Computation in Large-Scale Scientific and Internet Data Applications is a Focus of MMDS 2010

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The 2010 Workshop on Algorithms for Modern Massive Data Sets (MMDS 2010) was held at Stanford University, June 15–18. The goals of MMDS 2010 were (1) to explore novel techniques for modeling and analyzing massive, high-dimensional, and non-linearly-structured scientific and Internet data sets; and (2) to bring together computer scientists, statisticians, applied mathematicians, and data analysis practitioners to promote cross-fertilization of ideas. MMDS 2010 followed on the heels of two previous MMDS workshops. The first, MMDS 2006, addressed the complementary perspectives brought by the numerical linear algebra and theoretical computer science communities to matrix algorithms in modern informatics applications [1]; and the second, MMDS 2008, explored more generally fundamental algorithmic and statistical challenges in modern large-scale data analysis [2].

The MMDS 2010 program drew well over 200 participants, with 40 talks and 13 poster presentations from a wide spectrum of researchers in modern large-scale data analysis. This included both academic researchers as well as a wide spectrum of industrial practitioners. As with the previous meetings, MMDS 2010 generated intense interdisciplinary interest and was extremely successful, clearly indicating the desire among many research communities to begin to distill out and establish the algorithmic and statistical basis for the analysis of complex large-scale data sets, as well as the desire to move increasingly-sophisticated theoretical ideas to the solution of practical problems.

Several Recurring Themes

Several themes—recurring melodies, as one participant later blogged, that played as background music throughout many of the presentations—emerged over the course of the four days of the meeting. One major theme was that many modern data sets of practical interest are better-described by (typically sparse and poorly-structured) graphs or matrices than as dense flat tables. While this may be obvious to some—after all, both graphs and matrices are mathematical structures that provide a “sweep spot” between more descriptive flexibility and better computational tractability—this also poses considerable research and implementational challenges, given the way that databases have historically been constructed and the way that supercomputers have historically been designed. A second major theme was that computations involving massive data are closely tied to hardware considerations in ways that are very different than have been encountered historically in scientific computing and computer science—and this is true both for computations involving a single machine (recall recent developments in multicore computing) and for computations run across many machines (such as in large distributed data centers).

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Given that these and other themes were touched upon from many complementary perspectives and that there was a wide range of backgrounds among the participants, MMDS 2010 was organized loosely around six hour-long tutorial presentations.

Large-Scale Informatics: Problems, Methods, and Models

On the first day of the workshop, participants heard two tutorials that addressed computational issues in large-scale data analysis from two very different perspectives. The first was by Peter Norvig of Google, and the second was by John Gilbert of the University of California at Santa Barbara.

Norvig kicked-off the meeting with a tutorial on “Internet-Scale Data Analysis,” during which he described the practical problems of running, as well as the enormous potential of having, a data center so massive that “six-sigma” events, like cosmic rays, drunken hunters, blasphemous infidels, and shark attacks, are legitimate concerns. At this size scale, the data can easily consist of billions to trillions of examples, each of which is described by millions to billions of features. In most data-intensive Internet applications, the peak performance of a machine is less important than the price-performance ratio. Thus, at this size scale, computations are typically performed on clusters of tens or hundreds of thousands of relatively-inexpensive commodity-grade CPUs, carefully organized into hierarchies of servers, racks, and warehouses, with high-speed connections between different machines at different levels of the hierarchy. Given this cluster design, working within a software framework like MapReduce that provides stateless, distributed, and parallel computation has benefits; developing methods to maximize energy efficiency is increasingly-important; and developing software protocols to handle ever-present hardware faults and failures is a must.

Given all of this infrastructure, one can then do impressive things, as large Internet companies such as Google have demonstrated. Norvig surveyed a range of applications such as modelling flu trends with search terms, image analysis for scene completion (removing undesirable parts of an image and filling in the background with pixels taken from a large corpus of other images), and using simple models of text to perform spelling correction. In these and other Web-scale applications, simpler models trained on more data can often beat more complex models trained on less data. This can be surprising for those with experience in small-scale machine learning, where the curse of dimensionality and overfitting the data are paramount issues. In Internet-scale data analysis, though, more data mean different data, and throwing away even rare events can be a bad idea since much Web data consists of individually rare but collectively frequent events.

