ENTIRE SCALAR CURVATURE FLOW AND HYPERSURFACES OF CONSTANT SCALAR CURVATURE IN MINKOWSKI SPACE

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Abstract. We prove existence in the Minkowski space of entire space-like hypersurfaces with constant negative scalar curvature and given set of lightlike directions at infinity; we also construct the entire scalar curvature flow with prescribed set of lightlike directions at infinity, and prove that the flow converges to a spacelike hypersurface with constant scalar curvature. The proofs rely on barriers construction and a priori estimates.

1. Introduction

The Minkowski space $\mathbb{R}^{n,1}$ is the space $\mathbb{R}^n \times \mathbb{R}$ endowed with the metric $dx_1^2 + \cdots + dx_n^2 - dx_{n+1}^2$. We say that a hypersurface of $\mathbb{R}^{n,1}$ is spacelike if the metric induced on it by the Minkowski metric is Riemannian, and that a function $u : \mathbb{R}^n \to \mathbb{R}$ of class $C^1$ is spacelike if its graph is a spacelike hypersurface, which equivalently means that $|Du| < 1$ on $\mathbb{R}^n$. The principal curvatures of a spacelike hypersurface are the eigenvalues of its curvature endomorphism $dN$, where $N$ is the future oriented unit normal field. In the natural chart $(x_1, \ldots, x_n)$, the curvature endomorphism $\left( h^i_j \right)_{ij}$ of the graph of a spacelike function $u$ is given by

$$ h^i_j = \frac{1}{\sqrt{1 - |Du|^2}} \sum_{k=1}^n \left( \delta_{ik} + \frac{u_i u_k}{1 - |Du|^2} \right) u_k. $$

Let us denote by $H_k[u]$ the $k^{th}$ elementary symmetric function of the principal curvatures of the graph of $u$.

We are interested in the scalar curvature $S[u]$ of the graph of $u$, which is linked to $H_2[u]$ by

$$ S[u] = -2H_2[u]. $$

We say that $u : \mathbb{R}^n \to \mathbb{R}$ of class $C^2$ is admissible, if $u$ is spacelike and if $H_1[u] > 0$ and $H_2[u] > 0$ on $\mathbb{R}^n$. It is well known that the operator $H_2$ is elliptic on admissible functions, and that the Mac-Laurin inequality holds:

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on $\mathbb{R}^n$,
\[ H_2[u]^{\frac{1}{2}} \leq \sqrt{\frac{n-1}{2n}} H_1[u]. \] (1.1)

Let $F$ be a closed subset of the unit sphere $S^{n-1} \subset \mathbb{R}^n$. We suppose that $F$ is a union of arcs of circles on $S^{n-1}$. We first construct barriers whose set of lightlike directions at infinity is the set $F$. For definitions and examples, we refer to Sections 2 and 3.

**Proposition 1.1.** Let $F$ be as above, and consider $V_F : \mathbb{R}^n \to \mathbb{R}$ defined by
\[ V_F(x) := \sup_{\lambda \in F} \langle x, \lambda \rangle, \] where $\langle \cdot, \cdot \rangle$ stands for the canonical scalar product on $\mathbb{R}^n$. Let $h$ and $k$ be two positive constants such that
\[ h < \sqrt{\frac{2n}{n-1}} \quad \text{and} \quad k \geq 1. \] (1.2)

There exist two entire functions $u, \overline{u} : \mathbb{R}^n \to \mathbb{R}$, such that
\[ V_F < u < \overline{u} < V_F + c \] on $\mathbb{R}^n$ (1.3)
for some constant $c$, where $\overline{u}$ is smooth, spacelike, with constant mean curvature $H_1 = h$, and $u$ is the supremum of spacelike functions with constant scalar curvature $H_2 = k$. Moreover, for all $\xi \in F$,
\[ \lim_{r \to +\infty} u(r\xi) - r = \lim_{r \to +\infty} \overline{u}(r\xi) - r = 0, \] (1.4)
and, from (1.3), for all $\xi \in S^{n-1} \setminus F$,
\[ \lim_{r \to +\infty} \overline{u}(r\xi) - r = -\infty. \] (1.5)

Solving a sequence of Dirichlet problems between the barriers $u$ and $\overline{u}$, and extracting a convergent subsequence thanks to local estimates [3, 4, 19], we will first construct an entire spacelike hypersurface of constant negative scalar curvature, and whose set of lightlike directions at infinity is $F$:

**Theorem 1.2.** Let $F$ be a closed subset of $S^{n-1}$ as above. Then there exists $u : \mathbb{R}^n \to \mathbb{R}$, admissible, solution of
\[ H_2[u] = 1 \] in $\mathbb{R}^n$ (1.6)
such that, for all $\xi \in F$,
\[ \lim_{r \to +\infty} u(r\xi) - r = 0 \] (1.7)
and
\[ \sup_{\mathbb{R}^n} |u - V_F| < +\infty. \] (1.8)

In particular, the set of lightlike directions at infinity of $u$ is the set $F$.

**Remark 1.3.** Uniqueness of a solution of (1.6) satisfying (1.7) and (1.8) is still an open question.
We then study the entire scalar curvature flow. Starting with a smooth spacelike entire and strictly convex function between the barriers which has bounded scalar curvature, we prove that the entire scalar curvature flow is defined for all time and converges to a solution of the prescribed constant scalar curvature equation:

**Theorem 1.4.** Let $F$ be as above. We suppose that $F$ is not included in any affine hyperplane of $\mathbb{R}^n$. Let $h, k$ be two positive constants such that (1.2) holds, and let $u, \overline{u}$ be the barriers given by Proposition 1.1. Let $u_0 : \mathbb{R}^n \to \mathbb{R}$ be a smooth spacelike and strictly convex function such that

$$u < u_0 < \overline{u}$$

and

$$1 \leq H_2[u_0] \leq k.$$  

The parabolic problem

$$\begin{cases} 
-\frac{u}{\sqrt{1-|Du|^2}} + H_2[u] \frac{1}{2} = 1 & \text{in } \mathbb{R}^n \times (0, +\infty) \\
u(x, 0) = u_0(x) & \text{on } \mathbb{R}^n \times \{0\},
\end{cases}$$

has a smooth spacelike solution

$$u \in C^\infty(\mathbb{R}^n \times (0, +\infty)) \cap C^{1,1,0.1}(\mathbb{R}^n \times [0, +\infty)).$$

Moreover

$$u \leq u \leq \overline{u}$$

for all time, and $u$ converges to a solution of (1.6) as the time $t$ tends to infinity.

**Remark 1.5.** Note that (1.10) describes hypersurfaces moving with normal velocity given by the square root of the scalar curvature,

$$\frac{d}{dt}X = \left(H_2[X]^{\frac{1}{2}} - 1\right)N,$$

where $X$ is the embedding vector of the hypersurfaces.

**Remark 1.6.** If $F$ is included in some affine hyperplane, condition (1.9) with $u_0$ strictly convex is not possible: suppose that $\xi \in \mathbb{R}^n$ belongs to $F^\perp$; then $V_F(\xi) = 0$, and, by (1.3) and (1.9), $0 < u_0(\lambda\xi) < c$ for all $\lambda \in \mathbb{R}$, which is impossible if $\xi \neq 0$ and if $u_0$ is a strictly convex function. Note that the strictly convexity of $u_0$ is a crucial hypothesis for the resolution of the parabolic Dirichlet problem, Section 6. See also [3, 19].

**Remark 1.7.** If $u_0 : \mathbb{R}^n \to \mathbb{R}$ is a spacelike and strictly convex function such that $1 \leq H_2[u_0] \leq k$ and $\lim_{|x| \to +\infty} u_0(x) - |x| = 0$, we get the following: taking for the lower barrier $u$ (resp. for the upper barrier $\overline{u}$) the hyperboloid asymptotic to the cone $x_{n+1} = |x|$ and of scalar curvature $H_2 = k' > k$ (resp. of mean curvature $H_1 = h < \sqrt{\frac{2n}{n-1}}$), by the maximum principle we have $u < u_0 < \overline{u}$, and Theorem 1.4 shows that problem (1.10) has a (unique)
solution $u$ such that $\underline{u} \leq u \leq \overline{u}$ during the evolution. Moreover $u$ converges to the hyperboloid of scalar curvature $H_2 = 1$, as $t$ tends to infinity.

**Remark 1.8.** By scaling $u$ in Theorem 1.2, we obtain an admissible solution of $H_2[u] = \lambda^2$ in $\mathbb{R}^n$ such that (1.7) and (1.8) hold. Moreover, by scaling the barriers $\underline{u}, \overline{u}$ in Proposition 1.1, we obtain a result similar to Theorem 1.4 for the parabolic problem

$$
\begin{aligned}
-\frac{\ddot{u}}{\sqrt{1-|Du|^2}} + H_2[u]^2 &= \lambda \text{ in } \mathbb{R}^n \times (0, +\infty) \\
u(x, 0) &= u_0(x) \text{ on } \mathbb{R}^n \times \{0\},
\end{aligned}
$$

(1.12)

if $\underline{u} < u_0 < \overline{u}$ and $\lambda^2 \leq H_2[u_0] \leq \lambda^2k$ hold.

Let us quote some related papers: in Minkowski space, entire spacelike hypersurfaces of constant mean curvature are classified in [17] and entire hypersurfaces of constant Gauss curvature are studied in [5, 12]. In [3], we construct entire hypersurfaces with prescribed scalar curvature and given values at infinity which stay at a bounded distance of a lightcone.

The entire mean curvature flow in Minkowski space is studied in [8], and the entire Gauss curvature flow in [5]. The scalar curvature flow in globally hyperbolic Lorentzian manifolds having a compact Cauchy hypersurface is studied in [10, 11] and [9].

Finally, the parabolic Dirichlet problem for the scalar curvature operator in the Euclidean space is solved in [14, 15].

The outline of the paper is as follows. We recall the definition of the set of lightlike directions at infinity of a spacelike and convex function in Section 2. In Section 3 we construct the barriers with given set of lightlike directions at infinity, and construct the auxiliary functions needed for the local estimates. The entire solutions of the prescribed constant scalar curvature equation are constructed Section 4. We introduce further notation and recall the evolution equations of various geometric quantities Section 5, and we study the parabolic Dirichlet problem Section 6. In Section 7 we construct the entire scalar curvature flow, once local $C^1$ and $C^2$ estimates are known, and we prove that the flow converges. We carry out the local estimates in Sections 8 and 9. A short appendix ends the paper.

## 2. The set of lightlike directions at infinity of an entire spacelike hypersurface of constant scalar curvature

Let $u : \mathbb{R}^n \to \mathbb{R}$ be a spacelike and convex function. Following Treibergs [17], its **blow down** $V_u : \mathbb{R}^n \to \mathbb{R}$ is defined by

$$
V_u(x) = \lim_{r \to +\infty} \frac{u(rx)}{r}.
$$

As in [17], we denote by $Q$ the set of the convex homogeneous of degree one functions whose gradient has norm one whenever defined. The following holds:
Lemma 2.1. For every convex and spacelike solution \( u \) of the prescribed scalar curvature equation (1.6), the blow down \( V_u \) belongs to \( Q \).

Proof. This result is proved in [17], Theorem 1 for the prescribed mean curvature equation, using a barrier construction. The same barrier can be used for the prescribed constant scalar curvature equation as well. □

The set \( Q \) is in one-to-one correspondence with the set of closed subsets of \( S^{n-1} \); see [6], Lemma 4.3.

Lemma 2.2. [6, 17]. If \( F \) is a closed non-empty subset of \( S^{n-1} \),
\[
V_F(x) := \sup_{\lambda \in F} \langle x, \lambda \rangle
\]
belongs to \( Q \); the map \( F \mapsto V_F \) is one-to-one, and its inverse is the map
\[
w \in Q \mapsto F = \{ x \in S^{n-1} \subset \mathbb{R}^n : w(x) = 1 \}.
\]

In particular, the blow down of a convex solution \( u \) of (1.6) is determined by the set of its lightlike directions at infinity
\[
L_u := \{ x \in S^{n-1} : V_u(x) = 1 \}.
\]

Note that here, and in contrast with [5, 17], it is not known if a spacelike entire function of constant negative scalar curvature is necessarily convex. Nevertheless, the solutions \( u \) constructed in this article are such that \( V_F \leq u \leq V_F + c \), where \( F \) is a closed subset belonging to \( S^{n-1} \) and \( c \) is a constant. In that case, the blow down \( V_u \) and the set of lightlike directions \( L_u \) are well-defined, and satisfy
\[
V_u = V_F \text{ and } L_u = F.
\]

We finally recall a useful formula. Denoting by \( d_S \) the canonical distance on the sphere \( S^{n-1} \), we proved the following formula in [5], Lemma 4.6: for every \( x \in S^{n-1} \),
\[
V_F(x) = \cos(d_S(x, F)). \tag{2.1}
\]

3. The construction of the barriers

3.1. The semitrough. We first recall the properties of the standard semitrough of constant Gauss curvature in the Minkowski space \( \mathbb{R}^{2,1} \), constructed in [13]: this is the unique spacelike function \( \tilde{u} : \mathbb{R}^2 \to \mathbb{R} \) whose graph has constant Gauss curvature one, and which is such that
\[
D\tilde{u}(\mathbb{R}^2) = \{(x_1, x_2) \in B_1 : x_1 > 0\},
\]
and
\[
\lim_{|x| \to \infty} \tilde{u}(x) - V_{S^+}(x) = 0. \tag{3.1}
\]

Here \( B_1 \) is the unit ball in \( \mathbb{R}^2 \) centered at 0, and \( S^+ \) is the arc of the circle \( S^1 = \partial B_1 \) defined by \( S^+ := \{(x_1, x_2) \in S^1 : x_1 \geq 0\} \). Let \( S \) be a closed arc of circle on the sphere \( S^{n-1} \). This is a subset of the form \( f(S^+ \times \{0\}) \), where
\[
S^+ \times \{0\} = \{(x_1, x_2, 0, \ldots, 0) \in S^{n-1} : x_1 \geq 0\} \tag{3.2}
\]
and $f$ is a conformal transformation of $S^{n-1}$. From the existence of the standard semitrough, we deduce the following

**Lemma 3.1.** Let $S$ be a closed arc of circle on $S^{n-1}$, and let $k > 0$. There exists a spacelike entire function $u$ such that

$$H_2[u] = k \text{ and } \sup_{\mathbb{R}^n} |u - V_S| < +\infty.$$ 

**Proof.** Recall that a Lorentz transformation preserves $H_2$, and acts as a conformal transformation of $S^{n-1}$ on the sets of lightlike directions at infinity ($S^{n-1}$ is identified with the projective lightcone). Thus, applying a Lorentz transformation, we may suppose that $S$ is given by (3.2). The function $u$ defined by

$$u(x_1, x_2, x_3, \ldots, x_n) = \frac{1}{\sqrt{k}} \tilde{u}(\sqrt{k}(x_1, x_2)),$$

where $\tilde{u}$ is the standard semitrough defined above, satisfies the required properties. \qed

3.2. **The barriers.** Let $h$ be a positive constant and $F$ be a closed subset of $S^{n-1}$. From [17] p233, we know that there exists a smooth spacelike function $\tilde{u}: \mathbb{R}^n \to \mathbb{R}$ whose graph has constant mean curvature $H_1 = h$ and which is such that

$$V_F \leq \tilde{u} \leq V_F + \frac{n}{h} \text{ on } \mathbb{R}^n. \quad (3.3)$$

The function $\tilde{u}$ satisfies the further properties:

$$\limsup_{|x| \to +\infty} \tilde{u}(x) - |x| \leq 0, \quad (3.4)$$

and, for all $\xi \in F$,

$$\lim_{r \to +\infty} \tilde{u}(r\xi) - r = 0. \quad (3.5)$$

For these last properties, see the upper barrier $z_2$ used in [17] p233.

