Technical Note

A Hilbert-based method for processing respiratory timeseries

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ABSTRACT

In this technical note, we introduce a new method for estimating changes in respiratory volume per unit time (RVT) from respiratory bellows recordings. By using techniques from the electrophysiological literature, in particular the Hilbert transform, we show how we can better characterise breathing rhythms, with the goal of improving physiological noise correction in functional magnetic resonance imaging (fMRI). Specifically, our approach leads to a representation with higher time resolution and better captures atypical breathing events than current peak-based RVT estimators. Finally, we demonstrate that this leads to an increase in the amount of respiration-related variance removed from fMRI data when used as part of a typical preprocessing pipeline.

Our implementation is publicly available as part of the PhysIO package, which is distributed as part of the open-source TAPAS toolbox (https://translationalneuromodeling.org/tapas).

1. Introduction

There has been much recent interest in the impact of global artefacts on fMRI data (Burgess et al., 2016; Cicic et al., 2017; Liu et al., 2018; Murphy and Fox, 2017; Satterthwaite et al., 2013; Schölvinck et al., 2010), with many studies finding a link between physiological processes—particularly breathing—and these global signals (Byrge and Kennedy, 2018; Power et al., 2017a; 2020; 2019; 2017b). However, despite the fact that models for these physiological processes and their impact on fMRI are well established (Birn et al., 2006; 2008; Chang et al., 2009; Chang and Glover, 2009; Glover et al., 2000; Murphy et al., 2013), much recent work has focused on improved data-driven methods for artefact removal (Aquino et al., 2020; Glasser et al., 2018; Power et al., 2018). This is likely for two reasons. Firstly, even though physiologically-derived confounds have the advantage that they have a much greater a priori validity if one is concerned about mistakenly removing neural signal, there is a cost: they require extra data to be collected, inspected, and analysed (Glasser et al., 2018; 2019; Power, 2019; Power et al., 2020). Secondly, as Power et al. (2020) recently demonstrated, these fMRI artefacts typically arise in the context of unusual breathing events—very deep breaths, apnoeas, etc.—that are by definition hard for algorithms designed with “normal” tidal breathing in mind to properly detect and characterise.

What we introduce here is a method, inspired by work from the electrophysiological literature, that seeks to address both of these concerns in the context of preprocessing recordings from respiratory bellows. We introduce a new estimator for respiratory volume per unit time (RVT) that does not require peak detection—a process that often requires post hoc manual intervention—and demonstrate that this accurately captures atypical breathing events. Empirically, when used as a confound regressor, this also removes more variance from fMRI data compared to a peak-based RVT estimator. Finally, for a much more detailed discussion of both breathing and breathing-related issues pertaining to fMRI than space affords in this technical note, we refer the reader to the excellent overview in Power et al. (2020).

1.1. Respiratory models and fMRI denoising

In the context of removing global fMRI confounds, the aim of the most commonly utilised breathing-related metric, RVT (Birn et al., 2006), is to collapse simple measurements of breathing—typically from peripheral physiological recordings, such as respiratory bellows—down to a metric that will correlate over time with the pressures of blood gases (e.g. pCO2 and pO2). There are two components to this: an increase in breathing rate or an increase in breathing depth will tend to, for example...

This is distinct from and complementary to RETROICOR, which seeks to correct for instantaneous artefacts caused by the interaction between breathing-related motions and field changes, and cardiac pulsatility (Glover et al., 2000).
ple, decrease $p\text{CO}_2$. As such, RVT is simply the product of respiratory volume (RV) and breathing rate.

The other component to these fMRI-based models is the mapping from RVT to the blood-oxygen-level-dependent (BOLD) contrast. Any changes in the pressures of blood gases impact on key constituents of the BOLD contrast, such as blood volume (via vasodilation) (Gauthier and Fan, 2019). To account for these physiological processes and the inherent delays in the circulatory system, a respiratory response function (RRF) (Birn et al., 2008) is used to map from RVT to the BOLD signal. This is directly analogous to the haemodynamic response function which describes the mapping from neural activity to BOLD, and similar physiological models exist for changes in heart rate (Chang et al., 2009).

