Quantum Optimal Control for Particles at Cross-Section in Nucleus

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Abstract

In this work, a novel concept abstract surface (cross-section at nucleus) is proposed firstly. Quantum optimal control is interested in taking particles at Yukawa interaction of cross-section σ in the nucleus as target for controlling by external force. In the nucleus, as intersecting surface full of particles can be considered for applying control theory and numerical simulation using a stable semi-discrete algorithm. Theoretical investigation, computational approach and experimental demonstration had accomplished.

Keywords
Quantum control, Nucleus, Cross-section, Klein-Gordon-Schrödinger equation

Introduction

At the chemistry and physical fields, particle at matter (e.g., crystals, metal,...) surface had been researched for properties in chemical reactions. For instance, monolayers structure of a surface [1]; phase polarization control via coherent laser is understood by computational ability of supercomputer; control of electromagnetic radiation for plasmas design; optimization of 3D crystals to control electromagnetic field; and so forth. One of the achievements is awarded the Nobel Prize 2007 in chemistry [2] for Haber-Bosch process. Obviously, these outstanding contributions are laying on experimental methodology. On the other hand, quantum control in theory and in lab experiments are rapidly growing in a variety of fields, see previous papers [3-7]. It had already being stepped forward to control elementary particles at nucleus. Lasting striving must boost the appearance of breakthrough soonerafter. Meanwhile, a few contributions on control of particles as they are on the surface. One extremely interesting topic in here is focus on many-body problem at surface [1]. The objective particles can be regarded as electrons, nano-particles, atoms and molecules at a practical matter surface [1,5,8]. For example, observing Scanning Tunneling Microscope image, rectangular corrals in Figure 1A is representing quantum dots at a metal surface.

Poster [7] was to control of many body problem of elementary particles at corral of matter surface. Theoretical and computational issues had been surveyed for two dimensions case. Comparison to Scanning Tunneling Microscope (STM) images had evidenced of quantum control efficiently. The aim of [7] was to change the state of particle using external sorcing, such as electromagnetic field, Ti: Sapphire shaped laser, and ultra-short terahertz (THz) pulse. Computational approach of [7] is in (B) of Figure 1. As a attempt effort, numerical control approach is feasibly and flexibility in optical manipulation of quantum particles [9] at a practical surface.

In this article, the goal of quantum control is to originally propose the particles at abstract surface (intersecting surface) of a cross-section in nucleus. Not only theoretic investigation but also computational approach are executed for spatial dimension of two using a convergent numerical algorithm. The motivation is to apply quantum control theory to abstract surface science firstly, and illustrate proposed multi-body control theory by numerical experiments.

Lasting of decade study on control of nuclei, overwhelming the hesitation and difficulty, it is a surprising turning-point to find an entrance to pursue control of particles motion at cross-section in nucleus aided of basic physical concepts.

Many Body Physical Model

To deduce a rational physical control model for many-body Klein-Gordon-Schrödinger (K-G-S) dynamics system, full access for no control case can be found at Yukawa’s contributied works [8]. In here, it is to capture concerned matter for determining control. Citing [10], and with outing loss of generality to consider \( x = (x_1, x_2, x_3) \in \mathbb{R}^3 \), the governing system of \( 2n \) particles (nucleon \( \psi \), meson \( \phi_j \), j = 1, 2, ..., n) in the Yukawa interacting dynamics is

\[
\begin{align*}
\frac{i\hbar}{2} \frac{\partial}{\partial t} \psi^j &= \left\{ \frac{P^2}{2M} + g \left( \phi^j \sigma_+ \phi^j \sigma_- \right) + \frac{D}{2} \sigma_n \right\} \psi^j \\
\left\{ \Delta - \frac{1}{c^2} \frac{\partial^2}{\partial t^2} - \lambda^2 \right\} \phi^j &= -4\pi \kappa \psi^j \sigma_- \psi^j.
\end{align*}
\]

