An approximation solution for scheduling problem in single machine under unavailability constraints

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ABSTRACT
In this paper, an approximation solution for scheduling problem of n tasks on single machine with unavailability zones is proposed. This problem is strongly NP-complete which makes finding an optimal solution looks impossible task. In this frame, we suggested a heuristic (H1) in which availability periods of machine are filled with the highest weighted tasks. To improve the performance of this heuristic, we used, on one hand, different diversification strategies E1 and E2 with the aim of exploring unvisited regions of the solution space, and on the other hand, two neighborhoods (neighborhood by swapping and neighborhood by insertion). The computational experiment was carried out on single machine with different unavailability zones. It must be noted that tasks movement can be within one period or between different periods.

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1. Introduction

A scheduling problem consists in organizing tasks realization time with consideration of time constraints (time limits, tasks series character) and constraints related to using and availability of required resources. The scheduling constitutes a solution to the considered problem, describes the tasks execution and resources location during time and aims to satisfy one or many objectives (Zribi et al., 2005) have studied the problem 1/N – C/∑j=1n wjCj and have compared two exact methods: one is the Branch and Bound, the other is the integer programming. They have concluded that Branch and Bound method have better performance and it allowed resolving instances of more than 1000 tasks.

Chang et al. (2011) proposed a genetic algorithm (GA) enhanced by dominance properties for single machine scheduling problems to minimize the sum of the job’s setups and the cost of tardy or early jobs related to the common due date.

Zitouni and Selt (2016) have studied the problem:

\[ \frac{P_{\text{max}}}{N} - \frac{C}{\sum_{j=1}^{n} w_jC_j} \]; they carried out a comparative study of heuristic and metaheuristic for three identical parallel machines.

In this paper, the results of selt and zitouni (2014) research works are exploited to develop a different new heuristic to solve the tasks scheduling problem on single machine under different constraints.

2. Tabu search

Tabu search is metaheuristic that keeps track of the regions of the solution space that have already been searched in order to avoid repeating the search near these areas. It starts from a random initial solution and successively moves to one of the neighbors of the current solution.

The difference of tabu search from other Metaheuristic approaches is based on the notion of tabu list, which is a special short term memory. That is composed of previously visited solution s that includes prohibited moves. In fact, short term memory stores only some of the attributes of solutions instead of whole solution. So it gives no permission to revisited solutions and then avoids cycling and being stuck in local optima.

During the local search only those moves that are not tabu will be examined if the tabu move does not satisfy the predefined aspiration criteria. These aspiration criteria are used because the attributes in
the tabu list may also be shared by unvisited good quality solutions. The process of TS can be represented as follows.

**Algorithm**

Step 1: Generate initial solution x.
Step 2: Initialize the Tabu List.
Step 3: While set of candidate solutions X" is not complete.
Step 3.1: Generate candidate solution x" from current solution x
Step 3.2: Add x" to X" only if x" is not tabu or if at least one Aspiration Criterion is satisfied.
Step 4: Select the best candidate solution x* in X".
Step 5: If fitness(x*) > fitness(x) then x = x*.
Step 6: Update Tabu List and Aspiration Criteria
Step 7: If termination condition met finish, otherwise go to Step 3.

2.1. Neighborhood structure

Neighborhood determination constitutes the most important stage in metaheuristic methods elaboration. In the following part, we use two Neighborhoods, (neighborhood by swapping) and (neighborhood by insertion).

2.1.1. Neighborhood by swapping

**Definition**

Consider a sequence σ composed of n tasks. A neighborhood σ' is obtained by permuting two tasks, j and j' of respectively k and k' positions σ with k' = k + 1, k + 2, ..., n. The set,

\[ N_1(\sigma) = \{\sigma, \sigma \text{ is obtained by permutation of two tasks}\} \]

is called neighborhood of σ. This set is consequently obtained by permutation of all tasks of σ two by two.

**Formal statement 1**

Consider a sequence σ, the set's cardinal of \( N_1(\sigma) \) is \( \frac{n(n-1)}{2} \).

Proof: The permutation of all tasks; two by two consists in permuting each task of the sequence with all remained tasks; without identical ones. The number of possible permutations in a sequence σ composed of n tasks is:

\[ (n - 1) + (n - 2) + \ldots + 2 + 1 = \frac{n(n-1)}{2} \]

2.1.2. Neighborhood by insertion

**Definition**

Consider a sequence σ composed of n tasks; a neighborhood σ' is obtained by inserting one task j of a position k in a new position k' in the sequence σ. The set \( N_2(\sigma) = \{\sigma', \sigma' \text{ is obtained by inserting a task of position } k \text{ in } k'\} \) is a neighborhood of σ. This set is consequently obtained by realizing all possible insertions of all tasks of σ.

