Numerical Model Related to Impact Fluid / Solid Under the action of an Electric Field

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Abstract. The electrowetting is an area of significant interest. Many experimental studies have been conducted to find the relationship that binds the physical parameters of said phenomenon: the percentage of the white area inside the pixels of different sizes depending on the applied voltage etc. Our study is to develop a CFD model to validate the experimental results for the behavior of fluids (oil colored) within the reflector screens under the action of electric field.

1 Introduction

Electrowetting has become one of the most widely used for manipulating small amounts of liquids on surfaces under the influence of an electric field. This phenomenon is used in many industrial processes such as microfluidic "lab-on-a-chip", the devices (plans) of adjustable lenses to modify the convergence so in the industry of display screens. Our study is to develop a CFD (Computational Fluid Dynamics) method based on the VOF (Volume of Fluid) to follow the behavior of the liquid (in our case we choose the oil) inside a pixel under action of an electric field.

2 Mathematical Model

When a drop is placed on top of an electrode and the latter is then charged, the contact angle between the liquid surface (the drop) and the solid surface (electrode) is reduced. This is called electrowetting. Lippmann equation[1] reflects the change in the interfacial tension between the solid and the liquid as a function of the voltage V of the drop by the equation (1):

\[ \sigma_{SL}(V) = \sigma_{SL}(V = 0) - \frac{C}{2} V^2 \] (1)

Where, C is the specific capacity of the dielectric layer. From Young's equation (2) which describes the relationship between the contact angle \( \theta \) and the interfacial tension \( \sigma_{SL} \) between the interface solid-gas, solid-liquid and liquid-gas in the line of contact at the triple point (see Figure 1)

\[ \sigma_{LG} = \sigma_{SG} + \sigma_{SL} \cos \theta \] (2)

Fig.1 - The behavior of oil in water.

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Equation (3) Young-Lippmann [1] is given by:
\[
\cos \theta (V) - \cos \theta_0 = \frac{\varepsilon_0 \varepsilon_0}{2 \varepsilon_{LG} t} V^2
\]
\(\theta_0\): is the contact angle at equilibrium (V=0).
\(\varepsilon_0\): The permittivity of vacuum (8.85 \times 10^{-12} \text{ F/m}).
\(\varepsilon\): The dielectric constant of the dielectric layer.
\(t\): The thickness of the dielectric layer.

3 Numerical Model

A fundamental method to solve two-phase flow is the volume of fluid method (VOF), which was developed by Hirt and Nichols (1981). VOF method is a fixed mesh with the interface between immiscible fluids is modeled by a characteristic function (called volume fraction) [2].

3.1 The model equations

The Equations of mass and momentum conservation (4) and (5) for each phase are given by [3]:

\[\nabla \cdot V = 0\] (4)
\[\frac{\partial V}{\partial t} + \nabla \cdot (VV) = -\frac{1}{\rho} [\nabla P - \mu \nabla^2 V] + g + \frac{1}{\rho} F_{SF}\] (5)

Where \(V\) is the velocity vector, \(P\) is the pressure, and the \(F_{SF}\) is the surface force vector, \(\mu\) is the viscosity and density \(\rho\). The mixture density is calculated as follows:

\[\rho = \sum \alpha_k \rho_k\] (6)

Where \(\alpha_k\) is the volume fraction of the liquid. Any other property of the mixture is calculated as follows:

\[\varphi = \frac{\sum \alpha_k \rho_k \varphi_k}{\sum \alpha_k \rho_k}\] (7)

Where:
\(\alpha_k = 0\) : The cell is empty.
\(\alpha_k = 1\) : The cell is full.
\(0 < \alpha_k < 1\) : The cell contains an interface between the fluids.

The interface between the two phases was followed by solving the continuity equation for the function of the volume fraction:

\[\frac{\partial \alpha_k}{\partial t} + V \cdot \nabla \alpha_k = 0\] (8)
The surface tension has been modeled as a regular variation of the capillary pressures through the interface.

\[ F_{SF} = \alpha k n \left\lbrack \frac{\alpha_1 \rho_1 + \alpha_2 \rho_2}{1/2(\rho_1 + \rho_2)} \right\rbrack \]  

\[ n = \nabla \alpha_2 \]  

\[ k = -(\nabla \cdot \bar{n}) = \frac{1}{|n|} \left\lbrack \left( \frac{n}{|n|} \nabla \right) |n| - (\nabla \cdot n) \right\rbrack \]  

Where \( n \) is the surface normal, \( \bar{n} \) is the unit normal of the curvature. The surface normal \( n \) was evaluated in cells containing the interface and requires knowledge of the amount of volume of fluid present in the cell.

To calculate the electric potential in every area, the second order discretized form of the Laplace equation is solved at the beginning of each time step iteration [4].

\[ \nabla^2 \psi(x, y, z) = 0 \]  

### 3.2 Geometry and boundary conditions

We chose to study the problem in two dimensions. For this, the geometry is a square of dimension 1x1m². We used a structured grid square of size \( 5 \times 10^{-4} \) using the preprocessor Gambit 2.2.30. For the boundary conditions we used two conditions: the input condition is defined as a pressure inlet and the side walls are declared type Wall. Where the electrode is fixed between the insulator (Teflon) and the substrate is a white rectangle 15nm thick. The liquids used in this study are dodecane and water. A drop of dodecane whose radius is 10 \( \mu \)m is defined in the solver Ansys Fluent 12.0.16. The voltage applied to the surface of the Teflon is 15 volts. (See Figure 2.).

![Fig. 2 - a) Experimental Model [5] b) geometry in gambit.](image-url)
3.3 Results and Discussion

VOF method available in the code Ansys Fluent calculation allowed us a better observation of the drop profile and from the equation of fluid dynamics. The movement of the drop is observed when a voltage of 15V is applied to the electrode of time ranging from $t = 0$ to $t = 2.16 \times 10^{-2}$ s (FIG. 4).

It is clear that, at different $t$, the drop of oil contracts until the contact angle at the triple point reaches its maximum value.

Fig. 4 - the movement of a drop of oil in water under an electric field.
Fig. 5 - changing the radius of a drop of oil in water of dodecane under the effect of an electric field. We note that although the radius decreases as time increases.

Fig. 6 - electric potential distribution.

Figure 6 shows the distribution of equipotential for an actuation voltage of 15V. The maximum value of the electric potential is about 15V near the electrode.
The VOF model reflects the behavior of a drop of oil in the water under the effect of an electric field. We thus find the profile of the Lippmann equation (1) in perfect agreement with our model. This encourages us to find other relationships related to the behavior of droplets under the influence of an electric field, such as the numerical validation of the equation of Young-Lipmann.

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