Large Deviations for SPDEs of Jump Type

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Abstract

In this paper, we establish a large deviation principle for a fully non-linear stochastic evolution equation driven by both Brownian motions and Poisson random measures on a given Hilbert space $H$. The weak convergence method plays an important role.

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1 Introduction

In this paper, we are concerned with large deviation principles for stochastic evolution equations (stochastic partial differential equations (SPDEs) in particular) of jump type on some Hilbert space $H$:

$$X_t^\epsilon = X_0^\epsilon - \int_0^t A(X_s^\epsilon) ds + \sqrt{\epsilon} \int_0^t \sigma(s, X_s^\epsilon) d\beta(s) + \epsilon \int_0^t \int_X G(s, X_{s-}^\epsilon, v) \tilde{N}^\epsilon^{-1}(dsdv).$$ (1.1)

Here $A$ is an (normally unbounded) linear operator on $H$, $X$ is a locally compact Polish space. $\beta = (\beta_i)_{i=1}^\infty$ is an i.i.d. family of standard Brownian motions. $N^\epsilon^{-1}$ is a Poisson random measure on $[0, T] \times X$ with a $\sigma$-finite mean measure $\epsilon^{-1}\lambda_T \otimes \nu$, $\lambda_T$ is the Lebesgue measure on $[0, T]$ and $\nu$ is a $\sigma$-finite measure on $X$. $\tilde{N}^\epsilon^{-1}([0, t] \times B) = N^\epsilon^{-1}([0, t] \times B) - \epsilon^{-1}t\nu(B)$, $\forall B \in B(X)$ with $\nu(B) < \infty$, is the compensated Poisson random measure.

Large deviations for stochastic evolution equations and stochastic partial differential equations driven by Gaussian processes have been investigated in many papers, see e.g. [7], [8], [9], [15], [19]. The situations for stochastic evolution equations and stochastic partial differential equations driven by Lévy noise are drastically different because of the appearance of the jumps. There is not much work on this topic so far. The first paper on large deviations of SPDEs of jump type is [13] where the additive noise is considered. The case of multiplicative Lévy noise is studied in [16] where the large deviation was obtained on a larger space ( hence with a weaker topology ) than the actual state space of the solution. Recently, a new approach to large deviations of measurable maps of Poisson random measures (PRM) and Brownian motion (BM) was introduced in [5] based on variational representations of certain functionals of PRM and BM. One of the key elements in this approach is to prove
the weak convergence of random perturbations of the corresponding equations. So the underline topology is a very important factor to consider when establishing large deviations. In the new preprint [6], the authors applied the criteria in [5] to obtain a large deviation principle for stochastic partial differential equations driven by Poisson random measures on some nuclear spaces where tightness of measures are relatively easy to establish. Often the real state space of the solution of a stochastic partial differential equation is a smaller Hilbert space contained in the nuclear space. This makes it interesting to directly consider large deviations on the actual state space.

The aim of this paper is to establish a large deviation principle for a fully non-linear stochastic evolution equation driven by both Brownian motions and Poisson random measures like (1.1) on a given Hilbert space $H$. We will apply the criteria in [5]. Among other things, we need to prove the tightness of the solutions of random perturbations of the equation (1.1) on the space $D([0,T];H)$. To this end, we split the time interval $[0,T]$ into $[0,t_0]$ and $[t_0,T]$ for a given arbitrarily small positive constant $t_0 > 0$ because two different treatments are needed for these two intervals. This also make the proofs involved.

Finally we mention that large deviations for Lévy processes on Banach spaces and large deviations for solutions of stochastic differential equations driven by Poisson measures in finite dimensions were studied in [1], [2].

The rest of the paper is organized as follows. In Section 2, we recall the general criteria of large deviations obtained in [5] and formulate precisely the stochastic evolution equations we are going to study. Section 3 is devoted to the proof of the large deviation principle. A number of preparing propositions and lemmas will be proved in this section.

We end this section with some notations. For a topological space $\mathcal{E}$, denote the corresponding Borel $\sigma$-field by $\mathcal{B}(\mathcal{E})$. We will use the symbol $\Rightarrow$ to denote convergence in distribution. Let $\mathbb{N}$, $\mathbb{N}_0$, $\mathbb{R}$, $\mathbb{R}_+$, $\mathbb{R}^d$ denote the set of positive integers, non-negative integers, real numbers, positive real numbers, and $d$-dimensional real vectors respectively. For a Polish space $\mathcal{X}$, denote by $C([0,T],\mathcal{X})$, $D([0,T],\mathcal{X})$ the space of continuous functions and right continuous functions with left limits from $[0,T]$ to $\mathcal{X}$ respectively. For a metric space $\mathcal{E}$, denote by $M_b(\mathcal{E})$, $C_b(\mathcal{E})$ the space of real valued bounded $\mathcal{B}(\mathcal{E})/\mathcal{B}(\mathbb{R})$-measurable maps and real valued bounded continuous functions respectively. For $p > 0$, a measure $\nu$ on $\mathcal{E}$, and a Hilbert space $H$, denote by $L^p(\mathcal{E},\nu;H)$ the space of measurable functions $f$ from $\mathcal{E}$ to $H$ such that $\int_{\mathcal{E}} \|f(\nu)\|^p\nu(d\nu) < \infty$, where $\|\cdot\|_H$ is the norm on $H$. For a function $x : [0,T] \rightarrow \mathcal{E}$, we use the notation $x_t$ and $x(t)$ interchangeably for the evaluation of $x$ at $t \in [0,T]$. Similar convention will be followed for stochastic processes. We say a collection $\{X^\epsilon\}$ of $\mathcal{E}$-valued random variables is tight if the probability distributions of $X^\epsilon$ are tight in $\mathcal{P}(\mathcal{E})$ (the space of probability measures on $\mathcal{E}$).

2 Preliminaries

In the first part of this section, we will recall the general criteria for a large deviation principle given in [5]. To this send, we closely follow the framework and the notations in [6] and [5]. In the second part, we will precisely formulate the stochastic evolution equations we will study.
2.1 Large Deviation Principle

Let \( \{X^\epsilon, \epsilon > 0\} \equiv \{X^\epsilon\} \) be a family of random variables defined on a probability space \((\Omega, \mathcal{F}, \mathbb{P})\) and taking values in a Polish space (i.e., a complete separable metric space) \( \mathcal{E} \). Denote expectation with respect to \( \mathbb{P} \). The theory of large deviations is concerned with events \( A \) for which probability \( \mathbb{P}(X^\epsilon \in A) \) converge to zero exponentially fast as \( \epsilon \to 0 \).

The exponential decay rate of such probabilities is typically expressed in terms of a “rate function” \( I \) mapping \( \mathcal{E} \) into \([0, \infty]\).

**Definition 2.1 (Rate function)** A function \( I : \mathcal{E} \to [0, \infty] \) is called a rate function on \( \mathcal{E} \), if for each \( M < \infty \) the level set \( \{x \in \mathcal{E} : I(x) \leq M\} \) is a compact subset of \( \mathcal{E} \). For \( A \in \mathcal{B}(\mathcal{E}) \), we define \( I(A) = \inf_{x \in A} I(x) \).

**Definition 2.2 (Large deviation principle)** Let \( I \) be a rate function on \( \mathcal{E} \). The sequence \( \{X^\epsilon\} \) is said to satisfy the large deviation principle on \( \mathcal{E} \) with rate function \( I \) if the following two conditions hold.

a. Large deviation upper bound. For each closed subset \( F \) of \( \mathcal{E} \),

\[
\limsup_{\epsilon \to 0} \epsilon \log \mathbb{P}(X^\epsilon \in F) \leq -I(F).
\]

b. Large deviation lower bound. For each open subset \( G \) of \( \mathcal{E} \),

\[
\limsup_{\epsilon \to 0} \epsilon \log \mathbb{P}(X^\epsilon \in G) \geq -I(G).
\]

If a sequence of random variables satisfies a large deviation principle with some rate function, then the rate function is unique.

2.2 Poisson Random Measure and Brownian Motion

2.2.1 Poisson Random Measure

Let \( \mathbb{X} \) be a locally compact Polish space. Let \( \mathcal{M}_{FC}(\mathbb{X}) \) be the space of all measures \( \nu \) on \((\mathbb{X}, \mathcal{B}(\mathbb{X}))\) such that \( \nu(K) < \infty \) for every compact \( K \) in \( \mathbb{X} \). Endow \( \mathcal{M}_{FC}(\mathbb{X}) \) with the weakest topology such that for every \( f \in C_c(\mathbb{X}) \) (the space of continuous functions with compact supports), the function \( \nu \to \langle f, \nu \rangle = \int_{\mathbb{X}} f(u) d\nu(u), \nu \in \mathcal{M}_{FC}(\mathbb{X}) \) is continuous. This topology can be metrized such that \( \mathcal{M}_{FC}(\mathbb{X}) \) is a Polish space (see e.g. [5]). Fix \( T \in (0, \infty) \) and let \( \bar{\mathbb{X}}_T = [0, T] \times \mathbb{X} \). Fix a measure \( \mu \in \mathcal{M}_{FC}(\mathbb{X}) \), and let \( \nu_T = \lambda_T \otimes \nu \), where \( \lambda_T \) is Lebesgue measure on \([0, T] \).

We recall that a Poisson random measure \( \mathbf{n} \) on \( \mathbb{X}_T \) with mean measure (or intensity measure) \( \nu_T \) is a \( \mathcal{M}_{FC}(\mathbb{X}_T) \) valued random variable such that for each \( B \in \mathcal{B}(\mathbb{X}_T) \) with \( \nu_T(B) < \infty \), \( \mathbf{n}(B) \) is Poisson distributed with mean \( \nu_T(B) \) and for disjoint \( B_1, \ldots, B_k \in \mathcal{B}(\mathbb{X}_T) \), \( \mathbf{n}(B_1), \ldots, \mathbf{n}(B_k) \) are mutually independent random variables (cf. [13]). Denote by \( \mathbb{P} \) the measure induced by \( \mathbf{n} \) on \((\mathcal{M}_{FC}(\mathbb{X}_T), \mathcal{B}(\mathcal{M}_{FC}(\mathbb{X}_T))) \). Then letting \( \mathbb{M} = \mathcal{M}_{FC}(\mathbb{X}_T) \), \( \mathbb{P} \) is the unique probability measure on \((\mathbb{M}, \mathcal{B}(\mathbb{M})) \) under which the canonical map, \( N : \mathbb{M} \to \mathbb{M}, N(m) \equiv m \), is a Poisson random measure with intensity measure \( \nu_T \). With applications to large deviations in mind, we also consider, for \( \theta > 0 \), probability measures \( \mathbb{P}_\theta \) on \((\mathbb{M}, \mathcal{B}(\mathbb{M})) \) under which \( N \) is a Poisson random measure with intensity \( \theta \nu_T \). The corresponding expectation operators will be denoted by \( \mathbb{E} \) and \( \mathbb{E}_\theta \), respectively.

Let \( \mathbb{Y} = \mathbb{X} \times [0, \infty) \) and \( \mathbb{Y}_T = [0, T] \times \mathbb{Y} \). Let \( \mathbb{M} = \mathcal{M}_{FC}(\mathbb{Y}_T) \) and let \( \bar{\mathbb{P}} \) be the unique probability measure on \((\mathbb{M}, \mathcal{B}(\mathbb{M})) \) under which the canonical map, \( \bar{N} : \mathbb{M} \to \mathbb{M}, \bar{N}(m) \equiv m \),
is a Poisson random measure with intensity measure \( \tilde{\nu}_T = \lambda_T \otimes \nu \otimes \lambda_\infty \), with \( \lambda_\infty \) being Lebesgue measure on \([0, \infty)\). The corresponding expectation operator will be denoted by \( \mathbb{E} \).

Let \( \mathcal{F}_t = \sigma(\{N((0, s] \times A) : 0 \leq s \leq t, A \in \mathcal{B}(\mathcal{Y})\}) \), and let \( \mathcal{F}_t \) denote the completion under \( \mathbb{P} \).

We denote by \( \mathcal{P} \) the predictable \( \sigma \)-field on \([0, T] \times \mathcal{M} \) with the filtration \( \{\mathcal{F}_t : 0 \leq t \leq T\} \) on \((\mathcal{M}, \mathcal{B}(\mathcal{M}))\). Let \( \tilde{\mathcal{A}} \) be the class of all \( (\mathcal{P} \otimes \mathcal{B}(\mathcal{X}))/\mathcal{B}(0, \infty) \)-measurable maps \( \varphi : \mathcal{X}_T \times \mathcal{M} \to [0, \infty) \).

For \( \varphi \in \tilde{\mathcal{A}} \), define a counting process \( N^\varphi \) on \( \mathcal{X}_T \) by

\[
N^\varphi((0, t] \times U) = \int_{(0, t] \times U} 1_{[0, \varphi(s, x)]}(r) \tilde{N}(dsdxr), \quad t \in [0, T), U \in \mathcal{B}(\mathcal{X}).
\]

\( N^\varphi \) is the controlled random measure, with \( \varphi \) selecting the intensity for the points at location \( x \) and time \( s \), in a possibly random but non-anticipating way. When \( \varphi(s, x, \tilde{m}) \equiv \theta \in (0, \infty) \), we write \( N^\varphi = N^\theta \). Note that \( N^\theta \) has the same distribution with respect to \( \mathbb{P} \) as \( N \) has with respect to \( \mathbb{P}_\theta \).

### 2.2.2 PRM and BM

Denote \( C([0, T], \mathbb{R}_\infty) \) by \( \mathcal{W} \), where \( \mathbb{R}_\infty \) is the infinite product space of the real line \( \mathbb{R} \) and endowed with the product topology. Let \( \mathcal{V} = \mathcal{W} \times \mathcal{M} \). Then let the mapping \( \mathcal{N} : \mathcal{V} \to \mathcal{M} \) be defined by \( \mathcal{N}(w, m) = m \) for \((w, m) \in \mathcal{V}\), and let \( \beta = (\beta_i)_{i=1}^\infty \) be defined by \( \beta_i(w, m) = w_i \) for \((w, m) \in \mathcal{V}\). Define the \( \sigma \)-filtration \( \mathcal{G}_t := \sigma(\mathcal{N}((0, s] \times A), \beta_i(s) : 0 \leq s \leq t, A \in \mathcal{B}(\mathcal{Y}), i \geq 1) \).

For every \( \theta > 0 \), \( \mathbb{P}_\theta \) denotes the unique probability measure on \((\mathcal{V}, \mathcal{B}(\mathcal{V}))\) such that:

(a) \((\beta_i)_{i=1}^\infty\) is an i.i.d. family of standard Brownian motions.

(b) \( N \) is a PRM with intensity measure \( \theta \nu_T \).

