Interference Channel with Intermittent Feedback

Can Karakus
UCLA, Los Angeles, USA
karakus@ucla.edu

I-Hsiang Wang
EPFL, Lausanne, Switzerland
i-hsiang.wang@epfl.ch

Suhas Diggavi
UCLA, Los Angeles, USA
suhasdiggavi@ucla.edu

Abstract—We investigate how to exploit intermittent feedback for interference management. Focusing on the two-user linear deterministic interference channel, we completely characterize the capacity region. We find that the characterization only depends on the forward channel parameters and the marginal probability distribution of each feedback link. The scheme we propose makes use of block Markov encoding and quantize-map-and-forward at the transmitters, and backward decoding at the receivers. Matching outer bounds are derived based on novel genie-aided techniques. As a consequence, the perfect-feedback capacity can be achieved once the two feedback links are active with large enough probabilities.

I. INTRODUCTION

The simplest information theoretic model for studying interference is the two-user Gaussian interference channel (IC). It is shown that feedback can provide an unbounded gain in capacity for two-user Gaussian interference channels [1], in contrast to the bounded power gain provided by feedback in point-to-point, multiple access, and broadcast channels. This has been demonstrated when the feedback is unlimited, perfect, and free of cost in [1]. This motivates the natural question of whether feedback can provide similar gains under more practical feedback models.

In this work, we investigate how to exploit intermittent feedback for managing interference. Such intermittent feedback could occur in several situations. For example, one could use a side-channel such as WiFi for feedback; in this case since the WiFi channel is best effort, dropped packets might cause intermittent feedback. In other situations, control mechanisms in higher network layers could cause the feedback resource to be available intermittently. We study the effect of intermittent feedback using the linear deterministic model [2] of the two-user Gaussian IC. For the feedback links, Bernoulli processes \( \{S_1[t]\} \) and \( \{S_2[t]\} \) control the presence of feedback for user 1 and 2, respectively. Although the joint distribution \( p(S_1[t], S_2[t]) \) can be time-variant in general, for simplicity, we focus on the case where it is i.i.d. over time. Our results suggest that extension to the time-variant case is straightforward. We assume that the receivers are passive: they simply feedback their received signals back to the transmitters without coding. In other words, each transmitter receives from feedback a punctured version of the received sequence at its own receiver with unit delay. We focus on the passive feedback model as the intermittence of feedback is motivated by the availability of feedback resources (either through use of best-effort WiFi for feedback or through feedback resource scheduling). Therefore, it might be that the time-variant statistics of the intermittent feedback are not a priori available at the receiver and therefore precluding active coding. Moreover, the availability of the feedback resource may not be known ahead of transmission, therefore motivating the causal state-information at the transmitter.

In the literature, other practical feedback models are also investigated. Rate-limited feedback for the two-user IC was considered in [3], where the feedback from the receivers to the transmitters is modeled by two finite-capacity noiseless links. [3] characterized the capacity region of the linear deterministic IC with intermittent feedback. Although the joint distribution \( p(S_1[t], S_2[t]) \) can be time-variant in general, for simplicity, we focus on the case where it is i.i.d. over time. Our results suggest that extension to the time-variant case is straightforward. We assume that the receivers are passive: they simply feedback their received signals back to the transmitters without coding. In other words, each transmitter receives from feedback a punctured version of the received sequence at its own receiver with unit delay. We focus on the passive feedback model as the intermittence of feedback is motivated by the availability of feedback resources (either through use of best-effort WiFi for feedback or through feedback resource scheduling). Therefore, it might be that the time-variant statistics of the intermittent feedback are not a priori available at the receiver and therefore precluding active coding. Moreover, the availability of the feedback resource may not be known ahead of transmission, therefore motivating the causal state-information at the transmitter.

In contrast to our model, the receivers in [3] can actively code the feedback signals. On the other hand, [4] considered feedback with additive white Gaussian noise but the receivers are passive, that is, they cannot encode the feedback signal. The capacity region is characterized for the symmetric linear deterministic IC [4]. When feedback shares the same resource (spectrum) with the forward channel and hence is not free of cost, it is shown in [5] through the study on two-way interference channels that feedback can provide net capacity gain even taking the feedback cost into account.

Our main contribution is the characterization of the capacity region of the linear deterministic IC with intermittent feedback, which only depends on the forward channel parameters and the marginal distribution of \( S_1 \) and \( S_2 \), not on the joint distribution. Interestingly, the full benefit obtained via perfect feedback can be achieved once the “on” probabilities of the two feedback links are large enough. Our result in the linear deterministic model also suggests that in the Gaussian case, the capacity gain from intermittent feedback remains unbounded.

