Hierarchical Subdivision of the Simple Cubic Lattice

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The simple cubic lattice defines a set of points at regular distances. The volume of the Voronoi cells around each point may serve as a weight for integration over the entire space. We add interstitial points to this grid according to the rule that these have maximum distance to the existing points, or by the equivalent rule that they are placed at the vertices of the Voronoi cells of the existing lattice. Choices of that kind appear in numerical sampling with maximum independent data points if the numerical expense of computing values represented at the lattice points is high. The volumes and shapes of the Voronoi cells of these enriched/supersampled lattices are discussed in detail while this insertion is recursively executed three times in succession.

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I. THEME

Some numerical schemes sampling space with finite elements for interpolation or integration may employ mesh refinement techniques which start from a coarse grid of mesh points and build finer grids with denser point sets at latter stages. The requirements of (i) efficient use of the values samples at previous stages, and (ii) maximum independent information contributed by the refined stages will be embodied in this manuscript by the following recipe and guideline: Place points of the new, refined stages at interstitial positions of the previous grid such that they have maximum Euclidean distance to the points of the previous grid.

Other criteria based on Fourier amplitudes are possible and have been applied to symmetry-adapted sampling of the reciprocal lattice [3, 5, 9].

This idea will be worked out by starting from the square or hexagonal grid in two dimensions and as warm-up, then the simple cubic lattice in three dimensions. These grids are the basic ones because coding the lattice points in Cartesian coordinates is as simple as running with integer lattice coordinates independently through the base vectors of their lattices.

II. TWO-DIMENSIONAL TEMPLATES

A. Square Grid

The simplest coverage of the plane by a point grid is the square grid with lattice points placed at

$$\mathbf{p} = i\mathbf{e}_1^{(0)} + j\mathbf{e}_2^{(0)},$$

(1)

where the two unit vectors \(\mathbf{e}_1^{(0)}\) point from the Cartesian coordinates \((0, 0)\) at the origin to \((a, 0)\) and \((0, a)\). \(a\) is the lattice constant, and \(i\) and \(j\) run through all integers of both signs.

There are two evident choices for the unit cell:

- The primitive unit cell is a square and stretches from one lattice point to the two nearest neighbors at distance \(a\) to the right and up, and along diagonals of the square to the second nearest neighbors at distance \(\sqrt{2}a\).

- The Wigner-Seitz (WS) (or Voronoi) unit cell uses the Brillouin zone construction of solid state physics. Between each pair of points in the grid, a line is drawn that cuts mid-way orthogonally through the finite line that connects the two points, and which divides space into two half-spaces. The closest polygon around a point build from the finite pieces of these lines of separation encompasses the unit cell. It is the convex polytope defined by intersection of the half-spaces. For the square grid, this unit cell is also a square of edge length \(a\), but with a lattice point in the square center.

These unit cells have area \(a^2\).

The obvious choice for an additional set of points towards a denser mesh is to add one new point at the center of each primitive unit cell. This meets the requirement of maximum distance formulated above, because these points are \(a/\sqrt{2}\) away from any of the points of the original mesh. So around these we can draw the largest circles that contain no point of the original mesh.

These points could also be found by putting them at the vertices of the WS unit cells with maximum degree (the degree being the number of WS unit cells that meet there). By construction, these vertices are as far away from as many as possible points of the original grid. The reasoning with the Voronoi cells is more satisfactory from a conceptual point of view: finding a point in the plane with largest free circumsphere tastes like a minimization problem that needs numerical treatment. On the other hand, given a point \(\mathbf{o}\) in the plane with surface normal \(\mathbf{n}\), \(\mathbf{o}\) has a unique representation \(\mathbf{o} = \alpha\mathbf{n} + \mathbf{r}\) with \(\mathbf{r} \perp \mathbf{n}\),

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\( \alpha = \mathbf{o} \cdot \mathbf{n} \), and with normal form \( Ax + By + Cz + D = 0 \), \( D = -\alpha \) of the plane, where \( A, B, C \) are the Cartesian components of \( \mathbf{n} \). Finding the common vertex of an intersection of three planes is therefore equivalent to solving a \( 3 \times 3 \) inhomogeneous linear system of equations for three unknowns \( x, y \) and \( z \). (The equivalent statements appear in the 2-dimensional problem.) With some knowledge of which three lattice points nearby a pivotal lattice point define a vertex of the Voronoi polytope, the explicit determination of the Cartesian components of the vertex is therefore easy.

