Existence of two solutions for a fourth-order difference problem with $p(k)$ exponent

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Abstract
The existence of nontrivial solutions for a fourth-order discrete anisotropic boundary value problem involving the $p(k)$-Laplacian operator with the Dirichlet and the Neumann boundary value conditions is investigated. Variational approach based on a new critical point theorem is applied. An example is inserted to illustrate main results.

Keywords Discrete nonlinear boundary value problems · Nontrivial solution · Variational methods · Critical point theory

Mathematics Subject Classification 39A10 · 47A75 · 34B15

1 Introduction
The study of discrete boundary value problems has attracted intense research interests in the last decade. Modeling of certain nonlinear problems led to the rapid development of the theory of difference equations; see the monograph of [1]. Recently there have been an increasing interest to the existence and multiplicity results to boundary value problems for difference equations with the $p(k)$-Laplacian operator. Continuous versions of this kind of problem are known to be mathematical models of various phenomena arising in the study of elastic mechanics (see [24]), electrorheological fluids (see [22]), and image restoration (see [8]). Continuous variational anisotropic problems were started by Fan and Zhang in [9]. The research concerning the discrete fourth-order anisotropic problems have only been started,
see [17,20] and have been followed by the other authors (see [18,19]), where known tools from the critical point theory are applied to prove the existence of solutions. Concerning the fourth-order problems with exponent variable we mainly follow [18].

The results on this topic are usually achieved by using fixed point theorems in cones (see [3] and references therein). Another tool in the study of nonlinear difference equations is the upper and lower solution method (see, for instance, [13] and references therein). It is well known that variational method and critical point theory are important tools to deal with the problems for differential equations. Recently, the existence and multiplicity of solutions for nonlinear discrete boundary value problems have been investigated by adopting variational methods (see [2,12,15]).

The main goal of this paper is to establish the existence of three solutions for the discrete anisotropic problem with a positive real parameter \( \lambda \) on the form

\[
\begin{aligned}
- \Delta^2 (w(k-2)\phi_{p(k-2)}(\Delta^2 u(k-2))) + q(k)u(k)|^{p(k)-2}u(k) \\
= \lambda f(k,u(k)), \quad k \in [1,T],
\end{aligned}
\]

\( u(-1) = u(T+2) = \Delta u(-1) = \Delta u(T+1) = 0, \)

where \( T \geq 2 \) is a fixed positive integer, \([1,T]\) is the discrete interval \([1, \ldots , T]\), \( f : [1,T+2] \times \mathbb{R} \to \mathbb{R} \) is a continuous function, \( w : [-1,T+2] \to [1, \infty ) \), \( p : [-1,T+2] \to [2, \infty ) \) and \( q : [1,T+2] \to [1, \infty ) \) are given functions, \( \Delta u(k) = u(k+1) - u(k) \) is the forward difference operator and \( \phi_{p(k)} \) is the so called the \( p(k) \)-Laplacian operator defined as \( \phi_{p(k)}(s) = |s|^{p(k)-2}s \).

Directly from the definition of the forward difference operator we have

\( \Delta^2 u(k) = \Delta(\Delta u(k)) = u(k+2) - 2u(k+1) + u(k). \)

Let us put

\[
\begin{aligned}
p^+ &:= \max_{k \in [-1,T+2]} p(k), & p^- &:= \min_{k \in [-1,T+2]} p(k), \\
q^+ &:= \max_{k \in [1,T+2]} q(k), & w^+ &:= \max_{k \in [-1,T+2]} w(k), \\
\bar{q} &:= \sum_{k=1}^{T+2} q(k), & \bar{w} &:= \sum_{k=1}^{T+2} w(k-2).
\end{aligned}
\]

