Two-point correlation properties of stochastic “cloud processes”

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We study how the two-point density correlation properties of a point particle distribution are modified when each particle is divided, by a stochastic process, into an equal number of identical “daughter” particles. We consider generically that there may be non-trivial correlations in the displacement fields describing the positions of the different daughters of the same “mother” particle, and then treat separately the cases in which there are, or are not, correlations also between the displacements of daughters belonging to different mothers. For both cases exact formulae are derived relating the structure factor (power spectrum) of the daughter distribution to that of the mother. These results can be considered as a generalization of the analogous equations obtained in \cite{1} for the case of stochastic displacement fields applied to particle distributions. An application of the present results is that they give explicit algorithms for generating, starting from regular lattice arrays, stochastic particle distributions with an arbitrarily high degree of large-scale uniformity.

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I. INTRODUCTION

Point processes, i.e., stochastic spatial distributions of identical point particles, provide a very useful mathematical scheme for many different $N$-body and granular physical systems such as crystals (both regular, and perturbed)\cite{2, 3, 4}, quasi-crystals\cite{5}, structural glasses, fluids\cite{6}, self-gravitating systems in astrophysics and cosmology (see, e.g.,\cite{7, 8, 9}). They find also many applications in a wide range of scientific fields: computer image problems\cite{10}, and bio-metrical studies\cite{11}. These results can be considered as a generalization of the analogous equations obtained in \cite{1} for the case of a large scale SF inherent to \textsuperscript{\textit{b}} superhomogeneous (or hyper-uniform) stochastic point particle distributions\cite{12, 13, 14}. This class of distribution is characterized by the convergence of the SF to zero as $k \rightarrow 0$. We will show explicitly that, for the case that the mother distribution is a regular lattice array, the associated (positive) exponent in the $k \rightarrow 0$ limit of the SF is related to the conservation of the local mass moments in the passage from the single point particle to the cloud of daughter particles\textsuperscript{1}.

The main immediate application we have in mind of the present study, and the one we discuss at some length, is the determination of the constraints on the stochastic displacement field and the number of daughters $m$ required to produce a target behavior of the SF at large scale (i.e. small wave number $k$) in the daughter particle distribution. More specifically we are interested in the case of a large scale SF inherent to \textsuperscript{\textit{b}} superhomogeneous (or hyper-uniform) stochastic point particle distributions\cite{12, 13, 14}. This class of distribution is characterized by the convergence of the SF to zero as $k \rightarrow 0$. We will show explicitly that, for the case that the mother distribution is a regular lattice array, the associated (positive) exponent in the $k \rightarrow 0$ limit of the SF is related to the conservation of the local mass moments in the passage from the single point particle to the cloud of daughter particles\textsuperscript{1}.

The paper is structured as follows. In the next section

\footnote{1 We note that approximate heuristic derivations of some of these results can be found in the cosmological literature (see, e.g.,\cite{8, 15}) in which constructions of this kind are considered in discussions of “causality bounds”, i.e., bounds imposed on the large scale behavior of the SF by the existence of a causal horizon in cosmological models.}
we introduce our notation and the essential definitions, and then derive a general expression for the SF of the daughter distribution, before averaging over the realizations of the cloud process. In Sect. III we derive our general result for the SF for the case that there are only correlations between displacements of particles derived from the same mother. In the following section we apply this result to the specific case that the mother distribution is a regular lattice, and derive the small k behavior of the SF of the daughter distribution. In Sect. V we then derive our result for the more general case that there is also arbitrary correlation between the displacements of daughters of different mothers, and then also consider the specific case of an initial regular lattice. As an example we derive the small k behavior of the SF of a lattice of correlated dipoles. In the final section we summarize our results and discuss briefly both possible developments and further applications of the results reported here.

II. STRUCTURE FACTOR (SF) OF A STOCHASTIC CLOUD PROCESS

We start with a spatial distribution of M “mother” particles in a cubic volume V, for which we write the microscopic particle density as:

\[ n(x) = \sum_{i=1}^{M} \delta(x - x_i). \]  

Let us denote by \( \langle ... \rangle \) the average over the ensemble of realizations of this point process, which we assume to be uniform at large scales, i.e., to have a well defined (positive) mean particle density \( n_0 \) in the limit \( V \to \infty \). The SF (or power spectrum) is then defined (see, e.g., [9]) as

\[ S_n(k) = \lim_{V \to \infty} \frac{\langle |\tilde{n}(k; V)|^2 \rangle}{M} - (2\pi)^d n_0 \delta(k), \]  

where the limit \( V \to \infty \) is taken at fixed \( n_0 \), and

\[ \tilde{n}(k; V) = \int_V d^d x \, n(x) e^{-i k \cdot x} = \sum_{i=1}^{M} e^{-i k \cdot x_i}, \]

is the Fourier transform (FT) of the point distribution in the volume V. Note that, defined in this way, \( S_n(k \to \infty) = 1 \), which is the usual normalization of the shot noise present in any particle distribution at short distances\(^2\). We suppose further that the point distribution is statistically spatially homogeneous. In this case the SF is related by a FT to the usual two point correlation function. More specifically, if we denote by \( \tilde{h}_n(x) \)

\[ h_n(k) = FT[h_n(x)]. \]

Each particle in this distribution is a “mother” point which splits into \( m \geq 1 \) particles (“daughters”). We take these latter to have identical unitary mass \( m \). The daughter particle distribution, which we call a cloud process, thus clearly has an average particle density \( \rho_0 = mn_0 \).

Let us denote by \( u^{(i)} \) the displacement from the mother position of the \( r^{th} \) particle \((1 \leq r \leq m)\) belonging to the cloud generated by the \( i^{th} \) mother \((1 \leq i \leq M)\) of the distribution \( n(x) \). The resulting microscopic density of particles is then (see Fig. 1)

\[ \rho(x) = \sum_{r=1}^{m} \sum_{i=1}^{M} \delta(x - x_i - u^{(i)}). \]  

\[^2\text{An alternative quite widely used normalisation (e.g. in the cosmology literature) differs by a factor of } 1/n_0.\]

\[^3\text{We could equally take each daughter to have a mass } 1/m, \text{ so that mass is explicitly conserved. We choose unitary mass as this overall normalization factor cancels out in the SF.}\]
Let us now take the FT of \( \rho(x) \) in the volume \( V \)

\[
\tilde{\rho}(k; V) = \int_V d^d x \rho(x) e^{-ik \cdot x} = \sum_{r=1}^{m} \sum_{i=1}^{M} e^{i k \cdot (x_i + u_r^{(i)})}.
\]

We can now write the SF for \( \rho(x) \) as

\[
S_\rho(k) = \lim_{V \to \infty} \frac{\langle |\tilde{\rho}(k; V)|^2 \rangle}{N} = (2\pi)^d \rho_0 \delta(k),
\]

where \( \langle \ldots \rangle \) is, as above, the average over the realizations of \( n(x) \) and \( \langle \ldots \rangle \) is the average over the realizations of the displacement field. We will always assume here that the displacement field is statistically independent of the realization of the “mother” distribution, so that these two averages commute. In general, we can write

\[
|\tilde{\rho}(k; V)|^2 = N + \sum_{i=1}^{M} \sum_{r \neq s} e^{-ik \cdot (u_r^{(i)} - u_s^{(i)})} + \sum_{i \neq j}^{1, M} \sum_{1, m}^{1, m} e^{-ik \cdot (x_i - x_j) - u_r^{(i)} - u_s^{(j)}}.
\]

III. UNCORRELATED CLOUDS: GENERAL RESULT

In this section we assume the following statistical properties for the displacement field:

- The displacements applied to daughters with different mothers are statistically independent;
- The displacements applied to different daughters with the same mother may be arbitrarily correlated.

More precisely, let us denote by \( p(u) \) the probability density function (PDF) for a single displacement, by \( p_s(u, v) \) the joint PDF of the displacements \( u \) and \( v \) applied to two daughters of the same mother, and by \( p_d(u, v; x) \) the joint PDF of the displacements applied to two particles belonging to different mothers separated by \( x \). Our assumptions imply that we have \( p_d(u, v; x) = p(u) p(v) \) for any \( x \neq 0 \), while we allow \( p_s(u, v) \neq p(u) p(v) \).

