Digital light 3D printing of customized bioresorbable airway stents with elastomeric properties

Paunović, Nevena; Bao, Yinyin; Coulter, Fergal Brian; Masania, K.; Geks, Anna Karoline; Klein, Karina; Rafsanjani, Ahmad; Cadalbert, Jasmin; Franzen, Daniel; More Authors

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Central airway obstruction (CAO) is a stenosis of the trachea or mainstem bronchi that causes impaired air flow and has immense impact on morbidity and mortality (1, 2). Immediate relief in patients suffering from CAO can be provided after bronchoscopic insertion of airway stents, which are life-saving medical devices designed to restore the anatomical shape of the airways (3). The most widely used airway stents are made from flexible and elastic biocompatible medical-grade silicone. However, the commercial silicone stents are simple tubes associated with a high risk of migration due to geometrical mismatching with the complex tracheobronchial anatomy of the individual patient (1, 3). This is especially noticeable in pediatric patients who need additional interventions for stent removal or replacement due to the airway growth, which may cause further tissue damage (1, 4). Therefore, there is an unmet medical need for affordable patient-specific bioresorbable airway stents that can be manufactured in a reasonable time frame (1, 3). Nonetheless, conventional manufacturing technologies of airway stents make personalization expensive and time-consuming (5).

In combination with imaging techniques, three-dimensional (3D) printing technologies (6–13) provide enormous opportunities for rapid and affordable production of personalized medical devices (14–17). Nonetheless, their use in medicine is restricted by the lack of biocompatible and biodegradable materials that are suitable for the 3D printing of medical devices with silicone-like mechanical properties. So far, 3D printed bioresorbable airway stents have been made from thermoplastic polymers by fused deposition modeling and are prone to stress relaxation or even permanent deformation when being constrained before insertion (5, 18). These challenges could be overcome by digital light processing (DLP) of highly stretchable elastomers. While DLP offers the benefit of high resolution and surface quality (6, 19, 20) compared to other 3D printing techniques, it also heavily depends on the resin viscosity (21, 22). Therefore, only biodegradable oligomers or polymers with short chain length have been used to prepare DLP biomedical inks, and these produce rigid and brittle 3D printed objects (23–25). Hence, the development of inks for DLP 3D printing of biodegradable elastomers with mechanical properties comparable to silicone stents would be a big step forward to clinical application of personalized bioresorbable airway stents.

Here, we report dual-polymer DLP biomedical inks based on functionalized poly(D,L-lactide-co-e-caprolactone)s [poly(DLLA-co-CL)s], which are suitable for 3D printing of bioresorbable elastomers. The most promising material was identified on the basis of successive testing of mechanical performance, cytocompatibility, and degradability at physiological pH and further used to 3D print customized bioresorbable airway stents with elastomeric properties comparable to those of commercial state-of-the-art silicone stents (Fig. 1). This work proposes a blueprint for the design, manufacturing, characterization, and assessment of the next generation of airway stents (Fig. 1) that could, in the future, meet patients’ needs in terms of both geometry and bioresorbability.
than homopolymers of the same molecular weight (MW) (24, 26, 27). As branched polymers generally show lower viscosity (28) and higher cross-linking density together with better mechanical properties (29) than the linear ones, a series of four-arm poly(DLLA-co-CL) s was synthesized by Sn(Oct)$_2$-catalyzed ring opening polymerization at 140°C, with a molar feed ratio DLLA/CL of 3/7 and MW ranging from 1200 to 15,000 g mol$^{-1}$. These copolymers were further functionalized with methacrylates (degree of methacrylation ca. 80%) to make them suitable for photopolymerization (fig. S1). All photopolymers were amorphous (fig. S2) and liquid at room temperature. However, the viscosity of the copolymers with longer chain length (MW > 5000 g mol$^{-1}$) was still above the range required for DLP printing (fig. S3A) (21). To tackle this issue, we designed a customized temperature-controlled printing platform that allows for a reduction in the polymer viscosity by heating the resin tray (fig. S4). Printing at temperatures in the range of 70 to 90°C effectively decreased the viscosity of the photopolymers without causing thermocuring under the tested conditions (fig. S3). This approach could be used for high-resolution printing of even high-MW photopolymers if up to 8 (weight %) wt % of the reactive diluent N-vinyl-2-pyrrolidone (NVP) was added to the resin. Furthermore, the composition of the printing resin was optimized to achieve minimal amounts of additives, such as photoinitiator [phenylbis(2,4,6-trimethyl-benzoyl)phosphine oxide, BAPO] and light-absorbing dye (Sudan I), while maintaining the printing resolution and the mechanical properties within suitable ranges (fig. S5).

Although the biocompatibility and biodegradability of the resin components are of primary importance, suitable mechanical properties are essential for the proper function and performance of the printed stents. The mechanical properties of the printed object are defined by the chain length of the (macro)monomers and the cross-linking density of the polymer network created upon illumination (30, 31). To investigate the impact of photopolymer chain length on the mechanical properties of 3D printed objects, tensile tests were performed (fig. S6). The results indicated that the mechanical response of printed materials shifted from stiff and brittle to flexible and elastic with increasing MW and chain length of the copolymer. This was manifested by a gradual increase in elongation at break from ca. 30 to 150% and a reduction in Young’s modulus from 43.6 to 2.9 MPa, as the MW increased from 1200 to 15,000 g mol$^{-1}$. The photopolymer of 15,000 g mol$^{-1}$ (P1) was found to be most suitable for the intended application, owing to the highest elasticity among the tested materials provided by the long and flexible polymer chains.

