RANDOM PERTURBATION TO THE GEODESIC EQUATION

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Abstract. We study random perturbations to the geodesic equation. If the velocity of the geodesic with unit initial velocity is stirred sufficiently uniformly, the solutions, after suitable rescaling, converge to a Brownian motion scaled by $\frac{8}{n(n-1)}$ where $n$ is the dimension of the state space.

1. Introduction

Let $M$ be a complete smooth Riemannian manifold, $TM$ its tangent bundle and $T^*M$ its cotangent bundle. A geodesic $(x(t), t \in [0,1])$ is a solution to the geodesic equation $\frac{d}{dt} \dot{x}^k(t) = - \sum_{i,j} \Gamma^k_{ij}(x(t)) \dot{x}^i(t) \dot{x}^j(t)$, where the functions $\{\Gamma^k_{ij}\}$ are the Christoffel symbols. A geodesic is intuitively the motion of a free particle that minimises the energy function $E(x) = \frac{1}{2} \int_0^1 |\dot{x}(t)|^2 dt$; they are critical points of $E$. The velocity of a geodesic lives in the tangent bundle, but if we identify the tangent bundle with the cotangent bundle, the geodesic flow is the Hamiltonian flow on the cotangent bundle for the Hamiltonian function $H(x, y) = \frac{1}{2} |y|^2_x$, $(x, y) \in T^*M$. Let $(O, x)$ be a local coordinate chart for $M$, where $O$ is an open set of $M$ and by abuse of notation $x : O \to \mathbb{R}^n$ is a diffeomorphism to its image and $x = (x^1, \ldots, x^n)$. Then $(x, y)$ is the induced coordinate map for $T^*M$, and $(x, y)$ represents the cotangent vector $\sum_i y_i dx_i$. Let $(g^{ij})$ denote the inverse matrix to the Riemannian metric $(g_{ij})$ then $H(x, y) = \frac{1}{2} \sum_{i,j} g^{ij}(x) y_i y_j$. Let $\omega = \sum_i dx_i \wedge dy_i$ be the non-degenerate 2-form and define a vector field $X$ on $T^*M$ by $\iota_X \omega = dH$ where $\iota$ denotes interior product. The solution flow to $\dot{x}(t) = X(x(t))$ are geodesics, to see this more clearly.

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we will write the equation in local coordinates. First
\[
dH = \frac{1}{2} \sum_{i,j,k} \frac{\partial g^{ij}}{\partial x^k} y_i y_j dx_k + \sum_{i,j} g^{ij} y_i dy_j.
\]
If \(X = \sum_k f_k \frac{\partial}{\partial x^k} + \sum_k h_k \frac{\partial}{\partial y^k}\), then \(\iota_X \omega = \sum_k f_k dy_k - \sum_k h_k dx_k\). This means that \(X\) has the expression
\[
X = \sum_k \sum_i g^{ik} y_i \frac{\partial}{\partial x^k} - \sum_k \frac{1}{2} \sum_{i,j} \frac{\partial g^{ij}}{\partial x^k} y_i y_j \frac{\partial}{\partial y^k}.
\]
Let \((x_t, y_t)\) denote the integral curve of \(X\), then
\[
\dot{x}^k = \sum_j g^{kj} y_j, \quad \dot{y}^k = -\frac{1}{2} \sum_{i,j} \frac{\partial g^{ij}}{\partial x^k} y_i y_j.
\]
Next we differentiate \(\dot{x}^k\) once more, transform \(y_k\) to \(\dot{x}^k\)'s by raising the indices, apply the formula for Christoff symbols in terms of \((g_{i,j})\), and we see that this is indeed the geodesic equation.

Our formulation of the perturbation to the geodesics is best described by perturbation to an ODE on the frame bundle, see §2C for the passage from one to the other. A geodesic is the projection of a horizontal flow from the bundle of orthonormal frames of \(M\) to \(M\). Let \(u\) stand for an orthonormal frame at a point \(x\) of \(M\), i.e. an orthonormal basis of \(T_x M\). Let us denote by \(\pi\) the map that takes a frame \(u\) of \(T_x M\) to the point \(x \in M\). For \(e_0 \in \mathbb{R}^n\), let \(H_u(e_0)\) be the horizontal lift of \(u(e_0)\). Let \((u_{t}^{e_0})\) be the solution to
\[
\dot{u}(t) = H_{u_t}(e_0), \quad u(0) = u_0,
\]
then \(\pi(u_{t}^{e_0})\) is the geodesic with initial velocity \(u_0(e_0)\) and initial point \(\pi(u_0)\). We perturb this ODE in directions that are transversal,
\[
\dot{u}_t = H_{u_t}(e_0) + G^\epsilon(u_t),
\]
where \(G^\epsilon\) is to be specified, and conclude that there is an effective motion which projects to a scaled Brownian motion on \(M\) with a factor \(\frac{\epsilon}{n(n-1)}\). The perturbation \(G^\epsilon\) involves a Gaussian noise, so techniques involving parallel transport along a stochastic process and horizontal lifts of non-smooth curves will be used. Stochastic parallel translations goes back to Itô in 1962, [24, 26] where piecewise approximation was used for the construction, followed by Dynkin [8]. The canonical construction using a Stratonovich SDE on the orthonormal frame bundle can be found in Eells-Elworthy [9]. See also Malliavin [34]. Horizontal stochastic processes have been used in connection with the following topics: horizontal lifts of semi-martingales, construction of canonical
Brownian motions, Malliavin calculus, construction of line integrals, the geometry of diffusion operators. This study is an extension to and an application of the last mentioned topic.

Let \( N = \frac{n(n-1)}{2} \). If \( A \in \mathfrak{so}(n) \) we denote by \( A^* \) the fundamental vertical vector field on \( OM \) determined by right actions of the exponentials of \( tA \), see (2.1) below. We denote by \( \Delta^G \) the Laplacian on \( G \) and \( \Delta^H \) the horizontal Laplacian on \( OM \). If \( X \) is a vector field, we denote by \( L_X \) Lie differentiation in the direction of \( X \). Let \( \{A_1, \ldots, A_N\} \) be an o.n.b of \( \mathfrak{g} \), and \( \bar{A} \in \mathfrak{g} \). Let \( (u_{\epsilon t}) \) be the solution to the SDE

\[
\begin{align*}
\frac{du_{\epsilon t}}{dt} &= H_{u_{\epsilon t}}(e_0)dt + \frac{1}{\sqrt{\epsilon}} \sum_{k=1}^{N} A_k^*(u_{\epsilon t}) \circ dw_k + \bar{A}^*(u_{\epsilon t})dt, \\
u_{\epsilon 0} &= u_0.
\end{align*}
\]

The SDE is conservative. Let \( x_{\epsilon t} = \pi(u_{\epsilon t}) \) and let \( \tilde{x}_{\epsilon t} \) be the horizontal lift of \( x_{\epsilon t} \) to \( OM \) through \( u_0 \). Then

1. The processes \( x_{\epsilon t} \) and \( \tilde{x}_{\epsilon t} \) converge in law, as \( \epsilon \to 0 \).
2. The limiting law of \( x_{\epsilon t} \) is independent of \( e_0 \). It is a scaled Brownian motion with generator \( \frac{4}{n(n-1)} \Delta^G \). The limiting probability distribution of \( \tilde{x}_{\epsilon t} \) is that associated to the generator \( \frac{4}{n(n-1)} \Delta^H \).

If \( \epsilon = \infty \), the equation is the ‘geodesic equation’: \( \dot{x}_t = u_t e_0 \). The perturbation to the geodesic is exerted only through the perturbation of its velocity. Since \( u_t \) is a linear isometry, the velocity of the motion is always unitary. The effective motion is due to the fast rotation in the velocity field. The perturbed geodesic has rapid changing directions and we expect to see a jittering motion and indeed we obtain a scaled Brownian motion in the limit if the rotational motion is elliptic.

This agrees with the philosophy in Bismut [4], that \( \bar{x} = \frac{1}{T}(-\dot{x} + \dot{w}) \) interpolates between classical Brownian motion \( T \to 0 \) and the geodesic flow \( T \to \infty \). We also note limit theorems on line integrals of
the form \(\int_0^t \phi(dx_s)\), where \(\phi\) is a differential form and \((x_s)\) is a suitable process such as a Brownian motion. See Ikeda [22] and Ikeda-Ochi [23]. A central limit theorem is proven to be valid for line integrals along geodesic flows by Manabe-Ochi [35], where they used symbolic representations of geodesic flows. A related work is that by Pinsky [39], where a piecewise geodesic with a Poisson-type switching mechanism is shown to converge to the horizontal Brownian motion.

The scaling limit is consistent with the central limit theorem for geodesic flows \(\theta_s(v) = (\gamma_t(x,v), \dot{\gamma}_t(x,v))\) on the unit tangent bundle, where \((\gamma_t(x,v))\) denotes the geodesic with initial value \((x,v)\in STM\). Let us assume that \(M\) is a manifold of constant negative curvature and of finite volume. If \(f\) is a bounded measurable function on the unit tangent bundle, centred with respect to the normalised Louville measure \(m\), then the central limit theorem states that there is a number \(\sigma\) with the property that

\[
\lim_{t \to \infty} m\{\xi : \frac{\int_0^t f(\theta_s(\xi))ds}{\sigma \sqrt{t}} \leq a\} = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^a e^{-\frac{y^2}{2}} dy.
\]

See Sinai [41], Ratner [40], and Guivarch-LeJan [18], and Enriquez-Franchi-LeJan [15] for further developments. These results explores the chaotic nature of of the deterministic dynamical system on manifolds of negative curvatures.

In the homogenisation literature, the following work are particularly relevant: Khasminskii [28, 20], Nelson [36], Borodin, Freidlin [5], Freidlin,Wentzell [17], and Bensoussan, Lions, Papanicolaou [2]. In terms of scaling limits in manifolds we refer to Li [32] for averaging of integrable systems and to Gargate, Ruffino [27] for averaging on foliated manifolds. See also [33] for an earlier work on the orthonormal frame bundle. We also refer to Dowell [7] for a scaling limit of Ornstein-Uhlenbeck type and to Bismut [4] on Hypoelliptic Laplacians and orbital integrals.

