BEYOND THE BRIM OF THE HAT: KINEMATICS OF GLOBULAR CLUSTERS OUT TO LARGE RADII IN THE SOMBRERO GALAXY

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ABSTRACT

We have obtained radial velocity measurements for 51 new globular clusters around the Sombrero galaxy. These measurements were obtained using spectroscopic observations from the AAOmega spectrograph on the Anglo-Australian Telescope and the Hydra spectrograph at WIYN. Combining our own past measurements and velocity measurements obtained from the literature, we have constructed a large database of radial velocities that contains a total of 360 confirmed globular clusters. Previous studies’ analyses of the kinematics and mass profile of the Sombrero globular cluster system have been constrained to the inner ~9′ (~24 kpc or ~5R_e), but our new measurements have increased the radial coverage of the data, allowing us to determine the kinematic properties of M104 out to ~15′ (~41 kpc or ~9R_e). We use our set of radial velocities to study the GC system kinematics and to determine the mass profile and V-band mass-to-light profile of the galaxy. We find that M/L_V increases from 4.5 at the center to a value of 20.9 at 41 kpc (~9R_e or 15′), which implies that the dark matter halo extends to the edge of our available data set. We compare our mass profile at 20 kpc (~4R_e or ~7.4) to the mass computed from X-ray data and find good agreement. We also use our data to look for rotation in the globular cluster system as a whole, as well as in the red and blue subpopulations. We find no evidence for significant rotation in any of these samples.

Key words: galaxies: elliptical and lenticular, cD – galaxies: individual (M104) – galaxies: kinematics and dynamics – galaxies: star clusters: general

Online-only material: machine-readable and VO tables

1. INTRODUCTION

While the details of galaxy formation are not yet well understood, the current paradigm suggests that dark matter (DM) halos play a critical role in the process. In these halos, baryonic matter collects and cools to form stars and galaxies, and it is believed that the subsequent merging of these halos and their contents leads to the formation of more massive galaxies. Thus, understanding the structure of DM halos is fundamentally important for testing galaxy formation models and cosmological theories. One way to examine the DM halo of a galaxy is to analyze its mass profile out to large radii. For gas-rich galaxies such as spirals, this can be done by examining the kinematics of the stars and the neutral hydrogen gas. However this type of analysis is much more difficult for early-type galaxies since they lack these easily observed dynamical tracers. Globular cluster (GC) systems provide an excellent set of alternative tracers. Several photometric studies have been made of the GC system of M104. RZ04 performed a wide-field photometric study of the GC system of the galaxy in B, V, and R, and detected GC candidates out to 25′ (15R_e or 68 kpc). They also found that the GC system of the Sombrero contains roughly 1900 clusters with a de Vaucouleurs law radial distribution that extends to 19′ (11R_e or 51 kpc), where extent is defined as the radius where the surface density of GCs is consistent with zero within the estimated measurement errors. Larsen et al. (2001), Spitler et al. (2006), and Harris et al. (2010) performed Hubble Space Telescope photometry on the more crowded central regions of M104 in order to detect GC candidates closer to the center of the galaxy. All of these photometric studies found that the GC system of M104, like those of many giant galaxies, exhibits a bimodal color distribution which is assumed to correspond to a metal-rich red subpopulation and a metal-poor blue subpopulation (Gebhardt & Kissler-Patig 1999; Kundu & Whitmore 2001;
Rhode & Zepf 2004). Examining the kinematics of GCs in these two subpopulations can test whether or not they formed during two distinct phases of galaxy formation.

In addition to these photometric studies, several groups have performed spectroscopic observations of the M104 GC system (Bridges et al. 1997, 2007; Larsen et al. 2002; Alves-Brito et al. 2011). Bridges et al. (2007, hereafter B07) performed a relatively wide-field kinematic study using spectroscopically measured radial velocities for 108 GCs out to 20′ (12R_e or ∼54 kpc) with the Two-Degree Field (2dF) spectrograph on the Anglo-Australian Telescope (AAT). They found that the M/L_V ratio of the galaxy increases with distance from the center to ∼12 at 9.5′ (6R_e or ∼25 kpc), which provides tentative support for the presence of a DM halo around M104. In addition, they found no evidence of global rotation in the GC system or in the red and blue subpopulations. However, the limited number of GCs at large radii in this study makes the results in the outer regions uncertain. The most recent spectroscopic study by Alves-Brito et al. (2011) consists of a large number of clusters (over 200); however, they only observe GCs out to a distance of about 27 kpc (∼6R_e or ∼10′) from the center of the galaxy. In addition, they did not perform a kinematic analysis of their sample. They did, however, confirm the metallicity bimodality of the GC system detected in the earlier photometric studies (peaks at [Fe/H] = −1.4 and [Fe/H] = −0.6). In order to acquire a more complete understanding of the dynamical properties of the galaxy, it is crucial to obtain both large numbers of velocity measurements and measurements that provide significant spatial coverage.

We have obtained new spectroscopic observations of M104 GCs using the AAOmega spectrograph on the 3.9 m AAT and the Hydra spectrograph on the WIYN 3.5 m telescope. From these data we obtained 51 new GC velocities and we combine these new measurements with data from the literature to create a sample of 360 confirmed M104 GCs with reliable radial velocity measurements that include objects out to 24′ (∼14.1R_e or ∼64.9 kpc) in galactocentric distance. This is the largest sample of radial velocity measurements used for a kinematic study for the Sombrero to date. Using this sample, we were able to study the kinematics and mass profile of M104 to a larger radial extent than previous studies.

The paper is organized as follows. Section 2 covers the acquisition and processing of the data, while the methods used to obtain radial velocity measurements for our target GC candidates are discussed in Section 3. Section 4 provides an analysis of the rotation within the GC system and the determination of the mass profile. Section 5 provides a discussion of our results compared to kinematic studies of other mass tracers in M104 and other galaxies. Finally, Section 6 summarizes our findings.

2. OBSERVATIONS AND DATA REDUCTION

2.1. Observations

2.1.1. AAOmega Observations

Spectroscopic observations were acquired for this study during two observing runs. The first spectra were taken with the AAT using the AAOmega multi-object spectrograph in 2009 May. AAOmega is fed by the 2dF fiber positioner which contains 392 fibers. The wide field of view of AAOmega is well suited for our observations since the GC system of M104 extends to at least 19′ (∼11R_e or ∼51 kpc) from the galaxy center (Rhode & Zepf 2004). For each fiber the dual-beam spectrograph produces both a red and a blue spectrum. For our observations, the red arm of the spectrograph was configured with the 1000I VPH grating centered at 8580 Å, resulting in spectra with a dispersion of ∼0.54 Å pixel⁻¹ and a wavelength range of ∼8015–9120 Å. The blue arm of the spectrograph was configured with the 580V VPH grating centered on a wavelength of 4750 Å, yielding spectra that have a central dispersion of ∼1.04 Å pixel⁻¹ and a wavelength range of ∼3680–5800 Å. It should be noted that for the purpose of our analysis the red and the blue AAOmega spectra were treated as two independent data sets.