The additional grid points are obviously a copy of the original grid points translated by half a diagonal. They are located at positions

\[
(i + \frac{1}{2})\mathbf{e}_1^{(0)} + (j + \frac{1}{2})\mathbf{e}_2^{(0)}
\]

with integer \( i \) and \( j \). A pleasant observation is that the union of the old and new grid points again represents a simple square grid—with smaller lattice constant \( a/\sqrt{2} \) and rotated by \( 45^\circ \) relative to the original one. This could be noted by defining the unit vectors

\[
\mathbf{e}_1^{(1)} = \frac{1}{2}(\mathbf{e}_1^{(0)} + \mathbf{e}_2^{(0)}), \quad \mathbf{e}_2^{(1)} = \frac{1}{2}(-\mathbf{e}_1^{(0)} + \mathbf{e}_2^{(0)})
\]

and accessing the union of these lattice points of two levels by

\[
i\mathbf{e}_1^{(1)} + j\mathbf{e}_2^{(1)}.
\]

This leads to a simple recursive mesh refinement: iteratively the lattice constant is divided by \( \sqrt{2} \), and the two orthogonal unit vectors are rotated alternatingly by \( 45^\circ \) to the left and to the right.

B. Triangular (Hexagonal) Grid

The fundamental areal element of the triangular grid is the isosceles triangle with side length \( a \), and two unit vectors with Cartesian coordinates

\[
\mathbf{e}_1^{(0)} = (a, 0), \quad \mathbf{e}_2^{(0)} = (-a/2, \sqrt{3}a/2)
\]

with an angle of \( 120^\circ \) between. The unit cell has an area of \( \sqrt{3}a^2/4 \). The primitive unit cell is a kite shaped quadrangle formed by two of these triangular elements glued by one side. The WS unit cell is a hexagon centered at a lattice point.

The refinement of this triangular lattice is again obvious. By any of the two methods proposed above (maximum free distance or vertices of the WS unit cell) the additional points are placed in the middle (mid-point of the circumcircle) of each the two triangles of the primitive unit cell, called the \( K \) point in solid state plane groups [11]. The first has Cartesian coordinates \((a/2, a/(2\sqrt{3}))\), the second \((0, a/\sqrt{3})\).

| count | squared distance |
|-------|------------------|
| 6     | \( a^2 \)        |
| 12    | \( 2a^2 \)       |
| 8     | \( 3a^2 \)       |
| 6     | \( 4a^2 \)       |
| 24    | \( 5a^2 \)       |
| 24    | \( 6a^2 \)       |

The union of the grid points of the original lattice and the additional points at the interstitial locations establishes another triangular lattice, rotated by \( 30^\circ \) from the original lattice. The lattice constant is shrunk to \( a/\sqrt{3} \), the nearest neighbor distance in the refined grid. So the area of the unit cell of the refined grid has shrunk by a factor \( 1/3 \) compared to the area of the original cell. The factor of three is essentially indicating that the density of the mesh points has triplicated because we added two grid points into each unit cell of the original mesh, which contained one grid point.

Similar to the finding with the square grid, this refinement preserves the grid structure, and recursive refinement is therefore a rather easy task from a programmer’s point of view. At each step, the previous unit vectors are shrunk by a factor \( 1/\sqrt{3} \) and rotated by \( 30^\circ \).

