Abstract

By generalizing Bogolyubov’s reduced description method, we suggest a formalism to derive kinetic equations for many-body dissipative systems in external stochastic field. As a starting point, we use a stochastic Liouville equation obtained from Hamilton’s equations taking dissipation and stochastic perturbations into account. The Liouville equation is then averaged over realizations of the stochastic field by an extension of the Furutsu-Novikov formula to the case of a non-Gaussian field. As the result, a generalization of the classical Bogolyubov-Born-Green-Kirkwood-Yvon (BBGKY) hierarchy is derived. In order to get a kinetic equation for the one-particle distribution function, we use a regular cut off procedure of the BBGKY hierarchy by assuming weak interaction between the particles and weak intensity of the field. Within this approximation we get the corresponding Fokker-Planck equation for the system in a non-Gaussian stochastic field. Two particular cases by assuming either Gaussian statistics of external perturbation or homogeneity of the system are discussed.
The BBGKY Hierarchy and Fokker-Planck Equation for Many-Body Dissipative Randomly Driven Systems

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1 Introduction

The research topic of the present paper has quite a long history, dating back to a rigorous justification of the Boltzmann kinetic equation from the microscopic point of view. A consistent
dynamical foundation of statistical mechanics for classical (non-quantum) many-body systems has been given by Bogolyubov [1]. His method of a reduced description allows to construct a systematic procedure for obtaining closed dissipative kinetic equations based on the Bogolyubov-Born-Green-Kirkwood-Yvon (BBGKY) chain of reversible equations for many-particle distribution functions. Bogolyubov’s functional hypothesis reflects the idea of a relaxation time hierarchy. It allows one to truncate the BBGKY chain and get closed kinetic equations in two important cases, namely either low particle density, or weak particle interaction. In the former case we arrive at the Boltzmann equation, whereas the weak interaction approximation leads to the Fokker-Planck equation [2]. The BBGKY theory, together with Choh-Uhlenbeck’s generalization of the Boltzmann equation [3], constitute a ”cradle” of modern kinetic theory [4], having a great impact on the further development of important concepts in the theory of condensed matter and electromagnetic processes, see, e.g., [4, 5, 6]. For quantum systems a reduced description method was developed by Peletminskii and co-authors [2].

In the present paper we obtain a generalization of the classical BBGKY hierarchy by taking into account dissipative dynamics and non-Gaussian random driving. Apart from a fundamental scientific interest in developing and extending systematic methods of kinetic theory, our studies are motivated by the following physical reasons: Firstly, a wide variety of complex systems, such as colloidal suspensions, polymers, micelles etc., can be viewed as interacting Brownian particles that are in contact with a heat bath [7, 8, 9]. There are several approaches to the statistical description of Brownian dynamics where interaction between particles is taken into account, see, e.g., [10, 11, 12, 13, 14], and references therein. In the case of a Gaussian external field, the system investigated in our paper can be considered as a “prototype” of that of interacting Brownian particles. Secondly, there is a large and important class of many-body dissipative systems, such as granular media [15, 16] and their counterparts, traffic flows [17, 18]. All these systems exhibit a reach phenomenology and striking differences to the gases studied in the framework of the ”standard” BBGKY theory [19]. The kinetic approaches are under investigation, see [20, 21, 22, 23, 24, 25, 26, 27, 28, 29] for granular gas dynamics. We believe that alternative approaches and/or techniques are still on the agenda because of the strong complexity of these systems. Thirdly, a large class of biological systems which are referred to as active matter is studied theoretically and experimentally with the use of methods of statistical physics [30, 31, 32]. In contrast to passive Brownian particles, active self-propelled objects have the ability to take up energy from the environment, to store it

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in an internal depot, and to convert internal energy into kinetic energy. The kinetic description of active Brownian dynamics requires taking into account both dissipative dynamics with active friction responsible for self-propulsion, and external active fluctuations that are correlated with the current direction of motion of an active particle [31]. The approach of the present paper may pave the way for constructing a consistent microscopic kinetic theory of active gaseous-like systems. We refer the reader to Refs.[33, 34, 35, 36, 37] for recent developments and disputes in the field of the kinetic theory of active motion.

We would like to emphasize that the aim of the present paper is not to solve a particular problem of the systems mentioned above, but rather to outline a fundamental microscopic approach based on the generalization of a well-known systematic method of classical kinetic theory. However, in order to illustrate the simplest possible truncation of the BBGKY hierarchy, we consider a model of weakly interacting particles with the simplest form of dissipation. For such a model we obtain a Fokker-Planck equation and then present two particular cases by assuming either Gaussian statistics of external perturbations or homogeneity of the system under study.

The paper is organized as follows. In Section 2 starting from Hamilton’s equations we introduce a stochastic Liouville equation for many-body dissipative systems in an external stochastic field. In Section 3 we describe an averaging procedure over realizations of the stochastic field. In Section 4 we get the analogue of the BBGKY chain. In Section 5 a closed Fokker-Planck kinetic equation is obtained by assuming weak interaction between the particles. In Section 6 we deal with the simplest particular cases of the derived kinetic equation. Our results are summarized and discussed in Section 7.

2 Basic equations

We consider a system consisting of \( N \) identical particles of mass \( m \), each of which is characterized by a spatial coordinate \( x_\alpha \), \( 1 \leq \alpha \leq N \), measured from the center of mass, and momentum \( p_\alpha \), \( 1 \leq \alpha \leq N \). We assume that the system is placed in an external stochastic field with potential \( U^\omega (x, t) \) (here the index \( \omega \) reflects the fact that \( U^\omega (x, t) \) belongs to the set of random realizations of the external field). Following [39], we assume that the interaction between the particles consists of two parts, namely, “reversible” part described by the Hamiltonian \( H \), and “irreversible” one,
described by the dissipation function $R$. The Hamiltonian of the system reads:

$$H = H_0 + V = \sum_{1 \leq \alpha \leq N} \left( \frac{\mathbf{p}_\alpha^2}{2m} + U^\omega (\mathbf{x}_\alpha, t) \right) + \sum_{1 \leq \alpha < \beta \leq N} V_{\alpha,\beta},$$  \hspace{1cm} (1)$$

where $V_{\alpha,\beta}$ is the pair interaction potential,

$$V_{\alpha,\beta} \equiv V(\mathbf{x}_{\alpha\beta}), \mathbf{x}_{\alpha\beta} \equiv \mathbf{x}_\alpha - \mathbf{x}_\beta.$$  \hspace{1cm} (2)$$

In general case, we also assume that the dissipation function $R$ is determined only by the difference of coordinates $\mathbf{x}_{\alpha\beta}$ and momenta $\mathbf{p}_{\alpha\beta}$ of the particles. In view of this, the system in the absence of external field exhibits the Galilean invariance. Thus, the dissipation function can be represented as follows:

$$R = \sum_{1 \leq \alpha < \beta \leq N} R_{\alpha,\beta}, \quad R_{\alpha,\beta} \equiv R(\mathbf{x}_{\alpha\beta}, \mathbf{p}_{\alpha\beta}), \quad \mathbf{p}_{\alpha\beta} \equiv \mathbf{p}_\alpha - \mathbf{p}_\beta.$$  \hspace{1cm} (3)$$

Since the function $R$ is a scalar, it should depend only on $\mathbf{x}_{\alpha\beta}^2$, $\mathbf{p}_{\alpha\beta}^2$, $\mathbf{x}_{\alpha\beta} \mathbf{p}_{\alpha\beta}$ and their combinations.