**Open Questions.** (1) We have a rate estimate in Lemma 3.4 but we do not know the rate of convergence in Theorem 1.1. Can an estimate be obtained? (2) The local uniform bound on \(\nabla d\rho\) is only used in Lemma 3.2 for the proof of tightness. This bound can be weakened, for example replaced by a local uniform control over the rate of growth of the norms of \(\nabla \phi\) and \(\nabla \rho\). For the purpose of this article it is too long to be included, however it is worth further study in view of stochastic completeness of a Riemannian manifold. A manifold is stochastically complete if the Brownian motion is complete, i.e. has infinite life time. A geodesically complete manifold is not necessarily
stochastically complete; this was pointed out in Azencott [1] where the author studied negatively curved manifolds and noted that if the sectional curvature decays at infinity faster than $\rho^{2+}$, the manifold is stochastically incomplete. There have since been many results on the stochastic completeness. They are mostly in terms of the global decay of the Ricci curvature at infinity and the volume growth of a ball of radius $r$. The Brownian motion constructed in Theorem 1.1 will be automatically complete. The conditions in Theorem 1.1 appear to be related to the uniform cover criterion on stochastic completeness and could be studied in connection with that in Li [31]. If the manifold has a positive injectivity radius $a$, every point in the manifold is contained in a chart $(O, x)$ with $O$ contains a ball of radius $a$. A ‘uniform cover’ type condition for an SDE $dx_t = \sum_k \sigma_k(x_t) \circ dw^k_t + \sigma_0(x_t) dt$ is on the size of $|\phi^*_\sigma(\sigma_k)|$ or on how fast does a Brownian motion escapes the ball. Such bounded local coordinate method goes back to Itô [25] and was fully developed in Elworthy [12], and see also Clark [6]. This method evolved into ‘weak uniform covers’ in Li [31] where it was shown to be an effective criterion for the non-explosion and for for the $C_0$-property of the semi-groups. Also much of the work in this article is valid for a connection $\nabla$ with torsion; the horizontal tangent bundle and $\Delta_H$ will then be induced by this connection with torsion. The effect of the torsion will generally lead to an additional drift to the Brownian motion downstairs. In this case the geodesic completeness of the manifold $M$ may no longer be equivalent to the metric completeness of the metric space $(M, \rho)$.

2. Preliminaries

A. A frame $u$ is an ordered basis of $T_xM$. We denote by $FM$ the set of all frames on $M$ and $\pi$ the map that takes the frame $u$ to the point $x \in M$. Let $\pi^{-1}(x) = \{u \in FM : \pi(u) = x\}$. We call $FM$ the bundle of frames of $M$. Let $u = \{u_1, \ldots, u_n\}$ be a frame, where $u_i \in T_xM$. If $(O, x)$ is a coordinate system on $M$, $u_i = \sum_j u^j_i \frac{\partial}{\partial x_j}$. This gives a coordinate map on $FM$. The map $(x, u^j_i)$ is a homeomorphism from $\pi^{-1}(O)$ to $(x(O), GL(n, \mathbb{R}))$. We may consider the subspace of $FM$ that consists of bases of $T_xM$ that are orthonormal, w.r.t. the given Riemannian metric, in which case we have the bundle of orthonormal frames. We denote the orthonormal frame bundle by $OM$. The orthonormal frame bundle is a fibre bundle with group $O(n)$. If the manifold is oriented we may consider a connected component $SOM$.

If we identify a frame $u$ by the transformation $u : \mathbb{R}^n \to T_xM$, $FM$, $OM$ and $SOM$ are principle bundles with fibres $GL(n, \mathbb{R})$, $O(n)$, and
For ease of notation we denote by $P$ one of the bundles and $G$ one of the groups and $\mathfrak{g}$ its Lie algebras. The group $G$ acts on the right: if $u$ is a frame and $g \in G$ then $ug$ is another frame. For $g \in G$ let $R_g$ denotes the right action on $G$ or on $P$. We use the following conventions for $G$ the orthogonal group or the special orthogonal group. If $A, B \in \mathfrak{so}(n)$, we define $\langle A, B \rangle = \text{tr} AB^T$ which is bi-invariant and we define the Riemannian metric at $T_gG = \{A : gA^T + Ag^T = 0\}$ to be $\langle gA, gB \rangle = \langle A, B \rangle$.

A tangent vector $v$ in $P$ is vertical if $T \pi(v) = 0$. We introduce a family of vertical vector fields. If $A$ belongs to the Lie algebra $\mathfrak{g}$, we denote by $\exp(tA)$ the exponential map. If $u$ is a frame, the composition $u \exp(tA)$ is again a frame in the same fibre. We define the fundamental vertical vector fields associated to $A$ by

$$A^*(u) = \frac{d}{dt} \bigg|_{t=0} u \exp(tA).$$

B. Suppose that we are given an Ehresmann connection: $T_uP = HT_uP \oplus VT_uP$, so every tangent vector on $FM$ has a horizontal component and a vertical component. The horizontal space is right invariant: $(R_g)_{\ast}HT_P = HT_P$ and the projection $\pi$ induces an isomorphism between $HT_P$ and $TM$.

An Ehresmann connection determines and is determined by parallel translation. A piecewise $C^1$ curve $\gamma$ on $P$ is horizontal if the one sided derivatives $\dot{\gamma}(\pm)$ are horizontal for all $t$. If $c$ is a $C^1$ curve on $M$ there is a horizontal curve $\tilde{c}$ on $P$ such that $\tilde{c}$ covers $c$, i.e. $\pi(\tilde{c}(t)) = c(t)$. In fact $\tilde{c}(t)$ is the family of orthonormal frames along $c$ that are obtained by parallel transporting the frame $\tilde{c}(0)$. We say that $\tilde{c}$ is a horizontal lift of $c$. We will assume that the parallel translation is induced by the Levi-Civita connection. If $\tilde{c}$ is a horizontal lift of $c$, the translation of $\tilde{c}$ by $g \in G$, $R_g \circ c^*$, is also a horizontal curve. If we fix $\tilde{c}(0) = u_0 \in P$, there is only one horizontal lift with $\tilde{c}(0) = u_0$. Let $v = \tilde{c}(0)$ and $u = \tilde{c}(0)$. We define the horizontal lift of $c(0)$, $\mathfrak{h}_u(v)$, to be $\dot{v}(0)$. If $c$ is a solution of a stochastic differential equation we use the concept and theory of horizontal lifts in Eells-Elworthy [9, 11], Malliavin [34], Elworthy [10] and Emery [14]. We follow the notation in [10].

To each $e \in \mathbb{R}^n$ we associate a special horizontal vector field, the basic vector field $H_u(e) = \mathfrak{h}_u(ue)$. They satisfy $\pi_\ast(H_u(e)) = ue$. We will introduce a metric on $OM$ such that $\pi$ is an isometry between $H_uTOM$ and $T_{\pi(u)}M$, and on each fibre it is the bi-invariant metric on the Lie algebra. If $\{e_1, \ldots, e_n\}$ is an orthonormal basis of $\mathbb{R}^n$ then $\{H_u(e_1), \ldots, H_u(e_n)\}$ is an orthonormal basis for the horizontal tangent subspace $HT_P$ at $u$. 
C. We describe the relation between horizontal equations on frame bundles and the geodesic flows. The tangent bundle \( TM \) is the fibre bundle associated with the principal fibre bundle \( P \) with fibre \( \mathbb{R}^n \). The total space is \( P \times \mathbb{R}^n / \sim \) where the equivalent class is determined by \([u, e] \sim [ug^{-1}, ge], \) any \( g \in G \). Fix a unit vector \( e_0 \in \mathbb{R}^n \). Let \( H \) be the isotropy group at \( e_0 \) of the action of \( G \) on \( \mathbb{R}^n \). Each element \( v \in TM \) has a representation \([u, e_0] \) in \( P \times \mathbb{R}^n \) and it is unique up to right translation by elements of \( H \). We may identify \( P \times \mathbb{R}^n / \sim \) with the quotient bundle \( P/H \), whose element containing \( u \) is the equivalence class of elements of the form \( ug, g \in H \). Let \( \alpha \) be the associated map:

\[
\alpha_{e_0}: u \in P \rightarrow ue_0 \equiv [u, e_0] \in TM.
\]

The differential \( D\alpha_{e_0} \) induces a map from \( TuP \) to \( Tu_0TM \). Any vector field \( W \) that is invariant by right translations of elements of \( H \) induces a vector field on \( TM \). If \( v = ue'_0 = u e_0 \) there is \( g \in G \) with \( e'_0 = g^{-1} e_0 \).

Set \( u' = ug \). Since \( \alpha_{e_0}(u) = \alpha_{e'_0}(R_g u) \),

\[
D_u \alpha_{e_0}(W(u)) = D_u' \alpha_{e'_0} DR_g(W(u)) = D_u' \alpha_{e'_0}(W(u')),
\]

and the map \( W \in \Gamma TP \mapsto D_u \alpha_{e_0}(W(u)) \in \Gamma TT M \), is independent of the choices of \( e_0 \). If \( W(u) = H_u(e_0) \), the induced vector field \( X \) on the tangent bundle \( TM \) is a geodesic spray, i.e. in local co-ordinates \( X(x, v) = (x, v, v, Z(x, v)) \) and \( Z(x, sv) = s^2 Z(s, v) \). This corresponds to the geodesic equation on \( TM \): \( dv^k_i = -\Gamma^k_{ij} v_i v^j, \sigma_t = v_t, \sigma(0) = \pi(u_0), v(0) = u_0 e_0 \). A vector field on \( P \) that is horizontal and invariant under translation by the action of \( G \) projects to a vector field on the base manifold. It is worth remarking that \( H(e_0) \) does not project to a vector field on \( M \).