III. THREE-DIMENSIONAL GRID

A. Level 0: Simple Cubic

The starting point for an unbiased sampling in three dimensions is the Simple Cubic (SC) lattice with lattice constant \( a \), unit vectors \( \mathbf{e}_1^{(0)} = (a, 0, 0) \), \( \mathbf{e}_2^{(0)} = (0, a, 0) \), \( \mathbf{e}_3^{(0)} = (0, 0, a) \). The volume of the unit cell is

\[
V^{(0)} = a^3.
\]

Points are located at positions

\[
i\mathbf{e}_1^{(0)} + j\mathbf{e}_2^{(0)} + ke_3^{(0)}
\]

with integer coordinates \( i, j \) and \( k \).

Counting neighbors in shells of common distance to the grid points is a useful digital signature of the grid structure. For the SC lattice this statistics starts as in Table I for the smallest distances. Top to bottom, the 6 nearest neighbors are in the directions of the unit vectors \( \mathbf{e}_i^{(0)} \) and their opposites, the 12 second nearest neighbors are found at positions along the face diagonals, and the 8 third nearest neighbors are in the directions of the space diagonals [10, A005875].
TABLE II. Statistics of distances for points in the BCC lattice. [10, A004013]

| count | squared distance |
|-------|------------------|
| 8     | $\frac{1}{4}a^2$ |
| 6     | $a^2$            |
| 12    | $2a^2$           |
| 24    | $\frac{11}{4}a^2$ |
| 8     | $3a^2$           |
| 6     | $4a^2$           |
| 24    | $\frac{19}{4}a^2$ |
| 24    | $5a^2$           |
| 24    | $6a^2$           |

B. Level 1: Body-centered Cubic

The obvious first refinement places interstitial points half way along the space diagonal for another copy with points at

$$(i + \frac{1}{2})\mathbf{e}_1^{(0)} + (j + \frac{1}{2})\mathbf{e}_2^{(0)} + (k + \frac{1}{2})\mathbf{e}_3^{(0)}$$

with integer triples $i$, $j$ and $k$.

The major difference in comparison with the two-dimensional examples is that the union of these grid points does not define another simple cubic lattice but a body-centered cubic (BCC) lattice. The WS unit cell of this lattice is characterized by six squares in the directions of the six next nearest neighbors of the original unit cell plus eight hexagons in the directions of the eight new lattice points in the centers of the eight primitive cells with common vertex at $(0,0,0)$. In Brillouin zones of the corresponding space group, the mid points of the squares are labeled $X$ and the mid points of the hexagons are labeled $L$, and the vertices of the squares and hexagons are labeled $W$ [1, 4, 7].

The statistics of neighbors around the lattice points (at both levels) is indicated in Table II. The frequencies of neighbors around any of the new points at the positions (8) is the same as for the points of the zeroth level of refinement (7).

The weights associated with numerical integration are the volumes of the Voronoi cells around each lattice point. The two Voronoi cells around the points at level 0—enumerated by (7)—and around the points at level 1—enumerated by (8)—have the same shape, illustrated in Figure 1 and 2. The polyhedron of the Wigner-Seitz cell of that BCC lattice is a Truncated Octahedron with six quadratic and eight regular hexagonal faces. Figure 1 shows three of these unit cells. The two cells at the back share a common square face; the one at the front is attached to the one right at the back by a hexagon. The unit box is the primitive unit cell of the SC lattice. The volume of each Truncated Octahedron is half of the primitive unit cell,

$$V^{(1)}_\Gamma = a^3/2.$$  (9)

FIG. 1. Points on a BCC lattice (dotted squares). Three of them are surrounded by the truncated octahedra of the Wigner-Seitz cell.

FIG. 2. WS cells of the BCC lattice as in Figure 1, but with back surfaces hidden.

The upper index indicates that the volume is defined at level 1, after one refinement, and the lower label is the standard symbol for the type of symmetry of the center point of the cell.
C. Level 2: body-centered with W or X

1. Level 2: body-centered with W

The next refinement step adds points at W positions (the name of the points at the 24 vertices of the truncated octahedra in the associated Brillouin zone of the face-centered cubic lattice).