Research concerning the discrete anisotropic problems of type (1) was initiated by Kone and Ouaro in [17] and by Mihăilescu, Rădulescu and Tersian in [20]. One can find in [4] and [6] further tools and ideas to study anisotropic discrete nonlinear problems. For the continuous counterpart of the fourth order discrete problems, one can see [23]. Also we may think of (1) as a discrete analogue of the fourth-order functional differential equation

\[
\begin{aligned}
\frac{d^2}{dt^2}(w(t)) \frac{d^2 u(t)}{dt^2} |^{p-2} \left( \frac{d^2 u(t)}{dt^2} \right) + q(t)|u(t)|^{p-2}u(t) = f(t,u(t)), \quad t \in (0,1), \\
u(0) = u(1) = u''(0) = u''(1) = 0.
\end{aligned}
\]

A special case of the above equation is the equation

\[
\begin{aligned}
u^{(4)}(t) = f(t,u(t)), \quad t \in (0,1), \\
u(0) = u(1) = u''(0) = u''(1) = 0,
\end{aligned}
\]

which is used to model deformations of elastic beams [7,14,21].

The paper is arranged as follows. In Sect. 1 we recall the main tools. In Sect. 2, we introduce notations and provide several inequalities useful in our investigations. After variational
framework in Sect. 3 we formulate and prove the main result and special case. Finally we present an example.

2 Preliminaries

Let $E$ be a real finite dimensional space. Given two Gâteaux differentiable mappings $\Phi, H : E \to \mathbb{R}$ with derivatives $\varphi, h : E \to E^*$ we consider the following abstract equation

$$\varphi(u) = h(u), \quad u \in E.$$  \hspace{1cm} (2)

We denote by $J : E \to \mathbb{R}$ the action functional connected with (2), i.e.

$$J(u) = \Phi(u) - H(u).$$

**Theorem 1** [10, Corollary 3.3] Assume that $X \subset E$ contains at least two points. Assume that $H$ and $\Phi$ are convex on $E$. Let there exist $u \in E, v \in X$ satisfying $\varphi(v) = h(u)$ such that $J(u) \leq \inf_{x \in X} J(x)$. Then $u$ is a critical point to $J$, and thus it solves (2).

We finish with a simple multiplicity result.

**Theorem 2** [10, Theorem 3.4] Assume that $X \subset E$ contains at least two points. Assume that $H$ and $\Phi$ are convex on $E$. Let there exist $u \in E, v \in X$ satisfying $\varphi(v) = h(u)$ such that $J(u) \leq \inf_{x \in X} J(x)$. Then $u$ is a critical point to $J$, and thus it solves (2). If, moreover, $J$ is anti-coercive, then (2) has another solution different from $u$.

3 Auxiliary inequalities

Let us define the Euclidean space

$$W := \{u : [-1, T + 2] \to \mathbb{R} : \Delta u(-1) = \Delta u(T + 1) = u(-1) = u(T + 2) = 0\},$$

which is equipped with the norm

$$\|u\| := \left(\sum_{k=1}^{T+2} \left( w(k-2) |\Delta^2 u(k-2)|^{p^-} + q(k) |u(k)|^{p^-} \right) \right)^{1/p^-}.$$  \hspace{1cm} (3)

Let us also define the following equivalent norms

$$\|u\|_+ := \left(\sum_{k=1}^{T+2} \left( w(k-2) |\Delta^2 u(k-2)|^{p^+} + q(k) |u(k)|^{p^+} \right) \right)^{1/p^+},$$

$$\|u\|_{\max} := \max_{k \in [-1, T+2]} |u(k)|$$

and the Luxemburg norm

$$\|u\|_{\rho(\cdot)} = \inf \left\{ \mu > 0 : \sum_{k=1}^{T+2} \left( \frac{\Delta^2 u(k-2)}{\mu} \right)^{p(k-2)} + q(k) \frac{|u(k)|}{\mu} \leq 1 \right\}.$$  \hspace{1cm} (3)

Note that there exists constant $L > 0$ such that

$$\|u\| \leq L \|u\|_{\rho(\cdot)}.$$
Now we provide some inequalities used throughout the paper. Put

\[ K = \left( 2 \max\{\bar{w}, \bar{q}\} \right)^{\frac{p^- - p^+}{p^+ - p^-}}. \]

