The Effect of Lifting Speed on Cumulative and Peak Biomechanical Loading for Symmetric Lifting Tasks

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1. Introduction

The lifetime prevalence rate of low back pain (LBP) has been estimated to be between 60% and 80%, implying that over half of the general population will have LBP at some point during their lives. The LBP has a high price tag, estimated at billions of dollars annually. Manual material handling (MMH) is considered a task associated with LBP [1].

A survey of 1221 men in the age group of 18–55 years was conducted to determine their history of LBP. Approximately 70% of the respondents had experienced either moderate or severe LBP at some point during their lives. The researchers reported that repetitive heavy lifting in the workplace was a risk factor for LBP [2].

In another study, researchers evaluated over 400 repetitive MMH jobs. They found that the load moment was one of the five workplace factors that distinguished high- from low-risk jobs, based on their model [3].

Compressive forces have been used to assess spinal loading during MMH tasks, especially those at the L5/S1 interface [4]. Numerous researchers have found dynamic calculations to be superior to corresponding static calculations for predicting back compressive forces (BCFs) [5–7]. Static calculations at any speed would yield identical results for BCFs if postures were the same. Dynamic BCF calculations would differ if the speed of the MMH task was different, due to the dissimilar accelerations and decelerations of the load, even if postures were the same between lifts.

Although the effect of cumulative and peak loading in increasing the risk of LBP remains unclear, various models have been suggested to address the need for a model to recognize differences in loading patterns and musculoskeletal injury risk [8–10].

Results of several studies indicate that peak moment about the lower back increases with lifting speed [4,11–13]. In one study it was found that peak low BCF increases [14], whereas in another study, peak and average moment and peak and average axial force...
at the lower back was shown to be increased [15]. Interestingly, results of another study [16] indicated that the total absolute muscle work actually decreased with higher lifting speed. It is unclear whether any of these aforementioned studies investigated the effect of all three of the variables included in this study, namely, (1) lift speed, (2) lift type/location, and (3) load lifted, according to the specific task definitions used in this study.

Shoulder musculoskeletal disorders (MSDs) are also of concern among those with MMH jobs. In a previous study, shoulder MSDs in nurses were examined. Researchers found that over 70% of those who reported an MSD reported MSD at the shoulder. In addition, work place risk factors for nurses were manually handling patients and undertaking physically laborious work [17].

A major purpose of this investigation was to determine and analyze the impact of lifting speed and lift type on peak and cumulative BCF and shoulder moment (SM) loads during symmetric lifting. Another purpose was to investigate differences between the static and dynamic models used for computing these loads.

2. Materials and methods

2.1. Participants

The study population included 10 adult male participants with a mean ± standard deviation (SD) age of 27.5 ± (±4.1) years, height of 175.6 ± (±5.6) cm, and weight of 73.8 ± (±9.3) kg. All the participants were free from injuries or other disorders that would affect their ability to perform the lifting tasks. Each participant signed a consent document before participating in the study, which provided information about the study methods as well as possible risks of participation. The University of Utah’s Institutional Review Board approved this study protocol (IRB: 00013692).

2.2. Data acquisition

Reflective markers were attached unilaterally on the left side of a participant at the following locations: head, acromion process, lateral epicondyle of the humerus (elbow joint), distal radius (wrist joint), center of the hand, sacrum, greater trochanter, femoral condyle, malleolus, calcaneus, and metatarsal head. Two-dimensional motion data were captured with a GS-55 digital camcorder (Panasonic). A six-axis AMTI force plate (Advanced Mechanical Technologies Inc., Watertown, MA, USA) recorded the ground reaction force and moment data. The Vicon Motus (Vicon, Centennial, CO, USA) software was used to obtain and process camera and force plate data.

Three independent variables were used for the lifting conditions, namely, hand load (2.25 and 9 kg), lift type (floor to waist (FW), waist to shoulder (WS), and floor to shoulder (FS)), and lift speed (fast, medium, and slow). In total, each participant performed three cycles of all 18 symmetric lifting conditions, consisting of a combination of the three lifting variables. Fig. 1 shows the vertical dimensions for each lift type, with the uppermost shelf at shoulder height and the middle shelf at waist height.

Lifting speed was controlled using a metronome. For each lifting condition, the participant would begin lifting at the speed indicated by the metronome. Researchers began recording data when the lifting speed and metronome speed were closely matched. Data collection continued for several cycles. The lift conditions are shown in Table 1.

