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Intuitionistic Probability and the Bayesian Objection to Dogmatism

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Given a few assumptions, the probability of a conjunction is raised, and the probability of its negation is lowered, by conditionalising upon one of the conjuncts. This simple result appears to bring Bayesian confirmation theory into tension with the prominent dogmatist view of perceptual justification – a tension often portrayed as a kind of ‘Bayesian objection’ to dogmatism. In a recent paper, David Jehle and Brian Weatherson observe that, while this crucial result holds within classical probability theory, it fails within intuitionistic probability theory. They conclude that the dogmatist who is willing to take intuitionistic logic seriously can make a convincing reply to the Bayesian objection. In this paper, I argue that this conclusion is premature – the Bayesian objection can survive the transition from classical to intuitionistic probability, albeit in a slightly altered form. I shall conclude with some general thoughts about what the Bayesian objection to dogmatism does and doesn’t show.

I. THE BAYESIAN OBJECTION TO DOGMATISM

The dogmatist and the intuitionist seem unlikely bedfellows. And yet, according to David Jehle and Brian Weatherson (2012), the dogmatist about perceptual justification who is willing to countenance intuitionistic logic is in a strong position to resist a recent, influential criticism that has been levelled at the view – the so-called ‘Bayesian objection’ (Cohen, 2005, White, 2006). It’s intuitive to think that perceptual appearances can justify one in believing things about one’s surrounding environment without one needing antecedent justification for rejecting far-fetched sceptical hypotheses. It’s also intuitive to think that, if one has justification for believing $\varphi$ and can clearly see that $\varphi$ entails $\psi$, then one must also have justification for believing $\psi$. For present purposes, dogmatism can be taken to be the conjunction of these two claims (see Pryor, 2000, 2004). Whilst individually intuitive, these claims lead, in combination, to a rather surprising result.

Consider the following:

A: It appears to me that I have a mole on my left thigh.
M: I have a mole on my left thigh.
\( \neg (B \wedge A) \): It’s not the case that I am a brain in a vat and it appears to me that I have a mole on my left thigh.

According to the first dogmatist claim, learning \( A \) can provide me with justification for believing \( M \) without my having any antecedent justification for believing \( \neg (B \wedge A) \). But I can clearly see that \( M \) entails \( \neg B \), which entails \( \neg (B \wedge A) \) in which case, by the second dogmatist claim, once I learn \( A \) and acquire justification for believing \( M \), I will also acquire justification for believing \( \neg (B \wedge A) \).

It’s strange to think, though, that I could acquire justification for believing that \( B \wedge A \) is false by learning that \( A \) is true. It’s strange to think that noticing the appearance of a mole on my left thigh could provide me with justification for believing that I’m not a brain in a vat being supplied with an appearance of a mole on my left thigh. Suppose I do have a genuine paranoid concern that I may be a brain in a vat trapped in a simulated world in which I appear to have a mole on my left thigh. As I apprehensively roll up my trousers to look for a mole, I’m hardly going to be relieved if I actually find one. Far from relieving my anxieties, this is the very discovery that is going to stoke them.

One way to make these impressions more precise is by appealing to Bayesian confirmation theory. On the Bayesian picture, the degrees of support conferred upon propositions by a given body of evidence can be represented by a probability function, with a piece of evidence \( \psi \) confirming a hypothesis \( \phi \) just in case conditionalising on \( \psi \) raises the evidential probability of \( \phi \), and a piece of evidence \( \psi \) disconfirming a hypothesis \( \phi \) just in case conditionalising on \( \psi \) lowers the evidential probability of \( \phi \). More formally, if \( \text{Pr} \) is a prior evidential probability function representing the probabilities imposed by background evidence then, according to the Bayesian, \( \psi \) confirms \( \phi \) relative to \( \text{Pr} \) just in case \( \text{Pr}(\phi \mid \psi) > \text{Pr}(\phi) \) and disconfirms \( \phi \) relative to \( \text{Pr} \) just in case \( \text{Pr}(\phi \mid \psi) < \text{Pr}(\phi) \). Conditional probabilities are usually taken to be defined in terms of unconditional probabilities via the standard ratio formula (RF): \( \text{Pr}(\phi \mid \psi) = \frac{\text{Pr}(\phi \wedge \psi)}{\text{Pr}(\psi)} \) if \( \text{Pr}(\psi) > 0 \), and undefined in case \( \text{Pr}(\psi) = 0 \), but they could equally be taken as primitive, with the ratio formula treated as a theorem.

