Existence, general decay and blow-up of solutions for a viscoelastic Kirchhoff equation with Balakrishnan-Taylor damping and dynamic boundary conditions

Gang Li, Biqing Zhu, Danhua Wang
College of Mathematics and Statistics, Nanjing University of Information Science and Technology, Nanjing 210044, China.
E-mail: brucechu@163.com.

Abstract
Our aim in this article is to study a nonlinear viscoelastic Kirchhoff equation with strong damping, Balakrishnan-Taylor damping, nonlinear source and dynamical boundary condition. Firstly, we prove the local existence of solutions by using the Faedo-Galerkin approximation method combined with a contraction mapping theorem. We then prove that if the initial data enter into the stable set, the solution globally exists, and if the initial data enter into the unstable set, the solution blows up in a finite time. Moreover, we obtain a general decay result of the energy, from which the usual exponential and polynomial decay rates are only special cases.

Keywords: Blow-up, stable and unstable set, global solutions, viscoelastic equation, strong damping, Balakrishnan-Taylor damping, dynamic boundary conditions.

AMS Subject Classification (2000): 35L05, 35B40.

1 Introduction
In this paper, we are concerned with the following problem:

\[
\begin{cases}
  u_{tt} - M(t) \Delta u + \int_0^t g(t-s) \Delta u(x,s)ds + \alpha u_t - \beta \Delta u_t = |u|^{p-2}u, & x \in \Omega, t > 0, \\
  u(x,t) = 0, & x \in \Gamma_0, t > 0, \\
  u_{tt}(x,t) = -M(t) \frac{\partial u}{\partial \nu}(x,t) + \int_0^t g(t-s) \frac{\partial u}{\partial \nu}(x,s)ds - \beta \frac{\partial u}{\partial \nu}(x,t) - \gamma |u_t|^{m-2}u_t(x,t), & x \in \Gamma_1, t > 0, \\
  u(x,0) = u_0(x), u_t(x,0) = u_1(x), & x \in \Omega,
\end{cases}
\]  

(1.1)

where \( M(t) = a + b \| \nabla u(t) \|_2^2 + \sigma \int_\Omega \nabla u(t) \nabla u_t(t) dx \), \( \Omega \) is a regular and bounded domain of \( \mathbb{R}^N \), \( N \geq 1 \), \( \partial \Omega = \Gamma_0 \cup \Gamma_1 \), \( mes(\Gamma_0) > 0 \), \( \Gamma_0 \cap \Gamma_1 = \emptyset \), \( \frac{\partial}{\partial \nu} \) denotes the unit outer normal derivative, \( m \geq 2, p > 2 \) and \( a, b, \sigma, \alpha, \beta, \gamma \) are positive constants. The relaxation function \( g \) is a positive and uniformly decaying function. The function \( u_0, u_1 \) are given initial data.

From the mathematical point of view, these problems like (1.1) take into account acceleration terms on the boundary. Such type of boundary conditions are usually called dynamic boundary conditions. They come from several physical applications and play an important role in different dimension space (see [3], [6], [10], [27] for more details).
From the theoretical point of view, such as in the one-dimensional case, many existence, uniqueness and decay results have been established (see [17], [18], [19], [20], [41], [42], [55] for more details). For example, in [19] the author considered the following problem

\[
\begin{aligned}
&u_{tt} - u_{xx} - u_{txx} = 0, \\
u(0,t) = 0, \\
u_t(L,t) = -[u_x + u_{tx}](L,t), \\
u(x,0) = u_0(x), u_t(x,0) = v_0(x), \\
u(L,0) = \eta, u_t(L,0) = \mu
\end{aligned}
\]

(1.2)

By using the theory of B-evolutions and theory of fractional powers, the author proved that problem (1.2) gives rise to an analytic semigroup in an appropriate functional space and obtained the existence and the uniqueness of solutions. For a problem related to (1.2), an exponential decay result was obtained in [18], which describes the weakly damped vibrations of an extensible beam. Later, Zang and Hu [55], considered the problem

\[
\begin{aligned}
&u_{tt} - p(u_x)_{xt} - q(u_x)_x = 0, \\
u(0,t) = 0, \\
(p(u_x)_t + q(u_x)(l,t) + ku_{tt}(l,t)) = 0, \\
u(x,0) = u_0(x), u_t(x,0) = u_1(x),
\end{aligned}
\]

(1.3)

By using the Nakao inequality, and under appropriate conditions on \( p \) and \( q \), they established both exponential and polynomial decay rates for the energy depending on the form of the terms \( p \) and \( q \). In [42] the authors considered the following linear wave equation with strong damping and dynamical boundary conditions

\[
\begin{aligned}
&u_{tt} - u_{xx} - \alpha u_{txx} = 0, \\
u(0,t) = 0, \\
u_{tt}(l,t) = -\epsilon[u_x + \alpha u_{tx} + ru_t](l,t),
\end{aligned}
\]

(1.3)

as an alternative model for the classical ODE, namely

\[
m_1 u''(t) + d_1 u'(t) + k_1(t) = 0.
\]

(1.4)

Based on the semigroup theory, spectral perturbation analysis and dominant eigenvalues, they compared analytically these two approaches to the same physical system. Later, Pellicer in [41] considered (1.3) with a control acceleration \( \epsilon f(u(l,t), u_t(l,t))/\sqrt{\epsilon} \) as a model for a controlled spring-mass-damper system and established some results concerning its large time behavior. By using the invariant manifold theory, the author proved that the infinite dimensional system admits a two dimensional invariant manifold where the equation is well represented by a classical nonlinear oscillations ODE (1.4), which can be exhibited explicitly.
In the multi-dimensional cases, we can cite (22, 26, 48) for problems with the Dirichlet boundary conditions and (45, 46, 47) for the Cauchy problems. Recently, Gerbi and Said-Houair in (23, 24) studied problem (1.1) with \( M = 1 \) and without the relaxation function \( g \), linear damping \( \alpha u_t \). They showed in [23] that if the initial data are large enough then the energy and the \( L^p \) norm of the solution of the problem is unbounded, grows up exponentially as time goes to infinity. Later in [24], they established the global existence and asymptotic stability of solutions starting in a stable set by combining the potential well method and the energy method. A blow-up result for the case \( m = 2 \) with initial data in the unstable set was also obtained. For the other works, we refer the readers to (6, 27, 28, 43, 50, 52) and the references therein.

Many authors have investigated the existence, decay and blow-up results for nonlinear viscoelastic wave equation with boundary dissipation (see [31], [33], [35], [36]). For example, Cavalcanti et al [15] considered the following equation

\[
\begin{align*}
  u_{tt} - \Delta u + \int_0^t g(t - \tau) \Delta u(\tau) d\tau + a(x)u_t + |u|^\gamma u = 0, \\
  (x, t) \in \Omega \times (0, \infty)
\end{align*}
\]

where \( \Omega \) is a bounded domain of \( \mathbb{R}^n (n \geq 1) \) with smooth boundary \( \partial \Omega \), \( r > 0 \) and \( a : \Omega \rightarrow \mathbb{R}_+ \) is a bounded function, which may vanish on a part of the domain. \( g \) is a positive nonincreasing function defined on \( \mathbb{R}_+ \). Under the condition that \( a(x) \geq a_0 > 0 \) on \( \omega \subset \Omega \), with \( \omega \) satisfying some geometry restrictions, when \(-\xi_1 g(t) \leq g'(t) \leq -\xi_2 g(t)\), \( t \geq 0 \), for some positive constants \( \xi_1 \) and \( \xi_2 \), they proved an exponential rate of decay. Later, S. Berrimi and S. A. Messaoudi [7] improved Cavalcanti’s result by introducing a different functional, which allowed to weaken the conditions on both \( a \) and \( g \). Recently, in [25], Gerbi and Said-Houair studied problem (1.1) with \( M = 1 \), without the linear damping \( \alpha u_t \) and got the existence, exponential growth results. Jeong et al [29] concerned the following problem and proved the general energy decay for nonlinear viscoelastic wave equation with boundary damping.

\[
\begin{align*}
  u'' - \Delta u - \alpha \Delta u' + \int_0^t h(t - \tau) \text{div}[a(x)\nabla u(\tau)] d\tau = 0, & \quad \text{in } \Omega \times (0, \infty), \\
  u = 0, & \quad \text{on } \Gamma_0 \times (0, \infty), \\
  u'' + \frac{\partial u}{\partial \nu} + \alpha \frac{\partial u'}{\partial \nu} - \int_0^t h(t - \tau)[a(x)\nabla u(\tau)] \cdot \nu d\tau + |u'|^{m-2}u' = |u|^{p-2}u, & \quad \text{on } \Gamma_1 \times (0, \infty), \\
  u'(x, 0) = u_1(x), u(x, 0) = u_0(x), & \quad \text{in } \Omega.
\end{align*}
\]

When \( M(t) = a + b\|\nabla u(t)\|^2 + \sigma \int_\Omega \nabla u(t) \nabla u(t) dx \), with Balakrishnan-Taylor damping \( (\sigma = 0) \), equation (1.1) describes the motion of a deformable solid with a hereditary effect. The more details about the stability and the well-posedness of the system, we refer the readers to (2, 13, 14, 40). On the contrary, with Balakrishnan-Taylor damping \( (\sigma \neq 0) \) and \( g = 0 \), was initially proposed by Balakrishnan and Taylor in 1989 [4] and Bass and Zes [5]. It is used
to solve the spillover problem. The related problems also concerned by Tatar and Zarai in (43, 53, 54), Mu in 39 and Wu in 51.

Motivated by the above works, we intend to study the local existence, global existence, general decay and blow-up of solutions to problem (1.1). The main difficulties we encounter here arise from the simultaneous appearance of the viscoelastic term, the strong damping term, the Balakrishnan-Taylor damping, the nonlinear source term and the nonlinear boundary damping term. We will show that if the initial data is in the stable set, the solution is global. Otherwise, if the initial data is in the unstable set, by the concavity technique, we get the solution will blow up in a finite time (we can see 34 for more details). Then, for the relaxation function \( g \) satisfies (G2), by introducing suitable energy and Lyapunov functionals, we find that the energy decays at the same rate of \( g \), which are not necessarily decaying like polynomial or exponential functions.

The paper is organized as follows. In Section 2, we present some notations and material needed for our work. In Section 3, we establish the local existence. In section 4, the global existence for solutions is given. In Section 5, we prove the general decay result. A finite time blows-up result for initial data in the unstable set is given in Section 6.

