**Improved ChIP-chip analysis by a mixture model approach**

Wei Sun*1, Michael J Buck2, Mukund Patel3 and Ian J Davis*3,4

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**Background**

Microarray analysis of immunoprecipitated chromatin (ChIP-chip) has evolved from a novel technique to a standard approach for the systematic study of protein-DNA interactions. In ChIP-chip, sites of protein-DNA interactions are identified by signals from the hybridization of selected DNA to tiled oligomers and are graphically represented as peaks. Most existing methods were designed for the identification of relatively sparse peaks, in the presence of replicates.

**Results:** We propose a data normalization method and a statistical method for peak identification from ChIP-chip data based on a mixture model approach. In contrast to many existing methods, including methods that also employ mixture model approaches, our method is more flexible by imposing less restrictive assumptions and allowing a relatively large proportion of peak regions. In addition, our method does not require experimental replicates and is computationally efficient. We compared the performance of our method with several representative existing methods on three datasets, including a spike-in dataset. These comparisons demonstrate that our approach is more robust and has comparable or higher power than the other methods, especially in the context of abundant peak regions.

**Conclusion:** Our data normalization and peak detection methods have improved performance to detect peak regions in ChIP-chip data.
applied the Wilcoxon rank sum test and t-test, respectively, to generate test-statistics for sliding windows. Cawley et al. used a fixed p-value cutoff to select peak regions. Whereas Keles et al. employed the Benjamini and Hochberg step-up procedure [14] to control false discovery rate (FDR). In addition to the requirement for experimental replicates, Gottardo et al. [13] identified the absence of powerful multiple testing adjustment methods as a limitation of these methods. Li et al. [7] proposed a hidden Markov model (HMM) approach to identify peak regions, assuming model parameters could be estimated from previous experiments. Ji et al. [6] used a modified t-statistic with a more robust estimate of variance to measure probe-level binding signal, then used either moving window averaging or HMM to estimate window-level binding signal, and finally estimated local false discovery rate (lfdr) of each peak region [15]. Estimation of lfdr requires dissection of the mixture distribution of ChIP-chip signals, which includes the distribution of ChIP enriched signals (or peak signals) and the background (null) distribution. Ji et al. [6] estimated the mixture distribution by unbalanced mixture subtraction, which requires additional information to construct the unbalanced mixtures. Instead of concentrating exclusively on the strengths of binding signals, Zheng et al. [12] identified peaks using both signal strength and signal pattern. Specifically, they modeled the DNA fragmentation process with a Poisson point process and concluded that if the binding signal is transformed to log scale, isolated "peaks" should exhibit a triangular shape allowing development of a double regression method, Mpeak, to identify triangular patterns from ChIP-chip data.

Two recent studies [10,13] have employed Bayesian hierarchical models to identify protein binding sites from ChIP-chip data. A major advantage of Bayesian hierarchical models is that the information across probes can be shared; this is especially important when analyzing a limited number of replicates. However, the difficulty of fitting the complicated Bayesian hierarchical models poses a heavy computational burden. Despite their common characteristics, several attributes distinguish these two approaches. Keles’s method [10], HGMM (hierarchical gamma mixture model), adopted a hierarchical gamma-gamma model [16]. HGMM is able to detect peak regions of different sizes. However, its constant coefficient of variation assumption can have an undesired effect in the presence probe outliers [13], and it assumes at most one peak per genomic region, so that the genome has to be partitioned (often arbitrarily) into smaller regions before applying HGMM. Gottardo et. al.’s method [13], BAC (Bayesian Analysis of ChIP-chip), is based on approaches used for gene expression studies [17] with some additional modifications to exploit the spatial dependence between neighboring probes and to improve the robustness for ChIP-chip studies. However, BAC, as it is currently implemented, cannot be applied to a single sample.

In this paper, we propose a mixture model approach to identify peaks from ChIP-chip data. Our method builds on the important observation made by Buck et al. [5] that the signals from ChIP-chip data are not symmetric. When transformed into log scale and represented as a histogram, the signal density often has a heavier right-tail reflective of the presence of true positive signals. It is reasonable to assume that the majority of the left-tail of the signal density arises from background noise, which defines the null distribution. Based on the additional assumption that the null distribution is normal with mean of 0, Buck et al. [5] used negative signals to construct the null distribution and then evaluated the p-values of tested regions. Following Buck et al. [5], we assume that the null distribution is symmetric, but we allow the null distribution to be non-normal and allow its center to deviate from 0. We estimate the local false discovery rate (lfdr) [15] for each peak based on a nonparametric approach to dissect the null distribution (background signals) and alternative distribution (ChIP enriched signals). As pointed by Zheng et al. [12], omitting auto-correlation structure of nearby probes leads to bias in estimating the significance level of each peak. In this study, we adopted the Poisson point process used by Zheng et al. [12] to estimate auto-correlation and incorporate auto-correlation into the lfdr evaluation procedure.

Compared with the existing methods, our method does not rely on potentially restrictive assumptions, such as a normal null distribution [5], or prior knowledge, such as the availability of model parameters [7]. Our major assumption is that the null distribution is symmetric, which can typically be achieved after appropriate normalization (see below). Importantly, our method permits analysis in the absence of replicates, a situation that often arises in exploratory ChIP-chip studies [18]. In addition, our method functions well with abundant peak regions, which is common in the increasing popular epigenetic studies [19,20].

