The Kadomtsev-Petviashvili II Equation on the Half-Plane

D. Mantzavinos & A. S. Fokas

Department of Applied Mathematics and Theoretical Physics, University of Cambridge, Cambridge CB3 0WA, UK.

October 6, 2010

Abstract

The KPII equation is an integrable nonlinear PDE in 2+1 dimensions (two spatial and one temporal), which arises in several physical circumstances, including fluid mechanics where it describes waves in shallow water. It provides a multidimensional generalisation of the renowned KdV equation. In this work, we employ a novel approach recently introduced by one of the authors in connection with the Davey-Stewartson equation [1], in order to analyse the initial-boundary value problem for the KPII equation formulated on the half-plane. The analysis makes crucial use of the so-called d-bar formalism, as well as of the so-called global relation. A novel feature of boundary as opposed to initial-value problems in 2+1 is that the d-bar formalism now involves a function in the complex plane which is discontinuous across the real axis.

1 Introduction

The Kadomtsev-Petviashvili (KP) equation

\[ q_t + 6qq_x + q_{xxx} + 3\sigma\partial_x^{-1}q_{yy} = 0, \quad \sigma = \pm 1, \]  

(1.1)

with the operator \( \partial_x^{-1} \) defined by

\[ \partial_x^{-1} f(x) = \int_{-\infty}^{x} f(\xi) \, d\xi, \]

is one of the most notable integrable nonlinear equations in 2+1 dimensions (i.e. evolution equations in two spatial dimensions). It is the natural generalisation of the celebrated Korteweg-de Vries (KdV) equation from one to two spatial dimensions and, as such, it appears in various physical problems. In particular, it was first derived in the study of waves of long wavelength in shallow water. In this specific application, if the surface tension dominates over the gravitational force, then \( \sigma = -1 \) and equation (1.1) is called KPI [2], whereas if the gravitational force is dominant, then \( \sigma = 1 \) and equation (1.1) is called KPII [3].

The initial-value problem for the KdV equation was solved via the so-called Inverse Scattering transform (IST) in 1967 [4]; KPI and KPII equations were formally solved in [2] and [3] respectively, using a nonlocal Riemann-Hilbert formalism and a d-bar formalism respectively (see also [5], [6], [7], [8]). The solution of initial-boundary value (IBV) problems is considerably more complicated than the solution of pure initial-value problems. A unified transform method for solving linear and integrable nonlinear evolution PDEs in one spatial dimension was introduced in [9].
In particular, interesting results for the linearised version of the KdV and for the KdV itself formulated on the half-line are presented in [10], [11], [12] and [15]. The generalisation of these results from one to two spatial dimensions for linear and for integrable nonlinear equations is presented in [10] and [1] respectively.

Here, we employ the general methodology of [1] in order to analyse the KPII on the half-plane. It has been emphasised by one of the authors that the solution of the linearised version of a given nonlinear PDE via a Lax pair approach provides a useful starting point before analysing the nonlinear PDE itself. Hence, we will first solve the linearised version of the KPII equation on the half-plane,

\[ q_t + q_{xxx} + 3 \partial_x^{-1} q_{yy} = 0, \quad (x, y, t) \in \Omega, \quad (1.2) \]

where \( \Omega := \{-\infty < x < \infty, \quad 0 < y < \infty, \quad t > 0\} \), (1.3)

before analysing the KPII equation,

\[ q_t + 6qq_x + q_{xxx} + 3 \partial_x^{-1} q_{yy} = 0, \quad (x, y, t) \in \Omega. \quad (1.4) \]

Our approach to both problems involves the following steps:

1. **The formulation of the PDE in terms of a Lax pair.** For the spectral variable \( k = k_R + ik_I, \quad k_R, k_I \in \mathbb{R}, \) and for some sectionally analytic function \( \mu = \mu(x, y, t, k_R, k_I) \), the linearised KP equation (1.2) admits the Lax pair:

\[ \mu_y - \mu_{xx} - 2ik\mu_x = q, \quad (1.5a) \]

\[ \mu_t + 4\mu_{xxx} + 12ik\mu_{xx} - 12k^2\mu_x = -3 \left( q_x + 2ikq + \partial_x^{-1} q_y \right). \quad (1.5b) \]

Similarly, the KPII equation (1.4) possesses the Lax pair:

\[ \mu_y - \mu_{xx} - 2ik\mu_x = q\mu, \quad (1.6a) \]

\[ \mu_t + 4\mu_{xxx} + 12ik\mu_{xx} - 12k^2\mu_x = F\mu, \quad (1.6b) \]

where the operator \( F \) is defined by

\[ F(x, y, t, k) = -6q (\partial_x + ik) - 3 \left( q_x + \partial_x^{-1} q_y \right). \quad (1.7) \]

2. **The direct problem.** By applying a Fourier transform in \( x \), it is possible to analyse the two equations defining the Lax pair simultaneously in order to obtain an expression for \( \mu \) which is bounded for all \( k \in \mathbb{C} \). It turns out that \( \mu \) has different representations in different parts of the complex \( k \)-plane, namely

\[ \mu(x, y, t, k_R, k_I) = \begin{cases} 
\mu^+_2(x, y, t, k_R, k_I), & k \in I, \\
\mu^+_1(x, y, t, k_R, k_I), & k \in II, \\
\mu^-_1(x, y, t, k_R, k_I), & k \in III, \\
\mu^-_2(x, y, t, k_R, k_I), & k \in IV,
\end{cases} \quad (1.8) \]

where \( I - IV \) denote the four quadrants of the complex \( k \)-plane.

The above expression for \( \mu^\pm_1,2 \) depends on \( q(x, y, t), q(x, 0, t) \) and \( q_y(x, 0, t) \).
3. **The derivation of the global relation.** This relation is an algebraic equation coupling the so-called spectral functions. For the linearised KP these functions are appropriate transforms of

\[ q_0(x, y) = q(x, y, 0), \quad g(x, t) = q(x, 0, t), \quad h(x, t) = q_y(x, 0, t); \quad (1.9) \]

namely, the global relation couples \( \hat{q}, \hat{q}_0, \tilde{g}_T \) and \( \tilde{h}_T \), where

\[
\begin{align*}
\hat{q}(k_1, k_2, t) &= \int_{-\infty}^{\infty} dx \int_0^\infty dy \, e^{-ik_1 x - ik_2 y} q(x, y, t), \\
\hat{q}_0(k_1, k_2) &= \int_{-\infty}^{\infty} dx \int_0^\infty dy \, e^{-ik_1 x - ik_2 y} q_0(x, y), \\
\tilde{g}_T(k_1, k_2) &= \int_{-\infty}^{\infty} dx \int_0^T d\tau \, e^{-ik_1 x + \omega(k) \tau} g(x, \tau), \\
\tilde{h}_T(k_1, k_2) &= \int_{-\infty}^{\infty} dx \int_0^T d\tau \, e^{-ik_1 x + \omega(k) \tau} h(x, \tau), \quad k_1 \in \mathbb{R}, \quad \text{Im} k_2 \leq 0
\end{align*}
\]

and

\[
\omega(k) := -ik_1^3 + 3i \frac{k_2^2}{k_1}. \quad (1.11)
\]

For the KPII, the spectral functions can also be expressed in terms of \( q_0, g, \) and \( h \) via linear integral equations.

4. **The inverse problem.** By using the fact that the function \( \mu \) defined in step 2 is bounded for all \( k \in \mathbb{C} \), it is possible to obtain an alternative representation for this function using a d-bar formalism (or more precisely the so-called Pompeiu’s formula). In order to achieve this, it is necessary to: (a) compute \( \partial \mu / \partial \bar{k} \), (b) compute the jumps of \( \mu^+_{1,2} - \mu^-_{1,2} \) across the real and imaginary \( k \)-axes; actually the jump across the imaginary \( k \)-axis vanishes. For the linearised KP, \( \partial \mu / \partial \bar{k} \) and \( \mu^+_{1,2} - \mu^-_{1,2} \) can be expressed in terms of \( \hat{q}_0, \tilde{g}_T \) and \( \tilde{h}_T \).

Then, using Pompeiu’s formula, it is possible to express \( \mu \) in terms of \( \hat{q}_0, \tilde{g}_T \) and \( \tilde{h}_T \). In the nonlinear case, the d-bar derivatives and the jumps can be expressed in terms of the spectral functions. In summary, \( \mu \) can be expressed via the spectral functions and hence via \( q_0, g, \) and \( h \). After obtaining \( \mu \) it is straightforward to obtain a formula for \( q \).

**Notations and Assumptions**

- The complex variable \( k \) is defined as

\[
k = k_R + ik_I, \quad k_R, k_I \in \mathbb{R}.
\]

- A bar on top of a complex variable will denote the complex conjugate of this variable; in particular, \( \bar{k} = k_R - ik_I \).

- For the solution of the inverse problem we will make use of the so-called Pompeiu’s formula: if \( f(x, y) \) is a smooth function in some piece-wise smooth domain \( D \subset \mathbb{R}^2 \), then \( f \) is related to its value on the boundary of \( D \) and to its d-bar derivative inside \( D \) via the equation

\[
f(x, y) = \frac{1}{2i\pi} \int_{\partial D} \frac{d\zeta}{\zeta - z} f(\xi, \eta) + \frac{1}{2i\pi} \int_D \frac{d\zeta \wedge d\bar{\zeta}}{\zeta - z} \frac{\partial f}{\partial \bar{\zeta}}(\xi, \eta), \quad \zeta = \xi + i\eta,
\]

where

\[d\zeta \wedge d\bar{\zeta} = -2i d\xi d\eta.
\]
We will denote the initial value by
\[ q(x, y, 0) = q_0(x, y), \]  
and the boundary values \( q(x, 0, t) \) and \( q_y(x, 0, t) \) by
\[ q(x, 0, t) = g(x, t) \]  
and
\[ q_y(x, 0, t) = h(x, t). \]

We will assume that \( q_0 \in S(\mathbb{R} \times \mathbb{R}^+) \), where \( S \) denotes the space of Schwartz functions.

We will seek a solution which decays as \( y \to \infty \) for all fixed \((x, t)\) and which also decays as \(|x| \to \infty\) for all fixed \((y, t)\).

Throughout this paper we will assume that there exists a solution \( q(x, y, t) \) with sufficient smoothness and decay in \( \Omega \), which denotes the closure of the domain \( \Omega \).

A hat “\( \wedge \)” above a function will denote the Fourier transform of this function in the variable \( x \).

The index “\( o \)” on a function will denote evaluation at \( t = 0 \).

Whenever we write \( q \), we mean that \( q \) depends on the physical variables \((x, y, t)\).

Whenever we write \( \mu \), we mean that \( \mu \) depends on the physical variables \((x, y, t)\) and on the spectral variables \( k_R, k_I \in \mathbb{R} \).

2 The linearised KP equation

We consider the linearised KP equation (1.2) with the associated Lax pair (1.5). Differentiating equation (1.5a) with respect to \( t \) and equation (1.5b) with respect to \( y \), we find:
\[ \mu_{yt} - \mu_{xxt} - 2ik\mu_{xt} = q_t \]
and
\[ \mu_{ty} + 4\mu_{xxy} + 12ik\mu_{xyy} - 12k^2\mu_{xy} = -3 \left( q_{xy} + 2ikq_y + \partial_x^{-1}q_{yy} \right). \]

The requirement \( \mu_{ty} = \mu_{yt} \) implies equation (1.2), thus (1.5) is indeed a Lax pair for equation (1.2).

2.1 The direct problem

Proposition 2.1. Assume that there exists a solution \( q(x, y, t) \), \((x, y, t) \in \Omega\), to an initial-boundary value problem for equation (1.2). Then, there exists a solution \( \mu \) of the Lax pair (1.5) which is bounded \( \forall k \in \mathbb{C} \). This solution can be represented in the form
\[ \mu(x, y, t, k_R, k_I) = \begin{cases} 
\mu_1^+(x, y, t, k_R, k_I), & k_R \leq 0, k_I \geq 0, \\
\mu_1^-(x, y, t, k_R, k_I), & k_R \leq 0, k_I \leq 0, \\
\mu_2^-(x, y, t, k_R, k_I), & k_R \geq 0, k_I \leq 0, \\
\mu_2^+(x, y, t, k_R, k_I), & k_R \geq 0, k_I \geq 0, 
\end{cases} \]  
(2.1)
(see figure 2.1), where \( \mu_{1,2}^\pm \) can be expressed in terms of \( \{ q(x, y, t), g(x, t), h(x, t) \} \) by the following formulae:

\[
\begin{align*}
\mu_1^\pm &= \frac{1}{2\pi} \left( \int_{-\infty}^0 dl + \int_{-2kR}^0 dl \right) \int_{-\infty}^\infty d\xi \int_0^y d\eta \, e^{-i(l(\xi - x) + l(l+2k)(\eta - y))} q(\xi, \eta, t) \\
&\quad + \frac{1}{2\pi} \left( \int_{-\infty}^0 dl + \int_{-2kR}^0 dl \right) \int_{-\infty}^\infty d\xi \int_0^y d\eta \, e^{-i(l(\xi - x) - l(l+2k)y - 4ilt^2 + 3k^2)(\tau - t)} Q(\xi, \tau, k, l) \\
&\quad - \frac{1}{2\pi} \int_{-2kR}^0 dl \int_{-\infty}^\infty d\xi \int_y^\infty d\eta \, e^{-i(l(\xi - x) + l(l+2k)(\eta - y))} q(\xi, \eta, t), \tag{2.2}
\end{align*}
\]

and

\[
\begin{align*}
\mu_2^\pm &= \frac{1}{2\pi} \left( \int_{-\infty}^0 dl + \int_{-2kR}^0 dl \right) \int_{-\infty}^\infty d\xi \int_0^y d\eta \, e^{-i(l(\xi - x) + l(l+2k)(\eta - y))} q(\xi, \eta, t) \\
&\quad + \frac{1}{2\pi} \left( \int_{-\infty}^0 dl + \int_{-2kR}^0 dl \right) \int_{-\infty}^\infty d\xi \int_0^y d\eta \, e^{-i(l(\xi - x) - l(l+2k)y - 4ilt^2 + 3k^2)(\tau - t)} Q(\xi, \tau, k, l) \\
&\quad - \frac{1}{2\pi} \int_{-2kR}^0 dl \int_{-\infty}^\infty d\xi \int_y^\infty d\eta \, e^{-i(l(\xi - x) + l(l+2k)(\eta - y))} q(\xi, \eta, t), \tag{2.3}
\end{align*}
\]

where

\[
Q(x, t, k, l) = -3 \left[ i(l + 2k)g(x, t) + \partial_x^{-1} h(x, t) \right], \tag{2.4}
\]

and the functions \( g \) and \( h \) are defined by equations (1.13b) and (1.13d).

Figure 2.1: The function \( \mu \) in the four quadrants of the complex \( k \)-plane.

**Proof** Let \( \hat{\mu} \) denote the Fourier transform of \( \mu \) with respect to \( x \), i.e.

\[
\hat{\mu}(l, y, k_R, k_I) = \int_{-\infty}^\infty dx \, e^{-i\xi x} \mu(x, y, t, k_R, k_I), \quad l \in \mathbb{R}, \quad k \in \mathbb{C}, \tag{2.5a}
\]

with the inverse Fourier transform given by

\[
\mu(x, y, t, k_R, k_I) = \frac{1}{2\pi} \int_{-\infty}^\infty dl \, e^{i\xi x} \hat{\mu}(l, y, t, k_R, k_I), \quad k \in \mathbb{C}. \tag{2.5b}
\]

Then, the Fourier transform of equation (1.5a) gives:

\[
\left( \hat{\mu}(l, y, t, k_R, k_I) e^{i(l+2k)y} \right)_y = \hat{q}(l, y, t) e^{i(l+2k)y},
\]

5
We solve this equation by integrating either from $y = 0$ or $y = -\infty$:

$$\hat{\mu}(l, y, t, k_R, k_I) = \begin{cases} 
\int_0^y d\eta e^{l(l+2k)y} \hat{q}(l, \eta, t) + \hat{\mu}(l, 0, t, k_R, k_I) e^{-l(l+2k)y} \\
- \int_y^\infty d\eta e^{l(l+2k)(y-\eta)} \hat{q}(l, \eta, t).
\end{cases} \quad (2.6)$$

We look for a solution which is bounded \(\forall k \in \mathbb{C}\). In the first expression in equation \(2.6\), \(\eta - y \leq 0\), thus we require that \(\mathrm{Re} \left[ l(l+2k) \right] \geq 0\), i.e.

$$l(l+2k) \geq 0 \iff \begin{cases} 
  l \in (-\infty, 0) \cup [-2k_R, \infty), & k_R \leq 0 \\
  l \in (-\infty, -2k_R] \cup [0, \infty), & k_R \geq 0.
\end{cases}$$

Analogous considerations are valid for the second expression in equation \(2.6\), where \(\eta - y \geq 0\).

Let

$$\mu(x, y, t, k_R, k_I) = \begin{cases} 
\mu_1(x, y, t, k_R, k_I), & k_R \leq 0 \\
\mu_2(x, y, t, k_R, k_I), & k_R \geq 0.
\end{cases} \quad (2.7)$$

Inverting equation \(2.6\) we obtain:

$$\mu_1(x, y, t, k_R, k_I) = \frac{1}{2\pi} \left( \int_{-\infty}^0 dl + \int_{-2k_R}^\infty dl \right) e^{ilx-l(l+2k)y} \int_0^y d\eta e^{l(l+2k)\eta} \hat{q}(l, \eta, t)$$

$$+ \frac{1}{2\pi} \left( \int_{-\infty}^0 dl + \int_{-2k_R}^\infty dl \right) e^{ilx-l(l+2k)y} \hat{\phi}_1(l, t, k_R, k_I)$$

$$- \frac{1}{2\pi} \int_{-2k_R}^0 dl e^{ilx-l(l+2k)y} \int_y^\infty d\eta e^{l(l+2k)\eta} \hat{q}(l, \eta, t), \quad k_R \leq 0 \quad (2.8)$$

and

$$\mu_2(x, y, t, k_R, k_I) = \frac{1}{2\pi} \left( \int_{-2k_R}^{2k_R} dl + \int_0^\infty dl \right) e^{ilx-l(l+2k)y} \int_0^y d\eta e^{l(l+2k)\eta} \hat{q}(l, \eta, t)$$

$$+ \frac{1}{2\pi} \left( \int_{-\infty}^{-2k_R} dl + \int_0^\infty dl \right) e^{ilx-l(l+2k)y} \hat{\phi}_2(l, t, k_R, k_I)$$

$$- \frac{1}{2\pi} \int_{-2k_R}^{0} dl e^{ilx-l(l+2k)y} \int_y^\infty d\eta e^{l(l+2k)\eta} \hat{q}(l, \eta, t), \quad k_R \geq 0, \quad (2.9)$$

where \(\phi_1, \phi_2(x, t, k_R, k_I)\) denote the value of \(\mu_1, \mu_2(x, y, t, k_R, k_I)\) at the boundary \(y = 0\), i.e.

$$\phi_j(x, t, k_R, k_I) := \mu_j(x, 0, t, k_R, k_I), \quad j = 1, 2. \quad (2.10)$$

Equation \(2.8\) evaluated at \(y = 0\) yields

$$\phi_1(x, t, k_R, k_I) = \frac{1}{2\pi} \left( \int_{-\infty}^0 dl + \int_{-2k_R}^{2k_R} dl \right) e^{ilx} \hat{\phi}_1(l, t, k_R, k_I)$$

$$- \frac{1}{2\pi} \int_{-2k_R}^0 dl e^{ilx} \int_0^\infty d\eta e^{l(l+2k)\eta} \hat{q}(l, \eta, t) + \hat{\mu}(x, 0, t, k_R, k_I) e^{-l(l+2k)0}.$$
Using the definition (2.5b) with \( y = 0 \), we find
\[
\frac{1}{2\pi} \int_{-\infty}^{\infty} dl e^{ilx} \hat{\phi}_1(l, t, k_R, k_I) = \frac{1}{2\pi} \left( \int_{-\infty}^{0} dl + \int_{-2k_R}^{\infty} dl \right) e^{ilx} \hat{\phi}_1(l, t, k_R, k_I)
\]
\[= -\frac{1}{2\pi} \int_{0}^{2k_R} d\xi e^{i\xi x} \int_{0}^{\infty} d\eta e^{(l+2k)\eta} \hat{q}(l, \eta, t).\]

Thus, \( \hat{\phi}_1 \) does not satisfy any constraints for \( l \in (-\infty, 0) \cup [-2k_R, \infty) \), whereas it does satisfy the following constraint for \( l \in [0, -2k_R] \):
\[
\hat{\phi}_1(l, t, k_R, k_I) = -\int_{0}^{\infty} d\eta e^{(l+2k)\eta} \hat{q}(l, \eta, t), \quad l \in [0, -2k_R]. \tag{2.11}
\]

The situation is similar for \( \phi_2 \), namely \( \hat{\phi}_2 \) does not satisfy any constraint for \( l \in (-\infty, -2k_R) \cup (0, \infty) \), whereas it does satisfy the following constraint for \( l \in [-2k_R, 0] \):
\[
\hat{\phi}_2(l, t, k_R, k_I) = -\int_{0}^{\infty} d\eta e^{(l+2k)\eta} \hat{q}(l, \eta, t), \quad l \in [-2k_R, 0].
\]

In order to determine \( \hat{\phi}(l, t, k_R, k_I) \), we use the second of the equations defining the Lax pair, evaluated at \( y = 0 \):
\[
\phi_t + 4\phi_{xxx} + 12ik\phi_{xx} - 12k^2\phi_x = F(x, t, k_R, k_I), \tag{2.12}
\]
where
\[
F(x, t, k_R, k_I) : = -3 \left[ g_x + 2ikq + \partial_x^{-1}q_y \right] \bigg|_{y=0}
= -3 \left[ g_x(x, t) + 2ikg(x, t) + \partial_x^{-1}h(x, t) \right]. \tag{2.13}
\]

The Fourier transform in \( x \) of equation (2.12) yields
\[
(\hat{\phi}(l, t, k_R, k_I) e^{-4ilt(l^2+3kl+3k^2)})_t = \hat{F}(l, t, k_R, k_I) e^{-4ilt(l^2+3kl+3k^2)}.\]

Thus, integrating with respect to \( t \) either from \( t = 0 \) or from \( t = T \), we find
\[
\hat{\phi} = \left\{ \begin{array}{ll}
\int_{0}^{t} d\tau e^{-4ilt(l^2+3kl+3k^2)(\tau-t)} \hat{F}(l, \tau, k_R, k_I) + e^{4ilt(l^2+3kl+3k^2)}t \hat{\phi}_0 \\
-\int_{t}^{T} d\tau e^{-4ilt(l^2+3kl+3k^2)(\tau-t)} \hat{F}(l, \tau, k_R, k_I) + e^{-4ilt(l^2+3kl+3k^2)(T-t)} \hat{\phi}_T, & k \in \mathbb{C}.
\end{array} \right.
\]

Moreover, integration by parts of \( \hat{F} \) implies
\[
\hat{\phi} = \left\{ \begin{array}{ll}
\int_{0}^{t} d\tau e^{-4ilt(l^2+3kl+3k^2)(\tau-t)} \hat{Q}(l, \tau, k_R, k_I) + e^{4ilt(l^2+3kl+3k^2)}t \hat{\phi}_0 \\
-\int_{t}^{T} d\tau e^{-4ilt(l^2+3kl+3k^2)(\tau-t)} \hat{Q}(l, \tau, k_R, k_I) + e^{-4ilt(l^2+3kl+3k^2)(T-t)} \hat{\phi}_T, & k \in \mathbb{C}.
\end{array} \right. \tag{2.14}
\]

where \( \hat{Q} \) is the Fourier transform (2.5a) of the function \( Q \) defined by equation (2.4) and \( \hat{\phi}_T \) denotes the evaluation of \( \phi \) at \( t = T \).