D. A basic object we use in our computation is the connection 1-form \( \varpi \) on \( FM \) corresponding to the Ehresmann connection. We follow closely the notation in Kobayashi-Nomizu [30]. A connection form assigns a skew symmetric matrix to every tangent vector on \( FM \) and it satisfies the following conditions: (1) \( \varpi(A^\ast) = A \) for all \( A \in \mathfrak{g} \); (2) for all \( a \in G \) and \( w \in FM \), \( \varpi(R_{a\ast}w) = Ad(a^{-1})\varpi(w) \). We recall that \( R_{a\ast}(A^\ast) = (Ad(a^{-1}A))^\ast \) for all \( a \in G \). It is convenient to consider horizontal tangent vectors on \( P \) are elements of the kernel of \( \varpi \). If \( \{A_1, \ldots, A_N\} \) is a basis of \( \mathfrak{g} \), then the horizontal component of a vector \( w \) is \( w^h = w - \sum_j \varpi(v)A^j \).

The connection 1-form \( \varpi \) is basically the set of Christoffel symbols. Let \( E = \{E_1, \ldots, E_n\} \) be a local frame; we define the Christoffel symbols relative to \( E \) by \( \nabla E_j = \sum_{ki} \Gamma^k_{ij} dx_i \otimes E_k \). Let \( \theta^i \) be the set of dual differential 1-forms on \( M \) to \( \{E_i\} \): \( \theta^i(E_j) = \delta_{ij} \). We define \( \omega^i = \Gamma^i_{kj} \theta^k \).
Then $d\theta^i = -\sum_k \theta^k \wedge \omega^i_k$ and $\omega^i_k$'s measure the change of the dual forms $\theta^i$ in the direction of $E_j$. Let $A^j_i$ be a basis of $g$, to each moving frame we associate a 1-form, $\omega = \sum_{i,j} \omega^j_i A^j_i$, on $M$. If $(O, x)$ is a chart of $M$ and $s : O \rightarrow OM$ is a local section of $OM$, let us denote by $\omega_s$ the differential 1-form given above, then $\omega(s_v) = \omega_s(v)$. Conditions (1) and (2) are equivalent to the following: if $a : U \rightarrow G$ is a smooth function, 

$$\omega((s \cdot a)_v) = a^{-1}(x)da(v) + a^{-1}(x)\omega(s_v)a(x).$$

This corresponds to the differentiation of $s \cdot a$.

**E.** Let us work in a coordinate chart $(O, x)$. Let $c(t)$ be a curve and $\tilde{c}(t)$ a horizontal lift of $c(t)$ whose column vectors $\{\tilde{c}_i\}$ is a frame. Then $\tilde{c}(t)$ satisfies:

$$\frac{\partial \tilde{c}_i}{\partial t} + \sum_{i,j=1}^n \partial c^j_i \partial t \Gamma_{ij}^{k} \tilde{c}_j = 0.$$

Take $c(t) = (0, \ldots, t, \ldots, 0)$, where the non-zero entry is in the $i$-place. We obtain the principal part of the horizontal lift of $\frac{\partial}{\partial x_i}$:

$$h_{\tilde{c}(0)}\left(\frac{\partial}{\partial x_i}\right)_l = \left(\frac{\partial \tilde{c}}{\partial t}(0)\right)_l = -\left(\sum_j \Gamma^1_{ij} u^j_1, \ldots, \sum_j \Gamma^n_{ij} u^j_n\right)^T.$$

The horizontal space at $u$ is spanned has a basis

$$\left\{ \left( \frac{\partial}{\partial x_i}, -(\sum_{j=1}^n u^j_i \Gamma^b_{ij} \frac{\partial}{\partial u^b_j}) \right) \right\}.$$

**Example 2.1.** Let $H^2 = \{(x_1, x_2) : x_2 > 0\}$ be the the hyperbolic plane. It has a global chart and $g_{ij} = \frac{1}{(x_2)^2} \delta_{ij}$. Its non-zero Christoffel symbols are:

$$\Gamma^1_{12} = \Gamma^1_{21} = -\frac{1}{y}, \quad \Gamma^2_{22} = -\frac{1}{y}, \quad \Gamma^2_{11} = \frac{1}{y}.$$

The total space of the orthonormal frames is a product space. We let $u$ denote the principal part of an frame. For $u = (u^1, u^2)^T$ and $\pi(u) = x = (x_1, x_2) \in H^2$, let us define

$$X_1(u) = \frac{1}{x_2} \begin{pmatrix} -u^2_1 & -u^2_2 \\ u^1_1 & u^1_2 \end{pmatrix}, \quad X_2(u) = -\frac{1}{x_2} \begin{pmatrix} u^1_1 & u^1_2 \\ u^2_1 & u^2_2 \end{pmatrix}, \quad A = \begin{pmatrix} 0 & \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} & 0 \end{pmatrix}.$$
Let us take $e_0 = e_1$ then $ue_1 = u_1$ and our SDE becomes:

$$\dot{x} = u_1$$

$$du = u_1^1 \cdot X_1(u)dt - u_1^2 \cdot X_2(u)dt + \frac{1}{\sqrt{\epsilon}} u_1 A \circ dw_t.$$

In the equation we suppressed the $t$-variable as well as the superscript $\epsilon$ in the stochastic processes $(x^\epsilon(t), u^\epsilon(t))$. These are further subject to the following three constraints:

$$(u_1^1)^2 + (u_1^2)^2 = (x_2)^2, \quad (u_2^1)^2 + (u_2^2)^2 = (x_2)^2, \quad u_1^1 u_2^1 + u_1^2 u_2^2 = 0.$$  

We hence have a system of 3 SDE’s with a one dimensional driving Brownian motion $(w_t)$. The effective motion, obtained from the $x$ process, is a scaled hyperbolic Brownian motion.

**Example 2.2.** Let us strip off the geometry and take a close look at the example of $M = \mathbb{R}^d$ with the trivial Riemannian metric. Then $FM = \mathbb{R}^n \times GL(n)$ and $OM = \mathbb{R}^n \times SO(n)$ are the trivial product bundles. The horizontal vectors in the tangent space of $OM$ are those whose Lie-algebra component vanishes. We write a frame $u$ as $(x, g)$. The horizontal lift at $u = (x, g)$ of a vector $v \in T_x \mathbb{R}^n$ is $((x, g), (v, 0)) \in (\mathbb{R}^n \times G) \times (T_x \mathbb{R}^n \times \mathfrak{g})$. To ease the notation we omit the trivial component of the horizontal lift, we have $H_u(e) = (ge, 0)$ and the equation $\dot{u}_t = H_{u_t}(e_0)$ is equivalent to $\dot{x}_t = g_t e_0, \dot{g}_t = 0, g_0 e_0 = v_0$. Let $A_k \in \mathfrak{so}(n)$, the perturbed system is

$$\dot{x}_t^\epsilon = \dot{g}_t^\epsilon e_0, \quad \dot{g}_t^\epsilon = \frac{1}{\sqrt{\epsilon}} \sum_k g_t^\epsilon A_k \circ dw_t^k + g_t^\epsilon \tilde{A} dt,$$

with $x_0^\epsilon = x_0$ and $g_0^\epsilon = I$, the identity matrix. We claim that $x_t^\epsilon$ converges. At first glance this equation appears to have the wrong scaling. Let us set $y_t^\epsilon = \frac{1}{\epsilon} x_t^\epsilon$ and $\tilde{g}_t = g_t^\epsilon$. The above equation is equivalent to

$$\dot{y}_t^\epsilon = \tilde{g}_t^\epsilon e_0, \quad \dot{\tilde{g}}_t^\epsilon = \sum_k \tilde{g}_t^\epsilon A_k \circ dw_t^k + \epsilon \tilde{g}_t^\epsilon \tilde{A} dt$$

with $y_0^\epsilon = \frac{1}{\epsilon} x_0$ and $\tilde{g}_0^\epsilon = I$. Here $\{\tilde{w}_t^k\}$ is a family of independent Brownian motions and $(\tilde{g}_t^\epsilon)$ will be independent of $\epsilon$. Let us assume that $\tilde{A} = 0$, then $(\tilde{g}_t^\epsilon)$ is a reversible ergodic Markov process on $G$ with the invariant measure the Haar measure. We can apply central limit theorems for additive functionals of Markov processes. Let $e \in \mathbb{R}^n$ we set $V^e(g) = \langle ge_0, e \rangle$ and set $Y^e(t) = \int_0^t V^e(\tilde{g}_s) ds$. It is easy to check that for each $e$, $V^e$ satisfies the conditions in Theorem 1.8 and Corollary 1.9 in Kipnis-Varadhan [29], in particular $\int V^e dg = 0$. Hence
\( \epsilon Y^s(\frac{1}{\epsilon}) \) converges, and so does \( x^1_\epsilon = \epsilon y^1_\epsilon \). See also Helland [21]. If the connection on \( TO^R_n \) is not trivial, the non-zero Christoffel symbol will be involved. In this case the ergodic component and the non-ergodic component oscillate at speeds of different scale.

3. Some Lemmas

**Lemma 3.1.** Let \( M \) be a geodesically complete Riemannian manifold. Let \( (u^\epsilon_t) \) be the solution to the SDE (1.1). Let \( x^\epsilon_t = \pi(u^\epsilon_t) \), which has a unique horizontal lift, \( \tilde{x}^\epsilon_t \), through \( u^\epsilon_0 \equiv u^\epsilon_0 \). Then

\[
\frac{d}{dt} \tilde{x}^\epsilon_t = H_{\tilde{x}^\epsilon_t}(g^\epsilon_t e_0)
\]

\[
dg^\epsilon_t = \frac{1}{\sqrt{\epsilon}} \sum_{k=1}^m g^\epsilon_t A_k \circ dw^k_t + g^\epsilon_t \tilde{A} dt,
\]

where \( g^\epsilon_0 \) is the identity matrix. Consequently the SDE (1.1) is conservative.