2 Preliminaries

In this section we present some material needed in the proof of our result. For the relaxation function \( g \), we assume

\[(G1) \quad g : \mathbb{R}_+ \rightarrow \mathbb{R}_+ \text{ is a nonincreasing differentiable function satisfying} \\
g(0) > 0, \quad a - \int_0^\infty g(s)ds = l > 0.
\]

\[(G2) \text{ There exists a nonincreasing differentiable function } \xi : \mathbb{R}_+ \rightarrow \mathbb{R}_+ \text{ such that} \\
g'(s) \leq -\xi(s)g(s), \quad \forall s \in \mathbb{R}_+.
\]

We introduce the set \( H^1_{\Gamma_0} \) = \{ \( u \in H^1(\Omega) \) | \( u_{|\Gamma_0} = 0 \) \}, \( V = H^1_{\Gamma_0}(\Omega) \cap L^m(\Gamma_1) \). By \((\cdot, \cdot)\) we denote the scalar product in \( L^2(\Omega) \); i.e.,

\[(u, v)(t) = \int_\Omega u(x,t)v(x,t)dx.
\]

Also, by \( \| \cdot \|_q \) we mean the \( L^q(\Omega) \) norm for \( 1 \leq q \leq \infty \), by \( \| \cdot \|_{q,\Gamma_1} \) the \( L^q(\Gamma_1) \) norm. We will also use the embedding (see [1]): \( H^1_{\Gamma_0} \hookrightarrow L^q(\Gamma_1), \quad 2 \leq q \leq \overline{q} \), where \( \overline{q} \) satisfies

\[
\overline{q} = \begin{cases} 
\frac{2(N-1)}{N-2} > 1, & \text{if } N \geq 3, \\
+\infty, & \text{if } N = 1, 2.
\end{cases}
\]

We introduce the following functionals as in (8, 37, 38)

\[
I(t) := I(u(t)) = \left( a - \int_0^t g(s)ds \right) \| \nabla u(t) \|_2^2 + (g \circ \nabla u)(t) - \| u(t) \|_p^p + \frac{b}{2} \| \nabla u(t) \|_2^4,
\]  
\[
(2.1)
\]
\[
J(t) := J(u(t)) = \frac{1}{2} \left[ (a - \int_0^t g(s)ds) \|\nabla u(t)\|_2^2 + \frac{b}{2} \|\nabla u(t)\|_2^4 + (g \circ \nabla u)(t) \right] - \frac{1}{p} \|u(t)\|_p^p, \quad (2.2)
\]

\[
E(t) := E(u(t), u_t(t)) = J(t) + \frac{1}{2} \|u_t(t)\|_2^2 + \frac{1}{2} \|u_t(t)\|_{2, \Gamma_1}^2, \quad (2.3)
\]

where

\[
(g \circ \nabla u)(t) = \int_0^t g(t - s)\|\nabla u(t) - \nabla u(s)\|_2^2 ds \geq 0.
\]

We define the potential well depth as

\[
d(t) = \inf_{u \in H^1_{\Gamma_0}(\Omega) \setminus \{0\}} \sup_{\lambda \geq 0} J(\lambda u). \quad (2.4)
\]

### 3 Local existence result

In this section we will prove the local existence and the uniqueness of the solution of problem \((1.1)\). The process is closely related to \((23)\), Theorem 2.1) that Gerbi and Said-Houair have proved, where no memory term and Balakrishnan-Taylor damping were present.

**Theorem 3.1** Assume (G1) and (G2) hold, \(2 \leq p \leq \bar{p}\) and \(\max \left\{2, \frac{p}{p+1} \right\} \leq m \leq \bar{p}\). Then given \(u_0 \in H^1_{\Gamma_0}(\Omega)\) and \(u_1 \in L^2(\Omega)\), there exist \(T > 0\) and a unique solution \(u\) of problem \((1.1)\) on \((0, T)\) such that

\[
\begin{align*}
    u &\in C \left([0, T], H^1_{\Gamma_0}(\Omega)\right) \cap C^1 \left([0, T], L^2(\Omega)\right), \\
u_t &\in L^2 \left(0, T; H^1_{\Gamma_0}(\Omega)\right) \cap L^m \left((0, T) \times \Gamma_1\right)
\end{align*}
\]

By using the Fadeo-Galerkin approximations and the well-known contraction mapping theorem we can prove this theorem. In order to define the function for which a fixed point exists, for \(u \in C \left([0, T], H^1_{\Gamma_0}(\Omega)\right) \cap C^1 \left([0, T], L^2(\Omega)\right)\), we consider the following problem

\[
\begin{cases}
v_{tt} - N(t) \Delta v + \int_0^t g(t - s)\Delta v(x, s)ds + \alpha v_t - \beta \Delta v_t = |u|^{p-2}u, & x \in \Omega, t > 0, \\
v(x, t) = 0, & x \in \Gamma_0, t > 0, \\
v_t(x, t) = -N(t) \frac{\partial v}{\partial n}(x, t) + \int_0^t g(t - s)\frac{\partial v}{\partial n}(x, s)ds - \beta \frac{\partial v}{\partial n}(x, t) \\
-\gamma |v_t|^{m-2}v_t(x, t), & x \in \Gamma_1, t > 0, \\
v(x, 0) = u_0(x), v_t(x, 0) = u_1(x), & x \in \Omega,
\end{cases} \quad (3.1)
\]

where \(N(t) = a + b\|\nabla v(t)\|_2^2 + \sigma \int_{\Omega} \nabla v(t) \nabla v_t(t)dx\).

**Definition 3.2** A function \(v(x, t)\) such that

\[
v \in L^\infty \left(0, T; H^1_{\Gamma_0}(\Omega)\right),
\]

\[
v \in L^\infty \left(0, T; H^1_{\Gamma_0}(\Omega)\right),
\]

5
\[ v_t \in L^2 \left( 0, T; H^1_0(\Omega) \right) \cap L^m \left( (0, T) \times \Gamma_1 \right), \]
\[ v_t \in L^\infty \left( 0, T; H^1_0(\Omega) \right) \cap L^\infty \left( (0, T) \times L^2(\Gamma_1) \right), \]
\[ v_{tt} \in L^\infty \left( 0, T; L^2(\Omega) \right) \cap L^\infty \left( (0, T) \times L^2(\Gamma_1) \right), \]
\[ v(x, 0) = u_0(x), \quad v_t(x, 0) = u_1(x), \]

is a generalized solution to problem (3.1) if for any function \( \omega \in H^1_0(\Omega) \cap L^m(\Gamma_1) \) and \( \varphi \in C^1(0, T) \) with \( \varphi(T) = 0 \), we get
\[
\int_0^T (|u|^{p-2}u, w)(t)\varphi(t)dt = \int_0^T \left[ (v_{tt}, \omega)(t) + a(\nabla v, \nabla \omega)(t) + b \int_{\Omega} \|\nabla v(t)\|^2 \Delta v(t)\omega(t)dx \right. \\
+ \frac{\sigma}{2} \int_{\Omega} \frac{d}{dt}\|\nabla v(t)\|^2 \Delta v(t)\omega(t)dx + \alpha(v_t, \omega)(t) + \beta(\nabla v_t, \nabla \omega)(t) \\
- \int_0^t g(t - s)\nabla v(s) \cdot \nabla \omega(t)ds \big] \varphi(t)dt \\
+ \int_0^T \varphi(t) \int_{\Gamma_1} \left[ v_{tt}(t) + \gamma|v_t(t)|^{m-2}v_t(t) \right] \omega d\sigma dt.
\]

**Lemma 3.3** Assume (G1), (G2), \( 2 \leq p \leq q \) and \( 2 \leq m \leq q \) hold. Let \( u_0 \in H^2(\Omega) \cap V \), \( u_1 \in H^2(\Omega) \) and \( f \in H^1(0, T; L^2(\Omega)) \), then for any \( T > 0 \), there exists a unique generalized solution \( v(t, x) \) of problem (3.1).

**Proof.** We use Faedo-Galerkin method, some difficulties appear deriving a second-order estimate of \( v_{tt}(0) \), inspired by the ideas of Doronin and Larkin in [20] and Cavalcanti et al [11], we set \( \tilde{v} = v(t, x) - \psi(t, x) \) with \( \psi(t, x) = u_0(x) + tu_1(x) \). Therefore, we have
\[
\begin{cases}
\tilde{v}_{tt} - \tilde{N}(t)\Delta \tilde{v} + \int_0^t g(t - s)\Delta \tilde{v}(x, s)ds + \alpha\tilde{v}_t - \beta\Delta \tilde{v}_t = f(x, t) \\
\quad + \tilde{N}(t)\Delta \psi - \int_0^t g(t - s)\Delta \psi(s)ds - \alpha\psi_t + \beta\Delta \psi_t, \quad x \in \Omega, t > 0, \\
\tilde{v}(x, t) = 0, \quad x \in \Gamma_0, t > 0, \\
\tilde{v}_{tt}(x, t) = -\tilde{N}(t)\frac{\partial(\tilde{v} + \psi)}{\partial \nu}(x, t) + \int_0^t g(t - s)\frac{\partial(\tilde{v} + \psi)}{\partial \nu}(x, s)ds \\
\quad - \beta\frac{\partial(\tilde{v}_t + \psi_t)}{\partial \nu}(x, t) - \gamma|\tilde{v}_t + \psi_t|^{m-2}(\tilde{v}_t + \psi_t)(x, t), \quad x \in \Gamma_1, t > 0, \\
\tilde{v}(x, 0) = 0, \quad \tilde{v}_t(x, 0) = 0, \quad x \in \Omega,
\end{cases}
\]
where \( \tilde{N}(t) = a + b\|\nabla (\tilde{v} + \psi)\|^2 + \frac{\sigma}{2} \frac{d}{dt}\|\nabla (\tilde{v} + \psi)\|^2 \). We obtain that if \( \tilde{v} \) is a solution of problem (3.2) on \([0, T]\), then \( v \) is a solution of problem (3.1) on \([0, T]\). By using the Faedo-Galerkin method, for every \( h \geq 1 \), let \( W_h = \text{Span}\{\omega_1, \cdots, \omega_h\} \), where \( \{\omega_j\} \) is the orthogonal complete system of eigenfunctions of \( -\Delta \) in the space \( V \) such that \( \|w_j\|_2 = 1 \) for all \( j \). Then \( \{\omega_j\} \) is orthogonal and complete in \( L^2(\Omega) \cap L^2(\Gamma_1). \) Let
\[
\tilde{v}_h(t) = \sum_{j=1}^{n} \vartheta_{jh}(t)\omega_j,
\]
where \( \tilde{v}_h(t) \) are solutions to the finite-dimensional Cauchy problem, we have

\[
\int_\Omega \tilde{v}_{th}(t) \omega_j dx + \tilde{N}(t) \int_\Omega \nabla(\tilde{v}_h + \psi) \cdot \nabla \omega_j dx + \alpha \int_\Omega (\tilde{v}_h + \psi) t \omega_j dx \\
+ \beta \int_\Omega \nabla(\tilde{v}_h + \psi) t \cdot \nabla \omega_j dx - \int_0^t g(t-s) \int_\Omega \nabla(\tilde{v}_h + \psi) \cdot \nabla \omega_j dx \\
+ \int_{\Gamma_1} (\tilde{v}_{th} + \gamma)(\tilde{v}_h + \psi) t |^{m-2}(\tilde{v}_h + \psi) t \omega_j d\sigma \\
= \int_\Omega f \omega_j dx, \tag{3.4}
\]

According to [16], by the Caratheodory theorem, problem (3.4) has a unique solution \((\vartheta_{jh}(t)) \in H^3(0, t_h)\) defined on \([0, t_h]\). To do this, we need two priori estimates to show that for all \(h \in N\), \(t_h = T\) and those approximations converge to a solution of problem (3.2), for the proof of the estimates can be done as in [23], Lemma 2.2, we omit the details. Then, by using Aubin-Lions compactness lemma, the proof can be completed arguing as in [32]. The uniqueness of this solution follows from the energy inequality, we omit here. This finishes the proof of Lemma 3.3.

Next, we show the following existence result.

**Lemma 3.4** Assume (G1), (G2), 2 \(\leq p \leq 7\) and \(\max \left\{ 2, \frac{7}{p-1} \right\} \leq m \leq 7\) hold. Then given \(u_0 \in H_{\Gamma_0}^1(\Omega)\) and \(u_1 \in L^2(\Omega)\), there exist \(T > 0\) and a unique solution \(v\) of problem (3.1) on \((0, T)\) such that

\[
v \in C \left( [0, T], H_{\Gamma_0}^1(\Omega) \right) \cap C^1 \left( [0, T], L^2(\Omega) \right),
\]

\[
v_t \in L^2(0, T; H_{\Gamma_0}^1(\Omega)) \cap L^m \left( (0, T) \times \Gamma_1 \right)
\]

and satisfies the energy identity

\[
\frac{1}{2} \left[ \left( a - \int_0^{\tau} g(z) dz \right) \| \nabla v \|_2^2 + \frac{b}{2} \| \nabla v \|_2^2 + \| v_t \|_2^2 + \| v_t \|_{2, \Gamma_1}^2 + (g \circ \nabla v)(\tau) \right]_t^s + \alpha \int_s^t \| v_t(\tau) \|_2^2 d\tau \\
+ \frac{\sigma}{4} \int_s^t \left( \frac{d\| \nabla v(z) \|}{dz} \right)^2 dz + \beta \int_s^t \| \nabla v_t(\tau) \|_2^2 ds + \gamma \int_s^t \| v_t(\tau) \|_{m, \Gamma_1}^m d\tau - \frac{1}{2} \int_s^t (g' \circ \nabla v)(\tau) d\tau \\
+ \frac{1}{2} \int_s^t g(\tau) \| \nabla v(\tau) \|_2^2 d\tau \\
= \int_s^t \int_{\Omega} |u(\tau)|^{p-2} u(\tau) v_t(\tau) d\tau dx \tag{3.5}
\]

for \(0 \leq s \leq t \leq T\).