**Lemma 1** For every \( u \in W \) we have what follows

(I1) \[
\sum_{k=1}^{T+2} |\Delta^2 u(k-2)|^p \leq 3^{p-1}(2^p + 2) \sum_{k=1}^{T+2} |u(k)|^p \text{ for any } p > 1. 
\]

(I2) \[
\|u\| \leq (T + 2)^{\frac{1}{p^-} - \frac{1}{p^+}} \left( w^+ 3^{p-1}(2^p + 2) + q^+ \right)^{\frac{1}{p^+}} \left( \sum_{k=1}^{T+2} |u(k)|^{p^+} \right)^{\frac{1}{p^+}}.
\]

(I3) \[
\|u\|_+ \leq 2^{\frac{p^+ - p^-}{p^+ - p^-}} K \|u\|,
\]

(I4) \[
\|u\|_{\max} \leq \frac{1}{4} w^+ 3^{p-1}(2^p + 2) \left( \sum_{i=1}^{T+2} |u(i)|^{p^-} \right). 
\]

**Proof** Relation (I1) is obtained by similar argument as in [11]. Using the inequality \((|a_1| + |a_2| + |a_3|)^p \leq 3^{p-1}(|a_1|^p + |a_2|^p + |a_3|^p)\) for any \( p > 1 \) we have

\[
\sum_{i=1}^{T+2} |\Delta^2 u(i-2)|^p = \sum_{i=1}^{T+2} |u(i) - 2u(i-1) + u(i-2)|^p 
\leq 3^{p-1}(2^p + 2) \sum_{i=1}^{T+2} |u(i)|^p. 
\]

By (I1) we get (I2) as follows

\[
\|u\|^{p^-} \leq w^+ \sum_{i=1}^{T+2} \left( |\Delta^2 u(i-2)|^{p^-} + q^+ |u(i)|^{p^-} \right) 
\leq \left( w^+ 3^{p-1}(2^p + 2) + q^+ \right) \sum_{i=1}^{T+2} |u(i)|^{p^-}.
\]

By the Hölder inequality we get

\[
\sum_{i=1}^{T+2} |u(i)|^{p^-} \leq (T + 2)^{1 - \frac{p^-}{p^+}} \left( \sum_{i=1}^{T+2} |u(i)|^{p^+} \right)^{\frac{p^-}{p^+}}.
\]

Hence by (4) and (5) now we have (I2).
Relation (I3) is obtained by similar arguments as in [16]. By the weighted Hölder inequality and the Minkowski inequality we see that
\[
\|u\|^p_+ \leq (\max\{\bar{w}, \bar{q}\})^{\frac{p^- - p^+}{p^-}} \times \left(\left(\sum_{k=1}^{T+2} w(k-2)|\Delta^2 u(k-2)|^{p^-}\right)^{\frac{p^+}{p^-}} + \left(\sum_{k=1}^{T+2} q(k)|u(k)|^{p^-}\right)^{\frac{p^+}{p^-}}\right) \leq 2^{\frac{p^+-p^-}{p^-}} K^p \|u\|^p_+.
\]

