Third-order relativistic hydrodynamics: dispersion relations and transport coefficients of a dual plasma

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ABSTRACT: Hydrodynamics is now understood as an effective field theory that describes the dynamics of the long-wavelength and slow-time fluctuations of an underlying microscopic theory. In this work we extend the relativistic hydrodynamics to third order in the gradient expansion for neutral fluids in a general curved spacetime of d dimensions. We find 59 new transport coefficients, 20 due to third-order scalar corrections and 39 due to tensorial corrections. In the particular case of a conformal fluid, the number of new transport coefficients is reduced to 19, all of them due to third-order tensorial corrections. The dispersion relations of linear fluctuations in the third-order relativistic hydrodynamics is obtained, both in the rest frame of the fluid and in a general moving frame. As an application we obtain the transport coefficients of a relativistic conformal fluid in three-dimensions by using the AdS/CFT correspondence. The gravity dual of the fluctuations in this conformal fluid is described by the gravitational perturbations of four-dimensional anti-de Sitter black branes, which are solutions of the Einstein equations with a negative cosmological constant. To find the hydrodynamic quasinormal modes (QNMs) of the scalar sector we use the SUSY quantum mechanics of the gravitational perturbations of four-dimensional black branes. Such a symmetry allows us to find the hydrodynamic limit of the scalar-sector wave function from the known solution of the vector sector, which is in general easier to be found directly from the (vector) perturbation equations.

KEYWORDS: Relativistic Hydrodynamics, AdS/CFT, Black holes, Classical Theories of Gravity, Quasinormal Modes
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1 Introduction

The very unique properties of the quark-gluon plasma claim for the development of theoretical physics. In the last century it was speculated that, for very high temperatures, quarks and gluons would behave like free particles as a consequence of the asymptotic freedom [1]. In this century it has become possible to reach such very high temperatures in particle accelerators like the RHIC and LHC, where the quark-gluon plasma (QGP) has been produced in heavy ion collisions since 2005. Despite those initial expectations, quarks and gluons are far from being free in the QGP; rather, they are strongly coupled and the perturbative QCD is unable to give reliable predictions for this system [2]. Many challenges need to be overcome to find a complete theoretical description of the QGP since, besides the very high temperatures and strongly coupled interactions involved in the process, the quarks and gluons are confined so that direct measurements in QGP are forbidden and only the final hadronic states are observable [3]. Such a difficulty may be circumvent by following the 1950’s Landau proposal to make use of hydrodynamics to describe the collective behaviour of fundamental matter [4]. In fact, such a proposal has been successfully applied in the description of heavy ion collisions [2, 3, 5–7]. Therefore, the direct application of fluid dynamics to describe the evolution of QGP is a strong motivation to look for further developments on the theory of relativistic hydrodynamics.

The relativistic version of the Navier-Stokes equation has a well-known causality problem [8]. It has a mode that satisfies a partial differential equation of the heat kind whose Green function allows for instantaneous propagation. In this sense the relativistic Navier-Stokes equations are inconsistent with special relativity itself and a more refined treatment is required. The first refinement comes by considering two additional terms, each containing one extra derivative, first implemented for non-relativistic fluids [9] and then extended to the relativistic ones [10, 11]. The additional terms come with new transport coefficients, the relaxation times, and solve the causality problem, providing a consistent theory of viscous relativistic fluids known as the Muller-Israel-Stuart (MIS) theory.

It turns out that the additional terms included in the MIS theory to solve the causality problem do not represent the most general setup that should include first and second derivatives of the fundamental degrees of freedom of the fluid. In fact, the relativistic version of the Navier-Stokes equation, as well as the ideal fluid equations, can be expressed by the divergenceless of an energy-momentum tensor, suggesting that hydrodynamics can be formulated by fixing the general form of this energy-momentum tensor. This strategy has been used in [12] where the complete theory of conformal fluid dynamics involving terms up to second order in derivatives of the energy-momentum tensor is obtained. For non-conformal fluids the same procedure of fixing the most general energy-momentum tensor involving up to second-order derivatives was used in [13], thus generalizing the MIS theory. This way of constructing the theory of fluid dynamics by fixing the most general effective energy-momentum tensor up to some order in derivatives is known as the gradient expansion.

Now, by means of the AdS/CFT correspondence [15], the gradient expansion may be connected to gravitational perturbations on the anti-de Sitter (AdS) side of the duality.
In fact, we learned from the AdS/CFT that the energy-momentum tensor in a conformal quantum field theory is dual to the background metric of an asymptotically AdS spacetime. As a consequence, linear fluctuations around a thermal-equilibrium state in the field theory correspond to linear gravitational perturbations on an AdS black hole. Furthermore, the spectra of black-hole quasinormal modes (QNMs) [16] are characterized as linear perturbations with infalling boundary condition at the horizon, which is equivalent to consider retarded Green’s functions in the dual field theory. The relation between the poles of retarded Green’s functions and the QNMs requires that the condition imposed on the metric fluctuations at the AdS boundary must be of the Dirichlet type. With these boundary conditions the frequencies of the QNMs are complex numbers, whose imaginary parts may be interpreted as thermalization times in the dual field theory.

Still regarding the linear fluctuations of a black-hole metric, an underlying symmetry arises in four-dimensional spacetimes, which is similar to the supersymmetric (SUSY) quantum mechanics [17–19] and relates the axial (odd) and polar (even) sectors of the gravitational perturbations. Such a symmetry was first noticed in the context of the transformation theory developed by Chandrasekhar [23] and applied to the study of the metric perturbations of Schwarzschild black holes in asymptotically flat spacetimes (see for instance Refs. [20–22]). In the linearized gravity, the SUSY relation represents the gravitational counterpart of the electric/magnetic duality of the vacuum Maxwell equations [24, 25]. Additionally, the SUSY quantum mechanics of perturbations also occurs in the presence of a (positive or negative) cosmological constant. In particular, it has been shown to hold in four-dimensional asymptotically AdS spacetimes [26, 27].

Asymptotically anti-de Sitter black-hole like objects play a very important role in applications of the gauge/gravity duality. A particularly interesting case within this family is the four-dimensional black brane [28–32]. The fact that makes this solution important for applications in AdS/CFT is the non-spherical topology of the horizon, which may be planar ($\mathbb{R} \times \mathbb{R}$), cylindrical ($S^1 \times \mathbb{R}$) or toroidal ($S^1 \times S^1$). The gravitational and electromagnetic perturbations of these objects have been extensively studied in the last two decades [33–36, 38–40]. In Ref. [27] the authors studied the gravitoelectromagnetic perturbations of charged black branes and extended the Chandrasekhar’s transformation theory to the presence of sources. They found a SUSY quantum-mechanical relation between the axial and the polar sectors of these perturbations. It is worth mentioning that one of the main consequences of this symmetry is that the problem of finding the QNMs can be greatly reduced. For example, we might focus on the axial sector to find the QNM wave functions, and then use the SUSY relation to find the solutions of the polar sector, whose perturbation equations are in general more complicated to be solved. This fact is used in the development of the present work.

The first part of the present paper is dedicated to the development of the gradient expansion of both conformal and non-conformal fluids involving terms up to third order in derivatives. As far as we know, Ref. [14] is the first work dedicated to the construction of third order hydrodynamics and the present work is strongly motivated by it. Here we face the problem of finding a consistent and efficient way of establishing the third order hydrodynamics, in special for the case where conformal symmetry takes place, improving
the methodology presented in [14]. By working only with completely covariant gradients as fundamental structures we find additional constrains on conformal and non-conformal hydrodynamics reducing the number of transport coefficients in comparison to the previous results.

This work is organized as follows. Section 2 is dedicated to the study of the general case of non-conformal fluids in $d$-dimensional spacetimes. We use a systematic procedure to expand the energy-momentum tensor up to third order in the gradient expansion. In Section 3 we deal with conformal fluids. The conformal symmetry is implemented via minimal coupling what allows us to obtain third order conformal corrections in a direct way. Section 4 is devoted to study linearized fluctuations of the fluid and to find the dispersion relations as a functions of a reduced set of transport coefficients for either non-conformal and conformal fluids. In Section 5 we analyze an application of the general results obtained in previous sections, focusing on the gravitational perturbations of plane-symmetric static black holes, where we find the dispersion relations in the hydrodynamic limit, i.e., in the low energy and long wavelength limit, of the axial (transverse or vector) sector. Then, we use the SUSY relation to find the dispersion relations of the polar (longitudinal or scalar) sector in the hydrodynamic limit. We also include a discussion on different kind of variables that might be used to write the gravitational perturbations. At the end, we compute the energy transport coefficients arising up to third order in the gradient expansion of the conformal fluid, which is dual to the plane-symmetric static black hole. We present the conclusion and final remarks in Section 6. Additional material are left in Appendices A and B.

With the gradient expansion developed up to third order at disposal we then consider perturbations of the flow in momentum space to obtain the dispersion relations for shear and sound waves. We restrict the analysis to perturbations of a static flow, in this case only linear perturbations survive and a very reduced set of transport coefficients are relevant. We find the analytic expressions for the dispersion relations in a static frame and an algebraic equation in the general case in a moving frame. For a non-conformal fluid, both in the static and moving cases, only three third order coefficients are relevant for the dispersion relations, while only two third order coefficients appear in the dispersion relations of the conformal fluid cases.

2 Relativistic hydrodynamics

2.1 The basic formulation

The purpose here it to construct order by order the effective theory that describes the dynamics of a relativistic one-component and uncharged fluid. This is done by looking for corrections to the ideal fluid dynamics in the form of gradients of the fundamental degrees of freedom. The local fundamental variables of a fluid are the energy density $\varepsilon$, pressure $p$, entropy density $s$, temperature $T$, and the vector field $u^\mu$ corresponding to the flow velocity of a fluid element. In order to account for gravitational effects we assume the metric field to be a local degree of freedom, with the restriction in this aspect to torsion-free geometries, so that $g_{\mu\nu} = g_{\nu\mu}$. The relativistic equations for an ideal fluid are obtained
from the divergenceless condition $\nabla_\mu T_{\mu\nu}^{\text{ideal}} = 0$ on the energy-momentum tensor

$$T_{\mu\nu}^{\text{ideal}} = \varepsilon u^\mu u^\nu + p \Delta_{\mu\nu}, \quad (2.1)$$

where $\Delta_{\mu\nu} = g_{\mu\nu} + u^\mu u^\nu$ is the projector onto the hypersurface orthogonal to the velocity $u^\mu$, and we adopt the metric signature $(-, +, +, \ldots, +)$. The energy-momentum tensor of an ideal fluid does not contain derivatives of the local degrees of freedom, and its divergence-free equation $\nabla_\mu T_{\mu\nu}^{\text{ideal}} = 0$ leads to

$$u^\mu \nabla_\mu \varepsilon + (\varepsilon + p) \nabla_\mu u^\mu = 0,$$

$$(\varepsilon + p) u^\mu \nabla_\mu u^\nu + \Delta_{\mu\nu} \nabla_\mu p = 0. \quad (2.2)$$

Alternatively, the last equations for the perfect fluid can be derived from a Lagrangian formulation, as it has been done in Ref. [41], where the Einstein equations sourced by an ideal fluid were also obtained. However, for viscous relativistic fluids, an extreme principle governing the dynamics of the system is still under development (see, for instance, Refs. [42-47]). This is not a problem here, since the construction of the hydrodynamics is done at the level of the energy-momentum tensor, assuming that $\nabla_\mu T_{\mu\nu}^{\text{ideal}} = 0$.

### 2.2 Gradient expansion

The starting point to construct the gradient expansion is the ideal fluid, which has the energy-momentum tensor $T_{\mu\nu}^{\text{ideal}}$ given by (2.1). In the context of a perturbative expansion, the ideal fluid corresponds to the zero-order (unperturbed) system, and the perturbations involving derivatives are responsible by the introduction of dissipative effects. The energy-momentum tensor has its own symmetry properties: it is a divergenceless second-rank symmetric tensor, so that all corrections to (2.1) should preserve these properties.

The gradient expansion corrects $T_{\mu\nu}^{\text{ideal}}$ by terms involving some number of derivatives of the degrees of freedom: first-order corrections involve terms with only one derivative (first-order derivative terms), second-order corrections involve either terms with two derivatives (second-order derivative terms) and/or the product of two terms, each of them containing one derivative (quadratic first-order derivative terms), and so on. Schematically the energy-momentum tensor of the fluid at order $n$ is given by

$$T_{\mu\nu}^{(n)} = T_{\mu\nu}^{\text{ideal}} + \sum_{i=1}^{n} \Pi_{(i)}^{\mu\nu}, \quad (2.3)$$

where each $\Pi_{(i)}^{\mu\nu}$ represents all possible corrections at order $i$ in derivatives of the fundamental variables. The most general form for $\Pi_{(i)}^{\mu\nu}$ can be decomposed into scalar, vector and tensor components as

$$\Pi_{(i)}^{\mu\nu} = \mathcal{E}_{(i)} u^\mu u^\nu + \mathcal{P}_{(i)} \Delta^{\mu\nu} + (q_{(i)}^\mu u^\nu + q_{(i)}^\nu u^\mu) + t_{(i)}^{\mu\nu}, \quad (2.4)$$

where $q_{(i)}^\mu$ are transverse vectors ($u_\mu q_{(i)}^\mu = 0$) and $t_{(i)}^{\mu\nu}$ are transverse, symmetric and traceless.
(TST) tensors\(^1\).

