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Abstract

**Introduction:** Neuromuscular fatigue reduces the temporal structure, or complexity, of muscle torque output, purportedly through an effect on motor unit behaviour. Ischaemic pre-conditioning (IPC), an emerging ergogenic aid, has been demonstrated to have a potent effect on muscular output and endurance. We therefore tested the hypothesis that IPC would attenuate the fatigue-induced loss of muscle torque complexity. **Methods:** Ten healthy participants (6 male/4 female) performed intermittent isometric knee extension contractions (6 s contraction, 4 s rest) to task failure at 40% maximal voluntary contraction (MVC). Contractions were preceded by either IPC (three bouts of 5 minutes proximal thigh occlusion at 225 mmHg, interspersed with 5 minutes rest) or SHAM (as IPC, but occlusion at only 20 mmHg) treatments. Torque and EMG signals were sampled continuously. Complexity and fractal scaling were quantified using approximate entropy (ApEn) and the detrended fluctuation analysis (DFA) $\alpha$ scaling exponent. Muscle oxygen consumption ($\text{m}\cdot\text{VO}_2$) was determined using near-infrared spectroscopy. **Results:** IPC increased time to task failure by $43 \pm 13\%$ (mean $\pm$ SEM, $P = 0.047$). Complexity decreased in both trials (decreased ApEn, increased DFA $\alpha$; both $P < 0.001$), though the rate of decrease was significantly lower following IPC (ApEn, $-0.2 \pm 0.1$ vs. $-0.4 \pm 0.1$, $P = 0.013$; DFA $\alpha$, $0.2 \pm 0.1$ vs. $0.3 \pm 0.1$, $P = 0.037$). Similarly, the rates of increase in EMG amplitude ($P = 0.022$) and $\text{m}\cdot\text{VO}_2$ ($P = 0.043$) were significantly slower following IPC. **Conclusion:** These results suggest the ergogenic effect of IPC observed here is of neural origin and accounts for the slowing of the rates of change in torque complexity, EMG amplitude and muscle oxygen consumption as fatigue develops.

**Key words:** Exercise, ergogenic aids, muscular endurance, non-linear dynamics, muscle activity.
Introduction

The optimal pattern of force (or torque) production is often presumed to be one that is smooth and accurate, relative to the task demands. However, even in health muscular output fluctuates in a seemingly random fashion around the required target (1), with perturbations such as neuromuscular fatigue (2) and ageing (3) exacerbating these fluctuations. It was long thought that such fluctuations were unwanted system noise or a reflection of underlying pathology (4), though it is now being increasingly recognised that they may provide significant insight into motor control (5, 6). Over the past 20 years, it has become evident that the fluctuations in muscle torque output are not simply random noise; rather, they possess a statistically irregular temporal structure, or “complexity” (1). Measures of complexity quantify the degree of signal regularity (e.g. approximate entropy, ApEn; 7) and identify the presence of long-range fractal correlations (e.g. detrended fluctuation analysis, DFA; 8). The presence of complexity in muscular output is thought to reflect the adaptability of the neuromuscular system and the ability to modulate motor output rapidly and accurately in response to task demands (5).

Any loss of complexity in muscle torque output is indicative of neuromuscular system dysfunction, and reflects a decrement in motor control which could have important implications for task performance (5, 9). A loss of muscle torque complexity has been repeatedly observed with neuromuscular fatigue, occurring during both maximal and submaximal intermittent isometric contractions (6, 9, 10, 11). Although the mechanism(s) underpinning this loss of complexity is unclear, we recently showed that caffeine ingestion delays task failure and slows the fatigue-induced loss of muscle torque complexity, concomitant to attenuation of the loss of maximum
torque generating capacity and the development of central fatigue (12). Indeed, the loss of muscle torque complexity appears to be tightly coupled to the fatigue process, with complexity declining in tandem with the loss of torque generating capacity (12) and increase in muscle oxygen consumption (mVO2; 11). Interventions that delay task failure and slow the neuromuscular fatigue process should, therefore, be associated with an attenuated loss of muscle torque complexity (12). Moreover, such interventions should also provide further insight into the mechanistic basis of the fatigue-induced loss of complexity.

Ischaemic pre-conditioning (IPC) is a non-invasive technique, originally conceived as a cardioprotective intervention, that consists of repeated cycles of brief ischaemia followed by reperfusion (13). Since its first use in a sporting context as an ergogenic aid (14), IPC has been demonstrated to improve endurance in a variety of exercise modalities (15, 16), including isometric contractions (17, 18). Nevertheless, the mechanisms by which IPC exerts this ergogenic effect are complex and remain to be fully elucidated. Early findings suggested that IPC could serve to maintain oxygen supply and energy substrates to muscle, potentially through an effect on vascular or endothelial function (13, 14). However, recent research, both of a clinical (19) and sporting (20) nature, has suggested that neural mechanisms mediate the beneficial effects of IPC.

IPC has multiple positive effects on motor output, including increasing maximal force generation (21) and delaying task failure and neuromuscular fatigue (17, 18). These results suggest that neural adjustments may, in part, account for the effect of IPC on exercise tolerance (22). Studies in anaesthetised and electrically stimulated cats (23) and exercising humans (22, 24) have demonstrated that IPC results in greater electromyographic (EMG) activity and increased motor
unit recruitment during maximal contractions, and a decreased motor unit recruitment threshold during submaximal contractions (22). These findings are consistent with increased excitability of the motoneuron pool (25). We have previously argued that the fatigue-induced loss of muscle torque complexity must be related to factors directly affecting the motor unit pool (6) and, indeed, our previous data suggest that caffeine’s ergogenic effect on muscle torque complexity was mediated by a greater ability to excite the motor unit pool in the face of developing fatigue (12).

