Lefschetz thimble quantum Monte Carlo for spin systems

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Monte Carlo simulations are useful tools for modeling quantum systems, but in some cases they suffer from a sign problem, leading to an exponential slow down in their convergence to a value. While solving the sign problem is generically NP-hard, many techniques exist for mitigating the sign problem in specific cases; in particular, the technique of deforming the Monte Carlo simulation’s plane of integration onto Lefschetz thimbles (complex hypersurfaces of stationary phase) has seen significant success in the context of quantum field theories. We extend this methodology to spin systems by utilizing spin coherent state path integrals to re-express the spin system’s partition function in terms of continuous variables. Using some toy systems, we demonstrate its effectiveness at lessening the sign problem in this setting, despite the fact that the initial mapping to spin coherent states introduces its own sign problem. The standard formulation of the spin coherent path integral is known to make use of uncontrolled approximations; despite this, for large spins they are typically considered to yield accurate results, so it is somewhat surprising that our results show significant systematic errors. Therefore, possibly of independent interest, our use of Lefschetz thimbles to overcome the intrinsic sign problem in spin coherent state path integral Monte Carlo enables a novel numerical demonstration of a breakdown in the spin coherent path integral.

I. INTRODUCTION

The sign problem in quantum Monte Carlo (QMC) is a major impediment to efficiently simulating quantum systems classically. While the sign problem is basis dependent, it is NP-hard, in general, to find a basis with no sign problem [1, 2]. Still, there are numerous heuristic strategies for solving the sign problem in specific cases [3, 4], or mitigating it in others, reducing the severity of the exponential slow down without eliminating it [5, 6].

The sign problem arises via the protocol of reweighting, in which one pushes the quantum quasiprobability distribution’s phase onto the observable in order to get proper probabilities with which to conduct Monte Carlo simulations. Specifically, for some (complex) quasiprobability distribution $\rho = pe^{i\theta}$, we have that the expectation value of an observable $O$ is given by:

$$\langle O \rangle_{\rho} = \frac{\langle O e^{i\theta} \rangle_{p}}{\langle e^{i\theta} \rangle_{p}}. \quad (1)$$

This reweighting allows non-positive and non-real quasiprobabilities to be sampled via Monte Carlo methods, but the method falls apart when the phase is highly oscillatory. This is the case because for a Monte Carlo sampling of an $n$-particle system repeated $m$ times, the relative error in the phase can be written as

$$\frac{\Delta e^{i\theta}}{\langle e^{i\theta} \rangle_{p}} = \frac{e^{O(\beta n)}}{\sqrt{m}}, \quad (2)$$

where $\Delta e^{i\theta}$ is the standard deviation of $e^{i\theta}$ and $\beta$ is the inverse temperature [1]. Thus, to keep a constant level of relative error in the Monte Carlo simulation, $m$ must scale exponentially with both particle number and inverse temperature, neither of which is desirable.

The sign problem can be avoided by Hamiltonians that are stoquastic (where all the off-diagonal entries are real and non-positive) [7] or, more generally, by Hamiltonians that are in Vanishing Geometric Phase form [8, 9]. However, a variety of interesting quantum many-body systems are not of this form, motivating efforts to mitigate the sign problem. For instance, the spin-1/2 Heisenberg model on a Kagome lattice is a canonical example.

In addition to the clear relevance for condensed matter physics, attempts to mitigate the sign problem are of interest in regards to the study of analog quantum computation. In a quantum computing context, stoquastic Hamiltonians play into quantum complexity theory [10, 11]. In adiabatic quantum computing specifically, there is a large body of evidence that local sign-problem free Hamiltonians do not possess quantum advantage over classical computing [12, 13] and that quantum advantage with stoquastic Hamiltonians requires contrived non-local systems [14]. Adiabatic quantum computation with general Hamiltonians is known to be universal [15], and therefore, it is expected that the quantum advantage over classical computation arises for Hamiltonians that exhibit a sign problem. Nonetheless, many classical techniques are known to address the sign problem in certain instances, motivating us to consider for which Hamiltonians the sign problem makes classical simulation truly intractable.

Lefschetz thimble methods, based on Picard-Lefschetz theory [16], are one promising strategy for mitigating the
sign problem [17, 18]. These methods are a higher dimensional analogue of the stationary phase method, deforming an integral into complex space so that it sits on a manifold of stationary phase. This mostly eliminates the rapid phase oscillations which lead to the sign problem.

This approach has primarily been developed in the context of quantum field theories, both bosonic [19–24] and fermionic [25–32]. Most such field theoretic problems are immediately amenable to the Lefschetz thimble approach, as the relevant variables are continuous and, thus, easily complexified. The approach has also been applied to the Hubbard model [33–35], where prior to applying the techniques one must map the discrete partition function to a functional integral over continuous variables via a Hubbard-Stratonovich transformation [36, 37]. Similarly, for spin systems, one must also map the problem to continuous variables. This was recently done by mapping spins onto complex fermions, but this approach was limited to 2-body interactions between spin-1/2 particles [38].

In this paper, we adapt Lefschetz thimble Monte Carlo methods to generic spin systems by utilizing spin coherent states to map the partition function for a spin system into a continuous variable setting. Using these continuous variable models for spin, we implement a Lefschetz thimble method to mitigate the sign problem in these spin systems. This provides a potential path toward simulating a larger array of quantum systems using classical methods.

