Fundamental Solution of Laplace’s Equation in Hyperspherical Geometry

Howard S. COHL †‡

† Applied and Computational Mathematics Division, Information Technology Laboratory, National Institute of Standards and Technology, Gaithersburg, Maryland, USA
E-mail: howard.cohl@nist.gov

‡ Department of Mathematics, University of Auckland, 38 Princes Str., Auckland, New Zealand
URL: http://hcohl.sdf.org

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Abstract. Due to the isotropy of \(d\)-dimensional hyperspherical space, one expects there to exist a spherically symmetric fundamental solution for its corresponding Laplace–Beltrami operator. The \(R\)-radius hypersphere \(S^d_R\) with \(R > 0\), represents a Riemannian manifold with positive-constant sectional curvature. We obtain a spherically symmetric fundamental solution of Laplace’s equation on this manifold in terms of its geodesic radius. We give several matching expressions for this fundamental solution including a definite integral over reciprocal powers of the trigonometric sine, finite summation expressions over trigonometric functions, Gauss hypergeometric functions, and in terms of the associated Legendre function of the second kind on the cut (Ferrers function of the second kind) with degree and order given by \(d/2 - 1\) and \(1 - d/2\) respectively, with real argument between plus and minus one.

Key words: hyperspherical geometry; fundamental solution; Laplace’s equation; separation of variables; Ferrers functions

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1 Introduction

We compute closed-form expressions of a spherically symmetric Green’s function (fundamental solution of Laplace’s equation) for a \(d\)-dimensional Riemannian manifold of positive-constant sectional curvature, namely the \(R\)-radius hypersphere with \(R > 0\). This problem is intimately related to the solution of the Poisson equation on this manifold and the study of spherical harmonics which play an important role in exploring collective motion of many-particle systems in quantum mechanics, particularly nuclei, atoms and molecules. In these systems, the hyperradius is constructed from appropriately mass-weighted quadratic forms from the Cartesian coordinates of the particles. One then seeks either to identify discrete forms of motion which occur primarily in the hyperradial coordinate, or alternatively to construct complete basis sets on the hypersphere. This representation was introduced in quantum mechanics by Zernike & Brinkman [37], and later invoked to greater effect in nuclear and atomic physics, respectively, by Delves [5] and Smith [31]. The relevance of this representation to two-electron excited states of the helium atom was noted by Cooper, Fano & Prats [4]; Fock [10] had previously shown that the hyperspherical representation was particularly efficient in representing the helium wavefunction in the vicinity of small hyperradii. There has been a rich literature of applications ever since. Examples include Zhukov [38] (nuclear structure), Fano [9] and Lin [24] (atomic structure), and Pack & Parker [28] (molecular collisions). A recent monograph by Berakdar [2] discusses hyperspherical harmonic methods in the general context of highly-excited electronic systems. Useful background material relevant for the mathematical aspects of this paper can be found in [22, 33, 35]. Some historical references on this topic include [17, 23, 29, 30, 36].
This paper is organized as follows. In Section 2 we describe hyperspherical geometry and its corresponding metric, global geodesic distance function, Laplacian and hyperspherical coordinate systems which parametrize points on this manifold. In Section 3 for hyperspherical geometry, we show how to compute ‘radial’ harmonics in a geodesic polar coordinate system and derive several alternative expressions for a ‘radial’ fundamental solution of the Laplace’s equation on the $R$-radius hypersphere.

Throughout this paper we rely on the following definitions. For $a_1, a_2, \ldots \in \mathbb{C}$, if $i, j \in \mathbb{Z}$ and $j < i$ then $\sum_{n=1}^{j} a_n = 0$ and $\prod_{n=1}^{j} a_n = 1$. The set of natural numbers is given by $\mathbb{N} := \{1, 2, 3, \ldots\}$, the set $\mathbb{N}_0 := \{0, 1, 2, \ldots\} = \mathbb{N} \cup \{0\}$, and the set $\mathbb{Z} := \{0, \pm 1, \pm 2, \ldots\}$.

2 Hyperspherical geometry

The Euclidean inner product for $\mathbb{R}^{d+1}$ is given by $(x, y) = x_0 y_0 + x_1 y_1 + \cdots + x_d y_d$. The variety $(x, x) = x_0^2 + x_1^2 + \cdots + x_d^2 = R^2$, for $x \in \mathbb{R}^{d+1}$ and $R > 0$, defines the $R$-radius hyperspheres $S^d_R$. We denote the unit radius hypersphere by $S^d := S^d_1$. Hyperspherical space in $d$-dimensions, denoted by $S_R^d$, is a maximally symmetric, simply connected, $d$-dimensional Riemannian manifold with positive-constant sectional curvature (given by $1/R^2$, see for instance [22, p. 148]), whereas Euclidean space $\mathbb{R}^d$ equipped with the Pythagorean norm, is a Riemannian manifold with zero sectional curvature.

Points on the $d$-dimensional hypersphere $S^d_R$ can be parametrized using subgroup-type coordinate systems, i.e., those which correspond to a maximal subgroup chain $O(d) \supset \cdots$ (see for instance [18, 20]). The isometry group of the space $S^d_R$ is the orthogonal group $O(d)$. Hyperspherical space $S^d_R$, can be identified with the quotient space $O(d)/O(d-1)$. The isometry group $O(d)$ acts transitively on $S^d_R$. There exist separable coordinate systems on the hypersphere, analogous to parabolic coordinates in Euclidean space, which can not be constructed using maximal subgroup chains. Polyspherical coordinates, are coordinates which correspond to the maximal subgroup chain given by $O(d) \supset \cdots$. What we will refer to as standard hyperspherical coordinates, correspond to the subgroup chain given by $O(d) \supset O(d-1) \supset \cdots \supset O(2)$. (For a thorough discussion of polyspherical coordinates see Section IX.5 in [35].) Polyspherical coordinates on $S^d_R$ all share the property that they are described by $(d+1)$-variables: $R \in [0, \infty)$ plus $d$-angles each being given by the values $[0, 2\pi)$, $[0, \pi]$, $[-\pi/2, \pi/2]$ or $[0, \pi/2)$ (see [18, 19]).

