An Extension to Basis-Hypervectors for Learning from Circular Data in Hyperdimensional Computing

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Abstract—Hyperdimensional Computing (HDC) is a computation framework based on random vector spaces, particularly useful for machine learning in resource-constrained environments. The encoding of information to the hyperspace is the most important stage in HDC. At its heart are basis-hypervectors, responsible for representing atomic information. We present a detailed study on basis-hypervectors, leading to broad contributions to HDC: 1) an improvement for level-hypervectors, used to encode real numbers; 2) a method to learn from circular data, an important type of information never before addressed in HDC. Results indicate that these contributions lead to considerably more accurate models for classification and regression.

Index Terms—hyperdimensional computing, basis-hypervectors, circular data, machine learning, information theory

I. INTRODUCTION

For some time now, machine learning has largely dictated not just academic research and industrial applications, but aspects of modern society in general. Such aspects range from the widespread recommendation systems, which influence the way we consume products, news and entertainment, to social networks that impact the way we behave and relate. Given such broad importance, the demand for devices capable of learning has spread to resource constrained platforms such as embedded systems and Internet of Things (IoT) devices [1]. Such scenarios present obstacles to established methods, designed primarily to operate on powerful servers.

The most notable class of such methods is Deep Learning, which has achieved superhuman performance on certain tasks [2]. Although initially inspired by the remarkably efficient animal brain, Deep Learning owes much of its high energy and computational cost to neurally implausible design choices [3]–[5]. The dilemma is that these choices, especially error back-propagation and large depth, are also key drivers of its success [6]. Given this, the search for alternatives has received significant attention from the scientific community [7], [8].

One emerging alternative is Hyperdimensional Computing (HDC) [9]. Like Deep Learning, HDC is also inspired by neuroscience, but the central observation is that large circuits are fundamental to the brain’s computation. Therefore, information in HDC is represented using hypervectors, typically 10,000-bit words where each bit is independently and identically distributed (i.i.d). This i.i.d relationship, also known as holographic information representation, provides inherent robustness since each bit carries exactly the same amount of information. Furthermore, the arithmetic in HDC, as detailed in Section II, is generally dimension-independent, which opens up the opportunity for massive parallelism, providing the efficiency sought in HDC.

HDC has already proven to be useful in several applications, including both learning problems, such as classification [10] and regression [11], and classical problems, such as consistent hashing [12]. Regardless of the application, the most fundamental step in HDC is mapping objects in the input space to the hyperspace, a process called encoding. Encoding functions have been proposed for several different types of data, such as time series [13], text [14], images [15] and graphs [16]. All these encodings have one thing in common: they start by encoding simple information (e.g. pixel values, vertices and edges, letters, amplitudes of a signal), which are then combined to represent something complex. In this work we study basis-hypervectors, also called seed-hypervectors, the encoding of these atomic pieces of information.

Basis-hypervectors are a cornerstone of HDC and directly effect the accuracy of learned HDC models as we show in Section VI. We start with a study of the two existing types of basis-hypervectors, random and level-hypervectors, used respectively to represent uncorrelated and linearly-correlated data. Inspired by information theory, our first contribution is an improved method to create level-hypervectors.

Based on the improved level-hypervectors, our main contribution is a basis-hypervisor set for circular data. Circular data are derived from the measurement of directions, usually expressed as an angle from a fixed reference direction. In addition, it is common to convert time measurements, such as the hours of a day, to angles. As we will discuss in more detail in Section V, circular data is present in many fields of research, including astronomy, medicine, engineering, biology, geology and meteorology [17]–[19]. Embedded systems and IoT also deal with a wide variety of circular data, such as in robotics where the joints generate angular data [20], and satellites that fly in elliptical orbits [21]. The importance is such that the study and interpretation of this type of data gave rise to a subdiscipline of statistics called directional statistics (also known as circular or spherical statistics) [19]. Despite this great relevance, our work is the first to address learning from circular data in HDC.