**Lemma 3.2.** Let $h$ and $k$ be two positive constants such that $h < 2\sqrt{k}$. We assume that $F$ is a union of closed arcs of circles on $S^{n-1}$,

$$F = \bigcup_{i \in I} S_i. \quad (3.6)$$

Denoting by $u_i$ the entire spacelike function of constant scalar curvature $k$ associated to $S_i$ by Lemma 3.1 (and its proof), the function $\underline{u} = \sup_{i \in I} u_i$ satisfies

$$V_F < \underline{u} < \tilde{u} \text{ on } \mathbb{R}^n.$$

**Remark 3.3.** The closure of an open subset $U$ of $S^{n-1}$ with $C^1$ boundary is of the form (3.6). More generally, if $U$ satisfies an interior cone condition at each boundary-point (i.e. all $\xi \in \partial U$ is a vertex of a (geodesic) cone $\subset \overline{U}$), $\overline{U}$ is of the form (3.6). Of course, the set $F$ in (3.6) might be much more complicated (e.g. without interior point).
Since these functions are homogeneous of degree one, we may suppose that \( x \in S^{n-1} \subseteq \mathbb{R}^n \). By (2.1), this amounts to prove that \( d_S(x, F) = d_S(x, S_i) \) for some index \( i \in I \), where \( d_S \) is the natural distance on \( S^{n-1} \). Let \( x_0 \in F \) be such that \( d_S(x, F) = d_S(x, x_0) \), and \( i \in I \) be such that \( x_0 \) belongs to \( S_i \). Since \( S_i \subseteq F \), we have \( d_S(x, F) \leq d_S(x, S_i) \), and since \( x_0 \in S_i \) we have \( d_S(x, x_0) \geq d_S(x, S_i) \) and thus \( d_S(x, F) \geq d(x, S_i) \). Thus \( d_S(x, F) = d_S(x, S_i) \), and the result follows.

We now prove that \( \underline{u} \leq \overline{u} \). We fix \( i \in I \) and we prove that \( u_i \leq \overline{u} \) by applying a Lorentz transformation, we may assume that

\[
S_i = \{ (x_1, x_2, 0, \ldots, 0) \in S^{n-1} : x_1 \geq 0 \}.
\]

Let \( x' \in \mathbb{R}^{n-2} \), and set

\[
\tilde{u}_i(x_1, x_2) := u_i(x_1, x_2, x'_2) \quad \text{and} \quad \tilde{\overline{u}}(x_1, x_2) := \overline{u}(x_1, x_2, x'_2).
\]

Recalling the proof of Lemma 3.1, we observe that \( \tilde{u}_i \) is the (scaled) semitrough defined Section 3.1. From Lemma A.1 we get \( H_1[\tilde{u}] \leq h \). Since \( \tilde{u}_i \) is the semitrough with Gauss curvature equal to \( k \), from the geometric-arithmetic means inequality we get \( H_1[\tilde{u}_i] \geq 2 \sqrt{k} \). Thus \( H_1[\tilde{u}] \leq H_1[\tilde{u}_i] \). We suppose by contradiction that there exists \( x_0 = (x'^0_1, x'^0_2) \) such that \( \tilde{u}_i(x_0) > \overline{u}(x_0) \), and we consider \( \varepsilon > 0 \) such that

\[
\tilde{u}_i(x_0) > \overline{u}(x_0) + \varepsilon.
\]

Since \( S_i \) belongs to \( F \), we have \( V_F(., x'_0) \geq V_{S_i}(., x'_0) = V_{S^+} \), and we conclude from (3.1) and (3.3) that

\[
\liminf_{|x| \to +\infty} (\overline{u} + \varepsilon) - \tilde{u}_i \geq \varepsilon.
\]

Thus the non-empty open set

\[
U = \{ (x_1, x_2) \in \mathbb{R}^2 : \tilde{u}_i(x_1, x_2) > \overline{u}(x_1, x_2) + \varepsilon \}
\]

is bounded. Since \( \tilde{u}_i = \overline{u} + \varepsilon \) on \( \partial U \) and \( H_1[\tilde{u}_i] \geq H_1[\overline{u} + \varepsilon] \) in \( U \), we get a contradiction with the maximum principle. The claim is proved.

We finally prove the strict inequality \( \underline{u} < \overline{u} \) : we set \( \overline{\overline{u}}(x) := \frac{1}{\lambda} \overline{u}(\lambda x) \), with \( \lambda > 1 \) such that \( \lambda h < 2 \sqrt{k} \). Since \( H_1[\overline{\overline{u}}] = \lambda h \) and \( \overline{\overline{u}} > V_F \), the arguments given in the paragraph above (with \( \overline{\overline{u}} \) instead of \( \overline{u} \)) show that \( \underline{u} \leq \overline{\overline{u}} \). Since \( \overline{\overline{u}} < \overline{u} \), we obtain the result. \( \square \)

The useful properties of the barriers are gathered in Proposition 1.1.

**Remark 3.4.** By construction, it is clear that if the set \( F \) is contained in some affine subspace, in

\[
\{ (x', x'') \in \mathbb{R}^n = \mathbb{R}^k \times \mathbb{R}^{n-k} : x'' = 0 \}
\]

say, we may assume that the barriers \( \underline{u}, \overline{u} \) satisfy: for all \( (x', x'') \in \mathbb{R}^k \times \mathbb{R}^{n-k} \),

\[
\underline{u}(x', x'') = \underline{u}(x', 0) \quad \text{and} \quad \overline{u}(x', x'') = \overline{u}(x', 0).
\]
3.3. Construction of two auxiliary functions. This section is devoted to the construction of auxiliary functions which are crucial for the local $C^1$ and $C^2$ estimates. The functions $u, \overline{u}$ are the barriers constructed above. The following lemma is needed for the local $C^1$ estimate.

**Lemma 3.5.** Let $K$ be a compact subset of $\mathbb{R}^n$. There exists a smooth space-like function $\psi : \mathbb{R}^n \to \mathbb{R}$ such that

\[ \psi < u \text{ on } K \text{ and } \psi \geq \overline{u} \text{ near infinity}. \]

For the proof, we will need the following lemma:

**Lemma 3.6.** Let $F$ be a closed subset of $S^{n-1}$. Let $\varepsilon > 0$ and set

\[ F_\varepsilon := \{ \xi \in S^{n-1} : d_S(\xi, F) \leq \varepsilon \}. \]

The function $V_{F_\varepsilon} - V_F$ has the following properties:

\[ \sup_{\xi \in S^{n-1}} |V_{F_\varepsilon}(\xi) - V_F(\xi)| \leq \varepsilon, \tag{3.7} \]

and

\[ \inf_{\xi \in S^{n-1} \setminus F_\varepsilon} V_{F_\varepsilon}(\xi) - V_F(\xi) \geq m_\varepsilon, \tag{3.8} \]

for some positive constant $m_\varepsilon$.

**Proof.** By (2.1), for all $\xi \in S^{n-1}$,

\[ V_{F_\varepsilon}(\xi) - V_F(\xi) = \cos (d_S(\xi, F_\varepsilon)) - \cos (d_S(\xi, F)). \tag{3.9} \]

We first prove (3.7): we observe that, for all $\xi \in S^{n-1}$,

\[ |d_S(\xi, F_\varepsilon) - d_S(\xi, F)| \leq \varepsilon. \]

Since $|\cos(\alpha) - \cos(\beta)| \leq |\alpha - \beta|$ for all $\alpha, \beta \in \mathbb{R}$, we obtain (3.7).

We now prove (3.8): we suppose that $\xi \notin F_\varepsilon$; since $F \subset F_\varepsilon$, we have

\[ d_S(\xi, F) = d_S(\xi, F_\varepsilon) + \varepsilon. \tag{3.10} \]

This implies in particular that

\[ d_S(\xi, F_\varepsilon) \in [0, \pi - \varepsilon]. \]

Denoting $\alpha = d_S(\xi, F_\varepsilon)$, we obtain from (3.9) and (3.10) that

\[ V_{F_\varepsilon}(\xi) - V_F(\xi) = \cos \alpha - \cos(\alpha + \varepsilon) \geq m_\varepsilon, \]

where $m_\varepsilon = \inf_{\alpha \in [0, \pi - \varepsilon]} \int_0^{\alpha + \varepsilon} \sin(t)dt$ is positive, and we obtain (3.8). \qed

**Proof of Lemma 3.5.** Let $K$ be a compact subset of $\mathbb{R}^n$, and $R \geq 1$ be such that $K \subset \overline{B}_R$ (here and below $B_R$ stands for the open ball of radius $R$ in $\mathbb{R}^n$, centered at the origin). We fix $\delta_0 > 0$ such that

\[ \inf_{B_R} (u - V_F) \geq \delta_0. \tag{3.11} \]
Let $\varepsilon > 0$ and $F_\varepsilon := \{ \xi \in S^{n-1} | d(\xi, F) \leq \varepsilon \}$. From (3.7) we get

$$\sup_K |V_{F_\varepsilon} - V_F| < \frac{\delta_0}{8} \quad (3.12)$$

if $\varepsilon < \frac{\delta_0}{8}$. Thus, if $\varepsilon < \frac{\delta_0}{8}$,

$$\sup_K |(V_{F_\varepsilon} + \varepsilon) - V_F| < \frac{\delta_0}{4}. \quad (3.13)$$

Let $\psi$ be a spacelike function such that $\psi > V_{F_\varepsilon} + \varepsilon$ and

$$\sup_K |\psi - (V_{F_\varepsilon} + \varepsilon)| < \frac{\delta_0}{4}. \quad (3.14)$$

We may construct $\psi$ as follows: we first consider a spacelike function $v$ whose graph has constant mean curvature one and which is such that

$$V_{F_\varepsilon} < v < V_{F_\varepsilon} + c,$$

given by [17] Theorem 2; here $c$ is a positive constant. We then define

$$\psi(x) := \frac{1}{\lambda} v(\lambda x) + \varepsilon,$$

where $\lambda$ is a positive parameter. We have

$$\sup_{x \in \mathbb{R}^n} |\psi(x) - (V_{F_\varepsilon} + \varepsilon)(x)| = \sup_{x \in \mathbb{R}^n} \left| \frac{1}{\lambda} v(\lambda x) - V_{F_\varepsilon}(x) \right| = \frac{1}{\lambda} \sup_{x \in \mathbb{R}^n} |v(\lambda x) - V_{F_\varepsilon}(\lambda x)| \leq \frac{c}{\lambda} < \frac{\delta_0}{4}$$

if $\lambda$ is chosen sufficiently large. From (3.13) and (3.14) we get

$$\sup_K |\psi - V_F| < \frac{\delta_0}{2}, \quad (3.15)$$

and, from (3.11), on $K$,

$$u - \psi \geq \inf_K (u - V_F) - \sup_K |\psi - V_F| \geq \frac{\delta_0}{2}.$$ 

We now prove that there exists $r_\varepsilon > 0$ such that

$$\inf_{\mathbb{R}^n \setminus B_{r_\varepsilon}} (V_{F_\varepsilon} + \varepsilon - \overline{u}) \geq \frac{\varepsilon}{2}. \quad (3.16)$$

Since $\psi > V_{F_\varepsilon} + \varepsilon$, this will prove the last claim of the Lemma. We consider $x = r\xi \in \mathbb{R}^n \setminus \{0\}$, with $r > 0$ and $\xi \in S^{n-1}$. We first suppose that $\xi \in F_\varepsilon$. By (3.4) there exists $r_1$, independent of $\xi$, such that $\overline{u}(r\xi) \leq r + \frac{\varepsilon}{2}$ for all $r \geq r_1$. Thus, if $r \geq r_1$,

$$(V_{F_\varepsilon} + \varepsilon - \overline{u})(r\xi) \geq (r + \varepsilon) - \left( r + \frac{\varepsilon}{2} \right) \geq \frac{\varepsilon}{2}.$$ 

If we now suppose that $\xi \notin F_\varepsilon$, we have

$$(V_{F_\varepsilon} + \varepsilon - \overline{u})(r\xi) \geq (V_{F_\varepsilon} - V_F)(r\xi) + (V_F - \overline{u})(r\xi) \geq (V_{F_\varepsilon} - V_F)(r\xi) - c,$$
where the constant $c$ is given by (1.3). By (3.8), $V_{F,\varepsilon} - V_F(r\xi) \geq \varepsilon m_\varepsilon$ where the constant $m_\varepsilon$ is positive. Thus, there exists $r_2$ such that if $r \geq r_2$ and $\xi \not\in F_\varepsilon$, we have 

$$(V_{F,\varepsilon} + \varepsilon - \overline{\pi})(r\xi) \geq \frac{\varepsilon}{2}.$$ 

Taking $r_\varepsilon = \max(r_1, r_2)$ we obtain (3.16).

The following lemma is needed for the local $C^2$ estimate.

**Lemma 3.7.** We suppose that $F$ is not included in any affine hyperplane of $\mathbb{R}^n$, and we consider $K$ a compact subset of $\mathbb{R}^n$. There exist a ball $B_R$ which contains $K$ and a smooth and strictly convex function $\Phi : \overline{B}_R \to \mathbb{R}$ such that 

$$\Phi > \overline{\pi} \text{ on } K \text{ and } \Phi \leq \underline{u} \text{ on } \partial B_R.$$ 

**Proof.** We first note that the upper barrier $\overline{\pi}$ is strictly convex: this follows from the Splitting Theorem [6], Theorem 3.1, together with the assumption that $F$ is not included in any affine hyperplane of $\mathbb{R}^n$. Applying an affine Lorentz transformation if necessary, we may suppose that $\overline{\pi}(0) = 0$ and $d\overline{u} = 0$.