The coordinate triples of W on the left, bottom and front faces of the primitive unit cell of the SC are

\[ i\mathbf{e}_1^{(0)} + (j + \frac{1}{4})\mathbf{e}_2^{(0)} + (k + \frac{1}{2})\mathbf{e}_3^{(0)}, \]
\[ i\mathbf{e}_1^{(0)} + (j + \frac{3}{4})\mathbf{e}_2^{(0)} + (k + \frac{1}{2})\mathbf{e}_3^{(0)}, \]
\[ i\mathbf{e}_1^{(0)} + (j + \frac{1}{2})\mathbf{e}_2^{(0)} + (k + \frac{3}{4})\mathbf{e}_3^{(0)}, \]
\[ (i + \frac{1}{4})\mathbf{e}_1^{(0)} + (j + \frac{1}{2})\mathbf{e}_2^{(0)} + (k + \frac{1}{2})\mathbf{e}_3^{(0)}, \]
\[ (i + \frac{3}{4})\mathbf{e}_1^{(0)} + (j + \frac{1}{2})\mathbf{e}_2^{(0)} + (k + \frac{3}{4})\mathbf{e}_3^{(0)}, \]
\[ (i + \frac{1}{2})\mathbf{e}_1^{(0)} + (j + \frac{1}{4})\mathbf{e}_2^{(0)} + (k + \frac{3}{4})\mathbf{e}_3^{(0)}, \]
\[ (i + \frac{1}{2})\mathbf{e}_1^{(0)} + (j + \frac{3}{4})\mathbf{e}_2^{(0)} + (k + \frac{3}{4})\mathbf{e}_3^{(0)}, \]
\[ (i + \frac{1}{2})\mathbf{e}_1^{(0)} + (j + \frac{1}{2})\mathbf{e}_2^{(0)} + (k + \frac{3}{4})\mathbf{e}_3^{(0)}, \]

with integer \( i, j \) and \( k \).

A W point is also a point of maximum free range in the BCC lattice. The common distance between \((0, a/4, a/2)\) and its four nearest neighbors at \((0, 0, 0), (-a/2, a/2, a/2), (a/2, a/2, a/2)\) and \((0, 0, a)\) is \(\sqrt{5}a/4 \approx 0.55902a\).

Since each of the 24 W points is shared by two primitive unit cells of the SC lattice, adding the W points adds 12 points to the primitive unit cell, for a total of 14 once the 2 points already present at the previous levels of refinement are included. An alternative way of counting what is inside the WS cell of the BCC lattice looks as follows: each of the 24 W points is shared by 4 Wigner-Seitz cells that meet at each W. Adding W points therefore adds 24/4 = 6 points to the Wigner-Seitz cell of the BCC lattice for a total of 7.

After these points at W positions have been added to BCC lattice, the statistics of shells of neighbors around the Γ-points is gathered in Table III. The statistics of shells of neighbors around the W-points is obviously different: Table IV.

| count | squared distance |
|-------|------------------|
| 24    | $\frac{1}{16}a^2$ |
| 8     | $\frac{3}{4}a^2$  |
| 24    | $\frac{13}{16}a^2$ |
| 6     | $a^2$            |
| 48    | $\frac{5}{16}a^2$ |
| 72    | $\frac{29}{16}a^2$ |

TABLE III. Statistics of distances for points with Γ-symmetry after the W points have been added to the BCC lattice.

| count | squared distance |
|-------|------------------|
| 4     | $\frac{1}{2}a^2$  |
| 2     | $\frac{1}{4}a^2$  |
| 4     | $\frac{1}{16}a^2$ |
| 8     | $\frac{3}{8}a^2$  |
| 8     | $\frac{5}{8}a^2$  |
| 8     | $\frac{7}{8}a^2$  |

TABLE IV. Statistics of distances for points with W-symmetry after the W points have been added to the BCC lattice.

The weights of the two kinds of points in numerical integration are the volumes of their Voronoi cells, computed in Appendix A:

\[ V_W^{(2)} = \frac{125}{1152}a^3; \quad V_W^{(2)} = \frac{451}{6912}a^3; \quad 2V_W^{(2)} + 12V_W^{(2)} = V^{(0)}. \]

The generic algorithm to determine the volumes of polyhedra is to acquire the Cartesian coordinates of all vertices, to define the face set as a set of co-planar triangles and to sum the contribution of each triangle (with outward orientation of the face normal) to the volume with the divergence theorem. The contribution of each triangle is a sixth of the scalar triple product of the three vectors from the origin of coordinates to the triangle’s vertices.

