The non-perturbative renormalization group in the ordered phase.

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We study some analytical properties of the solutions of the non perturbative renormalization group flow equations for a scalar field theory with $\mathbb{Z}_2$ symmetry in the ordered phase, i.e. at temperatures below the critical temperature. The study is made in the framework of the local potential approximation. The non-perturbative solution is obtained by means of a cutoff procedure aiming at separating slow (q-cut-off version [9–12]. This method implements on the effective average action $\Gamma$ Nicoll, Chang and Stanley for the sharp cut-off version [7, 8] and Wetterich, Ellwanger and Morris for the smooth cut-off version [9–12].

The second formulation, called the “effective average action” approach, was developed after the seminal works of Nicoll, Chang and Stanley for the sharp cut-off version [7, 8] and Wetterich, Ellwanger and Morris for the smooth cut-off version [9–12]. This method implements on the effective average action $\Gamma_k[\phi]$ - roughly speaking the Gibbs free energy of the high modes $\tilde{\phi}_q, q > k$ of the classical field $\phi = \langle \phi \rangle$ - rather than on the Wilsonian action $S_k[\phi]$ the ideas of integration of high-energy modes that underlies any RG approach. The flow of $\Gamma_k$ results in equations which can be solved under the same kind of non perturbative approximations than those used for the Wilson-Polchinski or Wegner-Houghton equations. The main advantage of this more recent formulation is that it gives access to the

I. INTRODUCTION

During the last twenty years the non-perturbative approach to the renormalization group (RG) originated by Wilson [1, 2] has been the subject of a revival in both statistical and quantum field theory. Two main formulations of the non-perturbative renormalization group (NPRG) have been developed in parallel to study a system at equilibrium at, or near to, criticality : for instance, in the simplest case, a system described, at microscopic scale $\Lambda$ (in momentum scale), by an action $S_\Lambda[\phi]$ where $\phi$ is a scalar field. In the first approach, one realizes a continuous RG transformation of the action $S_k[\phi]$ from $k = \Lambda$ to $k = 0$ and, a priori, no expansion with respect to whatsoever small parameter being required. At scale $k$ (in momentum space) the high energy modes $\tilde{\phi}_q, |q| > k$, are integrated out in the “Wilsonian” action $S_k[\phi]$ which is a functional of the slow modes $\tilde{\phi}_q, |q| < k$. This “coarse-graining” operation requires the implementation of some cut-off of the propagator, either sharp or soft, aiming at separating slow ($|q| < k$) and fast ($|q| > k$) modes. This “coarse-graining” process is devised in such a way that all the Wilsonian actions $S_k[\phi]$ yield the same physics in the infra-red (IR) limit ($q \to 0$). The flow of $S_k[\phi]$, from the microscopic scale $k = \Lambda$ to the macroscopic scale $k = 0$, is governed by the Wilson-Polchinski equation [7, 8] in case of a smooth cut-off and the Wegner-Houghton [9, 10] equation in case of a sharp cut-off. Powerful approximation schemes has been devised to obtain approximate, non-perturbative solutions of these equations; for a review see Ref. [6].

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RG flow of physical quantities, i.e. the Gibbs free energy $\Gamma_k[\phi]$ and its field derivatives, the vertex functions, rather than to such an abstract object as the Wilsonian action $S_k[\phi]$. Quite remarkably, the same kind of formalism was developed in a less elaborated language by Reatto et al. in the domain of the theory of classical liquids \[13\, 15\], many years before these recent contributions to statistical field theory. The relations between these corpora of works is discussed in ref. \[16\]. Recent reviews and lectures devoted to Wetterich’s approach are available \[17\, 18\] and should be consulted for a thorough discussion. Wetterich’s version of the RG is in fact equivalent to that of Wilson-Polchinski as discussed in Ref. \[12\, 19\].

In this paper we will adhere to Wetterich point of view and focus on the study of approximate solutions of the NPRG for a scalar field theory with $Z_2$ symmetry, at a temperature $T$ below the critical temperature $T_c$, i.e. in the “ordered phase” or “two phase region”. For $T < T_c$ the system exhibits a spontaneous magnetization $M = \langle \varphi \rangle$ which can take any value in the interval $(−M_0(T), M_0(T))$ with an equal probability in the thermodynamic limit. Henceforth we shall reserve the name spontaneous magnetization for $M_0(T)$. As a result the susceptibility $\chi$ is infinite, or equivalently, the second derivative of the Gibbs free energy with respect to the magnetization $\Gamma''(M) = \chi^{-1} = 0$ in the ordered phase. The potential $\Gamma(M)$, strictly convex for $|M| > M_0$ ($\Gamma''(M) = \chi^{-1} > 0$) is affine for $−M_0 \leq M \leq M_0$.

The simplest non-perturbative version of the NPRG, i.e. the local potential approximation (LPA), yields indeed a convex free energy with a plateau as noticed in Refs \[13\, 14\, 17\, 20\]. However it has been discovered by Reatto et al. that the analytic behavior of $\Gamma''(M)$ in the vicinity of $\pm M_0$ depends strongly on the choice of cut-off and dimension $d$. For a sharp cut-off (and in $d = 3$), $\Gamma''(M)$ is a continuous function of $M$, notably at $\pm M_0$, and thus $\Gamma''(M_0+) = 0$. This is a serious flaw of the theory since obviously $\Gamma''(M)$ should be discontinuous at $\pm M_0$, i.e. vanishing identically in the two phase region with a jump to a finite positive value outside the two-phase region corresponding to a finite susceptibility. In other words one should have $\Gamma''(M_0−) = 0$ and $\Gamma''(M_0+) > 0$. However, with another choice of cut-off function proposed by Litim \[21\], it was shown by Parolla et al. in Ref. \[13\] that, at least in $d = 3$, $\Gamma''(M)$ exhibits the correct discontinuity at $\pm M_0$. In this work we extend these results to any kind of cut-off and dimensions $d$ of space and obtain the mathematical properties to be satisfied by the cut-off function to obtain the required discontinuity of the susceptibility at $M = \pm M_0$. The crux of the whole matter is that the RG flow of Gibbs free energy stops in the ordered phase at some finite RG time and that the solutions of the RG flow can thus be obtained as asymptotic stationary solutions for well chosen dimensionned functions the behavior of which gives insight on the region $M \sim M_0$.

These analytical results are then checked by numerical experiments in the case of a $\varphi^4$ potential where the RG flow equations are solved with a new algorithm which generalizes that devised by Bonanno and Lacagnina \[20\] to any kind of cut-off. The idea is to solve the RG flow for the threshold function rather than for the potential itself, or one of its derivatives. The partial differential equation for the threshold function is of quasi-linear parabolic type or equivalently, the second derivative of the Gibbs free energy with respect to the magnetization $\Gamma''(M) = \chi^{-1} > 0$ is affine for $−M_0 \leq M \leq M_0$. In this work we extend these results to any kind of cut-off and dimensions $d$ of space and obtain the mathematical properties to be satisfied by the cut-off function to obtain the required discontinuity of the susceptibility at $M = \pm M_0$. The crux of the whole matter is that the RG flow of Gibbs free energy stops in the ordered phase at some finite RG time and that the solutions of the RG flow can thus be obtained as asymptotic stationary solutions for well chosen dimensionned functions the behavior of which gives insight on the region $M \sim M_0$.

This study is finally completed by solving the adimensionned flow equations asymptotically in the same vein as that used to solve the dimensionned equations, i.e. by solving the fixed point equations and the associated eigenvalue problem for the threshold functions rather than for the potential. Fixed point functions and critical exponents are then obtained for the three cut-offs with a very high numerical precision, notably for the exponential smooth cut-off non considered up to now: in the case of the sharp and Litim’s cut-off we recover the results obtained previously \[22\, 23\].

The paper is organized as follows; in section II we summarize briefly Wetterich formalism and the LPA approximation. The properties of the RG in the two-phase region are then explored in depth yielding the mathematical conditions to be fulfilled by the cut-off function in order to obtain the correct discontinuous behavior of $\Gamma''(M)$ at $M = \pm M_0$. In section III we devise a new numerical algorithm in which a correct account of both initial and boundary conditions is given. This material is used to perform extensive numerical experiments aimed at testing the theoretical predictions of section II and at computing some universal and non-universal quantities of the $\varphi^4$ potential. Section IV is devoted to a somehow new presentation and numerical study of the adimensionned flow equations. Estimations of the critical exponents of the $\varphi^4$ (or Ising) 3$d$ model in the LPA and for three different cut-off are reported. In the case of Litim’s and sharp cut-off our results are in perfect agreement with those of ref. \[22\, 23\] and in the case of the exponential smooth cut-off we provide the first high precision data for the even and odd spectrum of critical
exponents. We conclude in Section \( \Box \) 

II. NPRG FLOW EQUATIONS IN THE LOCAL POTENTIAL APPROXIMATION

A. The model and the NPRG

We consider a scalar field theory defined at scale \( \Lambda \) by it’s microscopic action

\[
S_\Lambda [\varphi] = \int_x \left\{ \left( \nabla^2 \varphi_x \right)^2 + V_\Lambda (\varphi_x) \right\},
\]

where \( \varphi_x \) is a scalar field defined at some point \( x \) of the domain \( \Omega \) which encloses the system, \( \int_x \equiv \int_\Omega \frac{d^d x}{(2\pi)^d} \) \( (d \equiv \) dimensions of space\( ) \), \( Z_2 \) symmetry is assumed \( (i.e. \ V_\Lambda (\varphi_x) = V_\Lambda (-\varphi_x)) \) and we stick to the convention that brackets \( [\ldots] \) denote functionals while parenthesis \( (\ldots) \) are for functions. Below, for numerical applications, we shall restrict ourselves to the \( \varphi^4 \) potential, i.e., a coarse-grained version of the Ising model with \( V_\Lambda (\varphi_x) = \frac{1}{2} \varphi_x^2 + \frac{1}{4} \varphi_x^4 \) \( (\varphi > 0) \), and will denote by \( r_\varepsilon \) the value of parameter \( r \) at the critical point in the LPA approximation. Finally it is understood that \( \Lambda \) acts as an ultra-violet (UV) cut-off in integrals defined in Fourier space, i.e. \( \int_q \equiv \int_{|q|<\Lambda} \frac{d^d q}{(2\pi)^d} \).

Following Wetterich \([17]\) we introduce a family of related \( k \)-models depending on an index \( k \) in momentum space with \( 0 \leq k \leq \Lambda \). The bare action \( S_k [\varphi] \) of the \( k \)-model - not to be confused with the Wilsonian action briefly alluded to in the introduction- is defined by

\[
S_k [\varphi] = S_\Lambda [\varphi] + \frac{1}{2} \varphi \cdot R_k \cdot \varphi,
\]

where \( \varphi \cdot R_k \cdot \varphi \equiv \int_{p,q} \pi_p \bar{R}_k(p,q) \pi_q \) is a massive term aimed at separating high and low energy field modes. \( \bar{R}_k(p,q) \) is called the cut-off or regulator function. Translational invariance implies \( \bar{R}_k(p,q) = \bar{R}_k(q^2)(2\pi)^d \delta^d (p+q) \) and the general behavior of the cut-off function is \( \bar{R}_k(q^2) = Z_k k^2 (1 - \Theta_k(q,k)) \) where \( Z_k \) is some positive prefactor accounting for field-renormalization and \( \Theta_k(q,k) \) is some smooth approximation of the Heaviside step function \( \Theta(q - k) \) so that when \( \varepsilon \rightarrow 0 \) then \( \Theta_\varepsilon(q,k) \rightarrow \Theta(q - k) \). The cut-off functions must have the following generic behavior

(i) when \( k = 0 \), \( \bar{R}_{k=0}(q^2) = 0 \) identically (\( \forall q \)) and the original model is recovered.

