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Scattering by an oscillating barrier: Quantum, classical, and semiclassical comparison

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We present a detailed study of scattering by an amplitude-modulated potential barrier using three distinct physical frameworks: quantum, classical, and semiclassical. Classical physics gives bounds on the energy and momentum of the scattered particle, while also providing the foundation for semiclassical theory. We use the semiclassical approach to selectively add quantum-mechanical effects such as interference and diffraction. We find good agreement between the quantum and semiclassical momentum distributions. Our methods and results can be used to understand quantum and classical aspects of transport mechanisms involving time-varying potentials, such as quantum pumping.

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I. INTRODUCTION

Scattering dynamics involving periodic time-varying potentials is of fundamental importance to quantum transport physics and related applications in mesoscopic condensed matter physics. The quantum-mechanical treatment of an oscillating barrier was first studied by Büttiker and Landauer in order to understand electron tunneling times [1], and their work built on previous work on photon-assisted tunneling in superconducting diode junctions [2]. Since then several workers have developed theoretical tools for treating time-varying barrier or well potentials, for studying photon-assisted tunneling [3–5], quantum pumping [6], and electron scattering by intense laser-driven potentials [7]. These systems can display rich quantum and classical dynamics that include chaotic scattering and chaos-assisted tunneling [8–12], dynamical localization [13], and quantum interference [14].

Scattering by an amplitude-modulated potential barrier is of fundamental interest on its own, and it is also a building block for the more complex time-dependent potentials used in quantum pumping [15–17]. For example, the turnstile pump employs two potential barriers whose amplitudes oscillate $\pi/2$ out of phase from each other. Despite its technological promise of generating highly controlled and reversible currents at the single electron level [18], quantum pumping in normal mesoscopic conductors remains elusive [19,20] (though it has been recently observed in a hybrid superconducting system [21]).

Experimental systems based on ultracold atoms offer the possibility of conducting precision tests of quantum pumping theories, while avoiding the capacitive coupling and rectification effects that have plagued attempted solid state implementations [20]. Furthermore, the use of ultracold atomic gases allows control over the momenta of the pumped particles and the coherence of the gas, permits precision imaging of the transport [22] and velocity measurements, as well as the choice between Bose-Einstein and Fermi-Dirac statistics.

In this paper, we study classical, semiclassical, and quantum dynamics of one-dimensional scattering by an amplitude-modulated Gaussian barrier. Motivated by possible experimental implementations with ultracold atoms, our main theoretical results are based on calculations of the scattered momentum distribution for atomic wave packets of well-defined incident velocity, such as propagating Bose-Einstein condensates (BEC). By employing a semiclassical formalism, we start with the classical dynamics and selectively turn on quantum processes such as interference and diffraction. Our main results can be summarized as follows. (i) Classical physics gives bounds on the range of scattered momentum states. (ii) Semiclassical and full quantum calculations predict similar final momentum distributions. (iii) The heights of Floquet peaks, which are not easily predicted by quantum calculations, are explained quantitatively by the semiclassical method. Interestingly, the physical pictures for the scattering process are quite different for the semiclassical and quantum methods. The semiclassical approach interprets the discrete final momentum values as intercycle interference over multiple barrier oscillations, but with the relative amplitudes of these states determined by intracycle interference. In contrast, from the Floquet perspective of full quantum theory, the final momentum states can be viewed as sidebands of the initial momentum state.

The paper is structured as follows. We present our model in Sec. II, and in Sec. III display results of quantum and classical calculations for this model. Section IV explains the algorithm used for the semiclassical calculation, and Sec. V compares and discusses the semiclassical and full quantum methods. In Sec. VI, we show how the model and results of this paper can be tested experimentally with ultracold atoms. Section VII summarizes our main results. Appendices A and B fill in the details of the semiclassical algorithm, and Appendix C explains the range of scattered momenta based on a simpler potential.

II. MODEL

Our model is motivated by recent proposals [23,24] to simulate mesoscopic transport processes by studying ultracold atomic wave packets propagating in quasi-one-dimensional waveguides that scatter from well-defined, localized potentials. A laser beam, blue-detuned from an atomic resonance, and tightly focused at the center of the waveguide, can create a potential barrier with a Gaussian profile, its width determined by the laser spot size and its amplitude by the intensity of the laser.
We choose a one-dimensional (1D) Gaussian barrier, centered at the origin, whose amplitude is modulated sinusoidally at frequency \( \omega \), with potential energy \( U(x,t) \) given by

\[
U(x,t) = U_0[1 + A \sin(\omega t + \phi)]e^{-x^2/(2\sigma^2)).}
\]

(1)

\( U_0 \) is the average amplitude of the barrier, \( A \) is the relative modulation amplitude, \( \sigma \) is the standard deviation width of the barrier, and \( \phi \) is the phase of the modulation. The Hamiltonian describing particle motion and scattering from this potential is

\[
H = \frac{p^2}{2m} + U(x,t).
\]

(2)

We use wave packets with initial momentum \( p_0 > 0 \), centered at a point \( \bar{x} \) far to the left of the barrier, and whose position-space wave function is given by

\[
\Psi(x,t = 0) = F(x)e^{ip_0x},
\]

(3)

where \( F(x) \) is the envelope of the wave packet and is typically a Gaussian of width \( \beta \),

\[
F(x) = F_G(x) = \frac{1}{(2\pi\beta^2)^{1/4}} e^{-[(x-\bar{x})^2]/4\beta^2}.
\]

(4)

Alternatively, the envelope may have a Thomas-Fermi distribution of radius \( \beta \), such that

\[
F(x) = F_{TF}(x) = \begin{cases} \sqrt{\beta^2 - (x-\bar{x})^2}, & |x-\bar{x}| < \beta, \\ 0, & |x-\bar{x}| > \beta. \end{cases}
\]

(5)

The Thomas-Fermi and Gaussian envelopes are typical of BEC wave functions in strongly interacting and noninteracting limits, respectively. Unless otherwise noted, we employ wave packets that are much wider than the barrier width (\( \beta \gg \sigma \)), with packet width \( \beta \) sufficiently large such that \( \beta \gg 2\pi p_0/m_0\omega \), ensuring that many barrier oscillations occur while the packet interacts with the barrier.

In the rest of the paper, unless otherwise mentioned, we use \( U_0 = m = \hbar = 1 \), \( A = 0.5 \), \( \sigma = 10 \), and \( \beta = 300 \). The values of the incident momentum are in the range \( p_0 \approx 1-2 \), the oscillation frequency \( \omega \approx 0-0.2 \), and in most cases the phase, \( \phi \), is set equal to 0. In the case of a Gaussian packet, we select \( \bar{x} = -1500 \) to ensure separation of the initial packet from the barrier.

The choice of a theoretical unit convention based on \( \hbar = 1 \) and \( m = 1 \) is equivalent to selecting an arbitrary time unit \( t_u \) and a related length unit \( l_u = \sqrt{\hbar t_u/m} \), with \( \hbar = 1.054 \times 10^{-34} \text{ J s} \). The corresponding energy unit is \( E_u = \hbar /t_u \), while the mass unit is that of the particle, \( m_u = m \), and the momentum unit is \( p_u = \sqrt{\hbar m/t_u} \).

III. QUANTUM AND CLASSICAL CALCULATIONS

A. Quantum description

We consider both quantum-mechanical and classical descriptions of the scattering process. This dual framework allows us to distinguish the classical and quantum nature of a variety of scattering features.

Our quantum-mechanical approach is based on propagating the wave packet with the Schrödinger equation,

\[
\frac{-\hbar^2}{2m} \frac{\partial^2 \Psi}{\partial t^2} + U(x,t) \Psi = -i\hbar \frac{\partial \Psi}{\partial t},
\]

(6)

via a split-step operator method [25] that incorporates the time variation of the scattering potential \( U(x,t) \). The numerical calculation is done using a fast Fourier transform (FFT) in a parallelized routine in FORTRAN. With periodic boundary conditions implicit in the FFT, the spatial range \( R \) (typically \( \approx 8000 \) in dimensionless units) is chosen sufficiently large to allow the entire wave packet to interact with the barrier at \( R/2 \) without significant wraparound. The spatial grid density and the time step for propagation are both taken to be of the order of 0.1 in dimensionless units. The resulting momentum grid density \( 2\pi/R \approx 10^{-3} \) is more than sufficient to resolve the narrowest momentum space features that we encounter.

