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A Cookbook for Temporal Conceptual Data Modelling with Description Logics

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We design temporal description logics suitable for reasoning about temporal conceptual data models and investigate their computational complexity. Our formalisms are based on DL-Lite logics with three types of concept inclusions (ranging from atomic concept inclusions and disjointness to the full Booleans), as well as cardinality constraints and role inclusions. The logics are interpreted over the Cartesian products of object domains and the flow of time \((\mathbb{Z}, <)\), satisfying the constant domain assumption. Concept and role inclusions of the TBox hold at all moments of time (globally) and data assertions of the ABox hold at specified moments of time. To express temporal constraints of conceptual data models, the languages are equipped with flexible and rigid roles, standard future and past temporal operators on concepts and operators ‘always’ and ‘sometime’ on roles. The most expressive of our temporal description logics (which can capture lifespan cardinalities and either qualitative or quantitative evolution constraints) turns out to be undecidable. However, by omitting some of the temporal operators on concepts/roles or by restricting the form of concept inclusions we construct logics whose complexity ranges between \(\text{NLogSPACE}\) and \(\text{PSPACE}\). These positive results are obtained by reduction to various clausal fragments of propositional temporal logic, which opens a way to employ propositional or first-order temporal provers for reasoning about temporal data models.

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1. INTRODUCTION

The aim of this article is twofold. On the one hand, we investigate the complexity of reasoning about temporal conceptual data models depending on the available modelling constructs. On the other hand, we achieve this by encoding temporal conceptual data models in carefully crafted temporal description logics (TDLs, for short). As a result, we obtain a new family of TDLs and a clear understanding of how their constructs affect the complexity of reasoning. Most of the constructed TDLs feature an unexpectedly low complexity—compared to other known TDLs—such as \(\text{NLogSPACE}\), \(\text{PTIME}\), \(\text{NP}\) and \(\text{PSpace}\), which is good news for automated temporal conceptual modelling. However, some combinations of the constructs (which involve temporal operators on relationships) result in undecidability, giving a new type of undecidable fragments of first-order temporal logic.
Conceptual data modelling formalisms, such as the Extended Entity-Relationship model (EER) and Unified Modelling Language (UML), provide visual means to describe application domains in a declarative and reusable way, and are regarded as standard tools in database design and software engineering. One of the main tasks in conceptual modelling is to ensure that conceptual schemas satisfy various ‘quality properties’: for instance, one may wish to check whether a given schema is consistent, whether its entities and relationships can be populated, whether a certain individual is an instance of a certain class, etc. That was where conceptual modelling met description logics (DLs), a family of knowledge representation formalisms specifically designed to efficiently reason about structured knowledge [Baader et al. 2003]. Since 2007, DLs have been recognised as the backbone of the Semantic Web, underlying the standard Web Ontology Languages OWL and OWL 2.

Connections between conceptual data models (CMs, for short) and DLs have been investigated since the 1990s (see, e.g., [Calvanese et al. 1999; Borgida and Brachman 2003; Berardi et al. 2005; Artale et al. 2007a] and references therein), which resulted in a classification of CMs according to the computational complexity of checking schema consistency depending on the available modelling constructs. The standard EER/UML constructs include generalisation (inheritance) for entities (classes), relationships and attributes with disjointness and covering constraints on them, cardinality constraints for relationships and their refinements, multiplicity constraints for attributes and key constraints for entities. Reasoning over CMs equipped with the full set of constructs is ExpTime-complete, which was shown by mapping CMs into the DLs $\mathcal{DLR}$ and $\mathcal{ALCQI}$ [Calvanese et al. 1999; Berardi et al. 2005]. With the invention of the $\mathcal{DL-Lite}$ family [Calvanese et al. 2005; 2007; Artale et al. 2007b; 2009a], it became clear that reasoning over CMs can often be done using DLs much weaker than $\mathcal{DLR}$ and $\mathcal{ALCQI}$. For example, the NP-complete $\mathcal{DL-Lite}_{\text{core}}^{\mathcal{HN}}$ was shown to be adequate for representing a large class of CMs with generalisation and both disjointness and covering constraints, but no upper cardinality bounds on specialised relationships; see [Artale et al. 2007a] and Section 2.2 for details. If we are also prepared to sacrifice covering constraints, then the NLogSpace-complete fragment $\mathcal{DL-Lite}_{\text{core}}^{\mathcal{HN}}$ can do the job. (Note that $\mathcal{DL-Lite}_{\text{core}}^{\mathcal{HN}}$ contains the OWL 2 QL profile of OWL 2 and the DL fragment of RDF Schema, RDFS.)

Temporal conceptual data models (TCMs) extend CMs with means to represent constraints over temporal database instances. Temporal constraints can be grouped into three categories: timestamping, evolution and temporal cardinality constraints. Timestamping constraints discriminate between those classes, relationships and attributes that change over time and those that are time-invariant (or, rigid) [Theodoulidis et al. 1991; Gregersen and Jensen 1999; Finger and McBrien 2000; Artale and Franconi 1999; Parent et al. 2006]. Evolution constraints control how the domain elements evolve over time by migrating from one class to another [Hall and Gupta 1991; Mendelzon et al. 1994; Su 1997; Parent et al. 2006; Artale et al. 2007e]. We distinguish between qualitative evolution constraints describing generic temporal behaviour, and quantitative ones specifying the exact time of migration. Temporal cardinality constraints restrict the number of times an instance of a class can participate in a relationship: snapshot cardinality constraints do it at each moment of time, while lifespan cardinality constraints impose restrictions over the entire existence of the instance as a member of the class [Tauzovich 1991; McBrien et al. 1992; Artale and Franconi 2009].

Temporal extensions of DLs have been constructed and investigated since Schmiedel [1990] and Schild’s [1993] seminal papers (see [Gabbay et al. 2003; Artale and Franconi 2001; 2005; Lutz et al. 2008] for detailed surveys), with reasoning over TCMs being one of the main objectives. The first attempts to represent TCMs by means of TDLs resulted in fragments of $\mathcal{DLR}_{\text{US}}$ and $\mathcal{ALCQI}_{\text{US}}$ whose complexity ranged from ExpTime and ExpSpace up to undecidability [Artale and Franconi 1999; Artale et al. 2002; Artale et al. 2003]. A general conclusion one could draw from the obtained results is that—as far as there is a nontrivial interaction between the temporal

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1. www.w3.org/2007/OWL, www.w3.org/TR/owl2-overview
2. www.w3.org/TR/owl2-profiles
3. www.w3.org/TR/rdf-schema
and DL components—TDLs based on full-fledged DLs such as $\mathcal{ALC}$ turn out to be too complex for effective practical reasoning (in more detail, this will be discussed in Section 3.3).

The possibility to capture CMs using logics of the $\mathcal{DL}$-$\mathcal{Lite}$ family gave a glimpse of hope that automated reasoning over TCMs can finally be made practical. The first temporal extension of $\mathcal{DL}$-$\mathcal{Lite}_{bool}^{HN}$ was constructed by Artale et al. [2007c]. It featured rigid roles, with temporal and Boolean operators applicable not only to concepts but also to TBox axioms and ABox assertions. The resulting logic was shown to be EXPSPACE-complete. (To compare: the same temporalisation of $\mathcal{ALC}$ is trivially undecidable [Artale et al. 2002; Gabbay et al. 2003].) This encouraging result prompted a systematic investigation of TDLs suitable for reasoning about TCMs.

Our aim in this article is to design $\mathcal{DL}$-$\mathcal{Lite}$-based TDLs that are capable of representing various sets of TCM constructs and have as low computational complexity as possible. Let us first formulate our minimal requirements for such TDLs. At the model-theoretic level, we are interested in temporal interpretations that are Cartesian products of object domains and the flow of time $\mathbb{Z}$, $\mathbb{N}$. At each moment of time, we interpret the DL constructs over the same domain (thus complying with the constant domain assumption adopted in temporal databases [Chomicki et al. 2001]). We want to be able to specify, using temporal ABoxes, that a finite number of concept and role membership assertions hold at specific moments of time. We regard timestamping constraints as indispensable; this means, in particular, that we should be able to declare that certain roles and concepts are rigid (time-invariant) in the sense that their interpretations do not change over time. Other temporal and static (atemporal) modelling constraints are expressed by means of TBox axioms (concept and role inclusions). In fact, we observe that to represent TCM constraints, we only require concept and role inclusions that hold globally, at every time instant; thus, temporal and Boolean operators on TBox axioms [Artale et al. 2007; Baader et al. 2008; 2012] are not needed for our aims (but may be useful to impose constraints on schema evolution). Finally, in order to represent cardinality constraints (both snapshot and lifespan), we require number restrictions; thus, we assume this construct to be available in all of our formalisms.

The remaining options include the choice of (i) the underlying dialect of $\mathcal{DL}$-$\mathcal{Lite}$ for disjointness and covering constraints; (ii) the temporal operators on concepts for different types of evolution constraints, and (iii) the temporal operators on roles for lifespan cardinality constraints. For (i), we consider three DLs: $\mathcal{DL}$-$\mathcal{Lite}_{bool}^{HN}$ and its sub-Boolean fragments $\mathcal{DL}$-$\mathcal{Lite}_{krom}^{HN}$ and $\mathcal{DL}$-$\mathcal{Lite}_{core}^{HN}$. For (ii), we take various subsets of the standard future and past temporal operators (since and until, next and previous, sometimes and always, and covering constraints; (iii) the temporal operators on concepts for different types of evolution constraints. For (ii), we only use the undirected temporal operators ‘always’ and ‘sometime’ (referring to all time instants); roles in the scope of such operators are called temporalised.

Our most expressive TDL, based on $\mathcal{DL}$-$\mathcal{Lite}_{bool}^{HN}$, captures all the standard types of temporal constraints: timestamping, evolution and temporal cardinality. Unfortunately, and to our surprise, this TDL turns out to be undecidable. As follows from the proof of Theorem 6.1, it is a subtle interaction of functionality constraints on temporalised roles with the temporal operators and full Boolean on concepts that causes undecidability. On a more positive note, we show that even small restrictions of this interaction result in TDLs with better computational properties.

First, keeping $\mathcal{DL}$-$\mathcal{Lite}_{bool}^{HN}$ as the base DL but limiting the temporal operators on concepts to ‘always’ and ‘sometime’, we obtain an NP-complete logic, which can express timestamping and lifespan cardinalities. To appreciate this result, recall that a similar logic based on $\mathcal{ALC}$ is 2EXPSPACE-complete [Artale et al. 2007d]. Second, by giving up temporalised roles but retaining temporal operators on concepts, we obtain PSPACE- or NP-complete logics depending on the available temporal operators, which matches the complexity of the underlying propositional temporal logic. These TDLs have sufficient expressivity to capture timestamping and evolution constraints, but cannot represent temporal cardinality constraints (see Section 3). We prove these upper complexity bounds by a reduction to the propositional temporal logic $\mathcal{PTL}$, which opens a way to employ the existing temporal provers for checking quality properties of TCMs. Again, we note that a similar logic based on $\mathcal{ALC}$ is undecidable [Wolter and Zakharyaschev 1999; Artale et al. 2002; Gabbay et al. 2003].
We can reduce the complexity even further by restricting \( DL-Lite^{(\text{HN})} \) to its sub-Boolean fragments \( DL-Lite_{\text{com}}^{(\text{HN})} \) and \( DL-Lite_{\text{core}}^{(\text{HN})} \), which are unable to capture covering constraints. This results in logics within NP and PTIME. And if the temporal operators on concepts are limited to ‘always’ and ‘sometime’ then the two sub-Boolean fragments are \( \text{NLOGSPACE} \)-complete. To obtain these results we consider sub-Boolean fragments of \( PTL \) by imposing restrictions on both the type of clauses in Separated Normal Form [Fisher 1991] and the available temporal operators. We give a complete classification of such fragments according to their complexity (see Table III).

The rest of the article is organised as follows. Section 2 introduces, using a simple example, conceptual data modelling languages and illustrates how they can be captured by various dialects of \( DL-Lite \), which are formally defined in Section 2.2. Section 3 introduces temporal conceptual modelling constraints using a temporal extension of our example. In Section 3.2, we design \( DL-Lite \) based TDLs that can represent those constraints. Section 3.3 gives a detailed overview of the results obtained in this article together with a discussion of related work. Section 4 gives the reduction of TDLs to \( PTL \) mentioned above. In Section 5, we establish the complexity results for the clausal fragments of propositional temporal logic. Section 6 studies the complexity of TDLs with temporalised roles. We discuss the obtained results, open problems and future directions in Section 7.

2. CONCEPTUAL MODELLING AND DESCRIPTION LOGIC

Description logics (DLs; see, e.g., [Baader et al. 2003]) were designed in the 1980s as logic-based formalisms for knowledge representation and reasoning; their major application areas include ontologies in life sciences and the Semantic Web. Conceptual modelling languages [Chen 1976] are a decade older, and were developed for abstract data representation in database design. Despite apparent notational differences, both families of languages are built around concepts (or entities) and relationships using a number of ‘natural’ constructs; a close correspondence between them was discovered and investigated in [Calvanese et al. 1999; Borgida and Brachman 2003; Berardi et al. 2005; Artale et al. 2007a].

The \( DL-Lite \) description logics [Calvanese et al. 2005; 2007; Poggio et al. 2008; Artale et al. 2007b; 2009a] and the \( DL-Lite \)-based profile OWL 2 QL of OWL 2 have grown from the idea of linking relational databases and ontologies in the framework of ontology-based data access [Dolby et al. 2008; Heymans et al. 2008; Poggi et al. 2008]. The chief aims that determined the shape of the \( DL-Lite \) logics are: (i) the ability to represent basic constraints used in conceptual modelling, and (ii) the ability to support query answering using standard relational database systems. In this article, we concentrate on \( DL-Lite \) as a modelling language and briefly return to the issue of ontology-based data access (OBDA) in Section 7.

In this section, we give an intuitive example illustrating the main constructs of conceptual data models and their \( DL-Lite \) representations. In the example, we use the Extended Entity-Relationship (EER) language [Elmasri and Navathe 2007]; however, one can easily employ other conceptual modelling formalisms such as UML class diagrams (www.uml.org). Then we formally define the syntax and semantics of the \( DL-Lite \) logics to be used later on in this article.

2.1. A Motivating Example

Let us consider the EER diagram in Fig. 1 representing (part of) a company information system. The arrow from the entity Manager to the entity Employee stands for the statement ‘all managers are employees.’ The double arrow with a circle below Manager means that the set of managers is the union of the set of area managers and the set of top managers. These statements can be represented in the language of description logic as inclusions between concepts:

\[
\text{Manager} \sqsubseteq \text{Employee}, \quad \text{AreaManager} \sqsubseteq \text{Manager},
\]
\[
\text{Manager} \sqsubseteq \text{AreaManager} \sqcup \text{TopManager}, \quad \text{TopManager} \sqsubseteq \text{Manager}.
\]

Here \( \text{Manager}, \text{Employee}, \text{AreaManager}, \text{TopManager} \) are concept names (or unary predicates) and the symbols \( \sqsubseteq \) and \( \sqcup \) denote the usual set-theoretic inclusion and union, respectively. In a similar
way we read and represent the part of the EER diagram located below Organisational Unit; the only new ingredient here is the circled d, indicating that the union is disjoint:

\[ \text{Department} \sqsubseteq \text{OrganisationalUnit}, \quad \text{OrganisationalUnit} \sqsubseteq \text{Department} \sqsqcup \text{InterestGroup}, \quad \text{InterestGroup} \sqsubseteq \text{OrganisationalUnit}, \quad \text{Department} \sqcap \text{InterestGroup} \sqsubseteq \bot. \]

Here ⊕ denotes the empty set and □ the set-theoretic intersection.

The entity Employee in Fig. 1 has three attributes: Name, which is a string, and Payroll Number and Salary, both of which are integers. The attribute Payroll Number (underlined) is a key for the entity Employee. In description logic, we can encode attributes by means of roles (binary predicates). For example, to say that every employee has a salary, which is an integer number, we can represent the attribute Salary by a role, salary, together with the concept inclusions

\[ \text{Employee} \sqsubseteq \exists \text{salary}, \quad \exists \text{salary}^- \sqsubseteq \text{Integer}, \]

where \( \exists \text{salary} \) denotes the domain of salary, and \( \text{salary}^- \) is the inverse of salary, so that \( \exists \text{salary}^- \) is the range of salary. Then the fact that each individual has a unique salary attribute value can be expressed by the concept inclusion

\[ \geq 2 \text{salary} \sqsubseteq \bot, \]

where \( \geq 2 \text{salary} \) stands for the set of all domain elements with at least two values of salary attached to them (which must be empty according to this inclusion, i.e., salary is a functional role). The attributes Payroll Number and Name are represented in a similar manner. The fact that Payroll Number is a key for Employee can be encoded by the inclusion

\[ \geq 2 \text{payrollNumber}^- \sqsubseteq \bot. \]

Relationships are used to describe connections among objects from (possibly) different entities. Works On, Member and Manages in Fig. 1 are binary relationships. The argument emp of Works On is of type Employee in the sense that its values always belong to the entity Employee (in other words, Employee participates in Works On as emp). Likewise, the argument act of Works On is of type Project. In description logic, a binary relationship such as Works On can be represented by a role, say, \( \text{worksOn} \). If we agree that the first argument of \( \text{worksOn} \) corresponds to emp and the second to act, then the domain of \( \text{worksOn} \) belongs to Employee and its range to Project:

\[ \exists \text{worksOn} \sqsubseteq \text{Employee}, \quad \exists \text{worksOn}^- \sqsubseteq \text{Project}. \]

The expression \( (3, \infty) \) labelling the argument act of \( \text{worksOn} \) is a cardinality constraint meaning that every element of the set Project participates in at least three distinct tuples in the relationship Works On (each project involves at least three employees). This can be represented by the inclusion

\[ \text{Project} \sqsubseteq \geq 3 \text{worksOn}^- . \]
The expression $\langle 1, 1 \rangle$ labelling the argument $\text{prj}$ of the relationship $\text{Manages}$ means that each element of $\text{Project}$ participates in at least one and at most one (that is, exactly one) tuple in $\text{Manages}$, which is represented by two inclusions:

$$\text{Project} \subseteq \exists \text{manages}^{-}, \quad \text{Project} \subseteq \leq 1 \text{manages}^{-}.$$

Relationships of arity greater than 2 are encoded by using reification [Calvanese et al. 2001] (binary relationships can also be reified). For instance, to reify the binary relationship $\text{Works On}$, we introduce a new concept name, say $\text{C-WorksOn}$, and two functional roles, $\text{emp}$ and $\text{act}$, satisfying the following concept inclusions:

$$\text{C-WorksOn} \subseteq \exists \text{emp}, \quad \geq 2 \text{emp} \subseteq \bot, \quad \exists \text{emp} \subseteq \text{C-WorksOn}, \quad \exists \text{emp}^{-} \subseteq \text{Employee}, \quad (2)$$

$$\text{C-WorksOn} \subseteq \exists \text{act}, \quad \geq 2 \text{act} \subseteq \bot, \quad \exists \text{act} \subseteq \text{C-WorksOn}, \quad \exists \text{act}^{-} \subseteq \text{Project}. \quad (3)$$

Thus, each element of $\text{C-WorksOn}$ is related, via the roles $\text{emp}$ and $\text{act}$, to a unique pair of elements of $\text{Employee}$ and $\text{Project}$. Cardinality constraints are still representable for reified relations, e.g., the cardinality expressed by the formula (1) becomes

$$\text{Project} \subseteq \geq 3 \text{act}^{-}. \quad (4)$$

Of the data modelling constructs not used in Fig. 1, we mention here relationship generalisation, i.e., a possibility to state that one relationship is a subset of another relationship. For example, we can state that everyone managing a project must also work on the project. In other words: $\text{Manages}$ is a sub-relationship of $\text{Works On}$, which can be represented in description logic as the role inclusion $\text{manages} \sqsubseteq \text{worksOn}$ if both relationships are binary and not reified. On the other hand, if both relationships are reified then we need a concept inclusion between the respective reifying concepts as well as role inclusions between the functional roles for their arguments:

$$\text{C-Manages} \sqsubseteq \text{C-WorksOn}, \quad \text{prj} \sqsubseteq \text{act}, \quad \text{man} \sqsubseteq \text{emp}.$$

To represent database instances of a conceptual model, we use assertions such as $\text{Manager}(\text{bob})$ for ‘Bob is a manager’ and $\text{manages}(\text{bob, cronos})$ for ‘Bob manages Cronos.’

As conceptual data models can be large and contain non-trivial implicit knowledge, it is important to make sure that the constructed conceptual model satisfies certain quality properties. For example, one may want to know whether it is consistent, whether all or some of its entities and relationships are not necessarily empty or whether one entity or relationship is (not) subsumed by another. To automatically check such quality properties, it is essential to provide an effective reasoning support during the construction phase of a conceptual model.

We now define the reasoning problems formally, by giving the syntax and semantics of description logics containing the constructs discussed above.

### 2.2. DL-Lite Logics

We start with the logic called $\text{DL-Lite}_{\text{bool}}^\mathcal{N}$ in the nomenclature of Artale et al. [2009a]. The language of $\text{DL-Lite}_{\text{bool}}^\mathcal{N}$ contains object names $a_0, a_1, \ldots$, concept names $A_0, A_1, \ldots$, and role names $P_0, P_1, \ldots$. Roles $R$, basic concepts $B$ and concepts $C$ of this language are defined by the grammar:

$$R ::= P_k \mid P_k^-, \quad B ::= \bot \mid A_k \mid \geq q R, \quad C ::= B \mid \neg C \mid C_1 \cap C_2,$$

where $q$ is a positive integer represented in binary. A $\text{DL-Lite}_{\text{bool}}^\mathcal{N}$ $\mathcal{T}$Box, $\mathcal{T}$, is a finite set of concept inclusion axioms of the form

$$C_1 \sqsubseteq C_2.$$
An ABox, $A$, is a finite set of assertions of the form

$$A_k(a_i), \neg A_k(a_i), P_k(a_i, a_j), \neg P_k(a_i, a_j).$$

Taken together, $T$ and $A$ constitute the knowledge base (KB, for short) $K = (T, A)$.

An interpretation $I$ is a function $I$ that assigns to each object name $a_i$ an element $a_i^I \in \Delta^I$, to each concept name $A_k$ a subset $A_k^I \subseteq \Delta^I$, and to each role name $P_k$ a binary relation $P_k^I \subseteq \Delta^I \times \Delta^I$. As in databases, we adopt the unique name assumption (UNA): $a_i^I \neq a_j^I$ for all $i \neq j$ (note, however, that OWL does not use the UNA). The role and concept constructs are interpreted in $I$ as follows:

$$(P_k^-)^I = \{(y, x) \in \Delta^I \times \Delta^I \mid (x, y) \in P_k^I\},$$

$$\{x \in \Delta^I \mid \exists\{y \in \Delta^I \mid (x, y) \in R^I\} \geq q\},$$

$$(\neg C)^I = \Delta^I \setminus C^I,$$

$$(C_1 \cap C_2)^I = C_1^I \cap C_2^I,$$

where $\#X$ denotes the cardinality of $X$. We use the standard abbreviations:

$$C_1 \sqcup C_2 = \neg (\neg C_1 \sqcap \neg C_2), \quad \top = \neg \bot, \quad \exists R = (\geq 1) R, \quad \leq q R = (\geq q + 1) R.$$

Concepts of the form $\leq q R$ and $\geq q R$ are called number restrictions, and those of the form $\exists R$ are called existential concepts.

The satisfaction relation $\models$ is defined as expected:

$$I \models C_1 \sqsubseteq C_2 \iff C_1^I \subseteq C_2^I,$$

$$I \models A_k(a_i) \iff a_i^I \in A_k^I,$$

$$I \models \neg A_k(a_i) \iff a_i^I \notin A_k^I,$$

$$I \models P_k(a_i, a_j) \iff (a_i^I, a_j^I) \in P_k^I,$$

$$I \models \neg P_k(a_i, a_j) \iff (a_i^I, a_j^I) \notin P_k^I.$$

A knowledge base $K = (T, A)$ is said to be satisfiable (or consistent) if there is an interpretation $I$ satisfying all the members of $T$ and $A$. In this case we write $I \models K$ (as well as $I \models T$ and $I \models A$) and say that $I$ is a model of $K$ (and of $T$ and $A$). The satisfiability problem—given a KB $K$, decide whether $K$ is satisfiable—is the main reasoning problem we consider in this article.

Subsumption (given an inclusion $C_1 \sqsubseteq C_2$ and a TBox $T$), decide whether $I \models C_1^T \subseteq C_2^T$ for every model $I$ of $T$; or $T \models C_1 \sqsubseteq C_2$ in symbols) and concept satisfiability (given a concept $C$ and a TBox $T$, decide whether there is a model $I$ of $T$ such that $C^I \neq \emptyset$; or $T \models C \not\sqsubseteq \bot$) are reducible to satisfiability. For example, to check whether $T \models C_1 \sqsubseteq C_2$ we can construct a new KB $K = (T \cup \{A \sqsubseteq C_1, A \sqsubseteq \neg C_2\}, \{A(a)\})$ with a fresh concept name $A$, and check whether $K$ is not satisfiable.

The two sub-languages of DL-Lite$^{\text{core}}$ we deal with in this article are obtained by restricting the Boolean operators on concepts. In DL-Lite$^{\text{core}}$ TBoxes, concept inclusions are of the form

$$B_1 \sqsubseteq B_2,$$

(Here and below $B_1, B_2$ are basic concepts.) DL-Lite$^{\text{core}}$ only uses concept inclusions of the form

$$B_1 \sqsubseteq B_2 \quad \text{or} \quad B_1 \sqcap B_2 \sqsubseteq \bot.$$

As $B_1 \sqsubseteq \neg B_2$ is equivalent to $B_1 \sqcap B_2 \sqsubseteq \bot$, DL-Lite$^{\text{core}}$ is a sub-language of DL-Lite$^{\text{krom}}$. Although the Krom fragment does not seem to be more useful for conceptual modelling than DL-Lite$^{\text{core}}$, we shall see in Remark 3.2 that temporal extensions of DL-Lite$^{\text{krom}}$ can capture some important temporal modelling constructs that are not representable by the corresponding extensions of DL-Lite$^{\text{core}}$.

Most of the constraints in the company conceptual model from Section 2.1 were represented by means of DL-Lite$^{\text{core}}$ concept inclusions. The only exceptions were the covering constraints.

