Flexible Gas Sensor Printed on a Polymer Substrate for Sub-ppm Acetone Detection

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Abstract
Gas sensors are widely used in many industrial and home applications. There is therefore continued need to develop novel gas sensor substrates which provide good mechanical and electrical stability, and good flexibility in comparison with the conventional alumina and silicon-based materials. In this paper, we present the experimental results on flexible gas sensors based on the Kapton foil and alumina substrate covered by copper oxide as a gas-sensitive layer. These sensors exhibited good mechanical stability and gas-sensing characteristics. The Kapton-based CuO gas sensors were tested under exposure to acetone in the 0.05–1.25 ppm range (150 °C, 50%RH). The results confirmed that sensors deposited on the flexible substrate such as Kapton can be used in the exhaled breath analyzers dedicated to diabetes biomarker detection or other applications for which the elastic substrate is needed.

Graphic Abstract

Keywords  Gas sensors · Elastic gas sensor substrates · Acetone detector

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Abbreviations

| Abbreviation | Description                              |
|--------------|------------------------------------------|
| ABS          | Acrylonitrile butadiene styrene           |
| CNF          | Carbon nanofibers                         |
| FDM          | Fused deposition modelling                |
| GO           | Graphene oxide                            |
| ITO          | Indium-tin oxide                          |
| NF           | Nanofibers                                |
| NMF          | Nanofibrous mesh                          |
| NP           | Nanoparticles                             |
| NR           | Nanorods                                  |
| NS           | Nanostructures                            |
| NSph         | Nanospheres                               |
| PANI         | Polyaniline                               |
| PC           | Polycarbonate                             |
| PET          | Epoxyethylene terephthalate               |
| PI           | Polyimide, trademarked as Kapton           |
| PPy/N-MWCNT  | Polypropylene/nitrogen-doped multiwall carbon nanotube |
| PTFE         | Polytetrafluoroethylene                   |
| rGO          | Reduced graphene oxide                    |
| RH           | Relative humidity                         |
| RT           | Room temperature                          |
| SWCNT        | Single-walled carbon nanotubes            |

1 Introduction

Gas sensors have been developed over the few last decades in response to industrial demands: for the monitoring of air quality [1], in the automotive industry [2], in medicine for the detection of biomarkers in various diseases [3–5]. In principle, a gas sensor consists of a gas sensor substrate with a gas-sensitive layer, and package. Gas sensor substrates are usually realized in alumina [6], LTCC (low temperature cofired ceramics) [7–9] and silicon technology [10], and gas-sensitive layers are based on metal oxides [11–14]. Flexible gas sensor substrates are very promising in the portable exhaled breath analyzers. In recent years,

Table 1 A summary of the recently reported research on gas-sensing applications with flexible gas sensor substrates

