Radial velocity measurements from LAMOST medium-resolution spectroscopic observations: a pointing towards the Kepler field

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Abstract Radial velocity is one of the key measurements in understanding the fundamental properties of stars, stellar clusters and the Galaxy. A plate of stars in the Kepler field was observed in May of 2018 with the medium-resolution spectrographs of LAMOST, aiming to test the performance of this new system which is the upgraded equipment of LAMOST after the first five-year regular survey. We present our analysis on the radial velocity measurements (RVs) derived from these data. The results show that slight and significant systematic errors exist among the RVs obtained from the spectra collected by different spectrographs and exposures, respectively. After correcting the systematic errors with different techniques, the precision of RVs reaches \(\sim 1.3\), \(\sim 1.0\), \(\sim 0.5\) and \(\sim 0.3\) km s\(^{-1}\) at S/N\(_{r} = 10\), 20, 50 and 100, respectively. Comparing with the RVs of standard stars from the APOGEE survey, our RVs are calibrated with a zero-point shift of \(\sim 7\) km s\(^{-1}\). The results indicate that the LAMOST medium-resolution spectroscopic system may provide RVs with a reasonable accuracy and precision for the selected targets.

Key words: technique: spectroscopy — stars: radial velocity — stars: statistics

1 INTRODUCTION

The measurements of radial velocities (RVs) of a large number of stars play an important role in understanding the structure of the Galaxy (e.g., Binney & Merrifield 1998) and the kinematics of globular clusters (e.g., Gunn & Griffin 1979). RVs are also valuable for the discovery and determination of orbital parameters of binary systems (e.g., Nidever et al. 2002). In recent years, many large surveys provide RVs for large samples of stars with high-precision, such as the Sloan Digital Sky Survey (SDSS) for millions of stars (Alam et al. 2015; Eisenstein et al. 2011; Adelman-McCarthy et al. 2006) and the Gaia observations of some seven million sources with median RVs (Gaia Collaboration et al. 2018).

When combined with photometric observations, RV variations can offer more precise constraints on the theoretical frameworks of stellar pulsation models (Marconi et al. 2013) and present an unbiased mass determination of the components of eclipsing binary stars (e.g., Vučković et al. 2007). The Kepler space mission monitored about 200 000 stars in the region of the constellations Cygnus and Lyra for a period of \(\sim 4\) yr continuously (Borucki et al. 2010), providing unprecedentedly high-quality photometric data for many types of variable stars (Gilliland et al. 2011; Vogt et al. 2015; Wood et al. 2017).
LAMOST—instance, APOKASC (Pinsonneault et al. 2014, 2018) and Zhao et al. (2012). The Large Sky Area Multi-Object Fiber Spectroscopic Telescope (also called the Guoshoujing Telescope) which is located at the Xinglong Observatory, China. More details can be found in Cui et al. (2012) and Zhao et al. (2012).

2 OBSERVATIONS AND DATA REDUCTION

2.1 Observations

LAMOST has a focal plane of $5^\circ$ in diameter and is equipped with 4000 fibers, hence the telescope can observe 4000 targets (including sky light) per exposure. One circular field in the Kepler field, LK07, had been chosen to be observed, with the aim to test the precision of RVs from medium-resolution spectra. More details on the classification of each Kepler field can be found in De Cat et al. (2015). The central position of LK07 is defined by the coordinates of the bright star HIP 95119 with $V = 7.03$, $\alpha(2000) = 19:31:02.82$ and $\delta(2000) = +42:41:13.06$. This star is used for calculation of wavefronts to reshape the mirrors into good condition. The input targets are chosen based on several criteria as follows, with decreasing priority: two pulsating stars attracting particular interests, six standard stars, 164 eclipsing binary stars and the remaining stars with a similar strategy to what is described in Zong et al. (2018).

Table 1 displays the spatial distribution of 3626 targets which are finally allocated to fibers.

Table 1

| Observation date | Begin (UT) | End (UT) | Exposure time | Seeing (arcsec) | Parameter |
|------------------|------------|----------|---------------|-----------------|-----------|
| 2018 May 24      | 18:26:16   | 19:55:33 | 900 × 5       | ~3.0            | 7214      |
| 2018 May 28      | 17:23:20   | 19:39:33 | 900 × 7       | ~2.6            | 10375     |
| 2018 May 29      | 17:36:44   | 19:38:12 | 600 × 9       | ~2.3            | 12329     |
| 2018 May 30      | 17:58:56   | 19:29:23 | 900 × 5       | ~2.4            | 7414      |
| 2018 May 31      | 18:02:13   | 19:32:49 | 1200 × 4      | ~2.3            | 6088      |
| Total            |            |          | 25 500        | 43 420          |           |

Notes: The time between begin and end includes the readout time but not the overhead time.