In the Landau frame one identifies the longitudinal projection of the energy-momentum tensor with the energy density, \(u_\mu T^{\mu\nu}_{(i)} = -\varepsilon u^\nu\), and this requires the corrections to be transverse: \(u_\mu \Pi^{\mu\nu}_{(i)} = 0\). Such a choice of frame eliminates the corrections of the energy density \(\varepsilon^{(i)} = 0\), so that the scalar gradients will change only the pressure, and eliminates all vector corrections \(q^{(i)}_{\mu\nu} = 0\). The freedom of frame choice effectively reduces the number of transport coefficients, since one can always choose the Landau frame, which forces half of the scalar and all vector corrections to \(T^{\mu\nu}_{\text{ideal}}\) to vanish. In this section we focus on finding the set of transport coefficients and we will discuss only scalar and tensor structures. Our procedure can also be applied to non-conformal vector structures and we include the list of independent correction terms of vector type in Appendix B.

In order to implement corrections of the ideal fluid dynamics we look for the complete set of admissible terms, which should respect the underlying symmetries of the system. We are interested here in the description of a very general system; in particular, we consider the presence of the gravity field so that fluid dynamics is formulated in a curved background spacetime. The presence of the gravity is introduced in the gradient expansion by using the covariant derivative, e.g., \(\nabla_\mu u^\nu = \partial_\mu u^\nu + \Gamma^\nu_{\mu\sigma} u^\sigma\), where \(\Gamma^\nu_{\mu\sigma}\) stands for the Christoffel coefficients. Here we assume that the background geometry is torsion-free.

The fluid dynamics is characterized by its constitution, thermodynamics, background geometry and flow. We restrict the analysis to uncharged fluids in local thermodynamic equilibrium, which reduces the independent degrees of freedom to be the velocity field \(u^\mu\), the logarithm of the entropy density \(\ln s\), and metric \(g_{\mu\nu}\). Corrections to the ideal fluid are build with gradients of these degrees of freedom. Moreover, zeroth-order equations of motion impose additional relations\(^3\)

\[
D \ln s = -\nabla \cdot u, \quad Du^\mu = -c_s^2 \nabla_\perp \ln s, \tag{2.6}
\]

where \(c_s\) is the speed of sound in the fluid, and we have defined the transverse derivative by \(\nabla_\perp \mu = \Delta_\mu \nu \nabla_\nu\), and the longitudinal (or time) derivative as \(D = u^\mu \nabla_\mu\). The longitudinal derivative of the flow velocity is equivalent to the entropy gradient, and here we choose to use only the transverse gradient \(\nabla_\perp u^\nu\) that is a second-rank tensor and can be decomposed as

\[
\nabla_\perp u^\nu = \frac{1}{2} \sigma^{\mu\nu} + \Omega^{\mu\nu} - \frac{\Theta}{d - 1} \Delta^{\mu\nu}, \tag{2.7}
\]

where \(\sigma^{\mu\nu} = \nabla_\perp (u^\mu u^\nu)\) is the symmetric and traceless shear tensor, \(\Omega^{\mu\nu} = \nabla_\perp u^\nu - \nabla_\perp u^\mu\) is the anti-symmetric vorticity tensor, and \(\Theta = \nabla_\perp \cdot u\) is the scalar expansion. The requirement that velocity field is normalizable, \(u^\mu u_\mu = -1\), provides further identities regarding the

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\(^{1}\)The TST part of a general second-rank tensor \(T^{\mu\nu}\) is given by

\[
T^{(\mu\nu)} = \frac{1}{2} \Delta^{\mu} \Delta^{\nu} (T_{\alpha\beta} + T_{\beta\alpha}) - \frac{1}{d - 1} \Delta^{\mu} \Delta^{\nu} \Delta^{\alpha\beta} T_{\alpha\beta}. \tag{2.5}
\]

\(^{2}\)The energy density \(\varepsilon\) and the pressure \(p\) that appear in the ideal-fluid energy-momentum tensor and the local temperature \(T\) are related to \(\ln s\) by thermodynamic equilibrium equations.

\(^{3}\)These relations are equalities in the sense that their corrections require higher-order gradients.
first-order gradient of the velocity flow: \( u_\mu \nabla_\nu u^\nu = 0 =. \)

The strategy suggested in [14] is to build the corrections (2.4) by acting with the gradient operator on the fundamental degrees of freedom and contracting the resulting quantities systematically with the aim to obtain all the independent terms at the corresponding order in the gradient expansion. At each order one takes the terms coming from differentiating \( \ln s, u^\mu, g_{\mu\nu}, \) contracts in all possible ways, and then uses the equations of motion and other algebraic constraints to eliminate the redundancies. This procedure works fine at first and second order, but for third-order terms it is not easy to rule out redundancies due to the high number of possibilities, what may lead to mistakes. There is no problem in the systematic approach presented by [14], but if one uses it together with the strategy of working with the irreducible gradients as fundamental blocks, instead of the fundamental degrees of freedom, as done, e.g., in Ref. [63], one finds out the complete set of possible corrections in a more direct way. The use of irreducible gradients as fundamental structures seems to be a natural way of performing a gradient expansion since one is in fact looking for the irreducible set of higher-order gradients. In the following we work out the proposed strategy and obtain the complete irreducible set of third-order gradients for non-conformal and conformal hydrodynamics. The obtained results complement those presented in [14] by revealing equivalences between the third-order structures for non-conformal fluids and presenting the full set of third-order scalars and vectors for conformal fluids.

2.3 Revisiting the first- and second-order hydrodynamics

To find the higher-order corrections of hydrodynamics we take the set of irreducible gradients of the fundamental degrees of freedom \( \{ \nabla_\perp^\mu \ln s, \Theta, \Omega^{\mu\nu}, \sigma^{\mu\nu}, R^{\mu\nu}_{\alpha\beta} \} \) to build scalars, vectors and second rank tensors. In such a list we find one first-order scalar, one first-order vector, two first-order tensors of second rank, and one second-order tensor of fourth rank. The first-order vectors do not need to be considered because we are working in the Landau gauge. Moreover, at first order, there is no contribution from curvature, since it is second order in derivatives. The vorticity tensor is anti-symmetric and hence either its trace and its TST part vanish identically. As the vector \( \nabla_\perp^\mu \ln s \) is transverse its projection along \( u^\mu \) vanishes and we cannot make a first-order scalar with it. We have one first-order scalar \( \Theta \) as well as one TST tensor of second rank \( \sigma^{\mu\nu} \) that satisfies all symmetry requirements. Each independent structure we add on the energy-momentum tensor comes with one arbitrary parameter, the transport coefficient, that may depend on the temperature. For the first-order corrections the transport coefficients are the bulk viscosity \( \zeta \) and the shear viscosity \( \eta \), and the first-order energy-momentum tensor reads

\[
\Pi^{\mu\nu}_{(1)} = -\zeta \Theta \Delta^{\mu\nu} - \eta \sigma^{\mu\nu}. \tag{2.8}
\]

First-order hydrodynamics is obtained by the divergenceless of \( T^{\mu\nu}_{(1)} = T^{\mu\nu}_{\text{ideal}} + \Pi^{\mu\nu}_{(1)} \) and is precisely the relativistic version of the Navier-Stokes equation. The second law of thermodynamics imposes additional constraints in the transport coefficients. At first order it requires \( \eta > 0, \zeta > 0. \)
At second order the background curvature, represented by the Riemann tensor, plays an important role. The Riemann tensor manifests itself in the second-order derivatives of tensors. In particular, it is introduced by the commutation of the covariant derivatives of a vector \( \nabla_\mu \nabla_\nu u^\alpha = R^\alpha_{\mu\nu\gamma} u^\gamma \). It establishes that a change in the order of covariant derivatives can be compensated by the addition of the Riemann tensor. Hence, in the task of counting nonequivalent corrections, the order of covariant derivatives is irrelevant\(^4\) and two structures that differ only by the ordering of the derivatives are in fact redundant.

Pursuing the task of building second-order corrections, we now turn attention to the second-order scalars. Firstly one notes that, at first order, we have the scalar \( \Theta \) so that its square \( \Theta^2 \) will be second-order scalars. We can also square the first-order vector and the first-order tensors by obtaining \((\nabla_\perp \ln s)^2 = \nabla_\perp^\mu \ln s \nabla_\perp^\mu \ln s\).\(^\text{2nd}\) \(\sigma^2 = \sigma^{\mu\nu} \sigma_{\mu\nu}\) and \(\Omega^2 = \Omega^{\mu\nu} \Omega_{\mu\nu}\). Moreover, one has also to consider the divergence of the first-order vector \(\nabla^\mu \nabla_\perp^\mu \ln s\). Notice, however, that it can be replaced by the remaining structures through the use of Eq. (2.7). Due to the symmetries of the Riemann tensor under index permutations, there are only two nonequivalent scalars we can build from it, namely, \(R = g_{\mu\nu} R^{\mu\nu}\) and \(u^\mu u^\nu R_{\mu\nu}\), where \(R_{\mu\nu}\) is the Ricci tensor. The list of independent second-order scalars is given by

\[
\begin{align*}
S_1^{2\text{nd}} &= \sigma^2, \\
S_2^{2\text{nd}} &= \Theta^2, \\
S_3^{2\text{nd}} &= \Omega^2, \\
S_4^{2\text{nd}} &= (\nabla_\perp \ln s)^2, \\
S_5^{2\text{nd}} &= D\Theta, \\
S_6^{2\text{nd}} &= R, \\
S_7^{2\text{nd}} &= u^\mu u^\nu R_{\mu\nu}.
\end{align*}
\] (2.9)

In order to find the second-order tensors, we note that \(\sigma^{\mu\nu}\) is a first-order TST tensor and, hence, \(\Theta \sigma^{\mu\nu}\) and \(D\sigma^{(\mu\nu)}\) are second-order TST tensors. Moreover, the symmetric products of two first-order tensors such as \(\sigma \sigma\), \(\sigma \Omega\) and \(\Omega \Omega\) are also second-order tensors. As the Riemann tensor is a second-order correction, its projections and contractions are also second-order corrections and, taking into account its symmetry properties, it results only in two independent structures corresponding to the Ricci and the Riemann tensors projected along the flow. Collecting all the independent second-order tensors we get the following list:

\[
\begin{align*}
T_1^{2\text{nd}} &= \sigma^{(\mu \sigma \nu)} \alpha, \\
T_2^{2\text{nd}} &= \sigma^{(\mu \Omega \nu)} \alpha, \\
T_3^{2\text{nd}} &= \Omega^{(\mu \Omega \nu)} \alpha, \\
T_4^{2\text{nd}} &= \nabla_\perp^{(\mu} \ln s \nabla_\perp^{\nu)} \ln s, \\
T_5^{2\text{nd}} &= \Theta \sigma^{\mu\nu}, \\
T_6^{2\text{nd}} &= D\sigma^{(\mu\nu)}, \\
T_7^{2\text{nd}} &= u_\alpha u_\beta R^{\alpha(\mu\nu)} \beta, \\
T_8^{2\text{nd}} &= R^{(\mu\nu)},
\end{align*}
\] (2.10)

where the tensor indexes on left hand side of the equations were omitted.

With all scalar and tensor correction terms at hand, we can then write down the most general second-order correction to the energy momentum-tensor. There are 15 transport coefficients that we label as \(\xi_\alpha\) for the scalar and \(\lambda_b\) for tensor corrections, resulting in

\[
\Pi^{\mu\nu}_{(2)} = \sum_{a=1}^{7} \xi_\alpha S_\alpha^{2\text{nd}} \Delta^{\mu\nu} + \sum_{b=1}^{8} \lambda_b \left( T_b^{2\text{nd}} \right)^{\mu\nu}.
\] (2.11)

\(^4\)The argument presented here for vector fields also holds for any tensor structure; the difference for an \((r, s)\) rank tensor is that one needs to add \((r + s)\) terms of the Riemann tensor to compensate each permutation of two covariant derivatives.
The structures just found agree with those presented in [13], the only difference being that we use $\Theta$ instead of $\nabla \cdot u$. The labeling we adopt here for the transport coefficients is related to that employed in [13] according to the relations $\xi_5 = \zeta \tau_{\Pi}$, $\lambda_6 = \eta \tau_{\pi}$, recovering the relaxation times in the classical literature of relativistic hydrodynamics $\tau_{\Pi}$ and $\tau_{\pi}$, and also $\lambda_7 = (\tau_{\pi} + \tau_{\Pi}^\dagger)/(d - 1)$, $\lambda_7 = 2(\kappa - \kappa^*)$, and $\lambda_8 = \kappa$, while the remaining coefficients perfectly coincide with the notation employed in [13].

2.4 The third-order hydrodynamics

Now we use the structures defined in the previous section to find the third-order corrections to the energy-momentum tensor of a non-perfect uncharged fluid. The idea is that, once we have the list of first- and second-order structures, we should use it to find the third-order ones. There are two direct ways to build third-order terms: to take gradients of first- and second-order structures, or to multiply one first-order by one second-order structure.