To see (I4) note that for any \(u \in W\) and for any \(k \in [1, T + 2]\) we have
\[
|u(k)| = \left|\sum_{i=1}^{k} \Delta u(i-1)\right| \leq \sum_{i=1}^{k} |\Delta u(i-1)|
\]
and
\[
|u(k)| = \left|\sum_{i=k+1}^{T+2} \Delta u(i-1)\right| \leq \sum_{i=k+1}^{T+2} |\Delta u(i-1)|.
\]
Combining the above inequalities by adding the left-hand sides and right-hand sides we obtain
\[
2 |u(k)| \leq \sum_{i=1}^{T+2} |\Delta u(i-1)|.
\]
Since \(u(-1) = 0\), for any \(k \in [-1, T + 2]\), we get
\[
|u(k)| \leq \frac{1}{2} \sum_{i=1}^{T+2} |\Delta u(i-1)|. \tag{6}
\]
Arguing as above, for any \(k \in [1, T + 2]\), we obtain
\[
|\Delta u(k-1)| \leq \frac{1}{2} \sum_{i=1}^{T+2} |\Delta^2 u(i-2)|. \tag{7}
\]
Function \(w\) has only positive value, so for any \(u \in W\) by (6) and (7), respectively, we get
\[
|u(k)| \leq \frac{1}{2} \sum_{i=1}^{T+2} w(i-2)|\Delta u(i-1)| \quad \text{for any } k \in [-1, T + 2]
\]
and
\[
|\Delta u(k-1)| \leq \frac{1}{2} \sum_{i=1}^{T+2} w(i-2)|\Delta^2 u(i-2)| \quad \text{for any } k \in [1, T + 2].
Hence for any $k \in [-1, T + 2]$ the Hölder inequality implies
\[
|u(k)| \leq \frac{1}{2} \max_{k \in [1, T + 2]} |\Delta u(k - 1)| \sum_{i=1}^{T+2} w(i - 2)
\leq \frac{1}{4} w \sum_{i=1}^{T+2} w(i - 2)|\Delta^2 u(i - 2)|
\leq \frac{1}{4} w \frac{2p^{-1}}{p - 1} \left( \sum_{i=1}^{T+2} w(i - 2)|\Delta^2 u(i - 2)|^p + q(i)|u(i)|^p \right)^{\frac{1}{p}}
= \frac{1}{4} w \frac{2p^{-1}}{p - 1} \|u\|.
\]

The proof of Lemma 1 is complete. \hfill \Box

Let $\psi : W \to \mathbb{R}$ be given by the formula
\[
\psi(u) := \sum_{k=1}^{T+2} \left( w(k - 2)|\Delta^2 u(k - 2)|^{p(k-2)} + q(k)|u(k)|^{p(k)} \right).
\]

For any $u \in W$ the following properties hold (see [5]):
\[
\|u\|_{p(\cdot)} > 1 \Rightarrow \|u\|_{p(\cdot)}^{p^-} \leq \psi(u) \leq \|u\|_{p(\cdot)}^{p^+},
\] (8)

**Lemma 2** For all $u \in W$ we have
\[
\psi(u) \leq 2^{\frac{p^+ - p^-}{p - 1}} K_p^+ \|u\|^{p^+} + (w^+ + q^+)(T + 2).
\] (9)

**Proof** Let $u \in W$. By a similar argument as in [16], we have
\[
\sum_{k=1}^{T+2} w(k - 2)|\Delta^2 u(k - 2)|^{p(k-2)}
\leq \left( \sum_{\{k \in [1, T + 2]: |\Delta^2 u(k - 2)| < 1\}} + \sum_{\{k \in [1, T + 2]: |\Delta^2 u(k - 2)| \geq 1\}} \right) w(k - 2)|\Delta^2 u(k - 2)|^{p^-}
+ w(k - 2)|\Delta^2 u(k - 2)|^{p^+}
= \sum_{k=1}^{T+2} w(k - 2)|\Delta^2 u(k - 2)|^{p^+}
+ \sum_{\{k \in [1, T + 2]: |\Delta^2 u(k - 2)| < 1\}} \left( w(k - 2) \left( |\Delta^2 u(k - 2)|^{p^-} - |\Delta^2 u(k - 2)|^{p^+} \right) \right)
\leq \sum_{k=1}^{T+2} w(k - 2)|\Delta^2 u(k - 2)|^{p^+} + w^+(T + 2).
\]

In the same manner we get
\[
\sum_{k=1}^{T+2} q(k)|u(k)|^{p(k)} \leq \sum_{k=1}^{T+2} q(k)|u(k)|^{p^+} + q^+(T + 2).
\]
Combining the above inequalities in view of (I4) we obtain inequality (9).

\[ \square \]

4 Variational framework

In this section we connect solutions to (1) with critical points of a suitably chosen action functional. Let

\[ F(k, t) := \int_0^t f(k, \xi) d\xi \] for every \((k, t) \in [1, T] \times \mathbb{R}.\]

