Tripartite entropic uncertainty relation under phase decoherence

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We formulate the tripartite entropic uncertainty relation and predict its lower bound in a three-qubit Heisenberg XXZ spin chain when measuring an arbitrary pair of incompatible observables on one qubit while the other two are served as quantum memories. Our study reveals that the entanglement between the nearest neighbors plays an important role in reducing the uncertainty in measurement outcomes. In addition we have shown that the Dolatkhah’s lower bound (Phys Rev A 102(5):052227, 2020) is tighter than that of Ming (Phys Rev A 102(01):012206, 2020) and their dynamics under phase decoherence depends on the choice of the observable pair. In the absence of phase decoherence, Ming’s lower bound is time-invariant regardless the chosen observable pair, while Dolatkhah’s lower bound is perfectly identical with the tripartite uncertainty with a specific choice of pair.

In quantum mechanics, the precise instantaneous measurement of two incompatible observables of a quantum system is generally limited by Heisenberg’s uncertainty principle, in which a lower bound in measurement accuracy is given1. After Heisenberg’s work, there have been several attempts to formulate the uncertainty principle in a more comprehensive manner. As an example, Kennard and Robertson2,3 proposed an uncertainty principle for the standard deviation for an arbitrary quantum state $|\psi\rangle$ as follows

$$\Delta X \Delta Z \geq \frac{1}{2} |\langle\psi|[X,Z]|\psi\rangle|, \quad (1)$$

where $\Delta X$ and $\Delta Z$ are the standard deviations of the incompatible observables $X$ and $Z$, respectively. The uncertainty lower bound given by the right-hand side (r.h.s) of Eq. (1) depends on the quantum state under inspection $|\psi\rangle$, and becomes trivial ($= 0$) when $|\psi\rangle$ is one of the eigenstates of $X$ or $Z$. In contemporary quantum information, the standard deviation in the uncertainty principle is usually reformulated by Shannon entropy in the so-called entropic uncertainty relation (EUR)4,5. The EUR of arbitrary two incompatible observables, $X$ and $Z$ takes the form:

$$H(X) + H(Z) \geq \frac{1}{c} \log_2 c \equiv q_{\text{MU}}, \quad (2)$$

where $H(V) = -\sum_v p(v) \log_2 p(v)$ is the Shannon entropy of observable $V$ ($V \in \{X,Z\}$); $p(v)$ is the probability for the measurement outcome $v$, $c$ is the maximal complementarity between $X$ and $Z$, defined by $c = \max_{\{|x_0\rangle,|z_0\rangle\}} |\langle x_0|z_0\rangle|^2$, where $|x_0\rangle$ and $|z_0\rangle$ are eigenvectors of $X$ and $Z$, respectively. The benefit of expression (2) is evident that the lower bound only relates to measured observables, i.e., a state-independent one rather than that given by Eq. (1).

The desire to obtain more accurate measurements led to further improvements in the uncertainty relation. Significant progress has been made in this regard recently by Berta et al.6, by considering a bipartite system, A and B, in which one (A) is under measurement while the other (B) works as a quantum memory. The quantum-memory-assisted entropic uncertainty relation (QMA-EUR) reads

$$S(X|B) + S(Z|B) \geq S(A|B) + q_{\text{MU}}, \quad (3)$$
where \( S(V|B) = S(\rho_{VB}) - S(\rho_{B}) \) (\( V \in \{X,Z\} \)) is the conditional von Neumann entropy of the measurement outcomes (after \( V \) is measured) with \( S(\rho) = -\text{Tr}[\rho \log_2 \rho] \) for some density matrix, \( \rho_{AB} \) and \( \rho_{B} \) are the density matrices for the whole system and subsystem B. The density matrices of post-measurement states are

\[
\rho_{XB} = \sum_i (|x_i\rangle \langle x_i| \otimes I) \rho_{AB}(|x_i\rangle \langle x_i| \otimes I),
\rho_{ZB} = \sum_i (|z_i\rangle \langle z_i| \otimes I) \rho_{AB}(|z_i\rangle \langle z_i| \otimes I)
\]

(4)

Surprisingly, in the scenario that two observers, Alice and Bob may respectively conduct the measurements on subsystems A and B, the QMA-EUR states that the measurements may become less uncertain if A and B are entangled, i.e., \( S(A|B) < 0 \). By observing his own subsystem B, Bob can predict the result of Alice’s measurement on subsystem A, not to mention that the lower bound of uncertainty becomes zero when the subsystems are maximally entangled.

