Deriving Mixture Distributions Through Moment-Generating Functions

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ABSTRACT

This article aims to make use of moment-generating functions (mgfs) to derive the density of mixture distributions from hierarchical models. When the mgf of a mixture distribution doesn’t exist, one can extend the approach to characteristic functions to derive the mixture density. This article uses a result given by E.R. Villa, L.A. Escobar, Am. Stat. 60 (2006), 75–80. The present work complements E.R. Villa, L.A. Escobar, Am. Stat. 60 (2006), 75–80 article with many new examples.

1. INTRODUCTION

A random variable $X$ is said to have mixture distribution if it depends on a quantity that has a distribution. The mixture distribution arises from a hierarchical model (see [1], p. 165). A typical example of a hierarchical model is as follows: Consider a large number of eggs laid by an insect. The survival of each egg has a probability $\theta$. If each egg's survival is independent, then we have a sequence of Bernoulli trials on egg's survival. Assume that the "large number" of eggs laid is a random variable and follows the Poisson distribution with parameter $\lambda$. Hence, if we let $X$ is equal to the number of survivors and $Y$ is equal to the number of eggs laid, then

$$X|Y=y \text{ follows Binomial (} Y, \theta \text{) and } Y \text{ follows Poisson (} \lambda \text{),}$$

constitute a hierarchical model, where the notation $X|Y=y$ denotes the conditional distribution of $X$ given $Y = y$ follows Binomial $(Y, \theta)$, and the (marginal) distribution of $Y$ is Poisson $(\lambda)$. It turns out that the (marginal) distribution of $X$ is Poisson $(\lambda \theta)$. Thus, the distribution of the number of survivors $X$, which is Poisson $(\lambda \theta)$, is a mixture distribution as it is a result of combining the distribution of $X|Y$ and the distribution of $Y$. In general, hierarchical models lead to mixture distributions.

Mixture models play an important role in the theory and practice. There are textbooks, monographs, and journal articles discussing history, theory, applications, and the usefulness of mixture models. Mixture models became popular as, among others: (a) provide a simple device to include other variation and correlation in the model, (b) add model flexibility, and (c) allow modeling the data that arise in multi-stages. The literature shows several authors, namely Everitt and Hand [2], Titterington et al. [3], Böhning [4], McLachlan and Peel [5] have discussed mixture models and provided the statistical methodology and references on finite mixtures.

Lindsay [6] discussed the application of mixture models and its interrelation with other related fields, among others. In discussing mixture models, Casella and Berger [1] showed the derivation of mixture models from hierarchical models. Panjer and Willmot [7] consider applications of mixture models in actuarial sciences. Karlis and Xekalaki [8] derived results related to Poisson mixtures models with applications in various other fields. The mixture models of continuous and discrete types can be found in Johnson et al. [9,10] and Gelman et al. [11]. To fit plant quadrat data on the blue-green sedge, Skellam [12] used a mixture of binomial with varying sample sizes modeled with Poisson distributions. The Gamma mixture of Poisson r.v.'s yield negative-binomial, while Green and Yule [13] used this mixture distribution to model "accident proneness"; see Bagui and Mehra [14]. The research dated back to Pearson [15] shows modeling the mixing of different

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2. MIXTURE MODEL

Consider a two-stage mixture model of type (1) where \( X|Y \sim f_{X,Y}(x|y) \) and \( Y \sim f_Y(y) \). It is customary to derive the mixture distribution \( f_X(x) \) of the mixture \( X \) from the joint density of \( X \) and \( Y \), \( f_{X,Y}(x|y) = f_Y(y)f_X(x|y) \), as

\[
f_X(x) = \begin{cases} 
\int_{-\infty}^{\infty} f_Y(y)f_{X,Y}(x|y)dy & \text{if } Y \text{ is continuous} \\
\sum_{y} f_Y(y)f_{X,Y}(x|y) & \text{if } Y \text{ is discrete}
\end{cases}
\]