If controlled Poisson random measure is also considered, we set \( \mathcal{V} := \mathcal{W} \times \mathcal{M} \), and let the mapping \( \tilde{\mathcal{N}} : \mathcal{V} \to \mathcal{M} \) be defined by \( \tilde{\mathcal{N}}(\tilde{w}, \tilde{m}) = \tilde{m} \) for \((\tilde{w}, \tilde{m}) \in \mathcal{V}\). Analogously, we define \((\mathbb{P}_\theta, \mathcal{G}_t)\). We denote by \( \{\mathcal{F}_t\} \) the \( \mathbb{P} \)-completion of \( \{\mathcal{G}_t\} \) and \( \mathcal{P} \) the predictable \( \sigma \)-field on \([0, T] \times \mathcal{V} \) with the filtration \( \{\mathcal{F}_t\} \) on \((\mathcal{V}, \mathcal{B}(\mathcal{V}))\). Let \( \tilde{\mathcal{A}} \) be the class of all \((\mathcal{P} \otimes \mathcal{B}(\mathcal{X}))/\mathcal{B}(0, \infty) \)-measurable maps \( \varphi : \mathcal{X}_T \times \mathcal{V} \to [0, \infty) \).

Define \( l : [0, \infty) \to [0, \infty) \) by

\[
l(r) = r \log r - r + 1, \quad r \in [0, \infty).
\]

For any \( \varphi \in \tilde{\mathcal{A}} \) the quantity

\[
L_T(\varphi) = \int_{\mathcal{X}_T} l(\varphi(t, x, \omega)) \nu_T(dt dx)
\]

is well defined as a \([0, \infty] \)-valued random variable.

Let \( H \) be a separable Hilbert space.

Define function space

\[
\mathcal{L}_2 := \{ \psi : \psi \text{ is } \tilde{\mathcal{P}} \setminus \mathcal{B}(H) \text{ measurable and } \int_0^T \|\psi(s)\|_H^2 ds < \infty, a.s. - \mathbb{P} \}.
\]

Set \( \mathcal{U} = \mathcal{L}_2 \times \tilde{\mathcal{A}} \). Define \( \tilde{L}_T(\psi) := \frac{1}{2} \int_0^T \|\psi(s)\|_H^2 ds \) for \( \psi \in \mathcal{L}_2 \), and \( L_T(u) := \tilde{L}_T(\psi) + L_T(\varphi) \) for \( u = (\psi, \varphi) \).
2.3 A General Criteria

In this section, we recall a general criteria for a large deviation principle established in [5]. Let \( \{G^\epsilon \}_{\epsilon > 0} \) be a family of measurable maps from \( \bar{V} \) to \( U \), where \( \bar{V} \) is introduced in Section 2.2.1 and \( U \) is some Polish space. We present below a sufficient condition for large deviation principle (LDP in abbreviation) to hold for the family \( Z^\epsilon = G^\epsilon(\sqrt{\epsilon \beta}, \epsilon N^{\epsilon^{-1}}) \), as \( \epsilon \to 0 \).

Define

\[
S^N = \{ g : \mathbb{X}_T \to [0, \infty) : L_T(g) \leq N \},
\]

and

\[
\tilde{S}^N = \{ f : L^2([0, T] : H) : \tilde{L}_T(f) \leq N \}.
\]

A function \( g \in S^N \) can be identified with a measure \( \nu^g_T \in \mathcal{M} \), defined by

\[
\nu^g_T(A) = \int_A g(s, x) d\nu_T(dsdx), \quad A \in B(\mathbb{X}_T).
\]

This identification induces a topology on \( S^N \) under which \( S^N \) is a compact space, see the Appendix of [5]. Throughout we use this topology on \( S^N \). Set \( \tilde{S}^N = \tilde{S}^N \times S^N \). Define \( S = \bigcup_{N \geq 1} S^N \), and let

\[
U^N = \{ u = (\psi, \varphi) \in U : u(\omega) \in \tilde{S}^N, \bar{P} \text{ a.e. } \omega \},
\]

where \( U \) is introduced in Section 2.2.2.

The following condition will be sufficient to establish a LDP for a family \( \{Z^\epsilon\}_{\epsilon > 0} \) defined by \( Z^\epsilon = G^\epsilon(\sqrt{\epsilon \beta}, \epsilon N^{\epsilon^{-1}}) \).

**Condition 2.1** There exists a measurable map \( G^0 : \bar{V} \to U \) such that the following hold.

a. For \( N \in \mathbb{N} \), let \( (f_n, g_n) \), \( (f, g) \in \tilde{S}^N \) be such that \( (f_n, g_n) \to (f, g) \) as \( n \to \infty \). Then

\[
G^0(\int_0^T f_n(s)ds, \nu^n_T) \to G^0(\int_0^T f(s)ds, \nu_T) \quad \text{in} \quad \mathbb{U}.
\]

b. For \( N \in \mathbb{N} \), let \( u_\epsilon = (\psi_\epsilon, \varphi_\epsilon) = (\psi, \varphi) \in U^N \) be such that \( u_\epsilon \) converges in distribution to \( u \) as \( \epsilon \to 0 \). Then

\[
G^\epsilon(\sqrt{\epsilon \beta} + \int_0^T \psi_\epsilon(s)ds, \epsilon N^{\epsilon^{-1}} \varphi_\epsilon) \Rightarrow G^0(\int_0^T \psi(s)ds, \nu_\epsilon^T).
\]

For \( \phi \in \mathbb{U} \), define \( S_\phi = \{ (f, g) \in S : \phi = G^0(\int_0^T f(s)ds, \nu^T) \} \). Let \( I : \mathbb{U} \to [0, \infty] \) be defined by

\[
I(\phi) = \inf_{(f, g) \in S_\phi} \{ \tilde{L}_T(q) \}, \quad \phi \in \mathbb{U}.
\]

By convention, \( I(\phi) = \infty \) if \( S_\phi = \emptyset \).

The following criteria was established in [5].

**Theorem 2.3** For \( \epsilon > 0 \), let \( Z^\epsilon \) be defined by \( Z^\epsilon = G^\epsilon(\sqrt{\epsilon \beta}, \epsilon N^{\epsilon^{-1}}) \), and suppose that Condition 2.1 holds. Then \( I \) defined as in (2.7) is a rate function on \( \mathbb{U} \) and the family \( \{Z^\epsilon\}_{\epsilon > 0} \) satisfies a large deviation principle with rate function \( I \).
For applications, the following strengthened form of Theorem 2.3 is useful. Let \( \{K_n \subset X, n = 1, 2, \cdots \} \) be an increasing sequence of compact sets such that \( \bigcup_{n=1}^{\infty} K_n = X \). For each \( n \) let

\[
\tilde{A}_{b,n} = \{ \varphi \in \tilde{A} : \text{for all } (t, \omega) \in [0, T] \times \Omega, n \geq \varphi(t, x, \omega) \geq 1/n \text{ if } x \in K_n \text{ and } \varphi(t, x, \omega) = 1 \text{ if } x \in K_n^c \},
\]

and let \( \tilde{A}_b = \bigcup_{n=1}^{\infty} \tilde{A}_{b,n} \). Define \( \tilde{U}^N = U^N \cap \{(\psi, \phi) : \phi \in \tilde{A}_b \} \).

**Theorem 2.4** Suppose Condition 2.1 holds with \( U^N \) replaced by \( \tilde{U}^N \). Then the conclusions of Theorem 2.3 continue to hold.

### 2.4 SPDEs

In this section we introduce the stochastic partial differential equations (SPDEs in abbreviation) that will be studied in this paper. Let \( H, V \) be two separable Hilbert spaces such that \( V \) is continuously, densely imbedded in \( H \). Identifying \( H \) with its dual we have

\[
V \subset H \cong H' \subset V',
\]

where \( V' \) stands for the topological dual of \( V \). Let \( A \) be a bounded linear operator from \( V \) to \( V' \) satisfying the following coercivity hypothesis: There exist constants \( \alpha > 0 \) and \( \lambda_0 \geq 0 \) such that

\[
2\langle Au, u \rangle + \lambda_0 \|u\|^2_H \geq \alpha \|u\|^2_V, \text{ for all } u \in V.
\]

**Example 2.5** Let \( H = L^2(D) \), where \( D \subset \mathbb{R}^d \) is a bounded domain, and set

\[
V = H_{0,2}^1(D) = C_0^\infty(D),
\]

where \( C_0^\infty(D) \) is the space of infinite differentiable functions with compact supports and the norm is defined as follows

\[
\|f\|^2 := \|f\|^2_{L^2} + \|\nabla f\|^2_{L^2}.
\]

Denote by \( a(x) = (a_{ij}(x)) \) a matrix-valued function on \( D \) satisfying the uniform ellipticity condition:

\[
\frac{1}{c} I_d \leq a(x) \leq c I_d \quad \text{for some constant } c \in (0, \infty).
\]

Let \( b(x) \) be a vector field on \( D \) with \( b \in L^p(D) \) for some \( p > d \). Define

\[
Au = -\text{div}(a(x) \nabla u(x)) + b(x) \cdot \nabla u(x).
\]

Then (2.8) is fulfilled for \( (H, V, A) \).

**Example 2.6** Stochastic evolution equations associated with fractional Laplacian:

\[
dY_t = \Delta_\alpha Y_t dt + dL_t, \quad Y_0 = h \in H, \tag{2.9}
\]

where \( \Delta_\alpha \) denotes the generator of the symmetric \( \alpha \)-stable process in \( \mathbb{R}^d \), \( 0 < \alpha \leq 2 \). \( \Delta_\alpha \) is called the fractional Laplace operator. \( L_t \) stands for a Lévy process. It is well known that the Dirichlet form associated with \( \Delta_\alpha \) is given by

\[
E(u, v) = K(d, \alpha) \int \int_{\mathbb{R}^d \times \mathbb{R}^d} \frac{(u(x) - u(y))(v(x) - v(y))}{|x - y|^{d+\alpha}} \, dx \, dy,
\]
\[ D(E) = \{ u \in L^2(R^d) : \int_{R^d \times R^d} \frac{|u(x) - u(y)|^2}{|x-y|^{d+\alpha}} \, dx \, dy < \infty \}, \]

where \( K(d, \alpha) = \alpha 2^{\alpha-3} \pi^{-\frac{d+2}{2}} \sin(\frac{\alpha}{2}) \Gamma(\frac{d+2}{2}) \Gamma(\frac{\alpha}{2}) \). We choose \( H = L^2(R^d) \), and \( V = D(E) \) with the inner product \( \langle u, v \rangle = \mathcal{E}(u,v) + (u,v)_{L^2(R^d)} \).

Define
\[ \mathcal{A}u = -\Delta_{\alpha}. \]

Then (2.8) is fulfilled for \((H, V, \mathcal{A})\). See [12] for details about the fractional Laplace operator.

Assume that \( \mathcal{A}^{*} \) the adjoint operator of \( \mathcal{A} \), admits a complete system of eigenvectors; that is, there exists a sequence \( \{ \epsilon_k, k \geq 1 \} \subset V \) that forms an orthonormal basis of \( H \) such that
\[ \mathcal{A}^{*}e_k = \zeta_k e_k \quad \text{for} \ k \geq 1. \]

We assume \( 0 \leq \zeta_1 \leq \zeta_2 \leq \cdots \to \infty \) and denote by \( H_{\mathcal{A}^*} = \{ h \in H : \| \mathcal{A}^*h \|_H^2 < \infty \} \) the domain of \( \mathcal{A}^{*} \). Suppose that the \( H \) cylindrical Brownian motion \( \beta \) admits the following representation:
\[ \beta_t = \sum_{k=1}^{\infty} \beta_k(t)e_k \]

where \( \beta_k(t), k \geq 1 \) are independent standard Brownian motions.

Denote by \( L_2(H) \) the space of all Hilbert-Schmidt operators from \( H \) to \( H \). Let \( \sigma : [0, T] \times H \to L_2(H), \ G : [0, T] \times H \times \mathbb{X} \to H \) be maps satisfying the following conditions:

**Condition 2.2**

There exists \( K(\cdot) \in L^1([0, T], \mathbb{R}^+) \) such that

1. **(Growth)** For all \( t \in [0, T], \) and \( u \in H, \)
\[ \| \sigma(t,u) \|_{L^2(H)}^2 + \int_{\mathbb{X}} \| G(t,u,v) \|_H^2 \nu(dv) \leq K(t)(1 + \| u \|_H^2); \]

2. **(Lipschitz)** For all \( t \in [0, T], \) and \( u_1, u_2 \in H, \)
\[ \| \sigma(t,u_1) - \sigma(t,u_2) \|_{L^2(H)}^2 + \int_{\mathbb{X}} \| G(t,u_1,v) - G(t,u_2,v) \|_H^2 \nu(dv) \leq K(t)\| u_1 - u_2 \|_H^2. \]

Consider the following stochastic evolution equation:
\[ X^t = X^t_0 - \int_0^t \mathcal{A}X^s ds + \sqrt{\epsilon} \int_0^t \sigma(s, X^s) \, d\beta(s) + \epsilon \int_0^t \int_{\mathbb{X}} G(s, X^s_{\cdot}, v) \tilde{\nu}^{-1}(dsdv). \]  \( (2.11) \)

Here the precise definition of the solution to (2.11) is as follows.

**Definition 2.7** Let \((\tilde{\mathbb{V}}, \mathcal{B}(\tilde{\mathbb{V}}), \tilde{\mathbb{P}}, \{ \tilde{\mathcal{F}}_t \})\) be the filtered probability space described in Section 2.2. Suppose that \( X_0 \) is a \( \mathcal{F}_0 \)-measurable \( H \)-valued random variable such that \( \mathbb{E}\| X_0 \|_H^2 < \infty. \) A stochastic process \( \{ X^t \} \in [0, T] \) defined on \( \tilde{\mathbb{V}} \) is said to be a \( H \)-valued solution to (2.11) with initial value \( X_0 \), if

a) \( X^t_0 \) is a \( H \)-valued \( \mathcal{F}_t \)-measurable random variable, for all \( t \in [0, T]; \)

b) \( X^t \in D([0, T], H) \cap L^2([0, T], V) \) a.s.;
c) For all $t \in [0, T]$, every $\phi \in V$, 

$$
\langle X_t^\epsilon, \phi \rangle = \langle X_0, \phi \rangle - \int_0^t \langle AX_s^\epsilon, \phi \rangle ds + \sqrt{\epsilon} \int_0^t \sigma(s, X_s^\epsilon)d\beta(s, \phi) + \epsilon \int_0^t \int_X \langle G(s, X_s^\epsilon, v), \phi \rangle \tilde{N}^{-1}(ds, dv), \text{ a.s.}
$$

(2.12)

**Definition 2.8 (Pathwise uniqueness)** We say that the $H$-valued solution for the stochastic evolution equation (2.11) has the pathwise uniqueness if any two $H$-valued solutions $X$ and $X'$ defined on the same filtered probability space with respect to the same Poisson random measure and Brownian motion starting from the same initial condition $X_0$ coincide almost surely.