While our application of the Lefschetz thimble techniques is effective at mitigating the sign problem, unfortunately, our results show significant systematic errors compared to those obtained by exact diagonalization. This error is due to uncontrolled approximations made in the standard formulation of the spin coherent path integral [39, 40]. While it has previously been demonstrated analytically that these approximations can lead to inaccurate results [41], our use of Lefschetz thimbles provides, to our knowledge, the first numerical demonstration of such a breakdown. This is because standard spin coherent path integral Monte Carlo introduces its own sign problem, making such calculations extremely expensive without using our techniques to mitigate the sign problem.

Our novel numerical demonstration of such a breakdown is an interesting result in its own right, but for the purposes of applying Lefschetz thimbles to study large spin systems with a sign problem, it indicates a hurdle to be overcome. The success of these techniques at mitigating the sign problem demonstrate that better understanding and controlling the systematic errors that arise in spin coherent path integrals [42, 43], is a worthwhile goal as it would immediately unlock a powerful new technique for studying spin systems with a sign problem.

II. LEFSCHETZ THIMBLES

Consider an integral of the form

$$Z = \int_{\mathbb{R}^n} d^n x e^{-S(x)},$$

where, here, $n$ is the number of degrees of freedom, $x \in \mathbb{R}^n$ (boldface denotes a vector) are the state variables, and $S$ is the action. For a complex action $S$, this integral can be highly oscillatory, and, therefore, can suffer from the sign problem when numerically integrated via QMC. The core of the Lefschetz thimble approach is mitigating this sign problem is to promote $S(x) : \mathbb{R}^n \to \mathbb{C}$, to a holomorphic function $S(z) : \mathbb{C}^n \to \mathbb{C}$, and deform the original integration region, called an $n$-cycle, to a collection of cycles of stationary phase for the action, on which the imaginary part of the action is constant. On such stationary phase cycles, called Lefschetz thimbles, there is no sign problem.

To formally define the stationary phase cycles and to systematize deformation into them, we introduce the concept of a holomorphic flow. Let $\tau$ be the flow-time parameter, a non-physical parameterization of our deformation in the complex hyperplane. We write the result of flowing an initial integration point, $z_0$, for flow-time $\tau$ as $\varphi(z_0; \tau) : \mathbb{C}^n \times \mathbb{R} \to \mathbb{C}^n$. Letting $z(\tau) \equiv \varphi(z_0; \tau)$, we define the holomorphic flow via the differential equation

$$\frac{dz_i}{d\tau} = \frac{\partial S}{\partial z_i},$$

where the bar denotes complex conjugation. There are a few important things to note about Eq. (4). First, the holomorphic flow is such that the real part of the action monotonically increases under the flow, whereas the imaginary part of the action is constant. This can be confirmed by observing that

$$\frac{dS}{d\tau} = \sum_i \frac{\partial S}{\partial z_i} \frac{dz_i}{d\tau} = \sum_i \frac{\partial S}{\partial z_i} \frac{\partial S}{\partial \bar{z}_i} \geq 0,$$

and that $dS/d\tau$ is real. Alternatively one could simply observe that the holomorphic flow is: (a) the gradient flow of $\Re S$, and, therefore, it is the path of steepest ascent for $\Re S$; and (b) the Hamiltonian flow for a “Hamiltonian” given by $\Im S$, and, consequently, $\Im S$ is conserved under the flow. Second, the critical points of the action (i.e., where $\partial S/\partial z_i = 0$ for all $i$) are stationary under the flow. Finally, the Jacobian $J$ corresponding to the change of variables $z_0 \to \varphi(z_0; \tau)$ satisfies its own flow equation,

$$\frac{dJ}{d\tau} = \Pi J,$$

where $H = \begin{bmatrix} \frac{\partial^2 S}{\partial z_i \partial \bar{z}_j} \end{bmatrix}$ is the Hessian of $S$.

The flow equations allow us to formally define two interrelated stationary phase $n$-cycles: the Lefschetz thimble, and the anti-thimble. Let $\{p_\sigma \mid \sigma \in \Sigma\}$ be the collection of critical points of $S$, with some indexing set $\Sigma$. 
Then, we can define the Lefschetz thimble attached to \( p_\sigma \), denoted \( J_\sigma \), to be the collection of all points that flow away from \( p_\sigma \) under Eq. (4). Mathematically:

\[
J_\sigma = \{ z | \varphi(z; -\infty) = p_\sigma \}. \tag{6}
\]

Similarly, the anti-thimble attached to \( p_\sigma \), written \( K_\sigma \), is defined as the set of all points that flow to \( p_\sigma \). That is:

\[
K_\sigma = \{ z | \varphi(z; \infty) = p_\sigma \}. \tag{7}
\]

Notice that \( J_\sigma \), in addition to being a stationary phase cycle of \( S \), is also the steepest ascent cycle of \( S \) from \( p_\sigma \). This means that we know definitively that \( J_\sigma \) is a convergent integration cycle for \( e^{-S} \), as the boundaries of the integral go to zero as quickly as possible. On the other hand, \( K_\sigma \) is a cycle of steepest descent, and, therefore, divergent.