Figure 1 shows a quantum calculation of a Thomas-Fermi wave packet in position space at four separate times as it scatters from an amplitude-modulated Gaussian barrier. In order to show more details of the scattering, the packet width shown in this figure is intentionally more narrow than that used in the rest of the paper. The resulting transmitted and reflected wave packets show considerable structure, but with no clear pattern, except for some residual spatial oscillation suggesting some type of interference effect. While examining the scattering process in position space does not yield any simple clues regarding its dynamics, the momentum-space picture offers significantly more insight into the relevant physics.

To obtain the wave function in momentum space, at a chosen large time, \( t = t_f \), after the packet has moved away from the potential barrier, we compute the Fourier transform of \( \Psi(x,t_f) \):

\[
\tilde{\Psi}(p,t_f) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} e^{-ipx} \Psi(x,t_f) dx.
\]

(7)

We also compute the corresponding final-momentum probability density,

\[
\rho^f_{\Psi}(p_f) = |\tilde{\Psi}(p_f,t_f)|^2.
\]

(8)

Here, \( p_f \) is used to indicate momentum at the chosen final time. Also, we note that for sufficiently large times, such that
the packet has moved far from the barrier, the final momentum distribution is constant in time, while the momentum-space wave function is not.

A time-periodic potential produces energy and momentum sidebands to the incident carrier momentum state, which can be described by Floquet theory, the temporal analog of Bloch’s theorem. In our model, a wave packet is incident on the barrier with fixed group momentum \( p_0 \) and associated kinetic energy \( E_0 = p_0^2/(2m) \). Since we use spatially broad packets, the incident packet has a very narrow momentum spread. The interaction of the incident wave packet with the amplitude-modulated barrier produces a series of discrete momentum states separated in energy by \( \hbar \omega \). The allowed final-momentum states must obey the equation

\[
p_f(n) = \pm \sqrt{2m(E_0 + n\hbar \omega)}, \tag{9}\]

where \( n \) is any integer satisfying \( n \geq -E_0/\hbar \omega \), and with \((+\) and \((-\) corresponding to transmission and reflection, respectively.

Figure 2 shows the momentum-space distribution of the reflected and transmitted wave packets after scattering from the amplitude-modulated barrier. The results of the full quantum calculation show the regular “comb” of discrete momentum states consistent with Eq. (9). Figure 2 also plots the classical momentum-space distribution for a Gaussian ensemble of particles with the same initial momentum spread as the initial quantum wave packet (see next subsection for details). The classically allowed bounds for the final momentum roughly constrain the Floquet comb on both reflection and transmission, though we find that the comb often extends slightly past the classically allowed bounds. However, the amplitude of the teeth of the comb do not appear to have any obvious pattern, and only loosely follow the strength of the classical final-momentum distribution.

The semiclassical approach presented in Sec. IV and the Appendices will provide an alternative explanation for the positions of the teeth of the Floquet comb in terms of intercycle interference, and will provide an explanation for the relative amplitudes of the comb teeth in terms of intracycle interference.

### B. Classical description

The classical description of the scattering dynamics computes trajectories based on the Hamiltonian of Eq. (2). In the static limit, particles of incident energy above \( U_0 \) are transmitted, and those below are reflected. In contrast, scattering from an oscillating barrier leads to significant changes in the particle momentum distribution, as particles gain or lose energy with the rise and fall of the potential. The final outcome depends on the phase of the oscillation as the particle encounters the barrier, and must generally be computed numerically.

Our quantum and semiclassical calculations diminish the role of the phase of the barrier oscillation by studying Heisenberg-limited wave packets with a large position spread and a well defined momentum, so that many barrier oscillations occur while the wave packet is interacting with it. We mimic such wave packets in our classical approach by employing ensembles of particles with initial conditions whose position and momentum distributions, \( P_0^{\text{f}}(x) \) and \( P_0^{\text{f}}(p) \), match those of the quantum distributions:

\[
P_0^{\text{f}}(x) = |\Psi(x,t=0)|^2, \tag{10a}\]

\[
P_0^{\text{f}}(p) = |\tilde{\Psi}(p,t=0)|^2. \tag{10b}\]

Generally, our initial momentum distributions are sufficiently narrow that classical particles can begin with a fixed initial momentum, distributed along a line segment that substantially covers the width of the initial wave packet, with statistical weights \( P_0^{\text{f}}(x) \).

The distribution \( \tilde{P}_f(x_f) \) of final momenta \( p_f \) can be obtained by numerically integrating trajectories and grouping them in bins of final momentum to plot a histogram, as shown in Fig. 2 and Fig. 3(b). Alternatively, we can compute trajectories numerically to obtain the final momentum as a function of initial position \( x_0 \) and final time \( t_f, p_f = p(x_0,t_f) \), as shown in Fig. 3(a). We note that due to the periodicity of the barrier amplitude, \( p_f \) is a continuous periodic function of \( x_0 \), with period \( 2\pi \omega_0/\omega_0 \). Any such periodic function has a maximum and minimum, which define the classically allowed range of \( p_f \), as shown in Fig. 3. Furthermore, this periodicity means that many initial positions \( x_0^j(p_f,t_f) \) contribute to the final momentum distribution \( \tilde{P}_f(x_f) \). Each \( x_0^j(p_f,t_f) \) contributes to \( \tilde{P}_f(x_f) \) a term proportional to \( (\partial x_0^j/\partial p_f)|_{x_0=x_0^j(p_f,t_f)} \), so

\[
\tilde{P}_f(p_f) = \sum_j P_0^{\text{f}}(x_0^j(p_f,t_f))|\partial x_0^j/\partial p_f|. \tag{11}\]

Figure 3 shows the final classical momentum distribution \( \tilde{P}_f(p_f) \) computed by both the histogram method (solid line,
red online) and according to Eq. (11) (dashed curve, black online), as well as the final quantum momentum distribution. The maximum and minimum of \( p_f \) define the classically allowed region, with \( \partial p_f / \partial x_0 \) going to zero at these locations, and its reciprocal in Eq. (11) tending to infinity \([26]\).

When we compare the quantum calculation to this classical calculation [Figs. 2 and 3(b)] we see that the boundaries of the classically allowed region accurately define the region of momentum space in which Floquet peaks are large. Small peaks also appear outside but close to the classically allowed region. As we show in the semiclassical treatment of Sec. IV, these are the result of momentum-space tunneling (or diffraction) into the classically forbidden region.

We also find that the barrier oscillation frequency \( \omega \), an easily variable experimental parameter, can be used to control the concurrence of the classical and quantum calculations, with good agreement in the limits of very high and low frequencies. For a static barrier, or for extremely low frequencies, momentum conservation in classical and quantum theories ensures agreement. As the frequency is increased, keeping the initial packet unchanged, the agreement gets poorer [Figs. 3(b) and 4(b)]. The classical momentum distribution broadens, and the quantum distribution acquires a comb structure since Floquet peaks begin to resolve as their separations become greater than their widths (which depend inversely on the width of the initial packet in position space). This is the range of particular interest in this paper. At very high frequencies, the incident particles cannot respond fast enough to the modulation of the barrier, and so they effectively interact with the time average of the potential. The classically allowed region narrows, while in the Floquet picture, the spacing between the Floquet peaks increases [Fig. 4(c)]. When there is only one non-negligible Floquet peak remaining, it coincides with the classically allowed region, resulting again in good agreement between the two methods [Fig. 4(d)].