3 Large Deviation Principle

Assume $X_0$ is deterministic. Let $X^\epsilon$ be the $H$-valued solution to (2.11) with initial value $X_0$. In this section, we establish an LDP for $\{X^\epsilon\}$ under suitable assumptions.

We begin by introducing the map $G_0$ that will be used to define the rate function and also used for verification of Condition 2.1. Recall that $S = \bigcup_{N \geq 1} \bar{S}^N$, where $\bar{S}^N$ is defined in last section. As a first step we show that under the conditions below, for every $q = (f, g) \in S$, the deterministic integral equation

$$
\tilde{X}_t^q = X_0 - \int_0^t AX_s^q ds + \int_0^t \sigma(s, \tilde{X}_s^q)f(s)ds + \int_0^t \int_X G(s, \tilde{X}_s^q, v)(g(s, v) - 1)\nu(dv)ds
$$

(3.13)

has a unique continuous solution. Here $q = (f, g)$ plays the role of a control.

Let

$$
\|G(t, v)\|_{0,H} = \sup_{u \in H} \frac{\|G(t, u, v)\|_H}{1 + \|u\|_H}, \quad (t, v) \in [0, T] \times \mathbb{X}.
$$

$$
\|G(t, v)\|_{1,H} = \sup_{u_1, u_2 \in H, u_1 \neq u_2} \frac{\|G(t, u_1, v) - G(t, u_2, v)\|_H}{\|u_1 - u_2\|_H}, \quad (t, v) \in [0, T] \times \mathbb{X}.
$$

**Condition 3.1 (Exponential Integrability)** For $i = 0, 1$, there exists $\delta_i > 0$ such that for all $E \in \mathcal{B}([0, T] \times \mathbb{X})$ satisfying $\nu_T(E) < \infty$, the following holds

$$
\int_E e^{\delta_i \|G(s, v)\|^2_0} \nu(dv)ds < \infty.
$$

**Remark 1** Condition 3.1 implies that, for every $\delta_2 > 0$ and for all $E \in \mathcal{B}([0, T] \times \mathbb{X})$ satisfying $\nu_T(E) < \infty$, 

$$
\int_E e^{\delta_2 \|G(s, v)\|^2_0} \nu(dv)ds < \infty.
$$

Now recall the following inequalities from [6], which will be used later.

a) For $a, b, \sigma \in (0, \infty)$, there exists $C(\sigma)$ only depending on $\sigma$, such that

$$
ab = C(\sigma)e^{\sigma a} + \frac{1}{\sigma}(b \log b - b + 1) = C(\sigma)e^{\sigma a} + \frac{1}{\sigma}l(b);
$$

(3.14)
Lemma 3.3

b) For each $\beta > 0$ there exists $c_1(\beta) > 0$, such that $c_1(\beta) \to 0$ as $\beta \to \infty$ and

$$|x - 1| \leq c_1(\beta)l(x) \text{ whenever } |x - 1| \geq \beta;$$

c) For each $\beta > 0$ there exists $c_2(\beta) < \infty$, such that

$$|x - 1|^2 \leq c_2(\beta)l(x) \text{ whenever } |x - 1| \leq \beta.$$

The following lemma was proved in [6].

**Lemma 3.1** Under Condition 2.2 and Condition 3.1 for $i = 0, 1$ and every $N \in \mathbb{N}$,

$$C_{i,2}^N := \sup_{g \in S^N} \int_{X^T} \|G(s, v)\|_{i, H}^2 (g(s, v) + 1) \nu(dv) ds < \infty, \quad (3.15)$$

$$C_{i,1}^N := \sup_{g \in S^N} \int_{X^T} \|G(s, v)\|_{i, H} |g(s, v) - 1| \nu(dv) ds < \infty. \quad (3.16)$$

We also need the following lemma whose proof can be found in Chapter III of [17].

**Lemma 3.2** Assume that

$$\begin{cases}
  f = f_1 + f_2, \ f_1 \in L^2([0, T], V'), \ f_2 \in L^1([0, T], H), \\
  u_0 \in H,
\end{cases}$$

then there exists a unique function $u$ (denote by $u'$ its derivative) which satisfies

$$\begin{cases}
  u \in L^2([0, T], V) \cap C([0, T], H), \ u' \in L^2([0, T], V') + L^1([0, T], H), \\
  \langle u_t, \phi \rangle = \langle u_0, \phi \rangle - \int_0^t \langle Au_s, \phi \rangle ds + \int_0^t \langle f_s, \phi \rangle ds, \ \forall \phi \in V, \\
  \frac{d}{dt} \langle u, u \rangle = 2\langle u', u \rangle.
\end{cases}$$

**Lemma 3.3 a)** If $Y \in C([0, T], H)$, for any $q = (f, g) \in E$, then

$$\sigma(\cdot, Y(\cdot))f(\cdot) \in L^1([0, T], H), \ \int_X G(\cdot, Y(\cdot), v)(g(\cdot, v) - 1) \nu(dv) \in L^1([0, T], H);$$

b) If $Y_n \in C([0, T], H)$, $n \geq 1$ with $C = \sup_n \sup_{s \in [0, T]} \|Y_n(s)\|_H < \infty$, then

$$\tilde{C}_N := \sup_{q = (f, g) \in E} \sup_n \left[ \int_0^T \| \int_X G(s, Y_n(s), v)(g(s, v) - 1) \nu(dv) \|_H ds + \int_0^T \|\sigma(s, Y_n(s))f(s)\|_H ds \right] < \infty.$$

**Proof:** Since

$$\begin{align*}
  \int_0^t \| \int_X G(s, Y(s), v)(g(s, v) - 1) \nu(dv) \|_H ds \\
  \leq \int_0^t \int_X \|G(s, Y(s), v)(g(s, v) - 1)\|_H \nu(dv) ds \\
  = \int_0^t \int_X \frac{\|G(s, Y(s), v)\|_H}{1 + \|Y(s)\|_H} |g(s, v) - 1| (1 + \|Y(s)\|_H) \nu(dv) ds
\end{align*}$$
by Condition 2.2,

\[
\int_0^t \|\sigma(s, Y(s))f(s)\|_{H} ds \leq \int_0^t \|\sigma(s, Y(s))\|_{L_2(H)} \|f(s)\|_{H} ds
\]

\[
\leq \int_0^t \|\sigma(s, Y(s))\|^2_{L_2(H)} ds + \int_0^t \|f(s)\|^2_{H} ds
\]

\[
\leq \int_0^t \|\sigma(s, Y(s))\|^2_{H} ds + \int_0^t \|f(s)\|^2_{H} ds
\]

the lemma follows from Lemma 3.1.

**Theorem 3.1** Fix \( q = (f, g) \in S \). Suppose Condition 2.2 and Condition 3.1 hold. Then there exists a unique \( \tilde{X}_q^0 \in C([0, T], H) \) such that

\[
\langle \tilde{X}_q^t, \phi \rangle = \langle X_0, \phi \rangle - \int_0^t \langle \tilde{X}_q^s, A^* \phi \rangle ds + \int_0^t \langle \sigma(s, \tilde{X}_q^s) f(s), \phi \rangle ds
\]

\[
+ \int_0^t \int_X \langle G(s, \tilde{X}_q^s), \phi \rangle (g(s, v) - 1) \nu(dv) ds. \tag{3.17}
\]

Moreover, for fixed \( N \in \mathbb{N} \), there exists \( C_N > 0 \) such that

\[
\sup_{q \in S^N} \left( \sup_{s \in [0, T]} \|\tilde{X}_q^s\|^2_{H} + \int_0^T \|\tilde{X}_q^s\|^2_V ds \right) \leq C_N. \tag{3.18}
\]

**Proof: Existence of solution:** Let \( Y_0(t) := X_0, t \geq 0 \). Suppose \( Y_{n-1} \) has been defined, by Lemma 3.2 and Lemma 3.3 there exists a unique function \( Y_n \in L^2([0, T], V) \cap C([0, T], H) \) such that

\[
\langle Y_n(t), \phi \rangle = \langle X_0, \phi \rangle - \int_0^t \langle AY_n(s), \phi \rangle ds + \int_0^t \langle \sigma(s, Y_{n-1}(s)) f(s), \phi \rangle ds
\]

\[
+ \int_0^t \int_X \langle G(s, Y_{n-1}(s), v)(g(s, v) - 1), \phi \rangle \nu(dv) ds, \quad \phi \in V; \tag{3.19}
\]

and

\[
\|Y_{n+1}(t) - Y_n(t)\|^2_H
\]

\[
= -2 \int_0^t \langle A(Y_{n+1}(s) - Y_n(s)), Y_{n+1}(s) - Y_n(s) \rangle ds
\]

\[
+ 2 \int_0^t \langle (\sigma(s, Y_n(s)) - \sigma(s, Y_{n-1}(s))) f(s), Y_{n+1}(s) - Y_n(s) \rangle ds
\]

\[
+ 2 \int_0^t \int_X \langle G(s, Y_n(s), v) - G(s, Y_{n-1}(s), v), Y_{n+1}(s) - Y_n(s) \rangle (g(s, v) - 1) \nu(dv) ds.
\]
In view of (2.38),

\[
\|Y_{n+1}(t) - Y_n(t)\|_H^2 + \alpha \int_0^t \|Y_{n+1}(s) - Y_n(s)\|_Y^2 ds \\
\leq 2 \int_0^t \|\sigma(s, Y_n(s)) - \sigma(s, Y_{n-1}(s))\|_H \|Y_{n+1}(s) - Y_n(s)\|_H ds \\
+ 2 \int_0^t \int_X \|G(s, Y_n(s), v) - G(s, Y_{n-1}(s), v)\|_H \|Y_{n+1}(s) - Y_n(s)\|_H |g(s, v) - 1| \nu(dv) ds \\
+ \lambda_0 \int_0^t \|Y_{n+1}(s) - Y_n(s)\|_H^2 ds \\
\leq 2 \int_0^t \sqrt{K(s)} \|Y_n(s) - Y_{n-1}(s)\|_H \|Y_{n+1}(s) - Y_n(s)\|_H \|f(s)\|_H ds \\
+ \lambda_0 \int_0^t \|Y_{n+1}(s) - Y_n(s)\|_H^2 ds \\
+ \int_0^t \left( \int_X \|G(s, v)\|_{1,H} |g(s, v) - 1| \nu(dv) \right) \|Y_n(s) - Y_{n-1}(s)\|_H \|Y_{n+1}(s) - Y_n(s)\|_H ds \\
\leq C \int_0^t K(s) \|Y_{n+1}(s) - Y_n(s)\|_H^2 ds \\
+ C \int_0^t \|Y_n(s) - Y_{n-1}(s)\|_H^2 \|f(s)\|_H^2 ds \\
+ \lambda_0 \int_0^t \|Y_{n+1}(s) - Y_n(s)\|_H^2 ds \\
+ \int_0^t \left( \int_X \|G(s, v)\|_{1,H} |g(s, v) - 1| \nu(dv) \right) \|Y_n(s) - Y_{n-1}(s)\|_H^2 ds \\
+ \int_0^t \left( \int_X \|G(s, v)\|_{1,H} |g(s, v) - 1| \nu(dv) \right) \|Y_{n+1}(s) - Y_n(s)\|_H^2 ds
\]

We denote \( J(s) = K(s) + \|f(s)\|_H^2 + \int_X \|G(s, v)\|_{1,H} |g(s, v) - 1| \nu(dv) \) and set \( a_n(t) = \|Y_n(t) - Y_{n-1}(t)\|_H^2 \).

The above inequality yields that

\[
a_{n+1}(t) \leq C \int_0^t a_n(s) J(s) ds + C \int_0^t a_{n+1}(s) J(s) ds, \tag{3.20}
\]

and furthermore, we have

\[
a_{n+1}(t) e^{-C \int_0^t J(s) ds} J(t) \leq C e^{-C \int_0^t J(s) ds} J(t) \int_0^t a_n(s) J(s) ds
\]
\[ +Ce^{-C \int_0^t J(s) \, ds} J(t) \int_0^t a_{n+1}(s) J(s) \, ds \]

Set \( A_{n+1}(t) = \int_0^t a_{n+1}(s) J(s) \, ds \). It follows that,
\[
\frac{d}{dt} \left( A_{n+1}(t) e^{-C \int_0^t J(s) \, ds} \right) \leq CJ(t) e^{-C \int_0^t J(s) \, ds} A_n(t).
\]

So that,
\[
A_{n+1}(t) e^{-C \int_0^t J(s) \, ds} \leq C \int_0^t J(s) e^{-C \int_0^u J(s) \, ds} A_n(s) \, ds.
\]

Thus,
\[
A_{n+1}(t) \leq Ce^C \int_0^t J(s) A_n(s) \, ds
\leq Ce^C \int_0^t J(s) J_n(t) \int_0^t J(s) ds
\leq C_T A_n(t).
\]

It follows from (3.20) that
\[
a_{n+1}(t) \leq (C + C_T) \int_0^t a_n(s) J(s) \, ds. \tag{3.21}
\]

Iterating the above inequality, we get
\[
a_{n+1}(t) \leq \frac{(C + C_T)^n \int_0^T J(s) \, ds^n}{n!} \sup_{s \in [0,T]} a_1(s). \tag{3.22}
\]

Therefore, we have
\[
\sum_{n=0}^{\infty} a_{n+1}(t) < \infty.
\]

Hence there exists \( Y \in C([0, T], H) \) such that \( \lim_{n \to \infty} \sup_{s \in [0, T]} ||Y(s) - Y_n(s)||^2_H = 0. \)

On the other hand, by Lemma 3.2 and Lemma 3.3, there exists a unique function \( Y' \in L^2([0, T], V) \cap C([0, T], H) \) such that
\[
\langle Y'(t), \phi \rangle = \langle X_0, \phi \rangle - \int_0^t \langle AY'(s), \phi \rangle ds + \int_0^t \langle \sigma(s, Y(s)) f(s), \phi \rangle ds
+ \int_0^t \int_\Omega \langle G(s, Y(s), v)(g(s, v) - 1), \phi \rangle \nu(dv) ds, \ \phi \in V. \tag{3.23}
\]

Using the same argument leading to (3.22), we have
\[
\lim_{n \to \infty} \sup_{s \in [0, T]} ||Y'(s) - Y_n(s)||^2_H = 0. \tag{3.24}
\]

Hence \( Y' = Y, \ \ t \in [0, T] \) is a solution to (3.17).
We have proved the existence of the solution.

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Uniqueness: Assume $X$ and $X'$ are two solutions of equation (3.17). Then, as the proof of (3.21), we have,

$$\sup_{s \in [0, T]} \|X'(s) - X(s)\|_H^2 \leq (C + C_T) \int_0^T \|X'(s) - X(s)\|_H^2 J(s) \, ds$$

By Gronwall’s inequality, we conclude $X' = X$.