We look for a solution \( \hat{\phi} \) which is bounded \( \forall k \in \mathbb{C} \). Nothing that
\[
\text{Re} \left[ -4ilt(l^2 + 3kl + 3k^2)(\tau-t) \right] = 12lk(l + 2k_R)(\tau-t),
\]
it follows that the exponential \( e^{-4ilt(l^2+3kl+3k^2)(\tau-t)} \) is bounded, provided that
\[
lk(l + 2k_R)(\tau-t) \leq 0.
\]

In order to analyse this inequality, we consider the following cases:
• If \( k \in \{ k \in \mathbb{C} : k_R \leq 0, k_I \geq 0 \} \), then \( l \in (-\infty, 0) \cup (-2k_R, \infty) \) implies that \( \tau - t \leq 0 \), whereas \( l \in (0, -2k_R) \) implies that \( \tau - t \geq 0 \). Recalling our earlier analysis for \( \hat{\phi}_1 \), we can choose

\[
\hat{\phi}_1^+(l, 0, k_R, k_I) = 0 \quad \text{for} \quad l \in (-\infty, 0) \cup (-2k_R, \infty)
\]

and then relation (2.11) implies

\[
\hat{\phi}_1^+(l, T, k_R, k_I) = -\int_0^\infty d\eta e^{l(l+2k)^n} \hat{q}(l, \eta, T) \quad \text{for} \quad l \in (0, -2k_R).
\]

Consequently, equations (2.13) yield

\[
\hat{\phi}_1^+ = \begin{cases} 
\int_0^t d\tau e^{-4i(l^2+3kl+3k^2)(\tau-t)} \hat{Q}(l, \tau, k), & l \in (-\infty, 0) \cup (-2k_R, \infty) \\
- \int_t^T d\tau e^{-4i(l^2+3kl+3k^2)(\tau-t)} \hat{Q}(l, \tau, k) \\
-e^{-4i(l^2+3kl+3k^2)(T-t)} \int_0^\infty d\eta e^{l(l+2k)^n} \hat{q}(l, \eta, T), & l \in (0, -2k_R).
\end{cases}
\] (2.15)

• If \( k \in \{ k \in \mathbb{C} : k_R \leq 0, k_I \leq 0 \} \), then \( l \in (-\infty, 0) \cup [-2k_R, \infty) \) implies that \( \tau - t \geq 0 \), whereas \( l \in [0, -2k_R] \) implies that \( \tau - t \leq 0 \). Following steps similar to those used above, we find

\[
\hat{\phi}_1^-(l, 0, k_R, k_I) = -\int_0^\infty d\eta e^{l(l+2k)^n} \hat{q}_0(l, \eta) \quad \text{for} \quad l \in [0, -2k_R]
\]

and

\[
\hat{\phi}_1^-(l, T, k_R, k_I) = 0 \quad \text{for} \quad l \in (-\infty, 0] \cup [-2k_R, \infty).
\]

Then, equations (2.14) imply

\[
\hat{\phi}_1^- = \begin{cases} 
\int_0^T d\tau e^{-4i(l^2+3kl+3k^2)(\tau-t)} \hat{Q}(l, \tau, k, k_I), & l \in (-\infty, 0] \cup [-2k_R, \infty) \\
\int_t^T d\tau e^{-4i(l^2+3kl+3k^2)(\tau-t)} \hat{Q}(l, \tau, k, k_I) \\
-e^{-4i(l^2+3kl+3k^2)t} \int_0^\infty d\eta e^{l(l+2k)^n} \hat{q}_0(l, \eta), & l \in [0, -2k_R].
\end{cases}
\] (2.16)

• Similarly, we can show that for \( k \in \{ k \in \mathbb{C} : k_R \geq 0, k_I \geq 0 \} \),

\[
\hat{\phi}_2^+ = \begin{cases} 
\int_0^t d\tau e^{-4i(l^2+3kl+3k^2)(\tau-t)} \hat{Q}(l, \tau, k, k_I), & l \in (-\infty, -2k_R] \cup [0, \infty) \\
- \int_t^T d\tau e^{-4i(l^2+3kl+3k^2)(\tau-t)} \hat{Q}(l, \tau, k, k_I) \\
-e^{-4i(l^2+3kl+3k^2)(T-t)} \int_0^\infty d\eta e^{l(l+2k)^n} \hat{q}(l, \eta, T), & l \in [-2k_R, 0].
\end{cases}
\] (2.17)
• For \( k \in \{ k \in \mathbb{C} : k_R \geq 0, k_I \leq 0 \} \),

\[
\begin{aligned}
\tilde{\phi}_2^- &= \left\{ \begin{array}{l}
- \int_t^T d\tau e^{-4it(l^2+3k^2l^2)(\tau-t)} \hat{Q}(l, \tau, k_R, k_I), \quad l \in (-\infty, -2k_R] \cup [0, \infty) \\
\int_0^t d\tau e^{-4it(l^2+3k^2l^2)(\tau-t)} \hat{Q}(l, \tau, k_R, k_I) \\
- e^{4it(l^2+3k^2l^2)t} \int_{-\infty}^{\infty} d\eta e^{(l+2k)\eta} \hat{q}(l, \eta, 0), \quad l \in [-2k_R, 0].
\end{array} \right.
\end{aligned}
\]  

(2.18)

Inserting equations (2.15)-(2.18) in equations (2.8) and (2.9), we find equations (2.2) and (2.8) respectively.

2.2 The global relation

**Proposition 2.2.** Define \( \hat{q}(k_1, k_2, t) \), \( \hat{g}_t(k_1, k_2) \) and \( \hat{h}_t(k_1, k_2) \) by

\[
\begin{aligned}
\hat{q}(k_1, k_2, t) &= \int_{-\infty}^{\infty} dx \int_0^{\infty} dy \ e^{-ik_1x - ik_2y} q(x, y, t), \quad (2.19a) \\
\hat{g}_0(k_1, k_2) &= \int_{-\infty}^{\infty} dx \int_0^{\infty} dy \ e^{-ik_1x - ik_2y} g_0(x, y), \quad (2.19b) \\
\hat{g}_t(k_1, k_2) &= \int_{-\infty}^{\infty} dx \int_0^{t} d\tau e^{-ik_1x + \omega(k)\tau} g(x, \tau), \quad (2.19c) \\
\hat{h}_t(k_1, k_2) &= \int_{-\infty}^{\infty} dx \int_0^{t} d\tau e^{-ik_1x + \omega(k)\tau} h(x, \tau), \quad (2.19d)
\end{aligned}
\]

where

\[
\omega(k) := -ik_1^3 + \frac{k^2}{k_1}. \quad (2.20)
\]

The functions defined in (2.19) satisfy the so-called global relation:

\[
e^{\omega(k)t} \hat{q}(k_1, k_2, t) = \hat{q}_0(k_1, k_2, 0) + 3 \left[ \frac{k_2}{k_1} \hat{g}_t(k_1, k_2) - i \frac{k_1}{k_1} \hat{h}_t(k_1, k_2) \right], \quad k_1 \in \mathbb{R}, \quad \text{Im}k_2 \leq 0. \quad (2.21)
\]

**Proof** The linearised KP equation (1.2) can be written in divergence form as:

\[
\left[ -ik_1 e^{-ik_1x - ik_2y + \omega(k)t} q_x \right]_t + 3 \left[ e^{-ik_1x - ik_2y + \omega(k)t} \left( -ik_1 q_y - ik_2 q_x \right) \right]_y
\]

\[
+ \left[ e^{-ik_1x - ik_2y + \omega(k)t} \left( -ik_1 q_{xxx} + ik_1^3 q_x + k_1^2 q_{xx} + 3ik_2 q_y \right) \right]_x = 0. \quad (2.22)
\]

Green’s theorem in the plane implies

\[
\int_{-\infty}^{\infty} dx \int_0^{\infty} dy \left( e^{-ik_1x - ik_2y + \omega(k)t} q \right)_t = \int_{-\infty}^{\infty} dx \int_{-\infty}^{\infty} dy \left( e^{-ik_1x - ik_2y + \omega(k)t} \left( \partial_x^{-1} h + \frac{k_2}{k_1} \right) \right)
\]

\[
= \int_{-\infty}^{\infty} dx \int_{-\infty}^{\infty} dy \left( e^{-ik_1x - ik_2y + \omega(k)t} \left( \frac{k_2}{k_1} g - \frac{i}{k_1} h \right) \right). \quad (2.23)
\]
Integrating equation (2.23), we obtain the identity
\[
\int_{-\infty}^{\infty} d\xi \int_{0}^{\infty} d\eta e^{-ik_1 \xi - ik_2 \eta + \omega(k)t} q = \\
= \int_{-\infty}^{\infty} d\xi \int_{0}^{\infty} d\eta e^{-ik_1 \xi - ik_2 \eta} q_0 + \int_{-\infty}^{\infty} d\xi \int_{0}^{t} d\tau e^{-ik_1 \xi + \omega(k)\tau} 3 \left( \frac{k_2}{k_1} g - \frac{i}{k_1} h \right),
\]
valid for \( k_1 \in \mathbb{R} \) and \( \text{Im} k_2 \leq 0 \), which is equation (2.21). \( \square \)

**Remark 2.1** We also note that if \( t \) is replaced by \( T \geq t \), equation (2.21) becomes
\[
e^{\omega(k)T} \tilde{q}(k_1, k_2, T) = \tilde{q}_0(k_1, k_2) + 3 \left[ \frac{k_2}{k_1} \tilde{g}_T(k_1, k_2) - \frac{i}{k_1} \tilde{h}_T(k_1, k_2) \right], \quad k_1 \in \mathbb{R}, \, \text{Im} k_2 \leq 0,
\]
with \( \tilde{g}_T \) and \( \tilde{h}_T \) defined by equations analogous to (2.19c) and (2.19d).

**Remark 2.2** The global relation can also be obtained for the Lax pair (1.5). In fact, we have that
\[
\left( \hat{\mu} e^{l(l+2k)y-4il(l^2+3kl+3k^2)t} \right)_y = e^{l(l+2k)y-4il(l^2+3kl+3k^2)t} \int_{-\infty}^{\infty} dx e^{-ilx} q
\]
and
\[
\left( e^{l(l+2k)y-4il(l^2+3kl+3k^2)t} \hat{\mu} \right)_t = e^{l(l+2k)y-4il(l^2+3kl+3k^2)t} \times \int_{-\infty}^{\infty} dx e^{-ilx} \left[ -3 \left( q_x + 2ikq + \partial_x^{-1} h \right) \right].
\]

These two equations are compatible iff
\[
\left( e^{l(l+2k)y-4il(l^2+3kl+3k^2)t} \int_{-\infty}^{\infty} dx e^{-ilx} q \right)_t = \\
= -\left( e^{l(l+2k)y-4il(l^2+3kl+3k^2)t} \int_{-\infty}^{\infty} dx e^{-ilx} 3 \left( q_x + 2ikq + \partial_x^{-1} h \right) \right)_y.
\]
Hence, Green’s theorem over a domain \( A \) yields
\[
\int_{\partial A} \left[ e^{l(l+2k)y-4il(l^2+3kl+3k^2)t} \int_{-\infty}^{\infty} dx e^{-ilx} q \right] dy = \\
= \left\{ e^{l(l+2k)y-4il(l^2+3kl+3k^2)t} \int_{-\infty}^{\infty} dx e^{-ilx} 3 \left( q_x + 2ikq + \partial_x^{-1} h \right) \right\} dt.
\]
In particular, for the domain depicted in figure 2.2 we find the identity

**Figure 2.2:** The domain \( A \) for the global relation.

10
\[ \int_{-\infty}^{\infty} d\xi \int_{-\infty}^{0} d\eta e^{-i\xi + i(l+2k)\eta - 4il(l^2+3kl+3k^2)\xi} q = \int_{-\infty}^{\infty} d\xi \int_{0}^{\infty} d\eta e^{-i\xi + i(l+2k)\eta} q_0 \]
\[ + \int_{-\infty}^{\infty} d\xi \int_{0}^{t} d\tau e^{-i\xi - 4il(l^2+3kl+3k^2)\tau} \left[ i(l+2k)g + \partial^{-1}_\xi h \right], \quad l(l+2k_R) \leq 0. \]

The constraint on \( l \) is imposed in order for the exponential \( e^{i(l+2k)\eta} \) to be bounded.

### 2.3 The inverse problem

We will use Pompeiu’s formula in order to reconstruct \( \mu \) via a d-bar problem. Since the functions \( \mu_1^\pm \) and \( \mu_2^\pm \) depend explicitly both on \( k \) and on \( k_R \), we need to compute the jumps of \( \mu \) across the real and the imaginary \( k \)-axes, as well as the \( k \)-bar derivatives of \( \mu \) in each of the four quadrants.

**Proposition 2.3.** Let \( \mu \) be defined by equation (2.1). This function admits the following alternative representation in terms of appropriate transforms of \( q_0(x,y) \), \( g(x,t) \), \( h(x,t) \):

\[ \mu = \frac{1}{2\pi^2} \left( \int_0^\infty d\nu_R \left( \int_{-\infty}^\infty d\nu_I e^{-2i\nu_R x + 4i\nu_R \nu_I y + 8i\nu_R (3\nu_I^2 - \nu_R^2) t} \tilde{q}_0(\nu_R,\nu_I) \right) \right. \]
\[ + \frac{1}{2\pi^2} \int_0^\infty d\nu_R \int_{\partial D^+_1} \frac{d\nu_I}{\nu - k} e^{-2i\nu_R x + 4i\nu_R \nu_I y + 8i\nu_R (3\nu_I^2 - \nu_R^2) t} \tilde{S}_T(\nu_R,\nu_I) \]
\[ - \frac{1}{2\pi^2} \int_{-\infty}^0 d\nu_R \int_{\partial D^-_1} \frac{d\nu_I}{\nu - k} e^{-2i\nu_R x + 4i\nu_R \nu_I y + 8i\nu_R (3\nu_I^2 - \nu_R^2) t} \tilde{S}_T(\nu_R,\nu_I), \quad (2.27) \]

\[ \text{Figure 2.3: The regions } D^\pm_{1,2}. \]

where \( \tilde{q}_0 \) and \( \tilde{S}_T \) are defined by

\[ \tilde{q}_0(\nu_R,\nu_I) = \int_{-\infty}^{\infty} d\xi \int_{0}^{\infty} d\eta e^{2i\nu_R \xi - 4i\nu_R \nu_I \eta} q_0(\xi,\eta), \quad (2.28) \]
\[ \tilde{S}_T(\nu_R,\nu_I) = \int_{-\infty}^{\infty} d\xi \int_{0}^{T} d\tau e^{2i\nu_R \xi - 8i\nu_R (3\nu_I^2 - \nu_R^2) t} \left[ \partial^{-1}_\xi h(\xi,\tau) - 2\nu_I g(\xi,\tau) \right], \quad (2.29) \]
and the contours \( \partial D_1^+ \) and \( \partial D_1^- \) are the boundaries of the second and the third quadrant, with the orientation as shown in figure 2.3.

**Proof** The definitions (2.2) and (2.3) of \( \mu_1^+ \) and \( \mu_2^+ \) yield the following equations:

\[
\mu_1^+ \bigg|_{k R = 0} = \frac{1}{2\pi} \left( \int_{-\infty}^{0} dl + \int_{0}^{\infty} dl \right) \int_{-\infty}^{\infty} d\xi \int_{0}^{y} d\eta e^{-i(\xi-x) + i(l+2kR)(\eta-y)} q(\xi,\eta,t) \\
+ \frac{1}{2\pi} \left( \int_{-\infty}^{0} dl + \int_{0}^{\infty} dl \right) \int_{-\infty}^{\infty} d\xi \left\{ \int_{0}^{T} d\tau e^{-i(\xi-x) - i(l+2kR)y - 4i(l^2 + 3kR^2 - 3kR^2)(\tau-\tau)} Q(\xi,\tau,ik,l) \right\} \\
(2.30)
\]

\[
\mu_2^+ \bigg|_{k R = 0} = \frac{1}{2\pi} \left( \int_{-\infty}^{0} dl + \int_{0}^{\infty} dl \right) \int_{-\infty}^{\infty} d\xi \int_{0}^{y} d\eta e^{-i(\xi-x) + i(l+2kR)(\eta-y)} q(\xi,\eta,t) \\
+ \frac{1}{2\pi} \left( \int_{-\infty}^{0} dl + \int_{0}^{\infty} dl \right) \int_{-\infty}^{\infty} d\xi \left\{ \int_{0}^{T} d\tau e^{-i(\xi-x) - i(l+2kR)y - 4i(l^2 + 3kR^2 - 3kR^2)(\tau-\tau)} Q(\xi,\tau,ik,l) \right\} \\
(2.31)
\]

\[
\mu_1^+ \bigg|_{k l = 0} = \frac{1}{2\pi} \left( \int_{-\infty}^{0} dl + \int_{0}^{\infty} dl \right) \int_{-\infty}^{\infty} d\xi \int_{0}^{y} d\eta e^{-i(\xi-x) + i(l+2kR)(\eta-y)} q(\xi,\eta,t) \\
+ \frac{1}{2\pi} \left( \int_{-\infty}^{0} dl + \int_{0}^{\infty} dl \right) \int_{-\infty}^{\infty} d\xi \left\{ \int_{0}^{T} d\tau e^{-i(\xi-x) - i(l+2kR)y - 4i(l^2 + 3kR^2 + 3kR^2)(\tau-\tau)} Q(\xi,\tau,k,l) \right\} \\
- \frac{1}{2\pi} \int_{-2kR}^{0} dl \int_{-\infty}^{\infty} d\xi \int_{0}^{y} d\eta e^{-i(\xi-x) + i(l+2kR)(\eta-y)} q(\xi,\eta,t), \quad k R \leq 0 \\
(2.32)
\]

and

\[
\mu_2^+ \bigg|_{k l = 0} = \frac{1}{2\pi} \left( \int_{-\infty}^{0} dl + \int_{0}^{\infty} dl \right) \int_{-\infty}^{\infty} d\xi \int_{0}^{y} d\eta e^{-i(\xi-x) + i(l+2kR)(\eta-y)} q(\xi,\eta,t) \\
+ \frac{1}{2\pi} \left( \int_{-\infty}^{0} dl + \int_{0}^{\infty} dl \right) \int_{-\infty}^{\infty} d\xi \left\{ \int_{0}^{T} d\tau e^{-i(\xi-x) - i(l+2kR)y - 4i(l^2 + 3kR^2 + 3kR^2)(\tau-\tau)} Q(\xi,\tau,k,l) \right\} \\
- \frac{1}{2\pi} \int_{-2kR}^{0} dl \int_{-\infty}^{\infty} d\xi \int_{0}^{y} d\eta e^{-i(\xi-x) + i(l+2kR)(\eta-y)} q(\xi,\eta,t), \quad k R \geq 0. \\
(2.33)
\]

Equations (2.30) and (2.31) imply

\[
\left( \mu_1^+ - \mu_2^+ \right) \bigg|_{k R = 0} = 0 \quad \text{and} \quad \left( \mu_1^- - \mu_2^- \right) \bigg|_{k R = 0} = 0,
\]

thus \( \mu \) does not have a discontinuity across the imaginary \( k \)-axis.

On the other hand, equations (2.32) and (2.33) imply

\[
\left( \mu_1^+ - \mu_1^- \right) \bigg|_{k l = 0} = \frac{1}{2\pi} \left( \int_{-\infty}^{0} dl + \int_{-2kR}^{0} dl \right) e^{ilx-l(l+2kR)y} \hat{Q}_T(kR,l)
\]

and

\[
\left( \mu_2^+ - \mu_2^- \right) \bigg|_{k l = 0} = \frac{1}{2\pi} \left( \int_{-\infty}^{0} dl + \int_{0}^{\infty} dl \right) e^{ilx-l(l+2kR)y} \hat{Q}_T(kR,l),
\]

12
where the function $\tilde{Q}_T$ is given by
\[
\tilde{Q}_T(k, l) = \int_{-\infty}^{\infty} d\xi \int_{0}^{T} d\tau \ e^{-i\xi - 4il(t^2 + 3kl + 3k^2)} \tau Q(\xi, \tau, k, l),
\]  
(2.34)
with $Q$ defined by equation (2.4). Hence, $\mu$ is discontinuous across the real $k$-axis.

Pompeiu’s formula for the contour depicted in figure 2.4 yields
\[
\mu = \frac{1}{2\pi} \int_{-\infty}^{\infty} \frac{dv_R}{v_R - k} \left( \mu_1^+ - \mu_1^- \right) \bigg|_{v_1 = 0} + \frac{1}{2\pi} \int_{0}^{\infty} \frac{dv_R}{v_R - k} \left( \mu_2^+ - \mu_2^- \right) \bigg|_{v_1 = 0}
- \frac{1}{\pi} \int_{0}^{\infty} dv_R \int_{0}^{\infty} \frac{dv_1}{v - k} \frac{\partial \mu_1^+}{\partial \nu} - \frac{1}{\pi} \int_{0}^{\infty} dv_R \int_{0}^{\infty} \frac{dv_1}{v - k} \frac{\partial \mu_1^-}{\partial \nu}
- \frac{1}{\pi} \int_{0}^{\infty} dv_R \int_{0}^{\infty} \frac{dv_1}{v - k} \frac{\partial \mu_2^+}{\partial \nu} - \frac{1}{\pi} \int_{0}^{\infty} dv_R \int_{0}^{\infty} \frac{dv_1}{v - k} \frac{\partial \mu_2^-}{\partial \nu}.
\]  
(2.35)

In order to compute the associated d-bar derivatives, we recall the definition
\[
\frac{\partial \mu}{\partial \nu} = \frac{1}{2} \left( \frac{\partial}{\partial v_R} - i \frac{\partial}{\partial v_I} \right) \mu.
\]  
(2.36)

Thus, by differentiating equation (2.2), we find
\[
\frac{\partial \mu_1^+}{\partial \nu} = \frac{1}{2\pi} \int_{-\infty}^{\infty} d\xi \int_{0}^{\infty} d\eta \ e^{2i\nu_R(\xi - x) - 4i\nu_R v_I(\eta - y)} q(\xi, \eta, t)
+ \frac{1}{2\pi} \int_{0}^{\infty} d\xi \left\{ \int_{0}^{T} d\tau e^{2i\nu_R(\xi - x) + 4i\nu_R v_I y - 8i\nu_R(3v_I^2 - v_R^2)(\tau - t)} Q(\xi, \tau, \nu, -2\nu_R) \right\}
- \frac{1}{2\pi} \int_{0}^{\infty} d\xi \int_{0}^{\infty} d\eta e^{2i\nu_R(\xi - x) - 4i\nu_R v_I(\eta - y)} q(\xi, \eta, t)
+ \frac{1}{2\pi} \int_{0}^{\infty} d\xi \left\{ \int_{0}^{T} d\tau e^{2i\nu_R(\xi - x) + 4i\nu_R v_I y - 8i\nu_R(3v_I^2 - v_R^2)(\tau - t)} Q(\xi, \tau, \nu, -2\nu_R) \right\}
- \frac{1}{2\pi} \int_{-\infty}^{\infty} d\xi \int_{0}^{\infty} d\eta e^{2i\nu_R(\xi - x) - 4i\nu_R v_I(\eta - y)} q(\xi, \eta, t)
- \frac{1}{2\pi} \int_{0}^{\infty} d\xi \left\{ \int_{0}^{T} d\tau e^{2i\nu_R(\xi - x) + 4i\nu_R v_I y - 8i\nu_R(3v_I^2 - v_R^2)(\tau - t)} Q(\xi, \tau, \nu, -2\nu_R) \right\}.
\]

Similarly, using equation (2.3), we find
\[
\frac{\partial \mu_2^+}{\partial \nu} = -\frac{1}{2\pi} \int_{-\infty}^{\infty} d\xi \int_{0}^{\infty} d\eta e^{2i\nu_R(\xi - x) - 4i\nu_R v_I(\eta - y)} q(\xi, \eta, t)
+ \frac{1}{2\pi} \int_{0}^{\infty} d\xi \left\{ \int_{0}^{T} d\tau e^{2i\nu_R(\xi - x) + 4i\nu_R v_I y - 8i\nu_R(3v_I^2 - v_R^2)(\tau - t)} Q(\xi, \tau, \nu, -2\nu_R) \right\}
- \frac{1}{2\pi} \int_{-\infty}^{\infty} d\xi \int_{0}^{\infty} d\eta e^{2i\nu_R(\xi - x) - 4i\nu_R v_I(\eta - y)} q(\xi, \eta, t)
- \frac{1}{2\pi} \int_{0}^{\infty} d\xi \left\{ \int_{0}^{T} d\tau e^{2i\nu_R(\xi - x) + 4i\nu_R v_I y - 8i\nu_R(3v_I^2 - v_R^2)(\tau - t)} Q(\xi, \tau, \nu, -2\nu_R) \right\}.
\]

