On the nonreflecting boundary operators for the general two dimensional Schrödinger equation

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Of the two main objectives we follow in this paper, the first one consists in the studying operators of the form \((\partial_t - i\Delta)^a\), \(a = 1/2, -1/2, -1, \ldots\), where \(\Delta\) is the Laplace-Beltrami operator. These operators arise in the context of nonreflecting boundary conditions in the pseudo-differential approach for the general Schrödinger equation. The definition of such operators is discussed in various settings and a formulation in terms of fractional operators is provided. The second objective consists in deriving corner conditions for rectangular domains which are fundamentally inadmissible in the pseudo-differential approach. Stability and uniqueness of the solution is investigated for each of these novel boundary conditions.

I. INTRODUCTION

In this article we consider the problem of construction of nonreflecting boundary condition for the general two dimensional Schrödinger equation. In particular, we consider the following initial-value problem (IVP):

\[
\begin{align*}
    i\partial_t u + \Delta u + \phi(x, t, |u|^2) u &= 0, \quad (x, t) \in \mathbb{R}^2 \times \mathbb{R}_+, \\
    u(x, 0) &= u_0(x), \quad x \in \mathbb{R}^2.
\end{align*}
\]

The initial data is assumed to be supported within the computational domain, \(\Omega\), i.e., \(\text{supp}_x u_0(x) \subset \Omega\). This problem has been treated by several authors \([1]-[10]\). Exact formulations of the transparent boundary condition (TBC) for the free Schrödinger equation on convex domains, \(\Omega\), with smooth boundary was provided by Schädle \([4]\) in terms of a single and a double layer potential. The special case of a circular domain was treated by Han and Huang \([5]\). Earlier attempts to derive an exact TBC for a rectangular domain by Menza proved to be problematic on account of the presence of corners \([1,2]\). This problem is resolved in a recent work by Feshchenko and Popov \([6]\). On account of the lack of integrability, these techniques cannot be applied to the general Schrödinger equation and one has to turn to approximate methods (refer to the review article \([11]\) for a comprehensive literature survey).

For the approximate methods, we restrict ourselves to the pseudo-differential approach (in particular, the gauge transformation strategy) for constructing approximate nonreflecting boundary conditions referred to as the absorbing boundary conditions or artificial boundary conditions for various types of computational domains. Our goal is to understand operators of the form \((\partial_t - i\Delta)^a\), \(a = 1/2, -1/2, -1, \ldots\), which appeared in the works of Menza \([1, 2]\) and Antoine et al. \([3, 9]\). Several aspects of such artificial boundary conditions (ABCs) which comprises these operators are not quite well understood; we discuss these issues which motivate the present work in the subsequent paragraphs.

Contrary to the existing belief that the aforementioned operators can only be implemented via a Padé approximation of a monomial of fractional degree \(a\), i.e., \(e^a\), it is shown in various settings that this operator can be expressed in terms of fractional operators. For arbitrary functions \(f(x, t), \ (x, t) \in \mathbb{R} \times \mathbb{R}_+\), the operation \((\partial_t - i\Delta)^a f(x, t), \ a = 1/2, -1/2, -1, \ldots\), requires the knowledge of the function over its entire support. If \(\text{supp}_x f(x, t) \subset \Gamma_t, \ \forall t \geq 0\) or \(f(x, t)\) is periodic with respect to \(x\) and it can be uniquely defined by its values at \(x \in \Gamma_s\) for all \(s \geq 0\), then it is shown that a formulation particularly convenient for expressing the TBCs/ABCs for the IVP in \((1)\) can be developed\(^1\). Let us remark that the numerical implementation of such operators is not being considered in this paper; however, it can be easily seen that the formulation developed in this paper makes these operators amenable to convolution quadrature. It might be expected that the new scheme affords improvement in accuracy over the existing Padé approximation based method\(^2\) reported in \([10]\).

Further, it is well known that the pseudo-differential approach cannot be applied to computational domains with corners. This precludes the rectangular domain which happens to be a very convenient choice of the computational domain. The ABCs involving the operators of the form \((\partial_t - i\Delta)^a\) cannot be adapted to the rectangular domain in a straightforward manner; however, the ABCs obtained as local approximations (with respect to \(x\)) or equivalently the high-frequency approximations of this operator admit of the possibility of constructing corner conditions. We demonstrate this possibility for the free as well as the general Schrödinger equation given by \((1)\). Our approach is closely related to the ideas presented in \([12, 13]\).

Another program that we have followed in this paper is of obtaining the well-known energy estimate

\[
\|u(x, t)\|_{L^2(\Omega)} \leq \|u_0(x)\|_{L^2(\Omega)},
\]

for the IVP in \((1)\) with TBCs/ABCs as boundary conditions involving operators of the form \((\partial_t - i\Delta)^a\) or high-frequency approximations of it\(^3\). Under the assumption that the solution exists, this inequality guarantees the stability as well as the

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\(^1\) The TBCs derived by Feshchenko and Popov \([6]\) happen to be a special case where this operation can be carried without having to consider the function \(f(x, t)\) over its entire support. The function \(f(x, t)\) here refers to the restriction of the field \(u(x, t), x \in \mathbb{R}^2\), to the segments of the boundary of the rectangular domain.

\(^2\) A distinction must be made between the Padé approximation based methods which are applied directly to the operator \((\partial_t - i\Delta)^a\) and those applied to the fractional operator formulation of this operator discussed in this paper.

\(^3\) The corner conditions are also incorporated in this equivalent formulation.
uniqueness of the solution of the equivalent initial boundary-value problem (IBVP). In certain cases, this result can be obtained by resorting to a general construct such that for any pseudo-differential operator, $P$, and a function $u \in C^\infty_0(\Omega)$ we have

$$2\Re \langle u | Pu \rangle = \langle u | Pu \rangle + \langle u | P^* u \rangle,$$

where $P^*$ is adjoint of the operator $P$, $\Re$ stands for real part and $\langle u | v \rangle = \int_{\Omega} u^* v d\Omega$. Given the symbol $\sigma_P$ of $P$, the symbol of the adjoint, $\sigma_{P^*}$, can be computed using the following general formula: Assuming $x, y \in \mathbb{R}^n$ and $\xi$ the covariable of $y$, then

$$\sigma_{P^*}(y, \xi) = \sum_{\alpha \in \mathbb{N}^n} \frac{1}{\alpha! \rho^n} \partial_\xi^\alpha [\partial_x^\alpha \sigma_P(y, \xi)],$$

where $\sigma_{P^*}$ stands for complex conjugate of $\sigma_P$ (complex conjugate of $z \in \mathbb{C}$ is also denoted by $\overline{z}$). A more detailed discussion of this approach is provided in [A].

The discussion of the primary results in this paper is broadly divided into two sections: Section II deals with the free Schrödinger equation while Section III deals with the general Schrödinger equation. For each of these problems, we consider two types of domains, namely, the rectangular domain (or, infinite strip with periodic boundary condition along the unbounded direction) and convex domains with smooth boundary. The basic definition of the operator $(\partial_r - i\Delta_x)^\gamma$, $\gamma = 1/2, -1/2, -1, \ldots$, is discussed in various settings. Two families of ABCs are considered in this paper: first one obtained via the standard pseudo-differential approach and the second one obtained as the high-frequency approximation of the former. The derivation of corner conditions and the study of stability and uniqueness of the solution are carried out separately for each of these problems in the subsections.

II. FREE SCHRODINGER EQUATION

Let us start our discussion with the linear case of the equation (1) with null-potential, i.e.,

$$i\partial_t u + \Delta u = 0, \ (x, t) \in \mathbb{R}^2 \times \mathbb{R}_+,$$

$$u(x, 0) = u_0(x), \ x \in \mathbb{R}^2. \quad (5)$$

The problem of constructing transparent boundary condition can be exactly treated for the case of compactly supported initial data for a computational domain $\Omega$, with a general smooth boundary $\Gamma$. The basic approach involves solving the initial boundary value problem on the exterior domain. The exterior domain is defined by $\Omega_\infty = \mathbb{R}^2 \setminus \overline{\Omega}$. It is known that a boundedness condition at infinity does not ensure unique solution of the above IVP; one additionally needs to impose a Sommerfeld-like radiation condition at infinity in order to exclude all the incoming waves from infinity. This condition reads as

$$\lim_{|x| \to \infty} \sqrt{|x|} (\nabla u \cdot \frac{x}{|x|} + e^{-i\frac{x}{2}} \partial_{|x|}^{-1/2} u) = 0. \quad (6)$$

Using the decomposition of $u(x, t) \in L^2(\mathbb{R}^2) = L^2(\Omega) \oplus L^2(\Omega_\infty)$ and introducing the fields $v(x, t)$ and $w(x, t)$ we have

$$\begin{cases}
\partial_t v + \Delta v = 0, \ (x, t) \in \Omega, \ x \in \mathbb{R}_+; \\
v(x, 0) = u_0(x), \ x \in \Omega; \\
\partial_t w + \Delta w = 0, \ (x, t) \in \Omega \times \mathbb{R}_+, \\
u(x, 0) = 0, \ x \in \Omega; \\
\lim_{|x| \to \infty} \sqrt{|x|} (\nabla w \cdot \frac{x}{|x|} + e^{-i\frac{x}{2}} \partial_{|x|}^{-1/2} w) = 0; \\
v(x, t)|_{\Gamma} = w(x, t)|_{\Gamma}, \partial_{\nu} v(x, t)|_{\Gamma} = \partial_{\nu} w(x, t)|_{\Gamma}.
\end{cases} \quad (7)$$

Construction of the nonreflecting boundary conditions involves solving the exterior problem exactly. In the following sections we first consider a infinite strip as computational domain (or periodic boundary condition in the direction it extends to infinity) then extend the results to a rectangular domain.