The elastic polymer P1 reached ultimate true tensile stress of ca. 10 MPa, which is still an order of magnitude lower than the value obtained for commercial silicone rubber of airway stents (fig. S7). To further improve the mechanical performance of the DLP printed material, a dual-polymer resin was designed by combining the polymer P1 [number-average molecular weight ($M_n$)$_{NMR}$ = 15,000 g mol$^{-1}$] with a linear oligomer P2 ($M_n$$_{NMR}$ = 600 g mol$^{-1}$, equimolar ratio of DLLA to CL; 2,2-diethyl-1,3-propanediol as the initiator), as presented in Fig. 2A. The addition of the polymer P2 reduced the viscosity of the resin from ca. 10 to 5 Pa s at the printing temperature of 80°C (fig. S3B) and increased the cross-linking density of the formed network (fig. S8). This increased the ultimate true tensile stress of P1 from 10 to 25 MPa if a P1/P2 weight feed ratio of 75/25 was used in the printing resin (fig. 2B). All materials remained elastic,

![Fig. 1. Schematic workflow for manufacturing and testing of bioresorbable, biocompatible, and customized airway stents by DLP 3D printing.](image)

(A) A 3D model of the rabbit trachea was created from computed tomography scan images. (B) The customized stent was designed to match the tracheal geometry and surface topology. (C) Biomedical inks were developed by mixing photopolymerizable random copolymers of high (in blue) and low (in green) molecular weight (inset). The most promising 3D printed material, which was identified on the basis of successive testing of mechanical performance, cytocompatibility, and biodegradability, was used to manufacture bioresorbable customized stents by DLP. (D) The stents were then made radiopaque by postprinting gold incorporation and inserted in New Zealand white rabbits with an in-house–developed delivery device. (E) The rabbits were radiographically monitored over 10 weeks, and no stent was present in a respiratory tract upon completion of the study.
Fig. 2. Mechanical performance of 3D printed materials based on P1/P2 dual-polymer resins with various proportions of P2. (A) Schematic of the strategy for 3D printing of materials with dual-polymer resins. (B) Average true stress-strain tensile curves of materials produced with P1/P2 dual and P1 polymer resins. Mean ± SD (n = 6). (C) Average Young's modulus of materials containing P1 with various amounts of P2. Mean ± SD (n = 6). (D) Force-displacement curves of tubular specimens printed with P1/P2 dual-polymer resins and a NOVATECH silicone stent (H of 10.0 mm, Ø of 16.0 mm, and thickness of 1.2 mm), obtained in uniaxial compression tests. Inset: Force-displacement curves at low displacement (up to 15%). Mean ± SD (one stent at three different positions). (E) Force-displacement curves obtained in Mylar loop experiments. Mean ± SD (one stent at three different positions). (F) Comparison of mean values of key mechanical properties between NOVATECH silicone specimens (in gray) and DLP printed specimens from 75/25 (w/w) P1/P2 resin (in red) + SD (light gray and red, respectively) from n = 6. Maximum radial displacement, ultimate circumferential force, normal stiffness, and force exerted at the displacement corresponding to 50% of the inner diameter in the uniaxial compression test were selected as application-relevant mechanical properties. (G) Stents of different designs DLP 3D printed with 75/25 (w/w) P1/P2 resin. Photo credit: Yinyin Bao, ETH Zurich.
with Young’s modulus of ca. 3 to 6 MPa (Fig. 2C) and elongation at break above 60% (Fig. 2B).

Despite their lower tensile properties compared to silicone, our polymer networks shaped in stent-like tubular geometries were found to be sufficiently strong to withstand the high stress levels developed during radial compression and crimping. Resistance to buckling failure during radial compression and crimping is an essential requirement to ensure that airway stents are functional and can be loaded in the delivery device. Therefore, a series of nonmeshed tubular stents with size and shape corresponding to a NOVATECH silicone stent (height, $H$ of 10.0 mm; diameter, $\Omega$ of 16.0 mm; and thickness of 1.2 mm) were printed with our polymer blends and tested in two application-relevant loading configurations (Fig. 2, D and E). Uniaxial compression tests revealed that all polymer-based stents show higher load-bearing capacity than the silicone stent for displacements above 50% of their inner diameter (Fig. 2D). No buckling was observed during this test. To quantify the circumferential (hoop) forces developed during radial compression, a custom Mylar loop was designed (fig. S9) (32). All stents, except pure P1, showed similar force-displacement curves and buckling modes preceding crimping (Fig. 2E). On the basis of the optimal combination of high uniaxial compression resistance, circumferential forces, and displacements before crimping, the 75/25 (w/w) P1/P2 polymer blend was selected for all further experiments. The 3D printed material of this composition displayed almost 1.5 times higher maximum circumferential force, 20% larger maximal radial displacement, and 1.5 times higher uniaxial compression resistance at larger displacements compared to the NOVATECH silicone stent, while keeping a comparable normal stiffness of ca. 0.15 N mm$^{-1}$ (Fig. 2F). The high resolution and smooth surface quality achievable with the DLP 3D printing are demonstrated by manufacturing tubular objects with distinct designs using the optimal polymer blend (Fig. 2G).

