KINEMATIC MODELING OF THE MILKY WAY USING THE RAVE AND GCS STELLAR SURVEYS

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ABSTRACT

We investigate the kinematic parameters of the Milky Way disk using the Radial Velocity Experiment (RAVE) and Geneva–Copenhagen Survey (GCS) stellar surveys. We do this by fitting a kinematic model to the data and taking the selection function of the data into account. For stars in the GCS we use all phase-space coordinates, but for RAVE stars we use only ($l$, $b$, $v_{hel}$). Using the Markov Chain Monte Carlo technique, we investigate the full posterior distributions of the parameters given the data. We investigate the age–velocity dispersion relation for the three kinematic components ($\sigma_R$, $\sigma_\phi$, $\sigma_z$), the radial dependence of the velocity dispersions, the solar peculiar motion ($U_\odot$, $V_\odot$, $W_\odot$), the circular speed $\Theta_0$ at the Sun, and the fall of mean azimuthal motion with height above the midplane. We confirm that the Besançon-style Gaussian model accurately fits the GCS data but fails to match the details of the more spatially extended RAVE survey. In particular, the Shu distribution function (DF) handles noncircular orbits more accurately and provides a better fit to the kinematic data. The Gaussian DF not only fits the data poorly but systematically underestimates the fall of velocity dispersion with radius. The radial scale length of the velocity dispersion profile of the thick disk was found to be smaller than that of the thin disk. We find that correlations exist between a number of parameters, which highlights the importance of doing joint fits. The large size of the RAVE survey allows us to get precise values for most parameters. However, large systematic uncertainties remain, especially in $V_\odot$ and $\Theta_0$. We find that, for an extended sample of stars, $\Theta_0$ is underestimated by as much as 10% if the vertical dependence of the mean azimuthal motion is neglected. Using a simple model for vertical dependence of kinematics, we find that it is possible to match the Sgr A* proper motion without any need for $V_\odot$ being larger than that estimated locally by surveys like GCS.

Key words: galaxies: fundamental parameters – galaxies: kinematics and dynamics – methods: data analysis – methods: numerical – methods: statistical

Online-only material: color figures

1. INTRODUCTION

Understanding the origin and evolution of disk galaxies is one of the major goals of modern astronomy. The disk is a prominent feature of late-type galaxies like the Milky Way. As compared to distant galaxies, for which one can only measure the gross properties, the Milky Way offers the opportunity to study the disk in great detail. For the Milky Way, we can determine six-dimensional (6D) phase-space information, combined with photometric and stellar parameters, for a huge sample of stars. This has led to large observational programs to catalog the stars in the Milky Way in order to compare them with theoretical models.

The Milky Way stellar system is broadly composed of four distinct parts, although in reality there is likely to be considerable overlap between them: the thin disk, the thick disk, the stellar halo, and the bulge. In this paper, we mainly concentrate on understanding the disk components, which are the dominant stellar populations.

In the Milky Way, the thick disk was originally identified as the second exponential required to fit vertical star counts (Gilmore & Reid 1983; Reid & Majewski 1993; Jurić et al. 2008). Thick disks are also ubiquitous features of late-type galaxies (Yoachim & Dalcanton 2006). However, whether the thick disk is a separate component with a distinct formation mechanism is highly debatable and a difficult question to answer.

Since the Gilmore & Reid (1983) result, various attempts have been made to characterize the thick disk. Some studies suggest that thick-disk stars have distinct properties: they are old and metal poor (Chiba & Beers 2000) and $\alpha$ enhanced
(Fuhrmann 1998; Bensby et al. 2005, 2003). Jurić et al. (2008) fit the Sloan Digital Sky Survey (SDSS) star counts using a two-component model and find that the thick disk has a larger scale length than the thin disk. In contrast, Bovy et al. (2012d), using a much smaller sample of SDSS and SEGUE stars, find the opposite when they associate the thick disk with the \( \alpha \)-enhanced component. Finally, the idea of a separate thick disk has recently been challenged. Schönrich & Binney (2009a, 2009b) argued that chemical evolutionary models with radial migration and mixing can replicate the properties of the thick disk (see also Loebman et al. 2011, who explore radial mixing using \( N \)-body simulations). Ivezić et al. (2008) do not find the expected separation between metallicity and kinematics for F and G stars in SDSS, and Bovy et al. (2012b, 2012c) argue that the thick disk is a smooth continuation of the thin disk.

Opinions regarding the formation of a thick disk are equally divided. Various mechanisms have been proposed: accretion of stars from disrupted galaxies (Abadi et al. 2003), heating of disks divided. Various mechanisms have been proposed: accretion of the thick disk is a smooth continuation of the thin disk. and G stars in SDSS, and Bovy et al. (2012b, 2012c) argue that expected separation between metallicity and kinematics for F migration and mixing can replicate the properties of the thick disk using \( N \)-body simulations. Ivezic et al. (2008) do not find the expected separation between metallicity and kinematics for F and G stars in SDSS, and Bovy et al. (2012b, 2012c) argue that the thick disk is a smooth continuation of the thin disk.

The obvious way to test the different thick-disk theories is to compare the kinematic and chemical abundance distributions of the thick-disk stars with those of different models. Since the thin- and thick-disk stars strongly overlap in both space and kinematics, it is difficult to separate them using just position and velocity. To really isolate and study the thick disk, one needs a tag that stays with a star throughout its life. Age is a possible tag, but it is difficult to get reliable age estimates of stars. Chemical composition is another promising tag that can be used, but this requires high-resolution spectroscopy of a large number of stars. In the near future, surveys such as GALAH using the HERMES spectrograph (Freeman & Bland-Hawthorn 2008) and the Gaia–ESO survey using the FLAMES spectrograph (Gilmore et al. 2012) should be able to fill this void. In our first analysis, we restrict ourselves to a differential kinematic study of the disk components. We plan to treat the disk components separately at each spatial location, and the gravitational field cause stars to diffuse through phase space to regions of lower phase-space density. The fluctuations arise from several sources, including giant molecular clouds (GMCs), spiral arms, a rotating bar, and halo objects that come close to the disk. One approach to computing the consequences of these processes is \( N \)-body simulation, but stellar disks are notoriously tricky to simulate accurately, with the consequence that reliable simulations are computationally costly. In particular, they are too costly for it to be feasible to find a simulation that provides a good fit to a significant body of observational data. Instead, we characterize the properties of the Milky Way disk by fitting a suitable analytical formula. The formula summarizes large amounts of data, but its usefulness extends beyond this. The formula is traditionally taken to be a power law in age (although see Edvardsson et al. 1993; Quillen & Garnett 2001; Seabroke & Gilmore 2007). The exponents \( \beta_R \), \( \beta_\theta \), and \( \beta_z \) of these power laws may not be the same for all three components. The ratio \( \sigma_z/\sigma_R \) and the values of \( \beta_R \), \( \beta_\theta \), and \( \beta_z \) are useful for understanding the physical processes responsible for heating the disk (e.g., Binney 2013; Sellwood 2013).

The first generation of stellar population models characterized the density distribution of stars using photometric surveys. Bahcall & Soneira (1980a, 1980b, 1984) assumed an exponential disk with magnitude-dependent scale heights. An evolutionary model using population synthesis techniques was presented by Robin & Creze (1986). Given a star formation rate (SFR) and an initial mass function (IMF), one calculates the resulting stellar populations using theoretical evolutionary tracks. The important step forward was that the properties of the disk, like scale height, density laws, and velocity dispersions were assumed to be a function of age rather than being color–magnitude–dependent terms. Bienayme et al. (1987) later introduced dynamical self-consistency to link disk scale and vertical velocity dispersions via the gravitational potential. Haywood et al. (1997a, 1997b) further improved the constraints on SFR and IMF of the disk. The present state of the art is described in Robin et al. (2003) and is known as the Besançon model. Here the disk is constructed from a set of isothermal populations that are assumed to be in equilibrium. Analytic functions for the density distribution, age–metallicity relation (AMR), and IMF are provided for each population. A similar scheme is also used by the codes TRILEGAL (Girardi et al. 2005) and Galaxia (Sharma et al. 2011).

There is a crucial distinction between kinematic and dynamical models. In a kinematic model, one specifies the stellar motions independently at each spatial location, and the gravitational field in which the stars move plays no role. In a dynamical model, the spatial density distribution of stars and their kinematics are self-consistently linked by the potential, under the assumption that the system is in steady state. If one has expressions for three constants of stellar motion as functions of position and velocity, dynamical models are readily constructed via Jeans’s theorem. Binney (2012b) provides an algorithm for evaluating approximate action integrals and has used these to fit dynamical models to the Geneva–Copenhagen Survey (GCS) data (Binney 2012b). Binney et al. (2014) have confronted the predictions of the best of these models with Radial Velocity Experiment (RAVE) data and shown that the model is remarkably, but not perfectly, successful. Our approach is different in two key respects: we fit kinematic rather than dynamical models, and we avoid adopting distances to, or using proper motions of, RAVE stars.
Large photometric surveys such as DENIS (Epchtein et al. 1999), Two Mass All Sky Survey (2MASS) (Skrutskie et al. 2006), and SDSS (Abazajian et al. 2009) provide the underpinning for all Galaxy modeling efforts. SDSS has been used to provide an empirical model of the Milky Way stars (Jurić et al. 2008; Ivezić et al. 2008; Bond et al. 2010). The Besançon model was fitted to the 2MASS star counts, and its photometric parameters have been more thoroughly tested than its kinematic parameters because kinematic data for a large number of stars were not available when the model was constructed.

The Hipparcos satellite (Perryman et al. 1997) and the UCAC2 catalog (Zacharias et al. 2004) provided proper motions and parallaxes for ~10^5 stars in the solar neighborhood. Dehnen & Binney (1998b) used the Hipparcos data to study stellar kinematics as a function of color. They also determined the solar motion with respect to the local standard of rest (LSR) and the axial ratios of the velocity ellipsoid. Binney et al. (2000), also using Hipparcos stars, found the velocity dispersion to vary with function of age as \( \tau^{0.33} \). More recently, Aumer & Binney (2009), using data from a new reduction of the Hipparcos mission, estimated the solar motion and the AVR for all three velocity components. The AVR is assumed to be a power law in the Galaxy and provided analytic fits to the highly non-Gaussian distributions of \( v_R \). They also compared the observed kinematics of stars in different spatial bins with the predictions of a full dynamical model that had been fitted to the GCS data.

Stellar kinematics allow us to measure the peculiar motion \((U_\odot, V_\odot, W_\odot)\) of the Sun with respect to the LSR, and also the speed of the LSR (in other words, the circular speed at the location of the Sun, \( \Theta_0 = V_\odot(R_\odot) \)). There have been as many determinations of these as there have been new data, one of the earliest being \((U_\odot, V_\odot, W_\odot) = (9, 12, 7) \) km s\(^{-1}\) by Delhaye (1965). Very precise measurements of these have been extracted from the Hipparcos proper motions and the GCS survey. Dehnen & Binney (1998b) and Aumer & Binney (2009), using Hipparcos proper motions, got \((U_\odot, V_\odot, W_\odot) = (9.96 \pm 0.33, 5.25 \pm 0.54, 7.07 \pm 0.37) \) km s\(^{-1}\). A revision of \( V_\odot \) was suggested by Binney (2010) and McMillan & Binney (2010). Later Schönrich et al. (2010) explained why the previous estimates, which used colors as a proxy for age, gave incorrect results. Using a chemodynamical model calibrated on GCS data, they found \((U_\odot, V_\odot, W_\odot) = (11.1 \pm 0.72, 12.24 \pm 0.47, 7.07 \pm 0.36) \) km s\(^{-1}\). Schönrich (2012) described a model-independent method and suggests that \( U_\odot \) could be as high as 14 km s\(^{-1}\). As further evidence of an unsettled situation, Bovy et al. (2012a) find from a sample of 3500 APOGEE stars \( v_\odot = 218 \pm 6 \), \( V_\odot = 26 \pm 3 \), and \( U_\odot = 10.5 \) km s\(^{-1}\) and also suggest a revision of the LSR reference frame.

In this paper we refine the kinematic parameters of the Milky Way, using first a simple model based on Gaussian velocity distributions and then a model based on the Shu distribution function (DF). We explore the AVR, the radial gradient in dispersions, the solar motion, and the circular speed. A full exploration of this parameter space using Markov Chain Monte Carlo (MCMC) techniques has not been done before, even for a sample as small as the GCS.

The RAVE survey contains giants and dwarfs in roughly equal proportions, and it is hard to determine distances to giants. Moreover, many RAVE stars are sufficiently distant for the errors in their available, ground-based proper motions to give rise to errors in their tangential velocities that far exceed the small (~1 km s\(^{-1}\)) errors in their line-of-sight velocities. Hence, we choose not to use either distances or proper motions. Instead, we marginalize over these variables in addition to mass, age, and metallicity. When the velocity distribution is Gaussian, the marginalization over tangential velocity can be done analytically; in general, for other models, e.g., Shu DF models, the marginalization has to be done numerically, and it is computationally expensive.
Bovy et al. (2012a) recently used a similar procedure to fit models to 3500 APOGEE stars, but they did not investigate the AVR and considered only Gaussian models. In this paper we fit a kinematic model to 280,000 RAVE stars taking full account of RAVE’s photometric selection function. To handle the large data size, we introduce two new MCMC model-fitting techniques. Our aim is to encapsulate in simple analytical models the main kinematic properties of the Milky Way disk. Our results should be useful for making detailed comparison with simulations.

The paper is organized as follows. In Section 2 we introduce the analytic framework used to model the Galaxy (Sharma et al. 2011). The stellar content of the Galaxy is modeled as a set of distinct components: the thin disk, the thick disk, the stellar halo, and the bulge. The DF, i.e., the number density of stars as a function of position (r), velocity (v), age (τ), metallicity (Z), and mass (m) for each component, is assumed to be specified a priori as a function

\[ f_j(r, v, \tau, Z, m), \]

where \( j = 1, 2, 3, 4 \) runs over components. The form of \( f_j \) that correctly describes all the properties of the Galaxy and is self-consistent is still an open question. However, over the past few decades considerable progress has been made in identifying a working model dependent on a few simple assumptions (Robin & Creze 1986; Bienayme et al. 1987; Haywood et al. 1997a, 1997b; Girardi et al. 2005; Robin et al. 2003). Our analytical framework brings together these models as we describe below.