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4The Krom fragment of first-order logic consists of formulas in prenex normal form whose quantifier-free part is a conjunction of binary clauses.
Table I. Complexity of the DL-Lite logics.

| concept inclusions | role inclusions |
|--------------------|----------------|
|                     | DL-Lite\(N^\alpha\) | DL-Lite\((HN)^\alpha\) | DL-Lite\((HN)^\alpha\) |
| Bool               | NP              | NP                | ExpTime            |
| Krom               | NLOGSPACE       | NLOGSPACE         | ExpTime            |
| core               | NLOGSPACE       | NLOGSPACE         | ExpTime            |

Manager \sqsubseteq AreaManager \sqcup TopManager and OrganisationalUnit \sqsubseteq Department \sqcup InterestGroup, which belong to the language DL-Lite\(N^\alpha\)_bool, and the role inclusion manages \sqsubseteq worksOn. The extra expressive power, gained from the addition of covering constraints to DL-Lite\(N^\alpha\)_core, comes at a price [Artale et al. 2007b]: the satisfiability problem is NLOGSPACE-complete for DL-Lite\(N^\alpha\)_core and DL-Lite\(N^\alpha\)_bool KBs and NP-complete for DL-Lite\(N^\alpha\)_bool KBs.

The straightforward extension of DL-Lite\(N^\alpha\)_core with role inclusions of the form \(R_1 \sqsubseteq R_2\) (with \(I \models R_1 \sqsubseteq R_2 \iff R_1^I \subseteq R_2^I\)) leads to an even higher complexity: satisfiability becomes ExpTime-complete [Artale et al. 2009a]. The reason for this is the interaction of functionality constraints and role inclusions such as

\[ R_1 \sqsubseteq R_2 \quad \text{and} \quad \geq 2 R_2 \sqsubseteq \bot. \]

Note that inclusions of this sort are required when we use relationship generalisation with reification (see Section 2.1). If we restrict this interaction in TBoxes \(T\) by requiring that no role \(R\) can occur in \(T\) in both a role inclusion of the form \(R' \sqsubseteq R\) and a number restriction \(\geq q R\) or \(\geq q R^-\) with \(q \geq 2\), then the complexity of satisfiability checking with such TBoxes matches that of the language without role inclusions. The extension of DL-Lite\(N^\alpha\), where \(\alpha \in \{\text{core}, \text{krom}, \text{bool}\}\), with role inclusions satisfying the condition above is denoted by DL-Lite\((HN)^\alpha\); without this condition, the extension is denoted by DL-Lite\((HN)^\alpha\). Table I summarises the complexity of the KB satisfiability problem for DL-Lite logics (for details, consult [Artale et al. 2009a]).

Thus, already in the atemporal case, a conceptual data model engineer has to search for a suitable compromise between the expressive power of the modelling language and efficiency of reasoning. In the temporal case, the trade-off between expressiveness and efficiency becomes even more dramatic.

In the next section, we extend the atemporal conceptual data model considered above with a number of temporal constructs and use them to design a family of temporal description logics that are suitable for temporal conceptual modelling.

3. TEMPORAL CONCEPTUAL MODELLING AND TEMPORAL DESCRIPTION LOGIC

Temporal conceptual data models extend standard conceptual schemas with means to visually represent temporal constraints imposed on temporal database instances [Theodoulidis et al. 1991; Tauszovich 1991; Jensen and Snodgrass 1999; Artale et al. 2003; Parent et al. 2006; Combi et al. 2008].

When introducing a temporal dimension into conceptual data models, time is usually modelled by a linearly ordered set of time instants, so that at each moment of time we can refer to its past and future. In this article, we assume that the flow of time is isomorphic to the strictly linearly ordered set \((\mathbb{Z}, <)\) of integer numbers. (For a survey of other options, including interval-based and branching models of time, consult, e.g., [Gabbay et al. 1994; Gabbay et al. 2000; Gabbay et al. 2003].)

We will now introduce the most important temporal conceptual modelling constructs by extending the company information system example from Section 2.1.

3.1. The Motivating Example Temporalised

A basic assumption in temporal conceptual models is that entities, relationships and attributes may freely change over time as long as they satisfy the constraints of the schema at each time instant. Temporal constructs are used to impose constraints on the temporal behaviour of various com-
ponents of conceptual schemas. We group these constructs into three categories—timestamping, evolution and temporal cardinality constraints—and illustrate them by the model in Fig. 2.

Timestamping constraints [Theodoulidis et al. 1991; Gregersen and Jensen 1998; 1999; Finger and McBrien 2000; Artale and Franconi 1999; Parent et al. 2006] distinguish between entities, relationships and attributes that are

- **temporary** in the sense that no element belongs to them at all moments of time,
- **snapshot**, or time-invariant, in the sense that their interpretation does not change with time,
- **unconstrained** (all others).

In temporal entity-relationship diagrams, the temporary entities, relationships and attributes are marked with $T$ and the snapshot ones with $S$. In Fig. 2, Employee and Department are snapshot entities, Name, Payroll Number and Project Code are snapshot attributes and Member a snapshot relationship. On the other hand, Manager is a temporary entity, Salary a temporary attribute, and Works On a temporary relationship.

There are (at least) two ways of representing timestamping constraints in temporal description logics. One of them is to introduce special names for temporary and snapshot concepts and roles, and interpret them accordingly. Another way is to employ a temporal operator $\square$, which is read as ‘always’ or ‘at all—past, present and future—time instants.’ Intuitively, for a concept $C$, $\square C$ contains those elements that belong to $C$ at all time instants. Using this operator, the constraints ‘Employee is a snapshot entity’ and ‘Manager is a temporary entity’ can be represented as follows:

$$
\text{Employee} \sqsubseteq \square \text{Employee}, \quad \square \text{Manager} \sqsubseteq \bot.
$$

The first inclusion says that, at any moment of time, every element of Employee has always been and will always be an element of Employee. The second one states that no element can belong to Manager at all time instants. Note that both of these concept inclusions are meant to hold **globally**, that is, at all moments of time.

The same temporal operator $\square$ together with rigid roles (i.e., roles that do not change over time) can be used to capture timestamping of reified relationships. If the relationship Member is reified by the concept $C$-Member with two functional roles $\text{org}$ and $\text{mbr}$, satisfying the concept inclusions similar to (2) and (3), then the requirement that both roles $\text{org}$ and $\text{mbr}$ are rigid ensure that Member is a snapshot relationship. On the other hand, for the reified temporary relationship Works On we require the concept inclusion

$$
\square C-\text{WorksOn} \sqsubseteq \bot
$$

and two flexible roles $\text{emp}$ and $\text{act}$, which can change arbitrarily. Rigid roles are also used to represent both snapshot attributes and snapshot binary relationships. Temporary attributes can be captured by flexible roles or by using temporalised roles:

$$
\exists \square \text{salary} \sqsubseteq \bot,
$$

Fig. 2. A temporal conceptual model of a company information system.
where $\sqcap \text{salary}$ denotes the intersection of the relations salary at all time instants.

Evolution constraints control how the domain elements evolve over time by ‘migrating’ from one entity to another [Hall and Gupta 1991; Mendelzon et al. 1994; Su 1997; Artale et al. 2007e]. We distinguish between qualitative evolution constraints that describe generic temporal behaviour but do not specify the moment of migration, and quantitative evolution (or transition) constraints that specify the exact moment of migration. The dashed arrow marked with $\text{TEX}$ (Transition EXTension\(^3\)) in Fig. 2 is an example of a quantitative evolution constraint meaning that each project expires in exactly one time unit (one year) and becomes an instance of $\text{ExProject}$. The dashed arrow marked with $\text{DEV}$ (Dynamic EVolution) is a qualitative evolution constraint meaning that every area manager will eventually become a top manager. The $\text{DEX}^{-}$ (Dynamic EXTension) dashed arrow says that every manager was once an employee, while the $\text{PEX}$ (Persistent EXTension) dashed arrow means that a manager will always be a manager and cannot be demoted.

In temporal description logic, these evolution constraints are represented using temporal operators such as ‘at the next moment of time’ $\diamond_p$, ‘sometime in the future’ $\diamond_f$, ‘sometime in the past’ $\diamond_p$ and ‘always in the future’ $\Box_f$:

$$
\text{Project} \sqsubseteq \diamond_p \text{ExProject}, \quad \text{AreaManager} \sqsubseteq \diamond_p \text{TopManager},
$$

$$
\text{Manager} \sqsubseteq \diamond_p \text{Employee}, \quad \text{Manager} \sqsubseteq \Box_p \text{Manager}.
$$

Again, these concept inclusions must hold globally. In the following, the evolution constraints that involve $\diamond_p$ and $\diamond_f$ will be called migration constraints.

Temporal cardinality constraints [Tauzovich 1991; McBrien et al. 1992; Gregersen and Jensen 1998] restrict the number of times an instance of an entity participates in a relationship. Snapshot cardinality constraints do that at each moment of time, while lifespan cardinality constraints impose restrictions over the entire existence of the instance as a member of the entity. In Fig. 2, we use $(k, l)$ to specify the snapshot cardinalities and $|k, l|$ the lifespan cardinalities: for example, at any moment, every top manager manages exactly one project, but not more than five different projects over the whole career. If the relationship $\text{Manages}$ is not reified and represented by a role in temporal description logic then these two constraints can be expressed by the following concept inclusions:

$$
\text{TopManager} \sqsubseteq \exists \text{manages} \sqcap \leq 1 \text{manages}, \quad \text{TopManager} \sqsubseteq \leq 5 \otimes \text{manages},
$$

where $\otimes$ means ‘sometime’ (in the past, present or future), and so $\otimes \text{manages}$ is the union of the relations manages over all time instants. Snapshot and lifespan cardinalities can also be expressed in a similar way even for reified relationships (see, e.g., (4) which captures snapshot cardinalities). Observe that the above inclusions imply, in particular, that no one can remain a top manager for longer than five years (indeed, each top manager manages at least one project a year, each project expires in a year, and no top manager can manage more than five projects throughout the lifetime).

However, this is inconsistent with ‘every manager always remains a manager’, and so the entity $\text{Manager}$ cannot be populated by instances, which, in turn, means that $\text{Project}$ must also be empty (since each project is managed by a top manager). One can make these entities consistent by, for example, dropping the persistence constraint on $\text{Manager}$ or the upper lifespan cardinality bound on the number of projects a top manager can manage throughout the lifetime. In large schemas, situations like this can easily remain undetected if the quality check is performed manually.

To represent temporal database instances, we use assertions like $\diamond_p \text{Manager}(bob)$ for ‘Bob was a manager last year’ and $\diamond_p \text{manages}(bob, cronos)$ for ‘Bob will manage Cronos next year.’

### 3.2. Temporal DL-Lite Logics

It is known from temporal logic [Gabbay et al. 1994] that all the temporal operators used in the previous section can be expressed in terms of the binary operators $\mathcal{S}$ ‘since’ and $\mathcal{U}$ ‘until’ (details will be given below). So we formulate our ‘base’ temporal extension $T_{\mathcal{U}\mathcal{S}}\text{DL-Lite}_{\text{bool}}^N$ of the description

---

\(^3\)We refer to [Artale et al. 2010] for a detailed explanation of the various evolution constraints and their naming convention.
logic $DL\text{-}Lite^N_{\text{bool}}$ using only these two operators. The language of $T_{\text{lit}}DL\text{-}Lite^N_{\text{bool}}$ contains object names $a_0, a_1, \ldots$, concept names $A_0, A_1, \ldots$, flexible role names $P_0, P_1, \ldots$, and rigid role names $G_0, G_1, \ldots$. Basic concepts $B$, concepts $C$ and temporal concepts $D$ are given by the following grammar:

$$\begin{align*}
B & ::= \bot \mid A_i \mid \geq q R, \\
C & ::= B \mid D \mid \neg C \mid C_1 \sqcap C_2, \\
D & ::= C \mid C_1 U C_2 \mid C_1 S C_2,
\end{align*}$$

where, as before, $q$ is a positive integer given in binary. (We use two separate rules for $C$ and $D$ here because in the definitions of the fragments of $T_{\text{lit}}DL\text{-}Lite^N_{\text{bool}}$ below these rules will be restricted to the corresponding sub-Boolean and temporal fragments.) A $T_{\text{lit}}DL\text{-}Lite^N_{\text{bool}}$ TBox, $T$, is a finite set of concept inclusions of the form $C_1 \sqsubseteq C_2$. An ABox, $A$, consists of assertions of the form

$$\circ^n A_k(a_i), \quad \circ^n \neg A_k(a_i), \quad \circ^n S(a_i, a_j) \quad \text{and} \quad \circ^n \neg S(a_i, a_j),$$

where $A_k$ is a concept name, $S$ a (flexible or rigid) role name, $a_i, a_j$ object names and, for $n \in \mathbb{Z}$,

$$\circ^n = \underbrace{\circ \cdots \circ}_{n \text{ times}}, \quad \text{if } n \geq 0 \quad \text{and} \quad \circ^n = \underbrace{\circ \cdots \circ}_{-n \text{ times}}, \quad \text{if } n < 0.$$

Note that we use $\circ^n$ as an abbreviation and take the size of $\circ^n$ to be $n$ (in other words, the numbers $n$ in ABox assertions are given in unary). Taken together, the TBox $T$ and ABox $A$ form the knowledge base (KB) $K = (T, A)$.

A temporal interpretation is a pair $\mathcal{I} = (\Delta^T, \mathcal{I}(n))$, where $\Delta^T$ is a non-empty interpretation domain and $\mathcal{I}(n)$ gives a standard DL interpretation for each time instant $n \in \mathbb{Z}$:

$$\mathcal{I}(n) = (\Delta^T, a_0^T, \ldots, A_0^{\mathcal{I}(n)}, \ldots, P_0^{\mathcal{I}(n)}, \ldots, G_0^T, \ldots).$$

We assume, however, that the domain $\Delta^T$ and the interpretations $a_i^T \in \Delta^T$ of object names and $G_i^T \subseteq \Delta^T \times \Delta^T$ of rigid role names are the same for all $n \in \mathbb{Z}$. (For a discussion of the constant domain assumption, consult [Gabbay et al. 2003].) Recall also that we adopt the UNA.) The interpretations $A_i^{\mathcal{I}(n)} \subseteq \Delta^T$ of concept names and $P_i^{\mathcal{I}(n)} \subseteq \Delta^T \times \Delta^T$ of flexible role names can vary. The atemporal constructs are interpreted in $\mathcal{I}(n)$ as before; we write $C^{\mathcal{I}(n)}$ for the extension of $C$ in $\mathcal{I}(n)$. The interpretation of the temporal operators is as follows:

$$\begin{align*}
(C_1 U C_2)^{\mathcal{I}(n)} &= \bigcup_{k>n} (C_2^{\mathcal{I}(k)} \cap \bigcap_{n<m<k} C_1^{\mathcal{I}(m)}), \\
(C_1 S C_2)^{\mathcal{I}(n)} &= \bigcup_{k<n} (C_2^{\mathcal{I}(k)} \cap \bigcap_{n>m>k} C_1^{\mathcal{I}(m)}).
\end{align*}$$

Thus, for example, $x \in (C_1 U C_2)^{\mathcal{I}(n)}$ iff there is a moment $k > n$ such that $x \in C_2^{\mathcal{I}(k)}$ and $x \in C_1^{\mathcal{I}(m)}$, for all moments $m$ between $n$ and $k$. Note that the operators $S$ and $U$ (as well as the $\sqcap$ and $\sqcup$ operators to be defined below) are ‘strict’ in the sense that their semantics does not include the current moment of time. The non-strict operators, which include the current moment, are obviously definable in terms of the strict ones.

As noted above, for the aims of TCM it is enough to interpret concept inclusions in $\mathcal{I}$ globally:

$$\mathcal{I} \models C_1 \sqsubseteq C_2 \quad \text{iff} \quad C_1^{\mathcal{I}(n)} \subseteq C_2^{\mathcal{I}(n)} \quad \text{for all } n \in \mathbb{Z}.$$
ABox assertions are interpreted relatively to the initial moment, 0. Thus, we set:

\[ \mathcal{I} \models \bigcirc^n A_k(a_i) \iff a_i^T \in A_k^{(n)}, \quad \mathcal{I} \models \bigcirc^n S(a_i, a_j) \iff (a_i^T, a_j^T) \in S^{(n)}, \]
\[ \mathcal{I} \models \bigcirc^n - A_k(a_i) \iff a_i^T \notin A_k^{(n)}, \quad \mathcal{I} \models \bigcirc^n - S(a_i, a_j) \iff (a_i^T, a_j^T) \notin S^{(n)}. \]

We call \( \mathcal{I} \) a model of a KB \( \mathcal{K} \) and write \( \mathcal{I} \models \mathcal{K} \) if \( \mathcal{I} \) satisfies all elements of \( \mathcal{K} \). \( \mathcal{K} \) is satisfiable if it has a model. A concept \( C \) (role \( R \)) is satisfiable with respect to \( \mathcal{K} \) if there are a model \( \mathcal{I} \) of \( \mathcal{K} \) and \( n \in \mathbb{Z} \) such that \( C^{(n)} \neq \emptyset \) (respectively, \( R^{(n)} \neq \emptyset \)). It is readily seen that the concept and role satisfiability problems are equivalent to KB satisfiability.

We now define a few fragments and extensions of the base language \( T_{DL-Lite}^{N \text{bool}} \). Recall that to say that \( C \) is a snapshot concept, we need the ‘always’ operator \( \Box \) with the following meaning:

\[ (\Box C)^{I(n)} = \bigcap_{k \in \mathbb{Z}} C^{(k)}. \]

The dual operator ‘sometime’ is defined as usual: \( \Diamond C = \neg \Box \neg C \). In terms of \( S \) and \( U \), it can be represented as \( \Diamond C = \top U (\top S C) \). Define \( T_{DL-Lite}^{N \text{bool}} \) to be the sublanguage of \( T_{DL-Lite}^{N \text{bool}} \) the temporal concepts \( D \) in which are of the form

\[ D ::= C \mid \Box C. \]  

(U)

Thus, in \( T_{DL-Lite}^{N \text{bool}} \), we can express timestamping constraints (see Section 3.1).

The temporal operators \( \Diamond \) (‘sometime in the future’) and \( \Diamond_\rho \) (‘sometime in the past’) that are required for qualitative evolution constraints with the standard temporal logic semantics

\[ (\Diamond_\rho C)^{I(n)} = \bigcup_{k > n} C^{(k)} \quad \text{and} \quad (\Diamond_\rho C)^{I(n)} = \bigcup_{k < n} C^{(k)} \]

can be expressed via \( U \) and \( S \) as \( \Diamond_\rho C = \top U (\top S C) \) and \( \Diamond_\rho C = \top S C \); the operators \( \Box_\rho \) (‘always in the future’) and \( \Box_\rho \) (‘always in the past’) are defined as dual to \( \Diamond_\rho \) and \( \Diamond_\rho \): \( \Box_\rho C = \neg \Diamond_\rho \neg C \) and \( \Box_\rho C = \neg \Diamond_\rho \neg C \). We define the fragment \( T_{FPX}^{DL-Lite}^{N \text{bool}} \) of \( T_{DL-Lite}^{N \text{bool}} \) by restricting the temporal concepts \( D \) to the form

\[ D ::= C \mid \Box_\rho C \mid \Diamond_\rho C. \]  

(FP)

Clearly, we have the following equivalences:

\[ \Box C = \Box_\rho \Box_\rho C \quad \text{and} \quad \Diamond C = \Diamond_\rho \Diamond_\rho C. \]

In what follows, these equivalences will be regarded as definitions for \( \Box \) and \( \Diamond \) in those languages where they are not explicitly present. Thus, \( T_{FPX}^{DL-Lite}^{N \text{bool}} \) is capable of expressing both timestamping and qualitative (but not quantitative) evolution constraints.

The temporal operators \( \Diamond_\rho \) (‘next time’) and \( \Diamond_\rho \) (‘next previous time’), used in quantitative evolution constraints, can be defined as \( \Diamond_\rho C = \bigcup U C \) and \( \Diamond_\rho C = \bigcup S C \), so that we have

\[ (\Diamond_\rho C)^{I(n)} = C^{I(n+1)} \quad \text{and} \quad (\Diamond_\rho C)^{I(n)} = C^{I(n-1)}. \]

The fragment of \( T_{DL-Lite}^{N \text{bool}} \) with temporal concepts of the form

\[ D ::= C \mid \Box_\rho C \mid \Diamond_\rho C \mid \Diamond_\rho C \]  

(FPX)

will be denoted by \( T_{FPX}^{DL-Lite}^{N \text{bool}} \). In this fragment, we can express timestamping, qualitative and quantitative evolution constraints.

Thus, we have the following inclusions between the languages introduced above:

\[ T_{DL-Lite}^{N \text{bool}} \subseteq T_{FPX}^{DL-Lite}^{N \text{bool}} \subseteq T_{FPX}^{DL-Lite}^{N \text{bool}} \subseteq T_{DL-Lite}^{N \text{bool}}. \]
Similarly to the atemporal case, we can identify sub-Boolean fragments of the above languages. A temporal TBox is called a Krom or a core TBox if it contains only concept inclusions of the form

\[ D_1 \sqsubseteq D_2, \quad D_1 \sqsubseteq \neg D_2, \quad \neg D_1 \sqsubseteq D_2, \quad (krom) \]

\[ D_1 \sqsubseteq D_2, \quad D_1 \cap D_2 \sqsubseteq \bot, \quad (core) \]

respectively, where the \( D_i \) are temporal concepts defined by (FPX), (FP) or (U) with

\[ C ::= B \mid D. \]

Note that no Boolean operators are allowed in the \( D_i \). This gives us 6 fragments: \( T_{FPX}DL-Lite^N \), \( T_{FP}DL-Lite^N \) and \( T_{FP}DL-Lite^N \), for \( \alpha \in \{ \text{core}, \text{krom} \} \).

**Remark 3.1.** We do not consider the core and Krom fragments of the full language with since (S) and until (U) because, as we shall see in Section 4.4 (Theorem 4.5), these operators allow one to go beyond the language of binary clauses of the core and Krom fragments, and the resulting languages would have the same complexity as \( T_{ises}DL-Lite^N \) (but less expressive).

**Remark 3.2.** The introduced fragments of the full language \( T_{ises}DL-Lite^N \), do not contain \( \diamond \) and \( \lozenge_i \). Both operators, however, can be defined in the Krom and Bool fragments. For example, the concept inclusion \( \lozenge_i B_1 \sqsubseteq \lozenge_i B_2 \) can be represented by means of the inclusions

\[ \lozenge_i A_2 \sqsubseteq \lozenge_i A_1 \quad \text{and} \quad A_i \sqsubseteq \neg B_i, \quad \neg B_i \sqsubseteq A_i, \quad \text{for } i = 1, 2. \]

In the core fragments, where we do not have negation in the left-hand side, this trick does not work. Therefore, evolution constraints involving \( \lozenge_i \) or \( \lozenge \) (such as Manager \( \sqsubseteq \diamond \text{Employee} \)) are not expressible in the core fragments (but timestamping remains expressible).

As we have seen in our running example, in order to express lifespan cardinality constraints, temporal operators on roles are required. For a role \( R \) of the form

\[ R ::= S \mid S^- \mid \diamond R \mid \Box R, \]

we define the extensions of \( \diamond R \) and \( \Box R \) in an interpretation \( \mathcal{I} \) by taking

\[ (\diamond \mathcal{I})^{(n)}(k) = \bigcup_{k \in \mathbb{Z}} R^{(k)}(n) \quad \text{and} \quad (\Box \mathcal{I})^{(n)} = \bigcap_{k \in \mathbb{Z}} R^{(k)}(n). \]

In this article we consider three extensions of \( DL-Lite^N \) with such temporalised roles, which are denoted by \( T_{ises}DL-Lite^N_{pool} \), for \( \beta \in \{ X, FP, U \} \), where \( T_{ises}DL-Lite^N_{pool} \) allows only \( \lozenge_i, \lozenge \) as the temporal operators on concepts.

We can also extend our languages with role inclusions, which are interpreted globally (in the same way as concept inclusions):

\[ \mathcal{I} \models R_1 \sqsubseteq R_2 \quad \text{iff} \quad R_1^{(n)} \subseteq R_2^{(n)}, \quad \text{for all } n \in \mathbb{Z}. \]

These extensions are denoted by \( T_{ises}DL-Lite^N_{pool} \), \( T_{FP}DL-Lite^N_{pool} \), etc.

In the remaining part of the article, we investigate the computational complexity of the satisfiability problem for the temporal extensions of the \( DL-Lite^N \) logics designed above. But before that we briefly summarise the obtained results in the more general context of temporal description logics.

### 3.3. Summary of the Complexity Results and Related Work

The temporal \( DL-Lite^N \) logics we analyse here are collected in Table II together with the obtained and known complexity results. (Note that the complexity bounds in Table II are all tight except the case of \( T_{FP}DL-Lite^N_{core} \), where we only have an upper bound.) To avoid clutter, we omitted from the table the logics of the form \( T_{\beta}DL-Lite^N_{\alpha} \), whose complexity is the same as the complexity of the respective \( T_{\beta}DL-Lite^N_{\alpha} \).

The analysis of the constructs required for temporal conceptual modelling in Sections 2.1 and 3.1 has led us to temporalisations of \( DL-Lite^N \) logics, interpreted over the Cartesian products of object
Artale and Franconi [1998] gave a subclass of decidable interval-based temporal DLs. If we also require migration constraints (that involve tensions of ALC DLs were interval-based [Schmiedel 1990; Bettini 1997] considered interval-based temporal extensions of ALC in the style of Halpern and Shoham [1991] and established their decidability. Artale and Franconi [1998] gave a subclass of decidable interval-based temporal DLs.

domains and the flow of time (Z, <), in which (1) the future and past temporal operators can be applied to concepts; (2) roles can be declared flexible or rigid; (3) the ‘undirected’ temporal operators ‘always’ and ‘sometime’ can be applied to roles; (4) the concept and role inclusions are global, and the database (ABox) assertions are specified to hold at particular moments of time. The minimal logic required to capture all of the temporal and static conceptual modelling constraints is $T^{N\bowtie}_{FPX}$—alas, it is undecidable. In fact, even the logic $T^N_{X}$, capturing only the quantitative evolution constraints, lifespan cardinalities and covering, is undecidable. Replacing ‘quantitative’ with ‘qualitative’—i.e., considering $T^{N\bowtie}_{FPX}$—does not beat undecidability in the presence of lifespan cardinalities. Both these undecidability results will still hold if we replace arbitrary cardinality constraints ($\forall N$) with role functionality. To regain decidability in the presence of temporalised roles, we have to limit the temporal operators on concepts to the undirected operators $\bowtie / \exists$—thus restricting the language to only timestamping and lifespan cardinalities. We show that the logic $T^N_{FPX}$ is NP-complete using the quasimodel technique.

