An Optimal Skorokhod Embedding for Diffusions

A.M.G. Cox∗and D.G. Hobson†
Department of Mathematics,
University of Bath,
Bath BA2 7AY, UK

March 29, 2022

Abstract

Given a Brownian motion \((B_t)_{t \geq 0}\) and a general target law \(\mu\) (not necessarily centred or even in \(L^1\)) we show how to construct an embedding of \(\mu\) in \(B\). This embedding is an extension of an embedding due to Perkins, and is optimal in the sense that it simultaneously minimises the distribution of the maximum and maximises the distribution of the minimum among all embeddings of \(\mu\). The embedding is then applied to regular diffusions, and used to characterise the target laws for which a \(H^p\)-embedding may be found.

1 Introduction

Let \((X_t)_{t \geq 0}\) be an adapted stochastic process with state space \(I\), and let \(\mu\) be a probability measure on \(I\). Given \(X\) and \(\mu\), the Skorokhod embedding problem is to find a stopping time with the property that \(X_T \sim \mu\). For a general stochastic process \(X\), and an arbitrary measure \(\mu\), necessary and sufficient conditions for the existence of a solution to Skorokhod problem were given by \([10]\). Hence attention switches to the construction of solutions.

When \((X_t)_{t \geq 0}\) is a one-dimensional Brownian motion started at 0 and \(\mu\) is a zero-mean target distribution, many explicit constructions of stopping rules which embed \(\mu\) are known, see for example \([12, 3, 9, 2]\). For Brownian motion it is interesting to seek embeddings with additional optimality properties, such as the embedding which minimises the variance of the stopping time \([11]\), the embedding which stochastically minimises the law of the local time at zero \([15]\), or the embedding which maximises the law of the supremum of the stopped process \([1]\).

The first purpose of this article is to consider the embedding in Brownian motion of a target distribution which is not centred and may not even be
integrable. Note that if the target distribution has finite mean $m$ then one way to embed the law is to wait until the Brownian motion first hits the level $m$ and then adapt a favourite embedding for a centered target distribution for the shifted process now starting at $m$. However this cannot work if $m$ is not well-defined and finite and even if $m$ exists this construction may not share the optimality properties of the original embedding.

Instead, to embed a general law we adapt an embedding which was proposed in [7]. For zero mean target laws the Perkins embedding has the property that it simultaneously maximises the distribution of the minimum, and minimises the distribution of the maximum, amongst the class of all the stopping times which embed $\mu$. Our adaptation of the Perkins embedding extends to all target distributions and retains the optimality properties of the Perkins embedding.

The second purpose of this article is to consider the embedding of $\mu$ in a one-dimensional diffusion. The main technique is to use a change of scale to reduce the problem to the Brownian case, and under this transformation it is completely natural for the target measure to have non-zero mean in the Brownian scale. We will see that our embedding is a natural one to use in this situation, and we are able to identify the cases where it is possible to embed a given target distribution, thus rederiving a result in [6]. We also identify some properties of the maximum and minimum of the processes in these cases. Our results in this direction can be seen as an extension of the results in [4] (for drifting Brownian motion) and [6]. However in this last paper the authors use an extension of the Azema-Yor embedding which may not be defined in certain cases of interest. Thus our construction of a Skorokhod embedding is both different to, and more general than, the embedding in [6].

The remainder of the article is structured as follows. In the next section we consider the problem of embedding a general target probability in Brownian motion. We construct an embedding which is defined for all circumstances in which it is possible to find an embedding and with the property that the law of the maximum is stochastically as small as possible. In Section 3 we show this embedding can be applied to construct embeddings in regular diffusions and in the final section we answer the question of when it is possible to construct a $H^p$-embedding, i.e. given a diffusion process $Y$ and a target law $\nu$ when does there exists a stopping time $T$ such that $Y_T \sim \nu$ and $\mathbb{E}[(\sup_t |Y_{t\wedge T}|)^p] < \infty$.

## 2 An embedding of a general target measure in Brownian motion

Consider first the problem of embedding a target distribution $\mu$ in a one-dimensional local martingale $(M_t)_{t\geq 0}$, $M_0 = 0$ a.s.. We make no assumptions
on \( \mu \) other that that \( \mu(\mathbb{R}) = 1 \), and that \( \mu \) has no atom at 0. In fact this second assumption can be avoided by stopping immediately according to some independent randomisation with suitable probability, and then using the construction to embed the remaining mass of \( \mu \), conditional on not stopping at 0. Clearly such a construction is necessary in any stopping time that will minimise the maximum, and maximise the minimum.

For a general local martingale the above conditions are not sufficient to ensure that an embedding exists. However a sufficient condition for the existence of an embedding for any \( \mu \) is that our local martingale almost surely has infinite quadratic variation. Since any local martingale is simply a time change of Brownian motion, this just ensures that our time change does not stall.

We begin by defining a series of functions. Let

\[
  c(x) = \begin{cases} 
  \int_{\{u \geq 0\}} (x \wedge u) \mu(du) & : \ x \geq 0; \\
  \int_{\{u < 0\}} (|x| \wedge |u|) \mu(du) & : \ x < 0. 
  \end{cases} 
\]

Then \( c(x) \) is increasing and concave on \( \{x \geq 0\} \), decreasing and concave on \( \{x \leq 0\} \) and continuous on \( \mathbb{R} \) (see Figures 1 and 2). It is also differentiable Lebesgue-almost-everywhere and:

\[
  c'(x) = \begin{cases} 
  \mu((x, \infty)) & : \ x \geq 0; \\
  -\mu((-\infty, x]) & : \ x < 0; 
  \end{cases} 
\]

\[ (2) \]

\[
  c'(x) = \begin{cases} 
  \mu([x, \infty)) & : \ x > 0; \\
  -\mu(-\infty, x)) & : \ x \leq 0, 
  \end{cases} 
\]

\[ (3) \]

where \( c'(x) \), \( c'(x) \) are the left and right derivatives respectively. In particular, the points at which \( c(x) \) is not differentiable are precisely the atoms of our target distribution. We also note that \( c(\infty) < \infty \) if and only if our target distribution satisfies \( \int_{\{x \geq 0\}} x \mu(dx) < \infty \), and \( c(-\infty) = \int_{u < 0} |u| \mu(du) \). Finally, we have \( c(\infty) = c(-\infty) < \infty \) if and only if \( \mu \in L^1 \) and \( \mu \) is centred.

For \( \lambda > 0 \), define the following quantities:

\[
  \gamma_+(\lambda) = \arg\min_{x > 0} \left\{ \frac{c(\lambda) - c(-x)}{\lambda - (-x)} \right\}, 
\]

\[ (4) \]

\[
  \gamma_-(\lambda) = \arg\max_{x > 0} \left\{ \frac{c(x) - c(-\lambda)}{x - (-\lambda)} \right\}, 
\]

\[ (5) \]

\[
  \theta_+(\lambda) = -\inf_{x > 0} \left\{ \frac{c(\lambda) - c(-x)}{\lambda - (-x)} \right\}, 
\]

\[ (6) \]

\[
  \theta_-(\lambda) = \sup_{x > 0} \left\{ \frac{c(x) - c(-\lambda)}{x - (-\lambda)} \right\}, 
\]

\[ (7) \]
If the minimising (respectively maximising) $x$ in (4) (resp. (5)) is not unique then we take the smallest such $x$. If there is no minimising $x$, then the function we are minimising is decreasing (resp. increasing) as $x \to \infty$, and we define $\gamma_{+}(\lambda) = \infty$ (resp. $\gamma_{-}(\lambda) = \infty$). In this case we also define $\theta_{+}(\lambda) = 0$ (resp. $\theta_{-}(\lambda) = 0$).

