Multiple Positional Self-Attention Network for Text Classification

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Abstract
Self-attention mechanisms have recently caused many concerns on Natural Language Processing (NLP) tasks. Relative positional information is important to self-attention mechanisms. We propose Faraway Mask focusing on the \((2m+1)\)-gram words and Scaled-Distance Mask putting the logarithmic distance punishment to avoid and weaken the self-attention of distant words respectively. To exploit different masks, we present Positional Self-Attention Layer for generating different Masked-Self-Attentions and a following Position-Fusion Layer in which fused positional information multiplies the Masked-Self-Attentions for generating sentence embeddings. To evaluate our sentence embeddings approach Multiple Positional Self-Attention Network (MPSAN), we perform the comparison experiments on sentiment analysis, semantic relatedness and sentence classification tasks. The result shows that our MPSAN outperforms state-of-the-art methods on five datasets and the test accuracy is improved by \(0.81\%\), \(0.6\%\) on SST, CR datasets, respectively. In addition, we reduce training parameters and improve the time efficiency of MPSAN by lowering the dimension number of self-attention and simplifying fusion mechanism.

Introduction
Context representation provides critical information in Natural Language Processing (NLP) tasks. For different tasks and data, there are two commonly used architectures: Convolutional Neural Networks (CNN) (Kim 2014) and Recurrent Neural Networks (RNN) (Chung et al. 2014). RNN captures long-range dependencies through sequential architecture while CNN captures phrase features by encoding \(n\)-grams. More recently, attention mechanisms have been widely used in NLP tasks, such as neural machine translation (Luong, Pham, and Manning 2015) and sentiment analysis (Kokkinos and Potamianos 2017) etc. In contrast to RNN and CNN, attention mechanisms (Bahdanau, Cho, and Bengio 2015) allow modeling of dependencies without regard to the distances of the words in the input or output sequences (Kim et al. 2017).

As a variant of attention mechanism, self-attention has been used successfully in a variety of tasks including reading comprehension (Cheng, Dong, and Lapata 2016) and abstractive summarization (Parikh et al. 2016) etc. Recently, self-attention was used to replace RNN in context-aware encoding for learning long-range dependencies (Vaswani et al. 2017). The ability to learn long-range dependencies is affected by the length of the paths along which the forward and backward signals propagate in the network. The shorter path between tokens is, the easier it is to learn long-range dependency (Hochreiter et al. 2001), and self-attention works well in learning long-range dependencies (Vaswani et al. 2017).

However, there are two issues of self-attention mechanism to be addressed. One is that contrast to RNN, self-attention treats all input tokens as identical individuals and loses the temporal order information (Shen et al. 2018a), which might be important to the NLP tasks. Another is that the positional information is lost, i.e. self-attention does not take into account different importance to the tokens of different distances. For instance, adjacent words contribute more semantically to current phrase than distant ones (Guo, Zhang, and Liu 2019).

To address the first issue, there is a way of adding directional masks to furnish temporal order information (Shen et al. 2018a), but it didn’t consider positional information. About the second issue, we roughly classify several methods into two categories: adaptive positional information method (Gehring et al. 2017) and pre-tuned positional information method (Guo, Zhang, and Liu 2019). Compared to adaptive positional information method, the pre-tuned method can’t extract different positional information for different sentences. While compared to pre-tuned method, adaptive method lacks scalability. And all these pre-tuned methods and adaptive methods only explore positional information and overlook the temporal order information.

Therefore, we combined the adaptive and the pre-tuned positional information methods, temporal order information and positional information into a single model to benefit each other and to overcoming their inherent disadvantages. In our MPSAN, we designed two new masks that focus on distance information. And to integrate different masks containing different temporal order and positional information, we proposed a new Position-Fusion Layer with 3.24million fewer parameters than the Fusion Gate in DISAN (Shen et al. 2018a).

In general, our contributions are four-fold:

- We proposed two new positional masks: Faraway Mask which focuses only on the \((2m+1)\)-gram words and ig-
nores the influence of the word itself, and Scaled-Distance Mask which puts the logarithmic distance punishment. The two masks avoid and weaken the self-attention of distant words, respectively.

- We presented the Position-Fusion Layer which generates a weighted sum of Masked-Self-Attentions and Tokens-Position-Weight. This layer could balance the impact among different masks, and would make the combination of the masks more suitable for the current sentence adaptively.