John Gilbert then provided a complementary perspective in his tutorial “Combinatorial Scientific Computing: Experience and Challenges.” Combinatorial Scientific Computing (CSC) is a research area at the interface between scientific computing and algorithmic computer science; and an important goal of CSC is the development, application, and analysis of combinatorial algorithms to enable scientific and engineering computations. As an example, consider so-called fill-reducing matrix factorizations that arise in the solution of sparse linear systems, a workhorse for traditional high-performance scientific computation. “Fill” refers to the introduction of new non-zero entries into a factor, and an important component of sparse matrix solvers is an algorithm that attempts to solve the combinatorial problem of choosing an optimal ordering of the columns and rows of the initial matrix in order to minimize the fill. Similar combinatorial problems arise in scientific problems as diverse as mesh generation, iterative methods, climate modeling, computational biology, and parallel computing. Throughout his tutorial, Gilbert focused on two broad challenges—the challenge of architecture and algorithms, and the challenge of primitives—in applying CSC methods to large-scale data analysis.
The “challenge of architecture and algorithms” refers to the nuts and bolts of getting high-quality implementations to run rapidly on machines, *e.g.*, given architectural constraints imposed by communication and memory hierarchy issues or the existence of multiple processing units on a single chip. As an example of the impact of architecture on even simple computations, consider the ubiquitous three-loop algorithm for multiplying two $n \times n$ matrices, $A$ and $B$: foreach $i, j, k$,

$$C(i, j) = A(i, k) \ast B(k, j).$$

It seems obvious that this algorithm should run in $O(n^3)$ time (and it does in the Random Access Model of computation); but empirical results demonstrate that the actual scaling on real machines of this naïve algorithm for matrix multiplication can be closer to $O(n^5)$. Theoretical results in the Uniform Memory Hierarchy model of computation explain this scaling behavior, and it is only more sophisticated BLAS-3 GEMM and recursive blocked algorithms that take into account memory hierarchy issues that run in $O(n^3)$ time.

The “challenge of primitives” refers to the need to develop algorithmic tools that provide a framework to express concisely a broad scope of computations; that allow programming at the appropriate level of abstraction; and that are applicable over a wide range of platforms, hiding architecture-specific details from the users. Historically, linear algebra has served as the “middleware” of scientific computing. That is, by providing mathematical tools, interactive environments, and high-quality software libraries, it has provided an “impedance match” between the theory of continuous physical modeling and the practice of high-performance hardware implementations. Although there are deep theoretical connections between linear algebra and graph theory, Gilbert noted that it is not clear yet to what extent these connections can be exploited practically to create an analogous middleware for very large-scale analytics on graphs and other discrete data. Perhaps some of the functionality that is currently being added onto the basic MapReduce framework (and that draws strength from experiences in relational database management or high-performance parallel scientific computing) will serve this role, but this remains to be seen.

**New Perspectives on Old Approaches to Networked Data**

Although graphs and networks provide a popular way to model large-scale data, their use in statistical data analysis has had a long history. Describing recent developments in a broader historical context was the subject of tutorials by Peter Bickel of the University of California at Berkeley and Sebastiano Vigna of the Università degli Studi di Milano.

In his tutorial on “Statistical Inference for Networks,” Bickel described a nonparametric statistical framework for the analysis of clustering structure in unlabeled networks, as well as for parametric network models more generally. As background, recall the basic Erdős-Rényi (ER) random graph model: given $n$ vertices, connect each pair of vertices with probability $p$. If $p \gg \log(n)/n$, such graphs are “dense” and fairly regular—due to the high-dimensional phenomenon of measure concentration, such graphs are fully-connected; they are expanders (*i.e.*, there do not exist any good cuts, or partitions, of them into two or more pieces); and the empirically-observed degrees are very close to their mean. On the other hand, for the much less well-studied regime $1/n < p < \log(n)/n$, these graphs are very sparse and very irregular—such graphs are not even fully-connected; and when considering just the giant component, there are many small but deep cuts, and empirically-observed degrees can be much larger than their mean. This lack of large-scale regularity is also seen in “power law” generalizations of the basic ER model; it’s signatures are seen empirically in a wide range of very large social and information networks; and it renders traditional methods of statistical inference of limited usefulness for these very large real-world networks.
Bickel considered a class of models applicable to both the dense/regular and sparse/irregular regimes, but for which the assumption of statistical exchangeability holds for the nodes. This exchangeability assumption provides a regularity such that any undirected random graph whose vertices are exchangeable can be written as a mixture of “simple” graphs that can be parametrized by a function \( h(\cdot, \cdot) \) of two arguments. Popular stochastic blockmodels are examples of parametric models which approximate this class of nonparametric models—the block model with \( K \) classes is a simple exchangeable graph model, and block models can be used to approximate a general function \( h \). In this framework, Bickel considered questions of identifiability and consistency; and he showed that, under assumptions such as that the expected degree is sufficiently high, it is possible to recover “ground truth” clusters in this model.