The anti-thimbles \( K_\sigma \) serve their purpose, however, by helping to identify the set of thimbles \( J_\sigma \) that correspond to our initial integration contour \( \mathbb{R}^n \). In particular, if some modest conditions are met \([16, 18]\), the integral of \( e^{-S} \) over any convergent integration cycle can be deformed into an integral over a linear combination of \( J_\sigma \)'s.

Given our initial integration cycle \( \mathbb{R}^n \) we have that

\[
\mathbb{R}^n \simeq \sum_{\sigma'} (K_{\sigma'}, \mathbb{R}^n) J_{\sigma'}, \tag{8}
\]

up to equality of integration, where \((A, B)\) is the intersection pairing of \( n \)-cycles \( A \) and \( B \), i.e. the number of isolated intersections between \( A \) and \( B \).

Provided we can appropriately identify (or approximately identify) the correct intersection pairings, Eq. (8) provides us a pathway to ameliorating the sign problem by integrating over the appropriate linear combination of Lefschetz thimbles instead of \( \mathbb{R}^n \). While a variety of numerical treatments have shown this approach to be useful in many contexts \([21, 27–29, 44–47]\), it is important to emphasize that this change of integration contour does not fully solve the sign problem. One limitation is that, during the deformation process, the phase of the integrand will pick up a contribution from the Jacobian (the so-called residual phase), which may introduce a sign problem of its own \([19, 48]\). Furthermore, if multiple thimbles contribute to the partition function, a sign problem can still arise due to the presence of relative phases between different thimbles; such relative phases arise because, while \( \text{Im} S \) is constant on individual thimbles, it is not so between different thimbles \([48]\). Despite these caveats, in many cases of interest these issues have not been fatal and the Lefschetz thimble approach has seen great success \([19–35, 38]\), motivating its further application to sign problems in spin systems.

### III. ALGORITHMS

Now that we have introduced an analytic framework for addressing the sign problem, we consider the use of Lefschetz thimbles in QMC algorithms. A number of such algorithms have been introduced \([21, 27–29, 44–47]\); here we consider a particular approach called the generalized thimble method, first proposed in Ref. \([45]\). This algorithm is of particular interest since it does not require \textit{a priori} knowledge of the critical points of the action in the complexified space, and, in principle, guarantees sampling over all relevant thimbles.

The key to this algorithm is the observation that

\[
\varphi(\mathbb{R}^n; \infty) = \sum_{\sigma'} (K_{\sigma'}, \mathbb{R}^n) J_{\sigma'}, \tag{9}
\]

which can be intuitively understood by noting that the only structures that the flow can “get stuck” on are the thimbles, and all points not flowing to the thimbles will flow out to infinity, where they, too, will eventually arrive at the thimbles. Thus, for some sufficiently large time \( \tau \), a flow of \( \mathbb{R}^n \) will approach the appropriate ensemble of thimbles, ameliorating the sign problem.

See Algorithm 1 for a pseudocode sketch of the approach. The algorithm is a Metropolis-Hastings algorithm, with samples taken on the initial integration manifold \( \mathbb{R}^n \) according to the probability distribution \( e^{-S_{\text{eff}}} \) on the thimbles, taking into account the requisite change of variables. The larger \( \tau \) is, the more the probability landscape on the initial manifold will localize to small region(s) with high probability density. As a result, for large \( \tau \), the algorithm may become less effective at finding all relevant thimbles and arriving at the desired distribution. As such, there emerge conflicting incentives to both minimize and maximize \( \tau \), which implies there will be an optimal \( \tau \) balancing these desired outcomes.

It should also be noted that calculating \( \det J \) is by far the most computationally expensive aspect of this algorithm. In this work, we take the approach of simply numerically integrating Eq. (5), but more efficient schemes exist in the literature \([24, 47, 49]\).

A perennial issue in Monte Carlo methods is balancing the need to sufficiently explore the sample space and to spend time in high-weight regions of it. In the limit of in-

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**Algorithm 1** Generalized thimble method

\[
\begin{align*}
\text{Require:} & \quad N, \tau \geq 0, \ z \in \mathbb{R}^n. \\
1: & \quad z' = \varphi(z; \tau) \\
2: & \quad S_{\text{eff}} = S(z') - \log \det J \\
3: & \quad \text{for} \ i \in [0, N) \cap \mathbb{Z} \ \text{do} \\
4: & \quad \text{z}_{\text{next}} = z + \delta z, \ \delta z \ \text{random, symmetric} \\
5: & \quad \text{z}'_{\text{next}} = \varphi(\text{z}_{\text{next}}; \tau) \\
6: & \quad S_{\text{eff}, \text{next}} = S(\text{z}'_{\text{next}}) - \log \det J_{\text{next}} \\
7: & \quad \text{if} \ \text{Uniform}(0, 1) \leq e^{-\text{Re}(S_{\text{eff}, \text{next}} - S_{\text{eff}})} \ \text{then} \\
8: & \quad z = z_{\text{next}} \\
9: & \quad z' = z_{\text{next}}' \\
10: & \quad S_{\text{eff}} = S_{\text{eff}, \text{next}} \\
11: & \quad \text{end if} \\
12: & \quad \text{Record} \ z, z', S_{\text{eff}}. \\
13: & \quad \text{end for}
\end{align*}
\]
finite runtime this issue takes care of itself, but of course, no simulation has infinite time. Introduced in Ref. [50], Hybrid (or Hamiltonian) Monte Carlo (HMC) provides an alternative sampling scheme designed to address this problem by providing a mechanism to more efficiently explore the parameter space than standard approaches. This approach augments the “spatial” coordinates \( z \) with an auxiliary momentum \( \pi \in \mathbb{R}^n \). This new set of variables are then flowed via Hamilton’s equations with the Hamiltonian \( \mathcal{H}(z, \pi) = S(z) + \frac{\pi^2}{2} \):

