Probing Motion of Fast Radio Burst Sources by Timing Strongly Lensed Repeater

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Abstract

Given the possible repetitive nature of fast radio bursts (FRBs), their cosmological origin, and their high occurrence, detection of strongly lensed sources due to intervening galaxy lenses is possible with forthcoming radio surveys. We show that if multiple images of a repeating source are resolved with VLBI, using a method independent of lens modeling, accurate timing could reveal non-uniform motion, either physical or apparent, of the emission spot. This can probe the physical nature of FRBs and their surrounding environments, constraining scenarios including orbital motion around a stellar companion if FRBs require a compact star in a special system, and jet-medium interactions for which the location of the emission spot may randomly vary. The high timing precision possible for FRBs (~ms) compared with the typical time delays between images in galaxy lensing (~10days) enables the measurement of tiny fractional changes in the delays (~10−9) and hence the detection of time-delay variations induced by relative motions between the source, the lens, and the Earth. We show that uniform cosmic peculiar velocities only cause the delay time to drift linearly, and that the effect from the Earth’s orbital motion can be accurately subtracted, thus enabling a search for non-trivial source motion. For a timing accuracy of ~1 ms and a repetition rate (of detected bursts) of ~0.05 per day of a single FRB source, non-uniform displacement >0.1–1 au of the emission spot perpendicular to the line of sight is detectable if repetitions are seen over a period of hundreds of days.

Key words: gravitational lensing: strong – radio continuum: general

1. Introduction

Fast radio bursts (FRBs) are bright transients discovered at ~GHz frequencies with millisecond durations (Lorimer et al. 2007; Thornton et al. 2013). Their dispersion measures (DMs), which measure the free electron column density along the line of sight toward the source DM = ∫ n_e dl, exceed the contribution from the Galactic interstellar medium (ISM) by typically an order of magnitude. If intergalactic medium (IGM) accounts for most of the DM excess, these bursts must have travelled across cosmological distances. Recently the astrophysical nature of these radio transients has become one of the most intriguing mysteries in astronomy.

A major breakthrough was the serendipitous observation that one of the known bursts, FRB 121102, is sporadically repeating (Spitler et al. 2016). Very recently, this repeater has been successfully localized to sub-arcsecond resolution thanks to the Jansky Very Large Array and the European VLBI Network (Chatterjee et al. 2017; Marcote et al. 2017). It was found to be in association with a dwarf star-forming host galaxy at redshift z = 0.19 (Tendulkar et al. 2017), thus confirming its cosmological origin. FRB 121102 was the first and is to date the only FRB discovered by the Arecibo Observatory (Spitler et al. 2014). Despite dedicated follow-up monitoring (e.g., Petroff et al. 2015; Ravi et al. 2015), none of the other known FRBs (mostly found by the Parkes telescope) has been observed to repeat. This may suggest two physically distinct classes: non-repeating scenarios invoking cataclysmic processes (e.g., Hansen & Lyutikov 2001; Piro 2012; Kashiyama et al. 2013; Totani 2013; Falcke & Rezzolla 2014; Zhang 2014; Fuller & Ott 2015) and repeating mechanisms in which the source can last for long (e.g., Kulkarni et al. 2014; Lyubarsky 2014; Connor et al. 2016; Cordes & Wasserman 2016; Dai et al. 2016; Katz 2016b; Lyutikov & Wasserman 2016; Kumar et al. 2017; Zhang 2017). On the other hand, this may also be an observational bias due to the lower sensitivity and the coarser localization of Parkes relative to Arecibo.4 Indeed, observations so far are statistically consistent with all FRBs being repeaters with a repetition frequency and a peak flux distribution similar to those of FRB 121102 (Lu & Kumar 2016).

The estimation for the all-sky FRB rate above ~2 Jy ms is high ~103–104 day−1 (Thornton et al. 2013; Champion et al. 2016). Since FRBs can be visible out to cosmological distances z ~ 1, about ~few × 10−5 of them (Hilbert et al. 2008) are expected to be gravitationally lensed by intervening galaxies (Li & Li 2014; Dai et al. 2017). In fact, the observed strong lensing fraction should be higher than the prior probability due to magnification bias. Dominated by lens mass scales >1010 M_☉, this creates image multiplets separated by arcseconds, with mutual time delays typically on the order of weeks to months. In particular, a repeating source, if lensed, will result in a set of multiple bursts for each repetition. With the prospect that forthcoming large-scale radio surveys, including UTMOST (Caleb et al. 2017a), HIRAX (Newburgh et al. 2016), CHIME (Bandura et al. 2014), and later on SKA1 (Maccart et al. 2015), will have the capacity to find ~102–103 FRBs per year, 4 If FRB 121102 had a location error similar to those of the typical FRBs found by Parkes and it were to be followed up by Parkes, the true location may fall onto the low-sensitivity gaps between beams and perhaps none of the subsequent bursts could have been detected.
the interesting situation of a strongly lensed FRB repeater becomes worthy of consideration.

Since survey telescopes will be efficient at detecting a large number of sources, one realistic way to find strongly lensed events is to look up the catalog for special ones. Although typical survey telescopes are not able to spatially resolve multiple images, it is still possible to distinguish a lensed repeater from unlensed ones. Image multiplets should have coincidental locations on the sky up to localization error, and are expected to have similar but not identical DMs. Depending on what frequencies to observe, lensed bursts may be significantly scatter-broadened compared with ordinary ones, due to ISM in the lens galaxy. Furthermore, a series of image supernovae subject to strong lensing at cosmological distances, such as the host and the lens. Compared with other variable sources them in greater detail. It will then be desirable to capture more temporal pattern along a certain line of sight will uncover a strongly lensed repeater.

The discovery of strongly lensed repeaters should justify the use of more expensive observational resources in order to study them in greater detail. It will then be desirable to capture more repetitions in deep VLBI observations on sub-arcsecond angular scales, which will resolve multiple images and identify the host and the lens. Compared with other variable sources subject to strong lensing at cosmological distances, such as supernovae (SNe) and quasars, FRBs are unique because timing accuracy on the order of milliseconds is achievable, owing to their extremely narrow (de-dispersed) widths. This leads to the question of what we can potentially learn about astrophysics by exploiting this high level of precision. Previously it has been suggested that microlensing time delay can probe compact mass clumps along the line of sight (Muñoz et al. 2016). In this work, we explore the possibility that galaxy-lensing time delays can probe non-uniform motion of the source on ∼au scales, and hence constrain its astrophysical nature and its surrounding environment.

From one repetition to the next, the lensing delay time between a pair of images varies due to the motion of the source (Yonehara 1999; Goicoechea 2002), the lens, and the observer. Velocities that are quasi-constant over the observational time span (∼years) can induce a linear drift in the delay. These include cosmological peculiar velocities of the host galaxy, the lens galaxy, and the Milky Way, as well as the source’s large-scale motion within its host, and the Solar System’s motion within the Milky Way. Numerically large, these are not predictable for individual cases, but their statistics can be used to measure cosmological parameters and structure formation (Kochanek et al. 1996). For this work, we will account for their effects but assume they are not of main interest here.

By contrast, motions that are non-uniform over the observational timescale leave non-trivial signatures in the time delay on top of linear drifts. The Earth’s orbital motion generates a sinusoidal perturbation \(\lesssim 10^{3}\) s to the delay time, whose amplitude and phase provide information to indirectly localize the source to \(\sim 10^{6}\), which may then facilitate interferometric follow-ups. Furthermore, as we will show, if multiple images are well-resolved with VLBI and the host and lens redshifts are obtained, then the effect of the Earth’s orbital motion can be subtracted down to millisecond accuracy. Any additional non-trivial variation in the delay time probes non-uniform source motion transverse to the line of sight. As we will show, this method has the advantage that it does not require lens modeling.

This powerful method, if realized, will constrain the astrophysical nature of repeating FRBs. If spots of coherent radio emission wander around across a transverse region of size \(\sim 1\) au, stochastic variations will be imprinted in the delay time. This may occur when mini-jets, produced through the dissipation of magnetic energy inside a larger but slow jet (Giannios et al. 2009), collide with clouds in the ambient medium (Romero et al. 2016). In such scenario, radiation comes from slightly different locations from one burst to another. Non-detection of such behavior constrains the compactness of the source system, narrowing down possible astrophysical scenarios.

Many FRB models are based on young neutron stars (NSs; see Katz 2016a, for a brief review), in which case highly beamed (Lyubarsky 2014) or near-surface radio emission (Kumar et al. 2017) is not expected to cause detectable variations in the delay time. On the other hand, an NS with a stellar companion will imprint an effect due to its orbital motion. Core-collapse SNe in a binary system are more likely to give birth to isolated NSs, because the sudden mass loss and NS natal kick tend to unbind the system. However, when the kick velocity is small (\(\lesssim 100\) km s\(^{-1}\)) and the NS is kicked in the opposite direction of the pre-supernova orbital motion, the binary system may survive (and roughly a few percent of them do survive; Hills 1983). In this case, the eccentric orbit of a young system can have a semimajor axis large enough to produce noticeable signatures. For example, the binary pulsar PSR B1820-11, a relatively young NS at an age \(\sim 3\) Myr, has an eccentric orbit with \(e \approx 0.8\) (Lyne & McKenna 1989) and a large semimajor axis \(\sim 1.3\) au.\(^5\) Many known binary pulsars with main-sequence companions are found to have \(e \gtrsim 0.6\) and orbital semimajor axes \(\gtrsim 0.1\) au, while binary pulsars with white-dwarf companions have low eccentricities (\(e \ll 0.1\)) and a significant fraction of them have wide orbits on au scales (see, e.g., Tauris et al. 2012). If the birth rate for repeaters is much lower than that for core-collapse SNe, it may be that FRBs require special conditions for the source system (Lu & Kumar 2016), which provides further motivation to probe possible source motion. Moreover, other FRB models that predict the progenitor to have non-uniform motion could be testable with lensing time delay. For instance, the repeater FRB 121102 has been attributed to an NS traveling through an asteroid belt of another star (Dai et al. 2016), or it is subject to plasma lensing by density inhomogeneities in the host galaxy (Cordes et al. 2017). In both cases, the source position may have large non-uniform transverse motion \(\gtrsim 1\) au (either physical or apparent) detectable with the method we propose here. Given our limited understanding of FRBs to date, it is worthwhile to explore the scientific potential of this novel observational method.