A. Infinite strip

In this section we restrict ourself to the case of an infinite strip with the boundary parallel to one of the coordinate axes, or, rectangular domain with a periodic boundary condition along one of the coordinate axes. Let the coordinate axes be labelled as $e_1$ and $e_2$. For the infinite strip, say with boundary parallel to the axis $e_1$, we assume that supp $u_0(x)$ is bounded. The derivation of the TBCs for the infinite straight boundary is particularly simple and can be obtained using Laplace transform in time and a Fourier transform in space. Let us consider the IVP in (5) where the domain is defined by the infinite strip between $x_1 = x_l$ and $x_1 = x_r$. For the TBC on the right boundary, one must consider the IBVP on the right exterior domain $\Omega_\infty = \{x_1 \in \mathbb{R} \} \times \mathbb{R}_+$. Let the covariable of $(x_1, x_2)$ be denoted by $(\xi_1, \xi_2)$, respectively. We introduce the notation $\mathcal{F}_{x_1} f(x_1, x_2, t) = \mathcal{F}_{x_1}[f]{(\xi_1, x_2, t)}$ for one

![Diagram](image-url)
dimensional Fourier transform with respect to $x_1$ (similarly $\mathcal{F}_{x_2} f(x_1, x_2, t) = \mathcal{F}_{x_1} [f](x_1, \xi, t)$ for Fourier transform with respect to $x_2$). For denoting the Laplace transform of a function we use $\mathcal{L}_t f(t) = \mathcal{L}_t[f](s) = F(s)$.

Let us denote the Fourier transform with respect $x_2$ of $w(x_1, x_2, t)$ by $\tilde{w}(x_1, \xi, t)$ and Laplace transform with respect to $t$ of $\tilde{w}(x_1, x_2, t)$ by $\tilde{W}(x_1, \xi, s)$, i.e.,

$$\tilde{w}(x_1, \xi, t) = \mathcal{F}_{x_2} w(x_1, x_2, t),$$

$$\tilde{W}(x_1, \xi, s) = \mathcal{L}_t \tilde{w}(x_1, \xi, t).$$

(8)

For the case of compactly supported initial data, we have

$$(\partial_t^2 + \alpha^2)\tilde{W}(x_1, \xi, s) = 0, \ x_1 \in [x, \infty),$$

where $\alpha = \sqrt{i\xi - \xi_2^2}$ such that $\Im(\alpha) > 0$. The solution can be worked out as follows: observing

$$\partial_t \tilde{W}(x_1, \xi, t) = i\alpha \tilde{W}(x_1, \xi, t),$$

$$\mathcal{L}^{-1}[\partial_t \tilde{W}(x_1, \xi, t)] = \mathcal{L}^{-1}[i\alpha^{-1}] \ast \mathcal{L}^{-1}[\alpha^2 \tilde{W}(x_1, \xi, s)],$$

where the convolution kernel is given by

$$\mathcal{G}(x_2, 0) = \frac{e^{-i\xi/4}}{\sqrt{4\pi t}}, \ \text{with} \ \mathcal{G}(\xi, t) = e^{-i\xi^2 t/4}.\)\)

This map can be expressed compactly if we employ the notation

$$(\partial_t - i\partial_2)^{-1/2} f(x_2, t) = \frac{1}{\sqrt{\pi}} \int_0^\infty \left[ \int_{\mathbb{R}} f(x_1, x_2', \tau) \frac{\mathcal{G}(x_2 - x_2', t - \tau)}{\sqrt{t - \tau}} \right] dx_2' d\tau,$$

(12)

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(14)

where $f$ is assumed to be an element of $C^\infty(\mathbb{R} \times \mathbb{R}_+)$ such that it is of the Schwartz class with respect to $x_2$. On account of the singular nature of the symbol, it is not a pseudo-differential operator. However, away from the points satisfying $\xi + \xi_2^2 = 0$, it can be microlocally regarded as a pseudo-differential operator with a symbol $(i\xi + \xi_2^2)^{-1/2}$ with the branch cut defined by $-\pi \leq \arg(i\xi + \xi_2^2) < \pi$ where $(\xi_2, \xi)$ are the covariates of $(x_2, t)$. Further, if we take the operator $(\partial_t - i\partial_2)^{-1/2}$ to be defined by

$$(\partial_t - i\partial_2)^{-1/2} f = (\partial_t - i\partial_2)^{-1/2}[(\partial_t - i\partial_2)^{-1/2} f],$$

(15)

then

$$\partial_t w(x_1, t) + e^{-i\xi/4}(\partial_t - i\partial_2)^{-1/2} w(x_1, t) = 0, \ (x, t) \in \Omega \times \mathbb{R}_+.\)\)

(16)

where *s* represents the convolution operation, we have

$$\partial_t \tilde{w}(x_1, \xi, t) = e^{i\tau/4} e^{-i\xi^2/2} \partial_t^{\xi+1/2} \tilde{w}(\xi, t),$$

(10)

It is also easy to verify

$$\partial_t e^{-i\xi^2 t/2} \partial_t^{-1/2} e^{i\xi^2 t/2} \tilde{w}(x_1, \xi, t) = e^{-i\xi^2 t/2} \partial_t^{-1/2} e^{i\xi^2 t/2} \partial_t \tilde{w}(x_1, \xi, t).\)\)

(11)

Now, taking the inverse Fourier transform, we obtain the Dirichlet to Neumann map as

$$\mathcal{L}^{-1}[i\alpha^{-1}] = \frac{1}{2\pi} \int_{-\infty}^{\infty} \frac{e^{it}}{\sqrt{i\xi - \xi_2^2}} ds.$$

(17)

Next, we would like to obtain a more local approximation of this boundary condition valid for small times. To this end, let us consider

$$\mathcal{L}^{-1}[i\alpha^{-1}] = \frac{1}{2\pi} \int_{-\infty}^{\infty} \frac{e^{it}}{\sqrt{i\xi - \xi_2^2}} \frac{e^{i\xi^2 t}}{\sqrt{4\pi t}} ds.$$
For the periodic case, we may take the computational domain to be \( \Omega = [x, x_1] \times [0, 2\pi] \) so that

\[
wx(x_1, x_2, t) = \sum_{m \in \mathbb{Z}} \hat{w}_m(x_1, t) e^{imx_2},
\]

(20)

\[
W(x_1, x_2, s) = \sum_{m \in \mathbb{Z}} \hat{w}_m(x_1, s) e^{imx_2}.
\]

(21)

with \( \hat{w}_m(x_1, s) = \mathcal{F}^{(1)}[\hat{w}_m(x_1, t)] \). For simplicity we demonstrate the procedure for the \( m \)-th Fourier component. The complete result is obtained by superposing all the components. Putting \( \alpha_m = \sqrt{i s - m^2} \), the following results can be obtained in the same manner as before to obtain

\[
\partial_t \hat{w}_m(x_1, t) = e^{i\pi/4} e^{-im\pi/2} i^{\pi/2} e^{im\pi} \hat{w}_m(x_1, t) \times i \partial_t \hat{w}_m(x_1, t) - m^2 \hat{w}_m(x_1, t).
\]

(22)

It is also easy to verify the following relations:

\[
\partial_t e^{-im\pi/2} \partial_t^{1/2} e^{im\pi} \hat{w}_m(x_1, t) = e^{-im\pi/2} \partial_t^{1/2} e^{im\pi} \partial_t \hat{w}_m(x_1, t),
\]

(23)

\[
e^{-im\pi/2} \partial_t^{1/2} e^{im\pi} \left( i \partial_t \hat{w}_m(x_1, t) - m^2 \hat{w}_m(x_1, t) \right) = ie^{-im\pi/2} \partial_t^{1/2} e^{im\pi} \hat{w}_m(x_1, t).
\]

(24)

Using these relations, one can derive an equation analogous to (22)

\[
\partial_t w(x, t) = \frac{i \pi}{\sqrt{\pi}} \int_0^\infty \int_0^{2\pi} i \partial_t w(x_1, x_2, \tau) + \partial_{x_2}^2 w(x_1, x_2, \tau) \frac{G(x_2 - x_2', t - \tau)}{\sqrt{t - \tau}} dx_2' d\tau,
\]

(25)

with the convolution kernel given by

\[
G(x_2, t) = \sum_{m \in \mathbb{Z}} e^{imx_2 - im\pi/2},
\]

(26)

which is defined only in a distributional sense. For periodic functions the operator defined in (14) becomes

\[
(\partial_t - i \partial_{x_2}^2)^{-1/2} f(x_1, t) = \frac{1}{\sqrt{\pi}} \int_0^\infty \int_0^{2\pi} f(x_1, x_2, \tau) \frac{G(x_2 - x_2', t - \tau)}{\sqrt{t - \tau}} dx_2' d\tau,
\]

(27)

where the kernel is defined by (26). We now turn our attention to obtaining a form of the operator \( (\partial_t - i \partial_{x_2}^2)^{-1/2} \) which can be numerically implemented. Using the relation (24), we may write

\[
\partial_t w(x, t) = e^{-im\pi/2} \sum_{m \in \mathbb{Z}} e^{im\pi/2} \partial_t^{1/2} e^{im\pi} \hat{w}_m(x_1, t) e^{imx_2}],
\]

(28)

Introducing the auxiliary function \( \varphi(x_1, x_2, t, t') \) such that

\[
\varphi(x_1, x_2, t, t') = \sum_{m \in \mathbb{Z}} e^{im(t - t')} \hat{w}_m(x_1, t') e^{imx_2}],
\]

(29)

In order to determine all the values of the function needed to compute the non-local fractional derivative, the following relations can be used:

\[
\left[ i \partial_t + \partial_{x_2}^2 \right] \varphi(x_1, x_2, t, t') = 0, \quad x_1 \in [x_1, \infty),
\]

\[
\varphi(x_1, x_2, t', t') = w(x_1, x_2, t').
\]

(30)

For all possible values of \( t' \) satisfying \( 0 \leq t' \leq t \) and \( x_2 \in [0, 2\pi] \), one must solve the above initial value problem starting from the initial condition at \( t = t' \) under the periodic boundary condition in \( x_2 \). This process is schematically shown in Fig. 2. The history of the field is needed along the vertical line up to the diagonal in the (t, t')-plane.