For a given Galactic component, let the stars form at a rate \( \Psi(\tau) \) with a mass distribution \( \xi(m|\tau) \) (IMF) that is a parameterized function of age \( \tau \). Let the present-day spatial distribution of stars \( p(r|\tau) \) be conditional on age only. Finally, assuming the velocity distribution to be \( p(v|r, \tau) \) and the metallicity distribution to be \( p(Z|\tau) \), we have

\[ f(r, v, \tau, m, Z) = \frac{\Psi(\tau)}{\langle m \rangle} \xi(m|\tau) p(r|\tau) p(v|r, \tau) p(Z|\tau). \]

The functions conditional on age can take different forms for different Galactic components. The IMF here is normalized such that \( \int_{m_{\text{min}}}^{m_{\text{max}}} \xi(m|\tau) dm = 1 \) and \( \langle m \rangle = \int_{m_{\text{min}}}^{m_{\text{max}}} m \xi(m|\tau) dm \) is the mean stellar mass. The metallicity distribution is modeled as a lognormal distribution,

\[ p(Z, |\tau) = \frac{1}{\sigma_{\log Z(\tau)} \sqrt{2\pi}} \exp \left( -\frac{\left( \log Z - \log \tilde{Z}(\tau) \right)^2}{2\sigma_{\log Z(\tau)}^2} \right), \]

the mean and dispersion of which are given by age-dependent functions \( \tilde{Z}(\tau) \) and \( \sigma_{\log Z(\tau)} \). The \( \tilde{Z}(\tau) \) is widely referred to as the AMR. Functional forms for each of the expressions in Equation (2) are given in Sharma et al. (2011; see also Robin et al. 2003). For convenience we reproduce in Table 1 a short description of the thin- and thick-disk components. The axis ratio \( \epsilon \) of the thin disk is given by

\[ \epsilon(\tau) = \text{Min} \left( 0.0791, 0.104 \left( \frac{\tau/\text{Gyr} + 0.1}{10.1} \right)^{0.5} \right), \]

and this represents the age–scale height relation.

### 2. Analytic Framework for Modeling the Galaxy

We first describe the analytic framework used to model the Galaxy (Sharma et al. 2011). The stellar content of the Galaxy is modeled as a set of distinct components: the thin disk, the thick disk, the stellar halo, and the bulge. The DF, i.e., the number density of stars as a function of position (r), velocity (v), age (τ), metallicity (Z), and mass (m) for each component, is assumed to be specified a priori as a function

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\[ f(r, v, \tau, m, Z) = \frac{\Psi(\tau)}{\langle m \rangle} \xi(m|\tau) p(r|\tau) p(v|r, \tau) p(Z|\tau). \]
2.2. Gaussian Velocity Ellipsoid Model

In this model, the velocity distribution is assumed to be a triaxial Gaussian,

\[
p(v|\mathbf{r}, \mathbf{\tau}) = \frac{1}{\sigma_R \sigma_\phi \sigma_z} (2\pi)^{3/2} \exp\left[ -\frac{v_R^2}{2\sigma_R^2} \right] \exp\left[ -\frac{v_\phi^2}{2\sigma_\phi^2} \right] \exp\left[ -\frac{v_z^2}{2\sigma_z^2} \right] \times \exp\left[ -\frac{(v_\phi - \langle v_\phi \rangle)^2}{2\sigma_\phi^2} \right],
\]

where \(R, \phi, z\) are cylindrical coordinates. The \(\langle v_\phi \rangle\) is the asymmetric drift and is given by

\[
\langle v_\phi \rangle = v_\phi^2(R) + \sigma_\phi^2 \left( \frac{d \ln \rho}{d \ln R} + \frac{d \ln \sigma_R}{d \ln R} + 1 - \frac{\sigma_\phi^2}{\sigma_R^2} + 1 - \frac{\sigma_z^2}{\sigma_R^2} \right).
\]

This follows from Equation (4.227) in Binney & Tremaine (2008) assuming \(\sigma_R v_\phi = (v_\phi^2 - v_R^2)(z/R)\). This is valid for the case where the principal axes of the velocity ellipsoid are aligned with the \((r, \theta, \phi)\) spherical coordinate system. If the velocity ellipsoid is aligned with the cylindrical \((R, \phi, z)\) coordinate system, then \(\langle v_\phi \rangle = 0\). Recent results using the RAVE data suggest that the velocity ellipsoid is aligned with the spherical coordinates (Siebert et al. 2008; Binney et al. 2014). One can parameterize our ignorance by writing the asymmetric drift as follows:

\[
\langle v_\phi \rangle = v_\phi^2(R) + \sigma_\phi^2 \left( \frac{d \ln \rho}{d \ln R} + \frac{d \ln \sigma_R}{d \ln R} + 1 - \frac{\sigma_\phi^2}{\sigma_R^2} + 1 - \frac{\sigma_z^2}{\sigma_R^2} \right).
\]

This is the form that is used by Bovy et al. (2012a).

The dispersions of the \(R, \phi\) and \(z\) components of velocity increase as a function of age owing to secular heating in the disk, and there is a radial dependence such that the dispersion increases toward the Galactic center. We model these effects after Aumer & Binney (2009) and Binney (2010) using the functional form

\[
\sigma_{R,\phi,z}^\text{thin}(R, \tau) = \sigma_{R,\phi,z,\odot}^\text{thin} \exp\left[ -\frac{R - R_0}{R_0^\text{min}} \right] \times \left( \frac{\tau + \tau_{\text{min}}}{\tau_{\text{max}} + \tau_{\text{min}}} \right)^{\beta_{R,\phi,z}}.
\]

\[
\sigma_{R,\phi,z}^\text{thick}(R, \tau) = \sigma_{R,\phi,z,\odot}^\text{thick} \exp\left[ -\frac{R - R_0}{R_0^\text{thick}} \right].
\]

The choice of the radial dependence is motivated by the desire to produce disks in which the scale height is independent of radius. For example, under the epicyclic approximation, if \(\sigma_\phi/\sigma_R\) is assumed to be constant, then the scale height is independent of radius for \(R_g = 2R_d\) (van der Kruit & Searle 1982; van der Kruit 1988; van der Kruit & Freeman 2011). In reality there is also a \(z\) dependence of velocity dispersions, which we have chosen to ignore in our present analysis. This means that for a given mono age population the asymmetric drift is independent of \(z\). However, the velocity dispersion and asymmetric drift of the combined population of stars are functions of \(z\). This is because the scale height of stars for a given isothermal population is an increasing function of its vertical velocity dispersion.

For our kinematic analysis we assume \(d \ln \rho/dR = -1/R_d\) with \(R_d = 2.5\) kpc. While this is true for the thick disk adopted by us, for the thin disk this is only approximately true (see Table 1). The thin disk with age between 0.15 and 10 Gyr is exponential at large \(R\) with a scale length of 2.53 kpc.

2.3. Shu Distribution Function Model

The Gaussian velocity ellipsoid model has its limitations. In particular, the distribution of \(v_\phi\) is strongly non-Gaussian, being highly skewed to low \(v_\phi\).

For a two-dimensional disk, a much better approximation to the velocity distribution is provided by the Shu (1969) DF. Moreover, the Shu DF, being dynamical in nature, connects the radial and azimuthal components of velocity dispersion to each other and to the mean-streaming velocity, thus lowering the number of free parameters in the model.

Assuming that the potential is separable as \(\Phi(R, z) = \Phi_R(R) + \Phi_z(z)\), we can write the DF as

\[
f(E_R, L_z, E_z) = \frac{F(L_z) \exp\left[ -\frac{E_R}{\sigma_R^2(L_z)} \right]}{\sigma_z(L_z) \sqrt{2\pi}} \times \exp\left[ -\frac{(E_z - \sigma_z^2(L_z))}{2\sigma_z(L_z)} \right],
\]

where \(L = Rv_\phi\) is the angular momentum,

\[
E_z = \frac{v_z^2}{2} + \Phi_z(z)
\]

\[
E_R = \frac{1}{2} v_R^2 + \Phi(R) - \Phi(R_g, L_z) + \Phi(z, L_z)
\]

\[
= \frac{1}{2} v_R^2 + \Delta \Phi(R, L_z).
\]

with

\[
\Phi(R, L_z) = \frac{L_z^2}{2R^2} + \Phi(R) \simeq \frac{L_z^2}{2R^2} + v_c^2 \ln R
\]

being the effective potential. Let \(R_g(L_z) = L_z/v_c\) be the radius of a circular orbit with specific angular momentum \(L_z\). In Schönrich & Binney (2012; see also Sharma & Bland-Hawthorn 2013) it was shown that the joint distribution of \(R\) and \(R_g\) can be written as

\[
P(R, R_g) = \frac{(2\pi)^2 \Sigma(R_c)}{g\left(\frac{1}{2\pi}\right)} \times \exp\left[ -\frac{2 \ln(R_g/R) + 1 - R_g^2/R^2}{2a^2} \right],
\]

where \(\Sigma(R)\) is a function that controls the disk’s surface density and

\[
a = \sigma_R(R_g)/v_c
\]

\[
g(c) = c^\Gamma(c - 1/2)/2c^{c-1/2}.
\]

We assume \(a\) to be specified as

\[
a = a_0(\tau) \exp\left[ -\frac{R_g}{R_g} \right]
\]

\[
= \frac{\sigma_R(\odot)}{v_c} \left( \frac{\tau + \tau_{\text{min}}}{\tau_{\text{max}} + \tau_{\text{min}}} \right)^{\beta_a} \exp\left[ -\frac{R_g - R_0}{R_0} \right]
\]

(17)
Now this leaves us to choose \( \Sigma(R_z) \). This should be done so as to produce disks that satisfy the observational constraint given by \( \Sigma(R) \), i.e., an exponential disk (or disks) with scale length \( R_d \). A simple way to do this is to let

\[
\Sigma(R_z) = \frac{e^{-R_z/R_d}}{2\pi R_d^2}.
\]

However, this matches the target surface density only approximately. A better way to do this is to use the empirical formula proposed in Sharma & Bland-Hawthorn (2013) such that

\[
\Sigma(R_z) = \frac{e^{-R_z/R_d}}{2\pi R_d^2} - 0.00976\sigma_0^2 s^2 \times \left[ \frac{R_z}{(3.74 R_d(1 + q/0.523))} \right],
\]

where \( q = R_d/R_\sigma \) and \( s \) is a function of the following form:

\[
s(x) = ke^{-x/b}(x/a)^2 - 1),
\]

with \((k, a, b) = (31.53, 0.6719, 0.2743)\). This is the scheme that we employ in this paper.

As in the previous section, we adopt \( R_d = 2.5 \) kpc.

2.4. Model for the Potential

So far we have described kinematic models in which the potential is separable in \( R \) and \( z \). In such cases, the energy associated with the vertical motion \( E_z \) can be assumed to be the third integral of motion. In reality, the potential generated by a double-exponential disk is not separable in \( R \) and \( z \). For example, the hypothetical circular speed defined as \( \sqrt{R \partial \Phi(R, z)/\partial R} \) can have both a radial and a vertical dependence. We model it as

\[
v_c(R, z) = \sqrt{\frac{R \partial \Phi}{\partial R}} = \frac{(\Omega_0 + \alpha_R R)}{1 + \alpha_z|z|/\text{kpc}|^{3/4}}.
\]

The parameters \( \alpha_R \) and \( \alpha_z \) control the radial and vertical dependencies, respectively. The motivation for the vertical term comes from the fact that the above formula with \( \alpha_z = 0.0374 \) provides a good fit to the \( v_c(R_0, z) \) profile of the Milky Way potential by Dehnen & Binney (1998a), as well as that of Law & Majewski (2010) (see Figure 1). Both of them have bulge, halo, and disk components. The former has two double-exponential disks, while the latter has a Miyamoto--Nagai disk.

To accurately model a system, in which the potential is not separable in \( R \) and \( z \), requires a DF that incorporates the third integral of motion in addition to energy \( E \) and angular momentum \( L_z \), e.g., DFs based on action integrals \( J_R, J_z \), and \( L_z \) (Binney 2012b, 2010). Converting phase-space coordinates \((x, v)\) to action integrals is not easy, and techniques to make this possible are under development. One way to compute the actions is by using the adiabatic approximation, i.e., conservation of vertical action (Binney & McMillan 2011; Schönrich & Binney 2012). Using an adiabatic approximation, Schönrich & Binney (2012) extend the Shu DF to three dimensions and model the kinematics as a function of distance from the plane. Recently, it has been shown by Binney (2012a) that the adiabatic approximation is accurate only close to the midplane and that much better results are obtained by assuming the potential to be similar to a Stackel potential.

In this paper, to model systems where the potential is not separable in \( R \) and \( z \), we follow a much simpler approach. The approach is motivated by the fact that, for realistic galactic potentials, we expect the \( \Sigma_\phi \) of a single age population to fall with \( z \). It has been shown by both Binney & McMillan (2011) and Schönrich & Binney (2012) that when vertical motion is present, in a Milky-Way-type potential, the effective potential for radial motion (see Equation (13)) needs to be modified as the vertical motion also contributes to the centrifugal potential. Neglecting this effect leads to an overestimation of \( \Sigma_\phi \). As one moves away from the plane this effect is expected to become more and more important. Second, as shown by Schönrich & Binney (2012), in a given solar annulus, stars with smaller \( R_d \) will have larger vertical energy and hence larger scale height. This implies that stars with smaller \( R_d \) are more likely to be found at higher \( z \); consequently, the \( \Sigma_\phi \) should also decrease with height.

The fall of \( \Sigma_\phi \) with height is also predicted by the Jeans equation for an axisymmetric system

\[
\frac{\partial^2 \Sigma_\phi}{\partial z^2} = \frac{R \partial \Phi}{\partial R} + \frac{\sigma_R^2}{\sigma_z^2} \left[ 1 - \frac{\sigma_R^2}{\sigma_z^2} + \frac{\partial \ln (\rho \sigma_R^2)}{\partial R} \right] + R \frac{\partial v_c^2}{\partial z} + v_c \frac{\partial \ln \rho}{\partial z}.
\]

The \( \Sigma_\phi \) at high \( z \) will be lower both because \( R \partial \Phi/\partial R \) is lower and because the term in the third square bracket decreases with \( z \), e.g., assuming \( v_c(R, z) \) as given by Equation (22) in Equation (6). Given this prescription, we expect \( \alpha_z > 0.03744 \), so as to account for effects other than that involving the first term in Equation (23). In reality, the velocity dispersion tensor \( \sigma^2 \) will have a much more complicated dependence on \( R \) and \( z \) than what we have assumed, e.g., we
assumed that $\sigma_R, \sigma_\phi, \sigma_z$ only has an $R$ dependence that is given by an exponential form.