Logics in the last row have arbitrary role inclusions, which together with functionality constraints are expressive enough to model all ALC constructors [Artale et al. 2007a; Artale et al. 2009a], and so the resulting TDLs are as complex as the corresponding temporal extensions of ALC.

On a positive note, logics with restricted role inclusions and no temporal operators on roles exhibit much better computational properties. Our smallest logic, $T_{DL-Lite}^{N\bowtie}_{H\bowtie}$, is NL-complete. In the temporal dimension, it can only express timestamping constraints. It can also capture all the static constraints that are different from covering and do not involve any interaction between role inclusions and number restrictions. Extending the language with covering leads to the loss of tractability in $T_{DL-Lite}^{N\bowtie}_{H\bowtie}$. When covering is not needed and we are interested in temporal constraints different from lifespan cardinalities, we can regain tractability if we restrict the language to timestamping and evolution constraints that only capture persistence ($T_{FPX}^{N\bowtie}_{L\bowtie}$). If we also require migration constraints (that involve $\bowtie \land \bowtie$; see Remark 3.2); then we can use the Krom language $T^{N\bowtie}_{FPX}$, which is again NP-complete. Surprisingly, the addition of the full set of evolution constraints makes reasoning NP-complete even in $T^{N\bowtie}_{FPX}$. To better appreciate the formalisms designed in this article, we consider them in a more general context of temporal description logics (for more detailed surveys consult [Artale and Franconi 2001; 2005; Gabbay et al. 2003; Lutz et al. 2008]). Historically, the first temporal extensions of DLs were interval-based [Schmiedel 1990]. Bettini [1997] considered interval-based temporal extensions of ALC in the style of Halpern and Shoham [1991] and established their undecidability. Artale and Franconi [1998] gave a subclass of decidable interval-based temporal DLs.
Numerous point-based temporal DLs have been constructed and investigated since Schild’s seminal paper [1993]. One of the lessons of the 20-year history of the discipline is that logics interpreted over two- (or more) dimensional structures are very complex and sensitive to subtle interactions between constructs operating in different dimensions. The first TDLs suggested for representing TCMs were based on the expressive DLs $DLC Q\ell$ and $ALC Q T$ [Artale and Franconi 1999]. However, it turned out that already a single rigid role and the operator $\Diamond_p$ (or $\Box_p$) on $ALC$-concepts led to undecidability [Wolter and Zakharyaschev 1999]. In fact, to construct an undecidable TDL, one only needs a rigid role and three concept constructs: $\sqcap$, $\exists R.C$ and $\Diamond_p$, that is, a temporalised $\mathcal{EL}$ [Artale et al. 2007c]. There have been several attempts to tame the bad computational behaviour of TDLs by imposing various restrictions on the DL and temporal components as well as their interaction.

One approach was to disallow rigid roles and temporal operators on roles, which resulted in EXPSpace-complete temporalisations of $ALC$ [Artale et al. 2002; Gabbay et al. 2003]. Such temporalisations reside in the monodic fragment\(^6\) of first-order temporal logic [Hodkinson et al. 2000], for which tableau [Lutz et al. 2002; Kontchakov et al. 2004] and resolution [Degtyarev et al. 2006] reasoning algorithms have been developed and implemented [Hustadt et al. 2004; Guensel 2005; Ludwig and Hustadt 2010]. Another idea was to weaken the whole temporal component to the ‘undirected’ temporal operators $\Box$ and $\Diamond$ (which cannot discriminate between past, present and future) on concepts and roles, resulting in a 2EXPTIME-complete extension of $ALC$ [Artale et al. 2007d]. The third approach was to allow arbitrary temporal operators on $ALC$ axioms only (but not on concepts or roles) [Baader et al. 2008; 2012], which gave an EXPTIME-complete logic. The addition of rigid concepts to this logic increases the complexity to NEXPTIME, while rigid concepts and roles make it 2EXPTIME-complete. Finally, the fourth approach, which dates back to Schild [1993], was to use only global axioms. In this case, $ACC$ with temporal operators on concepts is EXPTIME-complete, which matches the complexity of $ACC$ itself (in contrast, temporal operators on axioms and concepts make the less expressive $DL-Lite_{bool}$ EXPSpace-complete [Artale et al. 2007c]).

As argued above, global axioms are precisely what we need in TCM. On the other hand, to capture timestamping and evolution constraints we need the full set of temporal operators on concepts, while to capture lifespan cardinalities and timestamping on relations we need temporalised or rigid roles. To achieve decidability in the case with rigid roles, we also weaken $ACC$ to $DL-Lite$, which, as we have seen above, perfectly suits the purpose of conceptual modelling. We thus start from the first promising results of Artale et al. [2009b], which demonstrated that even with rigid roles temporal extensions of $DL-Lite_{bool}$ could be decidable, and extend them to various combinations of temporal operators and different sub-Boolean fragments of $DL-Lite_{bool}$, proving encouraging complexity results and showing how these logics can represent TCM schemas.

The results in the first three rows of Table II are established by using embeddings into the propositional temporal logic $PTL$. To cope with the sub-Boolean core and Krom logics, we introduce, in Section 5, a number of new fragments of $PTL$ by restricting the type of clauses in Separated Normal Form [Fisher 1991] and the available temporal operators. The obtained complexity classification in Table III helps understand the results in the first three rows of Table II.

4. REDUCING TEMPORAL DL-LITE TO PROPOSITIONAL TEMPORAL LOGIC

In this section we reduce the satisfiability problem for $T_{ULS}DL-Lite_{bool}^N$ KBs to the satisfiability problem for propositional temporal logic. This will be achieved in two steps. First, we reduce $T_{ULS}DL-Lite_{bool}^N$ to the one-variable first-order temporal logic $QTL^1$ [Gabbay et al. 2003]. And then we show that satisfiability of the resulting $QTL^1$-formulas can be further reduced to satisfiability of $QTL^1$-formulas without positive occurrences of existential quantifiers, which are essentially propositional temporal formulas. To simplify presentation, we consider here the logic $T_{ULS}DL-Lite_{bool}^{(NN)}$ (without role inclusions). The full $T_{ULS}DL-Lite_{bool}^{(NN)}$ requires a bit more elaborate (yet absolutely routine) reduction that is similar to the one given by Artale et al. [2009b] for the atemporal case.

---

\(^6\)A temporal formula is monodic if all of its sub-formulas beginning with a temporal operator have at most one free variable.
4.1. First-Order Temporal Logic

The language of first-order temporal logic QTL contains predicates $P_0$, $P_1$, \ldots (each with its arity), variables $x_0, x_1, \ldots$ and constants $a_0, a_1, \ldots$. Formulas $\varphi$ of QTL are defined by the grammar:

$$\varphi ::= P_i(t_1, \ldots, t_k) \mid \bot \mid \forall x \varphi \mid \neg \varphi \mid \varphi_1 \land \varphi_2 \mid \varphi_1 \cup \varphi_2 \mid \varphi_1 \S \varphi_2,$$

where $k_i$ is the arity of $P_i$ and the $t_j$ are terms—i.e., variables or constants. These formulas are interpreted in first-order temporal models $\mathcal{M}$, which, for every $n \in \mathbb{Z}$, give a first-order structure

$$\mathcal{M}(n) = (\Delta^n, a^n_0, a^n_1, \ldots, P^n_0, P^n_1, \ldots)$$

with the same domain $\Delta^n$, the same $a^n_i \in \Delta$, for each constant $a_i$, and where $P^n_i$ is a $k_i$-ary relation on $\Delta^n$, for each predicate $P_i$ of arity $k_i$ and each $n \in \mathbb{Z}$. An assignment in $\mathcal{M}$ is a function $a$, that maps variables to elements of $\Delta^n$. For a term $t$, we write $t^n\mathcal{M}$ for $a(x)$ if $t = x$, and for $\phi^n\mathcal{M}$ if $t = a$. The semantics of QTL is standard (see, e.g., [Gabbay et al. 2003]):

- $\mathcal{M}, n \models^a P(t_1, \ldots, t_k)$ if $(t^n_1, \ldots, t^n_k) \in P^n$.
- $\mathcal{M}, n \not\models^a \bot$.
- $\mathcal{M}, n \models^a \forall x \varphi$ if $\mathcal{M}, n \models^a \varphi$, for all assignments $\varphi'$ that differ from $\varphi$ on $x$ only.
- $\mathcal{M}, n \models^a \neg \varphi$ if $\mathcal{M}, n \not\models^a \varphi$.
- $\mathcal{M}, n \models^a \varphi_1 \land \varphi_2$ if $\mathcal{M}, n \models^a \varphi_1$ and $\mathcal{M}, n \models^a \varphi_2$.
- $\mathcal{M}, n \models^a \varphi_1 \cup \varphi_2$ if there is $k > n$ with $\mathcal{M}, k \models^a \varphi_2$ and $\mathcal{M}, m \models^a \varphi_1$, for $n < m < k$.
- $\mathcal{M}, n \models^a \varphi_1 \S \varphi_2$ if there is $k < n$ with $\mathcal{M}, k \models^a \varphi_2$ and $\mathcal{M}, m \models^a \varphi_1$, for $k < m < n$.

We use the standard abbreviations such as

- $\top = \bot,$
- $\varphi_1 \lor \varphi_2 = \neg (\neg \varphi_1 \land \neg \varphi_2),$ 
- $\exists x \varphi = \neg \forall x \neg \varphi,$
- $\forall \varphi = \top \U \varphi,$
- $\forall \varphi = \neg \forall \varphi,$
- $\forall \varphi = \bot \U \varphi$

as well as the past counterparts for $\forall \varphi,$ $\forall \varphi,$ and $\forall \varphi$; we also write $\forall \varphi$ for $\forall \varphi.$

If a formula $\varphi$ contains no free variables (i.e., $\varphi$ is a sentence), then we omit the valuation $a$ in $\mathcal{M}, n \models^a \varphi$ and write $\mathcal{M}, n \models \varphi.$ If $\varphi$ has a single free variable $x$, then we write $\mathcal{M}, n \models [\varphi[a]]$ in place of $\mathcal{M}, n \models^a \varphi$ with $a(x) = a$.

A $QTL^1$-formula is a $QTL^1$-formula which is constructed using at most one variable. Satisfiability of $QTL^1$-formulas is known to be EXPSPACE-complete [Gabbay et al. 2003]. In the propositional temporal logic, $QTL$, only 0-ary predicates (that is, propositional variables) are allowed. The satisfiability problem for $QTL$-formulas is PSPACE-complete [Sistla and Clarke 1982].

4.2. Reduction to $QTL^1$

Given a $TBox\text{-DL-Lite}^N_{\text{bool}}$ KB $K = (\mathcal{T}, A)$, let $ob_A$ be the set of all object names occurring in $A$ and role $\text{R}$, the set of rigid and flexible role names occurring in $K$ and their inverses.

In our reduction, objects $a \in ob_A$ are mapped to constants $a$, concept names $A$ to unary predicates $A(x)$, and number restrictions $\geq q \text{R}$ to unary predicates $E_qR(x)$. Intuitively, for a role name $S$, the predicates $E_qS(x)$ and $E_qS^-(x)$ represent, at each moment of time, the sets of elements with at least $q$ distinct $S$-successors and at least $q$ distinct $S$-predecessors; in particular, $E_0S(x)$ can be thought of as the domain of $S$ and $E_1S^-(x)$ as the range of $S$. By induction on the construction of a $TBox\text{-DL-Lite}^N_{\text{bool}}$ concept $C$, we define the $QTL^1$-formula $C^*(x)$:

$$A^* = A(x), \quad \bot^* = \bot, \quad (\geq q \text{R})^* = E_qR(x), \quad (C_1 \cup C_2)^* = C_1^* \cup C_2^*, \quad (C_1 S C_2)^* = C_1^* S C_2^*, \quad (C_1 \cap C_2)^* = C_1^* \land C_2^*, \quad (\neg C)^* = \neg C^*.$$ 

It can be easily seen that the map $^*$ commutes with all the Boolean and temporal operators: e.g., $(\forall \varphi)^* = \forall \varphi^*$. For a TBox $\mathcal{T}$, we consider the following sentence, saying that the concept
Inclusions in \( \mathcal{T} \) hold globally:

\[
\mathcal{T}^\dag = \bigwedge_{C_i \subseteq C_2 \in \mathcal{T}} \Box \forall x \left( C_i^+(x) \rightarrow C_2^+(x) \right).
\]

In the translation above, we replaced binary predicates (i.e., roles) by collections of unary predicates, the \( E_q R(x) \). Clearly, we have to ensure that these predicates behave similarly to the respective number restrictions. In particular, the following three properties trivially hold in \( T_{\text{DL-Lite}}^\dag \) interpretations, for all roles \( R \) at all moments of time:

- every point with at least \( q' \) \( R \)-successors at all moments of time;
- if \( R \) is a rigid role, then every point with at least \( q \) \( R \)-successors at some moment has at least \( q \) \( R \)-successors at all moments of time;
- if the domain of a role is not empty, then its range is not empty either.

These conditions can be encoded by the following \( Q\mathcal{T}\mathcal{L}^1 \)-sentences:

\[
\bigwedge_{R \in \text{roles}_A} \bigwedge_{q,q' \in Q_T \text{ with } q' > q} \Box \forall x \left( (\geq q') R^*(x) \rightarrow (\geq q) R^*(x) \right), \tag{5}
\]

\[
\bigwedge_{R \in \text{roles}_A \text{ is rigid}} \bigwedge_{q \in Q_T} \Box \forall x \left( (\geq q) R^*(x) \rightarrow \Box (\geq q) R^*(x) \right), \tag{6}
\]

\[
\bigwedge_{R \in \text{roles}_A} \Box \left( \exists x \left( \exists R^*(x) \rightarrow \exists x (\exists \text{inv}(R))^*(x) \right) \right), \tag{7}
\]

where \( Q_T \) is the set containing 1 and all the numbers \( q \) such that \( \geq q \) \( R \) occurs in \( T \), and \( \text{inv}(R) \) is the inverse of \( R \), i.e., \( \text{inv}(S) = S^- \) and \( \text{inv}(S^-) = S \), for a role name \( S \). As we shall see later, these three properties are enough to ensure that the real binary relations for roles \( S \) in \( T_{\text{DL-Lite}}^\dag \) can be reconstructed from the collections of unary predicates \( E_q S(x) \) and \( E_q S^-(x) \) satisfying (5)–(7).

It is easy to extend the above reduction to ABox concept assertions: take \( \Box^n A(a) \) for each \( \Box^n \neg A(a) \in \mathcal{A} \), and \( \Box^n A(a) \) for each \( \Box^n \neg A(a) \in \mathcal{A} \). However, ABox role assertions need a more elaborate treatment. For every \( a \in \text{ob}_A \), if \( a \) has \( q \) \( R \)-successors in \( A \) at moment \( n \)—i.e., \( \Box^n R(a,b_1), \ldots, \Box^n R(a,b_q) \in \mathcal{A} \), for distinct \( b_1, \ldots, b_q \)—then we include \( (\Box^n \geq q \Box R(a)) \) in the translation of \( A \). When counting the number of successors, one has to remember the following property of rigid roles \( S \): if an ABox contains \( \Box^n S(a,b) \) then \( \Box^n S(a,b) \) holds for all \( n \in \mathbb{Z} \), and so \( \Box^n S(a,b) \) contributes to the number of \( S \)-successors of \( a \) and \( S^- \)-successors of \( b \) at each moment.

In what follows, we assume that \( A \) contains \( \Box^n S^-(b,a) \) whenever it contains \( \Box^n S(a,b) \). For each \( n \in \mathbb{Z} \) and each role \( R \), we define the temporal slice \( A^R_n \) of \( A \) by taking

\[
A^R_n = \begin{cases}
\{ (R(a,b) \mid \Box^n R(a,b) \in \mathcal{A} \text{ for some } m \in \mathbb{Z} \}, & \text{if } R \text{ is a rigid role}, \\
\{ (R(a,b) \mid \Box^n R(a,b) \in \mathcal{A} \}, & \text{if } R \text{ is a flexible role}.
\end{cases}
\]

The translation \( A^\dag \) of the \( T_{\text{DL-Lite}}^\dag \) ABox \( A \) is defined now by taking

\[
A^\dag = \bigwedge_{\Box^n A(a) \in \mathcal{A}} \bigwedge_{\Box^n \neg A(a) \in \mathcal{A}} \bigwedge_{\Box^n R(a,b) \in \mathcal{A}} \bigwedge_{\Box^n \neg(S(a,b) \in \mathcal{A})} \bigwedge_{\Box^n = S(b,a) \in \mathcal{A}} \bigwedge_{\Box^n \neg(S(a,b) \in \mathcal{A})}
\]

where \( q_A^R \) is the number of distinct \( R \)-successors of \( a \) in \( A \) at moment \( n \):

\[
q_A^R = \max \{ q \in Q_T \mid R(a,b_1), \ldots, R(a,b_q) \in A^R_n, \text{ for distinct } b_1, \ldots, b_q \}.
\]

We note that \( A^\dag \) can be effectively computed for any given \( K \) because we need temporal slices \( A^R_n \) only for those \( n \) that are explicitly mentioned in \( A \), i.e., those \( n \) with \( \Box^n R(a,b) \in \mathcal{A} \).

Finally, we define the \( Q\mathcal{T}\mathcal{L}^1 \)-translation \( \mathcal{K}^\dag \) of \( K = (\mathcal{T}, \mathcal{A}) \) as the conjunction of \( \mathcal{T}^\dag \), \( A^\dag \) and formulas (5)–(7). The size of \( \mathcal{T}^\dag \) and \( A^\dag \) does not exceed the size of \( \mathcal{T} \) and \( A \), respectively. The size
of (6) and (7) is linear in the size of $T$, while the size of (5) is cubic in the size of $T$ (though it can be made linear by taking account of only those $q$ that occur in $\geq q R$, for a fixed $R$, and replacing $q' > q$ in the conjunction index with a more restrictive condition $q' > q$ and there is no $q'' \in Q_T$ with $q' > q'' > q''$; for details, see [Artale et al. 2009a]).

The main technical result of this section is that $\mathcal{K}$ and $\mathcal{K}^\dagger$ are equisatisfiable; the proof (based on the unravelling construction) is given in Appendix B.

**Theorem 4.1.** A $\mathcal{T}_{\mathcal{US}}DL$-$\mathcal{L}$ite$^N_{\mathcal{box}}$ KB $\mathcal{K}$ is satisfiable iff the $\mathcal{Q}\mathcal{T}\mathcal{L}^1$-sentence $\mathcal{K}^\dagger$ is satisfiable.

Meanwhile, we proceed to the second step of our reduction.

### 4.3. Reduction to $\mathcal{P}\mathcal{T}\mathcal{L}$

Our next aim is to construct a $\mathcal{P}\mathcal{T}\mathcal{L}$-formula that is equisatisfiable with $\mathcal{K}^\dagger$. First, we observe that $\mathcal{K}^\dagger$ can be represented in the form $\mathcal{K}^{\dagger_0} \land \bigwedge_{R \in \text{role}_{\mathcal{K}}} \vartheta_R$, where

$$\mathcal{K}^{\dagger_0} = \forall \exists x \varphi(x) \land \psi \quad \text{and} \quad \vartheta_R = \forall \exists x ((\exists R)^*(x) \to \exists x (\exists \text{inv}(R))^*(x)),$$

for a quantifier-free first-order temporal formula $\varphi(x)$ with a single variable $x$ and unary predicates only and a variable-free formula $\psi$. We show now that one can replace $\vartheta_R$ by a formula without existential quantifiers. To this end we require the following lemma:

**Lemma 4.2.** For every $\mathcal{T}_{\mathcal{US}}DL$-$\mathcal{L}$ite$^N_{\mathcal{box}}$ KB $\mathcal{K}$, if there is a model $\mathcal{M}$ satisfying $\mathcal{K}^{\dagger_0}$ such that $\mathcal{M}, n_0 = (\exists R)^*[d]$, for some $n_0 \in \mathbb{Z}$ and $d \in \Delta^{\mathcal{M}}$, then there is a model $\mathcal{M}'$ extending $\mathcal{M}$ with new elements and satisfying $\mathcal{K}^{\dagger_0}$ such that, for each $n \in \mathbb{Z}$, there is $d_n \in \Delta^{\mathcal{M}'}$ with $\mathcal{M}', n = (\exists R)^*[d_n]$.

**Proof.** Consider a new model $\mathcal{M}'$ with domain $\Delta^{\mathcal{M}} \cup \{(d) \times \mathbb{Z}\}$ by setting

$$B^{\mathcal{M}'},n = B^{\mathcal{M}},n \cup \{(d, k) \mid d \in B^{\mathcal{M}},n-k, k \in \mathbb{Z}\}, \quad \text{for each } B \text{ of } \mathcal{K}^{\dagger_0} \text{ and } n \in \mathbb{Z}.$$

In other words, $\mathcal{M}'$ is the disjoint union of $\mathcal{M}$ and copies of $d$ ‘shifted’ along the timeline by $k$ steps, for each $k \in \mathbb{Z}$. It follows that, at each moment $n \in \mathbb{Z}$, the element $(d, n - n_0)$ belongs to $(\exists R)^*$, thus making $(\exists R)^*$ non-empty at all moments of time. Moreover, $\mathcal{M}', 0 = \mathcal{K}^{\dagger_0}$ because $\varphi(x)$ expresses a property of a single domain element and holds at each moment of time, $\psi$ depends only on the part of the model that corresponds to constants (and which are interpreted as in $\mathcal{M}$). \hfill \Box

Next, for each $R \in \text{role}_{\mathcal{K}}$, we take a fresh constant $d_R$ and a fresh propositional variable $p_R$ (recall that inv$(R)$ is also in role$\mathcal{K}$), and consider the following $\mathcal{Q}\mathcal{T}\mathcal{L}^1$-formula:

$$\mathcal{K}^{\dagger} = \mathcal{K}^{\dagger_0} \land \bigwedge_{R \in \text{role}_{\mathcal{K}}} \vartheta'_R,$$

where $\vartheta'_R = \forall \exists x ((\exists R)^*(x) \to \exists x (p_{\text{inv}(R)} \to (\exists R)^*(d_{R}))$ (where $p_{\text{inv}(R)}$ and $p_R$ indicate that inv$(R)$ and $R$ are non-empty whereas $d_R$ and $d_{\text{inv}(R)}$ witness that at 0).

**Lemma 4.3.** A $\mathcal{T}_{\mathcal{US}}DL$-$\mathcal{L}$ite$^N_{\mathcal{box}}$ KB $\mathcal{K}$ is satisfiable iff the $\mathcal{Q}\mathcal{T}\mathcal{L}^1$-sentence $\mathcal{K}^{\dagger}$ is satisfiable.

**Proof.** ($\Rightarrow$) If $\mathcal{K}$ is satisfiable then, by Theorem 4.1 and repeated application of Lemma 4.2, $\mathcal{K}^{\dagger_0}$ is satisfied in a model $\mathcal{M}$ such that, for each $R \in \text{role}_{\mathcal{K}}$, the predicates $(\exists R)^*$ and $(\exists \text{inv}(R))^*$ are either both empty at all moments of time or both non-empty at all moments of time. To satisfy the $\vartheta'_R$, for $R \in \text{role}_{\mathcal{K}}$, we extend $\mathcal{M}$ to $\mathcal{M}'$ as follows: if $(\exists R)^*$ and $(\exists \text{inv}(R))^*$ are non-empty, we set $p_{\text{inv}(R)}$ to be true at all $n \in \mathbb{Z}$, and take $d_R$ to be an element in $(\exists R)^*[0]\mathcal{M}$; otherwise, we set $p_{\text{inv}(R)}$ to be false and take some domain element as $d_R$. It follows that $\mathcal{M}', 0 = \mathcal{K}^{\dagger}$.

($\Leftarrow$) Conversely, suppose $\mathcal{M}, 0 = \mathcal{K}^{\dagger}$. By repeated application of Lemma 4.2, $\mathcal{K}^{\dagger_0}$ is satisfied in a model $\mathcal{M}'$ such that, for each $R \in \text{role}_{\mathcal{K}}$, the predicates $(\exists R)^*$ and $(\exists \text{inv}(R))^*$ are either both empty at all moments of time or both non-empty at all moments of time. It follows that $\mathcal{M}', 0 = \vartheta'_R$ for all $R \in \text{role}_{\mathcal{K}}$, and so $\mathcal{M}', 0 = \mathcal{K}^{\dagger}$. \hfill \Box
Finally, as $K^+$ contains no existential quantifiers, it can be regarded as a propositional temporal formula because all the universally quantified variables can be instantiated by all the constants in the formula (which only results in a polynomial blow-up). Observe also that the translation $\cdot^\dagger$ can be done in logarithmic space in the size of $K$. This is almost trivial for all conjuncts of $K^+$ apart from $(\geq q^{A(a)}_{A(n)}, R)^\ast$ in $A^1$, where the numbers can be computed using a LOGSPACE-transducer as follows: initially set $q = 0$; then enumerate all object names $b_i$ in $A$ incrementing $q$ for each $R(a, b_i) \in A^R_n$ and stop if $q = \max Q_T$ or the end of the object names list is reached; let $q^{A(a)}_{A(n)}$ be the maximum number in $Q_T$ not exceeding $q$. Note that in the case of $T_{LES\ DL-Lite^N_{bool}}$, the translation is feasible only in NLOGSPACE (rather than LOGSPACE) because we have to take account of role inclusions (and graph reachability is NLOGSPACE-complete).

### 4.4. Complexity of $T_{LES\ DL-Lite^N_{bool}}$ and its Fragments

We now use the translation $\cdot^\dagger$ to obtain the complexity results announced in Section 3.3.

**THEOREM 4.4.** The satisfiability problem for $T_{LES\ DL-Lite^N_{bool}}$ and $T_{FPX\ DL-Lite^N_{bool}}$ KBs is PSpace-complete.

**PROOF.** The upper bound follows from the reduction $\cdot^\dagger$ above and the fact that $PTL$ is PSpace-complete over $(\mathbb{Z}, <)$ [Rabinovich 2010; Reynolds 2010; Sistla and Clarke 1982]. The lower bound is an immediate consequence of the observation that $T_{FPX\ DL-Lite^N_{bool}}$ can encode formulas of the form $\theta \land \bigcirc (\varphi_i \rightarrow \bigcirc_p \psi_i)$, where $\theta$, the $\varphi_i$ and $\psi_i$ are conjunctions of propositional variables; satisfiability of such formulas is known to be PSpace-hard (see e.g., [Gabbay et al. 1994]).