Targets for our observations were selected from the photometric GC system study of RZ04, in which 1748 candidate GCs around M104 were identified using wide-field BVR images. From the RZ04 list we selected ∼500 candidates without measured velocities and with V magnitudes between 19.0 and 22.0. From this magnitude-limited list we created two spectrograph configurations to be observed over three nights with AAOmega. Selection of GC candidates for the two configurations was weighted by magnitude, with brighter objects receiving higher priority. Due to inclement weather we were only able to observe one of the two configurations during the run. Seeing during both nights of observations was poor and ranged from 2–3′. Our resulting data set is comprised of thirteen 1800 s exposures that include a total of 268 GC candidates. Internal quartz lamp flats and arc lamp spectra were also taken for calibration purposes.

2.1.2. Hydra Observations

Additional GC candidates were observed using the Hydra spectrograph on the WIYN 3.5 m telescope at Kitt Peak National Observatory (KPNO) in 2011 February. Hydra is a multi-object spectrograph with ∼85 available fibers and a one degree field of view. Targets for the Hydra observations were selected from the remaining unobserved objects in the RZ04 list described above. The throughput of the Hydra spectrograph is lower than that of AAOmega, so we further restricted our target selection to only those objects with V magnitudes brighter than 20.5. Our resulting target list contained 72 GC candidates. We observed a total of 12.5 hr on a single fiber configuration which contained a total of 48 GC targets. Due to a combination of high winds and high humidity, the seeing was relatively poor for WIYN and ranged from 1′ to 2′ throughout our observations. Dome flats, dark frames, and arc spectra were also obtained during the run. For the observations, Hydra was configured with the red fiber bundle and the 600@9.0 grating centered at a wavelength of 5300 Å, providing a spectral range that extends from 3880 to 6710 Å. This is similar to the spectral coverage of the blue arm of the AAOmega data. To improve the signal-to-noise ratio (S/N) of our spectra we also binned the pixels of the STA1 CCD two by two.

2.2. Reductions

2.2.1. AAOmega

The red and blue AAOmega spectra were reduced using the 2dfrd pipeline software (Croom et al. 2005). The spectra were first flat-fielded and then wavelength-calibrated using the arc lamp spectra. Next, a throughput calibration was performed.

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6 The WIYN Observatory is a joint facility of the University of Wisconsin-Madison, Indiana University, Yale University, and the National Optical Astronomy Observatory.

7 Kitt Peak National Observatory, part of the National Optical Astronomy Observatory, is operated by the Association of Universities for Research in Astronomy (AURA) under a cooperative agreement with the National Science Foundation.
using night sky lines, and the sky was subtracted using dedicated sky fibers. Finally, the individual spectra were extracted using a weighted extraction routine, and the object spectra were stacked to produce a final combined set of spectra.

Upon examination of the reduced data, we discovered that some fibers in each of the blue exposures exhibited poor calibration of the wavelength zero-point, with errors \( \sim 1\text{–}3 \, \text{Å} \). After further investigation we found that this problem affected a different set of fibers in each exposure, such that a given fiber might have bad calibration in only one or two of the 13 exposures. To circumvent this problem, we restacked the blue spectra manually using the IRAF\(^8\) task SCOMBINE, one fiber at a time, excluding any spectra with wavelength calibration errors greater than 1 Å.

Finally, to prepare the spectra for cross-correlation, we trimmed \( \sim 10 \, \text{Å} \) from the ends of each spectrum to remove any potential edge artifacts, and then continuum-subtracted the data using a Legendre polynomial fit (eighth order for the blue spectra and ninth order for the red).

2.2.2. Hydra

The Hydra spectra were reduced using the IRAF DOHYDRA spectral reduction package. Before running DOHYDRA, the flat field, arc lamp, and object spectra were bias-subtracted and corrected for dark current using CCDPROC. Next, DOHYDRA was used to extract the individual spectra and perform the throughput correction. Wavelength calibration of the object spectra was then performed using the arc lamp spectra. The final rms error of the best-fit wavelength solution was less than 5% of the dispersion of the spectra. Finally, the spectra were sky subtracted. Once the spectra were reduced they were scaled to the flux level of the brightest observation, cosmic ray cleaned, and stacked using SCOMBINE. To remove any edge effects \( \sim 10 \, \text{Å} \) was clipped from the two ends of each spectrum. Finally, the continuum for each spectrum was fit with an eighth-order Legendre polynomial, and subtracted to produce the final data set.

3. ANALYSIS

3.1. Measuring the Globular Cluster Velocities

Heliocentric radial velocities for our target objects were measured using the IRAF FXCOR task, which performs a Fourier cross-correlation of each object spectrum against a set of template spectra. Our template spectra were generated using the GALAXEV stellar population synthesis code (Bruzual & Charlot 2003). We chose the GALAXEV model templates since this allowed us to use one consistent set of templates for all of our spectra which cover a wide wavelength range from 3680 to 9120 Å. Six templates were created, each assuming a single instantaneous burst of star formation with a Salpeter initial mass function and a range of metallicities from an \([\text{Fe}/\text{H}]\) of \(-2.25\) to \(+0.56\). These values fully encompass the metallicity range for M104 GCs found by Alves-Brito et al. (2011).

Each run of the model was allowed to evolve for 12 Gyr, which is consistent with the 10–15 Gyr age spread for M104 GCs determined by Larsen et al. (2002). We ran additional tests using models with a range of ages spanning a few Gyr around our chosen value. However, at a given metallicity these small changes in the age of the models did not produce different cross-correlation results, and consequently we chose to use a single age for our final templates.

Once the spectra were cross-correlated with the GALAXEV templates, we had six velocity measurements and associated FXCOR uncertainties for every object in each of the three data sets. We then performed several cuts on each set of measurements to eliminate spurious values and weak detections from our sample. For bright target objects with high S/N (roughly 16% of the targets), the cross-correlation routine measures roughly the same velocity value for each of the six model templates. However, as the S/N of the target object spectra decreases, one or more of the templates may fail to produce a strong cross-correlation peak, resulting in velocity measurements that are wildly different from the rest of the measurements for that object. Keeping these spurious measurements would skew the calculation of the final mean velocity for these objects. Consequently, our first step was to examine the self-consistency of the six velocity measurements for each object by comparing each measurement with the median value for the ensemble. We used standard error propagation to compute the uncertainty on the median using the errors on the individual measurements from FXCOR. Those measurements that fell outside 3\(\sigma\) from the median value were rejected.

