Research Article Open Access

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Bakry-Émery Conditions on Almost Smooth Metric Measure Spaces

https://doi.org/10.1515/agms-2018-0007
Received June 29, 2018; revised September 14, 2018; accepted September 24, 2018

Abstract: In this short note, we give a sufficient condition for almost smooth compact metric measure spaces to satisfy the Bakry-Émery condition \( \text{BE}(K, N) \). The sufficient condition is satisfied for the glued space of any two (not necessary same dimensional) closed pointed Riemannian manifolds at their base points. This tells us that the BE condition is strictly weaker than the RCD condition even in this setting, and that the local dimension is not constant even if the space satisfies the BE condition with the coincidence between the induced distance by the Cheeger energy and the original distance. In particular, the glued space gives a first example with a Ricci bound from below in the Bakry-Émery sense, whose local dimension is not constant. We also give a necessary and sufficient condition for such spaces to be RCD\((K, N)\) spaces.

Keywords: Ricci curvature; Metric measure space

MSC: 53C21

1 Introduction

Let \((X, d, m)\) be a compact metric measure space, that is, \((X, d)\) is a compact metric space with \(\text{supp } m = X\) and \(m(X) < \infty\). There are several definitions of ‘lower Ricci bounds on \((X, d, m)\)’, whose studies are very quickly, widely developed now. We refer to, [36] by Lott-Villani, [38] by Sturm, and [2] by Ambrosio-Gigli-Savaré, as their pioneer works.

In this paper, we focus on two of them. One of them is the Bakry-Émery (BE) condition [12] by Bakry-Émery, denoted by \(\text{BE}(K, N)\), the other is the Riemannian curvature dimension (RCD) condition [2] by Ambrosio-Gigli-Savaré (in the case when \(N = \infty\)), [26] by Gigli (in the case when \(N < \infty\)), denoted by \(\text{RCD}(K, N)\). Both notions give us meanings that the Ricci curvature of \((X, d, m)\) is bounded below by \(K\), and the dimension of \((X, d, m)\) is bounded above by \(N\) in synthetic sense. The \(\text{BE}(K, N)\) condition is roughly stated by:

\[
\frac{1}{2} \Delta |\nabla f|^2 \geq \frac{(\Delta f)^2}{N} + \langle \nabla \Delta f, \nabla f \rangle + K |\nabla f|^2
\]  

(1.1)

holds in a weak form for all ‘nice’ functions \(f\) on \(X\) (Definition 2.1). It is known that if \((X, d)\) is a \(n\)-dimensional smooth Riemannian manifold \((M^n, g)\) and \(m\) is the Riemannian (or equivalently, the Hausdorff) measure, then, the \(\text{BE}(K, N)\) condition (1.1) is equivalent to satisfying \(n \leq N\) and \(\text{Ric}_{M^n} \geq K\), and that the \(\text{BE}(K, N)\) condition is also equivalent to some gradient estimates on the heat flow, so called Bakry-Émery/Bakry-Ledoux gradient estimates.

In general, the implication from \(\text{RCD}(K, N)\) to \(\text{BE}(K, N)\) is always satisfied. The inverse is true under adding a some property, so-called the ‘Sobolev to Lipschitz property’, which is introduced in [26] (Definition 2.2). This property (with BE), in a point of view in geometric analysis, plays a role to get the coincidence between the analytic distance \(d_{\text{ch}}\) (that is, the induced distance by the Cheeger energy) and the original (ge-
ometric) distance $d$. Moreover, the RCD condition also implies the Sobolev to Lipschitz property. Thus, the following equivalence is known:

$$ RCD(K, N) \iff \text{BE}(K, N) + \text{‘Sobolev to Lipschitz property’}. \quad (1.2) $$

The RHS of (1.2) is also called the metric BE$(K, N)$ condition. Thus, to keep the short presentation, we adopt the RHS of (1.2) as the definition of RCD$(K, N)$ condition in this paper (Definition 2.2). We refer to [3] by Ambrosio-Gigli-Savare’, [9], [7] by Ambrosio-Mondino-Savare’, and [25] by Erbar-Kuwada-Sturm for the details.

In these observation, more precisely, ‘RCD’ should be replaced by ‘RCD’*. However, since the equivalence between RCD and RCD* spaces is also recently established in [18] by Cavalletti-Milman, we use the notation ‘RCD’ only for simplicity.

In this paper, we discuss the condition:

$$ \text{BE}(K, N) + d_{CB} = d. \quad (1.3) $$

One of the goals in this paper is to provide an example satisfying (1.3), but it is not an RCD space. More precisely, for any two (not necessary same dimensional) closed pointed Riemannian manifolds $(M_i^{m_i}, g_i, p_i)(m_i \geq 2)$, the glued metric space $M_1^{m_1} \ast M_2^{m_2}$ at their base points with the standard measure is a BE$(K, \max\{m_1, m_2\})$ space, where $K := \min\{\inf\text{Ric}^{\tilde{g}_i}_{M_i^{m_i}}, \inf\text{Ric}^{\tilde{g}_i}_{M_i^{m_i}}\}$ (Example 3.18). It is easy to check that this metric measure space does not satisfy the Sobolev to Lipschitz property, thus, it is not a RCD$(L, \infty)$ space for any $L \in \mathbb{R}$.

This tells us that (1.3) does not imply the expected Bishop-Gromov inequality (Remark 3.9), and that (1.3) does not imply the constancy of the local dimension. In particular, the glued space gives a first example with a Ricci bound from below in the Bakry-Émery sense, whose local dimension is not constant. We point out a very recent result in [16] by Bruè-Semola, which states that for any RCD$(K, N)$ space, there exists a unique $k$ such that the $k$-dimensional regular set $\mathcal{R}_k$ has positive measure. This generalizes a result of Colding-Naber in [23] for Ricci limit spaces to RCD spaces. Thus, we know that the Sobolev-Lipschitz property is crucial to get the constant dimensional property. Note that in [34], Ketterer-Rajala constructed a metric measure space with the measure contraction property (MCP), which also characterize ‘Ricci bounds from below’ in a synthetic sense, but the local dimension is not constant. Therefore, in general, MCP and BE spaces are very different from RCD spaces.

Moreover, we should pay attention to a similar sufficient condition in [7] by Ambrosio-Mondino-Savare’, so-called the local to global property, which states in our compact setting; if $(X, d)$ is a geodesic (or equivalently, length) space and there exists an open covering $\{U_i\}_{i \in I}$ of $X$ such that $U_i \neq \emptyset$ and that $(U_i, d, m_i)$ satisfies the metric BE$(K, N)$ condition, then, $(X, d, m)$ satisfies the metric BE$(K, N)$ condition. In fact, the glued example shows that the openness of $U_i$ is essential because although $U_i := M_i^{m_i}$ in $M_1^{m_1} \ast M_2^{m_2}$ satisfies the assumptions except for their openness properties, but the glued space does not satisfy the metric BE$(K, N)$ condition for all $K, N$.

In order to justify these, we study almost smooth compact metric measure spaces. See Definition 3.1 for the definition, which allows us such spaces to have at least the codimension 2 singularities. Thus, compact (Riemannian) orbifolds with the Hausdorff measure are typical examples of them. Then, the main result in this paper is roughly stated as follows; if an almost smooth compact metric measure space satisfies the $L^2$-strong compactness condition and satisfies the gradient estimates on the eigenfunctions, then, a lower bound of the Ricci tensor of the smooth part implies a BE condition (Theorem 3.7). By using this, we can give a necessary and sufficient condition for such a space to be a RCD space (Corollary 3.10).

The organization of the paper is as follows.

In section 2, to keep the short presentation, we give a very quick introduction to calculus on metric measure spaces.

In section 3, we study our main targets, almost smooth metric measure spaces, and prove the main results.
2 BE and RCD spaces

We use the notation $B_r(x)$ for open balls and $\overline{B}_r(x)$ for $\{y : d(x, y) \leq r\}$. We also use the standard notation $\text{LIP}(X, d)$, $\text{LIP}_c(X, d)$ for the spaces of Lipschitz, compactly supported Lipschitz functions, respectively.

Let us now recall basic facts about Sobolev spaces in metric measure spaces $(X, d, m)$, see [1], [27] and [28] for a more systematic treatment of this topic. We shall always assume that

- the metric space $(X, d)$ is compact with $\text{supp } m = X$ and $m(X) < \infty$

for simplicity.