1.2. RVT estimators

As we describe in more detail later, current methods typically characterise the recordings from respiratory bellows via peak detection, but this has issues in terms of both robustness and temporal resolution. Here, we use a decomposition based on the Hilbert transform to characterise the respiratory recordings; this is a technique that has been more widely used in the context of characterising complex oscillatory waveforms from electrophysiological data (Brookes et al., 2011; Cole and Voytek, 2017; Engel et al., 2013; Hipp et al., 2012; Luckhoo et al., 2012; Nguyen et al., 2019; Voytek et al., 2013). The crucial link is that the quantities that we need to define RVT, breathing depth and rate, are simply the amplitude and (instantaneous) frequency of the breathing-related oscillation in the bellows recordings.

By way of contrast, RVT is typically estimated via peak detection, as described by Birn et al. (2006). Firstly, one detects points of maximum inhalation and exhalation (i.e. peaks and troughs in the respiratory waveform). Given these, respiratory volume is defined as the difference in belt positions between peaks and troughs, and breathing rate is the reciprocal of the time between successive peaks (with the relevant quantities linearly interpolated as necessary). However, peak detection is not robust to noisy recordings and fundamentally constrains the temporal resolution of the model to the observed breath durations. Taken together, these two issues are why RVT-based measures can often “miss” deep breaths (Power et al., 2020).

As such, alternatives to RVT with better estimability have been proposed. For example, Chang et al. (2009) define a simple alternative to peak-based methods by simply taking the standard deviation of the respiratory signal in a small window around the timepoint of interest. While this has some of the purported benefits of our method, namely that it “does not rely on the accuracy of peak detection required for breath-to-breath computations”, it does not directly capture the effects of changes in breathing rate. Similarly, Power et al. (2018) propose what is essentially a hybrid of our approach and the above, by calculating the standard deviation of the respiratory envelope in a small window. Again, this is a peak-free method, but does not permit a clean dissociation of breathing depth and rate.

While the above two measures are more robust, they lack the direct physiological interpretability with regard to blood gas pressures that RVT offers. Therefore, our aim is to estimate RVT itself, and all comparisons in this technical note are with a peak-based RVT estimator. We use the implementation in the PhysIO package (Kasper et al., 2017), and this is publicly available as part of the TAPAS toolbox (https://translationalneuromodeling.org/tapas).

2. Methodology

2.1. Properties of the Hilbert transform and analytic signal

The Hilbert transform is central to our method as it allows us to derive an alternative representation of the respiratory recordings. For a given real-valued signal, $s(t)$, we can define a unique analytic signal
\[ s_a(t) = s(t) + jH[s(t)] = s(t)e^{j\phi(t)} \]

Where the second line is simply a rearrangement of the first into polar coordinates. Much more detail on the properties of this approach can be found in, for example, Boashash (1992a); Huang et al. (2009).

The important aspect of this representation for the current work is the way we have split our signal into two components: an instantaneous magnitude, $s_m(t)$, and an instantaneous phase, $\phi(t)$. We can do one final rearrangement to make this more explicit:
\[ s(t) = \Re\left[s_m(t)e^{j\phi(t)}\right] = \Re\left[s_m(t)e^{j\phi(t)}\right] = s_m(t)\cos(\phi(t)) \]

We plot this decomposition of a signal recorded from respiratory bellows in Fig. 1. Note that we use the term amplitude envelope interchangeably with magnitude, as this is the common description in the electrophysiological literature.

Finally, these two terms are exactly what we need to calculate RVT. The respiratory volume (i.e. the difference between successive peaks and troughs) is simply twice the signal amplitude, $s_m(t)$. Similarly, the breathing rate is the instantaneous frequency, $s_f(t)$, which is the temporal derivative of the instantaneous phase:
\[ s_f(t) = \frac{1}{2\pi} \frac{d\phi(t)}{dt} \]

As a last step, we apply a low pass filter to these quantities to remove within-cycle fluctuations. The breathing rhythm is not sinusoidal, so the above terms will contain some high-frequency content that represents within-breath modulations of the waveform shape. Here, as in a typical preprocessing pipeline, RVT is convolved with the RRF—which is itself an aggressive low-pass filter—so this is not strictly necessary for fMRI denoising, but we do so because it affords more intuitive visualisations of the respiratory decomposition.