Thus, the d-bar derivatives of $\mu_1^\pm$ and $\mu_2^\pm$ are equal, i.e.,
\[
\frac{\partial \mu_2^\pm}{\partial \nu} = -\frac{\partial \mu_1^\pm}{\partial \nu}.
\]
Moreover, employing the global relation (2.24) together with the identity
\[ -\int_t^T = \int_0^l - \int_0^{l_T}, \]
we can express the above d-bar derivatives in terms of the initial and boundary
terms on the RHS of equation (2.39) become
\[ \frac{\partial \mu_1^+}{\partial \nu} = \frac{1}{2\pi} e^{-2ivR_x + 4ivR_{\nu_1}y + 8ivR(3v^2 - v_R^2)t} \tilde{q}_0(\nu_R, \nu_1), \]
\[ \frac{\partial \mu_2^+}{\partial \nu} = \frac{1}{2\pi} e^{-2ivR_x + 4ivR_{\nu_1}y + 8ivR(3v^2 - v_R^2)t} \tilde{q}_0(\nu_R, \nu_1) \]
and
\[ \frac{\partial \mu_1^-}{\partial \nu} = \frac{1}{2\pi} e^{-2ivR_x + 4ivR_{\nu_1}y + 8ivR(3v^2 - v_R^2)t} \left[ \tilde{q}_0(\nu_R, \nu_1) + \tilde{S}_T(\nu_R, \nu_1) \right], \]
\[ \frac{\partial \mu_2^-}{\partial \nu} = \frac{1}{2\pi} e^{-2ivR_x + 4ivR_{\nu_1}y + 8ivR(3v^2 - v_R^2)t} \left[ \tilde{q}_0(\nu_R, \nu_1) + \tilde{S}_T(\nu_R, \nu_1) \right], \]
where \( q_0 \) and \( \tilde{S}_T \) are defined by equations (2.28) and (2.29) respectively.
Thus, inserting the above expressions in Pompeiu’s formula (2.35), we obtain
\[ \left( \int_{-\infty}^{\infty} d\nu \right) e^{i\nu l} \left( \int_{-\infty}^{\infty} d\nu \right) e^{-2ivR_x + 4ivR_{\nu_1}y + 8ivR(3v^2 - v_R^2)t} \tilde{Q}_T(\nu_R, l) \]
\[ + \frac{1}{4i\pi} \int_{-\infty}^{\infty} d\nu_R \int_{-\infty}^{\infty} d\nu \left( \int_{-\infty}^{-2\nu_R} d\nu + \int_{-\infty}^{\infty} d\nu \right) e^{i\nu l} \left( \int_{-\infty}^{\infty} d\nu \right) e^{-2ivR_x + 4ivR_{\nu_1}y + 8ivR(3v^2 - v_R^2)t} \tilde{q}_0(\nu_R, \nu_1) \]
\[ + \frac{1}{2\pi^2} \left( \int_{-\infty}^{\infty} d\nu_R \int_{-\infty}^{\infty} d\nu_p \int_{-\infty}^{\infty} d\nu \right) e^{-2ivR_x + 4ivR_{\nu_1}y + 8ivR(3v^2 - v_R^2)t} \tilde{S}_T(\nu_R, \nu_1). \]
(2.39)

In the first two integrals on the RHS of equation (2.43), we make the change of variables
\[ l = 2\alpha, \]
\[ \nu_R = \beta - \alpha \]
\[ \leftrightarrow \]
\[ \alpha = \frac{l}{2}, \]
\[ \beta = \nu_R + \frac{l}{2}. \]
(2.40)
The Jacobian of this transformation is given by
\[ \frac{\partial(\nu_R, l)}{\partial(\beta, \alpha)} = \frac{\partial \nu_R}{\partial \beta} \frac{\partial l}{\partial \alpha} - \frac{\partial \nu_R}{\partial \alpha} \frac{\partial l}{\partial \beta} = 2. \]
The domains of integration are transformed as shown in figure 2.20, the first two terms on the RHS of equation (2.39) become
\[ 2 \left( \int_{-\infty}^{\infty} d\nu \int_{-\infty}^{\infty} d\nu \right) e^{-2i\alpha x - 4i\alpha y + 8i\alpha (\alpha^2 + 3\beta^2)t} \tilde{Q}_T(2\alpha, \beta - \alpha) \]
\[ + 2 \left( \int_{-\infty}^{\infty} d\nu \int_{-\infty}^{\infty} d\nu \right) e^{-2i\alpha x - 4i\alpha y + 8i\alpha (\alpha^2 + 3\beta^2)t} \tilde{Q}_T(2\alpha, \beta - \alpha) \]
We next introduce the transformation
\[ \beta = \nu_I, \]
\[ \alpha = -\nu_R \]
\[ \leftrightarrow \]
\[ \nu_I = -i\beta, \]
\[ \nu_R = -\alpha. \]
Figure 2.5: The regions of integration before and after the change of variables (2.40).

Then, integrating by parts and recalling definitions (2.29) and (2.34), we find

\[
\tilde{Q}_T(\beta - \alpha, 2\alpha) = \int_{-\infty}^{\infty} d\xi \int_{0}^{T} d\tau e^{-2i\alpha\xi - 8i\alpha(\alpha^2 + \beta^2)\tau} Q(\xi, \tau, \beta - \alpha, 2\alpha)
\]

\[
= \int_{-\infty}^{\infty} d\xi \int_{0}^{T} d\tau e^{2i\nu_R\xi - 8i\nu_R(3\nu_I^2 - \nu_R^2)\tau} \left[ 2\nu_I g(\xi, \tau) - \partial^{-1}_\xi h(\xi, \tau) \right]
\]

\[
= -\tilde{S}_T(\nu_R, \nu_I).
\]

Thus, the first two integrals on the RHS of equation (2.39) are equal to the following expression:

\[
-2i\left( \int_{0}^{\infty} d\nu_I \int_{\infty}^{0} \frac{d\nu_R}{\nu - k} + \int_{-\infty}^{0} d\nu_I \int_{-\infty}^{\infty} \frac{d\nu_R}{\nu - k} \right) e^{-2i\nu_R x + 4i\nu_R y + 8i\nu_R(3\nu_I^2 - \nu_R^2)\tau} \tilde{S}_T(\nu_R, \nu_I)
\]

\[
-2i\left( \int_{0}^{\infty} d\nu_I \int_{\infty}^{0} \frac{d\nu_R}{\nu - k} + \int_{-\infty}^{0} d\nu_I \int_{-\infty}^{\infty} \frac{d\nu_R}{\nu - k} \right) e^{-2i\nu_R x + 4i\nu_R y + 8i\nu_R(3\nu_I^2 - \nu_R^2)\tau} \tilde{S}_T(\nu_R, \nu_I)
\]

\[
= 2i\left( \int_{0}^{\infty} d\nu_I \int_{\infty}^{0} \frac{d\nu_R}{\nu - k} - \int_{0}^{\infty} d\nu_I \int_{\infty}^{0} \frac{d\nu_R}{\nu - k} \right) e^{-2i\nu_R x + 4i\nu_R y + 8i\nu_R(3\nu_I^2 - \nu_R^2)\tau} \tilde{S}_T(\nu_R, \nu_I).
\]

Using this expression into equation (2.39), we find equation (2.27). □

Remark 2.3 In equation (2.27), \(\tilde{S}_T\) can be replaced by \(\tilde{S}_t\), where

\[
\tilde{S}_t(\nu_R, \nu_I) = \int_{-\infty}^{\infty} d\xi \int_{0}^{t} d\tau e^{2i\nu_R\xi - 8i\nu_R(3\nu_I^2 - \nu_R^2)\tau} \left[ \partial^{-1}_\xi h(\xi, \tau) - 2\nu_I g(\xi, \tau) \right]. \tag{2.41}
\]

Indeed, we have that

\[
\text{Re}(4i\nu_R\nu_I y) \leq 0 \iff \begin{cases} \arg \nu_I \in [0, \pi], \nu_R \geq 0 \\ \arg \nu_I \in [\pi, 2\pi], \nu_R \leq 0 \end{cases}
\]
and

\[ \text{Re} \left[ -8i\nu_R(3\nu_R^2 - \nu_R^2)(t - \tau) \right] \leq 0 \iff \left\{ \begin{array}{l}
\arg \nu_I \in \left[ \frac{\pi}{2}, \pi \right] \cup \left[ \frac{3\pi}{2}, 2\pi \right], \nu_R \geq 0 \\
\arg \nu_I \in \left[ 0, \frac{\pi}{2} \right] \cup \left[ \pi, \frac{3\pi}{2} \right], \nu_R \leq 0.
\end{array} \right. \]

Hence, the exponential involved in the integrals along the contours \( \partial D_1^+ \) and \( \partial D_1^- \) is bounded and goes to zero as \( |\nu| \to \infty \) for \( \nu \in \{ \nu_R \geq 0, \nu_I \in D_1^+ \} \), and for \( \nu \in \{ \nu_R \leq 0, \nu_I \in D_1^- \} \).

Consequently, equation (1.5a) allows us to write \( q \) in terms of \( \mu \):

\[ q(x, y, t) = -2i \lim_{k \to \infty} \left[ k\mu(x, y, t, k_R, k_I) \right]. \]

Hence, by differentiating equations (2.23), we find:

\[ q(x, y, t) = \frac{2}{\pi^2} \left( \int_{-\infty}^{\infty} dv_R - \int_{-\infty}^{0} dv_R \right) \int_{-\infty}^{\infty} dv_I e^{-2i\nu_R + 4i\nu_R v_I y + 8i\nu_R (3\nu_R^2 - \nu_R^2)t} v_R \tilde{q}_0(\nu_R, \nu_I) \]

\[ + \frac{2}{\pi^2} \int_{-\infty}^{\infty} dv_R \int_{\partial D_1^+} dv_I e^{-2i\nu_R + 4i\nu_R v_I y + 8i\nu_R (3\nu_R^2 - \nu_R^2)t} v_R \tilde{S}_T(\nu_R, \nu_I) \]

\[ - \frac{2}{\pi^2} \int_{-\infty}^{\infty} dv_R \int_{\partial D_1^-} dv_I e^{-2i\nu_R + 4i\nu_R v_I y + 8i\nu_R (3\nu_R^2 - \nu_R^2)t} v_R \tilde{S}_T(\nu_R, \nu_I), \tag{2.42} \]

where \( \tilde{q}_0 \) and \( \tilde{S}_T \) are defined by equations (2.28) and (2.29) respectively.

According to remark 2.3 we can replace \( \tilde{S}_T \) by \( \tilde{S}_I \), thus an alternative representation for \( q \) is given by

\[ q(x, y, t) = \frac{2}{\pi^2} \left( \int_{-\infty}^{\infty} dv_R - \int_{-\infty}^{0} dv_R \right) \int_{-\infty}^{\infty} dv_I e^{-2i\nu_R + 4i\nu_R v_I y + 8i\nu_R (3\nu_R^2 - \nu_R^2)t} v_R \tilde{q}_0(\nu_R, \nu_I) \]

\[ + \frac{2}{\pi^2} \int_{-\infty}^{\infty} dv_R \int_{\partial D_1^+} dv_I e^{-2i\nu_R + 4i\nu_R v_I y + 8i\nu_R (3\nu_R^2 - \nu_R^2)t} v_R \tilde{S}_I(\nu_R, \nu_I) \]

\[ - \frac{2}{\pi^2} \int_{-\infty}^{\infty} dv_R \int_{\partial D_1^-} dv_I e^{-2i\nu_R + 4i\nu_R v_I y + 8i\nu_R (3\nu_R^2 - \nu_R^2)t} v_R \tilde{S}_I(\nu_R, \nu_I), \tag{2.43} \]

where \( \tilde{q}_0 \) and and \( \tilde{S}_I \) are defined by equations (2.28) and (2.41) respectively.

Let us introduce the variables \( k_1, k_2 \) by the equations

\[ \begin{cases} k_1 = -2\nu_R \\
k_2 = 4\nu_R \nu_I \end{cases} \iff \begin{cases} \nu_R = -\frac{k_1}{2} \\

\nu_I = -\frac{k_2}{2k_1}. \end{cases} \]

The Jacobian of this transformation is given by

\[ \left| \frac{\partial(\nu_R, \nu_I)}{\partial(k_1, k_2)} \right| = \left| \frac{\partial \nu_R}{\partial k_1} \frac{\partial \nu_I}{\partial k_2} - \frac{\partial \nu_R}{\partial k_2} \frac{\partial \nu_I}{\partial k_1} \right| = \frac{1}{4|k_1|^2}. \]
Thus, equation (2.43) becomes
\[ q(x, y, t) = \frac{1}{(2\pi)^2} \left( \int_{-\infty}^{0} dk_{1} \int_{-\infty}^{\infty} dk_{2} + \int_{0}^{\infty} dk_{1} \int_{-\infty}^{\infty} dk_{2} \right) e^{ik_{1}x+ik_{2}y-\omega(k)t} \tilde{q}_{0}(k_{1}, k_{2}) \]
\[ + \frac{1}{(2\pi)^2} \int_{-\infty}^{0} dk_{1} \int_{\partial D_{1}^{+}} dk_{2} e^{ik_{1}x+ik_{2}y-\omega(k)t} \tilde{S}_{1}(\frac{k_{1}}{2}, -\frac{k_{2}}{2k_{1}}) \]
\[ + \frac{1}{(2\pi)^2} \int_{0}^{\infty} dk_{1} \int_{\partial D_{1}^{-}} dk_{2} e^{ik_{1}x+ik_{2}y-\omega(k)t} \tilde{S}_{1}(\frac{k_{1}}{2}, -\frac{k_{2}}{2k_{1}}), \]  
(2.44)
where \( \tilde{q}_{0} \) and \( \tilde{S}_{1} \) are defined by equations (2.19a) and (2.41a), \( \omega(k) \) is given by equation (2.20) and the contours of integration are shown in figure 2.3.

The real part of \( \omega(k) \) is equal to \( -\text{Re}k_{2}\text{Im}k_{2}/k_{1} \) and, since \( \tau - t \leq 0 \), the exponential term in equation (2.44) is bounded in the domains \( \{k_{1} \geq 0, k_{2} \in D_{1}^{+} \cup D_{2}^{+}\} \) and \( \{k_{1} \leq 0, k_{2} \in D_{1}^{-} \cup D_{2}^{-}\} \). Hence, the contour \( \partial D_{1}^{+} \) can be deformed onto \( \partial D_{2}^{+} \) (see figure 2.3).

Then, equation (2.44) implies
\[ q(x, y, t) = \frac{1}{(2\pi)^2} \left( \int_{-\infty}^{0} dk_{1} \int_{-\infty}^{\infty} dk_{2} + \int_{0}^{\infty} dk_{1} \int_{-\infty}^{\infty} dk_{2} \right) e^{ik_{1}x+ik_{2}y-\omega(k)t} \tilde{q}_{0}(k_{1}, k_{2}) \]
\[ + \frac{1}{(2\pi)^2} \int_{-\infty}^{0} dk_{1} \int_{\partial D_{1}^{+}} dk_{2} e^{ik_{1}x+ik_{2}y-\omega(k)t} \tilde{S}_{1}(\frac{k_{1}}{2}, -\frac{k_{2}}{2k_{1}}) \]
\[ + \frac{1}{(2\pi)^2} \int_{0}^{\infty} dk_{1} \int_{\partial D_{1}^{-}} dk_{2} e^{ik_{1}x+ik_{2}y-\omega(k)t} \tilde{S}_{1}(\frac{k_{1}}{2}, -\frac{k_{2}}{2k_{1}}). \]
Integration by parts in the definition (2.41) of \( \tilde{S}_{1} \) yields that
\[ \tilde{S}_{1}(\frac{k_{1}}{2}, -\frac{k_{2}}{2k_{1}}) = \int_{-\infty}^{\infty} d\xi \int_{0}^{t} d\tau e^{-ik_{1}\xi+\omega(k)\tau} 3 \left[ \frac{k_{2}}{k_{1}} g(\xi, \tau) - \frac{i}{k_{1}} h(\xi, \tau) \right], \]
hence, recalling the definitions (2.19a) and (2.19c), we find the following expression:
\[ q(x, y, t) = \frac{1}{(2\pi)^2} \left( \int_{-\infty}^{0} dk_{1} \int_{-\infty}^{\infty} dk_{2} e^{ik_{1}x+ik_{2}y-\omega(k)t} \tilde{q}_{0}(k_{1}, k_{2}) \right) \]
\[ + \frac{1}{(2\pi)^2} \int_{-\infty}^{0} dk_{1} \int_{\partial D_{1}^{+}} dk_{2} e^{ik_{1}x+ik_{2}y-\omega(k)t} 3 \left[ \frac{k_{2}}{k_{1}} \tilde{g}_{1}(k_{1}, k_{2}) - \frac{i}{k_{1}} \tilde{h}_{1}(k_{1}, k_{2}) \right] \]
\[ + \frac{1}{(2\pi)^2} \int_{0}^{\infty} dk_{1} \int_{\partial D_{1}^{-}} dk_{2} e^{ik_{1}x+ik_{2}y-\omega(k)t} 3 \left[ \frac{k_{2}}{k_{1}} \tilde{g}_{1}(k_{1}, k_{2}) - \frac{i}{k_{1}} \tilde{h}_{1}(k_{1}, k_{2}) \right], \]
(2.45)
where \( \omega \) is defined by equation (1.3), \( \tilde{q}_{0}, \tilde{g}_{1}, \tilde{h}_{1} \) are defined by equations (2.19b), (2.19c) and (2.19d) respectively, and the contours \( \partial D_{1}^{+} \) and \( \partial D_{1}^{-} \) are shown in figure 2.3.

The solution \( q \) of an IBV problem for the linearised KP in the domain \( \Omega \) is given by equation (2.45).

According to remark 2.3, an equivalent formula for \( q \) is given by
\[ q(x, y, t) = \frac{1}{(2\pi)^2} \left( \int_{-\infty}^{0} dk_{1} \int_{-\infty}^{\infty} dk_{2} e^{ik_{1}x+ik_{2}y-\omega(k)t} \tilde{q}_{0}(k_{1}, k_{2}) \right) \]
\[ + \frac{1}{(2\pi)^2} \int_{-\infty}^{0} dk_{1} \int_{\partial D_{1}^{+}} dk_{2} e^{ik_{1}x+ik_{2}y-\omega(k)t} 3 \left[ \frac{k_{2}}{k_{1}} \tilde{g}_{1}(k_{1}, k_{2}) - \frac{i}{k_{1}} \tilde{h}_{1}(k_{1}, k_{2}) \right] \]
\[ + \frac{1}{(2\pi)^2} \int_{0}^{\infty} dk_{1} \int_{\partial D_{1}^{-}} dk_{2} e^{ik_{1}x+ik_{2}y-\omega(k)t} 3 \left[ \frac{k_{2}}{k_{1}} \tilde{g}_{1}(k_{1}, k_{2}) - \frac{i}{k_{1}} \tilde{h}_{1}(k_{1}, k_{2}) \right], \]
(2.46)
with \( \tilde{y}_T \) and \( \tilde{h}_T \) defined analogously to \( \tilde{y}_t \) and \( \tilde{h}_t \).

**Proposition 2.4.** The formula defined by equation (2.46) in terms of \( \{q_0(x, y), q(x, 0, t), \tilde{q}_0(x, 0, t)\} \) represents the solution to the linearised KP equation (1.2) in \( \Omega \), provided that the functions \( \tilde{q}_0, \tilde{y}_T, \tilde{h}_T \) satisfy the global relation (2.25). An equivalent representation is given by equation (2.46).

**Proof** Since equations (2.45) and (2.46) are equivalent, we can use either of them in the calculations that follow.

By differentiating equation (2.46), it is straightforward to show that \( q(x, y, t) \) satisfies the linearised KP equation.

**Initial Condition:** Evaluating the expression (2.45) at \( t = 0 \) and using the fact that

\[
\int d\lambda e^{i\lambda(x-\xi)} = 2\pi\delta(x - \xi), \quad \lambda \in D,
\]

we find

\[
q(x, y, 0) = \frac{1}{(2\pi)^2} \int_{-\infty}^{\infty} dk_1 \int_{-\infty}^{\infty} dk_2 e^{ik_1 x + ik_2 y} \tilde{q}_0(k_1, k_2)
= \frac{1}{(2\pi)^2} \int_{-\infty}^{\infty} dk_1 \int_{-\infty}^{\infty} dk_2 \int_{-\infty}^{\infty} d\xi \int_{-\infty}^{\infty} d\eta e^{ik_1(x-\xi) + ik_2(y-\eta)} \tilde{q}_0(\xi, \eta)
= \frac{1}{(2\pi)^2} \int_{-\infty}^{\infty} d\xi \int_{0}^{\infty} d\eta (2\pi)^2 \delta(x - \xi) \delta(y - \eta) \tilde{q}_0(\xi, \eta)
= q_0(x, y),
\]

thus the initial condition (1.13a) is satisfied.