(ii) when \( k = \Lambda \), \( \bar{R}_{k=\Lambda}(q^2) = Z_\Lambda \Lambda^2 \) is sufficiently ”large ” so that all the fluctuations are frozen by the massive term, i.e. the mean-field approximation becomes nearly exact.

(iii) when \( 0 < k < \Lambda \), \( \bar{R}_k(q^2) \) is a decreasing function of \( q \) which tends rapidly to 0 for \( |q| > k \), thus the rapid modes are unaffected by the massive term. On the contrary the slow modes have a large mass which decouples them from the fast modes.

The physics of the \( k \)-systems is encoded in their partition functions

\[
Z_k [J] = \int \mathcal{D}\varphi \exp \left( - S_k [\varphi] + J \cdot \varphi \right),
\]

where the functional measure \( \mathcal{D}\varphi \) integrates over all the field modes \( \varphi_q \ (|q| < \Lambda) \) and \( J \cdot \varphi \equiv \int_x J_x \varphi_x \ (J \ \text{source}) \). At scale ”\( k \)” the slow modes \( \varphi_q, |q| < k \), are frozen by their mass \( \bar{R}_k(q^2) \sim Z_k k^2 \) and \( W_k [J] = \log Z_k [J] \) can therefore be interpreted as the generator of the connected Green’s function with an IR cut-off. It is a convex function of the source \( J \) and it’s Legendre transform defined as

\[
\Gamma_k [\phi] = \sup_J (J \cdot \phi - W_k [J]),
\]

is also a convex functional of the order parameter \( \phi = < \varphi > \). \( \Gamma_k [\phi] \) is the ”true” Gibbs free energy of the \( k \)-system. However it proves convenient to introduce and consider rather the effective average action of Wetterich

\[
\Gamma_k [\phi] = \Gamma_k [\phi] - \frac{1}{2} \phi \cdot R_k \cdot \phi.
\]

By contrast with \( \Gamma_k [\phi] \) this functional of the field \( \phi \) is non-convex but has simple limits which follow from the mathematical properties of the cut-off function \( R_k [17] \), i.e.,
• when \( k = \Lambda \) no fluctuations has been integrated out. and we will suppose that \( \Gamma_{k=\Lambda} [\phi] \equiv S_{\Lambda} [\phi] \) (mean field approximation).

• when \( k = 0 \) all fluctuations have been integrated out and \( \Gamma_{k=0} [\phi] = \Gamma [\phi] \) is the Gibbs free energy of the model under study.

Therefore when \( k \) decreases from its initial value \( \Lambda \) to \( k = 0 \) all the fluctuations of the field are progressively integrated out and the effective action \( \Gamma_k [\phi] \) flows from the bare action \( S_{\Lambda} [\phi] \) (i.e. the mean-field approximation for \( \Gamma [\phi] \)) to the Gibbs free energy \( \Gamma [\phi] \) of the model. The flow equation reads as [17]

\[
\partial_k \Gamma_k [\phi] = \frac{1}{2} \int_q \partial_k \tilde{R}_k (-q, q) \left\{ \tilde{R}_k + \tilde{\Gamma}_k^2 \right\}^{-1} (-q, q),
\]

where the inverse in the r.h.s. of Eq. (6) has to be understood in the operator sense, \( \tilde{\Gamma}_k \) is the vertex function of order 2 and \( \tilde{\Gamma}_k^2 (p, q) \) denotes is 2d dimensional Fourier transform. Note that \( \tilde{\Gamma}_k^2 \) depends functionally on the field \( \phi \) and the equation for \( \Gamma_k [\phi] \) is thus not closed. One has to resort to approximations to solve the flow.

### B. The local potential approximation

A simple, non trivial way to tackle with Eq. (6) is to restrict the functional space to functionals of the form

\[
\text{(LPA ansatz)} \quad \Gamma_k [\phi] = \int_x \left\{ \frac{1}{2} (\nabla \phi_x)^2 + U_k(\phi_x) \right\},
\]

which constitutes the popular local potential approximation (LPA). Note that in this scheme there is no field-renormalization so that \( \tilde{Z}_k = 1 \). We also stress that the local potential \( U_k(\phi_x) \) is a function of the local field \( \phi_x \) at point \( x \), not a functional. Combining Eqs. (6) and (7) one then obtains a closed partial differential equation (PDE) for the \( U_k \) which reads as

\[
\partial_k U_k (M) = \frac{1}{2} \int_q \frac{\partial_k \tilde{R}_k(q^2)}{q^2 + \tilde{R}_k(q^2) + U''_k'(M)},
\]

where the potential \( U_k (M) \) is evaluated for a uniform magnetization \( \phi_x = M \) and \( U''_k (M) \equiv \partial^2 U_k (M) / \partial M^2 \) denotes its partial derivative with respect to \( M \). The PDE Eq. (8) is non-linear but however quite easy to solve numerically above the critical point \( (r > r_c, \text{in the case of the } \varphi^4 \text{ potential}) \). Difficulties arise in the ordered phase. To understand why, we rewrite Eq. (5) under a more convenient form. We define the dimensionless variable \( t = -\log(k/\Lambda) \), the RG time chosen to increases from 0 to \( +\infty \) when \( k \) decreases from \( \Lambda \) to 0, the dimensionless variable \( y = q^2/k^2 \) and the dimensionless functions of \( "y" \) : \( r(y) = \tilde{R}_k(q^2)/q^2 \) (so that \( \tilde{R}_k(q^2) = y r(y) k^2 \)), \( s(y) = -2y^2 r(y) \), and \( t(y) = y(1 + r(y)) \) so that

\[
\partial_t U_k (M) = -2v_d k^d \mathcal{L}(U''_k (M)/k^2),
\]

where \( v_d^{-1} = 2^{d+1} \pi^d \Gamma(d/2) \) and the threshold function \( \mathcal{L} \) (according to Wetterich terminology) is defined as

\[
\mathcal{L} : \omega \mapsto \frac{1}{2} \int_0^\infty y^{d-1} s(y) \frac{dy}{t(y) + \omega}.
\]

This function \( \mathcal{L} (\omega) \) plays a central role in the mathematical analysis of Sec. [14][16] and we need first to study its relevant analytical properties. For reasonable cut-off functions the two functions \( s(y) \), and \( t(y) \) are positive for \( y \geq 0 \) so that \( \mathcal{L} (\omega) \) is a decreasing function of it’s argument. In any reasonable case the function is defined on the interval \( [\omega_0, +\infty[ \) where \( \omega_0 \) is the largest pole of the integrand in the r.h.s. of Eq. (10) (for any reasonable choices of the cut-off \( r(y) \) there is in general only a single pole). Therefore \( \mathcal{L} (\omega) \) decreases from \( +\infty \) to 0 when \( \omega \) increases from \( \omega_0 \) to \( +\infty \). Finally note that \( U''_k (M)/k^2 \) is indeed a dimensionless quantity which gives sense to Eq. (9).

Before we tackle the general case let us consider two important cases. First, the (ultra) sharp cut-off defined by the regulator \( \tilde{R}_k(q^2) = \beta k^2 (1 - \theta(q^2 - k^2)) \) where the parameter \( \beta \to +\infty \). In that case one shows that \( \mathcal{L}(\omega) = -\ln(1+\omega) \) [17], so that the flow equation reads as

\[
\partial_t U_k (M) = 2v_d k^d \ln(1 + U''_k (M)/k^2).
\]
A second important case that we shall consider is Litim's regulator $\tilde{R}_k(q^2) = (k^2 - q^2)(1 - \theta(q^2 - k^2))$ which yields $L(\omega) = (2/d)/(1 + \omega)$ and the flow equation \[11\] $\partial_t U_k(M) = -4v_d \frac{k^d}{d^2} \frac{1}{1 + U_k^2(M)/k^2}$. 

**TABLE I:** Constants characterizing the exponential smooth cut-off threshold function in the case $\alpha = 6$.

| $y_0$ | $\omega_0$ | $K_0$ | $K_1$ | $K_2$ | $K_3$ | $C_1$ | $C_2$ | $C_3$ |
|-------|------------|-------|-------|-------|-------|-------|-------|-------|
| 2.3680622962455447582396946574 | -3.83637249545350290077137812782 | 34.2450749455029367943794121780 | 26.7493078693695013104149308428 | -123.598329790226947089342622508 | 600.184183291720248551501270440 | 26.7493078693695013104149308428 | -4.620602317622947089342622508 | 0.406488093691634129962437962261 |

Let us consider now a regular smooth cut-off function. We have retained the exponential regulator widely used in recent numerical studies (see e. g. ref [24])

$$\tilde{R}_k(q^2) = \alpha q^2 / (\exp(q^2/k^2) - 1)$$ \[13\] that is, written in reduced form $r(y) = \alpha/(\exp(y) - 1)$, where $\alpha$ is some positive parameter. It is easy to see that

(i) When $\alpha > 2$ the function $t(y) = y(r(y) + 1)$, defined for $y \in [0, +\infty]$, exhibits a single minimum at some $y_0 > 0$ and $t'(y_0) = 0$.

(ii) When $\alpha = 2$ the minimum of $t(y)$ occurs precisely at $y_0 = 0$ and $t'(0) = 0$.

(iii) When $0 < \alpha < 2$ the minimum of $t(y)$ on the interval $(0, \infty)$ is located at $y_0 = 0$ but $t'(0) > 0$.

The choice $\alpha = 6$ yields the better critical exponents according to the authors of reference [24] so we will retain this value; we are thus in the case (i) where the minimum of function $t(y)$ is located at some non-zero value $y_0$. We introduce $\omega_0 = -\min_{0 \leq y \leq \infty} t(y) = -t(y_0)$. The threshold function $\omega \mapsto L(\omega)$ is thus a monotonously decreasing function defined on the interval $[\omega_0, \infty]$. Let us precise now its asymptotic behavior at each boundary of the interval.

Wetterich et al. [17] have shown how to obtain the behavior of $L(\omega)$ for $\omega \rightarrow \omega_0^+$; one expands $t(y)$ around its minimum, i. e. $t(y) = -\omega_0 + t_2 \delta y^2 + \mathcal{O}(\delta y^3)$, where $\delta y = y - y_0$ and recognize the fact that, at the leading order,

$$L \simeq \frac{1}{2} \int_{-\infty}^{+\infty} \frac{y_0^{d/2-1}s(y_0)}{\omega - \omega_0 + t_2 \delta y^2} d\delta y,$$

$$\simeq K_0 (\omega - \omega_0)^{-1/2},$$ \[14\]

where

$$K_0 = \frac{\pi y_0^{d/2-1}s(y_0)}{2\sqrt{t_2}},$$ \[15\]

and $t_2 = t''(y_0)/2$.