- We reduced training parameters by lowering the dimension number of self-attention and designing a novel fusion mechanism with softmax function in Positional Self-Attention Layer and Position-Fusion Layer respectively, and achieved higher test accuracy at the same time.

- We evaluated our MPSAN on sentiment analysis, semantic relatedness and sentence classification tasks. The results show that our MPSAN achieves better performances than the state-of-the-art self-attention based models on SST, CR datasets, with the test accuracies improved by 0.81%, 0.6%, respectively.

Related Work
As mentioned before, self-attention loses temporal order information and positional information, which might be crucial and has attracted many researchers to study.

To encode temporal order information into attention-based models, Shen et al. proposed directional mask in Directional Self-Attention Network (DiSAN) (Shen et al. 2018a). In DiSAN, by adding the forward and backward directional masks to the logit of self-attention, words in a specific direction in the sentence were masked to avoid self-attention. In forward mask, there was only attention of later token \( j \) to early token \( i \), and vice versa in backward mask, which achieved the injection of temporal order information. Recently, Shen et al. has developed the Reinforced Self-Attention Network (ReSAN) (Shen et al. 2018b), in which reinforcement learning was used to select tokens from two copies (head tokens and dependent tokens) of the input sequence in parallel. Furthermore, ReSAN used self-attention to model the sparse dependencies between the head and dependent tokens. In a nutshell, the reinforcement learning in ReSAN is employed to catch the temporal order information between tokens. However, the two models above all didn’t consider positional information.

To inject positional information, there has been several ways, which can be roughly classified into two categories: adaptive positional information method and pre-tuned positional information method. The adaptive positional information method represents positional information by some trainable variables. For example, Gehring et al. proposed an entirely convolutional and attentional architecture (Gehring et al. 2017), and to capture positional information, they designed the position embeddings represented by a trainable embedding matrix. The empirical result shows that the position embeddings benefit their architecture. And Shaw et al. also proposed relative position encoding by adding two trainable vectors to self-attention to model localness (Shaw, Uszkoreit, and Vaswani 2018).

However, there are two possible defects with adaptive positional information method. One is obviously the loss of order information (Shen et al. 2018a), which also applies in the following pre-tuned method. In Gehring’s model, adding position embeddings only plays a role in distinguishing different sequence positions. Another is the lack of scalability (Vaswani et al. 2017), which will occur when the well-trained models deal with longer sentences that have never been processed. As a result, the words at the end of the sentence will be randomly assigned positional information.

By contrast, pre-tuned positional information method represents positional information by a variable which could not be altered in training progress. Based on Gehring’s adaptive position embeddings, Vaswani et al. used the \( \text{sine} \) and \( \text{cosine} \) functions to generate position embeddings (Vaswani et al. 2017). And motivated by DISAN, Im et al. proposed Distance Mask (Im and Cho 2017), which considers the words’ relative distance information through adding distance-based punishment. The empirical result showed that Distance Mask achieves a better performance on long sentences. More recently, Yang et al. and Guo et al. introduced a Gaussian prior to self-attention, in which adjacent words contributed more semantically to central words (Yang et al. 2018) (Guo, Zhang, and Liu 2019). The former is effective on NMT tasks, while the latter achieves new SOTA performance on NLI tasks. Yang et al. also proposed a novel Convolutional Self-Attention Network (CSAN) to capture neighboring dependencies (Yang et al. 2019).

Although we have seen several ways from above to fetch positional information and temporal order information from sentences, how to integrate different positional information is also very important to sentence representation. To realize information fusion, Shen et al. (Shen et al. 2018a) and Im et al. (Im and Cho 2017) all designed a Fusion Gate, where they used \( \text{sigmoid} \) function to combine the Masked-Self-Attention output and the hidden state. And then the concatenation of Backward and Forward self-attentions is used as input to the Multi-Dimensional Attention, which is 3-layer fully connected structure with unchanged size of hidden nodes and constant size of output nodes. Apparently, this way brings about too many parameters and can be optimized.

Multiple Positional Self-Attention Network
Overall Architecture
An overview of MPSAN is illustrated in Figure 1. Given an input sentence, we first use pre-trained word embeddings to obtain the embedding representation. Then the embedding representation is utilized by the Positional Self-Attention Layer to obtain multiple positional representations for one sentence through applying different masks on self-attention including Faraway Mask, Backward Mask, Distance Mask and Scaled-Distance Mask. The multiple positional representations are passed to the Position-Fusion Layer, and their weighted sum is treated as the sentence embeddings. Finally, a multi-dimensional attention is employed

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before a softmax classifier.