In fact, using the $U$-operator, we can establish the following:

**THEOREM 4.5.** The satisfiability problem for the core fragment of $T_{LES\ DL-Lite^N_{bool}}$ KBs is PSpace-hard.

**PROOF.** The proof is by reduction of the non-halting problem for deterministic Turing machines with a polynomial tape. Let $s(n)$ be a polynomial and $M$ a deterministic Turing machine that requires $s(n)$ cells of the tape given an input of length $n$. Without loss of generality, we assume that $M$ never runs outside the first $s(n)$ cells. Let $M = (Q, \Gamma, \#, \Sigma, \delta, q_0, q_f)$, where $Q$ is a finite set of states, $\Gamma$ a tape alphabet, $\# \in \Gamma$ the blank symbol, $\Sigma \subseteq \Gamma$ a set of input symbols, $\delta: (Q \setminus \{q_f\}) \times \Gamma \rightarrow Q \times \Gamma \times \{L, R\}$ a transition function, and $q_0, q_f \in Q$ the initial and accepting states, respectively. Let $\bar{a} = a_1, \ldots, a_n$ be an input for $M$. We construct a KB that is unsatisfiable iff $M$ accepts $\bar{a}$. This will prove PSpace-hardness. The KB uses a single object name $d$ and the following concepts, for $a \in \Gamma$, $q \in Q$ and $1 \leq i \leq s(n)$, representing configurations of $M$:

- $H_{iq}$, which contains $d$ if the head points to cell $i$ and the current state is $q$;
- $S_{ta}$, which contains $d$ if tape cell $i$ contains symbol $a$ in the current configuration;
- $D_i$, which contains $d$ if the head pointed to cell $i$ in the previous configuration.

Let $\mathcal{T}_M$ contain the following concept inclusions, for $a, a' \in \Gamma$, $q, q' \in Q$, and $1 \leq i, j \leq s(n)$:

\[
\begin{align*}
H_{iq} &\subseteq \bigcup_{j \neq i} H_{(i+1)q'}, \\
H_{iq} &\subseteq \bigcup_{j < i} S_{ia'}, \\
H_{iq} &\subseteq \bigcup_{j > i} S_{ia'}, \\
H_{iq} &\subseteq \bigcup_{j \neq i} D_i, \\
D_i \cap D_j &\subseteq \bot, \\
S_{ta} &\subseteq S_{ia} \cup D_i, \\
H_{iq} &\subseteq \bot,
\end{align*}
\]

and let $A_d$ consist of the following ABox assertions:

\[
\begin{align*}
H_{iq_0}(d), & \quad S_{ia}(d), \quad \text{for } 1 \leq i \leq n, \\
S_{ia}(d), & \quad \text{for } n < i \leq s(n).
\end{align*}
\]
Note that the concept inclusions in $T_M$ are of the form $B_1 \sqcap B_2 \sqsubseteq \bot$ or $B_1 \sqsubseteq B_2 \cup B_3$, where each $B_i$ is either a concept name or $\bot$, and that $U$, in essence, encodes the ‘next-time’ operator. The proof that $(T_M, A)$ is unsatisfiable iff $M$ accepts $\bar{a}$ is given in Appendix C. □

On the other hand, if we do not have the $U/S$ or $\bowtie_\phi/\bowtie_\psi$ operators in our languages, then the complexity drops to NP, which matches the complexity of the $\bowtie_\psi$-fragment of propositional temporal logic [Ono and Nakamura 1980]:

**Theorem 4.6.** Satisfiability of $T_{FP,DL-Lite}^N_{\text{bool}}$ and $T_U,DL-Lite^N_{\text{bool}}$ KBs is NP-complete.

**Proof.** The lower bound is immediate from the complexity of $DL-Lite^N_{\text{bool}}$. The upper bound for $T_{FP,DL-Lite}^N_{\text{bool}}$ can be shown using a slight modification of the reduction $\dag$ and the result of Ono and Nakamura [1980] mentioned above. We need to modify $\dag$ in such a way that the target language does not contain the $\bowtie_n$ operators of the ABox. We take a fresh predicate $H_C^n(x)$ for each ground atom $\bowtie_n C(a)$ occurring in $A^1$ and use the following formulas instead of $\bowtie_n C(a)$ in $A^1$:

\[
\begin{align*}
(\bowtie^n P(a) \land \neg\bowtie^{n+1} P(a)) \land \bowtie \left( H_C^n(a) \rightarrow C(a) \right), & \quad \text{if } n \geq 0, \\
(\bowtie^n P(a) \land \neg\bowtie^{n+1} P(a)) \land \bowtie \left( H_C^n(a) \rightarrow C(a) \right), & \quad \text{if } n < 0,
\end{align*}
\]

where $\bowtie^n$ and $\bowtie^n$ denote $n$ applications of $\bowtie$ and $\bowtie$, respectively. Note that $H_C^n(a)$ holds at $m$ iff $m = n$. Thus, we use these predicates to ‘mark’ a small number of moments of time in models.

The NP upper bound trivially holds for $T_U,DL-Lite^N_{\text{bool}}$, a sublanguage of $T_{FP,DL-Lite}^N_{\text{bool}}$. □

Our next theorem also uses the reduction $\dag$ and follows from the complexity results for the fragments $PTL_{\text{krom}}(\bowtie, \bowtie_\phi/\bowtie_\psi, \bowtie_\psi/\bowtie_\phi)$ and $PTL_{\text{core}}(\bowtie, \bowtie_\phi/\bowtie_\psi)$ of $PTL$, obtained by restricting the form of clauses in the Separated Normal Form (SNF) [Fisher 1991] and proved in Section 5.

**Theorem 4.7.** Satisfiability of $T_{FP,DL-Lite}^N_{\text{krom}}, T_{FP,DL-Lite}^N_{\text{core}}$, and $T_{FPX,DL-Lite}^N_{\text{core}}$ KBs is NP-complete.

**Proof.** The NP upper bound follows from the fact that the $\dag$ translation of a KB in any of the three languages is a $PTL_{\text{krom}}(\bowtie, \bowtie_\phi/\bowtie_\psi, \bowtie_\psi/\bowtie_\phi)$-formula. By Theorem 5.4, satisfiability of such formulas is in NP. The matching lower bound for $T_{FP,DL-Lite}^N_{\text{krom}}$ (and $T_{FPX,DL-Lite}^N_{\text{krom}}$) follows from the proof of NP-hardness of $PTL_{\text{core}}(\bowtie, \bowtie_\phi/\bowtie_\psi)$, which will be presented in Theorem 5.6: one can take concept names instead of propositional variables and encode, in an obvious way, the formulas of the proof of Theorem 5.6 in a KB; similarly, the lower bound for $T_{FPX,DL-Lite}^N_{\text{core}}$ follows from NP-hardness of $PTL_{\text{core}}(\bowtie, \bowtie_\phi/\bowtie_\psi)$; see Theorem 5.6. □

**Theorem 4.8.** Satisfiability of $T_{FP,DL-Lite}^N_{\text{core}}$ KBs is in PTIME.

**Proof.** The result follows from the observation that the $\dag$ translation of a $T_{FP,DL-Lite}^N_{\text{core}}$ KB is of the form $\phi' \land \phi''$, where $\phi'$ is a $PTL_{\text{core}}(\bowtie, \bowtie_\phi/\bowtie_\psi)$-formula representing the TBox and $\phi''$ is a conjunction of formulas of the form $\bowtie^n p$, for propositional variables $p$. A modification of the proof of Theorem 5.5 (explained in Remark 5.6) shows that satisfiability of such formulas is in PTIME.

We note in passing that the matching lower bound for $PTL_{\text{core}}(\bowtie, \bowtie_\phi/\bowtie_\psi)$, to be proved in Theorem 5.6, does not imply PTIME-hardness of $T_{FP,DL-Lite}^N_{\text{core}}$ as the formulas in the proof require an implication to hold at the initial moment of time, which is not expressible in $T_{FP,DL-Lite}^N_{\text{core}}$. □

Finally, we show that the Krom and core fragments of $T_U,DL-Lite^N_{\text{bool}}$ can be simulated by 2CNFs (see, e.g., [Börger et al. 1997]), whose satisfiability is NLSPACE-complete.

**Theorem 4.9.** The satisfiability problem for $T_U,DL-Lite^N_{\text{core}}$ and $T_U,DL-Lite^N_{\text{krom}}$ KBs is NLSPACE-complete.

**Proof.** The lower bound is trivial from NLSPACE-hardness of $DL-Lite^N_{\text{core}}$. We show the matching upper bound. Given a $T_U,DL-Lite^N_{\text{krom}}$ KB $\mathcal{K} = (T, A)$, we consider the $QTL^1$-formula $\mathcal{K}^\dag$, which, by Lemma 4.3, is satisfiable iff $\mathcal{K}$ is satisfiable. Now, we transform $\mathcal{K}^\dag$ into a two-sorted
first-order formula $K^{\updownarrow 2}$ by representing the time dimension explicitly as a predicate argument. Recall that $K^{\updownarrow}$ is built from the propositional variables $p_R$, for $R \in \text{role}_K$, and unary predicates $B^*$, for concepts $B$ of the form $A$ and $\geq q R$. Without loss of generality, we assume that there is at most one $\boxdot$ in front of each $B^*$ in $K^{\updownarrow}$. We replace each $B^*(x)$ in $K^{\updownarrow}$ that is not prefixed by $\boxdot$ with the binary predicate $B^*(x,t)$, and each $\square B^*(x)$ with a fresh unary predicate $U_B(x)$; the outermost $\boxdot$ is replaced by $\forall t$. To preserve the semantics of the $\boxdot B^*$, we also append to the resulting formula the conjuncts $\forall x \left( U_B(x) \leftrightarrow \forall t B^*(x,t) \right)$, which are equivalent to

$$\forall t \forall x \left( U_B(x) \rightarrow B^*(x,t) \right) \land \forall x \exists t \left( B^*(x,t) \rightarrow U_B(x) \right).$$

The propositional variables $p_R$ of $K^{\updownarrow}$ remain propositional variables in $K^{\updownarrow 2}$, and the second conjunct of $K^{\updownarrow}$ is replaced by the following formula:

$$(p_R \rightarrow (\exists \text{inv}(R))^*(d_{\text{inv}(R)},0)) \land \forall t \forall x \left( (\exists R)^*(x,t) \rightarrow p_R \right)$$

with constant 0. Finally, the ground atoms $\bigcirc^n B^*(a)$ in $A^\downarrow$ are replaced by $B^*(a,n)$ with constants $n$. Thus, $K^{\updownarrow 2}$ is a conjunction of (at most) binary clauses without quantifiers or with prefixes of the form $\forall t \forall x$ and $\forall x \exists t$. Since the first argument of the predicates, $x$, is always universally quantified, $K^{\updownarrow 2}$ is equisatisfiable with the conjunction $K^{\updownarrow 3}$ of the formulas obtained by replacing $x$ in $K^{\updownarrow 2}$ with the constants in the set $\text{ob}_A \cup \{d_R \mid R \in \text{role}_K\}$. But then $K^{\updownarrow 3}$ is equivalent to a first-order Krom formula in prefix form with the quantifier prefix $\exists^3 \forall$, satisfiability of which can be checked in $\text{NLOGSPACE}$ (see e.g., [Börger et al. 1997, Theorem 8.3.6]).

5. CLAUSAL FRAGMENTS OF PROPOSITIONAL TEMPORAL LOGIC

Our aim in this section is to introduce and investigate a number of new fragments of the propositional temporal logic $\mathcal{PTL}$. One reason for this is to obtain the complexity results required for the proof of Theorems 4.7 and 4.8. We believe, however, that these fragments are of sufficient interest on their own, independently of temporal conceptual modelling and reasoning.

Sistla and Clarke [1982] showed that full $\mathcal{PTL}$ is PSPACE-complete; see also [Halpern and Reif 1981; Lichtenstein et al. 1985; Rabinovich 2010; Reynolds 2010]. Ono and Nakamura [1980] proved that for formulas with only $\square$ and $\diamond$ the satisfiability problem becomes NP-complete. Since then a number of fragments of $\mathcal{PTL}$ with lower computational complexity have been identified and studied. Chen and Lin [1993] observed that the complexity of $\mathcal{PTL}$ does not change even if we restrict attention to temporal Horn formulas. Demri and Schnoebelen [2002] determined the complexity of fragments that depend on three parameters: the available temporal operators, the number of nested temporal operators, and the number of propositional variables in formulas. Markey [2004] analysed fragments defined by the allowed set of temporal operators, their nesting and the use of negation. Dixon et al. [2007] introduced a XOR fragment of $\mathcal{PTL}$ and showed its tractability. Bauland et al. [2009] systematically investigated the complexity of fragments given by both temporal operators and Boolean connectives (using Post’s lattice of sets of Boolean functions).

In this section, we classify temporal formulas according to their clausal normal form. We remind the reader that any $\mathcal{PTL}$-formula can be transformed to an equisatisfiable formula in Separated Normal Form (SNF) [Fisher 1991]. A formula in SNF is a conjunction of initial clauses (that define ‘initial conditions’ at moment 0), step clauses (that define ‘transitions’ between consecutive states), and eventuality clauses (ensuring that certain states are eventually reached). More precisely, for the time flow $\mathbb{Z}$, a formula in SNF is a conjunction of clauses of the form

$$L_1 \lor \cdots \lor L_k,$$

$$\square((L_1 \land \cdots \land L_k) \rightarrow \circ(L_1' \lor \cdots \lor L_m')),$$

$$\boxdot((L_1 \land \cdots \land L_k) \rightarrow \diamond p L),$$

$$\boxdot((L_1 \land \cdots \land L_k) \rightarrow \diamond p L),$$
where $L_1, \ldots, L_k, L'_1, \ldots, L'_m$ are literals—i.e., propositional variables or their negations—and $\neg$ is a short-hand for $\neg p$ (we will use this abbreviation throughout this section). By definition, we assume the empty disjunction to be $\bot$ and the empty conjunction to be $\top$. For example, the second clause with $m = 0$ reads $\neg(L_1 \land \cdots \land L_k \rightarrow \bot)$.

The transformation to SNF is achieved by fixed-point unfolding and renaming [Fisher et al. 2001; Plaisted 1986]. Recall that an occurrence of a subformula is said to be positive if it is in the scope of an even number of negations. Now, as $p \cup q$ is equivalent to $\neg q \lor (\neg p \land \neg (p \cup q))$, every positive occurrence of $p \cup q$ in a given formula $\varphi$ can be replaced by a fresh propositional variable $r$, with the following three clauses added as conjuncts to $\varphi$:

$$\neg(r \rightarrow \neg q \lor p), \quad \neg(r \rightarrow \neg q \lor r) \quad \text{and} \quad \neg(r \rightarrow q \lor r).$$

The result is equisatisfiable with $\varphi$ but does not contain positive occurrences of $p \cup q$. Similarly, we can get rid of other temporal operators and transform the formula to SNF [Fisher et al. 2001].

We now define four types of fragments of PTL, which are called $\PTL_{\text{core}}(X)$, $\PTL_{\text{krom}}(X)$, $\PTL_{\text{horn}}(X)$ and $\PTL_{\text{bool}}(X)$, where $X$ has one of the following four forms: $\neg$, $\neg p / \neg p$, $\neg p / \neg p$, or $\neg$, $\neg p / \neg p$, or $\neg$, $\neg p / \neg p$ or $\neg$. $\PTL_{\text{core}}(X)$-formulas, $\varphi$, are constructed using the grammar:

$$
\varphi ::= \psi \mid \neg \psi \mid \varphi_1 \land \varphi_2, \\
\psi ::= \lambda_1 \rightarrow \lambda_2 \mid \lambda_1 \land \lambda_2 \rightarrow \bot, \\
\lambda ::= \bot \mid p \mid \star \lambda, \quad \text{where} \star \text{is one of the operators in} X.
$$

Definitions of the remaining three fragments differ only in the shape of $\psi$. In $\PTL_{\text{krom}}(X)$-formulas, $\psi$ is a binary clause:

$$\psi ::= \lambda_1 \rightarrow \lambda_2 \mid \lambda_1 \land \lambda_2 \rightarrow \bot \mid \lambda_1 \lor \lambda_2. \quad \text{(krom)}$$

In $\PTL_{\text{horn}}(X)$-formulas, $\psi$ is a Horn clause:

$$\psi ::= \lambda_1 \land \cdots \land \lambda_n \rightarrow \lambda, \quad \text{(horn)}$$

while in $\PTL_{\text{bool}}(X)$-formulas, $\psi$ is an arbitrary clause:

$$\psi ::= \lambda_1 \land \cdots \land \lambda_n \rightarrow \lambda_1' \lor \cdots \lor \lambda_n'. \quad \text{(bool)}$$

Note that, if $X$ contains $\square$-operators then the corresponding $\diamond$-operators can be defined in the fragments $\PTL_{\text{krom}}(X)$ and $\PTL_{\text{bool}}(X)$.

Table III shows how the complexity of the satisfiability problem for PTL-formulas depends on the type of the underlying propositional clauses and the available temporal operators. The PSPACE upper bound is well-known; the matching lower bound can be obtained by a standard encoding of deterministic Turing machines with polynomial tape (cf. Theorem 4.4). The NP upper bound for $\PTL_{\text{bool}}(\neg, \neg p / \neg p)$ follows from [Ono and Nakamura 1980]. The NLOGSPACE lower bound is trivial and the matching upper bound follows from the complexity of the Krom formulas with the quantifier prefix of the form $\exists^* \forall$ [Börger et al. 1997] (a similar argument is used in Theorem 4.9). In the remainder of this section, we prove all other results in this table. It is worth noting how the addition of $\neg$ or $\neg$ increases the complexity of $\PTL_{\text{horn}}(\neg, \neg p / \neg p)$ and $\PTL_{\text{core}}(\neg, \neg p / \neg p)$.

THEOREM 5.1. The satisfiability problem for $\PTL_{\text{krom}}(\neg, \neg p / \neg p, \neg p / \neg p)$-formulas is in NP.
PROOF. We proceed as follows. First, in Lemma 5.2, we give a satisfiability criterion for $\mathcal{PTL}$-formulas in terms of types—sets of propositions that occur in the given formula—and distances between them in temporal models. The number of types required is polynomial in the size of the given formula; the distances, however, are exponential, and although they can be represented in binary (in polynomial space), in general there is no polynomial algorithm that checks whether two adjacent types can be placed at a given distance (unless $\text{PTIME} = \text{PSPACE}$). In the remainder of the proof, we show that, for formulas with binary clauses, this condition can be verified by constructing a polynomial number of polynomial arithmetic progressions (using unary automata). This results in a non-deterministic polynomial-time algorithm; guess types and distances between them, and then verify (in polynomial time) whether the types can be placed at the required distances.

Let $\varphi'$ be a $\mathcal{PTL}_{\text{com}}(\Box, \square_p, \lambda_p, \neg)$-formula. By introducing fresh propositional variables if required, we can transform $\varphi'$ (in polynomial time) to a formula

$$\varphi = \Psi \land \Box \Phi,$$

where $\Psi$ contains no temporal operators and $\Phi$ contains no nested occurrences of temporal operators.

Indeed, if $\varphi'$ contains a conjunct $\psi$ with a temporal $\lambda$, then we take a fresh propositional variable $\lambda'$, replace $\lambda$ in $\psi$ with $\lambda'$, and add to $\varphi'$ a new conjunct $\Box (\lambda \leftrightarrow \lambda')$. In a similar way we get rid of nested occurrences of temporal operators in $\Phi$.

We will not distinguish between a set of formulas and the conjunction of its elements, and write $\Box \Phi$ for $\bigwedge_{\forall \lambda \in \Phi} \Box \lambda$. As $\Box (\lambda \lor O_{\psi} \lambda')$ is equivalent to $\Box (O_{\psi} \lambda \lor \lambda')$, we can assume that $\Phi$ does not contain $O_{\psi}$ (remember that we agreed to denote $O_{\psi}$ by $\Box$). We regard $\Box$ inside $\Phi$ as defined by $\Box \lambda = \Box_p \Box_p \lambda$. Thus, we assume that $\Phi$ contains only $\Box_p, \Box_p \Box_p$ and $\Box_p \Box_p \Box_p$ (which are not nested).

We first characterise the structure of models for formulas of the form (14) (with $\Psi$ and $\Phi$ satisfying those conditions). It should be noted that this structure only depends on $\varphi$ being of that form (cf. [Gabbay et al. 1994; Gabbay et al. 2003] and references therein) and does not depend on whether or not $\Psi$ and $\Phi$ are sets of binary clauses. To this end, for each $\Box_p L$ in $\varphi$, we take a fresh propositional variable, denoted $\Box_p L$ and called the surrogate of $\Box_p L$; likewise, for each $\Box_p L$ we take its surrogate $\Box_p L$. Let $\Phi$ be the result of replacing $\Box$-subformulas in $\Phi$ by their surrogates. It should be clear that $\varphi$ is equisatisfiable with

$$\varphi = \Psi \land \Box \Phi \land \bigwedge_{\Box_p L \text{ occurs in } \Phi} (\Box_p L \leftrightarrow \Box_p L) \land \bigwedge_{\Box_p L \text{ occurs in } \Phi} (\Box_p L \leftrightarrow \Box_p L).$$

By a type for $\varphi$ we mean any set of literals that contains either $p$ or $\neg p$, for each variable $p$ in $\varphi$ (including the surrogates $\Box_p L$ and $\Box_p L$).

**Lemma 5.2.** The formula $\varphi$ is satisfiable iff there exist $k + 5$ integers

$$m_0 < m_1 < \ldots < m_{k+4}$$

(where $k$ does not exceed the number of $\Box_p L$ and $\Box_p L$) and a sequence $\Psi_0, \Psi_1, \ldots, \Psi_{k+4}$ of types for $\varphi$ satisfying the following conditions (see Fig. 3):

- (B_0) $m_{i+1} - m_i < 2|\varphi|$, for $0 \leq i < k + 4$;
- (B_1) there exists $\ell_0$ such that $0 \leq \ell_0 \leq k + 4$ and $\Psi \land \Psi_{\ell_0}$ is consistent;
- (B_2) for each $i$, $0 \leq i < k + 4$, and each $\Box_p L$ in $\Phi$, if $\Box_p L \in \Psi_i$ then $L, \Box_p L \in \Psi_{i+1}$, and if $\Box_p L \in \Psi_{i+1} \setminus \Psi_i$ then $L \notin \Psi_{i+1}$;
- (B_3) there exists $\ell_F < k + 4$ such that $\Psi_{\ell_F} = \Psi_{k+4}$ and, for each $\Box_p L$ in $\Phi$, if $\Box_p L \notin \Psi_{\ell_F}$ then $L \notin \Psi_j$, for some $j \geq \ell_F$;
- (B_4) for each $i$, $0 < i \leq k + 4$, and each $\Box_p L$ in $\Phi$, if $\Box_p L \in \Psi_i$ then $L, \Box_p L \in \Psi_{i-1}$, and if $\Box_p L \in \Psi_{i-1} \setminus \Psi_i$ then $L \notin \Psi_{i-1}$.
Fig. 3. Conditions $\text{(B}_2\text{)}, \text{(B}_4\text{)}$ and $\text{(B}_6\text{)}$ in Lemma 5.2.

$\text{(B}_5\text{)}$ there exists $\ell_P > 0$ such that $\Psi_{\ell_P} = \Psi_0$ and, for each $\Box_P L$ in $\Phi$, if $\Box_P L \not\in \Psi_{\ell_P}$, then $L \not\in \Psi_j$, for some $j \leq \ell_P$;

$\text{(B}_6\text{)}$ for all $i$, $0 \leq i < k + 4$, the following formula is consistent:

$$\Psi_i \lor \bigwedge_{j=1}^{m_{i+4} - m_i - 1} \bigcirc^j \Theta_i \lor \bigcirc^{m_{i+1} - m_i} \Psi_{i+1} \lor \overline{\Phi},$$

(15)

where $\bigcirc^j \Psi$ is the result of attaching $j$ operators $\bigcirc$ to each literal in $\Psi$ and

$$\Theta_i = \{ L, \overline{\Box_P L} \mid \Box_P L \in \Psi_i \} \cup \{ \overline{\Box_P L} \mid \Box_P L \not\in \Psi_i \} \cup \{ L, \overline{\Box_P L} \mid \Box_P L \in \Psi_{i+1} \} \cup \{ \overline{\Box_P L} \mid \Box_P L \not\in \Psi_{i+1} \}.$$

Proof. ($\Rightarrow$) Let $\mathfrak{M}, 0 \models \not\Phi$. Denote by $\Psi(m)$ the type for $\Phi$ containing all literals that hold at $m$ in $\mathfrak{M}$. As the number of types is finite, there is $m_P > 0$ such that each type in the sequence $\Psi(m_P), \Psi(m_P + 1), \ldots$ appears infinitely often; similarly, there is $m_F < 0$ such that each type in the sequence $\Psi(m_F), \Psi(m_F - 1), \ldots$ appears infinitely often. Then, for each subformula $\Box_P L$ of $\Phi$, we have one of the three options: (1) $L$ is always true in $\mathfrak{M}$, in which case we set $m_{\Box_P L} = 0$; (2) there is $m_{\Box_P L}$ such that $\mathfrak{M}, m_{\Box_P L} \models \neg L \land \Box_P L$, in which case $m_P < m_{\Box_P L} < m_F$; or (3) $\Box_P L$ is always false in $\mathfrak{M}$, in which case $L$ is false infinitely often after $m_P$, and so there is $m_{\Box_P L} \geq m_F$ such that $\mathfrak{M}, m_{\Box_P L} \models \neg L$. Symmetrically, for each subformula $\Box_P L$ of $\Phi$, (1) $L$ is always true in $\mathfrak{M}$, in which case we set $m_{\Box_P L} = 0$; or (2) there is an $m_{\Box_P L}$ such that $m_P < m_{\Box_P L} < m_F$ and $\mathfrak{M}, m_{\Box_P L} \models \neg L \land \Box_P L$; or (3) $\Box_P L$ is always false in $\mathfrak{M}$, in which case there is $m_{\Box_P L} \leq m_F$ such that $\mathfrak{M}, m_{\Box_P L} \models \neg L$. Let $m_1 < m_2 < \cdots < m_{k+3}$ be an enumeration of the set

$$\{0, m_P, m_F\} \cup \{m_{\Box_P L} \mid \Box_P L \text{ occurs in } \Phi\} \cup \{m_{\Box_P L} \mid \Box_P L \text{ occurs in } \Phi\}.$$

Let $m_{k+4} > m_{k+3}$ be such that $\Psi(m_{k+4}) = \Psi(m_F)$ and let $m_0 < m_1$ be such that $\Psi(m_0) = \Psi(m_F)$. We then set $\Psi_i = \Psi(m_i)$, for $0 \leq i \leq k + 4$. Let $\ell_0, \ell_P$ and $\ell_F$ be such that $m_{\ell_0} = 0$, $m_{\ell_P} = m_P$ and $m_{\ell_F} = m_F$. It should be clear that $\text{(B}_1\text{)}$–$\text{(B}_6\text{)}$ hold. Finally, given a model of $\not\Phi$ with two moments $m$ and $n$ such that the types at $m$ and $n$ coincide, we can construct a new model for $\not\Phi$ by ‘removing’ the states $i$ with $m \leq i < n$. Since the number of distinct types is bounded by $2^{|\Phi|}$, by repeated applications of this construction we can further ensure $\text{(B}_0\text{)}$.

