Revisiting the Impact of Atmospheric Dispersion and Differential Refraction on Widefield Multiobject Spectroscopic Observations

From VLT/VIMOS to Next Generation Instruments

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\textbf{ABSTRACT}

Context. Atmospheric dispersion and field differential refraction impose severe constraints on widefield, multiobject spectroscopic (MOS) observations, where the two joint effects cannot be continuously corrected. Flux reduction and spectral distortions must then be minimised by a careful planning of the observations – which is especially true for instruments that use slits instead of fibres. This is the case of VIMOS at the VLT, where MOS observations have been restricted, since the start of operations, to a narrow two-hour range from the meridian to minimise slit losses – the so-called two-hour angle rule.

Aims. We revisit in detail the impact of atmospheric effects on the quality of VIMOS-MOS spectra with the aim of enhancing the instrument’s overall efficiency, and improving the scheduling of observations.

Methods. We model slit losses across the entire VIMOS field-of-view as a function of target declination. We explore two different slit orientations at the meridian: along the parallactic angle (North-South), and perpendicular to it (East-West).

Results. We show that, for fields culminating at zenith distances larger than 20 deg, slit losses are minimised with slits oriented along the parallactic angle at the meridian. The two-hour angle rule holds for these observations using North-South orientations. Conversely, for fields with zenith angles smaller than 20 deg at culmination, losses are minimised with slits oriented perpendicular to the parallactic angle at the meridian. MOS observations can be effectively extended to plus/minus three hours from the meridian in these cases. In general, night-long observations of a single field will benefit from using the East-West orientation. All-sky or service mode observations, however, require a more elaborate planning that depends on the target declination, and the hour angle of the observations.

Conclusions. We establish general rules for the alignment of slits in MOS observations that will increase target observability, enhance the efficiency of operations, and speed up the completion of programmes – a particularly relevant aspect for the forthcoming spectroscopic public surveys with VIMOS. Additionally, we briefly address the (non-negligible) impact of field differential refraction on future widefield MOS surveys.

Key words. Atmospheric effects – Methods: observational – Techniques: spectroscopic – Instrumentation: spectrographs

1. Introduction

The effects of atmospheric dispersion on spectrophotometric observations were first tackled in a seminal paper by [Filippenko (1982)], and have since been addressed by many other authors (e.g., Cohen & Cromer [1988], Donnelly et al. [1989], Cuby [1994], Szokoly [2005]). Two different components contribute to slit losses: a chromatic dispersion caused by the wavelength variation of the index of refraction of air; and an achromatic differential refraction due to airmass variations across the field-of-view (FOV). As pointed out by [Cuby et al. (1998)], the chromatic effect is almost constant for a given field, and can thus be counterbalanced with an atmospheric dispersion compensator (ADC). On the other hand, field differential refraction cannot be continuously corrected, and this is especially problematic for optical instruments with large FOVs. In the case of multiojbect spectroscopic (MOS) observations the two joint effects cannot be compensated, so that aperture losses must be minimised by a careful planning of the observations (e.g., Cuby et al. [1998], Szokoly [2005]). This may range from frequent reconfiguration of the fibres, to imposing limited observability windows. The latter is actually the only alternative for instruments that use slits instead of fibres, even more so because field rotation prevents the alignment of all slits along the parallactic angle.

VIMOS\textsuperscript{[3]} (Le Fèvre et al. [2003]) is a widefield (4x7x8 arcmin\textsuperscript{2}) instrument with imaging, integral field, and MOS capabilities mounted at the Nasmyth B focus of VLT UT3. The instrument operates in the optical wavelength range (360-1000 nm), and is equipped with six sets of grisms, six sets of broadband filters, plus three additional filter sets specifically designed to be used in combination with the grisms to block the second order spectra. The unique combination of instrument FOV, large collecting power, and very high multiplexing (up to ~600 targets in the low resolution modes; see Table\textsuperscript{[1]} and Fig.\textsuperscript{[1]} has made VIMOS a particularly efficient instrument for large spectroscopic surveys of cosmological fields (e.g., Le Fèvre et al. [2005], Lilly et al. [2007], Popesso et al. [2009], Guzzo et al. [2013]).