\[
\frac{d\pi_i}{d\tau} = \frac{\partial \mathcal{H}}{\partial z^i} = \pi^i \tag{10}
\]

\[
\frac{dz_i}{d\tau} = -\frac{\partial \mathcal{H}}{\partial \pi^i} = \frac{\partial S}{\partial z_i}. \tag{11}
\]

Define \( F(z, \pi; \tau) := (z(\tau), \pi(\tau)) \) to be the Hamiltonian flow of \((z, \pi)\). A detailed implementation of the HMC method for thimble models is given in Algorithm 2.

### IV. SPIN COHERENT STATE PATH INTEGRALS

While Lefschetz thimble Monte Carlo has been shown to be effective in ameliorating the sign problem, it only works with partition functions expressed as integrals, not the sums seen in standard path integral QMC for spin systems. To apply Lefschetz thimble Monte Carlo to spin systems, we need to write the spin partition function as an actual integral. This can be accomplished using a resolution of the identity expressible as an integral. Spin coherent states provide one such resolution. The novel application of Lefschetz thimble Monte Carlo to spin systems in a general way via spin coherent states is a key result of this paper.

We define a generic spin-\( S \) spin coherent state as

\[
|\mu\rangle = \frac{1}{(1 + |\mu|^2)^{S}} \exp \{ \mu \hat{S}_- \} |\uparrow\rangle, \tag{12}
\]

where \( \hat{S}_- = \hat{S}_x - i \hat{S}_y \) is the lowering operator, \( |\uparrow\rangle \) is the \(+S\) state in the \( z\)-direction, and \( \mu \in \mathbb{C} \). Let \( \mu = e^{i\varphi} \tan \frac{\theta}{2} \); then \( |\mu\rangle \) corresponds to the \(+S\) eigenstate of the spin operator along an axis rotated from \(+z\) by \( \theta \) about the \( y\)-axis and then \( \varphi \) about the \( z\)-axis [51]. Importantly, spin coherent states can resolve the identity as

\[
I = \frac{2S + 1}{\pi} \int_{\mathbb{R}^2} \frac{d^2\mu}{(1 + |\mu|^2)^2} |\mu\rangle \langle \mu|, \tag{13}
\]

where, for brevity, we let \( d^2\mu := d(\text{Re} \mu)d(\text{Im} \mu) \).

Let \( \mu_j = x_j + iy_j \) at each “imaginary time-slice” \( j \in \{0, \cdots, T-1\} \) of the usual path integral. Inserting Eq. (13) at each time-slice, we obtain the discrete spin coherent state path integral up to \( \mathcal{O}(T) \)

\[
Z = \left( \prod_{j=0}^{T-1} \frac{2S + 1}{\pi} \int_{\mathbb{R}^2} \frac{dx_j dy_j}{(1 + x_j^2 + y_j^2)^2} \right) e^{-S[\{x_j\}, \{y_j\}]} \tag{14}
\]

where

\[
S[\{x_j\}, \{y_j\}] = \sum_{j=0}^{T-1} \sum_{j=1}^{j+1} \left( 2iS \frac{y_{j+1} x_j - x_{j+1} y_j}{(1 + x_j^2 + y_j^2)^2} + \frac{\beta}{T} H^c(x_j, y_j) \right). \tag{15}
\]

and \( H^c : \mathbb{R}^2 \rightarrow \mathbb{R} \) is the so-called classical Hamiltonian whose precise form depends on the problem of interest [52]. We refer the reader to Appendix A for the details of this standard calculation. We can absorb the volume element of the integral in Eq. (14) into the action by defining \( S' = S + 2 \sum_j \log(1 + x_j^2 + y_j^2) \).

Note the following regarding Eq. (15): (a) The first term, a geometric phase, introduces its own sign problem into the partition function. In standard spin coherent state QMC [53], one doesn’t attempt to correct this sign problem or any original sign problem contained in \( H^c \), potentially at exponential cost to the simulation algorithm; (b) Eq. (15) requires the assumption that \( y_{j+1} - y_j \) and \( x_{j+1} - x_j \) are \( \mathcal{O}(\frac{1}{T}) \). This is not mathematically well-founded at low spins [39, 40], but can be somewhat justified at higher spins [54]. This is the uncontrolled approximation in the spin coherent path integral described in the introduction. We shall see that our results cast doubt onto the extent to which the approximation is reasonable, even for large spins, motivating a more rigorous understanding of this issue than provided by standard treatments of the spin coherent path integral; (c) Both the geometric phase, and, it will turn out, the classical Hamiltonian, have a singularity when \( x_j^2 + y_j^2 = -1 \). This causes the action to diverge in finite flow time. Such divergences are also observed when applying the Lefschetz thimble technique to fermionic models [26, 27]. Consequently, when flowing the integration manifold, we seek a flow time sufficiently long to mitigate the sign problem, but not so long as to cause numerical blow-ups. While unnecessary in the examples we consider, one can also avoid such numerical issues by modifying the flow so that it slows as one approaches singularities [55].