Sebastiano Vigna provided a tutorial on “Spectral Ranking,” a general umbrella name for techniques that apply the theory of linear functions, e.g., eigenvalues and eigenvectors, to matrices that do not represent geometric transformations, but instead represent some other kind of relationship between entities. For example, the matrix \( M \) may be the adjacency matrix of a graph or network, where the entries of \( M \) represent some sort of binary relations between entities. In this case, a common goal is to use this information to obtain a meaningful ranking of the entities; and a common difficulty is that the matrix \( M \) may contain “contradictory” information—e.g., \( i \) likes \( j \), and \( j \) likes \( k \), but \( i \) does not like \( k \); or \( i \) is better than \( j \), \( j \) is better than \( k \), but \( i \) is not better than \( k \).

A variant of this was considered by J.R. Seely who, in an effort to rank children back in 1949, argued that the rank of a child should be defined recursively as the sum of the ranks of the children that like him. In modern terminology, this led to the computation of a dominant left eigenvector of \( M \) (normalized by row to get a stochastic matrix). A dual variant was considered by T.H. Wei who, in 1952, wanted to rank sports teams and argued that the score of a team should be related to the sum of the scores of the teams it defeated. This led to the computation of a dominant right eigenvector of \( M \) (with no normalization). Since then, numerous domain-specific considerations led researchers to propose methods that, in retrospect, are variants of this basic framework. For example, in 1953, L. Katz was interested in whether individual \( i \) endorses or votes for individual \( j \), and he argued that the importance of \( i \) depends on not just the number of voters, but on the number of the voters’ voters, etc., with a suitable attenuation \( \alpha \) at each step. Since, if \( M \) is a zero/one matrix representing a directed graph, the \( i, j \) entry of \( M^k \) contains the number of directed paths from \( i \) to \( j \), he was led to compute \( 1 \sum_{n=0}^{\infty} \alpha^n M^n = (I - \alpha M)^{-1} \). Similarly, in 1965, C.H. Hubbell was interested in a form of clustering used by sociologists known as clique identification. He argued that on can define a status index \( r \) by using the recursive equation \( r = v + rM \), where \( v \) is a “boundary condition” or “initial preference,” and this led him to compute \( v \sum_{n=0}^{\infty} M^n = v(I - M)^{-1} \).

From this broader perspective, the popular PageRank is the damped spectral ranking of the normalized adjacency matrix of the web graph; the boundary condition is the so-called preference vector; and this vector can be used for various generalizations such as to bias PageRank with respect to a topic or to generate trust scores. Remarkably, although PageRank is one of the most talked-about algorithms ever, there is no reproducible scientific proof that it works for the problem of ranking web pages, there is a large body of empirical evidence that it does not work, and it is likely to be of miniscule importance in today’s ranking algorithms. Nevertheless, partly because the basic ideas underlying spectral ranking are so intuitive, there are “gazillions” of small variants that could be (and are still being) introduced regularly in many areas of machine learning and data analysis. Unfortunately, this is often without reproducible scientific justification or careful evaluation of which variants are meaningful or useful.
Matrix Computations—in Data Applications

Challenges and tradeoffs in performing matrix computations in MMDS applications were the subject of the final pair of tutorials—one by Piotr Indyk of the Massachusetts Institute of Technology, and one by Petros Drineas of Rensselaer Polytechnic Institute.

Indyk discussed recent developments in “Sparse Recovery Using Sparse Matrices.” This problem arises when the data can be modeled by a vector \( x \) that is sparse in some (often unknown) basis; and it has received attention recently in areas such as compressive sensing, data stream computing, and combinatorial group testing. Traditional approaches first capture the entire signal and then process it for compression, transmission, or storage. Alternatively, one can obtain a succinct approximate representation by acquiring a small number of linear measurements of the signal. That is, if \( x \) is an \( n \)-vector, the representation is \( Ax \), for some \( m \times n \) matrix \( A \). Although typically \( m \ll n \), the matrix \( A \) can be constructed such that one can use a recovery algorithm to obtain a sparse approximation to \( x \). It is often useful (and sometimes crucial) that the measurement matrix \( A \) be sparse, in that it contains very few non-zero elements per column. For example, sparsity can be exploited computationally—one can compute the product \( Ax \) very quickly if \( A \) is sparse. Similarly, in data stream processing, the time needed to update the sketch \( Ax \) under an update \( \Delta_i \) is proportional to the number of non-zero elements in the \( i \)-th column of \( A \).