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Here $\sigma_i = (\sigma_\alpha \pm i\sigma_\pi) / 2$, $\sigma_\alpha$, $\sigma_\pi$, and $\sigma_n$ are Pauli matrices, $e = mc^2 \hbar$, $m$ is meson mass, $g$ is coupling constant for interaction of meson and nucleon ($g$ is $1 \sim 10$ fm, $1m = 10^{-15}$ m). $P = -i\hbar \mathbf{V}$ is momentum operator of a nucleon, $M = (M_n + M_p) / 2$, where $M_n$ and $M_p$ are the masses of a proton and a neutron, and $D = (M_n - M_p) \gamma$. The equation (1) represents Klein-Gordon equation for a particle $\psi$ in an external potential produced by nucleon field $\mathbf{V}$. In general, Klein-Gordon equation for a particle in electro-magnetic field takes the form of

$$\left\{ \left( \frac{i\hbar}{c} \partial_t + e \mathbf{A}_0 \right)^2 - c^2 \left( \frac{D}{c} \gamma^0 - M \right)^2 - m^2 c^4 \right\} \phi = 0,$$

where $\mathbf{A} = (A_0, \mathbf{A})$ is a vector potential of electro-magnetic field. The equation (2) can be regarded as Schrödinger equation [11] for a particle in an external potential produced by meson field $\mathbf{V}$. In particular, a standard way to introduce electro-magnetic interaction is by replacing in the figure brackets $P \rightarrow P - e \mathbf{A}$ and adding the term $-\mu \mathbf{H}$, where $\mu$ is magnetic moment of the particle and $\mathbf{H}$ is magnetic field. Hence, these given coupled equations for interacting mesons and nucleons in an external electromagnetic field:

$$\left\{ \left( \frac{i\hbar}{c} \partial_t + e \mathbf{A}_0 \right)^2 - c^2 \gamma^0 - M c^2 - e^2 \phi - m^2 c^4 \right\} \psi = 0,$$

where $\epsilon$ and $\epsilon'$ denote charges of corresponding neutron and meson. To access the physical quantities, cite [9] and [12]. Further, meson charge $e' = e$ for $\pi$ and $e' = -e$ for $\pi$ as in Table 1. Thus, one can attain free (uncontrolled) K-G-S system via the formulations (1) and (2), or (3) and (4) if set $H = 0$, $g \rightarrow -g$, $H_0 \rightarrow -\Delta$. Therefore, in the non-relativistic limit regime $0 < \epsilon < 1$ case, dissipative and damped Klein-Gordon-Schrödinger system can be deduced

$$\left\{ \frac{i\hbar}{c} \frac{\partial \psi}{\partial t} - \frac{\hbar^2}{2M} \nabla^2 \psi - \frac{\gamma}{2} \left( M_n - M_p \right) \psi = -e^2 \phi \psi', \right. \left. \frac{1}{c^2} \frac{\partial^2 \phi}{\partial t^2} + \Delta \phi - \frac{m^2 c^2}{\hbar^2} \phi' = 4\pi g \psi \psi. \right\} \psi,$$

where $H_{\Psi} = -i\alpha - e^2 \phi - e\epsilon$ and $H_{\phi} = \left\{ \frac{mc}{\hbar} \right\} - \gamma \phi - 2 e \psi$ are the external potential of Hamilton operators, which given by coupling and external control forces. $\alpha$ is dissipative constant, $\gamma$ is damped constant. Therefore, in the $(01)$ order speed of light regime $\epsilon = 1$, the control model for K-G-S system of $\psi$ and $\phi$ has the form of

$$\left\{ \frac{i\hbar \psi_j + \hbar^2}{2M} \nabla^2 \psi_j + i\alpha \psi_j + e \phi \psi_j + e\epsilon \psi_j = \alpha, \right.$$ \left. \frac{1}{c^2} \frac{\partial^2 \phi_j}{\partial t^2} + \phi_j + \gamma \phi_j = g \psi_j \right\}.$$

where $u$ and $v$ represent the external controlling inputs, and $j = 1, 2, ..., n$.

Quantum control is interested in taking particles at Yukawa

Table 1: Fundamental Physical Constants.