2. Level 2: body-centered plus X

That growth proposed in Section III C 1 for the number of points by a factor 7 compared to the BCC level may be too drastic for some applications. So in engineering practise one could as well add the X points at mid-points of the square faces of the BCC lattice, although their free range to their 2 nearest neighbors (the cube centers) is only \(a/2\), smaller than the free range of the W. The X are shared between two WS cells of the BCC lattice, so the total number of points in the WS unit cell of the BCC lattice raises by 3 to a total of 4.

With the simplified setup proposed above, the Level 2 grid points contain the SC points of (7), the body-centereded of (8) and—after a glance at Figure
FIG. 3. Geometry of the Tetrakis Hexahedra encapsulating the Γ points of the level 2 lattice. The edge length $e - e'$ of the cube is $5a/12$.

1—also the face-centered and edge-centered grid points. They have distance $a/2$ to their next nearest neighbors. In the language of Brillouin zones one could call these points $M$ points of the (level 0) Wigner-Seitz cell.

At that level, the full set of refined grid points is a SC lattice with lattice constant $a/2$, volume $a^3/8$ in the unit cell, and the same directions of its unit vectors as the host grid of level zero. In the SC unit cell of level 0 we started with one point per unit cell, added one point per unit cell at level 1, added three $X$ and three $M$ points per unit cell at level 2, such that there are now 8 lattice points per level 0 unit cell.

The benefit of that choice of adding points is equivalent to the one illustrated two refinements of the plane in Section II: Adding more points at finer levels onwards is a procedure continuing recursively with the procedure in Section III B, because the levels zero and three contain congruential sets of lattice points. The analysis is in that sense complete if points at $X$ had been added at level 2.

D. Level 3: body-centered with $W$ and $\Lambda$

If the points at $W$ have been added in level 2, the points with maximum minimum distance to be added in the next refinement of level 3 are located on the $\Lambda$-line of the space diagonal at $(\frac{5}{24}a, \frac{5}{24}a, \frac{5}{24}a)$. [This is close to but not precisely at the $L$ which is at $(\frac{1}{4}, \frac{1}{4}, \frac{1}{4})$;] There are three replicas of this point with the same point group symmetry along the space diagonal at $(\lambda a, \lambda a, \lambda a)$ with $\lambda = 1/2 - 5/24 = 7/24$, $1/2 + 5/24 = 17/24$ and $1 - 5/24 = 19/24$. Each point of these quartets adds equivalent positions on the other three space diagonals; so there are $4 \times 4 = 16$ new lattice points added here in level 3 for a combined total of 30 in the primitive SC unit cell.

The distance of this point $(5a/24, 5a/24, 5a/24)$ to its 7 nearest neighbors is $5\sqrt{3}/24a \approx 0.3608439a$. The set of 7 nearest neighbors contains $(0, 0, 0)$ and 6 $W$-points of the list (10), $(0, a/4, a/2)$, $(0, a/2, a/4)$, $(a/4, a/2, 0)$, $(a/2, a/4, 0)$, $(a/4, 0, a/2)$, $(a/2, 0, a/4)$. The geometric interpretation of these coordinates looks as follows: After the $W$-points have been added to the lattice, the Voronoi

FIG. 4. Voronoi Octahedron encapsulating the $W$ points of the level 2 lattice. The set of faces contains 4 regular triangles and 4 hexahedra. Each face normal of a triangle center is a 3-fold rotation axis.