In our context, a useful subset of polyspherical coordinate are geodesic polar coordinates $(\theta, \hat{x})$ (see for instance [27]). These coordinates, which parametrize points on $S^d_R$, have origin at $O = (R, 0, \ldots, 0) \in \mathbb{R}^{d+1}$ and are given by a ‘radial’ parameter $\theta \in [0, \pi]$ which parametrizes points along a geodesic curve emanating from $O$ in a direction $\hat{x} \in S^{d-1}$. Geodesic polar coordinate systems partition $S^d_R$ into a family of $(d-1)$-dimensional hyperspheres, each with a ‘radius’ $\theta := \theta_d \in (0, \pi)$, on which all possible hyperspherical coordinate systems for $S^{d-1}$ may be used (see for instance [35]). One then must also consider the limiting case for $\theta = 0, \pi$ to fill out all of $S^d_R$. Standard hyperspherical coordinates (see [21, 25]) are an example of geodesic polar coordinates, and are given by

\[
\begin{align*}
 x_0 &= R \cos \theta, \\
 x_1 &= R \sin \theta \cos \theta_{d-1}, \\
 x_2 &= R \sin \theta \sin \theta_{d-1} \cos \theta_{d-2}, \\
 &\vdots \\
 x_{d-2} &= R \sin \theta \sin \theta_{d-1} \cdots \cos \theta_2, \\
 x_{d-1} &= R \sin \theta \sin \theta_{d-1} \cdots \sin \theta_2 \cos \phi, \\
 x_d &= R \sin \theta \sin \theta_{d-1} \cdots \sin \theta_2 \sin \phi,
\end{align*}
\]

$\theta_i \in [0, \pi]$ for $i \in \{2, \ldots, d\}$, $\theta := \theta_d$, and $\phi \in [0, 2\pi)$.
In order to study a fundamental solution of Laplace’s equation on the hypersphere, we need to describe how one computes the geodesic distance in this space. Geodesic distances on \( S^d_R \) are simply given by arc lengths, angles between two arbitrary vectors, from the origin in the ambient Euclidean space (see for instance [22, p. 82]). Any parametrization of the hypersphere \( S^d_R \), must have \((x, x) = x_0^2 + \cdots + x_d^2 = R^2\), with \( R > 0 \). The distance between two points \( x, x' \in S^d_R \) on the hypersphere is given by

\[
d(x, x') = R \gamma = R \cos^{-1} \left( \frac{(x, x')}{(x, x)(x', x')} \right) = R \cos^{-1} \left( \frac{1}{R^2} (x, x') \right).
\]  

(2)

This is evident from the fact that the geodesics on \( S^d_R \) are great circles, i.e., intersections of \( S^d_R \) with planes through the origin of the ambient Euclidean space, with constant speed parametrizations.

In any geodesic polar coordinate system, the geodesic distance between two points on the submanifold is given by

\[
d(x, x') = R \cos^{-1} \left( \frac{1}{R^2} (x, x') \right) = R \cos^{-1} (\cos \theta \cos \theta' + \sin \theta \sin \theta' \cos \gamma),
\]

(3)

where \( \gamma \) is the unique separation angle given in each polyspherical coordinate system used to parametrize points on \( S^{d-1} \). For instance, the separation angle \( \gamma \) in standard hyperspherical coordinates is given through

\[
\cos \gamma = \cos(\phi - \phi') \prod_{i=1}^{d-2} \sin \theta_i \sin \theta'_i + \sum_{i=1}^{d-2} \cos \theta_i \cos \theta'_i \prod_{j=1}^{i-1} \sin \theta_j \sin \theta'_j.
\]

(4)

Corresponding separation angle formulae for any hyperspherical coordinate system used to parametrize points on \( S^{d-1} \) can be computed using (2) and the associated formulae for the appropriate inner-products.

One can also compute the Riemannian (volume) measure \( d\text{vol}_g \) (see for instance Section 3.4 in [16]), invariant under the isometry group \( SO(d) \), of the Riemannian manifold \( S^d_R \). For instance, in standard hyperspherical coordinates (1) on \( S^d_R \) the volume measure is given by

\[
d\text{vol}_g = R^d \sin^{d-1} \theta \, d\theta \, d\omega := R^d \sin^{d-1} \theta \, d\theta \, \sin^{d-2} \theta_{d-1} \cdots \sin \theta_2 \, d\theta_1 \cdots d\theta_{d-1}.
\]

(5)

The distance \( r \in [0, \infty) \) along a geodesic, measured from the origin, is given by \( r = \theta R \). To show that the above volume measure (5) reduces to the Euclidean volume measure at small distances (see for instance [21]), we examine the limit of zero curvature. In order to do this, we take the limit \( \theta \to 0^+ \) and \( R \to \infty \) of the volume measure (5) which produces

\[
d\text{vol}_g \sim R^{d-1} \sin^{d-1} \left( \frac{r}{R} \right) \, dr \, d\omega \sim r^{d-1} \, dr \, d\omega,
\]

which is the Euclidean measure in \( \mathbb{R}^d \), expressed in standard Euclidean hyperspherical coordinates. This measure is invariant under the Euclidean motion group \( E(d) \).