IPC has been hypothesised to exert its ergogenic effect centrally through stimulation of metabolite-sensitive group III and IV muscle afferents, which in turn engage brainstem centres to release excitatory neuromodulators, such as serotonin and noradrenaline (13, 26). An IPC-mediated increase in motoneuron excitability during fatiguing submaximal contractions should maintain central drive to the motoneuron pool (i.e. reduce the rate of central fatigue development). This, in turn, should delay the reduction in force generating capacity, and delay the consequent rise in EMG amplitude characteristic of neuromuscular fatigue (27). If changes in muscle torque complexity are directly related to motor unit recruitment and discharge adjustments in response to fatigue, then IPC should also slow the fatigue-induced loss of torque complexity (12). The purpose of the present study was, therefore, to investigate the effect of IPC on muscle torque complexity during subsequent fatiguing isometric contractions. We hypothesized that IPC would increase time to task failure and attenuate the rate of the fatigue-induced reduction in muscle torque complexity, quantified by a slower rate of decrease in ApEn and a slower rate of increase in the DFA α scaling exponent.
Materials and Methods

Participants

Ten healthy participants (6 male, 4 female; mean ± SD: age 25.9 ± 6.7 years; height 1.72 ± 0.10 m; weight 69.3 ± 12.7 kg) provided written informed consent to participate in the study, which was approved by the ethics committee of the University of Kent, and which adhered to the Declaration of Helsinki. Participants were instructed to arrive at the laboratory in a rested state (having performed no strenuous exercise in the preceding 24 hours) and to have consumed neither any food nor any caffeinated beverages in the 3 hours before arrival. Participants attended the laboratory at the same time of day (± 2 hours) during each visit.

Experimental design

Participants were required to visit the laboratory on three occasions over a 2-3 week period, with a minimum of 72 hours separating each visit. During their first visit, participants were familiarized with all testing equipment and procedures, and the settings for the dynamometer and femoral nerve stimulation were recorded. During the next two visits, participants performed, in a randomized order, a series of intermittent isometric knee extension contractions to task failure preceded by either ischaemic pre-conditioning (IPC) or a sham treatment (SHAM). To minimize any placebo effect or bias, participants were told that the purpose of the study was to compare the impact of two different cuff pressures, both of which could potentially alter performance (21). In each trial, torque output was sampled continuously to allow the quantification of complexity, muscle activity was measured using the vastus lateralis electromyogram (EMG), muscle oxygen consumption (m\(\ddot{V}O_2\)) was measured using near-infrared spectroscopy (NIRS) and maximal voluntary
contractions (MVCs) with supramaximal femoral nerve stimulation were used to quantify global, central and peripheral fatigue.

**Dynamometry**

During all visits, participants were seated in the chair of a Cybex isokinetic dynamometer (HUMAC Norm; CSMi, Massachusetts USA), initialized and calibrated according to the manufacturer’s instructions. Participants sat with relative hip and knee angles of 85° and 90°, respectively, with full extension being 0°. Their right leg was attached to the lever arm of the dynamometer and the seating position adjusted to ensure that the lateral epicondyle of the femur was in line with the axis of rotation of the lever arm. The lower leg was securely attached to the lever arm above the malleoli with a padded Velcro strap. Straps secured firmly across the waist and shoulders prevented any extraneous movement and the use of the hip extensors during the isometric contractions. The seating position was recorded during the familiarization and replicated during each subsequent visit.

**Electromyography**

The EMG of the vastus lateralis was sampled using Ag/AgCl electrodes (32 x 32 mm; Nessler Medizintechnik, Innsbruck, Austria). Prior to attachment of the electrodes, the skin of the participants was shaved, abraded and cleaned with an alcohol swab over the belly of the muscle, in order to reduce impedance. The electrodes were placed on the prepared skin over the belly of the muscle, parallel to the alignment of the muscle fibres. A reference electrode was placed on prepared skin medial to the tibial tuberosity. Care was taken to ensure that the electrode locations were identical between sessions. The raw EMG signals were sampled at 1 kHz, amplified (gain
1000; Biopac MP150; Biopac Systems Inc., California, USA) and band-pass filtered (10-500 Hz; Biopac MP150; Biopac Systems Inc., California, USA).

**Femoral nerve stimulation**

Electrical stimulation of the femoral nerve was used to assess neuromuscular fatigue processes, as described previously by Pethick et al. (6). The anode, a carbon rubber electrode with adhesive gel (100 x 50 mm; Phoenix Healthcare Products Ltd., Nottingham, UK), was placed lateral to the ischial tuberosity, on the posterior aspect of the leg. The position of the cathode was located using a motor point pen (Compex; DJO Global, Guildford, UK), and based on the location in the femoral triangle giving the largest twitch and greatest peak-to-peak amplitude of the compound muscle action potential (M-wave) following single stimulation at 100 mA, using a constant-current, variable voltage stimulator (Digitimer DS7AH, Welwyn Garden City, UK). Following determination of the precise cathode location, an Ag/AgCl electrode (32 x 32 mm; Nessler Medizintechnik) was placed over that point.