**Remark 1.** Such a procedure can be used to compute the action of any operator of the form \( (\partial_t - i \partial_{x_2}^2)^{-n/2} \), \( n = 1, 2, \ldots \), on any function periodic in \( x \in \mathbb{R} \), say, \( f(x, t) \). Introducing an auxiliary function \( \varphi(x, t, t') \) such that

\[
\varphi(x, t, t') = \sum_{m \in \mathbb{Z}} e^{-im(t - t')} \hat{f}_m(t') e^{imx_2}],
\]

(31)

\[
(\partial_t - i \partial_{x_2}^2)^{-n/2} f(x, t) = \partial_{x_2}^{-n/2} \varphi(x, t, t')|_{t=t'}.
\]

The associated IVP is given by

\[
[i \partial_t + \partial_{x_2}^2] \varphi(x, t, t') = 0,
\]

\[
\varphi(x, t', t') = f(x, t').
\]

(32)

1. **Stability and uniqueness**

An equivalent formulation of the IVP (3) on the computational domain \( \Omega = [x_1, x_2] \times [0, 2\pi] \) with periodic boundary
Therefore, we have

$$i \partial_t u + \Delta u = 0, \quad (x, t) \in \Omega_t \times \mathbb{R}_+,$$

$$u(x, 0) = u_0(x) \in L^2(\Omega), \quad u_0(x) \in \Omega_t,$$

$$u(x_1, x_2 + 2\pi, t) = u(x_1, x_2, t), \quad t > 0,$$

$$\partial_n u(x, t) + e^{-i\pi/4}(\partial_t - i\partial_x^2) u(x, t) = 0, \quad x \in \Gamma_I \cup \Gamma_r. \quad (33)$$

Assuming that the solution $u(x, t)$ exists, we have

$$\int_{\Omega_t} (\partial_t |u|^2) dx = 2\Re \int_{\Gamma_I} (u^* \nabla u) \cdot d\xi,$$

$$||u(x, T)||_{L^2(\Omega_t)}^2 - ||u_0(x)||_{L^2(\Omega)}^2 = \Re \int_0^T \int_{\Gamma_I} (u^* \nabla u) \cdot d\xi,$$

where $d\xi = e_x |dx|$ for $x \in \Gamma$. Further noting $\tilde{u}_m(x_1, t) \in H^{1/4}(0, T)$, we have

$$I_R = -2\Re \int_{\mathbb{R}_+} dt \int_{\Gamma_I} (u^* e^{i\pi/4} \sqrt{\partial_t - i\partial_x^2} u) dx_2,$$

$$= -4\pi \Re \sum_{m \in \mathbb{Z}} \int_{\mathbb{R}_+} dt \left( \tilde{u}_m(x_1, t) e^{-i\pi/4} \right) \left( \partial_t^{1/2} \tilde{u}_m(x_1, t) e^{-i\pi/4} \right).$$

$$= -2 \sum_{m \in \mathbb{Z}} \left[ \int_{|\xi|<0} d\xi \left| \tilde{u}_m(x_1, t) e^{-i\pi/4} \right|^2 \right]. \quad (35)$$

Similarly, it can be shown that

$$I_L = -2\Re \int_{\mathbb{R}_+} dt \int_{\Gamma_I} (u^* e^{i\pi/4} \sqrt{\partial_t - i\partial_x^2} u) dx_2 < 0. \quad (36)$$

Therefore, we have

$$||u(x, T)||_{L^2(\Omega_t)} \leq ||u_0(x)||_{L^2(\Omega)}. \quad (37)$$

This result also guarantees the uniqueness of the solution.

**B. Rectangular Domains**

Let us consider a rectangular domain given by

$$\Omega_t = \{(x_1, x_2) : x_1 \in \Omega_t \subset \mathbb{R}, \quad x_2 \in \Omega_t \},$$

and denote the boundaries as $\Gamma_{1,t} = \{(x_1, x_2) \in \partial \Omega_t : x_1 = x_1, \quad x_2 \in \Omega_t\}$, respectively and $\Gamma_{2,t} = \{(x_1, x_2) \in \partial \Omega_t : x_1 = \Omega_t\}$. Assuming $u_0(x)$ bounded in $\Omega_t$, the TBCs for the infinite strip cannot be taken to be the transparent boundary operators at the straight edges because the corresponding operator requires knowledge of the entire support of the field along the tangential direction at the boundary. This clearly cannot be achieved because after a certain time the field would have spread outside the domain defined by any segment of the rectangular domain, say, $\Gamma_r$. This issue can be resolved in the following way: Using the same notation as in the last section and observing that

$$\partial_x \tilde{u}(x_1, x_2, t) = e^{i\pi/4} e^{-i\pi/4} \frac{\partial_t^{1/2} e^{i\pi/4} i \partial_x \tilde{u}(x_1, x_2, t) + (\partial_x \tilde{u}(x_1, x_2, t))}{\partial_t \tilde{u}(x_1, x_2, t)} \quad (38)$$

$$\partial_x \tilde{w}(x_1, x_2, t) = e^{-i\pi/4} e^{-i\pi/4} \frac{\partial_t^{1/2} e^{-i\pi/4} \varphi(x_1, x_2, t) + (\partial \varphi(x_1, x_2, t))}{\partial_t \varphi(x_1, x_2, t)},$$

where the auxiliary function is defined by $\mathcal{F}_{x_2} \varphi(x_1, x_2, t, t') = e^{-i\pi/4} e^{-i\pi/4} \tilde{w}(x_1, x_2, t')$. It is easy to verify that the function $\varphi$ satisfies the following IVP

$$[i \partial_t + \partial_x^2] \varphi(x_1, x_2, t, t') = 0,$$

$$\varphi(x_1, x_2, t', t') = w(x_1, x_2, t').$$

The boundary conditions at the endpoints of the segment $\Gamma_r$ are not known because the original problem is defined on the infinite domain $x_2 \in \mathbb{R}$. However, it can be shown that the value of the auxiliary function $\varphi(x_1, x_2, t, t')$ at $t = 0$ is compactly supported in $\Gamma_r$ for $x_1 \in [x_r, \infty)$. This would allow one to impose the transparent boundary conditions at the endpoints of $\Gamma_r$. To this end, let us consider the IVP defined...
by \((5)\), it can be solved using Fourier transform in \((x_1, x_2)\). Putting \(\hat{u}_0(\zeta) = \mathcal{F}_{x_1, x_2} u_0(x)\), we have
\[
\mathcal{F}_{x_1, x_2} u(x, t) = e^{-i\zeta^2 t + i\zeta^2} \hat{u}_0(\zeta),
\]
\[
\varphi(x_1, x_2, t, t') = \frac{1}{(2\pi)^2} \int_{\mathbb{R}^2} e^{i\zeta x - i\zeta^2 t + i\zeta^2 t'} \hat{u}_0(\zeta) d^2\zeta.
\]
(41)

Therefore, \(supp, \varphi(x_1, x_2, 0, t') \subset \Gamma_r\), for \(x_1 \in \mathbb{R}\) and
\[
[i\partial_{t'} + \partial_{x_1}^2] \varphi(x_1, x_2, t, t') = 0.
\]
(42)

Hence, the boundary condition at the endpoints of \(\Gamma_r\) is given by
\[
\partial_{x_1} \varphi(x_1, x_2, t, t') \pm e^{-i\pi/4} \partial_{x_1}^{1/2} \varphi(x_1, x_2, t, t') = 0,
\]
\(x_1 \in \Gamma_r, x_2 \in \{x_2, x_0\}\), respectively. This knowledge of \(\varphi(x_1, x_2, t, t')\) for \(x_2 = \partial \Gamma_r\) and \(0 \leq t \leq t'\). The algorithm can be explained by means of the Fig. [4] There are two IVPs for the auxiliary field, \(\varphi(x_1, x_2, t, t')\) each of which evolve the field either above or below the diagonal in \((t, t')\)-plane starting from the values at the diagonal in their respective domains. These points are represented by filled circles and the arrows denote the direction of evolution. All diagonal points are evolved along \(t\) or \(t'\)-axis in order to provide the history needed for TBCs in the current time step (represented by horizontal or vertical line in \((t, t')\)-plane). The empty circles correspond to the corner points. The values of the auxiliary field at the corners are needed for the TBCs satisfied by the auxiliary field; this relationship is depicted by the broken lines. Note that these values at the corners can be taken from the adjacent segment of the boundary where it is already being computed.

