Implicit Linear Algebra and its Applications

H. Narayanan*

Department of Electrical Engineering, Indian Institute of Technology Bombay

Abstract

Linear systems often involve, as a basic building block, solutions of equations of the form

\[ A_S x_S + A_P x_P = 0 \]
\[ A'_S x_S = 0, \]

where our primary interest might be in the vector variable \( x_P \). Usually, neither \( x_S \) nor \( x_P \) can be written as a function of the other but they are linked through the linear relationship, that of \((x_S, x_P)\) belonging to \( \mathcal{V}_{SP} \), the solution space of the first of the two equations. If \( \mathcal{V}_S \) is the solution space of the second equation, we may regard the final space of solutions \( \mathcal{V}_P \) as derived from the other two spaces by an operation, say, \( \mathcal{V}_P = \mathcal{V}_{SP} \leftrightarrow \mathcal{V}_S \). This operation, together with linear relationships, can be used to build a version of linear algebra which we call ‘implicit linear algebra’. There are two basic results - an ‘implicit inversion theorem’ which describes when \( \mathcal{V}_S \) can be obtained from \( \mathcal{V}_P \) and \( \mathcal{V}_{SP} \), and an ‘implicit duality theorem’ which says \( \mathcal{V}_P = \mathcal{V}_{SP} \leftrightarrow \mathcal{V}_S \). These notions originally arose in the building of circuit simulators \([30]\), \([3]\). They have been reinterpreted for the present purpose. Using them, we develop an algorithmic version of linear multivariable control theory, avoiding the computationally expensive idea of state equations. We replace them by ‘emulators’, which are easy to build but can achieve most of whatever can be done with state equations. We define the notions of generalized autonomous systems and generalized operators, and develop a primitive spectral theory for the latter. Using these ideas, we develop the usual controllability - observability duality, state and output feedback, pole placement etc. Throughout, we illustrate the theory using electrical circuits. This allows us to stress that linkages, that are needed for representing practical dynamical systems, usually have a topological origin which can be exploited in consonance with implicit rather than classical linear algebra.

Keywords: Linear Dynamical Systems, State Space Theory, Behavioural Systems Theory, Controlled and Conditioned Invariant Spaces, Duality in Adjoint System, Implicit Linear Algebra, Implicit Duality Theorem

2000 MSC: 15A03, 15A04, 15A18

1. Introduction

The foundations of the work described in this paper originally arose in the study of electrical network topology with the aim of building efficient circuit simulators \([7]\), \([30]\), \([31]\), \([8]\) (open 2nd edition available at \([9]\)). An electrical network is defined by topological constraints, namely Kirchhoff’s current and voltage laws and device characteristic constraints. Our approach, towards building circuit simulators, was to get maximum advantage out of manipulating the topological - rather than the device characteristic, constraints.
Some fundamental questions here are: how to connect subnetworks, how to decompose networks into multiports, what is the minimum number of variables through which blocks of a partition of edges of the network interact, how to make minimal changes in the topology of the network for faster simulation etc.

From the point of view of application of linear algebra to electrical networks, it is more useful to deal with subspaces than with transformations. The variables of interest are currents and voltages associated with edges of the graph of the network and the injected currents and potentials at nodes. The spaces, that arise, can be regarded as subspaces of a ‘global’ space with a specified basis - in a vector \((x_1, \ldots, x_n), x_i\) refers to the variable associated with the \(i\)th edge or node. A characteristic feature of the approach is, as far as possible, to avoid speaking of networks in terms of matrices but rather in terms of other derived networks. The variables of interest would often be buried in a much larger set of network variables and we have to deal with the former implicitly without trying to eliminate the latter.

When one connects subnetworks, taking the device independent point of view, there is no direction to the flow of ‘information’, merely interaction, which could be regarded as working both ways. To capture this situation, linear transformations are not suitable, rather one needs linear relations. One is naturally led to the question whether parts of linear algebra can be developed based on linear relations and, more importantly, whether there are direct applications. As mentioned before, connections of networks provide instances. However, to carry the similarity to standard linear algebra to its limit, one needs to introduce direction to the flow of information. A beginning was made in \([12]\), where it was shown that linear time invariant systems can be regarded as indexed vector spaces, and, when this is done, Kalman dual etc. have simple descriptions. Some basic results and algorithms of multivariable control come through neatly and in a computationally efficient manner. The present paper carries this work farther. A primitive ‘spectral’ theory is developed for ‘generalized operators’. A generalization of state variables which we call an ‘emulator’ is used to describe relationships between essentially identical dynamical systems in an implicit way. The processes involved are more refined than similarity transformations, capable of linking systems with different numbers of variables and yielding more information about the interrelationship between the systems.

We now give a brief account of the basic ideas, which fortunately are just a few.

A vector \(f\) on \(X\) over \(F\) is a function \(f : X \to F\) where \(F\) is a field. It would usually be represented as \(f_X\). A collection of such vectors closed under addition and scalar multiplication is a vector space denoted by \(\mathcal{V}_X\).

A linkage \(\mathcal{V}_{S_1, \ldots, S_k}\) is a vector space on \(S_1 \cup \cdots \cup S_k\) with a specified partition \(\{S_1, \ldots, S_k\}\) of \(S_1 \cup \cdots \cup S_k\).

The usual sum and intersection of vector spaces are given extended meanings as follows.

\[
\mathcal{V}_X + \mathcal{V}_Y \equiv (\mathcal{V}_X \oplus \mathbf{0}_{Y\setminus X}) + (\mathcal{V}_Y \oplus \mathbf{0}_{X\setminus Y}),
\]

\[
\mathcal{V}_X \cap \mathcal{V}_Y \equiv (\mathcal{V}_X \oplus \mathcal{F}_{Y\setminus X}) \cap (\mathcal{V}_Y \oplus \mathcal{F}_{X\setminus Y}),
\]

where \(\mathbf{0}_Z\) represents the space containing only the 0 vector on \(Z\) and \(\mathcal{F}_Z\) represents the collection of all vectors on \(Z\).

Given \(\mathcal{V}_S, T \subseteq S\), the restriction of \(\mathcal{V}_S\) to \(T\), denoted by \(\mathcal{V}_S \circ T\), is the collection of all \(f_T\), where \((f_T, f'_{S\setminus T})\), for some \(f'_{S\setminus T}\), belongs to \(\mathcal{V}_S\).

The contraction of \(\mathcal{V}_S\) to \(T\) denoted by \(\mathcal{V}_S \times T\), is the collection of all \(f_T\), where \((f_T, 0_{S\setminus T})\), belongs to \(\mathcal{V}_S\).

The matched composition of \(\mathcal{V}_{SP}, \mathcal{V}_{PQ}\), with \(S, P, Q\) pairwise disjoint, is denoted by \(\mathcal{V}_{SP} \leftrightarrow \mathcal{V}_{PQ}\) and is defined to be the collection of all \((f_S, h_Q)\) such that there exists some \(gp\) with \((f_S, gp) \in \mathcal{V}_{SP}, (gp, h_Q) \in \mathcal{V}_{PQ}\).

The skewed composition of \(\mathcal{V}_{SP}, \mathcal{V}_{PQ}\), with \(S, P, Q\) pairwise disjoint, is denoted by \(\mathcal{V}_{SP} \rightharpoonup \mathcal{V}_{PQ}\) and is defined to be the collection of all \((f_S, h_Q)\) such that there exists some \(gp\) with \((f_S, -gp) \in \mathcal{V}_{SP}, (gp, h_Q) \in \mathcal{V}_{PQ}\).

The dot product of \(f_S, g_S\) is denoted by \((f_S, g_S)\) and is defined to be \(\sum_{e \in S} f(e)g(e)\).

The complementary orthogonal space to \(\mathcal{V}_S\) is denoted by \(\mathcal{V}_S^\perp\) and is defined to be \(\{g_S : (f_S, g_S) = 0, f_S \in \mathcal{V}_S\}\).

The two basic results (\([30]\)) are as follows.
The implicit inversion theorem states that the linkage equation

\[ V_{SP} \leftrightarrow V_{PQ} = V_{SQ}, \]

with specified \( V_{SP}, V_{SQ} \), but \( V_{PQ} \) as unknown, has a solution iff \( V_{SP} \circ S \supseteq V_{SQ} \circ S, V_{SP} \times S \subseteq V_{SQ} \times S \) and, further, under the additional conditions \( V_{SP} \circ P \supseteq V_{PQ} \circ P, V_{SP} \times P \subseteq V_{PQ} \times P \), it has a unique solution.

IT could be regarded as a generalization of the usual existence-uniqueness result for the solution of the equation \( Ax = b \). In the context of this paper, it is very much more useful.

The implicit duality theorem states that

\[ (V_{SP} \leftrightarrow V_{PQ})^\perp = (V_{SP}' \leftrightarrow V_{PQ}'). \]

IT was a folklore result in electrical network theory probably known informally to G.Kron ([13], [14]). An equivalent result is stated without proof in [1]. It can be regarded as a generalization of the result \((AB)^T = B^T A^T\).

A central theme of topological network theory is that of dealing efficiently with vector spaces of the kind \( V_{SP} \cap V_S \) where \( V_{SP} \) is in some way topological, for instance it could be the direct sum \( V_{SP} \oplus V_{SP'} \) (\( S = S' \cup S'', P = P' \cup P'', S', S'', P', P'', \) being pairwise disjoint), where the two spaces that make up the direct sum are the current and voltage spaces of a graph. The space \( V_S \) would usually have the form \( V_{S_1} \oplus \cdots \oplus V_{S_k} \) where the \( S_i \) are very small (usually of size not more than 10). Topological spaces have the characteristic feature that their contractions and restrictions remain topological. There are powerful ways of dealing with them which use only topology - for instance ‘multiport decomposition’ (see Section 2.3) and ‘topological transformations’ ([31]). The first half of the book [8] deals with these ideas and can be regarded as suggesting the need for implicit linear algebra by bringing out two facts:

- that many practical dynamical systems occur naturally as a composition of linkages, with the more complicated linkages having a topological origin,
- that the topological linkages can be simplified efficiently through topological methods within the ambit of implicit linear algebra.

The present paper also exploits topological ideas but is closer to standard linear algebra in the sense that a primitive implicit spectral theory of generalized operators (defined below) is developed. For a description of these ideas we need to define the notion of copies of sets and copies of collections of vectors on copies of sets. We say sets \( X, X' \) are copies of each other iff they are disjoint and there is a bijection, usually clear from the context, mapping \( e \in X \) to \( e' \in X' \). We need this operation in order to talk, for instance, of the vector \((v, i)\) where \( v \) is a voltage vector on the edge set of a graph while \( i \) is a current vector on the same set. We handle this by building a copy \( E' \) of the edge set \( E \) and say \( v \) is on \( E \) and \( i \) is on \( E' \). Let \( A, A' \) be two sets which are copies of each other and let \( e' \in A' \) denote the copy of \( e \in A \). We say vectors \( f_A, f_{A'} \) are copies of each other iff we have \( f_A(e) = f_{A'}(e'), e \in A \). By \((V_A)_{A'}\) we mean the copy of \( V_A \) obtained by collecting copies \( f_{A'} \) of \( f_A \in V_A \).

While there is no direction to interaction in a linkage, to deal with operators implicitly we have to bring in such direction. A generalized dynamical system \( V_{W \dot{W}}:M \) is on the set \( W \cup \dot{W} \cup M \), where \( \cup \) denotes disjoint union, \( W, \dot{W} \) are disjoint copies of each other and \( M \) is a set disjoint from \( W, \dot{W} \); intended to take care of manifest (visible) variables. A generalized autonomous system (genaut) \( V_{W \dot{W}} \) is on the set \( W \cup \dot{W} \). It is called a generalized operator (genop) if, additionally, it satisfies the conditions

\[ (V_{W \dot{W}} \circ W)_{\dot{W}} \supseteq V_{W \dot{W}} \circ W, \quad (V_{W \dot{W}} \times W)_{\dot{W}} \supseteq V_{W \dot{W}} \times \dot{W} \]

An ‘ordinary’ operator \( A \) which takes \( w^T \) to \( \dot{w}^T \) through \( \dot{w}^T = w^T A \) can be treated as the collection of all \((w^T, \dot{w}^T)\) which satisfy the equation and can be seen to be a genop.

Genauts and genops differ from ordinary operators in the following respects.
The domain for an operator can be regarded as $F_W$, the collection of all vectors on $W$. For the more general case of a genaut, the role of the domain is played by $\mathcal{V}_{W^W} \circ W$. In the case of an operator, 0 maps to 0. In the more general case of a genaut, 0 is linked to $\mathcal{V}_{W^W} \times \hat{W}$.

In the case of an operator, the range is a subspace of the domain. The analogous idea in the case of the genop is the condition $(\mathcal{V}_{W^W} \circ W)_{\hat{W}} \supseteq \mathcal{V}_{W^W} \circ \hat{W}$.

In the case of an operator, 0 maps to 0. The analogous idea in the case of the genop is $(\mathcal{V}_{W^W} \times W)_{\hat{W}} \supseteq \mathcal{V}_{W^W \times \hat{W}}$. This has essentially the same power as 0 mapping to 0.

Most controllability-observability results can be stated in terms of genauts which satisfy one of the two conditions that make up a genop.

An upper semi genop (USG) $\mathcal{V}_{W^W}$ satisfies $(\mathcal{V}_{W^W} \circ W)_{\hat{W}} \supseteq \mathcal{V}_{W^W} \circ \hat{W}$, while a lower semi genop (LSG) $\mathcal{V}_{W^W}$ satisfies $(\mathcal{V}_{W^W} \times W)_{\hat{W}} \supseteq \mathcal{V}_{W^W} \times \hat{W}$.

For instance, if we start with a dynamical system defined by state equations and keep input and output free, then we would get a USG, while if we set both input and output to zero, then we would get an LSG.

Practically everything that needs to be done with operators computationally can be done with genops, but with the added advantage that things can be done implicitly, exploiting, for instance, topology in the case of an electrical network. One can do all computations implicitly with systems of differing numbers of dynamical variables. They can also be built implicitly in cases like this.

As an illustration of the power of implicit linear algebra we define emulators for dynamical systems and genauts. We say $\mathcal{V}$ plays fundamental roles. We show how to deal with these ideas implicitly using genauts and genops.

Operators are treated as genops, their annihilation agrees with the generalized definition.

Polynomials of ordinary operators - for instance, there is a unique minimal annihilating polynomial. Here we say $p(s)$ annihilates $\mathcal{V}$ iff $p(\mathcal{V}_{W^W})$ is decoupled, i.e., is of the form $\mathcal{V}^1_{W^W} \oplus \mathcal{V}^2_{W^W}$. As is required, when ordinary operators are treated as genops, their annihilation agrees with the generalized definition.

In control theory, controllability, observability, pole placement through state feedback, output injection play fundamental roles. We show how to deal with these ideas implicitly using genauts and genops.

As an illustration of the power of implicit linear algebra we define emulators for dynamical systems and genauts. We say $\mathcal{V}$ are emulators of each other if there are linkages $\mathcal{V}^1_{WP}, \mathcal{V}^2_{W'P}$ such that $\mathcal{V}_{WP} \leftrightarrow \mathcal{V}^1_{W'M} \leftrightarrow \mathcal{V}^2_{W'P}$. We note that each of $\mathcal{V}^1_{WP}, \mathcal{V}^2_{W'P}$ would usually be written as an expression involving other more basic linkages associated for instance with elementary dynamical systems and graphs linking them. The pair of linkages $\mathcal{V}_{WP}, \mathcal{V}^2_{W'P}$ behave like a similarity transformation but have greater flexibility in dealing implicitly with systems of differing numbers of dynamical variables. They can also be built implicitly in linear time using purely topological methods in the case of electrical networks. One can do all computations associated with control including feedback, pole placement, observer building etc. using emulators. This
approach can be regarded as being consistent with the point of view of behaviourists ([4], [5]) while retaining the computational power of the state variable approach. The theory developed yields a unified description of both standard linear dynamical systems and linear singular systems (or linear descriptor systems) (see for example, [2], [3]). There is an additional simplification over standard linear algebra- we deal only with subspaces which arise through operations of the kind $\mathcal{V}_{SP} \leftrightarrow \mathcal{V}_P$, sums and intersections and not with quotient spaces.

Throughout, the theory that we build respects duality perfectly. At a primitive level, one may take the dual of a linkage $\mathcal{V}_{AB}$ to be $\mathcal{V}_{AB}^\perp$. If one wants the analogy with standard linear algebra stronger we could define the transpose $\mathcal{V}_{AB}^T$ to be $(\mathcal{V}_{AB}^A)^{-}\mathcal{V}_{AB}$, where this latter space is obtained by changing every $(f_A, f_B')$ in $\mathcal{V}_{AB}^\perp$ to $(-f_A, f_B')$. It will then turn out by IDT, that

$$(\mathcal{V}_{AB} \leftrightarrow \mathcal{V}_{BC})^T = \mathcal{V}_{AB}^T \leftrightarrow \mathcal{V}_{BC}^T,$$

$$(\mathcal{V}_{W\hat{V}}^1 + \mathcal{V}_{W\hat{V}}^2)^T = (\mathcal{V}_{W\hat{V}}^1)^T + \mathcal{V}_{W\hat{V}}^2; \quad (\lambda \mathcal{V}_{W\hat{V}})^T = \lambda^T \mathcal{V}_{W\hat{V}}.$$

The adjoints of dynamical systems are defined through similar ideas and we get the usual controllability-observability duality.

We now present an outline of this paper.

Section 2 is on preliminary definitions and results. Among others, matched and skewed compositions are defined. An important role is played by the operations of building copies, of sets and of vector spaces on copies of index sets, in increasing the effectiveness of these operations. A very general version of the implicit inversion theorem (IIT) is described with its proof. The implicit duality theorem (IDT) is stated and proved. A minimal set of definitions from graph theory required for this paper is presented. Multiport decomposition is described along with an algorithm for minimal decomposition.

Section 3 presents definitions on linkages. A simple example that relates IIT to standard existence and uniqueness of solution of linear equations is given. It is also shown how to make the ‘$\leftrightarrow$’ operation associative by the judicious use of copies of index sets. A natural variation (pseudoidentity) of the notion of identity is presented. The special case of two block linkages is described and the notion of transpose derived. A very general version of the intersection-sum operation over matched composition and scalar multiplication is presented. This result is true under certain conditions which are stated. Fortunately, these are sufficient for defining factorisation of polynomials of genops later in Section 8.

Section 4 presents basic definitions about dynamical systems such as regular dynamical systems, generalized autonomous systems (genauts), generalized operators (genops). The ideas are illustrated using an electrical circuit with resistors, capacitors, inductors and sources.

Section 5 describes the construction of dual statements to a given statement of the form

$$e(\mathcal{V}_1, \ldots, \mathcal{V}_k, +, \cap, \cap, \cap, \times, \leftrightarrow, \cap, \supseteq, \subseteq, =).$$

The adjoint of a dynamical system is defined and a basic result on adjoints is proved.

Section 6 describes conditioned and controlled invariant subspaces of a genaut. The duality between the two subspaces is brought out. It is shown that if we start with a USG $\mathcal{V}_{W\hat{V}}^u$, and a conditioned invariant subspace $\mathcal{V}_W$ in it, then $\mathcal{V}_{W\hat{V}}^u + \mathcal{V}_W$ is a genop. Dually if we start with a LSG $\mathcal{V}_{W\hat{V}}^l$, and a controlled invariant subspace $\mathcal{V}_W$ in it, then $\mathcal{V}_{W\hat{V}}^l \cap \mathcal{V}_W$ is a genop. These genops are analogous to uncontrollable and unobservable spaces respectively.

5
Section 7 is on \(wm_u\)–feedback and \(m_y \dot{w}\)–injection. These are analogues of state feedback and output injection in our framework. We prove that the two notions are dual to each other and give necessary and sufficient conditions for a genop \(V_{W_{\dot{w}}}\) to be obtainable from a genaut \(V'_{W_{\dot{w}}}\) by \(wm_u\)–feedback or \(m_y \dot{w}\)–injection.

Section 8 is on polynomials of genops. These are defined in general for genauts but for genops we show that the minimal annihilating polynomial is unique. Here annihilation is interpreted as resulting in a space of the kind \(V_{\dot{w}} \oplus V_{\ddot{w}}^2\). Proceeding analogously to multivariable control theory, given a USG \(V'_{W_{\dot{w}}}\), we determine what polynomials can be annihilating polynomials of a genop \(V_{W_{\dot{w}}} \subseteq V'_{W_{\dot{w}}}\) that satisfies \(V'_{W_{\dot{w}}} \circ W = V_{W_{\dot{w}}} \circ W\). We also state the dual and indicate its proof.

Section 9 is a description of the usual pole placement theory and algorithm in our framework. When the desired annihilating polynomial \(p(s)\) satisfies conditions derived in Section 8, we solve the problem of constructing state feedback and output injection, which, when imposed on the original dynamical system, result in a system with \(p(s)\) as its annihilating polynomial. In Appendix D, the algorithms of this section have been recast in a ‘line by line dualizable form’. The rule is simply to work only with vector spaces (not with vectors), avoid the ‘belongs to’ relation and use ‘contained in’ instead. In this case the vectors are converted to one dimensional subspaces and their duals to \(|−1| 1\) dimensional subspaces.

Section 10 is on emulators which have been defined earlier in this section. The idea is motivated through an example on linear dynamical circuits. The linear time topological procedure of multiport decomposition when applied to a capacitor + inductor + static circuit (RLC circuit) is shown to yield an emulator. Theorem 74 shows that if \(V_{W_{\dot{w}}}\), \(V_{\dot{w}p}\) are emulators of each other, so are \(p(V_{W_{\dot{w}}}), p(V_{\dot{w}p})\), provided the polynomial \(p(s)\) has no constant term. Thus if \(p(s)\) annihilates one of them, it will also annihilate the other. The ‘no constant term’ condition is shown to be easy to get around, since it means merely that eigenvectors corresponding to zero eigenvalues have to be handled separately. Theorem 70 shows that adjoints of emulators can be obtained by constructing emulators for the original dynamical system. Theorem 75 shows that invariant space computations can be performed on an emulator and the results transferred to the original space. Theorem 77 repeats this in the case of controllability-observability and Theorems 75–51 respectively, for state feedback and output injection.

Appendix A discusses the computation of basic operations explicitly and implicitly. The operations considered include vector space sum, vector space intersection and the \(\leftrightarrow\) operation. Appendix D has been described a couple of paragraphs earlier. Appendix E discusses, through an example, how to build an emulator implicitly for an RLC circuit using multiport decomposition. Appendix F discusses, through an example, the construction of the adjoint of an RLC circuit and the adjoint of its multiport decomposition based emulator.

In addition, the appendices also contain some routine proofs of theorems stated in the main body of the paper.

2. Preliminaries

The preliminary results and the notation used are from [8] (open 2nd edition available at [9]) and more specifically from [12]. A vector \(f\) on \(X\) over \(\mathbb{F}\) is a function \(f : X \to \mathbb{F}\) where \(\mathbb{F}\) is a field. In this paper we work primarily with the real field. When \(X, Y\) are disjoint, \(X \uplus Y\) denotes the disjoint union of \(X\) and \(Y\). A vector \(f_{X \uplus Y}\) on \(X \uplus Y\) would be written as \(f_X\) and would often be written as \((f_X, f_Y)\) during operations dealing with such vectors. The sets on which vectors are defined will always be finite. When a vector \(x\) figures in an equation, we will use the convention that \(x\) denotes a column vector and \(x^T\) denotes a row vector such as in \(Ax = b, x^TA = b^T\). Let \(f_Y\) be a vector on \(Y\) and let \(X \subseteq Y\). Then the restriction of \(f_Y\) to \(X\) is defined as follows:

\[
f_Y/\mathcal{X} \equiv g_X, \text{ where } g_X(e) = f_Y(e), \quad e \in X.
\]
When \( f \) is on \( X \) over \( \mathbb{F} \), \( \lambda \in \mathbb{F} \) then \( \lambda f \) is on \( X \) and is defined by \( (\lambda f)(e) \equiv \lambda[f(e)], \ e \in X \). When \( f \) is on \( X \) and \( g \) on \( Y \) and both are over \( \mathbb{F} \), we define \( f + g \) on \( X \cup Y \) by

\[
(f + g)(e) \equiv \begin{cases} 
  f(e) + g(e), & e \in X \cap Y \\
  f(e), & e \in X \setminus Y \\
  g(e), & e \in Y \setminus X.
\end{cases}
\]

When \( X \cap Y = \emptyset \) then \( f_X + g_Y \) is written as \( f_X \oplus g_Y \) or as \( (f_X, g_Y) \). When \( f, g \) are on \( X \) over \( \mathbb{F} \) the dot product \( \langle f, g \rangle \) of \( f \) and \( g \) is defined by

\[
\langle f, g \rangle \equiv \sum_{e \in X} f(e)g(e).
\]

We say \( f, g \) are orthogonal if \( \langle f, g \rangle = 0 \).

An arbitrary collection of vectors on \( X \) with \( 0_X \) as a member would be denoted by \( K_X \). \( K \) on \( X \) is a vector space iff \( f, g \in K \) implies \( \lambda f + \sigma g \in K \) for \( \lambda, \sigma \in \mathbb{F} \). We will use the symbol \( \mathcal{V}_X \) for vector space on \( X \) as opposed to \( K_X \) for arbitrary collections of vectors on \( X \) with a zero vector as a member. The symbol \( \mathcal{F}_X \) refers to the collection of all vectors on \( X \) and \( 0_X \) to the zero vector space on \( X \) as well as the zero vector on \( X \).

When the index set is clear from the context, to improve readability, we sometimes represent a vector space as \( \{[K]\} \) or as \( \{Kx = 0\} \). In the former case the vector space referred to is the row space of \( K \) and in the latter case, it is the solution space of \( Kx = 0 \).

When \( X, Y \) are disjoint we usually write \( K_{XY} \) in place of \( K_{X\cup Y} \). The collection \( \{(f_X, \lambda f_Y) : (f_X, f_Y) \in K_{XY}\} \) is denoted by \( K_{X(\lambda Y)} \). When \( \lambda = -1 \) we would write more simply \( K_{X(-Y)} \). Observe that \( K_{X(-Y)}(X(-Y)) = K_{XY} \).

### 2.1. Basic operations

The basic operations we use in this paper are as follows:

#### 2.1.1. Building Copies

An operation that occurs often during the course of this paper is that of building copies of sets and copies of collections of vectors on copies of sets. We say set \( X \), \( X' \) are copies of each other iff they are disjoint and there is a bijection, usually clear from the context, mapping \( e \in X \) to \( e' \in X' \).

When \( X, X' \) are copies of each other, the vectors \( f_X \) and \( f_{X'} \) are said to be copies of each other, i.e., \( f_{X'}(e') = f_X(e) \). If the vectors on \( X \) and \( X' \) are not copies of each other, they would be distinguished using notation, such as, \( f_X, \hat{f}_{X'} \), etc. Vectors without subscripts like, \( x, \hat{x} \) and \( w, \hat{w} \) are not necessarily copies of each other.

When \( X \) and \( X' \) are copies of each other, the collections of vectors \( K_X, K_{X'} \) always represent copies of each other, i.e.,

\[
K_{X'} \equiv \{f_{X'} : f_{X'}(e') = f_X(e), f_X \in K_X \}.
\]

This holds also for vector spaces \( \mathcal{V}_X, \mathcal{V}_{X'} \). If they are not copies they would be clearly distinguished from each other by the notation, for instance, \( K_X, \hat{K}_{X'}, \mathcal{V}_X, \hat{\mathcal{V}}_{X'}, \) etc.

When \( X \) and \( X' \) are copies of each other, the notation for interchanging the positions of variables \( X \) and \( X' \) in a collection \( K_{XX'Y} \) is given by \( (K_{XX'Y})_{X'XY} \), that is

\[
(K_{XX'Y})_{X'XY} \equiv \{ (g_X, f_{X'}, h_Y) \mid (f_X, g_{X'}, h_Y) \in K_{XX'Y}, g_X \text{ being copy of } g_{X'}, f_{X'} \text{ being copy of } f_X \}.
\]

When \( P, P' \) are copies of each other, \( \mathcal{F}_P \) is defined to be the vector space \( \{(f_P, f'_P) : f_P \in \mathcal{F}_P \} \).
2.1.2. Sum and Intersection

Let $K_X, K_Y$ be collections of vectors on sets $X, Y$ respectively. The sum $K_X + K_Y$ of $K_X, K_Y$ is defined over $X \cup Y$ as follows:

$$K_X + K_Y \equiv \{(fx, 0_{Y \setminus X}) + (0_{X \setminus Y}, fy) \mid f_x \in K_X, f_y \in K_Y\},$$

When $X, Y$ are disjoint, $K_X + K_Y$ is usually written as $K_X \oplus K_Y$ and is called the direct sum. Thus,

$$K_X + K_Y \equiv (K_X \oplus 0_{Y \setminus X}) + (0_{X \setminus Y} \oplus K_Y).$$

The intersection $K_X \cap K_Y$ of $K_X, K_Y$ is defined over $X \cup Y$ as follows:

$$K_X \cap K_Y \equiv \{fx \cap fy \mid fx \in K_X, fy \in K_Y, x_{Y \setminus X}, y_{X \setminus Y}\},$$

are arbitrary vectors on $Y \setminus X, X \setminus Y$ respectively.

Thus,

$$K_X \cap K_Y \equiv (K_X \oplus F_{Y \setminus X}) \cap (F_{X \setminus Y} \oplus K_Y).$$

2.1.3. Matched and Skewed Composition

The matched composition $K_X \leftrightarrow K_Y$ is on $(X \setminus Y) \cup (Y \setminus X)$ and is defined as follows:

$$K_X \leftrightarrow K_Y \equiv \{f : f = (g_{X \setminus Y}, h_{Y \setminus X}) \mid g \in K_X, h \in K_Y, g_{X \cap Y} = h_{Y \cap X}\}.$$

Matched composition is referred to as matched sum in [S]. In the special case where $Y \subseteq X$, matched composition is called generalized minor operation (generalized minor of $K_X$ with respect to $K_Y$).

The skewed composition $K_X \Rightarrow K_Y$ is on $(X \setminus Y) \cup (Y \setminus X)$ and is defined as follows:

$$K_X \Rightarrow K_Y \equiv K_{(X \setminus Y) \setminus (X \cap Y)} \leftrightarrow K_Y$$

$$= \{f : f = (g_{X \setminus Y}, h_{Y \setminus X}) \mid g \in K_X, h \in K_Y, g_{X \cap Y} = h_{Y \cap X}\}.$$

When $X, Y$ are disjoint, the matched and skewed composition both correspond to direct sum. The generalized minor of $K_{XY}$ relative to $K_Y$ is $K_{XY} \leftrightarrow K_Y$. When $K_{XY}, K_Y$ are vector spaces, observe that $K_{XY} \leftrightarrow K_Y = K_{XY} \leftarrow K_Y$. The operations $K_{XY} \leftrightarrow F_{Y}, K_{XY} \leftrightarrow 0_{Y}$ are called the restriction and contraction of $K_{XY}$ and are also denoted by $K_{XY} \circ X, K_{XY} \times X$, respectively. Here again $K_{XYZ} \circ XY, K_{XYZ} \times XY$, respectively when $X, Y, Z$ are pairwise disjoint, would denote $K_{XYZ} \circ Y, K_{XYZ} \times Y$.

2.1.4. Vector Space Results

If the collections of vectors, which go to make up the expression, are all closed under addition, it is clear that $+, \cap, \leftrightarrow, =$, yield collections which are closed under addition. It is also clear that $+, \cap, \leftrightarrow, =$, all yield vector spaces when they operate on vector spaces.

If $K$ is on $X$, then $K^\perp$ is defined by

$$K^\perp = \{g : \langle f, g \rangle = 0, f \in K\}.$$

Clearly $K^\perp$ is a vector space whether or not $K$ is. When $V$ is a vector space on a finite set $S$, it can be shown that $(V^\perp)^\perp = V$. This is fundamental for the results of the present work. The following results are easy to see

$$(V_X + \hat{V}_X^\perp)^\perp = V_X^\perp \cap \hat{V}_X^\perp, \quad X \text{ finite}$$

$$(V_X \cap \hat{V}_X^\perp)^\perp = V_X^\perp + \hat{V}_X^\perp, \quad X \text{ finite}.$$
2.1.5. Results on Generalized Minor

The above pair of results will be referred to as the dot-cross duality by the definition of intersection of vector spaces on two distinct sets.

When $X, Y$ are disjoint, it is easily verified that $(\mathcal{V}_X \oplus \mathcal{V}_Y) = \mathcal{V}_X^\perp + \mathcal{V}_Y^\perp$. When $X, Y$ are not disjoint, $\mathcal{V}_X + \mathcal{V}_Y = \mathcal{V}_X + \mathcal{V}_Y$. So

\[
(\mathcal{V}_X + \mathcal{V}_Y)^\perp = (\mathcal{V}_X^\perp + \mathcal{V}_Y^\perp) \cap (\mathcal{V}_Y^\perp + \mathcal{V}_X^\perp)
\]

by the definition of intersection of vector spaces on two distinct sets.

Let $\mathcal{V}$, we have $(\mathcal{V}_X \cap \mathcal{V}_Y)^\perp = \mathcal{V}_X^\perp + \mathcal{V}_Y^\perp$.

The following results can also be easily verified:

Using $(\mathcal{V}^\perp)^\perp = \mathcal{V}$, we have $(\mathcal{V}_X \cap \mathcal{V}_Y)^\perp = \mathcal{V}_X^\perp + \mathcal{V}_Y^\perp$.

The results in this subsection were originally derived in \[7, 30, 31\]. A comprehensive account is in \[8\].

The above pair of results will be referred to as the dot-cross duality.

2.1.5. Results on Generalized Minor

The results in this subsection were originally derived in \[7, 30, 31\]. A comprehensive account is in \[8\]. Let $X, Y$ and $Z$ be disjoint sets, then

\[
(\mathcal{V}_{XY} \leftrightarrow \mathcal{V}_X) \leftrightarrow \mathcal{V}_Y = (\mathcal{V}_{XY} \leftrightarrow \mathcal{V}_Y) \leftrightarrow \mathcal{V}_X = \mathcal{V}_{XZ} \leftrightarrow (\mathcal{V}_X \leftrightarrow \mathcal{V}_Y).
\]

When $\mathcal{V}_X \equiv \mathbf{0}_X, \mathcal{V}_Y \equiv \mathcal{F}_Y$, the above reduces to

\[
\mathcal{V}_{XZ} \times \mathcal{V}_Z = \mathcal{V}_{XZ} \circ \mathcal{V}_Z.
\]

The next lemma is a slightly modified version of a result (Problem 7.5) in \[8\].

**Lemma 1.**

1. Let $K_{SP}, K_{SQ}$ be collections of vectors on $S \uplus P, S \uplus Q$ respectively.

Then there exists a collection of vectors $K_{PQ}$ on $P \uplus Q$ s.t. $0_{PQ} \in K_{PQ}$ and $K_{SP} \leftrightarrow K_{PQ} = K_{SQ}$, only if $K_{SP} \circ S \supseteq K_{SQ} \circ S$ and $K_{SP} \times S \subseteq K_{SQ} \times S$.

2. Let $K_{SP}$ be a collection of vectors closed under subtraction on $S \uplus P$ and let $K_{SO}$ be a collection of vectors on $S \uplus Q$, closed under addition.

Further let $K_{SP} \times S \subseteq K_{SQ} \times S$ and $K_{SP} \circ S \supseteq K_{SQ} \circ S$.

Then the collection of vectors $K_{SP} \leftrightarrow K_{SO}$ is closed under addition, with $0_{PQ}$ as a member and further we have that $K_{SP} \leftrightarrow (K_{SP} \leftrightarrow K_{SQ}) = K_{SQ}$.

3. Let $K_{SP}$ be a collection of vectors closed under subtraction, and let $K_{SQ}$ satisfy the conditions, closure under addition, $0_{SQ} \in K_{SQ}, K_{SP} \times S \subseteq K_{SQ} \times S$ and $K_{SP} \circ S \supseteq K_{SQ} \circ S$.

Then the equation

\[
K_{SP} \leftrightarrow K_{PQ} = K_{SQ},
\]

where $K_{PQ}$ has to satisfy closure under addition, has a unique solution under the condition

$K_{SP} \circ P \subseteq K_{PQ} \circ P$ and $K_{SP} \circ P \supseteq K_{PQ} \circ P$.

If the solution $K_{PQ}$ does not satisfy these conditions, then there exists another solution, i.e.,

$K_{SP} \leftrightarrow K_{SQ}$.

**Proof.**

1. Suppose $K_{SP} \leftrightarrow K_{PQ} = K_{SQ}$ and $0_{PQ} \in K_{PQ}$.

It is clear from the definition of the matched composition operation that $K_{SP} \circ S \supseteq K_{SQ} \circ S$.

Since $0_{PQ} \in K_{PQ}$, if $f_S \oplus 0 P \in K_{SP}$, we must have that $f_S \oplus 0 P \in K_{SQ}$.

Thus, $K_{SP} \times S \subseteq K_{SQ} \times S$. 

9
2. On the other hand suppose \( K_{SP} \times S \subseteq K_{SQ} \times S \) and \( K_{SP} \circ S \supseteq K_{SQ} \circ S \).
Let \( K_{PQ} \equiv K_{SP} \leftrightarrow K_{SQ} \), i.e., \( K_{PQ} \) is the collection of all vectors \( f_p \oplus f_q \) s.t. for some vector \( f_s \), \( f_s \oplus f_q \in K_{SQ}, f_s \oplus f_p \in K_{SP} \).
Since \( K_{SP} \) is closed under subtraction, it contains the zero vector, the negative of every vector in it and is closed under addition.
Since \( 0 \oplus 0 \in K_{SP} \), we must have that \( 0 \in K_{SP} \times S \) and therefore \( 0 \in K_{SQ} \times S \). It follows that \( 0 \oplus 0 \in K_{SQ} \).

Remark 1. We note that the collections of vectors in Lemma 1 can be over rings rather than over fields—
in particular over the ring of integers. Also only \( K \) has to be closed over subtraction. The other two collections \( K_{PQ}, K_{SQ} \) are only closed over addition with a zero vector as a member. In particular \( K_{SP} \) could be a vector space over rationals while \( K_{PQ}, K_{SQ} \) could be cones over rationals. In all these cases the proof would go through without change.

The following theorem is a simple consequence. We will call this the implicit inversion theorem (IIT).

**Theorem 2.** Consider the equation \( V_{SP} \leftrightarrow V_{PQ} = V_{SQ} \). Then

1. given \( V_{SP}, V_{SQ}, \exists V_{PQ} \), satisfying the equation iff \( V_{SP} \circ S \supseteq V_{SQ} \circ S \) and \( V_{SP} \times S \subseteq V_{SQ} \times S \);
2. given \( V_{SP}, V_{PQ}, V_{SQ} \) satisfying the equation, we have \( V_{SP} \leftrightarrow V_{SQ} = V_{PQ} \) iff \( V_{SP} \circ P \subseteq V_{PQ} \circ P \) and \( V_{SP} \times P \subseteq V_{PQ} \times P \);
3. given \( V_{SP}, V_{SQ} \), assuming that the equation \( V_{SP} \leftrightarrow V_{PQ} = V_{SQ} \) is satisfied by some \( V_{PQ} \) it is unique under the condition \( V_{SP} \circ P \supseteq V_{PQ} \circ P \) and \( V_{SP} \times P \subseteq V_{PQ} \times P \).


It can be shown that the special case where \( Q = \emptyset \) is equivalent to the above result. For convenience we state it below.

**Theorem 3.** Let \( V_S = V_{SP} \leftrightarrow V_P \). Then, \( V_P = V_{SP} \leftrightarrow V_S \) iff \( V_{SP} \circ P \supseteq V_P \) and \( V_{SP} \times P \subseteq V_P \).
2.1.6. Implicit Duality Theorem

From the definition of matched composition, when \((X,Y,Z)\) are disjoint,
\[
\mathcal{V}_{XY} \leftrightarrow \mathcal{V}_{YZ} = (\mathcal{V}_{XY} + \mathcal{V}_{(-Y)Z}) \times (X \cup Z)
\]
and also equal to
\[
(\mathcal{V}_{XY} \cap \mathcal{V}_{YZ}) \circ (X \cup Z).
\]
Similarly from the definition of skewed composition,
\[
\mathcal{V}_{XY} \Rightarrow \mathcal{V}_{YZ} = (\mathcal{V}_{XY} + \mathcal{V}_{YZ}) \times (X \cup Z)
\]
and also equal to
\[
(\mathcal{V}_{XY} \cap \mathcal{V}_{(-Y)Z}) \circ (X \cup Z).
\]
Hence we have
\[
(\mathcal{V}_{XY} \leftrightarrow \mathcal{V}_{YZ})^\perp = [(\mathcal{V}_{XY} + \mathcal{V}_{(-Y)Z}) \times (X \cup Z)]^\perp
\]
\[
= (\mathcal{V}_{XY} + \mathcal{V}_{(-Y)Z}) \circ (X \cup Z)
\]
\[
= (\mathcal{V}_{XY} \cap \mathcal{V}_{(-Y)Z}) \circ (X \cup Z)
\]
\[
= \mathcal{V}_{XY} \cap \mathcal{V}_{(-Y)Z}
\]
In particular,
\[
(\mathcal{V}_{XY} \leftrightarrow \mathcal{V}_{Y})^\perp = \mathcal{V}_{XY}^\perp \leftrightarrow \mathcal{V}_{Y}^\perp
\]
since \(\mathcal{V}_{Y} = \mathcal{V}_{(-Y)}\). To summarize

**Theorem 4.** \((\mathcal{V}_{XY} \leftrightarrow \mathcal{V}_{YZ})^\perp = \mathcal{V}_{XY}^\perp \leftrightarrow \mathcal{V}_{YZ}^\perp\).

The above result will be referred to as the **implicit duality theorem** (IDT).

Observe that the dot-cross duality is also a consequence of the implicit duality theorem since
\[
(\mathcal{V}_{XY} \times X)^\perp = (\mathcal{V}_{XY} \times 0_X)^\perp = \mathcal{V}_{XY}^\perp \times \mathcal{F}_X = \mathcal{V}_{XY}^\perp \circ X.
\]

Implicit duality theorem and its applications are dealt with in detail in [30], [31], [7], [8]. There has been recent interest in the applications of this result in [32], in the context of ‘Pontryagin duality’. The above proof is based on the one in [7]. Versions for other contexts (such as orthogonality being replaced by polarity, or by the constraint of dot product being an integer) are available in [8], for operators in [10], [11], for matroids in [15].

Computational techniques for the basic operations are discussed in Appendix A.

2.2. Graphs

The motivation for the ideas in this paper arose from the attempt to understand the topological processes of electrical circuit theory and exploit them efficiently. So we require a few definitions from graph theory to state results from electrical networks. We follow [8].

An **undirected graph** is a triple \((V,E,f^u)\), where \(V\) is the set of **vertices**, \(E\) is the set of **edges**, and \(f^u\) is the **incidence function** which associates a pair of vertices with each edge. The incidence function defines the end vertices of the edges.

Similarly, a **directed graph** is also a triplet \((V,E,f^d)\), where \(f^d\) is the **incidence function** which associates with each edge an “ordered pair” of vertices and the sets \(V, E\) define the **vertices, edges**,
respectively of the graph. The incidence function defines the end vertices and also the direction of arrow for the edges.

An undirected path (of a graph) from vertex \( v_1 \) to vertex \( v_k \) is a disjoint alternating vertex-edge sequence \( v_1, e_1, v_2, e_2, \ldots, e_{(k-1)}, v_k \), such that every edge \( e_\ell \) is incident on vertices \( v_\ell \) and \( v_{\ell+1} \). When it is clear from the context, a path is simply denoted by its edge sequence. A graph is said to be connected, if there exists an undirected path between every pair of nodes. Otherwise it is said to be disconnected. A disconnected graph has connected components which are individually connected with no edges between the components.

A loop (or a circuit) (of any graph) is an undirected path in which the starting and ending vertices are the same and no other vertices or edges are repeated.

A tree of a graph is a sub-graph of the original graph with no loops. The edges of a tree are called branches. A spanning tree is a maximal tree with respect to the edges of a graph. Hence, the set obtained by adding any other edge of the graph to a spanning tree contains a (single) loop. For this reason, a spanning tree is also called maximal circuit free set. The loops obtained in this manner are called fundamental circuits associated with the tree.

It can be verified that every spanning tree of a connected graph with \( n \) nodes consists of \( n - 1 \) edges. Since addition of each edge to a spanning tree creates only one loop, the number of fundamental circuits (associated with a spanning tree) is \( e - n + 1 \), where \( e \) is the number of edges and \( n \) the number of vertices of the graph.

A cotree of a graph is defined with respect to a spanning tree. It consists of all the edges of the graph which are not in the spanning tree. The edges of a cotree are called links.

A forest of a disconnected graph is a disjoint union of the spanning trees of its connected components. The complement of a forest is called coforest. In this paper, the terms tree and cotree will be used to mean forest and coforest when it is clear from the context.

The number of edges in a forest of a graph is called the rank of the graph. For a graph \( G \) it is denoted by \( r(G) \).

A crossing edge set of a graph is the set of all edges which lie between two complementary subsets of the vertex set of the graph.

A cutset is a minimal crossing edge set, i.e., a minimal subset which when deleted from the graph increases the count of connected components by one.

A spanning tree of the graph can be used to systematically generate cutsets. Since in a spanning tree of a connected graph there exists only one path between any two vertices, deletion of a branch from the tree disconnects the tree into two components. The set of all edges in the graph, between these two components of the tree, forms a cutset of the graph. Since a spanning tree of a connected graph with \( n \) vertices contains \( n - 1 \) edges, one could associate \( n - 1 \) cutsets to it. The cutsets obtained in this manner are called fundamental cutsets of the graph with respect to the tree.

In a graph, an edge set \( E_1 \) is said to span another edge set \( E_2 \) if for each \( e_2 \in E_2 \), there exists a circuit \( L_1 \subseteq e_2 \cup E_1 \) with \( e_2 \in L_1 \). For example, a spanning tree of any graph spans the cotree of the same graph. Dually, an edge set \( E_1 \) is said to cospan another edge set \( E_2 \) if for each \( e_2 \in E_2 \), there exists a cutset \( C_1 \subseteq e_2 \cup E_1 \) with \( e_2 \in C_1 \). For instance, the cotree with respect to a spanning tree of any graph cospans the same spanning tree of the graph.

Let \( G \) be a graph and \( E \equiv E(G) \) be the edge set of \( G \) and \( T \subseteq E \). Then \( G \times (E - T) \) denotes the graph obtained by removing the edges \( T \) from \( G \) and fusing the end vertices of the removed edges. \( G \circ (E - T) \) denotes the graph obtained by removing the edges \( T \) from \( G \) and removing the isolated vertices. (Note that \( \times, \circ \) are also used to denote vector space operations. However, the context would make clear whether the objects involved are graphs or vector spaces.)

We refer to the space of vectors \( v_E \), which satisfy Kirchhoff's Voltage Law (KVL) of the graph \( G \), by \( \mathcal{V}^v(G) \) and to the space of vectors \( i_E \), which satisfy Kirchhoff's Current Law (KCL) of the graph \( G \), by \( \mathcal{V}^i(G) \).

Tellegen’s Theorem \( [8] \) states that \( \mathcal{V}^v(G) = \mathcal{V}^i(G)^\perp \). The following result on vector spaces associated
with graphs is useful.

\[ \forall^v(G \circ T) = \forall^v(G) \circ T, \quad \forall^v(G \times T) = \forall^v(G) \times T, \quad T \subseteq E(G); \]

\[ \forall^i(G \circ T) = \forall^i(G) \circ T, \quad \forall^i(G \times T) = \forall^i(G) \circ T, \quad T \subseteq E(G). \]

An electrical network \( \mathcal{N} \) is a pair \((G, D)\). Here \( G \) is a directed graph and \( D \) is a collection of pairs of vector functions of time \((v(\cdot), i(\cdot))\), where \( v(t), i(t) \) are vectors on the edge set of the graph. \( D \) is called the ‘device characteristic’ of the network.

A solution of \( \mathcal{N} \) is a pair \((v(\cdot), i(\cdot))\), satisfying

\[ v(t) \in \forall^v(G), \quad i(t) \in \forall^i(G) \quad \text{ (KVL, KCL) and } (v(\cdot), i(\cdot)) \in \mathcal{D}. \]

### 2.3 Topological transformation and multi-port decomposition

There are two important ideas of network analysis, which are essentially notions of implicit linear algebra, but which appear to have no counterparts in classical linear algebra. These are the methods called topological transformation and multiport decomposition (see [30], [31], [8]).

In the method of topological transformation, an electrical circuit is treated as though it has a more convenient topology but with some additional constraints. The idea is to exploit the new topology while meeting the additional constraints. In the language of this paper, we have two vector spaces \( V^1_S, V^2_S \) and we need to find a linkage \( V_{SP} \) and vector spaces \( V^1_P, V^2_P \), such that

\[ V_{SP} \leftrightarrow V^1_P = V^1_S, \quad V_{SP} \leftrightarrow V^2_P = V^2_S, \quad \text{and } |P| \text{ is the minimum possible.} \]

One can show that this minimum size is \( d(V^1_S, V^2_S) \equiv r(V^1_S + V^2_S) - r(V^1_S \cap V^2_S) \). A much harder problem is where \( V^1_S \) is given and \( V^2_S \) belongs to a class of vector spaces on \( S \), closed under sum and intersection, and we have to pick \( V^2_S \) to minimize \( d(V^1_S, V^2_S) \).

In this paper we use only multiport decomposition. A description follows.

Let \( G \) be a directed graph and let \( E_1, E_2 \) be a partition of edges of the graph. Then it can be shown that we can build three graphs \( G_{E_1,P_1}, G_{E_2,P_2}, G_{P_1,P_2} \) such that

\[ V^i(G) = \left( \forall^i(G_{E_1,P_1}) \oplus \forall^i(G_{E_2,P_2}) \right) \leftrightarrow \forall^i(G_{P_1,P_2}) \]

and therefore through Tellegen’s theorem and the implicit duality theorem

\[ \forall^v(G) = \left( \forall^v(G_{E_1,P_1}) \oplus \forall^v(G_{E_2,P_2}) \right) \leftrightarrow \forall^v(G_{P_1,P_2}), \]

where \( P_1, P_2 \) are additional sets of branches. This process is called multi-port decomposition. The two graphs \( G_{E_1,P_1}, G_{E_2,P_2} \) are called multiports and the graph \( G_{P_1,P_2} \) is called the port connection diagram for the multiport decomposition.

Let network \( \mathcal{N} \) be on directed graph \( G \), with a partition \( E_1, E_2 \) of edges of the graph specified such that the device characteristics of \( E_1, E_2 \) are independent in \( \mathcal{N} \). Let \( G_{E_1,P_1}, G_{E_2,P_2}, G_{P_1,P_2} \) be a multiport decomposition of \( G \). Define the networks \( \mathcal{N}_{E_1,P_1}, \mathcal{N}_{E_2,P_2} \) on graphs \( G_{E_1,P_1}, G_{E_2,P_2} \), by retaining the device characteristics of \( E_1, E_2 \) as in \( \mathcal{N} \) and having no device characteristic constraints on \( P_1, P_2 \). Then we say that

\( \mathcal{N}_{E_1,P_1}, \mathcal{N}_{E_2,P_2} \) is a multiport decomposition of \( \mathcal{N} \) with port connection diagram \( G_{P_1,P_2} \).

