CitySpec: An Intelligent Assistant System for Requirement Specification in Smart Cities

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Abstract—An increasing number of monitoring systems have been developed in smart cities to ensure that a city’s real-time operations satisfy safety and performance requirements. However, many existing city requirements are written in English with missing, inaccurate, or ambiguous information. There is a high demand for assisting city policy makers in converting human-specified requirements to machine-understandable formal specifications for monitoring systems. To tackle this limitation, we build CitySpec, the first intelligent assistant system for requirement specification in smart cities. To create CitySpec, we first collect over 1,500 real-world city requirements across different domains from over 100 cities and extract city-specific knowledge to generate a dataset of city vocabulary with 3,061 words. We also build a translation model and enhance it through requirement synthesis and develop a novel online learning framework with validation under uncertainty. The evaluation results on real-world city requirements show that CitySpec increases the sentence-level accuracy of requirement specification from 59.02% to 86.64%, and has strong adaptability to a new city and a new domain (e.g., F1 score for requirements in Seattle increases from 77.6% to 93.75% with online learning).

Index Terms—Requirement Specification, Intelligent Assistant, Monitoring, Smart City

I. INTRODUCTION

With the increasing demand for safety guarantees in smart cities, significant research efforts have been spent toward how to ensure that a city’s real-time operations satisfy safety and performance requirements [1]. Monitoring systems, such as SaSTL runtime monitoring [2], CityResolver [3], and STL-U predictive monitoring [4], have been developed in smart cities. Figure 1 shows a general framework of monitoring systems in smart cities. These systems are designed to execute in city centers and to support decision-making based on the verification results of real-time sensing data about city-states (such as traffic and air pollution). If the monitor detects a requirement violation, the city operators can take actions to change the states, such as improving air quality, sending alarms to police, calling an ambulance, etc.

The monitor systems have two important inputs, i.e., the real-time data streams and formal specified requirements. Despite that extensive research efforts have been spent toward improving the expressiveness of specification languages and efficiency of the monitoring algorithms, the research challenge of how to convert human-specified requirements to machine-understandable formal specifications has received only scant attention. Moreover, our study (see Section II) on over 1,500 real-world city requirements across different domains shows that, first, existing city requirements are often defined with missing information or ambiguous description, e.g., no location information, using words like nearby, or close to. They are not precise enough to be converted to a formal specification or monitored in a city directly without clarifications by policy makers. Secondly, the language difference between English specified requirements and formalized specifications is significant. Without expertise in formal languages, it is extremely difficult or impossible for policy makers to write or convert their requirements to formal specifications. Therefore, there is an urgent demand for an intelligent system to support policy makers for requirement specifications in smart cities.

Despite the prevalence of developing models to translate natural language to machine languages in various domains, such as Bash commands [5], Seq2SQL [6], and Python [7], it is very challenging to develop such an intelligent system for requirement specification in smart cities for the following reasons. First, unlike the above translation tasks with thousands or even millions of samples in a dataset, there is barely any requirement specification data. As a result, traditional language models are not sufficient to be applied directly. Moreover, the requirements usually contain city domain-specific descriptions and patterns that existing pre-trained embeddings like BERT or GloVE cannot handle effectively. Furthermore, requirements from different domains and cities vary significantly and evolve over time, thus building a system that can adapt to new domains at runtime is an open research question. Good adaptability can increase user experience (e.g., policy makers do not have to clarify new terms repeatedly), while one of the major challenges is validating and filtering the new knowledge and avoiding adversarial examples online.

In this paper, we target the above technical challenges, and describe CitySpec, an intelligent assistant system for
requirement specification in smart cities. To the best of our knowledge, it is the first specification system helping city policy makers specify and translate their requirements into formal specifications automatically. As shown in Figure 1, CitySpec is designed to bridge the gap between city policy makers and monitoring systems. It enables policy makers to define their requirements by detecting missing, inaccurate, or ambiguous information through an intelligent assistant interface. To effectively train the translation model using a small amount of city requirement data, CitySpec extracts city knowledge and enhances the learning process through requirement synthesis. CitySpec can easily adapt to a new city or domain through online learning and validation.