With a self-consistent set of measurements for each object, we next determined which measurements were too weak to be considered reliable. The most common way to do this is to use the Tonry–Davis \(R\) (TDR) coefficient (Tonry & Davis 1979) which is defined as

\[
R = \frac{h}{\sqrt{2\sigma_v}},
\]

where \(h\) is the height of the true peak of the cross correlation function, and \(\sqrt{2\sigma_v}\) is the average height of all the peaks in the cross-correlation function. Selection of the \(R\) value cutoff is a balance between maximizing the final sample size while also ensuring the reliability of the final velocity measurements. To determine our cutoff value we first cross-correlated nine of the sky spectra (that were observed for calibration purposes with our data) with our six model templates using the same FXCOR parameters that we used for the object spectra. This allowed us to estimate the values of \(R\) that could be produced by cross-correlating our templates with noise. We established a preliminary cut at an \(R\) value of 3.6 based on the mean \(R\) from the sky cross-correlations. We were then able to take advantage of the fact that we had dual AAOmega spectra to refine this limit. We compared the mean velocity for each object from the red AAOmega spectra to its corresponding mean velocity computed in the blue data. For a given object, the two data sets should produce the same velocity. Consequently, we incrementally increased the \(R\) value cut until the majority of the objects with highly discrepant, i.e., \(\gg 3\sigma\) or 400 km s\(^{-1}\), velocities between the red and blue data were eliminated from the sample. Using this, we determined the optimal \(R\) cut to be at a value of 4.25. Any measurements below this threshold were removed from the subsequent analysis.

Finally, we performed a rough velocity cut, and for each object, we removed velocity measurements less than \(-500\) km s\(^{-1}\) or greater than 15,000 km s\(^{-1}\). The lower limit of \(-500\) km s\(^{-1}\) encompasses the expected velocities of most nearby Galactic stars. For objects with low S/N, a pattern of strong, high velocity peaks above \(-15,000\) km s\(^{-1}\) began to appear in some of the cross correlation functions. These are unlikely to be real since

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\(^8\) IRAF is distributed by the National Optical Astronomy Observatories, which are operated by the Association of Universities for Research in Astronomy, Inc., under cooperative agreement with the National Science Foundation.
the strength of these peaks is inconsistent with the low S/N of the data and they occur at a frequency much higher than expected for genuine high-redshift objects. As a result, we chose to reject these individual measurements as unreliable. For the objects with one or more velocity measurements remaining after this series of cuts, the individual measurements were combined using an uncertainty-weighted mean to produce a final velocity measurement for that object. On average, four of the six velocity measurements for each object survived the cuts and were used in this final averaged velocity. The final uncertainties for the mean velocity for each object were computed by propagating the FXCOR errors from the individual measurements included in the mean. For reference, the average velocity uncertainty for an object is \( \approx 19 \text{ km s}^{-1} \). After this series of cuts, 18 objects remained from the 48 measured with Hydra, 48 objects remained from the blue AAOmega data set, and 117 objects remained in the red AAOmega data set.

There are 30 objects in common between the final red and blue AAOmega samples. Figure 1 shows the comparison between the red and the blue velocities for each of these objects. The mean difference between the red and blue velocities is \( 45.5 \pm 92.4 \text{ km s}^{-1} \), indicating that there is good overall agreement between the velocities determined from the two data sets. We find no significant systematic offset, which suggests that our cross correlation methods are self consistent.

![Figure 1](image.png)

**Figure 1.** AAOmega red velocity vs. AAOmega blue velocity for the 30 matching objects that pass the velocity selection criteria. The solid black line indicates a 1:1 velocity ratio. The mean velocity difference is \( 45.5 \pm 92.4 \text{ km s}^{-1} \), indicating that there is good overall agreement between the velocities determined from the two data sets. We find no significant systematic offset, which suggests that our cross correlation methods are self consistent.

In addition to our own velocity measurements, we assembled an additional sample of velocities using the results from previous work in the literature. First, we include 46 velocity measurements obtained by Bridges et al. (1997) using the William Herschel Telescope and the Low Dispersion Survey Spectrograph. An additional 16 objects were obtained from Keck Low Resolution Imaging Spectrometer observations of Larsen et al. (2002). This excludes the object identified as H2-27 in the Larsen et al. (2002) list since the authors declare the velocity measurement to be unreliable. B07 determined velocities for 170 objects with the 2dF spectrograph at the AAT and with the Hydra spectrograph on WIYN. Finally, Alves-Brito et al. (2011) measured 259 velocities for GC candidates using Keck and the Deep Imaging Multi-Object Spectrograph. We cross-matched the objects in each of these lists and found repeated velocity measurements for a total of 38 objects, including two objects that were repeated more than once. As with the repeats in our own observations, we adopted the uncertainty-weighted mean of all available velocity measurements as the velocity for these objects. The resulting literature sample consists of 450 unique objects.

Each of these studies used a different set of criteria to separate true GCs from contaminating objects such as foreground stars. Therefore, in order to implement a consistent method to separate true GCs from contaminating objects we have included velocities for all science objects measured in the literature, including those previously designated as contaminants.

### 3.2. Published Velocities

In addition to our own velocity measurements, we assembled an additional sample of velocities using the results from previous work in the literature. First, we include 46 velocity measurements obtained by Bridges et al. (1997) using the William Herschel Telescope and the Low Dispersion Survey Spectrograph. An additional 16 objects were obtained from Keck Low Resolution Imaging Spectrometer observations of Larsen et al. (2002). This excludes the object identified as H2-27 in the Larsen et al. (2002) list since the authors declare the velocity measurement to be unreliable. B07 determined velocities for 170 objects with the 2dF spectrograph at the AAT and with the Hydra spectrograph on WIYN. Finally, Alves-Brito et al. (2011) measured 259 velocities for GC candidates using Keck and the Deep Imaging Multi-Object Spectrograph. We cross-matched the objects in each of these lists and found repeated velocity measurements for a total of 38 objects, including two objects that were repeated more than once. As with the repeats in our own observations, we adopted the uncertainty-weighted mean of all available velocity measurements as the velocity for these objects. The resulting literature sample consists of 450 unique objects.

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### 3.3. Removing Duplicates

There are 23 objects in our observed sample that also match objects in the literature. These repeated velocity determinations provide a way to independently check our cross-correlations, and give us an estimate of the systematic errors associated with our velocity measurements. Figure 2 shows the difference between our velocity measurements and the literature values plotted against V magnitude for each of the 23 objects. Overall we find good agreement between the repeated measurements. The mean velocity difference for the 23 repeated objects is \( -23.1 \text{ km s}^{-1} \) with a dispersion in the values of \( 174.9 \text{ km s}^{-1} \), which is consistent with zero, given their mean velocity uncertainty of \( \approx 26 \text{ km s}^{-1} \). The increased spread seen in the data points at fainter magnitudes is expected since the spectra for...
the Alves-Brito et al. (2011) velocity has a lower uncertainty, we adopt our own velocity for this target. If we exclude this outlier from the calculation of the mean difference, we find a value of 5.1 km s\(^{-1}\) with a dispersion of 114.0 km s\(^{-1}\) (for all magnitudes), which shows even stronger agreement between our measurements and the literature. Once again, in the subsequent analysis we adopt the weighted average of the velocities for the repeated objects. After removing these duplicate measurements, our final data set contains velocities for a total of 579 unique GC candidates. Table 1 lists complete data for all of the objects for which we were able to measure a radial velocity. Whenever possible, the objects are identified using the sequence numbers assigned by RZ04 (given as RZ# in the table). In those cases where an object did not have an RZ04 identifier, we adopted the identifier number from the literature in the following order of preference: Spitler et al. (2006; S#), Larsen et al. (2002; C-# or H-#), and Bridges et al. (1997; 1-# or 2-#).