![Figure 1: Structure of the MPSAN](image1.png)

**Positional Self-Attention Layer**

The Positional Self-Attention Layer is composed by multiple Masked Positional Self-Attention units, which is illustrated in Figure 2. Before computing self-attention, we apply the linear function with an activation to calculate the sentence dense representation $h$, defined as formula (1):

$$h = [h_1, h_2, \ldots, h_n] = \sigma(W_T h w + b_h)$$  \hspace{1cm} (1)

where $W_h \in \mathbb{R}^{d_h \times d_h}$ and $b_h \in \mathbb{R}^{d_h}$ are trainable variables, $T$ is the transpose operation, $d_h$, $d_h$, and $n$ are the size of word embeddings, the size of hidden nodes and the number of words, respectively. $w = [w_1, w_2, \ldots, w_n]$ denotes the dense representation of the input sentence and $\sigma(\cdot)$ indicates activation function.

![Figure 2: Masked Positional Self-Attention](image2.png)

Given the embedding representation of a source sequence $h = [h_1, h_2, \ldots, h_n]$, a score between $h_i$ and $h_j$ is computed by a compatibility function $f(h_i, h_j)$, which measures the dependency between $h_i$ and $h_j$, or the self-attention of $h_j$ to $h_i$. Then the scores $[f(h_i, h_j)]_{i=1}^n$ are mapped to the probability distribution $p(z|h_j)$ for a given $h_j$ by a softmax function. Here $p(z = i|h_j)$ indicates the importance of $h_i$ to $h_j$ where $z = i$. In a word, large $p(z = i|h_j)$ means $h_i$ affects more on $h_j$, which makes it possible to extract the relationship between word pairs without the limitation of distance. The above process can be summarized by the following formulas (2), (3), (4).

$$p(z|h_j) = \text{softmax}([f(h_i, h_j)]_{i=1}^n)$$ \hspace{1cm} (2)

$$s_j = \sum_{i=1}^n p(z = i|h_j) h_i = E_{i \sim p(z|h_j)}(h_i)$$ \hspace{1cm} (3)

$$\text{Self-Attention} = [s_1, s_2, \ldots, s_n]$$ \hspace{1cm} (4)

The formulas (2), (3), (4) can be summarized as (5):

$$\text{Self-Attention}(h) = \left[ \sum_{i=1}^n \frac{\exp(f(h_i, h_j)) h_i}{\sum_{k=1}^n \exp(f(h_k, h_j))} \right]_{j=1}^n$$ \hspace{1cm} (5)

There are several types of self-attention, and they share the same form of self-attention, but are different in the compatibility function $f(h_i, h_j)$. In our MPSAN, the compatibility function is defined by formula (6):

$$f(h_i, h_j) = \sigma((Uh_i + Vh_j + b)/c)$$ \hspace{1cm} (6)

where $U, V \in \mathbb{R}^{d_h}$, $b \in \mathbb{R}$ are trainable parameters, $c$ is a hyper-parameter and it can be $\|h_i\| \cdot \|h_j\|$ or a constant. In our model, we set $c = 5$ to obtain stable output.

**Positional Masks**

The positional masks are applied to discard some elements in specific locations of self-attention by adding $-\infty$ to the compatibility functions.

Then the Masked-Self-Attention (MSA) can be written as formula (7):

$$s = \text{MSA}(h) = \sum_{i=1}^n \frac{\exp(f(h_i, h_j) + M_{ij}) h_i}{\sum_{k=1}^n \exp(f(h_k, h_j) + M_{kj})}$$ \hspace{1cm} (7)

If $M_{ij} = -\infty$, we have $p(z = i|h_j) = 0$, so the self-attention of $h_i$ to $h_j$ is not considered. By doing that, we can focus on the special pairs of words which we are interested in.

Here are five types of the positional mask we considered in our MPSAN.