We propose a block Markov encoding scheme to exploit intermittent feedback at the transmitters along with backward decoding at the receivers. For linear deterministic IC, the high-level idea is to exploit the additional information provided by intermittent feedback to refine the interfered signals or to relay additional information. Due to the passive nature of the receivers, not all the information contained in the feedback is useful, in sharp contrast to the case of rate-limited feedback [3]. Therefore, at the transmitters instead of the (partial) decode-and-forward scheme employed in [1] and [3], we use quantize-map-and-forward [2] to extract useful information.
from the intermittent feedback and send it to the receivers.

We also develop novel outer bounds that match the achievable rate region. Remarkably, in our proof we do not make use of the assumption that the states are known to the transmitters causally, which proves that even when the realization of \((S_1^N, S_2^N)\) is known non-causally, the capacity region remains the same.

The rest of this paper is organized as follows. We formulate the problem in Section [III] and present our main result in Section [III] Achievability and converse are proved in Section [IV] and Section [V] respectively. An extended version of this paper that includes the proof details can be found in [2].

II. PROBLEM FORMULATION

![Diagram](image-url)

In this paper, we focus on the linear deterministic model [2] of the two-user Gaussian IC. An illustration is given in Fig. [1].

The transmitted signal at transmitter \(i\) (Tx\(i\)) is \(X_i \in \mathbb{F}_2^n\), for \(i = 1, 2\). Here \(\mathbb{F}_2\) denotes the binary field \(\{0, 1\}\). The received signals at receiver 1 (Rx1) and receiver 2 (Rx2) are

\[
Y_1[t] = H_{11}X_1[t] + H_{12}X_2[t],
Y_2[t] = H_{22}X_2[t] + H_{21}X_1[t],
\]

where additions are modulo-two component-wise. Channel transfer matrices \(H_{ij} := S^{q-1}n_{ij}\) for \((i, j) \in \{1, 2\}^2\), where \(q = \max \{n_{11}, n_{12}, n_{21}, n_{22}\}\), and \(S \in \mathbb{F}_2^{n \times q}\) is the shift matrix \([I_{q-1} 0]\), where 0 is the zero vector in \(\mathbb{F}_2^{q-1}\) and \(I_{q-1}\) is the identity matrix in \(\mathbb{F}_2^{(q-1) \times (q-1)}\). The transmit signal from Tx\(i\) at time \(t\), \(X_i[t]\), is determined by the message \(W_i, \bar{Y}_i[1 : t - 1], (S_1[1 : t - 1], S_2[1 : t - 1])\), where \(\bar{Y}_i[t] := S_i[t]Y_i[t]\). Let us use the notation \(A \equiv B\) to denote that \(A\) is a function of \(B\). Then, \(X_i[t] \equiv (W_i, \bar{Y}_i[1 : t - 1], S_1[1 : t - 1], S_2[1 : t - 1])\).

The feedback state sequences have the joint distribution

\[
p(S_1^N, S_2^N) = \prod_{t=1}^N p(S_1[t], S_2[t]).
\]

Let \(q_{i2j} := p(S_1 = i_1, S_2 = i_2)\), \(i_1, i_2 \in \{0, 1\}\). Marginally, \(S_i[t] \sim \text{Ber}(p_i)\), i.i.d. over time. In other words, the feedback signal is erased with probability \(1 - p_i\), where

\[
p_1 := q_{10} + q_{11}, p_2 := q_{01} + q_{11}.
\]

For notational convenience, denote \(\bar{S} := (S_1, S_2)\) and \(V_i := H_{21}X_1, V_2 := H_{12}X_2, \bar{V}_1 := S_2V_1, \bar{V}_2 := S_1V_2\).

III. MAIN RESULT

The main result is summarized in the following theorem.

**Theorem 3.1 (Capacity Region):** The capacity region \(C\) for the linear deterministic IC with intermittent feedback is the collection of non-negative \((R_1, R_2)\) satisfying [1] – [6].

Note that the rate region defined by [1] – [3] is the perfect-feedback capacity region [1]. Therefore, once \(p_1\) and \(p_2\) are so large that [3] – [5] become inactive, the perfect-feedback performance can be attained even under intermittent feedback.

The thresholds on \(p_1, p_2\) will depend on \(\{q_{i2j}, i, j \in \{1, 2\}\}\).