### 3.4. Contaminant Rejection

The photometric studies of GC candidates that we used to select targets for our spectroscopic follow-up utilized broadband magnitudes and colors to select GCs around the Sombrero galaxy, e.g., RZ04. As a result, there is some contamination inherent in the data set which is primarily due to foreground stars and compact background galaxies that exhibit magnitudes and colors similar to GCs. Figure 3 shows the velocity histogram for all objects in our sample. The cluster of velocities near the systemic velocity of M104 at 1091 km s\(^{-1}\) (Tully et al. 2008) are GCs, while the objects at lower velocities are Galactic stars. Previous studies were able to take advantage of a large gap in the velocity histogram near ~500 km s\(^{-1}\) to separate GCs from the contaminants (Bridges et al. 2007). In our much larger sample, this break is less apparent; however, we can still apply a similar outlier rejection method detailed in Schuberth et al. (2010) and Schuberth (2003) for the remaining objects.

Figure 2. Difference between our velocity measurements and values from previous studies plotted as a function of V magnitude. Open symbols show results compared to values from Bridges et al. (2007), and filled symbols are a comparison to values from Alves-Brito et al. (2011). The various symbol shapes indicate from which of our data sets each velocity was measured: squares indicate velocities from the Hydra data, triangles indicate velocities from the red AAOmega data, and circles represent velocities from the blue AAOmega data. We find good agreement between our values and the literature, overall, with an expected increase in scatter toward fainter magnitudes.

Table 1
Properties of the Target Objects with MeasuredVelocities

| ID     | R.A.           | Decl.         | V   | B − V | R − V | X   | Y   | R   | θ   | \(v_g\) |
|--------|----------------|---------------|-----|-------|-------|-----|-----|-----|-----|---------|
| RZ1003 | 12:40:41.12    | −11:30:49.99  | 19.09| 0.92  | 1.53  | 10.21| 6.55| 12.13| 32.67| 63.0 ± 20.0 |
| RZ1005 | 12:40:41.07    | −11:54:11.87  | 19.65| 0.79  | 1.32  | 10.19| −16.81| 19.66| 301.21| 63.0 ± 28.0 |
| RZ102  | 12:41:13.25    | −11:48:14.43  | 21.62| 0.56  | 0.98  | 18.07| −10.86| 21.08| 328.99| 296.3 ± 11.1 |
| RZ1030 | 12:40:40.23    | −11:19:23.77  | 20.29| 0.63  | 1.06  | 10.00| 17.99| 20.58| 60.92| 178.0 ± 47.0 |
| RZ1039 | 12:40:39.93    | −11:25:59.49  | 20.49| 0.71  | 1.18  | 9.92 | 11.39| 15.11| 48.94| 278.7 ± 6.8 |
| RZ1045 | 12:40:39.82    | −11:36:55.14  | 19.67| 0.76  | 1.24  | 9.89 | 0.46| 9.90 | 2.69| 1025.5 ± 26.9 |
| RZ1059 | 12:40:39.33    | −11:41:16.8   | 19.29| 1.07  | 1.76  | 9.77 | −3.90| 10.52| 338.25| 62.0 ± 30.0 |
| RZ1060 | 12:40:39.31    | −11:52:08.0   | 19.83| 1.07  | 1.77  | 9.76 | −14.75| 17.69| 303.48| −15.0 ± 36.0 |
| RZ1061 | 12:40:39.30    | −11:45:10.86  | 20.70| 0.65  | 1.09  | 9.76 | −7.80| 12.49| 321.37| 259.3 ± 10.9 |
| RZ1070 | 12:40:39.00    | −11:55:01.95  | 19.68| 0.73  | 1.21  | 9.68 | −17.65| 20.13| 298.74| 1005.9 ± 31.6 |

Notes. Photometric data provided in this table is a compilation of data from the literature, and is not available for every source.

(This table is available in its entirety in machine-readable and Virtual Observatory (VO) forms in the online journal. A portion is shown here for guidance regarding its form and content.)
Figure 3. Velocity histogram of all 577 objects in our combined sample with velocities less than 2500 km s$^{-1}$ (there are two objects in our final sample with velocities greater than 2500 km s$^{-1}$ that are not shown). Objects with velocities within the large peak centered over 1091 km s$^{-1}$ are members of the M104 GC system, and objects with velocities in the second large peak at 150 km s$^{-1}$ are Galactic foreground stars. The tails of the two peaks overlap near ~500 km s$^{-1}$. The shaded region shows the final GC sample selected using the TME technique of Schuberth et al. (2010, 2012).

Figure 4. Results of the contaminant rejection algorithm. The filled points are the objects rejected as contaminants, and open points represent the objects in our final sample of confirmed GCs. The dashed line indicates the boundary established by the Schuberth et al. (2010, 2012) rejection routine used to select our final GC sample. Finally, the solid black line indicates the mean velocity of 1099.5 ± 204.2 km s$^{-1}$ for the GCs computed by fitting a double Gaussian to the velocity data. The dotted lines demonstrate the result of using a flat velocity cutoff at 3$\sigma$ above and below this mean value to separate GCs from contaminants. Two rejected contaminants have velocities greater than 3000 km s$^{-1}$, and are indicated using arrows.

Figure 5. Difference between the $m_N$ and $m_{N-1}$ values computed from Equation (2) plotted against $N$ for each step of the Schuberth et al. (2010, 2012) rejection algorithm. The vertical dotted line indicates our chosen rejection limit, which is the point at which the differences begin to converge. Using this cut we reject a total of 219 contaminating objects.