In accordance with (1) - (3) the (generalized) Hamilton’s equations can be written as:

$$\dot{\mathbf{p}}_\alpha = -\frac{\partial H}{\partial \mathbf{x}_\alpha} - \frac{\partial R}{\partial \mathbf{p}_\alpha}, \quad \dot{\mathbf{x}}_\alpha = \frac{\partial H}{\partial \mathbf{p}_\alpha}. \hspace{1cm} (4)$$

Thus, the force $\mathbf{F}_{\alpha,\beta}$, acting on the particle $\alpha$ from the particle $\beta$, is given by

$$\mathbf{F}_{\alpha,\beta} \equiv \mathbf{F}(\mathbf{x}_{\alpha\beta}, \mathbf{p}_{\alpha\beta}) = -\frac{\partial V_{\alpha,\beta}}{\partial \mathbf{x}_\alpha} - \frac{\partial R_{\alpha,\beta}}{\partial \mathbf{p}_\alpha}. \hspace{1cm} (5)$$

Moreover, as it follows from (1), the $\alpha$-th particle is under the influence of an external stochastic force $Y^\omega_{\alpha}$,

$$Y^\omega_{\alpha} \equiv Y^\omega(\mathbf{x}_\alpha, t) = -\frac{\partial}{\partial \mathbf{x}_\alpha} U^\omega(\mathbf{x}_\alpha, t). \hspace{1cm} (6)$$

The time derivative of the total energy of the system in accordance with (1) and (4) is given by

$$\frac{dH}{dt} = \frac{\partial'}{\partial t} \sum_{1 \leq \alpha \leq N} U^\omega(\mathbf{x}_\alpha, t) - \sum_{1 \leq \alpha \leq N} \frac{\mathbf{p}_\alpha}{m} \frac{\partial R}{\partial \mathbf{p}_\alpha}. \hspace{1cm} (7)$$

where the symbol “prime” in the partial time derivative means differentiation with respect to the explicit dependence of the potential $U^\omega(\mathbf{x}_\alpha, t)$ on time.

In this Section our aim is to obtain the Liouville equation. To this end, we first represent (1) in the equivalent form

$$\dot{\mathbf{x}}_\alpha(t) = h^\omega_{\alpha}(x_1(t), ..., x_N(t)), \ 1 \leq \alpha \leq N,$$  \hspace{1cm} (8)
where we introduce the notation
\[ x_a(t) \equiv (x_a(t), p_a(t)). \quad (9) \]

Alternatively, (8) can be written as
\[
\begin{align*}
\dot{x}_\alpha(t) &= h_x^{\omega}(x(t)), \\
\dot{p}_\alpha(t) &= h_p^{\omega}(x(t)), \quad (10)
\end{align*}
\]
where
\[
\begin{align*}
h_x^{\omega}(x(t)) &= \frac{\partial H}{\partial p_\alpha}, \\
h_p^{\omega}(x(t)) &= -\frac{\partial H}{\partial x_\alpha} - \frac{\partial R}{\partial p_\alpha}. \quad (11)
\end{align*}
\]
The coordinate and momentum of the \( \alpha \)-th particle at time \( t \) depend on coordinates and momenta \( x_0 \equiv (x_1(0),...,x_N(0)) \) of all the particles at initial time \( t = 0 \),
\[ x_\alpha^\omega(t) = X_\alpha^\omega(t,x_0) \equiv (X_\alpha^\omega(t,x_0), P_\omega^\alpha(t,x_0)), \quad (12) \]
where the functions \( X_\alpha^\omega(t,x_0), P_\omega^\alpha(t,x_0) \) satisfy the Hamilton’s equations (4) (or (8)-(11)). Let us assume that at \( t = 0 \) the initial conditions \( x_0 \equiv (x_1(0),...,x_N(0)) \) are distributed with the probability density \( D(x_1(0),...,x_N(0);0) \). Then
\[
\int dx_1(0)...x_N(0) D(x_1(0),...,x_N(0);0) \equiv \int dx_0 D(x_0;0) = 1. \quad (13)
\]
Then, at time \( t \) the \( N \)-particle probability density \( D^\omega(x_1,...,x_N;t) \equiv D^\omega(x;t), x \equiv (x_1,...,x_N), \) is determined by the expression
\[ D^\omega(x_1,...,x_N;t) = \int dx_0 D(x_0;0) \prod_{1 \leq \alpha \leq N} \delta(x_\alpha - X_\alpha^\omega(t,x_0)). \quad (14) \]

In [38] the stochastic Liouville equation is obtained for many-body system of non-interacting particles in external stochastic field. In [39], a similar procedure is used to obtain the Liouville equation for dissipative many-body system in the absence of a stochastic field. By directly combining these two procedures we arrive at the stochastic Liouville equation for many-body dissipative system driven by external stochastic field,
\[ \frac{\partial D^\omega}{\partial t} + \sum_{1 \leq \alpha \leq N} \frac{\partial}{\partial x_\alpha}(D^\omega h_\alpha^{\omega}) = 0, \quad (15) \]
where the function $h_\omega(x(t))$ is given by the expressions (10), (11). The Liouville equation can be written in the equivalent form as

$$\frac{\partial D^\omega}{\partial t} - \{H, D^\omega\} = \sum_{1 \leq \alpha \leq N} \frac{\partial}{\partial p_\alpha} \left(D^\omega \frac{\partial R}{\partial p_\alpha}\right),$$

(16)

where $\{A, B\}$ represent the $N$-particle Poisson brackets

$$\{A, B\} \equiv \sum_{1 \leq \alpha \leq N} \left(\frac{\partial A}{\partial x_\alpha} \frac{\partial B}{\partial p_\alpha} - \frac{\partial A}{\partial p_\alpha} \frac{\partial B}{\partial x_\alpha}\right).$$

(17)

For our purpose the following form of the Liouville equation appears to be more convenient:

$$\frac{\partial D^\omega}{\partial t} + \sum_{1 \leq \alpha \leq N} \frac{p_\alpha}{m} \frac{\partial D^\omega}{\partial x_\alpha} + \sum_{1 \leq \alpha < \beta \leq N} \frac{\partial}{\partial p_\alpha} D^\omega F_{\alpha,\beta} + \sum_{1 \leq \alpha \leq N} \frac{\partial}{\partial p_\alpha} D^\omega Y_\alpha^\omega = 0,$$

(18)

where the quantities $F_{\alpha,\beta}$, $Y_\alpha^\omega$ are defined by (5), (6). Equation (18) is a typical example of the evolution equation with multiplicative noise. This circumstance poses the task of averaging over random realizations of the field $Y_\alpha^\omega$.

