Yang’s Gravitational Theory

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Abstract

Yang’s pure space equations (C.N. Yang, Phys. Rev. Lett. 33, 445 (1974)) generalize Einstein’s gravitational equations, while coming from gauge theory. We study these equations from a number of vantage points: summarizing the work done previously, comparing them with the Einstein equations and investigating their properties. In particular, the initial value problem is discussed and a number of results are presented for these equations with common energy-momentum tensors.

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1 Introduction

Over 20 years ago C. N. Yang [1] introduced a system of equations which, while generalizing Einstein’s vacuum equations, take the Yang-Mills equations of gauge theory as their underlying structure. These equations, which we refer to as Yang’s equations, as obvious candidates (at the classical level at least) for the unification of gravitational and gauge theory, have been studied from a number of perspectives during the subsequent years. Our intention in this paper is threefold: to summarize the work that has been done on these equations as they relate to classical general relativity, to argue that these equations are worthy of closer scrutiny, and, finally, to extend the work that has already been done.

The basic variable in Yang’s theory is, as in general relativity, a Lorentz metric $g_{ab}$ on a 4-manifold $M$. The equations that this metric is required to satisfy are

$$\nabla_a R_{bc} - \nabla_b R_{ac} = 0,$$

(1)

where $R_{ab}$ is the Ricci tensor and $\nabla$ is the covariant derivative associated with $g_{ab}$.

Yang’s equations arise naturally by applying the Yang–Mills condition $^*D^*F = 0$ to the curvature 2-form (Riemann tensor) of an $so(3,1)$ valued Levi–Civita connection. In tensorial language, this reads $\nabla_a R^{abcd} = 0$, which by the Bianchi identities, is equivalent to (1).

We do not propose to allow these equations to supercede those of Einstein as the field equations of space-time, but rather intend on the one hand to investigate the consequences of Yang’s equations as being of interest in their own right, and on the other to study the implications of Yang’s equation for classical general relativity.

As a third order non-linear system, Yang’s equations are significantly more complex than those of either general relativity or Yang-Mills theory, both of which are second order. Nonetheless, shortly after Yang published his paper a number of exact solutions were discovered by Pavelle [2] [3], Thompson [4] [5], Ni [6] and Chen-Long et al [7] [8]. Later work by Aragone and Restuccia [9] investigated the linearized version of Yang’s equations, while Mielke [10] has looked at the equations with emphasis on the double anti-self dual ansatz, which yields a gravitational analog of the instanton pseudoparticle of Yang-Mills theory.
More recently, these equations have been subsumed into a general quadratic lagrangian approach, where the basic variables are the metric and the connection (which is not necessarily torsion free - see Baekler, Heyl and Mielke [11], Maluf [12][13] and Szczyrba [14]). Further interest in the equations has been generated by suggestions that they may be suitable for describing the propagation of gravitational waves in a non-vacuum (see van Putten [15]).

In the next section we shall outline a number of general properties of solutions to Yang’s equations. Many of these properties have been described in one form or another over the last 20 years. In addition, we study the relationship between the curvature orthogonality condition (a consequence of Yang’s equations) and the algebraic structure of the Ricci tensor.

Any classical dynamical equation is required to be deterministic, in the sense that, given some initial (possibly constrained) data on a spacelike slice of spacetime, the equations have a solution, at least for a short time into the future. Section 3 discusses this initial value problem for Yang’s equations and indicates how this can be shown to be well-posed.

Section 4 looks at the compatibility of different energy-momentum tensors with Yang’s equations. In particular, we show that all Einstein–Maxwell fields obeying Yang’s equations lie in Kundt’s class [16] and all perfect fluids have Robertson–Walker geometry.

There are many open questions concerning these equations which the authors consider worth pursuing. Describe the asymptotic fall-off for YPS. Does a peeling theorem apply? Is there a hamiltonian formulation for the dynamics of the theory? Are the equations linearisation stable? How do gauge symmetries of the Levi-Civita connection relate to Killing vectors of the metric? Further study of the existing exact solutions is also warranted.

Throughout, we will refer to Lorentz 4-manifolds \((M, g_{ab})\) which satisfy Yang’s equation as \textit{Yang Pure Spaces} (YPS).

\[ \text{The abbreviation shall be applied to both the singular and plural cases.} \]
2 Some Basic Properties of Yang Pure Spaces

In this section, we review three properties of solutions of Yang’s equation. These properties have been noted previously by other authors (see e.g. Thompson [4][5]); our aim is to present (and extend) these results as a preliminary step prior to obtaining solutions of Yang’s equations under various assumptions.

Firstly, we note that a contraction of Yang’s equations (1) yields
\[ \nabla_a R^a_b - \partial_b R = 0, \]
so that when this is compared with the contracted Bianchi identity
\[ \nabla_a R^a_b - \frac{1}{2} \partial_b R = 0, \]
we find that a necessary condition for \((M, g_{ab})\) be a YPS is that it be of constant scalar curvature.

On the other hand, because in four dimensions the full (second) Bianchi identities are equivalent to
\[ \nabla_a C^{abcd} = \nabla_a [R_{[cd]}^b] - \frac{1}{6} g_{[d} \nabla_c R, \]
Yang’s equations (1) is equivalent to
\[ \nabla_a C^{abcd} = 0, \quad R = \text{constant}. \tag{2} \]

From this, we can immediately identify three large classes of solutions:

**Theorem 2.1** The following are sufficient (though not necessary) for \((M, g_{ab})\) to be a YPS:

(a) \((M, g_{ab})\) is an Einstein space,

(b) \((M, g_{ab})\) is conformally flat with constant Ricci scalar,

(c) \((M, g_{ab})\) has parallel Ricci tensor.

It is worth noting that Yang’s equations are not conformally invariant. Indeed

**Theorem 2.2** Suppose that \((M, g_{ab})\) is a YPS. Then a conformally related metric also solves Yang’s equations if and only if the conformal curvature of \((M, g_{ab})\) is degenerate of type N, with twistfree repeated principal null direction.
It is also worth mentioning that all solutions of class (b) are obtained by solving the nonlinear wave equation

\[ \Box_M \Omega + \frac{1}{6} R \Omega^3 = 0, \tag{3} \]

for the conformal factor \( \Omega \) of the metric tensor \( g_{ab} = \Omega^2 \eta_{ab} \), where \( \Box_M \) is the d’Alembertian of flat space-time and \( R \) is the constant Ricci scalar of \( g_{ab} \). In fact, the existence of a solution to this equation constitutes a version of the "Lorentz Yamabe problem":

**Lorentz Yamabe Conjecture** Let \((M, g_{ab})\) be a closed or asymptotically flat Lorentz manifold, then equation (3) has a solution.