VIMOS-MOS observations are carried out using multislit masks, which provide very accurate sky subtraction and high instrumental throughput. However, the lack of ADCs makes at-
mospheric dispersion and field differential refraction factors that need to be taken into account. The atmospheric effects in instruments like VIMOS were studied by Cuby et al. (1998). They show that i) atmospheric dispersion dominates at shorter wavelengths, while differential refraction is not negligible at the red end of the visible spectrum; ii) in the former case, image drifts occur along the meridian; iii) differential refraction can be almost neglected for zenith distances smaller than 25 deg for exposure times up to two hours from the meridian (HA = 0 h). In view of these results they recommended that, in order to minimise slit losses, the slits be positioned along the dispersion direction at mid-exposure, and observations be limited to a narrow two-hour range from meridian crossing – the so-called two-hour angle rule. This guarantees that losses remain below 20 per cent for zenith angles < 50 deg at culmination. These rather limiting guidelines had always been in place for all MOS observations since the start of operations in 2003, and in practice translate into mandatory airmass constraint limits for the VIMOS-MOS observing blocks (OBs).

During the last few years the instrument performance has been significantly enhanced (see Hammersley et al. 2010, 2013, Brestow et al. 2012). All these improvements have made VIMOS a much more stable instrument, and have extended its lifetime in order to prepare it for the start of the spectroscopic public surveys for which ESO has recently issued a call. Further work to improve the operational efficiency of the instrument includes the present study, which has as its main goal to revisit the need for restricted observability of targets only within plus/minus two hours from the meridian in the MOS mode. Increasing the observability of targets in the MOS mode provides more flexibility to operations, because the number of masks that can be loaded in the instrument before the beginning of each night is limited. As we previously noted, VIMOS is very often used for deep observations of cosmological fields, where very long integrations are taken for the same field. By increasing the target visibility (relaxing the two-hour angle rule), the programmes can be completed faster.

In this paper we revisit in detail the impact of atmospheric dispersion on the quality – in terms of slit losses and spectrophotometric distortions – of VIMOS observations. Our aim is to establish general rules for the alignment of slits in MOS observations that enhance the efficiency of operations, not only for VIMOS, but for other operational and future multislit spectrographs as well. We note that the parameter space of this problem is large. Irrespective of image quality and atmospheric conditions, slit losses depend on slit size, orientation, and position within the FOV, observed wavelength range, target declination, total exposure time, and hour angle (HA) of the observations. We build upon the previous work by Cuby et al. (1998), but include specific calculations for all the grisms currently available in VIMOS, and present a more detailed analysis of the optimal slit orientation as a function of target declination.

This paper is organised as follows. In Section 2 we describe the model with which we compute slit losses in VIMOS. Section 3 presents the main results of our analysis, while in Section 4 we briefly address the specific contribution of field differential refraction, and its importance for widefield MOS observations. Finally, in Section 5 we discuss our main results, and summarise our findings.

2. A model to address slit losses in VIMOS-MOS

In order to investigate potential operational improvements that could enhance the efficiency of VIMOS, we have simulated the effects of slit losses under different circumstances. Our fiducial model (see Table 2) assumes a flat input spectrum and nine slits evenly distributed across the entire VIMOS FOV, from the centre to the corners, and with relative separations of seven arcmin. All slits have a $l = 10$ arcsec length and $w = 1$ arcsec width, which is typical for the majority of VIMOS-MOS observations. We assign two different orientations for the slits at meridian crossing, namely North-South (PA = 0 deg), and East-West (PA =...
2.1. Deviations from the fiducial model

We previously noted that the parameter space of this problem is very large. As a result, our fiducial model necessarily contains several simplifications, including a fixed FWHM-to-slitwidth ratio, and the assumption that the objects are perfectly centred within the slits. Here we estimate, to first order, how the results would change if we modify these conditions. The first parameter we vary is the FWHM-to-slitwidth ratio. Ideally, one would optimise the observations by adapting the slitwidth to the seeing conditions. While this ratio can of course not be anticipated in actual observations, the users can significantly restrict it by imposing a given seeing constraint in their service-mode OBs. In any case, we explore a sensible range of FWHM-to-slitwidth ratios, between 0.5 and 1.5. The second condition we relax is the assumption that the objects are perfectly centred within the slits. Typically, there is a lower limit of one pixel to the precision of mask positioning due to a variety of effects – including mechanical hysteresis, blind corrections during exposures, etc. Additional errors due to different airmass/HA between pre-imaging and MOS observations (or even pre-imageless MOS mask creation) will introduce an additional source of flux reduction. We estimate this flux reduction by assuming the object is displaced perpendicular to the slit – i.e., in the dispersion direction –, and compute the fractional through-slit flux that is transmitted in each case. We note that this calculation ignores all atmospheric dispersion and differential refraction effects. It is therefore equivalent to the flux obtained at the centre of the FOV, for a field observed at zenith.