Remark 2. From the discussion above we obtain the following useful definition of the operator \((\partial_t - i\partial_x^2)^{-1/2}\), \((x, t) \in \mathbb{R} \times \mathbb{R}_+\):
\[
(\partial_t - i\partial_x^2)^{-1/2} f(x, t) = \frac{1}{2\pi} \int d\zeta dx' e^{-i\zeta(x-x')} [\partial_{t'}^{1/2} e^{-i\zeta^2(t-t')} f(x', t')]_{t'=t},
\]
\(\forall x \in \mathbb{R}\). This definition makes it explicit that one has to consider the function \(f(x, t)\) over its entire support with respect to \(x \in \mathbb{R}\) in order to compute the expression; however, in special cases this can be avoided. Similarly, a formal definition of the operator \((\partial_t - i\partial_x^2)^{-m/2}\), \((x, t) \in \mathbb{R} \times \mathbb{R}_+, m > 0\), for any arbitrary function \(f(x, t)\) with sufficient smoothness property can be given. This operator can be defined as
\[
(\partial_t - i\partial_x^2)^{-m/2} f(x, t) = \frac{1}{2\pi} \int d\zeta dx' e^{-i\zeta(x-x')} [\partial_{t'}^{m/2} e^{-i\zeta^2(t-t')} f(x', t')]_{t'=t},
\]
\(\forall x \in \mathbb{R}\).
(45)

The integration with respect to \(x\) can be easily performed. Defining the convolution kernel \(\mathcal{K}(x, t)\) by
\[
\mathcal{K}(x, t) = \begin{cases} \frac{e^{-i\pi/4}}{2\sqrt{\pi} \Gamma(m/2)} t^{m-1} \exp[i t^2/\pi], & t > 0, \\ 0, & t \leq 0, \end{cases}
\]
we obtain
\[
(\partial_t - i\partial_x^2)^{-m/2} f(x, t) = \int dx' dt' \mathcal{K}(x-x', t-t') f(x', t').
\]
(47)

From this definition it is clear that the operator cannot be defined on a compact domain with respect to \(x\) for arbitrary functions. Let us introduce \(\varphi(x, t, t')\) defined by
\[
\varphi(x, t, t') = \frac{1}{2\pi} \int d\zeta dx' e^{-i\zeta(x-x')} e^{-i\zeta^2(t-t')} f(x', t'),
\]
so that
\[
(\partial_t - i\partial_x^2)^{-m/2} f(x, t) = \partial_{t'}^{m/2} \varphi(x, t, t')|_{t'=t},
\]
\(i\partial_t \varphi(x, t, t') + \partial_{x_1}^2 \varphi(x, t, t') = 0,
\varphi(x, t, t') = f(x, t').
\]
(49)

The possibility of defining the operator on a compact domain with respect to \(x\) depends on the initial condition \(\varphi(x, 0, t')\) given by
\[
\varphi(x, 0, t') = \frac{1}{2\pi} \int d\zeta dx' e^{-i\zeta(x-x')} e^{i\zeta^2 t'} f(x', t').
\]
(50)

If \(supp, \varphi(x, 0, t')\) is compact then the PDE in \((49)\) can be solved on any domain \(\Omega\) such that \(supp, \varphi(x, 0, t') \subset \Omega, \forall t' \geq 0\). This allows us to impose TBCs for \((49)\) at the boundaries; however, the value of the function \(\varphi(x, t, t')\) at the boundaries for \(t \in [0, t']\) needs to be computed.

1. High-frequency approximation

The high-frequency approximation affords the possibility of simplifying the TBC by making them “local” in terms of the spatial variable. The asymptotic expansion worked out in \((19)\) can be carried out for each of the edges of the rectangular domain to obtain the following ABCs:
\[
\partial_n u + e^{i\pi/4} \partial_{x_1} u - e^{-i\pi/4} \frac{1}{2} \partial_{x_1} \partial_{t'} u = 0, \quad x \in \Gamma_r \cup \Gamma_t,
\]
\[
\partial_n u + e^{-i\pi/4} \partial_{x_1} u - e^{-i\pi/4} \frac{1}{2} \partial_{x_1} \partial_{t'} u = 0, \quad x \in \Gamma_b \cup \Gamma_t.
\]
(51)

These boundary conditions become problematic at the corners of the rectangular domain. This aspect can be illustrated by the considering the weak formulation of the original IVP as follows: Consider a test function \(\psi(x) \in \mathcal{H}^1(\Omega_\epsilon)\); taking the inner product with the equation \((5)\) we have
\[
\int_{\Omega} (i\partial_t u + \nabla^2 u) \psi d^2x = i\partial_t \int_{\Omega} u \psi d^2x - \int_{\Omega} (\nabla u \cdot (\nabla \psi)) d^2x + \int_{\partial \Omega} \psi (\nabla u) \cdot d\zeta.
\]
(52)

Let us consider the top and right boundaries. The boundary integrals are given by
The TBCs for auxiliary field require the history of the auxiliary field at the endpoints, depicted by broken lines; these conditions for the other corners of the rectangular domain:

\[
\frac{\partial_{u}}{i\partial_{t}} + \frac{3}{2} e^{-in/4} \partial_{x}^{3/2} u = 0, \quad (x_{1}, x_{2}) \in \Gamma_{i} \cap \Gamma_{j},
\]

where \(i \neq j\) and \(i, j \in \{r, t, l, b\}\).

In order to evaluate this term, we proceed as follows. Carrying out the fractional integration, \(\partial_{x}^{-1/2}\), of the evolution equation (5), we have

\[
i \partial_{x}^{-1/2} u + (\partial_{x}^{2} + \partial_{y}^{2}) \partial_{x}^{-1/2} u = 0, \quad (x_{1}, x_{2}) \in \Gamma_{r} \cap \Gamma_{r}.
\]

Here, the fact that the field is zero at the corner at \(t = 0\) is explicitly used to arrive at the fractional derivative. Using BCs (51) and the last equation, we obtained the following corner condition:

\[
\partial_{x} u + \partial_{y} u + \frac{3}{2} e^{-in/4} \partial_{t}^{3/2} u = 0, \quad (x_{1}, x_{2}) \in \Gamma_{r} \cap \Gamma_{r}.
\]

A similar procedure can be used to the construct corner conditions for the other corners of the rectangular domain:

\[
\frac{\partial_{u}}{i\partial_{t}} + \frac{3}{2} e^{-in/4} \partial_{x}^{3/2} u = 0, \quad (x_{1}, x_{2}) \in \Gamma_{i} \cap \Gamma_{j},
\]

where \(i \neq j\) and \(i, j \in \{r, t, l, b\}\).

2. Stability and uniqueness

Let us write the equivalent formulation of the IVP (5) for a rectangular domain \(\Omega\), using the TBCs derived in the last section:

\[
i \partial_{x} u + \Delta u = 0, \quad (x, t) \in \Omega \times \mathbb{R}_{+},
\]

\[
u(x, 0) = u_{0}(x) \in L^{2}(\Omega), \quad \text{supp} u_{0}(x) \subset \Omega,
\]

\[
\partial_{u} u(x, t) + e^{-in/4}(\partial_{t} - i\partial_{x}^{2})^{1/2} u(x, t) = 0, \quad x \in \Gamma_{r} \cap \Gamma_{r},
\]

\[
\partial_{u} u(x, t) + e^{-in/4}(\partial_{t} - i\partial_{x}^{2})^{1/2} u(x, t) = 0, \quad x \in \Gamma_{b} \cap \Gamma_{b}.
\]

Assuming that the solution \(u(x, t)\) exits for \(t \in [0, T]\), we have

\[
\|u(x, T)\|^{2}_{L^{2}(\Omega)} - \|u_{0}(x)\|^{2}_{L^{2}(\Omega)} = 2 \text{Re} \int_{0}^{T} dt \int_{\Gamma_{r} \cap \Gamma_{r}} (u^{*} i\partial_{x} u) \cdot d\mathbf{\xi} + \int_{\Gamma_{b} \cap \Gamma_{b}} (u^{*} i\partial_{x} u) \cdot d\mathbf{\xi}.
\]

In the above equation, the fields in the boundary integral can be extended to \(\mathbb{R}_{+}\) without changing the value of the integral by setting them identically to zero outside the interval \([0, T]\). For the right boundary, we have

\[
I_{R} = -2 \text{Re} \int_{0}^{T} dt \int_{\Gamma_{r}} (u^{*} e^{-in/4} \sqrt{\partial_{t} - i\partial_{x}^{2}} u) dx_{2}.
\]
Again, without changing the value of the integral with respect to $x_2$ the fields can be extended to whole line by setting them identically to zero outside $\Gamma_r$. We these considerations, one can write

$$I_R = -2 \Re \int_{\mathbb{R}_x} \int_{\mathbb{R}} \left( u^* e^{i \omega t / 4} \sqrt{\partial_{x_2} - i \partial_{x_2}^2} u \right) dx_2,$$

$$= -\frac{1}{\pi} \int_{\mathbb{R}_x} \int_{\mathbb{R}} d\xi \left( \bar{u}(x_1, \xi_2, t) e^{-i \xi_2^2} \right) \left( \partial_{x_2}^1 \bar{u}(x_1, \xi_2, t) e^{-i \xi_2^2} \right),$$

$$= -\frac{1}{2 \pi^2} \int_{|\xi|<\pi} d\xi \left( \int_{\mathbb{R}_x} d\xi \left| e^{-i \xi_2^2} \right| \left| \partial_{x_2}^1 \bar{u}(x_1, \xi_2, t) e^{-i \xi_2^2} \right| \right)^2 \leq 0. \quad (61)$$

Similarly, it can be shown that the other boundary integrals namely $I_L, I_B$ and $I_F$ corresponding to the left, bottom and top boundary, respectively, also satisfy the same inequality as that of $I_R$. Therefore, we have

$$\|u(x, T)\|_{L^2(\Omega)} - \|u_0(x)\|_{L^2(\Omega)} \Rightarrow \|u_0(x)\|_{L^2(\Omega)}, \quad (62)$$

Since $T \in \mathbb{R}_t$ is arbitrary, one replace $T$ with $t$ in the above inequality. This result solution also guarantees the uniqueness of the solution.