Note also that because of (2), the Ricci and Weyl tensor terms in the Bianchi identities uncouple. Hence in the Newman–Penrose (NP) formalism, Yang’s equations are equivalent to the contracted Bianchi identities (equations 7.69 - 7.71 of Kramer et al [17] or equations 4.12.40-41 of Penrose and Rindler [18]), and the remaining Bianchi identities (equations 7.61-68 of [17] or equations 4.12.36-39 of [18]) with either all Weyl tensor terms ignored and \( \Lambda = R/24 \) held constant, or all Ricci tensor terms ignored. One or other version may be used according as one has information regarding the Weyl or Ricci tensor.

Secondly, Yang’s equations imply the equation

\[ \nabla^{DD'} \Psi_{ABCD} = 0, \]

for the Weyl spinor. Hence the classic Goldberg–Sachs theorem holds:

**Theorem 2.3** In a YPS \((M, g_{ab})\) a null vector \( k^a \) is a repeated principle null direction (pnd) of the Weyl tensor if and only if \( k^a \) is tangent to a shearfree null geodesic.

Thus this theorem, which is an indispensible tool in the study of exact solutions of Einstein’s equation, may also be used in the study of YPS.

Thirdly, on taking the covariant derivative of Yang’s equations and applying the Ricci identities, one can obtain the equation

\[ R_{ab[cd} R^{de]} = 0, \]

which has the irreducible form

\[ C_{ab[cd} R^{de]} = 0, \tag{4} \]
where $P_{ab} \equiv R_{ab} - (R/4)g_{ab}$ is the trace-free Ricci tensor. Thompson [1] has pointed out some of the consequences of this equation, which we will refer to as the Curvature Orthogonality Condition (COC), for the Petrov type of non-Einstein YPS. We wish to focus on these consequences in more detail.

In the section 4, we shall investigate the compatibility of different types of physical energy-momentum tensor with Yang’s equation. It is therefore of interest to determine what may be deduced from (4), assuming a particular structure for the energy-momentum tensor, which determines, via Einstein’s equation, the structure of the Ricci tensor. In particular, we will determine the Petrov types allowed by the COC for the different Segré types of the Ricci tensor. In order to do so, it will be convenient to write (4) in NP form. There are nine independent equations as we can see from the following.

Considering the tensor

$$T_{abcd} \equiv C_{ae}[bc, P^e_{\, \, d}],$$

there are four choices for each of the index sets $a$ and $bcd$. From the symmetries of $C_{abcd}$ and $P_{ab}$, we find that $T_{abcd}$ is completely trace-free yielding the six equations $T^a_{\, \, acd} = 0$, and in addition obeys

$$T_{(abc)} = \frac{1}{3} T_{dabc},$$

which is one further equation. There are no further possible identities, so that $T_{abcd}$ has nine independent components in all. Transvecting with appropriate members of a null tetrad, these nine equations may be written

\begin{align*}
- \Phi_{21} \Psi_0 + 2 \Phi_{22} \Psi_1 + \Phi_{02} \Psi_1 - \Phi_{01} (\Psi_2 + \bar{\Psi}_2) + \Phi_{00} \bar{\Psi}_3 &= 0, \quad (5) \\
\Phi_{02} \bar{\Psi}_0 - \Phi_{20} \Psi_0 + 2 \Phi_{10} \bar{\Psi}_1 - 2 \Phi_{01} \Psi_1 - \Phi_{00} (\Psi_2 - \bar{\Psi}_2) &= 0, \quad (6) \\
\Phi_{21} \Psi_1 - \Phi_{12} \bar{\Psi}_1 + 2 \Phi_{11} (\bar{\Psi}_2 - \Psi_2) + \Phi_{01} \Psi_3 - \Phi_{10} \bar{\Psi}_3 &= 0, \quad (7) \\
\Phi_{22} \Psi_1 - \Phi_{12} (2 \Psi_2 + \bar{\Psi}_2) + \Phi_{11} \bar{\Psi}_3 + \Phi_{02} \Psi_3 - \Phi_{10} \bar{\Psi}_4 &= 0, \quad (8) \\
\Phi_{22} (\Psi_2 - \bar{\Psi}_2) + 2 \Phi_{21} \bar{\Psi}_3 - 2 \Phi_{12} \Psi_3 + \Phi_{02} \Psi_4 - \Phi_{20} \bar{\Psi}_4 &= 0, \quad (9) \\
\Phi_{22} \Psi_0 - 2 \Phi_{12} \Psi_1 + \Phi_{02} (\Psi_2 - \bar{\Psi}_2) + 2 \Phi_{01} \Psi_3 - \Phi_{00} \bar{\Psi}_4 &= 0. \quad (10)
\end{align*}

Notice that equations (5), (8), (10) are complex, giving two real equations each.

The standard algebraic classification of the Ricci tensor (Hall [19], Kramer et al [17], §5.1) relies upon the number and multiplicities of the eigenvalues, and the nature (space-
like, time-like or null) and multiplicities of the eigenvectors of the eigen-problem

\[ R^a_{\ b} v^b = \lambda v^a. \]

In order to use (4) in the form (5) to (10), we will construct a null tetrad which is based on these eigenvectors and consider the NP components of the Ricci and Weyl tensors on this tetrad. A sample calculation is given below, and Tables I-IV give a complete description of the Petrov types allowed by the COC for a given Segré type. In the tables, the first column indicates the Segré type of the Ricci tensor. The second column gives the eigenvectors of the Ricci tensor, with time-like, null or complex eigenvectors before the comma, and eigenvectors with the same eigenvalue grouped in parentheses. Relations which arise for the NP Weyl scalars are given in the third column, and from these relations, the allowed Petrov types are determined and indicated in the fourth column. Where the Segré type has an important physical interpretation, this is given in the final column. Note that the COC provides no information about conformally flat or Einstein spaces (Segrè type \{(1,111)\}), and so these will be omitted from the discussion below.

