A Dirty Model for Multiple Sparse Regression

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Abstract—Sparse linear regression – finding an unknown vector from linear measurements – is now known to be possible with fewer samples than variables, via methods like the LASSO. We consider the multiple sparse linear regression problem, where several related vectors – with partially shared support sets – have to be recovered. A natural question in this setting is whether one can use the sharing to further decrease the overall number of samples required. A line of recent research has studied the use of \( \ell_1/\ell_q \) norm block-regularizations with \( q > 1 \) for such problems; however these could actually perform worse in sample complexity – vis a vis solving each problem separately ignoring sharing – depending on the level of sharing.

We present a new method for multiple sparse linear regression that can leverage support and parameter overlap when it exists, but not pay a penalty when it does not. A very simple idea: we decompose the parameters into two components and regularize these differently. We show both theoretically and empirically, our method strictly and noticeably outperforms both \( \ell_1 \) or \( \ell_1/\ell_q \) methods, over the entire range of possible overlaps (except at boundary cases, where we match the best method). We also provide theoretical guarantees that the method performs well under high-dimensional scaling.

Index Terms—Multi-task Learning, High-dimensional Statistics, Multiple Regression.

I. INTRODUCTION: MOTIVATION AND SETUP

High-dimensional scaling. In fields across science and engineering, we are increasingly faced with problems where the number of variables or features \( p \) is larger than the number of observations \( n \). Under such high-dimensional scaling, for any hope of statistically consistent estimation, it becomes vital to leverage any potential structure in the problem such as sparsity (e.g. in compressed sensing [3] and LASSO [17]), low-rank structure [12,16], or sparse graphical model structure [15]. It is in such high-dimensional contexts in particular that multi-task learning [4] could be most useful. Here, multiple tasks share some common structure such as sparsity, and estimating these tasks jointly by leveraging this common structure could be more statistically efficient.

Block-sparse Multiple Regression. A common multi-task learning setting, and which is the focus of this paper, is that of multiple regression, where we have \( r > 1 \) response variables, and a common set of \( p \) features or covariates. The \( r \) tasks could share certain aspects of their underlying distributions, such as common variance, but the setting we focus on in this paper is where the response variables have simultaneously sparse structure: the index set of relevant features for each task is sparse; and there is a large overlap of these relevant features across the different regression problems. Such “simultaneous sparsity” arises in a variety of contexts [18]; indeed, most applications of sparse signal recovery in contexts ranging from graphical model learning, kernel learning, and function estimation have natural extensions to the simultaneous-sparse setting [15,2,14].

It is useful to represent the multiple regression parameters via a matrix, where each column corresponds to a task, and each row to a feature. Having simultaneous sparse structure then corresponds to the matrix being largely “block-sparse” – where each row is either all zero or mostly non-zero, and the number of non-zero rows is small. A lot of recent research in this setting has focused on \( \ell_1/\ell_q \) norm regularizations, for \( q > 1 \), that encourage the parameter matrix to have such block-sparse structure. Particular examples include results using the \( \ell_1/\ell_\infty \) norm [19,3,11], and the \( \ell_1/\ell_2 \) norm [10,13].

Our Model. Block-regularization is “heavy-handed” in two ways. By strictly encouraging shared-sparsity, it assumes that all relevant features are shared, and hence suffers under settings, arguably more realistic, where each task depends on features specific to itself in addition to the ones that are common. The second concern with such block-sparse regularizers is that the \( \ell_1/\ell_q \) norms can be shown to encourage the entries in the non-sparse rows taking nearly identical values. Thus we are far away from the original goal of multitask learning: not only do the set of relevant features have to be exactly the same, but their values have to as well. Indeed recent research into such regularized methods [11,13] caution against the use of block-regularization in regimes where the supports and values of the parameters for each task can vary widely. Since the true parameter values are unknown, that would be a worrisome caveat.

We thus ask the question: can we learn multiple regression models by leveraging whatever overlap of features there exist, and without requiring the parameter values to be near identical? Indeed this is an instance of a more general question on whether we can estimate statistical models where the data may not fall cleanly into any one structural bracket (sparse, block-sparse and so on). With the explosion of complex and dirty high-dimensional data in modern settings, it is vital to investigate estimation of corresponding dirty models, which might require new approaches to biased high-dimensional estimation. In this paper we take a first step, focusing on such dirty models for a specific problem: simultaneously sparse multiple regression.

Our approach uses a simple idea: while any one structure might not capture the data, a superposition of structural classes might. Our method thus searches for a parameter matrix that can be decomposed into a row-sparse matrix (corresponding to the overlapping or shared features) and an elementwise sparse matrix (corresponding to the non-shared features). As we show both theoretically and empirically, with this simple fix we are able to leverage any extent of shared features, while
allowing disparities in support and values of the parameters, so that we are *always* better than both the Lasso or block-sparse regularizers (at times remarkably so).

The rest of the paper is organized as follows: In Sec 2, basic definitions and setup of the problem are presented. Main results of the paper is discussed in sec 3. Experimental results and simulations are demonstrated in Sec 4.

**Notation:** For any matrix $M$, we denote its $j^{th}$ row as $m_j$, and its $k$-th column as $m(k)$. The set of all non-zero rows (i.e. all rows with at least one non-zero element) is denoted by $\text{RowSupp}(M)$ and its support by $\text{Supp}(M)$. Also, for any matrix $M$, let $\|M\|_{1,1} := \sum_j, k |m_{j,k}|$, i.e. the sums of absolute values of the elements, and $\|M\|_{1,\infty} := \sum_j \|m_j\|_{\infty}$ where, $\|m_j\|_{\infty} := \max_k |m_{j,k}|$.

### II. Problem Set-up and Our Method

**Multiple regression.** We consider the following standard multiple linear regression model:

$$y(k) = X(k)\hat{\Theta}(k) + w(k), \quad k = 1, \ldots, r,$$

where, $y(k) \in \mathbb{R}^n$ is the response for the $k$-th task, regressed on the design matrix $X(k) \in \mathbb{R}^{n \times p}$ (possibly different across tasks), while $w(k) \in \mathbb{R}^n$ is the noise vector. We assume each $w(k)$ is drawn independently from $\mathcal{N}(0, \sigma^2)$. The total number of tasks or target variables is $r$, the number of features is $p$, while the number of samples we have for each task is $n$. For notational convenience, we collate these quantities into matrices $Y \in \mathbb{R}^{n \times r}$ for the responses, $\hat{\Theta} \in \mathbb{R}^{p \times r}$ for the regression parameters and $W \in \mathbb{R}^{n \times r}$ for the noise.

**Our Model.** In this paper we are interested in estimating the true parameter $\hat{\Theta}$ from data $\{y(k), X(k)\}$ by leveraging any (unknown) extent of simultaneous-sparsity. In particular, certain rows of $\Theta$ would have many non-zero entries, corresponding to features shared by several tasks ("shared" rows), while certain rows would be elementwise sparse, corresponding to those features which are relevant for some tasks but not all ("non-shared rows"), while certain rows would have all zero entries, corresponding to those features that are not relevant to any task. We are interested in estimators $\hat{\Theta}$ that automatically adapt to different levels of sharedness, and yet enjoy the following guarantees:

**Support recovery:** We say an estimator $\hat{\Theta}$ successfully recovers the true signed support if $\text{sign}(\text{Supp}(\hat{\Theta})) = \text{sign}(\text{Supp}(\hat{\Theta}))$. We are interested in deriving sufficient conditions under which the estimator succeed. We note that this is stronger than merely recovering the row-support of $\hat{\Theta}$, which is union of its supports for the different tasks. In particular, denoting $U_k$ for the support of the $k$-th column of $\hat{\Theta}$, and $U = \bigcup_k U_k$.

**Error bounds:** We are also interested in providing bounds on the elementwise $\ell_\infty$ norm error of the estimator $\hat{\Theta}$,

$$\|\hat{\Theta} - \Theta\|_\infty = \max_{j=1, \ldots, p} \max_{k=1, \ldots, r} |\hat{\Theta}_{j,k} - \Theta_{j,k}|.$$  

### A. Our Method

Our method models the unknown parameter $\Theta$ as a superposition of a block-sparse matrix $B$ (corresponding to the features shared across many tasks) and a sparse matrix $S$ (corresponding to the features shared across few tasks). We estimate the sum of two parameter matrices $B$ and $S$ with different regularizations for each: encouraging block-structured row-sparsity in $B$ and elementwise sparsity in $S$. The corresponding simple models would either just use block-sparse regularizations \[11\] \[13\] or just elementwise sparsity regularizations \[17\] \[21\], so that either method would perform better in certain suited regimes. Interestingly, as we will see in the main results, by explicitly allowing to have both block-sparse and elementwise sparse component (see Algorithm \[II-A\]), we are able to *outperform both classes* of these “clean models”, for *all regimes* $\Theta$.

### III. Main Results and Their Consequences

We now provide precise statements of our main results. A number of recent results have shown that the Lasso \[17\] \[21\] and $\ell_1/\ell_\infty$ block-regularization \[11\] methods succeed in model selection, i.e., recovering signed supports with controlled error bounds under high-dimensional scaling regimes. Our first two theorems extend these results to our model setting. In Theorem 1 we consider the case of deterministic design matrices $X(k)$, and provide sufficient conditions guaranteeing signed support recovery, and elementwise $\ell_\infty$ norm error bounds. In Theorem 2 we specialize this theorem to the case where the rows of the design matrices are random from a general zero mean Gaussian distribution: this allows us to provide scaling on the number of observations required in order to guarantee signed support recovery and bounded elementwise $\ell_\infty$ norm error.

Our third result is the most interesting in that it explicitly quantifies the performance gains of our method vis-a-vis Lasso and the $\ell_1/\ell_\infty$ block-regularization method. Since this entailed finding the precise constants underlying earlier theorems, and a correspondingly more delicate analysis, we follow Negahban and Wainwright \[11\] and focus on the case where there are two-tasks (i.e. $r = 2$), and where we have standard Gaussian design matrices as in Theorem 2. Further, while each of two-tasks depends on $s$ features, only a fraction $\alpha$ of these are common. It is then interesting to see how the behaviors of the different regularization methods vary with the extent of overlap $\alpha$.

**Comparisons.** Negahban and Wainwright \[11\] show that there is actually a “phase transition” in the scaling of the probability of successful signed support-recovery with the number of observations. Denote a particular rescaling of the sample-size $\theta_{\text{Lasso}}(n, p, \alpha) = \frac{n}{\log(p-\alpha s)}$. Then as Wainwright \[21\] show, when the rescaled number of samples scales as $\theta_{\text{Lasso}} > 2 + \delta$ for any $\delta > 0$, Lasso succeeds in recovering the signed support of all columns with probability converging to one. But when the sample size scales as $\theta_{\text{Lasso}} < 2 - \delta$ for any $\delta > 0$, Lasso fails with probability converging to one. For the $\ell_1/\ell_\infty$-regularized multiple linear regression, define a similar rescaled sample size $\theta_{1,\infty}(n, p, \alpha) = \frac{n}{\log(p^2 - 2\alpha s)}$. Then as
Algorithm 1 Complex Block Sparse

Solve the following convex optimization problem:
\[
(\hat{S}, \hat{B}) \in \arg \min_{S,B} \frac{1}{2n} \sum_{k=1}^{r} \left\| y^{(k)} - X^{(k)} \left( \hat{s}^{(k)} + \hat{b}^{(k)} \right) \right\|_2^2 + \lambda_a \|S\|_{1,1} + \lambda_b \|B\|_{1,\infty}.
\] (1)

Then output \( \hat{\Theta} = \hat{B} + \hat{S} \).

Negahban and Wainwright [11] show there is again a transition in probability of success from near zero to near one, at the rescaled sample size of \( \theta_{1,\infty} = (4 - 3\alpha) \). Thus, for \( \alpha < 2/3 \) ("less sharing") Lasso would perform better since its transition is at a smaller sample size, while for \( \alpha > 2/3 \) ("more sharing") the \( \ell_1/\ell_\infty \) regularized method would perform better.

As we show in our third theorem, the phase transition for our method occurs at the rescaled sample size of \( \theta_{1,\infty} = (2 - \alpha) \), which is strictly before either the Lasso or the \( \ell_1/\ell_\infty \) regularized method except for the boundary cases: \( \alpha = 0 \), i.e. the case of no sharing, where we match Lasso, and for \( \alpha = 1 \), i.e. full sharing, where we match \( \ell_1/\ell_\infty \). Everywhere else, we strictly outperform both methods. Figure III shows the empirical performance of each of the three methods; as can be seen, they agree very well with the theoretical analysis. (Further details in the experiments Section V).

A. Sufficient Conditions for Deterministic Designs

We first consider the case where the design matrices \( X^{(k)} \) for \( k = 1, \ldots, r \) are deterministic, and start by specifying the assumptions we impose on the model. We note that similar sufficient conditions for the deterministic \( X^{(k)} \)'s case were imposed in papers analyzing Lasso [21] and block-regularization methods [11, 13].

A0 Column Normalization: \( \|X^{(k)}\|_2 \leq \sqrt{2n} \) for all \( j = 1, \ldots, p \) and \( k = 1, \ldots, r \).

A1 Incoherence Condition:
\[
\gamma_b := 1 - \max_{j \in \mathcal{U}} \sum_{k=1}^{r} \left\| X_j^{(k)} \right\|_1 > 0,
\]
where \( \mathcal{U}_k \) denotes the support of the \( k \)-th column of \( \hat{\Theta} \) and \( \mathcal{U} = \bigcup_{k=1}^{r} \mathcal{U}_k \) denotes the union of the supports of all tasks. We will also find it useful to define
\[
\gamma_a := 1 - \max_{1 \leq k \leq r} \max_{j \in \mathcal{U}_k} \left\| X_{jk}^{(k)} \right\|_1.
\]
Note that by the incoherence condition A1, we have \( \gamma_a > 0 \).

A2 Minimum Curvature Condition:
\[
C_{\min} := \min_{1 \leq k \leq r} \lambda_{\min} \left( \frac{1}{n} \left( X_{kk}^{(k)} \right) \right) > 0.
\]
Also, define \( D_{\max} := \max_{1 \leq k \leq r} \left\| \frac{1}{n} \left( X_{kk}^{(k)} \right) \right\|_{\infty,1} \). As a consequence of A2, we have that \( D_{\max} \) is finite.