For the high-frequency approximation, we have the following equivalent formulation on $\Omega$: Putting $\Gamma = \partial \Omega_r$ and $\Gamma_c$, the set of four corner points, define the Laplace-Beltrami operator as $\partial_{\Gamma}$ so that

$$i \partial_t u + \Delta u - \epsilon u^* R^{\Gamma} \partial_t \bar{u}^{-1/2} u = 0, \quad (x, t) \in \Omega_r \times \mathbb{R}_t,$$

$$u(x, 0) = u_0(x) \in L^2(\Omega), \quad \text{supp} u_0(x) \subset \Omega_r,$$

$$\partial_{\Gamma} u + e^{-i \omega t / 4} \partial_{\Gamma}^{-1/2} u - \epsilon e^{i \omega t / 4} \frac{1}{2} \partial_{\Gamma} \partial_{\Gamma}^{-1/2} u = 0, \quad x \in \Omega \setminus \Gamma_c, \quad (63)$$

$$\partial_{\Gamma} u_{\Gamma_r} + \partial_{\Gamma} u_{\Gamma_j} + \frac{3}{2} e^{-i \omega t / 4} \partial_{\Gamma}^{-1/2} u = 0, \quad (x_1, x_2) \in \Gamma_i \cap \Gamma_j,$$

where $i \neq j$, and $i, j \in \{r, t, l, b\}$. Taking equation (59) and following the standard approach, we have

$$\int_{\Gamma_r} (u \cdot \nabla u) \cdot d\zeta = -e^{i \omega t / 4} \int_{\Gamma_r} u^* \partial_t^{1/2} u d|x| - \frac{1}{2} e^{-i \omega t / 4} \int_{\Gamma_r} |\partial_t u|^2 d|x| \quad (64)$$

$$= -e^{i \omega t / 4} \int_{\Gamma_r} u^* \partial_t^{1/2} u d|x| + \frac{1}{2} e^{-i \omega t / 4} \int_{\Gamma_r} |\partial_t u|^2 d|x| + \frac{3}{4} |\bar{u}(x_1, x_2)|^2 - \frac{3}{4} |u(x_1, x_2)|^2 + \frac{3}{4} |u(x_1, x_2)|^2 - \frac{3}{4} |u(x_1, x_2)|^2.$$

Taking the real part and plugging the result back into equation (59) yields

$$\|u(x, T)\|_{L^2(\Omega)} - \|u_0(x)\|_{L^2(\Omega)} \Rightarrow \|u_0(x)\|_{L^2(\Omega)} \quad (65)$$

$$= \left| \int_{|\xi|<\pi} d\xi \left( \int_{\mathbb{R}_x} d\xi \left| e^{-i \xi_2^2} \right| \left| \partial_{x_2}^1 \bar{u}(x_1, \xi_2, t) e^{-i \xi_2^2} \right| \right)^2 \right|^2 \leq \|u_0(x)\|_{L^2(\Omega)} \quad (66)$$

which guarantee stability and uniqueness of the solution on the bounded domain.

III. GENERAL SCHRÖDINGER EQUATION

The linear Schrödinger equation with time-dependent potential and the nonlinear case are treated in the same fashion. Let us consider the IVP corresponding to the general Schrödinger equation given by

$$i \partial_t u + \Delta u + \phi(x, t, |u|^2) u = 0, \quad (x, t) \in \mathbb{R}^2 \times \mathbb{R}_t,$$

$$u(x, 0) = u_0(x), \quad x \in \mathbb{R}^2. \quad (67)$$

The potential function, $\phi$ is assumed to be real valued.
curvilinear system is given by

\[ \text{construct various order ABCs given by} \]

The computational domain is taken to be a convex set \( \Omega_i \subset \mathbb{R}^2 \) with a smooth boundary \( \Gamma = \partial \Omega_i \). Let \( \chi(s) \) be the parametrization of the curve \( \Gamma \) where \( s \) is the length along the curve. Introducing the tangent vector \( e_r \), also a function of \( s \) only, and taking into account the convexity of the domain we have

\[ d\mathbf{x} = d\mathbf{e}_r + (1 + \kappa) ds \mathbf{e}_r, \]

where \( \kappa(s) \) is the curvature of the boundary \( \Gamma \) given by

\[ \kappa(s) = \left| \frac{d\mathbf{e}_r}{ds} \right| = \left| \frac{\text{det}(\chi', \chi'')}{\chi'^3} \right|. \]

The initial data is assumed to be compactly supported in the computational domain \( \Omega_i \). Carrying out the gauge transformation \( u = v e^{i\Phi} \), the evolution operator \( L \equiv i\partial_t + \Delta + \phi \) in the curvilinear system is given by

\[ L(r, s, t, \partial_r, \partial_s, \partial_t) = i\partial_t + \partial_r^2 + A \partial_r + h^2 \partial_s^2 + B \partial_s + C, \]

where \( A = (2i\Phi_t + h^{-1} \kappa) \), \( B = (2ih^{-2} \Phi_r + h^{-1} \partial_s h^{-1}) \) and \( C = i\Delta \Phi - (\nabla \Phi)^2 \). The pseudo-differential approach allows us to construct various order ABCs given by

**ABC\(_{1,0}\):**

\[ \partial_u u + e^{-i\Phi/4} e^{i\Phi} (\partial_t - i\partial_r^2)^{1/2} e^{-i\Phi} u = 0; \]

**ABC\(_{2,0}\):**

\[ \partial_u u + e^{-i\Phi/4} e^{i\Phi} (\partial_t - i\partial_r^2)^{1/2} e^{-i\Phi} u + \frac{1}{2} k u + e^{-i\Phi/4} \Phi_r e^{i\Phi} (\partial_t - i\partial_r^2)^{-1/2} \partial_s (e^{-i\Phi} u) + \frac{1}{2} i k e^{i\Phi} (\partial_t - i\partial_r^2)^{-1} \partial_r^2 (e^{-i\Phi} u) = 0. \]

where

\[ (\partial_t - i\partial_r^2)^{1/2} f(s, t) = (\partial_t - i\partial_r^2)(\partial_t - i\partial_r^2)^{-1/2} f(s, t), \]

assuming \( f(s, 0) = 0 \).

**Remark 3.** For the field \( u(x, t) \), the action of operators of the form \( (\partial_t - i\partial_r^2)^{\alpha} \), \( \alpha = 1/2, -1/2, -1, \ldots \), can be easily computed by observing that the field can be given a periodic extension in terms of the parametrization variable, \( s \), so that the method discussed in Remark 7 can be employed. The smoothness of the boundary is therefore a necessary condition for this method to be applicable. From the previous sections, we know that the operator represented by \( (\partial_t - i\partial_r^2)^{-m/2} \), where \( m \) is a positive integer, is defined as

\[ (\partial_t - i\partial_r^2)^{-m/2} f(s, t) = \frac{1}{2\pi} \int d\zeta d\xi \ e^{i(s-\xi)\zeta} (\partial_t e^{-i\xi} f(s, t))_{x=\xi}. \]

**Let** \( \mathcal{F}_x f(s, t) = \tilde{f}(\zeta, t) \), then the operation \( (\partial_t - i\partial_x^2)^{-m/2} \) involves the inverse Fourier transform of \( \tilde{f}(\zeta, t) e^{-i\xi(t-t')} \) with respect to \( \zeta \). Therefore, if \( f(s, t) \) is of the Schwartz class (with respect to \( s \in \mathbb{R} \)) then so is \( \tilde{f}(\zeta, t') e^{-i\xi(t-t')} \), so that \( (\partial_t - i\partial_x^2)^{-m/2} f(s, t) \) will also be of the Schwartz class (with respect to \( s \in \mathbb{R} \)). Further, it is straightforward to show that \( (\partial_t - i\partial_x^2)^{-m/2} f(s, t) \) is continuous at \( t = 0 \).

Next, our aim is to define the operator \( (\partial_t - i\partial_x^2)^{-m/2} \) for tempered distributions \( f(s, t) \) such that \( \text{supp} f \subset [0, \infty) \). To this end, let us observe that the transpose \( ^t(\partial_t - i\partial_x^2)^{-m/2} \) is given by

\[ ^t(\partial_t - i\partial_x^2)^{-m/2} g(s, t) = \frac{1}{2\pi} \int d\zeta d\xi \ e^{i(s-\xi)\zeta} (\partial_t e^{-i\xi} g(s, t'))_{x=\xi}, \]

where \( ^t\partial_x^{-m/2} \) denotes the Weyl fractional integral. The domain of definition of this operator is evident. Now, for any \( g(s, t) \in \mathcal{F}(\mathbb{R} \times \mathbb{R}) \) with \( \text{supp} g \subset [0, \infty) \), the operation \( (\partial_t - i\partial_x^2)^{-m/2} f(s, t) \) for distributions \( f(s, t) \in \mathcal{F}^{\prime}(\mathbb{R} \times \mathbb{R}) \) with \( \text{supp} f \subset [0, \infty) \) can be defined by introducing a Schwartz class function \( g_1(s, t) \) such that it agrees with \( ^t(\partial_t - i\partial_x^2)^{-m/2} g(s, t) \) for \( t \in [0, \infty) \) so that

\[ \langle g(s, t), (\partial_t - i\partial_x^2)^{-m/2} f(s, t) \rangle = \langle ^t(\partial_t - i\partial_x^2)^{-m/2} g(s, t), f(s, t) \rangle = \langle g_1(s, t), f(s, t) \rangle. \]

Therefore, \( (\partial_t - i\partial_x^2)^{-m/2} f(s, t) \) is also tempered such that \( \text{supp} (\partial_t - i\partial_x^2)^{-m/2} f(s, t) \subset [0, \infty) \). Note that any function of the tangential variable, \( s \), can be extended periodically on the whole line. Thus periodic functions being a tempered distribution can be easily included in the domain of definition of \( (\partial_t - i\partial_x^2)^{-m/2} \). It is interesting to note that by applying the Leibniz formula for the fractional integrals one can obtain local approximation of the ABCs with respect to \( s \):
The second family of various order ABCs are obtained under high-frequency assumption with respect to the temporal frequency. These are given by

**ABC}_1b:**

\[
\partial_n u + e^{-i\pi/4} e^{i\Phi} \partial_i e^{-i\Phi} u = 0. \tag{78}
\]