We organize this paper as follows. In Section 2, we first carry out order-of-magnitude estimates on motion-induced variations in lensing time delays, offering useful intuition on the relevant physical scales of the problem. Rigorous derivations then follow in Section 3. Then, in Section 4, we construct a hypothetical strong lensing event and describe the procedure of simulating mock time-delay measurements. This will serve as a realistic example in later sections for

\(^5\) Australia Telescope National Facility Pulsar Group, 2004, “ATNF Pulsar Catalog,” http://www.atnf.csiro.au/research/pulsar/psrcat/.
numerically assessing the accuracy of time-delay measurement and for verifying the back-of-the-envelope estimates in Section 2. In Section 5, we study indirect source localization using time delay variation between spatially unresolved multiple images. In Section 6, we study how non-uniform source motion can be measured if multiple images are resolved with very-long-baseline interferometry (VLBI). In Section 7, we discuss how microlensing and scattering might broaden the pulse and affect timing accuracy. Final remarks will be made in Section 8.

2. Order-of-magnitude Estimate

Before delving into detailed calculations, we first seek intuition by estimating the order of magnitude for the relevant physics scales. For simplicity, redshift factors are neglected. They will be easily recovered later. Since we mainly consider galactic-scale halos $M_h \approx 10^{12}$-$10^{13} M_\odot$ as the most probable intervening lenses, with typical gravitational radii much longer than the radio wavelength, the language of ray optics is suitable.

Imagine an FRB source located at a typical cosmological distance $D \sim 1$ Gpc away from the Earth, for which the optical depth to strong lensing by intervening galaxies is small but non-negligible. Assume a lens galaxy between the source and the observer. Typically the source-lens distance and the lens-observer distance are both of order $D$. Strong lensing splits each burst from the source into several images. They have typical angular separations $\Delta \theta \sim 1''$, which are not resolvable by single-dish telescopes or short-baseline arrays, but are within the reach of VLBI. They have mutual delays in the time of arrival on the order of $\Delta T \sim 0.01$–1 year. For FRBs, the typical (de-dispersed) burst width is remarkably short, even after scatter broadening, which enables the time of arrival to be measured within an accuracy of $\delta T \sim \Delta T$.

If a lensed source sporadically repeats, each repetition produces a set of multiple images. The time delay between a given pair of images, at zeroth order, is the same for all repetitions. However, the agreement is imperfect due to relative motions between the source, the lens, and the Earth, both perpendicular to the line of sight and parallel to the line of sight. Those alter the length of the optical path each burst has to travel before reaching the telescope.

2.1. Motion of the Earth

It is convenient to derive various kinematic effects in the rest frame of the Solar System barycenter. This can be treated as an inertial frame to good approximation, since the acceleration of the Solar System within the Milky Way is negligible over the observational time span. The orbital motion of the Earth in this frame is known to high precision, and hence perturbation to the time delay induced by Earth’s motion is predictable.

Due to the line-of-sight component of the Earth’s orbital motion, for each burst from the source, multiple images reach the Earth at different times. If the Earth recedes from the source at a velocity $v_{\parallel}^s$, at leading order, radio wave of a later image travels an additional distance $v_{\parallel}^s \Delta T$ relative to that of an earlier image, and therefore the mutual time delay changes by $(v_{\parallel}^s/c) \Delta T$ compared with the case without line-of-sight motion. This causes a measurable imprint between repetitions because $v_{\parallel}^s$ varies with time. Indeed, a constant $v_{\parallel}^s$ would not be distinguishable from the delay caused by stationary lensing.

The time delay varies annually by an amount

$$30 \text{ km s}^{-1} \times \Delta T/c \approx 300 \text{ s} \left(\frac{\Delta T}{0.1 \text{ year}}\right).$$

up to factors dependent on the orientation of the line of sight with respect to the Earth’s orbital plane, and the maximum time-delay variation is $2 \text{ au/c} \approx 1000 \text{ s}$. This is much larger than the timing resolution $\delta T \sim \text{ms}$.

The Earth’s orbital motion perpendicular to the direction of wave propagation (which is slightly different between images; see text below) has no effect on the travel time, since the wavefront is nearly planar far from the source. In fact, the curvature of the spherical wavefront only perturbs the travel time by

$$\frac{(v_{\parallel}^s T_{\text{obs}})^2}{2 c D} \approx 10^{-3} \text{ ms} \left(\frac{v_{\parallel}^s}{1000 \text{ km s}^{-1}}\right)^2 \left(\frac{T_{\text{obs}}}{5 \text{ year}}\right)^2 \left(\frac{1 \text{ Gpc}}{D}\right),$$

which is entirely negligible even for transverse velocity $v_{\perp}$ as large as the typical cosmic peculiar velocity. However, lensing deflection causes individual images to deviate from the unlensed source direction. This offset generates additional arrival-time perturbation from the Earth’s transverse motion. Since the size of the Earth’s orbit is much smaller than the typical transverse length scale on the lens plane $\sim D \Delta \theta \approx 5$ kpc, this perturbs the time delay by an amount that can be estimated by linear variation. This induces a sinusoidal perturbation to the time delay, whose amplitude is

$$\frac{2 \text{ au}}{c} \approx 5 \text{ ms} \left(\frac{\Delta \theta}{1''}\right).$$

up to an order-unity factor dependent on the orientation of the line of sight with respect to the Earth’s orbit. Interestingly, this is potentially measurable given the short FRB width $\sim \text{ms}$. However, this effect is degenerate with the effect from the line-of-sight projection of the Earth’s orbital motion, Equation (1), which is sinusoidal with exactly the same period but has an amplitude $\sim 10^{0.5}$ times greater! As we will discuss, measurement of time delay perturbation by the Earth’s transverse orbital motion would require precise knowledge of the Earth’s orbit to an accuracy better than $\sim 10^{-5}$, as well as image localization to $\lesssim 10^{-5}$ rad $\approx 2''$. Throughout this work, we assume that the former is the case, while the latter is achievable with VLBI observations.

For a ground-based telescope, the Earth’s rotation induces a diurnal variation in the time delay in a similar fashion. While the effect from the transverse velocity component coupled to image separation is much smaller than 1 ms, the line-of-sight velocity component creates a signature as large as $2 R_s/c \approx 40$ ms. Realistic data analysis will have to account for the Earth’s rotation in a similar way to how the Earth’s orbital motion is dealt with, but in this work we will neglect this effect for simplicity.

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\footnote{That is to say, the decomposition into line-of-sight motion and transverse motion differs slightly from one image to another, whose effect on the pulse travel time must be accounted for.}
2.2. Motions of the Source/Lens

The source and the lens galaxy typically have cosmic peculiar velocities \( \sim O(1000) \) km s\(^{-1}\) with respect to the Solar System, with velocity components both along and perpendicular to the line of sight. Over the observational time span, these can be treated as constant velocities.

Line-of-sight motion of the source and that of the lens change the radial distances of the source-lens-observer configuration. However, the accumulative change over the typical observation timescale \( T_{\text{obs}} \) is minuscule compared with \( D \). Taking the source’s motion as an example, a line-of-sight velocity component \( V_{s||} \) induces a change in the time delay

\[
\Delta T = \frac{T_{\text{obs}} V_{s||}}{D} \approx 0.02 \text{ ms} \left( \frac{\Delta T}{0.1 \text{ year}} \right) \times \left( \frac{V_{s||}}{1000 \text{ km s}^{-1}} \right) \left( \frac{T_{\text{obs}}}{5 \text{ year}} \right) \left( \frac{1 \text{ Gpc}}{D} \right),
\]

through the dependence of lensing time delay on the line-of-sight distances. This is negligible compared with FRB burst widths \( \sim \text{ms} \). Even if resolvable, this contributes to the linear drift in \( \Delta T \), distinct from the other non-uniform relative motions we will focus on in this paper. The same conclusion can be drawn for the line-of-sight motion of the lens galaxy.

On the other hand, motion of the source and of the lens perpendicular to the line of sight affect the time delay through a change in the lensing impact parameter. Dominated by the cosmic peculiar velocity, the source’s motion induces a linear drift in the time delay

\[
\frac{T_{\text{obs}} V_{s\perp}}{D} \Delta T \approx 3 \text{ s} \left( \frac{T_{\text{obs}}}{5 \text{ year}} \right) \left( \frac{V_{s\perp}}{1000 \text{ km s}^{-1}} \right) \times \left( \frac{1 \text{ Gpc}}{D} \right) \left( \frac{\Delta T}{0.1 \text{ year}} \right) \left( \frac{1''}{\Delta \theta} \right),
\]

and a similar effect for the lens. These will be measurable, if they are much larger than the typical burst width. Equation (5) is estimated from linear variation; the correction at quadratic order will be further suppressed by a factor \((T_{\text{obs}} V_{s\perp})/(D \Delta \theta) \sim 10^{-6}\), which is negligible.

The linear drift due to constant transverse velocities is guaranteed to exist, but in individual lensing case it offers limited insight because cosmic peculiar velocities are only statistically predictable. By contrast, any non-uniform transverse motion would be of greater interest.