The appropriate stimulator current was then established by incrementally increasing the current, in steps of 20 mA, until knee extensor torque and the M-wave response to single twitches had plateaued. This was verified with stimulation delivered during a contraction at 50% MVC to ensure that a maximal M-wave was also evident during an isometric contraction. The stimulator current was then increased to 130% of the current producing a maximal M-wave. In all subsequent trials, doublet stimulation (two 200 𝜇s pulses with 10 ms interpulse interval) was used.
**Near-infrared spectroscopy**

Muscle oxygen consumption (m\(\dot{\text{VO}}_2\)) of the vastus lateralis was obtained, as described in Pethick et al. (11), using a continuous-wave NIRS device (Oxymon Mk III; Artinis Medical Systems, Netherlands), calibrated according to the manufacturer’s instructions before each trial. The NIRS device generated light at three wavelengths (905, 850 and 770 nm) corresponding to the absorption wavelengths of oxyhaemoglobin (O\(_2\)Hb) and deoxyhaemoglobin (HHb). An area at the level of the largest circumference of the vastus lateralis was shaved, abraded and cleaned with an alcohol swab. The NIRS optode was then placed at this location and secured with Velcro straps and biadhesive tape, such that the optode could not move during contractions. A 13 cm wide blood pressure cuff (Hokanson E20 cuff inflator; D.E. Hokanson Inc., Bellevue, USA) was placed proximal to the NIRS optode, at the top of the thigh, and was used to maintain blood volume under the optode during measurement. NIRS data were collected at 10 Hz. An ischaemic calibration (performed at the end of each visit) eliminated any effect of adipose tissue thickness and scaled the NIRS signals according to the maximal physiological range (28).

**Protocol**

All visits followed a pattern of data acquisition similar to that which we have previously reported (6). Each visit began with the instrumentation of the participants and the establishment of the correct dynamometer seating position and supramaximal stimulation response. Participants then performed a series of brief (3 second) MVCs to establish their maximum torque. These contractions were separated by a minimum of 60 seconds rest, and continued until the peak torques in three consecutive contractions were within 5% of each other. Participants were given a countdown, followed by very strong verbal encouragement to maximize torque. The first MVC
was used to establish the fresh (i.e. non-exercised) maximal EMG signal, against which the subsequent EMG signals were normalized (Data analysis; see below). The second and third MVCs were performed with femoral nerve stimulation delivered during the contraction and at rest after the contraction. The stimulation during the contraction was delivered during a plateau in maximal torque, in order to test the maximality of the contractions and provide the fresh voluntary activation; while the stimulation at rest was delivered two seconds after the contraction, in order to establish the fresh potentiated doublet torque. All subsequent contractions with femoral nerve stimulation were conducted in this manner. Participants then rested for 10 minutes before undergoing either IPC or SHAM.

The IPC and SHAM protocols were performed by means of rapid inflation of the blood pressure cuff, already positioned for the NIRS measurements, at the top of the thigh. In the IPC condition, the cuff was inflated to 225 Hg for three periods of 5 minutes, interspersed with 5 minute periods of rest/reperfusion; while in the SHAM condition, the cuff was inflated to only 20 mmHg for three periods of 5 minutes, interspersed with 5 minute periods of rest/reperfusion (21, 29). Following completion of the IPC and SHAM protocols, participants rested for 20 minutes (29). They then performed an MVC, accompanied by femoral nerve stimulation, immediately prior to commencing the fatigue test.

Participants performed intermittent isometric knee extension contractions at 40% MVC. The target torque was based on the highest instantaneous torque recorded during the pre-test MVCs in the first experimental visit. The duty cycle for the contractions was 60%; with contractions held for 6 seconds and being followed by 4 seconds rest. Participants were instructed to match their
instantaneous torque with a target bar superimposed on the display in front of them and were required to continue matching this torque for as much of the 6 second contraction as possible. The contractions continued until task failure; defined as the point at which the participants failed to reach the target torque on three consecutive contractions, despite strong verbal encouragement. Participants were not informed of the elapsed time during the trials, but were informed of each “missed” contraction. At task failure, participants were instructed to immediately produce an MVC, which was accompanied by femoral nerve stimulation.

As in Pethick et al. (11), at the end of each minute of contractions (i.e. after every fifth contraction), ṁVO₂ was assessed based on the decrease in muscle oxygenation which accompanies an arterial occlusion (28). The blood pressure cuff was rapidly inflated to 300 mmHg for 5 seconds using a Hokanson AG101 (D.E. Hokanson Inc., Bellevue, USA), with ṁVO₂ calculated using linear regression over the course of this occlusion. This measure of ṁVO₂ was performed instead of a targeted contraction. ṁVO₂ was also assessed immediately prior to the MVC performed at task failure. Five minutes after task failure, an ischaemia/hyperaemia calibration was performed to normalize the NIRS signals. The blood pressure cuff was inflated to 300 mmHg for 5 minutes, with a plateau in the HHb signal being visually confirmed (28). This functionally, though not completely, deoxygenated the tissue under the optode (defined as 0% oxygenation), while the peak hyperaemic response upon release of the cuff was assigned a value of 100% oxygenation.

Data acquisition and participant interface

Data acquisition was performed in a similar manner as described in Pethick et al. (11). The isokinetic dynamometer, stimulator and EMG were connected via BNC cables to a Biopac MP150
(Biopac Systems Inc., USA) and a CED Micro 1401-3 (Cambridge Electronic Design, Cambridge, UK) interfaced with a personal computer. These data were sampled at 1 kHz and collected in Spike2 (Version 7; Cambridge Electronic Design, UK). The NIRS data were sampled at 10 Hz and collected in Oxysoft (Artinis Medical Systems, Netherlands).

