Nonlinear hydrodynamic theory of crystallization

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Abstract

We present an isothermal fluctuating nonlinear hydrodynamic theory of crystallization in molecular liquids. A dynamic coarse-graining technique is used to derive the velocity field, a phenomenology which allows a direct coupling between the free energy functional of the classical density functional theory and the Navier–Stokes equation. In contrast to the Ginzburg–Landau type amplitude theories, the dynamic response to elastic deformations is described by parameter-free kinetic equations. Employing our approach to the free energy functional of the phase-field crystal model, we recover the classical spectrum for the phonons and the steady-state growth fronts. The capillary wave spectrum of the equilibrium crystal–liquid interface is in good qualitative agreement with the molecular dynamics simulations.

(Some figures may appear in colour only in the online journal)

1. Introduction

A general molecular scale theory of crystallization that describes elastic and plastic deformations, including phonons, translation/rotation of the crystallites, and crack propagation is as yet unavailable. Practical problems, like dendrite fragmentation or a realistic model of defect dynamics in crystals, would require such a tool. Despite recent steps made in this direction, further work is needed. The advanced models developed in the past years are based on various formulations of the classical density functional theory (DFT) \([1–3]\), such as the perturbative approach by Ramakrishnan and Yussouff \([4]\), the non-perturbative theories like the weighted and modified weighted density approximations \([5, 6]\), and ultimately the fundamental measure theory \([7]\), followed by the recently proposed simple phase-field crystal (PFC) model \([8–10]\). The DFT models characterize the local state of the matter by the time-averaged one-particle density of which the free energy is a unique functional. The dynamic extensions of the DFT, termed dynamic density functional theories (DDFTs), address a great variety of crystallization related time dependent problems \([10]\), including grain boundary dynamics, homogeneous and heterogeneous nucleation, dendritic and eutectic growth, density- or solute trapping, freezing of competing crystalline phases, etc \([10]\).

The dynamic extension of the DFT even for simple atomic liquids is a rather demanding problem of non-equilibrium statistical physics, posing a number of difficulties \([11, 12]\). First the DDFT was worked out for strongly non-equilibrium Brownian liquids and colloidal systems \([12–15]\). Later the dynamics was extended for dense atomic liquids \([16]\). The unified dynamics derived for both molecular and colloidal fluids \([17]\) is a recent development, but it is valid only for small velocities (i.e. for dense liquids and/or close to equilibrium). The first time derivative in the dynamical equation originates from the presence of a medium, which is responsible for the damping. In the case of simple molecular liquids no medium is present, thus the velocity field cannot be neglected anymore. Some of the dynamic extensions to crystals rely on a purely diffusive dynamics (an overdamped, conservative kinetic equation yielding diffusive dynamics, more appropriate for colloidal suspensions than anything else, e.g., \([8–10, 18]\)), whereas other models incorporate a second order time derivative in the kinetic equation \([19]\), which may lead to the appearance of a second time scale resembling relaxation. A third category
is the linearized hydrodynamic model that would capture phonons in the crystal [20, 21]. However, only a few limited studies of the latter kind have been performed [21], in which the form of the associated phonon dispersion has not been tested.

A few other attempts have recently been made to couple fluid flow and the PFC model. Preatorius et al [22] proposed a simple advected PFC model to describe particle motion in a carrier fluid. A Navier–Stokes–Cahn–Hilliard model has been coupled with the PFC model to model jamming of colloidal particles at the liquid–liquid interface [23, 24]. This approach, however, also lacks the fluid flow for the density field.

The most essential problem of combining a molecular scale theory with hydrodynamics is that in the latter approach inertia and dissipation are formulated on the macroscopic level, which cannot be easily reconciled with molecular scale modeling (e.g., the large density gradients in the microscopic picture should not create spurious mass flow inside the crystal). In this paper, we raise the idea that a straightforward picture should not create spurious mass flow inside the model description.

In section 5, we offer a few concluding remarks. Technical remarks are made regarding coarse-graining applied and melting, and the capillary wave spectrum. Finally, a few studies of the latter kind have been performed [21], in which the form of the associated phonon dispersion has not been tested.

