Modelling the Social Buffering Hypothesis in an Artificial Life Environment

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Abstract

In social species, individuals who form social bonds have been found to live longer, healthier lives. One hypothesised reason for this effect is that social support, mediated by oxytocin, “buffers” responses to stress in a number of ways, and is considered an important process of adaptation that facilitates long-term wellbeing in changing, stressful conditions. Using an artificial life model, we have investigated the role of one hypothesised stress-reducing effect of social support on the survival and social interactions of agents in a small society. We have investigated this effect using different types of social bonds and bond partner combinations across environmentally-challenging conditions. Our results have found that stress reduction through social support benefits the survival of agents with social bonds, and that this effect often extends to the wider society. We have also found that this effect is significantly affected by environmental and social contexts. Our findings suggest that these “social buffering” effects may not be universal, but dependent upon the degree of environmental challenges, the quality of affective relationships and the wider social context.

Introduction

Positive social relationships play a significant role in the wellbeing of individuals in social species. For many species, individuals who maintain close social bonds have longer, healthier lives and reduced stress levels (DeVries et al., 2003; Holt-Lunstad et al., 2010; Levine, 2000). One way in which these relationships are hypothesised to provide these beneficial effects is through the “social buffering” phenomenon (Hennessy et al., 2009; Kikusui et al., 2006), which posits that social support provides individuals with a physiological and psychological “safety cushion” (Wittig et al., 2016) during stressful events. This has also been seen to reduce and adapt stress responses to future stressful situations (Wittig et al., 2016; Heinrichs et al., 2003), suggesting an anxiolytic effect of social support—likely as a result of oxytocin’s adaptive effects on stress-related physiological systems (Heinrichs et al., 2003).

This physiological adaptation through the social environment underpins the concept of social allostasis (Schulkin et al., 2004; Sterling, 2004), which describes the adaptation of the stability-seeking homeostatic mechanism (Cannon, 1929) over an individual’s lifetime, through internal, external, and social contexts. Our current work (Khan et al., 2019) is concerned with developing an adaptive, embodied model of social allostasis to facilitate long-term viability (Ashby, 1954) of (artificial) social agents across dynamic physical and social conditions.

Recent work from the field has also investigated the role of social interactions on the performance of agent models, such as the effects on cooperation (Andras, 2016; Rajagopalan et al., 2019), including affect-based approaches (Antunes and Magnenat-Thalmann, 2016; Santos et al., 2011); social learning (Marriott and Chebib, 2014; Jolley et al., 2016), and the evolution of social dynamics (Covert III et al., 2014; Miramontes et al., 2016). Though some work has looked at allostatic(-type) models for adaptation (Vouloutsi et al., 2013; Moulin-Frier et al., 2017; Lones et al., 2017), a model focusing on mechanisms of social allostasis is yet to be investigated.

Building on the social buffering hypothesis, we investigate the role of the presence of affective social bond partners on the wellbeing and social interactions of a small society across dynamic environmental conditions. Using a simulated social model of agents, we investigate these effects for two different types of affective social bonds—one where the bond strength between bond partners remains fixed, and one where the bond strength is strengthened and weakened through social interactions—across a number of different bond partner combinations related to social rank. We hypothesise that affective social bonds will provide survival-related (viability) benefits for bond partners across dynamic physical conditions, and that this improved survival will be facilitated by a reduction in stress and socio-negative interactions between bond partners. We present and discuss our experiments to test this hypothesis in this paper. Our results show some support for our hypothesis, and that the stress-reducing effects of social support is affected by the social and environmental contexts, as well as the type of affective bond between agents.
Agent Model

Action-Selection Architecture

Using the long-standing approach from our research group (Cañamero, 1997; Lones et al., 2017; Lewis and Cañamero, 2019), agent behaviour is driven by a homeostatically-controlled decision-making architecture, simply called the Action-Selection Architecture (ASA). The ASA selects behaviours in order to satisfy one of two physiological needs (Table 1). The first, Energy, is a physical need and a survival-critical variable: if it drops to its lower bound, the agent will “die”. The second, SocialNeed, is a non-critical need for social contact (i.e. agents can die of Hunger but not Loneliness) though it still drives error-correcting behaviours. These internal variables experience a small decay at each time step. The goal of this homeostatically-controlled model is to maintain stability by keeping these values as close to their ideal values as possible through one of two deficit-correcting behaviours: Eat or Touch.