### Algorithm 2 Generalized thimble Hybrid Monte Carlo

Require: \( N, \tau_1, \tau_2 \geq 0, \ z \in \mathbb{R}^n \).

1: \( \vec{z}' = \varphi(\vec{z}; \tau) \)
2: \( S_{\text{eff}} = S(\vec{z}') - \log \det J \)
3: for \( i \in [0, N] \cap \mathbb{Z} \) do
4: \( \pi = \text{Normal}(0, 1) \in \mathbb{R}^n \)
5: \( (z_{\text{next}}, \pi_{\text{next}}) = F(z, \pi; \tau_1) \)
6: \( z_{\text{next}} = \varphi(z_{\text{next}}; \tau_2) \)
7: \( S_{\text{eff}, \text{next}} = S(z_{\text{next}}) - \log \det J \)
8: if Uniform(0, 1) \leq e^{-Re(S_{\text{eff, next}} - S_{\text{eff}}) + \frac{x_{\text{next}}^2 - x^2}{2}} \) then
9: \( z = z_{\text{next}} \)
10: \( z' = z_{\text{next}} \)
11: \( S_{\text{eff}} = S_{\text{eff}, \text{next}} \)
12: end if
13: Record \( z, z', S_{\text{eff}} \).
14: end for

We define a generic spin-\( S \) spin coherent state as

\[
|\mu\rangle = \frac{1}{(1 + |\mu|^2)^{S}} \exp \{ \mu \hat{S}_- \} |\uparrow\rangle, \tag{12}
\]
V. NUMERICAL RESULTS

Two systems are studied in this paper: a single spin-40 particle and a frustrated triplet of spin-10 particles. A combined HMC/holomorphic gradient flow algorithm was used for both systems. First, proposals are generated on the parameterization manifold using molecular dynamics evolution. We use the leapfrog integrator defined in [50] to implement this evolution. Once a proposal is generated, both initial and proposed points are flowed according to Eq. (4), and their Jacobians according to Eq. (5). The proposal is then accepted/rejected according step 8 of Alg. 2 [56].

A. Single Spin

For the single spin-40 particle we consider the Hamiltonian \( H = \hat{S}_y \). This Hamiltonian has vanishing geometric phase, and thus has no sign problem. However, it serves as a good test to see whether the sign problem introduced by the spin coherent state path integral can be overcome by Lefschetz Spin QMC.

For this system we perform several studies. We first fix \( T = 3 \) and perform three sets of simulations: standard (unflowed) simulations sweeping across \( \beta \), a sweep across \( \tau \) at fixed beta, then finally a sweep across \( \beta \) at fixed \( \tau \). Unflowed simulations provide reference data for this proof-of-principles study, while a sweep across \( \tau \) at fixed \( \beta \) gives a rough idea as to what flow time is needed to handle the sign problem. Finally, with a suitable \( \tau \) established, a sweep over \( \beta \) can be performed. Unflowed simulations include \( 1 \times 10^6 \) HMC steps, with proposals using a leapfrog integration of “time” 1.0. The step-size of the integrator is chosen such that the acceptance rate remained above 90% for all simulations. Such large statistics (on the scale of lattice QCD and lattice effective field theory simulations) are required to overcome the sign problem—even then, at small \( \beta \) there is approximately 100% uncertainty in observables.

Flowed simulations take \( 5 \times 10^4 \) steps for each value of \( \beta \) and \( \tau \) considered, and the HMC trajectory length is reduced to 0.05. This reduction is required because the deformation of the parameterization manifold is large enough that an HMC trajectory of length 1.0 results in essentially no acceptances. For the study of how the results depend on flow time we fix \( \beta = 0.1 \), where the sign problem is the worst. From Fig. 1, it is clear that both the sign problem is mitigated and that the flow does not alter the value of observables. We find \( \tau = 0.003 \) sufficient to tame the sign problem, so we use this flow time in our sweep across \( \beta \).

For this single spin system, each flowed step takes about 20 times longer than an unflowed step, and we have chosen the statistics of the flowed simulations to be such that the wall-clock time of both flowed and unflowed simulations are equal. Looking at Fig. 2, it is clear that the statistical uncertainty of the flowed simulations are much smaller than unflowed simulations, especially at small \( \beta \); since the two simulations take equal time, flowing results in demonstrable improvement in Monte Carlo performance.

Finally for the single spin system, we perform a time-continuum limit extrapolation at \( \beta = 0.1 \), where the sign problem is severe. It is clear that at finite \( T \) there is a sizeable difference between the path-integral and exact results. Furthermore this difference is largest at small \( \beta \) as can be seen in Fig. 3. The question we wish to address is whether this difference goes to zero in the time continuum limit. If so, this discretization is demonstrably incorrect, in spite of its widespread usage in demonstrat-
At higher continuum limit, discretization most likely does not converge to the correct value. We wish to reiterate that, though this is an extremely simple model, to our knowledge, this is the first numerical demonstration of this fact, even for a single spin. The reason for this is the sign problem: for a single spin path integral contains uncontrolled errors, potentially leading to erroneous results, has been previously discussed in Refs. [39–43], although it appears this is the first numerical demonstration of this fact, even for a single spin. The reason for this is the sign problem: for \( T = 3 \) and certainly higher \( T \)'s, standard Monte Carlo simulations simply cannot resolve the phase oscillations in any reasonable time.