**Proof.** First, by a sequence \((u')_{i \in N} \subset C^\infty(0, T) \times \Omega\) by standard convolution arguments (see [22]), we approximate \(u \in C \left( [0, T], H_{\Gamma_0}^1(\Omega) \right) \cap C^1 \left( [0, T], L^2(\Omega) \right)\) endowed with the standard norm

\[
\| u \| = \max_{t \in [0, T]} \left( \| u_t(t) \|_2 + \| u(t) \|_{H^1(\Omega)} \right).
\]
We obtain \( f(u') = |u'|^{p-2}u' \in H^1(0,T;L^2(\Omega)) \). Next, we approximate the initial data \( u_1 \in L^2(\Omega) \) by a sequence \( \{u_1^i\} \in C^\infty_0(\Omega) \). At last, because the space \( H^2(\Omega) \cap V \cap H^1_{\Gamma_0}(\Omega) \) is dense in \( H^1_{\Gamma_0}(\Omega) \) for the \( H^1 \) norm, we approximate \( u_0 \in H^1_{\Gamma_0}(\Omega) \) by a sequence \( \{u_0^i\} \subset H^2(\Omega) \cap V \cap H^1_{\Gamma_0}(\Omega) \).

We now consider the following problem

\[
\begin{aligned}
&v_{tt}^i - N^i(t)\Delta v^i + \int_0^t g(t-s)\Delta v^i(x,s)ds + \alpha v_t^i - \beta \Delta v_t^i = |u'|^{p-2}u', \quad x \in \Omega, t > 0, \\
v^i(x,t) = 0, \quad x \in \Gamma_0, t > 0, \\
v_{tt}^i(x,t) = -N^i(t)\frac{\partial v^i}{\partial \nu}(x,t) + \int_0^t g(t-s)\frac{\partial v^i}{\partial \nu}(x,s)ds - \beta \frac{\partial v_t^i}{\partial \nu}(x,t) \\
-\gamma |v_t^i|^{m-2}v_t^i(x,t), \quad x \in \Gamma_1, t > 0, \\
v^i(x,0) = u_0^i(x), v_t^i(x,0) = u_1^i(x), \quad x \in \Omega, 
\end{aligned}
\]

(3.6)

where \( N^i(t) = a + b\|\nabla v^i(t)\|_2^2 + \sigma \int_\Omega \nabla v^i(t)\nabla v_t^i(t)dx \). As every hypothesis of Lemma [3.3] is satisfied, we can find a sequence of unique solutions \( \{v_k\} \) of problem (3.6). Next, we shall prove that \( \{v^i, v_t^i\} \) is a Cauchy sequence in the space

\[
Y_T = \{(v,v_t) : v \in C([0,T], H^1_{\Gamma_0}(\Omega)) \cap C^1([0,T], L^2(\Omega)), v_t \in L^2(0,T; H^1_{\Gamma_0}(\Omega)) \cap L^m((0,T) \times \Gamma_1)\}
\]

endowed with the norm

\[
\|(v,v_t)\|_{Y_T} = \max_{t \in [0,T]} \left[ \|v_t\|_2^2 + \|\nabla v\|_2^2 \right] + \|v_t\|_2^2 + \|\nabla v_t\|_{L^m((0,T) \times \Gamma_1)}^2 + \int_0^t \|\nabla v_t(s)\|_2^2 ds.
\]

To achieve this, we set \( U = u^i - u^j \), \( V = v^i - v^j \). It’s easy to see that \( V \) satisfies

\[
\begin{aligned}
&V_{tt} - N_1(t)\Delta V + \int_0^t g(t-s)\Delta V(x,s)ds \\
&+ \alpha V_t - \beta \Delta V_t = |u^i|^{p-2}u^i - |u^j|^{p-2}u^j, \quad x \in \Omega, t > 0, \\
V(x,t) = 0, \quad x \in \Gamma_0, t > 0, \\
V_{tt}(x,t) = -N_1(t)\frac{\partial V}{\partial \nu}(x,t) + \int_0^t g(t-s)\frac{\partial V}{\partial \nu}(x,s)ds - \beta \frac{\partial V_t}{\partial \nu}(x,t) \\
-\gamma \left( |v_t^i|^{m-2}v_t^i(x,t) - |v_t^j|^{m-2}v_t^j(x,t) \right), \quad x \in \Gamma_1, t > 0, \\
V(x,0) = u_0 - u_0^j, V_t(x,0) = u_1^i(x) - u_1^j, \quad x \in \Omega,
\end{aligned}
\]

where \( N_1(t) = a + b\|\nabla V(t)\|_2^2 + \sigma \int_\Omega \nabla V(t)\nabla V_t(t)dx \). By multiplying the above differential equation by \( V_t \) and integrating over \( \Omega \times (0,t) \), we arrive at

\[
\frac{1}{2} \left[ \left( a - \int_0^t g(s)ds \right) \|\nabla V(t)\|_2^2 + \frac{b}{2} \|\nabla V(t)\|_2^4 + \|V_t(t)\|_2^4 + \|V_t(t)\|_{2,\Gamma_1}^4 \right] + \alpha \int_0^t \|V_t(s)\|_2^2 ds
\]
\[ + \beta \int_0^t \|\nabla V(t)\|^2_s ds - \int_0^t (g' \circ \nabla V)(s) ds + (g \circ \nabla V)(t) + \int_0^t \int_\Omega g(s) \nabla V(s)^2 dxds \]

\[ + \frac{\sigma}{4} \|\nabla V(t)\|^2_s + \gamma \int_0^t \int_{\Gamma_1} \left( |v'_t|^m - 2v_t' - |v_t'|^m - 2v_t' \right) (v_t' - v_t) d\sigma ds \]

\[ = \frac{1}{2} \left[ (a - \int_0^t g(s) ds) \|\nabla V(0)\|^2_s + \frac{b}{2} \|\nabla V(0)\|^2_s + \|V_t(0)\|^2_s + \|V_t(0)\|^2_{2, \Gamma_1} \right] \]

By the algebraic inequality

\[ \forall m \geq 2, \quad \exists c > 0, \quad \forall a, b \in \mathbb{R}, \quad (|a|^{m-2} - |b|^{m-2}) (a - b) \geq c|a - b|^m, \quad (3.7) \]

we get

\[ \frac{1}{2} \left[ (a - \int_0^t g(s) ds) \|\nabla V(t)\|^2_s + \frac{b}{2} \|\nabla V(t)\|^2_s + \|V_t(t)\|^2_s + \|V_t(0)\|^2_{2, \Gamma_1} \right] \]

\[ + c_1 \|V_t\|^m_{m, \Gamma_1} + \frac{\sigma}{4} \|\nabla V(t)\|^2_s \]

\[ + \beta \int_0^t \|\nabla V_t(s)\|^2_s ds - \int_0^t (g' \circ \nabla V)(s) ds + (g \circ \nabla V)(t) \]

\[ + \int_0^t \int_\Omega g(s) \nabla V(s)^2 dxds \]

\[ \leq \frac{1}{2} \left[ (a - \int_0^t g(s) ds) \|\nabla V(0)\|^2_s + \frac{b}{2} \|\nabla V(0)\|^2_s + \|V_t(0)\|^2_s + \|V_t(0)\|^2_{2, \Gamma_1} \right] \]

\[ + \int_0^t \int_{\Omega} \left( |u'|^{p-2} - |u'|^{p-2} \right) (v_t' - v_t) d\sigma ds, \quad \forall t \in (0, T). \]

Then, by using Young’s inequality, Gronwall inequality and the result of Georgiev and Todorova [26], there exists a constant $C$ depending only on $\Omega$ and $p$ such that

\[ \|V\|_{Y_T} \leq C \left( \|\nabla V(0)\|^2_s + \|V_t(0)\|^2_s + \|V_t(0)\|^2_{2, \Gamma_1} \right) + CT\|U\|_{Y_T}. \]

By the above notation, we can obtain $V(0) = u'_0 - u'_0$, $V_t(0) = u'_1 - u'_1$. Thus, we conclude that \{(v_t', v_t')\} is a Cauchy sequence in $Y_T$, because \{(u'_0)\} is a converging sequence in $H^1_\Gamma_0(\Omega)$, \{u'_1\} is a converging sequence in $L^2(\Omega)$ and \{u'_t\} is a converging sequence in $C([0, T], H^1_\Gamma_0(\Omega)) \cap C^1([0, T], L^2(\Omega))$. So, we conclude that \{(v_t', v_t')\} converges to a limit $(v, v_t) \in Y_T$. As done by [26], we can prove that this limit is a weak solution of problem (3.1). This completes the proof of Lemma 3.4.

Now we are ready to prove the local existence result.

**Proof of Theorem 3.1** For $R > 0$ large and $T > 0$, we define the convex closed subset of $Y_T$, we define a class of functions as

\[ X_T = \{(v, v_t) \in Y_T : v(0) = u_0, v_t(0) = u_1 \text{ and } \|v\|_{Y_T} \leq R\}. \]

Then, Lemma 3.4 implies that, for any $u \in X_T$, we may define $v = \Phi(u)$ to be a unique solution of (3.1) corresponding to $u$. We would like to show that $\Phi$ is a contraction map
satisfying $\Phi(X_T) \subset X_T$ for a suitable $T > 0$. Firstly, we show $\Phi(X_T) \subset X_T$. For this, by using the energy identity, we have

\[ l\|\nabla v(t)\|_2^2 + \|v_t(t)\|_2^2 + \|v_t(t)\|_{2,\Gamma}^2 + 2\alpha \int_0^t \|v_t(s)\|_2^2 ds + 2\beta \int_0^t \|\nabla v_t(s)\|_2^2 ds + 2\gamma \int_0^t \|v_t(s)\|_m^{m_1} \Gamma_1 ds \]

\[ \leq \|\nabla u_0\|_2^2 + \|u_1\|_2^2 + \|u_1\|_{2,\Gamma}^2 + 2 \int_0^t \int_\Omega |u(s)|^{p-2} u_t(s)v_t(s) dx ds. \]  

(3.8)

By the Holder’s inequality, we estimate the last term in the right-hand side of the inequality (3.8) as follows

\[ \int_0^t \int_\Omega |u(s)|^{p-2} u_t(s)v_t(s) dx ds \]

\[ \leq \int_0^t \|u(s)\|_{2N/(N-2)}^{p-1} \|v_t(s)\|_{2N/(3N-Np+2(p-1))} 2N/(3N-Np+2(p-1)) dx ds. \]

As $p \leq \frac{2N}{N-2}$, we get

\[ \frac{2N}{(3N-Np+2(p-1))} \leq \frac{2N}{N-2}. \]

Thus, by Young’s and Sobolev’s inequalities, for all $\delta > 0, t \in (0, T)$, there exists a positive constant $C(\delta)$ such that

\[ \int_0^t \int_\Omega |u(s)|^{p-2} u_t(s)v_t(s) dx ds \leq C(\delta) t R^{2(p-1)} + \delta \int_0^t \|\nabla v_t(s)\|_2^2 ds. \]

Inserting the last estimate in the inequality (3.8) and choosing $\delta$ small enough, we have

\[ \|v\|_{Y_T}^2 \leq \frac{1}{2} R^2 + CTR^{2(p-1)}. \]

Then, choose $T$ small enough, we get $\|v\|_{Y_T} \leq R$, which shows that $\Phi$ maps $X_T$ into itself.

