Research Article

The Display System of a Patient’s History Using the RFID and Linux

Soo Young Ye¹ and Heung-kuk Jo²

¹ Department of Radiological Science, Catholic University of Pusan, 57 Oryundae-ro, Geumjeong-gu, Busan 609-757, Republic of Korea
² Division of Computer Information Engineering, Dongseo University, Jurae-dong, Sasang-gu, San 69-1, UIT 106, Busan 617-716, Republic of Korea

Correspondence should be addressed to Heung-kuk Jo; hkjo@gdsu.dongseo.ac.kr

Received 17 October 2012; Revised 17 January 2013; Accepted 20 January 2013

1. Introduction

Doctors and nurses need a mobile conversion system in a ubiquitous environment in a hospital to see their patient’s personal and medical histories [1–4]. An RFID system is first required, however, for recognition of the patient, as is a loaded embedded Linux system for data monitoring. The RFID tag system is essential for patients who wear a tag, as it recognizes a patient’s medical history without error [1–4]. The existing real-time embedded Linux operating system is more advanced than the previous system and supports more features, and through its current source, its development speed is fast increasing [5–9]. Judging from these facts, a mobile ability system is required for the design of a patient monitoring system. Its development cost is also lower. An integrated system for the monitoring of the patient’s history must be capable of real-time behavior. Moreover, immediately needed tag information for monitoring requires a fast-booting system, and one of the essential requirements for mobile conversion is a low-power mobile system [10–17]. In this study, to monitor RFID data in real time, the RFID system used a 125 kHz carrier wave with the EM4095 and an embedded Linux operating system with a 400 MHz PXA255 ARM RISC chip, a 512 Kbyte Boot Flash, and a 64 Mbyte SDRAM. Moreover, the system was configured to use a NAND Flash [9]. Given the overall system configuration and operating conditions, CC1020 was embedded in the RFID system using a wireless communication system [18–26]. The extended Linux system boot process and the overall boot loader, kernel, and application processes were operated in an orderly manner. In conclusion, the performance was analyzed and shown with pictures of the experimental systems.
2. System Configuration

2.1. System Concept. In Figure 1, tag information is sent to the 125 kHz RFID reader. The received tag data will be sent to the server using the wireless CC1020 module with a 433 kHz frequency [27–29]. The saved data from the server contains the corresponding patient medical history, and the tag information and corresponding data are retransmitted via a wireless module. After such data are received using RS232 communication, they will be transmitted to the embedded system that is equipped with the PAX255 ARM Chip. Based on the QT written monitoring program, the embedded system outputs a history of the patient’s medical history to a TFT-LCD.

2.2. System Configuration

2.2.1. RFID System. The RFID system used an EM4095 general purpose chip that was produced by the SWATCH group.

It is a CMOS device that uses the 125 kHz frequency band. The tag in the RFID system was EM4100 and will operate only in the Read-Only mode. Using EM4095, the reader system was set up to operate in the Read-Only mode. Figure 2 shows the circuit configuration of the RFID system.

L2 in Figure 2 is the antenna that is attached to the reader. Tag data are entered on the antenna of the EM4095 13-pin output. To input the data to the CC1020, Atmega128 MICOM was used.

2.2.2. Wireless Communication System with CC1020. Figure 3 shows the circuit that used the CC1020 chips. One of the important characteristics is shown in the schematic of the PLL circuit using fixed and variable frequencies by synchronous phase and LC filters.

The frequency of a particular band pass was used. CC1020 was needed to set the behavior of the PSEL, PCLK, PDI, and PDO pins and for a bidirectional AVRData interface. The DIO pins DCLK pin connection was required. An almost perfect CC1020 is shown in Figure 4 with synchronous serial interface settings, using the MCU.

This interface can be divided into two parts. First, the internal register has to install a CC1020 chip that supports the implementation of a communication system. After the completion of the second set, the actual data are used for transmission and receipt. The interface circuit in Figure 4 explains this process.

2.2.3. Embedded Linux System. EZBOOT was used for the embedded Linux system that was manufactured by Falinux. Its main feature is its ability to memorize, read, and write.
It uses ZMODEM to download images and flash memory to read and write. To display the history of the patient information system on the LCD, the embedded Linux system must be initialized. The initialization process should be performed as shown in Figure 5.