($\Leftarrow$) We construct a model $\mathfrak{M}$ of $\not\Phi$ by taking finite cuts of the models $\mathfrak{M}_i$ of the formulas in $\text{(B}_6\text{)}$; between the moments $m_0$ and $m_{k+4}$, the model $\mathfrak{M}$ coincides with the models $\mathfrak{M}_0, \ldots, \mathfrak{M}_{k+3}$ so that at the moment $m_i$ in $\mathfrak{M}$ we align the moment $0$ of $\mathfrak{M}_i$, and at the moment $m_{i+1}$ we align the moment $m_{i+1} - m_i$ of $\mathfrak{M}_i$, which coincides with the moment $0$ of $\mathfrak{M}_{i+1}$ because both are defined by $\Psi_{i+1}$; before the moment $m_0$, the model $\mathfrak{M}$ repeats infinitely often its own fragment between $m_0$ and $m_{\ell_P}$, and after $m_{k+4}$ it repeats infinitely often its fragment between $m_{\ell_P}$ and $m_{k+4}$ (both fragments contain more than one state). It is readily seen that $\mathfrak{M}, m_{\ell_0} \models \not\Phi$. □
By Lemma 5.2, if we provide a polynomial-time algorithm for verifying (B₀), we can check satisfiability of \( \varphi \) in \( \mathcal{NP} \). Indeed, it suffices to guess \( k + 5 \) types for \( \varphi \) and \( k + 4 \) natural numbers \( n_i = m_{i+1} - m_i \), for \( 0 \leq i < k + 4 \), whose binary representation, by (B₀), is polynomial in \( |\varphi| \). It is easy to see that (B₁)–(B₃) can be checked in polynomial time. We show now that (B₄) can also be verified in polynomial time for \( \mathcal{P}T\mathcal{L}_{\text{atom}}(\mathcal{B}, \mathcal{O}_{\mathcal{P}} / \mathcal{O}_{\mathcal{P}}, \mathcal{D}_{\mathcal{P}} / \mathcal{D}_{\mathcal{P}}) \)-formulas.

Our problem is as follows: given a number \( n \geq 0 \) (in binary), types \( \Psi \) and \( \Psi' \), a set \( \Theta \) of literals and a set \( \Phi \) of binary clauses of the form \( D_1 \lor D_2 \), where the \( D_i \) are temporal literals \( p, \neg p, \lor p \) or \( \neg \lor p \), decide whether there is a model satisfying

\[
\Psi \land \bigwedge_{k=1}^{n-1} \bigcirc^k \Theta \land \bigcirc^n \Psi' \land \boxdot \Phi. \tag{16}
\]

In what follows, we write \( \psi_1 \models \psi_2 \) as a shorthand for ‘in every \( \mathcal{M} \), if \( \mathcal{M}, 0 \models \psi_1 \) then \( \mathcal{M}, 0 \models \psi_2 \).’

For \( 0 \leq k \leq n \), we set:

\[
F^k_\Phi(\Psi) = \{ L' \mid L \land \boxdot \Phi \models \bigcirc^k L', \text{ for } L \in \Psi \},
\]

\[
P^k_\Phi(\Psi') = \{ L \mid \bigcirc^k L' \land \boxdot \Phi \models L, \text{ for } L' \in \Psi' \}.
\]

**Lemma 5.3.** Formula (16) is satisfiable if and only if the following conditions hold:

\[(L_1)\ F^0_\Phi(\Psi) \subseteq \Psi, \ F^k_\Phi(\Psi) \subseteq \Psi' \text{ and } P^k_\Phi(\Psi') \subseteq \Psi; \]

\[(L_2)\ \neg L \notin F^k_\Phi(\Psi) \text{ and } \neg L \notin P^{n-k}_\Phi(\Psi'), \text{ for all } L \in \Theta \text{ and } 0 < k < n.\]

**Proof.** It should be clear that if (16) is satisfiable then the above conditions hold. For the converse direction, observe that if \( L' \in F^k_\Phi(\Psi) \) then, since \( \Phi \) is a set of binary clauses, there is a sequence of \( \bigcirc \)-prefixed literals \( \bigcirc^m L_0 \leadsto \bigcirc^1 L_1 \leadsto \cdots \leadsto \bigcirc L_m \) such that \( k_0 = 0 \), \( L_0 \in \Psi \), \( k_m = k \), \( L_m = L' \), each \( k_i \) is between 0 and \( n \) and the \( \leadsto \) relation is defined by taking \( \bigcirc^1 L_1 \leadsto \bigcirc^1 L_{i+1} \) just in one of the three cases: \( k_{i+1} = k_i \) and \( L_i \rightarrow L_{i+1} \in \Phi \) or \( k_{i+1} = k_i + 1 \) and \( L_i \rightarrow L_{i+1} \in \Phi \) or \( k_{i+1} = k_i - 1 \) and \( L_i \rightarrow L_{i+1} \in \Phi \) (we assume that, for example, \( \neg q \rightarrow \neg p \in \Phi \) whenever \( \Phi \) contains \( p \rightarrow q \)). So, suppose conditions (L₁)–(L₂) hold. We construct an interpretation satisfying (16). By (L₁), both \( \Psi \land \boxdot \Phi \) and \( \bigcirc^n \Psi' \land \boxdot \Phi \) are consistent. So, let \( \mathcal{M}_\Psi \) and \( \mathcal{M}_\Psi' \) be such that \( \mathcal{M}_\Psi, 0 \models \Psi \land \boxdot \Phi \) and \( \mathcal{M}_\Psi', n \models \Psi' \land \boxdot \Phi \), respectively. Let \( \mathcal{M} \) be an interpretation that coincides with \( \mathcal{M}_\Phi \) for all moments \( k \leq 0 \) and with \( \mathcal{M}_\Psi \) for all \( k \geq n \); for the remaining \( k \), \( 0 < k < n \), it is defined as follows. First, for each \( p \in \Theta \), we make \( p \) true at \( k \) and, for each \( \neg p \in \Theta \), we make \( p \) false at \( k \); such an assignment exists due to (L₂). Second, we extend the assignment by making \( L \) true at \( k \) if \( L \in F^k_\Phi(\Psi) \cup P^{n-k}_\Phi(\Psi') \). Observe that we have \( \{ p, \neg p \} \notin F^k_\Phi(\Psi) \cup P^{n-k}_\Phi(\Psi') \); for otherwise \( L \land \Phi \models \bigcirc^k p \) and \( \bigcirc^{n-k} L' \land \Phi \models \neg p \), for some \( L \in \Psi \) and \( L' \in \Psi' \), whence \( L \land \Phi \models \bigcirc^n \neg L' \), contrary to (L₁). Also, by (L₂), any assignment extension at this stage does not contradict the choices made due to \( \Theta \). Finally, all propositional variables not covered in the previous two cases get their values from \( \mathcal{M}_\Psi \) (or \( \mathcal{M}_\Psi' \)). We note that the last choice does not depend on the assignment that is fixed by taking account of the consequences of \( \boxdot \Phi \) with \( \Psi \) and \( \Psi' \) and \( \Theta \) (because if the value of a variable depended on those sets of literals, the respective literal would be among the logical consequences and would have been fixed before). ☐

Thus, it suffices to show that conditions (L₁)–(L₂) can be checked in polynomial time. First, we claim that there is a polynomial-time algorithm which, given a set \( \Phi \) of binary clauses of the form \( D_1 \lor D_2 \), constructs a set \( \Phi^* \) of binary clauses that is ‘sound and complete’ in the following sense:

\[\text{(S₁)} \quad \boxdot \Phi^* \models \boxdot \Phi; \]

\[\text{(S₂)} \quad \text{if } \Phi \models L \rightarrow \bigcirc^k L_k \text{ then either } k = 0 \text{ and } L \rightarrow L_0 \in \Phi^*, \text{ or } k \geq 1 \text{ and there are } L_0, L_1, \ldots, L_{k-1} \text{ with } L = L_0 \text{ and } L_i \rightarrow \bigcirc L_{i+1} \in \Phi^*, \text{ for } 0 \leq i < k.\]

Intuitively, the set \( \Phi^* \) makes explicit the consequences of \( \boxdot \Phi \) and can be constructed in time \( (2^{|\Phi|})^2 \) (the number of temporal literals in \( \Phi^* \) is bounded by the doubled length \(|\Phi|\) of \( \Phi \) as each of its
literals can only be prefixed by $\lor$). Indeed, we start from $\Phi$ and, at each step, add $D_1 \lor D_2$ to $\Phi$ if it contains both $D_1 \lor D$ and $\neg D \lor D_2$; we also add $L_1 \lor L_2$ if $\Phi$ contains $\neg L_1 \lor \neg L_2$ (and vice versa). This procedure is sound since we only add consequences of $\Box \Phi$; completeness follows from the completeness proof for temporal resolution [Fisher et al. 2001, Section 6.3].

Our next step is to encode $\Phi^*$ by means of unary automata. For literals $L$ and $L'$, consider a nondeterministic finite automaton $A_{L,L'}$ over $\{0\}$, whose states are the literals of $\Phi^*$, $L$ is the initial and $L'$ is the only accepting state, and the transition relation is $\{(L_1, L_2) \mid L_1 \rightarrow \neg \circ L_2 \in \Phi^*)\}$. By $(S_1)$ and $(S_2)$, for all $k > 0$, we have

$A_{L,L'}$ accepts $0^k$ iff $\Box \Phi \models \Box (L \rightarrow \circ^k L')$.

Then both $F_0^k(\Psi)$ and $P_0^k(\Psi')$, for $k > 0$, can be defined in terms of the language of $A_{L,L'}$:

$F_0^k(\Psi) = \{L' \mid A_{L,L'}$ accepts $0^k$, for $L \in \Psi\}$,

$P_0^k(\Psi') = \{L \mid A_{L,L',\neg}$ accepts $0^k$, for $L' \in \Psi'\}$

(recall that $\circ^k L' \rightarrow L$ is equivalent to $\neg L \rightarrow \circ^k L'$). Note that the numbers $n$ and $k$ in conditions $(L_1)$ and $(L_2)$ are in general exponential in the length of $\Phi$ and, therefore, the automata $A_{L,L'}$ do not immediately provide a polynomial-time procedure for checking these conditions: although it can be shown that if $(L_2)$ does not hold then it fails for a polynomial number $k$, this is not the case for $(L_1)$, which requires the accepting state to be reached in a fixed (exponential) number of transitions.

Instead, we use the Chrobak normal form [Chrobak 1986] to decompose the automata into a polynomial number of polynomial-sized arithmetic progressions (which can have an exponential common period; cf. the proof of Theorem 5.4).

It is known that every $N$-state unary automaton $A$ can be converted (in polynomial time) into an equivalent automaton in Chrobak normal form (e.g., by using Martínez’s algorithm [To 2009]), which has $O(N^2)$ states and gives rise to $M$ arithmetic progressions $a_1 + b_1 \mathbb{N}, \ldots, a_M + b_M \mathbb{N}$, where $a_i + b_i \mathbb{N} = \{a_i + b_i m \mid m \in \mathbb{N}\}$, such that

- $M \leq O(N^2)$ and $0 \leq a_i, b_i \leq N$, for $1 \leq i \leq M$;
- $A$ accepts $0^k$ iff $k \in a_i + b_i \mathbb{N}$, for some $1 \leq i \leq M$.

By construction, the number of arithmetic progressions is quadratic in the length of $\Phi$.

We are now in a position to give a polynomial-time algorithm for checking $(L_1)$ and $(L_2)$, which requires solving Diophantine equations. In $(L_2)$, for example, to verify that, for each $p \in \Theta$, we have $\neg p \notin F_0^k(\Psi)$, for all $0 < k < n$, we take the automaton $A_{L,L,\neg p}$, for $L \in \Psi$, and transform them into the Chrobak normal form to obtain arithmetic progressions $a_i + b_i \mathbb{N}$, for $1 \leq i \leq M$. Then there is $k$, $0 < k < n$, with $\neg p \in F_0^k(\Psi)$ iff one of the equations $a_i + b_i m = k$ has an integer solution with $0 < k < n$. The latter can be verified by taking the integer $m = \lceil -a_i/b_i \rceil$ and checking whether either $a_i + b_i m$ or $a_i + b_i (m+1)$ belongs to the open interval $(0, n)$, which can clearly be done in polynomial time. This completes the proof of Theorem 5.1.

We can establish the matching lower bound for $\mathcal{PTL}_{core}(\boxplus, \circ_\ell/\circ_\ell)$-formulas by using a result on the complexity of deciding inequality of regular languages over singleton alphabets [Stockmeyer and Meyer 1973]. In the following theorem, we give a more direct reduction of the NP-complete problem 3SAT and repeat the argument of Stockmeyer and Meyer [1973, Theorem 6.1] to construct a small number of arithmetic progressions (each with a small initial term and common difference) that give rise to models of exponential size:

**Theorem 5.4.** The satisfiability problem for $\mathcal{PTL}_{core}(\boxplus, \circ_\ell/\circ_\ell)$-formulas is NP-hard.

**Proof.** The proof is by reduction of 3SAT [Papadimitriou 1994]. Let $f = \bigwedge_{i=1}^n C_i$ be a 3CNF with $m$ variables $p_1, \ldots, p_m$ and $n$ clauses $C_1, \ldots, C_n$. By a propositional assignment for $f$ we understand a function $\sigma: \{p_1, \ldots, p_m\} \rightarrow \{0, 1\}$. We will represent such assignments by sets of positive natural numbers. More precisely, let $P_1, \ldots, P_m$ be the first $m$ prime numbers; it is known that $P_m$ does not exceed $O(m^2)$ [Apostol 1976]. We say that a natural number $k$ represents an
assignment \( \sigma \) if \( k \) is equivalent to \( \sigma(p_i) \) modulo \( P_i \), for all \( i, 1 \leq i \leq m \). Not every natural number
represents an assignment. Consider the following arithmetic progressions:

\[
j + P_i \cdot \mathbb{N}, \quad \text{for } 1 \leq i \leq m \text{ and } 2 \leq j < P_i.
\]

Every element of \( j + P_i \cdot \mathbb{N} \) is equivalent to \( j \) modulo \( P_i \), and so, since \( j \geq 2 \), cannot represent an
assignment. Moreover, every natural number that cannot represent an assignment belongs to one of
these arithmetic progressions (see Fig. 4).

Let \( C_i \) be a clause in \( f \), for example, \( C_i = p_{i_1} \lor \neg p_{i_2} \lor p_{i_3} \). Consider the following progression:

\[
P_{i_1}^1 P_{i_2}^0 P_{i_3}^1 + P_{i_1} P_{i_2} P_{i_3} \cdot \mathbb{N}.
\]

Then a natural number represents an assignment making \( C_i \) true if and only if it does not belong to the
progressions (17) and (18). Thus, a natural number represents a satisfying assignment for \( f \) if and only if
it does not belong to any of the progressions of the form (17) and (18), for clauses in \( f \).

To complete the proof, we show that the defined arithmetic progressions can be encoded in
\( \mathcal{PTL}_{\text{core}}(\boxdot, \triangleleft\triangleright, /\triangleright) \). We take a propositional variable \( d \), which will be shared among many
formulas below. Given an arithmetic progression \( a + b \mathbb{N} \) (with \( a \geq 0 \) and \( b > 0 \)), consider the formula

\[
\theta_{a,b} = u_0 \land \bigwedge_{j=1}^{a} \Box (u_{j-1} \rightarrow \Box u_j) \land \Box (u_0 \rightarrow v_0) \land \bigwedge_{j=1}^{b} \Box (v_{j-1} \rightarrow \Box v_j) \land \Box (v_0 \rightarrow v_0) \land \Box (v_0 \rightarrow d),
\]

where \( u_0, \ldots, u_a \) and \( v_0, \ldots, v_b \) are fresh propositional variables. It is not hard to see that, in every
model satisfying \( \theta_{a,b} \) at moment \( 0 \), \( d \) is true at moment \( k \geq 0 \) whenever \( k \) belongs to \( a + b \mathbb{N} \).

So, we take \( \theta_{a,b} \) for each of the arithmetic progressions (17) and (18) and add two formulas,
\( p \land \Box(p \rightarrow \Box p) \land \Box(p \rightarrow d) \land \Box d \rightarrow \Box d \), which ensure that \( d \) and a fresh variable \( p \) are true at all
\( k \leq 0 \) but \( d \) is not true at all moments. The size of the resulting conjunction of \( \mathcal{PTL}_{\text{core}}(\boxdot, \triangleleft\triangleright, /\triangleright) \)-
formulas is \( O(n \cdot m^6) \). One can check that it is satisfiable iff \( f \) is satisfiable.

**Theorem 5.5.** The satisfiability problem for \( \mathcal{PTL}_{\text{horn}}(\boxdot, \triangleleft\triangleright, /\triangleright) \)-formulas is in PTIME.

**Proof.** Without loss of generality, we can assume that \( \Box \) does not occur in the formulas of
the form \( \lambda \) and that \( \triangleleft\triangleright, /\triangleright \) are applied only to variables. Now, observe that every satisfiable
\( \mathcal{PTL}_{\text{horn}}(\boxdot, \triangleleft\triangleright, /\triangleright) \)-formula \( \varphi \) is satisfiable in a model with a short prefix (of length linear in \( |\varphi| \))
followed by a loop of length 1 (cf. Lemma 5.2). More precisely, let \( \mathcal{M}, 0 \models \varphi \). Similarly to the proof
of Lemma 5.2, for each subformula \( \Box \varphi \) of \( \varphi \), we have only three possible choices: if \( \Box \varphi \) is always
true or always false, we set \( m_{\Box \varphi} = 0 \); otherwise, there is an \( m_{\Box \varphi} \) with \( \mathcal{M}, m_{\Box \varphi} \models \neg \varphi \lor \Box \varphi \).
Symmetrically, we take all moments \( m_{\Box \varphi} \) for all \( \Box \varphi \) in \( \varphi \). Consider the following set

\[
\{0\} \cup \{m_{\Box \varphi} \mid \varphi \text{ occurs in } \varphi\} \cup \{m_{\Box \varphi} \mid \Box \varphi \text{ occurs in } \varphi\}
\]

and suppose it consists of the numbers \( m_i, \ldots, m_j \) with \( m_i = m_j = 0 \). Let \( N \) be the number of \( \Box \varphi \)
and \( \Box \varphi \) occurring in \( \varphi \) plus 1. We extend the sequence by taking
\( m_i = m_k + 1 \), for \( k < i \leq N \), and \( m_i = m_{i-1} - 1 \), for \( i < k \). Therefore, \( \mathcal{M}, m_N \models \Box \varphi \) iff
\( \mathcal{M}, m_N \models p_i \) (and symmetrically for \( \Box \varphi \) at \( m_N \)). Let \( \mathcal{M}' \) be defined as follows:

\[
\mathcal{M}', n \models p_i \iff \begin{cases} 
\mathcal{M}, m_n \models p_i, & \text{if } n < N, \\
\mathcal{M}, m_n \models p_i, & \text{if } -N \leq n \leq N, \\
\mathcal{M}, m_N \models p_i, & \text{if } n > N.
\end{cases}
\]

It can be seen that \( \mathcal{M}', 0 \models \varphi \).
It remains to encode the existence of such a model by means of propositional Horn formulas, as Horn-SAT is known to be PTime-complete. To this end, for each propositional variable $p_i$, we take $2N + 1$ variables $p_i^m$, for $-N \leq m \leq N$. Also, for each formula $\Box_p p_i$, we take $2N + 1$ propositional variables, denoted $(\Box_p p_i)^m$, for $-N \leq m \leq N$, and similarly, for each $\Diamond p_i$, we take variables $(\Diamond p_i)^m$. Then each clause $\lambda_1 \land \cdots \land \lambda_n \rightarrow \lambda$ in $\varphi$ gives rise to the propositional clause 
\[ \lambda_0^m \land \cdots \land \lambda_n^m \rightarrow \lambda^0 \]
and each $\Box(\lambda_1 \land \cdots \land \lambda_n \rightarrow \lambda)$ in $\varphi$ gives rise to $2N + 1$ clauses 
\[ \lambda_1^m \land \cdots \land \lambda_n^m \rightarrow \lambda^m, \quad \text{for} \ -N \leq m \leq N. \]

Additionally, we need clauses that describe the semantics of $\Box_p p_i$ in $M'$ at $m$, $-N \leq m < N$:
\[ (\Box_p p_i)^m \rightarrow (\Box_p p_i)^{m+1}, \quad (\Box_p p_i)^m \rightarrow p_i^{m+1}, \quad (\Box_p p_i)^{m+1} \land p_i^{m+1} \rightarrow (\Box_p p_i)^m, \]
and clauses that describe the semantics of $\Box p_i$ in $M'$ at moment $N$:
\[ (\Box p_i)^N \rightarrow p_i^N, \quad p_i^N \rightarrow (\Box p_i)^N, \]
and symmetric clauses for each $\Box_p p_i$ in $\varphi$. It is not hard to show that every satisfying assignment for the set of the clauses above gives rise to a model $M'$ of $\varphi$ and, conversely, every model $M'$ of $\varphi$ with the structure as described above gives rise to a satisfying assignment for this set of clauses. \hfill \Box

**Remark 5.6.** In order to obtain Theorem 4.8, one can extend the proof above to formulas of the form $\varphi' \land \varphi''$, where $\varphi'$ is a $\mathcal{PTL}_{\Box_p}$-formula and $\varphi''$ a conjunction of $\mathcal{O}^n p$, for propositional variables $p$. To this end, in the definition of the set $M$, one has to take $0$ together with all $n$ for which $\mathcal{O}^n p$ occurs in $\varphi''$; the number $N$ is then equal to the number of those moments $n$ plus the number of all $\Box p$ and $\Box_p p$ occurring in $\varphi'$. The rest of the construction remains the same.

**Theorem 5.7.** The satisfiability problem for $\mathcal{PTL}_{\Box_p}$-formulas is PTime-hard.

**Proof.** The proof is by reduction of satisfiability of propositional Horn formulas with at most ternary clauses, which is known to be PTime-complete [Papadimitriou 1994]. Let $f = \land_{i=1}^n C_i$ be such a formula. We define $\varphi_f$ to be the conjunction of the following formulas:
\[ p, \quad \text{for all clauses $C_i$ of the form $p$}, \]
\[ p \rightarrow \bot, \quad \text{for all clauses $C_i$ of the form $\neg p$}, \]
\[ p \rightarrow q, \quad \text{for all clauses $C_i$ of the form $p \rightarrow q$}, \]
\[ c_i \land (p \rightarrow \Box_c c_i) \land (q \rightarrow \Box_c c_i) \land (\Box c_i \rightarrow r), \quad \text{for all clauses $C_i$ of the form $p \land q \rightarrow r$}, \]
where $c_i$ is a fresh variable for each $C_i$. It is easy to see that $f$ is satisfiable iff $\varphi_f$ is satisfiable. \hfill \Box

**Theorem 5.8.** The satisfiability problem for $\mathcal{PTL}_{\Box_p}$-formulas is NP-hard.

**Proof.** We proceed by reduction of the 3-colourability problem. Given a graph $G = (V, E)$, we use variables $p_0, \ldots, p_4$ and $v_i$, for $v_i \in V$, to define the following $\mathcal{PTL}_{\Box_p}$-formula:
\[ \varphi_G = p_0 \land \bigwedge_{0 \leq i \leq 3} \Box(p_i \rightarrow \Box p_{i+1}) \land \bigwedge_{v_i \in V} \Box(p_0 \land \Box_p \neg v_i \rightarrow \bot) \land \bigwedge_{v_i \in V} \Box(p_4 \land v_i \rightarrow \bot) \land \bigwedge_{(v_i, v_j) \in E} \Box(v_i \land v_j \rightarrow \bot). \]

Intuitively, the first 4 conjuncts choose, for each vertex $v_i$ of the graph, a moment $1 \leq n_i \leq 3$; the last one makes sure that $n_i \neq n_j$ in case $v_i$ and $v_j$ are connected by an edge in $G$. We show that $\varphi_G$ is satisfiable iff $G$ is 3-colourable. Suppose $c : V \rightarrow \{1, 2, 3\}$ is a colouring function for $G$. Define $M_i$ by setting $M_i, n \models v_i$ just in case $c(v_i) = n$, for $v_i \in V$, and $M_i, n \models p_i$ iff $n \geq i$, for $0 \leq i \leq 4$. Clearly, $M_i, 0 \models \varphi_G$. Conversely, if $M_i, 0 \models \varphi_G$ then, for each $v_i \in V$, there is $n_i \in \{1, 2, 3\}$ with $M_i, n_i \models v_i$ and $M_i, n_i \neq v_j$ whenever $(v_i, v_j) \in E$. Thus, $c : v_i \rightarrow n_i$ is a colouring function. \hfill \Box
6. **DL-LITE WITH TEMPORALISED ROLES**

Now we investigate the complexity of extensions of DL-Lite\textsubscript{bool} with temporalised roles of the form

\[ R ::= S | S^- | \Diamond R | \Box R, \]

where, as before, \( S \) is a flexible or rigid role name. Recall that the interpretation of \( \Diamond R \) and \( \Box R \) is defined by taking \( (\Diamond R)^{\mathcal{T}(n)} = \bigcup_{k \in \mathbb{Z}} R^{\mathbb{T}(k)} \) and \( (\Box R)^{\mathcal{T}(n)} = \bigcap_{k \in \mathbb{Z}} R^{\mathbb{T}(k)} \).

6.1. Directed Temporal Operators and Functionality: Undecidability

Our first result is negative. It shows, in fact, that any extension of DL-Lite\textsubscript{bool} with temporalised roles, functionality constraints on roles and either the next-time operator \( \circ \) or both \( \circ \) and \( \circ \) on concepts is undecidable.