2.2 Data Reduction

In this paper, we will address an estimation of the precision of RVs derived from the current LAMOST pipelines. It is evaluated through time-series spectroscopic observations pointing towards the Kepler field. The structure of this paper is organized as follows. The details of observations and data reduction are described in Section 2. We present the techniques to estimate the precision of RVs in Section 3, followed by a comparison with APOGEE RVs in Section 4. We give our discussion in Section 5 and conclude with our results in Section 6.
print will be observed continuously until it leaves the view of LAMOST or the twilight is too bright to continue the observation. The latter one is the main reason for stopping the observations in late May. During the observations, the weather condition typically has a seeing of around 2.5". A total of 30 plates has been obtained with exposures of 900 s × 5, 900 s × 7, 600 s × 9, 900 s × 5 and 1200 s × 4. The total exposure time corresponds to 7.08 hours.

### 2.2 Data Reduction

The raw products of LAMOST observations are the two-dimensional (2D) CCD frames. For each exposure, a total of 32 (16 blue and 16 red) 2D frames are obtained, with each frame containing 250 raw spectra almost equally distributed on the CCD. The first procedure to reduce those raw data is to evaluate the quality of observations and the telescope performance, such as seeing, cloud coverage and checking for light pollution. The 2D frames with good quality are used to produce one-dimensional (1D) calibrated spectra by the LAMOST 2D pipeline, which is implemented with procedures similar to those of SDSS (Stoughton et al. 2002). The main tasks of the LAMOST 2D pipeline include dark and bias subtraction, flat field correction, spectral extraction, sky subtraction and wavelength calibration (see more details in Luo et al. 2015). One notes that the 2D pipeline conducted on the medium-resolution data does not contain stacking of sub-exposures and combination of different wavelength bands with these procedures which were used for the low-resolution spectra.

The scientific quality of the obtained 1D spectra is evaluated before the atmospheric parameters are calculated. We use the signal-to-noise in SDSS-like r band (hereafter S/N for simplification) as the indicator. The spectra with S/N higher than 10 will be fed to the 1D pipeline to derive parameters from the LAMOST Stellar Parameter Pipeline (LASP) and to classify the spectral type. The RVs for stars and redshifts for galaxies (or quasi-stellar objects) are also provided through this pipeline. The current version v2.9.7 pipeline is used for medium-resolution spectra obtained from the LK07 plates. More details of these pipelines can be found in Luo et al. (2012) and Luo et al. (2015).

### 3 ANALYSIS OF RADIAL VELOCITIES

#### 3.1 Distributions of RV Measurements

The high-quality calibrated spectra can definitely produce atmospheric parameters. However, we will merely discuss the results of the measurement of the precision of RVs in this paper. The total number of RV measurements obtained from the 30 plates is 43 420. The last column of Table 1 lists the individual number of RVs in each night. We typically measured around 1500 RVs from each plate. We note that a scandium arc\(^2\) was used to calibrate the wavelength for the spectra of the first five exposures, while a thorium-argon arc was used for the remaining observations. We therefore will not consider the data set from the first five exposures in further analysis. Besides, we checked that the data do not affect the main scientific results significantly.

The total number of stars with RVs is 1880 from the spectra obtained through 2018 May 28–31. Figure 2 shows the distribution of the number of RV determinations that was derived for each of these stars from these 25 exposures. We find that more than half of the targets have 25 RV measurements. The RVs of the same stars visited multiple times can be an excellent practice to examine the robustness of RVs derived from one system (or telescope). We calculate the relative RVs (ΔRVs) for each

\(^2\) The scandium will not be used any longer as a result of comparison to the thorium-argon arc.

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**Fig. 1** Sky coverage of all targets (in grey) observed by LAMOST pointing towards the LK07 field. The stars with atmospheric parameters derived from LASP are marked in dark.

**Fig. 2** Distribution of the times for stars derived with RVs from the 25 exposures.
target by subtracting the weighted mean of their values, where the square of S/N is used as weight.

Figure 3 displays the scatter of the measured $\Delta RV$s. From the distribution we can directly see that the precision is roughly 1 km s$^{-1}$. However, the outlier measurements are possibly the results from RV variables in particular with high S/N.

3.2 Selection of Constant $RV$ Stars

To precisely check where the outlier points come from, or concretely to estimate the precision, we need to select the “constant” $RV$ stars first. Stars will fall into our sample if they have relatively small $\Delta RV$ from different plates. The concrete value is taken as 1 km s$^{-1}$ since it is the rough precision as estimated from Figure 3. In addition, we find that more than half of the 1880 stars exhibit RVs with standard deviation less than 1 km s$^{-1}$. This criterion can be more strict but it will lose a number of stars that we can use to compare the systematic errors in the following sections. The final sample contains 803 stars with 20 075 RVs, which are measured from all the 25 plates, called “common constant” stars below.

