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Equation (139) was incorrectly typeset. It should have been:

\[
\Psi(z) = \sum_\alpha z_\alpha^m \langle w_0 \alpha | \exp \left[ \frac{1}{2} \sum_{ij} \hat{B}_{ij} z_{ij} \right] \phi \rangle.
\] (139)
Invited Comment

The many-nucleon theory of nuclear collective structure and its macroscopic limits: an algebraic perspective

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Abstract

The nuclear collective models introduced by Bohr, Mottelson and Rainwater, together with the Mayer–Jensen shell model, have provided the central framework for the development of nuclear physics. This paper reviews the microscopic evolution of the collective models and their underlying foundations. In particular, it is shown that the Bohr–Mottelson models have expressions as macroscopic limits of microscopic models that have precisely defined expressions in many-nucleon quantum mechanics. Understanding collective models in this way is especially useful because it enables the analysis of nuclear properties in terms of them to be revisited and reassessed in the light of their microscopic foundations.

Keywords: nuclear collective models, algebraic models, many-nucleon quantum mechanics, the symplectic model, shell model coupling schemes

1. Introduction

During the time that the independent-particle shell model of the nucleus was being developed, the quadrupole moments of many odd nuclei were measured and determined to have small values for nuclei close to magic numbers. However, nuclei with intermediate nucleon numbers [1, 2] were often observed to have quadrupole moments much larger than those of a single nucleon. This was interpreted by Rainwater [3] to mean that such nuclei must have spheroidal as opposed to spherical shapes and challenged a standard belief of that time that even numbers of neutrons or protons would pair off to give states of zero spin so that the spin and the quadrupole moment of an odd nucleus would be that of the single unpaired nucleon. With considerable insight, Rainwater suggested that the independent-particle states of nucleons in a spheroidal potential should be expected to have density distributions of the same shape as the potential. Thus, on the basis of shape consistency he concluded that nuclei with spheroidal shapes could be expected.

Following Rainwater’s observations, Bohr [4] considered the quantum mechanics for the shape vibrations and deformations of a liquid-drop model of the nucleus. He also considered the possibility that the interactions between the nucleons and the deformed field that they generated could enhance the deformation of nuclei. In parallel with developments of the shell model [5, 6], Bohr and Mottelson [7] then extended the Bohr model to a unified model of a nucleus with coupled independent-particle and collective degrees of freedom.

A limitation of the Bohr model is that, as a quantum fluid, it has irrotational-flow moments of inertia which are much smaller than those needed to describe the low-energy rotational states of deformed nuclei. In the unified model, it was supposed, again with remarkable insight, that low-energy states would result with the introduction of vorticity associated with the nucleons in partially filled shells. Thus, the unified model was developed in a strong-coupling approximation in which the collective core of the nucleus would be polarised by the added nucleons and assume a spheroidal...
shape that would rotate adiabatically relative to the faster intrinsic dynamics of the coupled system. An important contribution to this development was the calculation by Nilsson [8] of single-particle states in a spheroidal shell-model potential. It would be an understatement to say that the Bohr–Mottelson–Nilsson model and its many developments (see, for example, [9–13] and the many references therein) have been successful in the interpretation of collective structure in nuclei. One measure of its success is that it continues to provide the basic concepts and language in terms of which nuclear collective phenomena are described. Thus, a great deal of effort has been expended by numerous researchers from a variety of geometrical, mean-field and algebraic perspectives, to give this phenomenologically conceived model a microscopic foundation. The several perspectives ultimately led to a formally precise many-nucleon theory of nuclear monopole and quadrupole collective dynamics.

Justifying this statement and explaining what it means is a primary objective of this paper. The many-nucleon theory that emerges is the so-called symplectic shell model. Like the standard shell model, the symplectic shell model is a formal framework in which simple models of nuclear properties can be understood and developed. The standard shell model expresses the many-nucleon Hilbert space as an ordered sum of spherical harmonic-oscillator subspaces, whereas the symplectic shell model expresses it as a sum of spaces that carry representations of a collective model. Solvable models then emerge, e.g., by restriction of the shell-model space to a subspace and by considering approximate model interactions.

The organisation of this paper is first to take stock of what has been achieved by extracting from the large body of literature a short and direct route to the many-nucleon theory of collective dynamics. The plan is to first identify the physical content and properties of the theory and then, by considering its macroscopic limits, explore how it can be used in simple ways to interpret experimental data and other models with microscopic observables. It is shown that the macroscopic limits are approached to an extraordinarily high level of accuracy in medium-to-heavy nuclei. It is also shown that the underlying microscopic structure of the unified models has strong implications for the low-energy beta- and gamma-vibrational states of rotational nuclei.

Models that are usefully considered from the symplectic-model perspective are those based on mean-field methods [14, 15]. A popular example is the pairing plus quadrupole model [16–18] which explores the competition [19] between pair-coupling of nuclei, as in the model of superconductivity [20], and the $Q, Q$ interaction of aligned coupling, as in the SU(3) model [21]. Such models are discussed briefly in section 13.

We would like this presentation to be easy to understand. At the same time, we wish to avoid suppressing the rigorous foundations on which the models are based. Thus, where appropriate, we start sections with a brief outline of their content so that a reader can obtain a quick understanding of its substance and return later to the more challenging details, which can be read as desired.

2. Early approaches

The search for a microscopic version of the collective model was initiated by Tomonaga [22] in two-dimensions and extended by Miyazima and Tamura [23] to three. It successfully identified irrotational-flow momenta that become canonically conjugate to quadrupole moments in a macroscopic limit. Had this approach been pursued, it could have led more directly to the expression of the Bohr model as a microscopic irrotational hydrodynamic model, as shown in section 3.2, and even to the model given in section 3.3 that included vorticity.

A few years later, Elliott introduced an SU(3) model as a coupling scheme for the spherical shell model and showed that the states of an irreducible SU(3) representation, within the space of valence-shell nucleons in a single spherical harmonic-oscillator shell, has properties that resemble those of a truncated rotor model. This showed that states with rotation-like properties can emerge in the shell model with effective interactions and other effective observables that conserve the symmetries of the SU(3) model. Subsequently, and unexpectedly, the SU(3) model re-emerged as a sub-model of the sought-after collective model and as the projected image of a rigid-rotor model onto the states of a single harmonic-oscillator shell-model energy. Thus, although Elliott’s model was only intended to apply to light nuclei, it acquired a relationship to the rotational states of well-deformed nuclei, albeit in spaces very different from those of the original SU(3) model.

The unified model of Bohr, Mottelson and Nilsson was based on the premise that a separation could be made between collective and intrinsic particle degrees of freedom of a nucleus. Thus, in seeking a derivation of this model, a suitable separation of the nucleon variables was pursued by many authors [24–31]. The several results were subsequently obtained [32, 33] as simple expressions of the nuclear kinetic energy as a Laplacian on a classical many-nucleon space of which collective model spaces were subspaces. Such methods also showed [26] that collective and intrinsic dynamics could only be completely decoupled if the intrinsic structure had an unphysical degree of rigidity. Otherwise the collective rotations would necessarily be strongly coupled to intrinsic vorticity. This posed a serious challenge because the vertex spin operators did not have simple expressions as one-body operators. However, the challenge evaporated with the recognition of an intimate relationship [32, 33] between the canonical transformation method and simple models based on the quantisation of Lie algebras of collective observables expressed in microscopic terms.

An algebraic expression of a rigid-rotor was given by Ui [34] and an algebraic expression for a rotor-vibrator model was given by Weaver, Biedenharn and Cusson [31, 34, 35]. Neither of them quite achieved the desired results; the first because a completely rigid rotor is unphysical and the second because non-zero vorticity, while clearly essential, is not conserved in nuclear collective dynamics. However, they were very influential and were quickly followed by the symplectic model [36–38] which contains these two models.
3. Realisations of microscopic collective models as algebraic models

A quick and simple approach to a microscopic theory of collective states in nuclei is obtained by identifying the essential observables that characterise their properties and expressing them in terms of a basic Lie algebra of observables. The elements of such a Lie algebra are the infinitesimal generators of a so-called dynamical group for the model. Any operator that is a polynomial in the elements of such a Lie algebra then has a well-defined representation on the states of an irreducible representation of that Lie algebra. In fact, the whole underlying many-nucleon quantum mechanics of nuclear structure theory makes use of this approach by recognising that the many-nucleon observables of a given nucleus are all expressible in terms of the finite Lie algebra, with simple commutation relations, generated by the position, momentum and intrinsic spins of nucleons. The remarkable property of this Lie algebra, without which nuclear physics would be impossibly complex, arises from the observation that nucleons are identical particles and obey the Pauli exclusion principle. This means that the many-nucleon quantum mechanics of a given nucleus has a single unique fully anti-symmetric representation in accordance with the Stone–von Neumann theorem.

In spite of its underlying simplicity, the representation of many-nucleon quantum mechanics is infinite-dimensional and has the potential for unlimited complexity. However, in common with most zero-temperature systems in physics, its lowest-energy states tend to be ones that maximise the available symmetries and its lowest-energy dynamics tend to be collective in nature and characterised by corresponding dynamical symmetries. This section shows how simple collective models emerge in many-nucleon quantum mechanics from this perspective.

The basic observables of all the models discussed in this section are fully symmetric quadratic functions of the nucleon position and momentum observables. Thus, in all applications, it is a simple matter to subtract the spurious centre-of-mass contributions to these observables. In effect, this operation reduces the effective number of particles from $A$ to $A - 1$ but does not change the commutation relations of their observables. Neither does it change the permutation symmetry of the model wave functions because the centre-of-mass wave function is always fully symmetric. This means that totally antisymmetric wave functions can be constructed as linear combinations of products of spatial and spin–isospin wave functions of conjugate permutation symmetry.

3.1. A microscopic rotor model

A simple rotor model was formulated by Ui [34] as an algebraic model, with a Lie algebra of basic observables that contains a set of commuting quadrupole operators, expressed as components of an $L = 2$ spherical tensor, and angular momentum operators $\{L_0, L_{\pm \pm} = \mp L_{\pm}/\sqrt{2}\}$ with commutation relations

$$[L_0, L_{\pm \pm}] = \pm L_{\pm \pm}, \quad [L_\pm \mp, L\pm \mp] = 2L_0,$$  
$$[L_{\pm \pm}, \mathbf{Q}_{2\nu}] = \sqrt{(2 + \nu)(2 \pm \nu + 1)} \mathbf{Q}_{2\nu \pm 1},$$  
$$[L_0, \mathbf{Q}_{2\nu}] = \nu \mathbf{Q}_{2\nu},$$  
$$[\mathbf{Q}_{2\nu}, \mathbf{Q}_{2\nu \mp}] = 0.$$ 

The quadrupole observables are elements of an Abelian Lie algebra and the angular momenta span an SO(3) Lie algebra. Together they form a so-called ROT(3) Lie algebra whose elements have expressions

$$\hat{L}_0 = \hat{L}_{22}, \quad \hat{L}_{\pm \pm} = \mp \frac{1}{\sqrt{2}}(\hat{L}_{31} \pm \hat{L}_{12}),$$  
$$\mathbf{Q}_{2\nu} = \frac{1}{\sqrt{2}}(\hat{Q}_{11} \mp \hat{Q}_{22} - \hat{Q}_{33}),$$ 

where the Heisenberg algebra for a single particle in ordinary three-dimensional space has a unitary representation on the infinite-dimensional Hilbert space of square-integrable functions of its spherical coordinates; this is the Hilbert space of a three-dimensional harmonic oscillator. However, whereas Lie algebras, in general, have infinite numbers of inequivalent unitary representations, the Stone–von Neumann theorem [47] shows that the Heisenberg algebra has only one. This uniqueness is generally taken for granted. In fact, it is quite remarkable and results in the simplification of many-particle quantum mechanics by many orders of magnitude.
\[ \hat{Q}_{z, \pm 1} = \sqrt{3} (\hat{Q}_{12} \pm i\hat{Q}_{13}), \]
\[ \hat{Q}_{z, \pm 2} = \frac{\sigma}{2} (\hat{Q}_{22} - \hat{Q}_{33} \pm 2i\hat{Q}_{23}), \]
in terms of the microscopic observables
\[ \hat{Q}_y = \sum_{n=1}^{A} \hat{x}_n \hat{x}_n, \quad \hbar \hat{L}_y = \sum_{n=1}^{A} (\hat{x}_n \hat{p}_m - \hat{x}_m \hat{p}_n). \]

The construction of the unitary representations of this Lie algebra, see section 6.3, is straightforward and provides a prototype for the construction of more general rotor models with appropriate intrinsic degrees of freedom such as those of the unified model. However, as it stands, its intrinsic states are eigenstates of the nuclear quadrupole moments with no vibrational fluctuations. Thus, the model admits no Coriolis or centrifugal stretching associated with the coupling between the intrinsic and rotational dynamics. In fact, its intrinsic states are effectively those of a rigid body and should have rigid-body moments of inertia [26, 32]. As a consequence, the irreducible representations of the Ui rotor model can only be realised on a many-nucleon Hilbert space in a limit in which their intrinsic wave functions approach delta functions in their quadrupole shapes. Nevertheless, it provided a microscopic version of the rigid-rotor model and was an important step towards the microscopic theory of nuclear rotations that was being sought.

### 3.2. The microscopic Bohr model

The original Bohr model of a nucleus was a hydrodynamic model with a sharply defined surface defined by its radius expressed as a function of angles in a spherical-harmonic expansion
\[ R(\theta, \phi) = R_0 \left( 1 + \sum_{LM} \alpha_{LM} Y_{LM}(\theta, \phi) + O(\alpha^2) \right). \]
Collective Hamiltonians were then considered of the form
\[ H = \frac{1}{2} \sum_M B_M |\delta_{LM}|^2 + V(\alpha), \]
where the \(B_M\) coefficients are mass parameters. The model was quantised by mapping the classical momenta \(p_{LM} = B_L \delta_{LM}\) to operators \(\hat{p}_{LM} = -i\hbar \partial / \partial \alpha_{LM}\). The various multipole moments of a nuclear density with shapes given by these parameters then defined corresponding collective models of nuclear vibrations and rotations.

A microscopic version of the Bohr model for combined monopole and quadrupole collective dynamics is obtained, as in Ui’s model, by replacing the surface monopole/quadrupole shape coordinates of the Bohr model with many-nucleon Cartesian quadrupole moments \(\hat{Q}_y = \sum_{n=1}^{A} x_n x_n\). Time derivatives and corresponding momenta are then given by
\[ \dot{\hat{Q}}_y = \frac{d\hat{Q}_y}{dt} = \sum_n (x_n \dot{x}_n + x_n \dot{x}_n), \]
\[ \dot{\hat{P}}_y = M\dot{\hat{Q}}_y = \sum_n (p_n \dot{x}_n + x_n \dot{p}_n), \]
where \(M\) is the nucleon mass. These moments and momenta are then quantised as appropriate for nucleons by replacing the \(x_n\) and \(p_{LM}\) coordinates by operators \(\hat{x}_n\) and \(\hat{p}_m\) with commutation relations \([x_n, \hat{p}_m] = i\hbar \delta_{mn}\) to obtain quantum observables
\[ \hat{Q}_y = \sum_n \hat{x}_n \hat{x}_n, \quad \hat{P}_y = \sum_n (\hat{p}_m \hat{x}_n + \hat{x}_m \hat{p}_n), \]
that satisfy the commutation relations
\[ [\hat{Q}_y, \hat{P}_x] = i\hbar (\delta_{xy} \hat{Q}_z + \delta_{zy} \hat{Q}_x + \delta_{xz} \hat{Q}_y + \delta_{yx} \hat{Q}_z). \]

The classical Bohr model, with a Heisenberg algebra of observables, is now regained by a contraction corresponding to a hydrodynamic limit of these commutation relations. The essential property of nuclear matter that is presumed in taking its so-called hydrodynamic limit is that it is essentially incompressible, to within quantum mechanical limits, over the range of states of interest. For practical purposes, it is a limit in which the volume of a nucleus, as characterised by its monopole moment, takes an essentially constant value. The contraction process we consider is similar to that introduced by Inoue and Wigner [48] to describe the contraction of the Lie algebra of the Lorentz group to that of the Galilean group when the observables of the Lie algebra are restricted to states of an object of velocities of small magnitude relative to the speed of light.

The contraction is obtained by expressing the monopole and quadrupole moments and momenta of a nucleus in units of a small parameter \(\epsilon\) that is assigned a value such that \(4\epsilon^2 = 1/\langle \hat{Q}_0 \rangle\), where \(\langle \hat{Q}_0 \rangle\) is the mean value of the close-to-constant monopole moment of the nucleus in its low-energy states. In these units, the monopole/quadrupole observables are given by
\[ \hat{q}_0 = \epsilon \hat{Q}_0 = \epsilon (\hat{Q}_{11} + \hat{Q}_{22} + \hat{Q}_{33}), \]
\[ \hat{p}_0 = \epsilon (\hat{P}_{11} + \hat{P}_{22} + \hat{P}_{33}), \]
and
\[ \hat{q}_{2,0} = \epsilon \hat{Q}_{2,0} = \frac{1}{\epsilon^2} (2 \hat{Q}_{11} - \hat{Q}_{22} - \hat{Q}_{33}), \]
\[ \hat{p}_{2,0} = \frac{1}{\epsilon^2} (2 \hat{P}_{11} - \hat{P}_{22} - \hat{P}_{33}), \]
\[ \hat{q}_{2,\pm 1} = \epsilon \hat{Q}_{2,\pm 1} = \sqrt{3} \epsilon (\hat{Q}_{12} \pm i\hat{Q}_{13}), \]
\[ \hat{p}_{2,\pm 1} = \sqrt{3} \epsilon (\hat{P}_{12} \pm i\hat{P}_{13}), \]
\[ \hat{q}_{2,\pm 2} = \epsilon \hat{Q}_{2,\pm 2} = (\hat{Q}_{22} \pm \hat{Q}_{33} \pm 2i\hat{Q}_{23}), \]
\[ \hat{p}_{2,\pm 2} = \frac{\sqrt{3}}{2} \epsilon (\hat{P}_{22} \pm \hat{P}_{33} \pm 2i\hat{P}_{23}). \]

Thus, with the commutation relations of equation (8), it is determined that
\[ [\hat{q}_0, \hat{p}_0] = i\hbar \hat{f} + O(\epsilon^2), \quad [\hat{q}_{2,\mu}, \hat{p}_{2,\nu}] = i\hbar \delta_{\mu \nu} + O(\epsilon), \]
and that the commutators, \([\hat{q}_0, \hat{p}_{2,\mu}], [\hat{q}_{2,\mu}, \hat{p}_0], [\hat{q}_{2,\mu}, \hat{q}_{2,\nu}], \) and \([\hat{p}_{2,\mu}, \hat{p}_{2,\nu}]\) are of order \(O(\epsilon)\).

Two significant observations follow for the Bohr model derived in this way. One is that its quadrupole moments are
the infinitesimal generators of irrotational flows, consistent with Bohr’s formulation of the model as a quantum fluid model. The second is that the simplest shell-model representation of the model in its spherical vibrational limit is given for a closed harmonic-oscillator shell-model nucleus. In such a representation, the one-phonon monopole excitation is at a high excitation energy as expected for almost-incompressible nuclear matter and the quadrupole excitations are high-energy giant-quadrupole resonance excitations. However, it is clear that, without the additional degrees of freedom of valence-shell nucleons, as introduced in the unified model, the microscopic Bohr model, is not able to provide a description of low-energy rotational states.

3.3. A microscopic Bohr model with vorticity

The previous section showed that the operators \( \{ \hat{Q}_{ij}, \hat{P}_{ij} \} \) become the elements of a Heisenberg algebra when restricted, as detailed in the previous section, to a subspace of the nuclear Hilbert space involving only giant-resonance degrees of freedom and in which nuclear matter is incompressible. In this respect the Bohr model is seen to be complementary to the SU(3) model which is the restriction of U(3)’s rigid rotor model to a subspace that excludes the giant-resonance excitations. However, as observed by Weaver, Biedenharn and Cusson \([35, 49]\), neither of these restrictions is necessary because the commutation relations of the \( \{ \hat{Q}_{ij}, \hat{P}_{ij} \} \) operators are all expressible in terms of angular-momentum operators \( \{ \hat{L}_{ij} \} \) defined by

\[
h\hat{L}_{ij} = \sum_{n=1}^{A} (\hat{x}_{ij} \hat{P}_{ij} - \hat{x}_{ij} \hat{P}_{ij}). \tag{12}
\]

Moreover, the commutation relations between all pair of operators in the augmented set \( \{ \hat{Q}_{ij}, \hat{P}_{ij}, \hat{L}_{ij} \} \) produce no new linearly independent operators and are a basis for a Lie algebra.

A model with this Lie algebra of observables is the so-called GCM(3) model \([35, 49]\) where GCM(3) is mnemonic for a generalised collective model in three-dimensions\(^5\).

Construction of the irreps (irreducible representations) of the GCM(3) model \([49, 50]\) shows that it extends the irrotational flows of the Bohr model to include an intrinsic angular momentum corresponding to quantised vorticity. Thus, it is significant that, with the admission of nuclear compressibility, however small, and the inclusion of the angular momentum to form a Lie algebra, the model acquires more general representations.

It is instructive to consider the microscopic version of the Bohr model with vorticity in the light of an argument \([26]\) that the states generated by rotation of a given intrinsic state can have only moments of inertia that differ from the rigid-body moments of inertia of the intrinsic density distribution if the intrinsic state includes cluster-like components of zero angular momentum. The complementary interpretation is now that the intrinsic states of a quantum fluid can only have moments of inertia different from those of irrotational flow if it has cluster-like components of non-zero vortex angular momentum.

3.4. The symplectic model

A serious problem with the GCM(3) model is that there is no easy way to construct a Hamiltonian for the model that gives energy spectra comparable to those observed. To describe rotational states, the Hamiltonian should clearly contain a kinetic-energy term. One possibility would be a kinetic energy proportional to the rotationally invariant quadratic

\[
\sum_{ij} \hat{P}_{ij} \hat{P}_{ij}. \]

A more meaningful choice would be the GCM(3)-conserving component of the many-nucleon kinetic energy. However, the many expansions \([28–30, 32]\) of the nuclear kinetic energy in terms of collective and complementary intrinsic coordinates, show this choice to be complicated. More significantly, the expansions that the nuclear kinetic energy contains large components that do not conserve the vorticity quantum number of a GCM(3) irrep. After many deliberations as to how to handle this problem, the answer that emerged was to simply add the many-nucleon kinetic energy to the Lie algebra of the GCM(3) model to form a still larger algebra. This is possible because the commutator of two bilinear combinations of nucleon position and momentum coordinates is again a bilinear combination of these coordinates. The algebra that emerges is the Lie algebra of the \( \text{Sp}(3, \mathbb{R}) \) symplectic group \([36]\).