### 3 Averaging the stochastic Liouville equation

We introduce the $N$-particle PDF $D(x_1, ..., x_N; t)$ as a statistical average of the $N$-particle PDF $D^\omega(x_1, ..., x_N; t)$ (see (14)) over the stochastic external field $Y^\omega(x, t)$ with the probability density $W[Y^\omega]$,

$$D(x_1, ..., x_N; t) \equiv \langle D^\omega(x_1, ..., x_N; t) \rangle_\omega,$$

$$\langle ... \rangle_\omega \equiv \int D^\omega(x, t) W[Y^\omega] ...$$

(19)

After averaging of (18) we get

$$\frac{\partial D}{\partial t} + \sum_{1 \leq \alpha \leq N} \frac{p_\alpha}{m} \frac{\partial D}{\partial x_\alpha} + \sum_{1 \leq \alpha < \beta \leq N} \frac{\partial}{\partial p_\alpha} D F_{\alpha,\beta} + \sum_{1 \leq \alpha \leq N} \frac{\partial}{\partial p_\alpha} \langle D^\omega Y_\alpha^\omega \rangle_\omega = 0.$$

(20)

To get a closed equation for the $N$-particle PDF we need to express the quantity $\langle D^\omega Y_\alpha^\omega \rangle_\omega$ through $D(x_1, ..., x_N; t)$. To this end, we use the Furutsu-Novikov formula [40, 41], which was generalized in [42] to the case of a non-Gaussian stochastic field. Below we follow the procedure of that paper and present some details of calculations for the readers’ convenience. At first we introduce the moments
Along with the moments (21) we introduce the correlation functions

\[ Y_{i_{1}...i_{n}}(x_{1}, ..., x_{n}; t_{1}, ..., t_{n}) \]

of the stochastic field \( Y^{\omega}(x, t) \),

\[ Y_{i_{1}...i_{n}}(x_{1}, ..., x_{n}; t_{1}, ..., t_{n}) = \langle Y_{i_{1}}^{\omega}(x_{1}, t_{1}) ... Y_{i_{n}}^{\omega}(x_{n}, t_{n}) \rangle_{\omega} \]

\[ Y_{i}^{\omega}(x, t) = \langle Y^{\omega}(x, t) \rangle_{i}, \quad i = (1, 2, 3). \] (21)

The generating functional \( P(v; Y_{a}) \) of these moments is determined by

\[ P(v; Y_{a}) \equiv \left\{ \exp \left( \int_{-\infty}^{\infty} dx \int_{-\infty}^{\infty} dt v_{i}(x, t) Y_{i}^{\omega}(x, t) \right) \right\}_{\omega}, \] (22)

where \( v_{i}(x, t) \) is a functional argument, and summation is implied over the repeated indices. By \( Y_{a} \) in the left-hand side of (22) we denote the entire set of the moments \( Y_{i_{1}...i_{n}}(x_{1}, ..., x_{n}; t_{1}, ..., t_{n}) \). Along with the moments (21) we introduce the correlation functions \( y_{i_{1}...i_{n}}(x_{1}, ..., x_{n}; t_{1}, ..., t_{n}) \),

\[ y_{i_{1}}(x; t) \equiv y_{i_{1}}(x; t), \]

\[ y_{i_{1}i_{2}}(x_{1}, x_{2}; t_{1}, t_{2}) = Y_{i_{1}}(x_{1}; t_{1}) Y_{i_{2}}(x_{2}; t_{2}) + y_{i_{1}i_{2}}(x_{1}, x_{2}; t_{1}, t_{2}), \]

\[ y_{i_{1}i_{2}i_{3}}(x_{1}, x_{2}, x_{3}; t_{1}, t_{2}, t_{3}) = Y_{i_{1}}(x_{1}; t_{1}) Y_{i_{2}}(x_{2}; t_{2}) Y_{i_{3}}(x_{3}; t_{3}) + Y_{i_{1}}(x_{1}; t_{1}) y_{i_{2}i_{3}}(x_{2}, x_{3}; t_{2}, t_{3}) + Y_{i_{2}}(x_{2}; t_{2}) y_{i_{1}i_{3}}(x_{1}, x_{3}; t_{1}, t_{3}) \]

\[ + Y_{i_{3}}(x_{3}; t_{3}) y_{i_{1}i_{2}}(x_{1}, x_{2}; t_{1}, t_{2}) + y_{i_{1}i_{2}i_{3}}(x_{1}, x_{2}, x_{3}; t_{1}, t_{2}, t_{3}). \] (23)

The generating functional of the correlation functions reads

\[ \mathcal{P}(v; y_{a}) \equiv \sum_{n=2}^{\infty} \frac{1}{n!} \int dx_{1} \int_{-\infty}^{\infty} dt_{1} ... \int dx_{n} \int_{-\infty}^{\infty} dt_{n} v_{i_{1}}(x_{1}, t_{1}) ... v_{i_{n}}(x_{n}, t_{n}) \]

\[ \times y_{i_{1}...i_{n}}(x_{1}, ..., x_{n}; t_{1}, ..., t_{n}), \] (24)

and it is related to the generating functional \( P(v; Y_{a}) \) by the following formula:

\[ P(v; Y_{a}) = \exp \left( \int dx \int_{-\infty}^{\infty} dt v_{i}(x, t) Y_{i}(x, t) \right) \exp \{ \mathcal{P}(v; y_{a}) \}, \] (25)

where

\[ Y(x, t) \equiv \langle Y^{\omega}(x, t) \rangle_{\omega}, \] (26)

and by \( y_{a} \) we denote the entire set of the correlation functions \( y_{i_{1}...i_{n}}(x_{1}, ..., x_{n}; t_{1}, ..., t_{n}) \). It was shown in [12] that the result of the averaging of an arbitrary functional \( A[Y^{\omega}(x, t)] \) over an external stochastic field with distribution \( W[Y^{\omega}(x, t)] \) can be presented as

\[ \langle A[Y^{\omega}(x, t)] \rangle_{\omega} = \exp \left\{ \mathcal{P} \left( \frac{\delta}{\delta Y}; y_{a} \right) \right\} A[Y], \] (27)
where \( \mathcal{P} \left( \frac{\delta}{\delta Y}; y_a \right) \) is the generating functional \((24)\), in which the functional argument \( v_i(x, t) \) is replaced by the operation of the functional differentiation over \( Y_i(x, t) \) (see \((21), (26)\)),

\[
v_i(x, t) \rightarrow \frac{\delta}{\delta Y_i(x, t)}.
\]

As the consequence of \((27)\),

\[
\langle Y^\omega_i(x, t) A[Y^\omega(x, t)] \rangle^\omega = \left( Y^\omega_i(x, t) + \frac{\delta \mathcal{P}(v; y_a)}{\delta v_i(x, t)} \right)_{v_i \rightarrow \delta/\delta Y_i} \times \exp \left\{ \mathcal{P} \left( \frac{\delta}{\delta Y}; y_a \right) \right\} A[Y].
\]

The same formula can be rewritten as

\[
\langle Y^\omega_i(x, t) A[Y^\omega(x, t)] \rangle^\omega = Y^\omega_i(x, t) \langle A[Y^\omega(x, t)] \rangle^\omega + \left( \frac{\delta \mathcal{P}(v; y_a)}{\delta v_i(x, t)} \right)_{v_i \rightarrow \delta/\delta Y_i} \langle A[Y^\omega(x, t)] \rangle^\omega.
\]

Equation \((29)\) is, indeed, the generalization of the Furutsu-Novikov formula to an arbitrary distribution of the external stochastic field (of course, it is assumed that this distribution has moments of any order). Note, that for the Gaussian distribution of the external stochastic field \((29)\) takes the form

\[
\langle Y^\omega_i(x, t) A[Y^\omega(x, t)] \rangle^\omega = Y^\omega_i(x, t) \langle A[Y^\omega(x, t)] \rangle^\omega + \int d\mathbf{x}' \int_{-\infty}^{\infty} dt' y_{ij}(\mathbf{x}, \mathbf{x}', t - t') \times \langle \frac{\delta A[Y^\omega]}{\delta Y_j(x', t')} \rangle^\omega,
\]

where \( y_{ij}(\mathbf{x}, \mathbf{x}', t - t') \) is the pair correlation function of the external Gaussian noise,

\[
y_{ij}(\mathbf{x}, \mathbf{x}', t - t') = \langle Y^\omega_i(x, t) Y^\omega_j(x', t') \rangle^\omega - \langle Y^\omega_i(x, t) \rangle^\omega \langle Y^\omega_j(x', t') \rangle^\omega.
\]

When \( Y^\omega_i(x, t) \equiv 0 \) expression \((30)\) coincides with that obtained in \([40, 41]\).

