Distortions are ubiquitous in nature. Under perturbations such as stresses, fields or other changes, a physical system reconfigures by following a path from one state to another; this path, often a collection of atomic trajectories, describes a distortion. Here we introduce an antisymmetry operation called distortion reversal that reverses a distortion pathway. The symmetry of a distortion pathway is then uniquely defined by a distortion group; it has the same form as a magnetic group that involves time reversal. Given its isomorphism to magnetic groups, distortion groups could have a commensurate impact in the study of distortions, as the magnetic groups have had in the study of magnetic structures. Distortion symmetry has important implications for a range of phenomena such as structural and electronic phase transitions, diffusion, molecular conformational changes, vibrations, reaction pathways and interface dynamics.
A distortion or distortion pathway refers to any one of the many possible paths between two or more states of a system. They are important for understanding chemical reaction kinetics\(^1\-^3\), phonon modes\(^2\-^7\), molecular pseudorotations and conformational changes\(^1\-^3\), diffusion\(^8\-^11\), the motion of interfaces such as grain boundaries\(^1\,^2\,^3\), domain walls\(^4\,^5\),\(^1\) and dislocations\(^1\,^6\,^7\), and emergent phenomena in transient or metastable states that arise from a distortion of the ground state\(^8\-^23\). There is often a privileged point on a pathway that is extremal in energy. For stable phonons, this is the ground state; for unstable phonons, the parent structure; for reaction pathways, the transition state; and for phase transitions, the saddle point. The relative energy of this point corresponds to the activation energy in the transition-state theory\(^1\,^2\,^4\). In many important pathways, it is found that the energies on either side of this privileged point are symmetric, for example, when opposite sides are mirror images of each other. An antisymmetry operation named distortion reversal, \(1^*\) is introduced here to describe the complete symmetry of such pathways. When combined with conventional symmetry groups, it gives rise to distortion groups. The symmetry of a distortion pathway is uniquely described by a distortion group.

Distortions, especially phonon modes, are studied today using representation analysis\(^5\-^7\) through decomposition onto a symmetry-adapted basis using irreducible representations (irreps). Why then is the concept of distortion-reversal symmetry and distortion groups necessary? It is instructive to look at the history, where a similar question has been posed for conventional symmetry groups, it gives rise to distortion groups. The symmetry of a distortion pathway is uniquely described by a distortion group.

In developing distortion symmetry, we discovered that a somewhat similar concept was introduced several decades ago in transition-state theory in the limited context of reversing reactants and products in simple molecular reactions\(^1\-^3\). We now make several important observations regarding the distortion-reversal operation, \(1^*\), on the distortion in Fig. 1a is the reversal of displacements \(\mathbf{u}_i\) of the atoms \(i = 1, 2, 3\) to \(-\mathbf{u}_i\) in Fig. 1b. These displacements have been decomposed in Fig. 1c into rotation (\(\mathbf{u}_{r,R}\)), translation (\(\mathbf{u}_{T,S}\), Fig. 1e), scaling (\(\mathbf{u}_{s,T}\), Fig. 1f) and deformation (\(\mathbf{u}_{D,T}\), Fig. 1g), that is, \(\mathbf{u}_i = \mathbf{u}_{r,R} + \mathbf{u}_{T,S} + \mathbf{u}_{s,T} + \mathbf{u}_{D,T}\). This is analogous to the Hellmoltz decomposition of continuous vector fields into components (see Methods). This decomposition is not necessary for implementing \(1^*\), but it is helpful to illustrate the relationship between \(1^*\) and the rotation-reversal operation, \(1^\Phi\), introduced by Gopalan and Litvin\(^30\). While \(1^\Phi\) reverses the rotation component, \(\mathbf{u}_{r,R}\) (Fig. 1e) to \(-\mathbf{u}_{r,R}\), it has no clear implications for the other components. This creates a problem in implementing \(1^\Phi\), because it requires the identification of appropriate polyhedra within a structure that exhibits rigid rotations, but not the other components; the process for such polyhedral identification is non-unique, and often approximate in real systems. In this work, no such polyhedron is required to be identified in implementing \(1^\Phi\) as seen from Fig. 1a,b. Further, \(1^\Phi\) reverses all the components of \(\mathbf{u}_i\) that is, \(1^\Phi(\mathbf{u}_{r,R}, \mathbf{u}_{T,S}, \mathbf{u}_{s,T}, \mathbf{u}_{D,T}) = (-\mathbf{u}_{r,R}, -\mathbf{u}_{T,S}, -\mathbf{u}_{s,T}, -\mathbf{u}_{D,T})\), not just rotation, \(\mathbf{u}_{r,R}\), and in this sense, \(1^\Phi\) is a special case of \(1^*\). There is an alternate way to view the action of \(1^*\) as described below, which will be used in the rest of this article. For linear atomic paths of atoms indexed by subscript \(i\), the final atomic positions \(\mathbf{r}'_i\) are given by \(\mathbf{r}'_i = \mathbf{r}_i + \mathbf{u}_{s,p}\), where \(-1 \leq \lambda \leq 1\) and \(\mathbf{r}_i\) are the initial positions of atoms, \(i\), in the intermediate state (Fig. 1h). A typical distortion pathway may begin at \(\lambda = -1\), go through an intermediate state at \(\lambda = 0\), and end at \(\lambda = +1\). We can reverse this pathway by reversing the parameter \(\lambda \rightarrow -\lambda\) while leaving the displacement amplitude \(\mathbf{u}_i\) constant. The atomic trajectories in this example are linear with respect to \(\lambda\), but in general, the pathway can be a nonlinear function \(\mathbf{r}'_i(\lambda)\); the action of \(1^*\) will then be to reverse this function \(\mathbf{r}'_i(\lambda) \rightarrow \mathbf{r}'_i(-\lambda)\).