We simulate at \( T \in \{2, 3, \cdots, 7\} \) to study the time continuum limit. Due to the severity of the sign problem at higher \( T \), we fix \( \tau = 0.003 \) and take \( 2.5 \times 10^5 \) steps in each simulation. We find a clear signal for the energy at every \( T \), though the quality decreases at large \( T \). Our results are displayed in Fig. 3. We find no evidence of a time continuum limit. Rather than smooth convergence to the continuum, a staggered pattern appears between even and odd number of timeslices. Furthermore, both branches trend upward, away from the correct result, as the continuum is approached. While it is logically possible that at extremely large \( T \) the lattice results converge to the exact result, we find no compelling reason to believe this. We posit that, if a time continuum limit exists for this discretization, it does not converge to the correct value. We wish to reiterate that, though this is an extremely simple model, to our knowledge, this is the first direct numerical demonstration that this textbook discretization most likely does not converge to the correct continuum limit.

We also consider a frustrated spin triplet of three spin-10 particles interacting via the Hamiltonian \( \hat{H} = \hat{S}_{z,1}\hat{S}_{z,2} + \hat{S}_{z,2}\hat{S}_{z,3} + \hat{S}_{z,3}\hat{S}_{z,1} + \hat{S}_{x,1}\hat{S}_{x,2} + \hat{S}_{x,2}\hat{S}_{x,3} + \hat{S}_{x,3}\hat{S}_{x,1} \). This example has a genuine sign problem [3]. Here, we again study \( T = 3 \) and perform three classes of simulations: a sweep across \( \beta \) on unflowed manifolds, a sweep across \( \tau \) at fixed \( \beta \), and finally a sweep across \( \beta \) at fixed \( \tau \). On unflowed manifolds we simulate \( 100 \times 10^6 \) HMC steps. Such high statistics are needed because the sign problem of this discretization is severe. Even with these high statistics, we only barely find a signal at the large \( \beta \).

As in the single spin case, we first sweep across \( \tau \) at fixed \( \beta = 0.1 \) to both demonstrate the correctness of the method and to establish a sufficient flow to tame the sign problem. These simulations consist of \( 1.25 \times 10^5 \) steps and the results are plotted in Fig. 4. The statistical uncertainty shrinks with \( \tau \) with no detectable deviation in the mean, demonstrating both the utility and correctness of the method. To sweep across \( \beta \), we fix \( \tau = 0.015 \) and perform simulations with \( 1 \times 10^6 \) steps. While the unflowed data is extremely noisy, we find agreement between the two methods for all \( \beta \), again demonstrating the correctness of the method. See Fig. 5.

We conclude with a cost comparison: every flowed step of the triplet system costs 50 times more than an unflowed step. Therefore, twice as much wall-clock time is taken in the unflowed simulation than in the flowed simulation. However, the cheaper, flowed, data is drastically more precise. This again demonstrates that flowed simulations result in concrete gains.

**FIG. 3.** Average sign (top) and energy expectation value (bottom) for the single spin example at \( \beta = 0.1 \) as a function of inverse time steps \( \frac{1}{T} \) in the spin coherent path integral. We use \( \tau = 0.003 \). Importantly, there is no evidence of a clear continuum limit as \( \frac{1}{T} \to 0 \) and we observe a staggered pattern, indicating odd/even dependence of the results. This provides numerical evidence of the breakdown of the spin coherent path integral due to the uncontrolled approximation that \( |y_{j+1} - y_j| \sim |x_{j+1} - x_j| \sim O \left( \frac{1}{T} \right) \) used in Eq. (15).

**FIG. 4.** Average sign (top) and energy expectation value (bottom) for the spin triplet example. As in the single spin example, while the flow is successful at mitigating the sign problem, there is a systematic error with respect to the true energy.
FIG. 5. The expectation value of energy as a function of $\beta$ for the spin triplet example as computed via exact diagonalization, (unflowed) Spin QMC, and Lefschetz Spin QMC flowed for $\tau = 0.015$.

VI. CONCLUSION AND OUTLOOK

These results indicate that the generalized Lefschetz thimble method is successful at mitigating the sign problem in spin systems. These numerical examples served mostly as a proof of principle of these techniques, but nothing stops them from being applicable to larger problems. However, despite the demonstrated success of these techniques for mitigating the sign problem, we showed that uncontrolled approximations made in the standard spin coherent state path integral can introduce problematic systematic errors. While the possibility of such a breakdown in the spin coherent path integral in the continuous time limit was known, to our knowledge, our results provide the first numerical demonstration of such a breakdown. The reason for the lack of numerical demonstration is the sign problem: spin coherent path integrals introduce their own sign problem beyond any that may or may not be present in the initial spin Hamiltonian. Lefschetz thimbles allow us to overcome this sign problem. These systematic errors persist over all flows used, as well as over multiple choices for the number of time steps $T$ in the spin triplet path integral. To confidently apply Lefschetz thimble techniques to larger spin systems where the systematic error cannot be reliably evaluated will require addressing this issue with the standard spin coherent path integral. Our results indicate that this will be worthwhile, allowing us to unlock the potential of Lefschetz thimble methods for studying spin systems with a sign problem.