In Figure 2 we show the fraction of transmitted flux as a function of FWHM-to-slitwidth ratio, for a Gaussian point source that is displaced perpendicular to the slit by a fractional amount of the slitwidth, \( \Delta x = (x - x_0)/w \). The inset panel shows the flux loss relative to the case where the object is perfectly centred within the slit. A slitlength \( l = 10\,\text{w} \) is assumed within the slits. Here we estimate, to first order, how the results would change if we modify these conditions. The first parameter we vary is the FWHM-to-slitwidth ratio. Ideally, one would optimise the observations by adapting the slitwidth to the seeing conditions. While this ratio can of course not be anticipated in actual observations, the users can significantly restrict it by imposing a given seeing constraint in their service-mode OBs. In any case, we explore a sensible range of FWHM-to-slitwidth ratios, between 0.5 and 1.5. The second condition we relax is the assumption that the objects are perfectly centred within the slits. Typically, there is a lower limit of one pixel to the precision of mask positioning due to a variety of effects – including mechanical hysteresis, blind corrections during exposures, etc. Additional errors due to different airmass/HA between pre-imaging and MOS observations (or even pre-imageless MOS mask creation) will introduce an additional source of flux reduction. We estimate this flux reduction by assuming the object is displaced perpendicular to the slit – i.e., in the dispersion direction –, and compute the fractional through-slit flux that is transmitted in each case. We note that this calculation ignores all atmospheric dispersion and differential refraction effects. It is therefore equivalent to the flux obtained at the centre of the FOV, for a field observed at zenith.

In Figure 2, we show the fraction of transmitted flux as a function of FWHM-to-slitwidth ratio, for a Gaussian point source that is displaced perpendicular to the slit by a fractional amount...
Fig. 3. Output simulated spectra for nine different slit positions across the VIMOS FOV. The relative positions (in arcmin) of the slits with respect to the centre of the FOV are indicated. At the meridian, $\Delta x$ and $\Delta y$ correspond to $\Delta \alpha$ and $\Delta \delta$, respectively. These are the result of a one-hour-long integration ($-3 < HA (h) < -2$) on a $\delta = 0$ deg field using the MR grism. In each panel we show the output spectra for two different slit orientations (solid for N-S, and dot-dashed for E-W). We also provide the corresponding relative flux loss ($f$) and spectral distortion ($\Delta$). The input spectrum is flat (dotted lines), but its flux is reduced by 24 per cent due to finite seeing and slit width. See text for details.

of the slitwidth, $\Delta x = (x - x_0)/w$. For VIMOS, and in the particular case of a $w = 1$ arcsec slit, the selected displacements correspond to $0 \leq \Delta x \leq 2$ pixels. The inset panel shows the fractional flux reduction relative to the case where there is no displacement, i.e., $\Delta x = 0$. Fig. 2 shows the importance of accurate centroiding, as significant losses can otherwise occur. In the case of VIMOS, however, a displacement of up to one pixel only results in a relative flux reduction of $\approx 6$ per cent. We recall that, for given conditions, this flux reduction is an absolute minimum, purely a result of geometrical effects. As we will see, slit losses will generally increase (nonlinearly) as a result of atmospheric dispersion and differential refraction during the observations.

3. VIMOS-MOS slit losses: dependence on grism, FOV orientation, field declination, and HA

Figure 3 shows an example of the output from our fiducial simulations. Each panel shows, for the nine different slit positions across the VIMOS FOV, the output spectra obtained after a one-hour-long integration ($-3 < HA (h) < -2$) on a $\delta = 0$ deg field, and using the MR grism. The slit positions are fixed with respect to the centre of the FOV. At the meridian, $\Delta x$ and $\Delta y$ correspond to $\Delta \alpha$ and $\Delta \delta$, respectively. Solid (dash-dotted) lines correspond to slits oriented along the N-S (E-W) direction at meridian cross-

$^4$ Source codes are available from the authors upon request.
Fig. 4. Shaded regions show, for the HR-blue grism, the entire range of spectral distortions (upper row) and flux losses (lower row) for the nine simulated slits as a function of target declination. The corresponding minimum, median and maximum values at fixed declination are indicated by solid lines. The plots show the effects for two different slit orientations at the meridian (N-S in grey and E-W in purple). Each column corresponds to a one-hour-long integration with target hour angle as indicated on top. The thick horizontal lines at 20 per cent indicate our assumed maximum tolerated loss/distortion level.