Prior to checking my left thigh, it is possible, but less than certain, that there will appear to me to be a mole there – in which case we have it that \( 0 < \text{Pr}(A) < 1 \). It is
presumably also possible that I am a brain in a vat being supplied with an appearance as of a mole on my left thigh in which case we also have it that \( \Pr(B \land A) > 0 \). But, given just these assumptions, and provided that \( \Pr \) is a classical (Kolmogorovian) probability function, it can be proved that \( \Pr(\neg(B \land A) \mid A) < \Pr(\neg(B \land A)) \). In addition to the ratio formula, the following proof makes use of three well known theorems of classical probability:

- **Bayes’ Theorem (BT)** according to which if \( \Pr(\psi) > 0 \) and \( \Pr(\varphi) > 0 \) then \( \Pr(\varphi \mid \psi) = (\Pr(\psi \mid \varphi).\Pr(\varphi))/\Pr(\psi) \)

- **Complementation (C)** according to which \( \Pr(\varphi) = 1 - \Pr(\neg\varphi) \)

- **Conditional Complementation (CC)** according to which if \( \Pr(\psi) > 0 \) then \( \Pr(\varphi \mid \psi) = 1 - \Pr(\neg(\varphi \mid \psi)) \)

**Proof**

1. \( 0 < \Pr(B \land A) \leq \Pr(A) < 1 \) \hspace{1cm} Stipulation
2. \( \Pr(B \land A \mid A) = (\Pr(A \mid B \land A).\Pr(B \land A))/\Pr(A) \) \hspace{1cm} 1, BT
3. \( \Pr(A \mid B \land A) = 1 \) \hspace{1cm} 1, RF
4. \( \Pr(B \land A \mid A) = \Pr(B \land A)/\Pr(A) \) \hspace{1cm} 2, 3
5. \( \Pr(B \land A \mid A) > \Pr(B \land A) \) \hspace{1cm} 1, 4
6. \( \Pr(B \land A) = 1 - \Pr(\neg(B \land A)) \) \hspace{1cm} C
7. \( \Pr(B \land A \mid A) = 1 - \Pr(\neg(B \land A) \mid A) \) \hspace{1cm} 1, CC
8. \( 1 - \Pr(\neg(B \land A) \mid A) > 1 - \Pr(\neg(B \land A)) \) \hspace{1cm} 5, 6, 7
9. \( \Pr(\neg(B \land A) \mid A) < \Pr(\neg(B \land A)) \) \hspace{1cm} 8

**QED**

The Bayesian, then, is committed to the claim that learning \( A \) disconfirms \( \neg(B \land A) \). This is just an instance of a more general principle that Bayesian confirmation theory vindicates: If a conjunction and one of its conjuncts both have probabilities strictly between 0 and 1 then learning that the conjunct is true will serve to confirm the conjunction and disconfirm its negation.

The dogmatist would have us believe that, by learning \( A \), I can acquire a justification for believing \( \neg(B \land A) \) while the Bayesian would have us believe that, by learning \( A \), \( \neg(B \land A) \) is disconfirmed by having its evidential probability diminished. There is a clear tension here which might be transformed into an out and out inconsistency via the following principle:
(Just) If, by learning \( \psi \), one acquires justification for believing \( \varphi \) and \( \text{Pr} \) is one’s prior evidential probability function, then \( \text{Pr}(\varphi \mid \psi) \geq \text{Pr}(\varphi) \).

According to Just, if I acquire justification for believing a hypothesis \( \varphi \) by learning a piece of evidence \( \psi \), then the evidential probability of \( \varphi \) given \( \psi \) cannot be any lower than the prior evidential probability of \( \varphi \). In previous work, I’ve defended a view on which Just can fail (Smith, 2010, 2016, chap. 2), though I’m inclined to think that challenging Just may not be a promising path for the dogmatist to take. On my view, there are certain kinds of evidence that can probabilistically support a proposition without conferring justification for believing it. As such, it is possible to construct cases in which evidence of this sort is replaced by probabilistically weaker evidence that is justification conferring, making for counterexamples to Just. But this particular kind of structure is not (or not obviously) present in the cases of Just that would need to fail in order to preserve dogmatism\(^1\).

In any case, I won’t explore this further here, as my concern is with another, rather unexpected, option that is available to the dogmatist – the option explored by Jehle and Weatherson. While the above proof is sound when \( \text{Pr} \) is interpreted as a classical probability function, it fails if \( \text{Pr} \) is interpreted as an intuitionistic probability function – that is, a probability function constrained by an intuitionistic logical consequence relation rather than a classical one. Indeed, as Jehle and Weatherson demonstrate, it is relatively easy to construct intuitionistic probability functions for which (1) is true and (9) is false.

The dogmatist, it seems, can embrace Just and acquiesce in the general Bayesian picture of confirmation, so long as he is prepared to question some of the strong classical assumptions that conventionally inform Bayesianism – and this may seem like a relatively low price to pay. The plan for the remainder of this paper is as follows: In the next section I shall explore the contrast between classical and intuitionistic probability functions and develop, in greater detail, the intuitionistic option that lies open to the dogmatist. In the final section I shall argue that the advantages of this option are largely illusory – on close inspection it still leaves the dogmatist effectively saddled with the Bayesian objection, though

\(^1\) For discussion of this, and a defence of a somewhat contrary view, see Zardini (2014, patic. sections 3.5-3.7). Kung (2010) also defends an account on which Just can fail in such a way as to protect dogmatism against the Bayesian objection.
in a slightly different guise. I will conclude with some general reflections on the significance of the Bayesian objection.