Contributions. We summarize the major contributions of this paper as follows:

- We collect and annotate over 1,500 real-world city requirements from over 100 cities across different domains. We extract city-specific knowledge and build a dataset of city vocabulary with 3,061 words in 5 categories.
- We create an intelligent assistant system for requirement specification in smart cities. In the system, we build a translation model and enhance it through requirement synthesis, and develop a novel online learning framework with validation under uncertainty.
- We evaluate CitySpec extensively using real-world city requirements. The evaluation results show that CitySpec is effective on supporting policy makers accurately writing and refining their requirements. It increases the sentence level accuracy of requirement specification from 59.02% to 86.64% through city knowledge injection. It shows strong adaptability (user experience) to a new city (e.g., F1 score in Seattle from 77.6% to 93.75%) and a new domain (e.g., F1 score in security domain from 62.93% to 93.95%).

Paper organization: In the rest of the paper, we describe the motivating study of city requirement specification in Section II, provide an overview of CitySpec in Section III and present the technical details in Section IV. We then present the evaluation results in Section V, discuss the related work in Section VI, and draw conclusions in Section VII.

II. MOTIVATING STUDY

In this section, we study real-world city requirements and their formal specification as motivating examples to discuss the demand and challenges of developing an intelligent assistant system for requirement specification in smart cities. We collect and annotate over 1,500 real-world city requirements across different domains (e.g., transportation, environment, security, public safety, indoor environments, etc.) from over 100 cities. We make the following observations from the analysis of the requirement dataset.

Existing city requirements are often defined with missing information or ambiguous description. In [2], the authors define essential elements for monitoring a city requirement. Within the 1500 requirements, many requirements have one or more missing elements. For example, 27.6% of the requirements do not have location information, 29.1% of the requirements do not have a proper quantifier, and 90% of the requirements do not have or only have a default time (e.g., always) defined. Additionally, requirements often have ambiguous descriptions that are difficult to be noticed by policy makers. For example, a location is specified as “nearby” or “close to”. As a result, it is very difficult or impossible for the monitoring system to monitor these requirements properly. It indicates a high demand for an intelligent assistant system to support the policy makers to refine the requirements.

The language difference between English specified requirements and their formal specifications is significant. In Table I, we give three examples of city requirements in English, their formal specification in SaSTL, and the Damerau–Levenshtein Distance (DLD) [3] between each pair of requirements. DLD measures the edit distance between two sequences. It shows that natural languages are different from machine-compatible input languages. Formal specifications usually consist of mathematical symbols, which makes the conversion even more difficult. As shown in Table I, the average DLD from English requirements to formal specifications is 67, which means that it requires an average of 67 edits. As a reference, the average DLD brought by translating these three English requirements to Latin is 64.67. It indicates that the conversion from English requirements to formal specifications even requires more edits than the translation of these requirements from English to Latin. In general, building a translator from English to Latin would require millions of samples. However, as an under-exploited domain, there is a very limited number of well-defined requirements. Moreover, annotation of formal specifications requires specialties in formal methods and is extremely time-consuming. It presents major challenges for building such a translation model.

III. SYSTEM OVERVIEW

CitySpec is designed to bridge the gap between city policy makers and monitoring systems. It supports policy makers to precisely write city requirements in English through an intelligent interface, and then converts them to formal specifications automatically. An overview of CitySpec is shown in Figure 2. There are four major components in CitySpec, including an intelligent assistant interface to communicate with policy makers (see Section IV-B), a Requirement Synthesis component to extract city knowledge and synthesize new requirements to build the translation model (see Section IV-C), a Translation Model to convert city requirements to formal specifications (see Section IV-D), and an Online Learning component to adapt the system to new knowledge (see Section IV-E).