A chart containing the instantaneous torque was projected onto a screen placed ~1 m in front of the participant. A scale consisting of a thin line (1 mm thick) was superimposed on the torque chart and acted as a target, so that participants were able to match their instantaneous torque output to the target torque during each visit.

Data analysis
All data were analyzed using code written in MATLAB R2017a (The MathWorks, Massachusetts, USA). The data analysis focused on four specific areas: 1) basic measures of torque and EMG; 2) measures of central and peripheral fatigue; 3) the variability and complexity of torque output; and 4) measures of muscle oxygen consumption (mVO$_2$).

Torque and EMG: The mean and peak torque for each contraction in both trials were determined. The mean torque was calculated based on the steadiest five seconds of each contraction, with MATLAB code identifying the five seconds of each contraction with the lowest standard deviation. The point of task failure was determined as in Pethick et al. (6). The mean torque produced during the first five contractions was calculated, with task failure deemed to occur when the mean torque recorded during three consecutive contractions was more than 5 N·m below the mean torque of the first five contractions, with the first of these contractions being considered the point of task failure.
The EMG output from the vastus lateralis for each contraction was full-wave rectified during each five second window. The average rectified EMG (arEMG) was then calculated and normalized by expressing the arEMG as a fraction of the mean arEMG obtained during a 3 s MVC from the fresh muscle performed at the beginning of the trial.

*Central and peripheral fatigue:* Measures of central and peripheral fatigue were calculated based on the stimuli delivered during and after the MVCs performed pre-test and at task end/failure. Peripheral fatigue was evidenced by a fall in the potentiated doublet torque. Central fatigue was evidenced by a decline in voluntary activation, quantified using the twitch interpolation technique (30):

\[
\text{voluntary activation (\%)} = 1 - \left( \frac{\text{superimposed doublet}}{\text{resting doublet}} \right) \times 100 \quad [1]
\]

where the superimposed doublet was that measured during the contraction of interest and the potentiated doublet was measured at rest two seconds after that contraction.

*Variability and complexity:* All measures of variability and complexity were calculated using the steadiest five seconds of each contraction, identified by MATLAB as the five seconds containing the lowest standard deviation (SD). The amount of variability in the torque output of each contraction was measured using the SD, which provides a measure of the absolute amount of variability in a time-series, and coefficient of variation (CV), which provides a measure of the amount of variability in a time-series normalized to the mean of the time-series.
The temporal structure, or complexity, of torque output was examined using multiple time domain analyses, as recommended by Goldberger et al. (4). The regularity of torque output was determined using approximate entropy (ApEn; 7) and the temporal fractal scaling of torque was estimated using the detrended fluctuation analysis (DFA; 8) $\alpha$ scaling exponent. The calculations of ApEn and DFA are detailed in Pethick et al. (6). In brief, ApEn was calculated with the template length, $m$, set at 2 and the tolerance, $r$, set at 10% of the SD of torque output, and DFA was calculated across time scales (57 boxes ranging from 1250 to 4 data points). In one participant in both the IPC and SHAM conditions, a significant degree of crossover was identified in the log-log plot of fluctuation size versus box size (as shown by an $r < 0.95$). To account for this effect, a least squares linear regression was used to fit two lines to the plot, and two $\alpha$ exponents were quantified. The second of these ($\alpha_2$, representing longer, physiologic timescales) was used in the DFA $\alpha$ exponent analysis (11).

*Muscle oxygen consumption:* $\text{mVVO}_2$ was determined as described in Ryan et al. (28). $\text{mVVO}_2$ was calculated as the slope of the change in $\text{O}_2\text{Hb}$ and $\text{HHb}$ during arterial occlusion using simple linear regression. The $\text{mVVO}_2$ measurements were based on the 5 second arterial occlusions (50 data points) at the end of each minute of exercise.

The NIRS data were corrected for blood volume changes as described in Ryan et al. (28), using custom-written MATLAB code. A blood volume correction factor ($\beta$) was calculated for each data point during the arterial occlusions:

$$\beta(t) = \frac{|\text{O}_2\text{Hb}(t)|}{(|\text{O}_2\text{Hb}(t)| + |\text{HHb}(t)|)}$$  \[2\]
where $\beta$ is the blood volume correction factor, $t$ is time, $O_2\text{Hb}$ is the oxygenated haemoglobin/myoglobin signal, and $HHb$ is the deoxygenated haemoglobin/myoglobin signal. Each data point was corrected using its corresponding $\beta$ according to Eqs. 3 and 4, below.

\[ O_{2\text{Hb}}(t) = O_{2\text{Hb}}(t) - [t\text{Hb}(t) \times (1 - \beta)] \]  \hspace{1cm} [3]
\[ HHb_c(t) = HHb(t) - [t\text{Hb}(t) \times \beta] \]  \hspace{1cm} [4]

where $O_{2\text{Hb}}_c$ and $HHb_c$ are the corrected oxygenated and deoxygenated haemoglobin/myoglobin signals, respectively; $t\text{Hb}$ is the blood volume signal from the NIRS device; $\beta$ is the blood volume correction factor; and $t$ is time. The raw $O_{2\text{Hb}}$ signal in equation 3 is corrected by subtracting the proportion of the blood volume change attributed to $O_{2\text{Hb}}$; while in equation 4 the raw $HHb$ signal is corrected by subtracting the proportion of blood volume change attributed to $HHb$.