The Cheeger energy $\text{Ch} = \text{Ch}_{d, m} : L^2(X, m) \to [0, +\infty]$ is a convex and $L^2(X, m)$-lower semicontinuous functional defined as follows:

$$\text{Ch}(f) := \inf \left\{ \lim\inf_{n \to \infty} \frac{1}{2} \int_X (\text{Lip} f_n)^2 \, dm : f_n \in \text{Lip}(X, d), \|f_n - f\|_{L^2} \to 0 \right\},$$

where $\text{Lip} f$ is the so-called slope, or local Lipschitz constant.

The Sobolev space $H^{1,2}(X, d, m)$ then coincides with $\{f : \text{Ch}(f) < +\infty\}$. When endowed with the norm

$$\|f\|_{H^{1,2}} := \left( \|f\|_{L^2(X, m)}^2 + 2\text{Ch}(f) \right)^{1/2}$$

this space is Banach, reflexive if $(X, d)$ is doubling (see [8]), and separable Hilbert if $\text{Ch}$ is a quadratic form (see [2]). According to the terminology introduced in [27], we say that a metric measure space $(X, d, m)$ is infinitesimally Hilbertian if $\text{Ch}$ is a quadratic form.

By looking at minimal relaxed slopes and by a polarization procedure, one can then define a $\text{carré du champ}$

$$\Gamma : H^{1,2}(X, d, m) \times H^{1,2}(X, d, m) \to L^1(X, m)$$

playing in this abstract theory the role of the scalar product between gradients (more precisely, the duality between differentials and gradients, see [27]). In infinitesimally Hilbertian metric measure spaces, the $\Gamma$ operator satisfies all natural symmetry, bilinearity, locality and chain rule properties, and provides integral representation to $\text{Ch}$: $2\text{Ch}(f) = \int_X \Gamma(f, f) \, dm$ for all $f \in H^{1,2}(X, d, m)$.

We can now define a densely defined operator $\Delta : D(\Delta) \to L^2(X, m)$ whose domain consists of all functions $f \in H^{1,2}(X, d, m)$ satisfying

$$\int_X hg \, dm = \int_X \Gamma(f, h) \, dm \quad \forall h \in H^{1,2}(X, d, m)$$

for some $g \in L^2(X, m)$. The unique $g$ with this property is then denoted by $\Delta f$ (see [1]).

From the point of view of Riemannian geometry, we will also adopt the following notation instead of $\Gamma$;

$$\langle \nabla f, \nabla g \rangle := \Gamma(f, g), \quad |\nabla f|^2 := \Gamma(f, f).$$

We are now in a position to introduce the $\text{BE}(K, N)$ condition (see [9], [7] and [25]):

**Definition 2.1 (BE spaces).** Let $(X, d, m)$ be a compact metric measure space, let $K \in \mathbb{R}$ and let $N \in [1, \infty]$. We say that $(X, d, m)$ is a $\text{BE}(K, N)$ space if for all $f \in D(\Delta)$ with $\Delta f \in H^{1,2}(X, d, m)$, Bochner’s inequality

$$\frac{1}{2} |\nabla f|^2 \geq \frac{(\Delta f)^2}{N} + \langle \nabla f, \nabla \Delta f \rangle + K |\nabla f|^2$$

holds in the weak form, that is,

$$\frac{1}{2} \int_X |\nabla f|^2 \Delta \varphi \, dm \geq \int_X \varphi \left( \frac{(\Delta f)^2}{N} + \langle \nabla f, \nabla \Delta f \rangle + K |\nabla f|^2 \right) \, dm$$

for all $\varphi \in D(\Delta) \cap L^\infty(X, m)$ with $\varphi \geq 0$ and $\Delta \varphi \in L^\infty(X, m)$. 

In order to introduce the class of RCD\((K, N)\) metric measure spaces, we follow the \(\Gamma\)-calculus point of view, based on Bochner’s inequality, because this is the point of view more relevant in our proofs. However, the equivalence with the Lagrangian point of view, based on the theory of optimal transport first proved in [3] (in the case \(N = \infty\)) and then in [25], [9] (in the case \(N < \infty\)). Moreover, the following definition should be written as RCD\((K, N)\) spaces. However, since it is known by [18] that these are equivalent notions, we use the notation RCD\((K, N)\) only for simplicity.

**Definition 2.2** (RCD spaces). Let \( (X, d, m) \) be a compact metric measure space, let \( K \in \mathbb{R} \) and let \( N \in [1, \infty] \). We say that \( (X, d, m) \) is a RCD\((K, N)\) space if it is a BE\((K, N)\) space with the Sobolev to Lipschitz property, that is,

- (Sobolev to Lipschitz property) any \( f \in H^{1,2}(X, d, m) \) with \( |\nabla f| \leq 1 \) m-a.e. in \( X \) has a 1-Lipschitz representative.

We end this section by giving the definition of local Sobolev spaces:

**Definition 2.3** (Sobolev spaces \( H^{1,2}_0(U) \)). Let \( U \) be an open subset of \( X \). We denote by \( H^{1,2}_0(U, d, m) \) the \( H^{1,2} \)-closure of \( \text{LIP}_c(U, d) \).

In the next section, the local Sobolev spaces will play a role to localize global Sobolev functions to smooth parts via the zero capacity condition.

## 3 Almost smooth metric measure space

Let us fix a compact metric measure space \((X, d, m)\).

### 3.1 Constant dimensional case

**Definition 3.1** (\(n\)-dimensional almost smooth compact metric measure space). Let \( n \in \mathbb{N} \). We say that \((X, d, m)\) is an \(n\)-dimensional almost smooth compact metric measure space associated with an open subset \(\Omega\) of \(X\) if the following three conditions are satisfied;

1. (Smoothness of \(\Omega\)) there exist an \(n\)-dimensional (possibly incomplete) Riemannian manifold \((M^n, g)\) and a map \(\varphi : \Omega \to M^n\) such that \(\varphi\) is a local isometry between \((\Omega, d)\) and \((M^n, d_g)\), that is, for all \(p \in \Omega\) there exists an open neighborhood \(U \subset \Omega\) of \(p\) such that \(\varphi|_U\) is an isometry from \(U\) to \(\varphi(U)\) as metric spaces;
2. (Hausdorff measure condition) The restriction \(m|_\Omega\) of \(m\) to \(\Omega\) coincides with the \(n\)-dimensional Hausdorff measure \(\mathcal{H}^n\) on \(\Omega\), that is, \(m(A) = \mathcal{H}^n(A)\) holds for all Borel subset \(A\) of \(\Omega\);
3. (Zero capacity condition) \(X \setminus \Omega\) has zero capacity in the following sense, that is, \(m(X \setminus \Omega) = 0\) is satisfied, there exists a sequence \(\varphi_i \in C^\infty_c(\Omega)\) such that the following two conditions hold;
   (a) for any compact subset \(A \subset \Omega\), \(\varphi_i|_A \equiv 1\) holds for all sufficiently large \(i\);
   (b) it holds that \(0 \leq \varphi_i \leq 1\) and that
   \[
   \sup_i \int_\Omega |\Delta \varphi_i| d\mathcal{H}^n < \infty. \tag{3.1}
   \]

The zero capacity condition is a kind of that ‘\(H^{1,2}\)-capacity of \(X \setminus \Omega\) is zero’ whose standard definition is given by replacing (3.1) by

\[
\int_\Omega |\nabla \varphi_i|^2 d\mathcal{H}^n \to 0 \quad (i \to \infty). \tag{3.2}
\]

See [35]. In particular, (3.2) is satisfied if \(\|\Delta \varphi_i\|_{L^1} \to 0\). Compare with (2) of Proposition 3.3.
Remark 3.2. Whenever we discuss ‘analysis/geometry on Ω locally’, we can identify (Ω, d) with the smooth Riemannian manifold \((M^n, g)\) (thus, sometimes, we will use the notations \((Ω, g), \text{Ric}_0^n\) and so on). Note that for all \(p \in M^n\) and all sufficiently small \(t > 0, B_t^g(p)\) is convex and it has a uniform lower bound on Ricci curvature. In particular, the volume doubling condition and the Poincaré inequality hold locally. Thus, Cheeger’s theory [19] can be applied locally. In particular, the Lipschitz-Lusin property holds for all \(f \in H^{1,2}(X, d, m)\) (this notion is equivalent to that of differentiability of functions introduced in [31]), that is, for all \(ε > 0\), there exists a Borel subset \(A\) of \(Ω\) such that \(m(Ω \setminus A) < ε\) and that \(f|_A\) is Lipschitz. Combining this with the locality property of the slope on both theories in [1], in [19], yields

\[
|\nabla f|(x) = |\nabla φ(f \circ φ^{-1})|(φ(x)) \quad \mathcal{H}^n - \text{a.e} x \in Ω,
\]

where the RHS means the minimal weak upper gradient in [19].