| Flexible substrate material | Gas-sensing layer material | Target gas | Concentration (ppm) | Response | Operating temp. (°C) | References |
|----------------------------|---------------------------|------------|---------------------|----------|----------------------|------------|
| PET                        | Polyaniline               | NH₃        | 25                  | 4.29**   | RT                   | [17]       |
| PET                        | TiO₂ + Bi₂WO₆ (NF)        | Ethanol    | 50                  | 12.6%**  | RT                   | [20]       |
|                            |                           |            | 800                 | 60%**    |                      |            |
| PET                        | Cu-(CH₃COO)₂             | H₂S        | 10                  | 10^5*    | RT                   | [19]       |
| PET                        | SWCNT + Cu               | H₂S        | 20                  | 25%**    | RT                   | [24]       |
| PET                        | In₂O₃ (NSph) + Au         | NH₃        | 100                 | 46*      | RT                   | [25]       |
| PET                        | Polyaniline-WO₃          | NH₃        | 100                 | 121%**   | RT                   | [26]       |
| PET                        | SnO₂-rGO/PANI             | H₂S        | 0.2                 | 23.9%**  | RT                   | [27]       |
| PET                        | Polyaniline hydrochloride| NH₃        | 50                  | 2.1*     | RT                   | [28]       |
| PI/PTFE                    | ZnO(NR) + Ag polyaniline coated | C₂H₂       | 1000                | 27.2*    | 200                  | [29]       |
| PI                         | WO₃ (NS) + Au/Pt          | Methanol   | 2000                | 4.3*     | 150-250              | [16]       |
|                            |                          | Ethanol    |                     | 6.4*     |                      |            |
|                            |                          | Acetone    |                     | 2.0*     |                      |            |
|                            |                          | Toluene    |                     | 1.8*     |                      |            |
| PI                         | Zn₄GeO₄                  | NH₃        | 200                 | 831**    | RT                   | [30]       |
| PI                         | TiO₂₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋₋˓→\n|                            | NH₃                      | 100       | 7%**               | 210      | [31]                 |
| PI                         | WO₃                      | Ethanol    | 100                 | 3%**     | 220                  | [32]       |
| PI                         | CNF + Au/Pd              | NH₃        | 500                 | 3%**     | 120                  | [33]       |
| PI                         | Polyaniline-CeO₂         | NH₃        | 10                  | 106.9%** | RT                   | [34]       |
| PI                         | PPy/N-MWCNT              | NO₂        | 5                   | 24.82%** | RT                   | [35]       |
| PI                         | TiO₂                     | Trimethylamine | 100        | 1.7*     | RT                   | [36]       |
| PI                         | ZnO (NP)                 | NH₃        | 0.1                 | 1.32*    | 300                  | [37]       |
|                            |                          | O₃         | 0.2                 | 15*      | 200                  |            |
| ITO-PET                    | GO                       | Isopropanol | 25 ppm             | 0.7%**   | RT                   | [38]       |
| Nylon fabric               | rGO-NFM                  | NO₂        | 1                   | 13%**    | RT                   | [39]       |
| PC                         | Cu/CuO                   | RH         | 0-95%               | 60%**    | RT                   | [21]       |

*Rₐ/Rₙ or Rₜ/Rₚ

**(Rₕ-Rₜ)/Rₜ, where Rₜ and Rₙ are electrical resistances in air and target gas, respectively
Flexible gas sensors have become increasingly attractive due to a number of advantages such as miniaturization, and portable or wearable properties. Flexible gas sensors based on the plastic substrates (plastic polyimide, PI) with titania nanotube (TNT) gas-sensitive layer for carbon monoxide (CO) and ammonia (NH₃) detection were reported in 2014 by Jang et al. [15]. The authors described gas-sensing performance of the flexible TNT sensors in which electrical current was measured during exposure to CO and NH₃ at 350 °C working temperature. The gas sensor response was defined as \((I_{\text{gas}} - I_0) / I_0 \times 100\%\), where \(I_{\text{gas}}\) and \(I_0\) are the electrical currents measured at exposure to target gas and air, respectively. Both gases were used in the 0–200 ppm concentration range, and the response obtained by the authors was 68.3% and 77.9% for 200 ppm of CO and NH₃ gases, respectively [15]. The main limitation of those sensors is still a high working temperature of 350 °C. The detection of volatile organic compounds (VOCs) using flexible gas-sensing devices was reported in 2015 by Vallejos et al. [16]. The gas sensors were based on highly crystalline tungsten oxide nanostructures functionalized with Au and Pt nanoparticles. These sensors were fabricated using commercial high heat resistant polyimide, where interdigital electrodes and heater were deposited. Gas-sensing tests were conducted at various operating temperatures (from 150 to 250 °C) and 0.2% concentrations of VOCs, such as ethanol, methanol, acetone, and toluene. The highest responses \((R_a / R_g)\), where \(R_a\) and \(R_g\) are electrical resistances to air and target gas, respectively) were obtained for Pt:WO₃ to methanol and Au:WO₃ to acetone at 220 °C [16]. A limitation of those sensors is the detection of high VOCs concentrations (2000 ppm). Apart from plastics and polyimide substrates, poly-PET (ethylene terephthalate) substrates were used for ammonia detection; the result for this material were reported in 2017 by Kumar et al. [17]. The authors presented gas sensors based on polyaniline (PANI) films as an active sensing layer. The PANI films were successfully deposited on a polyethylene terephthalate (PET) flexible substrate by a simple in situ polymerization technique. Ammonia gas-sensing properties of the films prepared at optimum conditions were examined at room temperature in the range of 5–1000 ppm. The fabricated sensors exhibited high responses and good long-term stability [17]. Similar results were reported by Hua et al. [18]. The single-walled carbon nanotubes (SWNTs)-Fe₂O₃ composite films deposited on plastic substrates were investigated as a potential gas sensor for NH₃, NO and NO₂ detection [18]. Recently, various different gas-sensing applications have been reported, including H₂S detection with inkjet-printed copper acetate on a flexible plastic substrate [19], ethanol detection with sensor consisting of a 1D TiO₂ nanofiber wrapped in a shell of Bi₃WO₆ nanosheets [20], and humidity detection of Cu/CuₓO integrated structure on flexible polycarbonate substrates [21]. Table 1 shows a brief summary of these recent studies, and a thorough review of flexible gas sensors can be found in Alrammouz et al. [22]. These authors conclude that flexible gas sensors are still in the development stage, and that future work will hopefully include new fabrication techniques, along with new composite materials and substrates, and that the field moves toward the integration of gas sensors in e-textiles, smart-packaging and application of sensors in the unconventional places [22].