In order to build scalars by multiplication, we can take the product of two scalars, contract two vectors, or contract a tensor with two vectors. On the other hand, building scalars by differentiating second-order structures one can take the divergence of second-order vectors or total derivatives of second-order scalars. These two processes would furnish many equivalent structures, and so a careful study is demanded. In fact, at third order the geometrical identities for curvature derivatives and the Einstein field equations play an important role. For instance, the quantity $u_\mu \nabla_\nu R^{\mu\nu}$ is proportional to $u^\mu \nabla_\mu R$ due to the Einstein equations. Algebraic relations like the anti-symmetry of the vorticity tensor also generates redundancies, eliminating from the list, for example, the scalar and the tensorial structures coming from $\Omega^3$. After a detailed and careful analysis, we find the irreducible set of third-order scalars to be

\begin{align}
S_1^{3rd} &= \nabla_\perp \Theta, \\
S_2^{3rd} &= \Theta \nabla_\perp \ln s, \\
S_3^{3rd} &= \Theta \nabla_\perp \ln s, \\
S_4^{3rd} &= \sigma^{\mu\nu} \nabla_\perp \ln s \nabla_\perp \ln s, \\
S_5^{3rd} &= \Omega^{\mu\nu} \nabla_\perp \ln s \nabla_\perp \ln s, \\
S_6^{3rd} &= \Theta (\nabla_\perp \ln s)^2, \\
S_7^{3rd} &= \Theta \Omega^2, \\
S_8^{3rd} &= \Theta \sigma^2, \\
S_9^{3rd} &= \Theta^3, \\
S_{10}^{3rd} &= \sigma_{\mu\nu} \Omega^{\mu\eta} \Omega^{\nu}_\eta, \\
S_{11}^{3rd} &= DR, \\
S_{12}^{3rd} &= u^\mu R_{\mu\nu}, \\
S_{13}^{3rd} &= \Theta R, \\
S_{14}^{3rd} &= \Theta^2 R, \\
S_{15}^{3rd} &= u^\mu u^\nu DR_{\mu\nu}, \\
S_{16}^{3rd} &= u^\mu u^\nu R_{\mu\nu}, \\
S_{17}^{3rd} &= u^\mu u^\nu \sigma^{\alpha\beta} R_{\mu\nu\alpha\beta}, \\
S_{18}^{3rd} &= R_{\mu\nu} \sigma^{\mu\nu}, \\
S_{19}^{3rd} &= \Theta u_\mu u^\nu R_{\mu\nu}.
\end{align}

The list obtained here differs from that presented in [14] where there are 23 third-order scalars. In particular the structures $\{\nabla_\perp \nabla_\perp \nabla_\perp \nabla_\perp \nabla_\perp u^\nu, \nabla_\perp \nabla_\perp \nabla_\perp \nabla_\perp \nabla_\perp u^\nu, \nabla_\perp \nabla_\perp \nabla_\perp \nabla_\perp \nabla_\perp u^\nu, \nabla_\perp \nabla_\perp \nabla_\perp \nabla_\perp \nabla_\perp u^\nu\}$\footnote{Notice that in [14] the authors use lower case Latin index to label spacetime components of a tensor.} are treated as independent structures in [14] but we note that they differ only by the ordering of successive covariant derivatives. The same happens for the structures $\{\nabla_\perp \nabla_\perp \nabla_\perp \nabla_\perp \nabla_\perp u^\nu, \nabla_\perp \nabla_\perp \nabla_\perp \nabla_\perp \nabla_\perp u^\nu, \nabla_\perp \nabla_\perp \nabla_\perp \nabla_\perp \nabla_\perp u^\nu\}$. Then we conclude that there are only two independent scalars from

this set of five, eliminating 3 transport coefficients and resulting in a reduced list with only 20 scalars.

The tensor structures form a larger list than the scalar structures, since there are many ways to “arrange symmetrically” two-rank tensors involving three derivatives of the fundamental fields. One can take direct product of one second-order scalar by $\sigma^{\mu\nu}$, multiply a second-order tensor by $\Theta$, take scalar derivatives of second-order tensors, or symmetric derivatives of second-order vectors, and also combine in a TST way one first-order vector with one second-order vector. After eliminating the equivalent terms, we present below the list of independent third-order tensor structures by omitting the indexes on the left side:

\[
\begin{align*}
T^{3rd}_1 &= \Omega^2 \sigma^{\mu\nu}, \\
T^{3rd}_4 &= (D\Theta) \sigma^{\mu\nu}, \\
T^{3rd}_7 &= \Theta \sigma_\eta^{(\mu\nu)\eta}, \\
T^{3rd}_{10} &= \Omega_\eta^{(\mu\nu)\alpha} \sigma_\eta^{\alpha}, \\
T^{3rd}_{13} &= \nabla^2 \sigma^{(\mu\nu)}, \\
T^{3rd}_{16} &= \Theta \nabla_\perp(\mu \nabla_\perp s) \nabla_\perp ln s, \\
T^{3rd}_{19} &= \sigma_\alpha^{(\mu \nabla_\perp s) \nabla_\perp ln s}, \\
T^{3rd}_{22} &= \nabla_\perp \Omega^{(\mu\nu)} \nabla_\perp \alpha ln s, \\
T^{3rd}_{25} &= R\sigma^{\mu\nu}, \\
T^{3rd}_{28} &= u^\gamma u^\alpha DR_\gamma^{(\mu\nu)\alpha}, \\
T^{3rd}_{31} &= u^\gamma (\nabla_\perp ln s) R_\gamma^{(\mu\nu)\alpha}, \\
T^{3rd}_{34} &= u^\gamma u^\alpha \Omega_\beta^{(\mu R^{\rho\gamma})\gamma}\beta, \\
T^{3rd}_{37} &= \Theta R^{(\mu\nu)}, \\
T^{3rd}_{40} &= \Theta^{(\mu R^{\rho\gamma})\gamma}, \\
T^{3rd}_{43} &= \Theta^{(\mu\nu)}, \\
T^{3rd}_{46} &= \Theta \sigma_\eta^{(\mu\nu)\eta}, \\
T^{3rd}_{49} &= \sigma_\eta^{(\mu\nu)\alpha} \sigma_\eta^{\alpha}, \\
T^{3rd}_{52} &= \Omega_\eta^{(\mu\nu)\alpha} \Omega_\eta^{\alpha}, \\
T^{3rd}_{55} &= \Theta \nabla_\perp (\mu \nabla_\perp s) \nabla_\perp ln s, \\
T^{3rd}_{58} &= \Omega_\alpha^{(\mu \nabla_\perp s) \nabla_\perp \alpha ln s}, \\
T^{3rd}_{61} &= \nabla_\perp \sigma_\alpha^{(\mu \nabla_\perp s) \nabla_\perp s}, \\
T^{3rd}_{64} &= u^\gamma R_\gamma^{(\mu\nu)\alpha}, \\
T^{3rd}_{67} &= u^\gamma u^\alpha \sigma_\beta^{(\mu\nu)\beta}, \\
T^{3rd}_{70} &= u^\gamma R_\gamma^{(\mu\nu)\alpha}, \\
T^{3rd}_{73} &= u^\gamma u^\alpha \sigma_\beta^{(\mu\nu)\beta}, \\
T^{3rd}_{76} &= u^\gamma R_\gamma^{(\mu\nu)\alpha}, \\
T^{3rd}_{79} &= \Omega_\eta^{(\mu\nu)\alpha} \Omega_\eta^{\alpha}.
\end{align*}
\]

This list of independent third-order tensor structures is reduced by 6 structures when compared to the previous tensors obtained in Ref. [14]. The reason for such a difference is the same as we pointed out previously for third-order scalars. To be explicit, the structures in each one of the sets of tensors \{\nabla_\perp \nabla_\perp \nabla_\perp (\mu u^\nu), \nabla_\perp \nabla_\perp \nabla_\perp (\mu \nabla_\perp s) \nabla_\perp ln s, \nabla_\perp \nabla_\perp \nabla_\perp (\mu \nabla_\perp \nabla_\perp u^\alpha), \nabla_\perp \nabla_\perp \nabla_\perp (\mu \nabla_\perp \nabla_\perp u^\alpha)\}, \{\nabla_\perp \nabla_\perp \nabla_\perp (\mu u^\nu), \nabla_\perp \nabla_\perp \nabla_\perp (\mu \nabla_\perp s) \nabla_\perp ln s, \nabla_\perp \nabla_\perp \nabla_\perp (\mu \nabla_\perp \nabla_\perp u^\alpha), \nabla_\perp \nabla_\perp \nabla_\perp (\mu \nabla_\perp \nabla_\perp u^\alpha)\} differ only by the ordering of covariant derivatives and hence six of them are redundant in the gradient and can be removed from the list.

Therefore, the general third-order corrections to the energy-momentum tensor come with 59 = 20 + 39 transport coefficients, that we label as $\chi_a$ for the scalars and as $\gamma_b$ for tensors, and the third-order contribution to the energy-momentum tensor may be represented.

\footnote{It is important to remark that although we work in Landau frame it is useful to have vector structures at hand in order to find the higher-order scalars and tensors. The vectors are presented in Appendix B.}
in the form
\[ \Pi^{\mu\nu}_{(3)} = \sum_{a=1}^{20} \chi_a S^{3rd}_a \Delta^{\mu\nu} + \sum_{b=1}^{39} \gamma_b \left( T^{3rd}_b \right)^{\mu\nu}. \]  
(2.14)

The reduction of the number of scalar and tensor corrections means a simplification of the higher-order hydrodynamics that is very welcome. The results presented here provide a reduction of 9 transport coefficients from the previous description of the third-order hydrodynamics for a non-conformal system.

3 Relativistic hydrodynamics of conformal fluids

3.1 Conformal covariance

Conformal symmetry is associated with the light-like particles in relativistic dynamics, it is the light-cone symmetry. A fluid built up from massive particles can approach conformal symmetry when kinetic energy is very large in comparison to other energy content of each fluid component. Such a situation is realized, for instance, in QGP formed in heavy ion collision. Now the invariance of the hydrodynamic system under conformal, or Weyl, scaling should be taken into account in order to build up correctly the respective gradient expansion.\(^{\text{7}}\) The energy-momentum tensor \( T^{\mu\nu} \) of a system that is invariant under a Weyl scaling \( g^{\mu\nu} \rightarrow e^{2\phi(x)} g^{\mu\nu} \) should transform as the tensor density, 
\[ T^{\mu\nu} \rightarrow e^{-(d-2)\phi(x)} T^{\mu\nu}. \]
Moreover, the energy-momentum tensor of a conformal theory should be traceless [12]. This implies that scalar corrections to the pressure of a conformal fluid vanishes, eliminating all transport coefficients coming from higher-order scalars. Since conformal scalars are absent in the gradient expansion we consider such structures separately in Appendix B.

The program of finding the hydrodynamic expansion for conformal fluids at third order is considered in [14] where the authors establish an approach to build admissible structures for the energy-momentum tensor. Despite their approach presents some positive features, problems arise in a higher-order expansion. The strategy adopted by the authors to find the higher-order structures is to take the list of all non-conformal structures, considering for each one its behaviour under conformal scaling, and then finding linear combinations in such a way that inhomogeneous terms are eliminated and the final structure is conformally covariant. The strategy works fine at first and second orders but the work becomes very hard at third order. For third-order gradients there is an accumulation of inhomogeneous terms when they are submitted to a Weyl scaling and to find the linear combinations that eliminate all of such terms is not an easy task. Alternatively, here we build the gradient expansion by using structures that are, by construction, covariant under symmetry transformations. In the same way as the partial derivative is corrected by introducing the Christofell connection terms to obtain covariant structures under diffeomorphism transformations, the covariant derivative needs to be corrected to obtain gradients that are covariant under Weyl scaling too. Namely, we define the Weyl-covariant derivative acting

\(^{7}\text{Here we treat Weyl symmetry and conformal symmetry on the same foot even though there are subtle differences between them. A discussion on this subject can be found in Refs. [71–73].}\)
in the fundamental fields in such a way to preserve their character of tensor density under Weyl scaling.

In the context of relativistic hydrodynamics the Weyl-covariant derivative was introduced in [62] using a vector connection. It was recently shown in [64] that the formulation of the Weyl covariance by a minimal coupling mechanism is in fact well defined. In such an approach the scaling factor of a fundamental field plays the role of the gauge charge associated with the symmetry under local Weyl scaling. The minimal coupling for Weyl symmetry works as follows. Let \( \psi \) be a tensor density of weight \( \omega \), we minimally couple it with Weyl connection \( A_\mu \) by replacing \( \partial_\mu \psi \) by \( (\partial_\mu + \omega A_\mu)\psi \) so that under conformal scaling it transforms as \( (\partial_\mu + \omega A_\mu)\psi \rightarrow e^{-\omega \phi} (\partial_\mu + \omega A_\mu)\psi \). The minimal coupling prescription is well defined for any composition of derivatives and is a direct mechanism to construct high order gradients that are Weyl covariant. To implement Weyl covariance in this way we need a vector field \( A_\mu \) that transforms as a connection under Weyl scaling, i.e., \( A_\mu \rightarrow A_\mu + \partial_\mu \phi \).

It was noted in [62] that, in hydrodynamics, the combination of first-order gradients

\[
A_\mu = -\frac{1}{d-1}(\nabla \ln s + \Theta u_\mu)
\]  

transforms in the mentioned form, i.e., transforms as a connection under Weyl scaling. The presence of a gauge connection for the Weyl symmetry is a necessary and sufficient condition to ensure that the minimal coupling prescription fulfills Weyl covariance. In order to build up the gradient expansion, we use only Weyl-covariant derivatives of the fundamental fields. These relations are discussed in detail in [62], and many equivalences obtained in that work are used here to rule out redundant corrections in the energy-momentum tensor of the conformal fluid. In the following the Weyl-covariant derivative is denoted by \( D_\mu \).

