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Bounding the order of a graph using its diameter and metric dimension
A study through tree decompositions and VC dimension

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Abstract
The metric dimension of a graph is the minimum size of a set of vertices such that each vertex is uniquely determined by the distances to the vertices of that set. Our aim is to upper-bound the order \( n \) of a graph in terms of its diameter \( d \) and metric dimension \( k \). In general, the bound \( n \leq d^k + k \) is known to hold. We prove a bound of the form \( n = \mathcal{O}(kd^2) \) for trees and outerplanar graphs (for trees we determine the best possible bound and the corresponding extremal examples). More generally, for graphs having a tree decomposition of width \( w \) and length \( \ell \), we obtain a bound of the form \( n = \mathcal{O}(kd^2(2\ell + 1)w + 1) \). This implies in particular that \( n = \mathcal{O}(kd^{O(1)}) \) for graphs of constant treewidth and \( n = \mathcal{O}(f(k)d^2) \) for chordal graphs, where \( f \) is a doubly-exponential function. Using the notion of distance-VC dimension (introduced in 2014 by Bousquet and Thomassé) as a tool, we prove the bounds \( n \leq (dk + 1)^{t-1} + 1 \) for \( K_t \)-minor-free graphs, and \( n \leq (dk + 1)^d(2^r+2) + 1 \) for graphs of rankwidth at most \( r \).

1 Introduction
A resolving set of a graph is a set of vertices that uniquely determines each vertex by means of the ordered set of distances to the vertices in the resolving set. The metric dimension of the graph is the smallest size of a resolving set. These concepts, introduced independently by Slater [29] (who called resolving sets locating sets) and by Harary and Melter [19], are widely studied since then, see for example the papers [2, 5, 12, 20, 21, 26]. More generally, they fit into the topic of identification or separation problems in discrete structures, such as separating systems, distinguishing sets and related concepts (for a few references, see [7, 8, 11, 22]). These concepts have many applications and connections to other areas. For example, the metric dimension can be applied to network discovery [4, 3], robot navigation [21], coin-weighing problems [26], T-joins [26], the Mastermind game [13], or chemistry [12].

The goal of this paper is to study the relation between the order, the diameter and the metric dimension of graphs, in particular for graphs belonging to specific graph classes.

Important concepts and definitions. All considered graphs are finite and simple. We will denote by \( N[v] \), the closed neighbourhood of vertex \( v \), and by \( N(v) \) its open neighbourhood \( N[v] \setminus \{v\} \). Let \( d_G(u, v) \), or simply \( d(u, v) \) if there is no ambiguity, denote the distance between two vertices \( u \) and \( v \) in graph \( G \). Similarly, for two sets \( X \) and \( Y \) of vertices of \( G \), \( d_G(X, Y) \) denotes the shortest distance between a vertex of \( X \) and a vertex of \( Y \).

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Definition 1. A set $R$ of vertices of a graph $G$ is a resolving set if for each pair $u, v$ of distinct vertices, there is a vertex $x$ of $R$ with $d(x, u) \neq d(x, v)$. The smallest size of a resolving set of $G$ is the metric dimension of $G$.

A graph is said to be {chordal} if it has no induced cycle of length at least 4. A graph is {planar} if it has an embedding in the plane that induces no edge-crossing. It is {outerplanar} if it is planar and has an embedding in the plane where each vertex lies on the outer face. A {minor} of a graph is a graph obtained by a succession of vertex- and edge-deletions and edge-contractions. We say that a graph $G$ is {H-minor-free} if $H$ is not a minor of $G$. By the Graph Minor Theorem [24], any minor-closed class of graphs (such as the classes of planar graphs, outerplanar graphs or graphs with treewidth at most $w$) is defined by a finite set of forbidden minors.

Previous work. One can easily observe that in a graph $G$ of diameter $d$ and with metric dimension $k$ and $n$ vertices, we have the bound $n \leq d^k + k$ [12, 21]. Indeed, given a resolving set $R$ of size $k$, every vertex outside of $R$ can be associated to a distinct vector of length $k$ and values ranging from 1 to $d$. This trivial bound, however, is only tight for $d \leq 3$ or $k = 1$ [20]. Nevertheless, the more precise (and tight) bound $n \leq ((2d/3) + 1)^k + k \sum_{i=1}^{[d/3]}(2i-1)^{k-1}$ is given in [21]. It is natural to ask for which kind of graphs a bound of this form is tight. We therefore wish to study the following problem.

Problem 1. Given a graph class $C$, determine the largest possible order of a graph in $C$ having metric dimension $k$ and diameter $d$.

This problem was considered by the third and fifth author, together with Mertzios, Naserasr and Valicov [17]. These authors studied interval graphs and permutation graphs, and proved bounds of the form $n = O(dk^2)$. These bounds were shown to be best possible (up to constant factors). In the case of unit interval graphs, bipartite permutation graphs and cographs, it was proved in the same paper that $n = O(dk)$.

Surprisingly, the above problem seems to have not been studied even for trees, despite the fact that the metric dimension of trees is well understood (see [12, 21, 29]). In this paper, we answer this question. We extend our result for trees in two ways. First, we give bounds involving the length and width of a tree decomposition of the graph. Second, we study graphs that have bounded {distance-VC dimension}. (These notions will be defined in the corresponding sections of the paper.)

As further recent work related to this paper, we remark that the metric dimension of $t$-trees has recently been investigated in [5], and the treelength of a graph has recently been used to design algorithms to compute the metric dimension [9]. Algorithms and complexity results regarding the computation of the metric dimension of graphs belonging to graph classes considered in the present paper, can be found in [14, 16, 18].

Our results and structure of the paper. In the first part of the paper, Section 2, we study trees and generalize our method using the tool of tree decompositions. We start in Section 2.1 by an exact bound of the form $n = (1 + o(1))d^2k$ for trees of order $n$, metric dimension $k$ and diameter $d$, and we characterize the trees reaching our bound. We then show in Section 2.2 that a graph with a tree decomposition of width $w$ and length $\ell$ satisfies $n = O(kd^2(2\ell + 1)^{3w+1})$. This implies the bound $n = O(k2^{\ell w}d^{3w+3})$ for graphs of treewidth at most $w$ and $n = O(kd^23^{\omega-2})$ for chordal graphs with maximum clique $\omega$.

The second part of the paper, Section 3, is devoted to the use of the distance-VC dimension. We first show (using the notion of test covers), how the VC dimension of the ball hypergraph of a graph can be used to derive a general bound on the order using the diameter and the metric dimension. We then bound the dual distance-VC dimension of $K_t$-minor-free graphs and graphs of rankwidth at most $r$, which implies the bounds $n \leq (dk + 1)^{t-1} + 1$ and $n \leq (dk + 1)^{t(3^2r + 2)} + 1$, respectively. In particular, this shows that for planar graphs, we have $n \leq (dk + 1)^2$; this partially answers an open question from [17]. We then use a completely different method in Section 3.4 to prove that $n = O(kd^2)$ for outerplanar graphs, which we show to be tight.

Finally, we conclude in Section 4 with some open questions.

2 Trees and graphs with specific tree decompositions

We first study Problem 1 for graphs admitting specific types of tree decompositions. We start with trees, which form the class of nontrivial graphs that is the simplest (with respect to tree decompositions).
2.1 Trees

We first give the constructions of some extremal trees. See Figure 1 for illustrations.