Villa and Escobar [17] derived mixture distributions from the moment-generating function (mgf) of \( X \), and they derived the mgf of \( X \) as

\[ M_{X,Y}(t) = E[M_{X|Y}(t)] = a_1(t)e^{a_2(t)Y} \]

where \( a_1(t) \) and \( a_2(t) \) are functions of \( t \) and may also depend on the parameter of the distribution of \( X|Y \). Then they arrived at the mgf of \( X \) as

\[ M_X(t) = E[M_{X|Y}(t)] = a_1(t)M_Y[a_2(t)] \]  

In the above, we assumed that all mgf's exist. When mgf of \( X|Y \) is not found from the known list, then the mgf of \( X \) can be computed directly as

\[ M_X(t) = E(e^{X}) = E(E(e^{X}|Y)) \]

From the joint mgf of \( X \) and \( Y \), \( M_{X,Y}(t,s) \), one can also derive the mgf of \( X \) as

\[ M_X(t) = E[M_{X|Y}(t)] = E(E(e^{X+Y}|Y)) = E(e^{Y}E(e^{X}|Y)) = E(e^{Y}M_{X|Y}(t)) \]

Then by setting \( s = 0 \) in the above Eq. (6), one would get the mgf of \( X \), \( M_X(t) \).

The main goal of this article is to derive mixture distributions that complements the examples of Villa and Escobar [17] using the above mgf method.

3. EXAMPLES

There are situations where obtaining the mixture distributions by using mgf is much easier than getting it by the marginalization of the joint distribution. The examples considered here are the complements of the cases discussed by Villa and Escobar [17].

3.1. The Binomial–Binomial Mixture

The mixture model of the Binomial mixture of Binomial random variables is

\[
\begin{align*}
X|Y & \sim \text{BIN}(Y, p_1) \\
Y & \sim \text{BIN}(n, p_2)
\end{align*}
\]

\[
\Rightarrow X \sim \text{BIN}(n, p_1p_2).
\]

Proof. The mgf for \( X|Y \) is

\[ M_{X,Y}(t) = \left[q_1 + p_1e^t\right]^Y = e^{\ln(q_1 + p_1e^t)} = a_1(t)e^{a_2(t)Y}, \]

where \( q_1 = 1 - p_1 \), \( a_1(t) = 1 \), and \( a_2(t) = \ln(q_1 + p_1e^t) \).

Now by Eq. (4),

\[ M_X(t) = a_1(t)M_Y[a_2(t)] = M_Y[\ln(q_1 + p_1e^t)] \]

\[ = \left[q_2 + p_2e^{\ln(q_1 + p_1e^t)}\right]^n = \left[q_2 + p_2(q_1 + p_1e^t)\right]^n \]

\[ = \left[q + pe^t\right]^n \text{, Binomial mgf}, \]

\[ (8) \]
where \( p = p_1p_2 \) and \( q = q_2 + p_2q_1 = 1 - p_1p_2 = 1 - p. \)
Thus, it follows from (8) that \( X \sim \text{BIN} \left( n, p, p_2 \right) \), (see Appendix, Table A1, Villa and Escobar [17]).

### 3.2. The Negative-Binomial–Binomial Mixture

The mixture model of the Negative-binomial mixture of Binomial random variables is

\[
X \mid Y \sim \text{BIN} \left( Y, p_1 \right) \quad Y \sim \text{NEGBIN} \left( \alpha, p \right),
\]

where \( p = p_2 / (p_2 + p_1p_2) \) and \( q_2 = 1 - p_2. \)

**Proof.** The mgf for \( X \mid Y \) is

\[
M_{X|Y}(t) = \left[ q_1 + p_1 e^{t} \right]^\alpha = e^{\ln(q_1 + p_1 e^{t})} = a_1(t)e^{a_2(t)Y},
\]

where \( q_1 = 1 - p_1, a_1(t) = 1, \) and \( a_2(t) = \ln (q_1 + p_1 e^{t}). \)

Now by Eq. (4),

\[
M_{X}(t) = a_1(t)M_{Y}[a_2(t)] = M_{Y}\left[ \ln \left( q_1 + p_1 e^{t} \right) \right]
\]

\[
= \left[ \frac{p_2}{1 - (1 - p_2) e^{\ln(q_1 + p_1 e^{t})}} \right]^\alpha = \left[ \frac{p_2}{1 - (1 - p_2) (q_1 + p_1 e^{t})} \right]^\alpha, \text{ negative-binomial mgf},
\]

where \( p = p_2 / (p_2 + p_1p_2) \). Thus, it follows from (10) that \( X \sim \text{NEGBIN}(\alpha, p) \), (see Appendix, Table A2, Villa and Escobar [17]).