| Quantities          | Symbol, Values (unit) |
|---------------------|------------------------|
| Speed of light      | $c = 2.99792 \times 10^8$ (m/s) |
| Reduced Planck constant | $\hbar = 1.05457 \times 10^{-34}$ (Js) |
| Electron mass       | $m_e = 9.10938 \times 10^{-28}$ (kg) |
| Electron charge     | $e = 1.60218 \times 10^{-19}$ (c) |
| Electron radius     | $r_e = 2.817939 \times 10^{-15}$ (m) |
| Neutron mass        | $m_n = 1.67262 \times 10^{-27}$ (kg) |
| Neutron charge      | $\mu = 0$ (c) |
| Neutron radius      | $r_n = 1.11492 \times 10^{-13}$ (m) |
| Proton mass         | $m_p = 1.672684 \times 10^{-27}$ (kg) |
| Proton charge       | $\mu = 1.60218 \times 10^{-19}$ (c) |
| Proton radius       | $r_p = 1.113386 \times 10^{-13}$ (m) |
| Meson mass          | $m = 2.305589 \times 10^{-26}$ (kg) |
| Pion mass            | $0.99551904 \times 10^{-26}$ (kg) |
| Pion mass charge    | $e^\pi = 0.48(7)$ (c) |
| Pion radius          | $r_\pi = 1.53472 \times 10^{-16}$ (m) |
| Cross-section $\sigma$ unit | 1 barn = $10^{-24}$ (m²) |
| Cross-section $\sigma$ unit | 1 shed = $10^{-32}$ (m²) |

Figure 1: (A) STM image of corral, iron (Fe) on copper Cu(111); (B) Compute result of corral in [7].

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interaction of cross-section in nucleus as target. It is a convenient way to supply the arguments on cross-section in nuclear physics as background preparation. In atomic physics, cross-section indicates the probability that a particular interaction taking place among particles. The value of cross-section for any interacting process is depending on the particles under bombardment and upon energy of bombarding particles. Suppose \( n \) particles per second are incident on a target area \( \Omega \) containing \( N \) particles, and there are \( n \) of the incident particles produce a given nuclear reaction. If \( n < n \), then \( n = nN/\Omega \), where \( \sigma \) is the cross-section for the reaction; \( \sigma \) can be regarded as a disk of area \( \Omega \) surrounding each particle. The unit of effective cross-section area of nucleus is barn, and one barn equal to \( 10^{-28} \) m\(^2\).

K-G-S Control Problems

Consider particles appeared at a cross-section \( \sigma \) of abstract surface in nucleus [13]. Despite of particles at cross-section, theoretic discussion is not limited to two dimensions. Let \( \Omega \) be an open bounded set of \( \mathbb{R}^3 \) and \( Q = (0, T) \times \Omega \) for \( T > 0 \). Thus, for \( x = (x_1, x_2, x_3), (t, x) \in Q \). Suppose \( 2n \) particles involving Yukawa interaction [8] at a cross-section \( \sigma \) in nucleus, hence, Klein-Gordon-Schrödinger many-body dynamics is taking the form of

\[
\begin{aligned}
&ih \sum_{j=1}^{2n} \psi_j + \nabla^2 \psi_j + c \sum_{j=1}^{2n} \psi_j' + \lambda \sum_{j=1}^{2n} \psi_j' = 0, \\
&\sum_{j=1}^{2n} \psi_j = 0,
\end{aligned}
\]

where \( \hbar \) is reduced Planck constant, \( M \) is mass of nucleon, \( c \) is speed of light, \( i \) is imaginary part unit of scalar complex space \( \mathbb{C} \). Coefficients \( \alpha, \gamma \) are positive constants at dissipative and damped terms. A complex-valued function \( \psi(t,x) \) represents probability of \( j \)-th nucleon field, and a real-valued function \( \phi(t,x) \) represents that of \( j \)-th meson field for \( j = 1, 2, \ldots, n \).

In this work, K-G-S model (6) represents a many body dynamics full of \( n \) nucleons and \( n \) mesons at Yukawa interaction on a cross-section \( \sigma \) in nucleus. In particular, cross-section is probability for particles taking place at chemical reaction or physical interaction. At one moment \( t \), control attention is the particle at a certain cross-section (intersecting surface). It is a kind of abstract surface (plane or curved). Theoretically, time depended controls \( \mu(t) \) and \( \nu(t) \) are corresponding to external ultra-short (e.g. femtosecond/attosecond) laser pulses in real lab, or specially indicating external force, such as control rod in nuclear fuel of neutrons reaction for uranium 235U. More precisely, in the case of chain reaction for neutrons from nuclear fission of uranium. The moderator is to reduce the energy of neutrons and no capture many of them. In other words, neutrons need to react and change direction on colliding to nucleus and release energy, but not include fission. Not lacking of generality, carbon, beryllium, water and heavy water as mutated moderator. The control rod, inserted in moderator such as boron \(^1\)B and cadmium \(^{4}\)Cd, had the ability to absorb the neutrons effectively.

