Reasoning on Schemata of Formulae*

Mnacho Echenim and Nicolas Peltier
University of Grenoble** (LIG, Grenoble INP/CNRS)

Abstract. A logic is presented for reasoning on iterated sequences of formulæ over some given base language. The considered sequences, or schemata, are defined inductively, on some algebraic structure (for instance the natural numbers, the lists, the trees etc.). A proof procedure is proposed to relate the satisfiability problem for schemata to that of finite disjunctions of base formulæ. It is shown that this procedure is sound, complete and terminating, hence the basic computational properties of the base language can be carried over to schemata.

1 Introduction

We introduce a logic for reasoning on iterated schemata of formulæ. The schemata we consider are infinite sequences of formulæ over a given base language, and these sequences are defined by induction on some algebraic structure (e.g. the natural numbers). As an example, consider the following sequence of propositional formulæ $\phi_n$, parameterized by a natural number $n$:

$$
\phi_0 \rightarrow \top \\
\phi_n+1 \rightarrow \phi_n \land (p(n) \Leftrightarrow p(n+1)).
$$

It is clear that the formula $\phi_n \land p(0) \land \neg p(n)$ is unsatisfiable, for every $n \in \mathbb{N}$. This can be easily checked by any SAT-solver, for every fixed value of $n$. Here the base language is propositional logic and the sequence is defined over the natural numbers. However, proving that it is unsatisfiable for every $n \in \mathbb{N}$ is a much harder task which obviously requires the use of mathematical induction.

Similarly, consider the sequence:

$$
\psi_{\text{nil}} \rightarrow \top \\
\psi_{\text{cons}(x,y)} \rightarrow \psi_y \land (\exists u \, p(y,u)) \Leftrightarrow (\exists v \, p(\text{cons}(x,y),v))
$$

Then $\psi_l \land p(\text{nil},a) \land \forall u \, \neg p(l,u)$ is unsatisfiable, for every (finite) list $l$. Here the base language is first-order logic and the sequence is defined over the set of lists. Such inductively defined sequences are ubiquitous in mathematics and computer

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** emails: Mnacho.Echenim@imag.fr, Nicolas.Peltier@imag.fr
science. They are often introduced to analyze the complexity of proof procedures. From a more practical point of view, schemata of propositional formulæ are used to model properties of circuits parameterized by natural numbers, which can represent, e.g., the number of bits, number of layers etc. (see for instance [14], where a language is introduced to denote inductively defined boolean functions which can be used to model such parameterized circuits). In mathematics, schemata of first-order formulæ can model inductive proofs, which can be seen as infinite (unbounded) sequences of first-order formulæ (see [5] for an example of the use of this technique in proof analysis).

We now provide a slightly more complex example. The following schema $\psi_i$ encodes a multiplexer, inductively defined as follows. The base case is denoted by $Base(x)$, where $x$ denotes an arbitrary signal. In this case, the output of the circuit is simply the output of $x$, denoted by $signal(x)$. The inductive case is denoted by $Ind(i, x, y)$, where $i$ is a select input and $x$ and $y$ are two smaller instances of the multiplexer. Its output is either the output of $x$ or that of $y$, depending on the value of $i$.

$$
\psi_{Base(x)} \rightarrow out(Base(x)) \leftrightarrow signal(x)
$$

$$
\psi_{Ind(i, x, y)} \rightarrow (\neg signal(i) \lor (out(Ind(x, y)) \leftrightarrow out(x)))
\land (signal(i) \lor (out(Ind(x, y)) \leftrightarrow out(y)))
\land \psi_x \land \psi_y
$$

Note that this kind of circuit cannot be encoded in the language of (regular) propositional schemata defined in [2,3], because the number of inputs is exponential in the depth of the circuit. Hence, the use of non-monadic function symbols is mandatory.

In this paper, we devise a proof procedure to check the satisfiability of these sequences. More precisely, we introduce a formal language for modeling sequences of formulæ defined over an arbitrary base language (encoded as first-order formulæ interpreted in some particular theory) and we show that the computational properties of the base logic carry over to these schemata: If the satisfiability problem is decidable (resp. semi-decidable) for the base language then it is also decidable (resp. semi-decidable) for the corresponding schemata. For instance, the satisfiability problem is decidable for schemata of propositional formulæ and semi-decidable for schemata of first-order formulæ. The basic principle of our proof procedure consists in relating the satisfiability of any iterated schemata of formulæ to that of a finite disjunction of base formulæ. The complexity of the satisfiability problem, however, is not preserved in general, since the number of formulæ in the disjunction may be exponential.

This work generalizes previous results [2,3] in two directions: first the base language is no longer restricted to propositional logic and second the sequences are defined over arbitrary algebraic structures, and not only over the natural numbers. Abstracting from the base language leads to an obvious gain in applicability since our approach now applies to any logic, provided a proof procedure

\footnote{A first extension to some decidable theories such as Presburger arithmetic was considered in [4].}
exists for testing the satisfiability of base formulæ. Besides, it has the advantage that the reasoning on schemata is now clearly separated from the reasoning on formulæ in the base language, which may be postponed. This should make our approach much more scalable, since any existing system could now be used as a “black box” to handle the basic part of the reasoning (whereas the two aspects were closely interleaved in our first approach, yielding additional computational costs). Both extensions significantly increase the scope of our approach.

The extension to arbitrary structures turns out to be the most difficult from a theoretical point of view, mainly because, as we shall see, the number of parameters can increase during the decomposition phase, yielding an increase of the number of related non-decomposable formulæ in each branch, which can in principle prevent termination. In contrast to what happens in the simpler case of propositional schemata [2], these formulæ cannot in general be deleted by the purity principle, since they are not independent from the other formulæ in the branch. To overcome this problem, we devise a specific instantiation strategy based on a careful analysis of the depth of terms represented by the parameters, and we define a new loop detection mechanism. This blocking rule is more general and more complex than the one in [2]. We show that it is general enough – together with the proposed instantiation strategy – to ensure termination. Termination is however much more difficult to prove than for propositional schemata defined over natural numbers.

The types of structures that can be handled are quite general: they are defined by sets of – possibly non-free – constructors on a sorted signature. The terms can possibly contain elements of a non-inductive sort. For instance, a list may defined inductively on an arbitrary set of elements.

Related Work

There exist many logics and frameworks in which the previous schemata can be encoded, for instance higher-order logic [7], first-order µ-calculus [17], or logics with inductive definitions [1] that are widely used in proof assistants [18]. However, the satisfiability problem is not even semi-decidable for these logics (due to Gödel’s famous result). Very little published research seems to be focused on the identification of complete subclasses and iterated schemata definitely do not lie in these classes and cannot be reduced to them either. Our approach ensures that the basic computational properties of the base language (decidability or semi-decidability) are preserved, at the cost of additional restrictions on the syntax of the schemata under consideration. Furthermore, the modeling of schemata in higher-order languages, although possible from a theoretical point of view, is cumbersome and not very natural in practice.

There exist several approaches in inductive theorem proving, ranging from explicit induction approaches (see for instance [11] or [6]) used mainly by proof assistants to implicit induction schemes used in rewrite-based theorem provers [8,9], or even to inductionless induction [15,12], where inductive validity is reduced to a mere satisfiability check. Such approaches can in principle handle
some of the formulæ we consider in the present work, provided the base language can be axiomatized. Existing approaches are usually only complete for refutation, in the sense that false conjectures can be disproved, but that inductive theorems cannot always be recognized (this is theoretically unavoidable). Once again, very few termination results exist for such provers and our language does not fall in the scope of the known complete classes (see for instance [13]).

In general, inductive theorem proving requires strong human guidance, especially for specifying the needed inductive lemmata. In contrast, our procedure is purely automatic. Of course, this comes at the expense of strongly reducing the form of the inductive axioms. Furthermore, although very restricted to ensure termination and/or completeness, our language allows for more general queries, possibly containing nested quantifiers, which are in general out of the scope of existing automated inductive theorem provers. Indeed, most existing approaches aim at establishing the inductive validity of universal queries w.r.t. a first-order axiomatization (usually a set of clauses). In contrast, our method can handle more general goals of the form $\forall x \phi$, where $x$ is a vector of variables interpreted over the considered algebraic structure and $\phi$ is a formula containing arbitrary quantifiers in the base language.

Practical attempts to use existing inductive theorem provers (such as ACL [10]) to check the satisfiability of schemata such as those in the Introduction fail for every formula except the most trivial ones. We believe that this is not due to a lack of efficiency, but rather to the fact that additional inductive lemmata are required, which cannot be generated automatically by the systems. In some sense, our method (and especially the loop detection rule) can be viewed as an automatic way to generate such lemmata. Our method is also more modular: we make a clear distinction between the reasoning over the base logic and the one over inductive definitions. Inference rules are devised for the latter and an external prover is used to establish the validity of formulæ in the base language.

Since parameterized schemata can obviously be seen as monadic predicates, a seemingly natural idea would be to encode them in monadic second-order logic and use an automata-based approach (see, e.g., [16]) to solve the satisfiability problem. However, as we shall see in Section 3, the unfolding of the inductive definitions contained in a given formula may well increase the number of parameters occurring in it. Since these parameters may share subterms, the formulæ containing them are not independent hence they must be handled simultaneously, in the same branch. Thus a systematic decomposition into monadic atoms (in the style of automata-based approaches) is not feasible.

All proofs can be found in the Appendix.

2 A Logic for Iterated Schemata

The schemata we consider in this paper are encoded as first-order formulæ, together with a set of rewrite rules specifying the interpretation of certain monadic predicate symbols. Our language is not a subclass of first-order logic: indeed, some sort symbols will be interpreted on an inductively defined domain (e.g.
on the natural numbers). Furthermore, the formulæ can be interpreted modulo some particular theory, specified by a class of interpretations.

We first briefly review usual notions and notations. We consider first-order terms and formulæ defined on a sorted signature. Let \( \mathcal{S} \) be a set of sort symbols. Let \( \Sigma \) be a set of function symbols, together with a function profile mapping every symbol in \( \Sigma \) to a unique non-empty sequence of elements of \( \mathcal{S} \). We write \( f : s_1 \times \cdots \times s_n \rightarrow s \) if profile\( (f) = s_1, \ldots, s_n, s \) with \( n > 0 \), and \( a : s \) if profile\( (a) = s \) (in this case \( a \) is a constant symbol). A symbol is of sort \( s \) and of arity \( n \) if its profile is of the form \( s_1, \ldots, s_n, s \) (possibly with \( n = 0 \)). The set of function symbols of sort \( s \) is denoted by \( \Sigma_s \). Let \( (V_s)_{s \in \mathcal{S}} \) be a family of pairwise disjoint set of variables of sort \( s \), and \( V \overset{\text{def}}{=} \bigcup_{s \in \mathcal{S}} V_s \). We denote by \( T_s \) the sets of terms of sort \( s \) built as usual on \( \Sigma \) and \( V \). A term not containing any variable is ground.

**Definition 1.** Let \( \mathcal{I} \) be a subset of \( \mathcal{S} \). The elements of \( \mathcal{I} \) are called the inductive sorts. An \( \mathcal{I} \)-term is a term of a sort \( s \in \mathcal{I} \).

Let \( \mathcal{C} \subseteq \Sigma \) be a set of constructors, such that the sort of every symbol in \( \mathcal{C} \) is in \( \bigcup_{s \in \mathcal{I}} \Sigma_s \) and such that every non-constant symbol of a sort in \( \bigcup_{s \in \mathcal{I}} \Sigma_s \) is in \( \mathcal{C} \). A parameter is a constant symbol of a sort occurring in the profile of a constructor (parameters are denoted by upper-case letters). A term containing only function symbols in \( \mathcal{C} \) and variables of sorts in \( \mathcal{S} \setminus \mathcal{I} \) is a constructor term.

Constructors of a sort \( s \in \mathcal{I} \) are meant to define the domain of \( s \), see Definition 6. The constant symbols that are not constructors can be seen as existential variables denoting arbitrary elements of a sort in \( \mathcal{I} \) (notice however that \( \mathcal{C} \) possibly contains constant symbols). We assume that \( \mathcal{I} \) contains a sort symbol \( \text{nat} \), with two constructors \( 0 : \text{nat} \) and \( \text{succ} : \text{nat} \rightarrow \text{nat} \).

