Hybrid quantum-classical master equations

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Abstract
We discuss hybrid master equations of composite systems, which are hybrids of classical and quantum subsystems. A fairly general form of hybrid master equations is suggested. Its consistency is derived from the consistency of Lindblad quantum master equations. We emphasize that quantum measurement is a natural example of exact hybrid systems. We derive a heuristic hybrid master equation of time-continuous position measurement (monitoring).

Keywords: open quantum systems, hybrid quantum-classical dynamics, hybrid kinetic equations

1. Introduction

The notion of hybrid systems—consisting of quantum and classical subsystems—arises in different contexts (e.g., refs. [1–18]). We are interested in those works which are using the notion of hybrid density explicitly, or implicitly at least, with a standard statistical interpretation. Hybrid dynamics in the narrow sense means dynamical coupling between a quantum and a classical dynamical system. Sometimes the latter is just another quantum subsystem described in classical phase space variables, but in all versions the coupling results in irreversibilities [1, 3, 7, 9, 12]. Hybrid formalism of quantum measurement means the irreversible interaction between a quantum dynamical system and the classical pointer of the measuring device cf, e.g., [2, 12, 15, 16]. Hybrid dynamics in the general sense means any—not necessarily canonical, unitary, or even reversible—dynamics of coexisting quantum and classical states and variables cf [10, 11].

The mathematical representation of hybrid systems unifies the mathematical representations of classical and quantum systems, respectively. The notion of hybrid density \( \hat{\rho} (x) \), to represent the hybrid state, follows from the notions of classical density \( \rho (x) \) and quantum density matrix \( \hat{\rho} \) in a straightforward way. (See section 2 for the rigorous definition.) An exact application of hybrid formalism is no doubt the action of quantum measurement (section 3). The hybrid dynamical equation, or master equation (ME), is an open issue. One can profit from the generic Pauli and Lindblad MEs of separate classical and quantum systems, respectively. We shall offer a partial solution as to the general structure of hybrid MEs (sections 4, 5). The lessons are applied in section 6 to construct the hybrid ME of time-continuous measurement (monitoring).

2. Hybrid density

As we mentioned, the general hybrid system consists of a quantum system and of any—not necessarily dynamical—classical system, including discrete as well as continuous classical systems. For example, let us, consider a classical system described by a discrete variable \( x \) of probability density \( \rho (x) \), together with an independent quantum system of state \( \hat{\rho} \). To model their coexistence, we form their hybrid system, whose hybrid state must be

\[
\hat{\rho} (x) = \rho (x) \hat{\rho}.
\]

The general, correlated, hybrid state must be positive semidefinite:

\[
\hat{\rho} (x) \geq 0, \quad \forall \ x
\]

and normalized:

\[
\text{Tr} \left( \sum_x \hat{\rho} (x) \right) = 1.
\]

The conditions (2, 3) are necessary and sufficient for \( \hat{\rho} (x) \) to be a legitimate hybrid density.

We define the reduced state (density matrix) of the quantum subsystem by

\[
\hat{\rho} = \sum_x \hat{\rho} (x),
\]

the reduced state (density) of the classical subsystem by

\[
\rho (x) = \text{Tr} \hat{\rho} (x),
\]

and the conditional state (density matrix) of the quantum
Table 1. States and dynamics in classical, quantum, and hybrid systems.

|                  | Classical | Quantum | Hybrid |
|------------------|-----------|---------|--------|
| Density:         | $\rho(x)$ | $\dot{\rho}$ | $\hat{\rho}(x)$ |
| Master equation: | Pauli     | Lindblad | ?      |

subsystem by

$$\hat{\rho} = \hat{\rho}(x)/\rho(x).$$  \hspace{1cm} (6)

Note that the conditional state of the classical subsystem is pointless, since the quantum subsystem does not feature conditions unless we perform a quantum measurement on it (table 1).

The statistical interpretation of the hybrid density is straightforward from the statistical interpretation of density matrices and classical densities. Let $\hat{O}(x) = \sum_x \hat{O}(x)\hat{\rho}(x)$ stand for the generic hybrid observable. Its expectation value can be calculated as follows, cf. e.g., [7]:

$$\{\hat{O}(x)\}_{\hat{\rho}(x)} = \text{Tr} \sum_x \hat{O}(x)\hat{\rho}(x).$$  \hspace{1cm} (7)

Having outlined the abstract features, let’s see an occasional list of very different hybrid systems with their respective hybrid densities. In molecular physics, $\hat{\rho}$ refers to quantized electrons and $(r, p)$ stands for classical nuclear positions and momenta yielding $\hat{\rho}(r, p)$ [3]. In quantum optics $\hat{\rho}$ refers to quantized electrons and $a$, $a^\dagger$ stand for the complex amplitudes of classical e.m. field modes yielding $\hat{\rho}(a, a^\dagger)$ [7]. In nanophysics $\hat{\rho}$ refers to the quantum dot and $n$ stands for the charge count yielding $\hat{\rho}(n)$. Last but not least, in quantum measurement $\hat{\rho}$ refers to the measured quantum system and $x$ stands for the measurement outcome yielding $\hat{\rho}(x)$ [12], as discussed below.