2. Model description

2.1. Dynamical equations

We present a time dependent density functional theory of crystallization based on fluctuating nonlinear hydrodynamics [26, 27]. Our starting point is a recent work of Shang et al [25], which has successfully addressed multiphase liquid and liquid–gas equilibrium interfaces. Considering isothermal processes, the respective dynamical equations read as

\[ \frac{\partial \rho}{\partial t} + \nabla \cdot \mathbf{p} = 0 \]  
\[ \frac{\partial \mathbf{p}}{\partial t} + \nabla \cdot (\mathbf{p} \otimes \mathbf{v}) = \nabla \cdot [\mathbb{R}(\rho) + \mathbb{D}(\mathbf{v}) + \mathbb{S}]. \]  

Here \( \rho \) is the mass and \( \mathbf{p} \) the momentum density, and \( \mathbf{v} \) the velocity field. \( \mathbb{R}(\rho) \) and \( \mathbb{D}(\mathbf{v}) \) are the reversible and dissipative stress tensors, respectively, whereas \( \mathbb{S} \) is a noise matrix representing thermal fluctuations. The dissipative stress of a Newtonian liquid is as follows:

\[ \mathbb{D}(\mathbf{v}) = \mu_S[(\nabla \otimes \mathbf{v}) + (\nabla \otimes \mathbf{v})^T] + (\mu_B - \frac{2}{3}\mu_S)(\nabla \cdot \mathbf{v}), \]  

where \( \mu_S \) and \( \mu_B \) are the shear and bulk viscosities, respectively. The fluctuation-dissipation theorem yields the following covariance tensor for the noise:

\[ \langle S_{ij}(t) S_{kl}(t') \rangle = (2k_B T \mu_S) \delta(r - r') \delta(t - t') \times \left[ \delta_{ik} \delta_{jl} + \delta_{ik} \delta_{il} + \frac{\mu_B}{\mu_S} \left(2 - \frac{3}{2}\right) \delta_{ij} \delta_{kl} \right]. \]  

where \( k_B \) is Boltzmann’s constant and \( T \) the temperature. The free energy functional of the classical DFT is anchored to the FHN model via the fundamental equation for the reversible stress tensor emerging from the least action principle [28],

\[ \nabla \cdot \mathbb{R}(\rho) = -\rho \nabla \frac{\delta F[\rho]}{\delta \rho}, \]  

where \( \delta F[\rho]/\delta \rho \) is the first functional derivative of the Helmholtz free energy functional \( F[\rho] \) with respect to the density.

Note that substituting the time derivative of equation (1) into the divergence of equation (2), and using equation (5) yields the following kinetic equation:

\[ \frac{\partial^2 \rho}{\partial t^2} = \nabla \cdot \left( \rho \nabla \frac{\delta F}{\delta \rho} \right) \]

\[ + \nabla \cdot [\nabla \cdot \mathbb{D}(\mathbf{v}) - \nabla \cdot (\mathbf{p} \otimes \mathbf{v}) + \nabla \cdot \mathbb{S}], \]  

which consistently recovers the undamped limit of the dynamics proposed by Archer [17] for small velocities (\( \mathbf{v} \to 0 \)) in the case of \( \mathbb{S} = 0 \). Since in equation (6) \( \rho \) and \( \mathbf{p} \) are the local time-averaged microscopic one-particle and momentum densities, respectively, the same applies for equations (1) and (2).

2.2. Scale separation via dynamic coarse-graining

The main difficulties associated with applying the free energy functional of a classical DFT of freezing directly in the dynamical equations (1) and (2) are as follows. (i) The validity limit of the Navier–Stokes equation coincides with that of the linear dissipation assumption. According to molecular dynamics simulations, the smallest length scale where the Navier–Stokes equation is considered to be valid in liquids is \( \approx 10^5 \sigma_0 \), where \( \sigma_0 \) is the effective molecular diameter [29]. On smaller length scales, the definition of the continuum velocity...
field breaks down, and the system shows an essentially different behavior (in other words, the molecular resolution must be taken into account in both space and time). (ii) In the classical DFT of freezing, the crystal is represented by a lattice periodic density distribution, which shows peaks at the lattice sites. Due to the high gradients of the density field, expressing \( \mathbf{v} \) by \( \mathbf{p} \) and \( \rho \) may lead to singularities in the velocity, yielding spurious convections in the interatomic space. To prevent such singularities while retaining the validity of the Navier–Stokes equation, we assume that the convection is related to the coarse-grained momentum and density fields as follows:

\[
\mathbf{v}(\mathbf{r}, t) := \frac{\mathbf{p}(\mathbf{r}, t)}{\rho(\mathbf{r}, t)},
\]

where \( \dot{\rho}(\mathbf{r}, t) \) and \( \dot{\mathbf{p}}(\mathbf{r}, t) \) stand for the space- and time-averaged microscopic one-particle density and momentum fields, respectively, where the spatial averaging results in the fields without their lattice periodic components. Consequently, this phenomenological ‘derivation’ relies on a two-step coarse-graining process. Note that the shortest possible wavelength in \( \mathbf{v}(\mathbf{r}, t) \), on which the Navier–Stokes equation is valid, corresponds to the thickness of the solid–liquid interface that should be several times the intermolecular distance, a condition not necessarily satisfied for faceted crystal–liquid interfaces. In addition, we apply the constant mobility approximation \([18]\) in equation (5),

\[
\nabla \cdot \mathbb{R}(\rho) = -\rho \nabla \frac{\delta F[\rho]}{\delta \rho},
\]

which corresponds to the trivial reversible stress tensor \( \mathbb{R}(\rho) = -\rho \nabla \frac{\delta F[\rho]}{\delta \rho} \mathbb{I} \) (where \( \mathbb{I} \) is the identity matrix). The coarse-grained velocity can be generated by using different lowpass filters. The properties and the effect of different filters will be discussed in section 4.5.