At runtime (as indicated by the orange arrows in Figure 2), a city policy maker inputs a requirement in English through an intelligent assistant interface, which sends the requirements to the translation model. The translation model converts the requirements to a formal specification and checks if there is any missing information or ambiguous description. The translation model is built with injected city knowledge through requirement synthesis at the training time and enhanced
TABLE I

| ID | English Requirement                                                                 | Formal Specification                                                                 | DLD |
|----|-------------------------------------------------------------------------------------|--------------------------------------------------------------------------------------|-----|
| 1  | Sliding glass doors shall have an air infiltration rate of no more than 0.3 cfm per square foot. | Everywhere city block Always 0 \( \in \) \( \mathbb{R} \), air infiltration rate \( \leq \) 0.3 cfm/foot | 59  |
| 2  | The operation of a Golf Cart upon a Golf Cart Path shall be restricted to a maximum speed of 15 miles per hour from 8:00 to 16:00. | Everywhere city block Always \( \in \) \( \mathbb{R} \), Golf Cart speed \( \leq \) 15 miles/hour | 67  |
| 3  | Up to four vending vehicles may dispense merchandise in any given city block at any time. | Everywhere city block Always 3 \( \leq \) 4 vending vehicles | 75  |

through online learning at runtime. Next, based on the returned results from the translation model, the intelligent interface communicates with the policy maker to acquire or clarify the essential information. In this process, the assistant supports the policy maker to refine the requirement until it is precisely defined and accepted by the monitor. We present the technical details in Section IV and develop a prototype tool of the CitySpec system and deploy it online.

IV. METHODOLOGY

In this section, we present the major components in CitySpec (as shown in Figure 2). We first introduce requirement specification using Spatial-aggregation Signal Temporal Logic (SaSTL) [2]. Then we show the design and technical details of the intelligent assistant interface, requirement synthesis, translation model, and online learning, respectively.

A. Requirement Specification using SaSTL

SaSTL is a powerful formal specification language for Cyber-Physical Systems. We select it as our specification language because of its advantages of expressiveness and monitoring for smart cities. However, CitySpec is general and can work with other specification languages. SaSTL is defined on a multi-dimensional spatial-temporal signal as \( \omega : T \times L \rightarrow \{ \mathbb{R} \cup \{ \bot \} \}^n \), where \( T = \mathbb{R}_{\geq 0} \) represents the continuous time and \( L \) is the set of locations. \( X = \{ x_1, \ldots, x_n \} \) is denoted by the set of variables for each location. The spatial domain \( D \) is defined as, \( D := (d_1, d_2) \), \( \psi := t | p | \neg \psi | \psi \lor \psi \), where \( \psi \) specifies the property over the set of propositions that must hold in each location.

The syntax of SaSTL is given by

\[
\varphi := x \sim c | \neg \varphi | \varphi_1 \land \varphi_2 | \varphi_1 \varphi_2 | A_{op} x \sim c | C_{op} \varphi \sim c
\]

where \( x \in X \), \( \varphi \in \{ <, \leq \} \), \( c \in \mathbb{R} \) is a constant, \( I \in \mathbb{R}_{>0} \) is a real positive dense time interval, \( U_I \) is the bounded until temporal operators from STL. The \( always \) (denoted \( \omega \)) and \( eventually \) (denoted \( \diamond \)) temporal operators can be derived the same way in STL, where \( \varphi \equiv \text{true} \) \( \varphi \), and \( D \varphi \equiv \neg \circ \varphi \). Spatial aggregation operators \( A_{op} x \sim c \) for \( op \in \{ \max, \min, \sum, \text{avg} \} \) evaluates the aggregated product of traces over a set of locations \( l \in L^1_D \), and counting operators \( C_{op} \varphi \sim c \) for \( op \in \{ \max, \min, \sum, \text{avg} \} \) counts the satisfaction of traces over a set of locations. From counting operators, we derive the \( everywhere \) operator as \( \& \varphi \equiv C_{\max} \varphi > 0 \), and \( somewhere \) operator as \( \& \varphi \equiv C_{\min} \varphi > 0 \). Please refer to [2] for the detailed definition and semantics of SaSTL.