Since $\overline{\pi}$ is strictly convex, we have 

$$\lim_{|x| \to +\infty} \overline{\pi}(x) = +\infty. \quad (3.17)$$

We fix $R'$ sufficiently large such that $K \subset \overline{B}_{R'}$. We set $\Phi_0 := \sup_{B_{R'}} \overline{\pi} + 1$. Recalling (1.3), $\underline{u} \geq \overline{\pi} - c$ on $\mathbb{R}^n$. We thus get from (3.17) the existence of $R > R'$ such that 

$$\inf_{\{x : |x| \geq R\}} \underline{u}(x) \geq \Phi_0 + 1. \quad (3.18)$$

We set, for all $x \in \mathbb{R}^n$,

$$\Phi(x) := \Phi_0 + \frac{1}{R'^2} |x|^2. \quad (3.19)$$

The function $\Phi$ is strictly convex, $\Phi \geq \overline{\pi} + 1$ on $B_{R'}$ and $\Phi \leq \underline{u}$ on $\partial B_R$. □

4. **The construction of an entire solution of the elliptic problem**

We assume that $F$, $\underline{u}$ and $\overline{\pi}$ are as in Proposition 1.1. The barriers $\underline{u}, \overline{\pi}$ are constructed in the previous section.

We first suppose that $F$ is not included in any affine hyperplane of $\mathbb{R}^n$.

For any positive $R$, we set $u_R$ for the admissible solution of 

$$\left\{ \begin{array}{ll} H_2[u_R] = & 1 \text{ in } B_R \\ u_R = & \overline{\pi} \text{ on } \partial B_R. \end{array} \right.$$ 

This Dirichlet problem is solvable since $\overline{\pi}$ is strictly convex (by the Splitting Principle [6], Theorem 3.1); see [3, 19]. From the Mac-Laurin inequality (1.1) we get $H_1[u_R] \geq \sqrt{\frac{2n}{n-1}}$. Thus, the comparison principle for the operator $H_1$ implies that $\overline{\pi} \geq u_R$. Since $\underline{u}$ is defined as a supremum of admissible functions
with scalar curvature \( H_2 = 1 \), we also have \( u_R \geq u \). Thus \( u_R \) lies between the barriers, for every \( R \). The following local uniform estimates hold: for any \( R_0 \geq 0 \), there exist \( R_1 = R_1(R_0) \) sufficiently large, \( \vartheta \in (0,1) \), and \( C \geq 0 \) such that: for every \( R \geq R_1 \),

\[
\sup_{B_{R_0}} |Du_R| \leq 1 - \vartheta \quad \text{and} \quad \sup_{B_{R_0}} |u_R| + \sup_{B_{R_0}} |D^2u_R| \leq C.
\]

For the \( C^1 \) local estimate, we refer to [4], Proposition 4.1. The auxiliary function \( \psi \) needed for the estimate is given here by Lemma 3.5. For the local \( C^2 \) estimate, we refer to [4], Proposition 5.1.; here is needed the auxiliary function \( \Phi \) given by Lemma 3.7. The proofs remain unchanged.

Evans-Krylov interior second derivative Hölder estimate, and Schauder interior regularity theory imply locally uniform estimates of higher derivatives. A diagonal process then yields a subsequence \( u_{R_k} \), \( R_k \to +\infty \), that locally converges to a smooth solution of (1.6). The properties (1.7) and (1.8) follow from the behavior at infinity of the barriers given by (1.3) and (1.4).

If \( F \) is included in some affine hyperplane of \( \mathbb{R}^n \), applying a Lorentz transformation we may suppose that \( F \) belongs to

\[
S^{k-1} \times \{0\} = \{(x_1, \ldots, x_n) \in S^{n-1} : x_{k+1} = \cdots = x_n = 0\}
\]

and that \( F \) is not included in any affine hyperplane of \( \mathbb{R}^k \times \{0\} \), where \( k \) belongs to \( \{1, \ldots, n-1\} \). By Remark 3.4, the restrictions \( \underline{w}_{\mathbb{R}^k}, \overline{w}_{\mathbb{R}^k} \) are barriers for the scalar curvature operator \( H_2 \) on \( \mathbb{R}^k \), with \( \overline{w}_{\mathbb{R}^k} \) strictly convex, and are such that (1.3)-(1.4) hold on \( \mathbb{R}^k \). Thus, there exists \( \tilde{u} : \mathbb{R}^k \to \mathbb{R} \) such that \( H_2[\tilde{u}] = 1 \) and \( \underline{w}_{\mathbb{R}^k} \leq \tilde{u} \leq \overline{w}_{\mathbb{R}^k} \). The function \( u \) defined on \( \mathbb{R}^n \) by

\[
u(x_1, \ldots, x_n) := \tilde{u}(x_1, \ldots, x_k)
\]
is an entire solution of (1.6) such that (1.7) and (1.8) hold.

5. Notation and evolution equations

5.1. Notation. Let \( \Sigma_0 \) be a spacelike hypersurface of \( \mathbb{R}^{n,1} \), and let \( X : \Sigma_0 \times [0, +\infty) \to \mathbb{R}^{n,1} \) be a family of spacelike embeddings of \( \Sigma_0 \) in \( \mathbb{R}^{n,1} \) : for every \( t \geq 0 \), \( \Sigma_t := X(\Sigma_0 \times \{t\}) \) is a spacelike hypersurface. We set \( N \) for the future oriented unit normal field of \( \Sigma_t \). We denote by \( (g_{ij}) \) and \( (h_{ij}) \) the metric and the second fundamental form induced by the Minkowski metric on the embedded hypersurface \( \Sigma_t \). We will use the Einstein summation convention, and raise or lower indices with respect to the metric \( (g_{ij}) \). The components of the curvature endomorphism are thus denoted by \( h^i_j \), and we will often write problem (1.10) in the equivalent form

\[
\begin{cases}
\dot{X} = (F((h^i_j)_{ij}) - \hat{f}(X,t))N \text{ in } \Sigma_0 \times (0, +\infty) \\
X(., 0) = X_0 \text{ on } \Sigma_0,
\end{cases}
\]

where \( X_0 \) is the canonical embedding of \( \Sigma_0 \), \( F(A) \) is the square root of the sum of the principal minors of order 2 of the matrix \( A \), and \( \hat{f} \) is a positive
function on \( \mathbb{R}^{n,1} \times [0, +\infty) \) (constant equal to one in (1.10)). Let
\[
F^j_i := \frac{\partial F}{\partial h^i_j} (h^i_j)_{i,j}.
\]
If \((h^i_j)_{i,j}\) is diagonal, so is \((F^j_i)_{i,j}\), and \(F_{ii} = \frac{1}{2F} \sigma_{1,i}\) for all \(i\), where
\[
\sigma_{1,i} = \sum_{k,k \neq i} \lambda_k.
\]
Here and below we denote by \(\lambda_1 \geq \cdots \geq \lambda_n\) the principal curvatures of \(\Sigma_t\).
\((F^j_i)_{i,j}\) defines a \((1,1)\) tensor on \(\Sigma_t\). Raising the index \(i\) we also will use the symmetric tensor \((F^{ij})_{i,j}\).

Analogously we define
\[
F^{ij,kl} := g^{ii'} g^{kk'} \frac{\partial^2 F}{\partial h^i_j \partial h^k_l} (h^i_j)_{i,j}.
\]
We say that \(X\) solution of (5.1) is admissible if, for every \(t \geq 0\), \(\Sigma_t\) is an admissible hypersurface, which means that \(H_1(\Sigma_t) > 0\) and \(H_2(\Sigma_t) > 0\). Admissibility of a solution of (1.10) is defined similarly. We denote by \(D\) the usual covariant derivative on \(\mathbb{R}^{n,1}\) (or on \(\mathbb{R}^n\)), \(\nabla\) the covariant derivative induced on \(\Sigma_t\), and use a semi-colon to denote the components of covariant derivatives on \(\Sigma_t\). Finally, the Minkowski metric on \(\mathbb{R}^{n,1}\) is denoted by \(\langle \cdot, \cdot \rangle\), the Minkowski norm of spacelike vectors of \(\mathbb{R}^{n,1}\) by \(|\cdot|\), and the usual euclidian norm by \(|\cdot|_{\text{eucl}}\).

5.2. Evolution equations. For a hypersurface moving according to
\[
\dot{X} = (F(h^i_j) - \hat{f}(X,t))N,
\]
we have
\[
\frac{d}{dt} g_{ij} = 2(F - \hat{f}) h_{ij},
\]
\[
\frac{d}{dt} (F - \hat{f}) - F^{ij}(F - \hat{f})_{ij} = -F^{ij} h_{ik} h^k_j (F - \hat{f}) - N^a \hat{f}_a (F - \hat{f}) - \hat{f}_i,
\]
\[
\frac{d}{dt} h_{ij} - F^{kl} h_{ij,kl} = F(h^a_i h_{aj}) - h_{ij} F^{kl}(h^a_k h_{al}) + F^{kl,pq} h_{kl,ij} h_{pq,ij} - \hat{f}_{ij} + (F - \hat{f}) h^k_i h_k j,
\]
and, defining \(u := -\langle e_{n+1}, X \rangle\) and \(\nu := -\langle e_{n+1}, N \rangle\),
\[
\dot{u} - F^{ij} u_{ij} = -\hat{f}\nu,
\]
and
\[
\dot{\nu} - F^{ij} u_{ij} = -\nu F^{ij} h^k_i h_{ki} + \hat{f}_j h^j_i,
\]
where the \(t^j\)'s are the coordinates of the component tangential to \(\Sigma_t\) of \(e_{n+1}\). For the proofs we refer to [10] and [5], where similar evolution equations are obtained.
6. The parabolic Dirichlet problem

The aim of this section is to prove the following

**Theorem 6.1.** Let $\Omega$ be a uniformly convex bounded domain in $\mathbb{R}^n$ with smooth boundary, let $u_0 : \overline{\Omega} \to \mathbb{R}$ be a smooth, spacelike and strictly convex function, and let $\hat{f} : \overline{\Omega} \times \mathbb{R} \times [0, +\infty) \to (0, +\infty)$, $(x, u, t) \mapsto \hat{f}(x, u, t)$ be a smooth positive function such that $\hat{f}_t \leq 0$. We suppose that, for all $x \in \Omega$,

$$H_2[u_0]^{\frac{1}{2}}(x) - \hat{f}(x, u_0(x), 0) \geq 0.$$  

Then the parabolic Dirichlet problem

\[
\begin{aligned}
- \frac{\hat{u}}{\sqrt{1 - |Du|^2}} + H_2[u]^{\frac{1}{2}} &= \hat{f}(x, u, t) \text{ in } \Omega \times (0, +\infty) \\
\frac{\partial u}{\partial t} &= u_0(x) \text{ on } \partial \Omega \times [0, +\infty) \cup \Omega \times \{0\},
\end{aligned}
\]  

(6.1)

has an admissible solution $u \in C^\infty(\Omega \times [0, +\infty))$ if, on the corner of the parabolic domain, the compatibility conditions of any order are satisfied.

At the boundary, compatibility conditions of any order are fulfilled, so we get a smooth admissible solution for a short time interval.

We consider $T$ maximal such that the parabolic Dirichlet problem (6.1) has an admissible solution on $\overline{\Omega} \times [0, T]$, and suppose by contradiction that $T < +\infty$. We need the following a priori estimates:

\[
\sup_{\overline{\Omega} \times [0, T]} |Du| \leq 1 - \vartheta, \quad \sup_{\overline{\Omega} \times [0, T]} |H_2[u]^{\frac{1}{2}} - \hat{f}| \leq C_1, \quad \sup_{\overline{\Omega} \times [0, T]} |D^2u| \leq C_2, \quad (6.2)
\]

and

\[
\alpha_0 \leq \inf_{\overline{\Omega} \times [0, T]} H_2[u]^{\frac{1}{2}}. \quad (6.3)
\]

with $\vartheta \in (0, 1]$, $C_1, C_2 \geq 0$, and $\alpha_0 > 0$. With these estimates at hand (and the obvious $C^0$ estimate), the estimates of Krylov and Safonov and the Schauder theory imply estimates of higher derivatives of $u$. We may thus extend $u$ to a solution on $[0, T]$. Admissibility at the time $T$ is guaranteed by (6.3) and Mac-Laurin inequality (1.1). The short time existence theory then yields a solution on $[0, T + \varepsilon)$, $\varepsilon > 0$, and thus a contradiction with the definition of $T$.

In the rest of the section we carry out estimates (6.2) and (6.3). Instead of (6.1) we will also consider the equivalent problem

\[
\begin{aligned}
\dot{X} &= (F - \hat{f}) N \text{ in } \Sigma_0 \times (0, T) \\
X &= X_0 \text{ on } \partial \Sigma_0 \times [0, T) \cup \Sigma_0 \times \{0\},
\end{aligned}
\]  

(6.4)

where $\Sigma_0 = \text{graph} u_0$ and $X : \Sigma_0 \times [0, T) \to \mathbb{R}^{n,1}$ denotes the embedding vector in $\mathbb{R}^{n,1}$.

We will denote by $D_0$ the domain of dependence in $\mathbb{R}^{n,1}$ of the boundary data $\Sigma_0 = \text{graph} u_0$ (a point $p$ belongs to $D_0$ if every non-spacelike ray through $p$ intersects $\Sigma_0$). $D_0$ is a compact subset of $\mathbb{R}^{n,1}$, and, since $X = X_0$ on $\partial \Sigma_0 \times [0, T)$ and $X$ is spacelike, $X(x, t)$ belongs to $D_0$ during the evolution.
6.1. The $C^1$ estimate.

6.1.1. The maximum principle for the first derivatives.

**Proposition 6.2.** Let $X : \Sigma_0 \times [0, T) \to \mathbb{R}^{n,1}$ be a smooth solution of (6.4). Then

$$\sup_{\Sigma_0 \times [0, T)} \nu \leq C,$$

where $C$ depends on the $C^0$ estimate, on $\sup_{D_0 \times [0, T]} |D \log \hat{f}|_{eucl}$ and on an upper bound of $\nu$ on the parabolic boundary $\partial \Sigma_0 \times [0, T) \cup \Sigma_0 \times \{0\}$.