Finally we prove the estimate (3.18). By Lemma 3.2, we have

$$\|\tilde{X}^q_t\|_H^2 + \alpha \int_0^t \|\tilde{X}^q_s\|_V^2 \, ds \leq \|X_0\|_H^2 + 2 \int_0^t \|\sigma(s, \tilde{X}^q_s)\|_{L_2(H)} \|f(s)\|_H \|\tilde{X}^q_s\|_H \, ds + 2 \int_0^t \int_X \|G(s, \tilde{X}^q_s, v)\|_H \|\tilde{X}^q_s\|_H |g(s, v) - 1| \nu(dv) \, ds + \lambda_0 \int_0^t \|\tilde{X}^q_s\|_H^2 \, ds \quad (3.25)$$

By Gronwall’s inequality,

$$\sup_{s \in [0, t]} \|\tilde{X}^q_s\|_H^2$$

$$\leq C \left[ \|X_0\|_H^2 + \int_0^t \int_X \|G(s, v)\|_{L_2(H)} |g(s, v) - 1| \nu(dv) \, ds \right] + \int_0^t \|f(s)\|_H^2 \, ds + \int_0^t \int_X \|G(s, v)\|_{L_2(H)} |g(s, v) - 1| \nu(dv) \, ds \quad (3.27)$$

By Lemma 3.1 (3.25) and (3.27), we obtain (3.18).

We can now present the main large deviations result. Recall that for $q = (f, g) \in S$, $\nu^q_\ell(dsdv) = g(s, v) \nu(dv) \, ds$. Define

$$G^q_\ell(\int_0^t f(s) ds, \nu^q_\ell) = \tilde{X}^q \text{ for } q = (f, g) \in S \text{ as given in Theorem 3.1} \quad (3.28)$$

Let $I : D([0, T], H) \to [0, \infty]$ be defined as in (2.7).

**Theorem 3.2** Suppose that Condition 2.2 and Condition 3.1 hold. Then $I$ is a rate function on $D([0, T], H)$, and the family $\{X^\varepsilon\}_{\varepsilon > 0}$ satisfies a large deviation principle on $D([0, T], H)$ with rate function $I$. 

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The rest of the paper is devoted to the proof of this theorem. According to Theorem 2.4, we need to prove that Condition 2.1 is fulfilled. The verification of Condition 2.1 a) will be given by Proposition 3.3. Condition 2.1 b) will be established in Theorem 3.5 and a number of preparing lemmas.

Let \( T_t, t \geq 0 \) denote the semigroup generated by \(-A\). It is easy to see that \( T_t, t \geq 0 \) are compact operators. For \( f \in L^1([0,T], H) \), denote the operator

\[
Rf(t) = \int_0^t T_{t-s}f(s)ds, \quad t \geq 0,
\]

which is the mild solution of the equation:

\[
Z(t) = -\int_0^t A[Z](s)ds + \int_0^t f(s)ds.
\]

The proof of the following lemma was given in [18].

**Lemma 3.4** If \( \mathcal{D} \subset L^1([0,T], H) \) is uniformly integrable, then \( \mathcal{Y} = R(\mathcal{D}) \) is relatively compact in \( C([0,T], H) \).

We also need the following lemma, the proof of which can be found in [6].

**Lemma 3.5** Let \( h : [0,T] \times X \to \mathbb{R} \) be a measurable function such that

\[
\int_{X_T} |h(s,v)|^2 \nu(dv)ds < \infty,
\]

and for all \( \delta \in (0,\infty) \)

\[
\int_E \exp(\delta|h(s,v)|)\nu(dv)ds < \infty,
\]

for all \( E \in \mathcal{B}([0,T] \times X) \) satisfying \( \nu_T(E) < \infty \).

a). Fix \( N \in \mathbb{N} \), and let \( g_n, g \in S^N \) be such that \( g_n \to g \) as \( n \to \infty \). Then

\[
\lim_{n \to \infty} \int_{X_T} h(s,v)(g_n(s,v) - 1)\nu(dv)ds = \int_{X_T} h(s,v)(g(s,v) - 1)\nu(dv)ds;
\]

b). Fix \( N \in \mathbb{N} \). Given \( \epsilon > 0 \), there exists a compact set \( K_\epsilon \subset X \), such that

\[
\sup_{g \in S^N} \int_{[0,T]} \int_{K_\epsilon} |h(s,v)||g(s,v) - 1|\nu(dv)ds \leq \epsilon.
\]

We now proceed to verify the first part of Condition 2.1. Recall the map \( \mathcal{G}^0 \) defined by (3.28).

**Proposition 3.3** Fix \( N \in \mathbb{N} \), and let \( q_n = (f_n, g_n), q = (f, g) \in \bar{S}^N \) be such that \( q_n \to q \) as \( n \to \infty \). Then

\[
\mathcal{G}^0(\int_0^t f_n(s)ds, \nu_T^{2n}) \to \mathcal{G}^0(\int_0^t f(s)ds, \nu_T^2) \quad \text{in} \quad C([0,T], H).
\]
Proof:
Firstly, we prove that $\{G^0(\int_0^t f_n(s)ds, \nu^{2n}_T)\}_{n \in \mathbb{N}}$ is relatively compact in $C([0, T], H)$.
By Theorem 3.1 and the relation between mild solution and weak solution,

$$G^0(\int_0^t f_n(s)ds, \nu^{2n}_T)(t) = T(t)X_0 + \int_0^t T(t-s)\left[\sigma(s, \tilde{X}^{q_n}(s))f_n(s) + \int_{\mathbb{X}} G(s, \tilde{X}^{q_n}(s), v)(g_n(s, v) - 1)\nu(dv)\right]ds.$$ (3.29)

By Lemma 3.4, it is sufficient to prove that

$$D = \{\sigma(\cdot, \tilde{X}^{q_n}(\cdot))f_n(\cdot) + \int_{\mathbb{X}} G(\cdot, \tilde{X}^{q_n}(\cdot), v)(g_n(\cdot, v) - 1)\nu(dv)\} \subset L^1([0, T], H)$$

is uniformly integrable.

We know that $D$ is uniformly integrable in $L^1([0, T], H)$ iff

(I) There exists a finite constant $\tilde{K}$ such that $\int_0^T \|h(s)\|_H ds \leq \tilde{K}$, for every $h \in D$;

(II) For every $\eta > 0$ there exists $\delta > 0$ such that, for every measurable subset $A \subset [0, T]$ with $\lambda_T(A) \leq \delta$ and every $h \in D$, $\int_A \|h(s)\|_H ds \leq \eta$.

In fact (I) follows from Lemma 3.5 and Theorem 3.1. We need to check (II). For any $n \in \mathbb{N}$ and any measurable subset $A \subset [0, T]$,

$$\int_A \left\| \int_{\mathbb{X}} G(s, \tilde{X}^{q_n}(s), v)(g_n(s, v) - 1)\nu(dv) \right\|_H ds$$

$$\leq \int_A \int_{\mathbb{X}} \|G(s, \tilde{X}^{q_n}(s), v)\|_H |g_n(s, v) - 1|\nu(dv) ds$$

$$\leq \int_A \int_{\mathbb{X}} \|G(s, \tilde{X}^{q_n}(s), v)\|_H (1 + \|\tilde{X}^{q_n}(s)\|_H)|g_n(s, v) - 1|\nu(dv) ds$$

$$\leq \left(1 + \sup_{s \in [0, T]} \|\tilde{X}^{q_n}(s)\|_H \right) \int_A \int_{\mathbb{X}} \|G(s, v)\|_{0, H} |g_n(s, v) - 1|\nu(dv) ds.$$

Given $\epsilon > 0$, by Lemma 3.5 we can find a compact subset $K_\epsilon \subset \mathbb{X}$ such that

$$\int_A \int_{K_\epsilon} \|G(s, v)\|_{0, H} |g_n(s, v) - 1|\nu(dv) ds \leq \epsilon, \ \forall n \geq 1. \quad (3.30)$$

On the other hand, by (3.14) for any $L > 0$, we have

$$\int_A \int_{K_\epsilon} \|G(s, v)\|_{0, H} |g_n(s, v) - 1|\nu(dv) ds$$

$$\leq C(L) \int_A \int_{K_\epsilon} \exp(L\|G(s, v)\|_{0, H})\nu(dv) ds + \frac{1}{L} \int_0^T \int_{\mathbb{X}} l(g_n(s, v))\nu(dv) ds$$

$$+ \int_A \int_{K_\epsilon} \exp(\|G(s, v)\|_{0, H})\nu(dv) ds. \quad (3.31)$$

We also have

$$\int_A \|\sigma(s, \tilde{X}^{q_n}(s))f_n(s)\|_H ds$$
\[ \leq \int_A \| \sigma(s, \tilde{X}^{q_n}(s))\|_{L^2(H)} \| f_n(s)\|_H ds \]

\[ \leq \int_A \sqrt{K(s)} \sqrt{\| \tilde{X}^{q_n}(s)\|_H^2 + 1} \| f_n(s)\|_H ds \]

\[ \leq \sup_{s \in [0,T]} \| \tilde{X}^{q_n}(s)\|_H^2 + 1 \times \left[ (\int_A K(s) ds)(\int_0^T \| f_n(s)\|_H^2 ds) \right]^{1/2} \]

\[ \leq [ \int_A K(s) ds]^{1/2} \times (1 + C_N)^{1/2} N^{1/2}, \] (3.32)

where \( \sup_{s \in [0,T]} \| \tilde{X}^{q_n}(s)\|_H^2 \leq C_N \) and \( \int_0^T \| f_n(s)\|_H^2 ds \leq N \).

Now for any \( \eta > 0 \), first choose \( \epsilon > 0 \) such that \( (1 + C_N)\epsilon \leq \eta/5 \), then select \( L > 0 \) so that \( (1 + C_N)L/N \leq \eta/5 \). Finally since \( \nu_T([0,T] \times K_\nu) = T \nu(K_\nu) < \infty \), there exists \( \delta > 0 \) such that for every measurable subset \( A \subset [0,T] \) satisfying \( \lambda_T(A) \leq \delta \), we have

\[ (1 + C_N)C(L) \int_A \int_{K_\nu} \exp(L\| G(s,v)\|_{0,H})\nu(dv)ds \leq \eta/5, \]

\[ (1 + C_N) \int_A \int_{K_\nu} \exp(\| G(s,v)\|_{0,H})\nu(dv)ds \leq \eta/5, \]

and

\[ [ \int_A K(s) ds]^{1/2} \times C_N^{1/2} N^{1/2} \leq \eta/5. \]

Combining all these inequalities gives (II).

Let \( \tilde{X} \) be any limit point of the sequence \( \{ \tilde{X}^{q_n}, n \geq 1 \} \). Now we will prove that \( \tilde{X} = \tilde{X}^q \).

Without loss of generality, we assume the whole sequence \( \{ \tilde{X}^{q_n} \} \) converges.

An application of dominated convergence theorem shows that, along the convergent subsequence,

\[ \int_0^t \langle \tilde{X}^{q_n}(s), A^*\phi \rangle ds \rightarrow \int_0^t \langle \tilde{X}(s), A^*\phi \rangle ds, \ \forall \phi \in H_{A^*}, \] (3.33)

as \( n \rightarrow \infty \). Furthermore, using the convergence of \( \tilde{X}^{q_n} \) to \( \tilde{X} \), and Lemma 3.1, we have that

\[ \int_0^t \int_\mathcal{X} \langle G(s, \tilde{X}^{q_n}(s), v), \phi(g_n(s,v) - 1)\nu(dv)ds \]

\[ - \int_0^t \int_\mathcal{X} \langle G(s, \tilde{X}(s), v), \phi(g_n(s,v) - 1)\nu(dv)ds \rightarrow 0, \ \forall \phi \in V. \] (3.34)

Also, since \( \tilde{X} \in C([0,T], H) \), we have for some \( \kappa \in (0, \infty) \)

\[ | \langle G(s, \tilde{X}(s), v), \phi \rangle | \leq \kappa \| \langle G(s, v), \phi \rangle \|_{0,H}, \ \forall \phi \in V, \ \forall (s,v) \in \mathcal{X}_T. \]

Combining this with Condition 2.2 and Lemma 3.5 we have, as \( n \rightarrow \infty \),

\[ \int_0^t \int_\mathcal{X} \langle G(s, \tilde{X}(s), v), \phi(g_n(s,v) - 1)\nu(dv)ds \]

\[ \rightarrow \int_0^t \int_\mathcal{X} \langle G(s, \tilde{X}(s), v), \phi(g(s,v) - 1)\nu(dv)ds, \ \forall \phi \in V. \] (3.35)
We also have, for every $\phi \in V$,
\[
\left| \int_0^t \langle \sigma(s, \widetilde{X}^q(s)) f_n(s), \phi \rangle ds - \int_0^t \langle \sigma(s, \widetilde{X}(s)) f(s), \phi \rangle ds \right|
\leq \|\phi\|_H \left[ \int_0^t \|\sigma(s, \widetilde{X}^q(s)) - \sigma(s, \widetilde{X}(s))\|_{L^2(H)} \|f_n(s)\|_H ds 
+ \int_0^t \|\sigma(s, \widetilde{X}(s))\|_{L^2(H)} \|f_n(s) - f(s)\|_H ds \right]
\leq \|\phi\|_H \left[ \int_0^t \sqrt{K(s)} \|\widetilde{X}^q(s) - \widetilde{X}(s)\|_H \|f_n(s)\|_H ds 
+ \int_0^t \sqrt{K(s)} \|\widetilde{X}(s)\|^2_H + 1 \|f_n(s) - f(s)\|_H^2 ds \right]
\leq \|\phi\|_H \left[ \sup_{s \in [0,T]} \|\widetilde{X}^q(s) - \widetilde{X}(s)\|_H \times \left( \int_0^T K(s) ds + \int_0^T \|f_n(s)\|^2_H ds \right) 
+ \sqrt{\sup_{s \in [0,T]} \|\widetilde{X}(s)\|^2_H + 1} \times \left( \int_0^T K(s) ds \right)^{1/2} \left( \int_0^T \|f_n(s) - f(s)\|^2_H ds \right)^{1/2} \right]
\to 0, \text{ as } n \to \infty.
\]
(3.36)

Combining (3.33), (3.34), (3.35) and (3.36), we see that $\widetilde{X}$ must satisfy
\[
\langle \widetilde{X}_t, \phi \rangle = \langle X_0, \phi \rangle - \int_0^t \langle A\widetilde{X}_s, \phi \rangle ds + \int_0^t \langle \sigma(s, \widetilde{X}(s)) f(s), \phi \rangle ds 
+ \int_0^t \int_X \langle G(s, \widetilde{X}, v), \phi \rangle (g(s, v) - 1) \nu(dv) ds, \forall \phi \in H_{\mathcal{A}^*}.
\]
(3.37)

Since $H_{\mathcal{A}^*}$ is dense in $V$, we have $\widetilde{X} = \widetilde{X}^q$, completing the proof. \hfill \blacksquare

**Remark 2** Fix $N \in \mathbb{N}$. By the proof of (3.30), it is easy to see that, for every $\eta > 0$, there exists $\delta > 0$ such that for any $A \subset [0,T]$ satisfying $\lambda_T(A) < \delta$

\[
\sup_{g \in S^N} \int_A \int_X \|G(s, v)\|_{0,H} |g(s, v) - 1| \nu(dv) ds \leq \eta.
\]
(3.38)

We now verify the second part of Condition 2.1 The next theorem can be proved similarly as in Section 3 in [18].

