Fast dynamics perspective on the breakdown of the Stokes-Einstein law in fragile glassformers

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The breakdown of the Stokes-Einstein (SE) law in fragile glassformers is examined by Molecular-Dynamics simulations of atomic liquids and polymers and consideration of the experimental data concerning the archetypical OTP glassformer. All the four systems comply with the universal scaling between the viscosity (or the structural relaxation) and the Debye-Waller factor \( \langle u^2 \rangle \), the mean square amplitude of the particle rattling in the cage formed by the surrounding neighbors. It is found that the SE breakdown is scaled in a master curve by a reduced \( \langle u^2 \rangle \). Two approximated expressions of the latter, with no and one adjustable parameters respectively, are derived.

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I. INTRODUCTION

Under hydrodynamic conditions the diffusion coefficient \( D \) is inversely proportional to the shear viscosity \( \eta \). More quantitatively, the Stokes-Einstein (SE) relation states that the quantity \( D\eta/k_B T \) is a constant of the order of the size of the diffusing particle, \( k_B \) being the Boltzmann constant \([1]\). Remarkably, despite its macroscopic derivation, SE accounts also well for the self-diffusion of many monoatomic and molecular liquids, provided the viscosity is low (\( \ll 10 \text{ Pa} \cdot \text{s} \)[2]). Distinctly, a common feature of several fragile glass formers is the breakdown of SE for increasing viscosity, that manifests as a partial decoupling between the diffusion and viscosity itself \([3–6]\). The decoupling is well accounted for by the fractional SE (FSE) \( D \sim \eta^{-\kappa} \)[7] where the non-universal exponent \( \kappa \) falls in the range \([0.5–1]\)[8]. The usual interpretation of the SE breakdown relies on dynamic heterogeneity (DH), the spatial distribution of the characteristic relaxation times \( \tau \) developing close to the glass transition (GT) \([3, 7, 9]\). In metallic liquids it has been shown that the crossover from SE to FSE is coincident with the emergence of DHs \([5, 10]\).

The SE law deals with long-time transport properties. Yet, several experimental and numerical studies evidenced universal correlations between the long-time relaxation and the fast (picosecond) dynamics as sensed by Debye-Waller (DW) factor \( \langle u^2 \rangle \), the collective \([11, 12]\) rattling amplitude of the particle within the cage of the first neighbours \([6, 13–20]\). In particular, correlations are found in polymers \([14, 21, 22]\), binary atomic mixtures \([18, 21]\), colloidal gels \([23]\), antiplasticized polymers \([17]\) and water-like models \([24, 25]\). Strictly related correlation between long-time relaxation and the shear elasticity are known \([26–29]\). Building on these ideas, using Molecular-Dynamics (MD) simulations of a polymer model, some of us showed that the SE breakdown is well signaled by the DW factor \( \langle u^2 \rangle \)[6]. Further, Douglas and coworkers demonstrated that it is possible to estimate the self-diffusion coefficient from linking the DW factor to the relaxation time and assuming that a FSE relation holds \([30]\). In the same spirit, we also mention the method for estimating from \( \langle u^2 \rangle \) data the characteristic temperatures of glass-forming liquids, including that of the SE breakdown and the onset of DHs \([31, 32]\).

The present paper provides novel evidence of the vibrational scaling of the breakdown of SE law in terms of the DW factor \( \langle u^2 \rangle \) by combining MD simulations of atomic and polymeric fragile glassformers and experimental data of the archetypical glassformer OTP \([33, 34]\).

The paper is organized as follows. In Sec. II details about the numerical models and the quantities of interest are given. The results are presented and discussed in Sec. III.