Note that in writing the PDFs in this way, without labels for the clouds and for the particles in a single cloud to which the displacements apply, we assume implicitly the following similarities: (i) \( p(u) \) is the same for all displacements, and (ii) \( p_s(u, v) \) does not depend on the cloud and is the same for all \( m(m-1)/2 \) couples of the \( m \) particles belonging to the same cloud. In other words, if call \( P(u_1, ..., u_m) \) is the joint PDF of the displacements applied to the \( m \) daughter particles in a cloud, we assume that \( P(u_1, ..., u_m) \) is the same for all clouds and is invariant under any permutation of the \( m \) displacement variables. This implies in particular that \( p_s(u, v) = p_s(v, u) \) and, as we show below, important constraints on the displacement-displacement correlations inside a single cloud. We clearly also have the consistency condition

\[
\int d^d v p_s(u, v) = p(u).
\]

With these assumptions it is simple to show that it follows from Eq. (8) that

\[
|\tilde{\rho}(k)|^2 = N + N(m - 1) \tilde{p}_s(k, -k) + m^2 |\tilde{p}(k)|^2 \sum_{i \neq j}^{1, M} e^{-ik \cdot (x_i - x_j)},
\]

where \( \tilde{p}_s(k, -k) = FT[p(u)] \) (i.e. the characteristic function of the single stochastic displacement) and \( \tilde{p}_s(k, -k) \) is the following diagonal two-point FT of \( p_s(u, v) \):

\[
\tilde{p}_s(k, -k) = \int d^d u d^d v p_s(u, v) e^{-ik \cdot (u - v)}.
\]

Note that

\[
\tilde{p}_s(k, -k) = \tilde{\phi}_s(k) = \int d^d w \phi_s(w) e^{-ik \cdot w},
\]

where \( \phi_s(w) \) is the PDF of \( n \)-th relative displacement \( w = (u - v) \) between two particles in the same cloud:

\[
\phi_s(w) = \int d^d u d^d v p_s(u, v) \delta(w - u + v).
\]

Since \( p_s(u, v) = p_s(v, u) \), \( \phi_s(w) \) is an even function of \( w \) and, as a consequence, \( \tilde{\phi}_s(k) \) is a real function. Further, from the fact that \( \phi_s(w) \) is a PDF, it follows that \( \tilde{\phi}_s(k = 0) = 1 \), and \( |\tilde{\phi}_s(k)| \leq 1 \) at all \( k \).

To perform the average \( \langle \ldots \rangle \) (over the realizations of the mother distribution), we use that

\[
\sum_{i \neq j}^{1, M} e^{-ik \cdot (x_i - x_j)} = \sum_{i,j}^{1, M} e^{-ik \cdot (x_i - x_j)} - M,
\]

and that from Eq. (2), for asymptotically large \( M \) (i.e. for \( V \to \infty \) with \( n_0 \) fixed), one has

\[
\langle \sum_{i,j}^{1, M} e^{-ik \cdot (x_i - x_j)} \rangle = M \left[ S_n(k) + (2\pi)^d n_0 \delta(k) \right].
\]

Using these results, together with \( N = mM \) and \( \rho_0 = mn_0 \), we finally obtain

\[
S_\rho(k) = 1 + (m - 1) \tilde{\phi}_s(k) - m |\tilde{\rho}(k)|^2 + m |\tilde{p}(k)|^2 S_n(k).
\]
This is the principle result of this section. It is useful to write it also in the form

\[
S_p(k) = S_{\rho}^{(0)}(k) + m|\tilde{p}(k)|^2S_m(k).
\]

(9)

where

\[
S_{\rho}^{(0)}(k) = 1 + (m - 1)\tilde{\phi}_s(k) - m|\tilde{p}(k)|^2
\]

(10)

depends only on the statistical properties of the displacement fields (i.e. independent of those of the mother distribution).

We note that for the case \(m = 1\) Eq. (8) reduces to

\[
S_1(k) = 1 - |\tilde{p}(k)|^2 + |\tilde{p}(k)|^2S_0(k).
\]

(11)

This is precisely the equation derived in [1, 2] for the transformation of the PS of a point particle distribution from \(S_0(k)\) to \(S_1(k)\) when each particle is randomly displaced, independently of the others, with a PDF \(p(u)\) for the single random displacements.

Another simple case is that in which the mother particle distribution \(n(x)\) is itself completely uncorrelated with \(h_n(x) = 0\), i.e., generated by a homogeneous Poisson process. Then \(S_n(k) = 1\) and consequently Eq. (8) gives

\[
S_{\rho}(k) = 1 + (m - 1)\tilde{\phi}_s(k),
\]

Since \(\tilde{\phi}_s(k \to 0) = 1\) it follows that \(S_{\rho}(k \to 0) = m\), i.e., at large scales the cloud process is identical to the original distribution (up to a change in the mean particle density by the factor \(m\)). This simply translates the fact that if a point process has no correlation, we cannot create correlation at large scales by dividing the particles into clouds by a stochastic process which incorporates no correlation between the different clouds.

A. Properties of \(S_{\rho}(k)\)

By definition any SF, and therefore the one we have derived, must satisfy the conditions

\[
\begin{align*}
S_{\rho}(k) & \geq 0 \quad \text{(12)} \\
S_{\rho}(k \to \infty) & = 1. \quad \text{(13)}
\end{align*}
\]

These must hold for any input \(S_n(k)\) (itself obeying these properties) and any finite value of \(m\).

The second property Eq. (13) is simple to verify. It follows from the fact that both \(\tilde{\phi}_s(k)\) and \(|\tilde{p}(k)|\) vanish in the large \(k\) limit. This is the case because they are FTs of functions which are integrable at the origin.

That the first property Eq. (12) must be satisfied by our result is trivial: we obtained \(S_{\rho}(k)\) by simply averaging Eq. (8) which is non-negative definite by construction. However, as we now discuss, it is not simple as one might anticipate to verify it directly from Eq. (8). The property Eq. (12) in fact encodes in a concise and very non-trivial manner constraints on the joint PDF \(p_s(u, v)\) which follow from the assumption that it is unique for any two particles in a cloud.

Firstly we note that Eq. (12) holds in fact if and only if

\[
S_{\rho}^{(0)}(k) \geq 0
\]

(14)

for all \(k\). This is the case because Eq. (12) must be true for an arbitrary \(S_n(k)\), and it is always possible to choose a mother point process for which it vanishes at any given \(k\) (taking, e.g., an appropriate regular lattice). For \(m = 1\) this condition is trivially satisfied, as \(|\tilde{p}(k)| \leq 1\) by definition (as FT of a PDF). For \(m \geq 2\) it may be rewritten as the condition

\[
\tilde{\phi}_s(k) \geq -\frac{1}{m - 1} + \frac{m}{m - 1}|\tilde{p}(k)|^2 > -1
\]

(15)

This does not trivially follow from the fact that \(\tilde{p}(k)\) and \(\tilde{\phi}_s(k)\) are FT of PDFs. As noted above, the latter gives only the weaker condition \(\tilde{\phi}_s(k) \geq -1\). Clearly Eq. (15) encodes a non-trivial constraint on \(\tilde{\phi}_s(k)\), arising from the fact that it is related to a PDF for the joint displacement PDF. The latter is not simply an arbitrary normalizable function. The condition Eq. (15) tells us that we have in fact constrained it mathematically by the assumption about it we have made in our derivation: we have assumed that the cloud is generated in such a way that the joint two-displacement PDF is identical for all couples of particles.

