Stochastic Resonance and Nonlinear Response by NMR Spectroscopy

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Let us consider a two-state quantum system whose density operator $\rho$ is represented in terms of the Bloch vector $\vec{s}$ as $\rho = (1 + \vec{s} \cdot \vec{d})/2$ i.e., $s_i(t) = \langle \sigma_i(t) \rangle$, $i = 1, 2, 3$, in the customary pseudo-spin formalism. Within the semigroup approach for open quantum systems, the most general (completely) positive relaxation dynamics induced by the coupling to some environment is described by a quantum Markov master equation of the form

$$\dot{\rho} = -\frac{i}{\hbar}[H(t), \rho] + \frac{1}{2} \sum_{k,l=1}^{3} a_{kl} \{[\sigma_k \rho, \sigma_l] + [\sigma_k \rho, \sigma_l]\}.$$

The Hamiltonian $H(t)$, which describes the interaction of the TLS with the (classical) driving field, can be expressed as $H(t) = \hbar \omega_0 \sigma_3/2 + V(t)$, $V(t) = \hbar (2\omega_1) \cos(\Omega t) \sigma_1/2$, where the Larmor frequency $\omega_0 = (E_2 - E_1)/\hbar$ associated with the TLS energy splitting and the Rabi frequency $\omega_1$ proportional to the alternating field amplitude have been introduced. The above Hamiltonian is identical to the one describing a driven tunneling process in a symmetric double-well system with “localized” states provided by $\sigma_1$-eigenstates: By rotating the spin coordinate by $\pi/2$ about the $\hat{z}$-axis, one formally recovers the picture of tunneling in the $\hat{z}$-representation that is encountered in the literature. The dissipative component of the TLS dynamics is fully characterized by the positive-definite $3 \times 3$ relaxation matrix $A = \{a_{kl}\}$, determining the equilibrium state of the system and the relaxation time scales connected with the equilibration process. The Bloch equations correspond to an especially simple realization of $A$, the non-zero elements being specified in terms of 3 independent parameters: $a_{11} = a_{22} = (2T_1)^{-1}$, $a_{33} = (T_2)^{-1}$, $a_{12} = a_{21} = i(\sqrt{2}T_1)^{-1}s_{eq}$, $T_1$, $T_2$, and $s_{eq}$ are identified as the longitudinal and transverse lifetimes, and the equilibrium value of the population difference respectively. Thus, Eq. (1) takes the following familiar form:

$$\begin{cases}
\dot{s}_1 &= \omega_0 s_2 - T_2^{-1}s_1, \\
\dot{s}_2 &= -\omega_0 s_1 - T_2^{-1}s_2 + 2\omega_1 \cos(\Omega t)s_3, \\
\dot{s}_3 &= -2\omega_1 \cos(\Omega t)s_2 - T_1^{-1}(s_3 - s_{eq}).
\end{cases}$$

In microscopic derivations of (1), including the ones based on the spin-boson model in the appropriate limit, relaxation is caused by elementary processes involving noise-assisted transitions between the TLS energy levels or purely dephasing events with no energy exchange between the system and the environment. The
overall relaxation rates $T_{1,2}^{-1}$ are obtained by integrating such fluctuation and dissipation effects over the environmental modes, weighted by the appropriate noise spectral densities. Since the latter contain the coupling strength between the system and the environment, relaxation rates are themselves directly proportional to the underlying noise intensity. Note that the above treatment in terms of a constant matrix $A$ is only valid for external fields that are relatively weak on the TLS energy scale \( i.e., 2|\omega_1| \ll \omega_0 \). In spite of the many restrictions involved, it is remarkable that the Bloch equations \( (3) \) are of such a wide applicability to cover the majority of magnetic or optical resonance experiments.