The dotted lines indicate the fiducial maximum flux discussed in Sect. For each slit position we also provide the corresponding values for the two figures-of-merit with which we characterise the results of the simulations (see Table 2). The first one is the relative flux loss:

\[ f = 1 - \left[ \int_{\lambda_{\text{min}}}^{\lambda_{\text{max}}} f_{\text{o}}(\lambda) \, d\lambda / \int_{\lambda_{\text{min}}}^{\lambda_{\text{max}}} f_{\text{i}} \, d\lambda \right], \]

where \( f_{\text{o}}(\lambda) \) is the output spectrum, and \( \int_{\lambda_{\text{min}}}^{\lambda_{\text{max}}} f_{\text{i}} \, d\lambda \) is the fiducial maximum flux from the (flat) input spectrum. \( f \) simply corresponds to the percentage flux reduction within the \([\lambda_{\text{min}}, \lambda_{\text{max}}]\) wavelength range of a given grism (see Table 3). The second parameter we investigate is the spectral distortion:

\[ \Delta = 1 - f_{\lambda_{\text{min}}} / f_{\lambda_{\text{max}}}, \]

where \( f_{\lambda_{\text{min}}} \) and \( f_{\lambda_{\text{max}}} \) are the minimum and maximum fluxes of the output spectrum, respectively. Figure 3 shows that \( \Delta \) provides supplementary information. Even though in this example the two slit orientations result in very similar median slit losses across the FOV (\( f = 0.02 \) and \( f = 0.04 \) for the E-W and N-S, respectively), the E-W alignment provides more stable results across the FOV, and a much lower median spectral distortion (\( \Delta = 0.13 \) vs. \( \Delta = 0.22 \)). This should therefore be the preferred orientation in this case.

Figures 4-9 illustrate the final results for the entire set of simulations for each of the six grisms. In all panels the solid curves show the minimum, median and maximum flux losses (lower row) and spectral distortions (upper row) for the nine simulated slits as a function of target declination. The shaded regions encompass all the output values. The plots show the effects for the two different slit orientations at the meridian (N-S in grey and E-W in purple). Each column corresponds to a one-hour-long integration with target hour angle as indicated on top. We note that the behaviour of the curves is similar for all grisms, but both losses and distortions are significantly smaller towards the red end of the visible spectrum. The general trends for the two slit orientations can be summarised as follows.

For the N-S (PA = 0 deg) orientation we find that at fixed HA there is a very weak dependence on declination (except for \(|HA| > 2 \text{ h}\) and the bluest wavelengths). For any given grism, there is a strong dependence on HA, such that larger distortions and flux losses occur at larger HAs. Both the amount of losses/distortions, and the dependence on declination, increase for bluer wavelengths. The minimum of the loss/distortion distributions increases and moves towards southern declinations at larger HAs.

On the other hand, for the E-W (PA = 90 deg) orientation we see that at fixed HA there is a very strong dependence on declination, but the behaviour flattens towards redder wavelengths. For any given grism, there is very little dependence on HA (except for extreme declinations). Finally, the dependence on declination of losses/distortions increases towards bluer wavelengths. The minimum of the loss/distortion distributions slightly decreases and moves towards southern declinations at larger HAs.
Fig. 5. Same as Fig. 4 but for the LR blue grism.

Fig. 6. Same as Fig. 4 but for the HR orange grism.
Fig. 7. Same as Fig. 4 but for the MR grism.

Fig. 8. Same as Fig. 4 but for the HR_red grism.
All these results correspond to the fiducial one-hour long integrations, which is the typical on-target exposure time of service-mode MOS OBs in VIMOS. In Fig. 10 we show that these trends also hold for longer integrations. Curves show, for the LR-blue grism, the median relative flux loss as a function of declination for two-hour-long integrations spanning a variety of hour angles – namely 0-2 h, 1-3 h, and 2-4 h. Solid (dot-dashed) lines show the results for slits that are oriented along (perpendicular to) the dispersion direction at the meridian. Naturally, the curve for a four-hour-long exposure before/after the meridian would simply be the mean between the 0-2 h and the 2-4 h ones. The fact that slit losses are strongly dependent on hour angle for the N-S orientation, but almost insensitive to HA (at a given target declination) when aligning the slits along the E-W direction, has important implications for the scheduling of observations.

