Method of Estimation of Turbulence Integral Parameters

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Abstract: The optical effects of turbulence are directly related to turbulence integral parameters, which are integrals of the refractive index structure constant over a whole path with different path-weighting functions (PWFs). We describe a method that utilizes measurable turbulence integral parameters, such as angle-of-arrival fluctuations and scintillation, to estimate turbulence integral parameters that cannot be measured directly. The estimates of the turbulence integral parameters are based on the linear combination of the PWFs of those measurable quantities. New measurable quantities and their PWFs under different propagation conditions were studied. Some interesting and meaningful results have been obtained. This method shows the prospect of characterizing anisoplanatism in adaptive optics and allows for the estimation of some optical turbulence parameters under non-ideal conditions, such as an isoplanatic angle in a finite distance.

Keywords: atmospheric optics; atmospheric turbulence; remote sensing and sensors; statistical optics

1. Introduction

A wave propagating through a turbulent atmosphere is subject to perturbations of its phase and amplitude due to the fluctuations of the refractive index along the whole propagation path. These perturbations, known as wavefront distortions, severely influence the performance of optical systems that operate in or through the atmosphere, such as adaptive optics systems, interferometers, optical wireless communication systems, and laser radar systems [1–3]. Therefore, it is important to understand how the effects of atmospheric turbulence on the propagation of a light wave can be quantified.

Clearly, the turbulence strength at each position of the propagation path contributes to the wavefront distortion. Therefore, the optical turbulence parameters that describe the optical effects of turbulence are often related to turbulence integral parameters, i.e., integrals of the refractive index structure constant $C_n^2(z)$ ($z$ denotes the position along the propagation path with the receiver plane at $z = 0$) over a whole path with different path-weighting functions (PWFs). For example, the atmospheric coherence length for plane waves $r_0,p$ has a PWF of $z^0$, the atmospheric coherence length for spherical waves $r_0,s$ has a PWF of $(L-z)^{5/3}$, and the isoplanatic angle $\theta_0$ has a PWF of $z^{5/3}$ [3]. In a practical situation, these optical turbulence parameters are often measured indirectly using only one measurable turbulence integral parameter, such as in the case of the differential image motion monitor (DIMM) [4], where angle-of-arrival fluctuations are measured, and in the case of the stellar scintillation isoplanometer [5,6], where intensity fluctuations (scintillation) are measured. However, in many applications, some of the desired optical turbulence parameters cannot be estimated using only one measurable quantity, especially due to the anisoplanatic problems in adaptive optics [7–8], where the expression of related PWFs is more complex and can only be evaluated numerically. For example, in the angular or focal anisoplanatic problems in adaptive optics, the PWF of the effective phase variance (the total phase variance with the piston removed or both the piston and the tilt removed) is neither $z^n$ nor $z^{5/3}$, so it cannot be estimated properly by $r_0$ or $\theta_0$ [7–9].
In this paper, we relate the optical effects of turbulence to the path-weighting functions (PWFs) and describe a method (referred to as the linear combination method) that uses more than one measurable turbulence integral quantity to estimate the turbulence integral parameters that cannot be measured directly. We generalize the PWFs of measurable integral parameters and investigate their characteristics in both a plane wave model and a spherical wave model for the common case where one source is used and the receive apertures are unobscured circles. Some interesting and meaningful results have been obtained. These results may enable us to measure \( r_0 \) not only at near-field but also at far-field using the covariance of tilt, and to measure \( \theta_{TA} \) using a small-aperture telescope instead of a large-aperture telescope using the covariance of intensity rather than scintillation.