The lower bound of the QMA-EUR was recently made tighter by Adabi et al.5:

\[
S(X|B) + S(Z|B) \geq S(A|B) + q_{MU} + \max\{0, \delta\},
\]

(5)

where a term \( \delta = I(\rho_{AB}) - [I(\rho_{XB}) + I(\rho_{ZB})] \) is added. \( I(\rho_{AB}) \) is the mutual information of A and B, while

\[
I(\rho_{VB}) = S(\rho_{B}) - \sum_i p_i S(\rho_{B}^i), \quad V \in \{X, Z\}
\]

(6)

is the Holevo quantity, which determines the maximum amount of the accessible information about the observable \( V \). Here, when Alice measures the observable \( V \) on the part A, she will obtain an \( i \)-th outcome \( v_i \) with a probability \( p_{v_i} = \text{Tr}[\rho_{AB} P_{v_i}^A \rho_{AB}^H P_{v_i}^H] \), and the corresponding state of Bob will be transformed into \( \rho_{B}^i = \text{Tr}_{A}[P_{v_i}^A \rho_{AB}^H P_{v_i}^H] \).

These new formulations of the uncertainty principle have facilitated the emergence of many potential applications in the field of quantum information, including cryptography14,10, quantum metrology11,12, quantum randomness13,14 and entanglement witness15–18. Much interest has been focused on clarifying how the QMA-EUR evolves in various systems including Heisenberg spin models19–28, Unruh–DeWitt detector model29,30, neutrino oscillations31 and some open quantum systems32,33–35.

Renes and Boileau36 presented the tripartite version of the QMA-EUR, which can be explained by a guessing game (called the monogamy game) played by Alice, Bob, and Charlie, who share a tripartite quantum state \( \rho_{ABC} \). At first, Alice measures her part A by choosing one of the observables \( X, Y, Z \) and obtains an outcome \( \kappa \). Then, informed by Alice with which observable she has measured, Bob and Charlie try to reduce their doubt about Alice’s result as they win when correctly guess her measurement outcome \( \kappa \). In this scenario, the tripartite QMA-EUR takes the form,

\[
S(X|B) + S(Z|C) \geq q_{MU},
\]

(7)

in which the lower bound of uncertainty remains the same regardless any change in the prepared state \( \rho_{ABC} \) since \( q_{MU} \) only depends on the complementarity between A and Z.

Very recently, Ming et al.37 introduced a tighter bound of the tripartite QMA-EUR by adding some terms related to mutual information and Holevo quantity as follows:

\[
S(X|B) + S(Z|C) \geq q_{MU} + \max\{0, \Delta\},
\]

(8)

in which

\[
\Delta = q_{MU} + 2S(\rho^A) - [I(A : B) + I(A : C)] + [I(Z : B) + I(X : C)] - [H(X) + H(Z)],
\]

(9)

where the mutual information \( I(X : C) \) and the Holevo quantity \( I(Z : B) \) are the same as those in Eq. (5), and Shannon entropy \( H(X) \) (\( H(Z) \)) of \( X \) (\( Z \)) measurement. In the same context, Dolatkhah et al.38 have proposed another lower bound of the tripartite uncertainty that is tighter than that suggested by Ming et al. (8) for some states \( \rho_{ABC} \). Their formula reads

\[
S(X|B) + S(Z|C) \geq q_{MU} + \frac{S(A|B) + S(A|C)}{2} + \max\{0, \delta\},
\]

(10)

in which

\[
\delta = \frac{[I(A : B) + I(A : C)]}{2} - [I(X : B) + I(Z : C)].
\]

(11)

In this study, we investigate the dynamical behavior of the tripartite QMA-EUR and its relations to the nearest- and next-nearest-neighbor entanglement in a three-qubit Heisenberg XXZ chain with decoherence. Also, we introduce a comparative study between the lower bound of Ming et al. and that of Dolatkhah et al., as well as how they depend on the choice of incompatible observables.