In retrospect, it can be seen that the \( \text{Sp}(3, \mathbb{R}) \) algebra is the smallest Lie algebra that contains the nuclear quadrupole moments and its kinetic energy, both of which are essential components of a microscopic model of nuclear collective states. It is the Lie algebra of observables spanned by the operators

\[
\hat{Q}_{ij} = \sum_{n=1}^{A} \hat{x}_{ij} \hat{x}_{ij}, \quad \hat{K}_{ij} = \sum_{n=1}^{A} \hat{x}_{ij} \hat{x}_{ij}, \quad \hat{P}_{ij} = \sum_{n=1}^{A} (\hat{x}_{ij} \hat{p}_{ij} + \hat{p}_{ij} \hat{x}_{ij}). \tag{13a}
\]

Thus, it includes monopole and quadrupole moments, given by linear combinations of the elements \( \{ \hat{Q}_{ij}, i, j = 1, 2, 3 \} \) which define the size and shape of a many-nucleon nucleus. It includes infinitesimal generators of size and shape change, given by linear combinations of \( \{ \hat{P}_{ij} \} \), and infinitesimal generators of rotations given by the angular momenta \( \{ \hat{L}_{ij} \} \) in units of \( h \). The nuclear kinetic energy is proportional to \( \sum_{n} \hat{p}_{ij}^{2} \) and the other elements \( \{ \hat{K}_{ij} \} \) are included to close the Lie algebra. It is interesting to note that elements of the symplectic model algebra are expressed in equation (13) in terms of elements of the subalgebras of the following chain,
that are added one set at a time

\[
\text{SO}(3) \subset \text{ROT}(3) \subset \text{GCM}(3) \subset \text{Sp}(3, \mathbb{R})
\]

The \text{Sp}(3, \mathbb{R}) Lie group that finally emerges is recognised as the group of all linear canonical transformations of a six-dimensional phase space \cite{42} with three position coordinates and three canonical momenta.

An alternative route to the symplectic model is obtained from the developments by Filippov, Vanagas, Smirnov, and many colleagues \cite{45, 51} of a translationally invariant shell model for which \(O(A - 1)\), where \(A\) is the nuclear mass number, is a symmetry group and for which \text{Sp}(3, \mathbb{R})\ is a complementary dual group as recognised in nuclear physics by Moshinsky and Quesne \cite{42}.

4. The symplectic model as a unified model

The most valuable property of the symplectic model is that it is a bridge between the shell model and the collective model. Thus, it is a microscopic unified model in every respect. From a collective model perspective, it is an algebraic model with observables defined in terms of nucleon position and momentum coordinates. However, when its dynamical group \text{Sp}(3, \mathbb{R})\ is combined with the spin and isospin \text{SU}(2)\ groups, it defines a complete coupling scheme for the many-nucleon shell-model Hilbert space in a spherical harmonic-oscillator basis. In fact, as this section will show, the whole many-nucleon Hilbert space is a sum of symplectic-model spaces with subspaces defined by the subgroups in the chain

\[
\text{Sp}(3, \mathbb{R}) \supset \text{U}(3) \supset \text{SU}(3) \supset \text{SO}(3)
\]

that are identical to those of the spherical harmonic-oscillator shell model.

4.1. The \text{Sp}(3, \mathbb{R}) Lie algebra of \text{U}(3) tensor operators

As a prelude to constructing symplectic-model spaces in \text{Sp}(3, \mathbb{R}) \supset \text{U}(3) \supset \text{SU}(3) \supset \text{SO}(3)\ coupled basis states, it is useful to express the \text{Sp}(3, \mathbb{R})\ Lie algebra in terms of \text{U}(3)\ tensor operators obtained by expressing the position and momentum coordinates of a nucleon in terms of harmonic-oscillator raising and lowering (boson) operators

\[
\hat{x}_n = \frac{1}{\sqrt{2} a} (c_n^+ + c_n), \quad \hat{p}_n = i\hbar \frac{a}{\sqrt{2}} (c_n^+ - c_n),
\]

where \(a = \sqrt{M\omega/\hbar}\) is the harmonic-oscillator unit of inverse length. The elements of the \text{Sp}(3, \mathbb{R})\ algebra then have expansions

\[
\hat{L}_{ij} = \frac{1}{2\sqrt{a}} (2\hat{Q}_{ij} + \hat{A}_{ij} + \hat{B}_{ij}),
\]

\[
\hat{K}_{ij} = \frac{1}{2\sqrt{a}} \hbar^2 (2\hat{Q}_{ij} - \hat{A}_{ij} - \hat{B}_{ij}),
\]

\[
\hat{P}_{ij} = i\hbar (\hat{A}_{ij} - \hat{B}_{ij}), \quad \hat{L}_{\pm 1} = -i(\hat{C}_{ij} - \hat{\tilde{C}}_{ij}).
\]

with

\[
\hat{A}_{ij} = \hat{A}_{ij} = \sum_n c_n^+ c_n^+ + \sum_n c_n c_n^+,
\]

\[
\hat{B}_{ij} = \hat{B}_{ij} = \sum_n c_n c_n^+ - \frac{1}{2} \hat{\epsilon}_{ij},
\]

\[
\hat{C}_{ij} = \frac{1}{2} (\hat{\tilde{C}}_{ij} + \hat{\tilde{C}}_{ij}).
\]

The \text{U}(3) \subset \text{Sp}(3, \mathbb{R})\ subalgebra is then spanned by the angular-momentum operators \{\hat{L}_{ij}\} and the \text{U}(3)\ components \{\hat{Q}_{ij}\}\. These \text{U}(3)\ operators are also more usefully expressed in terms of \text{SO}(3)\ spherical tensors, which include \(L = 1\) angular momentum operators

\[
\hat{L}_0 = \hat{L}_{23}, \quad \hat{L}_{\pm 1} = \mp \frac{1}{\sqrt{2}} (L_{11} \pm iL_{12}),
\]

\[
\hat{Q}_0 = \hat{Q}_{11} + \hat{Q}_{22} + \hat{Q}_{33},
\]

and \(L = 2\) quadrupole operators

\[
\hat{Q}_{2,0} = 2\hat{Q}_{11} - \hat{Q}_{22} - \hat{Q}_{33},
\]

\[
\hat{Q}_{2,\pm 1} = \mp \sqrt{6} (\hat{Q}_{12} \pm i\hat{Q}_{13}),
\]

\[
\hat{Q}_{2,\pm 2} = \frac{3}{\sqrt{2}} (\hat{Q}_{22} - \hat{Q}_{33} \pm 2i\hat{Q}_{23}).
\]

In addition, the \text{Sp}(3, \mathbb{R})\ Lie algebra contains Hermitian linear combinations of the creation and annihilation operators, \(\hat{A}_{ij}\) and \(\hat{B}_{ij}\), of two harmonic-oscillator quanta. They are, respectively, the \(2\hbar\omega\) raising and lowering operators of giant-resonance excitations. Monopole and quadrupole giant-resonance raising and lowering operators are expressed in spherical-tensor notation by

\[
\hat{A}_0 = \sqrt{\frac{\gamma}{6}} \sum_i \hat{A}_{ii},
\]

\[
\hat{A}_{2,0} = \sqrt{\frac{\gamma}{12}} (2\hat{A}_{11} - \hat{A}_{22} - \hat{A}_{33}),
\]

\[
\hat{A}_{2,\pm 1} = \mp \sqrt{\frac{\gamma}{2}} \hat{A}_{13},
\]

\[
\hat{A}_{2,\pm 2} = \sqrt{\frac{\gamma}{8}} (\hat{A}_{22} - \hat{A}_{33} \pm 2i\hat{A}_{23}),
\]

and

\[
\hat{B}_0 = \sqrt{\frac{\gamma}{6}} \sum_i \hat{B}_{ii}
\]

\[
\hat{B}_{2,0} = \sqrt{\frac{\gamma}{12}} (2\hat{B}_{11} - \hat{B}_{22} - \hat{B}_{33}),
\]

\[
\hat{B}_{2,\pm 1} = \mp \sqrt{\frac{\gamma}{2}} (\hat{B}_{12} \mp i\hat{B}_{13}),
\]

\[
\hat{B}_{2,\pm 2} = \sqrt{\frac{\gamma}{8}} (\hat{B}_{22} - \hat{B}_{33} \mp 2i\hat{B}_{23}).
\]

(The normalisation of these tensors is chosen for convenience and historical reasons.)

The above expressions show that the \text{Sp}(3, \mathbb{R})\ Lie algebra is the union of two subsets of operators: those of a \text{U}(3)\ subalgebra, and giant resonance raising and lowering operators. The \text{SU}(3)\ subalgebra is spanned by the subset of operators \{\hat{L}_0, \hat{Q}_{2,\pm}\}\ and the total monopole and quadrupole operators are the combinations given in harmonic-oscillator
\[ (a = 1) \text{ units by} \]
\[
\hat{Q}_0 = \hat{Q}_0 + \sqrt{3} (\hat{A}_0 + \hat{B}_0), \quad (24a) \\
\hat{Q}_2 = \hat{Q}_2 + \sqrt{3} (\hat{A}_2 + \hat{B}_2). \quad (24b)
\]

It is also seen that, whereas the operators \( \hat{Q}_0, \hat{L}_z \) and \( \hat{Q}_2 \) are infinitesimal generators of a U(3) Lie algebra, the giant-resonance raising operators \( \hat{A}_0 \) and \( \hat{A}_2 \) are the \( L = 0 \) and \( 2 \) components of a U(3) \( \{2, 0, 0\} \) tensor, and the lowering operators \( \hat{B}_0 \) and \( \hat{B}_2 \) are their Hermitian adjoints.

### 4.2. The properties of an \( \text{Sp}(3, \mathbb{R}) \) representation

The many-nucleon representations of the symplectic model are simply defined. They comprise sets of states based on those of a so-called lowest-grade U(3) irrep, which are states that are annihilated by the giant-resonance lowering operators, and form an infinite tower of \( 2\hbar \omega, 4\hbar \omega, 6\hbar \omega, \ldots \) giant-resonance U(3) representations created by the repeated action of the U(3)-coupled giant-resonance excitation operators on the lowest-grade U(3) states.

These many states have properties that relate naturally to those of the Bohr–Mottelson unified model in which the SU(3) states correspond to the intrinsic nucleon states of the unified model whereas the giant-resonance states correspond to those of the irrotational-flow Bohr model.

The relationship between the symplectic model and the Bohr–Mottelson unified model will be developed explicitly in the following sections. It is obtained by considering the asymptotic (macroscopic) limits of symplectic-model representations that are rapidly approached in nuclei with relatively large numbers of nucleons. In these limits, the SU(3) states are shown to approach those of a rigid rotor and the giant-resonance excitations approach those of a harmonic vibrator. The strong coupling between them results in a coupled rotor-vibrator (CRV) model with many-nucleon wave functions.

In spite of this close correspondence with the standard unified model, there are notable differences. In particular, the low-energy states are more like those of a triaxial rigid rotor with a truncated sequence of \( K \) bands, than those of an axially symmetric rotor with vibrational beta and gamma bands. This is because the vibrational excitations of the microscopic symplectic model are basically those of the giant-resonance excitations which are expected to occur at higher energies.

A primary objective of this paper will be to show how the symplectic model simplifies in its macroscopic limits so that it becomes easy to apply to the analysis of experimental data and thereby identify the microscopic origins of what is observed. Such simplifications will be particularly essential if one is to have hopes of understanding the transitions between different collective bands brought about by dynamical symmetry-breaking interactions.

Early applications of the symplectic model and its sub-models were reviewed in 1985 [38]. These applications were with algebraic and schematic interactions, and, with a few exceptions, involved only a single symplectic-model irrep. More recent calculations, with algebraic and schematic interactions, include those of Bahri [52], Dreyfuss et al [53], and Tobin et al [54]. Symplectic model calculations with general shell-model nucleon–nucleon interactions were initiated by Filippov and colleagues [55, 56] and developed by Vassanji et al [57–60].

### 5. The symplectic shell model

The many-nucleon Hilbert space is infinite dimensional and in any calculation it is necessary to truncate it to a finite-dimensional subspace. In the standard spherical shell model, the many-nucleon Hilbert space is expressed as a sum of subspaces ordered by increasing independent-particle-model energies as given, for example, by the Mayer–Jensen model [61]. This makes it possible to truncate the Hilbert space to a shell-model subspace of states with lowest independent-particle-model energies. However, for strongly deformed nuclei, the Mayer–Jensen shell-model ordering is wildly inappropriate. Already in light nuclei, one typically needs an effective charge of approximately twice the mean nucleon charge to relate the quadrupole moments and E2 transition rates obtained in a Mayer–Jensen shell-model space to those observed. For some of the more deformed states, such as those of the rotational band built on the first excited state of \( ^{16}\text{O} \) [62–65] and on the so-called Hoyle state of \( ^{12}\text{C} \) [53], one needs to consider shell-model states of spherical harmonic-oscillator excitation energy \( \sim 4\hbar \omega \), relative to the lowest spherical harmonic-oscillator energy of the nucleus, as well as a large effective charge to describe their E2 properties [66].

The inability of the spherical shell model to describe states of large deformation is explained in the Nilsson extension of the Mayer–Jensen model. It is observed, for example [67] that the Nilsson-model with a spheroidal potential determined by the observed deformation of a nucleus such as \( ^{160}\text{Er} \) is able to give a lowest-energy state for this nucleus with the observed deformation. However, because of the crossing of spherical shell-model levels as they evolve into Nilsson levels, such a Nilsson-model state has of the order of 12 harmonic-oscillator quanta more than that of the lowest-energy Mayer–Jensen states.

An important observation is that, in addition to being an algebraic collective model, the symplectic model also defines a coupling scheme for the complete many-nucleon Hilbert space and its expression as a sum of collective model subspaces [68, 154]. Thus, it gives a decomposition of the many-nucleon Hilbert space, which differs from that of the Mayer–Jensen shell model and is more appropriate for the description of collective rotational states. Moreover, as for the standard shell model, the collective model subspaces can be ordered for any given nucleus, e.g., by the energies of their lowest-weight states with respect to a suitable model Hamiltonian; see discussion of mean-field methods in section 13.

The decomposition of a many-nucleon space into subspaces that carry representation of useful groups by means of so-called coupling schemes, is standard practice in traditional shell-model calculations [69]. Typical coupling schemes are based on the use Wigner’s U(4) supermultiplet group [70].
which contains the SU(2)S × SU(2)p spin and isospin groups as subgroups, the compact symplectic group [71, 72] which is the symmetry group of a pairing model, and the SU(3) group which is the dynamical group of the Elliott model [21].

For deformed rotational nuclei it is appropriate to consider a decomposition of the many-nucleon Hilbert space by means of a coupling scheme based on the direct product group Sp(3, R) × U(4). For such a coupling one could contemplate many-nucleon calculations in spaces classified by states labelled by the quantum numbers of, for example, the groups in the chain

$$\text{Sp}(3, R) \times \text{SU}(2)_{S_p} \times \text{SU}(2)_{S_n} \supset \text{U}(3) \times \text{SU}(2)_p,$$

where SU(2)S_p and SU(2)S_n are the neutron and proton intrinsic spin groups, and SU(2)p is the total angular-momentum group. For convenience, we shall refer to the subspaces for the irreps of this coupling scheme as ‘collective subspaces’.

The symplectic model is then simply an expression of the Hilbert spaces of many-nucleon quantum mechanics as sums of collective subspaces of states that carry irreducible representations of the symplectic model together with other spin and isospin representations as required.

For a calculation with a meaningful Hamiltonian in a space of many-nucleon states restricted to a collective subspace, one would expect to see a low-energy band of states emerging with properties close to those of a rotor model. However, as noted in section 4.2, one would not expect to see low-energy excited rotational bands such as beta or gamma vibrational bands.

Observe that, because the full quadrupole operator of a nucleus is an element of the Sp(3, R) Lie algebra, there can be no isoscalar E2 transitions between the algebra’s different representation spaces. Thus, the observation of E2 transition between states of different rotational bands can give information on the mixing of collective subspaces arising from symplectic model symmetry-breaking interactions. Such mixing is expected to occur and, indeed, a symmetry breaking interaction could very well result in a coherent mixing of collective states in the manner of a quasi-dynamical symmetry [73] and lead to unexpected results. For example, it could be that strong pairing interactions could result in a mixing of lowest-grade SU(3) representations with the result that bands of states emerge with the properties of an axially symmetric rotor with vibrational excitations. One can learn as much, perhaps more, from the limitations of a model as from its successes.

In concluding this section, it is emphasised that the primary focus of this paper is on the interpretation of nuclear data in terms consistent with many-nucleon theory. Thus, we make little mention of the very significant developments of the so-called M-scheme methods [74, 75], that enable shell-model calculation in huge spaces. The huge no-core shell-model calculations in M-scheme basis have contributed enormously to establishing the foundations of nuclear structure theory in terms of many-nucleon quantum mechanics which, in this paper, are taken as understood. Also, because our concern is primarily with the interpretation of collective states in heavy nuclei, which are currently out of the reach of detailed shell-model calculations, we make little mention of the technology associated with the implementation of shell-model calculations with general nucleon interactions in a symplectic-model basis. We mention only that several authors, notably Suzuki and Hecht [76, 77], and Escher and Draayer [78], contributed to its development. Particularly important has been the facility to undertake multi-shell model calculations in a U(3)-coupled basis; for this the most significant developments were no doubt: the computer codes to determine U(3) coupling and recoupling coefficients of Akiyama, Draayer and Millener [79–81]; the SU(3)-reduced matrix packages of Braunschweig, Bahri and Draayer [82–84]; and ultimately the impressively large calculations with realistic interactions in large multi-shell model spaces in a U(3) × SU(2)S_p × SU(2)S_n ⊃ SU(3) × SU(2)_p coupled basis by Dytrych et al [85–88].

6. The representation of a collective model

The collective models have rich algebraic structures of which little use was made in the original formulations of the Bohr–Mottelson models. Indeed, they are often described as geometric models to distinguish them from purely algebraic models. This is not inappropriate because their physical content is most readily understood in geometrical terms. However, the theories of geometry, Lie groups and Lie algebras are very much intertwined. What is impressive is that, without explicit use of their algebraic structures, the model representations anticipated sophisticated developments in the theory of Lie group and Lie algebra representations which subsequently became important in identifying their microscopic generalisations.

The most powerful procedure for constructing representations of a Lie group (or Lie algebra) is by extending a representation of a subgroup (subalgebra) by the mathematical method of induced representations [89]. This procedure has a counterpart in physics in terms of coherent state [90] and more general vector coherent state (VCS) representations [91]. A remarkable relationship between an induced representation and a unified collective model is that the irreps of the dynamical group for the model are induced from a smaller group which defines the intrinsic states of the model’s representations.

The standard theory of coherent-state representations was developed by many [92–96] and is reviewed in [90, 97]. Its VCS extension was introduced [98, 99] specifically for the purpose of constructing irreps of the symplectic model but was quickly found to have a wide range of applications; see [101] and references therein. VCS theory is intuitively natural from the perspective of collective models in which richer models are obtained by adding intrinsic degrees of freedom to a simpler model. Thus, it is rewarding to discover its remarkable versatility in constructing representation of Lie

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6 Partial coherent-state representations were also defined by Deenen and Quesne [100].
algebras and Lie groups in general and that the collective models serve as prototypes for such applications.

A common property of collective models is that they are defined by sets of intrinsic states and groups of transformations of these states. Two types of representation are prevalent in collective models: the first relates to boson-expansion methods appropriate for models with vibrational degrees of freedom; the second relates to models with rotational degrees of freedom. The prototype of a vibrational coherent-state representation is given by the Bargmann representation of a harmonic-oscillator [102]. The prototype of a rotational coherent-state representation is given by the rotor model.

A valuable property of coherent state and VCS methods is that they give expressions of microscopic collective models in terms of the original collective models that they replace. As a result, traditional practices for interpreting nuclear properties in terms of collective models continue to apply with some adjustment.

6.1. Generalised Bargmann representations

Recall that the states of a one-dimensional harmonic oscillator span a unitary representation of a simple boson algebra with raising and lowering operators, $\hat{c}$, $\hat{c}^\dagger$, that satisfy the commutation relation

$$[\hat{c}, \hat{c}^\dagger] = 1,$$

and that orthonormal basis states for the harmonic oscillator are given by

$$|n\rangle = \frac{1}{\sqrt{n!}} (\hat{c}^\dagger)^n |0\rangle, \quad n = 0, 1, 2, \ldots,$$  

where $|0\rangle$ is the boson vacuum state. Thus, an arbitrary state of the harmonic oscillator is expressed in the form

$$|\psi\rangle = f(\hat{c}^\dagger) |0\rangle,$$

where $f(\hat{c}^\dagger)$ is a function of the boson creation operator. In the Bargmann representation, a state $|\psi\rangle$ is represented by a wave function, that is a function of a complex variable $z$, defined by the overlaps

$$|\psi\rangle \rightarrow \Psi(z) = \langle 0 | e^{i\hat{c}} | \psi\rangle.$$  

The orthonormal basis states of equation (27) then have the wave functions

$$|n\rangle \rightarrow \Psi_n(z) = \frac{1}{\sqrt{n!}} z^n, \quad n = 0, 1, 2, \ldots,$$  

The operation of a boson operator $\hat{X}$, i.e., $\hat{c}^\dagger$ or $\hat{c}$, on these wave functions is defined by the equation

$$\hat{X} \Psi_n(z) = \langle 0 | e^{i\hat{X}} | n\rangle = \langle 0 | \left[ \hat{X} + z[\hat{c}, \hat{X}] + \frac{1}{2} z^2 [\hat{c}, [\hat{c}, \hat{X}]] \right] e^{i\hat{c}} | n\rangle.$$  

Thus, it is determined that

$$\hat{c}^\dagger z, \quad \hat{c} = d/dz.$$  

The same methods can be used to derive exact boson expansions of other Lie algebras with raising and lowering operators [103–105]. The simplest example, is for the SU(2) Lie algebra, which has elements with commutation relations

$$[S_0, S_\pm] = \pm S_\mp, \quad [\hat{S}_+^2, S_-] = 2S_0.$$  

If $|0\rangle$ is a lowest-weight state for an SU(2) irrep of angular momentum $j$, it is an eigenstate of $\hat{S}_z$ with eigenvalue $-j$. A state $|\psi\rangle$ of the irrep then has a coherent-state wave function defined as a function of a variable $z$ by

$$\Psi(z) = \langle 0 | e^{i\hat{S}_z} | \psi\rangle.$$  

Thus the elements of the SU(2) Lie algebra have coherent-state representations given, in accord with equation (31), by

$$\hat{S}_+ \Psi(z) = \langle 0 | \hat{S}_+ e^{i\hat{S}_z} | \psi\rangle = \frac{d}{dz} \Psi(z),$$  

$$\hat{S}_- \Psi(z) = \langle 0 | \hat{S}_- e^{i\hat{S}_z} | \psi\rangle = -z \Psi(z),$$  

This is the famous Dyson representation [106]. To make use of it, one needs an orthonormal set of basis wave functions relative to which the matrix elements of the SU(2) Lie algebra operators can be calculated. A simple $K$-matrix procedure has been developed for this purpose [99, 107].