We present below a linear time algorithm ([30]) for decomposing a graph minimally, that is, in such a way that \(|P_1|, |P_2|\) have minimum size, when the partition \( E_1, E_2 \) is specified. We can show that this size is

\[ |P_1| = |P_2| = r(G \circ E_1) - r(G \times E_1) \]

\[ = r(G \circ E_2) - r(G \times E_2). \]

### Algorithm minimal port decomposition

Let \( G \) be a graph on edge set \( E \) and let a partition \( E_1, E_2 \) be given. Let \( t_1, t_2 \) be forests of \( G \circ E_1, G \circ E_2 \), respectively.
Start with \( t_1 \) and grow a forest \( t_1 \cup b, t_1 \subseteq t_2 \), of \( G \).
Start with \( t_2 \) and grow another forest \( t_2 \cup b, t_2 \subseteq t_1 \), of \( G \).
Build the graph \( G \circ (E_1 \cup t_1) \times (E_1 \cup (t_2 - t_1)) \). Rename the edges \( t_2 - t_1 \) as \( P_1 \), and the graph as \( G_{E_1P_1} \).
Build the graph \( G \circ (E_2 \cup t_1) \times (E_2 \cup (t_1 - t_2)) \). Rename the edges \( t_1 - t_2 \) as \( P_2 \), and the graph as \( G_{E_2P_2} \).
Build the graph \( G_{E_1P_1} \circ (t_1 \cup P_1) \times (P_1 :: (t_1 - t_2)) \). Rename \( t_1 - t_2 \) as \( P_2 \) as before, and the graph as \( G_{P_1P_2} \).
Output \( G_{E_1P_1}, G_{E_2P_2} \) as multiports and \( G_{P_1P_2} \) as the port connection diagram.
Algorithm ends.
When the decomposition is minimal, the sets \( P_i \) will not contain circuits or cutsets in \( G_{E_1P_1}, G_{P_1P_2} \), \( G_{P_1E_2} \). The following result is an immediate consequence.

**Theorem 5.** Let the decomposition of the directed graph \( G \) into \( G_{E_1P_1}, G_{E_2P_2}, G_{P_1P_2} \) be minimal. We then have the following.

1. The sets \( P_i \), \( i = 1, 2 \), do not contain circuits or cutsets in \( G_{E_1P_1}, G_{P_1P_2}, G_{E_2P_2} \).
2. Let \( i_E, v_E \) be current and voltage vectors of \( G \). Let \( (i_{E_1}, i_{P_1}), (i_{E_2}, i_{P_2}), (i_{P_1}, i_{P_2}) \) be current vectors and let \( (v_{E_1}, v_{P_1}), (v_{E_2}, v_{P_1}), (v_{P_1}, v_{P_2}) \) be voltage vectors of \( G_{E_1P_1}, G_{E_2P_2}, G_{P_1P_2} \), respectively. Then \( i_{P_1}, i_{P_2} \) are uniquely determined, given \( i_{E_1} \) or \( i_{E_2} \), and \( v_{P_1}, v_{P_2} \) are uniquely determined, given \( v_{E_1} \) or \( v_{E_2} \).

In Section [10] we will show how to build ‘emulators’ for electrical networks. These are based on multiport decomposition, can be built in linear time and can serve as a substitute for state equations.

### 3. Linkages and maps

A **linkage** is a vector space \( V_S \) with a partition \( \{S_1 \cdots S_k\} \) of \( S \), specified.

We will denote it by \( V_{S_1 \cdots S_k} \).

Observe that a map \( x^T K = y^T \) can be regarded as a linkage \( V_{XY} \), with a typical vector \( (x^T, y^T) \), whose basis is the set of rows of \([I \ K]\), the first set of columns of the matrix being indexed by \( X \) and the second set by \( Y \).

A linkage \( V_{S_1 \cdots S_k} \) is said to be **decoupled** iff \( V_{S_1 \cdots S_k} = V_{S_1 \cdots S_k} \times S_1, i = 1, 2, \ldots, k \). This is equivalent to saying that it has the form \( \bigoplus_i V_{S_i}, i = 1, 2, \ldots, k \).

The matched composition operation “\( \leftrightarrow \)” can be regarded as a generalization of the composition operation for ordinary maps.

Thus if \( x^T K = y^T, y^T P = z^T \), it can be seen that \( V_{XY} \leftrightarrow V_{YZ} \) would have as the basis, the rows of \([I \ K P]\), the first set of columns of the matrix being indexed by \( X \) and the second set by \( Z \).

**Remark 2.**

1. When we compose matrices, the order is important. In the case of linkages, since vectors are indexed by subsets, order does not matter. Thus \( V_{S_P} = V_{P_S} \) and \( V_{S_P} \leftrightarrow V_{P_Q} = V_{P_Q} \leftrightarrow V_{P_S} \).
2. \( V_{XY} \) mimics the map \( K \) by linking row vectors \( x^T, y^T \) which correspond to each other when \( x^T \) is operated upon by \( K \), into the long vector \( (x^T, y^T) \). The collection of all such vectors forms a vector space which contains all the information that the map \( K \) and \( K^{-1} \) (if it exists) contain and represents both of them implicitly.

But there are two essential differences: a map takes vectors in \( F_X \) to vectors in \( F_Y \), but takes the vector \( 0_X \) only to the vector \( 0_Y \). In the case of linkages only a subspace of \( F_X \) may be involved as \( V_{XY} \circ X \) and the vector \( 0_X \) may be linked to a nontrivial subspace of \( F_Y \).

**Example 6.** Consider the equation \( Ax = b \). In the present frame work, we will derive the usual existence and uniqueness result i.e.,

a solution exists iff \( b \) lies in the span of columns of \( A \), equivalently \( b \in (\text{col}(A))^\perp \),
and if the solution exists, it is unique iff columns of \( A \) are independent.
We will associate with \(A, x, b\) the vector spaces \(\mathcal{V}_{SP}, \mathcal{V}_{PQ}, \mathcal{V}_{SQ}\) respectively, where \(\mathcal{V}_{SP}\) is a space of vectors \((f_s, g_p)\) with \(f_s^T A = g_p^T\), \(\mathcal{V}_{PQ}\) is a space of vectors \((g_p, h_Q)\) with \(g_p^T x = h^T_Q\), \(\mathcal{V}_{SQ}\) is a space of vectors \((f_s, h_Q)\) with \(f_s^T b = h^T_Q\).

Observe that from \(\mathcal{V}_{SP}, \mathcal{V}_{PQ}, \mathcal{V}_{SQ}\) we can uniquely infer \(A, x, b\).

The equation \(Ax = b\) translates to \(\mathcal{V}_{SP} \leftrightarrow \mathcal{V}_{PQ} = \mathcal{V}_{SQ}\).

By Theorem 2 we have that \(\mathcal{V}_{PQ}\) exists such that \(\mathcal{V}_{SP} \leftrightarrow \mathcal{V}_{PQ} = \mathcal{V}_{SQ}\) iff
\[
\mathcal{V}_{SP} \circ S \supseteq \mathcal{V}_{SQ} \circ S \quad \text{and} \quad \mathcal{V}_{SP} \times S \subseteq \mathcal{V}_{SQ} \times S.
\]

The first condition is automatic for maps since the domain is \(\mathcal{F}_S\) which translates to \(\mathcal{V}_{SP} \circ S = \mathcal{F}_S\). The second condition is equivalent to stating that ‘whenever \(f_s^T A = 0\), we must also have \(f_s^T b = 0\),’ which is the same as saying \(b \in (\text{col}(A))_⊥\).

We need next to show that existence of a solution \(\mathcal{V}_{PQ}\) to the equation also implies that there is another solution of the form \([I \ x]\).

We do this as follows. If
\[
\mathcal{V}_{SP} \equiv \{[I \ A]\}, \mathcal{V}_{SQ} \equiv \{[I \ b]\}
\]
then
\[
\mathcal{V}_{PQ} \equiv \mathcal{V}_{SP} \leftrightarrow \mathcal{V}_{SQ} = \{[A \ b]\} \quad \text{and} \quad \mathcal{V}_{SP} \circ P = \mathcal{V}_{PQ} \circ P.
\]

We may assume wlog rows of \([A \ b]\) to be independent. This implies that the rows of \(A\) are linearly independent (using ‘whenever \(f_s^T A = 0\), we must also have \(f_s^T b = 0\)). Now extend \(\mathcal{V}_{PQ}\) to a vector space \(\mathcal{V}_{PQ}^\prime\) such that \(\mathcal{V}_{PQ}^\prime \circ P = \mathcal{F}_P\). It can be seen that \(\mathcal{V}_{SP} \leftrightarrow \mathcal{V}_{PQ}^\prime\) is equal to \(\mathcal{V}_{SP} \leftrightarrow \mathcal{V}_{PQ}\) and further has the form \([I \ x]\).

Next let \(\mathcal{V}_{SP}, \mathcal{V}_{SQ}\) be such that there exists some \(\mathcal{V}_{PQ}\) satisfying \(\mathcal{V}_{SP} \leftrightarrow \mathcal{V}_{PQ} = \mathcal{V}_{SQ}\).

We know by Theorem 2 it is unique iff
\[
\mathcal{V}_{SP} \circ P \supseteq \mathcal{V}_{PQ} \circ P \quad \text{and} \quad \mathcal{V}_{SP} \times P \subseteq \mathcal{V}_{PQ} \times P.
\]

The second condition is trivial since \(0_p^T A = 0_p\), so that \(\mathcal{V}_{SP} \times P = 0_p\).

Next note that since \(x\) is the map \(g_p^T x = h^T_Q\), we must have \(\mathcal{V}_{PQ} \circ P = \mathcal{F}_P\).

So the first condition implies that the range of the map \(f_s^T A = g_p^T\) must be \(\mathcal{F}_P\).

This means that columns of \(A\) are independent.

**Example ends**

The ‘\(\leftrightarrow\)’ operation is not inherently associative. For instance, consider the expression
\[
(\mathcal{V}_{AB} \leftrightarrow \mathcal{V}_{BC}) \leftrightarrow (\mathcal{V}_{CA} \leftrightarrow \mathcal{V}_{PQ}).
\]

Here, if we remove the brackets, we get a subexpression \(\mathcal{V}_{AB} \leftrightarrow \mathcal{V}_{BC} \leftrightarrow \mathcal{V}_{CA}\), where the index set becomes null and the ‘\(\leftrightarrow\)’ operation is not defined for such a situation. We say such an expression contains a ‘null’ subexpression. Let us only look at expressions which do not contain null subexpressions. For such expressions, there is a special case where the brackets can be got rid of without ambiguity. This is when no index set occurs more than twice in the expression. Consider for instance the expression
\[
\mathcal{V}_{A_1B_1} \leftrightarrow \mathcal{V}_{A_2B_2} \leftrightarrow \mathcal{V}_{A_1B_1},
\]
where all the \(A_i, B_j\) are mutually disjoint. It is clear that this expression has a unique meaning, namely, the space of all \((f_{A_2}, g_{B_1})\) such that there exist \(h_{A_1}, k_{B_2}\) with
\[
(h_{A_1}, g_{B_1}) \in \mathcal{V}_{A_1B_1}, \quad (f_{A_2}, k_{B_2}) \in \mathcal{V}_{A_2B_2}, \quad (h_{A_1}, k_{B_2}) \in \mathcal{V}_{A_1B_2}.
\]

Essentially the terms of the kind \(p_{AB}\) survive if they occur only once and they get coupled through the terms which occur twice. These latter dont survive in the final expression. Such an interpretation is valid even if we are dealing with signed index sets of the kind \(-A_i\). (We remind the reader that \(\mathcal{V}_{(-A)_B}\) is the space of all vectors \((-f_{A}, g_{B})\) where \((f_{A}, g_{B})\) belongs to \(\mathcal{V}_{AB}\).) If either \(-A_i\), or \(A_i\) occurs, it counts as one occurrence of the index set \(A_i\). We state this result as a theorem but omit the routine proof.
Theorem 7. An expression of the form \( \leftrightarrow_{j,k \ldots} (V_{(\pm A_i) (\pm B_j) (\pm C_k) \cdots}) \), where the index sets \( \pm A_i, \pm B_j, \pm C_k, \cdots \) are all mutually disjoint has a unique meaning provided it contains no null subexpression and no index set occurs more than twice in it.

3.1. Pseudoidentity

Definition 8. Let \( A' \) be a copy of \( A \). We say the linkage \( V_{AA'} \) is a pseudoidentity for a linkage \( V_{AB} \) iff

\[ V_{AA'} \leftrightarrow V_{AB} = (V_{AB})_{A'B}. \]

When \( A' \) is a copy of \( A \), we remind the reader that \( I_{AA'} \) is the vector space \( \{(f_A, f_A') : f_A \in F_A \} \).

Lemma 9. Let \( V_{AA'} \supseteq I_{AA'} \cap (V_{AA'} \circ A) \) and let \( V_{AA'} = (V_{AA'})_{AA'} \). Then \( V_{AA'} \) satisfies the following conditions.

1. \( (V_{AA'} \circ A)_{A'} = V_{AA'} \circ A' \) if \( f_A \in V_{AA'} \circ A \) then \( (f_A, f_A') \in V_{AA'}. \) Further, if \( (f_A, g_A) \in V_{AA'} \), then \( (g_A, f_A') \in V_{AA'}. \)

2. \( (f_A, g_A)(g_A, h_A') \in (V_{AA'})_{AA'} \) then \( (f_A, h_A') \in V_{AA'}. \)

Proof. 1. These are immediate from the hypothesis.

2. If \( (f_A, g_A) \in V_{AA'} \), then since \( (f_A, f_A') \in V_{AA'} \) and \( V_{AA'} \) is a vector space, we must have \( (0_A, g_A - f_A') \in V_{AA'}. \) Since \( (g_A, h_A') \in V_{AA'} \), we must have \( (h_A, g_A) \in V_{AA'} \).

So \( (h_A, g_A) - (0_A, g_A - f_A') = (h_A, f_A') \in V_{AA'}. \) So \( (f_A, h_A') \in V_{AA'}. \)

Definition 10. We will call a linkage \( V_{AA'} \), where \( A' \) is a copy of \( A \), symmetric, if \( V_{AA'} \supseteq I_{AA'} \cap (V_{AA'} \circ A) \) and \( V_{AA'} = (V_{AA'})_{AA'}. \)

We now have a simple procedure for building a symmetric pseudoidentity for a linkage \( V_{AB}. \)

Theorem 11. Let \( V_{AA'} \) be a symmetric linkage. We then have the following.

1. \( V_{AA'} \) is a pseudoidentity for a linkage \( V_{AB} \) if \( V_{AA'} \circ A \supseteq V_{AB} \circ A \) and \( V_{AA'} \times A \subseteq V_{AB} \times A. \)

2. \( V_{AP} \leftrightarrow (V_{AP})_{A'|P} \), where \( A' \) is a copy of \( A \) is a symmetric pseudoidentity for \( V_{AB} \), if

\[ V_{AP} \circ A \supseteq V_{AB} \circ A, \quad V_{AP} \times A \subseteq V_{AB} \times A. \]

3. \( V_{AB} \leftrightarrow (V_{AB})_{A'B} \), where \( A' \) is a copy of \( A \) is a pseudoidentity for \( V_{AB}. \)

Proof. 1. (only if) Suppose \( V_{AA'} \circ A \supseteq V_{AB} \circ A. \)

Then there exists \( (f_A, g_B) \in V_{AB} \) such that \( (f_A, f_A') \not\in V_{AA'}. \)

But then \( (f_A, g_B) \not\in (V_{AA'} \leftrightarrow V_{AB}) \), which contradicts the fact that \( V_{AA'} \leftrightarrow V_{AB} = (V_{AB})_{A'B}. \)

Next suppose \( V_{AA'} \times A \not\subseteq V_{AB} \times A. \)

Then there exists \( (f_A, 0_A) \in V_{AA'} \), such that \( (f_A, 0_A) \not\in V_{AB}. \)

Now \( (0_A, f_A) \in V_{AA'} \) and \( (0_A, 0_B) \in V_{AB}. \) So \( (f_A', 0_B) \in V_{AA'} \leftrightarrow V_{AB} = (V_{AB})_{A'B}, \) a contradiction.

2. (if) Let \( (f_A', g_B) \in (V_{AA'} \leftrightarrow V_{AB}). \)

Then there exist \( (h_A, f_A') \in V_{AA'}, \quad (h_A, g_B) \in V_{AB}. \)

Now \( (f_A, f_A) \in V_{AA'} \) so that \( (h_A - f_A, 0_A) \in V_{AA'}. \)

Thus \( (h_A - f_A) \in V_{AA'} \times A \not\subseteq V_{AB} \times A. \)

Since \( (h_A, g_B), (h_A - f_A, 0_B) \in V_{AB} \) and \( V_{AB} \) is a vector space, it follows that \( (f_A, g_B) \in V_{AB}. \)

Next let \( (f_A, g_B) \in V_{AB}. \)

Since \( f_A \in V_{AB} \circ A \subseteq V_{AA'} \circ A \), it follows from the symmetry of \( V_{AA'} \) that \( (f_A, f_A') \in V_{AA'}. \)

But then \( (f_A', g_B) \in (V_{AA'} \leftrightarrow V_{AB}). \)

It thus follows that \( V_{AA'} \leftrightarrow V_{AB} = (V_{AB})_{A'B}, \) i.e., \( V_{AA'} \) is a pseudoidentity for \( V_{AB}. \)

3. This is immediate from the preceding section of the present theorem.

\[ \square \]
3.2. Special operations for linkages with two block partitions

For linkages whose partition has exactly two blocks, there are simple generalizations of operations on maps which are available. The first is the transpose.

**Definition 12.** Let $\mathcal{V}_{AB}$ be a linkage. The transpose of $\mathcal{V}_{AB}$, $\mathcal{V}_{AB}^T \equiv (\mathcal{V}_{AB}^\perp)_{A(-B)}$.

For convenience we define the transpose of $\mathcal{V}_A$, $(\mathcal{V}_A)^T \equiv \mathcal{V}_A^\perp$. The following lemma is routine.

**Lemma 13.**
1. $(\mathcal{V}_A)^{−1} = \mathcal{V}_A$,
2. $(\mathcal{V}_{AB})_{A(-B)} = (\mathcal{V}_{AB})_{(-A)B}$,
3. $((\mathcal{V}_{AB})_{A(-B)})^\perp = (\mathcal{V}_{AB}^\perp)_{A(-B)}$,
4. $(\mathcal{V}_{AB})_{A(-B)} \circ A = \mathcal{V}_{AB} \circ A$ and $(\mathcal{V}_{AB})_{A(-B)} \times A = \mathcal{V}_{AB} \times A$.

Using the results from Subsection 2.1.4 and Lemma 13 we have from the definition of the transpose,

**Lemma 14.** Let $\mathcal{V}_A, \mathcal{V}_{AB}$ be linkages. Then

1. $\mathcal{V}_A^{TT} = \mathcal{V}_A$, $\mathcal{V}_{AB}^{TT} = \mathcal{V}_{AB}$,
2. $(\mathcal{V}_{AB} \circ B)^T = \mathcal{V}_{AB}^T \times B$.

The IDT (Theorem 4) could be restated as

**Theorem 15.**

$$\mathcal{V}_{AB} \leftrightarrow \mathcal{V}_{BC} = (\mathcal{V}_{AB} \leftrightarrow \mathcal{V}_{BC})^T.$$  

**Proof.** The left side of the expression in the statement of the theorem is

$$(\mathcal{V}_{AB}^\perp)_{A(-B)} \leftrightarrow (\mathcal{V}_{BC}^\perp)_{(-B)C} = (\mathcal{V}_{AB}^\perp) \leftrightarrow (\mathcal{V}_{BC}^\perp).$$

The right side of the expression is

$$(\mathcal{V}_{AB} \leftrightarrow \mathcal{V}_{BC})^\perp_{A(-C)}.$$  

Changing the sign of the index set $C$ on both sides, we need to verify whether

$$(\mathcal{V}_{AB}^\perp \leftrightarrow \mathcal{V}_{BC}^\perp)_{A(-C)}$$

equals $(\mathcal{V}_{AB} \leftrightarrow \mathcal{V}_{BC})^\perp$,

i.e., whether

$$\mathcal{V}_{AB}^\perp \leftrightarrow (\mathcal{V}_{BC}^\perp)_{B(-C)} = \mathcal{V}_{AB} \leftrightarrow (\mathcal{V}_{BC}^\perp)_{(-B)C} = (\mathcal{V}_{AB}^\perp = \mathcal{V}_{BC}^\perp) \leftrightarrow (\mathcal{V}_{AB} \leftrightarrow \mathcal{V}_{BC})^\perp$$

(we note that $(\mathcal{V}_{AB} \leftrightarrow (\mathcal{V}_{BC})_{(-B)C}) = (\mathcal{V}_{AB} = \mathcal{V}_{BC})$).

Since this equality holds by IDT (Theorem 4), this completes the proof. \qed

The above result generalizes the usual transpose rule for linear maps: $(FG)^T = GTFT$. For the ‘$\leftrightarrow$’ operation, order does not matter since the spaces are named with index sets.

For linkages whose partition has exactly two blocks, a useful operation which generalizes the usual sum of maps is the intersection-sum defined as follows.

**Definition 16.** Let $\mathcal{V}_{AB}, \mathcal{V}_{AB}$ be linkages. The intersection-sum

$$\mathcal{V}_{AB} \oplus \mathcal{V}_{AB} \equiv \{(f_A, f_B) : (f_A, f_B) \in \mathcal{V}_{AB}, (f_A, f_B^2) \in \mathcal{V}_{AB}, f_B = f_B + f_B^2\}.$$  

Such a definition, which speaks both of ‘domain’ and ‘range’ instead of only ‘range’ in the case of ordinary maps, is natural because for ordinary maps the domain has the form $\mathcal{F}_A$ whereas for linkages, $\mathcal{V}_{AB} \circ A$ and $\mathcal{V}_{AB} \circ A$ need not be the same.

An immediate consequence of the definition is the following
Lemma 17. The ‘+\_b ’ operation is associative and commutative.

We give below a useful way of visualizing the intersection-sum operation. We remind the reader that \([K]\) denotes the space spanned by the rows of the matrix \(K\). Thus

\[
\{[I_A \ I_{A'} \ I_{A''}]\}
\]
denotes the collection of all vectors

\[
f_{AA' A''} = (f_{AA' A''}/A) = (f_{AA' A''}/A')_A, \quad (A, A', A'' \text{ being copies of each other}).
\]

\[
\begin{bmatrix}
I_A & I_{A'} & 0 \\
I_A & 0 & I_{A'}
\end{bmatrix}
\]

(1)

denotes the collection of all vectors \(f_{AA' A''}\), where \(f_{AA' A''}/A = (f_{AA' A''}/A')_A + (f_{AA' A''}/A'')_A\).

It is clear that \(V_{AB} \leftrightarrow \{[I_A \ I_{A'}] \} = (V_{AB})_{A' B}\).

Next consider \(V_{A'B'} \oplus V_{A'B'}\). This space is a direct sum of copies of \(V_{AB} \hat{V}_{AB}\) built respectively on disjoint copies \(A' \cup B'\) and \(A'' \cup B''\) of \(A \cup B\). The space

\[
V_{A'B'} \oplus \hat{V}_{A'B'} \leftrightarrow \{[I_A \ I_{A'} \ I_{A''}]\} \oplus \left\{ \begin{bmatrix} I_B & I_{B'} & 0 \\ I_B & 0 & I_{B'} \end{bmatrix} \right\}
\]
is on the set \(A \cup B\) and can be seen to be the collection

\[
\{(f_A, f_B) : (f_A, f_B^B) \in V_{AB}, (f_A, f_B^B) \in \hat{V}_{AB}, f_B = f_B^B + f_B^T\}.
\]

[The ‘\leftrightarrow’ operation with \(\{[I_A \ I_{A'} \ I_{A''}]\} \oplus \left\{ \begin{bmatrix} I_B & I_{B'} & 0 \\ I_B & 0 & I_{B'} \end{bmatrix} \right\}\) forces equality of the \(A\) components and addition of the \(B\) components.]

We thus have the following lemma.

Lemma 18.

\[
V_{AB} + b \hat{V}_{AB} = V_{A'B'} \oplus \hat{V}_{A'B'} \leftrightarrow \{[I_A \ I_{A'} \ I_{A''}]\} \oplus \left\{ \begin{bmatrix} I_B & I_{B'} & 0 \\ I_B & 0 & I_{B'} \end{bmatrix} \right\}.
\]

The following lemma is easy to see

Lemma 19. \([I_A \ I_{A'} \ I_{A''}]^\perp = \]

\[
\begin{bmatrix}
I_A & -I_{A'} & 0 \\
I_A & 0 & -I_{A'}
\end{bmatrix}
\]

(2)

By IDT we get the following generalization of \((F + G)^T = F^T + G^T\).

(Note that \((V_{SP} \leftrightarrow V_P)^\perp = V_{SP}^\perp \leftrightarrow V_P^\perp\).)

Theorem 20. 1. \((V_{AB} + b \hat{V}_{AB})^\perp = V_{AB}^\perp + a \hat{V}_{AB}^\perp\).

2. \((V_{AB} + b \hat{V}_{AB})^T = V_{AB}^T + a \hat{V}_{AB}^T\).

Proof. 1. Noting that \((V_{SP} \leftrightarrow V_P)^\perp = V_{SP}^\perp \leftrightarrow V_P^\perp\),

\[
(V_{AB} + b \hat{V}_{AB})^\perp = V_{A'B'}^\perp \oplus \hat{V}_{A'B'}^\perp \leftrightarrow \left\{ \begin{bmatrix} I_A & -I_{A'} & 0 \\ I_A & 0 & -I_{A'} \end{bmatrix} \right\} \oplus \{[I_B - I_{B'} - I_{B''}]\}
\]

\[
= (V_{AB}^\perp + a \hat{V}_{AB}^\perp)(-A)(-B).
\]

2. \((V_{AB} + b \hat{V}_{AB})^T = (V_{AB} + b \hat{V}_{AB})^\perp_{A(-B)} = (V_{AB}^\perp + a \hat{V}_{AB}^\perp)_{A(-B)}
\]

\[
= (V_{AB})_{A(-B)} + (\hat{V}_{AB})_{A(-B)} = V_{AB}^T + a \hat{V}_{AB}^T.
\]

\[\Box\]
3.3. Scalar multiplication for linkages

Let $V_{AB}$ be a linkage. We define

$$\lambda^b V_{AB} \equiv V_{A(b)} + V_{AB} \times B \equiv \{(f_A, \lambda g_B) : (f_A, g_B) \in V_{AB}\} + V_{AB} \times B.$$ 

Note that, when $\lambda \neq 0$, we have $\lambda^b V_{AB} \equiv V_{A(b)} = (V_{AB} \leftrightarrow [(I_B \lambda I_{B'}]])_{AB}$, and more generally, if we include the case of $\lambda = 0$, we have $\lambda^b V_{AB} = (V_{AB} \leftrightarrow [(I_B \lambda I_{B'})])_{AB} + V_{AB} \times B$.

**Remark 3.** We note that when $\lambda \neq 0$, the above definition could have been rewritten more simply as $\lambda^b V_{AB} \equiv \{(f_A, \lambda g_B) : (f_A, g_B) \in V_{AB}\}$, since $0_A \oplus V_{AB} \times B \subseteq \{(f_A, \lambda g_B) : (f_A, g_B) \in V_{AB}\}$, when $\lambda \neq 0$. The contraction to $B$, of $\{(f_A, \lambda g_B) : (f_A, g_B) \in V_{AB}\}$, when $\lambda \neq 0$, is simply $V_{AB} \times B$.

However, when $\lambda = 0$, the vector space $\{(f_A, \lambda g_B) : (f_A, g_B) \in V_{AB}\}$ (which is the first term in the right side of the definition) is equal to $\{(f_A, 0_B) : (f_A, g_B) \in V_{AB}\}$. This does not contain $0_A \oplus V_{AB} \times B$ and its contraction to $B$ is simply $0_B$.

For reasons pertaining to the form of the duality result we state below, we prefer $V_{AB} \times B$ to the contraction of $\lambda^b V_{AB}$ to $B$ even when $\lambda = 0$. Hence we have explicitly added the term $V_{AB} \times B$ in the definition of $\lambda^b V_{AB}$ when $\lambda = 0$. Thus $0^b V_{W\hat{W}} = V_{W\hat{W}} \circ W \oplus \lambda^b V_{W\hat{W}} \times \hat{W}$.

**Theorem 21.** Let $V_{AB}$ be a linkage. Then

1. $$(\lambda_1^b + \lambda_2^b)V_{AB} = \lambda_1^b V_{AB} + b_{\lambda_2^b} V_{AB}.$$ 

2. $$(\lambda^b V_{AB})^T = \lambda^b V_{AB}^T.$$ 

**Proof.**
1. This is routine.
2. Let $\lambda = 0$. The LHS reduces to $(V_{AB} \circ A \oplus V_{AB} \times B)^T = (V_{AB}^T \times A \oplus V_{AB}^T \circ B)$, which is the RHS by definition of $\lambda^b V_{AB}$.

Next let $\lambda \neq 0$. We have $\lambda^b V_{AB} \equiv V_{A(b)} = (V_{AB} \leftrightarrow [(I_B \lambda I_{B'})])_{AB}$.

Therefore by Theorem 15

$$(\lambda^b V_{AB})^T = (V_{AB} \leftrightarrow [(I_B \lambda I_{B'})])_{AB} = (V_{AB} \leftrightarrow [(I_B \lambda I_{B'})])_{AB} = \lambda^b V_{AB}^T,$$

where we have made use of the fact that $[(I_B \lambda I_{B'})]^T = [(I_B \lambda I_{B'})]$. 

3.4. Distributivity of intersection-sum over matched composition and scalar multiplication

For ordinary maps we have the distributivity of addition over composition and scalar multiplication. Because this result is true we are able to develop the rich spectral theory of operators. In subsequent sections we will be speaking of generalized operators and polynomials of such objects. So we need to study the distributivity of intersection-sum over ‘$+$’. The following result is the best that can be done, but proves adequate for our purpose.

**Theorem 22.** Let $V_{AB}, \hat{V}_{AB}, V_{BC},$ be linkages, $A, B, C$, being pairwise disjoint.

1. If $V_{BC} \times B \subseteq V_{AB} \times B$, then

$$V_{BC} \leftrightarrow (V_{AB} + a \hat{V}_{AB}) = (V_{BC} \leftrightarrow V_{AB}) + a(V_{BC} \leftrightarrow \hat{V}_{AB}).$$

2. If $V_{BC} \times B \subseteq V_{AB}^1 \times B, \cdots V_{BC} \times B \subseteq V_{AB}^{k-1} \times B$, then

$$V_{BC} \leftrightarrow (V_{AB}^1 + a \cdots + a V_{AB}^k) = (V_{BC} \leftrightarrow V_{AB}^1) + a \cdots + a(V_{BC} \leftrightarrow V_{AB}^k).$$

19
3. Dually, if $\mathcal{V}_{BC} \circ B \supseteq \mathcal{V}_{AB} \circ B$, then

$$\mathcal{V}_{BC} \leftrightarrow (\mathcal{V}_{AB} \circ \mathcal{V}_{BC}) = (\mathcal{V}_{BC} \circ \mathcal{V}_{AB}) + (\mathcal{V}_{BC} \circ \mathcal{V}_{AB}).$$

4. If $\mathcal{V}_{BC} \circ B \supseteq \mathcal{V}_{AB} \circ B$, then $\mathcal{V}_{BC} \circ (\mathcal{V}_{AB} \circ \mathcal{V}_{BC}) \supseteq (\mathcal{V}_{BC} \circ \mathcal{V}_{AB}) + (\mathcal{V}_{BC} \circ \mathcal{V}_{AB})$.

**Proof.**

1. Let $(f_A, h_C) \in \mathcal{V}_{BC} \circ \mathcal{V}_{AB}$. Then there exist vectors

$$(g_B, h_C) \in \mathcal{V}_{BC}, (f_A, g_B) \in \mathcal{V}_{AB}, (f_A, g_B) \in \mathcal{V}_{AB},$$

such that $f_A = f_A^1 + f_A^2$. This means $(f_A^1, h_C) \in (\mathcal{V}_{BC} \circ \mathcal{V}_{AB})$ and $(f_A^2, h_C) \in (\mathcal{V}_{BC} \circ \mathcal{V}_{AB})$ and therefore

$$(f_A, h_C) \in (\mathcal{V}_{BC} \circ \mathcal{V}_{AB}) + (\mathcal{V}_{BC} \circ \mathcal{V}_{AB}).$$

Next let $(f_A, h_C) \in (\mathcal{V}_{BC} \circ \mathcal{V}_{AB}) + (\mathcal{V}_{BC} \circ \mathcal{V}_{AB})$. This means there exist vectors $(f_A^1, h_C) \in \mathcal{V}_{BC} \circ \mathcal{V}_{AB}$, $(f_A^2, h_C) \in \mathcal{V}_{BC} \circ \mathcal{V}_{AB}$ with $f_A = f_A^1 + f_A^2$.

Therefore there exist vectors $(f_A^1, f_B^2, (f_B, h_C), (f_B, h_C) \in \mathcal{V}_{BC}, \mathcal{V}_{BC}$ respectively and vectors $(f_A^2, f_B^2, (f_B, h_C) \in \mathcal{V}_{BC}, \mathcal{V}_{BC}$ respectively.

Therefore $(f_A^2, f_B^2, 0C) \in \mathcal{V}_{BC}$, i.e., $(f_A^2, f_B^2, 0C) \in \mathcal{V}_{BC} \times B \subseteq \mathcal{V}_{AB} \times B$.

Hence, $(0A, f_B^2, f_B^2) \in \mathcal{V}_{AB}$. Now $(f_A^1, f_B^2) \in \mathcal{V}_{AB}$. Therefore $(f_A^1, f_B^2) \in \mathcal{V}_{AB}$.

We already have that $(f_A^1, f_B^2) \in \mathcal{V}_{AB}$.

Hence

$$(f_A^1 + f_A^2, f_B^2) = (f_A, f_B^2) \in (\mathcal{V}_{AB} \circ \mathcal{V}_{AB}).$$

We know that $(f_B^2, h_C) \in \mathcal{V}_{BC}$. Therefore

$$(f_A, h_C) \in \mathcal{V}_{BC} \circ (\mathcal{V}_{AB} \circ \mathcal{V}_{AB}).$$

2. The proof is by induction on the number of terms within the bracket on the left hand side.

3. By the first part of the theorem we have if $\mathcal{V}_{BC} \times B \subseteq \mathcal{V}_{AB} \times B$, then

$$\mathcal{V}_{BC} \circ (\mathcal{V}_{AB} \circ \mathcal{V}_{BC}) = (\mathcal{V}_{BC} \circ \mathcal{V}_{AB}) + (\mathcal{V}_{BC} \circ \mathcal{V}_{AB}).$$

Hence, if $(\mathcal{V}_{BC} \times B) \circ (\mathcal{V}_{AB} \circ B)$, then

$$(\mathcal{V}_{BC} \circ (\mathcal{V}_{AB} \circ \mathcal{V}_{BC})) = (\mathcal{V}_{BC} \circ (\mathcal{V}_{AB} \circ \mathcal{V}_{BC})).$$

4. The proof is by induction on the number of terms within the bracket on the left hand side.

**Remark 4.** To see that the statement of the theorem fails without the ‘dot-cross’ conditions, take $\mathcal{V}_{BC}$ to be spanned by $(g^1_B, f_C, g^2_B, f_C)$, $\mathcal{V}_{AB}$ to be spanned by $(h^1_A, g^1_B)$, $\mathcal{V}_{AB}$ to be spanned by $(h^2_A, g^2_B)$, and take $g^1_B \neq g^2_B, h^1_A + h^2_A \neq 0_A$.

It can be seen that in this case

$$(\mathcal{V}_{BC} \circ (\mathcal{V}_{AB} \circ \mathcal{V}_{AB})) \neq (\mathcal{V}_{BC} \circ \mathcal{V}_{AB}) + (\mathcal{V}_{BC} \circ \mathcal{V}_{AB}).$$

The corresponding result for scalar multiplication is straightforward and we state it but skip its proof.

**Theorem 23.**

$$\lambda B(\mathcal{V}_{AB} \circ \mathcal{V}_{AB}) = (\lambda B\mathcal{V}_{AB}) + (\lambda B\mathcal{V}_{AB}).$$
4. Dynamical Systems

The algebraic operations we define are natural for dynamical systems and will be illustrated for them. While the motivation is through solutions of linear constant coefficient differential equations, the algebraic results are true for vectors over arbitrary (including finite) fields. The preliminary definitions from [12] are listed below.

A generalized dynamical system with additional variables (GDSA) is a vector space $V_{W \dot{W}\ M}$ on the set $W \parallel \dot{W} \parallel A \parallel M$ where $W, \dot{W}$, are copies of each other (intended to take care of the dynamical variables and their derivatives), and $A, M$, the additional variables and the manifest variables respectively. Thus $w(t) : W \rightarrow \mathbb{R}, \dot{w}(t) : \dot{W} \rightarrow \mathbb{R}, a(t) : A \rightarrow \mathbb{R}, m(t) : M \rightarrow \mathbb{R}$. We write $w(t)$ etc., simply as $w$ etc. The manifest variables are the ‘external variables’ of the system. Usually a GDSA would be available to us in the form of the solution space of constraint equations

$$\left[ S_\dot{W} \ S_W \ S_A \ S_M \right] \begin{pmatrix} \dot{w} \\ w \\ a \\ m \end{pmatrix} = 0. \quad (3)$$

Here $(w(t), \dot{w}(t), a(t), m(t))$ is a real vector which is a solution to the algebraic equation. That this arises from a set of linear constant coefficient differential equations with solutions of the kind $(w(\cdot), \dot{w}(\cdot), a(\cdot), m(\cdot))$ is not used strongly in the present paper except in the examples and in the definition of ‘regular generalized dynamical system’ given below.

We write $V_{W \dot{W}\ A M}$ alternatively as $V(w, \dot{w}, a, m)$.

We define a generalized dynamical system (GDS) as a vector space $V_{W \dot{W}\ M}$ on the set $W \parallel \dot{W} \parallel M$ where $W, \dot{W}$, are copies of each other. This is obtained from a GDSA by suppressing the additional variables that is,

$$V_{W \dot{W}\ M} = V_{W \dot{W}\ A M} \circ W \dot{W} M.$$

We study a GDS (or a GDSA) ‘relative to’ a vector space $V_M$. This vector space is expected to capture (and is a generalization of) the usual partition of the manifest variables into ‘input’ variables $m_u$ and ‘output’ variables $m_y$. We define a generalized autonomous system (genaut) as a vector space $V_{W \dot{W}}$ on the set $W \dot{W}$ where $W, \dot{W}$, are copies of each other. A genaut $V_{W \dot{W}}$ could be obtained from a GDS by taking a generalized minor with respect to $V_M$, i.e., $V_{W \dot{W}} = V_{W \dot{W}\ M} \equiv V_{W \dot{W}\ M} \circ W \dot{W} M$. Often GDSs arise with a natural partition $\{M_u, M_y\}$ of the index set $M$, corresponding to the input variables $m_u$ and the output variables $m_y$. We will call such a GDS, an input-output GDS. An example of such an input-output GDS would be the system $V_{W \dot{W}\ M_u M_y}$ defined by

$$L \dot{w} = Aw + Bm_u$$
$$m_y = Cw + Dm_u \quad (4a)$$

If we allow the variables $m_u, m_y$ to be free we would get the genaut $V_{W \dot{W}} \equiv V_{W \dot{W}\ M_u M_y} \circ W \dot{W}$.

**Definition 24.** We call a GDS $V_{W \dot{W}\ M}$, regular, iff it satisfies

$$V_{W \dot{W}\ M} \circ W \supseteq (V_{W \dot{W}\ M} \circ \dot{W})_W \quad (5a)$$
$$V_{W \dot{W}\ M} \times W \supseteq (V_{W \dot{W}\ M} \times \dot{W})_W \quad (5b)$$

We call an input-output GDS $V_{W \dot{W}\ M_u M_y}$, regular, iff $V_{W \dot{W}\ M}$, $M \equiv M_u \cup M_y$, is regular.
Remark 5. The conditions in Equations arise in the case of infinitely differentiable solutions to linear
contant coefficient differential equations. Suppose \((w(\cdot), \dot{w}(\cdot), m(\cdot))\) is a solution to the equations. Then

clearly so would \((\dot{w}(\cdot), \ddot{w}(\cdot), \ddot{m}(\cdot))\) be a solution. From this it is clear that whenever \(\dot{w}(t) \in (V_{W W} \circ \tilde{W})_W\) we
also have that \(\dot{w}(t) \in V_{W W} \circ W\). The first condition now follows because we can take any arbitrary real
vector \(x\) on \(W\) or \(\tilde{W}\) to be the vector \(\dot{w}(t)\). The second condition arises if we insist that the adjoint (see
Section 5.3 for a description) of a regular system be regular. This is desirable from duality considerations.

Definition 25. A genaut \(V_{W \tilde{W}}\) is a generalized operator (genop) iff

\[
V_{W \tilde{W}} \circ W \supseteq (V_{W \tilde{W}} \circ \tilde{W})_W \quad \text{and} \quad V_{W \tilde{W}} \times W \supseteq (V_{W \tilde{W}} \times \tilde{W})_W. \tag{6}
\]

A genaut that satisfies \(V_{W \tilde{W}} \circ W \supseteq (V_{W \tilde{W}} \circ \tilde{W})_W\) is called an upper semi genop or USG for short and

if it satisfies \(V_{W \tilde{W}} \times W \supseteq (V_{W \tilde{W}} \times \tilde{W})_W\), is called a lower semi genop or LSG for short.

As one can see, however, genops are weaker than the usual operators. Equation 6 does not force the
collection of permissible \(w\) vectors to be \(F_W\) and \(w = 0\) does not imply \(\dot{w} = 0\). We show below that genops
occur naturally. One can eliminate variables and write state equations for such systems but this would
be computationally expensive, destroy natural (topological ) structure making subsequent computations
also expensive. Fortunately, however, for all practical purposes, genops are sufficient. In particular, we can
define polynomials of genops in a manner similar to those of operators, we can compute minimal annihilating
polynomials etc. as we show in Section 5.

An example of a dynamical system with additional variables is a linear electrical network with dynamic
devices (capacitors (\(C\)) and inductors (\(L\)), static devices (resistors and controlled sources (\(r\))), voltage and
current sources (\(E\) and \(J\)). We will call such a network an \(RLCEJ\) network. The variables associated
with the devices are \(v_C, i_C, v_L, i_L, v_r, i_r, v_E, i_E, v_J, i_J\). In addition we can introduce output variables.
Voltage outputs are obtained by introducing open circuit branches across existing nodes and sensing the
voltage across them. Current outputs are obtained by splitting an existing node into two, introducing a
short circuit between the split nodes and sensing the current through the short circuit. Example of such a
network is given in Figure 7.

If all the \(R, L, C\) are positive (symmetric positive definite matrix for \(L\) in general) and voltage sources
and current sensors do not form loops and current sources and voltage sensors do not form cutsets, then one
can show that for arbitrary values of sources and consistent initial conditions (capacitor voltages according
to capacitor loops and inductor currents according to inductor cutsets), the solution is unique whether or
not the sources are zero. From this, it follows that Equation 5 (b) is satisfied trivially. The constraints
on \(W\) variables are the initial condition constraints and are only topological whereas the constraints on \(\tilde{W}\)
variables include the above topological conditions and additionally also other network conditions. Therefore
the corresponding GDS satisfies Equation 5 (a) and thus the system is regular. This argument is also
sufficient to show that the \(RLCEJ\) network (with the sources present) is regular. (The adjoint of this
system will satisfy Equation 5 (a) trivially but Equation 5 (b) nontrivially.)

The \(RLCEJ\) network of Figure 1 if treated as a GDSA \(V(w, \dot{w}, l_w, l_r, m)\) \((l_w, l_r\text{ being the additional}
variables), has the variables \(w, \dot{w}, l_w, l_r, m\) as shown below:

\[
w \equiv (v_{C1}, v_{C2}, v_{C3}, v_{C4}, i_{L1}, i_{L2}, i_{L3}), \quad \dot{w} \equiv (\dot{v}_{C1}, \dot{v}_{C2}, \dot{v}_{C3}, \dot{v}_{C4}, \frac{di_{L1}}{dt}, \frac{di_{L2}}{dt}, \frac{di_{L3}}{dt}),
\]

\[
l_w \equiv (i_{R1}, i_{R2}, i_{R3}, i_{E}, i_{v}, v_{y}, v_{r1}, v_{r2}, v_{r3}, v_{j}),
\]

\[
l_r \equiv (i_{C1}, i_{C2}, i_{C3}, i_{C4}, v_{L1}, v_{L2}, v_{L3}),
\]

\[
m \equiv (m_u, m_y), \quad m_u \equiv (i_j, v_E), \quad m_y \equiv (y_i, y_v).
\]

Note that \(l_w\) also includes the variables associated with sources and outputs other than the manifest variables,
such as, for instance, currents of voltage sources or voltages of current sensors.
Now

\[ \mathcal{V}(w, \hat{w}, l_r, m) = \mathcal{V}^{lo}(w, \hat{w}, l_r, m) \cap \mathcal{V}^{de}(\hat{w}, l_r, m) \]

where

\[ \mathcal{V}^{lo}(w, \hat{w}, l_r, m) \equiv \mathcal{V}(\mathcal{G}) \oplus \mathcal{V}(\mathcal{G}) \oplus \mathcal{V}_d(\hat{w}) , \]

\[ \mathcal{V}(\mathcal{G}) \text{ and } \mathcal{V}(\mathcal{G}) \text{ denote the current and voltage spaces of } \mathcal{G} \text{ and } \mathcal{V}^{lo}(\hat{w}) \text{ is the space of vectors } \hat{w} \text{ which satisfy the topological conditions on } \hat{w}. \]

In general the vector \( \hat{v}_C \) satisfies, just as \( v_C \) does, the KVL conditions of the graph obtained by open circuiting all branches other than capacitor branches and the vector \( \frac{di_L}{dt} \) satisfies, just as \( i_L \) does, the KCL conditions of the graph obtained by short circuiting all branches other than the inductor branches. The device characteristics constraints are

\[ \mathcal{V}^{de}(\hat{w}, l_r, m) = \mathcal{V}^{de}(\hat{w}, l_r) \oplus \mathcal{V}^{de}(l_r), \]

where \( \mathcal{V}^{de}(\hat{w}, l_r) \) is the solution space of the equations \( i_C = C \hat{v}_C, v_L = L \frac{di_L}{dt}, C, L \) being symmetric positive definite matrices. (Observe \( w \) variables are not involved in these equations).

\[ v_R = R i_R, \quad v_{yi} = 0, \quad i_{yv} = 0. \]

It is clear that the device characteristics constraints on \( (\hat{w}, l_r) \) do not involve \( l_r \) and vice versa.

Studying this network relative to a specified \( \mathcal{V}_M \) can be illustrated as follows: Let \( \mathcal{V}_M \equiv 0_{mu} \oplus F_{my} \). In this case this amounts to setting the sources to zero and the outputs free. If we work with \( \mathcal{V}_M \equiv F_{mu} \oplus 0_{my} \) it amounts to keeping the sources free but the output zero. In this case, note that the output branches have both current and voltage zero.

5. Duality

5.1. Perpendicular duality

Duality arises in implicit linear algebra in a very natural manner. The key idea for us is the following: Let

\[ \epsilon(V_1, \ldots, V_k, +, \cap, \oplus, \circ, \leftrightarrow, =, \subseteq, =) \]

be called the ‘primal’ statement. Consider the second statement

\[ \epsilon^2(V_1, \ldots, V_k, +, \cap, \oplus, \circ, \leftrightarrow, =, \subseteq, =) \equiv \epsilon(V_1^+, \ldots, V_k^+, +, \cap, \oplus, \circ, =, \leftrightarrow, \subseteq, =) \]
which is obtained by replacing \( \mathcal{V}_i \) by \( \mathcal{V}_i^\perp \), + by \( \cap \), \( \cap \) by +, \( \oplus \) by \( \oplus \), \( \circ \) by \( \times \), \( \times \) by \( \circ \), interchanging \( \leftrightarrow, \Leftrightarrow \), interchanging \( \supseteq, \subseteq \), and retaining = as = . Any left and right brackets that occur in the primal statement are left unchanged in the second. We have
\[
\epsilon(\mathcal{V}_1, \ldots, \mathcal{V}_k, +, \cap, \oplus, \circ, \times, \leftrightarrow, \supseteq, \subseteq, =) \quad \text{is true iff} \quad \epsilon(\mathcal{V}_1^\perp, \ldots, \mathcal{V}_k^\perp, +, \cap, \oplus, \circ, \times, \leftrightarrow, \supseteq, \subseteq, =) \quad \text{is true.}
\]
(If we assume that the connective ‘\( \leftrightarrow \)’ is between spaces of the form \( \mathcal{V}_S, \mathcal{V}_T \) where \( S \supseteq T \), then there is no need to introduce ‘\( \Leftrightarrow \)’. We can simply replace ‘\( \leftrightarrow \)’ by ‘\( \Leftrightarrow \)’ in the second statement.)

This fact is a routine consequence of the basic results
\[
(\mathcal{V}^\perp)^\perp = \mathcal{V}; \quad (\mathcal{V}_1 + \mathcal{V}_2)^\perp = \mathcal{V}_1^\perp \cap \mathcal{V}_2^\perp; \quad (\mathcal{V}_1 \Leftrightarrow \mathcal{V}_2)^\perp = (\mathcal{V}_1^\perp \Leftrightarrow \mathcal{V}_2^\perp).
\]
The statement
\[
\epsilon(\mathcal{V}_1, \ldots, \mathcal{V}_k, +, \cap, \oplus, \circ, \times, \leftrightarrow, \supseteq, \subseteq, =),
\]
obtained by replacing each \( \mathcal{V}_i \) by \( \mathcal{V}_i^\perp \) in the second statement
\[
\epsilon^2(\mathcal{V}_1, \ldots, \mathcal{V}_k, +, \cap, \oplus, \circ, \times, \leftrightarrow, \supseteq, \subseteq, =)
\]
is called the ‘\( \perp - \)dual’ statement.

**Example 26.** The second statement of
\[
[(\mathcal{V}_W \amalg \mathcal{V}_W^2) \leftrightarrow \mathcal{V}_W] \leftrightarrow [\mathcal{V}_W^\perp \leftrightarrow \mathcal{V}_W^\perp] \supseteq [\mathcal{V}_W \leftrightarrow \mathcal{V}_W], \quad (7)
\]
is
\[
[(\mathcal{V}_W \amalg \mathcal{V}_W^2)^\perp \leftrightarrow \mathcal{V}_W^\perp] \leftrightarrow [(\mathcal{V}_W \amalg \mathcal{V}_W^2)^\perp \leftrightarrow \mathcal{V}_W^\perp] \subseteq [(\mathcal{V}_W \amalg \mathcal{V}_W^2)^\perp \leftrightarrow \mathcal{V}_W^\perp]. \quad (8)
\]
The \( \perp - \)dual statement is
\[
[(\mathcal{V}_W \amalg \mathcal{V}_W^2) \leftrightarrow \mathcal{V}_W^\perp] \leftrightarrow [\mathcal{V}_W \leftrightarrow \mathcal{V}_W] \subseteq [\mathcal{V}_W \leftrightarrow \mathcal{V}_W]. \quad (9)
\]
In the above example, it is not necessary to replace \( \leftrightarrow \) of the primal with ‘\( \Leftrightarrow \)’ in the second or dual, since one of the index sets of vector spaces, linked by the operation, is contained in the other.

Now suppose that the primal statement is a general statement about vector spaces (using the permissible symbols) which is true even if each \( \mathcal{V}_i \) were replaced by \( \mathcal{V}_i^\perp \). Then, the ‘\( \perp - \)dual’ statement is true iff the primal statement is true. Clearly, this also follows from the basic results mentioned before.

What we have described is the most basic form of duality. Often for convenience one makes additional changes on the dual to retain some desirable property. A good example is the ‘transpose’. Recall that \( \mathcal{V}_{AB}^T \equiv (\mathcal{V}_{AB}^\perp)^{(A \rightarrow B)}. \) The adjoint defined in the next subsection is an extension of the same idea.

