Research Article

Computation of Deflections for PC Box Girder Bridges with Corrugated Steel Webs considering the Effects of Shear Lag and Shear Deformation

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Prestressed concrete (PC) girders with corrugated steel webs (CSWs) have received considerable attention in the past two decades due to their light self-weight and high prestressing efficiency. Most previous studies were focused on the static behavior of CSWs and simple beams with CSWs. The calculation of deflection is an important part in the static analysis of structures. However, very few studies have been conducted to investigate the deflection of full PC girders or bridges with CSWs and no simple formulas are available for estimating their deflection under static loads. In addition, experimental work on full-scale bridges or scale bridge models with CSWs is very limited. In this paper, a formula for calculating the deflection of PC box girders with CSWs is derived. The longitudinal displacement function of PC box girders with CSWs, which can consider the shear lag effect and shear deformation of CSWs, is first derived. Based on the longitudinal displacement function, the formula for predicting the deflection of PC box girders with CSWs is derived using the variational principle method. The accuracy of the derived formula is verified against experimental results from a scaled bridge model and the finite element analysis results. Parametric studies are also performed, and the influences of shear lag and shear deformation on the deflection of the box girder with CSWs are investigated by considering different width-to-span ratios and different girder heights. The present study provides an effective and efficient tool for determining the deflection of PC box girders with CSWs.

1. Introduction

Prestressed concrete (PC) girders with corrugated steel webs (CSWs) are a new type of girders that can take full advantages of the material properties of the concrete flanges, prestressed tendons, and steel webs. As shown in Figure 1, the upper and bottom concrete flanges provide the bending strength while the CSWs provide the necessary shear capacity but contribute little to the bending capacity [1].

Bridges with this type of girders are aesthetically pleasing and attractive from the viewpoint of both saving construction time and cost effectiveness. Moreover, the CSWs do not absorb much prestressing force in the concrete flanges and can therefore improve the prestressing efficiency over the conventional PC box girders.

Most of the previous studies focused on the shear buckling of CSWs [2, 3]. The static and dynamic characteristics of box girder bridges with CSWs considering the effects of shear lag and shear deformation have been studied by some scholars [4–6]. The flexural behavior of I-girders with CSWs has also been studied by many researchers [5, 7–11]. In addition, the fatigue performance of girders with CSWs was also studied by some researchers [12, 13].

Deflection is a very important indicator for structures’ stiffness and bearing capacity. However, very few studies have been conducted to investigate the deflections of full PC girders or bridges with CSWs. Meanwhile, no simple formulas are available for estimating the deflection of PC girder bridges with CSWs. In addition, most previous studies were focused on the behavior of CSWs or steel beams with CSWs rather than the performance of full bridges with CSWs, and very few experimental studies have been reported on the overall performance of PC girders with CSWs [14, 15].
Therefore, simple and accurate formulas for calculating the deflection of such girders/bridges are very desirable.

For a box girder, the shear lag effect reduces the in-plane stiffness of the flanges, leading to an increase of the girder deflection [16]. Therefore, the effect of shear lag on the deflection of PC girder bridges with CSWs is considered in this study. Based on the experiments and theoretical analyses carried out to date, it has been confirmed that the shear force in the girder is mostly resisted by the CSWs [1]. The CSWs, which usually have a thickness of 10 mm, are much thinner than the webs of conventional PC box girders and therefore have smaller shear stiffness. Therefore, the effect of the shear deformation of the CSWs on the total deflection of PC box girders with CSWs should be taken into account.

The main purpose of this paper is to provide an effective and efficient way for calculating the deflection of PC box girders with CSWs while considering the effects of both the shear lag and shear deformation of the CSWs. The longitudinal displacement function of PC box girders with CSWs which can consider the shear lag effect and shear deformation of CSWs is derived. Based on the longitudinal displacement function, the deflection formula of PC box girders with CSWs is deduced using the variational principle method. The accuracy of the derived formula is verified against experimental results from a scaled bridge model and also the finite element analysis (FEA) results.

