A minimal interface problem arising from a two component Bose–Einstein condensate via $\Gamma$-convergence

Amandine Aftalion · Jimena Royo-Letelier

Abstract We consider the energy modeling a two component Bose–Einstein condensate in the limit of strong coupling and strong segregation. We prove the $\Gamma$-convergence to a perimeter minimization problem, with a weight given by the density of the condensate. In the case of equal mass for the two components, this leads to symmetry breaking for the ground state. The proof relies on a new formulation of the problem in terms of the total density and spin functions, which turns the energy into the sum of two weighted Cahn–Hilliard energies. Then, we use techniques coming from geometric measure theory to construct upper and lower bounds. In particular, we make use of the slicing technique introduced in Ambrosio and Tortorelli (Commun Pure Appl Math 43(8):999–1036, 1990).

Mathematics Subject Classification 28A99 · 35J47 · 35Q40

1 Introduction

The aim of this paper is to prove a $\Gamma$-convergence result for a functional modeling a two component Bose–Einstein condensate in the case of segregation. We introduce a new formulation of the problem which transforms the two wave functions describing each component of the condensate into total density and spin functions. The new functional in the density and spin variables is given by the sum of two weighted Cahn–Hilliard energies modeling phase transition problems as in the Modica–Mortola problem [24]. In fact, our new functional is strongly related to that of Ambrosio–Tortorelli approaching the Mumford–Shah image segmenta-
tion functional [6]. We use techniques coming from geometric measure theory [4,6,9,10] to construct upper and lower bounds for our initial functional and prove $\Gamma$-convergence to a perimeter minimization problem, with a weight given by the density of the condensate. There is a large mathematical literature about the segregation patterns for two component Bose–Einstein condensates [7,8,13,14,26,28]: regularity of the limiting functions, regularity of the interface, asymptotic behaviour near the interface. All these papers use the limiting equations and do not take into account the trapping potentials and the $\Gamma$-convergence of the energy as we do.

Before introducing the functional for a two component Bose–Einstein condensate, we recall some properties of a single Bose–Einstein condensate (BEC). A single BEC is described by the wave function $\eta$ minimizing the energy

$$E_\varepsilon(\eta) = \frac{1}{2} \int_{\mathbb{R}^2} |\nabla \eta|^2 + \frac{1}{\varepsilon^2} V(x)|\eta|^2 + \frac{1}{2\varepsilon^2} |\eta|^4$$  \hspace{1cm} (1.1)

where $V$ is the trapping potential, usually taken to be harmonic, that is $V(x) = |x|^2$, $\varepsilon$ is a small parameter giving rise to a large coupling constant describing the repulsive self interaction of the condensate. The minimization is performed under the mass constraint $\int_{\mathbb{R}^2} |\eta|^2 = 1$. We define the ground state by

$$E_\varepsilon(\eta_\varepsilon) = \inf_{\int_{\mathbb{R}^2} |\eta|^2 = 1} E_\varepsilon(\eta),$$  \hspace{1cm} (1.2)

which is, up to multiplication by a constant, a real positive function. Let

$$\rho(x) = \max(\lambda^2 - |x|^2, 0)$$

with $\lambda > 0$ chosen such that $\int_{\mathcal{D}} \rho = 1$ where $\mathcal{D} = B(0, \lambda)$. \hspace{1cm} (1.3)

Then, when $\varepsilon$ is small, the ground state $\eta_\varepsilon$ is close to the function $\sqrt{\rho}$ in $\mathcal{D}$, with exponential decay at infinity. Properties of $\eta_\varepsilon$ can be found in [1,2,16,18,19].

A two component Bose–Einstein condensate can be experimentally realized as 2 isotopes of the same atom in different spin states [17] or isotopes of different atoms [25]. They are described by two wave functions $u_1$ and $u_2$, respectively representing components 1 and 2. The Gross–Pitaevskii energy of the two component condensate is given by

$$E_\varepsilon(u_1, u_2) = E_\varepsilon(u_1) + E_\varepsilon(u_2) + \frac{1}{2} g_\varepsilon \int_{\mathbb{R}^2} |u_1|^2 |u_2|^2,$$  \hspace{1cm} (1.4)

where $E_\varepsilon$ is given by (1.1) and $g_\varepsilon$ is the intercomponent coupling strength. The energy is minimized under the mass constraints

$$\int_{\mathbb{R}^2} |u_j|^2 = \alpha_j \quad \text{with } \alpha_j > 0 \text{ and } \alpha_1 + \alpha_2 = 1.$$  \hspace{1cm} (1.5)

In [22], numerical simulations have been performed to classify the ground states according to the values of $\varepsilon$, $g_\varepsilon$ and also the rotational velocity. For $\varepsilon$ small and $g_\varepsilon$ large, the numerical evidence is that, for $\alpha_1 = \alpha_2 = 1/2$, the preferred ground state is such that each component is asymptotically located in a half disk with a local inverted parabola profile. If $\alpha_1 \neq \alpha_2$, they occupy sections in a disk, the area of which is proportional to $\alpha_i$. In particular, when neither $\alpha_i$ is too small, this configuration has less energy than a disk vs annulus configuration, which
also provides segregation but preserves symmetry. Observation of symmetry breaking has also been obtained experimentally very recently [23]. The breaking of symmetry has been analyzed in [27] in a different limit, namely in the case \( \varepsilon \) large and \( g_{\varepsilon} \) large.

Here, we assume strong coupling between components, that is, \( g_{\varepsilon} \to \infty \), and we study the regime

\[
g_{\varepsilon} \varepsilon^2 \to +\infty \quad \text{and} \quad \varepsilon \to 0. \tag{1.6}
\]

A trick introduced in [22] is to use a spin formulation also called the nonlinear sigma model. In our special setting, since the ground states are non vanishing real functions, this amounts to defining

\[
v := \sqrt{|u_1|^2 + |u_2|^2} \quad \text{and} \quad \frac{\varphi}{2} := \text{Arg} \left( \frac{|u_1| + i|u_2|}{\sqrt{|u_1|^2 + |u_2|^2}} \right). \tag{1.7}
\]

where \( \eta_{\varepsilon} \) is defined in (1.2). The definition of \( \varphi \) implies that \( |u_1|^2 - |u_2|^2 = \eta_{\varepsilon}^2 v^2 \cos \varphi \). The mass constraints (1.5) can be written as

\[
\int_{\mathbb{R}^2} \eta_{\varepsilon}^2 v^2 = \alpha_1 + \alpha_2 = 1 \quad \text{and} \quad \int_{\mathbb{R}^2} \eta_{\varepsilon}^2 v^2 \cos \varphi = \alpha_1 - \alpha_2. \tag{1.8}
\]

We point out that \( \cos \varphi \) corresponds to the third component of the spin function. Because there is no rotation in the system, the ground states are, up to multiplication by a complex number of modulus one, positive functions. Thus, the second component of the spin is zero and the first one is \( \sin \varphi \).

Since the components are expected to segregate, the expected behaviour is thus that \( v \) tends to 1 except on a transition line corresponding to the interface between the two components, while \( \varphi \) tends to 0 on component 1 and \( \pi \) on component 2. This is what we want to analyze rigorously.

We split the energy into its main contributions and will prove that

\[
E_{\varepsilon}(u_1, u_2) = E_{\varepsilon}(\eta_{\varepsilon}) + F_{\varepsilon}(v, \varphi) \tag{1.9}
\]

where \( E_{\varepsilon} \) is given by (1.1), \( \eta_{\varepsilon} \) is the ground state of \( E_{\varepsilon} \) and

\[
F_{\varepsilon}(v, \varphi) = F_{\varepsilon}(v) + G_{\varepsilon}(v, \varphi) \tag{1.10}
\]

with

\[
F_{\varepsilon}(v) = \frac{1}{2} \int_{\mathbb{R}^2} \eta_{\varepsilon}^2 |\nabla v|^2 + \frac{1}{2\varepsilon^2} \eta_{\varepsilon}^4 (1 - v^2)^2, \tag{1.11}
\]

\[
G_{\varepsilon}(v, \varphi) = \frac{1}{8} \int_{\mathbb{R}^2} \eta_{\varepsilon}^2 v^2 |\nabla \varphi|^2 + \eta_{\varepsilon}^4 v^4 \tilde{g}_{\varepsilon} \{1 - \cos^2(\varphi)\} \tag{1.12}
\]

and \( \tilde{g}_{\varepsilon} = g_{\varepsilon} \left(1 - \frac{1}{g_{\varepsilon}^2} \right) \). Since \( \eta_{\varepsilon}^2 \) converges to \( \rho \) given by (1.3) in \( \mathcal{D} \), the limits of \( F_{\varepsilon} \) and \( G_{\varepsilon} \) can be analyzed as the limits of

\[
\frac{1}{2} \int_{\mathcal{D}} \rho |\nabla v_{\varepsilon}|^2 + \frac{1}{2\varepsilon^2} \rho^2 (1 - v_{\varepsilon}^2)^2 \tag{1.13}
\]

\[
\frac{1}{8} \int_{\mathcal{D}} \rho v_{\varepsilon}^2 |\nabla \varphi_{\varepsilon}|^2 + \rho^2 v_{\varepsilon}^4 \tilde{g}_{\varepsilon} \{1 - \cos^2(\varphi_{\varepsilon})\}. \tag{1.14}
\]
These two energies are of Modica Mortola types with a weight which vanishes on the boundary of $D$. Given the definition of $\varphi_\varepsilon$, there is a domain where $\cos \varphi_\varepsilon$ tends to 1 (asymptotic region of component 1) and a domain where $\cos \varphi_\varepsilon$ tends to $-1$ (asymptotic region of component 2), and thus a transition region exists between the two domains. Two options exist for $v_\varepsilon$:

- either $v_\varepsilon$ goes to 1 everywhere, which makes the first energy small and the second energy of order $\sqrt{\tilde{g}_\varepsilon}$,
- or $v_\varepsilon$ goes to zero on the transition line where $\cos \varphi$ varies from $+1$ to $-1$: this makes the second energy of lower order and the first energy of order $C/\varepsilon$.

Because of our hypothesis that $\varepsilon^2 \tilde{g}_\varepsilon$ tends to infinity, it is the second scenario which costs less energy. Though $v_\varepsilon$ goes to 1 on each component, it has a transition region of size $\varepsilon$ where it goes sharply to zero. The second energy is of lower order and cannot be seen in the limit. It has just the effect of creating a small region around the interface where $v_\varepsilon$ is small. The first energy can be analyzed with techniques coming from [6] and, once the rescaling in $\varepsilon$ is made, the $\Gamma$-limit comes from the problem on lines:

$$I(x) = \inf \left\{ \frac{1}{2} \int_0^\infty \rho(x)(w')^2 + \frac{1}{2} \rho(x)^2 (1-w^2)^2; \ w \in \text{Lip}(\mathbb{R}_+), \ w(0) = 0 \text{ and } w(+\infty) = 1 \right\}.$$  

Using the Euler–Lagrange equation associated with $I$, we shall see that for $x \in D$, the infimum is attained by the function

$$w_x(t) = \tanh \left( \sqrt{\frac{\rho(x)}{2}} t \right),$$

and we shall have

$$I(x) = \sigma \rho(x)^{3/2} \ \text{with } \sigma = \frac{1}{\sqrt{2}} \int_0^1 (1-t^2) \, dt. \quad (1.15)$$

This means that $w_x$ is the optimal profile transition at the point $x$, and that $\sigma \rho(x)^{3/2}$ is the minimum energy needed by $w$, to go from 0 to 1 at $x$. In the 1D direction, this provides a weight $2\sigma \rho(x)^{3/2}$ because as $\varepsilon \to 0$, $v_\varepsilon$ goes from 1 to 0 on one side of the interface between the two components, and from 0 to 1 on the other side. Therefore, we expect the limit to be defined as the integral on the interface where $\varphi$ goes from 0 to $\pi$ of the function $2\sigma \rho(x)^{3/2}$. The natural setting to define this interface is the set of functions of bounded variation.

We define $X$ as the space of functions $\varphi \in BV_{\text{loc}}(D; \{0, \pi\})$ such that

$$\int_{\mathbb{R}^2} \rho \cos \varphi = a_1 - a_2. \quad (1.16)$$

We will prove the $\Gamma$-convergence of $\varepsilon (\mathcal{E}_\varepsilon (\cdot, \cdot) - E_\varepsilon (\eta_\varepsilon))$ to $\mathcal{F}$ given in $X$ by

$$\mathcal{F}(\varphi) = \frac{2\sigma}{\pi} \int_D \rho^{3/2} |D\varphi|.$$  

The limiting energy $\mathcal{F}$ measures the length, with a weight of $\rho^{3/2}$, of the interface between the two phases of $\varphi$. Each phase of $\varphi$ corresponds to one component of the totally segregated
two-component limiting condensate. Notice that when $\mathcal{F}(\varphi)$ is finite, $\{\varphi = \pi\}$ has finite perimeter in compact subsets of $\mathcal{D}$, and

$$\mathcal{F}(\varphi) = 2\sigma \int_{\mathcal{D} \cap \partial^*\{\varphi = \pi\}} \rho^{3/2} d\mathcal{H}^1 = 2\sigma \int_{\mathcal{D} \cap J_\varphi} \rho^{3/2} d\mathcal{H}^1.$$ 

Here $\partial^*\{\varphi = \pi\}$ stands for the reduced boundary of $\{\varphi = \pi\}$ and $J_\varphi$ is the complement of the Lebesgue points of $\varphi$, that is,

$$J_\varphi = \left\{ x \in \mathcal{D}; \not\exists \, t \in \mathbb{R} \text{ such that } \lim_{r \to 0^+} \frac{1}{\pi r^2} \int_{B_r(x)} |\varphi(y) - t| \, dy = 0 \right\}.$$ 

We refer to [5,10] for the concepts related with function of bounded variation and to [3,11] for the concepts on $\Gamma$-convergence. Throughout this paper, instead of sequences of functions labeled by a continuous parameter $\varepsilon$ which tends to infinity, we consider families of functions labeled by some integer parameter which tends to infinity, we consider families of functions labeled by a continuous parameter $\varepsilon$ which tends to 0. Nevertheless we use the term sequence also to denote such families. Similarly, a subsequence of $u_\varepsilon$ is any sequence $u_{\varepsilon_n}$ such that $\varepsilon_n \to 0$ as $n \to \infty$. We now state our main theorem:

**Theorem 1.1** Let us assume that $V(x) = |x|^2$, and let

$$\mathcal{H} = \{ (u_1, u_2) \in H^1(\mathbb{R}^2; \mathbb{R}) \times H^1(\mathbb{R}^2; \mathbb{R}), \int_{\mathbb{R}^2} V(u_1^2 + u_2^2) < \infty, (u_1, u_2) \text{ satisfies } (1.5) \}.$$ 

The functional $\varepsilon (E_\varepsilon(\cdot, \cdot) - E_\varepsilon(\eta_\varepsilon))$ $\Gamma$-converges with respect to the $L^1_{loc}(\mathcal{D}) \times L^1_{loc}(\mathcal{D})$ distance to $\mathcal{F}(\varphi)$, in the following sense:

- (Compactness) for every sequence $\{(u_{1,\varepsilon}, u_{2,\varepsilon})\}_{\varepsilon > 0}$ of minimizers of $E_\varepsilon$ in $\mathcal{H}$ such that
  $$\sup_{\varepsilon > 0} \varepsilon \left( E_\varepsilon(u_{1,\varepsilon}, u_{2,\varepsilon}) - E_\varepsilon(\eta_\varepsilon) \right) < +\infty,$$
  there exists $\varphi \in X$ and a (not relabeled) subsequence such that
  $$\left( u_{1,\varepsilon}, u_{2,\varepsilon} \right) \to \sqrt{\rho} \left( 1_{\{\varphi = 0\}}, 1_{\{\varphi = 1\}} \right) \text{ in } L^1_{loc}(\mathcal{D}) \times L^1_{loc}(\mathcal{D});$$

- (Lower bound inequality) the limit inf of $\varepsilon \left( E_\varepsilon(u_{1,\varepsilon}, u_{2,\varepsilon}) - E_\varepsilon(\eta_\varepsilon) \right)$ is finite.

- (Upper bound inequality) for every $\varphi \in X$, there exists a sequence $\{(u_{1,\varepsilon}, u_{2,\varepsilon})\}_{\varepsilon > 0} \subset \mathcal{H}$, converging as $\varepsilon \to 0$ to $\sqrt{\rho} \left( 1_{\{\varphi = 0\}}, 1_{\{\varphi = 1\}} \right)$ in $L^1_{loc}(\mathcal{D}) \times L^1_{loc}(\mathcal{D})$, such that
  $$\lim_{\varepsilon \to 0} \sup \varepsilon \left( E_\varepsilon(u_{1,\varepsilon}, u_{2,\varepsilon}) - E_\varepsilon(\eta_\varepsilon) \right) \leq \mathcal{F}(\varphi).$$

We point out that we only prove the $\Gamma$-convergence at the level of minimizers of $E_\varepsilon$. Indeed, minimizers of the functional have the property that they are positive functions which do not vanish. Therefore, this property allows the definition of $(v, \varphi)$ through (1.7). As usual, the $\Gamma$-convergence theorem implies the convergence of the energy of the ground states:

**Corollary 1.2** If $\{(u_{1,\varepsilon}, u_{2,\varepsilon})\}_{\varepsilon > 0}$ is a sequence of minimizer of $E_\varepsilon$ in $\mathcal{H}$, then

$$\lim_{\varepsilon \to 0} \varepsilon \left( E_\varepsilon(u_{1,\varepsilon}, u_{2,\varepsilon}) - E_\varepsilon(\eta_\varepsilon) \right) = \inf_{X} \mathcal{F}.$$
A study of the ground states of $\mathcal{F}$ allows us to prove symmetry breaking when neither $\alpha_i$ is too small, for instance if $\alpha_1 = \alpha_2 = 1/2$:

**Corollary 1.3** There exists $\delta_0$ of order 0.15, such that if $\alpha_1 \in [\delta_0, 1 - \delta_0]$, then for $\varepsilon$ sufficiently small, the minimizers $(u_{1,\varepsilon}, u_{2,\varepsilon})$ of $\mathcal{E}_\varepsilon$ in $\mathcal{H}$ are not radial.

**Remark 1.4** Our main theorem remains true when $V$ is any trapping potential for which we have good estimates for the ground state $\eta_\varepsilon$, namely the estimates in Proposition 2.1.

1.1 Links with related problems

The segregation behaviour in two component condensates has been widely studied: regularity of the wave function [14, 26, 28], regularity of the interface [13], asymptotic behaviour near the interface [7, 8]. The main difference with these references is that, on the one hand, we use mainly the energy instead of the equation and, on the other hand, we do not switch off the trapping potential by blowing up the problem near the interface or by considering a bounded domain with no trapping. Indeed, we consider the limit where $\varepsilon$ goes to zero at the same time as $g_\varepsilon \varepsilon^2$ going to infinity, so that it is the trapping potential which provides the leading order behaviour of the wave function through the inverted parabola profile $\rho$. In all the previous quoted references, $\varepsilon$ is set to 1, so that in the limit $g_\varepsilon$ large, the trapping potential is not present, and the limiting profile is 1. We deal with the trapping potential by a proper division of the limiting wave function which allows to express nicely the energy using a trick introduced by [20]. Nevertheless, our proofs which rely on energy considerations also provide information for the case $\rho = 1$.

In [7], the authors fix a point $x_\infty$ on the interface $\partial A$, and consider a sequence $x_\varepsilon$ tending to $x_\infty$ such that $u_{1,\varepsilon}(x_\varepsilon) = u_{2,\varepsilon}(x_\varepsilon) = m_\varepsilon$. An open question in [7] is to prove in 2D that $g_\varepsilon m_\varepsilon^4$ stays bounded. This may be obtained with our technique since in our case $m_\varepsilon$ is probably related to the minimum of $v_\varepsilon$. We detail this remark in Sect. 5.3.

1.2 Main ideas in the proof

Let us now give more details on the proof. The proof consists of upper and lower bounds, that we construct for the functional $\mathcal{F}_\varepsilon$ defined in (1.10).

For the upper bound, we choose the set $A$ where asymptotically $u_2$ will be $\sqrt{\rho}$. In a first step, we assume that $\varphi = \pi_1 I_A$, where $A$ is an open bounded subset of $\mathbb{R}^2$ with smooth boundary such that $\mathcal{H}^1(\partial A \cap \partial D) = 0$. The test function $\varphi_\varepsilon$ is matched between 0, in a subdomain of $D \setminus \bar{A}$, to $\pi$, in a subdomain of $A$, using a transition region of size $\varepsilon t_\varepsilon$. In order to approximate the optimal 1-dimensional profile that solves $I(x)$, we define

$$w_\varepsilon^{\ell}(t) = \max(m_\varepsilon, \min((1 + 2\ell) \tanh(|t|) - \ell, 1))$$

where $0 < m_\varepsilon = o_{\varepsilon \to 0}(1)$. Then we define

$$w_\varepsilon^{\ell,x_i}(t) = w_\varepsilon^{\ell}\left(\frac{\sqrt{\rho(y)}}{2} t\right),$$

for $|t| = |d(x_i)|/\varepsilon < R$ where $d(x_i)$ is the signed distance to the boundary. In order to construct $v_\varepsilon$, we need a partition of unity for $\partial A$, where we match the functions $w_\varepsilon^{\ell,x_i}$, as $x_i$ varies along this partition. For this $v_\varepsilon$, we can estimate $\mathcal{F}_\varepsilon$ with techniques similar to those of Modica–Mortola [24], and to the adaptation of these techniques to problems with weight by Bouchitté [9]. Because $\rho$ vanishes, we cannot use directly the results of Bouchitté and
we need precise estimates on the behaviour of \( \eta_{\varepsilon} \) near the boundary. Since \( w_{\varepsilon} \) is the optimal profile for the 1D version of (1.13), there is a transition from 1 to 0 and a transition from 0 to 1 and we find an upper bound which is \( 2 \int_{\partial A} I(x) \, d\mathcal{H}^1(x) \). Then we prove that for this test function, \( G_{\varepsilon}(v_{\varepsilon}, \varphi_{\varepsilon}) \) is lower order: indeed, the transition layer for \( \varphi \) is of order \( \varepsilon \), so much smaller than the one of \( v_{\varepsilon} \). Hence in \( G_{\varepsilon}, v_{\varepsilon} \) can be approximated by \( m_{\varepsilon} \). We choose \( m_{\varepsilon}^{\frac{4}{\sigma/\pi)} = (\varepsilon^2 g_{\varepsilon})^{-1} \), which tends to 0, and makes \( G_{\varepsilon} \) of lower order.

This provides the upper bound for an open bounded subset \( A \) with smooth boundary such that \( \mathcal{H}^1(\partial A \cap \partial D) = 0 \). Using Lemma 4.2, for any \( \varphi \in X \) the set \( \{ \varphi = \pi \} \) can be approximated by sets \( A \) which are open bounded subsets of \( \mathbb{R}^2 \) with smooth boundary such that \( \mathcal{H}^1(\partial A \cap \partial D) = 0 \). Moreover, we show in Sect. 6 that the mass constraints can be satisfied for the approximating \( u_{1,\varepsilon}, u_{2,\varepsilon} \).

The difficulty in the lower bound is to prove that \( v_{\varepsilon} \) goes to zero on a line and that it provides a positive lower bound. Indeed, the usual Modica–Mortola bound would imply that \( v_{\varepsilon} \) goes to 1 almost everywhere and the lower bound is 0. We have to use \( G_{\varepsilon} \) and the upper bound to prove that \( v_{\varepsilon} \) has a transition to 0 and that \( \cos^2 \varphi_{\varepsilon} \) tends to 1. Hence, because of the mass constraint, we get two regions where asymptotically \( \varphi_{\varepsilon} \) is 0 and \( \pi \). To analyze the behaviour of \( v_{\varepsilon} \), we use the slicing method introduced in [6] (see also [10, Section 4.1]). This consists in looking at the transition for \( v_{\varepsilon} \) in one dimensional slices and get the 1D energy estimate. The use of the energy \( G_{\varepsilon} \) is only to prove that \( v_{\varepsilon} \) goes to zero. We first prove the lower bound for \( \varepsilon \mathcal{F}_{\varepsilon} \) in 1D using the coarea formula, and then in 2D using the slicing method. We get that for any \( \varphi \in X, v \in S^1 \), a open subset of \( D \) and \( (v_{\varepsilon}, \varphi_{\varepsilon}) \rightarrow (1, \varphi) \) as \( \varepsilon \rightarrow 0 \), \( \lim \inf_{\varepsilon \rightarrow 0} \varepsilon \mathcal{F}_{\varepsilon}(v_{\varepsilon}, \varphi_{\varepsilon}, A) \geq \mathcal{F}^v(\varphi; A) \), where \( \mathcal{F}^v(\varphi; A) = (2\sigma/\pi) \int_{A \setminus J_{\varepsilon}} \rho^{1/2}(\varphi_{\varepsilon}, v) \, d\mathcal{H}^1 \). We conclude using Proposition 1.6.

We end this subsection with two technical results. The first one can be found in [21, Lemma 2.2] or in [9, Proposition 2], and will be used in the proof of the upper bound. The usual coarea formula, used in the proof of the upper bound in the Modica–Mortola theorem, is stated for functionals of the form \( \int_\Omega g(x)|\nabla f(x)| \) (see for example Theorem 2.93 and Remark 2.94 in [5]). In our setting, we have a more complex structure, with the integral \( \mathcal{F}_{\varepsilon} \) depending on the triplet \((x, v, Dv)\), so we need a more general form of the coarea formula. The following variant will suit our needs:

**Proposition 1.5** Let \( \Omega \) be an open bounded subset of \( \mathbb{R}^N \), and \( \Psi(x, s, p) \) a Borel function of \( \Omega \times \mathbb{R} \times \mathbb{R}^N \), which is sublinear in \( p \). Let \( u \) be a Lipschitz continuous function on \( \Omega \) and, for every \( t > 0 \), \( S_t = \{ x \in \Omega; u(x) < t \} \). Then, for almost every \( t \in \mathbb{R}, 1_{S_t} \) belongs to \( BV(\Omega) \) and we have

\[
\int_{\Omega} \Psi(x, u, Du) \, dx = \int_{-\infty}^{\infty} dt \int_{\Omega} \Psi(x, t, D1_{S_t}). \tag{1.22}
\]

The second result states a property of the supremum of a family of measures and will be used in the proof of the lower bound. It can be found in [10, Proposition 1.16].

**Proposition 1.6** Let \( \mu \) be a function defined on the family of open subsets of \( \Omega \) which is super-additive on open sets with disjoint compact closures (i.e., \( \mu(A \cap B) \geq \mu(A) + \mu(B) \) for all open \( A, B \subset \Omega \) with \( A \cap B = \emptyset \) and \( A \cup B \subset \subset \Omega \)), let \( \lambda \) be a positive measure on \( \Omega \), let \( \phi_i \) be positive Borel functions such that \( \mu(A) \geq \int_A \phi_i \, d\lambda \) for all open sets \( A \) and let \( \phi = \sup_i \phi_i \). Then \( \mu(A) \geq \int_A \phi \, d\lambda \) for all open sets \( A \).
We will apply it with $\Omega = D$,

$$\mu(A) = \inf \left\{ \liminf_{\varepsilon \to 0} \varepsilon F_\varepsilon(v_\varepsilon, \varphi_\varepsilon; A); (v_\varepsilon, \varphi_\varepsilon) \to (1, \varphi) \text{ in } L^1_{loc}(D) \times L^1_{loc}(D) \right\},$$

$$\lambda = \rho \mathcal{H}^1 \res J_{\varphi} \text{ and } \phi_i = |\langle \nu_{\varphi}, v_i \rangle| \text{ for } \{v_i\} \text{ a dense family in } S^1.$$

The paper is organized as follows: in Sect. 2, we present the properties of $\eta_\varepsilon$. Then in Sect. 3, we prove the decoupling of energy (1.9) and how to go from the $(u_1, u_2)$ formulation to $(v, \varphi)$. Section 4 is devoted to the upper bound, and Sect. 5 to the lower bound. Finally, in Sect. 6, we prove our main theorem and its Corollary 1.3.