Next, we verify that $\Phi$ is a contraction. To this end, we set $U = u - \overline{u}$ and $V = v - \overline{v}$, where $v = \Phi(u)$ and $\overline{v} = \Phi(\overline{u})$. It’s straightforward to verify that $V$ satisfies

\[
\begin{cases}
V_{tt} - N_2(t) \Delta V + \int_0^t g(t-s) \Delta V(x,s) ds \\
\quad + \alpha V_t - \beta \Delta V_t = |u|^{p-2} u - |\overline{u}|^{p-2} \overline{u}, & x \in \Omega, t > 0, \\
V(x,t) = 0, & x \in \Gamma_0, t > 0, \\
V_t(x,t) = -N_2(t) \frac{\partial V}{\partial \nu}(x,t) + \int_0^t g(t-s) \frac{\partial V}{\partial \nu}(x,s) ds - \beta \frac{\partial V_t}{\partial \nu}(x,t) \\
\quad - \gamma \left( |v_t|^{m-2} v_t(x,t) - |\overline{v}_t|^{m-2} \overline{v}_t(x,t) \right), & x \in \Gamma_1, t > 0, \\
V(x,0) = 0, V_t(x,0) = 0, & x \in \Omega,
\end{cases}
\]

(3.9)
where \( N_2(t) = a + b\|\nabla V(t)\|^2 + \sigma \int_{\Omega} \nabla V(t) \nabla \psi(t) dx \). By multiplying the differential equation in \((3.9)\) by \( V_t \) and integrating over \( \Omega \times (0, t) \), we arrive at

\[
\frac{1}{2} \left[ a - \int_0^t g(s) ds \right] \| \nabla V(t) \|^2 + \frac{b}{2} \| \nabla V(t) \|^4 + \| V_t(t) \|^2 + \| V(t) \|_{2, \Gamma}^2 \right] + \alpha \int_0^t \| V(s) \|^2 ds
\]

\[
+ \beta \int_0^t \| \nabla V(s) \|^2 ds - \frac{1}{2} \int_0^t (g' \circ \nabla V)(s) ds + \frac{1}{2} (g \circ \nabla V)(t) + \frac{1}{2} \int_0^t \int_\Omega g(s) \nabla V(s)^2 dx ds
\]

\[
+ \frac{\sigma}{4} \| \nabla V(t) \|^2 + \gamma \int_0^t \int_{\Gamma_1} (|v_t|^{-2} v_t - |\nabla|^{-2} v_t) (v_t - \nabla_t) d\sigma ds
\]

\[
= \int_0^t \int_{\Omega} (|u|^{p-2} u - |\nabla|^{p-2} u) (v_t - \nabla_t) dx ds, \quad \forall t \in (0, T). 
\]

Similar to the discussion in \([23]\), we can get

\[
\| V \|^2_T \leq CR^{p-2} T^{1/2} \| U \|^2_T. \tag{3.10}
\]

By choosing \( T \) so small that \( CR^{p-2} T^{1/2} < 1 \), estimate \((3.10)\) shows that \( \Phi \) is a contraction. The contraction mapping theorem then guarantees the existence of a unique \( v \) satisfying \( v = \Phi(v) \). The proof of Theorem \( 3.1 \) is now completed.

### 4 Global existence

In this section, for the initial data in the stable set, we show the solution is global. We need the following definition and lemmas.

**Definition 4.1** Let \( 2 \leq p \leq \overline{q} \) and \( \max \left\{ 2, \frac{\overline{q}}{\overline{q}+1-p} \right\} \leq m \leq \overline{q} \). We denote \( u \) as the solution of \((1.1)\). We define

\[
T_{\max} = \sup \{ T > 0, u = u(t) \text{ exists on } [0, T] \}.
\]

**Lemma 4.2** Suppose that (G1), (G2), \( 2 \leq p \leq \overline{q} \) and \( \max \left\{ 2, \frac{\overline{q}}{\overline{q}+1-p} \right\} \leq m \leq \overline{q} \) hold. If \( u \) is the solution of \((1.1)\), then

\[
\begin{aligned}
E'(t) &= \frac{1}{2} (g' \circ \nabla u)(t) - \frac{1}{2} g(t) \| \nabla u(t) \|^2 - \sigma \left( \frac{1}{2} \| \nabla u(t) \|^2 \right)^2 - \alpha \| u_t(t) \|^2 \\
&\quad - \beta \| \nabla u_t(t) \|^2 - \gamma \| u_t(t) \|_{m, \Gamma}^m \leq 0,
\end{aligned}
\tag{4.1}
\]

for almost every \( t \in [0, T_{\max}] \).

**Proof.** In view of (G1), multiplying the differential equation in \((1.1)\) by \( u_t \) and integrating by parts over \( \Omega \), we obtain the result.

**Lemma 4.3** Let \((u_0, u_1) \in H^1_{\Gamma_0} \times L^2(\Omega)\) be given, suppose that (G1) and \( 2 \leq p \leq \overline{q} \) hold, such that

\[
\left\{ \begin{array}{l}
\frac{C_p}{I} \left( \frac{2p}{l(p-2)} E(0) \right)^{\frac{p-2}{2}} < 1, \\
I(u_0) > 0,
\end{array} \right. \tag{4.2}
\]

11
where $C_*$ is the best Poincare constant, then $I(u(t)) > 0$, $\forall t \in [0, T_{\text{max}}]$.

**Proof.** Since $I(0) > 0$, there exists a $T_* < T_{\text{max}}$ such that $I(t) > 0$ for all $t \in [0, T_*]$. This implies that

$$J(t) = \frac{p-2}{2p} \left[ \left( a - \int_0^t g(s) ds \right) \| \nabla u(t) \|^2 + (g \circ \nabla u)(t) + \frac{b}{2} \| \nabla u(t) \|^2 \right] + \frac{1}{p} I(t)$$

$$\geq \frac{p-2}{2p} \left( a - \int_0^t g(s) ds \right) \| \nabla u(t) \|^2 + \frac{b}{2} \| \nabla u(t) \|^2 .$$

(4.3)

Thus, by (G1), (2.1), (4.1), and (4.3), we have

$$l \| \nabla u \|^2 \leq \left( a - \int_0^t g(s) ds \right) \| \nabla u(t) \|^2 \leq \frac{2p}{p-2} J(t) \leq \frac{2p}{p-2} E(t) \leq \frac{2p}{p-2} E(0) ,$$

(4.4)

for all $t \in [0, T_*)$. This combines with the Sobolev imbedding, (G1) and (4.2), implies that

$$\| u \|^p \leq C^p \| \nabla u \|^p \leq C^p \| \nabla u \|^p \leq \frac{C^p}{l} \| \nabla u \|^p \leq \left( a - \int_0^t g(s) ds \right) \| \nabla u \|^2 ,$$

for all $t \in [0, T_*)$. Therefore, $I(t) > 0$, for all $t \in [0, T_*)$. By repeating this procedure and using the fact that

$$\lim_{t \to T_*} \frac{C^p}{l} \left( \frac{2p}{l(p-2)} E(0) \right) \leq 1 ,$$

where $T_*$ is extended to $T_{\text{max}}$.

**Theorem 4.4** Let $(u_0, u_1) \in H_{0,0}^1 \times L^2(\Omega)$ be given and satisfying (1.2), suppose that (G1), (G2), $2 \leq p \leq q$ and max $\left\{ 2, \frac{q}{q+1}\right\} \leq m \leq q$ hold. Then the solution is global and bounded.

**Proof.** We have just to check that

$$\| \nabla u(t) \|^2 + \| u_t(t) \|^2$$

is bounded and independently of $t$. To achieve this, by (2.1), (4.1) and (4.3), we have

$$E(0) \geq E(t) = J(t) + \frac{1}{2} \| u_t(t) \|^2 + \frac{1}{2} \| u_t(t) \|^2 _{2, \Gamma} + I(t)$$

$$\geq \frac{p-2}{2p} \left[ l \| \nabla u(x,t) \|^2 + (g \circ \nabla u)(x,t) + \frac{b}{2} \| \nabla u(t) \|^2 \right] + \frac{1}{2} \| u_t(t) \|^2 + \frac{1}{2} \| u_t(t) \|^2 _{2, \Gamma} + \frac{1}{p} I(t)$$

$$\geq \frac{p-2}{2p} \| \nabla u(t) \|^2 + \frac{1}{2} \| u_t(t) \|^2 + \frac{1}{2} \| u_t(t) \|^2 _{2, \Gamma} ,$$

(4.5)

since $I(t)$ and $(g \circ \nabla u)(t)$ are positive. Therefore

$$\| \nabla u(t) \|^2 + \| u_t(t) \|^2 \leq CE(0) , \quad \forall t \in [0, T_{\text{max}}) ,$$

where $C$ is a positive constant, which depends only on $p$ and $l$. Then by the definition of $T_{\text{max}}$, the solution is global, that is $T_{\text{max}} = \infty$. 12
5 Decay of solutions

In this section, we state and prove the general decay result. For positive constants $\varepsilon_1$ and $\varepsilon_2$, we use the following modified functional

$$L(t) = E(t) + \varepsilon_1 G(t) + \varepsilon_2 H(t),$$

(5.1)

where

$$G(t) = \int \Omega u_t udx + \int \Gamma_{1} u_t u dt + \frac{\alpha}{2} \|u_t\|_2^2 + \frac{\beta}{2} \|\nabla u\|_2^2 + \frac{\sigma}{4} \|\nabla u\|_4^4$$

(5.2)

and

$$H(t) = - \int \Omega u_t \int_0^t g(t-s) (u(t) - u(s)) ds dx - \int \Gamma_{1} u_t \int_0^t g(t-s) (u(t) - u(s)) ds d\sigma.$$  

(5.3)

It is easy to check that, by using Poincare’s inequality, trace inequality, (2.2), (2.3) and for $\varepsilon_1$, $\varepsilon_2$ small enough,

$$\alpha_1 L(t) \leq E(t) \leq \alpha_2 L(t)$$

(5.4)

holds for two positive constants $\alpha_1$ and $\alpha_2$.

**Theorem 5.1** Let $(u_0, u_1) \in H^1_{1,0} \times L^2(\Omega)$ be given. Assume that $g$ and $\xi$ satisfy (G1) and (G2). Then, for each $t_0 > 0$, there exist positive constants $K$ and $k$ such that the solution $\|u_t\|_p$ satisfies, for all $t \geq t_0$,

$$E(t) \leq Ke^{-k \int_0^t \xi(s) ds}.$$

(5.5)

**Lemma 5.2** Under the conditions of Theorem 5.1, the functional $G(t)$ defined by (5.2) satisfies

$$G'(t) \leq \|u_t(t)\|_2^2 + \|u_t(t)\|_2^2 + \int \Omega u_t u dx + \int \Gamma_{1} u_t u dt + \|u_t(t)\|_2^2 + \|u(t)\|_p^p$$

$$+ \frac{\gamma(m-1)}{m} \delta \|u_t(t)\|_{m, \Gamma_{1}}^m + \frac{a-l}{2l} (g \cdot \nabla u)(t),$$

(5.6)

for some $\delta > 0$.

