Wide-Area Network State Monitoring System Based On LoRa Communication

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Abstract

To meet the requirements of long range, small amount of data transmission, better data correctness and less delay, a wide-Area Network State Monitoring System approach based on LoRa communication is discussed in our Project. The objective is to study and test the performance of two communication techniques used in wide area monitoring system, a single input single output (SISO) system and a multiple input multiple output system (MIMO) in terms of Bit Error Rate (BER) with varying the signal to noise ratio (SNR). In addition, we study the Wide Area Monitoring system based on LoRa communication. The IEEE 14-bus power system with Phasor Measurement Units (PMUs) placed at selected buses is considered. The simulation results demonstrate that the MIMO system overtake the SISO system for better Bit Error Rate. Furthermore, the value of the reporting rate has been varied for both systems in MATLAB to see the effect on the data correctness and the results show that the Bit Error Rate value decreases with the increase of reporting rate. Finally, we dealt with a modified LoRa MATLAB code emulator to investigate the data error and delay. The results show that LoRa Technology has better performance in terms of delay and error.

Keywords : WAMS, State Monitoring, Communication, SISO, MIMO, LoRa, BER

1. Introduction

Power system is becoming more and more complex, mainly due to the increase of new technologies and the demand of using clean energy. Wide-area monitoring, wide-area control and wide-area protection utilize Wide Area Networks turn out to be the next-generation key to improve power system planning. The modern power grid is considered to be the most complex human-made system, which is monitored by wide-area monitoring system. Providing time-synchronized data of power system operating states, wide-area monitoring system will play a crucial role in next generation smart grid protection and control. Wide area monitoring system helps secure efficient energy transmission as well as reliable and optimal grid management. As the key enabler of a smart grid, numerous sensors such as PMU and current sensors transmit real-time dynamic data, which is usually protected by encryption algorithm from malicious attacks, over wide-area-network to power system control centers so that monitoring and control of the whole system is possible [1-3].

Nowadays, high data rate techniques have gained considerable interests in communication systems. Electric grid was designed to operate as a vertical structure consisting of generation, transmission, and distribution and supported with controls and devices to maintain reliability, stability, and efficiency. However, system operators are now facing new challenges including the penetration of Renewable Energy Resource in the legacy system, rapid technological change, and different types of market players and end users. The next iteration, the smart grid, will be equipped with communication support schemes and real-time measurement techniques to enhance resiliency and forecasting as well as to protect against internal and external threats. The design framework of the smart grid is based upon unbundling and restructuring the power sector and optimizing its assets [4-5].

With the rapid growth of IoT technology, it has been applied to an increasing number of fields, such as intelligent agriculture, industrial automation, smart city, smart home, etc. [6]. Currently, the most widely used ZigBee, Bluetooth, 2G, 3G, 4G, and other communication technologies have their own pros and cons [7][8]. Xing et al. proposed a greenhouse intelligent information monitoring system using ZigBee wireless sensor. This system used ZigBee wireless sensor to collect field environmental parameters and realized centralized monitoring, data display, data storage, and data mining [9]. Shen et al. enabled traffic information detection using Bluetooth communication, i.e., Bluetooth communication, i.e., to transmission of vehicle position, speed, etc. information via Bluetooth [10]. Zhang et al. proposed wireless sensor monitoring nodes powered by solar panels and realized real-time, accurate, and remote transmission data using GPRS technology [11]. However, ZigBee and Bluetooth are short-range radio technologies and are not suitable for long-range transmission scenarios. 2G, 3G, 4G, and other solutions based on cellular communication can
provide a wider coverage, but they consume too much energy and increase the operating costs [8].

To solve these problems, LPWAN has emerged and gained wide attention from researchers which have analyzed low-power and long-range wireless technology, implemented a networking scheme and tested the performance of LoRa wireless transmission technology [12]. Shi et al. proposed a smart parking system using NB-IoT communication technology, which can effectively improve the utilization rate of the existing parking facilities [13]. Anand et al. presented a remote monitoring mechanism for the water level in a storage tank using NB-IoT [14]. The above studies show that LoRa has the advantages of high stability, ultralong transmission, ultralow power, and low cost [15].