To illustrate this more explicitly we derive now the form taken by the constraint, in the form of Eq. (14), when \(S_{\rho}^{(0)}(k)\) is expanded in Taylor series around \(k = 0\). Such an expansion can be made assuming that both \(p(u)\) and \(\phi_s(w)\) are rapidly decreasing at large \(u\) and \(w\) so that their FT are analytic at \(k = 0\). We then have

\[
\tilde{p}(k) = \sum_{l=0}^{\infty} (-i)^l \frac{|k \cdot u|^l}{l!}.
\]

(16)

and

\[
\tilde{\phi}_s(k) \equiv \tilde{p}_s(k, -k) = \sum_{l=0}^{\infty} (-i)^l \frac{|k \cdot w|^l}{(l)!}.
\]

(17)

The condition (14) can therefore be rewritten as

\[
S_{\rho}^{(0)}(k) = \sum_{l=1}^{\infty} \frac{(-i)^l}{l!} \left\{(m - 1)\frac{|k \cdot (u - v)|^l}{l!} - m \sum_{l'=0}^{l} \frac{\left(\frac{l}{l'} \right)}{\left|\frac{k \cdot u}{l'}\right|^{l-l'} \times \left|\frac{k \cdot v}{l'}\right|^l} \right\} \geq 0,
\]

(18)

where we have written explicitly \(w = (u - v)\) and used the symmetry assumption \(\frac{|k \cdot v|^l}{\frac{k \cdot u}{l}} = \frac{|k \cdot w|^l}{\frac{k \cdot v}{l}}\) for any \(j\). This inequality, valid for all \(k\), fixes all the constraints on the two-displacement correlation function in any cloud.
Using again the fact that \( \phi_s(w) = \phi_s(-w) \), and making the further assumption that \( p(u) = p(-u) \), all the odd power terms in this expression vanish so that we obtain:

\[
S^{(0)}_\rho(k) = \sum_{l=1}^{\infty} \frac{(-1)^l}{(2l)!} \left\{ (m-1)[k \cdot (\mathbf{u} - \mathbf{v})]^{2l} - m \sum_{l^\prime = 0}^{l} \frac{2l}{2l^\prime} (k \cdot \mathbf{u})^{2l - 2l^\prime} \frac{(k \cdot \mathbf{v})^{2l^\prime}}{(2l^\prime)!} \right\} \geq 0.
\]

The leading term dominates at sufficiently small \( k \) and therefore has to be non-negative. This implies the following constraint on the correlations of any two displacements in the set of \( m \) correlated random displacements in each cloud: the matrix

\[
c_{\mu\nu} \equiv (m-1)u^{(\mu)}v^{(\nu)} + u^{(\mu)}u^{(\nu)},
\]

where \( \mu, \nu = 1, \ldots, d \), has to be non-negative definite. In our analysis in the next section, of the case that the mother distribution is a lattice, we will see how this constraint, and ones which can derived at subsequent order in this expansion, simplify and are explicitly verified in certain cases.

B. Behaviour at small \( k \)

Let us now consider specifically the properties of the SF of the mother and daughter distributions as \( k \to 0 \).

We note first that, because of the normalization conditions on the PDFs of the displacements, both \( \tilde{\phi}_s(k) \) and \( |\tilde{p}(k)| \) converge continuously to unity as \( k \to 0 \). It follows from Eq. (10) that \( S^{(0)}_\rho(k \to 0) \sim k^\alpha \), where \( \alpha > 0 \). Supposing now that the initial (mother) point distribution has \( S_n(k \to 0) \sim k^\gamma \), where \( i \gamma = \gamma \) for \( \gamma \leq 0 \), and \( ii \gamma = \min\{\gamma, \alpha\} \) for \( \gamma > 0 \).

Thus the exponent of the SF around \( k = 0 \) can never be larger in the cloud process than in the original mother point process. Further it may differ from it (in which case it is smaller) only if \( S_n(k = 0) = 0 \). Note that these conclusions hold independently of any assumption about the cloud process, other than that there is no correlation between the displacement sets creating different clouds and that the displacements are symmetrically distributed as shown above. This result may be explained more physically as follows. The exponent of the small \( k \) behavior of the SF can be considered as a measure of the degree of order in the stochastic point process at asymptotically large scales [13,17]. The greater the exponent the more ordered is the distribution. Indeed any lattice, which is the class of the most ordered particle distributions, the SF vanishes identically around \( k = 0 \), i.e., we can consider it to correspond to the behaviour \( k^\infty \). Clearly a cloud process, without any correlation between the arrangement of matter in the different clouds, cannot increase the degree of order. That it may, on the other hand, decrease the degree of order when the mother distribution has the property that \( S_n(k = 0) = 0 \), reflects the difference between this class of distributions and those with \( S_n(k = 0) > 0 \). Indeed this difference is that underlined by the classification of the former point processes as super-homogeneous (or hyper-uniform): the rapid decay of the density fluctuations at long wavelengths which characterizes them are the result of a delicate balance between small scale and large scale correlations in direct space. Indeed the condition \( S_n(k = 0) = 0 \) is explicitly an integral constraint on the two point correlation function over all space. The processes which we are considering, in which each particle “explodes” independently of all others, can break these global constraints by modifying only the small scale correlation properties. Instead for distributions with \( S_n(k = 0) \neq 0 \), which do not present such a correlation balance, such an uncorrelated re-distribution of matter at small scales cannot modify the nature of the system at large scales and also.

Let us now consider the problem of the construction of a point process with a target behavior of \( S(k \to 0) \). From the results we have just derived it follows that a cloud process of the type we have just analyzed, without correlations between the displacements of the members of different clouds, may be used to generate a distribution with the target exponent \( \alpha > 0 \) provided we start with \( \gamma > \alpha \). In practice we can start with \( \gamma = \infty \) by taking a regular lattice, for which \( S_n(k) = 0 \) identically in a finite region around \( k = 0 \) (specifically, in the first Brillouin zone). The generated distribution will then have the exponent \( \alpha \), which depends through Eq. (10) only on the statistical properties of the displacement fields. Since \( \alpha > 0 \) the generated process is necessarily superhomogeneous. The question we now address is what values of \( \alpha \) are attainable, and for what conditions on the number of daughters \( m \) and the displacement fields they are realized. We note that in [1] it has been shown that, for \( m = 1 \), one can realize by appropriate choice of \( p(u) \) any exponent in the range \( 0 < \alpha < 2 \). The upper bound \( \alpha = 2 \) results for any \( p(u) \) with a finite variance, while the lower exponents are realized for PDFs with appropriately divergent moments of displacements at order less than two. For the case of correlated displacements, with Gaussian statistics, it has been shown also in [1] (see also [19]) that a maximal value of \( \alpha = 4 \) may be attained. We will see now that, with an appropriate value of \( m \) and conditions on the displacement fields, arbitrarily large positive target value of \( \alpha \) are attainable. We will show that to obtain a certain value of \( \alpha \) requires that one fixes a sufficiently large number of mass moments of all clouds of particles with respect to their respective initial position on a regular lattice.

4 These can be classified into Poisson-like for \( S_n(k = 0) < +\infty \), and long-range correlated for \( S_n(k \to 0) \to +\infty \).
C. Explicit expansion around $k = 0$

For this study of the small $k$ behavior of $S_ρ(k)$ we consider the expansion of both $Φ_α(k)$ and $ρ_φ(k)$ in power series of $k$, which are given respectively by Eqs. (17) and (10). Using these expressions in Eq. (8) we obtain

$$S_ρ(k) = 1 + (m-1) \sum_{l=0}^{∞} (-i)^l \frac{(k \cdot (u - v))^l}{l!} + m \sum_{l=0}^{∞} (-i)^l \frac{(k \cdot u)^l}{l!} [S_n(k) - 1].$$ (21)

All these expressions are valid only under the assumption that all the moments in the sums are finite, while the derivation of Eqs. (8) and (10) required only the integrability of the probability distributions. If the probability distributions $p(u)$ and $Φ_α(w)$ have only a finite number of finite moments, the corresponding sums must be terminated at the appropriate order. There is then an additional term, of which the leading singular part can easily be determined. We will not discuss here the case in which there are such singularities \(^5\). The required generalization of the analysis described here is straightforward following the procedure defined in [1].