Our method also alleviates the burden of cross array normalization. In large scale studies, a number of arrays are often needed to cover the entire region of interest. Signal differences between arrays may due to technical effects (experimental bias) or relevant biological differences. If prior knowledge implies that there is no systematic biological difference across arrays, it may be more appropriate to combine those arrays prior to the application of peak finding methods. For example, in NimbleScan, the software provided by NimbleGen, the raw data (log ratio) is normalized by subtracting a robust estimate of the sample median. In other words, the data from different arrays
are aligned by their medians. However, in practice, it may be difficult to know whether biological differences contribute to systematic differences across arrays. Our method uses the signals derived from one array to identify peaks thereby avoiding the potential problem of cross array normalization. Peaks from different arrays can then be compared by their Ifdrs.

In raw data, the null distribution reflecting background noise may not be symmetric and may be heterogeneous depending on the GC-content of the probes [11]. Therefore, within-array data normalization is crucial to the success of our mixture distribution method. Song et al. [11] proposed a normalization method, MA2C (model based 2-color arrays), that normalizes data by assuming the log-intensities of the two channels follow a bivariate distribution with GC-specific means and variances. Song et al. have shown that MA2C standardizes data from different samples more efficiently than other existing methods. Although MA2C works well in many situations, sometime MA2C normalized data still have nonhomogenous null distributions across GC-contents. To overcome this issue, our method uses a Lowess smooth curve to capture the GC-content specific information.

Our mixture model approach is general enough to be applied to one-color arrays (e.g., some Affymetrix tiling arrays), two-color arrays (e.g., some Nimblegen tiling arrays), and high throughput sequencing data. However, since the normalization method pertains to two-color arrays, we focus on its application for two-color arrays. We have implemented our method into an R package, Mixer, which can be downloaded from http://www.bios.unc.edu/~wsun/software/mixer.htm.

Methods

Data normalization

Let the \( x_{2i} \) and \( x_{1i} \) be \( \log_2(Cy5) \) and \( \log_2(Cy3) \) of the \( i \)-th probe with GC content \( k \), and let \( \hat{\mu}_{2k} \) and \( \hat{\mu}_{1k} \) be the expected value of \( x_{2i} \) and \( x_{1i} \), respectively. MA2C normalizes data by calculating

\[
\frac{x_{2i} - x_{1i} - (\hat{\mu}_{2k} - \hat{\mu}_{1k})}{\hat{\sigma}_i},
\]

where \( \hat{\mu}_{2k} \) and \( \hat{\mu}_{1k} \) are robust estimates of \( \mu_{2k} \) and \( \mu_{1k} \), respectively, and \( \hat{\sigma}_i \) is a robust estimate of the standard deviation of \( x_{2i} - x_{1i} \). Considering \( \hat{\sigma}_i = x_{1i} + (\hat{\mu}_{2k} - \hat{\mu}_{1k}) \) as a predictive value of \( x_{2i} \) based on the linear model

\[
\log_2(Cy5) = \log_2(Cy3) + b_i
\]

where \( b_i \) is estimated by \( \hat{\mu}_{2k} - \hat{\mu}_{1k} \). Then \( x_{2i} - x_{1i} - (\hat{\mu}_{2k} - \hat{\mu}_{1k}) \) is the residual from the baseline model \( \log_2(Cy5) = \log_2(Cy3) + (\hat{\mu}_{2k} - \hat{\mu}_{1k}) \), and the MA2C normalized value is simply a variance-standardized residual of this linear model with a slope of 1 (see Fig. 6 of Song et al. [11] for an illustration). The underlying assumption of this baseline model is that \( \log_2(Cy5) - \log_2(Cy3) \) is constant given GC content. Although this assumption may be sufficient for some samples, the channel differences of log-intensities may depend on the intensities themselves. For example, analyzing previously published array data [21], we found that the channel difference in one array is negative when \( \log_2(Cy3) \) and \( \log_2(Cy5) \) are small, but approaches 0 as \( \log_2(Cy3) \) and \( \log_2(Cy5) \) become larger (Figure 1 (a–c)). This variation justifies the use of a fully parameterized linear model: \( \log_2(Cy5) = b_0 + b_1 \times \log_2(Cy3) \) as the baseline model. Therefore, an improvement over the MA2C normalization would be to assume a linear relation between \( \log_2(Cy5) \) and \( \log_2(Cy3) \) and estimate both intercept and slope from data in a robust way, for example, using median regression. However, we found that the relation between \( \log_2(Cy5) \) and \( \log_2(Cy3) \) may be non-linear, and not fully captured by median regression (See Figure 1, and Sup. Figure 1(a–b), Sup. Figure 2(a–b) in Additional file 1). To accommodate non-linear intensity-dependent patterns, we normalized data by Lowess curve fitting conditioning on GC-content. The Lowess normalization is able to account for either linear or non-linear relation and it is robust to outliers. Specifically, given GC-content, let \( z_i = g(x_{1i}) \) be the Lowess fit (we fit Lowess curve by R function lowess), the normalized log ratio difference is calculated as

\[
d_i = \frac{x_{2i} - z_i}{M_i},
\]

where \( M_i \) is the median of \( x_{2i} - z_i \). We found this Lowess normalization better captured the relationship between signal intensities (See Figure 1(a–c), and Sup. Figure 1(a–b), Sup. Figure 2(a–b) in Additional file 1). Although Lowess normalization has been applied to gene expression microarray data [22-24], to the best of our knowledge, this is its first application to ChIP-chip data.