FIG. 5. Level 2 dissection of the unit cell with lattice points at $\Gamma$ (the BCC lattice points) and at $W$. The Voronoi cells around the $\Gamma$ points have the shape of Figure 3; five of them are shown. The cells around the $W$ points have the shape of Figure 4; only one of these is shown. Each pair of cells around $\Gamma$ at a mutual distance $a$ are connected by 4 cells around the four intermediate $W$, which share the 4-fold rotation axis that runs through $X$. 
cell around the Γ-points are 24-hedrons (Tetrakis Hexahedra) with flat square pyramids glued to each side of a cube around the Γ-point (Figure 3).

The cube inside has an edge length of $5a/12$, so its eight vertices have coordinates of $±5a/24$.

The Voronoi cells around the $W$-points at level 2 are 8-hedrons (Figure 4) with 4 triangles that touch the triangles of the truncated octahedra and 4 irregular hexagons that touch 8-hedrons of adjacent $W$-points. The short sides of the hexagons are the residual left from the distance of $\sqrt{3}a/2$ between two truncated octahedra along the space diagonal after removal of the diagonals inside the two cubes of the truncated octahedra, $\sqrt{3}a/2 - 2 \times \sqrt{3}a/24 = \sqrt{3}a/12 ≈ 0.1443376a$. Two such edges are the two rightmost edges of the 8-hedron in Figure 6 that each join two of the Tetrakis Hexahedra.

The points added here at level 3 are those vertices around the $W$ Voronoi cell where a triangle meets a short edge of the hexagon. At these points the Tetrakis Hexahedron of the Voronoi cell around the Γ-points meets 6 Voronoi cells of $W$-points. They lie on the axes with 3m symmetry (along the space diagonal) of the SC lattice.

The factor $5/24$ that fixes the position of the new Λ points is then found by noticing that these short edges run along a space diagonal, that the projection of the new point on the $xy$ plane runs along the plane diagonal, and to solve the planar Voronoi cell problem for the triple of points $(0,0), (a/2,a/4)$ and $(a/4,a/2)$ in that plane.

The Voronoi cell around a Γ point at level 3 is an Octahedron with space diagonal $5a/8$ (all bounding box coordinates are $±5a/16$), so the edge length at the square base of the pyramid is $5a/(8\sqrt{2})$, and the volume is \[ V^{(3)}_\Gamma = \frac{125}{3072}a^3 \approx 0.04069010a^3. \] \[ (12) \]

The degeneracies of the various points in the SC lattice require

\[ 2V^{(3)}_\Gamma + 16V^{(3)}_\Lambda + 12V^{(3)}_W = a^3. \] \[ (13) \]

Taking the volume $V^{(3)}_\Lambda$ from Eq. (B1) and solving for $V^{(3)}_W$ we obtain

\[ V^{(3)}_W = \frac{24505}{663552}a^3 \approx 0.03693003a^3 \] \[ (14) \]

for the volumes associated with the $W$ points at level 3.

Finally, Figures 7–12 try to give an impression of how the three different types of Voronoi cells at level 3 subdivide the region near two points of the BCC WS cell.

**IV. SUMMARY**

Regular dissection of space with Voronoi cells on the points of the simple cubic grid assigns the volume (6) to each cell. If points are added at the body centers (8), the volume (9) is assigned to the Voronoi cells around the grid points. If another set of points is added at all $W$ positions (10), Voronoi cells of two different shapes appear, characterized by volumes defined in Eq. (11). If finally that set is augmented by points on the Λ line, space is divided by three different types of Voronoi cells with volumes of (B1), (12) and (14), respectively.
FIG. 8. Illustration of the bridging between the Octahedra of the level 3 lattice along each space diagonal of the SC lattice by pairs of Voronoi cells around the Λ points. This follows by extension of Figure 7 with mirror symmetry at the hexagonal face of the Λ cell.

FIG. 9. Level 3 Voronoi cell around any of the W points after W and Λ points have been added to the BCC lattice. It has 12 faces: two pairs of pentagons, each pair with a common long edge (right dihedral angle), plus a band of eight quadrangles that runs in between.

FIG. 10. Voronoi cells at a two Γ points plus three W cells of the shape of Figure 9 around W points after W and Λ points have been added to the BCC lattice. Each of the long edges of the pentagons of Figure 9 touches one point of an Octahedron.