Let us give a quick proof of (3.3) for reader’s convenience. By the Lipschitz-Lusin property with the localities of slopes as mentioned above, it suffices to check that under assuming \(f \in \text{LIP}(X, d)\), the LHS of (3.3) is equal to \(\text{Lipf}\) for \(m\)-a.e. \(x \in X\). Moreover, since it follows from [1] that \(|f|(x) \leq \text{Lipf}(x)\) \(m\)-a.e. \(x \in X\), let us check the converse inequality.

Let \(x \in Ω\) and fix any sufficiently small \(r > 0\) as above. Note that by [19], if \(f_i \in \text{LIP}(B_r(x), d)\) \(L^2\)-strongly converge to \(f\) on \(B_r(x)\), then

\[
\liminf_{i \to \infty} \int_{B_r(x)} (\text{Lip}f_i)^2 d\mathcal{H}^n \geq \int_{B_r(x)} (\text{Lip}f)^2 d\mathcal{H}^n.
\]

(3.4)

On the other hand, by [2], there exists a sequence \(F_i \in \text{LIP}(X, d)\) such that \(F_i, \text{Lip}F_i \to f, |∇f|\) in \(L^2(X, m)\), respectively. Applying (3.4) for \(f_i = F_i\) shows

\[
\int_{B_r(x)} |∇f_i|^2 d\mathcal{H}^n \geq \int_{B_r(x)} (\text{Lip}F_i)^2 d\mathcal{H}^n.
\]

Since \(r\) is arbitrary, we have the converse inequality, \(|∇f|(x) \geq \text{Lipf}(x)\) \(m\)-a.e. \(x \in X\), which completes the proof.

Similarly, the Sobolev space \(H^{1,2}_0(M^n, g, \mathcal{H}^n)\), which is defined by the standard way in Riemannian geometry (that is, the \(H^{1,2}\)-closure of \(C_c^∞(M^n)\)), coincides with \(H^{1,2}_0(Ω, d, m)\). We will immediately use these compatibilities below.

From now on, we use the same notation as in Definition 3.1 (e.g. \(Ω, φ_i\)) without any attention.

**Proposition 3.3.** Let \((X, d, m)\) be an \(n\)-dimensional almost smooth compact metric measure space. Then

1. \(φ_i \to 1\) in \(L^1(X, m)\) with \(\sup_i \|φ_i\|_{L^1} < \infty\);
2. the canonical inclusion map \(ι : H^{1,2}_0(Ω, d, \mathcal{H}^n) \hookrightarrow H^{1,2}(X, d, \mathcal{H}^n)\) is an isometry. In particular \((X, d, \mathcal{H}^n)\) is infinitesimally Hilbertian.

**Proof.** Since \(φ_i(x) \to 1\) \(m\)-a.e. \(x \in X\), applying the dominated convergence theorem shows that \(φ_i \to 1\) in \(L^1(X, m)\). Moreover, since

\[
\int_Ω |∇φ_i|^2 d\mathcal{H}^n = -\int_Ω φ_i Aφ_i d\mathcal{H}^n \leq \int_Ω |Aφ_i| d\mathcal{H}^n,
\]

we have (1).

Next, let us check (2). It is trivial that the map \(ι\) preserves the distances (we identify \(H^{1,2}_0(Ω, d, m)\) with the image by \(ι\) for simplicity). As written in Remark 3.2, it also follows from the smoothness of \(Ω\) that \(H^{1,2}_0(Ω, d, m)\) is a Hilbert space, and that \(φf \in H^{1,2}_0(Ω, d, m)\) for all \(f \in \text{LIP}(X, d)\).

Fix \(f \in \text{LIP}(X, d)\). Then, since

\[
\int_X |∇(φf)|^2 dm \leq \int_X \left(2|∇f|^2 + 2|f|^2 |∇φ|^2\right) dm,
\]
we have \( \sup_i \| \varphi_i f \|_{H^{1,2}} < \infty \). Therefore, since \( \varphi_i f \to f \) in \( L^2(X, m) \), Mazur’s lemma yields \( f \in H_0^{1,2}(\Omega, d, m) \).

In particular,
\[
\text{Ch}(\varphi + \psi) + \text{Ch}(\varphi - \psi) = 2\text{Ch}(\varphi) + 2\text{Ch}(\psi) \quad \forall \varphi, \psi \in \text{LIP}(X, d).
\]

(3.5)

By [1], for all \( F, G \in H^{1,2}(X, d, m) \), there exist sequences \( F_i, G_i \in \text{LIP}(X, d) \) such that \( F_i, G_i \to F, G \) in \( L^2(X, m) \), respectively and that \( \text{Ch}(F_i), \text{Ch}(G_i) \to \text{Ch}(F), \text{Ch}(G) \), respectively. Then, letting \( i \to \infty \) in the equality (3.5) for \( \varphi = F_i, \psi = G_i \) with the lower semicontinuity of the Cheeger energy shows

\[
\text{Ch}(F + G) + \text{Ch}(F - G) \leq 2\text{Ch}(F) + 2\text{Ch}(G).
\]

(3.6)

Replacing \( F, G \) by \( F + G, F - G \), respectively yields the converse inequality, that is, we have the equality in (3.6) for \( \varphi = F, \psi = G \), which proves that \( H^{1,2}(X, d, m) \) is a Hilbert space. Thus, by [2], \( \text{LIP}(X, d) \) is dense in \( H^{1,2}(X, d, m) \).

Since we already proved that \( \text{LIP}(X, d) \subset H_0^{1,2}(\Omega, d, m) \), we conclude.

\[ \square \]

Remark 3.4. Recall that if \( u_i \) \( L^2 \)-weakly converge to \( u \) in \( L^2(X, m) \) with \( \sup_i \| u_i \|_{H^{1,2}} < \infty \), then we see that \( u \in H^{1,2}(X, d, m) \) and that \( \nabla u_i \) \( L^2 \)-weakly converge to \( \nabla u \). Although this statement was already proved in general setting (e.g. [10] and [28]). See also [6] and [32], for reader’s convenience, let us give a proof as follows.

Mazur’s lemma yields the first statement, \( u \in H^{1,2}(X, d, m) \). To get the second one, since \( \sup_i \| \nabla u_i \|_{L^2} < \infty \), it is enough to check that

\[
\int_X (\nabla u_i, f \nabla h) \, dm \to \int_X (\nabla u, f \nabla h) \, dm \quad (i \to \infty) \quad \forall f, h \in C_c^\infty(\Omega).
\]

(3.7)

Then,
\[
\int_X (\nabla u_i, f \nabla h) \, dm = \int_X u_i (-\nabla f, \nabla h) - f \Delta h) \, dm \\
\to \int_X u (-\nabla f, \nabla h) - f \Delta h) \, dm = \int_X (\nabla u, f \nabla h) \, dm
\]

which proves (3.7).

**Definition 3.5** \((L^2\text{-strong compactness})\). A compact metric measure space \((Y, d, v)\) is said to satisfy the \( L^2 \)-strong compactness condition if the canonical inclusion \( i : H^{1,2}(Y, d, v) \to L^2(Y, v) \) is a compact operator.

It is well-known that there are several sufficient conditions to satisfy the \( L^2 \)-strong compactness condition, for instance, PI-condition (i.e. the volume doubling and the Poincaré inequality are satisfied), which follows from RCD(K, N)-conditions for \( N < \infty \) (see for instance [29] for the proof of the \( L^2 \)-strong compactness condition). However, in general, for an \( n \)-dimensional almost smooth compact metric measure space, the \( L^2 \)-strong compactness condition is not satisfied even if \( \Omega \) has a uniform lower Ricci bound. To see this, for any two pointed metric spaces \((X_i, d_i, x_i)(i = 1, 2)\), let us denote by \((X_1, d_1, x_1) \ast (X_2, d_2, x_2)\) their glued pointed metric space as \( x_1 = x_2 \), that is, the metric space is

\[
X_1 \ast X_2 := (X_1 \bigsqcup X_2)/(x_1 = x_2)
\]

with the intrinsic metric, and the base point is the glued point. See [17] for the detail. Sometimes, we denote the metric space by \((X_1 \ast X_2, d)\) without any attention on the base points for simplicity.

