Numerical Studies for Solving Fractional Integro-Differential Equations by using Least Squares Method and Bernstein Polynomials

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Abstract

In this paper, two numerical methods for solving fractional integro-differential equations are proposed. The fractional derivative is considered in the Caputo sense. The proposed methods are least squares method aid of Bernstein polynomials function as the basis. The proposed method reduces this type of equation into systems to the solution of system of linear algebraic equations. To demonstrate the accuracy and applicability of the presented methods some test examples are provided. Numerical results show that this approach is easy to implement and accurate when applied to fractional integro-differential equations. We show that the method is effective and has high convergency rate.

Keywords: Bernstein polynomials; Numerical studies; Convergency rate; Gaussian elimination method

Introduction

The fractional calculus has a long history from 30 September 1695, when the derivative of order \( \frac{1}{2} \) has been described by Leibniz [1-4]. The theory of derivatives and integrals of non-integer order goes back to Leibniz, Liouville, Grünwald, Letnikov and Riemann. There are many interesting books about fractional calculus and fractional differential equations [5-6]. The use of fractional differentiation for the mathematical modeling of real world physical problems has been wide spread in recent years, e.g., the modeling of earthquake, the fluid dynamic traffic model with fractional derivatives, measurement of viscoelastic material properties, etc. Derivatives of non-integer order are defined in different ways, e.g., Riemann–Liouville, Grünwald–Letnikov, Caputo and Generalized Functions Approach [4]. In this work we focus attention on Caputo’s definition which turns out to be more useful in real-life applications since it is coupled with initial conditions having a clear physical meaning.

Furthermore the use of numerical method for solving fractional integro-differential equations cannot be over emphasized, for, it is of great importance to Mathematician, Engineers and Physicists. In recent years, much attention has been given for the solutions of fractional differential and integro-differential equations [7]. Proposed an efficient method for solving systems of fractional integro-differential equations using adomian decomposition method (ADM). Munkhammar JD proposed a numerical solution of fractional integro-differential equations by collocation method [8]. He JH used the Adomian Decomposition Method to solve fractional Integro-differential equations. ADM requires the construction of Adomian polynomials which are somehow difficult to obtain [9]. Homotopy Perturbation and Homotopy Analysis methods were applied to solve initial value problems of fractional order by Lanczos C [10]. These authors decomposed the given problems into basically two parts using linear and nonlinear operators. The basic assumption was that the solutions of the problem could be expressed as series of polynomials. The truncated parts of these polynomials are then solved to get the approximate solutions of the problems [11]. Employed application of the fractional differential transform method (FDTM) to fractional-order integro-differential equations with nonlocal boundary conditions [11] also gives some application of nonlinear fractional differential equations and their approximation [12]. Presented numerical approximation of fractional integro-differential equations by an Iterative Decomposition Method (IDM). In the work, approximate solution of each problem is presented as a rapidly convergent series of easily computable terms [13] applied least square method for treating nonlinear fourth order integro-differential equations [14,16-18] applied an efficient method for solving fractional differential equations using Bernstein polynomials [15] applied least squares method and shifted Chebyshev polynomial for solving fractional integro-differential equations. In his work he used shifted Chebyshev polynomial of the first kind as basis function.

In this work, using the idea of Momani and Qaralleh [15], we proposed an alternative method, called Standard and perturbed least square methods by Bernstein polynomial as basis function [19-22].

In this work, we are concerned with the numerical solution of the following linear fractional integro-differential equation by standard and perturbed least square methods using Bernstein polynomial as basis function

\[
D^\alpha u(x) = f(x) + \int_0^x k(x,t) u(t) dt, \quad 0 \leq \alpha \leq 1, \quad a \leq x \leq b,
\]

With the following supplementary conditions:

\[
\begin{align*}
&u(0) = \beta, \\
&0 \leq \alpha \leq n, \quad n \in \mathbb{N}
\end{align*}
\]

Where \( D^\alpha u(x) \) indicates the \( \alpha \)th Caputo fractional derivative of \( u(x), f(x) \), \( K(x,t) \) are given smooth functions, \( x \) and \( t \) are real variables varying on \([0,1]) and \( u(x) \) is the unknown function to be determined.