We now use the generalized Furutsu-Novikov formula to calculate the last term on the left-hand side of equation \((20)\). Indeed, there is a functional dependence of the distribution function \( D^\omega(x_1, ..., x_N; t) \) on the external stochastic field \( Y^\omega_i(x, t) \),

\[
D^\omega \equiv D^\omega[Y^\omega],
\]
as is evident from (14) and (18). According to (29), the mean value $\langle D^\omega Y^\omega \rangle_\omega$ can be represented as

$$\langle D^\omega [Y^\omega]Y_i^\omega (x, t) \rangle_\omega = Y_i^\omega (x, t) D + \left. \frac{\delta P (v ; y_o)}{\delta v_i (x, t)} \right|_{v_i \to \delta Y_i} D^\omega [Y^\omega] \right> \omega . \quad (31)$$

Note that, in accordance with (24), the correlator

$$\langle y_{i_1} ... y_{i_n} (x, x_1, ... x_n ; t, t_1, ... t_n) \rangle \equiv \frac{\delta P (v ; y_o)}{\delta v_i (x, t)} \right|_{v_i \to \delta Y_i} D^\omega [Y^\omega] \right> \omega . \quad (32)$$

therefore, the correlator $\left. \frac{\delta P (v ; y_o)}{\delta v_i (x, t)} \right|_{v_i \to \delta Y_i} D^\omega [Y^\omega] \right> \omega$ in (31) reads as

$$\left. \frac{\delta P (v ; y_o)}{\delta v_i (x, t)} \right|_{v_i \to \delta Y_i} D^\omega [Y^\omega] \right> \omega = \sum_{n=1}^{\infty} \frac{1}{n!} \int dx_1 \int_{-\infty}^{\infty} dt_1 \ldots \int dx_n \int_{-\infty}^{\infty} dt_n \sum_{i_1, \ldots, i_n} \delta^n D^\omega [Y^\omega]$$

$$\times \langle y_{i_1} ... y_{i_n} (x, x_1, ... x_n ; t, t_1, ... t_n) \rangle \right> \omega . \quad (33)$$

To go further, we consider the first term of the sum in the right-hand side of (33),

$$I_i \equiv \int dx' \int_{-\infty}^{\infty} dt' y_{ij} (x, x'; t, t') \left. \frac{\delta D^\omega [Y^\omega]}{\delta Y_j^\omega (x', t')} \right|_\omega . \quad (34)$$

We assume that the pair correlation function $y_{ij} (x, x'; t, t')$ has a sharp peak at $t \approx t'$ and decays rapidly within the interval $|t - t'| \leq \tau_0$, where $\tau_0$ is a typical correlation time of the stochastic field. Then it is enough to calculate the functional derivative $\frac{\delta D^\omega [Y^\omega]}{\delta Y_j^\omega (x', t')}$ only at $t \approx t'$. The variational derivative $\frac{\delta D^\omega [Y^\omega]}{\delta Y_j^\omega (x', t')}$ at $t \approx t'$ undergoes a jump,

$$\frac{\delta D^\omega [Y^\omega]}{\delta Y_j^\omega (x', t')} \neq 0, \quad t' \leq t, \quad \frac{\delta D^\omega [Y^\omega]}{\delta Y_j^\omega (x', t')} = 0, \quad t' > t. \quad (35)$$

Indeed, according to (18), the function $D^\omega (t)$ cannot depend on the field $Y_j^\omega (x', t')$ taken at later time instant $t'$. Therefore, the integration over $t'$ in (34) is performed in the range from $-\infty$ to $t$, not from $-\infty$ to $+\infty$.

Differentiating (18) with respect to $Y_j^\omega (x', t')$ and noting that, according to (35), the derivative $\frac{\partial}{\partial t} \frac{\delta D^\omega [Y^\omega]}{\delta Y_j^\omega (x', t')}$ must contain a $\delta$-function singularity in time (while the functional derivative
\[ \frac{\delta D^\omega[Y^\omega]}{\delta Y_j^\omega(x', t')} \] does not), it is easy to obtain the following expression (see also [42]):

\[
\frac{\delta D^\omega[Y^\omega]}{\delta Y_j^\omega(x', t')} = -\vartheta (t - t') \sum_{1 \leq \alpha \leq N} \delta (x' - x_\alpha) \frac{\partial D^\omega[Y^\omega]}{\partial p_{\alpha j}}. \tag{36}
\]

This formula allows us to present the quantity \(I_i\), (34), as follows:

\[
I_i = \int_{-\infty}^t dt' \sum_{1 \leq \alpha \leq N} y_{ij}(x, x_\alpha; t, t') \frac{\partial D}{\partial p_{\alpha j}}. \tag{37}
\]

For the Gaussian processes, (37) is sufficient to evaluate expression (31), and hence to derive in a final form the averaged Liouville equation for dissipative system of many particles in an external stochastic field,

\[
\frac{\partial D}{\partial t} + \sum_{1 \leq \alpha \leq N} \frac{p_{\alpha}}{m} \frac{\partial D}{\partial x_\alpha} + \sum_{1 \leq \alpha < \beta \leq N} \frac{\partial F_{\alpha, \beta}}{\partial p_{\alpha}} + \sum_{1 \leq \alpha \leq N} Y(x_\alpha, t) \frac{\partial D}{\partial p_{\alpha}} - \int_{-\infty}^t dt' \sum_{1 \leq \alpha \leq N} y_{ij}(x_\alpha, x_\beta; t, t') \frac{\partial^2 D}{\partial p_{\alpha i} \partial p_{\beta j}} = 0. \tag{38}
\]

In fact, the method used here also allows for obtaining the average Liouville equation in case of non-Gaussian distribution of the external stochastic field (remind, that we assume existence of the moments of all orders). To do this, according to (33), one should calculate the functional derivative of \(n\)-th order. This quantity can be obtained with the help of (36). Indeed, by differentiating (36) over \(Y^\omega(x'', t'')\) we get

\[
\frac{\delta^2 D^\omega[Y^\omega]}{\delta Y_j^\omega(x', t') \delta Y_l^\omega(x'', t'')} = -\vartheta (t - t') \sum_{1 \leq \alpha \leq N} \delta (x' - x_\alpha) \frac{\partial D^\omega[Y^\omega]}{\partial p_{\alpha j} \delta Y_l^\omega(x'', t'')}.
\]