**ABC}_2b:**

\[
\partial_n u + e^{-i\pi/4} e^{i\Phi} \partial_i e^{-i\Phi} u + \frac{1}{2} \kappa u \\
- \frac{1}{2} e^{i\pi/4} \left( \frac{k^2}{4} + \partial_i^2 \right) e^{i\Phi} \partial_i^{-1/2} e^{-i\Phi} u = 0. \tag{79}
\]

**ABC}_3b:**

\[
\partial_n u + e^{-i\pi/4} e^{i\Phi} \partial_i e^{-i\Phi} u + \frac{1}{2} \kappa u \\
- \frac{1}{2} e^{i\pi/4} \left( \frac{k^2}{4} + \partial_s^2 \right) e^{i\Phi} \partial_i^{-1/2} e^{-i\Phi} u \\
+ i \left( \frac{k^3 + \partial_s^2 \kappa}{4} - \partial_s \Phi \right) \partial_i \partial_s \partial_i^{-1} e^{-i\Phi} u = 0. \tag{80}
\]

1. **Stability and uniqueness**

In order to study the stability property of the solution of the IVP defined by (67) with boundary condition ABC}_1a and ABC}_2a, respectively, we start with the relation:

\[
\begin{align*}
\forall u(x, T)|_{\partial \Omega} = |u_0(x)|_{\partial \Omega} = 2 \Re \int_0^T dt \int_{\Gamma} (u^* \nabla u) \cdot d\zeta. \tag{81}
\end{align*}
\]

Realization of the boundary operators requires an appropriate Fourier representation with respect to the tangential variable, s. To this end, one may either employ the Fourier series representation by extending the field periodically for all \(s \in \mathbb{R}\) or Fourier transform representation by extending the field to all \(s \in \mathbb{R}\) by setting it zero outside \(\Gamma\). The result for the first order ABCs, ABC}_1a, can be obtained by observing that the boundary integral

\[
I_1 = -e^{i\pi/4} \int_0^T dt \int_{\Gamma} (ue^{-i\Phi}) \partial_t - i\partial_s^2 (ue^{-i\Phi}) ds, \tag{82}
\]

satisfies \(\Re I_1 \leq 0\) so that

\[
\|u(x, T)\|_{L^2(\Omega)} \leq \|u_0(x)\|_{L^2(\Omega)}, \tag{83}
\]

For the second order ABCs, ABC}_2a, the energy estimate cannot be obtained for a general potential function. A special case of interest is when \(\partial_s \Phi = 0\) so that ABC}_2a is given by

\[
\partial_n u + e^{-i\pi/4} e^{i\Phi} (\partial_t - i\partial_s^2)^1/2 e^{-i\Phi} u = \frac{1}{2} \kappa u \\
+ \frac{1}{2} \kappa e^{i\Phi} (\partial_t - i\partial_s^2)^{-1} \partial_s^2 (ue^{-i\Phi}) = 0. \tag{84}
\]

Define the boundary integrals

\[
I_2 = -\frac{i}{2} \int_0^T dt \int_{\Gamma} (\kappa(s))|u|^2 ds, \tag{85}
\]

\[
I_3 = \frac{1}{2} \int_0^T dt \int_{\Gamma} (\kappa(s)(ue^{-i\Phi}) (\partial_t - i\partial_s^2)^{-1} \partial_s^2 (ue^{-i\Phi}) ds.
\]

If it follows that \(\Re I_2 = 0\). Define the symbol \(\sigma_p = (1/2)\kappa(s)(i\hat{\zeta} + \hat{\zeta}^2)^{-1}(-\hat{\zeta}^2)\) so that the symbol for the adjoint operator \(\sigma_{p^*}\) works out to be

\[
\sigma_{p^*} \sim -\frac{i}{2} \sum_{k \in \mathbb{Z}} \frac{1}{k! \kappa^k} (\partial_s^k \kappa) \partial_s^k \left( \frac{\kappa^2}{\xi + \zeta^2} \right). \tag{86}
\]

Let \(2Q = P + P^*\) so that

\[
2\sigma_Q \sim \frac{i}{2} \frac{\kappa \zeta^2}{\xi + \zeta^2} + \frac{i}{2} \sum_{k \in \mathbb{Z}} \frac{1}{k! \kappa^k} (\partial_s^k \kappa) \partial_s^k \left( \frac{\kappa^2}{\xi + \zeta^2} \right) + \ldots,
\]

and putting \(\psi = ue^{-i\Phi}\), we have

\[
\Re I_3 = \frac{1}{(2\pi)^2} \int d\zeta d\xi ds X, X_1(\psi(s), t) \sigma_Q(s, \xi, \zeta) X_1(\psi(s), t)e^{-i\hat{\zeta}s}. \tag{87}
\]

From the asymptotic expansion, to the zeroth order, we have \(\Re I_3 \approx 0\) (for constant curvature boundary, this result is exact). The energy estimate can thus be approximately established for the special case when \(\partial_s \Phi = 0\).

For the ABCs obtained in the high-frequency approximation, it is evident that the first order ABC, ABC}_1b, satisfies the energy estimate. For the higher-order ABCs, one requires an additional conditions, \(\partial_s \Phi = 0\) in order to obtain the energy estimate. In ABC}_2a, the term with the factor \(\kappa/2\) can be ignored.
as it leads to a purely imaginary quantity. Putting $\psi = u e^{i\phi}$, consider the following boundary integrals

$$I_1 = - \int_0^T dt \int_\Gamma \psi'((s, t)[e^{i\pi/4}\partial_t^1]^{1/2} + \frac{1}{2} e^{-i\pi/4}\partial_t^{-1/2}]\psi(s, t)ds,$$

$$I_2 = - \frac{1}{8} e^{-i\pi/4} \int_0^T dt \int_\Gamma \psi'((s, t)[e^{i\pi/4}\partial_t^{-1/2}]\psi(s, t)ds. \tag{89}$$

The first integral can be dealt with in the manner done before. The second integral can be dealt with in the manner described in the appendix. Defining $\sigma_P = -e^{-i\pi/4}\kappa(-\xi)^{-1/2}$ so that $\sigma_{P'} = -e^{i\pi/4}\kappa(-\xi)^{-1/2}$. Putting $2Q = P + P'$, we have $\sigma_Q = -\kappa^2 \cos[\pi/4 + \pi \text{sgn}(\xi)/4]$. The boundary integral can now be written as

$$\Re I_2 = - \frac{1}{16\pi} \int_0^T \int_\Gamma \partial_s \psi(s, t)[\kappa^2 \partial_t^{-1/2} \psi(s, t)]ds$$

so that $\Re I_2 \leq 0$. For $ABC_{3b}$, we define the following boundary integrals

$$I_3 = \frac{1}{8} \int_0^T dt \int_\Gamma \psi'((s, t)[(\kappa^3 + \partial_t^2\kappa)\partial_t^{-1}]\psi(s, t)ds,$$

$$I_4 = \frac{1}{2} \int_0^T dt \int_\Gamma \psi'((s, t)[\kappa\partial_t\partial_s\partial_t^{-1}]\psi(s, t)ds, \tag{91}$$

$$I_5 = - \frac{1}{4} \int_0^T dt \int_\Gamma \psi'((s, t)[\partial_t\partial_s\partial_t^{-1}]\psi(s, t)ds.$$

Defining $\sigma_P = (\kappa^3 + \partial_t^2\kappa)(-\xi)^{-1}$ so that $\sigma_Q = (\kappa^3 + \partial_t^2\kappa)\xi^{-1} \cos[\pi \text{sgn}(\xi)/4]$. From here it follows that $I_3$ is purely imaginary. Carrying out an integration by parts in $I_4$ with respect to $s$, we have

$$I_4 = - \frac{1}{2} \int_0^T dt \int_\Gamma \partial_t\psi((s, t))\partial_t^{-1}\partial_t\psi(s, t)ds$$

$$= - \frac{1}{2\pi} \int_0^T dt \int_\Gamma \kappa(\xi)^{-1}\partial_t\psi(s, t)ds. \tag{92}$$

Therefore, $I_4$ is purely imaginary. The discussion of the last integral is more involved. Define the symbol $\sigma_P = -(\partial_t\phi)(-\xi)^{-1}$ so that the symbol for the adjoint operator $\sigma_{P'}$ works out to be

$$\sigma_{P'} \sim - \sum_{k \neq 0} \frac{1}{k!1!k!} \partial_t^k \partial_s \phi \partial_t^{1-k}(-\xi)^{-1}. \tag{93}$$

Now

$$2\sigma_Q \sim -(\partial_t\phi)(\xi)^{-1} - \sum_{k \neq 0} \frac{1}{k!1!k!} \partial_t^k \partial_s \phi \partial_t^{1-k}(-\xi)^{-1}$$

$$= -(\partial_t\phi)(\xi)^{-1} + \ldots. \tag{94}$$

Therefore, the contribution from this last integral can be ignored on account of the lower order leading term in the above asymptotic expansion. Thus the energy estimate

$$||u(x, T)||_{L^2(\Gamma)}^2 \leq ||u_0(x)||_{L^2(\Gamma)}^2 \tag{95}$$

can be established for the ABC-family. ABC_{1b}, j = 1, 2, 3.

### B. Domains with straight boundary: infinite strip

The ABCs for the straight boundary can be written by setting the curvature $\kappa$ to zero.