**Proof.** Let $K$ be a positive constant to be chosen later. At an interior maximum of $\psi = e^{Ku} \nu$, we have

$$\frac{d}{dt} \log \psi - F^{ij}(\log \psi)_{ij} \geq 0.$$

Thus, using (5.5),

$$\frac{d}{dt} (\log \nu) - F^{ij}(\log \nu)_{ij} - K \hat{f} \nu \geq 0. \quad (6.5)$$

Moreover, we have

$$\frac{d}{dt} (\log \nu) - F^{ij}(\log \nu)_{ij} = \frac{1}{\nu} (\dot{\nu} - F^{ij} \nu_{ij}) + \frac{1}{\nu^2} F^{ij} \nu_i \nu_j,$$

with

$$\nu_i = u_i \lambda_i.$$

Here the tensors are written in an orthonormal basis of principal directions, and we used that $g_{ij} t^i t^j \leq \nu^2$. Thus, (6.5) implies

$$\left( \sum_{i=1}^{n} F^{ii} \lambda_i^2 - \sum_{i=1}^{n} F^{ii} \lambda_i^2 \frac{u_i^2}{\nu^2} \right) + K \hat{f} \nu \leq |\nabla \hat{f}|.$$

Discarding the first term which is positive, and using $|\nabla \hat{f}| \leq \nu |D \hat{f}|_{eucl}$, we obtain $K \hat{f} \leq |D \hat{f}|_{eucl}$, which is impossible for $K$ sufficiently large such that

$$K > \sup_{D_0 \times [0, T]} |D \log \hat{f}|_{eucl}. \quad (6.6)$$

Thus, if $K$ satisfies (6.6), the function $\psi = e^{Ku} \nu$ reaches its maximum on the parabolic boundary of $\Sigma_0 \times [0, T)$, and the result follows.  \(\square\)
6.1.2. The $C^1$ estimate at the boundary.

**Proposition 6.3.** Let $u : \overline{\Omega} \times [0, T) \rightarrow \mathbb{R}$ be an admissible solution of (6.1). Then there exists $\vartheta \in (0, 1]$ such that

$$\sup_{\partial \Omega \times [0, T)} |Du| \leq 1 - \vartheta.$$ 

The number $\vartheta$ depends on $\inf_{D_0 \times [0, T]} \hat{f}$, $\sup_{D_0 \times [0, T]} \hat{f}$, and $\sup_{\Omega} |Du_0|$.

**Proof.** We fix $x_0 \in \partial \Omega$, and we denote by $n$ the inner normal of $\partial \Omega$ at $x_0$. We define, for $c(n) = \sqrt{\frac{n-1}{2n}}$,

$$P_1[u] = -\frac{\dot{u}}{\sqrt{1 - |Du|^2}} + c(n)H_1[u], \quad P_2[u] = -\frac{\dot{u}}{\sqrt{1 - |Du|^2}} + H_2[u]^{\frac{1}{2}}.$$  

(6.7)

The construction of the upper barrier. Let $u_1$ be a spacelike function such that $u_1 \geq u_0$ in $\overline{\Omega}$, $u_1 = u_0$ on $\partial \Omega$, and $c(n)H_1[u_1] \leq \inf_{D_0 \times [0, T]} \hat{f}$. We may take for $u_1$ the solution of $H_1[u_1] = c$ in $\Omega$, $u_1 = u_0$ on $\partial \Omega$, where $c$ is a small constant; this Dirichlet problem is solved in [2], Theorem 4.1. Defining $u_1(x, t) := u_1(x)$, we have $P_1[u_1] \leq P_1[u]$ (since $P_1[u] = \hat{f} + c(n)H_1[u] - H_2[u]^{\frac{1}{2}}$ and using (1.1)), $u_1 \geq u$ on the parabolic boundary, and thus, by the maximum principle, $u_1 \geq u$ on $\overline{\Omega} \times [0, T)$. Since $u_1(x_0, t) = u(x_0, t) = u_0(x_0)$ for all $t \in [0, T)$, we obtain

$$\partial_n u(x_0, t) - \partial_n u_1(x_0) \leq 0, \quad \forall t \in [0, T).$$

The construction of the lower barrier. Let $u_2$ be an admissible function such that $u_2 \leq u_0$ in $\overline{\Omega}$, $u_2 = u_0$ on $\partial \Omega$, and $H_2[u_2]^{\frac{1}{2}} \geq \sup_{D_0 \times [0, T]} \hat{f}$. We may take for $u_2$ the strictly convex and spacelike solution of $K[u_2] = c$ in $\Omega$, $u_2 = u_0$ on $\partial \Omega$, where $c$ is a large constant; $K[u_2]$ stands for the Gauss curvature of graph $u_2$; this Dirichlet problem is solved in [7]. Defining $u_2(x, t) := u_2(x)$, we have $P_2[u_2] \geq P_2[u]$ on $\Omega \times (0, T)$, $u_2 \leq u$ on the parabolic boundary, and thus, by the maximum principle, $u_2 \leq u$ on $\overline{\Omega} \times [0, T)$. Since $u_2(x_0, t) = u(x_0, t) = u_0(x_0)$ for all $t \in [0, T)$, we obtain

$$\partial_n u(x_0, t) \geq \partial_n u_2(x_0), \quad \forall t \in [0, T).$$

Finally, since the tangential derivatives at the boundary of $u, u_1$ and $u_2$ coincide, we get

$$\sup_{\partial \Omega \times [0, T)} |Du| \leq \max(\sup_{\partial \Omega} |Du_1|, \sup_{\partial \Omega} |Du_2|),$$

and the result follows. \qed

6.2. The velocity estimate.

**Proposition 6.4.** Let $X$ be an admissible solution of the parabolic Dirichlet problem (6.4). We recall that $\hat{f} \leq 0$ and we suppose that $C$ and $K$ are two positive constants such that

$$|\hat{f}| \leq C \quad \text{and} \quad |N^\alpha \hat{f}| \leq K.$$  

(6.8)
during the evolution. If \( F - \hat{f} \geq 0 \) at \( t = 0 \) then, for all \( t \in [0, T) \),

\[
0 \leq F - \hat{f} \leq e^{Kt} \sup_{t=0} (F - \hat{f}) + \frac{C}{K} (e^{Kt} - 1).
\] (6.9)

In particular, there exist two constants \( \alpha_0, \beta_0 > 0 \) such that

\[
\alpha_0 \leq F \leq \beta_0
\] (6.10)
on \( \Sigma_0 \times [0, T) \). The constants \( \alpha_0, \beta_0 \) depend on \( C, K, T, \sup_{t=0} (F - \hat{f}), \) and \( \inf_{D_0 \times [0, T]} \hat{f} \).

Remark 6.5. The constants \( C \) and \( K \) in (6.8) are controlled by \( \sup_{D_0 \times [0, T]} |\hat{f}|, \sup_{D_0 \times [0, T]} |D^1 \hat{f}|_{\text{euc}}, \) and by the \( C^1 \) estimate obtained Section 6.1.

Proof. We first consider \( \Psi_1 := (F - \hat{f}) e^{-Kt} \). The evolution equation of \( \Psi_1 \) is

\[
\dot{\Psi}_1 - F^{ij} \Psi_{1ij} = \left[ \frac{d}{dt} (F - \hat{f}) - F^{ij} (F - \hat{f})_{ij} - K (F - \hat{f}) \right] e^{-Kt}
\]

\[
= \left[ -F^{ij} h_{ik} h_j^k (F - \hat{f}) - N^{\alpha} \hat{f}_\alpha (F - \hat{f}) - \hat{f}_t - K (F - \hat{f}) \right] e^{-Kt}
\]

\[
\geq \left[ -F^{ij} h_{ik} h_j^k - N^{\alpha} \hat{f}_\alpha - K \right] \Psi_1,
\]
since \( \hat{f}_t \leq 0 \). Let \( T_1 \in (0, T) \). The function \( \Psi_1 \) on \( \Omega \times [0, T_1] \) reaches its minimum at some point \((x_0, t_0)\). Assume that \((x_0, t_0) \in \Omega \times (0, T_1)\) and that \( \Psi_1(x_0, t_0) < 0 \). At \((x_0, t_0)\), we have \( \dot{\Psi}_1 - F^{ij} \Psi_{1ij} \leq 0 \), which gives

\[
-F^{ij} h_{ik} h_j^k - N^{\alpha} \hat{f}_\alpha - K \geq 0
\] (6.11)

and a contradiction with (6.8). Since \( \Psi_1 \geq 0 \) on the parabolic boundary, we conclude that \( \Psi_1 \geq 0 \) on \( \Omega \times [0, T) \), and thus that \( F - \hat{f} \geq 0 \) on \( \Omega \times [0, T) \).

We now consider \( \Psi_2 := \left( F - \hat{f} + \frac{C}{K} \right) e^{-Kt} \), whose evolution equation is

\[
\dot{\Psi}_2 - F^{ij} \Psi_{2ij} = \left[ -F^{ij} h_{ik} h_j^k (F - \hat{f}) - N^{\alpha} \hat{f}_\alpha (F - \hat{f}) - \hat{f}_t - K (F - \hat{f}) - C \right] e^{-Kt}.
\]

Let \( T_2 \in (0, T) \). The function \( \Psi_2 \) on \( \Omega \times [0, T_2] \) reaches its maximum at some point \((x_0, t_0)\). Assume that \((x_0, t_0) \in \Omega \times (0, T_2)\) and that \( \Psi_2(x_0, t_0) > \frac{C}{K} \).

The latter implies that \( F - \hat{f} > 0 \) at \((x_0, t_0)\). At \((x_0, t_0)\), \( \dot{\Psi}_2 - F^{ij} \Psi_{2ij} \geq 0 \), which gives

\[
-F^{ij} h_{ik} h_j^k (F - \hat{f}) - N^{\alpha} \hat{f}_\alpha (F - \hat{f}) - \hat{f}_t - K (F - \hat{f}) - C \geq 0
\] (6.12)

and a contradiction with (6.8). Since \( \Psi_2 \leq \frac{C}{K} \) on \( \partial \Omega \times [0, T] \) and \( \Psi_2 \geq \frac{C}{K} \) on \( \Omega \times \{0\} \), we conclude that, for all \((x, t) \in \Omega \times [0, T)\),

\[
\Psi_2(x, t) \leq \sup_{x \in \Omega} \Psi_2(x, 0),
\]

which proves the proposition. \( \Box \)

6.3. The \( C^2 \) estimate.
6.3.1. The maximum principle for the second derivatives.

**Proposition 6.6.** Let \( X : \Sigma_0 \times [0, T) \to \mathbb{R}^{n,1} \) be a solution of (6.4). Then
\[
\sup_{\xi \in T \Sigma_t, \ |\xi| = 1} h_{ij} \xi^i \xi^j \leq C
\]
during the evolution, for some constant \( C \) which depends on a bound of the second fundamental form on the parabolic boundary \( \partial \Sigma_0 \times [0, T) \cup \Sigma_0 \times \{0\} \) and on estimates obtained before.

**Proof.** The estimate relies on J. Urbas \( C^2 \) estimate [19] for the elliptic Dirichlet problem. We fix \( T_1 \in (0, T) \). For \( t \in [0, T_1] \), \( x \in \Sigma_0 \), and \( \xi \in T_{X(x,t)} \Sigma_t \) with \( |\xi| = 1 \), we consider
\[
\tilde{W}(x, \xi, t) := \eta^\beta (X(x, t)) h_{ij} \xi^i \xi^j,
\]
where \( \eta \) is a positive function on \( \mathbb{R}^{n,1} \) and \( \beta \) is a positive constant, which will be defined later. We suppose that \( \tilde{W} \) reaches its maximum at \( (x_0, \xi_0, t_0) \) where \( t_0 \in (0, T_1] \), \( x_0 \) is an interior point of \( \Sigma_0 \), and \( \xi_0 \in T_{X(x_0,t_0)} \Sigma_{t_0} \), with \( |\xi_0| = 1 \). We choose \( \hat{e}_1^0, \ldots, \hat{e}_n^0 \) a local frame on \( \Sigma_0 \) which induces on \( \Sigma_{t_0} \) an orthonormal frame \( \hat{e}_1, \ldots, \hat{e}_n \) such that
\[
\hat{e}_1(X(x_0, t_0)) = \xi_0 \quad \text{and} \quad \nabla_{\hat{e}_i} \hat{e}_j(X(x_0, t_0)) = 0.
\]
Observe that \( \hat{e}_1 \) is a principal direction of \( \Sigma_{t_0} \) at \( X(x_0, t_0) \), associated to the largest principal curvature. We still denote by \( \hat{e}_1, \ldots, \hat{e}_n \) the frame induced by \( e_1^0, \ldots, e_n^0 \) on \( \Sigma_t \), for every \( t \). The function
\[
W(x, t) := \eta^\beta II(\hat{e}_1, \hat{e}_1)/|\hat{e}_1|^2,
\]
where \( II \) stands for the second fundamental form of \( \Sigma_t \), reaches its maximum at \( (x_0, t_0) \); we get
\[
\frac{d}{dt} \log W - F^{ij} (\log W)_{ij} = \beta \left( \log \eta - F^{ij} (\log \eta)_{ij} \right) + \frac{1}{h_{11}} \left( \dot{h}_{11} - F^{ij} h_{11;ij} \right)
+ \frac{1}{h_{11}} F^{ij} h_{11;ij} - \frac{g_{11}}{g_{11}} \geq 0.
\]
From the evolution equation (5.4), we get:
\[
\dot{h}_{11} - F^{ij} h_{11;ij} = F h_{11}^2 - h_{11} F^{kl} (h_k^a h_{al})
+ F^{kl, pq} h_{kl;1} h_{pq;1} - \dot{f}_{11} + (F - \dot{f}) h_{11}^2,
\]
and thus:
\[
\beta \left( \log \eta - F^{ij} (\log \eta)_{ij} \right) + F h_{11} - F^{kl} (h_k^a h_{al})
+ \frac{1}{h_{11}} F^{kl, pq} h_{kl;1} h_{pq;1} - \frac{\dot{f}_{11}}{h_{11}} + (F - \dot{f}) h_{11}
+ \frac{1}{h_{11}} F^{ij} h_{11;ij} - \frac{g_{11}}{g_{11}} \geq 0. \tag{6.13}
\]
Recalling (6.10), \( |F - \dot{f}| \) is under control, and we have the following estimates (where the largest principal curvature is denoted by \( \lambda_1 \), and \( C_1, C_2, C_3 \) are constants under control):
\[
F h_{11} + (F - \dot{f}) h_{11} \leq C_1 (1 + \lambda_1),
\]
\[ |\hat{f}_{11}| \leq C_2(1 + \lambda_1), \quad (6.14) \]

and, from (5.2),
\[ \left| \frac{g_{11}}{g_{11}} \right| \leq C_3\lambda_1. \]

For estimate (6.14), we refer to [19] p312-313. Thus
\[
0 \geq -\beta \left( \log \eta - F^{ij}(\log \eta)_{ij} \right) + F^{kl}(h^a_k h_{al}) - C_4(1 + \lambda_1) - \frac{1}{h_{11}} F^{kl, pq} h_{kl, 1} h_{pq, 1} - \frac{1}{h_{11}^2} F^{ij} h_{11, i} h_{11, j}, \]

for some constant $C_4$. We choose $\log \eta = \Phi$, with
\[
\Phi(x_1, \ldots, x_n, x_{n+1}) := \varphi(x_1, \ldots, x_n),
\]

where $\varphi$ is some strictly convex function on $\mathbb{R}^n$. Note that
\[
\dot{\log \eta} = (F - \hat{f}) d\Phi_{X(x_0, t_0)}(N) \quad (6.16)
\]
is under control. Moreover, following J.Urbas [19], page 313,
\[
F^{ij}(\log \eta)_{ij} \geq C_0\tau - C
\]
where $\tau = \sum_i F^{ii}$, and $C_0, C$ are constants under control. Finally,
\[
0 \geq \beta(C_0\tau - C') + F^{kl}(h^a_k h_{al}) - C_4(1 + \lambda_1) - \frac{1}{\lambda_1} F^{kl, pq} h_{kl, 1} h_{pq, 1} - \frac{1}{\lambda_1^2} F^{ij} h_{11, i} h_{11, j},
\]

where $C'$ is under control, which is analogous to inequality (2.8) obtained by J.Urbas in [19] page 312. We then obtain the estimate of $\lambda_1$ following the arguments used in [19] p. 314-315, without any modification. This gives the $C^2$ estimate if the $C^2$ estimate at the parabolic boundary is known. \[\Box\]

6.3.2. The $C^2$ estimate at the boundary.

**Proposition 6.7.** Let $u : \overline{\Omega} \times [0, T) \to \mathbb{R}$ be a smooth solution of the parabolic Dirichlet problem (6.1). Then
\[
\sup_{(x,t)\in\partial\Omega\times(0,T)} |D^2u(x,t)| \leq C,
\]

for some constant $C$ under control (which depends on the estimates obtained Sections 6.1 and 6.2).