Inspired by neutrons chain reaction, it is clarifying to steer quantum control at nuclear scale by concentrating on particles at a cross-section \( \sigma \) in nucleus.

Figure 2: (A) Neutron \( n \), proton \( p \) interactions (from left to right); (B) Meson \( \pi \) exchange among neutron \( n \) and proton \( p \) (from bottom to top).
\( \psi \mapsto \mathbb{H} \mapsto \nabla \) two embeddings are continuous, dense and compact. Time
dependent controls \( u, v \in L^2(0, T) \) to ensure \( u_{\psi}, v_{\psi} \in L^2(0, T; V) \), avoid assumption on \( u(t, x), v(t, x) \) of nonsense, multiplied control terms to make well-posed in (6) and meaningful in practice.

For each particle \( \psi \) or \( \phi, j = 1, 2, \ldots, n \) at cross-section \( \sigma \) (take \( x = (x_1, x_2, 0) \)), apply control theory to quantum system (6) in the framework of variational method in Hilbert space [4,17]. Denote all particles probabilities as \( \psi = (\psi', \psi'', \ldots, \psi_n), \phi = (\phi', \phi'', \ldots, \phi_n) \) and analogous notations.

If ground states \( \psi_k \in \Psi, \phi_k \in \Phi, \phi \in H^\epsilon, then for control \( u(t) \) at arbitrary time \( t \in (0, T) \), above setting to assure that exist a weak solution \( (\psi, \phi, u) \) to solution space

\[
W(0,T) = \{ (\psi, \phi): |\psi| \in \mathbb{V}, |\psi'| \in \mathbb{V}' \}, \phi \in H^\epsilon, \phi' \in H^{1,\epsilon} \}
\]

for \( x = (x_1, x_2) \in \Omega \subset \mathbb{R}^2 \) and satisfy

\[
\int_{\Omega} \left[ \frac{1}{\hbar} \left| \phi \right|^\psi \right] + \frac{h^2}{2M} \left| \phi \right|^2 + i \epsilon \hbar \left[ \phi \right] + \hbar \phi \left[ \phi \right] \right] dx
\]

such that \( (\psi, \phi) = (\psi, \phi, u) = 0 \) a.e. in \( [0, T] \). From Sobolev space [16] to imply \( H^{-1}(0, T; \mathbb{L}^2(\Omega)) \) is dense in solution space (8) and weak form (7) too. It means that one wave packet \( \psi \) represent one nucleus \((n, \rho)\), and another wave packet \( \phi \) represent one meson \((\pi, \pi)\). The details interpretation in the equation (6). Qualitatively speaking, those solutions, \( \psi \), \( \phi \), are sufficiently smooth.

**Control Theory for Particles at Cross-section**

Start quantum nucleon control [13], suppose \( u = v \wedge v \in L^2(0, T) \) is the space of controls \( u \). For particles \( \psi', \phi', j = 1, 2, \ldots, n \) involved in Yukawa specific cross-section \( \sigma(x = (x_1, x_2)) \), quadratic cost criteria function of K-G-S many-body system (6) is described by

\[
J(u) = \varepsilon_1 \left| C_{\psi'}(u) - \psi_{\Sigma, \Sigma} \right|^2 + \varepsilon_2 \left| C_{\psi}(u) - \Sigma_\Sigma \right|^2
\]

where \( \psi_{\Sigma, \Sigma} = \Sigma, \Sigma \) are target states, \( \psi(u), \phi(u) \) are observed final states at time \( t_f \) respectively. In here, \( \varepsilon_i \) are weights coefficients for balancing the values of inherent cost and running cost. \( C \in L(\mathcal{W}(0, T), H) \) for Hamiltonian system, \( \Sigma \in L(\mathcal{U}(\mathcal{U}), H) \). To use the closed form of solution for many-body systems (6) subject to quadratic criteria function (8). The solution mapping \( u \mapsto (\psi, \phi); u \mapsto W(0,T) \) is continuous. Quantum optimal control \( u^* = (u^*, v^*) \) is characterized by simultaneously optimality system (Euler-Lagrange system) as:

\[
\begin{align*}
ih \psi_j &= \frac{\hbar^2}{2M} \psi_{\Sigma, \Sigma} + i \epsilon \psi_j + g \phi_j = eu_j \psi_j \quad \text{in } Q,