Note that in Litim’s case one has $\omega_0 = -1$, $t(y) = 1$; therefore the previous analysis breaks down and $L(\omega)$ diverges as $\sim (\omega - \omega_0)^{-1}$ rather than as $\sim (\omega - \omega_0)^{-1/2}$. In the case of the ultra sharp cut-off $\omega_0 = -1$ but the function $t(y)$ is not well defined yielding a logarithmic divergence of $L(\omega)$ as $\omega \rightarrow \omega_0 = -1$.

On the other hand an asymptotic behavior of $L(\omega)$ for $\omega \rightarrow \infty$ is readily obtained from \[11\] and reads

$$L(\omega) = \frac{K_1}{\omega} + \frac{K_2}{\omega^2} + \frac{K_3}{\omega^3} + \ldots$$

$$K_n \equiv \frac{(-1)^{n+1}}{2} \int_0^{\infty} dy y^{d/2-1}s(y)t(y)^{n-1}.$$ \[16\]
Since ω ↦→ L = L(ω) is bijective from ]ω₀, ∞[ to ]∞, 0[ it can be inverted and we denote by ω = L⁻¹ its inverse. This function is defined on the interval ]0, ∞[ where it decreases from +∞ to ω₀.

For L → 0 we infer from (16) that

\[ \omega(L) \approx \frac{C_1}{L} + C_2 + C_3 L + \ldots, \] (17)

where

\[ C_1 = K_1 \quad ; \quad C_2 = \frac{K_2}{K_1} \quad ; \quad C_3 = \frac{K_3 - K_2^2 / K_1}{K_1^2}, \] (18)

and for L → ∞

\[ \omega(L) = \omega_0 + \frac{K_2^2}{L^2} + \ldots. \] (19)

The values of the constants y₀, ω₀, K₀, K₁, K₂, K₃, C₁, C₂, C₃ are determined numerically; they are resumed in Table I in the case α = 6. For numerical applications the functions ω(L) or L(ω), as well as their derivatives if required, have been fitted by polynomial expressions taking into account their asymptotic behaviors.

C. Flow equations for the threshold functions

As suggested first by Bonanno and Lacagnina [20] (however in a more restricted context) it is convenient to perform the change of variables \((M, k, U) \Rightarrow (M, k, L)\) with

\[ L_k(M) = \mathcal{L}(U_k''(M)/k^2). \] (20)

The one to one mapping ω ⇔ L insures the mathematical equivalence of solving the RG flow equations either for \(U_k''\) or for \(L_k\). However, for numerical reasons the RG flow equation for \(L_k\) is much easier to solve than that for \(U_k\) [20]. The RG flow equation for \(L_k\) is readily deduced from that for \(U_k\) (cf. (9)):

\[ L_k'' = -\frac{k^{2-d}}{2v_d} \omega'(L_k) \frac{\partial L_k}{\partial t} + \frac{k^{2-d}}{v_d} \omega(L_k). \] (21)
Eq. (21) is a quasi-linear parabolic PDE which can be studied analytically in some depth, notably in the two phase region, and for which, in addition, the mathematicians have provided us with robust and efficient solvers in view of a numerical study. For the exponential smooth cut-off (13) the function $\omega(L_k)$ and its derivatives which enter Eq. (21) must be determined numerically. It is worthy to write down explicitly these flow equations

- for the sharp cut-off regulator ($L(\omega) = -\ln(1+\omega)$ and $\omega(L) = \exp(-L) - 1$)
  \[
  L''_k = \frac{k^{2-d}}{2v_d} \exp(-L_k) \frac{\partial L_k}{\partial t} + \frac{k^{2-d}}{v_d} \exp(-L_k) - 1 .
  \]  

- and for Litim’s regulator ($L(\omega) = (2/d)(1+\omega)$ and $\omega(L) = 2/(dL_k) - 1$)
  \[
  L''_k = \frac{k^{2-d}}{v_d} \frac{1}{dL_k^2} \frac{\partial L_k}{\partial t} + \frac{k^{2-d}}{v_d} \left( \frac{2}{dL_k} - 1 \right) .
  \]  

D. Behavior of the flow in the ordered phase

Below $T_c$, a spontaneous magnetization $M_0(r)$ can settle in the system in the absence of an external magnetic field $J$. More precisely, in the thermodynamic limit, any magnetization $-M_0(r) \leq M \leq M_0(r)$ is likely to settle with the same probability. Roughly speaking we have a coexistence region of two (or more) magnetized phases $\pm M_0$ analogous to a liquid-vapor coexistence. Therefore $\Gamma''(M) = \partial J/\partial M \propto \bar{T}^{(2)}(0)$ from which it follows that, in the limit $k \to 0$ the denominator of the r.h.s. of Eq. (5) tends to zero. Therefore the threshold function $L_k(M)$ should become large and positive as $k \to 0$ and finally it should diverge to $+\infty$ at $k = 0$ for any magnetization in the two phase region $-M_0 \leq M \leq M_0$.

With the hypothesis that $L_k$ is large and positive, $\omega(L_k) \sim \omega_0$ as follows from (13); then the flow equation (21) for $L_k$ simplifies to

\[
L''_k = \frac{k^{2-d}}{v_d} \omega_0 ,
\]
FIG. 3: Litim’s approximation: from right to left and bottom to top: local potential $U_k(M)$, the derivatives $U'_k(M)$ (magnetic field), $U''_k(M)$ (inverse susceptibility), and $U''_k(M)$ for different values of $k$ in the range $k_{min} < k < \Lambda$, with $k_{min} = 10^{-6}$. The $\varphi^4$ potential is used at scale $\Lambda = 10$ with $g = 1.2$, and $r = -0.35$ ($M_{max} = 8$). Red lines: result at $k = k_{min}$.

which can be integrated to give

$$L_k(M) = \frac{-k^{2-d}}{2\nu_d} \omega_0 (M_0(k)^2 - M^2).$$

for $-M_0(k) \leq M \leq M_0(k)$ where $M_0(k)$ is the constant of integration (depending on $k$) of Eq. (24). Clearly $M_0(k)$ can be interpreted as a precursor of the magnetization of the system at scale $k$. Note that $M_0(k)$ can be obtained numerically from the numerical solution of PDE (21) from the value of $L_k(M = 0) = -\omega_0 M_0(k)^2 k^{2-d}/(2\nu_d)$ at the origin. As expected one finds that for $d > 2$ the function $L_k(M)$ diverges to $+\infty$ (recall that $\omega_0 < 0$) when $k \rightarrow 0$ as $\propto k^{2-d}$ for any magnetization $M$ in the two phase region.

Outside the coexistence region - i.e. for $|M| > M_0(k)$- one expects a finite compressibility and thus $L_k(M)$ tends to 0 as $\sim K_1 k^2/U''_k(M)$ with $k$, as follows from (14). This behavior of $L_k(M)$ is exemplified in figure 1 (details concerning the numerical procedure to solve (21) will be given in Sec. III).

One of the consequences of Eq. (25) is the universal behavior:

$$\frac{L_k(M)}{L_k(0)} = 1 - x \text{ with } x = (M/M_0(k))^2 \text{ for } |x| \leq 1$$

$$\frac{L_k(M)}{L_k(0)} = 0 \text{ for } |x| \geq 1.$$
\[-M_0(k) \leq M \leq M_0(k)\]

\[
U_k''(M) = k^2 \omega_0 \\
U_k'(M) = k^2 \omega_0 M \\
U_k(M) = \frac{1}{2} k^2 \omega_0 M^2 + \text{constant},
\]

where we have noted that \(U_k'(M = 0) = 0\) for a \(Z_2\) symmetry; see figure \(\ref{fig:Z2_symmetry}\) for an illustration. In the special case of the sharp cut-off and Litim regulator recall that one has to set \(\omega_0 = -1\) in the above equations. Another interesting consequence of this simple behavior for the potential and its derivatives is the expression of the "true" susceptibility of the \(k\)-system (cf. Eq. \(\ref{eq:susceptibility}\)) which is a serious flaw in the theory (see figure \(\ref{fig:susceptibility}\)). In the special case of the sharp cut-off and Litim regulator recall that one has to set \(\omega_0 = -1\) in the above equations. Another interesting consequence of this simple behavior for the potential and its derivatives is the expression of the "true" susceptibility of the \(k\)-system (cf. Eq. \(\ref{eq:susceptibility}\)) which is a serious flaw in the theory (see figure \(\ref{fig:susceptibility}\)). In the special case of

\[
d^2 \Gamma_k(M) = \sum_{k}^\prime \left( \Gamma_k''(M) - \frac{\nu}{(\omega_0 - \omega)^\nu} \right),
\]

and is thus positive at any \(k \neq 0\). However the strict convexity of \(\Gamma_k(M)\) is preserved at each step of the RG flow in the LPA approximation only if \(\alpha > 2\) as follows from the discussion after Eq. \(\ref{eq:rg_flow}\). Note that in that case Eq. \(\ref{eq:susceptibility}\) becomes

\[
d^2 \Gamma_k(M) = (\alpha + \omega_0)k^2.
\]

In the case \(\alpha \leq 2\), strict convexity could be violated and the validity of the LPA is no more guaranteed.

The simple behavior described by Eqs. \(\ref{eq:potential}\) is independent of the regulator and has been known from long \(\ref{eq:potential}\) \(\ref{eq:regulator}\). However Parolla et al. \(\ref{eq:potential}\) \(\ref{eq:regulator}\) were the first to remark, in a more refined discussion, that the behavior of the susceptibility for \(M \to \pm M_0(k)\) depends strongly on the asymptotic behavior of \(\mathcal{L}(\omega)\) for \(\omega \to \omega_0^+\). For the sharp cut-off regulator they found that \(U_k''(M)\) is continuous and equal to zero at \(M = M_0\) (for \(d < 4\)) (see Ref. \(\ref{eq:potential}\)) while for the Litim regulator they found that, for \(d > 2\), \(U_k''(M)\) exhibits a discontinuity from a finite positive value at \(M = M_0^+\) to a zero value at \(M = M_0^-\) (cf. Ref. \(\ref{eq:potential}\)). This discontinuity of the susceptibility \(\chi\) jumping from an infinite value in the two-phase region to a finite one outside, is of course the expected physical behavior for \(\chi\). In other words, in the case of the sharp cut-off regulator, the spinodal and the binodal curves merge in a single curve, which is a serious flaw in the theory (see figure \(\ref{fig:merging_curves}\)).