In order to quantify the comparison of the final quantum momentum distribution, Eq. (8), with the final classical momentum distribution, Eq. (11), we define a kind of final momentum-density correlation coefficient,

\[
\chi_{QC} = \frac{\int dp_f \tilde{P}_Q^*(p_f) \tilde{P}_C(p_f)}{\sqrt{\int dp_f [\tilde{P}_Q^*(p_f)]^2 \int dp_f [\tilde{P}_C(p_f)]^2}}.
\]  

FIG. 4. (Color online) Momentum distributions for fixed velocity of incident packet but for different values of \( \omega \). The correlation between classical and quantum distributions reflected in Fig. 5 is seen. Comparison of quantum (blue and above axis) and classical (green and below axis) momentum distributions for \( p_0 = 1.0 \) with \( \omega = 0.0.00263, 0.2, 0.8 \). Quantum and classical results are correlated for low and high values of \( \omega \), with significant differences appearing at intermediate values. These correlations are quantified in Fig. 5.
peaks in the quantum calculations remain mysterious. They will be explained using a semiclassical method described in the next section.

IV. SEMICLASSICAL DESCRIPTION

It is a general principle of quantum mechanics [27] that when in classical mechanics we add probabilities associated with different paths leading to the same final state as in Eq. (11), in quantum mechanics we add amplitudes. In the semiclassical approach, each amplitude is the square root of the classical density combined with a phase. In the present case, Eq. (11) is replaced by

$$\tilde{P}_{SC}(p_f) = |\tilde{\Psi}_{SC}(p_f, t_f)|^2,$$

with

$$\tilde{\Psi}_{SC}(p_f, t_f) = \sum_j F(x_0^{(j)}(p_f, t_f))|\tilde{J}_f(p_f, t_f)|^{-1/2} \times \exp\left[i\tilde{S}(p_f, t_f)/h - \mu_i \pi/2\right],$$

where we are again using $p_f = p(x_0, t_f)$. $F(x_0)$ is the envelope of the initial wave packet, either $F_G(x_0)$ in Eq. (4) or $F_{TF}(x_0)$ in Eq. (5), and $x_0^{(j)}(p_f, t_f)$ has the same meaning as in the paragraph above Eq. (11): trajectories that arrive at any one $p_f$ began from a large number of discrete $x_0^{(j)}(p_f, t_f)$.

Reexamining Fig. 3(a), and thinking about $x_0(p_f, t_f)$ as a smooth but multivalued function of $p_f$, we divide the points $x_0^{(j)}(p_f, t_f)$ into intracycle and intercycle groups, where a cycle is one period of $p_f$. In Fig. 3(a), we may say that the pair of points $(\alpha, \beta)$ belongs to one cycle, the pair $(\gamma, \delta)$ to another cycle, etc. Alternatively, we may say that the pair $(\beta, \gamma)$ belongs to one cycle, $(\delta, \epsilon)$ to the next, etc. Summing over all the points $x_0^{(j)}(p_f, t_f)$ then means summing over points on distinct branches of $x_0(p_f, t_f)$ within a cycle, and then summing over cycles. Thus the index $j$ may become a composite index, $j = (b,c)$ where $b$ is an integer labeling a branch within a cycle, and $c$ is an integer labeling the cycle.

$$\tilde{J}_f(p_f, t_f)$$ is a Jacobian, which in the present case is the same derivative defined in Eq. (11),

$$\tilde{J}_f(p_f, t_f) = \left|\frac{\partial p_f(x_0, t_f)}{\partial x_0}\right|_{x_0=x_0^{(j)}(p_f, t_f)}.$$ (15)

Since $p_f$ is a periodic function of $x_0$, the values of this derivative depend on the branches within a cycle, but do not depend on which cycle is examined: $\tilde{J}_{0,c}(p_f, t_f)$ depends on the branch $b$ but is independent of the cycle $c$. In Fig. 3(a), $\tilde{J}_{0}(p_f, t_f) = \tilde{J}_{c}(p_f, t_f) = \tilde{J}_{d}(p_f, t_f) = \cdots$, while $\tilde{J}_{b}(p_f, t_f) = \tilde{J}_{c}(p_f, t_f) = \tilde{J}_{d}(p_f, t_f) = \cdots$.

$\tilde{S}_j(p_f, t_f)$ is a classical momentum-space action integrated along the path from $x_0^{(j)}(p_f, t_f)$ to the final point. This integral is

$$\tilde{S}_j(p_f, t_f) = -\int x \, dp - \int E \, dt$$

$$= -\int_0^{t_f} x(x_0, t) \frac{dp(x_0, t)}{dt} \, dt - \int_0^{t_f} E(t) \, dt.$$

There is a simple relationship between the values of $\tilde{S}_{0,c}(p_f, t_f)$ for different cycles at fixed $p_f$. Let label $c$ increase with decreasing $x_0^{(b,c)}$; i.e., it increases by 1 with each
successive cycle of the oscillating barrier. Then

$$\tilde{S}_{b,c}(p_f, t_f) = \tilde{S}_{b,c}(p_f, t_f) + N \Delta ET,$$

(17)

where $T$ is the period of one oscillation, $N$ is the number of periods separating the cycles, and $\Delta E$ is the change of energy of the particle,

$$\Delta E = \left( p_f^2 - p_0^2 \right)/2m.$$

(18)

Finally, we introduce the Maslov index $\mu_j$ associated with each branch of $x_0(p_f, t_f)$. The rule for determining it is given in Appendix B. Here let it suffice to say that, in Fig. 3(a), $\tilde{\mu}_j$ can be taken to equal one on branches $a, c, e, g, \ldots$ and equal to zero on branches $b, d, f, \ldots$.

In our calculations, we compute the final momentum as a function of initial position $p_f(x_0, t_f) = p(x_0, t_f)$, then for each $p_f$ we identify initial points $x_0^{b,c}(p_f, t_f)$ for all branches $b$ within a single cycle $c$. For each of them we find $\tilde{S}_b(p_f, t_f)$, $\tilde{\mu}_b$, and $\tilde{S}_{b,c}(p_f, t_f)$ for that particular cycle. We then calculate $\tilde{S}_{b,c}(p_f, t_f)$ for other cycles using Eq. (17), and then compute the sum Eq. (14) numerically. Steps are also taken to correct the semiclassical approximation near divergent points, and the calculation is extended into the classically forbidden regions; this procedure incorporates diffraction, or momentum space tunneling, into the semiclassical dynamics. Derivation and additional details of the semiclassical method are given in Appendix A.

Terms in the sum over cycles add with incommensurate phases, and tend to cancel unless $\Delta E = 2\pi K$ where $K$ is any integer. This condition explains the Floquet picture introduced earlier: the momentum distribution becomes a comb function, with the “teeth” occurring at momenta that satisfy the commensurate phase condition,

$$\frac{p_f^2}{2m} = \frac{p_0^2}{2m} + \frac{2\pi K}{T}.$$

(19)

In Fig. 7 we show the absolute squares of two single-cycle wave functions, one using branches $(b, c)$ (solid curve, red online) in Fig. 3(a), the other using branches $(c, d)$ (dashed curve, black online). These single-cycle probabilities intersect at momenta satisfying Eqs. (9) and (19). The relative amplitudes of these intersections are determined by both the classical densities and the differences in momentum-space action, Eq. (16), among the paths contributing to the wave function at each $p_f$.

Figure 8 shows quantities that determine the phase differences and interference for three trajectories ending with the same final momentum. Figures 8(a) and 8(b) show the position and momentum, respectively, versus time. Both plots show that particles see a decrease in velocity (and momentum) as they approach the potential barrier. Figures 8(c) and 8(d) illustrate

FIG. 7. (Color online) Probability distributions of final momenta. The sharp peaks (blue online) are obtained by summing over all branches of all cycles. Their heights are all multiplied by the same constant so that they are comparable to the other two curves. The oscillating curves are obtained by combining two branches of a single cycle, but with different definitions of the cycle. The solid curve (red online) corresponds to a cycle spanning branches $(b, c)$ in Fig. 3(a), and the dashed curve (black online) is for a cycle spanning branches $(c, d)$. Where those two curves intersect, the different cycles add in phase with each other, producing the sharp peaks.