Besides the properties of the constituent polymers, the mechanical performance of airway stents is also affected by geometrical parameters such as radius and wall thickness. To better understand the impact of geometry on the mechanical response of modeled tubular stents, we conducted finite element (FE) simulations on human-sized structures subjected to uniaxial compression (Fig. 3A). Using experimental data from tensile tests as input parameters, we found a very good fit of the numerical force-displacement curves to the experimental behavior of the tubular structures, confirming the validity of the computational analyses. Numerical snapshots of 75/25 (w/w) P1/P2-based stents during the uniaxial compression simulations (Fig. 3B) indicated no buckling of the tubes at high displacements, which is in accordance with the mechanical response observed in uniaxial compression experiments. The good agreement between experiments and simulations allowed us to apply the numerical tool to study the impact of radius and wall thickness on the normal stiffness of the stents based on 75/25 (w/w) P1/P2 3D printed materials. The simulation results revealed that the normal stiffness can change by as much as one order of magnitude by varying the radius and thickness within a range that is accessible by DLP 3D printing (Fig. 3C). Therefore, our analysis provides a design guide to determine the thickness needed to achieve the desired normal stiffness for a stent with the patient-defined radius.

### Cytocompatibility and in vitro degradation profile

The objects with the best mechanical properties that were 3D printed with 75/25 (w/w) P1/P2 were tested for cytocompatibility on human lung epithelial cells (A549). In compliance with International Organization for Standardization (ISO) standards (10993-5:2009 and 10993-7:2009), the stents showed no cytotoxicity in a cytocompatibility test, as indicated by their viability and proliferation rates comparable to culture medium controls. To evaluate degradation, the stents were immersed in PBS at 37°C for 30 days, and their weight loss was measured at regular intervals. The results indicated a gradual and linear weight loss, with the optimal polymer blend (75/25 w/w) P1/P2 showing the least weight loss over the test period. This suggests that the stents are biodegradable and can gradually release their material components over time, which is crucial for the long-term functionality of airway stents.

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**Fig. 3.** Numerical analysis of the mechanical properties of 3D printed materials based on P1/P2 dual-polymer resins. (A) Comparison between experimental (EXP) and numerical (FE) force-displacement curves of tubular specimens ($H$ of 10.0 mm, $\Omega$ of 16.0 mm, and thickness of 1.2 mm) 3D printed with P1/P2 (70/30, 75/25, and 90/10; w/w) dual-polymer resins. (B) Snapshots of a 75/25 (w/w) P1/P2-based tubular specimen ($H$ of 10.0 mm, $\Omega$ of 16.0 mm, and thickness of 1.2 mm) compressed between two rigid plates at different displacements (0, 5, and 10 mm; from top to bottom). The colors represent the distribution of the maximum principal strains. (C) Contour plot of normal stiffness with the variations of radius and thickness of the 75/25 (w/w) P1/P2-based stent ($H$ of 10.0 mm). The colored scale indicates normal stiffness.
For the development of medical devices, the medium extracts of produced materials were used as medium for the cells (34, 35). In addition, we developed a procedure in which 3D printed materials were placed on top of Transwell inserts to be directly immersed in the cell medium. Cell viability was determined by the MTS assay and compared to medium control. Incubation of A549 cells with the medium extracts of the 3D printed materials or 3D printed materials in Transwell inserts did not significantly affect cell viability (Fig. 4A).

To study the degradation of our customized material, we 3D printed nonmeshed tubular structures as stent prototypes (H of 10.0 mm,Ø of 8.0 mm, and thickness of 1.0 mm) and incubated them in phosphate-buffered saline (PBS) buffer (pH 7.4) at 37° and 50°C. As shown in Fig. 4B, the stents underwent substantial weight loss in...
accelerated degradation study (in red), with 60% of mass remaining after 6 weeks of incubation. At physiological temperature (in blue), almost no degradation was observed during that time. Degradation of the stents at 37°C became more evident from the fourth month, with weight loss reaching 20% after 5 months. These data were in line with the swelling of the stents (Fig. 4C), where weight ratio of water in the stents increased much faster at 50°C as compared to 37°C, reaching 70% of stent’s weight after 6 weeks. When comparing the water uptake levels at the same weight loss level (e.g., 20%), similar water uptake was observed (30 to 40%). To evaluate the changes in the mechanical performance of the stents during the degradation, all stents were characterized by uniaxial compression test at different time points. The compression curves of dry stents incubated at 37°C (Fig. 4D) revealed ca. 50% loss in compressive force over 6 weeks, while those at 50°C (Fig. 4E) lost their mechanical properties completely within 4 weeks. As illustrated in Fig. 4F, the stents incubated at physiological temperature displayed almost no or minor differences in compression force between the dry and the wet states. These stents also maintained their dimensions and surface morphology over 12 weeks (Fig. 4, G to I, and fig. S10) and were unaffected by water uptake up to ca. 10% (Fig. 4, I and J, and fig. S10). In line with the previous experiments (Fig. 4C), degradation at 50°C resulted in opaque hydrogel-like stents after 5 weeks (Fig. 4, K and L).

**In vivo study in a rabbit model**

In a pilot study, the insertion, tolerance, persistence, and bioreabsorbability of the customized DLP 3D printed airway stents prepared with the 75/25 (w/w) P1/P2 resin were assessed in healthy New Zealand white rabbits. Rabbits are commonly used in studies on airway stents because of the histological similarities of their tracheas with those of humans (36–41). Notably, a rabbit’s trachea is more sensitive to compressive forces (42) and its epithelium is more reactive (43), making the tissue response to a stent faster and more extensive compared to humans. An average rabbit’s trachea was created on the basis of computed tomography (CT) images of six rabbits. We designed customized round and slightly flattened stents fitting the model (length of 17 mm, Ø of 6.3 to 6.7 mm, and thickness of 0.6 mm) and oversized them by 15% (36) in diameter to prevent stent migration in vivo (Fig. 5A). The resulting 3D printed stents showed high resolution and flexibility (Fig. 5B). To make radiographically visible objects, gold was incorporated in the stents postprinting, rendering them radiopaque (Fig. S11A). When compared to the native stents, the gold-labeled stents showed slightly improved mechanical properties (Fig. S11B) because of the presence of metal particles (44), while preserving cytocompatibility (fig. S11C). After cleaning and drying, the stents were loaded into a customized delivery device (Fig. 5, C and D, and movie S1) developed for precise stent placement in a rabbit’s trachea at the level of the third cervical (C3) vertebrae. The delivery device was inserted in the anesthetized rabbit through a 5.5-mm uncuffed endotracheal tube, and the stent was deployed at the targeted position. After the placement, the position and the integrity of the stent were reviewed by flexible tracheoscopy (Fig. 5E) and radiography (Fig. 5F).