As an example, let us focus on the symmetric capacity \(C_{\text{sym}}\) under the symmetric setting \(n_{11} = n_{22} = n, n_{12} = n_{21} = \alpha n, p_1 = p_2 = p\): \(C_{\text{sym}} := \max\{R_1, R_2\} \in C\)

\[
\frac{C_{\text{sym}}}{n} = \left\{ \begin{array}{ll}
\min \{1 - \alpha/2, 1 - (1 - p)\alpha\}, & \alpha \leq 1/2 \\
\min \{1 - \alpha/2, p + (1 - p)\alpha\}, & 1/2 \leq \alpha \leq 1, \\
\alpha/2, & \alpha \geq 1
\end{array} \right.
\]

where the first term in each minimization is the perfect-feedback capacity. Hence, we find the threshold on \(p\) above which perfect-feedback capacity can be achieved, as follows:

\[
p^* = \left\{ \begin{array}{ll}
1/2, & \alpha \leq 1/2 \\
(2 - 3\alpha)/(2 - 2\alpha), & 1/2 \leq \alpha \leq 1, \\
(2\alpha^2)/(2\alpha - 2), & \alpha \geq 1
\end{array} \right.
\]

Note that in the regime \(2/3 \leq \alpha \leq 2\), feedback does not increase the symmetric capacity of IC [1] and hence \(p^* = 0\), that is, we do not need feedback at all. Also note that \(p^* \leq 1/2\) for all \(\alpha\). Therefore, once \(p \geq 1/2\), perfect-feedback capacity can be achieved with intermittent feedback regardless of channel parameters \(\alpha\) and \(n\). Note that the larger \(p\) is, the larger the amount of additional information about the past reception can be obtained through intermittent feedback at the transmitters. If the amount of such information is larger than a threshold, then sending it to the receivers will limit the rate for delivering fresh information. The threshold \(p^*\) represents the maximum limit at which the help of feedback is not neutralized by this effect.

IV. ACHIEVABILITY PROOF

To prove the achievability part of Theorem 3.1 in this section we provide a coding scheme to exploit intermittent feedback in the interference channel. Since the feedback is passive, one cannot code against the erasures in the feedback links. This is the key difference with the active feedback case [3]. In the active feedback case, a block Markov coding scheme based on decode-and-forward at the transmitters is employed, which is a natural extension of that in the perfect feedback case [1]. Instead, we employ a block Markov coding scheme based on quantize-map-and-forward, which can be viewed as a non-trivial extension of the perfect feedback scheme. Below we describe the scheme in detail.
A. High-level Description

For the two-user linear deterministic IC, Han-Kobayashi coding scheme is a natural choice where we split the message into common and private: \( W_i := (W_{ic}, W_{ip}) \) for \( i = 1, 2 \). The total number of blocks to be transmitted is \( B \), and the length of each block is \( N \). For block \( b \in [1 : B] \), the messages \( \{W_i(b), W_{ip}(b)\} \) are independent from the messages of other blocks. In the following we describe the encoding and decoding for a particular block \( b \) for user 1. Operations of user 2 are similar.

In the beginning of block \( b \), from the punctured feedback \( \tilde{Y}_1^N(b-1) \) and the state sequence \( \tilde{S}_1^N(b-1) \), Tx1 generates

\[
\tilde{V}_1^N(b-1) = S_1^N(b-1) \tilde{V}_1^N(b-1),
\]

\[
\tilde{V}_2^N(b-1) = \tilde{Y}_1^N(b-1) - S_1^N(b-1)X_1^N(b-1).
\]

Note that Tx2 can also generate \( \{\tilde{V}_1^N(b-1), \tilde{V}_2^N(b-1)\} \). The high-level idea is to use this common information to cooperatively refine the previously received signals at the receivers and/or relay additional information, as in the perfect feedback case \( \mathbb{I} \). The only difference is that here we do not decode at the transmitters. The reason is that the imperfect feedback may lay additional constraints on the achievable rate if we insist to decode. Decoding partially is not optimal since the realization of erasures in the feedback links is not known beforehand, and if we insist to decode at the transmitters some pre-assigned sub-messages, this could harm the achievable rate of other sub-messages.

Hence, we shall quantize \( \tilde{V}_1^N(b-1) \) and \( \tilde{V}_2^N(b-1) \), and map the quantized outputs to a codeword \( X_1^N(b) \) which contains the helping information for interference refinement or message relaying regarding block \( b - 1 \). On top of it, we further suppose fresh information of block \( b \), the messages \( W_{1c}(b) \) and \( W_{1p}(b) \), to generate the transmit codeword \( X_1^N(b) \).