We fix $(x_0, t_0) \in \partial \Omega \times (0, T)$. Following [15], we write the evolution equation (6.1) on the form
\[
-\dot{u} + \tilde{F}(Du, D^2u) = \hat{f}(x, u, t) \times \gamma(Du),
\]

where $\gamma(Du) = \sqrt{1 - |Du|^2}$, and $\tilde{F}(Du, D^2u)$ is the square root of the second elementary symmetric function of the principal values of the $n \times n$ matrix whose coefficient $(i, j)$ is given by
\[
\sum_{k=1}^n \left( \delta_{ik} + \frac{u_i u_k}{1 - |Du|^2} \right) u_{kj}. \quad (6.17)
\]
Let us consider the linear operator
\[
LW := -\dot{W} + \tilde{F}^{ij}W_{ij},
\]
where \(\tilde{F}^{ij} = \partial_{W_{ij}}(Du, D^2u)\). We suppose that \((e_1, \ldots, e_n)\) is a basis such that \((e_1, \ldots, e_{n-1})\) is an orthonormal basis made of principal vectors of \(\partial \Omega\) at \(x_0\) and \(e_n\) is the unit inner normal of \(\Omega\) at \(x_0\). Let
\[
W(x, t) := g(x, Du(x, t)) - K^2n^{-1}\sum_{k=1}^{n-1}(u_k(x, t) - u_k(x_0, t_0))^2,
\]
where \(g : \overline{\Omega} \times B(0, 1) \to \mathbb{R}\) is a given smooth function and \(K\) is a constant.

The following key inequality is a lorentzian analog of (2.4) in [15]:

**Lemma 6.8.** If \(K\) is sufficiently large under control, \(W\) satisfies
\[
LW \leq C_1(1 + |DW| + \sum_{ij} \tilde{F}^{ij}W_iW_j + \sum_i \tilde{F}^{ii}),
\]
where \(C_1\) depends on the \(C^1\) estimate and on the constants \(\alpha_0, \beta_0\) in (6.10).

*Sketch of the proof:* following the lines of [15] Section 3, we obtain the following expression for \(LW\), which is analogous to (3.13) in [15]:
\[
LW = -K\sum_{\alpha=1}^{n} \tilde{\sigma}_{1,\alpha} u_\alpha^2 \left( \sum_{k=1}^{n-1} \eta_k^2 \right) + j_1 + j_2 + j_3,
\]
with
\[
j_1 = -2\sum_{\alpha=1}^{n} \tilde{\sigma}_{1,\alpha} u_\alpha W_\alpha,
\]
\[
|j_2| \leq C \left( \sum_{\alpha=1}^{n} \tilde{\sigma}_{1,\alpha}|u_\alpha| + \sum_{\alpha=1}^{n} \tilde{\sigma}_{1,\alpha} \right) \text{ and } |j_3| \leq C (1 + |DW|),
\]
where \(C\) is a constant under control. Here we use the letter \(\alpha\) for derivatives in a basis \((\tau_\alpha)\) of \(\mathbb{R}^n\) which induces by the map \(x \mapsto (x, u(x, t))\) an orthonormal basis of principal vectors of graph \(u\) at \((x, u(x, t))\); moreover \(\tilde{\sigma}_{1,\alpha}\) denotes a sum of principal values of (6.17), and the numbers \(\eta_k^\alpha\) are such that \(e_k = \sum_\alpha \eta_k^\alpha \tau_\alpha\), for \(k = 1, \ldots, n\). Expression (6.19) is also analogous to (26) in [3]. We then follow the arguments in [3], from page 19 to page 23, without modification, and obtain (6.18). \(\square\)

Setting
\[
\tilde{W}(x, t) := \exp\left( -C_1g(x_0, Du(x_0, t_0))\right) - \exp(-C_1W) - b|x - x_0|^2,
\]
the following holds (see [15], inequality (2.5)):
Lemma 6.9. If b is sufficiently large,
\[ L\tilde{W} \leq C_2(1 + |D\tilde{W}|), \]
where \( C_2 \) is some constant under control.

We first estimate the mixed second derivatives. Let \( e_s \) be a unit vector tangent to \( \partial\Omega \) at \( x_0 \), and let \( \xi \) be the local vector field tangent to the boundary, and spanned by the vector \( e_s \) : for all \( x \in \overline{\Omega} \cap B_r(x_0) \),
\[ \xi(x) := e_s + \rho_s(x')e_n, \]
where \( e_n \) is the inner normal vector of \( \Omega \) at \( x_0 \), and where, in the splitting \( \mathbb{R}^n = T_{x_0}\partial\Omega \oplus \mathbb{R} e_n, x - x_0 = (x', x_n) \) and \( \partial\Omega \) is locally the graph of \( \rho \).
As in [3], we take \( g(x, p) = (p, \xi(x)) \), and we define the barrier function
\[ v = -a_0|x - x_0|^2 - h(d) + \psi(x'), \]
with \( h(d) = c_0(1 - e^{-bd}) \) and
\[ \psi(x') = \exp(-C_1u_0\xi(x_0)) - \exp(-C_1u_0\xi(x')) \exp \left( C_1K\sum_{k=1}^{n-1}(u_{0k}(x') - u_{0k}(x_0))^2 + 2C_1K(|u_{0n}(x')|^2 + 1)|D\rho(x')|^2 \right). \]
Here \( d \) denotes the distance function to the boundary-point \( x_0 \), \( u_0\xi(x) \) denotes \( \langle Du_0(x), \xi(x) \rangle \), and, for a function \( f \) defined on \( \mathbb{R}^n \), an expression like \( f(x') \) stands for \( f(x', \rho(x')) \).

We first verify that \( v \leq \tilde{W} \) on the parabolic boundary of \( \overline{\Omega} \cap B_r(x_0) \times [0, T) \):
- on \( \partial(\overline{\Omega} \cap B_r) \times [0, T) \) : \( v \leq \tilde{W} \) on \( \partial\Omega \cap \overline{B_r} \times [0, T) \) by the very definition of \( \psi \), and on \( \overline{\Omega} \cap \partial B_r \times [0, T) \) if \( a_0 = a_0(r, \sup|\psi|, \sup|\tilde{W}|) \) is chosen sufficiently large.
- on \( (\overline{\Omega} \cap B_r) \times \{0\} \) : we suppose that \( x_0 = 0 \), we fix \( x \in \overline{\Omega} \cap B_r \), and we consider \( \omega(s) = \tilde{W}(sx, 0) - v(sx), s \in [0, 1] \) (\( \Omega \) is convex). We have \( \omega(0) \geq 0 \). Setting
\[ C = \sup_{\mathbb{R}^n \cap B_r \times \{0\}} |D\tilde{W}| + \sup_{\mathbb{R}^n \cap B_r \times \{0\}} |D\psi|, \]
we see by a direct computation that, for all \( s \in [0, 1] \),
\[ \omega'(s) \geq |x|\{b_0c_0e^{-bd} - C\}. \]
We thus obtain the property if \( c_0 = c_0(b_0) \) is chosen large such that
\[ b_0c_0e^{-bd} \geq C. \]  (6.20)

From the proof of Lemma 4.6. in [3], we see that
\[ Lv > C_2(1 + |Dv|) \]
on \( \Omega \cap B_r(x_0) \times (0, T) \), if \( h' = b_0c_0e^{-bd}, \frac{h''}{r^2} = b_0 \) are large, which is compatible with (6.20). The comparison principle implies that \( v \leq \tilde{W} \) on the parabolic domain, and, since \( v(x_0) = \tilde{W}(x_0, t_0) = 0 \), we get
\[ v_n(x_0) \leq \tilde{W}_n(x_0, t_0), \]
which gives the estimate
\[ u_{\text{sn}}(x_0, t_0) \geq C_3, \]
where \( C_3 \) is a controlled constant. As in [3], to estimate \( u_{\text{sn}}(x_0, t_0) \) from above we do the same with \( g(x, p) = -\langle p, \xi(x) \rangle = -p_y - \rho_s(x', e_n) \).

We now estimate the double normal derivatives. A lower bound follows from \( H_1[u] > 0 \) and from the estimates of tangential and mixed second derivatives. To obtain an upper bound, we use a technique of N.S. Trudinger [16, 18]. We used this method in [3] for the elliptic Dirichlet problem. We define, for \( p' \in B(0, 1) \subset \mathbb{R}^{n-1} \) and \( q' \) a \((n-1) \times (n-1)\) symmetric matrix
\[
\tilde{F}_1(p', q') = \sum_{i,j=1}^{n-1} \left( \delta_{ij} + \frac{p'_i p'_j}{1 + |p'|^2} \right) q'_{ij}.
\]
We denote by \( \gamma \) the outward unit normal to \( \partial \Omega \) in \( \mathbb{R}^n \), and by \( \partial \) the tangential differential operator on \( \partial \Omega \). We fix \( T_1 \in (0, T) \), and \((y, t_1) \in \partial \Omega \times [0, T_1] \) such that \( \tilde{F}_1(\partial u_0, \partial^2 u_0 + u_s \partial \gamma) \) reaches its minimum at \((y, t_1)\). As in [3] page 27, an upper bound of \( u_{nn} \) on \( \partial \Omega \times [0, T_1] \) follows from an upper bound of \( u_{nn}(y, t_1) \). We keep the notation introduced above, but here adapted to the boundary-point \( y \). We set
\[ g(x, p) = \tilde{F}_1(\partial u_0(x'), \partial^2 u_0(x') + \langle p, \gamma(x') \rangle \partial \gamma(x')), \]
and
\[ \tilde{W}(x, t) = \exp[-C_1 g(y, Du(y, t_1))] \{ 1 - \exp[-C_1 (g(x, Du(x, t)) - g(y, Du(y, t_1)))] \times \exp \left( C_1 K \sum_{k=1}^{n-1} (u_k(x, t) - u_k(y, t_1))^2 \right) \} - b|x - y|^2. \]
We consider the barrier function
\[ v = -a_0|x - y|^2 - h(d) + \psi(x') \]
with \( h(d) = c_0(1 - e^{-bd_0d}) \) and
\[ \psi(x') = \exp(-C_1 g(y, Du(y, t_1)))) \left\{ 1 - \exp \left( C_1 K \sum_{k=1}^{n-1} (u_{0k}(x') - u_{0k}(y))^2 + 2C_1 K (|u_{0n}(x')|^2 + 1) |Dp(x')|^2 \right) \right\}. \]
For suitable constants \( a_0, b_0, c_0 \) under control, we have \( v \leq \tilde{W} \) on the parabolic boundary of \( \Omega \cap B_r \times [0, T_1] \), and \( L v > C_2(1 + |Dv|) \) in \( \Omega \cap B_r \times [0, T_1] \) (see above the estimate of the mixed derivatives). By the comparison principle and since \( v(y) = \tilde{W}(y, t_1) = 0 \), we obtain that \( v_n(y) \leq \tilde{W}_n(y, t_1) \), which gives
\[ u_{nn}(y, t_1) \leq C_4, \]
where \( C_4 \) is a constant under control. We finally observe that the bound is independent of \( T_1 \).
7. Existence of the entire flow reduced to obtaining local \( C^1 \) and \( C^2 \) estimates, and convergence

We suppose here that \( F, u, \overline{u} \) and \( u_0 \) satisfy the hypotheses of Theorem 1.4: \( \overline{u}, \overline{u} : \mathbb{R}^n \to \mathbb{R} \) are the barriers constructed Section 3 (\( \overline{u} \) is a smooth spacelike and strictly convex function with constant mean curvature \( h \) and \( u \) is the supremum of spacelike functions with constant scalar curvature \( H_2 = k \)) and \( u_0 : \mathbb{R}^n \to \mathbb{R} \) is some smooth spacelike and strictly convex function such that

\[
\underline{u} < u_0 < \overline{u} \quad \text{and} \quad 1 \leq H_2[u_0] \leq k.
\]  

(7.1)

To construct the entire flow, we solve a family of parabolic Dirichlet problems with parabolic boundary data \( u_0 \) on a growing sequence of balls. We modify slightly the equations near the boundary of the balls such that the problems are compatible on the corner of the parabolic domains. This is done in such a way that the normal velocities are uniformly bounded in terms of \( H_2[u_0] \). Moreover the functions \( \underline{u}, \overline{u} \) are still barriers for the modified evolution equations. This theorem is analogous to Theorem B.4 in [5] for the logarithmic Gauss curvature flow.