This paper is arranged as follows: in “Heisenberg model with phase decoherence and its solution”, the theoretical model with phase decoherence and its solution is introduced. The tripartite QMA-EUR, Ming’s bound, and
Dolatkhah’s bound of the proposed model are reported in “The tripartite QMA-EUR” for two different pairs of the incompatible observables. “Conclusions” contains a concise conclusion of our results.

**Heisenberg model with phase decoherence and its solution**

The equation that governs the dynamics of a quantum system described by Hamiltonian $H$ with phase decoherence can be obtained by applying the superoperator $\hat{L}$ to the density matrix $\rho$ as follows

$$\frac{d\rho}{dt} = \hat{L}\rho(t) = -i[H, \rho(t)] - \frac{\gamma}{2} [H, [H, \rho(t)]]$$

(12)

where $\gamma$ is the phase decoherence rate. The system under consideration is a three-qubit Heisenberg XXZ chain in a uniform magnetic field $B$:

$$H = \sum_{n=1}^{2} J(\sigma_n^x \sigma_{n+1}^x + \sigma_n^y \sigma_{n+1}^y) + J_z \sigma_n^z \sigma_{n+1}^z + B \sum_{n=0}^{2} \sigma_n^z,$$

(13)

where $\sigma_n^\alpha (\alpha = x, y, z)$ are Pauli spin matrices for qubit $n$. $J$ and $J_z$ are the spin coupling strengths that we may set $J = 1$ without loss of generality. Our choice of the Heisenberg XXZ spin chain model is justified by the fact that it has quantum simulation applications$^{39-41}$. Furthermore, the XXZ model in a transverse field was recently constructed using magnetic atoms on a surface$^{42}$, proposing that the quantum correlations in such models can be measured experimentally.

The solution of Eq. (12) is

$$\rho(t) = e^{i\mathbf{B}t} \rho(0),$$

(14)

where $\rho(0)$ is the initial density matrix of the system under consideration, and can be expressed as a linear combination of the eigenstates $|\psi_m\rangle$ as $\rho(0) = \sum_{mn} \alpha_{mn} |\psi_m\rangle \langle \psi_n|$. Eigenvectors $|\psi_m\rangle$ and the associated eigenvalues $E_m$ satisfy the eigenvalue equations for $H$, $H|\psi_m\rangle = E_m|\psi_m\rangle (m = 1, 2, \ldots, 8)$. Therefore, the operation of $\hat{L}$ on $|\psi_m\rangle$ is given by,

$$\hat{L}|\psi_m\rangle = -i(E_m|\psi_m\rangle \langle \psi_n| - |\psi_m\rangle \langle \psi_n|E_m)$$

$$- \frac{\gamma}{2} (E_m^2|\psi_m\rangle \langle \psi_n| - 2E_m|\psi_m\rangle \langle \psi_n|E_m + |\psi_m\rangle \langle \psi_n|E_m^2)$$

(15)

In turn, the temporal evolution of $\rho(0)$ takes the form:

$$\rho(t) = \sum_{m,n=1}^{8} \alpha_{mn} \beta_{mn} |\psi_m\rangle \langle \psi_n|,$$

(16)

in which

$$\beta_{mn} = \exp(-it(E_m - E_n)) - \frac{\gamma t}{2} (E_m - E_n)^2$$

(17)

Equation (16) gives a general description of the tripartite state shared by the three qubits for a given time $t$, $\rho_{ABC}(t)$, while the reduced density matrix of any two of the qubits can be obtained by tracing out the other one.