For $r \in \mathbb{N}$ let $L_r$ be the rooted tree obtained from a path $v_0, v_1, \ldots, v_r$ rooted at $v_0$ by attaching a path of length $r - i$ to vertex $v_i$ for $i = 1, 2, \ldots, r - 1$. Denote a path of length $r$ rooted at one of its end vertices by $P_r^*$. Let $k \in \mathbb{N}$ with $k \geq 2$.

For even $d \in \mathbb{N}$ we define the hairy spider $HS_{d,k}$ as the tree obtained from $k$ disjoint copies of $L_{d/2}$ and a path $P_{d/2}^*$ by identifying their roots to a vertex $v$. For odd $d \in \mathbb{N}$ with $d \geq 3$ and for $a \in \mathbb{N}$ with $0 \leq a \leq k$ we define $HS_{d,k,a}$ as the tree obtained from $k$ disjoint copies of $L_{(d-1)/2}$, two copies of $P_{(d-1)/2}^*$, and a path on two vertices, $u$ and $w$, by identifying the roots of a copies of $L_{(d-1)/2}$ and of one copy of $P_{(d-1)/2}^*$ with $u$, and the roots of the remaining $k - a$ copies of $L_{(d-1)/2}$ and the root of the other copy of $P_{(d-1)/2}^*$ with $w$.

![Figure 1: Extremal trees. Black vertices form optimal resolving sets.](image)

**Theorem 2.** Let $T$ be a tree of diameter $d$ and metric dimension $k$, where $k \geq 2$. Then

$$|V(T)| \leq \begin{cases} \frac{1}{2}(kd + 4)(d + 2) & \text{if } d \text{ is even}, \\ \frac{1}{2}(kd - k + 8)(d + 1) & \text{if } d \text{ is odd}. \end{cases}$$

Equality holds for even $d$ if and only if $T = HS_{d,k}$, and for odd $d$ if and only if $T = HS_{d,k,a}$ for some integer $a$ with $0 < a < k$.

**Proof.** Let $S = \{x_1, x_2, \ldots, x_k\}$ be a resolving set for $T$. Let $C$ be the set of central vertices of $T$, that is, the set of vertices of $T$ that minimize the maximum distance to all the other vertices of the tree. For $i = 1, 2, \ldots, k$, let $P_i$ be the shortest path from $C$ to $x_i$. Let $r = \max_{v \in V(T)} d_T(v, C)$, so if $d$ is even then $r = d/2$ and $r$ is the radius of $T$, and if $d$ is odd then $r = (d - 1)/2$ since for odd $d$ every vertex is within distance $(d - 1)/2$ of the nearest central vertex of $T$. Define the subtree $T_S$ of $T$ by

$$T_S = T[C] \cup \bigcup_{i=1}^{k} P_i. \quad (1)$$

For $v \in V(T_S)$ we define $T_v$ to be the largest subtree of $T$ containing $v$ and no other vertex of $T_S$. In other words, $T_v$ is the union of all branches of $T$ at $v$ not containing any edge of $T_S$. Possibly, $T_v = K_1$.

We first show that for every vertex $v$ of $T_S$,

$$T_v \text{ is a path with } v \text{ as an end-vertex.} \quad (2)$$

We first show that $v$ is an end-vertex (that is, a leaf) of $T_v$. Indeed, if $v$ had two neighbours in $T_v$, then they would have the same distance to every vertex in $S$, and so $S$ would not resolve them, a contradiction. The same argument shows that no vertex of $T_v$ has degree greater than two. This shows (2).

Hence $T$ is obtained from $T_S$ by appending a path on $|V(T_v)| - 1$ vertices to $v$ for all $v \in V(T_S)$. We now bound the length of this path by showing that

$$|V(T_v)| \leq r - d_T(v, C) + 1. \quad (3)$$

Let $v'$ be the end vertex of $T_v$ with $v' \neq v$. Then $d_T(v', v) = |V(T_v)| - 1$. Hence

$$r \geq d_T(v', C) = d_T(v', v) + d_T(v, C) = |V(T_v)| - 1 + d_T(v, C),$$

$$3|V(T_v)| - 1 \leq 2r = 2(d - 1)/2.$$
and (3) follows.

From (1) we obtain

\[ n = \sum_{v \in V(T)} |V(T_v)| \]

\[ \leq \sum_{v \in C} |V(T_v)| + \sum_{i=1}^{k} \sum_{w \in V(P_i) - C} |V(T_w)|. \]

(4)

By (3) we have \( |V(T_v)| \leq r + 1 \) for all \( v \in C \). The vertices of \( P_i \) are at distance \( 0, 1, \ldots, \ell_i \) from \( C \) in \( T \), where \( \ell_i \) is the length of \( P_i \). Hence, by (3) and \( \ell_i \leq r \) we get

\[ \sum_{w \in V(P_i) - C} |V(T_w)| \leq \sum_{j=1}^{\ell_i} (r - j + 1) \leq \sum_{j=1}^{r} (r - j + 1) = \frac{1}{2} r(r + 1). \]

(5)

In total we obtain

\[ n \leq |C|(r + 1) + \frac{k}{2} r(r + 1). \]

(6)

If \( d \) is even, then \( r = \frac{d}{2} \) and \( C \) contains only one vertex. Hence

\[ n \leq (r + 1) + \frac{k}{2} r(r + 1) = \frac{kr + 2}{2} r(r + 1) = \frac{(kd + 4)(d + 2)}{8}, \]

and the desired bound follows in this case. If \( d \) is odd, then \( r = \frac{d - 1}{2} \) and \( C \) contains exactly two vertices. Hence

\[ n \leq 2(r + 1) + \frac{k}{2} r(r + 1) = \frac{kr + 4}{2} r(r + 1) = \frac{(kd - k)(d + 1)}{8}, \]

and the desired bound follows also in this case.

Now assume that \( T \) is a tree of diameter \( d \) and metric dimension \( k \) attaining the bound. Then equality holds also in (6), in (4)–(5). So the paths \( P_i \) share no vertices other than central vertices, and each path has length \( r \). Moreover, equality in (3) implies that for the vertices \( v \) of \( P_i \), the trees \( T_v \) have order \( 2, 3, \ldots, r - 1 \), respectively, for each \( i \). Equality in (6) implies also that for each central vertex \( v \) the tree \( T_v \) has \( r + 1 \) vertices. In total it follows that \( T = HS_{d,k} \) if \( d \) is even, and, if \( d \) is odd, that \( T = HS_{d,k,a} \) for some \( a \in \{0, 1, \ldots, k\} \). It is easy to see that the trees \( HS_{d,k,0} \) and \( HS_{d,k,k} \) have metric dimension \( k + 1 \), so we conclude that \( T = HS_{d,k,a} \) for some \( a \in \{1, 2, \ldots, k - 1\} \).

2.2 Using tree decompositions

We now generalize our result for trees to graphs with tree decompositions of given width and length. These results also generalize results of [17] for interval graphs and permutation graphs (which have treewidth at most 1 and 2, respectively).\[ \]

We first recall the definition of tree decomposition introduced by Robertson and Seymour.\[ \]

We shall copy the definition given by Dourisboure and Gavoille which is slightly lighter in terms of indices.

Definition 3 (Tree decomposition [15]). Let \( G \) be a graph. A tree decomposition of \( G \) is a tree \( T \) whose vertices, called bags, are subsets of \( V(G) \) such that the following properties are satisfied.