For times long compared to the time scales $T_{1,2}$ of the transient dynamics, the motion of the system reaches a steady-state behavior that is insensitive to the initial condition and acquires the periodicity of the driving. In particular, the asymptotic TLS coherence properties are captured by the off-diagonal matrix element $s_1(t), s_2(t)$. It is standard practice to formulate an input/output problem, where the TLS is regarded as a dynamical system generating $s_1(t) = \langle \sigma_1(t) \rangle$ as the output signal in response to a given input drive $V(t)$. By letting $\lim_{t \to \infty} \langle \sigma_1(t) \rangle = s_1^\infty(t)$ denote the limiting steady-state value of $s_1(t)$, a figure of merit for the system response is the so-called \textit{fundamental spectral amplitude} $\eta$, \[ \eta(\Omega, \omega_1) = |s_1^\infty(t)| = \hbar(2\omega_1)|\chi(\Omega, \omega_1)|, \] where the connection to the complex susceptibility $\chi(\Omega, \omega_1) = \chi(\Omega, \omega_1) - i\chi''(\Omega, \omega_1)$ is made explicit.

The competition between driving and dissipative forces sets the boundary between the linear vs. nonlinear response regimes. In the limit where $\omega_1 \ll T_{1,2}^{-1}$, only first-order contributions in $\omega_1$ are significant and the susceptibility $\chi(\Omega, \omega_1) = \chi(\Omega)$ in \( (3) \) can be calculated within ordinary linear response theory. The linear regime implies that absorption of energy from the applied field occurs without disturbing populations from their equilibrium value $s_{eq}$. Linear behavior breaks down whenever $\omega_1 \gtrsim T_{1,2}^{-1}$. Strongly nonlinear-response regimes can be entered for arbitrarily weak fields as long as the coupling to the environment and the induced noise effects are weak enough. For both linear and nonlinear driving, the amplitude $\eta(\Omega, \omega_1)$ of the output signal also depends on the various parameters characterizing the noise process. Quite generally, the phenomenon of stochastic resonance can be associated with the appearance of non-monotonic dependencies upon noise parameters, leading to the optimization of the response at a finite noise level.

We focus on the Bloch equations \( (3) \) with resonant driving, $\Omega = \omega_0$. It is then legitimate to invoke the rotating-wave approximation and replace the alternating field $V(t)$ with $V(t) = \hbar \omega_1 \cos(\Omega t) \sigma_1/2 - \hbar \omega_1 \sin(\Omega t) \sigma_2/2$. The rotating-frame description of the Bloch vector $\overrightarrow{\mu}$ is introduced via the time-dependent rotation $R = \exp(i\Omega \sigma_3t/2)$ i.e., $R \overrightarrow{\rho} R^{-1} = (1 + \overrightarrow{\mu} \cdot \overrightarrow{\sigma})/2$, $\overrightarrow{\mu} = (u, v, w)$. The steady-state solution to the Bloch equations is well known \( (1,2) \). In particular, $\chi'$ and $\chi''$ are read from the dispersive and absorptive components $u, v$ of the Bloch vector respectively, and the spectral amplitude $\eta(\Omega = \omega_0, \omega_1) = (u^2 + v^2)^{1/2}$. A simple expression is found for the nonlinear response:

$$
\eta(\Omega = \omega_0, \omega_1) = s_{eq} \frac{\omega_1 T_2}{1 + \omega_1^2 T_1 T_2}. \tag{4}
$$

Suppose now that we have the capability of manipulating the strength of the coupling of the TLS to its environment, thereby changing the relaxation times $T_1, T_2$. For a fixed driving amplitude $\omega_1$, $\eta$ displays purely monotonic behaviors if $T_1, T_2$ are varied independently. However, if a single relaxation time is present, $T_1 = T_2 = T_{12}$, $\eta$ develops a local maximum characterized by

$$
T_{12}^* = \omega_1^{-1}, \quad \eta(\Omega = \omega_0, \omega_1, T_{12}^*) = \frac{s_{eq}}{2}. \tag{5}
$$

The occurrence of such a peak in the steady-state response as a function of the noise strength can be pictured as a stochastic resonance effect in the TLS. Physically, the condition for the maximum in \( (5) \) can be thought of as a synchronization between the periodicity of the rotating-frame vector in the absence of relaxation and the additional time scale emerging when dissipation is present. In semiclassical terms, a constraint of the form $T_1 = kT_2, k = \text{const.}$, indicates that the spectral densities of the fluctuating environmental fields along different directions are not independent upon each other. Simple examples include noise processes that effectively originate from a single direction or that equally affect the system in the three directions. In fact, the existence of a single relaxation time is a feature shared with earlier investigations of quantum SR based on the driven spin-boson model \( (3) \), where it arises as a necessary consequence of the initial assumption that environmental forces exclusively act along the tunneling axis. However, we emphasize that our discussion is done without reference to a specific model, encompassing in principle a larger variety of physical situations.