Some Relevant Basic Definitions

Definition 1

A real function \( x, \alpha > 0 \) [Mohammed (2004)], is said to be in the space \( C_\alpha \) if there

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**Defination 2**
A function \((x_0, x_0)\) is said to be in the space \(C_i\), \(m \in N\cup\{0\}\), if \(f^{(m)}\). 

**Defination 3**
The left sided Riemann–Liouville fractional integrator of the order \(\mu \geq 0\) of a function \(f \in C_{x_0}\), \(\mu \geq -1\), is defined as
\[
j^\alpha f(x) = \frac{1}{\Gamma(\alpha)} \int_{x_0}^{x} (x-t)^{\alpha-1} f(t) \, dt, \alpha > 0, x > 0, \tag{3}
\]
\[
j^0 f(x) = f(x) \tag{4}
\]

**Defination 4**
A standard integro-differential equation is an equation in which the unknown function \(y(x)\) appears under an integral sign and contain ordinary derivatives \(\partial^m y(x)\) as well. A standard integro-differential equation is of the form:
\[
y^{(m)}(x) = f(x) + \lambda \int_{a}^{b} K(x,t) y(t) \, dt \tag{7}
\]
Integral equations and integro-differential equations are classified into distinct types according to limits of integration and the kernel \(K(x,t)\) are as prescribed before.

1. If the limits of the integration are fixed, then the integral equation is called a Fredholm integral equation and is of the form:
\[
y(x) = f(x) + \lambda \int_{a}^{b} K(x,t) y(t) \, dt \tag{8}
\]
2. If at least one limits is a variable, then the equation is called a Volterra integral equation and is given as:
\[
y(x) = f(x) + \lambda \int_{a}^{b} K(x,t) y(t) \, dt \tag{9}
\]

**Defination 7**
Bernstein basis polynomials: A Bernstein polynomial [8] of degree \(n\) is defined by
\[
B_{n}(x) = \binom{n}{i} (1-x)^{n-i} x^i = 0, 1, ..., n, \tag{10}
\]
where,
\[
\binom{n}{i} = \frac{n!}{i!(n-i)!} \tag{11}
\]
Often, for mathematical convenience, we see \(B_{n}(x)=0\) if \(0\) or \(i>n\).

**Defination 8**
Bernstein polynomials: A linear combination Bernstein basis polynomials
\[
u_i(x) = \sum_{i=0}^{n} a_i B_{n}(x) \tag{12}
\]
is the Bernstein polynomial of degree \(n\) where \(a_i = 0, 1, 2, \ldots\) are constants.

**Defination 9**
Shifted Chebyshev polynomial of the first kind denoted by \(T_n(x)\) is denoted by the following [11]:
\[
T_n(x) = \cos \left( n \cos^{-1} (2x-1) \right); n \geq 0 \tag{13}
\]
and the recurrence relation is given by
\[
T_n+1(x) = (2x - 1)T_n(x) - T_{n-1}(x); n = 1, 2, \ldots \tag{14}
\]
With the initial condition
\[
T_0(x) = 1, \quad T_1(x) = 2x - 1 \tag{15}
\]

**Defination 10**
In this work, we defined absolute error as:
\[
\text{Absolute Error} = \left| \hat{y}(x) - y(x) \right|, 0 \leq x \leq 1 \tag{16}
\]

**Demonstration of the Proposed Methods**
In this section, we demonstrated the two proposed methods mentioned above.
**Standard Least Squares Method (SLM)**

The standard least square method with Bernstein polynomials as basis function is applied to find the numerical solution of fractional integro-differential equation given in equation (1). This method is based on approximating the unknown function \( u(x) \) by assuming an approximation solution of the form defined in equation (12).