**Faraway Mask** The Faraway Mask $M_{ij}^{fa(m)}$, shown as formula (8), focuses on the $(2m + 1)$-gram words, and ignores the influence of the word itself.

$$M_{ij}^{fa(m)} = \begin{cases} 0 & \text{if } |i-j| \leq m, i \neq j \\ -\infty & \text{otherwise} \end{cases}$$ \hspace{1cm} (8)

**Backward Mask** The Backward Mask $M_{ij}^{bw}$, shown as formula (9), prevents words that appear after the target word.

$$M_{ij}^{bw} = \begin{cases} 0 & \text{if } i < j \\ -\infty & \text{otherwise} \end{cases}$$ \hspace{1cm} (9)

**Forward Mask** The Forward Mask $M_{ij}^{fw}$, shown as formula (10), is the same with the Backward Mask except different direction.

$$M_{ij}^{fw} = \begin{cases} 0 & \text{if } i > j \\ -\infty & \text{otherwise} \end{cases}$$ \hspace{1cm} (10)
**Distance Mask** The Distance Mask $M^d_{ij}$, shown as formula (11), adds the distance punishment to the self-attention. The punishment score between the $i$th word and the $j$th word is defined by $-|i - j|$.

$$M^d_{ij} = \begin{cases} -|i - j| , & i \neq j \\ 0 , & \text{otherwise} \end{cases}$$ (11)

**Scaled-Distance Mask** In contrast to Distance Mask, the Scaled-Distance Mask adopts $-\log |i - j|$ for punishment score between the $i$th word and the $j$th word, shown as formula (12). This logarithmic distance is steep when $i$ and $j$ are close and is smooth when $i$ and $j$ are distant. By adding Scaled-Distance Mask to the compatibility function, the farther the word pair is, the smaller the self-attention. It means, as the distance from the target word increases, the influence of nearby words has a significant decline, and the influence of distant words is almost the same.

$$M^sd_{ij} = \begin{cases} -\log |i - j| , & i \neq j \\ 0 , & \text{otherwise} \end{cases}$$ (12)

Because of the Distance Mask and Scaled-Distance Mask are the penalties of self-attentions, we will not use them independently, instead, we will apply multiple masks through adding $M_{ij}$ to $f(h_i, h_j)$. For example, $s^f(a^{(m)}+sd)$ indicates using (2m + 1)-gram Faraway Mask and Scaled-Distance Mask on self-attention in the same time.

Our MPSAN applies two Faraway Masks $M^f(a^{(2)}), M^f(a^{(3)})$, Backward Mask $M^bw$ and Forward Mask $M^fw$. In addition, Scaled-Distance Mask $M^sd$ is added in Backward/Forward Mask.

**Position-Fusion Layer**

Since different positional information has been extracted in Positional Self-Attention Layer, the fusion of different positional information could be important to sentence representation. We supposed that every word in a sentence has a certain positional information and the representation $w$ of original input sentence contains the most abundant positional information. So here we use softmax function to extract the positional information from original input tokens, which we called Tokens-Position-Weight, shown as formula (13):

$$a = \text{softmax}(W^T_F w + b_F)$$ (13)

where $w \in \mathbb{R}^{d_w \times n}$ is the sentence representation composed of word embeddings, $W_F \in \mathbb{R}^{d_w \times k}$ and $b_F \in \mathbb{R}^{k \times n}$ are the weight and bias of the Position-Attention Layer, $k$ is the number of multiple self-attentions. The softmax function is applied on each column of $W^T_F w + b_F$.

The output of Position-Fusion Layer is a weighted sum of Masked-Self-Attentions and Tokens-Position-Weight, which is represented by formula (14).

$$o = [s^{(1)}; s^{(2)}; \cdots; s^{(k-1)}; w] \ast a$$ (14)

where $s^{(1)}; s^{(2)}; \cdots; s^{(k-1)} \in \mathbb{R}^{d_w \times n}$ are the multiple Masked-Self-Attentions from Positional Self-Attention Layer, $w \in \mathbb{R}^{d_w \times n}$ is the sentence representation composed of word embeddings, and $a$ is the Tokens-Position-Weight in (13). In practice, we set $d_w = d_h$ to make $s^{(1)}; \cdots; s^{(k-1)}$ and $w$ can be weighted together, and the output $o \in \mathbb{R}^{d_h \times n}$.

We supposed the self-attention results have multiple information in different dimensions, so we use $d_h$ groups of (13). Considering we have decided the combination of different masks in subsection 'Positional Self-Attention Layer', we have $a \in \mathbb{R}^{d_h \times n}$. The rewriting of formula (13), (14) are as follows:

$$a = \text{softmax}(W^T_F w + b_F)$$ (15)

$$o = [s^{f(a^{(2)})}; s^{f(a^{(3)})}; s^{bw+sd}; s^{fw+sd}; w] \ast a$$ (16)

where $w \in \mathbb{R}^{d_w \times n}$ is the sentence representation composed of word embeddings, $W_F \in \mathbb{R}^{d_w \times d_h}$ and $b_F \in \mathbb{R}^{d_h \times n}$ are the weight and bias of the Position-Fusion Layer, and $a$ is in $\mathbb{R}^{d_h \times n}$, $s^{f(a^{(2)})}, s^{f(a^{(3)})}, s^{bw+sd}, s^{fw+sd} \in \mathbb{R}^{d_h \times n}$ are four results of Masked-Self-Attentions. Finally, $o \in \mathbb{R}^{d_h \times n}$ is the weighted sum.