IV. UNCORRELATED CLOUD LATTICE

Given the above motivation we now analyze in detail the cloud processes in the previous section for the particular case that the mother particle distribution is a regular lattice, i.e.

$$n(x) = \sum_{R} δ(x - R),$$

where $R$ is the generic lattice site. In this case the SF of $n(x)$ is

$$S_n(k) = (2π)^d n_0 \sum_{H≠0} δ(k - H),$$ (22)

where the sum is over all the vectors $H$ of the reciprocal lattice but $H = 0$. Note that this vanishes identically in the first Brillouin zone, and therefore in this region of the $k$–space the following relation holds exactly:

$$S_ρ(k) = 1 + (m-1) \sum_{l=0}^{∞} (-i)^l \frac{(k \cdot w)^l}{l!} - m \sum_{l=0}^{∞} (-i)^l \frac{(k \cdot u)^l}{l!}$$

(23)

To simplify the presentation of our determination of the conditions required to have an arbitrary (analytic) small $k$ behavior of $S_ρ(k)$, we start with the one-dimensional case, for which Eq. (23) becomes

$$S_ρ(k) = 1 + (m-1) \sum_{l=0}^{∞} (-i)^l \frac{(u - v)^l}{l!} - m \sum_{l=0}^{∞} (-i)^l \frac{u^l}{l!}^2$$

(24)

where $u$ and $v$ are the displacements applied to two different particles belonging to the same cloud. First of all we see immediately, as above underlined, that the final particle distribution $ρ(x)$ is superhomogeneous, as the zero order contribution in $k$ to $S_ρ(k)$ vanishes identically for any choice of $p_ρ(u, v)$ [i.e. of $φ_α(u)$]. In the notation of the previous section, we have explicitly that $α ≥ 1$. We can write

$$\left| \sum_{l=0}^{∞} (-i)^l \frac{u^l}{l!}^2 \right|^2 = \sum_{l=0}^{∞} (-i)^l \sum_{j=0}^{l} (-1)^j \left( \frac{l}{j} \right) u^j \times v^{l-j},$$

where we have used $u$ and $v$ instead of only $u$ as the moments of the single displacement are the same for every particle. Moreover, by expanding the terms $(u - v)^l$ in Eq. (24), we have

$$\sum_{l=0}^{∞} (-i)^l \frac{(u - v)^l}{l!} = \sum_{l=0}^{∞} (-i)^l \sum_{j=0}^{l} (-1)^j \left( \frac{l}{j} \right) u^j \times v^{l-j}.$$ (25)

Therefore Eq. (24) becomes

$$S_ρ(k) = \sum_{l=1}^{∞} (-i)^l \sum_{j=0}^{l} (-1)^j \left( \frac{l}{j} \right) \times [u^j \times v^{l-j} - m u^j \times v^{l-j}]$$

Making the additional assumption of statistical symmetry in the displacements, $p(u) = p(-u)$, all the terms with odd $l$ in Eq. (25) vanish.

A. Order by order analysis and conservation of mass moments ($d = 1$)

Let us now analyze in detail Eq. (25), denoting by $O_ρ(k)$ its term proportional to $k^n$. Given our hypotheses the lowest order non-zero term is $n = 2$:

$$O_2(k) = \left[ u^2 + (m-1)u \times v \right] k^2.$$

It is simple to verify explicitly that $\left[ u^2 + (m-1)u \times v \right] ≥ 0$ always, as required (from the fact that $S_ρ(k)$ is a SF). First of all it is the one-dimensional version of the condition (20). This can be seen more directly as follows: if we denote by $u_i$ with $i = 1, ..., m$ the displacements applied respectively to the

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\(^5\) We will see below that to obtain exponents greater than four with uncorrelated clouds the PDFs for the displacements must, in fact, have compact support.
m daughter particles originating from the same mother (i.e. belonging to the same cloud), it is clear that

\[ \left( \sum_{i=1}^{m} u_i \right)^2 \geq 0. \]

This quantity, however, given our symmetry hypotheses about the displacements distribution is nothing other than

\[ \left( \sum_{i=1}^{m} u_i \right)^2 = m \left[ u^2 + (m-1)u \times v \right]. \]

Consequently the condition to have an identically vanishing \( O_2(k) \) term, and therefore a small k SF of order greater than two (i.e. \( \alpha > 2 \)), is \((\sum_{i=1}^{m} u_i)^2 = 0\), or in other words,

\[ \sum_{i=1}^{m} u_i = 0 \tag{26} \]

with probability one\(^6\). This means that the center of mass of each cloud does not move away from the mother particle when the displacements are applied. Clearly for \( m = 1 \) this condition can only be trivially satisfied by applying no displacement, in which case the daughter distribution is the original lattice distribution. For \( m = 2 \) it can be satisfied non-trivially: choosing the displacement of a first point with the PDF \( p(u) \), the other particle is then displaced deterministically by \(-u\). For \( m > 2 \) the condition can be satisfied while admitting a higher degree of stochasticity: it fixes deterministically the displacement of only one particle among \( m \) once the other \((m-1)\) are chosen stochastically.

The analysis of the term \( O_4(k) \) is more complex. We will now show that the condition for it to vanish is one on the second moment of the mass dispersion of each cloud. Directly from Eq. \( (25) \) we have

\[ O_4(k) = -\frac{k^4}{12} \left[ u^4 + 4(m-1)u^2v - 3(m-1)u^2v^2 + 3m\sigma^4 \right] \tag{27} \]

where we have denoted \( \sigma^2 = u^2 \) and again used the assumed symmetries of the displacement field. If the term of \( O_2(k) \) vanishes at all k, i.e., if Eq. \( (26) \) is satisfied for each cloud, then the \( O_4(k) \) term must be non-negative [since the SF \( S_p(k) \) must be non-negative at all k]. Thus the coefficient of \( k^4 \) in Eq. \( (27) \) must be non-negative. In order to show that this is indeed the case we note first that Eq. \( (26) \) implies that

\[ u_i^2 \sum_{i=1}^{m} u_i = u^4 + (m-1)u^2v = 0. \]

By using this relation in the coefficient of Eq. \( (27) \) we then have

\[ -4u^4 - 4(m-1)u^2v + 3(m-1)u^2v^2 - 3m\sigma^4 \]

\[ = 3u^4 + 3(m-1)u^2v^2 - 3m\sigma^4. \]

Further it is simple to show that

\[ 3m(u^4 + (m-1)u^2v^2 - m\sigma^4) \]

\[ = 3 \left[ \left( \sum_{i=1}^{m} u_i^2 \right)^2 - \left( \sum_{i=1}^{m} u_i^2 \right)^2 \right], \tag{28} \]

which is manifestly non-negative.

This result also gives the condition necessary in order to have both the \( O_2(k) \) and \( O_4(k) \) identically vanishing: once Eq. \( (26) \) for the conservation of the center of mass of each cloud of the system is assumed, in order to make the variance in Eq. \( (28) \) vanish one requires also that

\[ \sum_{i=1}^{m} u_i^2 = m\sigma^2 \tag{29} \]

for each cloud, with probability one.

In summary: in order to obtain with this algorithm a particle distribution with a SF of order larger than \( k^4 \) at small \( k \), one has to satisfy exactly the following two conditions:

- every cloud must have the same displacement of its center of mass from the initial point of the cloud or mother position [and, in particular, if \( p(u) = p(-u) \) the center of mass of the cloud must coincide with the position of the mother particle];
- every cloud must have the same inertial moment (or second moment of its mass dispersion) with respect to the initial point. The value of this inertial moment is fixed by the second moment of \( p(u) \) and \( m \) as \( m\sigma^2 \).

This analysis can be continued in order to determine the conditions needed to obtain a \( S_p(k) \) of order higher than \( k^{2n} \) at small \( k \), for any integer \( n \). The result is simply that in order to obtain this goal one has to fix the first \( n \) moments of the mass dispersion

\[ \sum_{i=1}^{m} u_i^j = c_j \quad \text{with } j = 1, \ldots, n \tag{30} \]

where the constants \( c_j \) are determined by the \( j \)-th moment of \( p(u) \) and \( m \) as \( c_j = m\sigma^j \). Clearly this gives \( n \) conditions and consequently one has to have at least \( m = n \) particles in each cloud in order to make the requirements given by Eq. \( (30) \) realizable. For \( m = n \) there may be a single non-trivial solution to the constraints, i.e., a unique choice of displacements. In this case the generated distribution will be a lattice with basis, with a SF which again vanishes in a finite region around \( k = 0 \).

\(^6\) Note that if we had allowed an asymmetric \( p(u) \) with a non-zero average value \( \overline{u} \) the same condition \( O_2(k) = 0 \) would have been written as \( \sum_{i=1}^{m} u_i = m\overline{u} \) for all the clouds.
For \( m > n \) the set of constraints may be satisfied (for some range of values of the constants \( c_j \)) while leaving free \((m-n)\) degrees of freedom. These may be then fixed stochastically, leading generally to a stochastic particle distribution \(^7\) with a leading non-zero term at \( O(\delta^{n+1}(k)) \).