**Theorem 3.4** Under Condition 2.2 if $X_0 \in H$, there exists a unique $H$-valued progressively measurable process $(X^\epsilon_t)$ such that, $X^\epsilon_t \in L^2(0,T;V) \cap D(0,T;H)$ for any $T > 0$ and

\[
X^\epsilon_t = X^\epsilon_0 - \int_0^t AX^\epsilon_s ds + \sqrt{\epsilon} \int_0^t \sigma(s, X^\epsilon_s) d\beta(s) + \epsilon \int_0^t \int_X G(s, X^\epsilon_s, v) \tilde{N}^\epsilon^{-1}(dsdv), \text{ a.s..} (3.39)
\]

It follows from this theorem that, for every $\epsilon > 0$, there exists a measurable map $G^\epsilon: \mathbb{V} \rightarrow D([0,T];H)$ such that, for any Poisson random measure $\tilde{N}^\epsilon$ on $[0,T] \times \mathbb{X}$ with mean measure $\epsilon^{-1} \lambda_T \times v$ given on some probability space, $G^\epsilon(\sqrt{\epsilon} \beta, \epsilon n^\epsilon)$ is the unique solution of (3.39) with $\tilde{N}^\epsilon$ replaced by $\tilde{n}^\epsilon$.

Let $\phi_\epsilon = (\psi_\epsilon, \varphi_\epsilon) \in \mathcal{U}^N$ and $\phi_\epsilon = \frac{1}{\varphi_\epsilon} \in \tilde{\mathcal{U}}^N$. The following lemma follows from Lemma 2.3 in [5].
Lemma 3.6

\[ \mathcal{E}_t^\epsilon(\phi) := \exp \left\{ \int_{[0,t] \times [0,\epsilon^{-1}]} \log(\phi(s,x)) \bar{N}(ds \, dx \, dr) + \int_{[0,t] \times [0,\epsilon^{-1}]} (\phi(s,x) + 1)\bar{\nu}_T(ds \, dx \, dr) \right\} \]

and

\[ \mathcal{E}_t^\epsilon(\varphi) := \exp \left\{ \frac{1}{\sqrt{\epsilon}} \int_0^t \varphi(s) \, d\beta(s) - \frac{1}{2\epsilon} \int_0^t \|\varphi(s)\|^2 \, ds \right\} \]

are \{\mathcal{F}_t\} - martingales. Set

\[ \mathcal{E}_t^\epsilon(\psi, \phi) := \mathcal{E}_t^\epsilon(\psi) \mathcal{E}_t^\epsilon(\phi) \]

then

\[ \mathbb{Q}_t^\epsilon(G) = \int_G \mathcal{E}_t^\epsilon(\psi, \phi) \, d\bar{\mathbb{P}}, \quad \text{for} \ G \in \mathcal{B}(\bar{\mathbb{V}}) \]

defines a probability measure on \( \bar{\mathbb{V}} \).

By the fact that \( \epsilon N^{\epsilon^{-1} \varphi} \) under \( \mathbb{Q}_t^\epsilon \) has the same law as that of \( \epsilon N^{\epsilon^{-1} \varphi} \) under \( \bar{\mathbb{P}} \), we know that \( \bar{X}^\epsilon = \mathcal{G}(\sqrt{\epsilon} \beta + \int_0^t \psi(s) \, ds, \epsilon N^{\epsilon^{-1} \varphi} \) is the unique solution of the following controlled stochastic differential equation:

\[
\begin{align*}
\bar{X}^\epsilon_t &= X_0 - \int_0^t A\bar{X}^\epsilon_s ds + \int_0^t \sigma(s, \bar{X}^\epsilon_s) \varphi(s) ds + \sqrt{\epsilon} \int_0^t \sigma(s, X^\epsilon_s) d\beta(s) \\
&\quad + \int_0^t \int_{\mathbb{X}} \mathcal{G}(s, \bar{X}^\epsilon_{s-}, v) \left( \epsilon N^{\epsilon^{-1} \varphi}(dsdv) - \nu(dv)ds \right) \\
&= X_0 - \int_0^t A\bar{X}^\epsilon_s ds + \int_0^t \sigma(s, \bar{X}^\epsilon_s) \varphi(s) ds + \sqrt{\epsilon} \int_0^t \sigma(s, X^\epsilon_s) d\beta(s) \\
&\quad + \int_0^t \int_{\mathbb{X}} \mathcal{G}(s, \bar{X}^\epsilon_{s-}, v) (\varphi(s,v) - 1)\nu(dv)ds \\
&\quad + \int_0^t \int_{\mathbb{X}} \epsilon \mathcal{G}(s, \bar{X}^\epsilon_{s-}, v) \left( N^{\epsilon^{-1} \varphi}(dsdv) - \epsilon^{-1} \varphi(s,v)\nu(dv)ds \right) \\
&= (3.40)
\end{align*}
\]

The following estimates will be used later.

Lemma 3.7 There exists \( \epsilon_0 > 0 \), such that,

\[
\sup_{0 < \epsilon \leq \epsilon_0} \mathbb{E} \sup_{0 \leq t \leq T} \|\bar{X}^\epsilon_t\|_H^2 < \infty. \quad (3.41)
\]

Proof: By Ito’s formula,

\[
\begin{align*}
\|\bar{X}^\epsilon_t\|_H^2 &= \|X_0\|_H^2 - 2 \int_0^t \langle \bar{X}^\epsilon_s, A^\epsilon \bar{X}^\epsilon_s \rangle ds + 2 \int_0^t \langle \bar{X}^\epsilon_s, \sigma(s, \bar{X}^\epsilon_s) \psi(s) \rangle ds + 2\sqrt{\epsilon} \int_0^t \sigma(s, \bar{X}^\epsilon_s) \bar{X}^\epsilon_s d\beta_s \\
&\quad + 2 \int_0^t \int_{\mathbb{X}} \langle \bar{X}^\epsilon_s, \mathcal{G}(s, \bar{X}^\epsilon_{s-}, v) \rangle \nu(dv)ds \\
&\quad + \int_0^t \int_{\mathbb{X}} \left( 2 \epsilon \mathcal{G}(s, \bar{X}^\epsilon_{s-}, v), \bar{X}^\epsilon_s \rangle + \|\epsilon \mathcal{G}(s, \bar{X}^\epsilon_{s-}, v)\|_H^2 \right) \left( N^{\epsilon^{-1} \varphi}(dsdv) - \epsilon^{-1} \varphi(s,v)\nu(dv)ds \right)
\end{align*}
\]

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\[ + \epsilon \int_0^t \int_{\mathcal{X}} \|G(s, \hat{X}_s^t, v)\|_{H}^2 \varphi_{\epsilon}(s, v) \nu(dv) ds + \epsilon \int_0^t \|\sigma(s, \hat{X}_s^t)\|_{L^2(H)}^2 ds. \]  

(3.42)

The third term on right hand side of last equation is estimated as follows.

\[ 2 \int_0^t \langle \hat{X}_s^t, \sigma(s, \hat{X}_s^t) \psi(s) \rangle ds \leq 2 \int_0^t \|\hat{X}_s^t\|_{H} \|\sigma(s, \hat{X}_s^t)\|_{L^2(H)} \|\psi(s)\|_{H} ds \]
\[ \leq \int_0^t \|\hat{X}_s^t\|_{H}^2 \|\psi(s)\|_{H}^2 ds + \int_0^t K(s)(1 + \|\hat{X}_s^t\|_{H}^2) ds \]
\[ \leq \int_0^t \|\hat{X}_s^t\|_{H}^2 (\|\psi(s)\|_{H}^2 + K(s)) ds + \int_0^t K(s) ds. \]  

(3.43)

Denote the forth term on the right hand side of equation (3.42) by \( W_i \). Then we have

\[ E[\sup_{0 \leq s \leq T} |W_s|] \leq 4E\sqrt[4]{\tau} \int_0^T |\hat{X}_s^t|_{H} \left(\int_0^T \|\sigma(s, \hat{X}_s^t)\|_{L^2(H)}^2 ds \right) \]
\[ \leq 4\sqrt{\tau}E\left[\sup_{0 \leq s \leq T} |\hat{X}_s^t|_{H} \cdot \int_0^T \|\sigma(s, \hat{X}_s^t)\|_{L^2(H)}^2 ds \right] \]
\[ \leq 4\sqrt{\tau}E\left[\sup_{0 \leq s \leq T} |\hat{X}_s^t|_{H}^2 + 4\sqrt{\tau}E\int_0^T \|\sigma(s, \hat{X}_s^t)\|_{L^2(H)}^2 ds \right] \]
\[ \leq 4\sqrt{\tau}E\left[\sup_{0 \leq s \leq T} |\hat{X}_s^t|_{H}^2 + 4\sqrt{\tau}E\int_0^T K(s)(1 + \|\hat{X}_s^t\|_{H}^2) ds \right] \]
\[ \leq 4\sqrt{\tau}(1 + \int_0^T K(s) ds) E[\sup_{0 \leq s \leq T} |\hat{X}_s^t|_{H}^2] + 4\sqrt{\tau}E\int_0^T K(s) ds. \]  

(3.44)

The fifth term on the right hand side of equation (3.42) has the following bound.

\[ 2 \int_0^t \int_{\mathcal{X}} \langle \hat{X}_s^t, G(s, \hat{X}_s^t, v) \rangle > (\varphi_{\epsilon}(s, v) - 1) \nu(dv) ds \]
\[ \leq 2 \int_0^t \int_{\mathcal{X}} \|\hat{X}_s^t\|_{H} \|G(s, \hat{X}_s^t, v)\|_{H} |\varphi_{\epsilon}(s, v) - 1| \nu(dv) ds \]
\[ \leq 2 \int_0^t \int_{\mathcal{X}} \|G(s, v)\|_{0,H}(1 + \|\hat{X}_s^t\|_{H}) \|\hat{X}_s^t\|_{H} |\varphi_{\epsilon}(s, v) - 1| \nu(dv) ds \]
\[ \leq 2 \int_0^t \int_{\mathcal{X}} \|G(s, v)\|_{0,H}(1 + 2\|\hat{X}_s^t\|_{H}^2) |\varphi_{\epsilon}(s, v) - 1| \nu(dv) ds \]
\[ \leq 2C_{0,1}^N + 4 \int_0^t \int_{\mathcal{X}} \|G(s, v)\|_{0,H} \|\hat{X}_s^t\|_{H}^2 |\varphi_{\epsilon}(s, v) - 1| \nu(dv) ds, \]  

(3.45)

where \( C_{0,1}^N \) is the constant from Lemma 3.1.

The seventh term in (3.42) is bounded by,

\[ \epsilon \int_0^t \int_{\mathcal{X}} \|G(s, \hat{X}_s^t, v)\|_{H}^2 \varphi_{\epsilon}(s, v) \nu(dv) ds \]
\[ \leq 2\epsilon \int_0^t \int_{\mathcal{X}} \|G(s, v)\|_{0,H}^2(1 + \|\hat{X}_s^t\|_{H}^2) \varphi_{\epsilon}(s, v) \nu(dv) ds \]

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where constant $C^N_{0.2}$ was defined in Lemma 3.1.

The last term in (3.42) is bounded by,

\[
\epsilon \int_0^t \|\sigma(s, \tilde{X}_s^\epsilon)|_{L_2(H)}^2 \, ds \leq \epsilon \int_0^t K(s) (1 + \|\tilde{X}_s^\epsilon\|^2_H) \, ds \\
\leq \epsilon \int_0^t \|\tilde{X}_s^\epsilon\|^2_H K(s) \, ds + \epsilon \int_0^t K(s) \, ds. \tag{3.47}
\]

Set

\[
M_t = \int_0^t \int_X <2\epsilon G(s, \tilde{X}_{s-}^\epsilon, v), \tilde{X}_s^\epsilon > \left( N^{1/\nu}(dsdv) - \epsilon^{-1} \varphi_{\epsilon}(s, v)\nu(dv)ds \right)
\]

and

\[
K_t = \int_0^t \int_X \|\epsilon G(s, \tilde{X}_s^\epsilon, v)\|^2_H \left( N^{1/\nu}(dsdv) - \epsilon^{-1} \varphi_{\epsilon}(s, v)\nu(dv)ds \right).
\]

We have

\[
\mathbb{E}[ \sup_{0 \leq t \leq T} |K_t| ] \leq \mathbb{E}[ \sup_{0 \leq t \leq T} \int_0^t \int_X \|\epsilon G(s, \tilde{X}_{s-}^\epsilon, v)\|^2_H N^{1/\nu}(dsdv) ] \\
+ \epsilon \mathbb{E}[ \int_0^T \int_X \|\epsilon G(s, \tilde{X}_s^\epsilon, v)\|^2_H \varphi_{\epsilon}(s, v)\nu(dv)ds ] \\
\leq 2\epsilon \mathbb{E}[ \int_0^T \int_X \|G(s, \tilde{X}_s^\epsilon, v)\|^2_H \varphi_{\epsilon}(s, v)\nu(dv)ds ] \\
\leq 4\epsilon \mathbb{E}[ \int_0^T \int_X \|G(s, v)\|^2_H (1 + \|\tilde{X}_s^\epsilon\|^2_H) \varphi_{\epsilon}(s, v)\nu(dv)ds ] \\
\leq 4\epsilon C^N_{0.2} (1 + \mathbb{E}[ \sup_{0 \leq t \leq T} \|\tilde{X}_s^\epsilon\|^2_H ]). \tag{3.48}
\]