It is unclear whether the source of an FRB has significantly non-uniform motion within its host. If the source has an orbital motion because of proximity to, for instance, a stellar companion or a massive black hole, a nonlinear perturbation to the time delay is possible.\(^7\) If the source’s orbital period is comparable or shorter than the observation time \( T_{\text{obs}} \), one may search for oscillation in the time delay on the order of

\[
\frac{d_s}{D} \frac{\Delta T}{\Delta \theta} \approx 3 \text{ ms} \left( \frac{d_s}{1 \text{ au}} \right) \left( \frac{\Delta T}{0.1 \text{ year}} \right) \left( \frac{1 \text{ Gpc}}{D} \right) \left( \frac{1''}{\Delta \theta} \right),
\]

where \( a_s \) is the semimajor axis of the source’s orbit. If the orbital period is much longer than \( T_{\text{obs}} \), acceleration may still leave a non-trivial imprint in the time delay, distinct from that of a constant motion.

Another possibility is that FRBs are emitted from numerous compact regions within an extended volume of space. In this case, different repetitions might originate from different regions, whose transverse separations translate into differences in the time delay,

\[
\frac{d_s}{D} \frac{\Delta T}{\Delta \theta} \approx 3 \text{ ms} \left( \frac{d_s}{1 \text{ au}} \right) \left( \frac{\Delta T}{0.1 \text{ year}} \right) \left( \frac{1 \text{ Gpc}}{D} \right) \left( \frac{1''}{\Delta \theta} \right),
\]

where \( d_s \) is the typical transverse separation between emission regions. Thus separations as small as a fraction of 1 au can be detectable, which by far exceeds the resolution of radio interferometry. Again, Equations (6) and (7) are based on linear variation of the lensing impact parameter; quadratic corrections are negligibly small.

The provided back-of-the-envelope estimates suggest that repeating FRBs, if strongly lensed into multiple images, may provide us with unique opportunities to measure time delay perturbations induced by the motions of the source and the Earth, thanks to their narrow burst widths. With information on the source’s motion, much may be learned about its physical properties and its surrounding environment. In the following, we derive rigorous equations.

3. Time-delay Perturbations

In this section, we rigorously derive the aforementioned kinematic effects on the lensing time delay. We first assume an observer at rest with respect to the barycenter of the Solar System. In the end we discuss how to convert observables into the Earth’s rest frame.

Consider the strong lensing geometry as in Figure 1(a): a repeating FRB is located at redshift \( z_L \) with an angular-diameter distance \( D_L \) to the Earth. An intervening galaxy lens is located at redshift \( z_L < z_S \) with an angular-diameter distance \( D_L \) to the Earth. The angular-diameter distance to the source as viewed from the lens is \( D_{LS} \).

Let \( y \) be the true (angular) position of the source, \( x \) be the image (angular) position on the lens plane, and \( z \) be the (angular) position of the lens galaxy. These are measured relative to a reference line of sight, which we call the optical axis. We first allow \( z = 0 \) for the convenience of considering lens motion; after calculations are done, we are free to set \( z = 0 \). For a stationary lensing configuration, the Fermat potential is given by (Schneider et al. 1992)

\[
F(x; y, z) = (1 + z_L) \frac{D_L}{c} \frac{1}{D_{LS}} \left[ \frac{1}{2} (x - y)^2 - \psi(x - z) \right],
\]

where \( \psi(x) \) is the usual lensing potential if the lens’s center is right on the optical axis. This is defined relative to the geometrical travel time from the source to the Earth along a direct straight line.

Images are located at the extremal points of the Fermat potential, which we label by \( I = a, b, c, \ldots \). Their positions \( x_I \) are roots of the lens equation,

\[
x - y - \alpha(x - z) = 0.
\]
Here the deflection angle $\alpha(x - z)$ equals the gradient of the lensing potential $\alpha(x - z) = \partial\psi(x - z)/\partial x$, where $\psi(x - z)$ is linearly proportional to the Shapiro time delay due to the gravitational field of the lens. The observed time delay of the $J$th image relative to the $I$th image is given by

$$D_T^J = D_T^I - D_T^{I,0},$$

and similarly for $\Delta T_{I,0}$. We have introduced a subscript $0$ to remind ourselves that this assumes no relative motion between the source, the lens, and the Earth.

Assume that the source gives off successive bursts, labeled by $k = 1, 2, 3, \ldots$. For each burst, the same set of multiple images is generated.

### 3.1. Earth’s Orbital Motion

First we study the effect of the Earth’s orbital motion around the Sun. As in Figure 1(c), suppose that relative to the normal of the Earth’s orbital plane, the true position of the source on the sky (as seen in the inertial frame of the barycenter of the Solar System) has an inclination angle $i$, and it has an azimuthal angle $\phi$ relative to the direction of perihelion. In the same coordinate system, the optical axis has inclination $i_o$ and azimuthal angle $\phi_o$. Note that $(i, \phi)$ and $(i_o, \phi_o)$ are not identical. They differ by a small angular displacement $y$.

Since the radio wave coming from each image has a (nearly) planar wavefront when reaching the Solar System, the correction to time delay, for the $k$th burst, is given by

$$\delta T_{J,k}^I = -\frac{1}{c} \mathbf{n}_I \cdot \mathbf{r}_E(t_k^I),$$

and

$$\delta T_{I,k}^I = \delta T_{J,k}^I(t_k^I) - \delta T_{J,k}^I(t_k^J).$$

Here $\mathbf{n}_I$ is the unit vector to the $I$th image on the sky. And we have used $t_k^I$ to denote the time of arrival for the $I$th image of the $k$th burst.

The vector $\mathbf{r}_E(t)$ is the Earth’s displacement in three-dimensional space at given time $t$. It can be written as

$$\mathbf{r}_E(t) = \frac{p_\odot}{1 + e_\odot \cos \phi_\odot(t)} [e_{\odot P} \cos \phi_\odot(t) + e_{\odot R} \sin \phi_\odot(t)].$$

Here $e_\odot = 0.0167$ is the orbital eccentricity, $a_\odot = 1.496 \times 10^8$ km is the semimajor axis, $p_\odot = a_\odot(1 - e_\odot^2)$ is the semilatus rectum, and $\phi_\odot(t)$ gives the azimuthal position of the Earth relative to the perihelion at a given time $t$. We also define $e_{\odot P}$ to be a unit vector pointing from the Sun to the perihelion, and $e_{\odot R}$ is another unit vector in the orbital plane orthogonal to
\[ e_{\odot} \cdot p. \] Since the orbital eccentricity is small, \( e_{\odot} \approx \Omega_{\odot} \cdot t \), where \( \Omega_{\odot} \) is the angular frequency of the Earth’s orbital motion.

It is convenient to decompose \( \mathbf{r}(t) \) into a component parallel to the optical axis \( \mathbf{d}_{\perp}(t) \) and a component perpendicular to it, 

\[ \begin{align*}
\mathbf{r}_\parallel(t) &= \mathbf{d}_\parallel(t) + l_\parallel(t) \mathbf{n}_\parallel, \\
\mathbf{r}_\perp(t) &= \mathbf{r}_\parallel(t) - [\mathbf{r}_\parallel(t) \cdot \mathbf{n}_\parallel] \mathbf{n}_\parallel,
\end{align*} \]

(13)

using a unit vector \( \mathbf{n}_\parallel \) pointing along the optical axis.8 Since \( \mathbf{n}_\parallel = \mathbf{n}_* + \mathbf{x}_* \), Equation (11) can be decomposed into an effect due to a line-of-sight motion, and an effect due to transverse motion,

\[ \delta T_{l,\parallel}^{(k)} = \delta T_{l,\parallel}^{(k)} + \delta T_{l,\perp}^{(k)}, \]

(19)

\[ \delta T_{l,\parallel}^{(k)} = -\frac{1}{c} l_\parallel(t_k^{(l)}), \]

\[ \delta T_{l,\perp}^{(k)} = -\frac{1}{c} \mathbf{x}_* \cdot \mathbf{d}_\perp(t_k^{(l)}), \]

(14)

where we have ignored terms quadratic in the small angles \( \mathbf{x}_* \)’s (which generate minuscule fractional corrections \( \sim(\Delta \theta)^2 \sim 10^{-12} \)). The effect due to line-of-sight motion therefore reads

\[ \delta T_{l,\parallel}^{(k)} = \delta T_{l,\parallel}^{(k)} - \delta T_{l,\parallel}^{(k)} = \frac{p_0 \sin \iota_*}{c} \left[ \cos(\phi_\parallel - \phi_\parallel(t_k^{(l)})) - \cos(\phi_\parallel - \phi_\parallel(t_k^{(l)})) \right] \\
\times \left[ 1 + e_{\odot} \cos \phi_\parallel(t_k^{(l)}) \right]. \]

(15)

On the other hand, the effect due to transverse motion is given by

\[ \delta T_{l,\perp}^{(k)} = \delta T_{l,\perp}^{(k)} - \delta T_{l,\perp}^{(k)} = \frac{1}{c} [\mathbf{x}_* \cdot \mathbf{d}_\perp(t_k^{(l)}) - \mathbf{x}_* \cdot \mathbf{d}_\perp(t_k^{(l)})], \]

(16)

which only depends on image positions \( \mathbf{x}_* \) but not on details of the lens.