FIG. 11. The configuration if a single cell of Figure 9 is added to Figure 7.

ACKNOWLEDGMENTS

Many images of Voronoi cells shown here have been created by loading stereolithography data into MeshLab [8].

Appendix A: Shape of the Voronoi cells at level 2

1. Tetrakis Hexahedra at Γ

The height of the six pyramids that cover the Tetrakis hexahedron in Figure 3 is determined by considering the mutual tilt of two planes that dissect the space from a Γ-point towards to neighboring W-points, for example Γ at (a/2, a/2, a/2), W at (0, a/2, a/4) and W at (0, a/2, 3a/4). The distances Γ → W are \( \sqrt{(1/2)^2 + 0^2 + (1/4)^2} = \sqrt{5}a/4 \). The angle of the line Γ → W versus the horizontal is \( \tan \phi = (a/4)/(a/2) \), \( \phi = \arctan \frac{1}{2} \approx 26.565^\circ \approx 0.463647 \text{ rad} [10, A073000] \).
This is the inclination of the triangles of the pyramids of the Tetrakis Hexahedron versus their cubic base, the tilt of the triangle \( c' - e - t \) versus the horizontal in Figure 3. The distance from the base \( b \) to the top \( t \) of the pyramids is a quarter of the edge length, \( 5a/16 \), because the slope of \( \phi \) is 1/2. The distance \( e - t \) is \( \sqrt{(5/24)^2 + (5/24)^2 + (5/48)^2}a = 5a/16 = 0.3125a \). This yields a height of the planar triangle of \( \sqrt{(5/16)^2 - (5/24)^2}a = 5^3/2a/48 \approx 0.23292a \). The internal angles of the triangle are \( \arccos \frac{5a/24}{5a/16} = \arccos \frac{5}{3} \approx 0.8411 \text{ rad} \approx 48.189685^\circ \) for \( e - c' - t \) [10, A228496] and the 180\(^\circ\) complement 83.62063\(^\circ\) for \( e' - t - e \). The volume of each pyramid is a third of the product of height by base area, \( (1/3) \times (5a/48) \times (5a/12)^2 = 125a^3/20736 \approx 0.00603a^3 \). The 6 pyramids plus the cube encapsulate a volume of

\[
V_{\Gamma}^{(2)} = \frac{125}{1152} a^3 \approx 0.1085a^3. \tag{A1}
\]

2. **Truncated Tetrahedra at \( W \)**

In the (irregular) truncated tetrahedra around the \( W \) points in Figure 4, the edge lengths of the triangular surfaces are the edge lengths 5a/12 and 5a/16 of the pyramids determined in Section A1. They also fix edge lengths 5a/12 and 5a/16 of the four hexagons. The missing edge length is defined by subtracting two pyramidal heights and two cube half edges from the distance \( a \) between two \( \Gamma \)-points of the lattice, proposed by the upper horizontal edge that connects two pyramidal summits in Figure 5, \( a - 2 \times 5a/24 - 2 \times 5a/48 = 3a/8 = 0.375a \). In summary, the hexagonal faces of the cell around the \( W \) points have one edge of length 5a/12, two edges of length 5a/16, two edges of length \( \sqrt{3a}/12 \), and one edge of length 3a/8.

One can reconstruct all the hexagonal surfaces starting with the vertex set of one of them, for example \((5/24)(e_1^{(0)} + e_2^{(0)} + e_3^{(0)})\), \((7/24)(e_1^{(0)} + e_2^{(0)} + e_3^{(0)})\), \((5/24)(-e_1^{(0)} + e_2^{(0)} + e_3^{(0)})\), \((7/24)(-e_1^{(0)} + e_2^{(0)} + e_3^{(0)})\), \((3/16)e_1^{(0)} + (1/2)e_2^{(0)} + (1/2)e_3^{(0)}, -3/16(e_1^{(0)} + (1/2)e_2^{(0)} + (1/2)e_3^{(0)})\), and applying the group operations of the BCC space group to it.