3.1. Beyond the two-hour angle rule

The trends previously discussed are well illustrated in Figure 11. Here we colour-code the declination-hour angle pairs according to whether the median spectral distortion, or median flux loss, are lower with slits oriented along the N-S (grey symbols) or E-W (purple symbols) directions at meridian crossing. Each column summarises the results for all the VIMOS grisms, always assuming one-hour-long integrations. The tendencies previously discussed are perhaps more evident in this Figure, where it is shown that the E-W orientation is progressively preferred at larger hour angles. It is the favoured orientation for all declinations at HA $\gtrsim 3$ h, but only optimal for fields culminating at small zenith distances at HA $\lesssim 1$ h. However, even if one of the orientations is formally superior to the other one, slit losses and distortions can be unacceptably large even for the preferred orientation. Additionally, a detailed inspection of Figs. 4-9 indicates that in several cases the differences between orientations are almost negligible – for all practical purposes they both perform equally well in these cases. Following the previous work by Cuby et al. (1998), we set the tolerance level for losses/distortions at 20 per cent. In Fig. 12 we similarly show the declination-hour angle pairs (again colour-coded according
Fig. 11. Filled circles show the declination-hour angle pairs for which the median spectral distortion (top row) or median flux loss (bottom row) across the VIMOS FOV are lower with slits oriented along the N-S (grey symbols) or E-W (purple symbols) directions at meridian.

to slit orientation) for which the median spectral distortion, or median flux loss, across the VIMOS FOV remain below this tolerance value during a one-hour-long integration.

From these two Figures it is evident that the optimal slit alignment for fields culminating at small (large) zenith distances is the one that follows the E-W (N-S) direction at meridian crossing. The N-S orientation suffers from severe slit losses, and especially distortions, outside the two-hour interval from the meridian. The effect is particularly strong for the blue grisms, and turns milder towards redder wavelengths. The E-W orientation, on the other hand, allows observations to be extended up to much larger hour angles – up to four hours for certain fields, according to our fiducial model. However, as discussed in Sect. 2.1, these are certainly lower limits to the actual losses and distortions. We therefore prefer to be conservative, and recommend to limit service-mode observations with VIMOS to within three hours from the meridian even when using slits oriented E-W.

4. A note on the impact of field differential refraction on widefield multiobject spectrographs

As discussed during this work, slit losses are the result of the combined effect of atmospheric dispersion and field differential refraction. The former effects is usually dealt with ADCs, which are a common feature in most upcoming multiobject spectrographs. The latter is however an achromatic effect, and as a result dominates slit losses at the red end of the visual spectrum. Naturally, it can not be corrected with ADCs, and is therefore always present in widefield MOS observations.

The field differential refraction across a given field can be approximated by

$$\Delta r \approx (n - 1) \phi X^2,$$

where $X$ is again the airmass, $\phi$ is the diameter of the FOV, and $n$ is the index of refraction of air, of the order of $(n - 1) \approx 2 \times 10^{-4}$ in the optical at the typical elevation of astronomical observatories. Equation 3 shows that, for FOVs similar to that of VIMOS, $\Delta r \approx 0.25$ arcsec even at moderate airmasses – and the effect increases linearly with $\phi$. This makes field differential refraction a non-negligible effect for most widefield multiobject spectrographs that can only be compensated by the scheduling of the observations. In the case of multislit spectrographs like VIMOS, the only alternative is to limit the observations to the airmass range where differential refraction is not critical. In fibre-fed spectrographs the fibres can be configured at the beginning of an observation, so that the mean effect during the entire exposure is minimised. The fibres will eventually need to be reconfigured to avoid a significant flux reduction, and the amount of time during which any given field can be observed without significant losses depends strongly on its declination. If we substitute for the airmass term in Eq. 3 and write the field differential refraction as a function of the hour angle for a given field:

$$\Delta r \approx (n - 1) \phi [\alpha + \beta \cos \mathrm{HA}]^2,$$

where $\alpha = \sin \varphi \sin \delta$, and $\beta = \cos \varphi \cos \delta$. In Fig. 13 we plot the incremental deviation (i.e., with respect to the effect at HA = 0 h) caused by differential refraction for three different instrument FOVs (diameters $\phi = 0.5, 1.2$ deg), and three different fields.
Fig. 12. Filled circles show the declination-hour angle pairs (colour-coded according to slit orientation) for which the median spectral distortion (top row) or median flux loss (bottom row) remain below the 20 per cent value during a one-hour-long integration. 