2. Materials and Methods

The turbulence integral parameter noted as \( P \) is written as follows:

\[
P = CL \int_0^1 C_n^2(uL)W(u)du
\]  

(1)

where \( C \) is a constant related to \( P \), \( L \) is the propagation path length through turbulence, \( C_n^2 \) is the turbulence strength, \( W(u) \) is the PWF, and \( u = z/L \) denotes the normalized position along the path with propagation from \( u = 1 \) to \( u = 0 \) at the receiver. The principle of the linear combination method is that any linear combination of turbulence integral parameters corresponds to the linear combination of their PWFs. The desired integral parameter \( P_d \) can be estimated from measurable integral parameters \( P_i \) if only the PWF of \( P_d \), noted as \( W_d(u) \), can be approximated by linear combination of the PWFs of \( P_i \), noted as \( W_i(u) \), i.e.,

\[
W_d(u) \approx \sum_{i=1}^{N} a_i W_i(u)
\]  

(2)

where \( a_i \) are the coefficients of \( W_i(u) \), and \( N \) is the number of measurable integral parameters used in this method. In practical applications, one should first select a suitable \( W_i(u) \) based on the shape of \( W_d(u) \) and then fit \( W_i(u) \) to \( W_d(u) \) using the least square fitting method. Equation (2) shows that the more measurable integral parameters and their PWFs we know, the more desired PWFs we can approximate using this method and, thus, the more integral parameters we can estimate. Therefore, it is important to investigate more measurable quantities and their PWFs.

Atmospheric turbulence causes phase and amplitude perturbations, and at present, only the tilt phase and piston amplitude, corresponding to the angle of arrival and the intensity of the light collected with an aperture, can be measured directly and relatively easily. In practice, the variance of the angle of arrival and the variance of intensity are used to obtain turbulence information through their PWFs, which is exactly the case in the DIMM and the stellar scintillation isoplanometer, respectively. However, the covariance functions for the angle of arrival or intensity provide more turbulence information due to their potentially large number of PWFs. The covariance of the tilt phase can be measured from the covariance of the angle of arrival [3,4], and the covariance of the piston amplitude can be measured from the covariance of intensity [6,10].

Assuming the Rytov approximation and Kolmogorov turbulence, using the analytic approach developed by Sasiela [3], the covariance functions for the phase and the log-amplitude related quantities can be derived as follows:

\[
\begin{bmatrix}
C_{\phi}(d) \\
C_{\chi}(d)
\end{bmatrix} = 0.132\pi^2k^2L \int_0^1 C_n^2(uL) \begin{bmatrix}
W_{C,\phi}(u) \\
W_{C,\chi}(u)
\end{bmatrix} du
\]  

(3)

where \( \phi \) and \( \alpha \) denote the phase and the log-amplitude related quantities, respectively; \( d \) is the center-to-center distance of two receive apertures; the optical wavenumber \( k = 2\pi/\lambda \),
where \( \lambda \) is the wavelength of the observed beacon; and \( W_{C,\phi}(u) \) and \( W_{C,\chi}(u) \) are path-weighting functions which are given by the following:

\[
\begin{bmatrix}
W_{C,\phi}(u) \\
W_{C,\chi}(u)
\end{bmatrix} = \int_0^\infty xf(\kappa) j_0(\gamma \kappa d) \kappa^{-1/3} \left[ \frac{\cos^2 \left( \frac{\kappa^2 uL}{2x} \right)}{\sin^2 \left( \frac{\kappa^2 uL}{2x} \right)} \right] \, d\kappa
\]  

(4)

where \( \kappa \) is the spatial wavenumber transverse to the \( z \) direction; \( \gamma \) is the propagation parameter, which depends on the geometric divergence of the light wave and has the simple value of \( \gamma = 1 \) for plane waves and \( \gamma = 1 - z/L \) for spherical waves; \( j_n \) is the \( n \)th order Bessel function of the first kind; and \( F(\gamma \kappa) \) is the filter function, which depends on propagation geometry, such as the size of the receive aperture and the distributed source, and measured related quantities, such as the tilt phase or piston amplitude. For circular apertures with diameter \( D \), the filter function for Zernike tilt and piston are as follows [3]:

\[
F_t(\gamma \kappa) = \left[ 8 J_2(\gamma \kappa D/2)/\gamma \kappa D \right]^2 \text{ (Tilt)}
\]