Schuberth et al. (2012), which utilizes the tracer mass estimator (TME) derived in Evans et al. (2003). One advantage of this method is that the selection is based on the projected distance of each object relative to the center of the galaxy, in addition to the radial velocity of each object. To use this method, we first compute the value $m_N$, which is defined as

$$m_N = \frac{1}{N} \sum_{i=1}^{N} v_i^2 R_i,$$

where $m_N$ is a proxy for the TME, $N$ is the number of GC candidates, $v_i$ is the velocity of the candidate relative to the galaxy (1091 km s$^{-1}$; Tully et al. 2008), and $R_i$ is its projected radial distance from the galaxy center. For computing the value of $R_i$, we adopt a value for the galaxy center from NED at an R.A. of 12h39m59s43 and a declination of $-11^\circ37'23''0$. Next, the object with the largest value of $v^2 R$ is removed, and Equation (2) is recomputed using the remaining sample. Figure 5 shows the difference between the $m_N$ and $m_{N-1}$ plotted against $N$ at each step. Objects that belong to the M104 system should trace the same overall mass, and removal of the contaminating objects will cause the values of $m_N$ to converge. Consequently, the cutoff between contaminants and GCs in this figure will appear as a flattening of the curve. We selected the last large jump in the value of $m_N - m_{N-1}$ at 218 as our cutoff value. Our chosen cutoff between true GCs and contaminants is shown by the vertical dashed line in Figure 5. This selection represents a tradeoff between removing the contaminants and maximizing the GCs in our final sample. The next largest jumps in Figure 5 above and below our chosen cutoff are at 214 and 227, which suggests that the uncertainty in the number of GCs in our final sample is of the order of 10 GCs.

Figure 4 shows the division of contaminants from GCs resulting from this method on a plot of relative velocity versus projected galactocentric distance. The boundary computed with
the TME method is shown by the dashed curve. Rejected objects are indicated by filled circles, and confirmed GCs are indicated by open circles. For illustrative purposes, the flat velocity cut discussed above is shown using dotted lines. Using our chosen cutoff from the TME method, we eliminate a total of 219 contaminating objects from our sample. Of the rejected objects, 205 are low velocity objects that are most likely foreground stars associated with the Galaxy. The remaining 14 high velocity objects are most likely a combination of background galaxies and spurious measurements of low S/N objects. The 360 confirmed GCs in our list extend to a distance of 24′ (∼14.1 R_e or ∼64.9 kpc) from the center of the galaxy and span a range of V magnitude from 18.79 to 23.72 and a B − V color range from 0.42 to 1.20. We use this sample of GCs for the remainder of our analysis.

4. RESULTS

4.1. Distribution

Figure 6 shows the spatial distribution of our confirmed GCs around the center of the Sombrero galaxy, which is located at the origin of the plot. The different symbols indicate the source of the velocity measurement for each object. GCs with final velocities that were averaged from multiple sources are denoted by upside-down triangles. Notably, our new velocity measurements obtained with AAOmega help to significantly improve the coverage of the data at radii greater than ∼10′ (6 R_e or ∼27 kpc). B07, who performed the most recent kinematic study of the M104 GC system, measured velocities for 16 GCs beyond 10′. Our new data set includes an additional 19 GCs outside of 10′, which more than doubles the number of GC velocities beyond this radius. The shading of the symbols in Figure 6 indicates whether the GC belongs to the red or blue subpopulation, where the division between red and blue is designated as a B − R color of 1.3 (Rhode & Zepf 2004). We identify 210 objects as blue GCs and 149 objects as red GCs. Note that there is one object in our final GC sample, GC #1–33, that does not have an available B − R color, and so although it is included in the analysis of the full GC sample, it is excluded from our analysis of the subpopulations. GC #1–33 was classified as a star by Bridges et al. (1997) and was not observed photometrically by RZ04.

As a result, its photometry was unreported in the literature. We measure its velocity as 448 ± 141 km s^{-1}, which is low for M104 GCs; however, because of its low projected distance from the center of the galaxy, it survives our contaminant rejection routine, and we therefore classify it as a GC in our sample. An initial visual inspection of Figure 6 appears to indicate that there is a difference in the distribution of red and blue GCs in our sample. Indeed, beyond a radius of ∼10′ (6 R_e or ∼27 kpc), there is a greater proportion of blue GCs to red GCs with 27 blue GCs and 8 red GCs. RZ04 observed a small radial color gradient in their 90% complete sample of M104 GCs with a slope of ∆(B − R)/∆(r) = −0.003 ± 0.001, which would be consistent with a changing ratio of blue to red objects at large galactocentric radii. However, a two-sample Kolmogorov–Smirnov (K-S) test on the full sample gives a p-value of 0.03 which indicates that the difference between the red and blue distributions is not significant, and we cannot rule out the possibility that the red and blue GCs are from the same parent distribution. Furthermore, a K-S test including only those GCs outside 10′ results in a p-value of 0.53, which further suggests that the two subpopulations within our sample do not have different radial distributions.

4.2. Rotation

We examined the radial velocities of our GCs as a function of projected distance along the major axis of M104. The resulting plot is shown in Figure 7. The solid line shows the result of performing smoothing to the data with a sliding average using a Gaussian weighting with standard deviation of 3′ (∼2 R_e or ∼8 kpc). For comparison, the dash-dotted line shows the result of this treatment determined by B07. Like B07, we find no evidence for obvious rotation in the GC system. This is in sharp contrast to the strong rotation seen in the stellar rotation curve of the galaxy (van der Marel et al. 1994) and in the H\alpha emission and H\i gas rotation curve from Kormendy & Westpfahl (1989), shown by the dashed and dotted lines, respectively.

We performed a closer examination of rotation by looking at radial velocity as a function of position angle for the system, as shown in Figure 8. We fit the following equation to the data using a non-linear least squares routine, based on Numerical Recipes MRQMIN (Press et al. 1992).

\[ v(\theta) = v_{\text{rot}} \sin(\theta - \theta_0) + v_0. \]  

In Equation (3), θ is the position angle of the GCs, v_0 is the systemic velocity of M104 for which we adopt the robust, biweight mean velocity of the full GC sample of 1097.3 km s^{-1}, v_{\text{rot}} is the rotation velocity of the GC system, and θ_0 is the position angle of the rotation. The best fitting curve to the full data set is shown as a solid black line in the top panel of Figure 8. We determined the significance of our fit by performing a Monte Carlo simulation on a series of simulated GC systems generated by creating random pairs of the observed θ and v values. We then calculated the significance value as the percentage of the Monte Carlo simulations that produced a better fit than the observed data.

Figure 6. Spatial distribution of the spectroscopically confirmed GC sample. The center of the Sombrero galaxy is located at the center of the plot at [0, 0]. The different shaped symbols indicate the source of the velocity measurement for each cluster. GCs with final velocities that were averaged from multiple sources are denoted by upside-down triangles. Our new data from AAOmega and Hydra, indicated by diamond symbols, doubles the number of GC velocities beyond 10′ (6 R_e or ∼27 kpc), and indicates a significant improvement in radial coverage over previous studies. Filled and open symbols indicate whether a particular cluster belongs to the red or blue subpopulation, respectively.