II. CLASSICAL AND INTUITIONISTIC PROBABILITY

Weatherson (2003) provides an elegant generalisation of Kolmogorov’s probability axioms intended to be neutral with respect to the underlying logic. Let $\mathcal{L}$ be a set of sentences closed under the sentential connectives and associated with a logical consequence relation $\vdash$. Call a sentence $\varphi$ a $\vdash$-theorem just in case, for any sentence $\chi \in \mathcal{L}$, $\chi \vdash \varphi$. Call a sentence $\varphi$ a $\vdash$-antitheorem just in case for any sentence $\chi \in \mathcal{L}$, $\varphi \vdash \chi$. Following Weatherson, let a $\vdash$-probability function be any function from $\mathcal{L}$ into the real interval $[0, 1]$ that conforms to the following four axioms:

(P0) If $\varphi$ is a $\vdash$-antitheorem then $\Pr(\varphi) = 0$

(P1) If $\varphi$ is a $\vdash$-theorem then $\Pr(\varphi) = 1$

(P2) If $\varphi \vdash \psi$ then $\Pr(\varphi) \leq \Pr(\psi)$

(P3) $\Pr(\varphi) + \Pr(\psi) = \Pr(\varphi \lor \psi) + \Pr(\varphi \land \psi)$

The conditional probability functor can be defined via RF or it can be supplied with its own axioms, with RF emerging as a theorem. Jehle and Weatherson prefer the latter approach but, for ease, I will opt for the former here. The only assumptions about conditional probability that are made in this paper are RF and its consequences and, as such, it makes no difference for present purposes whether RF be deemed a definition or a theorem.

The behaviour of a $\vdash$-probability function will, in effect, reflect the behaviour of the underlying logical consequence relation $\vdash$ in combination with the axioms P0 – P3. As Weatherson (2003) shows, a probability function based upon classical logical consequence will be identical to a probability function as described by Kolmogorov’s original axioms. Classical probability functions can be constructed in the following, familiar way: Let $W$ be a finite set of possible worlds and $V$ a valuation function taking members of $\mathcal{L}$ into subsets of $W$ and meeting the following constraints:

$w \in V(\varphi \land \psi)$ iff $w \in V(\varphi)$ and $w \in V(\psi)$

$w \in V(\varphi \lor \psi)$ iff $w \in V(\varphi)$ or $w \in V(\psi)$

$w \in V(\neg \varphi)$ iff $w \notin V(\varphi)$
Finally, let \( m \) be a probability mass distribution defined upon \( W \) – that is, a function from \( W \) into the real unit interval such that, \( \Sigma_{x \in w} m(x) = 1 \). For each \( \chi \in L \), if we let \( \Pr(\chi) = \Sigma_{x \in V(\chi)} m(x) \), it can be shown that \( \Pr \) will qualify as a classical probability function.

Intuitionistic logic is weaker than classical logic – that is, while all intuitionistic theorems are classical theorems, some classical theorems fail within intuitionistic logic, the most well known being the Law of Excluded Middle (LEM): \( \varphi \lor \neg \varphi \). In general, weaker logical consequence relations will give rise, via P0-P3, to probability functions that are less tightly constrained. As Jehle and Weatherson demonstrate, intuitionistic probability functions are freed up in just such a way as to tolerate the kind of probabilistic behaviour that the dogmatist seems to require.

Intuitionistic probability functions can be constructed by exploiting slightly simplified versions of the models developed by Kripke (1965) in his semantics for intuitionistic logic. These models take the form \( \langle W, R, V \rangle \) where \( W \), as before, is a finite set of possible worlds and \( R \) is a reflexive, transitive relation on \( W \). Let \( V \) be a valuation function taking sentences of \( L \) into subsets of \( W \) that are closed under \( R \) – that is, for any \( \chi \in L \), if \( w \in V(\chi) \) and \( wRw' \) then \( w' \in V(\chi) \). The valuation clauses for conjunction and disjunction are unchanged, but the clause for negation is amended as follows:

\[ w \in V(\neg \varphi) \text{ iff for all } w' \text{ such that } wRw', w' \notin V(\varphi) \]

Once again, let \( m \) be a probability mass distribution defined over the members of \( W \) with \( \Pr(\chi) = \Sigma_{x \in V(\chi)} m(x) \) for any \( \chi \in L \). As Weatherson (2003) demonstrates, any \( \Pr \), so defined, will meet the conditions for an intuitionistic probability function.

As I noted in the previous section, the derivation of \( \Pr(\neg(B \land A) \mid A) < \Pr(\neg(B \land A)) \) from \( 0 < \Pr(B \land A) \leq \Pr(A) < 1 \) does not go through if \( \Pr \) is interpreted as an intuitionistic, rather than a classical, probability function. Up until step (5) the proof survives the transition to intuitionistic probability, but it falters at step (6) – both Complementation and Conditional Complementation fail for intuitionistic probability functions. Thinking of these functions as arising from mass distributions over Kripke models can help to illustrate just why this is. The intensional semantic clause for negation, relative to a Kripke model, ensures that there can be worlds excluded both from the valuation of a sentence \( \varphi \) and from the valuation of its
negation \neg \phi. Since probability mass can accumulate at these worlds, it need not be exclusively divided between \phi and \neg \phi.