For decoding, we employ backward decoding. At the end of block \( b \), assuming that quantized version of \( \tilde{V}_1^N(b) \) and \( \tilde{V}_2^N(b) \) has been successfully decoded from the future block \( b+1 \), Rx1 decodes \( W_{1c}(b) \), \( W_{2c}(b) \), and \( W_{1p}(b) \) jointly with the quantized version of \( \tilde{V}_1^N(b-1) \) and \( \tilde{V}_2^N(b-1) \).

In the above scheme, we can see that \( \tilde{V}_1^N(b-1) \) and \( \tilde{V}_2^N(b-1) \) will contain some information of block \( b-2 \), which contains information about block \( b-3 \), and so on. This dependency across blocks hampers a single-letter characterization of the achievable rates, since the mutual information terms obtained will depend on all the signals sent in previous blocks. In order to remove the dependency across more than two blocks, we carry out the following operation before quantizing \( \tilde{V}_1^N(b-1) \) and \( \tilde{V}_2^N(b-1) \): generate

\[
\tilde{V}_1^N(b-1) := \tilde{V}_i^N(b-1) - \tilde{V}_{ie}^N(b-1)
\]

where \( \tilde{V}_i^N(b-1) := S_1^N(b-1)H_{ij}X_j^N(b-1) \) for \( (i, j) = (1, 2), (2, 1) \). The operation is feasible since both \( X_1^N(b-1) \) and \( X_2^N(b-1) \) are generated from shared information \( \tilde{V}_1^N(b-2) \) and \( \tilde{V}_2^N(b-2) \), and hence (by induction) available at both transmitters. In our proposed encoding architecture, the quantization is performed on \( \tilde{V}_1^N(b-1) \) and \( \tilde{V}_2^N(b-1) \). An illustration of the encoding architecture is given in Fig. 2.

![Fig. 2. Block Diagram of Encoder at Tx1](image)

B. Codebook Generation and Detailed Coding Process

We describe the scheme for block \( b \) in detail below.

Codebook Generation and Encoding:

Based on \( p(U_i) \), generate \( 2^{Nt} \) quantization codewords \( U_i^N \) i.i.d. over time, for \( i = 1, 2 \), to quantize \( \tilde{V}_i^N(b-1) \). Let \( q_1(b-1) \) and \( q_2(b-1) \) denote the quantization indices. The quantization is carried out by a joint typicality encoder as in standard source coding. We then choose a symbol-by-symbol map \( x_{1c}(u_{1c}, u_{2c}) \) for mapping \( (U_1^N(q_1(b-1)), U_2^N(q_2(b-1))) \) into \( X_1^N(b) \). This completes the joint-source-channel coding part of the encoder. Note that we shall use the same pair of quantization codebooks at both transmitters.
Superposition encoding is done in a standard way. We base on \( p(X_1, X_2) \) to generate \( 2^{N R_{1p}} \) common codewords \( X_1^N(W_{1p}(b), X_2^N(b)) \) i.i.d. over time. Then based on \( p(X_1, X_2) \), we generate \( 2^{N R_{1p}} \) transmit codewords \( X_1^N(W_{1p}(b), X_2^N(b)) \) i.i.d. over time.

**Decoding:**
At the end of block \( b \), we assume that quantization indices \( \{q_1(b), q_2(b)\} \) have been decoded from block \( b + 1 \). The additional information carried by \( \{U_1^N(q_1(b)), U_2^N(q_2(b))\} \) can be used in conjunction with \( Y_i^N(b) \) to decode \( (W_{1p}(b), W_{1p}(b), q_1(b - 1), q_2(b - 1)) = (i_1, i_2, q_1, q_2) \). We find such a unique \((i_1, i_2, q_1, q_2)\) and some \( W_{2c}(b) = i_2 \) such that

\[
\left( Y_1^N(b), U_1^N(q_1(b)), U_2^N(q_2(b)), U_1^N(q_1), U_2^N(q_2), X_1^N(i_1, q_1, q_2), X_2^N(i_2, q_1, q_2) \right)
\]

for some mapping functions \( \{x_{1e}(u_1, u_2), x_{2e}(u_1, u_2)\} \) and input distribution

\[
p(U_1, U_2) p(U_1', U_2') p(X_1|U_1, U_2^N) p(X_1|U_1') p(X_2|X_2).
\]

Here \( R_i = R_{ip} + R_{ic} \) is the achievable rate for user \( i, i = 1, 2 \).