**Theorem 7.1.** Let \( R > 1 \) and the ball of \( \mathbb{R}^n \), \( B_R := \{ x \in \mathbb{R}^n : |x| < R \} \). We choose a smooth function \( \eta : B_R \times \mathbb{R} \to [0, 1] \) such that \( \eta = 0 \) on \( (B_{R-1} \times \mathbb{R}) \cup \text{graph} \overline{u} \cup \text{graph} u \), and \( \eta = 1 \) near \( \text{graph} u_0 |_{\partial B_R} \). We also choose a smooth function \( \zeta : [0, +\infty) \to [0, 1] \) such that \( \zeta(t) = 1 \) near \( t = 0 \), \( \zeta(t) = 0 \) for \( t \geq 1 \), and \( \zeta' \leq 0 \). We set

\[
\hat{f}(x, u, t) := \eta(x, u)\zeta \left( \frac{t}{\varepsilon} \right) \left[ H_2[u_0]^{\frac{1}{2}} - 1 \right] + 1.
\]  

(7.2)

If \( \varepsilon > 0 \) is chosen sufficiently small, the parabolic Dirichlet problem

\[
\begin{align*}
-\frac{\underline{u}}{\sqrt{1-|Du|^2}} + H_2[u]^{\frac{1}{2}} &= \hat{f}(x, u, t) \quad \text{in} \ B_R \times (0, +\infty) \\
u(x, t) &= u_0(x) \quad \text{on} \ \partial B_R \times [0, +\infty) \cup B_R \times \{0\},
\end{align*}
\]  

(7.3)

has an admissible solution \( u : B_R \times [0, +\infty) \to \mathbb{R} \) such that the normal velocity \( \frac{\underline{u}}{\sqrt{1-|Du|^2}} \) is uniformly bounded in terms of \( H_2[u_0] \). Moreover

\[
\underline{u} \leq u \leq \overline{u}
\]  

(7.4)

for all time.

Observe that \( u \) solution of (7.3) is also solution of (1.10) on \( B_{R-1} \times [0, +\infty) \). We also write problem (7.3) in the equivalent form:

\[
\begin{align*}
\dot{X} &= (F - \hat{f})N \\
X &= X_0 \quad \text{on} \ \partial \Sigma^R_0 \times [0, +\infty) \cup \Sigma^R_0 \times \{0\},
\end{align*}
\]  

(7.5)

where \( \hat{f} \) is given by (7.2), \( \Sigma^R_0 = \text{graph}_{\overline{u}_R} u_0 \) and \( X : \Sigma^R_0 \times [0, +\infty) \to \mathbb{R}^{n+1} \) is the embedding function.
Proof. The existence of a solution follows from Theorem 6.1: \( \hat{f}_t \leq 0 \) holds, the compatibility conditions are fulfilled on the corner of the parabolic domain, and, observing that

\[
\hat{f}_{|t=0} = \eta H_2[u_0]^{\frac{1}{2}} + (1 - \eta)1 \leq H_2[u_0]^{\frac{1}{2}},
\]

we get \( (H_2^{\frac{1}{2}} - \hat{f})_{|t=0} \geq 0 \).

We now prove (7.4). We consider the operators \( P_1, P_2 \) defined in (6.7). We recall that \( u \) is of the form \( u = \sup_{i \in I} u_i \), where for all \( i \in I \) the function \( u_i \) is spacelike with \( H_2[u_i] = k \). Defining \( u_i(x, t) \) := \( u_i(x) \), we have \( P_2[u_i] = H_2[u_i]^{\frac{1}{2}} = k^{\frac{1}{2}} \). Moreover, from (7.2)-(7.1), we have \( P_2[u] = \hat{f} \leq k^{\frac{1}{2}} \).

Thus, since \( u \geq u_i \) on the parabolic boundary, we get by the maximum principle that \( u \geq u_i \) during the evolution, and finally that \( u \geq u \). Now, setting \( \overline{u}(x, t) := \overline{u}(x) \), we get

\[
P_1[\overline{u}] = c(n)h.
\]

Moreover, since \( \hat{f} \geq 1 \) and recalling (1.1), we have

\[
P_1[u] = f + c(n)H_1[u] - H_2[u]^{\frac{1}{2}} \geq 1.
\]

Since \( c(n)h \leq 1 \) (see Proposition 1.1), (7.7) and (7.8) imply that \( P_1[u] \geq P_1[\overline{u}] \), and thus that \( u \leq \overline{u} \) since this inequality also holds on the parabolic boundary.

We now estimate the normal velocity. We consider \( X : \Sigma_0^R \times [0, +\infty) \to \mathbb{R}^{n,1} \) solution of (7.5). We first suppose that \( t \in [0, \varepsilon] \). We note that \( |\hat{f}_t| \leq \frac{C_0}{\varepsilon K} \) where \( C_0 \) is a constant controlled in terms of \( H_2[u_0] \); recalling inequality (6.9) in Proposition 6.4, we get

\[
0 \leq F - \hat{f} \leq e^{Kt} \sup_{t=0} (F - \hat{f}) + \frac{C_0}{\varepsilon K} (e^{Kt} - 1),
\]

where \( K \) is a bound of \( |N^\alpha \hat{f}_\alpha| \). Observe that \( K \) may grow with \( R \) but is independent of \( \varepsilon \) (see Propositions 6.2 and 6.3). Taking \( \varepsilon = \frac{1}{K} \), we get the estimate: for all \( t \in [0, \varepsilon] \),

\[
0 \leq F - \hat{f} \leq C \left( \sup_{t=0} (F - \hat{f}), C_0 \right),
\]

where the right-hand side term is a constant bounded in terms of \( H_2[u_0] \).

For \( t \geq \varepsilon \) the normal velocity fulfills

\[
\frac{d}{dt} (F - \hat{f}) - F^{ij} (F - \hat{f})_{ij} = -(F - \hat{f}) F^{ij} h_{ik} h^k j,
\]

and the maximum principle implies that

\[
0 \leq F - \hat{f} \leq \sup_{t=\varepsilon} (F - \hat{f}).
\]

Estimates (7.9) and (7.10) imply the estimate of the normal velocity during the evolution in terms of the curvature \( H_2[u_0] \) only. \( \square \)
We set $u_R$ for a solution of the parabolic Dirichlet problem (7.3) on $\overline{B}_R \times [0, +\infty)$, $R > 1$. By construction, the normal velocity of the solution $u_R$ is bounded by a constant which is independent of $R$. Suppose that the following estimates hold: for any $R_0 \geq 0$, there exists $R_1 = R_1(R_0)$ larger than $R_0$, $\dot{\vartheta} \in (0, 1)$ and $C \geq 0$ such that, for every $R \geq R_1$,

$$
\sup_{\overline{B}_{R_0} \times [0, +\infty)} |Du| \leq 1 - \dot{\vartheta}, \quad \sup_{\overline{B}_{R_0} \times [0, +\infty)} |u_R| + |D^2u_R| \leq C. \quad (7.11)
$$

Then, higher order derivative estimates (due to Krylov, Safonov, and Schauder for positive times) imply that a subsequence converges in

$$
C^\infty(\mathbb{R}^n \times (0, +\infty)) \cap C^{1,\alpha,0,\frac{1}{2}}(\mathbb{R}^n \times [0, +\infty))
$$

for every $0 < \alpha < 1$ to a solution $u \in C^\infty(\mathbb{R}^n \times (0, +\infty)) \cap C^{1,1,0,1}(\mathbb{R}^n \times [0, +\infty))$ of (1.10).

We now prove the convergence of the entire flow $u$, following [9, 10]. We first note that $H_2[u]^\frac{1}{2} \geq 1$ during the evolution, since this property holds for the solutions of the Dirichlet problems (7.3). We deduce that $\dot{u} \geq 0$. Thus, for every $x \in \mathbb{R}^n$, $t \mapsto u(x,t)$ is an increasing function, bounded above by $\overline{u}(x)$, and

$$
u_\infty(x) := \lim_{t \to +\infty} u(x,t)
$$

is well defined. The a priori estimates, locally uniform in space and uniform in time, show that $u_\infty$ is a smooth and spacelike function, and that $u(.,t)$ smoothly converges to $u_\infty$ as $t$ tends to $+\infty$. We now fix $x \in \mathbb{R}^n$. Since $\dot{u} \geq 0$ and $\sup_{t \in [0, +\infty)} |Du(x,t)| < 1$, we get from (1.10) that

$$
0 \leq H_2[u]^\frac{1}{2}(x,t) - 1 \leq c(x)\dot{u}(x,t),
$$

where $c(x) \in \mathbb{R}$ does not depend on $t$. Thus

$$
\int_0^{+\infty} [H_2[u]^\frac{1}{2}(x,t) - 1]dt < +\infty,
$$

and there exists a sequence $(t_n)$ such that $t_n \to +\infty$ and $H_2[u](x,t_n) \to 1$ as $n$ tends to infinity. Thus $u_\infty$ is a solution of (1.6).

In the rest of the article, we prove the local estimates (7.11).

8. THE LOCAL $C^1$ ESTIMATE

We obtain here the local $C^1$ estimate in the spirit of R.Bartnik’s estimate concerning hypersurfaces of prescribed mean curvature. See e.g. [1].

8.1. The estimate with a general time function. We suppose that $X : \Sigma_0 \times [0, +\infty) \to \mathbb{R}$ is a solution of (5.1) with $\tilde{f} \equiv 1$. Let $\tau : \mathbb{R}^{n,1} \to \mathbb{R}$ be a smooth function whose lorentzian gradient $D\tau$ is a timelike and past oriented field ($\tau$ is a time function on $\mathbb{R}^{n,1}$). We set $\alpha^{-2} = -\langle D\tau, D\tau \rangle$ and $T = -\alpha D\tau$. Using the timelike vector field $T$, we define a Riemannian metric on $\mathbb{R}^{n,1}$ by

$$
|Y|_T^2 := \langle Y, Y \rangle + 2\langle Y, T \rangle.
$$
If $S$ is a tensor field on $\mathbb{R}^{n,1}$, we denote by $|S|_T$ its norm with respect to the metric $|.|_T$. For instance, if $Y$ is a vector field on $\mathbb{R}^{n,1}$,

$$|DY|_T = \left( \sum_{i,j=1}^{n+1} (D_{u_i} Y, u_j)^2 \right)^{\frac{1}{2}}$$

where $(u_1, \ldots, u_n, u_{n+1})$ is an orthonormal basis of $\mathbb{R}^{n,1}$ such that $u_{n+1} = T$. We fix $\tau_0 > 0$, and we suppose that, for every $t \geq 0$,

$$\Sigma_{t, \tau \geq \tau_0} := \{ X(x,t) : x \in \Sigma_0, \tau(X(x,t)) \geq \tau_0 \} \quad (8.1)$$

is a compact (spacelike) hypersurface such that $\tau = \tau_0$ on its boundary, and that the set $\Sigma_{t, \tau \geq \tau_0}$ is non-empty. We moreover suppose that $\tau, \alpha, \alpha^{-1}, |D\alpha|_T$, $|DT|_T$ and $|D^2T|_T$ are bounded on the region

$$D_{\tau_0} := \bigcup_{t \geq 0} \Sigma_{t, \tau \geq \tau_0} \quad (8.2)$$

of $\mathbb{R}^{n,1}$, and we fix $\tau_1$ such that $\tau_1 \geq \tau$ on $D_{\tau_0}$. Finally, we assume that $F$ has positive lower and upper bounds on $D_{\tau_0}$. Setting here $\nu := -\langle T, N \rangle$, we prove the following estimate:

**Theorem 8.1.** There exists a constant $C$ such that, for every $t \geq 0$,

$$\sup_{\Sigma_{t, \tau \geq \tau_0}} \nu \leq C. \quad (8.3)$$

The constant $C$ depends on $\tau_0, \tau_1$, upper bounds of $\alpha, \alpha^{-1}, |D\alpha|_T$, $|DT|_T$ and $|D^2T|_T$ on the set $D_{\tau_0}$, on lower and upper bounds of $F$ on $D_{\tau_0}$, and on $\sup_{\Sigma_{t, \tau \geq \tau_0}} \nu$.

This estimate relies on the maximum principle applied to the function $\varphi = \eta \nu$, where $\eta = (\tau - \tau_0)^K$ with $K$ a large constant. We fix $T_1 \in (0, +\infty)$, and we consider $\varphi$ on the compact set

$$J = \{(x,t) \in \Sigma_0 \times [0, T_1] : \tau(X(x,t)) \geq \tau_0 \}.$$

The function $\varphi$ reaches its maximum at a point $(x_0, t_0) \in J$. Our purpose is to estimate $\varphi(x_0, t_0)$ by a constant under control which does not depend on $T_1$; such an estimate clearly implies (8.3). If $t_0 = 0$, we readily get that $\varphi(x_0, t_0) \leq C'$ where $C' = C'(K, \tau_0, \tau_1, \Sigma_{\alpha, \tau \geq \tau_0})$ is a constant, and the result follows. We thus suppose that $t_0 > 0$, and we prove the following proposition, which implies the estimate of $\varphi(x_0, t_0)$, and the theorem:

**Proposition 8.2.** Let $\nu_0 > 1$. If $K$ is sufficiently large,

$$\nu(x_0, t_0) \leq \nu_0.$$ 

The constant $K$ depends on $\nu_0$, $\tau_0, \tau_1$, and on bounds on $\alpha, \alpha^{-1}, |DT|_T$, $|D^2T|_T$ and $F$ on the region $D_{\tau_0}$.
In the following, we suppose that \( \nu(x_0, t_0) > \nu_0 \), and we will obtain a contradiction if \( K \) is large under control. Let us denote by \( T^\parallel \) the orthogonal projection of \( T \) on the tangent space of \( \Sigma_{t_0} \). By definition of \( T \), we have \( T^\parallel = -\alpha \nabla \tau \), and

\[
\nu^2 - 1 = |T^\parallel|^2 = \alpha^2 |\nabla \tau|^2. \tag{8.4}
\]

Let \( Z \) be the tangent vector field of \( \Sigma_{t_0} \) such that \( \langle Z, h \rangle = \langle N, D_h T \rangle \), for all tangent vector \( h \). By a direct computation,

\[
\nabla \nu = -S(T^\parallel) - Z = \alpha S(\nabla \tau) - Z. \tag{8.5}
\]

Here \( S \) stands for the curvature endomorphism of \( \Sigma_{t_0} \).

**Lemma 8.3.** We have

\[
|Z| \leq C_0 \nu^2, \tag{8.6}
\]

where \( C_0 \) only depends on an upper bound of \( |DT|_T \).