B. Interface for Intelligent Assistant

City requirements often have missing or ambiguous information, which may be unnoticed by policy makers. It leads to the demand for human inputs and clarification when converting them into formal specifications. Therefore, we design an intelligent assistant interface in CitySpec serving as an intermediary between policy makers and the translation model. It communicates with policy makers and confirms the final requirements through an intelligent conversation interface.

To briefly describe the communication process, users first input a requirement in English, e.g., “due to safety concerns, the number of taxis should be less than 10 between 7 am to 8 am”. CitySpec interface passes the requirement to the translation model and gets a formal requirement (always \( \in \mathbb{R}_{\geq 0} \) number of taxi \( < 10 \)) with the keywords including,

- entity: the requirement’s main object, e.g., “the number”;
- quantifier: the scope of an entity, e.g., “taxi”;
- location: the location where this requirement is in effect, which is missing from the above example requirement,
time: the time period during which this requirement is in effect, e.g., “between 7 am to 8 am”,
condition: the specific constraint on the entity, such as an upper or lower bound of entity, e.g., “10”.

As a result, CitySpec detects that the location information is missing from the user’s requirement and generates a query for the user, “what is the location for this requirement?” Next, with new information typed in by the user (e.g., “within 200 meters of all the schools”), CitySpec obtains a complete requirement.

The next challenge is how to confirm the formal specification with policy makers. Since they do not understand the formal equation, we further convert it to a template-based sentence. Therefore, CitySpec presents three formats of this requirements for users to verify, (1) a template-based requirement with policy makers. Since they do not understand the formal equation, we further convert it to a template-based sentence. Therefore, CitySpec presents three formats of this requirement to a formal specification is challenging with a small amount of data. First, the amount of city requirement dataset is insufficient to train a decent translation model in an end-to-end manner. As we’ve discussed in Section I, it requires extensive domain knowledge in both city and formal specifications and is extremely time-consuming to annotate new requirements. Furthermore, a majority of the existing city requirements are qualitatively or imprecisely written, which can not be added to the requirement dataset without refinement. To mitigate the challenge of small data to build a translation model, we design a novel approach to incorporating city knowledge through controllable requirement specification.

There are two main reasons why converting a city requirement to a formal specification is challenging with a small amount of data. First, the vocabulary of city requirements are very diverse. For example, requirements from different cities (e.g., Seattle and New York City) or in different domains (e.g., transportation and environment) have totally different vocabulary for entities, locations, and conditions. Second, the sentence structure (patterns) of requirements vary significantly when written by different people. It is natural for human beings to describe the same thing using sentences.

Targeting these two challenges, we first extract city knowledge and build two knowledge datasets, i.e., a vocabulary set and a pattern set. The vocabulary set includes five keys of a requirement, i.e., entity, quantifier, location, time and condition. The pattern set includes requirement sentences with 5 keywords replaced by their labels. For instance, we have a requirement, “In all buildings/location, the average concentration of TVOC/quantifier should be no more than 0.6 mg/m³/condition for every day/time.”, the pattern extracted is “In #location, the average #entity of #quantifier should be no more than #condition for #time.”

We extract the knowledge set from city documents besides requirements so that we are not limited by the rules of requirements and enrich the knowledge of our model. For example, we extract 336 patterns and 3061 phrases (530 phrases in entity, 567 phrases in quantifier, 501 phrases in location, 595 phrases in condition, and 868 phrases in time).

Next, we designed an approach to synthesizing controllable requirement dataset efficiently. Intuitively, we can go through all the combinations of keywords and patterns to create the dataset of requirements, which is infeasible and may cause the model overfitting to the injected knowledge. In order to enhance the model’s performance, we need to keep a balance between the coverage of each keyword and the times of keywords being seen in the generation. We denote λ as the synthesis index, which indicates the minimum number of times that a keyword appears in the generated set of requirements. Assuming we have m set of keywords vocabularies \{V_1, V_2 \ldots V_m\} and a pattern set as P, we have the total number of synthesized requirements \( \ell = \lambda \cdot \max(|V_1|, |V_2|, \ldots, |V_m|) \) for each set of vocabularies \( V_i \), we first create a random permutation of \( V_i \) and repeat it until the total number of phrases reaches \( \ell \), then we concatenate them to an array \( S \). Once we obtain \( S_1, \ldots, S_m \), we combine them with pattern \( P \) to generate a requirement set \( R \). Refer to Algorithm 1 for more details.