**Experiments and Results**

We evaluate our model on six datasets including one sentiment analysis task and four sentence classification tasks and one semantic relatedness task.

| Model                        | $|\theta|$ | T(s) | Test Acc(%) |
|------------------------------|-----------|------|-------------|
| RNN$^a$                      | -         | -    | 43.2        |
| MV-RNN$^a$                   | -         | -    | 44.4        |
| RNTN$^a$                     | -         | -    | 45.3        |
| Bi-LSTM$^b$                  | -         | -    | 49.8        |
| Tree-LSTM$^c$                | -         | -    | 51.0        |
| CNN-non-static$^d$           | -         | -    | 48.0        |
| CNN-Tensor$^e$               | -         | -    | 51.2        |
| BLSL$^f$                     | -         | -    | 51.1        |
| LR-Bi-LSTM$^g$               | -         | -    | 50.6        |

Self-Attention Based Models

| Model                        | $|\theta|$ | T(s) | Test Acc(%) |
|------------------------------|-----------|------|-------------|
| Multi-head-SAN$^h$           | 1.5m      | 432  | 49.41       |
| Bi-LSTM-SAN$^h$              | 2.2m      | 1704 | 49.95       |
| DiSAN$^h$                    | 1.8m      | 485  | 51.72       |
| Bi-BloSAN$^i$                | 2.2m      | 425  | 51.49       |

Our MPSAN                     | 1.1m      | 359  | **52.53**   |

Table 1: SST results. $|\theta|$: the number of parameters (million level, not including word embedding part). T(s): average seconds per epoch. Test Acc(%): the accuracy on test set. "-" indicates that the data is not mentioned in the corresponding paper. The test accuracies of DiSAN, Bi-BloSAN and our MPSAN are the best results of ten runs, while other accuracies are extracted from the corresponding papers. The number of parameters and the average seconds per epoch of self-attention based models are obtained by the single run of their source codes. $^a$ (Socher et al. 2013), $^b$ (Li et al. 2015), $^c$ (Tai, Socher, and Manning 2015), $^d$ (Kim 2014), $^e$ (Lei, Barzilay, and Jaakkola 2015), $^f$ (Teng, Vo, and Zhang 2016), $^g$ (Qian et al. 2016), $^h$ (Shen et al. 2018a), $^i$ (Shen et al. 2018c).
For all tasks except semantic relatedness task, we use the pre-trained vectors GloVe-6B-300D (Pennington, Socher, and Manning 2014) to initialize word embeddings in our MPSAN. As for Out-Of-Vocabulary (OOV) words in training set, we use uniform distribution between (−0.05, 0.05) to initialize those words randomly. We set the hidden units number to 300, which is equal to the word embedding size. All weight matrices in our model are initialized by Xavier (Glorot and Bengio 2010) initialization and all biases are zero-initialized. We add dropouts between the layers of our model, and the dropout-ratio is 0.7. All the activation functions σ(·) are Exponential Linear Unit (ELU) if they are not specified. We use the sum of cross-entropy loss and L2 regularization penalty as our loss function, and the L2 regularization decay factor is $10^{-7}$. As for learning method, we use Adadelta, which is an optimizer of stochastic gradient descent, to minimize the loss function. The batch size of training is 64 and the learning rate is 0.5. All the training progress is completed on a single NVidia GTX-1080Ti GPU card with TensorFlow-1.4.0.

While in the semantic relatedness task, the loss function is the sum of KL-divergence and L2 regularization penalty. The dropout is set to 0.55, the L2 regularization weight decay factor is $5 \times 10^{-4}$, and the learning rate is set to 0.7. The word embeddings and other network parameters are the same as other tasks.

### Sentiment Analysis

The aim of sentiment analysis is to identify the emotion of a sentence. We use Stanford Sentiment Treebank (SST) for sentiment analysis (Socher et al. 2013). SST consists of 8544/1101/2210 (train/dev/test) sentences with five fine-grained labels including very positive, positive, neutral, negative and very negative.