We now extend the analysis of Parolla et al. to the quite general case:

\[
\mathcal{L}(\omega) = \frac{K_0}{(\omega - \omega_0)^\nu},
\]

where \(\nu > 0\) is an arbitrary exponent, not to be confused with the critical exponent of the correlation length! This expression includes notably the case of the exponential smooth cut-off considered in this paper - with \(\nu = 1/2\), cf. Eq. \(\ref{eq:potential}\) - since only the singularity of \(\mathcal{L}(\omega)\) as \(\omega \to \omega_0^+\) is relevant to study the behavior of \(U_k''(M)\) as \(M \to \pm M_0\). As follows from \(\ref{eq:potential}\), when \(k \to 0\) \(L_k(M)\), diverges therefore to \(+\infty\) for \(M < M_0\) for \(d < 2\) and tends uniformly to 0 outside the interval \((-M_0, M_0)\) (see fig. \(\ref{fig:potential}\)). This behavior is too "drastic" to discriminate the analytical properties of \(U''(M)\) in the vicinity of \(\pm M_0\). Borrowing an idea of Reatto et al. we introduce the following new function of the field

\[
F(k, M) = \frac{1}{(U_k''(M) - k^2 \omega_0)^\nu} = K_0^{-1} k^{-2\nu} L_k(M).
\]

In the two phase region \(U_k''(M) \to 0\) as \(k \to 0\) and thus \(F \to +\infty\), while outside \(0 < U_k''(M) < \infty\) yielding \(F\) to reach a finite value \(F_0\) at \(k = 0\). It follows from \(\ref{eq:potential}\) and \(\ref{eq:regulator}\) that for \(k \to 0\) and \(|M| \leq M_0(k)\)

\[
F(k, M) = k^{2-d-2\nu} \omega_0 (x^2 - x_0(k)^2)
\]

\[
x = \frac{M}{\sqrt{2} v_d K_0},
\]

\[
x_0(k) = \frac{M_0(k)}{\sqrt{2} v_d K_0}.
\]

We are led to introduce the new variable

\[
z = (x - x_0(k)) k^{2-d-2\nu}
\]
such that, at fixed $z$ and for $k \to 0$, one has

$$F(k, M) \approx 2\omega_0 x_0(k) z,$$  \hspace{1cm} (33)

valid if $2\nu > -d + 2$, i. e. $\nu > 0$ if $d > 2$. As quoted pleasingly by Parola et al.\[13, 15\] this variable $z$ allows us to "zoom" in the region $x \approx x_0(k)$. Inside the two-phase region $z \to -\infty$ and we have the asymptotic behavior (33) of $F$, while for $z \to \infty$, i. e. outside the the two-phase region, the function $F$ should reach a finite value $F_0$. To avoid a proliferation of notations we still write $F(k, z)$ the function $F(k, M)$ expressed in terms of its new variables $(k, z)$.

The dependence of the reduced spontaneous magnetization $x_0(k)$ on $k$ as $k \to 0$ will prove of great importance in our analysis. A priori it should be reasonable to assume a $k$-dependence as

$$M_0(k) \sim M_0 - ak^2$$ with $a > 0$  \hspace{1cm} (34)

for sufficiently small $k$’s, since $M_0(k)$ should be an analytical function of vector $\vec{k}$. Parameter $a > 0$ describes the displacement of the precursor of the spontaneous magnetization $M_0(k) = \sqrt{2d\nu(1/k_0)}$ with scale $k$. With this reasonable assumption we can finally wrote the RG flow equation:

$$z \equiv k^{2-d-2\nu}(x - x_0 + ak^2),$$

$$k^{4-d-2\nu} \frac{\partial^2}{\partial z^2} F(k, z) = 2k^2\omega_0 + \frac{-1}{\nu} \frac{1}{F^{1/\nu+1}(k, z))} \times$$

$$\times [k \partial_k F(k, z) + (2 - d - 2\nu)z\partial_z F(k, z) + 2ak^{4-d-2\nu}\partial_z^2 F(k, z)]. \hspace{1cm} (35)$$

We now analyse the asymptotic behavior of the stationary solutions ($k\partial_k F(k, z) = 0$) of EDP (35) at $z \to \pm\infty$ in the limit $k \to 0$. This is justified since below $r_c$ the flow stops at some finite $k$. These solutions are similar to scaling solutions at a fixed point; however $F(k, z)$ and $z$ have dimensions and we cannot thus speak of scaling solutions stricto sensu. Obviously, in order to find these solutions, which we cannot refrain to christen as fixed point solutions despite our previous remarks, we have to discriminate our study according the sign of the exponent $4 - d - 2\nu$ in Eq. (35).
Neglecting terms which tend to 0 when $k \to 0$ in Eq. (35) one finds the implicit fixed-point equation:

$$\frac{\partial^2}{\partial z^2} F(z) = 2a - \frac{1}{\nu} F^{1/\nu+1}(z) \frac{\partial}{\partial z} F(z),$$

(36)

where $F(z) \equiv F(k=0,z)$. This is an autonomous differential equation which can be solved analytically:

$$-cz + d = F_0 \left( F/F_0 \right),$$

(37)

where $c > 0, d$ are integration constants, $F_0 = (2a/c)\nu$ and $F(X)$ a primitive of $f(X) = 1/(1 - X^{-1/\nu})$. We define $n_0$ as the integer part of $\nu, \delta$ as its decimal part, i.e. $\nu = n_0 + \delta$, and we have

$$F(X) = X + \frac{\nu}{\delta} (X^{4/\nu} - 1) + \nu (1 - \delta n_0) \sum_{n=1}^{n_0-1} \frac{X^{(\nu-n)/\nu}}{\nu - n} - \nu X^{(\delta-1)/\nu} \Phi(X^{-1/\nu}, 1, 1 - \delta),$$

(38)

where the third term in the r.h.s. of the equation is present only if $\nu \geq 2$ and $\Phi(z, s, a)$ is the Lerch transcendent \[25, 26\]. This curiosity is defined on the disk $|z| < 1$ (although it can be extended by analytical continuation to the cut plane $\mathbb{C} - [1, \infty]$). It is defined as

$$\Phi(z, s, a) = \sum_{n=0}^{\infty} \frac{z^n}{(a+n)^s},$$

$$a \neq 0, -1, \ldots, |z| < 1; |z| = 1; \Re(s) > 1$$

(39)
When \( \nu = n_0 \) is an integer Eq. (38) reduces to the simple form:

\[
F(X) = X + \ln X + n_0 (1 - \delta_{n_0,1}) \sum_{p=1}^{n_0-1} \frac{X^{p/n_0}}{p} + n_0 \ln(1 - X^{-1/n_0}).
\]

This result was first obtain in Ref. [13] in the case \( n_0 = 1 \) (Litim case). From the known behavior of Lerch function, in particular \( \Phi(z^{-1/\nu}, 1, 1 - \delta) \sim -\ln(1 - z^{-1/\nu}) \) for \( z \to 1+ \) one deduces that

\[
\begin{align*}
F(X) &\sim X \text{ for } X \to +\infty \\
F(X) &\sim \nu \ln(X^{1/\nu} - 1) \text{ for } X \to 1+
\end{align*}
\]

We are now in position to discuss the property of the fixed point solution Eq. (37). In the two phase region, \( z \to -\infty \), the function \( F \sim 2\omega_0 x_0 z \) diverges to \( +\infty \), thus \( F(F/F_0) \sim F/F_0 \), and one has asymptotically \( -cz \sim 2\omega_0 x_0 z \) which fixes the value of the integration constant \( c = -2\omega_0 x_0 \), from which we deduce \( F_0 = (-a/(\omega_0 x_0))^\nu \). In the one phase sector, \( z \to +\infty \) we find that \( F \to F_0 \) reaches a finite value as \( k \to 0 \). Returning to our old variables \((k, M)\) we have shown that the fixed point solution satisfies:

\[
\begin{align*}
\lim_{M \to M_0 + k \to 0} \lim_{k \to 0} F(k, M) &= 0 < F_0 < \infty, \\
\lim_{M \to M_0 - k \to 0} \lim_{k \to 0} F(k, M) &= +\infty,
\end{align*}
\]

from which follows that for \( 4 - d - 2\nu < 0 \) (and \( d > 2 \)) the susceptibility \( \chi = F(0, M)^\nu \) is discontinuous at \( M = \pm M_0 \). See Fig. (5) for an illustration.

\[2. \quad 4 - d - 2\nu = 0\]

We consider here the marginal case \( 4 - d - 2\nu = 0 \). It is an important one since it corresponds to the general smooth cut-off (\( \nu = 1/2 \), cf Eq. (11)) in \( d = 3 \). Neglecting terms which tend to 0 when \( k \to 0 \) in Eq. (35) one finds the implicit fixed-point equation:

\[
\frac{\partial^2}{\partial z^2} F(z) + 2(a - z) \frac{1}{\nu} F^{1/\nu + 1}(z) \frac{\partial}{\partial z} F(z) = 0.
\]

This equation does not seem to have an analytical solution but, asymptotically:

\[
\begin{align*}
F(z) &\sim 2\omega_0 x_0 z \text{ for } z \to -\infty, \\
F(z) &\sim F_0 < +\infty \text{ for } z \to +\infty.
\end{align*}
\]

Equation (44a) is required by the correct matching with the solution (39) in the two-phase region while (44b) guarantees finite susceptibility outside the magnetization curve. We conclude again in favor of a discontinuity of the susceptibility at \( M = M_0 \). See Fig. (6) for an illustration.

\[3. \quad 4 - d - 2\nu > 0\]

In this case the term in "a" which accounts for the displacement of the spontaneous magnetization \( M_0(k) \) with scale \( k \) (cf Eq. (34)) can be discarded from Eq. (35). The function \( F(k, z) \) is no more adapted to our discussion and we are led to a new change of variables to eliminate the relevant dependence on \( k \) from the RG flow equation. Let us introduce

\[
G(k, z) = k^{-\mu} F(k, z),
\]

\[
\mu = \frac{d - 4 - 2\nu}{\nu + 1} > 0.
\]

By use of these variables the RG flow equation for \( G \) admits in the limit \( k \to 0 \) a stationary solution \( G(z) \) which satisfies the following differential equation:

\[
\frac{\partial^2}{\partial z^2} G(z) + \frac{1}{\nu} \frac{1}{G^{1/\nu + 1}(z)} \left\{ \mu G(z) + (2 - d - 2\nu) z \frac{\partial}{\partial z} G(z) \right\} = 0.
\]

\[46\]
This equation cannot be solved analytically but it satisfies the boundary conditions

\[ G(z) \propto z \text{ for } z \to -\infty, \quad (47a) \]

\[ G(z) \sim z^{\nu/(d-2-2\nu)} \text{ for } z \to +\infty. \quad (47b) \]

Equation \((47a)\) is required by the correct matching with the solution \((33)\) in the two-phase region, while \((47b)\) implies a non-physical divergence of the susceptibility on the magnetization curve. Indeed it follows from \((47b)\) and \((15)\) that

\[ U''_{k=0} = F^{-1/\nu} \propto (M - M_0)^\varpi \quad (M > M_0 \text{ since } z \to +\infty) \]

where the exponent

\[ \varpi = \frac{4 - d + 2\nu}{(\nu + 1)(d-2+2\nu)} \quad (48) \]

is strictly positive if \(d > 2\). Not unexpectedly, one recovers, in the limit \(\nu \to 0\), the exponent \(\varpi = (4 - d)/(d - 2)\) obtained by Parolla et al. in the case of the sharp cut-off \([13]\). For the cut-off considered in this section the LPA seems to detect the spinodal rather than the coexistence curve and the exponent \(\varpi\) can be interpreted as the exponent of the inverse compressibility \(\chi^{-1}(M)\) on the spinodal. Note that, however, it depends strongly on the non-physical exponent \(\nu\) which characterizes the divergence of the threshold function as \(\omega \to \omega_0\).