**ABC_{1a}**: 

$$\partial_n u + e^{-i\pi/4} e^{i\phi} (\partial_t - i\partial_t^2)^{-1/2} e^{-i\phi} u = 0. \tag{96}$$

**ABC_{2a}**: 

$$\partial_n u + e^{-i\pi/4} e^{i\phi} (\partial_t - i\partial_t^2)^{-1/2} e^{-i\phi} u$$

$$+ e^{-i\pi/4} \Phi e^{i\phi}(\partial_t - i\partial_t^2)^{-1/2} \partial_t(e^{-i\phi} u) = 0. \tag{97}$$

Along the direction in which the strip extends to infinity, we impose the periodic boundary condition. Note that an exact representation of the boundary operators is possible in this case which is based on the observations made in earlier sections. The energy estimate for the first order ABCs is easy to obtain; however, for the second order ABCs this result is not available. The high-frequency ABCs work out to be

**ABC_{1b}**: 

$$\partial_n u + e^{-i\pi/4} e^{i\phi} \partial_t e^{-i\phi} u = 0. \tag{98}$$

**ABC_{2b}**: 

$$\partial_n u + e^{-i\pi/4} e^{i\phi} \partial_t e^{-i\phi} u$$

$$- \frac{1}{2} e^{-i\pi/4} \partial_t^2(e^{i\phi} \partial_t^{-1/2} e^{-i\phi} u) = 0. \tag{99}$$

**ABC_{3b}**: 

$$\partial_n u + e^{-i\pi/4} e^{i\phi} \partial_t e^{-i\phi} u$$

$$- \frac{1}{2} e^{-i\pi/4} \partial_t^2(e^{i\phi} \partial_t^{-1/2} e^{-i\phi} u) - \frac{\text{i}}{4} \partial_t \Phi e^{i\phi} \partial_t^{-1} e^{-i\phi} u = 0. \tag{100}$$

The energy estimate for the general case is not available for such ABCs.

### C. Rectangular domains: corner conditions

Continuing with the rectangular domain as defined in Section 11B, let us consider the possibility of extending the results.

---

4 Only the second and third order ABCs require $\partial_t \phi = 0$ in order to establish the energy estimate.
obtained in Section II B 1 to the nonlinear/variable potential case. We confine our attention to the high-frequency ABCs only. We demonstrate the possibility of constructing the corner condition at the corner defined by \( \Gamma_r \cap \Gamma_t \). Consider the ABC\(_{2b}\) given by

\[
\begin{align*}
\partial_x u + e^{-ix/4} e^{i\Phi} \frac{\partial}{\partial_t} e^{-i\Phi} u \\
- \frac{1}{2} e^{ix/4} \frac{\partial}{\partial_x} \left( e^{i\Phi} \frac{\partial}{\partial_t} e^{-i\Phi} u \right) = 0,
\end{align*}
\]

(101)

\[
\begin{align*}
\partial_x u + e^{-ix/4} e^{i\Phi} \frac{\partial}{\partial_t} e^{-i\Phi} u \\
- \frac{1}{2} e^{ix/4} \frac{\partial}{\partial_x} \left( e^{i\Phi} \frac{\partial}{\partial_t} e^{-i\Phi} u \right) = 0,
\end{align*}
\]

(102)

Let us consider the weak formulation of the IVP defined by

\[
\begin{align*}
i \partial_t u + \Delta u + \phi u = 0, \quad (x, t) \in \Omega_t \times \mathbb{R}_+, \\
u(x, 0) = u_0(x), \quad x \in \Omega, \quad \text{with} \quad u_0(x) \subset \Omega.
\end{align*}
\]

(103)

Consider the test function \( \psi(x) \in H^1(\Omega) \) so that

\[
\int_\Omega (i \partial_t u + \nabla^2 u + \phi u) \psi d^2 x = \int_\Omega [i \partial_t u - (\nabla \psi) + \phi u] d^2 x + \int_{\Gamma_t} \psi(\nabla u) \cdot d\gamma.
\]

(104)

Let us consider the top and right boundaries. The boundary integrals are given by

\[
\begin{align*}
\int_{1x + 2x} \psi_{\partial_x} (e^{i\Phi} \frac{\partial}{\partial_t} e^{-i\Phi} u) \bigg|_{x_2 = x_1} - \int_{1x} (\partial_x \psi) \partial_x (e^{-i\Phi} \frac{\partial}{\partial_t} e^{-i\Phi} u) d x_1.
\end{align*}
\]

(105)

From here it is evident that the corner condition must provide the value of the following expression at \( \Gamma_r \cap \Gamma_t \):

\[
\begin{align*}
\partial_x (e^{i\Phi} \frac{\partial}{\partial_t} e^{-i\Phi} u) + \partial_x (e^{i\Phi} \frac{\partial}{\partial_t} e^{-i\Phi} u) \\
= i(\Phi_{x_1} + \Phi_{x_2}) e^{i\Phi} \frac{\partial}{\partial_t} e^{-i\Phi} u - i e^{i\Phi} \frac{\partial}{\partial_t} e^{i\Phi} u - i e^{i\Phi} \frac{\partial}{\partial_t} e^{-i\Phi} u + e^{i\Phi} \frac{\partial}{\partial_t} e^{-i\Phi} u.
\end{align*}
\]

(106)

For the linear case with variable potential, the last term in the above equation must be computed from a corner condition. However, for the non-linear case, \( \Phi \) is supposed to be dependent on some known field while our final intent is to restore its nonlinear dependence. In this light, the above equation cannot be made free of the derivatives of \( u \) at the corner as the equation is nonlinear. However, we may derive a condition at the corner which can be combined with the ABCs and eventually be solved by an iterative scheme. Putting \( u = \psi e^{i\Phi} \) in the evolution equation (103), we have

\[
\begin{align*}
i \partial_t \psi + \Delta \psi + 2i(\nabla \Phi) \cdot (\nabla \psi) + (e^{i\Phi} \Delta e^{i\Phi}) \psi = 0.
\end{align*}
\]

(107)

Carrying out the operation \( e^{i\Phi} \frac{\partial}{\partial_t} e^{-i\Phi} \) on both side of the equation above, we have

\[
\begin{align*}
i e^{i\Phi} \frac{\partial}{\partial_t} e^{-i\Phi} \psi + e^{i\Phi} \frac{\partial}{\partial_t} e^{-i\Phi} \Delta \psi + 2 e^{i\Phi} \frac{\partial}{\partial_t} e^{-i\Phi} (i \nabla \Phi) \cdot (\nabla \psi) + e^{i\Phi} \frac{\partial}{\partial_t} e^{-i\Phi} (e^{i\Phi} \Delta e^{i\Phi}) \psi = 0, \\
i e^{i\Phi} \frac{\partial}{\partial_t} e^{-i\Phi} \psi + e^{i\Phi} \frac{\partial}{\partial_t} e^{-i\Phi} \Delta \psi + 2 e^{i\Phi} (i \nabla \Phi) \cdot (\nabla \psi) + (\Delta e^{i\Phi}) \frac{\partial}{\partial_t} e^{-i\Phi} \psi + \ldots = 0.
\end{align*}
\]

(108)

This equation combined with the ABCs gives the following corner condition

\[
\begin{align*}
\text{CC}_1 : \partial_x u + \partial_x u + \frac{3}{2} e^{-ix/4} e^{i\Phi} \frac{\partial}{\partial_t} e^{-i\Phi} u = 0,
\end{align*}
\]

(110)

or, equivalently,

\[
\begin{align*}
\text{CC}_1 : e^{i\Phi} \frac{\partial}{\partial_t} e^{-i\Phi} (\partial_x u + \partial_x u) + \frac{3}{2} e^{-ix/4} u = 0.
\end{align*}
\]

(111)
Similarly, for ABC_{3b} one has the following corner condition
\[
CC_2 : \partial_{x_3} u + \partial_{x_3} u + \frac{3}{2} e^{-i\pi/4} e^{i\phi} \partial_t^{1/2} e^{-i\phi} u \\
- \frac{i}{4} \partial_{x_3} \phi + \frac{i}{4} e^{i\phi} \partial_t^{-3/2} e^{-i\phi} u = 0 \mod (\partial_t^{-5/2} e^{-i\phi} u). \tag{112}
\]
or, equivalently,
\[
CC_2 : e^{i\phi} \partial_t^{-1/2} e^{-i\phi} (\partial_{x_3} u + \partial_{x_3} u) + \frac{3}{2} e^{-i\pi/4} u \\
- \frac{i}{4} \partial_{x_3} \phi + \frac{i}{4} e^{i\phi} \partial_t^{-3/2} e^{-i\phi} u = 0 \mod (\partial_t^{-5/2} e^{-i\phi} u). \tag{113}
\]

D. Special case: \( \phi = \phi(t) \)

For time-dependent potentials with no spatial variation, the quantity \( \Phi \) is purely time-dependent and the ABCs for different domains types can be simplified considerably. It must be remarked that the exact form of the transparent boundary condition is only obtainable for an infinite-strip with periodic boundary condition in the unbounded direction or rectangular domains. At the appropriate segments of the boundary, it reads as
\[
\partial_{x} u + e^{-i\pi/4} e^{i\phi} (\partial_{t} - i \partial_{x}^{2})^{1/2} e^{-i\phi} u = 0. \tag{114}
\]
For rectangular domains, we consider this problem is more detail. At the boundary \( \Gamma_r \), we have
\[
\partial_{x} u + e^{-i\pi/4} e^{i\phi} (\partial_{t} - i \partial_{x}^{2})^{1/2} e^{-i\phi} u = 0. \tag{115}
\]

The auxiliary function, \( \varphi(x_1, x_2, t, t') \) as defined in Section II B in the present case is given by
\[
\mathcal{F}_x \{ \varphi(x_1, x_2, t, t') \} = e^{-i\xi_1^2 (t-t') - i\phi(t')} \mathcal{F}_x \{ u(x_1, x_2, t') \}, \tag{116}
\]
so that \( \varphi(x_1, x_2, t, t') = u(x_1, x_2, t)e^{-i\phi(t)} \). Putting \( \tilde{u}_0(\zeta) = \mathcal{F}_x \{ u(x_1, x_2, t) \} \), we have
\[
\mathcal{F}_x \{ \varphi(x_1, x_2, t, t') \} \approx e^{-i\xi_1^2 + \xi_2^2} \tilde{u}_0(\zeta), \\
\varphi(x_1, x_2, t, t') = \int_{\mathbb{R}^2} e^{i\xi_1 x_1 - i\xi_2 x_2} \tilde{u}_0(\zeta) d^2 \zeta. \tag{117}
\]
From here is follows that the IVPs satisfied by this auxiliary field is not different from that described in Section II B.