We now make several important observations regarding the distortion-reversal operation, \(1^*\). First, in addition to the ordinary dimensions, a distortion has a time-like dimension, \(\lambda\), that describes the extent of the distortion. For a reaction pathway, this is the reaction coordinate; for a phonon mode, this is the amplitude; and for a phase transition, this is the order parameter. In this article, we normalize these over the range \(-1 \leq \lambda \leq 1\).
Scaling (     )

The blue double-headed arrow indicates that repeated application of 1
reverses these displacements,

Translation (     )

Three

distortion-reversal operation, 1
reverse the localized magnetic moments of atoms, Gopalan and
Litvin’s rotation-reversal operation, 1 is well defined on any structure that is parameterized by \( \lambda \), not just a system of discrete atomic positions and displacements. For
example, in calculating ferroelectric polarization, the modern
time-reversal operation, 1
and not the reversal of displacement vectors, will be used in the rest of this article.

Deformation (     )

Application to molecular distortions. We first demonstrate
distortion symmetry in a distortion of a simple molecule and show how it can predict relevant property changes. Figure 2 shows the pseudorotation distortion of phosphorus pentafluoride, PF3, a well-known fluxional molecule. The ground-state geometry of PF3 has 62\( m \) symmetry. The distortion proceeds by the Berry mechanism\(^2 \) where the pair of fluorine atoms on the high-symmetry axis move down as another pair of fluorine atoms move up. The structure goes through an intermediate transition state with 4\( mm \) symmetry to a final state with 62\( m \) symmetry. Although this distortion is not a rotation, the final state is equivalent to the original structure rotated by \( 90^\circ \), hence the term ‘pseudorotation’. We calculated the MEP using the NEB method\(^22 \). The MEP represents the set of most likely trajectories that atoms will follow when physically transitioning between these states, and NEB calculations discretize the distortion pathway into a sequence of ‘images’. The highest-energy example on the MEP is known as the transition state and corresponds to \( \lambda = 0 \) in Fig. 2. The energy of the transition state corresponds to the activation energy.

The MEP of the PF3 pseudorotation was determined to have
4\( mm^* \) symmetry (see the Methods section). A polynomial fit to the energy profile, \( \Delta E \), of the MEP, shown in Fig. 2a, is symmetric, that is, it is invariant under \( \lambda \rightarrow - \lambda \). This is required by the distortion group, 4\( mm^* \), as shown next. Because 1 commutes with all spatial operations, the action of any starred symmetry operation on a coefficient of the power series expansion of \( P(\lambda) \) can be determined, where \( P \) is any property of the system. Specifically, the energy, \( P = \Delta E \) in Fig. 2 is a scalar property and is invariant under rotation. By applying tensor transformation rules, we find that 4\( \Delta E(\lambda) = \Delta E(-\lambda) \). However, since 4 is a symmetry operation, Neumann’s principle\(^33,34 \) states that 4\( \Delta E(\lambda) = \Delta E(\lambda) \). Equating the two, one obtains

\[
\Delta E(\lambda) = \Delta E(-\lambda).
\]

In other words, \( \Delta E(\lambda) \) is a symmetric function of \( \lambda \), which is consistent with the fit in Fig. 2. The three bond lengths, PF1, PF2 and PF3, also follow the requirements of the 4\( mm^* \) symmetry as shown in Fig. 2. For example, 4(PF1(\( \lambda \))) = PF1(-\( \lambda \)), 4(PF2(\( \lambda \))) = PF3(-\( \lambda \)) and 4(PF3(\( \lambda \))) = PF2(-\( \lambda \)). Since 4 is a symmetry of the distortion, by Neumann’s principle, PF1(\( \lambda \)) = PF1(-\( \lambda \)), PF2(\( \lambda \)) = PF3(-\( \lambda \)), and PF3(\( \lambda \)) = PF2(-\( \lambda \)). This is consistent with the results of the NEB calculation shown in Fig. 2b.