Figure 7. The best fitting curve to the data shows that there is no significant rotation in the GC system.
et al. (1994) and Kormendy & Westpfahl (1989), respectively. In contrast to the results obtained by B07 using the same method for the GCs in their data set, we see no significant rotation in the GC system. For the systemic velocity of M104, we adopt the robust, biweight mean velocity of the full GC sample of 1097.3 km s\(^{-1}\). The solid black lines in each panel show the best fit curve to Equation (3) determined by a nonlinear least-squares fit to each of the data sets. Figure 9 shows the difference between the GC velocities and the systemic velocity of M104 plotted against the major axis distance. In this case we have folded the data east to west in order to examine the velocity dispersion as a function of radius. The GCs in our sample extend to a radius of 24' (∼14.1\(R_e\)) or ∼64.9 kpc) from the center of the host galaxy. We therefore divided the clusters into three radial bins at 8' (∼4.7\(R_e\) or ∼21.6 kpc), and 16' (∼9.4\(R_e\) or ∼43.3 kpc), and computed the mean velocity and average dispersion for each bin. We find that inside 8' the velocity dispersion is 222.1 ± 12.8 km s\(^{-1}\), with a mean velocity of 1124.0 km s\(^{-1}\). In the outer two bins, the velocity dispersion decreases from 152.2 ± 21.3 km s\(^{-1}\) between 8' and 16', to 73.7 ± 27.8 km s\(^{-1}\) outside 16'. Similarly, the mean velocity also decreases from 1072.1 km s\(^{-1}\) to 1026.3 km s\(^{-1}\) in the middle and outer bins, respectively. We then computed the velocity dispersion profile by smoothing the discrete velocity profile with a Gaussian of gradually increasing width from \(\sigma = 2'\) (∼1\(R_e\) or ∼5 kpc) to \(\sigma = 4'\) (∼2\(R_e\) or ∼11 kpc) with increasing radius. Figure 10 shows the resulting smoothed profile. The heavy solid line is the computed profile, and the thin solid lines show the 1\(\sigma\) uncertainties. The 1\(\sigma\) dispersion profiles computed by B07 are shown as solid gray lines. In order to compute the uncertainties in the velocity dispersion profile, we used a jackknife technique to generate 1000 new velocity dispersion profiles using 1000 subsamples of GCs each.

4.3. Determination of the Mass Profile

4.3.1. Velocity Dispersion Profile

Figure 9 shows the difference between the GC velocities and the systemic velocity of M104 plotted against the major axis distance. In this case we have folded the data east to west in order to examine the velocity dispersion as a function of radius. The GCs in our sample extend to a radius of 24' (∼14.1\(R_e\) or ∼64.9 kpc) from the center of the host galaxy. We therefore divided the clusters into three radial bins at 8' (∼4.7\(R_e\) or ∼21.6 kpc), and 16' (∼9.4\(R_e\) or ∼43.3 kpc), and computed the mean velocity and average dispersion for each bin. We find that inside 8' the velocity dispersion is 222.1 ± 12.8 km s\(^{-1}\), with a mean velocity of 1124.0 km s\(^{-1}\). In the outer two bins, the velocity dispersion decreases from 152.2 ± 21.3 km s\(^{-1}\) between 8' and 16', to 73.7 ± 27.8 km s\(^{-1}\) outside 16'. Similarly, the mean velocity also decreases from 1072.1 km s\(^{-1}\) to 1026.3 km s\(^{-1}\) in the middle and outer bins, respectively. We then computed the velocity dispersion profile by smoothing the discrete velocity profile with a Gaussian of gradually increasing width from \(\sigma = 2'\) (∼1\(R_e\) or ∼5 kpc) to \(\sigma = 4'\) (∼2\(R_e\) or ∼11 kpc) with increasing radius. Figure 10 shows the resulting smoothed profile. The heavy solid line is the computed profile, and the thin solid lines show the 1\(\sigma\) uncertainties. The 1\(\sigma\) dispersion profiles computed by B07 are shown as solid gray lines. In order to compute the uncertainties in the velocity dispersion profile, we used a jackknife technique to generate 1000 new velocity dispersion profiles using 1000 subsamples of GCs each.

### Table 2

| GC Sample | N  | \(v_{\text{tot}}\) | \(\theta_0\) | Significance |
|-----------|----|-------------------|--------------|--------------|
|           |    | (km s\(^{-1}\)) | (deg)        | (%)          |
| All       | 360| 30.4 ± 22.2       | 54.7 ± 25.0  | 83.9         |
| 0–5'      | 233| 41.7 ± 32.8       | 43.2 ± 26.3  | 82.9         |
| 5–10'     | 92 | 18.6 ± 33.1       | 359.9 ± 91.3 | 24.4         |
| 10–15'    | 25 | 100.9 ± 41.8      | 133.8 ± 19.4 | 91.4         |
| 15–20'    | 8  | 55.8 ± 49.2       | 198.9 ± 58.5 | 2.5          |
| Red GCs   | 149| 43.7 ± 23.9       | 342.7 ± 29.0 | 82.3         |
| Blue GCs  | 210| 47.0 ± 22.1       | 80.9 ± 25.0  | 91.4         |
containing 270 GCs or roughly 75% of the full sample. These subsample profiles were then used to compute the 1σ range. The resulting velocity dispersion profile shows a steady decline from the center of the galaxy all the way out to the end of our data set at 25′ (∼15R_e or ∼68 kpc). Inside 10′ (∼6R_e or ∼27 kpc), our velocity dispersion profile shows good agreement with the B07 profile. However, our profile does not show the flattening seen by B07 for radii 10′ (≥6R_e or ≥27 kpc). This is likely due to the increased number of GCs in our sample outside of 10′ (∼6R_e or ∼27 kpc), which improves the sampling of the underlying dispersion profile. We repeat the smoothing process for the GC sample selected using the flat velocity cut (illustrated by the dashed black lines in Figure 10). Compared to the result for the final GC sample, this velocity dispersion profile exhibits a shape that is more flattened, although the overall trend of the velocity dispersion still decreases with radius.

To investigate the sensitivity of the velocity dispersion profile to the location of the cut used in the TME method (see Section 3.4), we created additional velocity dispersion profiles for GC samples created using rejection indices of 214 and 227. Inside of 10′ there is good agreement (within 1σ) between the resulting profiles for these samples and our chosen sample. Beyond this distance, the profiles begin to separate slightly. The profile generated from the 227 cutoff decreases more rapidly with radius and has a 1σ dispersion range of 73 to 93 km s⁻¹ at 20′. Like the profile produced by the flat cut, the 214 cutoff profile has a shallower slope and has a 1σ dispersion range of 110–159 km s⁻¹ at 20′. It should be noted that both of these profiles overlap with the velocity dispersion profile of our final GC sample shown in Figure 9, and they have a similar overall shape.

We also examined the velocity dispersion profiles of the red and blue GC subpopulations. This result is discussed in Section 5.1.