Thinking about intuitionistic probability in this way can also help us to appreciate why \Pr(\neg (B \land A) \mid A) < \Pr(\neg (B \land A)) fails to follow from 0 < \Pr(B \land A) \leq \Pr(A) < 1 when \Pr is interpreted as an intuitionistic probability function. If the probability of \(B \land A\) is greater than 0 and the probability of A is less than 1, then the effect of conditionalising upon A will be to redistribute probability mass to \(B \land A\). This holds true for both classical and intuitionistic probability functions. In the case of a classical function, however, this additional mass must be drained from the mass assigned to \(\neg (B \land A)\) as there is, in effect, no other source from which it can issue. In the case of an intuitionistic probability function, however, there may be a reservoir of unclaimed mass that can meet this need. Indeed, conditionalising upon A can have the effect of redistributing mass from the reservoir to both \(B \land A\) and \(\neg (B \land A)\) – thus the possibility that \(\Pr(\neg (B \land A) \mid A) \geq \Pr(\neg (B \land A))\).

It is relatively straightforward to construct an intuitionistic probability function for which \(0 < \Pr(B \land A) \leq \Pr(A) < 1\) and \(\Pr(\neg (B \land A) \mid A) \geq \Pr(\neg (B \land A))\) – indeed, for which \(\Pr(\neg (B \land A) \mid A) > \Pr(\neg (B \land A))\). Consider the following Kripke model and associated mass distribution:

\begin{align*}
W &= \{w_1, w_2, w_3\} \\
R &= \{\langle w_1, w_1 \rangle, \langle w_2, w_2 \rangle, \langle w_3, w_3 \rangle, \langle w_1, w_2 \rangle, \langle w_1, w_3 \rangle\} \\
V(A) &= \{w_2, w_3\} \\
V(B) &= \{w_2\} \\
m(w_1) = m(w_2) = m(w_3) &= \frac{1}{3}
\end{align*}

By the clauses for negation and conjunction we have it that:

\begin{align*}
V(\neg A) &= \emptyset \\
V(\neg B) &= \{w_3\} \\
V(B \land A) &= \{w_2\} \\
V(\neg (B \land A)) &= \{w_3\}
\end{align*}

Graphically, the model can be represented as follows:
The following probabilities can be easily calculated:

\[
\begin{align*}
\Pr(A) &= \frac{2}{3} \\
\Pr(B) &= \frac{1}{3} \\
\Pr(B \land A) &= \frac{1}{3} \\
\Pr(\neg(B \land A)) &= \frac{1}{3} \\
\Pr(B \land A \mid A) &= \frac{1}{2} \\
\Pr(\neg(B \land A) \mid A) &= \frac{1}{2}
\end{align*}
\]

Clearly, the probability mass is not divided exclusively between \(B \land A\) and \(\neg(B \land A)\) – there is a reservoir of unclaimed mass located at \(w_1\). The effect of conditionalising upon \(A\) is to redistribute this unclaimed mass, in this case evenly, amongst \(B \land A\) and \(\neg(B \land A)\). Thus, we have it that \(\Pr(\neg(B \land A) \mid A) > \Pr(\neg(B \land A))\) in spite of the fact that \(0 < \Pr(B \land A) \leq \Pr(A) < 1\).

Thinking of probability functions as tethered to logical consequence relations offers an intriguing new perspective on Bayesian confirmation theory – a perspective on which it incorporates two, potentially separable, commitments: First, there is a commitment to the idea that degrees of evidential support behave like probabilities and that confirmation and disconfirmation should be understood in terms of probability raising and lowering respectively. Second, there is a commitment to classical logic. The claim that \(A\) disconfirms \(\neg(B \land A)\) emerges from the combination of both commitments, but could coherently be denied by someone who held on to the former commitment, while opting for intuitionistic logic – someone who still deserves to be described as a ‘Bayesian’ in a suitably inclusive sense.
According to Jehle and Weatherson, then, the dogmatist who embraces intuitionistic logic has nothing to fear from the Bayesian objection. Further, Jehle and Weatherson claim that it isn’t even necessary for the dogmatist to fully commit to intuitionistic logic in order to put the Bayesian objection to one side – it may be enough that the dogmatist be *less than fully committed* to classical logic. If one is uncertain whether intuitionistic or classical logic is correct then, on one natural way of understanding what this uncertainty amounts to, one should have a preference for intuitionistic over classical probability (Jehle and Weatherson, 2012, section 2).

I’m inclined to think, however, that these conclusions are premature – even the dogmatist who is fully confident that intuitionistic logic is correct does not yet have a viable response to the Bayesian objection. Consider the sentence ‘Either I’m wearing socks or I’m not’. If I take intuitionistic logic seriously, then I may have reason to doubt that this sentence is true purely in virtue of its form, but I needn’t, of course, have any reason to doubt that it *is* true. If I adhere to a theory that prevents me from accepting this sentence, then I can’t get off the hook simply by expressing sympathy with intuitionistic logic. Similarly, if I take intuitionistic logic and probability seriously, I will have reason to doubt that $\Pr(\neg(B \land A) \mid A) < \Pr(\neg(B \land A))$ is true purely in virtue of its form, but I needn’t have any reason to doubt that it’s true, given the intended interpretations of A and B. The Bayesian objection to dogmatism requires only the latter claim, and not the former. As I shall argue in the remainder of this paper, the move from classical to intuitionistic probability leaves us, in fact, with very strong reasons for thinking that $\Pr(\neg(\neg(B \land A) \mid A) < \Pr(\neg(B \land A))$.