**Boundary Values:** At \( y = 0 \), equation (2.46) becomes

\[
q(x, 0, t) = \frac{1}{(2\pi)^2} \int_{-\infty}^{\infty} dk_1 \int_{-\infty}^{\infty} dk_2 e^{ik_1 x - \omega(k)t} \tilde{q}_0(k_1, k_2)
+ \frac{1}{(2\pi)^2} \int_{-\infty}^{0} dk_1 \int_{0}^{\infty} dk_2 e^{ik_1 x - \omega(k)t} \frac{k_2}{k_1} \begin{bmatrix} \bar{g}_T(k_1, k_2) - i k_1 \bar{h}_T(k_1, k_2) \\ - \bar{g}_T(k_1, k_2) - i k_1 \bar{h}_T(k_1, k_2) \end{bmatrix}
+ \frac{1}{(2\pi)^2} \int_{0}^{\infty} dk_1 \int_{\partial D_1^2} dk_2 e^{ik_1 x - \omega(k)t} \frac{k_2}{k_1} \begin{bmatrix} \bar{g}_T(k_1, k_2) - i k_1 \bar{h}_T(k_1, k_2) \\ - \bar{g}_T(k_1, k_2) - i k_1 \bar{h}_T(k_1, k_2) \end{bmatrix}.
\]

Under the symmetry transformation \( k_2 \mapsto -k_2 \) of \( \omega(k) \), the global relation (2.25) assumes the form:

\[
e^{\omega(k)} \tilde{q}(k_1, -k_2, t) = \tilde{q}_0(k_1, -k_2) - 3 \frac{k_2}{k_1} \bar{g}_T(k_1, k_2) - 3 \frac{i}{k_1} \bar{h}_T(k_1, k_2), \quad k_1 \in \mathbb{R}, \quad \text{Im} k_2 \geq 0,
\]

while we notice that the functions \( \tilde{y}_T \) and \( \tilde{h}_T \), which depend on \( k_2 \) only through \( \omega(k) \), remain invariant. Solving this expression for \( \bar{h}_T \) and substituting into equation (2.48), we find

\[
q(x, 0, t) = \frac{1}{(2\pi)^2} \int_{-\infty}^{\infty} dk_1 \int_{-\infty}^{\infty} dk_2 e^{ik_1 x - \omega(k)t} \tilde{q}_0(k_1, k_2)
+ \frac{1}{(2\pi)^2} \left( \int_{-\infty}^{0} dk_1 \int_{0}^{\infty} dk_2 + \int_{0}^{\infty} dk_1 \int_{\partial D_1^2} dk_2 \right) e^{ik_1 x - \omega(k)t} \frac{k_2}{k_1} \bar{g}_T(k_1, k_2)
- \frac{1}{(2\pi)^2} \left( \int_{-\infty}^{0} dk_1 \int_{\partial D_1^2} dk_2 + \int_{0}^{\infty} dk_1 \int_{\partial D_1^2} dk_2 \right) e^{ik_1 x - \omega(k)t} \tilde{q}_0(k_1, -k_2)
+ \frac{1}{(2\pi)^2} \left( \int_{0}^{\infty} dk_1 \int_{\partial D_1^2} dk_2 + \int_{0}^{\infty} dk_1 \int_{\partial D_1^2} dk_2 \right) e^{ik_1 x} \tilde{q}(k_1, -k_2, t).
\]
Recalling the definition (2.19b) of \( \hat{q} \), we note that the last term on the RHS of the above equation vanishes due to Jordan’s lemma on the complex \( k_2 \)-plane. Also, recalling the definition (2.19b) of \( q_0 \), equation (2.50) becomes

\[ q(x, 0, t) = \frac{1}{(2\pi)^2} \int_{-\infty}^{\infty} dk_1 \int_{-\infty}^{\infty} dk_2 e^{ik_1 x - \omega(k)t} \int_{-\infty}^{\infty} d\xi \int_{0}^{\infty} d\eta e^{-ik_1 \xi - ik_2 \eta} q_0(\xi, \eta) \]

\[ + \frac{1}{(2\pi)^2} \left( \int_{-\infty}^{0} dk_1 \int_{-\infty}^{0} dk_2 + \int_{0}^{\infty} dk_1 \int_{0}^{\infty} dk_2 \right) e^{ik_1 x - \omega(k)t} \frac{k_2}{k_1} \int_{-\infty}^{0} \frac{d\xi}{0} d\tau e^{-ik_1 \xi + \omega(k)\tau} g(\xi, \tau) \]

\[ - \frac{1}{(2\pi)^2} \left( \int_{-\infty}^{0} dk_1 \int_{-\infty}^{0} dk_2 + \int_{0}^{\infty} dk_1 \int_{0}^{\infty} dk_2 \right) e^{ik_1 x - \omega(k)t} \int_{-\infty}^{\infty} d\xi \int_{0}^{\infty} d\eta e^{-ik_1 \xi + ik_2 \eta} q_0(\xi, \eta). \]

(2.51)

The definition (2.20) of \( \omega \) implies

\[ \text{Re} \omega(k) = -\frac{6}{k_1} \text{Re} k_1 \text{Im} k_2, \]

hence we can deform the contours \( \partial D^+ \) and \( \partial D^+_2 \) onto the real \( k \)-axis in the third term on the RHS of equation (2.51), i.e.

\[ q(x, 0, t) = \frac{1}{(2\pi)^2} \int_{-\infty}^{\infty} dk_1 \int_{-\infty}^{\infty} dk_2 e^{ik_1 x - \omega(k)t} \int_{-\infty}^{\infty} d\xi \int_{0}^{\infty} d\eta e^{-ik_1 \xi - ik_2 \eta} q_0(\xi, \eta) \]

\[ + \frac{1}{(2\pi)^2} \left( \int_{-\infty}^{0} dk_1 \int_{-\infty}^{0} dk_2 + \int_{0}^{\infty} dk_1 \int_{0}^{\infty} dk_2 \right) e^{ik_1 x - \omega(k)t} \frac{k_2}{k_1} \int_{-\infty}^{0} \frac{d\xi}{0} d\tau e^{-ik_1 \xi + \omega(k)\tau} g(\xi, \tau) \]

\[ - \frac{1}{(2\pi)^2} \left( \int_{-\infty}^{0} dk_1 \int_{-\infty}^{0} dk_2 + \int_{0}^{\infty} dk_1 \int_{0}^{\infty} dk_2 \right) e^{ik_1 x - \omega(k)t} \int_{-\infty}^{\infty} d\xi \int_{0}^{\infty} d\eta e^{-ik_1 \xi + ik_2 \eta} q_0(\xi, \eta). \]

The first and the third term on the RHS of this equation cancel, while the change of variables

\[ l = -\frac{3k_2}{k_1} \Rightarrow dl = -\frac{3k_2}{k_1} \]

on the second term yields

\[ q(x, 0, t) = \frac{1}{(2\pi)^2} \int_{-\infty}^{\infty} dk_1 \int_{-\infty}^{\infty} dl e^{ik_1 x - (ik_1^2 + il)t} \int_{-\infty}^{\infty} d\xi \int_{0}^{T} d\tau e^{-ik_1 \xi + (ik_1^2 + il)\tau} g(\xi, \tau). \]

(2.52)

Using the identity (2.47), we find

\[ q(x, 0, t) = \frac{1}{(2\pi)^2} \int_{-\infty}^{\infty} d\xi \int_{-\infty}^{\infty} dk_1 e^{-ik_1 (\xi - x)} \int_{0}^{T} d\tau e^{-ik_1^2 (\tau - t)} \int_{-\infty}^{\infty} dl e^{il(\tau - t)} g(\xi, \tau) \]

\[ = \frac{1}{2\pi} \int_{-\infty}^{\infty} d\xi \int_{-\infty}^{\infty} dk_1 e^{-ik_1 (\xi - x)} \int_{0}^{T} d\tau e^{-ik_1^2 (\tau - t)} g(\xi, \tau) \delta(\tau - t) \]

\[ = \frac{1}{2\pi} \int_{-\infty}^{\infty} d\xi \int_{-\infty}^{\infty} dk_1 e^{-ik_1 (\xi - x)} g(\xi, t) \]

\[ = \int_{-\infty}^{\infty} d\xi g(\xi, t) \delta(\xi - x) \]

\[ = g(x, t). \]

(2.53)

In a similar way, it can be shown that \( q_y(x, 0, t) = h(x, t). \)
3 The KPII equation

The first Lax equation (1.6a) suggests that there exists a solution \( \mu \) with the asymptotic behaviour

\[
\mu = 1 + O \left( \frac{1}{k} \right), \quad k \to \infty.
\]  

(3.1)

3.1 The direct problem

**Proposition 3.1.** Assume that there exists a solution \( q(x, y, t) \), \((x, y, t) \in \Omega\), for an initial-boundary value problem of equation (1.4). Then, the function \( \mu \), which is bounded \( \forall k \in \mathbb{C} \) and is defined as

\[
\mu(x, y, t, k_R, k_I) = \begin{cases} 
\mu_1^+(x, y, t, k_R, k_I), & k_R \leq 0, \ k_I \geq 0, \\
\mu_1^-(x, y, t, k_R, k_I), & k_R \leq 0, \ k_I \leq 0, \\
\mu_2^-(x, y, t, k_R, k_I), & k_R \geq 0, \ k_I \leq 0, \\
\mu_2^+(x, y, t, k_R, k_I), & k_R \geq 0, \ k_I \geq 0,
\end{cases}
\]

(3.2)

in the different quadrants of the complex \( k \)-plane (see figure 2.1), admits the following representations in terms of \( q(x, y, t) \), \( q(x, 0, t) \) and \( q_y(x, 0, t) \):

\[
\mu_1^+ = 1 + \frac{1}{2\pi} \left( \int_{-\infty}^{0} dl + \int_{0}^{\infty} dl \right) \int_{-\infty}^{\infty} d\xi \int_{0}^{y} d\eta e^{-i(l(\xi-x)+l(\eta-y))} q(\xi, \eta, t) \mu_1^+ \\
+ \frac{1}{2\pi} \left( \int_{-\infty}^{0} dl + \int_{0}^{\infty} dl \right) \int_{-\infty}^{\infty} d\xi \int_{0}^{y} d\eta e^{-i(l(\xi-x)-l(\eta-y))} \frac{1}{\eta} H(\xi, \tau, k, l) \phi_1^+, \\
- \frac{1}{2\pi} \int_{-\infty}^{\infty} dl \int_{-\infty}^{\infty} d\xi \int_{0}^{y} d\eta e^{-i(l(\xi-x)+l(\eta-y))} q(\xi, \eta, t) \mu_1^+.
\]

(3.3)

\[
\mu_2^+ = 1 + \frac{1}{2\pi} \left( \int_{-\infty}^{-2k_R} dl + \int_{0}^{\infty} dl \right) \int_{-\infty}^{\infty} d\xi \int_{0}^{y} d\eta e^{-i(l(\xi-x)+l(\eta-y))} q(\xi, \eta, t) \mu_2^+ \\
+ \frac{1}{2\pi} \left( \int_{-\infty}^{-2k_R} dl + \int_{0}^{\infty} dl \right) \int_{-\infty}^{\infty} d\xi \int_{0}^{y} d\eta e^{-i(l(\xi-x)-l(\eta-y))} \frac{1}{\eta} H(\xi, \tau, k, l) \phi_2^+, \\
- \frac{1}{2\pi} \int_{-\infty}^{0} dl \int_{-\infty}^{\infty} d\xi \int_{0}^{y} d\eta e^{-i(l(\xi-x)+l(\eta-y))} q(\xi, \eta, t) \mu_2^+.
\]

(3.4)

where

\[
\phi_{1,2}^+(x, t, k_R, k_I) = \mu_{1,2}^+(x, 0, t, k_R, k_I),
\]

(3.5)

the function \( H \) is given by

\[
H(x, t, k, l) := 3 \left[ g_x(x, t) - 2i(l+k)g(x, t) - \partial_x^{-1} h(x, t) \right]
\]

(3.6)

and

\[
g(x, t) = q(x, 0, t), \quad h(x, t) = q_y(x, 0, t),
\]

as defined by equations (1.13b) and (1.13c).

**Proof** Define the Fourier transform of \( \mu \) with respect to \( x \) by

\[
\hat{\mu}(l, y, t, k_R, k_I) := \int_{-\infty}^{\infty} dx \ e^{-ilx} \left[ \mu(x, y, t, k_R, k_I) - 1 \right], \quad l \in \mathbb{R}, \ k \in \mathbb{C},
\]

(3.7a)
with the inverse Fourier transform given by

\[ \mu(x, y, t, k_R, k_I) := 1 + \frac{1}{2\pi} \int_{-\infty}^{\infty} dl \int_{-\infty}^{\infty} dt \ e^{ix(l+2k)y} \tilde{\mu}(l, y, t, k_R, k_I), \quad l \in \mathbb{R}, \ k \in \mathbb{C}. \quad (3.7b) \]

Applying the Fourier transform on the first Lax equation yields an ODE in \( y \):

\[ \hat{\mu}_y(l, y, t, k_R, k_I) + l(l + 2k) \hat{\mu}(l, y, t, k_R, k_I) = \tilde{\mu}(l, y, t, k_R, k_I), \quad (3.8) \]

where

\[ \hat{\mu}(l, y, t, k_R, k_I) := \int_{-\infty}^{\infty} dx \ e^{-ix} (q\mu) (x, y, t, k_R, k_I). \]

We solve this equation by integrating with respect to \( y \) either from \( y = 0 \) or from \( y = \infty \):

\[ \hat{\mu}(l, y, t, k_R, k_I) = \begin{cases} \int_0^y d\eta \ e^{i(l+2k)(\eta-y)} \hat{q}\tilde{\mu}(l, \eta, t, k_R, k_I) + \hat{\mu}(l, 0, t, k_R, k_I) e^{-i(l+2k)y} & \text{if } l(l+2k) \geq 0, \\ -\int_y^\infty d\eta \ e^{i(l+2k)(\eta-y)} \hat{q}\tilde{\mu}(l, \eta, t, k_R, k_I), & \text{if } l(l+2k) < 0, \end{cases} \]

(3.9)

where we have assumed that \( \hat{\mu} \to 0 \) as \( y \to \infty \).

We look for a solution which is bounded \( \forall k \in \mathbb{C} \). In the first expression in equation (3.9), \( \eta - y \leq 0 \), thus we require that \( \text{Re} \left[ l(l+2k) \right] \geq 0 \), i.e.

\[ l(l+2k) \geq 0 \iff \left\{ \begin{array}{l} l \in (-\infty, 0] \cup [-2k_R, \infty), \ k_R \leq 0 \\ l \in (-\infty, -2k_R] \cup [0, \infty), \ k_R \geq 0. \end{array} \right. \]

Analogous considerations are valid for the second expression in equation (3.9): \( \eta - y \geq 0 \) implies that \( \text{Re} \left[ l(l+2k) \right] \leq 0 \), i.e.

\[ l(l+2k) \leq 0 \iff \left\{ \begin{array}{l} l \in [0, -2k_R], \ k_R \leq 0 \\ l \in [-2k_R, 0], \ k_R \geq 0. \end{array} \right. \]

Applying the inverse Fourier transform (3.7b) on equations (3.9) and writing \( \mu \) according to the definition (3.2), we obtain

\[
\begin{align*}
\mu_1(x, y, t, k_R, k_I) &= 1 + \frac{1}{2\pi} \left( \int_{-\infty}^{0} dl + \int_{-2k_R}^{\infty} dl \right) e^{ixl(l+2k)y} \int_0^y d\eta \ e^{i(l+2k)\eta} \hat{q}\tilde{\mu}(l, \eta, t, k_R, k_I) \\
&\quad + \frac{1}{2\pi} \left( \int_{-\infty}^{0} dl + \int_{-2k_R}^{\infty} dl \right) e^{ixl(l+2k)y} \tilde{\phi}_1(l, t, k_R, k_I) \\
&\quad - \frac{1}{2\pi} \int_{-2k_R}^{0} dl \ e^{ixl(l+2k)y} \int_y^\infty d\eta \ e^{i(l+2k)\eta} \hat{q}\tilde{\mu}(l, \eta, t, k_R, k_I), \quad k_R \leq 0, \quad (3.10) \\
\mu_2(x, y, t, k_R, k_I) &= 1 + \frac{1}{2\pi} \left( \int_{-\infty}^{-2k_R} dl + \int_{0}^{\infty} dl \right) e^{ixl(l+2k)y} \int_0^y d\eta \ e^{i(l+2k)\eta} \hat{q}\tilde{\mu}(l, \eta, t, k_R, k_I) \\
&\quad + \frac{1}{2\pi} \left( \int_{-\infty}^{-2k_R} dl + \int_{0}^{\infty} dl \right) e^{ixl(l+2k)y} \tilde{\phi}_2(l, t, k_R, k_I) \\
&\quad - \frac{1}{2\pi} \int_{-2k_R}^{0} dl \ e^{ixl(l+2k)y} \int_y^\infty d\eta \ e^{i(l+2k)\eta} \hat{q}\tilde{\mu}(l, \eta, t, k_R, k_I), \quad k_R \geq 0. \quad (3.11)
\end{align*}
\]
Evaluating equation (3.10) at \( y = 0 \) and recalling the definition (3.7a) we find
\[
\phi_1(x, t, k_R, k_I) = 1 + \frac{1}{2\pi} \left( \int_{-\infty}^{\infty} dl + \int_{-2k_R}^{2k_R} dl \right) e^{ilx} \hat{\phi}_1(l, t, k_R, k_I)
\]
\[\quad - \frac{1}{2\pi} \int_{0}^{\infty} d\eta e^{ilx+il(l+2k_R)\eta} \hat{\mu}(l, \eta, t, k_R, k_I). \tag{3.12}\]

The definition (3.7b) yields
\[
\frac{1}{2\pi} \int_{-\infty}^{\infty} dl e^{ilx} \hat{\phi}_1(l, t, k_R, k_I) = \frac{1}{2\pi} \left( \int_{-\infty}^{\infty} dl + \int_{-2k_R}^{2k_R} dl \right) e^{ilx} \hat{\phi}_1(l, t, k_R, k_I)
\]
\[\quad - \frac{1}{2\pi} \int_{0}^{\infty} d\eta e^{ilx+il(l+2k_R)\eta} \hat{\mu}(l, \eta, t, k_R, k_I).
\]

This equation implies that \( \hat{\phi}_1 \) does not satisfy any constraints for \( l \in (-\infty, 0] \cup [-2k_R, \infty) \), whereas it does satisfy the following constraint for \( l \in [0, 2k_R] \):
\[
\hat{\phi}_1(l, t, k_R, k_I) = - \int_{0}^{\infty} d\eta e^{il(l+2k_R)\eta} \hat{\mu}(l, \eta, t, k_R, k_I), \quad l \in [0, 2k_R]. \tag{3.13}\]

The second Lax equation (1.6b) evaluated at \( y = 0 \) yields
\[
\phi_t + 4\phi_{xxx} + 12ik\phi_{xx} - 12k^2\phi_x - \Lambda \phi = 0, \tag{3.14}\]

where \( \Lambda \) is defined as
\[
\Lambda(x, t, k_R, k_I) = F(x, 0, t, k_R, k_I)
\]
\[\quad = -6g(x, t) (\partial_x + ik) - 3 \left[ g_x(x, t) + \partial_x^{-1} h(x, t) \right]. \]

By applying the Fourier transform (3.7a) on equation (3.14), we obtain the following ODE in \( t \):
\[
\hat{\phi}_1(l, t, k_R, k_I) - 4il (l^2 + 3kl + 3k^2) \hat{\phi}(l, t, k_R, k_I) = \hat{\Lambda}(l, t, k_R, k_I).
\]

Integrating this expression with respect to \( t \) either from \( t = 0 \) or from \( t = T \), we find:
\[
\hat{\phi}(l, t, k_R, k_I) = \begin{cases} 
\int_{0}^{T} d\tau e^{-4il(l^2+3kl+3k^2)(\tau-t)} \hat{\Lambda} \phi + e^{4il(l^2+3kl+3k^2)(T-t)} \hat{\phi} \big|_{t=0} \\
\int_{T}^{t} d\tau e^{-4il(l^2+3kl+3k^2)(\tau-t)} \hat{\Lambda} \phi + e^{4il(l^2+3kl+3k^2)(T-t)} \hat{\phi} \big|_{t=T}, \end{cases} \quad k \in \mathbb{C}.
\]

Integration by parts of the integral in \( \hat{\Lambda} \phi \) implies
\[
\hat{\phi}(l, t, k_R, k_I) = \begin{cases} 
\int_{0}^{T} d\tau e^{-4il(l^2+3kl+3k^2)(\tau-t)} \hat{H} \phi + e^{4il(l^2+3kl+3k^2)(T-t)} \hat{\phi} \big|_{t=0} \\
\int_{T}^{t} d\tau e^{-4il(l^2+3kl+3k^2)(\tau-t)} \hat{H} \phi + e^{4il(l^2+3kl+3k^2)(T-t)} \hat{\phi} \big|_{t=T}, \end{cases} \quad k \in \mathbb{C}, \tag{3.15}
\]

where the quantity \( H \) is defined by equation (3.6), and
\[
\hat{H} \phi(l, t, k_R, k_I) := \int_{-\infty}^{\infty} dx e^{-ilx} (H \phi)(x, \tau, k_R, k_I).
\]

In order for \( \phi \) to be bounded \( \forall k \in \mathbb{C} \), we require that the exponential involved in equation (3.15) is bounded. Noting that
\[
\text{Re} \left[ -4il(l^2 + 3kl + 3k^2) \right] = 12k_H l (l + 2k_R),
\]
we are led to consider the following cases (see also figure 2.1):
• If \( k \in \{ k \in \mathbb{C} : k_R \leq 0, k_I \geq 0 \} \), then \( l \in (-\infty, 0] \cup [-2k_R, \infty) \) implies that \( \tau - t \leq 0 \), whereas \( l \in [0, -2k_R] \) implies that \( \tau - t \geq 0 \). Thus, recalling our analysis for \( \hat{\phi}_1 \), we can choose

\[
\hat{\phi}_1^+(l, 0, k_R, k_I) = 0,\quad l \in (-\infty, 0] \cup [-2k_R, \infty),
\]

Equation (3.13) imposes

\[
\hat{\phi}_1^+(l, T, k_R, k_I) = -\int_0^\infty d\eta e^{(l+2k)\eta} \hat{q}_1^+(l, \eta, T, k_R, k_I),\quad l \in [0, -2k_R].
\]

Therefore, using equation (3.15) we find:

\[
\hat{\phi}_1^+(l, t, k_R, k_I) = \begin{cases}
\int_0^t d\tau e^{-4it(l^2+3kl+3k^2)(\tau-t)} H\hat{\phi}_1^+, \quad l \in (-\infty, 0) \cup (-2k_R, \infty) \\
-\int_t^T d\tau e^{-4it(l^2+3kl+3k^2)(\tau-t)} H\hat{\phi}_1^-
\end{cases}
\]

\[\quad -e^{-4it(l^2+3kl+3k^2)(T-t)} \int_0^\infty d\eta e^{(l+2k)\eta} \hat{q}_1^+ \bigg|_{t=T}, \quad l \in [0, -2k_R].
\]

(3.16)

Similar calculations for \( k \) in each of the other three quadrants yield the following results:

• for \( k \in \{ k \in \mathbb{C} : k_R \leq 0, k_I \leq 0 \} \),

\[
\hat{\phi}_1^-(l, t, k_R, k_I) = \begin{cases}
\int_0^t d\tau e^{-4it(l^2+3kl+3k^2)(\tau-t)} H\hat{\phi}_1^-, \quad l \in (-\infty, 0) \cup [-2k_R, \infty) \\
-\int_t^T d\tau e^{-4it(l^2+3kl+3k^2)(\tau-t)} H\hat{\phi}_1^-
\end{cases}
\]

\[\quad -e^{-4it(l^2+3kl+3k^2)(T-t)} \int_0^\infty d\eta e^{(l+2k)\eta} \hat{q}_1^- \bigg|_{t=0}, \quad l \in [0, -2k_R].
\]

(3.17)

• for \( k \in \{ k \in \mathbb{C} : k_R \geq 0, k_I \geq 0 \} \),

\[
\hat{\phi}_2^+(l, t, k_R, k_I) = \begin{cases}
\int_0^t d\tau e^{-4it(l^2+3kl+3k^2)(\tau-t)} H\hat{\phi}_2^+, \quad l \in (-\infty, -2k_R) \cup [0, \infty) \\
-\int_t^T d\tau e^{-4it(l^2+3kl+3k^2)(\tau-t)} H\hat{\phi}_2^+
\end{cases}
\]

\[\quad -e^{-4it(l^2+3kl+3k^2)(T-t)} \int_0^\infty d\eta e^{(l+2k)\eta} \hat{q}_2^+ \bigg|_{t=T}, \quad l \in [-2k_R, 0].
\]

(3.18)

• and for \( k \in \{ k \in \mathbb{C} : k_R \geq 0, k_I \leq 0 \} \),

\[
\hat{\phi}_2^-(l, t, k_R, k_I) = \begin{cases}
\int_0^t d\tau e^{-4it(l^2+3kl+3k^2)(\tau-t)} H\hat{\phi}_2^-, \quad l \in (-\infty, -2k_R) \cup [0, \infty) \\
-\int_t^T d\tau e^{-4it(l^2+3kl+3k^2)(\tau-t)} H\hat{\phi}_2^-
\end{cases}
\]

\[\quad -e^{-4it(l^2+3kl+3k^2)(T-t)} \int_0^\infty d\eta e^{(l+2k)\eta} \hat{q}_2^- \bigg|_{t=0}, \quad l \in [-2k_R, 0].
\]

(3.19)

Inserting equations (3.10)–(3.13) into equations (3.10) and (3.11), we obtain for \( \mu_1 \) and \( \mu_2 \) the representations (3.3) and (3.4) respectively.
3.2 The global relation

**Proposition 3.2.** Define \( g_0, g \) and \( h \) by equations (1.13a), (1.13b) and (1.13c) respectively. Also, define the functions \( \phi \) and \( H \) by equations (3.30) and (3.30).

Then, these functions satisfy the so-called global relation:

\[
\int_{-\infty}^{\infty} \int_{0}^{\infty} d\eta e^{-i \eta (l+2k)t} q_0(\eta, \mu_0) - \int_{-\infty}^{\infty} \int_{0}^{t} d\tau e^{-i \tau (l+2k)t} H(\xi, \tau, k, l) \phi \\
= \int_{-\infty}^{\infty} \int_{0}^{\infty} d\eta e^{-i \eta (l+2k)t} q(\xi, \eta, t) \mu, \quad k \in \mathbb{C}, \quad l(l + 2k_R) \leq 0.
\]

(3.20)

**Proof** Equation (3.8) yields

\[
\left( \mu e^{(l+2k)y-4il(l^2+3kl+3k^2)t} \right)_y = e^{(l+2k)y-4il(l^2+3kl+3k^2)t} \int_{-\infty}^{\infty} dx e^{-i \eta x} q_\mu.
\]

Also, the second equation of the Lax pair implies

\[
\left( \mu e^{(l+2k)y-4il(l^2+3kl+3k^2)t} \right)_t = e^{(l+2k)y-4il(l^2+3kl+3k^2)t} \int_{-\infty}^{\infty} dx e^{-i \eta x} H_\mu.
\]

The above equations imply

\[
\left( e^{(l+2k)y-4il(l^2+3kl+3k^2)t} \int_{-\infty}^{\infty} dx e^{-i \eta x} q_\mu \right)_y = \left( e^{(l+2k)y-4il(l^2+3kl+3k^2)t} \int_{-\infty}^{\infty} dx e^{-i \eta x} H_\mu \right)_y.
\]

Using Green’s theorem over the domain depicted in figure 2.2, we obtain the global relation (3.20):

\[
\int_{-\infty}^{\infty} \int_{0}^{\infty} d\eta e^{-i \eta (l+2k)t} q_0(\xi, \eta) \mu_0 - \int_{-\infty}^{\infty} \int_{0}^{t} d\tau e^{-i \tau (l+2k)t} H(\xi, \tau, k, l) \phi \\
= \int_{-\infty}^{\infty} \int_{0}^{\infty} d\eta e^{-i \eta (l+2k)t} q(\xi, \eta, t) \mu, \quad k \in \mathbb{C}, \quad l(l + 2k_R) \leq 0.
\]

Note that the constraint on \( l \) is needed in order for the exponential \( e^{(l+2k)y} \) to be bounded.