\frac{1}{C} \psi_j - \phi_j &= \epsilon \phi_j + \beta \phi_j = g |\psi_j|^2 + ev_j \phi_j \quad \text{in } Q,

\left( \psi_j, \phi_j \right) |_{t=0} &= (\psi_0, \phi_0, \phi_0) \quad \text{in } \Omega.
\end{align*}
\]

\[
\begin{align*}
ih \rho_j &= \frac{h^2}{2M} \rho_{\Sigma, \Sigma} + i \epsilon \rho_j + g \psi_j = eu_j \rho_j \quad \text{in } Q,

\frac{1}{C} q_j - q_{\Sigma, \Sigma} &= \epsilon \phi_j + \beta q_j = 2g |\psi_j|^2 + ev_j \phi_j \quad \text{in } Q,

q(T) &= 0, q(T) = C^* \left( C\psi_j(u^*) \right) \quad \text{in } \Omega.
\end{align*}
\]

(9) and (10)

\[
\begin{align*}
(u^* - u)^2 + \int_{Q} (p(u^*) - p(u)) dx dt \
\end{align*}
\]

where \( C^* \) is conjugate (adjoint) operator of \( C \). The weak solutions of adjoint system (10) corresponding to solution \( (\psi, \phi) \) of \( W(0,T) \) in (9). Respectively. It shows even that inequality (11) is the optimality necessary condition of quantum optimal control \( u^* = (u^*, v^*) \).

For Lagrange principle energy calculation, using vector \( y = (\psi', \phi', \psi', \phi')^T \) to write K-G-S many-body system (6) for one j-th particle in matrices as

\[
\begin{align*}
\begin{bmatrix}
 0 & 0 & 1 & 0 \\
 -1 & 0 & 0 & 1 \\
 0 & 0 & 1 & 0 \\
 0 & 1 & 0 & 0
\end{bmatrix} \begin{bmatrix}
 y \\
 y' \\
 y'' \\
 (\psi', \phi')
\end{bmatrix} = \begin{bmatrix}
 0 & 0 & 0 & 0 \\
 0 & 0 & 0 & 0 \\
 0 & 0 & 0 & 0 \\
 0 & 0 & 0 & 0
\end{bmatrix} \begin{bmatrix}
 y \\
 y' \\
 y'' \\
 (\psi', \phi')
\end{bmatrix} + K_{\psi'}(u) + (N(u) u)
\end{align*}
\]

Then for cost function (8), Lagrangian function of many body K-G-S control model 960 is generally in the form of

\[
\begin{align*}
L(\psi, \phi, u, v, p, \rho) &= \int_{Q} \left[ C_{\psi'}(u) - \psi_{\Sigma, \Sigma} \right] + \left[ C_{\phi}(u) - \phi_{\Sigma, \Sigma} \right] + (N(u) u)
\end{align*}
\]

In here, \( V^*, V \) are conjugate spaces of \( V^*, V \), and \( p \in V^*, q \in V, q_\Sigma \in \mathbb{V}, q_\Sigma \in \mathbb{H} \) are conjugates of \( \psi, \phi, \rho \), \( q_\Sigma \), \( \phi \), respectively. For practical calculation, take the form of integral of scalar product of duality, or take real form of complex function, and regard the dual of conjugate spaces as inner products of \( H \) by Gelfand tripe structures for effective values. Physical properties can be evaluated for Hamiltonian [19] function \( H(t) \) is the form of

\[
\begin{align*}
H(t) &= \int_{Q} \left[ C_{\psi'}(u) - \psi_{\Sigma, \Sigma} \right] + \left[ C_{\phi}(u) - \phi_{\Sigma, \Sigma} \right] + (N(u) u)
\end{align*}
\]

Here, \( p \in V^*, q \in V, q_\Sigma \in \mathbb{H} \) are solutions of adjoint system corresponding to \( \psi \in V^*, \psi \in \mathbb{V}, \phi \in H \) of K-G-S system (6). For given ground states \( \psi_0, \phi_0, \phi_0 \) Hamiltonian function only depended on
time $t$. Thus, from a start time $t_i$, the trajectory for one particle can be tracked and attain optimal control $u^*$ by $\inf u J(u) \rightarrow \inf u H(t)$.