Remark 1. Although we have given formal definitions these quantities are best described pictorially. Given $\lambda > 0$, we consider points $(y, c(y))$ for $y < 0$ and more specifically the line segment joining $(y, c(y))$ with $(\lambda, c(\lambda))$. As $y$ ranges over the negative reals we let $\theta_{+}(\lambda)$ be the largest possible slope of this line segment, and we let $\gamma_{+}(\lambda)$ be the absolute value of the $x$-coordinate of the point where this maximum is attained. See Figures 1 and 2.

The quantities $\theta_{-}(\lambda)$ and $\gamma_{-}(\lambda)$ are obtained by reflecting the picture. Alternatively, if we define the measure $\tilde{\mu}((\infty, x)) = \mu([-x, \infty))$ then we obtain a correspondence between the pairs of definitions above — that is
Figure 2: $c(x)$ for a non-integrable measure with an atom at $-\gamma_+^+(\lambda_1)$. As $x \to \infty$, $c(x) \to \int_{\{x \geq 0\}} x \mu(dx) = \infty$, while as $x \to -\infty$, $c(x)$ is asymptotic to the level $\beta = -\int_{\{x \leq 0\}} x \mu(dx)$, which for this example is taken to be finite. The point $\alpha$ is such that $c(\alpha) = \beta$, and for all $\lambda > \alpha$, $\gamma_+^+(\lambda) = \infty$.

$$
\gamma_\pm^\mu(\lambda) = \gamma_\pm^\mu(\lambda), \quad \theta_\pm^\mu(\lambda) = \theta_\pm^\mu(\lambda) \quad \text{and} \quad \mu_\pm(\lambda) = \tilde{\mu}_\pm(\lambda), \quad \text{with the obvious extension of the notation.}
$$

**Remark 2.** It is only possible for us to have $\gamma_+^+(\lambda) = \infty$ if $\int_{\{x \geq 0\}} x \mu(dx) > \int_{\{x \leq 0\}} |x| \mu(dx)$, see Figure 2. If this is true, then $\gamma_+^+(\lambda) = \infty$ for all $\lambda$ such that $c(\lambda) > \int_{\{x \leq 0\}} |x| \mu(dx)$ (and if the support of $\mu$ is not bounded below, also when equality holds).

We take this opportunity to record some further relationships between the various quantities defined in (4) to (9). It follows from (4) and (5) that for $\lambda > 0$:

$$
-c'(-\gamma_+^+(\lambda))_- \leq \theta_+(\lambda) \leq -c'(-\gamma_+^+(\lambda))_+, \quad (10)
$$
$$
c'(\gamma_-(\lambda))_+ \leq \theta_-(\lambda) \leq c'(\gamma_-(\lambda))_-, \quad (11)
$$

so there is equality in (10) or (11) when there is no atom of $\mu$ at $-\gamma_+^+(\lambda)$ or $\gamma_-(\lambda)$ respectively. From Figure 2 it is clear that if there is an atom of $\mu$ at $-\gamma_+^+(\lambda)$ then $c$ has a kink there, and $-\theta_+(\lambda)$ is then the gradient of the line joining $c(-\gamma_+^+(\lambda))$ and $c(\lambda)$. Further, for $\lambda > 0$ such that $\gamma_+^+(\lambda), \gamma_-(\lambda) < \infty$, 

5
we have
\[
\begin{align*}
c(\lambda) &= c(-\gamma+(\lambda)) - (\lambda + \gamma+(\lambda))\theta+(\lambda), \\
c(-\lambda) &= c(\gamma-(\lambda)) - (\lambda + \gamma-(\lambda))\theta-(\lambda).
\end{align*}
\]
Note that as a simple consequence of these equalities, \(c(\lambda) \leq c(-\gamma+(\lambda))\) and \(c(-\lambda) \leq c(\gamma-(\lambda))\).

**Remark 3.** By considering Figures 1 and 2, we see that alternative definitions for \(\gamma+(\lambda), \gamma-(\lambda), \theta+(\lambda)\) and \(\theta-(\lambda)\) are
\[
\begin{align*}
\gamma+(\lambda) &= -\sup \left\{ x < 0 : \frac{c(\lambda) - c(x)}{\lambda - x} \leq c'(x)_+ \right\}, \\
\gamma-(\lambda) &= \inf \left\{ x > 0 : \frac{c(x) - c(-\lambda)}{x - (-\lambda)} \geq c'(x)_- \right\}, \\
\theta+(\lambda) &= -\frac{c(\lambda) - c(-\gamma+(\lambda))}{\lambda - (-\gamma+(\lambda))}, \\
\theta-(\lambda) &= \frac{c(\gamma-(\lambda)) - c(-\lambda)}{\gamma-(\lambda) - (-\lambda)}.
\end{align*}
\]
As a result it is easy to see that, in the case where \(\mu\) is centred, these quantities are identical to the quantities defined in [7], where the quantity \(q+(\lambda)\) defined in [7] satisfies \(\theta+(\lambda) = q+(\lambda) + \mu((-\infty, -\gamma+(\lambda))).\)

Our first Theorem shows that for any target measure \(\mu\) there is an embedding which simultaneously stochastically maximises the distribution of the minimum, and minimises the distribution of the maximum.

**Theorem 4.** (i) Let \((M_t)_{t \geq 0}\) be a continuous local martingale, which vanishes at zero and has supremum process \(S_t = \sup_{u \leq t} M_u\) and infimum process \(J_t = -\inf_{u \leq t} M_u\), and let \(T\) be a stopping time such that \(M_T \sim \mu\). Then, for all \(\lambda \geq 0\), the following hold:
\[
\begin{align*}
\mathbb{P}(S_T \geq \lambda) &\geq \mu+(\lambda) \\
\mathbb{P}(J_T \geq \lambda) &\geq \mu-(\lambda)
\end{align*}
\]
(ii) For a continuous local martingale, \(M_t\), vanishing at zero and such that \(\langle M \rangle_{\infty} = \infty\) a. s., with supremum process \(S_t = \sup_{u \leq t} M_u\) and infimum process \(J_t = -\inf_{u \leq t} M_u\), define the stopping time
\[
T = \inf\{t > 0 : M_t \notin (-\gamma+(S_t), \gamma-(J_t))\}.
\]
Then the stopped process \(M_T\) has distribution \(\mu\), and equality holds in (18) and (19).
Remark 5. When $\mu$ is centred, the fact that the quantities $\gamma_+$ and $\gamma_-$ agree with those in \cite{7}, and the fact that in this case $T$ as defined in (20) is the Perkins stopping time, means that we know that $T$ embeds $\mu$. Moreover we know that $T$ minimises the law of the maximum, and maximises the law of the minimum. These results follows directly from Theorems 3.7 and 3.8 in \cite{7}. The content of Theorem 3 is that these results can be extended to any choice of $\mu$.

Remark 6. We may think of $\theta_+(\lambda)$ and $\theta_-(\lambda)$ as probabilities, and in particular, for the embedding defined in (20), $\theta_+(\lambda)$ is the probability that our process stops below $-\gamma_+(\lambda)$ but with a maximum above $\lambda$. If $\mu$ has no atom at $-\gamma_+(\lambda)$ then for this construction the maximum will be above $\lambda$ if and only if our final value is above $\lambda$ or below $-\gamma_+(\lambda)$. However if there is an atom at $-\gamma_+(\lambda)$, the process may stop there without previously having reached $\lambda$. This event is represented graphically by the fact that there are multiple tangents to $c$ at $-\gamma_+(\lambda)$. Also, when $\gamma_+(\lambda) = \infty$ for some $\lambda$, if the supremum of our process gets above $\lambda$ before stopping, then our stopping rule becomes simply to wait until we reach some upper level, dependent on the infimum.