We conclude that for \(4 - d - 2\nu > 0\) (and \(\nu \geq 0\) and \(d > 2\)) the LPA has the unphysical feature to give an infinite susceptibility at \(M = \pm M_0\). The isotherm \(U''(M)\) is continuous with \(M\) and vanishes exactly in the two-phase region. See Figs. (7) and (8) for an illustration.

The conclusion of this section is that, if the singularity of the threshold function \(\omega\) at \(\omega = \omega_0^+\) is characterized by the exponent \(\nu\) (cf Eq. \((29)\)) and if \(d > 2\), then

- For \(0 < \nu < \frac{4 - d}{2}\) the inverse compressibility \(U''(M)\) is continuous at \(M_0\), which constitutes a severe flaw of the theory.
- For \(\frac{4 - d}{2} \leq \nu\) the inverse compressibility \(U''(M)\) is discontinuous at \(M_0\)
III. NUMERICAL INTEGRATION OF THE DIMENSIONED RG FLOW EQUATIONS

A. Algorithm

In order to solve the EDP (21) we must specify

- (i) an arbitrary initial condition at \( t = 0 \) (\( k = \Lambda \))
  \[
  L_\Lambda(M) = L_i(M) \quad \forall M \in (-M_{\text{max}}, M_{\text{max}}),
  \]
  where \( M_{\text{max}} \) is some maximum magnetization.
- (ii) boundary conditions
  \[
  L_k(\pm M_{\text{max}}) = L_b(k) \quad \forall k \in (k_{\text{min}}, \Lambda),
  \]
  where \( k_{\text{min}} \) is some minimum value of the scale \( k \).
- (iii) The functions \( L_i(M) \) and \( L_b(k) \) \textit{a priori} arbitrary must be such that
  \[
  L_i(\pm M_{\text{max}}) = L_b(\Lambda).
  \]

Under these 3 conditions the RG flow equation for \( L_k \) have a unique solution. The choice of \( L_i \) and \( L_b \) relies on physical grounds. At \( k = \Lambda \) the cut-off function \( R \propto \infty \) should diverge \[17, 18\] such that \( U_\Lambda \equiv V_\Lambda \). Thus, clearly, \( L_i(M) = \mathcal{L}(V'_\Lambda(M)/\Lambda^2) \) must be imposed as an initial condition even if \( \Lambda \) is not large enough so that \( R_\Lambda \) is not actually infinite in the mathematical sense.

We propose to choose as boundary conditions the one-loop approximation for \( L_k(\pm M_{\text{max}}) \). Most authors usually adopt free boundary conditions. At a large \( M_{\text{max}} \) fluctuations are frozen and the one-loop approximation should be
FIG. 8: Same as in fig. [5] except that $d = 2.5$ and $r = -0.157.$

pertinent. It is easy to see that at the one-loop level one has, up to an additional constant, independent of the field

\begin{equation}
U_{1\text{-loop}}(M) = \frac{\Gamma_{1\text{-loop}}(M)}{\Omega} = V_k(M) + \frac{1}{2} \int_q \ln \left[ q^2 + V''_k(M) + \tilde{R}_k(q^2) \right], \tag{52}
\end{equation}

from which it follows that :

\begin{equation}
\partial_k U_{1\text{-loop}}(M) = \frac{1}{2} \int_q \frac{\partial_k \tilde{R}_k(q^2)}{q^2 + V''_k(M) + \tilde{R}_k(q^2)} = 2v_d k^{d-1} \mathcal{L}(V''_k(M)/k^2). \tag{53}
\end{equation}

Therefore the one-loop approximation for $L_k(M)$ reads as

\begin{equation}
L_{1\text{-loop}}(M) \equiv \mathcal{L}(V''_k(M)/k^2). \tag{54}
\end{equation}

To summarize we impose

- (i) initial condition : $L_i(M) = \mathcal{L}(V''_\Lambda(M)/\Lambda^2)$ for all $-M_{\text{max}} \leq M \leq M_{\text{max}}.$

- (ii) boundary conditions $L_k(k) = \mathcal{L}(V''_k(\pm M_{\text{max}})/k^2)$ for all $0 \leq k \leq \Lambda.$

and we stress that the compatibility condition \[51\] is obviously satisfied hence the RG flow equation can be solved safely at least from a mathematical point of view.
B. Numerical experiments

The RG flow equation (21), completed with the initial and boundary conditions of Section II A, is a standard well-conditioned quasi-linear parabolic EDP which can easily be solved numerically. We adopted the fully implicit predictor-corrector integration scheme of Douglas and Jones [32] which proved to be very efficient and precise. Douglas and Jones have proved that their procedure leads to an unconditional convergence to the solution and that the truncation error is of order $O(\delta t^2 + \delta M^2)$ where $\delta t$ is the discrete time-step and $\delta M$ the grid-step for the field.

We limited ourselves to the potential $V_{\Lambda}(\varphi) = \frac{1}{2} r \varphi^2 + \frac{1}{4!} g \varphi^4$ with $\Lambda = 10$ (arbitrary units) and $g = 1.2$ being kept fixed while varying $r$ in order to make some contact with previous numerical studies [20]. This is a well acceptable choice of initial condition provided one does not want to describe nonuniversal characteristics of, e.g., the Ising model. The model was studied with the sharp, Litim and smooth cut-off regulators introduced in Section II B. Some studies with the simplified smooth cut-off described by Eq. (29) with $\nu = 1/2$ were also performed to compute $\chi(M)$ in the vicinity of $\pm M_0$. Since no numerical simulations are available for this continuous version of the $\varphi^4$ model we tried to extract from our data similarities as well as differences between the various versions of the LPA.

Typically we retained $M_{\text{max}} = 8$, after checking that the results were not influenced by the boundaries conditions. The time-step was typically $\delta t = 2 \times 10^{-4}$ and the field-step ranging from $\delta M = 2 \times 10^{-3}$ to $\delta M = 2 \times 10^{-6}$ according to the problem at hand. In all cases the integration of the EDP was stopped at some $k_{\text{min}}$ between $\sim 10^{-6}$ and $\sim 10^{-10}$ after checking that the solution did not evolve any more. Typically about $N_t \sim 10^5$ time steps were necessary to reach convergence. For the smooth cut-off it was moreover necessary to fit the function $\omega(M)$ defined as the inverse of function $L$ (cf Eq. (10)), its derivatives and inverse yielding unavoidable systematic errors and a reduction of the precision on the data.

1. Thermodynamic potentials below $r_c$

We display in Fig. 1 the evolution of threshold function $L_k(M)$ when the scale-$k$ of the RG flow decreases from $\Lambda = 10$ to $k_{\text{min}} = 10^{-4}$. The curves have been obtained with Litim’s regulator; other approximations give similar curves, except the Sharp cut-off since $L_k$ can become negative in this case. The universal behavior (26) of the LPA is exemplified in Fig. 2 in the appropriate reduced variables.

The behavior of the potential $U_k(M)$ which can be extracted from $L_k(M)$ is displayed in Fig. 3. Note that the second
derivative the true Gibbs potential $U_k''(M)$ of the k-system remains positive as we shown in sec II D (cf. Eq. (28)). For the considered state and at the lowest $k = k_{\text{min}} = 10^{-4}$ where we stopped the integration of the RG flow one finds $M_0 = 0.9356$ and the inverse susceptibility $U_{k_{\text{min}}}''(M)$ jumps from $3.142$ at $M = M_0 + \delta M$ to $0.4512 10^{-10}$ at $M = M_0 - \delta M$. Lowering the value of $k_{\text{min}}$ does not change the value of the spontaneous magnetization $M_0$ (for a given grid step) while $U_{k_{\text{min}}}''(M)$ may be given any arbitrary small value for $|M| < M_0$.

The approach to convexity is also well illustrated by the anti-clockwise rotation of the plateau of $U_k''(M)$, i.e. the precursor of the magnetic field, towards an horizontal segment as $k \to 0$ in agreement with Eq. (27). Finally one notes that all the $U_k(M)$ behaves as parabola inside the coexistence curve, according to Eq. (26), as soon as $k$ is sufficiently small.

2. Continuity/discontinuity of the susceptibility

Here we check numerically the conclusions of Sec II D concerning the continuity or discontinuity of the susceptibility at $M = M_0$ in the various versions of the LPA. Fig 4 displays the inverse susceptibility $U_{k=0}''(M)$ in the vicinity of $M_0$ for the sharp, Litim’s, and exponential smooth cut-off in $d = 3$ dimensions. A relatively small field-step $\delta M = 2.10^{-6}$ is required to be convinced of the (dis)continuity of the curves. Although such numerical checks cannot be retained as mathematical proofs stricto sensu, the theoretical predictions, i.e. continuity of $U_{k=0}''(M)$ at $M = M_0$ for the sharp cut-off and discontinuity for the Litim and smooth exponential regulator are quite well supported by the numerical outcomes.

Figs 5, 6, 7 and 8 display the curves $U_k''(M)$ obtained numerically in the case of the simplified smooth cut-off threshold function, i.e. $\tilde{Z}(\omega) = K_0 (\omega - \omega_0)^{-1/2}$ for dimensions of space $d = 3.25$, $d = 3$, $d = 2.75$, and $d = 2.5$ respectively. Recall that the behavior of any theory involving a smooth regulator is expected to be of that type. In all cases $\Lambda = 10$, $g = 1.2$ and $M_{\text{max}} = 8$, while the parameter $r$ of the $\varphi^4$ potential has been adjusted for a spontaneous magnetization $M_0 \sim 0.05$. For each dimension $d$ we considered several values of field-step $\delta M$ ranging from $2.10^{-3}$ to $2.10^{-6}$ corresponding resp. to a sampling of $N_M = 4.10^3$ to $N_M = 4.10^6$ points in the interval $(0, M_0)$ in order to emphasize the numerical difficulty to check this (dis)continuity. As expected (see Sec II D) a spectacular change of behavior at $d = 3$. From continuous at low dimensions (cf the analysis of Sec II D) $U_{k=0}''(M)$
TABLE II: Influence of the field-step $\delta M$ on the critical parameter $r_c$ in all the variations of the LPA considered in this work: Sharp, Litim and exponential smooth cut-off. $r_c$ was determined by dicothomy as discussed in Sec III B 3. Reported data concern the $\varphi^4$ potential defined at $\Lambda = 10$, $g = 1.2$ and $r = r_c$. The RG flow equations have been interrupted at $k_{\text{min}} = 10^{-10}$. In all cases the time-step is $\delta t = 2 \times 10^{-4}$. We report 10 stable digits, numerical uncertainties only affect the 11th.

| $\delta M$ | $r_c$ (Litim) | $r_c$ (Sharp) | $r_c$ (Smooth) |
|------------|---------------|---------------|---------------|
| $2 \times 10^{-3}$ | -0.1969317598 | -0.2971859571 | -0.4120948764 |
| $2 \times 10^{-4}$ | -0.1969322088 | -0.2971863642 | -0.4120953249 |
| $2 \times 10^{-5}$ | -0.1969322133 | -0.2971863684 | -0.4120953292 |

becomes discontinuous for $d \geq 3$. Generally at most a single point seems to survive half the way the two discontinuity points whatever the tiny the value of $\delta M$ considered. In particular note that, exactly at $d = 3$, $U''_k(M)$ “looks” indisputably discontinuous at $M = \pm M_0$ as anticipated by the analysis of sect II D 2.