**Theorem 6.1.** Satisfiability of \( T^*_N \text{-DL-Lite}^N_{\text{bool}} \) and \( T^*_F \text{-DL-Lite}^N_{\text{bool}} \) KBs is undecidable.

**Proof.** The proof is by reduction of the \( \mathbb{N} \times \mathbb{N} \)-tiling problem (see, e.g., [Börger et al. 1997]): given a finite set \( \mathcal{T} \) of tile types \( T = (\uparrow(T), \downarrow(T), \leftarrow(T), \rightarrow(T)) \), decide whether \( \mathcal{T} \) can tile the \( \mathbb{N} \times \mathbb{N} \)-grid, i.e., whether there is a map \( \tau: \mathbb{N} \times \mathbb{N} \rightarrow \mathcal{T} \) such that \( \uparrow(\tau(i, j)) = \downarrow(\tau(i, j + 1)) \) and \( \rightarrow(\tau(i, j)) = \leftarrow(\tau(i + 1, j)) \), for all \( (i, j) \in \mathbb{N} \times \mathbb{N} \). We assume that the colours of tiles in \( \mathcal{T} \) are natural numbers from 1 to \( k \), for a suitable \( k > 1 \).

Consider first \( T^*_N \text{-DL-Lite}^N_{\text{bool}} \) and, given \( \mathcal{T} \), construct a KB \( K_{\mathcal{T}} = (T_{\mathcal{T}}, A) \) such that \( K_{\mathcal{T}} \) is satisfiable iff \( \mathcal{T} \) tiles the \( \mathbb{N} \times \mathbb{N} \)-grid. The temporal dimension will provide us with the horizontal axis of the grid. The vertical axis will be constructed using domain elements. Let \( R \) be a role such that

\[ \geq 2 \Diamond R \sqsubseteq \bot \quad \text{and} \quad \geq 2 \Diamond R^- \sqsubseteq \bot. \]  

(19)

In other words, if \( xRy \) at some moment then there is no other \( y' \) with \( xRy' \) at any moment of time (and similarly for \( R^- \)). We generate a sequence of domain elements: first, we ensure that the concept \( \exists R \cap \circ \exists R \) is non-empty, which can be done by taking \( A = \{ A(a) \} \) and adding

\[ A \sqsubseteq \exists R \cap \circ \exists R, \]  

(20)

to the TBox \( T_{\mathcal{T}} \), and second, we add the following concept inclusion to \( T_{\mathcal{T}} \) to produce a sequence:

\[ \exists R^- \cap \circ \exists R^- \sqsubseteq \exists R \cap \circ \exists R. \]  

(21)

(The reason for generating the \( R \)-arrows at two consecutive moments of time will become clear below.) It is to be noted that the produced sequence may in fact be either a finite loop or an infinite chain of distinct elements. Now, let \( T \) be a fresh concept name for each \( T \in \mathcal{T} \) and let the concepts representing the tile types be disjoint:

\[ T \sqcap T' \sqsubseteq \bot, \quad \text{for} \quad T \neq T'. \]  

(22)

Right after the double \( R \)-arrows we place the first column of tiles:

\[ \exists R^- \cap \circ \exists R^- \sqsubseteq \bigcup_{T \in \mathcal{T}} \circ \exists R \circ \exists R. \]  

(23)

The second column of tiles, whose colours match the colours of the first one, is placed \( k+1 \) moments later; the third column is located \( k + 1 \) moments after the second one, etc. (see Fig. 5):

\[ T \sqsubseteq \bigcup_{T' \in \mathcal{T} \text{ with } \text{right}(T') = \text{left}(T')} \circ \exists R \circ \exists R. \]  

(24)

This gives an \( \mathbb{N} \times \mathbb{N} \)-grid of tiles with matching \emph{left–right} colours. To ensure that the \emph{up–down} colours in this grid also match, we use the double \( R \)-arrows at the beginning and place the columns...
of tiles $k + 1$ moments apart from each other. Consider the following concept inclusions, for $T ∈ \mathcal{T}$:

\[
T \subseteq \neg \exists R^-, \quad \text{(25)}
\]

\[
T \subseteq \neg \bigcup_p \exists R^-, \quad \text{for } 1 \leq i \leq k \text{ with } i \neq \text{down}(T), \quad \text{(26)}
\]

\[
T \subseteq \bigcup_p \text{up}(T) \exists R. \quad \text{(27)}
\]

Inclusions (25), (22) and (26) ensure that between any two tiles $k + 1$ moments apart there may be only one incoming $R$-arrow. This means that after the initial double $R$-arrows no other two consecutive $R$-arrows can occur. The exact position of the incoming $R$-arrow is uniquely determined by the $\text{down}$-colour of the tile, which together with (27) guarantees that this colour matches the $\text{up}$-colour of the tile below. Fig. 5 illustrates the construction (the solid vertical arrows represent $R$).

Let $\mathcal{T}_F$ contain all the concept inclusions defined above. It is not hard to check that $(\mathcal{T}_F, A)$ is satisfiable iff $\mathcal{T}$ tiles the $\mathbb{N} \times \mathbb{N}$-grid.

The proof for $\mathcal{T}_{FP\text{-DL-Lite}}^N_{\text{pool}}$ is much more involved. To encode the vertical axis of the $\mathbb{N} \times \mathbb{N}$-grid, we again use the role $R$ satisfying the concept inclusions

\[
\geq 2 \diamond R \subseteq \bot \quad \text{and} \quad \geq 2 \diamond R^- \subseteq \bot. \quad \text{(28)}
\]

However, as $\bigcup_p$ is not available in $\mathcal{T}_{FP\text{-DL-Lite}}^N_{\text{pool}}$, we need a completely different construction to ensure that the tiles match in the horizontal dimension. Indeed, in the proof above (cf. (24)) we use $\bigcup_p^n$ and disjunction to place a suitable tile to the right of any tile in the grid. Without the $\bigcup_p$ operator, we use another role $S$ (whose $\diamond S$ is also inverse-functional) and create special patterns to represent colours (as natural number from 1 to $k$) similarly to the way we paired $\text{up}$ and $\text{down}$ colours above. In order to create patterns and refer to the ‘next moment’, we use a trick similar to the one we used in the proof of Theorem 4.6: given a concept $C$ and $n \geq 0$, let

\[
\diamond_p^n C = \diamond_p^n C \cap \neg \diamond_p^{n+1} C \quad \text{and} \quad \diamond_p^{-n} C = \diamond_p^{-n} C \cap \neg \diamond_p^{n+1} C.
\]

Note, however, that these $\diamond_p^n$-operators can mark a domain element with $C$ only once. So, every time we need a pattern, say of $\exists S$, of a certain length on a domain element, we create a new $S$-successor, use concepts $\text{bit}_i$ (with various superscripts in the proof) to mark certain positions on that $S$-successor by means of the operators $\diamond_p^{i/1} \text{bit}_i$ and then ‘transfer’ the markings back to our domain element via inclusions of the form $\text{bit}_i \subseteq \exists S^-$ and $\text{bit}_i \subseteq \neg \exists S^-$ with functional $\diamond S^-$.

The rest of the proof is organised as follows. In Step 1, we create the structure of the horizontal axis on a fixed ABox element $a$. The structure consists of repeating blocks of length $4k + 4$ (to represent the four colours of the tile); each block has a certain pattern of complementary $V_0$- and $V_1$-arrows (see Fig. 8), which are arranged using the same technique as we outlined for $S$ so that $a$ has a ‘fan’ of $V_p$-successors $(y_0, y_1, \ldots)$ and a ‘fan’ of $V_1$-successors $(x_0, x_1, \ldots)$. Then, in Step 2, we create a sequence $z_0, z_1, \ldots$ of $R$-successors to represent the vertical axis (see Fig. 10) so that each of the $z_i$ repeats the structure of the horizontal axis (shifted by $k + 1$ with each new $z_i$).
and places tiles on a ‘fan’ of its own $S$-successors. The particular patterns of $S$-arrows within the repeating $4k + 4$ blocks will then ensure that the right–left colours match (within the same ‘fan’) and, similarly, the patterns of $R$-arrows between the $z_i$ will ensure that the up–down colours match.

**Step 1.** We encode the horizontal axis using the ABox $\mathcal{A} = \{ A(a) \}$ and a number of concept inclusions with roles $V_0$, $V_1$ and concepts $bit_{V_1}^i$, for $1 \leq i \leq 2k + 2$, and $bit_{V_0}^i$, for $1 \leq i \leq 3k + 2$.

Consider first the following concept inclusions:

\[
A \subseteq \exists V_1 \cap \Box_p \neg \exists V_1, \quad (29)
\]

\[
\geq 2 \Box V_1^- \sqsubseteq \bot, \quad (30)
\]

\[
\exists V_1^- \cap \Box_p \neg \exists V_1^- \subseteq \bigcap_{1 \leq i \leq 2k+2} \Diamond_p \, \overset{=}{\exists} \, bit_{V_1}^i \cap \Box_p \exists^{2k+3} \neg \exists V_1^-, \quad (31)
\]

\[
bit_{V_1}^i \sqsubseteq \exists V_1^-, \quad \text{for } 1 \leq i \leq k, \quad (32)
\]

\[
bit_{V_1}^{k+i} \sqsubseteq \neg \exists V_1^-, \quad \text{for } 1 \leq i \leq k + 1, \quad (33)
\]

\[
bit_{V_1}^{2k+2} \sqsubseteq \exists V_1^- \quad (34)
\]

Suppose all of them hold in an interpretation $\mathcal{I}$. Then, by (29), $a^x$ has a $V_1$-successor, say $x_0$, at moment 0 and no $V_1$-successor at any preceding moment. By (30), $x_0$ does not have a $V_1$-predecessor before 0, and so, by (31)–(34), $x_0$ has a $V_1$-predecessor at every moment $i$ with $0 \leq i \leq k$ and $i = 2k + 2$, and no $V_1$-predecessor at any other times. By (30), all these $V_1$-predecessors must coincide with $a^x$ (Fig. 6). We also need similar concept inclusions for the role $V_0$:

\[
A \subseteq \Box_p \neg \exists V_0, \quad (35)
\]

\[
\geq 2 \Box V_0^- \sqsubseteq \bot, \quad (36)
\]

\[
\exists V_0^- \cap \Box_p \neg \exists V_0^- \subseteq \bigcap_{1 \leq i \leq 2k+2} \Diamond_p \, \overset{=}{\exists} \, bit_{V_0}^i \cap \Box_p \exists^{3k+3} \neg \exists V_0^-, \quad (37)
\]

\[
bit_{V_0}^i \sqsubseteq \exists V_0^-, \quad \text{for } 1 \leq i \leq k, \quad (38)
\]

\[
bit_{V_0}^{k+i} \sqsubseteq \neg \exists V_0^-, \quad (39)
\]

\[
bit_{V_0}^{2k+2} \sqsubseteq \exists V_0^- \quad (40)
\]

together with

\[
A \subseteq \Box_p (\exists V_1 \sqcup \exists V_0), \quad (41)
\]

\[
\exists V_0 \cap \exists V_1 \sqsubseteq \bot. \quad (42)
\]

Suppose all of them hold in $\mathcal{I}$. By (41), (42), at each moment after 0, $a^x$ has either a $V_0$- or a $V_1$-successor. By (29), (42) and the observations above, $a^x$ cannot have a $V_0$-successor in the interval between 0 and $k$. Suppose $y_0$ is a $V_0$-successor of $a^x$ at $k + 1$ (that this is the case will be ensured by (43)). By (35), (36), $y_0$ has no $V_0$-predecessors before 0; so, by (37)–(40), $y_0$ has $V_0$-predecessors.
Then, by (29), the choice of

\[ V \]

moments. By (36), all these \( V_0 \)-predecessors coincide with \( a^Z \) (see Fig. 6). We show now that if

\[ \geq 2 \ V_1 \subseteq \bot \]

also holds in \( I \), then \( a^Z \) has a \( V_0 \)-successor at \( k+1 \). Indeed, suppose \( a^Z \) has a \( V_1 \)-successor \( z \) at \( k+1 \). Then, by (29), the choice of \( x_0 \) and (43), \( z \) cannot be a \( V_1 \)-successor of \( a^Z \) at any moment before that. So, \( z \) must belong to the left-hand side concept of (31), which triggers the following pattern of \( V_1 \)-successors of \( a^Z \): \( x_0 \) at moments \( i \) with \( 0 \leq i \leq k \), \( z \) at \( i \) with \( k + 1 \leq i \leq 2k + 1 \), and \( z \) at \( 3k + 1 \) (see Fig. 7). This leaves only the moments \( i \), for \( 2k + 3 \leq i \leq 3k + 2 \), without any \( V_0 \)- or \( V_1 \)-successors. But in this case \( a^Z \) cannot have any \( V_0 \)- or \( V_1 \)-successor at \( 2k + 3 \). Indeed, such a \( V_0 \)-successor \( z' \) would have no \( V_0 \)-predecessor at any moment before \( 2k + 3 \), and so, by (36)–(40), would remain a \( V_0 \)-successor of \( a^Z \) for \( k + 1 \) consecutive moments, which is impossible with only \( k \) available slots; by a similar argument and (43), \( a^Z \) has no \( V_1 \)-successor at \( 2k + 3 \). Next, if in addition

\[ \geq 2 \ V_0 \subseteq \bot \]

holds in \( I \), then \( a^Z \) has a \( V_1 \)-successor, \( x_1 \), at \( 4k + 4 \). Indeed, using (44) and an argument similar to the one above, one can show that if \( a^Z \) has a \( V_0 \)-successor \( z \) at \( 4k + 4 \) then \( z \) is different from \( y_1 \) and \( z \) cannot have \( V_0 \)-predecessors before \( 4k + 4 \). But then the pattern of \( V_0 \)-successors required by (37)–(40) would make it impossible for \( a^Z \) to have any \( V_0 \)- or \( V_1 \)-successor at \( 6k + 6 \), where \( z \) has no \( V_0 \)-predecessor.

Thus, we find ourselves in the same situation as at the very beginning of the construction, but with \( x_1 \) in place of \( x_0 \). By repeating the same argument again and again, we obtain domain elements \( x_0, x_1, \ldots \) and \( y_0, y_1, \ldots \) of the interpretation \( I \) which are, respectively, \( V_1 \) and \( V_0 \)-successors of \( a^Z \) at the moments of time indicated in Fig. 8 by black points and intervals.

**Step 2.** We are now in a position to encode the \( \mathbb{N} \times \mathbb{N} \)-tiling problem. Let us regard each \( T \in \mathcal{T} \) as a fresh concept name satisfying the disjointness concept inclusions

\[ T \cap T' \subseteq \bot, \quad \text{for } T \neq T'. \]

Consider the following concept inclusions:

\[ A \subseteq \exists R \cap \square_p \neg \exists R, \]

\[ \exists R^-, \cap \square_p \neg \exists R^- \subseteq \bigotimes_{p=2k+1}^{2k+1} row \text{-start}, \]

\[ \exists S^- \cap \square_p \neg \exists S^- \subseteq \bigcup_{T \in \mathcal{T}} T. \]

Intuitively, (46) says that \( a \) has an \( R \)-successor, say \( z_0 \), at the moment 0, and no \( R \)-successors before 0. Then, by (28), \( z_0 \) has no \( R \)-predecessors before 0. Axioms (47)–(49) make sure that \( z_0 \) has an \( S \)-successor, \( w \), which is an instance of \( T \) at \(-2k+1\), for some tile \( T \). In this case, we say that \( T \) is placed on \( z_0 \) (rather than on \( w \)). Tiles will also be placed on domain elements having \( S \)-successors.
with a specific pattern of concepts $\exists S^-$ given by the following concept inclusions:

$$\begin{align*}
\geq 2 \diamond S^- & \subseteq \bot, \\
\geq 2 S & \subseteq \bot, \\
T & \subseteq \bigcap_{1 \leq i \leq 6k+4} \diamond_p^i \text{bit}^T_i \cap \diamond^{6k+5}_{p} \neg \exists S^-,
\end{align*}$$

(50) (51) (52)

$$\begin{align*}
\text{bit}^T_k & \subseteq \neg \exists S^-, \\
\text{bit}^T_{k+1} & \subseteq \neg \exists S^-, \quad \text{if } i = \text{left}(T), \\
\text{bit}^T_{2k+1} & \subseteq \neg \exists S^-, \quad \text{if } i = \text{down}(T), \\
\text{bit}^T_{3k+2} & \subseteq \neg \exists S^-, \quad \text{if } i = \text{up}(T), \\
\text{bit}^T_{4k+3} & \subseteq \exists S^-, \quad \text{if } i = \text{right}(T), \\
\text{bit}^T_{5k+4} & \subseteq \exists S^-.
\end{align*}$$

(53) (54) (55) (56) (57) (58)

Suppose a domain element $w$ is an instance of $T$ at some moment $t$, for some $T \in \mathbb{T}$. Then $w$ will be an instance of $\exists S^-$ at the moments $t, \ldots , t + k - 1$. We think of this time interval on $w$ (and, as before, on $z_0$) as the plug, or the P-section. After the plug we have a one-instant gap (where $w$ is an instance of $\neg \exists S$). The gap is followed by a sequence of $k$ moments of time that represent left($T$) in the sense that only at the $i$th moment of the sequence, where $i = \text{left}(T)$, $w$ does not have an $S$-predecessor. Then we again have a one-instant gap, followed by a sequence of $k$-moments representing down($T$) (in the same sense), another one-instant gap and a sequence representing up($T$) (see Fig. 9). At the next moment, $t + 4k + 3$, $w$ will be an instance of $\exists S^-$; then we have $k$ gaps (i.e., $\neg \exists S^-$), called the socket, or the S-section. After the socket, at $t + 5k + 4$, $w$ is again an instance of $\exists S^-$, and then we have a sequence of $k$ moments representing ‘inverted’ right($T$): the $i$th moment of this sequence has an $S$-predecessor iff $i = \text{right}(T)$. We note that, by (50), the pattern of $\exists S^-$ on $w$ in Fig. 9 is reflected by the pattern of $\exists S$ on the $S$-predecessor $z_0$ of $w$ at $t$, which (partly) justifies our terminology when we say that tile $T$ is placed on $z_0$ (rather than on $w$).

![Fig. 8. V0- and V1-successors of a in a model of K2.](image1)

![Fig. 9. Representing a tile using an S-successor.](image2)
Thus, if the concept inclusions above hold, a tile—denote it by $T_{00}$—is placed on $z_0$ at the moment $-(2k+1)$, or, equivalently, $T_{00}$ is placed on an $S$-successor $w$ of $z_0$. The following concept inclusions will ensure then that the tiling is extended properly along both axes:

$$\exists R^+ \sqcap \Box_p \neg \exists R^- \subseteq \Box_p (\exists S \sqcup \exists R \sqcup \exists R^-),$$  \hspace{1cm} (59)
$$\exists R^+ \sqcap \Box_p \neg \exists R^- \subseteq \Box_p \neg \exists R,$$  \hspace{1cm} (60)
$$\exists V_0 \neg \exists R \sqsubseteq \bot,$$  \hspace{1cm} (61)
$$\exists V_0 \exists R \sqsubseteq \bot,$$  \hspace{1cm} (62)
$$\exists S \sqcap \exists R \sqsubseteq \bot,$$  \hspace{1cm} (63)
$$\exists S \sqcap \exists R^- \sqsubseteq \bot,$$  \hspace{1cm} (64)
$$\exists R \exists R^- \sqsubseteq \bot.$$  \hspace{1cm} (65)

Indeed, consider the elements $z_0$ and $w$ with the tile $T_{00}$ placed on $z_0$ at $-(2k+1)$. Then $w$ has gaps (i.e., no incoming $S$-arrows) at moments 0, $down(T_{00})$, $k + 1$, $k + 1 + up(T_{00})$, $k$ gaps from $2k + 3$ to $3k + 2$ and $k - 1$ gaps from $3k + 4$ to $4k + 3$ (one of the positions is not a gap because of the inverted representation of right($T_{00}$)). By (59), each of those positions on $z_0$ must be filled either by an outgoing $S$-arrow, or by an incoming $R$-arrow, or by an outgoing $R$-arrow. Consider now what happens in these positions (see Fig. 10).

1. We know that there is an incoming $R$-arrow at 0 (i.e., $z_0$ is an instance of $\exists R^-$), and so, by (64) and (65), $z_0$ cannot be an instance of $\exists S$ and $\exists R$ at 0.

2. The position at $down(T_{00})$ is filled by an incoming $R$-arrow using the following concept inclusions (by (64), the incoming $R$-arrow can only appear at $down(T_{00})$):

$$A \sqsubseteq \bigcup_{1 \leq i \leq k} \Diamond^p \init\newcommand{init-bot}{{\text{init-bot}}},$$  \hspace{1cm} (66)
$$\init\newcommand{init-bot}{{\text{init-bot}}} \sqsubseteq \exists R.$$  \hspace{1cm} (67)

3. The position at $k + 1$ cannot be filled by an outgoing $S$-arrow because that would trigger a new tile sequence, which would require $k$ $S$-arrows of the P-section, which is impossible due to (51).

Next, as we observed above, $a^n$ belongs to $\exists V_0$ at all moments $i$ with $k + 1 \leq i \leq 2k + 1$, and so, by (28) and (61), $z_0$ cannot have an incoming $R$-arrow at moment $k + 1$. Thus, the position at $k + 1$ must be filled by an outgoing $R$-arrow. Thus, there is an $R$-successor $z_1$ of $z_0$, which, by (28), implies that $z_1$ has no incoming $R$-arrows before $k + 1$. Then, by (47)–(58), there will be a tile placed on $z_1$ at $-k = (k + 1) - (2k + 1)$. 
(4) Similarly, the position at $k + 1 + up(T)$ must be filled by an outgoing $R$-arrow, which ensures that the down-colour of the tile placed on $z_1$ matches the up-colour of the tile on $z_0$.

(5) The $k$ positions of the S-section from $2k + 3$ to $3k + 2$ cannot be filled by an incoming $R$-arrow. On the other hand, the tile placed on $z_1$ has its up-colour encoded in this range, and so an outgoing $R$-arrow cannot fill all these gaps either (as $k > 1$). So, $z_0$ has another S-successor $x_1$ at least one of the moments of the S-section. By (48), (50), $x_1$ does not belong to $\exists S^-$ before $-(2k+1)$. By (49), a tile is placed on $x_1$ between $-(2k+1)$ and $3k+2$, but, by (51) and because the tile requires $x_1$ to be the S-successor for $k$ consecutive moments of the P-section, it is only possible at $2k+2$. Moreover, since the left- and right-sections of these tile sequences overlap on $z_0$, by (51), the adjacent colours of these two tiles match. This ensures that the $k-1$ gaps of the inverted representation of the right-colour of the first tile are also filled.

Let $K_T$ be the KB containing all the concept inclusions above and $A$. If $I$ is a model of $K_T$ then the process described above generates a sequence $z_0, z_1, \ldots$ of domain elements such that each $z_i$ has a tile placed on it at every $4k + 4$ moments of time; moreover, the $R$-arrows form a proper $\mathbb{N} \times \mathbb{N}$-grid and the adjacent colours of the tiles match. We only note that the gaps at positions in the down-section do not need a special treatment after the very first tile $I_{10}$ at $(0,0)$ because, for each $z_i$, the sequence of tiles on $z_{i+1}$ will have their left- and right-sections, with no gap to be filled by an incoming $R$-arrow; thus, the only available choice for tiles on $z_i$ is $\exists R$.

We have proved that if $K_T$ is satisfiable then $\exists$ tiles $\mathbb{N} \times \mathbb{N}$. The converse implication is shown using the satisfying interpretation illustrated in Fig. 10. 

\section{6.2. Undirected Temporal Operators: Decidability and NP-completeness}

If we disallow the ‘previous time,’ ‘next time,’ ‘always in the past’ and ‘always in the future’ operators in the language of concept inclusions and replace them with ‘always’ ($\square$) then reasoning in the resulting logic $T^\square_i$DL-Lite$^{\text{core}}$ becomes decidable and NP-complete.

Obviously, the problem is NP-hard (because of the underlying DL). However, rather surprisingly, the interaction of temporalised roles and number restrictions is yet another source of nondeterminism, which is exhibited already by very simple TBoxes with concept inclusions in the core fragment. The following example illustrates this point and gives a glimpse of the difficulties we shall face in the proof of the NP upper bound by means of the quasimodel technique: unlike other quasimodel proofs [Gabbay et al. 2003], where only types of domain elements need to be guessed, here we also have to guess relations between ABox individuals at all relevant moments of time.

\textbf{Example 6.2.} Let $\mathcal{T} = \{ A \sqsubseteq \geq 5 R, \geq 7 \odot R \sqsubseteq \perp \}$ and $A = \{ \bigcirc R(a, b_1), R(a, b_1), R(a, b_2), R(a, b_2), \bigcirc R(a, b_1) \}$. The second concept inclusion of the TBox implies that, in any model $I$ of $(\mathcal{T}, A)$, $a$ cannot have more than 6 $(\bigodot R)^2$-successors in total; thus, it can only have $b_1, b_2, b_3$ and up to 3 $R^2$-successors from outside the ABox. At moment 1, however, $a$ must have at least 5 $R^2$-successors, including $b_1$. Thus, one of the $(\bigodot R)^2$-successors in the ABox has to be re-used: we have either $I \models \bigodot R(a, b_2)$ or $I \models \bigcirc R(a, b_3)$.

Consider now $\mathcal{T} = \{ \geq 6 \odot R \sqsubseteq \perp, \bigcap \geq 4 \odot R \}$ and $A = \{ R(a, b_1), R(a, b_2) \}$. Then, in every model $I$ of $(\mathcal{T}, A)$, either $I \models \bigodot R(a, b_1)$ or $I \models \bigodot R(a, b_2)$.

\textbf{Theorem 6.3.} The satisfiability problem for $T^\square_i$DL-Lite$^{\text{core}}$ KBs is NP-complete.