2.2. Practical considerations and algorithmic approach

While the Hilbert transform is theoretically well suited to the problem at hand, deriving the necessary quantities can present a formidable practical challenge (Boashash, 1992b; Huang et al., 1998). Noise—or, more specifically, multiple local extrema that are not part of zero-centred oscillations—can cause the instantaneous frequency to become negative (Huang et al., 2009). Correcting for these effects is a core part of the empirical mode decomposition (EMD) (Huang et al., 1998), whereby a single signal is decomposed into multiple modes, each of which is a monocomponent signal that admits a “well behaved” decomposition into amplitude and phase terms. However, this is a data-driven approach that does not guarantee that the main breathing rhythm will be represented by a single mode.

As such, while we could take an EMD-based approach here, we do something simpler. Rather than decomposing the signal and then selecting the breathing-related modes post hoc, we assume that we can make an approximately monocomponent signal by appropriately filtering the breathing signal. In practice, this requires a few rounds of iterative refinement, and the overall algorithm is detailed below. To aid the interpretation of the filtering operations below, note that the “normal”

\[ \text{Hilbert transform} \]

2 An analytic signal has no negative frequency components, and is often expressed in terms of instantaneous amplitude and phase. The Hilbert transform is equivalent to what is perhaps the conceptually simplest frequency-domain method for generating this (setting amplitudes of negative frequencies to zero, and doubling those for positive frequencies).

3 For example, compare the double peak in the envelope at 530 s in Fig. 1—caused by the square top to the waveform—with the filtered respiratory volume in Panel (b) of Fig. 3.
breathing rate in adults—from both subjects resting in a supine position and undergoing MRI scanning—is approximately 0.25 Hz (Power et al., 2019; Tobin et al., 1983).

Our proposed algorithm for RVT estimation based on the Hilbert transform consists of the following general steps:

1. PhysIO preprocessing: Remove low frequency drifts (less than 0.01 Hz) from the breathing signal, and remove high-frequency noise above 2.0 Hz. This version of the breathing signal is used for both RETROICOR and the peak-based RVT estimate in the physiological pipelines used in the Results section. This is the raw trace shown in Panel (a) of Fig. 3.

2. Lowpass filter the data again to more aggressively remove high-frequency noise above 0.75 Hz. This is the raw trace shown in Fig. 1. The combined frequency response of these first two filtering steps is shown in Supplementary Figure S2.

3. Decompose the signal into magnitude and phase components via the Hilbert transform.

4. Linearly interpolate any periods where the phase timecourse decreases, using the procedure in Fig. 2, to remove any artifactual negative frequencies. Reconstruct the oscillatory portion of the signal, \( \cos(\phi(t)) \), and lowpass filter at 0.75 Hz to remove any resulting artefacts. This procedure is repeated 10 times, with the new phase timecourse re-estimated from the filtered oscillatory signal.

5. Calculate RV from the signal magnitude and instantaneous breathing frequency as the numerical derivative of the phase timecourse. These estimated quantities are then filtered at 0.2 Hz to average the within-

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**Fig. 1.** Example of the properties of the respiratory signal we extract via the Hilbert transform. The lower panel zooms in on a portion of the trace shown in the upper panel. Within each panel, in the upper half we overlay the amplitude envelope, \( s_m(t) \), on the respiratory bellows trace. In the lower half we show the information carried by the instantaneous phase, which we illustrate as \( \cos(\phi(t)) \) as per Equation 2. The product of this oscillatory component and the amplitude recovers the original signal. A version of this plot showing a larger portion of the recorded signal is shown in Supplementary Figure S1.

**Fig. 2.** Graphical overview of the phase interpolation procedure used to ensure monotonicity. In brief, phase reversals are linearly interpolated from the time when the signal first crosses a threshold implied by the local minimum, to the equivalent time defined in terms of exceeding the local maximum.
cycle fluctuations caused by the non-sinusoidal breathing waveform. Finally, estimates are thresholded to remove physiologically implausible values.