Note that applying our approach to a simple Ginzburg–Landau (GL) type free energy functional (where the preferred density field distributions are homogeneous), the coarse-graining process simply results in \( \dot{\rho} \approx \rho, \dot{\mathbf{p}} \approx \mathbf{p} \) and \( \mathbf{v} \approx \mathbf{p}/\rho \) (if the characteristic length of the GL model (i.e. the interface width) is large compared to the interatomic distance). In this case, the model reduces to the description of Shang et al \([25]\), but with constant mobility in the reversible stress. (Since the GL models do not contain the elastic properties of the crystalline phase, the reduced model can be used only for liquid–liquid or liquid–vapor transitions.) Finally, we also mention that the present description is limited exclusively by the ratio of the interatomic distance and the interface thickness: the characteristic length scale on which the viscous dissipation acts must be large enough to retain the validity of the Navier–Stokes equation. Molecular dynamics investigations along the line described in \([29]\) are needed to clarify this limitation further.

### 2.3. Translational and rotational invariance

First we test our description against translational and rotational invariance. Pure translation and/or rotation can be expressed by the velocity field \( \mathbf{v}_0(\mathbf{r}) = \mathbf{v}_0 + \mathbf{w} \times (\mathbf{r} - \mathbf{r}_0) \), while the corresponding momentum distribution reads as \( \mathbf{p}(\mathbf{r}, t) = \rho(\mathbf{r}, t) \cdot \mathbf{v}_0(\mathbf{r}) \). Using equation (7) the coarse-grained velocity field is

\[
\mathbf{v}(\mathbf{r}, t) = \frac{\mathbf{p}(\mathbf{r}, t)}{\rho(\mathbf{r}, t)} = \frac{\dot{\mathbf{p}}(\mathbf{r}, t) \cdot \mathbf{v}_0(\mathbf{r})}{\dot{\rho}(\mathbf{r}, t)} = \mathbf{v}_0(\mathbf{r}),
\]

where we utilized that the spectrum of \( \mathbf{v}_0(\mathbf{r}) \) contains only a zero-frequency component.

Consider now an equilibrium density distribution \( \rho_0(\mathbf{r}) \), i.e. for which the first functional derivative of the free energy functional is constant: \( \{\delta F[\rho(\mathbf{r})]/\delta \rho\}|_{\rho(\mathbf{r})} = \mu \). The functional derivative shows translational and rotational invariance, namely: \( \{\delta F[\rho(\mathbf{r})]/\delta \rho\}|_{\rho(\mathbf{r}, \mathbf{t})} = \mu \) for \( \rho(\mathbf{r}, t) = \rho_0(\mathbf{r} - \mathbf{v}_0(\mathbf{r}) \cdot t) \). Using this together with \( \mathbf{p}(\mathbf{r}, t) = \rho(\mathbf{r}, t) \cdot \mathbf{v}_0(\mathbf{r}) \) and \( \mathbf{v}(\mathbf{r}) = \mathbf{v}_0(\mathbf{r}) \) in equations (1) and (2) yields

\[
\frac{\partial \rho(\mathbf{r}, t)}{\partial t} + \nabla \cdot [\rho(\mathbf{r}, t) \cdot \mathbf{v}_0(\mathbf{r})] = 0
\]

\[
\frac{\partial \mathbf{p}(\mathbf{r}, t)}{\partial t} + \nabla \cdot [\mathbf{p}(\mathbf{r}, t) \otimes \mathbf{v}_0(\mathbf{r})] = 0,
\]

where we used that \( \nabla \mu = 0 \) and \( \mathbb{D}[\mathbf{v}_0(\mathbf{r})] = 0 \). Note that equations (10) and (11) simply translate and rotate the initial density \( \rho_0(\mathbf{r}) \) and momentum \( [\mathbf{p}_0(\mathbf{r}) = \rho_0(\mathbf{r}) \cdot \mathbf{v}_0(\mathbf{r})] \) distributions.