It will be useful below to express the Dirac delta function on \( S^d_R \). The Dirac delta function on the Riemannian manifold \( S^d_R \) with metric \( g \) is defined for an open set \( U \subset S^d_R \) with \( x, x' \in S^d_R \) such that

\[
\int_U \delta_g(x, x') \, d\text{vol}_g = \begin{cases} 1 & \text{if } x' \in U, \\ 0 & \text{if } x' \notin U. \end{cases}
\]

(6)

For instance, using (5) and (6), in standard hyperspherical coordinates on \( S^d_R \) (1), we see that the Dirac delta function is given by

\[
\delta_g(x, x') = \frac{\delta(\theta - \theta') \delta(\theta_1 - \theta'_1) \cdots \delta(\theta_{d-1} - \theta'_{d-1})}{R^d \sin^{d-1} \theta' \sin \theta_2' \cdots \sin^{d-2} \theta'_{d-1}}.
\]
2.1 Laplace’s equation on the hypersphere

Parametrizations of a submanifold embedded in Euclidean space can be given in terms of coordinate systems whose coordinates are curvilinear. These are coordinates based on some transformation that converts the standard Cartesian coordinates in the ambient space to a coordinate system with the same number of coordinates as the dimension of the submanifold in which the coordinate lines are curved.

The Laplace–Beltrami operator (Laplacian) in curvilinear coordinates $\xi = (\xi^1, \ldots, \xi^d)$ on a Riemannian manifold is given by

$$\Delta = \sum_{i,j=1}^{d} \frac{1}{\sqrt{|g|}} \frac{\partial}{\partial \xi^i} \left( \sqrt{|g|} g^{ij} \frac{\partial}{\partial \xi^j} \right), \quad (7)$$

where $|g| = |\det(g_{ij})|$, the metric is given by

$$ds^2 = \sum_{i,j=1}^{d} g_{ij} d\xi^i d\xi^j, \quad (8)$$

and

$$\sum_{i=1}^{d} g_{ii} = \delta^i_i,$$

where $\delta^i_i \in \{0, 1\}$ is the Kronecker delta

$$\delta^i_i := \begin{cases} 1 & \text{if } i = j, \\ 0 & \text{if } i \neq j, \end{cases} \quad (9)$$

for $i, j \in \mathbb{Z}$. The relationship between the metric tensor $G_{ij} = \text{diag}(1, \ldots, 1)$ in the ambient space and $g_{ij}$ of (7) and (8) is given by

$$g_{ij}(\xi) = \sum_{k,l=0}^{d} G_{kl} \frac{\partial x^k}{\partial \xi^i} \frac{\partial x^l}{\partial \xi^j}.$$

The Riemannian metric in a geodesic polar coordinate system on the submanifold $S^d_R$ is given by

$$ds^2 = R^2 (d\theta^2 + \sin^2 \theta \ d\gamma^2), \quad (10)$$

where an appropriate expression for $\gamma$ in a curvilinear coordinate system is given. If one combines (1), (4), (7) and (10), then in a geodesic polar coordinate system, Laplace’s equation on $S^d_R$ is given by

$$\Delta f = \frac{1}{R^2} \left[ \frac{\partial^2 f}{\partial \theta^2} + (d-1) \cot \theta \frac{\partial f}{\partial \theta} + \frac{1}{\sin^2 \theta} \Delta_{S^{d-1}} f \right] = 0, \quad (11)$$

where $\Delta_{S^{d-1}}$ is the corresponding Laplace–Beltrami operator on $S^{d-1}$. 
3 A Green’s function on the hypersphere

3.1 Harmonics in geodesic polar coordinates

The harmonics in a geodesic polar coordinate system are given in terms of a ‘radial’ solution (‘radial’ harmonics) multiplied by the angular solution (angular harmonics).

Using polyspherical coordinates on $S^{d-1}$, one can compute the normalized hyperspherical harmonics in this space by solving the Laplace equation using separation of variables. This results in a general procedure which, for instance, is given explicitly in [18, 19]. These angular harmonics are given as general expressions involving trigonometric functions, Gegenbauer polynomials and Jacobi polynomials. The angular harmonics are eigenfunctions of the Laplace–Beltrami operator on $S^{d-1}$ which satisfy the following eigenvalue problem (see for instance (12.4) and Corollary 2 to Theorem 10.5 in [32])

$$\Delta_{S^{d-1}} Y^K_l(\hat{x}) = -l(l + d - 2)Y^K_l(\hat{x}),$$

(12)

where $\hat{x} \in S^{d-1}$, $Y^K_l(\hat{x})$ are normalized angular hyperspherical harmonics, $l \in \mathbb{N}_0$ is the angular momentum quantum number, and $K$ stands for the set of $(d-2)$-quantum numbers identifying degenerate harmonics for each $l$ and $d$. The degeneracy

$$(2l + d - 2)(d - 3 + l)!l!(d-2)!$$

(see (9.2.11) in [35]), tells you how many linearly independent solutions exist for a particular $l$ value and dimension $d$. The angular hyperspherical harmonics are normalized such that

$$\int_{S^{d-1}} Y^K_l(\hat{x})Y^{K'}_{l'}(\hat{x})d\omega = \delta^l_{l'}\delta^K_{K'},$$

where $d\omega$ is the Riemannian (volume) measure on $S^{d-1}$, which is invariant under the isometry group $SO(d)$ (cf. (5)), and for $x + iy = z \in \mathbb{C}$, $\overline{z} = x - iy$, represents complex conjugation. The angular solutions (hyperspherical harmonics) are well-known (see Chapter IX in [35] and Chapter 11 [8]). The generalized Kronecker delta symbol $\delta^K_{K'}$ (cf. (9)) is defined such that it equals 1 if all of the $(d-2)$-quantum numbers identifying degenerate harmonics for each $l$ and $d$ coincide, and equals zero otherwise.