In this paper, we describe a deposition of a copper oxide-based acetone sensor on a polymer substrate, with aim to enhance acetone detection and to bring the limit of detection of acetone into the sub-ppm range. These sensors are the main element of the portable exhaled breath analyzer for...
noninvasive diabetes monitoring, which is currently patent pending in the European Patent Office [23].

2 Materials and Methods

2.1 Flexible Gas Sensors Substrates

The design of the gas sensor substrate is shown in Fig. 1. It was designed based on the commercially available alumina substrates CC2 (BVT, Czech Republic), in which the geometry of the electrodes was set at the level that enables higher sensor sensitivity. The CC2 substrates (or similar) are widely used in the sensor society. A gas-sensitive layer was deposited on both substrates to allow comparison between the alumina and Kapton material. The shape of the electrodes enabled us to obtain a signal from the measuring electrode and the reference electrode at the same time. The electrode building process consists of three stages. First, a conductive layer is printed on a flexible substrate. For this stage, the aerosol jet printing technique was used with nanosilver ink from the UT Dots company. According to the manufacturer, the UTD AgTE ink based on the nanosilver particles is suitable for flexible substrates and after the sintering process, only silver material should be left in the layer. Because the sintering process is simply heating the ink to the temperature about 250 °C, it is possible for some residuals to be left in the layer, e.g. from surfactants or solvents. After the conductive layer is built the functional layer is deposited on the sensor; this is the last manufacturing step. The electrode lines were 40 μm wide and 2 μm thick. The Kapton foil 74 μm thick was used as a substrate material. This design of the sensor allows us to easily apply various gas-sensitive layers, such as metal oxides (schematically presented as blue boxes in Fig. 1).

Printed electrodes exhibit a slight non-linearity at the paths ends visible in Fig. 2, resulting from the limitations of aerosol printing deposition. The lines are homogeneous and parallel. Both the edges and the corners of the contact pads were printed correctly.

2.2 Gas-Sensitive Layer

The gas-sensitive layer was based on the copper oxide (CuO), which was previously confirmed to be a good gas-sensitive material in various measurement methods [40–44]. The CuO thin films were deposited by the magnetron sputtering system with a glancing angle deposition technique (GLAD). The base vacuum pressure and deposition vacuum pressures were 1 × 10⁻⁶ mbar and 3 × 10⁻³ mbar, respectively. The target to substrate distance was approximately 60 mm and the deposition temperature was 100 °C. The sputtering was conducted in a pure oxygen atmosphere. In this case, a metallic target was firstly presputtered to remove any contamination in pure Ar for 10 min at 100 W, then the pure O₂ was introduced to the chamber; the power, temperature, oxygen flow was fixed at 50 W, 100 °C and 20 sccm.

2.3 Gas-Sensing Measurements

The developed sensor presented in Fig. 2b was placed in the quartz-tube oven and the target gas at various concentrations was introduced. An electrometer (34401A HP) was used to record the electrical resistance changes. The various concentration levels were obtained by utilization of mass flow controllers 1179B (MKS Instruments, USA) and acetone canisters with 5 ppm of acetone (Air Products, UK). The gas-sensing measurement system was previously described in detail [45]. The gas-sensing measurements were performed at various temperatures and 50% relative
humidity (RH) level. Figure 3 shows the measurement system. The gas sensor response (S) was defined as resistance ratio $S = (R_{\text{gas}} - R_{\text{air}})/R_{\text{air}}$, where $R_{\text{gas}}$ and $R_{\text{air}}$ are electrical resistances in gas and air, respectively.