Six animals allocated in three groups were monitored for 2, 6, and 10 weeks, respectively, to assess the in vivo biocompatibility and bioreabsorbability of the printed stents. Allocation of the rabbits in the groups and the corresponding types of stents they received are reported in table S1. Radiographs showed that the stents stayed unchanged at the insertion place in five of six animals and were visible up to 7 weeks after the placement (Fig. 5F and fig. S12). Only in one animal, the stent migrated cranially to the C2 vertebrae after week 3 (fig. S12B), probably due to sneezing. During the first week, all rabbits showed intermittent stridor at exertion. They also exhibited periodic sneezing without nasal discharge between weeks 3 and 4 that was reduced in two of three animals after the treatment with acetylcysteine (3 mg/kg, p.o.). At euthanasia of the animals with the observation period of 2 and 6 weeks, macroscopic examination revealed the intact stents at the place of the insertion. After 10 weeks, the lungs of both animals upon euthanasia were clean and neither the stents nor pieces of stents could be recovered.

In addition to macroscopic examination, biocompatibility evaluation (45) based on histological findings at the contact surface between the stent and the mucosa showed a clear trend of inflammation and tissue response between different groups of animals (Fig. 5, G to I). When compared to the distal area, the stented area presented a slight overall reaction after 2 weeks that progressed and peaked at week 6 and became minimal or undetectable after 10 weeks (table S1). Similar to previously reported studies on airway stents (36, 37, 39), severe acute inflammation with infiltration of heterophils and mild to moderate dilatation and hyperemia was observed in animals after 2 weeks in the stented area (Fig. 5G). This remained on a similar level up to week 6 in the stented area (Fig. 5H), while declining in the distal area. As expected, chronic inflammation developed at week 6 with abundant lymphocytes, including plasma cells and macrophages (Fig. 5H). Eosinophils were noticeable in a small number up to 6 weeks. As shown in Fig. 5 (G to I), thin and thick irregular epithelia with ulcerations and necrosis were present up to week 6. Epithelial squamous metaplasia was present focally in most of the animals up to 6 weeks, with multifocal changes in one animal of 6 weeks of survival time (Fig. 5H). At week 10 (Fig. 5I), we found tracheal tissue of normal morphology with ciliated columnar epithelium without any traces of inflammation. The stent design (round versus slightly flattened) had no impact on inflammation and tissue response.

**DISCUSSION**

It is of prime importance that the bioreabsorbable stents maintain their mechanical properties during the treatment, especially at the early stage after the insertion. In vitro, dry and wet stents showed approximately the same dimensions and mechanical behavior up to 12 weeks (Fig. 4, F, I and J). This is an important requirement for a functional stent since wet conditions are more representative of the real application conditions. Furthermore, unchanged dimensions of the stents (Fig. 4, G and H, and fig. S10) when compressive resistance decreases for ca. 50% (Fig. 4D) should keep them in place despite the decrease in mechanical properties. In vivo, the gold-loaded stents based on the optimal dual-polymer resin of high- and low-MW poly(DLLA-co-CL) methacrylate in weight ratio of 75/25 preserved sufficient mechanical force to generally stay at the place of the insertion for 7 weeks. Afterward, they were not radiographically visible and at week 10, they were not present in the respiratory tract. In vitro, the evolution of mass loss of the printed objects (Fig. 4B) indicated bulk degradation with autocatalytic effect as the degradation mode (46). These materials lose their mechanical properties faster than their mass (Fig. 4, B and D), as the ester bond cleavage is ongoing from the beginning of the degradation process, while the diffusion of the monomers and oligomers resulting from the degradation of the...
polymer matrix is a relatively slow process (47, 48). On the basis of the literature (47), the same profile of degradation, but with higher degradation rate, is expected in vivo, particularly due to enzymatic activity and mechanical stress. The slower degradation observed in vitro compared to in vivo might also come from the design of the degradation test, which was focused on human application. In accordance to the thickness of a typical silicone airway stent used in human medicine, the in vitro tests were performed on 1-mm-thick stents at 37°C and pH 7.4. The thickness of the stents used in the animal study had to be decreased to 0.6 mm to achieve the required pliability for the insertion, thus making them more susceptible toward degradation. In addition, rabbits have higher body temperature (ca. 39.5°C) (49), which increases the rate of hydrolysis of polymer ester bonds. In the accelerated in vitro degradation experiment conducted at 50°C, the stents decreased their mechanical properties gradually with the hydrolysis of ester bonds (Fig. 4E). Once the mass of the stents dropped below 60% of the initial mass (Fig. 4B), the mechanical stability of the stents was too low and even a slight compression could break them. By that moment, the polymer scaffold became less hydrophobic due to hydroxyl and carboxyl groups formed upon hydrolysis, which together with accumulation of hydrophilic monomers and oligomers entrapped deep in the polymer network caused high water uptake (Fig. 4C) and led to a material with a hydrogel structure (Fig. 4, K and L). While this will eventually result in complete disintegration of the stent in the trachea, the structure will likely be fragmented to very soft pieces that could be easily resorbed or moved toward larynges and further ingested. This hypothesis was supported in vivo by the presence of intact stents in extracted rabbits’ tracheas at weeks 2 and 6, as well as by the absence of stents and fragments of stents 10 weeks after the insertion.