Mixture models of ChIP-chip data

ChIP-chip data analysis represents a combined mixture model problem. Observed probe-level data are sampled from the mixture distribution of background signals (null distribution) and ChIP-enriched signals (alternative distribution). In addition, peaks can be detected by moving windows of various lengths. Therefore there are two mixture model problems: one at the probe level and one at
Figure 1

**GC-dependent normalization of one sample.** Scatter plots of log intensities of Cy3 and Cy5 signals (from array GSM254806) based on the number GC base pairs of each 50-mer probe: 15 (a), 20 (b) or 30 (c). Density plots of raw data (d), MA2C (robust, C = 2) normalized data (e) and Lowess normalized data (f). Three curves are overlaid on figures (a)–(c). The blue line depicts the baseline model of MA2C normalization. The red line is fitted by median regression and the yellow line is the Lowess fit. In figures (d)–(f), vertical lines indicate mode and median of all probes. In raw and MA2C normalized data, the mode is bigger than median (d, e), indicating a heavier tail on the left. This unexpected feature usually indicates a problematic array or insufficient normalization.
the window level. Let \( f_0(x) \) and \( f_1(x) \) be the probe level density functions of the null and alternative distributions respectively, and let \( \pi_0 \) and \( \pi_1 \) be the corresponding mixture proportions respectively, then the observed probe-level data follows the mixture distribution

\[
\text{Probe-level analysis}
\]

\[
f_{\text{obs}}(x) = \pi_0 f_0(x) + \pi_1 f_1(x).
\]

We define a window as a fixed length region around a probe. Let the window-level density functions for null and alternative distributions be \( g_0(X) \) and \( g_1(X) \) respectively. We use \( X \) to denote the window level signal strength to distinguish it from the probe level signal strength \( x \). Let the corresponding mixture proportions be \( \kappa_0 \) and \( \kappa_1 \), then the observed window-level data follows mixture distribution

\[
g_{\text{obs}}(X) = \kappa_0 g_0(X) + \kappa_1 g_1(X).
\]

Let \( \mu_0 \) be the center of the null distribution, which is approximately the \( \pi_0/2 \) percentile of the whole distribution assuming that the vast majority of the signals smaller than \( \mu_0 \) arise from the null distribution. This is a reasonable assumption because most ChIP-enriched signals are higher than the majority of the background signals. Then in order to estimate \( \pi_0 \), we just need to estimate \( \mu_0 \). Based on the assumption that the null distribution is symmetric with center \( \mu_0 \) it is reasonable to assume that \( \mu_0 \) is the mode of the entire distribution, or one of the two modes if the ChIP-enriched signals also form a mode [25]. Therefore, in order to estimate \( \mu_0 \) we identify the mode(s) of the observed density \( f_{\text{obs}}(x) = \pi_0 f_0(x) + \pi_1 f_1(x) \)

We first rounded all the probe level signals to a given precision, for example, 0.01 or 0.001 to facilitate subsequent computation. The precision is chosen so that little or no information is lost. We estimate the signal density function by kernel method (R function density with normal kernel) [26,27]. If the estimated density function has two or more modes, we refer to the highest one as the major mode and the others as minor modes. For simplicity, if there is only one mode, we also refer to it as the major mode. A mode cannot be \( \mu_0 \) if it is bigger than the overall median, otherwise

\[
\pi_0 = 2P(x < \mu_0) > 1.
\]

Specifically, we estimate \( \mu_0 \) based on the following procedure.

1. If the major mode is smaller than the overall median, we take it as \( \mu_0 \).

2. If the major mode is bigger than the overall median and there is one and only one minor mode in 20th – 50th percentile of the observed signal (we chose this range for robustness, as explained below), we take the minor mode as \( \mu_0 \).

3. In all the other situations, we make a conservative estimation of the mode location of the null distribution. Specifically, we iterate all the signal strengths within 20th – 50th percentile (again, we chose this range for robustness, as explained below) and choose the greatest one so that the estimated null distribution is below the overall distribution, i.e., \( \pi_0 f_0(x) \leq f_{\text{obs}}(x) \). In practice, if such a conservative estimation has to be made, the resulting lfdr is an upper bound instead of an unbiased estimation of actual lfdr.
The major mode can be simply identified as the point with the highest density estimation. The minor mode can be identified as the point where the corresponding 1st derivative of the density function is 0 and the 2nd derivative is negative. We estimate the 1st and 2nd derivatives of the density function by Savitzky-Golay smoothing filters [28-30]. Because there are fewer observations at the tails of a density curve, the kernel estimations there may have bigger variations. This variation could result in "small" modes at the tails that happen by chance. In order to avoid these potentially artifactual modes, we assume that the proportion of null signals is between 40% and 100%. This range is wide enough to accommodate the vast majority of the ChIP experiments. For experiments with even smaller proportions of null signals, pattern reorganization methods that capture ChIP-enriched signals in segments may be more appropriate [31].