An alternative way to visualise the stopping time in (20) is shown in Figure 3. We think of the process $(J_t, S_t)$, and define the stopping time to be the first time it leaves the region defined via $\gamma_+$ and $\gamma_-$ as shown.
The first half of the proof of Theorem 4 is a consequence of the following lemma.

**Lemma 7.** Let \((M_t)_{t \geq 0}\) be a continuous local martingale with respect to a probability measure \(\mathbb{P}\). Suppose that \(M\) vanishes at zero, \(M\) converges a.s., and that \(M_\infty \sim \mu\), for some probability measure \(\mu\) on \(\mathbb{R}\). Then, for \(\lambda > 0\),

\[
\begin{align*}
\mathbb{P}(S_\infty \geq \lambda) &\geq \mu_+(\lambda), \\
\mathbb{P}(J_\infty \geq \lambda) &\geq \mu_-(\lambda),
\end{align*}
\]

where \(S_\infty = \sup_s M_s\), and \(J_\infty = -\inf_s M_s\).

**Proof.** For \(x < 0 < \lambda\), we define \(H_\lambda = \inf\{t > 0 : M_t \geq \lambda\}\) where we take \(\inf\emptyset = \infty\). By examining on a case by case basis, we find that the following inequality holds:

\[
1\{S_\infty \geq \lambda\} \geq 1\{M_\infty \geq \lambda\} + \frac{1}{\lambda - x} \{M_{H_\lambda} - (\lambda \wedge M_\infty) 1\{M_\infty \geq 0\} + (|M_\infty| \wedge x) 1\{M_\infty < 0\}\}.
\]

After taking expectations, this implies that

\[
\mathbb{P}(S_\infty \geq \lambda) \geq c'(\lambda)_- + \frac{1}{\lambda - x} \mathbb{E}M_{H_\lambda} - \frac{c(\lambda) - c(x)}{\lambda - x}.
\]

Now \(M_{H_\lambda}\) is a local martingale bounded above, and hence a submartingale, so \(\mathbb{E}M_{H_\lambda} \geq M_0 = 0\). Substituting this in the above equation, we get:

\[
\mathbb{P}(S_\infty \geq \lambda) \geq c'(\lambda)_- - \frac{c(\lambda) - c(x)}{\lambda - x},
\]

and since \(x\) is arbitrary,

\[
\mathbb{P}(S_\infty \geq \lambda) \geq c'(\lambda)_- + \sup_{x < 0} \left\{ \frac{c(x) - c(\lambda)}{\lambda - x} \right\}
\]

\[
\geq \mu([\lambda, \infty)) + \theta_+(\lambda) = \mu_+(\lambda),
\]

which is (21).

We may deduce (22) using the correspondence \(\mu \mapsto \tilde{\mu}\). \(\square\)

**Remark 8.** In particular, for equality to hold for fixed \(\lambda\) in the above, we must have

(i) if \(S_\infty \geq \lambda\), either \(M_\infty \geq \lambda\) or \(M_\infty \leq -\gamma_+(\lambda)\) a.s.,

(ii) if \(S_\infty < \lambda\), \(M_\infty \geq -\gamma_+(\lambda)\) a.s.,

(iii) \(\mathbb{E}M_{H_\lambda} = 0\), so that \(M_{H_\lambda}\) is a true martingale.

It can be seen that these will hold simultaneously for all \(\lambda\) in the case where the stopping time is that given in Theorem 4 and that this is almost surely the only stopping time where (21) and (22) hold.
Proof of Theorem \[4\]. We apply Lemma \[7\] to the process \((M_{T∧t})_{t≥0}\), which allows us to deduce \((18)\) and \((19)\).

For the second part of the theorem recall that if \(\mu\) is centred then the Theorem follows from Theorems 3.7 and 3.8 in \[7\]. In the case when \(\mu\) is not centred define

\[ \xi_+^n = \inf\{x : \mu([x, \infty)) ≤ \frac{1}{2n}\}, \]
\[ \xi_-^n = \sup\{x : \mu((-\infty, x]) ≤ \frac{1}{2n}\}, \]

and, for \(n\) sufficiently large, consider a sequence of measures \(\mu^n\) satisfying:

(i) \(\mu^n((\alpha, \beta)) = \mu((\alpha, \beta)), \quad \xi_-^n < \alpha ≤ \beta < \xi_+^n;\)

(ii) \(\mu^n([\xi_-^n, \xi_+^n]) = \mu^n([(-n) \wedge \xi_-^n, n \vee \xi_+^n]) = \frac{n-1}{n};\)

(iii) \(\mu^n(\{\xi_-^n\}) ≤ \mu(\{\xi_+^n\});\)

(iv) \(\int x \, \mu^n(dx) = 0;\)

(v) \(\int |x| \, \mu^n(dx) < \infty.\)

We can construct such a sequence by redistributing the mass that lies in the tails of \(\mu\) as follows: each \(\mu^n\) agrees with \(\mu\) on the interval \((\xi_-^n, \xi_+^n),\) and mass is placed at the endpoints of this interval to satisfy (ii) and (iii) if there are atoms here; the remaining mass is then placed outside the interval \([(-n) \wedge \xi_-^n, n \vee \xi_+^n]\) in such a way as to ensure that (iv) and (v) hold.

For the rest of this section a superscript \(n\) will denote the fact that a quantity is calculated relative to the measure \(\mu^n.\)

Note that if we can construct \(\mu^n\) in such a way that \(\mu^n(\mathbb{R}_-) = \mu(\mathbb{R}_-)\) then we find that \(c^n(x) \equiv c(x)\) on \([\xi_-^n, \xi_+^n]\). However it is not possible to construct \(\mu^n\) with this additional property if \(\mu(\mathbb{R}_-) = 0\) or 1, and in that case we need a more general argument.

Suppose \(\mu^n(\mathbb{R}_-) - \mu(\mathbb{R}_-) = \psi_n\) for some number \(\psi_n \in (-1/2n, 1/2n).\) Then \(c^n(x) = c(x) - \psi_n x\) for \(x \in [\xi_-^n, \xi_+^n].\) If both \(\lambda\) and \(\gamma_+(\lambda)\) lie in this interval then it is clear from \[4\] that \(\gamma_+^n(\lambda) = \gamma_+(\lambda).\) Conversely if \(\gamma_+(\lambda) = \infty,\) then \(\gamma_+^n(\lambda) ≥ n.\) Similar results hold for \(\gamma_-^n.\)

We define the stopping times associated with these measures,

\[ T^n := \inf\{t > 0 : M_t \notin (-\gamma_+^n(S_t), \gamma_-^n(J_t))\}, \]

so that \(M_{T^n} \sim \mu^n.\) Note that if \(M_{T^n} \in [(-n) \wedge \xi_-^n, n \vee \xi_+^n]\), then \(T = T^n\) a.s. (see Figure \[4\]). However this implies that \(\mathbb{P}(T = T^n) → 1,\) since these intervals are increasing to cover the whole of \(\mathbb{R}.\) Together with the fact that \(\mu^n([\lambda, \infty)) → \mu([\lambda, \infty))\), we conclude that \(M_T \sim \mu.\)
\[ \lambda_1 - \gamma + (\lambda_1 - \lambda_2) \gamma - (\lambda_2) c(x) \beta \alpha S_t \]

\[ J_t \gamma - (J_t) \gamma + (S_t) \gamma - \xi - \xi + n \gamma - (J_t) \gamma + \theta \mu_n + (\lambda) \]

Finally, we need to show that our process attains equality in (18) and (19). Fix \( \lambda > 0 \). We know that
\[ \mathbb{P}(S^n_T \geq \lambda) = \mu^n([\lambda, \infty)) + \theta^n \]

and since \( \mathbb{P}(T^n = T) \geq (n - 1)/n \), we have \( \mathbb{P}(S^n_T \geq \lambda) \rightarrow \mathbb{P}(S_T \geq \lambda) \).