Indyk described tradeoffs that arise when designing recovery schemes to satisfy the tricriterion of short sketches, low algorithmic complexity, and strong recovery guarantees. Randomization has proved to be an important computational resource, and thus a key issue has been to identify properties that hold for very sparse random matrices and also are sufficient to support efficient and accurate recovery algorithms. A key challenge is that, whereas dense random matrices are fairly homogeneous (e.g., since measure concentrates their eigenvalues follow Wigner’s semicircle law), very sparse random matrices are much less regular. One can say that a matrix \( A \) satisfies the \( RIP(p, k, \epsilon) \) property if

\[
\|x\|_p(1 - \epsilon) \leq \|Ax\|_p \leq \|x\|_p
\]

holds for any \( k \)-sparse vector \( x \). (This generalizes the well-known Restricted Isometry Property from \( p = 2 \) to general \( p \).) Although very sparse matrices cannot satisfy the \( RIP(2, k, \epsilon) \) property, unless \( k \) or \( \epsilon \) is rather large, Indyk showed that the adjacency matrices of constant-degree expander graphs do satisfy this property for \( p = 1 \) and that several previous algorithms generalize to very sparse matrices if this condition is satisfied.

In his tutorial on “Randomized Algorithms in Linear Algebra and Large Data Applications,” Petros Drineas used his work on DNA single-nucleotide polymorphisms (SNPs) to illustrate the uses of randomized matrix algorithms in data analysis. SNPs are sites in the human genome where a nonnegligible fraction of the population has one allele and a nonnegligible fraction has a second allele. Thus, they are of interest in population genetics and personalized medicine. In addition, they can be naturally represented as a \( \{−1, 0, +1\} \) matrix \( A \), where \( A_{ij} \) represents whether the \( i \)-th individual is homozygous for the major allele, heterozygous, or homozygous for the minor allele.

While some SNP data sets are rather small, data consisting of thousands or more of individuals typed at hundreds of thousands of SNPs are increasingly-common. Size is an issue since even getting off-the-shelf SVD and QR decomposition code to run on dense matrices of size, say, \( 5000 \times 500,000 \) is nontrivial on commodity laptops. The challenge is especially daunting if the computations need to be performed thousands of times in the course of a cross-validation experiment. Perhaps less obvious is the issue of interpretability—even if the data clusters well in the span of the top \( k \) “eigenSNPs,” these eigenSNPs cannot be assayed in the lab and they cannot be easily thought
about. Thus, while eigenvector-based methods for dimensionality reduction are popular among data analysts, the geneticists were more interested in the \( k \) actual SNPs that were most important.

Drineas described how to address these two challenges—the “challenge of size” and the “challenge of interpretability”—in a unified manner. He described a randomized approximation algorithm for choosing the best set of exactly \( k \) columns from an arbitrary matrix. The key structural insight was to choose columns according to an importance sampling distribution proportional to the diagonal elements of the projection matrix onto the span of the top \( k \) right singular vectors. These quantities can be computed exactly by computing a basis for that space, or they can be approximated more rapidly with more sophisticated methods. Importantly for interpretability, these quantities are the diagonal elements of the so-called “hat matrix,” and thus they have a natural interpretation in terms of statistical leverage and diagnostic regression analysis. Importantly for size and speed, Hadamard-based random projections approximately uniformize these scores, washing out interesting structure and providing a basis where simple uniform sampling performs well. This has led in recent years to fast high-quality numerical implementations of these and related randomized algorithms.

**Conclusions and Future Directions**

In addition to these tutorial presentations, MMDS participants heard about and discussed a wide range of theoretical and practical issues having to do with algorithm development and the challenges of working with modern massive data sets. As with previous MMDS meetings, the presentations from all speakers can be found at the conference website, [http://mmds.stanford.edu](http://mmds.stanford.edu); and as with previous MMDS meetings, participant feedback made it clear that there is a lot of interest in MMDS as a developing research area at the interface between computer science, statistics, applied mathematics, and scientific and Internet data applications. So keep an eye out for future MMDSs!

**Acknowledgments**

I am grateful to the numerous individuals who provided assistance prior to and during MMDS 2010; to my co-organizers Alex Shkolnik, Petros Drineas, Lek-Heng Lim, Gunnar Carlsson; and to each of the speakers, poster presenters, and other participants, without whom MMDS 2010 would not have been such a success.

**References**

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