For the martingale $M_t$, we have

\[
\mathbb{E}[ \sup_{0 \leq t \leq T} |M_t| ] \leq 4\mathbb{E}\sqrt{[M]_T} \\
\leq 4\mathbb{E} \left\{ \int_0^T \int_X \left( N^{1/\nu}(dsdv) - \epsilon^{-1} \varphi_{\epsilon}(s, v)\nu(dv)ds \right) \right\}^{\frac{1}{2}} \\
\leq 8\epsilon \mathbb{E} \left\{ \int_0^T \int_X \|G(s, \tilde{X}_{s-}^\epsilon, v)\|^2_H \|\tilde{X}_s^\epsilon\|^2_H N^{1/\nu}(dsdv) \right\}^{\frac{1}{2}} \\
\leq 8\epsilon \mathbb{E} (\sup_{0 \leq t \leq T} \|\tilde{X}_s^\epsilon\|^2_H) \left\{ \int_0^T \int_X \|G(s, \tilde{X}_{s-}^\epsilon, v)\|^2_H N^{1/\nu}(dsdv) \right\}^{\frac{1}{2}} \\
\leq \frac{1}{C} \mathbb{E} (\sup_{0 \leq t \leq T} \|\tilde{X}_s^\epsilon\|^2_H) + 16\epsilon^2 C \mathbb{E} \int_0^T \int_X \|G(s, \tilde{X}_{s-}^\epsilon, v)\|^2_H N^{1/\nu}(dsdv) ] \\
= \frac{1}{C} \mathbb{E} (\sup_{0 \leq t \leq T} \|\tilde{X}_s^\epsilon\|^2_H) + 16\epsilon^2 C \mathbb{E} \left[ \int_0^T \int_X \|G(s, \tilde{X}_{s-}^\epsilon, v)\|^2_H \varphi_{\epsilon}(s, v)\nu(dv)ds \right] \\
\leq \frac{1}{C} \mathbb{E} (\sup_{0 \leq t \leq T} \|\tilde{X}_s^\epsilon\|^2_H) + 32\epsilon C C^N_{0.2} (1 + \mathbb{E}[ \sup_{0 \leq t \leq T} \|\tilde{X}_s^\epsilon\|^2_H ]) \\
\]
Lemma 3.8 There exists $\epsilon_0 > 0$, such that, for any $t_0 \in [0, T)$, $0 < \epsilon < \epsilon_0$,

\[
\left(\frac{1}{2} - 4\epsilon^{1/2}\right)\mathbb{E}\left[ \sum_{0 \leq t \leq t_0} \mathbb{E}\left[ \sup_{0 \leq t \leq T} \left\| \tilde{X}_t^\epsilon \right\|_H^2 \right] \right] \\
\leq \sum_{i=k}^{\infty} \langle \tilde{X}_0^\epsilon, e_i \rangle^2 + (8N + 129\epsilon) \int_0^{t_0} K(s)ds \mathbb{E}\left[ \left(1 + \sup_{0 \leq t \leq t_0} \left\| \tilde{X}_t^\epsilon \right\|_H \right)^2 \right] \\
+ 4\mathbb{E}[ (1 + \sup_{0 \leq t \leq t_0} \left\| \tilde{X}_t^\epsilon \right\|_H^2 ) \cdot \sup_{g \in \mathcal{S}^N} \left( \int_0^{t_0} \int_X ||G(s,v)||_{0,H} |g(s,v) - 1| \nu(dv)ds \right)^2 ] \\
+ (4\epsilon^{1/2} + 2\epsilon)\mathbb{E}[ (1 + \sup_{0 \leq t \leq t_0} \left\| \tilde{X}_t^\epsilon \right\|_H^2 ) \cdot \sup_{g \in \mathcal{S}^N} \int_0^{t_0} \int_X ||G(s,v)||_{0,H}^2 g(s,v) \nu(dv)ds ].
\]
Proof: Recall that \( \{e_k, \ k \geq 1\} \) is an orthonormal basis of the Hilbert space \( H \). For convenience, let \( Y_i^\epsilon = \langle \hat{X}_i^\epsilon, e_i \rangle \). Then

\[
Y_i^\epsilon(t) = \langle \hat{X}_i^\epsilon, e_i \rangle = < X_0, e_i > - \zeta_i \int_0^t Y_i^\epsilon(s)ds + \int_0^t \langle \sigma(s, \hat{X}_i^\epsilon)\psi_i(s), e_i \rangle ds + \sqrt{\epsilon} \int_0^t \sigma(s, \hat{X}_i^\epsilon)d\beta(s), e_i > + \int_0^t \int_X < G(s, \hat{X}_i^\epsilon, v), e_i > (\varphi_\epsilon(s, v) - 1)\nu(dv)ds \\
+ \int_0^t \int_X < \epsilon G(s, \hat{X}_i^\epsilon, v), e_i > \hat{N}^{-1}\varphi_\epsilon(dsdv).
\]

By Ito’s formula,

\[
|Y_i^\epsilon(t)|^2 = |< X_0, e_i > |^2 - 2\zeta_i \int_0^t |Y_i^\epsilon(s)|^2 ds + 2 \int_0^t Y_i^\epsilon(s)\langle \sigma(s, \hat{X}_i^\epsilon)\psi_i(s), e_i \rangle ds \\
+ 2\sqrt{\epsilon} \int_0^t Y_i^\epsilon(s)\sigma(s, \hat{X}_i^\epsilon)d\beta(s), e_i > + \epsilon \int_0^t \| \sigma^*(s, \hat{X}_i^\epsilon) e_i \|^2_H ds \\
+ 2 \int_0^t \int_X Y_i^\epsilon(s) < G(s, \hat{X}_i^\epsilon, v), e_i > (\varphi_\epsilon(s, v) - 1)\nu(dv)ds \\
+ \int_0^t \int_X < 2\epsilon G(s, \hat{X}_i^\epsilon, v), Y_i^\epsilon(s-)e_i > + |\epsilon < G(s, \hat{X}_i^\epsilon, v), e_i > |^2 \hat{N}^{-1}\varphi_\epsilon(dsdv) \\
+ \epsilon \int_0^t \int_X | < G(s, \hat{X}_i^\epsilon, v), e_i > |^2 \varphi_\epsilon(s, v)\nu(dv)ds. \tag{3.51}
\]

Therefore, for \( t_0 > 0 \), we obtain

\[
\sup_{0 \leq t \leq t_0} \sum_{i=k}^\infty |Y_i^\epsilon(t)|^2 \\
\leq \sum_{i=k}^\infty | < X_0, e_i > |^2 + 2 \int_0^{t_0} \| \sigma(s, \hat{X}_i^\epsilon) \|_{L_2(H)} \| \psi_i(s) \|_H \| \sum_{i=k}^\infty Y_i^\epsilon(s) e_i \|_H ds \\
+ 2\sqrt{\epsilon} \sup_{0 \leq t \leq t_0} \sum_{i=k}^\infty \langle \int_0^t Y_i^\epsilon(s)\sigma(s, \hat{X}_i^\epsilon)d\beta(s), e_i > + \epsilon \int_0^{t_0} \sum_{i=k}^\infty \| \sigma^*(s, \hat{X}_i^\epsilon) e_i \|^2_H ds \\
+ 2 \int_0^{t_0} \int_X | < G(s, \hat{X}_i^\epsilon, v), \sum_{i=k}^\infty Y_i^\epsilon(s)e_i > (\varphi_\epsilon(s, v) - 1)\nu(dv)ds \\
+ 2 \sup_{0 \leq t \leq t_0} \int_0^t \int_X | < \epsilon G(s, \hat{X}_i^\epsilon, v), \sum_{i=k}^\infty Y_i^\epsilon(s-)e_i > \hat{N}^{-1}\varphi_\epsilon(dsdv) \\
+ 2 \int_0^{t_0} \int_X \| \epsilon G(s, \hat{X}_i^\epsilon, v) \|^2_H \hat{N}^{-1}\varphi_\epsilon(dsdv). \tag{3.52}
\]

Firstly, we estimate the second term on the right hand side of the above inequality.

\[
2E[ \int_0^{t_0} \| \sigma(s, \hat{X}_i^\epsilon) \|_{L_2(H)} \| \psi_i(s) \|_H \| \sum_{i=k}^\infty Y_i^\epsilon(s)e_i \|_H ds ] \\
\leq \frac{1}{8N}E[ \int_0^{t_0} \| \psi_i(s) \|_H^2 \| \sum_{i=k}^\infty Y_i^\epsilon(s)e_i \|_H^2 ds ] + 8NE[ \int_0^{t_0} K(s)(1 + \| \hat{X}_i^\epsilon \|_H) ds ]
\]
\[ \leq \frac{1}{8} E \left[ \sup_{0 \leq t \leq T} \sum_{i=k}^{\infty} |Y_i^*(t)|^2 \right] + 8N \left( \int_0^T K(s) ds \right) E \left[ (1 + \sup_{0 \leq t \leq T} \| \tilde{X}_t^* \|_H)^2 \right]. \quad (3.53) \]

The third term is bounded by,

\[ \begin{align*}
2\sqrt{\epsilon} E \left[ \sup_{0 \leq t \leq T} \sum_{i=k}^{\infty} \left\langle \int_0^t Y_i^*(s) \sigma(s, \tilde{X}_s^*) d\beta(s), e_i \right\rangle \right] \\
\leq 8\sqrt{\epsilon} E \left[ \int_0^T \| \sigma(s, \tilde{X}_s^*) \|_{L_2(H)}^2 \right] \sum_{i=k}^{\infty} |Y_i^*(t)|^2 ds \\
\leq 8\sqrt{\epsilon} E \left[ \left( \sup_{0 \leq t \leq T} \sum_{i=k}^{\infty} |Y_i^*(t)|^2 \right) + 128\epsilon \sum_{i=k}^{\infty} |Y_i^*(t)|^2 \right] \int_0^T \| \sigma(s, \tilde{X}_s^*) \|_{L_2(H)}^2 ds \\
\leq \frac{1}{8} E \left[ \sup_{0 \leq t \leq T} \sum_{i=k}^{\infty} |Y_i^*(t)|^2 \right] + 128\epsilon \left( \int_0^T K(s) ds \right) E \left[ (1 + \sup_{0 \leq t \leq T} \| \tilde{X}_t^* \|_H)^2 \right]. \quad (3.54) \end{align*} \]

The fourth term is estimated as follows,

\[ \begin{align*}
\epsilon E \left[ \int_0^T \sum_{i=k}^{\infty} \| \sigma^*(s, \tilde{X}_s^*) e_i \|_H^2 ds \right] \\
\leq \epsilon E \left[ \int_0^T \| \sigma(s, \tilde{X}_s^*) \|_{L_2(H)}^2 ds \right] \\
\leq \epsilon \left( \int_0^T K(s) ds \right) E \left[ (1 + \sup_{0 \leq t \leq T} \| \tilde{X}_t^* \|_H)^2 \right]. \quad (3.55) \end{align*} \]

The fifth term is bounded by,

\[ \begin{align*}
E \left[ \int_0^T \int_X | G(s, \tilde{X}_s^*, v) \sum_{i=k}^{\infty} Y_i^*(s) e_i | - | \varphi(s, v) - 1 | \nu dv ds \right] \\
\leq E \left[ \int_0^T \int_X \| G(s, \tilde{X}_s^*, v) \|_H (\sum_{i=k}^{\infty} |Y_i^*(s)|^2)^{\frac{1}{2}} | \varphi(s, v) - 1 | \nu dv ds \right] \\
\leq E \left[ \sup_{0 \leq t \leq T} (\sum_{i=k}^{\infty} |Y_i^*(s)|^2)^{\frac{1}{2}} \right] \int_0^T \int_X \| G(s, \tilde{X}_s^*, v) \|_H | \varphi(s, v) - 1 | \nu dv ds \right] \\
\leq \frac{1}{8} E \left[ \sup_{0 \leq t \leq T} (\sum_{i=k}^{\infty} |Y_i^*(s)|^2)^{\frac{1}{2}} \right] + 2E \left[ \left( \int_0^T \int_X \| G(s, \tilde{X}_s^*, v) \|_H | \varphi(s, v) - 1 | \nu dv ds \right)^2 \right] \\
\leq \frac{1}{8} E \left[ \sup_{0 \leq t \leq T} \sum_{i=k}^{\infty} |Y_i^*(s)|^2 \right] \\
+ \left( 1 + \sup_{0 \leq t \leq T} \| \tilde{X}_t^* \|^2 \right) \sup_{g \in S^N} \left( \int_0^T \int_X \| G(s, v) \|_{0, H} | g(s, v) - 1 | \nu dv ds \right)^2 \quad (3.56) \end{align*} \]

Set

\[ M_t := \int_0^t \int_X \epsilon G(s, \tilde{X}_s^*, v) \sum_{i=k}^{\infty} Y_i^*(s-) e_i > \tilde{N} t^{-1} \epsilon (dsdv). \]
Then we have,

\[
E[ \sup_{0 \leq t \leq t_0} |M_t|] \leq 4E\sqrt{|M|} \\
\leq 4E\left\{ \int_0^{t_0} \int_X |\epsilon G(s, \tilde{X}_{s-}, v), \sum_{i=k}^\infty Y_{t_i}^\epsilon (s-)e_i > |^2N^{\epsilon^{-1}}\varphi_\epsilon (dsdv) \right\}^{\frac{1}{2}}\\
\leq 4E\left\{ \int_0^{t_0} \int_X \|\epsilon G(s, \tilde{X}_{s-}, v)\|^2 \sum_{i=k}^\infty |Y_{t_i}^\epsilon (s-)|^2 N^{\epsilon^{-1}}\varphi_\epsilon (dsdv) \right\}^{\frac{1}{2}}\\
\leq 4E\left\{ \epsilon^{\frac{1}{2}} \sup_{0 \leq t \leq t_0} \sum_{i=k}^\infty |Y_{t_i}^\epsilon (t)|^2 \right\}^{\frac{1}{2}} \cdot \left\{ \int_0^{t_0} \int_X \epsilon^{\frac{1}{2}} \|\epsilon G(s, \tilde{X}_{s-}, v)\|^2 N^{\epsilon^{-1}}\varphi_\epsilon (dsdv) \right\}^{\frac{1}{2}}\\
\leq 2\epsilon^{\frac{1}{2}} \E \left( \left( 1 + \sup_{0 \leq t \leq t_0} \|\tilde{X}_{t}^\epsilon \|^2 \right) \left( \int_0^{t_0} \int_X \|G(s, v)\|^2_{H^0_{0,\varphi_\epsilon}} dsdv \right) \right)\\
\leq 2\epsilon^{\frac{1}{2}} \E \left( \left( 1 + \sup_{0 \leq t \leq t_0} \|\tilde{X}_{t}^\epsilon \|^2 \right) \cdot \sup_{g \in \mathcal{S}^N} \left( \int_0^{t_0} \int_X \|G(s, v)\|^2_{H^0_{0,\varphi_\epsilon}} dsdv \right) \right) \\
(3.57)
\]