A3 Regularizers: We require the regularization parameters satisfy
\[
\begin{align*}
A3-1 & \quad \lambda_a > \frac{(2 - \gamma_a) \sqrt{\log(pr)}}{\gamma_a \sqrt{n}}, \\
A3-2 & \quad \lambda_b > \frac{(2 - \gamma_a) \sqrt{\log(pr)}}{\gamma_b \sqrt{n}}, \\
A3-3 & \quad 1 \leq \frac{\alpha}{\gamma_a} \leq r \text{ and } \frac{\alpha}{\gamma_a} \text{ is not an integer (see Lemma 11 and 12 for the reason).}
\end{align*}
\]

Theorem 1. Suppose A0-A3 hold, and that we obtain estimate \( \hat{\Theta} \) from our algorithm. Then, with probability at least \( 1 - c_1 \exp(-c_2 n) \), we are guaranteed that the convex program (7) has a unique optimum and
(a) The estimate \( \hat{\Theta} \) has no false inclusions, and has bounded \( \ell_\infty \) norm error:
\[
\| \hat{\Theta} - \Theta \|_{\infty} \leq \sqrt{\frac{4\sigma^2 \log(pr)}{n \ C_{\min}}} + \lambda_a D_{\max}.
\] (2)
(b) The estimate \( \hat{\Theta} \) has no false exclusions, i.e., \( \text{sign}(\text{Supp}(\hat{\Theta})) = \text{sign}(\text{Supp}(\Theta)) \) provided that
\[
\min_{(j,k) \in \text{Supp}(\Theta)} \left\| \delta_{jk}^{(k)} \right\|_1 > b_{\min} \text{ for } b_{\min} \text{ defined in part (a).}
\]
The positive constants \( c_1, c_2 \) depend only on \( \gamma_a, \gamma_b, \lambda_a, \lambda_b \) and \( \sigma \), but are otherwise independent of \( n, p, r \), the problem dimensions of interest.

Remark: Condition (a) guarantees that the estimate will have no false inclusions; i.e. all included features will be relevant. If in addition, we require that it have no false exclusions and that recover the support exactly, we need to impose the assumption in (b) that the non-zero elements are large enough to be detectable above the noise.

B. General Gaussian Designs

Often the design matrices consist of samples from a Gaussian ensemble (e.g. in Gaussian graphical model structure learning). Suppose that for each task \( k = 1, \ldots, r \) the design matrix \( X^{(k)} \in \mathbb{R}^{n \times p} \) is such that each row \( X_i^{(k)} \in \mathbb{R}^p \) is a zero-mean Gaussian random vector with covariance matrix \( \Sigma^{(k)} \in \mathbb{R}^{p \times p} \), and is independent of every other row. Let \( \Sigma^{(k)} \in \mathbb{R}^{p \times p} \) be the submatrix of \( \Sigma^{(k)} \) with corresponding rows to \( \mathcal{V} \) and columns to \( \mathcal{U} \). We require these covariance matrices to satisfy the following conditions:

C1 Incoherence Condition:
\[
\gamma_b := 1 - \max_{j \in \mathcal{U}} \sum_{k=1}^{r} \left\| X_{jk}^{(k)} \right\|_1 > 0.
\]
Theorem 2. Suppose assumptions C1-C3 hold, and that the number of samples scale as 

\[ n > \max \left( \frac{2 \sigma^2 \log(pr)}{C_{\min}^2 \gamma^2}, \frac{2 \sigma r (r \log(2) + \log(p))}{C_{\min}^2 \gamma^2}, \frac{2 \sigma (r \log(2) + \log(p))}{C_{\min}^2} \right). \]

Suppose we obtain estimate \( \hat{\Theta} \) from our algorithm. Then, with probability at least 

\[ 1 - c_1 \exp(-c_2 (r \log(2) + \log(p))) - c_3 \exp(-c_4 \log(rs)) \to 1 \]

for some positive numbers \( c_1 - c_4 \), we are guaranteed that the algorithm estimate \( \hat{\Theta} \) is unique and satisfies the following conditions:

(a) The estimate \( \hat{\Theta} \) has no false inclusions, and has bounded \( \ell_{\infty} \) norm error so that 

\[ \| \hat{\Theta} - \Theta \|_{\infty, \infty} \leq \sqrt{\frac{4\sigma^2 \log(rs)}{nC_{\min} \sqrt{n}}} + \lambda_s \left( \frac{4s}{C_{\min} \sqrt{n}} + D_{\max} \right) \cdot g_{\min} \]

(b) The estimate \( \hat{\Theta} \) has no false exclusions, i.e., 

\[ \text{sign}(\text{Supp}(\hat{\Theta})) = \text{sign}(\text{Supp}(\Theta)) \text{ provided that} \]

\[ \min_{(j,k) \in \text{Supp}(\Theta)} |\hat{\beta}^{(k)}_{j,k} | > g_{\min} \text{for} g_{\min} \text{ defined in part (a)}. \]

C. Quantifying the gain for 2-Task Gaussian Designs

This is one of the most important results of this paper. Here, we perform a more delicate and finer analysis to establish precise quantitative gains of our method. We focus on the special case where \( r = 2 \) and the design matrix has rows generated from the standard Gaussian distribution \( N(0, I_{n \times n}) \). As we will see both analytically and experimentally, our method strictly outperforms both Lasso and \( \ell_1/\ell_{\infty} \)-block-regularization over all cases, except at the extreme endpoints of no support sharing (where it matches that of Lasso) and full support sharing (where it matches that of \( \ell_1/\ell_{\infty} \)). We now present our analytical results; the empirical comparisons...
are presented next in Section IV. The results will be in terms of a particular rescaling of the sample size $n$ as
\[ \theta(n,p,s,\alpha) := \frac{n}{(2-\alpha)s \log((p-2\alpha)s)}. \]

We also require that the regularizers satisfy
\[ F1_\lambda > \left(4\sigma^2 (1-\sqrt{s/n}) \log(p) \log(p-2\alpha) + (2\alpha s \log(p) + \log(p-2\alpha))) \right)^{1/2}. \]
\[ F2_\lambda > \left(4\sigma^2 (1-\sqrt{s/n}) r \log(p) \log(p-2\alpha) + (2\alpha s \log(p) + \log(p-2\alpha))) \right)^{1/2}. \]
\[ F3_\lambda \frac{(α)}{\sqrt{s}} = \sqrt{2}. \]

**Theorem 3.** Consider a 2-task regression problem $(n,p,s,\alpha)$, where the design matrix has rows generated from the standard Gaussian distribution $\mathcal{N}(0, I_{n \times n})$. Suppose
\[ \max_{j \in B} \left| \Theta_j^{(1)} - \Theta_j^{(2)} \right| \leq c_\lambda, \]
where $B^*$ is the submatrix of $\Theta^*$ with rows where both entries are non-zero and $c$ is a constant specified in Lemma 2. Then the estimate $\hat{\Theta}$ of the problem (1) satisfies the following:

**(Success)** Suppose the regularization coefficients satisfy $F1 - F3$. Further, assume that the number of samples scales as $\theta(n,p,s,\alpha) > 1$. Then, with probability at least $1 - c_1 \exp(-c_2 n)$ for some positive numbers $c_1$ and $c_2$, we are guaranteed that $\hat{\Theta}$ satisfies the support-recovery and $\ell_{\infty}$ error bound conditions (a-b) in Theorem 2.

**(Failure)** If $\theta(n,p,s,\alpha) < 1$ there is no solution $(\hat{B}, \hat{S})$ for any choices of $\lambda$ and $\lambda^*$ such that $\hat{\Theta} = \text{sign}(\text{Supp}(\hat{\Theta}))$.

**Remark:** The assumption on the gap $\left| \Theta_j^{(1)} - \Theta_j^{(2)} \right| \leq c_\lambda$ reflects the fact that we require that most values of $\Theta^*$ to be balanced on both tasks on the shared support. As we show in a more general theorem (Theorem 4) in Section VI-C, even in the case where the gap is large, the dependence of the sample scaling on the gap is quite weak.

### IV. Simulation Results

In this section, we provide some simulation results. First, using our synthetic data set, we investigate the consequences of Theorem 3 when we have $r = 2$ tasks to learn. As we see, the empirical result verifies our theoretical guarantees. Next, we apply our method regression to a real datasets: a handwritten digit classification dataset with $r = 10$ tasks (equal to the number of digits 0–9). For this dataset, we show that our method outperforms both LASSO and $\ell_1/\ell_\infty$ practically. For each method, the parameters are chosen via cross-validation; see supplemental material for more details.

#### A. Synthetic Data Simulation

Consider a $r = 2$-task regression problem of the form $(n,p,s,\alpha)$ as discussed in Theorem 3. For a fixed set of parameters $(n,s,p,\alpha)$, we generate 100 instances of the problem. Then, we solve the same problem using our model, $\ell_1/\ell_\infty$ regularizer and LASSO by searching for penalty regularizer coefficients independently for each one of these programs to find the best regularizer by cross validation. After solving the three problems, we compare the signed support of the solution with the true signed support and decide whether or not the program was successful in signed support recovery. We describe these process in more details in this section.

**Data Generation:** We explain how we generated the data for our simulation here. We pick three different values of $p = 128, 256, 512$ and let $s = \lfloor 0.1p \rfloor$. For different values of $\alpha$, we let $n = c \log(p-\alpha)p$ for different values of $c$. We generate a random sign matrix $\Theta^* \in \mathbb{R}^{p \times 2}$ for each entry is either $0, 1$ or $-1$ with column support size $s$ and row support size $(2\alpha)p$ as required by Theorem 3. Then, we multiply each row by a real random number with magnitude greater than the minimum required for sign support recovery by Theorem 3. We generate two sets of matrices $X^{(1)}, X^{(2)}$ and $W$ and use one of them for training and the other one for cross validation (test), subscripted $Tr$ and $Ts$, respectively. Each entry of the noise matrices $W_{Tr}, W_{Ts} \in \mathbb{R}^{s \times 2}$ is drawn independently according to $\mathcal{N}(0, \sigma^2)$ where $\sigma = 0.1$. Each row of a design matrix $X_{Tr}^{(k)}, X_{Ts}^{(k)} \in \mathbb{R}^{n \times p}$ is sampled, independent of any other rows, from $\mathcal{N}(0, I_{2 \times 2})$ for all $k = 1, 2$. Having $X^{(k)}, \Theta^*$ and $W$ in hand, we can calculate $Y_{Tr}, Y_{Ts} \in \mathbb{R}^{n \times 2}$ using the model $y^{(k)} = X^{(k)} \Theta^{(k)} + w^{(k)}$ for all $k = 1, 2$ for both train and test set of variables.

**Coordinate Descent Algorithm:** Given the generated data $X_{Tr}^{(k)}$ for $k = 1, 2$ and $Y_{Tr}$ in the previous section, we want to recover matrices $\hat{B}$ and $\hat{S}$ that satisfy (1). We use the coordinate descent algorithm to numerically solve the problem (see Appendix B). The algorithm inputs the tuple $(X_{Tr}^{(1)}, X_{Tr}^{(2)}, Y_{Tr}, \lambda^*_0, \lambda^*_s, c, B, S)$ and outputs a matrix pair $(\hat{B}, \hat{S})$. The inputs $(B, S)$ are initial guess and can be set to zero. However, when we search for optimal penalty regularizer coefficients, we can use the result for previous set of coefficients $(\lambda^*_0, \lambda^*_s)$ as a good initial guess for the next coefficients $(\lambda^*_0 + \xi, \lambda^*_s + \zeta)$. The parameter $\epsilon$ captures the stopping criterion threshold of the algorithm. We iterate inside the algorithm until the relative update change of the objective function is less than $\epsilon$. Since we do not run the algorithm completely (until $\epsilon = 0$ works), we need to filter the small magnitude values in the solution $(\hat{B}, \hat{S})$ and set them to be zero.

**Choosing penalty regularizer coefficients:** Dictated by optimality conditions, we have $1 > \frac{\lambda^*_0}{\lambda^*_s} > \frac{1}{2}$. Thus, searching range for one of the coefficients is bounded and known. We set $\lambda^*_0 = c \sqrt{\frac{\log(d)}{2n}}$ and search for $c \in [0.01, 100]$, where this interval is partitioned logarithmic. For any pair $(\lambda^*_0, \lambda^*_s)$ we compute the objective function of $Y_{Ts}$ and $X_{Ts}^{(k)}$ for $k = 1, 2$ using the filtered $(\hat{B}, \hat{S})$ from the coordinate descent algorithm. Then across all choices of $(\lambda^*_0, \lambda^*_s)$, we pick the one with minimum objective function on the test data. Finally we let $\Theta = \text{Filter}(\hat{B} + \hat{S})$ for $(\hat{B}, \hat{S})$ corresponding to the optimal $(\lambda^*_0, \lambda^*_s)$. 


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α

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1

8

2

512

L1/L∞ Regularizer

Dirty Model

Structure of the Dataset: In this dataset, there are 200 instances of handwritten digits 0-9 (totally 2000 digits). Each instance of each digit is scanned to an image of the size 30 × 48 pixels. This image is NOT provided by the dataset. Using the full resolution image of each digit, the dataset provides six different classes of features. A total of 649 features are provided for each instance of each digit. The information about each class of features is provided in Table I. The combined handwriting images of the record number 100 is shown in Fig III (ten images are concatenated together with a spacer between each two).

Fitting the dataset to our model: Regardless of the nature of the features, we have 649 features for each of 200 instance of each digit. We need to learn K = 10 different tasks corresponding to ten different digits. To make the associated numbers of features comparable, we shrink the dynamic range of each feature to the interval −1 and 1. We divide each feature by an appropriate number (perhaps larger than the maximum of that feature in the dataset) to make sure that the dynamic range of all features is a (not too small) subset of [−1, 1]. Notice that in this division process, we don’t care about the minimum and maximum of the training set. We just divide each feature by a fixed and predetermined number we provided as maximum in Table I. For example, we divide the Pixel Shape feature by 6, Karhunen-Loève coefficients by 17 or the last morphological feature by 18000 and so on. We do not shift the data; we only scale it.

Out of 200 samples provided for each digit, we take n ≤ 200 samples for training. Let X(k) = X ∈ ℜ

10n×649 for all 0 ≤ k ≤ 9 be the matrix whose first n rows correspond to the features of the digit 0, the second n rows correspond to the features of the digit 1 and so on. Consequently, we set the vector y(k) ∈ {0, 1}10n to be the vector such that y(k) = 1 if and only if the jth row of the feature matrix X corresponds to the digit k. This setup is called binary classification setup.

We want to find a block-sparse matrix B ∈ ℜ

649×10 and a sparse matrix S ∈ ℜ

649×10, so that for a given feature vector x ∈ ℜ

649 extracted from the image of a handwritten digit 0 ≤ k∗ ≤ 9, we ideally have k* = arg max0≤k≤9 x (B + S). To find such matrices B and S, we solve (I). We tune the parameters λb and λα in order to get the best result by cross validation. Since we have 10 tasks, we search for λb

α ∈ [10, 1] and let λb = c√2log(649)

n ≈ 5\sqrt{n}, where, empirically c ∈ [0.01, 10] is a constant to be searched.