An orthonormal basis is defined to within normalisation factors as monomial functions

$$\Psi_m(z) = k_m z^{j+m},$$  

where $m = -j$ for the lowest-weight state and

$$\hat{S}_+ \Psi_m(z) = m \Psi_m(z),$$

as desired. Application of the raising operator in the Dyson representation then gives

$$\hat{S}_+ \Psi_m(z) = k_m (j + m) z^{j+m+1} = \frac{k_m}{k_{m+1}} (j + m) \Psi_{j,m+1}(z).$$

Similarly, application of the lowering operator gives

$$\hat{S}_- \Psi_{j,m+1}(z) = k_{m+1} (j + m + 1) z^{j+m} = \frac{k_{m+1}}{k_m} (j + m + 1) \Psi_{j,m}(z).$$

Thus, the SU(2) matrix elements are given by

$$\langle j, m+1 | [\hat{J}_+, \hat{J}_m] = \frac{k_m}{k_{m+1}} (j - m),$$  

$$\langle j, m+1 | [\hat{J}_-, \hat{J}_m] = \frac{k_{m+1}}{k_m} (j + m + 1).$$

It follows that, to satisfy the Hermiticity relationships

$$\langle j, m+1 | [\hat{J}_-, \hat{J}_m] = (\langle j, m+1 | [\hat{J}_-, \hat{J}_m])^*$$
of a unitary representation, the norm factors have ratios
\[ \frac{k_{m+1}}{k_m} = \frac{j-m}{j+m+1} \]  
and we obtain the matrix elements
\[ \langle j, m \pm 1 \mid \hat{J}_ \pm |jm \rangle = \sqrt{(j+m)(j+m+1)}. \]

The coherent-state construction of representations works for many Lie algebras. For example, it works as readily for the infinite-dimensional representations of the non-compact SU(1, 1) Lie algebra as for SU(2). One can equally well start from a highest-weight state of a representation as from a lowest-weight state.

6.2. Vector coherent state representations

A serious limitation of the above coherent-state construction is that it applies only to Lie algebras for which the raising (likewise the lowering) operators commute with one another. For example, it does not apply to representations of the SU(3) Lie algebra which comprises two commuting U(1) operators, three non-commuting raising operators and three non-commuting lowering operators.

This obstacle is circumvented in a VCS representation by using, instead of a single intrinsic state, a set of intrinsic states that carry a multi-dimensional representation of an intrinsic-symmetry group. A simple example is the extension of the Bargmann representation to a particle with intrinsic spin states. A parallel collective-model example, could be the extension of the Bohr model by the addition of intrinsic states of non-zero vorticity. Indeed, the Bohr–Mottelson unified model is seen from this perspective as a Bohr model with intrinsic nucleon states.

In a VCS representation, the SU(3) Lie algebra is seen as comprising the four elements of a U(2) subalgebra, two commuting raising operators $[A_1, A_2]$ and two commuting lowering operators $[B_1, B_2]$. One can then define an orthonormal basis of highest-grade states $|\alpha\rangle$ for the irrep which are a subset of states of the irrep that are annihilated by the two commuting raising operators and transform as basis vectors $|\xi_\alpha\rangle$ for an irreducible U(2) representation. The basis vectors $|\xi_\alpha\rangle$ serve as intrinsic states for an irreducible VCS SU(3) representation in which a VCS wave function $\Psi$ of a state $|\psi\rangle$ in an irreducible SU(3) representation is a vector-valued function of $(z_1, z_2)$ coordinates defined by
\[ \Psi(z) = \sum_\alpha \xi_\alpha \langle \alpha \mid z_1 A_1 + z_2 A_2 \rangle |\psi\rangle. \]

The VCS construction has been shown to give explicit analytical expressions for the matrix elements of the SU(3) algebra [91] and indeed for the known representations of this [108] and other SU(n) Lie algebras in canonical U(n − 1) bases [109]. However, for applications to nuclear collective models the representations of SU(3) are required in an SO(3)-coupled basis [110, 111] for which the VCS representation of the rotor model provides a systematic procedure for deriving the standard rotor-model results.

6.3. The representation of an asymmetric rotor

The Hilbert space $|\Psi\rangle_{\text{ASR}}$ for a completely asymmetric rigid rotor, with no intrinsic degrees of freedom, is the space of all normalisable functions of the orientation angles of a set of axes fixed in the body of the rotor relative to a space-fixed set. The group of all rotations of a set of axes is the group SO(3). Thus, $|\Psi\rangle_{\text{ASR}}$ is spanned by the set of all wave functions of the form
\[ \psi_{KLM}(\Omega) = \sqrt{2L + 1} gL L M (e^{i\Omega}) \Omega \in \text{SO}(3), \]

in which $gL L M (e^{i\Omega})$, with $L \geq 0$ taking integer values, is a Wigner rotation-matrix function, and the wave functions are normalised with respect to the standard SO(3) volume element $d\Omega$ such that
\[ \langle KLM | K'L'M' \rangle = \int \psi^*_{KLM}(\Omega) \psi_{K'L'M'}(\Omega) \ d\Omega = \delta_{K,K'} \delta_{L,L'} \delta_{M,M'}. \]

From a coherent-state perspective, the rotor is described by an intrinsic state $|\phi\rangle$ defined in the body-fixed axes of the rotor and the wave function $\psi_{KLM}$ is expressed as the overlap function
\[ \psi_{KLM}(\Omega) = \langle \phi | R(\Omega) | KLM \rangle, \ \Omega \in \text{SO}(3). \]

This expression is consistent with equation (48) as seen from the expansion
\[ \psi_{KLM}(\Omega) = \sum_N \langle \phi | KLN \rangle \mathcal{D}^L_{NM}(\Omega) \]

in which, if the intrinsic wave function $\phi$ is a delta function in $\Omega$,
\[ \langle \phi | KLN \rangle = \int \phi^* (\Omega) \psi_{KLN}(\Omega) \ d\Omega = \frac{2L + 1}{8\pi^2} \delta_{N,K}. \]

An advantage of the coherent state expression is that the action of an SO(3) tensor operator, such as a quadrupole moment operator $\hat{Q}_{2\mu}$, is immediately defined on rigid-rotor wave function from the observation that, when the intrinsic axes of the rotor are the principal axes of the quadrupole tensor
\[ \hat{I}(Q_{2\mu}) \psi_{KLM}(\Omega) = \langle \phi | R(\Omega) \hat{Q}_{2\mu} | KLM \rangle \]
\[ = \sum_\mu \langle \phi | Q_{2\mu} R(\Omega) | KLM \rangle g_{\mu \mu} (\Omega) \]
\[ = \sum_\mu Q_{\mu} g_{\mu \mu} (\Omega) \psi_{KLM}(\Omega). \]

Where $Q_{\mu}$ are the quadrupole moments of the rotor in the principal axes frame and are such that
\[ \langle \phi | \hat{Q}_{2\mu} | \psi \rangle = [\delta_{\mu,0} \hat{Q}_0 + (\delta_{\mu,2} + \delta_{\mu,-2}) \hat{Q}_2] \langle \phi | \psi \rangle. \]

Thus, the coherent-state method provides a systematic procedure for deriving the standard rotor-model results.
This is particularly useful for rotors with intrinsic symmetries.

6.4. Rotors with intrinsic symmetry

In molecular physics, molecules with relatively well-defined shapes are described as symmetric tops, when two of their principal moments of inertia are equal, and as asymmetric tops, when all three are different. In both cases, rotations can occur about all three principal axes. However, rotations of the molecule that leave its principal axes invariant are regarded as intrinsic motions and the set of such rotations form a group known as the intrinsic-symmetry group of the molecule. Thus, the intrinsic symmetry group of a symmetric top is the group $D_{\infty}$ which comprises $SO(2) \subset SO(3)$ rotations about the symmetry axis and rotations through angle $\pi$ about a perpendicular axis. Likewise, an asymmetric top has an intrinsic symmetry group $D_2$ which comprises rotations through multiples of $\pi$ about all of its principal axes.

To illustrate the significance of the intrinsic symmetry group, we consider the representations of $U_i$’s rigid rotor model. The Lie algebra of $U_i$’s model, discussed in section 3.1, contains five commuting quadrupole-moment and three angular-momentum operators. An irreducible representation of this algebra is induced by VCS methods starting from a representation of the subalgebra generated by the five quadrupole moments and the single angular-momentum component $L_0$. A basis for such a representation, $\hat{\sigma}$, is given by an infinite set of intrinsic states $\{\xi_k\}$, with $K$ taking all integer values and for which

$$\hat{\sigma} (L_0) \xi_K = K \xi_K, \quad \hat{\sigma} (Q_{20}) \xi_K = \hat{Q}_0 \xi_K,$$

$$\hat{\sigma} (Q_{2\pm 2}) \xi_K = \hat{Q}_2 \xi_{K\pm 2}. \quad (55a)$$

However, to uniquely define an irreducible representation of the rotor model, it is also necessary that the intrinsic states transform in a well-defined way under all elements of the intrinsic symmetry group $D_2$. Transformation of the $\{\xi_k\}$ basis under rotations through angle $\pi$ about the axis of quantisation is already given by

$$e^{i \pi L_0} \xi_K = e^{i \pi K} \xi_K. \quad (56)$$

Because there are two irreducible representations of the discrete subgroup of $SO(3)$ generated by rotations through an angle $\pi$ about an axis perpendicular to the axis of quantisation, we also specify that the intrinsic states transform under such a rotation $e^{i \pi L_i}$ according to the equation

$$e^{i \pi L_i} \xi_K = \xi_K, \quad e^{i \pi L_i} \xi_K = \xi_K, \quad (57)$$

where the two irreducible representations are characterised by the two possible sign relations $\xi_K = \pm \xi_K$. (Note that for an odd-mass nucleus, $K$ takes half-odd integer values and changes sign under a $2\pi$ rotation about any axis; thus $\xi_K = \pm i \xi_{-K}$, where $i = \sqrt{-1}$.)

These intrinsic states now serve as basis vectors for a set of VCS wave functions

$$\psi_{\alpha L M} = \sum_{K} \xi_K \langle K | \tilde{R}(\Omega) | \alpha L M \rangle$$

$$= \sum_{K} \xi_K \langle K | \alpha L M \rangle \tilde{D}_{LM}^K(\Omega), \quad \Omega \in SO(3), \quad (58)$$

for the rigid-rotor algebra, where the states $\{ | K \rangle \}$ are a subset of states of the rotor that transform in the same way under $D_2$ rotations as the intrinsic states $\{\xi_K\}$, i.e.

$$\hat{L}_0 | K \rangle = K | K \rangle, \quad \hat{Q}_2 | K \rangle = \hat{Q}_0 | K \rangle,$$

$$\hat{Q}_2 | K \pm 2 \rangle = \hat{Q}_2 | K \rangle \pm 2}. \quad (59a)$$

It remains only to ensure that the consistency equations

$$\sum_{K} \delta (X) \xi_K \langle K | \tilde{R}(\Omega) | \alpha L M \rangle = \sum_{K} \xi_K \langle K | \tilde{X} \tilde{R}(\Omega) | \alpha L M \rangle \quad (60)$$

are satisfied for $X$ equal to any of the elements $\{L_0, Q_{20}, Q_{2\pm 2}, e^{i n L_i}\}$ that define the intrinsic states. With the standard normalisations given by equation (48), we then obtain the expression for the wave functions of an asymmetric top

$$\psi_{K L M}(\Omega) = \frac{2L + 1}{16 \pi^2 (1 + \delta_{K,0})} \{\xi_K \tilde{D}_{LM}^K(\Omega)$$

$$+ (-1)^{L+K} \xi_K \tilde{D}_{LM}^{K}(\Omega)\}, \quad (61)$$

in the familiar rotor-model form.

These expression are readily extended to nuclear rotational models with strongly coupled spin degrees of freedom. However, for present purposes, they will be used to provide a systematic procedure for the construction of $SU(3)$ representations in an $SO(3)$-coupled basis and for their physical interpretation in rotor-model terms.

7. Representations of SU(3) in an SO(3) angular-momentum basis

A fortuitous result that underlies the success of Elliott’s model [21] is that when the nuclear quadrupole moments of U’s rotor model [34] $\{\hat{Q}_{20}\}$ are restricted to the space of many-nucleon states of a single spherical harmonic-oscillator energy, they become elements $\{\tilde{Q}_{20}\}$ of an $SU(3)$ Lie algebra. This was shown in section 4.1. It follows that the states of an irreducible $SU(3)$ representation are the projected images of rigid-rotor model states. The $SU(3)$ representations in multi-shell spaces also acquire an enhanced significance as the building blocks of the microscopic collective theory.

Because of its use as a shell-model coupling scheme, the representation theory of $SU(3)$ and associated technology for its use have been well developed (see the review article of Harvey [114] for early references). Most important was the development of programs to calculate $SU(3)$ Clebsh–Gordan, Racah, and $9 - \lambda \mu$ coefficients [79–81, 115–117]; which are freely available in both $SU(2)$ and $SO(3)$ bases [79].
As defined in section 4.1, the SU(3) algebra is a sub-algebra of the U(3) algebra of operators \( \{ \hat{C}_{ij}, i, j = 1, 2, 3 \} \) that satisfy the commutation relations

\[
[\hat{C}_{ij}, \hat{C}_{kl}] = \delta_{ik} \hat{C}_{lj} - \delta_{il} \hat{C}_{kj}.
\]

(62)

It contains angular-momentum and quadrupole operators expressed in a spherical tensor basis by

\[
\hat{L}_0 = \hat{L}_2, \quad \hat{L}_{\pm 1} = \pm \sqrt{3} (\hat{L}_1 \pm i \hat{L}_1),
\]

(63a)

\[
\hat{Q}_{2,0} = 2 \hat{Q}_{11} - \hat{Q}_{22} - \hat{Q}_{33},
\]

(63b)

\[
\hat{Q}_{2,\pm 1} = \pm \sqrt{3} (\hat{Q}_{12} \pm i \hat{Q}_{13}),
\]

(63c)

\[
\hat{Q}_{2,\pm 2} = \frac{3}{2} (\hat{Q}_{22} - \hat{Q}_{33} \pm 2i \hat{Q}_{23}),
\]

(63d)

where

\[
\hat{L}_0 = -i (\hat{C}_{ij} - \hat{C}_{ij}), \quad \hat{Q}_i = \frac{1}{2} (\hat{C}_{ij} + \hat{C}_{ji}).
\]

(64)

The SU(3) algebra is finite and semi-simple, and its irreducible representations are easily constructed. They were determined by numerical methods [21, 118] within the framework of the shell model for light nuclei, and subsequently derived by the algebraic methods of VCS theory [110].

This section reviews a version [101] of the VCS construction in basis states that relate directly to those of UI’s rigid-rotor model. In this construction, the SU(3) quadrupole moments \( \{ \hat{Q}_r \} \) are represented as operators

\[
\hat{\Gamma} (\hat{Q}_{2\nu}) = (2\lambda + \mu + 3) \hat{\varphi}^{2\nu}_0 - \frac{1}{2} [\hat{\mathbf{L}} \cdot \hat{\mathbf{L}}, \hat{\varphi}^{2\nu}_0]
\]

\[
+ \sqrt{3} (\hat{\sigma}_+ \hat{\varphi}^{2\nu}_2 + \hat{\sigma}_- \hat{\varphi}^{2\nu}_{-2}),
\]

(65)

on linear combinations of rotor-model wave functions of the form

\[
\Phi_{(L,K,M)} (\Omega) = \frac{2L + 1}{16\pi^2(1 + \delta_{k0})} \left( \xi_K \hat{\varphi}^{-L}_{K,M} (\Omega) \right.
\]

\[
\left. + (-1)^{L+K} \xi_{-K} \hat{\varphi}^{-L}_{-K,M} (\Omega) \right),
\]

(66)

in which \( \hat{\varphi}^{2\nu}_0 \) is an operator that acts multiplicatively, i.e.

\[
\hat{\varphi}^{-2\nu}_0 \psi (\Omega) = \hat{\varphi}^{-2\nu}_{-\mu} (\Omega) \psi (\Omega),
\]

(67)

and \( \hat{\sigma}_0, \hat{\sigma}_x \) are operators that act on the intrinsic-spin states according to

\[
\hat{\sigma}_0 \xi_K = \frac{1}{2} K \xi_K,
\]

(68a)

\[
\hat{\sigma}_x \xi_K = \frac{1}{2} \sqrt{\mu + K}(\mu - K + 2) \xi_{K+2}.
\]

(68b)

A significant property of equation (65) is that, if it were not for the term \( \frac{1}{2} [\hat{\mathbf{L}} \cdot \hat{\mathbf{L}}, \hat{\varphi}^{2\nu}_0] \) which is of negligible importance when \( \hat{\Gamma} (\hat{Q}_{2\nu}) \) acts on states of angular momentum \( L \ll 2\lambda + \mu + 3 \), the properties of the SU(3) states including their wave functions and matrix elements would be those of a rigid-rotor, albeit with \( K \) limited to the range \( K = \mu, \mu - 2, \ldots, 1 \) or 0 of an SU(2) representation as defined by equation (68). However, as the angular momentum increases and becomes non-negligible in comparison with \( 2\lambda + \mu + 3 \), the \( \frac{1}{2} [\hat{\mathbf{L}} \cdot \hat{\mathbf{L}}, \hat{\varphi}^{2\nu}_0] \) term becomes of increasing importance and results in the termination of the rotation-like bands to those of a finite-dimensional SU(3) representation. Thus, although the \( \hat{\Gamma} (\hat{Q}_{2\nu}) \) operators have well-defined actions on the infinite-dimensional space of the rigid-rotor wave functions of equation (66), they generate the finite-dimensional subspace of an SU(3) irrep when applied repeatedly to any wave function that lies within the irreducible SU(3) subspace of rotor-model wave functions. This is illustrated in section 7.4 for \( (\lambda 0) \) and \( (\lambda 1) \) representations for which the SO(3)-reduced matrix elements of the SU(3) quadrupole tensor have simple analytical expressions.

For a generic representation with \( \mu > 1 \), there are multiple states of a given angular momentum \( L \) in the representation and \( K \) is no longer a precise quantum number. However, one can construct an orthogonal basis within the space of states of a common \( L \) by first diagonalising the easily calculated matrix of SO(3)-reduced matrix elements of the SU(3) quadrupole operator restricted to this space. It then only remains to renormalise these states as for multiplicity-free representations to obtain an orthonormal basis and the matrix elements of a unitary representation.

Note that a pair of so-called contragredient SU(3) representations \( (\lambda \mu) \) and \( (\mu \lambda) \) have complete sets of matrix elements that differ only in that their quadrupole matrix elements have opposite sign. Thus, it is sufficient to determine the representations with \( \lambda \geq \mu \) to obtain those for both \( \lambda \geq \mu \) and \( \lambda < \mu \).

The following subsections give derivations and details of the above results.

7.1. VCS wave functions for SU(3) in a rotor-model basis

An irreducible representation of SU(3) is characterised by a highest-weight state \( |\lambda \mu \rangle \), which is a state that is annihilated by the three raising operators \( \hat{C}_{12}, \hat{C}_{13} \) and \( \hat{C}_{23} \), and is an eigenstate of the operators

\[
\hat{h}_1 = \hat{C}_{11} - \hat{C}_{22}, \quad \hat{h}_2 = \hat{C}_{22} - \hat{C}_{33}.
\]

(69)

it satisfies the equations

\[
\hat{C}_{12} (|\lambda \mu \rangle) = \hat{C}_{13} (|\lambda \mu \rangle) = \hat{C}_{23} (|\lambda \mu \rangle) = 0,
\]

(70a)

\[
\hat{h}_1 (|\lambda \mu \rangle) = \lambda (|\lambda \mu \rangle), \quad \hat{h}_2 (|\lambda \mu \rangle) = \mu (|\lambda \mu \rangle).
\]

(70b)

A first step in the construction of a VCS representation of SU(3) extends this highest-weight state \( |\lambda \mu \rangle \) to a set of so-called highest-grade states. These are states that are annihilated by the commuting \( \hat{C}_{12} \) and \( \hat{C}_{13} \) raising operators, but not by \( \hat{C}_{23} \), and are a basis for an irreducible representation of a U(2) \( \subset \) SU(3) subalgebra. This U(2) sualgebra contains the U(1) element

\[
\hat{Q}_{2,0} = 2 \hat{h}_1 + \hat{h}_2.
\]

(71)
and elements $\hat{L}_0$ and $\hat{Q}_{2,\pm 2}$ that commute with $\hat{Q}_{2,0}$. The latter elements satisfy the SU(2) commutation relations

$$[\hat{L}_0, \hat{Q}_{2,\pm 2}] = \pm 2 \hat{Q}_{2,\pm 2}, \quad [\hat{Q}_{2,2}, \hat{Q}_{2,-2}] = 6 \hat{L}_0,$$

(72)

and can be identified with standard SU(2) spin operators

$$\hat{L}_0 \equiv 2 \hat{\sigma}_0, \quad \hat{Q}_{2,\pm 2} \equiv \sqrt{6} \hat{\sigma}_\pm,$$

(73)

with commutation relations

$$[\hat{\sigma}_0, \hat{\sigma}_\pm] = \pm \hat{\sigma}_\pm, \quad [\hat{\sigma}_+, \hat{\sigma}_-] = 2 \hat{\sigma}_0,$$

(74)

Thus, the U(2) representation on the highest-grade states follows directly from the well-known representations of the SU(2) spin algebra.