Next, we use (36) again,

\[
\frac{\delta^2 D^\omega[Y^\omega]}{\delta Y_j^\omega(x', t') \delta Y_l^\omega(x'', t'')} = \vartheta (t - t') \vartheta (t - t'') \times \sum_{1 \leq \alpha \leq N} \sum_{1 \leq \beta \leq N} \delta (x' - x_\alpha) \delta (x'' - x_\beta) \frac{\partial^2 D^\omega[Y^\omega]}{\partial p_{\alpha j} \partial p_{\beta l}}.
\]

Repeating this procedure, it is easy to come to the following expression:

\[
\frac{\delta^n D^\omega[Y^\omega]}{\delta Y_{i_1}^\omega(x_1, t_1) ... \delta Y_{i_n}^\omega(x_n, t_n)} = (-1)^n \vartheta (t - t_1) ... \vartheta (t - t_n) \left( \sum_{1 \leq \alpha_1 \leq N} \delta (x_1 - x_{\alpha_1}) \frac{\partial}{\partial p_{\alpha_1 i_1}} \right) ...
\]

\[
\times \left( \sum_{1 \leq \alpha_n \leq N} \delta (x_n - x_{\alpha_n}) \frac{\partial}{\partial p_{\alpha_n i_n}} \right) D^\omega[Y^\omega]. \tag{39}
\]
After substituting (39) into (33) and using (31), the evolution equation (20) can be written as:
\[
\frac{\partial D}{\partial t} + \sum_{1 \leq \alpha \leq N} \frac{p_\alpha}{m} \frac{\partial D}{\partial x_\alpha} + \sum_{1 \leq \alpha < \beta \leq N} \frac{\partial D F_{\alpha,\beta}}{\partial p_\alpha} + \sum_{1 \leq \alpha \leq N} Y(x_\alpha, t) \frac{\partial D}{\partial p_\alpha}
\]
\[+ \sum_{n=2}^\infty \left\{ \frac{(-1)^{n-1}}{(n-1)!} \int_{-\infty}^t dt_2 \ldots \int_{-\infty}^t dt_n \sum_{1 \leq \alpha_1 \leq N} \ldots \sum_{1 \leq \alpha_n \leq N} y_{i_1 \ldots i_n}(x_{\alpha_1}, \ldots, x_{\alpha_n}; t, t_2, \ldots, t_n) \right\} \frac{\partial^n D}{\partial p_{\alpha_{i_1}} \ldots \partial p_{\alpha_{i_n}}} = 0. \quad (40)
\]
Equation (40) is the generalized Liouville equation for dissipative systems of many particles, averaged over the external non-Gaussian stochastic field.

In case of stationary stochastic field the Liouville equation (40) can be further simplified. Indeed, the correlation functions
\[y_{i_1 \ldots i_n}(x_{\alpha_1}, \ldots, x_{\alpha_n}; t, t_2, \ldots, t_n) \equiv y_{i_1 \ldots i_n}(x_{\alpha_1}, \ldots, x_{\alpha_n}; |t_2 - t|, \ldots, |t_n - t|). \quad (41)\]
To simplify further calculations we also assume that the average value of the external stochastic field is zero,
\[Y(x, t) \equiv \langle Y^\omega(x, t) \rangle_\omega \equiv 0. \quad (42)\]
Then the Liouville equation (40) reads
\[
\frac{\partial D}{\partial t} + \sum_{1 \leq \alpha \leq N} \frac{p_\alpha}{m} \frac{\partial D}{\partial x_\alpha} + \sum_{1 \leq \alpha < \beta \leq N} \frac{\partial D F_{\alpha,\beta}}{\partial p_\alpha} + \sum_{n=2}^\infty \frac{(-1)^{n-1}}{2^{n-1} (n-1)!} \sum_{1 \leq \alpha_1 \leq N} \ldots \sum_{1 \leq \alpha_n \leq N} \bar{y}_{i_1 \ldots i_n}(x_{\alpha_1}, \ldots, x_{\alpha_n}) \frac{\partial^n D}{\partial p_{\alpha_{i_1}} \ldots \partial p_{\alpha_{i_n}}} = 0, \quad (43)\]
where the correlation functions
\[\bar{y}_{i_1 \ldots i_n}(x_{\alpha_1}, \ldots, x_{\alpha_n}) \equiv \int_{-\infty}^\infty dt_2 \ldots \int_{-\infty}^\infty dt_n y_{i_1 \ldots i_n}(x_{\alpha_1}, \ldots, x_{\alpha_n}; |t_2 - t|, \ldots, |t_n - t|). \quad (44)\]
are introduced.

4 Analogue of the BBGKY hierarchy for dissipative system in external stochastic field

Along with the probability density $D$ one may introduce the probability density of finding one or more particles in given elements of the phase space, regardless of where the other particles are.
These probabilities can be obtained by integrating the function $D$ over all variables except those related to the considered particles,

$$f_S(x_1, \ldots, x_S; t) = V^S \int \cdots \int d_x N D(x_1, \ldots, x_N; t),$$

where $D(x_1, \ldots, x_N; t)$ satisfies (40) (or (43)) and $V$ is the system’s volume. Following the procedure of [1, 2], one gets the following equation for $S$- particle distribution function $f_S(x_1, \ldots, x_S; t)$:

$$\frac{\partial f_S}{\partial t} = - \sum_{1 \leq \alpha \leq S} \frac{p_\alpha}{m} \frac{\partial f_S}{\partial x_\alpha} - \sum_{1 \leq \alpha < \beta \leq S} \frac{\partial f_S F_{\alpha,\beta}}{\partial p_\alpha} - \sum_{1 \leq \alpha \leq N} Y(x_\alpha, t) \frac{\partial f_S}{\partial p_\alpha} \ldots$$

$$\times \left[ \sum_{1 \leq \alpha_1 \leq S} \ldots \sum_{1 \leq \alpha_n \leq S} \bar{y}_{i_1\ldots i_n} (x_{\alpha_1}, \ldots, x_{\alpha_n}; t, t_2, ..., t_n) \frac{\partial^n f_S}{\partial p_{\alpha_1 i_1} \ldots \partial p_{\alpha_n i_n}} \right]$$

$$- \frac{1}{v} \sum_{1 \leq \alpha \leq S} \frac{\partial}{\partial p_\alpha} \int d_x S+1 f_{S+1} F_{\alpha,S+1}, \quad v \equiv \frac{V}{N},$$

if the function $D(x_1, \ldots, x_N; t)$ satisfies (40), and

$$\frac{\partial f_S}{\partial t} = - \sum_{1 \leq \alpha \leq S} \frac{p_\alpha}{m} \frac{\partial f_S}{\partial x_\alpha} - \sum_{1 \leq \alpha < \beta \leq S} \frac{\partial f_S F_{\alpha,\beta}}{\partial p_\alpha}$$

$$- \sum_{n=2}^{\infty} \frac{(-1)^{n-1}}{(n-1)!} \sum_{1 \leq \alpha_1 \leq S} \ldots \sum_{1 \leq \alpha_n \leq S} \bar{y}_{i_1\ldots i_n} (x_{\alpha_1}, \ldots, x_{\alpha_n}) \frac{\partial^n f_S}{\partial p_{\alpha_1 i_1} \ldots \partial p_{\alpha_n i_n}}$$

$$- \frac{1}{v} \sum_{1 \leq \alpha \leq S} \frac{\partial}{\partial p_\alpha} \int d_x S+1 f_{S+1} F_{\alpha,S+1}, \quad v \equiv \frac{V}{N},$$

if the function $D(x_1, \ldots, x_N; t)$ satisfies (43). The force $F_{\alpha,\beta}$ in (46) and (47) is still defined by (5). As it is seen, the equation for the $S$- particle distribution function contains an $S+1$- particle distribution function, that is, in fact, we have obtained endless chain of equations (46) and (47), which are generalizations of the famous BBGKY hierarchy for the dissipative systems of many particles under the influence of an external stochastic field. The chains (46) and (47) are equivalent to the Liouville equations (40) or (43), respectively, and thus provide the same level of complexity in the system’s description.