FIG. 8. (Color online) Quantities that determine the phase evolution and interference of three trajectories ending with the same final momentum. The solid (blue online), dashed (red online), and dotted curves (black online) correspond to the trajectories associated with $(p_f, x_0) = \beta, \gamma,$ and $\delta$ in Fig. 3(a), respectively. One may think of the $(\beta, \gamma)$ trajectories as being from a single cycle, with the $\delta$ trajectory one cycle ahead of the $\beta$ trajectory. (a) Position versus time. Each trajectory shows a decrease in velocity as the barrier is initially encountered near $x = 0$. (b) Momentum versus time. (c) $x(t)dp(t)/dt$ term in the momentum-space action [Eq. (16)] versus time. (d) Energy term in the momentum-space action [Eq. (16)] versus time.
the differences in the momentum-space action, Eq. (16). The differences in areas under the curves determine the phase differences between pairs of trajectories. Interference associated with phase differences related to $E(t)$ for different cycles [Fig. 8(d)] produces Floquet peaks. Phase differences between pairs of trajectories in the same cycle [Figs. 8(c) and 8(d)] give the interference that determines relative heights of Floquet peaks.

When we sum over cycles, the resulting probability is sharply peaked at the locations where the single-cycle probabilities intersect (Fig. 7), and the heights of the peaks correspond to the relative magnitude of the single-cycle probability at these locations. Finally, we have an explanation for the relative heights of the Floquet peaks.

V. CASE STUDIES

In this section, we study three separate scattering cases for identical barrier parameters but different incident momenta: pure transmission, pure reflection, and mixed transmission and reflection. We also compare the full quantum results with the predictions of the semiclassical approach and find relatively good agreement. While there is a large range of possible scattering behaviors that can be studied by adjusting the five input parameters of our model, these three cases capture most of the essential physics.

**Pure transmission.** The initial Gaussian wave packet is centered at $x = -1500$, with $\beta = 300$, with initial momentum $p_0 = 1.8$, and with barrier parameters $A = 0.5$ and $\omega = 0.1$. This is the same case that was shown earlier in Figs. 2(d), 3, and 7. This initial momentum corresponds to an energy higher than the maximum amplitude of the barrier. It takes more than fifteen barrier oscillations for the packet to pass over the barrier. There are two branches per cycle, as shown in Fig. 9(a). The classically allowed momentum values range from $p_f \approx 1.2506$ to 2.1411.

A comparison of $P_{SC}(p_f)$ (plotted upward, blue online), $P_Q(p_f)$ (plotted downward, red online), and $P_C(p_f)$ (plotted upward, black online) is shown in Fig. 9(b). The semiclassical and quantum-mechanical results can be seen to agree well. The final probability has fifteen peaks within the classical envelope. Both the classical density and interference contribute to the relative heights of peaks. At least two non-negligible classically forbidden peaks can be seen for momentum values on either side of the classical envelope. The semiclassical calculation has corrected divergent peaks near momentum turning points by using Airy forms of local wave functions (see Appendix A).

**Pure reflection.** We employ the same barrier parameters as in the previous case, but use an incident momentum of $p_0 = 1.0$, which corresponds to an energy equal to the minimum amplitude of the barrier. The barrier undergoes more than twenty-eight oscillations during the time the wave packet is interacting with it. There are two branches per cycle, shown in Fig. 10(a), with the classical envelope ranging from $p_f \approx -1.5043$ to $-0.6825$.

A comparison of $P_{SC}(p_f)$ (plotted upward, blue online), $P_Q(p_f)$ (plotted downward, red online) and $P_C(p_f)$ (plotted upward, black online) is shown in Fig. 10(b). The final probability has fifteen peaks within the classical envelope. Both the classical density and interference contribute to the relative heights of peaks. At least two non-negligible classically forbidden peaks can be seen for momentum values on either side of the classical envelope. The semiclassical calculation has corrected divergent peaks near momentum turning points by using Airy forms of local wave functions (see Appendix A).
FIG. 11. (Color online) (a) Reflected portion of final momentum vs initial position for the $\omega = 0.1$, $p_0 = 1.4142$ case. (b) Semiclassical (plotted upward, blue online), quantum-mechanical (plotted downward, red online), and classical (plotted upward, black online) final-momentum probabilities for the reflected portion of the wave packet.

FIG. 12. (Color online) (a) Transmitted portion of final momentum vs initial position for the $\omega = 0.1$, $p_0 = 1.4142$ case. (b) Semiclassical (plotted upward, blue online), quantum-mechanical (plotted downward, red online), and classical (plotted upward, black online) final-momentum probabilities for the transmitted portion of the wave packet.

Mixed reflection and transmission. We implement the same barrier parameters as in the previous cases, but use an incident momentum of $p_0 = 1.4142$, which corresponds to an energy between the minimum and maximum of the barrier amplitude range. In this case, the wave packet is partially reflected and partially transmitted. The periodic relationship between final momentum and initial position is more complicated in this case. Figures 11(a) and 12(a) show the reflected and transmitted portions of the trajectory ensemble, respectively. Some classically allowed final momenta have as many as six interfering trajectories within each cycle. The classical envelope ranges from $p_f \approx -1.6730$ to 1.8987.

Comparisons of the reflected and transmitted portions of $\tilde{P}_{SC}(p_f)$ (plotted upward, blue online), $\tilde{P}_C(p_f)$ (plotted downward, red online), and $P_C^T(p_f)$ (plotted upward, black online) are shown in Figs. 11(b) and 12(b), respectively. Every extremum in the $p_f(x_0, t_f)$ graph gives a “turning point” or caustic, at which $P_C(p_f)$ diverges. The classical amplitude is markedly higher for larger momentum values in both the reflected and transmitted portions of the wave packet; consequently, the semiclassical and quantum-mechanical final-momentum distributions have their largest peaks in these regions. Agreement between semiclassical and quantum methods is less precise in this case, particularly where turning points are close together. Turning points that are close together, as they are in this case, are the most significant cause of disagreement between our semiclassical and quantum-mechanical calculations, although additional correction techniques can be implemented into the semiclassical approach to improve agreement.

VI. PROPOSED EXPERIMENT

The theoretical predictions of the previous sections can be tested experimentally with the macroscopic wave function of a BEC serving as the atomic wave packet. While the BEC does not have to be strictly 1D, the use of a highly elongated BEC, confined in a long optical dipole trap [28,29], simplifies scattering experiments in which a monomode atomic sample interacts with a localized potential [30–32]. Furthermore, the BEC should be noninteracting since collisions between
SCATTERING BY AN OSCILLATING BARRIER: . . .

We consider a BEC of $^{39}$K atoms in the $|F = 1, m_F = +1\rangle$ hyperfine ground state, which has a vanishing $s$-wave scattering length at 350 G [34]. A red-detuned optical dipole trap produced by a 1 W 1064 nm laser focused to a 1/e$^2$ diameter of about 120 μm will confine the BEC with a Gaussian density profile and an axial width of $\beta = 40 \approx 10 \mu$m. A blue-detuned Gaussian barrier can be produced with a 532 nm laser focused to a radius of 5 μm with a barrier amplitude of $U_0 = 1 \equiv 197$ nK. Translating this barrier at a velocity of $12.9 \text{ mm/s}$ (corresponding to an incident momentum of $\mathbf{p}_0 = 2$ for particles of mass $m = 1 \equiv 6.5 \times 10^{-26}$ kg), while modulating it at $\omega_{\text{barrier}} = 0.35 \equiv 2\pi \times 1.4$ kHz with a modulation strength of $A = 1$, produces a purely transmitted wave packet with the final momentum distribution shown in the inset of Fig. 13. The velocity peaks of the distribution have a half width at half maximum of $\Delta v \approx 0.1 \text{ mm/s}$, determined by the axial extent of the BEC. This velocity spread requires a laser frequency difference stability on the order of $2\Delta v/\lambda \approx 250$ Hz ($\lambda = 767$ nm for $^{39}$K), which is within the practical resolution of Bragg spectroscopy [37]. Furthermore, we note that the axial confinement of the BEC does not play a significant role, since the trap has an axial oscillation frequency of $f_{\text{axial}} \approx 1$ Hz, which is considerably slower than the time scale of the scattering process.