Let \(\lambda > 0\) be fixed. We consider a functional \(I_\lambda : W \to \mathbb{R}\) defined by

\[ I_\lambda(u) := \sum_{k=1}^{T+2} \left( \frac{w(k-2)}{p(k-2)} |\Delta^2 u(k-2)|^{p(k-2)} + \frac{q(k)}{p(k)} |u(k)|^{p(k)} \right) - \lambda \sum_{k=1}^{T+2} F(k, u). \]

Put

\[ \Phi(u) := \sum_{k=1}^{T+2} \left( \frac{w(k-2)}{p(k-2)} |\Delta^2 u(k-2)|^{p(k-2)} + \frac{q(k)}{p(k)} |u(k)|^{p(k)} \right), \]

(10)

\[ H(u) := \sum_{k=1}^{T+2} F(k, u(k)). \]

(11)

Then \(I_\lambda = \Phi - \lambda H.\)

Applying twice, for the functional \(\Phi\), the summation by parts formula and use the conditions \(\Delta v(-1) = v(0) = \Delta v(T+1) = v(T+2) = 0\) we can see that

\[ \Phi'(u)(v) = \sum_{k=1}^{T+2} \left( \Delta^2 \left( w(k-2) \phi_{p(k-2)}(\Delta^2 u(k-2)) \right) v(k) + q(k) \phi_{p(k)}(u(k)) v(k) \right) \]

for all \(u, v \in W\). Therefore \(\Phi\) is of class \(C^1\) on \(W\).

The derivative of \(H\) reads

\[ H'(u)(v) = \sum_{k=1}^{T+2} f(k, u(k)) v(k) \]

for all \(u, v \in W\). Therefore \(H\) is of class \(C^1\) on \(W\). Hence \(I_\lambda\) is of class \(C^1\) on \(W\).

Lemma 3 The functional \(\Phi\) is coercive.

Proof To prove the coercivity of \(\Phi\) note that for \(\|u\|\) large as well , \(\|u\|_{p(\cdot)}\) is large enough, so by (8) and (3) we get

\[ \Phi(u) \geq \frac{\psi(u)}{p^+} \geq \frac{\|u\|_{p(\cdot)}^{p^-}}{p^+} \geq \frac{\|u\|^{p^-}}{p^+ L^{p^-}}. \]

Hence, as \(\|u\| \to +\infty\), we can conclude that \(\Phi(u) \to +\infty.\)

\[ \square \]

Lemma 4 The function \(u \in W\) is a critical point of \(I_\lambda\) in \(W\) iff \(u\) is a solution of problem (1).
Proof First, let $\overline{u}$ be a critical point of $I_\lambda$ in $W$. Then for all $v \in W$, $I'_\lambda(\overline{u})(v) = 0$ and
\[
\Delta u(-1) = \Delta u(T + 1) = \overline{u}(-1) = \overline{u}(T + 2) = 0.
\]
Thus, for every $v \in W$, taking twice summation by parts and taking $\Delta v(-1) = \Delta v(T + 1) = v(-1) = v(T + 2) = 0$ into account we have
\[
0 = I'_\lambda(\overline{u})(v)
= \sum_{k=1}^{T+2} \left( \Delta^2 \left( w(k-2)\phi_{p(k-1)}(\Delta^2 \overline{u}(k-2)) \right) v(k) + q(k)\phi_{p(k)}(\overline{u}(k)) v(k) \right)
- \lambda \sum_{k=1}^{T+2} f(k, \overline{u}(k)) v(k).
\]
Since $v \in W$ is arbitrary we get
\[
-\Delta^2 \left( w(k-2)\Delta^2 \overline{u}(k-2) \right)|_{p(k-2)-2} \Delta^2 \overline{u}(k-2) + q(k)|\overline{u}(k)|_{p(k)-2} \overline{u}(k)
= \lambda f(k, \overline{u}(k)),
\]
for every $k \in [1, T]$. Therefore, $\overline{u}$ is a solution of (1). We conclude that every critical point of $I_\lambda$ in $W$ is a solution of problem (1).

We will employ the following assumptions.