**Example 3.6.** Let us define a sequence of pointed compact metric spaces \((X_i, d_i, x_i)\) as follows. Fix \( n \geq 3 \) and consider a sequence of flat \( n \)-tori:

\[
\mathbb{T}_n^i := S^1(1/2^i) \times S^1(1/2^i) \times \cdots \times S^1(1/2^i)
\]

with fixed points \( p_i \in \mathbb{T}_n^i \), where \( S^1(1) := \{ v \in \mathbb{R}^2; |v| = r \} \). Then, let \((X_1, d_1, x_1) := (\mathbb{T}_n^1, d_{\mathbb{T}_n^1}, p_1)\) and let \((X_{i+1}, d_{i+1}, x_{i+1}) := (X_i, d_i, x_i) \ast (\mathbb{T}_n^{i+1}, d_{\mathbb{T}_n^{i+1}}, p_{i+1}) \quad \forall i \geq 1.\)
Then, let us denote by \((X, d, x)\) the pointed Gromov-Hausdorff limit space of \((X_i, d_i, x_i)\). Note that \((X, d)\) is compact, that \(Ω := X \setminus \{x\}\) satisfies the smoothness with \(\text{Ric}^\mathbb{R}_{0} \geq 0\), and that there exist canonical isometric embeddings \(\mathbb{T}_i^n \hookrightarrow X\) (we identify \(\mathbb{T}_i^n\) with the image). Then, we consider the \(n\)-dimensional Hausdorff measure \(\mathcal{H}^n\) as the reference measure \(m\) on \(X\).

Let us check the zero capacity condition. It is trivial that \(\mathcal{H}^n(X \setminus Ω) = 0\). For all \(e > 0\), take \(ψ_ε \in C^n(\mathbb{R})\) satisfying that \(ψ_ε|_{(-∞, ε)} = 0\), that \(0 ≤ ψ_ε ≤ 1\), that \(|ψ'_ε| = 100/ε\) and that \(|ψ''_ε| ≤ 100/ε^2\).

Define \(φ_i \in C^n(Ω)\) by
\[
φ_i(y) := \sum_{j=1}^{i} 1_{T^n_j}(y)ψ_{\epsilon^2 i 2^{-j}}(d(x, y)).
\]

Then, since it is easy to see that for some universal constant \(C_1 > 0\)
\[
|Δψ_{\epsilon^2 i 2^{-j}}(d(x, ·))(y)| ≤ C_1 2^{2j} \quad \forall j ≤ i, \forall y \in T^n_j \cap (\mathcal{B}_{\epsilon^2 i 2^{-j}}(x) \setminus B_{\epsilon^2 i 2^{-j+1}}(x)),
\]

we see that for all \(j ≤ i\)
\[
\int_{T^n_j} |Δψ_{\epsilon^2 i 2^{-j}}(d(x, y))| d\mathcal{H}^n = \int_{T^n_j \cap (\mathcal{B}_{\epsilon^2 i 2^{-j}}(x) \setminus B_{\epsilon^2 i 2^{-j+1}}(x))} |Δψ_{\epsilon^2 i 2^{-j}}(d(x, y))| d\mathcal{H}^n ≤ C_2 2^{(2-n)j},
\]
where \(C_2\) is also a universal constant. In particular,
\[
\int_{X} |Δφ_i| d\mathcal{H}^n ≤ C_2 i 2^{(2-n)i} → 0 \quad (i → ∞)
\]
which proves the zero capacity condition. Thus, \((X, d, \mathcal{H}^n)\) is an \(n\)-dimensional almost smooth compact metric measure space.

Let us define a sequence \(f_i \in L^2(X, \mathcal{H}^n)\) by
\[
f_i := \frac{1}{\mathcal{H}^n(\mathcal{B}^n_j)} 1_{\mathcal{B}^n_j}.
\]

Then, it is easy to see that \(f_i L^2\)-weakly converge to 0 and that \(f_i \in H^{1,2}(X, d, m)\) with \(∥f_i∥_{L^2} = ∥f_i∥_{H^{1,2}} = 1\) (see also Example 3.8). Since \(f_i\) does not \(L^2\)-strongly converge to 0, the \(L^2\)-strong compactness condition does not hold.

It follows from standard arguments in functional analysis that if an infinitesimally Hilbertian compact metric measure space \((Y, d, ν)\) satisfies the \(L^2\)-strong compactness condition with \(\dim L^2(Y, ν) = ∞\), then, the spectrum of \(-Δ\) is discrete and unbounded (each eigenvalue has finite multiplicities). Thus, we then denote the eigenvalues by
\[
0 = λ_1(Y, d, ν) ≤ λ_2(Y, d, ν) ≤ λ_2(Y, d, ν) ≤ \cdots → ∞
\]
counted with multiplicities, and denote the corresponding eigenfunctions by \(φ^2_i\) with \(∥φ^2_i∥_{L^2} = 1\). We always fix an \(L^2\)-orthogonal basis \(\{φ^2_i\}_i\) consisting of eigenfunctions, immediately. Moreover, it also holds that for all \(f \in L^2(Y, ν), \)
\[
f = \sum_{i} \left( ∫_{Y} fφ^2_i dν \right) φ^2_i \quad \text{in } L^2(Y, ν) \quad (3.8)
\]
and that for all \(f \in H^{1,2}(Y, d, ν), \)
\[
f = \sum_{i} \left( ∫_{Y} fφ^2_i dν \right) φ^2_i \quad \text{in } H^{1,2}(Y, d, ν). \quad (3.9)
\]

For reader’s convenience, we will give proofs of them in the appendix.

We are now in a position to give the main result:
Thus, the monotone convergence theorem yields

\[ \frac{1}{2} \Delta |∇f_N|^2 \geq |\text{Hess}_{f_N}|^2 + (\langle ∇A f_N, ∇f_N \rangle + K(n-1)|∇f_N|^2 \quad \forall x \in \Omega. \]

Then, multiplying \( φ_i \) on both sides and then integrating this over \( Ω \) show

\[ \frac{1}{2} \int_Ω |∇f_N|^2 Δφ_i \text{d}^n = \int_Ω φ_i \left( |\text{Hess}_{f_N}|^2 + (\langle ∇A f_N, ∇f_N \rangle + K(n-1)|∇f_N|^2 \right) \text{d}^n. \]

Since \( |∇f_N| \in L^∞(X, m) \) and our assumption on the zero capacity, the inequality (3.12) implies

\[ \limsup_{i \to \infty} \int_Ω φ_i |\text{Hess}_{f_N}|^2 \text{d}^n < \infty. \]

In particular,

\[ \int_Ω |\text{Hess}_{f_N}|^2 \text{d}^n \leq \limsup_{i \to \infty} \int_Ω φ_i |\text{Hess}_{f_N}|^2 \text{d}^n < \infty \quad \forall A \in Ω. \]

Thus, the monotone convergence theorem yields

\[ \int_Ω |\text{Hess}_{f_N}|^2 \text{d}^n < \infty. \]

On the other hand, since \( φ_i \in C^∞_c(Ω) \) and \( f_N|_Ω \in C^∞(Ω) \), we have \( φ_i|∇f_N|^2 \in H^{1,2}(X, d, m) \). Moreover, since

\[ \int_X |∇(φ_i|∇f_N|^2)|^2 \text{d}m \leq \int_X \left( 2|φ_i|^2 |∇f_N|^4 + 2|∇|∇f_N|^2|^2 \right) \text{d}m \]

\[ \leq \int_X \left( 2|φ_i|^2 |∇f_N|^4 + 2|\text{Hess}_{f_N}|^2 |∇f_N|^2 \right) \text{d}m, \]

by (3.13), we have \( \sup_i \|φ_i|∇f_N|^2\|_{H^{1,2}} < \infty \) which completes the proof of the desired statement, \( |∇f_N|^2 \in H^{1,2}(X, d, m) \), because \( φ_i|∇f_N|^2 \to |∇f_N|^2 \) in \( L^2(X, m) \).