All filters, except for the common preprocessing, are 10th-order infinite impulse response, with the cut-offs stated in terms of the half-power frequency. Filters are run forwards and backwards to ensure zero-phase responses, and use 10 s of circular padding (i.e. designfilt, padarray, and filtfilt in MATLAB). The filters used during the preprocessing are 20th-order and use 100 s of padding due to the low cut-off frequency of the filter used to remove drifts in the signal.

3. Results

3.1. Data overview and preprocessing pipeline

Here, we demonstrate the performance of our method on data from a pharmacological fMRI study (Iglesias et al., 2021). Briefly, we analyse data from 69 subjects who were scanned while performing an audiovisual associative learning task after receiving a minimal dose of either a dopaminergic antagonist (amisulpride), a cholinergic antagonist (biperiden), or placebo. Full details of the fMRI acquisition parameters, preprocessing pipeline, and task analyses can be found in the Supplementary Material.

We use this dataset to compare the performance of our RVT estimator to the peak-based approach implemented in PhysIO. As well as a set of qualitative comparisons, we run a group-level paired t-test to formally assess which method results in the stronger removal of respiratory-related variance.

3.2. Qualitative behaviour

In Fig. 3 we compare the quantities inferred from the raw respiratory belt recordings. We focus on a single deep breath (i.e. a sigh (LI and Yackle, 2017)), as this is the type of breath that Power et al. (2020) noted that RVT can miss. In Panel (a) we show the detected maxima and minima, which amounts to the complete description of the data for peak-based methods (the equivalent Hilbert-based decomposition is shown in Fig. 1). As detailed in Kasper et al. (2017), PhysIO uses a sophisticated peak detection algorithm that includes some assumptions about the regularity with which successive peaks appear in time. However, in the case of this particular complex waveform caused by the sigh, this results in local maxima and minima being incorrectly identified. This could be corrected post hoc—but this can be a time intensive procedure—or the assumption of regularity could be relaxed. However, as evidenced by other ambiguities in Supplementary Figure S3, and as discussed in Power et al. (2020), there is unlikely to be an optimal setting for peak detection algorithms. In this instance, one would manually mark a maximum at 528 s, a trough at 532 s, and the next maximum would be at 543 s; however, this is an incredibly sparse representation of 15 s of data and one which would conflate the increase in respiratory volume with the decrease in respiratory rate. Counter-intuitively therefore, the RVT method used here is more similar to an RV measure (i.e. the changes in breathing rate are small). Finally, note that while empirical results suggest that avoiding rate and depth changes cancelling in this manner may well improve denoising by reducing the number of “missed” deep breaths, one would rather have an RVT estimator that was sensitive to these two effects separately (Power et al., 2020).

Finally, in Panels (b), (c), and (d) we compare the inferred respiratory volumes, breathing rates, and RVT itself. What is clear is that our method correctly identifies the changes in volume and rate, and furthermore, because we have a measure that is well defined for all points in time, these are not temporally overlapping. This leads to the expected changes in RVT, namely a rise driven by an increase in breathing volume, followed by a drop to well below baseline driven by the reduced breathing rate.

The Supplementary Material contains one extra visualisation of the data from this subject: in Supplementary Figure S4 we compare the inferred RVT regressors with the greypoint of the fMRI data itself.

3.3. Quantitative performance

In Fig. 4 we compare the main effect of the RVT-based regressors at the group level. As detailed in the Supplementary Material, we run two
Fig. 4. Comparison of the fMRI-RVT associations for our Hilbert-based RVT estimator and a method based on peak detection. In the upper two panels we show the t-stats for the main effect of the RVT regressors across the group (peak-level FWE-corrected at \( p = 0.05 \)). In the lower panel we show the significant differences between the two as estimated via a group-level paired t-test (cluster-level FWE-corrected at \( p = 0.05 \) with cluster-forming threshold \( p = 0.001 \)).

4. Discussion

In summary, we have demonstrated that the quantities we can derive via the Hilbert transform—instantaneous estimates of amplitude and phase—naturally map onto the quantities we need to estimate RVT. This furnishes us with a simple method that allows us to calculate a time-resolved version of RVT, rather than one defined in terms of a sparse set of peaks and troughs. We have demonstrated that this can better capture atypical breathing events, even in the context of non-sinusoidal oscillations with large and rapid changes in amplitude and phase. Finally, when convolved with the RRF as part of a typical fMRI preprocessing pipeline, our RVT estimates remove more respiratory-related variance from fMRI data than our baseline peak-detection-based method.