**D. Rate Region Evaluation**
To achieve the capacity region, we choose the input distribution and the mapping function as follows. For the input distribution, we pick

\[
U_i = V_i := \tilde{V}_i - \tilde{V}_{ic}, \quad U_i, U_i : \text{i.i.d.}
\]

\[
X_{ic} = X_{ic} + \text{Ber}_{1/2}[\text{supp} V_i]
\]

and \( x_{ic}(u_1, u_2) \) is a linear map such that the random linear combinations of all levels of \( u_1 \) and \( u_2 \) is put uniformly at random on all the levels of \( \text{supp} X_i \). The support \( \text{supp} X_i \) and \( \text{supp} V_i \) denote the levels of \( X_i \) and \( V_i \) respectively, and \( \text{Ber}_{1/2}(A) \) denotes a random vector with i.i.d. \( \text{Ber}(1/2) \) random variables on all the levels of \( A \).

With the above choice, we have

\[
r_1 \geq I(U_1; V_1) = H(V_1) = p_2 n_{21}
\]

\[
r_2 \geq I(U_2; V_2) = H(V_2) = p_1 n_{12}
\]

We choose \( r_1 = p_2 n_{21} \) and \( r_2 = p_1 n_{12} \) and obtain the following rate region after eliminating \( r_1, r_2 \) and redundant terms (see Appendix [A] for details):

\[
R_{ip} \leq p_1 := (n_{11} - n_{21})^+
\]

\[
R_{ic} + R_{ip} \leq s_1 := \max \{(n_{11} - n_{21})^+, n_{12}\}
\]

\[
+ p_1 \min \{(n_{11} - n_{21})^+, n_{12}\}
\]

\[
R_1 \leq t_1 := n_{11} + p_2 (n_{21} - n_{11})^+
\]

\[
R_{ic} + R_{ip} \leq s_2 := \max \{(n_{22} - n_{12})^+, n_{21}\}
\]

\[
+ p_2 \min \{(n_{22} - n_{12})^+, n_{21}\}
\]

\[
R_2 \leq t_2 := n_{22} + p_1 (n_{12} - n_{22})^+
\]

\[
R_{ic} + R_{ip} \leq n_{22} \leq \text{max}(n_{22}, n_{21})
\]

After Fourier Motzkin elimination, \( (R_1, R_2) \) satisfying

\[
R_1 \leq \min \{t_1, n_{11}, p_1 + s_2\}
\]

\[
R_2 \leq \min \{t_2, n_{22}, p_2 + s_1\}
\]

\[
R_1 + R_2 \leq \min \{p_1 + n_{12}, p_2 + n_{21}\}
\]

\[
R_1 + R_2 \leq s_1 + s_2
\]

\[
2R_1 + 2R_2 \leq s_1 + s_2
\]
\[ R_1 + 2R_2 \leq p_2 + n_2 + s_1 \]
is achievable, which coincides with the capacity region \[ \text{I} - \text{G} \] except for the terms \( p_1 + s_2 \) and \( p_2 + s_1 \) in the individual rate constraints. We complete the achievability proof by the following fact.

Fact 4.1: \( t_1 \leq p_1 + s_2, \ t_2 \leq p_2 + s_1 \).

Proof: See Appendix 3.

V. CONVERSE PROOF

The converse proof is a novel modification of those in the perfect feedback case \[ \text{I} \] and the rate-limited feedback case \[ \text{B} \]. Due to space constraints, below we outline the main proof and leave the details of the four useful facts to Appendix 3.

Fact 5.1: For \((i,j) = (1,2), (2,1)\),
\[ X_i[t] \overset{\triangle}{=} \left( W_i, \tilde{V}_j^{t-1} \right) \overset{\triangle}{=} \left( W_i, \tilde{V}_j^{t-1} \right). \]

Fact 5.2: For \((i,j) = (1,2), (2,1)\),
\[ H(Y_i^n|W_i, S_i^n) = H\left( Y_i^n, \tilde{V}_j^n | W_i, S_i^n \right). \]

Fact 5.3: For \((i,j) = (1,2), (2,1)\),
\[ I(W_i; Y_i^n, \tilde{V}_j^n | S_i^n) = Np_jn_i. \]

Fact 5.4: For \((i,j) = (1,2), (2,1)\),
\[ N^{-1}H(Y_i^n | Y_i^n, \tilde{V}_j^n, S_i^n) \leq p_i(n_{ii} - n_{ji})^+ + (1 - p_i)max\{n_{ij}, (n_{ii} - n_{ji})^+\}, \]
\[ N^{-1}H(Y_i^n | Y_i^n, \tilde{V}_j^n, S_i^n) \leq p_j(n_{ji} - n_{j})^+ + (1 - p_j)n_{ji}. \]

A. Bounds on \( R_1 \) and \( R_2 \)

We focus on the bounds on \( R_1 \). The first term in the minimization is a cut-set bound and the proof is in \[ \text{I} \].