We now focus on ‘radial’ solutions of Laplace’s equation on $S^d_R$, which satisfy the following ordinary differential equation (cf. (11) and (12))

$$\frac{d^2u}{d\theta^2} + (d-1)\cot\theta\frac{du}{d\theta} - \frac{l(l + d - 2)}{\sin^2\theta}u = 0.$$  

(13)

Four solutions of this ordinary differential equation $u_{1\pm}^{d,l}, u_{2\pm}^{d,l} : (-1, 1) \to \mathbb{C}$ are given by

$$u_{1\pm}^{d,l}(\cos\theta) := \frac{1}{(\sin\theta)^{(d-1)/2}}P_{(d-1)/2}^{(d-1)/2}(\cos\theta),$$

and

$$u_{2\pm}^{d,l}(\cos\theta) := \frac{1}{(\sin\theta)^{(d-1)/2}}Q_{(d-1)/2}^{(d-1)/2}(\cos\theta),$$

(14)

where $P_{\nu}^\mu, Q_{\nu}^\mu : (-1, 1) \to \mathbb{C}$ are Ferrers functions of the first and second kind (associated Legendre functions of the first and second kind on the cut). The Ferrers functions of the first
and second kind (see Chapter 14 in [26]) can be defined respectively in terms of a sum over two Gauss hypergeometric functions, for all \( \nu, \mu \in \mathbb{C} \) such that \( \nu + \mu \notin -\mathbb{N} \),

\[
P_{\nu}^{\mu}(x) := \frac{2^{\mu+1}}{\sqrt{\pi}} \sin \left[ \frac{\pi}{2}(\nu + \mu) \right] \frac{\Gamma \left( \frac{\nu + \mu + 2}{2} \right)}{\Gamma \left( \frac{\nu - \mu + 1}{2} \right)} x(1 - x^2)^{-\mu/2} _2F_1 \left( \frac{1 - \nu - \mu}{2}, \frac{\nu - \mu + 2}{2}; \frac{3}{2}; x^2 \right)
+ \frac{2^\mu}{\sqrt{\pi}} \cos \left[ \frac{\pi}{2}(\nu + \mu) \right] \frac{\Gamma \left( \frac{\nu + \mu + 1}{2} \right)}{\Gamma \left( \frac{\nu - \mu + 2}{2} \right)} (1 - x^2)^{-\mu/2} _2F_1 \left( \frac{-\nu - \mu}{2}, \frac{\nu - \mu + 1}{2}; \frac{1}{2}; x^2 \right)
\]

(cf. (14.3.11) in [26]), and

\[
Q_{\nu}^{\mu}(x) := \sqrt{\pi} 2^\mu \cos \left[ \frac{\pi}{2}(\nu + \mu) \right] \frac{\Gamma \left( \frac{\nu + \mu + 2}{2} \right)}{\Gamma \left( \frac{\nu - \mu + 1}{2} \right)} x(1 - x^2)^{-\mu/2} _2F_1 \left( \frac{1 - \nu - \mu}{2}, \frac{\nu - \mu + 2}{2}; \frac{3}{2}; x^2 \right)
- \sqrt{\pi} 2^{\mu-1} \sin \left[ \frac{\pi}{2}(\nu + \mu) \right] \frac{\Gamma \left( \frac{\nu + \mu + 1}{2} \right)}{\Gamma \left( \frac{\nu - \mu + 2}{2} \right)} (1 - x^2)^{-\mu/2} _2F_1 \left( \frac{-\nu - \mu}{2}, \frac{\nu - \mu + 1}{2}; \frac{1}{2}; x^2 \right)
\]

(cf. (14.3.12) in [26]). The Gauss hypergeometric function \( _2F_1 : \mathbb{C} \times \mathbb{C} \times (\mathbb{C} \setminus \mathbb{N}_0) \times \{ z \in \mathbb{C} : \vert z \vert < 1 \} \to \mathbb{C} \), can be defined in terms of the infinite series

\[
_2F_1(a, b; c; z) := \sum_{n=0}^{\infty} \frac{(a)_n (b)_n}{(c)_n n!} z^n
\]

(see (15.2.1) in [26]), and elsewhere in \( z \) by analytic continuation. On the unit circle \( \vert z \vert = 1 \), the Gauss hypergeometric series converges absolutely if \( \text{Re} (c - a - b) \in (0, \infty) \), converges conditionally if \( z \neq 1 \) and \( \text{Re} (c - a - b) \in (-1, 0] \), and diverges if \( \text{Re} (c - a - b) \in (-\infty, -1] \). For \( z \in \mathbb{C} \) and \( n \in \mathbb{N}_0 \), the Pochhammer symbol \((z)_n\) (also referred to as the rising factorial) is defined as (cf. (5.2.4) in [26])

\[
(z)_n := \prod_{i=1}^{n} (z + i - 1).
\]

The Pochhammer symbol (rising factorial) is expressible in terms of gamma functions as (5.2.5) in [26]

\[
(z)_n = \frac{\Gamma(z + n)}{\Gamma(z)},
\]

for all \( z \in \mathbb{C} \setminus -\mathbb{N}_0 \). The gamma function \( \Gamma : \mathbb{C} \setminus -\mathbb{N}_0 \to \mathbb{C} \) (see Chapter 5 in [26]) is an important combinatoric function and is ubiquitous in special function theory. It is naturally defined over the right-half complex plane through Euler’s integral (see (5.2.1) in [26])

\[
\Gamma(z) := \int_{0}^{\infty} t^{z-1} e^{-t} dt,
\]

\( \text{Re} z > 0 \). The Euler reflection formula allows one to obtain values of the gamma function in the left-half complex plane (cf. (5.5.3) in [26]), namely

\[
\Gamma(z)\Gamma(1-z) = \frac{\pi}{\sin \pi z},
\]
0 < \Re z < 1$, for \Re z = 0, \Re z \neq 0, and then for \Re z shifted by integers using the following recurrence relation (see (5.5.1) in [26])

\[ \Gamma(z + 1) = z\Gamma(z). \]

An important formula which the gamma function satisfies is the duplication formula (i.e., (5.5.5) in [26])

\[ \Gamma(2z) = \frac{2^{2z-1}}{\sqrt{\pi}} \Gamma(z)\Gamma\left(z + \frac{1}{2}\right), \] \hspace{1cm} (16)

provided \(2z \not\in -N_0\).