Apart from this conceptual difference, the SR phenomenon evidenced above is characterized by the same distinctive features found for the spin-boson model on resonance \( (3) \). According to \( (3) \), the maximum steady-state response is independent of the driving amplitude, whereas the position of the peak shifts toward shorter relaxation times with increasing $\omega_1$. Thus, weaker noise strengths require weaker input fields to attain a large response. This brings the nonlinear nature of the SR mechanism to light, for weaker dissipation more easily pushes the system into a regime where $\omega_1 T_{12} \gtrsim 1$. No SR peak occurs in the limit $\omega_1 T_{12} \ll 1$ where linear response theory applies and $\eta \to s_{eq}(\omega_1 T_{12}) \ll s_{eq}$. Thus, SR results in efficient noise-assisted signal amplification. Breakdown of linear behavior is more convincingly demonstrated by looking at the dependence of the
response (4) upon the external field strength. It is easily checked that the condition (3) simultaneously optimizes the response against ω₁, with \( \omega_1^* = (T_1 T_2)^{-1/2} \). However, it is only when \( T_1 = kT_2 \) that the existence of such an optimal field amplitude coexists with a SR effect.

Nuclear Magnetic Resonance (NMR) provides a natural candidate for a direct experimental verification of the predicted phenomenon. In NMR, the Bloch equations (3) describe the motion of the magnetization vector \( \vec{M} \) of spin 1/2 nuclei (\(^1\)H) that are subjected to a static magnetic field \( B_0 \) along the \( \hat{z} \)-axis and a radio-frequency signal with amplitude \( 2|B_1| < B_0 \) applied at frequency \( \Omega \) along the \( \hat{x} \)-axis. The mapping is established by identifying \( \vec{s} = \vec{M} \), \( s_{eq} = M_0 \), \( \omega_0 = \gamma B_0 \), \( \omega_1 = \gamma B_1 \), \( M_0 \) and \( \gamma \) denoting the equilibrium magnetization and the gyromagnetic ratio respectively. Relaxation processes arise due to a multiplicity of microscopic mechanisms (12). For a liquid spin 1/2 sample, the leading contribution arises from fluctuations of the local dipolar field caused by bodily motion of the nuclei. The longitudinal relaxation time \( T_1 \) is essentially determined by the \( \hat{z} \)- and \( \hat{y} \)-components of the local magnetic fields at the Larmor frequency, while the transverse lifetime \( T_2 \) takes extra contributions from static components of the \( \hat{z} \)-field, implying that \( T_2 \leq 2T_1 \) ordinarily (3,13). Let us assume as above that \( \Omega = \omega_0 \). Once the steady state is reached, the magnetization vector \( \vec{M} \) precesses about the \( \hat{z} \)-axis with the periodicity of the r.f. field. The variation of the dipole moment in the transverse plane induces a measurable e.m.f. in a Faraday coil. This provides access to the relevant quantity \( \eta \) of Eqs. (3)-(6), which represents the length of the transverse magnetization vector, \( (\hat{u}^2 + \hat{v}^2)^{1/2} = (M_x^2(t) + M_y^2(t))^{1/2} \).

Our experiment consists in probing the steady-state magnetization response of water as a function of the noise strength inducing the natural relaxation processes. The \(^1\)H Larmor frequency at \( B_0 = 9.4 \) T is \( \omega_0/2\pi = 400 \) MHz, with relaxation times \( T_1 = 3.6 \) s, \( T_2 = 2.5 \) s. The sample can be brought to a regime where \( T_1 \approx T_2 \) upon addition of the paramagnetic salt copper sulfate (CuSO₄). With concentrations in the range between 40 mM and 100 mM, collision events with the impurity dominate the nuclear relaxation dynamics. This effectively pushes the system into a regime of rapid motion where the correlation time of the local magnetic fields seen by the nuclei is very short on the scale \( \omega_0^{-1} \), thereby ensuring that \( T_1 = T_2 = T_{12} \) (13). Higher concentrations of the CuSO₄ additive result in a shorter relaxation time \( T_{12} \) hence implying an effective tuning of the noise strength. All measurements were performed at room temperature with a Bruker AMX-400 spectrometer on five water samples with additive concentrations in the above range.