The elastic cross-linked stents we developed and assessed in the in vivo study showed superior performance compared to previously
reported bioresorbable stents made from thermoplastic polymers such as poly(ε-caprolactone), which are prone to stress relaxation or even permanent deformation when being constrained before implantation (18). Our dual-polymer stents were highly flexible, elastic, and restored their size and shape immediately after the deployment. The inflammation pattern that peaked at week 6 postinsertion was similar to the reaction described in previous reports on bioresorbable airway stents (36, 37). Besides, epithelial ulcerations with chronic lymphocytic inflammation were reported underneath all types of airway stents used in rabbit models, including metallic, silicone, and biodegradable poly(l-lactide) materials (39). On a tissue level, the mechanical stress applied by the stent on the healthy trachea caused transformation from pseudostratified columnar epithelium to squamous metaplastic epithelium. Similar effects, which may end up in obstructive granulation tissue formation, are also typically observed in humans (50). We intentionally chose the material with the stronger resistance to uniaxial compression at high displacement in a compression test (Fig. 2D), compared to a silicone stent, to maximize the mechanical performance and assure that the stent would stay in place and keep the tracheal lumen open during the initial several weeks of the treatment. Despite the high local stresses expected from this stiffer stent, all histological changes were completely reversible after the stent disappeared, confirming the biocompatibility of the produced medical device. Future studies should aim at the minimization of the trauma related to the stent insertion to allow for the use of these stents in disease models reproducing obstructed airways.

In summary, we developed a series of biomedical inks based on blends of poly(DLLA-co-CL) methacrylates with diverse polymer chain length and geometry that can serve to DLP 3D print bio-compatible elastic materials with tunable mechanical properties and predictable degradation. The key advancement in terms of ink design lies in the combination of high- and low-MW photopolymers in the same resin. This resulted in 3D printed objects that combine the enhanced strength arising from high cross-linking density and high elasticity provided by long and flexible polymer chains. Printing at higher temperatures with our customized heating system and the addition of a low-MW polymer in the resin reduced viscosity and enabled the generation of objects with complex architecture at high resolution and surface quality. These inks allowed for the manufacturing of customized prototype bioresorbable airway stents with mechanical properties comparable to state-of-the-art silicone stents. FE modeling was conducted to provide design guidelines for choosing the optimal thickness for the defined radius and normal stiffness of the stent for an individual patient. After further optimization, the proposed airway stents might be used to treat patients suffering from CAO in a more personalized way. These stents would disappear over time, preventing the need of additional interventions, which is particularly important for children and elderly patients. While the biomedical inks described in this study were primarily conceived to 3D print airways stents, the tunable mechanical properties of the produced elastic objects, as well as their biodegradable feature, could also be exploited in the future to design other types of personalized stents and medical devices.

**Materials and Methods**

**Materials**

Pentaerythritol, methacryloyl chloride, triethylene, tetrahydrofuran (THF; extra dry), and acetone (extra dry) were purchased from Acros Organics. CL was obtained from Tokyo Chemical Industry. 3,6-Dimethyl-1,4-dioxane-2,5-dione (DLLA) was purchased from Huizhou Foryou Medical Devices Co. Ltd. or Acros Organics. Tin(II) 2-ethylhexanoate [Sn(Oct)2], 2,2-diethyl-1,3-propanediol, sodium bicarbonate (NaHCO3), sodium chloride (NaCl), (+)-α-tocopherol (vitamin E), NVP, BAPO, 1-(phenylidazeyl)naphthalene-2-ol (Sudan I), borane-tert-butylamine complex [(CH3)2CNH2 BH3], and lithium bromide (LiBr) were purchased from Sigma-Aldrich. Hydrogen tetrachloroaurate(III) trihydrate (HAuCl4) was obtained from abcr. Hexane, dichloromethane (DCM), and dimethylformamide (DMF) were purchased from Thermo Fisher Scientific. Dimethyl sulfoxide-d6 (DMSO-d6) was obtained from ReseaChem. Methanol and 2-propanol were provided by VWR Chemicals. Midazolam was purchased from Sintetica. Alfaxalone was purchased from Jurox UK. Isoflurane was purchased from Provet AG. PBS was obtained from Thermo Fisher Scientific. All chemicals were used as received.

**Polymer synthesis**

Poly(DLLA-co-CL)s were synthesized by ring-opening polymerization of DLLA and CL initiated by pentaerythritol (four-arm structure) or 2,2-diethyl-1,3-propanediol (linear structure), with Sn(Oct)2 as a catalyst (fig. S1) (26). The MW of the polymers was controlled by varying the molar feed ratio of the monomers and initiators ([M]/[I]). Thereafter, poly(DLLA-co-CL)s were functionalized with methacryloyl chloride in the presence of triethylene in THF (fig. S1) (26).