2.3. Data analysis

Vicon Motus was used to process the motion and force plate data to calculate kinematics and kinetics. Centers of mass and locations of centers of mass were estimated based on anthropometric data [18]. Additional joint and muscle locations were estimated from previously published study results [19,20]. The start and end of each lift cycle were identified within each lifting trial. Three lift cycles were averaged to comprise a composite lifting cycle for every lifting condition. The composite lift cycle was normalized to 201 data points, which allowed for direct comparisons between the lifts performed at different speeds.

Forces and moments of interest were calculated using both static and dynamic equations to evaluate the effects of lifting speed on forces and moments at the shoulder and back. The following equations were used to calculate the static and dynamic BCFs based on motion and force data:

\[
BCF_{\text{static}}(N) = MF + [\cos(40) \times (L + m_{UB})] \times g \quad (1)
\]

\[
BCF_{\text{dynamic}}(N) = MF + [\cos(40) \times (L \times (g + a_{L})) + m_{UB} \times (g + a_{T})] \quad (2)
\]

where \(L\) is the load in the hands, \(g\) is gravity, \(a_{L}\) is the acceleration of the hands, \(a_{T}\) is the acceleration of the trunk, \(m_{UB}\) is the mass of the upper body, and MF is the erector spinae muscle force. The differences between the static and dynamic calculations are that the acceleration terms for each mass are accounted for in the dynamic equations, but are not included in the static equations. The

| Table 1 | Lift conditions |
|---------|----------------|
| Speed   | L = 2.25kg load | H = 9kg load |
|         | FW  | WS | FS | FW  | WS | FS |
| S (Slow)| S, L | S, L | FS | S, H | S, H | S, H |
| M (Medium)| M, L | M, L | FS | M, H | M, H | M, H |
| F (Fast) | F, L | F, L | FS | F, H | F, H | F, H |

A total of 18 conditions were used.

FS, floor-to-shoulder; FW, Lift types of floor-to-waist; WS, waist-to-shoulder.
influence from Coriolis acceleration is neglected. MF is calculated using the following formula:

\[
MF = \frac{M_{L5S1}}{D_{ES}}
\]  

(3)

where \(M_{L5S1}\) is the sum of the moments about the L5/S1 interface and \(D_{ES}\) is the perpendicular distance from the L5/S1 interface to the erector spinae muscle group. Static and dynamic equations for the SM are as follows:

\[
SM_{static} = [L \times (g \times D_{L-S}) + |m_{UA} \times (g \times D_{UA-S})| + |m_{LA} \times (g \times D_{LA-S})|
\]

(4)

\[
SM_{dynamic} = [L \times (g + a_{L}) \times D_{L-S}) + |m_{UA} \times (g + a_{UA}) \times D_{UA-S})| + |m_{LA} \times (g + a_{LA}) \times D_{LA-S})|
\]

(5)

where \(D_{L-S}, D_{UA-S},\) and \(D_{LA-S}\) are the distances from the shoulder to the load, to the upper arm center of mass, and to the lower arm center of mass, respectively. The masses of the upper and lower arms are \(m_{UA}\) and \(m_{LA}\) with accelerations of \(a_{UA}\) and \(a_{LA}\), respectively.

The authors’ technique for comparing results between participants is unique, in that the BCF values were normalized by body mass and the SM values were normalized by body mass and height. Normalization techniques are often used in gait analysis kinetics [21–23] and seem reasonable for making direct comparisons between individuals with different anthropometry for evaluating lifting tasks.

The cumulative load for a given variable was defined as the area under the curve for the duration of the lift cycle. The cumulative load was calculated for both BCF and SM by multiplying the average over the lift cycle by the total duration of the lift cycle. The cumulative loading of BCF and SM. The error bars in the figure represent the standard error of the mean.

Mean differences were calculated as follows:

\[
\text{Mean}_\text{difference} = \frac{X_1 - X_2}{(X_1 + X_2)/2} \times 100\%
\]

where \(X_1\) is the mean value of either BCF or SM at a certain speed or lift type and \(X_2\) is the mean BCF or SM value for a different speed or lift type that is to be compared with \(X_1\).