(5)

\[
F_p(\gamma \kappa) = \left[ 4 J_1(\gamma \kappa D/2)/\gamma \kappa D \right]^2 \text{ (Piston)}
\]

(6)

For a uniformly illuminated circular source with diameter \( D_s \) located at a distance \( L_s \), considering that the uniform circular source consists of incoherent point beacons, the source filter function is as follows [3]:

\[
F_s(\gamma \kappa) = \left[ 4L_s J_1(\kappa D_s z/2L_s)/\kappa D_s z \right]^2
\]

(7)

The final filter function is the product of any produced filter functions. Make a change to the variables by replacing \( \kappa D \) with \( x \) and use the replacement \( F_N = D^2/\lambda L \), where \( F_N \) is the Fresnel number, to simplify the final expression of the PWFs for the tilt phase (i.e., substituting \( F(\gamma \kappa) = F_t(\gamma \kappa) * F_s(\gamma \kappa) \) into Equation (4)) and piston amplitude (i.e., substituting \( F(\gamma \kappa) = F_p(\gamma \kappa) * F_s(\gamma \kappa) \) into Equation (4)), noted as \( W_{C,T}(u) \), \( W_{C,P}(u) \), to the following:

\[
\begin{bmatrix}
W_{C,T}(u) \\
W_{C,P}(u)
\end{bmatrix} = D^3 \int_0^\infty \left[ \frac{8 J_2(\gamma \kappa x/2)/\gamma \kappa x}{4 J_1(\gamma \kappa x/2)/\gamma \kappa x} \right]^2 \left[ \frac{2 J_1(\frac{uL_s D}{4LD_s})}{\sin^2 \left( \frac{x \gamma u L_s}{4LD_s} \right)} \right] j_0(\gamma \kappa D/2) x^{-\frac{3}{2}} \left[ \frac{\cos^2 \left( \frac{x \gamma u L_s}{4LD_s} \right)}{\sin^2 \left( \frac{x \gamma u L_s}{4LD_s} \right)} \right] \, dx
\]

(8)

From Equation (8), it is clear that the PWFs for the tilt phase and piston amplitude depend on four variables: \( \gamma, d/D, F_N, \) and \( D_s/L_s \) (i.e., the ratio of the angular diameter of the source to that of the receive aperture observed at plane \( z = L \)). In the following sections \( D_s/L_s \) will be noted as \( R \) for simplicity. Any change in these four variables will result in a new PWF. Obviously, we can obtain more PWFs by using the covariance function instead of the variance function, which is the special case of the covariance function for \( d = 0 \). The geometry and variables of the covariance functions are shown in Figure 1 for reference.

For convenience later, denote \( W_T(u) \) as the normalized PWF for the covariance of the tilt phase, and \( W_P(u) \) as the normalized PWF for the covariance of piston amplitude. To obtain qualitative knowledge of the effects of these four variables on the PWFs, next we will give the PWFs in a range of typical conditions by numerical evaluation.
3. Results
3.1. PWFs for Plane Waves

Consider Plane Waves (Ls Well above the Turbulent Atmosphere) for Which γ = 1. W_T(u) for Different d, F_N, and R is Plotted in Figure 2.

![Figure 1. The geometry and variables for the covariance functions.](image)

![Figure 2. Normalized path-weighting function W_T(u) for plane waves. (a) Point sources with various F_N (F_N = D^2/\lambda L) and d (the distance between the aperture centers) values. (b) Distributed sources with various R (R = D_S L/\lambda L_S) and d values when F_N = 1.](image)

