentially show the effect of the neural control of the gait on slip severity. Such knowledge is valuable since each muscle synergy is shown to be associated with a physical subtask of a gross motor task (Nazifi et al., 2017b). Hence, comparing walking muscle synergies is equivalent to identifying the walking subtasks that differ between mild and severe slips. These differences in walking muscle synergies may help pinpoint the underlying limb coordination and walking habits that may contribute to a higher risk of fall on a slippy surface and can potentially be used in the development of programs for slip/fall prevention, diagnosis, and rehabilitation.

**MATERIALS AND METHODS**

**Subjects**

A total number of 20 healthy young adults (nine females, 11 males) with an average age of 23.6 years old (SD = 2.52 years) participated in this study. Our previous studies (Nazifi et al., 2017a,b) showed that 18 subjects can provide enough power (effect size = 1.28, power = 0.8) for statistical analysis. Subjects had no history of illnesses affecting gait (e.g., musculoskeletal, neurological, and cardiovascular). All subjects signed the written consent forms prior to participation in this IRB-approved experiment at the University of Pittsburgh. Upon a secondary approval from IRBs of University of Pittsburgh and Texas A&M University, the anonymized data were analyzed in Texas A&M University for the current study.

**Procedures**

Subjects were asked to walk at their comfortable speed along a 10-m pathway with an embedded force plate at the middle. There were two or three practice trials before the main walking trial (i.e., data recording trial). The starting point was adjusted in each trial to make subjects step on the force plate with their right limb. All subjects were provided with polyvinyl chloride (PVC) soled shoes in their size to control the coefficient of friction across all the subjects. Subjects donned a harness to protect them from any potential injuries due to slipping during testing.

After the practice trial, subjects performed a normal walking trial during which the EMG signals and markers data were recorded for synergy extraction. After the normal walking trial, without informing the subjects of a change in walkway condition, a slippery solution was applied to the force plate. The slippery solution was a diluted glycerol solution, with 75% glycerol and 25% water, that has shown promise in providing a slippy surface by other researchers (Moyer et al., 2006; Chambers and Cham, 2007; Beschorner and Cham, 2008). The coefficient of friction was 0.53 and 0.03 for the dry and slippery conditions, respectively. Then, subjects performed an unexpected “slip trial” to classify the subjects into different severity groups (Figure 1). To minimize the audible and visible cues and ensure an unexpected slip, we administered the following: we dimmed the lights during the whole experiment. Also, between the trials, subjects were asked to look away from the walkway, while listening to loud music for 1 min. Next, subjects were asked to turn around to face the walkway again, place their feet on the instructed location, and start walking on the signal. Subjects were also asked to keep their eyes on a target at eye-level on the wall (i.e., horizon). The slipping trial was recorded only to classify subjects into either mild or severe slippers while the main data analyzed in this study were the walking behavior of the subjects.

Throughout the walking trials, bilateral EMG signals were recorded at 1,080 Hz from medial hamstring (MH), tibialis anterior (TA), vastus lateralis (VL), and medial gastrocnemius [MG; right/leading/slipping leg (L) and left/trailing/non-slipping leg (T); Figure 1]. A motion capture system (Vicon 612, Oxford, UK) was utilized to capture leg kinematics at 120 Hz.

**Data Analysis**

The peak heel speed (PHS) of each subject was used as representative of slip severity using the markers data. Upon recording the walking data, the slip data were used to classify subjects into severe and mild slippers. Persons with a PHS higher than 1.44 m/s were considered severe slippers (Lockhart et al., 2003) while others were labeled as mild slippers.
A $t$-test was used to identify potential inter-group differences in weight, height, and age between mild and severe slippers. Also, a Pearson’s chi-squared test was performed to examine if there was a significant difference between genders of mild and severe slippers (Table 1).