Thus, substituting equation (12) into equation (1), we obtained

\[
D^\tau \left( \sum_{i=0}^{n} a_i B_{\tau i}(x) \right) - \left( f(x) + \frac{1}{6} \left( k(x,t) \sum_{i=0}^{n} a_i B_{\tau i}(t) \right) dt \right) = 0 \quad (17)
\]

Hence, the residual equation is obtained as

\[
R(a_i,a_{i-1},\ldots,a_0) = D^\tau \left( \sum_{i=0}^{n} a_i B_{\tau i}(x) \right) - \left( f(x) + \frac{1}{6} \left( k(x,t) \sum_{i=0}^{n} a_i B_{\tau i}(t) \right) dt \right)
\]

Thus, we minimized equation (18) as

\[
S(a_i,a_{i-1},\ldots,a_0) = \int_0^1 R(a_i,a_{i-1},\ldots,a_0)^2 w(x) dx
\]

Where \( w(x) \) is the positive weight function defined in the interval, \([a,b]\), thus, equation (19) is given

\[
S(a_i,a_{i-1},\ldots,a_0) = \int_0^1 \left( D^\tau \left( \sum_{i=0}^{n} a_i B_{\tau i}(x) \right) - \left( f(x) + \frac{1}{6} \left( k(x,t) \sum_{i=0}^{n} a_i B_{\tau i}(t) \right) dt \right) \right)^2 w(x) dx
\]

We obtained values of \( a(i=\tau 0) \) by finding the minimum value of \( S \) as:

\[
\frac{\partial S}{\partial a_i} = 0, i = 0,1,\ldots,n
\]

Applying equation (21) into equation (20) for various values of \( i(i=\tau 0) \);

We obtained \((n+1)\) algebraic system of equations in \((n+1)\) unknown constants \( a_i\). The systems of equations are then solved by Gaussian elimination method. The results of the unknown constants obtained are then substituted back into the approximate solution given by equation (12) to get the required approximation for the appropriate order.

**Perturbed Least Squares Method (PLM)**

The basic idea of the method as conceived by [10], is the substitution of equation (12) into a slightly perturbed equation (1) to obtain

\[
D^\tau u(x) = f(x) + \frac{1}{6} \left( k(x,t) \sum_{i=0}^{n} a_i B_{\tau i}(t) \right) dt + H_{\tau i}(x), \quad \alpha \leq x, t \leq 1,
\]

Where, \( H_{\tau i}(x) = \tau_i T_{\tau i}(x) \)

And \( T_{\tau i}(x) \) is the shifted Chebyshev polynomials defined in equation (13) and \( \tau_i \) is a free tau parameter to be determined along with \( a(i=\tau 0) \). Equations (12) and (23) are substituted into equation (22) to get

\[
D^\tau \left( \sum_{i=0}^{n} a_i B_{\tau i}(x) \right) - \left( f(x) + \frac{1}{6} \left( k(x,t) \sum_{i=0}^{n} a_i B_{\tau i}(t) \right) dt \right) = 0 \quad (24)
\]

Hence the residual equation is defined as

\[
R(a_i,a_{i-1},\ldots,a_0) = D^\tau \left( \sum_{i=0}^{n} a_i B_{\tau i}(x) \right) - \left( f(x) + \frac{1}{6} \left( k(x,t) \sum_{i=0}^{n} a_i B_{\tau i}(t) \right) dt \right) - \tau_i T_{\tau i}(x)
\]

Thus we minimized equation (24) by denoting

\[
S(a_i,a_{i-1},\ldots,a_0,\tau_i) = \int_0^1 R(a_i,a_{i-1},\ldots,a_0)^2 w(x) dx
\]