After identifying the mode of the null distribution (μ0), hence πν, we take all the data points smaller than μν, denoted as D1, all the data points equal to μν, denoted as D2, and all the data points generated by flipping D1 around μν, denoted as D3, merge them together (i.e., D = {D1, D2, D3}) to estimate the null distribution f0(x) by kernel method (R function density with normal kernel) [26,27]. Finally the probe level lfdr, i.e., the posterior probability that one probe level signal arises from f0(x) is

\[
lfdr_p(x) = p_0(x) = \frac{\pi_0 f_0(x)}{\pi_0 f_0(x) + \pi f_1(x)},
\]

where \( p_0(x) \) indicates the probability that \( x \) is from the null distribution. In practice, kernel estimation of density functions may be unreliable at the tail area, due to limited number of observations. As a result, the lfdr estimates fluctuate. To circumvent this problem, we order those \( x \) where the lfdr is evaluated in ascending order \( x_{(1)} \leq x_{(2)} \leq \ldots \leq x_{(m)} \) and update \( p_0(x_{(i)}) \) by

\[
p_0(x_{(i)}) = \min(p_0(x_{(i)}), p_0(x_{(i-1)})), \quad i = 2, 3, \ldots, m
\]

Therefore the estimation of \( p_0(x) \) is smoothed and decreases or remain the same as \( x \) increases. A similar strategy has been used to define q-value from FDR estimates[32].

**Window-level analysis**

The window-level signal strength \( X \), which can be defined as mean or median (or other robust estimations, for example, those used in [11]), is a function of window size and the probe-level signals within the window. In this study, we assume the window size is pre-determined. Let the probe-level signals within one window be \( x_1, x_2, \ldots, x_n \), we calculate \( X \) as

\[
X = \frac{\bar{x} - \mu_0}{\sigma(\bar{x})},
\]

where \( \bar{x} \) is the average of probe-level signals and \( \sigma(\bar{x}) \) is the standard error of \( \bar{x} \) under null distribution. In other words, \( X \) measures the distance between \( \bar{x} \) and \( \mu_0 \), in terms of the standard error \( \sigma(\bar{x}) \), which is generally bigger than \( \sigma(x_i)/\sqrt{n} \) because there are auto-correlations between nearby probes even for background signals. We estimate \( \sigma(\bar{x}) \) by

\[
\sigma(\bar{x}) = \frac{1}{n} \sqrt{\text{var}(\sum_{i=1}^{n} x_i)} = \frac{1}{n} \sqrt{\text{var}(x) \left( n + 2 \sum_{1 \leq i < j \leq n} \text{corr}(x_i, x_j) \right)}
\]

Because we estimate \( \sigma(\bar{x}) \) under null distribution, \( \sigma(\bar{x}) \) depends only on the number of probes in the window and the distances between them, but not the particular probe level signals. This estimation in equation (4) has the same form as the one used by Zheng et al. [12]. However, based on the underlying assumption that the vast majority of the signals are from the null distribution, Zheng et al. used all the data below a threshold to estimate both \( \text{var}(x) \) and \( \text{corr}(x_i, x_j) \). Specifically, we estimate \( \text{var}(x) \) using the data \( D = \{D1, D2, D3\} \) and estimate \( \text{corr}(x_i, x_j) \) as follows. We model the signal strength at probe \( j \) by

\[
x_j = \omega_x x_i + e_{ij},
\]

where \( \omega_x \) is the probability that there is no break up of the DNA sequence between probe \( i \) and \( j \), and \( e_{ij} \) indicates the signal strength at probe \( j \) due to the DNA segments not harboring probe \( i \). \( x_i \) and \( x_j \) are measured based on a large number of sequence segments bound to the probe \( i \) and \( j \), respectively. Equation (5) can be understood as a summation of the contributions from all the sequence segments captured by probe \( j \) from an expectation perspective. Since \( e_{ij} \) is independent with \( x_r \),

\[
\text{cov}(x_i, x_j) = \text{cov}(x_i, \omega_x x_i + e_{ij}) = \omega_x \text{var}(x_i).
\]

Because we are modeling the correlation structures in the background signals, \( \text{var}(x_i) = \text{var}(x_j) = \text{var}(x) \), hence
corr(x_i, x_j) = ω_{ij}. In order to estimate ω_{ij}, we modeled the sonication process by Poisson point process [12]. Suppose, on average there is one break up of DNA sequence per k bp, the incident rate in the Poisson process is λ = 1/k, and ω_{ij} = exp(-λd_{ij}), where d_{ij} indicates the distance between probe i and j. Therefore given the parameter λ (or equivalently k), we can estimate ω_{ij} hence corr(x_i, x_j), and then we can calculate the window-level statistics X. Usually, the parameter λ (or k) can be obtained from the experimental setting for the DNA sonication process. For sequencing studies, ω_{ij} can be simply estimated from the distributions of sequence fragment lengths [33].

Next, the window level mixture distribution g_{obs}(X) = \kappa_0g_0(X) + \kappa_1g_1(X) can be dissected similarly to the analysis of the probe level data. Finally, the window level lfdr, i.e., the posterior probability that one window-level statistics X is from the null distribution is

$$lfdr_X(X) \equiv q_0(X) = \frac{\kappa_0g_0(X)}{\kappa_0g_0(X) + \kappa_1g_1(X)},$$

(7)

where q_0(X) indicates the probability that X is from the null distribution. Similarly to the probe-level analysis, we smooth the lfdr by updating q_0(X_{(i)}) as

$$q_0(X_{(i)}) = \min(q_0(X_{(i)}), q_0(X_{(i-1)})).$$

Here X_{(1)} ≤ X_{(2)} ≤ ... ≤ X_{(n)} are the window-level signals where the lfdr are evaluated.