Wide-area monitoring, wide-area control and wide-area protection utilize Wide Area Networks and turn out to be the next-generation key to improve power system planning, operation and protection in the smart grid. These applications employ the system broad data and wisely chosen local information to oppose the spread of harming disturbances [16]. Wide-area monitoring, control and protection applications present higher data resolution and shorter response time than the classical supervisory control and data acquisition (SCADA) and energy management (EMS) systems. Wide-area monitoring, control and protection applications provide high-resolution data contrary to SCADA/EMS which offers a measurement update interval of several seconds (or even minutes) [17].

The IEEE Standard for Synchrophasors for Power Systems (IEEE Std.C37.118 provides definitions of measurement and data transmission formats for real-time data reporting in electric power systems [18]. For wide-area monitoring applications, the size containing measurements made by a PMU has a minimum message of 52 bytes. The required response time for wide area monitoring applications is in the range of milliseconds to minutes, and the requirement on communication system reliability is very high. Due to the importance of the communication infrastructure in the success of smart grid implementation and operation, there has been a variety of research works in the literature focusing on this topic, so the suitable communication technologies for transmission-level systems for a long-distance are important [19].

Multiple-input multiple output (MIMO) techniques are being widely adopted in the current fourth generation (4G) telecommunication systems and they are expected to be a key technologies for the fifth-generation (5G) communications. MIMO systems take advantage of the multipath nature of the propagation channel. However, the antenna properties turn out to affect correlations among channel coefficients. MIMO, as a currently well established technology, offers considerable benefits, such as improving link quality and largely attainable data rates [20-21]. When antenna array elements are made closer one another, the effect of electromagnetic mutual coupling between them becomes a common phenomenon. The mutual coupling can dangerously deteriorate the performance of the array in the form of signal-to-interference-noise ratio (SINR) reduction and the signal processing algorithm non-convergence [22-23]. It precisely degrades some parameters such as the carrier frequency offset [24], channel [25], and angle of arrival estimations [26]. Also, the awful effect of mutual coupling on the active reflection coefficient of a MIMO antenna is another result that cannot be ignored [27]. Furthermore, the active voltage standing wave ratio (VSWR) may reach intolerable values. Despite the negative effects of mutual coupling, the MIMO system performance deterioration, it can be exploited for array calibrations as in [28-29]. The mutual coupling modifies the antenna characteristics in an array, and hence affects the MIMO system performance (e.g., capacity, error rate, and spectral re-growth). The system performance can be partly improved by adjusting out the mutual coupling using digital techniques but without improving the SINR. Thus, it is very imperative to lessen the mutual coupling when it comes to MIMO antenna design.

The aim of this paper is to use different communication technologies to improve data transfer in terms of data completeness and correctness in Wide Area Monitoring system by using the software MATLAB for the simulation. We started by two spatial diversity techniques which are SISO and MIMO systems after that we mainly studied the transmitted and the received signal of the IEEE-14 bus standard power system based on LoRa emulator code on MATLAB.

2. WAMS COMMUNICATION SYSTEMS

2.1. SISO and MIMO systems

Modern wireless communication demands constant improved spectral efficiency. More
number of users is needed to be accommodated in a given bandwidth with high quality standards for communication. Different diversity techniques are used for it. Spatial diversity deals with multiple number of transmitting and receiving antenna at transmitter and receiver respectively. When the same signal is transmitted or received via multiple devices, spatial diversity is formed. SISO is the simplest antenna technology in which one antenna is used at the source (transmitter) and one antenna is used at the destination (receiver). As no diversity is applicable in SISO case, multipath fading[29] is a prominent issue in this category of communication [30-32].