The ASA runs at each time step and works as follows:

![Diagram of Action-Selection Architecture](http://direct.mit.edu/isal/proceedings-pdf/isal2020/32/393/1908430/isal_a_00302.pdf)

**Table 1:** Relationship between each internal variable, motivations, behaviours and stimuli required to perform each behaviour. “Phys. Effect” = Physiological effects on performing agent (A) and recipient agent (i). OT = Oxytocin. CT = Cortisol.

| Internal Variables | Motivation | Behaviour | Stimuli | Phys. Effect | Phys. Effect |
|--------------------|------------|-----------|---------|--------------|--------------|
| P                  | m          | b         | S       | A            | i            |
| Energy             | Hungry     | Eat       | Food    | + Energy     | -            |
| SocialNeed         | Lonely     | Touch (Groom) | Agent | +SocialNeed +OT | -CT +OT      |
| SocialNeed         | Lonely     | Touch (Aggression) | Agent | +SocialNeed -CT | +CT          |

The error of each internal variable \(i\) is calculated as the difference between its ideal and current value (Eq. 1a). This error is then combined with the perceived availability of relevant stimuli \(c_i\) to calculate the “urgency” of each motivation (Eq. 1b). The motivation with the highest value is selected as the winning motivation (Eq. 1c). The behaviour with the largest physiological effect \(p_{ji}\) for the winning motivation is selected as the winning behaviour. As each motivation corresponds to a single behaviour, the resulting behaviour will either be Eat when the winning motivation is Hungry, or Touch when the winning motivation is Lonely (Eq. 1d,1e).

\[
d_i = \text{ideal}_i - \text{current}_i \quad (1a)
\]

\[
m_i = d_i + (d_i \times c_i) \quad (1b)
\]

\[
m_{\text{winner}} = \max(m_{\text{Hungry}}, m_{\text{Lonely}}) \quad (1c)
\]

\[
b_i = m_i \times p_{ji} \quad (1d)
\]

\[
b_{\text{winner}} = \max(b_{\text{Eat}}, b_{\text{Touch}}) \quad (1e)
\]

This winning behaviour then drives the agent towards relevant resources in order to satisfy their current motivation. Further details can be seen in Table 1.

Social Assessment Component

The Social Assessment Component (SAC) is an extension to the ASA (Khan et al., 2019), which introduced an additional step before behaviour execution by accounting for the social context—in this case, social rank differences and affective bond with others. Similar to the approach used in DomWorld (Hemelrijk et al., 2017), social rank is a value representing an agent’s hierarchical status within the society, and is associated with priority access to food and preference in being chosen as a grooming partner. An affective bond is a flag that represents a mutually-positive relationship between two agents. When the ASA calculates a winning behaviour, the SAC calculates a value \(\text{AgentVal}\) for each perceived agent \(i\) which determines (a) approach/avoid decisions when the winning behaviour is to Eat, and (b) partner selection when the winning behaviour is Touch. This
value is calculated using the difference in social rank between agents $A$ and $i$, and the presence (and quality) of an affective bond. A socially-influenced hormone of oxytocin (OT) is then used to modulate the valence of affective bonds in this calculation:

$$\text{rank-diff}_A = \text{rank}_i - \text{rank}_A \quad (2a)$$

$$\text{AgentVal}_i = \text{rank-diff}_A + (\text{bond}_A \times \text{DSI}_A \times \text{OT}_A) \quad (2b)$$

where rank-diff is a normalised value between $-1$ and $+1$ (in 0.25 increments) denoting the difference in social rank between agents $A$ and $i$. A negative value corresponds to a perceived agent being higher-ranked, and vice-versa. The bond$_A$ flag denotes if an affective bond exists between Agent $A$ and $i$ (1 if bond exists, else 0). The strength of this affective bond is denoted with the Dyadic Strength Index (DSI), in the range 0 to 2. Finally, OT denotes the level of oxytocin in an agent’s physiology, between 0 and 1. Agents turn away from (avoid) occupied food and other agents at a small angle when AgentVal $< 0$. Finally, agents are driven to Groom with the agent returning the largest AgentVal.