### 5.2. Adjoint duality

Adjoint dynamical systems have been natural constructs in mathematics and have been an important component of multivariable control theory, ever since Kalman’s seminal work [33]. In our notation all the essential features of the notion of adjoint come through in a neat way. We begin with the definition in this section and will describe the duality properties at appropriate places. In what follows we have omitted the brackets in a term like \((\mathcal{V}_{AB})^{(A \rightarrow B)}\) and written it more simply as \((\mathcal{V}_{AB})^{\rightarrow A}_{\rightarrow B}\).
Definition 27. Let \( \mathcal{V}_{\tilde{W}M} \) be a GDS. Let the set \( M \) be partitioned as \( M_a \sqcup M_y \). We define the adjoint of \( \mathcal{V}_{\tilde{W}M} \) as

\[
(\mathcal{V}_{\tilde{W}M})^a = \mathcal{V}_{\tilde{W}^aM_aM_y}^a \equiv (\mathcal{V}_{\tilde{W}M})^\perp - \tilde{W}^\perp M_y M_a,
\]

where \( W', \tilde{W}' \) are disjoint sets which are copies of \( W \) and \( M_a', M_y' \) are disjoint sets (also disjoint from \( W', \tilde{W}' \)), which are copies respectively of \( M_y, M_a \). The adjoint \( (\mathcal{V}_{\tilde{W}^aM_aM_y})^a \) of \( \mathcal{V}_{\tilde{W}^aM_aM_y} \) is defined to be on \( W \sqcup \tilde{W} \sqcup M_a \sqcup M_y \), with the same correspondence between primed and unprimed quantities as before.

Let \( \mathcal{V}_{\tilde{W}W} \) be a generalized autonomous system. We define its adjoint as

\[
(\mathcal{V}_{\tilde{W}W})^a \equiv (\mathcal{V}_{\tilde{W}})^a \equiv (\mathcal{V}_{\tilde{W}})^\perp \tilde{W}^\perp.
\]

The following theorem lists some routine properties of the adjoint which one expects should be true if the name ‘adjoint’ is to be appropriate.

Theorem 28. Let \( \mathcal{V}_{\tilde{W}M} \) be a GDS, let \( \mathcal{V}_{\tilde{W}W} \) be a vector space of the dynamic variables and let \( \mathcal{V}_{M_aM_y} \) be a vector space of the manifest variables. We have

1. \( \mathcal{V}_{\tilde{W}M} = (\mathcal{V}_{\tilde{W}W})^a \).

2. \( \mathcal{V}_{\tilde{W}W} = \mathcal{V}_{\tilde{W}} \iff \mathcal{V}_{M_aM_y} \)

3. \( \mathcal{V}_{\tilde{W}W} = (\mathcal{V}_{\tilde{W}})^a \).

4. \( \mathcal{V}_{\tilde{W}W} \) is a USG iff \( \mathcal{V}_{\tilde{W}W} \), is an LSG.

5. \( \mathcal{V}_{\tilde{W}W} \) is a genop iff \( \mathcal{V}_{\tilde{W}W} \), is a genop.

6. \( \mathcal{V}_{\tilde{W}W} \) is decoupled iff \( \mathcal{V}_{\tilde{W}W} \), is decoupled.

Proof. 1. We have

\[
(\mathcal{V}_{\tilde{W}W}M_aM_y)^a = (\mathcal{V}_{\tilde{W}M_aM_y})^\perp - \tilde{W}^\perp M_y M_a - \tilde{W} - M_a - M_y
\]

(noting that \( (\mathcal{V}_Z)^{-1} = \mathcal{V}_Z \)).

2. We have

\[
(\mathcal{V}_{\tilde{W}W})^a \equiv (\mathcal{V}_{\tilde{W}})^\perp \tilde{W}^\perp.
\]

So

\[
\mathcal{V}_{\tilde{W}W} \equiv \mathcal{V}_{\tilde{W}M_aM_y} \iff \mathcal{V}_{M_aM_y},
\]

iff

\[
\mathcal{V}_{\tilde{W}W} = (\mathcal{V}_{\tilde{W}M_aM_y} \iff \mathcal{V}_{M_aM_y})^\perp \tilde{W}^\perp.
\]
\[ = (V_{W\cdot M\cdot M_u})_{-W\cdot M'_u}^\perp \leftrightarrow (V_{M\cdot M_u})_{-M'_u}^\perp\]
i.e., iff
\[ V_{W\cdot W'} = V_{W\cdot M'_u M'_y}^\perp \leftrightarrow (V_{M\cdot M_u})_{-M'_u}^\perp.\]

3. Follows from the first part if we omit the \( M \) variables.

4. \( V_{W\cdot W} \) is USG iff
\[ V_{W\cdot W} \circ W \supseteq (V_{W\cdot W} \circ \tilde{W})_{W}.\]
i.e., iff
\[ ((V_{W\cdot W} \circ W)^\perp)_{W'} \subseteq ((V_{W\cdot W} \circ \tilde{W})^\perp)_{W'}.\]
i.e., iff
\[ (V_{W\cdot W}^\perp \times W)_{W'} \subseteq ((V_{W\cdot W}^\perp \times \tilde{W})_{W'}).\]
i.e., iff
\[ (V_{W\cdot W}^\perp \cdot W')_{W'} \subseteq ((V_{W\cdot W}^\perp \cdot \tilde{W})_{W'}).\]
i.e., iff
\[ V_{W\cdot W'}^\perp \cdot W' \subseteq (V_{W\cdot W'}^\perp \cdot W')_{W'}.\]
i.e., iff \( V_{W\cdot W'}^\perp \) is LSG.

5. Immediate from the previous part.

6. Follows immediately from the fact that \( (V_{W\cdot W}^\perp \oplus V_{W'}^\perp)^\perp = (V_{W\cdot W}^\perp)^\perp \oplus (V_{W'}^\perp)^\perp.\]

\[ \square \]

**Remark 6.** Statements about dynamical systems are naturally dualized using the adjoint operator which yields an adjoint system when applied to a dynamical system.

Parts 1 and 3 of Theorem 28 are basic for this purpose.

Parts 2 and 4 are typical instances of the dualization process.

In part 2, we are given that through the `↔` operation with a suitable linkage, an input-output GDS is converted into a GDS without manifest variables. Then, according to the result, through the `↔` operation with an appropriate ‘dual’ linkage, the adjoint input-output GDS is converted into the adjoint GDS without manifest variables. This makes `↔, ↔` a dual pair if we construct dual statements through the operation of taking adjoint, whereas, if the dual were constructed through the ‘⊥’ operation, then ‘↔, ⊥’ would form a dual pair.

5.2.1. Building the adjoint dual statement

The adjoint dual statement is built by constructing the adjoint based second statement and converting it later to the adjoint dual statement.

We construct the *adjoint based* second statement by first building the \( \perp - \) based second statement as outlined in Subsection 5.1.

Next we replace the index set
- \( W \) by \(-\tilde{W}'\),
- \( \tilde{W} \) by \( W'\),
- \( M_u \) by \(-M'_u\),
- \( M_y \) by \( M'_u\).
The adjoint based second statement can be rewritten as

Example 29. The adjoint based second statement of

\[(\mathcal{V}_W \bigoplus \mathcal{V}_{W,\hat{p}}^2) \leftrightarrow \mathcal{V}_{W,\hat{p}} \leftrightarrow (\mathcal{V}_{W,\hat{p}}^1 \leftrightarrow (\mathcal{V}_W^1 \leftrightarrow \mathcal{V}_W^2)_{\hat{p}} \supseteq \mathcal{V}_{W,\hat{p}} \leftrightarrow \mathcal{V}_W; \quad \mathcal{V}_{W,\hat{p}}^1 \supseteq (\mathcal{V}_{W,\hat{p}}^2)_{W,\hat{p}}. \]  

is

\[\{[\mathcal{V}_{W,\hat{p}}^1]_{W,\hat{p}}^1 \bigoplus (\mathcal{V}_{W,\hat{p}}^2)_{W,\hat{p}} \leftrightarrow (\mathcal{V}_W^1)_{W,\hat{p}} \leftrightarrow (\mathcal{V}_W^2)_{W,\hat{p}} \};\]

by

\[(\mathcal{V}_{W,\hat{p}}^1)_{W,\hat{p}} \subseteq \{[\mathcal{V}_{W,\hat{p}}^2]_{W,\hat{p}} \}_{W,\hat{p}}. \]  

The adjoint based second statement can be rewritten as

\[\{[\mathcal{V}_{W,\hat{p}}^1]_{W,\hat{p}} \bigoplus (\mathcal{V}_{W,\hat{p}}^2)_{W,\hat{p}} \leftrightarrow (\mathcal{V}_W^1)_{W,\hat{p}} \leftrightarrow (\mathcal{V}_W^2)_{W,\hat{p}} \};\]

by

\[(\mathcal{V}_{W,\hat{p}}^1)_{W,\hat{p}} \subseteq \{[\mathcal{V}_{W,\hat{p}}^2]_{W,\hat{p}} \}_{W,\hat{p}}. \]  

The adjoint dual statement is

\[([\mathcal{V}_{W,\hat{p}}^1]_{W,\hat{p}} \bigoplus (\mathcal{V}_{W,\hat{p}}^2)_{W,\hat{p}}) \leftrightarrow \mathcal{V}_W; \quad ([\mathcal{V}_{W,\hat{p}}^1]_{W,\hat{p}} \leftrightarrow (\mathcal{V}_W^1)_{W,\hat{p}} \subseteq ([\mathcal{V}_{W,\hat{p}}^2]_{W,\hat{p}} \leftrightarrow (\mathcal{V}_W^2)_{W,\hat{p}}); \quad \mathcal{V}_{W,\hat{p}}^1 \subseteq (\mathcal{V}_{W,\hat{p}}^2)_{W,\hat{p}}. \]  

5.2.2. Proof through duality

Suppose that the primal statement is true for arbitrary dynamical systems. Then the adjoint based second statement is also true for arbitrary dynamical systems and so will the adjoint dual be.

Typical ways of proving theorems through duality would be as described below.

Let \(A, B, C, D\) be statements of the kind

\[\epsilon(\mathcal{V}_1, \ldots, \mathcal{V}_k, +, \cap, \oplus, \circ, \times, \leftrightarrow, \neg, \supseteq, \subseteq, =)\]

Suppose we have a proof that \(A \implies B\). This is a statement always true for arbitrary vector spaces.

Let \(A, C\) form a primal-adjoint second pair and so also \(B, D\). Let \(A, C\) form a primal - adjoint dual pair and so also \(B, D\).

We then have a proof that \(C \implies D\), which is as follows:
Now \( C' \implies D' \) is a statement true for arbitrary vector spaces. So it will remain true if, in \( C' \) and \( D' \), every \( V \) is replaced by \( V' \), resulting in the statement \( C \implies D \), which is therefore proved to be true from the proof of \( A \implies B \).

**Remark 7.** Henceforth, we will denote adjoint dual by plain dual since it is the only kind of duality needed in dealing with dynamical systems. Similarly the adjoint based second statement will be denoted by plain second.

6. Invariant subspaces

Consider the system \( \mathcal{V}'_{W,M,M^t} \) defined through the equations

\[
\dot{w} = Aw + Bm, \\
m_y = Cw + Dm.
\]

We say that a subspace of states \( \mathcal{V}_W \) is conditioned invariant in this system if, once having entered it, we cannot leave it. We say it is controlled invariant in the system if, once it has entered it, we can prevent the system from leaving it.

In our framework we talk in terms of a genaut \( \mathcal{V}'_{W} = \mathcal{V}'_{W,M,M^t} \leftrightarrow \mathcal{V}_{M,M^t} \).

We say \( \mathcal{V}_W \) is **conditioned invariant** in \( \mathcal{V}'_{W} \) if

\[
\mathcal{V}'_{W} \leftrightarrow \mathcal{V}_W \subseteq (\mathcal{V}_W)'_W.
\]

We say \( \mathcal{V}_W \) is **controlled invariant** in \( \mathcal{V}'_{W} \) if

\[
\mathcal{V}'_{W} \leftrightarrow (\mathcal{V}_W)'_W \supseteq \mathcal{V}_W.
\]

If \( \mathcal{V}_W \) is both controlled and conditioned invariant, it is said to be **invariant** in \( \mathcal{V}'_{W} \).

The terms controlled invariant and conditioned invariant probably first appeared in [20]. These ideas appeared as \((A,B)\) invariance and its dual in [21]. Generalization of controllability and observability using invariant spaces is given in [22], [23], [24]. The concepts of conditioned and controlled invariants are also covered in the books [17], [16], and [26]. Controlled invariants have appeared in the context of bisimulation of linear dynamical systems and hybrid dynamical systems, cf. [19], [27], [28], [29].

For a detailed discussion of the ideas in this section illustrating how they are consistent with the conventional definitions of ‘controlled’ and ‘conditioned’ invariant subspaces as given in say [16], please see [12].

We present, in the next couple of paragraphs, a quick summary of the main ideas concerning such subspaces.

Given a subspace \( \mathcal{V}_{W}'_{\text{small}} \subseteq \mathcal{V}_{W}' \circ \mathcal{W} \), there is a unique minimal conditioned invariant subspace of \( \mathcal{V}_{\mathcal{W}'} \), that also contains \( (\mathcal{V}_{\text{small}})'_W \). The algorithm for the construction of this subspace is simple.

Take \( \mathcal{V}_{W}' = (\mathcal{V}_{\text{small}})'_W \). If \( \mathcal{V}_{\mathcal{W}'} \leftrightarrow \mathcal{V}_{W}' \subseteq \mathcal{V}_{\text{small}}'_{\mathcal{W}'} \), stop and take \( \mathcal{V}_{W}' \) to be the desired space.

Otherwise compute

\[
\mathcal{V}_{W}' = (\mathcal{V}_{\mathcal{W}'} \leftrightarrow \mathcal{V}_{W}'_{\text{small}})_{\mathcal{W}'} + \mathcal{V}_{W}'_{\text{small}}
\]

28
and so on until at some stage we have
\[ V_{W^i} \leftrightarrow V_{W^j} \subseteq V_{W^j}. \]

Let us call this subspace \( V_{W^j}^{final} \).

The algorithm will terminate because as long as the stopping criterion is not satisfied, the dimension of the subspaces \( V_{W^j} \) keeps increasing.

At every stage \( (V_{W^j}^i \downarrow) \subseteq V_{W^j} \circ \hat{W}^i \).

If the space \( V_{W^i} \) is USG, then \( V_{W^j} \) will also be a subspace of \( V_{W^j} \circ \hat{W}^i \).

This is sufficient for the controlled invariance condition to hold, namely
\[ V_{W^i} \leftrightarrow (V_{W^j}^{final})_{\hat{W}^i} \supseteq V_{W^j}^{final}. \]

When \( V_{W^j}^{M_{a,M_{b}}} \) is regular, we have that \( V_{W^i} \equiv V_{W^j}^{M_{a,M_{b}}} \circ \hat{W}^i \) is USG and if we take \( V_{W^j}^{final} \equiv V_{W^j} \circ \hat{W}^i \times \hat{W}^i \), then the invariant space \( V_{W^j}^{final} \) is the controllability subspace of \( (V_{W^j} \circ \hat{W}^i)_{\hat{W}^i} \).

The dual ideas are as follows. Given a subspace \( V_{W^j}^{large} \geq V_{W^j} \times \hat{W}^i \), there is a unique maximal controlled invariant subspace of \( V_{W^j} \) that is also contained in \( V_{W^j}^{large} \). The algorithm for the construction of this subspace is simple.

Take \( V_{W^j} \equiv (V_{W^j}^{large})_{\hat{W}^i} \). If \( V_{W^j} \leftrightarrow V_{W^j}^{1} \supseteq V_{W^j}^{large} \), stop and take \( V_{W^j}^{1} \) to be the desired space.

Otherwise compute \( V_{W^j}^{2} \equiv (V_{W^j} \leftrightarrow V_{W^j}^{1}) \cap V_{W^j}^{1} \) and so on until at some stage we have
\[ V_{W^j} \leftrightarrow V_{W^j}^{j} \supseteq V_{W^j}. \]

Let us call this subspace \( V_{W^j}^{final} \).

The algorithm will terminate because as long as the stopping criterion is not satisfied, the dimension of the subspaces \( V_{W^j} \) keeps decreasing.

At every stage \( V_{W^j} \supseteq V_{W^j} \times \hat{W}^i \).

If the space \( V_{W^j} \) is LSG, then \( V_{W^j}^{final} \) will also be a superspace of \( V_{W^j} \times \hat{W}^i \).

This is sufficient for the conditioned invariance condition to hold, namely
\[ V_{W^i} \leftrightarrow V_{W^j}^{final} \subseteq V_{W^j}^{final}. \]

When \( V_{W^j}^{M_{a,M_{b}}} \) is regular, we have that \( V_{W^i} \equiv V_{W^j}^{M_{a,M_{b}}} \times \hat{W}^i \) is LSG and if we take \( V_{W^j}^{large} \equiv V_{W^j} \circ \hat{W}^i \), then the invariant space \( V_{W^j}^{final} \) is the observability superspace of \( V_{W^j} \times \hat{W}^i \).

Conventionally, this would be a quotient space over the unobservable subspace of the system.

We need the following results for the development of the present paper.

Theorem 30 brings out the duality between conditioned and controlled invariance.

Theorem 31 stresses a necessary condition that conditioned invariant subspaces must satisfy and points out that a genop arises naturally from a conditioned invariant space in a USG.

Theorem 32 states the dual.

These results are counterparts of the controllable subspace and observable quotient space of multivariable control theory.

**Theorem 30.** \( V_{W^i} \) is conditioned (controlled) invariant in \( V_{W^j} \) if \( V_{W^i} \equiv V_{W^j} \circ \hat{W}^i \).
Proof. By Theorem 1 of the textbook, we have that

\[ \mathcal{V}_{\dot{W}} = \mathcal{V} \subseteq \mathcal{V}_{\ddot{W}} \]

iff

\[ \mathcal{V}_{\dot{W}}^\perp = \mathcal{V}_{\ddot{W}}^\perp \]

i.e., iff

\[ (\mathcal{V}_{\dot{W}})^{\perp} \cap W' \equiv (\mathcal{V}_{\ddot{W}})^{\perp} \cap W' \]

i.e., iff

\[ \mathcal{V}_{\ddot{W}} \equiv (\mathcal{V}_{\ddot{W}}^a)_{W'}, \]

Thus \( \mathcal{V}_{W'} \) is conditioned invariant in \( \mathcal{V}_{\ddot{W}} \) iff \( \mathcal{V}_{\ddot{W}}^a \) is conditioned invariant in \( \mathcal{V}_{\ddot{W}} \).

The ‘controlled in primal’ to ‘conditioned in dual’ part of the theorem follows from the fact that for any vector space \( V \), \( (V)^{\perp} = V \), and for any \( \mathcal{V}_{\ddot{W}} \), we have

\[ \mathcal{V}_{\ddot{W}} = (\mathcal{V}_{\ddot{W}}^a)_{W'} \]

\[ \Box \]

Theorem 31. Let \( \mathcal{V}_{\ddot{W}} \) be a genaut and let \( \mathcal{V}_{W} \) be conditioned invariant in \( \mathcal{V}_{\ddot{W}} \). Then

1. \( \mathcal{V}_{W} \supseteq (\mathcal{V}_{\ddot{W}} \times \hat{W})_{W} \).
2. If \( \mathcal{V}_{\ddot{W}} \) is a USG, we must have \( \mathcal{V}_{\ddot{W}} \cap (\mathcal{V}_{W} \oplus (\mathcal{V}_{\ddot{W}})_{W}) \) is a genop.

Proof. 1. By conditioned invariance of \( \mathcal{V}_{W} \) in \( \mathcal{V}_{\ddot{W}} \), and by Theorem 2 of the textbook, it follows that

\[ \mathcal{V}_{\ddot{W}} \equiv \mathcal{V}_{\ddot{W}} \cap \mathcal{V}_{W} \; \equiv \; \mathcal{V}_{\ddot{W}} \times \hat{W} \]

Therefore we have

\[ \mathcal{V}_{W} \supseteq (\mathcal{V}_{\ddot{W}} \times \hat{W})_{W} \]

2. We have,

\[ [\mathcal{V}_{\ddot{W}} \cap (\mathcal{V}_{W} \oplus (\mathcal{V}_{\ddot{W}})_{W})] \cap W = \mathcal{V}_{\ddot{W}} \cap W \]

and

\[ [\mathcal{V}_{\ddot{W}} \cap (\mathcal{V}_{W} \oplus (\mathcal{V}_{\ddot{W}})_{W})] \cap \hat{W} = \mathcal{V}_{\ddot{W}} \cap \hat{W} \]

Since \( \mathcal{V}_{\ddot{W}} \) is a USG it follows that \( (\mathcal{V}_{\ddot{W}} \cap W)_{W} \supseteq \mathcal{V}_{\ddot{W}} \cap \hat{W} \). Hence

\[ (\mathcal{V}_{\ddot{W}} \cap (\mathcal{V}_{W} \oplus (\mathcal{V}_{\ddot{W}})_{W})] \cap W \supseteq (\mathcal{V}_{\ddot{W}} \cap (\mathcal{V}_{W} \oplus (\mathcal{V}_{\ddot{W}})_{W})] \cap \hat{W} \]

Next we will show that

\[ (\mathcal{V}_{\ddot{W}} \cap (\mathcal{V}_{W} \oplus (\mathcal{V}_{\ddot{W}})_{W}] \times W)_{W} \supseteq (\mathcal{V}_{\ddot{W}} \cap (\mathcal{V}_{W} \oplus (\mathcal{V}_{\ddot{W}})_{W}] \times \hat{W} \]

Let \( g_{\ddot{W}} \) belong to the RHS of the above containment. This means there exists

\( (f_{\ddot{W}}, g_{\ddot{W}}') \in \mathcal{V}_{\ddot{W}} \) and \( (-f_{\ddot{W}}, g_{\ddot{W}}') \in \mathcal{V}_{\ddot{W}} \oplus (\mathcal{V}_{\ddot{W}})_{W} \), such that \( g_{\ddot{W}}' + g_{\ddot{W}}' = g_{\ddot{W}} \).

Thus \( f_{\ddot{W}} \in \mathcal{V}_{\ddot{W}} \), \( g_{\ddot{W}}' \in \mathcal{V}_{\ddot{W}} \) and \( g_{\ddot{W}}' \in \mathcal{V}_{\ddot{W}} \).

Thus \( g_{\ddot{W}} \in (\mathcal{V}_{\ddot{W}})_{W} \) and therefore \( g_{W} \in \mathcal{V}_{W} \).

Now, if \( g_{W} \in \mathcal{V}_{W} \) then \( (g_{W}, 0_{W}) \in \mathcal{V}_{\ddot{W}} \cap (\mathcal{V}_{W} \oplus (\mathcal{V}_{\ddot{W}})_{W}) \).

We conclude that \( g_{W} \in \mathcal{V}_{\ddot{W}} \cap (\mathcal{V}_{W} \oplus (\mathcal{V}_{\ddot{W}})_{W}] \times W \).
Hence, it is clear that
\[
(V_W \oplus (V_W)_W)[W \times W] \supseteq [V_W + (V_W \oplus (V_W)_W)] \times W,
\]
and therefore that \(V_{W\hat{W}} + (V_W \oplus (V_W)_W)\) is a genop.

The next result is the dual of Theorem 31. A detailed proof illustrating the use of duality is given in Appendix B.

**Theorem 32.** Let \(V_{W\hat{W}}\) be a genaut and let \(V_W\) be controlled invariant in \(V_{W\hat{W}}\). Then

1. \(V_W \subseteq V_{W\hat{W}} \circ W\).
2. If \(V_{W\hat{W}}\) is an LSG, \(V_{W\hat{W}} \cap (V_W \oplus (V_W)_W)\) is a genop.

7. **wm\(_u\) - Feedback and \(m_y\) \(\hat{w}\) - Injection**

In this section we present the central results about the genops that can be obtained by state feedback and output injection from a dynamical system \(V_{W\hat{W},M,W,M}\). The two operations are denoted by \(wm_u\) - feedback and \(m_y\) \(\hat{w}\) - injection. Essentially, we characterize in a simple manner, which genaut \(V_{W\hat{W}}\) can be obtained from a given dynamical system \(V_{W\hat{W},M,W,M}\) by \(wm_u\) - feedback and \(m_y\) \(\hat{w}\) - injection. For comparing with a standard treatment of this subject the reader may consult \[17\], \[16\].

**Definition 33.** Let \(V_{W\hat{W},M,W,M}\) be a GDS and \(V_{W,M,W,M}\) be a linkage. We say that the generalized autonomous system \(V_{W\hat{W}}\) is obtained from \(V_{W\hat{W},M,W,M}\) by \(wm_u\) - feedback through \(V_{W,M,W,M}\) iff

\[
V_{W\hat{W}} = (V_{W\hat{W},M,W,M} \cap V_{W,M,W,M}) \circ W \hat{W}.
\]

**Definition 34.** Let \(V_{W\hat{W},M,W,M}\) be a GDS and \(V_{W,M,W,M}\) be a linkage. We say that the generalized autonomous system \(V_{W\hat{W}}\) is obtained from \(V_{W\hat{W},M,W,M}\) by \(m_y\) \(\hat{w}\) - injection through \(V_{W,M,W,M}\) iff

\[
V_{W\hat{W}} = (V_{W\hat{W},M,W,M} + V_{W,M,W,M}) \times W \hat{W}.
\]

We relate these ideas to the corresponding notions in classical control. Consider the system described by

\[
\begin{align*}
\dot{w} &= Aw + Bm_u, \\
m_y &= Cw + Dm_u.
\end{align*}
\]

The space of solutions \(V_{W\hat{W},M,W,M}\) is (taking \(\lambda_1, \lambda_2\) to be free vectors of appropriate dimension)

\[
\begin{align*}
w &= \lambda_1, \\
\dot{w} &= A\lambda_1 + B\lambda_2, \\
m_u &= \lambda_2, \\
m_y &= C\lambda_1 + D\lambda_2.
\end{align*}
\]

The \(wm_u\) - feedback (state feedback) equations are

\[
m_u = Fw,
\]
with the space of solutions $V_{WM_y}$ given by

$$m_y = F\lambda_1$$
$$w = \lambda_1.$$

The space $(V_{WM_y} \cap V_{WM_y}) \circ W \dot{W}$ is

$$w = \lambda_1$$
$$\dot{w} = (A + BF)\lambda_1.$$

The $m_y \dot{w}$ injection (output injection) equations are

$$\dot{w} = Km_y,$$
with the space of solutions $V_{WM_y}$ given by

$$m_y = \sigma$$
$$\dot{w} = K\sigma.$$

The space $(V_{WM_y} \cap V_{WM_y}) \times W \dot{W}$ is obtained as

$$w = \lambda_1$$
$$\dot{w} = A\lambda_1 + B0 + K\sigma$$
$$m_u = 0$$
$$m_y = 0 = C\lambda_1 + D0 + \sigma,$$
which simplifies to

$$\dot{w} = (A - KC)w.$$

The natural problems that arise through these operations are

'given $V_{WM_y}$ and $V_{WM_y}$, can we find $V_{WM_y}$ so that $V_{WM_y} = (V_{WM_y} \cap V_{WM_y}) \circ W \dot{W}$ and, assuming it exists, under what conditions is it unique?'

'given $V_{WM_y}$ and $V_{WM_y}$, can we find $V_{WM_y}$ so that $V_{WM_y} = (V_{WM_y} \cap V_{WM_y}) \times W \dot{W}$ and, assuming it exists, under what conditions is it unique?'

We solve these problems in Theorem 37 and Theorem 38.

We begin with a result which states that $wm_u$ feedback and $m_y \dot{w}$ injection are duals.

**Theorem 35.** We have

$$V_{WM_y} = (V_{WM_y} \cap V_{WM_y}) \circ W \dot{W}$$

iff

$$V_{WM_y} = (V_{WM_y} \cap V_{WM_y}) \times W \dot{W}.'$$

**Proof.**
We have
\[ \mathcal{V}_{W'} = (\mathcal{V}_{W',M_y,M_y} \cap \mathcal{V}_{W,M_0}) \circ W \hat{W}; \]
iff
\[ \mathcal{V}_{W',W'} = (\mathcal{V}_{W'}^\perp)_{W',W'} = ((\mathcal{V}_{W',M_y,M_y} \cap \mathcal{V}_{W,M_0}) \circ W \hat{W})^\perp_{W',W'}, \]
i.e. iff
\[ \mathcal{V}_{W',W'} = ((\mathcal{V}_{W',M_y,M_y} \cap \mathcal{V}_{W,M_0})^\perp_{W',W'} - W') \times W', \]
i.e. iff
\[ \mathcal{V}_{W',W'} = ((\mathcal{V}_{W',M_y,M_y}^\perp)_{W',W'} - W') \times W', \]
i.e. iff
\[ \mathcal{V}_{W',W'} = ((\mathcal{V}_{W',M_y,M_y}^\perp)_{W',W'} + (\mathcal{V}_{W,M_0}^\perp)_{W',W'}) \times W'. \]

We will next show that both the above, feedback and injection operations, can be reduced to the ‘↔’ operation through a simple trick. We remind the reader that \( I_{W,W'} \) refers to the space of all \((f_W,f_{W'})\), where \(W,W'\) are copies of each other.

**Lemma 36.**

1. \[
(\mathcal{V}_{W',M_y,M_y} \cap \mathcal{V}_{W,M_0}) \circ W \hat{W} = [(\mathcal{V}_{W',M_y,M_y} \cap I_{W,W'}) \leftrightarrow (\mathcal{V}_{W,M_0} \oplus F_{my})]_{W,\hat{W}}.
\]

2. \[
(\mathcal{V}_{W',M_y,M_y} + \mathcal{V}_{W,M_y}) \times W \hat{W} = [(\mathcal{V}_{W',M_y,M_y} + I_{W,(-W')}) \leftrightarrow (\mathcal{V}_{W,M_y} \oplus 0_{mu})]_{W,\hat{W}}.
\]

**Proof.**

1. Let \((f_W,g_{\hat{W}})\) \in \text{LHS}.

Then there exist \(h_{M_0},h_{M_y}\) such that \((f_W,g_{\hat{W}},h_{M_0},h_{M_y}) \in \mathcal{V}_{W',M_y,M_y}, (f_W,h_{M_0}) \in \mathcal{V}_{W,M_0}.

Hence we must have
\[
(f_W,g_{\hat{W}},h_{M_0},h_{M_y}) \in \mathcal{V}_{W',M_y,M_y}, (f_W,f_{W'}) \in I_{W,W'}, (f_W,h_{M_0}) \in \mathcal{V}_{W,M_0},
\]
so that
\[
(f_W,g_{\hat{W}}) \in [(\mathcal{V}_{W',M_y,M_y} \cap I_{W,W'}) \leftrightarrow (\mathcal{V}_{W,M_0} \oplus F_{my})]
\]
and therefore
\[
(f_W,g_{\hat{W}}) \in [(\mathcal{V}_{W',M_y,M_y} \cap I_{W,W'}) \leftrightarrow (\mathcal{V}_{W,M_0} \oplus F_{my})]_{W,\hat{W}} = \text{RHS}.
\]

Next, let \((f_W,g_{\hat{W}})\) \in \text{RHS}.

Then
\[
(f_W,g_{\hat{W}}) \in [(\mathcal{V}_{W',M_y,M_y} \cap I_{W,W'}) \leftrightarrow (\mathcal{V}_{W,M_0} \oplus F_{my})]
\]
and therefore there exist \(h_{M_0},h_{M_y}\) such that
\[
(f_W,g_{\hat{W}},h_{M_0},h_{M_y}) \in \mathcal{V}_{W',M_y,M_y}, (f_W,f_{W'}) \in I_{W,W'}, (f_W,h_{M_0}) \in \mathcal{V}_{W,M_0}.
\]
Thus
\[(f_W; g_{\hat{W}}, h_{\hat{M}_u}, h_{\hat{M}_y}) \in \mathcal{V}_{W\hat{W}M_a^aM_y^a}, (f_W, h_{M_a}) \in \mathcal{V}_{W M_a},\]
so that \((f_W; g_{\hat{W}}) \in \text{LHS}.

2. This is dual to the previous part of the present lemma. Detailed proof given in Appendix B.

\[\square\]

**Remark 8.** One may visualize \((\mathcal{V}_{W\hat{W}M_a^aM_y^a} \cap I_{W\hat{W}})\) as the collection of all \((f_W, f_{\hat{W}}; g_{\hat{W}}, h_{m_a}, k_{m_y})\), where \((f_W; g_{\hat{W}}, h_{m_a}, k_{m_y}) \in \mathcal{V}_{W\hat{W}M_a^aM_y^a}\). Thus
\[
(V_{W\hat{W}M_a^aM_y} \cap I_{W\hat{W}}) \circ W\hat{W} M_a M_y = V_{W\hat{W}M_a^aM_y},
\]
\[
(V_{W\hat{W}M_a^aM_y} \cap I_{W\hat{W}}) \times W'\hat{W} M_a M_y = 0_{W'} \oplus V_{W\hat{W}M_a^aM_y} \times W' M_a M_y.
\]
\[
(V_{W\hat{W}M_a^aM_y} \cap I_{W\hat{W}}) \circ W\hat{W'} M_a \times W'\hat{W} = (V_{W\hat{W}M_a^aM_y} \cap I_{W\hat{W}}) \times W'\hat{W} M_a \circ W'\hat{W} = 0_{W'} \oplus V_{W\hat{W}M_a^aM_y} \circ W\hat{W} M_a \times W'.
\]

**Theorem 37.** Given \(V_{W\hat{W}M_a^aM_y}, V_{W\hat{W}}\), there exists \(V_{W M_a}\) such that
\[
(V_{W\hat{W}M_a^aM_y} \cap V_{W M_a}) \circ W\hat{W} = V_{W\hat{W}}
\]
iff
\[
V_{W\hat{W}M_a^aM_y} \circ W W' \hat{W} \supseteq V_{W\hat{W}}; \quad V_{W\hat{W}M_a^aM_y} \circ W W'\hat{W} M_a \times W' \hat{W} \subseteq V_{W\hat{W}} \times W'.
\]
Further, if such \(V_{W M_a}\) exists, it is unique under the condition
\[
V_{W\hat{W}M_a^aM_y} \circ W M_a \supseteq V_{W M_a}; \quad V_{W\hat{W}M_a^aM_y} \circ W W'\hat{W} M_a \times M_a \subseteq V_{W M_a} \times M_a
\]
and is equal to
\[
(V_{W\hat{W}M_a^aM_y} \cap V_{W\hat{W}}) \circ W M_a.
\]

**Proof.** Let us denote \(V_{W\hat{W}M_a^aM_y} \cap I_{W\hat{W}}\) by \(V_{W\hat{W}W M_a^aM_y}\); and \((V_{W\hat{W}} \cap I_{W\hat{W}}) \circ W' \hat{W}\) by \(V_{W'\hat{W}}\).

Thus, by Lemma [36], we need to examine the conditions under which there exists \(V_{W M_a}\) such that
\[
V_{W W'\hat{W} M_a^aM_y} \leftrightarrow (V_{W M_a} \oplus F_{M_a}) = V_{W'\hat{W}}, \ i.e., \ V_{W W'\hat{W} M_a^aM_y} \circ W W'\hat{W} M_a \leftrightarrow V_{W M_a} = V_{W'\hat{W}}.
\]
By Theorem [2], this happens if
\[
(a) V_{W W'\hat{W} M_a^aM_y} \circ W W'\hat{W} M_a \circ W W' \supseteq V_{W'\hat{W}}, \ i.e., \ V_{W W'\hat{W} M_a^aM_y} \circ W W' \circ W' \hat{W} \supseteq V_{W'\hat{W}}; \quad i.e., \ V_{W W'\hat{W} M_a^aM_y} \circ W \hat{W} \supseteq V_{W'\hat{W}}.
\]
and
\[
(b) V_{W W'\hat{W} M_a^aM_y} \circ W W'\hat{W} M_a \times W' \hat{W} \subseteq V_{W'\hat{W}}.
\]
The condition (a) is one of the conditions in Equation [18].

We now examine (b).
It is clear from Remark 8 that

\[ V_{WW'M_u,M_y} \circ W' \hat{W} M_u \times W' \hat{W} = 0_{W' \circ V_{WW'M_u,M_y}} \circ W' \hat{W} M_u \times W' = 0_{W' \circ V_{WW'M_u,M_y}} \circ W' \hat{W} M_u \times W'. \]

Therefore,

\[ V_{WW'M_u,M_y} \circ W' \hat{W} M_u \times W' \hat{W} \leq V_{WW'} \]

iff \( 0_W \oplus V_{WW'M_u,M_y} \circ W' \hat{W} M_u \times W' \hat{W} \leq 0_W \oplus V_{WW'} \times W' \hat{W}; \) i.e., iff \( V_{WW'M_u,M_y} \circ W' \hat{W} M_u \times W' \hat{W} \leq V_{WW'} \times W', \)

yielding the second condition in Equation 18.

Next, again by Theorem 2, if such \( V_{W,M_u} \) exists, it is uniquely obtained as

\[ (((V_{W,M_u} \cap I_{W'}) \circ W' W' \hat{M}_u) \leftrightarrow V_{W,M_u})_{W,M_u}, \]

under the conditions

\[ V_{WW'M_u,M_y} \circ W' M_u \geq V_{W,M_u} \text{ and } V_{WW'M_u,M_y} \circ W' \hat{W} M_u \times W M_u \leq V_{W,M_u}. \]

The first condition is equivalent to \( V_{W,M_u} \circ W M_u \geq V_{W,M_u}. \)

We simplify the second condition noting that

\[ V_{WW'M_u,M_y} \circ W' \hat{W} M_u \times W M_u = 0_W \oplus V_{WW'M_u,M_y} \circ W' \hat{W} M_u \times M_u = 0_W \oplus V_{WW'M_u,M_y} \circ W' \hat{W} M_u \times M_u. \]

Thus,

\[ V_{WW'M_u,M_y} \circ W' \hat{W} M_u \times W M_u \leq V_{W,M_u}, \]

iff

\[ 0_W \oplus V_{WW'M_u,M_y} \circ W \hat{W} M_u \times M_u \leq 0_W \oplus V_{W,M_u} \times M_u, \]

i.e., iff

\[ V_{WW'M_u,M_y} \circ W \hat{W} M_u \times M_u \leq V_{W,M_u} \times M_u. \]

The next theorem is dual to the previous result.

**Theorem 38.** Given \( V_{WW'M_u,M_y} \) \( V_{W,M_u} \), there exists \( V_{W,M_y} \) such that

\[ (V_{W,M_u} \cap V_{W,M_y}) \circ W \hat{W} = V_{W,M_y} \]

iff

\[ V_{W,M_u} \times W \hat{W} \leq V_{W,M_y}; \quad V_{W,M_u} \times W \hat{W} M_y \circ W \geq V_{W,M_y} \circ M_y. \]  

(16)

Further, if such \( V_{W,M_y} \) exists, it is unique under the condition

\[ V_{W,M_u} \times W \hat{W} M_y \leq V_{W,M_y}; \quad V_{W,M_u} \times W \hat{W} M_y \circ M_y \geq V_{W,M_y} \circ M_y \]

and is equal to \( (((V_{W,M_u} + I_{W}(-W')) \times W \hat{W} M'_y) \leftrightarrow V_{W,M_y})_{W,M_y} = (V_{W,M_u} + V_{W,M_y}) \times \hat{W} M_y. \)
Proof. We will merely identify dual pairs of statements for the existence case. The uniqueness is handled similarly.

Let statement $A$ denote

Given $\mathcal{V}_{\hat{W}M,\hat{m}}\cdot \mathcal{V}_{\hat{W}}$, there exists $\mathcal{V}_{W,M}$ such that

$$(\mathcal{V}_{\hat{W}M,M_u} \cap \mathcal{V}_{W,M}) \circ \hat{W} = \mathcal{V}_{\hat{W}}.$$  

Let statement $B$ denote

$$\mathcal{V}_{\hat{W}M,M_u} \circ \hat{W} \supseteq \mathcal{V}_{W,M_u}; \mathcal{V}_{\hat{W}M,M_u} \circ \hat{W} \times \hat{W} \subseteq \mathcal{V}_{W,M} \times \hat{W}. \quad (18)$$

Let statement $C$ denote

Given $\mathcal{V}_{W,M,\hat{m}}, \mathcal{V}_{W}$, there exists $\mathcal{V}_{\hat{W}M}$ such that

$$(\mathcal{V}_{\hat{W}M,M} + \mathcal{V}_{\hat{W}M}) \times \hat{W} = \mathcal{V}_{W}.$$  

Let statement $D$ denote

$$\mathcal{V}_{\hat{W}M,M} \times \hat{W} \subseteq \mathcal{V}_{W}; \mathcal{V}_{\hat{W}M,M} \times \hat{W} \subseteq \mathcal{V}_{W,M} \circ \hat{W} \supseteq \mathcal{V}_{W} \circ \hat{W}. \quad (19)$$

It can be seen that $(A,C)$ is a dual pair of statements and so also $(B,D)$. We have $A \implies B$.

By the argument in Subsection 5.2.2 $C \implies D$.  

8. Polynomials of generalized autonomous systems

8.1. Motivation

In this section we present the main definitions and results concerning polynomials of generalized operators (genops). It is possible to define polynomials even for the more general case of generalized autonomous systems (genauts). So we begin with this definition. But for genuats the usual factorisation of polynomials and the remainder theorem do not hold. Fortunately, however, these ideas go through neatly for genops and in Theorem 50 we present such a result and conclude from it the analogue, for generalized operators, of the uniqueness of the minimal annihilating polynomial of an operator. Some unusual notions are needed - for instance a zero is essentially a decoupled linkage (recall $\mathcal{V}_{AB}$ is decoupled iff $\mathcal{V}_{AB} \circ A \oplus \mathcal{V}_{AB} \circ B$).

Theorems 51, 58 contain the analogues of the usual results related to controllability and unobservability spaces in classical multivariable control theory.

We give a sketch of the results in terms of a state variable description. Let $\mathcal{V}_{W,M,M}$ be the dynamical system given below.

$$\dot{w} = Aw + Bm_u, \quad \dot{m}_y = Cw + Dm_u. \quad (20a)$$

Let $\mathcal{V}_{W} = \mathcal{V}_{W,M,M} \circ W\hat{W}$. We can see that $\mathcal{V}_{W} \circ W$ is $\mathcal{F}_W$ and $\mathcal{V}_{W} \circ \hat{W}$ is the range of the matrix $A$. Therefore $\mathcal{V}_{W}$ is USG. On the other hand, $\mathcal{V}_{W,\hat{W}} \times W$ is the inverse image under $A$ of the range of the matrix $B$ while $\mathcal{V}_{W,\hat{W}} \times \hat{W}$ is the range of the matrix $B$. Thus, in general $\mathcal{V}_{W,\hat{W}} \times W$ does not contain $(\mathcal{V}_{W,\hat{W}} \times \hat{W})_W$. So $\mathcal{V}_{W,\hat{W}}$ may not be a genop. If one performs state feedback on this system we will get a system $\mathcal{V}_{W}$ governed by

$$\dot{w} = (A + BF)w. \quad (21a)$$
Clearly, $V_{W\hat{W}}$ is a genop. Classical multivariable theory tells us that there are two important maps associated with $V_{W\hat{W}}$. The first is obtained by restricting the map $A + BF$ to the controllability space $V_W$ (in general any invariant space containing $V_W^u \times \hat{W}$). This is the genop $V_{W\hat{W}} \cap (V_W \oplus (V_W)_W)$ in Theorem 51. The second is a map obtained by quotienting the map $A + BF$ over $V_W$. This map depends only on $V_{W\hat{W}}^l$ and does not change under state feedback. This is the genop $V_{W\hat{W}}^l + (V_W)_W$ of Theorem 58.

Theorem 58 talks of the dual situation. Let us begin with $V_{W\hat{W}}^l = \{ V_{W\hat{W}}^l \circ W \}$. We can see that $V_{W\hat{W}}^l \circ W$ is the image under $A$ of the null space of $C$ while $V_{W\hat{W}}^l \circ W$ is the null space of the matrix $C$. Thus, in general $(V_{W\hat{W}}^l \circ W)$ is not contained in $V_{W\hat{W}}^l \circ W$. So $V_{W\hat{W}}^l$ may not be a genop. If one performs output injection on this system we will get a system $V_{W\hat{W}}^l$ governed by

$$\dot{w} = (A - KC)w.$$  \hfill (22a)

Clearly, $V_{W\hat{W}}^l$ is a genop. Classical multivariable theory tells us that there are two important maps associated with $V_{W\hat{W}}$. The first is obtained by quotienting the map $A - KC$ over the unobservability space $V_W$ (in general any invariant space contained in $V_{W\hat{W}}^l \circ W$). This is the genop $V_{W\hat{W}}^l + (V_W \oplus (V_W)_W)$ in Theorem 51. The second is a map obtained by restricting the map $A - KC$ to $V_W$. This map depends only on $V_{W\hat{W}}^l$ and does not change under output injection. This is the genop $V_{W\hat{W}}^l \cap V_W$ of Theorem 58.

We reiterate that our aim is to talk of the above situation without making explicit use of state equations. Later in Section 10 we define the notion of emulators which will very efficiently play the role of state equations. We will illustrate the use of these notions through RLC networks.

8.2. Polynomials of genauts and genops

To define the notion of polynomials of genauts we require the definition of sum, scalar multiplication and ‘operator’ multiplication. These are captured respectively by ‘+$,$’ ‘$\lambda^k,$’ and ‘*$’ operations. The ‘*$’ operation is built in terms of ‘$\leftrightarrow$’ operation and is defined below.

**Definition 39.** Let $V_{W\hat{W}}, V_{W\hat{W}}'$ be generalized autonomous systems. We define

$$V_{W\hat{W}} \ast V_{W\hat{W}}' \equiv (V_{W\hat{W}} \circ W) W_1 \leftrightarrow (V_{W\hat{W}}') W_1 \hat{W}.$$  

In the case of an operator $A$, if $V_{W\hat{W}}$ is the collection of all $(x^T, y^T)$ such that $x^T A = y^T$, then $V_{W\hat{W}}^2$ is the collection of all $(x^T, y^T)$ such that $x^T A^2 = y^T$.

Note that in the above definition, in the case of $V_{W\hat{W}}$, the ‘dummy’ set $W_1$ is treated as a copy of $W$, and in the case of $V_{W\hat{W}}'$, as a copy of $W$. This operation is associative, if we introduce disjoint dummy sets whenever required. Consider the expression

$$V_{W\hat{W}}^1 \ast V_{W\hat{W}}^2 \ast V_{W\hat{W}}^3 \ast \ldots \ast V_{W\hat{W}}^{n-1} \ast V_{W\hat{W}}^n \ast W_{\hat{W}}.$$  

This could be treated as

$$(V_{W\hat{W}}^1 W_1) W_2 \leftrightarrow (V_{W\hat{W}}^2 W_1) W_2 \leftrightarrow \ldots \leftrightarrow (V_{W\hat{W}}^{n-1} W_1) W_{n-2} \leftrightarrow (V_{W\hat{W}}^n W_1) W_{n-1} \hat{W},$$

where all the $W_i$ can be treated as disjoint from each other and from each of $W, \hat{W}$. It then follows from Theorem 7 that the meaning of the expression with ‘*$’ is independent of where brackets are introduced, i.e., the ‘*$’ operation is associative.

We now define polynomials of genauts.
Definition 40. Let $\mathcal{V}_{W^\prime}^W$ be a genaut. We define

$$
\mathcal{V}_{W^\prime}^{W(0)} = I_{W^\prime} + \omega [\mathcal{V}_{W^\prime}^W \circ W \oplus \mathcal{V}_{W^\prime}^W \times \hat{W}].
$$

$$
\mathcal{V}_{W^\prime}^{W(1)} = \mathcal{V}_{W^\prime}^W.
$$

$$
\mathcal{V}_{W^\prime}^{W(k)} = (\mathcal{V}_{W^\prime}^{W(k-1)})^* \mathcal{V}_{W^\prime}^W, \quad k = 2, \ldots.
$$

(By associativity of * operation $\mathcal{V}_{W^\prime}^{W(k)} \equiv (\mathcal{V}_{W^\prime}^{W(k-j)} \mathcal{V}_{W^\prime}^W)^{(j)}, \quad j = 1, 2, \ldots, k - 1.$)

Remark 9. Note that $\mathcal{V}_{W^\prime}^{W(0)} \times W$ does not in general contain $\mathcal{V}_{W^\prime}^W \times W$ and $\mathcal{V}_{W^\prime}^{W(0)} \circ \hat{W}$ is not in general contained in $\mathcal{V}_{W^\prime}^W \circ \hat{W}$.

In general, for a genaut $\mathcal{V}_{W^\prime}^W$, it would not be true that $\mathcal{V}_{W^\prime}^W \mathcal{V}_{W^\prime}^{W(0)}$ is equal to $\mathcal{V}_{W^\prime}^W$. But this would be true for genops (part 5 of Lemma 46), which is adequate for our purposes.

The definition of $\mathcal{V}_{W^\prime}^{W(0)}$ is as given so that, while being similar to the identity operator, it shares some desirable properties with other polynomials of $\mathcal{V}_{W^\prime}^W$. The characteristic properties of $\mathcal{V}_{W^\prime}^{W(0)}$, for the most important situation, are listed in the following lemma.

Lemma 41. Let $(\mathcal{V}_{W^\prime}^W \circ W)_{W^\prime} \supseteq \mathcal{V}_{W^\prime}^W \times \hat{W}$. Then

1. $\mathcal{V}_{W^\prime}^W \circ W = \mathcal{V}_{W^\prime}^{W(0)} \circ W = (\mathcal{V}_{W^\prime}^{W(0)} \circ \hat{W})_W$.
   $\mathcal{V}_{W^\prime}^W \times \hat{W} = (\mathcal{V}_{W^\prime}^{W(0)} \times W)_W = (\mathcal{V}_{W^\prime}^{W(0)} \times \hat{W})_W$.

2. $$(f_W, g_W) \in \mathcal{V}_{W^\prime}^{W(0)}, \quad f_W \in \mathcal{V}_{W^\prime}^W \circ W, \quad g_W \in (f_W + \mathcal{V}_{W^\prime}^W \times \hat{W}),$$
   i.e., iff
   $$g_W \in (\mathcal{V}_{W^\prime}^W \circ W)_W, \quad f_W \in (g_W + \mathcal{V}_{W^\prime}^W \times \hat{W})_W.$$!

3. $\mathcal{V}_{W^\prime}^{W(0)}$ is a genop.

4. $(\mathcal{V}_{W^\prime}^{W(0)})^a = (\mathcal{V}_{W^\prime}^{W(0)})^{(0)}$.

Definition 42. Let $\mathcal{V}_{W^\prime}^W$ be a genaut and let $p(s) = \Sigma^\alpha \alpha_i^s$ be a polynomial in $s$. We define

$$
p(\mathcal{V}_{W^\prime}^W) = \Sigma^\alpha \alpha_i^s \mathcal{V}_{W^\prime}^{W(i)},
$$

where

$$
\Sigma^\alpha \alpha_i^s (\mathcal{V}_{W^\prime}^{W(i)}) \equiv \alpha_0^s (\mathcal{V}_{W^\prime}^{W(0)}) + \omega \alpha_1^s (\mathcal{V}_{W^\prime}^{W(1)}) + \omega^2 \alpha_2^s (\mathcal{V}_{W^\prime}^{W(2)}) + \cdots + \omega^{n-1} \alpha_n^s (\mathcal{V}_{W^\prime}^{W(n)}).
$$

We define zero($\mathcal{V}_{W^\prime}^W$) $\equiv \mathcal{V}_{W^\prime}^W \circ W \oplus \mathcal{V}_{W^\prime}^W \times \hat{W}$. A polynomial $p(s)$ annihilates $\mathcal{V}_{W^\prime}^W$ iff $p(\mathcal{V}_{W^\prime}^W)$ is decoupled.