**Example 1.** Assume that we intend to reason on lists of elements of an arbitrary sort \( s \). Then \( \mathcal{S} \) contains the sort symbols \( s \) and \( \text{list} \), where \( \mathcal{I} = \{\text{list}\} \). The constructors are \( \text{nil} : \text{list} \) and \( \text{cons} : s \times \text{list} \rightarrow \text{list} \). The set of parameters contains constant symbols of sorts \( s \) or \( \text{list} \) (denoting respectively elements and lists). If \( A_1, A_2 \) are parameters of sort \( s \), then \( \text{cons}(A_1, \text{cons}(A_2, \text{nil})) \) is a term of sort \( \text{list} \).

Similarly, if one wants to reason on lists of natural numbers, then one should take \( \mathcal{I} = \mathcal{S} = \{\text{nat}, \text{list}\} \). In this case, \( \mathcal{C} = \{\text{nil}, \text{list}, \text{cons} : \text{nat} \times \text{list} \rightarrow \text{list}, 0 : \text{nat}, \text{succ} : \text{nat} \rightarrow \text{nat}\} \).

Let \( (D_s)_{s \in \mathcal{I}} \) be a family of disjoint sets of defined symbols of sort \( s \), disjoint from \( \Sigma \), and \( D \overset{\text{def}}{=} \bigcup_{s \in \mathcal{I}} D_s \). An atom is either an equation of the form \( t \simeq s \), where \( t, s \) are terms of the same sort, or a defined atom, of the form \( d \equiv t \), where \( d \in D_s \), for some \( s \in \mathcal{I} \), and \( t \in T_s \). The arguments of the symbols in \( D \) are written as indices in order to distinguish them from predicate symbols that may occur in \( \Sigma \) (such predicate symbols may be encoded as functions of profile \( s \rightarrow \text{bool} \)). Formulæ are built as usual on this set of atoms using the connectives \( \land, \lor, \neg, \forall, \exists \). We assume for simplicity that all formulæ are in Negation Normal Form (NNF). A variable \( x \) is free in \( \phi \) if it occurs in \( \phi \), but not in the scope of the quantifier \( \forall x \) or \( \exists x \). If \( \phi \) has no free variables then \( \phi \) is closed.
An interpretation $I$ maps every sort $s$ to a set of elements $s^I$, every variable $x$ of sort $s$ to an element $x^I \in s^I$, every function symbol $f : s_1 \times \cdots \times s_n \rightarrow s$ to a function $f^I$ from $s_1^I \times \cdots \times s_n^I$ to $s^I$ and every defined symbol $d \in D_d$ to a subset of $s^I$. The set $\bigcup_{s \in S} s^I$ is the domain of $I$. As usual, any interpretation $I$ can be extended to a function mapping every term $t$ of sort $s$ to an element $[t]^I \in s^I$ and every formula $\phi$ to a truth value $[\phi]^I \in \{\text{true}, \text{false}\}$. We write $I \models \phi$ (and we say that $I$ validates $\phi$) if $[\forall x \phi]^I = \text{true}$, where $x$ is the vector of free variables in $\phi$. We assume, w.l.o.g., that the sets $s^I$ (for $s \in S$) are disjoint.

Sets of formulæ are interpreted as conjunctions. If $\phi$ and $\psi$ are two formulæ or sets of formulæ, we write $\phi \equiv_I \psi$ if either $I \models \phi$ and $I \models \psi$ or $I \not\models \phi$ and $I \not\models \psi$. We write $\phi \equiv \psi$ if $\phi \equiv_I \psi$ for all interpretations $I$.

We introduce two transformations operating on interpretations. The first one is simple: it only affects the value of some variables or constant symbols. If $I$ is an interpretation, $x_1, \ldots, x_n$ are distinct variables or constant symbols of sort $s_1, \ldots, s_n$ respectively and $v_1, \ldots, v_n$ are elements of $s_1^I, \ldots, s_n^I$, then we denote by $I[v_1/x_1, \ldots, v_n/x_n]$ the interpretation coinciding with $I$, except that for every $i = 1, \ldots, n$, we have: $x_i^I[v_1/x_1, \ldots, v_n/x_n] \overset{\text{def}}{=} v_i$.

The second transformation is slightly more complex. The idea is to change the values of the elements of an inductive sort, without affecting the remaining part of the interpretation. An $I$-mapping for an interpretation $I$ is a function $\lambda$ mapping every element $e$ in the domain of $I$ to an element of the same sort, that is the identity on every element occurring in a set $s^I$, where $s \notin I$. Then $\lambda(I)$ is the interpretation coinciding with $I$, except that for every symbol $f$ of a sort $s \notin I$, we have: $f^\lambda(I)(e_1, \ldots, e_n) \overset{\text{def}}{=} f^I(\lambda(e_1), \ldots, \lambda(e_n))$.

In the following, we assume that all interpretations belong to a specific class $\mathcal{I}$. This is useful to fix the semantics of some of the symbols, for instance one may assume that the interpretation of a sort $\text{int}$ is not arbitrary but rather equal to $\mathbb{Z}$. Of course, $\mathcal{I}$ is not arbitrary: the following definitions specify all the conditions that must be satisfied by the considered class of interpretations. We start by the interpretation of the defined symbols. As explained in the Introduction, the value of these symbols are to be specified by convergent systems of rewriting rules, satisfying some additional conditions defined as follows:

**Definition 2.** Let $<$ be an ordering on defined symbols. Let $\mathcal{R}$ be an orthogonal system of rules of the form $d_f(x_1, \ldots, x_n) \rightarrow \phi$, where $d$ is a defined symbol in $s$, $f$ is of profile $s_1 \times \cdots \times s_n \rightarrow s$, and $x_1, \ldots, x_n$ are distinct variables of sorts $s_1, \ldots, s_n$. We assume that $\phi$ and $\mathcal{R}$ satisfy the following conditions:

1. The free variables of $\phi$ occur in $x_1, \ldots, x_n$.
2. All $I$-terms occurring in $\phi$ belong to the set $\{x_1, \ldots, x_n, f(x_1, \ldots, x_n)\}$.
3. If $\phi$ contains a formula $d'_t$ then either $d' < d$ and $t = f(x_1, \ldots, x_n)$, or $t \in \{x_1, \ldots, x_n\}$.
4. For every constructor $f$, $\mathcal{R}$ contains a rule of the form $d_f(x_1, \ldots, x_n) \rightarrow \phi$.

It is clear from the conditions of Definition 2 that $\mathcal{R}$ is convergent (the condition on the ordering ensures termination, and orthogonality ensures confluence). We denote by $d_t \downarrow_{\mathcal{R}}$ the normal form of $d_t$ w.r.t. $\mathcal{R}$. The following condition states
that the interpretation of defined symbols must correspond to the one specified by the rewrite system $\mathcal{R}$, for every interpretation in $\mathcal{I}$.

**Definition 3.** An interpretation is $\mathcal{R}$-compatible iff for all sort symbols $s \in \mathcal{S}$, for all function symbols $f : s_1 \times \cdots \times s_n \to s$, we have $d_f(x_1, \ldots, x_n) \equiv_I d_{f(x_1, \ldots, x_n)}^{\mathcal{R}}$.

The second condition that is required ensures that any equation between two constructor terms can be reduced to equations between variables:

**Definition 4.** An interpretation is $\approx$-decomposable iff the following conditions hold:

1. For every $s \in \mathcal{S}$ and for every $f, g \in \Sigma_s$ of arity $n$ and $m$ respectively, there exists a formula $\Delta^{(f,g)}$ built on $\lor, \land, \approx$ and on $n + m$ distinct variables $x_1, \ldots, x_n, y_1, \ldots, y_m$ such that $f(x_1, \ldots, x_n) \approx g(y_1, \ldots, y_m) \equiv_I \Delta^{(f,g)}$.
2. For every $i \in [1, n]$ we have $\Delta^{(f,g)} \models \bigwedge_{k=1}^{m} x_i \approx y_k$, and for every $j \in [1, m]$, we have $\Delta^{(f,g)} \models \bigvee_{k=1}^{n} y_k \approx x_j$.

If $t = f(t_1, \ldots, t_n)$ and $s = g(s_1, \ldots, s_m)$ are two non-variable $\mathcal{I}$-terms, we denote by $\Delta(t \approx s)$ the formula obtained from $\Delta^{(f,g)}$ by replacing each variable $x_i$ ($1 \leq i \leq n$) by $t_i$ and each variable $y_j$ ($1 \leq j \leq m$) by $s_j$.

**Example 2.** If, for instance, elements of a sort $s \in \mathcal{S}$ are interpreted as terms built on a set of free constructors, then we have $\Delta^{(f,g)} \approx \bot$ if $f \neq g$ and $\Delta^{(f,f)} \equiv x_1 \approx y_1 \land \cdots \land x_n \approx y_n$ (where $n$ denotes the arity of $f$). Indeed, in this case, we have $f(x_1, \ldots, x_n) \approx f(y_1, \ldots, y_n) \equiv (x_1 \approx y_1 \land \cdots \land x_n \approx y_n)$. If, on the other hand, $g$ is intended to denote a commutative binary function then we should have: $\Delta^{(g,g)} = (x_1 \approx y_1 \land x_2 \approx y_2) \lor (x_1 \approx y_2 \land x_2 \approx y_1)$. The variables $x_1$ and $y_1$ are those introduced in Definition $\mathcal{I}$.

The third condition ensures that the interpretation of every inductive sort is minimal (w.r.t. to set inclusion).

**Definition 5.** An interpretation is $\mathcal{I}$-inductive iff for every $s \in \mathcal{S}$, and for every element $u \in s^I$, there exists a constructor term $t$ such that $u = [t]^I$.

Notice that, by definition, a constructor term contains no variable of a sort in $\mathcal{I}$. For instance, every element in $\text{nat}^I$ should be equal to a ground term $\text{succ}^k(0)$, for some $k \in \mathbb{N}$. If $\text{list}$ denotes the sort of the lists built on elements of a sort $s \notin \mathcal{I}$, then any element of $\text{list}^I$ must be equal to a term of the form $\text{cons}(x_1, \text{cons}(x_2, \ldots, \text{cons}(x_n, \text{nil}) \ldots))$, where $x_1, \ldots, x_n$ are variables of sort $s$. This condition implies in particular that for every $s \notin \mathcal{I}$ and for every element $v \in s^I$, there exists a variable $x$ such that $x^I = v$ (this is obviously not restrictive, since the variables may be interpreted arbitrarily).

The next definition summarizes all the conditions that are imposed:

**Definition 6.** A class of interpretations $\mathcal{I}$ is schematizable iff all interpretations $I \in \mathcal{I}$ satisfy the following properties:
1. \( I \) is \( \mathcal{R} \)-compatible.
2. \( I \) is \( \simeq \)-decomposable.
3. \( I \) is \( I \)-inductive.
4. For all variables \( v \) of a sort \( s \) and for all elements \( e \in s^I \), \( I[e/v] \in \mathcal{I} \).
5. For all \( I \)-mappings \( \lambda \), \( \lambda(I) \in \mathcal{I} \).

A formula \( \phi \) is \( \mathcal{I} \)-satisfiable iff \( \phi \) has a model in \( \mathcal{I} \).

From now on we focus on testing \( \mathcal{I} \)-satisfiability for a schematizable class of interpretations. Before that we impose some restrictions on the formulæ to be tested. As we shall see, these conditions will be useful mainly to ensure that the proof procedure presented in Section 3 only generates a finite number of distinct formulæ, up to a renaming of the parameters. This property is essential for the proof of termination, although it is not a sufficient condition.