The second term is obtained as follows:

\[ N (R_1 - \epsilon_N) \leq I(W_1; Y_1^n | S_i^n) \leq I(W_1; Y_2^n | V_2^n, \tilde{V}_1^n, S_i^n) + I(W_1; V_2^n, \tilde{V}_1^n | S_i^n) \leq H(Y_1^n | V_2^n, \tilde{V}_1^n, S_i^n) + Np_{2n_21} \leq N \{ p_2(n_{11} - n_{21})^+ + (1 - p_2)n_{11} + p_2n_{21} \} = N \{ n_{11} + p_2(n_{21} - n_{11})^+ \}. \]

Here \( \epsilon_N \rightarrow 0 \) as \( N \rightarrow \infty \). (a) is due to Fact 5.3. Hence, \[ \text{I} \] holds. Similarly, so does \[ \text{G} \].

B. Bounds on \( R_1 + R_2 \)

The first bound \[ \text{I} \] is the bound when feedback is perfect, and the proof can be found in \[ \text{I} \]. The second bound \[ \text{B} \] is non-trivial and is proved as follows. If \((R_1, R_2)\) is achievable,

\[ N (R_1 + R_2 - \epsilon_N) \leq I(W_1; Y_1^n | S_i^n) + I(W_2; Y_2^n | S_i^n) \]
\[ = H(Y_1^n | S_i^n) - H(V_1^n, \tilde{V}_2^n | W_2, S_i^n) + H(Y_2^n | S_i^n) \leq H(Y_1^n | V_1^n, \tilde{V}_2^n, S_i^n) + I(W_2; V_1^n, \tilde{V}_2^n | S_i^n) \]
\[ + H(Y_2^n | V_2^n, \tilde{V}_1^n, S_i^n) + I(W_1; V_2^n, \tilde{V}_1^n | S_i^n) \]
\[ \leq N \{ \text{Right-Hand Side of } \text{B} \}. \]

Here \( \epsilon_N \rightarrow 0 \) as \( N \rightarrow \infty \). (a) is due to Fact 5.2. (b) is due to Fact 5.3 and 5.4. Hence \[ \text{B} \] holds.

C. Bounds on \( 2R_1 + R_2 \) and \( R_1 + 2R_2 \)

We focus on the bound in \[ \text{I} \]. If \((R_1, R_2)\) is achievable,

\[ N (2R_1 + R_2 - \epsilon_N) \leq I(W_1; Y_1^n | S_i^n) + I(W_2; Y_2^n | S_i^n) + I(W_1; Y_1^n | S_i^n) \]
\[ \leq H(Y_1^n | S_i^n) - H(V_2^n, \tilde{V}_1^n | W_1, S_i^n) + H(Y_2^n | S_i^n) \]
\[ - H(V_1^n, \tilde{V}_2^n | W_2, S_i^n) + I(W_1; Y_1^n | W_2, S_i^n) \]
\[ = H(Y_1^n | S_i^n) - H(V_2^n, \tilde{V}_1^n | S_i^n) + H(Y_2^n | S_i^n) \]
\[ + I(W_1; V_2^n, \tilde{V}_1^n | S_i^n) - H(V_1^n, \tilde{V}_2^n | W_2, S_i^n) \]
\[ + H(Y_1^n | W_2, S_i^n) \leq H(Y_1^n | S_i^n) + H(Y_2^n | V_2^n, \tilde{V}_1^n, S_i^n) \]
\[ + I(W_1; V_2^n, \tilde{V}_1^n | S_i^n) + H(Y_1^n | V_2^n, \tilde{V}_1^n, W_2, S_i^n) \]
\[ \leq N \{ max\{n_{11}, n_{12}\} + max\{n_{21}, (n_{22} - n_{12})^+\} \}
\[ + (n_{11} - n_{21})^+ + p_2 \min\{n_{21}, (n_{22} - n_{12})^+\} \}. \]

Here \( \epsilon_N \rightarrow 0 \) as \( N \rightarrow \infty \). (a) is due to Fact 5.2. (b) is due to Fact 5.3 and 5.4. and

\[ H(Y_1^n | V_1^n, \tilde{V}_2^n, W_2, S_i^n) \]
\[ = H(Y_1^n | V_1^n, \tilde{V}_2^n, W_2, S_i^n, X_2^n) \]
\[ = H(H_{11}X_1^n | V_1^n, \tilde{V}_2^n, W_2, S_i^n, X_2^n) \leq H(H_{11}X_1^n | V_1^n) \]
\[ \leq N (n_{11} - n_{21})^+ \]
due to Fact 5.1. Hence, \[ \text{B} \] holds.