Moreover \( \mu^n([\lambda, \infty)) \rightarrow \mu([\lambda, \infty)) \) so that in order to prove
\[ \mathbb{P}(S_T \geq \lambda) = \mu([\lambda, \infty)) + \theta^\mu \]

it is sufficient to show that \( \theta^n \rightarrow \theta^\mu \) as \( n \rightarrow \infty \). Now, when \( x \in [\xi^n_-, \xi^n_+] \), we have \( c^n(x) - c(x) = \psi_n x \) and for \( x \) outside this range \( (c^n)' - c' \leq 1/n \). Hence
\[ |c^n(x) - c(x)| \leq \frac{|x|}{n}, \]

for all \( x \). As a corollary, for \( x < 0 < \lambda \),
\[ \left| \frac{c^n(\lambda) - c^n(x)}{\lambda - x} - \frac{c(\lambda) - c(x)}{\lambda - x} \right| \leq \frac{1}{n}, \]

from which it follows that
\[ |\theta^n(\lambda) - \theta^\mu(\lambda)| \leq \frac{1}{n}. \]
using the representation (16).

As before we can also show (19) holds by using the correspondence \( \mu \mapsto \tilde{\mu} \).

\[ \square \]

3 Applications to diffusions

We now work with the class of regular (time-homogeneous) diffusions (see [8], V. 45) \( (Y_t)_{t \geq 0} \) on an interval \( I \subseteq \mathbb{R} \), with absorbing or inaccessible endpoints, and vanishing at zero. Consider the problem of determining when and how we may embed a distribution \( \nu \) on \( I^c \) in the diffusion. Since the diffusion is regular, there exists a continuous, strictly increasing scale function \( s : I \rightarrow \mathbb{R} \) such that \( M_t = s(Y_t) \) is a diffusion on natural scale on \( s(I) \). We may also choose \( s \) such that \( s(0) = 0 \). In particular, \( M_t \) is (up to exit from the interior of \( s(I) \)) a time change of a Brownian motion, with strictly positive speed measure.

If we now define the measure \( \mu \) on \( s(I) \) by

\[ \mu(A) = \nu(s^{-1}(A)), \quad A \subseteq s(I), \text{ Borel}, \]

then our problem is equivalent to that of embedding \( \mu \) in a Brownian motion before it leaves \( s(I)^c \). This is because \( M \) is a local martingale on \( s(I)^c \), and hence a time change of a Brownian motion on \( s(I) \), and if we construct a stopping time \( T \) such that \( M_T = s(Y_T) \sim \mu \), then \( Y_T \sim \nu \). It this context it makes sense to consider \( \nu \) and \( \mu \) as measures on \( \mathbb{R} \) which place all their mass on \( I^c \) and \( s(I)^c \) respectively. Our approach will be to use the embedding we established in Theorem 4 to embed \( \mu \) in the local martingale \( M \), and our first step will be to transfer the framework of the previous section to our new setting.

An advantage of using the embedding we established in Section 2 in this situation is that, because we have a strictly increasing scale function, the properties of the maximum and the minimum are preserved. In particular, this transformed stopping time will maximise the distribution of the minimum, and minimise the distribution of the maximum of the process \( (Y_{T \wedge t}) \) among all stopping times of \( Y_t \) with \( Y_T \sim \nu \).

It is clear that we may embed our distribution on \( s(I)^c \) if and only if, when we consider the problem of embedding \( \mu \) in Brownian motion, our process remains on \( s(I)^c \). However the transformed target distribution is also distributed only on this interval, so when we consider the form of \( \gamma_+(\lambda) \) and \( \gamma_-(\lambda) \) in the martingale scale, we see that problems can only occur if \( \gamma_+(\lambda) = \infty \) or \( \gamma_-(\lambda) = \infty \) for some \( \lambda \). Further examination shows that this is only possible when \( \mu \) is not integrable, or not centred — see Remark 2.

We can summarise these comments on the existence of a solution in the following lemma.

**Lemma 9.** There are three different cases:
(i) \( s(I^0) = \mathbb{R} \), in which case the diffusion is recurrent, and we can embed any distribution \( \nu \) on \( I^0 \) in \( Y \).

(ii) \( s(I^0) = (-\infty, \alpha) \) (respectively \((\alpha, \infty)\)) for some \( \alpha \in \mathbb{R} \). Then we may embed \( \nu \) in \( Y \) if and only if \( m = \int_I s(y) \nu(dy) \) exists, and \( m \geq 0 \) (resp. \( m \leq 0 \)).

(iii) \( s(I^0) = (\alpha, \beta) \), \( \alpha, \beta \in \mathbb{R} \). Then we may embed \( \nu \) in \( Y \) if and only if \( m = 0 \).

A similar result to Lemma 9 appears in [6], but under the additional assumption that \( \int_I |s(y)| \nu(dy) < \infty \).

Our aim in the remainder of this section is to look at some of the properties of the construction, and of embeddings in general. Our principal question is,

given a diffusion \( Y_t \), and a law \( \nu \), when does there exists an embedding for which the law of the maximum modulus of the process, \( \sup_t |Y_{T \wedge t}| \), lies in the space \( L^p \) of random variables with finite \( p \)th moment?

Before answering this question we show how the results of the previous section can be used to define an embedding of a target law in a diffusion.

Given \( \nu \) and \((Y_t)_{t \geq 0}\) define \( \mu \) and \( M = s(Y) \) as above. As before, for \( M \) on \( s(I) \) we can define

\[
c_M(x) = \begin{cases} 
\int_{\{u \geq 0\}} (x \wedge u) \mu(du) & : x \geq 0; \\
\int_{\{u < 0\}} (|x| \wedge |u|) \mu(du) & : x < 0,
\end{cases}
\]

together with the quantities defined in (4)–(9). Write

\[
c_Y(y) = c_M(s(y)) = \begin{cases} 
\int_{\{w \geq 0\}} (s(y) \wedge s(w)) \nu(dw) & : y \geq 0; \\
\int_{\{w < 0\}} (|s(y)| \wedge |s(w)|) \nu(dw) & : y < 0.
\end{cases}
\]

and, for \( z > 0 \), define the quantities:

\[
\rho_+(z) = \arg\min_{y > 0} \left\{ \frac{c_Y(z) - c_Y(-y)}{s(z) - s(-y)} \right\}, \quad (24)
\]

\[
\rho_-(z) = \arg\max_{y > 0} \left\{ \frac{c_Y(y) - c_Y(-z)}{s(y) - s(-z)} \right\}, \quad (25)
\]

\[
\zeta_+(z) = -\inf_{y > 0} \left\{ \frac{c_Y(z) - c_Y(-y)}{s(z) - s(-y)} \right\}, \quad (26)
\]

\[
\zeta_-(z) = \sup_{y > 0} \left\{ \frac{c_Y(y) - c_Y(-z)}{s(y) - s(-z)} \right\}, \quad (27)
\]

\[
\nu_+(z) = \zeta_+(z) + \nu([z, \infty)), \quad (28)
\]

\[
\nu_-(z) = \nu((-\infty, -z]) + \zeta_-(z). \quad (29)
\]
By convention, if \( \rho_+ (z) \) or \( \rho_- (z) \) is not uniquely defined then we take the smallest solution.