The next theorem corresponds to the result that, for a matrix $A$, $(p(A))^T = p(A^T)$.

Theorem 43. Let $\mathcal{V}_{W^\prime}^W$ be a genaut and let $p(s) = \Sigma^\alpha \alpha_i^s$ be a polynomial in $s$. Then

$$(p(\mathcal{V}_{W^\prime}^W))^a = p(\mathcal{V}_{W^\prime}^{W(a)}).$$

Therefore, $p(s)$ annihilates $\mathcal{V}_{W^\prime}^W$ iff it annihilates $\mathcal{V}_{W^\prime}^{W(a)}$. 

38
Proof. We note that

\[(\lambda^{(0)}_{W \dot{W}})^a = (\lambda^a_{W \cdot \dot{W}})^{(0)} ,\]

\[(\lambda^{(k)}_{W \dot{W}})^a = (\lambda^a_{W \cdot \dot{W}})^{(k)} , \quad k = 1, \ldots , \]

\[(\lambda^{(k)}_{W \cdot \dot{W}})^a = \lambda^a_{W \cdot \dot{W}} , \quad k = 0, 1, \ldots , \]

\[(\lambda_{W \cdot \dot{W}}^{(i)} + \lambda_{W \cdot \dot{W}}^{(j)} )^a = \lambda_{W \cdot \dot{W}}^{(i)} (\lambda^a_{W \cdot \dot{W}})^{(i)} + \lambda_{W \cdot \dot{W}}^{(j)} (\lambda^a_{W \cdot \dot{W}})^{(j)} .\]

These results follow from Theorem 4, Theorem 20, Theorem 21 and Lemma 41. Finally we need to use the fact that the complementary orthogonal space of the direct sum \( \mathcal{V}_A \oplus \mathcal{V}_B \) is \( \mathcal{V}_A \oplus \mathcal{V}_B^{\perp} \).

8.3. Polynomials of genops

The following lemmas have the ultimate purpose of showing that polynomials of genops behave similar to polynomials of operators (Theorem 50).

We begin with Lemma 44 which follows directly from the definition of intersection-sum of linkages. It relates the contraction and restriction to \( W, \dot{W} \), of the original genauts, to that of their intersection-sum. Lemmas 45 46 do this task for the ‘\(*\)’ operation. Lemma 47 does this for ‘\(\lambda^s\)’ operation. This is useful in showing that polynomials of a genop are also genops and further have the same restriction to \( W \) and contraction to \( \dot{W} \) as the original genop. This leads to determining when a polynomial of a genop becomes an annihilating polynomial for it.

Lemma 44. Let \( \mathcal{V}_{W \dot{W}}^{1,2}, \mathcal{V}_{W \dot{W}}^{1,2} \) be generalized autonomous systems and let \( \mathcal{V}_{W \dot{W}} = \mathcal{V}_{W \dot{W}}^{1} + \mathcal{V}_{W \dot{W}}^{2} \). Then,

1. \( \mathcal{V}_{W \dot{W}} \times \dot{W} = \mathcal{V}_{W \dot{W}}^{1} \times \dot{W} + \mathcal{V}_{W \dot{W}}^{2} \times \dot{W} \)

\( \mathcal{V}_{W \dot{W}} \circ W = \mathcal{V}_{W \dot{W}}^{1} \circ W \bigcap \mathcal{V}_{W \dot{W}}^{2} \circ W. \)

Hence if \( \mathcal{V}_{W \dot{W}}^{1,2} \) have the same restriction to \( W \), this space would also be the same as the restriction of \( \mathcal{V}_{W \dot{W}} \) to \( W. \)

Similarly if \( \mathcal{V}_{W \dot{W}}^{1,2} \), have the same contraction to \( \dot{W} \), this space would also be the same as the contraction of \( \mathcal{V}_{W \dot{W}} \) to \( \dot{W}. \)

2. \( \mathcal{V}_{W \dot{W}} \times W \supseteq \mathcal{V}_{W \dot{W}}^{1} \times W \bigcap \mathcal{V}_{W \dot{W}}^{2} \times W \)

\( \mathcal{V}_{W \dot{W}} \circ \dot{W} \subseteq \mathcal{V}_{W \dot{W}}^{1} \circ \dot{W} + \mathcal{V}_{W \dot{W}}^{2} \circ \dot{W}. \)

3. If \( \mathcal{V}_{W \dot{W}}^{1,2} \) are USG which have the same restriction \( \mathcal{V}_W \) to \( W \), then \( \mathcal{V}_{W \dot{W}} \) is a USG with \( \mathcal{V}_{W \dot{W}} \circ W = \mathcal{V}_W. \)

4. If \( \mathcal{V}_{W \dot{W}}^{1,2} \) are LSG which have the same contraction \( \mathcal{V}_W \) to \( W \), then \( \mathcal{V}_{W \dot{W}} \) is a LSG with \( \mathcal{V}_{W \dot{W}} \times W = \mathcal{V}_W. \)

5. If \( \mathcal{V}_{W \dot{W}}^{1,2} \) are genops which have the same restriction \( \mathcal{V}_W \) to \( W \) and have the same contraction \( \mathcal{V}_W \) to \( W \), then \( \mathcal{V}_{W \dot{W}} \) is a genop with \( \mathcal{V}_{W \dot{W}} \circ W = \mathcal{V}_W \) and \( \mathcal{V}_{W \dot{W}} \times W = \mathcal{V}_W. \)

The next lemma is immediate from the definition of the ‘\(*\)’ operation.
Lemma 45. Let $V_{W} \equiv V_{W}^{1} \ast V_{W}^{2}$. Then

$$V_{W} \circ W \subseteq V_{W}^{1} \circ W \quad (23)$$

$$V_{W} \circ W \subseteq V_{W}^{2} \circ W \quad (24)$$

$$V_{W} \times W \supseteq V_{W}^{1} \times W \quad (25)$$

$$V_{W} \times W \supseteq V_{W}^{2} \times W \quad (26)$$

Using this lemma and the definition of the $\ast$ operation we get the next lemma.

Lemma 46. Let $V_{W}^{1}, V_{W}^{2}$ be genauts and let $V_{W} \equiv V_{W}^{1} \ast V_{W}^{2}$.

1. If $V_{W}^{1}, V_{W}^{2}$ are USG which have the same restriction $V_{W}$ to $W$, then $V_{W}$ is a USG with

$$V_{W} \circ W = V_{W}.$$  

2. If $V_{W}^{1}, V_{W}^{2}$ are LSG which have the same contraction $V_{W}'$ to $W$, then $V_{W}$ is a LSG with

$$V_{W} \times W = V_{W}'.$$  

3. If $V_{W}^{1}, V_{W}^{2}$ are genops which have the same restriction $V_{W}$ to $W$ and have the same contraction $V_{W}'$ to $W$, then $V_{W}$ is a genop with

$$V_{W} \circ W = V_{W} \quad \text{and} \quad V_{W} \times W = V_{W}'.$$  

4. If $V_{W}$ is a genop, then so is $V_{W}^{(k)}$ for $k = 1, \ldots$, with the same restriction to $W$ and contraction to $W$ as $V_{W}$. Further,

$$V_{W}^{(k)} \circ W \subseteq V_{W} \circ W, \quad k = 1, \ldots$$

$$V_{W}^{(k)} \times W \supseteq V_{W} \times W, \quad k = 1, \ldots.$$  

5. If $V_{W}$ is a genop, then

$$V_{W}^{(j)} \ast V_{W}^{(j)} = V_{W}^{(j)} \ast V_{W}^{(j)} = V_{W}^{(j)} \ast V_{W}^{(j)}, \quad j = 0, 1, \ldots$$  

Remark 10. Sum and intersection of genops are not in general genops. It is easy to see that sum of USGs is a USG and intersection of LSGs is an LSG. But intersection of USGs is not in general a USG and sum of LSGs is not in general an LSG.

The next lemma follows from the definition of scalar multiplication of linkages. We remind the reader that

$$0^{2}V_{W} = V_{W} \circ W \oplus V_{W} \times W.$$  

Lemma 47. Let $V_{W}$ be a generalized autonomous system. Then

$$(\lambda \hat{W} V_{W}) \circ W = V_{W} \circ W, \quad (\lambda \hat{W} V_{W}) \times W = V_{W} \times W.$$  

Hence,
Lemma 49.

- If $V_{W^W}$ is USG, so is $\lambda^w V_{W^W}$ with the same restriction to $W$ as $V_{W^W}$.
- If $V_{W^W}$ is LSG, so is $\lambda^w V_{W^W}$ with the same contraction to $\hat{W}$ as $V_{W^W}$.
- If $V_{W^W}$ is a genop, so is $\lambda^w V_{W^W}$ with the same restriction to $W$ and contraction to $\hat{W}$ as $V_{W^W}$.

The next lemma is a useful fact about composing or performing intersection-sum operations with decoupled linkages. It is immediate from the definitions of the relevant operations and of decoupled linkages.

Lemma 48.

1. If $V_{AB}$ is decoupled, then so is $V_{AB} \leftrightarrow V_{BC}$. Further,

$$(V_{AB} \leftrightarrow V_{BC}) \circ A = (V_{AB} \leftrightarrow V_{BC}) \times A = V_{AB} \circ A, \quad (V_{AB} \leftrightarrow V_{BC}) \circ C = (V_{AB} \leftrightarrow V_{BC}) \times C = V_{BC} \times C.$$ 

2. If $V_{AB}^1$ is decoupled with

$$V_{AB}^1 \circ A \supseteq V_{AB}^2 \circ A, \quad V_{AB}^1 \times B \subseteq V_{AB}^2 \times B,$$

then

$$V_{AB}^1 + b V_{AB}^2 = V_{AB}^1 + b V_{AB}^1 = V_{AB}^2.$$

3. If $V_{AB}^1, V_{AB}^2$ are decoupled, then

$$V_{AB}^1 + V_{AB}^2 = (V_{AB}^1 \circ A + V_{AB}^2 \circ A) \oplus (V_{AB}^1 \circ B + V_{AB}^2 \circ B)$$

and

$$V_{AB}^1 + b V_{AB}^2 = (V_{AB}^1 \circ A \cap V_{AB}^2 \circ A) \oplus (V_{AB}^1 \circ B + V_{AB}^2 \circ B).$$

The next lemma does preliminary work on polynomials of genauts and also states that polynomials of genops are themselves genops.

Lemma 49. Let $V_{W^W}$ be a genaut. Let $p(s)$ be a polynomial in $s$. We have the following.

1. Let $p(s) = p_1(s) + p_2(s)$, where $p_1(s), p_2(s)$ are polynomials in $s$. Then $p(V_{W^W}) = p_1(V_{W^W}) + p_2(V_{W^W}).$

2. If $V_{W^W}$ is USG, then

$$p(V_{W^W}) \circ W \subseteq V_{W^W} \circ W, \quad p(V_{W^W}) \times \hat{W} \supseteq V_{W^W} \times \hat{W},$$

and, if $V_{W^W}$ is LSG, then

$$p(V_{W^W}) \circ \hat{W} = V_{W^W} \circ \hat{W}, \quad p(V_{W^W}) \times W = V_{W^W} \times W.$$ 

Therefore if $V_{W^W}$ is respectively USG, LSG, genop, then so is $p(V_{W^W})$. Further, when $V_{W^W}$ is a genop, $p(V_{W^W})$ has the same restriction to $W$ and contraction to $\hat{W}$ as $V_{W^W}$.

3. If $V_{W^W}$ is a genop, $\text{zero}(V_{W^W}) \equiv V_{W^W} \circ W \oplus V_{W^W} \times \hat{W}$, then

$$p(V_{W^W}) + \text{zero}(V_{W^W}) = p(V_{W^W}),$$

$$(p(V_{W^W})) \ast (\text{zero}(V_{W^W})) = (\text{zero}(V_{W^W})) \ast (p(V_{W^W})) = \text{zero}(V_{W^W}).$$
4. If $\mathcal{V}_{W\hat{W}}$ is a genop and if $p(\mathcal{V}_{W\hat{W}})$ is decoupled then

$$p(\mathcal{V}_{W\hat{W}}) = \mathcal{V}_{W\hat{W}} \circ W \oplus \mathcal{V}_{W\hat{W}} \times \hat{W} = \text{zero}(\mathcal{V}_{W\hat{W}}).$$

Proof. 1. This follows from Lemma 17 and the fact that $\lambda \psi^j \mathcal{V}_{W\hat{W}}^j + \omega^j \mathcal{V}_{W\hat{W}}^j = (\lambda_1 + \lambda_2) \psi^j \mathcal{V}_{W\hat{W}}^j$.

2. We combine terms of the kind $\lambda \psi^j \mathcal{V}_{W\hat{W}}^j$ through $+\omega$ intersection-sum. We need results of the kind ‘when $\mathcal{V}_{W\hat{W}}$ has a relevant property, then so do $\mathcal{V}_{W\hat{W}}^j \neq 0, \lambda \psi_j \mathcal{V}_{W\hat{W}} \neq 0, +\omega \lambda \psi_j \mathcal{V}_{W\hat{W}}^j \neq 0$.’ These results are available in Lemmas 144617.

Note that, in general, $\mathcal{V}_{W\hat{W}} \circ \hat{W}$ is not a subspace of $\mathcal{V}_{W\hat{W}} \circ \hat{W}$ and $\mathcal{V}_{W\hat{W}} \times W$ is not a superspace of $\mathcal{V}_{W\hat{W}} \times W$.

3. From the previous part of the present lemma, we have that

$$p(\mathcal{V}_{W\hat{W}}) \circ W = \mathcal{V}_{W\hat{W}} \circ W, \quad p(\mathcal{V}_{W\hat{W}}) \times \hat{W} = \mathcal{V}_{W\hat{W}} \times \hat{W}.$$

Therefore,

$$\text{zero}(\mathcal{V}_{W\hat{W}}) = p(\mathcal{V}_{W\hat{W}}) \circ W \oplus p(\mathcal{V}_{W\hat{W}}) \times \hat{W}.$$

The result now follows from Lemma 18.

4. Follows from the fact that, when $\mathcal{V}_{W\hat{W}}$ is a genop and $p(\mathcal{V}_{W\hat{W}})$ is decoupled,

$$p(\mathcal{V}_{W\hat{W}}) = p(\mathcal{V}_{W\hat{W}}) \circ W \oplus p(\mathcal{V}_{W\hat{W}}) \times \hat{W} = \mathcal{V}_{W\hat{W}} \circ W \oplus \mathcal{V}_{W\hat{W}} \times \hat{W}.$$ 

The next theorem establishes that polynomials of genops behave similarly to polynomials of operators, viz., they have minimal annihilating polynomials.

**Theorem 50.** 1. Let $\mathcal{V}_{W\hat{W}}$ be a genop. Suppose $p(s) = p_1(s)q(s)$. Then

$$p(\mathcal{V}_{W\hat{W}}) = (p_1(\mathcal{V}_{W\hat{W}}) * (q(\mathcal{V}_{W\hat{W}})).$$

2. Let $\mathcal{V}_{W\hat{W}}$ be a genop and let $p(s) = p_1(s)q(s) + a(s)$. Then

$$p(\mathcal{V}_{W\hat{W}}) = ((p_1(\mathcal{V}_{W\hat{W}}) * (q(\mathcal{V}_{W\hat{W}}))) + a(\mathcal{V}_{W\hat{W}}).$$

3. Within nonzero multiplying factor, there is a unique polynomial of minimum degree $\geq 1$ which annihilates a genop $\mathcal{V}_{W\hat{W}}$.

**Proof.** 1. Let $p_1(s) \equiv \sum_{j=0}^n \alpha_j s^j, \quad q(s) \equiv \sum_{i=0}^m \beta_i s^i$. Then

$$p_1(\mathcal{V}_{W\hat{W}}) = \sum_{j=0}^n \alpha_j \psi^j(\mathcal{V}_{W\hat{W}}), \quad q(\mathcal{V}_{W\hat{W}}) = \sum_{i=0}^m \beta_i \psi^i(\mathcal{V}_{W\hat{W}}).$$

We are given that $p(s) = p_1(s)q(s)$. In order to show that $p(\mathcal{V}_{W\hat{W}}) = (p_1(\mathcal{V}_{W\hat{W}}) * (q(\mathcal{V}_{W\hat{W}}))$, we will merely show that distributivity holds in the product

$$(\sum_{j=0}^n \alpha_j \psi^j(\mathcal{V}_{W\hat{W}})) * (\sum_{i=0}^m \beta_i \psi^i(\mathcal{V}_{W\hat{W}})).$$

We have

$$p_1(\mathcal{V}_{W\hat{W}}) * q(\mathcal{V}_{W\hat{W}})) = (p_1(\mathcal{V}_{W\hat{W}})) * (\sum_{i=0}^m \beta_i \psi^i(\mathcal{V}_{W\hat{W}})) = (p_1(\mathcal{V}_{W\hat{W}})) \mathcal{W}_W \Leftrightarrow (\sum_{i=0}^m \beta_i \psi^i(\mathcal{V}_{W\hat{W}})) \mathcal{W}_W.$$
Since \( V_{\tilde{W} \tilde{W}} \) is a genop, we have that
\[
(V_{\tilde{W} \tilde{W}} \times \tilde{W})_W \subseteq V_{\tilde{W} \tilde{W}} \times W.
\]
From the second part of Lemma [49] we know that
\[
p_1(V_{\tilde{W} \tilde{W}}) \times \tilde{W} = V_{\tilde{W} \tilde{W}} \times \tilde{W} \quad \text{and} \quad V_{\tilde{W} \tilde{W}} \times W \subseteq \beta_i(\gamma_{i})_{\tilde{W} \tilde{W}} \times \tilde{W}, \quad i \neq 0.
\]
It follows that
\[
(p_1(V_{\tilde{W} \tilde{W}})\times W_n \times W_n \subseteq \beta_i(\gamma_{i})_{\tilde{W} \tilde{W}} \times W_n, \quad i \neq 0.
\]
Therefore by Theorem [22] it follows that
\[
(p_1(V_{\tilde{W} \tilde{W}})\times W_n \leftrightarrow (\Sigma_{i=0}^{m}(\beta_i(\gamma_{i})_{\tilde{W} \tilde{W}}))_{W_n \tilde{W}} = \Sigma_{i=0}^{m}(p_1(V_{\tilde{W} \tilde{W}})\times W_n \leftrightarrow (\beta_i(\gamma_{i})_{\tilde{W} \tilde{W}}))_{W_n \tilde{W}}.
\]
In expanded form the equation reads
\[
(p_1(V_{\tilde{W} \tilde{W}})\times W_n \leftrightarrow [\beta_0(\gamma_{0})_{\tilde{W} \tilde{W}}]_{W_n \tilde{W}} + \ldots + \beta_m(\gamma_{m})_{\tilde{W} \tilde{W}})_{W_n \tilde{W}}.
\]
Thus,
\[
(p_1(V_{\tilde{W} \tilde{W}}) \times (\Sigma_{i=0}^{m}(\beta_i(\gamma_{i})_{\tilde{W} \tilde{W}}))) = \Sigma_{i=0}^{m}(p_1(V_{\tilde{W} \tilde{W}}) \times (\beta_i(\gamma_{i})_{\tilde{W} \tilde{W}})).
\]
Next consider the expression
\[
(p_1(V_{\tilde{W} \tilde{W}}) \times (\beta_i(\gamma_{i})_{\tilde{W} \tilde{W}})) = (p_1(V_{\tilde{W} \tilde{W}})\times W_n \leftrightarrow (\beta_i(\gamma_{i})_{\tilde{W} \tilde{W}})_{W_n \tilde{W}} = (\Sigma_{i=0}^{m}(p_1(V_{\tilde{W} \tilde{W}})\times W_n \leftrightarrow (\beta_i(\gamma_{i})_{\tilde{W} \tilde{W}}))_{W_n \tilde{W}}.
\]
From the second part of Lemma [49] we know that
\[
\alpha_j(\gamma_{j})_{\tilde{W} \tilde{W}} \subseteq V_{\tilde{W} \tilde{W}} \circ \tilde{W}, \quad j \neq 0 \quad \text{and} \quad \beta_i(\gamma_{i})_{\tilde{W} \tilde{W}} \circ W = V_{\tilde{W} \tilde{W}} \circ W.
\]
Since \( V_{\tilde{W} \tilde{W}} \) is a genop, we have that
\[
(V_{\tilde{W} \tilde{W}} \circ \tilde{W})_W \subseteq V_{\tilde{W} \tilde{W}} \circ W.
\]
It follows that
\[
\alpha_j(\gamma_{j})_{\tilde{W} \tilde{W}} \circ W_k \subseteq (\beta_i(\gamma_{i})_{\tilde{W} \tilde{W}})_{W_k \tilde{W}}, \quad j \neq 0.
\]
From Theorem [22] we then have that
\[
(\Sigma_{j=0}^{n}(\alpha_j(\gamma_{j})_{\tilde{W} \tilde{W}}))_{W_k \tilde{W}} \leftrightarrow (\Sigma_{j=0}^{n}(\beta_i(\gamma_{i})_{\tilde{W} \tilde{W}}))_{W_k \tilde{W}} = \Sigma_{j=0}^{n}((\alpha_j(\gamma_{j})_{\tilde{W} \tilde{W}}))_{W_k \tilde{W}} \leftrightarrow (\beta_i(\gamma_{i})_{\tilde{W} \tilde{W}}))_{W_k \tilde{W}}.
\]
In expanded form the equation reads
\[
(\alpha_0(\gamma_{0})_{\tilde{W} \tilde{W}})_{W_k \tilde{W}} \leftrightarrow (\beta_0(\gamma_{0})_{\tilde{W} \tilde{W}})_{W_k \tilde{W}} + \ldots + (\alpha_n(\gamma_{n})_{\tilde{W} \tilde{W}}))_{W_k \tilde{W}} \leftrightarrow (\beta_i(\gamma_{i})_{\tilde{W} \tilde{W}}))_{W_k \tilde{W}}.
\]
Thus,
\[
(p_1(V_{\tilde{W} \tilde{W}})) \times (\beta_i(\gamma_{i})_{\tilde{W} \tilde{W}}) = \Sigma_{j=0}^{n}(\alpha_j(\gamma_{j})_{\tilde{W} \tilde{W}}) \times (\beta_i(\gamma_{i})_{\tilde{W} \tilde{W}}) = \Sigma_{j=0}^{n}((\alpha_j(\gamma_{j})_{\tilde{W} \tilde{W}})) \times (\beta_i(\gamma_{i})_{\tilde{W} \tilde{W}}))\].

Thus
\[
(\Sigma_{j=0}^{n}(\alpha_j(\gamma_{j})_{\tilde{W} \tilde{W}})) \times (\Sigma_{i=0}^{m}(\beta_i(\gamma_{i})_{\tilde{W} \tilde{W}})) = \Sigma_{i=0}^{m}\Sigma_{j=0}^{n}((\alpha_j(\gamma_{j})_{\tilde{W} \tilde{W}})) \times (\beta_i(\gamma_{i})_{\tilde{W} \tilde{W}})).
\]
2. This follows from the first part of Lemma 49 and the previous part of the present theorem.

3. From the fourth part of Lemma 49 we have that if $V_{W\dot{W}}$ is a genop and $p(s)$ annihilates it, then

$$p(V_{W\dot{W}}) = \text{zero}(V_{W\dot{W}}).$$

If $p(s), q(s)$ both have the minimum degree among all polynomials that annihilate $V_{W\dot{W}}$, and do not differ only by a multiplying factor, then we can write

$$p(s) = p_1(s)q(s) + a(s), \text{ where } \text{degree}(a(s)) < \text{degree}(q(s)).$$

But then by the previous part of the present theorem, we will have

$$\text{zero}(V_{W\dot{W}}) = p(V_{W\dot{W}}) = ((p_1(V_{W\dot{W}})) \ast (\text{zero}(V_{W\dot{W}}))) + a(V_{W\dot{W}}) = a(V_{W\dot{W}}),$$

which violates the minimality of degree of $p(s), q(s)$.

\[\square\]

**Remark 11.**
- Just as in the case of the usual operators, in general for two genops $V^1_{W\dot{W}}, V^2_{W\dot{W}}$ it will not be true that $(V^1_{W\dot{W}}) \ast (V^2_{W\dot{W}})$ equals $(V^2_{W\dot{W}}) \ast (V^1_{W\dot{W}})$, but for two polynomials $p(s), q(s)$ it will be true that $(p(V_{W\dot{W}})) \ast (q(V_{W\dot{W}})) = (q(V_{W\dot{W}})) \ast (p(V_{W\dot{W}}))$.

- In the above proof of Theorem 50 note that, although it is not required, it is true that $(p_1(V_{W\dot{W}}))_{W\dot{W}} \times W_n \subseteq \beta_0(V^0_{W\dot{W}})_{W\dot{W}} \times W_n$ and $\alpha_0(V^0_{W\dot{W}})_{W\dot{W}} \circ W_n \subseteq (\beta_0(V^0_{W\dot{W}}))_{W\dot{W}} \circ W_n$.

A commonly occurring situation in multivariable control, when translated into the language of this paper, is that one genaut contains another but has the same restriction or contraction to some set.

For instance, in the case of the dynamical system $V^1_{W\dot{W}, M_n, M_{\dot{n}}}$ defined by Equation 20 the genop $V^1_{W\dot{W}, M_n, M_{\dot{n}}} \equiv V^1_{\dot{W}, M_{\dot{n}}, M_n} \leftrightarrow (F_{M_n} \oplus 0_{M_{\dot{n}}})$ is contained in $V^1_{W\dot{W}, M_n, M_{\dot{n}}} \circ W\dot{W}$ and contains $V^1_{W\dot{W}, M_n, M_{\dot{n}}} \times W\dot{W}$. In the former case it has the same restriction to $W$ as the genaut containing it and, in the latter case, the same contraction to $\dot{W}$ as the genaut that it contains. This is also true of every genop which can be obtained from $V^1_{W\dot{W}, M_n, M_{\dot{n}}}$ by $\text{wm}_n$-feedback or by $\text{wm}_{\dot{n}}$-injection.

The fundamental questions about annihilating polynomials of such genops, dealt with in the next section, will be discussed in detail through the next two theorems which are duals of each other. We prove the first in detail through a series of lemmas but skip the proof of the dual result.

**Theorem 51.** Let $V^u_{W\dot{W}}$ be a USG and let $V_{W\dot{W}}$ be a genop such that

$$V^u_{W\dot{W}} \subseteq V^u_{W\dot{W}} \quad \text{and} \quad V^u_{W\dot{W}} \circ W = V^u_{W\dot{W}} \circ W.$$ Let $\mathcal{W}$ be invariant in $V^u_{W\dot{W}}$. Then

1. $V^u_{W\dot{W}} \circ (V_{W\dot{W}})_{W\dot{W}} = V^u_{W\dot{W}} \circ (V_{W\dot{W}})_{W\dot{W}}$ and is a genop.

2. $\mathcal{W}$ is invariant in $V_{W\dot{W}}$ and therefore $V_{W\dot{W}} \cap \mathcal{W} = V_{W\dot{W}} \cap (V_{W\dot{W}} \oplus (V_{W\dot{W}})_{W\dot{W}})$ and $V_{W\dot{W}} \cap \mathcal{W}$ is a genop.

3. $p(V^u_{W\dot{W}} \circ (V_{W\dot{W}})_{W\dot{W}}) = p(V^u_{W\dot{W}}) \circ (V_{W\dot{W}})_{W\dot{W}}$.

4. $p(V^u_{W\dot{W}} \cap \mathcal{W}) = p(V^u_{W\dot{W}}) \cap \mathcal{W}$. 


5. If $p(\mathcal{V}_{\mathcal{W}}^{1})$ is decoupled, so are $p(\mathcal{V}_{\mathcal{W}}^{\mu} + (\mathcal{V}_{\mathcal{W}}^{1})_{\mu}^{+})$ and $p(\mathcal{V}_{\mathcal{W}}^{1} \cap \mathcal{V}_{\mathcal{W}})$.

6. If $p_{1}(\mathcal{V}_{\mathcal{W}}^{\mu} + (\mathcal{V}_{\mathcal{W}}^{1})_{\mu}^{+})$, $p_{2}(\mathcal{V}_{\mathcal{W}}^{1} \cap \mathcal{V}_{\mathcal{W}})$ are decoupled, then $p_{1}p_{2}(\mathcal{V}_{\mathcal{W}}^{1})$ is decoupled.

The proof of the theorem needs the following lemmas.

**Lemma 52.** Let $\mathcal{V}_{\mathcal{W}}^{1}$, $\mathcal{V}_{\mathcal{W}}^{2}$ be generalized autonomous systems with $\mathcal{V}_{\mathcal{W}}^{1} \supseteq \mathcal{V}_{\mathcal{W}}^{2}$.

1. If $p(s)$ is any polynomial in $s$, then $p(\mathcal{V}_{\mathcal{W}}^{1}) \supseteq p(\mathcal{V}_{\mathcal{W}}^{2})$.

2. Let $\mathcal{V}_{\mathcal{W}}^{1} \cap W = \mathcal{V}_{\mathcal{W}}^{2} \cap W$. Then $\mathcal{V}_{\mathcal{W}}^{1} \cap (\mathcal{V}_{\mathcal{W}}^{1} \times \hat{W}) = \mathcal{V}_{\mathcal{W}}^{2}$.

3. Let $\mathcal{V}_{\mathcal{W}}^{1} \times \hat{W} = \mathcal{V}_{\mathcal{W}}^{2} \times \hat{W}$. Then $\mathcal{V}_{\mathcal{W}}^{1} \cap (\mathcal{V}_{\mathcal{W}}^{2} \times \hat{W}) = \mathcal{V}_{\mathcal{W}}^{2} \times \hat{W}$.

4. Let $\mathcal{V}_{\mathcal{W}}^{1}, \mathcal{V}_{\mathcal{W}}^{2}$ be USG and let $\mathcal{V}_{\mathcal{W}}^{1} \cap W = \mathcal{V}_{\mathcal{W}}^{2} \cap W$. If $p(\mathcal{V}_{\mathcal{W}}^{2})$ is decoupled then so is $p(\mathcal{V}_{\mathcal{W}}^{1})$.

5. Let $\mathcal{V}_{\mathcal{W}}^{1}, \mathcal{V}_{\mathcal{W}}^{2}$ be LSG and let $\mathcal{V}_{\mathcal{W}}^{1} \times \hat{W} = \mathcal{V}_{\mathcal{W}}^{2} \times \hat{W}$. If $p(\mathcal{V}_{\mathcal{W}}^{2})$ is decoupled then so is $p(\mathcal{V}_{\mathcal{W}}^{1})$.

**Proof.**

1. If $\mathcal{V}_{\mathcal{W}}^{1} \supseteq \mathcal{V}_{\mathcal{W}}^{1}$, it is clear that

$$\mathcal{V}_{\mathcal{W}}^{(k)} \supseteq \mathcal{V}_{\mathcal{W}}^{(k)}$$

Thus LHS contains RHS as required.

2. Clearly RHS contains LHS. Let $(f_{\mathcal{W}}, g_{\mathcal{W}}) \in \mathcal{V}_{\mathcal{W}}^{1}$.

Since $\mathcal{V}_{\mathcal{W}}^{1} \cap W = \mathcal{V}_{\mathcal{W}}^{2} \cap W$, for some $f_{\mathcal{W}}' - g_{\mathcal{W}}' \in \mathcal{V}_{\mathcal{W}}^{2} \subseteq \mathcal{V}_{\mathcal{W}}^{1}$.

Therefore, $g_{\mathcal{W}} - g_{\mathcal{W}}' \in \mathcal{V}_{\mathcal{W}}^{1} \times \hat{W}$, so that

$$(f_{\mathcal{W}}, g_{\mathcal{W}}') + (0_{\mathcal{W}}, g_{\mathcal{W}} - g_{\mathcal{W}}') = (f_{\mathcal{W}}, g_{\mathcal{W}}') \in \mathcal{V}_{\mathcal{W}}^{2} + \mathcal{V}_{\mathcal{W}}^{1} \times \hat{W}.$$
Lemma 53. Let \( \mathcal{V}_{W}^{1}, \mathcal{V}_{W}^{2} \) be genauts and let \( \mathcal{V}_{W} \) be conditioned (controlled) invariant in them. Then

1. \( \mathcal{V}_{W} \) is conditioned (controlled) invariant in \( \mathcal{V}_{W}^{1} \ast \mathcal{V}_{W}^{2} \).

2. \( \mathcal{V}_{W} \) is conditioned (controlled) invariant in \( \mathcal{V}_{W}^{1} \ast \mathcal{V}_{W}^{2} \).

3. \( \mathcal{V}_{W} \) is conditioned (controlled) invariant in \( \lambda \mathcal{V}_{W}^{1} \).

4. If \( p(s) \) is a polynomial in \( s \), then \( \mathcal{V}_{W} \) is conditioned (controlled) invariant in \( p(\mathcal{V}_{W}^{1}) \).

Proof. We will consider only the conditioned invariant case, the controlled invariant case following by duality. Let \( \mathcal{V}_{W} \) be conditioned invariant in \( \mathcal{V}_{W}^{1}, \mathcal{V}_{W}^{2} \).

1. We have

\[
\mathcal{V}_{W} \leftrightarrow (\mathcal{V}_{W}^{1} \ast \mathcal{V}_{W}^{2}) = \mathcal{V}_{W} \leftrightarrow ([\mathcal{V}_{W} \leftrightarrow (\mathcal{V}_{W}^{1} \uplus \mathcal{V}_{W}^{2}]) \subseteq (\mathcal{V}_{W})_{W}.
\]

2. We have

\[
\mathcal{V}_{W} \leftrightarrow (\mathcal{V}_{W}^{1} \ast \mathcal{V}_{W}^{2}) \subseteq (\mathcal{V}_{W} \leftrightarrow \mathcal{V}_{W}^{1}) + (\mathcal{V}_{W} \leftrightarrow \mathcal{V}_{W}^{2}) \subseteq (\mathcal{V}_{W})_{W}.
\]

3. When \( \lambda \neq 0 \), it is clear that

\[
\mathcal{V}_{W} \leftrightarrow \lambda \mathcal{V}_{W}^{1} = \mathcal{V}_{W} \leftrightarrow \mathcal{V}_{W}^{1} \subseteq (\mathcal{V}_{W})_{W}.
\]

Next, to consider the case where \( \lambda = 0 \), note that \( \mathcal{V}_{W} \) being conditioned invariant in \( \mathcal{V}_{W}^{1} \) implies that

\[
(\mathcal{V}_{W})_{W} \supseteq \mathcal{V}_{W} \leftrightarrow \mathcal{V}_{W}^{1} \supseteq \mathcal{V}_{W}^{1} \times \hat{W}.
\]

We know that

\[
0 \mathcal{V}_{W}^{1} = \mathcal{V}_{W}^{1} \circ \mathcal{V}_{W}^{1} \times \hat{W},
\]

so that

\[
\mathcal{V}_{W} \leftrightarrow 0 \mathcal{V}_{W}^{1} = \mathcal{V}_{W} \leftrightarrow (\mathcal{V}_{W}^{1} \circ \mathcal{V}_{W}^{1} \times \hat{W}) = \mathcal{V}_{W}^{1} \times \hat{W} \subseteq (\mathcal{V}_{W})_{W}.
\]

4. This follows from the previous parts of the present lemma.

Lemma 54. Let \( \mathcal{V}_{W} \) be a genaut. Then

1. If \( \mathcal{V}_{W} \) is conditioned invariant in \( \mathcal{V}_{W}^{1}, \mathcal{V}_{W} \) is also conditioned invariant in \( \mathcal{V}_{W}^{1} \cap \mathcal{V}_{W} \);

    if \( \mathcal{V}_{W}^{1} \) is LSG(USG) then \( \mathcal{V}_{W}^{1} \cap \mathcal{V}_{W} \) is LSG(USG);

2. If \( \mathcal{V}_{W} \) is controlled invariant in \( \mathcal{V}_{W}^{1}, \mathcal{V}_{W} \) is also controlled invariant in \( \mathcal{V}_{W}^{1} + (\mathcal{V}_{W})_{W} \);

    if \( \mathcal{V}_{W}^{1} \) is LSG(USG) then \( \mathcal{V}_{W}^{1} + (\mathcal{V}_{W})_{W} \) is LSG(USG).
Lemma 55. Let $\mathcal{V}_W$ be genauts and let $\mathcal{V}_W$ be conditioned invariant in them. Then

1. $(\mathcal{V}_W)_{iW} \equiv (\mathcal{V}_{iW} \cap \mathcal{V}_W) = \mathcal{V}_W \equiv \mathcal{V}_{iW} \subseteq (\mathcal{V}_W)_{iW}$,

so that $\mathcal{V}_W$ is conditioned invariant in $\mathcal{V}_{iW} \cap \mathcal{V}_W$.

Next let $\mathcal{V}_{iW}^*$ be LSG i.e., $(\mathcal{V}_{iW}^* \times \mathcal{W})_{iW} \subseteq \mathcal{V}_{iW} \times \mathcal{W}$.

We know that $\mathcal{V}_{iW} \times \mathcal{W} \subseteq \mathcal{V}_W \equiv \mathcal{V}_{iW} \subseteq ((\mathcal{V}_{iW} \cap \mathcal{V}_W) \circ \mathcal{W})_{iW}$.

Thus $\mathcal{V}_{iW} \cap \mathcal{V}_W$ is LSG.

Next let $\mathcal{V}_{iW}^*$ be USG.

Since by conditioned invariance of $\mathcal{V}_W$,

$\mathcal{V}_W \equiv \mathcal{V}_{iW} = (\mathcal{V}_{iW} \cap \mathcal{V}_W) \circ \mathcal{W} \subseteq (\mathcal{V}_{iW} \cap \mathcal{V}_W)_{iW}$,

we have

$(\mathcal{V}_{iW} \cap \mathcal{V}_W) \circ \mathcal{W} = (\mathcal{V}_{iW} \cap \mathcal{V}_W)_{iW} \subseteq ((\mathcal{V}_{iW} \cap \mathcal{V}_W) \circ \mathcal{W})_{iW}$.

Thus $\mathcal{V}_{iW} \cap \mathcal{V}_W$ is USG.

2. This follows by duality from the previous part of the present lemma.

\[ \Box \]

Lemma 55. Let $\mathcal{V}_{iW}^1$, $\mathcal{V}_{iW}^2$ be genauts and let $\mathcal{V}_W$ be conditioned invariant in them. Then

1. $(\mathcal{V}_{iW}^1 \cap \mathcal{V}_{iW}^2) \cap \mathcal{V}_W = (\mathcal{V}_{iW}^1 \cap \mathcal{V}_W) \cap (\mathcal{V}_{iW}^2 \cap \mathcal{V}_W)$.
2. $(\mathcal{V}_{iW}^1 \cap \mathcal{V}_{iW}^2) \cap \mathcal{V}_W = (\mathcal{V}_{iW}^1 \cap \mathcal{V}_W) \cap (\mathcal{V}_{iW}^2 \cap \mathcal{V}_W)$.
3. $(\lambda^\circ \mathcal{V}_{iW}^1 \cap \mathcal{V}_W) = \lambda^\circ (\mathcal{V}_{iW}^1 \cap \mathcal{V}_W)$.
4. $p(s)$ is a polynomial in $s$ then $p(\mathcal{V}_{iW}^1 \cap \mathcal{V}_W) = p(\mathcal{V}_{iW}^1 \cap \mathcal{V}_W)$.

Proof. 1. We have

$(\mathcal{V}_{iW}^1 \cap \mathcal{V}_{iW}^2) \cap \mathcal{V}_W = (\mathcal{V}_{iW}^1 \cap \mathcal{V}_W) \cap (\mathcal{V}_{iW}^2 \cap \mathcal{V}_W) = (\mathcal{V}_{iW}^1 \cap \mathcal{V}_W) \cap (\mathcal{V}_{iW}^2 \cap \mathcal{V}_W) \cap \mathcal{V}_W$.

Now by conditioned invariance of $\mathcal{V}_W$ in $\mathcal{V}_{iW}^1$,

$\mathcal{V}_W \equiv (\mathcal{V}_{iW}^1 \cap \mathcal{V}_W) \cap \mathcal{V}_W = (\mathcal{V}_{iW}^1 \cap \mathcal{V}_W) \cap \mathcal{V}_W$.

So

$(\mathcal{V}_{iW}^1 \cap \mathcal{V}_W) \cap \mathcal{V}_W = (\mathcal{V}_{iW}^1 \cap \mathcal{V}_W) \cap \mathcal{V}_W$.

\[ \Box \]
2. (This does not require conditioned invariance of $\mathcal{V}_W$.)

That RHS is contained in LHS is immediate from the definition of the $+_\omega$ operation.
Let $(f_W, g_W) \in \text{LHS}$. Then

$$f_W \in (\mathcal{V}_W^1 \circ W) \cap (\mathcal{V}_W^2 \circ W) \cap \mathcal{V}_W.$$

Further we must have, for some $g_1^w, g_2^w$, that

$$g_1^w + g_2^w = g^w, \quad (f_W, g_1^w) \in \mathcal{V}_W^1, \quad (f_W, g_2^w) \in \mathcal{V}_W^2.$$

But then it is clear that

$$(f_W, g^w) \in (\mathcal{V}_W^1 \cap \mathcal{V}_W) \cap \mathcal{V}_W^1 + \omega (\mathcal{V}_W^2 \cap \mathcal{V}_W) = \text{RHS}.$$

3. This is routine. It is clear that it works out right also for $\lambda = 0$.

4. This is a consequence of the previous parts of this lemma.

The next lemma is the dual of the above lemma and therefore its proof is omitted.

**Lemma 56.** Let $\mathcal{V}_W^1, \mathcal{V}_W^2$ be genauts and let $\mathcal{V}_W$ be controlled invariant in them. Then

1. $(\mathcal{V}_W^1 * \mathcal{V}_W^2) + (\mathcal{V}_W)_W = (\mathcal{V}_W^1 + (\mathcal{V}_W)_W) * (\mathcal{V}_W^2 + (\mathcal{V}_W)_W)$.

2. $(\mathcal{V}_W^1 + \omega \mathcal{V}_W^2) + (\mathcal{V}_W)_W = (\mathcal{V}_W^1 + (\mathcal{V}_W)_W) + \omega (\mathcal{V}_W^2 + (\mathcal{V}_W)_W)$.

3. $(\lambda \mathcal{V}_W + (\mathcal{V}_W)_W) = \lambda (\mathcal{V}_W^1 + (\mathcal{V}_W)_W)$.

4. If $p(s)$ is a polynomial in $s$ then $p(\mathcal{V}_W^1) + (\mathcal{V}_W)_W = p(\mathcal{V}_W^1 + (\mathcal{V}_W)_W)$.

The Lemmas 54, 55 lead immediately to the following lemma.

**Lemma 57.** Let $\mathcal{V}_W$ be a genaut.

1. Let $\mathcal{V}_W$ be conditioned invariant in $\mathcal{V}_W$. Then $p(\mathcal{V}_W \cap \mathcal{V}_W) = p(\mathcal{V}_W) \cap \mathcal{V}_W$.

2. Let $\mathcal{V}_W$ be controlled invariant in $\mathcal{V}_W$. Then $p(\mathcal{V}_W + (\mathcal{V}_W)_W) = p(\mathcal{V}_W + (\mathcal{V}_W)_W)$.

We are now ready for the proof of Theorem 51.

**Proof.** Proof of Theorem 51.
1. Since $\mathcal{V}_W$ is controlled invariant in $\mathcal{V}^u_{\hat{W}W}$,

$$\mathcal{V}^u_{\hat{W}W} \circ W \supseteq \mathcal{V}^u_{\hat{W}W} \scale2leftrightarrow (\mathcal{V}_W)_{\hat{W}} \supseteq \mathcal{V}_W,$$

and since $\mathcal{V}_W$ is conditioned invariant in $\mathcal{V}^u_{\hat{W}W}$,

$$\mathcal{V}^u_{\hat{W}W} \times \hat{W} \subseteq \mathcal{V}^u_{\hat{W}W} \scale2leftrightarrow \mathcal{V}_W \subseteq (\mathcal{V}_W)_{\hat{W}}.$$

Now let $(f_W, g_{\hat{W}}) \in \mathcal{V}^u_{\hat{W}W} + (\mathcal{V}_W \oplus (\mathcal{V}_W)_{\hat{W}})$. We are given that, $\mathcal{V}^u_{\hat{W}W} \circ W = \mathcal{V}^u_{\hat{W}W} \circ W$, and we saw above that $\mathcal{V}^u_{\hat{W}W} \circ W \supseteq \mathcal{V}_W$.

Hence there exists $(f'_W, g'_{\hat{W}}) \in \mathcal{V}^u_{\hat{W}W}$, so that $g_{\hat{W}} - g'_{\hat{W}} \in \mathcal{V}^u_{\hat{W}W} \times \hat{W} \subseteq (\mathcal{V}_W)_{\hat{W}}$.

Therefore, $(f_W, g_{\hat{W}}) \in \mathcal{V}^u_{\hat{W}W} + (\mathcal{V}_W)_{\hat{W}}$.

Thus,

$$\mathcal{V}^u_{\hat{W}W} + (\mathcal{V}_W \oplus (\mathcal{V}_W)_{\hat{W}}) \subseteq \mathcal{V}^u_{\hat{W}W} + (\mathcal{V}_W)_{\hat{W}}.$$

Next, since $\mathcal{V}^u_{\hat{W}W} \circ W = \mathcal{V}^u_{\hat{W}W} \circ W$ and $\mathcal{V}^u_{\hat{W}W} \supseteq \mathcal{V}_{\hat{W}W}$, by Lemma 52 we know that $\mathcal{V}_{\hat{W}W} + \mathcal{V}^u_{\hat{W}W} \times \hat{W} = \mathcal{V}^u_{\hat{W}W}$.

Since $\mathcal{V}^u_{\hat{W}W} \times \hat{W} \subseteq (\mathcal{V}_W)_{\hat{W}}$,

$$\mathcal{V}^u_{\hat{W}W} + (\mathcal{V}_W)_{\hat{W}} \subseteq \mathcal{V}^u_{\hat{W}W} + (\mathcal{V}_W)_{\hat{W}}.$$

Thus

$$\mathcal{V}^u_{\hat{W}W} \supseteq \mathcal{V}^u_{\hat{W}W} + (\mathcal{V}_W)_{\hat{W}}.$$

Let

$$\mathcal{V}^2_{\hat{W}W} \equiv \mathcal{V}^u_{\hat{W}W} + (\mathcal{V}_W)_{\hat{W}} = \mathcal{V}^u_{\hat{W}W} + (\mathcal{V}_W)_{\hat{W}} = \mathcal{V}^u_{\hat{W}W} + (\mathcal{V}_W)_{\hat{W}}.$$

It is clear that

$$\mathcal{V}^2_{\hat{W}W} \circ W = \mathcal{V}^u_{\hat{W}W} \circ W + \mathcal{V}_W, \quad \mathcal{V}^2_{\hat{W}W} \circ \hat{W} = \mathcal{V}^u_{\hat{W}W} \circ \hat{W} + (\mathcal{V}_W)_{\hat{W}},$$

$$\mathcal{V}^2_{\hat{W}W} \times W = \mathcal{V}^u_{\hat{W}W} \times W + \mathcal{V}_W, \quad \mathcal{V}^2_{\hat{W}W} \times \hat{W} = \mathcal{V}^u_{\hat{W}W} \times \hat{W} + (\mathcal{V}_W)_{\hat{W}},$$

and it follows that $\mathcal{V}^2_{\hat{W}W}$ is a genop since $\mathcal{V}^u_{\hat{W}W}$ is one.

2. From the conditioned invariance of $\mathcal{V}_W$ in $\mathcal{V}^u_{\hat{W}W}$, it follows that

$$\mathcal{V}_W \leftrightarrow \mathcal{V}^u_{\hat{W}W} \subseteq \mathcal{V}_W \leftrightarrow \mathcal{V}^u_{\hat{W}W} \subseteq (\mathcal{V}_W)_{\hat{W}}.$$ 

So $\mathcal{V}_W$ is conditioned invariant in $\mathcal{V}^u_{\hat{W}W}$. Next we examine controlled invariance. We will show that

$$\mathcal{V}_W \leftrightarrow \mathcal{V}^u_{\hat{W}W} = \mathcal{V}^u_{\hat{W}W} \leftrightarrow \mathcal{V}^u_{\hat{W}W}.$$ 

The controlled invariance of $\mathcal{V}_W$ in $\mathcal{V}^u_{\hat{W}W}$ will follow from its controlled invariance in $\mathcal{V}^u_{\hat{W}W}$.

Since $\mathcal{V}^u_{\hat{W}W} \subseteq \mathcal{V}^u_{\hat{W}W}$, clearly

$$\mathcal{V}_W \leftrightarrow \mathcal{V}^u_{\hat{W}W} \subseteq \mathcal{V}_W \leftrightarrow \mathcal{V}^u_{\hat{W}W}.$$ 

To see the reverse containment, let $f_W \in \mathcal{V}^u_{\hat{W}W} \rightarrow \mathcal{V}^u_{\hat{W}W}$.

Then there exist $(f_W, g_{\hat{W}}) \in \mathcal{V}^u_{\hat{W}W}$, $g_{\hat{W}} \in \mathcal{V}^u_{\hat{W}W}$.
We know that \( V_{W^C} \cap W = V_{W^C} \cap W \).

So there exists \((f_W, g_W') \in V_{W^C} \subseteq V_{W^C} \).

It follows that \((g_W' - g_W') \subseteq V_{W^C} \times W \subseteq V_{W^C} \).

So \( g_W' \in V_{W^C} \), so that \( f_W \in V_{W^C} \). From Lemma 53.

Thus \( V_{W^C} \subseteq V_{W^C} \), and the equality between the two sides follows.

From the conditioned invariance of \( V_W \) in \( V_{W^C} \), it follows that

\[
V_{W^C} \cap V_W = V_{W^C} \cap V_W = V_{W^C} \cap (V_W \oplus (V_W)_W).
\]

Let

\[
V^2_{W^C} \equiv V_{W^C} \cap V_W = V_{W^C} \cap (V_W \oplus (V_W)_W).
\]

It is clear that

\[
V^2_{W^C} \cap W = V_{W^C} \cap W \cap (V_W \oplus (V_W)_W),
\]

\[
V^2_{W^C} \times W = V_{W^C} \times W \cap (V_W \oplus (V_W)_W),
\]

and it follows that \( V^2_{W^C} \) is a genop since \( V_{W^C} \) is one.

3. We have, \( V^u_{W^C}, V_{W^C} \) are USG, genop respectively and therefore by Lemma 49 \( p(V^u_{W^C}), p(V_{W^C}) \) are also respectively, USG, genop. \( V_W \) is invariant in \( V^u_{W^C}, V_{W^C} \) and therefore also in \( p(V^u_{W^C}) \) and in \( p(V_{W^C}) \) (Lemma 53).

From Lemma 56

\[
p(V^u_{W^C}) + (V_W)_W = p(V^u_{W^C}) + (V_W)_W.
\]

We have \( p(V^u_{W^C}) \supseteq p(V_{W^C}) \) and, by Lemma 49

\[
p(V^u_{W^C}) \cap W = p(V_{W^C}) \cap W.
\]

From the first part of the present theorem,

\[
p(V^u_{W^C}) + (V_W)_W = p(V^u_{W^C}) + (V_W)_W = p(V_{W^C}) + (V_W \oplus (V_W)_W).
\]

4. By Lemma 57 we have that \( p(V_{W^C} \cap V_W) = p(V_{W^C} \cap V_W) \).

Since \( V_W \) is invariant in \( V_{W^C} \), it is also invariant in \( p(V_{W^C}) \) (Lemma 53).