3. Measurement

What happens to the quantum state $\hat{\rho}$ of a quantum system, under measurement of the complete set of orthogonal projectors $\{\hat{P}_s\}$? We argue that hybrid formalism and interpretation are exact alternatives to the standard ones in textbooks. Textbook formalism says that the pre-measurement state $\hat{\rho}$ jumps randomly to the post-measurement conditional quantum state $\hat{\rho}_s$:

$$\hat{\rho} \longrightarrow \hat{\rho}_s = \frac{1}{\rho(x)}\hat{P}_s\hat{\rho}\hat{P}_s,$$  \hspace{1cm} (8)

with probability $\rho(x) = \text{Tr}(\hat{P}_s \hat{\rho}\hat{P}_s)$.

In hybrid formalism, we say that $\hat{\rho}$ jumps deterministically into the post-measurement hybrid state:

$$\hat{\rho} \longrightarrow \hat{\rho}(x) = \hat{P}_s \hat{\rho}\hat{P}_s.$$

The randomness of the outcome $x$ is now expressed through the statistical interpretation (7), as well as (4–6), of the hybrid state.

In complete generality, hybrid formalism is convenient for general (unsharp) quantum measurements defined by Kraus operators $\hat{M}_i$ instead of projectors $\hat{P}_s$, satisfying completeness $\sum_i \hat{M}_i\hat{M}_i^\dagger = \hat{I}$ but without orthogonality or hermiticity. In hybrid formalism, measurement is fully represented by the jump of the pre-measurement quantum state $\hat{\rho}$ into the post-measurement hybrid state:

$$\hat{\rho} \longrightarrow \hat{\rho}(x) = \hat{M}\hat{\rho}\hat{M}_i^\dagger.$$  \hspace{1cm} (10)

The statistical interpretation of $\hat{\rho}(x)$ reproduces the common rules (8) of measurement.

A remarkable example is the Gaussian unsharp position measurement whose Kraus operators are

$$\hat{M}_{\sigma} = \hat{M}_{\sigma}^\dagger = (2\pi\sigma^2)^{-1/4} \exp\left[-\frac{(q - x)^2}{4\sigma^2}\right].$$  \hspace{1cm} (11)

i.e., the square roots of unsharp ‘projectors’ labeled by their central positions $x$ (which are continuous classical variables this time). Their measurement in hybrid formalism (10) reads:

$$\hat{\rho} \longrightarrow \hat{\rho}(x) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left[-\frac{(q - x)^2}{4\sigma^2}\right] \hat{\rho} \exp\left[-\frac{(q - x)^2}{4\sigma^2}\right].$$  \hspace{1cm} (12)

This is the key to the time-continuous position measurement (monitoring) theory [19, 20]. (For a heuristic derivation of the corresponding hybrid ME, see section 6). We study general hybrid MEs first.

4. Hybrid dynamics

All Markovian classical MEs must have the Pauli form [21]:

$$\frac{d\rho(x)}{dt} = \sum_y \left[T(x,y)\rho(y) - T(y,x)\rho(x)\right],$$  \hspace{1cm} (13)

where $T(x,y) \geq 0$ is an arbitrarily given transition rate from $y$ to $x$. Note for completeness that also a drift term $-\partial_y v(x)\rho(x)$ of arbitrarily given drift velocity $v(x)$ can be added to the r.h.s. when $x$ is a continuous variable. In this case, the transition rates $T(x,y)$ can be smooth non-negative functions, but the particularly important diffusion process requires the singular ones:

$$T(x,y) = \lim_{\tau \rightarrow 0} \frac{1}{\sqrt{4\pi D\tau}} \exp\left[-\frac{(x - y)^2}{4D\tau}\right].$$  \hspace{1cm} (14)

Substituting this form into the ME (13) yields the standard diffusion ME:

$$\frac{d\rho}{dt} = D\hat{\nabla}^2\rho(x)$$  \hspace{1cm} (15)

with the diffusion coefficient $D$. 

All Markovian quantum MEs must have the Lindblad form [22]:
\[
\frac{d\hat{\rho}}{dt} = -i\left[\hat{H}, \hat{\rho}\right] + \sum_a \left[\hat{L}_a \hat{\rho} \hat{L}_a^\dagger - \frac{1}{2} \left\{ \hat{L}_a^\dagger \hat{L}_a, \hat{\rho} \right\}\right],
\]
where \(H\) is the Hamiltonian and \(\hat{L}_a\) are arbitrarily given Lindblad operators (transition amplitudes). In a particularly simple case, we have a single Hermitian Lindblad operator proportional to the position operator \(\hat{q}\) of a particle: 
\[
\hat{L} = \hat{L} = \sqrt{2D'} \hat{q}.
\]
This yields
\[
\frac{d\hat{\rho}}{dt} = -i\left[\hat{H}, \hat{\rho}\right] - D' \left[\hat{q}, \hat{q}, \hat{\rho}\right].
\]
which describes momentum diffusion and, equivalently, position decoherence with coefficient \(D'\). Note this quantum while
\[
\hat{\rho} = \hat{\rho} \hat{\rho}^\dagger = \sum_a \left[\hat{L}_a^\dagger \hat{L}_a \hat{\rho} \hat{L}_a \hat{L}_a^\dagger - \frac{1}{2} \left\{ \hat{L}_a^\dagger \hat{L}_a, \hat{\rho} \right\}\right],
\]
and take partial trace on both sides. The result \(\hat{\rho} = \hat{\rho} \hat{\rho}^\dagger\) is known to violate the positivity of \(\hat{\rho}\). Therefore the consistency of the latter is guaranteed by the Lindblad ME (22). This a central result of our work.