**Statistics**

All data are presented as means ± SEM. Two-way analysis of variance (ANOVAs) with repeated measures were used to test for differences between conditions and time points, and for a condition x time interaction for MVC torque, arEMG, potentiated doublet torque, voluntary activation, variability, complexity and $m\dot{\text{VO}}_2$. The arEMG, variability, complexity and $m\dot{\text{VO}}_2$ measures were analyzed using means from the second minute (to account for the primary amplitude of the $\dot{\text{VO}}_2$ response; 31), isotime (the time point in the IPC condition equivalent to task failure in the SHAM condition; 12) and the final minute before task failure. When main effects were observed, Bonferroni-adjusted 95% paired-samples confidence intervals were used to identify specific differences. Results were deemed statistically significant when $P < 0.05$. 
Results

Preliminary measures

The contractile properties of the knee extensors obtained 10 minutes before and 20 minutes after IPC/SHAM are shown in Table 1. These were intended to assess the effects of IPC in a rested state. Both IPC and SHAM resulted in a decrease in MVC torque (95% paired samples confidence intervals [95% CIs]: IPC, −24.2, −6.2 N·m; SHAM, −39.8, −2.8 N·m). Neither IPC nor SHAM resulted in any significant change in either potentiated doublet torque or voluntary activation.

Time to task failure, MVC torque and EMG

Example contractions from a representative participant are shown in Figure 1. IPC significantly increased time to task failure by 7.4 ± 3.2 mins (95% CIs: 0.1, 14.7 mins) or by 43 ± 13% (Table 2). Task failure occurred when participants were no longer able to achieve the target torque (100.3 ± 10.5 N·m), despite a maximal effort. Both conditions resulted in significant decreases in MVC torque (F = 43.14, P < 0.001), such that the mean MVC torque at task failure was not significantly different from the torque produced during the submaximal contractions. At task failure, there was no significant difference between the conditions for MVC torque (95% CIs: −15.5, 18.5 N·m). The rate of decrease in MVC torque was significantly attenuated in the IPC condition (IPC vs. SHAM: −7.6 ± 2.0 vs. −10.2 ± 2.8 N·m·min⁻¹; 95% CIs: −5.2, −0.4 N·m·min⁻¹; Table 2). The arEMG of the vastus lateralis increased over time in both conditions (F = 43.41, P < 0.001; Table 2; Figure 2A). The rate of change in arEMG was significantly attenuated in the IPC condition (IPC vs. SHAM: 1.8 ± 0.5 vs. 2.4 ± 0.6%; 95% CIs: −0.1, −1.2%; Figure 2C).
Peripheral and central fatigue

Both conditions resulted in significant reductions in potentiated doublet torque \((F = 53.94, P < 0.001; \text{Table 2})\), indicating the presence of peripheral fatigue. The values attained at task failure were not significantly different between the conditions (95% CIs: −19.1, 12.6 N·m). The rate of decrease in potentiated doublet torque was not significantly different between conditions (95% CIs: −1.3, 1.2 N·m·min⁻¹; Table 2). Both conditions also resulted in a significant decline in voluntary activation \((F = 20.43, P = 0.002; \text{Table 2})\), indicating the presence of central fatigue. The values attained at task failure were not significantly different between the conditions (95% CIs: −6.8, 4.0%). The rate of decrease in voluntary activation was not significantly different between conditions (95% CIs: −0.2, 0.9%·min⁻¹; Table 2).

Muscle oxygen consumption

After 2 minutes of contractions, wherein a steady state should have been observed, both conditions resulted in a significant increase in m\(\dot{V}O_2\) \((F = 17.23, P = 0.003; \text{Table 2}; \text{Figure 2B})\). There were no significant differences between conditions after either 2 minutes of contractions (95% CIs: −1.0, 0.2%·s⁻¹) or at task failure (95% CIs: −1.8, 0.3%·s⁻¹). The rate of increase in m\(\dot{V}O_2\) was significantly attenuated in the IPC condition (IPC vs. SHAM: 0.08 ± 0.02 vs. 0.16 ± 0.05%·s⁻¹; 95% CIs: −0.2, −0.003%·s⁻¹; Table 2; Figure 2D).

Variability and complexity

Both conditions resulted in a significant increase in the amount of variability, as measured by the SD \((F = 29.45, P < 0.001)\) and CV \((F = 43.19, P < 0.001; \text{Table 3})\). The values attained at task failure for the SD (95% CIs: −0.4, 0.5 N·m) and CV (95% CIs: −1.9, 3.2%) were not significantly
different between conditions (Table 3). The rates of increase in the SD (95% CIs: –0.2, 0.2 N·m) and CV (95% CIs: –0.2, 0.2%) did not differ between conditions.