II. MODELS AND METHODS

MD simulations for a Lennard-Jones binary mixture (BM) and the CuZr metallic alloy (MA) were carried out using LAMMPS molecular dynamics software \([35]\). As to BM, we consider a generic three-dimensional model of glass-forming liquid, consisting of a mixture of A and B particles, with \( N_A = 1600 \) and \( N_B = 400 \), interacting via a Lennard-Jones potential \( V_{\alpha\beta}(r) = 4\varepsilon_{\alpha\beta} \left( \frac{\sigma_{\alpha\beta}}{r} \right)^{12} - \left( \frac{\sigma_{\alpha\beta}}{r} \right)^6 \) with \( \alpha, \beta = A, B \) and \( r \) being the distance between two particles. The parameters \( \epsilon_{AA}, \sigma_{AA} \) and \( m_A \) define the units of energy, length and mass; the unit of time is given by \( \tau_0 = \sigma_{AA} \sqrt{m_A/\epsilon_{AA}} \). We set \( \epsilon_{AA} = 1.0, \epsilon_{AB} = 1.5, \epsilon_{BB} = 0.5, \sigma_{AA} = 1.0, \sigma_{AB} = 0.8 \) and \( \sigma_{BB} = 0.88 \) and \( m_A = m_B = 1 \). It is known that, with this choice, the system is stable against crystallization \([36]\). The potential is truncated at \( r = r_c = 2.5 \) for computational convenience. The total density \( \rho = 1.204 \) is fixed and periodic boundary conditions are used. The system is equilibrated in the NVT ensemble and the production runs are carried out in the NVE ensemble. As to MA, an embedded-

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atom model (EAM) potential was used to describe the interatomic interactions in the CuZr binary alloy [37]. Each simulation consists of a total number of 23328 atoms contained in a box with periodic boundary conditions. The initial configurations were equilibrated at 2000 K for 5 ns followed by a rapid quench to 500 K at a rate of 1011 K/s. The quench was performed in the NPT ensemble at zero pressure. During the quench run configurations at the temperatures of interest were collected and, after adequate relaxation, used as starting points for the production runs in the NVT ensemble.

We consider the mean square particle displacement (MSD) \( \Delta r^2(t) \) and define the Debye-Waller (DW) factor \( \langle u^2 \rangle = \Delta r^2(t) \) where \( t_{DW} \) is a measure of the trapping time of a particle in the cage of the surrounding ones and equals the time at which \( \log \text{MSD} \) vs \( \log t \) has minimum slope [14, 18]. For the BM systems \( t_{DW} \approx 1 \) whereas for the MA system \( t_{DW} \approx 1 \) ps, which is typical of metallic liquids. The self-diffusion coefficient \( D \) is determined via the long-time limit \( D = \lim_{t \to \infty} \Delta r^2(t)/6t \). We define the structural relaxation time \( \tau_\alpha \) via the relation \( F_s(q_{\max}, t) = 1/e \) where \( q_{\max} \) is the maximum of the static structure factor and \( F_s \) the self part of the intermediate scattering function (ISF) [14, 18].

The degree to which particle displacements deviate from a Gaussian distribution is quantified by the non-gaussian parameter (NGP) \( \alpha_2(t) = (3\Delta r^4(t)/5\Delta r^2(t)^2 - 1 \) where \( \Delta r^4(t) \) is the mean quartic displacement [38]. The viscosity \( \eta \) is calculated by integrating the stress autocorrelation function according to Green-Kubo formalism [39, i.e. \( \eta = (V/k_B T) \int_0^\infty \langle P_{\alpha\beta}(t_0)P_{\alpha\beta}(t_0 + t) \rangle dt \) where \( V \) is the volume, \( P_{\alpha\beta} \) is the off-diagonal \( \alpha\beta \) component of the stress and an average over the three components \( \alpha\beta = xy, xz, yz \) is performed.

III. RESULTS AND DISCUSSION

First, we focus on the increase of DHs upon cooling as quantified by the NGP \( \alpha_2 \). The NGP time dependence has non-monotonous behavior: first it increases with time and then decays to zero in the gaussian diffusive regime, resulting in a maximum \( \alpha_{2,max} \) for times comparable to the structural relaxation time \( \tau_\alpha \) [14]. In Fig. 1 (a,c) we plot the temperature dependence of \( \alpha_{2,max} \) for BM and MA systems. Data are shown separately for each component of the two systems, A and B for BM and Cu and Zr for MA. The increase of \( \alpha_{2,max} \) is slow at high temperature and accelerates as deeper supercooling is achieved. The crossover temperature \( T_s \) can be detected from the temperature derivative \( d\alpha_{2,max}/dT \), which is shown in Fig. 1 (b,d) [10]. We find \( T_s = 0.75(5) \) for the BM and \( T_s = 1000(50) \) K for the MA, with no dependence on the species within our precision.