**Hormonal Effects**

We include two hormones in our agent model. The first, oxytocin (OT), is a modulatory hormone, released in response to performing or receiving positive social interaction (Grooming). OT is released in both the initiator and recipient of the prosocial behaviour as a function of the intensity ($b_{touch}$) of the Touch behaviour:

$$OT_t = OT_{t-1} + (1 \times b_{touch}) \quad (3)$$

OT experiences a small decay (-0.005) at each time step. In the SAC calculation, OT is used to modulate the valence of affective bond partners (Eq. 2): an abstraction of OT’s effects on preferential attention towards affective partners (Taylor, 2006).

The second hormone, cortisol (CT) is a stress-related hormone with a number of modulatory effects. Firstly, it modulates the speed at which an agent moves. This increased speed depletes Energy at an increased rate. Therefore:

$$\text{speed}_t = \text{speed}_{default} \times (1 + (CT \times c)) \quad (4a)$$

$$\text{EnergyCost}_t = \text{EnergyCost}_{default} \times (2 \times \text{speed}_t) \quad (4b)$$

$$\text{Energy}_t = \text{Energy}_{t-1} - \text{EnergyCost}_t \quad (4c)$$

The second effect is that it increases the intensity of tactile behaviours being performed. The more CT in an agent’s system, the more “intense” the strength of the tactile behaviour:

$$\text{TactileIntensity} = b_{touch} \times CT \quad (5)$$

For the performing agent, this value determines the rate of their internal SocialNeed satisfaction:

$$\text{SocialNeed}_t = \text{SocialNeed}_{t-1} + (\text{TactileIntensity} \times c) \quad (6)$$

CT is reduced by the value of (TactileIntensity $\times c$) in the recipient agent during Grooming, but increased by the same amount when receiving Aggression. At the same time, the strength of a bond (DSI) is also increased or decreased as a function of TactileIntensity, depending on the behaviour:

$$\text{DSI}_A = \begin{cases} 
\text{DSI}_A + \text{TactileIntensity} \times c & \text{if Groom} \\
\text{DSI}_A - \text{TactileIntensity} \times c & \text{if Aggression}
\end{cases} \quad (7)$$

where $c$ is a constant to regulate values. The rate at which cortisol is secreted or reduced is a function of physiological (internal) stress (the deficits of internal variables), and psychological (external/social) stress (related to difficulties in satisfying internal deficits). Specifically:

$$\text{CTReleaseRate}_A = \frac{1}{2} \left( \sum_{i \in P} d_i \times \sum_{s \in S} \hat{S}_i \right) \times c \quad (8)$$

where $\sum d_i$ is the sum of errors of both internal variables ($P$), $\sum S_i$ is the sum of perceived “available” resources ($S$), and $c$ is a fixed constant. Availability of resources (food or agents) are those which an agent perceives it can access. Accessibility of resources is determined through the AgentVal calculation:

$$\sum d_i = d_{\text{Energy}} + d_{\text{SocialNeed}} \quad (9a)$$

$$\sum \hat{S}_i = \hat{S}_{\text{Agents}} + \hat{S}_{\text{Food}} \quad (9b)$$
where \( \hat{S}_{\text{agents}} = C_{\text{Agents}} \times (1 - \text{AgentVal}) \) and \( \hat{S}_{\text{Food}} = 1 \) when \( \text{AgentVal} \geq 0 \), else 0).