At the moment of the initialization of the embedded Linux system, the Bootloader must be executed in 512 Kbytes of the BIOS Boot Flash within sector 0, cylinder 0. The Bootloader will first initialize the hardware for the system to operate, and the CPU will make the access possible to the SDRAM. As shown in Figure 6, the kernel and RAMDISK images are stored in the 64 Mbyte NAND Flash and will be saved in the 64 Mbyte SDRAM.

Before the kernel is performed for the i386 Linux-2.4.19 to make it apt for ARM usage, ARM patching must be performed. Due to the use of a CPU as a PXA255 chipset, the kernels with the performed XScale must be loaded to the 64 M NAND Flash in the EZBOOT setup mode. The Linux kernel and arch/∗/kernel/head.S, which enable the C code to perform the operation, were programmed at the entry point. Moreover, the init/main.c has a start kernel () function, and such function of arch_init, trap_init, is
an architecture-dependent initialization function. Each part of the Linux kernel has an initialization function. The start kernel() function at the end of the kernel thread (init,...), as a function of the PID, will create a single kernel thread, and the start kernel() function itself is an idle task. Moreover, the init kernel thread will mount the root file system in the Read-Only mode. At this point, because the embedded Linux system does not have a hard disk, it must load the root file system to the Ram disk. When the Ram disk that serves as the root file system is loaded, the System V init is finally performed. The last kernel performance process in the exec/sbin/init is called the System V init program. It has the same functions and performance as the DOS program of the old, which had autoexec.bat (the Batch file that enabled automatic operation). The System V init and /etc/inittab file perform according to the contents of the inittab file, and the information contents vary depending on such performance. Table 1 shows the Runlevel per performance type, which groups the services into different categories.

In the embedded system, a specific user application, the booting must be carried out simultaneously. Therefore, the RFID tag data must be sent from the system and outputted to the TFT-LCD window immediately after the board booting is completed. Thus, the /etc/inittab file shown in Algorithm 1 was revised.

The Runlevel of the embedded Linux system is basically 3, 3:3:wait:/etc/rc.d/rc 3. The execution sequence of inittab is rc.sysinit>>rc.local>>rc3.d. As shown in Table 2, an executable script was added, and in the directory of etc/rc.d that was executed with rc.local, the rc.app application script was made. A brief description of the script follows.
Figure 6: Boot loader memory map.

Figure 7: Experiment system.

Figure 7(b) shows the capability of the 125 kHz RFID system and server, which are configured to communicate with a wireless communication module, the CC1020 system, to read tag information.

Figure 8 tag shows that the RFID system has read the data. The output of the TFT-LCD window shows the experiment results of the embedded Linux system.

As shown in the picture, if the tag has not made contact with the reader, a basic screen output will be shown like the picture shown in Figure 8(a).

If contact has been made between the reader and the tag, the data are immediately recognized and completed. These data will complete the communication through the server, and the output image will be displayed by the embedded systems of the TFT-LCD screen, as shown in Figure 8(b).

Table 3 shows the performance of the experiment device. The CC1020 transmission of the transferred data among the tag IDs involved removal of the starting byte and the stop byte of the tag ID. After only 8 bytes were removed, the information was transmitted and received. The experiment was repeated 100 times using the system, and no error occurred during the transmission.

4. Conclusion

In this study, through a digital wireless communication device, tag information data were transmitted between the client server and the server with an RFID system. Concerning the verified data, a system that could monitor information in real time was developed: the embedded Linux system with a PXA255 ARM chip. The RFID system developed a multichannel, unidirectional, and bidirectional transmission/receiving system using the ISM band. Its distinctive characteristics are low-power consumption, high sensitivity, a small chip, and
fewer external components. Therefore, the system showed the possibility of low-power usage and reduced production costs and sizes. Embedded Linux systems are integrated with the RFID tag System, and information must be outputted on a TFT-LCD window and must internally use EZBOOT with 2.4 kernels. This system was developed to simultaneously self-boot and run the QT application, so that it can monitor RFID data. The experiment was performed inside a walled building; and within 50 m, tag data were transmitted 100 times. There were no errors during the tag data monitoring. With this result, this system showed potential application in hospitals.

Acknowledgment

This research was supported by a research program of Dongseo University’s Ubiquitous Appliance Regional Innovation Center supported by the Grants from the Ministry of Knowledge Economy of the Korean government and Busan Metropolitan City (no. B0008352).

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