By a previous part of the present theorem we have that

\[
p(V_{W^C} \cap V_W) = p(V_{W^C} \cap V_W) = p(V_{W^C} \cap V_W) \cap (V_W \oplus (V_W)_W).
\]

5. If \( p(V_{W^C}) \) is decoupled, so are

\[
p(V_{W^C} \cap V_W) + (V_W \oplus (V_W)_W), p(V_{W^C} \cap V_W) \cap (V_W \oplus (V_W)_W).
\]

The result follows since

\[
p(V^u_{W^C} + (V_W)_W) = p(V^u_{W^C} + (V_W)_W) \quad \text{and} \quad p(V_{W^C} \cap V_W) = p(V_{W^C} \cap (V_W \oplus (V_W)_W)).
\]
Theorem 58. Let \( \mathcal{V}_{W^l} \) be a LSG and let \( \mathcal{V}_{W^l,W^W} \) be a genop such that
\[
\mathcal{V}_{W^l,W^W} \supseteq \mathcal{V}_{W^l} \quad \text{and} \quad \mathcal{V}_{W^l,W^W} \times \mathcal{W} = \mathcal{V}_{W^l} \times \mathcal{W}.
\]
Let \( \mathcal{W} \) be invariant in \( \mathcal{V}_{W^l} \). Then

1. \( \mathcal{V}_{W^l} \cap \mathcal{W} = \mathcal{V}_{W^l} \cap (\mathcal{W} \oplus (\mathcal{V}_{W^l})) \) and is a genop.

2. \( \mathcal{V}_{W^l} \) is invariant in \( \mathcal{V}_{W^l,W^W} \) and therefore \( \mathcal{V}_{W^l,W^W} \cap (\mathcal{V}_{W^l})^* = \mathcal{V}_{W^l,W^W} \cap (\mathcal{W} \oplus (\mathcal{V}_{W^l})) \) and
\( \mathcal{V}_{W^l,W^W} \cap (\mathcal{V}_{W^l})^* \) is a genop.

3. \( p(\mathcal{V}_{W^l} \cap \mathcal{W}) = p(\mathcal{V}_{W^l}) \cap (\mathcal{W} \oplus (\mathcal{V}_{W^l})) \).

4. \( p(\mathcal{V}_{W^l,W^W} \cap (\mathcal{V}_{W^l})^*) = p(\mathcal{V}_{W^l,W^W} \cap (\mathcal{V}_{W^l})^*) = p(\mathcal{V}_{W^l,W^W} \cap (\mathcal{W} \oplus (\mathcal{V}_{W^l})) \).

5. If \( p(\mathcal{V}_{W^l}) \) is decoupled, so are \( p(\mathcal{V}_{W^l} \cap \mathcal{W}) \) and \( p(\mathcal{V}_{W^l} \cap (\mathcal{V}_{W^l})) \).

6. If \( p(\mathcal{V}_{W^l,W^W} \cap (\mathcal{V}_{W^l}), p(\mathcal{V}_{W^l,W^W} \cap (\mathcal{V}_{W^l})^*) \) are decoupled, then \( p(\mathcal{V}_{W^l,W^W}) \) is decoupled.

The next result is a line by line dual of the previous theorem and therefore its proof is omitted.

9. Eigenvalue problem through annihilating polynomials

A fundamental problem in control theory is to ‘place poles’ in a desired region. The classical result here is that if the system is fully controllable, the poles can be placed where we wish using state feedback and dually, if the system is fully observable, the poles can be placed where we wish using output injection. There are neat refinements of this result when the system is not fully controllable or fully observable. In this section we derive implicit versions of this result.
9.1. Pole placement through state feedback and output injection

We will work with regular dynamical systems (RGDS), i.e.,

\[ \mathcal{V}_{W\hat{W}M,M_y} \circ W \supseteq (\mathcal{V}_{W\hat{W}M,M_y} \circ \hat{W})W, \quad \mathcal{V}_{W\hat{W}M,M_y} \times W \supseteq (\mathcal{V}_{W\hat{W}M,M_y} \times \hat{W})W. \]

This implies that \( \mathcal{V}_{W\hat{W}M,M_y} \circ W \hat{W} \) is a USG and \( \mathcal{V}_{W\hat{W}M,M_y} \times W \hat{W} \) is an LSG. Therefore ideas from Theorems 37 and 38 are applicable.

We now present the basic questions and remark upon their answers.

**Question 1.** Given an RGDS \( \mathcal{V}_{W\hat{W}M,M_y} \) what are the genops which can be obtained by \(wm_u \) feedback and \(m_y \hat{w} \) injection?

This question has been answered for general autonomous spaces in Theorems 37 and 38 and therefore also for genops. In brief the answer is:

The genop \( \mathcal{V}_{W\hat{W}} \) can be obtained by \(wm_u \) feedback iff it satisfies

\[ \mathcal{V}_{W\hat{W}M,M_y} \circ W \hat{W} \supseteq \mathcal{V}_{W\hat{W}}, \quad \mathcal{V}_{W\hat{W}M,M_y} \circ W \hat{W}M_u \times \hat{W} \subseteq \mathcal{V}_{W\hat{W}} \times \hat{W}. \]

The genop \( \mathcal{V}_{W\hat{W}} \) can be obtained by \(m_y \hat{w} \) injection iff it satisfies

\[ \mathcal{V}_{W\hat{W}M,M_y} \times W \hat{W} \subseteq \mathcal{V}_{W\hat{W}}, \quad \mathcal{V}_{W\hat{W}M,M_y} \times W \hat{W}M_y \circ W \supseteq \mathcal{V}_{W\hat{W}} \circ W. \]

**Question 2.** What polynomials can be made into minimal annihilating polynomials for genops obtainable by \(wm_u \) feedback and for those obtainable by \(m_y \hat{w} \) injection from the RGDF \( \mathcal{V}_{W\hat{W}M,M_y} \)?

We will only answer this question in a manner sufficient for pole placement purposes in order to simplify the discussion.

**\(wm_u \) feedback**

Let \( \mathcal{V}_{W\hat{W}}^{u} \equiv \mathcal{V}_{W\hat{W}M,M_y} \circ W \hat{W} \). We saw earlier that \( \mathcal{V}_{W\hat{W}}^{u} \) is a USG. If \( \mathcal{V}_{W\hat{W}}^{u} \) is already a genop, it cannot be altered by state feedback. We will therefore assume that \( \mathcal{V}_{W\hat{W}}^{u} \times W \) does not contain \( (\mathcal{V}_{W\hat{W}}^{u} \times \hat{W})W \).

Let \( \mathcal{V}_{W\hat{W}}^{com} \equiv (\mathcal{V}_{W\hat{W}}^{u} \times W \cap (\mathcal{V}_{W\hat{W}}^{u} \times \hat{W})W \).

Let \( \mathcal{V}_{W} \) be the minimal invariant space of \( \mathcal{V}_{W\hat{W}}^{u} \) containing \( \mathcal{V}_{W\hat{W}}^{u} \times \hat{W} \). In the case of \(wm_u \) feedback, the answer is:

1. A necessary condition is that the given polynomial must contain as a factor, the minimal annihilating polynomial \( p_u(s) \) of the genop \( \mathcal{V}_{W\hat{W}}^{u} + (\mathcal{V}_{W\hat{W}}^{u})\hat{W} \).
2. Let \( p_2(s) \) be any polynomial of degree equal to \( r(\mathcal{V}_{W}) \) \( r(\mathcal{V}_{W\hat{W}}^{com}) \). Then, through \(wm_u \) feedback, a genop \( \mathcal{V}_{W\hat{W}} \) can be obtained from \( \mathcal{V}_{W\hat{W}M,M_y} \) for which \( p_u p_2(s) \) is an annihilating polynomial.

In other words, the poles which are roots of \( p_u(s) \) cannot be shifted but we have full control over the remaining poles.

**\(m_y \hat{w} \) feedback**

Let \( \mathcal{V}_{W\hat{W}}^{l} \equiv \mathcal{V}_{W\hat{W}M,M_y} \times W \hat{W} \). We saw earlier that \( \mathcal{V}_{W\hat{W}}^{l} \) is an LSG. If \( \mathcal{V}_{W\hat{W}}^{l} \) is already a genop, it cannot be altered by output injection. We will therefore assume that \( \mathcal{V}_{W\hat{W}}^{l} \circ \hat{W} \) is not contained in \( (\mathcal{V}_{W\hat{W}}^{l} \circ W \hat{W} \circ W \).

Let \( \mathcal{V}_{W\hat{W}}^{com2} \equiv (\mathcal{V}_{W\hat{W}}^{l} \circ W) + (\mathcal{V}_{W\hat{W}}^{l} \circ \hat{W} \).

Let \( \mathcal{V}_{W} \) be the maximal invariant space of \( \mathcal{V}_{W\hat{W}}^{l} \) contained in \( \mathcal{V}_{W\hat{W}}^{l} \circ W \). In the case of \( m_y \hat{w} \) injection, the answer is:

52
1. A necessary condition is that the given polynomial must contain as a factor, the minimal annihilating polynomial \( p_l(s) \) of the genop \( V_{\hat{W}} \cap V_W \).

2. Let \( p_1(s) \) be any polynomial of degree equal to \( r(V_{\hat{W}}) - r(V_W) \). Then, through \( m_y \hat{w} \) injection, a genop \( V_{\hat{W}} \) can be obtained from \( V_{\hat{W}, M_\lambda M_\mu} \) for which \( p_1 p_1(s) \) is an annihilating polynomial.

In other words, the poles which are roots of \( p_l(s) \) cannot be shifted but we have full control over the remaining poles.

9.2. Constructing a genop with desired annihilating polynomial

Next, let us consider

**Question 3.** Let \( V_{\hat{W}} \) be the minimal invariant space of \( V_{\hat{W}} \), containing \( (V_{\hat{W}} \times \hat{W})_W \). How should we choose \( V_{\hat{W}} \) in such a way that \( V_{\hat{W}} \cap V_W \) has a desired annihilating polynomial?

The solution is well known in traditional control theory. We will give a simple solution in our frame work.

9.2.1. Building the genop \( V_{\hat{W}}^{\text{start}} \)

Our construction involves the idea of a ‘basic sequence’ which is analogous to the sequence 

\[
x^0, Ax^0, \ldots, A^k x^0, \ldots,
\]

for an operator \( A \). We will begin by building a genop \( V_{\hat{W}}^{\text{start}} \) (Algorithm I) with the annihilating polynomial of degree equal to \( r(V_W) - r(V_{\hat{W}}) \), where \( V_{\hat{W}}^{\text{com}} \equiv V_{\hat{W}} \times W \cap (V_{\hat{W}} \times \hat{W})_W \). Next, we modify the basic sequence of \( V_{\hat{W}}^{\text{start}} \) suitably (Equation 27) to obtain another sequence whose genop \( V_{\hat{W}}^{\text{end}} \) has the desired minimal annihilating polynomial.

**Definition 59.** Let \( V_{\hat{W}} \) be a USG and let \( V_W \) be invariant in it. We say \( x_0^W, x_1^W, \ldots, x_k^W \), is a basic sequence in \( V_{\hat{W}}^{\text{start}} \cap V_W \), iff 

\[
x_j^W \in V_W, \quad j = 0, 1, \ldots, k \\
V_W = sp\{x_j^W, j = 0, 1, 2, \ldots, k - 1\} + V_{\hat{W}}^{\text{com}}. \\
x_j^{W+1} \in (x_j^W \leftrightarrow V_{\hat{W}}^{\text{com}}), \quad j = 0, 1, \ldots, k - 1 \quad \text{and} \quad x_k^W \in V_W.
\]

We first construct a basic sequence in \( V_{\hat{W}}^{\text{start}} \cap V_W \), and from it build a genop \( V_{\hat{W}}^{\text{end}} \), for which it is a basic sequence.

**Algorithm I**

**Algorithm Basic sequence**

Input: genaut \( V_{\hat{W}}^{\text{start}} \)

Output:

1. A basic sequence \( x_0^W, x_1^W, \ldots, x_k^W \).
2. \( V_W \), the minimal space invariant in \( V_{\hat{W}}^{\text{start}} \cap V_W \), containing \( (V_{\hat{W}} \times \hat{W})_W \)
3. The genop \( V_{\hat{W}}^{\text{end}} \)

53
Step 1. Pick $x_0^W \in [(V^u_W \times \hat{W})_W - V^u_W \times W]$.

Step 2. Pick, if possible $x_{i+1}^W \in (x_i^W \leftrightarrow V^u_W)$, and $x_0^W, x_1^W, \ldots, x_{i+1}^W$ independent modulo $V^{com}_W$.

STOP if $x_i^W \leftrightarrow V^u_W \leq (sp\{x_i^W, j = 0, 1, 2, \ldots, j\} + V^{com}_W)_W$.

$k \leftarrow k + 1$.

$V_W \leftarrow sp\{x_i^W, j = 0, 1, 2, \ldots, k - 1\} + V^{com}_W$.

$V^{\text{start}}_W \leftarrow sp\{(x_i^W, x_{i+1}^W), j = 0, 1, 2, \ldots, k - 1\} + (V^{com}_W \oplus (V^{com}_W)_W)$.

Algorithm ends.

Note that the algorithm terminates, the first time the affine space $x_i^W \leftrightarrow V^u_W$ is contained in $(sp\{x_i^W, i = 0, 1, 2, \ldots, j\} + V^{com}_W)_W$. This is when $j = k - 1$. Thus we have,

$$(V^u_W)_W \equiv (sp\{x_i^W, j = 0, 1, 2, \ldots, k - 1\} + V^{com}_W)_W \text{ contains } x^{k-1}_W + V^u_W \times \hat{W} \text{ and therefore also } V^u_W \times \hat{W}.$$  

For $j < k - 1$, this does not happen.

Every vector in $x^{k-1}_W + V^u_W \times \hat{W} = x_i^W \leftrightarrow V^u_W$, $j = 0, 1, 2, \ldots, k - 1$, belongs to $(V^u_W)_W$ and

$$(x_i^W \leftrightarrow V^u_W)_W \subseteq V^u_W \times \hat{W} \subseteq (V^u_W)_W.$$  

Thus

$$(V^u_W)_W \leftrightarrow (V^u_W)_W \subseteq (V^u_W)_W.$$  

Now $V^u_W \circ W \supseteq V^u_W$, so that

$$(V^u_W)_W \leftrightarrow (V^u_W)_W \supseteq (V^u_W)_W.$$  

Thus $V_W$ is invariant in $V^u_W$.

Next any invariant space in $V^u_W$, containing $(V^u_W \times \hat{W})_W$ must contain $x_0^W$.

Therefore $(x_0^W \leftrightarrow V^u_W)_W$, $j = 0, \ldots, k - 1$.

It follows therefore that it must contain $V^u_W$.

Thus, $sp\{x_i^W, j = 0, 1, 2, \ldots, k - 1\} + V^{com}_W = V_W$, the minimal invariant space of $V^u_W$ containing $(V^u_W \times \hat{W})_W$.

It is clear that $V^{\text{start}}_W$ is USG since $V^{\text{start}}_W \circ W = V_W$ and $V_W$ is invariant in $V^u_W$.

Next the vectors $x_0^W, x_1^W, \ldots, x_k^W$ are independent modulo $V^{com}_W$.

So the only way in which vectors in $\{(x_i^W, x_{i+1}^W), j = 0, 1, 2, \ldots, k - 1\}$ can be linearly combined to yield a vector of the kind $(f_W, g_W)$, with $f_W \in V^{com}_W$, is through the trivial linear combination, which means that $g_W \in (V^{com}_W)_W$.

Therefore, $V^{\text{start}}_W \times W \subseteq (V^{com}_W)_W$.

It is LSG since $V^{\text{start}}_W \times W \supseteq V^{com}_W = (V^{\text{start}}_W \times \hat{W})_W$.

Thus $V^{\text{start}}_W$ is a genop.

**Definition 60.** We refer to $r(V_W^u) - r(V^{com}_W)$, as the essential rank of the invariant space $V^u_W$ of $V^u_W$.

For a genop $V_W$ the essential rank $er(V_W)$, is defined similarly to be $r(V_W W \circ W) - r(V_W W \times \hat{W})$.  

54
is the unique genop in the genaut $V$

**Definition 61.** The basic sequence $\{x^j_W\}$ output by the algorithm is referred to as a basic sequence for the genop $V^{\text{start}}_{W\hat{W}}$, while the genop $$ sp\{x^j_W, x^{j+1}_W, j = 0, 1, 2, \ldots k - 1\} + (V^\text{com}_{W\hat{W}} \oplus (V^\text{com})^c_{W\hat{W}}) $$

is the unique genop in the genaut $V^u_{W\hat{W}}$, for which $\{x^j_W, j = 0, 1, 2, \ldots k\}$ is a basic sequence. We will refer to this genop as the genop of the basic sequence.

**Remark 12.** Every genop does not have a basic sequence. A genop having a basic sequence is analogous to a matrix $A$ for which there exists a vector $x$ in its domain which is annihilated by the minimal annihilating polynomial of $A$.

**Claim 1.** Let $A$ be a polynomial of $A$.

Every genop does not have a basic sequence. A genop having a basic sequence is analogous to this genop as the genop of the basic sequence.

To prove the claim, we need to show that $p^{\text{start}}_{V^{\text{start}}_{W\hat{W}}}$ is decoupled and if $p'(s)$ has degree lower than that of $p^{\text{start}}_{V^{\text{start}}_{W\hat{W}}}$, then $p'(V^{\text{start}}_{W\hat{W}})$ is not decoupled.

Since $V^{\text{start}}_{W\hat{W}}$ is a genop, by Lemma 49, we have that for any polynomial $p(s)$,

$$ p(V^{\text{start}}_{W\hat{W}}) \circ W = V^{\text{start}}_{W\hat{W}} \circ W = V^W, \quad p(V^{\text{start}}_{W\hat{W}}) \times \hat{W} = V^{\text{start}}_{W\hat{W}} \times \hat{W} = (V^\text{com})_{W\hat{W}}. $$

This means that $p(V^{\text{start}}_{W\hat{W}})$ is decoupled if

$$ p(V^{\text{start}}_{W\hat{W}}) \circ W \iff p(V^{\text{start}}_{W\hat{W}}) \subseteq p(V^{\text{start}}_{W\hat{W}}) \times \hat{W} = V^{\text{start}}_{W\hat{W}} \times \hat{W} = (V^\text{com})_{W\hat{W}}. $$

We first show that for any vector $x^j_W$, $j = 0, 1, \ldots, k - 1$, we must have

$$ x^j_W \iff p^{\text{start}}_{V^{\text{start}}_{W\hat{W}}} \subseteq (V^\text{com})_{W\hat{W}}. $$

We have,

$$ (x^j_W)_{W\hat{W}} \in ((V^{\text{start}}(j)) \iff x^0_W). $$

Let $p_j(s) \equiv p^{\text{start}}_{V^{\text{start}}_{W\hat{W}}}s^j$. So

$$ p^{\text{start}}_{V^{\text{start}}_{W\hat{W}}} \iff x^j_W \subseteq p^{\text{start}}_{V^{\text{start}}_{W\hat{W}}} \iff (V^{\text{start}}(j)) \iff x^0_W = p^{\text{start}}_{V^{\text{start}}_{W\hat{W}}}((V^{\text{start}}(j)) \iff x^0_W = p_j(V^{\text{start}}_{W\hat{W}}) \iff x^0_W = [(V^{\text{start}}(j)) + p^{\text{start}}_{V^{\text{start}}_{W\hat{W}}}] \iff x^0_W = (V^{\text{start}}(j)) \iff p^{\text{start}}_{V^{\text{start}}_{W\hat{W}}} \subseteq (V^{\text{start}}(j)) \iff (V^\text{com})_{W\hat{W}} \subseteq (V^\text{com})_{W\hat{W}}. $$

Since every $x^j_W, j = 1, \ldots, k - 1$, satisfies $x^j_W \iff p^{\text{start}}_{V^{\text{start}}_{W\hat{W}}} \subseteq (V^\text{com})_{W\hat{W}}$, it follows that for every linear combination $x_W$ of these vectors we must have that $x_W \iff p^{\text{start}}_{V^{\text{start}}_{W\hat{W}}} \subseteq (V^\text{com})_{W\hat{W}}$.

Next for any polynomial $p(s)$, we have

$$ (p(V^{\text{start}}_{W\hat{W}}) \times W) \iff (p(V^{\text{start}}_{W\hat{W}}) \times W) = V^{\text{start}}_{W\hat{W}} \times \hat{W} = (V^\text{com})_{W\hat{W}}. $$

Now $p(V^{\text{start}}_{W\hat{W}}) \times W \subseteq V^{\text{start}}_{W\hat{W}} \times W \subseteq V^\text{com}_{W\hat{W}}$.

Hence, $V^\text{com}_{W\hat{W}} \iff p(V^{\text{start}}_{W\hat{W}}) = (V^\text{com})_{W\hat{W}}$.

Since $sp\{x^j_W, j = 0, 1, 2, \ldots k - 1\} + V^\text{com}_{W\hat{W}} = V_W$, we therefore have

$$ [p^{\text{start}}_{V^{\text{start}}_{W\hat{W}}} \circ W] \iff p^{\text{start}}_{V^{\text{start}}_{W\hat{W}}} = V_W \iff p^{\text{start}}_{V^{\text{start}}_{W\hat{W}}} \subseteq (V^\text{com})_{W\hat{W}} = p^{\text{start}}(V^{\text{start}}_{W\hat{W}}) \times \hat{W}, $$

55
i.e., $p^{start}(s)$ annihilates $V^{start}_{W_W}$.

Next, let $p(s) \equiv \sum_{i=0}^{t} c_i s^i$ and let $t \leq k - 1$. We have, $x_i^W \not\in sp\{x_0^W, x_1^W, \cdots, x_i^W - 1\} + V^{com}_{W_W}$. Let us temporarily, for the next couple of lines, denote $V^{start}_{W_W}$ by $V^{start}_{W_W}$ to simplify the notation.

Now $x_i^W \in V^{(t)}_{W_W} \iff x_0^W$. It follows that

$$p(s) \equiv \sum_{i=0}^{t} c_i s^i$$

does not annihilate $V^{start}_{W_W}$.

It follows that $p^{start}(s)$ is a polynomial of minimal degree that annihilates $V^{start}_{W_W}$. This proves the claim.

9.2.2. Building the genop $V^{end}_{W_W}$

Let $p^{end}(s) \equiv s^k + c_{k-1} s^{k-1} + \cdots + c_0$, be a specified polynomial. We will show how to modify $V^{start}_{W_W}$ to $V^{end}_{W_W}$ so that the latter has $p^{end}(s)$ as its minimal annihilating polynomial. We do this by building a basic sequence for $V^{end}_{W_W}$.

Let $y_0^W, y_1^W, \cdots, y_k^W$ be defined through

$$
\begin{align*}
y_0^W &= x_0^W \\
y_1^W &= x_1^W + \lambda_1 x_0^W \\
&\vdots \\
y_k^W &= x_k^W + \lambda_1 x_k^W + \cdots + \lambda_k x_0^W
\end{align*}
$$

We will adjust the $\lambda_i$ so that we have

$$y_k^W + c_{k-1} y_{k-1}^W + \cdots + c_0 y_0^W \in V^{com}_{W_W}.$$

Consider the vector equation, treating $x_i^W$ as symbols

$$
\begin{bmatrix}
x_0^W \\
x_1^W \\
\vdots \\
x_k^W
\end{bmatrix}
\begin{bmatrix}
\begin{bmatrix} c_0 \\ c_1 \\ \vdots \\ c_k \end{bmatrix} & \begin{bmatrix} x_0^W \\ x_1^W \\ \vdots \\ x_k^W \end{bmatrix}
\end{bmatrix} =
\begin{bmatrix}
\begin{bmatrix} \alpha_0 \\ \alpha_1 \\ \vdots \\ \alpha_k \end{bmatrix}
\end{bmatrix}
$$

(28)

(In the above equation $x_i^W, \alpha_i$ can be thought of as column vectors.) It is easy to see that this equation in the symbols $x_i^W$, can be rewritten as

$$
\begin{bmatrix}
c_0 & c_1 & \cdots & c_k \\ c_1 & \cdots & c_k & 0 \\ \vdots & \vdots & \vdots & \vdots \\ c_k & 0 & \cdots & 0
\end{bmatrix}
\begin{bmatrix}
x_0^W \\ x_1^W \\ \vdots \\ x_k^W
\end{bmatrix}
= 
\begin{bmatrix}
\begin{bmatrix} \alpha_0 \\ \alpha_1 \\ \vdots \\ \alpha_k \end{bmatrix}
\end{bmatrix}
$$

(29)

(Here however the symbols $x_i^W, \alpha_i$ are to be interpreted as row vectors.) Now consider the expression

$$
\begin{bmatrix}
\lambda_0 & \cdots & \lambda_k
\end{bmatrix}
\begin{bmatrix}
x_0^W \\
x_1^W \\
\vdots \\
x_k^W
\end{bmatrix}
= z.
$$

(30)
If we choose the $\lambda_i$ so that the Equation 27 is satisfied, Equation 30 would reduce to
\[
\begin{bmatrix}
y_0^W & y_1^W & \cdots & y_k^W
\end{bmatrix} \begin{pmatrix}
c_0 \\
c_1 \\
\vdots \\
c_k
\end{pmatrix} = z. \tag{31}
\]
We would like to choose $y_i^W$ so that $z \in V_{W}^{com}$. So we first rewrite the expression in Equation 30 as
\[
(\lambda_0 \cdots \lambda_k) \begin{bmatrix}
c_0 & c_1 & \cdots & c_k \\
c_1 & \cdots & c_k & 0 \\
\vdots & \vdots & \vdots & \vdots \\
c_k & 0 & \cdots & 0
\end{bmatrix} \begin{pmatrix}
x_0^W \\
x_1^W \\
\vdots \\
x_k^W
\end{pmatrix} = z \tag{32}
\]
and choose the $\lambda_i$ so that
\[
(\lambda_0 \cdots \lambda_k) \begin{bmatrix}
c_0 & c_1 & \cdots & c_k \\
c_1 & \cdots & c_k & 0 \\
\vdots & \vdots & \vdots & \vdots \\
c_k & 0 & \cdots & 0
\end{bmatrix} = (b_0 \cdots b_k) \tag{33}
\]
This is always possible since the coefficient matrix has nonzero entries $c_k = 1$ along the skew diagonal and zero entries beneath it. But now the expression in Equation 30 reduces to
\[
(b_0 \cdots b_k) \begin{pmatrix}
x_0^W \\
x_1^W \\
\vdots \\
x_k^W
\end{pmatrix} \in V_{W}^{com}, \tag{34}
\]
since $x_k^W + b_{k-1}x_{k-1}^W + \cdots + b_0x_0^W \in V_{W}^{com}$.

Thus if we choose
\[
(\lambda_0 \cdots \lambda_k) = (b_0 \cdots b_k) \begin{bmatrix}
c_0 & c_1 & \cdots & c_k \\
c_1 & \cdots & c_k & 0 \\
\vdots & \vdots & \vdots & \vdots \\
c_k & 0 & \cdots & 0
\end{bmatrix}^{-1}, \tag{35}
\]
and use this vector $(\lambda_0, \cdots, \lambda_k)$ in Equation 27 the resulting basic sequence $y_0^W, y_1^W, \cdots, y_k^W$ would define the genop $V_{W}^{end}$ through
\[
V_{W}^{end} \equiv sp\{y_j^W, y_{j+1}^W, j = 0, 1, 2, \ldots, k - 1\} + (V_{W}^{com} \oplus (V_{W}^{com}))_W.
\]
Since $y_k^W + c_{k-1}y_{k-1}^W + \cdots + c_0y_0^W \in V_{W}^{com}$, the polynomial $\rho_{end}(s) \equiv s^k + c_{k-1}s^{k-1} + \cdots + c_0$, annihilates $V_{W}^{end}$.

We summarize the above procedure to construct a genop with the desired annihilating polynomial in the following algorithm.
Algorithm II
Algorithm Annihilating polynomial to genop

Input: A genop $\mathcal{V}_{\text{start}} \subseteq \mathcal{V}_W^u$, with annihilating polynomial $p_u(s) = \sum_{i=0}^{k} b_i s^i$, and a desired annihilating polynomial $\sum_{i=0}^{k} c_i s^i$.

Output: A genop $\mathcal{V}_{\text{end}} \subseteq \mathcal{V}_W^u$ with annihilating polynomial $p_e(s) = \sum_{i=0}^{k} c_i s^i$.

Step 1. Compute $\lambda_i, i = 0, \ldots, k$ from $p_u(s), p_e(s)$ using Equation 28.

Step 2. Compute the basic sequence $y_0^W, \ldots, y_k^W$ from a basic sequence $x_0^W, \ldots, x_k^W$ of $\mathcal{V}_{\text{start}}^u$ using Equation 27.

Step 3. $\mathcal{V}_{\text{end}}^u \leftarrow sp\{(y_0^W, y_1^W), j = 0, 1, 2, \ldots k - 1\} + (\mathcal{V}_W^{\com} \oplus (\mathcal{V}_W^{\com})^W)$.

Algorithm Ends.

9.2.3. Building the genop $\mathcal{V}_{\text{new}}^u$ on $W^W$

Now we could grow $\mathcal{V}_{\text{end}}^u$ to a genop $\mathcal{V}_{\text{new}}^u$, where $\mathcal{V}_{\text{new}}^u \circ W = \mathcal{V}_W^u \circ W$. For this we use the following algorithm which starts with a basic sequence in $\mathcal{V}_W^u \cap \mathcal{V}_W^u$ and outputs $\mathcal{V}_{\text{new}}^u$.

Algorithm III
Algorithm Basic2genop

Input: A genop $\mathcal{V}_{\text{end}}^u \subseteq \mathcal{V}_W^u$.

Output: A genop $\mathcal{V}_{\text{new}}^u$ where $\mathcal{V}_{\text{new}}^u \circ W = \mathcal{V}_W^u \circ W$ and $\mathcal{V}_{\text{new}}^u \supseteq \mathcal{V}_{\text{end}}^u$.

Step 1. Let $t = r(\mathcal{V}_W^u \circ W) - r(\mathcal{V}_{\text{end}}^u \circ W)$. Construct a sequence of vectors $u_1^W, u_2^W, \ldots, u_t^W$ from $\mathcal{V}_W^u \circ W$, which are independent modulo $\mathcal{V}_W = \mathcal{V}_{\text{end}}^u \circ W$.

(Thus if $sp\{y_0^W, y_1^W, \ldots, y_k^W\} + \mathcal{V}_W^{\com} = \mathcal{V}_{\text{end}}^u \circ W$; then

$$sp\{y_0^W, y_1^W, \ldots, y_k^W, u_1^W, u_2^W, \ldots, u_t^W\} + \mathcal{V}_W^{\com} = \mathcal{V}_W^u \circ W.$$)

Step 2. Pick vectors $v_1^W, v_2^W, \ldots, v_t^W$, such that $(u_1^W, v_1^W), \ldots, (u_t^W, v_t^W) \in \mathcal{V}_W^u$.

Step 3. $\mathcal{V}_{\text{new}}^u \leftarrow sp\{u_1^W, v_1^W\}, \ldots, (u_t^W, v_t^W)\} + sp\{(y_0^W, y_1^W), j = 0, 1, 2, \ldots k - 1\} + (\mathcal{V}_W^{\com} \oplus (\mathcal{V}_W^{\com})^W)$.

Algorithm Ends.

9.2.4. Proof that $\mathcal{V}_{\text{new}}^u$ is a genop with desired annihilating polynomial

We will now show that $\mathcal{V}_{\text{new}}^u$ is a genop and has as an annihilating polynomial $p_u p_{\text{end}}(s)$, where $p_u(s)$ is the minimal annihilating polynomial of $\mathcal{V}_W^u$ and $p_{\text{end}}(s) \equiv k + c_k - 1 s^{k - 1} + \cdots c_0$, the annihilating polynomial of $\mathcal{V}_{\text{end}}^u$. We know that

$$\mathcal{V}_{\text{new}}^u \circ W = \mathcal{V}_W^u \circ W \supseteq (\mathcal{V}_W^u \circ \hat{W})_W \supseteq (\mathcal{V}_{\text{new}}^u \circ \hat{W})_W.$$
Next the the vectors \( y^0_W, y_W, \ldots, y^k_W, u^1_W, u^2_W, \ldots, u^{t}_W \) are independent modulo \( \mathcal{V}^\text{com}_W \). So the only way in which vectors in

\[
\{(y^j_W, y_W^{j+1}), j = 0, 1, 2, \ldots, k - 1\} \cup \{(u^1_W, v^1_W), \ldots, (u^t_W, v^t_W)\}
\]

can be linearly combined to yield a vector of the kind \((f_W, g_W)\), with \( f_W \in \mathcal{V}^\text{com}_W \) is through the trivial linear combination, which means that

\[
g_W, \in (\mathcal{V}^\text{com}_W)_W.
\]

Therefore, \( \mathcal{V}^{\text{new}}_{W\dot{W}} \times \dot{W} \subseteq (\mathcal{V}^\text{com}_W)_W \). We already know that \( \mathcal{V}^{\text{new}}_{W\dot{W}} \times \dot{W} \supseteq (\mathcal{V}^\text{com}_W)_W \), so that we must have

\[
\mathcal{V}^{\text{new}}_{W\dot{W}} \times \dot{W} = (\mathcal{V}^\text{com}_W)_W.
\]

It is clear that \( \mathcal{V}^{\text{new}}_{W\dot{W}} \times W \supseteq \mathcal{V}^\text{com}_W \) and \( (\mathcal{V}^{\text{new}}_{W\dot{W}} \times W)_W \supseteq (\mathcal{V}^\text{com}_W)_W \). Thus we conclude

\[
\mathcal{V}^{\text{new}}_{W\dot{W}} \times W \supseteq \mathcal{V}^\text{com}_W = (\mathcal{V}^{\text{new}}_{W\dot{W}} \times \dot{W})_W.
\]

Hence \( \mathcal{V}^{\text{new}}_{W\dot{W}} \) is a genop and has as an annihilating polynomial (using part 6 of Theorem 51) \( p_u p^{\text{end}}(s) \), where \( p_u(s) \) is the minimal annihilating polynomial of \( \mathcal{V}^u_{W\dot{W}} \), \( (\mathcal{V}_W \equiv (\mathcal{V}_W)_W) \) and \( p^{\text{end}}(s) \), the annihilating polynomial of \( \mathcal{V}^{\text{end}}_{W\dot{W}} \).

Further, the minimal annihilating polynomial of \( \mathcal{V}^{\text{new}}_{W\dot{W}} \) contains both \( p_u(s) \) and \( p^{\text{end}}(s) \) as factors by Theorem 51. Thus the poles of the controlled dynamical system are precisely the roots of \( p_u(s) \) and \( p^{\text{end}}(s) \).

Finally recall that any generalized autonomous system \( \mathcal{V}_{W\dot{W}} \) that satisfies

1. \( \mathcal{V}_{W\dot{W}M_u,M_u} \circ W \dot{W} \supseteq \mathcal{V}_{W\dot{W}} \),
2. \( \mathcal{V}_{W\dot{W}M_u,M_u} \circ W \dot{W}M_u \times \dot{W} \supseteq \mathcal{V}_{W\dot{W}} \times \dot{W} \),

can be realized by \( wM_u \)-feedback through \( \mathcal{V}_{W\dot{W}M_u} \), i.e.,

\[
\mathcal{V}_{W\dot{W}} = (\mathcal{V}_{W\dot{W}M_u,M_u} \cap \mathcal{V}_{W\dot{W}M_u}) \circ W \dot{W}M_u, \]

where \( \mathcal{V}_{W\dot{W}M_u,M_u} \equiv (\mathcal{V}_{W\dot{W}M_u,M_u} \cap \mathcal{V}_{W\dot{W}M_u}) \circ W \dot{W}M_u \).

The first condition states simply that \( \mathcal{V}^u_{W\dot{W}} \supseteq \mathcal{V}_{W\dot{W}} \). This is clearly satisfied by the genop \( \mathcal{V}^{\text{new}}_{W\dot{W}} \) constructed by the Algorithm II.

To satisfy the second condition we need that

\[
(\mathcal{V}_{W\dot{W}M_u,M_u} \circ W \dot{W}M_u \times \dot{W})_W \subseteq \mathcal{V}^\text{com}_{W\dot{W}} \equiv \mathcal{V}^u_{W\dot{W}} \times W \cap (\mathcal{V}^u_{W\dot{W}} \times \dot{W})_W.
\]

In commonly encountered situations if \( w(0) = 0 \) and the input is zero, the derivative \( \dot{w}(t) \) will be zero for \( t \geq 0 \) (and therefore also for \( t = 0 \)), which means \( \mathcal{V}_{W\dot{W}M_u,M_u} \circ W \dot{W}M_u \times \dot{W} = 0 \), so that the second condition is also satisfied by \( \mathcal{V}^{\text{new}}_{W\dot{W}} \).

Remark 13. Let \( \mathcal{V}_W \) be the minimal invariant space of a USG \( \mathcal{V}^u_{W\dot{W}} \) containing \( (\mathcal{V}^u_{W\dot{W}} \times \dot{W})_W \). We have seen above that we can choose a genop \( \mathcal{V}^{*}_{W\dot{W}} \) in such a way that \( \mathcal{V}_{W\dot{W}} \cap \mathcal{V}_W \) has any desired annihilating polynomial of degree \( k \), where

\[
k \equiv r(\mathcal{V}_W) - r(\mathcal{V}_W^\text{com}), \quad \mathcal{V}_W^\text{com} \equiv \mathcal{V}_W^u \times W \cap (\mathcal{V}_W^u \times \dot{W})_W.
\]

A consequence of part 4 of Lemma 52 is that, since

\[
\mathcal{V}_W = \mathcal{V}_{W\dot{W}} \cap \mathcal{V}_W \circ W = \mathcal{V}_W^u \cap \mathcal{V}_W \circ W, \quad \mathcal{V}_{W\dot{W}} \cap \mathcal{V}_W \subseteq \mathcal{V}_W^u \cap \mathcal{V}_W,
\]

59
the space $\mathcal{V}_{WW}^m \cap \mathcal{V}_W$, which is USG, can also be annihilated by any annihilating polynomial of degree $k$, in particular, by $s^k$.

Dually, if $\mathcal{V}_W$ be the maximal invariant space of an LSG $\mathcal{V}_{WW}^l$, contained in $\mathcal{V}_{WW}^l \circ W$, then by part 5 of Lemma 52.

$\mathcal{V}_{WW}^l + (\mathcal{V}_W)_W$, can be annihilated by any annihilating polynomial of degree $k$,

$$k \equiv r[\mathcal{V}_{WW}^l \circ W + (\mathcal{V}_{WW}^l \circ W)_W] - r(\mathcal{V}_W),$$

in particular, by $s^k$.

The foregoing algorithms can be used indirectly to do pole placement for $m_w$- injection. One does this by simply going to the adjoint and using the algorithms of the previous subsections to obtain suitable genops, taking their adjoints and returning to the primal dynamical system. It would, however, be of some interest to recast the algorithm in such a manner that they can be line by line dualized. This we do in Appendix D.

10. Emulators

10.1. Introduction

Dynamical systems do not always come in a form that is suitable for theoretical and practical studies. We usually convert the original system into another dynamical system that is more convenient for our purposes. The dynamical system as described by state variables is a very good example. We call such transformed systems, which capture the original dynamical system sufficiently well so that theoretical and computational studies can be carried out, ‘emulators’. A formal definition and examples follow.

**Definition 62.** Dynamical systems $\mathcal{V}_{WW}^l, \mathcal{V}_{PP}^l$ are said to be **emulators** of each other iff $\exists \mathcal{V}_W^1, \mathcal{V}_W^2$ with $\mathcal{V}_W^1 \supseteq (\mathcal{V}_W^2)_{WP}$ such that

$$\mathcal{V}_{WW}^l = \mathcal{V}_{PP}^l \leftrightarrow (\mathcal{V}_W^1 \bigoplus \mathcal{V}_W^2)$$

and

$$\mathcal{V}_{PP}^l = \mathcal{V}_{WW}^l \leftrightarrow (\mathcal{V}_W^1 \bigoplus \mathcal{V}_W^2).$$

In particular, when $M$ is void, $\mathcal{V}_{WW}^l, \mathcal{V}_{PP}^l$ are said to be **emulators** of each other iff $\exists \mathcal{V}_W^1, \mathcal{V}_W^2$ with $\mathcal{V}_W^1 \supseteq (\mathcal{V}_W^2)_{WP}$, such that,

$$\mathcal{V}_{WW}^l = \mathcal{V}_{PP}^l \leftrightarrow (\mathcal{V}_W^1 \bigoplus \mathcal{V}_W^2)$$

and

$$\mathcal{V}_{PP}^l = \mathcal{V}_{WW}^l \leftrightarrow (\mathcal{V}_W^1 \bigoplus \mathcal{V}_W^2).$$

If such $\mathcal{V}_W^1, \mathcal{V}_W^2$, exist, we say that $\{\mathcal{V}_{WW}^l, \mathcal{V}_{PP}^l\}$ is $\mathcal{E}$- linked through $\mathcal{V}_W^1, \mathcal{V}_W^2$, or that $\{\mathcal{V}_W^1, \mathcal{V}_W^2\}$ is an $\mathcal{E}$- **linkage pair** for $\{\mathcal{V}_{WW}^l, \mathcal{V}_{PP}^l\}$.

An immediate consequence is that elimination of the $M$ variables continues to result in a pair of spaces linked through the same $\mathcal{E}$- linkage pair.

**Lemma 63.** Let $\{\mathcal{V}_{WW}^l, \mathcal{V}_{PP}^l\}$ be $\mathcal{E}$- linked through $\mathcal{V}_W^1, \mathcal{V}_W^2$.

Then so is $\{\mathcal{V}_{WW}^l \leftrightarrow \mathcal{V}_M, \mathcal{V}_{PP}^l \leftrightarrow \mathcal{V}_M\}$ $\mathcal{E}$- linked through $\mathcal{V}_{WP}^1, \mathcal{V}_{WP}^2$. 60
Let Theorem 64.

emulators can be built in near linear time and these are in fact more useful than state equations.

the original dynamic system.

statement holds for $m$.

As another example, we will show that to perform

through the linkage, make the computations there and get back to $V_{W\hat{w}M}$ again through the $E-$ linkage. As another example, we will show that to perform $w_{m_{u}-}$ feedback we can first go to $V_{P\hat{P}M}$ through the $E-$ linkage, do the $pm_{u}-$ feedback $V_{PM_{\hat{P}}P_{\hat{P}}} V_{WP}W_{WP}$ and get back to $V_{W\hat{w}M}$ through the linkage $\{V_{WP}, V_{WP}^2 \}$. The effect would be the same as performing $w_{m_{u}-}$ feedback directly on $V_{W\hat{w}M}$. A similar statement holds for $m_{y}\hat{w}-$ injection.

Lastly, and most importantly, spectral computations can be performed on emulators and transferred to the original dynamical system.

We will show that for a large class of electrical circuits, which could be regarded as generic, some emulators can be built in near linear time and these are in fact more useful than state equations.

The following result describes an essential characteristic of emulator linkage pairs.

**Theorem 64.** Let $(V_{WP}^1, V_{WP}^2)$ be an $E-$ linkage for $\{V_{W\hat{w}M}, V_{P\hat{P}M}\}$. Then the following ‘dot-cross’ conditions hold

\[
V_{WP}^1 \circ W \supseteq V_{W\hat{w}M} \circ W \tag{36a}
\]
\[
V_{WP}^1 \times W \subseteq V_{W\hat{w}M} \times W \tag{36b}
\]
\[
V_{WP}^2 \circ \hat{W} \supseteq V_{W\hat{w}M} \circ \hat{W} \tag{36c}
\]
\[
V_{WP}^2 \times \hat{W} \subseteq V_{W\hat{w}M} \times \hat{W} \tag{36d}
\]

and also the same conditions replacing $W$ by $P$,

\[
V_{WP}^1 \circ P \supseteq V_{P\hat{P}M} \circ P \tag{37a}
\]
\[
V_{WP}^1 \times P \subseteq V_{P\hat{P}M} \times P \tag{37b}
\]
\[
V_{WP}^2 \circ \hat{P} \supseteq V_{P\hat{P}M} \circ \hat{P} \tag{37c}
\]
\[
V_{WP}^2 \times \hat{P} \subseteq V_{P\hat{P}M} \times \hat{P}. \tag{37d}
\]

Further, if the above conditions hold, then

$V_{W\hat{w}M} = V_{P\hat{P}M} \leftrightarrow (V_{WP}^1 \bigoplus V_{WP}^2)$
iff
\[ V_{P\dot{P}M} = V_{W\dot{W}M} \leftrightarrow (V_{WP}^1 \oplus V_{WP}^2). \]

**Proof.** The proof follows from Theorem 2 and the fact that
\((V_{AB} \oplus V_{CD}) \circ A = V_{AB} \circ A\) and \((V_{AB} \oplus V_{CD}) \times A = V_{AB} \times A\), when \(A, B, C, D\) are mutually disjoint. \(\square\)

The next lemma stresses an easy consequence of the definition of \(E-\) linkage, which is nevertheless useful.

**Lemma 65.** Let \(\{V_{W\dot{W}}, V_{P\dot{P}}\}\) be \(E-\) linked through \(V_{WP}, V_{WP}^2\). Then

1. \[ V_{W\dot{W}} \circ W \leftrightarrow V_{WP}^1 \circ P, \quad V_{W\dot{W}} \times W \leftrightarrow V_{WP}^1 \times P, \]
2. \[ V_{W\dot{W}} \circ \dot{W} \leftrightarrow V_{WP}^2 \circ \dot{P}, \quad V_{W\dot{W}} \times \dot{W} \leftrightarrow V_{WP}^2 \times \dot{P}. \]

**Proof.** 1. Follows directly from the definition of \(E-\) linkage.
2. If \(V_{W\dot{W}}\) is decoupled then \(V_{W\dot{W}} = (V_{W\dot{W}} \circ W) \oplus (V_{W\dot{W}} \circ \dot{W})\). The result now follows from the previous part of the present lemma.

\(\square\)

10.2. Motivation

In this subsection we illustrate the idea of emulators through examples involving electrical networks. Our aim is two fold. Firstly we try to show that something of the level of generality of emulators is needed to deal implicitly with the objects we are concerned with. Secondly our aim is to show that for large systems which interlink small dynamical systems through graphs, emulators can be built very efficiently and can serve as convenient starting points for practical computations.

**Example 66.** Consider the GDSA represented by the circuit \(\mathcal{N}\) in Fig 2. Let us take all capacitors of value 1F and all resistors of value 1Ω. The corresponding GDS \(V_{W\dot{W},M}\) is the solution space of the equations given below. Here the \(W\) variables are \(v_{C1}, v_{C2}, v_{C3}\), the \(\dot{W}\) variables are \(\dot{v}_{C1}, \dot{v}_{C2}, \dot{v}_{C3}\), and the \(M\) variables
are $j_5, v_6, v_5, i_6$.

\[
\begin{align*}
\dot{v}_C & = \begin{bmatrix} -2/3 & 0 & 0 \\ 1/3 & 0 & 0 \\ 1/3 & 0 & 0 \end{bmatrix} \begin{bmatrix} v_C \\ v_C \\ v_C \end{bmatrix} + \begin{bmatrix} 2/3 \\ -1/3 \\ -1/3 \end{bmatrix} v_6 + \begin{bmatrix} 2/3 \\ -1/3 \\ -1/3 \end{bmatrix} j_5 & \quad (38a) \\
0 & = \begin{bmatrix} 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} v_C \\ v_C \\ v_C \end{bmatrix} & \quad (38b) \\
\begin{bmatrix} i_6 \\ v_5 \end{bmatrix} & = \begin{bmatrix} 1 & 0 & 0 \\ -1 & 0 & 0 \end{bmatrix} \begin{bmatrix} v_C \\ v_C \\ v_C \end{bmatrix} + \begin{bmatrix} -1 \\ 0 \end{bmatrix} v_6 + \begin{bmatrix} 0 \\ 0 \end{bmatrix} j_5. & \quad (38c)
\end{align*}
\]

Since $P$ variables and $W$ variables have to be disjoint and so also the variables $\dot{W}$ and $\dot{P}$ we define the new $P, \dot{P}$ variables $v'_C, v'_C, v'_C, v'_C$ taking $v'_C = v_C, v'_C = v_C, v'_C = v_C, v'_C = v_C$. The GDS $\mathcal{V}_{P\dot{P}M}$ is the solution space of the state and output equations (of the circuit in Figure 2) given below:

\[
\begin{align*}
\begin{bmatrix} \dot{v}'_C \\ \dot{v}'_C \end{bmatrix} & = \begin{bmatrix} -2/3 & 0 \\ 1/3 & 0 \end{bmatrix} \begin{bmatrix} v'_C \\ v'_C \end{bmatrix} + \begin{bmatrix} 2/3 \\ -1/3 \end{bmatrix} v_6 + \begin{bmatrix} 2/3 \\ -1/3 \end{bmatrix} j_5 & \quad (39a) \\
\begin{bmatrix} i_6 \\ v_5 \end{bmatrix} & = \begin{bmatrix} 1 & 0 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} v'_C \\ v'_C \end{bmatrix} + \begin{bmatrix} -1 \\ 0 \end{bmatrix} v_6 + \begin{bmatrix} 0 \\ 0 \end{bmatrix} j_5. & \quad (39b)
\end{align*}
\]

The GDS pair $\{\mathcal{V}_{W\dot{W}M}, \mathcal{V}_{P\dot{P}M}\}$ is $E$-linked and the two GDS's are emulators of each other.

Next let us build a suitable $E$-linkage $\{\mathcal{V}_{WP}, \mathcal{V}_{WP}'\}$ for this pair. Observe that the constraint on $v_C, v_C, v_C$ is

\[
v_C + v_C + v_C = 0.
\]

The constraints on $\dot{v}_C, \dot{v}_C, \dot{v}_C$, are

\[
\begin{bmatrix} \dot{v}_C + \dot{v}_C + \dot{v}_C \\ \dot{v}_C/C - \dot{v}_C/C \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}.
\]

Thus the space of all vectors $(v_C, v_C, v_C)$ is the space spanned by the rows of

\[
\begin{bmatrix} 2 & -1 & -1 \\ 0 & 1 & -1 \end{bmatrix}.
\]

Similarly the space of all vectors $(\dot{v}_C, \dot{v}_C, \dot{v}_C)$ is the space spanned by the row

\[
\begin{bmatrix} 2 & -1 & -1 \end{bmatrix}.
\]

The space $\mathcal{V}_{WP}^1$ can be the space of all vectors $(v_C, v_C, v_C, v'_C, v''_C)$ spanned by the rows of

\[
\begin{bmatrix} 2 & -1 & -1 & 2 & -1 \\ 0 & 1 & -1 & 0 & 1 \end{bmatrix}.
\]

The space $\mathcal{V}_{WP}^2$, can be the space of all vectors $(\dot{v}_C, \dot{v}_C, \dot{v}_C, v'_C, v''_C)$ spanned by the row

\[
\begin{bmatrix} 2 & -1 & -1 & 2 & -1 \end{bmatrix}.
\]

One can verify just by inspection that

\[
\mathcal{V}_{W\dot{W}M} \leftrightarrow (\mathcal{V}_{WP}^1 \bigoplus \mathcal{V}_{WP}^2) = \mathcal{V}_{P\dot{P}M}'.
\]
and also that all the following ‘dot-cross’ conditions are satisfied:

\[ V_{WP}^1 \circ W = V_{WM} \circ W, \quad V_{WP}^1 \times W \subseteq V_{WM} \times W, \quad V_{WP}^2 \circ \dot{W} = V_{WM} \circ \dot{W}, \quad V_{WP}^2 \times \dot{W} = V_{WM} \times \dot{W}, \]

\[ V_{WP}^1 \circ P = V_{FM} \circ P, \quad V_{WP}^1 \times P \subseteq V_{FM} \times P, \quad V_{WP}^2 \circ \dot{P} = V_{FM} \circ \dot{P}, \quad V_{WP}^2 \times \dot{P} = V_{FM} \times \dot{P}. \]

This is equivalent to working with the reduced set of variables \( v_{C1}, v_{C2}, \dot{v}_{C1}, \dot{v}_{C2} \) when we move from \( W \) to \( P \) and \( \dot{W} \) to \( \dot{P} \) variables. It must be noted that other linkages would also work in this case. For instance we could have taken both \( V_{WP}^1 \) and \( V_{WP}^2 \) to be spanned by the vectors

\[
\begin{bmatrix}
2 & -1 & -1 & 2 & -1 \\
0 & 1 & -1 & 0 & -1
\end{bmatrix}.
\]

However, this latter linkage does not reveal as much about the relationship between the emulators as the linkage defined earlier and in this case the conditions

\[ V_{WP}^2 \circ \dot{W} \supseteq V_{WM} \circ \dot{W}, \quad V_{WP}^2 \circ \dot{P} \supseteq V_{FM} \circ \dot{P} \]

are not satisfied with equality.