In what follows we restrict ourselves to the case of a stationary stochastic field that is, we consider the chain (43) and omit the bar in the notation of the correlation functions defined by (44). The generalization to the non-stationary case given by (46) is straightforward.
A significant simplification in the system’s description occurs in two cases: when interaction between the particles is weak, or the particle density is low, and the interaction is arbitrary, but such that it does not lead to the formation of bound states [2]. This simplification is the result of the different behaviour of many- and singe-particle distribution functions during the evolution in time. In fact, at the initial stage of evolution, when time $t$ is of the order of the typical time $\tau_0$ of the correlation decay (which in turn, is of duration of a single collision), many-particle distribution functions $f_S(x_1, ..., x_S; t)$ change rapidly, in contrast to the single-particle distribution function $f_1(x, t)$ that experiences significant changes over time periods longer than the typical relaxation time $\tau_r$ necessary to reach an equilibrium state, $\tau_r \gg \tau_0$. Such a difference in the evolutionary behaviour of a single- and many-particle distribution functions formed the basis of the Bogolyubov’s idea about hierarchy of relaxation times [1].

According to the idea of a relaxation times hierarchy, the evolution of many-particle system can be divided into several stages. The simplest scenario is as follows. At $\tau_0 \ll t \ll \tau_r$, there is a kinetic stage of evolution of the system when the system behaviour can be described by a single-particle distribution function, only. Further simplification in the description of many-particle system occurs at $t \gg \tau_r$ (hydrodynamic stage of the evolution of the system), when the behaviour of the system can be described by hydrodynamic parameters, e.g., the particle density, average speed and temperature of the medium. In this paper, the reduced description method will be used for the derivation of the kinetic equations describing evolution of dissipative systems in the external stochastic field. Mathematically, the reduced description method introduces time-dependence of many-particle distribution functions $f_S(x_1, ..., x_S; t)$ as a functional time-dependence via the reduced description parameters at the corresponding stage of evolution. In particular, at the kinetic stage the many-particle distribution functions depend on time only through the single-particle distribution function $f_1(x', t)$,

$$f_S(x_1, ..., x_S; t) = f_S(x_1, ..., x_S; f_1(x', t)).$$  \hspace{1cm} (48)

Note, that the $x'$ - dependence on the right hand side of (48) implies functional dependence on the PDF $f_1$. In addition to the functional hypothesis (48), the principle of spatial correlation weakening is put into basis of the reduced description method. It can be summarized as follows. Let $S$ particles be divided into two subgroups containing $S'$ and $S''$ particles respectively $S = S' + S''$. If the distance $R$ between these subgroups of particles increases, $R \to \infty$, then due to the weakening of correlations
between the particles the $S$-particle distribution function is decomposed into the product of the distribution functions related to each subgroup of particles:

$$f_S(x_1, ..., x_S; t) \rightarrow_{R \rightarrow \infty} f_{S'}(x'_1, ..., x'_S; t) f_{S''}(x''_1, ..., x''_S; t),$$  \hspace{1cm} (49)

where the sign “prime” is used to denote the coordinates and momenta of the particles from the subgroup $S'$, and “two-primes” to denote the coordinates and momenta of the particles from the subgroup $S''$. It should be noted, however, that the principle of spatial correlations weakening (49) refers to many-particles distribution functions where the thermodynamic limit transition $V \rightarrow \infty$, $(N/V) = \text{const}$ was performed.

According to (48), the time derivative $\partial f_S / \partial t$ in (47) with $S \neq 1$ should be understood as follows:

$$\frac{\partial}{\partial t} f_S(x_1, ..., x_S; f_1(x, t)) = \int dx' \frac{\delta f_S(x_1, ..., x_S; f_1(x, t))}{\delta f_1(x', t)} \frac{\partial f_1(x', t)}{\partial t},$$  \hspace{1cm} (50)

where $\delta f_S(f_1(x, t)) / \delta f_1(x', t)$ is the functional derivative. According to (47), the single-particle distribution function $f_1(x', t)$ satisfies the following equation:

$$\frac{\partial f_1}{\partial t} + \frac{p_1}{m} \frac{\partial f_1}{\partial x_1} + \sum_{n=2}^{\infty} \frac{(-1)^{n-1}}{2^{n-1} (n-1)!} y_{i_1 ... i_n}(x_1, ..., x_1) \frac{\partial^n f_1}{\partial p_{i_1} ... \partial p_{i_n}} = \frac{1}{v} L(x_1; f_1), \hspace{1cm} v \equiv \frac{V}{N},$$  \hspace{1cm} (51)

where $L(x_1; f_1)$ is the (generalized) collision integral defined by the formula

$$L(x_1; f_1) \equiv -\frac{\partial}{\partial p_1} \int dx_2 f_2(x_1, x_2; f_1) F_{1.2}.$$  \hspace{1cm} (52)

In order to get a closed equation for a single-particle probability density one should find the collision integral (52) as a functional of a single-particle distribution function, thus, one should truncate the infinite set of equations (47). Such a truncation can be performed by using either low density or weak interaction approximation. In the next Section we demonstrate the cut off procedure and develop a perturbation theory in case of a weak interaction between the particles. We thus do not use the low density expansion and respectively, do not discuss the issues of divergency and non-analytical behavior of transport coefficients [4].
5 Kinetic equations for dissipative system of weakly interacting particles

We demonstrate such cut off procedure and develop a perturbation theory in case of weak interaction between particles embedded in a weak external stochastic field. Using (50), the set of equations can be written as

\[- \int dx \frac{\partial f_1(x, t)}{\partial t} \frac{p}{m} \frac{\partial f_1(x, t)}{\partial x} + \sum_{1 \leq \alpha \leq S} \frac{p_\alpha}{m} \frac{\partial f_1(f_i)}{\partial x_\alpha} = \frac{1}{v} K_S(f_i),\]

where

\[K_S(f_i) \equiv -v \sum_{1 \leq \alpha < \beta \leq S} \frac{\partial f_S}{\partial p_\alpha}, \quad \sum_{1 \leq \alpha \leq S} \frac{p_\alpha}{m} \frac{\partial}{\partial x_\alpha} \int dx f_{S+1} F_{\alpha, S+1},\]

\[- \int dx \frac{\delta f_S(f_i)}{\delta f_1(x, t)} \left\{ L(x; f_1) - v \sum_{n=2}^{\infty} \frac{(-1)^{n-1}}{2^{n-1} (n-1)!} \sum_{1 \leq \alpha_1 \leq S} \ldots \sum_{1 \leq \alpha_n \leq S} y_{i_1 \ldots i_n} (x_{\alpha_1}, \ldots, x_{\alpha_n}) \frac{\partial^n f_S}{\partial p_{\alpha_1} \ldots \partial p_{\alpha_n}} \right\} - \sum_{n=2}^{\infty} \frac{(-1)^{n-1}}{2^{n-1} (n-1)!} \times \sum_{1 \leq \alpha_1 \leq S} \ldots \sum_{1 \leq \alpha_n \leq S} y_{i_1 \ldots i_n} (x_{\alpha_1}, \ldots, x_{\alpha_n}) \frac{\partial^n f_S}{\partial p_{\alpha_1} \ldots \partial p_{\alpha_n}}.\]