**Proof.** By using the differential equation in (1.1), we get

$$G'(t) = \|u_t(t)\|_2^2 + \int \Omega u_t(t) u dx + \int \Gamma_{1} u_t(t) u dt + \|u_t(t)\|_2^2 + \alpha \int \Omega u_t u dx$$

$$+ \frac{\beta}{2} \int \Omega \nabla u_t \cdot \nabla u dx + \frac{\sigma}{2} \left( \int \Omega \frac{d}{dt} \|\nabla u\|_2^2 \right) \|\nabla u\|_2^2$$

$$= \|u_t(t)\|_2^2 + \|u_t(t)\|_2^2 + \int \Gamma_{1} \frac{\partial u(t)}{\partial \nu} u dt - (a+b \|\nabla u\|_2^2) \|\nabla u\|_2^2$$

$$- \int_0^t g(t-s) \int \Gamma_{1} \frac{\partial u(s)}{\partial \nu} u(s) ds + \int_0^t g(t-s) \int \Omega \nabla u(s) \cdot \nabla u dx ds$$

13
We now estimate the right hand side of (5.7). For two positive constants \(\delta\) and \(\eta\), we have the estimates as follows

\[
\int_{\Omega} \nabla u(t) \cdot \int_{0}^{t} g(t-s) \nabla u(s) ds \, dx \leq (\eta + a - l) ||\nabla u(t)||_{2}^{2} + \frac{a - l}{4\eta} (g \circ \nabla u)(t). \tag{5.8}
\]

By Young’s inequality, trace inequality and combining (4.1), we have

\[
\left| \int_{\Gamma_{1}} |u_{t}(t)|^{m-2} u_{t}(t) u(t) d\sigma \right| \leq \frac{\delta^{-m}}{m} ||u(t)||_{m, \Gamma_{1}}^{m} + \frac{m - 1}{m} \delta^{m-1} ||u(t)||_{m, \Gamma_{1}}^{m}, \tag{5.9}
\]

\[
||u(t)||_{m, \Gamma_{1}}^{m} \leq C ||\nabla u(t)||_{2}^{m} \leq C \left( \frac{2pE(0)}{l(p-2)} \right)^{\frac{m-2}{2}} ||\nabla u(t)||_{2}^{2}. \tag{5.10}
\]

Combining (5.7)–(5.10), we obtain

\[
G'(t) \leq ||u_{t}(t)||_{2}^{2} + ||u_{t}(t)||_{2, \Gamma_{1}}^{2} - \left( l - \eta - C\delta^{-m} \left( \frac{2pE(0)}{l(p-2)} \right)^{\frac{m-2}{2}} \right) ||\nabla u(t)||_{2}^{2} + ||u(t)||_{p}^{p} + \gamma \left( m - 1 \right) \delta^{m-1} ||u(t)||_{m, \Gamma_{1}}^{m} + \frac{a - l}{4\eta} (g \circ \nabla u)(t),
\]

Letting \(\eta = \frac{l}{2} > 0\) in above inequality, we arrive at (5.6).

**Lemma 5.3** Under the conditions of Theorem 5.1, the functional \(H(t)\) defined by (5.3) satisfies

\[
H'(t) \leq \left( \alpha + \delta - \int_{\Omega} g(s) ds \right) ||u_{t}(t)||_{2}^{2} + \left[ \delta + 2\delta(a - l)^{2} + \delta C_{v}^{2(p-1)} \left( \frac{2pE(0)}{l(p-2)} \right)^{p-2} \right] ||\nabla u(t)||_{2}^{2}
\]

\[
+ \left[ \frac{a - l}{4\delta} \left( a + 2pbE(0) \right) \right]^{2} + \frac{a - l}{4\delta} + \frac{a - l}{2\delta\lambda_{1}} + \frac{\beta(a - l)}{2} + \left( 2\delta + \frac{1}{4\delta} \right) (a - l)^{2}
\]

\[
+ \frac{\gamma C_{m}^{m} c}{4m \delta m} \left( \frac{8pE(0)}{l(p-2)} \right)^{\frac{m-2}{2}} \left( g \circ \nabla u(t) + \frac{\beta}{2} ||\nabla u_{t}(t)||_{2}^{2} + (\delta + a - l)||u_{t}(t)||_{2, \Gamma_{1}}^{2} \right)
\]

\[
+ \frac{\gamma \delta(m - 1)}{m} (a - l)||u_{t}(t)||_{m, \Gamma_{1}}^{m} + \frac{a - l}{2\delta\lambda_{1}} (-g' \circ \nabla u)(t) + \frac{\sigma(p - 2)}{2p} E(0) E'(t), \tag{5.11}
\]

for some \(\delta > 0\).

**Proof.** By using the differential equation in (1.1), we get

\[
H'(t) = - \int_{\Omega} u_{tt}(t) \int_{0}^{t} g(t-s) (u(t) - u(s)) ds \, dx - \int_{\Omega} u_{t}(t) \int_{0}^{t} g'(t-s) (u(t) - u(s)) ds \, dx
\]
- \left( \int_{0}^{t} g(s)ds \right) \int_{\Omega} |u(t)|^2 dx - \int_{\Gamma_1} u_t(t) \int_{0}^{t} g(t-s) (u(t) - u(s)) ds d\sigma \\
- \int_{\Gamma_1} u_t(t) \int_{0}^{t} g'(t-s) (u(t) - u(s)) ds d\sigma - \left( \int_{0}^{t} g(s)ds \right) \int_{\Gamma_1} |u_t(t)|^2 d\sigma \\
= - \int_{\Omega} \left( M(t) \Delta u(t) - \int_{0}^{t} g(t-s) \Delta u(s) ds - \alpha u_t(t) + \beta \Delta u_t(t) + |u(t)|^{p-2} u(t) \right) \\
\times \int_{0}^{t} g(t-s) (u(t) - u(s)) ds d\sigma - \int_{0}^{t} u_t(t) \int_{0}^{t} g'(t-s) (u(t) - u(s)) ds d\sigma \\
- \left( \int_{0}^{t} g(s)ds \right) \int_{\Omega} |u(t)|^2 dx - \int_{\Gamma_1} u_t(t) \int_{0}^{t} g'(t-s) (u(t) - u(s)) ds d\sigma \\
- \int_{\Gamma_1} \left( -M(t) \frac{\partial u}{\partial \nu}(x,t) + \int_{0}^{t} g(t-s) \frac{\partial u}{\partial \nu}(x,s) ds - \beta \frac{\partial u_t}{\partial \nu}(x,t) - \gamma |u_t|^{m-2} u_t(x,t) \right) \\
\times \int_{0}^{t} g(t-s) (u(t) - u(s)) ds d\sigma - \left( \int_{0}^{t} g(s)ds \right) \int_{\Gamma_1} |u_t(t)|^2 d\sigma \\
= \int_{\Omega} (a + b \| \nabla u(t) \|^2) \nabla u(t) \cdot \int_{0}^{t} g(t-s) (\nabla u(t) - \nabla u(s)) ds d\sigma \\
+ \beta \int_{\Omega} \nabla u_t(t) \cdot \int_{0}^{t} g(t-s) (\nabla u(t) - \nabla u(s)) ds d\sigma \\
- \int_{\Gamma_1} \nabla u(t) \int_{0}^{t} g(t-s) (\nabla u(t) - \nabla u(s)) ds d\sigma \\
+ \alpha \int_{\Omega} u_t(t) \int_{0}^{t} g(t-s) (u(t) - u(s)) ds d\sigma \\
- \int_{\Omega} |u(t)|^{p-2} u(t) \int_{0}^{t} g(t-s) (u(t) - u(s)) ds d\sigma \\
- \int_{\Omega} u_t(t) \int_{0}^{t} g'(t-s) (u(t) - u(s)) ds d\sigma - \left( \int_{0}^{t} g(s)ds \right) \| u_t(t) \|^2 \\
+ \gamma \int_{\Gamma_1} |u_t(t)|^{m-2} u_t(t) \int_{0}^{t} g(t-s) (u(t) - u(s)) ds d\sigma \\
- \int_{\Gamma_1} u_t(t) \int_{0}^{t} g'(t-s) (u(t) - u(s)) ds d\sigma \\
- \left( \int_{0}^{t} g(s)ds \right) \int_{\Gamma_1} |u_t(t)|^2 d\sigma \\
= - \int_{0}^{t} g(s)ds \| u_t(t) \|^2 + \sum_{i=1}^{10} I_i . \quad (5.12) \\

We now estimate \( I_i, i = 1, \cdots, 10 \) in the right side of (5.12). For \( \delta > 0 \), similar as in [8], exploiting \( E'(t) \leq -\sigma \left( \frac{1}{2} \frac{d}{dt} \| \nabla u(t) \|_2^2 \right) \) by (4.11), (4.14), Young's inequality, Hölder's inequality and Cauchy-Schwarz's inequality, we get

\[ I_1 = \int_{\Omega} (a + b \| \nabla u(t) \|^2) \nabla u(t) \cdot \int_{0}^{t} g(t-s) (\nabla u(t) - \nabla u(s)) ds d\sigma \]
\[ I_2 = \int_\Omega \sigma (\nabla u(t) \nabla u(t)) \nabla u(t) \cdot \int_0^t g(t-s) (\nabla u(t) - \nabla u(s)) \, ds \, dx \]
\[ \leq \delta^2 (\nabla u(t) \nabla u(t) dx)^2 \| \nabla u(t) \|_2^2 + \frac{1}{4l} \int_\Omega \left( \int_0^t g(t-s) (\nabla u(t) - \nabla u(s)) \, ds \right)^2 \, dx \]
\[ \leq \frac{-\sigma(p-2)}{2p} E(0) E'(t) + \frac{a-l}{4l} (g \circ \nabla u)(t), \]  

(5.14)

\[ I_3 = \beta \int_\Omega \nabla u_t(t) \cdot \int_0^t g(t-s) (\nabla u(t) - \nabla u(s)) \, ds \, dx \]
\[ \leq \frac{\beta}{2} \| \nabla u_t(t) \|_2^2 + \frac{\beta(a-l)}{2} (g \circ \nabla u)(t), \]

(5.15)

\[ I_4 = -\int_\Omega \int_0^t g(t-s) \nabla u(s) \, ds \int_0^t g(t-s) (\nabla u(t) - \nabla u(s)) \, ds \, dx \]
\[ \leq 2\delta(a-l)^2 \| \nabla u(t) \|_2^2 + \left( 2\delta + \frac{1}{4\delta} \right) (a-l)^2 (g \circ \nabla u)(t), \]

(5.16)

\[ I_5 = \alpha \int_\Omega u_t(t) \int_0^t g(t-s) (u(t) - u(s)) \, ds \, dx \]
\[ \leq \alpha \| u_t(t) \|_2^2 + \frac{a-l}{4\delta \lambda_1} (g \circ \nabla u)(t), \]

(5.17)

\[ I_6 = -\int_\Omega |u(t)|^{p-2} u(t) \int_0^t g(t-s) (u(t) - u(s)) \, ds \, dx \]
\[ \leq \delta C_\sigma^{p-1} \left( \frac{2p E(0)}{l(p-2)} \right)^{p-2} \| \nabla u(t) \|_2^2 + \frac{a-l}{4\delta \lambda_1} (g \circ \nabla u)(t), \]

(5.18)

\[ I_7 = -\int_{\Gamma_1} u_t(t) \int_0^t g'(t-s) (u(t) - u(s)) \, ds \, d\sigma \]
\[ \leq \delta \| u_t(t) \|_2^2 + \frac{a-l}{4\delta \lambda_1} (-g' \circ \nabla u)(t), \]

(5.19)

\[ I_8 = \gamma \int_{\Gamma_1} |u_t(t)|^{m-2} u_t(t) \int_0^t g(t-s) (u(t) - u(s)) \, ds \, d\sigma \]
\[ \leq \frac{\gamma \delta(m-1)}{m} (a-l) \| u_t(t) \|_m \| u_t(t) \|_{m,\Gamma_1} + \frac{\gamma C_\sigma^{m-1}}{4\delta m} \left( \frac{8p E(0)}{l(p-2)} \right)^{\frac{m-2}{2}} (g \circ \nabla u)(t), \]

(5.20)

\[ I_9 = -\int_{\Gamma_1} u_t(t) \int_0^t g'(t-s) (u(t) - u(s)) \, ds \, d\sigma \]
A combination of (5.13)-(5.22) yields (5.11).