To assess the practical impact of these contributions, we conducted experiments with publicly available datasets that contain circular data relevant to real-world applications. We compared the circular-hypervector set with the two existing basis sets in regression and classification tasks. Circular-hypervectors, like level-hypervectors, add no additional runtime overhead as they are generated once before training. We obtained an improvement of 7.2% in the classification of 15 types of surgical gestures. In regression, the error is reduced by 67.7% in temperature and power level prediction tasks.

II. HYPERDIMENSIONAL COMPUTING

Hyperdimensional Computing (HDC) is a computation model that relies on high dimensionality and randomness. Inspired by neuroscience, it seeks to mimic important characteristics of the animal brain while balancing accuracy, efficiency and robustness [9]. The central idea is to represent inputs $x \in \mathcal{X}$ by projecting them onto a hyperspace $H = \{0,1\}^d$, with $d \approx 10,000$ dimensions. This mapping $\phi : \mathcal{X} \to H$ is called encoding, and the resulting representations $\phi(x)$ are named hypervectors.

The intuitive principle that guides the design of encoding functions is that similar objects in input space need to be mapped to similar hypervectors in $H$. We use the normalized Hamming distance as
a measure of distance between hypervectors, which takes the form \( \delta : \mathcal{H} \times \mathcal{H} \to \{ \sigma \in \mathbb{R} \mid 0 \leq \sigma \leq 1 \} \), and define the hypervector similarity to be \( 1 - \delta \). All cognitive tasks in HDC are ultimately based on similarity. Predictions or decisions are inferred from a model which is created by transforming and combining information using HDC arithmetic.

### A. Operations

The arithmetic in HDC is based on a simple set of three element-wise operations [9], illustrated in Figure 1.

- **a) Binding:** Operation used to “associate” information. The function \( \otimes : \mathcal{H} \times \mathcal{H} \to \mathcal{H} \) multiplies two input hypervectors to produce a third vector dissimilar to both operands. Binding is commutative and distributive over bundling and serves at its own inverse, i.e., \( A \otimes (A \otimes B) = B \). The binding operation is efficiently implemented as element-wise XOR.

- **b) Bundling:** Operation is used to aggregate information. The function \( \oplus : \mathcal{H} \times \mathcal{H} \to \mathcal{H} \) performs addition on its inputs to produce a hypervector that is similar to its operands. Bundling is implemented as an element-wise majority operation. The output then represents the mean-vector of its inputs.

- **c) Permuting:** The operator \( \Pi : \mathcal{H} \to \mathcal{H} \) is often used to differentiate permutations of a sequence. The exact input can be retrieved with the inverse operation. The most used permutation is the cyclic shift, and with \( \Pi^i(A) \) we denote a cyclic shift of the elements of \( A \) by \( i \) coordinates.

![Fig. 1. Binding, bundling, and cyclic shift permutation operations illustrated on binary hypervectors A and B where the superscript denotes the element index of the hypervector. The logical gates in bundling are majority gates.](image)

Much of HDC’s ability to learn comes from the fact that the very high dimension of the \( \mathcal{H} \)-space allows combining information with these operations while preserving the information of the operands with high probability, due to the existence of a huge number of quasi-orthogonal vectors in the space [22].

### B. Classification

An overview of the HDC classification framework is illustrated in Figure 2. For each class \( i \in \{ 1, \ldots, k \} \) in the training set, we construct a hypervector \( M_i \) as follows:

\[
M_i = \bigoplus_{j \in \{ \ell(x_j) \}} \phi(x_j)
\]

where each \( x_j \in \mathcal{X} \) is a training sample and \( \ell(x_j) \in \{ 1, \ldots, k \} \) its respective label. The \( \bigoplus \) symbol represents the bundling of hyvevectors. The resulting \( M_i \) is named **class-vector**, and is used as a “prototype” of class \( i \). A trained HDC classification model is therefore denoted by \( \mathcal{M} = \{ M_1, \ldots, M_k \} \), and consists of a class-vector for each class.