### 3.3. The Exponential–Exponential Mixture

The mixture model of the exponential mixture of shifted exponential random variables is

\[
X \mid Y \sim \lambda e^{-\lambda(x-Y)}, \ x \geq Y \quad Y \sim (1 + \lambda)e^{-(1+\lambda)y}, y \geq 0 \quad \Rightarrow \quad X \sim \lambda(1 + \lambda)e^{-\lambda(x)} (1 - e^{-x}), \ x \geq 0.
\]

**Proof.** The mgf for \( X \mid Y \) is given by

\[
M_{X|Y}(t) = E_{X|Y}\left[ e^{Xt} \right] = \lambda \int_{Y}^{\infty} e^{tx} e^{-\lambda(x-y)} dx = \lambda e^{\lambda Y} \int_{Y}^{\infty} e^{-t(\lambda - x)} dx = \frac{\lambda e^{\lambda Y}}{(\lambda - t)}, \ t < \lambda,
\]

where \( a_1(t) = \frac{\lambda}{\lambda - t} \) and \( a_2(t) = t. \)

Now by Eq. (4),

\[
M_{X}(t) = \frac{\lambda}{\lambda - t} M_{Y}(t) = \frac{\lambda(1 + \lambda)}{(\lambda - t)(\lambda + 1 - \lambda - t)}.
\]

The above mgf is the mgf of the density \( f_X(x) = \lambda(1 + \lambda)e^{-\lambda x} (1 - e^{-x}), x \geq 0 \). It follows from (13) that \( X \sim \lambda(1 + \lambda)e^{-\lambda x} (1 - e^{-x}), x \geq 0. \)

#### 3.3.1. A specific exponential–exponential mixture

The mixture model of a specific exponential mixture of shifted exponential random variables is

\[
X \mid Y \sim e^{-(x-Y)}, \ x \geq Y \quad Y \sim e^{-Y}, \ y \geq 0 \quad \Rightarrow \quad X \sim \text{Gamma}(2, 1), \ x \geq 0.
\]
Proof. The mgf for $X|Y$ is given by

$$M_{X|Y}(t) = E_{X|Y}[e^{tX}] = \frac{e^{tY}}{1-t}, \quad (15)$$

where $a_1(t) = \frac{1}{1-t}$ and $a_2(t) = t$. Now by Eq. (4),

$$M_Y(t) = \frac{1}{1-t} M_Y(t) = \frac{1}{1-t} \times \frac{1}{1-t} = \frac{1}{(1-t)^2}, \quad (16)$$

Eq. (16) confirms that $X \sim \text{Gamma}(2, 1)$.

### 3.3.2. The exponential–normal mixture

The mixture model of the exponential mixture of normal random variables is

$$X|Y \sim \frac{1}{\sqrt{2\pi}} e^{-\frac{1}{2}(x-y)^2}, \quad -\infty < x < \infty \quad Y \sim e^{-y}, \quad y \geq 0$$

$$\Rightarrow X \sim \text{Convolution of } Y \text{ and an independent } Z \sim N(0, 1), \quad (17)$$

Proof. The mgf for $X|Y$ is given by

$$M_{X|Y}(t) = E_{X|Y}[e^{tX}] = e^{tY+\frac{t^2}{2}}, \quad (18)$$

where $a_1(t) = e^{t/2}$ and $a_2(t) = t$. Now by Eq. (4),

$$M_X(t) = e^{t/2} M_Y(t) = \frac{e^{t/2}}{(1-t)}, \quad (19)$$

which is the mgf of the convolution of $Y$ and an independent $Z \sim N(0, 1)$. Thus, $X$ follows the distribution of the convolution of $Y$ and an independent $Z \sim N(0, 1)$.