Notable that, if needing consideration of special curved surface inside a matter or metal, abstract surface concept would be well-posed as extension. Vice versa, in practice, taking a real problem as abstract surface or dealing as boundary problem, it is credible case by case. Comprehensively, in controlling of nuclei, it is good at adopting cross-section as abstract surface.

**Computational Approach**

At the viewpoint of physics, for practical formulation and plots of a cross-section, refer to section 39-40 in distinguishing paper [12]. For multi-body decay or collision, the calculation for mass of effective particles is extensively discussed in section 38 [12] in the case of production of $n$-body final state. The differential expression of a cross-section of two-body is worked for uncontrolled particles. Comprehensively, in controlling of nuclei, it is good at adopting cross-section as abstract surface.

Reviewing the successful algorithms for optimal control in the area of quantum system, the significant ones are iteration learning algorithm [3], genetic algorithm, evolutional algorithm. Former paper [20] is for case of $n = 2$ quantum control typically. In this paper, for finding quantum optimal $u^*$, a reasonable semi-discrete algorithm (spatial variable $x$ discrete, time $t$ continuous) is employed for controlling manly-bodies dynamics at a cross-section $\sigma$ of nucleus. The wave-particles duality and uncertainty principle [21] permit the ideal and reliable scheme. Finite element method and nonlinear (updated) conjugated gradient method composed a convergent numerical paradigm, refer to [4], [6] and [7]. The convergence is guaranteed in the first order. To avoid complication, take real atomic scale as Table 1 in computing. Roughly set $M = M_x = M_t = 1, a = y = 0, m = h = c = 1, g = f$ and parameters setting for visualization effect. Fortunately, because of particles at abstract surface, it is appropriate and enough to consider two-dimensional case for spatial variable. Set $X = Y = 50 \ \mu m$, spatial domain $\Omega = (0, X) \times (0, Y)$, or regularization as disk of cross-section $\sigma$. Set center location $x_0 = 20.0$. Time duration $(t_f, T)$, start time $t_i = 0.0(\text{fs})$, iteration number $N \leq 8$, $dt = 0.5$, then iteration step $t = ndt (\text{fs})$, final time $T = Ndt (\text{fs})$. Define appendix functions for initial states configuration.

\[
\begin{align*}
\psi(t, x; v) &= \frac{3\sqrt{2}}{4(1-v^2)}\sec^2\frac{1}{2(1-v^2)}(x-vt-x_i) \exp \left( i\left(\frac{1}{2}\sqrt{1-v^2} - vt\right)\right), \\
\Phi(t, x; v) &= \frac{3}{4(1-v^2)}\sec^2\frac{1}{2(1-v^2)}(x-vt-x_i),
\end{align*}
\]

where $x \in \Omega$ is spatial variable, $v_i$ and $v_f$ are velocities (a.u. m/s) of nucleon and meson. Set $v_i = 5/6$ and $v_f = 5/6$. Gaussian enveloped function $s(t, a) = \exp(-6\pi(t-a)^2)$, then initial control functions (intensity unit W/cm$^2$) are $\psi(t)$ and $\psi(t)$, defined in the form of $u(t) = s(k, t)(\sin(300t + \frac{\pi}{6}) + \sin(100t + \frac{\pi}{3}))$ and $v(t) = s(k, t)(\sin(240t + \frac{\pi}{6}) + \sin(450t + \frac{\pi}{6}))$ for $k = 1, 2, \ldots, N$. Rabi-frequency are 300,100(GHz) for $u$, and 240, 450 (GHz) for $v$. For $j = 1, 2, \ldots, n$ and $j = i + 1(k = 1)$, initial ground states is taken as

\[
\begin{align*}
\psi_0 &= \sum_{j=1}^{45} \psi_j' = \sum_{j=1}^{9} \sum_{k=1}^{5} \Phi(0, \sqrt{(x_j - 5i)^2} + (x_j - 10k + 5)^2, v_j), \\
\phi_0 &= \sum_{j=1}^{45} \phi_j' = \sum_{j=1}^{9} \sum_{k=1}^{5} \Phi(0, \sqrt{(x_j - 5i)^2} + (x_j - 10k + 5)^2, v_j).
\end{align*}
\]

For two dimension domain $\Omega$, total particles, 45 nucleons and 45 mesons, are in a cross-section $\sigma$ at nucleus as control target. Take coefficients $c_1 = 5.0 \times 10^3$ and $c_2 = 3.0 \times 10^6$ in cost function (8). Therefore, by limited iteration steps, simulating probabilities of nucleons $\psi(t, x)$ at cross-section $\sigma$ in nucleus are listed in Figure 3. The amplitude of $\psi$ are changing from scale 2 a.u. to $10^6$ a.u. (Notice that if taking amplitudes of initial controls as $10^{-36}$, by converting, final amplitude is to $10^3$, all the normalizing probability $\psi < 1$ for $1 \leq j \leq n$, it is a good agreement to physical result).