We consider the initial state of the system to be $|\psi(0)\rangle = \frac{1}{\sqrt{2}} (|000\rangle + |110\rangle)$ to determine the tripartite entropic uncertainty relation and its robustness when the measured qubit is maximally entangled with one of the quantum memories. According to this initial state the measured qubit $A$ and the quantum memory $B$ are initially in the maximally entangled state $|\psi(0)\rangle = \frac{1}{\sqrt{2}} (|00\rangle + |11\rangle)$ and the other quantum memory $C$ is initially in $|0\rangle$. Using the notation of basis $|000\rangle, |001\rangle, |011\rangle, |100\rangle, |101\rangle, |110\rangle, |111\rangle$, $\rho_{ABC}(t)$ can be written as

$$\rho_{ABC}(t) = \begin{pmatrix}
A_{11} & 0 & A_{14} & 0 & A_{16} & A_{17} & 0
A_{01} & 0 & 0 & 0 & 0 & 0 & 0
0 & 0 & 0 & 0 & 0 & 0 & 0
A_{41} & 0 & A_{44} & 0 & A_{46} & A_{47} & 0
0 & 0 & 0 & 0 & 0 & 0 & 0
A_{61} & 0 & A_{64} & 0 & A_{66} & A_{67} & 0
A_{71} & 0 & A_{74} & 0 & A_{76} & A_{77} & 0
0 & 0 & 0 & 0 & 0 & 0 & 0
\end{pmatrix},$$

(18)

and the non-vanishing elements are:
\[ A_{14} = \frac{e^{-2i(2B+J_z)}(\gamma)(2B+J_z)+i)}{4} + \sum_{\delta=\pm} 2e^{-\frac{1}{4}(t(4B+3J_z)\eta+\gamma(4B+3J_z)(\eta))} \Delta^2 \]

\[ A_{16} = \sum_{\delta=\pm} e^{-\frac{1}{4}(t(4B+J_z)\eta+\gamma(4B+J_z)(\eta))} \Delta^2 \]

\[ A_{17} = e^{-2i(2B+J_z)\gamma} \cos(2\eta t) + j_x^2 + 6 + \sum_{\delta=\pm} e^{-(4+J_z)\gamma} \cos(\delta \omega t) \]

\[ A_{44} = \frac{e^{-2i\gamma} \cos(2\eta t) + j_x^2 + 6 + \sum_{\delta=\pm} e^{-(4+J_z)\gamma} \cos(\delta \omega t)}{8 + j_x^3} \]

\[ A_{46} = \frac{I_x + \sum_{\delta=\pm} \frac{\eta}{2} \left( e^{-\frac{1}{4}(4+2J_z)\gamma} - e^{-2i\eta(2+\gamma)\gamma} \right) \Delta^2}{8 + j_x^3} \]

\[ A_{47} = e^{-2i\gamma} \cos(2\eta t) - 1 + \sum_{\delta=\pm} i e^{-(4+J_z)\gamma} \sin(\delta \omega t) \]

The tripartite QMA-EUR

Equations (18) and (19) enable us to get the tripartite entropic uncertainty denoted by \( U \), and lower bounds of Ming et al. (8) and Dolatkhah et al. (10), which will be denoted in this study as \( U_{M} \) and \( U_{D} \), respectively. The lower bounds require the calculation of the post-measurement states referred to which pair of incompatible measurements have been performed on qubit A. To show the dependence of the QMA-EUR on the choice of that pair, we will consider two different cases, \( (X, Z) = (\sigma_x, \sigma_z) \) and \( (\sigma_x, \sigma_y) \).