For the Shu model we replace $v_z$ in Equation (15) by the form in Equation (22). The idea again is to find the fall of $v_\phi$ with $z$. However, the prescription breaks the dynamical self-consistency of the model and turns it into a fitting formula. In reality, the $v_\phi$ may not exactly follow the functional form for the vertical dependence predicted by our model, but it is better than completely neglecting it.

### 2.5. Models and Parameters Explored

The parameters that we consider are solar motion ($U_\odot, V_\odot, W_\odot$), the logarithmic slopes of AVRs ($\beta_R, \beta_\phi, \beta_z$), the scale lengths of radial dependence of velocity dispersions ($R_0, R_\sigma$), and the velocity dispersions at $R = R_0$ of the thin disk ($\sigma_\phi, \sigma_z, \sigma_R$) and of the thick disk ($\sigma_\phi, \sigma_z, \sigma_R$); for simplicity the subscript $\odot$ is dropped here. The Gaussian models are denoted by GAU, whereas models based on the Shu DF are denoted by SHU. For models based on the Shu DF, the azimuthal motion is coupled to the radial motion; hence, $\beta_0, \sigma_\phi, \sigma_z$, and $\sigma_\phi$ are not required. When $\Theta_0$ is fixed, we assume its value to be $226.84 \text{ km s}^{-1}$. In some cases, we also keep the parameters $\beta_z$ and $R_0$ fixed. While reporting the results we highlight the fixed parameters.

| Model Parameter | Description |
|-----------------|-------------|
| $U_\odot$       | Solar motion with respect to LSR |
| $V_\odot$       | Solar motion with respect to LSR |
| $W_\odot$       | Solar motion with respect to LSR |
| $\sigma_R$      | The velocity dispersion at 10 Gyr
                           Normalization of thin disk AVR (Equation (8)) |
| $\sigma_\phi$   | The velocity dispersion at 10 Gyr
                           Normalization of thin disk AVR (Equation (8)) |
| $\sigma_z$      | The velocity dispersion at 10 Gyr
                           Normalization of thin disk AVR (Equation (8)) |
| $\sigma_{\text{thick}}$ | The velocity dispersion of thick disk (Equation (9)) |
| $\beta_R$       | The exponent of thin disk AVR (Equation (8)) |
| $\beta_\phi$    | The exponent of thin disk AVR (Equation (8)) |
| $\beta_z$       | The exponent of thin disk AVR (Equation (8)) |
| $R_0$           | Distance of Sun from the Galactic center |
| $\Theta_0$      | The circular speed at Sun |
| $\sigma_c$      | Vertical fall of circular velocity (Equation (22)) |
| $\sigma_R$      | Radial gradient of circular speed (Equation (22)) |

### 3. OBSERVATIONAL DATA AND SELECTION FUNCTIONS

In this paper we analyze data from two surveys, RAVE (Steinmetz et al. 2006; Zwitter et al. 2008; Siebert et al. 2011; Kordopatis et al. 2013) and GCS (Nordström et al. 2004; Holmberg et al. 2009). For fitting theoretical models to data from stellar surveys, it is important to take into account the selection biases that were introduced when observing the stars. This is especially important for spectroscopic surveys that observe only a subset of all possible stars defined within a color–magnitude range. So we also analyze the selection function for the RAVE and GCS surveys.

#### 3.1. RAVE Survey

The RAVE survey collected spectra of 482,430 stars between 2004 April and 2012 December, and stellar parameters, radial velocity, abundance, and distances have been determined for 425,561 stars. In this paper we used the internal release of RAVE from 2012 May, which consisted of 458,412 observations. The final explored sample after applying various selection criteria consists of 280,128 unique stars. These data are available in the DR4 public release (Kordopatis et al. 2013), where an extended discussion of the sample is also presented.

For RAVE we only make use of the $\ell$, $b$, and $v_\text{los}$ of stars. The $I_{\text{DENIS}}$ and 2MASS $J - K_s$ colors are used for marginalization over age, metallicity, and mass of stars taking into account the photometric selection function of RAVE. We do not use proper motions, or stellar parameters that could in principle provide tighter constraints, but then one has to worry about systematic differences between different proper-motion catalogs like PPMXL (Röser et al. 2008), SPM4 (Girard et al. 2011), and UCAC3 (Zacharias et al. 2010). As for stellar parameters, although they are reliable, no pipeline can claim to be free of unknown systematics, especially when working with low signal-to-noise ratio data. Hence, as a first step it is instructive to work with data that are least ambiguous, and then in the next step to check the results by adding more information. As we will show later, for the types of model that we consider, even using only $\ell$, $b$ and $v_\text{los}$ can provide good constraints on the model parameters.

We now discuss the selection function of RAVE. The RAVE survey was designed to be a magnitude-limited survey in the $I$ band. This means that theoretically it has one of the simplest selection functions, but, in practice, for a multitude of reasons, some biases were introduced. First, the DENIS and 2MASS surveys were not fully available when the survey started. Hence, the first input catalog (IC1) had stars from 6.5 to 9 kpc. The true value of $R_0$ is still debatable, ranging from 7.5 to 8.5 kpc. The classically accepted value of $8 \pm 0.5$ kpc is a weighted average given in a review by Reid (1993). The main reason we keep $R_0$ fixed is as follows. Given that we do not make use of explicit distances, proper motions, or external constraints like the proper motion of Sgr A*, it is clear that we will not be able to constrain $R_0$ well, especially if $\Theta_0$ is free. For example McMillan & Binney (2010), using parallax, proper motion, and line-of-sight velocity of masers in high star-forming regions, show that constraining both $\Theta_0$ and $R_0$ independently is difficult.

#### 3.2. GCS Survey

The GCS survey was designed to be a magnitude-limited survey in the $I$ band. This means that theoretically it has one of the simplest selection functions, but, in practice, for a multitude of reasons, some biases were introduced. First, the DENIS and 2MASS surveys were not fully available when the survey started. Hence, the first input catalog (IC1) had stars from 6.5 to 9 kpc. The true value of $R_0$ is still debatable, ranging from 7.5 to 8.5 kpc. The classically accepted value of $8 \pm 0.5$ kpc is a weighted average given in a review by Reid (1993). The main reason we keep $R_0$ fixed is as follows. Given that we do not make use of explicit distances, proper motions, or external constraints like the proper motion of Sgr A*, it is clear that we will not be able to constrain $R_0$ well, especially if $\Theta_0$ is free. For example McMillan & Binney (2010), using parallax, proper motion, and line-of-sight velocity of masers in high star-forming regions, show that constraining both $\Theta_0$ and $R_0$ independently is difficult.

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Tycho and SuperCOSMOS. For Tycho stars, $I$ magnitudes were estimated from $V_T$ and $B_T$ magnitudes. On the other hand, the SuperCOSMOS stars had $I$ magnitudes, but an offset was later detected with respect to $I_{\text{DENIS}}$. Later, as DENIS and 2MASS became available, the second input catalog IC2 was created. With the availability of DENIS, it became possible to have a direct $I$ magnitude measurement that was free from offsets like those observed in SuperCOSMOS. However, DENIS had its own problems—saturation at the bright end, duplicate entries, missing stripes in the sky, inter alia. To solve the problem of duplicate entries, the DENIS catalog was cross-matched with 2MASS to within a tolerance of 1′. This helped clean up the color–color diagram of ($J_{\text{DENIS}} - K_{\text{DENIS}}$) versus ($J_{\text{2MASS}} - K_{\text{2MASS}}$) in particular (Seabroke 2008).

Given this history, the question arises, how can we compute the selection function? Since accurate $I$ magnitude photometry is not available for stars that are only in IC1, the first cut we make is to select stars from IC2 only. Then we removed the duplicates—among multiple observations one of them was randomly selected to observe at a given time. However, it seems that later on this division was not strictly maintained (probably owing to the observation of calibration stars and some extra stars going to brighter magnitudes). This means that the selection function has to be computed as a function of $I_{\text{DENIS}}$ in much finer bins. Assuming that the DENIS $I$ magnitudes are correct and the cross-matching is correct, the only thing that needs to be taken into account is the angular completeness of the DENIS survey (missing stripes). To this end, we grid the observed and IC2 stars in $(\ell, b, I_{\text{DENIS}})$ space and compute a probability map. To grid the angular coordinates, we use the HEALPIX pixelization scheme (Górski et al. 2005). The resolution of HEALPIX is specified by the number $n_{\text{side}}$, and the total number of pixels is given by $12n_{\text{side}}^2$. For our purpose, we use $n_{\text{side}} = 16$, which gives a pixel size of 13.42 deg$^2$, which is smaller than the RAVE field of view of 28.3 deg$^2$. For magnitudes, we use a bin size of 0.1 mag, which again is much smaller than the magnitude range included in each observation. Given the fine resolution of the probability map, the angular and magnitude-dependent selection biases are adequately handled. Note that in the range ($225^\circ < \ell < 315^\circ$) and ($5^\circ < |b| < 25^\circ$), a color selection of $(J - K_s) > 0.5$ was used to selectively target giants, and we take this into account in our analysis.

Arce & Goodman (1999) suggest that the Schlegel et al. (1998) maps overestimate reddening by a factor of 1.3–1.5 in regions with smooth extinction $A_V > 0.5$, i.e., $E_{R-V} > 0.15$ (see also Cambresy et al. 2005). In Figure 2 the color and temperature distributions of our RAVE stars (black lines) are compared with predictions from Galaxia given the selection above (see Figure 3 for the distribution of stars in the $I, b$ plane). At high latitudes (second and fourth panels) the red model curves agree reasonably well with the black data curves, but in the top panel ($5^\circ < |b| < 25^\circ$) the red model distribution of $J-K$ colors is clearly displaced to red colors relative to the data. The low-latitude temperature distributions shown in the third panel show no analogous shift of the model curve to lower temperatures, so we have a clear indication that the model colors have been made too red by excessive extinction. To correct this problem, we modify the Schlegel $E_{R-V}$ as follows:

$$f_{\text{corr}} = 0.6 + 0.2 \left(1 - \tanh \left[ \frac{E_{R-V} - 0.15}{0.1} \right] \right). \quad (24)$$

The formula above reduces extinction by 40% for high-extinction regions; the transition occurs around $E_{R-V} \sim 0.15$ and is smoothly controlled by the tanh function. The green curves in the top two panels show the proposed correction to Schlegel maps. Although not perfect, the correction reduces the discrepancy between the model and data for low-latitude stars (top panel) while having negligible impact on high-latitude stars.

The fact that the temperature and color distributions in Figure 2 match up so well is encouraging, given that we selected on $I_{\text{DENIS}}$ magnitude alone. This implies that the spatial distribution of stars specified by Galaxia satisfies one of the necessary observational constraints.

### 3.2. GCS Survey

We fit the models to all six phase-space coordinates of a subset of the 16,682 F- and G-type main-sequence stars in the GCS (Nordström et al. 2004; Holmberg et al. 2009). A mock GCS sample was extracted from the model as in Sharma et al. (2011). Velocities and temperatures are available for 13,382 GCS stars. We found that while Galaxia predicts less than one halo star in the GCS sample for a distance less than 120 pc, when plotted in the $(\text{[Fe/H]}, v_Y)$ plane, the GCS has 29 stars with $\text{[Fe/H]} < -1.2$ and highly negative values of $v_Y$ (as expected for halo stars). Following Schönrich et al. (2010), we identify these as halo stars and exclude them from our analysis.

The GCS catalog is complete for F- and G-type stars within a volume given by $r < 40$ pc and $V \sim 8$ in magnitude; within these limits there are only 1342 stars. Since GCS is a color–magnitude-limited survey, there is no need to restrict the analysis to a volume-complete sample. In Nordström et al. (2004) magnitude completeness as a function of color is provided, and we use this (their Section 2.2). There is some ambiguity about the coolest dwarfs that were added for declination $\delta < -26^\circ$; from information gleaned from Nordström et al. (2004), we could not find a suitable way to take this into account.

We also applied some additional restrictions on the sample. For example, we restrict our analysis to stars with distance less than 120 pc, so as to avoid stars with large distance errors. The GCS survey selectively avoids giants. To mimic this, we use the selection function $M_V < 10(b - y) - 3$. The predicted temperature distributions show a mismatch with models, in particular, there are too many hot stars. Using Casagrande et al. (2011) temperatures, which are more accurate, we found an upper limit on $T_{\text{eff}}$ of 7244 K, which was applied to the models.

After the above-mentioned cuts, the final sample consisted of 5201 stars. Note that we do not remove possible binary stars as this will further reduce the number of stars. In the future, we think it will be instructive to check whether there is any systematic association with the inclusion or exclusion of binaries. The black histograms in Figure 4 show the distribution of these stars, while the red histograms show the predictions of...
the model. At the hot end, the temperature distributions of model and data are still discrepant, but the distance distributions agree nicely. The model’s age distribution is qualitatively correct, but differences can also be seen. The plotted GCS ages are significantly lower than the model ages, as done by GCS and taking into account uncertainties and systematics, which we do not do here. The peak in the model at 11 Gyr is due to the thick disk having a fixed age. The peaks in the data at 0 and 14 Gyr are most likely due to caps employed while estimating ages. The color distribution in GCS shows a peak around \( b - y = 0.3 \), which could be due to an unknown selection effect. The bump at \( b - y \sim 0.43 \), which is also seen in models, is due to turnoff stars. Overall, we think that our modeling reproduces to a good degree the selection function of the GCS stars.