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Appendix A: Derivation of Spin Coherent State Path Integral

In this appendix, we derive the spin coherent state path integral.

1. The Partition Function

To derive the spin coherent state path integral, we begin with the definition of the partition function:

\[ Z = \text{Tr} \{ e^{-\beta \hat{H}} \} \]

We restate the spin coherent state resolution of the identity here for convenience

\[ I = \frac{2S + 1}{\pi} \int_{\mathbb{R}^2} \frac{d^2\mu}{(1 + |\mu|^2)^2} |\mu\rangle \langle \mu| . \quad (A1) \]

Now, as \( \hat{H} \) commutes with itself, we can insert the spin coherent state resolution of the identity from Eq. (A1) between each imaginary-time step and rewrite this expression as

\[ Z = \text{Tr} \left\{ \left( e^{-\beta/T \hat{H}} \right)^T \right\} \]

\[ = \text{Tr} \left\{ \left( e^{-\beta/T \hat{H}} \right) \left( \frac{2S + 1}{\pi} \int_{\mathbb{R}^2} \frac{d^2\mu}{(1 + |\mu|^2)^2} |\mu\rangle \langle \mu| \right) \right\} \]

\[ = \left( \prod_{j=0}^{T-1} \frac{2S + 1}{\pi} \int_{\mathbb{R}^2} \frac{d^2\mu_j}{(1 + |\mu_j|^2)^2} \right) \left( \prod_{j=0}^{T-1} \langle \mu_{j+1}| e^{-\frac{\beta}{T} \hat{H}} |\mu_j \rangle \right) \quad (A2) \]

where, enforcing the periodicity imposed by the trace, we have \( \mu_T = \mu_0 \). Next we expand the exponential out to first order in \( \beta/T \) and get that

\[ \langle \mu_{j+1}| e^{-\frac{\beta}{T} \hat{H}} |\mu_j \rangle = \langle \mu_{j+1}| \left( I - \frac{\beta}{T} \hat{H} + \mathcal{O} \left( \frac{(\beta/T)^2}{T^2} \right) \right) |\mu_j \rangle \]

\[ = \langle \mu_{j+1}| \mu_j \rangle \left( 1 - \frac{\beta}{T} H^{cl}(\pi_{j+1}, \mu_j) + \mathcal{O} \left( \frac{(\beta/T)^2}{T^2} \right) \right) , \quad (A3) \]

where \( H^{cl}(\pi_{j+1}, \mu_j) \equiv \langle \mu_{j+1}| H |\mu_j \rangle / \langle \mu_{j+1}| \mu_j \rangle \) will be examined in detail in the next section. Now, using that the overlap of two spin coherent states \( |\mu\rangle \) and \( |\mu'\rangle \) is \( \langle \mu'|\mu \rangle = (1 + \bar{\mu} \mu)^2S/(1 + |\mu|^2)(1 + |\mu'|^2) \) \( [51] \), we can rewrite this expression as

\[ \langle \mu_{j+1}| \mu_j \rangle \left( 1 - \frac{\beta}{T} H^{cl}(\pi_{j+1}, \mu_j) + \mathcal{O} \left( \frac{(\beta/T)^2}{T^2} \right) \right) \quad (A4) \]

The next task is to simplify the inner product in front. To make this possible, we make the standard assumption in deriving path integral expansions that \( |\mu_{j+1} - \mu_j| \equiv |\delta_{j+1}| = \mathcal{O}(\beta/T) \). There is analytical evidence that this
where to get between the second and third, as well as third and fourth lines we use the binomial expansion.

Multiplying these two together, we finally get that

\[
\langle \mu_{j+1}| e^{-\beta H/T} |\mu_j \rangle = 1 + S\left(\frac{\delta_{j+1}\mu_j - \delta_{j+1}\mu_j}{(1 + |\mu_j|^2)} - \frac{\beta}{T} H^{cl}(\mu_{j+1}, \mu_j)\right) + O\left(\frac{(\beta / T)^2}{(\beta / T)}\right).
\]  

(A6)

Plugging this back into Eq. (A2), we get that

\[
Z = \left(\prod_{j=0}^{T-1} \frac{2S + 1}{\pi} \int_{\mathbb{R}^2} \frac{d^2\mu_j}{(1 + |\mu_j|^2)^2}\right) e^{-S[\mu_j]} + O(\beta / T),
\]

(A7)

where

\[
S[\{\mu_j\}] = \sum_{j=0}^{T-1} \left(-S\left(\frac{\delta_{j+1}\mu_j - \delta_{j+1}\mu_j}{(1 + |\mu_j|^2)} + \frac{\beta}{T} H^{cl}(\mu_{j+1}, \mu_j)\right)\right).
\]

(A8)

Letting \( x = \text{Re}\mu \) and \( y = \text{Im}\mu \), we arrive at

\[
Z = \left(\prod_{j=0}^{T-1} \frac{2S + 1}{\pi} \int_{\mathbb{R}^2} \frac{dx_j dy_j}{(1 + x_j^2 + y_j^2)^2}\right) e^{-S[\{x_j\}, \{y_j\}]} + O(\beta / T),
\]

(A9)

\[
S[\{x_j\}, \{y_j\}] = \sum_{j=0}^{T-1} \left(2iS\left(\frac{(y_{j+1} - y_j)x_j - (x_{j+1} - x_j)y_j}{1 + x_j^2 + y_j^2}\right) + \frac{\beta}{T} H^{cl}(\mu_{j+1}, \mu_j)\right) + O(\beta / T).
\]

(A10)

This action is similar to that of [52], but, importantly for our purposes, has no singularities over \( \mathbb{C}^{2T} \). Only when this action is continued to \( \mathbb{C}^{2T} \) will singularities emerge.