(P1) \( \bigcup_{X \in V(T)} X = V(G) \),

(P2) for every edge \( e \) of \( G \), there exists \( X \) in \( V(T) \) such that both ends of \( e \) are in \( X \), and

(P3) for \( X, Y \) and \( Z \) in \( V(T) \), if \( Y \) lies on the path in \( T \) from \( X \) to \( Z \), then \( X \cap Z \subseteq Y \).

As mentioned in [13], property (P3) of Definition 3 implies that, for any vertex \( x \) in \( V(G) \), the set of bags containing \( x \) induces a subtree of \( T \). The classic width parameter of a tree decomposition is defined as \(\max\{|X| - 1 : X \in V(T)\} \). For any bag \( X \) in \( V(T) \), the diameter of \( X \) is the maximum distance \( d_C(x, y) \) over every pair of vertices \( x \) and \( y \) in \( X \). (Note that here the distance is taken in \( G \), and not in
The length of a tree decomposition is the largest diameter of a bag over every bag \( X \) in \( V(T) \) [15]. The treewidth (respectively treelength) of a graph \( G \) is the minimum width (resp. length) among all tree decompositions of \( G \).

A tree decomposition is reduced if no bag is a subset of another bag. One may easily check that any tree decomposition can be turned into a reduced tree decomposition by removing the bags which are not maximal with respect to inclusion and without altering the width and the length of the decomposition.

A cutset of a graph \( G \) is a set of vertices in \( G \) whose removal increases the number of components. We shall prove the following theorem.

**Theorem 4.** Let \( G \) be a graph of order \( n \) and diameter \( d \). Let \( T \) be a reduced tree decomposition of \( G \) of length \( \ell \) and width \( w \). If there is a resolving set of size \( k \) in \( G \), then

\[
 n = \mathcal{O}(kd^2(2\ell + 1)^{3w+1}).
\]

**Proof.** Let \( G \) be a graph of diameter \( d \) with a resolving set \( S \) of size \( k \). Let \( T \) be a tree decomposition of \( G \) with length \( \ell \) and width \( w \). The following claim is easily derived from the definition of a tree decomposition.

**Claim 4.A.** Every bag \( X \) which is not a leaf in \( T \) is a cutset for \( G \).

For an easier reading of the following proofs, let us pick an arbitrary root \( X_r \) for \( T \). For any bag \( X \) in \( V(T) \), we define the subtree \( T(X) \) as the subtree of \( T \) induced by \( X \) and all its descendants.

**Claim 4.B.** Let \( X \) be a bag in \( V(T) \) such that for every bag \( Y \) in \( T(X) \), the set \( Y \cap S \) is included in \( X \). Let \( A \) be the set defined as

\[
 A = \bigcup_{Y \in V(T(X))} Y.
\]

Then,

\[
 |A| \leq (d + 1)(2\ell + 1)^w.
\]

**Proof of claim.** For any vertex \( x \) in \( A \), every path from \( x \) to an element of \( S \) has to go through \( X \) (this is implied by Claim 4.A). Therefore, the distances from \( x \) to the vertices of \( S \) are completely determined by the distances from \( x \) to the vertices of \( X \). Since \( S \) is a resolving set, the vertices in \( A \) must all have a different distance vector to \( X \). By taking a specific vertex of \( X \) as a pin point, the distance from \( x \) to this pin is at most \( d \), and all other distances can only differ from this distance by at most \( \ell \). There are at most \( w \) other vertices in \( X \). Thus, the number of possible vectors is smaller than or equal to

\[(d + 1)(2\ell + 1)^w,
\]

concluding the proof of Claim 4.B (□).

For each vertex \( v \), we call the bag in \( T \) that contains \( v \) and is at minimum distance from the root \( X_r \) of \( T \) the oldest bag in \( T \) containing \( v \). We note that such a bag is uniquely defined because of the subtre structure and the properties of a tree decomposition \( T \). For every vertex \( s \) in the resolving set \( S \), we denote the oldest bag in \( T \) containing \( s \) by \( X_s \), and we call it the ancestor of \( s \) in \( T \).

Let \( T_S \) be the subtree of \( T \) obtained by only considering the ancestors of all \( s \) in \( S \) and the paths from them to the root \( X_r \). Any leaf of \( T_S \) is the ancestor of some \( s \) in \( S \). As a direct consequence, \( T_S \) has at most \( k \) leaves. A thread in a graph \( G \) is a path all whose inner-vertices have degree 2 in \( G \).

**Claim 4.C.** Let \( P \) be a thread of length \( L \) in \( T_S \). Let \( X_0 \) and \( X_L \) be the bags at both ends of \( P \). Suppose that for every inner vertex \( X \) of \( P \), the set \( X \cap S \) is included in \( X_0 \cup X_L \). Then,

\[
 L \leq (\ell + 1)(2\ell + 1)^{2w+1}[d_G(X_0,X_L) + 1].
\]

**Proof of claim.** Let \( \lambda \) be the distance in \( G \) between the sets \( X_0 \) and \( X_L \). Let \( x_0x_1 \cdots x_\lambda \) be a shortest path in \( G \) between \( X_0 \) and \( X_L \) (\( x_0 \) is in \( X_0 \) and \( x_\lambda \) is in \( X_L \)). Note that every edge along the path \( x_0x_1 \cdots x_\lambda \) must be in one of the bags along \( P \).

If \( x \) is in \( X_i \) and \( X_{i+t} \) for some \( i, j \) along the thread, then it is in all the bags in between \( X_i \) and \( X_{i+t} \) (by the connectivity condition). Notice that every path between a vertex in \( \bigcup_{z=i}^{z=i+t} X_z \) and a vertex
in $S$ has to go through $X_i$ or $X_{i+t}$. This means that all vertices in $\bigcup_{z=1}^{\ell+t} X_z$ must have different distance vectors to $X_i \cup X_{i+t}$.

These distances are bounded above by $2\ell$ since $x$ is in all the bags along this thread. The distance to $x$ is at most $\ell$. There are at most $2w$ vertices different from $x$ in $X_i \cup X_{i+t}$. We may conclude that,

$$\left| \bigcup_{z=1}^{\ell+t} X_z \right| \leq (\ell + 1)(2\ell + 1)^{2w}.$$  

Since the tree decomposition is reduced, every bag $X_i$ must contain a vertex which is not in any $X_j$ for $j$ between 0 and $i - 1$. We derive that the number of bags is smaller than the number of vertices

$$k + 1 \leq (\ell + 1)(2\ell + 1)^{2w}.$$  

(7)

In other words, vertices cannot be in too many bags along the thread.

Now, we shall prove that $L$ cannot be too big with respect to $\lambda$. For this, let us denote by $i_q$ the largest index of a bag containing $x_q$ for $q$ between 0 and $\lambda$,

$$i_q = \max\{i : x_q \in X_i\}.$$  

With the help of (7), we may say that,

$$i_0 \leq (\ell + 1)(2\ell + 1)^{2w}.$$  

Since $x_q x_{q+1}$ is an edge, vertex $x_{q+1}$ has to appear in a bag before index $i_q$. By using (7) successively, we obtain

$$i_q \leq (q + 1)(\ell + 1)(2\ell + 1)^{2w}.$$  

Substituting $q$ with $\lambda$ in the previous equation and noting that $i_\lambda = L$, we obtain that

$$L \leq (\lambda + 1)(\ell + 1)(2\ell + 1)^{2w}.$$  

Since $\lambda = \text{dist}_G(X_0, X_\ell)$, this concludes the proof of Claim 4.C.