### 3.4. The Poisson–Chi-square Mixture

The mixture model of the Poisson mixture of Chi-square random variables is

$$X|Y \sim \chi^2_{n+2Y}, \quad x \geq Y \quad Y \sim \text{Poi}(\lambda)$$

$$\Rightarrow X \sim \chi^2_{n+2\lambda}, \quad (20)$$

Proof. The mgf for $X|Y$ is given by

$$M_{X|Y}(t) = E_{X|Y}[e^{tX}] = (1 - 2t)^{-(n+2Y)/2} = (1 - 2t)^{-n/2} e^{-\ln(1-2t)Y}, \quad (21)$$

where $a_1(t) = (1 - 2t)^{-n/2}$ and $a_2(t) = -\ln(1 - 2t)$. Now by Eq. (4),

$$M_X(t) = (1 - 2t)^{-n/2} M_Y[-\ln(1 - 2t)]$$

$$= (1 - 2t)^{-n/2} e^{\lambda(\ln(1-2t)-1)}$$

$$= (1 - 2t)^{-n/2} e^{2\lambda(1-2t)}, \quad (22)$$

which is an mgf of a noncentral chi-square distribution that has a noncentrality parameter $2\lambda$. It follows from (22) that $X$ has the noncentral chi-square distribution with the noncentrality parameter $2\lambda$. 
3.5. The Geometric–Gamma Mixture

The mixture model of the Geometric mixture of Gamma random variables is

\[ X|Y \sim \text{Gamma}(Y, \beta), \]
\[ Y \sim \text{Geometric}(\theta) \]

\( \Rightarrow X \sim \text{EXP}(\beta/\theta). \) (23)

**Proof.** The mgf for \( X|Y \) is given by

\[ M_{X|Y}(t) = E_{X|Y}[e^{itX}] = (1 - \beta t)^{-Y} = e^{-Y \ln(1 - \beta t)}, \] (24)

where \( a_1(t) = 1 \) and \( a_4(t) = -\ln(1 - \beta t). \) Now by the Eq. (4),

\[ M_{X}(t) = M_{Y} \left[ \ln(1 - \beta t)^{-1} \right] = \frac{\theta e^{\ln(1 - \beta t)^{-1}}}{1 - (1 - \theta) e^{\ln(1 - \beta t)^{-1}}} = \frac{\theta (1 - \beta t)^{-1}}{1 - (1 - \theta)(1 - \beta t)^{-1}} = \frac{\theta}{\theta - \beta t} = \frac{1}{1 - (\beta/\theta)t}, \] (25)

which is an mgf of an exponential distribution with shape parameter \( \beta/\theta. \) Thus, \( X \sim \text{EXP}(\beta/\theta). \)

4. EXTENSION TO MIXTURES THAT DO NOT HAVE AN mgf

When mgfs do not exist for the mixture distribution, one uses the characteristic function (cf) for the mixture distributions.

The cf of an r.v. \( X \) is defined by \( \phi_X(t) = E \left( e^{itX} \right), \) where \( t \in R \) and \( i = \sqrt{-1}. \) The conditional characteristic of \( X|Y \) is denoted and defined by \( \phi_{X|Y}(t) = E \left( e^{itX}|Y \right). \)

**The Chi-square–Normal Mixture**

\[ X|Y \sim N(0, 1/Y) \]
\[ Y \sim X^2 \]

\( \Rightarrow X \sim \text{Cauchy}(0, 1). \) (26)

**Proof.** The cf of \( X|Y \) is

\[ \phi_{X|Y}(t) = E \left( e^{itX}|Y \right) = e^{-t^2/Y}. \] (27)

The cf of \( X \) can be obtained from the Eq. (27) as

\[ \phi_X(t) = E \left[ \phi_{X|Y}(t) \right] = E \left[ e^{-t^2/Y} \right] = \int_0^\infty e^{-y^2} \frac{1}{\sqrt{2\pi}} y^{1/2-1} e^{-y/2} dy. \] (28)