**Definition 7.** A class of formulæ \( \mathcal{F} \) is admissible if all formulæ \( \phi \in \mathcal{F} \) satisfy the following properties:

1. For all parameters \( A, B \), \( \phi[B/A] \in \mathcal{F} \).
2. \( \phi \) contains no constructor and no variable of a sort in \( I \).
3. For every subformula \( \psi \) of \( \phi \), if \( \psi \) is not a disjunction, a conjunction, or a defined atom, then \( \psi \) contains no defined symbol and no pairs of distinct parameters.
4. For every defined symbol \( d \) occurring in \( \phi \) and for every rule \( d \rightarrow \phi \) in \( \mathcal{R} \), the formula obtained from \( \phi \) by replacing each \( I \)-term by an arbitrary parameter is in \( \mathcal{F} \).

A formula occurring in \( \mathcal{F} \) is a schema. It is a base formula iff it contains no defined symbol, and no equation between parameters.

The conditions in Definition 7 ensure that the formulæ in \( \mathcal{F} \) are boolean combinations (built on \( \lor, \land \)) of base formulæ containing at most one parameter, of defined atoms and of equations and disequations between parameters. The definition of base formulæ in Definition 7 ensures that the truth values of base formulæ do not depend on the interpretation of the parameters, but only on the relation between them. Base formulæ can contain parameters, but they can only occur as arguments of function symbols, whose images must be of a non-inductive sort. The only way of specifying properties of the parameters themselves (and not of the terms built on them) is by using the rewrite rules in \( \mathcal{R} \). As we shall see, this property is essential for proving the soundness of the loop detection rule that ensures termination of our proof procedure. Similarly, no quantification over variables of an inductive sort is allowed.

In the following, \( \mathcal{I} \) denotes a schematizable class of interpretations and \( \mathcal{F} \) denotes an admissible class of formulæ. The goal of the paper is to prove that if \( \mathcal{I} \)-satisfiability is decidable (resp. semi-decidable) for base formulæ in \( \mathcal{F} \) then it must be so for all formulæ in \( \mathcal{F} \). We give examples of classes of formulæ satisfying the previous conditions:
Example 3. Assume that $\Sigma$ only contains 0, succ and symbols of profile $\text{nat} \to \text{bool}$. Let $\mathfrak{I}_0$ be the class of all $\mathfrak{I}$-compatible interpretations on this language with the usual interpretation of $\text{nat}$, 0 and succ, and let $\mathfrak{I}_0$ be the set of all quantifier-free formulae containing no occurrence of 0 and succ. Clearly, $\mathfrak{I}_0$ is schematizable and $\mathfrak{I}_0$ is admissible. The formulæ in $\mathfrak{I}_0$ denote schemata of propositional formulæ. For instance the schema $p_0 \land \neg p_N \land \bigwedge_{K=0}^{N-1} (\neg p_K \lor p(\text{succ}(K)))$ is specified by the formulæ: $p(0) \land \neg p(N) \land d_N$, where $d$ is defined by the rules $d_0 \to \top$ and $d_{\text{succ}(K)} \to d_K \land (\neg p(K) \lor p(\text{succ}(K)))$. $\mathfrak{I}_0$ is equivalent to the class of regular schemata in \cite{3}.

Example 4. Let $\mathcal{S} = \{\text{nat}, \text{int}\}$ and $\mathcal{I} = \{\text{nat}\}$. Assume that $\Sigma$ contains the symbols 0 and succ, constant symbols of sort $\text{int}$, function symbols of profile $\text{nat} \to \text{int}$ and all the symbols of Presburger arithmetic. Let $\mathfrak{I}_\mathcal{Z}$ be the class of all $\mathfrak{I}$-compatible interpretations such that the interpretations of $\text{nat}, \text{int}, 0, \text{succ}, +, \cdot, \leq, \ldots$ are the usual ones. Let $\mathfrak{I}_\mathcal{Z}$ be the set of all formulae built on this language, containing no occurrence of 0, succ, and satisfying Condition 3 in Definition \ref{def:z}. It can be easily checked that $\mathfrak{I}_\mathcal{Z}$ is schematizable and that $\mathfrak{I}_\mathcal{Z}$ is admissible. Formulae in $\mathfrak{I}_\mathcal{Z}$ denote schemata of Presburger formulæ (the base formulæ in $\mathfrak{I}_\mathcal{Z}$ are formulæ of Presburger arithmetic). For instance $\bigvee_{K=0}^{N} a(K) > 0$ is denoted by $d_M$, with the rules $d_0 \to (a(0) > 0)$ and $d_{\text{succ}(K)} \to d_K \lor a(\text{succ}(K)) > 0$. Note however, that schemata containing atoms with several distinct terms of sort $\text{nat}$, such as $\bigwedge_{K=0}^{N} a(K) \simeq a(\text{succ}(K))$ cannot occur in $\mathfrak{I}_\mathcal{Z}$. It is also important to remark that the sort $\text{int}$ must be distinct from the sort of the indices $\text{nat}$ (terms of the form $d_{a(K)}$ are not allowed).

The class $\mathfrak{I}_\mathcal{Z}$ is not comparable to the class of SMT-schemata in \cite{4} (the latter class may contain formulæ of the previous form, at the cost of additional restrictions on the considered theory). Let $\mathfrak{I}_1$ and $\mathfrak{I}_1$ be the sets of interpretations and formulæ fulfilling the conditions of Definitions \ref{def:z} and \ref{def:z}. The following proposition is easy to establish ($\mathfrak{I}_0$ and $\mathfrak{I}_\mathcal{Z}$ are defined in Examples \ref{ex:z} and \ref{ex:z}).

**Proposition 1.** $\mathfrak{I}_0$-satisfiability (resp. $\mathfrak{I}_\mathcal{Z}$-satisfiability) is decidable for base formulæ in $\mathfrak{I}_0$ (resp. $\mathfrak{I}_\mathcal{Z}$), and $\mathfrak{I}_1$-satisfiability is semi-decidable for base formulæ in $\mathfrak{I}_1$.

Before describing the proof procedure for testing the satisfiability of schemata, we provide a simple example of an application. It is only intended to give a taste of what can be expressed in our logic, and of which properties are outside its scope (see also the examples in the Introduction, that can be easily encoded).

**Example 5.** A (binary) DAG $\delta$ labeled by elements of type $\text{elem}$ can be denoted by a function symbol $\text{elem} : \text{DAG} \to \text{elem}$, where the signature contains two constructors of sort $\text{DAG}$: a constant symbol $\bot$ (denoting the empty DAG), and a 3-ary symbol $c(n,l,r)$, where $l$ and $r$ denote the left and right children respectively and $n$ denotes the current node\cite{2}. Various properties can be expressed in our logic, for instance the following defined symbol $A_{\delta}^{l}\bowtie p$ expresses the fact that all the elements occurring in a DAG $\delta$ satisfies some property $p$.

\footnote{This extra-argument is necessary to ensure that distinct nodes can have the same children.}
\[ A_1^{δ,p} \rightarrow \top \quad A_2^{δ,p} \rightarrow A_1^{δ,p} \land A_2^{δ,p} \land p(δ(c(n,l,r))) \]

Obviously this can be generalized to any set of regular positions: for instance, we can state that there exists a path from the root to a leaf in the DAG on which all the element satisfy \( p \):

\[ E_{δ}^{Δ,p} \rightarrow \top \quad E_{c(n,l,r)}^{δ,p} \rightarrow (E_{δ}^{Δ,p} \lor E_{r}^{δ,p}) \land p(δ(c(n,l,r))) \]

\( δ \) and \( p \) are meta-variables: \( δ \) must be replaced by a function symbol of profile \( \text{DAG} \rightarrow \text{elem} \) and \( p \) can be replaced by any property of elements of sort \( \text{elem} \) (provided it is expressible in the base language e.g. first-order logic). For instance, we can express the fact that all the elements of \( δ \) are equal to some fixed value, or that all the elements of \( δ \) are even. We can check that the following formula is valid: \((∀x.p(x) \Rightarrow q(x)) \Rightarrow (E_{δ}^{Δ,p} \Rightarrow E_{δ}^{Δ.q})\). However, the converse cannot be expressed in our setting, because it would involve a quantification over an element of type \( \text{DAG} \) which is forbidden by Condition 2 in Definition 2. The formula \( A_{δ,p}^{Δ,p} \land \neg A_{δ,q}^{Δ,q} \land \neg A_{δ,q}^{Δ,q} \) is satisfiable on the interpretations whose domain contains two elements \( e_1, e_2 \) such that \( p(e_1), p(e_2), \neg q(e_1), \) and \( q(e_2) \) hold (but for instance it is unsatisfiable if \( p(x) \equiv (x \equiv 0)) \). We can express the fact that two DAGs \( δ \) and \( δ' \) share an element: \( ∃x, ∀y, (p(y) ⇔ x = y) \land \neg A_{δ,p}^{Δ'} \land \neg A_{δ',q}^{Δ'} \).

We can also define a symbol \( \text{Map}^{δ,δ',f} \) stating that \( δ' \) is obtained from \( δ \) by applying some function \( f \) on every element of \( δ \):

\[ \text{Map}_{c(n,l,r)}^{δ,δ',f} \rightarrow \top \quad \text{Map}_{c(n,l,r)}^{δ,δ',f} \land \text{Map}_{c(n,l,r)}^{δ,δ',f} \land δ'(c(n,l,r)) = f(δ(c(n,l,r))) \]

Then, we can check, for instance, that if all the elements of \( δ \) are even and if \( f \) is the successor function, then all the elements of \( δ' \) must be odd:

\[ (\text{even}(0) \land (\forall x. \text{even}(\text{succ}(x)) \equiv \neg \text{even}(x)) \land A_{A,\text{even}}^{δ,p}) \land \text{Map}_{c(n,l,r)}^{δ,δ',\text{succ}} \Rightarrow A_{A,\neg\text{even}}^{δ',q} \]

We are not able, however, to express transformations affecting the shape of the DAG (e.g. switching all the right and left subgraphs) because this would require to use non-monadic defined symbols.

\( \text{Alt}_{A}^{δ,p,q} \) expresses the fact that all the elements at even positions satisfy \( p \) and that the elements at odd positions satisfy \( q \):

\[ \text{Alt}_{c(n,l,r)}^{δ,p,q} \rightarrow \top \quad \text{Alt}_{c(n,l,r)}^{δ,p,q} \rightarrow A_{A}^{δ,p,q} \land \text{Alt}_{c(n,l,r)}^{δ,q,p} \land p(δ(c(n,l,r))) \]

Our procedure can be used to verify that \( \text{Alt}_{A}^{δ,p,q} \Rightarrow A_{A}^{δ,p,q} \). The following defined symbol \( p_{i}^{δ,δ',q'} \) states that a DAG \( δ'' \) is constructed by taking elements from \( δ \) and \( δ' \) alternatively:

\[ p_{c(n,l,r)}^{δ,δ',q''} \rightarrow \top \quad p_{c(n,l,r)}^{δ,δ',q''} \land p_{c(n,l,r)}^{δ,δ',q''} \land δ''(c(n,l,r)) = δ(c(n,l,r)) \]

We can check that if the elements of \( δ \) and \( δ' \) satisfy Properties \( p \) and \( q \) respectively, then the elements in \( δ'' \) satisfy \( p \) and \( q \) alternatively: \( p_{i}^{δ,δ',q'} \land A_{A}^{δ,p,q} \land A_{A}^{δ,q'} \Rightarrow A_{A}^{δ'',p,q} \).

Notice that, in this example, the subgraphs can share elements. Thus it is not possible in general to reason independently on each branch (in the style of automata-based approaches): one has to reason simultaneously on the whole DAG. Other data
structures such as arrays or lists can be handled in a similar way. An example of property that cannot be expressed is sortedness. Indeed, it would be stated as follows:

$$\text{Sort}^\delta_{\{n,l,r\}} \rightarrow \text{Sort}^\delta_{\{n,l,r\}} \land \delta(c(n,l,r)) \geq \delta_l \land \delta(c(n,l,r)) \geq \delta_r$$

However, the atom $$\delta(c(n,l,r)) \geq \delta_l$$ is not allowed in our setting: since it contains several parameters, it contradicts Condition 3 in Definition 4.