Given an unlabeled input \( \hat{x} \in \mathcal{X} \), i.e., a test sample, and a trained model \( \mathcal{M} \), we can compare \( \phi(\hat{x}) \), the **query-vector**, with each class-vector and infer that the label of \( \hat{x} \) is the one that corresponds to the most similar class-vector:

\[
\ell^*(\hat{x}) = \arg \min_{i \in \{ 1, \ldots, k \}} \delta(\phi(\hat{x}), M_i)
\]

where \( \ell^*(\hat{x}) \in \{ 1, \ldots, k \} \) is the predicted class for \( \hat{x} \).

### C. Regression

In a regression setting, an invertible encoding function \( \phi_i \) is used to map labels to hypervectors in a set \( \mathcal{L} = \{ L_1, \ldots, L_k \} \), whose generation is discussed in Section IV. The model \( \mathcal{M} \) consists of a single hypervector, which memorizes training samples \( x \in \mathcal{X} \) with their associated label \( \ell(x) \in \mathbb{R} \):

\[
\mathcal{M} = \bigoplus_{i} \phi(x_i) \otimes \phi_i(\ell(x_i))
\]

A prediction can be made given a trained model \( \mathcal{M} \) and an unlabeled input \( \hat{x} \in \mathcal{X} \). First the approximate label hypervector is obtained by binding the model with the encoded sample \( \mathcal{M} \otimes \phi(\hat{x}) \approx \phi_i(\ell(\hat{x})) \) [9], [22]. The precise label hypervector is then the most similar label hypervector \( L_i \), where:

\[
l = \arg \min_{i \in \{ 1, \ldots, k \}} \delta(\mathcal{M} \otimes \phi(\hat{x}), L_i)
\]

Finally, the label is obtained by decoding the label hypervector:

\[
\ell^*(\hat{x}) = \phi_i^{-1}(L_i)
\]

The encoding functions \( \phi \) and \( \phi_i \), are domain specific and use the HDC operations to encode complex information (e.g., a word) by combining simpler, atomic pieces of information (e.g., the letters of a word). An example is discussed in Section III-A. The first important decision in designing an HDC encoding is how to represent atomic information as hypervectors. These hypervectors represent the smallest pieces of meaningful information and are referred to as **basis-hypervectors**, the central subject in this paper. Our main goal is to show that a special set of basis-hypervectors (described in Section V) is more appropriate for dealing with circular data.

### III. BASIS-HYPERVECTORS

In this section we describe the two existing basis-hypervector sets used to encode unitary of information. Their main feature is the pairwise distances as illustrated in Figure 3.

#### A. Encoding symbols

Early applications in HDC focused on sequences of symbols such as text data [14]. The units of information, in this case characters, were mapped (one-to-one) to hypervectors \( \mathbf{R} = \{ R_1, \ldots, R_m \} \) sampled **uniformly** at random from the hyperspace \( \mathcal{H} \) called **random-hypervectors**. From this, a word \( w = \{ \alpha_1, \ldots, \alpha_n \} \) is typically encoded as:

\[
\phi(w) = \bigoplus_{i=1}^{n} \Pi^i(\phi_R(\alpha_i))
\]
where $\phi_R(\alpha_i) \in \mathbb{R}$ maps the character $\alpha_i$ to its corresponding random-hypervector $R_i$, and $\Pi$ is the permutation operator. In general, any sequence or set comprised of symbolic or categorical data can be encoded using random-hypervectors.

Because of the high dimensionality of $\mathcal{H}$, each pair of random-hypervectors is quasi-orthogonal with high probability [8], i.e., they are not correlated. While this seems suitable for encoding symbols, clearly it is not as adequate for other kinds of unitary information, such as real numbers.

B. Encoding real numbers

Many domains use real numbers to represent information such as distance and time. We encode real values to $\mathcal{H}$ with the function $\phi_L$, which maps them to a discrete set of hypervectors $L = \{L_1, \ldots, L_m\}$. First, we place $m$ points $\{\xi_1, \ldots, \xi_m\}$ evenly over the real interval $[a, b]$. Any real number $x$ is then represented in the hyperspace by $\phi_L(x) = L_l$, where:

$$l = \arg \min_{i \in \{1, \ldots, m\}} |x - \xi_i|$$

The central question here is how to construct the set of hypervectors $L$. There is clearly a stronger relation between neighboring points when compared to $\xi_1$ and $\xi_m$ due to the distance between them. Encoding strategies capable of capturing such relationships lead to better models (see Secs. VI and V). In the next section, we present how hypervectors with this relationship have been created thus far. Then, we propose an improved method that yields more representational power.