As OT and (the presence and quality of) affective bonds are included in the assessment of “available resources” when calculating \( C_{\text{TReleaseRate}} \), it offsets the stress response associated with internal and external stress, therefore “buffering” and reducing (the release rate of) CT.

Finally, each agent has a fixed internal tolerance to the amount of CT it can withstand before it becomes “stressed”. For this investigation, this \( \text{StressThreshold} \) is set to 0.5: when CT levels exceed this threshold, agents are stressed and adapt their social behaviours accordingly by either increased avoidance or \textit{Aggression} towards others (Figure 2).

\[ \text{AgentVal} < 0 \]

### Agent Perception and Behaviours

**Vision System:** Each agent has a fixed field-of-vision of length 20 units with an angle of 80 degrees (+/- 40 degrees) and can only perceive resources that fall within this range.

**Movement:** Random wandering constitutes an appetitive behaviour and is performed in absence of any relevant stimuli. Agents have a default wandering speed (0.5 units per time step), that is modulated by the amount of cortisol in their physiology (Equation 4). When agents perceive a stimuli that satisfies its current motivation, they focus on that resource and move towards it. Agents turn at a small angle \( (90^\circ \times C_{\text{T}}) \) from agents where \( \text{AgentVal} < 0 \).

**Eat:** When agents reach a food resource and look to satisfy their \textit{Hunger} motivation, they stop and take “bites” of the resource, satisfying their internal \textit{Energy} need at a fixed rate (+0.01) until their drive has been satisfied.

**Touch (Groom and Aggression):** \textit{Touch} encapsulates both a socio-positive (\textit{Groom}) and socio-negative behaviour (\textit{Aggression}), dependent upon the stressed state of the agent and its social relationship with the other agent (via the \textit{AgentVal}). In both cases, this behaviour takes place within a single time step. Recipient agents are “pushed” a short distance, relative to the intensity of tactile contact received. \textit{Groom} and \textit{Aggression} have opposite effects on CT (Table 1). The strength of a bond (DSI) is strengthened and weakened through \textit{Aggression} (Equation 7).

### Experiments & Results

#### Methodology

Experiments were conducted using the NetLogo platform (Wilensky, 1999) v5.3.1. Our model used a society of six agents (A1 to A6), with all agents holding a different hierarchical rank (Figure 3) and endowed with the action-selection model described in the Agent Model section. Experimental conditions were defined in terms of the presence and type of affective bonds, the affective bond combination, and the type of environment related to food availability. We ran 20 simulations for each experimental condition, and each simulation ran for 15,000 time steps.

In terms of the types of affective bonds, Experiment 1 had all agents unbonded and served as our control. In Experiment 2, affective bond strength remained fixed throughout the experiment (DSI = 2). In Experiment 3, affective bond strength was variable, with the bond strength (DSI) subject to decay \( (\mu = 0.9997) \) and changes as a function of social interactions (Equation 7).

In Experiments 2 & 3, we investigated three different affective bond partner combinations (Figure 3). In each condition, three agents were bonded and three were unbonded. Bond combinations related to the social rank of agents. Bond Condition A had A1-A2-A6 with affective bonds between them, Bond Condition B had A3-A4-A5 with bonds, and Bond Condition C had A4-A5-A6 with bonds.

Experiments were performed across three world conditions related to food availability. The first was a \textit{Static}
world where food availability remained constant (Figure 4, top left). Seasonal was a dynamic environment with food changes every 1000 time steps (after an initial static phase of 2000 time steps, Figure 4, orange arrows), steadily changing from 4 foods (Phase 1) to 1 food (Phase 4). The Extreme environment had more significant food change during these same phases (4 foods in Phase 1, 1 food in Phase 2; Figure 4, blue arrows).