2. Shear Modulus of CSWs

To understand the shear behavior of PC girder bridges with CSWs, it is necessary to determine the effective shear modulus of the CSWs. Samanta and Mukhopadhyay [17] proposed a formula for determining the effective shear modulus of CSWs as follows:

\[ G_s = \frac{(L_1 + L_3)}{(L_1 + L_2)} \frac{E_s}{2(1 + \nu_s)} = \alpha G_s \]  

where \( G, E_s, \) and \( \nu_s \) are the shear modulus, Young’s modulus of elasticity, and Poisson’s ratio of the flat steel plates, respectively, and \( \alpha \) is the length reduction factor, which is the ratio of the projected length \((L_1 + L_3)\) to the actual length of the corrugated plate \((L_1 + L_2)\) shown in Figure 2. Since the value of \( \alpha \) is less than 1, the shear modulus of CSWs is smaller than that of flat steel plates.

3. Governing Equilibrium Differential Equations

3.1. Description of the Problem and Assumptions. The basic assumptions made for the PC box girders with CSWs investigated in this study are summarized as follows:

(1) The CSWs have no contribution to the flexural strength of the PC box girders with CSWs due to the accordion effect.
(2) The materials of the girder are linear elastic, and the girder deflection and rotation are small.

3.2. Warping Displacement Function for Shear Lag. The warping displacement function for shear lag should be selected cautiously because it directly reflects the warping stress distribution due to the shear lag. In the box girder with CSWs, a large shear flow is normally transmitted from the webs to the horizontal flanges. This causes the in-plane shear deformation of the flange plates, the consequence of which is that the longitudinal displacement in the central zone of the
\[ \sigma_s: \text{Actual stress} \]
\[ \bar{\sigma}_s: \text{By elementary beam theory} \]

**Figure 3:** Cross section of box girder with CSWs.

\[ q(s) = -\frac{Q(z)}{I_y} \int y_s ds = \frac{Q(z)}{I_y} h_1 t s, \quad (3) \]

where \( Q(z) \) is the vertical shear on the cross section; \( I_y \) is the moment of inertia of the cross section about the \( y \) axis; \( h_1 \) is the distance between the \( y \) axis and the central surface of the top slab; \( t \) is the slab thickness; and \( s \) is the contour coordinate measured along the central line of the wall and its origin is at the intersection point between the \( x-z \) plane and the central surface of top slab.

The in-plane shear deformation of the top slab can be approximately expressed as

\[ y_{xy} = \frac{\partial u}{\partial s} = \frac{Q(s)}{G_t I_y} Q(z) h_1 s, \quad (4) \]

where \( u \) is the longitudinal displacement of the top slab and \( G_t \) is the shear modulus of concrete slab. In equation (4), the effect of the lateral displacement of the top slab on the shear deformation is assumed to be negligible. Integrating equation (4) with respect to \( s \) gives

\[ u - u_0 = \frac{Q(z) h_1 s^2}{2G_t I_y}, \quad (5) \]

where \( u_0 \) is the longitudinal displacement at the origin of \( s \).

The additional deflection induced by the shear lag effect of the top slab can be expressed as

\[ \xi_1(x) = u_1 - u_0 = \frac{Q(z) h_1 s^2}{2G_t I_y}. \quad (7) \]

Using the following boundary conditions, i.e., \( u = u_0 \) at \( y = 0 \) and \( u = u_1 \) at \( y = b \), the longitudinal displacement function at any point of the top slab can be expressed as

\[ u_t(x, y, z) = u_1(x, z) - \left( 1 - \frac{y^2}{b^2} \right) \xi_1(x). \quad (8) \]

The same method can also be applied to the cantilever slab and bottom slab. Therefore, the longitudinal displacement function at any point of the cantilever slab and bottom slab can be expressed as

\[ u_c(x, y, z) = u_1(x, z) - \left( 1 - \frac{(b + b - y)^2}{(b)^2} \right) \xi_2(x), \quad (9) \]

\[ u_b(x, y, z) = u_2(x, z) - \left( 1 - \frac{y^2}{b^2} \right) \xi_3(x), \quad (10) \]

where \( \xi_2(x) = \frac{(Q(z) h_1)/(2G_t I_y)}{(b)^2} \) is the additional deflection induced by shear lag effect of the cantilever slab and \( \xi_3(x) = \frac{-(Q(z) h_0)/(2G_t I_y)}{(b)^2} \) is the additional deflection induced by the shear lag effect of the bottom slab.