It is remarkable that the shear and vorticity tensors are naturally Weyl-covariant objects and can be defined as \( \sigma_{\mu\nu} = D_\mu u_\nu + D_\nu u_\mu \) and \( \Omega_{\mu\nu} = D_\mu u_\nu - D_\nu u_\mu \). However, neither the expansion \( \Theta \) nor the entropy gradient \( \nabla \ln s \) are Weyl covariant structures, but they combine to form the gauge connection shown in eq. (3.1). A connection is in fact not covariant, but it gives rise to a covariant field tensor \( F \) defined by its exterior derivative,

\[
F = dA = F_{\mu \nu} dx^\mu \wedge dx^\nu,
\quad F_{\mu \nu} = \partial_\mu A_\nu - \partial_\nu A_\mu.
\]  

The usual curvature tensors related to the Riemann tensor are not invariant under conformal transformations and, as pointed out in [64], there are two ways to deal with this situation. One can take combinations of the Riemann tensor and its contractions by building the Weyl tensor \( C_{\mu \nu \alpha \beta} \), or one can couple the metric to the Weyl connection through the minimal coupling prescription by obtaining the conformal Riemann tensor

\[
R_{\mu \nu \alpha \beta} = \mathcal{R}_{\mu \nu} g_{\alpha \beta}^* + \frac{1}{d-2} \delta_{[\mu} g_{\nu][\gamma \delta]}^* \left( \mathcal{R}_{\alpha \lambda} - \frac{1}{2(d-1)} \mathcal{R} g_{\alpha \lambda} \right) + F_{\mu \nu} g_{\alpha \beta}.
\]  

*The Weyl tensor can be obtained as a combination of the conformal Riemann (\( \mathcal{R} \)) and the Weyl curvature (\( \mathcal{F} \)),

\[
C_{\mu \nu \alpha \beta} = \mathcal{R}_{\mu \nu \alpha \beta} + \frac{1}{d-2} \delta_{[\mu} g_{\nu][\gamma \delta]}^* \left( \mathcal{R}_{\alpha \lambda} - \frac{1}{2(d-1)} \mathcal{R} g_{\alpha \lambda} \right) + F_{\mu \nu} g_{\alpha \beta}.
\]
Ref. [62], and then we may directly use the identities presented in that work. Therefore, the set of irreducible gradients we have at hand to define the gradient expansion for a conformal fluid is \( \{ \sigma^{\mu\nu}, \Omega^{\mu\nu}, F^{\mu\nu}, R^{\mu\nu\eta\sigma} \} \). Note that \( F \) is anti-symmetric and second order in derivatives. Due to its anti-symmetry it will not appear in the gradient expansion at second order and it will appear at first time in the third-order corrections for the conformal fluid. Two first-order terms \( \{ \Theta, \nabla^\mu \ln s \} \) allowed in the non-conformal case are now forbidden.

These two structures together are directly responsible for \( 1 + 0 \) transport coefficients at first order, \( 2 + 5 \) at second order and \( 12 + 21 \) at third order. This is the main reason why the gradient expansion of a conformal fluid is strongly simplified in comparison with the case of a non-conformal fluid.

### 3.2 The first- and second-order conformal hydrodynamics

Conformal symmetry requires the energy-momentum tensor to be traceless so that the pressure of the conformal fluid is constrained to be proportional to the energy density, \( p(\epsilon) = \epsilon/(d - 1) \) and the scalar corrections vanish \( (P_i = 0) \) in the Landau frame. Hence the ideal energy-momentum tensor of a conformal fluid may be cast into the form

\[
T_{\mu\nu}^{\text{ideal}} = \epsilon u^\mu u^\nu + \frac{\epsilon}{d - 1} \Delta^{\mu\nu}.
\]  

Conformal symmetry also changes the way in which the equations of motion are written in terms of the energy-momentum tensor, since the usual covariant derivative \( \nabla_\mu \) must be replaced by the Weyl-covariant derivative \( \mathcal{D}_\mu \) mentioned in the last section. The equations of motion of the conformal hydrodynamics are then \( \mathcal{D}_\mu T^{\mu\nu} = 0 \). In view of the form of the Weyl connection (3.1), it follows that \( \mathcal{D}_\mu u^\mu = 0 \), and the zeroth-order equations of motion for conformal fluids give us \( \mathcal{D}^\mu \epsilon = 0 \). As a consequence, all the higher-order energy gradients also vanish and can be excluded from the gradient expansion for a conformal fluid [62]. At first order, the gradient expansion becomes trivial since there is only one first-order structure allowed, \( \sigma^{\mu\nu} \), with one associated transport coefficient, \( \eta \), and so at this order the correction for the energy-momentum tensor is just

\[
\Pi_{(1)}^{\mu\nu} = -\eta \sigma^{\mu\nu}.
\]  

At second order there are more possibilities, but not so much as in comparison with the non-conformal case. To build the second-order tensors we can take symmetric derivatives of first-order structures, in particular we can take longitudinal derivatives \( u^\mu \mathcal{D}_\mu \), as well as symmetric products of first-order structures. Accordingly, the set of allowed structures is given by \( \{ \sigma_\alpha^{(\mu} \sigma^{\nu)}\alpha, \sigma_\alpha^{(\mu} \Omega^{\nu)\alpha}, \sigma_\alpha^{(\mu} \Omega^{\nu)\alpha}, u^\alpha \mathcal{D}_\alpha \sigma^{(\mu\nu)}, u^\alpha \mathcal{D}_\alpha \Omega^{(\mu\nu)}, u^\alpha u^\beta \mathcal{R}_\alpha^{(\mu\nu)}, \mathcal{R}^{(\mu\nu)} \} \). Notice, however, that not all of these elements are relevant. In fact, due to the anti-symmetry of the vorticity \( \Omega^{\mu\nu} \), we have identically that \( u^\alpha \mathcal{D}_\alpha \Omega^{(\mu\nu)} = 0 \). Algebraic identities allow us to express \( u^\alpha u^\beta \mathcal{R}_\alpha^{(\mu\nu)} \) as a linear combination of \( \sigma_\alpha^{(\mu} \sigma^{\nu)\alpha}, \Omega_\alpha^{(\mu} \Omega^{\nu)\alpha} \) and \( \mathcal{R}^{(\mu\nu)} \).
Using such relations we obtain only five independent second-order tensors,

\[
\begin{align*}
T^{2nd}_1 &= \sigma^\alpha_{(\mu} \langle \sigma^{\nu)}\rangle^\alpha, & T^{2nd}_2 &= \Omega^\alpha_{(\mu} \langle \Omega^{\nu)}\rangle^\alpha, & T^{2nd}_3 &= \sigma^\alpha_{(\mu} \Omega^{\nu)}\rangle^\alpha, & T^{2nd}_4 &= u^\alpha D_\alpha \sigma^{(\mu\nu)}, & T^{2nd}_5 &= R^{(\mu\nu)},
\end{align*}
\]

(3.5)

where again we have omitted the tensor indexes on the left hand side of the equations. At last, using the above notation, the second-order corrections to the energy-momentum tensor of a conformal fluid may be written as

\[
\Pi^{\mu\nu}_{(2)} = \sum_{a=1}^{5} v_a \left( T^{2nd}_a \right)^{\mu\nu},
\]

(3.6)

where the necessity of only five transport coefficients is apparent.

The last result showing only five second-order independent correction terms for a conformal fluid, requiring only 5 additional transport coefficients, is in complete agreement with the present literature. The manifestation of conformal symmetry indicates that the speeds involved are close to the speed of light, so that relativistic effects are dominant and we must take seriously the causality issue. We know that truncating the hydrodynamic expansion at first order one faces the problem of instantaneous propagation of sound [69]. Therefore, one needs to go at least up to second order in gradient expansion to find a consistent description of conformal fluids, and this requires in general the introduction of 6 transport coefficients, one at first order and five at second order.

3.3 The third-order conformal hydrodynamics

As commented above for the first- and second-order conformal hydrodynamics, the relevant independent corrections to \( T^{\mu\nu}_{\text{ideal}} \) at third order in the gradient expansion are also two-rank tensorial structures. However, for a question of completeness, the sets of independent third-order conformal scalars and vectors, which do not appear in previous works, are presented in Appendix B.

In order to find the third-order tensors we can perform symmetric products of first- and second-order gradients, and take symmetric derivatives of second-order structures. The third-order corrections for conformal fluids may be obtained in the same way as the third-order corrections for the non-conformal fluids, the difference between the two cases is the set of building blocks - covariant gradients - and the algebraic identities they satisfy in each case.

Considering the transversality of \( \sigma^{\mu\nu} \) and \( \Omega^{\mu\nu} \), one can show that \( u_\alpha D_\beta \left( \sigma^{\beta(\mu} \sigma^{\nu)}\right)^\alpha = -\frac{1}{2} \sigma^{\alpha(\mu} \sigma^{\nu)}\beta \) and \( u_\alpha D_\beta \left( \Omega^{\beta(\mu} \Omega^{\nu)}\right)^\alpha = -\Omega^{\alpha(\mu} \Omega^{\nu)}\beta \). Now the tensor \( \Omega_{\alpha\beta} \Omega^{\alpha(\mu} \Omega^{\nu)}\beta \) vanishes identically due to the anti-symmetric property of the vorticity. We can also remove from the list one tensor out of \( D_\alpha D^{\mu\nu} \), \( D_\alpha D^{\mu(\nu} \), and \( \Delta^{\alpha\beta} D_\alpha D_\beta \sigma^{(\mu\nu)} \), since the sum of the first two differs from the latter essentially by the order of the derivatives. The tensor \( \Omega_{\alpha\beta} \mathcal{R}^{(\mu\nu)}_{\alpha\beta} \) appears as a candidate for the list of independent structures but it also vanishes identically. We then find only 19 completely independent third-order conformally covariant tensors, which are given by
By labelling the third-order transport coefficients as \( \vartheta_b \), we finally obtain the complete third-order correction to the energy-momentum tensor of a conformal fluid in a closed form,

\[
\Pi^{\mu\nu}_{(3)} = \sum_{b=1}^{19} \vartheta_b \left( \Sigma_b^{3rd} \right)^{\mu\nu}.
\]

(3.8)

Considering that the generalization of the Navier-Stokes equation for a conformal fluid is given by the conformal (Weyl)-covariant divergence of its energy-momentum tensor, we then obtain the equations of motion for a conformal fluid up to third order in the gradient expansion by

\[
D_\mu \left( T_{\text{ideal}}^{\mu\nu} + \Pi^{\mu\nu}_{(1)} + \Pi^{\mu\nu}_{(2)} + \Pi^{\mu\nu}_{(3)} \right) = 0.
\]

(3.9)

The list of independent third-order tensor perturbations, that is found here to be 19, fixes the number of additional transport coefficients in conformal hydrodynamics. It is a dramatic reduction in comparison with the non-conformal hydrodynamics, where 59 third-order transport coefficients are needed, and so the constraints coming from the conformal symmetry eliminates 40 of them. We have found here only 19 independent tensors and it differs from the previous results of Ref. [14] which presents 20 tensors. The reduction of such a number by unity shows that there exists a non-trivial linear combination of the 20 previously known tensors that vanishes identically.

We call attention to the necessity of minimizing the redundancies when dealing with higher-order terms, which is a difficult task since the number of possibilities grows up exponentially for a higher-order expansion. In the particular case of conformal symmetry, the use of conformally covariant derivatives is essentially necessary, in the very same way one needs to implement the usual covariant derivative when considering a fluid living in a curved space-time. The way we proceed here differs from what was previously done in order to find the third-order tensors for conformal fluids in [14] exactly at this point. There the authors first list all non-conformal structures and then look for the linear combinations that transform covariantly under Weyl scaling. In this sense the results we present in this and in the previous sections do not contradict the results of [14], but rather complement them by improving the systematic methodology introduced there, by reducing the number of transport coefficients at third order in non-conformal and conformal hydrodynamics, and by allowing us to obtain a complete list of independent conformal scalars and vectors up to third order.
3.4 Comments on phenomenology

Even though hydrodynamics may be seen as an effective description of the collective effects of fundamental interactions, it does not deal with the interactions at all, in practice it deals with the symmetry of the interactions we expect to manifest in the macroscopic dynamics. We build up a gradient expansion for the energy-momentum tensor including all possible corrections for each order of derivatives and each term that enter as a correction comes with a free parameter, the transport coefficient. The equations of motion and other algebraic relations reveal linear dependencies between the possible corrections. When this is the case we can write one correction as a linear combination of the others and the associated transport coefficient is eliminated from the expansion. However, this does not mean that the transport coefficient vanishes; the list of independent transport coefficients is reduced by appropriately defining a new transport coefficient as a linear combination of the old ones. For example, in Ref. [67], the kinetic theory is used to compute the equations of motion for a conformal fluid including the contributions of third-order gradients and 14 different third-order tensors appear in the equations of motion, although there are only two transport coefficients ($\tau_\pi, \beta_\pi$). We find here 13 transport coefficients associated with the set of independent third-order conformal tensors in flat space. Theoretical consistence of both approaches is ensured if one can reproduce the results of the kinetic theory for some particular choice of transport coefficients. We expect that it can be done, but it is not a simple task and will not be developed here.

On the other hand, the absence of scalar perturbations in the energy-momentum tensor of a conformal fluid (due to the vanishing of its trace) has a very direct consequence. The non-vanishing of any transport coefficient associated with a scalar correction at any order of the gradient expansion implies that the system is not conformally invariant. Therefore, the presence of a non-vanishing scalar at a given order of the gradient expansion is enough to report the breaking of conformal symmetry at that order. It means that even the fluid looking conformal, for instance, at second-order hydrodynamics, it can be verified to be non-conformal when submitted to a third-order analysis.

4 Dispersion relations

4.1 The general approach

The dispersion relations of waves propagating in a fluid are obtained by considering the equations of motion for small perturbations in momentum space. Such equations may be obtained by applying the standard techniques of linear perturbation theory to the set of hydrodynamic equations for the fluid, these being obtained from the gradient expansion developed in the previous sections. At a given order $n$ in gradient expansion, the equations of motion for the fluid read $\nabla_\mu T^{\mu\nu}_{(n)} = 0$, where $T^{\mu\nu}_{(n)}$ is the energy-momentum tensor containing up to $n$ derivatives. This is a vector equation and can be locally projected along the flow $u_\mu$ as $u_\nu \nabla_\mu T^{\mu\nu}_{(n)} = 0$, as well as perpendicularly to the flow as $\Delta^\alpha_\nu \nabla_\mu T^{\mu\nu}_{(n)} = 0$. The perturbations are then small deviations from a fixed configuration that corresponds to a solution of the equations of motion. Here we assume that spacetime is flat and analyze
perturbations of a static configuration, where both the velocity and the entropy are constant throughout the system, \(u^\mu(x) = u^\mu_0\) and \(\ln s(x) = \ln s_0\). In the perturbed configuration the degrees of freedom read

\[
u^\mu(x) = u^\mu_0 + \delta u^\mu(x), \quad \ln s(x) = \ln s_0 + \delta \ln s(x).
\]

(4.1)

where the \(\delta\) symbol indicates small quantities. We now insert the expressions shown in Eq. (4.1) into the equations of motion for the fluid and look for the linear terms in \(\delta u\) and \(\delta \ln s\). The resulting linearized equations describe the propagation of waves in the fluid.