Due to the fact that the space \(S^d_R\) is homogeneous with respect to its isometry group, the orthogonal group \(O(d)\), and therefore an isotropic manifold, we expect that there exist a fundamental solution on this space with spherically symmetric dependence. We specifically expect these solutions to be given in terms of associated Legendre functions of the second kind on the cut with argument given by \(\cos \theta\). This associated Legendre function naturally fits our requirements because it is singular at \(\theta = 0\), whereas the associated Legendre functions of the first kind, with the same argument, is regular at \(\theta = 0\). We require there to exist a singularity at the origin of a fundamental solution of Laplace’s equation on \(S^d_R\), since it is a manifold and must behave locally like a Euclidean fundamental solution of Laplace’s equation which also has a singularity at the origin.

### 3.2 Fundamental solution of the Laplace’s equation on the hypersphere

In computing a fundamental solution of the Laplacian on \(S^d_R\), we know that

\[-\Delta S^d_R(x, x') = \delta_g(x, x'), \] \hspace{1cm} (17)

where \(g\) is the Riemannian metric on \(S^d_R\) (e.g., (10)) and \(\delta_g\) is the Dirac delta function on the manifold \(S^d_R\) (e.g., (6)). In general since we can add any harmonic function to a fundamental solution of Laplace’s equation and still have a fundamental solution, we will use this freedom to make our fundamental solution as simple as possible. It is reasonable to expect that there exists a particular spherically symmetric fundamental solution \(S^d_R\) on the hypersphere with pure ‘radial’, \(\theta := d(x, x')\) (e.g., (3)), and constant angular dependence due to the influence of the point-like nature of the Dirac delta function in (17). For a spherically symmetric solution to the Laplace equation, the corresponding \(\Delta_{S^{d-1}}\) term in (11) vanishes since only the \(l = 0\) term survives in (13). In other words we expect there to exist a fundamental solution of Laplace’s equation on \(S^d_R\) such that \(S^d_R(x, x') = f(\theta)\) (cf. (3)), where \(R\) is a parameter of this fundamental solution.

We have proven that on the \(R\)-radius hypersphere \(S^d_R\), a Green’s function for the Laplace operator (fundamental solution of Laplace’s equation) can be given as follows.

**Theorem 1.** Let \(d \in \{2, 3, \ldots\}\). Define \(\mathcal{I}_d : (0, \pi) \to \mathbb{R}\) as

\[ \mathcal{I}_d(\theta) := \int_0^{\pi/2} \frac{dx}{\sin^{d-1}x}, \]

\(x, x' \in S^d_R\), and \(S^d_R : (S^d_R \times S^d_R) \setminus \{(x, x) : x \in S^d_R\} \to \mathbb{R}\) defined such that

\[ S^d_R(x, x') := \frac{\Gamma(d/2)}{2\pi^{d/2}R^{d-2}} \mathcal{I}_d(\theta), \]
where \( \theta := \cos^{-1}([\hat{x}, \hat{x}']) \) is the geodesic distance between \( \hat{x} \) and \( \hat{x}' \) on the unit radius hypersphere \( S^d \), with \( \hat{x} = x/R, \hat{x}' = x'/R \), then \( S^d_R \) is a fundamental solution for \(-\Delta \) where \( \Delta \) is the Laplace–Beltrami operator on \( S^d_R \). Moreover,

\[
\mathcal{I}_d(\theta) = \begin{cases} 
(\frac{d-3}{2})!! \log \cot \frac{\theta}{2} + \cos \theta \sum_{k=1}^{\frac{d-1}{2}} \frac{(2k-2)!!}{(2k-1)!! \sin^{2k-1} \theta} & \text{if } d \text{ even}, \\
(\frac{d-3}{2})!! \sum_{k=1}^{\frac{d-1}{2}} \frac{(2k-3)!!}{(2k-1)!! \sin^{2k-1} \theta} \cot^{2k-1} \theta & \text{if } d \text{ odd}, \\
\cos \theta \ F_1 \left( \frac{1}{2}, \frac{d-3}{2}; \frac{3}{2}; \cos^2 \theta \right), \\
\sin^{d-2} \theta \ F_1 \left( 1, \frac{3-d}{2}; \frac{3}{2}; \cos^2 \theta \right), \\
\frac{(d-2)!}{\Gamma \left( \frac{d}{2} \right) \frac{2^{d/2-1}}{2} Q_{d/2-1} \left( \cos \theta \right)} & \text{if } d \text{ odd},
\end{cases}
\]

In the rest of this section, we develop the material in order to prove this theorem.