3. Determination of the critical point and the critical exponents

It follows from Eq. (27) that the quantity $y_k = U''_k(M = 0)/(k^2|\omega_0|)$ is well suited to discriminate states at a temperature above $r_c$ from those at a temperature below $r_c$. Indeed, as $k \to 0$, $y_k$ diverges to $+\infty$ at $r > r_c$, (since the inverse compressibility $U''_k(M = 0)$ is finite for $r > r_c$), while it tends to $-1$ for subcritical states, (cf Eq. (27)). A dicothomy procedure then yields the precise determination of the critical temperature as exemplifies by Fig 9 which displays results only for the ultra-sharp cut-off since in the other variations of the LPA (Litim’s or smooth cut-off) the bunch of curves is roughly similar and brings no new information. The results for $r_c$ are reported in table II. For a given approximation they depend slightly on the field-step $\delta M$ but as soon as $\delta M$ is as small as $2 \times 10^{-4}$ we noted no effect on $r_c$, up to its 12th digit, by decreasing its magnitude. Note that we can ascertain $\sim 8$ exact digits on the value of $r_c$ from the data obtained with $\delta M < 2 \times 10^{-4}$. Quite noticeable is the dispersion of the values of $r_c$ corresponding to different cut-off functions which casts some doubts to the validity of the LPA to predict quantitative non universal results. This is an important detail that the non-universal parameters appear to depend strongly on the initial value considered at $k = \Lambda$. If one changes something (a cutoff function for example), then the nonuniversal characteristics of the system change. Moreover the MF approximation injected as an initial condition for the flow is a too crude approximation. From this respect our results are only but superficially at odds with those obtained recently by Dupuis and Machado for the Ising and lattice $\varphi^4$ models where an excellent agreement (within a few percents) between the LPA prediction for $r_c$ and the MC data was found [29]. However in their work all these authors adopt a slightly modified version of the NPRG-LPA in which the effective action at $k = \Lambda$ is not taken as the mean field result but as the exact one (at this scale) and where integrations over the continuous momenta $q$ is replaced by a summation over the vectors $q$ of the first Brillouin zone. Similarly in the domain of the theory of liquids, the works reported by Reatto et al. attest good agreement between the LPA and the MC data [13,15]; in this case the exact physics of a reference system (the hard spheres fluid) is injected in the theory.

However when either the spontaneous magnetization $M_0(r)$ (for $r < r_c$) or the inverse susceptibility $U''(M = 0)$ (for $r > r_c$) are reported on a graph as functions of $r - r_c$ rather than versus $r$ all the curves obtained by means of different regulators collapse on a single, approximatively universal one, at least at large scale. This striking observation is exemplified in Fig. 10. In first approximation the effect of the cut-off seems to be a simple shift on $r_c$. If we abandon the Sirius point of view and zoom in the vicinity of $r \sim r_c$ the various routes yield in fact different behaviors since the critical exponents differ slightly. A series of numerical experiments which are resumed in Fig. 11 allows a rough determination of the critical exponents of the magnetization $-\beta$ and the susceptibility $-\gamma$. As apparent in Table III the values obtained for these two exponents in the case of the Litim and Smooth cut-off regulators are in good agreement but they differ quite significantly from those obtained for the sharp cut-off. By passing we note that
FIG. 11: Bottom: logarithm of the magnetization versus $\log_{10}(|r - r_c|)$ for Litim (circles), sharp (squares), exponential smooth cut-off (diamonds) regulators. The lines are linear regressions of the data. Top: logarithm of the inverse susceptibility $\chi^{-1} = U''_{k=0}(M = 0)$ versus $\log_{10}(|r - r_c|)$, same symbols. In both cases $\varphi^4$ model $\text{IN} d = 3$ with $\Lambda = 10$, $g = 1.2$, and $M_{\text{Max}} = 8$.

Rushbrook’s equality yields a negative $\alpha$ (exponent of the specific heat) in the case of the sharp cut-off, a well-known flaw of this approximation. A more stringent discussion will be given in next section where the exponents will be calculated with a high precision.

IV. INTEGRATION OF THE ADIMENSIONNED RG EQUATIONS

A. Adimensionned RG flow equations

In order to study fixed point solutions and the spectrum of critical exponents of the LPA we need to work with dimensionless potentials and fields. Since $[U] = k^d$ and $[M] = k^{1+d/2}$ we define the dimensionless magnetization $\tilde{M} = k^{1-d/2} M$ and the dimensionless potential $\tilde{U}(\tilde{M}) = k^{-d} U(M)$, so that the RG flow Eq. (19) takes now the form

$$\partial_t \tilde{U} = d \tilde{U} + (1 - \frac{d}{2}) \tilde{M} \tilde{U}' - 2v_d L(\tilde{U}'') ,$$  

(55)

in which the ‘ designates a derivative with respect to $x$. Further simplification can be obtained by introducing finally reduced variables. In the general case one defines $x = \tilde{M}/\sqrt{2v_d}$ and $u = \tilde{U}/(2v_d)$. Litim case will be our exception with the choice $x = \tilde{M}/\sqrt{4v_d/d}$, $u = d\tilde{U}/(4v_d)$ and the redefinition valid henceforth $L(\omega) = 1/(1 + \omega)$. With these notations we have now in any case :

$$\partial_t u = d u + (1 - \frac{d}{2}) x u' - L(u'') .$$  

(56)
Similarly one introduces the reduced threshold potential \( l(x,t) \triangleq L_k(M) = L(u''(x,t)) \) which obeys the following PDE
\[
\omega'(l) \partial_l l = 2\omega(l) + (1 - \frac{d}{2}) x \omega'(l) l' - l'' ,
\]
(57)
where we recall that \( \omega = L^{-1} \) is the inverse of function \( \omega \rightarrow L(\omega) \). Eq. (57) was obtained by differentiating twice Eq. (56) with respect to the field variable \( x \).

B. Fixed points and exponents

Fixed point solutions \( u^*(x) \) and \( l^*(x) \) of Eqs. (59) and (57) resp. are peculiar solutions of the ordinary differential equations (ODE)
\[
0 = du^* + (1 - \frac{d}{2}) x u''^* - L(u'''^*) ,
\]
(58a)
\[
0 = 2\omega(l^*) + (1 - \frac{d}{2}) x \omega'(l^*) l''^* - l'''^* ,
\]
(58b)
respectively. Note that if \( u^* \) is a solution of Eq. (58a) then \( l^*(x) = L \circ u'''^*(x) \) is a solution of Eq. (58b); similarly from a solution \( l^* \) of (58b) one builds \( u'''^*(x) = \omega \circ l^*(x) \) to get a solution of (58a).

Because of the assumed \( \mathbb{Z}_2 \) symmetry we will consider only even solutions \( u^*(x) = u^*(-x) \) of Eq. (58a). Then, since \( l^*(x) = L \circ u'''^*(x) \), \( l^*(x) \) is also an even solution of Eq. (58b). Once an even fixed point has been found (analytically or numerically) one investigates the behavior of the solutions of Eqs. (59a) and (57) in the vicinity of this fixed point. As usual, we write \( u(x,t) = u^*(x) + h_\lambda(x) \exp(\lambda t) \) and consider \( h_\lambda(x) \) as small. Linearizing Eq. (59a) with respect to \( h_\lambda \) leads to the eigenvalue equation :
\[
0 = (d - \lambda) h_\lambda + (1 - \frac{d}{2}) x h''_\lambda - \mathcal{L}'(u''^*)h''_\lambda .
\]
(59a)
Similarly writing \( l(x,t) = l^*(x) + g_\lambda(x) \exp(\lambda t) \) and linearizing the full RG flow equation with respect to \( g \) yields
\[
0 = g_\lambda \omega'(l^*) (2 - \lambda) + (1 - \frac{d}{2}) x \left\{ \omega'(l^*) g''_\lambda + \omega''(l^*) l''^* g^*_\lambda \right\} - g''_\lambda
\]
(59b)
A first glance, since
\[
l(x,t) = L(u'') \sim L(u'''^*) + L'(u''') h''_\lambda(x) \exp(\lambda t)
\]
the two spectra are identical and the eigenfunctions related by
\[
g_\lambda(x) = \mathcal{L}' \circ u'''^*(x) h''_\lambda(x) .
\]
(60)
Strictly speaking this is true only if \( h''_\lambda(x) \) is not identically equal to 0. Thus if it turns out that \( h_\lambda(x) \) is either a constant or a linear function of \( x \) then eigenvalue \( \lambda \) does not belong to the spectrum of the RG operator acting on \( l \). As well known, odd and even eigenvectors form two mutually orthogonal linear subsets and will be both considered in the sequel.

C. Trivial solutions

Such trivial solutions exist whatever the type of fixed point; they are more easily detected on the eigenvalue problem (59a), i.e. that attached to the linearization of the RG about \( u^*(x) \). Let us rewrite Eq. (58a) for \( u^* \) as well as the equation for its derivative \( f^* = u^* \); one has
\[
0 = du^* + (1 - \frac{d}{2}) x u''^* - L(u'''^*) ,
\]
(61a)
\[
0 = (1 + \frac{d}{2}) f^* + (1 - \frac{d}{2}) x f''^* - L'(u''')
\]
(61b)
Comparing these equations to the eigenvalue problem (59a) one readily sees that
(i) The constant $h_\lambda(x) = h_0$ is a trivial even eigenfunction of (59a) with the eigenvalue $\lambda = d$

(ii) $h_\lambda = f^*(-x)$ is also an eigenfunction of (59a) associated to the eigenvalue $\lambda = -1 + d/2$. Since $u^*(x)$ should be even then $f^*(x)$ is an odd eigenvector; according to Wegner it is associated with the shift operator [28].

(iii) $h_\lambda = x$ with $\lambda = 1 + d/2$ is another trivial odd eigenvector associated with the magnetic field.

From the remark of the previous section it follows that only the trivial odd eigenvalue $\lambda = -1 + d/2$ survives in the eigenvalue problem (59a), i.e. that attached to the linearization of the RG flow about $t^*(x)$. According to [60] the corresponding eigenvector is the odd function $g_{\lambda = -1 + d/2}(x) = L^* \circ f^*(x) \circ f^*(x)$.