Now with the transformation \( |t|z = y \) and simplifying (28), we have

\[ \phi_X(t) = \sqrt{\frac{2|t|}{\pi}} \times \frac{1}{2} \int_0^\infty z^{1/2-1} e^{-|t|z^{1/2+1/2}} dz = \sqrt{\frac{2|t|}{\pi}} \times K_{1/2} \left( |t| \right), \] (29)

where, \( K_u(v) \) is the modified Bessel function of third kind defined by

\[ K_u(v) = \frac{1}{2} \int_0^\infty z^{u-1} e^{-v/2} z^{1/2} dz, \ -\infty < u < \infty. \] (30)

It should be noted that asymptotic form for the modified Bessel function of the third kind is

\[ K_u(z) \sim \sqrt{\frac{\pi}{2z}} e^{-z} \left( 1 + \frac{4z^2 - 1}{8z} + \frac{(4z^2 - 1)(4z^2 - 9)}{2! (8z)^2} + \frac{(4z^2 - 1)(4z^2 - 9)(4z^2 - 25)}{3! (8z)^3} + \cdots \right). \] (31)

Therefore, by Eq. (31), we have

\[ K_{1/2}(v) = \sqrt{\frac{\pi}{2z}} e^{-z}, \] (32)
Now by Eqs. (29) and (32), we obtain the cf \( \phi_X(t) \) as
\[
\phi_X(t) = \sqrt{\frac{2|t|}{\pi}} \times \sqrt{\frac{\pi}{2|t|}} e^{-|t|} = e^{-|t|},
\]
which is the cf of the standard Cauchy distribution. Thus, we conclude that \( X \sim \text{Cauchy}(0, 1) \).

**Remarks.** The \( F \) distribution arises from the mixture of chi-square and Gamma distribution and it has no mgf. In this case, one may derive the cf of this mixture distribution. The \( t \)-distribution arises from the mixture of chi-square and normal distribution and it has no mgf, Hurst [18]. Similarly, Pareto distribution is a mixture of distributions and has no mgf. In all these cases, a cf can be used in the derivation of the mixture distributions.

5. CONCLUDING REMARKS

Mixture models play vital roles in statistics. They are used in modeling actuarial applications, biological spatial data, "accident proneness," plant data on sedge Carex flacca, and applied in many other areas of statistics. Because of the high importance of mixture distributions, students should be exposed to mixture distributions as soon as they have familiarity with conditional expectations. In the current textbooks, mixture distributions are derived from the joint distribution that originated from hierarchical mixture models as a marginal distribution.

This article finds mixture distributions using mgf method. The derivation of mixture distribution using mgfs is, in general, more straightforward and shorter than an origin of the marginal density of mixture random variable from a joint density. It is because, in the present method, one relies on mgfs that have already been derived or available. However, there are examples where the derivation of the marginal density of the mixture r.v. from a joint density is much simpler.

On the other hand, there are two difficulties in the mgf methods. First, one cannot get \( a_1(t) \) and \( a_2(t) \) as given in Eq. (3), for all mgfs \( M_{X|Y}(t) \) of the conditional distributions of \( X|Y \). Second, sometimes it is hard to map the derived mgf \( M_{X}(t) \) with a distribution. It requires good knowledge with familiarization of various distributions and corresponding mgfs. The mixtures that do not have an mgf, one can extend the mgfs method to cfs method.

As pointed out by [17], the idea of using mgf method for mixture distribution can be introduced in senior mathematical statistics courses at the level of Wackerly et al. [19] and Larsen and Marx [20] for students who are exposed to conditional expectations and mgfs. This article is directed to first-year graduate students in the mathematical statistics course at the level of Casella and Berger [1]. The mgf technique is underexposed in the current textbooks. From a pedagogical standpoint, mgf techniques can be used as a useful tool to derive mixture distributions. For mixtures that do not have an mgf, students with a background in complex analysis may use the cfs to extend the approach. Finally, the techniques learned here can be profitably used in the study of Bayes’ procedures.

CONFLICTS OF INTEREST

Authors have no conflict of interest to declare.

AUTHORS’ CONTRIBUTIONS

All authors contributed equally.