3.2. Motion of the Lens

As in Figure 1(a), the lens galaxy has a constant peculiar velocity \( V_L \) relative to the Solar System. According to Section 2, only the velocity component transverse to the optical axis induces a sizable perturbation to the time delay. To derive this effect, consider the differentiation of \( F(x; y, z) \) with respect to \( z \),

\[ \frac{d \Delta T_i}{dt} = \frac{V_{l,\parallel}^{(k)}}{D_L} \frac{\partial F(x_i; y, z)}{\partial z} \]

(17)

where \( t_i \) is the lens-frame time (measured relative to a chosen reference moment \( t_0 = 0 \)) satisfying \( dt = (1 + z_L) dt \) due to cosmic time dilation. When computing the derivative, we fix \( y \), but \( x \) is regarded dependent on \( z \) via the lens equation Equation (9),

\[ \frac{\partial}{\partial z} \psi(x - z) = \alpha_j(x - z) \left( \frac{\partial x_j}{\partial z} - \delta t_i \right). \]

(18)

Combining these results with the lens equation, integrating over \( t_i \), we obtain (and set \( z = 0 \) eventually)

\[ \delta T_{l,\parallel}^{(k)} = \left( 1 + z_L \right) \frac{D_L}{c D_{LS}} \alpha_j \cdot \mathbf{d}_\parallel(t_k^{(l)}), \]

\[ \delta T_{l,\perp}^{(k)} = \delta T_{l,\parallel}^{(k)} - \delta T_{l,\perp}^{(k)} = \left( 1 + z_L \right) \frac{D_S}{c D_{LS}} \times \left[ \alpha_j \cdot \mathbf{d}_\perp(t_k^{(l)}) - \alpha_j \cdot \mathbf{d}_\parallel(t_k^{(l)}) \right]. \]

(20)

Here \( d_i(t) \) is the linear displacement of the lens transverse to the line of sight at given lens-frame time \( t_i \). The deflection \( \alpha_j = \mathbf{x}_* - \mathbf{y} \) is not directly measurable without knowing the true source position \( \mathbf{y} \). The lens-frame time \( t_k^{(l)} \) when the \( i \)th image of the \( k \)th radio burst passes the lens may be chosen to be

\[ t_k^{(l)} = \frac{t_0^{(k)}}{1 + z_L} + \frac{1}{2} \frac{D_S}{c D_{LS}} \left( (x_0 - y)^2 \right) \]

(21)

\[ \frac{d \Delta T_i}{dt} = \frac{V_{l,\parallel}^{(k)}}{D_L} \frac{\partial F(x_i; y, z)}{\partial y} \]

(22)

The definition of \( t_k^{(l)} \) is arbitrary within the light-crossing time of the lens galaxy. The bottom line, however, is that the effect of the lens’s motion is to high precision merely a linear drift in the burst time of arrival in the observer’s frame, if we assume that \( V_L \) is constant.

3.3. Motion of the Source

The source also has a velocity \( V_s \) relative to the Solar System. As explained in Section 2, only the velocity component transverse to the optical axis is relevant. For the source, we first set \( z = 0 \), and then compute the linear variation of \( F(x; y, z = 0) \) with respect to \( y \),

\[ \frac{d \Delta T_i}{dt} = \frac{V_{l,\parallel}^{(k)}}{D_L} \frac{\partial F(x_i; y, z)}{\partial y} \]

(23)

Combining these results with the lens equation, integrating over \( t_i \), we derive the perturbation in time delay (Yonehara 1999),

\[ \delta T_{l,\parallel}^{(k)} = -\left( 1 + z_L \right) \frac{D_L}{c D_{LS}} \alpha_j \cdot \mathbf{d}_\parallel(t_k^{(l)}), \]

\[ \delta T_{l,\perp}^{(k)} = \delta T_{l,\parallel}^{(k)} - \delta T_{l,\perp}^{(k)} = -\left( 1 + z_L \right) \frac{D_S}{c D_{LS}} (x_0 - y) \cdot \mathbf{d}_\parallel(t_k^{(l)}), \]

(24)

where \( \mathbf{d}_\parallel(t) \) is the transverse displacement of the source at a given source-frame time \( t_i \), and \( t_k^{(l)} \) is the moment in the source frame when the \( k \)th burst is emitted, which is the same for all
images. The vector $\mathbf{d}_s(t_s)$ can be obtained by projecting the three-dimensional displacement of the source $\mathbf{r}_s(t_s)$ onto the plane perpendicular to the line of sight, namely $\mathbf{d}_s(t_s) = \mathbf{r}_s(t_s) - [\mathbf{r}_s(t_s) \cdot \mathbf{n}_s] \mathbf{n}_s$. Note that this result depends on $x_f$’s, which are direct observables, but not on the lens model.

The displacement of the source $\mathbf{r}_s(t_s)$ is expected to be dominated by a constant cosmic peculiar velocity $\mathbf{V}_c$ relative to the lens. If in addition the source has Keplerian motion orbiting a massive object (Figure 1(b)), described by an orbital eccentricity $e$, the semi-latus rectum of the orbit $p_s$, which is related to the semimajor axis $a$ through $p_s = a(1 - e^2)$, and the instantaneous azimuthal position in the orbital plane $\phi_s(t_s)$ (for simplicity, we neglect possible orbital precession), we can then write

$$\mathbf{r}_s(t_s) = \mathbf{V}_c t_s + \frac{p_s}{1 + e \cos \phi_s(t_s)} \times [\mathbf{e}_p \cos \phi_s(t_s) + \mathbf{e}_R \sin \phi_s(t_s)].$$  (26)

Here $\mathbf{e}_p$ is a unit vector pointing from the binary center of mass to the periapsis, and $\mathbf{e}_R$ is another unit vector in the orbital plane orthogonal to $\mathbf{e}_p$. Analogous to the case of the Earth’s motion, after Equation (26) is inserted into (24), the first term generates a linear drift in the time delay, while the second term induces an oscillatory perturbation.

In summary, the mutual time delay between a given pair of images belonging to the $k$th burst is given by the zeroth-order delay $\Delta T_{0,k}$ computed for a stationary lensing configuration, further corrected by various velocity effects,

$$\Delta T_{0,k}^j = \Delta T_{0,k} + \delta T_{0,k}^{(i)} + \delta T_{0,k}^{(j)} + \delta T_{0,k}^{(\parallel)} + \delta T_{0,k}^{(\perp)}.$$  (27)

Among them, the effect of the Earth’s motion results from the finite light travel time across the Earth’s orbit. By comparison, the effects of transverse motions for the lens and for the source depend on image separations and can be understood on the basis of a change in the lensing impact parameter.

**3.4. Observing in the Earth’s Rest Frame**

We have performed calculations in the rest frame of the Solar System barycenter, while radio telescopes co-move with the Earth, which defines a non-inertial frame. Moreover, a few relativistic effects may need to be accounted for if high precision is desired.

Bursts are timed by a clock co-moving with the Earth, which is slightly slower than a clock in the inertial frame of the Solar System, due to both kinetic and gravitational time dilation. However, dilation rescales all time intervals in the same way, so that it produces no drift or oscillation.

Localization using telescopes on the Earth are subject to relativistic aberration. The apparent position of an image annually traces an ellipse on the sky, whose semimajor axis is $\sim 20''$ and whose semiminor axis depends on the Ecliptic latitude. This affects the image coordinates for different repetitions at different times of the year. Aberration may be unimportant if sky localization is poor (and hence far from sufficient to resolve images), but needs to be corrected for with VLBI resolution. Annual aberration modulates the absolute, apparent position in the Ecliptic coordinates, but (nearly) preserves the angular separations between the images, the source, and the lens. In the following, we will assume that aberration due to the Earth’s orbital motion is always corrected for. The same can be done for diurnal aberration due to the Earth’s rotation.

**4. Simulating Mock Data**

To demonstrate how well the source’s motion can be inferred from the aforementioned effects on the time delay, we construct a hypothetical strong lensing event and simulate mock measurements. This example will be adopted throughout.

We hypothesize a repeater at $z_s = 1.0$, which is strongly lensed by an intervening galaxy at $z_L = 0.5$. Assuming the Planck best-fit cosmological parameters (Ade et al. 2016), we obtain angular-diameter distances $D_A = 1635$ Mpc, $D_L = 1251$ Mpc, and $D_{L,S} = 697$ Mpc. As a concrete example, the lens galaxy is assumed to be a singular isothermal ellipsoid (Kormann et al. 1994) with a velocity dispersion $\sigma_v = 250$ km s$^{-1}$ and an axis ratio $f = 0.4$. For simplicity, we ignore the possibility of an external shear.

Without lensing deflection, we assume that the line of sight to the source has an inclination $i = 0.5$ with respect to the normal of the Ecliptic plane, and an azimuthal position $\phi = 0.7$ relative to the Earth’s perihelion.

On the sky, we set up a Cartesian coordinate system centered at the geometrical center of the lens, whose first coordinate axis is parallel to the Ecliptic plane. Its major axis on the sky makes an angle $\phi_L = 0.7$ relative to the direction parallel to the Ecliptic plane. Under this coordinate system, we assume a source at angular location $\gamma = (0.223, -0.123)$, in units of the characteristic angular scale $\zeta_0 = 4 \pi (\sigma_v/c)^2 D_{L,S}/D_S = 0^\prime 770$. If the source-lens-observer configuration is stationary, four
images are produced in geometrical optics (Figure 2), whose angular locations and mutual time delays are presented in Table 1. Among them, $a$ precedes $b$, $c$, and $d$ by about 40 days, while the latter three images have mutual time delays on the order of a few days.

We assume that the source has a constant velocity relative to the Solar System, with a component transverse to the optical axis, $v_{\perp} = (\cos \theta_1, \sin \theta_1) \times 1200$ km s$^{-1}$ with $\theta_1 = 0.8$, and that the lens galaxy also moves at a constant velocity relative to the Solar System, with a component transverse to the optical axis, $v_{\perp} = (\cos \theta_2, \sin \theta_2) \times 800$ km s$^{-1}$ with $\theta_2 = 2.5$. As has been explained in Section 2, the line-of-sight components are not relevant.

Timing of bursts is then simulated according to the following procedure:

1. For simplicity, a sequence of repetition times $t_0^{(k)}$ for $k = 1, 2, \ldots$ are generated according to a random Poisson process with a constant repetition rate (albeit in reality the repeater FRB 121102 [Spitler et al. 2016] shows remarkable non-Poissonian behavior [Wang & Yu 2017; Opperman & Pen 2017]). These $t_0^{(k)}$’s serve as reference times of arrival in the observer’s frame for individual repetitions, corresponding to the case if strong lensing did not happen and if the source, the lens, and the Earth were not moving (i.e., radio waves travel directly along straight lines).