4. MODEL FITTING TECHNIQUES

If \( y_i \) are the observed properties of a star, we can describe the observed data by \( y = \{ y_i \in \mathbb{R}^d, 0 < i < N \} \). Also, let \( \theta \) be the set of parameters that define the model. Our job is to compute

\[
p(\theta | y) \propto p(y | \theta) p(\theta),
\]

where \( p(y | \theta) = \prod_i p(y_i | \theta) \). We employ an MCMC scheme to estimate \( p(\theta | y) \) and assume a uniform prior on \( \theta \). We now discuss how to compute \( p(y | \theta) \).

Generally, a model of a galaxy gives the probability density \( p(\mathbf{r}, \mathbf{v}, \tau, Z, m | \theta) \). For RAVE, the observed quantities are \( v_{\text{los}}, \ell, \) and \( b \), while for GCS they are \( \ell, b, r, v_l, v_b \) and \( v_{\text{los}} \). Since quantities like \( \tau, Z \) and \( m \) are unknown, one has to compute the marginal probability density by integration. For RAVE, the required marginal density is

\[
p(\ell, b, v_{\text{los}} | \theta) = \int p(\ell, b, r, \tau, Z, m, v_l, v_b, v_{\text{los}} | \theta) \times S(\ell, b, \tau, Z, m) dr d\tau dZ dm dv_l dv_b,
\]

and for GCS it is

\[
p(\ell, b, r, v_l, v_b, v_{\text{los}} | \theta) = \int p(\ell, b, r, \tau, Z, m, v_l, v_b, v_{\text{los}} | \theta) \times S(\ell, b, \tau, Z, m) dr d\tau dZ dm.
\]

Here \( S(\ell, b, \tau, Z, m) \) is the selection function specifying how the stars were preselected in the data. The actual selection is on photometric magnitude, which in turn is a function of \( \tau, Z \) and \( m \).

For the kinds of models explored here, the computations are considerably simplified owing to the fact that

\[
p(\ell, b, r, \tau, Z, m, v_l, v_b, v_{\text{los}} | \theta) = p(v_l, v_b, v_{\text{los}} | \ell, b, r, \tau, Z, m, \theta_3) \times p(\ell, b, r, \tau, Z, m | \theta_3),
\]

for which \( \theta_3 \) is the set of model parameters that govern the spatial distribution of stars and \( \theta \) is the set of model parameters that govern the kinematic distribution of stars. The

![Figure 2](image-url). Color and temperature distribution (from DR3 pipeline) of RAVE stars compared with Galaxia simulations with properly matched selection and statistical sampling. The effect of our new correction formula for the Schlegel extinction map is also shown. The results for \( |b| < 25^\circ \) and \( |b| > 25^\circ \) are shown separately. Note that Galaxia makes use of Padova isochrones. (A color version of this figure is available in the online journal.)
term $p(\ell, b, r, \tau, Z, m|\theta_S)$ is invariant in our analysis, and this is the main assumption that we make. In other words, we assume SFR, IMF, scale length of disk, age–scale height relation, AMR, and radial metallicity gradient for the disk. All these distributions can be constrained by the stellar photometry. The distribution $p(v_l, v_b, v_{los}|\ell, b, r, \tau, \theta)$ represents the kinematics, which is what we explore. It should be noted that the model $p(\ell, b, r, \tau, Z, m|\theta_S)$ that we use has been shown to satisfy the number count of stars (Robin et al. 2003; Sharma et al. 2011). Ideally, in a fully self-consistent model, the scale height, the vertical stellar velocity dispersion, and the potential are all related to each other, and this is something we would like to address in the future.

We can now integrate the last term in Equation (28) over $m$ and $Z$ such that

$$p(\ell, b, r, v_l, v_b, v_{los}, \tau|\theta) = p(v_l, v_b, v_{los}|\ell, b, r, \tau, \theta) \times p(\ell, b, r, \tau|\theta_S, S), \quad (29)$$

where

$$p(\ell, b, r, \tau|\theta_S, S) = \int \int p(\ell, b, r, \tau, Z, m|\theta_S) \times S(\ell, b, \tau, Z, m) \, dZ \, dm. \quad (30)$$

The term $p(\ell, b, r, \tau|\theta_S, S)$ is computed numerically using the code Galaxia (Sharma et al. 2011). Galaxia uses isochrones from the Padova database to compute photometric magnitudes for the model stars (Marigo et al. 2008; Bertelli et al. 1994). We first generate a fiducial set of stars satisfying the color–magnitude range of the survey. Then we apply the selection function and reject stars that do not satisfy the constraints of the survey. The accepted stars are then binned in $(\ell, b, r, \tau)$ space. Since the GCS is local to the Sun, we use the approximation $p(\ell, b, r, \tau|\theta_S, S) \propto p(\tau|\theta_S, S)$. The probability distribution in $(\ell, b, r, \tau)$ space for RAVE is shown in Figure 3.

For RAVE, we have to integrate over four variables $(r, \tau, v_l, v_b)$, but for GCS we integrate over only $\tau$. The four-dimensional marginalization for RAVE poses a serious computational challenge for data as large as the RAVE survey. For Gaussian DFs, the integral over $v_l$ and $v_b$ can be performed analytically to give an analytic expression for $p(v_{los}|\ell, b, r, \tau, Z, \theta)$, but in general it cannot be done analytically. Hence, we try two new methods. The first method is fast but has inflated uncertainties. The second method is slower to converge but gives correct estimates of uncertainties. Given these strengths and limitations, we use a combined strategy that makes best use of both the methods.

We use the first sampling and projection method to get an initial estimate of $\theta$ and also its covariance matrix. These are then used in the second data augmentation method. The initial estimate reduces the burn-intime, while the covariance matrix eliminates the need to tune the widths of the proposal distributions. In general, we use an adaptive MCMC scheme, which avoids manual tuning of the widths of the proposal distributions (Andrieu & Thoms 2008). At regular intervals, we compute the covariance matrix and scale it so as to achieve the desired acceptance ratio for the given number of parameters Gelman et al. (1996). We now discuss the two methods in more detail.

### 4.1. MCMC Using Sampling and Projection

Instead of doing the computationally intensive marginalization, at each step of the Markov chain of model parameters, we generate a sample of stars by Monte Carlo sampling the current model subject to the selection function. Binning these stars in $(\ell, b, v_{los})$ space then gives an estimate of $p(\ell, b, v_{los}|\theta)$. Note that, given the stochastic nature of our estimate of $p(\ell, b, v_{los}|\theta)$, the standard Metropolis–Hastings algorithm had to be altered to avoid the simulation from getting stuck at a stochastic maximum of the likelihood.

#### 4.2. MCMC Using Data Augmentation

Instead of marginalizing, one can treat the nuisance parameters as unknown parameters and estimate them alongside other parameters. This constitutes what is known as a sampling-based approach for computing the marginal densities. The basic form of this scheme was introduced by Tanner & Wong (1987) and later extended by Gelfand & Smith (1990). Let $x = \{x_i \in \mathbb{R}^d, 0 < i < N\}$ be an extra set of variables that are needed by the model to compute the probability density. Then we can write

$$p(\theta, x|y) \propto p(x, y|\theta)p(\theta), \quad (31)$$

where $p(x, y|\theta) = \prod_i p(x_i, y_i|\theta)$ and $p(x_i, y_i|\theta)$ is a function that is known and relatively easy to compute. For example, for the RAVE data $y_i = \{l_i, b_i, v_{los,i}\}$ and $x = \{r_i, \tau_i, v_{l,i}, v_{b,i}\}$. Because of the unusually large number of parameters, it is difficult to get satisfactory acceptance rates with the standard
Metropolis–Hastings scheme without making the widths of the proposal distributions extremely small. Thus, the chains would take an unusually long time to mix. To solve this, one uses the Metropolis scheme with Gibbs sampling (MWG; Tierney 1994). The MWG scheme is also useful for solving hierarchical Bayesian models, and its application for three-dimensional extinction mapping is discussed in Sale (2012).

In our case, the Gibbs step consists of first sampling x from the conditional density \( p(x|y, \theta) \) and then \( \theta \) from the conditional density \( p(\theta|y, x) \). The sampling in each Gibbs step is done using the Metropolis–Hastings algorithm.

### 4.3. Goodness of Fit

To assess the ability of a model to fit the data, we compute an approximate reduced \( \chi^2 \) value. To accomplish this, first we bin the data in the observational space. For RAVE, we bin the data in \((\ell, b, v_\text{los})\) space with bins of size 859 deg\(^2\) and 5 km s\(^{-1}\). Angular binning was done using the HEALPIX scheme. For GCS, we bin the \(U, V, W\) components of velocity separately with bins of size 5 km s\(^{-1}\). Next, an N-body realization of a given model was created satisfying the same constraints as the data. The reduced \( \chi^2 \) between the data and the model was then computed as

\[
\chi^2_{\text{red}} = \left( \sum_i \frac{(n_i - m_i/f_{\text{sample}})^2}{n_i + m_i/f_{\text{sample}}^2} \right) \quad \text{for } n_i > 0.
\]

Here \( n_i \) is the number of data points in a bin, \( m_i \) is the number of model points in the same bin, and \( f_{\text{sample}} = \sum_i m_i/\sum_i n_i \) is the sampling fraction. Choosing \( f_{\text{sample}} \) to be very high, one can increase the precision of the estimate, but then it increases the computational cost. For RAVE \( f_{\text{sample}} \) was 1, while for GCS it was 10. To decrease the stochasticity in the estimate, we computed the mean over 30 random estimates \( \langle \chi^2_{\text{red}} \rangle = \sum_{k=1}^{30} \chi^2_{\text{red},k}/30 \).

The reduced \( \chi^2 \) as computed above has its limitations. First, it is not an accurate estimator of the goodness of fit. Second, the \( \chi^2 \) value is sensitive to the choice of bin size and \( f_{\text{sample}} \). Hence, it is not advisable to estimate statistical significance using our reduced \( \chi^2 \). However, the reduced \( \chi^2 \) should be good enough to qualitatively compare the goodness of fit of two models.

### 4.4. Tests Using Synthetic Data

We now describe tests in which mock data are sampled from the DF and then fitted using the MCMC machinery. These tests serve two main purposes. First, they determine if our MCMC scheme works correctly. Second, they tell us which parameters can be recovered and with what accuracy. We study two classes of models based on (1) the Gaussian DF and (2) the Shu DF. Additionally, we study two types of mock data, one corresponding to the RAVE survey and the other to the GCS survey. For GCS we also study models where \( \Theta_0 \) is fixed. Altogether this leads to six different types of tests.

The results of these tests are summarized in Tables 3 and 4. The difference of a parameter \( p \) from input values divided by uncertainty \( \sigma_p \) measures the confidence of recovering the parameter. To aid the comparison, we color the values if they...
to check the systematics, the fitting should be repeated multiple times and the mean values should be compared with input values. However, the MCMC simulations being computationally very expensive, we report results with only one independent data sample for each of the test cases.

It can be seen that GCS-type data cannot properly constrain \( \Theta \). This is because the GCS sample is very local to the Sun. Keeping \( \Theta \) free also has the undesirable effect of increasing the uncertainty of \( R_R^{\text{thin}} \) and \( R_R^{\text{thick}} \). For Gaussian models, it is easy to see from Equation (6) that the effect of changing \( \Theta \) can be compensated by a change in \( R_R^{\text{thick}} \). Given these limitations, when analyzing GCS we keep \( \Theta \) fixed to 226.87 km s\(^{-1}\), a value that was used by Sharma et al. (2011) in the Galaxia code.

The solar motion is constrained well by both surveys, but better by RAVE. RAVE is also clearly better in constraining thick-disk parameters than GCS, mainly because the GCS has very few thick-disk stars (Galaxia estimates it to be 6% of the overall GCS sample). Across all parameters, for Shu models \( \beta_z \) is the only parameter that is constrained better by GCS than by RAVE. This is because RAVE only has radial velocities. This means that only those stars that lie toward the pole can carry meaningful information about the vertical motion, and such stars constitute a much smaller subset of the whole RAVE sample. This suggests that one can use the \( \beta_z \) value from GCS when fitting the RAVE data, as we show below.

### 5. Constraints on Kinematic Parameters

First, we discuss the fiducial parametric model for the Galaxy developed a decade ago by Robin et al. (2003). The so-called Besançon model is based on Gaussian velocity ellipsoid functions. In the Galaxia code, the tabulated functions of Robin et al. (2003) were replaced by analytic expressions, the parameters of which are given in Table 5. One main difference between the Galaxia and Besançon models is the value of \( R_0 \).
and the solar motion with respect to the LSR. Also, \textit{Galaxia} uses slightly different values of $R_{\sigma}$. In the Besançon model, the velocity dispersions are assumed to saturate abruptly at around $t_{\text{sat}} = 6.5$ Gyr. Moreover, the velocity dispersion of the thick disk does not have any radial dependence; hence, the value of $\sigma_{\text{thick}}$ only contributes to the calculation of the asymmetric drift. Neither of these Ansätze are assumed in our analysis.

Finally, in the Besançon model, the metallicity [Fe/H] of the thick disk is assumed to be $-0.78$ with a spread of $0.3$ dex. The spread is not taken into account when assigning magnitudes and colors from isochrones. This was done so as to prevent the thick disk from having a horizontal branch. We do not make this ad hoc assumption. Since our data do not have a strong color-sensitive selection, this has a negligible impact on our kinematic study.

We now discuss the results obtained from fitting models to the RAVE and the GCS data. The best-fit parameters and their uncertainties obtained using MCMC simulation for different models and data are shown in Tables 6 and 7. Note that the uncertainties quoted in the table are purely random and do not include systematics. We discuss systematics separately in Section 6.8. We begin by discussing results from the Gaussian DF before proceeding to the Shu DF.