To work in the momentum space, we Fourier transform the fluctuations

\[
\delta u(x) = \int d^d x e^{ik\mu x^\mu} \delta u(k), \quad \delta \ln s(x) = \int d^d x e^{ik\mu x^\mu} \delta \ln s(k).
\]

(4.2)

As known from the linear perturbation theory in flat spacetime, the set of differential equations in the configuration space translates into a set of algebraic equations for the fields \(\delta u(k), \delta \ln s(k)\) in the corresponding Fourier space, since the spacetime derivatives are replaced by the wavevector as \(\partial_\mu \rightarrow ik_\mu\). The solutions of such equations furnish the dispersion relations. Notice that a term of the energy-momentum tensor with \(n\) spacetime derivatives, or with spacetime derivatives of order \(n\), results in a power \(k^{n+1}\) in the algebraic equations of motion for the perturbations in the Fourier space. Hence a \(n\)-th order hydrodynamics provides an approximation up to power \(n + 1\) in the dispersion relations.

The perturbation equations may be conveniently projected along the flow and perpendicularly to the flow, since each projection of the fluid equations plays a different role. For we introduce here the wavevector projections

\[
k_\parallel = k_\mu u^\mu, \quad k_\perp = \Delta_{\mu\nu} k^\nu,
\]

(4.3)

that projects respectively along the flow and transverse to the flow.

The longitudinal projection of the equations of motion reads

\[
u^\mu \nabla_\mu \ln s + \Theta + (\nabla_\mu u_\nu) \Pi^{\mu\nu}_{(n)} = 0,
\]

but linearization rules out the last term. In fact, the products and powers of derivatives like \(\partial u \partial \ln s\), \((\partial u)^2\), etc., are higher order in the amplitudes and so are ruled out by linearization, which selects only the terms with successive derivatives of the same quantity such as \(\partial^2 u, \partial^2 \ln s\). Hence, independently of the gradient-expansion order, the longitudinal equation of motion gives

\[
u^\mu \partial_\mu (\delta \ln s) + \Delta^{\mu}_{\nu} (\partial_\mu \delta u^\nu) = 0.
\]

(4.4)

In terms of the velocity perturbations, the last differential equation gives the entropy perturbation

\[
\delta \ln s = -\frac{1}{k_\parallel} k_\perp \delta u_\mu,
\]

(4.5)

so that the longitudinal equation of motion can be used to eliminate \(\delta \ln s\) in terms of \(\delta u_\mu\).

The transverse projection of the equations of motion is strongly dependent on the order
of the gradient expansion, its linearization yields

\[ u^\nu \partial_\nu (\delta u^\mu) + c_s^2 \Delta^{\mu\nu} \partial_\nu (\delta \ln s) + \frac{1}{\epsilon + p} \Delta^{\mu\nu} \partial_\alpha \left( \sum_{i=1}^{n} \delta \Pi^{\nu\alpha}_{(i)} \right) = 0, \]  

(4.6)

where \( \delta \Pi^{\mu\nu}_{(i)} \) is the linear part of the energy-momentum tensor correction at order \( i \). In order to find out the dispersion relations, we need to express \( \partial_\alpha \delta \Pi^{\nu\alpha}_{(i)} \) in the momentum space and to linearize the expressions for \( \Pi^{\mu\nu}_{(i)} \) that we found in the previous sections. At first order we have

\[ \delta \Pi^{\mu\nu}_{(1)} = -\zeta \Delta^{\mu\nu} \delta \Theta - \eta \delta \sigma^{\mu\nu}, \]  

(4.7)

where the expressions for \( \delta \Theta \) and \( \delta \sigma^{\mu\nu} \) are given respectively by

\[ \delta \Theta = i k_\perp^\mu \delta u_\mu, \quad \delta \sigma^{\mu\nu} = i(k_\perp^\mu \delta u_\nu + k_\perp^\nu \delta u_\mu) - i \frac{2}{(d-1)} \Delta^{\mu\nu} k_\perp^\alpha \delta u_\alpha. \]  

(4.8)

Inserting expressions (4.7) and (4.8) into Eq. (4.6) and eliminating \( \delta \ln s \) by using Eq. (4.5), we find

\[
\left[ -i \eta \frac{k_\perp^2}{\epsilon + p} + k_\parallel \right] \delta u^\mu + \left\{ \frac{1}{\epsilon + p} \left[ \frac{\eta(d-3) + \zeta(d-1)}{d-1} \right] - \frac{c_s^2}{k_\parallel^2} \right\} (k_\perp^\alpha \delta u_\alpha) i k_\perp^\mu = 0,
\]  

(4.9)

where the definitions (4.3) have also been employed. This is a vector equation involving the perturbations in the velocity field as well as in the wavevector and we cannot assume that these vectors are linearly independent. However, we can take projections into independent directions and, as we are describing wave phenomena, it is natural to use the wavevector to define such directions. In fact, we can classify the waves as longitudinal (sound), that propagates in the direction of perturbations, and as transversal (shear), that propagates in the direction orthogonal to the perturbations. The longitudinal sector can be selected by projecting the perturbation equation in the direction of \( k_\perp^\mu \). This can be done by applying on (4.9) the projector

\[ \Sigma^{\mu\nu}_\parallel = \frac{k_\parallel^\mu k_\parallel^\nu}{k_\perp^2}. \]  

(4.10)

Note that \( \Sigma^{\mu\nu}_\parallel k_\perp^\nu = k_\perp^\mu \), while \( \Sigma^{\mu\nu}_\parallel \delta u_\nu = k_\perp^\mu (k_\perp^\alpha \delta u_\alpha)/k_\perp^2 \). Hence the dispersion relation for the sound wave involves the terms multiplying both \( \delta u^\mu \) and \( k_\perp^\mu \) and at first order we have

\[
k_\parallel^2 + i \left[ \frac{2\eta(d-2) + \zeta(d-1)}{\epsilon + p} \right] k_\parallel k_\perp^2 - c_s^2 k_\perp^2 = 0.
\]  

(4.11)

On the other hand, to select the shear-mode sector we use the transverse projector

\[ \Sigma^{\mu\nu}_\perp = \Delta^{\mu\nu} - \frac{k_\perp^\mu k_\perp^\nu}{k_\perp^2}, \]  

(4.12)

and this time we have that \( \Sigma^{\mu\nu}_\perp k_\perp^\nu = 0 \) so the terms multiplying \( k_\perp^\mu \) do not appear in the
dispersion relation and, at first order, we get for the shear mode that

$$k_\parallel + i\eta \frac{k^2}{\varepsilon + p} = 0.$$  \hspace{1cm} (4.13)

The equations obtained so far in this section are all at first-order corrections in the gradient expansion, so that their solutions provide consistent approximations for $\omega(k)$ up to $k^2$. However, our goal here is to study third-order hydrodynamics, so now we consider the corrections for second and third orders and then we solve the equations of motion to get $\omega(k)$ up to order $k^4$.

After linearization, the second-order corrections get simplified and the only terms that survive are the gradient of expansion and the gradient of shear, yielding

$$\delta \Pi^{\mu\nu}_{(2)} = \xi_5 \Delta^{\mu\nu} u^\alpha \partial_\alpha \delta \Theta + \lambda_6 u^\alpha \partial_\alpha \delta \sigma^{\mu\nu}. \hspace{1cm} (4.14)$$

It is seen that the linearization process reduces a list of six scalars and eight tensors to one scalar and one tensor. The effect of of additional derivatives is easily taken into account, in the Fourier space it is a task of multiplying the respective terms by powers of the wave-vector. Then, the second order equation for the shear mode results in

$$k_\parallel + i\eta \frac{k^2}{\varepsilon + p} + \lambda_6 \frac{k^2}{\varepsilon + p} k_\parallel = 0, \hspace{1cm} (4.15)$$

while for the sound mode it gives

$$k^2_{\parallel} - \xi_5^2 k^2_{\perp} + i \frac{1}{\varepsilon + p} \left[ \zeta + 2\eta \left( \frac{d - 2}{d - 1} \right) \right] k_\parallel k^2_{\perp} - \frac{1}{\varepsilon + p} \left[ \xi_5 + 2\lambda_6 \left( \frac{d - 2}{d - 1} \right) \right] k^2_{\perp} k_\parallel = 0. \hspace{1cm} (4.16)$$

Finally we proceed in the same way to include third order corrections for linearized equations of motion. In comparison to the second-order correction, this time we have one more possible structure. There are the laplacians of shear and expansion $\partial^2 \Theta$, $\partial^2 \sigma$, and combined derivatives of expansion $\partial \partial \Theta$ appearing in the linearized energy-momentum tensor, and the third-order correction reads

$$\delta \Pi^{\mu\nu}_{(3)} = \left( \chi_5 - \frac{2\gamma_{14}}{d - 1} \right) \Delta^{\mu\nu} \frac{\partial^2}{\varepsilon + p} \delta \Theta + \gamma_{13} \frac{\partial^2}{\varepsilon + p} \delta \sigma^{\mu\nu} + 2\gamma_{14} \frac{\partial^{(\mu} \partial^{\nu)}}{\varepsilon + p} \delta \Theta, \hspace{1cm} (4.17)$$

where $\partial^\mu = \Delta^{\mu\nu} \partial_\nu$. In the momentum space we can replace $\partial^\mu_{\perp}$ by $ik^\mu_{\perp}$, and then the third order dispersion relation for the shear mode becomes

$$k_\parallel - i\eta \frac{k^2}{\varepsilon + p} + \lambda_6 \frac{k^2}{\varepsilon + p} k_\parallel + i\gamma_{13} \frac{k^4}{\varepsilon + p} = 0, \hspace{1cm} (4.18)$$

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while for the sound mode it is

\[
\begin{align*}
\kappa^2 - \mu^2 k^2 + i \frac{1}{\varepsilon + p} \left[ \xi + 2 \eta \left( \frac{d - 2}{d - 1} \right) \right] k_{\parallel} k^2 \\
- \frac{1}{\varepsilon + p} \left[ \xi_5 + 2 \lambda_6 \left( \frac{d - 2}{d - 1} \right) \right] k_{\parallel} k^2 - \frac{i}{\varepsilon + p} \left[ \chi_1 + 2 (\gamma_{13} + \gamma_{14}) \left( \frac{d - 2}{d - 1} \right) \right] k_{\perp} k^4 = 0.
\end{align*}
\]

(4.19)

It is notorious that the holographic calculation of \(\eta/s\) for \(\mathcal{N} = 4\) SYM is one of the strongest results from AdS/CFT correspondence and represents a particular case where holography provides full description of the system, since at first order a conformal fluid has only one transport coefficient. Unfortunately this is not the case for higher order hydrodynamics where the linearized equations involve a very reduced number of transport coefficients from higher order terms. The present analysis allows us to evaluate only the transport coefficients associated with structures that survive linearization.

4.2 Dispersion relations in the comoving (static) frame

Due to relativistic effects the dispersion relation must be defined in a fixed reference frame, where the notion of frequency is fixed. We look first to the static frame where the observer see no flow, observing a fluid velocity \(u_{\text{static}}^\mu = (1, \vec{0})\). In such a situation the transverse projector projects on the hypersurfaces of constant time, \(\Delta^\mu_\nu = \delta^\mu_\nu + \delta^\mu_0 \eta^\nu_0 = \text{diag}(0, 1, 1, 1)\).

As a consequence, the parallel and transverse components of \(k^\mu\) are precisely the frequency and the spacial wave vector

\[
\begin{align*}
k_{\parallel} &= u_\mu k^\mu = -\omega, \\
k_{\perp} &= (0, \vec{k}),
\end{align*}
\]

and hence \(k_{\perp}^2 = k_{\parallel}^\mu k_{\perp}^\mu = \vec{k} \cdot \vec{k} \equiv k^2\).

We build the dispersion relations by starting with the shear mode. Inserting the expressions from Eq. (4.20) into Eq.(4.18) we find an algebraic equation for \(\kappa\) and \(\omega\) that, up to third order corrections, is given by

\[
-\omega - i \frac{\eta}{\varepsilon + p} \kappa^2 - \frac{\lambda_6}{\varepsilon + p} \omega k^2 + i \frac{\gamma_{13}}{\varepsilon + p} k^4 = 0,
\]

(4.21)

whose solution for \(\omega(k)\) furnishes the dispersion relation,

\[
\omega_{\text{shear}}(k) = -i \frac{\eta}{sT} k^2 - i \left( \frac{\eta \lambda_6}{s^2 T^2} - \frac{\gamma_{13}}{sT} \right) k^4
\]

(4.22)

where we made use of the equilibrium thermodynamic to write \(p + \epsilon = sT\).