2.4. Statistical analysis

The focus of the statistical analysis was on the peak and cumulative loads of BCFs and SMs. Statistical analyses were performed using SPSS (SPSS Inc., Chicago, IL, USA). Part of a three-way repeated measures analysis of variance (RM-ANOVA) analyzed the difference between static and dynamic measures for assessing peak and cumulative BCF and SM. In addition, RM-ANOVA was used to perform a comparative analysis between lift types and speeds. The RM-ANOVA was run for both light and heavy hand-load conditions. Paired comparisons were made with adjustments for multiple comparisons using the Bonferroni method. If the assumption of sphericity was violated based on Mauchly’s test, the Greenhouse–Geisser correction was used. The results were considered statistically significant when \(p < 0.05\) (\(\alpha = 0.05\)). The differences in BCF and SM loads, based on hand load, were not statistically analyzed, but the results are reported and shown for completeness.

3. Results

Participants performed a set of three cycles for all 18 lifting conditions. This resulted in mean (±SD) velocities of 0.64 (±0.17), 0.44 (±0.13), and 0.34 (±0.07) m/s for fast, medium, and slow lifts, respectively.

3.1. Static versus dynamic

Dynamic calculations were 16% and 5% higher than static calculations \((p < 0.001)\) for peak BCF and peak SM, respectively. For the BCF and SM cumulative loading, there was a difference of less than 1% and 2%, respectively, between static and dynamic calculations \((p < 0.001)\).

Fig. 2 illustrates the difference between static and dynamic calculations for a fast lift. The dynamic calculation for BCF shows a local maximum near the beginning of the lift due to initial acceleration of the load, much higher than the static calculation. A local minimum follows shortly after the maximum and drops below the static calculation. Once deceleration and additional control are warranted for object placement, the static and dynamic calculations are nearly the same. A similar pattern is seen for the static and dynamic SM calculations.

3.2. Lifting speed

Based on paired comparisons, peak BCF was significantly different between fast and slow lift speeds \((p < 0.01)\), whereas peak SM was not significantly different. Both BCF and SM cumulative loads were significantly different between fast and slow speeds \((p < 0.001)\). This was true for both light and heavy hand loads. Fig. 3 depicts the means of the dynamic calculations for peak and cumulative loading of BCF and SM. The error bars in the figure represent the standard error of the mean.

Table 2 is a summary of the mean differences between fast and slow lifting speeds for the variables in the previous figure. The values in Table 2 are positive if the fast lifting speed resulted in greater values than the slow lifting speed. Conversely, if the values

![Fig. 2.](image-url) (A) Average static versus dynamic back compressive force for floor-to-shoulder lift at fast speed with high weight. (B) Average static versus dynamic shoulder moment. BCF, back compressive force; BW, body weight; Ht, height; SM, shoulder moment.
are negative, slow lifting speeds produced greater values than the fast lifting speed.

3.3. Lift type

Based on paired comparisons, BCF peak and cumulative loading were significantly different between WS and other lift types ($p < 0.001$), with WS having smaller values. For SM, peak and cumulative load values were significantly lower for FW lifts than for FS and WS lifts ($p < 0.001$), as depicted in Fig. 4. These findings were true for both light and heavy hand loads. Absolute mean differences are shown in Table 3.

Table 2

Mean differences between fast and slow lift speeds

| Hand load (kg) | BCF Peak | Cumulative load | SM Peak | Cumulative load |
|---------------|----------|-----------------|---------|-----------------|
| 2.25          | 17.6%*   | -56.7%*         | 3.60%   | -66.0%*         |
| 9             | 18.3%*   | -58.2%*         | 2.70%   | -61.6%*         |

Positive mean differences indicate that fast lifting speed produced greater values than slow lifting speed; negative values indicate slow lifting speeds produced greater values than fast speed.

*Significant difference between fast and slow speeds ($p < 0.001$).

BCF, back compressive force; SM, shoulder moment.

Fig. 3. (A) Peak dynamic back compressive force (BCF), (B) cumulative dynamic BCF, (C) peak dynamic shoulder moment (SM), and (D) cumulative dynamic SM at three lifting speeds with two different hand loads. BW, body weight; Ht, height.