3 Proof Procedure

In this section, we present our procedure for testing the \(\exists\)-satisfiability of admissible formulas. We employ a tableaux-based procedure, with several kinds of inference rules: Decomposition rules that reduce each formula to a conjunction of base formulas, equational literals, and defined literals; Unfolding rules that allow to unfold the defined atoms (by applying the rules in \(\mathfrak{R}\)); Equality rules for reasoning on equational atoms; and Delayed instantiation schemes that replace a parameter \(A\) by some term \(f(B_1, \ldots, B_n)\), where \(f\) is a constructor and \(B_1, \ldots, B_n\) are new constant symbols. We consider proof trees labeled by sets of formulæ. If \(\alpha\) is a node in a tree \(T\) then \(T(\alpha)\) denotes the label of \(\alpha\). A node is closed if it contains \(\perp\). As usual, our procedure is specified by a set of expansion rules of the form $$\Psi_1 \cup \ldots \cup \Psi_n$$ with \(n \geq 1\), meaning that a non-closed leaf node labeled by a set \(\Phi \supseteq \Psi\) (up to a substitution of the meta-variables) may be expanded by adding \(n\) children labeled by \((\Phi \setminus \Psi) \cup \Psi_1, \ldots, (\Phi \setminus \Psi) \cup \Psi_n\), respectively. We assume moreover that the formulæ \(\Psi_1, \ldots, \Psi_n\) have not already been generated in the considered branch (to avoid redundant applications of the rules). For any tree \(T\), we write \(\alpha \geq_T \beta\) iff \(\beta\) is a child of \(\alpha\). \(\geq_T^+\) denotes as usual the reflexive and transitive closure of \(\geq_T\).

We need to introduce some additional notations and definitions. For any interpretation \(I\) and for any element \(v\) in the domain of \(I\), we denote by \(\text{depth}_I(v)\) the depth of the constructor term denoted by \(v\), formally defined as follows:

- \(\text{depth}_I(v) = 0\) if \(v\) is in \(D_s\) and \(s \notin I\), otherwise \(\text{depth}_I([f(t_1, \ldots, t_n)]^I) = 1 + \max\{\text{depth}_I([t_i]^I) \mid i \in [1, n]\}\), with the convention that \(\max(\emptyset) = 0\).

It is easy to check that the function \(v \mapsto \text{depth}_I(v)\) is well-defined, for every interpretation \(I \in \mathfrak{I}\).

For the sake of readability, we shall assume that there exists a function symbol \(\text{depth}\) such that: \(\text{depth}_I(v) \overset{\text{def}}{=} \text{depth}_I(v)\). The formula \(\max(E) \simeq t\) (where \(E\) is a finite set of terms) is written as a shorthand for \(\bigwedge_{s \in E}(s \leq t) \land \bigvee_{s \in E}(s \simeq t)\) if \(E \neq \emptyset\) and for \(0 \simeq t\) if \(E = \emptyset\).

Let \(T\) be a tree and let \(\alpha\) be a node in \(T\). A parameter \(A\) is solved in \(\alpha\) if the only formula of \(T(\alpha)\) containing \(A\) is of the form \(A \simeq B\) where \(B\) is a parameter. An equation \(A \simeq B\) is solved in \(\alpha\) if \(A\) is solved. Notice that \(\simeq\) is not considered as commutative. For every set of formulæ \(\Phi\), \(\text{Eq}(\Phi)\) denotes the set of equations in \(\Phi\) and \(\text{NonEq}(\Phi) \overset{\text{def}}{=} \Phi \setminus \text{Eq}(\Phi)\). A renaming is a function \(\rho\) mapping every parameter to a parameter of the same sort, such that \(\rho(N) = N\). Any renaming \(\rho\) can be extended into a function mapping every formula \(\phi\) to a formula \(\rho(\phi)\),
obtained by replacing every parameter $A$ occurring in $\phi$ by $\rho(A)$. Let $\Phi$ and $\Psi$ be two sets of formulae. We write $\Phi \sqsupseteq \Psi$ iff there exists a renaming $\rho$ such that $\rho(\Psi) \subseteq \Phi$.

A proof tree for $\phi$ is a tree constructed by the rules of Figure 1 below and such that the root is obtained by applying $\text{START}$ on $\phi$. We assume that $\lor$-$\text{DECOMPOSITION}$ and $\land$-$\text{DECOMPOSITION}$ are applied with the highest priority.

Most of the rules in Figure 1 are self-explanatory. We only briefly comment on some important points.

$\text{START}$ is only applied once, in order to create the root node of the tree. The label of this node contains the formula at hand together with an additional formula stating that the max of the depth of the constructor terms represented by the parameters must equal to some natural number $N$.

The decomposition and closure rules are standard. However, we do not use them to test the satisfiability of the formula, but only to decompose it into a conjunction of defined atoms, equational literals and base formulae. This is always feasible, thanks to the particular properties of formulæ in $\mathfrak{F}$ (see Definition 7). Notice that the separation rule has no premises. The only requirement is that $A$ and $B$ occur in the considered branch.

$\text{UNFOLDING}$ replaces a defined atom $d_A$ by its definition according to the rules in $\mathcal{R}$. This is possible only when the head symbol and arguments of the term represented by $A$ are known.

$\simeq$-$\text{DECOMPOSITION}$ decomposes equalities, using the specific properties of $\simeq$-decomposable interpretations: if a node contains two equations $A \simeq t$ and $A \simeq s$ then the formula $\Delta(t \simeq s)$ necessarily holds. $\not\simeq$-$\text{DECOMPOSITION}$ performs a similar task for inequalities.

Several rules are introduced to reason on the depth of the terms represented by the parameters. The principle is to separate the parameters representing terms of a depth exactly equal to $N$ from those whose depth is strictly less than $N$ (so that only the former ones may be instantiated). By definition of $\text{START}$, the initial node must contain an equation $\text{depth}(A) \preceq N$ for each parameter $A \neq N$. $\text{STRICNESS}$ expands this inequality by using the equivalence $x \preceq y \iff (x \prec y \lor x \simeq y)$. Then $\lor$-$\text{DECOMPOSITION}$ will apply, yielding either $x \prec y$ or $x \simeq y$.

$\prec$-$\text{DECOMPOSITION}$ gets rid of strict equalities of the form $\text{depth}(A) \prec \text{succ}(t)$ that are introduced by $N$-$\text{EXPLOSION}$.

The Explosion rules instantiate the parameters, which is done by adding equations of the form $A \simeq f(B)$, where $B$ is a vector of fresh parameters.

$\text{EXPLOSION}$ instantiates the parameters distinct from $N$. We choose to instantiate only the parameters representing terms of maximal depth, and only after $N$ has been instantiated. Thus we instantiate a parameter $B$ only if there exists an atom of the form $\text{depth}(B) \simeq t$, where $t$ is of the form $\text{succ}(s)$, for some $s \in \{0, N\}$. $\text{EXPLOSION}$ enables further applications of $\text{UNFOLDING}$, which in turn may introduce new complex formulæ into the nodes (by unfolding the defined symbols according to the rules in $\mathcal{R}$).

$N$-$\text{EXPLOSION}$ instantiates the parameter $N$. Since the depth of the terms of a sort in $I$ is at least 1 and since $N$ is intended to denote the maximal depth...
The root formula is \( \forall \) A term represented by occurs in the node, then A that satisfiability is preserved. The intuition is that if an equation such as and d consider the formula example 6. Consider the formula \( \forall x \neg p(x) \land d_A \), together with the rules: \( d_a \rightarrow p(b) \) and \( d_{f(x, y)} \rightarrow d_x \land d_y \) (where \( C = \{ ez, f s \rightarrow s, 0, succ \} \) and profile\( (A) = e \)). The root formula is \( \forall x \neg p(x) \land d_A \land \max\{\{\text{depth}(A)\}\} \simeq N \). By normalization using \( \land \)-Decomposition we get \( \{ \forall x \neg p(x), d_A, \text{depth}(A) \simeq N \} \). No rule applies, except N-Explosion, which replaces N by succ\( (0) \) or succ\( (N) \). In both cases, Explosion applies on A. In the first branch, the rule adds the formula \( A \simeq a \) and in the second one, it yields \( A \simeq f(B, C) \) (where B, C are fresh parameters). In the former branch, Unfolding replaces the formula \( d_A \) by \( p(b) \), then an irreducible node is reached. In the latter branch, the formula \( d_B \) and \( d_C \) are inferred. Then LOOP applies, using the renaming:
\( \rho(A) = B \) or \( \rho(A) = C \), hence the node is closed. The only remaining (irreducible) node is \( \{ p(b), \forall x \neg p(x) \} \). The unsatisfiability of this set of formulae can be easily checked.

The following example shows evidence of the importance of the depth rules:

**Example 7.** Consider the formula:
\[
p(A) \land d_A \land c_B
\]
with the rules \( d_{\text{succ}(x)} \rightarrow d_x, d_0 \rightarrow \top, c_{\text{succ}(x)} \rightarrow \bot \) and \( c_0 \rightarrow \neg p(0) \). If the parameters were instantiated in an arbitrary order, then one could choose for instance to instantiate \( A \) by \( \text{succ}(A') \), yielding an obvious loop (indeed, the unfolding of \( d_A \) yields \( d_{A'} \), thus it suffices to consider the renaming \( \rho(A) = A' \) and \( \rho(B) = B \)). Then the only remaining branch corresponds to the case \( A \simeq 0 \), which is actually unsatisfiable. This trivial but instructive example shows that reasoning on the depth of the parameters is necessary to ensure that the model will eventually be reached. In this example, the depth of \( A \) is maximal and that of \( B \) is not, e.g.: \( A \simeq \text{succ}(0) \) and \( B \simeq 0 \). The problem stems from the fact that Loop is *not* sound in general, since equational atoms are removed from the formulæ before testing for subsumption (the removal of such atoms is crucial for termination).

### 4 Properties of the Proof Procedure

This short section merely contains the theorems formalizing the main properties of the proof procedure. All proofs can be found in the Appendix. We first state that the previous rules are sound.

**Theorem 1.** Let \( T \) be a proof tree for a formula \( \phi \). If \( T \) is closed then \( \phi \) is unsatisfiable.

We then state that the procedure is complete, in the sense that the satisfiability of every irreducible node can be tested by the procedure for base formulæ.

**Theorem 2.** Let \( T \) be a proof tree. If \( \alpha \) is a node in \( T \) that is irreducible by all the expansion rules then \( T(\alpha) \) is \( \exists \)-satisfiable iff \( \text{NonEq}(T(\alpha)) \) is. Furthermore, \( \text{NonEq}(T(\alpha)) \) is a set of base formulæ.

We finally state that the procedure is terminating.

**Theorem 3.** The expansion rules terminate on every formula in \( \mathfrak{F} \).

**Corollary 1.** If the satisfiability problem is decidable (resp. semi-decidable) for base formulæ in \( \mathfrak{F} \) then it is so for all formulæ in \( \mathfrak{F} \).