Based on the quasiplane section assumption of the PC box girder with CSWs, the longitudinal displacement of the CSWs at Point 1 and Point 2 (shown in Figure 3) can be expressed, respectively, as follows:
where \( h_b \) is the distance between the \( y \) axis and the central surface of the bottom slab, as illustrated in Figure 3.

After substituting equations (11) and (12) into equations (8)–(10), the longitudinal displacement at any point of the cross section of the PC box girder with CSWs including the shear lag and shear deformation effects can be expressed as

\[
u(x, y, z) = h_b \left( \frac{dW}{dx - y_s} \right) + f(y, z) \xi(x),
\]

where \( f(y, z) \) is the warping displacement function for shear lag and \( \xi(x) = ((Q(z))2G, I_s)h^2 \) is the additional deflection induced by the shear lag effect.

### 3.3. Governing Equations Based on the Variational Principle.

Considering the symmetry of shear strain about the \( x-z \) plane, the normal strain and shear strain in the top slab, cantilever slab, and bottom slab can be given, respectively, as follows:

\[
\begin{align*}
\varepsilon_x &= \frac{\partial u(x, y, z)}{\partial x} = f(y, z) \cdot \xi'(x) + h_l \cdot (W'' - \gamma_s'), \\
\gamma_{xy} &= \frac{\partial u(x, y, z)}{\partial y} = f'(y, z) \cdot \xi(x).
\end{align*}
\]

Then, the strain energy of the top slab, cantilever slab, and bottom slab of the box girder with CSWs shown in Figure 3 can be expressed as follows:

\[
\nabla_b = \frac{1}{2} \int_0^l \int_A E_c T^2 \varepsilon dAdx + \frac{1}{2} \int_0^l \int_A G_c y^2 dAdx
\]

\[
= \frac{1}{2} \int_A E_c f^2(y, z)dA \int_0^l [\xi''(x)]^2 dx
\]

\[
+ \int_A E_c f(y, z)h_l dA \int_0^l \xi''(x) (W'' - \gamma'_s) dx
\]

\[
+ \frac{1}{2} \int_A E_c h^2 dA \int_0^l [W'' - \gamma'_s]^2 dx
\]

\[
+ \frac{1}{2} \int_A G_c [f'(y, z)]^2 dA \int_0^l [\xi(x)]^2 dx,
\]

where \( E_c \) and \( G_c \) are Young’s modulus and shear modulus of the concrete flange, respectively; \( I_y = \int_A h_l^2 dA; I_{fy} = \int_A f^2(y, z)dA; I_{fj} = \int_A f(y, z)h_l dA; \) and \( I_{Tf} = \int_A [f'(y, z)]^2 dA. \)

The strain energy in the CSWs is calculated as

\[
\nabla_f = \left( \int_0^l G_s A_s \gamma_s^2 dA, \right)
\]

where \( A_s \) is the total cross section area of the two CSWs.

For the box girder with CSWs shown in Figure 4, the potential energy stored in the girder \( W \) due to the external loading can be given by

\[
W = \int M(x)(W'' - \gamma'_s) dx + \int Q(x) y_s dx.
\]

As a result, the total potential energy of the box girder with CSWs can be calculated as \( \Pi = \nabla_b + \nabla_f + W. \) According to the principle of minimum potential energy, it can be obtained that \( \delta \Pi = 0. \) The governing differential equations and natural boundary conditions of the system are as follows:

\[
E_c I_f (W'' - \gamma'_s) + E_c I_{fh} \xi'(y) + M(x) = 0,
\]

\[
G_c I_{Tf} \xi(x) - E_c I_{jh} \left( W'' - \gamma'_s \right) - E_c I_{fj} \xi''(x) = 0,
\]

\[
\gamma_s = \frac{Q(x)}{G_s A_s},
\]

\[
\delta \xi(x) \left( E_c I_{fj} \xi'(y) + E_c I_{jh} (W'' - \gamma'_s) \right)_{y=0} = 0.
\]