2. Forcing emission at the source and reception at the Earth in general leads to an implicit equation, which we solve in the following iterative way to obtain sufficiently accurate arrival times. For the $I$th image of the $k$th burst, we first compute the trial time of arrival according to

$$t_I^{(k)} = t_0^{(k)} + \Delta T_{I,0} + \frac{p_{1.6}}{c} \sin \tau \frac{\cos (\phi_1 - \phi_{0.1}(t_I^{(k)}))}{1 + e_{\perp} \cos \phi_{0.1}(t_I^{(k)}))} \frac{D_s}{c D_{LS}} x_I \cdot d_{I}(t_I^{(k)}) + (1 + z_L) \frac{D_s}{c D_{LS}} \alpha_I \cdot d_{I}(t_I^{(k)}).$$

(28)

Here $t_I^{(k)} = t_0^{(k)}/(1 + z_S)$ is the time of emission of the $k$th burst in the source frame, and $t_I^{(k)}$ is given by Equation (21). We then find $t_I^{(k)}$ by re-calculating the right-hand side of Equation (28) and replacing the combination $t_0^{(k)} + \Delta T_{I,0}$ with the trial $t_I^{(k)}$ whenever the Earth’s instantaneous position needs to be computed—that is,

$$t_I^{(k)} = t_0^{(k)} + \Delta T_{I,0} + \frac{p_{1.6}}{c} \sin \tau \frac{\cos (\phi_1 - \phi_{0.1}(t_I^{(k)}))}{1 + e_{\perp} \cos \phi_{0.1}(t_I^{(k)}))} \frac{D_s}{c D_{LS}} x_I \cdot d_{I}(t_I^{(k)}) + (1 + z_L) \frac{D_s}{c D_{LS}} \alpha_I \cdot d_{I}(t_I^{(k)}).$$

(29)

In this way, we perturbatively ensure that the answer for $t_I^{(k)}$ is consistent with propagation along a null ray and is accurate to a level better than $\sim 1$ ms.

3. The time delay of the $J$th image relative to the $I$th image for the $k$th burst is readily found by $\Delta T_{IJ}^{(k)} = t_I^{(k)} - t_J^{(k)}$.

4. Finally, timing noise drawn from a normal distribution with zero mean and a standard deviation $\sigma_{\text{err}}$ is added to the mock times of arrival. This is to account for the limitation of finite burst width on the (de-dispersed) timing accuracy.

5. Localization Without Resolving Images

Single-dish telescopes or short-baseline arrays used for radio transient surveys are typically incapable of resolving lensed multiple images. Large interferometric arrays or VLBI technique are therefore needed to pin down the host-lens system and separate images on sub-arcsecond angular scales. However, the coarse localization of survey telescopes is adverse for efficient VLBI follow-ups. We now discuss, in the case of a multiply imaged repeater, how information on the time-delay perturbation might help improve localization and facilitate deep follow-ups.

As estimated in Section 2, line-of-sight projection of the Earth’s orbital motion induces the largest non-trivial perturbation to the time delay $\delta T_{IJ,0} \gtrsim 10^3$ s. Since $e_{\perp} \ll 1$, this has a nearly sinusoidal temporal variation. Assume that the Earth’s orbital motion is known to high accuracy, according to Equation (15), the inclination $i$ and azimuthal angle $\phi$ of the source’s sky position in the Ecliptic coordinates can be deduced from the amplitude and the phase of this variation.

We now study how precisely one can localize the source in this way. Suppose a total number of $N$ bursts are detected, each of which has multiple images. Since we seek variation on the order of hundreds of seconds, we may neglect non-uniform transverse velocities in $\delta T_{IJ,0}$ and $\delta T_{IJ,0}$. For the $I$th image and the $J$th image, we use the following model for the mutual delay:

$$\Delta T_{IJ}^{(k)} = \Delta T_{IJ,0} + \left( K_I t_J^{(k)} - K_J t_I^{(k)} \right) + \frac{p_{1.6}}{c} \sin \tau \frac{\cos (\phi_1 - \phi_{0.1}(t_I^{(k)}))}{1 + e_{\perp} \cos \phi_{0.1}(t_I^{(k)}))} \frac{D_s}{c D_{LS}} x_I \cdot d_{I}(t_I^{(k)})$$

(30)

which has five free parameters ($i$, $\phi$, $\Delta T_{IJ,0}$, $K_I$, $K_J$). Among them, we mainly aim to measure the sky localization $i$ and $\phi$ averaged over all images; Equation (30) does not account for image separations, since this method cannot achieve sufficient angular resolution to resolve individual images anyway. The other three are nuisance parameters: $\Delta T_{IJ,0}$ describes a constant...
time delay due to stationary lensing, and $K_I$ and $K_J$ account for linear drifts in the time delay induced by constant (but unknown) velocities. Assuming that one has perfect knowledge of the Earth’s orbital parameters, and that timing of all bursts have a Gaussian random uncertainty $\sigma_w$ due to finite burst widths, we can find the best-fit parameters by maximizing the log likelihood,

$$\ln L = -\frac{1}{4} \sigma_w^2 \sum_{k=1}^{N} \left( \Delta T_{I,J,k} - (K_I t_J^k - K_J t_I^k) \right)^2 - \frac{p_{\|} \sin l}{c} \left[ \cos (\phi - \hat{\phi}_0(t_J^k)) - \frac{\cos (\phi - \hat{\phi}_0(t_I^k))}{1 + e_\| \cos \hat{\phi}_0(t_I^k)} \right]^2 .$$

$$\text{(31)}$$

The factor of four in front of $\sigma_w^2$ comes from the fact that the difference between two independent timing measurements has a variance $2 \sigma_w^2$. Similar factors arise in equations presented later. It is worthy to note that this method does not require redshift information of the lens or the source.

The left panel of Figure 3 gives an example of how the delay between image $a$ and image $b$ might exhibit nearly sinusoidal variation among $\sim 30$ repetitions throughout 500 days of observation, which can be well fit by the five-parameter model Equation (30).

To numerically assess the uncertainty in the sky localization, we simulate a large number of mock observations. For each of them, we generate random source repetitions, compute predicted times of arrival, and then measure $(l, \phi)$ using Equation (30). Marginalizing over the nuisance parameters $(\Delta T_{I,J,0}, K_I, K_J)$, we infer the precision of localization from the amount of scatter in the best-fit values for $(l, \phi)$ around their true values. This is shown in the right panel of Figure 3.

Our results indicate that with the detection of $\sim 5$ ($\sim 25$) repetitions, using time delays for a single pair of images $(a, b)$, the inclination $i$ can be localized to $\sim 5''$ ($\sim 0.5''$) at 2$\sigma$. The uncertainty in $\phi$ of similar size. Using an image pair with a shorter time delay (e.g., $(b, d)$) leads to worse error-bars. The error-bar can further shrink if delay measurements from several pairs are combined. Since this level of localization is insufficient to resolve images, we have simply assumed the same $(l, \phi)$ for all images. At a repetition rate of $\sim 0.05$ day$^{-1}$ with$^{9}$ a total of $\sim 30$ repetitions detected, the statistical uncertainty can be reduced to $\lesssim 1''$. However, as shown in Figure 3 (right panel), localization will be systematically biased, in a way that depends on which image pair is being used. The reason for this bias is that the simple five-parameter model Equation (30) does not capture the (nearly) sinusoidal time-delay perturbation caused by the transverse projection of the Earth’s orbital motion through Equation (16), which cannot be predicted without knowing image separations. As the time delay between the image pair decreases, the effect of the Earth’s orbital motion parallel to the line of sight also decreases (Equation (15)). In contrast, the effect from the transverse motion does not vanish, as it is determined by the image separation. Therefore using an image pair of shorter time delay would lead to a larger bias.

Taking that into account, we may conclude that trustworthy source localization to about $2''$–$10''$ is achievable, given a pulse timing precision of a few milliseconds. This agrees with the anticipation in Section 2 that neglecting the Earth’s transverse orbital motion restricts the accuracy of angular localization to about $10^{-5}$ radian. For many survey telescopes, this level of localization would still help, narrowing down the area on the sky VLBI follow-ups have to search for (Effekhar & Berger 2017).

$^9$ This rate is much lower than the intrinsic rate inferred for FRB 121102 (Opperman & Pen 2017). However, the observed rate is reduced compared with the intrinsic rate, due to limitations from telescope sensitivity and observational cadence. The repetition rate we use in mock simulations always refers to the observed rate.
We add one caveat that millisecond timing precision might be prohibited by severe scattering broadening due to the lens galaxy (see estimates in Section 7.2). This is especially problematic at low frequencies $\lesssim 1$ GHz where many survey instruments will be operating, and for images close to the center of the lens. Scattering broadening is significantly mitigated when observing at higher frequencies $\gtrsim 2$ GHz (e.g., SKA1-MID; Macquart et al. 2015), but then indirect localization to $10''$ using time delay may not be superior to the instrument’s intrinsic resolution. In any case, VLBI follow-ups of a lensed repeater may or may not benefit from this indirect method. Once successfully done, they will help to identify both the host galaxy and the lens.

6. Probing Source Motion with VLBI Localization

Localization of a lensed repeater with VLBI, if eventually done, would enable precise angular resolution (e.g., at 5 GHz $\sim 5$ mas for EVN10 and $\sim1$ mas for VLBA11). This should be sufficient to resolve multiple images and measure $\chi$’s (although the true source position $y$ is still unknown without lens modeling). This high level of angular resolution would make it feasible to identify the lens galaxy as well as the lensed source galaxy in the background, following which their redshifts $z_S$ and $z_L$ can be separately determined from optical follow-ups.