Complexity decreased as fatigue developed in both conditions, as measured by ApEn ($F = 102.99$, $P < 0.001$) and DFA $\alpha$ ($F = 29.64$, $P < 0.001$; Table 3; Figure 3B and D). ApEn significantly decreased as the trials progressed, with the values at task failure being not significantly different between the conditions (95% CIs: –0.05, 0.09). However, at isotime in the IPC condition (the time point equivalent to task failure in the SHAM condition), ApEn remained significantly higher (IPC vs. SHAM: 0.27 ± 0.04 vs. 0.14 ± 0.02; 95% CIs: 0.001, 0.3; Figure 3A). The rate of decrease in ApEn was significantly attenuated in the IPC condition (IPC vs. SHAM: –0.02 ± 0.01 vs. –0.04 ± 0.01; 95% CIs: –0.003, 0.02; Figure 3C). DFA $\alpha$ significantly increased as the trials progressed, with the values at task failure being not significantly different between the conditions (95% CIs: –0.08, 0.02). The rate of increase in DFA $\alpha$ was significantly attenuated in the IPC condition (IPC vs. SHAM: 0.02 ± 0.01 vs. 0.03 ± 0.01; 95% CIs: –0.02, –0.007; Figure 3D).

**Discussion**

The major novel finding of the present study was that, consistent with our hypotheses, ischaemic pre-conditioning (IPC) delayed task failure and slowed the fatigue-induced loss of muscle torque complexity. These responses were accompanied by an attenuated rate of decrease in MVC torque, and attenuated rates of increase in arEMG activity and mVO$_2$. This investigation is the first to demonstrate that IPC positively influences muscle torque complexity and motor control, provides further evidence that the loss of muscle torque complexity is sensitive to the administration of ergogenic aids, and that this is tightly coupled to the neuromuscular fatigue process. Moreover,
these results indicate that the effect of IPC, on both time to task failure and muscle torque complexity, may be mediated by an attenuated requirement for the recruitment of additional motor units.

**Effect of ischaemic pre-conditioning on muscle torque complexity and fatigue**

It has recently been shown that IPC has a positive effect on motor output, increasing maximum force (21, 22) and delaying task failure (18). The present study is the first to demonstrate that IPC can also slow the previously observed fatigue-induced loss of muscle torque complexity (6, 9), suggesting that IPC can influence motor control. As fatigue developed, ApEn decreased (indicating increased signal regularity) and DFA α increased (indicating increasingly Brownian fluctuations in torque), with both metrics reaching the same level at task failure in each condition. However, the rate at which ApEn decreased and DFA α increased were significantly attenuated following IPC (Table 3; Figure 3C and D). Furthermore, at isotime in the IPC condition, ApEn remained significantly higher than at task failure in the SHAM condition (Figure 3A). Consequently, the complexity of neuromuscular output during fatiguing contractions was better maintained with prior IPC, which presumably preserved the adaptability of the neuromuscular system (5) and allowed the task to be sustained for a longer duration (10).

The increase in time to task failure and slowing of the loss of muscle torque complexity following IPC were accompanied by a significant slowing in the rate of global fatigue development (i.e. the loss of MVC torque; Table 2) and in the rates of increase in both mVO₂ and arEMG (Table 2; Figure 1C and D, respectively). There was, however, no slowing in the rate of central fatigue development, a finding consistent with Halley et al. (29). Previous studies have implicated both
alterations in EMG responses (20, 24) and $\dot{V}O_2$ (14; 24) in the ergogenic effect of IPC. The rise in m$\dot{V}O_2$ beyond the primary amplitude (i.e. first two minutes of exercise; 31) is likely the result of a slow component of the m$\dot{V}O_2$ response to high-intensity exercise (32). This slow component has been associated with the recruitment of additional motor units as exercise progresses (32), which is sometimes reflected in a greater arEMG amplitude (33). As such, these results imply that the requirement for additional motor unit recruitment as exercise progresses is reduced following IPC.

*Physiological basis for change in torque complexity with ischaemic pre-conditioning*

Although the utility of IPC as an ergogenic aid has only been established within the last decade (14), it has quickly been demonstrated in a range of exercise tasks (15, 16, 18). The results of the present study demonstrated that IPC increased time to task failure of the knee extensors during submaximal intermittent isometric exercise by ~43% (Table 2). Whilst there is a growing body of evidence which suggests that IPC improves exercise performance, the mechanistic basis for this has remained elusive. Initially, enhanced oxygen delivery to working muscle was considered the most likely mechanism of the IPC-mediated performance improvement (14; 34); however, recent evidence has suggested that changes in neural drive, as elucidated below, may be of greater importance (20; 22).

IPC has previously been demonstrated to increase EMG amplitude during exhaustive exercise at peak aerobic power output, and during maximal sprints and maximal isometric contractions (22, 24) and to decrease the force recruitment threshold of motor units during submaximal isometric contractions (22). These responses are consistent with increased excitability of the motoneuron pool (25). In contrast, the results of the present study show that the rate of increase in arEMG was
slowed following IPC (Table 2; Figure 2C). The progression of fatiguing submaximal contractions necessitates an increase in the excitatory drive to motoneurons, which leads to the more frequent activation of a larger number of motor units in order to maintain torque, with this response reflected in an increase in EMG activity (27). This results in increased energy demand and thus mVO₂ during submaximal contractions, as illustrated by the slow component response (32). Our results demonstrated that the fatigue-induced rate of decrease in MVC torque was attenuated with IPC, implying that IPC reduces fatigability, which in turn reduces the requirement for additional motor unit recruitment and thus increased mVO₂.