### Algorithm 1 Requirement Synthesis

**Input**: \( m \) set of keywords vocabularies \{V_1, V_2 \ldots V_m\}, Pattern \( P \), synthesis index \( \lambda \)

**Output**: Set of requirements \( R \)

1. Initialize \( R \) as an empty set
2. Initialize \( \ell \) as \( \lambda \cdot \max(|V_1|, |V_2|, \ldots, |V_m|) \)
3. for \( i \in 1 \ldots m \)
   4. Initialize \( S_i \) as an empty array
   5. while \(|S_i| < \ell \)
      6. Create a random permutation of \( S_i \)
      7. Concatenate \( P \) to \( S_i \), \( S_i = \text{Concat}(S_i, P) \)
   8. end while
   9. end for
10. for \( j \in 1 \ldots \ell \)
    11. Combine keywords \( S_1[j], S_2[j] \ldots S_m[j] \) with Pattern \( P \) to create a requirement \( r_j \)
12. end for
13. Add \( r_j \) to the set of requirements \( R \)
14. end for
15. return \( R \)
The second question is that how can CitySpec validate the new knowledge online? How can CitySpec learn the new knowledge before learning it permanently? We make the following observations from the results. First, the overlap between Stanford Pretrained NER Tagger prediction and vocabulary is only 9 out of 729. The pretrained tagger tends to give locations in higher granularity. Since this task is a city-level, more detailed location information is stated in a lower granularity by providing the street name, building name.
injection or training phases. We apply different synthesis requirements. We ensure that the trained model has not seen the requirements in the testing set to synthesize them. For a fair comparison, we do not use the requirements in the testing set to synthesize them; instead. In addition, terms like “occupancy of a shopping center” are confused to even humans if the requirement is changed to “The concentration of Sulfur dioxide (SO2) should be no more than 0.15 mg/m3 for every day.”, then entity is “concentration” and quantifier is “Sulfur dioxide (SO2)”. If the requirement is changed to “The maximum level of the concentration of Sulfur dioxide (SO2) should be no more than 0.15 mg/m3 for every day.”, then entity is “maximum level” and quantifier is “concentration” instead. In addition, terms like “occupancy of a shopping mall”, “noise level at a shopping mall”, and “the shopping mall of the commercial district” also introduce confusion between location, entity and quantifier, since the same token “shopping mall” can be entity, quantifier or location in certain cases.

From the results, we find that, for BERT and Bi-LSTM, there is an overall increase in performance in all token-level accuracy, sentence-level accuracy, overall F-1 score, and F-1 score on keywords. For example, BiLSTM+CRF’s token-level accuracy increases from 77.59% to 97% and sentence-level accuracy increases from 60.82% to 81.3%, BERT’s sentence-level accuracy increases from 59.02% to 86.64%.

In summary, the results show that injecting city knowledge with synthesized requirements boosts the translation model significantly. While improving policy maker’s user experience with higher accuracy and less clarifications, it also enhances the safety of the monitoring system potentially.

C. Performance on Online Validation

We evaluate the validation model through simulating four different testing scenarios: (I) randomly generated malicious input based on the permutation of letters and symbols; (II) all street names in Nashville; (III) real city vocabulary generated from Nashville requirements; (IV) generated float numbers with different units.