Given the high promise of the VLBI technique, we furthermore explore the possibility of probing the observable effect of any non-uniform transverse motion of the source, $\delta T_{J,i\parallel}^{(k)}$ (Equation (24)), by accurately subtracting the effect of the Earth’s orbital motion, $\delta T_{J,0\parallel}^{(k)}$ (Equation (15)) and $\delta T_{J,0\perp}^{(k)}$ (Equation (16)). Owing to superb VLBI resolution, the latter can be predicted with high precision. The residuals thus carry valuable information about the source.

6.1. Random Emission Spots

It might be that compact emission spots of radio bursts are hosted by an extended clump of material. Each time one spot within this clump has the right condition for coherent radio emission, a burst is emitted from that spot. As a toy model, let us assume that these emission spots are uniformly distributed and randomly switch on and off within a spherical volume of radius $R$; then for $R \gtrsim 1$ au detectable time-delay perturbation is induced as the spot of emission switches from one to another. This is only meant to demonstrate which level of displacement in the emission spot can produce detectable signatures. In reality, the geometry of the extended clump and the statistics of emission spots might be completely different.

If we are ignorant of this effect, we may simply use the following model to fit the time-delay data:

$$\Delta T_{J,i\parallel}^{(k)} = \Delta T_{J,0} + (K_I t_J^{(k)} - K_I t_i^{(k)}) + \frac{p_\alpha}{c} \sin \iota *$$

$$\times \left[ \frac{\cos (\phi_s - \phi_0(t_J^{(k)}))}{1 + e_\alpha \cos \phi_s(t_J^{(k)})} - \frac{\cos (\phi_s - \phi_0(t_i^{(k)}))}{1 + e_\alpha \cos \phi_0(t_i^{(k)})} \right]$$

$$+ \frac{1}{c} \left[ \mathbf{x}_J \cdot \mathbf{d}_\alpha(t_J^{(k)}) - \mathbf{x}_i \cdot \mathbf{d}_\alpha(t_i^{(k)}) \right].$$

(32)

with respect to seven free parameters ($x_J, y_J, \Delta T_{J,0}, K_I, K_J$). Here $t_J^{(k)}$ is the measured angular position of the $k$th image in the $k$th repetition. We assume that with VLBI $t_J^{(k)}$’s are measured with a standard deviation $\sigma_\delta$. The nuisance parameters $(\Delta T_{J,0}, K_J, K_I)$ are introduced to account for the constant and the linearly drifting part of the time delay.

In the left panel of Figure 4, we show examples of residuals after fitting the mock time-delay measurement for the image pair $(a,b)$. We assume a repetition rate 0.05 day$^{-1}$ and an angular resolution $\sigma_\delta = 5$ mas. We consider different radii for the extended clump $R = 0.1$ au, 1 au, 3 au. For small radii $R \ll 1$ au, Equation (32) provides a good fit to the noisy data, giving a $\chi^2$ per degree of freedom close to unity. For larger radii $R \sim 3$ au, Equation (32) gives a $\chi^2$ per degree of freedom that is way too high, suggesting that time-delay perturbations caused by randomized emission spots are resolved. To see which regions in the $\chi^2 - \sigma_\delta$ parameter space can be probed by timing measurements, we show in the right panel of Figure 4 the typical $\chi^2$ per degree of freedom as a function of both $R$ and $\sigma_\delta$. Since the smooth model Equation (32) does not produce stochastic fluctuations in the time delay, the conclusion will be robust, even for poor resolution $\sigma_\delta = 100$ mas. Again, the significance of the measurement can be further improved by jointly fitting the time delays for several image pairs.

6.2. Orbital Motion

Another possibility is that the compact source orbits around another mass. Orbital motion projected onto the plane of the sky perturbs the lensing time delay via Equation (25). For a simple but concrete example, consider a circular orbit for the source,12 whose normal is at an angle $\iota_s$ ($0 \leq \iota_s < \pi$) to the optical axis, and its projection onto the plane of the sky has a major axis at an angle $\phi_s$ ($0 \leq \phi_s < \pi$) to the first coordinate axis.

The oscillatory part of the source’s transverse displacement vector (barring constant motion), in its components, is given by

$$\mathbf{d}_\alpha(t_s) = a_s \cos \iota_s \cos \phi \cos (\Omega_t t_s - \varphi_0)$$

$$\sin \phi \sin (\Omega_t t_s - \varphi_0), \cos \iota_s \sin \phi \cos (\Omega_t t_s - \varphi_0)$$

$$- \cos \phi \sin (\Omega_t t_s - \varphi_0),$$

(34)

10 http://www.evlbi.org/user_guide/res.html
11 http://www.vlba.nrao.edu/astro/obstatus/2012-01-06/node24.html
12 The method can be easily generalized to the case of an eccentric orbit, which might be relevant for a young neutron star in a binary system.
where \( a_r > 0 \) is the orbital radius, \( \Omega_s > 0 \) is the source-frame orbital (angular) frequency, and \( \varphi_r \) (\( 0 \leq \varphi_r < 2\pi \)) is the orbital phase. For a single pair of images, we propose the following timing model:

\[
\Delta T_{ij}^{(k)} = \Delta T_{ij,0} + (K_i t_i^{(k)} - K_j t_j^{(k)}) + \frac{p_{ij}}{c} \sin \iota_s \\
\times \left[ \cos (\dot{x}_s - \dot{x}_s(t_i^{(k)})) - \cos (\dot{x}_s - \dot{x}_s(t_j^{(k)})) \right] \\
+ \frac{1}{c} [x_i \cdot d_{ij}(t_i^{(k)}) - x_j \cdot d_{ij}(t_j^{(k)})] + (1 + z_L) \frac{D_{ij}}{c D_{LS}} \\
\times [A_{ij} \cos (\Omega_s t_i^{(k)}) + B_{ij} \sin (\Omega_s t_i^{(k)})],
\]

where we define the source-frame time \( t_s \) using \( t_s = t_i^{(k)}/(1 + z_s) \). The last two terms describe a sinusoidal perturbation to the time delay due to the source’s orbital motion, parametrized by a source-frame frequency \( \Omega_s \). If \( z_s \) is not known, then only the redshifted orbital frequency \( \Omega_s/(1 + z_s) \) is measurable. The two coefficients \( A_{ij} \) and \( B_{ij} \) are dependent on the image separation as well as the orbital parameters,

\[
A_{ij} = a_r [(x_{i1} - x_{j1})(\cos \iota_s \cos \varphi_r - \sin \iota_s \sin \varphi_r) \\
+ (x_{i2} - x_{j2})(\cos \iota_s \cos \varphi_r + \sin \iota_s \sin \varphi_r)], \\
B_{ij} = b_r [(x_{i1} - x_{j1})(\cos \iota_s \sin \varphi_r - \sin \iota_s \cos \varphi_r) \\
+ (x_{i2} - x_{j2})(\cos \iota_s \sin \varphi_r + \sin \iota_s \cos \varphi_r)].
\]

A single pair of images is sufficient to infer \( \Omega_s \) (assume redshifts are known). However, at least two pairs with linearly independent image separation vectors are required to separately determine the other orbital parameters \( a_r, \iota_s, \dot{x}_s, \) and \( \varphi_r \). For three images forming two pairs \((I, J)\) and \((I, K)\), whose image separation vectors are in general not collinear, we can use a timing model containing 11 nuisance parameters plus 5 parameters that are related to source motion,

\[
(x_i, x_j, x_K, \Delta T_{ij,0}, \Delta T_{IK,0}, K_i, K_j, K_K; \Omega_s, A_{ij}, B_{ij}, A_{IK}, B_{IK}).
\]

From the last four parameters \((A_{ij}, B_{ij}, A_{IK}, B_{IK})\) we can solve for \((a_r, \iota_s, \dot{x}_s, \varphi_r)\). The corresponding likelihood reads

\[
\ln L = -\frac{1}{2} \frac{1}{\sigma^2_{\chi^2,k}} \sum_{k=1}^N \left[ (x_i^{(k)} - x_i)^2 + (x_j^{(k)} - x_j)^2 + (x_K^{(k)} - x_K)^2 \right] \\
- \frac{1}{6} \frac{1}{\sigma^2_{\chi^2,k}} \sum_{k=1}^N \left[ \delta T_{ij}^{(k)} + \delta T_{IK}^{(k)} \right]^{-1} \left[ \delta T_{ij}^{(k)} - 2 \delta T_{IK}^{(k)} \right],
\]

where the residual for a given image pair \((I, J)\) is given by

\[
\delta T_{ij}^{(k)} = t_i^{(k)} - t_j^{(k)} - \Delta T_{ij,0} - (K_i t_i^{(k)} - K_j t_j^{(k)}) - \frac{p_{ij}}{c} \sin \iota_s \\
\times \left[ \cos (\dot{x}_s - \dot{x}_s(t_i^{(k)})) - \cos (\dot{x}_s - \dot{x}_s(t_j^{(k)})) \right] \\
+ \frac{1}{c} [x_i \cdot d_{ij}(t_i^{(k)}) - x_j \cdot d_{ij}(t_j^{(k)})] + (1 + z_L) \frac{D_{ij}}{c D_{LS}} \\
\times [A_{ij} \cos (\Omega_s t_i^{(k)}) + B_{ij} \sin (\Omega_s t_i^{(k)})].
\]

Since the fitted value for \( \varphi_r \) artificially depends on the choice of zero-point for \( t_s \), it is of limited physical interest and is essentially another nuisance parameter.

In Figure 5, we give examples of how the time-delay residuals between two pairs of images would look if the source has an orbital motion on the timescale of \( \lesssim 1 \) year with a radius \( \sim 0.3-1 \) au, which is typical for a stellar companion. A repetition rate \( 0.05 \) day \(^{-1} \) is assumed throughout a 500 day observation. It can be seen that Equation (35) provides a good fit to the mock data, with source parameters solved using
Equation (36). We found that for timing accuracy $\sigma_t = 1$ ms, the orbital radius $a_s$ and the orbital period $P_s = (2 \pi) / \Omega_s$ can be recovered with good accuracy, while the orientation angles $i_s$ and $\phi_s$ are subject to large uncertainty. However, $a_s$ and $P_s$ are of major astrophysical interest here, as they imply the mass of the companion.