Supplementary Note 1 and Supplementary Fig. 1 present a similar application of distortion groups to molecular vibrations in
H2O and NH3 molecules. For vibrations of NH3 corresponding to the doubly degenerate irrep, E, in particular, the distortion-symmetry framework is shown to be far more intuitive and transparent than the equivalent representation analysis. Distortion-reversal symmetry can be used to avoid the complexities of representation analysis such as in two- or higher-dimensional irreps. For many problems, distortion symmetry offers a simple and elegant alternative to traditional representation analysis.

**Application to finding an MEP.** Next, we demonstrate a symmetry-based approach to testing the stability of a pathway and checking the results of numerical computations for accuracy. This is demonstrated in the NEB calculation of activation energy for an oxygen atom diffusing across a C6 ring on the surface of graphene (Fig. 3a,b). Although not typically thought of as a 'distortion', this diffusion path is a distortion within the symmetry framework presented in this article. Linear interpolation from the state with oxygen on the right (\(\lambda = -1\)), to the state with oxygen on the left (\(\lambda = +1\)) creates a path with \(m \times m^2\) symmetry with a high-activation-energy barrier (Fig. 3a,b); this is not an MEP. Typically, only the first and last images are specified when setting up a NEB calculation and a linear path, such as this would be constructed by default by the NEB implementation. For example, this is the case for VTST Tools for VASP and neb.x for Quantum Espresso (QE). Relaxing this path using NEB cannot and does not change the \(m \times m^2\) symmetry, because every NEB iteration must conserve distortion symmetry (Fig. 3c,d; Supplementary Note 2; Supplementary Figs 2–5), since the forces are balanced by symmetry. Without understanding that the symmetry needs to be broken, one might incorrectly conclude that the activation barrier for oxygen diffusion on graphene is several times larger than it actually is. We can now systematically explore perturbations to this path by using the irreps of \(m \times m^2\) summarized by the character table given in Table 1.

For a distortion path discretized into \(M\) images with \(N\) atoms, the perturbations form a 3NM-dimensional space; this is similar to the 3N-dimensional space of phonons. Similar to the methods applied to studying phonons and in mode crystallography, we can use the irreps in Table 1 to construct a symmetry-adapted basis (Supplementary Note 1) from an arbitrary basis set for general perturbations of the path. Using perturbations associated with the irreps, \(\Gamma_2\), \(\Gamma_3\) and \(\Gamma_4\), we can reduce the symmetry of our initial guess path to the symmetry of their kernels, \(2^*\), \(m\) and \(m^*\) respectively. To achieve a trivial symmetry (point group 1) path, we can combine these. For the example in Fig. 3, subspaces associated with \(\Gamma_2\) and \(\Gamma_3\) are stable (Fig. 3c), while for the subspace associated with \(\Gamma_4\) (Fig. 3d), one or more directions are unstable, that is, small perturbations of the path in these directions will decrease the energy of the path and there will be a net force driving the path away from \(m \times m^2\) and towards the \(m^*\) path symmetry as seen in Fig. 3d. This is similar to the unstable phonons of an unstable structure. The stability or instability of any path perturbation could clearly be calculated using a method analogous to finite displacement methods used for calculating phonon frequencies of static structures. Using a symmetry-adapted basis for the perturbations of a distortion path would convey the same benefits as it does for phonon calculations, for example, reducing the force constants matrix to block diagonal form.