5.1. Gaussian Models

First, we concentrate on GCS data (Column (1) of Table 6). For GCS we find that all the values are well constrained. However, percentage-wise $R^{\text{thick}}_{\sigma}$, $R^{\text{thick}}_{\beta}$, and $V_0$ have larger uncertainties as compared to other parameters. In Figure 5, where fits from Column (1) are plotted, it can be seen that the model is an acceptable fit to the data. The reduced $\chi^2$ values are quite high, especially in comparison with the mock models. This is mainly due to a significant amount of structure in $(U, V)$ velocity space (see Figure 5). The $\beta_{z\phi}$, $\sigma_{\text{thick}}$, $\sigma_{\text{thick}}$, and $\sigma_{\text{thick}}$ parameters are close to the corresponding Besançon values but show other differences. The most notable differences are that our value for $R^{\text{thick}}_{\sigma}$ is smaller, $R^{\text{thick}}_{\beta}$ is larger, and $\sigma_{\text{thick}}$ is lower. Other minor differences are as follows. Our $\beta_{z\phi}$ and $\beta_{\phi}$ are lower, and so are the velocity dispersions $\sigma_{\text{thick}}$, $\sigma_{\text{thick}}$. The thin-disk velocity dispersions are strongly correlated to $\beta_{z\phi}$ values, so fixing $\beta_{z\phi}$ to higher values will drive the corresponding thin-disk velocity dispersions closer to the Besançon values. Column (2) in Table 6 shows the results for the case where a separate thick disk is not assumed (the thick-disk stars are labeled as thin-disk in the model). In this case, $\beta_{z\phi}$ and $\beta_{\phi}$ increase, while $R^{\text{thick}}_{\sigma}$ decreases, which is expected since the thin disk has to accommodate the warmer thick-disk component.

We now discuss results for the RAVE data, beginning with the model where $\alpha_{z\phi} = 0$ (Column (4) of Table 6). Surprisingly, $R^{\text{thick}}_{\sigma}$ is found to be negative, whereas $R^{\text{thick}}_{\beta}$ is positive. The value of $\Theta_0$ is found to be significantly less than that reported in the literature. The $\beta_{z\phi}$ and $\beta_{\phi}$ values are also too small. We note that the $\beta_{z\phi}$ value in RAVE has more uncertainty than that in GCS, which we had also noted in the tests on mock data. From now on we keep $\beta_{z\phi}$ = 0.37, a value we get from GCS.
Figure 5. Comparison of model velocity distributions with that of GCS data. The right panels differ from the left only in range and scale of axes. The model used is the best-fit Gaussian (Column (1) of Table 6) and the Shu model (Column (1) of Table 7) for the GCS data. Both the models are acceptable fits to the data. Significant structures can be seen in the velocity space.

(A color version of this figure is available in the online journal.)

Table 7
Constraints on Model Parameters with the Shu Distribution Function

| Model | GCS SHU | GCS SHU | GCS SHU | RAVE SHU | RAVE SHU | RAVE SHU | RAVE SHU |
|-------|---------|---------|---------|----------|----------|----------|----------|
| $U_\odot$ | $10.02^{+0.39}_{-0.39}$ | $10.16^{+0.4}_{-0.4}$ | $10.23^{+0.39}_{-0.4}$ | $11.24^{+0.15}_{-0.13}$ | $10.92^{+0.14}_{-0.14}$ | $10.96^{+0.14}_{-0.14}$ | $11.05^{+0.15}_{-0.16}$ |
| $V_\odot$ | $9.95^{+0.3}_{-0.3}$ | $9.81^{+0.28}_{-0.28}$ | $9.83^{+0.3}_{-0.29}$ | $9.71^{+0.12}_{-0.11}$ | $7.53^{+0.16}_{-0.16}$ | $7.53^{+0.16}_{-0.16}$ | $7.62^{+0.13}_{-0.16}$ |
| $W_\odot$ | $7.14^{+0.19}_{-0.19}$ | $7.13^{+0.18}_{-0.19}$ | $7.12^{+0.18}_{-0.19}$ | $7.56^{+0.085}_{-0.086}$ | $7.54^{+0.089}_{-0.093}$ | $7.53^{+0.095}_{-0.095}$ | $7.55^{+0.086}_{-0.09}$ |
| $\sigma_{\text{thin}}$ | $38.14^{+0.96}_{-0.94}$ | $39.99^{+0.91}_{-0.91}$ | $42.71^{+0.83}_{-0.8}$ | $42.37^{+0.66}_{-0.66}$ | $39.78^{+0.81}_{-0.73}$ | $39.78^{+0.81}_{-0.73}$ | $39.56^{+0.66}_{-0.7}$ |
| $\sigma_{\text{thick}}$ | $23.39^{+0.77}_{-0.75}$ | $23.63^{+0.85}_{-0.8}$ | $25.91^{+0.64}_{-0.6}$ | $26.85^{+0.85}_{-0.92}$ | $24.7^{+0.66}_{-0.66}$ | $25.73^{+0.21}_{-0.21}$ | $25.73^{+0.23}_{-0.25}$ |
| $\beta_R$ | $70.1^{+3.7}_{-5.5}$ | $45.9^{+1.8}_{-1.8}$ | $38.8^{+1.2}_{-1.6}$ | $42.31^{+0.86}_{-0.9}$ | $42.43^{+0.95}_{-1.1}$ | $43.23^{+0.96}_{-1.1}$ | $43.23^{+0.96}_{-1.1}$ |
| $\alpha_R$ | $39^{+1.5}_{-2.2}$ | $32.6^{+0.9}_{-0.9}$ | $29.1^{+0.87}_{-0.79}$ | $34.66^{+0.61}_{-0.58}$ | $34.3^{+0.57}_{-0.57}$ | $34.48^{+0.54}_{-0.53}$ | $34.48^{+0.54}_{-0.53}$ |
| $\beta_z$ | $0.213^{+0.014}_{-0.014}$ | $0.237^{+0.013}_{-0.013}$ | $0.273^{+0.011}_{-0.011}$ | $0.236^{+0.011}_{-0.011}$ | $0.198^{+0.014}_{-0.014}$ | $0.195^{+0.011}_{-0.011}$ | $0.195^{+0.011}_{-0.011}$ |
| $\beta_z$ | $0.361^{+0.02}_{-0.02}$ | $0.366^{+0.021}_{-0.021}$ | $0.415^{+0.016}_{-0.016}$ | $0.398^{+0.03}_{-0.029}$ | $0.328^{+0.027}_{-0.024}$ | $0.37$ | $0.37$ |
| $\chi^2_{\text{red}}$ | $0.0065^{+0.0064}_{-0.0086}$ | $0.073$ | $0.077^{+0.0059}_{-0.0061}$ | $0.067^{+0.0028}_{-0.0028}$ | $0.072^{+0.0035}_{-0.0032}$ | $0.073^{+0.0037}_{-0.0032}$ | $0.072^{+0.0037}_{-0.0031}$ |
| $\chi^2_{\text{red}}$ | $0.0086^{+0.0022}_{-0.0066}$ | $0.132$ | $0.155^{+0.0046}_{-0.0056}$ | $0.133^{+0.0046}_{-0.0056}$ | $0.132^{+0.005}_{-0.0051}$ | $0.13^{+0.0056}_{-0.0046}$ |
| $\chi^2_{\text{red}}$ | $226.84$ | $232$ | $226.84$ | $212.6^{+1.3}_{-1.3}$ | $232.8^{+1.7}_{-1.6}$ | $231.9^{+1.5}_{-1.5}$ | $235.02^{+0.83}_{-0.83}$ |
| $R_0$ | $8$ | $8$ | $8$ | $8$ | $8$ | $8$ | $8$ |
| $\chi^2_{\text{red}}$ | $2.07$ | $1.8$ | $2.4$ | $1.52$ | $1.43$ | $1.42$ | $1.42$ |
| $\chi^2_{\text{red}}$ | $3.85$ | $3.86$ | $4.08$ | $5.15$ | $5.57$ | $5.42$ | $5.46$ |

Note. See Table 6 for further description.
and the Shu model (Column (6) of Table 7) for the RA VE data. The Shu model clearly models the wings of
differ from the left only in range and scale of axes. The top panel is for stars with 
Allowing for a vertical dependence of circular speed decreases
χ increased in both RA VE and GCS makes it easier to compare the other
We checked and found that fixing
Figure 6.
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5.2. Shu Models
First, we discuss RAVE results for the case where most of the parameters were free (Column (6) of Table 7). We find that
R_{\text{thin}} is positive, unlike for the Gaussian model. It can be seen from Figure 6 that the wings of the V component of velocity are better fitted by the Shu model than the Gaussian model. Another important feature is that σ_R for the thick disk is almost the same as for the thin disk. The σ_z values are also not too far apart. Apparently, as compared to the Gaussian model, the velocity dispersions for the thick disk are very similar to that of the old thin disk in the Shu model. However, R_{\text{thick}} is shorter than R_{\text{thin}}. If α is set to zero, Θ_0 is underestimated (Column (4)). If we impose the measured proper motion of Sgr A* as a prior, we can constrain the radial gradient of circular speed, which is found to be less than 1 km s^{-1} kpc^{-1} (Column (7)). Comparing Columns (5) and (6), it can be seen that fixing β_z to 0.37 mainly changes σ_{\text{thin}}^2, while the other parameters are relatively unaffected.
The thick-disk parameters for the GCS sample (Column (1) of Table 7) differ significantly from those for the RAVE sample. This is mainly due to the GCS having very few thick-disk stars. We next fix R_{\text{thick}} = 7.58 kpc and R_{\text{thin}} = 13.7 kpc for GCS. Doing so improves the agreement between the two sets for the thick disk, while the change in χ_{\text{red}} is very small (Column (2)). Most RAVE parameters agree to within 4σ of GCS, except for

\text{We checked and found that fixing β_z has negligible impact on other parameters.}
\text{We now let α, free, and this results in a higher value of Θ_0.}
The value of Θ_0 is now close to the proper motion of Sgr A*. Allowing for a vertical dependence of circular speed decreases
R_{\text{thin}} while increasing β_R and β_φ. However, these values are still lower than the GCS values. It can be seen from red lines in Figure 6 that the model does not fit well the projected V components of velocity. Clearly, there are some problems with this model.

\text{We now compare RAVE and GCS results using Columns (6) and (3), where we fix R_{\text{thin}}, R_{\text{thick}}, and α to values that we will get later from the Shu model. Having the same value of R_z in both RAVE and GCS makes it easier to compare the other parameters. Naturally, fixing some of the variables leads to an increased χ_{\text{red}}^2. We find that most of the values agree to within 4σ of each other. The two exceptions are β_φ and V_ϕ, which are higher for GCS.}

\text{To summarize, we find that the model parameters that best fit the RAVE data show important differences from those from GCS. The models differ mostly in their values of R_{\text{thin}} and R_{\text{thick}} with the RAVE values being systematically too high. If R_{\text{thin}} and R_{\text{thick}} are fixed to be the same, then V_ϕ in RAVE is found to be lower by about 2 km s^{-1}. The values of β_φ and β_R are also slightly lower in RAVE and are better constrained than β_z.}

\text{(A color version of this figure is available in the online journal.)}
Figure 7. Comparison of model velocity distributions with that of GCS data. The models used correspond to Columns (2) and (6) of Table 7. These are Shu models that (a) best fit the GCS data, but with a few parameters fixed, and (b) best fit the RAVE data. The positive wing of \( V \) is slightly overestimated by the RAVE best-fit model.

(A color version of this figure is available in the online journal.)

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\( V_\odot \), which is lower by about 2 km s\(^{-1}\) for RAVE. Finally, we also test models where the thick disk is ignored (Column (3)). As in the case of Gaussian models, this leads to an increase in \( \beta \) and \( \sigma \) and decreasing \( R_{\text{thin}} \).

In Figure 5 the best-fit Gaussian and Shu models for GCS are compared. Unlike RAVE, both models provide good fits. In fact, to discriminate the models, one requires a large number of warm stars that can sample the wings of the \( V \) distributions with adequate resolution. The GCS sample clearly lacks these characteristics. Next, in Figure 7 we plot the GCS Shu model alongside the RAVE Shu model (Columns (2) and (6) of Table 7) and compare them with the GCS velocities. It can be seen that both are acceptable fits. However, the RAVE Shu model slightly overestimates the right wing of the GCS \( V \) distribution. Note that in Figure 6 a slight mismatch at \( V' \sim 0 \) can be seen; the cause for this is not yet clear.

6. DISCUSSION

6.1. Correlations and Degeneracies

Not all parameters are independent. The dominant correlations are shown in Figures 8–11 where pairwise posterior distributions of parameters are plotted. The implication of any correlation is that a change in one of the values also changes the other value without affecting the quality of the fit. In other words, a precise value of one correlated quantity needs to be known in order to determine the other. We find that the \( \beta \) values are strongly correlated with the corresponding \( \sigma_{\text{thin}} \) values. This is mainly because we do not have enough information in the data to estimate the ages of stars. The model specifies the prior on the ages of stars, and the data give the velocities. The degeneracy reflects the fact that during fitting \( \beta \) can be adjusted while keeping the mean velocity dispersion constant.

In both thin and thick disks, \( \sigma_R \) is correlated with \( R_{\sigma} \). These correlations are stronger for the Shu model than the Gaussian model. To get a good estimate of \( R_{\sigma} \), ideally one would require a sample of stars distributed over a large volume. In the absence of an extended sample, the constraint on \( R_{\sigma} \) comes from the fact that it also determines the \( \nu_\phi \) distribution. The amount of asymmetric drift increases with \( \sigma_R \) and decreases with \( R_{\sigma} \) (see Equation (6)). If the asymmetric drift is fixed, this naturally leads to the correlation between \( R_{\sigma} \) and \( \sigma_R \). In the Shu model, the effective velocity dispersion \( \sqrt{\langle v_R^2 \rangle} \) not only is proportional to \( \sigma_R \) but also decreases with \( R_{\sigma} \). So one can keep the effective velocity dispersion constant by decreasing both \( R_{\sigma} \) and \( \sigma_R \) at the same time. This makes the correlation in the Shu model stronger.

Also, \( V_\odot \) is correlated with \( R_{\text{thin}} \), and this relation is stronger for the Gaussian model. This makes it difficult to determine \( V_\odot \) and \( R_{\text{thin}} \) reliably using the Gaussian models. The Shu model does not have this problem because in it the azimuthal motion is coupled to the radial motion, so it has three fewer parameters, i.e., has fewer degrees of freedom. This helps to resolve the \( R_{\text{thin}} - V_\odot \) degeneracy.
When fitting Shu models to RAVE, we find that an anti-correlation exists between thin- and thick-disk parameters, e.g., $(\sigma_R^\text{thin}, \sigma_R^\text{thick})$, $(\sigma_\alpha^\text{thin}, \sigma_\alpha^\text{thick})$, and $(R_R^\text{thin}, R_\alpha^\text{thick})$. This is mainly because we do not have any useful information about the ages of stars.