VII. CONCLUSION

In summary, we have studied scattering from an amplitude-modulated Gaussian barrier, and determined the final momentum-space probability distributions using classical, semiclassical, and quantum formalisms. We find that classical mechanics defines the boundaries of a classically allowed region of final momenta. Quantum calculations show (i) the probability that particles end with momentum outside the classically allowed region is small; (ii) the momentum distribution is peaked at momenta consistent with Floquet’s theorem; (iii) the heights of the Floquet peaks vary widely and seemingly erratically. Semiclassical calculations show that (a) for any

TABLE I. Table of proposed experiment parameters.

| Parameter       | Value                        |
|-----------------|------------------------------|
| Atomic state    | $|F = 1, m_F = +1\rangle$ state of $^{39}$K |
| Feshbach zero   | 350 G                        |
| BEC width $\beta$ | 10 μm                      |
| BEC velocity    | 12.9 mm/s                    |
| Barrier width $\sigma$ | 2.5 μm               |
| Barrier amplitude $U_0$ | 197 nK            |
| Barrier mod. ampl. $A$ | 1                      |
| Barrier mod. frequency $\omega$ | $2\pi \times 1.4$ kHz |
final momentum inside the classically allowed region, many classical paths arrive; (b) interference of waves propagating along these paths produces peaks consistent with Floquet theory, and determines their heights. Specifically, intercycle interference leads to discrete final momentum states, while intracycle interference determines the peak heights. Finally, momentum-space tunneling leads to diffractive population of momenta beyond the classically allowed bounds.

The semiclassical and full quantum propagation formalisms employed in this work are well suited for studying scattering from a turnstile pumping potential formed from two separated barriers, amplitude-modulated out of phase from each other. While no choice of system parameters for the single-barrier system leads to classical chaos, the addition of a second barrier introduces strong signatures of classical chaos, with quantum dynamics well suited to the type of semiclassical treatment developed in this paper. Such a treatment is essential for understanding the quantum and classical aspects of particle pumping in a turnstile pump, since interference and tunneling can be selectively included. Moreover, the scattering theories developed in this work can also be extended to examine spatial tunneling [38] through narrower barriers, and scattering from a potential well.

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APPENDIX A: SEMICLASSICAL ANALYSIS

We give here details and derivation of the semiclassical formulas used in Sec. IV. Most of the theory is similar to methods we have used in earlier papers [39–49], but some aspects of the present system are different. In most of our earlier work, we have studied stationary fixed-energy systems; only [43–46] dealt with time-dependent potentials. In the present case, the initial and final conditions are, from semiclassical perspectives, a little unusual. At the final time, we want a semiclassical approximation in momentum space. However, at the initial time, we cannot use a semiclassical approximation in momentum space, though we can in configuration space. Furthermore, the sum over cycles of the oscillating barrier is different from previous work.

1. Local wave function

Recall that we have an oscillating Gaussian barrier with a wave packet approaching from the left. At an initial time \( t_0 \), the wave function for \( x \ll 0 \) (far to the left of the barrier) is given by

\[
\Psi_0(x,t_0) = F(x)e^{i(p_0 x - E_0 x^2)/\hbar},
\]

where \( F(x) \) is a function describing the envelope of the initial packet in \((x,t)\) space. We include time and energy as canonical variables, expanding the phase space for the system. For reasons that will become clear, one regards \( t \) as a canonical momentum, and \( E \) as a canonical coordinate, \( q = (x,E) \) and \( p = (p,t) \).

Then defining an effective Hamiltonian, \( \mathcal{H} \), given by

\[
\mathcal{H} = \frac{p^2}{2m} + U(x,t) - E,
\]

the equations of motion are

\[
\frac{dx}{d\tau} = \frac{\partial \mathcal{H}}{\partial p} = \frac{\partial H}{\partial p},
\]

\[
\frac{dp}{d\tau} = -\frac{\partial \mathcal{H}}{\partial x} = -\frac{\partial H}{\partial x},
\]

\[
\frac{dE}{d\tau} = \frac{\partial \mathcal{H}}{\partial t} = \frac{\partial U}{\partial t},
\]

\[
\frac{dt}{d\tau} = -\frac{\partial \mathcal{H}}{\partial E} = 1,
\]

\[
\frac{dS}{d\tau} = \frac{dx}{dt} - E \frac{dt}{d\tau},
\]

\[
\frac{d\hat{S}}{d\tau} = -x \frac{dp}{dt} - E \frac{dt}{d\tau},
\]

where \( \tau \) is a “timelike” progress variable along the trajectories, and is related to \( t \) in the Schrödinger equation via \( \tau = t_0 + t \). We call \( \dot{S} \) the classical action along the trajectory, and \( \dot{\hat{S}} \) can be thought of as a “momentum-space action” along the trajectory. The form of Eqs. (A3c) and (A3d) justifies the identification of \( E \) as a canonical coordinate and \( t \) as its conjugate momentum.

We want to compute the probability that the particles end with a given final momentum, using the momentum-space wave function \( \Psi(p,t) \). Therefore, we want a semiclassical approximation in momentum space. However, since we have chosen an initial distribution with very small momentum spread, the initial wave function in momentum space is nearly a delta function, which cannot be described by a semiclassical approximation. Therefore, in order to calculate the desired momentum-space wave function, we start our calculation in \((x,t)\) space, and later transform to \((p,t)\) space.

The first step in constructing a semiclassical wave function is to propagate trajectories from a line of initial conditions. We choose the line of initial conditions to have a constant starting time \( t_0 = 0 \), variable starting position \( x \) covering the domain of the initial packet, and a fixed initial momentum \( p_0 \). The resulting trajectories sweep out a two-dimensional surface called a Lagrangian manifold in the four-dimensional \((x,p,E,t)\) phase space. A typical Lagrangian manifold for this system is shown in Fig. 14.

Integration of trajectories with respect to \( \tau \) gives a relationship between \((x_0,\tau)\) and \((z,\tau)\), where \( z \) is any dynamical variable \( x, p, E, S \), or \( \dot{S} \). From our choice of \( t_0 = 0 \), \( t \) is simply equal to \( \tau \), and \( x \) is the point at which the trajectory arrives at time \( t = \tau \). We may think of each of these quantities as a function of the initial variable \( x_0 \) and the progress variable \( \tau \), e.g., \( x(x_0,\tau), p(x_0,\tau), \) etc.

We define a Jacobian,

\[
J(x_0,\tau) = \det \left( \frac{\partial(x,t)}{\partial(x_0,\tau)} \right) = \frac{\partial x}{\partial x_0},
\]

with \( J_0 = J(x_0,0) = 1 \). This Jacobian is a single-valued function of \((x_0,\tau)\). For \( \tau \) not too large (and \( x \) not too far from \( x_0 \)) there is an invertible relationship between \((x_0,\tau)\) and \((x,t)\); i.e., we may consider \((x_0,\tau)\) as a function of \((x,t)\). With this
relationship, we may also consider the position-space action $S$ and Jacobian $J$ to be functions of $(x,t)$,

$$
S(x_0, \tau) = S(x_0(x,t), \tau(x,t)) = \mathcal{S}(x,t),
$$

$$
J(x_0, \tau) = J(x_0(x,t), \tau(x,t)) = \mathcal{J}(x,t).
$$

We may use these functions in the primitive semiclassical approximation for the $(x,t)$ space wave function,

$$
\Psi_{\text{SC}}(x,t) = \Psi_0(x_0, \tau = 0) \left| \frac{\mathcal{J}}{\mathcal{J}(x,t)} \right|^{1/2} e^{i\mathcal{S}(x,t)/\hbar},
$$

where $(x_0, \tau)$ are considered to be functions of $(x,t)$. The initial Maslov index has been set equal to zero, and

$$
\Psi_0(x_0, \tau = 0) = F(x_0) e^{i\mu x_0 / \hbar},
$$

where $(x_0, \tau)$ are again considered as functions of $(x,t)$.