First of all, the accuracy of validation model is very high. When the uncertainty threshold is set to 0.5, i.e., all inputs cause an uncertainty higher than 0.5 will be ruled out, CitySpec gives 100% success rate against scenario I among 2,000 malicious inputs, 91.40% acceptance rate among 2,107 samples in scenario II, 92.12% acceptance rate among 596 samples in scenario III, and 94.51% acceptance rate among 2,040 samples in scenario IV. Additionally, we find that the validation function easily confuses entity with quantifier if no further guidance is offered. We look into dataset and figure out entity and quantifier are confusing to even humans without any context information. Take the requirement “In all buildings, the average concentration of Sulfur dioxide (SO2) should be no more than 0.15 mg/m3 for every day.”, then entity is “concentration” and quantifier is “Sulfur dioxide (SO2)” if the requirement is changed to “The maximum level of the concentration of Sulfur dioxide (SO2) should be no more than 0.15 mg / m3 for every day.”, then entity is “maximum level” and quantifier is “concentration” instead. In addition, terms like “occupancy of a shopping mall”, “noise level at a shopping mall”, and “the shopping mall of the commercial district” also introduce confusion between location, entity and quantifier, since the same token “shopping mall” can be entity, quantifier or location in certain cases.

![Fig. 4. Performance improvement brought by requirement synthesis](image)

**TABLE II**

| Model           | Token-Acc | Sent-Acc | F-1 Score | Precision | Recall |
|-----------------|-----------|----------|-----------|-----------|--------|
| Vanilla Seq2Seq | 10.91 ± 0.57% | 1.38 ± 0.39% | 24.12 ± 0.25% | 65.58 ± 7.95% | 14.81 ± 1.58% |
| BiLSTM + CRF    | 77.59 ± 0.52% | 60.82 ± 1.22% | 80.46 ± 0.84% | 81.11 ± 1.38% | 79.83 ± 7.24% |
| BERT            | 80.41 ± 0.07% | 59.02 ± 0.42% | 81.43 ± 0.01% | 78.62 ± 0.01% | 84.46 ± 0.01% |

In summary, the results indicate that existing language models are not sufficient to serve as the translation model for CitySpec directly. There is a high demand for injecting city knowledge to build the translation model.

**B. Requirement Synthesis with City Knowledge**

Next, we evaluate CitySpec’s performance with our controllable synthesized requirements. For a fair comparison, we do not use the requirements in the testing set to synthesize requirements. We ensure that the trained model has not seen the requirements in the testing set in either the knowledge injection or training phases. We apply different synthesis indexes to test the effects on the prediction performance. We present the overall results on token-level and sentence-level accuracy in Figure 4 and F-1 scores on individual keyword in Figure 5. In the figures, x-axis represents the synthesis index. When the index equals to “initial”, it shows the results without synthesis data.

![Fig. 4. Performance improvement brought by requirement synthesis](image)
The results show that the validation algorithm can effectively accept new city knowledge, prevent adversarial inputs and safeguard online learning. Therefore, CitySpec reduces unnecessary interactions between policy makers and the system and increases efficiency.

D. Adaptability to different scenarios

In this section, we analyze CitySpec’s adaptability in different cities and different domains. Different cities have different regulation focuses and their city-specific vocabulary. For example, in the city of Nashville, location names like “Music Row”, “Grand Ole Opry” will probably never appear in any other cities. We select four cities, Seattle, Charlottesville, Jacksonville, and Changsha, with different sizes and from different countries as case studies. We separate the requirements of each mentioned city and extract the city-wise vocabulary based on each city independently. Each of four constructed pairs consists of: vocabulary I, which is extracted from the requirements from one city only, and vocabulary II, which is extracted from the requirements from all the cities but that specific one city. Injected knowledge is measured using the number along with the ratio of how much of the unique vocabulary one city causes. We augment vocabulary II using the number along with the ratio of how much of the unique vocabulary one city causes. We augment vocabulary II using 5 as the synthesis index and train a model on vocabulary II. As a result, the trained model is isolated from the vocabulary information from that one specific city. Afterward, we test the trained model performance on the generated requirements using vocabulary I. We pick CitySpec with Bi-LSTM + CRF and CitySpec with BERT in this scenario. We employ the validation function to validate all vocab in vocabulary I and pass the validated ones to vocabulary II. After that, we have a validated vocabulary including vocabulary II and validated vocabulary I. The deployed model is fine-tuned based on the validated vocabulary using few-shot learning.