Let us now focus on $T_S$. Recall that its leaves are a subset of the ancestors of vertices of $S$. Let $A$ be the set of ancestors and $I$ be the set of inner vertices of degree at least 3 in $T_S$ (note that $I$ has cardinality at most $k - 1$ since $T_S$ has at most $k$ leaves). We decompose $T_S$ into (not necessarily disjoint) threads as follows. From any vertex $X$ in $A \cup I$, consider the thread to the closest vertex that is either in $I$ or in $A$ on the unique path from $X$ to the root $X_r$. Each of these threads satisfies the conditions of Claim 4.C and thus has size bounded above by $(d + 1)(\ell + 1)(2\ell + 1)^{2w}$. Moreover we have at most $|A| + |I|$ such threads, and $|A| + |I|$ is at most $2k - 1$. We can then conclude that

$$|V(T_S)| \leq (2k - 1)(d + 1)(\ell + 1)(2\ell + 1)^{2w}.$$  

For each bag $X$ in $T_S$, we may have removed from $T$ a part of the subtree $T(X)$ verifying the hypothesis of Claim 4.C. In the end, the union of all the bags cannot be too large. We then obtain the following upper bound on the order of $G$.

$$|V(G)| \leq |V(T_S)| (d + 1)(2\ell + 1)^{2w}$$  

$$\leq (2k - 1)(d + 1)(\ell + 1)(2\ell + 1)^{2w}(d + 1)(2\ell + 1)^{2w}$$  

$$= O(kd^2(2\ell + 1)^{3w+1}).$$  

This concludes the proof of Theorem 4. $\square$

We immediately obtain some corollaries of Theorem 4. The first one is due to the fact that the treelength is trivially upper-bounded by the diameter; for graphs with constant treewidth, it implies the upper bound $n = O(kd^{O(1)})$.

**Corollary 5.** Let $G$ be a graph of treewidth at most $w$, diameter $d$ and a resolving set of size $k$. Then

$$n = O(kd^{3w + 3}).$$  

In particular, if $G$ is $K_4$-minor-free, then

$$n = O(kd^3).$$
We have another corollary for chordal graphs, based on the following observation and on the fact that chordal graphs have treelength 1 [15].

**Observation 6.** If $G$ is a chordal graph of treewidth $w$ and with a resolving set of size $k$, then $w \leq 3^k$.

**Proof.** Let $v$ be a vertex of $G$, and let $x \in N[v]$. For any vertex $s$ in a resolving set of size $k$ of $G$, there are at most three possible distance values for the distance $d(x, s)$, since any two vertices in $N[v]$ are at distance at most 2. Thus, there can be at most $3^k$ vertices in $N[v]$, which proves that $\Delta(G) \leq 3^k$. Now, a chordal graph of treewidth $w$ must have a clique of size $w + 1$ (indeed, it is well-known that in any optimal treedecomposition of a chordal graph, each bag forms a clique), thus we have $w \leq \Delta(G)$. \qed

**Corollary 7.** If $G$ is a chordal graph with diameter $d$, treewidth $w$ and a resolving set of size $k$, then

$$n = \mathcal{O}(kd^23^{3w+1}).$$

Moreover,

$$n = \mathcal{O}(d^22^{o(\epsilon(n))}).$$

We do not know whether the bounds presented in this section are tight. We note that for interval graphs, which are chordal, it is known that a bound of the form $n = \mathcal{O}(dk^2)$ holds, and there are interval graphs for which $n = \Theta(dk^2)$ [17]. By Theorem [2] there are trees that satisfy $n = \Theta(d^k k)$.

### 3 Graphs of bounded distance-VC dimension

Let $\mathcal{H} = (V, E)$ be a hypergraph. A test cover of $\mathcal{H}$ is a set of edges $C$ such that each vertex is covered by some edge of $C$ and for any pair $x, y$ of vertices there is an edge of $C$ containing exactly one vertex among $\{x, y\}$. We denote by $TC(\mathcal{H})$ the minimum size of a test cover of $\mathcal{H}$. A hypergraph is twin-free if for any two distinct vertices, there is at least one hyperedge containing exactly one of them. One can easily check that a hypergraph admits a test cover if and only if it is twin-free. The projection of $\mathcal{H}$ on a set $X$ of vertices, is defined as $\mathcal{H}_{|X} := \{e \cap X : e \in E\}$. A set of vertices $X$ is shattered in $\mathcal{H}$ if $|\mathcal{H}_{|X}| = 2^{|X|}$. The maximum size of a shattered set in $\mathcal{H}$ is the VC dimension of $\mathcal{H}$, denoted by $vc(\mathcal{H})$.

A 2-shattered set in a hypergraph $\mathcal{H}$ is a set $X$ such that for all $X' \subset X$ of size 2, there is a hyperedge $e$ such that $e \cap X = X'$. The 2-VC dimension of $\mathcal{H}$ is the maximum size of a 2-shattered set in $\mathcal{H}$. Clearly, the 2-VC dimension of $\mathcal{H}$ is at least as large as its VC dimension.

The dual hypergraph of a hypergraph $\mathcal{H}$ is denoted $\mathcal{H}^*$: it is the hypergraph whose vertices are the hyperedges of $\mathcal{H}$, and vice-versa, and where the incidence relation is the same as in $\mathcal{H}$. The dual VC dimension of $\mathcal{H}$ is the VC dimension of the dual and is denoted by $vc^*(\mathcal{H})$. We always have the following inequalities [1].

$$\log(vc^*(\mathcal{H})) \leq vc(\mathcal{H}) \leq 2^{vc^*(\mathcal{H})}.$$

The following standard lemma is crucial in the study of the VC dimension.

**Lemma 8** (Sauer-Shelah Lemma [25 [27]). If $\mathcal{H} = (V, E)$ is a hypergraph and $X$, a subset of vertices, then $|\mathcal{H}_{|X}| \leq |X|^{vc(\mathcal{H})} + 1$.

#### 3.1 A dichotomy theorem for test covers and VC dimension

If $G$ is a graph, one can define the closed neighbourhood hypergraph $\mathcal{H}_1(G)$ of $G$ that has vertex set $V(G)$ and edge set the set of closed neighbourhoods of vertices of $G$. An identifying code of $G$ is a test cover of $\mathcal{H}_1(G)$, and the VC dimension of $G$ is often defined as the VC dimension of $\mathcal{H}_1(G)$. A graph $G$ is twin-free if $\mathcal{H}_1(G)$ is twin-free. In [2], the VC dimension and identifying codes are related by the following dichotomy result.

**Theorem 9** ([1]). For every hereditary class of graphs $\mathcal{C}$, either

1. for every $k \in \mathbb{N}$, there exists a graph $G_k \in \mathcal{C}$ with more than $2^k - 1$ vertices and an identifying code of size $2k$, or
2. there exists $\varepsilon > 0$ such that no twin-free graph $G \in \mathcal{C}$ with $n$ vertices has an identifying code of size smaller than $n^\varepsilon$. 

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We show next that Theorem 8 can be extended to test covers.

**Proposition 10.** If $\mathcal{H}$ is a twin-free hypergraph, then

$$|V| \leq (TC(\mathcal{H}))^{vc^*(\mathcal{H})} + 1.$$ 

**Proof.** Let $\mathcal{H}^*$ be the dual hypergraph of $\mathcal{H}$. Let $C$ be a test cover of $\mathcal{H}$ of size $TC(\mathcal{H})$. We have $|\mathcal{H}^*| = |V|$ since otherwise two vertices of $V$ would belong to the same set of edges of $C$. Then by Lemma 8, we have $|\mathcal{H}^*| \leq |C|^{vc(\mathcal{H}^*)} = TC(\mathcal{H})^{vc^*(\mathcal{H})} + 1$. Therefore, $|V| \leq TC(\mathcal{H})^{vc^*(\mathcal{H})} + 1$. 