We now discuss the parameters $\Theta_0$ and $\alpha_z$, which were free only for RAVE data. The value of $\alpha_z$ is correlated with $\Theta_0$ and anti-correlated with $V_\odot$. The $\Theta_0$ parameter is anti-correlated with both $U_\odot$ and $R_\odot^\text{thin}$. For the GCS data, the $(\Theta_0, R_\odot^\text{thin})$ correlation is so strong that it is difficult to get meaningful constraints on $\Theta_0$, so the latter was fixed.

### 6.2. Solar Peculiar Motion

Among the three components of solar motion, $U_\odot$ and $W_\odot$ are only weakly correlated with other variables and give similar values for both Gaussian and Shu models. The only major dependence of $U_\odot$ is for RAVE, where it is anti-correlated with $\Theta_0$ by about $-0.5$. So models with $\alpha_z = 0$ that underestimate $\Theta_0$, will overestimate $U_\odot$. For RAVE we get $W_\odot = 7.54 \pm 0.1 \text{ km s}^{-1}$ and $U_\odot = 10.96 \pm 0.14 \text{ km s}^{-1}$ (Column (6) of Table 7). GCS values for $W_\odot$ and $U_\odot$ are lower by about 0.4 and 0.8 km s$^{-1}$, respectively, but their $3\sigma$ range matches with RAVE (Column (2) of Table 7). The small mismatch could be either due to large-scale gradients in the mean motion of stars (Williams et al. 2013) in RAVE or due to kinematic substructures in GCS.

Our GCS results (Column (2) of Table 7) are in excellent agreement with those of Dehnen & Binney (1998b) but differ from those of Schönrich et al. (2010) for $U_\odot$ by 1.0 km s$^{-1}$. Nevertheless, $U_\odot$ is well within their quoted $2\sigma$ range. The RAVE $U_\odot$ agrees with Schönrich et al. (2010). Interestingly, with the aid of a model-independent approach, Schönrich (2012) finds from SDSS stars $U_\odot = 14.0 \pm 0.3 \text{ km s}^{-1}$, but with a systematic uncertainty of 1.5 km s$^{-1}$. The systematic errors in distances and proper motion can bias this result. Additionally, the analyzed sample not being local, his results can also be biased if there are large-scale streaming motions.

We now discuss our results for $V_\odot$. For Gaussian models the estimated $V_\odot$ value depends strongly on the choice of $R_\sigma$ values and it is difficult to get a reliable value for either of them. For the Shu model, $V_\odot$ depends on whether $\alpha_z$ is fixed; in fact, they are anti-correlated (see Figure 11). For $\alpha_z = 0$, the GCS and RAVE agree with Schönrich et al. (2010) finds from SDSS stars $U_\odot = 14.0 \pm 0.3 \text{ km s}^{-1}$, but with a systematic uncertainty of 1.5 km s$^{-1}$. The systematic errors in distances and proper motion can bias this result. Additionally, the analyzed sample not being local, his results can also be biased if there are large-scale streaming motions.

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### 6.3. The Circular Speed

In a recent paper, Bovy et al. (2012a) used data from the APOGEE survey and analyzed stars close to the midplane of the disk to find $\Theta_0 = 218 \pm 6 \text{ km s}^{-1}$ and $V_\odot = 26 \pm 3 \text{ km s}^{-1}$. The resulting angular velocity $\Omega_0 = (\Theta_0 + V_\odot)/R_0$ agrees with the value of $30.24 \pm 0.11 \text{ km s}^{-1} \text{ kpc}^{-1}$ as estimated by Reid & Brunthaler (2004) using the Sgr A* proper motion or as estimated by McMillan & Binney (2010) using masers ($\Omega_2$ in the range $29.9-31.6 \text{ km s}^{-1} \text{ kpc}^{-1}$). However, Bovy et al. (2012a) found that $V_\odot$ is about $14 \text{ km s}^{-1}$ larger than the value measured in the solar neighborhood by GCS. As a way to reconcile their high $V_\odot$, Bovy et al. (2012a) suggest that the LSR itself is rotating with a velocity of $\sim 12 \text{ km s}^{-1}$ with respect to the RSR (rotational standard of rest as measured by circular speed in an axis-symmetric approximation of the full potential of the Milky Way).

For RAVE data, we get $\Theta_0 = 232 \pm 1.7 \text{ km s}^{-1}$ and $\Omega_0 = 29.9 \pm 0.3 \text{ km s}^{-1} \text{ kpc}^{-1}$, which agrees with the proper motion of Sgr A*, $30.24 \pm 0.1 \text{ km s}^{-1} \text{ kpc}^{-1}$. Hence, the RAVE data suggest that the LSR is on a circular orbit and is consistent with RSR. Our value $\alpha_z = 0.047$ is slightly higher than the value 0.0374 predicted by analytical models of the Milky Way potential Figure 1. This is expected because in our formalism, the parameter $\alpha_z$ also contributes to the decrease in mean rotation speed with height. If we explicitly put a prior on $\Theta_0$, then we have the liberty of constraining one more parameter, and we use it to constrain the radial gradient of circular speed $\alpha_R$. Doing so,
we find a small gradient of about 0.67 km s$^{-1}$ kpc$^{-1}$ (Column (7) of Table 7), and $\Theta_0$ increases to 235 km s$^{-1}$.

We find that the parameter $\alpha_z$ that controls the vertical dependence of circular speed plays an important role in determining $\Theta_0$. For models with $\alpha_z = 0$, $\Theta_0$ is underestimated and we end up with $\Theta_0 = 212 \pm 1.4$. This is in rough agreement with Bovy et al. (2012a), but $V_\odot$ is not. The resulting angular velocity $\Omega_\odot$ is also much lower than the value obtained from the proper motion of Sgr A*.

Table 8

| Source | $\beta_R$ | $\beta_\phi$ | $\beta_z$ |
|--------|----------|--------------|-----------|
| Fit to Robin et al. (2003) | 0.33 | 0.33 | 0.33 |
| Nordström et al. (2004) | 0.31 $\pm$ 0.05 | 0.34 $\pm$ 0.05 | 0.47 $\pm$ 0.05 |
| Seabroke & Gilmore (2007) | 0.48 $\pm$ 0.26 |
| Holmberg et al. (2007) | 0.38 | 0.38 | 0.54 |
| Holmberg et al. (2009) | 0.39 | 0.40 | 0.53 |
| Aumer & Binney (2009) | 0.307 | 0.430 | 0.445 |
| Just & Jahreß (2010) | 0.375 |
| Our GCS thin only | 0.27 $\pm$ 0.02 | 0.35 $\pm$ 0.02 | 0.43 $\pm$ 0.02 |
| Our GCS thin+thick | 0.20 $\pm$ 0.02 | 0.27 $\pm$ 0.02 | 0.36 $\pm$ 0.02 |
| Our RAVE thin+thick | 0.19 $\pm$ 0.01 | 0.3 $\pm$ 0.4 |

6.4. The Age–Velocity Dispersion Relation (AVR)

We now discuss our model predictions for the AVR in the thin disk, specifically the parameters $\beta_i = \beta_R, \beta_\phi, \beta_z$, $\sigma_{R,\phi,z}^{thin}$, and $\sigma_R^{thin}$. We find $\beta_R < \beta_\phi < \beta_z$. The GCS $\beta_{R,\phi,z}$ values were similar for both Gaussian and Shu models. The RAVE value of $\beta_R$ from the Shu model also agrees with these GCS values. The value of $\beta_z$ is difficult to determine precisely with RAVE, so, we used the corresponding GCS value in the fits. The values of $\beta_{R,\phi}$ from RAVE with the Gaussian model are systematically lower than the GCS values. Since the RAVE Gaussian model did not fit the data well, we give less importance to its $\beta$ values and ignore them for the present discussion. Overall, results in Column (1) of Table 6 provide a good representation of our predictions and are shown alongside literature values in Table 8.

Our values of $\beta$ and the velocity dispersion in the solar neighborhood for 10 Gyr old stars, $\sigma_{R,\phi,z}^{thin}$, depend on whether the thick disk is considered a distinct component: when only one component is provided, such that the thick disk has to be accommodated by the old tail of the thin disk, these quantities are naturally higher (Column (2) of Table 6). The values we recover for $\sigma_{R,\phi,z}^{thin}$ are very similar regardless of which survey or model we employ.

We now compare our results with previous estimates. In the Besançon model, the AVR for the thin disk was based on an analysis of Hipparcos stars by Gomez et al. (1997). Sharma et al. (2011) fitted their tabulated values using analytical functions, and the values are given in Table 5. Nordström et al. (2004) used their ages for individual GCS stars to find $(\beta_R, \beta_\phi, \beta_z) = (0.31, 0.34, 0.47)$. Seabroke & Gilmore (2007), using the same data, concluded that the error bars need enlarging and pointed out that excluding the Hercules stream increases $\beta_z$ to 0.5.

Holmberg et al. (2007) and Holmberg et al. (2009) updated the data with new parallaxes and photometric calibrations and found $(\beta_R, \beta_\phi, \beta_z) = (0.39, 0.40, 0.53)$. By contrast, Just & Jahreß (2010) used a selection of Hipparcos stars and an elaborate model of the solar cylinder to estimate $\beta_z = 0.375$. Aumer & Binney (2009) analyzed revised Hipparcos data with a refinement of the approach of Binney et al. (2000). Their analysis used only the variation with color of velocity dispersion and number density; they did not use age estimates for individual stars. The advantage of this approach is that one can include main-sequence stars with colors that span a much wider range than the GCS catalogue does. The disadvantage is that only proper motions can be used. They found $(\beta_R, \beta_\phi, \beta_z) = (0.307, 0.430, 0.445)$. Since they did not distinguish the thick disk, their $\beta$ values are closer to the values (0.268, 0.349, 0.432) we obtain without a thick disk. For the velocity dispersions, however, Aumer & Binney (2009) find $(\sigma_{R,\phi,z}^{thin}) = (41.90, 28.82, 23.93)$, which agree better with our values when we include a thick disk.

As (Table 8) shows, our values for $\beta$ are slightly lower than those from previous studies when we do not include a thick disk, and significantly lower when a thick disk is included. While uncertainty in ages remains a big worry in the analysis of Holmberg et al. (2009), the difference between our results and those of Aumer & Binney (2009) is most likely due to different methods, the main differences being that we use many fewer stars and use line-of-sight velocities rather than proper motions. In addition, the density laws assumed for the distribution of stars in space are different. In Figure 12, we show the velocity dispersion as a function of Strömgren $b-y$ color. Although we have not used this color, our fitted model correctly reproduces dispersion as a function of color. The Shu model is found to overpredict $\sigma_V$ for $(b-y) < 0.35$ but only slightly.

The ratio of $\sigma_{b} / \sigma_R$ and the $\beta$ values are useful for understanding the physical processes responsible for heating the disk. Spitzer & Schwarzschild (1953) first showed that scattering of stars by gas clouds can cause velocity dispersion to increase with age. This process was extensively analyzed by Binney & Lacey (1988), but they predicted a value of $\sigma_{b} / \sigma_R$ from cloud scattering that is too large because they assumed an isotropic distribution of star-cloud impact parameters. When the anisotropy of impact parameters is taken into account, in the steady state $\sigma_{b} / \sigma_R = 0.62$ (Ida et al. 1993; Shiihduka & Ida 1999; Sellwood 2008). Hänninen & Flynn (2002) showed that with GMCs one gets $\beta_R = 0.2$ and $\beta_z = 0.25$, compared with our favored values $\beta_R = 0.20$, $\beta_z = 0.36$. However, the population of massive gas clouds is not numerous enough to account for the measured acceleration of thin-disk stars—the role of clouds must be to convert random motion in the plane into random motion vertically (Jenkins 1992; Hänninen & Flynn 2002).

Lacey & Ostriker (1985) and Hänninen & Flynn (2002) have investigated scattering by $\sim 10^7 M_\odot$ halo objects such as black holes and found that $\beta_R > \sim 0.5$ and that $\sigma_{b} / \sigma_R$ lies between 0.40 and 0.67. Massive halo objects act differently from GMCs for several reasons: they are not confined to the disk, they are on highly noncircular orbits, and they have large escape velocities, so they can scatter through large angles.

For RAVE, from either the Gaussian or Shu models, we get $\sigma_{b} / \sigma_R \approx 0.65$ (Column (6) of Table 6 and Column (6) of Table 7). The corresponding GCS value is 0.58 (Column (3) of Table 6 and Column (2) of Table 7). Models without a thick disk give a similar value for $\sigma_{b} / \sigma_R$. These are values for a 10 Gyr old population, and we think they agree well with the above
predicts. For the thick disk we find that the Gaussian model predicts $\sigma_{\text{thick}}^{\text{thick}}/\sigma_{\text{thick}} = 0.68$, while the Shu model predicts a higher value, 0.80.

Heating by cloud scattering predicts $\beta_R \sim \beta_z$. Scattering by spiral arms at Lindblad resonances also heats disks. If spiral arms are transient, individual resonances are broad, and over the life of the disk one or more resonances are likely to have affected every region of the disk. Spirals only increase in-plane dispersions (Carlberg & Sellwood 1985; Binney & Lacey 1988; Sellwood 2013). The predicted values of $\beta_R$ are between 0.2 for high-velocity stars and 0.5 for low-velocity stars. Multiple spiral density waves (Minchev & Quillen 2006) or a combination of bar and spirals can also heat up the disk (Minchev & Famaey 2010). When the $\beta_i$ differ from one another, as we find, the axial ratios of the velocity ellipsoid are functions of age. If $\beta_i > \beta_R$, $\sigma_z/\sigma_R$ increases with age as $\tau^{1-\beta_z}$, so it is much lower for younger stars. Aumer & Binney (2009) also find that $\sigma_z/\sigma_R$ increases with age and remark that this trend is consistent with scattering by spiral arms playing a significant role for young stars.

Recently, Minchev et al. (2013) investigated the AVR for stars in simulations of disk galaxies and find it to be in rough agreement with observations. We now compare our results with their findings. In Figure 13 we plot their predictions for $\sigma_R$ and...
Figure 9. Marginalized posterior distribution of model parameters. The numbers are the linear Pearson correlation coefficient. Shown is the case of Shu model for GCS data (Column (1) of Table 7). The same dependencies as in Figure 8 can be seen. Dependency of ($R^\text{thin}_{\odot}$, $V_\odot$) has gotten weaker, while that of ($R^\text{thick}_{\odot}$, $\sigma_R^\text{thick}$) has become stronger.