Now define a stopping time for \( Y_t \) by:

\[
T = \inf\{ t > 0 : Y_t \notin (\rho_+ (s_t^Y), \rho_- (s_t^Y)) \} = \inf\{ t > 0 : M_t \notin (\gamma_+ (s_t^M), \gamma_- (s_t^M)) \},
\]

where we write \( s_t^Y = \sup_{s \leq t} Y_s \), \( J_t^Y = -\inf_{s \leq t} Y_s \), \( s_t^M = \sup_{s \leq t} M_s \) and \( J_t^M = -\inf_{s \leq t} M_s \). The two alternative characterisations of \( T \) are equivalent because of the identities

\[
s(\rho_+ (z)) = -\gamma_+ (s(z)),
\]

\[
s(\rho_- (z)) = \gamma_- (-s(z)).
\]

We also have that \( \zeta_+ (z) = \theta_+ (s(z)) \), and \( \zeta_- (z) = \theta_- (-s(z)) \). It follows that \( T \) embeds \( \mu \) in \( (M_t)_{t \geq 0} \), and hence \( \nu \) in \( (Y_t)_{t \geq 0} \). Also \( \nu_+ \) and \( \nu_- \) are the laws of the supremum and infimum respectively of \( Y_{T \wedge t} \).

We are interested in the measure \( \nu_* \) where \( \nu_* \) is the law of \( \sup_{t \leq T} |Y_t| \).

Trivially, for \( z \geq 0 \),

\[
\max (\nu_+ (z), \nu_- (z)) \leq \nu_\ast ([z, \infty)) \leq \nu_+ (z) + \nu_- (z),
\]

and it follows that \( \nu_* \in \mathcal{L}^p \) if and only both \( \nu_+ \) and \( \nu_- \) are elements of \( \mathcal{L}^p \).

The next two lemmas give upper and lower bounds on \( \nu_+ \) and \( \nu_- \). We give proofs in the case of \( \nu_+ \); the corresponding results for \( \nu_- \) can be deduced using the transformation \( \mu \mapsto \tilde{\mu} \).

**Lemma 10.** For all \( z > 0 \), we have

\[
\nu_+ (z) \leq \frac{1}{s(z)} \left[ c_\gamma (-z) - c_\gamma (z) - |s(-z)|\nu((-\infty, -z]) \right] \mathbf{1}_{\{\gamma_+ (z) < z\}} + \nu(\{\{y| y \geq z\})
\]

\[
\nu_- (z) \leq \frac{1}{|s(-z)|} \left[ c_\gamma (z) - c_\gamma (-z) - s(z)\nu([z, \infty)) \right] \mathbf{1}_{\{\gamma_- (z) < z\}} + \nu(\{\{y| y \geq z\})
\]

**Proof.** Suppose first that \( z > \rho_+ (z) \), or equivalently \( s(-z) < -\gamma_+ (s(z)) \). Then by the convexity of \( c_M \) on \( \mathbb{R}_- \),

\[
c_M (-\gamma_+ (s(z))) - \gamma_+ (s(z)) \theta_+ (s(z)) \leq c_M (s(-z)) + s(-z)\nu((-\infty, -z]),
\]

which translates to

\[
c_\gamma (-\rho_+ (z)) + s(-\rho_+ (z))\zeta_+ (z) \leq c_\gamma (-z) + s(-z)\nu((-\infty, -z]).
\]

Substituting this inequality into (26) we deduce that

\[
s(z)\zeta_+ (z) = s(-\rho_+ (z))\zeta_+ (z) + c_\gamma (-\rho_+ (z)) - c_\gamma (z)
\]

\[
\leq c_\gamma (-z) - c_\gamma (z) + s(-z)\nu((-\infty, -z]).
\]
Conversely, if \( z \leq \rho_+ \), then
\[
\zeta_+ \leq \nu((-\infty, -\rho_+)) \leq \nu((-\infty, -z)).
\]
Given that \( \nu_+(z) = \nu([z, \infty)) + \zeta_+ \), these two bounds lead directly to (32).

**Lemma 11.** For all \( z > 0 \), we have
\[
\nu_+(z) \geq \frac{c_+(-z) - c_+(z)}{s(z) + |s(-z)|} + \nu([z, \infty)) \tag{34}
\]
\[
\nu_-(z) \geq \frac{c_+(z) - c_+(-z)}{s(z) + |s(-z)|} + \nu((-\infty, -z)). \tag{35}
\]

**Proof.** By (26), for \( z > 0 \),
\[
\zeta_+ \geq c_+(z) - c_+(-z)
\]
Since we also know \( \zeta_+ \geq 0 \) the result follows easily from the identity \( \nu_+(z) = \nu([z, \infty)) + \zeta_+ \).

**Corollary 12.** For \( z > 0 \), we have:
\[
\frac{1}{s(z)} + \frac{1}{|s(-z)|} c_+(z) - c_+(-z) \geq \nu_+(z) + \nu_-(z) \geq \frac{c_+(z) - c_+(-z)}{s(z) + |s(-z)|} + \nu([|y| \geq z]).
\]

Let \( T' \) be an embedding of \( \nu \) in \( Y \). For \( p > 0 \) we say this embedding is a \( H^p \)-embedding if \( \text{sup}_t |Y_t \wedge T'| \) is in \( L^p \). We may ask when does there exist a solution of the Skorokhod problem which is a \( H^p \)-embedding, and when is every solution of the Skorokhod problem a \( H^p \)-embedding? In this paper we are interested in the first of these questions. By the extremality properties of our embedding \( T \) it is clear that there exists a \( H^p \)-embedding if and only if \( T \) is a \( H^p \)-embedding.

Corollary 12 can be used to give necessary and sufficient conditions for \( \nu_* \) to be an element of \( L^p \). In particular, the following result follows easily from Corollary 12 and (31).

**Theorem 13.** Let \( Y_t \) be a regular diffusion and suppose that \( \nu \) can be embedded in \( Y \). Consider the embedding \( T \) of \( \nu \) given in (30). A sufficient condition for \( T \) to be a \( H^p \)-embedding is that \( \nu \in L^p \) and
\[
\int_{-\infty}^{\infty} y^{p-1} \left( \frac{1}{s(z)} + \frac{1}{|s(-z)|} \right) |c_+(z) - c_+(-z)| \, dy < \infty. \tag{36}
\]

Necessary conditions are that \( \nu \in L^p \) and
\[
\int_{-\infty}^{\infty} y^{p-1} \frac{|c_+(z) - c_+(-z)|}{s(z) + |s(-z)|} \, dy < \infty. \tag{37}
\]
Remark 14. Note that in the symmetric case where \( s(z) = -s(-z) \) then (36) and (37) are equivalent and Theorem 13 gives a necessary and sufficient condition for \( T \) to be a \( H^p \)-embedding.

We return to the problem of the existence of a \( H^p \)-embedding in the next section, and close this section with a further observation about the optimality of the embedding \( T \).