My argument works as follows: Given the stipulation that $0 < \Pr(B \land A) \leq \Pr(A) < 1$ and the supposition that $\Pr(\neg(B \land A) \mid A) \geq \Pr(\neg(B \land A))$, I shall derive three further results within intuitionistic probability theory. Given the intended interpretations of A and B, each of these results is individually highly implausible. Taken together they amount, I think, to a strong reductio of the supposition. I shall conclude that even the dogmatist who embraces intuitionistic probability is under substantial pressure to concede that $\Pr(\neg(B \land A) \mid A) < \Pr(\neg(B \land A))$. 

III. THREE TROUBLESOME RESULTS

Consider the following Additivity principle (AD): If $\varphi \land \psi$ is an intuitionistic antitheorem, then $\text{Pr}(\varphi \lor \psi) = \text{Pr}(\varphi) + \text{Pr}(\psi)$. That this holds for intuitionistic probability functions can be proved straightforwardly from P0-P3:

*Proof*

1. $\varphi \land \psi$ is an intuitionistic antitheorem \hspace{1cm} Stipulation
2. $\text{Pr}(\varphi) + \text{Pr}(\psi) = \text{Pr}(\varphi \lor \psi) + \text{Pr}(\varphi \land \psi) \hspace{1cm} P3$
3. $\text{Pr}(\varphi \land \psi) = 0 \hspace{1cm} 1, P0$
4. $\text{Pr}(\varphi) + \text{Pr}(\psi) = \text{Pr}(\varphi \lor \psi) \hspace{1cm} 2, 3$

QED

In fact, we could harmlessly substitute ‘classical’ for ‘intuitionistic’ in this principle, since classical and intuitionistic logic share the same antitheorems. As such, AD represents a theorem of classical probability theory that is preserved when we move to intuitionistic probability.

While other well known theorems of classical probability theory don’t survive the transition to intuitionistic probability, it is often possible to identify weakened substitute theorems that do persevere. For instance, whilst Complementation fails for intuitionistic probability functions, the following theorem, which I shall call *Weak Complementation* (WC) holds: $\text{Pr}(\varphi) = \text{Pr}(\varphi \lor \neg\varphi) - \text{Pr}(\neg\varphi)$. This follows immediately from AD, given that $\varphi \land \neg\varphi$ is an intuitionistic antitheorem.

A *Weak Conditional Complementation* principle (WCC) can also be proved:

*Proof*

1. $\text{Pr}(\psi) > 0 \hspace{1cm} \text{Stipulation}$
2. $\text{Pr}((\varphi \land \psi) \lor (\neg\varphi \land \psi)) = \text{Pr}(\varphi \land \psi) + \text{Pr}(\neg\varphi \land \psi) \hspace{1cm} \text{AD}$
3. $\text{Pr}((\varphi \land \psi) \lor (\neg\varphi \land \psi))/\text{Pr}(\psi) = \text{Pr}(\varphi \land \psi)/\text{Pr}(\psi) + \text{Pr}(\neg\varphi \land \psi)/\text{Pr}(\psi) \hspace{1cm} 1, 2$
4. $\text{Pr}((\varphi \lor \neg\varphi) \mid \psi) = \text{Pr}(\varphi \mid \psi) + \text{Pr}(\neg\varphi \mid \psi) \hspace{1cm} 3, \text{RF}$
5. $\text{Pr}(\varphi \mid \psi) = \text{Pr}((\varphi \lor \neg\varphi) \mid \psi) - \text{Pr}(\neg\varphi \mid \psi) \hspace{1cm} 4$

QED
Evidently, then, if we could appeal to \( \Pr((B \land A) \lor \neg(B \land A)) = 1 \) as an auxiliary assumption, the proof in section I could go through, using only theorems that hold for intuitionistic probability functions:

Proof

(1) \( 0 < \Pr(B \land A) \leq \Pr(A) < 1 \) \hspace{1cm} Stipulation
(2) \( \Pr((B \land A) \lor \neg(B \land A)) = 1 \) \hspace{1cm} Assumption
(3) \( \Pr((B \land A) \lor \neg(B \land A) \mid A) = 1 \) \hspace{1cm} 1, 2, RF
(4) \( \Pr(B \land A \mid A) = (\Pr(A \mid B \land A) \cdot \Pr(B \land A)) / \Pr(A) \) \hspace{1cm} BT
(5) \( \Pr(A \mid B \land A) = 1 \) \hspace{1cm} 1, RF
(6) \( \Pr(B \land A \mid A) = \Pr(B \land A) / \Pr(A) \) \hspace{1cm} 4, 5
(7) \( \Pr(B \land A \mid A) > \Pr(B \land A) \) \hspace{1cm} 1, 6
(8) \( \Pr(B \land A) = \Pr((B \land A) \lor \neg(B \land A)) - \Pr(\neg(B \land A)) \) \hspace{1cm} WC
(9) \( \Pr(B \land A) = 1 - \Pr(\neg(B \land A)) \) \hspace{1cm} 2, 8
(10) \( \Pr(B \land A \mid A) = \Pr((B \land A) \lor \neg(B \land A) \mid A) \)
\[ - \Pr(\neg(B \land A) \mid A) \] \hspace{1cm} 1, WCC
(11) \( \Pr(B \land A \mid A) = 1 - \Pr(\neg(B \land A) \mid A) \) \hspace{1cm} 3, 10
(12) \( 1 - \Pr(\neg(B \land A) \mid A) > 1 - \Pr(\neg(B \land A)) \) \hspace{1cm} 7, 9, 11
(13) \( \Pr(\neg(B \land A) \mid A) < \Pr(\neg(B \land A)) \) \hspace{1cm} 12

QED

When \( \Pr \) is an intuitionistic probability function, we have the following result:

If \( 0 < \Pr(B \land A) \leq \Pr(A) < 1 \) and \( \Pr(\neg(B \land A) \mid A) \geq \Pr(\neg(B \land A)) \) then \( \Pr((B \land A) \lor \neg(B \land A)) < 1 \)

This is the first, and perhaps most obvious, of the three results that I shall establish. By this result, it’s not enough for the dogmatist to entertain general doubts about the universal validity of LEM. In order to resist the conclusion that \( \Pr(\neg(B \land A) \mid A) < \Pr(\neg(B \land A)) \), the dogmatist must entertain doubts about one very particular instance: \((B \land A) \lor \neg(B \land A)\) – that is, ‘Either I’m a brain in a vat and it appears to me that there is a mole on my left thigh or it’s not the case that I’m a brain in a vat and it appears to me that there is a mole on my left thigh’. In effect, the dogmatist must harbour some suspicion that there is no fact of the matter as to whether or not I’m a brain in a vat being supplied with an appearance of a mole on my left thigh. But this, I think, is very difficult to motivate.
Some antirealists have been moved to reject (that is, not accept) instances of LEM for sentences that are deemed to be verification transcendent\(^2\). One could insist that B is an example of a verification transcendent sentence and motivate doubts about B \(\lor \sim\)B on this basis. But anyone who doubted B \(\lor \sim\)B, one might argue, would also have a basis for doubting (B \& A) \(\lor \sim\)(B \& A). Even if we accept this kind of antirealism, though, there are a number of potential problems with this reasoning. First, it’s not clear that B really should be regarded as verification transcendent – it seems that we could, with sufficient imagination, conceive of empirical evidence both for and against the hypothesis. Second, even if B is deemed to be verification transcendent, it’s clear that B \& A is something on which empirical evidence can bear, and a claim which could, in principle, be conclusively refuted (though not perhaps conclusively proved).

A final problem with this line of thought is that the potential verification transcendence of B seems utterly incidental to the workings of the Bayesian objection. B could, in principle, be replaced by any sentence that is compatible with A and incompatible with M. Consider the following:

F: I have a fake plastic mole glued to my thigh and no real mole.

The dogmatist is committed to thinking that learning A could provide me with justification for believing \(\sim\)(F \& A) as well as \(\sim\)(B \& A). And any dogmatist who exploits intuitionistic logic in order to maintain that Pr(\(\sim\)(F \& A) \mid A) \geq\) Pr(\(\sim\)(F \& A)) will be committed to doubting (F \& A) \(\lor \sim\)(F \& A). But such doubts cannot be motivated by scruples about verification transcendence – F and F \& A are clearly verifiable.

Next, consider the following proof, exploiting only theorems that hold for intuitionistic probability functions:

**Proof**

1. \(0 \leq \Pr(B \& A) \leq \Pr(A) < 1\)  \hspace{1cm} \text{Stipulation}
2. \(\Pr(B \& A \mid A) = (\Pr(A \mid B \& A).\Pr(B \& A))/\Pr(A)\)  \hspace{1cm} 1, BT
3. \(\Pr(A \mid B \& A) = 1\)  \hspace{1cm} 1, RF
4. \(\Pr(B \& A \mid A) > \Pr(B \& A)\)  \hspace{1cm} 1, 2, 3

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\(^2\) This interpretation of antirealism is closely associated with Michael Dummett (see, for instance, Dummett, 1991, Introduction).
By (8), the extent to which conditionalising on A boosts the evidential probability of \( \neg(B \land A) \) must be strictly less than the extent to which it boosts the evidential probability of \( (B \land A) \lor \neg(B \land A) \). If we suppose that \( \Pr(\neg(B \land A) \mid A) \geq \Pr(\neg(\neg(B \land A))) \) then, via (8), we can easily prove that \( \Pr((B \land A) \lor \neg(B \land A) \mid A) > \Pr((B \land A) \lor \neg(B \land A)) \). With \( \Pr \) an intuitionistic probability function, this is the second result to which I wish to draw attention:

\[
\Pr((B \land A) \lor \neg(B \land A) \mid A) > \Pr((B \land A) \lor \neg(B \land A))
\]

This is nicely illustrated by the intuitionistic probability function developed in the previous section. Relative to that function, as can be easily checked, conditionalising on A boosts the evidential probability of \( \neg(B \land A) \) by 1/6 (moving it from 1/3 to 1/2) and boosts the evidential probability of \( (B \land A) \lor \neg(B \land A) \) by 1/3 (taking it from 2/3 to 1)\(^3\).