Differentiating equation (18) with respect to the path variable \( x \) and then substituting the term \( (W'' - \gamma'_s) \) into equation (19) results in
\[ \xi''(x) - \frac{G_c}{E_c} I_y \frac{I_y}{I_y I_f - I_{f_h}^2} \xi(x) = \frac{1}{E_c} \frac{I_{f_h}^2}{I_{f_h}^2 - I_y I_f} Q(x). \] (22)

Equation (22) can be further simplified into the following:
\[ \xi''(x) - k^2 \xi(x) = -k_1 Q(x), \] (23)

where \( k^2 = \left( G_c / E_c \right) \left( I_y / I_y I_f - I_{f_h}^2 \right)/\left( I_{f_h}^2 - I_y I_f \right) \).

Then, the general solution of equation (23) can be expressed as
\[ \xi(x) = a_1 shkx + a_2 chkx + \xi^*, \] (24)

where \( \xi^* \) is the special solution related to \( Q(x) \) and the constants \( a_1 \) and \( a_2 \) are determined based on the boundary conditions.

Further simplification of equation (18) gives
\[ W'' = -\frac{M(x)}{E_c I_f} \frac{I_y}{I_y} - \frac{1}{I_y} Q(x) + \frac{G_c A_x}{I_x} \xi(x), \] (25)

Integrating equation (25) with respect to \( l \), the total vertical deflection of the box girder with CSWs is calculated as
\[
W(x) = -\int \left[ \int \frac{M(x)}{E_c I_f} \frac{dx}{dx} - \frac{1}{I_y} \int \left[ \int \xi''(x) dx \right] dx \right]
+ \int \left[ \int \frac{Q(x)}{G_c A_x} dx \right] dx + C_1 x + C_2
= W_0 + W_1 + W_2 + C_1 x + C_2, \] (26)

where \( W_0 \) is the displacement calculated with traditional beam theory and can be calculated as \( W_0 = -\int \left[ \int \frac{M(x)}{E_c I_f} dx \right] dx + C_{10} x + C_{20} \); \( W_1 \) is the displacement due to the shear lag effect and can be calculated as \( W_1 = -\left( I_{f_h}/I_y \right) \int \left[ \int \xi''(x) dx \right] dx + C_{11} x + C_{21} \); and \( W_2 \) is the displacement considering shear deformation effect and can be calculated as \( W_2 = \int \left[ \int \xi''(x) dx \right] dx + C_{12} x + C_{22} \). In the previous displacement expressions, \( C_{11}, C_{22}, C_{10}, C_{20}, C_{11}, C_{21}, C_{12}, \) and \( C_{22} \) are constants and can be determined from the boundary conditions at the two ends of the box girder with CSWs.

The two-span continuous box girder with CSWs under uniformly distributed load \( q \) (as shown in Figure 6), the bending moment, and shear force at any section \( x \) can be obtained:
\[
M(x) = \frac{3}{8} q l x - \frac{q x^3}{2}, \] (27)
\[
Q(x) = \frac{3}{8} q l - q x. \]

(1) \( W_0 \) is the displacement calculated with traditional beam theory:

\[ W_0 = -\int \left[ \int \frac{M(x)}{E_c I_f} dx \right] dx + C_{10} x + C_{20}, \] (28)

\[ = -\frac{q}{24 E_c I_f} \left( \frac{3}{2} l x^3 - x^4 \right) + C_{10} x + C_{20}, \]

in which the constants of integration, \( C_{10} \) and \( C_{20} \), may be determined by using the boundary conditions: When \( x = 0 \),
\[
W_0 = 0, \; C_{20} = 0. \]

When \( x = l \),
\[
W_0 = 0, \; C_{10} = (q l^2/48 E_c I_f). \]