A Ricci tensor of Segré type A1 non-degenerate (\{(1,111)\} in Segré notation) has a pseudo-orthonormal tetrad of eigenvectors, \{u^a, v^a_{\alpha}\}_{\alpha=2,3,4} with corresponding eigenvalues \(\rho_1, \rho_\alpha\), no two of which may be equal. (The pseudo-orthonormality conditions are \(g_{ab}v^a_{\alpha}v^b_{\alpha} = -g_{ab}u^a u^b = 1\), no sum over \(\alpha\).) From these we construct the null tetrad

\[
k^a = \frac{(u^a + v^a)}{\sqrt{2}}, \quad n_a = \frac{(u^a - v^a)}{\sqrt{2}}, \quad m^a = \frac{(v^a_2 + iv^a_3)}{\sqrt{2}}, \quad \bar{m}^a = \frac{(v^a_2 - iv^a_3)}{\sqrt{2}}.
\]

Then we can write

\[
R_{ab} = -(\rho_1 + \rho_2)k_(a)n_b + \frac{1}{2}(\rho_2 - \rho_1)(k_a k_b + n_a n_b)
+ (\rho_3 + \rho_4)m_(a)\bar{m}_b + \frac{1}{2}(\rho_3 - \rho_4)(m_a m_b + \bar{m}_a \bar{m}_b).
\]

In this case, the NP components \(\Phi_{00} = \Phi_{22}\) and \(\Phi_{02} \in \mathbb{R}\) must be non-zero, and \(\Phi_{11}\) may also be non-zero; all other terms are necessarily zero. Specializing equations (5) - (10) to this case, we find immediately that \(\Psi_1 = \Psi_3 = 0\). Furthermore, in order to avoid degeneracy among the eigenvalues, we must have \(\{\Psi_0 = \Psi_4, \Psi_2\} \subset \mathbb{R}\). Then the only allowed Petrov types are I and D (cf. §4.4 of Kramer et al [17]). The rest of the table for Class A1 Ricci tensors is deduced by allowing degeneracies among the eigenvalues above. The same form for the Ricci tensor obtains. The results are summarised in Table I.
For a Ricci tensor of class A2, there exists a complex conjugate pair of eigenvectors $z^a_{\pm} = k^a \pm i n^a$ with eigenvalues $\rho_1 \pm i \rho_2, \rho_2 \neq 0$, and a pair of space-like eigenvectors $v_3, v_4$ as above. $k^a, n^a$ are necessarily null, and the normalization $k_a n^a = -1$ may be imposed. Then the Ricci tensor may be written as

$$R_{ab} = -2\rho_1 k(a n_b) + \rho_2 (k_a k_b - n_a n_b) + (\rho_3 + \rho_4) m(a \bar{m}_b) + \frac{1}{2} (\rho_3 - \rho_4) (m_a m_b + \bar{m}_a \bar{m}_b),$$

and the following Table II results. No physical Ricci tensor may have this structure.

For a Ricci tensor of class A3, there exists a double null eigenvector $k^a$ with eigenvalue $\rho_1$ and a pair of spacelike eigenvectors $v_3^a, v_4^a$ as above. Taking $n^a$ to complete a null tetrad in the standard way, the Ricci tensor may be written

$$R_{ab} = -2\rho_1 k(a n_b) + \lambda k_a k_b + (\rho_3 + \rho_4) m(a \bar{m}_b) + \frac{1}{2} (\rho_3 - \rho_4) (m_a m_b + \bar{m}_a \bar{m}_b),$$

where we must have $\lambda \neq 0$, for otherwise $n^a$ would be a fourth independent eigenvector. The results are in Table III.

A class B Ricci tensor has a triple null eigenvector $k^a$ with eigenvalue $\rho_1$ and a unique spacelike eigenvector $v_4^a$ orthogonal to $k^a$. We complete a null tetrad with $n^a$ and $v_3^a$. Then the Ricci tensor may be written

$$R_{ab} = -2\rho_1 k(a n_b) + 2\sigma k(a v_3) + (\rho_1 + \rho_4) m(a \bar{m}_b) + \frac{1}{2} (\rho_1 - \rho_4) (m_a m_b + \bar{m}_a \bar{m}_b),$$

where $\sigma$ must be non-zero. Then Table IV results. There are no physical Ricci tensors of this type.

Several results may be read off Tables I-IV. For instance we have the following theorem.

**Theorem 2.4** If $k^a$ is a double (respectively triple) null eigenvector of $R_{ab}$, then $k^a$ is at least a 2-fold (respectively 3-fold) repeated pnd of the Weyl tensor.

Note that the converse of this result is not implied by the COC. For example, for class A2, the Weyl tensor is type D if and only if (following the results above) $\Psi_0 = \Psi_4 = 0$, so that $k^a$ and $n^a$ are both 2-fold repeated pnd’s. However the Ricci tensor has no null eigenvectors.

The COC is implied by Yang’s equation, but is obviously true for more general space-times. In fact we shall see in section 4 that the condition $\nabla_{[a} R_{b]c} = 0$ imposes quite severe constraints on space-times having certain Segré types.
3 The Initial Value Problem

The Cauchy initial value problem for the Einstein equations of general relativity has received much attention over the last 40 years, from the original work of Lichnerowitz [20] and Choquet-Bruhat [21], to the sharper results of Hughes, Kato and Marsden [22] and the recent work of Choquet-Bruhat and York [23]. Similarly, the initial value problem for the Yang-Mills equations on Minkowski space has been treated by Kerner [24], Eardley and Moncrief [25][26] and Klainerman and Machedon [27]. Both the Einstein and Yang-Mills equations initial value problems have been solved in somewhat restricted situations. For the Einstein equations, short time existence only has been established, except in certain cases. Indeed, in view of the singularity theorems (Hawking and Ellis [28]), it appears that long term existence is not possible in the general case. On the other hand, while long term existence has been established for the Yang-Mills equations, this has only been possible when the gauge group is compact and the base manifold is conformally related to Minkowski space-time (Choquet-Bruhat, Paneitz and Segal [29]). In the case of non-compact gauge group, blow-up can occur (Yang [30]) and it is not known what conditions guarantee long term existence over a general non-conformally flat Lorentz manifold.

We do not expect Yang’s equations to have a long term well-posed initial value problem for a number of reasons. In the first case, they generalize the Einstein vacuum equations, and so the singularity theorems of general relativity will also apply to them. Secondly, when viewed from a gauge-theoretic perspective, the equations lie naturally in the special orthonormal frame bundle of the base manifold, and therefore the gauge group is SO(3,1), which is non-compact. Consequently, we consider only short time existence for these equations.