### 5 Conclusion

We have proposed a proof procedure for reasoning on schemata of formulæ (defined by induction on an arbitrary structure, such as natural numbers, lists, trees etc.) by relating the satisfiability problem for such schemata to that of a finite disjunction of formulæ in the base language. Our approach applies to a wide range of formulæ, which may be interpreted in some specific class of structures (e.g. arithmetics). It may be seen as a generic way to add inductive capabilities
START: $φ, \max(\{\text{depth}(A_i) \mid i \in [1,n]\}) \simeq N$

Where $φ$ denotes the formula at hand

$A_1, \ldots, A_n$ are the parameters in $φ$

$∨$-DECOMPOSITION: $\phi \lor \psi \vdash \psi$ Λ-DECOMPOSITION: $\phi \land \psi \vdash \phi, \psi$ Λ-DECOMPOSITION: $\phi \land \psi$ not a base formula

Closure: $\neg φ, φ \perp \perp$ N-Closure: $0 \simeq \text{succ}(t)$

UNFOLDING: $d_A, A \simeq f(B) \psi \neg d_A, A \simeq f(B) \text{NNF}(\neg ψ)$

$\neg$-DECOMPOSITION: $A \simeq f(B), A \simeq g(C) \psi, A \simeq f(B)$

Where $ψ = Δ(f(B) \simeq g(C))$

REPLACEMENT: $φ[A/B], A \simeq B$ If $A$ and $B$ are two parameters and $A$ occurs in $φ$

$\leq$-DECOMPOSITION: $\text{depth}(A) \leq N \lor \text{depth}(A) < N$ $\iff$-DECOMPOSITION: $t \leq \text{succ}(N)$

$\iff$-SEPARATION: $\text{depth}(A) \leq N, \text{depth}(B) \simeq N$ $\text{depth}(A) < N, \text{depth}(B) \simeq N, A \neq B$ SEPARATION: $A \simeq B \lor A \neq B$

EXPLOSION: $\text{depth}(B) \simeq \text{succ}(t)$

\[ \forall i \in [1,n] \max(E_i) \simeq t \land B \simeq t \]

If $t_i$ are terms of the form $f_i(A_i)$, such that $f_1, \ldots, f_n$ are all the function symbols of the same sort as $B$, and the $A_i$'s are vectors of pairwise distinct, fresh, constant symbols of the appropriate sort, and $E_i$ is the set of terms $\text{depth}(C)$, where $C$ is a component of $A_i$ of a sort in $I$.

\[ \Phi \simeq \Phi[\text{succ}(0)/N] \simeq \Phi[\text{succ}(N)/N] \]

If no other rule applies and $N$ occurs in $\Phi$. Notice that in contrast with the previous rules, $\Phi$ must denote the whole label (not a subset of it)

\[ \Phi \perp \perp \]

If there exists in the same branch a (non leaf) layer labeled by a set of formulae $ψ$ such that $\text{NonEq}(ψ) \supset \text{NonEq}(ψ)$

\[ a \text{ See Definition } 4 \text{ for the definition of } Δ(t \simeq s) \]

Fig. 1. Expansion rules
into logical languages, in such a way that the main computational properties of the initial language (namely decidability or semi-decidability) are preserved. To the best of our knowledge, no published procedure offers similar features. There are very few decidability or even completeness results in inductive theorem proving and we hope that the present work will help to promote new progress in this direction. Future work includes the implementation of the proof procedure and its extension to non-monadic defined symbols.

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6 Proof of Proposition 1

Proof. Since the base formulae contain no equations between elements of sort nat, we can assume that all parameters are mapped to distinct natural numbers (it is clear that this operation preserves satisfiability). Then any formula in $\mathfrak{F}_0$ (resp. $\mathfrak{F}_2$, resp. $\mathfrak{F}_1$) is essentially equivalent to a propositional formula (resp. to a formula of Presburger arithmetic, resp. to a first-order formula).

7 Proof of Theorem 1

We begin by showing that \textsc{Start} preserves satisfiability:

Lemma 1. For every proof tree $T$ of root $\alpha$ for $\phi$, $\phi$ is $\mathcal{I}$-satisfiable iff $T(\alpha)$ has a model $I \in \mathcal{I}$.

Proof. By definition, $T(\alpha)$ is of the form $\{\phi\} \cup \{\max(\{\text{depth}(A_i) \mid i \in [1,n]\}) \leq N\}$, where $\{A_1,\ldots, A_n\}$ is the set of parameters occurring in $\phi$ and $N$ does not occur in $\phi$. Obviously, if $T(\alpha)$ is satisfiable, then $\phi$ also is. Conversely, let $I$ be a model of $\phi$. Let $J$ be the interpretation coinciding with $I$, except for the interpretation of $N$ that is defined as follows:

$$[N]^J \overset{\text{def}}{=} \max(\{\text{depth}_J([A_i]^J) \mid i \in [1,n]\})$$

Since $I$ and $J$ coincide on every symbol occurring in $\phi$ we must have $J \models \phi$. Furthermore, since $I$ and $J$ have the same domain and coincide on every constructor symbol, we must have $\text{depth}_I(v) = \text{depth}_J(v)$ for every element $v$. Consequently, for every $i \in [1,n]$ we have: $\text{depth}_J([A_i]^J) = \text{depth}_I([A_i]^J)$ (since $A_i \neq N$), hence $J \models \text{depth}(A_i) \leq N$. Thus $J \models T(\alpha)$.

We then show that most expansion rules preserve logical equivalence.

Lemma 2. The rules: $\lor$-\textsc{Decomposition}, $\land$-\textsc{Decomposition}, Closure, $N$-\textsc{Closure}, $\simeq$-\textsc{Closure}, Unfolding, $\simeq$-\textsc{Decomposition}, Replacement, Separation, Strictness, $\prec$-\textsc{Separation} and $\prec$-\textsc{Decomposition} are sound and invertible, i.e. for every proof tree $T$ and for every node $\alpha$ in $T$ on which one of these rules is applied, we have, for every interpretation $I \in \mathcal{I}$:

$$I \models T(\alpha) \iff \exists \beta, \beta \leq_T \alpha \land I \models T(\beta).$$

Proof. We consider each rule separately.

- Decomposition Rules. The proof is straightforward.

- Equality Rules.
  - $\simeq$-\textsc{Decomposition}: The node $\alpha$ is labeled by $\Phi \cup \{A \simeq f(A_1,\ldots, A_n), A \simeq g(B_1,\ldots, B_m)\}$ and has only one child $\beta$ labeled by $\Phi \cup \{\Delta(f(A_1,\ldots, A_n) \simeq g(B_1,\ldots, B_m)), A \simeq f(A_1,\ldots, A_n)\}$. Obviously, $T(\alpha) \equiv \Phi \cup \{f(A_1,\ldots, A_n) \simeq g(B_1,\ldots, B_n), A \simeq f(A_1,\ldots, A_n)\}$. By Condition $2$ in Definition $4$ we have $f(A_1,\ldots, A_n) \simeq g(B_1,\ldots, B_m) \equiv_I \Delta(f(A_1,\ldots, A_n) \simeq g(B_1,\ldots, B_m))$. Thus $T(\alpha) \equiv_I T(\beta)$. 


• \( \not\sim\)-Decomposition: The proof is similar.
• Separation: We have \( A \supseteq B \lor A \not\supseteq B \equiv \top \), hence the proof is immediate.
• Replacement: Obviously, \( \phi \land A \supseteq B \equiv \Phi[B/A] \land A \supseteq B \).
• \( \not\sim\)-Closure: By definition, \( A \not\supseteq A \equiv \bot \).

- Depth Rules.
  - Strictness: By definition of the interpretation of \( \leq \) and \( \prec \), we have \( \text{depth}(A) \leq N \equiv (\text{depth}(A) \supseteq N \lor \text{depth}(A) \prec N) \).
  - \( \not\prec \)-Separation: By definition of the interpretation of \( \prec \), if \( I \models A \supseteq B \) then \( I \models \text{depth}(A) \supseteq \text{depth}(B) \), thus \( \text{depth}(A) \not\prec N \land \text{depth}(B) \not\simeq N \equiv \text{depth}(A) \not\prec N \land \text{depth}(B) \not\simeq N \land A \not\supseteq B \).
  - \( \not\prec\)-Decomposition: By definition of the interpretation of \( \prec \) and succ, we have \( \text{depth}(A) \not\prec \text{succ}(N) \equiv \text{depth}(A) \not\simeq N \).

- Unfolding Rule.
  - Unfolding: The node \( \alpha \) is labeled by a set of formulæ \( \Phi \cup \{d_A\} \cup \{A \supseteq f(B)\} \). Moreover, \( \alpha \) has only one child \( \beta \) labeled by: \( \Phi \cup \{\psi\} \cup \{A \supseteq f(B)\} \), where \( \psi \) is the formula obtained from \( d_f(B)\downarrow_{\mathcal{RT}} \) by replacing every occurrence of \( f(B) \) by \( A \). If \( I \not\models A \supseteq f(B) \) then we have obviously \( T(\alpha) \equiv_I T(\beta) \equiv_I \bot \). Otherwise, \( \psi \equiv_I d_{f(B)}\downarrow_{\mathcal{RT}} \) and \( d_A \equiv_I d_{f(B)} \). Furthermore, by Condition 1 in Definition 8 we have \( d_{f(B)} \equiv_I d_{f(B)}\downarrow_{\mathcal{RT}} \).

We now prove that the remaining rules (except Loop) preserve \( \exists \)-satisfiability. We first need to analyze the form of the formula containing \( \text{depth} \) occurring in the proof tree:

**Lemma 3.** A depth-atom is an atom containing the depth function symbol. Let \( T \) be a proof tree and let \( \alpha \) be a node in \( T \). If \( \phi \) is depth-atom occurring in a formula \( \psi \in T(\alpha) \) then:

- \( \psi \) is a boolean combination of depth-atoms.
- \( \phi \) is of the form \( \text{depth}(A) \prec t \), where \( t \in \{\preceq, \prec, \leq\} \) and \( t \in \{N, \text{succ}(N), \text{succ}(0)\} \).
- If \( \alpha \) is a layer, then \( \prec \in \{\preceq, \prec\} \).

**Proof.** The only rules that can introduce formulæ containing \( \text{depth} \) are Start, Strictness, \( \not\prec\)-Decomposition and Explosion. It is clear, by inspection of these rules, that the added formulæ fulfill the above properties. Moreover, if \( \alpha \) is a layer then by irreducibility w.r.t. \( \not\sim\)-Decomposition and \( \not\sim\)-Decomposition, \( \psi \) must be an atom. By irreducibility w.r.t. Strictness, \( \prec \) cannot be \( \leq \) and by irreducibility w.r.t. Explosion, \( t \) must be \( N \). N-Explosion can affect the right-hand side of a depth-atom by replacing \( N \) by \( \text{succ}(N) \) or \( \text{succ}(0) \). However, due to the control, this rule is only applied on layers, thus the right-hand side must be \( N \), hence no formula of the form \( \text{succ} \left( \text{succ}(t) \right) \) can be introduced.

**Lemma 4.** The rules Explosion and N-Explosion preserve satisfiability: for every proof tree \( T \) and for every node \( \alpha \) in \( T \) on which one of these rules is applied and for every interpretation \( I \in \mathcal{I} \), the following properties are equivalent:
Proof. This is an immediate consequence of Lemmata 2 and 4.

Corollary 2. Let $\mathcal{T}$ be a proof tree. Then:

- If $I \models \mathcal{T}(\beta)$ and $\alpha \geq_{\mathcal{T}} \beta$ then $I[[[N]^l + k]/N] \models \alpha$.
- If $I \models \mathcal{T}(\alpha)$ then there exists a leaf $\beta$ such that $\alpha \geq_{\mathcal{T}} \beta$ and an interpretation $J$ such that $J \models \mathcal{T}(\beta)$, $I$ and $J$ coincide on any symbol occurring in $\mathcal{T}(\alpha)$ distinct from $N$ and $[N]^l = [N]^l - 1$.

Proof. This is an immediate consequence of Lemmata 2 and 1.
There only remains to handle the case of the Loop rule, which is actually the most complex one. To this aim, we need to introduce some additional definitions and lemmata.

**Definition 8.** A parameter $A$ is instantiated in a node $\alpha$ of a proof tree $T$ iff $T(\alpha)$ contains a formula of the form $A \simeq f(B)$. It is $N$-controlled if $T(\alpha)$ contains a formula of the form $\text{depth}(A) \prec t$ with $\prec \in \{\prec, \simeq, \preceq\}$.

**Definition 9.** A node that is irreducible by $\lor$-Decomposition and $\land$-Decomposition is decomposed.

We write $\alpha \triangleright_T \beta$ if $\alpha$ is non-decomposed and $\alpha \geq_T \beta$. Due to the control, $\beta$ is obtained by applying $\lor$-Decomposition or $\land$-Decomposition.

**Proposition 2.** Let $T$ be a proof tree. Let $\alpha \geq_T \beta$.

1. If $A$ is instantiated in $\alpha$ and not solved in $\beta$ then it is also instantiated in $\beta$.
2. If $A$ is $N$-controlled in $\alpha$ and if $\alpha \triangleright_T \beta$ then $A$ is $N$-controlled in $\beta$.