QMA-EUR for \((\sigma_x, \sigma_z)\)-measurement pair. First we consider the case that Alice measures one of the pair \((\sigma_x, \sigma_z)\) on her quantum system. If \( \sigma_x \) is her choice, then Bob has to guess her outcome. If she chooses \( \sigma_z \), Charlie will take the turn. Thereby, one could derive the post-measurement states and the corresponding entropies for the two choices and those of the reduced matrices \( \rho_{AB} = \text{tr}_{C}(\rho_{ABC}) \) and \( \rho_{C} = \text{tr}_{AB}(\rho_{ABC}) \). Hence, the tripartite uncertainty can be expressed as:

\[ U = S(\rho_{AB}) - S(\rho_B) + S(\rho_{AC}) - S(\rho_C) \]

\[ = h_{\text{bin}} \left( 1 - \sqrt{1 - 4\omega} \right) \]

\[ - \sum_i h_{\text{bin}} \left( 1 - 2A_i \right) + \sum_{i=0}^{3} A_i \log_2 A_i + \frac{3}{2} \]

where \( \omega = A_{11}A_{44} + A_{44}A_{66} + A_{11}A_{77} + A_{66}A_{77} - (A_{44}A_{66} + A_{11}A_{77})/(A_{17}A_{16}^*), \) and \( h_{\text{bin}}(\mu) = -\mu \log_2 \mu - (1-\mu) \log_2 (1-\mu) \) is the binary entropy function.

With some simplifications and the fact that the complementarity of any pair of Pauli observables is \( c = \frac{1}{2} \), Ming’s lower bound \( U_{M} \) takes the following form:

\[ U_{M} = 1 + \max(0, \Delta^{(xz)}), \]

\[ \Delta^{(xz)} = 1 + S(\rho_{AB}) + S(\rho_{AC}) - S(\rho_{AB}) - S(\rho_{AC}) - S(\rho_{AB}) \]

The von Neumann entropies \( S(\rho) \) could be calculated by using the eigenvalues (noted by \( \lambda_i \)) of \( \rho \) as follows:
\[
S(\rho_{\alpha}) = \sum_{i=1}^{4} \beta_{i}^{\alpha} \log_{2} \beta_{i}^{\alpha}, \quad (\alpha = AB, AC),
\]
\[
S(\rho_{\alpha, C}) = h_{\text{bin}} \left( 1 - \frac{\sqrt{1 - 4\sigma}}{2} \right) + 1,
\]
\[
S(\rho_{\alpha, h}) = \frac{1}{2} \sum_{i=4,6,7} A_{ii} \log_{2} A_{ii},
\]
where \(\beta_{i}^{AB} = \frac{1}{2} [A_{11} + A_{22} \pm \sqrt{(A_{11} - A_{22})^2 + 4|A_{12}|^2}],\)
\(\beta_{i}^{AC} = \frac{1}{2} [A_{11} + A_{66} \pm \sqrt{(A_{11} - A_{66})^2 + 4|A_{16}|^2}],\)
\(\beta_{i}^{BC} = \frac{1}{2} [A_{44} + A_{77} \pm \sqrt{(A_{44} - A_{77})^2 + 4|A_{47}|^2}],\) and
\(\rho = A_{11}A_{44} + A_{16}A_{76} + A_{46}A_{74} - (A_{17}A_{46} + A_{16}A_{74}).\)

For the same observables, \(\sigma_{x}\) and \(\sigma_{z}\), Dolatkhah's lower bound \(U_{D}\) can be written as:
\[
U_{D} = 1 + \frac{S(\rho_{AB}) + S(\rho_{AC}) - S(\rho_{B}) - S(\rho_{C})}{2} + \max[0, \delta^{(xz)}],
\]
\[
\delta^{(xz)} = \frac{2S(\rho_{A}) + S(\rho_{B}) + S(\rho_{C}) - [S(\rho_{AB}) + S(\rho_{AC})]}{2} - [I(X : B) + I(Z : C)],
\]
where
\[
I(X : B) = h_{\text{bin}} \left( 1 - \frac{2A_{66}}{2} \right) - h_{\text{bin}} \left( 1 - \frac{\sqrt{1 - 4\sigma}}{2} \right),
\]
\[
I(Z : C) = \sum_{i=4,6,7} h_{\text{bin}} \left( 1 - \frac{2A_{ii}}{2} \right) + \sum_{i=4,6,7} A_{ii} \log_{2} A_{ii}.
\]