3.3 The inverse problem

It will be shown later (see equation (3.40)) that

\[
(\mu^+_1 - \mu^-_2) |_{k_R=0} = 0.
\]

Assuming that \( \mu \) is continuous across the imaginary \( k \)-axis, Pompeiu’s formula (1.12)

\[
\mu(k_R, k_I) = \frac{1}{2\pi i} \int_{\partial \mathcal{D}} \frac{dv}{v-k} \mu(v_R, v_I) + \frac{1}{2\pi} \int_{\mathcal{D}} \frac{dv \wedge d\bar{v}}{v-k} \frac{\partial}{\partial v} \mu(v_R, v_I),
\]

applied in the simple domain \( \mathcal{D} \) (see figure 2.3), yields

\[
\mu = 1 + \frac{1}{2\pi} \int_{0}^{\infty} \frac{dv_R}{v_R-k} \Delta \mu_1 + \frac{1}{2\pi} \int_{0}^{\infty} \frac{dv_R}{v_R-k} \Delta \mu_2 \\
- \frac{1}{\pi} \int_{0}^{\infty} dv_R \int_{-\infty}^{0} \frac{dv_I}{v-I-k} \frac{\partial}{\partial v} \mu_2 \\
- \frac{1}{\pi} \int_{0}^{\infty} dv_R \int_{0}^{\infty} \frac{dv_I}{v-I-k} \frac{\partial}{\partial v} \mu_1 \\
- \frac{1}{\pi} \int_{0}^{\infty} dv_R \int_{-\infty}^{0} \frac{dv_I}{v-I-k} \frac{\partial}{\partial v} \mu_1 \\
- \frac{1}{\pi} \int_{-\infty}^{0} dv_R \int_{0}^{\infty} \frac{dv_I}{v-I-k} \frac{\partial}{\partial v} \mu_1 \\
- \frac{1}{\pi} \int_{\infty}^{0} dv_R \int_{0}^{\infty} \frac{dv_I}{v-I-k} \frac{\partial}{\partial v} \mu_1. \tag{3.21}
\]
where
\[ \Delta \mu_j(x, y, t, k_R) := (\mu_j^+ - \mu_j^-) (x, y, t, k_R, 0), \quad j = 1, 2. \]  

(3.22)

Therefore, we need to derive expressions for the discontinuities of \( \mu \) across the real \( k \)-axis and for the d-bar derivatives of \( \mu \) in the complex \( k \)-plane.

**Proposition 3.3. (The d-bar derivatives)** Define the functions \( \mu_1^\pm \) and \( \mu_2^\pm \) by equations (3.2), (3.3) and (3.4). Then,

\[
\frac{\partial \mu_1^\pm}{\partial k}(x, y, t, k_R, k_I) = e^{-2ik_Rx+4ik_Rk_Iy-8ik_R(k_R^2-3k_I^2)t} \gamma_1^\pm(k_R, k_I) \mu_2^\pm(x, y, t, -k_R, k_I),
\]

and

\[
\frac{\partial \mu_2^\pm}{\partial k}(x, y, t, k_R, k_I) = -e^{-2ik_Rx+4ik_Rk_Iy-8ik_R(k_R^2-3k_I^2)t} \gamma_2^\pm(k_R, k_I) \mu_1^\pm(x, y, t, -k_R, k_I),
\]

where

\[
\gamma_1^+(k_R, k_I) = \beta_1^+(k_R, k_I), \quad k_R \leq 0, k_I \geq 0, \quad (3.25)
\]

\[
\gamma_1^-(k_R, k_I) = \beta_1^-(k_R, k_I) - \alpha_1^-(k_R, k_I), \quad k_R \leq 0, k_I \leq 0, \quad (3.26)
\]

\[
\gamma_2^+(k_R, k_I) = \beta_2^+(k_R, k_I), \quad k_R \geq 0, k_I \geq 0, \quad (3.27)
\]

\[
\gamma_2^-(k_R, k_I) = \beta_2^-(k_R, k_I) - \alpha_2^-(k_R, k_I), \quad k_R \geq 0, k_I \leq 0 \quad (3.28)
\]

and \( \alpha_{1,2}^\pm, \beta_{1,2}^\pm \) are defined in the appropriate quadrant of the complex \( k \)-plane by the following formulae:

\[
\alpha_1^-(k_R, k_I) = \frac{1}{2\pi} \int_{-\infty}^{\infty} d\xi \int_{0}^{T} d\tau \, e^{2ik_R\xi+4ik_Rk_I\eta} H(\xi, \tau, k, -2k_R) \phi_1^- (\xi, \tau, k_R, k_I),
\]

(3.29)

\[
\beta_1^+(k_R, k_I) = \frac{1}{2\pi} \int_{-\infty}^{\infty} d\xi \int_{0}^{\infty} d\eta \, e^{2ik_R\xi-4ik_Rk_I\eta} \mu_1^+(\xi, \eta, 0, k_R, k_I),
\]

(3.30)

\[
\alpha_2^-(k_R, k_I) = \frac{1}{2\pi} \int_{-\infty}^{\infty} d\xi \int_{0}^{T} d\tau \, e^{2ik_R\xi+4ik_Rk_I\eta} H(\xi, \tau, k, -2k_R) \phi_2^- (\xi, \tau, k_R, k_I),
\]

(3.31)

\[
\beta_2^+(k_R, k_I) = \frac{1}{2\pi} \int_{-\infty}^{\infty} d\xi \int_{0}^{\infty} d\eta \, e^{2ik_R\xi-4ik_Rk_I\eta} \mu_2^+(\xi, \eta, 0, k_R, k_I),
\]

(3.32)

where the functions \( \phi_{1,2}^- \) and \( H \) are defined by equations (3.15) and (3.12) respectively.

**Proof** Differentiating equation (3.3) according to the definition (2.36) of the d-bar
derivative, we find the following expression:
\[
\frac{\partial \mu_1^\pm}{\partial k} = \frac{1}{2\pi} \left( \int_{-\infty}^{0} dl + \int_{2k_R}^{\infty} dl \right) \int_{-\infty}^{\infty} d\xi \int_{0}^{\infty} d\eta e^{-i(\xi - x) + i(l + 2k)(\eta - y)} q \frac{\partial \mu_1^\pm}{\partial k} \\
+ \frac{1}{2\pi} \left( \int_{-\infty}^{0} dl + \int_{-2k_R}^{\infty} dl \right) \int_{-\infty}^{\infty} d\xi \int_{y}^{\infty} d\eta e^{-i(\xi - x) + i(l + 2k)(\eta - y)} q \frac{\partial \mu_1^\pm}{\partial k}
\]

This expression can be written as an integral equation for \( \partial \mu_1^\pm / \partial k \):
\[
\frac{\partial \mu_1^\pm}{\partial k} = \frac{1}{2\pi} \left( \int_{-\infty}^{0} dl + \int_{2k_R}^{\infty} dl \right) \int_{-\infty}^{\infty} d\xi \int_{0}^{\infty} d\eta e^{-i(\xi - x) + i(l + 2k)(\eta - y)} q \frac{\partial \mu_1^\pm}{\partial k} \\
+ \frac{1}{2\pi} \left( \int_{-\infty}^{0} dl + \int_{-2k_R}^{\infty} dl \right) \int_{-\infty}^{\infty} d\xi \int_{y}^{\infty} d\eta e^{-i(\xi - x) + i(l + 2k)(\eta - y)} q \frac{\partial \mu_1^\pm}{\partial k}
\]

where \( \Gamma_1^\pm(t, k_R, k_I) \) is defined by
\[
\Gamma_1^\pm(t, k_R, k_I) = \frac{1}{2\pi} \int_{-\infty}^{\infty} d\xi \int_{0}^{\infty} d\eta e^{2i k_R \xi - 4i k_R k_I \eta} q \mu_1^\pm
\]

Using the identity \( (3.37) \), we can write equation \( (3.34) \) in the following form:
\[
\Gamma_1^\pm(t, k_R, k_I) = \frac{1}{2\pi} \int_{-\infty}^{\infty} d\xi \int_{-\infty}^{\infty} d\eta e^{2i k_R \xi - 4i k_R k_I \eta} q \mu_1^\pm
\]

where \( \mathcal{H} \) denotes the Heaviside function.
Then, equation (3.36) can be written in the form

\[ \partial_{\mu} + \frac{1}{\sqrt{-g}} \int_{-\infty}^{\infty} d\xi \int_{0}^{\infty} d\eta \, e^{2ik_{R}\xi} \phi_{1}^{\pm} = \right. \]

\[ = \int_{-\infty}^{\infty} d\xi \int_{0}^{\infty} d\eta \, e^{2ik_{R}\xi} \phi_{1}^{\pm} \left. \right] \] 

dropping the prime, equation (3.38) becomes

Hence, equation (3.35) implies that

\[ \partial_{\mu} + \frac{1}{\sqrt{-g}} \int_{-\infty}^{\infty} d\xi \int_{0}^{\infty} d\eta \, e^{2ik_{R}\xi} \phi_{1}^{\pm} \]

The global relation (3.20) for \( l = -2k_{R} \) yields

\[ \int_{-\infty}^{\infty} d\xi \int_{0}^{\infty} d\eta \, e^{2ik_{R}\xi} \phi_{1}^{\pm} = \]

\[ = \int_{-\infty}^{\infty} d\xi \int_{0}^{\infty} d\eta \, e^{2ik_{R}\xi} + \frac{1}{\sqrt{-g}} \int_{-\infty}^{\infty} d\xi \int_{0}^{\infty} d\eta \, e^{2ik_{R}\xi} \phi_{1}^{\pm} \]

Let us introduce the notations

\[ \mathcal{M}_{1}^{\pm}(x, y, t, k_{R}, l_{I}) = \frac{e^{2ik_{R}x - 4ik_{R}y(i + l + 2k)(y - \eta)} qM_{1}^{\pm}(x, y, t, k_{R}, l_{I})} {\gamma_{1}^{\pm}(k_{R}, l_{I})} \]

and

\[ \mathcal{F}_{1}^{\pm}(x, y, t, k_{R}, l_{I}) = \mathcal{M}_{1}^{\pm}(x, 0, t, k_{R}, l_{I}) \]

Then, equation (3.36) can be written in the form

\[ \mathcal{M}_{1}^{\pm} = 1 + \frac{1}{2\pi} \left( \int_{-\infty}^{0} d\xi \int_{0}^{\infty} d\eta \, e^{-i(l(2-k)(\xi - \eta)) + (l + 2k) + 4ik_{R}k_{l_{I}}(\eta - \eta)} qM_{1}^{\pm} \right) \]

\[ + \int_{-\infty}^{\infty} d\xi \left\{ \int_{0}^{\pi} e^{-i((2-k)(\xi - \eta)) - (l + 2k + 4ik_{R}k_{l_{I}})(\eta - \eta)} H(\xi, \tau, k_{R}, l_{I}) \right\} \]

\[ - \frac{1}{2\pi} \int_{0}^{2\pi} dt \int_{-\infty}^{\infty} d\xi \int_{0}^{\infty} d\eta \, e^{-i(l(2-k)(\xi - \eta)) + (l + 2k) + 4ik_{R}k_{l_{I}}(\eta - \eta)} \]

Let \( l' = l + 2k_{R} \) in the integrals on the RHS of equation (3.38). Consequently,

\[ l(l + 2k) = l'(l' - 2k) - 4ik_{R}k_{l_{I}} \]

\[ il = il' - 2ik_{R} \]

\[ -4il(l^{2} + 3kl + 3k_{R}^{2}) = -4il'(l'^{2} + 3kl' + 3k_{R}^{2}) + 8ik_{R}(k_{R}^{2} - 3k_{l_{I}}^{2}) \]

Dropping the prime, equation (3.38) becomes

\[ \mathcal{M}_{1}^{\pm} = 1 + \frac{1}{2\pi} \left( \int_{-\infty}^{\infty} d\xi \int_{0}^{\infty} d\eta \, e^{-i((\xi - \eta)(l + 2k) + 4ik_{R}k_{l_{I}}(\eta - \eta))} qM_{1}^{\pm} \right) \]

\[ + \int_{-\infty}^{\infty} d\xi \left\{ \int_{0}^{\pi} e^{-i((\xi - \eta)(l + 2k) + 4ik_{R}k_{l_{I}}(\eta - \eta))} H(\xi, \tau, k, l - 2k_{R}) \right\} \]

\[ - \frac{1}{2\pi} \int_{0}^{2\pi} dt \int_{-\infty}^{\infty} d\xi \int_{0}^{\infty} d\eta \, e^{-i((\xi - \eta)(l + 2k) + 4ik_{R}k_{l_{I}}(\eta - \eta))} qM_{1}^{\pm}. \]
Employing the transformation $k \mapsto -\bar{k}$ in the definition of $H$, we find

$$H(\xi, \tau, l - 2k_R) \mapsto H(\xi, \tau, -\bar{k}, l + 2k_R) = H(\xi, \tau, k, l).$$

Introducing the notation

$$\mathcal{M}_1^{\pm} = \mathcal{M}_1^{\pm}(x, y, t, -k_R, k_I),$$

equation becomes:

$$\mathcal{M}_1^{\pm} = 1 + \frac{1}{2\pi} \left( \int_{-\infty}^{-2k_R} dl + \int_{0}^{\infty} dl \right) \int_{-\infty}^{\infty} d\xi \int_{0}^{y} d\eta e^{-i((\xi - x) + l((\tau - t) + 2k_R)^2)q} \mathcal{M}_1^{\pm}$$

$$+ \frac{1}{2\pi} \left( \int_{-\infty}^{-2k_R} dl + \int_{0}^{\infty} dl \right) \int_{-\infty}^{\infty} d\xi \int_{0}^{\infty} d\tau \int_{0}^{t} d\tau' e^{-i((\xi - x) - l((\tau - t) - 2k_R)^2)q} H(\xi, \tau, k, l) \mathcal{X}_1^{\pm}$$

$$- \frac{1}{2\pi} \left( \int_{-\infty}^{-2k_R} dl + \int_{0}^{\infty} dl \right) \int_{-\infty}^{\infty} d\xi \int_{0}^{\infty} d\eta e^{-i((\xi - x) + l((\tau - t) + 2k_R)^2)q} \mathcal{M}_1^{\pm}.$$

Thus, it follows that this equation is identical with equation hence, assuming that the solution is unique, it follows that

$$\mathcal{M}_1^{\pm}(x, y, t, -k_R, k_I) = \mu_2^{\pm}(x, y, t, k_R, k_I),$$

or, equivalently,

$$\mathcal{M}_1^{\pm}(x, y, t, k_R, k_I) = \mu_2^{\pm}(x, y, t, -k_R, k_I).$$

Therefore, using the definition for the d-bar derivative of $\mu_1^{\pm}$. In a similar way, we can derive the expression for the d-bar derivative of $\mu_2^{\pm}$. 

In order to show that $\mu$ is continuous across the imaginary $k$-axis, we evaluate the expressions and at $k_R = 0$ and then subtract the resulting equations:

$$\left( \mu_1^{\pm} - \mu_2^{\pm} \right)_{k_R = 0} = \frac{1}{2\pi} \left( \int_{-\infty}^{\infty} dl \int_{-\infty}^{\infty} d\xi \int_{0}^{y} d\eta e^{-i((\xi - x) + l((\tau - t) + 2k_R)^2)q} \left( \mu_1^{\pm} - \mu_2^{\pm} \right) \right)_{k_R = 0}$$

$$+ \frac{1}{2\pi} \left( \int_{-\infty}^{\infty} dl \int_{-\infty}^{\infty} d\xi \int_{0}^{\infty} d\tau \int_{0}^{t} d\tau' e^{-i((\xi - x) - l((\tau - t) - 2k_R)^2)q} H(\xi, \tau, k, l) \left( \mu_1^{\pm} - \mu_2^{\pm} \right) \right)_{k_R = 0}.$$

This equation evaluated at $y = 0$ implies

$$\left( \phi_1^{\pm} - \phi_2^{\pm} \right)_{k_R = 0} =$$

$$\frac{1}{2\pi} \left( \int_{-\infty}^{\infty} dl \int_{-\infty}^{\infty} d\xi \int_{0}^{t} d\tau e^{-i((\xi - x) - l((\tau - t) - 2k_R)^2)q} H(\xi, \tau, k, l) \left( \phi_1^{\pm} - \phi_2^{\pm} \right) \right)_{k_R = 0};$$

hence, assuming uniqueness we find $\left( \phi_1^{\pm} - \phi_2^{\pm} \right)_{k_R = 0} = 0$.

Then, it follows that $\mu_1^{\pm} - \mu_2^{\pm}$ satisfies a homogeneous integral equation, hence under the assumption of uniqueness,

$$\mu_1^{\pm}(x, y, t, 0, k_I) = \mu_2^{\pm}(x, y, t, 0, k_I).$$

Next, we compute the jump of $\mu$ across the real $k$-axis.
Proposition 3.4. (The jumps across the real $k$-axis) Define the functions $\mu_1^\pm$ and $\mu_2^\pm$, by equation (3.2), (3.3) and (3.4). These functions satisfy the following discontinuity relations across the real $k$-axis:

\[
\Delta \mu_1(x, y, t, k_R) = \int_{-\infty}^{0} d\lambda \chi_2(k_R, \lambda) \left( e_\lambda \mu_2^+ \right)(x, y, t, k_R, \lambda)
\]
\[
+ \int_{-2k_R}^{0} d\lambda \chi_1(k_R, \lambda) \left( e_\lambda \mu_1^+ \right)(x, y, t, k_R, \lambda), \quad k_R \leq 0, \quad (3.41)
\]
\[
\Delta \mu_2(x, y, t, k_R) = \int_{-\infty}^{-2k_R} d\lambda \psi_2(k_R, \lambda) \left( e_\lambda \mu_2^+ \right)(x, y, t, k_R, \lambda)
\]
\[
+ \int_{0}^{1} d\lambda \psi_1(k_R, \lambda) \left( e_\lambda \mu_1^+ \right)(x, y, t, k_R, \lambda), \quad k_R \geq 0, \quad (3.42)
\]

where $\Delta \mu_{1,2}$ are defined by equation (3.22), and

\[
\tilde{\mu}_j(x, y, t, k_R, \lambda) := \mu_j(x, y, t, -k_R - \frac{\lambda}{2} \frac{i\lambda}{2} t), \quad j = 1, 2, \quad \lambda \in \mathbb{R}, \quad (3.43)
\]
\[
e_\lambda(x, y, t, k_R, \lambda) := e^{-i\lambda(\lambda+2k_R)k_R - 4\lambda(\lambda+\lambda+3k_R^2)k_R - 8i\lambda^2 t}. \quad (3.44)
\]

The functions $\chi_2$, $\chi_1$, $\psi_2$ and $\psi_1$ are the solutions of the following systems of Volterra integral equations:

\[
\chi_2(k_R, \lambda) = \int_{-\infty}^{\lambda} d\lambda \chi_2(k_R, l) r_2(k_R, l, -2k_R - \lambda)
\]
\[
- \int_{-2k_R}^{\lambda} d\lambda \chi_1(k_R, l) r_1(k_R, \lambda, -2k_R - \lambda) = p_1(k_R, -2k_R - \lambda), \quad k_R \leq 0, \quad \lambda \leq 0, \quad (3.45a)
\]
\[
\chi_1(k_R, \lambda) = \int_{-\infty}^{-2k_R - \lambda} d\lambda \chi_2(k_R, l) r_2(k_R, l, -2k_R - \lambda)
\]
\[
- \int^{\lambda}_{\lambda} d\lambda \chi_1(k_R, l) r_1(k_R, \lambda, -2k_R - \lambda) = p_1(k_R, -2k_R - \lambda), \quad k_R \leq 0, \quad \lambda \geq -2k_R \quad (3.45b)
\]

and

\[
\psi_2(k_R, \lambda) = \int_{-\infty}^{\lambda} d\lambda \psi_2(k_R, l) r_2(k_R, l, -2k_R - \lambda)
\]
\[
+ \int_{0}^{-2k_R - \lambda} d\lambda \psi_1(k_R, l) r_1(k_R, \lambda, -2k_R - \lambda) = p_1(k_R, -2k_R - \lambda), \quad k_R \geq 0, \quad \lambda \leq -2k_R, \quad (3.46a)
\]
\[
\psi_1(k_R, \lambda) = \int_{-\infty}^{-2k_R - \lambda} d\lambda \psi_2(k_R, l) r_2(k_R, l, -2k_R - \lambda)
\]
\[
+ \int_{0}^{\lambda} d\lambda \psi_1(k_R, l) r_1(k_R, \lambda, -2k_R - \lambda) = p_1(k_R, -2k_R - \lambda), \quad k_R \geq 0, \quad \lambda \leq 0, \quad (3.46b)
\]
with \( r_2, r_1 \) and \( p_1 \) defined by
\[
\begin{align*}
  r_2(k_R, \lambda, l) &= \frac{1}{2\pi} \int_{-\infty}^{\infty} d\xi \int_0^\infty d\eta \, e^{-i\xi + \frac{i}{4l(1+2k_R)}(\eta-y)} q_0(\xi, \eta) \left( e_{\lambda \mu_2^+} \right)(\xi, \eta, 0, k_R, \lambda), \\
  r_1(k_R, \lambda, l) &= \frac{1}{2\pi} \int_{-\infty}^{\infty} d\xi \int_0^\infty d\eta \, e^{-i\xi + \frac{i}{4l(1+2k_R)}(\eta-y)} q_0(\xi, \eta) \left( e_{\lambda \mu_1^+} \right)(\xi, \eta, 0, k_R, \lambda), \\
  p_1(k_R, l) &= \frac{1}{2\pi} \int_{-\infty}^{\infty} d\xi \int_0^T d\tau \, e^{-i\xi - \frac{i}{4l(1+2k_R)}(\tau-t)} H(\xi, \tau, k_R, l) \phi_1(\xi, \tau, k_R, 0),
\end{align*}
\]
(3.47) (3.48) (3.49)

and \( h \) given by equation (3.6).