**Peak Identification**

After probe-level and window-level analyses, we identify peaks by the following steps. First, "peak windows" with elevated signal strengths are identified using a window-level lfdr cutoff, e.g., lfdr ≤ 0.20. Second, overlapped "peak windows" are separated into discrete peak regions. Third, each resulting peak region is evaluated by further restriction on the number of probes within it and the signal strengths of those probes. A typical rule could be "a peak region should harbor at least 5 probes", or "a peak region should harbor at least 3 probes with probe level lfdr ≤ 0.2". The third step is optional but recommended since "isolated peaks" composed of only one or two probes are unlikely to represent true sites of protein-DNA interactions. Similar rules have been used in other ChIP-chip data analysis methods [6,12].

**Results**

We compared the results of our peak detection strategy with other published algorithms using three datasets. We focused on two common conditions that were typically not evaluated during the development of the existing peak detection algorithms: the absence of experimental replicates and the presence of abundant peak regions.

**Spike-in Data**

We initially evaluated our method using the data set from a recent spike-in study [21]. In this benchmark study comparing ChIP-chip conditions, human genomic DNA was combined with defined cloned regions ("spike-ins") over a wide range of concentrations to reflect the enrichment ratios often observed in ChIP experiments. The use of an experimental spike-in data set allows definitive knowledge of the regions that are enriched. Although multiple tiling array designs were tested, since the current implementation of our normalization method is for two-color arrays, we analyzed the data generated from seven NimbleGen arrays. The original data in "pair" format, which includes signals from both Cy3 and Cy5 channels, were downloaded from NCBI GEO database. Four arrays (GEO sample accession number: GSM254930, GSM254971, GSM254972, GSM254973) were hybridized to DNA spiked with specific unamplified fragments. The other three arrays (GSM254805, GSM254806, GSM254807) were hybridized to DNA spiked with fragments that had been amplified. Each array harbors 385,149 probes spanning 44 ENCODE-selected regions[34]. 100 or 98 regions were spike-in with unamplified and amplified DNA, respectively, at various concentrations from 1.25 fold to more than 100 fold. A complete description of these data can be found in Johnson et al. [21].

In the original data, the peak regions were sparse (covering ~0.2% of the total number of probes). We simulated data with increasingly abundant peak regions by replacing the signals from non-spike-in regions with the signals from spike-in regions. To better mimic the original data and more faithfully replicate the flanking contexts, we replicated each spike-in region (450–550 bp) including 500 bp on either side (or to the boundaries of the corresponding ENCODE regions) as a unit, which we refer to as a peak-containing region. Lengths of such peak-containing regions vary from 1,172 bp to 1,550 bp, with median of 1,496 bp. We split the remaining non-peak-containing regions into 18,531 segments of 1,600 bp. We then used the peak-containing regions to replace (fractions of the same lengths of) randomly selected non-peak-containing segments. In the first augmented data set, we replicated each peak-containing region 20 times, resulting in 2,100/2,058 peak-containing regions (covering ~4.3% of the total number of probes) in the unamplified/amplified DNA samples, respectively. In the second augmented data set, we replicated each peak-containing region 50 times, resulting in 5,100/4,998 peak-containing regions (covering ~10.2% of the total number of probes) in the unamplified/amplified DNA samples, respectively.

**Analysis of Spike-in Data**

Using the native and augmented spike-in data, we compared the efficacy of our peak detection method, which we named Mixer, with three other methods: MA2C, TileMap,
Log2 transformed data were pre-normalized using the We employed CisGenome for TileMap calculation. Tested Mixer with data normalized by both methods. The difference between Lowess and MA2C normalization, we significantly change the results. In order to demonstrate the substitution of values from 500 bp to 1500 bp did not significantly change the results. In order to demonstrate the difference between Lowess and MA2C normalization, we tested Mixer with data normalized by both methods.

We employed CisGenome for TileMap calculation. Log2 transformed data were pre-normalized using the quantile normalization option in CisGenome. TileMap summarizes window-level signals by either moving average or HMM. The significance of each peak is measured by an lfdr estimated from unbalanced mixture subtraction (UMS). We used HMM because it yields superior results in an lfdr cutoff. Two parameters (p and q) must be provided to UMS to enable selection of probes (with percentiles greater than 100p-th and less than 100q-th) from the overall distribution to construct the null/alternative distributions. We used either the default values (p = 0.01 and q = 0.05) or adjusted values based on the knowledge of true proportion of spike-in signals. Specifically, we set p = 0.002 and q = 0.02 for the original data with ~0.2% of spike-in probes; p = 0.03 and q = 0.08 when ~4.3% of the probes are from spike-ins; p = 0.08 and q = 0.13 when ~10.2% of the probes are from spike-ins. The R package R/HGMM was used for HGMM calculation. HGMM can take into account a distribution of peak sizes. We generated this distribution based on the actual lengths of the spike-in regions. In most experiments, however, this information can only be estimated. Raw data (PM measure from pair file) were log2 transformed and normalized using the preprocess function of R/HGMM before applying the HGMM function.