**Proof.** Let \( u_1, \ldots, u_n, u_{n+1} \) be an orthonormal basis such that \( u_{n+1} = T \). Writing \( N = \sum_{j=1}^n \alpha_j u_j + \nu T \), we have \( \sum_{j \leq n} \alpha_j^2 = \nu^2 - 1 \). Let \( h := \frac{1}{\sum_{i=1}^{n+1} h_i u_i} \) be a vector tangent to \( \Sigma_{t_0} \). Since \( \langle T, D_h T \rangle = 0 \),

\[
|\langle N, D_h T \rangle| \leq \sum_{i=1}^{n+1} \left| \sum_{j=1}^n h_i \alpha_j \langle u_j, D_{u_i} T \rangle \right| \leq \nu |h|_T |DT|_T. \tag{8.7}
\]

Observe that inequality

\[
|h|_T \leq \sqrt{2} \nu |h| \tag{8.8}
\]

holds for all tangent vector \( h \). To prove this, suppose that \( h \neq 0 \), and define

\[
\delta := \frac{h_{n+1}^2}{\sum_{i=1}^n h_i^2}. \tag{8.9}
\]

By a straightforward computation,

\[
|h|_T^2 = \left( \frac{1 + \delta}{1 - \delta} \right) |h|^2.
\]

Since \( h \) is a tangent vector, \( \langle h, N \rangle = \sum_{i=1}^n h_i \alpha_i - h_{n+1} \nu = 0 \), and the Schwarz inequality readily gives that \( \delta \leq \frac{\nu^2 - 1}{\nu^2} \); inequality (8.8) then follows from (8.9). Finally, inequalities (8.7) and (8.8) imply that \( |\langle Z, h \rangle| \leq \sqrt{2} \nu^2 |h||DT|_T \), and the lemma. \( \square \)

We need the evolution equation of \( \nu \):

**Lemma 8.4.** During the evolution,

\[
\dot{\nu} - F^{ij} \nu_{ij} = \langle D_N T, N \rangle + F^{ij} \langle D_{e_i}^2 T, N \rangle + 2 F^{ij} \langle D_{e_i} T, D_{e_j} N \rangle - \nu F^{ij} h_j^k h_{ki}. \tag{8.10}
\]

Here \((e_i)\) is a basis of \( T\Sigma_t \) at \( X(x, t) \).
Proof. By Lemma 3.3 in [10], the normal evolves according to \( \dot{N} = \nabla F \) (recall that \( \dot{f} \equiv 1 \) here) and thus
\[
\langle T, \dot{N} \rangle = g^{ij} F_{ij} t_j = g^{ij} F^{kl} h_{kl;ij} t_j.
\]
Thus
\[
\dot{\nu} = -\langle \dot{T}, N \rangle - \langle T, \dot{N} \rangle
= -(F - \dot{f}) \langle D_N T, N \rangle - g^{ij} F^{kl} h_{kl;ij} t_j.
\] (8.11)
We fix \((x,t) \in \Sigma_0 \times [0, +\infty)\). Let \((e_i)\) be a local frame of \(\Sigma_t\) such that \(\nabla_{e_i} e_j(X(x,t)) = 0\). Thus \(D_{e_i} e_j(X(x,t)) = h_{ij} N\), and we have
\[
D_{e_j}(D_{e_i} T) = D^2_{e_i,e_j} T + h_{ij} D_N T
\]
and
\[
D_{e_j}(D_{e_i} N) = D_{e_j}(h^k_{ij} e_k) = h^k_{ij} e_k + h^k_i h_{kj} N.
\]
Thus\[
F^{ij}_{\nu ij} = -F^{ij} \langle D^2_{e_i,e_j} T, N \rangle - F \langle D_N T, N \rangle - 2F^{ij} \langle D_{e_i} T, D_{e_j} N \rangle
- F^{ij} h^k_{ij} (\dot{T}, e_k) + F^{ij} h^k_i h_{kj} \nu.
\] (8.12)
Equations (8.11) and (8.12), together with the symmetry in the three indices (the Codazzi equations), imply (8.10).

Thus, the maximum condition \(\frac{d}{dt}(\log \varphi) - F^{ij}(\log \varphi)_{ij} \geq 0\) reads
\[
\left( F^{ij} h^k_{ij} h_{ki} - \frac{1}{\nu^2} F^{ij} \nu \nu_j \right) - \left( \frac{d}{dt} \log \eta - F^{ij}(\log \eta)_{ij} \right)
\leq \frac{1}{\nu} \left( \langle D_N T, N \rangle + F^{ij}(D^2_{e_i,e_j} T, N) + 2F^{ij} \langle D_{e_i} T, D_{e_j} N \rangle \right).
\] (8.13)
Moreover, since \(\nu_i = -h^k_i t_k - Z_i\) (see (8.5)), we get:
\[
F^{ij} h^k_{ij} h_{ki} - \frac{1}{\nu^2} F^{ij} \nu \nu_j = \left( F^{ij} h^k_{ij} h_{ki} - \frac{1}{\nu^2} F^{ij} h^k_i t_k h^l_j t_l \right)
- \frac{1}{\nu^2} F^{ij} Z_i Z_j - \frac{2}{\nu^2} F^{ij} h^k_i t_k Z_j.
\] (8.14)
We now estimate the terms in the expressions above:

**Lemma 8.5.** There exist constants \(C_1, C_2, C_3\) such that
\[
|\langle D_N T, N \rangle| \leq C_1 \nu^2,
\] (8.15)
\[
\left| F^{ij} \langle D^2_{e_i,e_j} T, N \rangle + \frac{1}{\nu} F^{ij} Z_i Z_j \right| \leq C_2 \sigma_1 \nu^3,
\] (8.16)
and
\[
\left| \frac{2}{\nu} F^{ij} h^k_i t_k Z_j + 2F^{ij} \langle D_{e_i} T, D_{e_j} N \rangle \right| \leq C_3 \nu^2 \sum_i |\lambda_i|.
\] (8.17)
The constants \(C_1, C_2, C_3\) only depend on bounds on \(|DT|_T, |D^2T|_T\) and \(F\).
Proof. Let \((u_i)_{1 \leq i \leq n+1}\) be an orthonormal basis of \(\mathbb{R}^{n,1}\) such that \(u_{n+1} = T\). We suppose that \(e_1, \ldots, e_n\) is an orthonormal basis of principal directions of \(\Sigma_{t_0}\) at \(x_0\), and we define \((\alpha_{ij})_{1 \leq i,j \leq n+1}\) such that

\[
e_i = \sum_{j=1}^{n+1} \alpha_{ij} u_j \text{ and } N = \sum_{j=1}^{n+1} \alpha_{n+1,j} u_j.
\]

The following estimates hold: for all \(i = 1, \ldots, n+1\),

\[
\sum_{j=1}^{n+1} \alpha_{n+1,i} \alpha_{n+1,j} |\langle u_i, D_u_j T \rangle| \leq 2 \nu^2 |DT|_T,
\]

and we get (8.15).

We first prove (8.15): using the Schwarz inequality,

\[
|\langle N, D_N T \rangle| \leq \sum_{i,j=1}^{n+1} |\alpha_{n+1,i}||\alpha_{n+1,j}||\langle u_i, D_u_j T \rangle| \leq 2 \nu^2 |DT|_T,
\]

and we get (8.15).

We estimate the first term in (8.16):

\[
\left| \sum_{ij} F^{ij} \langle N, D^2_{e_i,e_j} T \rangle \right| \leq \frac{1}{2F} \sum_{i} \sigma_{1,i} \sum_{j,l} |\alpha_{n+1,j}||\alpha_{i,l}||\langle u_j, D^2_{u_k,u_l} T \rangle| \leq \frac{1}{2F} (n-1)2^{3/2} \sigma_1 \nu |D^2 T|_T.
\]

For the second term in (8.16), we readily get: \(F^{ij} Z_i Z_j \leq \frac{n-1}{2F} \sigma_1 |Z|^2\), and we obtain the estimate from (8.6).

We finally prove (8.17):

\[
\left| \frac{2}{\nu} F^{ij} h^{k}_{ij} t_k Z_j + 2 F^{ij} \langle D_{e_i} T, D_{e_j} N \rangle \right| \leq \frac{1}{F} \sum_i \sigma_{1,i} |\lambda_i| \left( \frac{1}{\nu} |t_i||Z_i| + |\langle D_{e_i} T, e_i \rangle| \right);
\]

using \(|T|| \leq \nu, |Z| \leq C_0 \nu^2\) (Lemma 8.3) and \(|\langle D_{e_i} T, e_i \rangle| \leq 2 \nu^2 |DT|_T\) we obtain (8.17).

We now prove that the smallest principal curvature of \(\Sigma_{t_0}\) at \(x_0\) is negative, with absolute value arbitrarily large, if the constant \(K\) is chosen sufficiently large:

**Lemma 8.6.** If

\[
K \geq 2C_0 \alpha (\tau_1 - \tau_0) \frac{\nu^2}{\nu^2 - 1},
\]

the smallest principal curvature \(\lambda_n\) is negative and is estimated by

\[
\lambda_n \leq -\frac{1}{2} \frac{\alpha^{-1} K}{\nu}. \tag{8.19}
\]

Note that since \(\varphi\) vanishes if \(\tau = \tau_0\) and is positive if \(\tau > \tau_0\), we have \(\tau > \tau_0\) at \((x_0, t_0)\).
Proof. By (8.5),

\[ S(\nabla \tau) = \frac{1}{\alpha}(\nabla \nu + Z); \]

moreover, the extremum condition \( \nabla \varphi(x_0, t_0) = 0 \) reads

\[ \frac{\nabla \nu}{\nu} = -\frac{K}{\tau - \tau_0} \nabla \tau. \]

Thus

\[ \left\langle S\left(\frac{\nabla \tau}{|\nabla \tau|}\right), \frac{\nabla \tau}{|\nabla \tau|}\right\rangle = -\nu \alpha^{-1} \frac{K}{\tau - \tau_0} + \frac{\alpha^{-1}}{|\nabla \tau|^2} \langle Z, \nabla \tau \rangle. \tag{8.20} \]

By Lemma 8.3 and expression (8.4), we estimate

\[ \frac{\alpha^{-1}}{|\nabla \tau|^2} \langle Z, \nabla \tau \rangle \leq \alpha^{-1} \frac{|Z|}{|\nabla \tau|} \leq C_0 \frac{\nu^3}{\nu^2 - 1}. \]

Since \( \nu > \nu_0 > 1 \), we have \( \frac{\nu^2}{\nu^2 - 1} \leq \frac{\nu_0^2}{\nu_0^2 - 1} \), and thus

\[ -\nu \alpha^{-1} \frac{K}{\tau - \tau_0} + C_0 \frac{\nu^3}{\nu^2 - 1} \leq \nu \left(-\alpha^{-1} \frac{K}{\tau - \tau_0} + C_0 \frac{\nu_0^2}{\nu_0^2 - 1}\right) \leq -\frac{1}{2} \alpha^{-1} \frac{K}{\tau - \tau_0} \nu \]

if \( \frac{1}{2} \alpha^{-1} \frac{K}{\tau - \tau_0} \geq C_0 \frac{\nu_0^2}{\nu_0^2 - 1} \), which follows from the hypothesis (8.18). Thus

expression (8.20) is bounded by \( -\frac{1}{2} \alpha^{-1} \frac{K}{\tau - \tau_0} \nu \), and the result follows. \( \square \)

As in Lemma 4.6. of [4], we obtain the key inequality:

**Lemma 8.7.** If \( \lambda_n \leq 0 \),

\[ F^{ij} h_k^i h_{k_j} - \frac{1}{\nu^2} F^{ij} h_i^k h_j^l t_l \geq \varepsilon \sigma_{1,n} \lambda_n^2, \]

where \( \varepsilon \) is a positive constant which only depends on an upper bound of \( F \).

**Proof.** Just follow the lines of the proof of Lemma 4.6. in [4], with \( \lambda_n \) instead of \( \lambda_{i_0} \) and \( t_i \) instead of \( u_i \), using here identity (8.4). \( \square \)

Inequality (8.13) and Lemmas 8.5 and 8.7 thus imply that

\[ \varepsilon \sigma_{1,n} \lambda_n^2 - \left( \frac{d}{dt} \log \eta - F^{ij} (\log \eta)_{ij} \right) \leq C_1 \nu + C_2 \sigma_1 \nu^2 + C_3 \nu \sum_i \sigma_{1,i} |\lambda_i| \]

\( \tag{8.21} \)

The next lemma permits to balance the last term in (8.21):

**Lemma 8.8.** If \( \lambda_n \leq 0 \), then, for all \( i \),

\[ \sigma_{1,i} |\lambda_i| \leq \sigma_2 + \frac{\beta}{\nu} \sigma_{1,n} \lambda_n^2, \]

where \( \beta \) is a constant arbitrarily small, if \( K = K(\alpha, \beta, \tau_0, \tau_1) \) is chosen sufficiently large.
Proof. We first suppose that $\lambda_i \leq 0$ : we thus have $|\lambda_i| \leq |\lambda_n|$, and, since $\sigma_{1, n} \geq \sigma_{1, i}$,

$$\sigma_{1, i}|\lambda_i| \leq \sigma_{1, n}|\lambda_n|.$$ 

By estimate (8.19) in Lemma 8.6, $\frac{\nu}{\beta} \leq |\lambda_n|$, if $K = K(\tau_0, \tau_1, \alpha, \nu_0, \beta)$ is sufficiently large. This implies

$$\sigma_{1, i}|\lambda_i| \leq \frac{\beta}{\nu} \sigma_{1, n} \lambda_n^2,$$

and the estimate. We now suppose that $\lambda_i \geq 0$ : the proof relies on the following inequality:

$$\lambda_i \sigma_{1, i} \leq \sigma_2 + \gamma_n \sigma_{1, n} |\lambda_n|, \quad (8.22)$$

where $\gamma_n$ is a positive constant which only depends on $n$. With this inequality at hand, taking as above $K$ sufficiently large such that $\frac{\nu}{\beta} \leq |\lambda_n|$, we obtain the lemma. To finish the proof we thus focus on the proof of (8.22): first,

$$\lambda_i \sigma_{1, i} = \sigma_2 - \sigma_{2, in} - \sigma_{1, ni} \lambda_n,$$

where $-\sigma_{2, in}$ is a sum of terms of the form $-\lambda_j \lambda_k$, with $j \neq k$, and $j, k \notin \{i, n\}$. We observe that $-\sigma_{1, ni} \lambda_n = \sigma_{1, ni} |\lambda_n| \leq \sigma_{1, n} |\lambda_n|$, since $\lambda_i \geq 0$. It thus remains to bound the positive terms appearing in $-\sigma_{2, in}$ : let $j, k \notin \{i, n\}$ be such that $-\lambda_j \lambda_k > 0$. We suppose that $\lambda_k < 0$, and thus that $\lambda_j > 0$. We have $\lambda_j \leq \sigma_{1, n} \lambda_n = \lambda_j + \sigma_{1, j} - \lambda_n$ with $\sigma_{1, j}$ and $-\lambda_n$ positive. Moreover $|\lambda_k| \leq |\lambda_n|$ since $\lambda_n \leq \lambda_k \leq 0$. Thus $-\lambda_j \lambda_k \leq \sigma_{1, n} |\lambda_n|$, which concludes the proof of (8.22). \[ \square \]

From (8.21) and Lemma 8.8 we obtain the inequality

$$\varepsilon \sigma_{1, n} \lambda_n^2 - \left( \frac{d}{dt} \log \eta - F_{ij} (\log \eta)_{ij} \right) \leq C_1 \nu + C_2 \sigma_1 \nu^2 + n C_3 \nu \left( \sigma_2 + \frac{\beta}{\nu} \sigma_{1, n} \lambda_n^2 \right). \quad (8.23)$$

Choosing $\beta$ small such that $\varepsilon - n C_3 \beta \geq \frac{\varphi}{\varphi}$, we obtain

$$\frac{\varepsilon}{2} \sigma_{1, n} \lambda_n^2 - \left( \frac{d}{dt} \log \eta - F_{ij} (\log \eta)_{ij} \right) \leq C_1 \nu + C_2 \sigma_1 \nu^2 + n C_3 \nu \sigma_2. \quad (8.24)$$

We now estimate the contribution of the cut-off function:

**Lemma 8.9.** There exists a constant $C_4$ such that

$$\frac{d}{dt} (\log \eta) - F_{ij} (\log \eta)_{ij} \leq C_4 K \nu^2 \frac{\sigma_1}{\tau - \tau_0} \left( 1 + \frac{1}{\tau - \tau_0} \right).$$

The constant $C_4$ depends on bounds on $\alpha^{-1}, |D\alpha|_T, |DT|_T$ and $F$.