Let $\{(|\lambda\mu\rangle K)\}$ denote an orthonormal basis of highest-grade states for a U(3) representation defined by the equations

$$\hat{C}_{ij}|(\lambda\mu)K\rangle = 0,$$

(75)

for $j = 2, 3$ and

$$\hat{L}_0|(\lambda\mu)K\rangle = K|(\lambda\mu)K\rangle,$$

(76)

for $K = -\frac{1}{2} \mu, -\frac{1}{2} \mu + 1, \ldots, \frac{1}{2} \mu$, and let $\{\xi_k\}$ denote an equivalent set of spin states. The relationship (73) then implies that these spin states satisfy the equations

$$\hat{\sigma}_0 \xi_k = \frac{1}{2} K \xi_k,$$

(77a)

$$\hat{\sigma}_+ \xi_k = \frac{1}{2} \sqrt{(\mu + K)(\mu + K + 2)} \xi_{k+2},$$

(77b)

$$\hat{\sigma}_- \xi_k = (2\lambda + \mu) \xi_k,$$

(77c)

and that the highest-grade states satisfy the corresponding equations

$$\hat{L}_0|(\lambda\mu)K\rangle = K|(\lambda\mu)K\rangle,$$

(78a)

$$\hat{Q}_{2,\pm 2}|(\lambda\mu)K\rangle$$

$$= \begin{pmatrix} \sqrt{2}(\mu + K)(\mu + K + 2) \end{pmatrix}^{\frac{1}{2}} (|\lambda\mu\rangle K \pm 2),$$

(78b)

$$\hat{Q}_{2,0}|(\lambda\mu)K\rangle = (2\lambda + \mu)|\lambda\mu\rangle K\rangle.$$
for the angular-momentum operators. The VCS representation of the SU(3) quadrupole operator is defined by the equation

\[ \Gamma(Q_{2,\nu})\Psi_{\alpha N}^{(\lambda)}(\Omega) = \sum_{\Omega'} \xi_{K} \langle (\lambda\mu)K | \hat{R} | \hat{Q}_{2,\nu} | (\lambda\mu)\alpha LM \rangle \]

\[ = \sum_{\nu'} \xi_{K} \langle (\lambda\mu)K | \hat{Q}_{2,\nu'} | \hat{R} | \hat{Q}_{2,\nu} | (\lambda\mu)\alpha LM \rangle \]

\[ \times \langle (\lambda\mu)\alpha LM | \hat{Q}_{2,\nu'} | (\lambda\mu)\alpha LM \rangle, \]

(88)

By making the substitutions

\[ \langle (\lambda\mu)K | \hat{Q}_{2,0} | (\lambda\mu)K \rangle = (2\lambda + \mu) \Psi_{\alpha N}^{(\lambda)}(\Omega), \]

(89a)

\[ \langle (\lambda\mu)K | \hat{Q}_{2,\pm 1} | (\lambda\mu)K \rangle = - \sqrt{3 \over 2}\xi_{K} \hat{L}_{\pm} \Psi_{\alpha N}^{(\lambda)}(\Omega), \]

(89b)

\[ \langle (\lambda\mu)K | \hat{Q}_{2,\pm 2} | (\lambda\mu)K \rangle = \sqrt{6} \xi_{K} \hat{J}_{\pm} \Psi_{\alpha N}^{(\lambda)}(\Omega), \]

(89c)

of which the first two are obtained from equations (63)–(64) and the observation from (75) that

\[ \langle (\lambda\mu)K | \hat{C}_{21} | (\lambda\mu)K \rangle \hat{C}_{31} = 0 \]

(90)

and the third is obtained from a comparison of equations (78) and (68), it follows that

\[ \sum_{K} \xi_{K} \langle (\lambda\mu)K | \hat{Q}_{2,0} | \hat{R} | \hat{Q}_{2,0} | (\lambda\mu)\alpha LM \rangle \]

\[ = (2\lambda + \mu) \Psi_{\alpha N}^{(\lambda)}(\Omega), \]

(91a)

\[ \sum_{K} \xi_{K} \langle (\lambda\mu)K | \hat{Q}_{2,\pm 1} | \hat{R} | \hat{Q}_{2,0} | (\lambda\mu)\alpha LM \rangle \]

\[ = - \sqrt{3 \over 2}\xi_{K} \hat{L} \Psi_{\alpha N}^{(\lambda)}(\Omega), \]

(91b)

\[ \sum_{K} \xi_{K} \langle (\lambda\mu)K | \hat{Q}_{2,\pm 2} | \hat{R} | \hat{Q}_{2,0} | (\lambda\mu)\alpha LM \rangle \]

\[ = \sqrt{6} \xi_{K} \hat{J} \Psi_{\alpha N}^{(\lambda)}(\Omega), \]

(91c)

where \( L_{\pm} \) are infinitesimal generators of left rotations. Their actions, defined by

\[ [L_{\pm} \hat{\Phi}_{KM}](\Omega) = (L_{\pm} K)\hat{\Phi}_{KM}(\Omega) \]

\[ = \sum_{N} (L_{\pm} K)\hat{\Phi}_{LN} \hat{\Phi}_{KM}(\Omega), \]

(92)

give the expressions, familiar in the nuclear rotor model

\[ L_{\pm} \hat{\Phi}_{KM} = K \hat{L}_{\pm} \hat{\Phi}_{KM}, \]

(93a)

\[ L_{\pm} \hat{\Phi}_{KM} = \sqrt{(L_{\pm} K)(L_{\pm} K + 1)} \hat{L}_{\pm} \hat{\Phi}_{KM}, \]

(93b)

Thus, equations (88) and (91) lead to the expression

\[ \hat{\Gamma}(Q_{2,\nu}) = (2\lambda + \mu) \hat{J}_{\nu} - \sqrt{3 \over 2} (\hat{J}_{1,\nu} \hat{L} + \hat{J}_{-1,\nu} \hat{L}) \]

\[ + \sqrt{6} [\hat{J}_{\nu} \hat{J}_{\nu} + \hat{J}_{\nu} \hat{J}_{-\nu}] \]

(94)

which simplifies, by use of the identity

\[ [\hat{L}^{2}, \hat{J}_{\nu}^{2}] = 6 \hat{J}_{\nu}^{2} + 2 {\sqrt{3 \over 2}} [\hat{J}_{\nu}^{2} \hat{L} + \hat{J}_{-\nu}^{2} \hat{L}], \]

(95)

to equation (65).

7.3. SU(3) transformations of rotor-model wave functions

The transformations of the rotor-model wave functions \( \psi_{\alpha N}^{(\lambda)} \) by the \( \hat{\Gamma}(Q_{2,\nu}) \) operators given by equation (65) are determined by use of the equations

\[ \hat{\Gamma}(Q_{2,\nu}) \hat{\Psi}_{\alpha N}^{(\lambda)}(\Omega) = (L_{\pm} K) \hat{\Psi}_{\alpha N}^{(\lambda)}(\Omega) \]

\[ = \sum_{\beta} \langle (\beta\lambda\mu)L | (\lambda\mu)\alpha LM \rangle \hat{J}_{\nu} \hat{\Psi}_{\alpha N}^{(\lambda)}(\Omega), \]

(96)

\[ \hat{\Gamma}(Q_{2,\nu}) \hat{\Psi}_{\alpha N}^{(\lambda)}(\Omega) = \frac{1}{2 \sqrt{2L + 1}} \sum_{\mu} \langle (\lambda\mu)\alpha L' | (\lambda\mu)\alpha L \rangle \hat{J}_{\nu} \hat{\Psi}_{\alpha N}^{(\lambda)}(\Omega), \]

(97)

from which it follows that

\[ \hat{\Gamma}(Q_{2,\nu}) \hat{\Psi}_{\alpha N}^{(\lambda)}(\Omega) = \frac{2L + 1}{2L + 1} \sum_{\mu} \langle (\lambda\mu)\alpha L' | (\lambda\mu)\alpha L \rangle \hat{J}_{\nu} \hat{\Psi}_{\alpha N}^{(\lambda)}(\Omega), \]

(98)

with

\[ M_{\nu \mu}^{KL} = \left[ (2\lambda + \mu + 3) - \frac{1}{2} (L' + 1) \right] \hat{J}_{\nu} \hat{\Psi}_{\alpha N}^{(\lambda)}(\Omega), \]

\[ \times \left[ 2L + 1 \right] \left[ \hat{\Psi}_{\alpha N}^{(\lambda)}(\Omega) \right] \]

(99a)

\[ M_{\nu \mu}^{KL} = \frac{1}{2 \sqrt{2L + 1}} \left[ \hat{\Psi}_{\alpha N}^{(\lambda)}(\Omega) \right], \]

\[ \times \left[ 2L + 1 \right] \left[ \hat{\Psi}_{\alpha N}^{(\lambda)}(\Omega) \right], \]

(99b)

7.4. SO(3)-reduced matrix elements for SU(3) representations of type \( (\lambda 0) \) and \( (\lambda 1) \)

SO(3)-reduced matrix elements are now obtained from the expression

\[ \hat{\Gamma}(Q_{2,\nu}) \hat{\Psi}_{\alpha N}^{(\lambda)}(\Omega) = \sum_{\beta} \langle (\beta\lambda\mu)L | (\lambda\mu)\alpha L \rangle \hat{J}_{\nu} \hat{\Psi}_{\alpha N}^{(\lambda)}(\Omega), \]

(100)

of the Wigner–Eckart theorem in an orthonormal basis.

For a \( (\lambda 0) \) representation, for which the multiplicity index \( \alpha \) of an SU(3) wave function \( \psi_{\alpha N}^{(\lambda)} \) is not needed, \( K = 0 \) is a good quantum number and an orthonormal set of basis wave functions is of the form

\[ \psi_{\alpha N}^{(\lambda)} = k_{\lambda} \Psi_{\lambda K}^{(\lambda 0)} \]

(101)

where \( k_{\lambda} \) is a norm factor and \( L \) is restricted to even or odd integers according as \( \lambda \) is even or odd. Equations (65) and (98) then lead to the reduced matrix elements

\[ \langle (\lambda 0)\alpha L' | \hat{\Psi}_{\lambda K}^{(\lambda 0)} | (\lambda 0)\alpha L \rangle = k_{\lambda} \left[ \frac{1}{2 \sqrt{2L + 1}} \left( 2L + 1 \right) (L \alpha L') \right], \]

(102)

and

\[ \langle (\lambda 0)\alpha L | \hat{\Psi}_{\lambda K}^{(\lambda 0)} | (\lambda 0)\alpha L \rangle = \frac{1}{2 \sqrt{2L + 1}} \left( 2L + 1 \right) (L \alpha L'), \]

(103a)
\[
\langle (\lambda 0) L + 2 | \hat{Q}_2 | (\lambda 0) L \rangle = 2 \frac{k_{L+2}}{k_L} \sqrt{2L + 1} \left( \lambda - L \right)
\times \left( L 0 20|L + 2, 0 \right),
\]
\[
\langle (\lambda 0) L | \hat{Q}_2 | (\lambda 0) L + 2 \rangle = 2 \frac{k_{L+2}}{k_L} \sqrt{2L + 5} \left( \lambda + L + 3 \right)
\times \left( L + 2, 0 20|L0 \right) = 2 \frac{k_{L+2}}{k_L} \sqrt{2L + 1}
\times \left( \lambda + L + 3 \right) \left( L 0 20|L + 2, 0 \right).
\]

Thus, to satisfy the Hermiticity relations, as required for a unitary representation
\[
\langle (\lambda 0) L^* | \hat{Q}_2 | (\lambda 0) L \rangle = \langle (\lambda 0) L | \hat{Q}_2 | (\lambda 0) L^* \rangle
\]
the norm factors must have ratios
\[
\left| \frac{k_{L+2}}{k_L} \right|^2 = \frac{\lambda - L}{\lambda + L + 3}.
\]

It follows that, for \( L \leq \lambda \),
\[
\langle (\lambda 0) L + 2 | \hat{Q}_2 | (\lambda 0) L \rangle = \langle (\lambda 0) L | \hat{Q}_2 | (\lambda 0) L + 2 \rangle
\]
\[
= \left[ 4(2L + 1)(\lambda - L)(\lambda + L + 3) \right]^{1/2}
\times \left( L 0 20|L + 2, 0 \right)
\]
and the sequence of increasing angular-momentum states terminates at \( L = \lambda \).

For a \( (\lambda 1) \) representation, one similarly obtains
\[
\langle (\lambda 1) L | \hat{Q}_2 | (\lambda 1) L \rangle = \sqrt{2L + 1} (2\lambda + 4)(L 0 20|L0)
\]
\[
- (-1)^{\lambda+1} \sqrt{6} \left( L - 1 2|L1 \right),
\]
\[
\langle (\lambda 1) L + 1 | \hat{Q}_2 | (\lambda 1) L \rangle = \sqrt{2L + 1} (L 1 20|L + 1, 1)
\]
\[
\times \left[ 2\lambda - L + 3 + (-1)^{\lambda+1} (L + 1) \right]^{1/2}
\times \left[ 2\lambda + L + 5 - (-1)^{\lambda+1} (L + 1) \right]^{1/2},
\]
\[
\langle (\lambda 1) L + 2 | \hat{Q}_2 | (\lambda 1) L \rangle = \sqrt{2L + 1} (L 1 20|L + 2, 1)
\]
\[
\times \left[ 2\lambda - 2L + 1 - (-1)^{\lambda+1} \right]^{1/2}
\times \left[ 2\lambda + 2L + 7 - (-1)^{\lambda+1} \right]^{1/2},
\]
consistent with the termination of the sequence of states at \( L = \lambda + 1 \).

7.5. \textit{SO}(3)-reduced matrix elements for \textit{SU}(3) representations \((\lambda, \mu)\) with \( \mu > 1 \)

The above multiplicity-free examples, highlight the fact that the Hermiticity relationships make it straightforward to re-normalise an orthogonal basis to obtain an orthonormal basis. An orthogonal basis for an irreducible representation of \textit{SU}(3) can be defined generally by the eigenstates of the \textit{SO}(3)-invariant operator \( \hat{X}_3 = [\hat{L} \otimes \hat{Q}_2 \otimes \hat{L}_3] \) (or for a closer relationship with the rotor model, as discussed in the following section, by a particular linear combination of the \textit{SO}(3)-invariants \( \hat{X}_3 \) and \( \hat{X}_4 = [\hat{L} \otimes (\hat{Q} \otimes \hat{Q}_2) \otimes \hat{L}_3] \)).

For an orthonormal basis of eigenstates of the operator \( \hat{X}_3 = [\hat{L} \otimes \hat{Q}_2 \otimes \hat{L}_3] \), the VCS wave functions satisfy the equation
\[
\hat{\Gamma}(\hat{X}_3) | \Psi^{(\lambda\mu)}_{aLM} \rangle = \psi^{(\lambda\mu)}_{aLM}(L \hat{\otimes} \hat{Q}_2 \hat{\otimes} \hat{L}_3) (L \mu aL) \]
\[
\sqrt{2L + 1} = \psi^{(\lambda\mu)}_{aLM}(L \hat{\otimes} \hat{Q}_2 \hat{\otimes} \hat{L}_3) (L \mu aL),
\]
with \( f(L) = \sqrt{(L + 1)(2L + 1)(2L + 3)} \). This implies that the reduced matrix elements \( \langle (\lambda\mu) \beta L^* | \hat{Q}_2 | (\lambda\mu) \alpha L \rangle \), defined by the Wigner–Eckart theorem (100), should be diagonal when \( L' = L \), i.e., vanish if \( L' \neq L \) but \( \beta \neq \alpha \).

The first step of a so-called \( \mathcal{K} \)-matrix transformation
\[
\psi^{(\lambda\mu)}_{aLM}(\Omega) = \sum_K \psi^{(\lambda\mu)}_{aLM}(K) \psi^{(\lambda\mu)}_{aLM},
\]
on to an orthonormal basis \( \{ \psi^{(\lambda\mu)}_{aLM} \} \) is to construct an orthogonal set of functions \( \{ \psi^{(\lambda\mu)}_{aLM} \} \) (with Greek index \( \alpha \)) by a unitary transformation
\[
\psi^{(\lambda\mu)}_{aLM} = \sum_K \psi^{(\lambda\mu)}_{aLM} \psi^{(\lambda\mu)}_{aLM},
\]
of the rotor-model wave functions \( \{ \psi^{(\lambda\mu)}_{aLM} \} \) of equation (66), where \( U^L \) is the unitary matrix that diagonalises the matrix \( M^L_{LL} \) given by equations (99a) and (99b). It then only remains to renormalise this set to obtain orthonormal basis states, with VCS wave functions
\[
\psi^{(\lambda\mu)}_{aLM}(K) = k_L \psi^{(\lambda\mu)}_{aLM},
\]
that satisfy the Hermiticity relations
\[
\langle (\lambda\mu) \beta L^* | \hat{Q}_2 | (\lambda\mu) \alpha L \rangle = (-1)^{L' - L} \langle (\lambda\mu) \beta L^* | \hat{Q}_2 | (\lambda\mu) \alpha L \rangle
\]
of a unitary representation.

An expansion of the left side of equation (100) gives
\[
[\hat{\Gamma}(\hat{Q}_2) \otimes \psi^{(\lambda\mu)}_{aLM}]_{LM'} = k_{LM} \sum_K [\hat{\Gamma}(\hat{Q}_2) \otimes \psi^{(\lambda\mu)}_{aLM}]_{LM'} U^L_{LMK},
\]
and, with (98) followed by the inverse of (110),
\[
[\hat{\Gamma}(\hat{Q}_2) \otimes \psi^{(\lambda\mu)}_{aLM}]_{LM'} = k_{LM} \frac{2L + 1}{2L' + 1} \sum_{KK' \beta} \psi^{(\lambda\mu)}_{aLM} U^L_{LMK} U^L_{LMK'},
\]
consistent with the termination of the sequence of states at \( L = \lambda + 1 \).
and, from the Wigner–Eckart theorem (100), the reduced matrix element
\[
\langle (\mu \alpha L)\beta L' || \hat{Q}_2 \rangle (\lambda \beta L) = \frac{k_L^L}{k_{\beta}^L} \sqrt{2L + 1} \mathcal{M}_{3 \alpha}^{LL'}.
\]
with
\[
\mathcal{M}_{3 \alpha}^{LL'} = \sum_{K, K'} u_{K, L}^L u_{K', L}^{L'} \mathcal{M}_{K}^{L L'}.
\]
It likewise follows that
\[
\langle (\mu \alpha L) \beta L' || \hat{Q}_2 \rangle (\lambda \beta L) = \frac{k_L'^{L'}}{k_{\alpha}^L} \sqrt{2L' + 1} \mathcal{M}_{3 \alpha}^{LL'}.
\]
Thus, to satisfy the Hermiticity equation (112), it is required that
\[
\frac{k_L^L}{k_{\beta}^L} \sqrt{2L + 1} \mathcal{M}_{3 \alpha}^{LL'} = (-1)^{L-L'} \frac{k_L'^{L'}}{k_{\alpha}^L} \sqrt{2L' + 1} \mathcal{M}_{3 \alpha}^{LL'}
\]
which means that the renormalisation coefficients have ratios given by
\[
\left( \frac{k_{\beta}^L}{k_{\alpha}^L} \right)^2 = (-1)^{L-L'} \frac{2L + 1}{2L' + 1} \frac{\mathcal{M}_{3 \alpha}^{LL'}}{\mathcal{M}_{3 \alpha}^{LL'}}.
\]
The ratios found in this expression are easily determined recursively, starting from the state of the representation of angular momentum \( L = 0 \) or \( L = 1 \), which is always multiplicity free and for which one can set \( k_{\beta}^L = 1 \). This expression yields normalisation factors \( k_{\beta}^L \) for those states with non-vanishing norms within the SU(3) representation under construction while those states for which \( k_{\beta}^L \) vanishes are simply discarded.

8. Macroscopic limits of the SU(3) model

Large-dimensional limits of the SU(3) model have been considered by many authors [111, 119–124]. In such limits, the properties of an SU(3) representation asymptotically approach those of a rigid-rotor model. We refer to these, and more precise limits brought to light by VCS representations [110, 111], as macroscopic limits. They are easily calculated and are valuable for assessing the relevance of particular SU(3) representations in potential applications, e.g., as discussed in section 11.1. This section examines the intimate relationship between the rigid-rotor and the SU(3) model in its macroscopic limits and shows how closely accurately computed results for finite-dimensional SU(3) representations approach their asymptotic limits.