1.3 To go further

1.3.1 Analysis of the limiting problem

A natural question is to analyze the limiting problem, that is the ground state of $F$ under the constraint (1.16). If we define $A$ to be the set where $\cos \varphi = 1$. Then $\int_A \rho = \alpha_1$ and $\int_{D \setminus A} \rho = \alpha_2$ with $\alpha_1 + \alpha_2 = 1$.

If $\rho = 1$, then the problem of minimizing $F$ amounts to minimizing $|\partial A|$ under the constraints $|A| = \alpha_1$ and $|D \setminus A| = \alpha_2 = 1 - \alpha_1$. The Euler–Lagrange equation of the minimization problem yields that the curvature is a constant, hence $A$ is either a disk, an annulus or a disk sector. The equivalent problem with a weight $\rho$ is open.

If we assume that the solution is either two disks sectors or a disk and an annulus, we can compute explicitly the energy $F$: we find that if $\alpha_1 = \alpha_2$, then the optimal configuration is two half disks, while if $\alpha_1$ is much less then $\alpha_2$, then the ground state is a disk and an annulus (see Sect. 6.3). Indeed, the energy of two disk sectors is $3\sigma/2$, while the energy of a disk and annulus is $8\sigma(1 - \alpha_1)^{3/4}(1 - \sqrt{1 - \alpha_1})^{1/2}$ if $\alpha_1$ corresponds to the mass of the inside disk. If $\alpha_1$ or $\alpha_2 = 1 - \alpha_1$ is too small, then the disk and annulus becomes the preferred configuration. In the case $\alpha_1 = \alpha_2 = 1/2$, it follows from our theorem that symmetry breaking occurs since at the limit, the disk plus annulus configuration does not minimize the energy. These two cases are well illustrated in the experimental observations of [23, figure 4].

We insist on the point that a rigorous analysis of the ground states of $F$ in $X$ is an interesting open question.

1.3.2 Convergence for $u_{1,\varepsilon}, u_{2,\varepsilon}$

The convergence that we have for $(u_{1,\varepsilon}, u_{2,\varepsilon})$ to $\sqrt{\rho}(1_{|\varphi=0|}, 1_{|\varphi=\pi|})$ is very weak. Nevertheless, we expect that on compact subsets of $1_{|\varphi=\pi|}$ or $1_{|\varphi=0|}$, the convergence can be improved. For instance, it would be natural to have similar convergence as that of $\eta_\varepsilon$ to $\sqrt{\rho}$ (that is $C^1_{loc}$) on these domains.

1.3.3 Case $g_\varepsilon \varepsilon^2$ of order 1

An interesting open question is to deal with the case when $g_\varepsilon \varepsilon^2$ tends to a positive finite constant $c_2^2$. In this case, $F_\varepsilon$ and $G_\varepsilon$ become of the same order and we expect that $m = \liminf_{\varepsilon \to 0} v_{\varepsilon}$ is a positive constant (on the interface where $\varphi$ varies), instead of being 0. We believe that our techniques still provide an upper bound for the problem. We expect the...
\[ \Gamma\text{-limit to be} \]
\[ \left( 2\sigma_m + c_0 \frac{\pi}{4} m^3 \right) \frac{1}{\pi} \int \rho^{3/2} |D\varphi| \]

where \( \sigma_m = \frac{1}{\sqrt{2}} \int_0^1 (1 - t^2) \, dt \).

1.3.4 Case of different scattering lengths

In this paper, we consider that the scattering lengths are the same for both components, that is, in (1.4) it is the same energy \( E_\varepsilon \) for both components. When the two components result experimentally from different atoms, the two scattering lengths are very close but not equal. This leads to an energy \( E_{\varepsilon,i}(\eta) \) depending on the component, namely

\[ E_{\varepsilon,i}(\eta) = \frac{1}{2} \int_{\mathbb{R}^2} |\nabla \eta|^2 + \frac{1}{\varepsilon^2} |x|^2 |\eta|^2 + \frac{g_i}{2\varepsilon^2} |\eta|^4, \]

where \( g_i \) is related to the scattering length of component \( i \). If \( g_1 \neq g_2 \), then the leading order Thomas Fermi approximation is no longer the same for each component, namely it is

\[ g_i \rho_i = \lambda_i^2 - |x|^2 \text{ in } B_i = B(0, \lambda_i). \]

The limiting problem becomes: find a partition of \( B_1 \cup B_2 \) into three sets \( A_1, A_2 \) and \( N \), such that \( u_{i,\varepsilon}^2 \to \rho_i 1_{A_i} \), \( \int_{A_i} \rho_i = \alpha_i \) and it minimizes

\[ \int_{A_1} |x|^2 \rho_1 + \frac{g_1}{2} \rho_1^2 + \int_{A_2} |x|^2 \rho_2 + \frac{g_2}{2} \rho_2^2. \] (1.23)

This problem is open and is probably related to the problem of finding a partition of the disk into two subdomains which minimize the sum of the first eigenvalues of the Dirichlet Laplacian.

Of course, in our case, since we have \( B_1 = B_2, \rho_1 = \rho_2 \) and \( N = \emptyset \), (1.23) does not provide any information at leading order. This is why we have to go to the next order which yields the perimeter minimization problem.

2 Estimates for \( \eta_\varepsilon \)

Let \( \eta_\varepsilon \) be the ground state defined by (1.2). The ground state is a non vanishing radially symmetric function. It is unique up to multiplication by a constant of modulus one, and satisfies the Gross–Pitaevskii equation

\[ -\Delta \eta_\varepsilon + \frac{1}{\varepsilon^2} |x|^2 \eta_\varepsilon + \frac{1}{\varepsilon^2} |\eta_\varepsilon|^2 \eta_\varepsilon = \frac{\lambda_\varepsilon}{\varepsilon^2} \eta_\varepsilon. \] (2.1)

The term \( \varepsilon^{-2} \lambda_\varepsilon \) is the Lagrange multiplier associated with the mass constraint, and the pair \( (\eta_\varepsilon, \lambda_\varepsilon) \) is unique among positive solutions of (2.1). As \( \varepsilon \) tends to 0, \( \eta_\varepsilon \) tends to \( \sqrt{\rho} \) given by (1.3). Throughout the paper, we will need precise estimates for this convergence. The following proposition, based on previous results in [2, 15, 16, 18, 19], sums up the properties of \( \eta_\varepsilon \). We point out that it follows from [15, 16, 19] that an approximation of \( \eta_\varepsilon \) by \( \sqrt{\rho} \) holds as close to the boundary of \( D \) as needed and is given by (2.5). We also include an estimate of \( \rho \) in terms of the distance to the bulk that will be used in the proofs.
Proposition 2.1 There are constants $c, C > 0, \alpha \in (1/2, 3/5)$ and $\gamma \in (1/2, 3/4)$, such that for $\varepsilon$ sufficiently small, $\rho, \lambda$ being given by (1.3),

$$E_\varepsilon(\eta_\varepsilon) \leq C/\varepsilon^2,$$  \hfill (2.2)

$$|\lambda_\varepsilon - \lambda| \leq C \varepsilon |\ln \varepsilon|^{1/2},$$  \hfill (2.3)

$$\|\eta_\varepsilon - \sqrt{\rho}\|_{C^1(K)} \leq C_{\varepsilon^2} \ln \varepsilon \quad \text{for } K \subset \subset D,$$  \hfill (2.4)

$$|\eta_\varepsilon(x) - \sqrt{\rho}(x)| \leq C \varepsilon^\gamma \quad \text{for } x \in B(0, \lambda - c \varepsilon^\alpha),$$  \hfill (2.5)

$$\eta_\varepsilon(x) \leq C \varepsilon^{1/6} e^{c\varepsilon^{-1/3}(\lambda - |x|)} \quad \text{for } x \in \mathbb{R}^2 \setminus D,$$  \hfill (2.6)

$$\delta_{\varepsilon}(\eta_\varepsilon(x)) \leq 0 \quad \text{for } x \in \mathbb{R}^2,$$  \hfill (2.7)

$$\frac{\rho(x)}{\lambda_{dist}(x, \partial D)} \in [1, 2] \quad \text{for } x \in D.$$  \hfill (2.8)

Proof For the proof of (2.2), one can rewrite the energy as

$$E_\varepsilon(\eta) = E_\varepsilon^1(\eta) + \frac{1}{2\varepsilon^2} \left( \lambda^2 - \frac{1}{2} \int_{\mathcal{D}} \rho^2 \right),$$  \hfill (2.9)

where

$$E_\varepsilon^1(\eta) = \frac{1}{2} \int_{\mathbb{R}^2} |\nabla \eta|^2 + \frac{1}{2\varepsilon^2} \left( |\eta|^2 - \rho(x) \right)^2 + \frac{1}{\varepsilon^2} (\lambda^2 - |x|^2) - |\eta|^2,$$

and $(\lambda^2 - |x|^2)_-$ is the negative part of $(\lambda^2 - |x|^2)$. In Theorem 2.1 of [2], it is proved that $E_\varepsilon^1(\eta) \leq C |\ln \varepsilon|$. Then (2.2) follows from (2.9) and the fact that $\int_{\mathcal{D}} \rho^2 = 2\lambda^2/3$.

Estimate (2.4) is proved in Proposition 2.2 of [18]. Estimates (2.3) and (2.6) are proved in Theorem 2.1 of [2]. Estimate (2.7) is also proved in Theorem 2.1 of [2], but only in a neighborhood of $\partial D$. But the proof, however, works in the case $V(x) = |x|^2$ and the estimate holds in all $\mathbb{R}^2$.

We now prove (2.5). For $\lambda > 0$, we define $\tilde{\eta}_{\varepsilon, \lambda}$ as the unique radially symmetric, positive solution of the equation

$$-\varepsilon^2 \Delta \eta + (\lambda^2 - |x|^2) \eta + \eta^3 = 0.$$  \hfill (2.10)

The function $\tilde{\eta}_{\varepsilon, \lambda}$ corresponds to a ground state of a BEC without mass constraint. In [15, 16, 18], the behavior of $\tilde{\eta}_{\varepsilon, \lambda}$ is studied. Using the results in Proposition 1.2, Remark 1.3 and Proposition 1.4 in [15], we obtain

$$\tilde{\eta}_{\varepsilon, 1}(x) = \varepsilon^{1/3} v_0 \left( \frac{1 - |x|^2}{\varepsilon^{2/3}} \right) + \mathcal{O}(\varepsilon),$$

where

$$v_0(y) = y^{1/2} - \frac{1}{2} y^{-3/2} + \mathcal{O}_{y \to \infty}(y^{-11/3}), \quad y \in (-\infty, \varepsilon^{-2/3}].$$

Hence, for $x \in B(0, 1)$ we obtain

$$|\tilde{\eta}_{\varepsilon, 1}(x) - \sqrt{1 - |x|^2}| \leq C (\varepsilon^2 (1 - |x|^2)^{-3/2} + \varepsilon^4 (1 - |x|^2)^{-11/3} + \varepsilon).$$

In particular, if $x \in B(0, \lambda - \varepsilon^\alpha)$ with $\alpha \in (1/2, 3/5)$, we get

$$|\tilde{\eta}_{\varepsilon, 1}(x) - \sqrt{1 - |x|^2}| \leq C (\varepsilon^{3/2} e^{-5\alpha/2} + \varepsilon^4 e^{-11\alpha/2} + \varepsilon) = \mathcal{O}(\varepsilon^\gamma).$$  \hfill (2.11)
with \( \gamma \in (1/2, 3/4) \). We will use (2.11) to prove (2.5). First, a straight computation shows that defining \( \varepsilon_\lambda = \lambda^{-2} \varepsilon, \tilde{\eta}_{\varepsilon, \lambda} \) solves Eq. (2.10) with \( \lambda = 1 \). Hence, considering (2.11), a change of variables gives
\[
|\tilde{\eta}_{\varepsilon, \lambda}(x) - \sqrt{\rho}(x)| = O(\varepsilon^\gamma),
\]
for \( x \in B(0, \lambda - (\lambda^{-2} \varepsilon)\alpha) \). In Proposition 2.2 and Theorem 2.2 in [18], it is proved that
\[
\|\nabla \eta\|_{L^\infty(\mathbb{R}^2)} = O(\varepsilon^{-1});
\]
and that
\[
\eta_{\varepsilon, \lambda}(x) = \ell_{\varepsilon, \lambda}^{-1/2} \tilde{\eta}_{\varepsilon, \lambda}(\ell_{\varepsilon, \lambda}^{-1} x),
\]
where
\[
\ell_{\varepsilon, \lambda} = \left(1 + \frac{\varepsilon \lambda}{\lambda}\right) \quad \text{and} \quad \tilde{\varepsilon} = \ell_{\varepsilon, \lambda}^{-1} \varepsilon.
\]
It follows from (2.3) that
\[
\ell_{\varepsilon, \lambda} = 1 + O(\varepsilon^2 |\ln \varepsilon|^{1/2}) \quad \text{and} \quad \tilde{\varepsilon} = \varepsilon + O(\varepsilon^2 |\ln \varepsilon|^{1/2}).
\]
Hence, using (2.13) and (2.14), we obtain
\[
\eta_{\varepsilon, \lambda}(x) = \tilde{\eta}_{\varepsilon, \lambda}(x) + O(\varepsilon |\ln \varepsilon|^{1/2}).
\]
Putting this last estimate in (2.12), and using that \( \gamma \in (1/2, 3/4) \), we obtain
\[
|\eta_{\varepsilon, \lambda}(x) - \sqrt{\rho}(x)| = O(\varepsilon^\gamma),
\]
for \( x \in B(0, \lambda - c \varepsilon \alpha) \) with \( c > 0 \). We derive (2.5) by changing \( \varepsilon_\lambda \) by \( \varepsilon \) in the previous estimate. Finally, writing
\[
\frac{\rho(x)}{\lambda \text{dist}(x, \partial D)} = \frac{(\lambda + |x|)}{\lambda}
\]
we get (2.8) for \( |x| < \lambda \).

\[ \Box \]

3 Rewriting the energy

In this section, we prove equality (1.9), that is, the reformulation of the Gross–Pitaevskii energy of a two component condensate in (1.4), as the weighted Cahn–Hilliard energy for the pair \((v, \varphi)\) defined by (1.7), plus the energy of the ground state \( \eta_\varepsilon \) of a one component condensate. We start by giving the properties of the minimizers of \( E_\varepsilon \) and the properties of the corresponding pairs \((v_\varepsilon, \varphi_\varepsilon)\) defined by (1.7).