The chain (53) should be supplied with “initial conditions”. For those, we use the fact that many-particle distribution functions satisfy the principle of spatial correlation weakening, (49). To this end, following [1, 2], we introduce the auxiliary parameter $\tau$, having the dimension of time, but not necessarily representing the physical time. We next consider the many-particle distribution function $f_S \left( x_1 - \frac{p_1}{m} \tau, p_1, \ldots, x_S - \frac{p_S}{m} \tau, p_S; f_1 \right)$. According to (49) this function must satisfy the asymptotic relation:

\[f_S \left( x_1 - \frac{p_1}{m} \tau, p_1, \ldots, x_S - \frac{p_S}{m} \tau, p_S; f_1 \right) \longrightarrow \prod_{1 \leq \alpha \leq S} f_1 \left( x_\alpha - \frac{p_\alpha}{m} \tau, p_\alpha \right).\]

If we further define the shift operator $\hat{\Lambda}_S^0$ in coordinate space by a formula

\[i \hat{\Lambda}_S^0 \equiv \sum_{1 \leq \alpha \leq S} \frac{p_\alpha}{m} \frac{\partial}{\partial x_\alpha},\]

than (55) can be rewritten as:

\[e^{i \tau \hat{\Lambda}_S^0} f_S(\tau) \longrightarrow \prod_{1 \leq \alpha \leq S} f_1(x_\alpha),\]

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where \( \exp \left(i \tau \hat{\Lambda}_0^0 \right) \) is a so-called “free evolution operator” and

\[
 f_S (\tau) \equiv f_S \left( x_1, ..., x_S; e^{-i \tau \hat{\Lambda}_0^0} f_1 (x') \right) = f_S \left( x_1, ..., x_S; f_1 \left( x' - \frac{p'}{m} \tau, p' \right) \right).
\]  

(58)

With the use of the operators introduced, expression (53) can be rewritten as:

\[
 \frac{\partial}{\partial \tau} e^{i \tau \hat{\Lambda}_0^0} f_S (\tau) = \frac{1}{v} e^{i \tau \hat{\Lambda}_0^0} K_S (\tau),
\]  

(59)

where

\[
 K_S (\tau) \equiv K_S \left( x_1, ..., x_S; e^{-i \tau \hat{\Lambda}_0^0} f_1 (x') \right) = K_S \left( x_1, ..., x_S; f_1 \left( x' - \frac{p'}{m} \tau, p' \right) \right).
\]  

(60)

Integrating (59) over \( \tau \) between \(-\infty \) and 0 and using the asymptotic conditions (57), we obtain

\[
 f_S (x_1, ..., x_S; f_1 (x')) = \prod_{1 \leq \alpha \leq S} f_1 (x_\alpha) + \frac{1}{v} \int_{-\infty}^0 d\tau e^{i \tau \hat{\Lambda}_0^0} K_S (\tau).
\]  

(61)

Equation (61) demonstrates that the assumption of factorization of many-particle distribution function is valid only if the second term in the right-hand side is negligibly small. On the other hand, Eq. (61) allows us to develop a perturbation theory. Indeed, it follows from Eqs. (54) and (52) that the second term in the right-hand side of Eq. (61) is small if the intensity of the stochastic field and the particle interactions (potential and dissipative ones) are weak enough. Under these assumptions, the value \( K_S (\tau) \), see (54), can be considered as small and, therefore, in the main approximation we have

\[
 f_S (x_1, ..., x_S; f_1 (x')) = \prod_{1 \leq \alpha \leq S} f_1 (x_\alpha),
\]

which implies

\[
 f_2 (x_1, x_2) = f_1 (x_1) f_1 (x_2).
\]  

(62)

Next, substituting (62) into (52) and using (31) and (51), we obtain the following closed kinetic equation,

\[
 \frac{\partial f_1}{\partial t} + \frac{p_1}{m} \frac{\partial f_1}{\partial x_1} + \sum_{n=2}^\infty \frac{(-1)^{n-1}}{n!} y_{1i_1...i_n}(x_1, ..., x_1) \frac{\partial^n f_1}{\partial p_{i_1i_2}...\partial p_{i_1i_n}}
\]

\[
 = \frac{1}{v} \frac{\partial}{\partial p_1} f_1 (x_1) \left( \int dx_2 f_1 (x_2) \frac{\partial V_{12}}{\partial x_1} + \int dx_2 f_1 (x_2) \frac{\partial R_{12}}{\partial p_1} \right),
\]  

(63)
which describes the kinetic stage evolution of many-particle dissipative systems under the influence of an external stochastic field. If we make a simplest assumption that the dissipation function is quadratic in the particles’ momenta, then the function \( R_{1,2} \), following [43], can be chosen as

\[
R_{1,2} = \frac{1}{2} \tilde{\gamma} (x_1 - x_2) (p_1 - p_2)^2 ,
\]

\[
\tilde{\gamma} (x_1 - x_2) > 0.
\] (64)

If there is no dissipation, \( \tilde{\gamma} (x_1 - x_2) = 0 \), (63) is reduced to the Vlasov equation for a system in external stochastic field, with the self-consistent field

\[
U (x_1) = \frac{1}{v} \int dx_2 V (x_1 - x_2) \int dp_2 f_1 (x_2, p_2) .
\] (65)

In general case, equation (63) can be treated as the Fokker-Planck equation for the system of weakly interacting particles influenced by non-Gaussian stochastic field. We dwell on this more in the next Section.

6 Two particular cases of the Fokker-Planck equation

6.1 Gaussian stochastic field

We consider first (63) with the dissipation function given by (64), and assume the Gaussian statistics of the external stochastic field. Thus, the odd correlation functions of the field vanish, and the even ones are expressed via the pair correlation function. We choose it in the form

\[
y_{ij} (x_1, x_2) \equiv \delta_{ij} g (x_1, x_2)
\]

to simplify calculations. Also for simplicity, we assume that the single-particle distribution function is isotropic in the momentum space,

\[
f_1 (x, p, t) \equiv f_1 (x, |p|, t) .
\] (66)

Equation (63) takes then the “traditional” form of the Fokker-Planck equation,

\[
\frac{\partial f_1 (x, t)}{\partial t} + \frac{p}{m} \frac{\partial f_1 (x, t)}{\partial x} - \frac{\partial U (x)}{\partial x} \frac{\partial f_1 (x, t)}{\partial p} = \frac{\partial}{\partial p} \left( \gamma (x, t) p f_1 (x, t) + \frac{1}{2} g (x, x) \frac{\partial f_1 (x, t)}{\partial p} \right) ,
\] (67)

where the self-consistent field \( U (x, t) \) is given by (65), and \( \gamma (x, t) \) is determined by

\[
\gamma (x, t) \equiv \frac{1}{v} \int dx' \tilde{\gamma} (x - x') \int dp' f_1 (x', t) , \quad \gamma (x) > 0.
\] (68)
6.2 Homogeneous system embedded in non-Gaussian stochastic field