It is first shown that, in the limit in which the value of its Casimir invariant is large, an irreducible representation of the SU(3) algebra contracts to that of a rigid-rotor model with intrinsic quadrupole moments
\[
\tilde{Q}_0 = (2\lambda + \mu + 3), \quad \tilde{Q}_2 = \sqrt{\frac{2}{3}} (\mu + 1).
\]
It is then shown that an exceedingly close approach of SU(3) states to rotor-model states with integer-valued \( K \) quantum numbers is given by eigenstates of the operator
\[
\hat{Z}^{(\mu)} = \hat{L} \otimes [\hat{Q}_2 \otimes \hat{Q}_2 \otimes \hat{L}]_0 - \sqrt{\frac{2}{3}} \hat{Q}_0 [\hat{L} \otimes \hat{Q}_2 \otimes \hat{L}]_0.
\]
It also shown that precise SU(3) matrix elements are approached rapidly for \( L/\lambda < 0.4 \) by those of a rotor with the intrinsic quadrupole moments given by equation (121) and, as shown in section 8.3, even more rapidly by the asymptotic expressions
\[
\langle (\mu \alpha L) || \hat{Q}_2 || (\lambda \beta L) \rangle (\lambda \beta L) = \sqrt{2L + 1} \times (LK 20[LK] \hat{Q}_0 + \delta_{K,1}\Delta^{LL}),
\]
where \( \hat{Q}_0 = 2\lambda + \mu + 3 \) and
\[
\Delta^{LL} = (-1)^{L+1} \frac{2}{\sqrt{3}} (\mu + 1) \frac{(L_3 - 1)2[L/1]}{(L1 20[L/1])}.
\]
8.1. Contraction of an SU(3) irrep

A standard contraction [48] of the SU(3) Lie algebra is obtained with renormalised quadrupole moments
\[
q_{2\nu} = \varepsilon Q_{2\nu},
\]
where \( \varepsilon \) is a small parameter. In terms of these quadrupole moments, the SU(3) commutation relations become
\[
[L_k, L_{k'}] = \sqrt{2} (1k' 1k | L + 1), \quad L_{k+k}',
\]
\[
[L_4, q_{2\mu}] = \sqrt{6} (2\nu 1k | L + \nu), \quad q_{2\mu+k'},
\]
\[
[q_{2\mu} + q_{2\nu}] = -3 \sqrt{10} (2\mu 2\nu | L + \nu), \quad \varepsilon^2 L_{\mu + \nu} = O(\varepsilon^2).
\]
The circumstances under which this contraction is realised are obtained by setting $\varepsilon^2 = 1/I_2(\lambda \mu)$ \cite{38,119}, where

$$I_2(\lambda \mu) = \langle \hat{Q}_2 \cdot \hat{Q}_2 + 3 \hat{L} \cdot \hat{L} \rangle = 4(\lambda^2 + \lambda \mu + \mu^2 + 3 \lambda + 3 \mu)$$ \hspace{1cm} (127)

is the value of the SU(3) Casimir invariant for the representation $(\lambda \mu)$, it follows that the $(q_{2,\mu})$ quadrupole moments of states of angular momentum $L$, for which $3L(L+1) \ll I_2(\lambda \mu)$, are normalised such that

$$\langle \hat{q}_2 \cdot \hat{q}_2 \rangle = \varepsilon^2 \langle \hat{Q}_2 \cdot \hat{Q}_2 \rangle \approx 1.$$ \hspace{1cm} (128)

However, the commutators $[q_{2,\mu}, q_{2,\mu}] = O(\varepsilon^2)$ become negligible. Thus, as $\varepsilon \to 0$, the SU(3) Lie algebra contracts to that of the rotor algebra (see section 3.1) with commuting quadrupole operators. The physical significance of this contraction is that states of low angular momentum of a large-dimensional irreducible SU(3) representation, for which $\varepsilon \ll 1$, are expected to exhibit rotor-model properties.

The deformation parameters of the rotor model to which a given SU(3) representation contracts \cite{122,123,125}, are obtained by comparing the shape invariants $Q_2 \cdot Q_2$ and $[Q_2 \otimes Q_2 \otimes Q_2]_0$ of a rotor with the corresponding SU(3) Casimir invariants. For a rotor with intrinsic quadrupole moments

$$\hat{Q}_0 = \beta \cos \gamma, \hspace{0.5cm} \hat{Q}_2 = \sqrt{7} \beta \sin \gamma,$$ \hspace{1cm} (129)

these invariants are given by

$$Q_2 \cdot Q_2 = \beta^2, \hspace{0.5cm} \sqrt{70} [Q_2 \otimes Q_2 \otimes Q_2]_0 = -2\beta^2 \cos 3\gamma.$$ \hspace{1cm} (130)

It is then determined that, with the intrinsic quadrupole moments

$$\hat{Q}_0 = (2\lambda + \mu + 3), \hspace{0.5cm} \hat{Q}_2 = \sqrt{7} (\mu + 1),$$ \hspace{1cm} (131)

the rotor-model invariants take the values

$$Q_2 \cdot Q_2 = (2\lambda + \mu + 3)^2 + 3\mu(\mu + 2) = 4(\lambda^2 + \lambda \mu + \mu^2 + 3 \lambda + 3 \mu + 3),$$ \hspace{1cm} (132)

$$\sqrt{70} [Q_2 \otimes Q_2 \otimes Q_2]_0 = -8(2\lambda + \mu + 3)(\lambda - \mu)(\lambda + 2\mu + 3),$$ \hspace{1cm} (133)

which, with neglect of the constant 3 on the right side of equation (132), are the values of the SU(3) Casimir invariants $\hat{T}_2$ and $\hat{T}_3$.

8.2. The $K$ quantum number

Given the close relationship between the SU(3) and rotor models, it was natural to seek an optimal one-to-one correspondence between states of an irreducible SU(3) representation and a subset of rotor model states with good $K$ quantum numbers. Rosensteel, Leschber and colleagues \cite{122,126} suggested that the SU(3) states of the corresponding pairs should be eigenstates of some linear combination of the SO(3)-invariant operators $[\hat{L} \otimes \hat{Q}_2 \otimes \hat{L}]_0$ and $[\hat{L} \otimes [\hat{Q} \otimes \hat{Q}]_2 \otimes \hat{L}]_0$. This proved to be correct \cite{127} and, as this section shows, gives useful canonical SO(3)-coupled bases for irreducible SU(3) representations with extraordinarily good $K$ quantum numbers.

It has been shown \cite{127} that rotor model states with good $K$ quantum numbers and for which the intrinsic quadrupole moments take the constant $K$-independent values

$$\langle \xi_k | \hat{Q}_{2,0} | \xi_k \rangle = \hat{Q}_0, \hspace{0.5cm} \langle \xi_{k+\pm2} | \hat{Q}_{2,\pm2} | \xi_k \rangle = \hat{Q}_2,$$ \hspace{1cm} (134)

are eigenstates of the operator

$$\hat{Z}^{(\text{rot})} = |L \otimes \hat{Q}_2 \otimes \hat{Z}_2| \otimes \hat{L}_0,$$

$$-\sqrt{\frac{5}{7}} \hat{Q}_0 |L \otimes \hat{Q}_2 \otimes \hat{L}_0|.$$ \hspace{1cm} (135)

This was shown by observing that, for such a generally triaxial rotor, the ratios

$$R(K', L, K) = \frac{|K' L| |\hat{Q}_2 \otimes \hat{Q}_2| |KL|}{|K' L||\hat{Q}_2||KL|}$$ \hspace{1cm} (136)

have the $L$- and $K$-independent off-diagonal values

$$R(K + 2, L, K) = \sqrt{\frac{5}{7}} \hat{Q}_0.$$ \hspace{1cm} (137)

for all $L$ and $K$. This implies that standard rotor-model states $[|KLM\rangle_0]$, with good $K$ quantum numbers, are eigenstates of the operator $\hat{Z}^{(\text{rot})}$ of (135). Thus, an approach of an SU(3) state of angular momentum $L$ to a state with a good $K$ quantum number, which becomes precisely that of the rotor model in a $\lambda/L \to \infty$ asymptotic limit, can be defined as an eigenstate of the operator $\hat{Z}^{(\text{rot})}$ of equation (122).

Recall that SU(3) states with the same $L, M$ angular-momentum values were distinguished in the VCS construction of section 7.5 by choosing them to be eigenstates of the third-order SO(3)-invariant operator $[|KLM\rangle]$ , with good $K$ quantum numbers, one has simply to adjust the VCS construction by replacing this operator with the linear combination $\hat{Z}^{(\text{rot})}$ of the third- and fourth-order SO(3) invariants. There should then be far less mixing of rotor model wave functions in the construction of orthonormal SU(3) states. The mean values of the $K$ quantum numbers

$$\langle K \rangle_{\alpha L} = \sum_K |K \rangle_{\alpha K} |K \rangle_{\alpha L},$$ \hspace{1cm} (138)

where $|K \rangle_{\alpha K}$ are the coefficients in the expansion (109) for a range of SU(3) eigenstates of $\hat{Z}^{(\text{rot})}$ are shown in table 1 for two SU(3) representations, (70 6) and (70 7), typical of those appropriate for rare-Earth nuclei and one, (10 4), that is more typical for a light nucleus. They are seen to be astonishingly close to corresponding integer rotor-model values with the exception of those for a few states in the upper angular-momentum ranges of the finite-dimensional SU(3) bands. Also shown are the quadrupole moments of these states in comparison with their rotor-model values.

It will be noted that the rotor contraction limit is expected to be valid when both $\lambda/L$ and $\mu/L$ take large values. However, assuming that $\lambda \gg \mu$, the asymptotic limit only requires $\lambda/L$ to be large. Results are shown for both even and
odd values of $\mu$ because it is known that in the rotor-model description of a $K = 1$ band, which occurs only in SU(3) for odd $\mu$, the matrix elements of the quadrupole operators connect intrinsic states with $K = \pm 1$ and, as a consequence, show different properties to those of other bands. It is in fact necessary to include the cross-over intrinsic terms in both the precise and asymptotic limits to get the good agreement shown in table 1.

Results are shown for large values of $\lambda$ and small values of $\mu$, typical of the values appropriate for applications in rare-Earth nuclei. They are also shown for a (10 4) representation for which one would not expect the results of the contraction limit to be accurate for any but the lowest values of $L$. Thus, it is quite remarkable to discover the extent to which $K$ remains a good quantum number for this representation until the point at which the bands reach their upper bounds; i.e., for $L \leq 10$ for the (10 4) representation.

8.3. Comparison of asymptotic and exact SU(3) matrix elements

The results of table 1 show that, when orthonormal basis states for an SU(3) irrep are given by eigenstates of the Hermitian operator $\hat{Q}_{\mu \lambda}^A$, the $K$ quantum numbers are defined and rapidly approach the integer values matching those of the rotor model for even modestly large values of $\lambda/L$. Thus, one obtains asymptotic limits, that should be more accurate than the contraction limits, from the observation that the SU(3) wave functions are given accurately to within normalisation factors by good K rotor-model wave functions. The asymptotic limits that result are given by equations (123)-(124). In fact, the contraction and asymptotic limits of the diagonal matrix elements $(\langle \lambda \mu \rangle KL \mid \hat{Q}_{\mu \lambda}^A \mid \langle \lambda \mu \rangle KL)$ coincide and both are given by equation (123a).

Transition matrix elements, given by the rotor contraction and the higher-order asymptotic expressions (123b)-(124), are compared with accurately computed matrix elements in table 2, again for the irreps (70 6), (70 7) and (10 4). For the large in-band transitions, the matrix element of the rotor contraction limit are seen to be remarkably accurate and the higher-order asymptotic limit are as good as exact for all matrix elements shown with the only exceptions being for the $\Delta L = 1$ in-band transitions of the $K = 1$ band; note the comparisons for the $L = 29, K = 1$ to $L = 30, K = 1$ matrix elements for the (70 7) representation.

$K = 1$ bands are special both in SU(3) and in the rotor model because it is only for such a band that there is a matrix element of a quadrupole operator between the $K = \pm 1$ intrinsic states; it is given by the $\Delta^L$ terms in equations (123)-(124). Thus, for an in-band $K = 1$ matrix element there are two contributing terms which for a $\Delta L = 1$ matrix element are of opposite sign. In a situation in which they of near equal magnitude, the error in their difference, as given by their asymptotic values, can then be relatively large. This cancellation of terms of opposite sign is exhibited for $\Delta L = 1$ in-band $K = 1$ transition matrix elements in more detail in the lower part of table 2. Note that, in contrast, the two terms contributing to $\Delta L = 2$ transition matrix between $K = 1$ states are of the same sign and their sum is large and given to a high level of accuracy.

There is also a second reason for larger differences between the precise and asymptotic values of interband transition matrix elements for SU(3) irreps with $\mu \ll \lambda$. It arises because, although the mixing of states of different integer-$K$ values is exceedingly small in appropriately defined SU(3) states, the huge difference in the magnitudes of the $K$-conserving matrix elements relative to the $K$-changing matrix elements, means that the mixing has an exaggerated effect on the magnitude of the interband matrix elements. Thus, in general, the smaller inter-band matrix elements are expected to be given considerably less accurately by their asymptotic limits than the large matrix elements as is seen to be the case.

9. Representations of $Sp(3, \mathbb{R})$ in a U(3) basis

As defined in section 4, the $Sp(3, \mathbb{R})$ Lie algebra comprises elements of a U(3) subalgebra and giant-monopole and giant-quadrupole raising and lowering operators. Thus, an irreducible $Sp(3, \mathbb{R})$ representation is defined by a set of
so-called lowest-grade states that are annihilated by the giant-
resonance lowering operators and are a basis for an irre-
ducible $U(3)$ representation. Basis states for the $Sp(3, \mathbb{R})$
representation are then generated by acting repeatedly on
these lowest-grade $U(3)$ states with the giant-resonance rais-
ing operators $\hat{A}_i$. Matrix elements for such a representation
were first derived by use of recursion relations [128] and
subsequently by VCS methods [98, 99].

This section outlines the VCS construction. It starts with
a basis of lowest-grade states $\{|w_0(\alpha)\rangle\}$ for the desired
$Sp(3, \mathbb{R})$ representation. These states transform under $U(3)$ as

\[
\Psi(z) = \sum_\alpha \Psi^{w_0}_\alpha \langle w_0(\alpha)| \exp \left[ \frac{1}{2} \sum_{ij} z_{ij} \hat{B}_{ij} \right] |\psi\rangle, \tag{139}
\]

where $z = \{z_{ij} = \bar{z}_{ij}\}$ is a set of 6 complex variables.

Section 9.1 shows that, in this VCS representation, the
elements of the $Sp(3, \mathbb{R})$ Lie algebra, as defined in

\[
\begin{array}{cccccc}
\langle \lambda \mu \rangle & K^{\text{rot}}_{ij} & L_f & K^{\text{rot}}_{ik} & L_i & L_f/\langle \Psi^{\text{AL}}_{\mu} \rangle \langle \Psi^{\text{L}}_{\rho} \rangle \langle \Psi^{\text{Q}}_{\lambda} \rangle \\
\hline
(70 6) & 0 & 10 & 0 & 8 & 0.14 & 397.170 \quad 393.928 \quad 393.919 \\
& 0 & 10 & 2 & 8 & 0.14 & 10.407 \quad 10.301 \quad 10.385 \\
& 2 & 10 & 2 & 8 & 0.14 & 379.415 \quad 376.318 \quad 376.311 \\
& 2 & 10 & 4 & 8 & 0.14 & 4.249 \quad 3.839 \quad 3.867 \\
& 4 & 10 & 6 & 8 & 0.14 & 1.967 \quad 1.376 \quad 1.385 \\
& 0 & 30 & 2 & 29 & 0.43 & 45.365 \quad 44.900 \quad 45.808 \\
& 2 & 30 & 2 & 29 & 0.43 & 94.078 \quad 92.152 \quad 92.111 \\
& 2 & 30 & 4 & 29 & 0.43 & 29.730 \quad 26.861 \quad 27.402 \\
& 4 & 30 & 6 & 29 & 0.43 & 27.276 \quad 19.089 \quad 19.460 \\
& 0 & 30 & 0 & 28 & 0.43 & 700.754 \quad 643.476 \quad 643.290 \\
& 0 & 30 & 2 & 28 & 0.43 & 21.700 \quad 21.478 \quad 23.425 \\
& 2 & 30 & 2 & 28 & 0.43 & 697.530 \quad 640.516 \quad 640.379 \\
& 2 & 30 & 4 & 28 & 0.43 & 13.263 \quad 11.983 \quad 12.996 \\
& 4 & 30 & 6 & 28 & 0.43 & 11.333 \quad 7.932 \quad 8.593 \\
(70 7) & 1 & 20 & 1 & 19 & 0.29 & 27.111 \quad 25.981 \quad 26.340 \\
& 1 & 22 & 1 & 21 & 0.31 & 22.895 \quad 21.405 \quad 21.984 \\
& 1 & 24 & 1 & 23 & 0.34 & 19.092 \quad 17.103 \quad 18.032 \\
& 1 & 30 & 1 & 29 & 0.43 & 9.487 \quad 0.000 \quad 7.948 \\
& 1 & 30 & 3 & 29 & 0.43 & 35.336 \quad 34.214 \quad 34.271 \\
& 3 & 30 & 3 & 29 & 0.43 & 141.668 \quad 138.806 \quad 138.967 \\
& 3 & 30 & 5 & 29 & 0.43 & 32.588 \quad 28.222 \quad 28.799 \\
& 1 & 30 & 1 & 28 & 0.43 & 685.855 \quad 627.359 \quad 627.034 \\
& 1 & 30 & 3 & 28 & 0.43 & 16.325 \quad 15.807 \quad 16.493 \\
& 3 & 30 & 3 & 28 & 0.43 & 698.155 \quad 641.881 \quad 641.850 \\
& 3 & 30 & 5 & 28 & 0.43 & 14.03 \quad 12.153 \quad 13.173 \\
(10 4) & 0 & 2 & 0 & 0 & 0.00 & 27.000 \quad 26.833 \quad 26.823 \\
& 2 & 2 & 0 & 0 & 0.20 & 8.660 \quad 8.485 \quad 8.516 \\
& 0 & 4 & 0 & 2 & 0.40 & 43.296 \quad 41.816 \quad 41.743 \\
& 2 & 4 & 0 & 2 & 0.40 & 8.964 \quad 8.783 \quad 9.081 \\
& 4 & 4 & 0 & 2 & 0.40 & 0 \quad 0 \quad 0.003 \\
& 0 & 8 & 0 & 6 & 0.80 & 63.894 \quad 53.126 \quad 52.406 \\
& 2 & 8 & 0 & 6 & 0.80 & 10.607 \quad 10.392 \quad 12.629 \\
& 4 & 8 & 0 & 6 & 0.80 & 0 \quad 0 \quad 0.158 \\
& 2 & 8 & 2 & 6 & 0.80 & 59.286 \quad 49.295 \quad 48.911 \\
(70 7) & 1 & 26 & 1 & 25 & 0.37 & 15.625 \quad 12.890 \quad 14.409 \\
& 1 & 28 & 1 & 27 & 0.40 & 12.438 \quad 8.409 \quad 11.062 \\
& 1 & 30 & 1 & 29 & 0.43 & 9.487 \quad 0.000 \quad 7.948 \\
& 1 & 32 & 1 & 31 & 0.46 & 6.736 \quad -7.115 \quad 5.036 \\
& 1 & 34 & 1 & 33 & 0.49 & 4.159 \quad -9.204 \quad 2.304 \\
& 1 & 36 & 1 & 35 & 0.51 & 1.732 \quad -10.247 \quad -0.266 \\
& 1 & 38 & 1 & 37 & 0.54 & -0.562 \quad -10.662 \quad -2.684 \\
\end{array}
\]
section 4.1, are realised as operators of the form
\begin{align}
\hat{\Gamma}(C_{ij}) &= \hat{C}_{ij} + (z \nabla)_{ij}, \quad (140a)
\hat{\Gamma}(B_{ij}) &= \nabla_{ij}, \quad (140b)
\hat{\Gamma}(A_{ij}) &= \{\hat{A}, \hat{z}_{ij}\}, \quad (140c)
\end{align}
where \(\hat{C}_{ij}\) is the representation of the U(3) element \(\hat{C}_{ij}\) on the space of lowest-grade states, \(\{\nabla_{ij} = (1 + \delta_{ij})/\partial\partial z_{ij}\}\) and \(\{z_{ij}\}\) satisfy the commutation relations
\begin{equation}
[\nabla_{ij}, z_{kl}] = \delta_{ik} \delta_{lj} + \delta_{il} \delta_{kj}, \quad (141)
\end{equation}
\(\hat{\Lambda}\) is a U(3) scalar operator
\begin{equation}
\hat{\Lambda} = \frac{1}{2}(\hat{C} + z \nabla) \cdot (\hat{C} + z \nabla) - \frac{1}{4}(\nabla^2 - \hat{z} \cdot \nabla - \nabla \cdot \hat{z}) \quad (142)
\end{equation}
that is diagonal in a U(3)-coupled basis for the representation, \(z \nabla\) is a tensor with components \(\{\nabla_{ij}\} = \sum_k z_{ik} \nabla_{jk}\) and \(z \cdot \nabla = \sum_k (\nabla_k z_k)\).

The six variables \(z_{ij}\) and the corresponding derivative operators \(\nabla_{ij}\) in these expressions can be regarded as coherent-state representations of boson operators, \(a_{ij}^\dagger\) and \(a_{ij}\), with commutation relations
\begin{equation}
[a_{ij}, a_{kl}^\dagger] = \delta_{ik} \delta_{lj} + \delta_{il} \delta_{kj}. \quad (143)
\end{equation}

The linear combinations
\begin{align}
s^i &= \sqrt{\frac{1}{6}} \sum_i a_{ij}^\dagger, \quad s = \sqrt{\frac{1}{6}} \sum_i a_{ij}, \quad (144a)
d_0^i &= \sqrt{\frac{1}{12}} (2a_{11}^i - a_{22}^i - a_{33}^i), \quad (144b)
d_0 &= \sqrt{\frac{1}{12}} (2a_{11} - a_{22} - a_{33}), \quad (144c)
d_{1\pm}^i &= \mp \sqrt{\frac{1}{3}} (a_{11}^i \pm ia_{12}^i), \quad (144d)
d_{2\pm} &= \mp \sqrt{\frac{1}{3}} (a_{12}^i \pm ia_{13}^i), \quad (144e)
d_{12} &= \sqrt{\frac{1}{8}} (a_{12}^i - a_{13}^i \pm 2ia_{23}^i), \quad (144f)
d_{22} &= \sqrt{\frac{1}{8}} (a_{22} - a_{33} \mp 2ia_{23}), \quad (144g)
\end{align}
are then interpreted as the \(s (L = 0)\) and \(d (L = 2)\) boson raising and lowering operators of a Bohr model of monopole and quadrupole vibrations. The boson operators are also recognised as components of a U(3) \([2 \ 0 \ 0]\) tensor. Thus, the VCS algebra is understood in terms of representations of two simpler commuting algebras: the lowest-grade representation of U(3) and the representation of the boson algebra of the Bohr model. The combination of these two algebras is known as a U(3)-boson algebra [129].

The operators of equation (140) define a representation of the Sp(3, \(\mathbb{R}\)) Lie algebra in terms of a U(3)-boson algebra in which a set of boson vacuum state \(|w_{0\alpha}\rangle\), which satisfy the equations
\begin{equation}
a_{ij} |w_{0\alpha}\rangle = 0, \quad i, j = 1, 2, 3, \quad (145)
\end{equation}
are the lowest-grade states of a set of U(3)-coupled states
\begin{equation}
|w_{0n\rho\omega}\rangle = [P_n(a_1^\dagger \otimes a_2^\dagger \otimes \cdots a_3^\dagger]_{\rho\omega}, \quad (146)
\end{equation}
in which \(P_n(a) = [a^\dagger \otimes a^\dagger \otimes \cdots a^\dagger]_{\rho\omega}\) is a U(3) tensor with components that transform as a basis for a U(3) irrep \(n = \{n_1, n_2, n_3\}\) for which \(n_1 \geq n_2 \geq n_3 \geq 0\) are even integers and \(\rho\) indexes the multiplicity of the U(3) irreps \(\{n\} \otimes \{0\}\).