The most significant technological developments in communication are using Multiple Input Multiple Output (MIMO) antenna architectures [33]. In a MIMO system, multiple element antenna arrays are deployed at both the transmitter and the receiver. The suitability of a MIMO wireless system for spatial multiplexing is largely dependent on the characteristics of the wireless channel, the antenna configuration and the ability of the receiver to accurately recover the channel coupling matrix coefficients. The communications challenge lies in designing the sets of signals simultaneously sent by the transmit antennas and the algorithms for processing those observed by the receive antennas, so that the quality of the transmission (i.e., bit error probability) and/or its data rate are superior to those supported by traditional single antenna systems [34]. These gains can then provide increased reliability, reduced power requirements and higher composite data rates. What is especially exciting about the benefits offered by MIMO technology is that they can be attained without increasing the data rate. The most meaningful criterion for evaluation of performance of communication systems is the bit error rate (BER). The Bit Error Rate (BER) is the number of acceptable errors you are prepared to tolerate. This ratio is closely linked to the Signal-to-Noise-Ratio (SNR) which is measured in decibels (dB). In the case of orthogonal communications systems, the main sources affecting its BER performance are additive white Gaussian noise (AWGN) and Inter-carrier Interference (ICI). In most of the cases, the ICI is assumed to have a normal distribution; however such assumption is not accurate theoretically. With the help of well-developed conventional single carrier communication systems, the BER expression of OFDM systems can be obtained without knowing the ICI distribution function.

2.2. Performance Measures
Signal-to-noise ratio (SNR) is defined as the ratio of the desired signal power to noise power. SNR indicates the reliability of link between the transmitter and receiver. In OFDM based multicarrier modulation system, the channel bandwidth is wide and interference is not constant over the whole band in use. It is very likely that there is variation of spectral content over the OFDM sub carriers i.e. some part of spectrum is more affected by interference than the other parts of spectrum. The most meaningful criterion for evaluation of performance of communication systems is the bit error rate (BER). The Bit Error Rate (BER) is the number of acceptable errors you are prepared to tolerate. This ratio is closely linked to the Signal-to-Noise-Ratio (SNR) which is measured in decibels (dB).

2.3. Description of LoRa Technology:
As one of IoT communication technologies, LoRa is a kind of ultra-long distance wireless transmission technology based on the spread spectrum transmission techniques and CSS (chirp spread spectrum) modulation, which is one of the IoT communication technologies. Its name comes from the abbreviation of “long range”. LoRa’s spread spectrum technology changes the balance between transmission power consumption and transmission distance, and completely changes the situation in the field of embedded wireless communication. This technology presents a new communication technology that enables long-distance, long battery life, large system capacity and low hardware costs to meet the IoT needs [35].

Table 1 compares some parameters including transfer rate, transmission range, power consumption and cost between some popular wireless technologies. Accordingly, LoRa has shown its superiority in many aspects. Its only weakness is the data rate. However, in wireless sensor network applications, this is not an issue.
### Table 1: Comparison of some wireless technology

| Technology       | TX Rate | TX Power | Sleep Power | Cost  |
|------------------|---------|----------|-------------|-------|
| Bluetooth        | 15 M    | 20 mA    | 16 µA       | low   |
| Wifi (CC3200)   | 150 M   | 75 mA    | 3.5 µA      | high  |
| 3G/4G (U8300)   | 14 Mbp  | 800 mA   | 50 µA       | high  |
| ZigBee (REX 3DP)| 250 Kbps| 200 mA   | 0.4 µA      | low   |
| LoRa (SX1278)   | 3000 M  | 110 mA   | 2.0 µA      | low   |

LoRa was developed by Semtech to work in 433.868 or 915 MHz ISM Band (depend on the regional placement) with transmission rate between 0.25kbps-50kbps [37]. The parameters that possibly changed in LoRa modulation are Bandwidth, Spreading Factor and Code Rate. The spreading factors are - in short - the duration of the chirp. LoRa operates with spread factors from 7 to 12. SF7 is the shortest time on air and SF12 will be the longest. Each step up in spreading factor doubles the time on air to transmit the same amount of data [38] [39].