(H1) $B^\infty := \min_{x \in [1, T]} \limsup_{x \to +\infty} \frac{F(k, x)}{|x|^p} > 0$ and $x \to F(k, x)$ is convex on $\mathbb{R}$ for all $k \in [1, T].$

Let
\[
\lambda^* := \frac{2 \frac{p^+ - p^-}{p} K^p}{p^\infty (3p^\infty - 1) w^+(2p^\infty + 2) + q^+} \left( 1 - \frac{p^+}{p^-} \right) (T + 2) \frac{1}{p^-}.
\]

Lemma 5 Assume that (H1) is satisfied. Then for any $\lambda > \lambda^*$ the functional $I_\lambda$ is anti-coercive, i.e. $I_\lambda(u) \to -\infty$ as $\|u\| \to +\infty$.

Proof Let us fix $\lambda > \lambda^*$. Taking $\limsup_{x \to +\infty} \frac{F(k, x)}{|x|^p} \geq B^\infty$ we will find $\delta > 0$ with $F(k, x) \geq B^\infty |x|^p$ for any $k \in [1, T]$ and for any $x \in \mathbb{R}$ with $|x| > \delta$.

For $\|u\|$ sufficiently large, by (13) we get
\[
-\lambda \sum_{k=1}^{T+2} F(k, u(k)) \leq -\lambda B^\infty \sum_{k=1}^{T+2} |u(k)|^p
\leq -\lambda B^\infty (3p^\infty - 1) w^+(2p^\infty + 2) + q^+ \left( 1 - \frac{p^+}{p^-} \right) (T + 2) \frac{1}{p^-} \|u\|^p + (w^+ + q^+)(T + 1) \tag{12}
\]
and by (9) we have
\[
\Phi(u) \leq \frac{\psi(u)}{p^-} \leq \frac{1}{p^-} \left( 2 \frac{p^+ - p^-}{p} K^p \|u\|^p + (w^+ + q^+)(T + 1) \right). \tag{13}
\]
Hence, by (12) and (13) we obtain

$$I_\lambda(u) = \Phi(u) - \lambda \sum_{k=1}^{T+1} F(k, u(k)) \leq \frac{1}{p^-} \left( 2 \frac{p^+ - p^-}{p^-} K^{p^+} \|u\|^{p^+} + (w^+ + q^+)(T + 1) \right)$$

$$- \lambda B^\infty (3^{p^- - 1} w^+(2^{p^-} + 2) + q^+) \frac{p^+}{p^-} (T + 2) \frac{1 - p^+}{p^-} \|u\|^p^+$$

$$= \frac{1}{p^-}(w^+ + q^+)(T + 1)$$

$$+ \left( \frac{1}{p^-} 2 \frac{p^+ - p^-}{p^-} K^{p^+} \lambda B^\infty (3^{p^- - 1} w^+(2^{p^-} + 2) + q^+) \frac{p^+}{p^-} (T + 2) \frac{1 - p^+}{p^-} \right) \|u\|^p^+$$

$$= \frac{1}{p^-}(w^+ + q^+)(T + 1)$$

$$+ B^\infty (3^{p^- - 1} w^+(2^{p^-} + 2) + q^+) \frac{p^+}{p^-} (T + 2) \frac{1 - p^+}{p^-} (\lambda^* - \lambda) \|u\|^p^+.$$ 

So taking $B^\infty > 0$, one can conclude that $I_\lambda(u) \to -\infty$ as $\|u\| \to +\infty$. □

5 Main results

We state our main result as follows.

**Theorem 3** Suppose that assumption (H1) is satisfied. Then, for any $\lambda \in \Lambda_1 := ]\lambda^*, +\infty[$ problem (1) has at least one nontrivial solution.