**Proof.** By the defining properties of the basic horizontal vector fields, \( \dot{x}^\epsilon_t = \pi_\ast(H_{u^\epsilon_t(e_0)}) = u^\epsilon_t e_0 \). Since \( u^\epsilon_t e_0 \) has unit speed, the solution exists for all time if \( (u^\epsilon_t) \) does, and

\[
\frac{d}{dt} \tilde{x}^\epsilon_t = h_{\tilde{x}^\epsilon_t}(\tilde{x}^\epsilon_t) = h_{\tilde{x}^\epsilon_t}(u^\epsilon_t e_0).
\]

At each time \( t \), the horizontal lift \( (\tilde{x}^\epsilon_t) \) of the curve \( (x^\epsilon_t) \) through \( u_0 \) and the original curve \( u^\epsilon_t \) belong to the same fibre. Let \( g^\epsilon_t \) be an element of \( G \) with the property that \( u^\epsilon_t = \tilde{x}^\epsilon_t g^\epsilon_t \). Then \( g^\epsilon_0 \) is the identity matrix and

\[
\frac{d}{dt} \tilde{x}^\epsilon_t = h_{\tilde{x}^\epsilon_t}(\tilde{x}^\epsilon_t g^\epsilon_t e_0) = H_{\tilde{x}^\epsilon_t}(g^\epsilon_t e_0).
\]

If \( a_t \) is a \( C^1 \) path with values in \( G \), \( a_t^{-1} \dot{a}_t = \frac{d}{dr}_{r=0} e^{\gamma a_t^{-1} \dot{a}_t} \), its action on \( u \) gives rise to a fundamental vector field,

\[
\frac{d}{dt} \bigg|_t ua_t = \frac{d}{dr}_{r=0} ua_t a_t^{-1} a_r + t = (a_t^{-1} \dot{a}_t)^\ast(ua_t).
\]

By Itô’s formula applied to the product \( \tilde{x}^\epsilon_t g^\epsilon_t \),

\[
du^\epsilon_t = Tr_{g^\epsilon_t} \, d\tilde{x}^\epsilon_t + (TL_{(g^\epsilon_t)^{-1}} \circ dg^\epsilon_t) \ast (u^\epsilon_t).
\]

Since right translation of horizontal vectors are horizontal, the connection 1-form vanishes on the first term and \( \varpi(\circ du^\epsilon_t) = TL_{(g^\epsilon_t)^{-1}} \circ dg^\epsilon_t \).
We apply $\omega$ to the SDE for $u^\epsilon_t$,
\[
dg^\epsilon_t = T L g^\epsilon_t (\circ du^\epsilon_t) = T L g^\epsilon_t \omega \left( \frac{1}{\sqrt{\epsilon}} \sum_{k=1}^{N} A_k^\epsilon(u^\epsilon_t) \circ dw^k_t + \bar{A}^\epsilon(u^\epsilon_t)dt \right) = \frac{1}{\sqrt{\epsilon}} \sum_{k=1}^{m} g^\epsilon_k A_k \circ dw^k_t + g^\epsilon_t \bar{A}dt.
\]

There is a global solution to the above equation. The ODE $\frac{d}{dt} \tilde{x}^\epsilon_t = H g^\epsilon_t e_0$ has bounded right hand side and has a global solution. It follows that $u^\epsilon_t = \tilde{x}^\epsilon_t g^\epsilon_t$ has a global solution. \hfill $\square$

The stochastic process $(g^\epsilon_t)$ is a Markov process on $SO(n)$ with infinitesimal generator
\[
\mathcal{L}^\epsilon_G = \frac{1}{2\epsilon} \sum_{k=1}^{N} L g_{Ak} L g_{Ak} + L g_{\bar{A}}.
\]
If $\{A_k\}$ is an orthonormal basis of $\mathfrak{g}$, then $\mathcal{L}^\epsilon_G = \frac{1}{2\epsilon} \Delta^G + L g_{\bar{A}}$. Let $\mathcal{L}_G = \frac{1}{2} \sum_{k=1}^{N} L g_{Ak} L g_{Ak}$ so $\mathcal{L}^\epsilon_G = \frac{1}{\epsilon} \mathcal{L}_G + L g_{\bar{A}}$.

**Lemma 3.2.** Let $M$ be a complete Riemannian manifold with positive injectivity radius. Suppose that there are numbers $C > 0$ and $a_1 > 0$ such that $\sup_{\rho(x,y)\leq a_1} |\nabla \rho|(x,y) \leq C$. Let $T > 0$. The probability distributions of the family of stochastic processes $\{\tilde{x}^\epsilon_t, t \leq T\}$ is tight.

There is a metric $\tilde{d}$ on $M$ such that $\{(\tilde{x}^\epsilon_t)\}$ is equi Hölder continuous with exponent $\alpha < \frac{1}{2}$.

**Proof.** Let $\mu^\epsilon$ be the probability laws of $(\tilde{x}^\epsilon_t)$ on the path space over $OM$ with initial value $u_0$, which we denote by $C([0,T]; OM)$. Since $\tilde{x}^\epsilon_0 = u_0$ it suffices to estimate the modulus of continuity and show that for all positive numbers $a, \eta$, there exists $\delta > 0$ such that for all $\epsilon$ sufficiently small, see Billingsley [3] and Ethier-Kurtz [16],
\[
P(\omega : \sup_{\|s-t\|<\delta} d(\tilde{x}^\epsilon_t, \tilde{x}^\epsilon_s) > a) < \delta \eta.
\]

Here $d$ denotes a distance function on $OM$. We will choose a suitable distance function. The Riemannian distance function $\tilde{d}(x,y)$ is not smooth in $y$ if $y$ is in the cut locus of $x$. To avoid any assumption on the cut locus of $OM$ we construct a new distance function that preserves the topology of $OM$.

Let $2a$ be the minimum of $1, a_1$ and the injectivity radius of $M$. Let $\phi : \mathbb{R}_+ \rightarrow \mathbb{R}_+$ be a smooth concave function such that $\phi(r) = r$ when $r < a$ and $\phi(r) = 1$ when $r \geq 2a$. Let $\rho$ and $\bar{\rho}$ be respectively the
Riemannian distance on $M$ and $OM$. Then $\phi \circ \rho$ and $\phi \circ \tilde{\rho}$ are distance functions on $M$ and on $\tilde{M}$ respectively. Then for $r < t$,

$$\phi^2 \circ \tilde{\rho}(\tilde{x}_t^r, \tilde{x}_s^r) = \int_t^s D(\phi^2 \circ \tilde{\rho}(\tilde{x}_r^t, \cdot))_{\tilde{x}_r^t} (H_{\tilde{x}_r^t}(g_s^r e_0)) \, ds.$$  

Since $H_{\tilde{x}_r^t}(g_s^r e_0)$ has unit length, from the equation above we do not observe directly a uniform bound in $\varepsilon$.

For further estimates we work with a $C^2$ function $F : OM \to \mathbb{R}$ to simplify the notation. Also the computations below and some of the identities will be used later in the proof of Theorem 1.1. Let $0 \leq r < t,$

$$F(\tilde{x}_t^r) = F(\tilde{x}_s^r) + \int_r^s (DF)_{\tilde{x}_s^t}(H_{\tilde{x}_s^t}(g_s^r e_0)) \, ds. \tag{3.1}$$

Let $\{e_i\}$ be an orthonormal basis of $\mathbb{R}^n$. We define two sets of functions $f_i : OM \to \mathbb{R}$ and $h_i : G \to \mathbb{R}$:

$$f_i(u) = (DF)_u(H_{u} e_i), \quad \alpha_i(g) = \langle ge_0, e_i \rangle.$$  

From the linearity of $H_u$ we obtain the identity $H_u(ge_0) = \sum_{i=1}^{n} f_i(u) \alpha_i(u)$. Since the Riemannian metric on $SO(n)$ is bi-invariant the Riemannian volume measure, which locally has the form $\sqrt{\det(g_{ij})} dx^1 \wedge \cdots \wedge dx^n$, is the Haar measure. Let $dg$ be the Haar measure normalised to be a probability measure. Let $\tilde{g}$ be a vector such that $\tilde{g} e_0 = -e_0$. Then $\int_G g(\tilde{g} e_0) dg = \int_G g(e_0) dg$. The integral of $ge_0$ with respect to the Haar measure on $G$ vanishes. In particular $\int_G \alpha_i dg = 0$. On a compact Riemannian manifold the Poisson equation with a smooth function that is centred with respect to the Riemannian volume measure has a unique centred smooth solution. For each $i$, let $h_i : G \to \mathbb{R}$ be the smooth centred solution to the Poisson equation $L_G = \alpha_i$. We apply Itô’s formula to the function $f_i h_i$ and $r < t$,

$$f_i(\tilde{x}_t^r) h_i(g_t^r) = f_i(\tilde{x}_s^r) h_i(g_s^r) + \int_r^s (DF)_{\tilde{x}_s^t}(H_{\tilde{x}_s^t}(g_s^r e_0)) h_i(g_s^r) \, ds 
+ \frac{1}{\sqrt{\varepsilon}} \sum_{k} \int_r^s f_i(\tilde{x}_s^r)(Dh_i)(g_s^r)(g_s^r A_k) \, du^k_s
+ \int_r^s f_i(\tilde{x}_s^r)L_{g_s^r} h_i(g_s^r) \, ds + \frac{1}{\varepsilon} \int_r^s f_i(\tilde{x}_s^r)L_G h_i(g_s^r) \, ds.$$  