D. Gaussian fixed point

We show now that, provided that $d > 2$, the LPA admits a Gaussian fixed point, with the usual spectrum of exponents, irrespective to the type of cut-off. The fixed-point equation for $u^*$, i.e. Eq. (58b), admits $u^*''(x) = 0$ as a special solution. By integration it gives $u^*''(x) = 0$ ($\mathbb{Z}_2$ symmetry) and $u^*(x) = u_C$ with $d u_C = L(0)$; where $L(0) = 0, 1$ for the sharp and Litim’s cut-off respectively and, numerically, $L(0) = 5.9973827$ for our smooth cut-off. Obviously $t^*(x) = l_C$ is the related special solution of Eq. (58b) provided $l_C = d u_C$.

The linearized eigenvalue problem for $u(x,t)$ reads

$$(d - \lambda) h(x) + (1 - \frac{d}{2}) x h'(x) - L'(0) h''(x) = 0,$$  \hspace{1cm} (62)

where $L'(0) < 0$ (cf $L'(0) = -1$ for Sharp and Litim’s cut-off, while, numerically $L'(0) = -1.37960752$ for the smooth-cut-off). The change of variables

$$h(x) = H(y), \hspace{1cm} y = \beta x$$

$$\beta = \sqrt{\frac{4}{(2 - d) L'(0)}}, \hspace{1cm} 2n = \frac{4(d - \lambda)}{d - 2}$$  \hspace{1cm} (63a)

allows to rewrite Eq. (62) as Hermite equation:

$$H''(y) - 2y H'(y) + 2n H(y) = 0,$$  \hspace{1cm} (64)

If we request the potential to be bounded by polynomials, $n$ must be restricted to an integer. Then Eq. (64) becomes the equation defining Hermite Polynomials $H_n(y)$. The parity of $H_n(y)$ being that of $n$, the spectrum of even eigenvalues is given by

$$\lambda_p = d - p(d - 2),$$  \hspace{1cm} (65)

with $n = 2p$ and $p = 0, 1, 2, \ldots$. The trivial relevant operator $H_0$ with $\lambda_0 = d$ is indeed present in the spectrum as discussed in sec IV C. Whatever the type of cut-off we recover the well-known result: in $d = 4$ we find one relevant operator ($H_2$ with $\lambda_1 = 2$), a marginal operator ($H_4$ with $\lambda_2 = 0$) and the first irrelevant operator with $\lambda_2 = -2$ ($H_6$) while in $d = 3$ there are two relevant operators ($H_2$ and $H_4$ with $\lambda_1 = 2$ and $\lambda_2 = 1$, respectively) and a marginal operator ($H_6$ with $\lambda_3 = 0$), while the first irrelevant operator is $H_8$ with $\lambda_4 = -1$. Some remarks are in order.

- An analysis similar to that of ref. [3] reveals that the marginal operators become irrelevant at the quadratic order.

- The trivial eigenvalue $\lambda_{p=0} = d$ disappears from the spectrum of Eq. (59b). The eigenvectors of Eq. (59b) are given by $g_{\lambda_0}(x) = (4/(2 - d)) H''_{2p}(y)$ as follows from Eq. (60).

- The odd spectrum is given by $\lambda_p = d - (p+1/2)(d-2)$, $p$ an integer. It includes the trivial solution $\lambda_0 = 1 + d/2$. The other trivial odd eigenvalue $\lambda = -1 + d/2$ is absent accidently from the spectrum, since it should correspond to a zero eigenvector ($h_\lambda = f^*_C \equiv 0$).
E. Non Gaussian fixed point

In this section we focus on the non Gaussian fixed point in $d > 2$. Recently, the LPA fixed point equation for $u^*(x)$ have been solved with a very high numerical precision for the sharp and Litim’s cut-off \cite{22, 23}. Here we report numerical solutions for $l^*(x)$ only in dimension $d = 3$; the three cut-offs considered in this paper were examined and compared. Eq (58b) can be solved by the shooting method with boundary conditions imposed either at the origin $x = 0$ or at $x = \infty$ \cite{22, 23}, hence the names given to the two methods considered below.

1. ab origine

|       | Litim       | Sharp       | Smooth     |
|-------|-------------|-------------|------------|
| $l^*(0)$ | 0.122859820243702 | 0.61903040294652 | 7.355923051 |
| $u^*''(0)$ | -0.186064249470314 | -0.46153372011621 | -0.7995141985 |
| $x_c$   | 20.644305503116 | 94.128646935418 | 22.95208767 |

The LPA fixed point equation (58b) is a second order ODE for the function $l^*(x)$. Here we solve it numerically in $d = 3$ by providing two initial conditions at $x = 0$. The first one, $l^*(x) = 0$ ensures the parity $l^*(-x) = l^*(x)$ required by $Z_2$ symmetry. It is now well-known that an arbitrary value of $l^*(0)$ yields a solution singular at some finite value $x_c$ of the field. At $x_c$ we have $l^*(x_c) = 0$ for the Smooth or Litim’s cut-off and $l^*(x_c) = -\infty$ for the sharp cut-off. These singular values for $l^*(x_c)$ correspond to $u^*''(x_c) = +\infty$. Actually, the general solution of (58b) involves a moving singularity of the form

\[
l(x) \sim K_1 \sqrt{d-2} (x_c - x)^{1/2} x_c^{1/2}
\]

where, in the case of Litim’s cut-off $K_1 = 1$ (the behavior near the singularity $x_c$ is driven by the asymptotics at infinity of the function $L(u^-)$, cf Eq. (16)). Figure 12 displays the variation of the singular point $x_c$ in the case of the Smooth cut-off (similar curves are obtained for the Sharp and Litim’s cut-off). Two peaks where $x_c$ diverges to $\infty$ can be noticed. The one on the left corresponds the Gaussian fixed point where $l(x)$ is a constant with $l(0) = l_G = L(0) = 5.9973827$ (see section IV.D). The one one the right corresponds to the Wilson-Fisher fixed point with $l(0) = 7.355923051$ that we are looking at.

Our requirement is that the physical solution must be non singular on the entire range $x \in (0, \infty)$ so we must push $x_c$ to infinity by adjusting the value of $l(0)$ by a dichotomy process in the vicinity of the right peak of figure 12 \cite{33}. Of course high precision ODE solvers are required for this kind of study.
FIG. 13: Fixed point solution $l^*(x)$ for the smooth cut-off. Red line : shooting *ab origine*, black line : shooting *ad originem*.

We solved equation (58b) as well as all the ODE of this paper with the DOPRI853 algorithm of Hairer et al. [31] which is an explicit Runge-Kutta integrator of order “8” and order “5” embedded, with adaptive step-size. We imposed relative and absolute errors of $10^{-18}$ and $10^{-25}$ respectively; the code was written in FORTRAN90 in quadruple precision. Even with this high technology it is impossible to obtain very large values of $x_c$ by tuning $l(0)$. Our results are summarized in Table IV. Our results for $u^*(0)$ deduced of our result for $l^*(0)$ agree within 14 figures with those of ref.[22, 23] in the case of Litim’s and sharp cut-off regulators. The data reported in Table IV for the smooth cut-off are much less precise due to the use of fits for computing function $L(\omega)$. The complicated behavior of function $l^*(x)$ is exemplified in fig. (13) (red curve); We displayed only the result for the smooth cut-off, Litim’s case is similar while for the sharp cut-off $l^*(x)$ tends to $-\infty$ at $x_c$ instead of “0”.

This *ab origine* method is rather deceptive but however useful to check the data obtained by the *ad originem* shooting method that we discuss now.

2. *ad originem*

The existence of a moving singularity at $x_c$ which seems impossible to “push” at infinity suggests to solve Eq. (58b) with initial conditions at infinity, at least $x_{\text{max}}$ large, towards $x = 0$. The analysis of the asymptotic solutions of (58b) for $x \to \infty$ shows the existence of power law solutions. This second family of solutions with regular scaling properties must obviously be preferred to the singular solutions discussed in section (IV.E.1). One can show that, asymptotically, for $x \to \infty$ one has, for the smooth cut-off regulator

$$l^*(x) = b_l x^{-\beta_l} + \frac{C_2}{C_1} b_l^2 x^{-2\beta_l} + \left( \frac{C_3}{C_1} + \frac{C_2^2}{C_1^2} \right) b_l^3 x^{-3\beta_l} + O(x^{-4\beta_l}) ,$$

(67a)

with $\beta_l = 4/(d-2)$ and $b_l$ an arbitrary coefficient. Recall that $C_1, C_2, C_3$ enters the asymptotic behavior (17) of $\omega(l^*)$ as $l^* \to 0$ and are given in table II. Litim’s case can be obtained from (67a) by the substitution $C_1 = 1$, $C_2 = -1$ and $C_3 = 0$. In the case of the sharp cut-off one has

$$l^*(x) = -\ln b_l - \beta_l \ln x - \frac{1}{b_l} x^{-\beta_l} - \frac{4}{b_l d (d-2)} x^{-\beta_l-2} + O(x^{-\beta_l-4}) .$$

(67b)
In all cases the asymptotics depend on a single parameter $b_l$ which fixes the two initial conditions $l^*(x)$ and $l^*'(x)$ at $x = x_{\text{max}}$. $b_l$ is determined in such a way that $l^*'(0) = 0$. This is the shooting method \textit{ad \textit{originem}}.

![Histogram $p(x)$ of the order parameter of the (d=3) Ising model at the critical point. Black: MC data \cite{34}, red: LPA (Litim), green: LPA (Sharp), blue: LPA (Smooth)](image)

The code DOPRI853 detects a stiff problem at large $x$ so it is impossible to choose a very large value of $x_{\text{max}}$. Actually we retained $x_{\text{max}} = 15, 22$ and 20 for Litim’s, the sharp and smooth cut-off regulators respectively. However taking into account the full asymptotic expansions \cite{(67a), (67b)} one recovers exactly, \textit{i.e.} with all the significant figures reported in table \textbf{V}, the values of $l^*(0)$ obtained by the shooting \textit{ab origine}. The values of coefficient $b_l^*$ at the fixed point obtained by a dichotomy are given in table \textbf{V}.

Figure 13 displays our results for $l^*(x)$ (smooth cut-off case) obtained by the two shooting methods. At small $x$ both curves coincide quasi exactly up to some $x$; at $x$ two branches of the solution separate one that comes from the origin, the other, with scaling properties at infinity which comes from infinity. This hysteresis phenomenon cannot be discarded numerically.

From $l^*$ one deduce $u^{*''} = \omega(l^*)$ and thus the fixed point $u^*$ by integration (up to an additional constant). In private and informal discussions the opinion circulates that the histogram of the order parameter $p(x)$ of the 3d Ising model at its critical point should coincide with $\exp(-u^*(x))$ (up to normalization constants). We are not aware of any rigorous proof of this assertion but tentatively took it seriously. This histogram has been obtained by Monte Carlo simulations \cite{34} and is compared in figure 14 with the theoretical predictions of the LPA within the three versions considered in this paper. Note that all the histograms has been normalized in such way that the two first even moments are equal to unity, \textit{i.e.} $\int dx p(x) = 1$ and $\int dx p(x) x^2 = 1$. To inject some quantitative elements in the discussion of these curves we note that the kurtosis $K = \int dx p(x) x^4$ is $K = 1.60399$ experimentally, while in the LPA one finds $K = 1.86162, 1.70294$ and 1.51128 for Litim’s, the sharp and smooth regulators respectively.