We are now in a position to finish the proof. Let \( φ \in D(Δ) \cap L^∞(X, m) \) with \( Δφ \in L^∞(X, m) \) and \( φ \geq 0 \). Multiplying \( φφ_i \) on both sides of (3.11) and integrating this over \( X \) show

\[ \frac{1}{2} \int_X (φ_0φ_i), |∇|∇f_N|^2| \text{d}m = \int_X φ_i \left( |\text{Hess}_{f_N}|^2 + (\langle ∇A f_N, ∇f_N \rangle + K(n-1)|∇f_N|^2 \right) \text{d}m. \]
Recall that $\varphi_i \to 1$ in $L^2(X, m)$ and that $\nabla \varphi_i$ $L^2$-weakly converge to $\nabla 1 = 0$ with $\nabla (\varphi \varphi_i) = \varphi_i \nabla \varphi + \varphi \nabla \varphi_i$. Thus, we have $$\text{LHS of (3.14)} \to -\frac{1}{2} \int_X \langle \nabla \varphi, \nabla |\nabla f_N|^2 \rangle \, dm = \frac{1}{2} \int_X |\nabla f_N|^2 \Delta \varphi \, dm,$$ where we used $\|\nabla |\nabla f_N|^2\|_{L^2} \leq 2\|\text{Hess}_{f_N}\|_{L^2} \|\nabla f_N\|_{L^\infty} < \infty$ and $|\nabla f_N|^2 \in H^{1,2}(X, d, m)$. Moreover, the dominated convergence theorem yields $$\text{RHS of (3.14)} \to \int_X \varphi \left( |\text{Hess}_{f_N}|^2 + \langle \nabla \Delta f_N, \nabla f_N \rangle + K(n-1)|\nabla f_N|^2 \right) \, dm.$$ Thus, combining these with letting $i \to \infty$ in (3.14) shows $$\frac{1}{2} \int_X |\nabla f_N|^2 \Delta \varphi \, dm \geq \int_X \varphi \left( |\text{Hess}_{f_N}|^2 + \langle \nabla \Delta f_N, \nabla f_N \rangle + K(n-1)|\nabla f_N|^2 \right) \, dm$$ $$\geq \int_X \varphi \left( \frac{|\Delta f_N|^2}{n} + \langle \nabla \Delta f_N, \nabla f_N \rangle + K(n-1)|\nabla f|^2 \right) \, dm.$$ Therefore, letting $N \to \infty$ yields $$\frac{1}{2} \int_X |\nabla f|^2 \Delta \varphi \, dm \geq \int_X \varphi \left( \frac{|\Delta f|^2}{n} + \langle \nabla \Delta f, \nabla f \rangle + K(n-1)|\nabla f|^2 \right) \, dm,$$ which completes the proof. \hfill $\square$

Let us apply Theorem 3.7 to an explicit simple example as follows.

**Example 3.8.** Let us check that the metric measure space $$(X, d, m) := (S^n(1) \ast S^n(1), d, \mathcal{H}^n)$$ satisfies the BE($n-1, n$)-condition ($n \geq 2$), where $S^n(r) := \{v \in \mathbb{R}^{n+1}; |v| = r\}$. Let us denote by $S^n_1(1)$ and $S^n_2(1)$, respectively, the images of the canonical isometric embeddings $S^n(1) \hookrightarrow X$ to the first sphere and the second one, respectively. Moreover, we denote by $p$ the intersection point of them. It is worth pointing out that $(X, d, m)$ satisfies the Ahlfors $n$-regularity, which is easily checked.

**Being an $n$-dimensional almost smooth compact metric measure space.** Let $\Omega := X \setminus \{p\}$. Then, it is trivial that $\Omega$ satisfies the smoothness with $\text{Ric}^n_D \geq (n-1)$ and $\mathcal{H}^n(X \setminus \Omega) = 0$.

Let us use $\varphi_x$ as in Example 3.6. Then, by an argument similar to that in Example 3.6, it is easy to check that the functions $\varphi_k(x) := \varphi_x(p_k(x))$ satisfies the zero capacity condition. Thus, $(X, d, m)$ is an $n$-dimensional almost smooth compact metric measure space.

**Satisfying the $L^2$-strong compactness condition.** We remark that $$f^1_{S^n_1(1)} \in H^{1,2}(X, d, m) \quad \forall f \in H^{1,2}(X, d, m)$$ and $$h^1_{S^n_2(1)} \in H^{1,2}(X, d, m) \quad \forall h \in H^{1,2}(S^n_2(1), d, \mathcal{H}^n)$$ are satisfied, which come from the zero capacity condition with the truncation argument, that is, for functions $\varphi_1 f_{S^n_1(1)}(f \wedge L \vee -L)$ and $\varphi_1 h_{S^n_2(1)}(h \wedge L \vee -L)$, letting $i \to \infty$ and then letting $L \to \infty$ show (3.15) and (3.16) (recall the proof of (2) of Proposition 3.3).

Let $f_i \in H^{1,2}(X, d, m)$ with $\sup_i \|f_i\|_{H^{1,2}} < \infty$. Put $f^1_i := f_i 1_{S^n_1(1)} \in H^{1,2}(S^n_1(1), d, \mathcal{H}^n)$. Then, since the $L^2$-strong compactness condition holds for $(S^n_1(1), d, \mathcal{H}^n)$, there exist a subsequence $i(k)$ and $f^1 \in L^2(S^n_1(1), \mathcal{H}^n)$ such that $f^1_{i(k)} \to f^1$ in $L^2(S^n_1(1), \mathcal{H}^n)$ for all $j \in \{1, 2\}$. In particular, $f^1_i = f^1_{i(k)} + f^2_{i(k)} \to f^1 + f^2$. Secondly, it is also easy to check that $f_{i(k)} \to f$ in $L^2(X, m)$ for $f \in L^2(X, m)$, which proves the $L^2$-strong compactness condition for $(X, d, m)$. 

Satisfying the gradient estimates on the eigenfunctions and the BE\((n - 1, n)\) condition. Let \(f\) be an eigenfunction, that is, \(f \in D(\Delta)\) with \(-\Delta f = \lambda f\) for some \(\lambda \geq 0\). For any \(h \in H^{1,2}(S^n m)\), put \(\hat{h} = h1_{S^n(1)} \in H^{1,2}(X, d, m)\). Then, since
\[
\int_X (\nabla f, \nabla \hat{h}) \, dm = \lambda \int_X f \, \hat{h} \, dm \tag{3.17}
\]
and
\[
\text{LHS of (3.17)} = \int_{S^n(1)} (\nabla f, \nabla h) \, d\mathcal{H}^n, \quad \text{RHS of (3.17)} = \lambda \int_{S^n(1)} fh \, d\mathcal{H}^n,
\]
we see that \(f|_{S^n(1)}\) is an eigenfunction of \((S^n m, \mathcal{H}^n)\). Thus, \(|\nabla f| \in L^\infty(S^n(1), \mathcal{H}^n)\), which implies \(|\nabla f| \in L^\infty(X, m)\).

Therefore, we can apply Theorem 3.7 to show that \((X, d, m)\) satisfies the BE\((n - 1, n)\)-condition.

Coincidence between the induced distance \(d_{ch}\) by the Cheeger energy and \(d\). Let us prove:
\[
d_{ch}(x, y) = d(x, y), \quad \forall x, y \in X, \tag{3.18}
\]
where
\[
d_{ch}(x, y) := \sup \left\{ \varphi(x) - \varphi(y); \varphi \in C^0(X) \cap H^{1,2}(X, d, m), |\nabla \varphi|(z) \leq 1, m - a.e. z \in X \right\} . \tag{3.19}
\]

Let \(x \in S^n(1)\) and let \(y \in S^n(1)\). For any \(\varphi\) as in the RHS of (3.19),
\[
\varphi(x) - \varphi(y) = \varphi|_{S^n(1)}(x) - \varphi|_{S^n(1)}(y) + \varphi|_{S^n(1)}(p) - \varphi|_{S^n(1)}(y) \\
\leq d_{ch}(1_{S^n(1)}, p, y) = d(x, y), \tag{3.20}
\]
where we used the fact that \(d = d_{ch}\) in \((S^n m, d, \mathcal{H}^n)\). Thus, taking the supremum in (3.20) with respect to \(\varphi\) shows the inequality ‘≤’ in (3.18).

To get the converse inequality, let
\[
\varphi(z) := (1_{S^n(1)}(z) - 1_{S^n(1)}(z))d(p, z).
\]
Then, we see that \(\varphi \in \text{LIP}(X, d)\), that \(\text{LIP}(\varphi) \leq 1\) for all \(z \in X\), and that \(\varphi(x) - \varphi(y) = d(x, y)\), which proves the converse inequality ‘≥’ in (3.18).

Similarly, we can prove (3.18) in the remaining case, thus, we have (3.18) for all \(x, y \in X\).

Poincaré inequality and RCD\((K, \infty)\) condition are not satisfied. Assume that \((X, d, m)\) satisfies the \((1, 2)\)-Poincaré inequality, that is, there exists \(C > 0\) such that for all \(r > 0\), all \(x \in X\) and all \(f \in H^{1,2}(X, d, m)\), it holds that
\[
\frac{1}{m(B_r(x))} \int_{B_r(x)} f - \frac{1}{m(B_r(x))} \int_{B_r(x)} f \, dm \leq Cr \left( \frac{1}{m(B_r(x))} \int_{B_r(x)} |\nabla f|^2 \, dm \right)^{1/2} . \tag{3.21}
\]
Let \(\varphi := 1_{S^n(1)} - 1_{S^n m}\). By (3.16), we have \(\varphi \in H^{1,2}(X, d, m)\). Then, by the locality of the slope, we have \(|\nabla \varphi| = 0\) m.a.e. In particular, (3.21) yields that \(\varphi\) must be a constant, which is a contradiction.