For \( n = 2 \), for instance, we need at least two particles. In order to fix the center of mass of the pair at the lattice site, and its second mass moment to a given value \( c_2 \), clearly fixes deterministically the points to lie at \( \pm \sqrt{c_2} \).

Taking three particles one can instead satisfy the constraints fixing one degree of freedom stochastically: placing one point at \( u \) with probability \( p(u) \), the position \( u' \) of a second point is determined by solving the quadratic equation \((u')^2 + uu' + (u^2 - c_2/2) = 0\), and finally a third point is placed at \(- (u + u')\).

Note that the existence of a solution to the quadratic equation places a strict upper bound on \( u, u \leq \sqrt{2c_2/3} \). Thus the probability \( p(u) \) necessarily has finite support (and cannot in particular be Gaussian) which is proportional to \( \sqrt{c_2} \). It is clear that this is a general requirement for any algorithm of this kind producing a SF with a leading small \( k^n \) with \( n > 4 \): in order to make the coefficient of the \( k^4 \) term vanish the second moment of the mass dispersion of the cloud must be limited with probability one. Since the displacement of any particle contributes in proportion to its square, the probability of displacement larger than \( \sqrt{c_2} \) must be zero.

### B. Generalization to \( d > 1 \)

In dimensions higher than one the problem is essentially the same. The analysis is, however, considerably more complicated because of the vectorial nature of the displacements.

Let us first consider the conditions required to make the terms \( \mathcal{O}(k^2) \) and \( \mathcal{O}(k^4) \) vanish. Fixing the center of mass in \( d \) dimensions gives \( d \) scalar equations

\[
\sum_{i=1}^{m} u_i^{(\mu)} = 0
\]

where \( u_i^{(\mu)} \) is the \( \mu \)th (with \( \mu = 1, \ldots, d \)) component of the displacement of the \( i \)th particle of the cloud. To satisfy this condition non-trivially evidently requires that there are at least two particles in each cloud. Fixing the second moments of the mass dispersion of the cloud gives \( d(d + 1)/2 \) scalar equations, i.e., \( d \) equations of the form

\[
\sum_{i=1}^{m} \left[ u_i^{(\mu)} \right]^2 = a_{\mu\mu} > 0 \quad \text{for} \quad \mu = 1, \ldots, d
\]

with \( a_{\mu\mu} = m[u_i^{(\mu)}]^2 \), and \( d(d - 1)/2 \) equations of the form

\[
\sum_{i=1}^{m} u_i^{(\mu)} u_i^{(\nu)} = a_{\mu\nu} \quad \text{for} \quad 1 \leq \mu < \nu \leq d,
\]

with \( a_{\mu\nu} = mu_i^{(\mu)}u_i^{(\nu)} \). Therefore to obtain a SF \( S_\rho(k) \) of order larger than the fourth at small \( k \) imposes \( [d + d(d + 1)/2] = d(d + 3)/2 \) scalar constraints on the displacements. This counting of constraints may be continued to higher orders, determining the number of conditions \( \mathcal{N}(n, d) \) which must be satisfied to obtain, in \( d \) dimensions, an \( S_\rho(k) \) vanishing faster than \( k^{2n} \) at small \( k \).

Noting that all the moments of given order, say \( l \), of the mass dispersion constitute a fully symmetric \( l \)-rank tensor in \( d \) dimensions, which has \( \binom{d + l - 1}{d - 1} \) independent components, we find

\[
\mathcal{N}(n, d) = \sum_{l=1}^{n} \left( d + l - 1 \right)
\]

Generalizing the reasoning for the case \( d = 1 \), one might then be tempted to conclude that, since each particle brings \( d \) degrees of freedom, the minimal number \( m \) of particles per cloud required to give a \( S_\rho(k) \) of order larger than \( 2k^n \) at small \( k \) is \( \mathcal{N}(n, d)/d \). This conclusion is, however, not correct in that it tells us the number of particles required to satisfy such conditions for arbitrary physical values of the mass moments. To make the coefficients in the expansion of \( S_\rho(k) \) vanish up to some order, while remaining non-vanishing at subsequent orders, we require only that a number of particles sufficient to allow us fix a set of physical values of the mass moments up to a certain order, while allowing higher moments to vary. Put another way, by imposing additional symmetries or constraints on the PDF of the displacements, we can reduce the number of non-trivial constraints (i.e., equations), reducing the others to simple identities. The following example illustrates this point trivially: in \( d > 1 \) we can always make a cloud lattice by putting together at infinite number of one dimensional cloud lattices, i.e., by constraining the displacements of the particles to lie along a chosen axis of the lattice. The calculation in \( d = 1 \) then remains valid, as all the additional constraints on the mass moments of the clouds with components in orthogonal directions are trivially satisfied. The same is true in fact if the displacements are in an arbitrary (but fixed) direction.

One can also evidently consider less radical “dimensional reductions”, taking in \( d \) dimension the displacements of particles in each cloud only in a hyperplane of dimension smaller than \( d \).

Even without such a reduction to a lower dimensional problem, it is easy to give examples in \( d > 1 \) which satisfy the constraints required to make all terms of the SF up to a certain order \( 2n \) vanish, with much less than \( \mathcal{N}(n, d)/d \) particles, and which do not have the feature

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\(^7\) Here we mean by “stochastic” that there is a non-empty compact domain of \( k \)-space in which \( S_\rho(k) \) is continuous and strictly positive.
of the above examples of breaking the statistical spatial isotropy of the clouds. Consider, for example, the case that each cloud contains an even number of particles, arranged symmetrically with respect to the center of mass. From the derivation we have given above, it follows immediately that \( S_\rho(k) \propto k^{\gamma} \) at small \( k \) with \( \gamma \geq 4 \) (as the inversion symmetry gives automatically the conservation of the centre of mass). As shown above the coefficients of the term proportional to \( k^4 \) will vanish if the second order moments of the mass distribution are cloud-independent. This can be attained, for example, in \( d \) dimensions, by taking \( d \) pairs of particles arranged symmetrically about, and equidistant, from the origin, and all mutually orthogonal. This gives a second moment of the mass dispersion of the cloud which is proportional to the identity matrix, and therefore invariant under a random rotation \( R \in SO(d) \) of the whole configuration. Further it is possible to show (see Appendix A for detail) that, because of the imposed inversion symmetry, the terms proportional to \( k^6 \) vanish identically. Thus, placing such a cloud with an orientation chosen randomly at each site, one obtains a leading non-zero term of order \( k^8 \). This term is non-zero because the (tensor) fourth mass moment is not invariant under rotation of the configuration. Further, if the stochastic process determining the orientation is statistically isotropic, the SF at small \( k \) reflects this isotropy and is a function of \( k \) only (rather than the vector \( \mathbf{k} \)). It is simple to check that the number of required particles for this algorithm \( 2d \) is less, for any \( d \), than the number \( N(3, d)/d \) given above.

V. CORRELATED CLOUDS

We now consider the case in which also displacements applied to particles belonging to different clouds may be arbitrarily correlated. In the notation introduced above for the joint PDFs of the displacements, this means that we now assume, at least for some separation of mother particles \( \mathbf{x} \), that \( p_d(\mathbf{u}, \mathbf{v}; \mathbf{x}) \neq p(\mathbf{u})p(\mathbf{v}) \). Further we make the following natural assumptions:

\[
\lim_{x \to \infty} p_d(\mathbf{u}, \mathbf{v}; \mathbf{x}) = p(\mathbf{u})p(\mathbf{v}). \tag{31}
\]

We have, of course, also the consistency condition

\[
\int d^d \mathbf{v} p_d(\mathbf{u}, \mathbf{v}; \mathbf{x}) = p(\mathbf{u}) \quad \forall \mathbf{x} \tag{32}
\]

Note also that, strictly speaking, the displacement field is not continuous as a function of spatial separation because the correlation \( \mathbf{u} \cdot \mathbf{v}(\mathbf{x}) \) between two displacements applied to two spatial point at vector distance \( \mathbf{x} \) in general does not converge to \( \mathbf{u}^2 \) for \( \mathbf{x} \to 0 \). The natural choice for this limit is \( p_d(\mathbf{u}, \mathbf{v}; \mathbf{x} \to \mathbf{0}) = p_s(\mathbf{u}, \mathbf{v}) \). How precisely this limit is taken will not, however, be of importance for our main application concerning a regular lattice distribution of the centers of the clouds, as in this case the distance between two different centers is always different from zero.