Then,
\[ W_0 = -\frac{q}{24 E_c I_f} \left( \frac{3}{2} l x^3 - x^4 \right) + \frac{q l^3}{48 E_c I_f} x. \] (29)

(2) \( W_1 \) is the displacement due to the shear lag effect:
\[ W_1 = \frac{28 q}{3 E_c I_f} \left( \frac{3}{8} l - x \right) \] (30)

The solution is as follows:
\[ \xi(x) = \frac{28 q}{3 E_c I_f k^2} \left[ \frac{3}{8} l - x \right] - \frac{1}{k} \left( \theta + \frac{5 k l}{8 c k l} \right) \] (31)

in which the constants of integration, \( C_{11} \) and \( C_{22} \), may be determined by using the boundary conditions: When \( x = 0 \),
\[
W_1 = 0, \; C_{22} = 0. \]

When \( x = l \),
\[
W_1 = 0, \; C_{11} = \frac{7 q l}{k^2 E_c I_f} \left[ \frac{3}{2} + \frac{1 - c k l}{k^2} + \left( \theta + \frac{5 k l}{8 c k l} \right) \right], \]
\[ W_1 = \frac{7 q}{E_c I_f k^2} \left[ \frac{x^2}{2} + \frac{1 - c k l}{k^2} + \left( \theta + \frac{5 k l}{8 c k l} \right) \right] - \frac{7 q}{k^4 E_c I_f} \] (32)

(3) \( W_2 \) is the displacement considering shear deformation effect.
in which the constants of integration, $C_{12}$ and $C_{22}$, may be determined by using the boundary conditions:

When $x = 0$,
$$W_2 = 0, \quad C_{22} = 0.$$  

When $x = l$,
$$W_2 = 0, \quad C_{10} = \left(\frac{q_3}{48E_cI}\right).$$

Then,
$$W_2 = -\frac{q}{2G_A}x^2 + \frac{q}{2G_A}xl,$$  \hspace{1cm} (34)

For continuous box girder under concentrated loads (as shown in Figure 7), $C_{11}, C_{22}, C_{10}, C_{20}, C_{11}, C_{21}$, and $C_{22}$ are constants and can be determined from the boundary conditions at the two ends of the box girder with CSWs by the same method.

When $0 \leq x \leq (l/2)$,
$$C_{10} = (1.496/48E_cI)P_{c1}^2, \quad C_{20} = 0, \quad C_{11} = (7P/2E_cIk^2), \quad C_{21} = 0, \quad C_{12} = 0, \quad C_{22} = 0.$$  

When $(l/2) < x \leq l$,
$$C_{10} = (7.496/48E_cI)P_{c1}^2, \quad C_{20} = -(1P_3/48E_cI), \quad C_{11} = -(7P/2E_cIk^2), \quad C_{21} = (7P/2E_cIk^2), \quad C_{12} = 0, \quad C_{22} = 0.$$  

Equation (26), which considers the effects of shear lag and shear deformation, can be used to calculate the deflection of PC box girders with CSWs provided that the boundary conditions can be given. It should also be noted that the displacement of both simply supported girders and continuous girders can be calculated provided that the boundary conditions are properly defined.

4. Experimental Study

4.1. Bridge Model and Test Setup. The bridge model used in the experimental study is a one-tenth scale model built for the Juancheng Yellow River Bridge located in Shandong Province, China. This bridge model, as shown in Figure 8, is a two-span continuous concrete box girder bridge with CSWs. The length of the bridge model is 6 m in total. The bridge model is supported by a hinge in the middle and a roller support at each end. The CSWs of the bridge model have a thickness of 1.2 mm. The steel material has a yield stress of $f_{y} = 296$ MPa, Poisson’s ratio of $v_{s} = 0.3$, and Young’s modulus of $E_{s} = 206$ GPa. The compressive stress $f_{c}$, Young’s modulus $E_{c}$, and Poisson’s ratio $v_{c}$ for the upper and lower concrete flanges are taken as 51.2 MPa, 34.5 GPa, and 0.2, respectively. The dimensions of the PC box girder bridge model with CSWs are shown in Figure 8.