For a point source such as a star, for which R = 0, the W_T(u) for different F_N and d values is shown in Figure 2a. It can be seen that F_N influences the PWF of the tilt phase variance (W_T(u) for d = 0) as expected. Due to the effect of diffraction [3,4], the W_T(u) for d = 0 decreases slowly with u, which deviates from the near-field value that is constant along the path, and the deviation becomes notable when F_N < 1, suggesting that the smaller the F_N is, the bigger the deviation is. This explains why the DIMM operates at the near-field...
approximation (big \( F_N \)). Comparing \( W_T(u) \) for \( F_N = 1, d = 0D \) (dash line) and \( F_N = 1, d = 2D \) (dash dot line) shows that the effect of diffraction on the tilt covariance is far smaller than that on the tilt variance, which indicates that the effect of diffraction appears to be partly counteracted by the covariance term \( I_d(\gamma \kappa d/D) \) (see Equation (8)). For a distributed source such as a planet, the \( W_T(u) \) for different \( R \) and \( d \) values with a fixed Fresnel number \( F_N = 1 \) is shown in Figure 2b. It can be seen that the \( W_T(u) \) for \( d = 0 \) decreases significantly with \( u \). For larger \( R \) values, the downward trend of \( W_T(u) \) is more obvious (dot line versus solid line). By comparing the \( W_T(u) \) for \( d = 0 \) and \( d = 2D \) with the same \( R \) value, again we can see that the effect of diffraction on the tilt covariance is smaller than that on the tilt variance.

For plane waves, the \( W_P(u) \) values for different \( d, F_N, \) and \( R \) values are plotted in Figure 3.

![Figure 3](image-url)  

**Figure 3.** Normalized path-weighting function \( W_P(u) \) for the covariance of piston amplitude for plane waves. (a) Point sources with various \( F_N \) (\( F_N = D^2/\lambda L \)) and \( d \) (the distance between the aperture centers) values. (b) Distributed sources with various \( R \) (\( R = D_3L/DL_3 \)) and \( d \) values when \( F_N = 1 \).

For a point source such as a star, for which \( R = 0 \), the \( W_P(u) \) for different \( F_N \) and \( d \) values is shown in Figure 3a. It can be seen immediately that the asymptotic behavior of the \( W_P(u) \) for \( d = 0 \) with respect to \( F_N \) is consistent with well-known asymptotic behavior [5], i.e., the PWFs of stellar scintillations (\( W_P(u) \) for \( d = 0 \)) are approximate to \( u^{5/6} \) for a small \( D \) (i.e., small \( F_N \) when \( \lambda L \) is fixed) and \( u^2 \) for a large \( D \). When the selected \( F_N \) is satisfactory (approximately equals one, dash line), the \( W_P(u) \) for \( d = 0 \) is approximate to \( u^{5/3} \), which is needed to calculate the isoplanatic angle [5,6]. In Figure 3a, there is a remarkable place where the curves of \( W_P(u) \) for \( d = 0.5D, F_N = 1 \) and \( d = 0D, F_N = 5 \) seem almost identical, both approximating \( u^2 \), which is needed to calculate the tilt isoplanatic angle (\( \theta_{TA} \)) [1,3]. For a distributed source such as the sun or a planet, the \( W_P(u) \) for different \( R \) and \( d \) values with a fixed Fresnel number \( F_N = 1 \) is shown in Figure 3b. It can be seen that the peak position of \( W_P(u) \) with the same \( d \) value moves toward the start of the path with the increase in the \( R \) value, and that the peak position of \( W_P(u) \) with the same \( R \) value shifts slightly toward the end of the path with the increase in the \( d \) value. When the receiver size \( D \) is very small and the distributed source is the sun or the moon, we will obtain the PWFs that are used in SHABAR [11] (SHAdow BAnd and Ranging) or LuSci [12] (Lunar Scintillometer), both of which are used to measure surface layer turbulence.

3.2. PWFs for Spherical Waves

Now Consider Spherical Waves (i.e., \( L_S \) equal to \( L \)) for Which \( \gamma = 1 - u \). \( W_T(u) \) for Different \( d, F_N, \) and \( R \) is Plotted in Figure 4.
Figure 4. Normalized path-weighting function for spherical waves. (a) Point sources with various $F_N (F_N = D^2/\lambda L)$ and $d$ (the distance between aperture centers) values. (b) Distributed sources with various $R (R = D_5/L_5)$ and $d$ values when $F_N = 1$.