Compared the test accuracy from the official leaderboard of SST in Table 1, MPSAN improves the best test accuracy of attention based models (achieved by DiSAN) by a significant gap of 0.81%. Moreover, we compare MPSAN with RNN-based models, including RNN, MV-RNN, RNTN, Bi-LSTM and Tree-LSTM, and MPSAN outperforms them by 9.33%, 8.13%, 6.83%, 2.73%, 1.53%, respectively. Furthermore, MPSAN achieves better test accuracies than CNN-based models like CNN-non-static and CNN-Tensor by 4.53% and 1.33%.

### Mask Performance Analysis

To evaluate the performance of masks, we make a comparison between different masks in Table 2. Except MPSAN, the seven models in Table 2 use different combinations of various masks.

- **BW&FW**: Compared with Model 0, Model 1 has BW and FW, having 2.35% improvement. In addition, based on Model 3, Model 4 adds BW and FW, and have 0.86% improvement. So we come to the conclusion that employing BW and FW can improve the performance of the model.

- **FA**: Compared with Model 0, Model 3 has two FAs (Faraway Mask with $m = 2$ and $m = 3$, recorded as $F.A(2)$ and $F.A(3)$, respectively), having 1.94% improvement. In other models, Model 4’s test accuracy is 0.45% higher than Model 1’s, and our MPSAN’s test accuracy is 0.72% higher than Model 2’s. The above comparisons indicate that FA can improve the performance of the model. We don’t use $F.A(1)$ because of the performance of $F.A(1)$ is worse than $F.A(2)$ and $F.A(3)$. And we find using $F.A(2)$ and $F.A(3)$ at the same time is better than using them separately. Maybe we can find a better mask combination, but we don’t study this further in this paper.

- **D/SD**: Compared with Model 4, Model 6 adds Distance Mask on BW and FW having 0.18% improvement and our MPSAN adds Scaled-Distance Mask on BW and FW having 0.54% improvement. So adding distance penalty on BW and FW can improve the performance of the model and adding Scaled-Distance Mask is slightly better than adding Distance Mask on BW and FW. Compared with our MPSAN, we also add Scaled-Distance Mask on two FAs in Model 5, but the test accuracy of the model slightly reduced. This may be because the FA extracts local information, while the BW and FW extracts long-range positional information, and the distance penalty is more suitable for long-range positional information. In addition, compared with Distance Mask, Scaled-Distance Mask is more suitable for the extraction of long-range positional information. So adding Scaled-Distance Mask on BW and FW can improve the performance of the model.

In summary, various masks have different capabilities, and a good combination is better than using them separately.

### Techniques for Reducing Parameters

Although the combination of different masks can achieve better results, the number of training parameters will increase as the number of masks increases. Excessive parameters can lead to training costs increasing, and even cause memory overflow that make the model untrainable. We propose two

| Model  | BW  | FW  | FA   | Test Acc(%) |
|--------|-----|-----|------|-------------|
| 0      | -   | -   | -    | 49.19       |
| 1      | ✓   | ✓   | -    | 51.54       |
| 2      | ✓+SD| ✓+SD| -    | 51.81       |
| 3      | -   | -   | 2.3  | 51.13       |
| 4      | ✓   | ✓   | 2.3  | 51.99       |
| 5      | ✓+SD| ✓+SD| 2+SD,3+SD | 52.48       |
| 6      | ✓+D | ✓+D | 2.3  | 52.17       |
| MPSAN  | ✓+SD| ✓+SD| 2.3  | 52.53       |

Table 2: Mask study. BW (Backward Mask), FW (Forward Mask), FA (Faraway Mask), D (Distance Mask), SD (Scaled-Distance Mask) represent different masks mentioned in subsection ‘Positional Self-Attention Layer’. Under the column FA, “2” means use $F.A(2)$, and “2,3” means use $F.A(2)$ and $F.A(3)$ at the same time, but in different Masked Positional Self-Attention (Figure 2) modules. “.” indicates that the corresponding mask is not used in the model while “✓” indicates the mask is used. “+D” and “+SD” means adding Distance Mask or Scaled-Distance Mask on the corresponding mask, respectively. Model 1~6 have Positional Self-Attention Layer and Position-Fusion Layer, but Model 0 don’t. For each model, the accuracy is the best result of ten runs.
techniques in Position-Fusion Layer and Positional Self-Attention Layer respectively to reduce the parameters of the model.