**Formal statement 2**

Consider a sequence σ, the set's cardinal of \( N_2(\sigma) \) is \( (n - 1)^2 \).

Proof: Inserting a task j of position k in another position k' in the sequence σ allows getting n-1 possible insertions. Hence, for n tasks, there is n(n-1) insertions to be done. To avoid getting identical sequences, adjacent tasks insertions are counted once. Consequently n-1 insertions will be deleted. Finally, the number of obtained insertions is:

\[ n(n - 1) - (n - 1) = (n - 1)^2 \]

**Formal statement 3**

It must be noted that tasks movement can be within one period or between different periods.

2.2. Tabu list structure

The tabu method is based on the principle that consists in maintaining in memory the last visited solutions and in forbidding the return to them for a certain number of iterations. The aim is to provide sufficient time to the algorithm so it can leave the local optimum. In other words, the tabu method conserves in each stage a list L of solutions (Tabu's) which it is forbidden to pass-by temporarily. The necessary space for saving a set of solutions tabus in the memory is indispensable.

The list, that we propose, contains the found solutions sequences. After many tests, a dynamic size list, which varies according to the search amelioration state, is conceived. The initial size of this list is considered to be \( \frac{3\sqrt{n}}{2} \) where n is the tasks number. After that, during the search, when 5 successive iterations pass without amelioration of solution, the list is reduced to a number inferior or equal to \( \sqrt{n} \). On the other hand, when 5 successive iterations pass and the solution is ameliorated, the list is increased to a number superior or equal to \( 2\sqrt{n} \). The Tabu list is consequently dynamic and its size varies within the interval \( [\sqrt{n}, 2\sqrt{n}] \). The decrease or the increase of list size must always be done at the end of the list.

2.3. Heuristic

An initial solution is always necessary. For this reason, we suggest in this part the following heuristic: assigne the (best) task h where \( \frac{p_h}{w_h} = \min_{j \in J} \left( \frac{p_j}{w_j} \right) \) to the best machine based on two principles justified by the two following propositions:

**Formal statement 4**

In an optimal scheduling, it is necessary to schedule the tasks; in each availability period of the machine according to the order SWPT.
Proof: It results directly by adjacent task exchange like used by Smith (1956) for the corresponding periods.

**Formal statement 5**

It is not useful to let the machine (idle) if a task can be assigned to this machine.

Notations:
We denote by:
- \( J = \{1, 2, \ldots, n\} \): The set of tasks.
- \( P_h \): Execution time of the task \( h \).
- \( k \): Single machine
- \( n \): Number of availability zones.
- \( Z = \{1, 2, \ldots, k\} \): Availability zones.
- \( E_z \): Period of unavailability zones.
- \( \sigma \): Sequence assigned to machine \( I \)
- \( W_h \): Weight of the task \( h \)
- \( C_h \): Execution time of the task \( h \) by the machine \( I \)
- \( C_z(\sigma \in Z) \): Execution time of the task \( j \in Z \), allocated to the zone \( z \).
- \( f(\sigma) \): Objective function cost.
- \( f_{\text{swapp}} \): Swapping algorithm cost.
- \( f_{\text{insert}} \): Insertion algorithm cost.

**Initialization**

\[ j = \{1, 2, \ldots, n\}; \quad E_1 = 0; \quad \sigma = \emptyset; \quad f(\emptyset) = 0; \quad P_j = \text{random}(1.99); \quad W_j = \text{random}(1.10); \quad z = 1 \]

Sort tasks \( h \in J \) in increasing order according to the criterion \( \frac{P_j}{W_j} \) in a list \( U_1 \).

Sort tasks \( h \in J \) in decreasing order according to the criterion \( \frac{P_j}{W_j} \) in a list \( U_2 \).