In the mean time, for above particles, corresponding contour plots of nucleon $\psi(t, x)$ refer Figure 4 at same atomic scale of spatial $x$. Changing of the probabilities is for all particles as time varying.

Similarly, simulation results for probabilities of mesons $\phi(t, x)$ at cross-section $\sigma$ in nucleus are given in Figure 5. Clearly, from positive
to negative, the probability of meson is changed dramatically than that of nucleon. Finally, the amplitude of $\phi$ are changing from scale $2 \text{ a.u.}$ to $-10^{-11} \text{ a.u.}$ (Analogously, normalizing initial controls to $10^{-24}$ gauge, converted amplitude of meson $\phi$ from $10^{-24}$ to final $10^{-13}$, it is close the neutron radius (1), the right distance for meson into or escape from a neutron at a cross section $\sigma$ if the meson in the cloud of the neutron. Clearly, all the probability $\psi < 1$ for $1 \leq j \leq n$, and cross-section $\sigma$ is a confidence region as precise measurement).

From Table 1, meson mass $m \ll$ nucleon mass $M$ (pion $\pi$ mass is 0.148 times proton mass). The influence of external force is greater on mesons than on nucleons. Certainly, it is coincide to physics experiments. At each iteration, one can find corresponding contour plots of $\phi(t; x)$ in Figure 6 for mesons changing as time increasing.

At natural, through the matched simulation, particles transfer momentum and energy from one to another. Cost function at each step is calculated as $J = (1148.82, 1090.29, 2.60404 \times 10^{8}, 1.24037 \times 10^{10}, 1.15821 \times 10^{12}, 7.17372 \times 10^{14}, 7.22776 \times 10^{16}, 5.17419 \times 10^{18})$. Optimal cost value $J(u^*) = 1090.29 \text{ a.u.}$ for minimum of two terms in cost function (8), cost error is estimated as $58.5312 \text{ a.u.}$ Quantum optimal control functions $u^* = 0.000656573 \sin(300) \sin(200) \text{ W/cm}^2$ and $v^* = 0.00377467 \sin(250) \sin(450) \text{ W/cm}^2$.

Remarkable that the interaction between nucleons at nucleus is in huge and short range. Realistic quantum control at nuclei is much more difficult and complicated than theoretic prediction.

**Figure 4:** Contour plots of 45 nucleons $\psi(t; x)$ at per iteration $k$ under control $u(t)$, $k = 1, 2, \ldots, N$. One circle is expressed a contour plot of a particle.

**Figure 5:** Plots of 45 mesons $\phi(t; x)$ at per iteration $k$ under control $\psi(t)$, $k = 1, 2, \ldots, N$. One up-peak or down-peak is representing the probability of a particle at cross-section $\sigma$ in a nucleus.
Numerous problems needs us to solve for getting definite and correct conclusion: we worry about break the system itself by quantum measurement, and make control nonsense. we worry whether the results what we obtained is controlled the particle; and so on. These tough issues are laying on the physics and chemistry field in the near future.

Computational approach is occurred at two spatial dimension case to fit disklike cross-section $\sigma$ in nucleus as guidance. For various irregular shape cross-section, by adequate normalization or planarization, the bright idea can be extended to a broad class abstract surface inside of matter or metal. Additionally, comparison to STM image could be found from a large number of papers at atom or molecular manipulation of quantum dot.

Discussion

For control of one type particles in cost function (8), it concerns nuclear reaction, such as neutron absorption cross-section of uranium $^{235}\text{U}$ fission to neutrons by inserting control rod for nuclear fuel. Absolutely, if require maximum of first term in criteria cost function (8), it makes emission of huge energy from chain reaction of neutrons. Cost function optimal value $5.17419 \times 10^{23}$ a.u. is exactly indicating this case. Theoretical conclusion and numerical approach sufficiently verified each other, that also discriminate the uncertainties of separating or isolating simulation from realistic physics fact. It is convinced that computational result is certainly reflecting the situation of particles at a cross-section $\sigma$ under proper control. Definitely, calculation of Lagrange function and Hamiltonian function $H(t)$ for particles at a cross-section is satisfying for status of dynamical controlling. For given trajectories in spatial axes, one can define and calculate total energy potential function, Winger function $W(t)$ by sum of all the particles.