In terms of metrics, we measured results across three viability-related (Ashby, 1954) measures: Life Length (LL), describing the length of time an agent or group survives as a percentage of total simulation run time (from 0–100%); Mean Comfort (MC), describing the mean value of the two homeostatically-controlled variables (between 0–1); and Physiological Wellbeing (PW), describing the homogeneity of the satisfaction of these two internal variables (between 0–1). We also measured mean hormone levels and the distribution of social behaviours. We complemented our quantitative results with qualitative analysis of the experiments. Statistical significance testing was performed using one-way ANOVA testing.

Results: Viability Indicators

Experiment 1 (Control): As expected, viability performance of the overall society was greatest in the Static environments (LL: 33%, PW: 0.75). The results from the two dynamic world conditions were similar for both of these viability indicators (LL: 22%, PW: 0.49, 0.51 for Seasonal and Extreme conditions respectively) (Table 2).

Experiment 2: Like control, viability was greatest in the Static world condition (LL: 49%–53%, PW: 0.95), with bonded (B) groups outliving unbonded (UB) agents (B: 51–55%, UB: 46–50%) and a slightly improved Physiological Wellbeing (+0.15 vs. UB). Viability improvements were also seen in the Seasonal condition (LL: 34%–37%, PW: 0.56–0.64) with bonded agents (LL: 37%–39%, PW: 0.59–0.70) again seeing improved performance vs. UB agents (LL: 31%–33%, PW: 0.54–0.61). In Extreme environments, group viability was improved across all bond combinations (LL: 33%–37%, PW: 0.65–0.73), with bond agents (LL: 35%–39%, PW: 0.72–0.79) outperforming unbonded agents (LL: 30%–39%, PW: 0.55–0.74) in all but one Bond Condition (C) where there was a non-significant difference between bonded and unbonded viability. All other reported results were statistically-significant ($p < 0.01$) vs. control.

Experiment 3: All bond combinations saw significant increases in viability vs. control. This was most notable in the Seasonal (LL: +39% to +42%, PW: +0.29) and Extreme (LL: +43% to +45%, PW: +0.25) conditions. Again, bonded agents (LL: 31%–46%, PW: 0.50–0.86) showed improved viability compared to unbonded (LL: 27%–41%, PW: 0.48–0.79), though group survival was lower (LL: −5.9% to −29%) vs. fixed bonds. We highlight the largest differences in grey in Table 2. Physiological Wellbeing for all combinations were significantly improved vs. control (+0.03 to +0.29). Despite lower Life Lengths, aggregated Physiological Wellbeing remained consistent for all conditions (0.75–0.79).

Overall, these showed viability improvements for both bonded and unbonded agents when affective bond partners were available for some agents. Comparing experiments, viability was significantly improved for the overall society in experiments with fixed bonds, with smaller viability improvements noted in Experiment 3 vs. control conditions.

Results: Hormone Levels

Experiment 1: With no affective bonds, we saw that mean CT levels for the group increased as the physical challenge increased (Static: 0.49, Seasonal, 0.68, Extreme, 0.71). OT was not present in these conditions.

Experiment 2 saw lower overall CT levels for bonded and, in some conditions, unbonded agents (Table 3, grey cells) vs. control. CT levels for bonded agents were between 0.28–0.37 in Static environments, 0.56–0.58 in the Seasonal environment, and 0.62–0.65 in the Extreme environments. We noted significantly high levels of OT for all conditions (0.82–0.95). We also saw reduced levels of CT in unbonded agents (Static: 0.36–0.42, Seasonal: 0.49–0.60, Extreme: 0.54–0.65). Here, the presence of fixed bonds for three agents reduced the stress of all agents in the society.