For a point source, the $W_T(u)$ for different $F_N$ and $d$ values is shown in Figure 4a. Not surprisingly, for $d = 0$, the $W_T(u)$ for a large $F_N$ value (dot line) has the form $(1-u)^{5/3}$ that can be used to measure $r_{0_5}$; the $W_T(u)$ for a small $F_N$ value deviates slightly from $(1-u)^{5/3}$ due to the effect of diffraction. The two curves of $W_T(u)$ for $d = 0D$, $F_N = 5$ and $d = 2D$, $F_N = 1$ almost coincide with each other, as the effect of diffraction on the tilt covariance is smaller than that on the variance. For a distributed source, the $W_T(u)$ for different $R$ and $d$ values and a fixed Fresnel number $F_N = 1$ is shown in Figure 4b. It can be seen that the $W_T(u)$ for a finite-size source deviates significantly from $(1-u)^{5/3}$; therefore, the larger the $R$ value is, the faster the decline in $W_T(u)$ is. When comparing the $W_T(u)$ for $d = 0$ and $d = 2D$, again we can see that the effect of diffraction on the tilt covariance is smaller than that on the tilt variance.

For spherical waves, $W_P(u)$ for different $d$, $F_N$ and $R$ values are plotted in Figure 5.

Figure 5. Normalized path-weighting function for the covariance of piston amplitude $W_P(u)$ for spherical waves. (a) Point sources with various $F_N (F_N = D^2/\lambda L)$ and $d$ (the distance between aperture centers) values. (b) Distributed sources with various $R (R = D_5/L_5)$ and $d$ values when $F_N = 1$. 

One can see that the peak position of $W_P(u)$ for fixed $d$ and $R$ values moves towards the end of the path with an increasing $F_N$ value, as shown in Figure 5a; that the peak position of $W_P(u)$ for fixed $F_N$ and $d$ values moves towards the start of the path with an increasing $R$ value, as shown in Figure 5b; and that the peak position of $W_P(u)$ for fixed $F_N$ and $R$ values moves towards the end of the path with an increasing $d$ value, as shown in Figure 5a,b.

4. Discussion

From the above numerical results, we can see how each of the four variables ($\gamma, d/D, F_N$, and $R$) influence the curve shapes of PWFs, which is helpful in the creation of a desired PWF using the linear combination method (Equation (2)). When we focused on the PWFs for different $F_N$ values without changing the other variables, we found that the effect of diffraction on the covariance of the tilt phase or piston amplitude is far smaller than that on the variance.

Note that the PWFs investigated here only considered the common case where one source is used and the receive apertures are unobscured circles. When the shape of the receive aperture is changed or two sources are used, the curve shapes of the related PWFs will also change, as in the case of MASS [13] (Multi-Aperture Scintillation Sensor), where the receive aperture is annulus, or SloDAR [14] (Slope Detection And Ranging) and SciDAR [15,16] (Scintillation Detection And Ranging), where two sources are used. Thus, there are potentially a large number of various $W_i(u)$ values that we can obtain, which would make the linear combination method more powerful.

In some applications, the PWFs of $P_d$ (the desired turbulence integral parameter) have complex analytic expressions, most of which can only be evaluated numerically, and $P_d$ is often difficult to measure at present. For example, in the angular or focal anisoplanatic problems in adaptive optics, the effective phase variance $\sigma_{\text{Eff}}^2$ (the total phase variance $\sigma_\phi^2$ with the piston removed or both the piston $\sigma_p^2$ and the tilt $\sigma_{TA}^2$ removed, i.e., $\sigma_{\text{Eff}}^2 = \sigma_\phi^2 - \sigma_p^2 - \sigma_{TA}^2$) is such a $P_d$ [3,7–9]. For natural guide star adaptive optics (NGS AO), it is well known that $\sigma_\phi^2 = (\theta/\theta_0)^{5/3}$, and one can easily derive $\sigma_{\text{Eff}}^2 = 4.25 \sigma_{TA}^2 = 4.25 (\theta/\theta_{TA})^2$ for small angles, where $\theta_{TA}$ is the tilt isoplanatic angle [1,3,17]. Therefore, if $\theta_{TA}$ can be measured along with $\theta_0$, one can obtain the effective phase variance in NGS AO using the relationship $\sigma_{\text{Eff}}^2 = (\theta/\theta_0)^{5/3} - 4.25(\theta/\theta_{TA})^2$. As far as we know, the direct measurement of $\theta_{TA}$ has not been reported. Based on the linear combination method proposed in this paper, we have proposed one direct measurement scheme of $\theta_{TA}$ in our other accompanying manuscript [18].