\( \delta = -75, -25, +25 \) deg) observed from Paranal. Naturally, the effect is more important at larger airmasses, and for instruments with large FOVs.

Indeed, in Fig. 14 we show, for a multiobject spectrograph featuring a 3 deg diameter FOV (e.g., 4MOST, de Jong 2011), the amount of time needed for incremental field differential refraction to exceed a given deviation, as a function of target declination (assuming Paranal’s latitude). In general, southern fields can be observed for times longer than one hour without resulting in significant deviations – hence with minimal flux reduction. On the other hand, the deviation rapidly exceeds 0.2 arcsec for northern fields, and fibre reconfiguration will be needed before the first hour of integration. All-sky type MOS surveys must therefore carefully plan the scheduling of observations in order to minimise these effects.

5. Discussion and conclusions

We have shown that the optimal slit alignment in widefield MOS observations is a complex function of target declination and hour angle (Fig. 11). The traditional orientation of slits along the parallactic angle at the meridian provides very stable results for observations within two hours from the meridian. A setup where slits are oriented perpendicular to the parallactic angle at the meridian is however preferred in the case of fields culminating at low zenith distances, or generally when observations extend to \( |\text{HA}| > 2 \) h. This result can readily be understood from the following qualitative line of arguments. As discussed by Szokoly (2005), slit losses depend on the interplay between two effects. The first one is independent of the slit orientation, as both atmospheric dispersion and differential refraction are larger at increasing airmasses. On the other hand, the angle between the slit and the parallactic angle is constantly changing. When slits are oriented along the parallactic angle at the meridian (N-S), the angle between the slits and the parallactic angle tends to increase, and the two effects amplify each other. Conversely, when slits are oriented perpendicular to the parallactic angle at the merid-

Fig. 13. Curves show the incremental field differential refraction for three different instrument FOVs (\( \phi = 0.5, 1, 2 \) deg), and three different fields (\( \delta = -75, -25, +25 \) deg) observed from Paranal. All deviations are shown relative to the effect at \( \text{HA} = 0 \) h. The effect starts to become significant (\( \gtrsim 0.1 \) arcsec) even for \( \text{HA} \sim 1 \) h for fields culminating to the North.
strongly on HA, but not so much on and hour angle depicted in Figs. 4–9: the N-S orientation depends systematically closer to the parallactic angle at higher airmasses, while the strong dependence of the E-W orientation on δ is almost invariant to changes on HA.

This has important implications for the scheduling of observations. Night-long observations of a single field (visitor mode) will generally benefit from using the E-W orientation for slits at the meridian. All-sky or service mode observations, however, require a more elaborate planning that depends on the target and the hour angle of the observations. This is a particularly relevant aspect for the forthcoming spectroscopic public surveys with VIMOS, where observations will be carried out in visitor mode. We conclude that the two-hour angle rule, together with the default N-S slit orientation, provide the most stable results for service observations with VIMOS, with slit losses and spectral distortions below 20 per cent – and almost independent of target declination. This should always be the preferred option for users having targets at δ ≳ −5 deg or δ ≲ −45 deg. However, for targets within the −45 ≲ δ ≲ −5 deg range, the E-W orientation results in comparable or even reduced slit losses. This slit orientation allows for observations to go past the two-hour angle rule, and be effectively extended up to |HA| = 3 hours, hence making it a preferred option. This holds for all grisms currently offered in VIMOS, provided the acquisition is done with a filter that closely matches the grism wavelength range.

Figure 15 shows the new airmass constraint limits for MOS OBs. They have been significantly relaxed for fields culminating at small zenith distances, thus increasing target observability. This shall enhance the efficiency of operations, and speed up the completion of programmes. Even though the results presented here are specifically tailored to VIMOS, these general recommendations apply to all current and future widefield multi-slit spectrographs (e.g., Magellan/MACS, [Dressler et al. 2011], GMT/GMACS, [DePoy et al. 2012]). They are already in place since September 2013 for VIMOS-MOS observations (Sánchez-Janssen et al. 2013).

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