In order to find the expression for \( S_\rho(\mathbf{k}) \), once \( S_n(\mathbf{k}) \) and \( p_d(\mathbf{u}, \mathbf{v}; \mathbf{x}) \) are given, we have to go back to Eq. (6). From this it is simple to show that

\[
\frac{[\hat{\rho}(\mathbf{k})]^2}{N} = 1 + (m-1)\hat{\rho}_s(\mathbf{k}, -\mathbf{k}) + m^2 \sum_{i \neq j} e^{-ik \cdot (\mathbf{x}_i - \mathbf{x}_j)} \hat{\rho}_d(\mathbf{k}, -\mathbf{k}; \mathbf{x}_{ij}),
\]
where $x_{ij} = x_i - x_j$ and
\[
\tilde{p}_d(k, -k; x) = \int d^du \int dv \ p_d(u, v; x)e^{-ik(u-v)}.
\]

Note that, analogously to $\tilde{p}_s(k, -k)$, the function $\tilde{p}_d(k, -k; x)$ is the characteristic function of the stochastic vector $w(x) = u(x) - u(0)$, i.e., of the difference between the displacements applied to two particles belonging to clouds whose mother particles are separated by $x$. In other words, if $\phi_d(w; x)$ is the PDF of $w(x)$, we have
\[
\tilde{p}_d(k, -k; x) = \tilde{\phi}_d(k; x),
\]
where $\tilde{\phi}_d(k; x) = FT[\phi_d(w; x)]$. In order to perform the average $\langle \cdots \rangle$, we recall that in general for any function $f(x, y)$ of two spatial variables one has
\[
\left\langle \sum_{i \not= j} f(x_i, x_j) \right\rangle = n_0^2 \int_{V} d^dx \ d^dy f(x, y) [1 + h_n(x - y)]
\]
where $h_n(x)$ is the two point correlation function as defined in Eq. (33). Using this relation, we obtain
\[
\left\langle \sum_{i \not= j} e^{-ik(x_i-x_j)}\tilde{\phi}_d(k; x_{ij}) \right\rangle = n_0^2 \int_{V} d^dx \ d^dy \ e^{-ik(x-y)}\tilde{\phi}_d(k; x-y) [1 + h_n(x-y)].
\]
(33)

Taking the limit $V \to \infty$ with $N/V = \rho_0$ and $m \geq 2$ fixed, we arrive at our result:
\[
\tilde{S}_0(k) = 1 + (m - 1)\tilde{\phi}_s(k) + \rho_0 \int d^dx \ e^{-ik \cdot x} \tilde{\phi}_d(k; x) [1 + h_n(x)] - (2\pi)^d \rho_0 \delta(k).
\]
(34)

Note that the case $m = 1$ can be included in Eq. (34) by considering, only for this value of $m$, $p_d(u, v; x)$ to be spatially continuous, i.e., converging to $p(u; v - v)$ for $x \to 0$. The result Eq. (34) for $m = 1$ then agrees exactly with the analogous equation found in [1] for the PS of a particle distribution after the application of a correlated displacement field.

We will not analyse here the small $k$ expansion of Eq. (34), but simply note that such an analysis can be done easily by following the steps for the study of the similar equation for the case $m = 1$ in [1].

Let us now give the special expression of Eq. (34) for the specific case in which $n(x)$ is a regular lattice point distribution.

A. Correlated cloud lattice

When $n(x)$ is a regular lattice
\[
h_n(x) = \frac{1}{n_0} \sum_{R \not= 0} \delta(x - R) - 1,
\]
where $R$ runs over all the lattice vectors except $R = 0$. We therefore have
\[
\tilde{S}_0(k) = 1 + (m - 1)\tilde{\phi}_s(k) + m \sum_{R \not= 0} e^{-ik \cdot R} \tilde{\phi}_d(k; R) - (2\pi)^d \rho_0 \delta(k).
\]
(35)

This formula is a good starting point for the study of the small $k$ behavior of $S_0(k)$ for a cloud lattice for different choices of $p_d(u, v; R)$ and $m$. We now use the following chain of identities to rewrite Eq. (34) in a more useful form:
\[
(2\pi)^d \rho_0 \delta(k) = (2\pi)^d \rho_0 \left[ \sum_{H} \delta(k - H) - \sum_{H_0} \delta(k - H) \right]
\]
\[
= m \sum_{R} e^{-ik \cdot R} - m S_n(k),
\]
(36)

where we have used the definition (22) of $S_n(k)$ for a regular lattice and the lattice identity
\[
\sum_{R} e^{-ik \cdot R} = (2\pi)^d \rho_0 \sum_{H} \delta(k - H).
\]
(37)

By using Eq. (36), we rewrite Eq. (35) as
\[
S_0(k) = (m - 1) \tilde{\phi}_s(k) - 1 + m \sum_{R \not= 0} e^{-ik \cdot R} \tilde{\phi}_d(k; R) - 1 + m S_n(k).
\]
(38)

Note that $S_n(k)$ vanishes identically in the first Brillouin zone, so that it does not contribute to the small $k$ expansion of Eq. (35). Therefore, assuming all the moments of the displacements to be finite, in this region of $k$–space we can write
\[
S_0(k) = (m - 1) \sum_{l=1}^{\infty} (-i)^l \frac{[k \cdot w_s]^l}{l!}
\]
\[
+ m \sum_{R \not= 0} e^{-ik \cdot R} \sum_{l=1}^{\infty} (-i)^l \frac{[k \cdot w_d(R)]^l}{l!},
\]
(39)

where we have denoted, respectively, $w_s$ the relative displacement of two different particles belonging to the same cloud, and $w_d(R)$ the relative displacement of two particles belonging to two clouds whose centers are separated by the lattice vector $R$. From this formula we can deduce the conditions on the two-displacement correlations to have a given small $k$ SF for the resulting particle distribution.

B. Example: lattice of random correlated dipoles

Let us consider the following example as an application of Eq. (39). Each particle on a perfect lattice is split
into two particles, and the following displacements are applied:

\[ u_1(R) = +\eta(R), \quad u_2(R) = -\eta(R) \quad (40) \]

where \( \eta(R) \) is a random vector at each \( R \) specified by a lattice translationally invariant correlated stochastic process. The average over all the realizations of the displacements of a function \( X(\{\eta(R)\}) \) of the displacements may be written as the functional integral

\[ X = \prod_R \int d^d\eta(R) \mathcal{P}(\{\eta(R)\}) X(\{\eta(R)\}). \quad (41) \]

We assume that the joint probability density function of all the displacements \( \mathcal{P}(\{\eta(R)\}) \) is invariant under any lattice translation. Moreover it is simple to show, given our symmetry assumption for the displacements, that we can take \( \mathcal{P}(\{\eta(R)\}) \) to be invariant under the change of sign of any individual \( \eta(R) \). This ensures that \( \rho_d(u,v;x) \) is well-defined as required in our derivation, i.e., the joint probability for displacements to two particles at different sites is the same for all couples, and depends only on their relative separation. With this assumption it follows that all odd powers \( \ell \) in the sums in Eq. (42) vanish. Calculating the contribution at second order in \( k \) we have

\[ |k \cdot w| = 4|k \cdot \eta|^2 \quad (42) \]

and

\[ |k \cdot w_d(R)| = \int d^d\eta(0) d^d\eta(R) \rho_d(\eta(0), \eta(R); R) \times |k \cdot (\eta(0) - \eta(R))|^2 = 2|k \cdot \eta|^2. \quad (43) \]

The latter results uses the fact that the two point correlation function \( \eta(0) \cdot \eta(R) = 0 \), because of the assumed inversion symmetry. Using these results in Eq. (49) together with the identity Eq. (47) one finds that the two contributions cancel in the first Brillouin zone to give zero.