As the trajectories are propagated forward in $\tau$, they come to the barrier region, where $p$ is no longer constant, and we may use $(p,t)$ locally as independent variables to describe the Lagrangian manifold, as shown in Figs. 14, 15(a), 15(c), and Fig. 16.

A “momentum chart” is a region of the Lagrangian manifold that has a diffeomorphic projection to momentum space, $(p,t)$. In Fig. 16, a constant-time slice of the Lagrangian manifold is shown. For each value of $p$, there are many corresponding values of $x$; each can be regarded as a “branch” of a multivalued function, and each is a constant-time slice of a momentum chart.

We transform to the momentum-space wave function via

$$
\tilde{\Psi}(p,t) = (2\pi\hbar)^{-1/2} \int \Psi_{\text{mc}}(x,t) e^{-ipx_i/\hbar} dx.
$$

We evaluate the integral for the part of the wave function that corresponds to the initial momentum chart by using the stationary phase approximation. We use the function $\mathcal{P}(x,t) = \partial S/\partial x$ to describe the Lagrangian manifold, and $p$ is the independent variable in $\tilde{\Psi}(p,t)$. When we substitute the semiclassical approximation (A6) into Eq. (A8), each classically allowed $p$ has a stationary phase point, $\hat{x}$, where $p = \mathcal{P}(\hat{x}, t)$, i.e., where the line $p = \text{const}$ intersects the Lagrangian manifold, as shown in Fig. 16 for $p = 1.7$. In evaluating the integral, we also make use of the momentum-space action, defined in Eq. (A3f), and define a momentum-space Jacobian

$$
\mathcal{J}(x_0, \tau) = \text{det} \left( \frac{\partial(p,t)}{\partial(x_0, \tau)} \right) = \frac{\partial p}{\partial x_0}.
$$

The locally invertible relationship between $(p,t)$ and $(x_0, \tau)$ allows us to consider $\tilde{\mathcal{S}}(x_0, \tau)$ and $\tilde{\mathcal{J}}(x_0, \tau)$ to be functions of $(p,t)$, i.e.,

$$
\tilde{\mathcal{S}}(x_0(p,t), \tau(p,t)) = \tilde{\mathcal{S}}(p,t),
$$

$$
\tilde{\mathcal{J}}(x_0(p,t), \tau(p,t)) = \tilde{\mathcal{J}}(p,t).
$$

FIG. 14. (Color online) Typical Lagrangian manifold for this system. The solid line (red online) shows a slice at a constant time. FIG. 15. (Color online) (a) Slice of Lagrangian manifold at small time. (b) Periodic final momentum as a function of initial position. (c) Final momentum, $p_f = p(x_0, \tau_f)$, as a function of final position, $x_f = x(x_0, \tau_f)$. This corresponds to the final-time slice of the Lagrangian manifold. FIG. 16. (Color online) Slice of Lagrangian manifold at an intermediate time. The numbers correspond to intermediate-time slices of different momentum charts, which are separated by local extrema in the function $p = \mathcal{P}(x,t)$ for fixed time, denoted by large circles. For every given momentum (e.g., the dashed line), there are many corresponding values of $x$.
With these definitions, the stationary phase approximation in the initial momentum chart yields
\[ \Psi_i(p, t) = F(x_0^i(p, t)) e^{i J_i(p, t) - i \pi/2} |J_i(p, t)|^{-1/2}. \] (A11)

Generally, for every momentum chart of the Lagrangian manifold, there is a comparable term contributing to the momentum-space wave function. We write the local, primitive form of the momentum-space wave function for each momentum chart as
\[ \Psi_j(p, t) = F(x_0^j(p, t)) \left| \frac{1}{J_j(p, t)} \right|^{1/2} \exp \left( \frac{i \tilde{J}(p, t)}{\hbar} - \frac{i \tilde{\mu}_j \pi}{2} \right), \] (A12)
where \( \tilde{\mu}_j \) is the Maslov index for the given momentum chart.

### a. Maslov index

Here, we state the rule for the Maslov index for each momentum chart. As indicated in Fig. 16, momentum charts are separated by momentum turning points, which are extrema of locally defined functions \( p = \bar{\mathcal{P}}(x, t) \) for fixed \( t \), i.e., points where \( \partial \mathcal{P}(x, t) / \partial x = 0 \).

Each time any path on the Lagrangian manifold passes through a momentum turning point, the Maslov index changes. In Fig. 15(c), we show a slice of the Lagrangian manifold at the final time \( t_f \). If we take any two points on this slice of the manifold, they can be connected by a path on this slice. At each point that the path passes through a momentum turning point, the Maslov index changes by \( \pm 1 \), and we use the following rule to determine the increment. This rule applies if the \( (x, p) \) plane is drawn in the most usual way, with \( x \) increasing to the right and \( p \) increasing upward. When the path passes through a momentum turning point that separates the \( i \)th momentum chart from the \( j \)th momentum chart, then
\[ \tilde{\mu}_j = \tilde{\mu}_i + 1, \quad \text{if the path curves right (CW)}, \] (A13a)
\[ \tilde{\mu}_j = \tilde{\mu}_i - 1, \quad \text{if the path curves left (CCW)}, \] (A13b)
where CW and CCW denote clockwise and counterclockwise, respectively.

The \( \exp(-i\pi/2) \) term in the primitive wave function for the first momentum chart, Eq. (A11), corresponds to \( \tilde{\mu}_j = 1 \) in Eq. (A12). All other Maslov indices for the remaining momentum charts are constructed relative to it, using Eqs. (A13a) and (A13b).

For the two paths shown in Figs. 15(c) and 16, moving from left to right, the Maslov index increases at every maximum, and decreases at every minimum.

### b. Corrections near momentum turning points

The primitive semiclassical wave function diverges at momentum turning points, where \( \tilde{J}_j(p, t) \) vanishes. To correct this, we construct an alternative way of writing the primitive wave function, which will be valid near momentum turning points in classically allowed regions. We then match this form of the wave function to the Airy function and its derivative, in order to extend the semiclassical approximation into classically forbidden regions [50].

We start by adding the primitive forms of the wave function, Eq. (A12), for two successive momentum charts, and we denote this wave function \( \Psi_{m+n}(p, t) \). We introduce the following notation:
\[ A(p, t) = |J(p, t)|^{-1/2}. \] (A14a)
\[ \Delta \tilde{J}(p, t) = \tilde{S}_n(p, t) - \tilde{S}_m(p, t). \] (A14b)
\[ \Delta \tilde{S}(p, t) = [\tilde{S}_n(p, t) + \tilde{S}_m(p, t)]/2. \] (A14c)
\[ \Delta A(p, t) = A_n(p, t) - A_m(p, t). \] (A14d)
\[ \Delta F(x_0(p, t)) = F_n(x_0(p, t)) - F_m(x_0(p, t)). \] (A14f)
\[ F(x_0(p, t)) = [F_n(x_0(p, t)) + F_m(x_0(p, t))]/2. \] (A14g)

We match the separate terms of Eq. (A15) to the first-order asymptotic forms of the Airy function and its derivative, respectively, so that we may write Eq. (A15) as
\[ \Psi_{m+n}(p, t) = C(p, t) A \sin(z(p, t)) + D(p, t) A \cos(z(p, t)), \] (A16)
where
\[ C = 2 \exp \left[ i \left( \frac{3}{8} - \tilde{\mu}_n \pi - \frac{3}{8} \right) / \left( \frac{\Delta \tilde{J}(p, t)}{\hbar} \right) \right] A \tilde{J}(p, t) \tilde{\mu}_i \pi / 2 \] (A17a)
\[ D = -2 \exp \left[ i \left( \frac{3}{8} - \tilde{\mu}_n \pi - \frac{3}{8} \right) / \left( \frac{\Delta \tilde{J}(p, t)}{\hbar} \right) \right] A \tilde{J}(p, t) \tilde{\mu}_i \pi / 2 \] (A17b)
\[ z(p, t) = \left( \frac{3 \Delta \tilde{S}(p, t)}{4 \hbar} \right)^{2/3}, \] (A17c)
where \( m \) and \( n \) subscripts denote the momentum chart with the lower and higher Maslov index, respectively. We use these definitions to write

\[ \Psi_{m+n}(p, t) = 2 \exp \left( \frac{i \tilde{J}(p, t)}{\hbar} - \frac{i \tilde{\mu}_n \pi}{2} \right) \times \left\{ \left( \frac{\Delta F}{\hbar} + \frac{\Delta \Delta F}{\hbar^2} \right) e^{\pi i \Delta \tilde{J}(p, t) / 2 \hbar} \sin \left( \frac{\Delta \tilde{J}(p, t) \pi / 2 \hbar}{2} \right) \right\}, \] (A15)

We use wave functions of the form of Eq. (A16) in the classically allowed regions near momentum turning points, where Eq. (A12) is not valid.