To deal with the sound mode it is convenient to define reduced coefficients by the combination of transport coefficients that appear in the expressions for dispersion relations as

\[
\begin{align*}
\beta_1 &= \zeta + 2 \eta \frac{d - 2}{d - 1}, \\
\beta_2 &= \xi_5 + 2 \lambda_6 \frac{d - 2}{d - 1}, \\
\beta_3 &= \chi_1 + 2 (\gamma_{13} + \gamma_{14}) \frac{d - 2}{d - 1}.
\end{align*}
\]

(4.23)

Using these definitions, and replacing the expressions from Eq. (4.20) into Eq.(4.19) we get
the following algebraic equation
\[ \omega^2 - c^2 k^2 - i \frac{k^2 \omega}{sT} \beta_1 - \frac{k^2 \omega^2}{sT} \beta_2 + i \frac{k^4 \omega}{sT} \beta_3 = 0. \] (4.24)

This is a polynomial or second order in \( \omega \) which generates two solutions, \( \omega_+ \) and \( \omega_- \), corresponding to waves traveling in opposite directions, \( \omega_+ \) (\( \omega_- \)) corresponds to modes propagating forwards (backwards) with respect to the wave vector direction. The power series solution for the \( \omega_+ \) mode up to \( k^4 \) gives
\[ \omega_+(k) = ck - \frac{i \beta_1}{2sT} k^2 - \left( \frac{\beta_1^2}{8c s^2 T^2} - \frac{c \beta_2}{2sT} \right) k^3 - i \left( \frac{\beta_3}{2sT} - \frac{\beta_1 \beta_2}{2s^2 T^2} \right) k^4. \] (4.25)

The negative solution \( \omega_- \) is related to the positive one by \( \omega_- (k) = \omega_+ (-k) \).

The obtained expressions for dispersion relations involves the transport coefficients directly related with the shear tensor in eq.(4.22) and combinations of transport coefficients either from shear and expansion appearing in eq.(4.25) in the reduced coefficients \( \beta_1, \beta_2, \beta_3 \).

The dispersion relations in the presence of conformal symmetry are obtained from the general, non-conformal, case by imposing constrains on the transport coefficients. For the choices we performed here we obtain dispersion relations for the conformal fluid by fixing \( \zeta = \xi_5 = 0, \lambda_6 = v_4 \) at first and second order while third order we have fix \( \gamma_{14} = \vartheta_6, \gamma_{13} = \vartheta_7, \chi_1 = 0 \). The transport coefficient \( \vartheta_{11} \) is absent in the dispersion relation of a conformal fluid because the linear fluctuation of the tensor \( u_\eta D^{(\mu F^{\nu})n} \) in a static flow vanishes. The identification gives the expressions for the reduced coefficients present in the sound mode as functions of the transport coefficients of conformal hydrodynamics
\[ \beta_1 = 2\eta \left( \frac{d - 2}{d - 1} \right), \quad \beta_2 = 2v_4 \left( \frac{d - 2}{d - 1} \right), \quad \beta_3 = 2(\vartheta_6 + \vartheta_7) \left( \frac{d - 2}{d - 1} \right). \] (4.26)

### 4.3 Dispersion relations in a moving frame

In a moving frame the velocity flow may be decomposed as \( u^\mu = \gamma (1, \vec{v}) \), with \( \gamma = 1/\sqrt{1 - \vec{v}^2} \), and the projections \( k_\parallel \) and \( k_{\perp} \) defined in Eq. (4.3) are such that
\[ k_\parallel = \gamma (\vec{k} \cdot \vec{v} - \omega), \quad k_{\perp}^2 = -\omega^2 + (\vec{k})^2 + \gamma^2 (\vec{k} \cdot \vec{v} - \omega)^2. \] (4.27)

Here it is convenient to project the space components of the wave-vector in the parallel and perpendicular directions with respect to the space components of the velocity field \( \vec{v} \), respectively, by defining \( \vec{m} = (\vec{k} \cdot \vec{v}) \hat{e} \) and \( \vec{q} = \vec{k} - \vec{m} \). From these definitions it follows \( \vec{k} \cdot \vec{v} = mv \), and \( \vec{q}^2 = q^2 + m^2 \), and Eq. (4.27) gives
\[ k_\parallel = \gamma (-\omega + mv), \quad k_{\perp}^2 = q^2 + \gamma^2 (m - \omega v)^2. \] (4.28)
Inserting the relations from the last equation into Eqs. (4.18) and (4.19) we find, respectively,
\[ i \frac{\gamma_{13}}{sT} \left( \frac{(m - v \omega)^2}{1 - v^2} + q^2 \right) - i \frac{\eta}{sT} \left( \frac{(m - v \omega)^2}{1 - v^2} + q^2 \right) + \frac{\lambda_6}{sT} \frac{mv - \omega}{\sqrt{1 - v^2}} \left( \frac{(m - v \omega)^2}{1 - v^2} + q^2 \right) + \frac{mv - \omega}{\sqrt{1 - v^2}} = 0, \] (4.29)
for the shear mode, and
\[ \frac{(mv - \omega)^2}{1 - v^2} - c^2 \sqrt{\frac{(m - v \omega)^2}{1 - v^2} + q^2} + i \frac{\beta_1}{sT} \frac{mv - \omega}{\sqrt{1 - v^2}} \sqrt{\frac{(m - v \omega)^2}{1 - v^2} + q^2} - \frac{\beta_2}{sT} \frac{(mv - \omega)^2}{1 - v^2} \sqrt{\frac{(m - v \omega)^2}{1 - v^2} + q^2} = 0, \] (4.30)
for the sound mode. The dispersion relations in the moving frame \( \omega = \omega(m, q) \) are given implicitly by the last two equations. Explicit solutions for \( \omega \) in power series of \( m \) and \( q \) result in cumbersome expressions for the general case and are not be presented here.

5 The \( \mathcal{N} = 8 \) SUSY Yang-Mills plasma

5.1 General remarks

In this section we apply the general results presented above to the study of a system that can be holographically described by the AdS\(_4\)/CFT\(_3\) correspondence [15], namely, the \( \mathcal{N} = 8 \) supersymmetric (SUSY) Yang-Mills plasma. Specifically, we deal with the problem from the gravitational point of view in order to obtain the transport coefficients of the plasma up to third order in the gradient expansion. As it is known from the holographic dictionary, the metric of an asymptotically AdS spacetime is dual to the energy-momentum tensor of the boundary conformal field theory. This allows us to relate perturbations of a classical black-hole background to the energy-momentum fluctuations in the dual thermal field theory. We focus in the long-distance and low-energy behavior of these perturbations, i.e., the regime where the constituents of the system present the collective behavior typical of a continuous medium [48, 49]. In the context of the gauge/gravity duality, this is the hydrodynamic limit of the gravitational perturbations [50, 51].

The gravitational AdS background is a plane-symmetric static black hole, which is a solution of the Einstein equations with negative cosmological constant obtained in Ref. [29]. To deal with this problem we need to extend the previous results presented in Refs. [34, 36, 38]. Such results were obtained using first-order expansion of the energy-momentum tensor. In order to obtain the dispersion relations we are going to use techniques implemented in Refs. [53, 54]. At the end, the transport coefficients are obtained by comparing the dispersion relations obtained in both sides of the duality, i.e., fluids and gravity.
5.2 The background spacetime and the perturbation equations

The gravitational background considered here is the spacetime of a plane-symmetric static AdS$_4$ black hole whose metric may be written in the form

$$ds^2 = \alpha^2 r^2 \left[ -f(r) dt^2 + dx^2 + dy^2 \right] + \frac{dr^2}{\alpha^2 r^2 f(r)},$$

(5.1)

where $\alpha$ is a parameter related to the AdS radius $\ell$ by $\alpha = 1/\ell = \sqrt{-3/\Lambda}$, with $\Lambda$ being the negative cosmological constant, and $f(r) = 1 - r_h^3/r^3$ the horizon function (also named the redshift factor, or the blackening factor). The coordinate ranges are $-\infty < t < +\infty$, $0 \leq r < \infty$, $-\infty < x < +\infty$, and $-\infty < y < +\infty$. This metric describes a black hole spacetime whose event horizon is located at $r = r_h$ where $f(r) = 0$, and the AdS boundary lies at $r \to \infty$ where $f(r) \to 1$. Since the topology of the surfaces $t, r = \text{constant}$ is a plane, metric 5.1 is usually referred as describing black branes.

The Hawking temperature of static black holes (and black branes) is obtained by evaluating the following expression at the horizon

$$T = \frac{1}{4\pi} \left| \frac{d}{dr} \left( \alpha^2 r^2 f(r) \right) \right|,$$

(5.2)

so that we obtain

$$T = \frac{3\alpha^2 r_h}{4\pi}.$$

(5.3)

From the dual field theory perspective, $T$ is the local temperature of the conformal plasma [55, 56]. For the forthcoming analysis it is convenient to introduce the variable $u = r_h/r$, in such a coordinate the AdS boundary lies at $u = 0$ and the horizon at $u = 1$. To completely characterize the AdS black hole as a thermodynamic system we have to consider the equation of state $\epsilon = -p + s T$, where $\epsilon$, $p$, and $s$ are the energy, pressure and entropy densities, respectively. The entropy is determined through the Bekenstein-Hawking formula

$$S = \frac{A}{4G},$$

(5.4)

where $A$ is the horizon area and $G$ the gravitational coupling. In Ref. [37] it was obtained a relationship between the gravitational coupling and the number of colours, $N$, in the context of the AdS/CFT correspondence, this relation reads as $G = 3\ell^2/(2N)^{3/2}$. In turn, the horizon area is given by $A = r_h^2 V_2/\ell^2$, where $V_2$ represents the “volume” along the transverse coordinates. Hence, after replacing in (5.4) and using (5.3) we get

$$s = \frac{S}{V_2} = \frac{2^{7/2}}{3^3} \pi^2 N^{3/2} T^2.$$

(5.5)

It is worth mentioning that this result is in agreement with the one obtained in Ref. [37].

Let us mention that gravitational perturbations of static plane-symmetric black holes were investigated previously in the literature, see for instance Refs. [34, 36, 38]. For rotating
black strings see Ref. [57], and for gravitoelectromagnetic perturbations Ref. [27]. In this part of the paper we are going to use the results presented in Ref. [27] in the zero charge and angular momentum limit. The motivation for using these results here, besides comparing them to the relativistic hydrodynamics developed in the preceding sections, is to explore the supersymmetric relationship between the vector and scalar sectors investigated there. We give additional details about this supersymmetry in Sec. 5.4.

Let us start by writing the differential equations governing the vector and scalar sectors of the gravitational perturbations on the background (5.1). As remarked in Ref. [27], in the zero charge limit, the gravitoelectromagnetic perturbations decoupled and may be splitted in electromagnetic and gravitational perturbations. The interest in this work is to investigate the gravitational perturbations, which are identified with the variables $Z_{2^{(-)}}^2$ and $Z_{2^{(+)}}^2$ for the vector and scalar sectors, respectively. These variables are known in the literature as the Regge-Wheeler-Zerilli (RWZ) master variables. In order to compare with previous results [34, 36, 38, 57] we change the master variables $Z_{2^{(-)}}^2 \rightarrow \Phi_V$ and $Z_{2^{(+)}}^2 \rightarrow \Phi_S$, respectively. Hence, the Schrödinger-like form of the differential equations become (cf. Eq. (71) in Ref. [27])

$$
[f \partial_u (f \partial_u) + w^2 - V_{V,S}] \Phi_{V,S} = 0,
$$

(5.6)

where $V_{V}(V_{S})$ refers to the vector(scalar) potential defined as

$$
V_V(u) = f (q^2 - 3u),
$$

(5.7)

$$
V_S(u) = f \frac{q^4 + 9 (2 + q^2 u^2 + u^3)}{q^2 + 3u},
$$

(5.8)

where $w$ and $q$ are respectively the frequency and the magnitude of wave vector, both normalized by the Hawking temperature $T$ as follows,

$$
w = \frac{3 \omega}{4\pi T}, \quad q = \frac{3 k}{4\pi T}.
$$

(5.9)

In the following we investigate some of the solutions of Eq. (5.6).

5.3 Analytical solutions for the vector sector

The aim in this part of the work is to generalize the results obtained for the dispersion relations of vectorial perturbation modes in four-dimensional spacetimes (see Ref. [36]), and also in arbitrary $d$–dimensional black branes Ref. [38]. Previous results in the literature were obtained by considering first- and second-order hydrodynamics, see e.g. Refs. [12, 52], here we go up to the third order.

Let us first investigate the behavior of the wave function $\Phi_V(u)$ close to the horizon, i.e. for $u$ in the vicinity of $u = 1$. In such a region, the wave function behaves like $\Phi_V \propto f^\beta$, where $\beta$ is a constant parameter that may be obtained by replacing this expression into Eq. (5.6). In doing so, the leading-order equation has two solutions for $\beta$, namely, $\beta = \pm \frac{iw}{3}$, where $+i\omega/3$ corresponds an ingoing wave falling into the black hole horizon while the other solution corresponds to an outgoing wave. In the forthcoming analysis we
use the ingoing solution at the horizon because classically nothing comes out of the black hole interior.

In the next stage we are going to solve Eq. (5.6) perturbatively in the parameters \((w, q_2)\). Inspired by the procedure implemented in Refs. [53, 54], we assume that the wave function \(\Phi_V\) may be expressed as follows

\[
\Phi_V(u) = f^{-i w/3} F(u, m, q) G(u).
\]  

By plugging this into Eq. (5.6) it drives to two second-order differential equations, one for \(G(u)\) and another for \(F(u, m, q)\). It is possible to split the equations so that \(G(u)\) is an arbitrary function of the holographic coordinate only, while \(F(u, m, q)\) depends on \(u\) and also on the the wave numbers \((m, q)\). Additionally, it is required that \(F(u, m, q)\) reduces to a constant in the limit \((m, q) \to (0, 0)\). For more details on this procedure see Appendix A. Hence, the transformation (5.10) allows us to simplify drastically the analysis of solving Eq. (5.6). The next step is to expand \(F(u, m, q)\) as a double series in the parameters \(w\) and \(q\). To capture results up to third-order in the hydrodynamic approximation, we expand \(F(u)\) up to fourth-order, namely [50, 51],

\[
F(u, m, q) = F_0 + w F_1 + q^2 F_2 + w^2 F_3 + wq^2 F_4 + q^4 F_5 + \cdots, \tag{5.11}
\]

where \(F_0\) is a constant while \(F_1, F_2, \cdots\) depend on the holographic coordinate and are determined by solving order by order the resulting differential equation for \(F(u, m, q)\), see Eq. (A.3).