Performance Analysis: Table III shows the results of our analysis for different sizes of the training set as \frac{n}{100}.
| Feature | Size  | Type   | Dynamic Range |
|---------|-------|--------|---------------|
| 1       | Pixel Shape (15 × 16) | 240   | Integer       | 0-6            |
| 2       | 2D Fourier Transform Coefficients | 74   | Real          | 0-1            |
| 3       | Karhunen-Loeve Transform Coefficients | 64   | Real          | -17:17         |
| 4       | Profile Correlation | 216   | Integer       | 0-1400         |
| 5       | Zernike Moments | 46   | Real          | 0-800          |
| 6       | Morphological Features | 3   | Integer       | 0-6            |

TABLE I

SIX DIFFERENT CLASSES OF FEATURES PROVIDED IN THE DATASET. THE DYNAMIC RANGES ARE APPROXIMATE NOT EXACT. THE DYNAMIC RANGE OF DIFFERENT MORPHOLOGICAL FEATURES ARE COMPLETELY DIFFERENT. FOR THOSE 6 MORPHOLOGICAL FEATURES, WE PROVIDE THEIR DIFFERENT DYNAMIC RANGES SEPARATELY.

$\ell_1/\ell_\infty$ regularizer method and LASSO.

V. PROOF OUTLINE

In this section we illustrate the proof outline of all three theorems as they are very similar in the nature. First, we introduce some notations and definitions and then, we provide a three step proof technique that we used to prove all three theorems.

A. Definitions and Setup

In this section, we rigorously define the terms and notation we used throughout the proofs.

Notation: For a vector $v$, the norms $\ell_1$, $\ell_2$ and $\ell_\infty$ are denoted as $\|v\|_1 = \sum_k |v^{(k)}|$, $\|v\|_2 = \sqrt{\sum_k |v^{(k)}|^2}$ and $\|v\|_\infty = \max_k |v^{(k)}|$, respectively. Also, for a matrix $Q \in \mathbb{R}^{p \times r}$, the norm $\ell_{\zeta}/\ell_\rho$ is denoted as $\|Q\|_{\rho,\zeta} = \left\| \left( \|q_1\|_{\zeta} , \cdots , \|q_p\|_{\zeta} \right) \right\|_{\rho}$. The maximum singular value of $Q$ is denoted as $\lambda_{\max}(Q)$. For a matrix $X \in \mathbb{R}^{n \times p}$ and a set of indices $U \subseteq \{1, \cdots, p\}$, the matrix $X_U \in \mathbb{R}^{n \times |U|}$ represents the sub-matrix of $X$ consisting of $X_j$'s where $j \in U$.

1) Towards Identifying Optimal Solution: This is a key step in our analysis. Our proof proceeds by choosing a pair $\hat{B}, \hat{S}$ such that the signed support of $\hat{B} + \hat{S}$ is the same as that of $\bar{\Theta}$, and then certifying that, under our assumptions, this pair is the optimum of the optimization problem (1). We construct this pair via a surrogate optimization problem – dubbed oracle problem in the literature as well as our proof outline below – which adds extra constraints to (1) in a way that ensures signed support recovery. Making the oracle problem is a key step in our proof.

For (1), let $d = \lceil \frac{\lambda_{\max}}{\lambda_{\rho}} \rceil$; in this paper we will always have $1 \leq d \leq r$, where we recall $r$ is the number of tasks. Using this $d$, we now define two matrices $B^*, S^*$, such that $B^* + S^* = \Theta$, as follows. In each row $\bar{\Theta}_j$, let $v_j$ be the $(d + 1)^{th}$ largest magnitude of the elements in $\Theta_j$. Then, the $(j,k)^{th}$ element $s_j^{*(k)}$ of the matrix $S^*$ is defined as follows

$$s_j^{*(k)} = \text{sign}(\theta_j^{(k)}) \max \left\{ 0, |\theta_j^{(k)}| - v_j \right\}$$

measure the classification error on the test set for each digit to get the 10-vector of errors. Then, we find the average error and the variance of the error vector to show how the error is distributed over all tasks. We compare our method with
In words, to obtain $S^*$ we take the matrix $\tilde{\Theta}$ and for each element we clip its magnitude to be the excess over the $(d + 1)th$ largest magnitude in its row. We retain the sign. Finally, define $B^* = \tilde{\Theta} - S^*$ to be the residual. It is thus clear that

- $S^*$ will have at most $d$ non-zero elements in each row.
- Each row of $B^*$ is either identically 0, or has at least $d$ non-zero elements. Also, in the latter case, at least $d$ of them have the same magnitude.
- If any element $(j,k)$ is non-zero in both $S^*$ and $B^*$ then its sign is the same in both.

$S^*$ thus takes on the role of the “true sparse matrix”, and $B^*$ the role of the “true block-sparse matrix”. We will use $B^*, S^*$ to construct our oracle problem later. The pair also has the following significance: our results will imply that if we have infinite samples, then $B^*, S^*$ will be the solution to \( \mathbb{I} \).

2) Sparse Matrix Setup: For any matrix $S$, define $\text{Supp}(S) = \{(j,k) : s^{(k)}_j \neq 0\}$, and let $U_s = \{ S \in \mathbb{R}^{p \times r} : \text{Supp}(S) \subseteq \text{Supp}(S^*) \}$ be the subspace of matrices whose support is the subset of the matrix $S^*$. The orthogonal projection to the subspace $U_s$ can be defined as follows:

\[
(P_{U_s}(S))_{j,k} = \begin{cases} 
  s^{(k)}_j & (j,k) \in \text{Supp}(S^*) \\
  0 & \text{ow.}
\end{cases}
\]

We can define the orthogonal complement space of $U_s$ to be $U_s^c = \{ S \in \mathbb{R}^{p \times r} : \text{Supp}(S) \cap \text{Supp}(S^*) = \emptyset \}$. The orthogonal projection to this space can be defined as $P_{U_s^c}(B) = B - P_{U_s}(B)$.

For a given matrix $B \in \mathbb{R}^{p \times r}$, let $M_j(B) = \{ k : |b^{(k)}_j| = \|b_j\|_\infty > 0 \}$ be the set of indices that the corresponding elements achieve the maximum magnitude on the $j$th row with positive or negative signs. Also, let $M(B) = \min_{1 \leq j \leq r} |M_j(B)|$ be the minimum number of elements who achieve the maximum in each row of the matrix $B$.

The following technical lemma is useful in the proof of all three theorems.

**Lemma 1.** If $(B,S) = \mathcal{H}_d(\Theta)$ then

(P1) $M(B) \geq d + 1$ and $D(S) \leq d$.
(P2) $\text{sign}(s^{(k)}_j) = \text{sign}(b^{(k)}_j)$ for all $j \in \text{RowSupp}(B)$ and $k \in M_j(B)$.
(P3) $s_j^{(k)} = 0$ for all $j \in \text{RowSupp}(B)$ and $k \notin M_j(B)$.

**Proof:** The proof follows from the definition of $\mathcal{H}$.

3) Row-Sparse Matrix Setup: For any matrix $B$, define $\text{RowSupp}(B) = \{ j : \exists k \text{ s.t. } b^{(k)}_j \neq 0 \}$, and let $U_b = \{ B \in \mathbb{R}^{p \times r} : \text{RowSupp}(B) \subseteq \text{RowSupp}(B^*) \}$ be the subspace of matrices whose row support is the subset of the row support of the matrix $B^*$. The orthogonal projection to the subspace $U_b$ can be defined as follows:

\[
(P_{U_b}(B))_j = \begin{cases} 
  b_j & j \in \text{RowSupp}(B^*) \\
  0 & \text{ow.}
\end{cases}
\]

We can define the orthogonal complement space of $U_b$ to be $U_b^c = \{ B \in \mathbb{R}^{p \times r} : \text{RowSupp}(B) \cap \text{RowSupp}(B^*) = \emptyset \}$.

The proofs of all three of our theorems follow a primal-dual witness technique, and consist of two steps, as detailed in this section. The first step constructs a primal-dual witness candidate, and is common to all three theorems. The second step consists of showing that the candidate constructed in the first step is indeed a primal-dual witness. The theorem proofs differ in this second step, and show that under the respective conditions imposed in the theorems, the construction succeeds with high probability. These steps are as follows:

**STEP 1:** Denote the true optimal solution pair $(B^*, S^*) = \mathcal{H}_d(\Theta)$ as defined in Section \([\text{V-A}]\) for $d = \lceil \frac{n}{m} \rceil$. See Lemma \([\text{I}]\) for basic properties of these matrices $B^*$ and $S^*$.

**Primal Candidate:** We can then design a candidate optimal solution $(\hat{S}, \hat{B})$ with the desired sparsity pattern using a restricted support optimization problem, called oracle problem:

| Method          | Average Classification Error | Average Support Size | Average Row Support Size |
|-----------------|------------------------------|----------------------|-------------------------|
| Our Model       | 8.6%                         | 0.57%                | B:165                   |
|                 | 9.9%                         | 0.64%                | B + S:171               |
|                 | 10.8%                        | 1.0%                 | B + S:1651              |
| LASSO           | 2165                         | 3669                 | S:18                    |
|                 | 2.2%                         | 0.56%                | B:211                   |
|                 | 3.5%                         | 0.62%                | B + S:226               |
|                 | 4.1%                         | 2.2%                 | B + S:2118              |
| S               | 368                          | 0.51%                | S:34                    |
|                 | 3.2%                         | 0.68%                | B:270                   |
|                 | 368                          | 0.85%                | B + S:299               |
|                 | 539                          | 3.5%                 | B + S:2761              |

**TABLE II**

Simulation Results for Our Model, \(\ell_1/\ell_\infty\) and LASSO.
(\bar{S}, \bar{B}) \in \arg \min_{S \in \mathcal{S}, B \in \mathcal{B}_U} \frac{1}{2n} \sum_{k=1}^r \left\| y_j^{(k)} - X_j^{(k)} (s_j^{(k)} + b_j^{(k)}) \right\|_2^2 + \lambda_s \|S\|_{1,1} + \lambda_b \|B\|_{1,\infty}.

(C2) \quad P_{U_\epsilon} (\bar{Z}) = \left\{ \begin{array}{ll} t_j^{(k)} \text{sign} \left( \hat{b}_j^{(k)} \right) & , \quad k \in M_j(B^*) \text{ a.w.} \\
0 & \end{array} \right.

\text{such that } \sum_{k \in M_j(B^*)} t_j^{(k)} = \lambda_b.

(C3) \quad \left\| P_{U_\epsilon} (\bar{Z}) \right\|_{\infty,\infty} < \lambda_s.

(C4) \quad \left\| P_{U_\epsilon} (\bar{Z}) \right\|_{\infty,1} < \lambda_b.

(C5) \quad \frac{1}{n} \left( X_j^{(k), X_k^{(k)}} \right) \left( \hat{b}_j^{(k)} + \hat{z}_j^{(k)} \right) - \frac{1}{n} (X_j^{(k)})^T y_j^{(k)} + \hat{z}_j^{(k)} = 0

Proof: By assumptions (C1) and (C3), \( \bar{Z} \in \partial \| \bar{S} \|_{1,1} \) and by assumptions (C2) and (C4), \( \frac{1}{n} \bar{Z} \in \partial \| \bar{B} \|_{1,\infty} \). Thus, \((\bar{S}, \bar{B}, \bar{Z})\) is a feasible primal-dual pair of \((\text{I})\) according to the Lemma 3.

Let \( \mathbb{B} \) and \( \mathbb{S} \) to be balls of \( \ell_\infty/\ell_1 \) and \( \ell_\infty/\ell_\infty \) with radius \( \lambda_b \) and \( \lambda_s \), respectively. Considering the fact that \( \lambda_b \|B\|_{1,\infty} = \sup_{Z \in \mathbb{B}} \|Z, B\| \) and \( \lambda_s \|S\|_{1,1} = \sup_{Z \in \mathbb{S}} \|Z, S\| \), the problem \((\text{I})\) can be written as

\[
(\bar{S}, \bar{B}) = \arg \inf_{S, B \in \mathbb{B} \cap \mathbb{S}} \sup_{Z \in \mathbb{Z}} \left\{ \frac{1}{2n} \sum_{k=1}^r \left\| y_j^{(k)} - X_j^{(k)} (b_j^{(k)} + s_j^{(k)}) \right\|_2^2 + \langle Z, S \rangle + \langle Z, B \rangle \right\}.
\]

This saddle-point problem is strictly feasible and convex-concave. To prove the dual feasibility, consider the primal optimal \((\hat{S}, \hat{B})\). We have \( \lambda_b \|\hat{B}\|_{1,\infty} = \langle \hat{Z}, \hat{B} \rangle \) and \( \lambda_s \|\hat{S}\|_{1,1} = \langle \hat{Z}, \hat{S} \rangle \). This implies that \( \hat{b}_j = 0 \) if \( \|\hat{z}_j\|_1 < \lambda_b \) (because \( \lambda_b \sum_j \|\hat{b}_j\|_\infty \leq \sum_j \|\hat{z}_j\|_1 \|\hat{b}_j\|_\infty \) and if \( \|\hat{z}_j\|_1 < \lambda_b \) for some \( j_0 \), then others can not compensate for that in the sum due to the fact that \( \hat{Z} \in \mathbb{B} \), i.e., \( \|\hat{z}_j\|_1 \leq \lambda_s \). It also implies that \( \hat{z}_j^{(k)} = 0 \) if \( \|\hat{z}_j^{(k)}\|_1 < \lambda_s \). Hence, \( P_{U_\epsilon} (\hat{B}) = 0 \) and \( P_{U_\epsilon} (\hat{S}) = 0 \). This means that solving the restricted problem \((\text{II})\) is equivalent to solving the problem \((\text{I})\).

The uniqueness follows from our (stationary) assumptions on design matrices \( X^{(k)} \) that the matrix \( \frac{1}{n} \left\langle X_j^{(k)}, X_k^{(k)} \right\rangle \) is invertible for all \( 1 \leq k \leq r \). Using this assumption, the problem \((\text{II})\) is strictly convex and the solution is unique. Consequently, the solution of \((\text{I})\) is also unique, since we showed that these two problems are equivalent. This concludes the proof of the lemma.

\[ \text{STEP 2:} \text{ This step consists of showing that the pair} \ (\bar{S}, \bar{B}, \bar{Z}) \text{ constructed in the earlier step is actually a feasible primal-dual pair of} \ (\text{I}). \text{ This would then the required support-recovery result since the constructed primal candidate} \ (\bar{S}, \bar{B}) \text{ had the required sparsity pattern by construction.} \]

We will make use of the following lemma that specifies a set of sufficient (stationary) optimality conditions for the \((\bar{S}, \bar{B})\) from \((\text{II})\) to be the unique solution of the (unrestricted) optimization problem \((\text{I})\).