(A color version of this figure is available in the online journal.)

$\sigma_z$ for stars in a solar cylinder defined by $7 < R < 9$ kpc. The red curves show our AVR from Equation (8) with $\beta_z = 0.37$ and $\beta_R = 0.23$, values that fit both the RAVE and GCS data well when using the Shu model (Column (2) of Table 7). It can be seen that for ages less than 7 Gyr, the adopted $\beta$ values correctly reproduce the profiles seen in simulations. However, the simulations require a smaller value $\sigma_z/\sigma_R \sim 0.5$ than the data require, and the red curves in Figure 13 have been individually scaled to fit the simulations. Hence, although the normalization constant $\sigma_z^\text{thin}$ is roughly in agreement with our results for the Galaxy, the normalization constant $\sigma_R^\text{thin}$ is too high by about 10 km s$^{-1}$. There is a slight hint that in the simulations $\sigma_R$ flattens beyond 5 Gyr, but it is also consistent with our power-law prescription. Since the simulation data are for $7 < R < 9$ kpc, and the density of stars and the velocity dispersion increase inward, the dispersions in the simulations are expected to be slightly high compared to dispersions at $R = R_0$. In our model the thin disk started forming 10 Gyr ago (solid line), and stars older than this belong to the thick disk with a constant age of 11 Gyr (shown by red triangles). This is an effective if rather crude representation of what is found in the simulations.
Finally, the Gaussian model to GCS (Column (3) of Table 6) are in good agreement with results of Soubiran et al. (2003). In the Shu models, we find that the thick-disk dispersions are very similar to the old thin disk (Column (6) of Table 7). However, $R_{\text{thick}}^{\text{stellar}}$ is much shorter than $R_{\text{thin}}^{\text{stellar}}$. The Gaussian and Shu models differ in their estimates for the thick-disk velocity dispersions for the following reason. In the Shu model, the parameter $\sigma_R^2$, which controls the velocity dispersion, is a function of age $\tau$ and guiding radius $R_g$ and is not equal to the velocity dispersion $\sigma_R^2(\tau, R)$. For a positive $R_g$, $\sigma_R^2(\tau, R) = \int \sigma_R^2(\tau, R_g) P(R_g|R, \tau) dR_g > \sigma_R^2(\tau, R_g = R)$. In a warm disk there are generally a significant number of stars with $R_g < R$ at radius $R$. Decreasing $R_g$ not only makes stars at small radii hotter but also makes them more likely to be found

![Figure 10](image-url)  
Marginalized posterior distribution of model parameters. The numbers are the linear Pearson correlation coefficient. Shown is the case of Gaussian model for RAVE data (Column (5) of Table 6). Strong dependency can be seen between $\beta$ and $\sigma_{\text{thick}}$ values. Additionally, $(R_{\text{thick}}^{\text{stellar}}, V_\odot)$ and $(R_{\text{thick}}^{\text{stellar}}, \sigma_R^{\text{thick}})$ also show dependency. Finally, the $\theta_0$ is anti-correlated to $U_\odot$ and $\alpha_z$ to $V_\odot$.

(A color version of this figure is available in the online journal.)

6.5. The Thick Disk

First, we discuss our results for the Gaussian model. Our values for $(\sigma_R^{\text{thick}}, \sigma_{\phi}^{\text{thick}}, \sigma_z^{\text{thick}})$ for the thick disk from fitting the Gaussian model to GCS (Column (3) of Table 6) are in good agreement with results of Soubiran et al. (2003) (39 ± 4, 39 ± 4, 63 ± 6) but differ from those of Robin et al. (2003) regarding $\sigma_{\phi}^{\text{thick}}$. The RAVE $\sigma_R^{\text{thick}}$ is lower than GCS by 7 km s$^{-1}$ (Column (6) of Table 6), but the other dispersions match up with GCS.

In the Gaussian model the thick-disk velocity dispersions are much larger than those of the old thin disk. In the Shu models, we find that the thick-disk dispersions are very similar to the old thin disk (Column (6) of Table 7). However, $R_{\text{thick}}^{\text{stellar}}$ is much shorter than $R_{\text{thin}}^{\text{stellar}}$. The Gaussian and Shu models differ in their estimates for the thick-disk velocity dispersions for the following reason. In the Shu model, the parameter $\sigma_R^2$, which controls the velocity dispersion, is a function of age $\tau$ and guiding radius $R_g$ and is not equal to the velocity dispersion $\sigma_R^2(\tau, R)$. For a positive $R_g$, $\sigma_R^2(\tau, R) = \int \sigma_R^2(\tau, R_g) P(R_g|R, \tau) dR_g > \sigma_R^2(\tau, R_g = R)$. In a warm disk there are generally a significant number of stars with $R_g < R$ at radius $R$. Decreasing $R_g$ not only makes stars at small radii hotter but also makes them more likely to be found.
at $R > R_*$, so decreasing $R_*$ increases $\sqrt{v_R^2(\tau, R)}$. For the set of parameters given in Column (6) of Table 7, we find that at $R = R_0$, 

$$\sqrt{v_{z, \text{thin}}^2(\tau)} = 26.8 \left( \frac{\tau + 0.1}{10.1 \text{ Gyr}} \right)^{0.41} \text{ km s}^{-1},$$

(33)

$$\sqrt{v_{z, \text{thick}}^2(\tau)} = 41.4 \left( \frac{\tau + 0.1}{10.1 \text{ Gyr}} \right)^{0.22} \text{ km s}^{-1},$$

(34)

with $0 < \tau < 10 \text{ Gyr}$. So the total thick disk $\sqrt{v_{z, \text{thick}}^2}$ in the solar neighborhood is still much larger than that of the thin disk.

In the Shu model the dispersions at $R_* = R_0$ of the old thin disk and the thick disk are similar, consistent with the thick disk...
being merely the tail of the thin disk. Moreover, although $R_{\text{thick}}^{\text{Shu}}$ is much smaller than $R_{\text{thick}}^{\text{min}}$, we cannot at this stage exclude a smooth decrease in $R_\sigma$ with age. Additionally, our prior on age and distance distribution assumes a distinct thick disk, e.g., in

Figure 12. Velocity as a function of $b-y$ Stromgren color for GCS stars. The error bars were estimated from Poisson noise. Shown alongside are predictions from various models. Note that the color distribution was not taken into account when fitting models to data. (A color version of this figure is available in the online journal.)

Figure 13. Comparison of our AVR (solid line) with that of Minchev et al. (2013) (black points). The slopes used are $\beta_z = 0.37$ and $\beta_R = 0.23$ for $\sigma_R = 50.0$ and $\sigma_z = 24.0$. The triangles are for the thick disk in our Gaussian models for GCS. (A color version of this figure is available in the online journal.)

Table 9

| Model | RAVE BOVY | RAVE BOVY | RAVE BOVY | RAVE BOVY |
|-------|-----------|-----------|-----------|-----------|
| $U_0$ | $10.16^{+0.15}_{-0.15}$ | $11.78^{+0.13}_{-0.15}$ | $11.59^{+0.15}_{-0.14}$ | $10.96^{+0.14}_{-0.14}$ |
| $V_0$ | $13.36^{+0.25}_{-0.22}$ | $6.2^{+0.18}_{-0.18}$ | $8.77^{+0.26}_{-0.28}$ | $0.032^{+0.052}_{-0.024}$ |
| $W_0$ | $7.364^{+0.098}_{-0.098}$ | $7.688^{+0.09}_{-0.09}$ | $7.694^{+0.097}_{-0.089}$ | $7.622^{+0.094}_{-0.087}$ |
| $\alpha_{\text{min}}$ | $26.455^{+0.095}_{-0.096}$ | $33.11^{+0.26}_{-0.27}$ | $25.83^{+0.26}_{-0.38}$ | $33.84^{+0.26}_{-0.27}$ |
| $\sigma_R^{\text{min}}$ | $41.39^{+0.17}_{-0.16}$ | $57.58^{+0.31}_{-0.31}$ | $41.55^{+0.57}_{-0.62}$ | $51.44^{+0.29}_{-0.27}$ |
| $\sigma_z^{\text{min}}$ | $22.99^{+0.12}_{-0.12}$ | $31.55^{+0.3}_{-0.3}$ | $23.29^{+0.6}_{-0.6}$ | $33.6^{+0.29}_{-0.29}$ |
| $\sigma_R^{\text{black}}$ | | | | $37.45^{+0.56}_{-0.56}$ |
| $\sigma_z^{\text{black}}$ | | | | $65.69^{+0.55}_{-0.64}$ |
| $\beta_R$ | $0.01$ | $0.4584^{+0.0071}_{-0.0066}$ | $0.193^{+0.013}_{-0.012}$ | $0.3568^{+0.0045}_{-0.0049}$ |
| $\beta_z$ | $0.01$ | $0.3747^{+0.0033}_{-0.0034}$ | $0.166^{+0.013}_{-0.013}$ | $0.4151^{+0.0081}_{-0.0093}$ |
| $\rho_0$ | $0.01$ | $0.514^{+0.016}_{-0.016}$ | $0.263^{+0.025}_{-0.027}$ | $0.588^{+0.013}_{-0.016}$ |
| $\rho_R$ | $0.01$ | | | $0.0493^{+0.0026}_{-0.0024}$ |
| $\rho_z$ | | | | $0.0116^{+0.0051}_{-0.0055}$ |
| $1/R_{\sigma_{\text{min}}}$ | $-0.023^{+0.003}_{-0.005}$ | $0.0493^{+0.0026}_{-0.0024}$ | $0.0116^{+0.0051}_{-0.0055}$ | $0.0418^{+0.0028}_{-0.0031}$ |
| $k_{\text{rad}}$ | $0.069^{+0.0038}_{-0.0039}$ | | | | $0.968^{+0.022}_{-0.021}$ |
| $\Phi_0$ | $210.8^{+1.5}_{-1.6}$ | $205.5^{+1.5}_{-1.4}$ | $213.9^{+1.6}_{-1.5}$ | $239.1^{+1.7}_{-1.9}$ |

Note. See Table 6 for further description.

Figure 3 it can be seen that the distance distribution changes suddenly at 10 Gyr. This could be responsible for $R_{\text{thick}}$ being shorter than $R_{\text{thick}}^{\text{min}}$, perhaps because all scale lengths decrease with age as Bovy et al. (2012d) infer.

6.6. The Radial Gradient of Velocity Dispersions

To date, there has been little discussion in the literature about the parameter $R_\sigma$ that controls the radial dependence of velocity dispersion. This choice of the radial dependence is motivated by the desire to produce disks in which the scale height is independent of radius. For example, under the epicyclic approximation, if $\sigma_z/\sigma_R$ is assumed to be constant, then the scale height is independent of radius for $R_\sigma = 2 R_d$ (van der Kruit & Searle 1982; van der Kruit 1988; van der Kruit & Freeman 2011). Lewis & Freeman (1989), using 600 old disk K giants spanning 1–17 kpc in galactocentric radius, estimate $R_\sigma$ to be 8.7 kpc for radial velocity and 6.7 kpc for azimuthal velocity. Ojha et al. (1996), using a survey of $UBVR$ photometry and proper motions in different directions of the Galaxy, estimated $R_\sigma = 11 \pm 1.6$ kpc. Bovy et al. (2012c), using SDSS/SEGUE data, find $R_\sigma = 7.1$ kpc for vertical velocity dispersions. Bovy et al. (2012a), using APOGEE data, find $R_\sigma/R_d$ to be between $-0.24$ and 0.03, for the radial and azimuthal motion. In our modeling, the radial gradient is assumed to be the same for all three components.

Our results indicate that for GCS, $R_\sigma$ is positive for both Gaussian and Shu models. In the case of RAVE, the Shu model yields $R_\sigma \sim 14$ kpc, but the Gaussian model requires $R_\sigma$ to be negative. Moreover, we find that when the Gaussian model used by Bovy et al. (2012a) is fitted to the RAVE data, $R_\sigma$ is again negative: $R_{\sigma_{\text{min}}} = -34$ kpc (Column (1) of Table 9), similar to their result ($-0.24 < R_\sigma < 0.03$). Since the Shu model also fits the data better, we think that negative values of $R_\sigma$ obtained with Gaussian models are spurious. The Gaussian model does not fit the RAVE data well because in a warm disk the $\nu_\phi$ distribution is very skew, and the Shu DF correctly handles
the asymmetry. Moreover, the $R_{\text{thin}}$ estimate from the Shu model agrees for both GCS and RAVE, lending further support to the proposition that the problem is related to the use of the Gaussian model.

Positive $R_c$ agrees with the findings of Lewis & Freeman (1989). It should be noted that in both our analysis and that of Bovy et al. (2012a) the value of $R_c$ is strongly influenced by how the asymmetric drift is modeled. On the other hand, the values reported by Lewis & Freeman (1989) are a direct measure of the radial gradient of velocity dispersion. From RAVE data, the thick disk’s value of $R_c$ is in general higher than the thin disk’s value.

6.7. Comparison with Bovy’s Kinematic Model

We carried out a more detailed analysis of the kinematic model used by Bovy et al. (2012a). We stress that there are significant differences regarding both data and methodology between the analysis done by us and that by Bovy et al. (2012a), and these should be kept in mind when comparing the results. Their sample is close to the plane $|b| < 1.5^\circ$ and lies in the range $30^\circ < \ell < 330^\circ$. Being close to the plane, they cannot measure vertical motion, but the advantage is that they do not have to worry about the dependence of asymmetric drift with vertical height $z$. The $\ell$ and $b$ range being different means that their data and ours probe spatially different regions of the Milky Way. If the disk is axisymmetric, we hope to get similar answers, but not otherwise.