Since a spherically symmetric choice for a fundamental solution satisfies Laplace’s equation everywhere except at the origin, we may first set \( g = f' \) in (11) and solve the first-order equation

\[
g' + (d-1) \cos \theta \ g = 0,
\]

which is integrable and clearly has the general solution

\[
g(\theta) = \frac{df}{d\theta} = c_0 (\sin \theta)^{1-d}, \tag{18}
\]

where \( c_0 \in \mathbb{R} \) is a constant. Now we integrate (18) to obtain a fundamental solution for the Laplacian on \( S^d_R \)

\[
S^d_R(\mathbf{x}, \mathbf{x'}) = c_0 \mathcal{I}_d(\theta) + c_1, \tag{19}
\]

where \( \mathcal{I}_d : (0, \pi) \to \mathbb{R} \) is defined as

\[
\mathcal{I}_d(\theta) := \int_0^{\pi/2} \frac{dx}{\sin^{d-1} x}, \tag{20}
\]

and \( c_0, c_1 \in \mathbb{R} \) are constants which depend on \( d \) and \( R \). Notice that we can add any harmonic function to (19) and still have a fundamental solution of the Laplacian since a fundamental solution of the Laplacian must satisfy

\[
\int_{S^d_R} (-\Delta \varphi)(\mathbf{x'}) S^d_R(\mathbf{x}, \mathbf{x'}) \, d\text{vol}_g' = \varphi(\mathbf{x}),
\]

for all \( \varphi \in S(S^d_R) \), where \( S \) is the space of test functions, and \( d\text{vol}_g' \) is the Riemannian (volume) measure on \( S^d_R \) in the primed coordinates. Notice that our fundamental solution of Laplace’s equation on the hypersphere ((19), (20)) has the property that it tends towards \(+\infty\) as \( \theta \to 0^+ \). 

and tends towards $-\infty$ as $\theta \to \pi^-$. Therefore our fundamental solution attains all real values. As an aside, by the definition therein (see [14, 15]), $S^d_R$ is a parabolic manifold. Since the hypersphere $S^d_R$ is bi-hemispheric, we expect that a fundamental solution of Laplace’s equation on the hypersphere should vanish at $\theta = \pi/2$. It is therefore convenient to set $c_1 = 0$ leaving us with

$$S^d_R(x, x') = c_0 \mathcal{I}_d(\theta).$$  \hspace{1cm} (21)

In Euclidean space $\mathbb{R}^d$, a Green’s function for Laplace’s equation (fundamental solution for the Laplacian) is well-known and is given by the following expression (see [11, p. 94], [12, p. 17], [3, p. 211], [6, p. 6]). Let $d \in \mathbb{N}$. Define

$$G^d(x, x') = \begin{cases} \frac{\Gamma(d/2)}{2\pi^{d/2}(d-2)} \|x - x'\|^{2-d} & \text{if } d = 1 \text{ or } d \geq 3, \\ \frac{1}{2\pi} \log \|x - x'\|^{-1} & \text{if } d = 2, \end{cases}$$  \hspace{1cm} (22)

then $G^d$ is a fundamental solution for $-\Delta$ in Euclidean space $\mathbb{R}^d$, where $\Delta$ is the Laplace operator in $\mathbb{R}^d$. Note that most authors only present the above theorem for the case $d \geq 2$ but it is easily-verified to also be valid for the case $d = 1$ as well.

The hypersphere $S^d_R$, being a manifold, must behave locally like Euclidean space $\mathbb{R}^d$. Therefore for small $\theta$ we have $e^\theta \simeq 1 + \theta$ and $e^{-\theta} \simeq 1 - \theta$ and in that limiting regime

$$\mathcal{I}_d(\theta) \approx \int_0^1 dx \frac{1}{x^{d-1}} \simeq \begin{cases} -\log \theta & \text{if } d = 2, \\ \frac{1}{\theta^{d-2}} & \text{if } d \geq 3, \end{cases}$$

which has exactly the same singularity as a Euclidean fundamental solution. Therefore the proportionality constant $c_0$ is obtained by matching locally to a Euclidean fundamental solution

$$S^d_R = c_0 \mathcal{I}_d \simeq G^d,$$  \hspace{1cm} (23)

in a small neighborhood of the singularity at $x = x'$, as the curvature vanishes, i.e., $R \to \infty$.

We have shown how to compute a fundamental solution of the Laplace–Beltrami operator on the hypersphere in terms of an improper integral (20). We would now like to express this integral in terms of well-known special functions. A fundamental solution $\mathcal{I}_d$ can be computed using elementary methods through its definition (20). In $d = 2$ we have

$$\mathcal{I}_2(\theta) = \int_0^{\pi/2} \frac{dx}{\sin x} = \frac{1}{2} \log \frac{\cos \theta + 1}{\cos \theta - 1} = \log \cot \frac{\theta}{2},$$

and in $d = 3$ we have

$$\mathcal{I}_3(\theta) = \int_0^{\pi/2} \frac{dx}{\sin^2 x} = \cot \theta.$$

In $d \in \{4, 5, 6, 7\}$ we have

$$\mathcal{I}_4(\theta) = \frac{1}{2} \log \cot \frac{\theta}{2} + \frac{\cos \theta}{2 \sin^2 \theta},$$

$$\mathcal{I}_5(\theta) = \cot \theta + \frac{1}{3} \cot^3 \theta,$$

$$\mathcal{I}_6(\theta) = \frac{3}{8} \log \cot \frac{\theta}{2} + \frac{3 \cos \theta}{8 \sin^2 \theta} + \frac{\cos \theta}{4 \sin^2 \theta},$$

and

$$\mathcal{I}_7(\theta) = \cot \theta + \frac{2}{3} \cot^3 \theta + \frac{1}{5} \cot^5 \theta.$$
Now we prove several equivalent finite summation expressions for $I_d(\theta)$. We wish to compute the antiderivative $I_m : (0, \pi) \to \mathbb{R}$, which is defined as

$$I_m(x) := \int \frac{dx}{\sin^m x},$$

where $m \in \mathbb{N}$. This antiderivative satisfies the following recurrence relation

$$I_m(x) = -\cos x (m - 1) \sin^{m-1} x + \frac{(m - 2)}{(m - 1)} I_{m-2}(x),$$

which follows from the identity

$$\frac{1}{\sin^m x} = \frac{1}{\sin^{m-2} x} + \frac{\cos x}{\sin^m x} \cos x,$$