3.3 Analysis of Systematic Errors

Figure 4 shows the distribution of $\Delta RV$ where the common constant stars are divided into 16 groups as labeled by their spectrograph IDs. The results suggest very small systematic errors between different spectrographs, as revealed by the weighted values$^3$ of the $\Delta RV$. The values are all near zero but with different standard deviations (see the errorbars in this figure). We note that the symbol itself represents a size of about 200 m s$^{-1}$. The existence of systematic errors between different plates is illustrated in Figure 5. The measured RVs are now divided into 25 groups labeled by the sequence number of the observed plate. We clearly see that there are several $\Delta RV$ leaps between different nights (as indicated by red vertical lines), typically with values on the order of a few hundred m s$^{-1}$. In addition, within the same night, shifts are seen between consecutive plates though they are generally smaller than the typical values between different nights.

3.4 Correction for Systematic Errors

As shown in the previous section, systematic errors exist among the $RV$ measurements when they are obtained at different observational times (major factor) and from different spectrographs (minor factor). These errors induce an enlargement in the uncertainties of RV measurements from the LAMOST medium resolution spectra. In this section, we introduce a technique to handle these systematic errors, which will significantly improve the RV precision.

We still use the common constant stars to correct the systematic errors. This time, all these stars are divided into $25 \times 16$ groups by their plate ID and spectrograph ID. We calculate the averaged weights $\overline{\Delta RV}_{ij}$ with the formula

$$\overline{\Delta RV}_{ij} = \frac{\sum_k x_k \cdot \Delta RV_{ijk}}{\sum_k x_k},$$

(1)

where $x_k$ is the square of S/N and the index $k$ denotes the sequence of each star within one group which is identified by its indices $i \in [1, 25]$ and $j \in [1, 16]$. $\Delta RV_{ij}$ are the systematic errors since the RVs of the common constant stars are independent of their observational time and spectrograph. We can easily correct the systematic errors by applying the formula

$$RV_{corr} = RV - \overline{\Delta RV}_{ij},$$

(2)

where RV (with the omission of the subscripts $i$, $j$, $k$) is the measured RV from the LAMOST pipelines.

Figure 6 displays the distribution of $\Delta RV$s before and after correcting the systematic errors. The distribution of $\Delta RV$s now is unimodal centered around zero with a slight shift of about 0.03 km s$^{-1}$ to its uncorrected values, which suggests that the systematic errors have been corrected. The fitting curve demonstrates that the precision of the RV measurement is a function of the quality of the spectrum (S/N). We note that the fitting is performed on the data with S/N $\in [10, 150]$ since the number of spectra with a higher S/N value is very small and the outlier data points will greatly affect the fitting of the curve. The 1σ precision reaches $\sim 1.3$, $\sim 1.0$, $\sim 0.5$ and $\sim 0.3$ km s$^{-1}$ at S/N=10, 20, 50 and 100 after the correction, instead of $\sim 2.9$, $\sim 1.5$, $\sim 0.6$ and $\sim 0.3$ km s$^{-1}$ before the correction, respectively. This correction indicates that the precision will be especially improved for the spectra with S/N $< 50$.

4 CALIBRATION OF RVs

4.1 External Errors with APOGEE

As we discussed the internal errors in the above section, in this section, we will compare the LAMOST RV common constant stars with APOGEE RV standard stars. We have cross-identified 34 stars with RV measurements in our target list and from Huang et al. (2018), in a range from about $-110$ km s$^{-1}$ to $50$ km s$^{-1}$. We consider the RV values after correction with Equation (1).

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$^3$ The same weight is taken as the one mentioned in Section 3.1.
Fig. 3 Distribution of the relative RVs ($\Delta RV$) as a function of the spectra quality, S/N (bottom panel). The projection of the $\Delta RV$ histogram with a bin width of 0.2 km s$^{-1}$ is shown in the top panel. We note that the long side wings are not shown in this plot.

Fig. 4 Distribution of the relative RVs ($\Delta RV$) for the “common constant” stars as a function of S/N (the IDs of spectrographs are marked in numbers. The S/N scale between two consecutive vertical lines is set to be 200. The horizontal dashed line represents the RV under ideal measurement, which is zero, without any deviation. The weight values of each group are signified by open squares with their associated errors (standard deviations). More details are given in the text.

Fig. 5 Similar to Fig. 4 but according to the times of exposure. The vertical (red) lines indicate the exposure sequences in different nights marked by their dates (UTC) just below the exposure number.

Figure 7 shows a statistical comparison for these 34 stars, where a good agreement between the two data sets can be clearly seen. The optimal fitting is a line that is nearly parallel to the bisectrix with a zero-point shift of about 7 km s$^{-1}$.