**Proposition 3.1** (i) Let \( \{(u_{1, \varepsilon}, u_{2, \varepsilon})\}_{\varepsilon > 0} \) be a sequence of minimizing pairs of \( E_\varepsilon \) in \( \mathcal{H} \) satisfying (1.17). Then, each component is a non vanishing smooth function, and there is \( C > 0 \) such that
\[
\|u_{1, \varepsilon}\|_{L^\infty(\mathbb{R}^2)}, \|u_{2, \varepsilon}\|_{L^\infty(\mathbb{R}^2)} < C
\]
for every \( \varepsilon > 0 \). Moreover, the pairs \((v_\varepsilon, \varphi_\varepsilon)\) are well defined by (1.7), verify the mass constraints (1.8) and we have
\[
(v_\varepsilon, \varphi_\varepsilon) \in Lip_{loc}(\mathbb{R}^2; (0, +\infty) \times [0, \pi])
\]
and
\[ \sup_{\varepsilon > 0} \| v_\varepsilon \|_{L^\infty(K)} < C_K \quad \text{for every } K \subset \subset D. \] (3.3)

(ii) Conversely, let \((v, \varphi) \in \text{Lip}(\mathbb{R}^2; (0, +\infty) \times [0, \pi])\) satisfying (1.8) such that \(v, \nabla v, \nabla \varphi \in L^\infty(\mathbb{R}^2)\). Then, defining
\[ u_1 = \eta_\varepsilon v \cos(\varphi/2) \quad \text{and} \quad u_2 = \eta_\varepsilon v \sin(\varphi/2), \] (3.4)
we have \((u_1, u_2) \in \mathcal{H}\) and \(|u_1|^2 + |u_2|^2 > 0\).

Proof. (i) Let \((u_{1,\varepsilon}, u_{2,\varepsilon})\) be a minimizer of \(E_\varepsilon\) in \(\mathcal{H}\). Since \(E_\varepsilon(|u_{1,\varepsilon}|, |u_{2,\varepsilon}|) \leq E_\varepsilon(u_{1,\varepsilon}, u_{2,\varepsilon})\), the pair of the absolute values satisfies the system
\[ -\Delta u_{1,\varepsilon} + (\varepsilon^{-2} V + \varepsilon^{-2} u^2_{1,\varepsilon} + g_u u^2_{2,\varepsilon}) u_{1,\varepsilon} = \lambda_{1,\varepsilon} u_{1,\varepsilon}, \] (3.5)
\[ -\Delta u_{2,\varepsilon} + (\varepsilon^{-2} V + \varepsilon^{-2} u^2_{2,\varepsilon} + g_u u^2_{1,\varepsilon}) u_{2,\varepsilon} = \lambda_{2,\varepsilon} u_{2,\varepsilon}, \] (3.6)
where \(\lambda_{1,\varepsilon}\) and \(\lambda_{2,\varepsilon}\) are the Lagrange multipliers associated with (1.5). The strong maximum principle yields that \(|u_{1,\varepsilon}|\) and \(|u_{2,\varepsilon}|\) are positive functions. Using standard elliptic regularity, we deduce further that \(u_{1,\varepsilon}\) and \(u_{2,\varepsilon}\) are non vanishing smooth functions. We use an argument in [18] to prove that \(u_{1,\varepsilon}\) and \(u_{2,\varepsilon}\) are uniformly bounded in \(\mathbb{R}^2\). Let us define \(w = \varepsilon^{-1}|u_{1,\varepsilon}| - \lambda_{1,\varepsilon}^{1/2}\). We have \(w \in L^3_{loc}(\mathbb{R}^2)\) and \(\Delta w \in L^1_{loc}(\mathbb{R}^2)\). Kato's inequality and Eq. (3.5) give
\[ \Delta(w^+) \geq \text{sgn}^+(w) \Delta w \geq \varepsilon^{-3} \text{sgn}^+(w) \varepsilon w + \varepsilon \lambda_{1,\varepsilon}^{1/2}/2 \geq (w^+)^3. \]
Hence, \(-\Delta(w^+) + (w^+)^3 \leq 0\) weakly in \(\mathbb{R}^2\) and Lemma 2 in [12] yield \(w^+ \leq 0\). We obtain \(|u_{1,\varepsilon}| \leq \varepsilon \lambda_{1,\varepsilon}^{1/2}\). Multiplying Eq. (3.5) by \(u_{1,\varepsilon}\) and then integrating we find \(\lambda_{1,\varepsilon}^{1/2} \leq 2 \varepsilon E_\varepsilon(|u_{1,\varepsilon}|, |u_{2,\varepsilon}|)\). Since \((u_{1,\varepsilon}, u_{2,\varepsilon})\) verifies (1.17), from estimate (2.2), we derive
\[ 0 < |u_{1,\varepsilon}| \leq \varepsilon \sqrt{(E_\varepsilon(u_{1,\varepsilon}, u_{2,\varepsilon}) - E_\varepsilon(\eta_\varepsilon)) + E_\varepsilon(\eta_\varepsilon)} < C. \]

We similarly prove that \(0 < |u_{2,\varepsilon}| < C\), so (3.1) is proved. Since \(\eta_\varepsilon > 0\), \(u_{1,\varepsilon}\) and \(u_{2,\varepsilon}\) do not vanish in \(\mathbb{R}^2\), the pairs \((v_\varepsilon, \varphi_\varepsilon)\) are well defined by (1.7) and \(v_\varepsilon > 0\). Since \(u_{1,\varepsilon}\) and \(u_{2,\varepsilon}\) are smooth, \(v_\varepsilon\) and \(\varphi_\varepsilon\) are locally Lipschitz functions so (3.2) holds. The definition of \(v_\varepsilon\) and (1.5) give
\[ \int_{\mathbb{R}^2} \eta_\varepsilon^2 v_\varepsilon^2 = \alpha_1 + \alpha_2. \]

From the definition of \(\varphi_\varepsilon\), we infer that
\[ \cos(\varphi_\varepsilon) = \frac{|u_{1,\varepsilon}|^2 - |u_{2,\varepsilon}|^2}{|u_{1,\varepsilon}|^2 + |u_{2,\varepsilon}|^2}, \] (3.7)
which, together with (1.5), yields
\[ \int_{\mathbb{R}^2} \eta_\varepsilon^2 v_\varepsilon^2 \cos \varphi_\varepsilon = \alpha_1 - \alpha_2. \]

Hence, \((v_\varepsilon, \varphi_\varepsilon)\) satisfies (1.8). Finally, the estimate (2.4) gives \(\eta_\varepsilon \geq c_\varepsilon > 0\) in \(K \subset \subset D\), so (3.1) yields (3.3).
\( (ii) \) Consider \((v, \varphi)\) as in the statement and define \((u_1, u_2)\) by \((3.4)\). Since \((v, \varphi)\) verifies \((1.8)\), relation \((3.4)\) gives
\[
\int_{\mathbb{R}^2} |u_1|^2 + |u_2|^2 = \int_{\mathbb{R}^2} \eta_e^2 v^2 = \alpha_1 + \alpha_2
\]
and
\[
\int_{\mathbb{R}^2} |u_1|^2 - |u_2|^2 = \int_{\mathbb{R}^2} \eta_e^2 v^2 \cos^2 \varphi = \alpha_1 - \alpha_2.
\]
Thus, \((u_1, u_2)\) verifies \((1.5)\). We have
\[
|u_1|^2 + |u_2|^2 > 0. \text{ Indeed, if it was not the case, since } v > 0 \text{ then } \varphi \text{ should take simultaneously the values } 0 \text{ and } \pi. \text{ Since } v \in L^\infty(\mathbb{R}^2), \text{ bounds } (2.5) \text{ and } (2.6) \text{ on } \eta_e \text{ give}
\]
\[
\int_{\mathbb{R}^2} V(\eta_e^2 v^2) \leq C \int_{\mathbb{R}^2} V \eta_e^2 < +\infty.
\]
We compute
\[
|\nabla u_1|^2 \leq C \left( v^2 |\nabla \eta_e|^2 + \eta_e^2 |\nabla \eta_e|^2 + v^2 \eta_e^2 |\nabla \varphi|^2 \right).
\]
The right hand side of the inequality is integrable in \(\mathbb{R}^2\) because \(v, \nabla v, \nabla \varphi \in L^\infty(\mathbb{R}^2)\) and \(\eta_e \in H^1(\mathbb{R}^2) \cap L^\infty(\mathbb{R}^2)\). Thus, \(u_{1,e} \in H^1(\mathbb{R}^2)\). We prove similarly that \(u_{2,e} \in H^1(\mathbb{R}^2)\). We have proved that \((u_{1,e}, u_{2,e}) \in \mathcal{H}.\)

We now prove the rewriting of the energy.

**Proposition 3.2** Let \((u_1, u_2) \in \mathcal{H}\) satisfying \(|u_1|^2 + |u_2|^2 > 0\). Defining \((v, \varphi)\) by \((1.7)\) we have
\[
\mathcal{E}_\varepsilon(u_1, u_2) = \mathcal{E}_\varepsilon(\eta_e) + F_\varepsilon(v) + G_\varepsilon(v, \varphi),
\]
where \(E_\varepsilon, F_\varepsilon\) and \(G_\varepsilon\) are given respectively by \((1.1)\), \((1.11)\) and \((1.12)\).

**Proof** Since \(|u_1|^2 + |u_2|^2 > 0\), the pair \((v, \varphi)\) is well defined. The definitions of \(v\) and \(\varphi\) yield
\[
|u_1| = \eta_e v \cos(\varphi/2) \quad \text{and} \quad |u_2| = \eta_e v \sin(\varphi/2), \tag{3.8}
\]
which give
\[
|u_1|^2 + |u_2|^2 = \eta_e^2 v^2
\]
\[
|u_1|^2 |u_2|^2 = \frac{1}{4} \eta_e^4 v^4 \{1 - \cos^2 \varphi \} \tag{3.9}
\]
\[
|u_1|^4 + |u_2|^4 = \frac{1}{2} \eta_e^4 v^4 \{1 + \cos^2 \varphi \}.
\]
Since \(u_1\) and \(u_2\) are real, we have \(|\nabla u_1|^2 = |\nabla |u_1||^2\) and \(|\nabla u_2|^2 = |\nabla |u_2||^2\). The relations in \((3.8)\) give then
\[
|\nabla u_1|^2 + |\nabla u_2|^2 = |\nabla (v \eta_e)|^2 + \frac{1}{4} (v \eta_e)^2 |\nabla \varphi|^2. \tag{3.10}
\]
Completing the square for \( \mathcal{E}_\varepsilon(u_1, u_2) \) we get
\[
\mathcal{E}_\varepsilon(u_1, u_2) = \frac{1}{2} \int |\nabla (v\eta_\varepsilon)|^2 + \frac{1}{\varepsilon^2} V \eta_\varepsilon^2 v^2 + \frac{1}{4\varepsilon^2} \eta_\varepsilon^2 |\nabla \varphi|^2 + \frac{1}{4\varepsilon^2} \eta_\varepsilon^4 v^4 \{1 + \cos^2 \varphi\} + \frac{1}{4} g_\varepsilon \eta_\varepsilon^4 v^4 \{1 - \cos^2 \varphi\}.
\] (3.11)

The previous formulation of the energy is the one given by the spin formulation (see the introduction and [22]). We now show how the phase transition model is obtained. Performing an integration by parts, using (2.1) and the first mass constraint in (1.8), we obtain
\[
\int |\nabla (v\eta_\varepsilon)|^2 + \frac{1}{\varepsilon^2} V \eta_\varepsilon^2 v^2 = \int v^2 \eta_\varepsilon (-\Delta \eta_\varepsilon + \frac{1}{\varepsilon^2} V \eta_\varepsilon) + \eta_\varepsilon^2 |\nabla v|^2
\]
\[
= \int v^2 \eta_\varepsilon (-\Delta \eta_\varepsilon + \frac{1}{\varepsilon^2} V \eta_\varepsilon + \frac{1}{\varepsilon^2} \eta_\varepsilon^3) - \frac{1}{\varepsilon^2} \eta_\varepsilon^4 v^2 + \eta_\varepsilon^2 |\nabla v|^2
\]
\[
= \frac{\lambda_\varepsilon}{\varepsilon^2} \int v^2 \eta_\varepsilon^2 + \int \eta_\varepsilon^2 |\nabla v|^2 - \frac{1}{\varepsilon^2} \eta_\varepsilon^4 v^2
\] (3.12)
\[
= \frac{\lambda_\varepsilon}{\varepsilon^2} + \int \eta_\varepsilon^2 |\nabla v|^2 - \frac{1}{\varepsilon^2} \eta_\varepsilon^4 v^2.
\]

Using again (2.1), together with the mass constraint for \( \eta_\varepsilon \), we have that
\[
\frac{\lambda_\varepsilon}{\varepsilon^2} = 2 \left( E_\varepsilon(\eta_\varepsilon) + \frac{1}{4\varepsilon^2} \eta_\varepsilon^4 \right).
\] (3.13)

Replacing (3.13) in (3.12), and then (3.12) in (3.11) we get
\[
\mathcal{E}_\varepsilon(u_1, u_2) = E_\varepsilon(\eta_\varepsilon) + \frac{1}{2} \int \eta_\varepsilon^2 |\nabla v|^2 + \frac{1}{2} \eta_\varepsilon^4 \{1 - 2v^2\}
\]
\[
+ \frac{1}{2} \int \frac{1}{4} v^2 \eta_\varepsilon^2 |\nabla \varphi|^2 + \frac{1}{4} \eta_\varepsilon^4 v^4 \{1 + \cos^2 \varphi\} + \frac{1}{4} g_\varepsilon \eta_\varepsilon^4 v^4 \{1 - \cos^2 \varphi\}.
\]

