Non-Abelian Moduli on Domain Walls

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Abstract

We study a simple model supporting domain walls which possess two orientational moduli in addition to the conventional translational modulus. This model is conceptually close to Witten’s cosmic strings. We observe an $O(3)$ sigma model on the wall world volume in the low-energy limit. We solve (numerically) classical static equations of motion and find the wall profile functions and the value of the coupling of the $O(3)$ model in terms of the bulk parameters. In the second part a term describing a spin-orbit interaction in the bulk is added, which gives rise to an entanglement between rotational and translational moduli. The corresponding extra term in the low-energy Lagrangian is calculated.
1 Introduction

Some field theories support topological defects with non-Abelian moduli on the world volume of these defects. This discovery was first made in 2003 in the context of supersymmetric Yang-Mills theories with matter (for a thorough review and an extensive list of references see [1]). Since then much effort has been invested in the studies of the so-called non-Abelian strings – topological defects of codimension two. In this paper we develop a similar construction of codimension one, i.e. non-Abelian walls. To this end we generalize the analysis of the simplest model [2] supporting topologically stable strings with non-Abelian moduli. The model [2] was inspired by Witten’s construction for cosmic strings [3] and used in [4, 5, 6] to study diverse effects associated with non-Abelian moduli on the string world sheet.

Our task is to identify non-Abelian moduli on domain walls and study their low-energy dynamics. We will show that, as in [2], the latter will be described by the O(3) sigma model. Then we deform our basic model by adding a Lorentz violating term of a special form (relevant to condense-matter systems) in the bulk. This term (similar to that in [5]) leads to a coupling between translational and orientational moduli.

The qualitative non-Abelian string picture [2] is supported in the wall case by numerical calculations, in a way similar to that in [6] for the Abrikosov-Nielsen-Olesen string. In the wall case the emphasis is put on qualitative aspects too, rather than on exact results. Calculations are carried out in the quasiclassical approximation at weak coupling.

We begin with a simple domain wall in a model of a single real scalar field, and then add an extra term with a \( \chi^i \) field in the Lagrangian. It is shown that the standard domain wall solution becomes unstable. A nonvanishing \( \chi^i \) develops in the wall core resulting in rotational moduli. For a fixed set of parameters the two-field solution is found numerically from the standard Euler-Lagrange equations. We discuss both translational and rotational moduli. In the last part a spin-orbit interaction is introduced. It gives rise to an entanglement of translational and rotational moduli.

\[ ^1 \text{In [2] the basic idea of domain walls with non-Abelian moduli due to the “\( \chi \)-structure” (see below) was outlined, but calculations of the wall profiles were not carried out.} \]

\[ ^2 \text{For technical reasons the relevant coupling constants, although small, are not too small. We are at the borderline of the quasiclassical domain.} \]
2 Domain wall and an additional field

Let us start from a simple model of a single real scalar field, described by the Lagrangian

\[
\mathcal{L}_0 = \frac{1}{2} \partial_\mu \varphi \partial^\mu \varphi - V(\varphi), \quad V(\varphi) = \lambda (\varphi^2 - v^2)^2, \tag{1}
\]

where \(\lambda\) and \(v\) are constants. This Lagrangian obviously possesses a \(\mathbb{Z}_2\) symmetry \((\varphi \rightarrow -\varphi)\) which is spontaneously broken in the vacuum. Hence, the model supports domain walls. In this model there are two physically equivalent vacua. For a wall, oriented in the \((x, y)\) plane, we have the boundary condition \(\varphi = \pm v\) for \(z = \mp \infty\) (or vice versa). In this case the solution for \(\varphi\) can be found analytically,

\[
\varphi(z) = -v \tanh \left[ \frac{m_\varphi}{2} (z - z_0) \right], \tag{2}
\]

where \(m_\varphi = \sqrt{8\lambda v^2}\) is the mass of the \(\varphi\) field, and \(z_0\) is the wall center. The minus sign in the right-hand side of (2) was chosen for convenience of the subsequent consideration.