Remark 15. Let \( f: \mathbb{R} \to \mathbb{R} \) be some function, \( (Y_t)_{t \geq 0} \) a regular diffusion with \( Y_0 = 0 \) and \( \nu \) a probability measure on \( \mathbb{R} \). Then the embedding defined in (30) minimises the distribution of \( \sup_{t \geq 0} f(Y_t \wedge T') \) over all stopping times \( T' \) such that \( Y_{T'} \sim \nu \).

In particular the minimising choice of stopping time does not depend on the function \( f \). This is in contrast with the problem of finding the Skorokhod embedding which maximises the law of \( \sup_{t \geq 0} f(Y_t \wedge T') \). In that case the optimal embedding will in general depend on \( f \).

4 \( H^p \) embeddings for diffusions.

Our goal in this section is to investigate further conditions on whether \( T \) is a \( H^p \)-embedding in the cases when \( s(I) = (-\infty, \alpha), (\alpha, \infty), (\beta, \alpha) \) and \( \mathbb{R} \). The first two cases are equivalent up to the map \( x \mapsto -x \) and we consider them first.

4.1 Diffusions transient to \( +\infty \).

Theorem 16. Let \( Y_t \) be a diffusion on \( I \) with scale function \( s(z) \), such that \( s(0) = 0 \), \( \sup_{z \in I} s(z) = \alpha < \infty \), and \( \inf_{z \in I} s(z) = -\infty \). We may embed a law \( \nu \) in \( Y \) if and only if \( \int_I |s(z)| \nu(dz) < \infty \) and \( m = \int_I s(z) \nu(dz) \geq 0 \).

Under these conditions:

- if \( m > 0 \), then a necessary and sufficient condition for \( \mathbb{E} \sup_t |Y_{T \wedge t}|^p < \infty \) is that
  \[
  \int_{-\infty}^{\infty} \frac{z^{p-1}}{|s(-z)|} dz < \infty \quad \text{and} \quad \nu \in \mathcal{L}^p; \tag{38}
  \]
- if \( m = 0 \), this is also a sufficient condition. A necessary and sufficient condition is:
  \[
  \int_{-\infty}^{\infty} \frac{z^{p-1}}{|s(-z)|} \left| c_Y(z) - c_Y(-z) \right| dz < \infty \quad \text{and} \quad \nu \in \mathcal{L}^p. \tag{39}
  \]

Proof. The first part of this Theorem is a restatement of Lemma 8(i). For the second part assume \( m \geq 0 \) where \( m = \int_{-\infty}^{\infty} s(y) \nu(dy) - \int_{-\infty}^{0} |s(y)| \nu(dy) \).
For $z \geq 0$,
\[
\begin{align*}
c_Y(-z) - c_Y(z) &= -\int_{\{y < -z\}} |s(y)| \, \nu(dy) + \int_{\{y < z\}} s(y) \, \nu(dy) - m \\
&\quad + \int_{\{y \leq -z\}} |s(-z)| \, \nu(dy) - \int_{\{y \geq z\}} s(z) \, \nu(dy) \\
&\leq \int_{\{y > z\}} s(y) \, \nu(dy) + \int_{\{y \leq -z\}} |s(-z)| \, \nu(dy),
\end{align*}
\]
so by Lemma 10,
\[
\begin{align*}
\nu_+(z) &\leq \frac{1}{s(z)} [c_Y(-z) - c_Y(z) - |s(-z)| \nu((\infty, -z)) + 1_{\{z > \rho_+(z)\}} \\
&\quad + \nu(\{|y| \geq z\}) \\
&\leq \int_{\{y > z\}} \frac{s(y)}{s(z)} \, \nu(dy) + \nu(\{|y| \geq z\}) \\
&\leq \frac{\alpha}{s(z)} \nu(\{|y| \geq z\}).
\end{align*}
\]
Since $\alpha/s(z) < 2$ for sufficiently large $z$ it follows that $\nu \in \mathcal{L}^p$ is a necessary and sufficient condition for $\nu_+ \in \mathcal{L}^p$.

Now consider $\nu_-(z)$. We note that given $\varepsilon > 0$, for sufficiently large $z$,
\[
m - \varepsilon \leq c_Y(z) - c_Y(-z) \leq m + \varepsilon,
\]
and so by Lemma 10,
\[
\nu_-(z) \leq \frac{1}{|s(-z)|} (m + \varepsilon) + \nu(\{|y| \geq z\}).
\]
As a result (38) is a sufficient condition for $\nu_- \in \mathcal{L}^p$ when $m \geq 0$.

Conversely, if $m > 0$ Lemma 11 implies that for sufficiently large $z$,
\[
\nu_-(z) \geq \frac{1}{2|s(-z)|} (m - \varepsilon),
\]
and so (38) is also necessary.

Now suppose $m = 0$. By (33),
\[
\nu_-(z) \leq \frac{1}{|s(-z)|} [c_Y(z) - c_Y(-z)]_+ + \nu(\{|y| \geq z\})
\]
so (39) is a sufficient condition for $\nu_- \in \mathcal{L}^p$. By Corollary 12, for sufficiently large $z$,
\[
\nu_+(z) + \nu_-(z) \geq \frac{|c_Y(z) - c_Y(-z)|}{2|s(-z)|} + \nu(\{|y| \geq z\}).
\]
If $\nu_\ast \in \mathcal{L}^p$ then both $\nu_+$ and $\nu_-$ lie in $\mathcal{L}^p$, and so (39) is a necessary condition.
Example 17 (Drifting Brownian Motion). Suppose $Y$ is drifting Brownian motion on $\mathbb{R}$,
\[ Y_t = B_t + \kappa t, \]
for $t \geq 0$ and $\kappa > 0$. Then $s(y) = 1 - e^{-2\kappa y}$ is the scale function for $Y$, so $\sup_y s(y) = 1$. If $\int_{\mathbb{R}} s(y) \nu(dy) < 0$, then it is not possible to embed $\nu$ in $Y$. If $\int_{\mathbb{R}} s(y) \nu(dy) \geq 0$, we may embed $\nu$ in $Y$, and since
\[ \int_{-\infty}^{\infty} \frac{y^{p-1}}{|s(-y)|} dy = \int_{-\infty}^{\infty} \frac{y^{p-1}}{e^{2\kappa y} - 1} dy < \infty, \]
if follows that if $\nu \in \mathcal{L}^p$, then $\sup_t |Y_{T \wedge t}|$ is too.

These conclusions should be compared with those in [4]. Grandits and Falkner conclude that if $Y$ is drifting Brownian motion, and if $T'$ is any embedding of $\nu$ in $Y$, then $T' \in H^1$.

Example 18 (Bessel 3 Process). In [5] the authors consider a Skorokhod embedding for the $\text{Bes}(3)$ process. Let $Y$ solve
\[ dY_t = dB_t + \frac{1}{Y_t} dt, \quad Y_0 = 1. \]
Then $I = (0, \infty)$ and $s(y) = -1/y$. We do not have $Y_0 = 0$, nor $s(0) = 0$ but the modifications to the theory are trivial. We can embed $\nu$ in $Y$ if and only if $\int_0^{\infty} \nu(dy)/y < 1$. Furthermore $Y$ is only defined on the positive reals, so in deciding whether $\nu_+ \in \mathcal{L}^p$ we need only consider $\nu_+$. But, provided we may embed $\nu$ in $Y$, it follows from the proof of Theorem 16 that a necessary and sufficient condition for $\nu_+ \in \mathcal{L}^p$ is $\nu \in \mathcal{L}^p$.