We modeled the mass profile using a spherical, isotropic Jeans mass model. We used the smoothed velocity dispersion profiles computed above combined with the surface density profile of GCs from RZ04 as input to the model. Figure 11 shows the 1σ limits of our computed mass profile as solid black lines. Similar to the smoothed velocity dispersion, the mass uncertainties were computed using 1000 jackknife samples each containing 270 GCs. To ensure that the mass profile determined from the jackknife sample was self consistent, the velocity dispersion was first calculated from the sample and this dispersion was used to calculate the sample’s mass profile. The mass profile begins at 4.0 × 10¹⁰ M☉ at our innermost bin and increases to 4.9 × 10¹¹ M☉ at 5′ (∼3R_e or ∼14 kpc). Beyond 5′, the mass increases more gradually, with the total mass reaching 1.3 × 10¹² M☉ at 15′ (∼9R_e or ∼41 kpc). We do not see a flattening of the mass profile, indicating that the data do not extend to the edge of the DM halo of the galaxy. We also show the 1σ limits on the mass profile computed for the flat-cut GC sample (dashed black lines). Within the errors, the mass profiles derived from the two GC samples are consistent. As an additional side note, the mass profiles produced from the GC samples derived using the TME method with cutoffs at 214 and 227 (see Section 4.3.1) are also in excellent agreement with our final mass profile to within the errors, which suggests that our results are not strongly sensitive to the exact rejection index chosen.

Also shown in Figure 11 is the 1σ mass profile result from the B07 paper as a set of solid gray lines. The histogram at the bottom of the figure shows the number of GCs at each radius.

Figure 9. Relative GC velocity as a function of projected radius. GCs are indicated by the open circles. The horizontal lines show the locations of the mean velocity for GCs in three bins divided at 8′ (∼4.7R_e or ∼21.6 kpc) and 16′ (∼9.4R_e or ∼43.3 kpc). The vertical lines show the width of the average velocity dispersion for the GCs in each bin.

Figure 10. Velocity dispersion profile, shown by the heavy solid black line, that is the result of smoothing the data in Figure 9 with a Gaussian with a gradually increasing width from 2′ (∼1R_e or ∼5 kpc) to 4′ (∼2R_e or ∼11 kpc). The 1σ limits for this profile are shown by the thin solid black lines. The dashed black lines denote the velocity dispersion profile computed using the GC sample selected using the flat velocity cut. The velocity dispersion of our final GC sample steadily decreases with radius, and does not show any signs of the flattening seen in the 1σ limits of the velocity dispersion profile of B07, represented by the solid gray lines. By comparison, the velocity dispersion of the flat-cut GC sample exhibits a more flattened shape.

4.3.2. Mass Profile
radius binned in 1′ (\(\sim 0.5 R_e\) or \(\sim 3\) kpc) bins, with the shaded region showing the B07 sample for comparison. Of significant note is that our new mass profile extends nearly \(\sim 5′ (\sim 3R_e\) or \(\sim 14\) kpc) farther from the galaxy center in radius than the B07 profile. Our confidence in the mass profile beyond \(\sim 15′ (\sim 9R_e\) or \(\sim 41\) kpc) is low due to the low number of GC velocity measurements beyond this distance. The effect can also be seen in the increased uncertainty in the profile. More measurements are needed to solidify the shape of the profile for larger radii. Overall we find good agreement between our profile and that of B07 inside 5′. The slope of the B07 profile outside of this radius is slightly steeper than our mass profile. At 5′, both profiles have a mass of approximately \(5 \times 10^{11} M_{\odot}\). However at 8′ (\(\sim 5R_e\) or \(\sim 22\) kpc) the B07 profile is \(\sim 12\%\) higher than our profile at the same radius. The exact origin of the discrepancy is unclear; however it is likely related to the flattening of the B07 velocity dispersion profile at these radii.

4.3.3. V-band Mass-to-light Profile

We next determined the \(M/L_V\) profile of the galaxy by dividing our mass profile by the luminosity profile for M104 determined by Kormendy & Westpfahl (1989), which includes three components: a de Vaucouleurs profile which is the primary component, a disk component, and a nonisothermal bulge. Each of these components is based on fits to their decomposed stellar light profiles out to roughly 5′. The top panel of Figure 12 shows the \(M/L_V\) profile we computed with uncertainties shown as solid black lines. The \(M/L_V\) in the innermost bin is \(\sim 4.5\), and the profile rises linearly to a value of \(\sim 14\) at 8′ (\(\sim 5R_e\) or \(\sim 22\) kpc). There is a slight flattening in the profile around 10′ (\(\sim 6R_e\) or \(\sim 27\) kpc) before it continues with a roughly linear increase to an \(M/L_V\) of \(\sim 19\) at 15′ (\(\sim 9R_e\) or \(\sim 41\) kpc). It is not clear whether the flattening in the \(M/L_V\) profile is real because the \(1\sigma\) error profiles in the mass widen at this same radius. It should be noted that the luminosity profile at these radii is an extrapolation of the Kormendy & Westpfahl (1989) components. The \(M/L_V\) profile for the flat-cut GC sample, illustrated by the dashed lines, is consistent within the errors with the final GC sample.

Once again we have overplotted the result from B07 in gray. The discrepancy between our \(M/L_V\) profile and the B07 profile beyond 5′ is a direct consequence of the turnover and higher slope of the B07 mass profile at around 7′ (\(\sim 4R_e\) or \(\sim 19\) kpc).

5. DISCUSSION

5.1. Comparison of the Red and Blue Subpopulations to Other Galaxies

Galaxies with well-studied GC kinematics are few, and are most commonly giant cluster ellipticals. In spite of this limited sample, galaxy to galaxy comparisons of GC kinematics have begun to provide interesting results. Hwang et al. (2008) compared the kinematic properties of GCs in six well-studied giant elliptical galaxies (M60, M87, M49, NGC 1399, NGC 5128, and NGC 4636), and most recently Pota et al. (2013) examined the kinematics of GCs in 12 early-type galaxies (9 ellipticals and...
higher than that of the red GCs by et al. (2005), we find that the central velocity dispersion of the blue GCs is higher than that of the red GCs by \( \sim 60 \) km s\(^{-1} \).

3 S0s as part of the SAGES Legacy Unifying Globulars and Galaxies Survey (SLUGGS). Both of these studies found that, for their galaxies, the rotational properties of the GC systems and the GC system subpopulations were highly varied and are likely to depend on the merger history of the individual galaxy. Numerical simulations of dissipationless mergers by Bekki et al. (2005) suggest that outside a radius of \( \sim 20 \) kpc (\( \sim 4.3R_e \) or \( \sim 7.4 \) at the distance of M104) both GC subpopulations should exhibit rotation on the order of 30–40 km s\(^{-1} \). However, as discussed in Section 4, we see no significant rotation in our GC sample for M104 as a whole or in the individual subpopulations. This perhaps suggests a more complex merger history for this galaxy.