Now let us add, according to [2], a triplet field \(\chi^i, i = 1, 2, 3\), described by the Lagrangian

\[
\mathcal{L}_\chi = \frac{1}{2} \partial_\mu \chi^i \partial^\mu \chi^i - U(\chi, \varphi), \\
U(\varphi, \chi^i) = \gamma \left[ (\varphi^2 - \mu^2) \chi^i \chi^i + \beta (\chi^i \chi^i)^2 \right], \quad v^2 > \mu^2. \tag{3}
\]

The deformed model with the extra field \(\chi^i\) is described by the Lagrangian

\[
\mathcal{L} = \mathcal{L}_0 + \mathcal{L}_\chi. \tag{4}
\]

In the vacuum, where \(\varphi = \pm v\), the expectation value of \(\chi\) is 0, but in the core of the wall, where \(\varphi\) is small, \(\chi\) develops a non-vanishing expectation value

\[
\chi_0 \approx \sqrt{\frac{\mu^2}{2\beta}}. \tag{5}
\]
3 Instability of the $\chi = 0$ solution

The stability analysis is similar to that in [3] and [6]. Let us assume that the field $\varphi$ is given by (2) and $\chi$ is small. This allows us to work in the quadratic in $\chi$ approximation. We have the following energy functional

$$E_\chi = A \int \left[ \frac{1}{2} \left( \frac{\partial \chi}{\partial z} \right)^2 + \gamma (\varphi^2 - \mu^2) \chi^2 \right] dz,$$

where $A$ is the area of the wall. After integration by parts we arrive at

$$E_\chi = A \int \left[ -\frac{1}{2} \chi \frac{\partial^2 \chi}{\partial z^2} + \gamma (\varphi^2 - \mu^2) \chi^2 \right] dz. \tag{7}$$

Whether or not $\chi = 0$ is a stable solution depends on the eigenmodes of the operator in (7). Existence of negative mode(s) will imply instability.

The eigenvalue equation can be interpreted as a Schrödinger equation. Taking $\varphi$ from (2) directly, we have the eigenvalue equation

$$- \chi'' + \frac{\gamma}{4\lambda} \mathcal{V}(\zeta) \chi = \epsilon \chi, \tag{8}$$

where

$$\mathcal{V}(\zeta) = \left[ \left( 1 - \frac{\mu^2}{v^2} \right) - \frac{1}{\cosh^2 \frac{\zeta}{2}} \right]. \tag{9}$$

Moreover, $\zeta = m \varphi z$, differentiation over $\zeta$ is denoted by prime, and the center of the wall is $\zeta_0 = 0$.

A plot of the potential (9) for the set of parameters used (see Sec. 4 for our numerical choice) is depicted in Fig. 1. We see a negative-energy domain near the origin, which allows in principle the existence of negative modes. Concretely, the lowest-eigenenergy $\epsilon$ was found numerically to be $-0.11$ for the choice of parameters presented in (15).

4 Equations and solutions

The Lagrangian (4) implies the following classical static equations of motion:

$$\begin{cases} 
\varphi'' = 4\lambda \varphi (\varphi^2 - v^2) + 2\gamma \chi^2 \varphi, \\
\chi^i'' = 2\gamma (\varphi^2 - \mu^2) \chi^i + 4\beta \gamma \chi^2 \chi^i, 
\end{cases} \tag{10}$$
where $\chi^2 = \chi^i\chi^j$ ($i, j = 1, 2, 3$), and $z$ differentiation is denoted by prime. The wall ansatz is implied: the solution sought for is independent of $x$ and $y$.

The function $\chi(z)$ is determined by energy minimization, but orientation of $\chi^i$ in the internal space can be arbitrary. Thus it is obvious that we can use an ansatz with a fixed orientation, for example,

$$\chi_i = \chi(z) \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}. \quad (11)$$

This gives us

$$\begin{cases} \varphi'' = 4\lambda\varphi(\varphi^2 - v^2) + 2\gamma\chi^2\varphi, \\ \chi'' = 2\gamma(\varphi^2 - \mu^2)\chi + 4\beta\gamma\chi^3. \end{cases} \quad (12)$$