Experiment 3 saw comparative CT levels for both bonded and unbonded agents vs. fixed bonds, with some differences (Table 3, dark grey cells). In Static world con-

| World Condition | Bond | Control (1) | Fixed Bonds (2) | Variable Bonds (3) |
|------------------|------|-------------|-----------------|-------------------|
| Static A         | 32.8% | 53.0%       | 43.0%           |
| Static B         | 32.8% | 49.0%       | 34.8%           |
| Static C         | 32.8% | 49.7%       | 46.5%           |
| Seasonal A       | 21.7% | 33.1%       | 30.7%           |
| Seasonal B       | 21.7% | 34.3%       | 30.7%           |
| Seasonal C       | 21.7% | 34.6%       | 30.3%           |
| Extreme A        | 21.6% | 33.5%       | 31.3%           |
| Extreme B        | 21.6% | 33.3%       | 31.1%           |
| Extreme C        | 21.6% | 36.6%       | 31.0%           |

Table 2: Viability Indicator results across all experimental conditions, aggregated for all six agents in the society. Differences in bonded and unbonded viability discussed where relevant. Mean Comfort values were non-significant, and have not been included in the analysis.
Table 3: Mean oxytocin (OT) and cortisol (CT) levels for bonded (B) and unbonded (UB) agents across all experiments. Results in grey are discussed in this section.

| World Condition | Bond | OT (Avg) | CT (B) | CT (UB) | OT (B) | CT (B) | CT (UB) |
|-----------------|------|----------|--------|---------|--------|--------|---------|
| Static A        | Seasonal | 0.68     | 0.95   | 0.87    | 0.39   | 0.47   | 0.60    |
|                 | Extreme | 0.71     | 0.83   | 0.64    | 0.34   | 0.54   | 0.64    |
| Static B        | Seasonal | 0.68     | 0.82   | 0.56    | 0.45   | 0.56   | 0.55    |
|                 | Extreme | 0.71     | 0.86   | 0.62    | 0.45   | 0.59   | 0.57    |
| Static C        | Seasonal | 0.68     | 0.84   | 0.58    | 0.46   | 0.58   | 0.52    |
|                 | Extreme | 0.71     | 0.83   | 0.65    | 0.42   | 0.66   | 0.55    |

Table 4: Social behaviour of bonded agents in Experiment 2, as a percentage of total Grooming/Aggression performed by bonded agents. Grey results are discussed in this section.

| Bond Condition | World Condition | Intra-Bond Grooming % | Intra-Bond Aggression % |
|----------------|-----------------|------------------------|-------------------------|
| A              | Static          | 63%                    | 0%                      |
| A              | Seasonal        | 73%                    | 10%                     |
| A              | Extreme         | 83%                    | 2%                      |
| B              | Static          | 42%                    | 0%                      |
| B              | Seasonal        | 45%                    | 56%                     |
| B              | Extreme         | 46%                    | 8%                      |
| C              | Static          | 17%                    | 0%                      |
| C              | Seasonal        | 24%                    | 100%                    |
| C              | Extreme         | 23%                    | 100%                    |

Figure 5: Amount of intra-bond Aggression performed during each phase of food availability (Phase 2-12 only), broken down by Bond Condition (colour). Experiment 2 = Fixed Bonds (top). Experiment 3 = Variable Bonds (bottom).

Results: Social Interactions

Experiment 1: Due to the increased CT levels from increasing world challenges (Table 3), Aggression increased through the three environments, accounting for 12%, 35%, and 39% of total social interactions. We observed a steady distribution of aggressive encounters in Static environments, and a cyclical distribution of Aggression related to the phases of food availability in Seasonal and Extreme environments. As no bonds were present, no intra-bond social behaviours were measured.

Experiment 2: Intra-bond Grooming increased as the world challenge increased (Table 4). Agents in Bond Condition A showed the highest amount of intra-bond Grooming (63% to 83%), while Bond Condition C exhibited the lowest amounts (17% to 23%). Intra-bond Aggression was highest in the Seasonal world condition for all bonds: accounting for between 10% (Bond Condition A), and 56% (Bond Condition B) of all Aggression performed by bonded agents. Despite a significant world challenge, few intra-bond Aggression behaviours were observed in the Extreme environment (Figure 5).