Once the wave function (5.10) is obtained, it is expanded close to the boundary, \(u = 0\), in a power series of \(u\) as

\[
\Phi_V(u) = \tilde{\Phi}_V (1 + \Pi_V u + \cdots), \tag{5.12}
\]

where \(\tilde{\Phi}_V\) and \(\Pi_V\) are functions of the parameters \((w, q)\), and the ellipsis represent higher order contributions. The dispersion relation of this sector is identified from the pole of the scalar function \(\Pi_V\) [53, 54]. The explicit form of this function is presented in Appendix A. Here we write the resulting dispersion relation of the vectorial sector in the hydrodynamic limit,

\[
\omega = -\frac{i}{4\pi T} k^2 - i \frac{9 + \sqrt{3} \pi - 9 \ln 3}{384 \pi^3 T^3} k^4 + \mathcal{O}(k^6), \tag{5.13}
\]

where \(\mathcal{O}(k^6)\) represents higher order contributions. From the gravitational point of view, Eq. (5.13) represents the dispersion relation of the low-lying gravitational perturbations of the geometry (5.1). As we are at the hydrodynamic limit, the present results may be compared to the corresponding results obtained from the relativistic hydrodynamics presented in Eq. (4.22). For example, the first term represents the leading term and captures the information of waves propagating with energy \(k^2\), in the dual description this result may be compared with the corresponding result obtained using first-order hydrodynamics (see Section 2.3). Moreover, the contribution of the second-order hydrodynamics vanishes because there is not contribution of terms proportional to \(k^3\) in Eq. (5.13). However, the
subleading contribution of Eq. (5.13) is due to the fourth-order wavenumber, which may
be compared with the corresponding results obtained in third-order hydrodynamics (see
Section 3.3). As it is clear from the dispersion relation (5.13), the frequency is a purely
imaginary number representing damping waves. The corresponding damping time is re-
lated to the imaginary part $\tau = 1/\omega_I$. It is worth mentioning that the same result was
obtained in Ref. [52].

5.4 Analytical solutions for the scalar sector

It is known that obtaining the dispersion relation of the scalar sector of the gravita-
tional perturbations is, in general, an involved and lengthy process. To avoid this, here
we use the supersymmetric relationship, also called electric/magnetic duality of linearized
gravity, that connects the vector and scalar sectors of the gravitational perturbations in
four-dimensional spacetimes. In the case of charged rotating black strings in asymptotically
AdS spacetimes, this supersymmetric relation was investigated in Ref. [27] (SUSY 2015).
It should be clear that the supersymmetric relationship arises when the perturbations are
represented by the RWZ variables.

Now it is worth mentioning the difference between the RWZ and the Kovtun-Starinets
(KS) variables, that are frequently used in holography. The KS variables prevail in hologra-
phy because Dirichlet boundary conditions imposed on these variables at the AdS boundary,
$u = 0$, allow us to find the poles of the retarded Green functions in the corresponding dual
field theory. This means that the poles of the retarded Green functions are the frequencies
of the quasinormal modes of the corresponding dual theory. Hence, we need a relation
relation between RWZ and KS variables, as it was obtained in Ref. [38]. However, such a
relation between is quite involved and we do not employ it here. However, in Ref. [58] the
authors introduced new master fields that we call Edalati-Jottar-Leigh (EJL) variables,
and established a relation between them and the RWZ variables. It is worth mentioning
that KS and EJL variables are equivalent in the sense that both furnish the poles of the
retarded Green functions by imposing Dirichlet conditions at the AdS boundary. Fortu-
nately, the relation between RWZ and EJL variables is simpler than the relation between
RWZ and KS variables, and then we employ here the EJL set of variables. In Fig. 1 we
display a schematic representation of the road we follow to obtain the dispersion relations
of the scalar sector by using the EJL variable. Regarding the difference between RWZ and
EJL variables, we point out that the low-lying quasinormal modes, hydrodynamic QNMs,
arise by imposing Robin type boundary conditions on the RWZ variables, while for EJL
variables it is necessary just Dirichlet boundary conditions at the boundary $u = 0$.

To implement the above-mentioned strategy we start by writing the supersymmetric
relation between the RWZ variables of the vector and scalar sectors of the gravitational
perturbations. In the limit of zero electric charge, the case of interest here, Eqs. (105) and

\[ w = \frac{3}{2} w^{\text{Natsumo}} \]

\[ q = \frac{3}{2} q^{\text{Natsumo}} \]

See the SAdS case in Table III to compare with. Notice that the normalization factors are different
from the present work. The relations between parameters used here and in Ref. [52] are: $w = \frac{3}{2} w^{\text{Natsumo}}$
and $q = \frac{3}{2} q^{\text{Natsumo}}$. 

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The next stage is to write explicitly the relation between Φ\(_S\) and EJL variable. For our benefit this relation was obtained in Ref. [58] and is giving by

\[
ψ\_S = 3r^2 k^2 \frac{q^4}{k^2} Φ\_S + f \frac{q^2}{k^2} \frac{\partial}{\partial u} Φ\_S,\]

(5.16)

Hence, \(ψ\_S\) is a function of the wave function \(Φ\_V\). The EJL variable is completely determined because \(Φ\_V\) is given by Eq. (5.10), it is possible to find an explicit relation between \(ψ\_S\) and \(Φ\_V\) if we replace Eq. (5.15) in Eq. (5.16). Additionally, we should introduce the normalized parameter \(w\) and \(q\) which also may be obtained as \(ω = w r_h / ℓ^2 = w r_h α^2\) (the same is true for the wavenumber), at the end we obtain

\[
q^2 (q^4 - 6iω) \psi_s = 3 \left[ q^2 (q^2 - 2ω²) - 2 r_h^2 f_2 \left[ q^6 - 9 (1 - q^2 r_h^2 f_2) \right] \right] Φ\_V
+ f \left[ q^6 - 18 (1 - q^2 r_h^2 f_2) \right] \frac{\partial}{\partial u} Φ\_V.
\]

(5.17)

This is the complete relation between the vector sector described by the RWZ variables and the scalar sector described by using the EJL variables. We then obtain the dispersion relation of the low-lying scalar QNMs by imposing Dirichlet condition on the master field \(ψ\_s\) at the boundary, for discussions see for instance Refs. [38, 57, 60, 61]. The resulting dispersion relation of the scalar sector may be written as

\[
ω = \frac{1}{k} + \frac{i}{8π T} k^2 + \frac{15 + \sqrt{3} π - 9 \ln 3}{192 \sqrt{2} π^2 T^2} k^3
+ \frac{i \left[ 144 + 4 \sqrt{3} π + 3 π^2 - 6 (6 + \sqrt{3} π) \ln 3 + 27 ln^2 3 - 12 ψ^{(1)} (2/3) \right]}{6144 \pi^3 T^3} k^4 + O(k^5),
\]

(5.18)

\(^{10}\)We point out some typos in Ref. [27]. The corrected version of Eq. (30) is obtained by replacing \(k \rightarrow ℓk\). The correct expression of the operator \(Λ^2\) presented in Eq. (63) is \(Λ^2 = \frac{d^2}{dr^2} + ω^2\).
where $\psi^{(1)}(2/3)$ is the polygamma function and $O(k^5)$ represents higher order contributions. Eq. (5.18) extends previous results in the literature. For instance, by comparing it with the result of Ref. [52] (see Table IV, the $S\text{AdS}_4$ case, in this reference) we observe that both results are in agreement up to third-order in the wavenumber. This is a remarkable result since we obtain Eq. (5.18) by using as starting point the results obtained for the vector sector, and then we apply the supersymmetric relationship. Moreover, we point out that the last term on the right-hand-side of Eq. (5.18) was not previously obtained in the literature. We also notice that the dispersion relations of the scalar sector have real and imaginary parts representing waves propagating and being damped, differently from the wave functions in the vector sector which are purely damped.

5.5 Transport coefficients

After obtaining the dispersion relations of the gravitational perturbations in the hydrodynamic limit, cf. Eqs. (5.13) and (5.18), we are able to get the transport coefficients by comparing such relations to the corresponding dispersion relations obtained in the relativistic hydrodynamic analysis, cf. Eqs. (4.22) and (4.25), respectively. To determine the transport coefficients we also must consider the conformal case with $d = 3$ where $\beta_1 = \eta$, $\beta_2 = v_4$ and $\beta_3 = \vartheta_6 + \vartheta_7$, so we finally obtain

$$
\begin{align*}
\eta &= \frac{2^{3/2} \pi}{3^3} N^{3/2} T^2, \\
v_4 &= \frac{18 + \sqrt{3} \pi - 9 \ln 3}{162 \sqrt{2}} N^{3/2} T, \\
\vartheta_7 &= \frac{1}{72 \sqrt{2} \pi} N^{3/2}, \\
\vartheta_6 &= \frac{12 \psi^{(1)}(\frac{2}{3}) - 3 \pi^2 + 2 \sqrt{3} \pi (2 + 3 \ln 3) - 9 \ln 3 (4 + 3 \ln 3)}{5184 \sqrt{2} \pi} N^{3/2} - \vartheta_7,
\end{align*}
$$

where we also have used Eq. (5.5). It is worth noticing that the transport coefficients emerging at the second order in the gradient expansion depend on the temperature, whereas the transport coefficients emerging at third order do not depend on the temperature. From these coefficients the relaxation time which is frequently used in the literature may be determined, namely,

$$
\tau = \frac{v_4}{\eta} = \frac{18 + \sqrt{3} \pi - 9 \ln 3}{24 \pi T}.
$$

6 Final remarks

We have faced the program of building the theory of hydrodynamics in order to find out the complete description of conformal and non-conformal fluids up to third order in gradient expansion. By assuming that hydrodynamics is an effective theory that respects the underlying symmetries of the system we state that the construction of the gradient expansion should include only structures that are completely covariant under these symmetries. For non-conformal fluids we find that the full set of independent third order gradients is
composed by 20 scalars, 33 vectors, and 39 tensors, thus requiring 59 additional transport coefficients. This represents a reduction of 9 transport coefficients in comparison with the current literature and is a consequence of the equivalences between structures that differs only by the order of derivatives. The presence of conformal symmetry is treated on the same foot as the general covariance and we consider only Weyl covariant gradients in our construction. We find a set of 19 conformal third order tensors, representing a reduction of one transport coefficient in comparison to the present results in the literature. We also find 6 independent conformal scalars and 11 independent conformal vectors. We study fluctuations of a static flow and obtain analytic expressions for the dispersion relations at third order in gradient expansion for shear and sound waves in a static reference frame, as well as the algebraic equations governing the dispersion relations for such modes in a boosted frame.

We applied the results of the general analysis in the study of the AdS$_4$/CFT$_3$ correspondence. We focused on the vector sector of the gravitational perturbations of the AdS$_4$ background written in terms of the RWZ variable. We solved the differential equation in the hydrodynamic limit using a double series expansion, so to obtain the wave function in this regime. Additionally, the dispersion relations of the perturbations were obtained up to fourth-order corrections in momentum. Next, we found the wave function of the scalar sector using the RWZ variable by using the SUSY relation, cf. Eq. (5.15). In the sequence we mapped this solution into the corresponding EJL variables, which relate QN frequencies to the poles of retarded Green functions by imposing Dirichlet condition at the boundary, cf. Eq. (5.16). The dispersion relations of this sector are obtained up to fourth-order in momentum, just like the vector sector. We also showed the agreement of the result obtained in the vector sector with results available in the literature. The same is true for the scalar sector, the results obtained are in agreement with the known results up to third-order in momentum. However, so far there is no results reported in the literature considering the forth-order correction in momentum. Finally, we obtained the transport coefficients by comparing the dispersion relations for the gravitational perturbations of static black branes to the corresponding dispersion relations obtained from linear fluctuations of a relativistic conformal fluids. We realized that the transport coefficients arising from the third-order hydrodynamics do not depend on the temperature.

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A Perturbative solution of the vector sector

In this Appendix we are going to write details on the perturbative solution of the vector sector of the gravitational perturbation. In the forthcoming analysis we follow the ideas implemented in Refs. [53, 54]. By replacing Eq. (5.10) in Eq. (5.6) we obtain the following differential equation

\[
- q^2 f(u) - \nu^2 \left( \frac{f'^2}{f} - \frac{9}{9f^2} \right) - \nu \left( \frac{i f''}{3f} + \frac{2i f' G'(u)}{3f G(u)} \right) + \frac{3u}{f} + \frac{f' G'(u)}{f G(u)} + \frac{G''(u)}{G(u)} \right] F(u) \\
+ \left[ \frac{2G'(u)}{G(u)} + \left( 1 - \frac{2i \nu}{3} \right) \frac{f'}{f} \right] F'(u) + F''(u) = 0.
\] (A.1)

In this equation we observe terms, in the coefficient of \( F(u) \), which do not depend on the frequency and wave numbers, so that we may separate these terms as a differential equation,

\[
\frac{3u}{f} G(u) + \frac{f'}{f} G'(u) + G''(u) = 0.
\] (A.2)

This is a smart way to split the problem in one piece depending on the holographic coordinate, \( G(u) \), and another depending on the coordinate, frequency and wave number, \( F(u) \). The solution to the differential Eq. (A.2) used here is the simplest one, given by \( G(u) = a_0 u \), where \( a_0 \) is a constant.