Their main analysis uses a single-population Gaussian model that does not include an AVR, so we set $\beta_\ell = \beta_\phi = 0$. They use a modified formula for the asymmetric drift (Equation (7)). In this formula we set the parameter $k_{\text{sd}}$ (in the notation of Bovy et al. 2012a) to 0.85. Our results are shown in Column (1) of Table 9. As mentioned earlier, using RAVE data and a Gaussian model, we obtain a negative value of $R_{\text{thin}} = -34$ kpc, just as they do, in consequence of modeling a warm population with a Gaussian model. Our value of $\Theta_0$ is also in agreement, but our $\sigma_R$ is much larger than their value, 31.4 km s$^{-1}$. Their sample could be dominated by cold stars on account of its proximity to the plane. They find $\sigma_\phi/\sigma_R = 0.83$, which is higher by about 0.1 than our ratio for either RAVE or GCS using any type of model.

They also explored multiple populations with a prior on age given by an exponentially declining SFR. However, they only quote $\Theta_0$, $R_0$ and $\sigma_R$ for it. For multiple populations, their prior on age for the selected stars ignores the fact that scale height increases with age. This will probably have little impact on $\Theta_0$, but their $\sigma_R$ values cannot be compared with ours. Also, they assume a priori that $\beta_R = \beta_\phi = 0.38$, but we have shown that $\sigma_R$ depends on the choice of $\beta_R$, and when we leave $\beta$ free, we obtain values that differ from 0.38 (Column (2) of Table 9). If the thick disk is included, the $\beta$ values are significantly reduced (Column (3)). In agreement with Bovy et al. (2012a), we find that the value of $\Theta_0$ is not affected much by the choice of AVR. Including the thick disk leads to an increase in $\Theta_0$ by only 8 km s$^{-1}$. Interestingly, when $k_{\text{sd}}$ is left free, we find that the data favor very high values (Column (4)). This suggests that we are underestimating the asymmetric drift, most probably owing to our neglect of the vertical dependence.

6.8. Systematics

Although we get quite precise values for most model parameters, there are additional systematic uncertainties that we have neglected. We performed some additional MCMC runs to investigate these systematics. The results are summarized in Table 10. The first set of systematics is due to two parameters that were kept fixed in our analysis, while the second set is related to our choice of priors on the age and distance distribution of stars.

The distance of the Sun from the Galactic center $R_0$ and the radial gradient of circular speed $\alpha_R$ were kept fixed at 8.0 kpc and zero for most of our analysis. This is because these are strongly correlated with $\Theta_0$. Using just the angular position and radial velocity of RAVE stars, it is not possible to constrain them. The effect of changing $R_0$ from 7.5 to 8.5 kpc can be seen in Columns (1) and (2) of Table 10, while the effect of changing $\alpha_R$ from zero to 0.65 km s$^{-1}$ kpc$^{-1}$ can be gauged by comparing Columns (1) and (2) in the same table. Using these tables, if needed one can obtain values for any given $R_0$ and $\alpha_R$ by linearly interpolating between the respective columns. Increasing $R_0$ increases $\Theta_0$, while the other parameters are relatively unaffected. Increasing $\alpha_R$ increases $\alpha_z$ as well as $\Theta_0$. Again, there is little change in other parameters. The value of $\Omega_0$ was found to decrease from 30.8 km s$^{-1}$ kpc$^{-1}$ at $R_0 = 7.5$ kpc to 29.4 km s$^{-1}$ kpc$^{-1}$ at $R_0 = 8.5$ kpc. The above relationship tentatively suggests that at $R_0 \sim 7.92$ one can match the proper motion of Sgr A*.

We also checked the effect of setting $\alpha_z = 0.0374$, the value we expect from analytical models. We found that this makes $\Theta_0 \sim 229.2$ km s$^{-1}$ and $V_\odot \sim 8.0$, which is not significantly far from the value we get when $\alpha_z$ is free.

We now discuss systematics related to our choice of priors. Our main prior is that the age and distance distribution of stars along a particular line of sight is in accordance with the Besançon model of the Galaxy. Additionally, the distance distribution for a given $\mu_{\text{DENIS}}$ magnitude of a star depends on the isochrones that are used in the model. As a crude way to gauge the sensitivity to our priors in age, we run a model with $\beta_\ell = \beta_R = 0.01$ (Column (7)), which makes the kinematics of the thin disk independent of age. As expected, the thin- and thick-disk parameters change. Other than this, $\alpha_z$ and $\Theta_0$ are found to increase by 12% and 2%, respectively.

Next, we test the effect of changing the distance prior. This could be, for example, due to a systematic offset in magnitudes predicted by the isochrones. For this we alternately increase and decrease our prior distance distribution by multiplying the distances by a factor of 1.1 and 0.9. The values of $V_\odot$, $\Theta_0$, and $R_{\text{thin}}$ show significant changes. It should be noted that this is only an approximate way to check the sensitivity of our results on the priors. In reality, if magnitudes predicted by isochrones are systematically wrong, then the spatial density model that we use will not match the number count of stars obtained from photometric surveys. So, the mass density laws of the model will have to be modified as well. The proper way to do this is to do a dynamical modeling in which the kinematics and the spatial distribution of stars are fitted jointly to the observational data (e.g., Binney 2012b).

The biggest source of systematic uncertainty is related to the accuracy of the theoretical models that we use. As discussed earlier in Section 2.4, our treatment of the vertical dependence of the kinematics is not fully self-consistent. In reality, for a three-dimensional system, the vertical and planar motions are coupled to each other. To model such a system properly, one needs a DF that incorporates the third integral of motion. Finally, our models will give rise to errors because they are kinematic rather than dynamical models. Kinematic models offer greater freedom than physics really allows. For example, the parameters $\sigma_R$ and $\sigma_\phi$ of the Gaussian model are tightly
coupled, as are $\beta_R$ and $\beta_\phi$. The Shu model has fewer free parameters and so is less open to this criticism, but it fails to take into account the coupling between the vertical profiles of $\sigma_R$ and the mean-streaming velocity $v_\phi$ (e.g., Binney 2012a). It is not unreasonable to hope that the values that emerge from the fits for fundamentally superfluous parameters are similar to the values truly mandated by physics, but noise in the data may confound this hope. Clearly, we should proceed as quickly as possible to fitting RA VE with dynamical models like those developed by Binney (2012a).

7. SUMMARY AND CONCLUSIONS

In this paper we have constrained the kinematic parameters of the Milky Way disk using stars from the RAVE and the GCS surveys. To constrain kinematic parameters, we use analytic kinematic models based on the Gaussian and Shu DFs. We use these DFs, Padova stellar tracks (Marigo et al. 2008; Bertelli et al. 1994), and the selection functions of the surveys to predict the likelihood of each observed star. For GCS data, which has full phase-space information for the stars, we compute the likelihood in ($\ell$, $b$, $v_{\text{hel}}$) phase space. For RAVE data, we choose to fit the likelihood in ($\ell$, $b$) space to avoid use of uncertain distances and proper motions. We explored the full posterior distribution of model parameters using the MCMC technique. The parameters constrained include the solar peculiar motion ($U_\odot$, $V_\odot$, $W_\odot$), the circular speed at the Sun $\Theta_0$, a parameter $\alpha_z$ that controls the vertical gradient of $R \delta \Phi / \partial R$, the AVRs (via $\beta_R$, $\beta_\phi$, $\sigma_R$, $\sigma_\delta$, $\sigma_\Phi$, $\sigma_\Psi$, $\sigma_\beta_R$, $\sigma_\beta_\phi$, $\sigma_\alpha_z$, $\sigma_\alpha_\phi$, $\sigma_\psi$, $\sigma_\phi$, $\sigma_\theta$), and the scale lengths on which the dispersions vary, $R_{\text{thin}}^{\delta\Phi}$ and $R_{\text{thick}}^{\delta\Phi}$. Our results for both RAVE and GCS data are summarized in Tables 6 and 7. The final best-fit model is given in Table 11.

The main assumption we make is that we assume an SFR, IMF, and density laws that describe the spatial distribution of stars in accordance with the Besançon model of Robin et al. (2003), but with slight modifications as described in Sharma et al. (2011). This model provides a good fit to the photometric star counts of the Milky Way. Thus, the kinematic results that we present are in some sense in the context of the model for the spatial distribution of stars that we adopt. Moreover, kinematic models offer greater freedom than physics really allows. To overcome these concerns, one should fit both the kinematics and the spatial distribution of stars together, and they should be dynamically linked via the potential in which the stars move.

One could in principle constrain model parameters using the two surveys, RAVE and GCS, simultaneously. However, the two surveys probe different volumes, and it is not clear that a
single value of a given parameter, for example, the solar motion $U_\odot$, is appropriate for both volumes: the immediate vicinity of the Sun may be moving with respect to the wider disk, for example. If such systematic differences exist, the simple models we are fitting cannot provide an adequate account of the entire body of data, and parameter values obtained from a joint fit will be of doubtful physical significance. Hence, in this paper we first analyzed the surveys separately and tried to understand the systematics. Then, having understood the extent to which each survey constrained each parameter, we fixed values of some parameters from the results of one survey while analyzing the other. We do this only for those parameters that we believe should take the same values for both surveys.

The Gaussian model proves to be unsuitable for estimating disk parameters such as $R_\text{thin}$ and $V_\odot$ because the fits prove to be strongly degenerate. The Gaussian model gives different values of $R_\text{thin}$ for RAVE and GCS. For RAVE it predicts negative values, implying that $\sigma_R$ increases outward. This result is inconsistent with the disk’s scale height and value of $\sigma_z/\sigma_R$ being constant. Negative values of $R_\text{thin}$ also disagree with the findings of Lewis & Freeman (1989). The Shu model has three fewer parameters than the Gaussian model, and this helps it to break the degeneracy between $R_\text{thin}$ and $V_\odot$. It gives positive and consistent values for $R_\text{thin}$ for both RAVE and GCS. The Shu model also fits the RAVE data better than the Gaussian model, especially with regard to stars’ values of $\Theta_0$.

The RAVE data allow us to constrain the solar peculiar motion and the local circular speed quite precisely. Our $U_\odot$ and $W_\odot$ are in good agreement with the results of Schönrich et al. (2010), but our $V_\odot$ is lower by 5 km s$^{-1}$. The RAVE $U_\odot$ and $W_\odot$ are within $2\sigma$ range of GCS values, but $V_\odot$ is lower by 2 km s$^{-1}$. Using $R_0 = 8.0$ kpc and assuming $\partial v_i/\partial R = 0$, we get $\Theta_0 \sim 232$ km s$^{-1}$. Combining the estimates of $\Theta_0$ and $V_\odot$, we find the solar angular velocity with respect to the Galactic center to be in good agreement with the measured proper motion of Sgr A*. We find that if the fall of mean azimuthal velocity with height $z$ above the midplane is neglected, then this leads to an underestimation of $\Theta_0$.

Although our random uncertainty regarding most parameters is quite small, owing to a large number of stars in the RAVE survey, significant sources of systematic uncertainty remain, especially regarding $\Theta_0$ and $V_\odot$. Our treatment of the vertical dependence of the kinematics is not fully self-consistent. This needs to be investigated with models that can handle the third integral of motion, e.g., models based on action integrals. Also, we need to explore dynamical models that are self-consistent rather than pure kinematic models as studied here. The values of $\Theta_0$ and $V_\odot$ are also sensitive to the priors on age and distance distribution of stars. Hence, systematic errors of the order of the uncertainty in the priors are also expected.

When using the Shu model, all parameters except $V_\odot$ and thick-disk parameters show similar values for RAVE and GCS. Since there are very few thick-disk stars in GCS, we deem the RAVE thick-disk parameters to be more reliable. Also, the uncertainty on $R_\text{thin}$ and $R_\text{thick}$ is substantially less for RAVE than for GCS. The only parameter that is constrained better by GCS than RAVE is $\beta_z$, and this is partly due to the fact that we only use radial velocities in RAVE. In an attempt to build a concordance model, and to enable better comparison between the two data sets, we fix $\beta_z$ in RAVE to GCS values and then fix $R_\text{thin}$ and $R_\text{thick}$ in GCS to RAVE values. Doing so, we find that RAVE results are within $3\sigma$ of GCS results. The most significant difference between the two is the value of $V_\odot$, which is lower for RAVE by about 2 km s$^{-1}$. The presence of prominent kinematic substructures in GCS could be responsible for this discrepancy. However, inaccuracy in our vertical treatment of kinematics could also be responsible.

We find that the AVR in general satisfy $\beta_R < \beta_\odot < \beta_z$, with $\beta_\odot$ closer to $\beta_R$ than $\beta_z$, contrary to the finding of Aumer & Binney (2009). This result is consistent with the physical principle that peculiar motions in the radial and azimuthal directions are strongly coupled by epicyclic dynamics and largely decoupled from vertical motions. The fitted $\beta$ values depend on whether the thick disk is added separately or is left to be represented by the old tail of the thin disk, and they are naturally higher when it is not added separately. The axial ratio $\sigma_z/\sigma_R$ of the thin-disk velocity ellipsoid for the 10 Gyr population is consistent with those predicted by Sellwood (2008) for cloud scattering. Our values of $\beta_R$ and $\beta_\odot$ agree well with age-velocity profiles measured by Minchev et al. (2013) for ages $\lesssim 7$ Gyr in simulations of disk galaxies. At ages larger than 7 Gyr, a model that consists of power-law growth in the thin disk combined with a distinct thick-disk population is too crude to represent the simulations adequately. In the future it may be appropriate to use more elaborate models inspired by simulations.

In the Shu model, the thick-disk velocity dispersions for $R_z = R_t$ are very similar to those of the old thin disk. However, the radial scale length of the thick-disk velocity dispersions, $R_\text{thick}$, proved to be much smaller than that of the thin disk. Bovy et al. (2012d) suggested a decrease of radial density scale length with age. In this regard, the role of our adopted priors on age and distance distribution of stars needs to be investigated further.

Given the essential role that age plays in disk dynamics, it is unfortunate that the ages of stars are so hard to measure. Fortunately, big advances in this area are expected soon. Stellar astroseismology with missions like CoRoT and Kepler makes it possible to measure ages more accurately than before (Chaplin et al. 2010, 2011; Appourchaux et al. 2008), and Gaia will dramatically improve age estimates by geometrically determining distances to large numbers of stars. Meanwhile, chemical abundances, especially of the alpha elements, provide a fair proxy for age at a given metallicity. Hence, studying the relationship of kinematic properties with abundance will be crucial. Bovy et al. (2012d) argued that each mono-abundance population has a distinct spatial distribution, and we expect cohorts of coeval stars to have spatial distributions that are characteristic of their ages.