Figure 3e shows that the path with trivial symmetry (that is, point group 1) relaxes to a much lower-energy path with \(m^*\) symmetry. The perturbations are exaggerated in Fig. 3; the maximum displacement of oxygen along the path was 0.1 Å in panel a and about 0.18 Å in panel b. Because NEB can only raise the symmetry of the path, not lower it (see Methods), the \(2^*\) path cannot achieve the same results and has approximately the same energy as the original relaxed \(m \times m^2\) path. Essentially, the same path as our \(m \times m^2\) path was studied by Dai et al.35 who reported a high-energy transition state with a barrier of 1.75 eV. Dai et al. also report a lower-energy transition state, apparently similar to our 0.66 eV state, but with 0.81 eV and an energy profile that is highly asymmetric with respect to the distortion coordinate. It thus erroneously violates the \(m^*\) symmetry that our symmetry analysis in Fig. 3 indicates it must possess. Such unintentional errors are in fact quite common in literature as the survey...
distortion symmetry would have been useful; this is clearly a very small subset of such studies. Distortion symmetry analysis can help identify errors and properly symmetrize computational results. We implemented a two-dimensional potential energy surface similar to the oxygen diffusion on graphene problem (see Supplementary Note 3; Supplementary Fig. 6 and Supplementary Software 1) to test whether there are potential efficiency gains in an NEB code by implementing distortion-reversal symmetry. The results shown in the histograms in Fig. 3f suggests that NEB codes can potentially converge in about half as many iterations if distortion symmetry is implemented. This benefit is in addition to the benefit of reducing the number of asymmetric images that would be necessary. Together, these two benefits may potentially speed up NEB convergence by a factor of four, that is, a fourfold reduction in total central processing unit (CPU) time, for paths with starred symmetry. Finally, our brief examples in Supplementary Table 1 indicate. Supplementary Table 1 gives 50 examples of published studies where distortion symmetry would have been useful; this is clearly a very small subset of such studies. Distortion symmetry analysis can help identify errors and properly symmetrize computational results. We implemented a two-dimensional potential energy surface similar to the oxygen diffusion on graphene problem (see Supplementary Note 3; Supplementary Fig. 6 and Supplementary Software 1) to test whether there are potential efficiency gains in an NEB code by implementing distortion-reversal symmetry. The results shown in the histograms in Fig. 3f suggests that NEB codes can potentially converge in about half as many iterations if distortion symmetry is implemented. This benefit is in addition to the benefit of reducing the number of asymmetric images that would be necessary. Together, these two benefits may potentially speed up NEB convergence by a factor of four, that is, a fourfold reduction in total central processing unit (CPU) time, for paths with starred symmetry. Finally, our brief

**Figure 3** | The consequences of distortion symmetry and balanced forces for NEB calculations. (a–d) Superimposed images along oxygen (red atom) diffusion paths on graphene (grey carbon atoms connected by grey bonds). In a and b, an initial linear path is assumed for the diffusion of a single oxygen atom from right ($\lambda = -1$) to left ($\lambda = +1$), across a $C_6$ graphene ring. The symmetry of the path in a and b is $m'm^2$; the symmetry traps the path and prevents convergence to a minimum-energy pathway (MEP). To break the $m'm^2$ symmetry, we perturb this linear path as $m'm^2 \rightarrow 2^*$ and $m'm^2 \rightarrow 1$, respectively, as shown schematically exaggerated as green curves in a and b and indicated by the text in the inset. (c, d) The final paths after NEB relaxation starting from the perturbed paths of a and b, respectively, as indicated by red vertical arrows. The paths c and d have distortion symmetries of $2^*$ and $m'$, respectively. The $2^*$ symmetry continues to trap the transition state (just like $m'm^2$ did for the linear path), whereas the initial path with trivial symmetry can correctly converge to a MEP with $m'$ symmetry. (e) The calculated energies of the images and the interpolation provided by QE's NEB module. (f) Results for an example two-dimensional potential energy surface inspired by the above problem, using a simple NEB implementation. The plots are smoothed and rescaled histograms showing the frequency of NEB convergence at a given number of iterations in this example system for 100,000 randomly generated initial paths each with $m'$ or with trivial symmetry of 1. The two curves are rescaled to the same maximum height. Symmetrizing using the correct symmetry, $m'$ (red curve) reduced the number of NEB iterations needed in 98.97% of test cases. The average reduction was $\sim 2.3 \times$ as compared with conventional symmetry (blue curve). This demonstrates that distortion symmetry can reduce the number of NEB iterations necessary for convergence.
survey in Supplementary Table 1 suggests that a large number of references to the use of NEB in materials science are made in the study of pathways with energetically equivalent end points, such as in diffusion, dislocation, interface, and grain boundary motion, and ferroelectric and magnetic switching of domains36, and therefore may have distortion-reversing symmetries.