and integration by parts. The antiderivative $I_m(x)$ naturally breaks into two separate classes, namely

$$\int \frac{dx}{\sin^{2n+1} x} = -\frac{(2n - 1)!!}{(2n)!} \left[ \log \cot \frac{x}{2} + \cos x \sum_{k=1}^{n} \frac{(2k - 2)!!}{(2k - 1)!!} \frac{1}{\sin^{2k} x} \right] + C,$$

and

$$\int \frac{dx}{\sin^{2n} x} = \begin{cases} \frac{(2n - 2)!!}{(2n - 1)!!} \sum_{k=1}^{n} \frac{(2k - 3)!!}{(2k - 2)!!} \frac{1}{\sin^{2k-1} x} + C, & \text{if } d \text{ even}, \\ -(n - 1)! \sum_{k=1}^{n} \frac{\cot^{2k-1} x}{(2k - 1)(k - 1)! (n - k)!} + C, & \text{if } d \text{ odd}. \end{cases}$$

where $C$ is a constant. The double factorial $(\cdot)!! : \{-1, 0, 1, \ldots\} \to \mathbb{N}$ is defined by

$$(n!!) := \begin{cases} n \cdot (n - 2) \cdots 2 & \text{if } n \text{ even} \geq 2, \\ n \cdot (n - 2) \cdots 1 & \text{if } n \text{ odd} \geq 1, \\ 1 & \text{if } n \in \{-1, 0\}. \end{cases}$$

Note that $(2n)!! = 2^n n!$ for $n \in \mathbb{N}_0$. The finite summation formulae for $I_m(x)$ all follow trivially by induction using (24) and the binomial expansion (cf. (1.2.2) in [26])

$$(1 + \cos^2 x)^n = n! \sum_{k=0}^{n} \frac{\cot^{2k} x}{k!(n - k)!}.$$ 

The formulae (25) and (26) are essentially equivalent to (2.515.1–2) in [13], except (2.515.2) is in error with the factor $2^{8k}$ being replaced with $2^k$. This is also verified in the original citing reference [34]. By applying the limits of integration from the definition of $I_d(\theta)$ in (20) to (25) and (26) we obtain the following finite summation expression

$$I_d(\theta) = \begin{cases} \frac{(d - 3)!!}{(d - 2)!!} \left[ \log \cot \frac{\theta}{2} + \cos \theta \sum_{k=1}^{(d/2)-1} \frac{(2k - 2)!!}{(2k - 1)!!} \frac{1}{\sin^{2k} \theta} \right] & \text{if } d \text{ even}, \\ \left( \frac{d - 3}{2} \right)! \sum_{k=1}^{(d-1)/2} \frac{\cot^{2k-1} \theta}{(2k - 1)(k - 1)! ((d - 2k - 1)/2)!}, & \text{if } d \text{ odd}. \end{cases}$$

(27)
Moreover, the antiderivative (indefinite integral) can be given in terms of the Gauss hypergeometric function as

\[
\int \frac{d\theta}{\sin^{d-1} \theta} = -\cos \theta \ _2F_1 \left( \frac{1}{2}, \frac{3}{2}; \frac{1}{2}; \cos^2 \theta \right) + C, \tag{28}
\]

where \( C \in \mathbb{R} \). This is verified as follows. By using

\[
\frac{d}{dz} \ _2F_1(a, b; c; z) = \frac{ab}{c} \ _2F_1(a + 1, b + 1; c + 1; z)
\]

(see (15.5.1) in [26]), and the chain rule, we can show that

\[
-\frac{d}{d\theta} \cos \theta \ _2F_1 \left( \frac{1}{2}, \frac{3}{2}; \frac{1}{2}; \cos^2 \theta \right) = \sin \theta \left[ _2F_1 \left( \frac{1}{2}, \frac{3}{2}; \frac{1}{2}; \cos^2 \theta \right) + \frac{d}{3 \cos^2 \theta} \ _2F_1 \left( \frac{3}{2}, \frac{d + 2}{2}, \frac{5}{2}; \cos^2 \theta \right) \right].
\]

The second hypergeometric function can be simplified using Gauss’ relations for contiguous hypergeometric functions, namely

\[
z \ _2F_1(a + 1, b + 1; c + 1; z) = \frac{c}{a - b} \left[ _2F_1(a, b + 1; c; z) - _2F_1(a + 1, b; c; z) \right]
\]

(see [7, p. 58]), and

\[
_2F_1(a, b + 1; c; z) = \frac{b - a}{b} \ _2F_1(a, b; c; z) + \frac{a}{b} \ _2F_1(a + 1, b; c; z)
\]

(see (15.5.12) in [26]). By applying these formulae, the term with the hypergeometric function cancels leaving only a term which is proportional to a binomial through

\[
_2F_1(a, b; b; z) = (1 - z)^{-a}
\]

(see (15.4.6) in [26]), which reduces to \( 1/\sin^{d-1} \theta \). By applying the limits of integration from the definition of \( I_d(\theta) \) in (20) to (28) we obtain the following Gauss hypergeometric representation

\[
I_d(\theta) = \cos \theta \ _2F_1 \left( \frac{1}{2}, \frac{d}{2}; \frac{3}{2}; \cos^2 \theta \right). \tag{29}
\]

Using (29), we can write another expression for \( I_d(\theta) \). Applying Eulers’s transformation

\[
_2F_1(a, b; c; z) = (1 - z)^{c-a-b} \ _2F_1(c - a, c - b; c; z)
\]

(see (2.2.7) in [1]), to (29) produces

\[
I_d(\theta) = \frac{\cos \theta}{\sin^{d-2} \theta} \ _2F_1 \left( \frac{1}{2}, \frac{3 - d}{2}; \frac{3}{2}; \cos^2 \theta \right).
\]