We examined the influence of the proportion of null signals on Mixer’s performance. Figure 2 shows the estimated densities of probe and window-level signals from the original and two simulated datasets from one array. As the number of spike-in regions increases, the right tail of the window-level signal density becomes heavier. The increased signal density enhances accuracy and robustness to dissect the mixture distribution. Similar patterns were also observed for other arrays.

We then evaluated Mixer, MA2C, TileMap and HGMM using the spike-in data. First, given a fixed cutoff of either FDR ≤ 0.20 (for MA2C) or lfdr ≤ 0.20 (for the other methods), we compared the power and actual FDR of these methods (Tables 1, 2 and 3). The discovery of a peak region was counted as a true discovery (or a true positive) if its center was within a spike-in region; otherwise it was counted as a false discovery. Although an alternative comparison would examine the top K peaks identified by different methods, we based our comparison on fixed lfdr/
FDR. This approach is more relevant since the number of binding sites is typically unknown.

We compared the results of Mixer after data normalization by Lowess or by MA2C. For the original data when the spike-in regions are sparse, in general, Mixer performs much better with Lowess normalization than with MA2C normalization. Mixer with MA2C normalization often includes many false discoveries resulting in a high FDR (see Table 1). As spike-in regions become more abundant, the normalization method makes less difference (Table 2, 3). Dissection of the mixture distribution becomes easier with additional data to estimate the alternative distribution, which may overcome the differences attributable to the normalization methods.

We then compared the performance of the peak detection algorithms on the original and augmented data sets. HGMM was computationally intensive, requiring more than 10 hours to analyze one array. In contrast, the other methods we tested completed the analysis of a single array in less than 10 minutes. With the original data, (i.e., no replicates and a small proportion of spike-in regions), HGMM failed for four arrays due to errors in numerical optimization. Although the use of initial values other than the defaults may avoid such errors, we did not explore this due to the high computational cost. In the augmented data sets (with a larger proportion of spike-in regions), HGMM did not fail for any array. However, HGMM was often over-conservative missing 30–50% of spike-in regions (Table 2, 3).

At the default parameters of p = 0.01 and q = 0.05 (i.e. using the top 1% of the data to estimate alternative distribution and 95% of the data to estimate null distribution), TileMap was over-conservative and had limited power, especially when the proportion of spike-in regions is high. TileMap performed much better when provided appropriate values for parameters p and q based on the true proportion of alternative distribution (Tables 1, 2 and 3). However, in actual applications, the alternative distribution is typically unknown. For example, for amplified DNA samples when there are 4998 (~10.2%) spike-in regions, with injecting smaller than 0.2, TileMap identifies ~70–80% of the spike-in regions if p = 0.08 and q = 0.13.

### Table 2: Comparison of different methods for the simulated data set with 2,100/2,058 spike-in regions for unamplified/amplified samples, respectively

| Sample     | Mixer (Lowess) D | FDR | Mixer (MA2C) D | FDR | MA2C D | FDR | TileMap (p = 0.01, q = 0.05) D | FDR | TileMap (p = 0.03, q = 0.08) D | FDR | HGMM D | FDR |
|------------|------------------|-----|----------------|-----|--------|-----|-------------------------------|-----|-------------------------------|-----|--------|-----|
| GSM254930  | 2159             | 0.23| 1694           | 0.17| 2219   | 0.28| 1475                         | 0.004| 1619                         | 0.004| 1605   | 0.03|
| GSM254971  | 1965             | 0.21| 2033           | 0.22| 2187   | 0.30| 1395                         | 0.003| 1578                         | 0.006| 1577   | 0.03|
| GSM254972  | 2015             | 0.19| 2226           | 0.27| 2151   | 0.27| 1553                         | 0.003| 1713                         | 0.009| 1553   | 0.03|
| GSM254973  | 1575             | 0.14| 1929           | 0.19| 2094   | 0.28| 1334                         | 0.004| 1504                         | 0.008| 1520   | 0.02|
| GSM254805  | 1982             | 0.30| 1764           | 0.24| 1671   | 0.27| 1034                         | 0.013| 1140                         | 0.019| 939    | 0.03|
| GSM254806  | 2180             | 0.27| 2344           | 0.33| 1910   | 0.23| 1404                         | 0.008| 1687                         | 0.027| 1372   | 0.03|
| GSM254807  | 1495             | 0.14| 1926           | 0.18| 2034   | 0.27| 1486                         | 0.003| 1655                         | 0.009| 1519   | 0.03|

See main text for the simulation methods. Approximately 4.3% of the probes are from spike-in regions.