Representative synthesis of P1 (four-arm)—pentaerythritol (0.19 g, 1.4 mmol), CL (13.60 g, 120 mmol), DLLA (7.48 g, 52 mmol), and Sn(Oct)2 (5 μl, 0.015 mmol)—were added to a Schlenk flask. The flask was exposed to vacuum for 1 hour and purged with argon for three cycles to remove water and oxygen and then placed in an oil bath at 140°C for 48 hours under stirring. The product was dissolved in THF and precipitated in hexane, resulting in a transparent and highly viscous polymer. On the basis of 1H nuclear magnetic resonance (1H NMR) spectroscopy, the conversions of DLLA and CL were ca. 90 and 99%, respectively (fig. S13). The synthesis resulted in a polymer of low polydispersity, which was confirmed by size exclusion chromatography (SEC) (fig. S14 and table S2). The unfunctionalized polymer (18.71 g) was then dissolved in THF (100 ml). After the addition of triethylene (2.34 ml, 16.8 mmol), the solution was purged with nitrogen for 15 min. Methacryloyl chloride (1.63 ml, 16.8 mmol) was diluted in THF (5 ml) and added dropwise to the polymer solution while stirring and cooling in an ice bath. The reaction mixture was then stirred for 24 hours at room temperature. Afterward, the salts were removed by centrifugation (4000g, 4°C, 20 min) and vitamin E (0.05 g) was added to the supernatant to prevent premature cross-linking. The supernatant was concentrated under vacuum, followed by precipitation in methanol. The obtained transparent viscous polymer was dried under high vacuum for a week. On the basis of 1H NMR spectroscopy, the conversion of hydroxyl end groups of the polymer chains was 70 to 87% (fig. S15). The same procedure was followed for the synthesis of four-arm polymers of MW 5000 to 11,000 g mol⁻¹, CL/DLLA molar ratio of 7/3, with varying [M]/[I] (figs. S13 to S15 and table S2).

Representative synthesis of P2 (linear)—2,2-diethyl-1,3-propanediol (6.61 g, 50 mmol), CL (11.38 g, 100 mmol), DLLA (14.23 g, 100 mmol), and Sn(Oct)2 (160 μl, 0.5 mmol)—were added to a Schlenk flask. The synthesis was further performed following the same protocol as described for unfunctionalized P1 polymer. The conversions of DLLA and CL based on 1H NMR spectroscopy were ca. 55 and 99%,
respectively (fig. S16A). The synthesis resulted in a polymer of low polydispersity, which was confirmed by matrix-assisted laser desorption/ionization–time-of-flight (MALDI-TOF) (fig. S17). The unfunctionalized polymer (18 g) was dissolved in THF (150 ml). After the addition of triethyamine (17.0 ml, 122 mmol), the solution was purged with nitrogen for 15 min. Methacryloyl chloride (11.0 ml, 114 mmol) was diluted in THF (10 ml) and added dropwise to the polymer solution while stirring and cooling in an ice bath. The reaction mixture was stirred for 24 hours at room temperature. Afterward, the salts were removed by centrifugation (4000 g, 4°C, 20 min) and the supernatant with vitamin E (0.05 g) was concentrated. The polymer was dissolved in DCM (200 ml), washed with saturated NaHCO₃ and NaCl aqueous solutions, and dried with anhydrous Na₂SO₄. After addition of vitamin E (0.05 g), the solution was concentrated under vacuum and the polymer was further dried under high vacuum for a week. On the basis of ¹H NMR, the conversion of hydroxyl end groups of the polymer chains was 51 to 54% (fig. S16B). The same procedure was followed for the synthesis of four-arm polymer of MW 1200 g mol⁻¹, CL/DLLA molar ratio of 7/3, with pentaerythritol as initiator and with varying [M]/[I], while polydispersity was quantified by SEC (figs. S13 to S15 and table S2).

**Polymer characterization**

¹H NMR spectra were recorded on Bruker AV400 spectrometer at 400 Hz using DMSO-d₆ as a solvent. SEC was carried out on a Viscotek TDAmax system equipped with two Viscotek columns (D3000, poly(styrene-co-divinylbenzene)) and differential refractive index detector (TDA 302, Viscotek). All samples were dissolved in DMF, filtered using 0.2-μm syringe filters (polytetrafluoroethylene, PTFE) and eluted using DMF with LiBr (0.1 wt %) as a mobile phase. The macromolecular characteristics were determined relative to a poly(methyl methacrylate) standard curve (PSS Polymer Mainz; 2500 to 89, 300 g mol⁻¹). Differential scanning calorimetry (DSC) analysis was performed using TA Q200 DSC (TA Instruments–Waters LLC). The samples (ca. 10 mg) were placed on Tzero hermetic pans (TA Instruments–Waters LLC) and exposed to heat-cool-heat cycles from −80°C to 200°C under nitrogen flow (50 ml min⁻¹) using heating and cooling rates of 10°C min⁻¹. Data were analyzed using TA Instruments Universal Analysis 2000 software (5.5.3). Viscosity measurements were performed using a HAAKE RheoStress 600 rotational rheometer (Thermo Electron Corporation) with cone and plate geometry (35 mm/2°). Viscosity was determined at a shear rate of 100 s⁻¹ in the temperature range of 70 to 100°C, applying a heating rate of 0.05°C s⁻¹. Water was analyzed by RheoWin Data Manager (Thermo Electron Corporation). Fourier transform infrared spectra were recorded on a Perkin-Elmer Spectrum 65 (Perkin-Elmer Corporation) in transmission mode in the range of 600 to 4000 cm⁻¹. MALDI-TOF spectra were measured on a Bruker Daltonics Ultraflex II spectrometer in the positive ion reflector mode using trans-2-[3-(4-tert-butylphenyl)-2-methyl-2-propenylidene] as a matrix.