Completing the square for \( \{1 - v^2\} \) we get
\[
\mathcal{E}_\varepsilon(u_1, u_2) = E_\varepsilon(\eta) + \frac{1}{2} \int \eta^2 |\nabla v|^2 + \frac{1}{2} \eta^4 \{1 - v^2\}^2 - \frac{1}{2} \eta^4 v^4
\]
\[
+ \frac{1}{2} \int \frac{1}{4} v^2 \eta^2 |\nabla \varphi|^2 + \frac{1}{4} \eta^4 v^4 \{1 + \cos^2 \varphi\} + \frac{1}{4} g_\varepsilon \eta^4 v^4 \{1 - \cos^2 \varphi\}
\]
\[
= E_\varepsilon(\eta) + \frac{1}{2} \int \eta^2 |\nabla v|^2 + \frac{1}{2} \eta^4 \{1 - v^2\}^2
\]
\[
+ \frac{1}{2} \int \frac{1}{4} v^2 \eta^2 |\nabla \varphi|^2 + \frac{1}{4} \eta^4 g_\varepsilon \left(1 - \frac{1}{g_\varepsilon^2}\right) \{1 - \cos^2 \varphi\},
\]
which finishes the proof.
\( \square \)

4 Upper bound inequality

In this section, we consider the formulation of the problem in \((v, \varphi)\) and prove:

**Proposition 4.1** (Upper bound inequality for \(\varepsilon \mathcal{F}_\varepsilon\)) Let \( \varphi = \pi 1_A \in X \). There is a sequence of pairs \((v_\varepsilon, \varphi_\varepsilon) \in Lip(\mathbb{R}^2; (0, 1] \times [0, \pi])\), converging as \( \varepsilon \to 0 \) to \((1, \varphi)\) in \(L^1_{loc}(\mathcal{D}) \times \mathbb{R}^2\).
\[L^1_{loc}(D), \text{ such that}\]
\[
\limsup_{\varepsilon \to 0} \varepsilon \mathcal{F}_\varepsilon(v_\varepsilon, \varphi_\varepsilon) \leq \mathcal{F}(\varphi).
\]

The proof is based on Bouchitté’s paper [9], where he proves the \(\Gamma\)-convergence of an anisotropic phase transition Cahn–Hilliard energy. We point out that our weight \(\eta_\varepsilon\) depends on \(\varepsilon\) and vanishes asymptotically on the boundary of \(D\).

We will first prove the upper bound for open bounded subsets \(A\) of \(\mathbb{R}^2\) with smooth boundary such that \(\mathcal{H}^1(\partial A \cap \partial D) = 0\). We conclude then thanks to a density argument using:

**Lemma 4.2** Let \(A \subset D\) with \(1_A \in BV_{loc}(D)\). There exists a sequence \(\{A_k\}_{k \in \mathbb{N}}\) of open bounded subsets of \(\mathbb{R}^2\) with smooth boundaries such that:

(i) \(\lim_{k \to \infty} L^2((A_k \cap D)\Delta A) = 0\),

(ii) \(\limsup_{k \to \infty} \int_D \rho^{3/2} |D1_{A_k}| \leq \int_D \rho^{3/2} |D1_A|\),

(iii) \(\int_{A_k \cap D} \rho = \int_A \rho\) and \(\mathcal{H}^1(\partial D \cap \partial A_k) = 0\) for \(k\) large enough.

This lemma is essentially the same as Lemma 4.3 in [9], which in turn is a generalization of Lemma 1 in [24]. The proof follows very closely the proof of Lemma 4.3 in [9] so we omit it here.

We remark that we do not consider here the mass constraints in (1.8).

Before proving the upper bound, we recall some results about sets with smooth boundary, that can be found in Lemmas 3 and 4 of [24]. For small \(\tau > 0\), define the measure

\[\mu_\tau = \mathcal{H}^1 \downarrow (D \cap S_\tau)\]

and notice that \(\mu_0 = \mathcal{H}^1 \downarrow (D \cap A)\). As in Lemma 4 in [24], \(\mathcal{H}^1(\partial A \cap \partial D) = 0\) yields \(\liminf_{\tau \to 0} \mu_\tau(\Omega) \geq \mu_0(\Omega)\) for every open \(\Omega \subset \mathbb{R}^2\), and \(\lim_{\tau \to 0} \mu_\tau(D) = \mu_0(D)\). Hence, as \(\tau \to 0\), \(\mu_\tau\) converges weakly* to \(\mu_0\), which implies

\[
\limsup_{\tau \to 0} \int_D u \, d\mu_\tau \leq \int_D u \, d\mu_0
\]

for every upper semicontinuous function \(u : D \to \mathbb{R}\) with compact support (see Propositions 1.62 and 1.80 in [5]).

We define \(\eta_0 = \sqrt{\rho}\) and for \(\varepsilon \geq 0\), \(f_\varepsilon : \mathbb{R}^2 \times \mathbb{R} \times \mathbb{R}^2 \to \mathbb{R}_+\) by

\[
f_\varepsilon(x, t, p) = \frac{1}{2} \eta_\varepsilon^2(x) |p|^2 + \frac{1}{4} \eta_\varepsilon^4(x)(1 - t^2)^2.
\]

For \(|p| = 1\) and \(s \in \mathbb{R}\) we also write \(f_\varepsilon(x, t, s) = f_\varepsilon(x, t, sp)\).

**Proof of Proposition 4.1** we first assume that \(A\) is an open subset of \(\mathbb{R}^2\) with smooth, non empty compact boundary such that

\[\mathcal{H}^1(\partial A \cap \partial D) = 0,\]

and we define \(\varphi = \pi \chi_A\).

We recall that \(D = B(0, \lambda)\) and for \(\delta > 0\) we get

\(D_\delta = B(0, \lambda - \delta)\).

**Step 1: construction of the pairs of test functions** For small \(\varepsilon, \ell > 0\) define

\[w_\varepsilon(t) = \tanh(\sqrt{\rho(x)/2} |t|)\]

and \(w^{\ell}_{\varepsilon, x} = \max(m_\varepsilon, \min((1 + 2\ell)w_\varepsilon - \ell, 1))\)

\(\square\) Springer
where $0 < m_\varepsilon = o_{\varepsilon \to 0}(1)$ will be chosen later. We note $w^\ell_x = w^\ell_{0,x}$ with $m_0 = 0$. Notice that $w^\ell_{x,x}$ has uniform Lipchitz bounds with respect $x \in D$ and $\varepsilon, \ell \in (0, 1)$. Moreover, since $\rho$ is bounded from below in $D_\delta$, for fixed $\ell > 0$ there exist $R > 0$, $\varepsilon_0 > 0$ and $C_\delta > 0$ such that

$$w^\ell_{x,x} = m_\varepsilon \text{ in } (-r_\varepsilon, r_\varepsilon) \quad \text{and} \quad w^\ell_{x,x} = 1 \text{ in } \mathbb{R} \setminus (-R, R) \quad (4.3)$$

for all $x \in D_\delta$ and $\varepsilon \in (0, \varepsilon_0)$, where $1/C_\delta < r_\varepsilon/m_\varepsilon < C_\delta$.

Thanks to the compactness of $\partial A \cap D_\delta$, there is a finite family $\{\Sigma_i\}_{i=1}^N$ of open disjoint subsets of $\partial A \cap D_\delta$, and a corresponding family of points $x_i \in \Sigma_i$, such that

$$\mathcal{H}^1\left( \partial A \cap D_\delta \setminus \bigcup_{i=1}^N \Sigma_i \right) = 0 \quad (4.4)$$

and

$$\int_0^R f_0(x, w^\ell_{x,i}(t), (w^\ell_{x,i})'(t)) \, dt \leq \int_0^R f_0(x, w^\ell_x(t), (w^\ell_x)'(t)) \, dt + \delta \quad (4.5)$$

in $\Sigma_i$, for every $1 \leq i \leq N$.

We will use the functions $w^\ell_{x,x_i}$ to define a sequence of test functions, so we have to interpolate between the different $\Sigma_i$’s. Define first $\Sigma_0 = \partial A \setminus D_\delta$ and $x_0 = (\lambda - \delta, 0) \in \partial D_\delta$. For small $s > 0$ define $\Sigma^s_i = \{x \in \Sigma_i; \text{dist}(x, \partial \Sigma_i) \geq s\}$, so

$$\mathcal{H}^1(\Sigma_i \setminus \Sigma^s_i) \to 0 \text{ as } s \to 0. \quad (4.6)$$

Notice that in particular we can take $s = s_\delta = o_{\delta \to 0}(1)$.

Consider then $\{\hat{\theta}_i\}_{i=0}^N$ such that $\hat{\theta}_i \in C^\infty(\partial A, [0, 1])$,

$$\sum_{i=0}^N \hat{\theta}_i = 1 \text{ on } \partial A \quad \text{and} \quad \hat{\theta}_i = 1 \text{ in } \Sigma_i. \quad (4.7)$$

We define the signed distance to $\partial A$ by $d(x) = \text{dist}(x, A) - \text{dist}(x, \mathbb{R}^2 \setminus A)$ and $N_t = \{|d| \leq t\}$ for $t > 0$ small. The function $d$ is Lipschitz continuous and for $t$ small enough, the projection $\pi$ over $\partial A$ is well defined in $N_t$ and we have $C^2(N_t) = O(t)$. We deduce a smooth partition of the unity on $N_{\varepsilon R}$ by setting $\theta_i = \hat{\theta}_i \circ \pi$ and we define

$$v_\varepsilon = \begin{cases} 1 & \text{in } \mathbb{R}^2 \setminus N_{\varepsilon R} \\ \sum_{i=0}^N \theta_i(x) w^\ell_{x,x_i} \left( \frac{d(x)}{\varepsilon} \right) & \text{in } N_{\varepsilon R}. \end{cases} \quad (4.8)$$

Since $x_i \in D_\delta$ for $0 \leq i \leq N$, (4.3) and the uniform Lipschitz bounds of $w^\ell_{x,x_i}$ yield that $v_\varepsilon$ is a continuous function and there is $C > 0$ such that for $\varepsilon$ small enough,

$$\|v_\varepsilon\|_{C^0(\mathbb{R}^2)} \leq C/\varepsilon. \quad (4.9)$$

We also define

$$\varphi_\varepsilon(x) = \begin{cases} \pi & \text{if } x \in A \setminus N_{\varepsilon t_c} \\ \xi(d(x)/\varepsilon t_c) & \text{if } x \in N_{\varepsilon t_c} \\ 0 & \text{if } x \in \mathbb{R}^2 \setminus (A \cup N_{\varepsilon t_c}), \end{cases} \quad (4.10)$$
Bose–Einstein condensate via Γ-convergence

where \( \xi(t) = (\pi/2)(1 + t) \) and \( t_{\mathcal{E}} = \tanh^{-1}(m_{\mathcal{E}}) = o_{\mathcal{E}\to0}(1) \). We get \((v_{\mathcal{E}}, \varphi_{\mathcal{E}}) \in Lip(\mathbb{R}^2; \{0, 1\} \times [0, \pi])\) and \((v_{\mathcal{E}}, \varphi_{\mathcal{E}}) \to (1, \varphi)\) as \( \mathcal{E} \to 0 \) in \( L^1_{\text{loc}}(\mathcal{D}) \times L^1_{\text{loc}}(\mathcal{D}) \).

(Step 2: estimating the energy \( \varepsilon G_{\mathcal{E}} \)) After (4.3), for \( \varepsilon \) small enough we have \( v_{\mathcal{E}} = m_{\mathcal{E}} \) in \( N_{\mathcal{E}t_{\mathcal{E}}} \), so

\[
G_{\mathcal{E}}(v_{\mathcal{E}}, \varphi_{\mathcal{E}}) = \frac{1}{8} \int_{N_{\mathcal{E}t_{\mathcal{E}}}} \eta_{\mathcal{E}}^2 m_{\mathcal{E}}^2 |\nabla \varphi_{\mathcal{E}}|^2 + \eta_{\mathcal{E}}^4 m_{\mathcal{E}}^4 \tilde{g}_{\mathcal{E}}\{1 - \cos^2(\varphi_{\mathcal{E}})\}.
\]

The definitions of \( t_{\mathcal{E}}, \varphi_{\mathcal{E}} \) and \( \tilde{g}_{\mathcal{E}} \), together with the fact that \( \eta_{\mathcal{E}} \) is uniformly bounded, yield

\[
G_{\mathcal{E}}(v_{\mathcal{E}}, \varphi_{\mathcal{E}}) \leq C\left(m_{\mathcal{E}}^2 \varepsilon t_{\mathcal{E}} - 2 + g_{\mathcal{E}}^4 \tilde{g}_{\mathcal{E}}\varepsilon \right)\mathcal{L}^2(N_{\mathcal{E}t_{\mathcal{E}}}) \leq C(m_{\mathcal{E}} \varepsilon^{-1} + m_{\mathcal{E}} g_{\mathcal{E}} \varepsilon).
\]

Taking \( m_{\mathcal{E}} = (g_{\mathcal{E}} \varepsilon^2)^{-1/4} \), \( G_{\mathcal{E}}(v_{\mathcal{E}}, \varphi_{\mathcal{E}}) \leq Cg_{\mathcal{E}}^{-1/4} \varepsilon^{-3/2} \) and (1.6) yields

\[
(4.10)
\]

(Step 3: computing the energy \( \varepsilon F_{\mathcal{E}} \)) We have

\[
\varepsilon F_{\mathcal{E}}(v_{\mathcal{E}}) = \int_{N_{\mathcal{ER}}} \phi_{\mathcal{E}} + \int_{N_{\mathcal{ER} \setminus (D \setminus D_{\delta})}} \phi_{\mathcal{E}} + \int_{N_{\mathcal{ER} \setminus D}} \phi_{\mathcal{E}}.
\]

where

\[
\phi_{\mathcal{E}}(x) = \frac{1}{\varepsilon} f_{\mathcal{E}}(x, v_{\mathcal{E}}, \varepsilon \nabla v_{\mathcal{E}}).
\]