Lemma 2. Under our (stationary) assumptions on the design matrices \( X^{(k)} \), the matrix pair \((\bar{S}, \bar{B})\) is the unique solution of the problem \((\text{I})\) if there exists a matrix \( \bar{Z} \in \mathbb{R}^{p \times r} \) such that

\[
\text{C1) } P_{U_\epsilon} (\bar{Z}) = \lambda_s \text{sign} (\bar{S}).
\]
VI. PROOFS

The proofs of our three main theorems are in sections VI-A, VI-B and VI-C respectively.

A. Proof of Theorem 1

Let $d = \lfloor \frac{\Delta}{\Delta^*} \rfloor$ and $(B^*, S^*) = \mathcal{H}_d(\Theta)$. Then, the result follows from Proposition 1 below.

**Proposition 1 (Structure Recovery).** Under assumptions of Theorem 1, with probability $1 - c_1 \exp(-c_2 n)$ for some positive constants $c_1$ and $c_2$, we are guaranteed that the following properties hold:

(P1) Problem (1) has unique solution $(\hat{S}, \hat{B})$ such that $\text{Supp}(\hat{S}) \subseteq \text{Supp}(S^*)$ and $\text{RowSupp}(\hat{B}) \subseteq \text{RowSupp}(B^*)$.

(P2) $\left\| \hat{B} + \hat{S} - B^* - S^* \right\|_{\infty} \leq \sqrt{\frac{4\sigma^2 \log(pr)}{C_{\min} n} + \lambda_s D_{\max}}$.

(P3) $\text{sign}(\text{Supp}(\hat{s}_j)) = \text{sign}(\text{Supp}(s_j^*))$ for all $j \notin \text{RowSupp}(B^*)$ provided that

$$\min_{j \notin \text{RowSupp}(B^*), (j,k) \in \text{Supp}(S^*)} \left| s_j^*(k) \right| > b_{\min}.$$

(P4) $\text{sign}(\text{supp}(\hat{s}_j + \hat{b}_j)) = \text{sign}(\text{supp}(s_j^* + b_j^*))$ for all $j \in \text{RowSupp}(B^*)$ provided that

$$\min_{(j,k) \in \text{Supp}(B^*)} \left| b_j^*(k) + s_j^*(k) \right| > b_{\min}.$$

**Proof:** We prove the result separately for each part.

(P1) Considering the constructed primal-dual pair, it suffices to show that (C3) and (C4) in Lemma 2 are satisfied by high probability. By Lemma 3 with probability at least $1 - c_1 \exp(-c_2 n)$ those two conditions hold and hence, $(\hat{S}, \hat{B}) = (\hat{S}, \hat{B})$ is the unique solution of (1) and the property (P1) follows.

(P2) Using (5), we have

$$\max_{j \notin \mathcal{U}_k} \left| \Delta_j^* \right| \leq \left\| \frac{1}{n} \left( X_{\mathcal{U}_k}^\top X_{\mathcal{U}_k} \right) \right\|_{\infty}^{\frac{1}{2}} \left\| \left( X_{\mathcal{U}_k}^\top X_{\mathcal{U}_k} \right)^{-1} z_{\mathcal{U}_k} \right\|_{\infty}^{\frac{1}{2}} \leq \sqrt{\frac{4\sigma^2 \log(pr)}{C_{\min} n} + \lambda_s D_{\max}},$$

where, the second inequality holds with high probability as a result of Lemma 4 for $\alpha = \epsilon \sqrt{\frac{4\sigma^2 \log(pr)}{C_{\min} n}}$ for some $\epsilon > 1$, considering the fact that $\text{Var}(\Delta_j^*) \leq \frac{\sigma^2}{\text{Var}(\Delta_j^*)}$.

(P3) Using (P1) in Lemma 11, this event is equivalent to the event that for all $j \notin \text{RowSupp}(B^*)$ with $(j,k) \in \text{Supp}(S^*)$, we have $\left( \Delta_j^* + s_j^* \right) \text{sign}(s_j^*) > 0$. By Hoeffding inequality, we have

$$\mathbb{P} \left[ \left( \Delta_j^* + s_j^* \right) \text{sign}(s_j^*) > 0 \right] = \mathbb{P} \left[ - \Delta_j^* \text{sign}(s_j^*) < |s_j^*| \right] \geq \mathbb{P} \left[ |\Delta_j^*| < |s_j^*| \right].$$

By part (P2), this event happens with high probability if

$$\min_{j \notin \text{RowSupp}(B^*), (j,k) \in \text{Supp}(S^*)} |s_j^*| > b_{\min}.$$

(P4) Using (P1) in Lemma 11, this event is equivalent to the event that for all $j \in \text{RowSupp}(B^*)$, we have $\left( \Delta_j^* + b_j^* + s_j^* \right) \text{sign}(b_j^* + s_j^*) > 0$. By Hoeffding inequality, we have

$$\mathbb{P} \left[ \left( \Delta_j^* + b_j^* + s_j^* \right) \text{sign}(b_j^* + s_j^*) > 0 \right] = \mathbb{P} \left[ - \Delta_j^* \text{sign}(b_j^* + s_j^*) < |b_j^* + s_j^*| \right] \geq \mathbb{P} \left[ |\Delta_j^*| < |b_j^* + s_j^*| \right].$$

By part (P2), this event happens with high probability if

$$\min_{(j,k) \in \text{Supp}(B^*)} |b_j^* + s_j^*| > b_{\min}.$$

**Lemma 3.** Under conditions of Proposition 1, the conditions (C3) and (C4) in Lemma 2 hold for the constructed primal-dual pair with probability at least $1 - c_1 \exp(-c_2 n)$ for some positive constants $c_1$ and $c_2$.

**Proof:** First, we need to bound the projection of $\mathcal{Z}$ into the space $U_{\xi}^\perp$. Notice that

$$\left\| P_{U_{\xi}^\perp} (\mathcal{Z}) \right\|_k^\perp = \begin{cases} \frac{\lambda_b - \lambda_s \| s_j \|_0}{\| M_j(\hat{B}) - [s_j] \|_0} & j \in \text{RowSupp}(\hat{B}) \land (j,k) \notin \text{Supp}(\hat{S}) \\ \left\| z_j^\perp \right\| & j \in \bigcap_{k=1}^{r} U_k^\perp \\ 0 & \text{o.w.} \end{cases}. $$

By our assumption on the ratio of the penalty regularizer coefficients, we have $\frac{\lambda_b - \lambda_s \| s_j \|_0}{\| M_j(\hat{B}) - [s_j] \|_0} < \lambda_s$. Moreover, we have

$$\left\| z_j^\perp \right\| \leq \max_{j \in \bigcap_{k=1}^{r} U_k^\perp} \left\| \frac{1}{n} \left( X_j^\top X_k \right) \right\|_{\infty} \left\| \frac{1}{n} \left( X_j^\top X_k \right)^{-1} z_{U_k} \right\|_{\infty} \left\| \frac{1}{n} \left( X_j^\top X_k \right)^T w_k \right\|_{\infty} + \left\| z_{U_k} \right\|_{\infty} \leq \left( 2 - \gamma_s \right) \frac{1}{n} \left( X_j^\top X_k \right)^T w_k \right\|_{\infty} + \left( 1 - \gamma_s \right) \lambda_s \left\| z_{U_k} \right\|_{\infty} \leq \left( 2 - \gamma_s \right) \frac{1}{n} \left( X_j^\top X_k \right)^T w_k \right\|_{\infty} + (1 - \gamma_s) \lambda_s.$$
Thus, the event $\|P_{U_k}^r(\tilde{Z})\|_{\infty,\infty} < \lambda_s$ is equivalent to the event $\max_{1 \leq k \leq r} \left\| \frac{1}{n} \left( X^{(k)} \right)^T w^{(k)} \right\| \leq \frac{\gamma a}{2 - \gamma a} \lambda_s$. By Lemma 4, this event happens with probability at least $1 - 2 \exp\left(-\frac{\gamma^2 n \lambda_s^2}{4(2 - \gamma a)^2 \sigma^2 + \log(pr)}\right)$. This probability goes to 1 if $\lambda_s > \frac{2(2 - \gamma a)\sqrt{\log(pr)}}{\gamma a \sqrt{n}}$ as stated in the assumptions.

Next, we need to bound the projection of $\tilde{Z}$ into the space $U_k^r$. Notice that

$$r \sum_{k=1}^{r} \left| (P_{U_k}^r(\tilde{Z}))^{(k)}_j \right| = \left\{ \begin{array}{ll} \lambda_s \left\| \tilde{s}_j \right\|_0 & j \in \bigcup_{k=1}^{r} U_k - \text{RowSupp}(B^*) \\ \sum_{k=1}^{r} \left| z_j^{(k)} \right| & j \in \bigcup_{k=1}^{r} U_k \end{array} \right.$$

We have $\lambda_s \left\| \tilde{s}_j \right\|_0 \leq \lambda_b D(S^*) < \lambda_b$ by our assumption on the ratio of the penalty regularizer coefficients. We can establish the following bound:

$$r \sum_{k=1}^{r} \left| z_j^{(k)} \right| \leq (1 - \gamma a)\lambda_b + \max_{1 \leq k \leq r} \left\| \frac{1}{n} \left( X^{(k)} \right)^T w^{(k)} \right\|_{\infty,\infty} \leq \gamma a \lambda_b$$

Thus, the event $\|P_{U_k}^r(\tilde{Z})\|_{\infty,1} < \lambda_b$ is equivalent to the event $\max_{1 \leq k \leq r} \left\| \frac{1}{n} \left( X^{(k)} \right)^T w^{(k)} \right\|_{\infty,1} \leq \frac{\gamma a}{2 - \gamma a} \lambda_b$. By Lemma 4, this event happens with probability at least $1 - 2 \exp\left(-\frac{\gamma^2 n \lambda^2}{4(2 - \gamma a)^2 \sigma^2 + \log(pr)}\right)$. This probability goes to 1 if $\lambda_b > \frac{2(2 - \gamma a)\sqrt{\log(pr)}}{\gamma a \sqrt{n}}$ as stated in the assumptions.

Hence, with probability at least $1 - c_1 \exp(-c_2 n)$ conditions (C3) and (C4) in Lemma 2 are satisfied.

**Lemma 4.**

$$P \left[ \max_{1 \leq k \leq r} \left\| \frac{1}{n} \left( X^{(k)} \right)^T w^{(k)} \right\|_{\infty,1} < \alpha \right] \geq 1 - 2 \exp\left(-\frac{\alpha^2 n}{4a^2} + \log(pr)\right).$$

**Proof:** Since $w^{(k)}_j$’s are distributed as $N(0, \sigma^2)$, we have $\frac{1}{n} \left( X^{(k)} \right)^T w^{(k)}$ distributed as $N \left( 0, \frac{\sigma^2}{n} \right) \left( X^{(k)} \right)^T X^{(k)}$. Using Hoeffding inequality, we have

$$P \left[ \left\| \frac{1}{n} \left( X^{(k)} \right)^T w^{(k)} \right\|_{\infty,1} \geq \alpha \right] \leq \sum_{j=1}^{n} P \left[ \left\| \frac{1}{n} \left( X^{(k)} \right)^T w^{(k)} \right\| \geq \alpha \right] \leq \sum_{j=1}^{n} 2 \exp\left(-\frac{\alpha^2 n}{2a^2} \left( X^{(k)} \right)^T X^{(k)} \right) \leq 2p \exp\left(-\frac{\alpha^2 n}{4a^2}\right).$$

By union bound, the result follows.

**B. Proof of Theorem 2**

Let $d = \left\{ \frac{1}{\lambda_a} \right\}$ and $(B^*, S^*) = \mathcal{H}_d(\tilde{Q})$. Then, the result follows from the next proposition.

**Proposition 2.** Under assumptions of Theorem 2, if

$$n > \max \left( B_s \log(pr), \frac{B_{sr} (r \log(2) + \log(p))}{C_{min} \lambda^2} \right)$$

then with probability at least $1 - c_1 \exp(-c_2 (r \log(2) + \log(p))) - c_3 \exp(-c_4 \log(rs))$ for some positive constants $c_1 - c_4$, we are guaranteed that the following properties hold:

**(P1)** The solution $(\hat{B}, \hat{S})$ to (1) is unique and $\text{RowSupp}(\hat{B}) \subseteq \text{RowSupp}(B^*)$ and $\text{Supp}(\hat{S}) \subseteq \text{Supp}(S^*)$.

**(P2)** $\|\hat{B} + \hat{B}^* - S^*\|_{\infty,\infty} \leq \sqrt{\frac{50r^2 \log(rs)}{4 n C_{min} \lambda} + \lambda_b (\frac{D_b}{C_{min} \sqrt{n}} + D_{max})}$.

**(P3)** $\text{sign}(\text{Supp}(\hat{s}_j)) = \text{sign}(\text{Supp}(s^*_j))$

for all $j \notin \text{RowSupp}(B^*)$ provided that

$$\min_{j \notin \text{RowSupp}(B^*)} \left| s^*_j \right| > g_{min}.$$

**(P4)** $\text{sign}(\text{Supp}(\hat{s}_j + \hat{b}_j)) = \text{sign}(\text{Supp}(s^*_j + b^*_j))$

for all $j \in \text{RowSupp}(B^*)$ provided that

$$\min_{(j,k) \in \text{Supp}(B^*)} \left| b^*_j + s^*_j \right| > g_{min}.$$

**Proof:** We provide the proof of each part separately.

**(P1)** Considering the constructed primal-dual pair $(\tilde{S}, \tilde{B}, \tilde{Z})$, it suffices to show that the conditions (C3) and (C4) in Lemma 2 are satisfied under these assumptions. Lemma 5 guarantees that with probability at least $1 - c_1 \exp(-c_2 (r \log(2) + \log(p)))$ those conditions are satisfied. Hence, $(\hat{B}, \hat{S}) = (\tilde{B}, \tilde{S})$ are the unique solution to (1) and (P1) follows.