We can also prove the converse.

**Proposition 11.** Let $C$ be a class of hypergraphs that is stable by taking projections. If $C$ has unbounded dual VC dimension, then for any integer $k$, there exists a hypergraph $\mathcal{H}$ in $C$ with $2^k - 1$ vertices and a test cover of size $k$.

**Proof.** Notice first that for any $k$, $\mathcal{C}$ contains a hypergraph with dual VC dimension exactly $k$. Indeed, assume that $\mathcal{H}$ is the hypergraph of $\mathcal{C}$ with the smallest dual VC dimension $k'$ larger or equal to $k$. Then let $\mathcal{A}$ be a shattered set of hyperedges of size $k'$. Let $\mathcal{X}$ be a set of vertices that shatters $\mathcal{A}$ (that is, for each subset of hyperedges of $\mathcal{A}$ there is a unique vertex of $X$ belonging to this subset). Remove one vertex $x$ from $\mathcal{X}$ and let $\mathcal{H'} = \mathcal{H} \setminus x$. Then $\mathcal{H'}$ belongs to $\mathcal{C}$ and $vc^*(\mathcal{H'}) = k' - 1$. Thus, by our assumptions, $k' = k$.

Now consider a hypergraph of $\mathcal{C}$ with dual VC dimension $k$ and as before, let $\mathcal{A}$ be a shattered set of size $k$ and $\mathcal{X}$ be a set of $2^k$ vertices such that for each subset of hyperedges of $\mathcal{A}$ there is exactly one vertex of $\mathcal{X}$ that is contained to exactly this subset of hyperedges. Let $x_0$ be the vertex of $\mathcal{X}$ that is contained in no hyperedges and consider the hypergraph $\mathcal{H}$ induced by $\mathcal{X} \setminus \{x_0\}$. Notice first that $\mathcal{H}$ belongs to $\mathcal{C}$. By construction, $\mathcal{H}$ has $2^k - 1$ vertices and the set of hyperedges of $\mathcal{A}$ forms a test cover. Furthermore, any proper subset of hyperedges is not a test cover since the minimum size of a test cover among $2^k - 1$ vertices is $k$.

3.2 Metric dimension, VC dimension and diameter

In contrast to test covers, there is no direct relation between the VC dimension of $G$ and its metric dimension. Indeed, consider the family of line graphs. Any line graph has VC dimension at most 4. Nevertheless, there is a line graph with more than $2^k$ vertices, diameter 4 and metric dimension at most $k$. Indeed, consider the following graph. Take $k$ disjoint edges $\{e_1, ..., e_k\}$ and $2^k - 1$ disjoint edges $\{e'_i, I \subseteq \{1, ..., k\}, I \neq \emptyset\}$ corresponding to the nonempty subsets of $\{e_1, ..., e_k\}$. For each edge $e'_i$, add $|I|$ edges between one endpoint of $e'_i$ (always the same one) and all the endpoints of $e_i$ for $i \in I$ (again, choose always the same endpoint for $e_i$). Let $G$ be the line graph of this graph. The graph $G$ has $k + 2^k - 1 + \sum_{i=1}^k i^2(i^3)$ vertices and diameter 4. Moreover, the set $S$ of vertices corresponding to the edges $\{e_1, ..., e_k\}$ forms a resolving set. Indeed, a vertex corresponding to an edge $e'_i$ has distance 2 to $e_i$ if $i \in I$ and 4 otherwise. A vertex corresponding to an edge between $e'_i$ and $e_i$ (with $i \in I$) has distance 1 to $e_i$, 2 to $e_j$ when $j \in I$ and 4 otherwise. Therefore all the edges have unique distance vector to $S$.

However, there is such a relation when we consider the distance-VC dimension, introduced by Bousquet and Thomassé [10]. The distance hypergraph of $G$ is the hypergraph $\mathcal{H}(G)$ with vertex set $V$ and for all $i$, all the balls of radius $\ell$. The distance-VC dimension of $G$, $dv^*(G)$, is the VC dimension of $\mathcal{H}(G)$. The dual distance-VC dimension of $G$, denoted $dv^*(G)$, is the VC dimension of $\mathcal{H}(G)^*$. Similarly, the (dual) 2-distance VC dimension of $G$ is the 2-VC dimension of $\mathcal{H}(G)$ ($\mathcal{H}(G)^*$, respectively).

We first give a relation between test covers in $\mathcal{H}(G)$ and the metric dimension of $G$.

**Proposition 12.** If $G$ is a graph of diameter $d$ and metric dimension $k$, then we have the following.

$$\frac{TC(\mathcal{H}(G)) - 1}{d} \leq k \leq TC(\mathcal{H}(G)).$$

**Proof.** Let $T$ be a test cover of $\mathcal{H}(G)$. Then the set of centers of the balls corresponding to the hyperedges of $T$ form a resolving set. Indeed, let $x, y \in V$ and assume without loss of generality that there exists $B \in T$ such that $x \in B$ and $y \notin B$. Let $v$ be the center of $B$ and let $r$ be its radius. Then $v$ resolves $\{x, y\}$ since $d(v, x) \leq r < d(v, y)$. This shows that $k \leq TC(\mathcal{H}(G))$. 

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Now let $R$ be a resolving set and let $T$ be the set of balls centered in vertices of $R$ for all radius from 0 to $d-1$ plus any ball with radius $d$. Then $T$ is a test cover of $\mathcal{H}(G)$. Indeed let $x, y \in V$ and let $z \in R$ such that $d(z, x) \neq d(z, y)$. Assume without loss of generality that $d(z, x) < d(z, y)$. Then $d(z, x) < d$ and the ball centered in $z$ with radius $d(z, x)$ distinguishes $x$ and $y$. Thus, since any vertex is covered by the ball of radius $d$, the test cover $T$ has size $d|R| + 1$. □

We deduce the following.

**Proposition 13.** If $G$ is a graph of order $n$ with diameter $d$ and a resolving set of size $k$, then

$$n \leq (dk + 1)^{dvc(G)} + 1.$$ 

**Proof.** By Proposition 10, $n \leq (TC(\mathcal{H}(G)))^{dvc(G)} + 1$. Then, by Proposition 12 we have $TC(\mathcal{H}(G)) \leq kd + 1$. □

Proposition 13 is useful when one can bound the dual distance-VC dimension of a graph. The next proposition gives a relation between $dvc$ and $dvc^*$.