To get the continuum limit, which we do not actually use in our analysis, but is nevertheless the most compact and aesthetically pleasing way of presenting the path integral, we then take \( T \rightarrow \infty \) and notice that as \( \delta_j = O(\beta / T) \) by assumption, we can define derivatives with respect to that parameter. Thus, we get that

\[
Z = \int Dx Dye^{-S[x,y]},
\]

(A11)

where

\[
S[x,y] = \int_0^T d\tau \left(2iS\left(\frac{\dot{x}y - \dot{y}x}{1 + x^2 + y^2} + H^{cl}(x,y)\right),
\]

(A12)

and \( H^{cl}(x,y) \equiv H^{cl}(x - iy, x + iy) \).
2. Classical Hamiltonian Elements

One thing that we have not done yet is calculate $H^{cl}(x, y)$ explicitly. To do this, notice that $|\uparrow\rangle = (|+1/2\rangle)^{\otimes 2S}$ and that

$$\hat{S}_- = (\hat{\sigma}_x - i\hat{\sigma}_y) \otimes I^{(2S-1)} + I \otimes (\hat{\sigma}_x - i\hat{\sigma}_y) \otimes I^{(2S-2)} + \cdots + I^{\otimes 2S-1} \otimes (\hat{\sigma}_x - i\hat{\sigma}_y).$$  \hspace{1cm} (A13)

The definition of a spin coherent state is

$$|\mu\rangle = \frac{1}{(1 + |\mu|^2)^S} \exp\{\mu \hat{S}_-\} |\uparrow\rangle.$$  \hspace{1cm} (A14)

Plugging Eq. (A13) and the definition of $|\uparrow\rangle$ into Eq. (A14), we can utilize the commutivity of the terms in Eq. (A13) to get that

$$|\mu\rangle = \frac{1}{(1 + |\mu|^2)^S} \sum_{n=1}^{2S} (\exp\{\mu(\hat{\sigma}_x - i\hat{\sigma}_y)\} |+1/2\rangle).$$

We can write out the state in the spin-1/2 space explicitly, using that $(\hat{\sigma}_x - i\hat{\sigma}_y)^2 = 0$, to obtain that

$$\exp\{\mu(\hat{\sigma}_x - i\hat{\sigma}_y)\} |+1/2\rangle = |+1/2\rangle + \mu |-1/2\rangle.$$

Now, let $\mu \equiv x + iy$, and notice that we can write $\hat{S}_x$, $\hat{S}_y$, and $\hat{S}_\mu$ in the same way as $\hat{S}_-$. Thus, We can use this expression to finally get the classical Hamiltonians corresponding to the spin operators:

$$\hat{S}_x : \ H^{cl}(x, y) = 2S \frac{x}{1 + x^2 + y^2}$$ \hspace{1cm} (A15)

$$\hat{S}_y : \ H^{cl}(x, y) = 2S \frac{y}{1 + x^2 + y^2}$$ \hspace{1cm} (A16)

$$\hat{S}_z : \ H^{cl}(x, y) = S \frac{1 - x^2 - y^2}{1 + x^2 + y^2}.$$ \hspace{1cm} (A17)

3. Multi-particle Systems

Adapting the above derivations to systems with multiple particles is straightforward. Doing so, we get that for an $n$-particle system the path integral is:

$$Z = \int \left( \prod_{j=1}^{n} Dx^{(j)} D\dot{x}^{(j)} \right) e^{-S\{x^{(j)}, \dot{x}^{(j)}\}}$$ \hspace{1cm} (A18)

where

$$S\{x^{(j)}, \dot{x}^{(j)}\} = \int_0^T d\tau \left( 2iS \sum_{j=1}^{n} \frac{\dot{x}^{(j)} x^{(j)} - \dot{x}^{(j)} y^{(j)} y^{(j)} + (y^{(j)})^2 H^{cl}\{x^{(j)}, y^{(j)}\}}{1 + (x^{(j)})^2 + (y^{(j)})^2} \right)$$ \hspace{1cm} (A19)

and $H^{cl}\{x^{(j)}, y^{(j)}\}$ is obtained by replacing $\hat{S}_a$ acting on the $j^{th}$ particle by its corresponding single-particle classical Hamiltonian $H^{cl}\{x^{(j)}, y^{(j)}\}$, i.e.

$$\hat{S}_z \otimes \hat{S}_x \rightarrow \left( S \frac{1 - (x^{(1)})^2 - (y^{(1)})^2}{1 + (x^{(1)})^2 + (y^{(1)})^2} \right) \left( \frac{2S x^{(2)}}{1 + (x^{(2)})^2 + (y^{(2)})^2} \right).$$  \hspace{1cm} (A20)