By the same reason, for all \(K \in \mathbb{R}\), \((X, d, m)\) does not satisfy RCD\((K, \infty)\)-condition.

Remark 3.9. Example 3.8 also tells us that (1.3) does not imply the expected Bishop-Gromov inequality. In fact, under the same notation as in Example 3.8, letting \(q\) be the antipodal point of \(p\) in \(S^n(1)\) yields
\[
\frac{m(B_{2\pi}(q))}{m(B_\pi(q))} = 2 > 1 = \frac{\mathcal{H}^n(B_{2\pi}(1))}{\mathcal{H}^n(B_{\pi}(1))} \quad \forall x \in S^n(1)
\]
which is the ‘reverse’ Bishop-Gromov inequality. Similarly, the BE\((n - 1, n)\) condition with ‘\(d = d_{ch}\)’ does not imply the expected Bonnet-Myers theorem.
Corollary 3.10 (Characterization of RCD condition on almost smooth compact metric measure space). Let \((X, d, m)\) be an \(n\)-dimensional almost smooth compact metric measure space associated with an open subset \(\Omega\) of \(X\), and let \(K \in \mathbb{R}\). Then, \((X, d, m)\) is a RCD\((K(n-1), n)\) space if and only if the following four conditions hold:

1. the Sobolev to Lipschitz property holds;
2. the \(L^2\)-strong compactness condition holds;
3. any eigenfunction is Lipschitz;
4. \(\text{Ric}_D^X \geq K(n-1)\) holds.

Proof. By Theorem 3.7, it is enough to check ‘only if’ part. If \((X, d, m)\) is a RCD\((K(n-1), n)\), then, applying Gigli’s Bochner inequality (for \(H^1_{1/2}\)-vector fields) in [28] shows that for all \(f, h \in C_0^\infty(\Omega)\) with \(\varphi \equiv 0\),

\[
\frac{1}{2} \int_X \frac{\varphi}{m} \Delta [f \nabla h]^2 \geq \int_X \varphi \left( |\nabla (f \nabla h)|^2 - \langle \Delta_H f, (f \nabla h) \rangle + Kn(n-1) |f \nabla h|^2 \right) dm
\]

which implies

\[
\frac{1}{2} \int_X \frac{\varphi}{m} \Delta [f \nabla h]^2 \geq |\nabla (f \nabla h)|^2 - \langle \Delta_H f, (f \nabla h) \rangle + Kn(n-1) |f \nabla h|^2 \quad \forall x \in \Omega
\]  

(3.22)

because \(\varphi\) is arbitrary, where \(\Delta_H := d\delta + \delta d\) is the Hodge Laplacian acting on 1-forms. In particular, since (3.22) is equivalent to \(\text{Ric}_D^X(f \nabla h, f \nabla h) \geq Kn(n-1)|f \nabla h|^2\) for all \(x \in \Omega\), we have \(\text{Ric}_D^X \geq K(n-1)\) because \(f, h\) are also arbitrary.

The Sobolev to Lipschitz property is in the definition of RCD space. Moreover, as written previously, the \(L^2\)-strong compactness condition follows from the doubling condition and the Poincaré inequality, which are justified by the Bishop-Gromov inequality [38] and by [37]. Finally, since the Lipschitz regularity on the eigenfunctions is satisfied by [33], we conclude.

Corollary 3.11 (Another characterization of RCD condition). Let \((X, d, m)\) be an \(n\)-dimensional almost smooth compact metric measure space associated with an open subset \(\Omega\) of \(X\), and let \(K \in \mathbb{R}\). Then, \((X, d, m)\) is a RCD\((K(n-1), n)\) space if and only if the following four conditions hold:

1. \((X, d, m)\) is a PI space;
2. the induced distance \(d_{Ch}\) by the Cheeger energy is equal to the original distance \(d\);
3. any eigenfunction \(f\) satisfies \(|\nabla f| \in L^\infty(X, m)\);
4. \(\text{Ric}_D^X \geq K(n-1)\) holds.

Proof. Since the proof of ‘only if’ part is same to that of Corollary 3.10, let us check ‘if’ part. By Theorem 3.7, we see that \((X, d, m)\) is a \(\text{BE}(K(n-1), n)\) space. Thus, it suffices to check the Sobolev to Lipschitz property.

Let \(f \in H^{1,2}(X, d, m)\) with \(|\nabla f(x)| \leq 1\) \(m\)-a.e. \(x \in X\). Then, the telescope argument with the PI condition (c.f. [19]) yields that there exists \(\tilde{f} \in \text{LIP}(X, d)\) such that \(f(x) = \tilde{f}(x)\) \(m\)-a.e. \(x \in X\). Then, since it is proved in [5] that

- any \(h \in H^{1,2}(X, d, m) \cap C^0(X)\) with \(|\nabla h| \leq 1\) \(m\)-a.e. \(x \in X\) is 1-Lipschitz,

we see that \(\tilde{f}\) is 1-Lipschitz, that is, the Sobolev-Lipschitz property holds. Thus, we conclude.

Remark 3.12. We should mention that very recently, similar characterization of RCD conditions for stratified spaces, which give almost smooth metric measure spaces as typical examples, is proved in [15].

We end this section by giving a sufficient condition to satisfy the Sobolev to Lipschitz property. For that, let us introduce the definition of the segment inequality:

Definition 3.13 (Segment inequality). Let \((Y, d, \nu)\) be a metric measure space satisfying that \((Y, d)\) is a geodesic space. For a nonnegative valued Borel function \(f\) on \(Y\), define

\[
\mathcal{F}_f(x, y) := \inf_{\gamma} \int_0^{d(x, y)} f(\gamma) d\sigma, \quad \forall x, y \in Y,
\]
where the infimum runs over all minimal geodesics \( \gamma \) from \( x \) to \( y \). Then, we say that \((Y, d, v)\) satisfies the segment inequality if there exists \( \lambda > 0 \) such that

\[
\int_{B_r(x)} \mathcal{F}_f(y, z)d(v \times v) \leq \lambda rv(B_r(x)) \int_{B_r(x)} f dv \quad \forall x \in Y, \forall r > 0, \forall f.
\]

Cheeger-Colding proved in [21] that if \((Y, d, v)\) satisfies the volume doubling condition and the segment inequality, then the \((1, 1)\)-Poincaré inequality holds (see also [20] and [30]).

**Proposition 3.14** (Segment inequality with doubling condition implies Sobolev to Lipschitz property). Let \((Y, d, v)\) be a compact metric measure space satisfying that \((Y, d)\) is a geodesic space. Assume that \((Y, d, v)\) satisfies the volume doubling condition and the segment inequality. Then, the Sobolev to Lipschitz property holds.

**Proof.** Let \( f \in H^{1,2}(Y, d, v) \) with \( |\nabla f| \leq 1 \) \( v \)-a.e.. As written above, since \((1, 1)\)-Poincaré inequality is satisfied, \( f \) has a representative in \( \tilde{f} \in \text{LIP}(Y, d) \) by the telescope argument (see for instance [19]). Thus, since we have \( |\text{LIP}(\tilde{f})| \leq 1 \) \( v \)-a.e., which also follows from [19], it suffices to check that \( \tilde{f} \) is 1-Lipschitz.

Let us take a Borel subset \( A \) of \( Y \) such that \( v(Y \setminus A) = 0 \) and that

\[
\text{LIP}(\tilde{f}) \leq 1, \quad \forall x \in A.
\]

Applying the segment inequality for \( 1_{Y \setminus A} \) yields that there exists a Borel subset \( B \) of \( Y \times Y \) such that \((v \times v)((Y \times Y) \setminus B) = 0 \) and that for any \((x, y) \in B \) and any \( \epsilon > 0 \), there exists a minimal geodesic \( \gamma \) from \( x \) to \( y \) such that

\[
\int_{[0, d(x,y)]} 1_{Y \setminus A}(\gamma(s)) ds < \epsilon.
\]

Therefore, since \( \text{LIP}(\tilde{f}) \) is an upper gradient of \( \tilde{f} \), we have

\[
|\tilde{f}(x) - \tilde{f}(y)| \leq \int_{[0, d(x,y)]} \text{LIP}(\tilde{f})(\gamma(s)) ds = \int_{[0, d(x,y)]} 1_A(\gamma(s))\text{LIP}(\tilde{f})(\gamma(s)) ds + \int_{[0, d(x,y)]} 1_{Y \setminus A}(\gamma(s))\text{LIP}(\tilde{f})(\gamma(s)) ds \\
\leq d(x, y) + \sup_{z} \text{LIP}(\tilde{f})(z)\epsilon. \tag{3.23}
\]

Since \( \epsilon \) is arbitrary and \( B \) is dense in \( Y \times Y \), (3.23) yields that \( \tilde{f} \) is 1-Lipschitz. \( \square \)

**Remark 3.15.** Let us give remarks on related works. Note that in the following, the spaces are not necessary compact. As we already used, Jiang proved in [33] the gradient estimates on solutions of Poisson’s equations (including eigenfunctions) in the setting of metric measure spaces under assuming mild geometric conditions and a heat semigroup curvature condition (or called an weighted Sobolev inequality). Bamler and Chen-Wang proved in [14], in [22], such conditions (including the segment inequality) in their almost smooth settings, independently.