**Proof** Evaluating equations (3.47) at \( k_I = 0 \) and subtracting the resulting expressions yields the following equation for \( \Delta \mu_1 \):
\[
\begin{align*}
  \Delta \mu_1 &= \frac{1}{2\pi} \left( \int_{-\infty}^{0} d\xi \int_{\infty}^{\infty} d\eta \, e^{-i(\xi - 2k_R)(\eta-y)} q \Delta \mu_1 \\
  &+ \frac{1}{2\pi} \left( \int_{-\infty}^{0} d\xi \int_{-\infty}^{\infty} d\eta \, e^{-i(\xi - 2k_R)(\eta-y)} q \Delta \mu_1 \right) \bigg|_{\xi = 0} \right) \\
  &+ \frac{1}{2\pi} \left( \int_{-\infty}^{0} d\xi \int_{-\infty}^{\infty} d\eta \, e^{-i(\xi - 2k_R)(\eta-y)} q \Delta \mu_1 \right) \bigg|_{\xi = 0} \bigg|_{\xi = 0} \\
  &+ \frac{1}{2\pi} \left( \int_{-\infty}^{0} d\xi \int_{\infty}^{\infty} d\eta \, e^{-i(\xi - 2k_R)(\eta-y)} q \Delta \mu_1 \right) \bigg|_{\xi = 0},
\end{align*}
\]
(3.50)

Furthermore, using the identity (2.33), we can rewrite this expression in the following form:
\[
\begin{align*}
  \Delta \mu_1 &= \frac{1}{2\pi} \left( \int_{-\infty}^{0} d\xi \int_{\infty}^{\infty} d\eta \, e^{-i(\xi - 2k_R)(\eta-y)} q \Delta \mu_1 \right) \\
  &+ \frac{1}{2\pi} \left( \int_{-\infty}^{0} d\xi \int_{-\infty}^{\infty} d\eta \, e^{-i(\xi - 2k_R)(\eta-y)} q \Delta \mu_1 \right) \bigg|_{\xi = 0} \bigg|_{\xi = 0} \\
  &+ \frac{1}{2\pi} \left( \int_{-\infty}^{0} d\xi \int_{\infty}^{\infty} d\eta \, e^{-i(\xi - 2k_R)(\eta-y)} q \Delta \mu_1 \right) \bigg|_{\xi = 0},
\end{align*}
\]
(3.50)

In what follows, by analysing the Lax pair, we will construct an equation similar to equation (3.50). This equation will be satisfied by an appropriate combination of the functions \( \mu_1^+ \) and \( \mu_2^+ \). Therefore, assuming uniqueness, the solution \( \Delta \mu_1 \) of equation (3.50) equals the above combination.

Consider the Fourier transform pair (3.77), but now let \( l = s - 2k_R \). This transformation will allow us, after applying a suitable change of variables, to split the exponential terms into two parts: one which will match the exponentials on the RHS of equation (3.50) and one which will be independent of \( l \):
\[
  \begin{align*}
  \hat{\mu}(l, y, t, k_R, k_I) \bigg|_{l = s - 2k_R} &= \int_{-\infty}^{\infty} dx \, e^{i(s-2k_R)x} \left( \mu(x, y, t, k_R, k_I) - 1 \right), \quad s \in \mathbb{R}, \ k_R \in \mathbb{R} \\
  \mu(x, y, t, k_R, k_I) &= 1 + \frac{1}{2\pi} \int_{-\infty}^{\infty} ds \, e^{i(s-2k_R)x} \hat{\mu}(l, y, t, k_R, k_I) \bigg|_{l = s - 2k_R}, \quad k_R \in \mathbb{R}.
\end{align*}
\]
(3.51a) (3.51b)
We now follow a similar approach to the one presented in section 3.1: applying the transform (3.51a) on the Lax equation (1.6a), we find
\[ \left( \hat{\mu}_y + (s - 2kR) (s + 2i k) \hat{\mu} \right) \bigg|_{l=s-2kR} = \int_{-\infty}^{\infty} dx \: e^{-i(s-2kR)x} q \mu. \] (3.52)

Using the change of variables
\[ \begin{aligned}
  k_R &\rightarrow -k_R - \frac{\lambda}{2} \\
  k_l &\rightarrow \frac{i\lambda}{2}
\end{aligned} \]
\[ \Rightarrow \begin{aligned}
  k &\rightarrow -k_R - \lambda, \quad \lambda \in \mathbb{R},
\end{aligned} \]

equation (3.52) becomes:
\[ \left( \hat{\mu}_y + (s + 2kR + \lambda) (s - \lambda) \hat{\mu} \right) \bigg|_{l=s+2kR+\lambda} = \int_{-\infty}^{\infty} dx \: e^{-i(s+2kR+\lambda)x} q mu. \]

with \( \hat{\mu} \) defined by equation (3.43). Hence,
\[ \left( e^{(s+2kR+\lambda)(s-\lambda)y} \hat{\mu} \right) \bigg|_{l=s+2kR+\lambda} = e^{(s+2kR+\lambda)(s-\lambda)y} \hat{q} \mu \bigg|_{l=s+2kR+\lambda}, \]

where
\[ \hat{q} \mu \bigg|_{l=s+2kR+\lambda} = \int_{-\infty}^{\infty} dx \: e^{-i(s+2kR+\lambda)x} q \hat{\mu}. \]

We solve this equation by integrating with respect to \( y \) either from \( y = 0 \) or from \( y = \infty \):
\[
\begin{aligned}
  \hat{\mu} \bigg|_{l=s+2kR+\lambda} &\rightarrow \begin{cases}
  \int_{0}^{y} \! \! d\eta \: e^{(s+2kR+\lambda)(s-\lambda)(\eta-y)} \hat{q} \mu \bigg|_{l=s+2kR+\lambda} + e^{-(s+2kR+\lambda)(s-\lambda)y} \hat{q} \mu \bigg|_{l=s+2kR+\lambda} \\
  - \int_{y}^{\infty} \! \! d\eta \: e^{(s+2kR+\lambda)(s-\lambda)(\eta-y)} \hat{q} \mu \bigg|_{l=s+2kR+\lambda} 
\end{cases},
\end{aligned} \]

(3.54)

where we have assumed that \( \hat{\mu} \rightarrow 0 \) as \( y \rightarrow \infty \).

We are interested in obtaining an expression for the difference \( \Delta \mu_1 \), thus we assume that \( k_R \leq 0 \). Also, since \( \mu_1 \) must be bounded for \( k_R \leq 0 \), the exponential involved in equation (3.54) must be bounded and hence, we need to control the sign of \( (s + 2kR + \lambda)(s-\lambda)(\eta-y) \). We consider two cases for \( \lambda \), namely \( \lambda \leq -k_R \) or \( \lambda \geq -k_R \). According to the definition (3.52), the distinction between \( \mu_1 \) and \( \mu_2 \) is made on the basis of the sign of the real part of \( k \). However, the transformation (3.53) implies that \( k = -k_R - \lambda \in \mathbb{R} \), hence \( \mu = \mu_2 \) in the first case, whereas \( \mu = \mu_1 \) in the second case.

Inverting the expression (3.54) (by making use of equation (3.51b)), recalling the definition (3.43) and relabeling \( s \) to \( l \), we find the following equations:
\[
\begin{aligned}
  \hat{\mu}_2 &= 1 + \frac{1}{2\pi} \left( \int_{-\infty}^{\lambda} \! \! dl + \int_{-2kR-\lambda}^{\lambda} \! \! dl \right) \int_{-\infty}^{\infty} \! \! d\xi \int_{0}^{y} \! \! d\eta \: e^{(l+2kR+\lambda)(\xi-x)+(l+2kR+\lambda)(l-\lambda)(\eta-y)} \hat{q} \mu_2 \\
  &+ \frac{1}{2\pi} \left( \int_{-\infty}^{\lambda} \! \! dl + \int_{-2kR-\lambda}^{\lambda} \! \! dl \right) \int_{-\infty}^{\infty} \! \! d\xi \int_{y}^{\infty} \! \! d\eta \: e^{-(l+2kR+\lambda)(\xi-x)-(l+2kR+\lambda)(l-\lambda)(\eta-y)} \hat{q} \mu_2 \\
  &- \frac{1}{2\pi} \int_{-2kR-\lambda}^{\lambda} \! \! dl \int_{-\infty}^{\infty} \! \! d\xi \int_{0}^{y} \! \! d\eta \: e^{-(l+2kR+\lambda)(\xi-x)+(l+2kR+\lambda)(l-\lambda)(\eta-y)} \hat{q} \mu_2, 
\end{aligned} \]
which is valid for $\lambda \leq -k_R$, $k_R \leq 0$, and
\[
\tilde{\mu}_1 = 1 + \frac{1}{2\pi} \left( \int_{-\infty}^{-2k_R-\lambda} dl + \int_{-\lambda}^{\infty} dl \right) \int_{-\infty}^{0} \int_{0}^{y} d\eta e^{-i(l+2k_R+\lambda)(\xi-x)+i(l+2k_R+\lambda)(\eta-y)} q \tilde{\mu}_1 + \\
+ \frac{1}{2\pi} \left( \int_{-\infty}^{-2k_R-\lambda} dl + \int_{-\lambda}^{\infty} dl \right) \int_{-\infty}^{0} \int_{0}^{y} d\eta e^{-i(l+2k_R+\lambda)(\xi-x)+(l+2k_R+\lambda)(\eta-y)} \frac{q}{\phi_1} \\
- \frac{1}{2\pi} \int_{-2k_R-\lambda}^{\lambda} dl \int_{-\infty}^{0} \int_{0}^{y} d\eta e^{-i(l+2k_R+\lambda)(\xi-x)+(l+2k_R+\lambda)(\eta-y)} q \tilde{\mu}_1,
\]
which is valid for $\lambda \geq -k_R$, $k_R \leq 0$.

Following the approach used in section 3.1, we can employ the second Lax equation (1.6b) in order to eliminate the dependence in $y$ from the second term on the RHS of the above expressions. This yields the following equations:
\[
e_{\lambda} \tilde{\mu}_2^+ = e_{\lambda} + \frac{1}{2\pi} \left( \int_{-\infty}^{-2k_R-\lambda} dl + \int_{-\lambda}^{\infty} dl \right) \int_{-\infty}^{0} \int_{0}^{y} d\eta e^{-i(l+2k_R+\lambda)(\eta-y)} q e_{\lambda} \tilde{\mu}_2^+ + \\
+ \frac{1}{2\pi} \left( \int_{-\infty}^{-2k_R-\lambda} dl + \int_{-\lambda}^{\infty} dl \right) \int_{-\infty}^{0} \int_{0}^{y} d\eta e^{-i(l+2k_R+\lambda)(\eta-y)} q e_{\lambda} \tilde{\mu}_1^+ + \\
- \frac{1}{2\pi} \int_{-2k_R-\lambda}^{\lambda} dl \int_{-\infty}^{0} \int_{0}^{y} d\eta e^{-i(l+2k_R+\lambda)(\eta-y)} q e_{\lambda} \tilde{\mu}_1^+,
\]
which is valid for $\lambda \leq -k_R$, $k_R \leq 0$, and
e_{\lambda} \tilde{\mu}_1^+ = e_{\lambda} + \frac{1}{2\pi} \left( \int_{-\infty}^{-2k_R-\lambda} dl + \int_{-\lambda}^{\infty} dl \right) \int_{-\infty}^{0} \int_{0}^{y} d\eta e^{-i(l+2k_R+\lambda)(\eta-y)} q e_{\lambda} \tilde{\mu}_1^+ + \\
+ \frac{1}{2\pi} \left( \int_{-\infty}^{-2k_R-\lambda} dl + \int_{-\lambda}^{\infty} dl \right) \int_{-\infty}^{0} \int_{0}^{y} d\eta e^{-i(l+2k_R+\lambda)(\eta-y)} q e_{\lambda} \tilde{\mu}_1 + \\
- \frac{1}{2\pi} \int_{-2k_R-\lambda}^{\lambda} dl \int_{-\infty}^{0} \int_{0}^{y} d\eta e^{-i(l+2k_R+\lambda)(\eta-y)} q e_{\lambda} \tilde{\mu}_1^+,
\]
which is valid for $\lambda \geq -k_R$, $k_R \leq 0$, where $e_{\lambda}$ is defined by equation (3.44), $\tilde{H}$ is given by
\[
\tilde{H}(x, t, k_R, l) := H(x, t, -k_R - \lambda, l + 2k_R + \lambda)
\]
and $H$ is defined by equation (3.6).

In order for $\tilde{\mu}_{1,2}$ to satisfy an equation similar to equation (3.56), we need to split the integrals with respect to $l$. However, in order to ensure that the resulting integrals remain bounded, we impose two additional conditions: in equation (3.56), where $\lambda \leq -k_R$, we actually require the stronger condition that $\lambda \leq 0$, and in equation (3.56), where $\lambda \geq -k_R$, we demand the stronger condition that $\lambda \geq -2k_R$.

Under these new restrictions, the expressions (3.55) and (3.56) become
\[
e_{\lambda} \tilde{\mu}_2^+ = e_{\lambda} - R_2 + \\
+ \frac{1}{2\pi} \left( \int_{-\infty}^{0} dl + \int_{-\lambda}^{\infty} dl \right) \int_{-\infty}^{0} \int_{0}^{y} d\eta e^{-i(l+2k_R+\lambda)(\eta-y)} q e_{\lambda} \tilde{\mu}_2^+ + \\
+ \frac{1}{2\pi} \left( \int_{-\infty}^{0} dl + \int_{-\lambda}^{\infty} dl \right) \int_{-\infty}^{0} \int_{0}^{y} d\eta e^{-i(l+2k_R+\lambda)(\eta-y)} q e_{\lambda} \tilde{\mu}_1^+ + \\
- \frac{1}{2\pi} \int_{0}^{-2k_R} dl \int_{-\infty}^{0} \int_{0}^{y} d\eta e^{-i(l+2k_R+\lambda)(\eta-y)} q e_{\lambda} \tilde{\mu}_2^+,
\]
(3.58)
which is valid for $\lambda \geq -2k_R, k_R \leq 0$.

Concerning $R_2$, we have

$$\lambda \leq l \leq 0 \leq -2k_R \quad \text{or} \quad 0 \leq -2k_R \leq l \leq -2k_R - \lambda.$$  

Thus, the exponentials $e^{-t(l+2k_R)y}$ and $e^{(l-\lambda)(l+2k_R+\lambda)\eta}$, which are involved in the definition of $R_2$, are bounded.

Concerning $R_1$, we have

$$-2k_R - \lambda \leq l \leq 0 \leq -2k_R \quad \text{or} \quad 0 \leq -2k_R \leq l \leq \lambda.$$

Thus, the exponentials $e^{-t(l+2k_R)y}$ and $e^{(l-\lambda)(l+2k_R+\lambda)\eta}$, which are involved in the definition of $R_1$, are also bounded.

The expressions for $R_2$ and $R_1$ can be rewritten in the following form:

$$R_2 = \frac{1}{2\pi} \left\{ \int_{-\infty}^{\infty} dl \left[ \int_{-2k_R}^{0} dl e^{t(l+2k_R)y+4il(t^2+3k_R^2l+3k_R^2)t} \right] e^{ilx(l+2k_R)y+4il(t^2+3k_R^2l+3k_R^2)t} q e_\lambda \tilde{\mu}_2^+ + \int_{-\infty}^{\infty} d\xi \int_{0}^{t} d\tau e^{-i\xi-l(l+2k_R)\eta-4il(t^2+3k_R^2l+3k_R^2)\tau} \tilde{H} e_\lambda |_{\eta=0} \tilde{\phi}_2^+ \right\} \quad (3.62)$$
and

\[ R_1 = \frac{1}{2\pi} \left( \int_{-2k_R-\lambda}^{0} dl + \int_{-2k_R}^{\lambda} dl \right) e^{i\xi - l(l+2k_R)y + 4il(l^2+3k_Rl+3k_R^2)t} \times \left\{ \int_{-\infty}^{\infty} d\xi \int_{0}^{\infty} d\eta \ e^{-il\xi+l(l+2k_R)\eta-4il(l^2+3k_Rl+3k_R^2)\tau} q e_{\lambda} \tilde{\mu}_j^+ \right. \\
+ \left. \int_{-\infty}^{\infty} d\xi \int_{0}^{t} d\tau \ e^{-il\xi-4il(l^2+3k_Rl+3k_R^2)\tau} H e_{\lambda}|_{\eta=0} \phi_j^+ \right\}. \tag{3.63} \]

Applying the transformation [3.53] to the identity (3.20), and then replacing \( l \) by \( l + \lambda + 2k_R \), we find the following identity:

\[ \int_{-\infty}^{\infty} d\xi \int_{0}^{\infty} d\eta \ e^{-il\xi+l(l+2k_R)\eta} q_0 \left( e_{\lambda} \tilde{\mu}_j^+ \right) |_{l=0} = \int_{-\infty}^{\infty} d\xi \int_{0}^{\infty} d\eta \ e^{-il\xi+l(l+2k_R)\eta-4il(l^2+3k_Rl+3k_R^2)\tau} q e_{\lambda} \tilde{\mu}_j^+ \\
+ \int_{0}^{t} d\tau \int_{-\infty}^{\infty} d\xi \ e^{-il\xi-4il(l^2+3k_Rl+3k_R^2)\tau} H e_{\lambda}|_{\eta=0} \phi_j^+ \ , \quad j = 1, 2. \]

Note that if \( l \) satisfies the restrictions imposed in the domain of \( R_1 \) and \( R_2 \) then the exponential \( e^{(l-\lambda)(l+2k_R+\lambda)\theta} \) is bounded, hence the global relation (3.20) is satisfied. Thus, employing the global relation in the expressions (3.62) and (3.63), we find

\[ R_2(x, y, t, k_R, \lambda) = \left( \int_{\lambda}^{0} dl + \int_{-2k_R-\lambda}^{-2k_R} dl \right) E(x, y, t, k_R, l) r_2(k_R, \lambda, l), \quad \lambda \leq 0, \tag{3.64} \]

and

\[ R_1(x, y, t, k_R, \lambda) = \left( \int_{-2k_R-\lambda}^{-2k_R} dl + \int_{\lambda}^{0} dl \right) E(x, y, t, k_R, l) r_1(k_R, \lambda, l), \quad \lambda \geq -2k_R, \tag{3.65} \]

where

\[ E(x, y, t, k, l) := e^{ilx-l(l+2k)y+4il(l^2+3kl+3k^2)t}, \tag{3.66} \]

and \( r_2 \) and \( r_1 \) are defined by equations (3.47) and (3.48).

In summary, we have obtained two integral equations for \( \tilde{\mu}_j^+ \) and \( \tilde{\mu}_j^1 \), namely equations (3.58) and (3.59), with the quantities \( R_2 \) and \( R_1 \) given by equations (3.64) and (3.65), respectively.

Next, we multiply equation (3.58) by \( \chi_2 \) and integrate with respect to \( \lambda \) from \(-\infty\) to \( 0 \); similarly, we multiply equation (3.59) by \( \chi_1 \) and integrate with respect to \( \lambda \) from \(-2k_R\) to \( \infty \) (the precise form of the functions \( \chi_1 \) and \( \chi_2 \) will be determined later). Adding the two resulting expressions and defining \( S_1 \) by

\[ S_1(x, y, t, k_R) = \int_{-\infty}^{0} d\lambda \chi_2(k_R, \lambda) e_{\lambda} \tilde{\mu}_j^+ + \int_{-2k_R}^{\infty} d\lambda \chi_1(k_R, \lambda) e_{\lambda} \tilde{\mu}_j^1, \tag{3.67} \]
where \( \tilde{E} \)

In order to identify equation (3.68) with equation (3.50), the functions \( \chi \) implies that we find:

\[
\int_0^\infty d\xi \int_0^l d\eta e^{-i\xi(x-y) + il(l+2k_R)(\eta-y)} q S_1
\]

\[
+ \frac{1}{2\pi} \left( \int_{-\infty}^0 dl + \int_{-2k_R}^\infty dl \right) \int_{-\infty}^\infty d\xi \int_0^l d\eta e^{-i\xi(x-y) + il(l+2k_R)(\eta-y)} q \tilde{H} S_1 |_{\eta=0}
\]

\[
- \frac{1}{2\pi} \int_{-2k_R}^\infty dl \int_{-\infty}^\infty d\xi \int_y^\infty d\eta e^{-i\xi(x-y) + il(l+2k_R)(\eta-y)} q S_1
\]

\[+ \mathcal{F}_1(x, y, t, k_R), \tag{3.68} \]

where \( \tilde{H} \) is defined by equation (3.57), and

\[
\mathcal{F}_1(x, y, t, k_R) = \int_{-\infty}^0 d\lambda \chi_2(k_R, \lambda) (e_\lambda - R_2) + \int_{-2k_R}^\infty d\lambda \chi_1(k_R, \lambda) (e_\lambda - R_1).
\]

In order to identify equation (3.68) with equation (3.50), the functions \( \chi_1 \) and \( \chi_2 \) must be defined in such way that equations (3.68) and (3.50) have the same forcing, i.e. so that

\[
\mathcal{F}_1(x, y, t, k_R) = \left( \int_{-\infty}^0 dl + \int_{-2k_R}^\infty dl \right) E(x, y, t, k_R, l) p_1(k_R, l),
\]

where \( E \) is defined by equation (3.60) and \( p_1 \) is given by equation (3.49). This implies that \( \chi_1 \) and \( \chi_2 \) must satisfy the following condition:

\[
\int_{-\infty}^0 d\lambda \chi_2(k_R, \lambda) e_\lambda(x, y, t, k_R, l) - \int_{-\infty}^0 d\lambda \chi_2(k_R, \lambda) \int_\lambda^0 dl E(x, y, t, k_R, l) r_2(k_R, \lambda, l)
\]

\[
- \int_{-\infty}^0 d\lambda \chi_2(k_R, \lambda) \int_{-2k_R}^{-\lambda} dl E(x, y, t, k_R, l) r_2(k_R, \lambda, l)
\]

\[
+ \int_{-2k_R}^\infty d\lambda \chi_1(k_R, \lambda) e_\lambda(x, y, t, k_R, l)
\]

\[
- \int_{-2k_R}^\infty d\lambda \chi_1(k_R, \lambda) \int_{-2k_R}^{-\lambda} dl E(x, y, t, k_R, l) r_1(k_R, \lambda, l)
\]

\[
- \int_{-2k_R}^\infty d\lambda \chi_1(k_R, \lambda) \int_{-2k_R}^\lambda dl E(x, y, t, k_R, l) r_1(k_R, \lambda, l) =
\]

\[
= \int_{-\infty}^0 d\lambda E(x, y, t, k_R, l) p_1(k_R, \lambda) + \int_{-2k_R}^\infty d\lambda E(x, y, t, k_R, \lambda) p_1(k_R, \lambda), \tag{3.69} \]

where \( l \) has been relabeled as \( \lambda \) on the RHS.

Our aim is to obtain appropriate integral equations for \( \chi_1 \) and \( \chi_2 \). In this respect, we note that we can interchange the order of integration with respect to \( \lambda \) and \( l \):

\[
\int_{-\infty}^0 d\lambda \int_\chi^0 dl = \int_{-\infty}^0 dl \int_{-\infty}^l d\lambda,
\]

\[
\int_{-\infty}^0 d\lambda \int_{-2k_R}^{l-\lambda} dl = \int_{-\infty}^0 dl \int_{-2k_R}^{l-\lambda} d\lambda,
\]

\[
\int_{-2k_R}^\infty d\lambda \int_{-2k_R}^{l-\lambda} dl = \int_{-\infty}^0 dl \int_{-2k_R}^{l-\lambda} d\lambda,
\]

and

\[
\int_{-2k_R}^\infty d\lambda \int_{-2k_R}^\lambda dl = \int_{-2k_R}^\infty dl \int_{-2k_R}^\lambda d\lambda.
\]
Therefore, equation (3.69) becomes:
\[
\int_{-\infty}^{0} dl \chi_2(kR, l) e_i(x, y, t, kR, l) - \int_{-\infty}^{0} dl E(x, y, t, kR, l) \int_{-\infty}^{l} d\lambda \chi_2(kR, \lambda) r_2(kR, \lambda, l) \\
- \int_{-2kR}^{\infty} dl E(x, y, t, kR, l) \int_{-\infty}^{-2kR-l} d\lambda \chi_2(kR, \lambda) r_2(kR, \lambda, l) \\
+ \int_{-2kR}^{\infty} dl \chi_1(kR, l) e_i(x, y, t, kR, l) - \int_{-\infty}^{0} dl E(x, y, t, kR, l) \int_{-2kR}^{\infty} d\lambda \chi_1(kR, \lambda) r_1(kR, \lambda, l) \\
- \int_{-2kR}^{\infty} dl E(x, y, t, kR, l) \int_{-\infty}^{\infty} d\lambda \chi_1(kR, \lambda) r_1(kR, \lambda, l) = \\
= \int_{-\infty}^{0} dl E(x, y, t, kR, l) p_1(kR, l) + \int_{-2kR}^{\infty} dl E(x, y, t, kR, l) p_1(kR, l).
\]
In addition, it follows from the definitions (3.44) and (3.66) of \( e_\lambda \) and \( E \), that
\[
E(x, y, t, kR, -\lambda - 2kR) = e_\lambda(x, y, t, kR, \lambda). \tag{3.70}
\]
Hence the transformation \( l \mapsto -2kR - l \) in the terms involving the exponential \( E \) yields
\[
\int_{-\infty}^{0} dl e_i(x, y, t, kR, l) \left\{ \chi_2(kR, l) - \int_{-\infty}^{l} d\lambda \chi_2(kR, \lambda) r_2(kR, \lambda, -2kR - l) \\
- \int_{-2kR}^{\infty} d\lambda \chi_1(kR, \lambda) r_1(kR, \lambda, -2kR - l) - p_1(kR, -2kR - l) \right\} \\
+ \int_{-2kR}^{\infty} dl e_i(x, y, t, kR, l) \left\{ \chi_1(kR, l) - \int_{-\infty}^{-2kR-l} d\lambda \chi_2(kR, \lambda) r_2(kR, \lambda, -2kR - l) \\
- \int_{-\infty}^{\infty} d\lambda \chi_1(kR, \lambda) r_1(kR, \lambda, -2kR - l) - p_1(kR, -2kR - l) \right\} = 0. \tag{3.71}
\]
This condition can be identically satisfied provided that we set both curly brackets
equal to zero, i.e. provided that
\[ \chi_2(k_R, \lambda) = \int_{-\infty}^{\lambda} d\lambda \chi_2(k_R, l) r_2(k_R, l, -2k_R - \lambda) - \int_{-2k_R - \lambda}^{\infty} d\lambda \chi_1(k_R, l) r_1(k_R, l, -2k_R - \lambda) = p_1(k_R, -2k_R - \lambda), \quad \lambda \leq 0 \]
and
\[ \chi_1(k_R, \lambda) = \int_{-\infty}^{-2k_R - \lambda} d\lambda \chi_2(k_R, l) r_2(k_R, l, -2k_R - \lambda) - \int_{-2k_R - \lambda}^{\infty} d\lambda \chi_1(k_R, l) r_1(k_R, l, -2k_R - \lambda) = p_1(k_R, -2k_R - \lambda), \quad \lambda \geq -2k_R, \]
which are equations (3.45a) and (3.45b) respectively.