At next non-trivial order, fourth order in \( k \), we find

\[ |k \cdot w| = 16|k \cdot \eta|^4 \quad (44) \]

and

\[ |k \cdot w_d(R)| = \int d^d\eta(0) d^d\eta(R) \rho_d(\eta(0), \eta(R); R) \times |k \cdot (\eta(0) - \eta(R))|^4 = 2|k \cdot \eta|^4 + 6|k \cdot \eta(0)|^2|k \cdot \eta(R)|^2. \quad (45) \]

Using again the identity Eq. (47), we obtain the leading non-trivial contribution to the PS which may be written

\[ S_{\alpha}(k) \approx \frac{1}{2} k_\alpha k_\beta k_\gamma k_\delta \sum_R e^{-ik \cdot R} \eta_\alpha(0) \eta_\beta(0) \eta_\gamma(R) \eta_\delta(R), \quad (46) \]

where we adopted the sum convention on the repeated index \( \alpha, \beta, \gamma, \delta \). The sum over \( R \) is just the FT (on the lattice) of a two point correlation function, the behavior of which as \( k \to 0 \) depends on the nature of these correlations. The leading small \( k \) behaviour of the SF will depend on that of the sum. If the correlations of the dipoles are short-range, the sum converges to a positive constant at small \( k \), giving a leading behaviour proportional to \( k^4 \). If, on the other hand, they are long range correlated, this sum will diverge as a power-law at small \( k \), with an exponent less than that of the dimension of the space. This will lead to behaviour of the overall SF proportional to \( k^\gamma \) with \( 4 - d < \gamma \leq 4 \). Finally, if the correlations of the dipoles have themselves superhomogeneous properties\(^8\), one can obtain such a behaviour with \( \gamma > 4 \).

### VI. SUMMARY AND DISCUSSION

In this paper we have introduced and analyzed a wide class of non-trivial stochastic point processes for which it is possible to write exactly the two-point correlation function and/or SF. They are obtained from a given “mother” particle distribution, the SF of which is assumed known, by substituting each particle with a cloud of a fixed number \( m \) of other particles. The position of the new particles composing the clouds is determined by that of the related mother particle plus a stochastic displacement vector. An important assumption in all our calculations of the SF is that the stochastic process determining the displacements of the particles is independent of the mother distribution, i.e., the displacements of the cloud particles do not depend on the properties, statistical or otherwise, of the mother distribution to which they are applied. In practice this means that our SF is defined with respect to an ensemble average over two independent ensembles: one describing the realizations of the mother distribution, the other those of the displacement process.

We have distinguished two cases in which: (i) only the displacements of different particles belonging to the same cloud may be correlated, and (ii) the displacements of particle belonging to different clouds may also be statistically dependent. In both cases we obtain a direct generalization of the relations found in [1] for \( m = 1 \). In the first case, once the average over realizations is taken, the SF of the final particle distribution is related to the SF of the mother distribution by a local relation in the wave vector \( k \), while the second case leads to a more complex relation. A detailed analysis of case (i) led us to find and to discuss, in the case of an initial lattice mother distribution, the relations linking the ex-

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\(^8\) Note that, as the functions \( \eta_\alpha(0) \eta_\beta(0) \eta_\gamma(R) \eta_\delta(R) \) for \( \alpha = \beta \) and \( \gamma = \delta \) are non-negative at all \( R \), their lattice Fourier transforms can vanish at \( k = 0 \) only if they are identically zero for all \( R \).
ponent of the final SF to the number of conserved mass moments in each cloud: we have seen that such an exponent, if larger or equal to 4, tells us directly which are the locally conserved mass moments in the distribution. When we move to case (ii), the presence of cloud-cloud displacement correlations “interact” with the local mass moments conservation in determining the small $k$ behavior of the SF of the particle distribution.

One application we have in mind of the results derived here for this class of “stochastically ordered” point processes is in the systematic study of the dynamics of particle systems driven by long range pair interactions. More specifically, in the case of gravity, it is expected (see, e.g., [8]) that the large scale fluctuations in an infinite particle system dominate the dynamics of the gravitational clustering for an initial SF with a small $k$ behaviour proportional to $k^3$ and $\gamma < 4$. This “hierarchical” behavior has been observed numerically for a range of such $\gamma$ proportional to $k^\gamma$ that the large scale fluctuations in an infinite particle system dominate the dynamics of the gravitational clustering for an initial SF with a small $k$ behaviour proportional to $k^3$ and $\gamma < 4$. This “hierarchical” behavior has been observed numerically for a range of such $\gamma$, up to a maximal value of $\gamma = 2$ (see [21] for a recent discussion, and further references). No study of the regime of initial conditions $\gamma > 4$ has been performed up to now, as no algorithm has been given in the literature, to our knowledge, which can generate such an initial condition.

It is expected that the gravitational clustering will be qualitatively different in this case, with structures being built up from smaller to larger scales. Indeed the reason why we expect such a difference can be understood easily in the context of our constructions here of such point processes. For $\gamma > 4$ the fluctuations in mass are so suppressed that gravity is effectively “screened” (at least in the initial conditions): in a multipole expansion of the mass far away from a given point in the “uncorrelated cloud lattice” only the leading moment varying from cloud to cloud will contribute (as the contributions from the moments which are fixed will cancel out). If this leading contributing moment is the second moment, this gives an effectively short-range force (decaying as the inverse of the fourth power of the distance).

Our analysis here has been limited to the case of “analytic” exponents for the SF derived from short tailed displacements probability density functions (PDF). In principle one can consider also the case in which such PDFs have a long power law tail. In this case a singular part of the small $k$ expansion of the related displacement characteristic function arises. This leads (see [1, 9]) to a final SF characterized by non-analytic (e.g. fractional) small $k$ exponents. We have seen, however, that in the uncorrelated cloud lattice, to attain powers larger than $\gamma = 4$ we must in fact take limited displacements, and thus we necessarily obtain “analytic” exponents (and, in fact, a analytic behaviour of the SF at small $k$). In the case of the correlated cloud lattice, nevertheless, we have given an example (random correlated dipoles) which shows how such non-analytic powers should be attainable by including appropriate correlations between the clouds.

We return finally to an important feature of Eq. (34) which we have discussed at some length in Sect. III. This is that the exponent in the small $k$ scaling behavior of $S_{\rho}(k)$ cannot be larger than that in $S_{\mu}(k)$. As we explained, this can be understood physically as it means that the replacements of particles by clouds cannot make the initial particle distribution more ordered. We underline, however, that this is true given the assumptions we have made, and specifically assuming that the stochastic process generating the clouds is independent of the mother distribution. In a forthcoming article with another collaborator we will report results on a related kind of construction of superhomogeneous point processes, starting from tilings of space with equal volume tiles. In this case it turns out that one can, in certain circumstances, ascribe a cloud of particles to each particle of a given point distribution and as a result increase the exponent $\gamma$. The reason why this becomes possible is that the displacements of the particles are not applied independently of the correlation properties of the underlying point process, as we have assumed here. Indeed in order to increase the exponent requires that the movements of the clouds are “tuned” appropriately to the tile in which the mother point lies. We note also that, in the case that the initial tiling is taken to be a lattice, the algorithm described coincides with that given here and similar results to those given here are recovered. Details will be reported in [23].

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APPENDIX A: SYMMETRIC CLOUD LATTICES

In this appendix we study the SF for an uncorrelated cloud process on a lattice, for the case that each cloud is symmetric with respect to its own lattice site.

The number density of such a particle distribution can be written as:

$$\rho(x) = \sum_{R} \sum_{j=1}^{m} \delta(x - R - u_j^{(R)})$$  \hspace{1cm} (A1)

where $R$ is the lattice site and $m$ is the number of particle per cloud. Since we consider symmetric clouds, $m$ is even and can be written as $m = 2p$ where $p$ is a positive integer. We consider initially a finite lattice with $M$ sites (occupying a corresponding finite volume $V$), and then send $M \to \infty$ at the end of calculations. Taking the FT of Eq. (A1), we have

$$\tilde{\rho}(k, V) = \sum_{R} \sum_{j=1}^{m} e^{-ik \cdot (R + u_j^{(R)})}$$.  \hspace{1cm} (A2)

Now we impose the inversion symmetry for the clouds with respect to their center of mass (i.e. the lattice site).
This means that for each particle at \((R + u)\) there is another particle placed at \((R - u)\). Therefore for each cloud we can count with \(j\) from 1 to \(p = m/2\) a set of particles which are not the symmetric image one of each other, and with \(p + j\) their respective symmetric images. Particles in a single cloud with \(1 \leq j \leq p\) can be arbitrarily correlated. Let us call as above \(R\) of particles which are not the symmetric image one of each other, and with \(p + j\) their respective symmetric images.