One of interesting questions is; if an \( n \)-dimensional almost smooth (compact) metric measure space \((X, d, m)\) satisfies that the induced distance \( d_{\epsilon} \) by \( g \) on \( \Omega \) coincides with \( d|_{\Omega} \), then, being \( \text{Ric}^g_{\Omega} \geq K(n-1) \) is equivalent to that \((X, d, m)\) is a \( \text{RCD}(K(n-1), n) \)-space?

### 3.2 Nonconstant dimensional case

In this section, let us discuss a variant of \( n \)-dimensional almost smooth compact metric measure spaces. Let us recall that we fix a compact metric measure space \((X, d, m)\).
Definition 3.16 (Generalized almost smooth compact metric measure space). We say that \((X, d, m)\) is a \textit{generalized almost smooth compact metric measure space associated with an open subset \(\Omega\) of \(X\)} if the following two conditions are satisfied:

1. (Generalized smoothness of \(\Omega\)) for all \(p \in \Omega\), there exist an integer \(n(p) \in \mathbb{N}\), an open neighborhood \(U_p\) of \(p\) in \(\Omega\), an \(n(p)\)-dimensional (possibly incomplete) Riemannian manifold \((M^{n(p)}, g)\) and a map \(\varphi : U_p \to M^{n(p)}\) such that \(\varphi\) is a local isometry between \((U_p, d)\) and \((M^{n(p)}, d_g)\).

2. (Hausdorff measure condition) For all \(p \in \Omega\), take \(U_p\) as above. Then, the restriction of \(m\) to \(U_p\) coincides with the \(n(p)\)-dimensional Hausdorff measure \(\mathcal{H}^{n(p)}\).

3. (Zero capacity condition) \(X \setminus \Omega\) has zero capacity in the sense of Definition 3.1.

By an argument similar to the proof of Theorem 3.7, we have the following:

Theorem 3.17 (From \(\text{Ric}^g_{\Omega} \geq K\) to \(\text{BE}(K, N))\). Let \((X, d, m)\) be a generalized almost smooth compact metric measure space associated with an open subset \(\Omega\) of \(X\). Assume that \((X, d, m)\) satisfies the \(L^2\)-strong compactness condition, that each eigenfunction \(q_i\) satisfies \(|\nabla q_i| \in L^\infty(X, m)\) and that \(\text{Ric}^g_{\Omega} \geq K\) for some \(K \in \mathbb{R}\). Then, \((X, d, m)\) satisfies the \(\text{BE}(K, N)\)-condition, where \(N := \sup_p n(p)\).

Example 3.18. By an argument similar to that in Example 3.8, we can easily see that for any two (not necessary same dimensional) closed pointed Riemannian manifolds \((M_i^{m_i}, g_i, p_i)(m_i \geq 2)\) with \(\text{Ric}^{g_i}_{M_i^{m_i}} \geq K\) for some \(K \in \mathbb{R}\), the metric measure space

\[
\left( \frac{M_1^{m_1} \times M_2^{m_2}}{d, \mathcal{H}^{m_1} \mathcal{L}_{M_1^{m_1}} + \mathcal{H}^{m_2} \mathcal{L}_{M_2^{m_2}}} \right)
\]

is a \(\text{BE}(K, \text{max}(m_1, m_2))\) space with \(d_{CH} = d\).

More generally, similar constructions of \(\text{BE}(K, N)\) spaces by gluing embedded closed convex submanifolds \(N_i^{m_i} \subset M_i^{m_i}\), which are isometric to each other, with \(m_i - n_i \geq 2\) are also justified.

Remark 3.19. In this paper we discuss only the \text{\textit{unweighted}}} case, that is, the restriction of the reference measure to the smooth part is the optimal Hausdorff measure \(\mathcal{H}^n\). Similar results are also obtained in the weighted case, \(e^{-f} \mathcal{H}^{n}\), where \(f \in C^\infty(\Omega)\), under suitable assumptions on \(f\) by using the Bakry-Émery \((N)\)-Ricci tensor and the Witten Laplacian \(\Delta_f\), respectively instead of using the original Ricci tensor and the Laplacian \(\Delta\), respectively. However, we do not discuss the details because our main focus is to discuss some ‘flexibility’ on the \(\text{BE}(K, N)\) conditions as in Example 3.18, which is very different from the \(\text{RCD}(K, N)\) conditions, and to give a bridge between almost smooth spaces and noncollapsed \(\text{RCD}\) spaces introduced in [24], as in Corollary 3.10.

A Appendix

Let \((Y, d, v)\) be an infinitesimally Hilbertian compact metric measure space and assume that \((Y, d, v)\) satisfies the \(L^2\)-strong compactness condition with \(\dim L^2(Y, v) = \infty\). In this appendix, we will show that the spectrum of \(-\Delta\) is discrete and unbounded, and that (3.8) and (3.9) hold.

Let us begin with proving the following lemma:

Lemma A.1. For all \(\lambda \in \mathbb{R}\), let \(E(\lambda) := \{f \in D(\Delta); -\Delta f = \lambda f\}\).

1. If \(\dim E(\lambda) \geq 1\), then \(\lambda \geq 0\) (which is called an eigenvalue of \(-\Delta\)).

2. \(\dim E(\lambda) < \infty\) holds.

Proof. Let us check (1). Taking \(f \in E(\lambda)\) with \(f \neq 0\) in \(L^2(Y, v)\) yields \(\lambda = \frac{\int_Y |\nabla f|^2 dv}{\int_Y f^2 dv} \geq 0\).

To prove (2), with no loss of generality, we can assume \(\dim E(\lambda) \geq 1\). Let us check \((E(\lambda), \|\cdot\|_{L^2})\) is a Hilbert space. Take a Cauchy sequence \(f_j\) in \(E(\lambda)\). Let \(f \in L^2(Y, v)\) be the \(L^2\)-strong limit function. Since \(\|\nabla f_j\|_{L^2}^2 = \)
Proof. Note that since \( \lambda \| f_{i}\|_{L^2}^2 \), \( f_{i} \) is a bounded sequence in \( H^{1,2}(Y, d, v) \). Thus, Mazur’s lemma shows that \( f \in H^{1,2}(Y, d, v) \) and that \( f_{i} \) converge weakly to \( f \) in \( H^{1,2}(Y, d, v) \). Therefore, letting \( i \to \infty \) in
\[
\int_Y (\nabla f_{i}, \nabla g) dv = \lambda \int_Y f g dv \quad \forall g \in H^{1,2}(Y, d, v)
\]
yields
\[
\int_Y (\nabla f, \nabla g) dv = \lambda \int_Y f g dv \quad \forall g \in H^{1,2}(Y, d, v)
\]
which shows \( f \in \mathcal{E}(\lambda) \), where the convergence of the left hand sides comes from the polarization. Thus, \( (E(\lambda), \| \cdot \|_{L^2}) \) is a Hilbert space.

Then, similar argument with the \( L^2 \)-strong compactness condition allows us to prove that \( S(\lambda) \) is a compact subset of \( \mathcal{E}(\lambda) \), where \( S(\lambda) := \{ f \in \mathcal{E}(\lambda); \| f \|_{L^2} = 1 \} \). Therefore, \( \dim \mathcal{E}(\lambda) < \infty \). □

Lemma A.2. The set \( \mathcal{E}(Y, d, v) := \{ \lambda \in \mathbb{R}_{>0}; \dim \mathcal{E}(\lambda) \geq 1 \} \) is discrete.