IV. GENERATING LEVEL-HYPERVECTORS

A method for representing real numbers with linearly correlated hypervectors was first described by Rahimi et al. [13] and Widows and Cohen [23]. These sets are widely used in HDC and are generally referred to as level-hypervectors. The generation of $L = \{L_1, \ldots, L_m\}$ starts by assigning a uniform random vector to $L_1$. Each subsequent vector is obtained by flipping $d/2/m$ bits. Flipped bits are never unflipped and, therefore, the vectors $L_1$ and $L_m$ share exactly $d/2$ bits, making them precisely orthogonal. In this section, we argue that if the precise distance constraint is relaxed, a set with greater representational power can be created.

A. The importance of quasi-orthogonality

From an information theory perspective, the amount of information conveyed in the outcome of a random trial is a function of the probability of that outcome. More formally, for a given random variable with possible outcomes $\varepsilon_1, \ldots, \varepsilon_n$, which occur with probability $P(\varepsilon_1), \ldots, P(\varepsilon_n)$, the Shannon information content $I$ of an outcome $\varepsilon_i$ is defined as [24]:

$$I(\varepsilon_i) = \log_2 \frac{1}{P(\varepsilon_i)}$$

If we think of a random-hypervector set as a random sample, the probability of each realization is extremely low. Thus the entropy, or information content, is very high. This is one of the main theoretical foundations of HDC.

Note that random-hypervectors are independently and uniformly sampled, resulting in quasi-orthogonal vectors. These vectors are simple to create, but more importantly, they have greater representational power than precisely-orthogonal vectors. In mathematical terms, while the number of orthogonal vectors in $\mathcal{H}$ is $d$, the number of quasi-orthogonal vectors is almost $2^d$ [8]. Given that each set is sampled uniformly, a much larger sample space implies a much lower probability of occurrence per outcome. By the definition above, this results in greater information content.

B. Level-hypervectors revisited: applying the notion of “quasi”

As discussed above, the key to the representational power of random-hypervectors—and more generally of HDC—comes from the relaxed notion of distance: quasi-orthogonality. In contrast, the level-hypervectors created with the existing method have a fixed distance between each pair of hypervectors. This limits the number of possible outcomes of their generation which is equivalent to constraining their representation power. Instead, we want the distance between two hypervectors $L_i$ and $L_j$ in $\mathcal{L}$, with $i < j$, to be proportional to $j-i$ in expectation. If we denote by $\Delta_{i,j}$ the desired value for $E[\delta(L_i, L_j)]$, then:

$$\Delta_{i,j} = \frac{j-i}{2(m-1)}$$

To achieve this goal, we propose the Algorithm 1 presented below. The method starts by assigning two uniformly random hypervectors to $L_1$ and $L_m$, and a $d$-dimensional vector whose elements are sampled uniformly from $[0,1]$ to $\Phi$. Then, for each remaining level $L_i$ an interpolation threshold value $\tau_i$ is set and $\Phi$ acts as a filter to determine each bit, copied either from $L_i$ or from $L_m$. Proposition 1 establishes that the obtained set of level-hypervectors meets the previously motivated property.

**Algorithm 1:** Level-hypervectors using interpolation filter

**Input:** Two positive integers $m$ and $d$

**Output:** A set of $m$ $d$-dimensional level-hypervectors $L = \{L_1, \ldots, L_m\}$

1. $L_1 \leftarrow$ uniform_sampled($0,1)^d$
2. $L_m \leftarrow$ uniform_sampled($0,1)^d$
3. $\Phi \leftarrow$ uniform_sampled($0,1)^d$
4. for each remaining level $l \in \{2, \ldots, m-1\}$ do
5.   $\tau_l \leftarrow \frac{m-l}{m-1}$
6. if each dimension $\partial \in \{1, \ldots, d\}$ do
7.   if $\Phi(\partial) < \tau_l$ then
8.     $L_l(\partial) \leftarrow L_1(\partial)$
9. else
10.    $L_l(\partial) \leftarrow L_m(\partial)$
11. return $\{L_1, \ldots, L_m\}$