### 2.4. Advantages of the model

The novel scale separation method proposed here leads to the proper momentum equation in the long wavelength regime, while realizing wave dynamics for small wavelengths (the latter is responsible for the kinetics of the periodic field, i.e., freezing and melting). The frequency regimes are coupled via the nonlinear terms of the Navier–Stokes equation. The main advantages of the proposed dynamics compared to former descriptions are as follows. (i) As a direct consequence of the scale separation, the present formalism is independent from the particular choice of the free energy functional, and (ii) the elastic properties of the crystal are inherently incorporated into the classical DFT free energy functional, while the macroscopic liquid viscosity is coupled only to the coarse-grained velocity field. In contrast, in the cases of hydrodynamics-coupled Ginzburg–Landau type or phenomenological phase-field models the elastic crystal behavior is simply replaced by rigid body motion, which is usually achieved by applying a phase state dependent viscosity in the dissipative term. Unfortunately, this approximation violates both the linear dissipation approximation and the fluctuation-dissipation theorem at the interface.

### 3. Application to the phase-field crystal model

#### 3.1. Free energy functional

We have chosen the free energy functional of a simple classical DFT, the phase-field crystal theory (PFC) \([8]\), to demonstrate the capabilities of our approach. Variants of this PFC model have been successfully used to describe elastic interactions in the crystal \([19, 30]\), planar
crystal front growth [31], faceting and branching during crystallization in colloidal systems [32], homogeneous [33] and heterogeneous nucleation [34], multiple time scales during glass formation [35], or even solute trapping [36]. (For a review, see [10].) The free energy functional we use reads as [37]

\[ F_{\text{free}} = \int dV \left\{ f(n) - \frac{C_2}{2} (\nabla n)^2 - \frac{C_4}{2} (\nabla^2 n)^2 \right\}, \quad (12) \]

where the local free energy density is

\[ f(n) = (1 - C_0) n^2 \frac{2}{1 - \frac{a}{2}} - \left( \frac{b}{3} \right) \frac{n^3}{1 - \frac{a}{2}} + \left( \frac{b}{3} \right) \frac{n^4}{1 - \frac{a}{2}}, \quad (13) \]

Here the order parameter is the normalized mass density, \( n = \tilde{\rho} - 1 \), where \( \tilde{\rho} = \rho / \rho_0 \) (\( \rho_0 = m n_0 \) is the reference density, where \( m_0 \) is the atomic mass and \( n_0 \) the number density of the reference liquid). The parameter \( C_0 \) can be related to the bulk modulus of the reference liquid via \( K_0 = (1 - C_0)(\rho_0 k_B T) \), while \( C_2 \) and \( C_4 \) are responsible for elasticity. Using \( n(r, t) := \tilde{n} + b n(t, r) \) (where \( \tilde{n} \) is the average and \( b n_t \) is the fluctuation) in equations (12) and (13) together with equation (5) yields the isothermal speed of sound \( c \) in the liquid as the function of the average density,

\[ c^2 = (1 - C_0 - a \tilde{n} + b \tilde{n}^2)(k_B T / m_0), \]

which recovers that of the reference liquid \( (c_0 = \sqrt{K_0 / \rho_0}) \) for \( \tilde{n} = 0 \). From the viewpoint of the numerical simulations it is convenient to scale the length by \( \lambda = \sqrt{2/\mathcal{C}_4 / \mathcal{C}_2} \), the free energy by \( k_B T \), the density by \( \rho_0 \), and the time by \( \tau = \sqrt{\rho_0 \lambda^2 / (k_B T)} \) in the dynamical equations.

3.2. Model parameters

The physical parameters used in the simulations refer to a metallic system (a rough approximant of iron, see table 1). With the present choice of the parameters, the PFC model prefers a homogeneous liquid–triangular crystal equilibrium in 2D with the following equilibrium properties: the scaled average liquid density is \( \tilde{\rho}_L^\text{eq} = 1.051822 \), and the relative equilibrium density gap is \( 2(\tilde{\rho}_L^\text{eq} - \tilde{\rho}_T^\text{eq})/(\tilde{\rho}_L^\text{eq} + \tilde{\rho}_T^\text{eq}) = 0.1875\% \), where \( \tilde{\rho}_L^\text{eq} \) is the equilibrium crystal density, whereas the scaled lattice constant is \( \sigma_0 \approx 1.001 \times 4\pi / \sqrt{3} \).

4. Results and discussion

We performed illustrative simulations in two dimensions (2D) for (i) the elastic response to compression and torsion on an equilibrium crystalline cluster, (ii) planar crystal growth and melting fronts (without noise), and (iii) the capillary wave spectrum of the planar equilibrium crystal–liquid interface. The kinetic equations were solved using a pseudo-spectral scheme with a second order Runge–Kutta time stepping (the grid spacing and time increment were \( \Delta x = \sigma_0 / 8 \) and \( \Delta t = 0.025 \)), respectively [25].