**Algorithm**

**Step 1:** Get an initial solution \( \sigma \) and \( T[1]=0 \);

**Step 2:** Do permutation by swapping

**Step 3:** Do permutation by insertion

**Step 4:** Compute: \( f_{\text{swapp}}; f_{\text{insert}} \)

**Step 5:** Consider \( L(\text{Tabu list size}) \)

**Step 6:** for \( k=1 \) to 3 Do

If \( f_{\text{swapp}} < f \) Do

**Step 6.1:** \( T[1] = f_{\text{swapp}} \)

else \( T[1] = f_{\text{insert}} \)

End if

**Step 6.2:** Display \( \sigma(f_{\text{swapp}}) \)

**2.4. Diversification strategies**

The final time to execute this problem is chosen as \( T \geq 700 \). It is divided according to diversification strategy to two times \( E_1 \) and \( E_2 \). After many experiments, these periods are chosen as follows:

- \( E_1 \): Initial starting time; uses long term memory to store the frequency of the moves executed through of the search.
- \( E_2 \): 1000s restarting time makes use of influential moves.

**3. Numerical example**

Consider the problem \( P_1 \) with the following data:

| \( j \) | 1 | 2 | 3 | 4 | 5 | 6 |
|---|---|---|---|---|---|---|
| \( P_j \) | 11 | 36 | 88 | 10 | 91 | 31 |
| \( W_j \) | 3 | 6 | 8 | 7 | 4 | 1 |
| \( P_j/W_j \) | 3.66667 | 6 | 11 | 1.42 | 22.75 | 31 |
| \( P_j(\text{MAX}) \) | 91 | 88 | 36 | 31 | 11 | 10 |

**Table 1:** 6 Tasks scheduling results

6 Tasks scheduling results for example:

- Results of heuristic \( (H_2) \) are: \( f = 2548 \);
- Execution time = 0.650 s;
- Results of tabu (swapping) are: \( f = 1986 \);
- Execution time = 0.991 s;
- Results of tabu (insertion) are: \( f = 2367 \);
- Execution time = 1.542 s;
- Execution time = 0.945

The best results are obtained by using by tabu (swapping) for \( f = 1986 \).

**4. Computational analysis**

Determine \( \sigma = \sigma \cup \{h\} \) and \( f_{\sigma} = f_{\sigma} + w_h C_{\sigma} \); and

End
 Else
 Begin
 Set \( Z = Z + 1 \);
 End
 If \( f_{\text{swapp}} < f \) Do

**Step 6.1:** \( T[1] = f_{\text{swapp}} \)

else \( T[1] = f_{\text{insert}} \)

End if

Step 6.2: Display \( \sigma(f_{\text{swapp}}) \)

Data generation

The heuristic were tested on problems generated with 500 tasks similar to that used in previous studies (Ho and Chang, 1995; M’Hallah and Bulfin, 2005) for each task \( j \) an integer processing time \( p_j \) was randomly generated in the interval \( (1.99) \) with a weight randomly \( w_j \) chosen in interval \( (1.10) \). The Table 2 presents:

1- The initial mean values of objective function corresponding to initial sequence.
2- The initial mean values of objective function obtained by using on one hand, the neighborhood by
swapping and on the other hand, the neighborhood by insertion.  

3- The average times corresponding to the two neighborhoods.  
4- The best costs.  

| Initial Solution (average of 3 instances) | Tabu search by swap | Tabu search by insertion | Best costs |
|------------------------------------------|---------------------|--------------------------|------------|
| AC 0,897                                 | 44957               | 44845                    | 44845      |
| 41544                                    | 1,01                | 41235                    | 41094      |
| 34220                                    | 0,99                | 33020                    | 34008      |
| 202482                                   | 4,43                | 200848                   | 201830     |
| 220786                                   | 6,65                | 220364                   | 210600     |
| 230501                                   | 3,98                | 197233                   | 226582     |
| 903625                                   | 7,65                | 834570                   | 856713     |
| 863040                                   | 9,86                | 791284                   | 786173     |
| 875476                                   | 10,23               | 774283                   | 855364     |
| 909476                                   | 20,14               | 970528                   | 985476     |
| 1098437                                  | 28,76               | 925376                   | 906718     |
| 1287142                                  | 27,97               | 1001583                  | 973027     |
| 22206778                                 | 40,12               | 19765183                 | 21165329   |
| 15016104                                 | 45,67               | 13489345                 | 13987543   |
| 21646539                                 | 42,56               | 21135631                 | 21598743   |

5. Conclusion

In this paper, scheduling problem with single machine and availability zones is solved using a novel metaheuristic polynomial approach (Tabu search) with complexity $O(\ln n)$. The tabu list of this problem is dynamic and its size varies according to amelioration state of the solution. The developed approach is based on diversification strategy using solution search algorithm that restarts from the point of the solution that was chosen among the earlier best unmaintained found solutions. According to the curried out tests, it is concluded that the proposed approach ensure acceptable results. It must be noted that the neighborhood by swapping presents the best costs with an acceptable execution time.

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