Again, the von Neumann entropies of the reduced density matrices \(\rho_{A}, \rho_{B}\), and \(\rho_{C}\) are:
\[
S(\rho_{A}) = h_{\text{bin}}(1/2 - A_{44}), \quad S(\rho_{B}) = h_{\text{bin}}(1/2 - A_{66}), \quad S(\rho_{C}) = h_{\text{bin}}(1/2 - A_{77}).
\]

The great relevance between bipartite QMA-EUR and quantum correlation encouraged us to include entanglement in our study, by considering the residual entanglement to quantify simultaneous entanglement between all qubits in a multi-qubit system. For a three-qubit system, the residual entanglement can be expressed as:
\[
\pi_{ABC} = \frac{1}{3} (\pi_{A} + \pi_{B} + \pi_{C}),
\]
\[
\pi_{A} = N_{A}^{ABC} - N_{AB}^{2} - A_{AC}^{2},
\]
\[
\pi_{B} = N_{B}^{ABC} - N_{BA}^{2} - A_{BC}^{2},
\]
\[
\pi_{C} = N_{C}^{ABC} - N_{CA}^{2} - A_{CB}^{2},
\]
where the negativity of tripartite and bipartite systems can be expressed, respectively, as \(N_{\alpha\beta} = \|\rho_{\alpha\beta}\| - 1\) and \(N_{\alpha}(\rho_{\alpha'}) = \|\rho_{\alpha\beta'}^{\alpha}\| - 1\), \(\|\rho\| = \text{tr}[\sqrt{\rho^{2}}]\) is the trace norm of \(\rho\), \(\rho_{\alpha'}^{\alpha}\) represents the partial transpose of \(\rho\) with respect to the qubit \(\alpha\).

Figure 1 displays the dynamics of \(U_{f}, U_{M}\), and \(U_{D}\) for the case without decoherence, \(\gamma = 0\). The residual entanglement, \(\pi_{ABC}\), and bipartite entanglement, \(N_{\alpha\beta}\), are also included.

One can observe that all quantities, except \(U_{M}\), oscillate periodically with the growth of time \(t\). The three bipartite negativities, \(N_{AB}, N_{BC}, N_{AC}\), exhibit different behaviors in such a way that nearest-neighbor entanglements, \(N_{AB}\) and \(N_{BC}\), evolve oppositely, namely if one is maximum, the other is zero. In contrast, the next-to-nearest neighbor entanglement, \(N_{AC}\), is modulated the same as the residual entanglement (\(\pi_{ABC}\)) with a different amplitude. On the other hand, the time variations of \(U_{f}, U_{M}\), and \(U_{D}\) can be summarized in the following points:

- Regardless of the \(J_{z}\) value, the entropic uncertainty perfectly corresponds to the residual entanglement, indicating that the uncertainty in the measurement outcome increases with the overall entanglement of the system.
- Interestingly, it can be observed that the oscillation of \(U_{D}\) is completely identical to that of \(U_{f}\), while \(U_{M}\) freezes at a lower value 1. This indicates that Dolatkhah's lower bound is tighter than Ming's lower bound and can be used to express entropic uncertainty. This conclusion is confirmed for various \(J_{z}\) values when \((\sigma_{x}, \sigma_{z})\) is the pair of the incompatible observables as shown in Figs. 2 and 3.
- \(U_{f}\) and therefore \(U_{D}\), reaches its minima if either pair of nearest-neighbor qubits is maximally entangled. Their oscillation frequency increases with \(J_{z}\).
The dynamics of all quantities in various magnetic fields is shown in Fig. 2. Despite the fact that the quantum entanglement does not change with $B$, the fluctuation of the entropic uncertainty $U$ increases significantly with $B$. This indicates that the entropic uncertainty is not necessarily synchronized with the entanglement in all circumstances. In addition, the freezing of $U_M = 1$ was not violated by the presence of a magnetic field, similar to what has been found in Fig. 1. Also, the assertion that minimal $U = U_D = 1$ is associated with the maximum entanglement between one of the nearest-neighbor qubit pair remains valid.