Where all the parameters involved are mentioned above, thus, equation (24) is given

\[
S(a_0,a_1,\ldots,a_n) = \int_0^1 \left( \sum_{i=0}^{n} \sum_{j=0}^{n} a_i \left( \frac{\partial^\tau}{\partial \tau^i} \right) \sum_{j=0}^{n} a_j \left( \frac{\partial^\tau}{\partial \tau^j} \right) - \left( f(x) + \frac{1}{6} \left( k(x,t) \sum_{i=0}^{n} a_i \left( \frac{\partial^\tau}{\partial \tau^i} \right) \right) dt \right)^2 w(x) dx
\]

We obtained the values of \( a(i=\tau 0) \) and \( \tau_i \) by finding the minimum value of \( S \) as:

\[
\frac{\partial S}{\partial a_i} = 0, i = 0,1,\ldots,n
\]

and

\[
\frac{\partial S}{\partial \tau_i} = 0
\]

Applying equation (29) and (28) into equation (27) for various values of \( i(i=\tau 0) \);

To obtain \((n+2)\) algebraic equations in \((n+2)\) unknown constants \( a_0\). The systems of equations are then solved by Gaussian elimination method. The results of the unknown constants obtained and then substituted back into the approximate solution given by equation (12) to get the required approximation.

**Remark 1:** The convergence and stability of the method were discussed in Taiwo (1991) while the existence and uniqueness of solution have been proved by Adeniyi (1991).

**Numerical Examples**

In this section, we demonstrated the proposed methods discussed above on some examples.

**Example 1:** Consider the following fractional Integro-differential equation:

\[
D^\frac{\tau}{\alpha} u(x) = \left( \frac{1}{\sqrt{\pi}} \right) \int_0^x \frac{w(t)}{\sqrt{x-t}} dt + \frac{x^\beta}{12} \quad 0 \leq x \leq 1,
\]

Subject to \( u(0)=0 \) with exact solution \( B(x)=x^\beta \) \( \beta \in (-1,0) \)

We have solved the above problem for \( n=3 \) in order to compare the results obtained with the exact solution. Also graphical representations of the result are presented.

For case \( n=3 \),

Thus, the approximate solution given in equation (12) becomes

\[
u_i(x) = \sum_{i=0}^{n} a_i B_{\tau i}(x)
\]

Hence expanding equation (32) further, we have

\[
u_i(x) = a_0 \left( 1 - 2x + 3x^2 \right) + a_1 \left( 3x - 6x^2 + 3x^3 \right) + a_2 \left( 3x^2 - 3x^3 \right) + a_3 x^3
\]

Substituting (33) into (31), we have

\[
D^\frac{\tau}{\alpha} \left( a_0 \left( 1 - 2x + 3x^2 \right) + a_1 \left( 3x - 6x^2 + 3x^3 \right) + a_2 \left( 3x^2 - 3x^3 \right) + a_3 x^3 \right) = \left( \frac{1}{\sqrt{\pi}} \right) \int_0^x \frac{w(t)}{\sqrt{x-t}} dt + \frac{x^\beta}{12}
\]

Applying the Caputo properties on equation (34), we have

\[
\left[ \frac{\left( \frac{\tau}{\alpha} + 1 \right)^2}{\left( \frac{\tau}{\alpha} + 1 \right)^2} \right] a_0 \left( 1 - 2x + 3x^2 \right) + \left[ \frac{\left( \frac{\tau}{\alpha} + 1 \right)^2}{\left( \frac{\tau}{\alpha} + 1 \right)^2} \right] a_1 \left( 3x - 6x^2 + 3x^3 \right) + \left[ \frac{\left( \frac{\tau}{\alpha} + 1 \right)^2}{\left( \frac{\tau}{\alpha} + 1 \right)^2} \right] a_2 \left( 3x^2 - 3x^3 \right) + \left[ \frac{\left( \frac{\tau}{\alpha} + 1 \right)^2}{\left( \frac{\tau}{\alpha} + 1 \right)^2} \right] a_3 x^3
\]