**Proof of Theorem 5.1.** Since \( g \) is continuous and \( g(0) > 0 \), then for any \( t_0 > 0 \), we have

\[
\int_0^t g(s)ds \geq \int_0^{t_0} g(s)ds := g_0 > 0,
\]

for all \( t \geq t_0 \). From (4.1), (5.6), (5.11), then from (5.1), we get

\[
L'(t) = E'(t) + \varepsilon_1 G'(t) + \varepsilon_2 H'(t)
\]

\[
\leq - \left[ \alpha - \varepsilon_1 - \varepsilon_2 \left( \alpha + \delta - \int_0^t g(s)ds \right) \right] \|u_t(t)\|_2^2
\]

\[
- \left[ \frac{1}{2} g(t) - \varepsilon_1 \left( -\frac{l}{2} + \frac{C_1\delta^{-m}}{m} \frac{(2pE(0)) \frac{m-2}{p}}{l(p-2)} \right) \right] \|\nabla u(t)\|_2^2
\]

\[
- \left( \beta - \frac{\beta \varepsilon_2}{2} \right) \|\nabla u(t)\|_2^2 + \left[ \varepsilon_1 \frac{(a-l)}{2l} + \varepsilon_2 K_{\delta} \right] (g \circ \nabla u)(t)
\]

\[
+ \left[ \varepsilon_1 + \varepsilon_2 \left( \delta + a - l \right) \right] \|u_t(t)\|_{2, \Gamma_1}^2
\]

\[
- \left[ \frac{1}{2} - \varepsilon_2 \frac{(a-l)}{2\delta \lambda_1} \right] (g' \circ \nabla u)(t) + \varepsilon_1 \|u(t)\|_p^p - \frac{\sigma(p-2)}{2p} E(0) E'(t),
\]

where

\[
K_{\delta} = \delta + 2\delta(a-l)^2 + \delta C_2^{2(p-1)} \left( \frac{2pE(0)}{l(p-2)} \right)^{p-2} > 0,
\]

\[
K_{\mu} = \frac{a-l}{4\delta} \left( a + \frac{2pbE(0)}{(p-2)l} \right)^2 + \frac{\beta(a-l)}{2} + \left( 2\delta + \frac{1}{4\delta} \right) (1-l)^2
\]

\[
+ \frac{\gamma C_2^{m-2}}{4\delta m} \left( \frac{8pE(0)}{l(p-2)} \right)^{\frac{m-2}{2}} + \frac{a-l}{4l} + \frac{a-l}{2\delta \lambda_1} > 0.
\]

By the trace inequality

\[
\|u_t\|_{2, \Gamma_1}^2 \leq C_1 \|u_t\|_{W^{1,2}(\Omega)} \leq C \|u_t\|_2^2,
\]

then we have

\[
L'(t) \leq - \left[ \alpha - \varepsilon_1 - \varepsilon_2 \left( \alpha + \delta - \int_0^t g(s)ds \right) - C \left[ \varepsilon_1 + \varepsilon_2 (\delta + a - l) \right] \right] \|u_t(t)\|_2^2
\]
We then choose
\[ \gamma - \varepsilon_1 \frac{(m-1)\delta_{m-1}}{m} - \varepsilon_2 \frac{\gamma \delta (m-1)(a-l)}{m} \|
abla u(t)\|_{m, \Gamma_1} \]

\[ + \left[ \frac{1}{2} - \varepsilon_2 \frac{(a-l)}{2\delta \lambda_1} \right] (g' \circ \nabla u)(t) + \varepsilon_1 \|u(t)\|_p^p - \frac{\sigma(p-2)}{2p} E(0)E'(t). \]  

(5.24)

At this point, we choose \( \delta > 0 \) satisfying
\[ 0 < \delta < \frac{\alpha - \varepsilon_1 - \varepsilon_2 \left( \alpha - \int_0^t g(s)ds \right) - C \left[ \varepsilon_1 + \varepsilon_2 (a-l) \right]} {\left( 1 + C \right) \varepsilon_2}, \]
so we get

\[ k_1 = \alpha - \varepsilon_1 - \varepsilon_2 \left( \alpha - \delta - \int_0^t g(s)ds \right) - C \left[ \varepsilon_1 + \varepsilon_2 (\delta + a-l) \right] > 0. \]  

(5.25)

We then choose \( \varepsilon_1 \) and \( \varepsilon_2 \) so small that (5.4) and (5.25) remain valid and

\[ k_2 = \frac{1}{2} g(t) - \varepsilon_1 \left( -\frac{l}{2} + \frac{C \gamma \delta_{m-1} \left( 2pE(0) \right)^{\frac{m-2}{2}}}{l(p-2)} \right) - \varepsilon_2 K_\delta > 0, \]

\[ k_3 = \beta - \frac{\beta \varepsilon_2}{2} > 0, \]

\[ k_4 = \gamma - \varepsilon_1 \frac{(m-1)\delta_{m-1}}{m} - \varepsilon_2 \frac{\gamma \delta (m-1)(a-l)}{m} > 0, \]

\[ k_5 = \frac{1}{2} - \varepsilon_2 \frac{(a-l)}{2\delta \lambda_1} > 0. \]

Therefore, we have

\[ L'(t) \leq -k_1 \|u(t)\|_2^2 - k_2 \|
abla u(t)\|_2^2 - k_3 \|
abla u(t)\|_2^2 + \left[ \varepsilon_1 \frac{a-l}{2l} + \varepsilon_2 K_\mu \right] (g \circ \nabla u)(t) \]

\[ - k_4 \|u(t)\|_{m, \Gamma_1}^m + k_5 (g' \circ \nabla u)(t) + \varepsilon_1 \|u(t)\|_p^p - \frac{\sigma(p-2)}{2p} E(0)E'(t). \]  

(5.26)

Then, by (G1) and (G2), for positive constants \( M \) and \( \alpha_3 \) we obtain

\[ L'(t) \leq -ME(t) + \alpha_3 (g \circ \nabla u)(t) - \frac{\sigma(p-2)}{2p} E(0)E'(t), \forall t \geq t_0. \]  

(5.27)

Assume that (G1) and (G2) are satisfied, multiplying (5.27) by \( \xi(t) \), we have

\[ \xi(t)L'(t) \leq -M\xi(t)E(t) + \alpha_3 \xi(t)(g \circ \nabla u)(t) - \frac{\sigma(p-2)}{2p} E(0)\xi(t)E'(t), \forall t \geq t_0, \]  

(5.28)
using (G2), (4.1) and the fact that $\xi$ and $g$ are nonincreasing, we get
\[ \xi(t) \int_0^t g(t-s)\|\nabla u(t) - \nabla u(s)\|^2 ds \leq - \int_0^t g'(t-s)\|\nabla u(t) - \nabla u(s)\|^2 ds \leq -2E'(t) \]
and
\[ \frac{\sigma(p-2)}{2p}E(0)\xi(t)E'(t) \leq \frac{\sigma(p-2)}{2p}E(0)\xi(0)E'(t). \]

(5.29)

Inserting the last two inequalities in (5.28), we can obtain
\[ \xi(t)L'(t) + 2\alpha_4 E'(t) \leq -M\xi(t)E(t), \quad \forall t \geq t_0, \]
where $\alpha_4 = \alpha_3 + \frac{\sigma(p-2)}{2p}E(0)\xi(0)$ is a positive constant.

Now we consider the functional
\[ \Phi = \xi L + 2\alpha_4 E. \]

Using the facts that $\Phi \sim E$ and $\xi$ is nonincreasing, (5.30) gives
\[ \Phi'(t) \leq -k\xi(t)\Phi(t), \quad \forall t \geq t_0, \]
for some $k > 0$. Therefore, direct integration leads to
\[ \Phi(t) \leq \Phi(t_0)e^{-k\int_{t_0}^t \xi(s)ds}, \quad \forall t \geq t_0 \]
and the fact that $\Phi \sim E$ yields
\[ E(t) \leq \alpha_4 \Phi(t_0)e^{-k\int_{t_0}^t \xi(s)ds} = Ke^{-k\int_{t_0}^t \xi(s)ds}, \quad \forall t \geq t_0, \]
where $\alpha_4$ is a positive constant and $K = \alpha_4 \Phi(t_0)$. This completes the proof.

6 Blow up

In this section, we prove a finite time blow-up result for initial data in the unstable set. From the definition (2.4) of the potential depth $d$, for $u \in H^1_{\Gamma_0}(\Omega) \{0\}$, we have

Theorem 6.1 Suppose $2 \leq p \leq \overline{p}$, $m = 2$, (G1) and (G2) hold. Let $u$ be the unique local solution to problem (1.1), for any fixed $\delta < 1$, assume that $u_0, u_1$ satisfy
\[ E(0) = \delta d_1, \]
\[ I(0) = 0. \]
Suppose that

\[ \int_0^\infty g(s)ds \leq \frac{p-2}{a(p-2) + 1/[(1-\delta)^2p + 2\delta(1-\delta)]^\delta, \tag{6.3} \]

where \( \bar{\delta} = \max\{0, \delta\} \) and suppose further that \( \int_\Omega u_0u_1dx + \int_{\Gamma_1} u_0u_1d\sigma > 0 \) for \( 0 \leq E(0) < d_1 \), then \( T < \infty \). For \( t \geq 0 \), by (2.4), we have \( d_1 \) is the lower bound of \( d(t) \).

**Lemma 6.2** Under the same assumption as in Theorem [6.1], one has \( I(t) < 0 \) and

\[ d_1 < \frac{p-2}{2p} \left[ (a - \int_0^t g(s)ds) \|\nabla u(t)\|_2^2 + (g \circ \nabla u)(t) + \frac{b}{2}\|\nabla u(t)\|_2^4 \right] < \frac{p-2}{2p} \|u(t)\|_p^p, \tag{6.4} \]

for all \( t \in [0, T_{\text{max}}) \).

**Proof.** By Lemma [4.2] and (6.1), we have \( E(t) \leq \delta d_1 \), for all \( t \in [0, T_{\text{max}}) \). Moreover, we can obtain \( I(t) < 0 \) for all \( t \in [0, T_{\text{max}}) \). However, if it is not true, then there exists some \( t^* \in [0, T_{\text{max}}) \) such that \( I(t^*) = 0 \). Thus \( I(t) < 0 \) for all \( 0 \leq t < t^* \), i.e.

\[ \left( a - \int_0^t g(s)ds \right) \|\nabla u(t)\|_2^2 + (g \circ \nabla u)(t) + \frac{b}{2}\|\nabla u(t)\|_2^4 < \|u(t)\|_p^p, \quad 0 \leq t < t^*. \tag{6.5} \]

By the definition of \( d \), we have

\[ d < \frac{p-2}{2p} \left[ (a - \int_0^t g(s)ds) \|\nabla u(t)\|_2^2 + (g \circ \nabla u)(t) + \frac{b}{2}\|\nabla u(t)\|_2^4 \right], \quad 0 \leq t < t^*. \tag{6.6} \]

Combined with (6.5) and (6.6), we get

\[ \|u(t)\|_p^p > \frac{2p}{p-2} d_1 > 0, \quad 0 \leq t < t^*. \]

By the continuity of \( t \mapsto \|u(t)\|_p^p \), we get \( u(t^*) \neq 0 \). Because \( d_1 \) is the lower bound of \( d \) and (2.2), we obtain

\[ d_1 \leq \frac{p-2}{2p} \|u(t^*)\|_p^p = J(u(t^*)), \]

which contradicts to \( J(u(t^*)) \leq E(t^*) < d_1 \). By repeating the previous step, we obtain (6.4).

