Parametric Study of Factors Influencing Dynamic Behavior of High Speed Spindles

Vignesh Suresh¹, Prabhu Raja V²

¹Bachelor of Engineering in Mechanical Engineering, PSG College of Technology, Coimbatore
²Associate Professor, Dept. of Mechanical Engineering, PSG College of Technology, Coimbatore

Abstract: The performance of a high speed spindle is mainly attributed to the dynamics of spindle system. Hence, it is very significant to simulate the dynamic behavior. Finite element analysis is carried out for a typical high speed spindle by considering various bearing preload and spacing conditions to investigate the stiffness and natural frequency rise of the spindle assembly. The design variable that contributes the most to stiffness and frequency change was found.

Keywords: high speed spindle, finite element analysis, stiffness, natural frequency, design variable;

1. Introduction

The spindle is probably the most critical element [1] in high speed machining, so to maintain maximum productivity and accuracy. Enhancing the efficiency of compact drive motors and improving the accuracy and lifetime of bearings are the main goals of spindle design [2]. Bossman [3] has proposed a model of 32kW spindle. In the present work a finite element model of spindle is developed to study the dynamic effects.

2. Finite Element Model of the High Speed Spindle

A typical high speed spindle of 32 kW, 25,000 rpm meant for end milling is considered for study. Two sets of hybrid angular contact ball bearings are mounted on the spindle in an O arrangement according to the fixed-floating bearings principle, the fixed bearings near the spindle nose and the floating bearings at the rear end of the spindle. High speed spindle system was developed as a beam element using ANSYS software is shown in Fig. 1. The element has 23 sections [5]. The front bearing preload is 890 N whereas the rear bearing preload is 340 N [5]. The corresponding radial and axial stiffness are 3.39E8 N/m and 1.4E8 N/m for front bearings. It is 2.12E8 N/m and 0.87E8 N/m for rear bearings. The natural frequency of the system was found as 921 Hz.

3. Design Variables

a) Rear Bearing Preload – DV1

The rear bearing is initially preloaded with 340N, the maximum preload that can be given by hydraulic devices is 680 N. The corresponding radial and axial stiffness for 680N are 2.6E8 N/m and 1.08E8 N/m.

Figure 1: Finite element model of spindle

Figure 2: Spindle speed vs Stiffness for various values of DV1

A typical high speed spindle of 32 kW, 25,000 rpm meant for end milling is considered for study. Two sets of hybrid angular contact ball bearings are mounted on the spindle in an O arrangement according to the fixed-floating bearings principle, the fixed bearings near the spindle nose and the floating bearings at the rear end of the spindle. High speed spindle system was developed as a beam element using ANSYS software is shown in Fig. 1. The element has 23 sections [5]. The front bearing preload is 890 N whereas the rear bearing preload is 340 N [5]. The corresponding radial and axial stiffness are 3.39E8 N/m and 1.4E8 N/m for front bearings. It is 2.12E8 N/m and 0.87E8 N/m for rear bearings. The natural frequency of the system was found as 921 Hz.

3. Design Variables

a) Rear Bearing Preload – DV1

The rear bearing is initially preloaded with 340N, the maximum preload that can be given by hydraulic devices is 680 N. The corresponding radial and axial stiffness for 680N are 2.6E8 N/m and 1.08E8 N/m.
It is evident from the figures 2 & 3 that the rear bearing preload does not contribute much to the stiffness variation. But the natural frequency varies significantly from 921 Hz to 1000 Hz on varying the front bearing preload from 890 to 3290 N.

b) Front Bearing Spacing – DV2

The maximum span that the bearings can have is 120.8 mm exceeding that will lead to change in diameter of the bearing races in order to suit the spindle diameter. The minimum span that the bearings can have is 18 mm because the width of each bearing is 18 mm.

c) Rear Bearing Spacing – DV3

Similar to DV2, DV3 also has geometry constraints i.e the spacing of rear bearings can be changed only to a certain extent. Beyond which it will demand change in bearing size. From figure 3.2 it is clear that the rear bearings can move only in elements 19, 20, 21. The maximum permissible variation is 85 mm. Modal analysis was done with rear bearing spacing of 85 mm. The result shows that the spindle’s natural frequency has been increased from 921 Hz to 951 Hz on changing the span of rear bearing from 45 mm to 85 mm.