Remark 5.1: In the above proof, we do not make use of the assumption that the realization of the feedback states \((S_i^n, S_i^n)\) is known to the transmitters causally. In other words, even if we allow some genie to provide the whole state sequence \((S_i^n, S_i^n)\) to all four terminals beforehand, the capacity region remains the same.

VI. ACKNOWLEDGEMENTS

The work of C. Karakus and S. Diggavi was supported in part by NSF award 1136174 and MURI award AFOSR FA9550-09-064. The work of I.-H. Wang was supported by EU project CONECT FP7-ICT-2009-257616.
Appendix A

Achievable Rate Evaluation

Let us evaluate the rate constraints corresponding to the decoding at Rx1:

\[
R_{1_p} \leq I (X_1; Y_1, U_1, U_2 | X_{1c}, X_{2c}, U'_1, U'_2) = H(Y_1, U_1, U_2 | X_{1c}, X_{2c}, U'_1, U'_2) \\
= H(X_1 | X_{1c}, X_{1e}, U'_1, U'_2)
\]

\[
R_{2c} + R_{1p} \leq I (X_{2c}, X_1; Y_1, U_1, U_2 | X_{1c}, U'_1, U'_2) = H(Y_1, U_1, U_2 | X_{1c}, U'_1, U'_2) \\
= H(Y_1, U_2 | X_{1c}, X_{1e}, X_{2c}, U'_1, U'_2) \\
= \max \left\{ (n_{11} - n_{21})^+, n_{12} \right\} + p_1 \min \left\{ (n_{11} - n_{21})^+, n_{12} \right\}
\]

\[
R_1 \leq I (X_1; Y_1, U_1, U_2 | X_{2c}, U'_1, U'_2) = H(Y_1, U_1, U_2 | X_{2c}, U'_1, U'_2) \\
= H(X_1 | X_{2c}, X_{1e}, U'_1, U'_2)
\]

\[
R_{2c} + R_1 \leq I (X_{2c}, X_1; Y_1, U_1, U_2 | U'_1, U'_2) = H(Y_1, U_1, U_2 | U'_1, U'_2) \\
= H(Y_1, U_1, U_2 | X_{1e}, X_{2c}, U'_1, U'_2) \\
= \left\{ \begin{array}{l}
q_{00} \max(n_{11}, n_{12}) \\
+ q_{01} \max(n_{11}, n_{12} + n_{21}) \\
+ q_{10} n_{11} + n_{12} \\
+ q_{11} (\max(n_{11}, n_{21}) + n_{12}) \\
\end{array} \right.
\]

\[
r_1 + r_2 + R_{2c} + R_1 \leq I (U'_1, U'_2, X_{2c}, X_1; Y_1, U_1, U_2) = H(Y_1, U_1, U_2) \\
= \max(\max_{n_{11}, n_{12}}, p_2 n_{21} + p_1 n_{12})
\]

Plug in \( r_1 = p_2 n_{21}, r_2 = p_1 n_{12} \) we obtain

\[
R_{1p} \leq (n_{11} - n_{21})^+ \\
R_{2c} + R_{1p} \leq \max \left\{ (n_{11} - n_{21})^+, n_{12} \right\} + p_1 \min \left\{ (n_{11} - n_{21})^+, n_{12} \right\} \\
R_1 \leq n_{11} + p_2 (n_{21} - n_{11})^+
\]

\[
R_{2c} + R_1 \leq \left\{ \begin{array}{l}
q_{00} \max(n_{11}, n_{12}) \\
+ q_{01} \max(n_{11}, n_{12} + n_{21}) \\
+ q_{10} n_{11} + n_{12} \\
+ q_{11} (\max(n_{11}, n_{21}) + n_{12}) \\
\end{array} \right.
\]

Appendix B

Proof of Fact 4.1

Note that both \( t_1 \) and \( p_1 + s_2 \) are affine in \( p_2 \). Plugging in \( p_2 = 0 \), we see that

\[
t_1 = n_{11} \\
\leq p_1 + s_2 = \max \left\{ (n_{22} - n_{12})^+, (n_{11} - n_{21})^+, n_{21}, n_{11} \right\}
\]

Plugging in \( p_2 = 1 \), we see that

\[
t_1 = \max(n_{11}, n_{21}) \\
\leq p_1 + s_2 = (n_{11} - n_{21})^+ + n_{21} + (n_{22} - n_{12})^+
\]

Hence, \( t_1 \leq p_1 + s_2 \) for all \( p_2 \). Similarly, \( t_2 \leq p_2 + s_1 \).