4.2 An Scientific Example of Combination with Photometry

After we determined the external and internal errors, the RVs derived from medium-resolution spectra can be cal-
Fig. 6 Similar to Fig. 3 but for the constant stars before (in blue) and after (in brown) correction for the systematic errors. The solid curves represent the optimal fitting whose function is given in the bottom panel (see text for details).

Fig. 7 Statistical comparison of RV between LAMOST and APOGEE. The best linear fit corresponds to a line that is nearly parallel to the bisectrix. Note that the errors are smaller than the symbols themselves.

Fig. 8 The folded light curves (top panel) and RVs (bottom panel) of KIC 6863229 as a function of phase. The fitting curve in the bottom panel shows a sinusoidal wave (solid line).

\[ \text{Min.I} = \text{BJD} 2454954.485(52) + 1.99492(28) \times E, \]

where \( T_0 = \text{BJD} 2454954.485(52) \) and \( P = 1.99492(5) \) (d) are the time of a primary eclipse and the available period, respectively, while \( E \) refers to the cycle number. A more detailed analysis of those data can be found in a forthcoming paper (Liu et al. 2019, in prep.).

5 DISCUSSION

The precision of RVs from LAMOST medium-resolution spectra suffers from slight and significant systematic errors induced by different spectrographs and observation times, respectively, particularly for the observation campaigns with large gaps. The most significant systematic errors are found between different observational nights, which may have zero-point differences of about 0.5 km s\(^{-1}\). A slight drift also exists for the RV measurements during the same night, typically with a value of a few hundred m s\(^{-1}\). The instrumental effects can account for that, such as the cooling device which is put on the CCDs of LAMOST. Due to coolant consumption, the weight of that device will change and influence the position of spectra where their position is used for calibrating the wavelength. To avoid this, a semiconductive device will be used for cooling the CCDs without changing their weight. The slight systematic errors between different spectrographs are very possibly caused by zero-point differences between these spectrographs, thus, again, changing the wavelengths which are used for deriving RVs.

Although the RVs suffer from systematic errors, these errors can be corrected through different techniques. In this

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4 \url{http://archive.stsci.edu}
paper, we address one method to correct the measured $RV$s and the results look reasonable. Our calculation is based on 803 common “constant” stars which have $RV$s that do not change $>$ 1 km s$^{-1}$ over time. The systematic errors caused by instrumental effects or observational campaigns should be the same for all the stars. Therefore, one can use these stars to evaluate the intrinsic precision of $RV$ measurements. Our results also give an estimation of the precision for different quality of medium-resolution spectra as indicated by their S/N in the SDSS-like $r$ band. After the correction, the precision reaches $\sim$1.3, $\sim$1.0, $\sim$0.5 and $\sim$0.3 km s$^{-1}$ at S/N=10, 20, 50 and 100, for which the corresponding values before correction are $\sim$2.9, $\sim$1.5, $\sim$0.6 and $\sim$0.3 km s$^{-1}$, respectively. Another technique is to calculate differential $RV$s before re-shifting the $RV$ zero-points, which is very similar to the measurement of differential magnitudes for variable stars in photometry (Pan et al. in prep.). Our method should also draw one’s attention to the fact that low-resolution spectra probably suffer from systematic errors as well. However, time series plates are only obtained for a low percentage of plates. A better way to remove systematic errors in low-resolution spectra can be by using some standard $RV$ stars based on a similar technique.

The external errors of LAMOST are also calculated through 34 common stars with the APOGEE catalog from Huang et al. (2018). We find a systematic difference of $\sim$7 km s$^{-1}$ between those two data sets. We discuss an example of an eclipsing binary star, whose calibrated $RV$ curve with reasonable accuracy was analyzed in combination with Kepler photometry. This could be very useful to derive robust fundamental parameters for such stars, in particular for masses (Zhang et al. 2017).

6 CONCLUSIONS

A plate in the Kepler field had been observed by LAMOST with the medium-resolution spectrographs and produced through the most updated pipelines with $RV$s. These targets that were visited multiple times offer an opportunity to test the accuracy and precision of the $RV$s derived from this new system. By analyzing the 25 plates obtained through 2018 May 28–31, we find that there are systematic errors between different spectrographs and observational campaigns. However, these errors can be removed well by dividing the targets into different groups according to the two observational factors. The internal errors for $RV$s are found to have the values of 1.3, 1.0, 0.5 and 0.3 km s$^{-1}$ at S/N=10, 20, 50 and 100, respectively. We also compare our results with the APOGEE $RV$ standard stars and find the external error is about 7 km s$^{-1}$ based on 34 common stars.

We end this paper with the remark that the precision of $RV$s for medium-resolution spectra is a fundamental measurement for the medium-resolution survey of LAMOST in the next five years, as well as the atmospheric parameters. The scientific goals that can be studied with such spectra are built on these precisions.

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