4.1. Dynamical response for elastic deformations

4.1.1. Compression and torsion of a crystalline cluster.. First, the elastic response of a deformed 2D crystal was studied. The simulations were performed on a \( 1024 \times 1024 \) grid. The initial condition was a circular crystal grain equilibrated with the surrounding liquid. Next, two types of deformation were applied on the cluster: (i) compression, by radial \( h \), and (ii) torsion, by tangential modification of the pattern. In case (i) circular compression waves were observed: the average first neighbor distance (lattice constant) in a thin ring oscillates around its equilibrium value, which is the consequence of the wave dynamics. A similar phenomenon could be observed in the case of (ii), where as a response to the torsion the rings have performed angular oscillations (see figures 1(c) and (d)). Figure 1(d) displays the time evolution of the angle \( \alpha \) shown in figure 1(c) (\( \alpha \) is the angle of the vector anchored to an individual particle, i.e. a density maximum). Our results imply that the inclusion of inertia establishes qualitatively correct dynamics for elastic properties.

4.1.2. Phonon spectrum.. As a more precise analysis of the dynamical response for elastic deformations, we measured the phonon spectrum of the bulk crystal. In the 2d monatomic triangular lattice two acoustic phonon branches are present: a longitudinal and a transverse branch. Considering a crystal orientation described by the real-space basis vector set \( \{0, \sigma_0, \pm (\sqrt{3}/2) \sigma_0, -\sigma_0/2\} \) the following two dominant phonon modes emerge from the classical (spring–mass harmonic oscillator) model: (i) for \( \mathbf{q} = [q, 0] \)

\[ \omega_T(q) \propto \sqrt{1 - \cos([\sqrt{3}/2] q \sigma_0)} \quad (14) \]

\[ \omega_L(q) \propto \sqrt{3 [1 - \cos((\sqrt{3}/2) q \sigma_0)]}, \quad (15) \]

where \( T \) and \( L \) denote the transverse \( (\mathbf{u}_\perp \parallel \mathbf{q}) \) and longitudinal \( (\mathbf{u}_0 \perp \mathbf{q}) \) branches, respectively; (ii) for \( \mathbf{q} = [0, q] \), in contrast,

\[ \omega_T(q) \propto \sqrt{3 [1 - \cos(q \sigma_0/2)]} \quad (16) \]

\[ \omega_L(q) \propto \sqrt{3 - \cos(q \sigma_0/2) - 2 \cos(q \sigma_0/2)} \quad (17) \]

Taylor expanding equations (14)–(17) for small wavenumbers gives the following linear relationships:

\[ \omega_{T,L}^{1,2} = \left( \frac{c_{T,L}^{1,2}}{c_{T,L}^{1,2}} \right) q, \quad (18) \]

where superscripts 1 and 2 refer to the \( \mathbf{q} = [q, 0] \) and \( \mathbf{q} = [0, q] \) directions, respectively, while \( c_T^{1,2}/c_{T}^{1,2} = \sqrt{3} \) and \( c_L^{1,2}/c_{L}^{1,2} = c_T^{1,2}/c_{T}^{1,2} = 1 \).

| Table 1. Model parameters taken from [37], [38] and [25], denoted by [a], [b] and [c], respectively. |
|-----------------|-----------------|-----------------|-----------------|-----------------|-----------------|-----------------|-----------------|
| \( C_0 \) | \( C_2 (\AA^2) \) | \( C_4 (\AA^4) \) | \( a \) | \( b \) | \( T \) (K) | \( n_0 \) (Å\(^3\)) | \( m_0 \) (amu) | \( \mu_0^2 \) (mPa s) | \( \mu_B^2/\mu_0^2 \) |
| \(-10.9153^{[a]}\) | \(2.6^{[a]} \) | \(-0.1459^{[a]} \) | \(0.6917^{[a]} \) | \(0.0854^{[a]} \) | \(1833^{[a]} \) | \(0.8081^{[a]} \) | \(55.845 \) | \(5.0^{[b]}\) | \(2^{[c]}\) |
Figure 1. Response of a crystalline cluster to deformations. (a), (c) Typical density distributions (colored maps) and coarse-grained velocity field (arrows) in the case of compression/torsion. (b) Time evolution of the normalized average lattice constant $||\langle\sigma\rangle||=\langle\sigma\rangle/\sigma_0-1$ ($\langle\sigma\rangle$ measured inside a ring between the two concentric circles in panel (a)) in the case of compression. (d) Time evolution of the angle (relative to the $x$ axis) shown in panel (c) in the case of torsion. For the definition of the vector, see the text.

Figure 2. Phonon spectrum of a bulk triangular crystal for (a) the $q=[q, 0]$ and (b) the $q=[0, q]$ directions. Here $T_p$ is the period and $\lambda_p$ the wavelength of the phonon.