**(P2)** From (5), we have

$$\max_{j \in \text{Supp}(\hat{B})} \left| \Delta_j^{(k)} \right| \leq \left\| \left( \frac{1}{n} \left( X^{(k)} \right)^T X^{(k)} \right) \right\|_{\infty,\infty} + \left\| \left( \frac{1}{n} \left( X^{(k)} \right)^T X^{(k)} \right) \right\|_{\infty,\infty} + \left\| \left( \frac{1}{n} \left( X^{(k)} \right)^T X^{(k)} \right) \right\|_{\infty,\infty}$$

We need to bound these three quantities. Notice that

$$\left\| \left( \frac{1}{n} \left( X^{(k)} \right)^T X^{(k)} \right) \right\|_{\infty,\infty} \leq \left\| \left( \frac{1}{n} \left( X^{(k)} \right)^T X^{(k)} \right) \right\|_{\infty,\infty} \leq D_{max} \lambda_b.$$
Also, we have
\[
n\left\| \left( \frac{1}{n} \langle X_{(k)} \rangle - \langle Y_{(k)} \rangle \right)^{-1} \tilde{z}_{(k)} \right\|_\infty \\
\leq \lambda_{\max} \left( \frac{1}{n} \langle X_{(k)} \rangle - \langle Y_{(k)} \rangle \right)^{-1} \left\| \tilde{z}_{(k)} \right\|_2 \\
\leq \lambda_{\max} \left( \frac{1}{n} \langle X_{(k)} \rangle - \langle Y_{(k)} \rangle \right)^{-1},
\]
where, the last inequality holds with probability at least
\[
1 - c_1 \exp \left( -c_2 \left( \sqrt{n} - \sqrt{s} \right)^2 \right)
\]
for some positive constants \( c_1 \) and \( c_2 \) as a result of [3] on eigenvalues of Gaussian random matrices. Conditioned on \( X_{(k)} \), the vector \( W^{(k)} \in \mathbb{R}^{|U_k|} \) is a zero-mean Gaussian random vector with covariance matrix
\[
\frac{s^2}{n} \left( \frac{1}{n} \langle X_{(k)} \rangle \right)^{-1}.
\]
Thus, we have
\[
\frac{1}{n} \lambda_{\max} \left( \frac{1}{n} \langle X_{(k)} \rangle - \langle Y_{(k)} \rangle \right)^{-1} \\
\leq \frac{1}{n} \lambda_{\max} \left( \frac{1}{n} \langle X_{(k)} \rangle - \langle Y_{(k)} \rangle \right)^{-1} + \frac{1}{n} \lambda_{\max} \left( \frac{1}{n} \langle X_{(k)} \rangle - \langle Y_{(k)} \rangle \right)^{-1} \\
\leq \frac{1}{n} \left( \frac{4}{\min n} + \frac{1}{C_{\min}} \right) \\
\leq \frac{5}{n C_{\min}}.
\]
From the concentration of Gaussian random variables (Lemma 4) and using the union bound, we get
\[
P \left[ \max_{1 \leq k \leq r} \left\| W^{(k)} \right\|_2 \leq t \right] \leq 2 \exp \left( -\frac{t^2 n C_{\min}}{50 \sigma^2} + \log(r s) \right).
\]
For \( t = \epsilon \sqrt{\frac{20 \sigma^2 \log(r s)}{n C_{\min}}} \) for some \( \epsilon > 1 \), the result follows.

(P3),(P4) The results are immediate consequence of (P2).

Lemma 5. Under the assumptions of Proposition 2, the conditions (C3) and (C4) in Lemma 2 hold for the constructed primal-dual pair with probability at least
\[
1 - c_1 \exp \left( -c_2 (r \log(2) + \log(p)) \right)
\]
for some positive constants \( c_1 \) and \( c_2 \).

Proof: First, we need to bound the projection of \( \tilde{Z} \) into the space \( U_{(k)} \). Notice that
\[
\left\| \left( P_{U_{(k)}} \right)^{(k)} \right\|_1 \\
= \sum_{j \in \text{RowSupp}(B) \& \ (j, k) \notin \text{Supp}(\tilde{S})} \lambda_j - \lambda_{\lambda} \| \tilde{s}_j \|_0 \\
+ \sum_{j \in \bigcap_{k=1}^r U_{(k)}} \left\| \tilde{s}_j \right\|_0 \text{ ow}.
\]
By our assumptions on the ratio of the penalty regularizer coefficients, we have
\[
\frac{\lambda_j - \lambda_{\lambda} \| \tilde{s}_j \|_0}{\| M_j(B) \| - \| \tilde{s}_j \|_0} < \lambda_{\lambda}.
\]
For all \( j \in \bigcap_{k=1}^r U_{(k)} \) with i.i.d. standard Gaussian entries (see Lemma 4 in [1]), we have
\[
\left| \left( \mathcal{R}^{(k)} \right) \right| \\
\leq \max_{j \in \bigcap_{k=1}^r U_{(k)}} \left\| \mathcal{R}^{(k)} \right\|_2 \\
+ \sum_{j \in \bigcap_{k=1}^r U_{(k)}} \left\| \mathcal{R}^{(k)} \right\|_2
\]
for some \( c_1, c_2 \) as a result of [3] on eigenvalues of Gaussian random matrices. Conditioned on \( X_{(k)} \), the vector \( W^{(k)} \in \mathbb{R}^{|U_k|} \) is a zero-mean Gaussian random vector with covariance matrix
\[
\frac{s^2}{n} \left( \frac{1}{n} \langle X_{(k)} \rangle \right)^{-1}.
\]
Thus, we have
\[
\frac{1}{n} \lambda_{\max} \left( \frac{1}{n} \langle X_{(k)} \rangle - \langle Y_{(k)} \rangle \right)^{-1} \\
\leq \frac{1}{n} \lambda_{\max} \left( \frac{1}{n} \langle X_{(k)} \rangle - \langle Y_{(k)} \rangle \right)^{-1} + \frac{1}{n} \lambda_{\max} \left( \frac{1}{n} \langle X_{(k)} \rangle - \langle Y_{(k)} \rangle \right)^{-1} \\
\leq \frac{1}{n} \left( \frac{4}{\min n} + \frac{1}{C_{\min}} \right) \\
\leq \frac{5}{n C_{\min}}.
\]
From the concentration of Gaussian random variables (Lemma 4) and using the union bound, we get
\[
P \left[ \max_{1 \leq k \leq r} \left\| W^{(k)} \right\|_2 \leq t \right] \leq 2 \exp \left( -\frac{t^2 n C_{\min}}{50 \sigma^2} + \log(r s) \right).
\]
For \( t = \epsilon \sqrt{\frac{20 \sigma^2 \log(r s)}{n C_{\min}}} \) for some \( \epsilon > 1 \), the result follows.

(P3),(P4) The results are immediate consequence of (P2).

Lemma 4. Under the assumptions of Proposition 2, the conditions (C3) and (C4) in Lemma 2 hold for the constructed primal-dual pair with probability at least
\[
1 - c_1 \exp \left( -c_2 (r \log(2) + \log(p)) \right)
\]
for some positive constants \( c_1 \) and \( c_2 \).

Proof: First, we need to bound the projection of \( \tilde{Z} \) into the space \( U_{(k)} \). Notice that
\[
\left\| \left( P_{U_{(k)}} \right)^{(k)} \right\|_1 \\
= \sum_{j \in \text{RowSupp}(B) \& \ (j, k) \notin \text{Supp}(\tilde{S})} \lambda_j - \lambda_{\lambda} \| \tilde{s}_j \|_0 \\
+ \sum_{j \in \bigcap_{k=1}^r U_{(k)}} \left\| \tilde{s}_j \right\|_0 \text{ ow}.
\]
By our assumptions on the ratio of the penalty regularizer coefficients, we have
\[
\frac{\lambda_j - \lambda_{\lambda} \| \tilde{s}_j \|_0}{\| M_j(B) \| - \| \tilde{s}_j \|_0} < \lambda_{\lambda}.
\]
For all \( j \in \bigcap_{k=1}^r U_{(k)} \) with i.i.d. standard Gaussian entries (see Lemma 4 in [1]), we have
\[
\left| \left( \mathcal{R}^{(k)} \right) \right| \\
\leq \max_{j \in \bigcap_{k=1}^r U_{(k)}} \left\| \mathcal{R}^{(k)} \right\|_2 \\
+ \sum_{j \in \bigcap_{k=1}^r U_{(k)}} \left\| \mathcal{R}^{(k)} \right\|_2
\]
for some \( c_1, c_2 \) as a result of [3] on eigenvalues of Gaussian random matrices. Conditioned on \( X_{(k)} \), the vector \( W^{(k)} \in \mathbb{R}^{|U_k|} \) is a zero-mean Gaussian random vector with covariance matrix
\[
\frac{s^2}{n} \left( \frac{1}{n} \langle X_{(k)} \rangle \right)^{-1}.
\]
Thus, we have
\[
\frac{1}{n} \lambda_{\max} \left( \frac{1}{n} \langle X_{(k)} \rangle - \langle Y_{(k)} \rangle \right)^{-1} \\
\leq \frac{1}{n} \lambda_{\max} \left( \frac{1}{n} \langle X_{(k)} \rangle - \langle Y_{(k)} \rangle \right)^{-1} + \frac{1}{n} \lambda_{\max} \left( \frac{1}{n} \langle X_{(k)} \rangle - \langle Y_{(k)} \rangle \right)^{-1} \\
\leq \frac{1}{n} \left( \frac{4}{\min n} + \frac{1}{C_{\min}} \right) \\
\leq \frac{5}{n C_{\min}}.
\]
From the concentration of Gaussian random variables (Lemma 4) and using the union bound, we get
\[
P \left[ \max_{1 \leq k \leq r} \left\| W^{(k)} \right\|_2 \leq t \right] \leq 2 \exp \left( -\frac{t^2 n C_{\min}}{50 \sigma^2} + \log(r s) \right).
\]
For \( t = \epsilon \sqrt{\frac{20 \sigma^2 \log(r s)}{n C_{\min}}} \) for some \( \epsilon > 1 \), the result follows.

(P3),(P4) The results are immediate consequence of (P2).
Next, we need to bound the projection of $\vec{Z}$ into the space $U_b^c$.

Notice that

$$\sum_{k=1}^{r}\left|\mathbb{E}_{\mathcal{U}_{k}^{c}}(\vec{Z})_{(k)}\right| = \left\{ \begin{array}{ll} \lambda_{b}\|\vec{Z}\|_{0} & j \in \bigcup_{k=1}^{r} \mathcal{U}_{k} - \text{RowSupp}(B^{*}) \\
\sum_{k=1}^{r} z_{(k)}^{j} & j \in \bigcup_{k=1}^{r} \mathcal{U}_{k}^{c}\end{array} \right. $$

We have $\lambda_{b}\|\vec{Z}\|_{0} \leq \lambda_{b}D(S^{*}) < \lambda_{b}$ by our assumption on the ratio of the penalty regularizer coefficients. For all $j \in \bigcap_{k=1}^{r} \mathcal{U}_{k}^{c}$, we have

$$\sum_{k=1}^{r} z_{(k)}^{j} \leq \max_{j \in \bigcap_{k=1}^{r} \mathcal{U}_{k}^{c}} \sum_{k=1}^{r} \left|1 - n^{-1}X_{j}^{(k)} \left(\frac{1}{n}X_{U_{k}^{c}}X_{U_{k}^{c}}^{T}\right)^{-1}X_{U_{k}^{c}}\right| z_{(k)}^{j}$$

Actually prove a more general theorem, from which Theorem 3 would follow as a corollary. Among shared features (with size $\alpha s$), we say a fraction $\tau$ has different magnitudes on $\Theta$. Let $\tau_{1}$ be the fraction with larger magnitude on the first
and \( \tau_2 \) the fraction with larger magnitude on the second task (so that \( \tau = \tau_1 + \tau_2 \)). Moreover, let \( \frac{\lambda_0}{\lambda_\kappa} = \kappa \) and

\[
f(\kappa) = f(\kappa, \tau, \alpha) = 2 - 2(1 - \tau)\alpha - 2\tau\alpha\kappa + \left(\frac{1 + \tau}{2}\right)\alpha\kappa^2,
\]

and

\[
g(\kappa, \tau, \alpha) = \max \left( \frac{2f(\kappa)}{\kappa^2}, f(\kappa) \right).
\]

**Theorem 4.** Under the assumptions of the Theorem 3, if

\[
\left\{ j \in \text{RowSupp}(B^*) : \left| \frac{\theta_j^{(1)}}{\theta_j^{(2)}} \right| \leq c\lambda_\alpha \right\} \leq (1 - \tau)\alpha s,
\]

then the result of Theorem 3 holds for

\[
\theta(n, s, \tau, \alpha) = \frac{n}{g(\kappa, \tau, \alpha) s \log (p - (2 - \alpha)s)}.
\]

**Corollary 4.** Under the assumptions of the Theorem 4, if the regularization penalties are set as \( \kappa = \lambda_0/\lambda_\kappa = \sqrt{2} \), then the result of Theorem 3 holds for \( \theta(n, s, \tau, \alpha) = \frac{n}{(2 - \alpha)(3 - 2\sqrt{2}) \tau \alpha} \).

**Proof:** Follows trivially by substituting \( \kappa = \sqrt{2} \) in Theorem 4. Indeed, this setting of \( \kappa \) can also be shown to minimize \( g(\kappa, \tau, \alpha) \):

\[
\min_{1 < \kappa < 2} \max \left( \frac{2f(\kappa)}{\kappa^2}, f(\kappa) \right) = \min_{1 < \kappa < 2} \frac{2}{\sqrt{2} < \kappa < 2} f(\kappa) = 2 - \alpha + (3 - 2\sqrt{2}) \tau \alpha.
\]

**Proof of Theorem 3:** The proof follows from Corollary 4 by setting \( \tau = 0 \) and \( \kappa = \sqrt{2} \).

We will now set out to prove Theorem 4. We will first need the following lemma.

**Lemma 7.** For any \( j \in \text{RowSupp}(B^*) \), if \( \left| S_j^{(k)} \right| < c\lambda_\kappa \) for some constant \( c \) specified in the proof, then \( S_j^{(k)} = 0 \) with probability \( 1 - c_1 \exp(-c_2 n) \).