**Lemma 6.3** Let \( F(t) \) be a positive, twice differentiable function, for \( t > 0 \), we can obtain

\[ F(t)F''(t) - (1 + \kappa)F'(t)^2 \geq 0, \]

with some \( \kappa > 0 \). If \( F(0) > 0 \) and \( F'(0) > 0 \), then there exists a time \( T^* \leq F(0)/[\kappa F'(0)] \) such that \( \lim_{t \to T^*} F(t) = \infty \). We can see [30] for more details.
Proof of Theorem 6.1. Assume by contradiction that the solution \( u \) is global. Then for any \( T > 0 \), let us define the functional \( F \) as follows

\[
F(t) = \|u(t)\|_2^2 + \|u(t)\|_{2,1}^2 + \frac{\sigma}{2} \int_0^t \|\nabla u(s)\|^2_2 ds + \alpha \int_0^t \|u(s)\|_2^2 ds + \beta \int_0^t \|\nabla u(s)\|^2 ds + \gamma \int_0^t \|u(s)\|_{2,1}^2 ds + (T - t) \left[ \alpha \|u_0\|_2^2 + \beta \|\nabla u_0\|_2^2 + \gamma \|u_0\|_{2,1}^2 + \frac{\sigma}{2} \|\nabla u_0\|_2^2 \right] + b(t + T_0)^2,
\]

where \( T \) and \( T_0 \) are positive constants to be chosen later, \( b > 0 \) if \( E(0) < 0 \) and \( b = 0 \) if \( E(0) > 0 \). Then \( F(t) > 0 \) for all \( t \in [0, T] \). Furthermore,

\[
F'(t) = 2 \int_{\Omega} u_t u dx + 2 \int_{\Gamma_1} u_t u d\sigma + \frac{\sigma}{2} \int_0^t \frac{d}{dt} \|\nabla u(s)\|^2_2 ds + 2\alpha \int_0^t \int_{\Omega} u_t u dx ds + 2\beta \int_0^t \int_{\Omega} \nabla u_t \cdot \nabla u dx ds + 2\gamma \int_0^t \int_{\Gamma_1} u_t u d\sigma ds + 2b(t + T_0),
\]

and

\[
F''(t) = 2 \left[ \|u_t(t)\|_2^2 - \left( a - \int_0^t g(s) ds \right) \|\nabla u(t)\|^2_2 + \|u_t(t)\|_{2,1}^2 + \frac{\sigma}{2} \|\nabla u_0\|_2^2 \right] + \int_0^t \nabla u(t) \cdot \left( \int_0^t g(t - s) (\nabla u(t) - \nabla u(s)) ds \right) dx + \|u\|_p^p + b \right].
\]

Therefore, using the definition of \( F(t) \), we get

\[
F(t)F''(t) - \frac{p\|u\|_p^p}{4} F'(t)^2 = F(t)F''(t) + (p + 2) \left[ \eta(t) - (F(t) - (T - t) \left( \alpha \|u_0(t)\|_2^2 + \beta \|\nabla u_0(t)\|_2^2 + \frac{\sigma}{2} \|\nabla u_0\|_2^2 \right) + b(t + T_0)^2 \right]
\]

where the function \( \eta \) is defined by

\[
\eta(t) = \left( \|u(t)\|_2^2 + \|u(t)\|_{2,1}^2 + \frac{\sigma}{2} \int_0^t \|\nabla u(s)\|^2_2 ds + \alpha \int_0^t \|u(s)\|_2^2 ds + \beta \int_0^t \|\nabla u(s)\|^2 ds + \gamma \int_0^t \|u(s)\|_{2,1}^2 ds + b(t + T_0)^2 \right) \left( \|u_t(t)\|_2^2 + \|u_t(t)\|_{2,1}^2 + \frac{\sigma}{2} \|\nabla u_0\|_2^2 \right) + \int_0^t \|u_t(s)\|_2^2 ds + \alpha \int_0^t \|u_t(s)\|_{2,1}^2 ds + \beta \int_0^t \|\nabla u_t(s)\|_2^2 ds + \gamma \int_0^t \|u_t(s)\|_{2,1}^2 ds + b(t + T_0)^2 \right] - \left[ \int_{\Omega} u_t(t) u(t) dx + \int_{\Gamma_1} u_t(t) u(t) d\sigma + \frac{\sigma}{4} \int_0^t \frac{d}{dt} \|\nabla u(s)\|^2_2 ds + \alpha \int_0^t \int_{\Omega} u_t(t) u(t) dx ds + \beta \int_0^t \int_{\Omega} \nabla u_t(t) \nabla u(t) dx ds + \gamma \int_0^t \int_{\Gamma_1} u_t(t) u(t) d\sigma ds + b(t + T_0) \right]^2.
\]
By Cauchy-Schwarz inequality, for all \( t \in [0, T] \), we have \( \eta(t) \geq 0 \). As a consequence, we read the following differential inequality

\[
F(t)F'(t) - \frac{p + 2}{4} F'(t)^2 \geq F(t) \zeta(t), \quad \forall t \in [t, T].
\] (6.8)

where

\[
\zeta(t) = -p \Vert u_t(t) \Vert_2^2 - 2 \left(a - \int_0^t g(s)ds\right) \Vert \nabla u(t) \Vert_2^2 - \frac{b}{2} \Vert \nabla u(t) \Vert_2^4 - p \Vert u_t(t) \Vert_{2, \Gamma_1}^2 + 2 \Vert u(t) \Vert_p^p
\]

\[-(p + 2) \left( \alpha \int_0^t \Vert u_t(s) \Vert_2^2 ds + \beta \int_0^t \Vert \nabla u_t(s) \Vert_2^2 ds + \gamma \int_0^t \Vert u_t(s) \Vert_{2, \Gamma_1}^2 ds \right)
\]

\[+ \frac{\sigma}{2} \int_0^t \Vert \nabla u_t(s) \Vert_2^2 ds - 2 \int_\Omega \nabla u(t) \cdot \left( \int_0^t g(t-s) (\nabla u(t) - \nabla u(s)) ds \right) dx - pb\]

\[= -2pE(t) + (p - 2) \left(a - \int_0^t g(s)ds\right) \Vert \nabla u(t) \Vert_2^2 + p(g \circ \nabla u)(t) + \frac{(p - 1)b}{2} \Vert \nabla u(t) \Vert_2^4
\]

\[-(p + 2) \left( \alpha \int_0^t \Vert u_t(s) \Vert_2^2 ds + \beta \int_0^t \Vert \nabla u_t(s) \Vert_2^2 ds + \gamma \int_0^t \Vert u_t(s) \Vert_{2, \Gamma_1}^2 ds \right)
\]

\[+ \frac{\sigma}{2} \int_0^t \Vert \nabla u_t(s) \Vert_2^2 ds - 2 \int_\Omega \nabla u(t) \cdot \left( \int_0^t g(t-s) (\nabla u(t) - \nabla u(s)) ds \right) dx - pb.\]

From the equality (4.1), (G1), (G2) and \( m = 2 \) we have

\[
E'(t) = \frac{1}{2} (g' \circ \nabla u)(t) - \frac{1}{2} g(t) \Vert \nabla u(t) \Vert_2^2 - \alpha \Vert u_t(t) \Vert_2^2 - \beta \Vert \nabla u_t(t) \Vert_2^2
\]

\[-\gamma \Vert u_t(t) \Vert_{2, \Gamma_1}^2 - \sigma \left( \frac{1}{dt} \Vert \nabla u(t) \Vert_2^2 \right)^2 \]

\[\leq -\alpha \Vert u_t(t) \Vert_2^2 - \beta \Vert \nabla u_t(t) \Vert_2^2 - \gamma \Vert u_t(t) \Vert_{2, \Gamma_1}^2 - \sigma \left( \frac{1}{dt} \Vert \nabla u(t) \Vert_2^2 \right)^2.\]

Thus, we can write

\[
\zeta(t) \geq -2pE(0) + (p - 2) \left(a - \int_0^t g(s) ds\right) \Vert \nabla u(t) \Vert_2^2 + p(g \circ \nabla u)(t) + \frac{(p - 1)b}{2} \Vert \nabla u(t) \Vert_2^4
\]

\[+ (p - 2) \left( \alpha \int_0^t \Vert u_t(s) \Vert_2^2 ds + \beta \int_0^t \Vert \nabla u_t(s) \Vert_2^2 ds + \gamma \int_0^t \Vert u_t(s) \Vert_{2, \Gamma_1}^2 ds \right)
\]

\[+ \frac{\sigma}{2} \int_0^t \Vert \nabla u_t(s) \Vert_2^2 ds - 2 \int_\Omega \nabla u(t) \cdot \left( \int_0^t g(t-s) (\nabla u(t) - \nabla u(s)) ds \right) dx - pb.\] (6.9)

By Young's inequality, we have

\[
2 \int_\Omega \nabla u(t) \cdot \left( \int_0^t g(t-s) (\nabla u(t) - \nabla u(s)) ds \right)
\]

\[\leq \frac{1}{\varepsilon} \int_0^t g(s) \Vert \nabla u(t) \Vert_2^2 ds + \varepsilon (g \circ \nabla u)(t),\] (6.10)

for any \( \varepsilon > 0 \). Substitute (6.10) for the fifth term of the right hand side of (6.9), we have

\[
\zeta(t) \geq -2pE(0) + \left[a(p - 2) - \left(p - 2 + \frac{1}{\varepsilon} \right) \int_0^t g(s) ds\right] \Vert \nabla u(t) \Vert_2^2 + (p - \varepsilon)(g \circ \nabla u)(t)
\]

22
\[ + (p - 2) \left( \alpha \int_0^t \| u_t(s) \|_2^2 ds + \beta \int_0^t \| \nabla u_t(s) \|_2^2 ds + \gamma \int_0^t \| u_t(s) \|_{2, \Gamma_1}^2 ds \right) \\
+ \frac{\sigma}{2} \int_0^t \| \nabla u_t(s) \|_2^2 ds + \frac{(p-1)b}{2} \| \nabla u(t) \|_2^4 - pb. \tag{6.11} \]

On the one hand, if \( \delta < 0 \), then \( E(0) < 0 \), we choose \( \varepsilon = p \) in (6.11) and \( b \) small enough such that \( b \leq -2E(0) \). Then, by (6.3), we get

\[
\zeta(t) \geq \left[ a(p-2) - \left( p - 2 + \frac{1}{p} \right) \int_0^t g(s) ds \right] \| \nabla u(t) \|_2^2 + p(-2E(0) - b) + \frac{(p-1)b}{2} \| \nabla u(t) \|_2^4 \\
+ (p - 2) \left( \alpha \int_0^t \| u_t(s) \|_2^2 ds + \beta \int_0^t \| \nabla u_t(s) \|_2^2 ds + \gamma \int_0^t \| u_t(s) \|_{2, \Gamma_1}^2 ds \right) \\
+ \frac{\sigma}{2} \int_0^t \| \nabla u_t(s) \|_2^2 ds \right] \geq 0. \tag{6.12} \]

On the other hand, if \( 0 \leq \delta < 1 \), then \( 0 \leq E(0) = \delta d_1 < d_1 \), we choose \( \varepsilon = (1-\delta)p + 2\delta \) in (6.11). Then, we have

\[
\zeta(t) \geq -2pE(0) + \delta(p-2)(g \circ \nabla u)(t) + \frac{(p-1)b}{2} \| \nabla u(t) \|_2^4 \\
+ \left[ a(p-2) - \left( p - 2 + \frac{1}{(1-\delta)p + 2\delta} \right) \int_0^t g(s) ds \right] \| \nabla u(t) \|_2^2 \\
+ (p - 2) \left( \alpha \int_0^t \| u_t(s) \|_2^2 ds + \beta \int_0^t \| \nabla u_t(s) \|_2^2 ds + \gamma \int_0^t \| u_t(s) \|_{2, \Gamma_1}^2 ds \right) \\
+ \frac{\sigma}{2} \int_0^t \| \nabla u_t(s) \|_2^2 ds \right]. \]

By (6.3), we obtain

\[
a(p-2) - \left( p - 2 + \frac{1}{(1-\delta)p + 2\delta} \right) \int_0^t g(s) ds \geq \delta(p-2) \left( a - \int_0^t g(s) ds \right), \]

and therefore, by (6.4), we have

\[
\zeta(t) \geq -2pE(0) + \delta(p-2) \left[ a - \int_0^t g(s) ds \right] \| \nabla u(t) \|_2^2 + (g \circ \nabla u)(t) + \frac{(p-1)b}{2} \| \nabla u(t) \|_2^4 \\
+ (p - 2) \left( \alpha \int_0^t \| u_t(s) \|_2^2 ds + \beta \int_0^t \| \nabla u_t(s) \|_2^2 ds + \gamma \int_0^t \| u_t(s) \|_{2, \Gamma_1}^2 ds \right) \\
+ \frac{\sigma}{2} \int_0^t \| \nabla u_t(s) \|_2^2 ds \right]. \]
\[ \geq (p - 2) \left( \alpha \int_0^t \| u_t(s) \|_2^2 ds + \beta \int_0^t \| \nabla u_t(s) \|_2^2 ds + \gamma \int_0^t \| u_t(s) \|_{H^1}^2 ds \right. \\
+ \left. \frac{\sigma}{2} \int_0^t \| \nabla u_t(s) \|_2^2 ds \right) + \frac{(p - 1)b}{2} \| \nabla u(t) \|_2^4 + 2p(\delta d_1 - E(0)) \geq 0. \]  
(6.13)

From (6.8), (6.12) and (6.13), we get

\[ F(t)F''(t) - \frac{p + 2}{4} F'(t)^2 \geq 0, \quad \forall t \in [t, T]. \]

By (6.7), we can choose \( T_0 \) sufficiently large such that \( F'(0) = 2 \int_\Omega u_0 u_1 dx + 2 \int_{\Gamma_1} u_0 u_1 d\sigma + 2bT_0 > 0 \), when \( E(0) < 0 \). As \( 0 \leq E(0) < d_1 \), the condition \( \int_\Omega u_0 u_1 dx + \int_{\Gamma_1} u_0 u_1 d\sigma > 0 \) also ensure that \( F'(0) > 0 \). As \( (p + 2)/4 > 1 \), letting \( \kappa = (p - 2)/4 \), by using the concavity argument, we get \( \lim_{t \to T^*} F(t) = \infty \), which implies that \( \lim_{t \to T^*} \| \nabla u(t) \|_2^2 = \infty \).