Imposing this symmetry of the clouds we can rewrite Eq. (A2) as

\[
\hat{p}(k, V) = 2 \sum_{R} e^{-ik \cdot R} \sum_{j=1}^{p} \cos(k \cdot u_j(R)) . \tag{A3}
\]

Then taking the squared modulus we obtain

\[
|\hat{p}(k, V)|^2 = 4 \sum_{R, R'} e^{-ik \cdot (R - R')} \sum_{i,j}^{1,p} \cos(k \cdot u_j(R)) \cos(k \cdot u_j(R'))
\]

\[
= 4 \sum_{R} \left\{ \sum_{j=1}^{p} \cos(k \cdot u_j(R))^2 \right\} + \sum_{i \neq j}^{1,p} \cos(k \cdot u_j(R)) \cos(k \cdot u_j(R'))
\]

\[
+ \sum_{R \neq R'} e^{-ik \cdot (R - R')} \sum_{i,j}^{1,p} \cos(k \cdot u_j(R)) \cos(k \cdot u_j(R')) \right\} \tag{A4}
\]

We can now take the average over the displacements. In order to do this we recall that we are assuming that the displacements related to particles belonging to different clouds are uncorrelated. Consequently the first and the third terms in Eq. (A2) have to be averaged over only \(p(u)\), while the second one as to be averaged over \(p_s(u, v)\) containing all the two-displacements correlators in a single cloud. This gives

\[
\langle |\hat{p}(k, V)|^2 \rangle = 4Mp \langle |\cos(k \cdot u)|^2 \rangle + 4Mp(p - 1) \langle \cos(k \cdot u) \cos(k \cdot v) \rangle
\]

\[
+ 12p^2 \sum_{R \neq R'} e^{-ik \cdot (R - R')} \langle \cos(k \cdot u) \rangle^2 \tag{A5}
\]

\[
= 2N \langle |\cos(k \cdot u)|^2 \rangle + N(m - 2) \langle \cos(k \cdot u) \cos(k \cdot v) \rangle
\]

\[
- Nm \langle \cos(k \cdot u) \rangle^2 + l.t. \tag{A6}
\]

which gives rise to the third term of the last step. Now we use the definition of the SF

\[
S_p(k) = \lim_{M \to \infty} \frac{\langle |\hat{p}(k, V)|^2 \rangle}{N} - (2\pi)^d \rho_0 \delta(k) ,
\]

which gives

\[
S_p(k) = 2 \langle |\cos(k \cdot u)|^2 \rangle + (m - 2) \langle \cos(k \cdot u) \cos(k \cdot v) \rangle
\]

\[
- m \langle \cos(k \cdot u) \rangle^2 + l.t. \tag{A7}
\]

It is simple to verify that, as expected, \(S_p(0) = 0\). We now expand Eq. (A6) in power series of \(k\) and study it order by order:

\[
S_p(k) = \sum_{a,b} \frac{(-1)^{a+b}}{(2a)!(2b)!} \left[ 2 \langle \cos(k \cdot u)^{2(a+b)} \rangle \right. \tag{A8}
\]

\[
+ (m - 2) \langle \cos(k \cdot u)^{2a} \rangle \langle \cos(k \cdot v)^{2b} \rangle - m \langle \cos(k \cdot u)^{2a} \rangle \langle \cos(k \cdot v)^{2b} \rangle \right]
\]

We see that only even powers of \(k\) are present. Let us call \(O_{2n}(k)\) the term of order \(2^n\) in the series above. We see immediately that

\[
O_{2}(k) = 0
\]

as all the clouds conserve the center of mass at their lattice site for symmetry. Therefore the first non trivial term is \(O_{4}(k)\), which after some manipulation can be written as

\[
O_{4}(k) = \frac{1}{2} \left[ \langle \cos(k \cdot u)^4 \rangle + (p - 1) \langle \cos(k \cdot u)^2 \rangle \langle \cos(k \cdot v)^2 \rangle \right.
\]

\[
- p \langle \cos(k \cdot u)^2 \rangle^2 \right] . \tag{A9}
\]

The next term is

\[
O_{6}(k) = - \frac{1}{12} \left[ \langle \cos(k \cdot u)^6 \rangle + (p - 1) \langle \cos(k \cdot u)^4 \rangle \langle \cos(k \cdot v)^2 \rangle \right.
\]

\[
- p \langle \cos(k \cdot u)^4 \rangle \langle \cos(k \cdot u)^2 \rangle \right] . \tag{A10}
\]

Both terms are in general non-zero. In order to find the condition for \(O_{4}(k)\) to vanish, we rewrite it as

\[
O_{4}(k) = \frac{1}{2} \left\{ \left[ \langle \cos(k \cdot u)^2 \rangle - \langle \cos(k \cdot u)^2 \rangle \right]^2 \right\}
\]

\[
+ (p - 1) \left\{ \left[ \langle \cos(k \cdot u)^2 \rangle - \langle \cos(k \cdot u)^2 \rangle \right]^2 \right\}
\]

In any cloud there are \(p = m/2\) stochastic displacements which constitute a closed set of \(p\) symmetrically correlated variables (i.e. the correlation between any pair of these displacement is constant and there is no correlation with displacements in other clouds). Since the correlation matrix of the random variables \(\langle (k \cdot u)^2 \rangle - \langle (k \cdot u)^2 \rangle\), with \(j = 1, ..., p\) in a single cloud, has to be, as all the correlation matrix of a set of random variables, positive definite (see above) we always have \(O_{4}(k) \geq 0\). This can be seen in a more intuitive way by noticing what follows:

\[
\left\{ \left[ \sum_{j=1}^{p} \langle (k \cdot u)^2 \rangle - \langle (k \cdot u)^2 \rangle \right]^2 \right\} = 2pO_{4}(k) \tag{A11}
\]
which is a variance and consequently manifestly non-negative. Equation (A11) also implies that $O_4(k)$ vanishes if and only if
\[
\left\langle \left( \sum_{j=1}^{P} [(\mathbf{k} \cdot \mathbf{u}_j)^2 - \langle (\mathbf{k} \cdot \mathbf{u}_j)^2 \rangle] \right)^2 \right\rangle = 0,
\]
i.e., if with probability 1 we have
\[
\sum_{j=1}^{P} (\mathbf{k} \cdot \mathbf{u}_j)^2 = p \langle (\mathbf{k} \cdot \mathbf{u})^2 \rangle.
\]
This is just the “conservation law” of the second moment of the mass dispersion of the clouds in the direction of $\mathbf{k}$. As the orientation of $\mathbf{k}$ is arbitrary, this means that, in order to have $O_4(k) = 0$ identically, the second moment of the mass of the clouds must be conserved as a tensor $I_{\mu\nu} = \sum_{j=1}^{P} u_{j\mu} u_{j\nu}$ with $\mu, \nu = 1, \ldots, d$.

We now analyze $O_6(k)$ which is given by Eq. (A9). First of all we note that
\[
\left\langle \left( \sum_{j=1}^{P} (\mathbf{k} \cdot \mathbf{u}_j)^4 \right)^2 \right\rangle = -12pO_6(k).
\]
But, as seen above, if $O_4(k) = 0$ the second sum in Eq. (A12) vanishes identically, and therefore we can conclude that when $O_4(k) = 0$ identically also $O_6(k) = 0$ automatically, and the dominant term in $S_\rho(k)$ becomes $O_8(k)$.

One can continue this analysis further and show, after some more involved algebra, that the dominant term in the small $k$ expansion of the SF is of order $k^{4n}$ with $n$ integer, and next order terms are proportional to $k^{4n+2q}$ with $q$ again an integer. The exponent $n$ depends on the order to which the moments of the mass dispersion of the clouds are conserved.

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