In some other applications, though expressions for the PWF of $P_d$ are simple, it cannot be measured under non-ideal conditions. For example, $r_{0,p}$ and $\theta_0$ in a finite distance cannot be measured using the conventional method (DIMM and stellar scintillation isoplanometer) since the light wave propagating in the turbulence path is not a plane wave. Generally, the light wave is a spherical wave for a point beacon in a finite distance. Then, the parameter measured using DIMM is actually $r_{0,s}$ rather than $r_{0,p}$, and the parameter measured using the conventional isoplanometer has a PWF with a curve shape similar to the red dashed line in Figure 5a rather than the red dashed line in Figure 3a (i.e., the well-known $u^{5/3}$).

The linear combination method shows promise of estimating the real-time $P_d$ with high accuracy if the suitable $W_i(u)$ can be found. As an application example of this method, one can measure the isoplanatic angle in a finite distance through the combination of one spherical wave scintillation and two covariances of intensity in three receive apertures [10], and the validity of this method was proven by real data from the validation experiment [19].

One can also roughly estimate $P_d$ through the optical turbulence profile obtained from those turbulence profilers [12–16]. Nevertheless, the linear combination method offers another feasible solution.
5. Conclusions

It was found that the path-weighting functions (PWFs) for covariance depend on four variables: $\gamma, d/D, F_N$, and $D_S/L_D$. In other words, the optical effects of turbulence are influenced by not only the turbulence strength but also these four variables. Numerical results show that the effect of diffraction on the variance of the tilt phase or piston amplitude is more significant than it is on the covariance, e.g., the two curves of $W_T(u)$ for $d = 0D, F_N = 5$ and $d = 2D, F_N = 1$ almost coincide with each other, and it is possible to measure the tilt isoplanatic angle through the covariance of intensity rather than scintillation. More specifically, the curve of the PWFs for the tilt phase shifts upwards as the value of $d/D$ or $F_N$ increases, or the value of $R (R = D_S/L_D)$ decreases (see Figures 2 and 4). The peak position of $W_P(u)$ shifts to the start of the path as the value of $d/D$ or $F_N$ decreases, or the value of $R$ increases (see Figures 3 and 5).

In the future, work will be conducted to prove the validity of measuring the tilt isoplanatic angle through the covariance of intensity and to investigate more suitable PWFs for practical applications. The linear combination method is an effective and powerful method for measuring the turbulence integral parameters of interest as there are a potentially large number of various PWFs that we can obtain.

Author Contributions: Conceptualization, H.S. and L.Y.; methodology, H.S. and L.Y.; formal analysis, H.S., L.Y., and X.J.; investigation, F.T.; resources, X.J.; data curation, F.T.; writing—original draft preparation, H.S.; writing—review and editing, L.Y.; funding acquisition, H.S. and L.Y. All authors have read and agreed to the published version of the manuscript.

Funding: This research was funded by the National Natural Science Foundation of China, grant numbers 61665004 and 41605007.

Institutional Review Board Statement: Not applicable.

Informed Consent Statement: Not applicable.

Data Availability Statement: The data presented in this study are available on request from the corresponding author.

Conflicts of Interest: The authors declare no conflict of interest.

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