We have previously argued that changes in the ensemble behaviour of the motor unit pool, specifically increases in common synaptic input, may be responsible for the fatigue-induced loss of muscle torque complexity (6; 9). Common synaptic input has been postulated to be the main determinant of torque variability (35), based on the coherence between the cumulative motor unit spike train and muscle torque output (36). Furthermore, common synaptic input to motoneurons has been demonstrated to increase when the net excitatory drive to motoneurons increases as a consequence of both changes in force and the development of neuromuscular fatigue (37). The presently observed IPC-mediated attenuation of the rate of fatigue development (i.e. slowing of the decrease in MVC torque and increases in arEMG and mVO₂) therefore suggests a slowing in the fatigue-induced increase in common synaptic input (37). We have postulated that any increase in common synaptic input should be reflected in a decrease in muscle torque complexity (10). Thus, a slowing in the fatigue-induced increase in common synaptic input should result in a concomitant slowing in the decrease in muscle torque complexity. However, as previously noted (12), direct measurement of individual motor unit spike trains, using either high-density surface of
intramuscular EMG (rather than the bipolar EMG used in the present study), is necessary to conclusively demonstrate a link between muscle torque complexity and common synaptic input.

**Limitations**

The present study was subject to some limitations. Firstly, it was not possible to blind participants to the two experimental conditions, as they are aware of the significant pressure difference between the IPC and SHAM conditions. This is, however, a limitation inherent to any study on IPC. To account for this, participants were informed that both IPC and SHAM might influence performance (21). Secondly, there are limitations associated with the estimation of m\(\text{VO}_2\) using NIRS. The penetration of the NIRS probe is approximately 1.5cm, meaning that it detects changes in a small and relatively superficial volume of the vastus lateralis. Koga *et al.* (38) demonstrated that the kinetics of [HHb] are not different at two different depths in the rectus femoris, but are different from those of the vastus lateralis. Our estimation of m\(\text{VO}_2\) is, therefore, specific to the vastus lateralis and may not reflect the m\(\text{VO}_2\) of the other quadriceps muscles. Thirdly, we were unable to identify the location of the neural effects of IPC. This could be achieved in future through the use of further electrical stimulation techniques (i.e. H-reflexes), transcranial magnetic stimulation and cervicomedullary stimulation. Finally, as mentioned above, the use of bipolar surface EMG does not allow the characterisation of individual motor unit thresholds and firing rates, which previous studies have implicated in the fatigue-induced loss of muscle torque complexity (6, 12) and IPC’s effect on motor output (22). The use of high-density arrays and/or intramuscular EMG is required to confirm whether such changes in motor unit behaviour are responsible for the loss of torque complexity and the ergogenic effect of IPC.
Conclusion

In summary, the present study has demonstrated that IPC increased time to task failure and slowed the fatigue-induced loss of muscle torque complexity, as measured using ApEn and DFA $\alpha$, during submaximal intermittent isometric knee extensor exercise. IPC also attenuated the rates of increase in $m\dot{V}O_2$ and EMG amplitude. The loss of motor output complexity, and adaptability, therefore remains tightly coupled to the neuromuscular fatigue process and the greater activation of the motor unit pool this entails. These results further suggest a neural contribution to the loss of muscle torque complexity with neuromuscular fatigue and provide further evidence that IPC’s ergogenic effect is mediated by neural mechanisms.
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The results of the study are presented clearly, honestly, and without fabrication, falsification, or inappropriate data manipulation.

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Figure legends

Figure 1: Raw torque output during contractions in the SHAM (top panels) and IPC (bottom panels) conditions from a representative participant.

Figure 2: The average rectified EMG (arEMG; Panel A) mVO₂ (panel B) responses to contractions performed in the IPC (black circles) and SHAM (white circles) conditions, and the group and individual rates of change in EMG (Panel C) and mVO₂ (panel D). Note first values in panel B are resting measurements taken prior to and after IPC/SHAM treatment. Values are means ± SEM. * = significantly different from SHAM.

Figure 3: The ApEn (panel A) and DFA α exponent (panel B) responses to contractions performed in the IPC (black circles) and SHAM (white circles) conditions, and the group and individual rates of change in ApEn (Panel C) and DFA α (panel D). Values are means ± SEM. * = significantly different from SHAM.
Figure 1

SHAM

ApEn = 0.43
DFA $\alpha = 1.39$

ApEn = 0.12
DFA $\alpha = 1.65$

IPC

ApEn = 0.42
DFA $\alpha = 1.39$

ApEn = 0.25
DFA $\alpha = 1.50$

ApEn = 0.10
DFA $\alpha = 1.62$

Task beginning

Task failure SHAM
Isotime IPC

Task failure IPC
Table 1. Effects of IPC and SHAM on voluntary torque and electrically-elicited muscle contractile properties.

| Parameter     | SHAM     | IPC       |
|---------------|----------|-----------|
|               | Pre      | Post      | Pre        | Post      |
| MVC, N·m      | 248.1 ± 26.6 | 228.6 ± 24.7* | 249.1 ± 24.7 | 233.9 ± 24.2* |
| Doublet, N·m  | 91.7 ± 9.8 | 89.6 ± 10.1 | 90.5 ± 10.3 | 86.5 ± 8.8  |
| VA, %         | 92.4 ± 0.9 | 90.0 ± 5.2  | 92.7 ± 1.6  | 90.4 ± 1.6  |

Values are means ± SEM. MVC, maximal voluntary contractions; VA, voluntary activation. * = significantly different from Pre.
Table 2. Voluntary torque, potentiated doublet torque, voluntary activation, EMG and $\dot{m}$VO$_2$ responses during contractions in the IPC and SHAM conditions.