**Application to crystals and tensor properties.** Next we demonstrate the application of distortion groups in predicting allowed energy couplings that are odd powers in the distortion parameter and may appear at first to be disallowed by conventional symmetry groups. We will use beta barium borate, $\beta$-BaB$_2$O$_4$, a widely used nonlinear optical crystal, as an example. Using a parent structure ($\lambda = 0$) with $R\bar{3}c$ symmetry, we construct a distortion with $R\bar{3}c$ variants at $\lambda = -1$ and $\lambda = +1$. This distortion pathway has $R\bar{3}c$ symmetry. The calculated energy profile, $\Delta E(\lambda)$, is shown in Fig. 4a and is symmetric with respect to $\lambda$. This is a consequence of the starred symmetry operations, just as with the PF$_5$ example. In Fig. 4b, we depict the sequence of intermediate structures along the distortion pathway by superimposing them using a colour scale. From the blurred pattern, we can see that this distortion is mostly the nearly rigid rotation of the B$_3$O$_6$ rings. For $\beta$-BaB$_2$O$_4$ and distortion group $R\bar{3}c$ (no. 4306 in the complete double-antisymmetry space group (DASG) listing38,39), the B$_3$O$_6$ rings are on the 12c site. From referring to the listing, this means that there are rings located at [0, 0, 0], [0, 0, 0 - z + 1/2], [0, 0, z], and [0, 0, z + 1/2] with rotation vectors of [0, 0, $\omega_x$], [0, 0, $\omega_y$], [0, 0, $-\omega_x$] and [0, 0, $-\omega_y$], respectively. This tells us that the $R\bar{3}c$ symmetry requires that the rotation (or) of the rings is only along the $z$ axis and alternates every two rings along the column, that is, clockwise, clockwise, counterclockwise, counterclockwise and so on. The distortion symmetry listing also tells us that the displacement of the rings is only along the $z$ axis and all the rings displace in the same direction with the same magnitude. This is just one of the many ways in which the concept of distortion symmetry can be used to make useful predictions about distortions.

Table 1 | The character table of the distortion group $m'm^2$m$^2$.

| 1   | 2$^*$ | $m$ | $m^2$ | Kernel |
|-----|-----|-----|-------|--------|
| $\Gamma_1$ | 1   | 1   | 1     | 1      |
| $\Gamma_2$ | 1   | -1  | 1     | 1      |
| $\Gamma_3$ | 1   | -1  | -1    | -1     |
| $\Gamma_4$ | 1   | -1  | -1    | 1      |

The four one-dimensional irreducible representations (irreps), $\Gamma_1-\Gamma_4$, represent four distinct types of perturbations to a distortion pathway with $m'm^2$m$^2$ symmetry. Each irrep has a kernel symmetry shown in the last column.

Figure 4 | The application of distortion symmetry to a distortion of $\beta$-BaB$_2$O$_4$. The mostly rigid rotation of the B$_3$O$_6$ rings leads to two variants of $\beta$-BaB$_2$O$_4$ with $R\bar{3}c$ symmetry group, the $\lambda = -1$ variant (inset in orange in a) and the $\lambda = +1$ variant (inset in cyan in a), transforming through a transition state at $\lambda = 0$ (inset in magenta in a) with a symmetry of $R\bar{3}c$. The symmetry of this path, $R\bar{3}c$, requires that the energy profile in a is symmetric. (b) The superimposed images of $\beta$-BaB$_2$O$_4$ along the distortion pathway, their colour varies from orange, through magenta to cyan as $\lambda$ varies from $-1$ through $0$ to $+1$. (c) The optical second harmonic generation tensor coefficients along this pathway calculated by Cammarata and Rondinelli37 (red, green and blue circles) and a polynomial fit (red, green and blue lines) using only the coefficients that are consistent with $3'$m point-group symmetry. Distortion symmetry predicts that these coefficients will be odd functions of the distortion parameter, $\lambda$, and zero when $\lambda = 0$. That the function should be odd with respect to $\lambda$, and hence the even coefficients (A, C and so on) should be exactly zero. It also clearly implies that $d_{ijkl}(0) = 0$. The points marked by open circles at $\lambda = 1.0$ and $\lambda = 2.0$ are from previously reported calculations37. The curves are the result of solving for $d_{ijkl}(\lambda) = B_{ijkl}\lambda + D_{ijkl}\lambda^3$ that goes through these points. Since it was not obvious a priori that $d_{ijkl}$ should be an odd function of this distortion, this example demonstrates how applying distortion symmetry predicts the
form of the tensors that describe the change in any property as a function of a distortion. This also suggests that in the Landau phenomenology, there should be an energy coupling of the form
\[ U \propto Q_{ijk} P^{2\alpha}_{ij} P^{2\beta}_{jk} \lambda + R_{ijk} P^{2\alpha}_{ij} P^{2\beta}_{jk} \lambda^3 \tag{3} \]
in the parent \textit{R}3\textit{c} (point group \textit{3m}) phase. However, the polar third-rank tensors \( Q_{ijk} \) and \( R_{ijk} \) would be identically zero in the conventional \textit{3m} parent phase as deduced by noticing that \( I(\pi) = -P \) and \( I(\lambda) = \lambda \). The only way such a coupling would exist is if the complete distortion symmetry of the pathway, namely, \( \textit{3}m \) is considered, since \( I(\pi) = -P \) and \( I(\lambda) = -\lambda \). This example shows the value of distortion symmetry analysis in easily revealing energy invariants that are odd powers in \( \lambda \). It is far more transparent than the corresponding representation theory-based analysis.