### c. Classically forbidden regions

One can show that if the momentum turning points are quadratic maxima or minima, the following functions vary linearly with \( p \) near the turning point \( \tilde{p} \):
\[ [\Delta \tilde{J}(p, \tilde{p})]^{2/3} \propto (p - \tilde{p}), \] (A18a)
\[ \tilde{S}(p, t) + \tilde{S}(\tilde{p}, t) \propto (p - \tilde{p}), \] (A18b)
\[ A(p, t) \tilde{J}(p, \tilde{p}) \propto (p - \tilde{p}), \] (A18c)
\[ [\Delta A(p, \tilde{p})]^{2} \propto (p - \tilde{p}). \] (A18d)

We continue these quantities into the classically forbidden regions using these linear approximations. To obtain values for \( F(x_0(p, t)) \) in these regions, we extrapolate \( x_0 \) into the
classically forbidden regions, and use it to evaluate \( F(x_0(p, t))\).
This extrapolation yields complex values of \( x_0 \).

2. Global wave function

We denote as branches the regions separated by momentum turning points in \( p(x_0, \tau_f) \), i.e., regions separated by points where \( \partial p(x_0, \tau_f) / \partial x_0 = 0 \). We define a “cycle” as one barrier oscillation, i.e., one period of \( p(x_0, \tau_f) \).

We want to construct a final wave function that is valid in both classically allowed and classically forbidden regions. We have seen that each momentum chart contributes a term to the final wave function, so our first step is to construct all local wave functions.

We will illustrate the steps necessary to construct the final wave function for the simplest case, like that shown in Fig. 3(a), which contains two branches per cycle. We must determine the regions of validity of the two forms of the wave function, Eqs. (A12) and (A16), for all branches. Due to the periodicity of final momentum and initial position, we can do this for a single cycle only, as Eqs. (A12) and (A16) are valid in the same regions for the \( i \)th branch within every cycle. Further consequences of this periodicity are discussed in Appendix B.

We choose the cycle spanning branches \((a, b, c)\) in Fig. 3(a). We start with branches \( a \) and \( b \), and construct the primitive form of the wave function by adding Eq. (A12) for the two branches. We then construct \( \tilde{\Psi}_{a+b}(p, t) \) via Eq. (A16). These two forms of the wave function are valid in different but overlapping regions, and we compare the two to determine the region of validity for each. This comparison shows that the Airy form is valid in regions \( D \) and \( E \) in Fig. 3(a) \((p \lesssim 1.66)\).

In region \( D \) \((1.36 \lesssim p \lesssim 1.66)\), where both forms of the wave function are valid, we use a switching function that varies between 0 and 1 to weight each form, and use a linear combination of the two. Then we use

\[
\tilde{\Psi}_{a+b}(p, t) = f_1(p)[\text{Airy form}] + [1 - f_1(p)][\text{Prim. form}],
\]

(A19)
as the local wave function for branches \( a \) and \( b \) in regions \( C \), \( D \), and \( E \), where \( f_1 \) is the switching function; \( f_1 \to 0 \) at the boundary between regions \( D \) and \( E \). “Airy form” and “Prim. form” in Eq. (A19) refer to \( \tilde{\Psi}_{a+b}(p, t) \) calculated via Eqs. (A16) and (A12), respectively.

We repeat this process for branches \( b \) and \( c \), and find that the Airy form of this wave function, \( \tilde{\Psi}_{p+c}(p, t) \), is valid in regions \( A \) and \( B \) \((p \gtrsim 1.77)\). Both forms of the wave function are valid in region \( B \) \((1.77 \lesssim p \lesssim 2.01)\). We use a switching function in region \( B \) to weight each form of the wave function, and use a linear combination of the two. We use primitive semiclassical wave functions for all branches in region \( C \) \((1.66 \lesssim p \lesssim 1.77)\).

With knowledge of where each branch’s primitive and Airy forms of the local wave function may be used, one may construct a final wave function, which is a linear combination of all local wave functions. For cases with more than two branches per cycle, a more elaborate version of the same process is used.

APPENDIX B: SEMICLASSICAL IMPLICATIONS OF PERIODICITY

An initial wave function that is long in position space needs many oscillation cycles to pass through the barrier region. Semiclassically, this means that the summation of the primitive wave function \( \tilde{\Psi}_j(p, t) \) [Eq. (A12)] over the momentum charts \( j \) involves a sum over trajectories with initial \( x_0 \) values extending over numerous oscillation cycles of \( p(x_0, \tau_f) \), as seen in Fig. 15(b). This creates interference of trajectories belonging to different cycles of oscillation. This intercycle interference constructively enhances final momentum values satisfying \( \Delta E = \hbar \omega_0 \), consistent with Floquet theory. Here we clarify how this constraint arises semiclassically and derive explicit formulas for the resulting momentum-space wave functions. The following discussion refers to the classically allowed regions, but its validity could be extended to include regions near turning points, and classically forbidden regions, by using the appropriate Airy forms of local wave functions.

Let \( L \) denote the initial interval of \( x \) values over which the initial wave packet is defined. We consider all those trajectories ending with a given value of \( p_f \) and beginning with any initial \( x_0 \) in \( L \). We further restrict attention to trajectories whose final point \( x(x_0, \tau_f) \) is sufficiently far outside the barrier region that the potential is essentially flat. This is appropriate when most of the wave packet has either reflected from or passed through the barrier region. Now, we choose some interval \( I \) of length \( p_0 T/m \), corresponding to one oscillation period \( T = 2\pi / \omega_0 \), within \( L \). Label all those trajectories ending at \( p_f \) which have \( x_0 \) inside \( I \) with an index \( b \); i.e., the initial position for each such trajectory is labeled \( x_0^b \). Each \( x_0^b \) is one member of an entire family of initial positions \( x_0^{(b,c)} = x_0^b - c p_0 T/m \), indexed by an integer \( c \); note that \( x_0^{(b,0)} = x_0^b \). Thus \( b \) (branch) labels trajectories within one oscillation cycle of Fig. 15(b), and \( c \) (cycle) distinguishes trajectories between different oscillation cycles.