\textbf{Proof.} Let $K = (\mathcal{T}, A)$ be a $T^\square_i$DL-Lite$^{\text{core}}$ KB. In what follows, given an interpretation $I$, we write $(\geq q \odot R)^2$ and $(\geq q \odot R)^{\mathcal{T}(a)}$ instead of $(\geq q \odot R)^2$ and $(\geq q \odot R)^{\mathcal{T}(a)}$, for $n \in \mathbb{N}$, because temporalised roles are time-invariant. As before, $\text{ob}_A$ denotes the set of all object names occurring in $\mathcal{A}$ (we assume $|\text{ob}_A| \geq 1$) and $\text{role}_A$ the set of role names in $\mathcal{K}$ and their inverses. Let $Q_T \subseteq \mathbb{N}$ be the set (cf. p. 17) comprised of 1 and all $q$ such that one of $\geq q \odot R, \geq q R$ or $\geq q \odot R$ occurs in $\mathcal{T}$ and let $Q_A$ be the set of all natural numbers from 0 to $|\text{ob}_A|$. Let $q_K = \max(Q_T \cup Q_A) + 1$. First,
we show that it is enough to consider interpretations with the number of $\square R$-successors bounded by $q_K - 1$ (see Appendix D for a proof):

**Lemma 6.4.** Every satisfiable $T^*_v\text{-DL-Lite}_\text{bod}^N$ KB $K$ can be satisfied in an interpretation $I$ with ($\geq q_K \square R)^I = \emptyset$, for each $R \in \text{role}_K$.

Next, we define the notion of quasimodel. Let $Q \supseteq Q_T \cup Q_A$ be a set of natural numbers with $\max Q = q_K - 1$. We assume that the usual order on the natural numbers in $Q = Q \cup \{\omega\}$ is extended to $\omega$, which is the greatest element: $0 < 1 < \cdots < q_K - 1 < \omega$. Let $\Sigma$ consist of the following concepts and their negations: subconcepts of concepts occurring in $K$ and $\geq q \square R$, $\geq q R$ and $\geq q \oplus R$, for all $R \in \text{role}_K$ and $q \in Q$. A $\Sigma$-type $t$ is a maximal consistent subset of:

$(t_1)$ $C \in t$ iff $\neg C \notin t$, for each $C \in \Sigma$,
$(t_2)$ $C_1 \cap C_2 \in t$ iff $C_1, C_2 \in t$, for each $C_1 \cap C_2 \in \Sigma$,
$(t_3)$ if $\boxdot C \in t$ then $C \in t$, for each $\boxdot C \in \Sigma$,
$(t_4)$ if $\geq q R \in t$ then $\geq q' R \in t$, for each $\geq q' R \in \Sigma$ with $q > q'$ (similarly for $\square R$ and $\oplus R$),
$(t_5)$ $\geq 0 \square R \in t$ but $\geq \omega \square R \notin t$, for each role $R$,
$(t_6)$ if $\geq q \square R \in t$ then $\geq q R \in t$ and if $\geq q R \in t$ then $\geq q \oplus R \in t$, for each role $R$,
$(t_7)$ if $\geq q R \in t$ then $\geq q R \in t$, for each rigid role $R$.

Denote by $Z_A$ the set of all integers $k$ such that at least one of $\bigcirc_k A(a)$, $\bigcirc_k \neg A(a)$, $\bigcirc_k S(a,b)$ or $\bigcirc_k \neg S(a,b)$ occurs in $A$, and let $Z \supseteq Z_A$ be a finite set of integers.

By a $(Z, \Sigma)$-run (or simply run, if $Z$ and $\Sigma$ are clear from the context) we mean a function $r$ from $Z$ to the set of $\Sigma$-types. Concepts of the form $\boxdot C$, $\geq q \square R$, $\geq q \oplus R$ and their negations are called *rigid*. A run $r$ is said to be *coherent* if the following holds for each rigid concept $\bar{D}$ in $\Sigma$:

$(r_1)$ if $D \in r(k_0)$, for some $k_0 \in Z$, then $D \in r(k)$ for all $k \in Z$.

In the following, the runs are assumed to be coherent and so, for rigid concepts $D$, we can write $D \in r$ in place of $D \in r(k)$, for some (all) $k \in Z$. The required $\bar{D}$-rank of $r$ at $k \in Z$ and the required $\square R$- and $\oplus R$-ranks of $r$ are defined by taking

\[
\varrho^{\bar{D},k}_r = \max\{q \in \hat{Q} \mid \geq q R \in r(k)\}, \quad \varrho^{\square R}_r = \max\{q \in \hat{Q} \mid \geq q \square R \in r\},
\]

\[
\bar{\varrho}^{\bar{D},k}_r = \max\{q \in \hat{Q} \mid \geq q \square R \in r(k)\}, \quad \bar{\varrho}^{\square R}_r = \max\{q \in \hat{Q} \mid \geq q \oplus R \in r\}.
\]

By the definition of $\Sigma$-types, $\varrho^{\square R}_r \leq \varrho^{\bar{D},k}_r \leq \bar{\varrho}^{\bar{D},k}_r$. Moreover, if $R$ is rigid then $\bar{\varrho}^{\bar{D},k}_r = \bar{\varrho}^{\bar{D}}_r < \omega$. For flexible roles, however, the inequalities may be strict. A run $r$ is *saturated* if the following hold:

$(r_2)$ for every flexible role $R \in \text{role}_K$, if $\bar{\varrho}^{\bar{D},k}_r < \bar{\varrho}^{\bar{D}}_r$ then
- there is $k_0 \in Z$ with $\bar{\varrho}^{\bar{D},k_0}_r < \bar{\varrho}^{\bar{D},k_0}_r$,
- if additionally $\bar{\varrho}^{\bar{D},k_0}_r < \omega$, then there is $k_1 \in Z$ with $\bar{\varrho}^{\bar{D},k_1}_r < \bar{\varrho}^{\bar{D},k_1}_r$,
$(r_3)$ for every $\boxdot C \notin r$, there is $k_0 \in Z$ with $C \notin r(k_0)$.

Finally, we call $E$ a consistent $Z$-extension of $A$ if $E$ extends $A$ with assertions of the form $\bigcirc_k S(a, b)$, for $k \in Z$ and $a, b \in \text{ob}_A$, such that $\bigcirc_k S(a, b) \notin E$ for all $\bigcirc_k \neg S(a, b) \in A$. Example 6.2 shows that, given an ABox, we have first to guess such an extension to describe a quasimodel. More precisely, we have to count the number of $\bar{D}$-successors among the ABox individuals in $E$. To this end, define the following sets, for $a \in \text{ob}_A$, $R \in \text{role}_K$ and $k \in Z$:

\[
\mathcal{E}_a^{\bar{D},k} = \{b \mid \bigcirc_k R(a, b) \in E\}, \quad \mathcal{E}_a^{\square R} = \{b \mid \bigcirc^n R(a, b) \in E \text{, for all } n \in Z\},
\]

\[
\mathcal{E}_a^{\square R} = \{b \mid \bigcirc^n R(a, b) \in E \text{, for some } n \in Z\},
\]

where, as on p. 17, we assume that $E$ contains $\bigcirc^n \neg S^{-}(b, a)$ whenever it contains $\bigcirc^n S(a, b)$. We say that a $(Z, \Sigma)$-run $r$ is *a-faithful* for $E$ if

$(r_4)$ $A \in r(k)$, for all $\bigcirc_k A(a) \in E$, and $\neg A \in r(k)$, for all $\bigcirc_k \neg A(a) \in E$;
We assume that \( \omega = n \), for any natural number \( n \).

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Thus, let keeps track of this process. In contrast to the proof of Theorem 4.1, however, the runs are defined $R$ the runs in $\max q$ elements of $\rho$, whence the number of non-ABox $R$\,s that are saturated $\Delta$–successor of $\Delta$ is constructed by adding to $\Delta$, observe that, by definition, $\Delta$-successor of $\Delta$ follows from the choice of $\Delta$ and $\Delta$ exist because $\Delta \models \kappa$. We now show that $n_0$ required in $Z_3$ also exists. Suppose, on the contrary, that $a^T \not\in (q_0 + 1) R^{(n)}$, with $q_0$ as above, for all $n \in \mathbb{Z}$. Then $a^T$ has at most $\left(\rho_0^{\text{gr}} + (\left|I_a^{\text{n}}, n \right| - |I_a^{\text{gr}}|)\right)$-many $R$-successors, whence the number of non-ABox $R$-successors of $a^T$ does not exceed $\rho_0^{\text{gr}} - |I_a^{\text{gr}}|$.

Thus, $|Z_0| \leq |D| \cdot |\kappa|$, $|Z_1| \leq |2D| \cdot |\text{role}_K|$, $|Z_2| \leq |2|\text{ab}_A|^2 \cdot |\text{role}_K|$ and $|Z_3| \leq 2 \cdot |\text{ab}_A| \cdot |\text{role}_K|$. Now show that $n_0$ required in $Z_3$ also exists. Suppose, on the contrary, that $a^T \not\in (q_0 + 1) R^{(n)}$, with $q_0$ as above, for all $n \in \mathbb{Z}$. Then $a^T$ has at most $\left(\rho_0^{\text{gr}} + (\left|I_a^{\text{n}}, n \right| - |I_a^{\text{gr}}|)\right)$-many $R$-successors, whence the number of non-ABox $R$-successors of $a^T$ does not exceed $\rho_0^{\text{gr}} - |I_a^{\text{gr}}|$.
constructed interpretation $\mathcal{I}$ may contain infinite sequences of domain elements related by roles, we will need to ensure that each $\Sigma$-type of the run appears infinitely often along $\mathcal{Z}$ (note, however, that the actual order of time instants is important only for $Z_\Delta$, the instants of the ABox).

The interpretation of role names in $\mathcal{I}$ is constructed inductively along with the construction of the domain: $S^{n,m}_\mathcal{I} = \bigcup_{m \geq 0} S^{n,m}$, where $S^{n,m}_\mathcal{I} \subseteq \Delta_m \times \Delta_m$, for $m \geq 0$. Given $m \geq 0$ and $u \in \Delta_m$, we define the actual $S$-rank at moment $n \in \mathbb{Z}$ and the actual $\Box S$- and $\Diamond S$-ranks on step $m$:

$$r^{S,n}_{u,m} = \{u' \in \Delta_m \mid (u, u') \in S^{n,m}_\mathcal{I}\}, \quad r^{\Box S,n}_{u,m} = \{u' \in \Delta_m \mid (u, u') \in S^{k,m}_\mathcal{I}, \text{ for all } k \in \mathbb{Z}\},$$

$$r^{\Diamond S,n}_{u,m} = \{u' \in \Delta_m \mid (u, u') \in S^{k,m}_\mathcal{I}, \text{ for some } k \in \mathbb{Z}\}.$$ 

The actual $S^-$, $\Box S^-$ and $\Diamond S^-$-ranks are defined similarly, with $(u, u')$ replaced by $(u', u)$. Let

$$\delta^{\Box S,n}_{u,m} = \delta^{\Box S}_{\mathcal{I}^\mathit{cp}(u)} - r^{\Box S,n}_{u,m}, \quad \delta^{\Diamond S,n}_{u,m} = \delta^{\Diamond S}_{\mathcal{I}^\mathit{cp}(u)} - r^{\Diamond S,n}_{u,m} \quad \text{for each } n \in \mathbb{Z}.$$ 

The inductive construction of the domain and sets $S^{n,m}$ will ensure that, for each $m \geq 0$, the following holds for all $u \in \Delta_m \setminus \Delta_{m-1}$ (for convenience, we assume $\Delta_{-1} = \emptyset$):

1. (fn) $r^{\Diamond S,n}_{u,m} < \omega$, for all $R \in \text{role}_\mathcal{I}$;
2. (rn) $0 \leq r^{\Box S,n}_{u,m} \leq r^{\Diamond S,n}_{u,m}$, for all $R \in \text{role}_\mathcal{I}$ and all $n \in \mathbb{Z}$;
3. (df) for all $R \in \text{role}_\mathcal{I}$, if $\delta^{\Box S,n}_{u,m} < \delta^{\Diamond S,n}_{u,m}$ then
   - if additionally $\delta^{\Box S,n}_{u,m} < \omega$, then $\delta^{\Box S,n}_{u,m} < \delta^{\Diamond S,n}_{u,m}$, for infinitely many $n \in \mathbb{Z}$, and
   - if additionally $\delta^{\Box S,n}_{u,m} < \omega$, then $\delta^{\Box S,n}_{u,m} < \delta^{\Diamond S,n}_{u,m}$, for infinitely many $n \in \mathbb{Z}$.

Note that, by (fn), $\delta^{\Box S,n}_{u,m}$ and $\delta^{\Box S,n}_{u,m}$ are well-defined and $\delta^{\Diamond S,n}_{u,m} = \omega$ is just in case $\delta^{\Box S,n}_{u,m} = \omega$.

For the basis of induction ($m = 0$), set $\Delta_0 = \text{ob}_\mathcal{A}$ and $\alpha^\mathcal{A} = \alpha$, for each $\alpha \in \text{ob}_\mathcal{A}$. By (Q2), for each $\alpha \in \Delta_0$, there is a run $r_{\alpha} \in R$ that is $\alpha$-faithful for $E$. So, set $\mathcal{I}^\mathit{cp}(\alpha) = r_{\alpha}$ and take $\nu_{\alpha} = \nu$, for some fixed function $\nu : \mathbb{Z} \to Z$ such that $\nu(k) = k$ and $\nu^{-1}(k)$ is infinite, for each $k \in \mathbb{Z}$. For every role name $S$, let

$$S_{n,0}^n = \{(a, b) \in \Delta_0 \times \Delta_0 \mid \nu^{(n)}(S(a, b)) \in E\} \quad \text{for } n \in \mathbb{Z}. \quad (68)$$

By definition, $r^{\Box S,n}_{0,0} = |E^\mathcal{A}|$, $r^{\Box S,n}_{0,0} = |E^\mathcal{R,\nu(n)}|$, for all $n \in \mathbb{Z}$, and $r^{\Diamond S,n}_{0,0} = |E^\mathcal{R}|$. For each $\alpha \in \Delta_0$, (fn) is by construction, (rn) is immediate from (r5) and (df) follows from (r6) and the fact that $\nu^{-1}(k)$ is infinite, for each $k \in \mathbb{Z}$.

Assuming that $\Delta_m$ and the $S^{n,m}_\mathcal{I}$ have been defined and (fn), (rn) and (df) hold for some $m \geq 0$, we construct $\Delta_{m+1}$ and the $S^{n,m+1}_\mathcal{I}$ and show that the properties also hold for $m + 1$. By (rn), for all $u \in \Delta_m$ and $R \in \text{role}_\mathcal{I}$, we have $\delta^{\Box S,n}_{u,m} \geq 0$, $\delta^{\Diamond S,n}_{u,m} \geq 0$, for all $n \in \mathbb{Z}$, and $\delta^{\Box S,n}_{u,m} \geq 0$. If these inequalities are actually equalities then we are done. However, in general this is not the case as there may be "defective" elements whose actual rank is smaller than the required rank. Consider the following four sets of defects in $S^{n,m}_\mathcal{I}$, for $R = S$ and $R = S^-$:

$$\Lambda_{\mathcal{R}}^{m} = \{u \in \Delta_m \setminus \Delta_{m-1} \mid 0 < \delta^{\Box S,n}_{u,m}\} \quad \text{and} \quad \Lambda_{\mathcal{R}}^{m} = \{u \in \Delta_m \setminus \Delta_{m-1} \mid \delta^{\Box S,n}_{u,m} < \delta^{\Diamond S,n}_{u,m}\}.$$ 

The purpose of $\Lambda_{\mathcal{R}}^{m} \mathcal{R}$ is to identify elements $u \in \Delta_m \setminus \Delta_{m-1}$ that should have $\delta^{\Box S,n}_{u,m}$ many distinct $\Box S$-arrows (according to $Q$), but some arrows are still missing (only $\delta^{\Box S,n}_{u,m}$ arrows exist in $\Delta_m$).

The purpose of $\Lambda_{\mathcal{R}}^{m} \mathcal{R}$ is to identify elements $u$ that should have $\delta^{\Diamond S,n}_{u,m}$ many distinct $\Diamond S$-arrows (according to $Q$), but some arrows are still missing—only $\delta^{\Box S,n}_{u,m}$ arrows exist in $\Delta_m$ and $\delta^{\Box S,n}_{u,m}$ of those are in fact $\Box S$-arrows. Although $\Box S$-arrows are also $\Diamond S$-arrows, their defects are repaired using a separate rule; and defects of $S$-arrows are dealt with as part of repairing defects of $\Diamond S$-arrows. The following rules extend $\Delta_m$ to $\Delta_{m+1}$ and each $S^{n,m}_\mathcal{I}$ to $S^{n+1,m}_\mathcal{I}$.
By construction, the rules guarantee that, for any $m \in \mathbb{N}$, $A. Artale, R. Kontchakov, V. Ryzhikov, M. Zakharyaschev$

(2.3) If $\delta_{GS}^{u,n} > 0$ then $\theta_{cp}^{GS}(v_i) \geq 1$. We add $q = \delta_{GS}^{u,n}$ copies $v_1, \ldots, v_q$ of the run $r'$ to $\Delta_{m+1}$ and set $cp(v_i) = r'$, add $(u, v_i)$ to $S^{m,n+1}$, for all $n \in \mathbb{Z}$, and let $\nu_{v_i} : Z \rightarrow Z$ be such that $\nu_{v_i}^{-1}(k)$ is infinite, for each $k \in Z$.

(2.4) Let $K$ be $\{i \mid 0 \leq i \leq \delta_{u,m}^{GS} - \delta_{u,m}^{GS}\}$ if $\delta_{u,m}^{GS} < \omega$ and $\{i \mid 0 < i \leq q_K + 1\}$ otherwise. By assumption, $K \neq \emptyset$. We attach $|K|$ fresh $\otimes S$-successors to $u$ so that the required $\oplus S$, $\otimes S$- and $\otimes S$-ranks coincide with the respective actual ranks at step $m + 1$. By (fn) and (df), there exists a function $\gamma : Z \rightarrow 2^K$ such that, for each $i \in K$, there are infinitely many $n_0 \in \mathbb{Z}$ with $i \notin \gamma(n_0)$ and infinitely many $n_1 \in \mathbb{Z}$ with $i \in \gamma(n_1)$, and for all $n \in \mathbb{Z}$,

$$|\gamma(n)| = \begin{cases} \delta_{u,m}^{GS} - \delta_{u,m}^{GS}, & \text{if } \delta_{u,m}^{GS} < \omega, \\ q_K, & \text{otherwise.} \end{cases}$$

By assumption, we have $\theta_{cp(u)}^{\otimes R} < \theta_{cp(u)}^{\otimes R}$, by definition, $\tau_{u,m}^{\otimes R} \leq \tau_{u,m}^{\otimes R}$ and, by (fn), $\tau_{u,m}^{\otimes R} < \omega$, whence $\theta_{cp(u)}^{\otimes R} < \theta_{cp(u)}^{\otimes R}$. Therefore, by (Qs), there exists $r' \in \mathbb{R}$ with $\theta_{cp(u)}^{\otimes S} < \theta_{cp(u)}^{\otimes S}$. We add $|K|$ fresh copies $v_1, \ldots, v_{|K|}$ of $r'$ to $\Delta_{m+1}$ and, for each $i \in K$, set $cp(v_i) = r'$ and, for every $n \in \mathbb{Z}$, add $(u, v_i)$ to $S^{n,m+1}$ iff $i \in \gamma(n)$. Let

$$Z^{\otimes S} = \{k \in Z \mid \theta_{cp}^{\otimes S}(k) = \theta_{cp}^{\otimes S}\}$$

$$Z^{\otimes S} = \{k \in Z \mid \theta_{cp}^{\otimes S}(k) \neq \theta_{cp}^{\otimes S}\},$$

otherwise.

For each $v_i$, we take a function $\nu_{v_i} : Z \rightarrow Z$ such that each $\nu_{v_i}^{-1}(k)$ is infinite, for $k \in Z$, and

- if $k \in Z^{\otimes S}$ then $i \notin \gamma(n)$, for each $n \in \nu_{v_i}^{-1}(k)$;
- if $k \in Z \setminus (Z^{\otimes S} \cup Z^{\otimes S})$ then $i \in \gamma(n)$ for infinitely many $n \in \nu_{v_i}^{-1}(k)$ and $i \notin \gamma(n)$ for infinitely many $n \in \nu_{v_i}^{-1}(k)$;
- if $k \in Z^{\otimes S}$ then $i \notin \gamma(n)$, for each $n \in \nu_{v_i}^{-1}(k)$

(see Fig. 11). Intuitively, if $k$ is such that not every $S$-predecessor is required to be a $\oplus S$-predecessor then there should be infinitely many copies of $k$ with $(u, v_i) \in S^{n,m+1}$; symmetrically, if $k$ is such that not every $\otimes S$-predecessor is required to be an $S$-predecessor, there should be infinitely many copies of $k$ with $(u, v_i) \notin S^{n,m+1}$.

(2.2) and (2.4) are the mirror images of (2.1) and (2.3), respectively.

By construction, the rules guarantee that, for any $m \geq 0$ and $u \in \Delta_m$,

$$0 = \delta_{v,m+1}^{\otimes R} = \delta_{u,m+1}^{\otimes R}, \quad \text{for all } R \in \text{role}_c \text{ and all } n \in \mathbb{Z}. \quad (69)$$

We now show that (fn), (rn) and (df) hold for each $v \in \Delta_{m+1} \setminus \Delta_m$. Indeed, (fn) holds because $\tau_{v,m+1}^{\otimes S} \leq 1$. In the case of (2.2), property (rn) follows from

$$1 = \tau_{v,m+1}^{\otimes S} \leq \tau_{v,m+1}^{\otimes S} = \tau_{v,m+1}^{\otimes S} \leq \theta_{cp}^{\otimes S}(v_i) \leq \theta_{cp}^{\otimes S}(v_i), \quad (70)$$

$$0 = \tau_{v,m+1}^{\otimes R} = \tau_{v,m+1}^{\otimes R} = \theta_{cp}^{\otimes R}(v_i) \leq \theta_{cp}^{\otimes R}(v_i), \quad (71)$$

Then (df) is by the definition of $\nu_{v_i}$. The case of (2.3) is similar. For the case of (2.4), we observe that, for each $R \neq S^-$, we have (71), and so (rn) and (df) follow as above. Let us consider $S^-$. By (r2), both $Z \setminus Z^{\otimes S}$ and $Z \setminus Z^{\otimes S}$ are non-empty. It follows that $\tau_{v,m+1}^{\otimes S} = 0$ and $\tau_{v,m+1}^{\otimes S} = 1$. By definition, we also have (rn). To show (df), suppose $\theta_{cp}^{\otimes S}(v_i) < \theta_{cp}^{\otimes S}(v_i)$. Clearly, $Z^{\otimes S} \cap Z^{\otimes S} = \emptyset$. If there is $k \in Z^{\otimes S}$ then $\tau_{v,m+1}^{\otimes S} = \theta_{cp}^{\otimes S}(v_i)$ and $\tau_{v,m+1}^{\otimes S} = 1$, for all (infinitely many) $n \in \nu_{v_i}^{-1}(k)$, whence the first item of (df) holds; otherwise, there is $k \in Z \setminus (Z^{\otimes S} \cup Z^{\otimes S})$ and therefore,
The second item of \( \text{df} \) holds. The second item of \( \text{df} \) is specified inside the square nodes. Note that, at instant \( k \) run \(|K|\) which are of polynomial size in \( \nu \) and the fact that arrows to \( u \). The basis of induction is by definition for \( \nu \) \( C \). Next, we show by induction on the construction of concepts \( A \) from the complexity of \( K \) structure. The induction step for \( C \) \( \mathbb{Q} \) \( \mathbb{Z}, \mathbb{R} \), \( \mathbb{E} \) consisting of a set \( \mathbb{X} \) of runs and an extension \( \mathbb{E} \) of the ABox \( A \), both of which are of polynomial size in \( |K| \), and check that \( \Omega \) is a quasimoodel for \( K \). NP-hardness follows from the complexity of \( DL\)-\textit{Lite} \( bool \). This completes the proof of Theorem 6.3.

\[
\begin{align*}
\psi_{cp}^{S-} & = 0, \quad \psi_{\phi}^{S-} = 2 \\
\psi_{cp}^{S-} & = 1, \quad \psi_{\phi}^{S-} = 3 \\
\psi_{cp}^{S-} & = 1, \quad \psi_{\phi}^{S-} = 1
\end{align*}
\]

Fig. 11. Repairing defects of \( u \): the required \( S \)-rank, \( \theta_{cp}^{S-} \), of \( u \) is specified inside the circular nodes. Rule \((\Lambda_{cp}^{S-})\) uses run \( r' \) to create \( v_1 \); \((\Lambda_{\phi}^{S-})\) uses copies of run \( r'' \) to create \( v_2 \) and \( v_3 \). The required \( S^{-}\)-rank, \( \theta_{cp}^{S-} \), of the created points is specified inside the square nodes. Note that, at instant \( k_3 \), the element \( v_3 \) requires an \( S \)-successor different from \( u \).

\[\psi_{cp}^{S-} < \theta_{cp}^{S-} \quad \text{and} \quad \tau_{S^{-}, n} > 0, \text{ for infinitely many } n \in \nu^{-1}(k), \text{ whence the first item of } \text{(df)} \text{ holds. The second item of } \text{(df)} \text{ is obtained by a symmetric argument.}\]

The definition of \( I \) is completed by taking \( A^{(n)} = \{ u \in \Delta^I \mid \exists A \in r(\nu_a(n)), r = \phi(\nu) \} \), for each concept name \( A \). Observe that \( I \models E \) because each \( \nu_a, a \in \partial_A \), coincides with the fixed \( \nu \). Next, we show by induction on the construction of concepts \( C \) in \( K \) that

\[C \in r(\nu_a(n)) \text{ with } r = \phi, \text{ iff } u \in C^{(n)}, \text{ for all } n \in \mathbb{Z} \text{ and } u \in \Delta^I.\]

The basis of induction is by definition for \( C = \bot \) and \( C = A \); for \( C = \geq q R \) it follows from (69) and the fact that arrows to \( u \in \Delta m \setminus \Delta m - 1 \) can be added only at steps \( m \) and \( m + 1 \) as part of the defect repair process. The induction step for \( C = \neg C_1 \) and \( C = C_1 \cap C_2 \) follows from the induction hypothesis by (t1) and (t2), respectively. The induction step for \( C = \bigcirc C_1 \) follows from the induction hypothesis by (t1), (t3), (r1) and (r3). Thus, by (Q), \( I \models T \).

It remains to show \( I \models A \). By the definition of \( \mathbb{E} \) and \( I \), if \( \bigcirc^k A(a) \in A \), then \( I \models \bigcirc^k A(a) \) and if \( \bigcirc^k \neg A(a) \in A \) then \( I \models \bigcirc^k \neg A(a) \). If \( \bigcirc^k S(a, b) \in A \) then \( \bigcirc^k S(a, b) \), and \( \bigcirc^k \neg S(a, b) \), then \( (a^2, b^2) \in S^{k,0} \), whence \( I \models \bigcirc^k S(a, b) \). If \( \bigcirc^k \neg S(a, b) \in A \) then \( (a^2, b^2) \notin \mathbb{E} \), whence \( (a^2, b^2) \notin S^{k,0} \) by (68), and so \( I \models \bigcirc^k \neg S(a, b) \) as no new arrows can be added between ABox individuals.