\[
\left[ \frac{\left( \frac{\tau}{\alpha} + 1 \right)^2}{\left( \frac{\tau}{\alpha} + 1 \right)^2} \right] a_0 \left( 1 - 2x + 3x^2 \right) + \left[ \frac{\left( \frac{\tau}{\alpha} + 1 \right)^2}{\left( \frac{\tau}{\alpha} + 1 \right)^2} \right] a_1 \left( 3x - 6x^2 + 3x^3 \right) + \left[ \frac{\left( \frac{\tau}{\alpha} + 1 \right)^2}{\left( \frac{\tau}{\alpha} + 1 \right)^2} \right] a_2 \left( 3x^2 - 3x^3 \right) + \left[ \frac{\left( \frac{\tau}{\alpha} + 1 \right)^2}{\left( \frac{\tau}{\alpha} + 1 \right)^2} \right] a_3 x^3
\]
\[ a_2 = -3.333014828, \]
\[ a_3 = -3.552432041 \times 10^{-6} \]

These values are then substituted into equation (33), after simplifying we have the approximate solution as
\[ u_i(x) = -0.0000348788303 - 0.9997989856x + 0.999798159x^2 + 0.00001808x^3 \]

(48)

Demonstration of Perturbed Least Square Method

Example 1

Consider the following fractional Integro-differential equation:
\[ D^{\delta}_{t, T} u(x) = \left( \frac{8}{3} \right) x^{3/5} - 2x^{2/5} + \frac{1}{12} \int_0^x H_x(t) dt, 0 \leq x \leq 1, \]

(49)

Subject to \( u(0) = 0 \), with exact solution \( u(x) = x^2 - x \)

(50)

Solution

We have solved the problem above for the case \( n = 3 \) with perturbation term \( H(x) \) given in equation (23). Thus, equation (50) becomes
\[ D^{\delta}_{t, T} u(x) = \left( \frac{8}{3} \right) x^{3/5} - 2x^{2/5} + \frac{1}{12} \int_0^x H_x(t) dt + H_1(x), \]

(51)

Where \( H_1(x) = r_1 T_1^m(x) \)

(52)

and \( H_2(x) = r_1 T_2^m(x) = H_2(x) = x \left( 32x^2 - 48x^2 + 18x - 1 \right) \)

(53)

The approximate solution given in equation (12) becomes
\[ u_i(x) = \sum a_i B_i(x) \]

(54)

Hence, expanding equation (54) further, we have
\[ u_i(x) = a_1 \left( 1 - 2x + 3x^2 \right) + a_2 \left( 3x^2 - 3x^3 + 3x^4 \right) + a_3 \left( 3x^2 - 3x^3 \right) + \alpha_1 x^5 \]

(55)

Substituting equations (53) and (55) into equation (51) we have
\[ D^{\delta}_{t, T} u(x) = a_1 \left( 1 - 2x + 3x^2 \right) + a_2 \left( 3x^2 - 3x^3 + 3x^4 \right) + a_3 \left( 3x^2 - 3x^3 \right) + \alpha_1 x^5 \]

\[ + \frac{8}{3} \left[ x^{3/5} - 2x^{2/5} \right] \]

\[ + \frac{1}{12} \int_0^x H_1(t) dt \]

\[ + H_2(x) \]

(56)

Applying the Caputo properties on equation (56) we have
\[ \frac{D^\delta_{t, T} u(x)}{\Gamma(1-\delta)} = -u_1(x) \int_0^x \frac{H_1(t)}{\Gamma(1-\delta)} dt + \frac{D^\delta_{t, T} u(x)}{\Gamma(1-\delta)} + r_1 \left( 32x^2 - 48x^2 + 18x - 1 \right) \]

(57)

Simplifying equation (57), we have
\[ \frac{D^\delta_{t, T} u(x)}{\Gamma(1-\delta)} = -u_1(x) \int_0^x \frac{H_1(t)}{\Gamma(1-\delta)} dt + \frac{D^\delta_{t, T} u(x)}{\Gamma(1-\delta)} - r_1 \left( 32x^2 - 48x^2 + 18x - 1 \right) \]

\[ + \frac{8}{3} \left[ x^{3/5} - 2x^{2/5} \right] \]

\[ + \frac{1}{12} \int_0^x H_1(t) dt \]