Parameter Reduction for Fusion Our Tokens-Position-Weight is a natural extension of the Fusion Gate in DiSAN. The parameters we consider here include the fusion part and Multi-Dimensional Attention (MDA) part.

In Fusion Gate, the Masked-Self-Attention output $s$ in formula (7) and the input $h$ are combined together through sigmoid function, and the number of parameters is $2 \times 2d_h^2$, where $d_h$ is the size of hidden nodes. Then the output of self-attention layer is the concatenation of Backward and Forward self-attentions, so the size of output vector nodes is $2d_h$. After that, the MDA is applied, which is 3-layer fully connected structure with unchanged size of hidden nodes and constant size of output nodes, so the number of parameters is $2 \times (2d_h)^2 \times (2d_h) \times d_h$. The total number of parameters is $2 \times 2d_h^2 + 2 \times (2d_h)^2 \times (2d_h) \times d_h = 14d_h^2$.

In contrast, as for our Tokens-Position-Weight, the Forward Masked-Self-Attention output $s^{fw}$, the Backward Masked-Self-Attention output $s^{bw}$ and the sentence representation $w$ can be combined together through softmax function, so the size of output vector nodes is $d_h$, half of Fusion Gate. The total number of parameters is $3 \times d_h^2 + 2 \times d_h^2 + d_h \times d_h = 6d_h^2$.

If now we have $k$ Masked-Self-Attentions, then the number of parameters in Fusion Gate and MDA are $k \times 2d_h^2 + 2 \times (kd_h)^2 \times (kd_h) \times d_h = (2k^2 + 3k)d_h^2$, while the number of parameters in Tokens-Position-Weight and MDA are $(k+1) \times d_h^2 + 2 \times d_h^2 + d_h \times d_h = (k+4)d_h^2$. Here we don’t consider bias weights because they can’t affect the quantity level of the parameters. In our MPSAN, we set $k = 4$ and $d_h = 300$, so the parameter number of Fusion Gate and MDA is $(2k^2 + 2k - 4)d_h^2 = 3.24$ million more than the parameter number of Tokens-Position-Weight and MDA.

We evaluated the performance of the models on SST dataset in Table 3.

| Model          | $|\theta|$ | T(s) | Test Acc(%) |
|----------------|-----------|------|-------------|
| B&F + FG       | 1.45m     | 298  | 51.36       |
| B&F + TPW      | 0.73m     | 276  | 51.76       |
| mul + FG       | 4.33m     | 497  | 52.39       |
| mul + TPW      | 1.09m     | 359  | 52.53       |

Table 3: A study on the fusion way. B&F indicates using Backward and Forward Masked-Self-Attention introduced in subsection ‘Positional Self-Attention Layer’ while “mul” indicates using the masks combination introduced in Mask Performance Analysis. FG indicates Fusion Gate, while TPW indicates Tokens-Position-Weight. “mul + TPW” is our MPSAN. The test accuracies are the best results of ten runs. The number of parameters $|\theta|$ and the average seconds per epoch T(s) are obtained by the single run.

Compared to Fusion Gate methods, our Tokens-Position-Weight methods have a significant reduction in model parameters and a slightly decrease in time cost. In the meantime, our Tokens-Position-Weight can also bring some improvement on the test accuracy of the model.

Parameter Reduction in Compatibility Function We have $f(h_i, h_j) \in \mathbb{R}$ in formula (5), and we call it one-dimensional self-attention, recorded as 1-D. When $U, V \in \mathbb{R}^{d_h \times d_h}, b \in \mathbb{R}^{d_h}$, we have $f(h_i, h_j) \in \mathbb{R}^{d_h}$, which is multi-dimensional self-attention, and we record it as M-D. We explored the effect of using 1-D or M-D in Table 4.

| Model          | $|\theta|$ | T(s) | Test Acc(%) |
|----------------|-----------|------|-------------|
| M-D + B&F + TPW| 1.09m     | 466  | 51.95       |
| 1-D + B&F + TPW| 0.73m     | 276  | 51.76       |
| M-D + mul + TPW| 1.81m     | 953  | 52.67       |
| 1-D + mul + TPW| 1.09m     | 359  | 52.53       |

Table 4: A study on the weights of the compatibility function. "1-D + mul + TPW" is our MPSAN. The test accuracies are the best results of ten runs. The number of parameters and the average seconds per epoch are obtained by the single run.