Two prestressing tendons were used in the bridge model, as shown in Figure 9, with the prestressing force monitored by the pressure sensors installed at the two ends of the bridge model. The prestressing tendon has a tensile strength of $f_{pk} = 1860$ MPa and Young’s modulus of $E_p = 195$ GPa. An effective prestressing force of 130 kN was applied to each prestressing tendon.

The prestressing force is only used to prevent bottom concrete flange from cracking due to the large deformation caused by the self-weight when the test girder is lifted in laboratory. During the loading test, the influence of prestress force is not considered in the model test girder.

4.2. Static Tests. In this paper, only one bridge model is made, and two loading cases were adopted to study the deflections of this bridge model. The deflection is in an uncracked stage of concrete at low level of loading, and the deflection of the composite box girder with CSWs is calculated when there is no crack in the bottom concrete flange. Load Case 1 is a uniformly distributed load, as shown in Figure 8. In this study, three different magnitudes of uniformly distributed loads were tested, namely, 2 kN/m, 4 kN/m, and 6 kN/m, respectively. Figure 10 shows a picture of the bridge model loaded with a uniformly distributed load of 4 kN/m in the laboratory.

Load Case 2 consists of two equal concentrated loads applied at the midpoints of the two spans. Three different levels of concentrated load, namely, 5.0 kN, 10.0 kN, and 15.0 kN, were adopted.

4.3. Finite Element Model for the Bridge Model. A finite element model (FEM) was created for the PC box girder bridge model with CSWs using the software ANSYS-14. The Shell63 element, which has both bending and membrane capabilities and allows both in-plane and out-of-plane loads, was used to model the CSWs. This element has six degrees of freedom (DOFs), including three translational and three...
rotational DOFs, at each node. The concrete flanges and diaphragms were all modeled using the eight-node three-dimensional (3D) solid element Solid45 [18]. This element has three translational DOFs at each node. The Solid45 element also has plasticity, creep, swelling, stress stiffening, large deflection, and large strain capabilities. The pre-stressing tendons were modeled by the 3D two-node spar element LINK8. This element is a uniaxial tension-compression element with three translational DOFs at each node. An initial strain can be given to the LINK8 element to simulate the prestressing force.

The connection between the steel webs and concrete flanges was treated as rigid connection. The same boundary conditions as described in the previous section were adopted in the finite element model. Figure 11 shows the FEM of the PC box girder with CSWs.

5. Results and Discussion

Figures 12 and 13 show the measured midspan deflections of the two spans under the uniformly distributed loads and concentrated loads, respectively. The results obtained from the finite element analysis and the developed formula are also presented for comparison. As can be seen from Figures 12 and 13, the results obtained from the developed formula match very well with the results predicted from the finite element analysis and those measured from the tested bridge model, indicating that the developed formula has satisfactory accuracy. It can also be seen from Figures 12 and 13 that the measured results of the tested bridge model are slightly smaller than the results from the finite element analysis and those measured from the tested bridge model. The reason is that actual size of bridge model is slightly larger than the design size due to the manufacturing deviation or the mold deformation, which increases the rigidity of the bridge model.
It can also be observed from Figures 12 and 13 that the deflections of the two spans increase linearly with the increase of loads, indicating that the bridge model was working in the linear-elastic range under all the loading cases considered.

6. Parametric Study

In order to further evaluate the present method, a parametric study was conducted to investigate the effects of two important parameters, namely, the width-to-span ratio and girder height, on the deflection of the girder with CSWs. The effects of shear lag and shear deformation of CSWs on the deflection of the PC box girder with CSWs were also investigated.

6.1. Effect of Width-to-Span Ratio. In order to analyze the influences of shear lag and shear deformation of CSWs on the deflection of PC box girders with CSWs under different width-to-span ratios, the height of the bridge model
was assumed as constant. Six span lengths were investigated, namely, 1 m, 2 m, 3 m, 4 m, 5 m, and 6 m, for each span of the continuous bridge, respectively, which correspond to six width-to-span ratios of 0.650, 0.325, 0.217, 0.163, 0.130, and 0.108, respectively.