In this Sp(3, \(\mathbb{R}\)) representation the matrix elements of the U(3) operators \(\hat{\Gamma}(C_{ij})\) are identical to those of a standard unitary representation of U(3) in an orthonormal U(3)-coupled basis and the matrix elements of \(\hat{\Lambda}\) are easily determined; see equation (170). Thus, it only remains to determine the SU(3)-reduced matrix elements \(<w_{0n\rho\omega}|a^\dagger|w_{0n\rho'\omega'}\rangle\) and the related matrix elements \(<w_{0n\rho\omega}|a|w_{0n'\rho'\omega'}\rangle\). It is shown in section 9.2 that
\begin{equation}
<w_{0n'\rho'\omega'}|a^\dagger|w_{0n\rho\omega}\rangle = \langle n'||a||n\rangle \times U((\lambda_{0}\mu_{0})(\lambda_{w}\mu_{w})(\lambda_{w'}\mu_{w'})(2\ 0)); \quad (147)
\end{equation}
where \(U((\lambda_{0}\mu_{0})(\lambda_{w}\mu_{w})(\lambda_{w'}\mu_{w'})(2\ 0)); \quad (147)\) is an SU(3) Racah coefficient with
\begin{align}
\lambda_n &= n_1 - n_2, \quad \mu_n = n_2 - n_3, \quad (148a)
\lambda_w &= w_1 - w_2, \quad \mu_w = w_2 - w_3. \quad (148b)
\end{align}
and
\begin{align}
\langle n'||a||n\rangle &= \delta_{n'_1n_1+2}\delta_{n'_2n_2+2}\delta_{n'_3n_3}
\times \frac{(n_1 + 4)(n_1 - n_2 + 2)(n_1 - n_3 + 3)}{2(m_1 - n_2 + 3)(m_1 - n_3 + 4)} \frac{1}{2}
+ \delta_{n'_1n_1}\delta_{n'_2n_2+2}\delta_{n'_3n_3}
\times \frac{(n_2 + 3)(n_2 - n_1)(n_2 - n_3 + 2)}{2(n_2 - n_1 - 1)(n_2 - n_3 + 3)} \frac{1}{2}
+ \delta_{n'_1n_1}\delta_{n'_2n_2}\delta_{n'_3,n_3+1}
\times \frac{(n_3 + 2)(n_3 - n_2)(n_3 - n_1 + 1)}{2(n_3 - n_2)(n_3 - n_1)} \frac{1}{2}. \quad (149)
\end{align}

The above equations satisfy the Hermiticity requirements of a unitary representation of the U(3)-boson algebra. They also give explicit expressions of the matrix elements of the VCS operators of equations (140a)-(140c) in this U(3)-boson basis. However, the representations of the Sp(3, \(\mathbb{R}\)) algebra obtained in this way do not satisfy the Hermiticity requirements of a unitary representation. This is because the orthonormal U(3)-boson basis is not an orthonormal basis for a unitary representation of the Sp(3, \(\mathbb{R}\)) Lie algebra. This is to be expected because, with respect to the boson inner product, the Hermitian adjoint of \(\nabla_{ij}\) is \(\nabla_{ji}^{\dagger} = z_{ij}\) whereas \(\hat{\Gamma}(B_{ij}) = z_{ij} \neq \hat{\Gamma}(A_{ij})\). Thus, a transformation to an appropriate orthonormal basis is required and, as reviewed in section 9.4, it is is obtained by a K-matrix algorithm.

Special cases are the multiplicity-free representations found on one-dimensional U(3) lowest-grade
representations. These are the representations corresponding to multiple giant-resonance excitations of a spherical-harmonic oscillator closed-shell nucleus which relates to a six-dimensional Bohr model with only vibrational degrees of freedom [130]. Analytical expressions are obtained for the matrix elements of these representations in section 9.3.

9.1. VCS representation of the $Sp(3, \mathbb{R})$ Lie algebra

The Hilbert space $H_{wN}^{w_0}$ of an irreducible $Sp(3, \mathbb{R})$ representation is spanned by sets of coherently states

$$\{ |w_0\alpha; z\rangle = \exp \frac{i}{2} \sum_j z_j^* \hat{A}_j |w_0\alpha\rangle \},$$  

(150)

where $\{|w_0\alpha\rangle \}$ is a basis of lowest-grade states for a U(3) representation $w_0$ and $|z_j\rangle$ is a set of complex variables. A state vector $|\psi\rangle \in H_{wN}^{w_0}$ is characterized by the set of overlap functions

$$\{ \Psi_\alpha(z) = \langle w_0\alpha; z|\psi\rangle = \langle w_0\alpha|e^{\hat{Z}(z)}|\psi\rangle \},$$  

(151)

with $\hat{Z}(z) = \sum_j z_j \hat{B}_j$. In a VCS representation, these overlaps are regarded as components of the vector-valued wave function $\Psi$ defined by equation (139).

The representation of state vectors in $H_{wN}^{w_0}$ by VCS wave functions also defines a representation $\hat{X} \mapsto \hat{\Gamma}(\hat{X})$ of a linear operator $\hat{X}$ on state vectors by

$$\hat{\Gamma}(X)\Psi(z) = \sum_\alpha \mathcal{C}_{\alpha}^{w_0} (w_0\alpha|e^{\hat{Z}(z)}\hat{X}|w_0\alpha),$$  

(152)

A special case is when $\hat{X} = \hat{C}_j$ and $|\psi\rangle = |w_0\alpha\rangle$ is a lowest-grade state. In this situation

$$\hat{\Gamma}(C_j)\xi_\alpha^{w_0} = \eta_\alpha^{w_0} \mathcal{C}_{\alpha},$$  

(153)

where

$$\mathcal{C}_{\alpha}^{w_0} \xi_\alpha^{w_0} = \sum_\beta \sum_\beta \mathcal{C}_{\alpha}^{w_0} (w_0\beta|e^{\hat{Z}(z)}\hat{C}_j|w_0\alpha),$$  

(154)

With the definition (152), the VCS operators representing elements of the $Sp(3, \mathbb{R})$ Lie algebra are determined by use of the expansion

$$e^{\hat{Z}(z)} = \hat{X} + [\hat{Z}, \hat{X}] + \frac{1}{2!} [\hat{Z}, [\hat{Z}, \hat{X}]] + \cdots,$$  

(155)

which, because $\hat{Z}$ is a sum of $Sp(3, \mathbb{R})$ lowering operators, terminates at or before the third term. The identities

$$\sum_\alpha \mathcal{C}_{\alpha}^{w_0} \langle w_0\alpha|\hat{C}_j e^{\hat{Z}(z)}|w_0\alpha\rangle = \mathcal{C}_{\alpha} \langle z\rangle,$$  

(156a)

$$\sum_\alpha \mathcal{C}_{\alpha}^{w_0} \langle w_0\alpha|\hat{B}_j e^{\hat{Z}(z)}|w_0\alpha\rangle = \nabla_j \langle z\rangle,$$  

(156b)

$$\sum_\alpha \mathcal{C}_{\alpha}^{w_0} \langle w_0\alpha|\hat{A}_j e^{\hat{Z}(z)}|w_0\alpha\rangle = 0,$$  

(156c)

and the observation that $\hat{B}_j e^{\hat{Z}(z)} = \nabla_j e^{\hat{Z}(z)}$ then leads to the VCS representation

$$\hat{\Gamma}(C_j) = \hat{C}_j + (z\nabla)_j,$$  

(157a)
matrix elements of the SU(3) tensor with components
\[ \hat{X}_{lm}^{(1)} = \delta_{l2} \hat{Q}_{2,m} + \delta_{l1} \sqrt{3} \hat{L}_m. \]  
(163)

SU(3)-reduced matrix elements of this tensor are obtained from the observation that its scalar product
\[ \hat{X}^{(1)} \cdot \hat{X}^{(1)} = \sum_q (\hat{X}_q^{(1)})^* \hat{X}_q^{(1)}, \]
(164)
is the SU(3) Casimir invariant
\[ \hat{T}_2 = \hat{Q} \cdot \hat{Q} + 3 \hat{L} \cdot \hat{L}, \]
(165)
which, for an SU(3) representation (\(\lambda\mu\)), has values
\[ \hat{T}_2(\lambda\mu) = 4(\lambda^2 + \lambda \mu + \mu^2 + 3 \lambda + 3 \mu). \]
(166)
It follows that
\[ |(\lambda\mu')||\hat{X}^{(1)}||\lambda\mu| = \delta_{\lambda\lambda'} \delta_{\mu\mu'} 4(\lambda^2 + \lambda \mu + \mu^2 + 3 \lambda + 3 \mu). \]
(167)
The sign of the matrix element
\[ \langle \lambda\mu||\hat{X}^{(1)}||\lambda\mu \rangle = \pm 2(\lambda^2 + \lambda \mu + \mu^2 + 3 \lambda + 3 \mu)^{\frac{3}{2}}, \]
(168)
is undetermined by this expression but is fixed by the phase convention used in the determination of SU(3) Clebsch–Gordan coefficients to be the same as that of the coefficient \( (\lambda\mu)_{\alpha L} \), \( (\lambda\mu)_{\beta L} \).

Because the operator \( \hat{A} \) appearing in equation (158) is diagonal in the U(3)-boson basis
\[ \hat{A} |w_0 n \rho \nu \nu \rangle = \Omega_{nw} |w_0 n \rho \nu \nu \rangle, \]
(169)
and has eigenvalues given by
\[ \Omega_{nw} = \frac{3}{2} \sum_{j=1}^{3} \left[ 2w_j^2 - n_j^2 + 8(w_j - n_j) - 2j(w_j - n_j) \right], \]
(170)
the matrix elements of the VCS representations of the Sp(3, R) algebra have the explicit expressions
\[ \langle w_0 n' \rho' \nu' \nu' \rangle \hat{C} |w_0 n \rho \nu \nu \rangle = \pm 2 \delta_{n',n} \delta_{\rho',\rho} \delta_{\nu',\nu} \]
(171a)
\[ \times (\lambda^2 + \lambda \mu + \mu^2 + 3 \lambda + 3 \mu)^{\frac{3}{2}}, \]
\[ \langle w_0 n' \rho' \nu' \nu' \rangle \hat{B} |w_0 n \rho \nu \nu \rangle = \langle w_0 n' \rho' \nu' \nu' \rangle |w_0 n \rho \nu \nu \rangle \]
(171b)
\[ \times (\lambda^2 + \lambda \mu + \mu^2 + 3 \lambda + 3 \mu)^{\frac{3}{2}}, \]
\[ \langle w_0 n' \rho' \nu' \nu' \rangle \hat{A} |w_0 n \rho \nu \nu \rangle = \langle w_0 n' \rho' \nu' \nu' \rangle |w_0 n \rho \nu \nu \rangle \]
(171c)
in the above-defined U(3)-boson basis. However, while this basis is orthonormal with respect to the inner product of the U(3)-boson representation, it is not orthonormal with respect to the appropriate inner product for a unitary Sp(3, R) representation. As a consequence the matrix elements (171) are inconsistent with the Hermiticity relationship \( \hat{C}(A_{ij}) = \hat{B}(B_{ij}) \) that should be satisfied in an appropriate orthonormal basis. The following subsection uses K-matrix methods to derive an appropriate orthonormal basis. But first we consider the simple cases in which the multiplicity index \( \rho \) is not needed and for which analytical results are simply obtained [98].

9.3. Multiplicity-free representations of Sp(3, R)

Multiplicity-free representations are representations for which the basis states are uniquely defined by their quantum numbers without a need of multiplicity indices. For Sp(3, R), the multiplicity-free representations \( \langle w_0 \rangle \equiv \langle N_0(\lambda_0 \mu_0) \rangle \) are those with \( \lambda_0 = \mu_0 = 0 \). (Note that angle brackets \( \langle N_0(\lambda_0 \mu_0) \rangle \) are used to distinguish an Sp(3, R) representation from the corresponding lowest-grade representation \( \{N_0(\lambda_0 \mu_0)\} \) of its U(3) subgroup.) The significant property of these representations is that the U(3)-boson basis states are already an orthogonal set with respect to the Sp(3, R) inner product and it only remains to renormalise them to obtain an orthonormal basis. It follows immediately from the equations (171) that the appropriate renormalisation factors should be such as to give the matrix elements in the corresponding orthonormal basis (with angle brackets) for these multiplicity-free representations
\[ \langle w_0 n w' || \hat{C} || w_0 n' w' \rangle = 2 \delta_{n,n'} \delta_{w,w'} \]
(172a)
\[ \times (\lambda^2 + \lambda \mu + \mu^2 + 3 \lambda + 3 \mu)^{\frac{3}{2}}, \]
\[ \langle w_0 n w' || \hat{B} || w_0 n' w' \rangle = (\Omega_{n'w'} - \Omega_{nw})^{\frac{3}{2}}, \]
(172b)
\[ \times (w_0 n' w' || a || w_0 n' w'), \]
\[ \langle w_0 n' w' || \hat{A} || w_0 n w \rangle = (\Omega_{n'w'} - \Omega_{nw})^{\frac{3}{2}}, \]
(172c)
\[ \times (w_0 n' w' || a || w_0 n w). \]
These expressions, given here as a special simple case of the VCS construction [98], were first derived in an equivalent form by Castaños et al [130].

9.4. K-matrix theory and generic representations of Sp(3, R) with lowest-weight states

All the Sp(3, R) representations that arise in nuclear physics have lowest-weight states and are unitary when expressed in appropriate orthonormal bases. However, as shown above, they are not unitary in bases for which the U(3)-boson algebra is unitary. Thus, to make use of the simple results obtained in a U(3)-boson model basis, an orthonormal basis of VCS wave functions \( \{\Psi_s\} \) is expanded
\[ \Psi_s = \sum_{x} \phi_s K_{sx}, \]
(173)
in terms of an orthonormal basis \( \{\phi_s\} \) for a corresponding U(3)-boson model representation. The matrix elements of \( K \), expressed as overlaps in terms of the U(3)-boson inner product by
\[ K_{sx} = \langle \phi_s | \Psi_x \rangle, \]
(174)
are determined by the K-matrix methods of [99, 107].

From the expansion
\[ \hat{C}(X) \Psi_s = \sum_{\tau} \Psi_t (\tau | \hat{X} | \sigma), \]
(175)
for an element $X$ of the $\text{Sp}(3, \mathbb{R})$ Lie algebra, we obtain the relationship
\[
\sum_{s} (\phi_s, \hat{\Gamma}(X) \phi_s) K^s_{\sigma \tau} = \sum_{\tau} K^s_{\tau \sigma} (\gamma | \bar{X} | \sigma).
\] (176)

This and a corresponding equation for the operator $\hat{X}^\dagger$ are conveniently expressed as matrix equations
\[
\Gamma(X) K = \mathcal{K} M(X), \quad \Gamma(X') K = \mathcal{K} M(X'),
\] (177)

where
\[
\Gamma_{\sigma \tau}(X) = (\phi_s, \hat{\Gamma}(X) \phi_s), \quad M_{\sigma \tau}(X) = \langle \sigma | \hat{X} | \tau \rangle.
\] (178)

We now seek a set of $K$ matrices such that the $M$ matrices satisfy the Hermiticity relationships
\[
M_{\sigma \tau}(X') = M^*_{\tau \sigma}(X)
\] (179)
of a unitary representation. Multiplying the right-hand side of each equation in (177) by $K^\dagger$ gives the identities
\[
\Gamma(X) S = \mathcal{K} M(X) K^\dagger, \quad \Gamma(X') S = \mathcal{K} M(X') K^\dagger,
\] (180)

where $S$ is the Hermitian matrix
\[
S = \mathcal{K} K^\dagger.
\] (181)

Taking the Hermitian adjoint of the first equation of (180) and imposing the required Hermiticity condition (179), then gives the equation
\[
\mathcal{S} \Gamma(X) \mathcal{S} = \mathcal{K} M(X) \mathcal{K} K^\dagger = \Gamma(X') S
\] (182)
for $X$ in the $\text{Sp}(3, \mathbb{R})$ Lie algebra. This equation is equivalently expressed as an operator identity
\[
\hat{\mathcal{S}} \hat{\Gamma}(X) \hat{\mathcal{S}} = \hat{\Gamma}(X' \hat{\mathcal{S}}),
\] (183)

A result, confirmed by this identity, is that
\[
\hat{\Gamma}(C_{ij}) \hat{S} = \hat{\mathcal{S}} \hat{\Gamma}(C_{ij}),
\] (184)

for every element $C_{ij}$ of the $U(3) \subset \text{Sp}(3, \mathbb{R})$ subalgebra. Thus, $\hat{S}$ commutes with the VCS representation of elements of the $U(3) \subset \text{Sp}(3, \mathbb{R})$ subalgebra and it follows that the $S$ matrices are block diagonal, i.e., they have no off-diagonal elements between states of inequivalent $U(3)$ representations. Also, if restricted to a single irreducible $U(3)$ representation, $S$ becomes a multiple of the identity (by Schur’s lemma). This is consistent with the observation that the $U(3)$ subrepresentations of both the $\text{Sp}(3, \mathbb{R})$ and $U(3)$-boson representations are already unitary.

It is then appropriate to augment the labelling of basis states to include their $U(3)$ quantum numbers. Thus, we now label basis states for the Hilbert space of the $\text{Sp}(3, \mathbb{R})$ representation by $\{|\sigma w \alpha \rangle\}$, where $\alpha$ labels basis states for an irreducible $U(3)$ representation $w$, and $\sigma$ distinguishes multiple occurrences of this representation. Basis states $\{|w \alpha \rangle\}$ for the $U(3)$-boson space are similarity labelled. Equation (173) is then expressed in the form
\[
\Psi_{\sigma w \alpha} = \sum_{s} \phi_{\sigma w \alpha} K^w_{\sigma \tau}.
\] (185)

and the $S^w$ block has matrix element
\[
S^w_{\alpha \tau} = \sum_{\sigma} K^w_{\alpha \sigma} K^{w^*}_{\sigma \tau}.
\] (186)

The following shows that the $S^w$ matrices can be determined recursively starting from that for the multiplicity-free lowest-grade $U(3)$ representation, $S^w_{\alpha 0}$, which can be set equal to the identity matrix. The $S^w$ matrices for successively higher-grade $U(3)$ representations are then obtained from equation (183) with $X = E_{ij}$ which gives
\[
\hat{S} a^+_{ij} = [\hat{\Lambda}, a^+_{ij}] \hat{S}
\] (187)
and hence
\[
\hat{S} a^+ \cdot a = \sum_{ij} [\hat{\Lambda}, a^+_{ij}] \hat{S} a_{ij},
\] (188)

where $a^+ \cdot a = \sum_{ij} a^+_{ij} a_{ij}$. Taking matrix elements of both sides of this expression with
\[
S^w_{\alpha \tau} = \langle w \alpha | \hat{S} | \alpha w \rangle,
\] (189)

and noting that $a^+ \cdot a$ and $\hat{\Lambda}$ are diagonal, gives the equation
\[
S^w_{\alpha \tau} (\tau' \beta | a^+ \cdot a | \tau w' \beta) = \sum_{\alpha w' \alpha w} (\tau' \beta | \hat{\Lambda}, \alpha w' \alpha w) S^w_{\tau \tau' \beta}
\] (190)
\times (\tau w' | a_{ij} | \tau w' \beta).

From the observation that $[a^+ \cdot a, a^+_{ij}] = 2 a^+_{ij}$ and, because $a^+_{ij}$ increases the harmonic-oscillator energy of a state by $2\hbar \omega$ implying that $[\hat{H}_0, a^+_{ij}] = 2 a^+_{ij}$, it follows that
\[
(a^+ \cdot a | \omega \alpha) = (N_w - N_w) | \omega \alpha),
\] (191)

where
\[
N_w = w_1 + w_2 + w_3.
\] (192)

Equation (190) then becomes
\[
S^w_{\alpha \tau} = \frac{1}{N_w - N_0} \sum_{\omega \omega' \alpha w} (\omega \omega' | a_{ij} | \omega \omega' \alpha w) S^w_{\tau \tau' \beta} \times (\tau \omega' | a^+_{ij} | \tau \omega' \beta) \times (\omega | a_{ij} | \omega \beta) S^w_{\tau \tau' \beta},
\] (193)

where the matrix elements on the right side of this equation are reduced with respect to $SU(3)$ and $n (s)$ is the value of $n$ in the multiplicity label $s \equiv n p$. Thus, from $S^w$, one obtains a matrix $S^w$ matrix with $N^w = N_w + 2$, etc.

Once a Hermitian matrix $S^w$, with elements $S^w_{\alpha \tau} = \sum_{\sigma} K^w_{\alpha \sigma} K^{w^*}_{\sigma \tau}$, has been determined, it can be diagonalised by a unitary transformation. Also, because the $S^w$ matrices are non-negative by construction, their eigenvalues are real and non-negative. Thus, the $S^w$ matrices are expressible in the form
\[
S^w = \sum_{\sigma} U^w_{\alpha \sigma} (k^w_{\sigma \tau} U^w_{\tau \sigma}),
\] (194)
where $U^w$ is unitary, from which one obtains the $\mathcal{K}^w$ matrix with elements

$$\mathcal{K}^w_{st} = U^w_{st} k^w_{s}.$$  \hfill (195)

The VCS wave functions $\{\psi_{\text{vcs}}\}$ for an orthonormal basis $\{\{\sigma_{\text{vcs}}\}\}$ for the Hilbert space $\mathbb{H}^{\text{vcs}}$ of an Sp(3, $\mathbb{R}$) irrep are then expressed by the equation

$$\psi_{\text{vcs}} = \mathcal{K} \phi_{\text{vcs}} = \sum_s \phi_{\text{vcs}} U^w_{st} k^w_s.$$ \hfill (196)

It is noted from this expression that any state $\{\sigma_{\text{vcs}}\}$, with VCS wave function $\psi_{\text{vcs}}$, for which $k^w_{s}$ is zero will vanish. This can happen if there are normalisable states in the U(3)-boson Hilbert space that have no counterparts in the Sp(3, $\mathbb{R}$) space $\mathbb{H}^{\text{vcs}}$. The Sp(3, $\mathbb{R}$) → U(3) branching rules [134] show precisely when this can happen which, in fact, is only for Sp(3, $\mathbb{R}$) irreps in nuclei of nucleon number $A \leq 6$. The non-vanishing matrix elements of any element $X$ in the Sp(3, $\mathbb{R}$) Lie algebra are then obtained from equation (177) and given by

$$\langle \sigma_{\text{vcs}} \mid [\hat{X}] \mid \tau_{\text{vcs}} \rangle = \frac{1}{k^\sigma} \sum_{st} U^w_{st} (sw) \langle \hat{X} \rangle (\Omega) \langle tw \rangle U^w_{tr} k^w_r.$$ \hfill (197)

### 10. Macroscopic limits of the symplectic model

In this section, we consider the macroscopic limits of the symplectic model that are approached in heavy deformed nuclei and which provide the means to interpret their properties quickly and easily in a manner that relates to a microscopic many-nucleon interpretation.