One of the aspects of our method we have emphasised throughout this technical note is the way it can dissociate changes in the depth and rate of breathing. However, the summary metric typically used for denoising, RVT, is the product of these two quantities. As Power et al. (2020) note, this introduces an ambiguity as “a larger-than-normal breath transpiring over a longer-than-normal time may appear quantitatively just like a typical breath occurring over a typical time”, or, in other words, RVT “is by definition relatively insensitive to outlier breath volumes so long as they [inversely] scale with breath times”. Our results speak to this in two ways. Firstly, what our results hint at is that this is often primarily an artefact of the low time-resolution implied by reducing a signal down to its peaks alone, and not RVT itself. Fig. 3 clearly shows how the changes in rate and depth we infer are not temporally coincident around a large and slow breath, and therefore we still see large changes in RVT in this instance. Secondly, however, if there are distinct differences in physiological responses to depth and rate changes (Birn et al., 2008; Lynch et al., 2020; Power et al., 2020) then our method provides both time series separately. This would allow one to derive fMRI regressors for both effects, which may improve the denoising performance for respiratory artefacts.

Next, in so far as our approach implies a model for the data, it is embodied by Equation 2: \( s(t) = s_0(t) \cos(\phi(t)) \). There are two key assumptions here. Firstly, that the Hilbert transform provides a physically mean-
ingul separation of fluctuations in magnitude and phase. The Hilbert transform is common, but splitting one-time-varying signal into two time-varying quantities is an underdetermined problem that admits different solutions (Boashash, 1992a). Similarly, the interactions between the two quantities can themselves carry meaningful information (Huang et al., 2016; Nguyen et al., 2019). Therefore, it may be that other decompositions or regularisation strategies improve performance. Secondly, the implicit assumption is that we can remove the vast majority of noise by appropriately filtering \( g(t) \). Again, this is an oversimplification in the presence of structured artefacts caused by, for example, contractions of the abdominal musculature unrelated to breathing or belt slippages (Power et al., 2020). A more formal model might explain the data better here.

On the other hand, the simplicity of our model allows one to apply it robustly to a wide range of data, which may render it a useful quality control measure in and of itself. For example, given the magnitude and phase timecourses one could reconstruct the signal as modelled, and then compute a time-resolved measure of goodness-of-fit to the original recording. This may prove useful if it could, for example, be used to flag “bad” timepoints that warrant manual inspection.

Finally, the other key aspect of the removal of these respiratory artefacts is the mapping from RVT to the BOLD signal via the RRF. It may be that the case our RVT estimator requires a subtly different RRF because it characterises large breaths in a slightly different manner. However, given the substantial variability in physiological responses across subjects and brain regions (Chen et al., 2020; Falahpour et al., 2013; Kassinopoulos and Mitis, 2019), we suspect that the use of flexibly parameterised, subject-specific response functions will dramatically improve the performance of denoising algorithms, and hope that the method proposed here is a useful addition to the overall physiological noise modelling pipeline.

5. Conclusion

In this technical note we have introduced a new method for estimating RVT from respiratory recordings for the purpose of removing physiological artefacts from fMRI data. We have demonstrated how this can both improve the detection of atypical breathing events and more strongly attenuate global fMRI artefacts as compared to current techniques.

Credit authorship contribution statement

Samuel J. Harrison: Conceptualization, Methodology, Software, Validation, Formal analysis, Writing - original draft, Writing - review & editing, Visualization, Funding acquisition. Samuel Bianchi: Software, Validation, Data curation, Writing - review & editing. Jakob Heinzel: Conceptualization, Writing - review & editing. Klaas Enno Stephan: Writing - review & editing, Supervision, Funding acquisition. Sandra Iglesias: Investigation, Data curation, Writing - review & editing. Lars Kasper: Conceptualization, Software, Writing - review & editing.

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Supplementary material

Supplementary material associated with this article can be found, in the online version, at 10.1016/j.neuroimage.2021.117787.
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