Independent measurements of \( T_1 \) and \( T_2 \) were made to confirm that the amount of CuSO₄ was sufficient to make them equal. \( T_1 \) was measured via an inversion recovery technique (13), by looking at the recovery curve of \( M_z(t) \) after the application of a \( \pi \) pulse causing \( M_z(0) = -M_0 \). Values of \( T_2 \) were inferred from the decay of the echo signals in a standard Carr-Purcell sequence where \( \pi \) rotations were used to refocus dephasing due to inhomogeneous broadening (13). For the 5 concentrations utilized, \( T_1 \) and \( T_2 \) were found to be within 1 ms of the average value \( T_{12} \) which is listed for each sample in Table I.

| CuSO₄ (mM) | \( T_{12} \) (ms) | ± 1 ms |
|-----------|------------------|-------|
| 40        | 45.5             |       |
| 50        | 36.5             |       |
| 60        | 28.5             |       |
| 75        | 25.0             |       |
| 100       | 18.0             |       |

TABLE I. Relaxation time \( T_{12} = T_1 = T_2 \) as a function of the CuSO₄ paramagnetic impurity concentration for the 5 water samples used in the experiment.

For each sample, the response to a long external r.f. pulse was measured for various values of the driving amplitude. A few remarks are in order concerning the

For the 5 concentrations utilized, \( T_1 \) and \( T_2 \) were found to be within 1 ms of the average value \( T_{12} \) which is listed for each sample in Table I.
specific case of NMR. First, the present experiment is not a stochastic NMR experiment \cite{14}. While the obvious similarity is that both methods probe the nuclear spin system by looking at the transverse magnetization response, in stochastic NMR the system is directly excited by noise, which is therefore always extrinsic (and classical) in origin. More importantly, as mentioned already, the solutions to the Bloch equation have a long history as a tool to investigate magnetic resonance behaviors. In particular, the existence of an optimum r.f. amplitude $\omega^*_1 = (T_1 T_2)^{-1/2}$ is a feature pointed out long ago by Bloch himself \cite{9}. However, only the SR paradigm provides the motivation to regard relaxation features as controllable output parameters and to look at the usual response behavior along different axes in the parameter space. Even once this is done, this does not automatically lead to SR. Rather, it is the recognition that a single axis \( T_1 = T_2 \) is effectively needed to bring out the fingerprint of the phenomenon and the novel element added to the standard NMR analysis.

In summary, we established both theoretically and experimentally the occurrence of stochastic resonance in two-state quantum systems whose relaxation dynamics are described by Bloch equations. In addition to substantially broadening the existing paradigm for stochastic resonance in quantum systems, our results point to the possibility of characterizing intrinsic relaxation behavior via resonance effects. By offering an optimized way for input/output transmission against noise, stochastic resonance carries a great potential for systems configured to perform specific signal processing and communication tasks \cite{5}. In particular, full exploitation of stochastic resonance phenomena could potentially disclose a useful scenario for reliable transmission of quantum information in the presence of environmental noise and decoherence.

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**FIG. 1.** Normalized steady-state response $\eta/s_{eq}$ vs. relaxation time $T_{12}$ for resonant driving $\Omega/2\pi = 400$ MHz at different driving amplitudes: $\omega_1/2\pi = 6.3$ Hz (circles), 5.5 Hz (crosses), 4.8 Hz (squares). Solid lines: theoretical predictions from Eq. (4), after systematic correction for the frequency (no free parameters).

**FIG. 2.** Normalized steady-state response $\eta/s_{eq}$ vs. Rabi frequency $\omega_1/2\pi$ for resonant driving $\Omega/2\pi = 400$ MHz at different relaxation times: $T_{12} = 18.0$ ms (circles), 28.5 ms (squares), 45.5 ms (diamonds). Solid lines as above.