Including distortion-reversing symmetry operations (that is, starred operations) can place greater restrictions on invariant property tensors. Table 2 compares the form of various types of tensors for a conventional symmetry group versus a group that includes starred operations corresponding to the distortion of the \( \beta\)-Ba\textsubscript{2}BO\textsubscript{4} given in Figure 4. Because of how the \( A_{ijk} \) and \( C_{ijk} \) terms transform, \( A_{ijk} \) and \( C_{ijk} \) are \( 1 \)-even third-rank polar tensors. Likewise, \( B_{ijk} \) and \( D_{ijk} \) are \( 1 \)-odd third-rank polar tensors. From consulting Table 2, we find that the power series expansion of \( d_{ijk}(\lambda) \) to the third power contains half as many degrees of freedom if the full symmetry group \( 3 \text{m} \) is considered instead of only the unstarred symmetry of the distortion, \( \textit{3m} \). If instead of the \( P^{2\alpha}_{ij} = d_{ijk} E^{\alpha}_{ij} E^{\beta}_{jk} \) interaction, we had considered \( P^{2\alpha}_{ij} = d_{ijk} E^{\alpha}_{ij} (\nabla \times E)^{\alpha}_{jk} \) as an example, then the corresponding tensors \( A_{ijk} \) and \( C_{ijk} \) in an expansion similar to (2) would be axial \( 1 \)-even, \( 1 \)-even tensors, while the tensors \( B_{ijk} \) and \( D_{ijk} \) would be axial, \( 1 \)-odd, \( 1 \)-even tensors. Their forms and how they differ between the distortion group and conventional group is also given in Table 2. Thus, distortion symmetry can significantly reduce the number of tensor coefficients that are predicted to be non-zero.

**Application to diverse phenomena.** The ubiquity of distortion symmetry is further illustrated in Fig. 5 with four examples. Each panel depicts the structures from \( \lambda = -1 \) to \( \lambda = +1 \). The tensor coefficients shown for each structure in an energy invariant form of the form \( U \propto P^3 \) or \( P^5 \) are identical between the two symmetry groups. Four other tensor types, namely, polar \( 1 \)-odd \( 1 \)-odd, polar \( 1 \)-odd \( 1 \)-even, axial \( 1 \)-odd \( 1 \)-odd and axial \( 1 \)-odd \( 1 \)-even, have identical tensor forms for the two symmetry groups, and hence are not shown.

### Table 2 | Tensor forms for \( \textit{3m} \) versus \( \textit{3m} \) symmetry groups.

| Rank | Type | 1\text{st} | 2\text{nd} | 3\text{rd} | 4\text{th} |
|------|------|--------|--------|--------|--------|
| Polar | 1\text{st} even | 0 | 0 | 0 | 0 |
|       | 1\text{st} odd | 0 | 0 | 0 | 0 |
|       | 2\text{nd} even | 0 | 0 | 0 | 0 |
|       | 2\text{nd} odd | 0 | 0 | 0 | 0 |
|       | 3\text{rd} even | 0 | 0 | 0 | 0 |
|       | 3\text{rd} odd | 0 | 0 | 0 | 0 |
|       | 4\text{th} even | 0 | 0 | 0 | 0 |
|       | 4\text{th} odd | 0 | 0 | 0 | 0 |

A comparison of the form of various general tensors of different ranks (columns) and types (rows) that are predicted by the distortion group \( \textit{3m} \) versus that predicted by the conventional \( \textit{3m} \) symmetry group, which are the distortion symmetry and conventional symmetry groups, respectively, of the distortion path for \( \beta\)-Ba\textsubscript{2}BO\textsubscript{4}. For example, the second row, sixth column corresponds to the form of a general \( 1 \)-even third-rank polar tensor, \( Q_{ijk} \) (\( j \)-\( k \) correspond to an orthogonal crystal physics coordinate system) that is invariant under time reversal, \( 1 \), and distortion reversal, \( 1 \). The tensor coefficients shown in colour are the predictions that differ between the distortion symmetry (in green) versus the conventional symmetry group (in red). The remaining coefficients in black correspond to predictions that are identical between the two symmetry groups. Four other tensor types, namely, polar \( 1 \)-odd \( 1 \)-odd, polar \( 1 \)-odd \( 1 \)-even, axial \( 1 \)-odd \( 1 \)-odd and axial \( 1 \)-odd \( 1 \)-even, have identical tensor forms for the two symmetry groups, and hence are not shown.
made available by VanLeeuwen et al. These kinds of distortion pathways should exist in most ferroelectrics and multiferroics. One can analyse what pathways a domain wall could take in moving by a unit cell inside a ferroelectric, a ferromagnet or a multiferroic, using methods similar to the oxygen diffusion problem discussed in Fig. 3.