Of particular interest is the evolution of the symplectic model of nuclear collective dynamics to that of a rigid (generally triaxial) rotor strongly coupled to high-energy giant-resonance vibrations. The macroscopic model that emerges is shown to be much as envisaged in the phenomenological Bohr–Mottelson [7] and Davydov–Filippov [9, 135] models, albeit with the low-energy beta- and gamma-vibrational excitations replaced with the higher-energy giant resonances excitations of a deformed nucleus.

The macroscopic limits of the SU(3) matrix elements to those of a rigid rotor have been given in section 8. Thus, for representations with non-zero U(2)$_L$ spin, the close relationship of the symplectic model to the phenomenological collective models suggests that, because of the adiabaticity of the low-lying SU(3)-rotational states of the symplectic model, a strong spin-orbit interaction will result in a corresponding strong coupling of the rotational and spin degrees of freedom of the model. It could also result in rotationally aligned coupling and to a mixing of rotational bands from different Sp(3, $\mathbb{R}$) representations. These are properties of the model that need to be explored, to see the extent to which the insights gained from the many analyses in terms of the unified model are consistent with its microscopic realisation.

The U(1) × SU(3) labelling $\{N(\lambda\mu)\}$ of an irreducible U(3) representation $\{w\} = \{w_1, w_2, w_3\}$ is given by setting

$N_w = w_1 + w_2 + w_3, \quad \lambda_w = w_2 - w_3, \quad \mu_w = w_2 - w_3.$ \hfill (198)

An irreducible Sp(3, $\mathbb{R}$) representation $\langle w_0 \rangle$ with lowest-grade U(3) representation $\{w_0\}$ is then similarly labelled by the U(1) × SU(3) quantum numbers $\{N_0(\lambda_0\mu_0)\}$ with $N_0 = N_{w_0}, \quad \lambda_0 = \lambda_{w_0}, \quad \mu_0 = \mu_{w_0}.$

The minimum value $N_{\text{min}}$ that the $N_0$ quantum number can have for an Sp(3, $\mathbb{R}$) representation of a nucleus (with its centre-of-mass contribution removed) is, for example, $118\frac{1}{2}$ for $^{40}$Ca and $81\frac{1}{2}$ for $^{166}$Er. It can be estimated [129] as a function of the nuclear mass number $A$, from the expression of the mean-square radius of the nuclear ground state given, in harmonic-oscillator units after removal of its centre-of-mass contribution, by

$$\langle r^2 \rangle = \frac{N_{\text{min}}}{A - 1} \frac{\hbar^2}{M_{\omega}}.$$ \hfill (199)

From the assumed $A^{2/3}$-dependence of $\langle r^2 \rangle$ and the usual $A^{-1/3}$ dependence of $\omega$, this gives

$$N_{\text{min}} \approx 0.9 A^{1/3},$$ \hfill (200)

and exhibits its rapid increase with the mass number $A$. Thus, it is expected that good approximations can be obtained for a wide range of nuclei by neglecting terms of order $1/N_0$. This gives the so-called macroscopic limits.

#### 10.1. The U(3)-boson model as a contraction limit of the symplectic model

The U(3)-boson algebra [129, 136] is a contraction of the Sp(3, $\mathbb{R}$) algebra that is realised for states of relatively few bosons in representations for which $N_0 \to \infty$. It was introduced to derive a much simplified version of the symplectic model that is appropriate for its application to heavy nuclei. Most fortuitously, as detailed in section 9.1, it transpires that the analytical expressions for the matrix elements of the U(3)-boson algebra provide precisely what is required for the accurate calculation of the Sp(3, $\mathbb{R}$) matrix elements. Applications of the U(3)-boson model were made by Rochford, Castraños and Draayer [137, 138].

The U(3)-boson contraction of the symplectic model algebra was obtained [129] by observing that, with $\varepsilon^2 = 3/(2N_0)$, the commutation relations of the giant-resonance raising and lowering operators are given by

$$[\varepsilon \hat{B}_{0,0}, \varepsilon \hat{A}_{0,0}] = \frac{2}{N_0} \hat{C}_0 = \frac{1}{N_0} \hat{C}_0.$$ \hfill (201)

$$[\varepsilon \hat{B}_{2,0}, \varepsilon \hat{A}_{2,0}] = \frac{1}{N_0} \hat{C}_0 + \frac{1}{2N_0} \hat{Q}_{2,0}.$$ \hfill (202)

When acting on a state of angular momentum $L$ of a U(3) irrep $\{N(\lambda\mu)\}$, $\hat{C}_0$ takes the value $N$, and, if $L < L_{\text{max}}$ for the SU(3) irrep $(\lambda_0\mu_0)$, $\hat{Q}_{2,0}$ takes a value smaller than $2\lambda + \mu$. Thus, for states for which $(N - N_0)/N_0 < 1$ and $2\lambda + \mu < 2N_0$, the giant-resonance raising and lowering
operators contract to boson operators, i.e.
\[ \hat{A}_0^{(0)} \rightarrow \sqrt{\frac{2N_0}{3}} \hat{a}_s^{1}, \quad \hat{B}_0^{(0)} \rightarrow \sqrt{\frac{2N_0}{3}} \hat{a}_s, \quad (203) \]
\[ \hat{A}_{2,\nu}^{(0)} \rightarrow \sqrt{\frac{2N_0}{3}} \hat{d}_s^{1}, \quad \hat{B}_{2,\nu} \rightarrow \sqrt{\frac{2N_0}{3}} \hat{d}_s, \quad (204) \]

that obey the commutation relations
\[ [s, s^\dagger] = 1, \quad [d_\mu^\dagger, d_\nu^\dagger] = \delta_{\mu,\nu} \hat{1}, \quad (205) \]
where \( d_\mu^\dagger = (-1)^\nu d_{-\mu} = (d_\mu)^\dagger \). However, the contracted raising and lowering operators continue to transform under \( U(3) \) in exactly the same way as given by the boson expansion
\[ \hat{C}_{ij} \equiv \hat{C}_{ij} + (a\dagger a)_{ij}, \quad (206) \]
of elements of the \( U(3) \) Lie algebra given by equation \((157a)\). Thus, the quadrupole tensor of the symplectic model, given in harmonic-oscillator units by equation \((24)\), has contraction
\[ \hat{Q}_2 = \hat{Q}_2 + \sqrt{3} (\hat{A}_2 + \hat{B}_2) \rightarrow \hat{Q}_2 + \sqrt{2N_0} (d_1^+ + d_1^\dagger), \]
and the \( \text{Sp}(3, \mathbb{R}) \) matrix elements have values in the contraction limit given by
\[ \langle w_0 n_\rho \rho' \omega' | \hat{C} | w_0 n_\rho' \rho' \omega' \rangle = \pm 2 \delta_{n_\rho, n_\rho'} \delta_{n_\omega, n_\omega'} \times (\lambda^2 + \lambda \mu + \mu^2 + 3 \lambda + 3 \mu)^{1/2}, \quad (208a) \]
\[ \langle w_0 n_\rho \rho' \omega' | | \hat{B} | | w_0 n_\rho' \rho' \omega' \rangle \rightarrow \sqrt{2N_0 / 3} \times \langle w_0 n_\rho \rho' \omega' | | a \rangle | | w_0 n_\rho' \rho' \omega' \rangle, \quad (208b) \]
\[ \langle w_0 n_\rho' \rho' \omega' | | \hat{A} | | w_0 n_\rho \rho \omega \rangle \rightarrow \sqrt{2N_0 / 3} \times \langle w_0 n_\rho' \rho' \omega' | | a \dagger \rangle | | w_0 n_\rho \rho \omega \rangle. \quad (208c) \]

10.2. The large \( N_0 \) asymptotic limit of an \( \text{Sp}(3, \mathbb{R}) \) representation

An asymptotic limit of an \( \text{Sp}(3, \mathbb{R}) \) representation that is approached much more rapidly than that of its contraction as \((\lambda_0 + \mu_0)/N_0 \rightarrow 0\) was given in \([98,99]\) and its accuracy for relatively small values of \((\lambda_0 + \mu_0)/N_0\) was confirmed by Hecht \([139]\). It follows directly from the observation, implied by the above contraction, that in the \( N_0 \rightarrow \infty \) limit, while \( \lambda \) and \( \mu \) remain finite, the basis states for an irreducible unitary representations of the \( U(3) \)-boson algebra need only to be renormalised to become an orthonormal basis for a VCS representation of \( \text{Sp}(3, \mathbb{R}) \). Thus, improved asymptotic matrix elements, for large values of \( N_0 \), are obtained directly from the VCS representation of \( \text{Sp}(3, \mathbb{R}) \) elements in states that are asymptotically proportional to \( U(3) \)-boson states, i.e., for which
\[ \langle w_0 n_\rho \rho' \omega | k_{n_\rho}^{w} \rangle \sim \langle w_0 n_\rho \rho' \omega \rangle, \quad (209) \]

A similarity transformation of equations \((172a)-(172c)\), is then obtained by setting
\[ k_{n_\rho}^{w} = (\Omega_{n_\rho}^{w} - \Omega_{\omega'}^{w})^{1/2}, \quad (\Omega_{n_\rho}^{w} > \Omega_{\omega'}^{w}) \]
and leads to the asymptotic matrix elements
\[ \langle w_0 n_\rho \rho' \omega' | | \hat{C} | | w_0 n_\rho' \rho' \omega' \rangle = 2 \delta_{n_\rho, n_\rho'} \delta_{n_\omega, n_\omega'} \times (\lambda^2 + \lambda \mu + \mu^2 + 3 \lambda + 3 \mu)^{1/2}, \quad (211a) \]
\[ \langle w_0 n_\rho \rho' \omega' | | \hat{B} | | w_0 n_\rho' \rho' \omega' \rangle \sim (\Omega_{n_\rho}^{w} - \Omega_{\omega'}^{w})^{1/2} \times \langle w_0 n_\rho \rho' \omega' | | a \rangle | | w_0 n_\rho' \rho' \omega' \rangle, \quad (211b) \]
\[ \langle w_0 n_\rho' \rho' \omega' | | \hat{A} | | w_0 n_\rho \rho \omega \rangle \sim (\Omega_{n_\rho}^{w} - \Omega_{\omega'}^{w})^{1/2} \times \langle w_0 n_\rho' \rho' \omega' | | a \dagger \rangle | | w_0 n_\rho \rho \omega \rangle. \quad (211c) \]

These expressions were shown to be accurate to fourth order in the small parameter \((\lambda_0 + \mu_0)/2N_0\) \([99]\). Moreover, they are precise for multiplicity-free representations \( | N_0(\lambda_0, \mu_0) \rangle \) with \( \lambda_0 = \mu_0 = 0 \) as seen from the expressions for these matrix elements in section 9.3 and, as shown in \([98]\), they agree with the results calculated by Castaños et al \([130]\).

10.3. Comparisons with precisely computed matrix elements

The motivation for considering the macroscopic limits of the symplectic model is two-fold; the first is to assess the extent to which they reproduce the results of the standard Bohr–Mottelson-based collective models and the adjustments to these models implied by their many-nucleon foundations; the second is to understand their limitations as approximations to precise calculations.

It is emphasised that an important use of the symplectic model and the associated many-nucleon coupling scheme is to identify the many-nucleon spaces needed for realistic descriptions of observed collective states of nuclei. Exploratory model calculations, e.g., in section 11.1, indicate that, in a spherical–harmonic oscillator shell-model basis, these spaces are not small even when restricted to a single \( \text{Sp}(3, \mathbb{R}) \) irrep. Typically, for a rotational rare-earth nucleus, states from 15 to 20 major harmonic-oscillator shells may be required for calculations of the desired level of convergence. Thus, it appears that in many situations, improved accuracy is likely to be possible by use of asymptotic matrix elements in larger spaces. It is also recognised that the restriction of a symplectic model to a single representation is only a beginning. One will eventually want to consider calculations with symplectic symmetry-breaking interactions in spaces of mixed representations.

In this section, we compare matrix elements calculated in the asymptotic \((211)\) and \((U(3))\)-boson approximations \((208)\) with precisely computed values. In tables 3 and 4 the asymptotic (\text{ASp3R}) and the \((U(3))\)-boson (\text{U3BC}) approximations are compared, respectively, with precisely computed reduced matrix elements for \( \mathcal{A} \) and \( \mathcal{C} \). The matrix elements are calculated for the symplectic irrep \((824,80,0)\), as used by Bahri \([140]\) for the ground state rotational band of \(^{166}\)Er.
Table 3. Comparison of selected reduced matrix elements $\langle \sigma' w' | || A || | \rho w \rangle$ calculated in the U(3)-boson contraction (U3BC) and asymptotic limits (ASp3R) with accurately computed Sp(3, $\mathbb{R}$) matrix elements (Sp3R). The state $\{|w_0 n p w\},$ to which a state $|\rho w \rangle$ approaches in the asymptotic limit, is labelled by the U(3)-boson quantum numbers $NPW$ shown.

| $w_0 = 824(80, 0)$ | $w_0 = 836(78, 10)$ |
|-------------------|-------------------|
| $w'$ | $\sigma'$ | $n'$ | $\rho'$ | $w$ | $\sigma$ | $n$ | $\rho$ | Sp3R | ASp3R | U3BC |
| 826 (78, 2) | 1 | 2 (0, 2) | 1 | 824 (80, 0) | 1 | 0 (0, 0) | 1 | 22.2261 | 22.2261 | 23.4379 |
| 830 (82, 2) | 2 | 6 (2, 2) | 1 | 828 (82, 1) | 1 | 4 (4, 0) | 1 | −15.0319 −15.0317 −14.6415 |
| 830 (80, 0) | 1 | 0 (0, 0) | 1 | 828 (79, 1) | 1 | 4 (0, 2) | 1 | 23.8723 23.8721 23.2927 |
| 830 (86, 0) | 1 | 6 (6, 0) | 1 | 828 (84, 0) | 1 | 4 (4, 0) | 1 | 44.4972 44.4972 40.5956 |
| 834 (82, 4) | 3 | 10 (2, 4) | 1 | 832 (82, 3) | 2 | 8 (4, 2) | 1 | −21.2952 −21.2947 −20.7062 |
| 834 (79, 1) | 2 | 10 (0, 2) | 1 | 832 (78, 2) | 2 | 8 (0, 2) | 1 | −30.7897 −30.7896 −30.0684 |
| 834 (90, 0) | 1 | 10 (10, 0) | 1 | 832 (88, 0) | 1 | 8 (8, 0) | 1 | 57.6194 57.6194 52.4087 |
| 838 (82, 6) | 2 | 14 (2, 6) | 1 | 836 (82, 5) | 2 | 12 (4, 4) | 1 | −26.1261 −26.1254 −25.3598 |
| 838 (78, 2) | 1 | 14 (2, 6) | 1 | 836 (80, 0) | 1 | 12 (0, 0) | 1 | 31.5594 31.5595 31.1461 |
| 838 (94, 0) | 1 | 14 (14, 0) | 1 | 836 (92, 0) | 1 | 12 (12, 0) | 1 | 68.3813 68.3813 62.0108 |
| 842 (86, 6) | 2 | 18 (0, 18) | 1 | 840 (88, 4) | 2 | 16 (16, 0) | 1 | 17.8690 17.8680 18.9966 |
| 842 (80, 0) | 1 | 20 (0, 18) | 1 | 840 (79, 1) | 3 | 16 (0, 2) | 1 | 41.4913 41.4907 40.3442 |
| 842 (98, 0) | 1 | 18 (18, 0) | 1 | 840 (96, 0) | 1 | 16 (16, 0) | 1 | 77.7689 77.7689 70.3136 |
| 846 (88, 7) | 2 | 22 (2, 22) | 1 | 844 (90, 5) | 3 | 20 (20, 0) | 1 | 18.3142 18.3127 19.5096 |
| 846 (79, 1) | 2 | 22 (0, 2) | 1 | 844 (78, 2) | 5 | 20 (2, 0) | 1 | −41.4521 −41.4518 −40.3410 |
| 846 (102, 0) | 1 | 22 (2, 22) | 1 | 844 (100, 0) | 1 | 20 (20, 0) | 1 | 86.2322 86.2322 77.7346 |

and for the irrep $\langle 836(78, 10) \rangle$ which, according to Jarrio et al. [67], is the kind of irrep implied by the observed properties of $^{168}$Er. The precise matrix elements of table 3 are those of equation (197) and the asymptotic and U(3)-boson matrix elements are, respectively, those of equations (211c) and (208c). The reduced matrix elements of $C$ are obtained by noting from (206) that $C_{ij}$ can be expressed in terms of the $U(3)$ elements $C_{ij}$ of the $Sp(3, \mathbb{R})$ algebra and the boson creation and annihilation operators. Its reduced matrix elements are then given in the U(3)-boson basis by

$$(w_0 | w_0' | \sigma' \rho' \sigma \rho w \rangle_{\rho_{\rho}} = (w_0 | w_0' | \sigma' \rho' \sigma \rho w \rangle_{\rho_{\rho}} - (w_0 | \rho' \rho \sigma \sigma w \rangle_{\rho_{\rho}} \langle \sigma \sigma | \sigma \sigma \rangle)_{\rho_{\rho}}.$$  (212)

The corresponding precise and asymptotic matrix elements of $C$ are then obtained from the expansions of the precise and asymptotic bases in the U(3)-boson basis.

The selected matrix elements shown in tables 3 and 4 include those for which the approximations are the most and least accurate for each $N_p$ and $N_n$. The tables show, for both irreps, that the asymptotic and precise matrix elements are essentially the same to a high level of accuracy. However, the precision of the asymptotic matrix elements, in the current implementation, is approximately a factor of 5 times faster. The U(3)-boson reduced matrix elements do not provide the same accuracy as the asymptotic approximation and are only marginally easier to compute. However, and more significantly as pursued in section 11.1, they are amenable to analytical model calculations.

11. A simple model application

The above macroscopic limits of the symplectic model as a U(3)-boson model and of its lowest-grade U(3) states as those
of a triaxial rigid rotor, as reviewed in section 8, show that, in a combined macroscopic limit, for which both $L/\lambda_0$ and $(\lambda_0 + \mu_0)/N_0$ are small, the states of an $Sp(3, \mathbb{R})$ representation $\langle N_0(\lambda_0, \mu_0) \rangle$ of angular momentum $L$, are those of a coupled-rotor-vibrator model. Thus, to address the usefulness of these macroscopic limits of the symplectic model in fitting experimental data in a manner that gives information on their many-nucleon structure, we consider a simple symplectic model Hamiltonian that is simply solvable in its macroscopic CRV limit.

The coupled-rotor-vibrator model was introduced by Le Blanc et al. [111, 141] as a union of rigid-rotor and (giant-resonance) vibrational models. It is particularly significant in the present context because of its close correspondence with the Bohr–Mottelson unified model, in which intrinsic valence-shell states, described in the symplectic model as lowest-grade U(3) states, are added to a Bohr irrotational-flow vibrational model corresponding to giant monopole/quadrupole vibrations; in the absence of valence-shell particles, e.g., for closed-shell nuclei, the giant-resonance vibrational states would have irrotational-flow mass parameters (see [142] section 8.2.6).

11.1. The coupled-rotor-vibrator model

We consider a symplectic model with a Hamiltonian of the form

\[ \hat{H} = \hat{H}_{\text{crv}} - \kappa_1 \hat{Q}_2 \cdot (\hat{A}_2 + \hat{B}_2) + \kappa_2 \hat{A}_2 \cdot \hat{B}_2 + \kappa_3 \hat{A}_0 \cdot \hat{B}_0, \tag{213} \]

in which $\hat{Q}_2$ is the restriction of the quadrupole tensor $\hat{Q}_2$, defined by equations (63) and (64) to the lowest-grade SU(3) irrep $(\lambda_0, \mu_0)$ of an $Sp(3, \mathbb{R})$ irrep $\langle N_0(\lambda_0, \mu_0) \rangle$; its components commute with the giant-resonance operators. This Hamiltonian is expressed in terms of symplectic model operators and can be diagonalised within the space of an $Sp(3, \mathbb{R})$ irrep. It is then of interest to interpret the results that emerge in terms of the corresponding analytically solvable CRV model.
Thus, if one already knows the spectrum of the SU(3)-rotor Hamiltonian $\hat{H}_{\text{rot}}$, which we suppose to be given in a $\{|KL\}$ basis with energies $\{E_{\alpha}\}$, it is immediately inferred that the energy levels of the Hamiltonian $\hat{H}_{\text{CRV}}$ are given within terms of order $\alpha^2$ by

$$E_{\text{rot,crv}} = E_{\alpha} + n_0 \hbar \omega_0 + n_2 \hbar \omega_2 + O(\alpha^2).$$

Thus, in the CRV limit, the structure of the energy spectrum is little changed by introduction of the $\hat{Q}_2 \cdot (\hat{\mathcal{A}}_2 + \mathcal{B}_2)$ term in (213) that couples the intrinsic SU(3) and giant resonance degrees of freedom. However, there is a significant change in the quadrupole moments of the low-lying states and the E2 transition matrix elements between them.