We assume that the spacetime is the product of $V^3 \times \mathbb{R}$, where $V^3$ is a compact oriented 3-manifold and that the curves $\{p\} \times \mathbb{R}$ are timelike everywhere with respect to $g$, while $V^3 \times \{t\}$ are spacelike everywhere for all $t$. Thus if we denote the unit normal to $V^t$ by $\eta$ then $g^{ab}\eta_a\eta_b = -1$ and $g$ restricted to $V^t$ is positive definite. Endow $M$ with a smooth positive definite background metric $\overline{g}$ and denote the associated Levi-Civita connection by $\nabla$. Let $h$ be $\overline{g}$ restricted to $V_0$. Define the Sobolev spaces $E_s(V^3 \times I)$ to be the space of tensors $\phi$ on $V^3 \times I$ such that
(i) the restriction of \( \phi \) and its derivatives \( \nabla^z \phi \) of any order \(|z| \leq s\) to each \( V_t \) is almost everywhere defined and square integrable in the metric \( h \). Set
\[
\| \phi \|_{H^s(V_t)} \equiv \left( \int_{V_t} \sum_{|z| \leq s} |\nabla^z \phi|^2 \, d\mu(h) \right)^{\frac{1}{2}}.
\]

(ii) the map \( I \to \mathbb{R} \) with \( t \mapsto \| \phi \|_{H^s(V_t)} \) is continuous and bounded, while \( I \to \mathbb{R} \) with \( t \mapsto \| \phi \|_{H^s(V_t)} \) is measurable and essentially bounded.

\( E_s(V^3 \times I) \) endowed with the norm
\[
\| \phi \|_{E_s(V^3 \times I)} \equiv \text{Ess sup}_{t \in I} \| \phi \|_{H^s(V_t)},
\]
is a Banach space. For \( s > \frac{5}{2} \), \( E_s(V^3 \times I) \) has nice embedding and multiplication properties (see Choquet-Bruhat et al \[31\]). Moreover, these are the appropriate spaces for looking at the initial value problem for quasi-linear wave equations, such as the Einstein vacuum and Yang-Mills equations. We shall use these spaces to study the initial value problem for Yang’s equations.

We now find the constraints of Yang’s equations on \( V_0 \). Denote by \( \tilde{g} \) the pullback of \( g \) to \( V_0 \). The second fundamental form \( K \) is a symmetric 2-tensor on \( V_0 \) given by
\[
K_{ab} = \tilde{g}_c^a \tilde{g}_d^b \nabla_c \eta_d.
\]
Since Yang’s equations are third order in \( g_{ab} \), we also require certain 2nd derivatives of \( g_{ab} \) to be prescribed on the initial hypersurface. Introduce the symmetric 2-tensor \( N_{ab} \) on \( V_0 \) which is the pullback of the Ricci tensor of \( g_{ab} \) to \( V_0 \):
\[
N_{cd} \equiv \tilde{g}_a^c \tilde{g}_b^d R_{ab}.
\]

\textbf{Proposition 3.1} The equations (1) when pulled back to \( V_0 \) read:

\[
D_{[c} N_{b]a} = K_{a[b} D^d K_{c]d} - K_{a[b} D_c K^{cd} K
\]
\[
K_{[a} D_{b]a} N_{c]} = D_{[a} D^d K_{b]d} \quad \text{constant} = 3R + K^2 - K_{ab} K^{ab} - 2N_{a}^a.
\]

Here \( K \equiv g^{ab} K_{ab} \) is the mean curvature of the embedding and \( D \) is the Levi-Civita connection and \( 3R \) the scalar curvature associated with \( \tilde{g} \).
Now we state a theorem which establishes short time existence for Yang’s equations.

The details can be found in Guilfoyle [32].

**Theorem 3.2 (Local Existence for the Yang’s Equations)** Let $V^3$ be a compact orientable 3-manifold and $\hat{3}g \in H_4(V^3)$, $K \in H_3(V^3)$, $N \in H_2(V^3)$ be symmetric 2-tensors on $V^3$, with $\hat{3}g$ positive definite. Let $\hat{3}g$, $K$ and $N$ satisfy the constraints (11), (12) and (13). Then there exists $I \subset \mathbb{R}$ and a unique Lorentz metric $\hat{g} \in E_4(V^3 \times I)$ satisfying Yang’s equations with

$$\hat{g}|_{V^3_0} = g, \quad \partial_0 \hat{g}|_{V^3_0} = K \quad \text{and} \quad \text{Ricci}(\hat{g})|_{V^3_0} = N.$$ 

**Proof:**

The proof follows that of the initial value problem for the Yang-Mills and Einstein equations, where the quasi-linear equations in an appropriate gauge are viewed as a perturbation of the corresponding linear systems. Then, by use of energy estimates for the linear system, a mapping on the spaces $E_s(V \times I)$ is shown to be a contraction for small enough interval $I$ (and large enough $s$). Since these are Banach spaces, such a map has a unique fixed point, the solution of the non-linear system.

For the Yang system of equations, a number of extra complications arise. Yang’s equations constitute a third order quasi-linear system of partial differential equations for $g_{ab}$ and so fall outside of the usual (2nd order) wave equation framework used for the initial value problem of general relativity and gauge theory. In order to overcome this difficulty we can separate the connection from the metric and propagate them separately by wave equations, to which we can apply standard techniques. The key to the success of this method is the fact that if the connection and metric are initially compatible, they remain so throughout the evolution. This follows from a geometric identity which dictates the propagation of torsion. The appropriate gauge condition for these equations is a combination of the harmonic co-ordinate condition

$$g^{ce}(\hat{\Gamma}^d_{ce} - \Gamma^d_{ce}) = 0,$$

and a generalized Lorentz gauge for the connection 1-forms $A$

$$\nabla^c A^{(b)}_{c(a)} = 0.$$ 

With this approach, the proof of the initial value problem goes through as in the Einstein case. $\square$
4 The Energy-Momentum Tensor of a YPS

As outlined above, we do not consider replacing Einstein’s equation with Yang’s, but rather consider the latter to be a complementary condition which is to be imposed on space-time. We consider YPS to be worthy of study in their own right, but also feel it is important to investigate the interaction of the two theories. Taking this point of view, we are led naturally to the following question. What are the consequences of Yang’s equations for the space-times most commonly studied in general relativity?