**DLP 3D printing**

Resins were prepared by adding a solution of BAPO (photoinitiator, 1.0 wt %) and Sudan I (blue light-absorbing dye used to reduce the curing depth, 0.03 wt %) in NVP (8.0 wt %) to the photopolymers and vitamin E (radical inhibitor used to prevent premature cross-linking, 0.3 wt %). The resins were sonicated at 60°C until a homogenous mixture was obtained. A commercial DLP 3D printer (Asiga PICO2) comprising the light-emitting diode light source of 405 nm with customized resin tray and printing head with heating functions (fig. S4) was used to fabricate all the objects. The printing was performed at a temperature of 80°C, with exposure time of 3.3 s, and initial exposure time of 15 s. After printing, the printed objects were cleaned in acetone and 2-propanol and then cured in an Asiga Pico Flash UV chamber for 15 min.

**Mechanical characterization of 3D printed objects**

Tensile, compression, and Mylar loop tests were performed using an AGS-X (Shimadzu) universal testing machine with a 100-N capacity load cell. Tensile tests were carried out on dog bone–shaped 3D printed specimens (ASTM 638 type IV) with a gauge length of 13 mm at a rate of 20 mm min⁻¹. Compression tests were performed on nonmeshed tubular 3D printed specimens (H of 10.0 mm, Ø of 16.0 or 8.0 mm, and thickness of 1.0 or 1.2 mm) at a rate of 10 mm min⁻¹. Every sample was tested three times. Mylar loop experiments were carried out on tubular 3D printed specimens (H of 10.0 mm, Ø of 16.0 mm, and thickness of 1.2 mm), with an in-house–developed Mylar loop (fig. S9) at a rate of 20 mm min⁻¹. Every sample was tested three times. True stress and strain were calculated using Eqs. 1 and 2 (51), respectively

\[
\sigma = \frac{F}{A_0} \times \left(1 + \frac{L}{L_0}\right) \\
\varepsilon = \ln \left(1 + \frac{L}{L_0}\right)
\]

where \(\sigma\) is true stress, \(\varepsilon\) is the true strain, \(F\) is the force, \(A_0\) is the initial cross-sectional area, \(L\) is the elongation, and \(L_0\) is the initial gauge length. Normal stiffness was calculated as a slope of the initial linear region of compression-displacement curves obtained in uniaxial compression tests.

**Numerical simulations**

The simulations were carried out using the commercial nonlinear FE package ABAQUS 2017 (SIMULIA). The ABAQUS/STANDARD solver was used for all simulations. To describe the material properties of our polymers, given the softening-hardening nature of stress-strain curves, we assumed an incompressible Gent hyperelastic material model (52) and used MATLAB curve fitting tool to fit the full range of dog bone–shaped tensile test specimens to this model. The obtained parameters (shear modulus and stretch limit) are introduced to simulations using a user-defined subroutine (*UHYPER subroutine in ABAQUS). The tubes are discretized with solid elements (type C4D8) and compressed between two rigid plates that are meshed with shell elements (type S4). We performed dynamic implicit analysis (*DYNAMIC module in ABAQUS) by lowering the plate until it touches the tube and compressing it to the desired deformation against the bottom fixed plate. A simple contact law was assigned to the model with a hard contact for normal behavior and a frictionless tangential behavior between the rigid plates and the tube. The reaction force of the top plate was recorded as a function of the applied displacement in the normal direction and was compared against experimental compression test data. Last, a Python script was developed to perform a parametric study on the role of variation in radius and thickness on the normal stiffness of tubes. The slope of the initial linear region of the compression-displacement curve is reported as the normal stiffness of the tubes.
**In vitro degradation study**

The 3D printed nonmeshed tubular specimens (H of 10.0 mm, Ø of 8.0 mm, and thickness of 1.0 mm) were immersed separately in 50 ml of PBS (pH 7.4) at 37° ± 1°C, in tightly closed 50-ml Falcon tubes. The buffer was replaced at weekly intervals. At each sampling time point, the specimens were taken out, rinsed with deionized water, wiped with paper tissue, and dried under vacuum at 50°C overnight. The water uptake (wt %) was calculated using Eq. 3

\[
\text{water uptake} = \frac{\text{wt}_{\text{wet}} - \text{wt}_{\text{dry}}}{\text{wt}_{\text{dry}}} \times 100
\]

where \(\text{wt}_{\text{wet}}\) is the mass of a stent in a wet state after the wiping, and \(\text{wt}_{\text{dry}}\) is the mass of a stent in a dry state after drying under vacuum. The dried specimens were studied by a uniaxial compression test. In the degradation study performed at 37°C, a compression test was also performed with stents in a wet state. Both degradation studies were performed with four 3D printed tubular specimens but with two different batches of P1 and P2. Objects were visualized using a Keyence scanning laser microscope.

**Cell culture**

Human lung epithelial cells (A549, American Type Culture Collection) were cultured at 37°C in a humidified atmosphere with 5% CO2. The cells were used up to passage number 12 and were tested for mycoplasm contamination (Mycoplasma Detection Kit, Lonza) at first and last passage numbers. A549 cell line was cultured in complete medium containing DMEM (Dulbecco’s modified Eagle’s medium) (high glucose, GlutaMax, pyruvate; Thermo Fisher Scientific) supplemented with 10% fetal bovine serum (Thermo Fisher Scientific) and 1% penicillin-streptomycin (Thermo Fisher Scientific).

**In vitro cytocompatibility test**

The tests were performed in 24-well plates with seeding density of 50,000 cells per well and repeated in three independent experiments, each one with three-well replicates. For positive and negative controls, cells were incubated in complete medium with 10 mM hydrogen peroxide and complete medium only, respectively, under the same conditions as the tested materials. Cell viability was determined using the MTS assay (CellTiter 96 Aqueous One Solution Cell Proliferation Assay, G3580, Promega) according to the manufacturer’s instructions and was calculated as a percentage of the negative control. 3D printed disks (native or loaded with gold, see the “Manufacturing radiopaque stents” section) were washed in acetone (50 ml) for 30 min, dried, and then washed in PBS (50 ml, pH 7.4) overnight. Afterward, the objects were dried under vacuum at room temperature for 24 hours and then cured in an Asiga Pico Flash UV chamber. Thereafter, they were cleaned in acetone (50 ml) for 30 min, dried, washed in PBS (50 ml, pH 7.4) for 24 hours, rinsed with deionized water, and then dried in a desiccator for 24 hours.