The 670 cm$^{-1}$ B$_{1u}$ mode of a superconductor, YBa$_2$Cu$_3$O$_{6.5}$, is shown in Fig. 5d. This mode has a distortion symmetry of Pm$'$/m/m, and has recently been shown to couple with A$^g$ modes to create a transient structure that was reported to exhibit room-temperature coherent interlayer transport on picosecond timescales, reminiscent of superconductivity. Including the coupling between this B$_{1u}$ mode and the A$^g$ modes retains the same distortion symmetry. The form of the invariant tensors describing changes in any property in these example systems as a function of distortion can be deduced, similar to that shown in Table 2.

Application to the electronic structure and Berry phase. Finally, we show that distortion symmetry can be applied to the electronic structure of a distortion and has implications for Berry phase calculations. Ceresoli and Tosatti give the Berry phase along a path as:

$$\gamma \cong - \Im \log \det \prod_{\xi=0}^{N-1} \langle \psi_{\xi} | \psi_{\xi+1} \rangle$$

where $\xi = 0$ through $\xi = N$ are the indices of discrete images along the path (that is, each corresponds to a set of nuclear positions which can be used to compute the ground state electronic structure, $\psi_{\xi}$). The product expressed in equation (4) for Berry phase expands as follows:

$$\prod_{\xi=0}^{N-1} \langle \psi_{\xi} | \psi_{\xi+1} \rangle = \langle \psi_0 | \psi_1 | \psi_2 | \cdots | \psi_{N-2} | \psi_{N-1} | \psi_N \rangle$$

(5)

1$^*$ reverses the path such that the last image (at $\xi = N$) becomes the first image (at $\xi = 0$) and vice versa. Thus:

$$1^* (\langle \psi_0 | \psi_1 | \psi_2 | \cdots | \psi_{N-2} | \psi_{N-1} | \psi_N \rangle) = \langle \psi_N | \psi_{N-1} | \psi_{N-2} | \psi_{N-3} | \cdots | \psi_1 | \psi_0 \rangle$$

(6)

Substituting this into equation (4) for the Berry phase and simplifying leads to the conclusion that $1^* \gamma = - \gamma$ for $|\gamma| < \pi$. Thus, if a distortion path is invariant with $R^*$ symmetry (that is, if $R^* \gamma = \gamma$, for any Euclidean motion, $R$), then we conclude that

$$\gamma = 0.$$
Thus, for a path with $1^*$ symmetry, $\gamma = 0$ (assuming $|\gamma| < \pi$). Because $\gamma$ is invariant under rotations, mirrors and translations (that is, Euclidean motions, $R$), this general result states that for any distortion pathway with a starred symmetry, $R^*$, the Berry phase will be exactly zero. This includes all the example distortions given in this work that are described by distortion groups that contain any operation $R^*$.

**Discussion**

In the course of this study, we have come to conclude that distortion symmetry introduced here has applicability to a very wide range of physical problems, including atomic and electronic structure reconfigurations, reconfigurations of proteins and other biomolecules, motion of domain walls and grain boundaries, distortion tuning of metamaterials such as those exhibiting photonic bandgaps, distortion-reversal symmetry protection of topological boundary modes analogous to time-reversal symmetry protection of topological insulators via Kramers theorem, the search for transient and metastable phases exhibiting emergent properties under a distortion and the search for intermediate stable structures in materials away from equilibrium, by reducing the asymmetric domain. The double-antisymmetry groups created from incorporating both distortion-reversal and time-reversal antisymmetries could be applied to explore the energy landscape of magnetic structures under a distortion. Similar to the impact of time-reversal antisymmetry and magnetic groups, we foresee a commensurate impact of distortion-reversal antisymmetry and distortion groups on a diverse set of problems and design tools used in the physical sciences.

**Methods**

**The decomposition of a vector field.** The decomposition applied to the simple distortion seen in Fig. 1 was performed by selecting a basis for translation, rotation, scaling and deformation components. Supplementary Fig. 1 shows an example of such a basis for a water molecule and, in this case, it is also symmetry adapted. After the basis is selected, the displacement vectors are projected onto it and each component can be isolated as shown in Fig. 1. This and other notions of decomposition into rotational and non-rotational components were explored in our attempts to formalize the concepts of rotation-reversal symmetry.