EMG signals were processed (demeaned, rectified, and filtered) for the walking trial according to previously described procedures (Nazifi et al., 2017b). EMG was then normalized to the maximum activity of each muscle for each subject throughout all of his/her walking and slipping trials. The force plate data were used only to detect the heel strike moment and the gait duration was normalized to 100 points (0 being the first right heel strike, 50 being left heel strike, 100 being the second right heel strike) and an iterative non-negative matrix factorization technique was used to extract walking muscle synergies (Nazifi et al., 2017b) and their coefficients from the normalized gait cycle for each subject (Nazifi et al., 2017a). Prior studies (Nazifi et al., 2017a,b) indicated that, for walking, four muscle synergies are enough to account for more than 95% of the EMG variability during walking (Nazifi et al., 2017b). Hence, four walking muscle synergies were extracted from each subject (Figure 2). We wish to emphasize that the slipping trial was performed only to classify the subjects into potential mild and severe slippers, and the synergy analysis was performed only on walking trials.

Statistical analysis revealed differences in both walking muscle synergies and their activation coefficients (Figure 2). Significant difference contributions of three muscles were found. The different contributions belonged to MH_T, TA_T, and VL_L muscles. MH_T and VL_L muscle had a significantly higher activation in mild slippers, while a higher activation of TA_T was associated with severe slipping (Figure 2, walking muscle synergy 1 and 3, i.e., W1 and W3). The inter-group comparison also found differences in activation of the first and the third walking muscle synergies (Figure 2, C1 and C3). Bonferroni’s 95% confidence interval showed a divergence in the first synergy’s coefficient “C1” between mild and severe slippers from 11 percent to 15 percent (Figure 2) of the gait cycle (Table 1). A higher activation of C1 in the aforementioned period was associated with mild slips. Also, the activation coefficient of the third muscle synergy, “C3” was higher in mild slippers from 37 percent to 45 percent (Figure 2) of the gait cycle according to the same analysis.

**RESULTS**

From the unexpected slip trial, PHS measurement classified 12 subjects as mild slippers and eight subjects as severe slippers. No significant differences were found in sex, height, mass, and age across severity levels (Table 1). According to our previous studies, four muscle synergies were enough to account for more than 95% of the EMG variability during walking (Nazifi et al., 2017b). Hence, four walking muscle synergies were extracted from each subject (Figure 2). We wish to emphasize that the slipping trial was performed only to classify the subjects into potential mild and severe slippers, and the synergy analysis was performed only on walking trials.

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**DISCUSSION**

The results have indicated that a higher activation of the MH muscle right before the heel strike is associated with less severe slips (Figure 2, MH_T right before the trailing limb’s heel strike at 50%). This point can be seen in both higher contribution of MH_T in the third synergy (W3), and in its higher activation coefficient (C3), right before the trailing limb’s heel strike (which happens around 50%). Hamstring muscle is known to be involved in deceleration of the swing (same as trailing here) leg in right before the heel strike.
(Basmajian and De Luca, 1985; Medved, 2000; Rose and Gamble, 2005; Lockhart and Kim, 2006), hence contributing to less slip severity by reducing the heel velocity at the moment of heel strike. According to a prior study from this group (Nazifi et al., 2017a), a relatively similar subtask was found to be associated with one of the slipping muscle synergies, where subjects with a higher contribution of Hamstring group during slipping experienced less severe slips (Nazifi et al., 2017a). This fact further clarifies the key role that the hamstring group plays in fall prevention and slip recovery. Interestingly, as the MH contribution is higher both after a novel slip initiation according to Nazifi et al. (2017a) and Yang and Pai (2010) and before slip initiation (i.e., in this study, walking trials), it is probable that not only does the hamstrings group have a reactive role in fall prevention but it also may have a proactive role.

Moreover, prior studies on walking muscle synergies found one of the synergies to be responsible for the “load acceptance” synergy (Nazifi et al., 2017b). This synergy prepared the weight to be shifted from the trailing limb to the leading limb. Despite the different scope of the studies, a comparable pattern was found in W1 in this study and is considered to be associated with the load acceptance. Statistical analysis of this synergy shows that a higher activation of the VL muscle right after the heel strike is associated with less severity in slips. This conclusion was made upon the observation of a higher contribution of VL_L in W1 along with a higher activation in C1, right after the leading limb’s heel strike (which happens around 0%, Figure 2). Considering the role of VL in load acceptance, this conclusion remains consistent with existing studies claiming that a late activation of the VL may reduce the forward velocity of the center of mass relative to the base of support, resulting in less stability (Cham and Redfern, 2001; Chambers and Cham, 2007). In other words, mild slippers had a higher activation on their load acceptor muscle (VL_L) shortly after the leading limb’s heel contact, enabling them to transfer their weight with more support.