**Proof.** 1. If $A$ is instantiated in $\alpha$ then $T(\alpha)$ contains a formula of the form $A \simeq f(B)$. Since $A$ cannot be replaced, it is easy to check (by inspection of the expansion rules) that no rule can remove such a formula (except $\simeq$-Decomposition, but in this case another formula of the form $A \simeq g(C)$ occurs in the node). Thus $A$ is instantiated in $\beta$.
2. This is immediate since $\lor$-Decomposition and $\land$-Decomposition cannot delete non-complex formulæ.

**Lemma 5.** Let $T$ be a proof tree. Let $\alpha$ be a non-closed decomposed node in $T$. Every parameter distinct from $N$ occurring in $T(\alpha)$ that is neither solved nor instantiated is $N$-controlled in $\alpha$.

**Proof.** The proof is by induction on the depth of $\alpha$ in $T$.

Assume first that all the parent nodes of $\alpha$ are non-decomposed. Since $\lor$-Decomposition and $\land$-Decomposition are applied with the highest priority, this implies that $\gamma \triangleright_T \alpha$, where $\gamma$ is the root of $T$. These rules cannot introduce new parameters hence $A$ occurs in $T(\gamma)$. Thus, by definition of $\text{Start}$, $T(\gamma)$ must contain exactly one formula of the form $\text{depth}(A) \preceq N$. Hence $A$ is $N$-controlled in $\gamma$. By Proposition 2 (Point 2), it must be $N$-controlled in $\alpha$.

Now assume that there exists a node $\beta \geq_T \alpha$ that is irreducible by $\lor$-Decomposition and $\land$-Decomposition. We assume that $\beta$ is the deepest node having this property. Then there exists a node $\lambda$ such that $\beta \geq_T \lambda \triangleright_T \alpha$. We distinguish two cases.

- Assume that $A$ occurs in $T(\beta)$. By Proposition 2 (Point 1), $A$ is also non-instantiated in $\beta$. By the induction hypothesis, $\beta$ contains a formula $\text{depth}(A) \prec t$. If $A$ is $N$-controlled in $\lambda$ then the proof follows immediately from Proposition 2 (Point 2). Now assume that $A$ is not $N$-controlled in $\lambda$, i.e., that the rule applied to $\beta$ deletes the formula $\text{depth}(A) \prec t$. By inspection of the expansion rules, it can be seen that the only rules that can
Let Proposition 4. The proof is by structural induction on \( \lambda \). If \( \lambda \) is decomposed, \( T(\alpha) \) contains either \( depth(A) \geq N \) or \( depth(A) \leq N \), hence \( A \) is \( N \)-controlled in \( \alpha \), which is impossible by assumption. If \( \alpha \) is decomposed, \( T(\alpha) \) contains either \( depth(A) \geq N \) or \( depth(A) \leq N \), hence \( A \) is \( N \)-controlled in \( \alpha \). If \( \alpha \) is decomposed, \( T(\alpha) \) contains either \( depth(A) \geq N \) or \( depth(A) \leq N \), hence \( A \) is \( N \)-controlled in \( \alpha \). If \( \alpha \) is decomposed, \( T(\alpha) \) contains either \( depth(A) \geq N \) or \( depth(A) \leq N \), hence \( A \) is \( N \)-controlled in \( \alpha \).

Now, assume that \( A \) does not occur in \( T(\beta) \). The only rule that can introduce a new parameter \( A \) is \( \text{EXPL} \), but this rule simultaneously introduces a formula \( \text{max}(E) \geq N \), where \( A \in E \). After some decomposition steps, an atom of the form \( depth(A) \geq N \) or \( depth(A) \leq N \) must occur in every branch. Thus the property remains true.

**Definition 10.** Let \( I \) be an interpretation, let \( A \) be a parameter of sort \( s \) and let \( v \) be an element of \( s^I \). We denote by \( \lambda(I,A,v) \) the \( I \)-mapping for \( I \) such that \( \lambda(v) \equiv A^I \) and \( \lambda(e) \equiv e \) for every \( e \neq v \), and by \( J(I,A,v) \) the interpretation obtained from \( \lambda(I) \) by replacing the value of every parameter \( B \) such that \( I \models B \equiv A \) by \( v \).

**Proposition 3.** Let \( \phi \) be a base formula. Let \( I \) be an interpretation, let \( A \) be a parameter of sort \( s \) and let \( v \) be an element of \( s^I \). If for all parameters \( B \) occurring in \( \phi \), we have \( B^I \neq v \), then:

1. For every term \( t \) of a sort \( s' \notin \mathcal{I} \) occurring in \( \phi \), we have \( [t]^{J(I,A,v)} = [t]^I \).
2. For every subformula \( \psi \) of \( \phi \), \([\psi]^{J(I,A,v)} = [\psi]^I \).}

*Proof.* The proof is by structural induction on \( \psi \) and \( \phi \). We only give the detailed proof for \( \psi \), since the inductive cases for \( \psi \) are straightforward (since base formulæ cannot contain equations between terms of a sort in \( \mathcal{I} \)).

Let \( J = J(I,A,v) \) and \( \lambda = \lambda(I,A,v) \). If \( t \) is a variable, then \( I \) and \( J \) coincide on \( t \), thus we have \( [t]^J = [t]^I \). Assume that \( t \) is of the form \( f(t_1,\ldots,t_n) \), where \( f \) is a function symbol of profile \( s_1 \times \cdots \times s_n \rightarrow s \). By definition of \( \lambda(I) \), we have \( [t]^J = f^I(\lambda[t_1]^I,\ldots,\lambda[t_n]^I) \).

By the induction hypothesis, for every \( i \in [1,n] \), if \( s_i \notin \mathcal{I} \) then \( [t_i]^J = [t_i]^I \), thus \( \lambda([t_i]^J) = [t_i]^I \) (since \( \lambda \) is the identity on any element distinct from \( v \), hence on any element of the domain of a sort non occurring in \( \mathcal{I} \)).

Now, assume that there exists \( i \in [1,n] \) such that \( t_i \) is of an inductive sort. Since \( t \) occurs in \( \phi \), it cannot contain any constructor symbol (by Condition 2 in Definition 2), hence \( t_i \) must be a parameter. If \( I \models t_i \equiv A \), then \( \lambda([t_i]^J) = \lambda(v) = [A]^I = [t_i]^I \). Otherwise \( \lambda([t_i]^J) = \lambda([t_i]^I) = [t_i]^I \).

Thus for all \( i \in [1,n] \), \( \lambda([t_i]^J) = [t_i]^I \) and \( [t]^J = f^I([t_1]^I,\ldots,[t_n]^I) = [t]^I \).

**Proposition 4.** Let \( \mathcal{T} \) be a proof tree. Let \( \alpha \) be a layer in \( \mathcal{T} \). Let \( I \) be a model of \( \mathcal{T}(\alpha) \). If \( A \) is neither solved nor instantiated in \( \alpha \) then \( \text{depth}_I([A]^I) \leq [N]^I \).

If \( A \) is instantiated in \( \alpha \) then \( \text{depth}_I([A]^I) > [N]^I \).
Proof. The first point is a direct consequence of Lemma \[1\]. Let \(A\) be a parameter that is instantiated in \(\alpha\). Then \(T(\alpha)\) must contain a formula of the form \(A \simeq f(B_1, \ldots, B_n)\). The only rule that can introduce such a formula is EXPLOSION. Thus there must exist a node \(\beta \succeq \alpha\) on which EXPLOSION is applied, yielding a formula of the form \(A' \simeq f(B'_1, \ldots, B'_n)\). Furthermore, \(A'\) must be reduced to \(A\) by REPLACEMENT, hence there exist \(k\) nodes \(A_1, \ldots, A_k\) with \(A_1 = A, A_k = A'\) and for all \(i \in [1, k-1]\), there exists a node \(\gamma_i\) such that \(\beta \succeq \gamma_i \succeq \alpha\) and \(A_i \simeq A_{i+1} \in T(\gamma_i)\). By definition of EXPLOSION, \(T(\beta)\) contains a formula \(\text{depth}(A') \simeq \text{succ}(N)\). By Corollary \[2\] there exists \(l \in \mathbb{N}\) such that \(I[[N]^l + l/N]\) validates the formula \(\text{depth}(A') \simeq \text{succ}(N)\) and all the formulæ \(A_i \simeq A_{i+1}\) \((1 \leq i \leq k-1)\). Then we must have \(\text{depth}_I(A) = [\text{succ}(N)]^l + l > [N]^l\).

**Proposition 5.** Let \(T\) be a proof tree. Let \(\alpha\) be a layer in \(T\). Any equation between parameters occurring in \(T(\alpha)\) is solved.

Proof. If \(T(\alpha)\) contains a non-solved equation \(A \simeq B\) then by definition REPLACEMENT would apply.

**Lemma 6.** Let \(T\) be a proof tree. Let \(\alpha\) be a layer in \(T\). If \(I \models \text{NonEq}(T(\alpha))\) then there exists an interpretation \(J\) such that \(J \models T(\alpha)\) and \([N]^I = [N]^J\).

Proof. We denote by RmEq(\(\Phi\)) the set obtained from \(\Phi\) by removing all formulæ of the form \(A \simeq f(B)\).

If \(I \models \text{NonEq}(T(\alpha))\) then it is obvious that there exists an interpretation \(I'\) such that \(I' \models \text{RmEq}(T(\alpha))\); indeed, all the formulæ occurring in \(\text{RmEq}(T(\alpha))\), but not in \(\text{NonEq}(T(\alpha))\), are equations between parameters, which must be solved by Proposition \[3\]. Thus it suffices to interpret each solved parameter \(A\) in the same way as the – necessarily unique – parameter \(B\) such that \(A \simeq B\) occurs in \(\text{RmEq}(T(\alpha))\).

\(N\) cannot be solved, thus \([N]^I = [N]^J\). By definition, the solved parameters cannot occur in \(\text{NonEq}(T(\alpha))\), thus \(I\) and \(I'\) coincide on any formulæ in \(\text{NonEq}(T(\alpha))\) and \(I' \models \text{NonEq}(T(\alpha))\). Moreover, \(I'\) validates all solved equations, by definition.

Let \(>\) be a total order on parameters such that \(A > B\) if \(\text{depth}_I(A) > \text{depth}_I(B)\).

For any parameter \(A\), we denote by \(\text{RmEq}'(\Phi, A)\) the set of formulæ obtained from \(\Phi\) by deleting all formulæ of the form \(B \simeq f(B)\) where \(B > A\). We shall show, by induction on \(A\), that one can construct an interpretation \(J\) such that \(J \models \text{RmEq}'(T(\alpha), A)\) and \([N]^J = [N]^I\). Then the result will follow, simply by instantiating \(A\) with the \(<\)-maximal parameter.

Assume that \(J\) has been constructed for the greatest parameter \(C\) such that \(A > C\) (if \(A\) is minimal, then we simply take \(J = I'\)). If \(T(\alpha)\) contains no formulæ of the form \(A \simeq f(B_1, \ldots, B_n)\) then obviously \(\text{RmEq}'(T(\alpha), A) = \text{RmEq}'(T(\alpha), C)\) and \(J \models \text{RmEq}'(T(\alpha), A)\). Thus we assume that \(T(\alpha)\) contains such a formulæ. Since \(\alpha\) is a layer, by irreducibility w.r.t. \(\simeq\)-DECOMPOSITION, this formulæ must be unique. Let \(v = [f(B_1, \ldots, B_n)]^I\). Let \(\lambda = \lambda(I, v, A)\) and \(K = J(J, v, A)\).
We first show that for all parameters in \( \text{RmEq}'(T(α), A) \), we have \([A']^j \neq v\).

Notice that, by definition, \( A' \) cannot be solved in \( α \). If \( A' \) is non-instantiated then by Proposition 4 we have \( \text{depth}_J(A') \leq N \). Moreover, since \( A \) is instantiated, we have, still by Proposition 4 \( \text{depth}_J(A) > n \), thus \( \text{depth}_J(v) > n \) and \([A']^j \neq v\).