We are now in a position to establish the NP membership of the satisfiability problem for \( T_U^{DL\text{-}Lite} \text{\_} bool \) KBs. To check whether a KB \( K = (\mathbb{T}, A) \) is satisfiable, it is enough to guess a structure \( \Omega = (Q, Z, \mathbb{R}, \mathbb{E}) \) consisting of a set \( \mathbb{X} \) of runs and an extension \( \mathbb{E} \) of the ABox \( A \), both of which are of polynomial size in \( |K| \), and check that \( \Omega \) is a quasimoodel for \( K \). NP-hardness follows from the complexity of \( DL\text{-}Lite \text{\_} bool \). This completes the proof of Theorem 6.3.

7. CONCLUSIONS

Logics interpreted over two- (or more) dimensional Cartesian products are notorious for their bad computational properties, which is well-documented in the modal logic literature (see [Gabbay et al. 2003; Kurucz 2007] and references therein). For example, satisfiability of bimodal formulas over Cartesian products of transitive Kripke frames is undecidable [Gabelaia et al. 2005]; by dropping the requirement of transitivity we gain decidability, but not elementary [Göller et al. 2012]; if one dimension is a linear-time line then the complexity can only become worse [Gabbay et al. 2003].

The principal achievement of this article is the construction of temporal description logics that (i) are interpreted over 2D Cartesian products, (ii) are capable of capturing standard temporal conceptual modelling constraints, and (iii) in many cases are of reasonable computational complexity. Although TDLs \( T_{FP}^{DL\text{-}Lite} \text{\_} bool \) and \( T_X^{DL\text{-}Lite} \text{\_} bool \), capturing lifespan cardinalities to-
gether with qualitative or quantitative evolution, turned out to be undecidable (as well as TDLs with unrestricted role inclusions), the complexity of the remaining ten logics ranges between \text{NLogSPACE} and \text{PSpace}. We established these positive results by reductions to various clausal fragments of propositional temporal logic (the complexity analysis of which could be of interest on its own). We have conducted initial experiments, using two off-the-shelf temporal reasoning tools, NuSMV [Cimatti et al. 2002] and TeMP [Hustadt et al. 2004], which showed feasibility of automated reasoning over TCMs with both timestamping and evolution constraints but without sub-relations (\(T_{\text{FPX}} \text{DL-Lite}^N_{\text{core}}\)). Many efficiency issues are yet to be resolved but the first results are encouraging.

The most interesting TDLs not considered in this article are probably \(T_{\text{FPX}} \text{DL-Lite}^N_{\text{core}}\) and \(T_{\text{FPX}} \text{DL-Lite}^N_{\text{core \_total}}\). We conjecture that both of them are decidable. We also believe that the former can be used as a variant of temporal RDFS (cf. [Gutiérrez et al. 2005]).

Although the results in this article establish tight complexity bounds for TDLs, they can only be used to obtain upper complexity bounds for the corresponding fragments of TCMs; the lower bounds are mostly left for future work [Artale et al. 2010].

The original \text{DL-Lite} family [Calvanese et al. 2007] was designed with the primary aim of ontology-based data access (OBDA) by means of first-order query rewriting. In fact, OBDA has already reached a mature stage and become a prominent direction in the development of the next generation of information systems and the Semantic Web; see [Polleres et al. 2013; Kontchakov et al. 2013] for recent surveys and references therein. In particular, W3C has introduced a special profile, \text{OWL 2 QL}, of the Web Ontology Language \text{OWL 2} that is suitable for OBDA and based on the \text{DL-Lite} family. An interesting problem, both theoretically and practically, is to investigate how far this approach can be developed in the temporal case and what temporal ontology languages can support first-order query rewriting; see recent [Gutiérrez-Basulto and Klarman 2012; Motik 2012; Artale et al. 2013; Baader et al. 2013; Borgwardt et al. 2013] for some initial results.

**ELECTRONIC APPENDIX**

The electronic appendix for this article can be accessed in the ACM Digital Library.

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A PROOF OF THEOREM 4.1

**THEOREM 4.1.** A \( T_{\text{US}} \text{DL-Lite}^\mathcal{N} \) KB \( \mathcal{K} = (\mathcal{T}, \mathcal{A}) \) is satisfiable iff the QT \( \mathcal{L}^1 \) sentence \( \mathcal{K}^1 \) is satisfiable.

**Proof.** \((\Leftarrow\Rightarrow)\) Let \( \mathfrak{M} \) be a first-order temporal model with a *countable* domain \( D \) and \( \mathfrak{M}, 0 \models \mathcal{K}^1 \).

Without loss of generality we may assume that the \( a^m \), for \( a \in \text{ob}_A \), are all distinct. We are going to construct a \( T_{\text{US}} \text{DL-Lite}^\mathcal{N} \) interpretation \( \mathcal{I} \) satisfying \( \mathcal{K} \) and based on some domain \( \Delta^\mathcal{I} \) that will be inductively defined as the union

\[
\Delta^\mathcal{I} = \bigcup_{m \geq 0} \Delta_m, \quad \text{where} \quad \Delta_0 = \{ a^m \mid a \in \text{ob}_A \} \subseteq D \quad \text{and} \quad \Delta_m \subseteq \Delta_{m+1}, \text{for} \ m \geq 0.
\]

The interpretations of object names in \( \mathcal{I} \) are given by their interpretations in \( \mathfrak{M} \): \( a^\mathcal{I} = a^m \in \Delta_0 \).

Each set \( \Delta_{m+1} \), for \( m \geq 0 \), is constructed by adding to \( \Delta_m \) some new elements that are fresh copies of certain elements from \( D \setminus \Delta_0 \). If such a new element \( u \) is a copy of \( u' \in D \setminus \Delta_0 \) then we write \( cp(u) = u' \), while for \( u \in \Delta_0 \) we let \( cp(u) = u \).

The interpretation \( A^\mathcal{I}(n) \) of each concept name \( A \) in \( \mathcal{I} \) is defined by taking

\[
A^\mathcal{I}(n) = \{ u \in \Delta^\mathcal{I} \mid \mathfrak{M}, n \models A^\mathcal{I}[cp(u)] \}. \tag{72}
\]

The interpretation \( S^\mathcal{I}(n) \) of each role name \( S \) in \( \mathcal{I} \) is constructed inductively as the union

\[
S^\mathcal{I}(n) = \bigcup_{m \geq 0} S^{n,m}, \quad \text{where} \quad S^{n,m} \subseteq \Delta_m \times \Delta_m, \text{for all} \ m \geq 0.
\]

We require the following two definitions to guide our construction. The *required R-rank* \( \rho_{d}^{R,n} \) of \( d \in D \) at moment \( n \) is

\[
\rho_{d}^{R,n} = \max(\{0\} \cup \{ q \in Q_T \mid \mathfrak{M}, n \models E_q R[d] \}).
\]

By (5), \( \rho_{d}^{R,n} \) is a function and if \( \rho_{d}^{R,n} = q \) then \( \mathfrak{M}, n \models E_q R[d] \) for every \( q' \in Q_T \) with \( q' \leq q \), and \( \mathfrak{M}, n \models \neg E_q R[d] \) for every \( q' \in Q_T \) with \( q' > q \). We also define the *actual R-rank* \( \tau_{u,m}^{R,n} \) of \( u \in \Delta^\mathcal{I} \) at moment \( n \) and step \( m \) by taking

\[
\tau_{u,m}^{R,n} = \max(\{0\} \cup \{ q \in Q_T \mid (u, u_1), \ldots, (u, u_q) \in R^{n,m} \text{ for distinct } u_1, \ldots, u_q \in \Delta^\mathcal{I} \}),
\]

where \( R^{n,m} \) is \( S^{n,m} \) if \( R = S \) and \( \{(u', u) \mid (u, u') \in S^{n,m}\} \) if \( R = S^- \), for a role name \( S \).

For the basis of induction, for each role name \( S \), we set

\[
S^{n,0} = \{(a^T, b^T) \in \Delta_0 \times \Delta_0 \mid S(a, b) \in \mathcal{A}^S_n\}, \quad \text{for} \ n \in \mathbb{Z} \tag{73}
\]

(note that \( S(a, b) \in \mathcal{A}^S_n \) for all \( n \in \mathbb{Z} \) if \( \bigcirc b S(a, b) \in \mathcal{A} \), for a rigid role name \( S \)). It follows from the definition of \( \mathcal{A}^I \) that, for all \( R \in \text{role}_\mathcal{C} \) and \( u \in \Delta_0 \),

\[
\rho_{cp(u)}^{R,n} \leq \rho_{d}^{R,n}, \tag{74}
\]
Suppose that $\Delta_m$ and the $S^{n,m}$ have been defined for some $m \geq 0$. If, for all roles $R$ and $u \in \Delta_m$, we had $\tau_{R,u,m} = \vartheta_{cp(u)}^R$ then the interpretation of roles would have been constructed. However, in general this is not the case because there may be some ‘defects’ in the sense that the actual rank of some elements is smaller than the required rank. Consider the following two sets of defects in $S^{n,m}$:

$$\Lambda^{n,m}_R = \{ u \in \Delta_m \setminus \Delta_{m-1} \mid \tau_{R,u,m} < \vartheta_{cp(u)}^R \},$$

for $R \in \{ S, S^- \}$

(for convenience, we assume $\Delta_{-1} = \emptyset$). The purpose of, say, $\Lambda^{n,m}_S$ is to identify those ‘defective’ elements $u \in \Delta_m \setminus \Delta_{m-1}$ from which precisely $\vartheta_{cp(u)}^S$ distinct $S$-arrows should start (according to $\mathfrak{M}$), but some arrows are still missing (only $\tau_{S,u,m}$ arrows exist). To ‘repair’ these defects, we extend $\Delta_m$ to $\Delta_{m+1}$ and $S^{n,m}$ to $S^{n,m+1}$ according to the following rules:

1. ($\Lambda^{n,m}_S$) Let $u \in \Lambda^{n,m}_S$. Denote $d = cp(u)$ and $q = \vartheta_{S,u,m}^S - \tau_{S,u,m}^R$. Then $\mathfrak{M}, n \models E_qS[d]$ for some $q' \geq q > 0$. By (5), we have $\mathfrak{M}, n \models E_1S[d]$ and, by (7), there is $d' \in D$ such that $\mathfrak{M}, n \models E_1S^-[d']$. In this case we take $q$ fresh copies $u_1', \ldots, u_q'$ of $d'$ (so $\vartheta_{S,u,m}^S(d') = q$), add them to $\Delta_{m+1}$ and add the pairs $(u, u_1'), \ldots, (u, u_q')$ to $S^{n,m+1}$. If $S$ is rigid we add these pairs to all $S^{k,m+1}$, for $k \in \mathbb{Z}$.

2. ($\Lambda^{n,m}_S$) Let $u \in \Lambda^{n,m}_S$. Denote $d = cp(u)$ and $q = \vartheta_{S^-u,m}^S - \tau_{S^-u,m}^R$. Then $\mathfrak{M}, n \models E_qS^-[d]$ for $q' \geq q > 0$. By (5), $\mathfrak{M}, n \models E_1S^-[d]$ and, by (7), there is $d' \in D$ with $\mathfrak{M}, n \models E_1S[d']$. In this case we take $q$ fresh copies $u_1', \ldots, u_q'$ of $d'$, add them to $\Delta_{m+1}$ and add the pairs $(u_1', u), \ldots, (u_q', u)$ to $S^{n,m+1}$. If $S$ is rigid we add these pairs to all $S^{k,m+1}$, for $k \in \mathbb{Z}$.

Now we observe the following property of the construction: for all $m_0 \geq 0$ and $u \in \Delta_{m_0} \setminus \Delta_{m_0-1}$,

$$\tau_{R,u,m} = \begin{cases} 
0, & \text{if } m < m_0, \\
\vartheta_{cp(u)}^R, & \text{if } m = m_0, \text{ for some } q \leq \vartheta_{cp(u)}^R, \\
\vartheta_{cp(u)}^R, & \text{if } m > m_0.
\end{cases}$$

(75)

To prove this property, consider all possible cases. If $m < m_0$ then $u \notin \Delta_m$, i.e., it has not been added to $\Delta_m$ yet, and so $\tau_{R,u,m} = 0$. If $m = m_0 = 0$ then $\tau_{R,u,m} \leq \vartheta_{cp(u)}^R$ by (74). If $m = m_0 > 0$ then $u$ was added at step $m_0$ to repair a defect of some $u' \in \Delta_{m_0-1}$. This means that either $(u', u) \in S^{n,m_0}$ and $u' \in \Lambda_{S,m_0-1}^{n,m_0-1}$, or $(u, u') \in S^{n,m_0}$ and $u' \in \Lambda_{S,m_0-1}^{n,m_0-1}$, for a role name $S$. Consider the first case. Since fresh witnesses $u$ are picked up every time the rule $(\Lambda_{S,m_0-1}^{n,m_0-1})$ is applied and those witnesses satisfy $\mathfrak{M}, n \models E_1S^-[cp(u)]$, we obtain $\tau_{R,u,m_0} = 0$, $\tau_{S,u,m_0} = 1$ and $\vartheta_{cp(u)}^S \geq 1$. The second case is similar. If $m = m_0+1$ then all defects of $u$ are repaired at step $m_0+1$ by applying the rules $(\Lambda_{S,m_0}^{n,m_0})$ and $(\Lambda_{S,m_0}^{n,m_0})$. Therefore, $\tau_{R,u,m_0} = \vartheta_{cp(u)}^R$. If $m > m_0 + 1$ then (75) follows from the observation that no new arrows involving $u$ can be added after step $m_0 + 1$.

It follows that, for all $R \in \text{role}_K$, $q \in \mathcal{Q}$, $n \in \mathbb{Z}$ and $u \in \Delta^T$,

$$\mathfrak{M}, n \models E_qR[cp(u)] \text{ iff } u \in (\geq q)^{T(n)}.$$  

(76)

Indeed, if $\mathfrak{M}, n \models E_qR[cp(u)]$ then, by definition, $\vartheta_{cp(u)}^R \geq q$. Let $u \in \Delta_{m_0} \setminus \Delta_{m_0-1}$. Then, by (75), $\tau_{R,u,m} = \vartheta_{cp(u)}^R \geq q$, for all $m > m_0$. It follows from the definition of $\tau_{R,u,m}$ and $R^{T(n)}$ that $u \in (\geq q)^{T(n)}$. Conversely, let $u \in (\geq q)^{T(n)}$ and $u \in \Delta_{m_0} \setminus \Delta_{m_0-1}$. Then, by (75), we have $q \leq \tau_{R,u,m} = \vartheta_{cp(u)}^R$, for all $m > m_0$. So, by the definition of $\vartheta_{cp(u)}$ and (5), we obtain $\mathfrak{M}, n \models E_qR[cp(u)]$. 

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C. PROOF OF THEOREM 4.5

The basis of induction is trivial for an interpretation for the Booleans ($C = \neg C_1$ and $C = C_1 \cap C_2$) and the temporal operators ($C = C_1 U C_2$ and $C = C_1 S C_2$) follows from the induction hypothesis. Thus, $\mathcal{I} \models T$.

It only remains to show that $\mathcal{I} \models A$. If $\cap^\mathcal{I} A(a) \in \mathcal{A}$ then, by the definition of $\mathcal{A}^\mathcal{I}$ and (72), $\mathcal{I} \models \cap^\mathcal{I} A(a)$. If $\cap^\mathcal{I} A(a) \in \mathcal{A}$ then, analogously, $\mathcal{I} \models \cap^\mathcal{I} A(a)$. If $\cap^\mathcal{I} S(a, b) \in \mathcal{A}$ then, by (73), $(a, b) \in S^\mathcal{I}(n)$, whence, by the definition of $S^\mathcal{I}(n)$, $\mathcal{I} \models \cap^\mathcal{I} S(a, b)$. If $\cap^\mathcal{I} S(a, b) \in \mathcal{A}$ then, by (73), $(a, b) \notin S^\mathcal{I}(n)$, and so, as no new arrows can be added between ABox individuals, $\mathcal{I} \models \cap^\mathcal{I} S(a, b)$.

$(\Rightarrow)$ is straightforward. □

C. PROOF OF THEOREM 4.5

THEOREM 4.5. The satisfiability problem for the core fragment of $T_{\text{MSDL}}$-$\text{Lite}^N_{\text{pool}}$ KBs is PSPACE-complete.

PROOF. The proof is by reduction of the halting problem for Turing machines with a polynomial tape. We recall that, given a deterministic Turing machine $M = (Q, \Sigma, \#, \Sigma, \delta, q_0, q_f)$ and a polynomial $s(n)$, we construct a $\text{TB}x_M$ containing concept inclusions (8)–(13), which we list here for the reader’s convenience:

$$H_{iq} \subseteq \cup U H_{(i+1)q'}, \quad H_{iq} \subseteq \cup U S_{ia'}, \quad \text{if } \delta(q, a) = (q', a', R) \text{ and } i < s(n),$$

$$H_{iq} \subseteq \cup U H_{(i-1)q'}, \quad H_{iq} \subseteq \cup U S_{ia'}, \quad \text{if } \delta(q, a) = (q', a', L) \text{ and } i > 1,$$

$$H_{iq} \subseteq \cup U D_i,$$

$$D_i \cap D_j \subseteq \bot, \quad \text{if } i \neq j,$$

$$S_{ia} \subseteq S_{ia} \cup D_i,$$

$$H_{iq} \subseteq \bot.$$  

(10)  
(11)  
(12)  
(13)

For an input $\vec{a} = a_1 \ldots a_n$ of length $n$, we take the following ABox $\mathcal{A}_{\vec{a}}$:

$$H_{iq_0}(d), \quad S_{ia}(d), \quad \text{for } 1 \leq i \leq n, \quad S_{i\#}(d), \quad \text{for } n < i \leq s(n).$$

We show that $(\mathcal{M}, \mathcal{A}_{\vec{a}})$ is unsatisfiable iff $M$ accepts $\vec{a}$. We represent configurations of $M$ as tuples of the form $\mathcal{C} = (b_1 \ldots b_{s(n)}, i, q)$, where $b_1 \ldots b_{s(n)}$ is the contents of the first $s(n)$ cells of the tape with $b_j \in \Gamma$, for all $j$, the head position is $i, 1 \leq i \leq s(n)$, and $q \in Q$ is the control state. Let $\mathcal{I}$ be an interpretation for $\mathcal{K}_{M, \mathcal{A}}$. We say that $\mathcal{I}$ encodes configuration $\mathcal{C} = (b_1 \ldots b_{s(n)}, i, q)$ at moment $k$ if $d^\mathcal{I} \in H_{iq}^\mathcal{I}(k)$ and $d^\mathcal{I} \in S_{jb}^\mathcal{I}(k)$, for all $1 \leq j \leq s(n)$. We note here that, in principle, many different configurations can be encoded at moment $k$ in $\mathcal{I}$. Nevertheless, any prefix of a model of $(\mathcal{M}, \mathcal{A}_{\vec{a}})$ contains the computation of $M$ on the given input $\vec{a}$.

LEMMA C.1. Let $c_0, \ldots, c_m$ be a sequence of configurations representing a partial computation of $M$ on $\vec{a}$. Then every model $\mathcal{I}$ of $(\mathcal{M}, \mathcal{A}_{\vec{a}})$ encodes $c_k$ at moment $k$, for $0 \leq k \leq m$.

PROOF. The proof is by induction on $k$. For $k = 0$, the claim follows from $\mathcal{I} \models A_{\vec{a}}$. For the induction step, let $\mathcal{I}$ encode $c_k = (b_1 \ldots b_i \ldots b_{s(n)}, i, q)$ at moment $k$, and let $c_{k+1} = (b_1 \ldots b'_i \ldots b_{s(n)}, i', q')$. Then we have $q \in Q \setminus \{q_f\}$. Consider first $\delta(q, b_i) = (q', b'_i, L)$, in which case $i > 1$ and $i' = i - 1$. Since $d^\mathcal{I} \in H_{iq}^\mathcal{I}(k)$ we have, by (10), $d^\mathcal{I} \in D_{i}^\mathcal{I}(k+1)$ and, by (9), $d^\mathcal{I} \in H_{(i-1)q'}^\mathcal{I}(k)$ and $d^\mathcal{I} \in S_{jb}^\mathcal{I}(k+1)$. Consider cell $j$, $1 \leq j \leq s(n)$, such that $j \neq i$. By (11), $d^\mathcal{I} \notin D_{j}^\mathcal{I}(k+1)$, and so, since $d^\mathcal{I} \in S_{jb}^\mathcal{I}(k)$, we obtain, by (12), $d^\mathcal{I} \in S_{jb}^\mathcal{I}(k+1)$. Hence, $\mathcal{I}$ encodes $c_{k+1}$ at moment $k + 1$. The case of $\delta(q, b_i) = (q', b'_i, R)$ is analogous. □
It follows that if $M$ accepts $\vec{a}$ then $(T_M, A_{\vec{a}})$ is unsatisfiable. Indeed, if $M$ accepts $\vec{a}$ then the computation is a sequence of configurations $c_0, \ldots, c_m$ such that $c_m = \langle b_1 \ldots b_{s(n)}, i, q_f \rangle$. Suppose $(T_M, A_{\vec{a}})$ is satisfied in a model $\mathcal{I}$. By Lemma C.1, $d^\mathcal{I} \in H_{tq^\mathcal{I}}$, which contradicts (13).

Conversely, if $M$ rejects $\vec{a}$ then $(T_M, A_{\vec{a}})$ is satisfiable. Let $c_0, \ldots, c_m$ be a sequence of configurations representing the rejecting computation of $M$ on $\vec{a}$, $c_k = \langle b_{1,k}, \ldots, b_{s(n),k}, i_k, q_k \rangle$, for $0 \leq k \leq m$. We define an interpretation $\mathcal{I}$ with $\Delta^\mathcal{I} = \{d\}$, $d^\mathcal{I} = a$ and, for every $a \in \Gamma$, $q \in Q$, $1 \leq i \leq s(n)$ and $k \geq 0$, we set (note that $q_m$ is a rejecting state and so, $\delta(q_f, a)$ is undefined):

\[
H_{tq}^\mathcal{I}(k) = \begin{cases} 
\Delta^\mathcal{I}, & \text{if } k \leq m, i = i_k \text{ and } q = q_k, \\
\emptyset, & \text{otherwise}, 
\end{cases}
\]

\[
S_{ta}^\mathcal{I}(k) = \begin{cases} 
\Delta^\mathcal{I}, & \text{if } k \leq m \text{ and } a = b_{i,k}, \\
\Delta^\mathcal{I}, & \text{if } k = m + 1 \text{ and } a = b_{i,m}, \\
\emptyset, & \text{otherwise}, 
\end{cases}
\]

\[
D_{t_s}^\mathcal{I}(k) = \begin{cases} 
\Delta^\mathcal{I}, & \text{if } 0 < k \leq m + 1 \text{ and } i = i_{k-1}, \\
\Delta^\mathcal{I}, & \text{if } k = m + 2 \\
\emptyset, & \text{otherwise}. 
\end{cases}
\]

It can be easily verified that $\mathcal{I} \models (T_M, A_{\vec{a}})$.

### D. Proof of Theorem 6.3

**Lemma 6.4.** Let $K$ be a $T_U^*$ DL-Lite$_{Ded}$ KB and $q_K = \max(Q_L \cup Q_A) + 1$. If $K$ is satisfiable then it can be satisfied in an interpretation $\mathcal{I}$ such that $(\geq q_K \uprod R^\mathcal{I}) = \emptyset$, for each $R \in \text{role}_K$.

**Proof.** Let $\mathcal{I} \models K$. Without loss of generality, we will assume that the domain $\Delta^\mathcal{I}$ is at most countable. Construct a new interpretation $\mathcal{I}^*$ as follows. We take $\Delta^\mathcal{I} \times \mathbb{N}$ as the domain of $\mathcal{I}^*$ and set $a^{\mathcal{I}^*} = (a^\mathcal{I}, 0)$, for all $a \in \text{ob}_A$. For each $n \in \mathbb{Z}$, we set

\[
A^{\mathcal{I}^*(n)} = \{ (u, i) \mid u \in \Delta^\mathcal{I}(n), i \in \mathbb{N} \},
\]

\[
S^{\mathcal{I}^*(n)} = \{ ((u, i), (v, i)) \mid (u, v) \in S^\mathcal{I}(n), i \in \mathbb{N} \},
\]

for every concept name $A$, and for every role name $S$.

It should be clear that $\mathcal{I}^* \models K$.

Suppose that $u \in \Delta^\mathcal{I}$ has at least $q_K$-many $\uprod R$-successors in $\mathcal{I}$ and assume that the pairs

\[
\{(u, i), (u_1, i)\}, \ldots, \{(u, i), (u_{q_K-1}, i)\}, \{(u, i), (u_{q_K}, i)\},
\]

are all in $(\uprod R)\Delta^\mathcal{I}$. We can also assume that if $(u_j, 0) = a^{\mathcal{I}^*}$, for some $a \in \text{ob}_A$, then $j < q_K$. We then rearrange some of the $R$-arrows of the form $((u, i), (u_j, i'))$, simultaneously at all moments of time, in the following manner. We remove $((u, i), (u_j, i))$ from $(\uprod R)\Delta^\mathcal{I}$, for all $j$ and $i$ such that $j \geq q_K$ and $i > 0$. Note that this operation does not affect the $\uprod R$-arrows to the ABox individuals. To preserve the extension of concepts of the form $\geq q \uprod R$, we then add new $\uprod R$-arrows of the form $((u, i), (u_j, i'))$, for $i > i' \geq 0$, to $(\uprod R)\Delta^\mathcal{I}$ in such a way that the following conditions are satisfied:

- for every $(u, i')$, there is precisely one $\uprod R$-arrow of the form $((u, i), (u, i'))$,
- for every $(u, i)$, there are precisely $(q_K - 1)$-many $\uprod R$-arrows of the form $((u, i), (u, i'))$.

Such a rearrangement is possible because $\mathcal{I}^*$ contains countably infinitely many copies of $\mathcal{I}$. We leave it to the reader to check that the resulting interpretation is still a model of $K$.

The rearrangement process is then repeated for each other $u \in \Delta^\mathcal{I}$ with at least $q_K$-many $\uprod R$-successors. □

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