Our derivation for a fundamental solution of Laplace’s equation on the \( R \)-radius hypersphere in terms of Ferrers function of the second kind (associated Legendre function of the second kind on the cut) is as follows. If we let \( \nu + \mu = 0 \) in the definition of Ferrers function of the second kind \( Q_\nu^\mu \) \((-1, 1) \rightarrow \mathbb{C} \) (15), we derive

\[
Q_{-\nu}^\nu(x) = \sqrt{\pi} x(1 - x^2)^{\nu/2} \ _2F_1 \left( \frac{1}{2}, \nu + 1; \frac{3}{2}; x^2 \right),
\]
for all \( \nu \in \mathbb{C} \). If we let \( \nu = d/2 - 1 \) and substitute \( x = \cos \theta \), then we have

\[
Q_{d/2-1}^{1-d/2}(\cos \theta) = \sqrt{\frac{\pi}{2d-2}} \frac{\cos \theta \sin^{d/2-1} \theta}{\Gamma \left( \frac{d-1}{2} \right)} 2F_1 \left( \frac{1}{2}, \frac{3}{2}; \frac{1}{2}; \cos^2 \theta \right).
\]

(30)

Using the duplication formula for gamma functions (16), then through (30) we have

\[
\mathcal{I}_d(\theta) = \frac{(d-2)!}{\Gamma((d/2)2^{d/2-1})} \frac{1}{\sin^{d/2-1} \theta} Q_{d/2-1}^{1-d/2}(\cos \theta).
\]

(31)

We have therefore verified that the harmonics computed in Section 3.1, namely \( u_{2+}^{d,0} \) (14), give an alternate form for a fundamental solution of the Laplacian on the hypersphere.

Note that as a result of our proof, we see that the relevant associated Legendre functions of the second kind on the cut for \( d \in \{2, 3, 4, 5, 6, 7\} \) are (cf. (27) and (31))

\[
Q_0(\cos \theta) = \log \cot \frac{\theta}{2},
\]

\[
\frac{1}{(\sin \theta)^{1/2}} Q_{1/2}^{-1/2}(\cos \theta) = \sqrt{\frac{\pi}{2}} \cot \theta, \]

\[
\frac{1}{\sin \theta} Q_{1}^{-1}(\cos \theta) = \frac{1}{2} \log \cot \frac{\theta}{2} + \frac{\cos \theta}{2 \sin^2 \theta},
\]

\[
\frac{1}{(\sin \theta)^{3/2}} Q_{3/2}^{-3/2}(\cos \theta) = \frac{1}{2} \sqrt{\frac{\pi}{2}} \left( \cot \theta + \frac{1}{3} \cot^3 \theta \right),
\]

\[
\frac{1}{(\sin \theta)^{2}} Q_{2}^{-2}(\cos \theta) = \frac{1}{8} \log \cot \frac{\theta}{2} + \frac{\cos \theta}{8 \sin^2 \theta} + \frac{\cos \theta}{12 \sin^4 \theta}, \quad \text{and}
\]

\[
\frac{1}{(\sin \theta)^{5/2}} Q_{5/2}^{-5/2}(\cos \theta) = \frac{1}{8} \sqrt{\frac{\pi}{2}} \left( \cot \theta + \frac{2}{3} \cot^3 \theta + \frac{1}{5} \cot^5 \theta \right).
\]

The constant \( c_0 \) in a fundamental solution for the Laplace operator on the hypersphere \( S^d_R \) (21) is computed by locally matching up, through (23), to the singularity of a fundamental solution for the Laplace operator in Euclidean space (22). The coefficient \( c_0 \) depends on \( d \) and \( R \). For \( d \geq 3 \) we take the asymptotic expansion for \( c_0 \mathcal{I}_d(\theta) \) as \( \theta \to 0^+ \), and match this to a fundamental solution for Euclidean space (22). This yields

\[
c_0 = \frac{\Gamma \left( \frac{d}{2} \right)}{2\pi^{d/2}}.
\]

(32)

For \( d = 2 \) we take the asymptotic expansion for

\[
c_0 \mathcal{I}_2(\theta) = -c_0 \log \tan \frac{\theta}{2} \simeq c_0 \log \| x - x' \|^{-1},
\]

as \( \theta \to 0^+ \), and match this to \( G^2(x, x') = (2\pi)^{-1} \log \| x - x' \|^{-1} \), therefore \( c_0 = (2\pi)^{-1} \). This exactly matches (32) for \( d = 2 \). The \( R \) dependence of \( c_0 \) originates from (20), where \( x \) and \( \theta \) represents geodesic distances (cf. (3)). The distance \( r \in [0, \infty) \) along a geodesic, as measured from the origin of \( S^d_R \), is given by \( r = \theta R \). To show that a fundamental solution (21) reduces to the Euclidean fundamental solution at small distances (see for instance [21]), we examine the limit of zero curvature. In order to do this, we take the limit \( \theta \to 0^+ \) and \( R \to \infty \) of (20) with the substitution \( x = r/R \) which produces a factor of \( R^{d-2} \). So a fundamental solution of Laplace’s equation on the Riemannian manifold \( S^d_R \) is given by

\[
S^d_R(x, x') := \frac{\Gamma \left( \frac{d}{2} \right)}{2\pi^{d/2} R^{d-2}} \mathcal{I}_d(\theta).
\]

The proof of Theorem 1 is complete.
Apart from the well-known historical results in two and three dimensions, the closed form expressions for a fundamental solution of Laplace’s equation on the $R$-radius hypersphere given by Theorem 1 in Section 3.2 appear to be new. Furthermore, the Ferrers function (associated Legendre) representations in Section 3.1 for the radial harmonics on the $R$-radius hypersphere do not appear to be have previously appeared in the literature.

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