We sum up the above equation from $i = 1$ to $n$, since $\sum_{i=1}^n f_i(u) L_G h_i(g) = H_u(ge_0)$ we identify the last term as that in $F(\tilde{x}_t^r)$. Plug this back to $F(\tilde{x}_t^r)$ to see the following.
We also remark that for \( p \in E \) when for some constant \( T \) is a function that is \( BC \) that \( u = \sum \epsilon_i (\bar{F}(e, A) x \epsilon_i) = 0 \). If \( |H_{\bar{x}} e_i| = 1, |H_{\bar{x}} g_{s} e_i| = 1, |g_{s} | = |\bar{A}|. If F is a function that is \( BC^2 \), by the Kunita-Watanabe inequality, for any \( p \geq 1 \),

\[
\mathbb{E} \left| F(\bar{x}) - F(\bar{x'}) \right|^p \leq C_1(T) e^p (|DF|_\infty + |\nabla dF|_\infty) + C(T)|DF|_\infty |t - r|^{\frac{p}{2}},
\]

for some constant \( C_1(T) \). Hence \( \mathbb{E} \left| F(\bar{x}) - F(\bar{x'}) \right|^p \leq 2C_1(T)|t - r|^{\frac{p}{2}}, \) when \( \epsilon^2 \leq |t - r|. \) If \( |t - r| < \epsilon^2 \), we estimate directly from (3.1)

\[
|F(\bar{x}) - F(\bar{x'})| \leq C \frac{t - r}{\epsilon} \leq C \sqrt{t - r}.
\]
Thus, for $C(T) = 2C_1(T) + C^p$,
\[
\mathbb{E}\left| F(\tilde{x}_t^\epsilon) - F(\tilde{x}_r^\epsilon) \right|^p \leq C(T)|t - r|^\frac{p}{2}.
\]
We apply the above formula to $F = \phi^2 \circ \tilde{\rho}(\cdot, u_0)$ where $u_0 = \tilde{\rho}_0$. Since $\phi$ is bounded so is $F$. Since $|\nabla \tilde{\rho}(\cdot, u_0)| = 1$ and $\phi'$ is bounded, $\nabla F = 2\phi\phi' \nabla \tilde{\rho}(\cdot, u_0)$ is bounded. The norm of its second derivative is:
\[
|2(\phi')^2 \nabla \tilde{\rho} \otimes \nabla \tilde{\rho} + 2(\phi'') \nabla \tilde{\rho} \otimes \nabla \rho + 2(\phi') \nabla d\rho|,
\]
and the tensor is evaluated at $\rho(x, y)$. We remark that $\phi'(x, y) = 0$ when $\rho(x, y) \geq a$ and $|\nabla d\rho(\rho(x, y))| \leq C$ when $\rho(x, y) \geq a$. Hence for all $u_0$, there is a common number $C(T)$ s.t.
\[
\mathbb{E}\left| \tilde{d}(\tilde{x}_t^\epsilon, u_0) \right|^p \leq C(T)t^\frac{p}{2}.
\]
Conditioning on $\mathcal{F}_r$ to see that,
\[
\mathbb{E}\left| \tilde{d}(\tilde{x}_t^\epsilon, \tilde{x}_r^\epsilon) \right|^p \leq C(T)|t - r|^\frac{p}{2}.
\]
The tightness of the law of $\{\tilde{x}_t^\epsilon\}$ follows. By Kolmogorov’s criterion, $\{\tilde{x}_t^\epsilon\}$ is Hölder continuous with exponent $\alpha$ for any $\alpha < \frac{1}{2}$. The Hölder constants are independent of $\epsilon$ and, for any $p' < p$, Kolmogorov’s criterion yields
\[
(3.3) \quad \sup_{\epsilon} \mathbb{E}\sup_{s \neq t} \left( \frac{\tilde{d}(\tilde{x}_t^\epsilon, \tilde{x}_s^\epsilon)}{|t - s|^\alpha} \right)^{p'} < \infty,
\]
thus concluding the proof.

We will need the following lemma in which we make a statement on the limit of a function of two variables, one of which is ergodic and the other one varies significantly slower. The result is straightforward, but we include the proof for completeness. If $f : N \to \mathbb{R}$ is a Lipschitz continuous function on a metric space $(N, d)$ with distance function $d$, we denote by $|f|_{\text{Lip}}$ its Lipschitz semi-norm. If $S$ is a subset of $N$, we let $\text{Osc}_S(f)$ denote $|\sup_{x \in S} f(x) - \inf_{x \in S} f(x)|$, the Oscillation of $f$ over $S$. Let $\text{Osc}(f) = \text{Osc}_N(f)$.

Let $E(N)$ be one of the following classes of real valued functions on a metric space $(N, d)$,
\[
E(N) = \{ f : N \to \mathbb{R} : |f|_{\text{Lip}} < \infty, \text{Osc}(f) < \infty \}
\]
or $E_r(N) = E(N) \cap C^r$, where $r = 0, 1, \ldots, \infty$. Denote
\[
|f|_E = |f|_{\text{Lip}} + \text{Osc}(f).
\]
Let $d$ be the metric with respect to which the Lipschitz property is defined. We define $\bar{d} = d \wedge 1$ to be a new metric on $N$. Then $|f|_{Lip} \leq C$ and $Osc(f) \leq C$ is equivalent $f$ being Lipschitz with respect to $\bar{d}$.

Let $p > 1$ and let us denote the Wasserstein $p$-distance between two probability measures on a metric space with distance $d$ by $W_p(N)$:

$$(W_p(\mu_1, \mu_2))^p = \inf_{\nu : (\pi_1), \nu = \mu_1, (\pi_2), \nu = \mu_2} \int_{N \times N} (d(x, y))^p d\nu(x, y).$$

Let $\mu^t, \mu$ be a family of probability measures on the metric space $(N, d)$. Then $\mu^t \to \mu$ in $W_p(N)$ if and only if they converge weakly and $\sup_{x \in N} \int (d(x, y))^p d\mu^t(y)$ is bounded for any $x \in N$. If $\bar{d} = d \wedge 1$, then $\bar{d}$ and $d$ induce the same topology on $N$ and the concepts of weak convergence are equivalent. With respect to $d$, weak convergence is equivalent to Wasserstein $p$-convergence.

Let $(\Omega, \mathcal{F}, (\mathcal{F}_t), P)$ be a filtered probability space. Let $(Y, \rho)$, $(Z, d)$ be metric spaces or $C^m$ manifolds. Let $\{(y^t, t \leq T), t > 0\}$ be a family of $\mathcal{F}_t$-adapted stochastic processes with state space $Y$. Let $(z^t)$ be a family of sample continuous $\mathcal{F}_t$-Markov processes on $Z$.

**Assumption 3.3.** (1) The stochastic processes $(y^t, t \leq T)$ are equi uniformly continuous and converge weakly to a continuous process $(\bar{y}_t, t \leq T)$.

(2) For each $\epsilon$, $(z^t, t \leq T)$ has an invariant measure $\mu_\epsilon$. There exists a function $C$ on $\mathbb{R}_+ \times Z \times \mathbb{R}_+$ with the property that $\delta(\cdot, z, \epsilon)$ is non-decreasing for each pair of $(z, \epsilon)$ and $\lim_{\epsilon \to 0} \sup_{z \in Z} \delta(K, z, \epsilon) = 0$ for all $K$ and for all $f \in E_\epsilon(Z)$ and $t > 0$,

$$E \left| \frac{1}{t} \int_0^t f(z^t_{\epsilon}) ds - \int_Z f(z) d\mu_\epsilon(z) \right| \leq \delta(|f|^E, z_0, \epsilon, \frac{\epsilon}{t}).$$

(3) There exists a probability measure $\mu$ on $W^1(C([0, T]; Z))$ s.t. $\lim_{\epsilon \to 0} W_1(\mu_\epsilon, \mu) = 0$.

(4) The processes $(y^t_\epsilon)$ converges to $(\bar{y}_t)$ in $W_1(Z)$, and there exists an exponent $\alpha > 0$ such that

$$\sup_{\epsilon} E \left( \sup_{s \neq t} \frac{d(y^t_\epsilon, y^s_\epsilon)}{|t - s|^{\alpha}} \right) < \infty.$$ 

We cannot assume that $(\bar{y}_t)$ is adapted to the filtration with respect to which $(z^t)$ is a Markov process. The process $(z^t_\epsilon)$ is usually not convergent and we do not assume that $(y^t_\epsilon, z^t_\epsilon)$ and $(\bar{y}_t)$ are realized in the same probability space.
We denote by \( \hat{\eta} \) the probability distribution of a random variable \( \eta \) and let \( T \) be a positive real number. If \( r \) is a positive number, let \( C([0, r]; Y) \) denotes the space of continuous paths, \( \sigma : [0, r] \to Y \), on \( Y \). If \( F : C([0, r]; Y) \to \mathbb{R} \) is a Borel measurable function we use the shorter notation \( F(y_{r}^{\epsilon}) \) for \( F\left((y_{r}^{\epsilon}, u \leq r)\right) \).

**Lemma 3.4.** Let \((\Omega, \mathcal{F}, (\mathcal{F}_t), P)\) be a filtered probability space. Let \((Y, \rho), (Z, d)\) be metric spaces or \(C^m\) manifolds in case \( m \geq 1 \). Let \( \{(y_{\epsilon}^{\epsilon}, t \leq T), \epsilon > 0\} \) be a family of \( \mathcal{F}_t \)-adapted stochastic processes on \( Y \). Let \((z_{\epsilon}^{\epsilon}\}) \) be a family of sample continuous \( \mathcal{F}_t \)-Markov processes on \( Z \). Let \( G \in E_m(Y \times Z) \). Let \( 0 \leq r < t \) and let \( F : C([0, r]; Y) \to \mathbb{R} \) be a bounded continuous function. We define

\[
A(\epsilon) \equiv A(\epsilon, F, G) := F(y_{r}^{\epsilon}) \int_{r}^{t} G(y_{r}^{\epsilon}, z_{r}^{\epsilon})ds.
\]

- If (1)-(3) in Assumption 3.3 holds, then the random variables \( A(\epsilon) \) converge weakly to \( A \) as \( \epsilon \to 0 \), where

\[
A \equiv A(F, G) := F(\tilde{y}) \int_{r}^{t} \int_{Z} G(\tilde{y}, z) d\mu(z)ds.
\]

- Assume (1)-(4) in Assumption 3.3. Then there is a constant \( c \), s.t. for \( \epsilon < 1 \),

\[
W_1\left( \hat{\mathcal{P}}_{A(\epsilon)}, \hat{\mathcal{P}}_{A} \right) \leq c|F|_{\infty} \max_{z \in Z} \delta \left( |G|_{E}, z, \frac{\epsilon}{t-r} \right)
+ c(t-r)|F|_{\infty} |G|_{Lip} \left( \epsilon^\alpha + W_1\left( \hat{\mathcal{P}}_{y_{r}^{\epsilon}}, \hat{\mathcal{P}}_{\tilde{y}} \right) + W_1(\mu^\epsilon, \mu) \right).
\]