Let us now consider spatially homogeneous system. In this case, the correlation functions \( y_{i_1...i_n}(x_{\alpha_1}, ..., x_{\alpha_n}) \), see (44) and (54), depend only on the coordinate difference \( x_{\alpha_i} - x_{\alpha_j} \). Then, the correlation functions \( y_{i_1...i_n}(x_1, ..., x_1) \) entering (63) do not depend on the spatial coordinate,

\[
y_{i_1...i_n}(x_1, ..., x_1) \equiv y_{i_1...i_n}.
\]  

(69)

Thus, in the spatially homogeneous case (63) takes the form (assuming that (64) is also valid)

\[
\frac{\partial f_1(p, t)}{\partial t} + \sum_{n=2}^{\infty} \frac{(-1)^{n-1}}{2^{n-1} (n-1)!} y_{i_1...i_n} \frac{\partial^n f_1(p, t)}{\partial p_{i_1}...\partial p_n} = \tilde{\gamma} \frac{\partial}{\partial p_1} f_1(p_1) \int dp_2 f_1(p_2)(p_1 - p_2),
\]

(70)

\[
\tilde{\gamma} \equiv \frac{1}{v} \int d\mathbf{x}' \tilde{\gamma}(\mathbf{x} - \mathbf{x}').
\]

Note that the system in the momentum space may not be isotropic, in contrast to (66). We now consider the mean kinetic energy \( \bar{\varepsilon}(t) \) of the system,

\[
\bar{\varepsilon}(t) \equiv \int dp f_1(p, t) \frac{p^2}{2m}.
\]

(71)

The evolution equation for this quantity is an immediate consequence of the kinetic equation (70):

\[
\frac{\partial \bar{\varepsilon}(t)}{\partial t} = \frac{3}{2} y_{jj} \rho - \frac{\tilde{\gamma}}{2mv} \int dp_1 \int dp_2 f_1(p_2, t) f_1(p_1, t)(p_1 - p_2)^2,
\]

(72)

where \( \rho \) is the particle density,

\[
\rho \equiv \int dp f_1(p, t),
\]

(73)

and the following equalities hold,

\[
\frac{\partial}{\partial t} \int dp f_1(p, t) = 0, \quad \frac{\partial}{\partial t} \int dp f_1(p, t) p = 0,
\]

(74)

which imply conservation of the density and momentum.

From (72) one may conclude that the investigated system can be heated or cooled, depending on the sign of the right hand side of (72). If we assume that initially the average momentum of the particles equals zero, then according to (74), it is always equal to zero, and (72) takes the form

\[
\frac{\partial \bar{\varepsilon}(t)}{\partial t} = -2\gamma \bar{\varepsilon}(t) + \frac{3}{2} y_{jj} \rho, \quad \gamma \equiv \rho \tilde{\gamma};
\]

(75)
where we take into account that \( \rho \) is constant, and therefore, the coefficient \( \gamma \) does not depend on time. Taking \( \bar{\varepsilon}(t = 0) = \bar{\varepsilon}_0 \), we get the solution of (75),

\[
\bar{\varepsilon}(t) = \frac{3}{4} \frac{y_{jj}\rho}{m\gamma} + \left( \bar{\varepsilon}_0 - \frac{3}{4} \frac{y_{jj}\rho}{m\gamma} \right) \exp(-2\gamma t),
\]

(76)

From this equation one can see that the mean kinetic energy of the system decreases during the evolution (the system cools down) if \( \bar{\varepsilon}_0 > \frac{3}{4} \frac{y_{jj}\rho}{m\gamma} \), while the system is heated, if \( \bar{\varepsilon}_0 < \frac{3}{4} \frac{y_{jj}\rho}{m\gamma} \). If \( \bar{\varepsilon}_0 = \frac{3}{4} \frac{y_{jj}\rho}{m\gamma} \), the mean kinetic energy does not change (we note that the homogeneous cooling state of a granular flow in the low-density limit was investigated in \[44, 45, 46\]). As it is seen from (76), the applied stochastic force can reverse the sign of the effect, leading to the heating of dissipative system. If the Maxwell distribution is established during the evolution of the gaseous dissipative system, the expression for the equilibrium mean kinetic energy \( \bar{\varepsilon}(\infty) = \frac{3}{4} \frac{y_{jj}\rho}{m\gamma} \), that follows from (76), coincides with the well-known formula \( \bar{\varepsilon}(\infty) = \frac{3}{2} \rho T \), where \( T \) is the temperature of the medium. That means that the pair correlation function of the external stochastic field \( y_{jj} \) satisfies the relation \( y_{jj} = 2m\gamma T \), known in the theory of classical Brownian motion.

We note that for the non-interacting Brownian particles the concepts of equilibrium, Maxwell distribution and the temperature of a heat bath have a well-known physical meaning. For the dissipative systems, as far as the authors know, to define a notion of temperature is a non-trivial issue. A relevant discussion can be found in \[47, 48, 49\].

We also note that according to (72) and (76), only pair correlation function of external field is responsible for pumping energy into the system. Therefore, (72) and (75) also hold in case of the Gaussian external field, see (67). Obviously, this is because the kinetic energy of a single particle depends on the square of the momentum, \( \varepsilon_p = p^2/2m \), see (70) and (71). The higher order correlation functions are involved in the evolution equations for higher order moments of the single-particle distribution function.

In this Section we considered only the simplest example of the mean energy evolution. Indeed, (70), (72), (75) and (76) were obtained for a special form (64) of the dissipative function \( R_{1,2} \), and with additional assumption of homogeneity, see (69). In a more general case, as follows from (63) and the definition (71), the mean energy evolution can be more complex than predicted by (75) or (72).
7 Summary

In this paper, we contributed to developing the kinetic theory of many-particle dissipative systems in an external stochastic field. We suggested a procedure to obtain an infinite BBGKY hierarchy for many-particle distribution functions by using the Furutsu-Novikov formula generalized to the case of a non-Gaussian stochastic field, provided it has moments of any order. Further, we extended the reduced description method and developed a technique to derive a kinetic equation in the case of a weak interaction between the particles and a low intensity of the external stochastic field. In the case of a Gaussian external field the kinetic equation becomes a Fokker-Planck equation in its “standard” form, with the friction coefficient expressed through the one-particle distribution function. As another simple particular case, we considered the mean energy evolution in a homogeneous system demonstrating competition between the processes of cooling and heating.

We now briefly outline the direct extensions of the perturbation theory developed. First, it allows one to reduce the assumptions of weak interaction between the particles and weak intensity of the external field by calculating higher order corrections to the kinetic equation. Second, a similar approach can be used to construct the kinetic theory in the case of a low particle density, with no assumption of a weak particle interaction (as long as this interaction does not lead to the formation of bound states). Along these lines, the Boltzmann equation for dissipative randomly driven system arises (along with the problem of the divergence of higher order density corrections; however it does not rule out the significance of the Boltzmann equation). Also, an interesting possibility within the framework of the reduced description method is to take into account long-lived fluctuations which are of importance for dissipative systems. In fact, the reduced description method is applicable to systems with long lasting memory effects, however, it requires modifications as mentioned in Ref.[50], where the equations of fluctuating hydrodynamics have been derived, together with reproducing the results for long time tails. We believe that this theory can straightforwardly be extended to dissipative systems. Similar procedures generalizing Bogolyubov’s theory have been used in Refs.[51] and [52].

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