Next let us consider an emulator which does not correspond to state equations of the system. It is important because it is easy to construct algorithmically (near linear time) but captures the eigen spaces of the system, corresponding to nonzero eigen values, exactly. It is sufficient for complete solution of the network as we show in Example 6.7.

We define the new \( Q, \dot{Q} \) variables \( v_C, \dot{v}_C \), taking

\[ v_C = v_{C1}, \quad \dot{v}_C = -v_{C2} - v_{C3}, \quad \dot{v}_C = \dot{v}_{C1} + \frac{1}{2} (v_{C1} + \dot{v}_{C2}). \]

The GDS \( V_{QM} \), is the solution space of the equations (of the circuit in Figure 2) given below:

\[
\begin{align*}
\dot{v}_C &= \begin{bmatrix} -2/3 \end{bmatrix} v_C + \begin{bmatrix} 2/3 \end{bmatrix} v_6 + \begin{bmatrix} 2/3 \end{bmatrix} j_5 \quad (41a) \\
\begin{bmatrix} \dot{v}_6 \end{bmatrix} &= \begin{bmatrix} 1 \\ -1 \end{bmatrix} v_C + \begin{bmatrix} -1 \\ 0 \end{bmatrix} v_6 + \begin{bmatrix} 0 \\ 0 \end{bmatrix} j_5. \quad (41b)
\end{align*}
\]

The GDS pair \( \{V_{WM}, V_{QM}\} \) is \( \mathcal{E} \)-linked and the two GDS’s are emulators of each other.

Next let us build a suitable \( \mathcal{E} \)-linkage \( \{V_{WQ}, V_{WQ}^2\} \) for this pair.

The space \( V_{WQ}^1 \) can be the space of all vectors \((v_{C1}, v_{C2}, v_{C3}, v_C)\) spanned by the rows of

\[
\begin{bmatrix}
2 & -1 & -1 & 2 \\
0 & 1 & -1 & 0
\end{bmatrix}.
\]

The space \( V_{WQ}^2 \) can be the space of all vectors \((\dot{v}_{C1}, \dot{v}_{C2}, \dot{v}_{C3}, \dot{v}_C)\) spanned by the row

\[
\begin{bmatrix}
2 & -1 & -1 & 2
\end{bmatrix}.
\]

One can verify just by inspection that

\[ V_{WM} \leftrightarrow (V_{WQ}^1 \bigoplus V_{WQ}^2) = V_{QM}. \]

and also that all the following ‘dot-cross’ conditions are satisfied (with equality):

\[ V_{WQ}^1 \circ W = V_{WM} \circ W, \quad V_{WQ}^1 \times W = V_{WM} \times W, \quad V_{WQ}^2 \circ \dot{W} = V_{WM} \circ \dot{W}, \quad V_{WQ}^2 \times \dot{W} = V_{WM} \times \dot{W}, \]
Figure 3: An RLCEJ Network and its multiport decomposition into capacitive multiport and (static + L) multiport

\[ V_{WQ} \circ Q = V_{QQM} \circ Q, \quad V_{WQ}^1 \times Q = V_{QQM} \times Q, \quad V_{WQ}^2 \circ \dot{Q} = V_{QQM} \circ \dot{Q}, \quad V_{WQ}^2 \times \dot{Q} = V_{QQM} \times \dot{Q}. \]

This is equivalent to working with the reduced set of variables \( v_C, \dot{v}_C \) when we move from \( W \) to \( Q \) and \( \dot{W} \) to \( \dot{Q} \) variables.

**Example 67.** In this example we outline the topological procedure of multiport decomposition for building an emulator.

Consider the GDSA represented by the circuit \( N \) in Figure 3(a).

In order to efficiently build an emulator for the system we follow the procedure given below.

**Topological procedure for emulator construction**

**Step 1.** Decompose the network \( N \) into two multiports \( N_{CP}, N_{2P_1} \) and the port connection diagram \( G_{P_1P_3} \) with minimum number of ports as in Fig 3. Here \( N_{CP} \) contains all the capacitors and \( N_{2P_1} \), all the other devices.

It can be shown that in any multiport decomposition with minimum number of ports, the ports will not contain cutsets or circuits of the graphs which figure in the decomposition.

[A linear time algorithm for doing this, based only on the graph of the network, is given in Subsection 2.3. This is justified in [30] and [8]. For general vector space based systems slower decomposition algorithms are available in the same references.]

Figure 3 shows (a) an RLCEJ Network \( N \), its multiport decomposition into (b) the capacitive multiport \( N_{CP} \), (c) the port connection diagram \( G_{P_1P_3} \), and (d) the (static + L) multiport \( N_{2P_1} \).

**Step 2.** Decompose the network \( N_{2P_1} \) into two multiports \( N_{P_1SP_2}, N_{LP_1} \) and the port connection diagram \( G_{P_1P_L} \) with minimum number of ports as in Figure 4. Here \( N_{LP_1} \) contains all the inductors and \( N_{P_1SP_2} \).
Figure 4: Multiport decomposition of \((\text{static} + L)\) multiport into static multiport and inductive multiport.
all the static devices such as resistors, linear controlled sources, input and output ports of \( \mathcal{N} \), the ‘old’ ports \( P_1 \) (which were present in the multiport \( \mathcal{N}_{SP_2} \) during the decomposition of \( \mathcal{N} \) into \( \mathcal{N}_{CP_1}, \mathcal{N}_{SP_2} \) and the port connection diagram \( \mathcal{G}_{P_1P_2} \)), and the new ports \( P_2 \) that arose when \( \mathcal{N}_{SP_2} \) was decomposed into two multiports and a port connection diagram.

Figure 1 shows the (static + L) multiport (d), its multiport decomposition into (e) the static multiport \( \mathcal{N}_{P_1SP_2} \), (f) the port connection diagram \( \mathcal{G}_{P_1P_2L} \), and (g) the inductive multiport \( \mathcal{N}_{LP_1} \).

Let us denote the original GDS \( V_{WWM} \) corresponding to the network \( \mathcal{N} \) by \( V_{WWM}^{v_{PC}i_{PL}v_{PC}i_{PL}M} \) since the latter notation is natural for RLC networks. The set \( M \) contains all the input and output variables. In this case they are \( u_i, u_e, y_i, y_e \).

The emulator for this GDS is \( V_{WWM}^{v_{PC}i_{PL}v_{PC}i_{PL}M} \) which is represented implicitly by the three multiports \( \mathcal{N}_{CP_1}, \mathcal{N}_{P_1SP_2}, \mathcal{N}_{LP_1} \), and the port connection diagrams \( \mathcal{G}_{P_1P_2} \), and \( \mathcal{G}_{P_1P_2L} \).

The original dynamic variables are \( w = (v_{C}, i_{L}) \equiv (v_{C1}, v_{C2}, v_{C3}, v_{C4}, i_{L1}, i_{L2}, i_{L3}) \). These variables are not state variables because of the presence of capacitor loops and inductor cutsets which cause the voltages to form a dependent set and similarly the currents. A proper subset say \( v_{C1}, v_{C2}, v_{C3}, i_{L1}, i_{L2} \) can be taken as the state variables. However, the network has capacitor cutsets and inductor loops which result in zero eigen values. For computational purposes, it is more convenient to work with the dynamic variables \( (v_{PL}, i_{PL}) \) which form a smaller subset than the set of state variables but from which the dynamics of the system can be inferred very easily.

An example, in which we spell out all the spaces which implicitly go to make up the emulator, is given in Appendix E.

One of the uses of implicit linear algebra is to make dynamical system computations using implicit descriptions. However, in the present case, for greater clarity, we describe below how to obtain an explicit description for \( V_{WWM}^{v_{PC}i_{PL}v_{PC}i_{PL}M} \) and show how computations made on it can be easily translated to computations on \( V_{WWM} \).

An explicit description for \( V_{WWM}^{v_{PC}i_{PL}v_{PC}i_{PL}M} \)

**Step 1.** Using the constraints of \( \mathcal{N}_{CP_1} \), obtain the relationship \( i_{PC} = C_{PC}v_{PC} \).

The constraints are

(a). \( (\dot{v}_{C}, \dot{v}_{PC}) \in V^v(\mathcal{G}_{CP_1}) \), where \( \mathcal{G}_{CP_1} \) is the graph of \( \mathcal{N}_{CP_1} \). This is the same as satisfying the Kirchhoff voltage equations of \( \mathcal{G}_{CP_1} \).

(b). \( (i_{C}, i_{PC}) \in V^i(\mathcal{G}_{CP_1}) \). This is the same as satisfying Kirchhoff current equations of \( \mathcal{G}_{CP_1} \).

(c). \( i_{C} = C_{PC}\dot{v}_{C} \). Here \( C \) is symmetric positive definite.

**Step 2.** Using the constraints of \( \mathcal{N}_{LP_1} \), obtain the relationship \( i_{PL} = L_{PL}\dot{i}_{PL} \).

The constraints are

(a). \( (\dot{i}_{L}, \dot{i}_{PL}) \in V^i(\mathcal{G}_{LP_1}) \), where \( \mathcal{G}_{LP_1} \) is the graph of \( \mathcal{N}_{LP_1} \). This is the same as satisfying the Kirchhoff current equations of \( \mathcal{G}_{LP_1} \).

(b). \( (v_{L}, v_{PL}) \in V^v(\mathcal{G}_{LP_1}) \). This is the same as satisfying Kirchhoff voltage equations of \( \mathcal{G}_{LP_1} \).

(c). \( v_{L} = L_{PL}\dot{i}_{L} \). Here \( L \) is symmetric positive definite.
Step 3. Similarly using the constraints of $N_{P_i,S_{P_i}}$, we obtain

$$
\begin{pmatrix}
i_{P_i} \\
v_{P_i}
\end{pmatrix} = 
\begin{bmatrix}
H_{11} & H_{12} \\
H_{21} & H_{22}
\end{bmatrix}
\begin{pmatrix}
v_{P_i} \\
i_{P_i}
\end{pmatrix} + 
\begin{bmatrix}
H_{13} \\
H_{23}
\end{bmatrix} u
$$

(43a)

$$
y = [H_{31} \ H_{32}]
\begin{pmatrix}
v_{P_i} \\
i_{P_i}
\end{pmatrix} + [H_{33}] u.
$$

(43b)

Step 4. Use the topological constraints of $G_{P_C,P_1}$ to transform $i_{P_i}$ to $i_{P_C}$ and $v_{P_i}$ to $v_{P_C}$.

(This is always possible because when the port decomposition has minimum number of ports, the ports cannot contain circuits or cutsets of the port connection diagram (Theorem 5). This means that the graph $G_{P_C,P_1}$ has $P_C, P_1$ as cospanning forests. From this it follows that voltage (current) of $P_C (P_1)$ can be written in terms of voltage (current) of $P_1 (P_C)$.)

Step 5. Similarly use the topological constraints of $G_{P_L,P_2}$ to transform $i_{P_L}$ to $i_{P_L}$ and $v_{P_L}$ to $v_{P_L}$.

(The graph $G_{P_L,P_2}$ has $P_2, P_L$ as cospanning forests.)

Step 6. The transformed version of Equation 43 now involves $i_{P_C}, v_{P_C}$ in place of $i_{P_i}, v_{P_i}$ and $v_{P_L}, i_{P_L}$ in place of $v_{P_L}, i_{P_L}$. 

Step 7. Now substitute $v_{PC} = C_{PC} i_{PC}$, $v_{P_C} = L_{PL} i_{PL}$ in the above transformed equation to get rid of the variables $i_{P_C}, v_{P_L}$ and obtain

$$
\begin{pmatrix}
\dot{i}_{P_C} \\
\dot{i}_{P_L}
\end{pmatrix} = 
\begin{bmatrix}
\dot{H}_{11} & \dot{H}_{12} \\
\dot{H}_{21} & \dot{H}_{22}
\end{bmatrix}
\begin{pmatrix}
v_{P_C} \\
i_{P_L}
\end{pmatrix} + 
\begin{bmatrix}
\dot{H}_{13} \\
\dot{H}_{23}
\end{bmatrix} u
$$

(44a)

$$
y = [\dot{H}_{31} \ \dot{H}_{32}]
\begin{pmatrix}
v_{P_C} \\
i_{P_L}
\end{pmatrix} + [\dot{H}_{33}] u.
$$

(44b)

This final equation only involves $v_{P_C}, \dot{v}_{P_C}, i_{P_L}, \dot{i}_{P_L}$ and $u, y$ variables as required. The solution space of this equation is the dynamical system $V^{v_{P_C},i_{P_L},\dot{v}_{P_C},i_{P_L}}_{W^{l}_{W^M}}$, which it represents.

We now show that $V^{v_{P_C},i_{P_L},\dot{v}_{P_C},i_{P_L}}_{W^{l}_{W^M}}$, captures the essential dynamics of the network and therefore of the dynamical system $V^{v_{PC},i_{PC},\dot{v}_{PC},i_{PC}}_{W^{l}_{W^M}}$, which it represents.

Using the constraints of the capacitive multiport $N_{PC_C}$, we can write $\dot{v}_C = T_C \dot{v}_{PC}$. (This is a network solution problem and here we are treating $(\dot{v}_C, \dot{v}_{PC})$ as the voltage variables and $(i_C, i_{PC})$ as the current variables of $N_{PC_C}$. Now in $G_{PC_C}$, the set of edges $PC$ does not contain loops or cutsets (since the port decomposition is minimal). If the matrix $C$ is symmetric positive definite such a network will have a unique solution for any given $i_{PC}$ or $\dot{v}_{PC}$.)

$$
v_C(t) = v_C(0) + T_C \int_0^t \dot{v}_{PC} \ dt
\begin{align*}
&= v_C(0) + T_C (v_{PC}(t) - v_{PC}(0)).
\end{align*}
$$

Using the constraints of the inductive multiport $N_{PL}$, we can write $\dot{i}_L = T_L \dot{i}_{PL}$. (This is a network solution problem and here we are treating $(\dot{i}_L, \dot{i}_{PL})$ as the current variables and $(v_L, v_{PL})$ as the voltage variables of $N_{PL}$. Now in $G_{PL}$, the set of edges $PL$ does not contain loops or cutsets (since the port decomposition is minimal). If the matrix $L$ is symmetric positive definite such a network will have a unique
solution for any given \( v_{PL} \) or \( i_{PL} \).}

\[
i_L(t) = i_L(0) + T_L \int_0^t i_{PL} \, dt
= i_L(0) + T_L (i_{PL}(t) - i_{PL}(0)).
\]

We thus see that, even though \( v_{PC}, i_{PL} \) are not state variables, their evolution in time along with \( v_C(0), i_L(0) \) fully determines \( v_C(t), i_L(t) \). The notion of emulator is meant to capture this property of \( \mathcal{V}_{v_{PL}, i_{PL} : v_{PL}, i_{PL} : M} \), with respect to \( \mathcal{V}_{W \tilde{W}, M} \equiv \mathcal{V}_{v_C, i_L, \tilde{v}_C, \tilde{i}_L : M} \). Usually in the process of moving from the original system to the emulator we could lose invariant space information about zero eigenvalues of the system (see for instance Theorem 71). In the present case, working with the emulator \( \mathcal{V}_{v_{PL}, i_{PL} : v_{PL}, i_{PL} : M} \) does not give us information about the zero eigenvectors of the original system which has to be independently provided. But the original system \( \mathcal{V}_{v_C, i_L, \tilde{v}_C, \tilde{i}_L : M} \) provides complete information about the emulator, namely, knowing \( v_C, i_L \), we can uniquely obtain \( v_{PC}, i_{PL} \).

10.3. Transitivity and duality for emulators

In order for the notion of emulator to be useful, we need it to have two essential properties

- emulators of emulators should continue to be emulators of the original dynamical system;
- when we dualize \( \mathcal{E} \)-linked dynamical systems, this should result in \( \mathcal{E} \)-linked dynamical systems for which the linkages are dual to the original.

Theorem 68 of Subsection 10.3.1 shows that the first of these properties does indeed hold. The second property is handled by Theorem 70 in the next subsection.

10.3.1. Transitivity

**Theorem 68.** Let \( \{ \mathcal{V}_{W \tilde{W}, P}, \mathcal{V}_{\tilde{W} Q} \} \) be \( \mathcal{E} \)-linked through \( \mathcal{V}_{W P}^1, \mathcal{V}_{W Q}^2 \) and let \( \{ \mathcal{V}_{\tilde{W} \tilde{W} P}, \mathcal{V}_{\tilde{W} \tilde{W} Q} \} \) be \( \mathcal{E} \)-linked through \( \mathcal{V}_{W \tilde{W} P}^{3, 4}, \mathcal{V}_{W \tilde{W} Q}^{5, 6} \). Then \( \{ \mathcal{V}_{\tilde{W} \tilde{W} P}, \mathcal{V}_{\tilde{W} \tilde{W} Q} \} \) is \( \mathcal{E} \)-linked through \( \mathcal{V}_{\tilde{W} P}^{7, 8}, \mathcal{V}_{\tilde{W} Q}^{9} \), where \( \mathcal{V}_{\tilde{W} \tilde{W} P} \equiv (\mathcal{V}_{\tilde{W} P} \leftrightarrow \mathcal{V}_{\tilde{W} Q}), \mathcal{V}_{\tilde{W} \tilde{W} Q} \equiv (\mathcal{V}_{\tilde{W} P} \leftrightarrow \mathcal{V}_{\tilde{W} Q}). \)

**Proof.** By the definition of a linkage we have that

\[
\mathcal{V}_{Q \tilde{Q}} = (\mathcal{V}_{W Q}^1 \oplus \mathcal{V}_{\tilde{W} Q}^2) \leftrightarrow \mathcal{V}_{W \tilde{W}}
= (\mathcal{V}_{W Q}^1 \oplus \mathcal{V}_{\tilde{W} Q}^2) \leftrightarrow (\mathcal{V}_{W P}^1 \oplus \mathcal{V}_{\tilde{W} P}^2) \leftrightarrow \mathcal{V}_{P \tilde{P}}.
\]

By Theorem 7 we then have

\[
\mathcal{V}_{Q \tilde{Q}} = ((\mathcal{V}_{W Q}^1 \leftrightarrow \mathcal{V}_{W P}^1) \oplus (\mathcal{V}_{\tilde{W} Q}^2 \leftrightarrow \mathcal{V}_{\tilde{W} P}^2)) \leftrightarrow \mathcal{V}_{P \tilde{P}}.
\]

By the definition of a linkage we have that

\[
\mathcal{V}_{P \tilde{P}} = (\mathcal{V}_{W P}^1 \oplus \mathcal{V}_{\tilde{W} P}^2) \leftrightarrow \mathcal{V}_{W \tilde{W}}, \quad \mathcal{V}_{W \tilde{W}} = (\mathcal{V}_{W Q}^1 \oplus \mathcal{V}_{\tilde{W} Q}^2) \leftrightarrow \mathcal{V}_{Q \tilde{Q}}.
\]

Therefore, in the above sequence of statements, we could have interchanged the roles of \( \mathcal{V}_{P \tilde{P}}, \mathcal{V}_{Q \tilde{Q}} \) so that we get

\[
\mathcal{V}_{P \tilde{P}} = ((\mathcal{V}_{W Q}^1 \leftrightarrow \mathcal{V}_{W P}^1) \oplus (\mathcal{V}_{\tilde{W} Q}^2 \leftrightarrow \mathcal{V}_{\tilde{W} P}^2)) \leftrightarrow \mathcal{V}_{Q \tilde{Q}}.
\]
10.3.2. Adjoints of emulators

We show in this subsection that adjoints of emulators can be obtained through construction of emulators of adjoints. We introduce the following definition primarily as a typographical simplification.

**Definition 69.** Let \( \{ \mathcal{V}_{WP,M_{m}}, \mathcal{V}_{WP,M_{m}} \} \) be \( \mathcal{E} \)-linked through \( \mathcal{V}_{WP}, \mathcal{V}_{WP} \), and let \( \{ \mathcal{V}_{WP}, \mathcal{V}_{WP} \} \) also be \( \mathcal{E} \)-linked through \( \mathcal{V}_{WP}, \mathcal{V}_{WP} \).

Let

\[
\begin{align*}
\tilde{V}_{WP}^{1} \equiv (\mathcal{V}_{WP})^{a} & = (\mathcal{V}_{WP})_{\mathcal{E}-}\mathcal{E}_{WP}^{a} = (\mathcal{V}_{WP})_{\mathcal{E}-}\mathcal{E}_{WP}^{a}, \\
\tilde{V}_{WP}^{2} \equiv (\mathcal{V}_{WP})^{a} & = (\mathcal{V}_{WP})_{\mathcal{E}-}\mathcal{E}_{WP}^{a} = (\mathcal{V}_{WP})_{\mathcal{E}-}\mathcal{E}_{WP}^{a}, \\
\tilde{V}_{WP,M_{m}} & = (\mathcal{V}_{WP,M_{m}})^{a} = (\mathcal{V}_{WP,M_{m}})^{a}, \\
\tilde{V}_{WP,M_{m}}^{1} & = (\mathcal{V}_{WP,M_{m}})^{a} = (\mathcal{V}_{WP,M_{m}})^{a}, \\
\tilde{V}_{WP,M_{m}}^{2} & = (\mathcal{V}_{WP,M_{m}})^{a} = (\mathcal{V}_{WP,M_{m}})^{a}.
\end{align*}
\]

**Theorem 70.** 1. Let \( \mathcal{V}_{WP,M_{m}} = (\mathcal{V}_{WP} \oplus \mathcal{V}_{WP}) \leftrightarrow \mathcal{V}_{WP,M_{m}} \). Then

\[
\tilde{V}_{WP,M_{m}} = (\mathcal{V}_{WP} \oplus \mathcal{V}_{WP}) \leftrightarrow \mathcal{V}_{WP,M_{m}}.
\]

2. Let \( \mathcal{V}_{WP} = (\mathcal{V}_{WP} \oplus \mathcal{V}_{WP}) \leftrightarrow \mathcal{V}_{WP} \). Then \( \tilde{V}_{WP} = (\mathcal{V}_{WP} \oplus \mathcal{V}_{WP}) \leftrightarrow \mathcal{V}_{WP} \).

**Proof.** 1. We have

\[
\begin{align*}
\tilde{V}_{WP}^{1} & = (\mathcal{V}_{WP})^{a} = (\mathcal{V}_{WP})_{\mathcal{E}-}\mathcal{E}_{WP}^{a}, \\
\tilde{V}_{WP}^{2} & = (\mathcal{V}_{WP})^{a} = (\mathcal{V}_{WP})_{\mathcal{E}-}\mathcal{E}_{WP}^{a}, \\
\tilde{V}_{WP,M_{m}} & = (\mathcal{V}_{WP,M_{m}})^{a} = (\mathcal{V}_{WP,M_{m}})^{a}, \\
\tilde{V}_{WP,M_{m}}^{1} & = (\mathcal{V}_{WP,M_{m}})^{a} = (\mathcal{V}_{WP,M_{m}})^{a}.
\end{align*}
\]

(now on left side of \( \equiv \) we change sign of \( W \) and on right side, sign of \( W' \))

\[
\begin{align*}
\tilde{V}_{WP}^{1} & = (\mathcal{V}_{WP})^{a} \mathcal{E}_{WP}^{a}, \\
\tilde{V}_{WP}^{2} & = (\mathcal{V}_{WP})^{a} \mathcal{E}_{WP}^{a}, \\
\tilde{V}_{WP,M_{m}} & = (\mathcal{V}_{WP,M_{m}})^{a} \mathcal{E}_{WP,M_{m}}^{a}, \\
\tilde{V}_{WP,M_{m}}^{1} & = (\mathcal{V}_{WP,M_{m}})^{a} \mathcal{E}_{WP,M_{m}}^{a}.
\end{align*}
\]

i.e.,

\[
\begin{align*}
\tilde{V}_{WP}^{1} & = (\mathcal{V}_{WP})^{a} \mathcal{E}_{WP}^{a}, \\
\tilde{V}_{WP}^{2} & = (\mathcal{V}_{WP})^{a} \mathcal{E}_{WP}^{a}, \\
\tilde{V}_{WP,M_{m}} & = (\mathcal{V}_{WP,M_{m}})^{a} \mathcal{E}_{WP,M_{m}}^{a}, \\
\tilde{V}_{WP,M_{m}}^{1} & = (\mathcal{V}_{WP,M_{m}})^{a} \mathcal{E}_{WP,M_{m}}^{a}.
\end{align*}
\]

2. The proof is identical to the previous part, but omitting the \( M \) variables.

An example illustrating the construction of adjoint for an RLC network is given in Appendix F.
Lemma 72.

Let building blocks for constructing polynomials.

10.4. Polynomials of \( E^- \) linked spaces

We will now describe, through a series of results, how operations on a GDS \( V_{WP} \) transfer across an \( E^- \) linkage to another GDS \( V_{WP} \), and, similarly, in the case of generalized autonomous systems \( V_{WP} \). In this subsection our primary concern is with polynomials of linked genauts. Our final result of this subsection, Theorem \( 73 \), states that polynomials, without constant terms, of linked spaces continue to be linked. Under extra conditions this is true for even the ones with constant terms. This implies that annihilation of a genaut by a polynomial, holds true across linkages. So eigenvalue, eigenvector computations can be carried out through the most convenient emulators that we decide to choose. The qualification, about not having constant terms, is not a serious impediment. It only means that zero eigenvector computations, which any way are usually topological and therefore very inexpensive, may have to be done directly on the original dynamical system.

The following result describes a form of ‘cancellation’ which makes \( E^- \) linkages behave like similarity transformations. This enables the continued linkage of polynomials of linked spaces.

**Lemma 71.** Let \( V_{AB}, V_{BC} \) be linkages and let linkages \( V^{1}_{BQ}, V^{2}_{BQ} \) satisfy

\[
V^{1}_{BQ} \supseteq V^{2}_{BQ}, \quad V^{2}_{BQ} \circ B \supseteq V_{AB} \circ B, \quad V^{1}_{BQ} \times B \subseteq V_{BC} \times B.
\]

Then

\[
V_{AB} \leftrightarrow V_{BC} = V_{AB} \leftrightarrow V^{2}_{BQ} \leftrightarrow (V^{1}_{BQ})_{B,Q} \leftrightarrow (V_{BC})_{B,C}.
\]

**Proof.** Let \((f_A,h_C) \in V_{AB} \leftrightarrow V_{BC} \). Then there exists \( g_B \) such that

\[
(f_A,g_B) \in V_{AB}, \quad (g_B,h_C) \in V_{BC}.
\]

Since \( V^{2}_{BQ} \circ B \supseteq V_{AB} \circ B \), there exists \( k_Q \) such that \((g_B,k_Q) \in V^{2}_{BQ} \) and since \( V^{1}_{BQ} \supseteq V^{2}_{BQ} \), it follows that \((g_B,k_Q) \in V^{1}_{BQ} \).

Noting that \( B_1 \) is a copy of \( B \), we must have \((g_B,k_Q) \in (V^{1}_{BQ})_{B_1,Q} \). Thus we have

\[
(f_A,g_B) \in V_{AB}, \quad (g_B,k_Q) \in V^{2}_{BQ}, \quad (g_B,k_Q) \in (V^{1}_{BQ})_{B,Q}, \quad (g_B,h_C) \in (V_{BC})_{B,C}
\]

so that

\[
(f_A,h_C) \in V_{AB} \leftrightarrow V^{2}_{BQ} \leftrightarrow (V^{1}_{BQ})_{B,Q} \leftrightarrow (V_{BC})_{B,C}.
\]

Thus \( LHS \subseteq RHS \).

Next let \((f_A,h_C) \in V_{AB} \leftrightarrow V^{2}_{BQ} \leftrightarrow (V^{1}_{BQ})_{B,Q} \leftrightarrow (V_{BC})_{B,C} \). Then there exist

\[
(f_A,g_B) \in V_{AB}, \quad (g_B,k_Q) \in V^{2}_{BQ}, \quad (g_B',k_Q) \in (V^{1}_{BQ})_{B,Q}, \quad (g_B',h_C) \in (V_{BC})_{B,C}.
\]

But this means

\[
(g_B,k_Q), (g_B',k_Q) \in (V^{1}_{BQ})_{B,Q} \quad \text{since} \quad V^{2}_{BQ} \subseteq V^{1}_{BQ}.
\]

Therefore,

\[
(g_B - g_B') \in (V^{1}_{BQ})_{B,Q} \times B_1 \subseteq (V_{BC})_{B,C} \times B_1.
\]

We conclude that \((g_B,h_C) \in (V_{BC})_{B,C} \) and equivalently \((g_B,h_C) \in V_{BC} \). Thus

\[
(f_A,g_B) \in V_{AB}, \quad (g_B,h_C) \in (V_{BC}). \quad \text{So} \quad (f_A,h_C) \in V_{AB} \leftrightarrow V_{BC}.
\]

Thus \( RHS \subseteq LHS \).

The next lemma sets up the machinery to deal with polynomials across linkages by dealing with the building blocks for constructing polynomials.

**Lemma 72.** Let \( \{V_{WP}, V^{2}_{WP}\} \) be \( E^- \) linked through \( V_{WP}, V^{2}_{WP} \). Then
1. $\{\lambda^w(V_{WP}), \lambda^p(V_{PP})\}$ is $\mathcal{E}$-linked through $V_{WP}^1, V_{WP}^2$.
2. $\{(V_{WP})^{(k)}, (V_{PP})^{(k)}\}, k \neq 0$ is $\mathcal{E}$-linked through $V_{WP}^1, V_{WP}^2$.
3. If further,

$$V_{WP} \circ W = (V_{WP} \circ \hat{W}) \circ W = (V_{WP} \circ \hat{W}) \circ W, \quad V_{WP} \circ \hat{P} = (V_{WP} \circ \hat{P}) \circ P, \quad V_{P\hat{P}} \circ P = (V_{P\hat{P}} \circ \hat{P}) \circ P,$$

then we have $\{(V_{WP})^{(0)}, (V_{WP})^{(0)}\} \mathcal{E}$-linked through $V_{WP}^1, V_{WP}^2$.

Proof. 1. When $\lambda = 0$, $\lambda^w(V_{WP}) = V_{WP} \circ W \oplus V_{WP} \times \hat{W}$. From Lemma 65 it follows that

$$\lambda^w(V_{WP}) \leftrightarrow (V_{WP} \oplus V_{WP}^2) = (V_{WP} \circ W \oplus V_{WP} \times \hat{W}) \leftrightarrow (V_{WP} \oplus V_{WP}^2) = V_{WP} \circ P \oplus V_{WP} \times \hat{P} = \lambda^p(V_{PP}).$$

Next let $\lambda \neq 0$ and let $(f_P, \lambda g_P) \in \lambda^w(V_{WP}) \leftrightarrow (V_{WP} \oplus V_{WP}^2).

Then there exist

$$(h_W, \lambda k_P) \in \lambda^w(V_{WP}), \quad (h_W, f_P) \in V_{WP}^1, \quad (\lambda k_P, \lambda g_P) \in V_{WP}^2,$$

so that $(f_P, g_P) \in V_{WP}$. It follows that

$$(f_P, \lambda g_P) \in \lambda^p(V_{PP}), \text{ i.e., } \lambda^w(V_{WP}) \leftrightarrow (V_{WP} \oplus V_{WP}^2) \subseteq \lambda^p(V_{PP}).$$

The same argument, using $V_{WP} \circ W \oplus V_{WP} \times \hat{W}$, proves the reverse containment.

2. We are given that $\{(V_{WP}), (V_{PP})\}$, is $\mathcal{E}$-linked through $V_{WP}^1, V_{WP}^2$.

Suppose $\{(V_{WP})^{(k)}, (V_{PP})^{(k)}\}, 0 < k < r$, is $\mathcal{E}$-linked through $V_{WP}^1, V_{WP}^2$.

We will show that the statement is true also for $k = r$.

By Lemma 65 we have that for any genaut $V_{WP}$,

$$\langle (V_{WP})^{(k)} \circ \hat{W} \subseteq V_{WP} \circ W, \quad (V_{WP})^{(k)} \times W \supseteq V_{WP} \times W. \rangle$$

We therefore have

$$V_{WP} \times W \subseteq V_{WP} \times W \subseteq (V_{WP})^{(k)} \times W \text{ and } V_{WP}^2 \circ \hat{W} \supseteq V_{WP} \circ \hat{W} \supseteq (V_{WP})^{(k)} \circ \hat{W}.$$
3. We need to show that
\[ V_{WP}^1 \leftrightarrow V_{WP}^{(0)} \leftrightarrow V_{WP}^2 = V_{PP}^{(0)} . \]

Since the conditions specified in the hypothesis are symmetric with respect to \( W, P, \) and \( \hat{W}, \hat{P}, \) the same arguments would be valid for showing
\[ V_{WP}^1 \leftrightarrow V_{WP}^{(0)} \leftrightarrow V_{WP}^2 = V_{PP}^{(0)} . \]

We will denote \( V_{WP}^1 \leftrightarrow V_{WP}^{(0)} \leftrightarrow V_{WP}^2 \) by \( T(\gamma_{WP}) \) and \( V_{WP}^1 \leftrightarrow V_{WP}^{(0)} \leftrightarrow V_{WP}^2 \) by \( T'(\gamma_{WP}^{(0)}) . \)

Let \( (h_P, k_P) \in T(\gamma_{WP}^{(0)}) \).

Then there exist \( (f_W, h_W), (f_W, g_W), (g_W, k_W) \) respectively in \( V_{WP}^1, V_{WP}^{(0)}, V_{WP}^2 \).

Since \( V_{WP} \supseteq (V_{WP}^2)_{WP} \), we must have \( (g_W, k_P) \in V_{WP}^1 \).

Hence, \( (f_W - g_W, h_P - k_P) \in V_{WP}^1 \).

Since \( (f_W, g_W) \in V_{WP}^1 \), we must have \( (f_W - g_W, k_W) \in V_{WP}^1 \times \hat{W} = V_{WP}^{(0)} \times \hat{W} \) (part 2 of Lemma 41).

Thus
\[ (h_P - k_P) \in V_{WP}^1 \leftrightarrow (V_{WP}^1 \times \hat{W})_W = V_{WP}^1 \leftrightarrow V_{WP}^1 \times W = V_{PP}^{(0)} = \hat{P} = (V_{PP}^{(0)} \times \hat{P})_P, \]
i.e., \( (h_P - k_P) \in V_{PP}^{(0)} \).

Now \( h_P \in V_{WP}^1 \leftrightarrow V_{WP}^{(0)} \circ W = V_{WP}^1 \circ W \).

Therefore, \( (h_P, h_P - (h_P - k_P)) = (h_P, k_P) \in V_{PP}^{(0)} \).

Thus \( T(\gamma_{WP}^{(0)}) \subseteq V_{PP}^{(0)} \).

Similarly \( T'(\gamma_{WP}^{(0)}) \subseteq V_{WP}^{(0)} \).

By the definition of \( T(\cdot) \), it is clear that it is an increasing function, i.e., \( T(V) \subseteq T(V'), V \subseteq V' \).

This is also true of \( T'(\cdot) \).

Using the definition of \( E- \) linkage, the hypothesis of this part of the lemma, the properties of \( V_{WP}^{(0)} \) listed in Lemma 41 and Theorem 2, it is clear that \( T'(T(\gamma_{WP}^{(0)})) = \gamma_{WP}^{(0)} \) and \( T(T'(\gamma_{WP}^{(0)})) = \gamma_{WP}^{(0)} \).

Therefore \( V_{WP}^{(0)} \supseteq T(\gamma_{WP}^{(0)}) \supseteq TT'(\gamma_{WP}^{(0)}) = \gamma_{WP}^{(0)} \).

It follows that \( T(\gamma_{WP}^{(0)}) = \gamma_{WP}^{(0)} \) and \( T'(\gamma_{WP}^{(0)}) = \gamma_{WP}^{(0)} \).

The next lemma continues the task begun by the previous lemma for dealing with polynomials by showing \( + \) becomes \( + \) across a linkage. It also contains similar results for \( + \) and \( \cap \) operations. These latter are useful while dealing with invariance across a linkage.

**Lemma 73.**

1. Let \( \{ \hat{V}_{WP}^1, \hat{V}_{WP}^2 \} \), \( \{ \hat{V}_{WP}^1, \hat{V}_{WP}^2 \} \) be both \( E- \) linked through \( \{ V_{WP}^1, V_{WP}^2 \} \).

Then so is \( \{ \hat{V}_{WP}^1 + \hat{V}_{WP}^2, \hat{V}_{WP}^1 + \hat{V}_{WP}^2 \} \) \( E- \) linked through \( \{ V_{WP}^1, V_{WP}^2 \} \).

2. Let \( \{ V_{WP}^1, V_{WP}^2 \} \), \( \{ V_{WP}^1, V_{WP}^2 \} \) be \( E- \) linked through \( \{ V_{WP}^1, V_{WP}^2 \} \).

Then so is \( \{ V_{WP}^1 + V_{WP}^2, V_{WP}^1 + V_{WP}^2 \} \) \( E- \) linked through \( \{ V_{WP}^1, V_{WP}^2 \} \).

3. Let \( \{ V_{WP}^1, V_{WP}^2 \} \), \( \{ V_{WP}^1, V_{WP}^2 \} \) be \( E- \) linked through \( \{ V_{WP}^1, V_{WP}^2 \} \).

Then so is \( \{ V_{WP}^1 \cap V_{WP}^2, V_{WP}^1 \cap V_{WP}^2 \} \) \( E- \) linked through \( \{ V_{WP}^1, V_{WP}^2 \} \).
Proof. 1. The result follows by using the distributivity of ‘\(\leftrightarrow\)’ over the intersection-sum operation for appropriate conditions (Theorem 22). We have

\[
\begin{align*}
\nu_{WP}^1 \leftrightarrow (\hat{\nu}_{WP}^1 + \hat{\nu}_{WP}^1) & \leftrightarrow \nu_{WP}^2 \\
= ((\nu_{WP}^1 \leftrightarrow \hat{\nu}_{WP}^1) + \hat{\nu}_{WP}^1) & \leftrightarrow \nu_{WP}^2
\end{align*}
\]

(since \(\nu_{WP}^1 \times W \subseteq \hat{\nu}_{WP}^1 \times W\), \(\nu_{WP}^1 \times W \subseteq \hat{\nu}_{WP}^1 \times W\))

\[
= (\nu_{WP}^1 \leftrightarrow \hat{\nu}_{WP}^1) + \hat{\nu}_{WP}^1 (\nu_{WP}^1 \leftrightarrow \nu_{WP}^2)
\]

(since \((\nu_{WP}^1 \leftrightarrow \hat{\nu}_{WP}^1) \circ \hat{W} \subseteq \hat{\nu}_{WP}^1 \circ \hat{W} \subseteq \nu_{WP}^2 \circ \hat{W}\), \((\nu_{WP}^1 \leftrightarrow \hat{\nu}_{WP}^1) \circ \hat{W} \subseteq \hat{\nu}_{WP}^1 \circ \hat{W} \subseteq \nu_{WP}^2 \circ \hat{W}\))

\[
= \hat{\nu}_{WP}^1 + \hat{\nu}_{WP}^1.
\]

The same argument, because of the properties of \(\mathcal{E}\)–linkage being symmetric with respect to \(W, P\) and \(\hat{W}, \hat{P}\), works for showing

\[
\nu_{WP}^1 \leftrightarrow (\hat{\nu}_{WP}^1 + \hat{\nu}_{WP}^1) \leftrightarrow \nu_{WP}^2 = \hat{\nu}_{WP}^1 + \hat{\nu}_{WP}^1.
\]

2. It is easily seen that

\[
\nu_{WP}^1 \leftrightarrow (\nu_{WP}^1 + \nu_{WP}^1) \leftrightarrow \nu_{WP}^2 \supseteq (\nu_{WP}^1 \leftrightarrow \nu_{WP}^1) + (\nu_{WP}^1 \leftrightarrow \nu_{WP}^1) \supseteq \nu_{WP}^1 + \nu_{WP}^1,
\]

and similarly

\[
\nu_{WP}^1 \leftrightarrow (\nu_{WP}^1 + \nu_{WP}^1) \leftrightarrow \nu_{WP}^2 \supseteq \nu_{WP}^1 + \nu_{WP}^1.
\]

Further,

\[
\begin{align*}
\nu_{WP}^1 \circ W & \supseteq \nu_{WP}^1 \circ W + \nu_{WP}^1 \circ W = (\nu_{WP}^1 \circ \nu_{WP}^1) \circ W, \\
\nu_{WP}^1 \times W & \supseteq \nu_{WP}^1 \times W + \nu_{WP}^1 \times W \supseteq (\nu_{WP}^1 \circ \nu_{WP}^1) \times W, \\
\nu_{WP}^2 \circ \hat{W} & \supseteq \nu_{WP}^2 \circ \hat{W} + \nu_{WP}^2 \circ \hat{W} = (\nu_{WP}^2 \circ \nu_{WP}^2) \circ \hat{W}, \\
\nu_{WP}^2 \times \hat{W} & \supseteq \nu_{WP}^2 \times \hat{W} + \nu_{WP}^2 \times \hat{W} \supseteq (\nu_{WP}^2 \circ \nu_{WP}^2) \times \hat{W}.
\end{align*}
\]

A similar set of conditions is clear in terms of the \(P, \hat{P}\) variables.

Thus the dot-cross \(\mathcal{E}\)–linkage conditions are satisfied for \((\nu_{WP}^1 \circ \nu_{WP}^1), (\nu_{WP}^1 \circ \nu_{WP}^1)\).

Let us now denote \(\nu_{WP}^1 \leftrightarrow (\nu_{WP}^1 \circ \nu_{WP}^1) \leftrightarrow \nu_{WP}^2 \) by \(T(\nu_{WP}^1 \circ \nu_{WP}^1)\) and \(\nu_{WP}^1 \leftrightarrow (\nu_{WP}^1 \circ \nu_{WP}^1) \leftrightarrow \nu_{WP}^2 \) by \(T(\nu_{WP}^1 \circ \nu_{WP}^1)\).

Using Theorem 22, we have

\[
T^T(\nu_{WP}^1 \circ \nu_{WP}^1) = \nu_{WP}^1 \circ \nu_{WP}^1, \quad T^T(\nu_{WP}^1 \circ \nu_{WP}^1) = \nu_{WP}^1 \circ \nu_{WP}^1.
\]

It is clear that \(T(\cdot), T^T(\cdot)\) are increasing functions. Therefore we have

\[
\begin{align*}
\nu_{WP}^1 + \nu_{WP}^1 & \supseteq \nu_{WP}^1 + \nu_{WP}^1 \supseteq \nu_{WP}^1 + \nu_{WP}^1, \\
\nu_{WP}^1 + \nu_{WP}^1 & \supseteq \nu_{WP}^1 + \nu_{WP}^1 \supseteq \nu_{WP}^1 + \nu_{WP}^1.
\end{align*}
\]

We conclude,

\[
T(\nu_{WP}^1 \circ \nu_{WP}^1) = \nu_{WP}^1 \circ \nu_{WP}^1, \quad T(\nu_{WP}^1 \circ \nu_{WP}^1) = \nu_{WP}^1 \circ \nu_{WP}^1.
\]

Therefore, \((\nu_{WP}^1 \circ \nu_{WP}^1), (\nu_{WP}^1 \circ \nu_{WP}^1)\) is \(\mathcal{E}\)–linked through \(\nu_{WP}^1, \nu_{WP}^2\).
3. This result is dual to the previous part of the present lemma. 

Remark 14. In Lemma 72, the conditions about $\mathcal{E}$– linking $(\mathcal{V}_{W}^{(0)},\mathcal{V}_{P}^{(0)})$ that are stated imply that polynomials of $\mathcal{E}$– linked genops may not necessarily be also so linked unless the constant term is zero. In particular if a polynomial with constant term ‘annihilates’ a genop, it may not necessarily annihilate another that is $\mathcal{E}$– linked to it unless the genauts satisfy special properties. We will illustrate these ideas through an example later (see Example Appendix B and Remark 16 at the end of it).

From Lemma 53 Lemma 72 and the first part of Lemma 73 we obtain immediately,

**Theorem 74.** Let $p(s)$ be a polynomial with no constant term. Let $\mathcal{V}_{W},\mathcal{V}_{P}$ be genops such that $\{\mathcal{V}_{W},\mathcal{V}_{P}\}$ is $\mathcal{E}$– linked through $\mathcal{V}_{WP},\mathcal{V}_{WP}$.

Then so is $(p(\mathcal{V}_{W},p(\mathcal{V}_{P}))$ $\mathcal{E}$– linked through $\mathcal{V}_{WP},\mathcal{V}_{WP}$. If one of $p(\mathcal{V}_{W},p(\mathcal{V}_{P}))$ is decoupled so would the other be.

If however, $\mathcal{V}_{WP} \cap W = (\mathcal{V}_{WP} \cap \hat{W})_{WP}$, $\mathcal{V}_{WP} \times W = (\mathcal{V}_{WP} \times \hat{W})_{WP}$, $\mathcal{V}_{WP} \cap P = (\mathcal{V}_{WP} \cap \hat{P})_{WP}$, $\mathcal{V}_{WP} \times P = (\mathcal{V}_{WP} \times \hat{P})_{WP}$, then since $(\mathcal{V}_{WP}^{(0)},\mathcal{V}_{WP}^{(0)})$ is $\mathcal{E}$– linked through $\mathcal{V}_{WP}^{(1)},\mathcal{V}_{WP}^{(1)}$, $(p(\mathcal{V}_{W},p(\mathcal{V}_{P}))$ is $\mathcal{E}$– linked through $\mathcal{V}_{WP}^{(1)},\mathcal{V}_{WP}^{(1)}$, even if $p(s)$ has a constant term. If one of $p(\mathcal{V}_{W},p(\mathcal{V}_{P}))$ is decoupled so would the other be.

10.5. Invariance across $\mathcal{E}$– linking

In this subsection, our concern is with showing that controlled and conditioned invariant spaces of a genaut transfer in a natural manner to the corresponding spaces in a linked genaut.

**Theorem 75.** Let $\{\mathcal{V}_{W},\mathcal{V}_{WP}\}$ be $\mathcal{E}$– linked through $\mathcal{V}_{WP},\mathcal{V}_{WP}$.

1. Let $\mathcal{V}_{W}$ be controlled invariant in $\mathcal{V}_{WP}$. Then $\mathcal{V}_{WP} \leftrightarrow \mathcal{V}_{W}$, $(\mathcal{V}_{WP},\mathcal{V}_{WP}) \leftrightarrow \mathcal{V}_{W}$ are controlled invariant in $\mathcal{V}_{WP}$.

2. Let $\mathcal{V}_{W}$ be conditioned invariant in $\mathcal{V}_{WP}$. Then $\mathcal{V}_{WP} \leftrightarrow \mathcal{V}_{W}$, $(\mathcal{V}_{WP},\mathcal{V}_{WP}) \leftrightarrow \mathcal{V}_{W}$ are conditioned invariant in $\mathcal{V}_{WP}$.

3. Let $\mathcal{V}_{W}$ be invariant in $\mathcal{V}_{WP}$. Then $\mathcal{V}_{WP} \leftrightarrow \mathcal{V}_{W}$, $(\mathcal{V}_{WP},\mathcal{V}_{WP}) \leftrightarrow \mathcal{V}_{W}$ are invariant in $\mathcal{V}_{WP}$.

Proof. 1. We are given that $\mathcal{V}_{WP} \leftrightarrow \mathcal{V}_{W} \supseteq \mathcal{V}_{W}$. We will first show that

$$((\mathcal{V}_{WP}^{1} \oplus \mathcal{V}_{WP}^{2}) \leftrightarrow \mathcal{V}_{WP} \leftrightarrow \mathcal{V}_{W} \leftrightarrow (\mathcal{V}_{WP} \leftrightarrow \mathcal{V}_{W}) \mathcal{V}_{WP} \mathcal{V}_{WP} \mathcal{V}_{WP} \mathcal{V}_{WP}) \mathcal{V}_{WP} \mathcal{V}_{WP}.$$ 

(45)

The LHS of equation 45 can be rewritten as

$$((\mathcal{V}_{WP}^{1} \leftrightarrow \mathcal{V}_{WP}^{2}) \leftrightarrow \mathcal{V}_{WP} \leftrightarrow \mathcal{V}_{W} \leftrightarrow (\mathcal{V}_{WP}^{1} \leftrightarrow \mathcal{V}_{W} ),$$

where $\mathcal{V}_{WP}^{1} \equiv \mathcal{V}_{WP}^{1} \mathcal{V}_{WP}^{1} \mathcal{V}_{WP}^{1} \mathcal{V}_{WP}^{1}$ and $\mathcal{V}_{W} \equiv \mathcal{V}_{W} \mathcal{V}_{W} \mathcal{V}_{W} \mathcal{V}_{W}$ and we note that $\mathcal{V}_{WP}^{1} \oplus \mathcal{V}_{WP}^{2}$ can be written also as $\mathcal{V}_{WP}^{1} \mathcal{V}_{WP}^{1} \mathcal{V}_{WP}^{1} \mathcal{V}_{WP}^{1}$.

We will rewrite the term $(\mathcal{V}_{WP}^{1} \leftrightarrow \mathcal{V}_{W})$ as $(\mathcal{V}_{WP}^{1} \leftrightarrow \mathcal{V}_{W})$, where $\mathcal{V}_{WP}^{1} \equiv (\mathcal{V}_{WP}^{1} \leftrightarrow \mathcal{V}_{WP}^{1}) \mathcal{V}_{WP}^{1}$ and $\mathcal{V}_{W} \equiv (\mathcal{V}_{W} \rightarrow \mathcal{V}_{W})$.

The LHS of equation 45 now appears as

$$((\mathcal{V}_{WP}^{1} \leftrightarrow \mathcal{V}_{WP}^{2}) \leftrightarrow \mathcal{V}_{WP} \leftrightarrow (\mathcal{V}_{WP} \leftrightarrow \mathcal{V}_{W} \mathcal{V}_{WP} \mathcal{V}_{WP} \mathcal{V}_{WP} \mathcal{V}_{WP}).$$

75
Lemma 76. Let $V_{WP} \supseteq V_{W_P}$.

1. Suppose $V_{WP} \circ W = V_{W_P} \circ W$, $V_P \supseteq V_{WP} \times P$. Then, $V_{WP} \leftrightarrow V_P = V_{W_P} \leftrightarrow V_P$.

Hence, $(V_{WP} \leftrightarrow V_P)_{WP} = (V_{W_P} \leftrightarrow V_P)_{WP}$.

2. Suppose $V_{WP} \times W = V_{W_P} \times W$, $V_P \subseteq V_{WP} \circ W$. Then, $V_{WP} \leftrightarrow V_P = V_{W_P} \leftrightarrow V_P$.

Hence, $(V_{WP} \leftrightarrow V_P)_{WP} = (V_{W_P} \leftrightarrow V_P)_{WP}$. 