Note that the restrictions on \( \lambda \) originate from equation (3.72); furthermore, these restrictions ensure that \( r_2 \) and \( r_1 \) are well defined, see equations (3.47) and (3.48).

Equations (3.46a) and (3.46b) can be derived in a similar way. \( \square \)

3.4 The spectral functions

Consider the initial-boundary value problem for the KPII equation (1.1), with the initial and the boundary values defined by equations (1.13a)-(1.13c). This problem is well posed provided that one of the two boundary values, (1.13b) or (1.13c), is known. It is then possible to obtain the unknown boundary value in terms of the initial condition and the given boundary condition via the global relation (3.20).

Now, we will define a map from the initial condition \( q_0 \) and from the boundary values \( g \) and \( h \) to the spectral functions of propositions 3.3 and 4.4:
\[ \{q_0(x, y), \ g(x, t), \ h(x, t)\} \mapsto \{\alpha_{1,2}(k_R, k_I), \beta_{1,2}(k_R, k_I), \chi_{1,2}(k_R, \lambda), \psi_{1,2}(k_R, \lambda)\}, \]
(3.72)
where \((x, y, t) \in \Omega, \ k_R \leq 0 \) for \( \{\alpha_{1,2}, \beta_{1,2}^+\} \) and \( k_R \geq 0 \) for \( \{\alpha_{2,2}, \beta_{2,2}^-\} \), \( k_I \geq 0 \) for \( \beta_{1,2}^+ \), \( k_I \leq 0 \) for \( \alpha_{1,2}, \beta_{1,2}^- \) and \( \lambda \in \mathbb{R} \).

1. \( q_0 \mapsto \{\rho_1^+(x, y, k_R, k_I), \rho_2^+(x, y, k_R, k_I)\} \), for \((x, y, t) \in \Omega \) and \( k_I \geq 0 \), where the functions \( \rho_1^+ \) and \( \rho_2^+ \) are defined in terms of \( q_0 \) via the following linear integral equations:
\[ \rho_1^+ = 1 + \frac{1}{2\pi} \left( \int_{-\infty}^{0} dl + \int_{-2k_R}^{0} dl \right) \int_{-\infty}^{\infty} d\xi \int_{0}^{y} d\eta e^{-il(\xi-x)+(l+2k)(\eta-y)} q_0 \rho_1^+ \]
\[ - \frac{1}{2\pi} \int_{0}^{-2k_R} dl \int_{-\infty}^{\infty} d\xi \int_{y}^{\infty} d\eta e^{-il(\xi-x)+(l+2k)(\eta-y)} q_0 \rho_1^+, \quad k_R \leq 0, \]
(3.73a)
\[ \rho_2^+ = 1 + \frac{1}{2\pi} \left( \int_{-\infty}^{-2k_R} dl + \int_{0}^{\infty} dl \right) \int_{-\infty}^{\infty} d\xi \int_{0}^{y} d\eta e^{-il(\xi-x)+(l+2k)(\eta-y)} q_0 \rho_2^+ \]
\[ - \frac{1}{2\pi} \int_{-2k_R}^{0} dl \int_{-\infty}^{\infty} d\xi \int_{y}^{\infty} d\eta e^{-il(\xi-x)+(l+2k)(\eta-y)} q_0 \rho_2^+, \quad k_R \geq 0. \]
(3.73b)
\[ \begin{align*}
\rho_1^- &= 1 + \frac{1}{2\pi} \left( \int_{-\infty}^{0} dl + \int_{-2kR}^{0} dl \right) \int_{-\infty}^{0} d\xi \int_{0}^{t} d\tau \, e^{-i(l(x-x) - \tau - 2kR)(\eta-y)} q_0 \rho_1^- \\
&- \frac{1}{2\pi} \left( \int_{-\infty}^{0} dl + \int_{-2kR}^{0} dl \right) \int_{-\infty}^{0} d\xi \int_{0}^{t} d\tau \, e^{-i(l(x-x) - \tau - 2kR)(\eta-y)} H \phi_1^- \\
&- \frac{1}{2\pi} \int_{0}^{-2kR} dl \int_{-\infty}^{0} d\xi \int_{0}^{t} d\tau \, e^{-i(l(x-x) - \tau - 2kR)(\eta-y)} q_0 \rho_1^- , \quad k_R \leq 0 ,
\end{align*} \]

and

\[ \begin{align*}
\rho_2^- &= 1 + \frac{1}{2\pi} \left( \int_{-\infty}^{0} dl + \int_{-2kR}^{0} dl \right) \int_{-\infty}^{0} d\xi \int_{0}^{t} d\tau \, e^{-i(l(x-x) - \tau - 2kR)(\eta-y)} q_0 \rho_2^- \\
&- \frac{1}{2\pi} \left( \int_{-\infty}^{0} dl + \int_{-2kR}^{0} dl \right) \int_{-\infty}^{0} d\xi \int_{0}^{t} d\tau \, e^{-i(l(x-x) - \tau - 2kR)(\eta-y)} H \phi_2^- \\
&- \frac{1}{2\pi} \int_{0}^{-2kR} dl \int_{-\infty}^{0} d\xi \int_{0}^{t} d\tau \, e^{-i(l(x-x) - \tau - 2kR)(\eta-y)} q_0 \rho_2^- , \quad k_R \geq 0 ,
\end{align*} \]

with \( H \) defined by equation (3.6).

The motivation for the above definitions emanates from proposition 3.1. Indeed, evaluating equations (3.3) and (3.4) at \( t = 0 \) and letting \( \mu_{1,2}^{+} = \rho_{1,2}^{-} \), we recover equations (3.73a) + (3.73b). Furthermore, applying the inverse Fourier transform (3.71) for \( \phi_{1,2}^{-} \) on equations (3.17) and (3.19), we find equations (3.75a) and (3.75b).
3. \( \{q_0, g, h\} \mapsto \{\alpha_{1,2}^{-1}(k_R, k_I), \beta_{1,2}^{+1}(k_R, k_I)\} \),
where the functions \( \alpha_{1,2}^{-1} \) and \( \beta_{1,2}^{+1} \) are defined by the equations:

\[
\alpha_{1}^{-1}(k_R, k_I) = \frac{1}{2\pi} \int_{-\infty}^{\infty} d\xi \int_{0}^{T} d\tau \, e^{2ikR\xi + 8ikR(k_R^2 - 4k_R^2)\tau} H(\xi, \tau, k, -2k_R)\phi_1^{-}, \\
\alpha_{2}^{-1}(k_R, k_I) = \frac{1}{2\pi} \int_{-\infty}^{\infty} d\xi \int_{0}^{T} d\tau \, e^{2ikR\xi + 8ikR(k_R^2 - 4k_R^2)\tau} H(\xi, \tau, k, -2k_R)\phi_2^{-}, \\
\beta_{1}^{+1}(k_R, k_I) = \frac{1}{2\pi} \int_{-\infty}^{\infty} d\xi \int_{0}^{T} d\eta \, e^{2ikR\xi - 4ikRk_I\eta} q_0 \rho_1^{+}, \\
\beta_{2}^{+1}(k_R, k_I) = \frac{1}{2\pi} \int_{-\infty}^{\infty} d\xi \int_{0}^{T} d\eta \, e^{2ikR\xi - 4ikRk_I\eta} q_0 \rho_2^{+}.
\]

(3.76a)

(3.76b)

(3.76c)

(3.76d)

4. \( \{q_0, g, h\} \mapsto \{r_{1,2}(k_R, \lambda, l), p_{1}(k_R, l)\} \), with \( l \in \mathbb{R} \),
where the functions \( r_{1,2} \) and \( p_1 \) are defined by the following equations:

\[
r_2(k_R, \lambda, l) = \frac{1}{2\pi} \int_{-\infty}^{\infty} d\xi \int_{0}^{\infty} d\eta \, e^{-i\xi \lambda + l(1 + 2k_R)\eta} q_0(\xi, \eta) \left( \epsilon_\lambda \tilde{\rho}_2^+ \right)(\xi, \eta, k_R, \lambda), \\
r_1(k_R, \lambda, l) = \frac{1}{2\pi} \int_{-\infty}^{\infty} d\xi \int_{0}^{\infty} d\eta \, e^{-i\xi \lambda + l(1 + 2k_R)\eta} q_0(\xi, \eta) \left( \epsilon_\lambda \tilde{\rho}_1^+ \right)(\xi, \eta, k_R, \lambda), \\
p_1(k_R, l) = \frac{1}{2\pi} \int_{-\infty}^{\infty} d\xi \int_{0}^{T} d\tau \, e^{-i\xi \lambda - 4il(1 + 3k_R)\tau} H(\xi, \tau, k_R, l)\phi_1^{-}(\xi, \tau, k_R, 0),
\]

(3.77a)

(3.77b)

(3.77c)

with \( \epsilon_\lambda \) given by equation \((3.44)\) and

\[
\tilde{\rho}_{1,2}(x, y, k_R, \lambda) = \rho_{1,2}(x, y, -k_R - \frac{\lambda}{2}, \frac{\lambda}{2}).
\]

5. \( \{r_{1,2}, p_1\} \mapsto \{\chi_{1,2}(k_R, \lambda), \psi_{1,2}(k_R, \lambda)\} \),
where the functions \( \chi_{1,2} \) and \( \psi_{1,2} \) are defined via the following integral equations:

\[
\chi_2(k_R, \lambda) = \int_{-\infty}^{\lambda} d\lambda_2 r_2(k_R, l, -2k_R - \lambda) \\
- \int_{-2k_R - \lambda}^{\infty} d\lambda_2 r_1(k_R, l, -2k_R - \lambda) = p_1(k_R, -2k_R - \lambda), \quad k_R \leq 0, \quad \lambda \leq 0,
\]

(3.78a)

\[
\chi_1(k_R, \lambda) = \int_{-\infty}^{-2k_R - \lambda} d\lambda_2 r_2(k_R, l, -2k_R - \lambda) \\
- \int_{\lambda}^{\infty} d\lambda_2 r_1(k_R, l, -2k_R - \lambda) = p_1(k_R, -2k_R - \lambda), \quad k_R \leq 0, \quad \lambda \geq -2k_R
\]

(3.78b)
and

\[ \psi_2(k_R, \lambda) + \int_{-\infty}^{\lambda} dl \psi_2(k_R, l) r_2(k_R, l, -2k_R - \lambda) + \int_{-2k_R - \lambda}^{0} dl \psi_1(k_R, l) r_1(k_R, l, -2k_R - \lambda) = p_1(k_R, -2k_R - \lambda), \quad k_R \geq 0, \quad \lambda \leq -2k_R. \]  
(3.79a)

\[ \psi_1(k_R, \lambda) + \int_{-\infty}^{-2k_R - \lambda} dl \psi_2(k_R, l) r_2(k_R, l, -2k_R - \lambda) + \int_{0}^{\lambda} dl \psi_1(k_R, l) r_1(k_R, l, -2k_R - \lambda) = p_1(k_R, -2k_R - \lambda), \quad k_R \geq 0, \quad \lambda \geq 0. \]  
(3.79b)

In summary, steps 1-5 provide the map (3.72) from \{q_0, g, h\} to the spectral functions.

As mentioned in the beginning of section 3.3, the function \( \mu \) satisfied Pompeiu’s formula (3.21). We notice that, under the definition (3.66) of the exponential \( E \), equations (3.41) and (3.42) for the discontinuities across the real \( k \)-axis, Pompeiu’s formula (2.35) yield the following expressions:

\[ \frac{\partial \mu^\pm_{k, R}}{\partial k} (x, y, t, k, \lambda) = E(x, y, t, k, -2k_R) \gamma^\pm_{1}(k, \lambda) \mu^\pm_{2}(x, y, t, -k, \lambda), \quad k_R \leq 0 \]

and

\[ \frac{\partial \mu^\pm_{k, R}}{\partial k} (x, y, t, k, \lambda) = -E(x, y, t, k, -2k_R) \gamma^\pm_{2}(k, \lambda) \mu^\pm_{1}(x, y, t, -k, \lambda), \quad k_R \geq 0. \]

Using these expressions for the d-bar derivatives, as well as equations (3.41) and (3.42) for the discontinuities across the real \( k \)-axis, Pompeiu’s formula (2.35) yield the following expressions:

\[ \mu(x, y, t, k, \lambda) = 1 + \frac{1}{2\pi} \int_{-\infty}^{0} \frac{dv_R}{\nu - k} \left[ \int_{v_R}^{\infty} d\nu \gamma^\pm_{2} (\nu, \nu) E(x, y, t, \nu, -2\nu_R) \mu^\pm_{1} (x, y, t, -\nu_R, \nu) \right] (x, y, t, \nu_R, \lambda) + \frac{1}{\pi} \int_{0}^{\infty} \frac{dv_R}{\nu - k} \left[ \int_{0}^{\infty} d\nu \gamma^\pm_{1} (\nu, \nu) E(x, y, t, \nu, -2\nu_R) \mu^\pm_{2} (x, y, t, -\nu_R, \nu) \right] (x, y, t, \nu_R, \lambda) \]

Using the transformation

\[ \nu_R + \frac{\lambda}{2} = \hat{\nu}_R \quad \text{and} \quad \frac{\lambda}{2} = \hat{\nu}_l, \]  
(3.81)

the second and the third terms on the RHS of equation (3.80) become

\[ \frac{1}{2\pi} \int_{-\infty}^{0} d\hat{\nu}_R \int_{-\hat{\nu}_R}^{0} d\hat{\nu}_l \frac{\gamma^\pm_{2} (\hat{\nu}_R - \hat{\nu}_l, 2\hat{\nu}_l)}{\hat{\nu}_R - \hat{\nu}_l - k} e_\lambda(x, y, t, \hat{\nu}_R - \hat{\nu}_l, 2\hat{\nu}_l) \mu^\pm_{2} (x, y, t, -\hat{\nu}_R, i\hat{\nu}_l) \]

\[ + \frac{1}{\pi} \int_{0}^{\infty} d\hat{\nu}_R \int_{-\hat{\nu}_R}^{0} d\hat{\nu}_l \frac{\gamma^\pm_{1} (\hat{\nu}_R - \hat{\nu}_l, 2\hat{\nu}_l)}{\hat{\nu}_R - \hat{\nu}_l - k} e_\lambda(x, y, t, \hat{\nu}_R - \hat{\nu}_l, 2\hat{\nu}_l) \mu^\pm_{1} (x, y, t, -\hat{\nu}_R, i\hat{\nu}_l). \]
Moreover, letting $\hat{\nu}_I = -i\tilde{\nu}_I$, we find

$$
\hat{\nu}_I \lambda \hat{\nu}_R = \nu_R \hat{\nu}_R \hat{\nu}_I - \hat{\nu}_R \nu_I \hat{\nu}_I - k e^\lambda(x,y,t,\hat{\nu}_R + i\hat{\nu}_I, -2i\hat{\nu}_R) \mu_+^2(x,y,t,\hat{\nu}_R, \hat{\nu}_I).
$$

The definitions (3.44) and (3.66) imply

$$
e^\lambda(x,y,t,\hat{\nu}_R + i\hat{\nu}_I, -2i\hat{\nu}_R) = E(x,y,t,\hat{\nu}_R + i\hat{\nu}_I, -2\hat{\nu}_R).
$$

Replacing the tilde by the hat and letting $\hat{\nu} = \nu_R + i\nu_I$, we can write the second and the third term as follows:

$$
\frac{1}{\pi} \int_{-\infty}^{0} d\hat{\nu}_R \int_{0}^{i\hat{\nu}_R} d\hat{\nu}_I \frac{1}{\nu - k} \chi_2(\hat{\nu}, -2i\hat{\nu}_I) E(x,y,t,\hat{\nu}, -2\hat{\nu}_R) \mu_2^+(x,y,t, -\hat{\nu}_R, \hat{\nu}_I)
$$

$$
- \frac{1}{\pi} \int_{0}^{\infty} d\hat{\nu}_R \int_{i\hat{\nu}_R}^{\infty} d\hat{\nu}_I \frac{1}{\nu - k} \chi_1(\hat{\nu}, -2i\hat{\nu}_I) E(x,y,t,\hat{\nu}, -2\hat{\nu}_R) \mu_1^+(x,y,t, -\hat{\nu}_R, \hat{\nu}_I).
$$

(3.82)

The same transformations applied on the fourth and the fifth term on the RHS of equation (3.80) yield

$$
\frac{1}{\pi} \int_{-\infty}^{0} d\hat{\nu}_R \int_{0}^{-i\hat{\nu}_R} d\hat{\nu}_I \frac{1}{\nu - k} \psi_2(\hat{\nu}, -2i\hat{\nu}_I) E(x,y,t,\hat{\nu}, -2\hat{\nu}_R) \mu_2^+(x,y,t, -\hat{\nu}_R, \hat{\nu}_I)
$$

$$
- \frac{1}{\pi} \int_{0}^{\infty} d\hat{\nu}_R \int_{i\hat{\nu}_R}^{\infty} d\hat{\nu}_I \frac{1}{\nu - k} \psi_1(\hat{\nu}, -2i\hat{\nu}_I) E(x,y,t,\hat{\nu}, -2\hat{\nu}_R) \mu_1^+(x,y,t, -\hat{\nu}_R, \hat{\nu}_I).
$$

(3.83)

Dropping the hats and inserting equations (3.82) and (3.83) into equation (3.80),
we conclude that

\[
\mu(x, y, t, k_R, k_I) = 
1 + \frac{1}{\pi} \int_{-\infty}^{\infty} d\nu_R \int_{-\infty}^{\infty} \frac{d\nu_I}{\nu - k} \chi_2(\nu, -2i\nu_I) E(x, y, t, \nu, -2\nu_R) \mu_2^+(x, y, t, -\nu_R, \nu_I) 
- \frac{1}{\pi} \int_{0}^{\infty} d\nu_R \int_{\nu - k}^{\infty} \chi_1(\nu, -2i\nu_I) E(x, y, t, \nu, -2\nu_R) \mu_1^+(x, y, t, -\nu_R, \nu_I) 
+ \frac{1}{\pi} \int_{-\infty}^{\infty} d\nu_R \int_{-\infty}^{\infty} \frac{d\nu_I}{\nu - k} \psi_2(\nu, -2i\nu_I) E(x, y, t, \nu, -2\nu_R) \mu_2^+(x, y, t, -\nu_R, \nu_I) 
- \frac{1}{\pi} \int_{0}^{\infty} d\nu_R \int_{\nu - k}^{\infty} \psi_1(\nu, -2i\nu_I) E(x, y, t, \nu, -2\nu_R) \mu_1^+(x, y, t, -\nu_R, \nu_I) 
+ \frac{1}{\pi} \int_{0}^{\infty} d\nu_R \int_{0}^{\infty} \frac{d\nu_I}{\nu - k} \gamma_2^+(\nu_R, \nu_I) E(x, y, t, \nu, -2\nu_R) \mu_1^+(x, y, t, -\nu_R, \nu_I) 
- \frac{1}{\pi} \int_{-\infty}^{\infty} d\nu_R \int_{-\infty}^{\infty} \frac{d\nu_I}{\nu - k} \gamma_1^+(\nu_R, \nu_I) E(x, y, t, \nu, -2\nu_R) \mu_2^+(x, y, t, -\nu_R, \nu_I). 
\]

Proposition 3.5. Assume that \( q(x, y, t) \) satisfies an IBV problem for the KPII equation \( (1.4) \) with given initial condition \( q(x, y, 0) = q_0(x, y) \). Let

\[
q(x, 0, t) = g(x, t), \quad q_y(x, 0, t) = h(x, t).
\]

Assume that the following global relation is valid:

\[
\int_{-\infty}^{\infty} d\xi \int_{0}^{\infty} d\eta e^{-i\xi(1+2k)\eta} q_0(\xi, \eta) \rho_j^- - \int_{-\infty}^{\infty} d\xi \int_{0}^{\infty} d\eta e^{-i\xi(1+2k)\eta} q(\xi, \eta, t) \mu_j^- = 0, \quad j = 1, 2, \quad k \in \mathbb{C}, \quad l(1+2k) \leq 0,
\]

where \( \mu_j^- \) are bounded \( \forall k \in \mathbb{C}, \rho_j^- \), \( \phi_j^- \) are defined by equations \( (3.74), (3.75) \) and \( H \) is given by \( (3.76) \), i.e. by

\[
H(x, t, k, l) = 3 \left[ g_x(x, t) - 2i(l+k)g(x, t) - \partial_x^{-1} h(x, t) \right].
\]

Given \( q_0(x, y), g(x, t) \) and \( h(x, t) \), define the functions \( \gamma_{1,2}^+(k_R, k_I) \) by

\[
\gamma_1^+(k_R, k_I) = \beta_1^+(k_R, k_I), \quad k_R \leq 0, \quad k_I \geq 0,
\gamma_1^-(k_R, k_I) = \beta_1^-(k_R, k_I) - \alpha_1^-(k_R, k_I), \quad k_R \leq 0, \quad k_I \leq 0,
\gamma_2^+(k_R, k_I) = \beta_2^+(k_R, k_I), \quad k_R \geq 0, \quad k_I \geq 0,
\gamma_2^-(k_R, k_I) = \beta_2^-(k_R, k_I) - \alpha_2^-(k_R, k_I), \quad k_R \geq 0, \quad k_I \leq 0.
\]
where the functions $\alpha_{1,2}(k_R, k_I)$, $\beta_{1,2}(k_R, k_I)$ are given by

$$
\alpha_1^-(k_R, k_I) = \frac{1}{2\pi} \int_{-\infty}^{\infty} d\xi \int_0^T dt \, e^{2i k_R \xi + 8i k_R (k_R^2 - 3k_I^2) t} H(\xi, t, k, -2k_R) \phi_1^-(\xi, t, k_R, k_I),
$$

$$
\beta_1^+(k_R, k_I) = \frac{1}{2\pi} \int_{-\infty}^{\infty} d\xi \int_0^T dt \, e^{2i k_R \xi - 4i k_R k_I \eta} \eta_0(\xi, \eta) \rho_1^+(\xi, \eta, k_R, k_I),
$$

$$
\alpha_2^-(k_R, k_I) = \frac{1}{2\pi} \int_{-\infty}^{\infty} d\xi \int_0^T dt \, e^{2i k_R \xi + 8i k_R (k_R^2 - 3k_I^2) t} H(\xi, t, k, -2k_R) \phi_2^-(\xi, t, k_R, k_I),
$$

$$
\beta_2^+(k_R, k_I) = \frac{1}{2\pi} \int_{-\infty}^{\infty} d\xi \int_0^T dt \, e^{2i k_R \xi - 4i k_R k_I \eta} \eta_0(\xi, \eta) \rho_2^+(\xi, \eta, k_R, k_I).
$$

Assume that the following systems of Volterra integral equations have a unique solution for the functions $\chi_{1,2}(k_R, \lambda)$ and $\psi_{1,2}(k_R, \lambda)$ respectively:

$$
\chi_2(k_R, \lambda) - \int_{-\infty}^{\lambda} dl \chi_2(k_R, l) r_2(k_R, l, -2k_R - \lambda)
$$

$$
- \int_{-2k_R - \lambda}^{\infty} dl \chi_1(k_R, l) r_1(k_R, l, -2k_R - \lambda) = p_1(k_R, -2k_R - \lambda), \quad k_R \leq 0, \quad \lambda \leq 0,
$$

$$
\chi_1(k_R, \lambda) - \int_{-\infty}^{-2k_R - \lambda} dl \chi_2(k_R, l) r_2(k_R, l, -2k_R - \lambda)
$$

$$
- \int_{\lambda}^{\infty} dl \chi_1(k_R, l) r_1(k_R, l, -2k_R - \lambda) = p_1(k_R, -2k_R - \lambda), \quad k_R \leq 0, \quad \lambda \geq -2k_R
$$

and

$$
\psi_2(k_R, \lambda) + \int_{-\infty}^{\lambda} dl \psi_2(k_R, l) r_2(k_R, l, -2k_R - \lambda)
$$

$$
+ \int_{0}^{\lambda} \int_{-2k_R - \lambda}^{\infty} dl \psi_1(k_R, l) r_1(k_R, l, -2k_R - \lambda) = p_1(k_R, -2k_R - \lambda), \quad k_R \geq 0, \quad \lambda \leq -2k_R,
$$

$$
\psi_1(k_R, \lambda) + \int_{-\infty}^{-2k_R - \lambda} dl \psi_2(k_R, l) r_2(k_R, l, -2k_R - \lambda)
$$

$$
+ \int_{0}^{\lambda} \int_{-\infty}^{0} dl \psi_1(k_R, l) r_1(k_R, l, -2k_R - \lambda) = p_1(k_R, -2k_R - \lambda), \quad k_R \geq 0, \quad \lambda \geq 0,
$$

where

$$
r_1(k_R, \lambda, l) = \frac{1}{2\pi} \int_{-\infty}^{\infty} d\xi \int_0^T dt \, e^{-i \xi l + i(l+2k_R) t} \eta_0(\xi, \eta) (e_\lambda \tilde{\rho}_1^+) (\xi, \eta, k_R, \lambda), \quad \lambda \geq -2k_R,
$$

$$
r_2(k_R, \lambda, l) = \frac{1}{2\pi} \int_{-\infty}^{\infty} d\xi \int_0^T dt \, e^{-i \xi l + i(l+2k_R) t} \eta_0(\xi, \eta) (e_\lambda \tilde{\rho}_2^+) (\xi, \eta, k_R, \lambda), \quad \lambda \geq 0,
$$

$$
p_1(k_R, l) = \frac{1}{2\pi} \int_{-\infty}^{\infty} d\xi \int_0^T dt \, e^{-i \xi l - 4i(l+2k_R+3k_I^2) t} H(\xi, t, k_R, l) \phi_1^- (\xi, t, k_R, 0),
$$

and $e_\lambda$ is given by equation (3.70).