Denote the contribution of the shear lag effect and shear deformation of CSWs on the total girder deflection as $J_1$ and $J_2$, respectively; $J_1$ and $J_2$ can be calculated as follows:

\[ J_1 = \text{Shear lag effect on total girder deflection (\%)} \]
\[ J_2 = \text{Shear deformation effect on total girder deflection (\%)} \]
Figures 14 and 15 show the contribution of the shear lag effect and shear deformation of CSWs on the total girder deflection under uniformly distributed loads, respectively. From Figures 14 and 15, it can be seen that the shear deformation of the CSWs has a significant influence on the deflection of the bridge girder with CSWs while the shear lag effect has a relatively small influence, which only accounts for less than 6%. In addition, it is observed that the influences of shear lag and shear deformation of CSWs decrease significantly with the increase of the width-to-span ratio. As for the influence of the shear deformation of the CSWs, the contribution is reduced from over 90% with a width-to-span ratio of 0.650 to less than 50% with a width-to-span ratio of 0.108.

Figures 16 and 17 show the contribution of the shear lag effect and shear deformation of CSWs to the total girder deflection under concentrated loads, respectively. As can be seen from Figures 16 and 17, similar observations can be made as those observed from Figures 14 and 15. From the comparison of the results under different load cases, it is also observed that the contribution of the same parameter to the total girder deflection changes under different load cases.

6.2. Effect of Girder Height. In order to analyze the influences of shear lag effect and shear deformation of CSWs on the deflection of the PC box girder with CSWs that have different heights (denoted as $h_w$ in Figure 3), the dimensions of the top and bottom flanges were kept the same. Seven CSW heights were investigated, namely, 50 mm, 100 mm, 150 mm, 200 mm, 250 mm, 300 mm, and 350 mm, respectively.
Figures 18 and 19 show the contribution of the shear lag effect and shear deformation of CSWs to the total girder deflection under uniformly distributed loads, respectively. As compared to Figures 14 and 15, it can be seen from Figures 18 and 19 that the change in the height of the CSWs does not cause a significant change in the influence of both the shear lag effect and shear deformation of CSWs on the deflection of PC continuous box girder with CSWs.

Figures 20 and 21 show the contribution of the shear lag effect and shear deformation of CSWs on the total girder deflection under concentrated loads, respectively. Similar observations can be observed in Figures 20 and 21 as those observed in Figures 18 and 19. Based on the results in this section, it can be concluded that the influence of the shear deformation on the deflection of PC continuous box girder with CSWs is significant and should be considered in practice while the influence of the shear lag effect is relatively small.

7. Summary and Conclusion

In this study, the formula for calculating the deflection of box girders with CSWs was derived. The longitudinal displacement function of PC box girders with CSWs which can consider the shear lag effect and the shear deformation of CSWs was first derived based on the in-plane shear deformation of the flange plates, the distribution law of flexural shear flow, and the quasipline section assumption of the PC box girder with CSWs. Based on the longitudinal displacement function, the deflection of box girders with CSWs was then deduced using the variational principle method. The accuracy of the formula was verified against the experimental results and FEA results. The influences of shear lag and shear deformation of CSWs on the total deflection of box girders with CSWs were also investigated. Based on the results from this study, the following conclusions can be drawn:

1. The developed formula can predict the displacement of PC box girders with CSWs with satisfactory accuracy as illustrated by the fact that the results predicted by the derived formula match very well with the experimental results and FEA results. The present method can significantly reduce the computational effort as compared to the FEA method.

2. The influence of both the shear lag effect and shear deformation of CSWs on the deflection of PC continuous box girders with CSWs decreases significantly with the increase of the width-to-span ratio while it is not affected much by the height of the CSWs.

3. The results from this study indicate that the influence of the shear deformation of CSWs on the deflection of PC continuous box girders with CSWs is significant and should be considered in practice while the influence of the shear lag effect is relatively small.

Data Availability

The data used to support the findings of this study are available from the corresponding author upon request.

Conflicts of Interest

The authors declare that they have no conflicts of interest.

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