In addition to rotation, mergers can also impart differences in the overall velocity dispersion profile of the GC system. Another prediction of the Bekki et al. (2005) simulation is that the velocity dispersion profiles of the GC systems of galaxies formed by major mergers decrease as a function of radius. In multiple-merger scenarios, they find that their modeled velocity dispersion profiles can become more flattened. As discussed in earlier sections of this paper, the shape of the velocity dispersion profile determined from observational data is sensitive to the selection of member GCs, therefore, it is difficult to determine whether the decreasing shape of the velocity dispersion profile shown in Figure 10 is intrinsic or a result of the GC selection process.

Although the shape of the velocity dispersion profile is uncertain, we can still compare the properties of the velocity dispersion for the red and blue subpopulations. Pota et al. (2013) found observational evidence for a difference in the central velocity dispersions between the subpopulations in the GC systems of their SLUGGS galaxies. They found that, in general, the velocity dispersion profiles for the blue GC subpopulations were higher overall than the velocity dispersion profiles of the red GCs. Figure 13 shows the smoothed velocity dispersion profiles for the red and blue GC subpopulations in our M104 sample. Consistent with the results of Pota et al. (2013) and the velocity dispersions between the subpopulations in the GC systems of galaxies formed by major mergers decrease as a function of radius. In multiple-merger scenarios, they find that their modeled velocity dispersion profiles can become more flattened. As discussed in earlier sections of this paper, the shape of the velocity dispersion profile determined from observational data is sensitive to the selection of member GCs, therefore, it is difficult to determine whether the decreasing shape of the velocity dispersion profile shown in Figure 10 is intrinsic or a result of the GC selection process.

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\[ \text{Figure 13. Comparison of the velocity dispersion profiles of the red (solid lines) and blue (dashed lines) GC subpopulations. The lines indicate the 1\sigma error profiles for each subpopulation. Similar to Pota et al. (2013) and Bekki et al. (2005), we find that the central velocity dispersion of the blue GCs is higher than that of the red GCs by } \sim 60 \text{ km s}^{-1}. \]

\[ \text{Figure 14. Comparison of the inner } 8' \text{ of the GC mass profile to the mass estimates from other kinematic tracers. The solid black and solid gray lines are the 1\sigma error profiles of our GC mass profile, with the gray lines showing the results of the GC sample selected with the flat velocity cut. The dashed line is the mass profile from the H}\alpha study of Kormendy & Westpfahl (1989). The circles represent the mass estimates from X-ray observations from the work of Forman et al. (1985) and Li et al. (2007). There is good overall agreement between the GC mass profile and the Kormendy & Westpfahl (1989) mass profile. The X-ray mass estimate of Li et al. (2007) is in excellent agreement with the GCs. Forman et al. (1985) do not report errors on their X-ray mass estimate, but if we assume a modest uncertainty of 10%, their result falls within the 3\sigma range of the GC mass profile.} \]

5.2. Comparison to Other Mass Tracers

The most easily observed kinematic tracers in galaxies are the stars and the gas. Although these tracers are limited in their radial extent, it is useful to compare the results from these types of studies with the results from the GC system since they should trace the same underlying mass distribution. Kormendy & Westpfahl (1989) measured the rotation curve of the stars and gas in M104 using optical spectra from the Canada–France–Hawaii Telescope and used their results to calculate the mass profile of the galaxy out to roughly 3.5. Bridges et al. (2007) found that the Kormendy & Westpfahl (1989) profile was in excellent agreement with their mass profile derived from the GCs (see Bridges et al. 2007, Figure 7 and associated discussion). We also find good agreement between the Kormendy & Westpfahl (1989) mass profile and our updated GC mass profile. Figure 14 shows the 1\sigma boundaries of our mass profile out to 8' (\( \sim 4.7R_e \) or \( \sim 21.6 \) kpc) shown as solid black lines. The 1\sigma mass profile boundaries for the GCs identified using a flat velocity cut are also shown with solid gray lines. Overplotted on this figure is the mass profile of Kormendy & Westpfahl (1989), illustrated by the dashed line. Both of our...
mass profiles are consistent with the Kormendy & Westpfahl (1989) profile, although inward of ∼2′ the mass profile derived from the flat GC sample is in slightly better agreement.

X-ray emission from hot coronal gas has been predicted by galaxy formation models (White & Rees 1978; White & Frenk 1991), and has been observed in many giant elliptical and S0 galaxies (Forman et al. 1985). It has also been found in a few spiral galaxies (Bogdan et al. 2013; Benson et al. 2000). M104 has been shown to possess extended, diffuse X-ray emitting hot gas out to ∼20 kpc (∼4 Re or ∼7.4) from the galaxy center (Li et al. 2007, 2011). These observations can provide additional estimates of the host galaxy mass. Using measurements of the diffuse X-ray emission of M104 from the Einstein Observatory, Forman et al. (1985) estimated a total mass for M104 of 9.5 × 1011 M⊙ at a radius of ∼6.6 (∼3.9 Re or ∼17.9 kpc). Li et al. (2007) observed diffuse X-ray emission in the Sombrero using Chandra and XMM-Newton. They measured a uniform plasma temperature of 0.6–0.7 keV extending to a radius of 20 kpc (∼4 Re or ∼7.4) from the galaxy center. Assuming the gas is in virial equilibrium, we calculate a total mass enclosed inside this radius between 6.7 × 1011 and 7.8 × 1011 M⊙. The masses determined from the X-ray results of Forman et al. (1985) and Li et al. (2007) are shown in comparison to our GC mass profile in Figure 14 as open and filled circles, respectively. We plot the average value for the mass range computed from the Li et al. (2007) data, with the full range indicated by the error bars. The mass estimate from the Li et al. (2007) X-ray results are in excellent agreement with our GC mass profile; however, the Forman et al. (1985) mass estimate falls above our mass profile by roughly 3 × 1011 M⊙ or approximately 5σ. It is difficult to judge the consistency between the Forman et al. (1985) and other mass determinations due to the absence of a well-determined gas temperature. However, we note that a modest uncertainty on the Forman et al. (1985) result of 10% would place our mass profile within 3σ of this result.

6. SUMMARY

We have measured radial velocities for 51 previously unmeasured GCs in M104. Combined with data from the literature, we have assembled and analyzed 360 GC velocities in this galaxy’s system. This is the largest sample of GC radial velocity measurements ever compiled for a kinematic analysis of M104. The sample also provides double the available data beyond ∼10′ (∼6Re or ∼27 kpc), greatly improving the radial coverage over previous work. As in previous studies, we find little or no evidence for rotation in the GC system as a whole, and we also do not find evidence of a significant level of rotation within the red or blue subpopulations. We examined the velocity dispersion profile and found that the velocity dispersion decreases steadily to the edge of our available data. We used an isotropic Jeans model to find the mass profile and M/LV profile of the GC system which extend ∼5′ (∼3Re or ∼14 kpc) farther from the galaxy center than previous studies. Finally, our mass profile agrees well with masses estimated from diffuse X-ray data in the literature.

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