In this section we focus on these consequences for space-times satisfying Einstein’s field equation,

$$R_{ab} - \frac{1}{2} R g_{ab} = 8\pi T_{ab},$$

(14)

with an energy-momentum tensor having one of the following three physically significant forms:

(a) Perfect fluid.

$$T_{ab} = (\mu + p) u_a u_b + p g_{ab}, \quad u_a u^a = -1.$$  

(15)

(b) Electromagnetic field.

$$T_{ab} = F_{ac} F_b^c - \frac{1}{4} F_{cd} F^{cd}, \quad F_{ab} = -F_{ba}.$$  

(16)

(c) Self-interacting Scalar Field.

$$8\pi T_{ab} = \nabla_a \phi \nabla_b \phi - \frac{1}{2} (\nabla_c \phi \nabla^c \phi - V(\phi)) g_{ab}.$$  

(17)

Combining Yang’s equations with Einstein’s leads to

$$\nabla_a T_{b|c} = 0.$$  

(18)

We consider the consequences of this equation for each of the three cases above. The energy-momentum tensor always obeys the conservation equation $\nabla^a T_{ab} = 0$, and so (18) implies $T = g^{ab} T_{ab} = \text{constant}.$

4.1 Perfect Fluid

The condition $T = \text{constant}$ leads to the equation of state

$$p = \frac{1}{3} \mu + c.$$  

(19)
for some constant $c$, and the conservation equations for any perfect fluid read

$$\dot{\mu} + \theta(\mu + p) = 0$$

$$\nabla_a p + \dot{p} u_a + (\mu + p) \dot{u}_a = 0,$$

where a dot indicates covariant differentiation along the fluid flow lines. Then a straightforward calculation gives

$$0 = u^a \nabla_i (\mu + p)(3 u^b \dot{u}_c - \nabla^i u^b).$$

Transvecting with $u^b$ then yields

$$(\mu + p) \dot{u}_a = 0,$$

and so assuming $\mu + p \neq 0$, which we shall do henceforth, we obtain $\dot{u}_a = 0$, so that the fluid flow lines are geodesic. The conservation equations then give

$$\nabla_a \mu = \theta(\mu + p) u_a,$$

so that the spatial gradients of both $\mu$ and $p$ vanish. Furthermore, this allows us to calculate

$$0 = \nabla_i (\mu + p)(\frac{1}{3} \theta g_{a[b} u_{c]} + u_{[b} \nabla^a u_{c]} + \nabla_{[a} u_{b]} u_a).$$

Transvecting with $u^b$ then yields

$$\nabla_c u_a = \frac{1}{3} \theta h_{ac},$$

(20)

where as usual $h_{ab} \equiv g_{ab} + u_a u_b$ is the metric tensor on the 3-spaces orthogonal to $u^a$. Therefore the fluid flow lines are shear-free and twist-free as well as geodesic. It is well known (Krasiński [33], Ellis [34]) that these are necessary and sufficient conditions for a perfect fluid filled space-time to have Robertson-Walker geometry. If $\mu + p = 0$, then $\mu$ and $p$ are both constant, giving $R_{ab} = \text{constant} \times g_{ab}$, an Einstein space. Since (20) along with (19) is also a sufficient condition on (18) to ensure equation (17), we can summarise as follows.

**Theorem 4.1** A perfect fluid space-time $(M, g)$ with $\mu + p \neq 0$ is a YPS if and only if $(M, g)$ is a Robertson-Walker space-time with $p = \frac{1}{3} \mu + c$ for some constant $c$. 

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This theorem may be rephrased in terms of Segré types. The usual interpretation is that a perfect fluid space-time is one for which the Ricci tensor has Segré type \( \{1, (111)\} \).

The energy density \( \mu \) and pressure \( p \) are determined from the time-like eigenvalue \( \rho_1 \) and space-like eigenvalue \( \rho_2 \) by \( \rho_1 = -4\pi(\mu + 3p) \), \( \rho_2 = 4\pi(\mu - p) \). The non-degeneracy condition \( \rho_1 \neq \rho_2 \) is equivalent to \( \mu + p \neq 0 \). In addition, \( \mu \) and \( p \) are usually required to satisfy certain positivity requirements, the weak or dominant energy conditions (Hawking and Ellis [28], §4.3). Clearly the result above does not depend on such conditions, and so may be restated as follows.

**Theorem 4.2** A Segré type \( \{1, (111)\} \) space-time \( (M, g) \) is a YPS if and only if \( (M, g) \) is a Robertson-Walker space-time with constant Ricci scalar.

Comparing with the first table of §3 above, we see that in this case, the COC is quite weak. In fact, since Robertson-Walker space-times are conformally flat, there are no space-times of Petrov type I, II, D or N in this class. The central relation which constrains solutions to be of Robertson-Walker form is (20). From this equation, the Ricci identities yield conformal flatness and 3-spaces of constant curvature. The same occurs if there is a unit spacelike eigenvector \( n^a \) of the Ricci tensor obeying

\[
\nabla_a n_b = \frac{1}{3} (\nabla^c n_c)(g_{ab} - n_a n_b).
\]  

(21)

In this case, the 3-spaces orthogonal to \( n^a \) are time-like, i.e. have Lorentzian signature. Following the steps above, it is easily seen that (21) holds for a Ricci tensor with Segré type \( \{(1,11)1\} \) and \( R = \text{constant} \), with \( n^a \) the spacelike eigenvector with distinct eigenvalue. Thus we have the following counterpart of Theorem 4.2:

**Theorem 4.3** A space-time \( (M, g) \) with Segré type \( \{(1,11)1\} \) is a YPS if and only if \( (M, g) \) has constant Ricci scalar and line element

\[
ds^2 = dz^2 + \frac{A^2(z)}{(1 + \frac{k}{4}(x^2 + y^2 - t^2))^2}(dx^2 + dy^2 - dt^2),
\]

with \( k \) constant.

Finally, we note that the presence of a cosmological constant in Einstein’s equation does not alter any of the results derived above. The only difference is that the constant \( c \) in (18) above is in the general case equal to \( (4\lambda - R)/3 \), where \( \lambda \) is the cosmological constant and \( R \) is the Ricci scalar.
4.2 Electromagnetic Fields

We turn next to the case of a YPS generated by an electromagnetic field. The two cases, where the electromagnetic field is non-null and where it is null will be dealt with separately. We use the NP formalism throughout this section.