In Figure 6, we demonstrate how well source parameters can be typically measured from time-delay residuals, by simulating a large number of mock observations. In particular, we focus on three parameters of foremost astrophysical interest: the orbital frequency $\Omega_s$, the radius $a_s$, and the inclination $i_s$. The orbital frequency $\Omega_s$ in general can be recovered with fairly good accuracy. An observational span of 500 days is sensitive to an orbital period on the order of 0.1 au. An even longer observational span would significantly improve the measurement for the case of longer orbital period $P_s \sim 1$ year. Typically, with a timing accuracy $\sigma_t \sim 1$ ms, the orbital radius is measurable if $a_s \gtrsim 0.1$ au. Smaller orbital amplitudes produce time-delay perturbations that are too small to be recognizable. However, as shown in Figure 6, it is more difficult to determine the orbital inclination $i_s$ accurately.

In summary, source binary motion with separation on the order of $\geq 0.1$–1 au is detectable under reasonable assumptions about the quality of VLBI observation of a lensed repeater. Generally speaking, three factors can improve the measurement of the orbital motion: (1) better timing accuracy for individual bursts, (2) longer observational span, and (3) detection of more repetitions.

For another plausible situation, if the source closely orbits a massive black hole, acceleration transverse to the line of sight will induce a quadratic deviation from simple linear drift in the lensing time delay, which should be detectable if acceleration generates additional transverse displacement that accumulates to $\gtrsim 0.1$ au over the observational time span. For an order-of-magnitude estimate, the additional displacement is given by

$$
\Delta \delta \sim \frac{G M_{\text{BH}}}{R^2} \left( \frac{T_{\text{obs}}}{1 + z_S} \right)^2 \approx 0.6 \text{ au} \left( \frac{10^6 M_\odot}{M_{\text{BH}}} \right) \times \left( \frac{0.1 \text{ pc}}{R} \right)^2 \left( \frac{T_{\text{obs}}}{5 \text{ year}} \right)^2 \left( \frac{2}{1 + z_S} \right)^2,
$$

(40)

where $M_{\text{BH}}$ is the black hole mass and $R$ is the typical distance to the black hole. In this case, the orbital period is roughly

$$
2 \pi \left( \frac{R^3}{G M_{\text{BH}}} \right)^{1/2} \approx 3000 \text{ year} \left( \frac{R}{0.1 \text{ pc}} \right)^{3/2} \left( \frac{10^6 M_\odot}{M_{\text{BH}}} \right)^{1/2},
$$

(41)

much longer than the observational time span.

7. Discussion

Our method is based on the assumption that time of arrival can be measured to an accuracy $\sim 1$ ms. However, a received (de-dispersed) pulse could still be broadened, due to either gravitational microlensing by stars in the lens galaxy, or scattering by the inhomogeneous ISM in the lens galaxy.

To address these issues, in Section 7.1, we first discuss the monochromatic effect of microlensing on pulse broadening and show that it is most likely unimportant. Then, in Section 7.2, we estimate scattering broadening by the ISM of the lens galaxy, which may adversely affect detection and timing at low frequencies. Finally, in Section 7.3, we discuss angular broadening of the source due to scattering in the host galaxy.
7.1. Broadening Due to Microlensing

Taking the same example \((z_L = 0.5 \text{ and } z_S = 1)\) as in Section 4, the critical surface mass density is given by 
\[
\Sigma_{\text{crit}} = \frac{c^2}{(4 \pi G D_L D_S)} \simeq 3000 M_\odot \text{ pc}^{-2}.
\]
We define the optical depth for microlensing as \(\tau_s = \Sigma_s / \Sigma_{\text{crit}}\), where \(\Sigma_s\) is the surface mass density of stars (including stars of all evolution stages and compact objects). If the image is behind the outskirts of the lens galaxy, we have \(\tau_s \ll 1\), and at most one star may cause microlensing. Then the delayed time between the two micro-images is given by
\[
\Delta t_{\text{ML, thin}} \simeq \frac{2 r_E^2}{D_L c} \simeq 7 \times 10^{-3} \text{ ms},
\]
where
\[
r_E = \left(\frac{4 G M_\odot}{c^2} \frac{D_L D_S}{D_S}\right)^{1/2} \simeq 2 \times 10^{16} \text{ cm}
\]

Figure 6. 1σ and 2σ joint spread in the maximum-likelihood estimation for the source’s orbital frequency \(\Omega_s\), semimajor axis \(a_s\), and inclination \(i_s\), derived by simulating 500 independent observations. Taking the strong lensing configuration of Figure 2, we use time delays between two image pairs, \((a, b)\) and \((a, d)\), simultaneously. We assume a repetition rate \(0.05 \text{ day}^{-1}\), timing accuracy \(\sigma_t = 1 \text{ ms}\), and image localization accuracy \(\sigma_q = 5 \text{ mas}\). Two different lengths of observation are in comparison: 500 days (orange) and 1000 days (blue). The upper panels are for the case \(P = 0.2 \text{ year}\) and \(a = 0.3 \text{ au}\), and the lower panels are for the case \(P = 0.8 \text{ year}\) and \(a = 1.0 \text{ au}\). In all cases we fix \(i_s = 0.3, \phi_s = 0.7, \text{ and } \phi_s = 0.9\). In each panel, a black cross marks the correct values for the source orbital parameters.
is the Einstein radius, and we have taken an average stellar mass $M_\star = 0.4 \, M_{\odot}$. On the other hand, if radio waves pass within the central few kpc of the lens galaxy, microlensing optical depth may reach order unity. Then multiple microlenses may be strongly coupled and 90% of the flux from numerous micro-images spread out to a typical angular scale of (Katz et al. 1986)

$$\Delta \theta_{\text{ML}, \pm} = 3 \left( \frac{2}{D_L} \gamma \frac{\sigma_k^{1/2}}{[1 - \sigma_k \pm \gamma]} \right), \quad (44)$$

where $\gamma$ is the local macrolensing shear and “±” correspond to the two principal directions that diagonalize the macrolensing distortion matrix $\partial \delta / \partial x$. The surface brightness beyond this angular scale decreases rapidly as distance to the fourth power. The temporal broadening of the FRB is given by the maximum time delay between the micro-images

$$\Delta t_{\text{ML}, \text{thick}} \approx 3 \left[ \max(\Delta t_{\text{ML}, +}, \Delta t_{\text{ML}, -}) \right] L_D / c \approx 10 \, \sigma_k \max \frac{1}{(1 - \sigma_k - \gamma)^2} \times \Delta t_{\text{ML}, \text{thin}} \approx 10 \, \sigma_k \max.$$ \quad (45)

According to Equation (45), only near caustics $\sigma_k + \gamma$ or $\sigma_k - \gamma$ may become close to 1, and then the macro-image can be broadened by more than $\sim$ms. Therefore significant microlensing broadening is expected to occur only rarely.

### 7.2. Scattering Broadening by the Lens Galaxy

Next we consider scattering broadening due to the ISM of the lens galaxy. The observed wavefront of a point source at the lens plane due to turbulent electron density fluctuations, the power spectrum of which follows a power-law between some inner length scale $l_0 \lesssim 100$ km (Spangler & Gwinn 1990; Armstrong et al. 1995) and some outer length scale $L_0 \gtrsim 100$ pc (Armstrong et al. 1995). If we assume a Kolmogorov spectrum (power-law index $\beta = 11/3$) and a spiral galaxy like the Milky Way, the amplitude of the turbulence per unit length is given by (Armstrong et al. 1995)

$$C_N^2 = \frac{(\beta - 3) \rho_{\text{me}, L_0} - \beta}{2(2\pi)^{3-\beta}} \approx (8.5 \times 10^{-5} \, \text{m}^{-20/3} n_{\text{me}, -1.5} L_0^{-2/3})^{6/5}.$$ \quad (46)

where $n_{\text{me}} = n_{\text{me}, -1.5} 10^{-1.5} \text{ cm}^{-3} = \langle \delta n_e^2 \rangle^{1/2}$ is the root-mean-square (rms) electron density and $L_0 = 0.2 \text{ pc}$ is the outer scale. The scattering mean (strength of scattering) is given by the turbulence amplitude $C_N^2$ multiplied by the path length through the lens galaxy $L_{\text{gal}} = L_{\text{gal, kpc}} \text{ kpc}$—that is, $SM \approx (8.5 \times 10^{-5} \, \text{kpc} \, \text{ m}^{-20/3} n_{\text{me}, -1.5} L_0^{-2/3})^{6/5}$. Note that typical lines of sight perpendicular to the Milky Way disk in the solar neighborhood have $SM \approx 10^{-4} \, \text{kpc} \, \text{ m}^{-20/3}$ and the mean number density (pulsars’ DMs divided by their distances) $n_k \sim 10^{-1.5} \, \text{cm}^{-3}$ (Cordes & Lazio 2003). In fact, the lens galaxy is more likely a giant elliptical with little star formation but significant gas content dominated by hot ionized medium ($T \sim 1$ keV). Compared with the Milky Way, the gas density of a giant elliptical is typically lower, $n_k \sim 10^{-2} \, \text{cm}^{-3}$, but the path length is longer, $L_{\text{gal}} \gtrsim 10 \, \text{kpc}$ (Mathews & Brighenti 2003). There have been observational evidences for angular broadening of strongly lensed extragalactic radio sources due to scattering in the lens (Jones et al. 1996; Marlow et al. 1999; Winn et al. 2003b; Biggs et al. 2004), although in many cases the lens galaxy is confirmed or suspected to be of late-type. In fact, we know very little about the turbulent density fluctuations $\langle \delta n_e^2 \rangle^{1/2} / (n_e)$ in giant elliptical galaxies (or in general any galaxies other than our own), so it is unclear whether the scattering measure is larger or smaller than the estimate provided here. To be conservative, in the following we take $SM = 10^{-3} \, \text{kpc} \, \text{ m}^{-20/3}$ as our fiducial value.