Experiment 3: Intra-bond Grooming was similar vs. Experiment 2 (64%, 37% and 15% for Bond Conditions A, B, and C respectively). However, intra-bond Aggression saw a significant increase: Bond Condition A saw intra-bond Aggression between 21%–35% of total Aggression performed by bonded agents: 78%–92% for Bond Condition B, and 100% in Bond Condition C. In contrast to fixed bond groups, a significant amount of socio-negative behaviours performed by bonded agents were on their own bond partners. In Seasonal environments, Bond Condition B saw significant intra-bond Aggression during the phase of worst food availability (Phase 4, 1 food: Figure 5), and maintained high levels of intra-bond Aggression in successive phases. In the Extreme condition, intra-bond Aggression was increased during phases of good food availability (phase 3, 5, 7), particularly for Bond Conditions B and C (Figure 5).
### Table 5: Social behaviour of bonded agents in Experiment 3, as a % of total Grooming/Aggression performed by bonded agents. Grey results denote notable differences vs. Table 4.

| Bond Condition | World Condition | Intra-Bond Grooming | Intra-Bond Aggression |
|----------------|------------------|----------------------|-----------------------|
| A Static       |                  | 64%                  | 21%                   |
| A Seasonal     |                  | 60%                  | 32%                   |
| A Extreme      |                  | 60%                  | 35%                   |
| B Static       |                  | 37%                  | 78%                   |
| B Seasonal     |                  | 42%                  | 91%                   |
| B Extreme      |                  | 29%                  | 78%                   |
| C Static       |                  | 15%                  | 100%                  |
| C Seasonal     |                  | 17%                  | 100%                  |
| C Extreme      |                  | 22%                  | 100%                  |

### Discussion

Regardless of the type of affective bond (fixed or variable), we observed significant improvements to the viability of agents with social support across a number of physically-challenging conditions vs. conditions with no bonds. In many cases, the wider society also saw reduced stress (CT) levels and, as a result, improved viability. Comparing Experiments 2 & 3, we noted significant viability advantages for bonds with fixed affective bonds vs. variable bonds. In our model, we find that the buffering of the stress response via social support resulted in significant advantages to bonded, and in some cases unbonded, agent viability through behavioural adaptation and additional stress-reducing coping mechanisms. We propose that this type of behavioural and physiological adaptation via social interactions is a type of social allostasis. We complement our quantitative results with qualitative analysis of emergent interactions.

**“Tend-and-Befriend” vs. “Fight-or-Flight”**

We noted that for all bond combinations in Experiment 2, intra-bond Grooming increased as the world conditions became more challenging (Table 4). In the Seasonal and Extreme conditions, rather than become stressed and perform Aggression towards others, bonded agents would instead seek out social contact with their own affective bonds: performing Grooming, reducing CT, releasing OT and strengthening the bond between them (Figure 6, top right). This contributed to survival in future, more challenging situations (Table 2). We considered this an important behavioural response that facilitated viability in difficult conditions. When affective bond strength was fixed, we saw behaviours related to the “tend-and-befriend” hypothesis (Taylor, 2006), which proposes that, rather than looking for outlets of aggression, social individuals with strong relationships seek out positive social contact during times of stress. This behaviour is also seen to be related to individuals with higher levels of OT (Taylor, 2006), mirroring our results from Experiment 2 (Table 3).

In contrast, in experiments with variable bond strength and lower OT levels, we observed larger rates of intra-bond Aggression as a coping behaviour for stress (Figures 5 & 6, bottom right). This behaviour then impacted affective bond strength and therefore survival rates of agents. Considering these results, we support the suggestion that additional context such as bond stability, partner identity and the degree of affiliation may affect the efficacy of social buffering effects (Kikusui et al., 2006), and therefore impact the different stress-reducing coping behaviours.

**Reconciliation is Hindered in Challenging Environments**

In some conditions in Experiment 3, we found that weaker affective bonds did not provide the hypothesised stress-reducing effect when the world conditions were challenged (Seasonal and Extreme environments). Due to the lack of the stress-reducing effect from (weak) social support, (lower-ranked) bonded partners were targeted for Aggression (Figure 5) by stressed agents, and intra-bond Aggression increased as a result (Table 5). This significantly reduced bond quality, and the ongoing stress caused by challenges from the Seasonal and Extreme environments limited the opportunity for Grooming between bond partners. This eventually resulted in a permanent loss of social support.