As the initial condition for the numerical simulations we used the bulk equilibrium density distribution of the crystal $\rho(r, 0) = \rho_{eq}^{cl}(r)$ and a small amplitude momentum perturbation $p(r, 0) = \rho_{eq}^{cl}(r) \cdot v_0(r)$, where $v_0(r) = v_0 \sin[q \cdot r]$ (the wavelength $q$ was commensurable with the system size). After a short transient time the system comes to a coherent phonon state. Measuring the displacement field $u(r_i, t)$ by tracking the lattice sites (where $r_i$ denotes the equilibrium position of a density peak) gives the time dependent phonon amplitude $u_0(t) = u_0 \sin[\omega(q)t]$, where $u_0 \parallel v_0$. The results are summarized in figure 2, where the inverse frequency ($1/T_p$, where $T_p$ is the period of the phonon measured in natural units) is plotted against the inverse phonon wavelength $\sigma_0/\lambda_p$ (where $\lambda_p$ is the phonon wavelength). The linear fit $1/T_p = C_1 \sigma_0/\lambda_p$ resulted in the following coefficients: $C_1^T = 0.024555$, $C_1^L = 0.042227$, $C_2^T = 0.024405$ and $C_2^L = 0.042286$. The relative errors of the coefficients’ ratios compared to the corresponding theoretical ratios of coefficients $c_1^{L,T}$ are less than 0.7%, which means an excellent agreement with the classical theory for phonon wavelengths $\lambda_p > 20\sigma_0$.

4.2. Steady front propagation

Next, the propagation of the (10) triangular planar front has been studied during freezing and melting. The calculations were performed on a $65536 \times 128$ grid. As expected, steady propagation of the crystal–liquid interface was observed, which follows from the presence of the fluid flow. The front velocity as a function of the relative supersaturation is shown in figure 3(d).

Figures 3(b) and (c) show typical cross sections of the coarse-grained density during crystallization and melting, respectively. In both cases a density wave travels ahead of the crystal–liquid front at close to the speed of sound in the liquid and the crystal. Behind the density wave a steady convective mass flux evolves (denoted by $v_L$ and $v_S$ in the figures), establishing the required mass flux for freezing, or the removal
of the excess material in the case of melting. The velocity of the crystal–liquid front satisfies mass continuity in both cases: \((\dot{\rho}_S - \rho_L)_V = \rho_L \cdot V_L\) for freezing, and \((\dot{\rho}_S - \rho_L)_V = \rho_S \cdot V_S\) for melting.

It is worth noting that the analytical results of [40, 41] for the steady front velocity refer to the unstable liquid that exists beyond the linear stability line, which lies far beyond the supersaturation regime covered by our simulations. The assumptions made in deriving the analytical expression are not valid in the latter regime. Unfortunately, we were unable to get a steady-state planar front for higher supersaturations due to a stress induced destabilization of the growth front at large supersaturations, where the dynamically forming lattice constant differs from the equilibrium lattice constant, which in turn was used in setting the width of the long simulation box. Evidently, carefully designed simulations may overcome this difficulty, however, such investigations are left for a future publication. We wish to stress, furthermore, that the front velocities deduced in [40, 41] apply best probably for describing the ‘fast’ diffusionless mode of solidification 4.3. Capillary wave analysis