**Proposition 14.** If $G$ is a graph of diameter $d$, then

$$\frac{1}{\log dvc(G)} (dvc(G) - \log d) \leq dvc^*(G) \leq d \cdot dvc(G).$$

**Proof.** For the first inequality, let $k$ denote $dvc(G)$. Let $S$ be a shattered set of $\mathcal{H}(G)$ of size $k$. For each subset $X$ of $S$, there exists a ball $B$ such that $B \cap X = X$. Let $B$ be the set of those balls. Among all the radii used in $B$, let us consider the most used $\ell$ and let $B_\ell$ be the set of balls of $B$ of radius $\ell$. We have $|B_\ell| \geq \frac{|B|}{2^{\ell-1}} \geq \frac{d}{2^{\ell-1}}$. Considering the hypergraph $\mathcal{H}_\ell(G)$ formed by all balls of $G$ of radius $\ell$, we have $|\mathcal{H}_\ell(G)| \geq |B_\ell| \geq \frac{d}{2^{\ell-1}}$ and then, by Lemma 8 $\frac{d}{\log(k)} \leq k^{\log\log(k)}$ which implies that $\frac{d}{\log(k)} \leq \log(\mathcal{H}_\ell(G))$. Now since $\mathcal{H}_\ell$ is isomorphic to its dual we have $\frac{k}{\log(k)} \leq \log(\mathcal{H}_\ell(G)) \leq \log(\mathcal{H}(G)) = dvc^*(G)$.

For the second inequality, let $S$ be a shattered set of $\mathcal{H}(G)^*$ of size $dvc^*(G)$. Let $\ell$ be the most used radius in $S$ and let $S_\ell$ be the set of balls of $S$ of radius $\ell$. Let $\mathcal{H}_\ell(G)$ be the hypergraph formed by all balls of $G$ of radius $\ell$. Notice that $\mathcal{H}_\ell(G)$ is isomorphic to its dual $\mathcal{H}_\ell(G)^*$ and then $\log(\mathcal{H}_\ell(G)) = \log(\mathcal{H}_\ell(G)^*)$. Observe now that $S_\ell$ is a shattered set of $\mathcal{H}_\ell(G)^*$ and since $|S_\ell| \geq \frac{dvc^*(G)}{d}$ we have $dvc(G) \geq \log(\mathcal{H}_\ell(G)) \geq \frac{dvc^*(G)}{d}$. □

Bousquet and Thomassé proved that graphs of bounded rankwidth\footnote{We do not define this concept here, since we barely use it, and refer the reader to [10] instead. Note that any graph of bounded treewidth or cliquewidth also has bounded rankwidth.} and $K_t$-minor free graphs have bounded distance-VC dimension (and thus, bounded distance-VC dimension).

**Theorem 15 ([10]).** A $K_t$-minor-free graph has distance 2-VC dimension at most $t-1$. The distance 2-VC dimension of a graph with rankwidth $r$ is at most $3 \cdot 2^r + 2$.

Since the distance 2-VC dimension is always larger than the distance-VC dimension and using Proposition 13 we have the following corollaries of Proposition 13.

**Corollary 16.** Let $G$ be a graph of order $n$, diameter $d$ and with a resolving set of size $k$. If $K_t$ is not a minor of $G$, then

$$n \leq (dk + 1)^{d(t-1)} + 1.$$ 

If $G$ has rankwidth at most $r$, then

$$n \leq (dk + 1)^{d(3 \cdot 2^r + 2)} + 1.$$
3.3 The dual 2-distance VC dimension and $K_t$-minor free graphs

In this section, we improve the bound of Corollary 16 for $K_t$-minor-free graphs.

**Theorem 17.** If $G$ is a $K_t$-minor-free graph of diameter $d$ and order $n$, with a resolving set of size $k$, then $n \leq (dk + 1)^{t-1} + 1$.

To prove Theorem 17, we combine Proposition 14 with the following theorem, which is a “dual” version of Theorem 15. We denote the length of a path $P$ by $\ell(P)$.

**Theorem 18.** If the dual distance 2-VC dimension of a graph $G$ is at least $t$, then $K_t$ is a minor of $G$.

**Proof.** To prove Theorem 18, we adapt the proof of Theorem 10 for distance 2-VC dimension to the dual distance 2-VC dimension, and prove the following.

Let $\{(v_1, r_1), \ldots, (v_t, r_t)\}$ be a 2-shattered set in the dual of $\mathcal{H}(G)$. Then, for all $i, j$, there exists $x_{ij}$ such that:

- $d(x_{ij}, v_i) \leq r_i$
- $d(x_{ij}, v_j) \leq r_j$
- $d(x_{ij}, x_k) > r_k$ if $k \notin \{i, j\}$

For any such $x_{ij}$, a path formed by a path $P$ between $v_i$ and $x_{ij}$ and a path $P'$ between $x_{ij}$ and $v_j$ such that $\ell(P) \leq r_i$ and $\ell(P') \leq r_j$ is called a good $ij$-path. For a path $P$ and two vertices $x, y$ in $P$, we denote by $P[x, y]$ the subpath of $P$ between $x$ and $y$.

**Claim 18.A.** If $i, j, k, l$ are distinct and $P_{ij}, P_{kl}$ are two good paths, then $P_{ij} \cap P_{kl} = \emptyset$.

**Proof of claim.** Let $P_i := P_{ij}[v_i, x_{ij}]$ be the path from $v_i$ to $x_{ij}$ and let $P_k := P_{kl}[v_k, x_{kl}]$ be the path from $v_k$ to $x_{kl}$. Suppose for contradiction that there exists $u \in P_{ij} \cap P_{kl}$. Assume without loss of generality that $u \in P_i \cap P_k$ and that $\ell(P_k[u, x_{kl}]) \leq \ell(P_i[u, x_{ij}])$. Then, since $\ell(P_i) = \ell(P_i[v_i, u]) + \ell(P_i[u, x_{ij}]) \leq r_i$, we have $d(v_i, x_{kl}) \leq \ell(P_i[v_i, u]) + \ell(P_i[u, x_{kl}]) \leq r_i$, which is a contradiction. ($\Box$)

**Claim 18.B.** If $i, j, k$ are distinct and $P_{ij}, P_{ik}$ are two good paths that intersect in $z$, then $x_{ij}$ and $x_{ik}$ cannot both be in the part of $P_{ij}$ (resp. $P_{ik}$) that is between $v_i$ and $z$. Hence, at least one of $x_{ij} \in P_{ij}[z, v_j]$ or $x_{ik} \in P_{ik}[z, v_k]$ is true.

**Proof of claim.** Suppose, to the contrary, that both $x_{ij}$ and $x_{ik}$ are between $z$ and $v_i$ and assume without loss of generality that $\ell(P_{ij}[z, x_{ij}]) \leq \ell(P_{ik}[z, x_{ik}])$. Then we have

$$d(v_k, x_{ij}) \leq \ell(P_k[v_k, z]) + \ell(P_{ij}[z, x_{ij}]) \leq \ell(P_k[v_k, z]) + \ell(P_{ik}[z, x_{ik}]) = \ell(P_k[v_k, x_{ik}]) \leq r_k$$

contradicting the fact that $d(v_k, x_{ij}) > r_k$. ($\Box$)

**Claim 18.C.** If $i, j, k$ are distinct and $P_{ij}, P_{ik}$ and $P_{jk}$ are three good paths, then $P_{ij} \cap P_{ik} \cap P_{jk} = \emptyset$.

**Proof of claim.** Let $z \in P_{ij} \cap P_{ik} \cap P_{jk}$. Assume without loss of generality that

$$\ell(P_{ij}[z, x_{ij}]) = \min(\ell(P_{ij}[z, x_{ij}]), \ell(P_{ik}[z, x_{ik}]), \ell(P_{jk}[z, x_{jk}]))$$

Assume furthermore that $x_{ij} \in P_{ij}[v_i, z]$. By Claim 18.B, $x_{ik} \in P_{ik}[z, v_k]$ and $x_{jk} \in P_{jk}[z, v_j]$. Now we have

$$d(v_k, x_{ij}) \leq \ell(P_{jk}[v_k, z]) + \ell(P_{ij}[z, x_{ij}]) \leq \ell(P_{jk}[v_k, z]) + \ell(P_{jk}[z, x_{jk}]) = \ell(P_{jk}[v_k, x_{jk}]) \leq r_k$$

contradicting the fact that $d(v_k, x_{ij}) > r_k$. ($\Box$)

For all $x \in V$, we give label $i$ to $x$ if there exists two good paths $P_{ij}$ and $P_{ik}$ that intersects in $x$. Note that $v_i$ has label $i$.