### Table 3: Comparison of different methods for the simulated data set with 5,100/4,998 spike-in regions for unamplified/amplified samples, respectively

| Sample     | Mixer (Lowess) D | FDR | Mixer (MA2C) D | FDR | MA2C D | FDR | TileMap (p = 0.01, q = 0.05) D | FDR | TileMap (p = 0.03, q = 0.08) D | FDR | HGMM D | FDR |
|------------|------------------|-----|----------------|-----|--------|-----|-------------------------------|-----|-------------------------------|-----|--------|-----|
| GSM254930  | 4359             | 0.16| 5753           | 0.28| 4829   | 0.19| 2775                         | 0.001| 3872                         | 0.003| 3707   | 0.02|
| GSM254971  | 4969             | 0.23| 5110           | 0.23| 4697   | 0.22| 2758                         | 0.001| 3682                         | 0.005| 3615   | 0.02|
| GSM254972  | 5135             | 0.22| 3957           | 0.19| 4738   | 0.19| 2978                         | 0.001| 4114                         | 0.011| 3558   | 0.03|
| GSM254973  | 4714             | 0.18| 4795           | 0.20| 4560   | 0.20| 2695                         | 0.001| 3534                         | 0.003| 3493   | 0.02|
| GSM254805  | 4537             | 0.25| 4784           | 0.27| 3860   | 0.22| 1946                         | 0.003| 2744                         | 0.022| 2237   | 0.03|
| GSM254806  | 4878             | 0.21| 5826           | 0.32| 4284   | 0.17| 2672                         | 0.0004| 3924                         | 0.022| 3085   | 0.03|
| GSM254807  | 4957             | 0.21| 5157           | 0.24| 4569   | 0.20| 2487                         | 0.0004| 3802                         | 0.003| 3508   | 0.02|

See main text for the simulation methods. About 10.2% of the probes are from spike-in regions.
but only ~60% of the spike-in regions with the default parameters, p = 0.01 and q = 0.05.

Both Mixer and MA2C have better power than TileMap and HGMM. As shown in Tables 1, 2 and 3, Mixer has lower FDR than MA2C for original data with sparse spike-in regions and has slightly better power than MA2C with abundant spike-in regions. However, a straightforward comparison between Mixer and MA2C is confounded by the fact that, unlike other methods, MA2C provides FDR estimates rather than lfdr estimates. Since lfdr and FDR cutoffs are not directly comparable, we employed ROC (receiver operating characteristic)-like curve to compare Mixer and MA2C (Figure 3). Unlike a typical ROC curve, these ROC-like curves plot (number of true positives)/(number of spike-in clones) on the Y-axis against (number of false positives)/(number of spike-in clones) on the X-axis in order to accommodate the large number of true negatives in ChIP-chip data, [21]. To simplify the plots, we averaged across samples for amplified/unamplified DNA respectively. FDR and lfdr cutoffs were set between 0.01 to 0.50. Mixer outperformed MA2C when the spike-in regions were abundant (Figure 3). However, when the spike-in regions were sparse, MA2C outperformed Mixer if an appropriate FDR cutoff was chosen.

**Analysis of CTCF-binding Data**

We also evaluated our method using the ChIP-chip data from a study of the zinc finger insulator protein CTCF (CCCTC-binding factor) in IMR90 human fibroblast cells[36]. This dataset includes 38 arrays each with about 38,500 50-mer probes tiling the non-repetitive sequences of the human genome in 100 bp resolution. The original pair data (pair data includes the intensities for two channels, Cy5 (CTCF ChIP sample) and Cy3 (input genomic DNA)) were obtained from the Ren laboratory website [http://bioinformatics-renlab.ucsd.edu/rentrac/wiki/CTCF_Project](http://bioinformatics-renlab.ucsd.edu/rentrac/wiki/CTCF_Project). Each of the 38 arrays was analyzed separately. The results of different peak-finding algorithms were compared to the results of an independent ChIP-seq based analysis that identified 20,262 CTCF binding sites in human CD4+ T cells[37]. HGMM was not evaluated due to its high computational cost. Model parameters were similar to those described above. For TileMap, window-level signals were summarized by HMM, and the lfdr of each peak region was estimated from unbalanced mixture subtraction (UMS) with default parameters (p = 0.01 and q = 0.05). For MA2C, default options were used to normalize data (robust with C = 2) and summary window-level signals (by median). In Mixer, the average DNA fragment length was set to 1500 bp (T. Kim, personal communication).

Although true CTCF binding sites are unknown, to permit a systematic evaluation of the various peak detection strategies, we compared the peak regions identified by each method with the 20,262 CTCF binding sites reported from a ChIP-seq study by Barski et al. [37]. Since experimental variation will likely result in differences between ChIP-chip and ChIP-seq data, ChIP-seq data serves as a common and independent source for comparison, rather than a perfect standard. A common site was called when the center of the ChIP-chip peak was located within the ChIP-seq peak. Without the knowledge of all true CTCF binding sites we are unable to compare FDRs, as we had done for the spike-in data. Therefore, we examined a fixed number of high confidence peak regions and compared the proportion of overlap. Specifically, we examined the overlap between the ChIP-seq reported sites and 5,000, 10,000, or 20,000 peak regions with the highest confidence (lowest FDR or lfdr) identified by each peak detection algorithm. Peaks identified by Mixer consistently demonstrate a greater overlap with ChIP-seq peaks than those identified by MA2C and TileMap (Table 4).

**Analysis of FAIRE Data**

We also compared Mixer, MA2C, and TileMap on array data produced by hybridization of DNA enriched by Formaldehyde-Assisted Isolation of Regulator Elements (FAIRE)[19,38]. Briefly, FAIRE identifies open chromatin
regions using organic extraction of formaldehyde crosslinked chromatin. DNA recovered in the aqueous phase is fluorescently labeled and hybridized to arrays. FAIRE typifies the data from epigenetic studies where relevant features are expected to be abundant genome-wide. FAIRE-chip thus provides an appropriate application for Mixer. For this analysis, FAIRE was performed on chromatin isolated from human foreskin fibroblasts and hybridized to a 1% ENCODE tiling array at 38-bp resolution [19].