4.2.1 Non-null Electromagnetic Fields

A non-null Einstein-Maxwell space-time is known as a *Rainich geometry* and there are two conditions which are necessary and sufficient for space-time to be such. These are the algebraic part,

\[ R_{ab} R^b_c = \frac{1}{4} g_{ac} R_{bd} R^{bd} \neq 0, \tag{22} \]

and the analytic part,

\[ \nabla_{[a} \alpha_{b]} = 0, \quad \alpha_{b} \equiv (R_{cd} R^{cd})^{-1} \epsilon_{bgef} R^{g} h \nabla^{f} R^{he}. \tag{23} \]

The first of these is equivalent to the Segré type of the Ricci tensor being \{1, 1\}(11), while the second follows immediately from Yang’s equation. Equation (22) allows for the existence of a cosmological constant in (14), so that while the trace of the energy-momentum tensor necessarily vanishes, the Ricci scalar need not. However since we are using the original form (14) of Einstein’s equation, we wish to rule out this possibility, and so demand for the moment that \( R = 0 \). We have then

**Theorem 4.4** All Segré type \{1, 1\}(11) YPS with \( R = 0 \) are non-null Einstein-Maxwell space-times.

We can explicitly determine all such space-times. In this case, there exists a null tetrad field for which

\[ T_{ab} = 4 \phi_1 \bar{\phi}_1 \{ k_{(a} n_{b)} + m_{(a} \bar{m}_{b)} \}. \tag{24} \]

\( k^a \) and \( n^a \) are the pnd’s of the electromagnetic field. Thus the only non-vanishing Ricci tensor term is

\[ \Phi_{11} = 8 \pi \phi_1 \bar{\phi}_1 > 0. \]

The field equations are the separated Bianchi identities. From these, we immediately obtain

\[ \kappa = \sigma = \lambda = \nu = \rho = \mu = \pi = \tau = 0, \]
\[ \Psi_0 = \Psi_1 = \Psi_2 = \Psi_3 = \Psi_4 = 0, \]
\[ D\Phi_{11} = \Delta \Phi_{11} = \delta \Phi_{11} = 0, \]
so that space-time is conformally flat (and hence by (2) includes all conformally flat Einstein-Maxwell space-times), \( \Phi_{11} \) is constant and both pnd’s of the electromagnetic field are non-diverging. Hence the space-time lies in Kundt’s class (Kramer et al [17] §27). There is only one such space-time, the conformally flat Bertotti-Robinson solution (Kramer et al [17] §10.3), for which the line element may be written
\[ ds^2 = -2dudr - 2\Phi_{11}r^2du^2 + 2(1 + \Phi_{11}\zeta\bar{\zeta})^{-2}d\zeta d\bar{\zeta}. \] (25)

The coordinates \( x^a = \{u, r, \zeta, \bar{\zeta}\} \) are respectively a label for the surfaces orthogonal to \( k^a \) (\( k_a = \nabla_a u \)), an affine parameter along the integral curves of \( k^a \) and holomorphic coordinates on the 2-spaces of constant curvature given by \( u, r \) constant. In fact (24) is the direct product of two 2-spaces of the same constant curvature, and provides an example of a decomposable space-time as discussed by Thompson [5]. This space-time is static; \( \xi_a = (2\Phi_{11}r^2, 1, 0, 0) \) is a hypersurface-orthogonal timelike Killing vector field.

We can also completely determine all YPS generated, via Einstein’s equation with a cosmological constant, by a non-null electromagnetic field. Here, (14) is replaced by
\[ R_{ab} - \frac{1}{4}Rg_{ab} + \lambda g_{ab} = 8\pi T_{ab}, \]
where \( \lambda \) is the cosmological constant. Then
\[ R = 4\lambda = \text{constant}, \]
and with \( T_{ab} \) as in (24), the only difference for the spin coefficients and curvature tensor is
\[ \Psi_2 = -\frac{R}{12} = -\frac{\lambda}{3}. \]
Again, the field equations may be completely integrated, yielding a type D (in general) space-time which is decomposable into two 2-spaces of constant curvature. The line element may be written as
\[ ds^2 = -2dudr - 2(\Phi_{11} - \frac{\lambda}{2})r^2du^2 + 2(1 + (\Phi_{11} + \frac{\lambda}{2})\zeta\bar{\zeta})^{-2}d\zeta d\bar{\zeta}. \] (26)

The difference between this and the conformally flat (25) lies in the different values of the constant curvature of the two 2-spaces.

We can summarise the results for non-null electromagnetic fields as follows.
Theorem 4.5  All Segré type \{(1,1)(11)\} YPS have line element given by (26) and have $R = 4\lambda$. The space-time is generated, via Einstein’s field equations with cosmological term $\lambda$, by a non-null electromagnetic field.

As with any Rainich geometry, the electromagnetic field is only determined up to a constant duality rotation, $\phi_1 \rightarrow e^{i\alpha}\phi_1$, $\alpha$ constant. (26) may be generated by an electrostatic, magnetostatic or general static electromagnetic field.

4.2.2 Null Electromagnetic Fields and Pure Radiation

By definition, an energy-momentum tensor which is one of these types has the form

$$T_{ab} = Hk_ak_b,$$

for some null vector field $k^a$ and function $H$. Then on any null tetrad based on $k^a$, we have from Einstein’s equation $\Phi_{22} = 8\pi H$, and all other Ricci tensor terms vanish. (In the presence of a cosmological term, $R = \text{constant}$ may also be non-zero.) Equivalently, the Ricci tensor has Segré type \{(2,11)\} with vanishing Ricci scalar.

From the results of the section 2, we see that the Weyl tensor must be algebraically special with repeated pnd $k^a$, which by the Goldberg-Sachs theorem must be shear-free and geodesic. The only other consequence of the COC is that $\Psi_2 = \bar{\Psi}_2$ for any null tetrad preserving the direction of $k^a$. With $\kappa = \sigma = 0$, Lorentz transformations of the null tetrad may be used to set $\epsilon = \mu - \bar{\mu} = 0$ and $\tau = \bar{\tau} = \bar{\alpha} + \beta$. Then the only field equations (Bianchi identities with Weyl tensor terms ignored) which are not identically satisfied are

$$\delta\Phi_{22} = -\tau\Phi_{22}, \quad D\Phi_{22} = 0 = \bar{\rho}\Phi_{22},$$

and so $\rho = 0$. Thus $k^a$ is non-diverging, and the space-time lies in Kundt’s class (Kramer et al [17] §27). For the case of a null electromagnetic field, $\phi_2$ (the only non-zero electromagnetic field tensor term) must satisfy the relevant Maxwell equations. These results also follow when the cosmological constant is non-zero. Thus we have the following.

Theorem 4.6  A YPS generated by a pure radiation energy-momentum tensor or a null electromagnetic field, or equivalently one with a Ricci tensor of Segré type \{(2,11)\}, lies in Kundt’s class. The non-diverging geodesic repeated pnd is the double null eigenvector of the Ricci tensor, and in a null tetrad adapted to this vector, $\Psi_2 = \bar{\Psi}_2$. 