**Proof.** Let us fix the functions \( F, G, r, t \) and define:

\[
\mathcal{E}_1(r, t) = \int_{r}^{t} G(y_{r}^{\epsilon}, z_{r}^{\epsilon})ds - \int_{r}^{t} \int_{Z} G(y_{r}^{\epsilon}, z)d\mu(z)ds;
\]

\[
\mathcal{E}_2 = F(y_{r}^{\epsilon}) \left( \int_{r}^{t} \int_{Z} G(y_{r}^{\epsilon}, z)d\mu(z)ds - \int_{r}^{t} \int_{Z} G(y_{r}^{\epsilon}, z)d\mu(z)ds \right);
\]

\[
I(\epsilon) = F(\tilde{y}) \int_{r}^{t} \int_{Z} G(\tilde{y}, z)d\mu(z)ds;
\]

\[
I = F(\tilde{y}) \int_{r}^{t} \int_{Z} G(\tilde{y}, z)d\mu(z)ds.
\]

The proof is split into three parts: (i) \( F(y_{r}^{\epsilon})\mathcal{E}_1(r, t) \) converges to zero in \( L_p(\Omega) \) for any \( p > 1 \), (ii) \( \mathcal{E}_2 \) converges to zero in \( L_p(\Omega) \) for any \( p > 1 \), and (iii) \( I(\epsilon) \) converges to \( I \) weakly.
We first prove that \( F (y^r([0, \frac{t_1}{\epsilon}])) \int_0^t G(y^\epsilon_t, z^\epsilon_t)ds \) converges to zero in \( L_p(\Omega) \). Since \( F \) is bounded and \( (y^\epsilon_t, z^\epsilon_t) \) is a Markov process, it is sufficient to take \( r = 0 \) and \( F \) a constant, and to work with \( \mathcal{E}_1(0, r) \). Let us write

\[
\mathcal{E}_1 := \int_0^t G(y^\epsilon_t, z^\epsilon_t)ds - \int_0^t \int_{\mathcal{Z}} G(y^\epsilon_t, z)d\mu_\epsilon(z)ds.
\]

Let \( 0 = t_0 < t_1 < \cdots < t_M \leq t \) be a partition of \([0, t]\) into pieces of size \( t\epsilon \). Let \( M \equiv M_\epsilon [\frac{1}{\epsilon}] \). Let \( \Delta t_i = t_{i+1} - t_i \) and let \( \hat{t} = t\epsilon \). Below \( a \sim b \) indicates \('a - b = o(\epsilon)'\) as \( \epsilon \) converges to 0. Since \( G \) is bounded,

\[
\left| \int_0^t G(y^\epsilon_t, z^\epsilon_t)ds \right| \leq |G|_\infty (t - \hat{t}) \sim \epsilon |G|_\infty.
\]

By the Lipschitz continuity of \( G \), for each \( \epsilon > 0 \) the following holds.

\[
\mathcal{E}_4 := \left| \sum_{i=0}^{M_\epsilon - 1} \int_{t_i}^{t_{i+1}} G(y^\epsilon_t, z^\epsilon_{s\epsilon})ds - \sum_{i=0}^{M_\epsilon - 1} \int_{t_i}^{t_{i+1}} G(y^\epsilon_t, z^\epsilon_{s\epsilon})ds \right|
\leq |G|_{\text{Lip}} \sum_{i=0}^{M_\epsilon - 1} \int_{t_i}^{t_{i+1}} \rho (y^\epsilon_t, y^\epsilon_{s\epsilon})ds.
\]

By equi uniform continuity of \( (y^\epsilon_t) \), for almost surely all \( \omega \), \( \mathcal{E}_4 \) converges to zero. Since \( \mathcal{E}_4 \) is bounded the convergence is in \( L_p(\Omega) \). If \( (y^\epsilon_t) \) is assumed to be equi Hölder continuous as in condition (4), there is a convergence rate of \( \epsilon^a|G|_{\text{Lip}} \) for the \( L^p \) convergence.

We prove next that \( \sum_{i=0}^{M_\epsilon - 1} \int_{t_i}^{t_{i+1}} G(y^\epsilon_t, z^\epsilon_t)ds \) converges. We apply the Markov property of \( (z^\epsilon_t) \) and we use the fact that \( (y^\epsilon_t) \) is adapted to the filtration \( (\mathcal{F}_t) \), with respect to which \( (z^\epsilon_t) \) is a Markov process.

\[
\sum_{i=1}^{M_\epsilon - 1} \mathbb{E} \left| \int_{t_i}^{t_{i+1}} G(y^\epsilon_t, z^\epsilon_t)ds - \Delta t_i \int_{\mathcal{Z}} G(y^\epsilon_t, z)d\mu_\epsilon(z) \right|
\leq \sum_{i=1}^{M_\epsilon - 1} \Delta t_i \mathbb{E} \left( \mathbb{E} \left( \left| \frac{1}{\Delta t_i} \int_{t_i}^{t_{i+1}} G(y^\epsilon_t, z^\epsilon_t)ds - \int_{\mathcal{Z}} G(y^\epsilon_t, z)d\mu_\epsilon(z) \right| \middle| \mathcal{F}_{\hat{t}} \right) \right)
\leq \sum_{i=1}^{M_\epsilon - 1} \Delta t_i \mathbb{E} \left( \mathbb{E} \left( \left| \frac{\epsilon^2}{\Delta t_i} \int_{t_i}^{t_{i+1}} G(y, z^\epsilon_{s\epsilon})ds - \int_{\mathcal{Z}} G(y, z)d\mu_\epsilon(z) \right| \middle| y = y^\epsilon_{t_i} \right) \right).
\]
Since \( \frac{\epsilon^2}{\Delta t_i} = \frac{t}{t} \), we may now apply condition (2) and obtain
\[
E \left( \left| \int_{t_i}^{t_{i+1}} G(y, z_{\epsilon}) ds - \int_Z G(y, z) d\mu_\epsilon(z) \right| \right) 
\leq \delta \left( |G|_{E, z, \frac{\epsilon}{t}} \right) \leq \delta \left( |G|_{E, z, \frac{\epsilon}{t}} \right).
\]

We record that
\[
\mathcal{E}_5 := E \left| \sum_{i=0}^{M-1} \int_{t_i}^{t_{i+1}} G(y_{\frac{\epsilon}{t}}, z_{\epsilon}) ds - \sum_{i=0}^{M-1} \Delta t_i \int_Z G(y_{\frac{\epsilon}{t}}, z) d\mu_\epsilon(z) \right| \leq \max_{z \in Z} \delta \left( |G|_{E, z, \frac{\epsilon}{t}} \right).
\]

Let us define
\[
\mathcal{E}_6 := \sum_{i=0}^{M-1} \Delta t_i \int_Z G(y_{\frac{\epsilon}{t}}, z) d\mu_\epsilon(z) - \int_{0}^{t} \int_Z G(y_{\frac{\epsilon}{t}}, z) d\mu_\epsilon(z) ds.
\]

By the definition of Riemann integral
\[
\mathcal{E}_6 \leq |G|_{Lip} \sum_{i=0}^{M-1} \Delta t_i \text{Osc}_{[s_i, s_{i+1}]}(y_{\frac{\epsilon}{t}})
\]
where \( \text{Osc}_{[a,b]}(f) \) denotes the oscillation of a function \( f \) in the indicated interval. Since \( (y_{\frac{\epsilon}{t}}) \) is equiv uniform continuous on \([0, T]\), \( \mathcal{E}_6 \to 0 \) in \( L_p \). Given Hölder continuity of \( (y_{\frac{\epsilon}{t}}) \) from condition (4), we have the quantitative estimates: \( |\mathcal{E}_6|_{L_p(\Omega)} \leq C|G|_{Lip} \epsilon^\alpha \). It follows that
\[
F(y_{\frac{\epsilon}{t}}) \mathcal{E}_1(r, t) \to 0 \text{ in } L_p.
\]

When condition (4) holds, there is a constant \( C \) such that
\[
\left| F(y_{\frac{\epsilon}{t}}) \mathcal{E}_1(r, t) \right|_{L_p(\Omega)} \leq C(e^\alpha + \epsilon)|F|_{\infty} |G|_{Lip} + C|F|_{\infty} \max_{z \in Z} \delta \left( |G|_{E, z, \frac{\epsilon}{t}} \right).
\]

For any two random variables on the same probability space and with the same state space, the \( L_p \) norm of their difference dominates their Wasserstein \( p \)-distance. The random variable
\[
F(y_{\frac{\epsilon}{t}}) \int_t^s G(y_{\frac{\epsilon}{t}}, z_{\epsilon}) ds \to 0 \text{ as } \epsilon \to 0 \text{ in } L_p,
\]
with the same rate as indicated above.
We proceed to step (ii). It is clear that for almost all \( \omega \), \( F(y^*_z) \int_r^t G(y^*_z, z)ds \) is Lipschitz continuous in \( z \). For any \( z_1, z_2 \in Z \),

\[
\left| F(y^*_z) \int_r^t G(y^*_z, z_1)ds - F(y^*_z) \int_r^t G(y^*_z, z_2)ds \right|
\leq |F|_\infty d(z_1, z_2) \int_r^t |G(y^*_z, \cdot)|_{Lip} ds \leq (t - r) d(z_1, z_2) |F|_\infty |G|_{Lip}.
\]

By the Kantorovich duality formula, for the distance between two probability measures \( \mu_1 \) and \( \mu_2 \):

\[
W_1(\mu_1, \mu_2) = \sup \left\{ \int U d\mu_1 - \int U d\mu_2 : |U|_{Lip} \leq 1 \right\},
\]

we have

\[
|\mathcal{E}_2| \leq (t - r) \cdot |F|_\infty \cdot |G|_{Lip} \cdot W_1(\mu^t, \mu).
\]

For part (iii) let \( U \) be a continuous function on \( C([0, T]; Y) \). If \( \sigma \in C([0, T]; Y) \), let us denote by \( \sigma([0, r]) \) the restriction of the path to \([0, r]\). Since \( F \) is bounded continuous and \( G \) is Lipschitz continuous,

\[
\sigma \mapsto U \left( F(\sigma([0, r])) \left( \int_r^t \int_Z G(\sigma_s, z) d\mu(z) ds \right) \right)
\]

is a continuous function on \( C([0, T]; Y) \). By the weak convergence of \((y^*_z, E(U(I(\epsilon)))) \) converges to \( E(U(I)) \) and the random variables \( I(\epsilon) \) converge weakly to \( I \). By now we have proved that \( A(\epsilon, F, G) \) converges to \( A(F, G) \) weakly; we thus conclude the first part of the lemma.