4.2 Recurrent Diffusions

The general case is covered by Theorem 13. If we have some control on the scale function then we are able to make the results more explicit.

Theorem 19. Suppose for $|y| \geq 1$ there exists $k, K > 0$ such that
\[ k|y|^r \leq |s(y)| \leq K|y|^q, \text{ for some } q \geq r \geq 0. \tag{40} \]
Then for $p > 0$,

(i) if $p > q$,
\[ m = 0 \text{ and } \nu \in \mathcal{L}^{p+q-r} \implies \nu_+ \in \mathcal{L}^p \implies \nu \in \mathcal{L}^p \text{ and } m = 0; \]

(ii) if $p < r$,
\[ \nu \in \mathcal{L}^{p+q-r} \implies \nu_+ \in \mathcal{L}^p \implies \nu \in \mathcal{L}^p; \]
(iii) if \( r \leq p \leq q \),

\[
\int_{1}^{\infty} y^{p-r-1} |c_Y(y) - c_Y(-y)| \, dy < \infty \quad \text{and} \quad \nu \in \mathcal{L}^p
\]  

\[
\Rightarrow \nu_* \in \mathcal{L}^p
\]

\[
\Rightarrow \nu \in \mathcal{L}^p \quad \text{and} \quad \int_{0}^{\infty} y^{p-q-1} |c_Y(y) - c_Y(-y)| \, dy < \infty. \quad \text{(42)}
\]

In particular, if \( r = q \), the three cases each become if and only if statements.

**Proof.** (i) Suppose \( p > q \). If \( \nu \in \mathcal{L}^q \) then since \(|s(y)| \leq K|y|^q\) for \(|y| \geq 1\), we have \( \int |s(y)| \nu(dy) < \infty \), so \( m \) exists.

Now suppose \( m = 0 \) and \( \nu \in \mathcal{L}^{p+q-r} \). By Theorem 13 it is sufficient to show

\[
\int_{1}^{\infty} y^{p-1} \left( \frac{1}{s(y)} + \frac{1}{|s(-y)|} \right) |c_Y(y) - c_Y(-y)| \, dy < \infty
\]

For \( y > 0 \),

\[
c_Y(y) - c_Y(-y)
\]

\[
= \int_{|w| \leq y} s(w) \, \nu(dw) + \int_{|w| > y} s(y) \, \nu(dw) - \int_{|w| < -y} |s(-y)| \, \nu(dw)
\]

\[
= - \int_{|w| > y} s(w) \, \nu(dw) + s(y) \nu(\{w > y\}) - |s(-y)| \nu(\{w < -y\}).
\]

where we have used the fact that \( m = 0 \). By assumption

\[
\left( \frac{1}{s(y)} + \frac{1}{|s(-y)|} \right) \leq \frac{2}{k y^r}, \quad \text{for} \ y \geq 1
\]

so that

\[
\int_{1}^{\infty} y^{p-1} \left( \frac{1}{s(y)} + \frac{1}{|s(-y)|} \right) |c_Y(y) - c_Y(-y)| \, dy
\]

\[
\leq \frac{2}{k} \int_{1}^{\infty} y^{p-r-1} \left[ Ky^q \nu((y, \infty)) + Ky^q \nu((-\infty, -y)) \right]
\]

\[
+ \int_{|w| > y} |s(w)| \, \nu(dw) \] dy.

The first two terms in the bracket will be finite upon integration since \( \nu \in \mathcal{L}^{p+q-r} \). Also, by Fubini,

\[
\int_{1}^{\infty} y^{p-r-1} \left[ \int_{|w| > y} s(w) \, \nu(dw) \right] \, dy = \int_{|w| > 1} \left[ \int_{1}^{w} y^{p-r-1} s(w) \, dy \right] \nu(dw)
\]

\[
\leq K \int_{|w| > 1} w^{q+p-r} \nu(dw) < \infty.
\]
We can show a similar result for the integral over \( \{ w < 0 \} \) and it follows that \( \nu_* \in \mathcal{L}^p \).

Now suppose that \( \nu_* \in \mathcal{L}^p \). Then clearly \( \nu \in \mathcal{L}^p \), and

\[
\mathbb{E} \sup_t |s(Y_{T\wedge t})| \leq K \mathbb{E} \left( \sup_t |Y_{T\wedge t}|^q + 1 \right) \leq K \mathbb{E} \left( \sup_t |Y_{T\wedge t}|^p \right) + K < \infty.
\]

Furthermore \( s(Y_t) \) is a local martingale, so, since \( \mathbb{E} \sup_t |s(Y_{T\wedge t})| < \infty \), \( s(Y_{T\wedge t}) \) is a UI martingale, and hence

\[ m = \mathbb{E} (s(Y_T)) = 0. \]

(ii) Suppose now \( p < r \), and \( \nu \in \mathcal{L}^{p+q-r} \). Then as before, by Theorem 13 it is sufficient to show

\[
\int_1^{\infty} y^{p-1} \left( \frac{1}{s(y)} + \frac{1}{|s(-y)|} \right) |c_Y(y) - c_Y(-y)| \, dy < \infty.
\]

A simple inequality gives

\[
|c_Y(y) - c_Y(-y)| \leq c_Y(y) + c_Y(-y)
\]

\[
= \int_{\{|w| \leq y\}} |s(w)| \nu(dw) + s(y) \nu(\{|w| > y\}) + |s(-y)| \nu(\{|w| < -y\}),
\]

and so

\[
\int_1^{\infty} \left( \frac{1}{s(y)} + \frac{1}{|s(-y)|} \right) |c_Y(y) - c_Y(-y)| \, dy
\]

\[
\leq 2 \int_1^{\infty} y^{p-r-1} \left[ Ky^q \nu(\{|w| > y\}) + \int_{\{|w| \leq y\}} |s(w)| \nu(dw) \right] \, dy,
\]

where, as before, the first term is finite upon integration. For the final term

\[
\int_1^{\infty} y^{p-r-1} \left[ \int_{\{0 < w \leq y\}} s(w) \nu(dw) \right] \, dy
\]

\[
= \int_{\{w > 0\}} s(w) \left[ \int_{w \wedge 1}^{\infty} y^{p-r-1} \, dy \right] \nu(dw)
\]

\[
\leq \int_{\{w > 0\}} \frac{(w \vee 1)^{p-r}}{r-p} s(w) \nu(dw)
\]

\[
\leq \int_0^1 s(w) \, \nu(dw) + \frac{K}{r-p} \int_{\{w > 1\}} |w|^{p+q-r} \nu(dw),
\]

which is finite by assumption since \( \nu \in \mathcal{L}^{p+q-r} \). The corresponding result also holds over \( \{ w < 0 \} \). So we have shown \( \nu \in \mathcal{L}^{p+q-r} \implies \nu_* \in \mathcal{L}^p \). The second implication \( \nu_* \in \mathcal{L}^p \implies \nu \in \mathcal{L}^p \) is clear.

(iii) This case is a trivial application of (40) to Theorem 13. \( \square \)
For the integral condition in (41) to hold, a necessary condition is that \(|c_Y(z) - c_Y(-z)| \to 0\) as \(z \to \infty\). However this occurs if and only if \(m = 0\), provided \(m\) exists. So if \(m\) exists, if \(r = p = q\) and if \(\nu \in \mathcal{L}^p\), then \(m = 0\) is a necessary condition for \(\nu_* \in \mathcal{L}^p\). We show in Example 20 that this condition is not sufficient.