**Proof** Take $E = W$ and $\Phi, H$ as in (10) and (11). Note that these are convex $C^1$ functionals.

By Lemma 5 functional $I_\lambda$ for any $\lambda \in \Lambda_1$ is anticoercive and since it is $C^1$ functional in a finite dimensional $W$, so it has obviously at least one maximizer which is a critical point of $I_\lambda$. Thus by Lemma 4 the problem (1) has at least one nontrivial solution. □

Let

(H2) $B_0 := \max_{k \in [1, T+2]} \liminf_{x \to 0} \frac{F(k, x)}{|x|^{p^- + 1}} < \infty$.

Put

$$\lambda^{**} = \frac{4 L^{-p^- - 2}}{(p^- + 1) B_0 w^{2p^- - 1}}$$

**Theorem 4** Suppose that the assumption (H2) is satisfied. Then for any $\lambda \in ]0, \lambda^{**}[$ problem (1) has at least one nontrivial solution.

**Proof** From (H2), one can conclude that

$$f(k, x) \leq (p^- + 1) B_0 |x|^{p^-} \quad \text{for all } |x| \leq L \text{ and all } k \in [1, T+2],$$

where $L > 0$ satisfies (3). Let us define a set $D \subseteq E$ by

$$D = \{x \in E : \|x\|_{p(\cdot)} \leq L\}.$$
Fix $\lambda \in [0, \lambda^*]$. We shall apply Theorem 1. The functional $I_\lambda$ is continuous and the subset $D$ is closed and bounded, therefore there exists a minimum of $I_\lambda$ over $D$, which we denote by $x_0$, so

$$\|x_0\|_{p(\cdot)} < L.$$  \hfill (15)

Consider on the space $E$ the following Dirichlet problem

$$\begin{cases}
-\Delta^2 (w(k - 2)\phi_{p(k-2)}(\Delta^2 x(k - 2)) + q(k)|x(k)|^{p(k) - 2}x(k) = \lambda f(k, x_0(k)), & k \in [1, T], \\
x(-1) = x(T + 2) = \Delta x(-1) = \Delta x(T + 1) = 0.
\end{cases}$$  \hfill (16)

The energy functional $J : E \to \mathbb{R}$ corresponding to (16) is on the form

$$J(x) = \Phi(x) - \lambda H(x_0).$$

From Lemma 3 the functional $J$ is coercive. It is also $C^1$ and strictly convex, so problem (16) is uniquely solvable by some $v \in E$. We shall prove that $v \in D$. If $\|v\| < 1$ the conclusion is immediate. Suppose $\|v\| \geq 1$. Multiplying

$$-\Delta^2 (w(k - 2)\phi_{p(k-2)}(\Delta^2 v(k - 2)) + q(k)|v(k)|^{p(k) - 2}v(k) = \lambda f(k, x_0(k))$$

by $v$ and summing from 1 to $T + 2$ we have what follows

$$\sum_{k=1}^{T+2} \left( \Delta^2 (w(k - 2)\phi_{p(k-2)}(\Delta^2 v(k - 2))) v(k) + q(k)\phi_{p(k)}(v(k))v(k) \right) = \lambda \sum_{k=1}^{T+2} f(k, x_0(k))v(k).$$

Taking twice summation by parts and taking $\Delta v(-1) = \Delta v(T + 1) = v(-1) = v(T + 2) = 0$ into account, one has