If \( A' \) is instantiated, \( T(α) \) contains a formula \( A' \simeq g(B'_1, \ldots, B'_k) \). By irreducibility w.r.t. SEPARATION, \( T(α) \) contains \( A \neq A' \). By irreducibility w.r.t. \( \neq \text{-DECOMPOSITION} \), \( T(α) \) must contain a set of disequations \( E \) between elements of \( B_1, \ldots, B_n, B'_1, \ldots, B'_k \) such that \( E \vdash f(B_1, \ldots, B_n) \neq g(B'_1, \ldots, B'_k) \). But \( E \subseteq \text{RmEq}'(T(α), A) \), thus \( J \models E \), whence \([A']^j \neq [A]^j\).

By definition \( K \models A \simeq f(B_1, \ldots, B_n) \). Let \( φ \) be a formula occurring in \( \text{RmEq}'(T(α), A) \). We know that \( J \models φ \). We prove that \( K \models φ \).

By Proposition 3 if \( φ \) is a base formula then \([φ]^j = [φ]^K\), thus \( K \models φ \).

If \( φ \) is of the form \( \text{depth}(A') \triangleleft N \). for some \( \triangleleft \in \{\leq, \prec, \sim\} \) then by Proposition 4 \( A' \) cannot be instantiated, hence \( A' \neq A \) and \( J,K \) coincide on \( φ \), thus \( K \models φ \).

If \( φ \) is of the form \( A' = g(B_1, \ldots, B_m) \) then we have \( A' < A \), hence \( B'_1, \ldots, B'_m > A \), thus \( J \) and \( K \) coincide on \( A, B'_1, \ldots, B'_m \) and the proof is immediate.

If \( φ \) is of the form \( B \simeq C \) or \( B \neq C \) then by definition of \( K \) we have \( K \models φ \).

**Proposition 6.** If \( Φ \supseteq Ψ \) and \( I \models Φ \) then there exists an interpretation \( J \) such that \([N]^j = [N]^I\) and \( J \models Ψ \).

**Proof.** By definition, we have \( ρ(Ψ) \subseteq Φ \), for some renaming \( ρ \). It suffices to consider the interpretation \( J \) coinciding with \( I \) except that every parameter \( A \) is mapped to \([ρ(A)]^I\).

It is clear that for every expression \( e, [e]^j = [ρ(e)]^I \). Since \( I \models Φ \) we have \( I \models ρ(Ψ) \), hence \( J \models Ψ \).

A proof tree \( T \) is \( J \)-satisfiable iff there exists a leaf node \( α \) in \( T \) such that \( T(α) \) is \( J \)-satisfiable.

**Lemma 7.** LOOP preserves global satisfiability i.e. if \( T \) is \( J \)-satisfiable then any proof tree \( T' \) obtained from \( T \) by applying LOOP is also \( J \)-satisfiable.

**Proof.** Let \( α \) be the node on which LOOP is applied. \( T' \) is identical to \( T \) except that \( α \) has a child \( β \) whose label contains \( ⊥ \). Obviously, if \( T' \) is satisfiable then so is \( T \) (since all \( J \)-satisfiable leaves of \( T' \) are in \( T \)).

Conversely, let \( γ \) be the root of \( T \) and let \( I \) be a model of \( T(γ) \) such that the interpretation of \( N \) is minimal (i.e. if \([N]^j < [N]^I\) then \( J \models T(γ) \)). By Corollary 2 there exists a leaf \( α' \) in \( T \) and an interpretation \( J \) such that \( J \models T(α') \), \( γ \models T, k \ α' \) and \([J]^N = [I]^N - k \). If \( α' \) is distinct from \( α \), then \( α' \) is a leaf in \( T' \) and the proof is immediate. Thus we assume that \( α' = α \). By definition of LOOP, there exists a node \( β \geq γ \ α \) such that \( \text{NonEq}(Φ) \supseteq \text{NonEq}(Ψ) \), with \( T(α) = Φ \) and \( T(β) = Ψ \). By Proposition 6 there exists an interpretation \( J' \) such that \( J' \models \text{RmEq}(Ψ) \) and \([N]^j = [N]^I \). By Lemma 6 there exists an interpretation \( J'' \) such that \( J'' \models Ψ \) and \([N]^j = [N]^I \).

By definition, there exist \( k' \) and \( k'' > 0 \) such that \( γ \geq T, k' \ β \geq T, k'' \ α \), where \( k = k' + k'' \). By Proposition 5 there exists an interpretation \( K \) such that \( K \models
$\mathcal{T}(\alpha)$ and $[N]^K = [N]^J = [N]^I - k$. By Corollary 2, $J''([N]^J + k')/N \models T(\gamma)$. But the value of $N$ in $J''([N]^J + k')$ is $[N]^I - k + k'' = [N]^I - k''$. Since $k'' \neq 0$ this contradicts the minimality of $I$.

Main proof

This follows immediately from the previous lemmata.

8 Proof of Theorem 2

Lemma 8. Let $\mathcal{T}$ be a proof tree. Let $\alpha$ be a layer in $\mathcal{T}$. Let $\phi$ be a formula in $\text{NonEq}(\mathcal{T}(\alpha))$. One of the following conditions holds:

- $\phi$ is a base formula.
- $\phi$ is of the form $d_A$ where $A$ is a parameter.
- $\phi$ is of the form $\text{depth}(A) \triangleleft N$, where $\triangleleft \in \{\triangleleft, \simeq\}$.
- $\phi$ is of the form $A \not\simeq B$, where $A, B$ are parameters.

Furthermore, if $A$ and $B$ are two non solved parameters occurring in $\mathcal{T}(\alpha)$ then $A \not\simeq B \in \mathcal{T}(\alpha)$.

Proof. Let $\phi$ be a formula occurring in $\text{NonEq}(\mathcal{T}(\alpha))$. By definition, $\phi$ cannot be an equation. If $\phi$ contains a $\text{depth}$-atom then by Lemma 3 it must be of the form $\text{depth}(A) \triangleleft N$, where $\triangleleft \in \{\triangleleft, \simeq\}$. Otherwise, $\phi$ must be a subformula introduced either by START or by UNFOLDING (up to a renaming of parameters). Hence $\phi$ must be in $\mathcal{F}$. If $\phi$ is not a base formula then $\lor$-DECOMPOSITION or $\land$-DECOMPOSITION applies.

Finally, if $A$ and $B$ are two parameters occurring in $\mathcal{T}(\alpha)$ then by irreducibility w.r.t. SEPARATION, either $A \simeq B$ (or $B \simeq A$) occurs in $\mathcal{T}(\alpha)$ (in which case $A$ or $B$ is solved) or $A \not\simeq B \in \mathcal{T}(\alpha)$.

Main proof

The first point follows from Lemma 6.

By Lemma 8 we only have to prove that $\mathcal{T}(\alpha)$ contains no $\text{depth}$-atoms and no defined atoms.

Assume that $\mathcal{T}(\alpha)$ contains an occurrence of $N$. Then since no other rule applies, $N$-EXPLOSION must apply, which is impossible. Thus $N$ does not occur in $\mathcal{T}(\alpha)$. This implies that $\mathcal{T}(\alpha)$ contains no $\text{depth}$-atoms. But then by Lemma 3 this implies that all non solved parameters occurring in $\mathcal{T}(\alpha)$ are instantiated.

Assume that $\mathcal{T}(\alpha)$ contains a defined symbol $d$. By irreducibility w.r.t. $\lor$-DECOMPOSITION and $\land$-DECOMPOSITION, this defined symbol must occur in a formula $d_A \in \mathcal{T}(\alpha)$. Since $A$ is instantiated then UNFOLDING applies, which is impossible.
9 Proof of Theorem 3

We define the following measures on formulæ:

**Definition 11.** Let \( a \) be the maximal arity of the symbols in \( \Sigma \). We denote by weight a function mapping every term, atom or literal to a natural number, defined as follows:

1. \( \text{weight}(A) = 1 \) if \( A \) is a parameter.
2. \( \text{weight}(f(t_1, \ldots, t_n)) \overset{df}{=} 1 + \sum_{i=1}^{n} \text{weight}(t_i) \) if \( f \neq \text{depth}, \text{succ} \).
3. \( \text{weight}(\text{depth}(t)) \overset{df}{=} \text{weight}(t) \).
4. \( \text{weight}(\text{succ}(t)) \overset{df}{=} 3 + a + \text{weight}(t) \).
5. \( \text{weight}(t \simeq s) = \text{weight}(t \prec s) = \text{weight}(t) + \text{weight}(s) + 1 \).
6. \( \text{weight}(\neg \phi) \overset{df}{=} 1 + \text{weight}(\phi) \).
7. \( \text{weight}(t \preceq s) = \text{weight}(t) + \text{weight}(s) + 2 \)
8. \( \text{weight}(d_A) = 1 + \max_{f \in \Sigma} \text{weight}(\psi_f) \), where \( \psi_f \) is obtained from \( d_f(B) \downarrow R \) by replacing every occurrence of \( f(B) \) by \( A \). \( B \) denotes a vector of parameters of the same sort as the domain of \( f \) (the value of weight does not depend on the names of the parameter, thus they can be chosen arbitrarily).

**Definition 12.**

\( \text{mes}(S) \overset{df}{=} (\{ \text{weight}(\phi) \mid \phi \in S' \}, \text{separable}(S), \text{diseq}(S), \text{unsolved}(S)) \)

where:

- \( S' \) denotes the set of formulæ in \( S \) that are not of the form \( A \simeq B \) or \( A \not\simeq B \), with \( A, B \in \mathcal{P} \).
- \( \text{separable}(S) \) denotes the number of pairs of parameters \((A, B)\) occurring in \( S \) such that neither \( A \simeq B \) nor \( A \not\simeq B \) is contained in \( S \).
- \( \text{diseq}(S) \) denotes the number of formulæ in \( S \) on which \( \not\simeq \)-Decomposition applies.
- \( \text{unsolved}(S) \) is the number of unsolved parameters in \( S \).

The measure \( \text{mes} \) is ordered by the lexicographic and multiset extensions of the usual ordering on natural numbers.

The next lemma shows that all the expansion rules, except \( N \)-Explosion, strictly decrease \( \text{mes} \) (possibly after some applications of the decomposition rules):

**Lemma 9.** Let \( T \) be a proof tree. If \( \alpha \) is a node obtained from a node \( \beta \) by applying an expansion rule distinct from \( N \)-Explosion, then there exists a node \( \alpha' \) such that \( \alpha \succeq_\tau \alpha' \) and \( \text{mes}(T(\alpha')) < \text{mes}(T(\beta)) \).

**Proof.** We distinguish several cases.

- Decomposition Rules. The rules \( \lor \)-Decomposition, \( \land \)-Decomposition, Closure, \( N \)-Closure and \( \simeq \)-Closure remove (at least) one logical symbol from \( S \), thus weight decreases strictly.
– Unfolding Rule. The rule replaces a formula \( d_A \) by a formula \( \psi \) obtained from \( d_f(B_1,\ldots,B_n) \) by replacing \( f(B_1,\ldots,B_n) \) by \( A \). By definition of weight, we have \( \text{weight}(d_A) > \text{weight}(\psi) \), thus \( \text{mes} \) decreases strictly.

– Equality Rules.

  - \( \sim \)-DECOMPOSITION. The rule temporality increases weight, since a (complex) formula \( \psi = \Delta(f(A_1,\ldots,A_n) \sim g(B_1,\ldots,B_m)) \) is added in \( S \). However, due to the control, the decomposition rules must be immediately applied on this formula. By definition, \( \Delta(f(A_1,\ldots,A_n) \sim g(B_1,\ldots,B_m)) \) only contains the symbols \( \lor, \land, \sim \) and parameters in \( A_1,\ldots,A_n,B_1,\ldots,B_m \), thus it must be reduced by decomposition into equations between parameters. Thus weight cannot increase. Furthermore, since an equation \( A \sim g(B_1,\ldots,B_m) \) is added, weight must decrease.