From the results shown in Table III, we observe that (1) although CitySpec immigrates to a completely unknown city, it is still able to provide satisfying performance, e.g., 84.9% token-acc and 77.6% F-1 score in Seattle, but the sent-acc tends to be low. (2) With new knowledge injected, the performance increases significantly, e.g., Sent-Acc for Seattle increases from 48% to 84.8% with BiLSTM+CRF, and from 46.4% to 80.7% with BERT.

We also explore CitySpec’s adaptability to different topics. We choose four topics including noise control, indoor air control, security, and public access. The results also show that (1) even though CitySpec has not seen vocabulary from a totally different topic, it still gives a competitive performance; (2) online learning brings obvious improvements when adaptation is further applied.

In summary, it indicates the capability of CitySpec in both city and domain adaptation. It can also adapt to new requirements evolving overtime. Moreover, with a different set of domain-specified knowledge, CitySpec can be potentially applied to other application domains (e.g., healthcare).

E. Case Study

Due to the absence of a real city policy maker, we emulate the process of using CitySpec by taking the real-world city requirements and assuming that they are input by policy makers. Specifically, this case study shows the iteration of communication between CitySpec and the policy maker to clarify the requirements. We emulate this process 20 times with 100 requirements randomly selected from our datasets each time. The results show that the average and maximum rounds of clarification are 0.8 and 4 per requirement, respectively, due to the missing or ambiguous information. Averagely, 28.35% of requirements require clarification on location. For example, “No vendor should vend after midnight.”, CitySpec asks users to clarify the time range for “after midnight” and the location defined for this requirement. Overall, CitySpec obtains an average sentence-level accuracy of 90.60% (with BERT and synthesize index = 5). The case study further proves the effectiveness of CitySpec in city requirement specification.

VI. RELATED WORK

Translation Models. Researchers have developed models to translate the natural language to machine languages in various domains, such as Bash commands [5], Seq2SQL [6], and Python codes [7]. These translation models benefit from enormous datasets. The codex was trained on a 159 GB dataset that contains over 100 billion tokens. WikiSQL, which Seq2SQL was trained on, consists of 80,654 pairs of English-SQL conversions. NL2Bash [5] was trained on approximately 10,000 pairs of natural language tasks and their corresponding bash commands. As an under-exploited domain, there is a very limited number of well-defined requirements. Therefore, existing translation models do not apply to our task. This paper develops a data synthesis-based approach to build the translation model.

Data Synthesis. Data synthesis exploits the patterns in study findings and synthesizes variations based on those patterns. Data augmentation is a simple application of data synthesis. Previous augmentation approaches wield tricks like synonym substitution [12], [13] and blended approaches [14]. In the smart city scenario, we need new data samples which fit in...
the smart city context. Therefore, we extract extra knowledge from smart cities and fully exploit semantic and syntactic patterns instead of applying straightforward tricks like chopping, rotating, or zooming. This paper is the first work synthesizing smart-city-specific requirements to the best of our knowledge.

**Online Learning.** Online machine learning mainly deals with the situation when data comes available to the machine learning model sequentially after being deployed. Similar to continuous learning, online learning aims to give model accumulated knowledge and improve model performance continuously given incoming learning samples [15], [16]. Some of the existing papers focus on developing sophisticated optimization algorithms [17] or exploiting the differences between new and old samples [18]. However, these papers do not have a mechanism to detect or prevent adversarial samples online. This paper develops a two-stage online learning process with online validation against potential malicious inputs.

**VII. SUMMARY**

This paper builds an intelligent assistant system, CitySpec, for requirement specification in smart cities. CitySpec bridges the gaps between city policy makers and the monitoring systems. It incorporates city knowledge into the requirement translation model and adapts to new cities and domains through online validation and learning. The evaluation results on real-world city requirement datasets show that CitySpec is able to support policy makers accurately writing and refining their requirements and outperforms the baseline approaches. In future work, we plan to have CitySpec used by real city policy makers, but this is outside the scope of this paper.

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