**PF, pseudorotation NEB calculations.** The PF, pseudorotation NEB calculation was performed using DMol3 in Materials Studio 6.0 (ref. 32). The approximate structure was input using Materials Studio’s tools and then geometrically optimized using DMol3. This structure was taken as the $\lambda = 0$ variant and was copied and rotated 90° around the high-symmetry axis to make the $\lambda = 1$ variant. Then the Transition State Preview tool was used to match the atoms of the structures and generate an initial guess path. This guess was used as input for the DMol3 Transition State Search tool whose output was then run in the Transition State Conformation Tool, which performs NEB to find a MEP. The output from NEB was symmetrized to remove the small asymmetric numerical errors and used to construct the plots in Fig. 2.

**Oxygen diffusion on graphene NEB calculations.** These calculations were from an example calculation used at the QE2014 workshop held at PennState. The $\lambda = 0$ structure consists of a 3 x 3 supercell of graphene with an oxygen atom bonded to the surface, as part of an epoxy functional group. This was mirrored to create the $\lambda = -1$ structure. These structures were used as the first and final images in the input for QE’s NEB module (neb.x). Seven images were used. These are linearly interpolated from the first and final images. This initial guess path, discretized into a chain of seven images, relaxed into the path seen in Fig. 3a and Fig. 3b with $m^* m^*$ symmetry.

Next, two new paths were created from the $m^* m^*$ path using small symmetry-breaking perturbations of the oxygen trajectory parallel to the graphene sheet. The first was a sinusoidal perturbation with an amplitude of 0.1 Å resulting in a path with 2* symmetry. The second was a perturbation of $- (\ell^2 + 5x^2 - 6.2x - 3(3x^2 + 7x + 3)/32 \; \Lambda$ resulting in a path with only trivial symmetry (that is, point group 1). These two new paths were then relaxed using QE’s NEB module again to get the paths shown in Fig. 3c,d.

The reason that small symmetry operations affect the results of NEB calculations in this way is because NEB commutes with $1^*$ in the same way that conventional symmetry operations commute with physical laws. Clearly, NEB(X) gives the same result as $A^{-1}$NEB(AX) where $X$ is the initial guess path and $A$ is an ordinary symmetry operation, such as a rotation or a mirror. Similarly, NEB(X) gives the same result as $1^{-1}$NEB(1X) and, since $1^{-1} = 1$, NEB(X) gives the same result as $1$NEB(1X). This is no different from the idea that physical laws should not depend on what basis one chooses for their coordinate system. If $A^*$ is a symmetry of the initial guess path, that is, $\lambda = X \cdot A$, then, by substitution, NEB(X) = $A^*X$NEB(X). Thus, due to the commutativity of $A^*$ with NEB, $X \cdot A^*$ implies NEB(X) = $A^*$NEB(X), that is, a symmetry of the initial guess will also be a symmetry of the results. In practice, however, $A^{-1}$NEB(X) is not exactly equal to NEB(X) because the NEB implementation will have small symmetry-breaking numerical errors.

**Method for determining the distortion symmetry group.** Let $S(\lambda)$ denote the structure at $\lambda$. Let $G(\lambda)$ denote the conventional symmetry group of $S(\lambda)$. If there exists $A \in GL(n, \mathbb{Z})$ such that $S(A\lambda) = S(\lambda)$ for all $1 \leq \lambda \leq 1 + \theta$, then the symmetry of the distortion is $H \cdot (\lambda A)$. $H = \prod_{k=1}^{m} G(\lambda_k)$ (where $\lambda_k = \lambda$). Otherwise, $H$ is the symmetry of the distortion. In other words, find the conventional symmetry group of all the images in a pathway ($\lambda_k$ from 1 to 1+ $\theta$); the intersection of these groups is the group $H$. Now find an element $A$ in the conventional symmetry group of the structure at $\lambda = 0$ that can transform a structure at $k$ to a structure at $\lambda = k$. The distortion group of the pathway is then $H \cdot A \cdot H$. If no such A can be found, then $H$ is the symmetry of the distortion pathway.

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Author contributions

B.K.V. found the initial problems with V.G.’s rotation-reversal symmetry and distortion symmetry evolved out of the discussions with V.G. about these problems. V.G. suggested looking for approaches that work directly with atomic displacements from parent structures. B.K.V. contributed the idea of replacing polyhedral rotations with the general parameterization of a pathway by λ, 1° for reversing λ and the application to NEB and the transition-state theory. V.G. contributed sections on applying Neumann’s principle, Landau phenomenology (energy couplings and energy invariants), initial ideas on the decomposition seen in Fig. 1 and proposed studying the distortions seen in Figs 4 and 5, and Supplementary Fig. 1. B.K.V. and V.G. co-wrote the paper and made the figures. Computational results and Supplementary Table 1 are from B.K.V.

Additional information

Supplementary Information accompanies this paper at http://www.nature.com/naturecommunications

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