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APPENDIX

Table A.1 | Examples of other mixture distributions that have moment-generating functions (mgfs) [17].

| Conditional | Mixing | Marginal |
|-------------|--------|---------|
| X| Y ~ f(x|Y) | Y ~ g(y) | X ~ f_2(x) |
| BIN (Y, p) | POI (λ) | POI (pα) |
| POI (Y) | GAM (α, β) | NEGBIN (α, 1/(1 + β)) |
| NOR (Y, σ^2) | NOR (μ, τ^2) | NOR(μ, σ^2 + τ^2) |
| POI (Y) | φ POI (αt) | Neyman-Λ (λ, φ) |
| POI (Y) | GIG (y, x, ψ) | SICHEL (γ, 2/ψ^2, √χ(ψ + 2)) |
| LEV (Y, σ) | σ SEV (ξ, 1) | LOGIS(μ, σ), μ = ξσ |
| ∑_n X_i | Λ LOGSER (p) | POI (λ) | NEGBIN (−1/(λ + p)) |

Table A.2 | List of probability density functions or probability mass functions and corresponding moment-generating functions (mgfs) [17].

| Distribution | Ppdf/pmff(x) | mgf |
|-------------|-------------|-----|
| BIN (n, p) | (n^k)(1 − p)^n−k, k = 0, 1, ⋯ , n | (1 − p + pe^t)^n |
| CHISQ (χ^2_n) | 1/Γ(n/2) x^(n-2)e^−x, x ≥ 0 | 1/(2e^−2^t), t < 1/2 |
| CHISQ - noncentral (χ^2_n, λ) | 1/2 e^−(x+λ)/2 (x/2)^(k-2)/2 (√λx) | exp(λ/2) (1 − 2t)^−k/2, t < 1/2 |
| EXP (λ) | λe^−λx, x ≥ 0 | λ/λt, t < λ |
| GAM (α, β) | 1/Γ(α/β) x^(α−1)e^−x/β, x ≥ 0 | 1/(1 − e^−βt), t < 1/β |
| GEO (p) | p(1 − p)^(k−1), k = 1, 2, ⋯ | 1/(1 − e^−pt), t < ln(1 − p) |
| GIG (y, x, ψ) | (ψx)^y/(x/2)^y−1/2 e^−x/(x+y) | exp(μt)Γ(1 − σt), t < 1/σ |
| LEV (μ, σ) | 1/2 [φ_(lev) (x/σ)] , x ∈ R | exp(μt)Γ(1 − σt), t < 1/σ |
| LOGIS (μ, σ) | 1/2 [φ_(logis) (x−μ)/σ], x ∈ R | exp(μt)Γ(1 − σt), |t| < 1/σ |
| LOGSER (p) | (1−p)^t/(x−p), x ∈ 1, 2, ⋯ | ln[1/(1−e^−pt)], t < ln(1 − p) |
| NEGBIN (α, p) | (x+1)^p/(x−1)^α, x = 0, 1, ⋯ | [p/(1−e^−pt)], t < −ln(1 − p) |
| NOR (μ, σ^2) | 1/√(2πσ^2) e^−(x^2)/(2σ^2), x ∈ R | exp(μt + σ^2t^2/2) |
| SEV (μ, σ) | 1/2 [φ_(sev) (x−μ)/σ], x ∈ R | exp(μt)Γ(1 + σt), t > −1/σ |
| SICHEL (γ, θ, α) | 1/(α−γ) K_+(α), x ∈ N | 1/(α−θ) Γ^2 K_+(α−θ, α) − ln θ |

Here, n denotes the number of trials, p is the probability of success, α and β are the shape parameters for the Gamma distribution, y is the response variable, x is the explanatory variable, χ is the chi-squared distribution, λ is the rate parameter, σ is the scale parameter, μ is the location parameter, σ is the shape parameter, p is the probability of success, α is the shape parameter, λ is the scale parameter, θ is the location parameter, and γ is the shape parameter for the Sichel distribution. The mgf is the moment-generating function, which is a function of the parameter t used to compute moments of the distribution.