Concluding remark, the newly obtained results interpret and suggest that one can do control nuclear reaction at cross-section in nucleus at a substantial way. It cannot be crucial for solidly supporting by reliable particle physical concept of cross-section, developed surface science and successful quantum control theory.

Remarkably, the concept of abstract surface is breaking the subjects of definition on basic and practical surface, throughout all the scientific fields including mathematics, chemistry, physics and other areas. Beside cross-section in nucleus, abstract surface can be immediately extended and suitable to other intersecting surface. Hopefully, a completely different consideration for surface science and quantum control should be appeared. A great deal researches would be straightforwardly generated and developed by the benefit of this original work. Numerous mysteries are arising in here: quantitatively calculating the practical control force in nucleus at details; new type of physical control model; new control equipments and methodologies; new theory establishments; nuclear-scaled numerical approach; nuclear based quantum computation; and so forth. Apart from sophisticated control and traditional surface, a transparent pathway is found from surface science to nucleus. It is not just limited on quantum control, a perfect shortcut and interface to start a lot of discoveries and inventions from inside to outside. It is a confident insight along the direction to one of frontier realms.

Questions

A few questions are asked on quantum control nucleus at cross-section.

i) Why cross-section is selected for controlling particles in nuclei, not other mechanism or methodologies?

In fact, particles interacted others just like a kind of random Brown motion, or scatter. It is nonsense if tracking one particle using a laser-like force (gamma ray, $\gamma$, massless photon). As is well known, annihilation of electron-positron pair $e^-e^+ \rightarrow f \bar{f}$, and Tevatron proton-proton collision $p\bar{p} \rightarrow H^+H^-$ to produce Higgs particles (massive scale field, neutral Higgs boson) for fitting unsymmetric electroweak field at CERN (Higgs theory [2] awarded Nobel Prize 2013). Different from moving atom or...
molecular using tip of STM, it is incredible using one particle to interact (or collision) to another [7]. At current experimental level, LHC, one can produce a large number of particles (electron, proton) to interact or collide other large number of particles (positron, proton). It is quite like detect or discover a new particle, such as Higgs. For a tiny particle, its three-dimensional motion is not so important than that on two-dimensional cross-section. Although no awareness, indeed, it had and have been adopted on the CERN, SLAC, LHC, ALICE, etc. All detected result is intersected 2D picture of particles. In resultant, it is enough to control particle through cross-section at nucleus.

ii) How control takes place at cross-section?

Actually, aiding of the concept of cross-section, one can do control particles at nucleus directly, immediately and straightforwardly. At least, it is sufficiently for controlling particle now quantitatively, calculably in real physical lab. Theoretically, one can freely choose any cross-section for control purpose. Analytically, particles scatter to each other elastically or inelastically, using their incident angle to calculate and formulate the differential of cross-section $\sigma$. In converting to a solvable differential equation mathematically, no problems there whatever kind of particles involving control. Not lost of generality, cross-section give us huge space to do control in nuclei scale. In practice, benefiting from mutated equipments, one can control particles just like detect them.

iii) Never use one force to control or track a particle trajectory one by one in 3D nucleus solidly?

It is completely depended on the new instruments or improved equipments. Nowadays, one can step-forward to cross-section firstly.

iv) It needs clarifying that control at cross-section just in one atom?

No. Control taking place in a atom, it is a limited theoretic case. Neutrons chain reaction indicate a amount of neutrons fission from $^{235}$U, and non-stopping collide to others. It is covered in the scope of quantum control.

Conclusions

Consequently, initially in this work, controlling of many-body problem is explored for particles at rational abstract surface of a cross-section $\sigma$ in nucleus. Particle is changing from ground state to exciting state by acting of appropriate external forces. Theoretical and computational study is fairly interesting in the area of particle and quantum physics. To do control at abstract surface would be a new field of surface science in laboratory experiments aiding of modern advanced optical tools [22].

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