The primitive form of the momentum-space wave function is given by summing Eq. (A12) over the double index \( j = (b, c) \):

\[
\tilde{\Psi}(p, t) = \sum_b \sum_{c=-\infty}^{\infty} F(x_0^{(b,c)}(p, t)) \frac{1}{\bar{J}_{(b,c)}(p, t)} \left| \frac{1}{\bar{J}_{(b,c)}(p, t)} \right|^{1/2} \times \exp \left( \frac{i \tilde{\tilde{S}}_{(b,c)}(p, t) - i \pi \tilde{\tilde{\mu}}_{(b,c)}(p, t)}{\hbar} \right).
\]

(B1)

Here, we allow \( c \) to range over all integers, since the initial profile \( F(x_0) \) serves to effectively eliminate any trajectories that begin outside \( L \). Since two trajectories with initial positions \( x_0^{(b,c)} \) and \( x_0^{(b',c')} \), having the same \( b \) index, differ only in their (uniform) motion outside of the barrier region, they have the same Jacobian and Maslov index, i.e.,

\[
\bar{J}_{(b,c)}(p, t) = \bar{J}_{(b,0)}(p, t) \equiv \bar{J}_{b}(p, t),
\]

(B2)
The actions too can be related to one another. Considering first \( \tilde{\tilde{S}}_{(b,0)} \) and \( \tilde{\tilde{S}}_{(b,1)} \), the \( (b,0) \) and \( (b,1) \) trajectories follow the same path in the barrier region, but the \( (b,1) \) trajectory spends one more cycle to the left of the barrier, whereas the \( (b,0) \) trajectory spends one more cycle to the right. Hence by
Eq. (A3f)
\[ \tilde{S}_{b,1}(p,t) - \tilde{S}_{b,0}(p,t) = \Delta E T, \]  
(B3)
where \( \Delta E = p^2/2 - p_0^2/2 \) is the energy gained (or lost) by the trajectory due to scattering from the barrier. Since \( \Delta E \) does not depend on the indices \( b \) or \( c \), we conclude that
\[ \tilde{S}_{b,c} = \tilde{S}_{b,0} + c \Delta E T \equiv \tilde{S}_b + c \Delta E T. \]  
(B4)

Equations (B2) and (B4) provide an efficient method for constructing terms when computing the semiclassical wave function. Rather than directly integrating the entire line of initial conditions \( L \), one only needs to integrate trajectories for initial conditions within one cycle, e.g., the interval \( I \), and construct \( \tilde{S}_{b,c} \) for other branches via Eq. (B4). The semiclassical sum can thus be rewritten as
\[ \Psi(p,t) = \sum_b D_b(p,t) \left| \frac{1}{f_b(p,t)} \right|^{1/2} \exp \left( \frac{i \tilde{S}_b(p,t)}{\hbar} - \frac{i \pi \mu_b}{2} \right), \]  
(B5)
where
\[ D_b(p,t) = \sum_{c=\infty}^{N} F(x_0^b(p,t) - c p_0 T/m) e^{i \epsilon \Delta E T/\hbar}. \]  
(B6)

In most of our calculations, we perform this sum numerically. However, in some cases, the sum can be expressed in closed form.

We consider Eq. (B6) for two initial packet profiles, rectangular and Gaussian. Considering the rectangular profile first, take \( F(x_0) = F_0 \) constant over an interval of length \( N p_0 T \), corresponding to \( N \) oscillation cycles, and \( F(x_0) = 0 \) outside this interval. Then Eq. (B6) can be rewritten as
\[ D_b(p,t) = D(p) = F_0 \sum_{c=0}^{N-1} e^{2\pi i c e} = F_0 e^{2\pi i (N - 1)/2} \frac{\sin(\pi e N)}{\sin(\pi e)}. \]  
(B7)
where \( e = \Delta E/(\hbar \omega) \). Since \( D(p) \) does not depend on \( b \), Eq. (B5) factors into the product of \( D(p) \), involving only a \( c \) sum, and a quantity involving only a sum over \( b \):
\[ \Psi(p,t) = \sum_b D(p) \left| \frac{1}{f_b(p,t)} \right|^{1/2} \exp \left( \frac{i \tilde{S}_b(p,t)}{\hbar} - \frac{i \pi \mu_b}{2} \right). \]  
(B8)

As the length of the initial wave packet goes to infinity (i.e., \( N \) goes to infinity), \( \Psi \) approaches a comb of delta functions according to
\[ \lim_{N \to \infty} \frac{\sin(\pi e N)}{\sin(\pi e)} = \sum_{k=-\infty}^{\infty} \delta(e - k). \]  
(B9)
Thus the scattered wave function obeys \( \Delta E = \hbar \omega \), in agreement with Floquet theory. Convergence to the delta functions is illustrated by the lower curves in Fig. 17, which show \( D(p) \) [Eq. (B7)] as a function of \( e \) for \( N = 3 \) and 10.

Considering the Gaussian profile next, we now take \( F(x_0) \) equal to \( F_G(x_0) \) in Eq. (4). Then in the limit of a long packet
\[ \beta \gg p_0 T, \]  
(B6) reduces to
\[ D_b(p,t) = D(p) = \frac{1}{\sqrt{\beta(2\pi)^{1/2}}} \theta_3(\pi e, e^{-(p_0 T)^2/(2p^2)}) \]  
(B10)
where \( \theta_3(z,q) \) is a Jacobi theta function \([51]\),
\[ \theta_3(z,q) = 1 + 2 \sum_{n=1}^{\infty} q^n \cos(2nz). \]  
(B11)
The upper curves in Fig. 17 illustrate \( D \) [Eq. (B10)] as a function of \( e \). As in the case of a rectangular initial condition, \( D \) converges to a comb of delta functions as the initial packet width increases. Unlike the rectangular case, however, there are no higher order peaks between the primary peaks at integer values of \( e \). This agrees with the results presented in the paper (Figs. 2–4 and 9–12), which also show no higher-order peaks between the primary Floquet peaks.

**APPENDIX C: BOUNDARIES OF CLASSICALLY ALLOWED REGIONS**

It would be nice to obtain some simple estimates of the maximum and minimum classically allowed energy change. This turns out not to be as easy as we might wish. The simplest model is an “elevator”:
\[ V_l(x,t) = \begin{cases} U_0[1 + A \sin(\omega t + \phi)], & 0 \leq x \leq L, \\ 0, & \text{otherwise.} \end{cases} \]  
(C1)
A particle of mass \( m \) and initial momentum \( p_0 \) arrives at \( x = 0 \) at time \( t = 0 \). If at that instant its kinetic energy is less than \( V_l(0,0) \), then the particle is reflected with momentum \(-p_0\). Otherwise, it hops onto the elevator, traverses it with momentum \( p' = [p_0^2 - 2m V_l(0,0)]^{1/2} \), and arrives at the end of the elevator at time \( t_b = mL/p' \). There it hops off, gaining potential energy \( V_l(L,t_b) \), so the final energy and the change in energy are
\[ E_f = \frac{p'^2}{2m} + V_l(L,t_b), \]  
(C2a)
\[ \Delta E = V_l(L,t_b) - V_l(0,0) \]  
(C2b)
\[ = AU_0 [\sin(\omega t_b + \phi) - \sin \phi]. \]  
(C2c)
The maximum possible range of \( \Delta E \) is \( \pm 2AU_0 \). It is also important to note that \( t_b \) depends on \( \phi \).
Intuitively we expect that, if \( \omega t_b \) is small, then the particle will gain the most energy if it arrives at the barrier when the elevator is most rapidly rising, i.e., if \( \phi = 0 \). This is a respectable guess; however, if it arrives a bit later, then it will spend a longer time on the elevator, and thereby gain more energy. Likewise, we may expect that it will lose the most energy if it arrives when the elevator is falling most rapidly, \( \phi = \pi \). However, if it arrives a bit earlier, then again it stays longer on the elevator, and so it loses more energy.

A graph of \( \Delta E \) vs \( \phi \) is shown in Figs. 18 and 19 for small \( \omega t_b \). The maximum increase in energy occurs when \( \phi = \phi_\ast \),

\[ \Delta E \approx \frac{mAU_0}{(p_0^2 - 2mU_0)^2}, \]  

and the greatest decrease occurs when \( \phi = \phi_\ast \), where

\[ \phi_\ast \approx \pi - \frac{mAU_0}{(p_0^2 - 2mU_0)^2}. \]

The change in energy predicted by these values of \( \phi \) are shown in Fig. 18. For wider barriers, the behavior becomes more complex.

There are also other solvable models, such as

\[ V_2(x,t) = \begin{cases} V_0(t) - |x|, & 0 \leq |x| \leq V_0(t), \\ 0, & \text{otherwise} \end{cases} \]  

and

\[ V_3(x,t) = \begin{cases} V_0(t) - x^2, & 0 \leq |x|^{1/2} \leq V_0(t), \\ 0, & \text{otherwise} \end{cases} \]

where \( V_0(t) = U_0[1 + A \sin(\omega t)] \), but they are more complicated.

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