Four arrays hybridized with FAIRE-selected chromatin were normalized individually. After averaging identical probes across the arrays Mixer was applied. MA2C and TileMap were run using their default options for replicate analysis. Since hypersensitivity to endonucleases is a standard method to identify open chromatin regions, we compared the results with 3,150 open chromatin regions identified by DNase I hypersensitivity-chip in lymphoblastoid cell lines [39,40]. The FAIRE regions identified by each of the three methods share ~40% overlap with DNase sites, indicating similar specificities for the various methods. Since different techniques and different cell lines are compared, this overlap likely represents an underestimate of specificity. However, Mixer offers increased sensitivity as it identifies more peaks (especially those peaks with relatively weaker signals) at the same specificity. At a local FDR (for Mixer or TileMap) or FDR (for MA2C) cutoff of 0.2, Mixer identifies 1137 peaks (42.1% overlap with DNase hypersensitivity sites) whereas MA2C identifies 750 sites (43.3% overlap), and TileMap identifies 1114 sites (40.3% overlap). At a local FDR/FDR cutoff of 0.5, Mixer identifies 1559 peaks (40.3% overlap); MA2C identifies 1175 (39.7% overlap); and TileMap identifies 1202 (39.7% overlap).

A local FDR less than 0.5 is a much more stringent cutoff than FDR less than 0.5. The former means that the highest FDR for any one of the peak regions is 0.5, whereas the latter indicates that the average FDR is 0.5. Averaging the local FDR less than 0.5 results in an estimated FDR for Mixer or TileMap of less than 0.15. Because it uses a less stringent FDR cutoff, MA2C is expected to identify more peaks. The actual identification of fewer peaks by MA2C suggests the introduction of bias by MA2C normalization. To test this hypothesis, we supplied MA2C with Mixer-normalized data and observed a significant improvement of its sensitivity; 1,483 peaks (~40% overlap DNase sites) were identified at FDR less than 0.20, still fewer than the 1,559 peaks identified by Mixer with an estimated FDR of less than 0.15.

Discussion

We have developed a mixture model approach to dissect the mixture distributions of ChiP-chip data: the null distribution (corresponding to the background signals) and the alternative distribution (corresponding to the ChiP-enriched signals), at both probe and window levels. This approach builds on the method of Buck et al. [5] to estimate null (background) distribution of ChiP-chip signal data and utilizes the Poisson point process assumption proposed by Zheng et al. [12] to model DNA fragmentation. An advance over most existing peak detection strategies, our approach is less dependent on key assumptions and prior knowledge. Our method takes into account the auto-correlation structure of nearby probes, permits a relatively large proportion of ChiP-enriched signals in the mixture distribution, and does not require cross-array normalization. After dissecting the mixture distribution, both probe-level and window-level lfdrs are provided to evaluate the statistical significance of the identified peaks. Using three data set representing widely divergent experimental conditions, we demonstrated that our method performs comparably or better than several representative existing methods, especially when the true peak regions are abundant. Our method also applies Lowess fit data normalization to capture the non-linear relationship between log(Cy3) and log(Cy5) signals from two-color arrays. Mixer emphasizes the identification of abundant short peak regions rather than extended binding regions. We have recently developed a different method to identify broad signal patterns [31].

Despite Mixer’s advances, areas for improved performance remain. We smooth the lfdr estimate so that it decreases as probe-level/window-level signals increase. This smoothing strategy avoids major fluctuations of lfdr estimates when observations are limited (e.g. in tail
areas). A similar strategy has been used to define q-value from FDR estimates [32]. However, smoothing may lead to under-estimates of the lfdr, especially for small lfdr. To improve the lfdr estimates, both signal strength and signal pattern (for example the “triangle” pattern used by Zheng et al. [12]) could be incorporated, a strategy we are currently evaluating.

The use of high throughput sequencing based chromatin identification (ChIP-seq) has become increasingly common. However, determination of sufficient sequencing depth remains a significant challenge, especially for abundant epigenetic events. ChIP-chip remains a valuable method for pilot experiments and to cross validate results, a particularly appropriate application of Mixer. Mixer could also be adapted to dissect mixture distributions from sequencing data. Tag counts derived from unfractionated input control could model a null distribution [41]. We are currently testing this approach.

Conclusion
In summary, we have developed a method that combines improved data normalization and peak detection for ChIP-chip studies. Mixer offers several advantages including lfdr determination and enhanced performance when peak regions are abundant, a common scenario for genome-wide studies of chromatin organization and epigenetics [4,19,20].

Availability and requirements
We have implemented our method in an R package mixer, which can be freely downloaded from http://wwwbios.unc.edu/~wsun/software/mixer.htm. The source code can be redistributed and/or modified under the terms of the GNU General Public License as published by the Free Software Foundation.

Authors’ contributions
All authors have read and approved the final manuscript. WS, IJD and MJB conceived this study. WS implemented the methods and analyzed the data. WS, IJD, MJB and MP wrote the paper.

Additional material

Additional File 1
Supplementary Materials for “Improved ChIP-chip analysis by mixture model approach”. Supplementary results demonstrating different data normalization methods.

Click here for file [http://www.biomedcentral.com/content supplementary/1471-2105-10-173-S1.pdf]

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