**Proof:** Let \( \hat{S} \) be a matrix equal to \( S \) except that \( S_j^{(k)} = \zeta_j \). Using the concentration of Gaussian random variables and optimality of \( S \), we get

\[
\mathbb{P} \left[ \left| S_j^{(k)} \right| > 0 \right] \leq \mathbb{P} \left[ 2n\lambda_\kappa |S_j^{(k)}| < \left\| y^{(k)} - X^{(k)}(\hat{B}^{(k)} + \hat{S}^{(k)}) \right\|_2^2 \right]
\]

\[
= \mathbb{P} \left[ 2n\lambda_\kappa < \left( \frac{\left\| y^{(k)} - X^{(k)}(\hat{B}^{(k)} + \hat{S}^{(k)}) \right\|_2^2}{\left\| S_j^{(k)} \right\|_2} \right)^{\frac{1}{2}} \left\| X_j^{(k)} \right\|_2 \right]
\]

\[
\leq \mathbb{P} \left[ 2n\lambda_\kappa < 2 \left\| X_j^{(k)} \right\|_2 \left\| y^{(k)} - X^{(k)}(\hat{B}^{(k)} + \hat{S}^{(k)}) \right\|_2 \right]
\]

\[
= \mathbb{P} \left[ n\lambda_\kappa \left\| X_j^{(k)} \right\|_2 \left\| X^{(k)}(B^{(k)} + S^{(k)} - \hat{B}^{(k)} - \hat{S}^{(k)}) + w^{(k)} \right\|_2 \right]\]
The second equality holds by orthogonality of projections. We thus have
\[
\begin{align*}
\text{Var}\left(\tilde{Z}^{(k)}\right) & \geq \max_{\lambda_{\min}} \left(\frac{1}{n} \left(\lambda_{\min} \left(\frac{1}{n} \left(\mathbf{x}^{(k)} - \mathbf{n} \mathbf{u}_k - \mathbf{n} \mathbf{u}_k^*\right)\right)^{-1}\right) \right) \frac{\|\mathbf{u}_k\|_2^2}{n} \\
& \geq \frac{\|\mathbf{u}_k\|_2^2}{\sqrt{n} + \sqrt{s}}.
\end{align*}
\]

The second inequality holds with probability at least \(1 - c_1 \exp\left(-c_2 (\sqrt{n} + \sqrt{s})^2\right)\) as a result of [6] on the eigenvalues of Gaussian matrices. The third inequality holds with probability at least \(1 - c_1 \exp\left(-c_2 n\right)\) as a result of [8] on the magnitude of \(\chi^2\) random variables. Considering \(B + S\), assume that among shared features (with size \(s\)) assume that among shared features (with size \(s\)), a portion of \(\tau_{\ell}\) has larger magnitude on the first task and a portion of \(\tau_2\) has larger magnitude on the second task (and consequently a portion of \(1 - \tau_1 - \tau_2\) has equal magnitude on both tasks). Assuming \(\lambda = \frac{\kappa}{\lambda_\alpha}\) for some \(\kappa \in (1, 2)\), we get
\[
\begin{align*}
\sigma^2 & := \text{Var}\left(\tilde{Z}^{(1)}\right) \\
& = \frac{(1 - \alpha)s \lambda^2 + \tau_1 \alpha s \lambda^2 + \tau_2 \alpha s (\lambda_\alpha - \lambda_\alpha) + (1 - \tau_1 - \tau_2) \alpha s \lambda^2}{\sqrt{n} + \sqrt{s}} \\
& = \frac{f_1(\kappa)s \lambda^2}{n \left(1 + \sqrt{\frac{\kappa}{n}}\right)^2}.
\end{align*}
\]

The first equality follows from the construction of the dual matrix and the fact that we have recovered the sign support correctly. The last strict inequality follows from the assumption that \(0 < n, p, s, \alpha < 1\). Similarly, we have
\[
\begin{align*}
\sigma^2 & := \text{Var}\left(\tilde{Z}^{(2)}\right) \\
& > \frac{(1 - \alpha)s \lambda^2 + \tau_2 \alpha s \lambda^2 + \tau_1 \alpha s (\lambda_\alpha - \lambda_\alpha) + (1 - \tau_1 - \tau_2) \alpha s \lambda^2}{\sqrt{n} + \sqrt{s}} \\
& = \frac{f_2(\kappa)s \lambda^2}{n \left(1 + \sqrt{\frac{\kappa}{n}}\right)^2}.
\end{align*}
\]

Given these lower bounds on the variance, by results on Gaussian maxima (see [6]), for any \(\delta > 0\), with high probability,
\[
\begin{align*}
\max_{1 \leq k \leq r} \max_{\tau_{\ell} \in U_k} \left|\tilde{Z}^{(k)}\right| & \geq (1 - \delta) \sqrt{(\sigma^2_1 + \sigma^2_2) \log \left(\frac{p - (2 - \alpha)s}{2}\right)}. \\
\end{align*}
\]

This in turn can be bounded as
\[
\begin{align*}
(1 - \delta) (\sigma^2_1 + \sigma^2_2) \log \left(\frac{p - (2 - \alpha)s}{2}\right) & \geq (1 - \delta) \frac{\left(f_1(\kappa) + f_2(\kappa)\right) s \log \left(\frac{p - (2 - \alpha)s}{2}\right) \lambda^2}{n \left(1 + \sqrt{\frac{\kappa}{n}}\right)^2} \\
& \geq (1 - \delta) \frac{f(\kappa) s \log \left(\frac{p - (2 - \alpha)s}{2}\right) \lambda^2}{n \left(1 + \sqrt{\frac{\kappa}{n}}\right)^2}.
\end{align*}
\]

Consider two cases:

1) \(\tilde{Z} = \Omega(1)\): In this case, we have \(s > cn\) for some constant \(c > 0\). Then,
\[
\begin{align*}
(1 - \delta) \frac{\left(f(\kappa)\right) s \log \left(\frac{p - (2 - \alpha)s}{2}\right) \lambda^2}{n \left(1 + \sqrt{\frac{\kappa}{n}}\right)^2} & = (1 - \delta) \frac{\left(f(\kappa)\right) (s/n) \log \left(\frac{p - (2 - \alpha)s}{2}\right) \lambda^2}{n \left(1 + \sqrt{\frac{s}{n}}\right)^2} \\
& > \epsilon f(\kappa) \log \left(\frac{p - (2 - \alpha)s}{2}\right) \lambda^2 \\
& > (1 + \epsilon) \lambda^2,
\end{align*}
\]
for any fixed \(\epsilon > 0\), as \(p \to \infty\).

2) \(\tilde{Z} \to 0\): In this case, we have \(s/n = o(1)\). Here we will use that the sample size scales as \(n < (1 + \nu) s \log(p - (2 - \alpha)s)\).
\[
\begin{align*}
(1 - \delta) \frac{f(\kappa) s \log \left(\frac{p - (2 - \alpha)s}{2}\right) \lambda^2}{n \left(1 + \sqrt{\frac{\kappa}{n}}\right)^2} & \geq (1 - \delta) \frac{(1 - o(1)) \lambda^2}{1 - \nu} \\
& > (1 + \epsilon) \lambda^2,
\end{align*}
\]
for some \(\epsilon > 0\) by taking \(\delta\) small enough.

Thus with high probability, \(\exists k \forall j \in \bigcap_{k=1}^r U_k\) such that \(\tilde{Z}^{(k)}_j > \lambda_s\). This is a contradiction to Lemma [13].

Case (ii): We need to show that with high probability, there exist a row that violates the sub-gradient condition of \(\ell_\infty\)-norm: \(\exists j \in \bigcap_{k=1}^r U_k\) such that \(\tilde{Z}^{(k)}_j > \lambda_0\). This is a contradiction to Lemma [13].

Following the same proof technique, notice that \(\sum_{k=1}^r \tilde{Z}^{(k)}_j\) is a zero-mean Gaussian random variable with \(\text{Var}\left(\sum_{k=1}^r \tilde{Z}^{(k)}_j\right) \geq r(\sigma^2_1 + \sigma^2_2)\). Thus, with high probability
\[
\begin{align*}
\max_{j \in \bigcap_{k=1}^r U_k} \left|\tilde{Z}^{(k)}_j\right| & \geq (1 - \delta) \sqrt{r(\sigma^2_1 + \sigma^2_2) \log \left(\frac{p - (2 - \alpha)s}{2}\right)}.
\end{align*}
\]

Following the same line of argument for this case, yields the required bound \(\left|\tilde{Z}^{(k)}_j\right| > (1 + \epsilon) \lambda_0\).

This concludes the proof of the theorem.

**Lemma 8.** Under assumptions of Theorem 3, the conditions (C3) and (C4) in Lemma 2 hold with probability at least \(1 - c_1 \exp\left(-c_2 n\right)\) for some positive constants \(c_1\) and \(c_2\).

**Proof:** First, we need to bound the projection of \(\tilde{Z}\) into
By our assumption on the penalty regularizer coefficients, we have $\frac{\lambda_0 - \lambda_s \| \tilde{S}_j \|_0}{|M_j(\hat{B})| - \| \tilde{S}_j \|_0} < \lambda_s$. Moreover, we have

$$\| \tilde{Z}_j \| \leq \frac{\max \{ \lambda_0 - \lambda_s \| \tilde{S}_j \|_0 : j \in \text{Row Supp}(\hat{B}) \} + (j, k) \notin \text{Supp}(\hat{S}) \} \leq \frac{\max \{ \lambda_0 - \lambda_s \| \tilde{S}_j \|_0 : j \in \text{Row Supp}(\hat{B}) \} + (j, k) \notin \text{Supp}(\hat{S}) \} \leq \frac{\lambda_0 - \lambda_s \| \tilde{S}_j \|_0}{|M_j(\hat{B})| - \| \tilde{S}_j \|_0} < \lambda_s.$$

By Lemma[2] if $n \geq \frac{2^2}{2^{2/3}} \log(pK)$ then with high probability $\| X_{ik} \|_2^2 \leq 2n$ and hence $\text{Var}(W_j(k)) \leq \frac{2a^2}{n}$. Notice that $\mathbb{E}[\| X_{ik} \|_2^2] = n$ and we added the factor of 2 arbitrarily to use the concentration theorems. Using the concentration results for the zero-mean Gaussian random variable $W_j(k)$ and using the union bound, for all $t > 0$, we get

$$\mathbb{P}\left\{ \max_{j \in \text{Supp}(\hat{B})} \| W_j \|_2 \geq t \right\} \leq 2 \exp\left( -\frac{t^2}{4n} + \log \left( \frac{n-2(2-\alpha)s}{2} \right) \right).$$

Conditioning on $(X_{ik}, u_{ik}, \tilde{Z}_j(k))$, we have that $Z_j(k)$ is a zero-mean Gaussian random variable with

$$\text{Var}(Z_j(k)) = \frac{1}{n} \max \left\{ \left\langle X_{ik}, X_{ik} \right\rangle - 1 \right\} \| \tilde{Z}_j \|_2^2.$$ 

According to the result of [6] on singular values of Gaussian matrices, for the matrix $X_{ik}$, for all $\delta > 0$, we have

$$\mathbb{P}[\| X_{ik} \|_{\text{F}}^2 \leq (1 - \delta) (\sqrt{n} - \delta) \leq \exp \left( -\frac{\delta^2 (\sqrt{n} - \delta)^2}{2} \right),$$

and since $\lambda_{\text{max}} \left( \left\langle X_{ik}, X_{ik} \right\rangle^{-1} \right) = \sigma_{\text{min}} \left( X_{ik} \right)^{-2}$, we get

$$\mathbb{P}[\lambda_{\text{max}} \left( \left\langle X_{ik}, X_{ik} \right\rangle^{-1} \right) \geq (1 + \delta) \frac{1}{1 - \frac{\delta}{\sqrt{n}}} \leq \exp \left( -\frac{(\sqrt{n} - 1 - 1)^2 (\sqrt{n} - \delta)^2}{2(1 + \delta)} \right).$$

According to Lemma [2] if $\| \Theta_j^{(1)} - \Theta_j^{(2)} \| = o(\lambda_s)$, then with high probability $\| \tilde{S}_j \| = 0$, so that $|\Theta_j^{(1)}| = |\Theta_j^{(2)}|$. Thus, among shared features (with size $\alpha_s$), a fraction $\tau$ have differing magnitudes on $\Theta$. Let $\tau_1$ be the fraction with larger magnitude on the first task and $\tau_2$ the fraction with larger magnitude on the second task (so that $\tau = \tau_1 + \tau_2$). Then, with high probability, recalling that $\lambda_0 = \kappa \lambda_s$ for some $1 < \kappa < 2$, we get

$$\text{Var}(Z_j^{(1)}) \leq \frac{\| \tilde{Z}_j(k) \|_2^2}{(\sqrt{n} - \delta)^2} = \frac{(1 - \alpha) \alpha \lambda_s^2 + \tau_2 \alpha s (\lambda_0 - \lambda_s) + (1 - \tau_1 - \tau_2) \alpha \lambda_s^2}{(\sqrt{n} - \delta)^2} \leq \frac{f_2(\alpha) \lambda_s^2}{(\sqrt{n} - \delta)^2}.$$ 

Similarly,

$$\text{Var}(Z_j^{(2)}) \leq \frac{\| \tilde{Z}_j(k) \|_2^2}{(\sqrt{n} - \delta)^2} = \frac{(1 - \tau_1 - \tau_2) \alpha - 2\tau_1 \alpha s + (\tau_1 + \frac{1 - \tau_1 - \tau_2}{\sqrt{n} - \delta}) \alpha \lambda s^2}{(\sqrt{n} - \delta)^2} \leq \frac{f_2(\alpha) \lambda_s^2}{(\sqrt{n} - \delta)^2}.$$ 

By concentration of Gaussian random variables, we have

$$\mathbb{P}\left[ \max_{j \in \text{Supp}(\hat{B})} \| W_j(k) \|_2 \geq t \right] \leq 2 \exp \left( -\frac{t^2}{2n} + \log \left( \frac{n-2(2-\alpha)s}{2} \right) \right).$$

Using these bounds, we get

$$\mathbb{P}\left[ \max_{j \in \text{Supp}(\hat{B})} \| Z_j(k) \|_2 \geq t \right] \leq 2 \exp \left( -\frac{t^2}{4n} + \log \left( \frac{n-2(2-\alpha)s}{2} \right) \right).$$

This probability goes to 1 for

$$t_0 = \frac{\sqrt{(f_1(\kappa) + f_2(\kappa)) \alpha s \lambda_s}}{\sqrt{(f_1(\kappa) + f_2(\kappa)) \alpha s \lambda_s} + 2\sigma (\sqrt{n} - \delta)^2} \lambda_s,$$

the (solution to $t_0^2 (\sqrt{n} - \delta)^2 = (\lambda_s - t_0^2)^2 n$), if

$$\lambda_s > \sqrt{\frac{4\alpha^2}{\delta^2} \left( \log(r) + \log \left( \frac{n-(2-\alpha)s}{2} \right) \right)} \left( \log(r) + \log \left( \frac{n-(2-\alpha)s}{2} \right) \right) \cdot \sqrt{(f_1(\kappa) + f_2(\kappa)) s \left( \log(r) + \log \left( \frac{n-(2-\alpha)s}{2} \right) \right)}.$$

provided that (substituting $r = 2$),

$$n > (f_1(\kappa) + f_2(\kappa)) s \log \left( \frac{n-(2-\alpha)s}{2} \right) + \left( 1 + f_1(\kappa) + f_2(\kappa) \right) \log(2)$$

$$+ 2 \sqrt{(f_1(\kappa) + f_2(\kappa)) \log(2) + \log \left( \frac{n-(2-\alpha)s}{2} \right)} s.$$
Since $f_1(\kappa) + f_2(\kappa) = f(\kappa)$ by definition, for large enough $p$ with $\frac{\lambda}{\kappa} = o(1)$, we require
\[
n > f(\kappa) s \log \left( p - (2 - \alpha)s \right). \tag{7}
\]

Next, we need to bound the projection of $\tilde{Z}$ into the space $U_b^c$. Notice that
\[
\sum_{k=1}^r \left| (P_{U_b^c}(\tilde{Z}))_j^{(k)} \right| = \begin{cases} \sum_{k=1}^r |Z_j^{(k)}| & j \in \bigcup_{k=1}^r U_b - \text{Row Supp}(B^*) \\ 0 & j \in \bigcap_{k=1}^r U_b^c \end{cases}
\]