Not only must the dogmatist grant that \( (B \land A) \lor \neg(B \land A) \) is doubtful or uncertain, he must, by this result, also grant that it is positively confirmed by A. Not only must the dogmatist harbour some suspicion that there is no fact of the matter as to whether or not I am a brain in vat being supplied with an appearance as of a mole on my left thigh, the dogmatist must also hold that an appearance of a mole on my left thigh would actually help to put these suspicions to rest – would help to confirm that there really is a fact of the matter after all.

\(^3\) While \( \Pr((B \land A) \lor \neg(B \land A) \mid A) = 1 \) for the intuitionistic probability function that I’ve described, \( (B \land A) \lor \neg(B \land A) \) need not, in general, be conclusively confirmed by A. It is in fact possible for \( (B \land A) \lor \neg(B \land A) \) to be disconfirmed by A (though, by the above result, \( \neg(B \land A) \) would need to be disconfirmed even more strongly). Suppose we amend the function I’ve described by adding another world \( w_4 \) to \( W \) and allowing the probability mass to be evenly divided amongst these four worlds. Suppose \( w_4 \) is an ‘isolated’ world that stands in \( R \) only to itself and is not part of the valuation of either \( A \) or \( B \). Suppose, finally, that we expand the valuation of \( A \) to include \( w_1 \). As can be checked, we would then have it that \( \Pr((B \land A) \lor \neg(B \land A) \mid A) > 2/3 < \Pr((B \land A) \lor \neg(B \land A)) = 3/4 \).
This is surely very puzzling. And the verification transcendence motivation for doubting instances of LEM, as far as I can tell, would only serve to deepen our puzzlement over this.

Thinking about intuitionistic probability functions as arising from mass distributions over the points of Kripke models can, I think, help us to appreciate why these two results hold. As discussed in the previous section, conditionalising on A can only boost or leave constant the evidential probability of \( \sim(B \land A) \) on the condition that there is a reservoir of unclaimed probability mass relative to \( B \land A \land \sim(B \land A) \). But this is just to say that there is a reservoir of probability mass not assigned to \( (B \land A) \lor \sim(B \land A) \). Thus the first result. Furthermore, conditionalising on A can only boost or leave constant the evidential probability of \( \sim(B \land A) \) if conditionalising on A partially drains this reservoir in order to give the probability of \( B \land A \) its required boost. But this is just to say that conditionalising on A raises the probability of \( (B \land A) \lor \sim(B \land A) \). Thus the second result.

The final result that I shall prove is perhaps the most troubling of the three. In intuitionistic logic, the classical equivalence between \( \varphi \) and \((\varphi \land \psi) \lor (\varphi \land \sim \psi)\) breaks down due to the failure of the following expansion principle: \( \varphi \vdash (\varphi \land \psi) \lor (\varphi \land \sim \psi) \). The reverse contraction principle, however, remains valid: \((\varphi \land \psi) \lor (\varphi \land \sim \psi) \vdash \varphi \). As such, the following will hold for intuitionistic probability functions as a direct consequence of P2:

\[
\Pr((\varphi \land \psi) \lor (\varphi \land \sim \psi)) \leq \Pr(\varphi).
\]

With this in mind, consider the following proof:

**Proof**

\begin{align*}
(1) & \quad 0 < \Pr(B \land A) \leq \Pr(A) < 1 & \text{Stipulation} \\
(2) & \quad \Pr(A \lor \sim A) = 1 & \text{Assumption} \\
(3) & \quad \Pr(A) + \Pr(\sim A) = 1 & 2, \text{AD} \\
(4) & \quad \Pr(\sim A) > \Pr(\sim A).\Pr(\sim(B \land A)) & 1 \\
(5) & \quad \Pr((B \land A) \land \sim A) > \Pr(\sim A).\Pr((B \land A)) & 4, \text{P2} \\
(6) & \quad \Pr((B \land A) \lor (\sim(B \land A) \land \sim A)) \leq \Pr((B \land A)) & \text{P2} \\
(7) & \quad \Pr((B \land A) \lor \Pr((B \land A) \land \sim A)) \leq \Pr((B \land A)) & 6, \text{AD} \\
(8) & \quad \Pr((B \land A) \lor \Pr((B \land A) \land \sim A)) \leq \Pr((B \land A)).(\Pr(A) + \Pr(\sim A)) & 3, 7 \\
(9) & \quad \Pr((B \land A) \lor \Pr((B \land A) \land \sim A)) \leq \Pr((B \land A)).\Pr(A) + \Pr((B \land A)).\Pr(\sim A) & 8
\end{align*}
This is the third and final result that I’ll emphasise:

If \(0 < \Pr(B \land A) \leq \Pr(A) < 1\) and \(\Pr(\neg(B \land A) | A) \geq \Pr(\neg(B \land A))\) then \(\Pr(A \lor \neg A) < 1\).