From Table 4, we can conclude that using 1-D instead of M-D not only reduces the number of parameters, but also makes the model training faster and the performances of the models are similar. In a short word, reducing multiple positional information seems to be more effective than increasing the dimension number of self-attention so we use 1-D in our model.

| Model          | $|\theta|$ | T(s) | Test Acc(%) |
|----------------|-----------|------|-------------|
| MPSAN          | 1.09m     | 359  | 52.53       |
| MPSAN w/o fusion| 0.55m     | 325  | 51.22       |
| MPSAN w/o position | 0.64m   | 204  | 49.19       |
| MPSAN w/o attention | 0.09m | 115  | 44.93       |

Table 5: An ablation study of MPSAN

Component Analysis Furthermore, to evaluate the contribution of each component, we make an ablation study of MPSAN. As shown in Table 5, we remove each component one by one and record the number of parameters, average time per epoch and test accuracy.

In this paragraph, Position Fusion Layer and Positional Self attention Layer is abbreviated as PFL and PSAL respectively. Based on MPSAN, we remove 1) PFL, 2) PFL and PSAL, 3) all attention modules. In terms of accuracy, the results show that 1) attention-based module do contribute to the prediction and brings 7.6% improvement; 2) using PFL and PSAL improves accuracy by 3.34%; 3) By removing PFL from MPSAN, the accuracy declines by 1.31%. In terms of time cost, it shows that 1) PFL and PSAL occupy more time but have better test accuracy; 2) applying the PFL and PSAL takes up negligible time and improves significant performance.

Sentence Classification We evaluate our MPSAN on four sentence classification tasks, and the results are shown in Table 6. Text REtrieval
Table 6: Sentence Classification Tasks. Except our MPSAN, the reported accuracies and standard deviations are recorded by Shen et al. in Bi-BloSAN (Shen et al. 2018c). Except the accuracies on TREC are the mean of five runs, the accuracies on the other datasets are the mean of 10-fold cross validation. All standard deviations are in parentheses.

| Model                  | TREC  | CR   | MPQA | SUBJ |
|------------------------|-------|------|------|------|
| CBOW (Mikolov et al. 2013) | 87.3  | 79.9 | 86.4 | 91.3 |
| Skip-thought (Kiros et al. 2015) | 92.2  | 81.3 | 87.5 | 93.6 |
| DCNN (Kalchbrenner, Grefenstette, and Blunsom 2014) | /     | /    | /    | 93.0 |
| AdaSent (Zhao, Lu, and Poupart 2015) | 91.1 (1.0) | 83.6 (1.6) | **90.4 (0.7)** | 92.2 (1.2) |
| Bi-LSTM (Graves, Jaitly, and Mohamed 2013) | 94.4 (0.3) | 84.6 (1.6) | 90.2 (0.9) | **94.7 (0.7)** |
| Multi-head (Vaswani et al. 2017) | 93.4 (0.4) | 82.6 (1.9) | 89.8 (1.2) | 94.0 (0.8) |
| DiSAN (Shen et al. 2018a) | 94.2 (0.1) | 84.8 (2.0) | 90.1 (0.4) | 94.2 (0.6) |
| Bi-BloSAN (Shen et al. 2018c) | **94.8 (0.2)** | 84.8 (0.9) | **90.4 (0.8)** | 94.5 (0.5) |
| MPSAN                  | 94.8 (0.2) | **85.4 (1.4)** | 90.4 (0.8) | 94.6 (0.7) |

Table 7: SICK results. The reported accuracies are the mean of five runs. a (Graves, Jaitly, and Mohamed 2013), b (Kim 2014), c (Gehring et al. 2017), d (Vaswani et al. 2017), e (Shen et al. 2018a), f (Shen et al. 2018c)

**Conclusion**

In this paper, we have proposed two new positional masks (Faraway Mask and Scaled-Distance Mask) to extract word positional relationships in sentences. Moreover, combining with Forward Mask and Backward Mask, we present a Tokens-Position-Weight to balance the impact between different masks. On the other hand, our MPSAN achieves competitive performances on five open datasets. MPSAN is much faster and more memory efficient than the state-of-the-art self-attention based models like DiSAN, Bi-BloSAN. In the future work, we attempt to find a more general pattern to combine self-attentions and masks to avoid complexity in mask combination method. And we will verify the performance of our MPSAN on more tasks like Natural Language Inference and Reading Comprehension.

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