**Proposition 1.** Let $L = \{L_1, \ldots, L_m\}$ denote a set of hypervectors generated by Algorithm 1. For all $i$ and $j > i$ in $\{1, \ldots, m\}$, we have $E[\delta(L_i, L_j)] = \Delta_{i,j}$.
probability of the event, we get:

\[ \delta(L_i, L_j) = \frac{1}{d} \sum_{\partial = 1}^{d} \bar{\delta} (L_i^\partial \neq L_j^\partial) \]

where \( \bar{\delta} \) is the indicator function. By applying the linearity of expectation property, the i.i.d. property for all dimensions of \( L_i \), and considering that the expectation of an indicator function equals the probability of the event, we get:

\[ \mathbb{E} [\delta(L_i, L_j)] = \mathbb{P} (L_i^\partial \neq L_j^\partial) \] (1)

where \( \partial \in \{1, \ldots, d\} \) indicates that the probability is dimension independent. Then, from Algorithm 1 we have:

\[ \mathbb{P}(L_i^\partial = L_j^\partial) = \mathbb{P}(\Phi^\partial < \tau_i) + \mathbb{P}(\Phi^\partial \geq \tau_i) \mathbb{P}(L_i^\partial = L_j^\partial) \]

Given that \( \Phi^\partial \) is uniform in \([0, 1]\) and \( \tau_i = \frac{m-1}{m} \) according to the algorithm, we can calculate this probability to be:

\[ \mathbb{P}(L_i^\partial = L_j^\partial) = 1 - \frac{j - i}{2(m - 1)} \] (2)

Considering that the event is binary, from Equations 1 and 2, we get:

\[ \mathbb{E} [\delta(L_i, L_j)] = \Delta^{i-j} \]

In Figure 4 we illustrate how this algorithm can be implemented using a simple circuit. Part (A) shows that, for each level \( L_i \), the output dimensions are the result of a 2-to-1 multiplexer between \( L_{i-1} \) and \( L_m \), whose select line is the result of a comparator between the filter \( \Phi \) and the threshold \( \tau_i \). The filter and threshold value can be represented as random integers instead of floating points for efficiency. We call each of these blocks a Select. In part (B), we show how the vector corresponding to each level is obtained as the output of a Select block by changing only one of the inputs which is the corresponding \( \tau_i \) threshold.

Note that creating basis-hypervectors is an offline process that runs before any training or inference steps, and once created, they can be reused in different applications. We emphasize that their creation, with the proposed method or with the existing one, does not introduce any concrete overhead.

V. Encoding Circular Data

Symbols and real numbers can be represented in the hyperspace with random and level-hypervector sets. However, not every type of data falls into these two categories. Consider, for instance, angular data in \( \Theta = [0, 2\pi] \). The distance \( \rho \in [0, 1] \) between two angles \( \alpha \) and \( \beta \) in \( \Theta \) is defined as [25]:

\[ \rho(\alpha, \beta) = \frac{1}{2} (1 - \cos(\alpha - \beta)) \]

If we use level-hypervectors to encode the \( \Theta \)-interval, the distances between the hypervectors would not be proportional to the distance between the angles. Notice that the endpoints of an interval represented with level-hypervectors are completely dissimilar, while a circle has no endpoints.

Angles are widely used to represent information in meteorology [26], ecology [27], medicine [20], [28], astronomy [29] and engineering [30]. Moreover, many natural and social phenomena have circular-linear correlation on some time scale. Consider for example the seasonal temperature variations over a year or the behavior of fish with respect to the tides in a day. In these cases, it makes sense to represent the time intervals (e.g., Jan 1st - Dec 31st) as cyclic intervals [25], [27].

Given the multitude of applications using circular data, unsurprisingly there has been great scientific effort to adapt statistical and learning methodologies to handle it appropriately [18]. This gave rise to a branch of statistical methodology known as directional statistics [19]. Despite all this effort, to the best of our knowledge, our work is the first to address the adaptation in the context of HDC learning.