We see that this system of equations has the first integral

$$\frac{1}{2} \left( \frac{d\varphi}{dz} \right)^2 + \frac{1}{2} \left( \frac{d\chi}{dz} \right)^2 - W(z) = 0, \quad (13)$$

where

$$W(z) = U[\varphi(z), \chi(z)] + V[\varphi(z), \chi(z)], \quad (14)$$

with $V$ from (1) and $U$ from (3). The constant was chosen to vanish, because at infinity $\varphi = v$, $\chi = 0$, and the kinetic term is zero. Equation (13) allows us
Figure 2: Potential $-W(z)$ as a function of $\varphi$ and $\chi$. The points denoted by • ($\varphi = \pm v$ and $\chi = 0$) correspond to the vacua of the system, and a domain wall can be visualized as a trajectory of motion in this potential with time standing for the $z$ coordinate.

to visualize Eq. (12) as equations of motion for a particle in a two-dimensional potential $-W(z)$, where $\varphi$ and $\chi$ play the role of coordinates, and $z$ the role of time.

The “potential” $-W(z)$ as a function of $\varphi$ and $\chi$ is plotted in Figure 2. Parameters used are

$$\lambda = \frac{1}{12}, \quad \beta = 0.2, \quad \gamma = \frac{2}{3}, \quad \frac{\mu}{v} = 0.55.$$  \hfill (15)

We use this set of parameters for finding a sample solution. The quartic constants are moderately small which warrants the validity of the quasiclassical approximation.

The unstable maxima of $-W(z)$ with $\varphi = \pm v$ and $\chi = 0$ correspond to the vacua of the system, and trajectories connecting these points correspond to the domain wall configurations. We have a nonvanishing solution for $\chi$ in the wall core when the “particle” is “dragged” near the starting point in the $\chi$ direction, and then goes along $\varphi$. To have a wall without $\chi$, the “particle”
should move exactly in the $\varphi$ direction, but, as it was proved previously, for a certain set of parameters such a configuration is unstable.

Now let us proceed to numerical solution of the system (12). Since we have boundary conditions set at infinity, we need to examine the asymptotic behavior of our equations there.

If $\varphi(-\infty) = v, \chi(-\infty) = 0$, then at $z$ near minus infinity $\chi$ and $\eta \equiv v - \varphi$ are small; therefore,

$$
\begin{cases}
\eta'' = 8v^2 \lambda \eta, \\
\chi'' = 2\gamma(v^2 - \mu^2) \chi,
\end{cases}
$$

which implies the following asymptotic behavior:

$$
\eta = A \exp \left( \sqrt{8v^2 \lambda} \, z \right), \quad \chi = B \exp \left[ \sqrt{2\gamma(v^2 - \mu^2)} \, z \right]
$$

at $z \to -\infty$. Here $A$ and $B$ are some unknown constants.

For a system of the second-order equations we need boundary conditions for both functions themselves and their first derivatives. Asymptotical solutions above provide us with the connection between functions and their derivatives at infinity. Since we need both $\varphi$ and $\chi$ at the boundary and the analytical connection between them is unknown, the shooting method was used: we set a small initial value for $\eta$ at $z = -\infty$ (on the left edge of the interval under consideration) and varied the initial value of $\chi$ in solving the system of equations, until we obtained the desired value of $\varphi$ at $+\infty$ (the right edge of the interval under consideration). The results obtained are presented in Figs. 3 and 4, where $\chi$ is normalized by $\chi_0 = \frac{\mu}{\sqrt{2\beta}}$ and $z$ normalized by $m_{\varphi}$. For comparison the plot of $\varphi$ from (2) (i.e. with $\chi = 0$) is also given in Fig. 3.

5 Moduli

If we have the solutions for $\varphi(z)$ and $\chi(z)$, then due to rotations in the internal space the general solution has rotational moduli

$$
\chi^i = \chi(z) \cdot S^i(x, y, t), \quad S^i S^i = 1, \ i = 1, 2, 3.
$$

The kinetic term takes the form

$$
\partial_\mu \chi^i \partial^\mu \chi^i \to \left[ \chi(z)^2 \right] \partial_p S^i \partial^p S^i - \left( \frac{d\chi}{dz} \right)^2, \quad p = 0, 1, 2,
$$
which leads us to the following term in action on the world volume

$$\Delta S_1 = \frac{1}{2} \frac{\chi_0^2}{m_\varphi} I_1 \int dt \, dx \, dy \, \left( \partial_\mu S^i \partial^\mu S^i \right).$$