Our discussion will now focus on the decoherence effects on the tripartite entropic uncertainty and its lower bounds. As what can be easily seen in Fig. 3, the decoherence eliminates the regular oscillatory behaviors of $U$, $U_D$, and all entanglement measures after some time related to $\gamma$. Also, the presence of the intrinsic decoherence breaks the frozen behavior of $U_M$, which shows a damped oscillation similar to that of $U$ and $U_D$. There are some other findings similar to what aforementioned including: $U$ and $U_D$ are identical, $U$ and $\pi_{ABC}$ are synchronized, and the minimum of $U$ corresponds to the maximum of $N_{AB}$ or $N_{BC}$ Finally, it can be concluded that $U$, $U_M$ and $U_D$ evolve together into the same steady maxima as there is diminishing quantum entanglement between the qubits resulting from a greater $B$ and $\gamma$ as shown in Fig. 3b,d.

The persistent overlapping between $U$ and $U_D$ illustrated in the previous figures can be shown as follows: According to Eq. (10), Dolatkah's bound can be expressed as:

$$U_D = q_{MU} + \frac{S(A|B) + S(A|C)}{2} + \delta,$$

(27)

and can be further simplified as (Eq. 23):

$$U_D = 1 + S(\rho_A) - [I(X : B) + I(Z : C)].$$

(28)

With the measurement pair $(\sigma_x, \sigma_z)$, the information amount that Alice shares with Bob and Charlie, $I(X : B)$ and $I(Z : B)$ are explicitly given by Eq. (24). Inserting these values and $A_{11} = \frac{1}{2}$ into Eq. (28), one can finally get:
In this section, we consider that Alice chooses the observables pair \((\sigma_x, \sigma_y)\). The tripartite uncertainty in this scenario can be expressed as:

\[
\mathcal{U} = \frac{\sqrt{1 - 4\omega^2}}{2} \sum_{i=6,7} h_{\text{bin}} \left(1 - 2A_{ii}\right)^2 \right) + \sum_{i=6,7} A_{ii} \log_2 A_{ii} + \frac{3}{2}
\]

\[
\Rightarrow \mathcal{U}.
\]

**QMA-EUR for \((\sigma_x, \sigma_y)\)-measurement pair.** In this section, we consider that Alice chooses the observables pair \((\sigma_x, \sigma_y)\). The tripartite uncertainty in this scenario can be expressed as:

\[
\mathcal{U} = S(\rho_{\sigma_x B}) - S(\rho_B) + S(\rho_{\sigma_y C}) - S(\rho_C)
\]

\[
= \sum_{\alpha=0,\sigma} h_{\text{bin}} \left(1 - \sqrt{1 - 4\alpha^2}\right) - \sum_{i=6,7} h_{\text{bin}} \left(1 - 2A_{ii}\right)^2 + 2,
\]

where \(\omega\) and \(\sigma\) are the same as those in Eqs. (20) and (21), respectively.

On the other hand, Ming's and Dolatkhah's lower bounds remain the same forms as those for \((\sigma_x, \sigma_z)\) measurement pair by simply replacing \(\Delta^{(xz)}\) by \(\Delta^{(sy)}\) and \(\delta^{(sy)}\), respectively:

\[
\Delta^{(sy)} = 1 + S(\rho_{AB}) + S(\rho_{AC}) - S(\rho_{\sigma_x B}) - S(\rho_{\sigma_y C}) - [S(\rho_{\sigma_y A}) + S(\rho_{\sigma_y C})]
\]

\[
\delta^{(sy)} = \frac{2S(\rho_A) + S(\rho_B) + S(\rho_C) - [S(\rho_{AB}) + S(\rho_{AC})]}{2} - I(X : B) + I(Y : C).
\]
in which

\[ S(\rho_{\sigma_zB}) = h_{\text{bin}} \left( \frac{1 - \sqrt{1 - 4\omega^2}}{2} \right) + 1, \]

\[ I(Y : C) = S(\rho_C) - h_{\text{bin}} \left( \frac{1 - \sqrt{1 - 4\vartheta^2}}{2} \right). \]

(32)

Other von Neumann entropies and the Holevo quantity \( I(X : B) \) are the same as those in the case of \((\sigma_x, \sigma_z)\) pair.