The upper bound of the last term in (3.52) is given by,

\[
E[\int_0^{t_0} \int_X \|\epsilon G(s, \tilde{X}_{s}, v)\|^2_{H^0_{0,\varphi_\epsilon}} (dsdv)]\\
\leq \epsilon E[\int_0^{t_0} \int_X \|G(s, \tilde{X}_{s}, v)\|^2_{H^0_{0,\varphi_\epsilon}} (dv) ds]\\
\leq \epsilon E[\left( 1 + \sup_{0 \leq t \leq t_0} \|\tilde{X}_{t}^\epsilon \|^2 \right) \cdot \sup_{g \in \mathcal{S}^N} \left( \int_0^{t_0} \int_X \|G(s, v)\|^2_{H^0_{0,\varphi_\epsilon}} (dv) ds \right) ]. \\
(3.58)
\]

Therefore, combining the above inequalities, we get

\[
E[\sup_{0 \leq t \leq t_0} \sum_{i=k}^\infty |Y_{t_i}^\epsilon (t)|^2]\\
\leq \sum_{i=k}^\infty | < X_0, e_i > |^2 + \left( \frac{1}{2} + 4\epsilon^{\frac{1}{2}} \right) E[ \sup_{0 \leq t \leq t_0} \left( \sum_{i=k}^\infty |Y_{t_i}^\epsilon (s)|^2 \right)]\\
+ (8N + 129\epsilon) \left( \int_0^{t_0} K(s) ds \right) E[\left( 1 + \sup_{0 \leq t \leq t_0} \|\tilde{X}_{t}^\epsilon \|^2 \right) ]
\]

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Lemma 3.9 There exists $\epsilon_0 > 0$, such that, for any $t_0 \in [0, T]$,

$$\sup_{0 < \epsilon < \epsilon_0} \sup_{\phi_0 = (\varphi_1, \varphi_2) \in \Omega^N} \mathbb{E} \sup_{t_0 \leq t \leq T} \sum_{i=k}^{\infty} |\langle \tilde{X}_t^\epsilon, e_i \rangle|^2 \leq e^{-2\zeta \epsilon t_0} C. \quad (3.60)$$

Proof: By (3.51), we have

$$\sum_{i=k}^{\infty} |Y_i^\epsilon(t)|^2 \leq \sum_{i=k}^{\infty} \langle X_0, e_i \rangle^2 - 2\zeta_k \int_0^t \sum_{i=k}^{\infty} |Y_i^\epsilon(s)|^2 ds$$

$$+ 2 \int_0^t \int_X \langle G(s, \tilde{X}_s^\epsilon, v), \sum_{i=k}^{\infty} Y_i^\epsilon(s)e_i \rangle \langle \varphi_1(s, v) - 1 \nu(dv) ds$$

$$+ 2 \int_0^t \int_X \langle \epsilon G(s, \tilde{X}_s^\epsilon, v), \sum_{i=k}^{\infty} Y_i^\epsilon(s)e_i \rangle \tilde{N}^{\epsilon^{-1} \varphi_1} (dv, ds)$$

$$+ \int_0^t \int_X \sum_{i=k}^{\infty} |\langle \epsilon G(s, \tilde{X}_s^\epsilon, v), e_i \rangle|^2 \tilde{N}^{\epsilon^{-1} \varphi_1} (dv, ds)$$

$$+ 2 \int_0^t \langle \sqrt{\epsilon} \sigma(s, \tilde{X}_s^\epsilon) d\beta_s, \sum_{i=k}^{\infty} Y_i^\epsilon(s)e_i \rangle$$

$$+ 2 \int_0^t \langle \varphi(s, \tilde{X}_s^\epsilon) \psi(s), \sum_{i=k}^{\infty} Y_i^\epsilon(s)e_i \rangle ds$$

$$+ \epsilon \int_0^t \|\varphi(s, \tilde{X}_s^\epsilon)\|_{L_2(H)}^2 ds$$

$$\leq \sum_{i=k}^{\infty} \langle X_0, e_i \rangle^2 - 2\zeta_k \int_0^t \sum_{i=k}^{\infty} |Y_i^\epsilon(s)|^2 ds$$

$$+ 2 \int_0^t \int_X |\langle G(s, \tilde{X}_s^\epsilon, v), \sum_{i=k}^{\infty} Y_i^\epsilon(s)e_i \rangle \langle \varphi_1(s, v) - 1 \nu(dv) ds$$

$$+ 2 \sup_{0 \leq t \leq T} | \int_0^t \int_X \langle \epsilon G(s, \tilde{X}_s^\epsilon, v), \sum_{i=k}^{\infty} Y_i^\epsilon(s)e_i \rangle \tilde{N}^{\epsilon^{-1} \varphi_1} (dv, ds)$$

$$+ 2 \int_0^T \int_X \sum_{i=k}^{\infty} |\langle \epsilon G(s, \tilde{X}_s^\epsilon, v), e_i \rangle|^2 \tilde{N}^{\epsilon^{-1} \varphi_1} (dv, ds)$$

$$+ 2 \sup_{t \in [0, T]} | \int_0^t \langle \sqrt{\epsilon} \sigma(s, \tilde{X}_s^\epsilon) d\beta_s, \sum_{i=k}^{\infty} Y_i^\epsilon(s)e_i \rangle$$

$$+ 2 \int_0^T \|\sigma(s, \tilde{X}_s^\epsilon) \psi(s)\|_H \sum_{i=k}^{\infty} Y_i^\epsilon(s)e_i \|_H ds$$

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by the Gronwall’s inequality this implies that
\[
\sum_{i=k}^{\infty} |Y_i(t)|^2 \leq e^{-2\zeta t} [I_1 + 2I_3 + 2I_4 + I_5 + 2I_6 + 2I_7 + I_8].
\]
Hence, for any \( t_0 > 0 \), we have
\[
\sup_{t_0 \leq t \leq T} \sum_{i=k}^{\infty} |Y_i(t)|^2 \leq e^{-2\zeta t_0} [I_1 + 2I_3 + 2I_4 + I_5 + 2I_6 + 2I_7 + I_8]. \tag{3.61}
\]
\[
\mathbb{E}I_3 \leq E \int_0^T \int_X \|G(s, \bar{X}_s^\epsilon, v)\|_H \|\bar{X}_s^\epsilon\|_H |\varphi(s, v) - 1| \nu(dv)ds
\]
\[
\leq E \left[ \sup_{0 \leq s \leq T} (\|\bar{X}_s^\epsilon\|_H + \|\bar{X}_s^\epsilon\|_H^2 ) \cdot \int_0^T \int_X \|G(s, v)\|_{0,H} |\varphi(s, v) - 1| \nu(dv)ds \right] \tag{3.62}
\]
\[
\leq E \left[ (1 + 2 \sup_{0 \leq s \leq T} \|\bar{X}_s^\epsilon\|_H^2 ) \cdot \sup_{g \in S^N} \int_0^T \int_X \|G(s, v)\|_{0,H} |g(s, v) - 1| \nu(dv)ds,
\]
\[
\mathbb{E}I_4 \leq \mathbb{E} \left[ \left( \int_0^T \int_X \left| (\epsilon G(s, \bar{X}_s^\epsilon, v), \sum_{i=k}^{\infty} Y_i^\epsilon(s)e_i) \right|^2 N^{-1} \phi^\epsilon (dv, ds) \right)^{1/2} \right]
\]
\[
\leq \mathbb{E} \left[ \left( \int_0^T \int_X \epsilon^2 \|G(s, \bar{X}_s^\epsilon, v)\|_H^2 \|\bar{X}_s^\epsilon\|_H^2 N^{-1} \phi^\epsilon (dv, ds) \right)^{1/2} \right]
\]
\[
\leq \epsilon^{1/2} \mathbb{E} \left[ \sup_{0 \leq s \leq T} \|\bar{X}_s^\epsilon\|_H^2 \right] + \epsilon^{1/2} \mathbb{E} \left[ \left( \int_0^T \int_X \|G(s, \bar{X}_s^\epsilon, v)\|_H^2 N^{-1} \phi^\epsilon (dv, ds) \right)^{1/2} \right]
\]
\[
\leq \epsilon^{1/2} \mathbb{E} \left[ \sup_{0 \leq s \leq T} \|\bar{X}_s^\epsilon\|_H^2 \right] + \epsilon^{1/2} \mathbb{E} \left[ \left( 1 + \sup_{0 \leq s \leq T} \|\bar{X}_s^\epsilon\|_H^2 \right)^2 \cdot \left( \int_0^T \int_X \|G(s, v)\|_{0,H}^2 \phi^\epsilon (s, v) \nu(dv)ds \right) \right]
\]
\[
\leq \epsilon^{1/2} \mathbb{E} \left[ \sup_{0 \leq s \leq T} \|\bar{X}_s^\epsilon\|_H^2 \right] + \epsilon^{1/2} \mathbb{E} \left[ \left( 1 + \sup_{0 \leq s \leq T} \|\bar{X}_s^\epsilon\|_H^2 \right)^2 \cdot \sup_{g \in S^N} \int_0^T \int_X \|G(s, v)\|_{0,H}^2 g(s, v) \nu(dv)ds \right]. \tag{3.63}
\]
\[
\mathbb{E}I_5 \leq \epsilon \mathbb{E} \left[ \int_0^T \int_X \|G(s, \bar{X}_s^\epsilon, v)\|_H^2 \phi^\epsilon (s, v) \nu(dv)ds \right]
\]
\[
\leq \epsilon \mathbb{E} \left( 1 + \sup_{0 \leq s \leq T} \|\bar{X}_s^\epsilon\|_H^2 \right)^2 \cdot \sup_{g \in S^N} \int_0^T \int_X \|G(s, v)\|_{0,H}^2 g(s, v) \nu(dv)ds. \tag{3.64}
\]
\[
\mathbb{E}I_6 \leq \sqrt{\epsilon}\mathbb{E}\left\{\int_0^T \|\sigma(s, \tilde{X}_s^\epsilon)\|^2_{L^2(H)}\|\tilde{X}_s^\epsilon\|^2_H ds\right\}^{1/2}
\]
\[
\leq \sqrt{\epsilon}\mathbb{E}\left[\sup_{s \in [0, T]} \|\tilde{X}_s^\epsilon\|_H^2 + 1\right] \times \left[\int_0^T K(s) ds\right]^{1/2},
\]  
(3.65)

\[
\sup_{\psi \in \tilde{S}^N} \mathbb{E}I_7 \leq \mathbb{E}\int_0^T \sqrt{K(s)}\sqrt{\|\tilde{X}_s^\epsilon\|_H^2 + 1}\|\tilde{X}_s^\epsilon\|_H \|\psi(s)\|_H ds
\]
\[
\leq \mathbb{E}\left[\sup_{s \in [0, T]} \|\tilde{X}_s^\epsilon\|_H^2 + 1\right] \times \left(\int_0^T K(s) ds + N\right),
\]  
(3.66)

\[
\mathbb{E}I_8 \leq \epsilon\mathbb{E}\left[\sup_{s \in [0, T]} \|\tilde{X}_s^\epsilon\|_H^2 + 1\right] \times \int_0^T K(s) ds,
\]  
(3.67)

By (3.61)-(3.67), Lemma 3.1 and (3.41), we have

\[
\sup_{0 < \epsilon < \epsilon_0} \mathbb{E}\sup_{t_0 \leq t \leq T} \sum_{i=k}^{\infty} |\langle \tilde{X}_t^\epsilon, e_i \rangle|^2 \leq e^{-2\zeta \epsilon_0} C_N.
\]  

\[
\text{Remark 3 By Lemma 3.1, Remark 2, (3.41), (3.50) and the integrability of } K(s), \text{ for every } 0 < \epsilon < \epsilon_0 \text{ and } \eta > 0, \text{ there exists } t_0 \in [0, T] \text{ such that }
\]
\[
(1/2 - 4\epsilon^{1/2})\mathbb{E}\left[\sup_{0 \leq t \leq t_0} \sum_{i=k}^{\infty} |\langle \tilde{X}_t^\epsilon, e_i \rangle|^2 \right] \leq \sum_{i=k}^{\infty} \langle \tilde{X}_0^\epsilon, e_i \rangle^2 + C\eta + C(\epsilon^{1/2} + \epsilon)
\]  
(3.68)

In the sequel, the next two tightness results in \(D([0, T], H)\) and \(D([0, T], \mathbb{R})\) will be used.

\[
\lim_{N \to \infty} \limsup_{n \to \infty} \mathbb{P}\left(\mathbb{E}I_6(s) > \epsilon \right. \left. \text{for some } s, \ 0 \leq s \leq T \right) \to 0. \quad (3.69)
\]

Here we say a \(H\)-valued sequence \(\{X^n\}_{n \in \mathbb{N}}\) is “\(D\)-weakly tight” (in \([11]\)) if \(\langle X^n, \phi \rangle\) as a \(\mathbb{R}\)-valued sequence is tight, for every \(\phi \in D\).

In order to prove “\(D\)-weakly tight” in Lemma 3.10 we need the tightness result in \(D([0, T], \mathbb{R})\); and one can refer to [3].

\[
\text{Remark 3 By Lemma 3.1, Remark 2, (3.41), (3.50) and the integrability of } K(s), \text{ for every } 0 < \epsilon < \epsilon_0 \text{ and } \eta > 0, \text{ there exists } t_0 \in [0, T] \text{ such that }
\]
\[
(1/2 - 4\epsilon^{1/2})\mathbb{E}\left[\sup_{0 \leq t \leq t_0} \sum_{i=k}^{\infty} |\langle \tilde{X}_t^\epsilon, e_i \rangle|^2 \right] \leq \sum_{i=k}^{\infty} \langle \tilde{X}_0^\epsilon, e_i \rangle^2 + C\eta + C(\epsilon^{1/2} + \epsilon)
\]  
(3.68)

In the sequel, the next two tightness results in \(D([0, T], H)\) and \(D([0, T], \mathbb{R})\) will be used.

\[
\lim_{N \to \infty} \limsup_{n \to \infty} \mathbb{P}\left(\mathbb{E}I_6(s) > \epsilon \right. \left. \text{for some } s, \ 0 \leq s \leq T \right) \to 0. \quad (3.69)
\]
Let \( \{ Y^\epsilon \}_{\epsilon \in [0, \epsilon_0]} \) be a sequence of random elements of \( D([0, T], \mathbb{R}) \), and \( \{ \tau_\epsilon, \delta_\epsilon \} \) be such that:

(a) for each \( \epsilon, \tau_\epsilon \) is a stopping time with respect to the natural \( \sigma \)-fields, and takes only finitely many values.

(b) for each \( \epsilon \), the constant \( \delta_\epsilon \in [0, T] \) and \( \delta_\epsilon \to 0 \) as \( \epsilon \to 0 \).

We introduce the following condition on \( \{ Y^\epsilon \} \) : for each sequence \( \{ \tau_\epsilon, \delta_\epsilon \} \) satisfying (a)(b),

\[ \text{Condition (A)} \quad Y^\epsilon(\tau_\epsilon + \delta_\epsilon) - Y^\epsilon(\tau_\epsilon) \to 0, \text{ as } \epsilon \to 0, \text{ in probability}. \]

For \( f \in D([0, T], \mathbb{R}) \), let \( J(f) \) denote the maximum of the jump \( |f(t) - f(t^-)| \).