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The converse of this result (“Kundt’s class with null electromagnetic field or pure radiation energy-momentum tensor is a YPS”) is not true, as Yang’s equation gives an ‘extra’ Bianchi identity arising from the splitting of the identities into homogeneous equation for the Ricci and Weyl tensors. Modulo the implications of this extra equation, the results of §27.6 of Kramer et al [17] apply to this class of YPS. It may be possible to use this extra equation to obtain further results on these solutions. This is currently being investigated.

4.3 Self-interacting Scalar Fields

The energy momentum tensor for a self-interacting scalar field $\phi$ with interaction potential $V(\phi)$ is given by

$$8\pi T_{ab} = \phi_a \phi_b - g_{ab} (\tfrac{1}{2} \phi_c \phi^c - V(\phi)), \quad (27)$$

where $\phi_a \equiv \nabla_a \phi$ and for convenience, the gravitational constant has been absorbed into the definition of $\phi$ and $V$. The governing equation for $\phi$ is equivalent to the vanishing divergence of (27):

$$\Box \phi + V'(\phi) = 0. \quad (28)$$

Then Einstein’s field equation (14) gives

$$R_{ab} = \phi_a \phi_b - V g_{ab}, \quad (29)$$

and hence

$$\phi_c \phi^c = R + 4V. \quad (30)$$

Yang’s equations imply that $R$ is constant.

If $\phi_c \phi^c = 0$ over some open subset of space-time, then we see from (30) that $V = -R/4$ is constant, and consequently the Ricci tensor has Segre type $(2,11)$, as $\phi_a$ is null. This situation was dealt with in the previous subsection, and so we assume henceforth that $\phi_c \phi^c$ is non-zero and we can therefore restrict our attention to open subsets of space-time on which the sign of $\phi_a \phi^a$ does not change. We thus note immediately that Theorem 4.2 and Theorem 4.3 apply in this case; for $\phi_c \phi^c < 0$, the Segre type is $(1,11)$, while for $\phi_c \phi^c > 0$, the Segre type is $(1,111)$. We now proceed to see how these geometries arise.
Following the steps of §4.1, we find that the covariant derivative of $\phi_a$ is given by

$$\nabla_a \phi_c = 3(\phi_b \phi^b)^{-1}V'\phi_a \phi_c - V'g_{ac}. \quad (31)$$

This equation is equivalent to (18) for an energy-momentum tensor of the form (27). The unit vector field normal to the surfaces $\Sigma_\phi$ of constant $\phi$ is

$$n^a = (\pm \phi_c \phi^c)^{-1/2} \phi^a,$$

where here and throughout, the upper sign corresponds to $\phi_c \phi^c > 0$ ($\Sigma_\phi$ time-like), and the lower sign to $\phi_c \phi^c < 0$ ($\Sigma_\phi$ space-like). We find that (31) leads to

$$\nabla_a n_b = -V' (\pm \phi_c \phi^c)^{-1/2} h_{ab}, \quad (32)$$

where $h_{ab} \equiv g_{ab} \mp n_an_b$ is the metric tensor of $\Sigma_\phi$. Using (31) and (32), an explicit expression may be obtained for the second covariant derivative of $n^a$. Then the Ricci identities may be used to prove that space-time is conformally flat and that $\Sigma_\phi$ have constant curvature. In addition, we find that $V$ must obey

$$(R + 4V)V'' - 3(V')^2 = \frac{1}{3}(R + 3V)(R + 4V). \quad (33)$$

Equation (32) allows us to introduce 'co-moving coordinates' (the case $\phi_c \phi^c$ may be referred to as a tachyon fluid) such that

$$n_a = \pm \nabla_a u, \quad u = x^0.$$ 

Surfaces of constant $u$ are surfaces of constant $\phi$, and so $\phi = \phi(u)$, $V = V(u)$. The possible line elements are

$$ds^2 = \pm du^2 + A^2(u) \left(1 + \frac{k}{4}(x^2 + y^2 + z^2)\right)^{-2} \left(dx^2 + dy^2 + dz^2\right), \quad (34)$$

and $k$ may be normalized to -1, 0 or +1. The 3-spaces $\Sigma_\phi$ are Lorentzian for $\phi_c \phi^c > 0$, and Riemannian for $\phi_c \phi^c < 0$.

Imposing the condition $R = \text{constant}$ on (34) yields a differential equation for $A(u)$ which may be integrated to give

$$A^2(u) = -6kR^{-1} + a_0 \exp \left(\pm \frac{R}{3} u\right) + a_1 \exp \left(-\sqrt{\frac{R}{3}} u\right), \quad (R \neq 0) \quad (35)$$

$$A^2(u) = \pm ku^2 + a_0 u + a_1, \quad (R = 0). \quad (36)$$
In (36) a coordinate transformation of the form \((u \rightarrow u + \text{constant})\) has been used to set a constant of integration to zero. (34) along with (33) with the lower sign gives the possible line elements for a YPS with a perfect fluid energy-momentum tensor.

The scalar field \(\phi\) and potential \(V\) may be determined as follows. Using a dot to indicate differentiation with respect to \(u\), we have

\[
\phi_a = \pm \dot{\phi} n_a,
\]

and so using (31),

\[
V'(\phi) = \pm \frac{1}{2} \ddot{\phi}.
\]

In the coordinates of (34), we find

\[
\Box \phi = \pm (\ddot{\phi} + 3A^{-1} \dot{A} \dot{\phi}),
\]

and so (28) gives

\[
\ddot{\phi} + 2A^{-1} \dot{A} \dot{\phi} = 0,
\]

which has the first integral

\[
\dot{\phi} = aA^{-2}(u),
\]

where \(a\) is a constant. Thus by (31),

\[
V = \pm \frac{a^2}{4} A^{-4} - \frac{R}{4}.
\]

Then evaluating the terms in (33), we find that \(A\) must satisfy

\[
\ddot{A} = -\frac{1}{4} a^2 A^{-3} \pm \frac{R}{12} A.
\]

We compare this equation with (35) to determine \(a\).

For \(R = 0\), we find that \(a = a_0\). (37) may be integrated and we find

\[
\phi = \ln \left| \frac{u}{\pm ku + a_0} \right|, \quad V = \pm \frac{a_0^2}{4} (\pm ku^2 + a_0u)^{-2}.
\]

For \(R \neq 0\), comparison of (38) and (35) yields

\[
a^2 = \pm 12R^{-1} \mp \frac{4}{3} a_0 a_1 R.
\]

\(\phi\) is determined via (37) and (35) by an elliptic integral.