The capillary wave spectrum of the fluctuating 2D crystal–liquid equilibrium interface has been analyzed in the presence of fluctuations. In order to exclude subatomic level noise components, the noise field is colored, namely \(S_0(k) = 0\) for \(|k| > k_{\text{max}}\), where \(k_{\text{max}} < k_0/2\). Accordingly, the numerical covariance tensor of the noise matrix corresponding to equation (4) has the prefactor \(\Gamma/(\Lambda^3 \Delta t)\) [39], where \(\Lambda = (k_0/k_{\text{max}})(\epsilon_0/2)\) is the correlation length of the noise consistently with the crystal structure, whereas the factor \(\Gamma = (2\pi/\Delta x)^3/([4\pi/3]k_{\text{max}}^3)\) establishes the constant total power of the noise independently from \(k_{\text{max}}\). (The power spectral density of a Gaussian white noise is constant, therefore the total power is simply proportional to the number of discretized wavevectors.) The simulations were performed on a 1024 \(\times\) 4096 grid, with an equilibrium liquid–crystal–liquid slab as the initial condition. Figure 4(a) shows a snapshot of the fluctuating (11) triangular crystal–liquid interface (only part of the simulation box is presented here). The white curve shows the interface position \(h(x,t)\) calculated from the lattice site positions (locations of local maxima of the density distribution above a threshold value \(\Pi\)). In our calculations \(\Pi = 4\) was chosen. On the basis of the capillary wave theory [43] the interface stiffness can be measured by investigating the long wavelength behavior of the capillary wave spectrum, \(\langle|\hat{h}(q)|^2\rangle = (k_B T)/(q^2 \tilde{\gamma} L)\), where \(\langle\cdot\rangle\) denotes time averaging. The interface stiffness reads as \(\tilde{\gamma} = \gamma(\theta) + \gamma''(\theta)\), where \(\gamma(\theta)\) is the line free energy (two-dimensional interfacial free energy) as a function of the orientation of the crystal face, and \(\gamma''(\theta)\) its second derivative with respect to the orientation. \(L\) denotes the size of the box in the \(x\) direction. Figure 4(b) shows the capillary wave spectrum of the (11) interface, which is in excellent qualitative agreement with the result of molecular dynamics simulations [44]. From the long wavelength fitting \(\log(|\hat{h}(q)|^2) = -2q + \log(\tilde{\gamma} L)\) the stiffness \(\tilde{\gamma}\) can be determined as a function of the crystal plane orientation. For weak anisotropies (the equilibrium crystalline cluster is almost circular, see figure 1(a)), the anisotropic line free energy of a triangular crystal can be approximated as \(\gamma(\theta) = \gamma_0[1 + \epsilon \cos(6\theta)]\). The anisotropy parameter can be evaluated from the simulations as \(\epsilon = (\gamma_{\text{max}} - \gamma_{\text{min}})/[\gamma_{\text{max}} + \gamma_{\text{min}}]\). Unfortunately, the anisotropy of the present system is comparable to the error of fitting \(\log(L\tilde{\gamma})\), therefore only a rough estimate of the anisotropy parameter can be obtained. Assuming \(\tilde{\gamma} = \gamma_0[1 - 35\epsilon \cos(6\theta)]\) the anisotropy parameter

![Figure 3. Steady crystal growth/melting.](image_url)
is approximated as $\epsilon \approx |(\gamma_{\text{max}} - \gamma_{\text{min}})/(\gamma_{\text{max}} + \gamma_{\text{min}})|/35$. Measuring the stiffness for ten differently oriented crystal faces resulted in $\epsilon \lesssim 0.002$, which is somewhat smaller than in the noiseless case, where a direct evaluation of the line free energy [45] yields $\approx 0.0026$ [46]. It is worth noting that at the same reduced temperature the anisotropy of the bcc-liquid system is larger by an order of magnitude [47], suggesting an anisotropy of 1–2%, in agreement with molecular dynamics results for metallic systems [48].

4.4. Growth versus shear- and bulk viscosity

We address here the dependence of the crystal growth rate on the shear viscosity ($\mu_S$) and the bulk viscosity ($\mu_B$). While theoretical considerations and molecular dynamics simulations suggest that the front velocity scales with $\mu_S^{-1}$ in the vicinity of the melting point, a smaller negative exponent is reported at large undercoolings [49]. Shear viscosity can be measured with relative ease in a broad temperature range via combining various methods, and is well known for a range of metallic systems [50, 51]. Much less is known about the bulk viscosity, mainly due to the complexity and the associated uncertainty of the measurement techniques [52]. The handful of relevant experimental data for metallic systems vary between $\mu_B/\mu_S = 1/2$ and 8 [53]. Although this is a quite broad range, the effect on the front velocity is expected to be small in systems with small density gaps (e.g., when the divergence of the velocity field is moderate).

First, we investigate the dependence of front velocity on shear viscosity. The results are summarized in figure 5(a). For constant relative supersaturation ($\|\rho_L\| \approx 0.01$) we recover the expected $v_F \propto \mu_S^{-1}$ relationship for $\mu_B/\mu_S = 2$.

Next, we study the effect of bulk viscosity on front propagation in the range of $\mu_B/\mu_S^0 = 1/16$–8 at constant $\mu_S = \mu_S^0$. As indicated by figure 7(b), the front velocity is a ‘weak’ function of the bulk viscosity, $(v_F - v_F^0)/v_F^0 \propto \log(\mu_B/\mu_B^0)$, where $\mu_B^0 = 2\mu_S^0$ is the reference bulk viscosity and $v_F^0$ the corresponding front velocity. Remarkably, a factor of 16 in the bulk viscosity results in only a factor of less than 2.5 in the front velocity. In addition, in real metallic systems the dimensionless compressibility of the liquid is smaller by a factor of 4 than the $C_0$ used here, therefore the respective physical density gap is less than 3% [37], suggesting an even smaller effect of the bulk viscosity on the steady-state front velocity.