On the other hand, to find the solutions for \( F(u) \) we must replace Eq. (5.11) into Eq. (A.1) and rearrange the resulting differential equation to get differential equations for each one of the functions \( F_1, F_2, \ldots \). For instance, the differential equation for \( F_1 \) is

\[
\left( \frac{f'}{f} + \frac{2G'(u)}{G(u)} \right) F'_1(u) + F''_1(u) = \left( \frac{i f''}{3f} + \frac{2i f' G'(u)}{3f G(u)} \right) F_0.
\] (A.3)

We do not write here the differential equations for the other functions: \( F_2, F_3, F_4, F_5 \), how-
ever, for completeness we list the solutions of such equations, for the functions $F_1, F_2, \cdots, F_5,$

$$F_1(u) = \frac{iF_0}{18} \left( 18 + 2\sqrt{3} \pi - 9 \ln 3 \right)$$
$$+ iF_0 \left( \frac{1}{u} - \frac{1}{\sqrt{3}} \arctan \left[ \frac{1 + 2u}{\sqrt{3}} \right] + \frac{1}{2} \ln \left[ 1 + u + u^2 \right] \right),$$

$$F_2(u) = \frac{F_0}{3} \left( \frac{1}{u} - 1 \right),$$

$$F_3(u) = \frac{F_0}{432} \left( 72 \text{Li}_2 \left( \frac{(-1)^{1/6}(1 - u)}{\sqrt{3}} \right) + 72 \text{Li}_2 \left( \frac{(-1)^{5/6}(u - 1)}{\sqrt{3}} \right) - 24i\sqrt{3} \text{Li}_2 \left( e^{-\frac{2i}{3} \left( \pi - 3 \arctan \left[ \left( \frac{2n+1}{\sqrt{3}} \right) \right] \right)} \right) + 72i\sqrt{3} \text{Li}_2 \left( -e^{2i \arctan \left[ \left( \frac{2n+1}{\sqrt{3}} \right) \right]} \right) ight.$$ 

$$- 36 \ln^2 (1 - u^3) + 72(\ln 3 - 3) \ln \left[ u^2 + u + 1 \right] + 4\sqrt{3}\pi \left( \ln \left[ \frac{-36 \left( 2\sqrt{3}u + \sqrt{3} + 3i \right)^2}{((\sqrt{3} + i)u + \sqrt{3} - i)^4 (u^2 + u + 1)^2} \right] - 4 \ln [1 - u] \right.$$ 

$$- 2i \arctan \left[ \frac{2u + 1}{\sqrt{3}} \right] + 3 \ln 3 \right)$$ 

$$+ 36 \ln [1 - u] \left( \ln [1 - u^3] + \ln [u^2 + u + 1] \right) + 48i\sqrt{3} \arctan \left[ \frac{2u + 1}{\sqrt{3}} \right]^2$$ 

$$+ 8\sqrt{3} \left( 6 \ln \left[ \frac{1}{216} \left( 3 + i\sqrt{3} \right) (u - 1) \left( 2\sqrt{3}u + \sqrt{3} + 3i \right)^2 \right] \right.$$ 

$$+ 5i\pi + 18 \right) \arctan \left[ \frac{2u + 1}{\sqrt{3}} \right] - 6i\sqrt{3}\pi (\pi - 8i) - 36(\ln 3 - 6) \ln 3$$ 

$$+ 2 \left( -18 \psi^{(1)} \left( \frac{1}{3} \right) + \left( 12 - \frac{4i}{\sqrt{3}} \right) \pi^2 \right),$$

$$F_4(u) = \frac{iF_0}{18} \left( 2\sqrt{3} \pi + 3 \ln 3 \right) - \frac{iF_0}{54} \left( 9 \ln 3 - 2\sqrt{3} \pi - 9(1 - u) \ln \left[ 1 + u + u^2 \right] \right.$$ 

$$+ 6i\sqrt{3} (1 + 3u) \arctan \left[ \frac{1 + 2u}{\sqrt{3}} \right] \right),$$

$$F_5(u) = \frac{F_0}{54} \left( -2\sqrt{3} \pi - 3 \right) + \frac{F_0}{18} \left( \frac{1}{u} + 2\sqrt{3} \arctan \left[ \frac{2u + 1}{\sqrt{3}} \right] \right),$$

where $\text{Li}_2 \left( \frac{(-1)^{n/6}(u - 1)}{\sqrt{3}} \right)$ is the polylogarithm and $\psi^{(1)} \left( \frac{1}{3} \right)$ is the polygamma function. It is worth mentioning that all the integration constants were fixed by the requirement of regularity at the horizon ($u = 1$).

In turn, the approximation of the wave function close to the boundary may be written as, c.f. Eq. (5.12),

$$\Phi_\nu(u) = \tilde{\Phi}_\nu (1 + \Pi_\nu u + \cdots), \quad (A.4)$$
where $\tilde{\Phi}_V$ and $\Pi_V$ depend on the wave numbers. As commented in Sec. 5.3, the pole of $\Pi_V$ gives us the dispersion relation for the vector sector. The explicit form of $\Pi_V$ is

$$
\Pi_V(w, q) = \frac{d(w, q)}{i w (q^2 (\sqrt{3} \pi - 9 \ln 3) - 54) + 3 q^2 (6 + q^2)},
$$

where $d(w, q)$ is given by

$$
d(w, q) = 1 - \frac{q^2}{3} - \frac{1}{54} \left(3 + \sqrt{3} \pi\right) q^4 + w \left(\frac{i}{18} \left(18 + \sqrt{3} \pi - 9 \ln 3\right) - \frac{i}{54} q^2 \left(-18 + \sqrt{3} \pi - 9 \ln 3\right)\right)
$$

$$
+ w^2 \left(\psi^{(1)}(1) \frac{1}{12} + \frac{1}{648} \left[36 i \sqrt{3} \left(3 Li_2 \left(-\sqrt{3}\right) - Li_2 \left(\frac{\sqrt{3}}{3}\right)\right) - 36 (\pi - 18) \ln 2 - 9 \ln 3 \left(-72 + 2 \pi - 2 \sqrt{3} \pi + 18 \ln 2 + 9 \ln 3\right)\right]\right).
$$

\section*{B Irreducible gradients not present in the gradient expansion}

Vector corrections to the energy-momentum tensor in the general case of non-conformal fluid can be ruled out by choosing Landau frame and, hence, they do not introduce new transport coefficients in addition to the set needed by scalar and tensor corrections. In the case of conformally symmetric fluids, the traceless nature of the energy-momentum tensor constrains all transport coefficients coming from conformal scalars to vanish. This is the reason why the list of irreducible conformal and non-conformal vectors and conformal scalars were not written in section 3 and 2. For completeness, these kinds of structures are listed below.

\subsection*{B.1 Non-conformal vectors}

For ordinary non-conformal fluids we have at first order only one admissible transverse vector, namely, $\nabla_\perp^\mu \ln s$. To build second order vectors we can take gradients of a first order scalar, divergences of a first order tensor and also multiply two first order structures, obtaining the list

1. $\nabla_\perp^\mu \Theta$
2. $\nabla_\perp \sigma^{\mu\nu} - \frac{1}{2} w^\mu \sigma^2$
3. $\nabla_\perp \Omega^{\mu\nu} - w^\mu \Omega^2$
4. $\Theta \nabla_\perp^\mu \ln s$
5. $\sigma^{\mu\nu} \nabla_\perp \ln s$
6. $\Omega^{\mu\nu} \nabla_\perp \ln s$
7. $\Delta^\mu_{\nu} w^\eta R_{\nu\eta}$

The third order vectors are found by following the same strategy. We can take gradients of second order scalars, divergence of second order tensors or multiplying one second order with one third order structure. There is no special constraint in addition to those already presented above, and the complete list we find is
1. $\nabla^\mu \Theta^2$
2. $\sigma^{\mu\nu} \nabla_{\perp\nu} \Theta$
3. $\Omega^{\mu\nu} \nabla_{\perp\nu} \Theta$
4. $\Theta \nabla_{\perp\nu} \sigma^{\mu\nu}$
5. $\Theta \nabla_{\perp\nu} \Omega^{\mu\nu}$
6. $\Theta^2 \nabla_\perp \ln s$
7. $\Theta \sigma^{\mu\nu} \nabla_{\perp\nu} \ln s$
8. $\Theta \Omega^{\mu\nu} \nabla_{\perp\nu} \ln s$
9. $D \Theta \nabla_\perp \ln s$
10. $\nabla_\perp D \Theta$
11. $\nabla_\perp^2$

This list presents 33 independent vectors and differs from the one presented in [14], where there are only 28 vectors and we can note, for example, that $\nabla_\perp^\mu R$ is missing there. Differently from the scalars and tensors, we found a larger list of independent vectors at third order in gradient expansion.

B.2 Conformal vectors

The conformal symmetry reduces the number of possible structures in comparison to the non-conformal fluid. At first order there is no conformal transverse vectors, and the only first order vectorial structure is in fact the connection defined in eq.(3.1).

To get a second order conformal vectors we can take divergence of a first order tensor (presented in section 3.2) and also project the second order tensor along the flow. At second order we have four conformal vectors, namely,

1. $u_\sigma F^{\mu\sigma}$
2. $\Delta^{\mu}_\nu u_\eta R^{\nu\eta}$

It is remarkable that the first vector in the list has a nice physical meaning. It is the accelerating force on a test particle due to the presence of the tensor field of the Weyl connection, being analogous to the Lorentz force due to the Faraday-Maxwell electromagnetic tensor field. The vectors $u_\sigma F^{\mu\sigma}$, $\Delta^{\mu}_\nu u_\eta R^{\nu\eta}$ we present here do not appear in previous works. In particular, it is staded in Ref. [68] that there are only two second order conformal vectors. This increment of two vectors follows from implementing Weyl covariance through the Weyl connection, generating the conformal covariant tensor $F^{\mu\nu}$ and allowing for a second order Weyl covariant vector associated to the Ricci tensor.
Third order conformal vectors are obtained by the same strategy resulting in the followin list

1. $\Delta^\mu_\nu D^\nu \sigma^2$
2. $\Delta^\mu_\nu D^\nu \Omega^2$
3. $\Delta^\mu_\nu D^\mu (\sigma^\nu \sigma^\eta)$
4. $\Delta^\mu_\nu D^\mu (\sigma^\nu \Omega^\eta)$
5. $\Delta^\mu_\nu D^\mu (\Omega^\eta \Omega^\eta)$
6. $\Delta^\mu_\nu D^\mu \sigma^\nu \sigma^\eta$
7. $\Delta^\mu_\nu \sigma^\nu \sigma^\eta u^\eta$
8. $\Delta^\mu_\nu \sigma^\nu \Omega^\eta u^\eta$
9. $\Delta^\mu_\nu \sigma^\nu u^\delta R^\nu_\eta$
10. $\Delta^\mu_\nu \sigma^\nu u^\delta D^\eta R^\nu_\eta$

B.3 Conformal scalars

There are no first order conformal scalars.

Considering second order conformal scalars we have the scalar product of first order structures and the scalar projections of the conformal Riemann tensor, namely, $\sigma^2$, $\Omega^2$, $R$, and $u^\mu u^\nu R_{\mu\nu}$, respectively. Notice that the field tensor $F^\mu_\nu$ is of second order but, due to its anti-symmetric character, it is traceless and we have the algebraic relation $u^\mu u^\nu R_{\mu\nu} = \sigma^2 + \Omega^2$, which allows us to remove the structure $u^\mu u^\nu R_{\mu\nu}$ from the list. So, there are only three independent second order conformal scalars,

$$\Psi^{2nd}_1 = \Omega^2, \quad \Psi^{2nd}_2 = \sigma^2, \quad \Psi^{2nd}_3 = R.$$

Third order conformal scalars can be made by products (contractions) of first-order and second-order structures, and also by taking total derivatives of second order scalars. We have schematically $\sigma \Omega^2 \sim u^\mu D^\mu \Omega^2 + D^2 \Omega, \quad u^\mu D^\nu R_{\mu\nu} \sim u^\mu D^\mu R, \quad$ and $\Omega_{\mu\nu} R^\mu_{\nu} = \Omega_{\mu\nu} F^\mu_{\nu} \sim D^\mu D^\nu \Omega_{\mu\nu}$, which eliminates four scalars. We also have $\Omega F \sim \sigma \Omega^2 + u^\mu D^\mu \Omega^2, \quad$ and $\sigma \Omega^2 \sim u^\mu D^\mu \Omega^2 + D^\mu D^\nu \Omega_{\mu\nu}^{\alpha \beta}$, which eliminates two more scalars, and the anty-symmetry of $\Omega$ gives that $\Omega^3$ vanishes identically. Equation (A.1) in [62] allows to express $\Omega^{\mu\nu} u^\alpha u^\beta R_{\mu\alpha \nu \beta}$ and $\sigma^{\mu \nu} u^\alpha u^\beta R_{\mu \alpha \nu \beta}$ as a combination of the other third order scalars, eliminating the two scalars from the list of third-order independent scalar structure. Finally we end up with a list of six conformal third order scalars, namely,

$$\Psi^{3rd}_1 = \Omega_{\mu\nu} F^\mu_{\nu}, \quad \Psi^{3rd}_2 = u^\mu D^\mu \sigma^2, \quad \Psi^{3rd}_3 = \sigma^{\mu \nu} \sigma^{\eta \mu \nu} \quad \Psi^{3rd}_4 = D^\mu D^\nu \sigma^\mu \sigma^\nu, \quad \Psi^{3rd}_5 = u^\mu D^\mu \sigma^\eta, \quad \Psi^{3rd}_6 = \sigma^{\mu \nu} R^{\mu \nu}.$$

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