Estimates (4.8), (2.7) and (2.8) yield

\[
\int_{N_{\mathcal{ER} \setminus (D \setminus D_{\delta})}} \phi_{\mathcal{E}} \leq C\left(\max_{D_{\delta}}\rho + \rho^2 + C_{\mathcal{E}} \varepsilon^2 |\ln \varepsilon|\right) \varepsilon^{-1} \mathcal{L}^2(N_{\mathcal{ER}} \cap (D \setminus D_{\delta})) \leq C\left(\delta + C_{\mathcal{E}} \varepsilon^2 |\ln \varepsilon|\right) \varepsilon^{-1} \mathcal{L}^2(N_{\mathcal{ER}})
\]

so

\[
\lim_{\varepsilon \to 0} \int_{N_{\mathcal{ER} \setminus (D \setminus D_{\delta})}} \phi_{\mathcal{E}} = o_{\delta \to 0}(1). \quad (4.12)
\]

Similarly, from (2.6), we have

\[
\int_{N_{\mathcal{ER} \setminus D}} \phi_{\mathcal{E}} \leq C \sup_{\mathbb{R}^2 \setminus D} \left(\eta_{\mathcal{E}}^2 + \eta_{\mathcal{E}}^4\right) \varepsilon^{-1} \mathcal{L}^2(N_{\mathcal{ER}}) = o_{\varepsilon \to 0}(1). \quad (4.13)
\]

Now, remembering the interpolation from (4.7) we have

\[
\int_{N_{\mathcal{ER} \setminus D_{\delta}}} \phi_{\mathcal{E}} = \sum_{i=1}^{N} \int_{N_{\mathcal{ER} \setminus B_i}} \phi_{\mathcal{E}} + \int_{N_{\mathcal{ER} \setminus C_i}} \phi_{\mathcal{E}}
\]

where

\[
B_i = \{x \in D_{\delta}; \pi(x) \in \Sigma_i^+\} \quad \text{and} \quad C_i = \{x \in D_{\delta}; \pi(x) \in \Sigma_i \setminus \Sigma_i^+\}.
\]
As before, since \( \eta_\varepsilon \) is uniformly bounded (4.6) gives

\[
\int_{N_\varepsilon \cap C_i} \phi_\varepsilon \leq C \mathcal{H}^1(\Sigma_i \setminus \Sigma_i^\varepsilon) = o_{\varepsilon \to 0}(1). \tag{4.14}
\]

In \( N_\varepsilon \cap B_i \) we have \( v_\varepsilon(x) = w_{x_i, \varepsilon}^\varepsilon(d(x)/\varepsilon) \) and \( |\nabla d| = 1 \) in \( N_\varepsilon B_i \). Hence,

\[
\int_{N_\varepsilon \cap B_i} \phi_\varepsilon = \int_{N_\varepsilon \cap B_i} |\nabla (d/\varepsilon)|(x)f_\varepsilon(x, w_{x_i, \varepsilon}^\varepsilon(d(x)/\varepsilon), (w_{x_i, \varepsilon}^\varepsilon)'(d(x)/\varepsilon)).
\]

The coarea formula from Proposition 1.5 gives

\[
\int_{N_\varepsilon \cap B_i} \phi_\varepsilon = \int_{-R}^{R} dt \int_{B_i \cap \{d = \varepsilon t\}} f_\varepsilon(x, w_{x_i}^\varepsilon(t), (w_{x_i}^\varepsilon)'(t)) d\mathcal{H}^1(x).
\]

Hence,

\[
\int_{N_\varepsilon \cap B_i} \phi_\varepsilon \leq \int_{-R}^{R} dt \int_{B_i \cap \{d = \varepsilon t\}} f_\varepsilon(x, w_{x_i}^\varepsilon(t), (w_{x_i}^\varepsilon)'(t)) d\mathcal{H}^1(x) + R_{1, \varepsilon}^1 + R_{1, \varepsilon}^2. \tag{4.15}
\]

The first error here before comes from the modification of \( w_{x_i} \) near 0, so there is \( C > 0 \) such that

\[
R_{1, \varepsilon}^1 \leq C \varepsilon \sup_{t \in (0, R)} \mathcal{H}^1(\{d = \varepsilon t\}) = o_{\varepsilon \to 0}(1).
\]

The second error appears when replacing \( f_\varepsilon \) by \( f_0 \), so using estimates (2.4) and (2.8), together with \( x_i \in D_\delta \), there is \( C_\delta > 0 \) such that

\[
R_{2, \varepsilon}^2 \leq C_\delta \varepsilon^2 |\ln \varepsilon| \sup_{t \in (0, R)} \mathcal{H}^1(\{d = \varepsilon t\}) = o_{\varepsilon \to 0}(1).
\]

Using Fubini’s formula, we rewrite then (4.15) as

\[
\int_{N_\varepsilon \cap B_i} \phi_\varepsilon \leq \int_D 1_{B_i}(x) \int_{-R}^{R} f_0(x, w_{x_i}^\varepsilon(t), (w_{x_i}^\varepsilon)'(t)) dt \, d\mu(x) + o_{\varepsilon \to 0}(1).
\]

The set \( B_i \) is close and the inner integral is a continuous function of \( x \), so the function inside the outer integral is an upper semicontinuous function of \( x \). Hence, (4.1) yields

\[
\limsup_{\varepsilon \to 0} \int_{N_\varepsilon \cap B_i} \phi_\varepsilon \leq \int_{\Sigma_i^\varepsilon} \left( \int_{-R}^{R} f_0(x, w_{x_i}^\varepsilon(t), (w_{x_i}^\varepsilon)'(t)) dt \right) \, d\mu_0(x).
\]

Notice that since \( \mu_0 \) is supported in \( \partial A \), we replaced \( B_i \) by \( \Sigma_i^\varepsilon \). From (4.5) and since \( w_{x_i}^\varepsilon \) is an even function, we have

\[
\limsup_{\varepsilon \to 0} \int_{N_\varepsilon \cap B_i} \phi_\varepsilon \leq 2 \int_{\Sigma_i^\varepsilon} \left( \int_{0}^{\infty} f_0(x, w_{x_i}^\varepsilon(t), (w_{x_i}^\varepsilon)'(t)) dt + \delta \right) \, d\mu_0(x) \tag{4.16}
\]
(Step 4: upper bound) Putting together (4.10)–(4.14) and (4.16) we get
\[
\limsup_{\varepsilon \to 0} \varepsilon F_\varepsilon(v_\varepsilon, \varphi_\varepsilon) \leq 2 \sum_{i=1}^{N} \int_0^\infty \int_0^\infty f_0(x, w^\ell_x(t), (w^\ell_x)'(t)) \, dt \, d\mu_0(x) + o_{\delta \to 0}(1).
\]
Finally, taking a sequence \( \ell = \ell_\delta = o_{\delta \to 0}(1) \) as \( \delta \to 0 \), Fubini’s formula and dominated convergence theorem together with (4.4) and (4.6) yield
\[
\lim_{\delta \to 0} \left( \limsup_{\varepsilon \to 0} \varepsilon F_\varepsilon(v_\varepsilon, \varphi_\varepsilon) \right) \leq 2 \int D \left( \int_0^\infty f_0(x, w_x(t), (w_x)'(t)) \, dt \right) \, d\mu_0(x).
\]
Remembering the definitions of \( f_0, \mu_0 \) and \( w_x \), (1.15) yields
\[
\lim_{\delta \to 0} \left( \limsup_{\varepsilon \to 0} \varepsilon F_\varepsilon(v_\varepsilon, \varphi_\varepsilon) \right) \leq 2 \sigma \int D \cap \partial A \rho^{3/2}(x) \, dH^1(x),
\]
so a diagonal argument gives then the existence of a sequence \( \delta_\varepsilon \to \varepsilon \to 0 \), such that as \( \varepsilon \to 0 \), \( (v_\varepsilon, \delta_\varepsilon, \varphi_\varepsilon, \delta_\varepsilon) \) converges in \( L^1_{\text{loc}}(D) \times L^1_{\text{loc}}(D) \) to \( (1, \varphi) \), and
\[
\limsup_{\varepsilon \to 0} \varepsilon F_\varepsilon,\delta_\varepsilon(v_\varepsilon,\delta_\varepsilon, \varphi_\varepsilon, \delta_\varepsilon) \leq 2 \sigma \int D \cap \partial A \rho^{3/2}(x) \, dH^1(x).
\]
Another diagonal argument and Lemma 4.2 allows to remove the condition (4.2) which yield the proposition.

5 Lower bound inequality and compactness

In this section we prove the compactness and the lower bound for \( \varepsilon F_\varepsilon \). The lower bound is first proved on lines and then in open subsets of \( D \) by using the slicing method. We conclude with a localisation argument described in [10, Section 4.1.1].

5.1 Compactness

**Proposition 5.1** Let \( (v_\varepsilon, \varphi_\varepsilon) : \mathbb{R}^2 \to (0, +\infty) \times (0, \pi) \) such that
\[
\sup_{\varepsilon > 0} \varepsilon F_\varepsilon(v_\varepsilon, \varphi_\varepsilon) < \infty. \tag{5.1}
\]
Then, there is \( \varphi \in BV_{\text{loc}}(D; [0, \pi]) \) such that up to a subsequence,
\[
(v_\varepsilon, \varphi_\varepsilon) \to (1, \varphi) \text{ in } L^1_{\text{loc}}(D) \times L^1_{\text{loc}}(D). \tag{5.2}
\]

**Proof** Let \( A \subset \subset D \). After estimate (2.4) there is \( c = c(A) > 0 \) such that \( \eta_\varepsilon > c \) in \( A \). Hence, (5.1) gives
\[
\|1 - v_\varepsilon\|_{L^1(A)}^2 \leq \frac{4\varepsilon^2}{c^4} |A_\varepsilon| F_\varepsilon(v_\varepsilon, \varphi_\varepsilon; A) = o_{\varepsilon \to 0}(1).
\]
Thus, \( v_\varepsilon \to 1 \) in \( L^1_{\text{loc}}(D) \). Similarly, (1.6) gives
\[
\int_A v_\varepsilon^4 |1 - \cos^2(\varphi_\varepsilon)| \leq \frac{8}{8\varepsilon^4} F_\varepsilon(v_\varepsilon, \varphi_\varepsilon; A_\varepsilon) = o_{\varepsilon \to 0}(1),
\]
so up to a (not relabeled) subsequence
\[ \cos^2(\varphi_\varepsilon) \to 1 \text{ a.e. in } L^1(A). \] (5.3)

Considering the function \( \psi(s, t) = h(t)s^3(4/3 - s) \) with \( h(t) = \int_0^t |1 - \cos^2(s)|^{1/2} \, ds \), there is \( C > 0 \) such that
\[ \varepsilon \mathcal{F}_\varepsilon(v_\varepsilon, \varphi_\varepsilon; A) \geq \frac{1}{C} \int_A |\nabla \psi(v_\varepsilon, \varphi_\varepsilon)|. \]

It follows from (5.1) that the sequence \( \psi(v_\varepsilon, \varphi_\varepsilon) \) is uniformly bounded in \( BV(A) \), so
\[ \psi(v_\varepsilon, \varphi_\varepsilon) \to \psi_0 \text{ in } L^1(A) \]
with \( \psi_0 \in BV(A) \). Hence, since \( h \) is monotone and \( v_\varepsilon \to 1 \), we obtain that \( \varphi_\varepsilon \to \varphi = h^{-1}(\psi_0) \), with \( \varphi \in \{0, \pi\} \) a.e. in \( A \) thanks to (5.3). Moreover, \( v_\varepsilon \to 1 \) a.e. in \( A \) also gives that \( J_\varphi = J_{\varphi_0} \), which yields \( \varphi \in BV_{loc}(\mathcal{D}) \).

\[ \Box \]

5.2 The slicing method

Consider an open set \( A \subset \mathbb{R}^2 \) and let \( \nu \in S^1 \) be a fixed direction. We call \( \pi_\nu \) the hyperplane orthogonal to \( \nu \) and \( A_\nu \) the projection of \( A \) on \( \pi_\nu \). We define the one dimensional slices of \( A \), indexed by \( x \in A_\nu \), as
\[ A_x = \{ t \in \mathbb{R}; x + t \nu \in A \}. \]

For every function \( f \) in \( A \), we define \( f_x \) as the restriction of \( f \) to the slice \( A_x \), defined by \( f_x(t) = f(x + t \nu) \). For \( (v, \varphi): A_x \to (0, 1] \times (0, \pi) \), we define the energies
\[
F_\varepsilon(v; A_x) = \frac{1}{2} \int_{A_x} \eta_{\varepsilon,x}(v')^2 + \frac{1}{2\varepsilon^2} \eta_{\varepsilon,x}^4 \{1 - v^2\}^2,
\]
\[
G_\varepsilon(v, \varphi; A_x) = \frac{1}{8} \int_{A_x} \eta_{\varepsilon,x}^2 v^2(\varphi')^2 + \eta_{\varepsilon,x}^4 v^4 \tilde{g}_\varepsilon \{1 - \cos^2(\varphi)\} \quad \text{and}
\]
\[
\mathcal{F}_\varepsilon(v, \varphi; A_x) = F_\varepsilon(v; A_x) + G_\varepsilon(v, \varphi; A_x).
\]

Similarly, for \( \varphi \in BV_{loc}(A_x; \{0, \pi\}) \) we define
\[
\mathcal{F}(\varphi; A_x) = \frac{2\sigma}{\pi} \int_{A_x} \rho_x^{3/2} |D\varphi|.
\]

With the previous notations, we have the following result:

**Proposition 5.2** (Lower bound inequality in lines) Let \( \varphi \in BV_{loc}(\mathcal{D}_x, \{0, \pi\}) \) and \( (v_\varepsilon, \varphi_\varepsilon): \mathbb{R} \to (0, +\infty) \times (0, \pi) \) in \( Lip_{loc}(\mathcal{D}_x) \) such that
\[
(v_\varepsilon, \varphi_\varepsilon) \to (1, \varphi) \text{ in } L^1_{loc}(\mathcal{D}_x) \times L^1_{loc}(\mathcal{D}_x)
\] (5.4)

and
\[
\sup_{\varepsilon > 0} \varepsilon \mathcal{F}_\varepsilon(v_\varepsilon, \varphi_\varepsilon; \mathcal{D}_x) < \infty.
\] (5.5)

Then, for any \( A_x \) open subset of \( \mathcal{D}_x \),
\[
\liminf_{\varepsilon \to 0} \varepsilon \mathcal{F}_\varepsilon(v_\varepsilon, \varphi_\varepsilon; A_x) \geq \mathcal{F}(\varphi; A_x).
\] (5.6)
Proof Let $A_x$ be any open subset of $\mathcal{D}_x$ and $B$ any open subset of $A_x$ relatively compact in $\mathcal{D}_x$. Consider $\{t_1, \ldots, t_n\} \subset J_\varphi \cap B$ and $\delta_0 > 0$ such that for every $\delta \in (0, \delta_0)$, the intervals

$$I_{i,\delta} = B \cap (t_i - 2\delta, t_i + 2\delta)$$

are disjoint and contained in $B$. Suppose that

$$\inf_{I_{i,\delta}} \left\{ \inf_{\varepsilon > 0} v_{\varepsilon} \right\} \geq c_i > 0 \quad (5.7)$$

where $\tilde{I}_{i,\delta} = B \cap (t_i - \delta, t_i + \delta)$. Using $\tilde{B} \subset \mathcal{D}_x$ and estimate (2.4), there is $c > 0$ such that $\eta_\varepsilon > c$ in $B$. Then, from (5.5) there is $C > 0$ such that

$$\frac{4C c_i^{-3} c^{-3}}{\sqrt{\delta_0^2 \varepsilon^2}} \geq \int_{\tilde{I}_{i,\delta}} |\varphi_\varepsilon'| |1 - \cos^2(\varphi_\varepsilon)|^{1/2} = \int_{\tilde{I}_{i,\delta}} |(h \circ \varphi_\varepsilon)'| \quad (5.8)$$

where $h(t) = \int_0^t |1 - \cos^2(z)|^{1/2} dz$. Taking the lim inf in the previous inequality, (1.6), $h' > 0$ and the lower semi-continuity of the $BV$ norm with respect to the $L^1$ convergence yield

$$0 \geq h(\pi) \int_{\tilde{I}_{i,\delta}} |D1\{\varphi=\pi\}| \geq h(\pi) \mathcal{H}^0(\{t_i\}) > 0.$$ 

This contradiction implies that (5.7) cannot be satisfied, so for every $\delta > 0$ we may extract a (not relabeled) subsequence such that there are $\{t_i,\varepsilon\}_{\varepsilon > 0} \subset \tilde{I}_{i,\delta}$ with

$$t_i,\varepsilon \to \tilde{t}_i \in \tilde{I}_{i,\delta} \quad \text{and} \quad v_{\varepsilon}(t_i,\varepsilon) \to 0 \quad \text{as} \quad \varepsilon \to 0. \quad (5.9)$$

For $\varepsilon > 0$, define $I_{i,\varepsilon}^\pm = \{t \in I_{i,\delta}; \pm(t_i,\varepsilon - t) < 0\}$ and $v_{\varepsilon,\pm} : I_{i,\delta} \to (0, +\infty)$ by

$$v_{\varepsilon, \pm}(t) = 1_{I_{i,\varepsilon}^\pm} v_{\varepsilon}(t_i, \varepsilon) + 1_{I_i^\varepsilon} v_{\varepsilon}(t).$$

Using (2.4) again, together with the fact that $v_{\varepsilon, \pm}$ is constant in $I_{i,\varepsilon}^\pm$ while equal to $v_{\varepsilon}$ in $I_{i,\varepsilon}$, we obtain

$$\sqrt{2} \varepsilon \mathcal{F}_x(v_{\varepsilon}, \varphi_\varepsilon; A_x) \geq \sum_{i=1}^n \int_{I_{i,\delta}} \rho_\varepsilon^3/2 \left( |v_{\varepsilon, \pm}'| \left| 1 - (v_{\varepsilon, \pm})^2 \right| + |v_{\varepsilon, \pm}'| ^2 \right) + o_{\varepsilon \to 0}(1).$$

Using the coarea formula (1.22) we rewrite

$$\sqrt{2} \varepsilon \mathcal{F}_x(v_{\varepsilon}, \varphi_\varepsilon; A_x) \geq \sum_{i=1}^n \int_0^1 dt \left( 1 - t^2 \right) \int_{I_{i,\delta}} \rho_\varepsilon^3/2 \left( |D1_{v_{\varepsilon, \pm}}| + |D1_{v_{\varepsilon, \pm}}| \right) + o_{\varepsilon \to 0}(1),$$

where $V_{v_{\varepsilon, i, \pm}}^\pm = \{t \in I_{i,\delta}; v_{\varepsilon, i, \pm} > t\}$. Using then that $t_i,\varepsilon \to \tilde{t}_i$, $v_{\varepsilon}(t_i, \varepsilon) \to 0$ and $v_{\varepsilon} \to 1$ a.e. in $I_{i,\delta}$, we obtain $1_{V_{v_{\varepsilon, i, \pm}}^\pm} \to 1_{V_{v_{\varepsilon, i, \pm}}^\pm}$ in $L^1(I_{i,\delta})$, where $I_{i,\delta}^\pm = \{t \in I_{i,\delta}; \pm(t_i - t) \leq 0\}$. Using again the lower semi-continuity of the $BV$ norm with respect to the $L^1$ convergence we derive that

$$\liminf_{\varepsilon \to 0} \varepsilon \mathcal{F}_x(v_{\varepsilon}, \varphi_\varepsilon; A_x) \geq 2\sigma \sum_{i=1}^n \int_{I_{i,\delta}} \rho_\varepsilon^3/2 \left( |D1_{I_i^\varepsilon}| + |D1_{I_i^\varepsilon}| \right) \geq \sum_{i=1}^n 2\sigma \rho_\varepsilon^3/2(\tilde{t}_i). \quad (5.10)$$
Since \( \rho_x > 0 \) in \( \overline{B} \), \( n \) is bounded, so \( J_x \cap B = \{t_1, \ldots, t_N\} \) for some \( N \in \mathbb{N} \). Thus, \( \varphi \in BV_{loc}(D_x) \). Moreover, since \( \rho_x \) is a continuous function and since (5.10) holds for any \( \delta \in (0, \delta_0) \), we get

\[
\liminf_{\varepsilon \to 0} \varepsilon \mathcal{F}_\varepsilon(v_\varepsilon, \varphi_\varepsilon; A_x) \geq 2\sigma \sum_{i=1}^{N} \rho_x^{3/2}(t_i) = \frac{2\sigma}{\pi} \int_B \rho_x^{3/2} d|D\varphi|.
\]

Finally, the arbitrariness in the choice of \( B \) gives (5.6).

We will now prove the lower bound inequality for the localised \( \Gamma - \lim \inf \) of \( \varepsilon \mathcal{F}_\varepsilon \), defined for \( \varphi \in BV_{loc}(D; \{0, \pi\}) \) as the set function given in \( \mathcal{A}(D) \) by

\[
\mathcal{F}'(\varphi; A) = \inf \left\{ \liminf_{\varepsilon \to 0} \varepsilon \mathcal{F}_\varepsilon(v_\varepsilon, \varphi_\varepsilon; A); (v_\varepsilon, \varphi_\varepsilon) \to (1, \varphi) \text{ in } L^1_{loc}(D) \times L^1_{loc}(D) \right\}.
\]

**Proposition 5.3** Let \( \varphi \in BV_{loc}(D; \{0, \pi\}) \). Then,

\[
\mathcal{F}'(\varphi; A) \geq \mathcal{F}(\varphi, A)
\]

(5.11)

for any open \( A \subset D \).

**Proof** let \( A \) be any open subset of \( D \), \( v \in S^1 \) and \( x \in A_v \). Consider \( (v_\varepsilon, \varphi_\varepsilon) \) a sequence of test functions for \( \mathcal{F}'(\varphi; A) \). We may assume that

\[
\sup_{\varepsilon > 0} \varepsilon \mathcal{F}_\varepsilon(v_\varepsilon, \varphi_\varepsilon; A) < \infty
\]

(5.12)

since otherwise there is nothing to prove.

Since \( v_\varepsilon, \eta_\varepsilon \) are non vanishing continuous functions, for fixed \( \varepsilon > 0 \) and \( B \subset \subset D \), (5.12) yields

\[
C \geq \varepsilon \mathcal{F}_\varepsilon(v_\varepsilon, \varphi_\varepsilon; B) \geq \frac{\varepsilon}{2} \inf_{B} \eta_\varepsilon^2 \int_B |\nabla v_\varepsilon|^2 + \frac{\varepsilon}{8} \inf_{B} v_\varepsilon^2 \eta_\varepsilon \int_B |\nabla \varphi_\varepsilon|^2
\]

\[
\geq c_{\varepsilon, B} \left\{ \int_B |\nabla v_\varepsilon|^2 + \int_B |\nabla \varphi_\varepsilon|^2 \right\},
\]

so \( v_\varepsilon \) and \( \varphi_\varepsilon \) belong to \( W_{loc}^{1,2}(D) \). Hence (see [10, Theorem 4.1]),

\[
v'_{\varepsilon, x}(t) = D_v v_\varepsilon(x + t \nu) \quad \text{and} \quad \varphi'_{\varepsilon, x}(t) = D_v \varphi_\varepsilon(x + t \nu)
\]

for a.e. \( t \in A_x \) and a.e. \( x \in A_v \). Using then \( |\nabla v_\varepsilon|^2 \geq |D_v v_\varepsilon|^2 \), we get the slicing inequality

\[
\varepsilon \mathcal{F}_\varepsilon(v_\varepsilon, \varphi_\varepsilon; A) \geq \int_{A_v} \varepsilon \mathcal{F}_\varepsilon(v_\varepsilon, x, \varphi_\varepsilon, x; A_x) dx.
\]

(5.13)

After (5.12) and (5.13), \( \varepsilon \mathcal{F}_\varepsilon(v_\varepsilon, x, \varphi_\varepsilon, x; A_x) \) is uniformly bounded with respect to \( \varepsilon \) for a.e. \( x \in A_v \). For such \( x \), Proposition 5.2 gives

\[
\liminf_{\varepsilon \to 0} \varepsilon \mathcal{F}_\varepsilon(v_\varepsilon, x, \varphi_\varepsilon, x; A_x) \geq \mathcal{F}(\varphi; A_x).
\]

(5.14)
Using (5.13), (5.14), Fatou’s lemma and Fubini’s formula, we obtain

\[ \liminf_{\varepsilon \to 0} \varepsilon F_{\varepsilon}(v_{\varepsilon}, \varphi_{\varepsilon}; A) \geq \int A \varphi_{\varepsilon} dx \int A \rho_{\varepsilon}^{3/2} d|D\varphi_{\varepsilon}| \]

\[ = \frac{2\sigma}{\pi} \int A \rho_{\varepsilon}^{3/2} |\langle \nu \varphi, v_{\varepsilon} \rangle| dH^1. \]  

(5.15)

We derive that for any family \( \{v_{i}\} \) dense in \( S^1 \),

\[ F'(\varphi; A) \geq \frac{2\sigma}{\pi} \int A \rho^{3/2} |\langle \nu \varphi, v_{i} \rangle| dH^1. \]

Since all the \( \varepsilon F_{\varepsilon} \) are local, \( F'(\varphi; \cdot) \) is supper-additive on open sets with disjoint compact closures. We may then apply Proposition 1.6 with \( \mu(\cdot) = F'(\varphi; \cdot), \Omega = D, \lambda = \rho(x) H^1 L \partial^*{\varphi = \pi} \) and \( \phi_{i} = |\langle \nu \varphi, v_{i} \rangle| \). Remarking that \( \sup_{i} |\langle \nu \varphi, v_{i} \rangle| = 1 \) we obtain

\[ F'(\varphi; A) \geq \frac{2\sigma}{\pi} \int A \rho^{3/2} dH^1 = F(\varphi; A). \]

\[ \square \]

5.3 Remark about a lower bound for \( v_{\varepsilon} \) in the transition zone

We end this section with a discussion about the infimum of \( v_{\varepsilon} \) in the transition zone. Let \{\( (v_{\varepsilon}, \varphi_{\varepsilon}) \}_{\varepsilon>0} \) be a sequence of minimizers of \( F_{\varepsilon} \), and let \( \varphi \in BV_{\text{loc}}(D; \{0, \pi\}) \) be the \( L^1_{\text{loc}} \)-limit of \( \varphi_{\varepsilon} \) given in (1.18). Let \( K \subset \subset D \) be an open smooth set, with non negligible intersection with \( J_{\varphi} \), that is,

\[ H^1(K \cap J_{\varphi}) > 0. \]

For every \( \varepsilon > 0 \), we define

\[ m_{\varepsilon,K} = \inf_{x \in K} v_{\varepsilon}(x). \]

We would like to obtain an upper bound for \( m_{\varepsilon,K} \), in connection with an open question in [7], namely

\[ m_{\varepsilon,K} \leq C_K (g_{\varepsilon} \varepsilon)^{-1/4}. \]  

(5.16)

If we assume that we have the upper and lower inequalities for each \( \varepsilon > 0 \), that is

\[ \varepsilon F_{\varepsilon}(v_{\varepsilon}) \leq F(\varphi) \]  

(5.17)

and

\[ \varepsilon F_{\varepsilon}(\tilde{v}_{\varepsilon}) \geq F(\varphi), \]  