| Parameter                              | SHAM            | IPC             |
|----------------------------------------|-----------------|-----------------|
| Time to task failure, min              | 17.3 ± 4.3      | 24.7 ± 6.2#     |
| Global fatigue                         |                 |                 |
| Pre-exercise MVC, N·m                  | 228.6 ± 24.7    | 233.9 ± 24.2    |
| Peak MVC at task failure, N·m          | 126.7 ± 16.0*   | 128.1 ± 17.4*   |
| Mean MVC at task failure, N·m          | 104.8 ± 12.6    | 108.9 ±14.8     |
| $\Delta$MVC/$\Delta$t, N·m·min$^{-1}$ | −10.2 ± 2.8     | −7.6 ± 2.0#     |
| Peripheral fatigue                     |                 |                 |
| Pre-exercise doublet, N·m              | 89.6 ± 9.6      | 86.5 ± 8.4      |
| Doublet at task failure, N·m           | 72.2 ± 10.0*    | 69.0 ± 8.0*     |
| % Change at task failure               | 23.2 ± 5.0      | 24.4 ± 3.6      |
| $\Delta$doublet/$\Delta$t, N·m·min$^{-1}$ | −1.3 ± 0.2     | −1.4 ± 0.6      |
| Central fatigue                        |                 |                 |
| Pre-exercise VA, %                     | 90.0 ± 1.6      | 90.4 ± 1.5      |
| VA at task failure, %                  | 77.0 ± 3.0*     | 75.6 ± 3.6*     |
| % Change at task failure               | 16.7 ± 3.3      | 18.3 ± 4.2      |
| $\Delta$VA/$\Delta$t, %/min           | −1.2 ± 0.4      | −0.8 ± 0.2      |
| Surface EMG                            |                 |                 |
| arEMG at task beginning, % MVC         | 41.2 ± 3.1      | 37.0 ± 2.6      |
| arEMG at isotime, % MVC                | −              | 57.0 ± 3.6      |
|                           |       |       |
|---------------------------|-------|-------|
| arEMG at task failure, % MVC | 65.8 ± 5.2° | 59.8 ± 4.8° |
| ∆arEMG/∆t, % MVC·min⁻¹     | 2.4 ± 0.6 | 1.8± 0.5# |
| m\(\dot{V}O_2\)          |       |       |
| m\(\dot{V}O_2\) at task beginning, %·s⁻¹ | 2.3 ± 0.3 | 1.8 ± 0.3 |
| m\(\dot{V}O_2\) at isotime, %·s⁻¹ | – | 2.7 ± 0.3 |
| m\(\dot{V}O_2\) at task failure, %·s⁻¹ | 3.7 ± 0.4° | 3.1 ± 0.3° |
| ∆m\(\dot{V}O_2\)/Δt, %·s⁻¹ | 0.2 ± 0.05 | 0.1 ± 0.02# |

Values are means ± SEM. MVC, maximal voluntary contraction; VA, voluntary activation; EMG, electromyogram; arEMG, average rectified EMG of the vastus lateralis; m\(\dot{V}O_2\), muscle oxygen consumption; ∆, change; t, time. Symbols indicate a statistically significant difference compared to the following: °pre-exercise value/value at task beginning (2 mins into exercise, to account for primary amplitude of \(\dot{V}O_2\) response), #SHAM. Isotime in the IPC condition is compared with task failure in the SHAM condition.
Table 3. Variability, complexity and fractal scaling responses during contractions in the IPC and SHAM conditions.

| Parameter                              | SHAM    | IPC     |
|----------------------------------------|---------|---------|
| SD                                     |         |         |
| SD at task beginning, N·m              | 2.0 ± 0.2 | 2.0 ± 0.2 |
| SD at isotime, N·m                     | –       | 3.4 ± 0.6 |
| SD at task failure, N·m                | 4.3 ± 0.4* | 5.0 ± 0.7* |
| ΔSD/Δt, N·m·min⁻¹                      | 0.3 ± 0.1 | 0.3 ± 0.1 |
| CV                                     |         |         |
| CV at task beginning, %                | 2.0 ± 0.2 | 2.0 ± 0.1 |
| CV at isotime, %                       | –       | 3.4 ± 0.3 |
| CV at task failure, %                  | 5.0 ± 0.6* | 5.6 ± 0.7* |
| ΔCV/Δt, %/min                         | 0.4 ± 0.1 | 0.3 ± 0.1 |
| ApEn                                   |         |         |
| ApEn at task beginning                 | 0.44 ± 0.02 | 0.44 ± 0.02 |
| ApEn at isotime                        | –       | 0.27 ± 0.04* |
| ApEn at task failure                   | 0.14 ± 0.02* | 0.16 ± 0.03* |
| ΔApEn/Δt                               | −0.04 ± 0.01 | −0.02 ± 0.01* |
| DFA α                                  |         |         |
| DFA α at task beginning                | 1.33 ± 0.05 | 1.33 ± 0.05 |
| DFA α at isotime                       | –       | 1.43 ± 0.06 |
| DFA α at task failure                  | 1.53 ± 0.05* | 1.50 ± 0.06* |
| ΔDFA α / Δt | 0.03 ± 0.01 | 0.02 ± 0.01* |

Values are means ± SEM. SD, standard deviation; CV, coefficient of variation; ApEn, approximate entropy; DFA α, detrended fluctuation analysis; Δ, change; t, time. Symbols indicate a statistically significant difference compared to the following: *value at task beginning (2 mins into exercise, to account for primary amplitude of VO₂ response), #SHAM. Isotime in the IPC condition is compared with task failure in the SHAM condition.