**Claim 18.D.** For all $x \in V$, $x$ has at most one label.
Proof of claim. Let $P_{ij}$ and $P_{kl}$ be two good paths containing $x$. By Claim [18.A] we have $\{i,j\} \cap \{l,k\} \neq \emptyset$. Assume without loss of generality that $i = k$. Assume now that there exists a third good path $P_{mn}$ containing $x$. We show that $i \in \{m,n\}$. Suppose, to the contrary, that $i \neq m$ and $i \neq n$. Since $x \in P_{ij} \cap P_{mn}$, by Claim [18.A] either $m = j$ or $n = j$ (say $m = j$). Now since $x \in P_{il} \cap P_{mn}$, we have that $n = i$. But then $x \in P_{ij} \cap P_{l} \cap P_{jl}$ which is in contradiction with Claim [18.C]. So every good path containing $x$ is a good path from $v_i$ and then $x$ has only label $i$. (\(\square\))

Let $C_i$ be the set of vertices that are labeled $i$. Since $v_i$ has label $i$, $C_i$ is non-empty.

Claim 18.E. For all $i \leq d$, $C_i$ induces a connected subgraph.

Proof of claim. We will prove that for each vertex $u \in C_i$, there exists a path in $C_i$ from $u$ to $v_i$. Assume that $u \in P_{ij} \cap P_{il}$. By Claim [18.B] either $ij \in P_{ij}[v_i,u]$ or $il \in P_{il}[v_i,u]$. Assume without loss of generality that $ij \in P_{ij}[v_i,u]$. By definition of $x_{il}$, $r_j < d(v_j,x_{il}) \leq \ell(P_{ij}[u,v_j]) + \ell(P_{il}[u,x_{il}])$ and since $\ell(P_{ij}[u,v_j]) + \ell(P_{il}[u,x_{il}]) = \ell(P_{il}[u,x_{il}]) \leq r_i$, we have $\ell(P_{il}[u,x_{il}]) > \ell(P_{ij}[x_{il},u])$. Then since $\ell(P_{il}[v_i,u]) + \ell(P_{il}[u,x_{il}]) = \ell(P_{il}[v_i,u]) + \ell(P_{il}[u,x_{il}]) \leq r_i$. Thus $P_{il}[v_i,u] \cup P_{ij}[x_{ij},v_j]$ is a good $ij$-path. We conclude that all vertices of $P_{il}[v_i,u]$ have label $i$ (that is, $P_{il}[v_i,u] \subseteq C_i$). (\(\square\))

Assume now that $\{(v_1,r_1),\ldots,(v_i,r_i)\}$ is a 2-shattered set in the dual of $\mathcal{H}(G)$. Then the sets $C_i$ form non-empty connected disjoint sets of vertices and there are disjoint paths between any pair of such sets. Thus there is a minor $K_{11}$, completing the proof of Theorem [18] (\(\square\)).

3.4 Outerplanar graphs

Outerplanar graphs are $K_4$-minor-free and have treewidth at most 2. Hence, by Theorem [17] $n = \mathcal{O}(d^3k^3)$ and by Corollary [5] $n = \mathcal{O}(d^3k^3)$. We will improve these bounds using a different method.

Theorem 19. If $G$ is an outerplanar graph with diameter $d$ and a resolving set of size $k$, then $G$ has order at most $2kd^2 - 2d^2 + d + 1 = \mathcal{O}(kd^2)$.

Proof. Let $S$ be a resolving set of $G$ of size $k$. We consider a circular layout of $G$, that is, a planar representation of $G$ with all the vertices lying on the boundary of a circle $C$ (it is not difficult to see that such a layout exists, see [28]). The vertices of $G$ can be naturally ordered following $C$ and starting by $s_1$. We denote this order by $<$.

Claim 19.A. Let $x < y < z < t$ be four vertices of $G$. Let $P_1$ be a path from $y$ to $t$ and $P_2$ be a path from $x$ to $z$. Then $P_1$ and $P_2$ must intersect.

Proof of claim. Indeed, the drawing of the path $P_2$ cuts the disk formed by $C$ into two disjoint components and the vertices $y$ and $t$ are not in the same component. Therefore, the drawing of the path $P_1$ must intersect $P_2$, and since the representation is planar, it must be on a vertex. (\(\square\))

For each $1 \leq i \leq d$, we define $L_i$ to be the set of vertices at distance exactly $i$ of $s_1$. The following claim is key to our proof.

Claim 19.B. Let $i \in \{1,\ldots,d\}$. Let $s \in S$ and $y$ a vertex of $L_i$ that minimizes the distance between $s$ and vertices of $L_i$. Let $u$ and $v$ be vertices of $L_i$. If $y < u < v$ or $v < u < y$, then $d(s,u) \leq d(s,v)$.

Proof of claim. We assume that $s_1 < y < u < v$ (the other case is symmetric).

We first prove that $d(y,u) \leq d(y,v)$. Let $P_1$ be a shortest path from $y$ to $v$ and $P_2$ be a shortest path from $u$ to $s_1$. By Claim [19.A] $P_1$ and $P_2$ must intersect in some vertex $z$. Since $P_2$ is a shortest path from $u$ to $s_1$, it has length $i$ and $d(z,s_1) \leq i$, and so $z \in L_j$ with $j \leq i$. Furthermore, we have $d(z,v) \geq i-j = d(z,u)$. Let $P$ be the path from $y$ to $u$ that consists of the subpath of $P_1$ from $y$ to $z$, followed by the subpath of $P_2$ from $z$ to $u$. Since $d(z,u) \leq d(z,v)$, the path $P$ is not longer than $P_1$ and thus $d(y,u) \leq d(y,v)$.

This proves the claim when $s \in L_i$. Assume now that $s \in L_j$ and that $j < i$. Let $P_1$ be a path formed by the union of a shortest path $P_{1,1}$ from $y$ to $s$ and a shortest path $P_{1,2}$ from $s$ to $v$. Let $P_2$ be a shortest path from $u$ to $s_1$. By Claim [19.A] $P_1$ and $P_2$ must intersect in $z$ and as before, $z \in L_k$ with $k \leq i$. If $z$ belongs to $P_{1,1}$, that is, to a shortest path between $y$ and $s$, then the path from $s$ to $u$ following $P_{1,1}$ until $z$ and then $P_2$ until $u$ is shorter than $P_{1,1}$ (since $d(z,u) \leq d(z,y)$). Hence $d(s,u) \leq d(s,y)$ but $y$ is
minimizing the distance between $s$ and a vertex of $L_i$. Therefore, $d(s, y) = d(s, u) \leq d(s, v)$. Otherwise, $z$ must belong to $P_{1,2}$, a shortest path between $s$ and $v$. Then the path $P$ from $s$ to $u$ that follow $P_{1,2}$ until $z$ and then $P_2$ until $u$ is shorter than $P_{1,2}$. Indeed, since $z \in L_k$, we have $d(z, u) = i - k$ and $d(z, v) \geq i - k$. Thus $d(s, u) \leq d(s, v)$.