$$\psi(v) = \lambda \sum_{k=1}^{T+2} f(k, x_0(k))v(k).$$

By (8) we see

$$\|v\|_{p(\cdot)}^{p^-} \leq \psi(v).$$

On the other hand from (14), (3), (15), (14), (3), respectively, we obtain

$$\begin{align*}
\lambda \sum_{k=1}^{T+2} f(k, x_0(k))v(k) &\leq \lambda \sum_{k=1}^{T+2} (p^- + 1)B_0|x_0(k)|^{p^-}v(k) \\
&\leq (p^- + 1)\lambda B_0\|v(k)\|_{p(\cdot)}^{p^-} \sum_{k=1}^{T+2} |x_0|^p \leq (p^- + 1)\lambda B_0\|v(k)\|_{p(\cdot)}^{p^-} \|x_0\|^{p^-} \\
&\leq (p^- + 1)\lambda B_0 L^{p^-} \|x_0\|_{p(\cdot)}^{p^-} \|v\|_{p(\cdot)}^{p^-} \leq (p^- + 1)\lambda B_0 L^{2p^-} \|v\|_{p(\cdot)}^{p^-} \\
&\leq (p^- + 1)\lambda B_0 L^{2p^-} \frac{1}{4} \frac{2p^- - 1}{w} \|v\| \leq \frac{1}{4} (p^- + 1)\lambda B_0 L^{2p^-} \frac{2p^- - 1}{w} L\|v\|_{p(\cdot)}^{p^-} \\
&= \frac{1}{4} (p^- + 1)\lambda B_0 L^{2p^- + 1} \frac{2p^- - 1}{w} \|v\|_{p(\cdot)}^{p^-}. 
\end{align*}$$
So
\[ \|v\|_{p,\lambda}^{p-1} \leq \frac{1}{4} (p^+ + 1) \lambda B_0 L^{2p^+ + 1} \frac{2p^- - 1}{p} \|v\|_{\lambda} \]
and then
\[ \|v\|_{p,\lambda}^{p-1} \leq \frac{1}{4} (p^+ + 1) \lambda B_0 L^{2p^+ + 1} \frac{2p^- - 1}{p} \cdot \]
Hence for any \( \lambda < \lambda^{**} \) we obtain
\[ \|v\|_{p,\lambda}^{p-1} \leq \frac{1}{4} (p^+ + 1) \lambda B_0 L^{2p^+ + 1} \frac{2p^- - 1}{p} < L^{p^- - 1}. \]
Therefore, \( v \in D \). Applying Theorem 1 we see that problem \( (1) \) has at least one nontrivial solution. \( \square \)

**Theorem 5** Suppose that the assumptions \((H1)-(H2)\) are satisfied. Let \( \lambda^* < \lambda^{**} \). Then for any \( \lambda \in \left[ \lambda^*, \lambda^{**} \right] \) problem \( (1) \) has at least two nontrivial solutions.

**Proof** To prove our result it is enough to apply Theorem 3 and Theorem 4. By Theorem 3, \( u \) is a critical point to \( J \), and thus it solves \( (1) \). Also \( J \) is anti-coercive, then \( (1) \) has another solution different from \( u \). \( \square \)

**Corollary 1** By Theorem 5, if the conditions \( B_\infty = +\infty \) and \( B_0 = 0 \) hold. Then for any \( \lambda > 0 \) problem \( (1) \) has at least two nontrivial solutions.

Finally, we present a special case of our main result with an example.

**Theorem 6** Let \( f \) be a continuous function on \( \mathbb{R} \) and let \( F(x) = \int_0^x f(\xi) d\xi \) be a convex function on \( \mathbb{R} \) satisfying following conditions
\[ \limsup_{x \to +\infty} \frac{F(x)}{|x|^{p^+}} = +\infty, \quad \liminf_{x \to 0} \frac{F(x)}{|x|^{p^+ + 1}} = 0. \] (17)
Then, for each \( \lambda > 0 \) the problem
\[ \begin{cases} -\Delta^2 (|\Delta^2 u(k - 2)|^{p(k - 2)} - 2 \Delta^2 u(k - 2)) + |u(k)|^{p(k - 2)} u(k) \\ = \lambda f(u(k)), k \in [1, T] \\
\} \]
\[ u(-1) = u(T + 2) = \Delta u(-1) = \Delta u(T + 1) = 0, \] (18)
admits at least two solutions.

**Example 1** Let \( T = 4, p(k) = \frac{6k^2 - 34k + 54}{k^2 - 6k + 10} \), hence \( p^+ = p(4) = 7, p^- = p(2) = 5 \). Let \( f(t) = \sum_{n=4}^{\infty} a_n t^{2n+1}, a_n \in \mathbb{R}^+, \) and \( F(t) = \sum_{n=4}^{\infty} a_n \frac{t^{2n+2}}{2n+2} \). Conditions (17) are fulfilled, so by Theorem 6, for each \( \lambda > 0 \) problem (18) admits at least two solutions.

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