Let us assume condition (4) from Assumption 3.3. In particular \((y^*_z) \) converges in \( W_1(C([0, T]; Y)) \). Let \( U \) be a Lipschitz continuous function on \( C([0, T]; Y) \). We define \( \tilde{U} : C([0, T]; Y) \rightarrow \mathbb{R} \) by

\[
\tilde{U}(\sigma) = U \left( F(\sigma([0, r])) \left( \int_r^t \int_Z G(\sigma_s, z) d\mu(z) ds \right) \right).
\]

Let \( \sigma^1, \sigma^2 \) are two paths on \( Y \),

\[
\left| \tilde{U}(\sigma_1) - \tilde{U}(\sigma_2) \right|
\leq |U|_{Lip} \cdot |F|_\infty \left| \int_r^t \int_Z G(\sigma^1_s, z) d\mu(z) ds - \int_r^t \int_Z G(\sigma^2_s, z) d\mu(z) ds \right|
\leq (t - r) |U|_{Lip} \cdot |F|_\infty \cdot |G|_{Lip} \cdot \sup_{0 \leq s \leq T} \rho(\sigma^1_s, \sigma^2_s).
\]

By Kantorovitch duality and Assumption (4),

\[
W_1 \left( \hat{P}_{I(\epsilon)}, \hat{P}_I \right) \leq (t - r) \cdot |F|_\infty \cdot |G|_{Lip} \cdot W_1 \left( \hat{P}_{y^*_z}, \hat{P}_{y^*_y} \right).
\]
We collect all the estimations together. Under Assumption (1-4), the following estimates hold.

\[
W_1 \left( \hat{P}_{A(\epsilon)}, \hat{P}_{A} \right) \leq C |F|_{\infty} |G|_{\text{Lip}}(\epsilon^\alpha + \epsilon) + C |F|_{\infty} \max_{z \in Z} \delta \left( |G|_{E, z}, \frac{\epsilon}{t-r} \right) + C(t-r) \cdot |F|_{\infty} \cdot |G|_{\text{Lip}} \cdot \left( W_1 \left( \hat{P}_{y^t}, \hat{P}_{\bar{y}} \right) + W_1(\mu_\epsilon, \mu) \right).
\]

We may now limit ourselves to \( \epsilon \leq 1 \) and conclude part (2) of the Lemma.

\[\square\]

**Remark 3.5.** In the lemma above we should really think that the \( z^\epsilon \) process and process \( y^\epsilon \) follow different clocks, the former is run at the fast time scale \( \frac{1}{\epsilon} \) and the latter at scale 1.

**Example 3.6.** Let \((g_s)\) be a Brownian motion on \( G = SO(n) \), solving

\[dg_t = \sum_{k=1}^{N} L_{g_t A_k} dw_t^k.\]

Here \( \{A_1, \ldots, A_N\} \) is an orthonormal basis of \( g \). In Lemma 3.4 we take \( z^\epsilon_t = g^\epsilon_t \), then condition (2) holds. If \( f \) is a Lipschitz continuous function, it is well known that the law of large numbers holds for \( \int_0^t f(g_s)ds \), so does a central limit theorem. The remainder term in the central limit theorem is of order \( \sqrt{t} \) and depends on \( f \) only through the Lipschitz constant \( |f|_{\text{Lip}} \).

It is easy to see that the remainder term in the law of large numbers depends only on the Lipschitz constant of the function. Without loss of generality we assume that \( \int f dg = 0 \). Let \( \alpha \) solve the Poisson equation:

\[\Delta^G \alpha = f.\]

Then

\[\frac{1}{t} \int_0^t f(g_s)ds = \frac{1}{t} \alpha(g_t) - \frac{1}{t} \alpha(g_0) - \sum_k \frac{1}{t} \int_0^t (D\alpha)(g_s A_k) dw_s^k.\]

Since \( \alpha \) is bounded, we are only concerned with the martingale term. By Burkholder-Davis-Gundy inequality, its \( L^2 \) norm is bounded by

\[
\frac{1}{t} \left( \sum_{k=1}^{N} \int_0^t \mathbb{E} \left( (D\alpha)(g_s A_k) \right)^2 \right)^{\frac{1}{2}} ds \leq \frac{\sqrt{N}}{\sqrt{t}} \int_0^t \mathbb{E} |D\alpha|_{g_s}^2 ds.
\]

By elliptic estimates, \( |D\alpha| \) is bounded by the \( |f|_{\text{Lip}} \). Since \( f \) is centred, it is bounded by \( \text{Osc}(f) \). In summary,

\[
\mathbb{E} \left( \frac{1}{t} \int_0^t f(g_s)ds - \int_N f(g)dg \right)^2 \leq \sqrt{N} \text{Osc}(f) t^{-\frac{1}{2}}.
\]
In Theorem 1.1 we may wish to add an extra drift of the form $\frac{1}{\epsilon}A^*$ where $A \in \mathfrak{g}$, so that $\mathcal{L}_G$ is $\frac{1}{2}\Delta^G + LgA$. Translations by orthogonal matrices are isometries, so for any $A \in \mathfrak{g}$ the vector field $gA$ is a killing field, and the Haar measure remains an invariant measure for the diffusion with infinitesimal generator $\frac{1}{2}\Delta^G + LgA$. However, on a compact Lie group no left invariant vector field is the gradient of a function and $\frac{1}{2}\Delta^G + LgA$ is no longer a symmetric operator. In this case we do not know how to obtain the estimate in the example.

4. Proof

We are ready to prove the main theorem. We use some ideas from Papanicolaou, Stroock, Varadhan [38, 37] and Hairer, Pavliotis [19].

Proof. We define a Markov generator $\bar{L}$ on $OM$. If $F : OM \to \mathbb{R}$ is bounded and Borel measurable and $\{e_i\}$ is an orthonormal basis of $\mathbb{R}^n$, we define

$$\bar{L}F = -\sum_{i=1}^{n} \int_{G} (\nabla DF)_u (H_u (ge_0), H_u (e_i)) h_i(g) dg$$

$$- \sum_{i=1}^{n} \int_{G} (DF)_u (H_u e_i) LgA h_i(g) dg.$$  \hfill (4.1)

Since $(\tilde{x}^t_{\epsilon})$ is tight by Lemma 3.2, every sub-sequence of $(\tilde{x}^t_{\epsilon})$ has a sub-sequence that converges in distribution. We will prove that the probability distributions of $(\tilde{x}^t_{\epsilon})$ converge weakly to the probability measure, $\bar{P}$, determined by $\bar{L}$. It is sufficient to prove that if $(\tilde{y}^t_{\epsilon})$ is a limit of $(\tilde{x}^t_{\epsilon})$, then

$$F(\tilde{y}_t) - F(u_0) - \int_0^t \bar{L}F(\tilde{y}_s) ds$$

is a martingale. Since the convergence is weak, and the Markov process $(\tilde{x}^t_{\epsilon}, g^t_{\epsilon})$ is not tight, we do not have a suitable filtration on $\Omega$ to work with. We formulate the above convergence on the space of continuous paths over $OM$ on a given time interval $[0, T]$.

Let $X_t$ be the coordinate process on the path space over $OM$, $\mathcal{G}_t = \sigma\{X_s : 0 \leq s \leq t\}$ and let $\bar{P}_{x^\epsilon}$ be the probability distribution of $(\tilde{x}^t_{\epsilon})$ on the path space over $OM$. By taking a subsequence if necessary, we may assume that $\{\bar{P}_{x^\epsilon}\}$ converges to $\bar{P}$. 
Let $F: OM \to \mathbb{R}$ be a smooth function with compact support. We will prove that with respect to $\bar{P}$,

$$
\mathbb{E} \left\{ (F(X_t) - F(X_r) - \int_r^t \bar{L}F(X_s)ds \mid \mathcal{G}_r) \right\} = 0.
$$

Since $\hat{P}_{\bar{x}_s} \to \bar{P}$ weakly, we only need to prove that for all bounded and continuous real value random variables $\xi$ that are measurable with respect to $\mathcal{G}_r$,

$$
(4.2) \lim_{\epsilon \to 0} \int \xi(F(X_t) - F(X_r))d\hat{P}_{\bar{x}_s} = \mathbb{E} \left( \xi \int_r^t \bar{L}F(X_s)dsd\bar{P} \right).
$$

By formula (3.2) in the proof of Lemma 3.2, for $t \geq r$,

$$
F(\bar{x}_s) - F(\bar{x}_r) \\
\sim - \epsilon \sum_{i=1}^n \int_r^t (\nabla DF)(\bar{x}_s)(H_{\bar{x}_s}(g_s^i e_0), H_{\bar{x}_s}(e_i)) h_i(g_s^i) ds
$$

$$
- \epsilon \sum_{i=1}^n \int_r^t (DF)(\bar{x}_s)(H_{\bar{x}_s}(e_i)) L_{g_s^i \bar{A}} h_i(g_s^i) ds
$$

$$
- \sqrt{\epsilon} \sum_{i=1}^n \sum_{k=1}^N \int_r^t (DF)(\bar{x}_s)(H_{\bar{x}_s}(e_i), Dh_{i}(g_s^i)(g_s^k A_k)) dw_s^k.
$$

Hence up to a term of order $\epsilon$,

$$
\int \xi(F(X_t) - F(X_r)) d\hat{P}_{\bar{x}_s}
$$

$$
= o(\epsilon) - \epsilon \sum_{i=1}^n \int \left( \xi \int_r^t (\nabla DF)_{X_s}(H_{X_s}(G_s e_0), H_{X_s}(e_i)) h_i(G_s) ds \right) d\hat{P}_{\bar{x}_s}
$$

$$
- \epsilon \sum_{i=1}^n \int \left( \xi \int_r^t (DF)_{X_s}(H_{X_s}(e_i)) L_{G_s \bar{A}} h_i(G_s) ds \right) d\hat{P}_{\bar{x}_s}.
$$