Assume finally that $s \in L_j$ with $j > i$. We have $d(s, y) = j - i$ (indeed, a shortest path from $s$ to $s_1$ must pass by a vertex $y' \in L_i$ and then $d(s, y') = j - i$). Let $P_1$ be a path formed by the union between a shortest path $P_{1,1}$ from $y$ to $s$ and a shortest path $P_{1,2}$ from $s$ to $v$. Let $P_2$ a shortest path from $u$ to $s_1$. Again, $P_1$ and $P_2$ must intersect in $z \in L_k$, with $k \leq i$. Since $P_{1,1}$ is a path of length $j - i$ between $L_i$ and $L_j$, all the vertices of $P_{1,1}$ are in a layer $L_{i'}$ with $i \leq i' \leq j$. It is not possible to have $z = y$ since in $P_2$ there is exactly one vertex $y_{j'}$ for $j' \leq i$, and $u \neq y$ is this vertex for $j' = i$. Hence $z$ is in $P_{1,2}$. It means that there is a vertex $z' \in L_j$ on the path from $s$ to $z$: indeed when going from $L_j$ to $L_k$ a path must intersect all the layers between $L_k$ and $L_j$. We choose for $z'$ the first vertex of $L_i$ we meet on $P_{1,2}$ going from $s$ to $v$. If $z' < u < s$ then as in the first case of the proof, $d(z', u) \leq d(z', v)$ and so $d(s, u) \leq d(s, v)$ and we are done. Otherwise, we have $s_1 < y < u < z'$ and there is a path from $y$ to $z'$ (the path $P_1$ stopped in $z'$) that is not intersecting a path from $s_1$ to $u$, which contradicts Claim [19.A]. This completes the proof of Claim [19.B].

We can now finish the proof of Theorem [19]. By Claim [19.B] each vertex $s \neq s_1$ of $S$ partitions the vertices of $L_i$ with respect to the order $<$. into at most $2d + 1$ parts such that two vertices belonging to the same part have the same distance to $s$. Hence, together, the vertices of $S \setminus \{s_1\}$ partition $L_i$ into at most $2d(k - 1) + 1$ parts and the distance to $S$ of each vertex of $L_i$ is determined by its position in the partition. Hence, there is at most one vertex in each part, and thus $|L_i| \leq 2d(k - 1) + 1$. Finally, the total number of vertices of $G$ is at most $1 + \sum_{i=1}^d |L_i| \leq 2d^2(k - 1) + d + 1$. This completes the proof of Theorem [19].

We now show that Theorem [19] is tight, up to a constant factor. For two integers $d, k \geq 2$, let $O_{d,k}$ be the outerplanar graph constructed as follows. First, for some integer $i$, we define a graph $H_i$ as follows. Consider a cycle $C$ of length $2i + 1$, where $x$ is a distinguished vertex of $C$. To any vertex $v$ of $C$ at distance $j \geq 1$ of $x$, we attach a path of length $i - j + 1$ to $v$, and to one of the two vertices at distance $i$ of $x$ in $C$, we attach a second arc. Now, $O_{d,k}$ is built from $k - 1$ copies of $H_{[d/2] - 1}$ and one copy of $H_{[d/2]}$ identified at $x$, with an additional path of length $[d/2]$ attached to $x$. (Note that we may optionally add chords to the cycles in $O_{d,k}$, as long as the outerplanarity and the distances from each vertex having two leaves attached are preserved.) The order of $O_{d,k}$ is $d^2 + k \left( 2 \sum_{i=1}^{d/2} i - 1 \right)$ when $d$ is even, and $d^2 + k \left( 2 \sum_{i=1}^{d/2} i - 1 \right)$ when $d$ is odd; this is $(\frac{1}{4} + o(1))kd^2$. See the graph of Figure [2] for an illustration of $O_{7,3}$ and $O_{8,3}$.

Proposition 20. Let $d, k \geq 2$ be two integers. The outerplanar graph $O_{d,k}$ has diameter $d$, metric dimension $k$ and order $(\frac{1}{4} + o(1))kd^2$.

Proof. The values of the diameter and the order follow from the definition. To see that the metric dimension is $k$, consider the $k$ vertices that have two neighbours of degree 1. In order for these two neighbours to be distinguished, one of them needs to be in any resolving set. Now, we pick exactly one of them and repeat this for every such pair; we obtain a set $S$ of $k$ vertices. We claim that $S$ is a resolving set. Let $S = \{s_1, \ldots, s_k\}$ and let us call $C_i$ the component of $O_{d,k} - x$ containing $s_i$. (There are $k + 1$ components in $O_{d,k} - x$, with one of them isomorphic to a path and not containing any vertex of $S$.) Any two vertices $u$ and $v$ from different components of $O_{d,k} - x$ are distinguished, since at least one of them (say $u$) has a vertex $s_j$ of $S$ in its component $C_j$, and $d(u, s_j) < d(v, s_j)$. Within a component $C$ of $O_{d,k} - x$, vertices with distinct distances to $x$ are distinguished by the vertices of $S$ not in $C$. Finally, vertices at the same distance of $x$ in a component $C_i$ are distinguished by $s_i$. □

4 Conclusion

For trees and outerplanar graphs, we know that $n = O(kd^2)$ and this is tight. We do not know whether our other bounds are tight. It would be interesting to further study the classes of graphs of fixed treewidth $w$ (or the more restricted case of $w$-trees) and the class of chordal graphs. We have proved
that \( n = \mathcal{O}(kd^{3w+3}) \) for constant \( w \) (Corollary 5) and \( n = \mathcal{O}(f(k)d^2) \) for chordal graphs, where \( f \) is doubly-exponential (Corollary 7). Can these bounds be improved? Moreover, Corollary 14 gives a bound in terms of rankwidth. Trying to get a similar result in terms of cliquewidth seems to be a natural follow-up.

Another interesting problem is to determine the best possible bound for planar graphs, that is, whether our \( n = \mathcal{O}(d^4k^4) \) bound that follows from Theorem 17 can be improved. Note that \( n = \mathcal{O}(d^2) \) holds when the metric dimension is 2, indeed in this case we have \( n \leq d^2 + 2 \) for any graph \([12, 21]\). This quadratic bound is matched by any square grid, which has metric dimension 2 and \( n = d^2 \). Nevertheless, there are planar graphs with metric dimension 3 and order \( \Theta(d^3) \). Such a family of graphs can be described as follows. Pick any integer \( t \) and consider \( t \) disjoint copies \( G_1, G_2, \ldots, G_t \) of a \( t \times t \) grid. For \( i \) between 1 and \( t - 1 \), add an edge between the top left corners of \( G_i \) and \( G_{i+1} \) and another edge between the top right corners of \( G_i \) and \( G_{i+1} \). The diameter of this graph is \( 4t \) and its order is \( t^3 \). Moreover the top corners of \( G_1 \) together with the bottom left corner of \( G_t \) form a resolving set of size 3. We do not know whether there are planar graphs with small metric dimension and order \( \Theta(d^3) \).

For the smaller class of treewidth 2 graphs (that is, \( K_4 \)-minor free graphs), we know that \( n = \mathcal{O}(d^3k^3) \) (Theorem 17) and \( n = \mathcal{O}(d^9k) \) (Corollary 5), but we doubt that these bounds are optimal. We remark that our proof method for outerplanar graphs does not seem to be easily generalizable to this class.

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