In our case, the diffusive length $r_{\text{diff}}$ over which the rms phase variation due to scattering equals 1 radian is greater than the inner scale $l_0$, so we have (Narayan 1992; Macquart & Koay 2013)

$$r_{\text{diff}} \approx (3.2 \times 10^9 \, \text{cm})(1 + z_L)^{6/5} \rho_\odot^{6/5}.$$ \quad (47)

Incoming radio waves are scattered into an angle $\theta_{\text{scat}} \approx \lambda / \left( 2 \pi r_{\text{diff}}(1 + z_L) \right)$, and the temporal broadening is given by

$$\tau \approx \frac{(1 + z_L) D_{\text{eff}} \theta_{\text{scat}}^2}{c}.$$ \quad (48)

where $D_{\text{eff}} = D_c D_{\text{LS}} / D_\odot$. Taking $z_L = 0.5$ and $z_L = 1.0$ for the example in Section 4, we have $D_{\text{eff}} = 533 \, \text{Mpc}$, and the temporal broadening is

$$\tau \approx (31 \, \text{ms}) \rho_\odot^{4.4} \left( \frac{SM}{10^{-3} \, \text{kpc} \, \text{ m}^{-20/3}} \right)^{6/5} \left( \frac{1 + z_L}{1.5} \right)^{-4.4}.$$ \quad (49)

The angular broadening is given by $(D_{\text{LS}} / D_\odot) \theta_{\text{scat}} \approx (0.17 \, \text{mas}) \rho_\odot^{2.2} (1 + z_L)^{2.2} (SM / 10^{-3} \, \text{kpc} \, \text{ m}^{-20/3})^{3/5}$, which may be resolved by VLBI at sufficiently low frequencies.

This analysis suggests that scattering broadening by the lens galaxy is enhanced by the cosmological distance leverage. It may strongly limit the accuracy of delay-time measurement, and more importantly, some of the images may have a fluence too temporally spread out to be detectable at all. However, as can be seen in Equation (49), scattering broadening is rapidly suppressed toward higher frequencies. For instance, observing at 3 GHz instead of 1 GHz reduces temporal broadening by a factor of $3^{-4.4} \approx 8 \times 10^{-3}$ for Kolmogorov turbulence $\beta = 11/3$, bringing down the temporal broadening to $\tau \approx 0.25 \, \text{ms}$. Thus the method described in this paper will still be useful at a few GHz, which is accessible at SKA1 and at many of the VLBI instruments. In fact, going to higher frequencies decreases not only scattering broadening but also intraban dispersion, so pulse time of arrival may be measured to an accuracy better than $\sim$1 ms.

Even though accurate timing may not be achievable for survey telescopes at low frequencies $\lesssim 1$ GHz (such as CHIME and UTMOST), they may still be able to detect lensed bursts.
(albeit severely broadened). Note that the signal-to-noise ratio depends on both the fluence $F$ and de-dispersed pulse width $\tau$ as $S/N \propto F^{1/2} \tau^{-1/2}$. Given the fact that many bursts with duration $\sim 10 \text{ ms}$ have been detected (e.g., Champion et al. 2016; Caleb et al. 2017b), further broadening by a factor of $\sim 10$ (to $10^2 \text{ ms}$) will decrease $S/N$ by a factor of $\sim 3$ (the fluence is unchanged). Future telescopes may be a factor of a few more sensitive than current ones. Moreover, strongly lensed images typically have magnification factors of a few. Therefore it is entirely possible to at least detect strongly lensed (and temporally broadened) FRBs at $\lesssim 1 \text{ GHz}$. On the other hand, we strongly encourage carrying out blind FRBs surveys at higher frequencies ($\gtrsim 3 \text{ GHz}$) and increasing the maximum pulse width within which FRBs are being searched for. Turning the argument around, abnormally large burst width may be a hint for an intervening lens galaxy.

7.3. Scattering in the Host Galaxy

The assumption of a point source for the computation of galaxy lensing could be invalidated by significant scattering in the host galaxy. A large fraction ($\sim 1/2$) of known FRBs show frequency-dependent asymmetric pulse broadening, with scattering times at $\sim 1–10 \text{ ms}$ at $1 \text{ GHz}$ (Cordes et al. 2016). The scattering is inconsistent with being due to the Milky Way along the observed lines of sight or due to the IGM (Luan & Goldreich 2014; Masui et al. 2015; Cordes et al. 2016; Xu & Zhang 2016). In the strong scattering regime, scattering in the host galaxy by an effective thin screen at a distance $D_h$ from the source with typical scattering angle $\theta_{\text{sca,h}}$ gives rise to temporal broadening

$$\tau_\ell \simeq \frac{D_h \theta_{\text{sca,h}}^2}{c} \quad (50)$$

and a larger source size

$$\ell_s \simeq D_h \theta_{\text{sca,h}} \simeq \sqrt{D_h \tau_{\text{sca,h}}} \simeq (1 \times 10^{13} \text{ cm}) D_{h,\text{pc}}^{1/2} \tau_{\text{h,ms}}^{1/2} \quad (51)$$

where $D_{h,\text{pc}} = D_h / \text{pc}$ and $\tau_{\text{h,ms}} = \tau_h / \text{ms}$. For a lensed image with a deflection angle $\alpha \sim 1^\circ$, the additional temporal broadening due to lensing is (cf. Equation (24))

$$\tau_\ell \sim \frac{\alpha \ell_s}{c} \approx (1.6 \text{ ms}) \left(\frac{\alpha}{1^\circ}\right) D_{h,\text{pc}}^{1/2} \tau_{\text{h,ms}}^{1/2}$$

Since $\tau_\ell \propto \nu^{-4}$, the temporal broadening due to lensing scales is $\tau_\ell \propto \nu^{-2}$, which can potentially be used to probe the location of the scattering screen (e.g., either near the progenitor $D_h \sim \text{pc}$, or far in the ISM $D_h \sim \text{kpc}$). At sufficiently high frequencies ($\gtrsim 3 \text{ GHz}$), both $\tau_{\text{sca}}$ and $\tau_\ell$ become negligible compared with the intrinsic width, and the method proposed in earlier sections is still applicable.

Dense ISM in the host galaxy might cause large but coherent refraction, which deflects the propagation of radio waves. Due to relative peculiar motions between the source, the lens, and the Earth, the light ray samples the inhomogeneous distribution of free electrons. As a result, from the perspective of the lens, the apparent location of the emission spot can have random shifts transverse to the line of sight. Sufficiently large apparent shifts may imprint stochastic perturbations in the time delay, in a way similar to the scenario of Section 6.1.

8. Conclusion

With good prospects for detecting a large number of FRBs at cosmological redshifts using forthcoming radio telescopes, finding strongly lensed sources is not unthinkable. Moreover, it is possible that repetition is a generic feature for FRBs. In that case, a multiply imaged repeater, if uncovered from the burst catalog, would enable the measurement of time delay to millisecond accuracy.

In this paper, we have worked out how the motions of the Earth, the lens galaxy, and the source generate perturbations to the time delay for a generic lensing configuration. The orbital motion of the Earth induces a large sinusoidal modulation to the delay time $\sim 10^3 \text{ s}$, which may be used to narrow down source position in the case of poor sky localization. More interestingly, if VLBI follow-ups resolve multiple images, time-delay perturbations can be used to probe non-uniform source motion, hence providing valuable information about the astrophysical details of the source. For that purpose, the effects of unknown cosmic peculiar motions for the source and the lens are modeled as linear drift in the delay, and then the effect of the Earth’s orbital motion is accurately subtracted. Our proposed method relies entirely on direct observables and does not require modeling of the lens.

Using mock observations, we have demonstrated that source orbital motion with a size $\gtrsim 0.1–1 \text{ au}$ on a timescale $\sim 1 \text{ year}$ is measurable, assuming a timing accuracy of $\sim 1 \text{ ms}$. This is based on a conservative repetition rate $\sim 0.05 \text{ day}^{-1}$ and only requires monitoring repetitions for $1–2 \text{ years}$. Key orbital parameters such as the orbital period and semimajor axis can be recovered. This will reveal the possible existence of a stellar companion if FRBs require a compact star in a special environment. For other FRB mechanisms, source regions may vary across a distance $\gtrsim 1 \text{ au}$. These scenarios will also be constrained by time-delay perturbations. Moreover, refraction by dense materials in the host system may cause apparent shifts in the source location as viewed from the lens, which may also leave noticeable imprints in the lensing delay time.

At low frequencies $\lesssim 1 \text{ GHz}$, scattering broadening to $\gtrsim 30 \text{ ms}$ by the lens galaxy could degrade timing accuracy. The effect is significantly larger than scattering in the host galaxy and in the Milky Way. If this does not completely prevent detection, large scattering broadening should hint at intervening objects and hence strong lensing event. Therefore extending burst search to larger burst widths can be useful for finding lensed FRBs. As long as a lensed source is found, scattering broadening should not pose an issue at high frequencies $\gtrsim 3 \text{ GHz}$.

Finally, we note that even with scattering broadening, timing accuracy for FRBs much better than $\sim 1 \text{ ms}$ may be possible through the technique of de-scattering the voltage time series (i.e., the voltage signal as a function of time at the receiver) using bright bursts (Pen & Yang 2015; Main et al. 2017), if bursts are intrinsically very narrow. In that case, non-trivial source motion on scales smaller than $0.1–1 \text{ au}$ may be probed. At such a high degree of timing accuracy, further study is needed to see if the time delay models introduced here are sufficient.

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