Let $\hat{H}(\alpha)$ denote the Hamiltonian

$$\hat{H}(\alpha) = \hat{H}_{\text{rot}} + \hbar \omega_2 \hat{D} \cdot \hat{D}$$

with $D^\dagger = D_d - \alpha \hat{Q}_d$ and $D_d = d_d - \alpha \hat{Q}_d$, where $\{\hat{Q}_d\}$ are commuting quadrupole operators. The transformation between the $d$- and $D$-boson operators, given by

$$e^{\alpha \hat{Q}(d^\dagger - d)} e^{-\alpha \hat{Q}(d^\dagger - d)} = D^\dagger,$$

then implies that

$$\hat{H}(\alpha) = e^{\alpha \hat{Q}(d^\dagger - d)} \hat{H}(0) e^{-\alpha \hat{Q}(d^\dagger - d)}.$$

Thus, if $|\varphi\rangle$ is any eigenstate of $\hat{H}(0)$, the transformed state

$$|\varphi(\alpha)\rangle = e^{\alpha \hat{Q}(d^\dagger - d)} |\varphi\rangle$$

will be an eigenstate of $\hat{H}(\alpha)$ with the same energy, as already observed. The quadrupole moments between the transformed state are similarly obtained. Within the space of lowest-grade SU(3) (boson-vacuum) states, matrix elements of the quadrupole operator are, by definition, given by

$$\langle \varphi | \hat{Q}_n | \varphi \rangle \propto \langle \varphi | \hat{Q}_n | \varphi \rangle,$$

and in the corresponding space of $D$-boson vacuum states, they are given by

$$\langle \varphi(\alpha) | \hat{Q}_n | \varphi(\alpha) \rangle \propto \langle \varphi | \hat{Q}_n | \varphi \rangle e^{-\alpha \hat{Q}(d^\dagger - d)} |\varphi\rangle$$

$$= \langle \varphi | \hat{Q}_n | \varphi \rangle - \frac{2N_0}{\sqrt{2N_0}} \langle \varphi | \hat{Q}_n | \varphi \rangle + 2 \alpha \sqrt{2N_0} \langle \varphi | \hat{Q}_n | \varphi \rangle.$$
which means that, when the giant-resonance states are regarded as harmonic-oscillator states, the states $|\varphi(\kappa_1)\rangle$ are interpreted as coherent states or, in other words, polarised vacuum states. In fact, we have found that, with a suitable value of the coupling constant $\alpha$, the states $|\varphi(\kappa_1)\rangle$ have quadrupole moments with essentially equal contributions to their values coming from the SU(3) rotor and the polarised giant-resonance vacuum. In pictorial terms, the interaction between the lowest-grade SU(3) rotor and the giant-resonance degrees of freedom results in a polarisation of the giant-resonance vacuum which then rotates in unison with the SU(3) rotor in much the same way as a tidal wave on the Earth’s surface follows the Moon’s orbit.

11.2. Comparison of symplectic and CRV model results

To examine the interaction between intrinsic SU(3) and giant-resonance degrees of freedom, as introduced by the $\hat{Q}_1 \cdot (\hat{A}_\alpha + \hat{B}_\alpha)$ term in the Hamiltonian (213), we compare symplectic model calculations with and without the presence of this term. We use appropriately defined values of the parameters $\kappa_2$ and $\kappa_3$ so as to place the giant monopole and quadrupole resonances at reasonable energies (as described section 11.1). Then, we carry out calculations either with $\kappa_1 = 0$, that is, with the coupling between the SU(3) and giant-resonance degrees of freedom suppressed, or with $\kappa_1$ chosen to approximately double the matrix elements of quadrupole operators, or quadruple the corresponding $B(E2)$ reduced transition probabilities, for consistency with experiment. Recall that, in the CRV approximation, changing this coupling is expected to leave the energy spectrum essentially unchanged.

Specifically, we apply the model Hamiltonian (213) to a description of the $^{166}$Er ground-state rotational band and its giant-quadrupole resonance excitations. These are treated within an $|824 \langle 80 \rangle\rangle$ symplectic irrep, resulting in the energy levels and $B(E2)$ reduced transition probabilities for the uncoupled ($\kappa_1 = 0$) and coupled ($\kappa_1 \neq 0$) Hamiltonian shown in figure 1. In these calculations, the parameters in (213) were set as follows. For the intrinsic SU(3) Hamiltonian

$$\hat{H}_{\text{int}} = H_0 - \chi \hat{Q} \cdot \hat{Q},$$

(233)

$\chi = 0.011$ was set to give the excitation energy of the first $2^+$ state; the value $h\omega = 7.36$ MeV was determined by use of the Blomqvist–Molinari formula [146]; values of $\kappa_2 = 0.019$ and $\kappa_3 = 0.025$ were chosen to give the giant quadrupole resonance at $\sqrt{2} h\omega = 10.4$ MeV and the giant monopole resonance at $2h\omega = 14.7$ MeV; the parameter $\kappa_1 = 0.006$ was then adjusted to obtain the experimental value of the $B(E2; 2^+ \rightarrow 0^+)$ transition for the ground-state rotational band.

Because the asymptotic reduced matrix elements are indistinguishably close to the exact reduced matrix elements to the level of accuracy of these calculations, the asymptotic matrix elements were used to construct the Hamiltonian.

The calculations were carried out in an $\text{Sp}(3, \mathbb{R})$ space truncated by $N_\theta = N_\kappa - N_\kappa_1 \leq N_{\text{max}}$, with $N_{\text{max}} = 20$. This truncated space was sufficiently large to provide convergence of all observables to the accuracy shown in figure 1.

The calculations were carried out for an $N_{\text{max}} = 20$ truncation. The energies and $B(E2)$’s of the ground state band and the giant quadrupole resonance band are shown in figure 1 for both the uncoupled ($\kappa_1 = 0$) and coupled ($\kappa_1 \neq 0$) Hamiltonian.

The results in figure 1 show the extent to which the properties of a microscopic model Hamiltonian that have been derived in a large multi-shell calculation can be obtained much more simply from its macroscopic rotor-vibrator limit. The essential predictions of the CRV limit of the Hamiltonian (213) are that the coupling between low-energy $\text{U}(3)$ and giant-resonance degrees of freedom has a small effect on the low energy-level spectrum but, for an appropriate value of the $\kappa_1$ coupling constant, it essentially doubles the effective charge of quadrupole operators. In accord with these predictions, the figures show remarkably little change in the energy-level spectra of either the ground state or giant-resonance rotational bands due to a relative strong coupling. They also show the predicted enhancement of calculated quadrupole strengths. Recall that the strength of the coupling was chosen to reproduce experimental $E2$ transition rates. The enhancement of $\sim 1.8$ required to match experiment for the chosen representation is slightly smaller than, but comparable to, the factor of $\sim 2$ expected on the basis of mean-field self-consistency considerations [68, 145]; see the results of [140]. One must also be aware of the sensitivity of quadrupole moments and $E2$ transition rates to the tails of wave functions and, hence, to small components of the wave functions lost on truncation of the space and to the fundamental limitations of a very simple model.

12. Spin–orbit interactions

The nuclear spin $S$ and isospin $T$ are good quantum numbers of the $\text{Sp}(3, \mathbb{R}) \times \text{U}(2)_S \times \text{U}(2)_T$ coupling scheme. However, the spatial and spin–isospin degrees of freedom are inextricably intertwined by the total antisymmetry of many-nucleon wave functions. Thus, an $\text{Sp}(3, \mathbb{R})$ representation with a given space symmetry can only be combined with spin–isospin states of complementary symmetry. It follows that, if the isospin of an $\text{Sp}(3, \mathbb{R})$ representation of an even–even nucleus takes its smallest value $T = (N - Z)/2$, the spin $S$ of that representation is most often uniquely determined by the space symmetry of the $\text{Sp}(3, \mathbb{R})$ representation.

The spherical harmonic-oscillator states of even–even nuclei that are most deformed and most lowered in energy by a corresponding deformation of the harmonic-oscillator potential are states of maximal space symmetry with wave functions that are Slater-determinants of spin $S = 0$ and isospin $T = (N - Z)/2$. On the basis of shape-consistent mean-field considerations [68], it is also expected that the $\text{Sp}(3, \mathbb{R}) \times \text{U}(2)_S \times \text{U}(2)_T$ representations of a given isospin are partially ordered with those of smaller spin lying lower in energy, and those of $T = (N - Z)/2$ lying lowest.
For representations of non-zero spin, the intertwining of the spin and spatial degrees of freedom in forming lowest-weight symplectic states is particularly significant because, in the macroscopic limit in which a lowest-weight state becomes the intrinsic state of a rotor, it generates rotational states in which the spin and spatial degrees of freedom are strongly coupled as generally presumed in the Bohr–Mottelson–Nilsson model.

This follows from the observation that an irreducible $\text{Sp}(3, \mathbb{R}) \times U(2)_N$ representation has a macroscopic limit in which it approaches a $\text{ROT}(3) \times U(2)_N$ model with the same angular momenta and commuting quadrupole moment operators (also with high-energy giant-resonance vibrational states). Thus, it is expected that the low-energy rotational states of heavy nuclei with non-zero spin, will be close to those of a strongly coupled rotor-model with both $\text{SO}(3)$ rotational and $\text{SU}(2)$ spin angular momenta.

By definition, strong-coupling of the intrinsic spin of a rotor takes place in the intrinsic frame of the rotor as in the Nilsson model. It is favoured particularly in rotational nuclei in low total angular-momentum states, partly because of the adiabaticity of the rotational degrees of freedom and, more importantly, because the existence of four spin–isospin states allows the spatial states of nucleon to be maximally aligned [19] to form states of large deformation. This understanding underlies the interpretation of deformation alignment as opposed to rotational alignment and back-bending in nuclei [12, 147]. It also counters the concern that, although the spin–orbit interactions do not conserve $\text{SU}(3)$ or $\text{Sp}(3, \mathbb{R})$ symmetry, their symmetry breaking effects are expected to be suppressed in strongly deformed nuclei.

### 13. Relationships with mean-field models

The microscopic theory of collective dynamics has traditionally been approached in terms of Hartree–Fock (HF) mean-field theory, and its Hartree–Fock–Bogolyubov (HFB) and time-dependent (TDHF and TDHFB) extensions [148] 7. For a deformed nucleus, static HF theory, returns a minimal energy Slater determinant of single-nucleon states from among a continuous set of such determinants that is generally not rotationally invariant. The rotations and small-amplitude vibrations about such a minimum energy HF equilibrium state are then given by the TDHF extension of HF theory. A popular model based on this theory is Kumar and Baranger’s pairing-plus-quadrupole model [18, 149–152].

To appreciate the contribution that mean-field theory can make to the understanding of collective states of nuclei, it is useful to first contrast the HF theory of nuclear states with the theory of many-nucleon quantum mechanics. In both cases one starts with a so-called particle–hole vacuum state which is an anti-symmetric product of a subset of single-nucleon states described as occupied single-particle states. Such a state is a lowest-weight state for the irrep of the infinite-dimensional Lie algebra of one-body Hermitian operators, in the sense that

\[ J_k = L_k + S_k. \]  

(234)

By definition, strong-coupling of the intrinsic spin of a rotor takes place in the intrinsic frame of the rotor as in the Nilsson model. It is favoured particularly in rotational nuclei in low total angular-momentum states, partly because of the adiabaticity of the rotational degrees of freedom and, more importantly, because the existence of four spin–isospin states allows the spatial states of nucleon to be maximally aligned [19] to form states of large deformation. This understanding underlies the interpretation of deformation alignment as opposed to rotational alignment and back-bending in nuclei [12, 147]. It also counters the concern that, although the spin–orbit interactions do not conserve $\text{SU}(3)$ or $\text{Sp}(3, \mathbb{R})$ symmetry, their symmetry breaking effects are expected to be suppressed in strongly deformed nuclei.

### Figure 1

Comparison of the energies and $B(E2)$’s calculated obtained from the uncoupled $\kappa_1 = 0$ (left) and coupled $\kappa_1 = 0.006$ (right) Hamiltonians for the ground state band (bottom) and the giant quadrupole band (top). Energies are given in keV and $B(E2)$’s are in Weisskoff units.
it is annihilated by all the so-called particle–hole lowering operators. From this single particle–hole vacuum state, one can use the particle–hole raising operators of the Lie algebra of one-body operators to generate the whole many-nucleon Hilbert space of the nucleus. On the other hand, by applying the Lie group of one-body unitary transformations to the particle–hole vacuum state, one generates the continuous HF manifold of all possible Slater determinants for the nucleus. The many-nucleon Hilbert space and HF manifold are very different spaces but have an intimate and complementary relationship. Unlike a Hilbert space, the HF manifold is not a vector space which is evident from the fact that the sum of any two Slater determinants cannot be expressed as a single Slater determinant. In fact, a HF manifold has the properties of a classical phase space whereas the Hilbert space generated by the particle–hole raising operators is its quantisation. The geometry of a HF manifold as a classical phase and the TDHF dynamics on this space was shown, for example, in [153] (and references therein) and reviewed in chapter 8 of [142]. However, for present purposes we only need its simple familiar properties.

Some remarkable properties are seen to emerge if one starts from a lowest-weight state for a symplectic model irrep and restricts the group of one-body unitary transformations to those of the unitary irrep of Sp(3, R) with this lowest-weight state. It is well known that, for a suitable definition of the Sp(3, R) lowest-weight state as a U(3) highest-weight state, the Hilbert space of the lowest-grade U(3) representation is spanned by its SO(3) rotations through all angles. It is similarly known [58], that the whole Hilbert space of the Sp(3, R) irrep with this lowest-weight state, is spanned by the general linear transformations of its lowest-weight state.

By standard mean-field methods, one can find a state on this manifold in which the expectation value of a rotationally invariant Hamiltonian is minimised and which is oriented such that its monopole/quadrupole moments are aligned to give \( (Q_0) = \delta_{ij} q_i \). With respect to the nine-dimensional mean-field dynamics of the time-dependent mean-field equations of motion, the minimum energy state is then an equilibrium state with three rotational and six vibrational degrees of freedom. Thus, it can be interpreted as the intrinsic state of a microscopic version of a unified collective model. Moreover, in its macroscopic limits, its rotational dynamics is asymptotical that of a triaxial rotor and its vibrational degrees of freedom contract to those of a boson algebra. However, the quantisation of the microscopic version of this model, which is simply the symplectic model, is given by its irreducible unitary representation.

In this way one regains the CRV model and its relationship to the TDHF and TDHFB methods and the possibility of benefitting from the many insights obtained as, for example, the effects of pairing correlations. The mean-field perspective on the properties of the symplectic model is further developed in a forthcoming review [154].

14. Conclusions and challenges for further progress

Much has been gained from the complementary perspectives of nuclear structure underlying the Nobel prize winning models of the 1950 years. The Mayer–Jensen model of independent-particles in a spherical field led to the nuclear shell model while the Bohr–Mottelson–Rainwater model of particles moving as a fluid in a spheroidal field led to the nuclear collective models.

This review has focused on the evolution of many-nucleon models of nuclear collective states and their macroscopic limits that incorporate both of the early perspectives. The approach is based on the Dirac–Weyl [155, 156] formulation of the quantum mechanics of a system in terms of unitary representations of its algebra of observables. The perspective emerges that, whereas the many-nucleon Hilbert space is a sum of shell-model subspaces, it is also expressible as a sum of collective-model subspaces. Such collective-model subspaces are usefully defined as the spaces for irreducible representations of the direct product group \( \text{Sp}(3, \mathbb{R}) \times U(2)_b \times U(2)_r \), where \( U(2)_b \) and \( U(2)_r \) are, respectively, the nucleon spin and isospin groups. The decomposition (discussed further in [68]) corresponds to the use of the subgroup chains

\[
\text{Sp}(3, \mathbb{R}) \supset U(3) \supset \text{SO}(3), \tag{235a}
\]

\[
\text{SO}(3) \times U(2)_b \supset U(2)_r, \tag{235b}
\]

to define a coupling scheme for the many-nucleon Hilbert space. It has the significant property that there can be no non-zero matrix elements of a nuclear quadrupole moment, or any other element of the \( \text{Sp}(3, \mathbb{R}) \times U(2)_b \times U(2)_r \) Lie algebra, between states that belong to different collective-model subspaces. The selection rule associated with this property promises to provide a powerful tool in the experimental identification of the microscopic structure of observed collective states.

To describe the rotational properties of a deformed nucleus, it is appropriate to consider the restriction of a suitable Hamiltonian to a truncated many-nucleon space of many symplectic-model subspaces. However, this poses challenges as to the choice of subspaces and Hamiltonian to be employed. If it were not for practical limitations on the sizes of matrices that can be diagonalised, it would be meaningful to work in sufficiently large spherical harmonic-oscillator shell-model bases, that the results for the states of interest would not change to the required level of accuracy if the dimension of the shell-model space were increased. The physical significance of the results of the calculation could then be understood subsequently by expanding them in symplectic-model bases.

In fact, such calculations with realistic interactions have been successfully pursued in multi-shell calculations of low-energy states of light nuclei by Dytrych and colleagues [85–88, 157]. The calculations were carried out in \( U(3) \times U(2)_b \times U(2)_r \) coupled harmonic-oscillator shell-model bases and are especially valuable because they show
the emergence of results consistent with their expression in terms of a small number of $\text{Sp}(3, \mathbb{R}) \times \text{U}(2)_k \times \text{U}(2)_\gamma$ irreducible representations without a priori assumptions that they should do so. However, already for very light nuclei, such calculations require the use of supercomputers and it is inconceivable that corresponding calculations could be carried out, in the foreseeable future, for heavy nuclei for which the symplectic-model interpretation of collective dynamics was developed. Thus, a primary challenge in exploring the symplectic-model-based description of deformed nuclei is to identify the relevant collective- (i.e., symplectic-) model subspaces that are appropriate for the nuclear states of interest. This is important because, as discussed in several contributions to a focus issue on nuclear shape coexistence [158], there is strong evidence that many-nucleon states of much larger deformation than one would expect from a spherical shell-model perspective fall into the low-energy domain even in light nuclei.

In the spherical shell model, many-nucleon subspaces are ordered by the sums of the independent-particle energies of $jj$-coupled basis states. There is then a natural coupling scheme for a number of nucleons in such a subspace given by their pair-coupling [71, 72] symmetries. However, such a coupling scheme is wildly inappropriate for heavy strongly deformed nuclei for which the deformation of the mean field has a dominant controlling influence.

Within the framework of the collective model, the Nilsson model [8] and Mottelson’s comparisons of aligned versus pair coupling [19] indicate that deformation-alignment of nucleons takes place in the intrinsic frame of a rotor. Such a coupling has a natural realisation in mean-field theory in which states of good angular momentum are obtained by angular-momentum projection from minimal-energy mean-field states. However, this approach does not, in general, translate easily into a rotationally invariant coupling scheme for the many-nucleon Hilbert space because states projected from different mean-field states do not form complete orthonormal sets of states.

To our knowledge, the only coupling scheme for the many-nucleon Hilbert space that admits such deformation-aligned coupling, without restriction to eigenstates of a spherical harmonic oscillator, corresponds to an $LS$-coupled decomposition of the many-nucleon Hilbert space into a sum of $\text{Sp}(3, \mathbb{R}) \times \text{U}(4) \supset \text{U}(3) \times \text{U}(2)_k \times \text{U}(2)_\gamma$ invariant subspaces, where $\text{U}(4)$ is the Wigner supermultiplet group. In companions to this review [68, 154], the ordering of $\text{Sp}(3, \mathbb{R}) \times \text{U}(4)$ subspaces and the corresponding microscopic descriptions of collective states restricted to these subspaces is considered in terms of mean-field methods.

In this review, our primary concern has been with the interpretation of experimental data. If the mixing of different collective model subspaces is small, it would appear that, by analysis of experimental data in terms of the macroscopic limits of low-energy rotational bands as $\text{U}(3)$-rotor bands with an effective charge, it should be possible to identify candidates for the collective-model subspaces involved along the lines pursued by Jarrio et al [67]. Such analyses would at least assist in identifying critical data for which more accurate measurements are needed.

Identifying critical data for estimating $K$-band mixing in the description of rotational states is a particular challenge. It is difficult because the interband $E2$ transitions between states of good $K$ quantum numbers are small in comparison with large in-band transitions for close to axially symmetric nuclei. This suggests that the way to proceed would be to start with fits of macroscopic limits of the symplectic models, and their mixtures, to large bodies of experimental data. The systematics of nuclear shapes of nuclei and information gathered from nucleon transfer reactions and their Nilsson model interpretation would undoubtedly also provide valuable information.

In concluding this summary, it is emphasised that an essential difference between the Bohr–Mottelson–Nilsson and the macroscopically based model presented is that the BMN rotor is axially symmetric and has low-energy beta- and gamma-vibrational excitations, whereas the macroscopic limit of the symplectic model is a triaxial rotor with only high-energy giant-resonance excitations. Hopefully the analysis of experimental data will be able to distinguish between the two models. It must be recognised, however, that with coherent mixtures of rotational states it may be possible to generate states with some of the properties of beta and gamma vibrational states. For example, there is a distinct possibility that pairing interaction could effect a partial restoration of the axial symmetry by mixing different symplectic-model representations. A systematic study of candidates for one-phonon gamma vibrational states could be rewarding from this perspective and that of quasi-dynamical symmetry [73, 159].

Major challenges to unravelling the experimental implications for the microscopic structure of the rotational states of nuclei arise both from the mixing of different representations and the mixing of different rotational $K$ bands within a given representation. These are huge problems but hopefully they can be tackled from both ends, i.e., by considering theoretical models that produce results consistent with observed data.

An important consideration in the analysis of experimental data is that many candidates for $\text{Sp}(3, \mathbb{R}) \times \text{U}(2)_k \times \text{U}(2)_\gamma$ representations of the same spin and isospin are similar, in that their matrix elements are close to being linearly related to one another. As a result their differences can be accommodated for the most part by choice of an effective charge. It has also been observed that a symmetry breaking interaction has a tendency to mix the representations of a would-be dynamical symmetry in the coherent manner of the previously mentioned quasi-dynamical symmetry [73, 159]. When this happens, the states of the mixed representations behave as though they belonged to an average of the mixed representations and the transitions between such mixed bands of states tend to be systematic and relatively easy to interpret. However, this is a subject that merits further and detailed examination.

It is important to recognise that one can learn as much, perhaps more, from the limitations of a model as from its successes. Thus, one should always look for experimental or theoretical observations that disagree and are not naturally
explained in terms of a model. In the present context, it promises to be useful to explore the systematics of E2 and other transitions between states that are contrary to the expectations of the simple symplectic model in its asymptotic limits and have the potential to reveal phenomena associated with competing dynamical symmetries.

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