We have $\lambda_b \| \tilde{S}_j \|_0 \leq \lambda_b D(S^*) < \lambda_b$ by our assumption on the ratio of penalty regularizer coefficients. For all $j \in \bigcap_{k=1}^r U_b^c$, we have
\[
\sum_{k=1}^r |Z_j^{(k)}| \leq \max_{j \in \bigcap_{k=1}^r U_b^c} \sum_{k=1}^r \left| \frac{1}{n} \left( \chi_j^{(k)} \mathbf{I} - \frac{1}{n} \chi_j^{(k)} \left( \frac{1}{n} \chi_j^{(k)} \chi_j^{(k)^T} \right)^{-1} \chi_j^{(k)^T} \right) X^{(k)} \right| v_j^{(k)}
\]

\[
+ \max_{j \in \bigcap_{k=1}^r U_b^c} \sum_{k=1}^r \left| \frac{1}{n} \left( \chi_j^{(k)} \chi_j^{(k)^T} \right)^{-1} \tilde{Z}_j^{(k)} \right| v_j^{(k)}
\]

\[
= \max_{j \in \bigcap_{k=1}^r U_b^c} \sum_{k=1}^r |Z_j^{(k)}| + \max_{j \in \bigcap_{k=1}^r U_b^c} \sum_{k=1}^r |W_j^{(k)}|.
\]

Let $v \in \{-1, +1\}^r$ be a vector of signs such that $\sum_{k=1}^r W_j^{(k)} = \sum_{k=1}^r v_k W_j^{(k)}$. Thus,
\[
\text{Var} \left( \sum_{k=1}^r W_j^{(k)} \right) = \text{Var} \left( \sum_{k=1}^r v_k W_j^{(k)} \right) \leq \frac{2\sigma^2}{n}.
\]

Using the union bound and previous discussion, for all $t > 0$, we get
\[
P \left[ \max_{j \in \bigcap_{k=1}^r U_b^c} \sum_{k=1}^r |W_j^{(k)}| \geq t \right]
\]

\[
= P \left[ \max_{j \in \bigcap_{k=1}^r U_b^c} \max_{v \in \{-1, +1\}^r} \sum_{k=1}^r v_k W_j^{(k)} \geq t \right]
\]

\[
\leq 2 \exp \left( - \frac{t^2 n}{4\sigma^2} + r \log(2) + \log \left( p - (2 - \alpha)s \right) \right).
\]

Also from the previous analysis, assuming $\lambda_b = \kappa \lambda_s$ for some $1 < \kappa < 2$, we get
\[
\text{Var} \left( \sum_{k=1}^r |Z_j^{(k)}| \right) = \text{Var} \left( \sum_{k=1}^r v_k Z_j^{(k)} \right) \leq \sum_{k=1}^r \left| Z_j^{(k)} \right|^2 \left( \frac{1}{\sqrt{n}} - \sqrt{s} \right)^2
\]

\[
= \frac{2(1 - \alpha)s \lambda_s^2 + (\tau_1 + \tau_2)\alpha s \lambda_s^2 + (\tau_1 + \tau_2)\alpha s (\kappa - \lambda_s)^2 + 2(1 - \tau_1 - \tau_2)\alpha s \lambda_s^2}{\left( \frac{1}{\sqrt{n}} - \sqrt{s} \right)^2}
\]

\[
= \frac{1}{\frac{1}{\sqrt{n}} - \sqrt{s}} \frac{(f_1(\kappa) + f_2(\kappa)) s \lambda_s^2}{\left( \frac{1}{\sqrt{n}} - \sqrt{s} \right)^2}.
\]

and consequently for all $t > 0$,
\[
P \left[ \max_{j \in \bigcap_{k=1}^r U_b^c} \sum_{k=1}^r |Z_j^{(k)}| \geq t \right]
\]

\[
= P \left[ \max_{j \in \bigcap_{k=1}^r U_b^c} \max_{v \in \{-1, +1\}^r} \sum_{k=1}^r v_k Z_j^{(k)} \geq t \right]
\]

\[
\leq 2 \exp \left( - \frac{t^2 (\sqrt{n} - \sqrt{s})^2}{s} + r \log(2) + \log \left( p - (2 - \alpha)s \right) \right).
\]

Finally, we have
\[
P \left[ \|P_{U_b^c}(\tilde{Z})\|_\infty \leq \lambda_b \right]
\]

\[
\geq P \left[ \max_{j \in \bigcap_{k=1}^r U_b^c} \sum_{k=1}^r |Z_j^{(k)}| + \max_{j \in \bigcap_{k=1}^r U_b^c} \sum_{k=1}^r |W_j^{(k)}| < \lambda_b \right]
\]

\[
\geq P \left[ \max_{j \in \bigcap_{k=1}^r U_b^c} \sum_{k=1}^r |Z_j^{(k)}| \leq \lambda_b - t_0 \right]
\]

\[
\geq \left( 1 - 2 \exp \left( - \frac{t_0^2 (\sqrt{n} - \sqrt{s})^2}{s} + r \log(2) + \log \left( p - (2 - \alpha)s \right) \right) \right)
\]

\[
\left( 1 - 2 \exp \left( - \frac{(\lambda_b - t_0) t_0^2 s}{4\sigma^2} + r \log(2) + \log \left( p - (2 - \alpha)s \right) \right) \right).
\]

This probability goes to 1 for
\[
t_0 = \frac{\sqrt{\frac{1}{\kappa^2} (f_1(\kappa) + f_2(\kappa)) n s \lambda_b}}{\sqrt{\frac{1}{\kappa^2} (f_1(\kappa) + f_2(\kappa)) n s \lambda_b} + 2\sigma (\sqrt{n} - \sqrt{s}) \lambda_b}
\]

and the solution to $\frac{(\lambda_b - t_0) t_0^2 s}{4\sigma^2} = \frac{\lambda_b^2 (\sqrt{n} - \sqrt{s})^2}{s (f_1(\kappa) + f_2(\kappa)) s \lambda_b^2 + 2\sigma (\sqrt{n} - \sqrt{s}) \lambda_b}$, if
\[
\lambda_b > \frac{\sqrt{\frac{1}{\kappa^2} (f_1(\kappa) + f_2(\kappa)) s \log \left( p - (2 - \alpha)s \right)} \sqrt{\frac{1}{\kappa^2} (f_1(\kappa) + f_2(\kappa)) s r \log(2) + \log \left( p - (2 - \alpha)s \right)}}{\sqrt{n} - \sqrt{s} - \sqrt{\frac{1}{\kappa^2} (f_1(\kappa) + f_2(\kappa)) s r \log(2) + \log \left( p - (2 - \alpha)s \right)}}.
\]

provided that (substituting $r = 2$),
\[
n > \frac{2}{\kappa^2} (f_1(\kappa) + f_2(\kappa)) s \log \left( p - (2 - \alpha)s \right)
\]

\[
+ \frac{1}{\kappa^2} (f_1(\kappa) + f_2(\kappa)) 2 \log(2)
\]

\[
+ 2\sqrt{\frac{2}{\kappa^2} (f_1(\kappa) + f_2(\kappa)) \left( 2 \log(2) + \log \left( p - (2 - \alpha)s \right) \right)}.
\]

For large enough $p$ with $\tilde{p} = o(1)$, we require
\[
n > \frac{2}{\kappa^2} f(\kappa) s \log \left( p - (2 - \alpha)s \right).
\]

Combining this result with (7), the lemma follows. 

\[\blacksquare\]
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APPENDIX A

DETERMINISTIC NECESSARY OPTIMALITY CONDITIONS

In this appendix, we investigate deterministic necessary conditions for the optimality of the solutions \((B, \hat{S})\) of the problem \((\mathcal{P})\).

A. Sub-differential of \(\ell_1/\ell_\infty \) and \(\ell_1/\ell_1 \) Norms

In this section we state the sub-differential characterization of the norms we used in out convex program. The results can be directly derived from the definition of sub-differential of a function.

Lemma 9 (Sub-differential of \(\ell_1/\ell_\infty\)-Norm). The matrix \(\tilde{Z} \in \mathbb{R}^{P \times r}\) belongs to the sub-differential of \(\ell_1/\ell_\infty\)-norm of matrix \(\tilde{B}\), denoted as \(\tilde{Z} \in \partial \| \tilde{B} \|_{1,\infty}\), iff

(i) for all \(j \in \text{RowSupp}(\tilde{B})\), we have \(z_j^{(k)} = t_j^{(k)} \text{sign}(\hat{b}_j^{(k)})\) for all \(k \in M_j(\tilde{B})\), where, \(t_j^{(k)} \geq 0\) and \(\sum_{k=1}^r t_j^{(k)} = 1\).

(ii) for all \(j \notin \text{RowSupp}(\tilde{B})\), we have \(\sum_{k=1}^r \left| z_j^{(k)} \right| \leq 1\).

Lemma 10 (Sub-differential of \(\ell_1/\ell_1\)-Norm). The matrix \(\tilde{Z} \in \mathbb{R}^{P \times r}\) belongs to the sub-differential of \(\ell_1/\ell_1\)-norm of matrix \(\tilde{S}\), denoted as \(\tilde{Z} \in \partial \| \tilde{S} \|_{1,1}\), iff

(i) for all \((j, k) \in \text{Supp}(\tilde{S})\), we have \(z_j^{(k)} = \text{sign}(\hat{b}_j^{(k)})\).

(ii) for all \((j, k) \notin \text{Supp}(\tilde{S})\), we have \(\left| z_j^{(k)} \right| \leq 1\).

B. Necessary Conditions

The first lemma shows a necessary condition for any solution of the problem \((\mathcal{P})\).

Lemma 11. If \((\tilde{S}, \tilde{B})\) is a solution (uniqueness is NOT required) of \((\mathcal{P})\) then the following properties hold:

(P1) \(\text{sign}(\hat{s}_j^{(k)}) = \text{sign}(\hat{b}_j^{(k)})\) for all \((j, k) \in \text{Supp}(\tilde{S})\) with \(j \in \text{RowSupp}(\tilde{B})\).

(P2) if \(\frac{1}{\lambda_s} \) is not an integer, \(\frac{1}{\lambda_s} > \frac{1}{\lambda_B} > \frac{1}{\lambda_M(\tilde{B})}\).

(P3) \(\left| \hat{b}_j^{(k)} \right| = \left| \hat{b}_j \right|_{\infty}\) for all \((j, k) \in \text{Supp}(\tilde{S})\).

(P4) if \(\frac{1}{\lambda_s} \) is not an integer, \(\forall j \exists k\) such that \((j, k) \notin \text{Supp}(\tilde{S})\) and \(\left| \hat{b}_j^{(k)} \right| = \left| \hat{b}_j \right|_{\infty}\).
Proof: We provide the proof of each property separately.

(P1) Suppose there exists \((j_0, k_0) \in \text{Supp}(\hat{S})\), such that 
\[
\text{sign}(\hat{s}^{(k_0)}_{j_0}) = -\text{sign}(\hat{b}^{(k_0)}_{j_0}).
\]
Let \(B, \hat{S} \in \mathbb{R}^{p \times r}\) be matrices equal to \(\hat{B}, \hat{S}\) in all entries except at \((j_0, k_0)\). Consider the following two cases:

1) \[
\text{sign}(\hat{s}^{(k_0)}_{j_0}) = -\text{sign}(\hat{b}^{(k_0)}_{j_0}) \leq \hat{b}^{(k_0)}_{j_0} : \text{Let } \hat{b}^{(k_0)}_{j_0} = \hat{b}^{(k_0)}_{j_0} + \hat{s}^{(k_0)}_{j_0}
\]
and \(\hat{s}^{(k_0)}_{j_0} = 0\). Notice that \((j_0, k_0) \notin \text{Supp}(\hat{S})\).

2) \[
\text{sign}(\hat{s}^{(k_0)}_{j_0}) + \hat{b}^{(k_0)}_{j_0} \geq \hat{b}^{(k_0)}_{j_0} : \text{Let } \hat{b}^{(k_0)}_{j_0} = -\text{sign}(\hat{s}^{(k_0)}_{j_0}) \hat{b}^{(k_0)}_{j_0} + \hat{s}^{(k_0)}_{j_0} = \hat{s}^{(k_0)}_{j_0} + \hat{b}^{(k_0)}_{j_0} - \hat{b}^{(k_0)}_{j_0}.
\]
Notice that \(\text{sign}(\hat{s}^{(k_0)}_{j_0}) = \text{sign}(\hat{b}^{(k_0)}_{j_0})\).

Since \(\hat{B} + \hat{S} = \hat{B} + \hat{S}\) and \(\|\hat{b}^{(k_0)}_{j_0}\|_\infty \leq \|\hat{b}^{(k_0)}_{j_0}\|_\infty\), it is a contradiction to the optimality of \((\hat{B}, \hat{S})\).

(P2) We prove the result in two steps by establishing 1. \(M(\hat{B}) > \frac{\lambda_s}{\lambda_0}\) and 2. \(D(\hat{S}) < \frac{\lambda_s}{\lambda_0}\).

1) In contrary, suppose there exists a row \(j_0 \in \text{RowSupp}(\hat{B})\) such that \(M(j_0, \hat{B}) \leq \frac{\lambda_s}{\lambda_0}\). Let \(k^*\) be the index of the element whose magnitude is ranked \(\left(\frac{\lambda_s}{\lambda_0}\right) + 1\) among the elements of the vector \(\hat{b}^{(k_0)}_{j_0} + \hat{s}^{(k_0)}_{j_0}\). Let \(B, \hat{S} \in \mathbb{R}^{p \times r}\) be matrices equal to \(\hat{B}, \hat{S}\) in all entries except on the row \(j_0\) and
\[
\hat{b}^{(k_0)}_{j_0} = \begin{cases} 
\hat{b}^{(k_0)}_{j_0} + \hat{s}^{(k_0)}_{j_0} & \text{sign}(\hat{s}^{(k_0)}_{j_0}) \geq \hat{b}^{(k_0)}_{j_0} + \hat{s}^{(k_0)}_{j_0} \\
\hat{b}^{(k_0)}_{j_0} + \hat{s}^{(k_0)}_{j_0} & \text{otherwise}
\end{cases}
\]
and \(\hat{s}^{(k_0)}_{j_0} = \hat{s}^{(k_0)}_{j_0} + \hat{b}^{(k_0)}_{j_0} - \hat{b}^{(k_0)}_{j_0}\). Notice that \(M(\hat{B}) > \frac{\lambda_s}{\lambda_0}\) and \(\text{sign}(\hat{s}^{(k_0)}_{j_0}) = \text{sign}(\hat{b}^{(k_0)}_{j_0})\) for all \((j_0, k_0) \in \text{Supp}(\hat{S})\). Since \(\hat{B} + \hat{S} = \hat{B} + \hat{S}\) and \(\|\hat{b}^{(k_0)}_{j_0}\|_\infty = \|\hat{b}^{(k_0)}_{j_0}\|_\infty + \|\hat{s}^{(k_0)}_{j_0}\|_\infty + \|\hat{b}^{(k_0)}_{j_0}\|_\infty\), this is a contradiction to the optimality of \((\hat{B}, \hat{S})\).