d) Spacing Between Front And Rear Bearing – DV4

This parameter involves altering the distance between front and rear bearings. The front and rear bearings are initially 370 mm apart. It is evident from figure 3.2 that the spacing can be reduced only to 330 mm, more than that it will lead to geometry constraints (for bearing).
The DV4 (spacing between front and rear bearings) has an impact on the stiffness of the spindle system. Figure 8 and 9 indicate that the stiffness gets augmented by $0.3 \times 10^6$ on reducing DV4 from 370 mm to 330 mm.

e) Spacing Between Midspan of Bearings and Cutter

In this case the distance between midline of bearings and end of cutter is reduced from 407 mm to 405 mm. The natural frequency after changing DV5 was found by doing modal analysis.

f) Material of Spindle

The material used is steel (Young’s modulus = $2 \times 10^{11}$ N/m$^2$). The maximum improvement in young’s modulus is $4 \times 10^{11}$ N/m$^2$ (Tungsten). Because material with young’s modulus more than this will have more carbon content. It will lead to more weight. Silicon Carbide has more young’s modulus but carbon content is more.

Thus the figure 12 and 13 clearly show that the material of spindle is the most important factor contributing to stiffness change. On improving the Young’s modulus (twice) the stiffness changes from $8.13 \times 10^6$ N/m to $1.52 \times 10^6$ N/m. The frequency also improves from 921 Hz to 1070 Hz.
g) Spindle Diameter

The spindle diameter has been reduced from 22.25 mm to 15.78 mm. The corresponding variation in frequency was found to be 927 Hz.

It is apparent from figure 14 that diameter of the spindle doesn’t contribute much to the stiffness change i.e the change in stiffness due to change in diameter of the spindle shaft is negligible. The frequency shift is also not significant.

h) Front Bearing Preload

The front bearing is preloaded by hydraulic devices. It is initially given a preload of 890N. The maximum preload that can be given by the hydraulic devices for front bearing is 3290N. The corresponding radial and axial stiffness for 3290 N are 5.22 E8 N/m and 2.22 E8 N/m. The natural frequency improved from 921 Hz to 949 on altering the front bearing preload.

It is evident from figure 16 & 17 that the spindle stiffness variation for various speeds is significant for the two extreme cases of preload i.e 890 N and 3290 N, whereas the natural frequency drops from 972 Hz to 926 Hz for an initial preload of 3290 N when the spindle speed changes from 0 rpm to 25000 rpm.

4. Conclusion

A 32 kW spindle system was selected for study. The natural frequency was found to be 921 Hz. Eight design variables were chosen and their effect on the spindle’s stiffness and natural frequency was found by FEM approach. The cumulative effect of all the design variables resulted in a frequency enhancement from 921 Hz to 1300 Hz.

References

[1] A. Zahedi, M.R. Movahhedy: Thermo-mechanical modeling of high speed spindles, Scientia Iranica B (2012) 19 (2), pp.282–293.
[2] E. Uhlmanna, J. Hu: Thermal modelling of a high speed motor spindle, Institute of MachineTools and Factory Management, TU Berlin,10587, Germany, Procedia CIRP 1(2012), pp.313 –318.
[3] Bernd Bossmanns, Jay F. Tu: A power flow model for high speed motorized spindles-heatgeneration characterization, ASME J. Mfg. Science and Engg, Vol. 123, pp. 494-505(2001).
[4] Xu Mina, Jiang Shuyuna, CaiYingb: An improved thermal model for machine tool bearings, International Journal of Machine Tools & Manufacture 47 (2007), pp.53–62.
[5] Chi-Wei Lin, Jay F. Tu, Joe Kamman “An integrated thermo-mechanical-dynamic model to characterize motorized machine tool spindles during very high speed rotation”(2003), pp.1035-1050.
[6] Chi-Wei Lin, Jay F. Tu “Model-Based Design of Motorized Spindle Systems to Improve Dynamic Performance at High Speeds”(2007), vol .9, No. 2, pp.94-108.