References

[1] R. A. Adams, *Sobolev spaces*, Academic Press, New York, 1975.

[2] C. O. Alves et al., On existence, uniform decay rates and blow up for solutions of systems of nonlinear wave equations with damping and source terms, Discrete Contin. Dyn. Syst. Ser. S 2 (2009), no. 3, 583–608.

[3] K. T. Andrews, K. L. Kuttler and M. Shillor, Second order evolution equations with dynamic boundary conditions, J. Math. Anal. Appl. 197 (1996), no. 3, 781–795.

[4] A. V. Balakrishnan and L. W. Taylor, Distributed parameter nonlinear damping models for flight structures. in: *Proceedings “Daming 8”*, Flight Dynamics Lab and Air Force Wright Aeronautical Labs, WPAFB, 1989.

[5] R. W. Bass and D. Zes, Spillover nonlinearity, and flexible structures. in: The Fourth NASA Workshop on Computational Control of Flexible Aerospace Systems, Taylor, L.W.(ed.), NASA Conference Publication 10065, 1991, pp. 1-14.

[6] J. T. Beale, Spectral properties of an acoustic boundary condition, Indiana Univ. Math. J. 25 (1976), no. 9, 895–917.

[7] S. Berrimi and S. A. Messaoudi, Exponential decay of solutions to a viscoelastic equation with nonlinear localized damping, Electron. J. Differential Equations 2004, No. 88, 10 pp. (electronic).

[8] S. Berrimi and S. A. Messaoudi, Existence and decay of solutions of a viscoelastic equation with a nonlinear source, Nonlinear Anal. 64 (2006), no. 10, 2314–2331.

[9] Haim Brezis, *Analyse Fonctionnelle*, Masson, Paris, 1983.
[10] B. M. Budak, A. A. Samarskii and A. N. Tikhonov, *A collection of problems on mathematical physics*, Translated by A. R. M. Robson; translation edited by D. M. Brink. A Pergamon Press Book, Macmillan, New York, 1964.

[11] M. M. Cavalcanti et al., On the existence and the uniform decay of a hyperbolic equation with non-linear boundary conditions, Southeast Asian Bull. Math. 24 (2000), no. 2, 183–199.

[12] M. M. Cavalcanti et al., Existence and uniform decay rates for viscoelastic problems with nonlinear boundary damping, Differential Integral Equations 14 (2001), no. 1, 85–116.

[13] M. M. Cavalcanti, V. N. Domingos Cavalcanti and J. Ferreira, Existence and uniform decay for a non-linear viscoelastic equation with strong damping, Math. Methods Appl. Sci. 24 (2001), no. 14, 1043–1053.

[14] M. M. Cavalcanti, V. N. Domingos Cavalcanti and P. Martinez, General decay rate estimates for viscoelastic dissipative systems, Nonlinear Anal. 68 (2008), no. 1, 177–193.

[15] M. M. Cavalcanti, V. N. Domingos Cavalcanti and J. A. Soriano, Exponential decay for the solution of semilinear viscoelastic wave equations with localized damping, Electron. J. Differential Equations 2002, No. 44, 14 pp.

[16] E. A. Coddington and N. Levinson, *Theory of ordinary differential equations*, McGraw-Hill Book Company, Inc., New York, 1955.

[17] M. Grobbelaar-Van Dalsen, On fractional powers of a closed pair of operators and a damped wave equation with dynamic boundary conditions, Appl. Anal. 53 (1994), no. 1-2, 41–54.

[18] M. Grobbelaar-Van Dalsen, On the initial-boundary-value problem for the extensible beam with attached load, Math. Methods Appl. Sci. 19 (1996), no. 12, 943–957.

[19] M. Grobbelaar-Van Dalsen and A. van der Merwe, Boundary stabilization for the extensible beam with attached load, Math. Models Methods Appl. Sci. 9 (1999), no. 3, 379–394.

[20] G. G. Doronin and N. A. Larkin, Global solvability for the quasilinear damped wave equation with nonlinear second-order boundary conditions, Nonlinear Anal. 50 (2002), no. 8, Ser. A: Theory Methods, 1119–1134.

[21] G. G. Doronin, N. A. Larkin and A. J. Souza, A hyperbolic problem with nonlinear second-order boundary damping, Electron. J. Differential Equations 1998, No. 28, 10 pp.

[22] F. Gazzola and M. Squassina, Global solutions and finite time blow up for damped semilinear wave equations, Ann. Inst. H. Poincaré Anal. Non Linéaire 23 (2006), no. 2, 185–207.
[23] S. Gerbi and B. Said-Houari, Local existence and exponential growth for a semilinear damped wave equation with dynamic boundary conditions, Adv. Differential Equations 13 (2008), no. 11-12, 1051–1074.

[24] S. Gerbi and B. Said-Houari, Asymptotic stability and blow up for a semilinear damped wave equation with dynamic boundary conditions, Nonlinear Anal. 74 (2011), no. 18, 7137–7150.

[25] S. Gerbi and B. Said-Houari, Global existence and exponential growth for a viscoelastic wave equation with dynamic boundary conditions, Adv. Nonlinear Anal. 2 (2013), no. 2, 163–193.

[26] V. Georgiev and G. Todorova, Existence of a solution of the wave equation with nonlinear damping and source terms, J. Differential Equations 109 (1994), no. 2, 295–308.

[27] G. R. Goldstein, Derivation and physical interpretation of general boundary conditions, Adv. Differential Equations 11 (2006), no. 4, 457–480.

[28] P. J. Graber and B. Said-Houari, Existence and asymptotic behavior of the wave equation with dynamic boundary conditions, Appl. Math. Optim. 66 (2012), no. 1, 81–122.

[29] J. Jeong, J. Y. Park and Y. H. Kang, Energy decay rates for viscoelastic wave equation with dynamic boundary conditions, J. Comput. Anal. Appl. 19 (2015), no. 3, 500–517.

[30] H. A. Levine, Instability and nonexistence of global solutions to nonlinear wave equations of the form $Pu_{tt} = -Au + F(u)$, Trans. Amer. Math. Soc. 192 (1974), 1–21.

[31] H. A. Levine, S. R. Park and J. Serrin, Global existence and global nonexistence of solutions of the Cauchy problem for a nonlinearly damped wave equation, J. Math. Anal. Appl. 228 (1998), no. 1, 181–205.

[32] J. L. Lions, Quelques Methodes de Resolution des Problemes aux Limites Nolineaires, Dunod, 1969.

[33] W. Liu, The exponential stabilization of the higher-dimensional linear system of thermo-viscoelasticity, J. Math. Pures Appl. (9) 77 (1998), no. 4, 355–386.

[34] W. Liu, Global existence, asymptotic behavior and blow-up of solutions for a viscoelastic equation with strong damping and nonlinear source, Topol. Methods Nonlinear Anal. 36 (2010), no. 1, 153–178.

[35] S. A. Messaoudi, Blow up and global existence in a nonlinear viscoelastic wave equation, Math. Nachr. 260 (2003), 58–66.
[36] S. A. Messaoudi, Blow-up of positive-initial-energy solutions of a nonlinear viscoelastic hyperbolic equation, J. Math. Anal. Appl. 320 (2006), no. 2, 902–915.

[37] S. A. Messaoudi and N.-E. Tatar, Global existence and asymptotic behavior for a nonlinear viscoelastic problem, Math. Sci. Res. J. 7 (2003), no. 4, 136–149.

[38] S. A. Messaoudi and N. Tatar, Global existence and uniform stability of solutions for a quasilinear viscoelastic problem, Math. Methods Appl. Sci. 30 (2007), no. 6, 665–680.

[39] C. Mu and J. Ma, On a system of nonlinear wave equations with Balakrishnan-Taylor damping, Z. Angew. Math. Phys. 65 (2014), no. 1, 91–113.

[40] M. I. Mustafa, Well posedness and asymptotic behavior of a coupled system of nonlinear viscoelastic equations, Nonlinear Anal. Real World Appl. 13 (2012), no. 1, 452–463.

[41] M. Pellicer, Large time dynamics of a nonlinear spring-mass-damper model, Nonlinear Anal. 69 (2008), no. 9, 3110–3127.

[42] M. Pellicer and J. Solà-Morales, Analysis of a viscoelastic spring-mass model, J. Math. Anal. Appl. 294 (2004), no. 2, 687–698.

[43] F. Sun and M. Wang, Non-existence of global solutions for nonlinear strongly damped hyperbolic systems, Discrete Contin. Dyn. Syst. 12 (2005), no. 5, 949–958.

[44] N. Tatar and A. Zaraï, Exponential stability and blow up for a problem with Balakrishnan-Taylor damping, Demonstratio Math. 44 (2011), no. 1, 67–90.

[45] G. Todorova, Cauchy problem for a nonlinear wave equation with nonlinear damping and source terms, C. R. Acad. Sci. Paris Sér. I Math. 326 (1998), no. 2, 191–196.

[46] G. Todorova, Stable and unstable sets for the Cauchy problem for a nonlinear wave equation with nonlinear damping and source terms, J. Math. Anal. Appl. 239 (1999), no. 2, 213–226.

[47] G. Todorova and E. Vitillaro, Blow-up for nonlinear dissipative wave equations in $\mathbb{R}^n$, J. Math. Anal. Appl. 303 (2005), no. 1, 242–257.

[48] E. Vitillaro, Global nonexistence theorems for a class of evolution equations with dissipation, Arch. Ration. Mech. Anal. 149 (1999), no. 2, 155–182.

[49] E. Vitillaro, A potential well theory for the wave equation with nonlinear source and boundary damping terms, Glasg. Math. J. 44 (2002), no. 3, 375–395.

[50] S.-T. Wu, Non-existence of global solutions for a class of wave equations with nonlinear damping and source terms, Proc. Roy. Soc. Edinburgh Sect. A 141 (2011), no. 4, 865–880.
[51] S.-T. Wu, General decay of solutions for a viscoelastic equation with Balakrishnan-Taylor damping, Taiwan. J. Math. 19 (2015), no. 2, 553–566.

[52] R. Z. Xu, Global existence, blow up and asymptotic behaviour of solutions for nonlinear Klein-Gordon equation with dissipative term, Math. Methods Appl. Sci. 33 (2010), no. 7, 831–844.

[53] A. Zaraï and N.-E. Tatar, Global existence and polynomial decay for a problem with Balakrishnan-Taylor damping, Arch. Math. (Brno) 46 (2010), no. 3, 157–176.

[54] A. Zaraï, N. Tatar and S. Abdelmalek, Elastic membrane equation with memory term and nonlinear boundary damping: global existence, decay and blowup of the solution, Acta Math. Sci. Ser. B Engl. Ed. 33 (2013), no. 1, 84–106.

[55] H. Zhang and Q. Hu, Energy decay for a nonlinear viscoelastic rod equations with dynamic boundary conditions, Math. Methods Appl. Sci. 30 (2007), no. 3, 249–256.