4.5. The effect of the coarse-graining filter

Finally, we explore how the results depend on the choice of the coarse-graining filter. Evidently, the coarse-grained density (and momentum) must be flat in the bulk phases. The coarse-grained fields are generated by using the following convolution [54]:

$$\hat{\phi}(\mathbf{r}, t) := \int d\mathbf{r}' \langle K(\mathbf{r} - \mathbf{r}')\phi(\mathbf{r}', t) \rangle,$$

where $\phi$ can be either the density or the momentum fields, and $K(\mathbf{r})$ is the kernel of the filter. In our calculations we used various lowpass filters. The spectral kernel of a generalized quasi-ideal lowpass filter reads as

$$K(q) = (1 - \tanh[(q - q_0)/\xi])/2,$$
where $\xi$ is a small parameter. Note that for $\xi \to 0$ this filter recovers the ideal lowpass filter, $K(q) = \theta(q - q_0)$, where $\theta(x)$ is the Heaviside function. Another possible choice can be the Gaussian filter, for which

$$K(q) = \exp\left[-(qs)^2/2\right],$$  

where the real-space filtering length, $s$ (i.e. the standard deviation), emerges from symmetry considerations as follows.

The density can be approximated as

$$\rho(r) \approx \rho_0 + f(r) \left[ \Delta \rho + \sum_i A_i \exp(i\Gamma_i r) \right],$$  

where we have a lattice periodic function (plus a density gap $\Delta \rho$) modulated by the slowly varying envelope function $f(r)$ (as illustrated in figure 6(a)), while the corresponding coarse-grained density reads as

$$\hat{\rho}(r) = \rho_0 + f(r) \Delta \rho$$  

(see figure 6(c)). The slow variation of $f(r)$ means that its spectrum decays relatively fast around $q = 0$. Because of the discrete sum in equation (22) in the spectrum of the full density $\tilde{\rho}(q)$, the spectrum of the envelope function $\tilde{f}(q)$ is simply repeated around every reciprocal lattice vector (see figure 6(b)),

$$\hat{\rho}(q) = \rho_0 \cdot \delta(q) + \Delta \rho \tilde{f}(q) + \sum_i A_i \tilde{f}(q - \Gamma_i),$$  

where $\delta(q)$ is the delta function. Choosing one of the first reciprocal lattice vectors ($q_0$) and taking the cross section of the spectrum at $q = t \cdot q_0$ one can define the functions $g(t) := |\tilde{f}(t \cdot q_0)|$ and $h(t) := |\hat{\rho}(t \cdot q_0)|$. If $g(t)$ is a fast decaying function, then $h(t)$ decays around $t = 0$ and $t = 1$ as $\Delta \rho \cdot f(t)$.
and $A_0 \cdot f(1-t)$, respectively (as indicated by the vectors in figure 6(b)). Therefore, the expected optimum spectral cutoff distance for the filters is at $t_0 = \Delta \rho / A_0$. In our case the density gap is $\Delta \rho \approx 0.2$, while the amplitude is $A_0 \approx 1$, therefore, $t_0 \approx 0.2$.

Although the approximation described above might seem to be too simple and rough, it has been verified numerically for the Gaussian filter. We have investigated both $h(t)$ and the coarse-grained density in the crystal as a function of the real-space filtering length $s$ (standard deviation) for an equilibrium crystalline cluster. Figure 7(a) shows $h(t)$ for various filtering lengths $s/\sigma_0$. It can be clearly seen that the spectrum is practically independent from $s$. The best choice for $s$ is then determined by the flatness of the coarse-grained density in the bulk crystal and the behavior of the solid–liquid interface (see figure 7(b)). If the filtering length is too large, $s/\sigma_0 \approx 0.2$, the coarse-grained density in the crystal as a function of the coarse-grained gap is $A \approx 0$ and $J$. Phys.: Condens. Matter 2007 Phys. Rev. B 135 980 2775 (http://prb.aps.org/abstract/PRB/v19/i5/p2775_1)

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5. Summary

We have presented a nonlinear hydrodynamic density functional theory of crystallization. Our work couples the classical density functional theory to the Navier–Stokes equation directly via a phenomenological coarse-graining technique that prevents velocity singularities in the interatomic space. The dynamical equations are fundamental and supplemented with momentum fluctuations emerging from the fluctuation-dissipation theorem. The main virtue of the present model is that the elasticity of the crystal and the liquid is incorporated consistently. This is demonstrated by illustrative simulations including dynamic response to elastic deformations, phonon spectrum and steady crystal growth/melting. In addition, the capillary wave spectrum and the anisotropy of the interfacial free energy are also in good qualitative agreement with the results of atomistic simulations. Our work opens up the way to address a range of microscopic phenomena, such as homogeneous and heterogeneous nucleation, morphology evolution, kinetic roughening, fragmentation, etc in forced convection.

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