Proof. The proof is done by contradiction. Assume that there exists a sequence \( \lambda_{i} \in \mathcal{E}(Y, d, v) \) such that \( \lambda_{i} \neq \lambda_{j} \) (\( i \neq j \)) and that \( \lambda_{i} \to \lambda \in \mathbb{R} \). Take \( f_{i} \in \mathcal{E}(\lambda_{i}) \) with \( \| f_{i} \|_{L^2} = 1 \). Then, since \( \| f_{i} \|_{L^2}^2 = \lambda_{i} \) by the \( L^2 \)-strong compactness condition, with no loss of generality, we can assume that there exists the \( L^2 \)-strong limit function \( f \) of \( f_{i} \). Thus, \( \| f \|_{L^2} = 1 \). Moreover, similar argument as in the proof of (2) of Lemma A.1 shows \( f \in \mathcal{E}(\lambda) \). In particular, \( \lambda \) is an eigenvalue of \( -\Delta \). Let \( \{ g_{j} \}_{j=1,2,\ldots,N} \) be an ONB of \( \mathcal{E}(\lambda) \). Since \( g_{j} \perp f_{i} \) in \( L^2(Y, v) \), letting \( i \to \infty \) yields \( g_{j} \perp f \). Therefore, \( \{ g_{j} \}_{j} \cup \{ f \} \) are linearly independent in \( \mathcal{E}(\lambda) \), which contradicts that \( \{ g_{j} \}_{j} \) is a basis of \( \mathcal{E}(\lambda) \). □

Lemma A.3. The set \( \mathcal{E}(Y, d, v) \) is unbounded.

Proof. Note that since \( 1 \in \mathcal{E}(0) \), we have \( \mathcal{E}(Y, d, v) \neq \emptyset \).

Assume that \( \mathcal{E}(Y, d, v) \) is bounded. Then, Lemma A.2 yields that \( \mathcal{E}(Y, d, v) \) is a finite set. By Lemma A.1, there exists an ONB, \( \{ f_{i} \}_{i=1,2,\ldots,N} \), of \( \bigoplus_{\lambda \in \mathcal{E}(Y, d, v)} \mathcal{E}(\lambda)(= V) \).

On the other hand, it is easy to see that the number
\[
\lambda_{\star} := \inf f \in V \int_Y |\nabla f|^2 dv / \int_Y |f|^2 dv
\]
is also an eigenvalue of \( -\Delta \) and that there exists a minimizer \( f_{\star} \) of the right hand side with \( f_{\star} \in \mathcal{E}(\lambda_{\star}) \) and \( \| f_{\star} \|_{L^2} = 1 \), where we used our assumption, \( \dim L^2(Y, v) = \infty \), to make sense in the infimum. Thus, since \( f_{\star} \in V \) and \( f_{\star} \perp V \), we have \( f_{\star} = 0 \), which contradicts that \( \| f_{\star} \|_{L^2} = 1 \). □

Lemmas A.2 and A.3 allow us to denote the eigenvalues of \( -\Delta \) by
\[
0 = \lambda_{1}(Y, d, v) \leq \lambda_{2}(Y, d, v) \leq \cdots \to \infty
\]
counted with multiplicities. Fix the corresponding eigenfunctions by \( \phi^{Y}_{i} \) with \( \| \phi^{Y}_{i} \|_{L^2} = 1 \).

Proposition A.4. For all \( f \in L^2(Y, v) \), we have (3.8).

Proof. We first assume that \( f \in H^{1,2}(Y, d, v) \). For all \( N \in \mathbb{N} \), let \( f_{N} := \sum_{i=1}^{N} (\int_Y f \phi^{Y}_{i} dv) \phi^{Y}_{i} \) and let \( g_{N} := f - f_{N} \). With no loss of generality, we can assume that \( g_{N} \equiv 0 \) for all \( N \).

Then, since for all \( i \leq N \)
\[
\int_Y g_{N} \phi^{Y}_{i} dv = \int_Y f \phi^{Y}_{i} dv - \sum_{j=1}^{N} \left( \int_Y f \phi^{Y}_{j} dv \right) \int_Y \phi^{Y}_{i} \phi^{Y}_{j} dv = \int_Y f \phi^{Y}_{i} dv - \int_Y f \phi^{Y}_{i} dv = 0,
\]
we have (3.8).
we have $g_N \perp V_N$, where $V_N := \text{span} \{\varphi_i^N\}_{i=1,2,...,N}$.

On the other hand, it is easy to see that the number
\[
\lambda_{N+1} := \inf_{h \perp V_N} \frac{\int_Y |\nabla h|^2 \, dv}{\int_Y |h|^2 \, dv}
\]
coincides with $\lambda_{N+1}(Y, d, v)$ (the inequality $\lambda_{N+1} \leq \lambda_{N+1}(Y, d, v)$ is trivial. The converse is done by checking that $\lambda_{N+1}$ is an eigenvalue of $-\Delta$, which is similar to the proof of Lemma A.3).

Therefore, we have $\|\nabla g_N\|_{L^2}^2 \geq \lambda_{N+1}(Y, d, v)\|g_N\|_{L^2}^2$. Since
\[
\int_Y |\nabla g_N|^2 \, dv = \int_Y |\nabla f|^2 \, dv - 2 \int_Y (\nabla f \cdot \nabla f_N) \, dv + \int_Y |\nabla f_n|^2 \, dv
\]
we have $\|g_N\|_{L^2}^2 \leq (\lambda_{N+1}(Y, d, v))^{-1}\|\nabla f\|_{L^2}^2 \to 0$ as $N \to \infty$, which shows (3.8) in the case when $f \in H^{1,2}(Y, d, v)$.

Next, let us check (3.8) for general $f \in L^2(Y, v)$. Take a sequence $F_n \in H^{1,2}(Y, d, v)$ with $F_n \to f$ in $L^2(Y, v)$. Let $a_i := \int_Y f \varphi_i^Y \, dv$, let $a_{n,i} := \int_Y F_n \varphi_i^Y \, dv$, let $f_N := \sum_i a_i \varphi_i^Y$, and let $F_{n,N} := \sum_i a_{n,i} \varphi_i^Y$. For all $\epsilon > 0$, there exists $n_0$ such that $\|f - F_{n_0}\|_{L^2} < \epsilon$. Then, there exists $N_0$ such that for all $N \geq N_0$, we have $\|F_{n_0} - F_{n_0,N}\|_{L^2} < \epsilon$. Moreover,
\[
\int_Y |F_{n_0,N} - F_N|^2 \, dv \leq \sum_i (a_{n_0,i} - a_i)^2 
\leq \sum_i (a_{n_0,i} - a_i)^2
= \sum_i \left( \int_Y (F_{n_0} - f_i) \varphi_i^Y \, dv \right)^2 \leq \|F_{n_0} - f\|_{L^2}^2 \leq \epsilon^2,
\]
where we used the fact that for any ONS, $\{e_i\}_i$ in a Hilbert space $(H, \langle \cdot, \cdot \rangle)$, we have $|v|^2 \geq \sum_i (v, e_i)^2$ for all $v \in H$. Therefore, for all $N \geq N_0$,
\[
\|f - F_N\|_{L^2} \leq \|f - F_{n_0}\|_{L^2} + \|F_{n_0} - F_{n_0,N}\|_{L^2} + \|F_{n_0,N} - F_N\|_{L^2} \leq 3\epsilon,
\]
which completes the proof.

**Proposition A.5.** For all $f \in H^{1,2}(Y, d, v)$, we have (3.9).

**Proof.** Let $f_N := \sum_i a_i \varphi_i^Y$, where $a_i = \int_Y f \varphi_i^Y \, dv$. Then,
\[
\|\nabla f_N\|_{L^2}^2 = \sum_i \lambda_i(Y, d, v)(a_i)^2.
\]
On the other hand,
\[
\int_Y (\nabla f \cdot \nabla f_N) \, dv = \sum_i a_i \int_Y (\nabla f \cdot \nabla \varphi_i^Y) \, dv
\]
\[
= \sum_i a_i \lambda_i(Y, d, v) \int_Y f \varphi_i^Y \, dv = \sum_i \lambda_i(Y, d, v)(a_i)^2 = \|\nabla f_N\|_{L^2}^2.
\]
In particular, the Cauchy-Schwartz inequality yields $\|\nabla f_N\|_{L^2}^2 \leq \|\nabla f\|_{L^2}^2 \|\nabla f_N\|_{L^2}^2$. Thus, since $\|\nabla f_N\|_{L^2} \leq \|\nabla f\|_{L^2}$, we have sup $\|f_N\|_{H^{1,2}} < \infty$. Since $f_N \to f$ in $L^2(Y, v)$ as $N \to \infty$, Mazur’s lemma shows (3.9).
Acknowledgements: A part of the work is done during the author’s stay in Yau Mathematical Sciences Center (YMSC) at Tsinghua University. The author would like to express his appreciation to Guoyi Xu for his warm hospitality. He is also grateful to YMSC for giving him nice environment. He thanks Luigi Ambrosio, Nicola Gigli, Bangxian Han and Aaron Naber for helpful comments. Moreover, He thanks the referee for the careful reading of the manuscript and for the suggestions in the revision. Finally, he acknowledges the supports of the Grant-in-Aid for Young Scientists (B), 16K17585, and of the Grant-in-Aid for Scientific Research (B), 18H01118.

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