The volume of the Voronoi cell is determined by partitioning of the SC cell volume \( a^3 \) in (6): The volume of the cells around \( \Gamma \) points is \((A1)\). There are effectively two of them in the SC unit cell (one in the BCC body center and an eights of each of the shared points in the eight corners). There are effectively 12 cells around \( W \) per SC unit cell. Each of them needs to contribute

\[
V_{W}^{(2)} = \frac{451}{6812} a^3 \approx 0.0665128a^3 \tag{A2}
\]

to satisfy equation (11).

**Appendix B: Voronoi Cells of \( \Lambda \) at level 3**

The coordinates of points of the \( \Lambda \) cell in Figure 7 are determined as follows:

- The points on the triangular face attached to the Octahedron at \( \Gamma \) are fixed by the Octahedron, \((5/16)e_3^{(0)}, (5/16)e_1^{(0)}, \) and \((5/16)e_2^{(0)}\).

- A first vertex on the hexagonal face is at \((95/288)e_1^{(0)} + (13/144)e_2^{(0)} + (95/288)e_3^{(0)}\). It is found by construction of (i) the plane that divides the space between \( \Lambda \) at \((5/24)(e_1^{(0)} + e_2^{(0)} + e_3^{(0)})\) and \( \Lambda \) at \((7/24)(e_1^{(0)} + e_2^{(0)} + e_3^{(0)})\), of (ii) the plane that divides the space between \( \Lambda \) at \((5/24)(e_1^{(0)} + e_2^{(0)} + e_3^{(0)})\) and \( W \) at \((1/4)e_1^{(0)} + (1/2)e_3^{(0)}\), and (iii) of the plane that divides the space between \( \Lambda \) at \((5/24)(e_1^{(0)} + e_2^{(0)} + e_3^{(0)})\) and \( W \) at \((1/2)e_1^{(0)} + (1/4)e_3^{(0)}\), followed by intersection of these three planes. The other five points are obtained from this one by rotations around the space diagonal by multiples of 60\(^\circ\), \((59/144)e_1^{(0)} + (49/288)e_1^{(0)} + (49/288)e_3^{(0)}\), \((95/288)e_1^{(0)} + (95/288)e_2^{(0)} + (13/144)e_3^{(0)}\), \((49/288)e_1^{(0)} + (59/144)e_2^{(0)} + (49/288)e_3^{(0)}\), and so on.

FIG. 12. A composite of Figure 8, Figure 11 and two further cells (around a \( \Lambda \) point on a different space diagonal and around a second \( W \) point).
The missing three points that are vertices of quadrangles are at \((35/128)(e_1^{(0)} + e_3^{(0)})\), \((35/128)(e_1^{(0)} + e_2^{(0)})\), and \((35/128)(e_2^{(0)} + e_3^{(0)})\). The quadrangle is constructed by (i) the plane that divides the space between \(\Lambda\) at \((5/24)(e_1^{(0)} + e_2^{(0)} + e_3^{(0)})\) and \(\Lambda\) at \((5/24)(e_1^{(0)} - e_2^{(0)} + e_3^{(0)})\), (ii) the plane that divides the space between \(\Lambda\) at \((5/24)(e_1^{(0)} + e_2^{(0)} + e_3^{(0)})\) and \(W\) at \((1/4)e_1^{(0)} + (1/2)e_3^{(0)}\), (iii) the plane that divides the space between \(\Lambda\) at \((5/24)(e_1^{(0)} + e_2^{(0)} + e_3^{(0)})\) and \(W\) at \((1/2)e_1^{(0)} + (1/4)e_3^{(0)}\), followed by intersection of these three planes.

The volume of the Voronoi cell surrounding \(\Lambda\) points is computed by the divergence theorem, adding up the contributions of the eleven faces
- one regular hexagon,
- six quadrangles that share sides with the hexagon,
- one triangle shared with a face of the octahedron,
- and three triangles that share one side with the octahedron and two sides with two of the quadrangles.

The result is
\[
V_{\Lambda}^{(3)} = \frac{26291}{884736}a^3 \approx 0.0297162a^3. \quad (B1)
\]