Fig. 4. (A) Peak dynamic back compressive force (BCF), (B) cumulative dynamic BCF, (C) peak dynamic shoulder moment (SM), and (D) cumulative dynamic SM for three lift types with two different hand loads. BW, body weight; FS, floor to shoulder; FW, floor to waist; Ht, height; WS, waist to shoulder.
4. Discussion

This research indicates that dynamic calculations of peak loading during lifting tasks account for the existing forces and those which are not captured using static models alone. Dynamic calculations take the speed of lift into account unlike the static calculations. This finding confirms the results of other studies that have used dynamic calculations to determine peak loading [5–7]. However, the results of this study show that if cumulative loading is the only desired output, static calculations would be a good approximation for the dynamic loading of the lifting task. There was a difference of less than 2% for both BCF and SM calculations between the static and dynamic cumulative loads.

Results suggest that the analysis of parameters of interest plays an important role in predicting risk during lifting [20]. Using BCF as the parameter of interest and examining risk using peak value, it is clear that the slow lifting speed is preferable to the fast lifting speed because the peak BCF value is approximately 18% lower on average than the fast speed. It has been reported that BCF at a slow lifting speed was different from other lifting speeds [24] and also that the slow speed was different from other lifting speeds [24] and also that the slow lifting speed is preferable to the fast lifting speed because BCF at a slow lifting speed was different from other lifting speeds [24].

Another option is to alter the speed of lift during the lift cycle. Various assessment methods exist to account for both peak and cumulative BCF to determine risk for each lift cycle [8]. Additional methods should be developed and compared with epidemiological data to determine the best assessment method to evaluate risk in terms of the individual lift cycle. A better assessment of an individual lift cycle would lead to better determination of risk for a job that includes multiple lifts. This assessment should use dynamic measures rather than static measures.

It might be possible to predict BCF and SM peak and cumulative load values based on the BCF and SM values at the beginning and end of lift as well as the lift duration and lift type. Using such prediction equations would allow researchers to assess the risk for a lift cycle quickly rather than assessing the whole lift cycle to obtain an accurate evaluation of risk [27].

In addition, lifting speed should be incorporated into current, widely available models that predict the BCF and SM values or the risk of the lift. These models include the NIOSH revised lifting equation, the Snook Liberty Tables, Michigan’s Three-Dimensional Static Strength Prediction Program, and the Utah Back Compressive Force model.

After five participants had participated in the study, a “stop” was added to the shelves to help researchers identify the end of the lift cycle for the remaining five participants. This should also

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### Table 3

| Hand load (kg) | FW–WS Peak | FW–WS Cumulative load | FW–FS Peak | FW–FS Cumulative load | WS–FS Peak | WS–FS Cumulative load |
|---------------|-------------|-----------------------|-------------|-----------------------|-------------|-----------------------|
| BCF 2.25      | 72.7%*      | 69.7%                 | 5.30%       | 20.1%                 | 68.0%*      | 86.8%                 |
| BCF 9         | 50.6%*      | 55.8%                 | 4.6%        | 28.1%                 | 46.3%*      | 80.7%                 |
| SM 2.25       | 29.8%*      | 85.6%                 | 27.7%*      | 95.1%                 | 2.20%       | 11.90%                |
| SM 9          | 25.7%*      | 74.1%                 | 23.8%*      | 96.0%*                | 1.90%       | 26.60%                |

*Significant difference ($p < 0.001$).

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3.4. Load

Peak and cumulative BCF and SM loads were higher for the 9-kg, heavy, hand-load condition than the 2.25-kg, light, hand-load condition in all cases for every participant.
make the starting location of the hand load consistent for the WS lift. Slow, medium, and fast speeds were controlled by allowing participants to adjust to a metronome. Although the participants aimed to match the metronome, small errors still occurred. Additional errors occurred due to adjustments during the lift cycle as participants slowed down toward the end of a lift to try and make a lift longer. As was mentioned previously, researchers tried to minimize this speed error by allowing participants to lift a number of cycles until they became accustomed to that speed before collecting data.

Motion-collection techniques using cameras and reflective markers are subject to small errors resulting from marker placement, skin motion, and camera resolution. In addition, in this two-dimensional study, a one-sided marker set and only one video camera were used to capture and analyze data, with symmetry assumed. This may have led to additional errors in terms of marker-camera were used to capture and analyze data, with symmetry assumed. This may have led to additional errors in terms of marker location compared with the actual underlying anthropometric data, and inaccuracies due to minor asymmetry in lifting. Although there may be slight errors in the overall quantification of BCF and SM, the findings related to speed of lift and the use of dynamic calculations hold true, due to the nature of the comparisons and the statistical analysis used.

Conflict of interest

No potential conflict of interest relevant to this article was reported.

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