(58)

Hence, the residual equation is defined as
\[ R\left( a_0, a_1, a_2 \right) = \]

(59)
These algebraic linear equations are as follows:

\[
\begin{align*}
S(a_0) &= 0.00000345887 \\
S(a_1) &= 0.00001080032 \quad (62) \\
S(a_2) &= -0.00003555247 \quad (63) \\
S(a_3) &= -0.00000345887 \\
\end{align*}
\]

Integrating the equations (62-66) with respect to \( x \) over the interval \([0, 1]\), we have algebraic linear equations in 5 unknown constants. These algebraic linear equations are as follows:

\[
\begin{align*}
1.023551680a_0 + 0.1798737760a_1 + 0.2375240373a_2 + 0.3649803917a_3 + 0.07300583245 \tau_1 &= 0.05409736947 = 0 \quad (67) \\
-0.1798737760a_0 + 0.2368150383a_1 + 0.1014859295a_2 - 0.131040572a_3 - 0.2401096907 \tau_1 + 0.1127425214 &= 0 \quad (68)
\end{align*}
\]

**Tables of Results**

**Numerical Results of Example 1 (Table 1)**

**Examples 2**

Consider the following fractional integro-differential equation:

\[
D^p u(x) = \frac{1}{\Gamma(1-p)} \int_0^x (x-t)^{p-1} u(t) dt, \quad x \in [0, 1] \quad (73)
\]

Subject to \( u(0) = 0 \) with the exact equation \( U(x) = x - x^3 \)

**Numerical results of Example 2 (Table 2)**

**Graphical Representation of the Two Methods (Figures 1-4)**

**Conclusion**

In this paper, least square method with the aid of Bernstein polynomials was successfully deduced for solving fractional integro-differential equations. The numerical results in the tables and graphs show that the present method provides highly accurate numerical solutions for solving these types of equations.
| X  | Exact Solution | Approximate Solution of standard least squares method (SLM) | Approximate solution of perturbed (PLM) | Absolute error of standard least squares method (SLM) | Absolute error of perturbed least squares method (PLM) |
|----|----------------|-------------------------------------------------------------|----------------------------------------|------------------------------------------------------|------------------------------------------------------|
| 0.0| 0.00           | 0.00010284974                                              | 0.00010996755                          | 1.0284E-4                                           | 1.0996E-4                                           |
| 0.1| 0.099          | 0.099063038620                                             | 0.09907034368                          | 6.3036E-5                                           | 0.7034E-5                                           |
| 0.2| 0.192          | 0.19202656970                                             | 0.1920342150                           | 2.5659E-4                                           | 3.3421E-4                                           |
| 0.3| 0.273          | 0.27299313320                                             | 0.27300160370                          | 6.8668E-6                                           | 1.6037E-6                                           |
| 0.4| 0.336          | 0.33696787000                                             | 0.33597729340                          | 3.2130E-5                                           | 2.2706E-5                                           |
| 0.5| 0.375          | 0.3749528320                                              | 0.37496289360                          | 4.7716E-5                                           | 3.7106E-5                                           |
| 0.6| 0.384          | 0.38394878610                                             | 0.38396080680                          | 5.1213E-5                                           | 3.9193E-5                                           |
| 0.7| 0.357          | 0.35695979180                                             | 0.3569743630                           | 4.0208E-5                                           | 2.6563E-5                                           |
| 0.8| 0.288          | 0.28798771360                                             | 0.28800318470                          | 1.2286E-5                                           | 3.1847E-5                                           |
| 0.9| 0.171          | 0.17103496450                                             | 1.71052455200                          | 3.4964E-5                                           | 5.2455E-5                                           |
| 1.0| 0.00           | 0.00010395790                                              | 0.00012365050                          | 1.0395E-5                                           | 1.2365E-4                                           |

Table 2: Numerical results of Example 2.
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