Again, we found that, despite social bond partners offering some “buffering” effect when bonds were strong (Experiment 2), these weakened bonds were susceptible to being lost beyond reconciliation during significantly challenging conditions. Therefore, in our model, the stress-reducing effects of social support was significantly affected by the environmental challenges and the strength of affective bonds between agents.

**Aggression Increases During Periods of Food Abundance**

In Extreme environments when bond strength was variable (Experiment 3), for agents in Bond Conditions B and C (when lower-ranked agents were bonded), we observed an increase in intra-bond Aggression when food availability was “good” (Phase 3, 5, 7, 9, Figure 5, bottom). Despite our prediction that aggression would decrease during “easier” physical periods, we saw that the magnitude of changes associated with the Extreme environment did not allow the agents to adapt to the constantly-changing conditions fast enough. As a result, the sudden shortage of food would increase group stress, which then carried over into the next phase (where food is abundant), increasing Aggression during these periods. This is not seen in Bond Condition A, or in conditions where the physical environment changes more gradually (Seasonal). In those conditions, we see Aggression increase and decrease roughly in line with the food availability. In terms of the stress-reducing effects associated with social support in our model, we found that these effects were not one-size-fits-all, but impacted by the magnitude of the environmental challenge, the quality of affective
bonds and social rank of bond partners.

“Outsiders” can Damage Weaker Relationships

In Experiment 3, we had noted that weak (variable) bonds had the potential to be indirectly and irreversibly damaged by outside social influences. Specifically, unbonded, higher-ranked agents (such as A2 or A3) would become stressed in physically-challenging periods. This resulted in Aggression towards lower-ranking agents (i.e., A4): increasing its stress level. For these lower-ranked agents, if their current bonds were already weakened, they would become aggressive towards their own (lower-ranking) bond partners. Rather than the “tend-and-befriend” behaviour that we described earlier (Figure 6, top right), these agents would perform Aggression towards their own bond partners (Figure 6, bottom right), reducing their affective bond strength. This loss of affective bond quality had an impact on the availability of future coping mechanisms and bond partner viability.

In these situations, when bonds were weak or if agents were experiencing higher levels of stress, socio-negative behaviours from higher-ranked members of society had a “trickle-down” effect on their interactions with bond partners. This loss of affective relationship resulted in subordinate bond partners withdrawing from interactions in the future (Figure 6, bottom left). In this scenario, an affective bond partner could go from being a source of social support to one of social stress. This highlighted the significance of the wider social context on the quality and maintenance of affective relationships. While affective bonds reduced stress in some contexts, this effect was impacted by significant environmental challenges and the wider social context.

Conclusions

In this paper, we have studied one aspect of the “social buffering” hypothesis, by investigating the effects of affective social support on the wellbeing and social interactions of individuals across a number of dynamic environmental conditions. We hypothesised that the presence of social bond partners would benefit the viability of our agents through a reduction of stress and behaviour adaptation. Using a simulated model, we have investigated these effects using a number of different affective bond combinations related to individual social rank, as well as both “fixed” and “variable” strengths of affective bonds. While we found some support for our hypothesis, we also found that the stress-reducing effects of social support were contextual, and that they were impacted by the degree of the wider social and environmental challenges, as well as the type of affective bond between agents. In many cases, we also found improvements in viability and reduced stress levels in agents without affective bonds, suggesting that the stress-reducing effects of social support may impact the wider social group in some conditions.

Extrapolating from our findings, we suggest that, for real-world societies, the stress-reducing effects of social support may not be universal, but that they may depend upon the relative environmental and social challenges, as well as the strength of affective relationships. As part of future work, we would like to see these findings of our model inspire new research in the study of related phenomena in biological agents.

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