6. Quantum monitoring

We are going to construct the phenomenological hybrid equations of quantum monitoring. Suppose we are continuously measuring (monitoring) the position \(\hat{q}\). The classical variable \(X\) will encode the monitored value, so we introduce the hybrid density \(\hat{\rho}(X)\) to represent the joint statistics of the particle quantum observables and the monitored value of \(\hat{q}\).

The hybrid ME that evolves \(\hat{\rho}(X)\) should contain a coupling between \(\hat{q}\) and \(X\). Heuristically, we take the following naive ME:
\[
\frac{d\hat{\rho}(X)}{dt} = -i\left[\hat{H}, \hat{\rho}(X)\right] - \frac{1}{2} \hat{q} \cdot \hat{q} - D\hat{\rho}(X).
\]
The coupling term yields the following relationship:
\[
\frac{dX}{dt} = \langle \hat{q} \rangle.
\]
So far so good: the statistics of \(X\) provide relevant and transparent information on the potential values of the position \(\hat{q}\). Our heuristic model seems to work.

There is a problem, however. The structure
\[
\hat{L} = \hat{q} / \sqrt{8D'} \hat{I} = \sqrt{2D'} \hat{q} \hat{I} \otimes \int \langle \partial_x X \rangle \langle X \rangle \, dX.
\]
Substitute this into (22), multiply both sides by \(\hat{I} \otimes \langle X \rangle \langle X \rangle\), and take partial trace on both sides. The result is a correct hybrid ME of position monitoring:
\[
\frac{d\hat{\rho}(X)}{dt} = -i\left[\hat{H}, \hat{\rho}(X)\right] - \frac{1}{2} \hat{q} \cdot \hat{q} \hat{\rho}(X) + D\hat{\rho}(X)
\]
Note the appearance of two additional diffusion terms on the
Ito stochastic differential equations for the conditional state of quantum monitoring [19], which prescribes two coupled the measured signal

Let’s integrate both sides over $X$. We find that the reduced quantum state $\hat{\rho}$ obeys the simple Lindblad ME (17) with $D' = 1/16D$. A more complex derivative of the hybrid ME of monitoring is the following non-autonomous Fokker-Planck equation for the reduced classical density:

$$\frac{dp(X)}{dt} = -\partial_x(q)\partial_x(X) + D\partial^2_x p(X),$$

where $\partial_x(q) = Tr(\hat{q}\hat{\rho}_X)$ is the conditional expectation value of $\hat{q}$. This equation expresses the diffusive noise superposed on the measured signal $X$ at diffusion coefficient $D$.

The hybrid ME (26) is equivalent to the standard theory of quantum monitoring [19], which prescribes two coupled Ito stochastic differential equations for the conditional state $\hat{\rho}_X$ and the measured signal $X$, respectively, instead of the hybrid ME for $\hat{\rho}(X)$. The proof of equivalence of the two Ito equations with the hybrid ME is straightforward and will be shown elsewhere.

7. Summary, outlook

We gave a short introduction into the concept of hybrid systems. We emphasized that quantum measurement has a natural hybrid formalism. We have proposed a novel general structure of hybrid ME to unify the Pauli and Lindblad structures. This approach demonstrates an application to quantum continuous measurement (monitoring).

Ad hoc hybrid theories often fall short. Certain ad hoc MEs violate the positivity of the hybrid density. This failure is abandoned by our class of hybrid MEs. Certain ad hoc hybrid theories don’t pass the ‘free will test’ [24]. The measurement-related theories, where the classical variable is the measured outcome, do pass it. Nonetheless, the consistency of hybrid theories is currently under discussion. There can be a number of further consistency tests [25].

The present work is a deliberate outline of certain important features of hybrid systems, with an emphasis on quantum measurement. Some novel results, including the general structure of hybrid ME and the hybrid ME of quantum monitoring, will be detailed and further clarified in forthcoming works [26].

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| Reduced Q | Reduced C | Conditional C | Conditional Q |
|-----------|-----------|---------------|---------------|
| $\hat{\rho} = \sum \hat{\rho}(x)$ | $\rho(x) = Tr \hat{\rho}(x)$ | $\hat{\rho}_c = \hat{\rho}(x)/\rho(x)$ | $\#.$ |