2) In contrary, suppose there exists a row \(j_0 \in \text{RowSupp}(\hat{S})\) such that \(\|\hat{s}^{(k_0)}_{j_0}\|_\infty \geq \frac{\lambda_s}{\lambda_0}\). Let \(k^*\) be the index of the element whose magnitude is ranked \(\left(\frac{\lambda_s}{\lambda_0}\right) + 1\) among the elements of the vector \(\hat{b}^{(k_0)}_{j_0} + \hat{s}^{(k_0)}_{j_0}\). Let \(B, \hat{S} \in \mathbb{R}^{p \times r}\) be matrices equal to \(\hat{B}, \hat{S}\) in all entries except on the row \(j_0\) and
\[
\hat{b}^{(k_0)}_{j_0} = \begin{cases} 
\hat{b}^{(k_0)}_{j_0} + \hat{s}^{(k_0)}_{j_0} & \text{sign}(\hat{s}^{(k_0)}_{j_0}) \geq \hat{b}^{(k_0)}_{j_0} + \hat{s}^{(k_0)}_{j_0} \\
\hat{b}^{(k_0)}_{j_0} + \hat{s}^{(k_0)}_{j_0} & \text{otherwise}
\end{cases}
\]
and \(\hat{s}^{(k_0)}_{j_0} = \hat{s}^{(k_0)}_{j_0} + \hat{b}^{(k_0)}_{j_0} - \hat{b}^{(k_0)}_{j_0}\). Notice that \(D(\hat{S}) < \frac{\lambda_s}{\lambda_0}\) and \(\text{sign}(\hat{s}^{(k_0)}_{j_0}) = \text{sign}(\hat{b}^{(k_0)}_{j_0})\) for all \((j_0, k) \in \text{Supp}(\hat{S})\). Since \(\hat{B} + \hat{S} = \hat{B} + \hat{S}\) and \(\|\hat{b}^{(k_0)}_{j_0}\|_\infty = \|\hat{b}^{(k_0)}_{j_0}\|_\infty + \|\hat{s}^{(k_0)}_{j_0}\|_\infty + \|\hat{b}^{(k_0)}_{j_0}\|_\infty\), this is a contradiction to the optimality of \((\hat{B}, \hat{S})\), due to the fact that \(\lambda_s \left(\frac{\lambda_s}{\lambda_0}\right) - 1 < \lambda_0 < \lambda_s\).

This concludes the proof of the lemma.

The next lemma shows why the assumption that the ratio of penalty regularizer parameters is crucial for our analysis. This is not a deterministic result, but since it is related to optimality conditions, we included this lemma in this appendix.

Lemma 12. If \((\hat{S}, \hat{B})\) with \(\hat{B} \neq 0\) is a solution to (I) and \(d = \frac{\lambda_s}{\lambda_0}\) is an integer then \((\hat{S}, \hat{B})\) is not the unique solution.

Proof: In contrary, assume that \((\hat{S}, \hat{B})\) is the unique solution. Take a non-zero row \(\hat{b}^{(k_0)}_{j_0}\) with \(j_0 \in \text{RowSupp}(\hat{B})\). If \(M(j_0, \hat{B}) < d\), then let \(\hat{B}, \hat{S} \in \mathbb{R}^{p \times r}\) be two matrices equal to \(\hat{B}, \hat{S}\) except on the row \(j_0\) and let \(\hat{b}^{(k_0)}_{j_0} = 0\) and \(\hat{s}^{(k_0)}_{j_0} = \hat{b}^{(k_0)}_{j_0} + \hat{s}^{(k_0)}_{j_0}\). Then, \((\hat{B}, \hat{S})\) are strictly better solutions than \((\hat{B}, \hat{S})\). This contradicts the optimality of \((\hat{B}, \hat{S})\). Hence,
\[ |M_{j_0}(\hat{B})| \geq d. \] with similar argument we can conclude that 
\[ |\hat{S}_{j_0}|_0 \leq d. \]

If \[ |\hat{S}_{j_0}|_0 = d, \] then let \( 0 < \delta \leq \min_{(j_0, k) \in \text{Supp}(\hat{S})} |\hat{b}_{j_0}^{(k)}| \) and \( \hat{\delta}(\delta), \hat{S}(\delta) \in \mathbb{R}^{p \times r} \) be two matrices equal to \( \hat{B}, \hat{S} \) except for the entries indexed \((j_0, k) \in \text{Supp}(\hat{S})\) and let \( \hat{\delta}_{j_0}^{(k)} = \hat{b}_{j_0}^{(k)} + \delta \text{sign} \left( \hat{b}_{j_0}^{(k)} \right) \) and \( \hat{s}_{j_0}^{(k)} = \hat{s}_{j_0}^{(k)} - \delta \text{sign} \left( \hat{s}_{j_0}^{(k)} \right) \) for all \((j_0, k) \in \text{Supp}(\hat{S})\). Then, \((\hat{B}(\delta), \hat{S}(\delta))\) is another solution to \( \text{(1)} \). This contradicts the uniqueness of \((\hat{B}, \hat{S})\).

If \[ |\hat{S}_{j_0}|_0 < d, \] then using Lemma \[ \text{[11]} \] and Equation \[ \text{[5]} \] we have
\[
\mathbb{P} \left[ |M_{j_0}(\hat{B})| \geq d + 1 \right] = \sum_{i=1}^{r-d} \mathbb{P} \left[ |M_{j_0}(\hat{B})| = d + i \right] = \sum_{i=1}^{r-d} \mathbb{P} \left[ \exists k_1, \ldots, k_{i+1} \in M_{j_0}(\hat{B}) \quad \forall t = 1, \ldots, i+1 : \right.
\]
\[
\|\hat{b}_{j_0}^{(k_{i+1})} + \hat{s}_{j_0}^{(k_{i+1})} - \hat{b}_{j_0}^{(k_{i+1})}\|_0 = \|\hat{b}_{j_0}^{(k_{i+1})}\|_\infty
\]
\[
= \sum_{i=1}^{r-d} \mathbb{P} \left[ \exists k_1, \ldots, k_{i+1} \in M_{j_0}(\hat{B}) \quad \forall t = 1, \ldots, i+1 : \right.
\]
\[
\|\Delta_{j_0}^{(k_{i+1})}\| = \|\hat{b}_{j_0}^{(k_{i+1})} + \hat{s}_{j_0}^{(k_{i+1})} - \hat{b}_{j_0}^{(k_{i+1})}\|_\infty
\]
\[
= \sum_{i=1}^{r-d} \mathbb{P} \left[ \exists k_1, \ldots, k_{i+1} \in M_{j_0}(\hat{B}) \quad \forall m = 1, \ldots, i+1 : \right.
\]
\[
\|\Delta_{j_0}^{(k_{i+1})}\| = \left| C_{k_1, k_{i+1}} \right| + \|\hat{b}_{j_0}^{(k_{i+1})}\|_\infty
\]
In above equation \( C_{k_1, k_{i+1}} \) are some constants. The last conclusion follows from the fact that \( \Delta_{j_0}^{(k_{i+1})} \)'s are continuous Gaussian variables and the cardinality of this event is less than the cardinality of the space they lie in. Hence, \( |M_{j_0}(\hat{B})| = d \).

Let \( 0 < \delta < \|\hat{b}_{j_0}\|_\infty \) and \( \hat{B}(\delta), \hat{S}(\delta) \in \mathbb{R}^{p \times r} \) be two matrices equal to \( \hat{B}, \hat{S} \) except for the entries indexed \((j_0, k) \) for \( k \in M_{j_0}(\hat{B}) \) and let \( \hat{b}_{j_0}^{(k)} = \hat{b}_{j_0}^{(k)} - \delta \) and \( \hat{s}_{j_0}^{(k)} = \hat{s}_{j_0}^{(k)} + \delta \) for all \( k \in M_{j_0}(\hat{B}) \). Then, \((\hat{B}(\delta), \hat{S}(\delta))\) is another solution to \( \text{(1)} \). This contradicts the uniqueness of \((\hat{B}, \hat{S})\).

Next lemma characterizes the optimal solution by introducing a dual variable \( Z \).

**Lemma 13 (Convex Optimality).** If \((\hat{B}, \hat{S})\) is a solution of \( \text{(1)} \) then there exists a matrix \( Z \in \mathbb{R}^{p \times r} \), called dual variable, such that \( Z \in \lambda_0 \delta ||\hat{S}||_{1,1} \) and \( Z \in \lambda_0 \delta ||B||_{1,1} \) and for all \( k = 1, \ldots, r \),
\[
\frac{1}{n} \left( X^{(k)} \right)^T \left( \hat{Z}^{(k)} + \hat{b}^{(k)} \right) - \frac{1}{n} \left( X^{(k)} \right)^T \hat{y}^{(k)} + \hat{Z}^{(k)} = 0.
\] (8)

**Proof:** The proof follows from the standard first order optimality argument.

### APPENDIX B

**COORDINATE DESCENT ALGORITHM**

We use the coordinate descent algorithm described as follows. The algorithm takes the tuple \((X, Y, \lambda_s, \lambda_b, \epsilon, B, S)\) as input, and outputs \((\hat{B}, \hat{S})\). Note that \( X \) and \( Y \) are given to this algorithm, while \( B \) and \( S \) are our initial guess or the warm start of the regression matrices. \( \epsilon \) is the precision parameter which determines the stopping criterion.

We update elements of the sparse matrix \( S \) using the subroutine \( \text{UpdateS} \), and update elements in the block sparse matrix \( B \) using the subroutine \( \text{UpdateB} \), respectively, until the regression matrices converge. The pseudocode is in Algorithm 1 to Algorithm 3.

**Algorithm 2 Our Model Solver**

**Input:** \( X, Y, \lambda_s, \lambda_b, B, S \) and \( \epsilon \)

**Output:** \( \hat{S} \) and \( \hat{B} \)

**Initialization:**

for \( j = 1 : p \) do

for \( k = 1 : r \) do

\( c_j^{(k)} \leftarrow X_j^{(k)} y_j \)

for \( i = 1 : p \) do

\( d_{i,j}^{(k)} \leftarrow X_i^{(k)} X_j^{(k)} \)

end for

end for

end for

**Updating:**

loop

\( S \leftarrow \text{UpdateS}(c; d; \lambda_s; B; S) \)

\( B \leftarrow \text{UpdateB}(c; d; \lambda_b; B; S) \)

if Relative Update < \( \epsilon \) then

BREAK

end if

end loop

RETURN \( \hat{B} = B, \hat{S} = S \)

**A. Correctness of Algorithms**

In this algorithm, \( B \) is the block sparse matrix and \( S \) is the sparse matrix. We alternatively update \( B \) and \( S \) until they converge. When updating \( S \), we cycle through each element of \( S \) while holding all the other elements of \( S \) and \( B \) unchanged; When updating \( B \), we update each block \( B_j \) (the coefficient vector of the \( j \)th feature for \( r \) tasks) as a whole, while keeping \( S \) and other coefficient vector of \( B \) fixed.

For updating \( B \), the subproblem is updating \( B_j \)

\[
\hat{b}_j = \arg\min_{b_j} \frac{1}{2} \sum_{k=1}^{r} \left\| r_j^{(k)} - b_j^{(k)} X_j^{(k)} \right\|_2^2 + \lambda_b \| b_j \|_\infty \quad \text{(9)}
\]

If we take the partial residual vector \( r_j^{(k)} = y_j^{(k)} - \sum_{i \neq j} (b_i^{(k)} X_i^{(k)}) - \sum_i (d_i^{(k)} X_i^{(k)}) \), the correctness
Algorithm 3 UpdateB

**Input:** c, d, \( \lambda_b \), B and S

**Output:** B

Update B using the cyclic coordinate descent algorithm for \( \ell_1/\ell_\infty \) while keeping S unchanged.

\[
\text{for } j = 1 : p \text{ do } \\
\quad \text{for } k = 1 : r \text{ do } \\
\quad \quad \alpha_j^{(k)} \leftarrow c_j^{(k)} - \sum_{i \neq j} (b_i^{(k)} + s_i^{(k)})d_{i,j} - s_i^{(k)}d_{j,j} \\
\quad \quad \text{if } \sum_{k=1}^r |\alpha_j^{(k)}| \leq \lambda_b \text{ then } \\
\quad \quad \quad b_j \leftarrow 0 \\
\quad \quad \text{else } \\
\quad \quad \quad \text{Sort } \alpha \text{ to be } |\alpha_j^{(k_1)}| \geq |\alpha_j^{(k_2)}| \geq \cdots \geq |\alpha_j^{(k_r)}| \\
\quad \quad \quad m^* = \arg \max_{1 \leq m \leq r} (\sum_{k=1}^r |\alpha_j^{(k_m)}| - \lambda_b)/m \\
\quad \quad \quad \text{for } i = 1 : r \text{ do } \\
\quad \quad \quad \text{if } i > m^* \text{ then } \\
\quad \quad \quad \quad \beta_j^{(k_i)} \leftarrow \alpha_j^{(k_i)} \\
\quad \quad \quad \text{else } \\
\quad \quad \quad \quad \beta_j^{(k_i)} \leftarrow \frac{\text{sign}(\alpha_j^{(k_i)})}{m^*} (\sum_{i=1}^{m^*} |\alpha_j^{(k_i)}| - \lambda_b) \\
\quad \quad \quad \text{end if } \\
\quad \quad \text{end for } \\
\quad \quad \text{end if } \\
\quad \text{end for } \\
\text{end for } \\
\text{RETURN } B
\]

Algorithm 4 Update-S

**Input:** c, d, \( \lambda_s \), B and S

**Output:** S

Update S using the cyclic coordinate descent algorithm for LASSO while keeping B unchanged.

\[
\text{for } j = 1 : p \text{ do } \\
\quad \text{for } k = 1 : r \text{ do } \\
\quad \quad \alpha_j^{(k)} \leftarrow c_j^{(k)} - \sum_{i \neq j} (b_i^{(k)} + s_i^{(k)})d_{i,j} - s_i^{(k)}d_{j,j} \\
\quad \quad \text{if } |\alpha_j^{(k)}| \leq \lambda_s \text{ then } \\
\quad \quad \quad s_j^k \leftarrow 0 \\
\quad \quad \text{else } \\
\quad \quad \quad s_j^k \leftarrow \alpha_j^{(k)} - \lambda_s \text{sign}(\alpha_j^{(k)}) \\
\quad \quad \text{end if } \\
\quad \text{end for } \\
\text{end for } \\
\text{RETURN } S
\]

of this algorithm will directly follow from the correctness of coordinate descent algorithm of \( \ell_1/\ell_{\infty} \) in [9]. With the same argument, the correctness of the Algorithm 3 can be proven.