### 3. SIMULATION RESULTS AND DISCUSSIONS

#### 3.1. System description

The work considers a small scale wide area monitoring system, the power system used in our work is the IEEE 14 bus standard system, the placement of PMUs is important as we want to make the entire system observable, with zero injection at bus 7, only 3 PMUs placed at bus 2, 6 and 9 are needed. SISO and MIMO communication Simulink models are considered. The data collected from each PMU is sent through both SISO and MIMO systems. The three PMUs are synchronized using GPS clock. The state of all the power system is estimated using the received data from these three PMUs, to compare the performance of both SISO and MIMO Systems in terms of Bit Error Rate; BER (data correctness). The SNR (signal to noise ratio) with an additive White Gaussian Noise (AWGN) block was varied and the effect of this change on the BER is investigated. The measurement are sent by using the Function LoRa_Tx and received by the function LoRa_Rx on MATLAB which are an open source code in [40]. The work is based on a modified pilot file that is changed into 3 different files to allow transferring of real values measurement’s for the 2nd bus, 6th bus and the 9th bus.

#### 3.2. Results and Discussions

Performing simulations based on the Simulink model and the Pilot files produces figures 1, 2 and 3 for buses 2, 6 and 9 in terms of amplitude, phase and frequency, respectively.

![Fig. 1 Amplitude, Phase and Frequency for 2nd bus.](image1)

![Fig. 2 Amplitude, Phase and Frequency for 6th bus.](image2)

![Fig. 3 Amplitude, Phase and Frequency for 9th bus.](image3)

From the above figures, we can see that the transmitted signal is approximately the same as the received one, with a slight change at some different period of time. The simulation time is 42.000000 min and 14.400000 sec with...
a decision instant of 1.483674 sec. Table 2 gives the time delay for each bus and their corresponding transmission error.

| Time delay (sec) | Error          |
|------------------|----------------|
| 2nd bus          | 0.845881       |
| 6th bus          | 0.805521       |
| 9th bus          | 0.786660       |

The data in the above table shows that the time delay and the error for each bus is achieving good results for the same reporting rate at different buses in the system.

| Time delay (sec) | Error          |
|------------------|----------------|
| 2nd bus          | 0.783991       |
| 6th bus          | 0.768762       |
| 9th bus          | 0.774819       |

From Table 3, we can see that the time delay and error decrease as we change the reporting rate factor which lead to a new value of the reporting rate. The increase of the reporting rate affect the time delay and error positively which we can say that the interval length at which the event will be reported should been taken into consideration for achieving better time delay and data error.

The effect of varying the reporting rate on error and delay:
We have changed the reporting rate by changing the reporting factor \( k \) =4. The following results are obtained. The simulation time is 39.000000 min and 0.631000 sec with a decision instant of 1.459555 sec.

From Table 3, we can see that the time delay and error decrease as we change the reporting rate factor which lead to a new value of the reporting rate. The increase of the reporting rate affect the time delay and error positively which we can say that the interval length at which the event will be reported should been taken into consideration for achieving better time delay and data error.

It should be noted that for the same Signal to Noise Ratio, it can be clearly seen that the MIMO system outperforms the SISO system in terms of data correctness (BER) which recommends its deployment in WAMS. As an example, The BER for the 2nd bus increases from 0.34893984308837 for SNR =0 to 0.441029359724782 for SNR=30 in the SISO system. However, it rises from 0.137060844986704 for SNR=0 to 0.208282807752671 for SNR=30 in the case of the MIMO system.

4. CONCLUSION
In this paper, communication techniques used in wide area monitoring systems have been investigated with focus on LoRa communication technology. The performance of the LoRa communication in terms of Bit Error Rate has been studied for both Single Input Single Output (SISO) and Multiple Input and Multiple Output (MIMO) systems. The transmitted and received signal based on LoRa modulation and coding scheme are almost identical which demonstrates the benefit of the LoRa communication technology over the other technologies for achieving better error and delay time. The simulation results demonstrate that the MIMO system is an option to adopt compared to the SISO system as better BER is achieved for the same SNR. Also, if blended with the LoRa technology, the results show that this Technology is more practical which is beneficial to the design of better communication infrastructure in wide area systems.

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