Here

$$I_1 = \frac{m_\varphi}{\chi_0^2} \int \chi(z)^2 dz.$$  \hspace{1cm} (21)

From numerical integration over $z$, using the known function $\chi(z)$, we obtain

$$I_1 = 0.38.$$ \hspace{1cm} (22)

Next, we should take into account the fact that small excitations due to the translational symmetry breaking on the wall, give rise to a single translational modulus. Under translations the function $\chi(z)$ does not change but the center of the wall is displaced,

$$\chi(z) = \chi[z - z_0(t, x, y)].$$

As a result,

$$\partial_\mu \chi^i \partial^\mu \chi^i \rightarrow \left( \frac{d\chi}{dz} \right)^2 \left[ \partial_\mu z_0 \partial^\mu z_0 - 1 \right].$$  \hspace{1cm} (23)
implying the emergence of an additional term in the action,

$$\Delta S_2 = \frac{1}{2} \chi_0^2 m_\varphi I_2 \int dt \, dx \, dy \, (\partial_p z_0 \partial^p z_0),$$  \hfill (24)$$

where

$$I_2 = \frac{1}{\chi_0^2 m_\varphi} \int \left( \frac{d\chi}{dz} \right)^2 \, dz.$$  \hfill (25)$$

From numerical integration we obtain $I_2 = 0.14$.

Let us add this term to the world-volume action for the field $\varphi$,

$$\frac{1}{2} \left[ \int \left( \frac{d\varphi}{dz} \right)^2 \, dz \right] \int dt \, dx \, dy \, (\partial_p z_0 \partial^p z_0).$$  \hfill (26)$$

Equation (13) imply for the tension

$$T = \int \left[ \frac{1}{2} \left( \frac{d\varphi}{dz} \right)^2 + \frac{1}{2} \left( \frac{d\chi}{dz} \right)^2 + V(z) \right] \, dz = \int \left[ \left( \frac{d\varphi}{dz} \right)^2 + \left( \frac{d\chi}{dz} \right)^2 \right] \, dz.$$  \hfill (27)$$

The world-volume action for the translational modulus is obtained from our calculation as

$$\Delta S_{\text{trans}} = \frac{T}{2} \int dt \, dx \, dy \, (\partial_p z_0 \partial^p z_0),$$  \hfill (28)$$
as it should be on general grounds. Numerically (under our choice of parameters) the total tension is

\[ T = 0.998m_\varphi^3, \]

the integral over the \( \varphi \) derivative term is

\[ T_\varphi = 0.844m_\varphi^3, \]

and the integral over the \( \chi \) derivative term is

\[ T_\chi = 0.154m_\varphi^3. \]

6 Adding a spin-orbit interaction

Previously translational and rotational modes were independent. Now let us introduce an additional term for spin-orbit interaction,

\[ \mathcal{L}_{so} = -\varepsilon(\partial_i \chi^j)^2. \]  

(29)

The raison d’être of such a term and its possible origin is discussed in [5].

To the leading order in \( \varepsilon \), now we obtain an additional term in the action,

\[ \Delta S_3 = -\varepsilon \chi_0^2 m_\varphi I_2 \int dt dx dy \left\{ (\partial_k z_0)(\partial_l z_0)S^k S^l + S^3 S^3 + 2(\partial_k z_0)S^k S^3 \right\} \]

\[ - \varepsilon \frac{\chi_0^2}{m_\varphi} I_1 \int dt dx dy (\partial_k S^k)^2, \quad k = 1, 2. \]

(30)

We see that the structure of this entangled term is quite different from that in [6] for the Abrikosov-Nielsen-Olesen string. The entanglement between the translational and orientational moduli of a special form is evident.

In higher orders in \( \varepsilon \) the spin-orbit interaction will also change the formula for the \( \chi(z) \) solution compared to that following from Eq. (12).

7 Conclusions

We considered the simplest model with a domain wall and non-Abelian moduli fields, localized on it. Instability of the solution without the additional \( \chi \) field was shown, and then the numerical solution with \( \chi \neq 0 \) was found. The latter implies the existence of extra rotational moduli on the wall volume. Then we considered this model with addition of a spin-orbit interaction.
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