The behavior of $p(x)$ at large deviations $x$ can also be obtained in the framework of the LPA by computing the asymptotics of the fixed point solution $u^*(x)$. Assuming a power law behavior as $x \to +\infty$, Eq. \textbf{58a} is used to obtain

$$u^*(x) = b_u^* x^{\beta_u} + \frac{K_1}{b_u^*} \frac{(d-2)^2}{2d(d+2)^2} x^{-(\beta_u-2)} + \frac{K_2}{b_u^*} \frac{(d-2)^4}{(2d)^2(d+2)^4(d+4)} x^{-2(\beta_u-2)} + \ldots , \quad \text{(68a)}$$

with $\beta_u = \beta_l + 2 = 2d/(d-2)$ and $b_u^*$ a coefficient which enters at each order in the asymptotics $u^*(x)$ (it’s value is such that $u^{*''}(0) = 0$). Of course $b_u^*$ is related to the coefficient $b_l^*$ which governs the asymptotics of $l^*(x)$, one finds

\begin{table}[h]
\centering
\begin{tabular}{|c|c|c|c|}
\hline
 & Litim & Sharp & Smooth \\
\hline
$b_l^*$ & 33.3250777220334 & 0.91029082436564 & 392.879344670467 \\
\hline
\end{tabular}
\caption{Results for the coefficient $b_l^*$.}
\end{table}
that \( b_t = K_1 (d - 2)^2 / (b_t^* 2d (d + 2)) \). Recall finally that \( K_1, K_2 \) enters the asymptotic behavior \((16)\) of \( l = L(\omega) \) as \( \omega \to +\infty \) and are given in table \[\](\[I\])

Litim’s case can be obtained from \((68a)\) by the substitution \( K_1 = 1 \) and \( K_2 = -1 \) while, in the case of the sharp cut-off, one has

\[
\begin{align*}
\tilde{u}^*(x) &= b^*_u x^{\beta_u} - \frac{4}{d(d - 2)} \ln x + \\
&\quad (2 + \ln(b^*_u \beta_u (\beta_u - 1))) / d, 
\end{align*}
\]

(68b)

where, once again \( \beta_u = 2d / (d - 2) \) but \( b^*_u = b^*_u 2d(d + 2) / (d - 2)^2 \).

3. critical exponents

We turn now to the eigenvalue equation \((59b)\). Again this is a second order ODE the solution of which is characterized \textit{a priori} by two integration constants. Actually one of these is irrelevant and corresponds to the arbitrariness of the normalization of an eigenfunction. Since the fixed point solution \( l^*(x) \) is an even function of \( x \) equation \((59b)\) is invariant under a parity change and the spectrum separates into even and odd eigenvalues. The second integration constant is thus fixed by the choice \( g(0) = 0 \) (even) or \( g(0) = 0 \) (odd). The shooting ad originem method seems mandatory and one proceeds as in section IV E 2.

For the smooth cut-off regulator the asymptotic behavior of the eigenfunctions as \( x \to +\infty \) is found to be

\[
\begin{align*}
g(x) &\sim S \left( x^{\alpha_1} + 2 \frac{C_2}{C_1} b^*_u x^{\alpha_1 - \beta_1} + \\
&\quad 3 b^*_u 2 \left( \frac{C_2}{C_1} + \frac{C_3}{C_1} \right) x^{\alpha_1 - 2\beta_1} + \ldots \right), 
\end{align*}
\]

(69a)

where \( S \) is an arbitrary constant and \( \alpha_1 = (\lambda + 2) / (1 - d/2) \). Imposing this form for \( g(x) \) at some large \( x_{\text{max}} \) one tunes \( \lambda \) to obtain either \( g(0) = 0 \) (even) or \( g(0) = 0 \) (odd). The case of the sharp cut-off is special:

\[
\begin{align*}
g(x) &\sim S \left( x^{\alpha_1} - \frac{x^{\alpha_1 - \beta_1}}{b_1^*} + \ldots \right), 
\end{align*}
\]

(69b)

where \( \alpha_1 = \lambda / (1 - d/2) \).

Our results for the even and odd spectra are reported in table \[\](\[VI\]). In the even case there are no trivial eigenvalues, as shown in Sec. \[\](\[IV C\]) and the first eigenvalue \( \lambda_1 \) is related to the critical exponent \( \nu = 1 / \lambda_1 \) of the correlation length of the Ising model. The first negative eigenvalue \( \lambda_2 \) is minus the Ising-like first correction-to-scaling exponent

| \( \lambda \)  | Litim | Sharp  | Smooth  |
|----------|-------|--------|---------|
| \( \lambda_1 \) | 1.539499459806177 | 1.45041251707412 | 1.53706 |
| \( \nu \)  | 0.64956177380648 | 0.6894590561235 | 0.650594 |
| \( \omega_1 \) | 0.655749399193339 | 0.595239852232561 | 0.654104 |
| \( \omega_2 \) | 3.180065120591689 | 2.838426658241768 | 3.17183 |
| \( \omega_3 \) | 5.912306127701584 | 5.18419205359884 | 5.55112 |
| \( \omega_4 \) | 8.796092825413934 | 7.56792580450411 | 8.76972 |
| \( \omega_5 \) | 11.79807658336587 | 10.057968960649436 | 11.7609 |
| \( \omega_6 \) | 14.896053175688298 | 12.56722422589013 | 14.8473 |

| \( \tilde{\lambda} \)  | Litim | Sharp  | Smooth  |
|----------|-------|--------|---------|
| \( \tilde{\lambda}_1 \) | 0.4999999999999999 | 0.4999999999999999 | 0.500004 |
| \( \tilde{\omega}_1 \) | 1.8867038380914204 | 1.691338925641807 | 1.88197 |
| \( \tilde{\omega}_2 \) | 4.5243907336707728 | 3.998514715824934 | 4.51219 |
| \( \tilde{\omega}_3 \) | 7.337650643543136 | 6.38253789820088 | 7.31630 |
| \( \tilde{\omega}_4 \) | 10.283907240259583 | 8.821709390384049 | 10.2522 |
| \( \tilde{\omega}_5 \) | 13.336199643459432 | 11.30299660411253 | 13.2933 |
\(\omega_1 = -\lambda_2\) and so on. In the odd case, as discussed in Sec. [LV C] there are in general two positive trivial eigenvalues \(\lambda_1\) and \(\lambda_2\), among which only the second one \(\lambda_2 = d/2 - 2 = 0.5\) survives in the spectrum. The first non-trivial eigenvalue is negative and defines the subcritical exponent \(\theta_\lambda = \tilde{\omega}_1 = -\lambda_3\) and so on.

The numerical data for \(\lambda_2 = 0.5\) serves as a stringent test for the precision of the numerical procedure; while (at least) 15 significant digits are obtained for the sharp and Litim’s cut-off no more than 6 digits can be ascertain in the case of the smooth cut-off. It originates in the various fitting procedures devised to evaluate the function \(\omega(l)\) and its derivatives. In the case of Litim’s and the sharp cut-off our results are in perfect agreement with those of ref. [22, 23]. Overall good agreement between the Litim and smooth cut-off spectra should be stressed.

Since \(\eta = 0\) in the LPA, one can compute all critical exponents from the critical exponent of the correlation length \(\nu\) by the scaling relations. One has for \(d = 3\) : \(\alpha = 2 - 3\nu\), \(\beta = \nu/2\), and \(\gamma = 2\nu\). The values are reported in table VII. The comparison with the data of Table III obtained by solving the dimensioned PDE flow equation, is deceptive since there is no good agreement even by taking into account the error bars. The values obtained for \(\beta\) (\(\gamma\)) by the numerical experiments of section III are systematically larger (smaller) than that obtained in this section. The explanation of this discrepancy relies probably in systematic errors due to the size of the field and time steps in the numerical resolution of the PDE.

| \(\beta\)       | \(\gamma\)       | \(\alpha\)       |
|----------------|----------------|----------------|
| 0.324780886940324 | 0.34472952808106675 | 0.325297      |
| 1.299123547761296  | 1.37991811232427  | 1.301188      |
| 0.051314678358056   | 0.068377168486405  | 0.048218      |

V. CONCLUSION

In this paper we attempted to make an exhaustive study of the properties of the \(\varphi^4\) model in the ordered phase in the framework of the NPRG within the LPA approximation.

We shown that the approach to the convexity is independent of the cut-off, but that fine details are strongly affected by the choice of the regulator, notably the analytical behavior of the inverse magnetic susceptibility \(\chi^{-1}(M)\) at \(M = \pm M_0\). We proved that the singularity of the threshold function \(\mathcal{L}(\omega)\) about its largest pole (or essential singularity) \(\omega_0\) governs the behavior of \(\chi^{-1}(M)\) at \(M = \pm M_0\); if \(\mathcal{L}(\omega) \sim (\omega - \omega_0)^{-\nu}\) as \(\omega \to \omega_0^+\) then the inverse compressibility is discontinuous at \(M = \pm M_0\) (as required on physical grounds) only if the inequality \(4 - d - 2\nu \leq 0\) holds. In particular Litim’s and any smooth cut-off yield a discontinuity of \(\chi^{-1}(M)\) in dimension \(d = 3\), while the sharp cut-off incorrectly predicts a continuous behavior and thus a merging of the spinodal and binodal curves.

We have confirmed these subtle properties of the solution below \(r_c\) by extensive numerical experiments with the help of a new algorithm which solves the RG flow equations for the threshold functions rather than for the potential or one of its derivatives. The main advantage of the method is to replace the numerical resolution of a highly non linear PDE which exhibits numerical instabilities in the ordered phase by that of a quasi-linear parabolic PDE with good convergence properties.

The "standard" version of the LPA retained in this work does not allow to compute the critical parameter \(r_c\) of the model which depends strongly upon the choice of cut-off. The main reason is that the choice of the MF approximation as an initial condition for the RG flow is too crude approximation. Modified versions of the NPRG [13, 19, 20] remedy to this flaw and yield a quite precise estimate for \(r_c\). However we noticed that, choosing as a new variable \(r - r_c\), instead of \(r\), the thermodynamics of the LPA (spontaneous magnetization, magnetic susceptibility) for the \(\varphi^4\) potential is remarkably independent of the cut-off, except very close to the critical point. The latter merely shift \(r_c\) to incorrect values. The numerical solution of the dimensionned RG flow equation does not yield a very precise estimate of the critical exponents either, probably because of small numerical errors in the resolution of the PDE.

In order to compute precisely the critical exponents one must solve the linearized RG about the Fisher fixed point. It can also be done for the threshold functions instead of the potential or its derivatives without any noticeable numerical differences but with the advantage of getting rid of some trivial solutions corresponding to redundant operators. The solution of the resulting fixed point equations and associated eigenvalue problems can be obtained with a high numerical precision with the help of a non-stiff solver like DOPRI853 [31] for instance. Since the ad originem problem is stiff, stiff integrators could be of some help however to reduce the integration step and should be tested.
It is not clear whether the LPA scenario for the ordered phase survives for more elaborate approximation schemes, this could be the subject of further investigations.

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