### 2.4 Mechanical Tests

The mechanical stability tests were performed to verify the mechanical durability and possible distortions that may occur during the resistance measurements, which in turn may lead to errors of gas concentration measurement. A synthesized test procedure was developed, followed by the design of a testbench for automated testing. The flexible sensors can be bent in many degrees of freedom; the tests therefore should be limited to a set of well-defined bending directions. Let us denote the length of the substrate as the X direction and the width as Y. The fundamental deformations that can be introduced are (1) linear contraction in X, (2) linear contraction in Y, (3) axial twist in X, (4) axial twist in Y. Because the sensor is significantly larger in the X direction than in Y and that the length of Y is substantially small, the deformations introduced in X will be of greatly smaller magnitude. Thus the most impactful would be the linear (Fig. 4a, b) and axial deformation (Fig. 4c, d) in the X-axis. These assumptions were taken as the basis for designing a testbench for automated mechanical testing. The testbench was designed as a 3D model and manufactured using common FDM 3D printing in ABS material.

The testbench consists of a servomotor, with one of two adapters mounted on its axle—one for linear bending (Fig. 5a) and one for axial rotation (Fig. 5b). In the axial configuration the base of the sensor is mounted in a stationary clamp at the top of the device, while the tip
fitted with a bar clamp and dangles loosely between rotating pillars. When the servo rotates the pillars by a certain angle, the sensor is also rotated. This rather unusual construction is necessary since during rotation the sensor is shortened in longitude. When the testbench is set up to test linear contraction, the servo adapter is swapped to a crank mechanism. The crank pushes a sliding clamp, clamping one end of the sensor, while the other end is in a stationary clamp. In both modes of operation, the sensor contacts are near the static clamps which allow for easy connection to an electrometer to measure resistance. The angle of the servomotor is controlled by a microcontroller with a USB serial interface, through which the setpoint angle is transmitted, the resistance of the gas-sensitive layer was measured by the electrometer (6514E, Keithley).

3 Results and Discussion

3.1 Characterization

In order to determine the sample phase composition, we used Panalytical Empyrean X-ray diffractometer with Co Kα radiation in grazing incidence configuration of 1°. Figure 6 shows the Grazing Incidence X-ray Diffraction (GIXD) patterns of Kapton-based CuO gas sensor as well as reference samples: silver contacts on polyimide Kapton substrate and polyimide Kapton substrate. Diffraction patterns for all three samples show the characteristic amorphous envelope and peaks due to some degree of crystallinity of the polyimide substrate [46] in the range of 20

Fig. 7 SEM images of the fabricated sensors: a general view, b zoom (×200000) of the CuO thin film deposited on the Kapton foil

Fig. 8 Resistance changes during the mechanical tests: a axial rotation tests, b linear compression tests
of 15°–35°. The obtained pattern shows that the sensor is mostly amorphous material with one weak diffraction peak at 41.5°, which may indicate the presence of CuO phase and is convolution of CuO (111) and (002) crystal planes [47]. In addition, there is no evidence of diffraction peaks for any other copper oxides phases. Low intensity GIXD peaks observed at 51.8° and 51.8°, correspond to Ag, which was used to make sensor electric contacts. Due to the low-intensity of diffraction peaks logarithmic scale was used to show the intensity curves along the y-axis. The XRD patterns for alumina-based CuO gas sensors were previously presented and discussed in [40–44].

The morphology of thin films was examined by Scanning Electron Microscopy ZEISS Gemini SEM (5 kV, WD 7.0 mm). SEM images are presented in Fig. 7. Figure 7a shows the general view of the sensor, where Kapton substrate uncovered and covered by CuO thin film is presented. The zoom (× 200,000) of the CuO thin film is presented in Fig. 7b.