Figure 2 shows the decoupling of diffusion and viscosity in BM and MA. In both models, for each component, the SE relation is obeyed at high temperature and breaks down in the supercooled regime. The decoupling is marked by a crossover towards a FSE relation \( D \propto (\tau_\alpha/T)^{\kappa} \) with \( \kappa \) equal 0.77 and 0.65 for A and B particles respectively in the BM model and \( \kappa \) equal 0.66 and 0.73 for Cu and Zr atoms respectively in the MA model. It is worth noting that consideration of the ratio \( \eta/T \) or \( \eta \) alone in FSE is just a matter of convenience, given the huge change of viscosity in the small temperature range where FSE is observed. The above results concerning the characteristic exponent \( \kappa \) are intermediate between the prediction of the “obstruction model” \( \kappa = 2/3 \) [8] and the universal value \( \kappa = 0.85 \) found by Mallamace et al [39]. The SE product \( D\tau_\alpha/T \) and its temperature derivative \( d(D\tau_\alpha/T)/dT \) reveals that the breakdown becomes apparent below 0.7 and 1000 K for the BM and MA models respectively. In both cases, this breakdown corresponds to the crossover temperature \( T_s \) of the onset of DHs.

Hall and Wolynes [13] first elaborated a vibrational model relating the slowing down on approaching GT with the accompanying decrease of the DW factor \( \langle u^2 \rangle \) due to the stronger trapping effects [13]. They identified \( \tau_\alpha \) with \( \tau_\alpha^{(HW)} \) where:

\[
\tau_\alpha^{(HW)} = \tau_0^{(HW)} \exp \left( \frac{a^2}{2(u^2)} \right)
\]

with \( \tau_0^{(HW)} \) and \( a^2 \) adjustable constants. In particular, \( a \) is the displacement to overcome the barrier activating the structural relaxation. We test Eq.1 in Figure 3. For both BM and MA models, we find good agreement with simulation data if mobility is high (high \( \langle u^2 \rangle \) or low \( \tau_\alpha \)). Otherwise, deviations become apparent, as already reported [14, 17, 18]. In particular, deviations from Eq. 1 correlate to the emergence of DHs in polymer melts [6]. This conclusion is in close agreement with the finding that deviations from Eq. 1 become evident for both BM and MA models around the crossover temperature \( T_s \), see Figure 3.

An extension of Eq.1 interprets the observed concavity of

![Figure 1: Panels a) and c): Temperature dependence of \( \alpha_{2,max} \), the maximum of the NGP, for the BM (a) and MA (c) systems. Panels b) and d): temperature derivative \( d\alpha_{2,max}/dT \) as a function of temperature for the BM (b) and MA (d) systems. The shaded regions mark the onset of dynamical heterogeneities at \( T_s = 0.75(5) \) for the BM and \( T_s = 1000(50) \) K for the MA, with no dependence on the species within our precision.](image-url)
FIG. 2: Panels a) and c): Self-diffusion coefficient as a function of the ratio \(\tau_a/T\) (a) or \(\eta/T\) (b) for the BM (a) and MA (c) systems. Dashed lines correspond to SE relation \(D \propto (\tau_a/T)^{-1}\) or \(D \propto (\eta/T)^{-1}\). Full lines correspond to fractional SE relation \(D \propto (\tau_a/T)^{-\alpha}\) or \(D \propto (\eta/T)^{-\alpha}\). Panels b) and d): SE product \(D\tau_a/T\) (b) and \(D\eta/T\) (d) versus temperature. Insets: corresponding temperature derivative \(d(D\tau_a/T)/dT\) and \(d(D\eta/T)/dT\). Shaded regions mark the onset of the breakdown of SE relation.

FIG. 3: Panels a) and b): Structural relaxation time as a function of the inverse DW factor for the BM (a) and MA (b) systems. Dashed lines correspond to Eq. 1. The location of the onset temperature \(T_s\) is indicated for all the species.