A. Circular-hypervectors

We propose a method for creating a basis-hypervector set, called circular-hypervectors, suitable for learning from circular data in HDC. Our method is based on Heddes et al. [12], which proposes the use of hypervectors for a dynamic hashing system. The algorithm for generating equidistant vectors on the circle is improved and extended for the learning context through our analysis of level-hypervectors and the information content control mechanism presented in section V-B.

We want to build a set of hypervectors \( \mathbf{C} = \{C_1, \ldots, C_m\} \) such that for all \( C_i \) and \( C_j \) in \( \mathbf{C} \) their distance \( \delta \) in \( \mathcal{H} \) is proportional to the distance between the angles they represent:

\[ \mathbb{E} [\delta(C_i, C_j)] = \frac{1}{2} \rho \left( \frac{(i - 1)2\pi}{m}, (j - 1)\frac{2\pi}{m} \right) \]

This relationship is in terms of expected value to improve the information content as discussed in Section IV.

The creation of circular-hypervectors, shown in Figures 5 and 4, is divided into two phases, one for each half of the circle. The first half is simply a set of \( m/2 + 1 \) level-hypervectors, with \( C_1 \) and \( C_{m/2+1} \) quasi-orthogonal. The second half is created by applying the transitions between the levels of the first half, in order, from the last hypervector:

\[ C_i = C_{i-1} \oplus T_{i-m/2-1}, \quad i \in \{m/2 + 2, \ldots, m\} \]

where the transition \( T_i = C_i \oplus C_{i+1} \) are the flipped bits between levels \( i \) and \( i + 1 \). The circuit for this process is provided in

1We assume \( m \) to be even to simplify discussions. Sets of odd cardinality can be generated as subsets \( \{C_1, C_3, C_5, \ldots, C_{2m-1}\} \) of a set of size \( 2m \).
Authorized licensed use limited to: Access paid by The UC Irvine Libraries. Downloaded on December 14, 2023 at 18:31:21 UTC from IEEE Xplore. Restrictions apply.
The label is the power level at a given time, encoded as a level-hypervector. The mean squared error for both regression tasks are presented in Table II. Circular-hypervectors reduce the error by 67.7% and 84.4% on average compared to level and random-hypervectors, respectively. These results, combined with those for classification, indicate that circular-hypervectors are indeed more suitable for encoding circular data.

C. r-value
We evaluated separately the effect of the \( r \) parameter on the tasks above by varying its value to interpolate between circular and random-hypervectors. We use the normalized mean squared error for the regression tasks and the normalized accuracy error, defined as \( 1 - \frac{\alpha}{\bar{\alpha}} \) where \( \alpha \) is the accuracy and \( \bar{\alpha} \) the reference accuracy, for classification. The reference for all tasks is set to the performance of random-hypervectors.

Figure 7 shows that better performance can be achieved when \( r > 0 \), as is inline with the theoretical analysis presented in Section IV-A. These results indicate the importance of considering the information content of a basis-hypervector set as we propose. In addition, it shows the value of the proposed \( r \) parameter to control the trade-off between representation power and the ability to preserve correlations in the hyperspace.

![Graph](image)

Fig. 7. Error of the circular-hypervectors with varying \( r \)-parameter, normalized against the random-hypervectors performance.

VII. CONCLUSION
We study basis-hypervectors: stochastically created vectors used to represent atomic information in HDC. Taking inspiration from information theory, we propose a method for creating level-hypervectors with greater representational power. Furthermore, we introduce a method to handle circular data in HDC. This method, which uses the improved level-hypervectors, is the first approach to learning from circular data in HDC. We believe that these contributions have the potential to benefit HDC in general, as they improve the accuracy of models based on circular and real data, present in most learning applications.

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TABLE II

| Dataset       | Random   | Level  | Circular |
|---------------|----------|--------|----------|
| Beijing       | 441.1    | 126.8  | 21.9     |
| Mars Express  | 1294.1   | 715.6  | 339.1    |