Observe that in this expression no index set appears more than twice. Therefore, by Theorem 7, the expression can have only a unique meaning even without brackets and we can rearrange the terms according to convenience. We now rearrange terms and write the expression as

$$(V_{WP}^1 \leftrightarrow V_{W_P}^2) \leftrightarrow V_{W_P}^1 \leftrightarrow V_{WP}^2).$$

We observe that $(V_{WP}^2 \leftrightarrow V_{W_P}^2) \leftrightarrow V_{W_P} = (V_{W_P}^1 \leftrightarrow V_{W_P}^1)$ by Theorem 11 and further that $V_{WP}^1 \supseteq V_{W_P}^2$. Hence

$$(V_{WP}^1 \leftrightarrow V_{W_P}^2) \leftrightarrow V_{W_P} \supseteq (V_{W_P}^1 \leftrightarrow V_{W_P}^1) \leftrightarrow V_{WP}^1 \supseteq V_W \leftrightarrow V_{WP}^2).$$

This proves the required result.

We will next show that

$$(V_{WP}^1 \leftrightarrow V_{W_P}^2) \leftrightarrow V_{W_P} \supseteq (V_{W_P}^2 \leftrightarrow V_{W_P}^1) \supseteq (V_{WP}^2 \leftrightarrow V_W),$$

(46)

where $V_{WP}^2 \equiv (V_{W_P}^2)_{WP}$.

The LHS of equation (46) can be rewritten as

$$(V_{WP}^1 \leftrightarrow V_{W_P}^2) \leftrightarrow V_{W_P} \supseteq (V_{W_P}^2 \leftrightarrow V_{W_P}^1) \supseteq (V_{WP}^2 \leftrightarrow V_W).$$

As before this expression can be rewritten as

$$(V_{WP}^1 \leftrightarrow V_{W_P}^2) \leftrightarrow V_{W_P} \supseteq (V_{W_P}^2 \leftrightarrow V_{W_P}^1).$$

Rearranging terms (Theorem 7), this reduces to

$$(V_{WP}^1 \leftrightarrow V_{W_P}^2) \leftrightarrow V_{W_P} \supseteq (V_{W_P}^2 \leftrightarrow V_{WP}^1).$$

This simplifies, using Theorem 11 to

$$V_{W_P} \supseteq V_{W_P} \supseteq V_{WP}^1 \supseteq V_{WP}^2.$$

We note that $V_{WP} \supseteq (V_{W_P}^2)_{WP}$. Hence

$$(V_{WP}^1 \leftrightarrow V_{W_P}^2) \leftrightarrow V_{W_P} \supseteq (V_{W_P}^1 \leftrightarrow V_{WP}^1) \supseteq (V_{WP}^1 \leftrightarrow V_{WP}^2) \supseteq V_W \leftrightarrow V_{WP}^2.$$

This proves the required result.

2. This is dual to the previous part.

3. Follows from the preceding parts of the lemma.

The following lemma is used in the proof of Theorem 77.

Lemma 77. Let $V_{WP}^1 \supseteq V_{W_P}^2$.

1. Suppose $V_{WP} \circ W = V_{WP} \circ W$, $V_P \supseteq V_{WP} \times P$. Then, $V_{WP} \leftrightarrow V_P = V_{W_P} \leftrightarrow V_P$.

Hence, $(V_{WP} \leftrightarrow V_P)_{WP} = (V_{W_P} \leftrightarrow V_P)_{WP}$.

2. Suppose $V_{WP} \times W = V_{WP} \times W$, $V_P \subseteq V_{WP} \circ W$. Then, $V_{WP} \leftrightarrow V_P = V_{W_P} \leftrightarrow V_P$.

Hence, $(V_{WP} \leftrightarrow V_P)_{WP} = (V_{W_P} \leftrightarrow V_P)_{WP}$. 

76
Proof. 1. It is clear that $V_{WP}^1 \leftrightarrow V_P \supseteq V_{WP}^2 \leftrightarrow V_p$. Let $g_w \in V_{WP}^1 \leftrightarrow V_p$.

Then there exist $(f_p, g_w) \in V_{WP}^1, f_p \in V_p$.

Since $V_{WP}^1 \circ W = V_{WP}^1 \circ W$, there exists $(f_p', g_w) \in V_{WP}^2 \subseteq V_{WP}^1$.

But then $(f_p - f_p') \in V_{WP}^1 \times P \subseteq V_p$, so that $f_p' \in V_p$.

Thus $(f_p, g_w) \in V_{WP}^2, f_p' \in V_p$, so that $g_w \in V_{WP}^2 \leftrightarrow V_p$.

2. Dual to the previous result.

In Theorem 58, we had shown the analogue of controllable and uncontrollable spaces in the context of USGs and in Theorem 59, the dual notions of the unobservable and observable spaces in the context of LSGs. In the former case, starting with a USG $V_{W\hat{W}}^u$, a genop contained in it and a space $V_p$ invariant in it, we had shown that if $p_l(s)$ annihilates the ‘uncontrollable’ space $V_{WP}^u + (V_p)_{\hat{W}},$ and $p_2(s)$, the ‘controllable’ space $V_{W\hat{W}} \cap V$, then $p_1p_2(s)$ annihilates $V_{W\hat{W}}$. A dual statement was proved for an LSG. The primal part of the following result states, essentially, that linked versions of the uncontrollable and controllable spaces can be computed in the emulator, and the result transferred to the original across $E-$ linkage. It also contains the dual statement about observable and unobservable spaces.

Theorem 77. Let $\{V_{W\hat{W}}, V_{WP}^1\}$ be $E-$ linked through $V_{WP}^1, V_{WP}^2, \ldots$.

1. Let $V_p$ be invariant in $V_{WP}^1$ with $(V_p)_{\hat{W}} \subseteq V_{WP}^1 \circ \hat{P},$ let $(V_{WP}^1 \times W)_{\hat{W}} = V_{WP}^2 \times \hat{W}$ and let $V_w \equiv (V_{WP}^2 \times WP) \leftrightarrow V_p$.

Then

(a) $V_w = V_{WP}^1 \leftrightarrow V_p$ and $V_w$ is invariant in $V_{WP}^1 \circ W$ with $V_{WP}^1 \circ W \supseteq (V_p)_{\hat{W}}$.

(b) $\{V_{WP}^1 \oplus (\nu_w \oplus (V_p)_{\hat{W}}), V_{WP}^2 \oplus (V_p \oplus (V_p)_{\hat{W}})\}$ is also $E-$ linked through $V_{WP}^1, V_{WP}^2, \ldots$.

2. Let $V_p$ be invariant in $V_{WP}^1$ with $V_p \supseteq V_{WP}^1 \circ P$, and let $(V_{WP}^1 \times W)_{\hat{W}} = V_{WP}^2 \circ \hat{W}$.

Let $V_{WP}^1 \equiv (V_{WP}^1 \times WP) \leftrightarrow V_p$.

Then

(a) $(V_w)_{\hat{W}} = V_{WP}^2 \circ \hat{P}$ and $V_{WP}^1 \circ W \subseteq V_w$.

(b) $\{V_{WP}^1 \cap (V_w \oplus (V_p)_{\hat{W}}), V_{WP}^2 \cap (V_p \oplus (V_p)_{\hat{W}})\}$ is also $E-$ linked through $V_{WP}^1, V_{WP}^2, \ldots$.

Proof. 1. (a) We have, by the property of $E-$ linkages (Theorem 63) and the hypothesis,

$$V_{WP}^2 \circ \hat{P} \supseteq (V_p)_{\hat{W}} \circ \hat{P} \supseteq (V_p)_{\hat{W}}.$$  

Further, $(V_{WP}^1 \times W)_{\hat{W}} = V_{WP}^2 \times \hat{W}$. So by part 2 of Lemma 76,

$$V_{WP}^1 \leftrightarrow V_p = (V_{WP}^2 \circ \hat{P} \equiv (V_p)_{\hat{W}})_{\hat{W}} = V_w.$$  

By Theorem 75, it follows that $V_w$ is invariant in $V_{WP}^1$. 

Next, since $\{V_{WP}^1, V_{WP}^2\}$ is an $E-$ linkage for $\{V_{WP}^1, V_{WP}^2\}$, by Lemma 63

$$V_{WP}^1 \circ W = V_{WP}^2 \circ \hat{P} \equiv (V_p \circ \hat{P}) \supseteq V_{WP}^2 \circ (V_p)_{\hat{W}} = (V_p)_{\hat{W}}.$$  

77
(b) By the previous subpart of the theorem, it is clear that
\[ \{ V_W \bigoplus (V_W)_\hat{\alpha}, V_P \bigoplus (V_P)_\hat{\beta} \} \]
is $\mathcal{E}$ - linked through $V_{W_P}^1, V_{W_P}^2$.
Since $\{ V_{W_\hat{\alpha}}, V_{P_\hat{\beta}} \}$ is also $\mathcal{E}$ - linked through $V_{W_P}^1, V_{W_P}^2$, by Lemma 72 it follows that
\[ \{ V_{W_\hat{\alpha}} + (V_W \bigoplus (V_W)_\hat{\alpha}), V_{P_\hat{\beta}} + (V_P \bigoplus (V_P)_\hat{\beta}) \} \]
is $\mathcal{E}$ - linked through $V_{W_P}^1, V_{W_P}^2$.

2. This is dual to the previous result.

Remark 15. Note that, if $V_{W_\hat{\alpha}} \times W = 0_W$ and $V_{P_\hat{\beta}} \times P = 0_P$, equivalently, if the system and the emulator have no zero eigenvalue, then there is a one to one correspondence between invariant spaces of $V_{W_\hat{\alpha}}$ and $V_{P_\hat{\beta}}$.

Even when $V_{W_\hat{\alpha}} \times W \neq 0_W$, a convenient emulator with $V_{P_\hat{\beta}} \times P = 0_P$ can usually be built. See for instance Example Appendix E.

Now define
\[ V_{W_\hat{\alpha}}' \equiv ((V_{W_P}^2 \oplus V_{W_P}^2)_P \oplus V_{W_\hat{\alpha}}) \leftrightarrow V_{P_\hat{\beta}}. \]

Theorem 77 indicates that invariant spaces can be computed in $V_{P_\hat{\beta}}'$ and transformed through $(V_{W_P}^2 \oplus V_{W_P}^2)_P$ to invariant subspaces of $V_{W_\hat{\alpha}}'$. If to each of these spaces, we add invariant subspaces of $V_{W_\hat{\alpha}} \times W$ we will account for all invariant subspaces of $V_{W_\hat{\alpha}}'$.

10.6. State feedback and output injection through $\mathcal{E}$ - linkages

In this subsection we show that we can perform $wm_u - feedback/m_p\hat{w} - injection$ using $V_{W_{M_u}}$/$V_{W_{M_u}}'$ on a GDS $V_{W_{M_u}}$, by first moving to an emulator $V_{P_\hat{\beta}M_u}$ through the $\mathcal{E}$ - linkage $(V_{W_P}^1 \oplus V_{W_P}^2)$, performing the operation using $(V_{W_{M_u}} \leftrightarrow V_{W_P})/(V_{W_{M_u}} \leftrightarrow V_{W_P})'$ on it, obtaining $V_{P_\hat{\beta}}$ and then returning to $V_{W_\hat{\alpha}}'$ through $(V_{W_P} \oplus V_{W_P})'$.

The following theorem essentially formalizes the above informal statement on $wm_u - feedback$.

Theorem 78. Let
\[ (V_{W_P}^1 \oplus V_{W_P}^2) \leftrightarrow V_{W_{P_M_u}} = V_{P_\hat{\beta}M_u} \] and let $V_{W_P}^1 \times W \subseteq V_{W_{P_M_u}} \circ W_{M_u} \times W$.

Let $V_{W_{M_u}}$ be a space on $W \oplus M_u$, $V_{P_{M_u}} \equiv V_{W_{M_u}} \leftrightarrow V_{W_P}$. Let $V_{W_\hat{\alpha}} \equiv (V_{W_{\hat{\alpha}M_u}} \cap V_{W_{M_u}}) \circ W_{\hat{\alpha}}$ and let $V_{P_\hat{\beta}} \equiv (V_{P_\hat{\beta}M_u} \cap V_{P_{M_u}}) \circ P_\hat{\beta}$. Then
\[ (V_{W_P}^1 \oplus V_{W_P}^2) \leftrightarrow V_{W_\hat{\alpha}} = V_{P_\hat{\beta}}'. \]

We need the following lemmas to prove this theorem.

Lemma 79. Let $V_{W_{\hat{\alpha}M_u}} \equiv V_{W_{\hat{\alpha}M_u}} \circ W_{\hat{\alpha}}M_u$. Let $V_{W_P}^1 \times W \subseteq V_{W_{\hat{\alpha}M_u}} \times W$. Then,
\[ V_{W_P}^1 \leftrightarrow (V_{W_{\hat{\alpha}M_u}} \cap V_{W_{M_u}}) = (V_{W_P}^1 \leftrightarrow V_{W_{\hat{\alpha}M_u}}) \cap (V_{W_P} \leftrightarrow V_{W_{M_u}}). \]
Proof. It is easy to see that

\[ V_{WP}^1 \leftrightarrow (V_{W\dot{W}M_u} \cap V_{WM_u}) \subseteq (V_{WP}^1 \leftrightarrow V_{W\dot{W}M_u}) \bigcap (V_{WP}^1 \leftrightarrow V_{WM_u}). \]

Let \((f_P, g_{\bar{W}}, f_{M_u}) \in \text{R.H.S.}\) Then there exist \((f_W, f_P), (f_{\bar{W}}, f_P) \in V_{WP}^1\) such that \((f_W, g_{\bar{W}}, f_{M_u}) \in V_{W\dot{W}M_u}\) and \((f_{\bar{W}}, f_{M_u}) \in V_{WM_u}\).

But this means

\[ f_W - f_W' \in V_{WP}^1 \times W \subseteq V_{W\dot{W}M_u} \times W \]

It follows that \((f_W - f_W', 0_{\bar{W}}, 0_{M_u}) \in V_{W\dot{W}M_u}\)

so that \((f_W', g_{\bar{W}}, f_{M_u})\) belongs to \(V_{W\dot{W}M_u}\) and therefore also belongs to \((V_{W\dot{W}M_u} \cap V_{WM_u})\).

Since \((f_W', f_P) \in V_{WP}^1\), it follows that

\[ (f_P, g_{\bar{W}}, f_{M_u}) \in V_{WP}^1 \leftrightarrow (V_{W\dot{W}M_u} \cap V_{WM_u}). \]

\[ \square \]

The following lemma is routine and the proof is omitted.

**Lemma 80.** Let \(V_{\dot{W}M_u} \equiv V_{WP}^1 \leftrightarrow V_{W\dot{W}M_u}\) and let \(V_{PM_u} \equiv V_{WP}^1 \leftrightarrow V_{WM_u}\). Then

\[ V_{\dot{W}P}^2 \leftrightarrow (V_{\dot{W}M_u} \cap V_{PM_u}) = (V_{\dot{W}P}^2 \leftrightarrow V_{\dot{W}M_u}) \bigcap (V_{WP}^1 \leftrightarrow V_{PM_u}). \]

**Proof.** (of Theorem 78).

From Lemmas 79 and 80 we have that

\[
(V_{\dot{W}P}^1 \oplus V_{\dot{W}P}^2) \leftrightarrow (V_{W\dot{W}M_u} \cap V_{WM_u}) \\
= V_{\dot{W}P}^2 \leftrightarrow ((V_{WP}^1 \leftrightarrow V_{W\dot{W}M_u}) \bigcap (V_{WP}^1 \leftrightarrow V_{WM_u})) \\
= ((V_{WP}^1 \oplus V_{\dot{W}P}^2) \leftrightarrow V_{W\dot{W}M_u}) \bigcap (V_{WP}^1 \leftrightarrow V_{WM_u}).
\]

It follows that

\[
[(V_{\dot{W}P}^1 \oplus V_{\dot{W}P}^2) \leftrightarrow (V_{W\dot{W}M_u} \cap V_{WM_u})] \leftrightarrow F_{M_u} = [(V_{WP}^1 \oplus V_{\dot{W}P}^2) \leftrightarrow V_{W\dot{W}M_u}] \bigcap (V_{WP}^1 \leftrightarrow V_{WM_u}) \leftrightarrow F_{M_u}.
\]

By Theorem 7 the L.H.S can be rewritten as

\[
(V_{\dot{W}P}^1 \oplus V_{\dot{W}P}^2) \leftrightarrow [(V_{W\dot{W}M_u} \cap V_{WM_u}) \leftrightarrow F_{M_u}] = (V_{\dot{W}P} \oplus V_{\dot{W}P}^2) \leftrightarrow [(V_{W\dot{W}M_u} \cap V_{WM_u}) \leftrightarrow F_{M_u}] \\
\]

and is therefore equal to \((V_{\dot{W}P} \oplus V_{\dot{W}P}^2) \leftrightarrow V_{W\dot{W}}\) and the R.H.S is

\[
(V_{\dot{W}P} \cap V_{PM_u}) \circ P_{\dot{W}} = (V_{\dot{W}P} \cap V_{PM_u}) \circ P_{\dot{W}} = V_{\dot{W}P}.
\]

The theorem follows. \(\square\)

The following result is a formalization of the statement about performing \(m\dot{w}\) injection through an emulator, at the beginning of this subsection. It is the dual of Theorem 78.

**Theorem 81.** Let

\[
(V_{WP}^1 \oplus V_{\dot{W}P}^2) \leftrightarrow V_{W\dot{W}M_{M_y}} = V_{\dot{W}P} \cap V_{PM_u}, \quad \text{and let} \quad V_{\dot{W}P} \circ \dot{W} \supseteq V_{W\dot{W}M_{M_y}} \times W\dot{W} \cap V_{WM_u}.
\]

Let \(V_{\dot{W}M_y}\) be a space on \(\dot{W} \cup M_y\), \(V_{\dot{W}M_y} \equiv V_{WP}^2 \leftrightarrow V_{\dot{W}P}^2\). Let \(V_{W\dot{W}} \equiv (V_{W\dot{W}M_y} \times W\dot{W}) \text{ and let } V_{\dot{W}P} = (V_{\dot{W}P} \cap V_{PM_u}) \times P_{\dot{W}}\). Then

\[
(V_{WP}^1 \oplus V_{\dot{W}P}^2) \leftrightarrow V_{W\dot{W}} = V_{\dot{W}P}.
\]
Proof. We will merely show that if \{V, W, P, M, \ldots\} satisfies Theorem 78, the adjoint pair \{\tilde{V}, \tilde{W}, \tilde{P}, \tilde{M}, \ldots\} satisfies the present theorem.

We follow Definition 80. We have

\[
\tilde{V}_{W \rightarrow P} \equiv (V^{2}_{P \rightarrow W})^{-1}_{W \rightarrow P}, \quad \tilde{V}_{W \rightarrow M} \equiv (V^{1}_{W \rightarrow P})^{-1}_{W \rightarrow P},
\]

\[
\tilde{V}_{W \rightarrow M_{1}^{M_{2}}} \equiv (V^{1}_{W \rightarrow P} \cap V^{1}_{W \rightarrow P} \cap V^{1}_{W \rightarrow P})^{-1}_{W \rightarrow P}, \quad \tilde{V}_{P \rightarrow P_{1}^{P_{1}}} \equiv (V^{1}_{P \rightarrow P} \cap V^{1}_{P \rightarrow P} \cap V^{1}_{P \rightarrow P})^{-1}_{P \rightarrow P},
\]

\[
\tilde{W}_{W \rightarrow P} \equiv (V^{1}_{W \rightarrow P})^{-1}_{W \rightarrow P}, \quad \tilde{W}_{W \rightarrow P} \equiv (V^{1}_{W \rightarrow P})^{-1}_{W \rightarrow P}.
\]

Further, let \tilde{V}_{W \rightarrow M_{1}^{M_{2}}} \equiv (V_{W \rightarrow M}^{-1})_{W \rightarrow M}.

By Theorem 78 if \{V_{W \rightarrow M}, V_{P \rightarrow P}, \ldots\} is \mathcal{E}-- linked through \tilde{V}_{W \rightarrow P}, \tilde{V}_{W \rightarrow P}, so will \{V_{W \rightarrow W}, V_{P \rightarrow P}, \ldots\} be, where \(\mathcal{E}_{W \rightarrow W} \equiv \{V_{W \rightarrow W} \cap V_{W \rightarrow W} \cap V_{W \rightarrow W} \cap V_{W \rightarrow W} \cap V_{W \rightarrow W}\} \circ W \tilde{W}\)

and \{V_{W \rightarrow W}, V_{P \rightarrow P}, \ldots\} is \mathcal{E}-- linked through \tilde{V}_{W \rightarrow P}, \tilde{V}_{W \rightarrow P},

and \{V_{W \rightarrow W} \cap V_{P \rightarrow P}, \ldots\} \mathcal{E}-- linked through \tilde{V}_{W \rightarrow P}, \tilde{V}_{W \rightarrow P}, \tilde{V}_{W \rightarrow P}, \tilde{V}_{W \rightarrow P}, \tilde{V}_{W \rightarrow P},

Now

\[
\tilde{V}_{W \rightarrow W} \equiv (V_{W \rightarrow W})^{-1}_{W \rightarrow W} = (W \tilde{W})^{-1}_{W \rightarrow W}, \quad \tilde{V}_{P \rightarrow P} \equiv (V_{P \rightarrow P})^{-1}_{P \rightarrow P} = (W \tilde{W})^{-1}_{P \rightarrow P},
\]

This proves the result.

\[\square\]

11. Conclusions

In this paper we made a beginning towards developing an implicit form of linear algebra, basing it on linear relations (‘linkages’) rather than on linear transformations.

The basic operation was the ‘matched composition ↔’ which generalized ordinary composition of maps to that of linkages. We defined the ‘intersection-sum’ and ‘scalar multiplication’ for linkages which were analogues of sum and scalar multiplication of maps. Using the basic results (80) - implicit inversion theorem and implicit duality theorem - we proved results for linkages (eg. that intersection-sum of transposes of linkages is the transpose of intersection-sum of linkages, that, under mild conditions, matched composition is distributive under intersection-sum) analogous to those for maps.

We generalized the notion of an operator in our framework and developed a primitive spectral theory for it using intersection-sum as ‘sum’ and matched composition as ‘multiplication’.

We developed computationally efficient counterparts (‘emulators’) to state variables and showed that standard computations such as those involving invariant subspaces, feedback etc., and also spectral computations, could be done with emulators.

We tried to show that our ideas are useful from a computational point of view by first systematically developing the standard linear multivariable control theory, as expounded for instance in [17], in terms of linkages and showing that all the operations can be done implicitly without eliminating variables until the very end, when it would be required.

We illustrated our ideas with a paradigmatic instance namely a resistor, inductor, capacitor circuit. In particular we showed for such circuits that emulators could be built in linear time.
It is hoped that the ‘necessity’ of implicit linear algebra is evident since the illustrative examples show that operators are usually available in practice as composition of linkages (e.g. associated with the graph of a network) and more elementary operators (e.g. the device characteristics of a network). To efficiently exploit topology (for instance through port decompositon) we need to work in terms of linkages rather than in terms of maps.

Appendix A. Computing the basic operations

Appendix A.1. Representation

A vector space $V_A$ may be specified in one of the two following ways:

1. Through generator set for $V_A$:
   \[ f_A = \lambda^T [R_A] , \]
   where the rows of $R_A$ generate $V_A$ by linear combination. When the rows of $R_A$ are linearly independent $R_A$ is called a representative matrix of $V_A$.

2. Through constraint equations:
   \[ [S_A] f_A = 0 , \]
   where the rows of $S_A$ generate $V_A^\perp$. The solution space of this equation is $(V_A^\perp)^\perp = V_A$.

One or the other of these representations might be convenient depending upon the context.

Appendix A.2. Computing $V_{AB} \circ A$ and $V_{AB} \times B$ explicitly

Let $V_{AB} \circ A$ be defined through
\[
[S_A S_B] \begin{pmatrix} f_A \\ f_B \end{pmatrix} = 0.
\]

We do row operations so that the coefficient matrix is in the form
\[
\begin{bmatrix}
S_{1A} & 0 \\
S_{2A} & S_{2B}
\end{bmatrix},
\]
where the rows of $S_{2B}$ are linearly independent (or, if more convenient, columns of $S_{2A}$ are dependent on columns of $S_{2B}$). Then $[S_{1A}] f_A = 0$ defines $V_{AB} \circ A$ and $[S_{2B}] f_B = 0$ defines $V_{AB} \times B$. The statement about $V_{AB} \circ A$ may be seen as follows: Clearly if any $(f_A, f_B) \in V_{AB}$, then $f_A$ satisfies $[S_{1A}] f_A = 0$ so that $V_{AB} \circ A$ is contained in the solution space of the latter. Next let $f_A$ satisfy $[S_{1A}] f_A = 0$. Since columns of $S_{2A}$ are linearly dependent on columns of $S_{2B}$, the equation
\[
[S_{2B}] f_B = -[S_{2A}] f_A
\]
has a solution $\hat{f}_B$. Thus for any solution of $[S_{1A}] f_A = 0$, we can always find $\hat{f}_B$ such that $(f_A, \hat{f}_B) \in V_{AB}$. This completes the proof that $V_{AB} \circ A$ is the solution space of $[S_{1A}] f_A = 0$.

The statement about $V_{AB} \times B$ is routine.

Appendix A.3. Computing $V_A^1 \cap V_A^2$ Explicitly

Suppose $[S_A^1] f_A = 0$, $[S_A^2] f_A = 0$ define $V_A^1$, $V_A^2$ respectively. Let $A'$, $A''$ be copies of $A$ with $A$, $A'$, $A''$ disjoint. Build the space $V_{AA'A''}$ defined through
\[
\begin{bmatrix}
S_A^1 & S_A^2 \\
0 & I \\
I & 0
\end{bmatrix} \begin{pmatrix} f_A' \\ f_A'' \\ f_A \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \quad (A.1)
\]

It is clear that the vectors $f_A$ are precisely those in both $V_A^1$ and $V_A^2$. Thus $V_{AA'A''} \circ A$ is $V_A^1 \cap V_A^2$. The explicit construction of the dot operation has been discussed above.
Appendix A.4. Computing \( V_1^A + V_2^A \) Explicitly

Let \( V_1^A \) and \( V_2^A \) be defined as above. We define \( \hat{V}_{AA'} \) through

\[
\begin{pmatrix}
S_1^A & S_2^A \\
-I & -I & I
\end{pmatrix}
\begin{pmatrix}
f_1^A \\
I
\end{pmatrix} = \begin{pmatrix}
0 \\
0
\end{pmatrix}.
\]  
(A.2)

In this case again it is easy to see that \( \hat{V}_{AA'} \circ A = V_1^A + V_2^A \) and we complete the explicit construction as above.

Often the spaces \( V_1^A, \ V_2^A \) may themselves be available to us only implicitly — usually in the form of a generalized minor \( V_{AB} \leftrightarrow V_B \). We discuss this situation below after we discuss the computation of the generalized minor.

Appendix A.5. Computing \( V_{AB} \leftrightarrow V_B \) Implicitly

Let \( V_{AB} \) be defined by

\[
[S_A \ S_B] \begin{pmatrix} f_A \\ f_B \end{pmatrix} = 0
\]

and \( V_B \) by

\[
[S_B] f_B = 0.
\]

Let \( \hat{V}_{AB} \) be defined by

\[
[S_A \ S_B] \begin{pmatrix} f_A \\ f_B \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}.
\]  
(A.3)

Then

\[
\hat{V}_{AB} \circ A \equiv \{ f_A \ | \ (f_A, f_B) \in V_{AB}, f_B \in V_B \}
\]

\[
= V_{AB} \leftrightarrow V_B.
\]

Appendix A.6. Computing \( V_{AB} \leftrightarrow V_B \) Explicitly

In order to explicitly represent \( V_{AB} \leftrightarrow V_B \) as the solution space of an equation

\[
[S_A] f_A = 0,
\]

one has to do row operations and recast [A.3] as

\[
\begin{pmatrix}
S_1^{tA} & S_1^{tB} \\
S_2^{tA} & 0 \\
0 & S_B
\end{pmatrix}
\begin{pmatrix}
f_A \\
f_B
\end{pmatrix} = \begin{pmatrix}
0 \\
0
\end{pmatrix},
\]  
(A.4)

where the rows of \( S_1^{tB} \) together with those of \( S_B \) are independent. The solution space of

\[
[S_2^{tA}] f_A = 0,
\]

is clearly \( \hat{V}_{AB} \circ A (\hat{V}_{AB} \text{ as in Equation A.3}) \) that is, \( V_{AB} \leftrightarrow V_B \).

In general when one is performing operations such as intersection or sum with vector spaces, their representation may not be explicitly available but in the form \( V_{AB} \leftrightarrow V_B \).
Let $\hat{f}_B \in (\mathcal{V}_{AB} \cap \mathcal{V}_B) \circ B$. To find $\mathcal{V}_{AB} \leftrightarrow \{\hat{f}_B\}$ we first find one solution $\hat{f}_A$ to the equation using the first rows of (A.4)

$$
\begin{bmatrix}
S_1^A \\
S_2^A
\end{bmatrix} \hat{f}_A = \begin{bmatrix} S_1^B \hat{f}_B \\
0
\end{bmatrix}.
$$

Then

$$
\mathcal{V}_{AB} \leftrightarrow \{\hat{f}_B\} = \hat{f}_A + \mathcal{V}_{AB} \times A.
$$

$\mathcal{V}_{AB} \times A$ can be seen to be the solution to

$$
\begin{bmatrix}
S_1^A \\
S_2^A
\end{bmatrix} \tilde{f}_A = \begin{bmatrix} 0 \\
0
\end{bmatrix}.
$$

**Appendix A.7. Computing $\mathcal{V}^1_A \cap \mathcal{V}^2_A$ Implicitly**

Suppose $\mathcal{V}^1_A \cap \mathcal{V}^2_A$ is to be computed where

$$
\mathcal{V}^1_A = \mathcal{V}_{AB} \leftrightarrow \mathcal{V}^1_B
$$

$$
\mathcal{V}^2_A = \mathcal{V}_{AB} \leftrightarrow \mathcal{V}^2_B.
$$

Let $\mathcal{V}^1_{AB}, \mathcal{V}^2_{AB}$ be defined respectively through

$$
\begin{bmatrix}
S_1^A & S_B
\end{bmatrix} \begin{bmatrix} f_1^A \\
f_2^B
\end{bmatrix} = 0,
$$

$$
\begin{bmatrix}
S_2^A & S_B
\end{bmatrix} \begin{bmatrix} f_2^A \\
f_2^B
\end{bmatrix} = 0.
$$

Let $\mathcal{V}^1_B, \mathcal{V}^2_B$ be defined respectively through

$$
\begin{bmatrix}
\tilde{S}_B
\end{bmatrix} f_B = 0,
$$

$$
\begin{bmatrix}
\tilde{S}_B
\end{bmatrix} f_B = 0.
$$

We proceed now as in (A.1) by first copying set $A$ into $A', A''$ and $B$ into $B', B''$ and write the final equations as

$$
\begin{bmatrix}
S_1^A & S_1^B \\
S_2^A & S_2^B
\end{bmatrix} \begin{bmatrix}
S_1^A & S_1^B \\
S_2^A & S_2^B
\end{bmatrix}
\begin{bmatrix}
I \\
-I
\end{bmatrix}
\begin{bmatrix}
\begin{bmatrix}
\tilde{f}_A \\
\tilde{f}_B
\end{bmatrix}
\end{bmatrix} = 0
$$

(A.5)

If the above equation has the solution space $\mathcal{V}_{AA'BB''}$ then we can show that

$$
\mathcal{V}_{AA'BB''} \circ A = \mathcal{V}^1_A \cap \mathcal{V}^2_A.
$$

To see this, note that $\mathcal{V}^1_A$ is the collection of all $f_1^A$, which can be part of a solution vector $(f_1^A, f_1^B)$ of the first two rows of (A.3). $\mathcal{V}^2_A$ is the space of all vectors $f_2^A$, which can be part of the solution vector $(f_2^A, f_2^B)$ of the next two rows of (A.3). Now $f_A$, by the last two rows of the equation, is seen to a copy of both $f_1^A$ as well as $f_2^A$. Any such vector therefore belongs to $\mathcal{V}^1_A \cap \mathcal{V}^2_A$. Conversely any vector in $\mathcal{V}^1_A \cap \mathcal{V}^2_A$ can clearly be a copy of a part of some solution vector of the first two rows and therefore of the middle two rows also — which means it is a part of a solution vector of (A.5).
Appendix A.8. Computing $V_A^1 + V_A^2$ Implicitly

By similar arguments we can show that we can write the constraints for $V_A^1 + V_A^2$ as an implicit version as follows:

$$
\begin{bmatrix}
S_A^1 & S_B^1 \\
S_A^2 & S_B^2 \\
-I & -I & I
\end{bmatrix}
\begin{bmatrix}
f_A^1 \\
f_B^1 \\
S_B^1 \\
S_B^2 \\
f_A^2 \\
-I & -I & I
\end{bmatrix} = 0
$$

(A.6)

If $\tilde{V}_{AA',A''B'B''}$ is the solution space of the above equation then

$$V_A^1 + V_A^2 = \tilde{V}_{AA',A''B'B''} \circ A.$$

Appendix A.9. Computing $V_{WW}$, $V_{WW}$, and $V_{W}$ for Networks

The computation of $V_{WW}$, $V_{WW}$, and $V_{W}$ for Networks are important examples of implicit linear algebra. We describe how to perform such computations for a $RLCEJ$ network for one of the instances of $V_M$. The essential idea is to transform the problem to one of solving the three multi-ports under appropriate conditions.

Appendix A.9.1. $V_{WW}$, $V_{WW}$, $V_{W}$, $V_{M}$ = $0_{mu} \oplus F_{my}$

For the case $V_{WW}$, $V_{M}$ = $0_{mu} \oplus F_{my}$, see [12].

To compute $V_{WW}$, $V_{W}$, we begin once again by setting all sources to zero. Let $\dot{w} = (\dot{v}_C, \frac{di_L}{dt}) \in V_{WW}$. We will show how to find all $w$ such that $(\dot{w}, w) \in V_{WW}$.

The first step is to compute all $w = (v_C, i_L)$ corresponding to $\dot{w} = 0$. When the device characteristic matrices $C, L$, are positive definite, the collection of all such $v_C$ is the voltage space of $G_{CP} \times E_C$ and the collection of all such $i_L$ is the current space of $G_{LP} \circ E_L$.

Setting $\dot{w} = 0$ implies $\dot{v}_C = 0$ and $\frac{di_L}{dt} = 0$. This implies $C \dot{v}_C = 0$ and $L \frac{di_L}{dt} = 0$. Hence $i_C = 0$, $v_L = 0$.

Therefore in the multi-ports $N_{CP}$, $N_{LP}$, since $P_C$, $P_L$ do not contain cutsets, $i_{CP} = 0$, $v_{LP} = 0$.

Using KCL, KVL of $G_{CP}P_C$, $G_{LP}P_L$, this implies $i_{CP} = 0$, $v_{LP} = 0$.

In the multi-port $N_{ECP}E_{CP}$, the sources have already been set to zero (since $V_M = 0_{mu} \oplus F_{my}$).

In this network $P_{CP}$, $P_{LP}$ contain no loops or cutsets even when all sources are set to zero.

Under mild genericity conditions on the static devices, this network can be shown to have a unique solution for arbitrary values of $i_{P_C}$, $v_{P_C}$. So in particular if $i_{P_C} = 0$, $v_{P_L} = 0$ we would have only the zero solution. Hence $v_{P_C}$, $i_{P_L}$ are zero vectors.

This means, through KCL, KVL of $G_{CP}P_C$, $G_{LP}P_L$ that $v_{P_C} = 0$, $i_{P_L} = 0$.

The corresponding space of $v_C$ (with $v_{P_C} = 0$) would therefore be the space of solutions of KVL constraints of $G_{CP}$ with $P_C$ short circuited, that is, the voltage space of $G_{CP} \times E_C$.

(Under minimal multi-port decomposition this is the space of solutions of KVL constraints of $G$ with all branches other than the $C$ branches short circuited).

The corresponding space of $i_L$ (with $i_{P_L} = 0$) can similarly be shown to be the space of KCL constraints of $G_{LP}$ with $P_L$ open circuited, that is, the current space of $G_{LP} \circ E_L$.

(Under minimal multi-port decomposition this is the space of solutions of KCL constraints of $G$ with all branches of $G$ other than $L$ branches open circuited).

Next we compute a single $w_1 \in V_W$ corresponding to a $\dot{w}_1 \in V_{WW}$.

Let $\dot{w}_1 \in V_{WW}$. Now let $\dot{w}_1 = (v_{1C}, \frac{di_{1L}}{dt})$. 

84
Using \( i_{L}^{c} = C \frac{dv_{L}^{c}}{dt}, v_{L}^{c} = L \frac{di_{L}^{c}}{dt} \) we get \( i_{L}^{c}, v_{L}^{c} \).

Using KVL, KCL of \( G_{CP_{c}}, G_{LP_{c}} \), since \( P_{c}, P_{L} \) contain no loops or cutsets in these graphs we can compute \( i_{L}^{c}, v_{L}^{c} \) uniquely.

Using KCL, KVL of \( G_{P_{c}P_{L}}, G_{LP_{c}} \) we can compute \( i_{P_{c}}^{1}, v_{P_{c}}^{1} \).

In the multi-port \( \mathcal{N}_{E_{p},E_{m}P_{c}P_{L}} \), the sources have already been set to zero (since \( V_{M} = 0 = \mathcal{F}_{mg} \)).

As before we can compute \( v_{P_{c}}^{1}, i_{P_{c}}^{1} \) uniquely.

Through KCL, KVL of \( G_{P_{c}P_{L}}, G_{P_{c}P_{L}}, v_{P_{c}}^{1}, i_{P_{c}}^{1} \) can be computed uniquely.

One solution \( v_{L}^{1} \) can be obtained by extending \( P_{c} \) to a tree \( t_{C} \) in \( G_{CP_{c}}, \) assigning arbitrary voltages to branches in \( t_{C} - P_{c} \) and hence by KVL of \( G_{CP_{c}}, \) computing voltages for \( E_{C} - t_{C} \).

Similarly, one solution \( i_{L}^{1} \) corresponding to \( i_{L}^{c} \) can be obtained by extending \( P_{L} \) to a cotree \( t_{L} \) in \( G_{LP_{L}} \) assigning arbitrary currents to branches in \( t_{L} - P_{L} \) and hence by KCL of \( G_{LP_{L}} \) computing currents for \( E_{L} - t_{L} \).

The vectors \( v_{L}^{1}, i_{L}^{1} \) together constitute the desired \( w_{1} \in \mathcal{V}_{W} \).

The collection of all vectors \( K_{C}^{1} \oplus K_{L}^{1} \) corresponding to \( v_{P_{c}}^{1}, i_{P_{c}}^{1} \) (and therefore also corresponding to \( \dot{w}_{1} = (v_{L}^{1}, \frac{dv_{L}^{1}}{dt}) \)) is obtained as follows:

\[
K_{C}^{1} = v_{L}^{1} + V_{C}^{0}, K_{L}^{1} = i_{L}^{1} + V_{L}^{0}, \text{ where } V_{C}^{0}, V_{L}^{0} \text{ correspond to } \dot{v}_{C} = 0, \frac{dv_{L}}{dt} = 0.
\]

In the above, the computations which involve only KCL, KVL are, being linear time, inexpensive. The significant computation is the one that involves solution of the multi-port \( \mathcal{N}_{E_{p},E_{m}P_{c}P_{L}} \) for given \( i_{P_{c}}^{1}, v_{P_{c}}^{1} \).

Appendix B. Proof of Theorem 32

Proof. 1. By Theorem 30 any \( \mathcal{V}_{W} \) that has \( \mathcal{V}_{W} \) controlled invariant in it, is adjoint to the genaut \( \mathcal{V}_{W} \), which has \( \mathcal{V}_{W} \), conditioned invariant in it.

Now \( \mathcal{V}_{W} = (\mathcal{V}_{W})^{a}, \text{ and } (\mathcal{V}_{W})^{a} = \mathcal{V}_{W} \).

So it is sufficient for us to show that if \( \mathcal{V}_{W} \) has \( \mathcal{V}_{W} \) conditioned invariant in it, then \( \mathcal{V}_{W} \subseteq \mathcal{V}_{W} \).

Let \( \mathcal{V}_{W} \) be a genaut and have \( \mathcal{V}_{W} \) conditioned invariant in it.

From Theorem 30, we know that \( \mathcal{V}_{W} \subseteq (\mathcal{V}_{W} \times \mathcal{V}_{W}) \).

It follows that

\[
\mathcal{V}_{W} \subseteq (\mathcal{V}_{W} \times \mathcal{V}_{W})^{\perp},
\]

i.e.,

\[
\mathcal{V}_{W} \subseteq (\mathcal{V}_{W} \circ \mathcal{V}_{W}) \],
\]

i.e.,

\[
(\mathcal{V}_{W} \circ \mathcal{V}_{W}) \subseteq ((\mathcal{V}_{W} \circ \mathcal{V}_{W}) \circ \mathcal{V}_{W}) \]

i.e.,

\[
\mathcal{V}_{W} \subseteq \mathcal{V}_{W} \circ \mathcal{V}_{W} \]

2. From Theorem 30, \( \mathcal{V}_{W} \) is LSG with \( \mathcal{V}_{W} \) controlled invariant in it iff \( \mathcal{V}_{W}^{a} \) is USG and has \( \mathcal{V}_{W}^{a} \) conditioned invariant in it.

By Theorem 31, when \( \mathcal{V}_{W}^{a} \) is USG, we have that

\[
\mathcal{V}_{W}^{a} \circ (\mathcal{V}_{W} \oplus (\mathcal{V}_{W} \circ \mathcal{V}_{W}))
\]

is a genop.
So it is sufficient to show that, if $\mathcal{V}_{\hat{W}}$ is USG and has $\mathcal{V}_{W}$ conditioned invariant in it, then $\mathcal{V}_{\hat{W}^2} \cap (\mathcal{V}_{\hat{W}} \oplus (\mathcal{V}_{\hat{W}})^{\perp})_{\hat{W} \hat{W}^2}$ is a genop.

Let $\mathcal{V}_{\hat{W}}$ be USG and have $\mathcal{V}_{W}$ conditioned invariant in it. From Theorem 31, we know that, $\mathcal{V}_{\hat{W}} \oplus (\mathcal{V}_{W})_{\hat{W}}$ is a genop. But then by Theorem 28 we have that $(\mathcal{V}_{\hat{W}} \oplus (\mathcal{V}_{W})_{\hat{W}})^{\perp}$ is a genop.

\[ i.e., (\mathcal{V}_{\hat{W}} \oplus (\mathcal{V}_{W})_{\hat{W}})^{\perp} \text{ is a genop,} \]

\[ (\mathcal{V}_{\hat{W}} \oplus (\mathcal{V}_{W})_{\hat{W}})^{\perp} \cap (\mathcal{V}_{W} \oplus (\mathcal{V}_{W})_{\hat{W}}) \text{ is a genop,} \]

\[ i.e., \mathcal{V}_{\hat{W}} \cap (\mathcal{V}_{W} \oplus (\mathcal{V}_{W})_{\hat{W}}) \text{ is a genop.} \]

\[ \square \]

**Appendix C. Proof of Lemma 36 part 2**

**Proof.** Note that

\[ (\mathcal{V}_{\hat{W}^2} \cap \mathcal{V}_{W}) \circ \hat{W} = ((\mathcal{V}_{\hat{W}^2} \cap \mathcal{V}_{W}) \circ \hat{W})^{\perp}, \]

which reduces to

\[ (\mathcal{V}_{\hat{W}^2} \cap \mathcal{V}_{W}) \circ \hat{W} = (((\mathcal{V}_{\hat{W}^2} \cap \mathcal{V}_{W}) \circ \hat{W})^{\perp})^{\perp}, \]

which is equivalent to

\[ (((\mathcal{V}_{\hat{W}^2} \cap \mathcal{V}_{W}) \circ \hat{W})^{\perp})^{\perp} = ([((\mathcal{V}_{\hat{W}^2} \cap \mathcal{V}_{W}) \circ \hat{W})^{\perp}])^{\perp}, \]

This can be interpreted as

\[ (\mathcal{V}_{\hat{W}^2} \cap \mathcal{V}_{W}) \circ \hat{W} = (\mathcal{V}_{\hat{W}^2} \cap \mathcal{V}_{W}) \circ \hat{W}, \]

where we have denoted by $\mathcal{V}_{\hat{W}^2} \cap \mathcal{V}_{W}$ the genop. Since any dynamical system is the adjoint of its adjoint and for any space $\mathcal{V}$, we have $(\mathcal{V}^{\perp})^{\perp}$, this proves this part of the lemma. $\square$

**Appendix D. Dualization of pole placement algorithms**

In this section we recast the algorithms of Subsection 9.1 in such a manner that they can be line by line dualized.

The rule is simply to work only with vector spaces (and not with vectors), avoid the ‘belongs to’ relation and use ‘contained in’ instead. We give interpretations to all the entities that occur in the algorithms of the previous subsections.

**Interpreting basic sequences**

$x^0_W$ is a one dimensional subspace satisfying

\[ x^0_W \subseteq \mathcal{V}^u_{\hat{W}} \times \hat{W}, \quad x^0_W \not\subseteq (\mathcal{V}^u_{\hat{W}} \times \hat{W}). \]
(This is possible since $V^u_{W,W}$ is a USG but has been assumed not to be a genop.)

All the $x^j_w$ are one dimensional subspaces.

$$x^{j+1}_w \subseteq (V^u_{W,W} \cap x^j_w) \circ \hat{W}, \quad x^{j+1}_w \nsubseteq x^0_w + x^1_w + \cdots + x^j_w + V^{com}_{W,W}.$$  

We stop when $(V^u_{W,W} \cap x^j_w) \circ \hat{W} \subseteq x^0_w + x^1_w + \cdots + x^j_w + V^{com}_{W,W}$, i.e., at $j = k - 1$.

We build the following subspaces

$$\begin{align*}
x^{00}_{W,W} & \equiv x^0_w \cap (V^u_{W,W})^{(0)} \cap x^0_w + V^{com}_{W,W} \oplus V^{com}_{W,W}, \\
x^{01}_{W,W} & \equiv x^0_w \cap (V^u_{W,W})^{(1)} \cap x^1_w + V^{com}_{W,W} \oplus V^{com}_{W,W}, \\
& \vdots \\
x^{0j}_{W,W} & \equiv x^0_w \cap (V^u_{W,W})^{(j)} \cap x^j_w + V^{com}_{W,W} \oplus V^{com}_{W,W}, \\
& \text{till } j = k - 1. \text{ Here}
\end{align*}$$

$$(V^u_{W,W})^{(0)} \equiv (I_{W,W} \cap V^u_{W,W} \circ \hat{W}) + V^u_{W,W} \times \hat{W}, \quad (V^u_{W,W})^{(1)} \equiv V^u_{W,W}, \quad (V^u_{W,W})^{(j+1)} \equiv (V^u_{W,W})^j \ast V^u_{W,W}.$$  

At $j = k$, we can pick $b_t$ such that

$$b_t^j x^{0j}_{W,W} \oplus V^{com}_{W,W} \subseteq x^0_w \oplus V^{com}_{W,W} \oplus V^{com}_{W,W}.$$  

We will show that this implies that the LHS is decoupled.

Let $V'_{W,W} \equiv LHS.$

Each term $b_t^j x^{0j}_{W,W}$ satisfies $b_t^j x^{0j}_{W,W} \times \hat{W} \supseteq V^{com}_{W,W}.$

Therefore $V'_{W,W} \supseteq 0_{W,W} \oplus V^{com}_{W,W}$, so that $V'_{W,W} \times \hat{W} \supseteq V^{com}_{W,W}.$

But $V'_{W,W} \subseteq x^0_w \oplus V^{com}_{W,W} \oplus V^{com}_{W,W},$ implies that $V'_{W,W} \circ \hat{W} \subseteq V^{com}_{W,W}.$

Therefore $V'_{W,W} \circ \hat{W} \subseteq V'_{W,W} \times \hat{W}.$

Since we always have $V'_{W,W} \circ \hat{W} \supseteq V'_{W,W} \times \hat{W},$ this means that $V'_{W,W} \circ \hat{W} = V'_{W,W} \times \hat{W},$ and that $V'_{W,W}$ is decoupled.

**Constructing genops from basic sequence analogues**

Define

$$\begin{align*}
\lambda_{W,W}^{(j+1)} & \equiv x^j_w \cap V^u_{W,W} \cap x^{j+1}_w + V^{com}_{W,W} \oplus V^{com}_{W,W}, \\
\lambda_{start_{W,W}} & \equiv \lambda_{W,W}^{01} + \cdots + \lambda_{W,W}^{(j+1)} + \cdots + \lambda_{W,W}^{(k-1)k} + V^{com}_{W,W} \oplus V^{com}_{W,W}.
\end{align*}$$

Observe that $\lambda_{W,W}^{(j+1)}$ are LSGs and would be one dimensional if $V^{com}_{W,W} = 0_{W,W}.$ The space $\lambda_{start_{W,W}},$ which is a sum of spaces $\lambda_{W,W}^{(j+1)}$ and $V^{com}_{W,W} \oplus V^{com}_{W,W},$ is a genop since

1. $\lambda_{start_{W,W}} \circ W = x^0_w + \cdots + x^{k-1}_w + V^{com}_{W,W} \supseteq x^j_w + \cdots + x^k_w + V^{com}_{W,W} = (\lambda_{start_{W,W}} \circ \hat{W})_W.$
2. $\lambda_{start_{W,W}} \circ W = x^0_w + \cdots + x^{k-1}_w + V^{com}_{W,W}$ and the only way of obtaining a vector in $V^{com}_{W,W}$ as a linear combination of nonzero vectors of $x^0_w, \ldots, x^{k-1}_w$ is by the trivial linear combination, so that

$$\begin{align*}
\lambda_{start_{W,W}} \times \hat{W} = V^{com}_{W,W} \subseteq (V^{com}_{W,W})_W \subseteq (\lambda_{start_{W,W}} \times W)_\hat{W}.
\end{align*}$$
\(V_{\text{start}}\) would be annihilated by the polynomial \(b_0 + \cdots + b_{k-1}s^{k-1} + s^k\). The proof is essentially the same as the one for Claim 1.

**Transforming basic sequence analogues**

Next we build spaces which are analogues of \(y_{W'}^j\) by constructing a subspace version of Equation 27.

\[
\begin{align*}
\mathcal{Y}_W^{00} & \equiv \mathcal{X}_W^{00}, \\
\mathcal{Y}_W^{01} & \equiv \mathcal{X}_W^{01} + w_1 \mathcal{X}_W^{00'}, \\
& \quad \vdots \\
\mathcal{Y}_W^{0k} & \equiv \mathcal{X}_W^{0k} + w_1 \mathcal{X}_W^{0(k-1)'} + \cdots + w_k \mathcal{X}_W^{00'}.
\end{align*}
\]

(D.1)

Define

\[
\mathcal{Y}_W^{j0} \equiv \mathcal{Y}_W^{j0}, \quad \mathcal{Y}_W^{j(j+1)} \equiv \mathcal{Y}_W^{j0} \oplus \mathcal{Y}_W^{j0 (j+1)}
\]

and

\[
\mathcal{Y}_W^{end} \equiv \mathcal{Y}_W^{01} + \cdots + \mathcal{Y}_W^{j(j+1)} + \cdots + \mathcal{Y}_W^{(k-1)k} + \mathcal{Y}_W^{\text{com}} \oplus \mathcal{Y}_W^{\text{com}}.
\]

\(\mathcal{Y}_W^{end}\) would be annihilated by the polynomial \(c_0 + \cdots + c_{k-1}s^{k-1} + s^k\), where \((c_0, \ldots, c_k), c_k = 1\) satisfies Equation 33.

**Line by line dualization**

Once ideas have been cast in the subspace context the algorithms can be dualized line by line as follows.