Summarising the main results, we have the following.
Theorem 4.7 A YPS generated by a self-interacting scalar field $\phi$ obeying $\nabla_a \phi \nabla^a \phi \neq 0$ has line element

$$ds^2 = \epsilon du^2 + A^2(u)(1 + \frac{k}{4}(x^2 + y^2 - \epsilon z^2))^{-2}(dx^2 + dy^2 - \epsilon dz^2),$$

where $\epsilon = \text{sgn}(\nabla_a \phi \nabla^a \phi)$ and $A^2(u)$ is given by (35).

5 Conclusions

Perhaps the most important result reported here is that the short-time initial value problem for Yang’s equations is well-posed. This is a prerequisite for YPS to be worthy of study as physical models, and has not been demonstrated before [32]. Other authors have emphasised their criticisms of Yang’s equations as the fundamental gravitational field equations [3], [35], [5]. This has been done principally on the basis that Birkhoff’s theorem does not apply to YPS; source-free ($\nabla_a R_{bc} = 0$) spherically symmetric solutions are not necessarily static, and indeed the static spherical source-free solutions form a four parameter family, rather than the one parameter (Schwarzschild mass) family of general relativity. Consequently, one can easily produce ‘vacuum’ spherically symmetric solutions, which are candidates for the gravitational field of the sun, but which display unphysical characteristics - lack of gravitational red-shift, lack of bending of starlight, and incorrect values (and direction!) for the perihelion shift.

We have attempted here to establish an alternative philosophy for Yang’s equations: they are to be used in conjunction with Einstein’s equation and/or appropriate boundary conditions in our description of space-time. In this way, well established results of relativistic astrophysics and cosmology may be maintained. Our hope is that a study of these equations may shed further light on the classical gauge theoretic structure of gravity and in turn classical gauge theory in general. For example the link between a symmetry of a YPS as a gauge configuration and as a space-time may yield insight into the question of how the former is to be defined [35]. This work is to be undertaken in the future; we are currently investigating the structure of static YPS. Details on the short-time initial value problem will appear elsewhere.

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Yang’s Gravitational Theory

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Table I: Class A1 Ricci Tensor

| Segré Notation | Eigenvectors | Weyl Scalars | Allowed Petrov Types | Physical Interpretation |
|----------------|--------------|--------------|----------------------|-------------------------|
| {1,111}        | \{u, v_2 v_3 v_4\} | Ψ_1 = Ψ_3 = 0, \{Ψ_0 = Ψ_4, Ψ_2 \} ⊂ \mathbb{R} | I or D                |                         |
| {(1,1)11}      | \{(u, v_2) v_3 v_4\} | Ψ_1 = Ψ_3 = 0, \{Ψ_0, Ψ_4, Ψ_2 \} ⊂ \mathbb{R} | I II D or N            |                         |
| {1,1(11)}      | \{u, v_2 (v_3 v_4)\} | Ψ_1 = Ψ_3 = 0, \Ψ_0 = Ψ_4, Ψ_2 \in \mathbb{R} | I or D                |                         |
| {(1,1)(11)}    | \{(u, v_2)(v_3 v_4)\} | Ψ_1 = Ψ_3 = 0, \Ψ_2 \in \mathbb{R} | I II D or N            | Non-null em field.      |
| {1,(111)}      | \{u, (v_2 v_3 v_4)\} | Ψ_3 = −Ψ_1, Ψ_4 = Ψ_0, Ψ_2 \in \mathbb{R} | I II D or N            | Perfect fluid: scalar field. |
| \{ (1,11)1\}  | \{(u, v_2 v_3) v_4\} | Ψ_A \in \mathbb{R}, A = 0 - 4. | I II D III or N | Scalar field.            |
Table II: CLASS A2 Ricci Tensor

| Segré Notation | Eigenvectors | Weyl Scalars | Allowed Petrov Types |
|----------------|--------------|--------------|---------------------|
| \{z\bar{z}, 11\} | \{z_+z_-, v_3v_4\} | \begin{align*} \Psi_1 &= \Psi_3 = 0 \\
\{\Psi_4 = -\Psi_0, \Psi_2\} &\subseteq \mathbb{R}\end{align*} | I or D |
| \{z\bar{z}, (11)\} | \{z_+z_-, (v_3v_4)\} | \begin{align*} \Psi_1 &= \Psi_3 = 0 \\
\{\Psi_4 = -\Psi_0, \Psi_2\} &\subseteq \mathbb{R}\end{align*} | I or D |
Table III CLASS A3 Ricci Tensor

| Segré Notation | Eigenvectors | Weyl Scalars | Allowed Petrov Types | Physical Interpretation. |
|----------------|-------------|--------------|---------------------|-------------------------|
| \{2,11\}      | \{k, v_3 v_4\} | \begin{align} \Psi_0 &= \Psi_1 = \Psi_3 = 0, \\
                      & \{\Psi_2, \Psi_4\} \subset \mathbb{R} \end{align} | II D or N            |                         |
| \{2,(11)\}    | \{k, (v_3 v_4)\} | \begin{align} \Psi_0 &= \Psi_1 = \Psi_3 = 0, \\
                      & \Psi_2 \in \mathbb{R} \end{align} | II D or N            |                         |
| \{(2,1)1\}    | \{(k, v_3) v_4\} | \begin{align} \Psi_0 &= \Psi_1 = 0, \\
                      & \{\Psi_2, \Psi_3, \Psi_4\} \subset \mathbb{R} \end{align} | II D III or N        |                         |
| \{(2,11)\}    | \{(k, v_3 v_4)\} | \begin{align} \Psi_0 &= \Psi_1 = 0, \\
                      & \Psi_2 \in \mathbb{R} \end{align} | II D III or N        | Null em field, pure radiation. |
Table IV: CLASS B Ricci Tensor

| Segré Notation | Eigenvectors | Weyl Scalars | Allowed Petrov Types |
|----------------|--------------|--------------|----------------------|
| \{3,1\}       | \{k, v_4\}  | \Psi_0 = \Psi_1 = \Psi_2 = 0, \{\Psi_3, \Psi_4\} \subset \mathbb{R} | III or N             |
| \{(3,1)\}     | \{(k, v_4)\} | \Psi_0 = \Psi_1 = \Psi_2 = 0, \Psi_3 \in \mathbb{R} | III or N             |