Note that it is not necessary for \(m\) to exist for the integral condition in (37) to be satisfied, and for \(\nu_*\) to be an element of \(\mathcal{L}^p\). For example, suppose that both the scale function and the target measure are symmetric about 0, i.e. suppose \(s(z) = -s(-z)\) and \(\nu(dz) = \nu(d(-z))\). Then \(c_Y(z) = c_Y(-z)\) and (37) is trivially satisfied. If \(s\) and \(\nu\) are symmetric then \(\nu_* \in \mathcal{L}^p\) if and only if \(\nu \in \mathcal{L}^p\).

Example 20. We now consider a diffusion on \(\mathbb{R}\) with behaviour specified by

\[dY_t = 2 \sqrt{|Y_t|} dB_t + \alpha \text{sign}(Y_t) dt,\]

where \(Y_0 = 0\), and \(\alpha \in (0, 2)\). The solution to this SDE is not unique in law, but we make it so by assuming the law of the process is symmetric about 0, and that the process does not wait at 0. In particular, \(|Y_t|\) is a Bessel process of dimension \(\alpha\). Such a process is recurrent, and we can construct the process \(Y_t\) from \(|Y_t|\) by assigning to each excursion away from 0 an independent random variable with value either 1 or \(-1\). Alternatively we may define the process by its scale function

\[s(y) = \left(|y|^{1-\frac{\alpha}{2}}\right) \text{sign}(y),\]

and write \(Y_t = s(W_{A_t})\), for a Brownian motion \(W_t\) and a suitable time change \(A_t\). Since \((Y_t)_{t \geq 0}\) is recurrent on \(\mathbb{R}\) we may embed any target distribution.

We may apply Theorem 19 to this process for some target distribution \(\nu\) and examine the behaviour of \(\sup_t |Y_{T \wedge t}|\), for our embedding \(T\). We note that, using the notation of Theorem 19, \(r = q = 1 - \frac{\alpha}{2}\), so the statements in the theorem each become if and only if statements. We can consider each case separately:

(i) In the case where \(p > 1 - \frac{\alpha}{2}\), \(\nu \in \mathcal{L}^p\) guarantees that \(m\) exists, and a necessary and sufficient condition for \(\sup_t |Y_{T \wedge t}| \in \mathcal{L}^p\) is that \(m = 0\).

(ii) If \(p < 1 - \frac{\alpha}{2}\), \(\nu \in \mathcal{L}^p\) is both necessary and sufficient for \(\sup_t |Y_{T \wedge t}| \in \mathcal{L}^p\).

(iii) Suppose now that \(p = 1 - \frac{\alpha}{2}\). If \(m \neq 0\) then \(\sup_t |Y_{T \wedge t}| \notin \mathcal{L}^p\). However we now show that \(m = 0\) is not a sufficient condition for \(\sup_t |Y_{T \wedge t}| \in \mathcal{L}^p\).

We embed the probability measure \(\nu\) defined by

\[\nu(dy) = \frac{y^{-p-1}}{(\log y)^2} dy \quad \text{for } y \geq e,\]
with the rest of the mass placed at $-b$. Here $b$ is chosen so that $\int s(y) \nu(dy) = 0$. It can be checked that $\nu \in L^p$. Then, provided $z > \max(e, -s^{-1}(-b))$,

$$|c_Y(z) - c_Y(-z)| = \int_{z}^{\infty} \frac{1}{y(\log y)^2} dy - z^p \nu((z, \infty))$$

$$= \frac{1}{\log z} - z^p \nu([z, \infty)).$$

Consequently, because $\nu \in L^p$ and $\int_{z}^{\infty} \frac{1}{y \log(y)} dy = \infty$,

$$\int_{z}^{\infty} y^{-1}|c_Y(y) - c_Y(-y)| dy = \infty.$$ 

So $m = 0$ is not sufficient to ensure that $\sup \left| Y_{T \wedge t} \right| \in L^p$.

4.3 Diffusions which in natural scale have state space consisting of a finite interval.

**Theorem 21.** Let $Y_t$ be a diffusion on $I$ with scale function $s(z)$, such that $s(0) = 0$, $\sup_{z \in I} s(z) = \alpha < \infty$, and $\inf_{z \in I} s(z) = \beta > -\infty$. We may embed a law $\nu$ in $Y$ if and only if $\int_I |s(z)| \nu(dz) < \infty$ and $m = \int_I s(z) \nu(dz) = 0$.

Furthermore $\nu_* \in L^p$ if and only if $\nu \in L^p$.

**Proof.** The first part of this result follows from Lemma 9(iii). The remaining part follows from Theorem 19. In our setting the scale function $s$ is bounded — so we have $q = r = 0$, $p > 0$ and we are in case (i). In particular, $m$ exists, and $\nu_* \in L^p$ if and only if $m = 0$ and $\nu \in L^p$. However we have already noted that in order to be able to embed in this case we must have $m = 0$, so our condition is essentially $\nu_* \in L^p \iff \nu \in L^p$.

**References**

[1] J. Azéma and M. Yor. Une solution simple au problème de Skorokhod. In Séminaire de Probabilités, XIII (Univ. Strasbourg, Strasbourg, 1977/78), pages 90–115. Springer, Berlin, 1979.

[2] R. V. Chacon and J. B. Walsh. One-dimensional potential embedding. In Séminaire de Probabilités, X (Prémière partie, Univ. Strasbourg, Strasbourg, année universitaire 1974/1975), pages 19–23. Lecture Notes in Math., Vol. 511. Springer, Berlin, 1976.

[3] L. E. Dubins. On a theorem of Skorohod. Ann. Math. Statist., 39:2094–2097, 1968.

[4] P. Grandits and N. Falkner. Embedding in Brownian motion with drift and the Azéma-Yor construction. Stochastic Process. Appl., 85(2):249–254, 2000.
[5] B.M. Hambly, G. Kersting, and A.E. Kyprianou. Upper and lower space-time envelopes for oscillating random walks conditioned to stay positive. Preprint, 2002.

[6] J. L. Pedersen and G. Peskir. The Azéma-Yor embedding in non-singular diffusions. *Stochastic Process. Appl.*, 96(2):305–312, 2001.

[7] E. Perkins. The Cereteli-Davis solution to the $H^1$-embedding problem and an optimal embedding in Brownian motion. In *Seminar on stochastic processes, 1985 (Gainesville, Fla., 1985)*, pages 172–223. Birkhäuser Boston, Boston, MA, 1986.

[8] L. C. G. Rogers and D. Williams. *Diffusions, Markov processes, and martingales. Vol. 2: Itô calculus*. Cambridge University Press, Cambridge, 2000. Reprint of the second (1994) edition.

[9] D. H. Root. The existence of certain stopping times on Brownian motion. *Ann. Math. Statist.*, 40:715–718, 1969.

[10] H. Rost. The stopping distributions of a Markov Process. *Invent. Math.*, 14:1–16, 1971.

[11] H. Rost. Skorokhod stopping times of minimal variance. In *Séminaire de Probabilités, X (Première partie, Univ. Strasbourg, Strasbourg, année universitaire 1974/1975)*, pages 194–208. Lecture Notes in Math., Vol. 511. Springer, Berlin, 1976.

[12] A. V. Skorokhod. *Studies in the theory of random processes*. Translated from the Russian by Scripta Technica, Inc. Addison-Wesley Publishing Co., Inc., Reading, Mass., 1965.

[13] P. Vallois. Quelques inégalités avec le temps local en zero du mouvement brownien. *Stochastic Process. Appl.*, 41(1):117–155, 1992.