As well as entertaining doubts about \((B \land A) \lor \neg(B \land A)\), the dogmatist must also entertain doubts about \(A \lor \neg A\). Not only must the dogmatist harbour some suspicion that there is no fact of the matter as to whether or not I am a brain in vat being supplied with an appearance of a mole on my left thigh, the dogmatist must harbour some suspicion that there is no fact of the matter as to whether or not it appears to me that there is a mole on my left thigh. Surely this is about as simple and straightforwardly verifiable a hypothesis as one could ask for.

Certain theories of vagueness predict that LEM can fail in borderline cases of vague predicates – so a sentence such as ‘The patch is red or the patch is not red’ will fail to be true for borderline red patches. Plausibly, there can be ‘borderline’ moles and ‘borderline’ appearances in which case there could be borderline cases for a sentence such as \(A\) which, on the present approach, will be cases in which \(A \lor \neg A\) fails to be true. Needless to say, this is a very controversial approach to vagueness\(^4\), but even if we accept it, it provides little comfort to a dogmatist. This account of vagueness will only license doubts about \(A \lor \neg A\) in certain specialised cases, but the predictions made by dogmatism are in no way limited to such cases. If I’m certain that the present case is not a borderline case for \(A\), then it will remain true that \(\Pr(\neg(B \land A) | A) < \Pr(\neg(B \land A))\), contrary to what dogmatism predicts.

Furthermore, even if the dogmatist could find a way to motivate the idea that \(A \lor \neg A\) is a generally dubious instance of LEM, this is not enough to safeguard the theory. There are any number of different appearance hypotheses that could be used to run the Bayesian objection – it appears to me that I’m sitting down, it appears to me that I’m breathing, it appears to me that I have two hands, it appears to me that there is no vat in the immediate

\(^4\) Most contemporary theories of vagueness, including supervaluationist, epistemicist and dialetheist accounts, endorse LEM in borderline cases. The failure of LEM in such cases is, however, characteristic of some ‘many-valued’ approaches to vagueness (see Williamson, 1994, chap. 4).
vicinity etc. Once we consider the sheer variety of forms that such hypotheses could take, it becomes clear that the dogmatist who wishes to avail himself of this response is facing quite rampant LEM failure.

Any dogmatist who appeals to intuitionistic probability in order to try and circumvent the Bayesian objection is committed to the three consequences derived here. And, while I haven’t discussed these consequences in great detail, to an extent they speak for themselves. At the very least, it is incumbent upon the dogmatist who wishes to exploit the intuitionistic option to explain just how such consequences could be acceptable, otherwise the Bayesian objection retains its bite.

IV CONCLUSION

I shall conclude with some brief, general thoughts about the Bayesian objection to dogmatism and, in particular, about the very idea of modifying Bayesian confirmation theory in an attempt to accommodate this theory\(^5\). In a way, I think that the Bayesian objection to dogmatism is misnamed. It’s a mistake to portray this objection as involving a clash between two theories – dogmatism and Bayesian confirmation theory – either of which might be fair game when it comes to affecting a resolution. The true clash, I think, is between dogmatism and a series of very intuitive claims, such as the claim I’ve focussed on here: By learning A – that it appears to me that I have a mole on my left thigh – I cannot acquire justification for believing \(\sim(B \land A)\) – that I’m not a brain in a vat being supplied with an appearance of a mole on my left thigh.

It is true enough that this claim can be derived from classical Bayesian confirmation theory, along with a philosophical assumption such as \textbf{Just} – but it’s not as though we need to derive the claim from \textit{anything} in order to convince ourselves that it’s true. To put things slightly differently, this claim is not some \textit{artefact} of classical Bayesian confirmation theory – not some surprising prediction that the theory foists upon us. On the contrary, this is a claim that \textit{any} adequate approach to confirmation and justification should arguably deliver – a claim that is plausible before we’ve engaged in any systematic theorising about these

\(^5\) Other attempts to implement this kind of strategy are pursued by Weatherson (2007) and Zardini (2014).
topics. And an intuitionistic Bayesian confirmation theory will deliver the claim – it’s just that it needs to be supplemented by further, very plausible, assumptions in order to do so.

Modifying classical Bayesian confirmation theory is not, I think, a viable way to address the Bayesian objection to dogmatism. This is not because classical Bayesian confirmation theory is sacrosanct – rather, it is because any viable modification of the theory should continue to deliver the claims that clash with dogmatism. The Bayesian objection to dogmatism is not, at its heart, ‘Bayesian’ at all. In my view, classical Bayesian confirmation theory offers just one way of dramatising a problem that is, for all intents and purposes, internal to dogmatism itself.

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