  - \( \neq \)-DECOMPOSITION. The rule temporality increases weight, since a (complex) formula \( \psi \) is added in \( S \). However, due to the control, the decomposition rules must be immediately applied on this formula. By definition, \( \Delta(f(A_1,\ldots,A_n) \sim g(B_1,\ldots,B_m)) \) only contains the symbols \( \lor, \land, \sim \) and parameters in \( A_1,\ldots,A_n,B_1,\ldots,B_m \). Thus NNF(\( \neg \psi \)), being the nnf of \( \neg \Delta(f(A_1,\ldots,A_n) \sim g(B_1,\ldots,B_m)) \), must be reduced by decomposition into disequations between parameters. Thus weight cannot increase. Obviously, separable does not increase either and diseq decreases, by definition.

  - SEPARATION. It is clear that the rule does not increase weight (since only equations or disequations between parameters are added) and decreases separable.

  - REPLACEMENT. The rule does not increase weight, separable and diseq and decreases unsolved.

– Depth Rules.

  - STRICTNESS: A formula \( \text{depth}(A) \leq N \) is replaced by \( \text{depth}(A) \sim N \lor \text{depth}(A) \prec N \). After decomposition, this last formula is reduced to either \( \text{depth}(A) \sim N \) or \( \text{depth}(A) \prec N \). We have \( \text{weight}(\text{depth}(A) \sim N) = \text{weight}(\text{depth}(A) \prec N) = 3 \) and \( \text{weight}(\text{depth}(A) \leq N) = 4 \). Thus weight decreases.

  - \( \prec \)-SEPARATION: Since the rule only adds a disequation between parameters, weight does not increase. Moreover, separable decreases, due to the control.

  - \( \prec \)-DECOMPOSITION: A formula \( \text{depth}(A) \prec \text{succ}(N) \) is replaced by \( \text{depth}(A) \leq N \). We have \( \text{weight}(\text{depth}(A) \prec \text{succ}(N)) = 6 + a \) and \( \text{weight}(\text{depth}(A) \leq N) = 5 \). Thus weight decreases.

– EXPLOSION. After decomposition, a formula of the form \( \text{depth}(B) \sim \text{succ}(t) \) is replaced by formulae of the form \( B \sim t_i \) or \( \text{depth}(A) \sim t \) or \( \text{depth}(A) \prec t \).

  - We have \( \text{weight}(\text{depth}(B) \sim \text{succ}(t)) = 4 + a + \text{weight}(t) \) and \( \text{weight}(B \sim t_i) = 2 + \text{weight}(t_i) \leq 3 + a, \text{weight}(\text{depth}(A) \sim t) = 2 + \text{weight}(t), \text{weight}(\text{depth}(A) \leq t) = 3 + \text{weight}(t) \). Thus weight decreases.

A layer formula is a set of formulae that is irreducible w.r.t. all expansion rules, except N-EXPLOSION.
We now prove that $\sqsubseteq$ is a well quasi-order for layer formulæ. We need to introduce some additional definitions. A sequence of sets of formulæ $(\Phi_i)_{i \in [0,n]}$ (with $n \in \mathbb{N} \cup \{\infty\}$) is $\sqsubseteq$-bad iff there are no indices $i, j \in [0,n]$ such that $i < j$ and $\Phi_j \sqsubseteq \Phi_i$. A layer formula $\Phi$ is built on a set of base formulæ $\Gamma$ iff all the non-equational formulæ in $\Phi$ are of the form $\phi[A/x]$, where $\phi \in \Gamma \cup \{\text{depth}(x) \prec N, \text{depth}(x) \simeq N\}$ ($x$ is a variable and $A$ a parameter).

**Proposition 7.** Let $T$ be a proof tree for a formula $\phi$. There exists a finite set of base formulæ $\Gamma$ such that for every layer $\alpha$, $\text{NonEq}(T(\alpha))$ is built on $\Gamma$.

**Proof.** Let $\alpha$ be a layer in $T$. By Lemma 8, all the formulæ containing depth must be of the form $\text{depth}(A) \prec N$ where $\prec \in \{\prec, \simeq\}$. By Lemma 8, the remaining formulæ must be base formulæ. The only rules that can add new base formulæ into the proof tree (up to a renaming of parameters) are START and UNFOLDING. The former only adds base formulæ occurring in $\phi$. The formulæ introduced by the latter rule are of obtained from formulæ occurring in $\mathcal{R}$ by instantiating variables by constant symbols and replacing a term $f(A)$ by a parameter. By definition there are only finitely many such formulæ (up to a renaming of parameters).

**Lemma 10.** Let $(\Phi_i)_{i \in \mathbb{N}}$ be an infinite sequence of layer formulæ built on a given finite set of base formulæ $\Gamma$. The sequence $(\text{NonEq}(\Phi_i))_{i \in \mathbb{N}}$ is $\sqsubseteq$-good.

**Proof.** Let $\Psi_i = \text{NonEq}(\Phi_i)$. By Lemma 8, $\Psi_i$ contains only base formulæ, formulæ of the form $d_A$ or $\text{depth}(A) \prec N$ and disequations between parameters.

For every parameter $A$, we denote by $\Psi_i|_A$ the set of base formulæ $\psi \in \Gamma \cup \{\text{depth}(x) \prec N, \text{depth}(x) \simeq N\}$ containing a variable $x$ and such that $\psi[A/x] \in \Psi_i$. We write $A \sim_{\psi_i} B$ iff $\Psi_i|_A = \Psi_i|_B$. The relation $\sim_{\psi_i}$ is obviously an equivalence relation. For every $\Lambda \subseteq \Gamma \cup \{\text{depth}(x) \prec N, \text{depth}(x) \simeq N\}$, we denote by $P(\Lambda, \Psi_i)$ the set of parameters $A$ such that $\Psi_i|_A = \Lambda$.

For any sequence $\Psi = (\Psi_i)_{i \in I}$ of sets of formulæ, we denote by $Q(\Psi)$ the set $\{\Psi_i|_A | A \in P, i \in I\}$. Note that $Q(\Psi) \subseteq 2^{\Gamma \cup \{\text{depth}(x) \prec N, \text{depth}(x) \simeq N\}}$.

Assume that $\Psi = (\Psi_i)_{i \in \mathbb{N}}$ is $\sqsubseteq$-bad. Without loss of generality, we assume that $Q(\Psi)$ is minimal, i.e. if $\Psi'$ is a sequence of base formulæ built on $\Gamma$ such that $Q(\Psi') \subset Q(\Psi)$, then $\Psi'$ is $\sqsubseteq$-good.

If $Q(\Psi) = \emptyset$ then necessarily, the $\Psi_i$’s ($i \in I$) contain only sets of formulæ in $\Gamma$ and disequation between parameters. Since $\Gamma$ is finite, the number of sets of formulæ in $\Gamma$ is also finite. Since $\Psi_i$ is infinite, there exists some subsequence $\Psi' = \Psi'_{i_n}$ of $\Psi$ such that for every $i, j \in \mathbb{N}$, $\Psi_i'$ and $\Psi_j'$ only differ by disequations. Let $i \in I$ be the index in $\mathbb{N}$ such that the number of parameters in $\Psi_i'$ is minimal.

We show that $\Psi_{i+1}' \sqsupseteq \Psi_i'$. By definition the number of parameters occurring in $\Psi_i'_{i+1}$ is greater or equal to that of $\Psi_i'$. Thus there exists an injective function $\rho$ from the set of parameters in $\Psi_i'$ onto the set of parameters in $\Psi_i'_{i+1}$. Then, if $A \not\sim B$ is a formula in $\Psi_i'$, there must exist two distinct parameters, $A', B'$ such that $\rho(A) = A'$ and $\rho(B) = B'$, and $A', B'$ occurs in $\Psi_i'_{i+1}$. Furthermore, by Lemma 8, $A' \not\sim B'$ occurs in $\Psi_i'_{i+1}$. Thus $\rho(\Psi_i') \subseteq \Psi_i'_{i+1}$, whence $\Psi_i'_{i+1} \sqsupseteq \Psi_i'$. This means that $\Psi'$ (hence also $\Psi$) is $\sqsubseteq$-good, which contradicts our hypothesis.
Thus we must have $Q(\Psi) \neq \emptyset$. Let $A$ be a parameter occurring in $\Psi_0$ and let $A \simeq \Psi_0 | A$. Let $k \in [0, |P(A, \Psi_0)|]$. Consider the set of indices $\{i_j | j \in \mathbb{N}\}$ such that $|P(A, \Psi_{i_j})| = k$. Let $\Psi' = \psi_{i \in I'}$ be the sequence such that $\Psi'$ is obtained from $\Psi_{i_j}$ by removing each formula $\phi$ containing a parameter $A \in P(A, \Psi_{i_j})$. By definition of $\Psi'$, we have $Q(\Psi') \subset Q(\Psi)$ (since $Q(\Psi')$ cannot contain $A$).

Assume that $\Psi'$ is infinite. By minimality of $\Psi$, $\Psi'$ must be $\exists$-good. Consequently, there exist two indices $j < j'$ such that $\Psi'_j \supseteq \Psi'_{j'}$, i.e. there exists a renaming $\rho$ such that $\rho(\Psi'_j) \subseteq \Psi'_{j'}$. By definition of $\Psi_{i_j}$, we have $|P(A, \Psi_{i_j})| = |P(A, \Psi_{i_{j'}})| = k$. Let $\rho'$ be any bijective renaming from $P(A, \Psi_{i_j})$ to $P(A, \Psi_{i_{j'}})$. By definition of $\Psi'$, $\rho'$ and $\rho$ must have disjoint domains. Let $\rho'' = \rho \cup \rho'$. It is easy to check that we have $\rho''(\Psi_{i_j}) \subseteq \Psi_{i_{j'}}$, hence $\Psi_{i_{j'}} \supseteq \Psi_{i_j}$, which is impossible. Thus $\Psi'$ is finite. Since this is true for every $k \leq |P(A, \Psi_0)|$, this implies that there exists some index $j$ such that for every $i \geq j$, we have $|P(A, \Psi_i)| \geq |P(A, \Psi_0)|$. But then, since the same reasoning holds for every $A$, there must exist some $j \in I$ such that for every $i \geq j$ and for every $A \subseteq I \cup \{\text{depth}(x) \leq N, \text{depth}(x) \leq N\}$: $|P(A, \Psi_i)| \geq |P(A, \Psi_0)|$ (it suffice to take the maximal value of all the $j$'s corresponding to each $A$, which is possible since the number of distinct set $A$ is finite).

We have in particular: $\forall A \subseteq I \cup \{\text{depth}(x) \leq N, \text{depth}(x) \leq N\}, |P(A, \Psi_i)| \geq |P(A, \Psi_0)|$.

Thus there exists an injective renaming $\rho_A$ from $P(A, \Psi_0)$ to $P(A, \Psi_i)$. By definition, if $A \neq A'$, then $\rho_A$ and $\rho_{A'}$ have disjoint domains. Let $\rho = \bigcup_{A \subseteq I \cup \{\text{depth}(x) \leq N, \text{depth}(x) \leq N\}} \rho_A$. It is clear that $\rho(\Psi_0) \subseteq \Psi_i$. Thus $\Psi$ is $\exists$-good.

**Main proof**

Assume that there exists an infinite proof tree $T$. $T$ must have at least one infinite branch $(\alpha_i)_{i \in \mathbb{N}}$. If there exist $i, j \in \mathbb{N}$ such that $i < j$ and $T(\alpha_j) \supseteq T(\alpha_i)$ then LOOP applies on $j$, which is impossible. Thus, by Lemma 10, the subsequence of layer formulæ in $T(\alpha_i)_{i \in \mathbb{N}}$ is finite, and there exists $i \in \mathbb{N}$ such that for every $j \geq i$, $\alpha_j$ is not a layer formula. In this case, $\text{N-EXPLOSION}$ cannot be applied on $\alpha_j$, hence by Lemma 11 we have $\text{mes}(T(\alpha_{j+l})) < \text{mes}(T(\alpha_j))$, for some $l > 0$. Since $\text{mes}$ is well-founded, we get a contradiction.