Our notation is as follows:

The dual of \(x_W^j\) is \(x_W^{j'} = ((x_W^j)^*)_W\), dual of \(x_W^j\) is \(x_W^{j'} = ((x_W^j)^*)_W\).

The dual of \(\mathcal{Y}_W^{j0}\) is \(\mathcal{Y}_W^{j0'} = ((\mathcal{Y}_W^{j0})^*)_W\).

The dual of \(\mathcal{Y}_W^{j0'}\) is \(\mathcal{Y}_W^{j0'} = \mathcal{Y}_W^{j0} \oplus \mathcal{Y}_W^{j0}\).

The dual of \(\mathcal{Y}_W^{(k-1)k}\) is \(\mathcal{Y}_W^{(k-1)k} = \mathcal{Y}_W^{j0} \oplus \mathcal{Y}_W^{j0}\).

**Interpreting basic sequences**

We are given an LSG \(\mathcal{Y}_W^{j0} \equiv (y_W^j)_W\) is an \(n - 1\) \((n = |W|)\) dimensional subspace satisfying

\[
x_W^{j0} \supseteq \mathcal{Y}_W^{j0} \circ W, \quad x_W^{j0} \supseteq (\mathcal{Y}_W^{j0} \circ W)_W.
\]

(This is possible since \(\mathcal{Y}_W^{j0}\) is an LSG but has been assumed not to be a genop.)

All \(x_W^{j0}\) are \(n - 1\) dimensional subspaces.

\[
x_W^{j0} = (\mathcal{Y}_W^{j0} \circ W + (\mathcal{Y}_W^{j0} \circ W)_W).
\]

We stop when \((\mathcal{Y}_W^{j0} + x_W^{j0})_W \supseteq x_W^{00} \cap x_W^{j0} \cap \cdots \cap x_W^{j0} \cap \mathcal{Y}_W^{\text{com}}, \text{i.e., at } j = k - 1.

We build the following subspaces

\[
\mathcal{X}_W^{000} \equiv (x_W^{00} + (\mathcal{Y}_W^{j0})^{(0)} + x_W^{00} \cap (\mathcal{Y}_W^{\text{com}} \circ W).\]

\[
\mathcal{X}_W^{100} \equiv (x_W^{10} + (\mathcal{Y}_W^{j0})^{(1)} + x_W^{00} \cap (\mathcal{Y}_W^{\text{com}} \circ W),
\]

\[
\vdots \]

88
\[ X^{(j_0)}_{W W} \equiv \left( x_{W}^{(j)} + (V_{W W}^{(j)}) + x_{W}^{(0)} \right) \cap (V_{W W}^{com} \oplus V_{W W}^{com}), \]

till \( j = k - 1. \)

Here

\( (V_{W W}^{(j)})^{(0)} \equiv (I_{W W} \cap V_{W W}^{(j)} \circ W) + V_{W W}^{(j)} \times W, \quad (V_{W W}^{(j)})^{(1)} \equiv V_{W W}^{(j)}, \quad (V_{W W}^{(j)})^{(j+1)} \equiv (V_{W W}^{(j)}) \ast V_{W W}^{(j)}. \)

(Note that we could equivalently have written \( (V_{W W}^{(j)})^{(0)} \equiv (I_{W W} + V_{W W}^{(j)} \times W) \cap V_{W W}^{(j)} \circ W. \)

At \( j = k, \) we can pick \( b_i \) such that

\[ b_i W_{W}^{(k-1)} \cap A_{W W}^{(k-1)} + \cdots + b_{k-1} W_{W}^{(k-1)} \cap A_{W W}^{(k-1)} \cap V_{W W}^{(k-1)} \supseteq W_{W}^{(k)} + V_{W W}^{com} \oplus V_{W W}^{com}. \]

We will show that this implies that the LHS is decoupled. Let \( V_{W W}^{\prime} \equiv LHS. \) Each term \( b_j W_{W}^{(j)} \) satisfies

\[ b_j W_{W}^{(j)} \circ W \subseteq V_{W W}^{com}. \]

Therefore \( V_{W W}^{\prime} \subseteq V_{W W}^{com} \oplus V_{W W}^{com}, \) so that \( V_{W W}^{\prime} \circ W \subseteq V_{W W}^{com}. \)

But \( V_{W W}^{\prime} \supseteq \cap A_{W W}^{(k-1)} \cap V_{W W}^{(k-1)} \), implies that \( V_{W W}^{\prime} \times W \supseteq V_{W W}^{com}. \)

Since we always have \( V_{W W}^{\prime} \times W \subseteq V_{W W}^{\prime} \circ W, \) this means that \( V_{W W}^{\prime} \circ W = V_{W W}^{\prime} \times W, \) and that \( V_{W W}^{\prime} \) is decoupled.

**Constructing genops from basic sequence analogues**

Define

\[ X^{(j_0)}_{W W} \equiv (x_{W}^{(j)} + (V_{W W}^{(j)}) + x_{W}^{(0)}) \cap (V_{W W}^{com} \oplus V_{W W}^{com}), \]

\[ Y^{\text{start}}_{W W} \equiv (X^{(j_0)}_{W W} \cap \cdots \cap X^{(j_0)}_{W W} \cap \cdots \cap X^{(k-1)}_{W W} \cap \cdots \cap X^{(k-1)}_{W W} \cap \cdots \cap \hat{V}_{W W}^{com} \oplus \hat{V}_{W W}^{com}). \]

Observe that \( X^{(j_0)}_{W W}, X^{(j_0)}_{W W} \) are USGs and would be \( |W| - 1 \) dimensional if \( V_{W W}^{com} = F_{W W}. \) The space \( V_{W W}^{\text{start}}, \) which is an intersection of spaces \( X^{(j_0)}_{W W}, X^{(j_0)}_{W W} \), is a genop since we saw earlier that its dual is a genop. \( V_{W W}^{\text{start}} \) would be annihilated by the polynomial \( b_0 + \cdots + b_{k-1} s^{k-1} + s^k. \)

**Transforming basic sequence analogues**

Next we build spaces which are analogues of \( y_{W}^{(j)} \) by constructing a subspace version of Equation (D.2)

\[
\begin{align*}
\hat{y}_{W W}^{(j_0)} &= \hat{A}_{W W}^{(j_0)} \\
\hat{y}_{W W}^{(j_1)} &= \hat{A}_{W W}^{(j_1)} + \hat{v} W_{W}^{(0)} \\
\hat{y}_{W W}^{(j_2)} &= \hat{A}_{W W}^{(j_2)} + \hat{v} W_{W}^{(1)} + \hat{v} W_{W}^{(2)} \\
\hat{y}_{W W}^{(j_k)} &= \hat{A}_{W W}^{(j_k)} + \hat{v} W_{W}^{(k-1)} + \cdots + \hat{v} W_{W}^{(0)}
\end{align*}
\]

Define

\[ y_{W W}^{(j_0)} \equiv (y_{W W}^{(j_0)}, y_{W W}^{(j_1)}, \cdots, y_{W W}^{(j_k)}), \quad y_{W W}^{(j_0)} \equiv y_{W W}^{(j_0)} \ast y_{W W}^{(j_0)} \]

We define \( y_{W W}^{(j_0)} \equiv (y_{W W}^{(j_0)}, \cdots, y_{W W}^{(j_k)}), \quad y_{W W}^{(j_0)} \mid (V_{W W}^{com} \oplus V_{W W}^{com}). \)

\( y_{W W}^{(j_0)} \) would be annihilated by the polynomial \( c_0 + \cdots + c_{k-1} s^{k-1} + s^k, \) where \( (c_0, \cdots, c_k), c_k = 1 \) satisfies Equation (33).
Figure E.5: The primal network with port decomposition into capacitor inductor and static multiports
Appendix E. Building an emulator implicitly for a network based dynamical system

We give an example where we spell out all the vector spaces, which implicitly determine the multiport based emulator.

Example 82. The primal \( \mathcal{N} \) shown in Figure E.5 (or rather its solution space \( \mathcal{V}^{sol}(\mathcal{N}) \)), is a GDSA (generalized dynamical system with additional variables) with the variables

\[
v_C, i_L, i_C, v_L, \dot{i}_C, i_L, v_R, i_R, u_i, u,v, y_i, v_{ui}, v_{ig}, i_{yg},
\]

(each of \( v_C, i_L, \cdots \) is itself a subvector, for instance \( v_C \equiv (v_{C1}, v_{C2}, v_{C3}) \)). Of these the dynamical variables are \( v_C, i_L, \dot{i}_C, i_L \), the manifest variables \( M_u \) are \( u_i, u, \) and the manifest variables \( M_y \) are \( y_i, y_v \). The additional variables are \( i_C, v_L, i_R, v_{ui}, i_{uv}, v_{gi}, i_{gy} \). For greater readability, we will make this total set of variables, the index set. We also use a convenient notation \( \{ x = Ky \} \) to denote the solution space \( \mathcal{V}_{xy} \) of the equation \( x = Ky \).

Let \( \mathcal{G} \) be the graph of the network. Let the device characteristic constraints of the network be

\[
i_C = C \dot{i}_C; \quad v_L = L \dot{i}_L; \quad v_R = R \dot{i}_R; \quad v_{yi} = 0; \quad i_{yi} = 0; \quad v_{ui} \text{ free}, \quad i_{uv} \text{ free},
\]

where the matrices \( C, L, R \) are symmetric positive definite. The topological constraints are

\[
v \in \mathcal{V}^v(\mathcal{G}), \quad i \in \mathcal{V}^i(\mathcal{G}), \quad \dot{i}_C \in \mathcal{V}^i(\mathcal{G}) \circ E_C = \mathcal{V}^v(\mathcal{G} \circ E_C), \quad \dot{i}_L \in \mathcal{V}^i(\mathcal{G}) \circ E_L = \mathcal{V}^v(\mathcal{G} \times E_L).
\]

We will denote

- the above vector space to which \( \dot{i}_C \) belongs, by \( \mathcal{V}_{\dot{i}_C}^{top} \),
- the vector space to which \( \dot{i}_L \) belongs, by \( \mathcal{V}_{\dot{i}_L}^{top} \), and

\[
\mathcal{V}^v(\mathcal{G}) \oplus \mathcal{V}^i(\mathcal{G}) \oplus \mathcal{V}_{\dot{i}_C}^{top} \oplus \mathcal{V}_{\dot{i}_L}^{top} \quad \text{by} \quad \mathcal{V}^{top}(\mathcal{N}).
\]

The original GDS \( \mathcal{V}_{W\hat{W}M_uM_y} \) corresponding to \( \mathcal{N} \) has the index set \( \{ v_C, i_L, i_C, i_L, u_i, u, v, y_i, v_{ui}, v_{ig}, i_{yg} \} \). We have

\[
\mathcal{V}_{W\hat{W}M_uM_y} = (\{ v_R = R \dot{i}_R \} \oplus \{ \dot{i}_C = C \dot{i}_C \}) \cap \{ \{ u_i, u, v, y_i, v_{ui}, v_{ig}, i_{yg} \} \}
\]

In order to build the emulator \( \mathcal{V}_{P_{\hat{P}M_uM_y}} \), the network \( \mathcal{N} \) is now decomposed into multiports and port connection diagrams, with minimum number of ports, as outlined in Section 2.3. This is shown in Figure E.5 The relevant multiports are

\[
\mathcal{N}_{CP_C}, \quad \mathcal{N}_{P_CP_L}^{\text{Ray}}, \quad \mathcal{N}_{LP_L}.
\]

We denote their graphs respectively by

\[
\mathcal{G}_{CP_C}, \quad \mathcal{G}_{P_CP_L}^{\text{Ray}}, \quad \mathcal{G}_{LP_L}.
\]

The device characteristics of the multiport \( \mathcal{N}_{CP_C} \) are

\[
\{ i_C = C \dot{i}_C \}, \quad v_C, i_{PC}, v_{PC} \text{ free},
\]

those of the multiport \( \mathcal{N}_{LP_C} \) are

\[
\{ v_L = L \dot{i}_L \}, \quad i_L, i_{PL}, v_{PL} \text{ free},
\]

those of the multiport \( \mathcal{N}_{P_CP_L}^{\text{Ray}} \) are

\[
\{ v_R = R \dot{i}_R \}, \quad v_{ui}, i_{ui}, v_{uv}, i_{uv}, v_{yi}, i_{yi}, i_{PC}, v_{PC}, i_{PL}, v_{PL} \text{ free}, \quad i_{yu}, v_{yi} \text{ zero}.
\]
The topological constraints of the multiport $N_{CP_C}$ are
\[
(v_C, v_{PC}, i_C, i_{PC}) \in V^v(G_{CP_C}), \quad (i_C, i_{PC}) \in V^i(G_{CP_C}), \quad \dot{v}_C \in V^v(G_{CP_C}) \circ E_C = V^v(G) \circ E_C = V^v(G \circ E_C) = V^v_{i_C}.
\]

The topological constraints of the multiport $N_{LP_L}$ are
\[
(v_L, v_{PL_L}, i_L, i_{PL_L}) \in V^v(G_{LP_L}), \quad (i_L, i_{PL_L}) \in V^i(G_{LP_L}), \quad \dot{i}_L \in V^i(G_{LP_L}) \circ E_L = V^i(G \times E_L) = V^i_{i_L}.
\]

(The statements $V^v(G_{CP_C}) \circ E_C = V^v(G) \circ E_C$, $V^i(G_{LP_L}) \circ E_L = V^i(G) \circ E_L$ follow from the properties of multiport decomposition.)

The port connection diagram is $G_{PC,PC} \oplus G_{PL,L}$. For simplicity let us write for any graph $G'$,
\[
V^\text{top}(G') = (V^v(G') \oplus V^i(G')).
\]

By the definition of multiport decomposition, we have
\[
V^\text{top}(G) = (V^\text{top}(G_{CP_C}) \oplus V^\text{top}(G_{LP_L}) \oplus V^\text{top}(G_{PC,PC} \oplus G_{PL,L})) \leftrightarrow (V^\text{top}(G_{PC,PC}) \oplus V^\text{top}(G_{PL,L})).
\]

We denote the space of solutions of the device characteristic of a linear network $N$ by $V^\text{dev}(N)$ and the space of solutions of the network by $V^\text{sol}(N)$. In each of the multiports, the port edges have no constraints on their currents or voltages. The multiports do not have common variables. Thus
\[
V^\text{dev}(N) = [V^\text{dev}(N_{CP_C}) \circ \{v_C, i_C, \dot{v}_C\}] \oplus [V^\text{dev}(N_{LP_L}) \circ \{v_L, i_L, \dot{i}_L\}] \oplus [V^\text{dev}(N_{PC,PC} \oplus G_{PL,L}) \circ \{v_R, i_R, u, u, y, y, y, u, i_u, y_u\}].
\]

Since the port branches have no device characteristic constraints, we can write
\[
V^\text{sol}(N) = (V^\text{sol}(N_{CP_C}) \oplus V^\text{sol}(N_{LP_L}) \oplus V^\text{sol}(N_{PC,PC} \oplus G_{PL,L})) \leftrightarrow (V^\text{top}(G_{PC,PC}) \oplus V^\text{top}(G_{PL,L})).
\]

The dynamical system $V_{W \oplus M, M}$ is the restriction of the above space to \{\{v_C, i_L, \dot{v}_C, i_L, u, u, y, y\}, with $W \equiv \{v_C, i_L\}, W' \equiv \{i_C, i_L\}, M_u \equiv \{u, u\}, M_y \equiv \{y, y\}$. This can be rewritten as
\[
V_{W \oplus M, M} = \\
\left[\left(\left(V^\text{top}(G_{CP_C}) \oplus V^\text{top}_{i_C}\right) \cap \{i_C = C \dot{v}_C\}\right) \leftrightarrow F_{i_C}\right] \\
\oplus \left[\left(V^\text{top}(G_{LP_L}) \oplus V^\text{top}_{i_L}\right) \cap \{v_L = L \dot{i}_L\}\right] \leftrightarrow F_{v_L}\right] \\
\oplus \left[V^\text{top}(G_{PC,PC} \oplus G_{PL,L} \circ Ruy) \leftrightarrow \{v_R = R Ri_R \oplus 0_{u, y_u} \oplus F_{i_u, v_u}\}\right] \\
\leftrightarrow \left[V^\text{top}(G_{PC,PC}) \oplus V^\text{top}(G_{PL,L})\right].
\]

We now describe the emulator dynamical system $V_{P \oplus M, M}$ implicitly. This has the index set of variables \{\{v_{PC}, i_{PL}, \dot{v}_{PC}, i_{PL}, u, u, y, y\}. Here $P = \{v_{PC}, i_{PL}\}, \dot{P} = \{i_{PC}, i_{PL}\}, M \equiv \{u, u, y, y\}$. The variables $\dot{v}_{PC}, i_{PL}$ are newly introduced and are defined by
\[
(\dot{v}_{PC}, \dot{v}_{PC}) \in V^v(G_{CP_C}); \quad (i_{PL}, i_{PL}) \in V^i(G_{LP_L}).
\]

If $P, PL$ do not contain circuits or cutsets, which happens when the port decomposition is minimal, $\dot{v}_{PC}$ is uniquely determined by $\dot{v}_C$ and $i_{PL}$ is uniquely determined by $i_L$ through the above definitions.

Let us now modify $N_{CP_C}$ to a new object $N_{CP_C}'$ by adding an additional constraint involving ($\dot{v}_C, \dot{v}_{PC}$).
Thus the constraints of $N^v_{PC}$ are:

$$(i_C, i_{PC}) \in V^v(G_{CP_C}); \quad (v_C, v_{PC}) \in V^v(G_{CP_C}); \quad (i_C, v_{PC}) \in V^v(G_{CP_C}); \quad i_C = C v_C.$$

Let us denote the solution space of these constraints restricted to\{i_{PC}, v_{PC}\} by $V_{i_{PC}, v_{PC}}$. Clearly

$$V_{i_{PC}, v_{PC}} = \langle [V^v(G_{CP_C})]_{i_C, v_{PC}} \oplus V^i(G_{CP_C}) \rangle \leftrightarrow \{i_C = C v_C\}.$$

Since the port decomposition is minimal, the ports $P_C$ will contain neither circuits nor cutsets of $G_{CP_C}$. If the matrix $C$ is positive definite, it can be shown that from either $i_{PC}$ or $v_{PC}$ we can determine all the variables in\{i_C, v_C, i_{PC}, v_{PC}\}, uniquely.

Next let us modify $N_{PL_L}$ to a new object $N'_{PL_L}$ by adding an additional constraint involving\{i_L, i_{PL}\}. Thus the constraints of $N'_{PL_L}$ are

$$(v_L, v_{PL}) \in V^v(G_{PL_L}); \quad (i_L, i_{PL}) \in V^v(G_{PL_L}); \quad (i_L, v_{PL}) \in V^v(G_{PL_L}); \quad v_L = L i_L.$$

Let us denote the solution space of these constraints restricted to the index set\{v_{PL}, i_{PL}\} by $V_{v_{PL}, i_{PL}}$. Clearly

$$V_{v_{PL}, i_{PL}} = \langle [V^v(G_{PL_L})]_{i_L, v_{PL}} \oplus V^v(G_{PL_L}) \rangle \leftrightarrow \{v_L = L i_L\}.$$

Since the port decomposition is minimal, the ports $P_L$ will contain neither circuits nor cutsets of $G_{PL_L}$. If the matrix $L$ is positive definite, it can be shown that from either $v_{PL}$ or $i_{PL}$, we can determine all the variables in\{v_L, i_L, v_{PL}, i_{PL}\}, uniquely.

The constraints of $N'_{PL_L}^\prime_{PL_L, Ray}$ are

$$i_{PL_L, Ray} \in V^i(G_{PL_L}^\prime_{PL_L, Ray}); \quad v_{PL_L, Ray} \in V^v(G_{PL_L}^\prime_{PL_L, Ray}); \quad v_R = R i_R; \quad i_{uv} \text{ free}; \quad v_{ui} \text{ free}; \quad v_{yi} = 0; \quad i_{vy} = 0.$$

Let us denote the solution space of these constraints restricted to the index set\{v_{PC}, v_{PL_L}, v_{uv}, i_{PC}, i_{PL_L}, i_{ui}, i_{yi}\}, briefly by $V_{stat}$.

The emulator $V_{P \hat{P}_{M,M'}}$ on the index set\{v_{PC}, i_{PL_L}, v_{PC}, i_{PL_L}, ui, uv, yi, yv\}, \(P \equiv \{v_{PC}, i_{PL_L}\}, \hat{P} \equiv \{v_{PC}, i_{PL_L}\}, M \equiv \{ui, uv, yi, yv\}\), is expressed implicitly by

$$V_{P \hat{P}_{M,M'}} = V_{v_{PC}} \leftrightarrow [V^v(G_{PC}^v) \oplus V^v(G_{PC}^v)] \leftrightarrow V_{stat} \leftrightarrow [V^v(G_{PC}^v) \oplus V^v(G_{PC}^v)] \leftrightarrow V_{v_{PL_L}}.$$

Next let us consider the linking between the primal dynamical system $V_{W \hat{W}_{M,M'}}$ and its emulator $V_{P \hat{P}_{M,M'}}$, by eliminating the most natural candidates for the spaces $V_{W}^1_{W}$ and $V_{W}^2_{\hat{W} \hat{P}}$.

Here $W \equiv \{i_C, i_L\}, P \equiv \{v_{PC}, i_{PL_L}\}$, and $\hat{W} \equiv \{i_C, i_L\}, \hat{P} \equiv \{v_{PC}, i_{PL_L}\}$.

The relationship between $i_{PC}, v_{PC}$ is entirely topological, merely that \(v_{PC}, v_{PC} \in V^v(G_{CP_C})\). Similarly, the relationship between $i_L, i_{PL_L}$ is merely that \(i_L, i_{PL_L} \in V^v(G_{PL_L})\). Thus

$$V_{W}^1_{W} \equiv [V^v(G_{CP_C}) \oplus V^v(G_{PL_L})].$$

On the other hand the relationship between $\hat{W}, \hat{P}$ involves more constraints.

$$(i_C, i_{PC}) \in V^v(G_{CP_C}); \quad (i_C, i_{PC}) \in V^v(G_{CP_C}); \quad i_C = C v_C.$$
Let us denote the restriction of the solution space of these constraints to \( \{i_C, \hat{v}_{PC} \} \) by \( \mathcal{V}_{i_C, \hat{v}_{PC}} \). Thus
\[
\mathcal{V}_{i_C, \hat{v}_{PC}} = [(\mathcal{V}^u(\mathcal{G}_{PC}); i_C, \hat{v}_{PC}) \oplus \mathcal{V}^v(\mathcal{G}_{PC})] \cap \{i_C = C \hat{v}_{PC}\} \circ \{i_C, \hat{v}_{PC}\}.
\]
Next,
\[
(i_L, i_{PL}) \in \mathcal{V}^i(\mathcal{G}_{LP_L}); \quad (v_L, \hat{v}_{PL}) \in \mathcal{V}^v(\mathcal{G}_{LP_L}); \quad v_L = L_iL. \]
Let us denote the restriction of the solution space of these constraints to \( \{i_L, i_{PL} \} \) by \( \mathcal{V}_{i_L, i_{PL}} \). Thus
\[
\mathcal{V}_{i_L, i_{PL}} = [(\mathcal{V}^i(\mathcal{G}_{LP_L}); i_L, i_{PL}) \oplus \mathcal{V}^v(\mathcal{G}_{LP_L})] \cap \{v_L = L_iL\} \circ \{i_L, i_{PL}\}.
\]
We then have
\[
\mathcal{V}_{WP}^2 = \mathcal{V}_{i_C, \hat{v}_{PC}} \oplus \mathcal{V}_{i_L, i_{PL}}.
\]
From the construction of \( \mathcal{V}_{WP}^1, \mathcal{V}_{WP}^2 \), it is clear that
\[
\mathcal{V}_{WP}^1 \circ \mathcal{V}_{WP}^2 \equiv \mathcal{V}_{WP}^2 \circ \mathcal{V}_{WP}^1 \equiv \mathcal{V}_{WP}.
\]
From the properties of the multiport decomposition, it follows that
\[
\mathcal{V}_{WP}^1 \circ \mathcal{V}_{WP}^2 = \mathcal{V}_{WP}^2 \circ \mathcal{V}_{WP}^1 = \mathcal{V}_{WP}^1 \times \mathcal{V}_{WP}^2 = \mathcal{V}_{WP} \times \mathcal{V}_{WP} = \mathcal{V}_{WP} \times \mathcal{V}_{WP} = \mathcal{V}_{WP}.
\]
From the construction of \( \mathcal{V}_{WP}^2 \), it follows that
\[
\mathcal{V}_{WP}^2 \circ \mathcal{V}_{WP}^2 = \mathcal{V}_{WP}^2 \circ \mathcal{V}_{WP}^2 = \mathcal{V}_{WP}^2 \times \mathcal{V}_{WP}^2 = \mathcal{V}_{WP}^2 \times \mathcal{V}_{WP}^2 = \mathcal{V}_{WP}^2.
\]
By Theorem 2 it follows that
\[
\mathcal{V}_{WP}^2 = (\mathcal{V}_{WP}^1 \oplus \mathcal{V}_{WP}^2) = (\mathcal{V}_{WP}^1 \oplus \mathcal{V}_{WP}^2).
\]
Note that, in general, \( \mathcal{V}_{WP}^2 \subseteq \mathcal{V}_{WP}^1 \). Indeed knowing \( \hat{P} \) variables we can uniquely fix \( \hat{W} \) variables if the \( C, L \) matrices are symmetric positive definite, while knowing \( P \) variables we cannot uniquely fix \( W \) variables if there are capacitor cutsets and inductor loops in the original circuit.

**Remark 16.** Let \( \mathcal{V}_{WP} \equiv \mathcal{V}_{WP} \equiv (0_M \oplus F_M) \), \( \mathcal{V}_{WP} \equiv \mathcal{V}_{WP} \equiv (0_M \oplus F_M) \). Let us examine the emulator pair \( \{\mathcal{V}_{WP}, \mathcal{V}_{WP}\} \) - linked through \( \{\mathcal{V}_{WP}, \mathcal{V}_{WP}\} \). When the port decomposition is minimal, in the three multiports, the ports \( P_C, P_L, P'_L \) will not contain cutsets or circuits. The generic situation for the static multiport, when \( P_C, P_L \) are thus, is to have a unique solution for arbitrary values of \( v_{P_C}, v_{P_L} \).

If in addition, \( C, L \) matrices are symmetric positive definite, it is easy to show that if \( \hat{P} = 0 \), we must have \( p = 0 \). This means \( \mathcal{V}_{WP} \times \mathcal{V}_{WP} = 0_{WP} \), and equivalently, that \( \mathcal{V}_{WP} \) possesses no zero eigenvalue. However, in the present example, it is clear that \( \mathcal{V}_{WP} \times \mathcal{W} \neq 0_{WP} \). This happens because of the presence of capacitor cutsets and inductor loops. (Pick \( v_{C3} = 0 \) and \( v_{C1}, v_{C2} \) consistently, pick \( i_{L1}, i_{L2}, i_{L3} \) so that they constitute a circulating current within the inductor loop. The rest of the circuit will not be affected.) This is an instance where the minimal annihilating polynomial \( p(s) \) for \( \mathcal{V}_{WP} \), which has a constant term, does not annihilate \( \mathcal{V}_{WP} \). But on the other hand, as it should follow from Theorem 74, the polynomial \( sp(s) \) annihilates both \( \mathcal{V}_{WP} \) and \( \mathcal{V}_{WP} \).
Appendix F. Implicit construction of adjoint and its emulator

**Example 83. Building the adjoint implicitly for a network based dynamical system**

We have seen in Examples 67 and 82 that in order to study the network \( \mathcal{N} \) one can use an emulator constructed implicitly through a multiport decomposition. We first build the adjoint network \( \mathcal{N}^\text{ad} \) and then show that the (multiport decomposition based) emulator of the adjoint can be built by constructing adjoints of the multiport decomposition of \( \mathcal{N} \). We have, however, simplified the description so that the adjoint has negative resistors and capacitors requiring less changes of sign when replacing variables of the primal by the corresponding ones in the adjoint.

The primal \( \mathcal{N} \) (or rather its solution space \( \mathcal{V}^{\text{sol}}(\mathcal{N}) \)), shown in Figure E.5, is a GDSA (generalized dynamical system with additional variables) with the variables

\[
v_C, i_L, i_C, v_L, v_C, i_R, u_i, u_w, y_i, y_v, v_{ui}, v_{uw}, y_{ui}, y_{uv}.
\]

Of these the dynamical variables are \( v_C, i_L, \dot{v}_C, i_C, \dot{i}_L \) and the manifest variables are \( y_i, y_v \). The additional variables are \( i_C, v_L, i_R, v_{ui}, v_{uw}, y_{ui}, y_{uv} \). For greater readability, we will make this total set of variables, the index set.

Let \( G \) be the graph of the network. Let the device characteristic constraints of the network be

\[
\begin{align*}
  v_C = C \dot{v}_C; & \\
  v_L = L \dot{i}_L; & \\
  v_R = R \dot{r}_R; & \\
  y_i = 0; & \\
  y_v = 0; & \\
  v_{ui} \text{ free}, & \\
  v_{uw} \text{ free},
\end{align*}
\]

where the matrices \( C, L, R \) are symmetric positive definite. The original GDS \( \mathcal{V}_{W\hat{W}M_M \hat{M}_p} \) corresponding to \( \mathcal{N} \) has the index set \( \{v_C, i_L, \dot{v}_C, i_C, \dot{i}_L, u_i, u_w, y_i, y_v\} \). We have, as we saw before,

\[
\mathcal{V}_{W\hat{W}M_M \hat{M}_p} = [(\mathcal{V}^{\text{top}}(\mathcal{N}) \leftrightarrow \{v_R = Ri_R \} \oplus 0_{v_R,i_R} \oplus F_{v_{wi},i_{wi}})] \bigcap (\{i_C = C \dot{v}_C\} \oplus \{v_L = L \dot{i}_L\}) \leftrightarrow F_{i_C v_L},
\]

where we denote

\[
\mathcal{V}^i(G) \oplus \mathcal{V}^i(G) \oplus \mathcal{V}^{\text{top}}_{v_C i_L} \text{ by } \mathcal{V}^{\text{top}}(\mathcal{N}).
\]

So

\[
\mathcal{L}_{W\hat{W}M_M \hat{M}_p}^{i_C v_L} = [(\mathcal{V}^i(G) \oplus \mathcal{V}^i(G) \oplus \mathcal{V}^{\text{top}}_{v_C i_L} \oplus \mathcal{V}^{\text{top}}_{v_C i_L}) \leftrightarrow \{v_R = Ri_R \} \oplus 0_{v_R,i_R} \oplus F_{v_{wi},i_{wi}}] + (\{i_C = C \dot{v}_C\} \oplus \{v_L = L \dot{i}_L\}) \leftrightarrow 0_{i_C v_L}
\]

Next we make the following changes of variables: replace \( v \) by \( -\psi \), \( i \) by \( -\psi \), \( v_C \) by \( q_C \), \( i_L \) by \( \psi \). We also make use of \( (\mathcal{V}^i(G))^{\perp} = \mathcal{V}^i(G) \); \( (\mathcal{V}^i(G))^{\perp} = \mathcal{V}^i(G) \). So the above expression reduces to

\[
[(\mathcal{V}^i(G))^{\perp} \oplus (\mathcal{V}^i(G))^{\perp} \oplus (\mathcal{V}^{\text{top}}_{v_C i_L})^{\perp} \oplus (\mathcal{V}^{\text{top}}_{v_C i_L})^{\perp} \leftrightarrow \{v_R = Ri_R \} \oplus 0_{v_R,i_R} \oplus F_{v_{wi},i_{wi}} \oplus 0_{v_{wi},i_{wi}} + (\{C \dot{v}_C = q_C\} \oplus \{L \dot{i}_L = \psi\})]
\]

\[
\leftrightarrow 0_{v_C i_L}.
\]

We remind the reader that \( \mathcal{V}^{\text{top}}_{v_C} = \mathcal{V}^v(G \circ E_C), \quad \mathcal{V}^{\text{top}}_{i_L} = \mathcal{V}^i(G \times E_L) \) so that

\[
(\mathcal{V}^{\text{top}}_{v_C})^{\perp} = (\mathcal{V}^v(G \circ E_C))_{q_C}, \quad (\mathcal{V}^{\text{top}}_{i_L})^{\perp} = (\mathcal{V}^i(G \times E_L))_{\psi_L}.
\]

We will denote \( \mathcal{V}^v(G \circ E_C)_{q_C} \) by \( \mathcal{V}^{\text{top}}_{q_C} \) and \( \mathcal{V}^i(G \times E_L)_{\psi_L} \) by \( \mathcal{V}^{\text{top}}_{\psi_L} \).
Since \((\mathcal{V}_{ABC} + \mathcal{V}_{BC}) \times AC = (\mathcal{V}_{ABC} \cap \mathcal{V}_{-BC}) \circ AC\), the above expression reduces to
\[
\left((\mathcal{V}^\dagger(\mathcal{G})) \oplus (\mathcal{V}^\dagger(\mathcal{G})) \circ \mathcal{V}^\text{top} \oplus \mathcal{V}^\text{top} \right) \overset{\mathcal{F}_{v',v''} = 0}{\overrightarrow{\mathcal{F}_{v',v''}}} = \bigcap \left\{ -Cv_C = q_C \bigcap \{ -Li_L = \psi_L \} \right\}
\]
Next change the names of the edges \(yi, yv, ui, uv\) respectively to \(u'v, u''v, y''v, y'i\) respectively so that the expression reduces to
\[
\left((\mathcal{V}^\dagger(\mathcal{G})) \oplus (\mathcal{V}^\dagger(\mathcal{G})) \circ \mathcal{V}^\text{top} \oplus \mathcal{V}^\text{top} \right) \overset{\mathcal{F}_{v',v''} = 0}{\overrightarrow{\mathcal{F}_{v',v''}}} = \bigcap \left\{ -Cv_C = q_C \bigcap \{ -Li_L = \psi_L \} \right\}
\]
This space is on the variables (which we also treat as index set) \(\mathcal{V}^\dagger, v''\mathcal{L}, q_C, u''v, u''i, y''v, y''i\). We rename \(\mathcal{V}^\dagger\) as \(q_C, v''\mathcal{L}\) and rename \(-y''v, -y''i\) as \(y'v, y'i\) (which can be done by reversing the arrows of \(y''v, y''i\)), and rename
\[
v''\mathcal{C}, v''\mathcal{L}, v''v, v''i, y''v, y''i, v''u, v''u, v''y, v''y, v''v', v''i', \text{ respectively as}
\]
\[
\mathcal{V}'\mathcal{C}, \mathcal{V}'\mathcal{L}, \mathcal{V}'v, \mathcal{V}'i, \mathcal{V}'y, \mathcal{V}'i', \mathcal{V}'u, \mathcal{V}'u, \mathcal{V}'y, \mathcal{V}'y', \mathcal{V}'v', \mathcal{V}'i', \mathcal{V}'u', \mathcal{V}'u', \mathcal{V}'y', \mathcal{V}'y',
\]
Let us call the graph obtained from \(\mathcal{G}\) by reversing the arrows of the edges corresponding to \(y''v, y''i\), the graph \(\mathcal{G}'\). This results in the (final!) expression
\[
\left((\mathcal{V}^\dagger(\mathcal{G})) \oplus (\mathcal{V}^\dagger(\mathcal{G})) \circ \mathcal{V}^\text{top} \oplus \mathcal{V}^\text{top} \right) \overset{\mathcal{F}_{v',v''} = 0}{\overrightarrow{\mathcal{F}_{v',v''}}} = \bigcap \left\{ -Cv_C = q_C \bigcap \{ -Li_L = \psi_L \} \right\}
\]
The above constraints are those corresponding to the adjoint network shown in Figure F.6. Note that the constraints on the initial conditions on \(q_C\) are according to the space \(\mathcal{V}^\text{top}\) which is the current space \(\mathcal{V}^\dagger(\mathcal{G} \circ \mathcal{E}_C)\) and those on \(\psi_L\) are according to the space \(\mathcal{V}^\text{top}\) which is the voltage space \(\mathcal{V}^\dagger(\mathcal{G} \times \mathcal{E}_L)\), whereas in the original network the initial conditions on \(q_C\) are according to the voltage space \(\mathcal{V}^\dagger(\mathcal{G} \circ \mathcal{E}_C)\) and those on \(i_L\) are according to the current space \(\mathcal{V}^\dagger(\mathcal{G} \times \mathcal{E}_L)\).

The resulting space corresponding to the above final expression is
\[
(\mathcal{V}^\dagger_{W,\mathcal{W},M_a,M'_a}) - W, \mathcal{W}, -M'_a = \mathcal{V}^\text{a}_{W,\mathcal{W},M_a,M'_a}
\]
Here \(W' = \{q_C, \psi_L\}, W' = \{q_C, \psi_L\}, M_a = \{u'v, u'i\}, M'_a = \{y'i, y''v\}.

Building the emulator implicitly for the adjoint

To build the emulator \(\mathcal{V}^\text{a}_{P,\mathcal{P},M_a,M'_a}\) of \(\mathcal{V}^\text{a}_{W,\mathcal{W},M_a,M'_a}\) we could start with the latter and build its emulator, or equivalently, build the emulator \(\mathcal{V}^\text{a}_{P,\mathcal{P},M_a,M'_a}\) for the primal and then construct the adjoint of the primal emulator. We will follow the latter procedure. We have
\[
\mathcal{V}^\text{a}_{P,\mathcal{P},M_a,M'_a} \equiv (\mathcal{V}^\dagger_{P,\mathcal{P},M_a,M'_a}) - P, \mathcal{P}, -M'_a = \mathcal{V}^\text{top}(\mathcal{G}')
\]
The primal emulator is given to us in an implicit form in terms of the multiport decomposition. We will build its adjoint also implicitly. We begin with the expression for \(\mathcal{V}^\text{a}_{P,\mathcal{P},M_a,M'_a}\) in terms of the multiport decomposition, rearranging terms and expanding \(\mathcal{V}^\text{top}(\mathcal{G}')\) for each occurrence of \(\mathcal{G}'\):
\[
\mathcal{V}^\text{a}_{P,\mathcal{P},M_a,M'_a}
\]
Figure F.6: The adjoint network with port decomposition into capacitor inductor and static multiports
\[ = (V_{i_{PC}, i_{PL}} \oplus V_{\text{stat}} \oplus V_{v_{PL}, i_{PL}}) \leftrightarrow (V'(G_{PC}, P'_C) \oplus V'(G_{PL}, P'_L)). \]

We remind the reader that
\[ V_{i_{PC}, i_{PL}} = [(V'(G_{PC}C))_{i_{PL}} \oplus V'(G_{PC})] \leftrightarrow \{ i_{C} = C \hat{v}_{C} \}, \]
\[ V_{v_{PL}, i_{PL}} = [(V'(G_{PL}))_{i_{PL}} \oplus V'(G_{PL})] \leftrightarrow \{ v_{L} = L \hat{v}_{L} \}, \]
\[ V_{\text{stat}} = (V'(G_{PC}, P'_C, R, u, v, y, y, y)) \oplus V'(G_{PL}, P'_L, R, u, v, y, y, y) \leftrightarrow \{ \{ v_{R} = R \hat{v}_{R} \} \oplus 0, v_{uv}, i_{uv}, v_{yu}, i_{yu}, i_{y} \}, \]

index set for \( V_{\text{stat}} \) is \( \{ v_{PC}, i_{PC}, v_{PL}, i_{PL}, v_{yu}, i_{uv}, v_{yu}, i_{yu}, i_{y} \} \),

\[ P \equiv \{ v_{PC}, i_{PL} \}, \; \hat{P} \equiv \{ v_{PC}, i_{PL} \}, \; M_u \equiv \{ u, v \}, \; M_y \equiv \{ y, v, y \}. \]

\[ (V_P, \hat{P}, M_u, M_y) \]
\[ = (V_{i_{PC}, i_{PL}}) \oplus (V_{v_{PL}, i_{PL}}) \oplus (V'(G_{PC}, P'_C) \oplus V'(G_{PC}, P'_C)) \]

We will now expand each of these terms and change the variables as follows:

\[ v, i, \hat{v}_{C}, i_{PL}, i_{PL}, \] respectively to \( -i', -v', q_{C}, q_{PC}, \psi_{PL}, \psi_{PL}, \)

\[ i_{C}, i_{C}, i_{PL}, \] respectively to \( \hat{q}_{C}, \hat{q}_{PC}, \hat{v}_{L}, \hat{v}_{L}, \phi_{PL}, \phi_{PL}, \]

\[ u, u, y, v \] respectively to \( -y'v, -y'i, u'v, u'i. \]

We have,
\[ V_{i_{PC}, i_{PL}} \rightarrow v_{PC}, q_{PC} \]
\[ = (V'(G_{PC}))_{v_{PC}, q_{PC}} \oplus (V'(G_{PC}))_{-v_{C}, -v_{PC}} \leftrightarrow \{ -C_{ic} = \hat{v}_{C} - v_{C}, q_{C} = q_{C} \}. \]

Therefore,
\[ (V_{i_{PC}, i_{PL}})_{v_{PC}, q_{PC}} = (V'(G_{PC}))_{v_{PC}, q_{PC}} \oplus (V'(G_{PC}))_{v_{PC}, q_{PC}} \leftrightarrow \{ -C_{ic} = \hat{v}_{C} - v_{C}, q_{C} = q_{C} \}. \]

So, denoting \( (V_{i_{PC}, i_{PL}})_{v_{PC}, q_{PC}} \) by \( V_{v_{PC}, q_{PC}} \),
\[ V_{v_{PC}, q_{PC}} = (V'(G_{PC}))_{v_{PC}, q_{PC}} \oplus (V'(G_{PC}))_{v_{PC}, q_{PC}} \leftrightarrow \{ -C_{ic} = \hat{v}_{C} - v_{C}, q_{C} = q_{C} \}. \]

Proceeding analogously and denoting
\[ (V_{v_{PC}, q_{PC}})_{v_{PC}, q_{PC}} \]
we get
\[ V_{v_{PL}, v_{PL}} \equiv (V'(G_{PL}))_{v_{PL}, v_{PL}} \oplus (V'(G_{PL}))_{v_{PL}, v_{PL}} \leftrightarrow \{ L \hat{v}_{L} = \psi_{L} \}. \]

Similarly in the case of \( V_{\text{stat}} \), denoting
\[ V_{\text{stat}} = (V'(G_{PC}, P'_C) \oplus V'(G_{PL}, P'_L)) \]
(we have replaced \( v_{PC}, i_{PC}, v_{PL}, i_{PL}, v_{yu}, i_{uv}, v_{yu} \) respectively by \( -i'v_{PC}, -v'i_{PC}, -i'P'_C, -v'i_{PL}, -i'v_{yu}, -v'i_{uv}, -v'i_{yu}, -i'v_{yu}, -v'i_{yu} \), and the graph
\[ G_{PC, P'_C, R, u, v, y, y, y, y} \]
by \( G_{\text{stat}} \))
we get

\[ \mathcal{V}_{\hat{P}_C, \hat{P}_L}^{\hat{\nu}, \nu, \mu, \mu', \mu''} = (\mathcal{V}(\mathcal{G}_{stat}))_{\hat{P}_C, \hat{P}_L}^{\hat{\nu}, \nu, \mu, \mu', \mu''} + (\mathcal{V}(\mathcal{G}_{stat}))_{\hat{P}_C, \hat{P}_L}^{\nu', \nu, \mu, \mu', \mu''} \]

\[ \leftrightarrow \left( \left\{ -R^\nu = v^\nu R \right\} \oplus 0_{v^\nu u^\nu + v^\nu u^\nu} \oplus \mathcal{F}_{v^\nu u^\nu v^\nu u^\nu} \right). \]

This space is on the variables \( \nu, \nu', \mu, \mu', \mu'' \) with the arrows \( G, G' \), respectively, with the arrows \( \hat{P}_C, \hat{P}_L \), \( R, y', y'', u', u'' \), and reverse the arrows of the branches \( y', y'' \) and \( u', u'' \). This causes the required sign change - \( u'v \) becoming \( -y'y' \) and \( u'v \) becoming \( -y'y'' \).

Thus the graph \( G_{stat}^{\hat{P}_C, \hat{P}_L, R, u, v, y, y, y, u, v, u, v} \) is modified to \( G_{stat} \) on the set of branches \( P_C, P_L, R, y', y'', u', u'' \), respectively, with the arrows \( y, y' \) reversed in \( u', u'' \).

The resulting space is on the variables \( \nu, \nu', \mu, \mu', \mu'' \) and will be denoted by \( \mathcal{V}_{\nu, \nu', \mu, \mu', \mu''}^{stat} \). We therefore have

\[ \mathcal{V}_{\nu, \nu', \mu, \mu', \mu''}^{stat} = (\mathcal{V}(\mathcal{G}_{stat}))_{\nu, \nu', \mu, \mu', \mu''} + (\mathcal{V}(\mathcal{G}_{stat}))_{\nu, \nu', \mu, \mu', \mu''} \]

\[ \leftrightarrow \left( \left\{ -R^\nu = v^\nu R \right\} \oplus 0_{v^\nu u^\nu + v^\nu u^\nu} \oplus \mathcal{F}_{v^\nu u^\nu v^\nu u^\nu} \right). \]

Thus

\[ \mathcal{V}_{\nu, \nu', \mu, \mu', \mu''}^{stat} = \mathcal{V}_{\nu, \nu', \mu, \mu', \mu''}^{stat} \leftrightarrow \mathcal{V}_{\nu, \nu', \mu, \mu', \mu''}^{stat} \]

\[ \mathcal{V}_{\nu, \nu', \mu, \mu', \mu''}^{stat} \]

Here

\[ P' = \{ q_{P_C}, \psi_{P_L} \}, \hat{P}' = \{ \hat{q}_{P_C}, \hat{\psi}_{P_L} \}, M'_y = \{ v'_{y, v}, v''_{y, v} \}, M'_y = \{ v'_{y, v}, v''_{y, v} \}. \]

The multipart decomposition corresponding to the emulator of the adjoint which is also the adjoint of the emulator of the original dynamical system is shown in Figure F.6.

Next let us consider the linking between the adjoint dynamical system \( \mathcal{V}_{\nu, \nu', \mu, \mu', \mu''}^{stat} \) and its emulator

\[ \mathcal{V}_{\nu, \nu', \mu, \mu', \mu''}^{stat}. \] We have by Theorem 70

\[ \mathcal{V}^0_{\hat{W}, \hat{P}'} = ((\mathcal{V}^0_{\hat{W}, \hat{P}'})^\top)_{\hat{W}, \hat{P}'}. \]

\[ = ((\mathcal{V}^0_{\hat{W}, \hat{P}'})^\top)_{\hat{W}, \hat{P}'} \oplus (\mathcal{V}^0_{\hat{W}, \hat{P}'})_{\hat{W}, \hat{P}'} \]

\[ = (\mathcal{V}^0_{\hat{W}, \hat{P}'})_{\hat{W}, \hat{P}'} \oplus (\mathcal{V}^0_{\hat{W}, \hat{P}'})_{\hat{W}, \hat{P}'} \]

99
References

[1] V. Belevitch: Classical Network Theory (Holden-Day, San Francisco, 1968).
[2] F. Gantmacher, The Theory of Matrices: Vol. 2, Chelsea publishing company, 1959.
[3] F. L. Lewis, A survey of linear singular systems, Circuits, Systems, and Signal Processing 5 (1) (1986) 3–36.
[4] J. Willems, Paradigms and puzzles in the theory of dynamical systems, IEEE Trans. on Automatic Control 36 (3) (1991) 259–294.
[5] J. W. Polderman, J. C. Willems, Introduction to Mathematical Systems Theory: a Behavioural Approach, Springer-Verlag, 1997.
[6] H. Narayanan, Some applications of an implicit duality theorem to connections of structures of special types including dirac and reciprocal structures, Systems & Control Letters 45 (2) (2002) 87 – 95.
[7] H. Narayanan, A Unified Construction of Adjoint Systems and Networks, Circuit Theory and Applications 14 (1986) 263–276.
[8] H. Narayanan, Submodular Functions and Electrical Networks, Annals of Discrete Mathematics, vol. 54, North Holland, Amsterdam, 1992.
[9] H. Narayanan, Submodular Functions and Electrical Networks, Open 2nd edition, http://www.ee.iith.ac.in/~hn/, 2009.
[10] H. Narayanan, On the Duality between Controllability and Observability in Behavioural Systems Theory, Proc. International Conference on Communications Control and Signal Processing, CCSP 2000, Bangalore, July 25-July 28, 2000, 183–186.
[11] H. Narayanan, Matroids representable over Modules, Electrical Network Topology and Behavioural Systems Theory, Research report of the EE Dept., IIT Bombay, May 2000.
[12] H. Narayanan, H. Priyadarshan, A subspace approach to linear dynamical systems, Linear Algebra and its Applications 438 (2013) 3576–3599.
[13] G. Kron, Tensor Analysis of Networks, J. Wiley, New York, 1939.
[14] G. Kron, Diakoptics - Piecewise Solution of Large Scale Systems, McDonald, London, 1963.
[15] Siva Theja, H. Narayanan, On the notion of generalized minor in topological network theory and matroids, Linear Algebra and its Applications 458 (2014) 1–46.
[16] H. L. Trentelman, A. A. Stoorvogel, M. L. J. Hautus, Control Theory for Linear Systems, Springer-Verlag, London, 2001.
[17] W. M. Wonham, Linear Systems Theory: A Geometric Approach, Springer-Verlag, New York, USA, 1978.
[18] A. J. van der Schaft, J. M. Schumacher, An introduction to hybrid dynamical systems, Vol. 251 of Lecture Notes in Control and Information Sciences, Springer, 2000.
[19] A. van der Schaft, Equivalence of hybrid dynamical systems, in: International Symposium on Mathematical Theory of Networks and Systems, Vol. 16, Leuven: Belgium, 2004.
[20] G. Basile, G. Marro, Controlled and conditioned invariant subspaces in linear system theory, Journal of Optimization Theory and Applications 3 (5) (1969) 306–315.
[21] W. Wonham, A. Morse, Decoupling and pole assignment in linear multivariable systems: a geometric approach, SIAM J. Control 8 (1) (1970) 1–18.
[22] B. Molinari, Extended controllability and observability for linear systems, IEEE Trans. on Automatic Control 21 (1) (1976) 136 – 137.
[23] Molinari, B., A strong controllability and observability in linear multivariable control”, IEEE Trans. on Automatic Control 21 (5) (1976) 761 – 764.
[24] B. Molinari, Zeros of the system matrix, IEEE Trans. on Automatic Control 21 (5) (1976) 795 – 797.
[25] A. S. Morse, Structural invariants of linear multivariable systems”, SIAM Journal on Control 11 (3) (1973) 446–465. URL http://link.aip.org/link/?SJC/11/446/1
[26] G. Basile, G. Marro, Controlled and Conditioned Invariants in Linear System Theory, Prentice-Hall, Englewood Cliffs, N.J., 1992.
[27] G. Pappas, Bisimilar linear systems, Automatica 39 (12) (2003) 2035–2047.
[28] A. Van Der Schaft, Bisimulation of dynamical systems, Hybrid Systems: Computation and Control (2004) 291–294.
[29] A. Van der Schaft, Equivalence of dynamical systems by bisimulation, Automatic Control, IEEE Transactions on 49 (12) (2004) 2160–2172.
[30] H. Narayanan, On the decomposition of vector spaces, Linear Algebra and its Applications 76 (1986) 61–98.
[31] H. Narayanan, Topological transformations of electrical networks, International Journal of Circuit Theory and Applications 15 (3) (1987) 211–233.
[32] G. D. Forney, M. D. Trott, The Dynamics of Group Codes : Dual Abelian Group Codes and Systems, IEEE Transactions on Information Theory 50 (11) (2004) 1–30.
[33] R.E.Kalman, Mathematical description of linear dynamical systems, SIAM J. Control 1 (1963) 152–192.