IV. CONCLUSION

In this paper we have discussed the formulation of the operator \((\partial_t - i\partial_x)^{\alpha}\), \(\alpha = 1/2, -1/2, -1, \ldots \), in terms of the fractional operators. This allows the TBCs/ABCs for the free Schrödinger equation and general Schrödinger equation formulated on various types of computational domains to be expressed in a natural way. In particular, two families of ABCs are studied in this paper: first obtained with the standard pseudo-differential approach and the second one obtained as the high-frequency approximation of the former. For the rectangular domains, we have developed various order corner conditions for the family of ABCs obtained in the high-frequency approximation. Each of these families of ABCs (along with corner conditions) are also investigated for stability and uniqueness of the solution of the resulting initial-boundary value problem. The discussion of the time-discrete version of the TBCs/ABCs is beyond the scope of this paper; this investigation is in progress and it will be published in a forthcoming paper along with the numerical results.

Appendix A: Some properties of pseudo-differential operators

Let us consider the symbol space \( S^m_M(Y \times \mathbb{R}^n) \) of \( M \)-quasi homogeneous symbols [14] where \( Y \) is an open subset of \( \mathbb{R}^n \) and \( M = (\mu_1, \mu_2, \ldots, \mu_n) \) is an \( n \)-tuple of numbers \( \mu_i > 0 \). Let \( P \) be a pseudo-differential operator with the symbol \( p(y, \zeta) \in S^m_M(Y \times \mathbb{R}^n) \) so that
\[
Pu(y) = \int p(y, \zeta)e^{i\xi \cdot \zeta} \tilde{u}(\zeta)d^n \zeta, \tag{A1}
\]
where \( u(y) \in C^\infty(Y) \) and \( d\zeta = d\zeta_1d\zeta_2 \ldots d\zeta_n, d\xi = dy_1dy_2 \ldots dy_n \). The adjoint of this operator, denoted by \( P^* \), can be defined as
\[
P^*u(y) = (2\pi)^{-n} \int p^*(y', \zeta)e^{-i\xi \cdot \zeta} u(y')dy'd\zeta, \tag{A2}
\]
This operator belongs to a more general class of pseudo-differential operators defined by
\[
Pu(y) = \int p(y, y', \zeta)e^{i\xi \cdot (y-y')} u(y')dy'd\zeta, \tag{A3}
\]
where the symbol \( p(y, y', \zeta) \in C^\infty(Y \times Y \times \mathbb{R}^n) \) lies in \( S^m_M(Y \times Y \times \mathbb{R}^n) \). The adjoint of this operator is defined by the symbol
\[
p^*(y, y', \zeta) = p^*(y', y, \zeta). \tag{A4}
\]
Note that the primed variable is to be integrated over. These new operators do not have unique symbols but they do admit of a representation in terms of the former kind of operators as \( P = OP(\sigma P(y, \zeta)) + R \) where \( \sigma P(y, \zeta) \in S^m_M(Y \times \mathbb{R}^n) \) and \( R \) is an operator with kernel \( K_R(y, y') \in C^\infty(Y \times Y) \) such that
\[
\sigma_p(y, \zeta) - \sum_{a \in \mathcal{P}^\eta, |a| < N - 1} \frac{1}{a!} \partial_y^a \partial_{\zeta}^a [\sigma_p(y, y', \zeta)]_{y' = y}, \quad (A5)
\]

where \( N > 0 \) and \( \mu \) is smallest element of \( M \). The relationship in equation (A3) defines the asymptotic expansion of the symbol and we write

\[
\sigma_p(y, \zeta) \sim \sum_{a \in \mathcal{P}^\eta} \frac{1}{a!} \partial_y^a \partial_{\zeta}^a [\sigma_p(y, y', \zeta)]_{y' = y}, \quad (A6)
\]

This determines \( \sigma_p(y, \zeta) \) only up to a smoothing operator. The formula expressing \( \sigma_p(y, \zeta) \) in terms of \( \sigma^\ast_p(y', \zeta) \) can be obtained by writing

\[
p^\ast(y', y, \zeta) - \sigma^\ast_p(y', \zeta) \in \mathcal{S}_M^{\infty}(Y \times Y \times \mathbb{R}^n), \quad (A7)
\]

and using the asymptotic expansion (A6)

\[
\sigma^p_p(y, \zeta) \sim \sum_{a \in \mathcal{P}^\eta} \frac{1}{a!} \partial_y^a \partial_{\zeta}^a [\sigma_p(y, y', \zeta)]_{y' = y}, \quad (A8)
\]

where \( R \) being a smoothing operator does not show up in the asymptotic expansion. The adjoint can be used to write the Fourier transform of \( Pu(y) \) by noticing that \( (P^\dagger)_y = P \), so that

\[
Pu(y) = (2\pi)^{-n} \int \left( \int \sigma^p_p(y', \zeta)e^{-i\zeta \cdot y'}u(y')d\zeta \right)e^{i\zeta \cdot y}d\zeta. \quad (A9)
\]

Consider the inner product defined by \( \langle u|v \rangle = \int u^\ast v dy \). An expression of the form \( \mathbb{R} \langle u|Pu \rangle \) arises in establishing the stability of the ABCs. This can be computed by observing

\[
2\mathbb{R} \langle u|Pu \rangle = \langle u|Pu \rangle + \langle u|P^\dagger u \rangle. \quad (A10)
\]

Define \( 2Q = (P + P^\dagger) \) and using Plancherel’s theorem, we have

\[
\mathbb{R} \langle u|Pu \rangle = (2\pi)^{-n} \int d\zeta d\zeta' \bar{u}(\zeta) \sigma_Q(y', \zeta)u(y')e^{-i\zeta \cdot y'}. \quad (A11)
\]

If \( \sigma_Q(y, \zeta) \) is independent of \( y \), then

\[
\mathbb{R} \langle u|Pu \rangle = (2\pi)^{-n} \int d\zeta |\bar{u}(\zeta)|^2 \sigma_Q(\zeta). \quad (A12)
\]

The sign of this expression can solely be decided by the sign of \( \sigma_Q(\zeta) \). If \( \sigma_Q(y, \zeta) = \phi(y)\sigma(\zeta) \) where \( \zeta = (\zeta_2, \zeta_3, \ldots, \zeta_n) \in \mathbb{R}^{n-1} \) and \( \zeta = (\zeta_2, \zeta_3, \ldots, \zeta_n) \in \mathbb{R}^{n-1} \) then

\[
\mathbb{R} \langle u|Pu \rangle = (2\pi)^{-(n-1)} \int dy_1 d\zeta |\bar{u}(y_1, y)|^2 \phi(y_1)\sigma(\zeta). \quad (A13)
\]

On account of the ambiguity in the knowledge of the exact symbol, the conclusion remains valid only up to an infinitely smoothing operator (except for the special cases where the symbol is of principle type).

- Fractional operators with symbol \( p(t, \xi) = \eta(i\xi)^\alpha \) (where \( \eta \in \mathbb{R} \) with covariable \( \xi \in \mathbb{R} \setminus \{0\} \)):

\[
\sigma_Q(\xi) \sim \frac{1}{2}[\eta(i\xi)^\alpha + \eta^\ast(-i\xi)^\alpha] = |\eta||\xi|^\alpha \cos \left[ \frac{\pi \alpha}{4} \text{sgn}(\xi) + \arg \eta \right]. \quad (A14)
\]

- Operators with symbol \( p(x, t, \zeta, \xi) = \eta(i\xi + i\zeta)^\alpha \) (where \( (x, t) \in \mathbb{R}^2 \) with covariables \( (\zeta, \xi) \in \mathbb{R}^2 \setminus \{(\zeta, \xi) \in \mathbb{R}^2 : \zeta + \xi^2 = 0\} \)):

\[
\sigma_Q(\xi, \zeta) \sim \frac{1}{2}[\eta(i\xi + i\zeta)^\alpha + \eta^\ast(-i\xi - i\zeta)^\alpha] = |\eta||\xi + \zeta|^\alpha \cos \left[ \frac{\pi \alpha}{4} \text{sgn}(\xi + \zeta^2) + \arg \eta \right]. \quad (A15)
\]

- Let \( \sigma_p = \eta \phi(x)(i\xi)^\alpha \) with real valued function \( \phi(x) > 0, \forall x \in \mathbb{R} \) where the meaning of the variables is same as that of the last example. Then

\[
\sigma_Q(x, t, \zeta, \xi) \sim \frac{1}{2}[i\phi(x)(i\xi)^\alpha + \phi(x)(-i\xi)^\alpha] = |\eta|\phi(x)|\xi|^\alpha \cos \left[ \frac{\pi \alpha}{4} \text{sgn}(\xi) + \arg \eta \right], \quad (A16)
\]

so that

\[
\mathbb{R} \langle u|Pu \rangle = |\eta| \int d\xi d\xi' \mathcal{F}[u(x, t)](x, \xi)|^2 \phi(x)|\xi|^\alpha \cos \left[ \frac{\pi \alpha}{4} \text{sgn}(\xi) + \arg \eta \right]. \quad (A17)
\]

In all the above cases, when \( \alpha < 1 \) and \( \arg \eta = \pi/4 \), it is easy to show that the sign of \( \sigma_Q \) remains fixed. This case is treated exactly in the main body of the paper for the aforementioned operators without resorting to the properties of the pseudo-
differential operators (i.e. the ambiguity resulting from the lack of knowledge of the exact symbol is circumvented).

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