The curve \(\log \tau_a vs 1/\langle u^2 \rangle\) in Figure 3 as due the dispersion of the \(a\) parameter, modelled by a truncated gaussian distribution \(p(a^2)\) with characteristic parameters \(\bar{a}^2\) and \(\sigma_{a^2}^2\) [14, 18, 21]. Here, we define \(\langle X \rangle_{a^2}\) the average of \(X\) according to \(p(a^2)\) and \(\tau_a = (\tau_a^{(HW)})_{a^2}\). According to that approach, the relation between \(\tau_a\) and the DW factor reads [14, 18, 21]:

\[
\tau_a = \tau_0 \exp \left( \frac{\bar{a}^2}{2\langle u^2 \rangle} + \frac{\sigma_{a^2}^2}{8\langle u^2 \rangle^2} \right)
\]

(2)

\[
\tau_a = \tau_0 \exp \left( \beta (\langle u^2 \rangle/\langle u^2 \rangle) + \gamma (\langle u^2 \rangle/\langle u^2 \rangle^2) \right)
\]

(3)

In Eq.2 \(\tau_0\), \(\bar{a}^2\) and \(\sigma_{a^2}^2\) are system-dependent parameters. Eq. 2 is recast in the universal form given by Eq.3 where \(\langle u^2 \rangle\) is the DW factor at GT (defined via \(\tau_a = 10^2 s\) or \(\eta = 10^{12} Pa \cdot s\)) [14]. In particular, now the universal constants \(\beta = \beta 10 = 3.7(1)\) and \(\gamma = \gamma 10 = 28.4(2)\) are introduced, with \(\beta\) and \(\gamma\) defined in [14], and \(\tau_0\) ensures \(\tau_a = 10^2 s\) at GT [14]. Indeed, Eq. 3 was shown to provide a good description of experimental data in several systems [14, 18, 21].

Now, we analyze the correlation between the SE breakdown and the fast dynamics. To this aim, we consider the ratio \(K_{SE}/K_0\) between \(K_{SE} = D\eta\) (or \(K_{SE} = D\tau_a\), when viscosity data are missing) and \(K_0\), the quantity \(K_{SE}\) evaluated at high temperature (\(\tau_a \approx 1 ps\)). In Figure 4 we plot \(K_{SE}/K_0\) as a function of \(\langle u^2 \rangle/\langle u^2 \rangle\). We complement the MD results concerning the BM and MA models with literature data for few archetypical systems, specifically MD simulations of a model polymer melt [6] and experimental data for ortho-terphenyl (OTP) [33, 34]. All the numerical and the experimental data presented in Figure 4 exhibit the universal scaling.
expressed by Eq. 3, see top inset for the BM and MA systems and ref.[14, 16] for the polymer melt and OTP. Figure 4 is the major result of the present paper. It evidences the scaling of the SE violation in terms of the DW in three different numerical atomic and polymeric models (BM, MA, polymer melt) and OTP. Consideration of the data above \( \langle u^2 \rangle / u_g^2 \sim 10 \) to dynamical heterogeneities [14]. Alternatively, we assume the FSE form \( D\tau_{\alpha} \approx \tau_\alpha^{1 - \kappa} \tau_{\alpha}^{1 - \kappa} \) and \( \tau_{\alpha} \) as given from Eq. 3 so that \( K_{SE}/K_0 \approx (\tau_{\alpha}/\tau_0)^{1 - \kappa} \). Best-fit is found for \( \kappa = 0.85 \) (orange curve in Fig.4), which interestingly equals the universal value found by Mallamace et al [39].

The present results strongly suggest that the vibrational scaling in terms of the reduced DW factor \( \langle u^2 \rangle / u_g^2 \) encompasses the DH influence on the SE breakdown. A similar conclusion was reached by evaluating the DW factor of a simulated 2D glassformer in a time lapse being one order of magnitude larger than the one setting \( \langle u^2 \rangle / u_g^2 \) [40]. Even if the experimental and the MD results are fairly scaled to a master curve by the reduced DW factor \( \langle u^2 \rangle / u_g^2 \), the proposed universal character of this scaling has to be corroborated by further investigations. Two distinct guidelines are in order: i) a wider range of simulated and experimental systems, the latter at present time being limited mainly by the lack of DW data, ii) a better description of the universal master curve with respect to the one provided by Eq.4 by improving the form of the distribution of the squared displacements controlling the structural relaxation and diffusion, in particular in the part that affects the latter.

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