We prove this by working with the original processes. Let $(\bar{x}_s^\epsilon)$ denote a sub-sequence of the original sequence with limit $(\bar{y}_s)$. For each $i, l = 1, \ldots, n$, let us define

$$
\beta_{li}(u) = (\nabla DF)_u(H_u(e_l), H_u(e_i)).
$$
By linearity of $H_u$ and $\nabla DF$,
\[
(\nabla DF)_u (H_u(g_0), H_u(e_i)) h_i(g) \\
= \sum_{i=1}^n (\nabla DF)_u (H_u(e_i), H_u(e_i)) \langle g e_0, e_i \rangle h_i(g) \\
= \sum_{i=1}^n \beta_{li}(u) \langle g e_0, e_i \rangle h_i(g).
\]
for each $i = 1, \ldots, n$; and
\[
- \epsilon \int_t^\xi (\nabla DF)_{\bar{\xi}^\epsilon} (H_{\bar{\xi}^\epsilon}(g_0^\epsilon), H_{\bar{\xi}^\epsilon(s)}(e_i)) h_i(\bar{\xi}^\epsilon_s) \, ds \\
= -\epsilon \sum_{i=1}^n \int_t^\xi \beta_{li}(\bar{\xi}^\epsilon_s) \langle g_\epsilon^\epsilon, e_i \rangle h_i(g_\epsilon^\epsilon) \, ds \\
= -\sum_{i=1}^n \int_r^t \beta_{li}(\bar{\xi}^\epsilon_r) \langle g_\epsilon^\epsilon, e_i \rangle h_i(g_\epsilon^\epsilon) \, ds.
\]

We observe that $(g_\epsilon^\epsilon)$ satisfies the equation $dg_t = \sum_k g_t A_k \circ dw_t^k$ with initial value the identity. The solution stays in the connected component $SO(n)$. It is ergodic with the normalized Haar measure $dg$ on $SO(n)$ its invariant measure and satisfies Birkhoff Ergodic Theorem, see Example 3.6. By Lemma 3.2, $(\bar{\xi}^\epsilon_s)$ is tight, and equi uniformly Hölder continuous on $[0, T]$. In Assumption 3.3 we take $z_t^\epsilon = g_t^\epsilon$, $d\mu_\epsilon = dg$, $g_t^\epsilon = \bar{\xi}^\epsilon_t$ and check that conditions (1)- (4) are satisfied. In Lemma 3.4 we take $G(x, g) = \sum_{i=1}^n \beta_{li}(u) \langle g e_0, e_i \rangle h_i(g)$. Since the function $h_i : G \to \mathbb{R}$ are smooth and $G$ is compact, also $\beta_{li}$ are smooth and bounded by construction, we may apply Lemma 3.4. If $\phi$ is a bounded real valued continuous function on $C([0, r]; OM)$, let $\xi = \phi(\bar{\xi}^\epsilon_u, 0 \leq u \leq r)$. Then
\[
\lim_{\epsilon \to 0} \mathbb{E} \left( \xi \sum_{i=1}^n \int_t^\xi \beta_{li}(\bar{\xi}^\epsilon_s) \langle g_\epsilon^\epsilon, e_i \rangle h_i(g_\epsilon^\epsilon) \, ds \right) \\
= \sum_{i=1}^n \mathbb{E} \left( \xi \int_r^t \beta_{li}(\bar{\xi}_s) \, ds \right) \int_G \langle g e_0, e_i \rangle h_i(g) \, dg \\
= \sum_{i=1}^n \mathbb{E} \left( \xi \int_r^t \nabla DF_{\bar{\xi}_s} (H_{\bar{\xi}_s}(e_i), H_{\bar{\xi}_s}(e_i)) \right) \int_G \langle g e_0, e_i \rangle h_i(g) \, dg \\
= \sum_{i=1}^n \mathbb{E} \left( \xi \int_r^t \int_G \nabla DF_{\bar{\xi}_s} (H_{\bar{\xi}_s}(g e_0), H_{\bar{\xi}_s}(e_i)) h_i(g) \, dg \right).
For the same reasoning, we also have,

\[
\lim_{\epsilon \to 0} \mathbb{E} \left( \xi \int_{t}^{t+\epsilon} (DF)x_{s} \left( H_{x_{s}} e_{i} \right) L_{g_{s}h_{i}(g_{s})} \right) = \mathbb{E} \left( \xi \int_{0}^{t} (DF)g_{s} \left( H_{g_{s}} e_{i} \right) ds \int_{G} L_{g} \bar{h}_{i}(g) dg \right).
\]

We have proved (12). Since every sub-sequence of \( \hat{P}_{x} \) has a sub-sequence that converges to the same limit, we have proved \( \hat{P}_{x} \to \bar{P} \) weakly. To identify the limit \( \bar{\mu} \) we take \( G = SO(n) \). For \( g \in G \), we define

\[
\bar{h}_{i}(g) = \frac{4}{n-1} \langle ge_{0}, e_{i} \rangle.
\]

Let us first work on the first order term,

\[
L_{g} \bar{h}_{i} = \frac{4}{n-1} \langle g \bar{A} e_{0}, e_{i} \rangle
\]

and compute the following integral:

\[
\int_{G} (DF)u(H_{u} e_{i}) L_{g} \bar{h}_{i}(g) dg = -\frac{4}{n-1} \int_{G} (DF)u(H_{u} g \bar{A} e_{0}) dg
\]

\[
= -\frac{4}{n-1} (DF)u \left( H_{u} \left( \int_{G} g \bar{A} e_{0} dg \right) \right) = 0.
\]

Next we compute

\[
\mathcal{L}_{G} h_{i} = \frac{1}{2} \sum_{k=1}^{N} L_{g_{A_{k}}} L_{g_{A_{k}}} h_{i} = -\frac{2}{n-1} \sum_{k=1}^{N} \langle g(A_{k})^{2} e_{0}, e_{i} \rangle.
\]

Since \( \sum_{k=1}^{N} (A_{k})^{2} = -\frac{n-1}{2} I \), we conclude that \( \mathcal{L}_{G} h_{i} = \langle ge_{0}, e_{i} \rangle \). Let us define

\[
a_{i,j}(e_{0}) = -\int_{G} \langle ge_{0}, e_{j} \rangle \frac{1}{2} (\Delta^{G})^{-1} \langle ge_{0}, e_{i} \rangle dg
\]

\[
= \frac{4}{n-2} \int_{G} \langle ge_{0}, e_{j} \rangle \langle ge_{0}, e_{i} \rangle dg.
\]

We first prove that \( a_{i,j}(e_{0}) \) is independent of \( e_{0} \). Let \( e_{0}' \in \mathbb{R}^{n} \) we take \( O \) such that \( O e_{0}' = e_{0} \). By the right invariant property of the Haar measure,

\[
\int_{G} \langle ge_{0}', e_{j} \rangle \langle ge_{0}', e_{i} \rangle dg = \int_{G} \langle gOe_{0}, e_{j} \rangle \langle gOe_{0}, e_{i} \rangle dg = \int_{G} \langle ge_{0}, e_{j} \rangle \langle ge_{0}, e_{i} \rangle dg.
\]
We first compute the case of $i \neq j$ and $n = 2$.

$$a_{1,2}(e_1) = \int_{SO(2)} \langle ge_1, e_2 \rangle \langle ge_1, e_2 \rangle dg = - \int_0^{2\pi} \cos(\theta) \sin(\theta) d\theta = 0.$$  

If $n > 2$, for any $i \neq j$, there is an element $O \in G$ such that $Oe_i = -e_i$ and $Oe_j = e_j$. For example if $i = 1, j = 2$, we take $O = (-e_1, e_2, -e_3, e_4, \ldots, e_n)$. So

$$\int_G \langle ge_0, e_j \rangle \langle ge_0, e_i \rangle dg = - \int_G \langle ge_0, Oe_j \rangle \langle ge_0, Oe_i \rangle dg = - \int_G \langle ge_0, e_j \rangle \langle ge_0, e_i \rangle dg.$$  

Thus $a_{i,j} = 0$ if $i \neq j$. Let

$$C_i = \int_G \langle ge_0, e_i \rangle^2 dg.$$  

For $i = 1, \ldots, n$, $C_i = \int_G \langle ge_0, e_i \rangle^2 dg$ is independent of $i$ and

$$\int_G \sum_{i=1}^n \langle ge_0, e_i \rangle^2 dg = 1$$  

and consequently $C_i = \frac{1}{n}$. The non-zero values of $(a_{i,j})$ are:

$$a_{i,i} = \frac{4}{n-1} \int_G \langle ge_0, e_i \rangle^2 dg = \frac{4}{(n-1)n}.$$  

By the definition, $\Delta_H F = \sum_{i=1}^n L_{H(e_i)} L_{H(e_i)}^{-1} \langle ge_0, e_i \rangle^2$; we see that

$$\bar{L}F = - \sum_{i,j} \int_G \nabla dF \langle H(u)e_j, H(u)e_i \rangle \langle ge_0, e_j \rangle L_{G^{-1}}^{-1} \langle ge_0, e_i \rangle dg$$  

$$= \frac{4}{(n-1)n} \sum_{i=1}^n \nabla dF(h_u(ue_i), h_u(ue_i))$$  

$$= \frac{4}{(n-1)n} \Delta_H.$$  

We conclude that $(\tilde{x}^t)$ is a diffusion process with infinitesimal generator $\frac{4}{(n-1)n} \Delta_H$. Since $(\tilde{x}^t)$ is the projection of $(\tilde{x}^t)$ and it is also convergent.

The operators $\Delta^H$ and $\Delta$ are intertwined by $\pi$; for $f : M \to \mathbb{R}$ smooth, $(\Delta^H f) \circ \pi = \Delta(f \circ \pi)$. See e.g. Theorem 4C of Chapter II in Elworthy [10] and also Elworthy, LeJan, Li [13]; $\Delta_H$ is cohesive and a horizontal operator in the terminology of [13] and is the horizontal lift of $\Delta$. We see that $(\tilde{x}^t)$ converges to a process with generator $\frac{4}{(n-1)n} \Delta$. We have completed the proof of Theorem 1.1. \qed
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