Lemma 3.11 \( (14) \) Suppose that \( \{ Y^\epsilon \}_{\epsilon \in \mathbb{N}} \) satisfies Condition (A), and either \( \{ Y^\epsilon(0) \} \) and \( \{ J(Y^\epsilon) \} \) are tight on the line; or \( \{ Y^\epsilon(t) \} \) is tight on the line for each \( t \in [0, T] \), then \( \{ Y^\epsilon \} \) is tight in \( D([0, T], \mathbb{R}) \).

Theorem 3.5 Fix \( M \in \mathbb{N} \), and let \( \phi_\epsilon = (\psi_\epsilon, \varphi_\epsilon), \phi = (\psi, \varphi) \in \tilde{U}^M \) be such that \( \phi_\epsilon \) converges in distribution to \( u \) as \( \epsilon \to 0 \). Then

\[ \mathcal{G}^\epsilon(\sqrt{\epsilon} \beta + \int_0^\epsilon \psi_\epsilon(s)ds, \epsilon N^{-1/2} \varphi) \Rightarrow \mathcal{G}^0(\int_0^\epsilon \psi(s)ds, \nu^\varphi). \]

Proof: First, we prove that \( \mathcal{G}^\epsilon(\sqrt{\epsilon} \beta + \int_0^\epsilon \psi_\epsilon(s)ds, \epsilon N^{-1/2} \varphi) \) is tight in \( D([0, T], H) \). We will use Lemma 3.10 and Lemma 3.11 to prove this result.

By (3.68) and (3.69), it follows that for any \( \delta > 0 \) and \( t_0 \leq T \),

\[
\sup_{0 \leq t \leq t_0} \sup_{\phi_\epsilon = (\psi_\epsilon, \varphi_\epsilon) \in \tilde{U}^N} P(\sup_{0 \leq t \leq T} \sum_{i=k}^\infty \langle \tilde{X}_t^\epsilon, e_i \rangle^2 > \delta) \leq \delta^{-1} \sup_{0 \leq t \leq t_0} \sup_{\phi_\epsilon = (\psi_\epsilon, \varphi_\epsilon) \in \tilde{U}^N} \mathbb{E}(\sup_{0 \leq t \leq T} \sum_{i=k}^\infty \langle \tilde{X}_t^\epsilon, e_i \rangle^2)
+ \delta^{-1} \sup_{0 \leq t \leq t_0} \sup_{\phi_\epsilon = (\psi_\epsilon, \varphi_\epsilon) \in \tilde{U}^N} \mathbb{E}(\sup_{t_0 \leq t \leq T} \sum_{i=k}^\infty \langle \tilde{X}_t^\epsilon, e_i \rangle^2)
=: (I) + (II).
\]

By estimates (3.50), for any \( \tilde{\epsilon} > 0 \), there exists \( K_1 > 0 \) and \( \tilde{t}_0 > 0 \), such that for any \( k > K_1 \) and \( t_0 < \tilde{t}_0 \), we have \( (I) \leq \frac{\tilde{\epsilon}}{2} \).

Fixing a constant \( 0 < t_0 \leq \tilde{t}_0 \), by estimates (3.60), we know that there exists constant \( K_2 > 0 \), such that for any \( k > K_2 \),

\[ (II) \leq e^{-2\tilde{\epsilon}t_0} C \leq \frac{\tilde{\epsilon}}{2}. \] (3.70)

Since \( \tilde{\epsilon} \), we have

\[ \lim_{k \to \infty} \sup_{0 \leq t \leq t_0} \sup_{\phi_\epsilon = (\psi_\epsilon, \varphi_\epsilon) \in \tilde{U}^N} P(\sup_{0 \leq t \leq T} \sum_{i=k}^\infty \langle \tilde{X}_t^\epsilon, e_i \rangle^2 > \delta) = 0. \]

Hence by Lemma 3.10, we only need to prove that, for every \( \phi \in H_A^\epsilon \), \( \mathcal{G}^\epsilon(\sqrt{\epsilon} \beta + \int_0^\epsilon \psi_\epsilon(s)ds, \epsilon N^{-1/2} \varphi), \phi \) is tight in \( D([0, T], \mathbb{R}) \).

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satisfies the condition of Lemma 3.11. Hence it remains to prove

By (3.41),

$$\sup_{0<\epsilon<\epsilon_0} \mathbb{P}(|Y^\epsilon(t)| > L) \leq C/L^2,$$

hence \{Y^\epsilon(t)\} is tight on the line for each $t \in [0, T]$.

Hence it remains to prove Condition (A). For each sequence \{\tau_\epsilon, \delta_\epsilon\} satisfying (a)(b),

$$Y^\epsilon(\tau_\epsilon + \delta_\epsilon) - Y^\epsilon(\tau_\epsilon) = -\int_{\tau_\epsilon}^{\tau_\epsilon + \delta_\epsilon} \langle \tilde{X}^\epsilon(s), \mathcal{A}^* \phi \rangle ds$$

$$+ \int_{\tau_\epsilon}^{\tau_\epsilon + \delta_\epsilon} \int_X \langle G(s, \tilde{X}^\epsilon(s), v), \phi \rangle \left( \epsilon N^{-1} \varphi^\epsilon (dv, ds) - \nu(dv) ds \right)$$

$$+ \int_{\tau_\epsilon}^{\tau_\epsilon + \delta_\epsilon} \langle \sqrt{\epsilon} \sigma(s, \tilde{X}^\epsilon(s)) d\beta_s, \phi \rangle$$

$$+ \int_{\tau_\epsilon}^{\tau_\epsilon + \delta_\epsilon} \langle \sigma(s, \tilde{X}^\epsilon(s)) \psi_{\epsilon}(s), \phi \rangle ds$$

$$= -\int_{\tau_\epsilon}^{\tau_\epsilon + \delta_\epsilon} \langle \tilde{X}^\epsilon(s), \mathcal{A}^* \phi \rangle ds$$

$$+ \int_{\tau_\epsilon}^{\tau_\epsilon + \delta_\epsilon} \int_X \langle G(s, \tilde{X}^\epsilon(s), v), \phi \rangle \epsilon N^{-1} \varphi^\epsilon (dv, ds)$$

$$+ \int_{\tau_\epsilon}^{\tau_\epsilon + \delta_\epsilon} \int_X \langle G(s, \tilde{X}^\epsilon(s), v), \phi \rangle (\varphi - 1) \nu(dv) ds$$

$$+ \int_{\tau_\epsilon}^{\tau_\epsilon + \delta_\epsilon} \langle \sqrt{\epsilon} \sigma(s, \tilde{X}^\epsilon(s)) d\beta_s, \phi \rangle$$

$$+ \int_{\tau_\epsilon}^{\tau_\epsilon + \delta_\epsilon} \langle \sigma(s, \tilde{X}^\epsilon(s)) \psi_{\epsilon}(s), \phi \rangle ds$$

$$= I_1 + I_2 + I_3 + I_4 + I_5,$$  \hspace{1cm} (3.71)
By the same argument leading to (3.30), we can show that, for every $\eta > 0$, there exists $\delta > 0$, such that

$$
\sup_{g \in \mathcal{S}^M} \int_A \int_X \|G(s, v)\|_{0, H} |g(v, s) - 1| \nu(dv)ds \leq \eta, \quad \forall \, A \in [0, T], \, \lambda_T(A) \leq \delta.
$$

Hence, if $\delta_\epsilon \leq \delta$, we deduce that

$$
\mathbb{E}(|I_3|) \leq \eta \|\phi\|_H \mathbb{E}(1 + \sup_{s \in [0, T]} \|\tilde{X}^\epsilon(s)\|_H).
$$

(3.74)

For the terms in $I_4$ and $I_5$, we have

$$
\mathbb{E}(|I_4|^2) \leq \epsilon \|\phi\|^2_H \mathbb{E} \int_0^T \|\sigma(s, \tilde{X}^\epsilon(s))\|_{L_2(H)}^2 ds
$$

$$
\leq \epsilon \|\phi\|^2_H (\mathbb{E} \sup_{s \in [0, T]} \|\tilde{X}^\epsilon(s)\|^2_H + 1) \times \int_0^T K(s) ds;
$$

(3.75)

$$
\mathbb{E}(|I_5|) \leq \|\phi\|_H \mathbb{E} \int_{\tau_\epsilon}^{\tau_\epsilon + \delta_\epsilon} \|\sigma(s, \tilde{X}^\epsilon(s))\|_{L_2(H)} \|\psi_\epsilon(s)\|_H ds
$$

$$
\leq \|\phi\|_H \mathbb{E} \int_{\tau_\epsilon}^{\tau_\epsilon + \delta_\epsilon} \sqrt{K(s)} \sqrt{\|\tilde{X}^\epsilon(s)\|^2_H + 1} \|\psi_\epsilon(s)\|_H ds
$$

$$
\leq M^{1/2} \|\phi\|_H \mathbb{E} \left\{ \sup_{s \in [0, T]} \sqrt{\|\tilde{X}^\epsilon(s)\|^2_H + 1} \times [\int_{\tau_\epsilon}^{\tau_\epsilon + \delta_\epsilon} K(s) ds]^{1/2} \right\},
$$

where $M = \int_0^T \|\psi_\epsilon(s)\|^2_H ds$.

Since $K(\cdot) \in L^1([0, T], \mathbb{R})$, there exists $\tilde{\delta} > 0$ such that, if $\delta_\epsilon \leq \tilde{\delta}$,

$$
\mathbb{E}(|I_5|) \leq \eta M^{1/2} \|\phi\|_H \mathbb{E} \sqrt{\sup_{s \in [0, T]} \|\tilde{X}^\epsilon(s)\|^2_H + 1}.
$$

(3.76)

By (3.72)–(3.76) and Chebyshev inequality, we see that Condition (A) holds. Thus we have proved that $\mathcal{G}^{\epsilon}(\sqrt{\epsilon} \beta + \int_0^\epsilon \tilde{\psi}_\epsilon(s) ds, \epsilon N^{\epsilon^{-1} \nu})$ is tight in $D([0, T], H)$.

Finally, we prove that $\mathcal{G}^{\epsilon}(\int_0^\epsilon \psi_\epsilon(s) ds, \nu^\epsilon)$ is the unique limit point of $\mathcal{G}^{\epsilon}(\sqrt{\epsilon} \beta + \int_0^\epsilon \psi_\epsilon(s) ds, \epsilon N^{\epsilon^{-1} \nu})$.

Note that $\tilde{X}^\epsilon$ satisfies

$$
\langle \tilde{X}^\epsilon(t), \phi \rangle = \langle X_0, \phi \rangle - \int_0^t \langle \tilde{X}^\epsilon(s), A^s \phi \rangle ds
$$

$$
+ \int_0^t \int_X \langle G(s, \tilde{X}^\epsilon(s), v), \phi \rangle \epsilon \tilde{N}^{\epsilon^{-1} \nu} \nu dv ds
$$

$$
+ \int_0^t \int_X \langle G(s, \tilde{X}^\epsilon(s), v), \phi \rangle (\tau_\epsilon - 1) \nu dv ds
$$

$$
+ \int_0^t \langle \sqrt{\epsilon} \sigma(s, \tilde{X}^\epsilon(s)) d\beta_s, \phi \rangle
$$

$$
+ \int_0^t \langle \sigma(s, \tilde{X}^\epsilon(s)) \psi_\epsilon(s) ds, \phi \rangle, \quad \forall \phi \in V.
$$

(3.77)
Denote \( M^\epsilon(t) = \int_0^t \sqrt{\epsilon} \sigma(s, X^\epsilon(s)) \, d\beta_s \) and \( M^\epsilon(t) = \int_0^t \int_X G(s, Y(s), v) \sqrt{\epsilon} \, d\nu^\epsilon (dv, ds) \). Since

\[
\mathbb{E}( \sup_{s \in [0,T]} \| M^\epsilon(s) \|_H^2) \leq \epsilon \mathbb{E} \int_0^T \| \sigma(s, \tilde{X}^\epsilon(s)) \|_{L^2(H)}^2 \, ds
\]

and

\[
\mathbb{E}( \sup_{s \in [0,T]} \| M^\epsilon(s) \|_H^2) \leq \mathbb{E} \left( \int_0^T \int_X \| G(s, \tilde{X}^\epsilon(s), v) \|_H^2 (1 + \| \tilde{X}^\epsilon(s) \|_H^2)^2 \varphi \, \nu(dv) \, ds \right)
\]

by Lemma 3.1 and (3.41), \( \overline{M} \to 0 \) and \( M^\epsilon \to 0 \), as \( \epsilon \to 0 \).

Choose a subsequence along which \((\tilde{X}^\epsilon, u_\epsilon, \overline{M}, M^\epsilon)\) converges to \((\tilde{X}, u, 0, 0)\) in distribution. By the Skorokhod representation theorem, we may assume \((\tilde{X}^\epsilon, u_\epsilon, \overline{M}, M^\epsilon) \to (\tilde{X}, u, 0, 0)\) almost surely.

Note that convergence in Skorokhod topology to a continuous limit is equivalent to the uniform convergence, and \(C([0,T], H)\) is a closed subset of \(D([0,T], H)\). Hence

\[
\lim_{\epsilon \to 0} \sup_{s \in [0,T]} \| M^\epsilon(s) \|_H^2 = 0, \ \mathbb{P} - a.s..
\]

Since \( \tilde{X}^\epsilon - M^\epsilon \in C([0,T], H) \) and \( \tilde{X}^\epsilon - M^\epsilon \to \tilde{X} \) almost surely in \(D([0,T], H)\), we have \( \tilde{X} \in C([0,T], H) \), and

\[
\lim_{\epsilon \to 0} \sup_{s \in [0,T]} \| \tilde{X}^\epsilon(s) - \tilde{X}(s) \|_H^2 = 0, \ \mathbb{P} - a.s..
\]

Along the same lines of the proof of Theorem 3.1 and Proposition 3.3, letting \( \epsilon \to 0 \), we see that \( \tilde{X} \) must solve

\[
\langle \tilde{X}(t), \phi \rangle = \langle X_0, \phi \rangle - \int_0^t \langle \tilde{X}(s), \mathcal{A} \phi \rangle \, ds + \int_0^t \langle \sigma(s, \tilde{X}(s)) \psi(s), \phi \rangle \, ds
\]

\[
+ \int_0^t \int_X \langle G(s, \tilde{X}(s), v), \phi \rangle (\varphi - 1) \nu(dv) \, ds, \ \forall \phi \in V.
\] (3.78)

By the uniqueness, this gives that \( \tilde{X} = \mathcal{G}^0(\int_0^t \psi(s) \, ds, \nu^\varphi) \). Proof is completed. \( \blacksquare \)

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