Given $\{\chi_{1,2}, \psi_{1,2}, \gamma_{1,2}^\pm\}$, define $\mu$ as the solution of equation (3.84), where

$$
\mu(x, y, t, k_R, k_I) = \begin{cases}
\mu_1^+(x, y, t, k_R, k_I), & k_R \leq 0, \ k_I \geq 0,
\mu_1^-(x, y, t, k_R, k_I), & k_R \leq 0, \ k_I \leq 0,
\mu_2^-(x, y, t, k_R, k_I), & k_R \geq 0, \ k_I \leq 0,
\mu_2^+(x, y, t, k_R, k_I), & k_R \geq 0, \ k_I \geq 0,
\end{cases}
$$
and assume that equation (3.34) has a unique solution.

Define $q(x, y, t)$ by

$$q(x, y, t) = -2i \lim_{k \to \infty} \left[ k \mu_2(x, y, t, kR, kI) \right].$$

Then $q(x, y, t)$ solves the KPII equation (1.4).

**Remark 3.1** By differentiating equation (3.84) with respect to $x$ we can write an integral representation for the solution $q$:

$$\frac{i \pi}{2} q = -\int_{-\infty}^{0} d\nu_R \int_{0}^{i \nu_R} d\nu_I \chi_2(\nu, -2i\nu_I) \left( E(x, y, t, \nu, -2\nu_R) \mu_1^+(x, y, t, -\nu_R, \nu_I) \right)_{x}$$

$$+ \int_{0}^{\infty} d\nu_R \int_{\nu_R}^{\infty} d\nu_I \chi_1(\nu, -2i\nu_I) \left( E(x, y, t, \nu, -2\nu_R) \mu_1^+(x, y, t, -\nu_R, \nu_I) \right)_{x}$$

$$- \int_{-\infty}^{0} d\nu_R \int_{-\infty}^{-i \nu_R} d\nu_I \psi_2(\nu, -2i\nu_I) \left( E(x, y, t, \nu, -2\nu_R) \mu_1^+(x, y, t, -\nu_R, \nu_I) \right)_{x}$$

$$+ \int_{0}^{\infty} d\nu_R \int_{0}^{i \nu_R} d\nu_I \psi_1(\nu, -2i\nu_I) \left( E(x, y, t, \nu, -2\nu_R) \mu_1^+(x, y, t, -\nu_R, \nu_I) \right)_{x}$$

$$- \int_{0}^{\infty} d\nu_R \int_{0}^{\nu_R} d\nu_I \alpha_2^+(\nu_R, \nu_I) \left( E(x, y, t, \nu, -2\nu_R) \mu_1^+(x, y, t, -\nu_R, \nu_I) \right)_{x}$$

$$+ \int_{-\infty}^{0} d\nu_R \int_{-\infty}^{0} d\nu_I \alpha_1^+(\nu_R, \nu_I) \left( E(x, y, t, \nu, -2\nu_R) \mu_1^+(x, y, t, -\nu_R, \nu_I) \right)_{x}$$

**Remark 3.2** (The case of zero initial condition)

Consider the special case $q_0(x, y) = 0$. Then, equations (3.45a)-(3.46b) imply that the functions $\chi_{1,2}$ and $\psi_{1,2}$ are given explicitly by

$$\chi_2(kR, \lambda) = \chi_1(kR, \lambda) = \psi_2(kR, \lambda) = \psi_1(kR, \lambda) = p_1(kR, -2kR - \lambda),$$

with $p_1$ defined by equation (3.49).

Also, equations (3.30) and (3.32) yield

$$\beta_{1,2}^\pm(kR, kI) = \beta_{2,2}^\pm(kR, kI) = 0,$$

thus, according to equations (3.28) - (3.25):

$$\gamma_{1,2}^+(kR, kI) = \gamma_{2,2}^+(kR, kI) = 0$$

and

$$\gamma_1^-(kR, kI) = -\alpha_{1,2}^-(kR, kI), \quad \gamma_2^-(kR, kI) = -\alpha_{2,2}^-(kR, kI),$$

where $\alpha_{1,2}$ are defined by equations (3.29) and (3.31).
Hence, equation \(3.84\) for \(\mu\) becomes significantly simpler, i.e.

\[
\mu(x, y, t, k_R, k_I) = \\
1 + \frac{1}{\pi} \int_{-\infty}^{0} d\nu_R \int_{0}^{\infty} d\nu_I \frac{d\nu_I}{\nu - k} p_1(\nu, -2\nu R) E(x, y, t, \nu, -2\nu R) \mu_2^+(x, y, t, -\nu R, \nu_I) \\
- \frac{1}{\pi} \int_{0}^{\infty} d\nu_R \int_{\nu_R}^{\infty} d\nu_I \frac{d\nu_I}{\nu - k} p_1(\nu, -2\nu R) E(x, y, t, \nu, -2\nu R) \mu_1^+(x, y, t, -\nu R, \nu_I) \\
+ \frac{1}{\pi} \int_{-\infty}^{0} d\nu_R \int_{0}^{\infty} d\nu_I \frac{d\nu_I}{\nu - k} p_1(\nu, -2\nu R) E(x, y, t, \nu, -2\nu R) \mu_1^+(x, y, t, -\nu R, \nu_I) \\
- \frac{1}{\pi} \int_{0}^{\infty} d\nu_R \int_{\nu_R}^{\infty} d\nu_I \frac{d\nu_I}{\nu - k} p_1(\nu, -2\nu R) E(x, y, t, \nu, -2\nu R) \mu_2^-(x, y, t, -\nu R, \nu_I) \\
+ \frac{1}{\pi} \int_{-\infty}^{0} d\nu_R \int_{0}^{\infty} d\nu_I \frac{d\nu_I}{\nu - k} \alpha^-_2(\nu_R, \nu_I) E(x, y, t, \nu, -2\nu R) \mu_2^-(x, y, t, -\nu R, \nu_I),
\]

where \(E(x, y, t, \nu, \nu_I) = e^{i\xi x - t(4k + 4\nu + 3k^2)} \), the functions \(p_1\) and \(\alpha^-_{1,2}\) are given by

\[
\begin{align*}
p_1(k_R, l) &= \frac{1}{2\pi} \int_{-\infty}^{\infty} d\xi \int_{0}^{T} d\tau e^{-i\xi \tau - 4i(l^2 + 3k^2)\tau} H(\xi, \tau, k_R, l) \phi^-_1(\xi, \tau, k_R, 0), \\
\alpha^-_1(k_R, k_I) &= \frac{1}{2\pi} \int_{-\infty}^{\infty} d\xi \int_{0}^{T} d\tau e^{2ik_R \xi + 8i(k^2 - 3k^2)\tau} H(\xi, \tau, k, -2k_R) \phi^-_1(\xi, \tau, k_R, k_I), \\
\alpha^-_2(k_R, k_I) &= \frac{1}{2\pi} \int_{-\infty}^{\infty} d\xi \int_{0}^{T} d\tau e^{2ik_R \xi + 8i(k^2 - 3k^2)\tau} H(\xi, \tau, k, -2k_R) \phi^-_2(\xi, \tau, k_R, k_I),
\end{align*}
\]

and \(\phi^-_{1,2}\) are defined by equations \(3.75\).

### 3.5 The linear limit

Suppose now that \(q\) is small, i.e. let

\[
q(x, y, t) = \varepsilon u(x, y, t) + O(\varepsilon^2), \quad \varepsilon \to 0.
\]

Then, the \(O(\varepsilon)\) term of the nonlinear KPII equation \((1.4)\) yields a linear equation which, as expected, is the linearised KP equation:

\[
u_t + u_{xxx} + 3\partial_x^{-1}u_{yy} = 0.
\]

The following integral representation of the solution of an IBV problem was derived in section \(2\)

\[
u = \frac{2}{\pi} \left( \int_{0}^{\infty} d\nu_R \int_{-\infty}^{0} d\nu_I \right) \int_{-\infty}^{\infty} d\xi \int_{-\infty}^{\infty} d\eta E(x - \xi, y - \eta, t, \nu, -2\nu R) u_0 \\
- \frac{2}{\pi} \int_{0}^{\infty} d\nu_R \left( \int_{-\infty}^{0} d\nu_I + \int_{\nu_R}^{\infty} d\nu_I \right) \int_{-\infty}^{\infty} d\xi \int_{0}^{T} d\tau E(x - \xi, y, t - \tau, \nu, -2\nu R) 3\nu_R (2\nu_R v - \partial_x^{-1} w) \\
+ \frac{2}{\pi} \int_{0}^{\infty} d\nu_R \left( \int_{-\infty}^{0} d\nu_I + \int_{\nu_R}^{\infty} d\nu_I \right) \int_{-\infty}^{\infty} d\xi \int_{0}^{T} d\tau E(x - \xi, y, t - \tau, \nu, -2\nu R) 3\nu_R (2\nu_R v - \partial_x^{-1} w),
\]

where

\[
u_0(x, y) = u(x, y, 0), \quad v(x, t) = u(x, 0, t), \quad w(x, t) = u_0(x, 0, t).
\]
For the nonlinear problem, equations (3.49) and (3.51) suggest that, in the linear limit, \( \mu = 1 + O(\varepsilon) \).

Moreover, equations (3.47), (3.48) and (3.49) imply that

\[
    r_2 = O(\varepsilon), \quad r_1 = O(\varepsilon), \quad p_1 = O(\varepsilon),
\]

and then, equations (3.45a) and (3.45b) suggest that \( \chi_2 = O(\varepsilon) \) and \( \chi_1 = O(\varepsilon) \).

In fact, we can write

\[
    \mu = 1 + \varepsilon M + O(\varepsilon^2), \quad p_1 = \varepsilon P_1 + O(\varepsilon^2), \quad \chi_2 = \varepsilon X_2 + O(\varepsilon^2), \quad \chi_1 = \varepsilon X_1 + O(\varepsilon^2),
\]

for some functions \( M, P_1, X_2 \) and \( X_1 \), independent of \( \varepsilon \). Then, equation (3.49) yields

\[
    P_1(k_R, l) = \frac{1}{2\pi} \int_{-\infty}^{\infty} d\xi \int_{0}^{T} d\tau \ E(-\xi, 0, -\tau, k_R, l) \left[ \psi_1(\xi, \tau) - 2i(l+k_R)\nu(\xi, \tau) - \partial_{\xi}^{-1}w(\xi, \tau) \right].
\]

Integrating by parts, we find

\[
    P_1(k_R, l) = \frac{1}{2\pi} \int_{-\infty}^{\infty} d\xi \int_{0}^{T} d\tau \ E(-\xi, 0, -\tau, k_R, l) \left[ -i(l+2k_R)\nu(\xi, \tau) - \partial_{\xi}^{-1}w(\xi, \tau) \right],
\]

therefore, equations (3.45a) and (3.45b) yield

\[
    X_2(k_R, \lambda) = X_1(k_R, \lambda) = P_1(k_R, -2k_R - \lambda). \tag{3.86}
\]

A similar analysis for \( \psi_1 \) and \( \psi_2 \) implies

\[
    \Psi_2(k_R, \lambda) = \Psi_1(k_R, \lambda) = P_1(k_R, -2k_R - \lambda).
\]

Furthermore, equations (3.29) - (3.32) suggest that \( A_{1,2} = A \) and \( B_{1,2} = B \), where

\[
    B(k_R, k_I) = \frac{1}{2\pi} \int_{-\infty}^{\infty} d\xi \int_{0}^{\infty} d\eta \ E(-\xi, -\eta, 0, k, -2k_R)u_0(\xi, \eta), \tag{3.87}
\]

\[
    A(k_R, k_I) = \frac{1}{2\pi} \int_{-\infty}^{\infty} d\xi \int_{0}^{T} d\tau \ E(-\xi, 0, -\tau, k, -2k_R) \left[ 2k_I\nu(\xi, \tau) - \partial_{\xi}^{-1}w(\xi, \tau) \right]. \tag{3.88}
\]

Hence it follows from the definitions (3.29) and (3.27) that \( \gamma_1^+ = \gamma_2^+ \) and \( \gamma_1^- = \gamma_2^- \).

Then, the \( O(\varepsilon) \) term of equation (3.84) yields

\[
    M = \frac{1}{\pi} \left( \int_{0}^{\infty} d\nu_R \int_{-\infty}^{-i\infty} d\nu_I - \int_{0}^{\infty} d\nu_R \int_{-\infty}^{i\infty} d\nu_I \right) \frac{1}{\nu - k} E(x, y, t, \nu, -2\nu_R) P_1(\nu, -2\nu_R) + \frac{1}{\pi} \left( \int_{0}^{\infty} d\nu_R \int_{-\infty}^{\infty} d\nu_I - \int_{-\infty}^{0} d\nu_R \int_{-\infty}^{\infty} d\nu_I \right) \frac{1}{\nu - k} E(x, y, t, \nu, -2\nu_R) B(\nu_R, \nu_I) - \frac{1}{\pi} \left( \int_{0}^{\infty} d\nu_R \int_{-\infty}^{0} d\nu_I - \int_{-\infty}^{0} d\nu_R \int_{-\infty}^{0} d\nu_I \right) \frac{1}{\nu - k} E(x, y, t, \nu, -2\nu_R) A(\nu_R, \nu_I). \tag{3.89}
\]

Employing the formulae (3.86), (3.87) and (3.88) into equation (3.89), and using the definition

\[
    u(x, y, t) = -2i \lim_{k \to \infty} \left[ kM_x(x, y, t, k_R, k_I) \right],
\]

we recover the expression (3.56).
4 Conclusion

It is shown in [11] that there exists a much simpler derivation for the integral representation of \( q \) for the linearised KPII equation than the one presented in section 2. However, this simpler approach cannot be “nonlinearised”. On the other hand, the approach presented in section 2 contains all necessary conceptual steps needed for the solution of KPII. However, the analysis of KPII is technically quite involved. In particular, in order to formulate proposition (3.5), it is necessary to compute both the d-bar derivatives \( \partial \mu_j^\pm / \partial \bar{k} \) and the jumps \( (\mu_j^+ - \mu_j^-) \), \( j = 1, 2 \); the latter computation is quite complicated, as was also the case for the analogous computation is DSII [1].

We note that an additional novelty of the IBV problems in 2+1, as opposed to IBV problems in 1+1, is that now the global relation plays an even more important role. Namely, it is necessary in order to express the jumps of \( \mu \) across the real \( k \)-axis in terms of the initial and the boundary values.

Several problems remain open, in particular:

1. For a well posed problem, either \( g \) or \( h \) are prescribed as boundary conditions; on the other hand, the solution obtained in proposition (3.5) depends on both \( g \) and \( h \). Thus, in order for this solution to be effective it is necessary to use the global relation to eliminate the unknown boundary value. For the linearised KPII, this is achieved in [11]; the analogous problem for the KPII remains open. In this connection we note that until recently, for problems in 1+1, it was not possible to express the spectral functions directly in terms of the given boundary conditions, but it was necessary to first obtain the unknown boundary values, i.e. to determine the so-called Dirichlet to Neumann map (see [13]-[15]). However, in a recent breakthrough, it has been shown that for the nonlinear Schrödinger (NLS) equation on the half-line it is possible to express the spectral functions directly in terms of the given initial and boundary conditions. The question of whether this new approach can be extended to equations in 2+1 remains open.

2. For the initial-value problem of the KPII, the linear integral equation analogous to (3.84) admits a unique solution for \( \mu \) for real initial conditions. This is due to the existence of a so-called “vanishing lemma”, which is based on the theory of generalised analytic functions of Vekua. The question of whether there exists an analogous result for equation (3.84) remains open.

3. The spectral functions are defined in terms of linear integral equations. The question of existence and uniqueness for these equations remains open. Actually, it is expected that these equations do possess homogeneous solutions which will give rise to coherent structures.

4. In spite of the fact that the representation of \( q \) involves both \( g \) and \( h \), it should still be possible to obtain effective formulae for the large \( t \) asymptotics of the solution. (for equations in 1+1 this has been achieved by the Deift-Zhou approach [16], [17])

5. The new method is particularly effective for a class of boundary conditions called linearisable. In this case, it is possible to express the spectral functions directly in terms of the given initial and boundary conditions using only algebraic manipulations, see for example [18]-[23]. The question of identifying lineasable boundary conditions for the KPII remains open.

6. For KPII the formalism presented here involves the crucial assumption that several linear integral equations have a unique solution. In spite of the fact
that these equations are of Fredholm type, it is not difficult to establish uniqueness under the assumption of sufficiently “small data”. However, the elimination of the “small norm” assumption is a formidable task (see also remark 3 above).

References

[1] A. S. Fokas, The Davey-Stewartson Equation on the Half-Plane, Comm. Math. Phys. 289, 957-993 (2009).
[2] A. S. Fokas and M. J. Ablowitz, On the Inverse Scattering of the Time Dependent Equation and the Associated KPI Equation, Stud. Appl. Math. 69, 211-228 (1983).
[3] M. J. Ablowitz, D. BarYaacov and A. S. Fokas, On the Inverse Scattering Transform for the Kadomtsev-Petviashvili Equation, Stud. Appl. Math. 69, 135-143 (1983).
[4] C. S. Gardner, J. M. Greene, M. D. Kruskal, and R. M. Miura, Method for Solving the Korteweg-de Vries Equation, Phys. Rev. Lett. 19, 1095-1097 (1967).
[5] M. Boiti, J.J.-P. Leon, F. Pempinelli, Spectral Transform and Orthogonality Relations for the Kadomtsev-Petviashvili Equation, Physics Letters A, 141, 96-100 (1989).
[6] A. S. Fokas and L. Y. Sung, On the Solvability of the N-Wave, the Davey-Stewartson and the Kadomtsev-Petviashvili Equation, Inverse Problems 8, 673-708 (1992).
[7] A. S. Fokas, The Kadomtsev-Petviashvili Equation Revisited and Integrability in 4+2 and 3+1, Stud. Appl. Math. 122, 347-359 (2009).
[8] R. Beals and R.R. Coifman, Linear Spectral Problem, Nonlinear Equations and the $\bar{\partial}$ Method, Inverse Problem 5, 87-130 (1989).
[9] A. S. Fokas A Unified Transform Method for Solving Linear and Certain Nonlinear PDEs, Proc. R. Soc. Lond. A 453, 1411-1443 (1997).
[10] A. S. Fokas and B. Pelloni, The Solution of Certain Initial-Boundary Value Problems for the Linearized Korteweg-De Vries Equation, Proc. Math. Phys. and Eng. Sciences 454, 645-657 (1998).
[11] A. S. Fokas, A New Transform Method for Evolution PDEs, IMA J. Appl. Math. 67, 1-32 (2002).
[12] A. S. Fokas, A Unified Approach to Boundary Value Problems, SIAM (2008).
[13] A. Boutet de Monvel, A. S. Fokas and D. Shepelsky, The Analysis of the Global Relation for the Nonlinear Schrödinger Equation on the Half-Line, Lett. Math. Phys. 65, 199-212 (2003).
[14] A. S. Fokas, A Generalised Dirichlet to Neumann Map for Certain Nonlinear Evolution PDEs, Comm. Pure Appl. Math. LVIII, 639-670 (2005).
[15] P. A. Trehanne, A. S. Fokas, The Generalized Dirichlet to Neumann map for the KdV Equation on the Half-Line, J. Nonlinear Science 18, 191-217 (2008).
[16] P. Deift and X. Zhou, A Steepest Descent Method for Oscillatory Riemann-Hilbert Problems, Bull.Amer.Math.Soc. (N.S.) 20, 119-123 (1992).

[17] P. Deift and X. Zhou, A Steepest Descent Method for Oscillatory Riemann-Hilbert Problems, Asymptotics for the mKdV, Ann. of Math. (2) 137, 245-338, (1993).

[18] A. S. Fokas, Integrable Nonlinear Evolution Equations on the Half-Line, Comm. Math. Phys. 230, 1-39 (2002).

[19] A. S. Fokas, Linearizable Initial-Boundary Value Problems for the sine-Gordon Equation on the Half-Line, Nonlinearity 17, 1521-1534 (2004).

[20] A. S. Fokas, A. R. Its and L. Y. Sung, The Nonlinear Schrödinger Equation on the Half-Line, Nonlinearity 18, 1771-1822 (2005).

[21] A. S. Fokas and J. Lenells, Explicit Soliton Asymptotics for the Korteweg-de-Vries Equation on the Half-Line, Nonlinearity 23, 937-976 (2010).

[22] A. S. Fokas and B. Pelloni, Boundary Value Problems for the Elliptic sine-Gordon Equation in a Semi-Strip (submitted).

[23] A. S. Fokas and J. Lenells, Linearizable Boundary Value Problems for the Elliptic sine-Gordon and the Elliptic Ernst Equations (submitted).

Acknowledgments

ASF is grateful to Guggenheim Foundation for partial support and to V. Zakharov for suggesting the investigation of KPII on the half-plane.

D. Mantzavinos was supported by an EPSRC Doctoral Training Grant.