**Proof.** By a direct computation,

$$\frac{d}{dt} (\log \eta) = (F - \hat{f}) \frac{K}{\tau - \tau_0} D\tau(N).$$

Since $|D\tau(N)| = \nu \alpha^{-1}$, we get

$$\frac{d}{dt} (\log \eta) \leq C \frac{K}{\tau - \tau_0} \nu, \quad (8.25)$$
where \( C \) depends on bounds on \( \alpha^{-1} \) and \( F - \hat{f} \). Moreover
\[
\sum_i \sigma_{1,i} (\log \eta)_{ii} = K \left( \sum_i \sigma_{1,i} \frac{\tau_{1,i}}{\tau - \tau_0} - \sum_i \sigma_{1,i} \frac{\tau_{1,i}^2}{(\tau - \tau_0)^2} \right). \quad (8.26)
\]
Using (8.4), the last term is directly estimated by
\[
\sum_i \sigma_{1,i} \frac{\tau_{1,i}^2}{(\tau - \tau_0)^2} \leq (n-1)\alpha^{-2} \nu^2 \frac{\sigma_1}{(\tau - \tau_0)^2}. \quad (8.27)
\]
To estimate the first term in (8.26), we extend \( e_1, \ldots, e_n \) to vector fields of \( \Sigma_0 \) such that \( \nabla_{e_i} e_i(x_0) = 0 \). Since \( \tau_i = -\langle \alpha^{-1} T, e_i \rangle \) and \( D_{e_i} e_i = \lambda_i N \), we get
\[
\tau_{ii} = -\langle D_{e_i} (\alpha^{-1} T), e_i \rangle + \alpha^{-1} \nu \lambda_i.
\]
Since \( \langle D_{e_i} (\alpha^{-1} T), e_i \rangle = (\alpha^{-1})_i (T, e_i) + \alpha^{-1} \langle D_{e_i T}, e_i \rangle \), and since
\[
|\langle T, e_i \rangle| \leq \nu, \quad |\langle D_{e_i T}, e_i \rangle| \leq 2\nu |DT|_T, \quad \text{and} \quad |(\alpha^{-1})_i| \leq \sqrt{2} \nu |D\alpha^{-1}|_T
\]
(see the proof of Lemma 8.5), we obtain
\[
\left| \sum_i \sigma_{1,i} \frac{\tau_{1,i}}{\tau - \tau_0} \right| \leq \frac{\alpha^{-1}}{\tau - \tau_0} \left( 2(n-1)\sigma_1 \nu^2 \left\{ \frac{1}{\alpha^{-1}} |D\alpha^{-1}|_T + |DT|_T \right\} + 2\nu \sigma_2 \right).
\]
Observing moreover that \( \sigma_1 \) is bounded below by a positive constant (MackLaurin inequality), this last estimate together with (8.26) and (8.27) imply that
\[
-F^{ij} (\log \eta)_{ij} \leq CK^2 \nu^2 \frac{\sigma_1}{\tau - \tau_0} \left( 1 + \frac{1}{\tau - \tau_0} \right) \quad (8.28)
\]
where \( C \) only depends on bounds on \( \alpha^{-1}, |D\alpha|_T, |DT|_T \), and \( F \). Finally, estimates (8.25) and (8.28) give the result. \( \square \)

Using the lower bound \( \varepsilon \frac{\sigma_1}{2} n \lambda_n^2 \geq \varepsilon \frac{\sigma_1}{2} n \alpha^{-2} K^2 \nu^2 \) given by Lemma 8.6, we finally obtain
\[
\varepsilon \frac{1}{2} \sigma_1 \frac{K^2 \nu^2}{4(\tau - \tau_0)^2} - C_1 K^2 \nu^2 \alpha^2 \sigma_1 ((\tau - \tau_0) + 1) \leq (C_1 \nu + C_2 \sigma_1 \nu^2 + nC_3 \nu \sigma_2) \alpha^2 (\tau - \tau_0)^2,
\]
which is impossible if \( K \) is sufficiently large under control.

8.2. The construction of the adapted time function. We suppose that \( \Psi \) and \( \varpi \) are the barriers constructed Section 3. Let \( R_0 > 0 \), and consider \( \Phi : \mathbb{R}^n \to \mathbb{R} \) such that \( \Phi < \mathcal{U} \) on \( B_{R_0} \), and \( \Psi \geq \varpi \) near infinity, given by Lemma 3.5. We define
\[
\tau(x_1, \ldots, x_n, x_{n+1}) := x_{n+1} - \Phi(x_1, \ldots, x_n).
\]
The function \( \tau \) is a time function since \( \psi \) is spacelike. We fix \( \tau_0 > 0 \) such that \( \Phi + 2\tau_0 \leq \mathcal{U} \) on \( B_{R_0} \). We also fix \( R_1 \) such that \( \psi(x) \geq \varpi(x) \) if \( |x| \geq R_1 \), and, for \( R \geq R_1 + 1 \), we consider \( X^R : \Sigma_0^R \times [0, +\infty) \to \mathbb{R}^{n,1} \) solution of (7.5). We set \( K \) for the compact set \( \{ \psi(x_1, \ldots, x_n) \leq x_{n+1} \leq \Phi(x_1, \ldots, x_n) \} \). Note that \( \hat{f} \equiv 1 \) on \( K \), and that the normal velocity \( F \) is bounded from above and
from below during the evolution, uniformly in \( R \). For all \( t \in [0, +\infty) \), the set \( \Sigma^R_{t, \tau \geq \tau_0} \) defined by (8.1) is compact, and is such that \( \tau = \tau_0 \) on its boundary. Moreover, since the set \( D_{\tau_0} \) defined by (8.2) belongs to the compact set \( K \), the time function \( \tau \) satisfies all the requirements of the previous section. Thus Theorem 8.1 applies and gives the gradient estimate on the set

\[
\{(x,t) \in \Sigma^R_0 \times [0, +\infty) : \tau(X^R(x,t)) \geq 2\tau_0\}.
\]

We deduce the required local gradient estimate (7.11) since \( \text{graph} B_{R_0} u \subset \{ X \in \mathbb{R}^{n+1} : \tau(X) \geq 2\tau_0 \} \).

9. THE LOCAL \( C^2 \) ESTIMATE

We suppose that \( \underline{\nu}, \overline{\nu} \) are the barriers constructed Section 3.

**Theorem 9.1.** Let \( R_0 \geq 0 \), and let \( R_0' \geq R_0 \) and \( \Phi : B_{R_0'} \rightarrow \mathbb{R} \) be such that

\[
\Phi > \overline{\nu} \quad \text{on} \quad B_{R_0'}, \quad \Phi \leq \underline{\nu} \quad \text{on} \quad \partial B_{R_0'}.
\]

given by Lemma 3.7. We fix \( \delta_0 > 0 \) such that \( \Phi \geq \overline{\nu} + \delta_0 \) on \( B_{R_0} \), and we set, for all \( X = (x_1, \ldots, x_{n+1}) \in B_{R_0'} \times \mathbb{R} \subset \mathbb{R}^{n+1} \),

\[
\eta(X) := \Phi(x_1, \ldots, x_n) - x_{n+1}.
\]

Then, there exists \( R_1 \geq R_0' \) such that, for all \( R \geq R_1 \), the solution \( X^R \) of (7.5) satisfies the following local \( C^2 \) estimate:

\[
\sup_{\{(x,t) : \eta(X^R(x,t)) \geq \delta_0\}} |II^R_{(x,t)}| \leq C.
\]

Here \( |II^R_{(x,t)}| \) stands for the norm of the second fundamental form of \( \Sigma_t^R \) at \( X^R(x,t) \), and \( C \) is a constant controlled by the local \( C^1 \) estimate on the set where \( \eta \geq 0 \).

**Proof.** We fix \( R_1 \geq R_0' \) such that for all \( R \geq R_1 \) the local \( C^1 \) estimate holds on the set where \( \underline{\nu} \leq x_{n+1} \leq \Phi \). For \( T_1 > 0 \) we define

\[
\Gamma_{T_1} = \{(x,t) \in \Sigma^R_0 \times [0, T_1] : \eta(X^R(x,t)) \geq 0\}.
\]

Following J.Urbas [19], we suppose that the function

\[
\tilde{W}(x, t, \xi) := \eta^\beta(X^R(x,t)) h_{ij} \xi^i \xi^j, \quad (9.1)
\]

defined for all \( (x, t) \in \Gamma_{T_1} \) and all unit \( \xi \in T_{X^R(x,t)} \Sigma_t \), reaches its maximum at a point \( (x_0, t_0, \xi_0) \), with \( t_0 > 0 \). Arguing as in Paragraph 6.3.1, we also get here inequality (6.15) at \( (x_0, t_0) \). Moreover, using the evolution equation (5.5) of \( u = x_{n+1} \), we obtain

\[
\frac{d}{dt} \log \eta - F^{ij} (\log \eta)_{ij} = \frac{\nu \tilde{f}}{\eta} + \frac{1}{\eta} (\Phi - F^{ij} \Phi_{ij}) + F^{ij} \frac{\eta \eta_{ij}}{\eta^2}. \quad (9.2)
\]
The following estimates hold: $F^{ij}\Phi_{ij} \geq c_0 \sum_i F^i_i - c$, $\dot{\Phi} \leq c$, and $\nu \dot{f} \leq c$ where $c_0$ and $c$ are controlled constants; for the first estimate we refer to [19] p.313, and for the second estimate to (6.16). Thus

$$-\beta \left( \frac{d}{dt} \log \eta - F^{ij} (\log \eta)_{ij} \right) \geq \frac{\beta}{\eta} \left( c_0 \sum_i F^i_i - c \right) - \beta F^{ij} \eta^i \eta_j.$$  (9.3)

Inequalities (6.15) and (9.3) give inequality (2.8) obtained by J.Urbas in [19] p. 312 (where the first term in (2.8) is moreover estimated by (2.12) [19] p. 313). We then follow the arguments in [19], and obtain an upper bound of $W(x_0, t_0, \xi_0)$, if $\beta$ is chosen sufficiently large (under control). The bound is independent of $T_f$ and $R$. This gives an upper bound of the second fundamental form during the evolution, on the set where $\eta \geq \delta_0$. \qed

This estimate implies the local $C^2$ estimate (7.11) since

$$\text{graph} \bar{B}_{R_0} u_R \subset \{ X \in \mathbb{R}^{n+1} : \eta(X) \geq \delta_0 \},$$

and thus completes the proof of Theorem 1.4.

**Appendix A**

**Lemma A.1.** Let $u$ be a spacelike and convex function defined on $\mathbb{R}^n$, and let $x' \in \mathbb{R}^{n-2}$. Setting

$$\tilde{u}(x_1, x_2) := u(x_1, x_2, x' \cdot),$$

we have, for all $(x_1, x_2) \in \mathbb{R}^2$,

$$H_1[\tilde{u}](x_1, x_2) \leq H_1[u](x_1, x_2, x' \cdot).$$

**Proof.** The second fundamental form of the graph of $\tilde{u}$ in the chart $(x_1, x_2)$ is

$$\tilde{II} = \frac{1}{\sqrt{1 - |D\tilde{u}|^2}} D^2 \tilde{u}.$$  

Since $|Du| \geq |D\tilde{u}|$ and $D^2 \tilde{u} = D^2u|_{\mathbb{R}^{2\times n}}$, we obtain

$$\frac{1}{\sqrt{1 - |D\tilde{u}|^2}} D^2 \tilde{u} \leq \frac{1}{\sqrt{1 - |Du|^2}} D^2u|_{\mathbb{R}^{2\times n}}.$$  

The right-hand side term is the second fundamental form $II$ of the graph of $u$, in the chart $(x_1, \ldots, x_n)$, restricted to the plane $x_3 = \cdots = x_n = 0$. Let us fix $(e_1, e_2, \ldots, e_n)$ a basis in the chart $(x_1, \ldots, x_n)$ which induces an orthonormal basis $(\hat{e}_1, \ldots, \hat{e}_n)$ of the tangent space of graph $u$ at $(x_1, x_2, x' \cdot)$. We suppose moreover that $e_1, e_2$ belong to the plane $x_3 = \cdots = x_n = 0$. Thus $\hat{e}_1, \hat{e}_2$ are tangent to graph $\tilde{u}$, and we get:

$$H_1[\tilde{u}](x_1, x_2) = \tilde{II}(\hat{e}_1) + \tilde{II}(\hat{e}_2) \leq II(\hat{e}_1) + II(\hat{e}_2) \leq \sum_{i=1}^n II(\hat{e}_i) \leq H_1[u](x_1, x_2, x' \cdot),$$

where the second inequality follows from the convexity of $u$. \qed
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