Appendix C

Proof of Fact 5.1-5.3

A. Proof of Fact 5.1

By definition, we have

\[
X_1[t] \triangleq \left( W_1, Y_1^{t-1}, T^{t-1} \right) \triangleq \left( W_1, X_1^{t-1}, T^{t-1}, S^{t-1} \right)
\]

Similarly, the other functional relationship holds.

B. Proof of Fact 5.2

Let us focus on the first equality.

\[
H \left( Y_1^N | W_1, S^N \right) = \sum_{t=1}^{N} H \left( Y_1[t] | W_1, S^N, Y_1^{t-1} \right)
\]

\[
= \sum_{t=1}^{N} H \left( Y_1[t] | W_1, S^N, Y_1^{t-1}, X_1^t \right)
\]

\[
= \sum_{t=1}^{N} H \left( V_2[t] | W_1, S^N, V_2^{t-1}, X_1^t \right)
\]

where (a) is by definition, (b) is due to Fact 5.1. The other holds similarly.
C. Proof of Fact 5.3

Below we shall prove the inequality for \((i, j) = (1, 2)\). The second one follows in a similar way.

\[
I \left( W_1; V_2^N, \tilde{V}_1^N | S^N \right) \\
\leq I \left( W_1; W_2, \tilde{V}_1^N | S^N \right) = I \left( W_1; \tilde{V}_1^N | S^N , W_2 \right) \\
= H \left( \tilde{V}_1^N | S^N, W_2 \right) - H \left( \tilde{V}_1^N | S_2^N \right) \\
\leq E_{S_2^N} \left[ \sum_{i=1}^{N} H \left( s_2^N | V_1^N \right) \right] \right| S_2^N = s_2^N \\
\leq E_{S_2^N} \left[ \sum_{i=1}^{N} H \left( s_2^N | V_1^N \right) \right] \right| S_2^N = s_2^N \\
= Np_{2n_{21}}.
\]

Here \( N_1(\cdot) \) denotes the number of 1's in the sequence. (a) follows because \( V_2^N \leq \left( W_2, \tilde{V}_1^N, S^N \right) \).

D. Proof of Fact 5.4

We focus on \((i, j) = (1, 2)\) below. For the first inequality,

\[
H \left( Y_1^N | V_1^N, \tilde{V}_2^N, S^N \right) \leq H \left( Y_1^N | V_1^N, \tilde{V}_2^N, S_1^N \right) \\
= E_{S_1^N} \left[ H \left( Y_1^N | V_1^N, (s_1V_2)^N \right) \right| S_1^N = s_1^N \\
\leq E_{S_2^N} \left[ \sum_{i=1}^{N} H \left( Y_1^N | V_1^N, s_1V_2^N \right) \right| S_1^N = s_1^N \\
\leq E_{S_2^N} \left[ N_1 \left( s_1^N \right) \left( n_{11} - n_{21} \right) + N \left( s_1^N \right) \max \left\{ n_{12}, (n_{11} - n_{21}) \right\} \right| S_1^N = s_1^N \\
= Np_1 \left( n_{11} - n_{21} \right) + N \left( 1 - p_1 \right) \max \left\{ n_{12}, (n_{11} - n_{21}) \right\}.
\]

Here \( N_1(\cdot) \) and \( N_0(\cdot) \) denote the number of 1's and 0's respectively in the sequence.

For the second inequality,

\[
H \left( Y_1^N | V_2^N, \tilde{V}_1^N, S^N \right) \leq H \left( Y_1^N | V_2^N, \tilde{V}_1^N, S_2^N \right) \\
= E_{S_2^N} \left[ H \left( Y_1^N | V_2^N, s_2V_1^N \right) \right| S_2^N = s_2^N \\
\leq E_{S_2^N} \left[ \sum_{i=1}^{N} H \left( Y_1^N | V_2^N, s_2V_1^N \right) \right| S_2^N = s_2^N \\
\leq E_{S_2^N} \left[ N_1 \left( s_2^N \right) \left( n_{11} - n_{21} \right) + N \left( s_2^N \right) n_{11} \right| S_2^N = s_2^N \\
= Np_2 \left( n_{11} - n_{21} \right) + N \left( 1 - p_2 \right) n_{11}.
\]

The other cases when \((i, j) = (2, 1)\) follow similarly.