Fig. 9 Gas-sensing characteristics of Kapton-based and alumina-based CuO gas sensor obtained under exposure to acetone: a resistance changes measured in the 1.25–0.1 ppm range, b response versus operating temperature under exposure to 0.75 ppm of acetone (50% RH)

Fig. 10 Gas-sensing characteristics for Kapton-based CuO gas sensor: a the resistance changes, b the calibration curve of the CuO-based sensor in the 0.05–0.8 ppm acetone range
3.2 Mechanical Results

The measurement procedure is controlled by a Python program running on a PC. The PC has serial interfaces to control the servo angle and to trigger resistance measurements on the electrometer. The procedure is simple and involves changing the rotation angle or linear distance in equal steps and triggering a resistance measurement after each step. The initial series of axial rotation tests and linear compression tests are shown in Fig. 8a, b, respectively. In the case of axial tests, the sensor was bent both clockwise and counterclockwise in 10° steps between −50° and +50°. In the case of linear tests, the sensor was compressed from the resting (flat) position up to 3.6 mm compression and back in 0.9 mm steps. The graph shows little change in the sensor resistance when exposed to bending. In the case of linear deformation, the average resistance throughout all tests was 35.24 MΩ with a standard deviation of 735.8 kΩ. In the case of axial deformation, the average resistance was 61.98 MΩ with a standard deviation of 1.72 MΩ. However, it has to be underlined that such measurements were carried out at room temperature (~23 °C) and relative humidity around ~35%.

3.3 Gas-Sensing Characteristics

The fabricated sensors were tested in the various temperature ranges dependent on the gas sensor substrates. The sensors were tested in the range of 50–200 °C for Kapton-based CuO, since over 200 °C the Kapton foil with electrodes and thin-film lost their stability, and in the range of 50–350 °C for alumina-based. The highest responses were obtained at 150 °C and 300 °C for Kapton-based and alumina-based substrates, respectively. Figure 9 shows the gas-sensing characteristics measured under exposure to acetone in the 0.1–1.25 ppm range. The resistance changes are presented in Fig. 9a and sensitivity vs. operating temperature in Fig. 9b. As can be observed in Fig. 9b, the higher responses have been obtained for Kapton-based gas sensors, which is mostly related to different growth of the gas-sensitive layer on the Kapton foil in comparison with alumina substrate. The different growth impacts to higher surface to volume ratio. Moreover, the main goal was to reduce the operating temperature to the minimum, which will reduce the power consumption in the gas detectors.

Our main goal was to develop sensors able to detect acetone in the ‘healthy’ and ‘diabetic’ range, which is 0.2–0.8 ppm and over 2 ppm, respectively. The resistance changes of the CuO-based Kapton sensor under exposure to acetone in the 0.05–0.8 ppm range are presented in Fig. 10a. As can be noticed, sensors exhibited limit of detection as low as 0.05 ppm, and good response is obtained in the 0.05–0.8 ppm acetone range. The calibration curve for the sensor is presented in Fig. 10b. Moreover, the exhaled breath consists of highly concentrated humidity. We therefore measured gas sensors response under exposure to various humidity concentrations (Fig. 11). As shown in Fig. 11, the Kapton-based CuO gas sensors are slightly sensitive to humidity changes in the 50–150 °C temperature range. The alumina-based CuO gas sensors are less sensitive to humidity in the same range; however, these sensors are not sensitive to acetone below 250 °C (Fig. 9b). While these developed sensors could be used with success for the exhaled acetone detection, the relative humidity level needs to be measured at the same time, and the final response has to be corrected for it.

Exhaled acetone is considered to be a biomarker of diabetes, which is why gas sensors with a limit of detection in the sub-ppm range are of high interest. We must emphasize...
that there are so far no commercially available sensors for acetone detection in the ‘diabetic’ and ‘healthy’ regimes. Additionally, sensors with flexible construction can be used to develop other novel sensing devices, which can be easily integrated into electronic devices or clothes.

4 Conclusions

We describe the design, preparation, and experimental results for the gas sensors deposited on an elastic substrate. Our results demonstrate that electrodes aerosol jet printed on flexible substrates are suitable for the fabrication of gas sensors with metal oxides based gas-sensitivity layers. Kapton-based CuO gas sensor exhibited a sub-ppm detection limit for acetone at 150 °C temperature. Sensors were tested under exposure to other compounds, such as hydrogen and propane; however, the responses obtained for those gases were below 3%. Future work will focus on the application for portable devices for diabetes diagnostics. The design of multi-sensor matrix on the elastic substrate is a key problem for the construction of such devices. One of the designs described in this paper is currently patent pending [23]. The mechanical test confirmed a possibility of utilizing such sensors in a portable application.

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Compliance with Ethical Standards

Conflicts of interest The authors declare no conflict of interest.

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