The third muscle synergy suggests a toe lift behavior. Based on the contribution of each muscle, it is likely that this synergy contributes to elevation of the toes right before the heel strike, probably to avoid tripping or foot drop. However, there was an association between higher activation of the TA muscle

| TABLE 1 | Demographics of different severity groups and the resulting statistical analysis. |
|-----------------|-----------------|-----------------|-----------------|-----------------|
| Mean ± SD (Unit) | PHS (m/s)       | Age            | Mass (Kg)       | Height (cm)     |
| Mild            | 0.63 ± 0.25     | 24.17 ± 2.79   | 68.41 ± 11.89   | 171.75 ± 8.59   | 5/7             |
| Severe          | 1.87 ± 0.27     | 22.75 ± 1.48   | 70.00 ± 11.37   | 175.19 ± 7.57   | 6/2             |
| p-value         | 0.001 >**       | 0.228          | 0.798           | 0.395           | 0.142           |

Please note that Pearson's chi-squared test was used for sex while an independent t-test was used for the others. * indicate significant differences.
before the heel strike and high slip severity. TA_T muscle had a higher contribution in the third muscle synergy (W3). It was previously shown that severe slippers’ high activation of TA right before their heel strike increases their foot-floor angle (FFA) significantly and was found to be associated with their severe slips (Nazifi et al., 2017a). An excessive dorsiflexion and FFA right before the heel strike also challenges achievement of flat-foot and recovery (Chambers and Cham, 2007). It is also known that a reduced FFA (i.e., flat-foot walking) is a strategy used by individuals to increase dynamic stability of the gait (Strandberg and Lanshammar, 1981; Marigold and Patla, 2002; Gao and Abeysekera, 2004; Bhatt et al., 2006). Finding of an excessive contribution from TA muscle in walking muscle synergies of severe slippers verifies our findings about a correlation between FFA and propensity to falls while normal walking.

CONCLUSION

This study examined the walking muscle synergies and their differences for different slip severities. We found significant differences in the walking muscle synergies of mild and severe slippers. This study provides a basis for a potential diagnostic method to identify the vulnerable population and people with high risk of fall based on solely their walking pattern and improves their safety and, consequently, quality of life. Such a diagnosis method will be valuable as it does not require an actual slip trial once a predictive model is developed. There were a few limitations to our study. Our study was performed only on young adults and can be significantly improved by including older populations. Also, as falls impose more detrimental consequences on the older adults, our future studies would test the differences between mild and severe slippers in older populations. Moreover, this study only targeted unexpected slips. A potential difference can be present between the response to unexpected and expected slips that can be addressed in future. Also, only eight major muscles (i.e., four muscles per limb) were studied. Future studies can resolve this limitation by studying more muscles that may contribute to human gait. Future studies will also develop and study the effectiveness of a predictive model in identifying severe slippers. Another limitation of this study is the limited number of subjects. A future study is needed to confirm the findings in a larger group. Also, although our statistical analysis did not find the slip severity to be gender-related, since prior studies have shown gender-related discrepancies in walking patterns (Cho et al., 2004), gender’s association with slip severity will be studied in a larger data set. Lastly, this study has not controlled for footedness of the subjects and it can be improved by controlling the footedness of each subject upon heel strike on a slippery surface.

DATA AVAILABILITY STATEMENT

The datasets generated for this study are available on request to the corresponding author.

ETHICS STATEMENT

The studies involving human participants were reviewed and approved by Texas A&M University’s IRB and University of Pittsburgh IRB. The patients/participants provided their written informed consent to participate in this study.

AUTHOR CONTRIBUTIONS

MN and PH contributed with data analysis, data interpretation, and writing. KB contributed to data analysis, interpretation and provided help for writing.

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Conflict of Interest: The authors declare that the research was conducted in the absence of any commercial or financial relationships that could be construed as a potential conflict of interest.

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