**Fabrication of the delivery device**

In-house delivery device was composed of two coaxial tube assemblies (Fig. 5C). The outer tube was fabricated from PTFE to minimize friction during insertion. Using a heat-shrink process, the tube was flared at one end to create a compartment for loading a crimped stent. The inner tube was a modified Acclarent balloon dilation device (Acclarent, Inspira Air; 7 × 24 mm) modified using a Pebax heat-shrink tubing to increase stiffness and decrease balloon size. This part was used for pushing the stent out of the device and repositioning if necessary. The device was applied through a commercial 5.5-mm ID (inside diameter) uncuffed endotracheal tube (5.5-mm ID; Shiley Oral/Nasal Endotracheal Tubes, Cuffless, Non-DEHP, Murphy Eye). As the procedure of stent insertion lasts only for a few seconds, no oxygen supply was needed.

**Design of the stents for in vivo study**

A CT scan of the head and lungs was acquired for each rabbit. The DICOM (Digital Imaging and Communications in Medicine) file was imported into the open-source InVesalius software (version 3.1). The area of interest, i.e., the larynx and the trachea up to the first bronchial branch, was cropped and then isolated using a watershed threshold between −1024 and −700 Hounsfield units. The isolated tracheal surface was then exported as an stereolithography (STL) mesh. The mesh for each animal was imported into the CAM package Rhino 3D (version 6, McNeel Software), and all were reoriented such that the bottom of larynx lays on the xy plane and the trachea was oriented as vertically as possible along the z axis. A series of 16 planes offset from 30 to 46 mm below the xy plane were created and then intersected with the mesh. The result was a series of planar curves equating to the outline of the trachea for each animal (within the area of interest). The length of each curve was measured and corresponding curves at each tracheal position across the six animals were averaged. The series of averaged lengths were used as the circumference for a group of coaxial circles, each spaced 1 mm apart. These circles were converted to a nonuniform tubular surface using the Rhino 3D “Loft” command. Last, a second surface was created by offsetting inward by the desired stent wall thickness of 0.6 mm. The two surfaces were joined, capped, and exported as a printable STL mesh.
in vivo study
The experimental protocol was approved by the Zürich Cantonal Animal Ethics Committee (ZH069/18) and performed according to the Swiss Animal Welfare Act (TSchG, 455). The stents were inserted in nine adult female New Zealand white rabbits (Charles River Laboratories, Germany) with age of 6 months and average weight of 3.5 kg. Before anesthesia, animals were preoxygenated with oxygen (2 liter min⁻¹) over 5 min through a breathing mask. Anesthesia was induced by intranasal application of midazolam (0.1 mg kg⁻¹) and alfaxalone (3.0 to 5.0 mg kg⁻¹). After intravenous application of a bolus of propofol (0.6 mg kg⁻¹), a bronchoscope (Ambu aScope 4 Broncho slim 3.8/1.2) was introduced into the trachea and the endotracheal tube slid over the endoscope to secure the airway. The anesthesia was maintained by isoflurane and oxygen. The delivery device for the stent was lubricated with a methylcellulose-based lubricant and the stent was crimped and loaded in. It was applied through an endotracheal tube, and the stent was positioned in the area of the C3 vertebrae. After the placement, the position and the integrity of the stent were reviewed by flexible tracheoscopy (Ambu aScope 4 Broncho Regular 3.8/1.2) and radiographic examination (in lateral recumbency of the animal). Three animals were excluded from the analysis because of Aspergillus infection, deep stent insertion, and respiratory distress in the absence of the stent. The remaining six animals were allocated into three groups of two according to the monitoring time (2, 6, and 10 weeks). The animals were housed in groups with free access to hay and water. They were checked daily for respiratory distress, food, and water intake, while radiographic examinations were performed once per week. Body weight was checked 24 hours before surgery and frequently during the postoperative observation period.

The animals were euthanized at 2, 6, or 10 weeks after stent placement. Complete histopathological examination was performed from the trachea including the stented and the area distally to the stent, the monitoring time (2, 6, and 10 weeks). The animals were housed in groups with free access to hay and water. They were checked daily for respiratory distress, food, and water intake, while radiographic examinations were performed once per week. Body weight was checked 24 hours before surgery and frequently during the postoperative observation period.

Statistical analysis
Statistical significance in cytotoxicity experiments between the treated groups and a negative control was calculated by one-way analysis of variance (ANOVA) with Tukey’s comparison test with P value < 0.001 considered as significant.

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SUPPLEMENTARY MATERIALS
Supplemental material for this article is available at http://advances.sciencemag.org/cgi/content/full/7/6/eabe9499/DC1
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Digital light 3D printing of customized bioresorbable airway stents with elastomeric properties

Nevena Paunovic, Yinyin Bao, Fergal Brian Coulter, Kunal Masania, Anna Karoline Geks, Karina Klein, Ahmad Rafsanjani, Jasmin Gadalbert, Peter W. Kronen, Nicole Kleger, Agnieszka Karol, Zhi Luo, Fabienne Rüber, Davide Brambilla, Brigitte von Rechenberg, Daniel Franzen, André R. Studart and Jean-Christophe Leroux

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