The results for \( B = 0 \) and \( B = 2 \) are respectively shown in Figs. 4, 5. Comparing with the results for \((\sigma_x, \sigma_z)\) case shown in Figs. 1, 2 and 3 one can easily conclude that the tripartite QMA-EUR and the two bounds do depend on the choice of measurement pair. The only exception \( U_M = 1 \) occurs in the special case \( \gamma = 0 \) regardless of which pair is chosen. In addition, unlike the results for \((\sigma_x, \sigma_z)\), \( U \) and \( U_D \) are no longer the same but \( U \geq U_D \) still holds for \((\sigma_x, \sigma_z)\).

Figure 4 shows the dynamics of all quantities for various decoherence rates \( \gamma \) at \( J_z = 0 \). It can be seen that the entropic uncertainty \( U \) is related to \( N_{AB} \) and \( N_{BC} \) rather than \( N_{AC} \) and \( \pi_{ABC} \). The minimum of \( U \) is associated with the maximum of \( N_{AB} \) and the minimum of \( N_{BC} \). A closer inspection reveals that there is a tiny anomaly in the \( \gamma = 0 \) case (Fig. 4a), in which \( N_{AB} \) exhibits one more peaks per period than \( U \).

The importance of nearest-neighbor entanglement asserts that the best guess on the measurement outcomes can be obtained when Alice is maximally entangled with Bob but not with Charlie. We can also state that the measurement accuracy is affected by the choice of measured observables, since the best guess occurs when either nearest neighbors are maximally entangled for the \((\sigma_x, \sigma_z)\) choice, but not for the other.
The presence of the magnetic field $B$ changes the way the $U$, $U_M$, and $U_D$ oscillate, as shown in Fig. 5. It also assists the decay of entanglement between system components with a finite $\gamma$, thus shortens the time $U$, $U_M$, and $U_D$ saturate to a fixed maximum compared to that for $B = 0$.

Regardless of the various cases in our study, Dolatkhah's bound is tighter than Ming's and the inequality $2 \geq U \geq U_D \geq U_M \geq 1$ always holds.

Conclusions

We have investigated the dynamical characteristic of the tripartite QMA-EUR and its lower bounds in a three-qubit Heisenberg XXZ spin chain under intrinsic decoherence. The relationship between tripartite uncertainty and quantum entanglement between system components has been also investigated using tripartite and bipartite negativities. The results clearly confirm the dependence of the tripartite uncertainty on the choice of observable pair that Alice would measure. We showed that an inequality for the tripartite uncertainty, $2 \geq U \geq U_D \geq U_M \geq 1$ always holds and Dolatkhah's lower bound $U_D$ is identical to the tripartite uncertainty, $U = U_D$, with the complementary measurements pair $(\sigma_x, \sigma_z)$. When there is no intrinsic decoherence, Ming's lower bound $U_M = 1$ is always fixed as the time evolves with any choice of Pauli measurement pair. We have also verified that the connection between uncertainty and the quantum entanglement between the system components would change with the choice of incompatible observables: for the pair $(\sigma_x, \sigma_z)$, the best measurement accuracy occurs when the nearest neighbors are maximally entangled, while for $(\sigma_x, \sigma_y)$ the best measurement accuracy can be obtained when Alice is maximally entangled with Bob. Our results provide a better understanding of the lower bounds of the tripartite QMA-EUR which are crucial in improving quantum measurements in quantum information processing.
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Author contributions

R.A.A. and A.-B.A.M. prepared all figures and performed the mathematical calculations. M.T. and R.A.A. wrote the original draft. H.E. and W.K. reviewed and edited the draft. All authors have read and agreed to the published version of the manuscript.

Competing interests

The authors declare that they have no known competing financial interests or personal relationships that could have appeared to influence the work reported in this paper. Also, we do not have any conflict with the authors.

Additional information

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