(5.18)
we can give estimates on \( G_\varepsilon \) in order to obtain the upper bound for \( m_{\varepsilon,K} \). So assume that we have (5.17) and (5.18). On the one hand, estimates (2.4) and (2.8) give then
\[
G_\varepsilon(v_\varepsilon, \varphi_\varepsilon; K) \geq \frac{1}{4} \sqrt{g_\varepsilon \varepsilon^2 m_{\varepsilon,K}^3} \left( \inf_K \rho^{3/2} - C_K \varepsilon^2 |\ln \varepsilon|^2 \right) \int_K |\nabla \varphi_\varepsilon| \sin \varphi_\varepsilon
\]
\[
\geq C_K \sqrt{g_\varepsilon \varepsilon^2 m_{\varepsilon,K}^3} \int_K |\nabla \varphi_\varepsilon| \sin \varphi_\varepsilon.
\]
We claim that the integral here below is bounded away from zero. Indeed, if this not the case, we will have
\[
\liminf_{\varepsilon \to 0} \int_K |\nabla \varphi_\varepsilon| \sin \varphi_\varepsilon = 0.
\]
Hence, since \( \varphi_\varepsilon \to \varphi \) in \( L^1(K) \), the coarea formula together with the lower semi continuity of the BV norm imply the contradiction
\[
0 = \liminf_{\varepsilon \to 0} \int_0^\pi \sin t \, dt \int_K |D1_{|\varphi_\varepsilon| < t}| \geq \int_0^\pi \sin t \, dt \int_K |D1_{|\varphi| = 0}| = 2 \mathcal{H}^1(J_\varphi \cap K).
\]
We thus derive that there is \( C'_K > 0 \) such that
\[
G_\varepsilon(v_\varepsilon, \varphi_\varepsilon; K) \geq C'_K \sqrt{g_\varepsilon \varepsilon^2 m_{\varepsilon,K}^3}.
\]
(5.19)

In the other hand, by inspection of the proof of Proposition 4.1 (see estimate (4.10)), we see that the pair of test function \((\tilde{v}_\varepsilon, \tilde{\varphi}_\varepsilon)\) satisfies
\[
G_\varepsilon(\tilde{v}_\varepsilon, \tilde{\varphi}_\varepsilon; K) \leq C(g_\varepsilon \varepsilon^2)^{-1/4}.
\]
(5.20)

Hence, considering (5.17)–(5.20), together with the fact that \((v_\varepsilon, \varphi_\varepsilon)\) minimizes \( \mathcal{F}_\varepsilon \), we obtain
\[
2\sigma \int_K \rho^{3/2} |D\varphi| + C_K \sqrt{g_\varepsilon \varepsilon^2 m_{\varepsilon,K}^3} \leq \varepsilon \mathcal{F}_\varepsilon(v_\varepsilon, \varphi_\varepsilon; K)
\]
\[
\leq \varepsilon \mathcal{F}_\varepsilon(\tilde{v}_\varepsilon, \tilde{\varphi}_\varepsilon; K)
\]
\[
\leq 2\sigma \int_K \rho^{3/2} |D\varphi| + C(g_\varepsilon \varepsilon^2)^{-1/4}.
\]

Multiplying both sides of the previous inequality by \((g_\varepsilon \varepsilon^2)^{1/4}\) we find the upper bound (5.16) for \( m_{\varepsilon,K}^3 \).

However, we are not able to prove (5.17) and (5.18) as such because of the error terms. Indeed, the proof of the upper bound of Theorem 1.1 says that there is a sequence \(\{(\tilde{v}_\varepsilon, \tilde{\varphi}_\varepsilon)\}_{\varepsilon > 0}\) such that
\[
\limsup_{\varepsilon \to 0} \varepsilon F_\varepsilon(\tilde{v}_\varepsilon) \leq \mathcal{F}(\varphi).
\]
(5.21)

In the proof of (5.21), we first approximate the locally Caccioppoli set \( A = \{\varphi = \pi\} \) by characteristic functions of open sets \( A_k \) with compact smooth boundary. This gives a small error in terms of \( k \in \mathbb{N} \) in the upper bound inequality (5.21). Then for each \( k \in \mathbb{N} \), we construct a test function for which (5.21) holds, up to a small error term depending on a parameter \( \delta > 0 \). In these two steps, we use diagonal extraction arguments in order to get rid
of the error terms, so it is not possible to compute them explicitly. Similarly, in the proof of the lower bound of Theorem 1.1, we use the lower semi-continuity of the BV norm with respect to the $L^1$ convergence, so we cannot estimate the error term in the lower bound inequality

$$ \liminf_{\varepsilon \to 0} \varepsilon F_\varepsilon(v_\varepsilon) \geq \mathcal{F}(\varphi). \quad (5.22) $$

6 Proof of the $\Gamma$-convergence for $\varepsilon (E_\varepsilon(\cdot) - E_\varepsilon(\eta_\varepsilon))$

6.1 Proof of the compactness and the lower bound inequality in Theorem 1.1

Let $\{ (u_{1,\varepsilon}, u_{2,\varepsilon}) \}_{\varepsilon > 0}$ be a sequence of minimizers of $E_\varepsilon$ in $\mathcal{H}$ satisfying (1.17). From Proposition 3.1(i), the pairs $(v_\varepsilon, \varphi_\varepsilon)$ are well defined by (1.7), belong to $Lip_{loc}(\mathbb{R}^2; (0, +\infty) \times [0, \pi])$ and satisfy (1.8). Proposition 3.2 yields $\varepsilon F_\varepsilon(v_\varepsilon, \varphi_\varepsilon) < \infty$. The hypotheses of Proposition 5.1 are then fulfilled by $(v_\varepsilon, \varphi_\varepsilon)$ so

$$(v_\varepsilon, \varphi_\varepsilon) \to (1, \varphi) \quad \text{in} \quad L^1_{loc}(D) \times L^1_{loc}(D)$$

for some $\varphi \in BV_{loc}(D; [0, \pi])$. Identity (3.4) yields (1.18). We get that $\varphi \in X$ from (1.8) and the $L^1$ convergence. From Proposition 5.3 with $A = D$ we derive that

$$ \liminf_{\varepsilon \to 0} \varepsilon F_\varepsilon(v_\varepsilon, \varphi_\varepsilon) \geq F'(\varphi; D) \geq \mathcal{F}(\varphi). $$

Equality (1.9) yields then

$$ \liminf_{\varepsilon \to 0} \varepsilon (E_\varepsilon(u_{1,\varepsilon}, u_{2,\varepsilon}) - E_\varepsilon(\eta_\varepsilon)) \geq \mathcal{F}(\varphi). $$

In order to prove the upper bound we have to work a little more. We first modify the pairs of test functions from Proposition 4.1 to make them satisfy the mass constraints (1.8). We prove then that this modification do not change the limit of the energy. We finish by verifying that the pairs of modified test functions are the image by (1.7) of a pair in $\mathcal{H}$, and we conclude using Proposition 4.1.

6.2 Proof of the upper bound inequality in Theorem 1.1

(Step 1: Modification of the pairs of test functions) With the notations from the proof of Proposition 4.1, we write $N_\varepsilon = N_{\varepsilon R}$ and we define $(\tilde{v}_\varepsilon, \varphi_\varepsilon)$ the sequence of pairs of test functions such that

$$ \limsup_{\varepsilon \to 0} \varepsilon F_\varepsilon(\tilde{v}_\varepsilon, \varphi_\varepsilon) \leq \mathcal{F}(\varphi). \quad (6.1) $$

Consider $\kappa \in C^\infty(\mathbb{R}_+; [0, 1])$ with $\text{supp} \kappa \subset (0, 1)$ and $\kappa = 1$ in $(0, 1/2)$. Since $A$ is a non empty open set, there is $B_0 = B_{r_0}(x_0) \subset \subset A \cap D$. For $\ell \in [-1, 1]$ and $\tau \in (1/2, 1)$, define $\kappa_\varepsilon = \kappa_{\varepsilon, \ell, \tau}$ by

$$ \kappa_\varepsilon(x) = \varepsilon^\tau \ell \kappa(|x - x_0|/r_0). $$
We define then $\tilde{v}_\varepsilon = \tilde{v}_x + \kappa x$ and $v_\varepsilon = c_\varepsilon \tilde{v}_\varepsilon$, with $c_\varepsilon = \|\eta_\varepsilon \tilde{v}_\varepsilon\|^{-2}$. For $\varepsilon$ small enough $N_\varepsilon$ and $B_0$ are disjoints. We estimate

$$
c_\varepsilon^{-1} = 1 + \int_{N_\varepsilon \cup B_0} \eta_\varepsilon^2 (\tilde{v}_\varepsilon - 1)$$

$$= 1 + 2 \int_{B_0} \eta_\varepsilon^2 \kappa_\varepsilon + \int_{N_\varepsilon} \eta_\varepsilon^2 (\tilde{v}_\varepsilon - 1) + \int_{B_0} \eta_\varepsilon^2 \kappa_\varepsilon^2$$

$$= 1 + 2 \int_{B_0} \eta_\varepsilon^2 \kappa_\varepsilon + \mathcal{O}(\varepsilon) + \mathcal{O}(\varepsilon^{2\tau}).$$

Hence, using that $\tau \in (1/2, 1)$ we get $c_\varepsilon^2 = 1 - r_\varepsilon$ with

$$r_\varepsilon = 4 \int_{B_0} \eta_\varepsilon^2 \kappa_\varepsilon + \mathcal{O}(\varepsilon) = \mathcal{O}(\varepsilon^\tau). \quad (6.2)$$

Notice that for $\varepsilon$ small enough, $r_\varepsilon$ may be positive or negative depending on the sign of $\ell$.

The definition of $w_\varepsilon^{\ell}$ insures that $v_\varepsilon > 0$. The first mass constraint in (1.8) is immediately satisfied by the definition of $v_\varepsilon$. Remember the definition of $\varphi_\varepsilon$ in (4.9). For the second mass constraint we write

$$c_\varepsilon^{-2} \int_{\mathbb{R}^2} \eta_\varepsilon^2 v_\varepsilon^2 \cos \varphi_\varepsilon = \int_{\mathbb{R}^2} \eta_\varepsilon^2 (1_{\mathbb{R}^2 \setminus (A \cup N_\varepsilon)} - 1_{A \setminus (N_\varepsilon \cup B_0)} + 1_{N_\varepsilon \cup B_0} \tilde{v}_\varepsilon^2 \cos \varphi_\varepsilon).$$

Adding and removing $1_{N_\varepsilon \setminus A} \eta_\varepsilon^2$, $1_{N_\varepsilon \cup A} \eta_\varepsilon^2$ and $1_{B_0} \eta_\varepsilon^2$ in the previous integral, we get

$$c_\varepsilon^{-2} \int_{\mathbb{R}^2} \eta_\varepsilon^2 v_\varepsilon^2 \cos \varphi_\varepsilon = \int_{\mathbb{R}^2} \eta_\varepsilon^2 (1_{\mathbb{R}^2} - 21_A) + \int_{B_0} \eta_\varepsilon^2 (\tilde{v}_\varepsilon + \kappa_\varepsilon)^2 - 1 \quad (6.3)$$

$$+ \int_{N_\varepsilon} \eta_\varepsilon^2 (\tilde{v}_\varepsilon \cos \varphi_\varepsilon - 1_A + 1_{\mathbb{R}^2 \setminus A}). \quad (6.4)$$

For the third term in (6.3), we have that $\eta_\varepsilon$, $\tilde{v}_\varepsilon$ and $\cos \varphi_\varepsilon$ are bounded while $L^2(N_\varepsilon) = \mathcal{O}(\varepsilon)$. Hence,

$$\int_{N_\varepsilon} \eta_\varepsilon^2 (\tilde{v}_\varepsilon^2 \cos \varphi_\varepsilon - 1_A + 1_{\mathbb{R}^2 \setminus A}) = \mathcal{O}(\varepsilon). \quad (6.5)$$

For the first term in (6.3), using that $\int_{\mathbb{R}^2} \eta_\varepsilon^2 = 1 = \alpha_1 + \alpha_2$ and that $\int_{D \setminus A} \rho = \alpha_2$, we obtain

$$\int_{\mathbb{R}^2} \eta_\varepsilon^2 (1_{\mathbb{R}^2} - 21_A) = \alpha_1 - \alpha_2 + \int_{A \setminus D} (\eta_\varepsilon^2 - \rho) + \int_{A \setminus D} \eta_\varepsilon^2.$$

Using (2.5) we get, for $\alpha \in (1/2, 3/5)$ and $\gamma \in (1/2, 3/4),

$$\int_{A \setminus D} (\eta_\varepsilon^2 - \rho) = \int_{A \setminus B(0, \lambda - \varepsilon^\alpha)} (\eta_\varepsilon^2 - \rho) + \int_{(A \setminus D) \setminus B(0, \lambda - \varepsilon^\alpha)} (\eta_\varepsilon^2 - \rho) = \mathcal{O}(\varepsilon^\gamma) + \mathcal{O}(\varepsilon^\alpha). \quad (6.6)$$
Moreover, from (2.7), we have \( \eta_\varepsilon^2(x) \leq \eta_\varepsilon^2(x_\alpha) \) in \( A \setminus D \), with \( x_\alpha \in \partial B(0, \lambda - \varepsilon^\alpha) \). From (2.5) and (2.8) we get

\[
\eta_\varepsilon^2(x) \leq \eta_\varepsilon^2(x_\alpha) = \eta_\varepsilon^2(x_\alpha) - \rho(x_\alpha) + \rho(x_\alpha) = \mathcal{O}(\varepsilon^\alpha),
\]

so using that \( A \) is a bounded set we obtain

\[
\int_{A \setminus D} \eta_\varepsilon^2 = \mathcal{O}(\varepsilon^\alpha). \tag{6.7}
\]

For the second term in (6.3), the definitions of \( \kappa_\varepsilon \) and \( r_\varepsilon \) yield

\[
\int_{B_0} \eta_\varepsilon^2 \kappa_\varepsilon (2 + \kappa_\varepsilon) = \frac{1}{2} r_\varepsilon + \mathcal{O}(\varepsilon) + \mathcal{O}(\varepsilon^{2\tau}). \tag{6.8}
\]

Putting (6.5)–(6.8) in (6.3) and considering (6.2) we get

\[
c_{\varepsilon}^{-2} \int_{\mathbb{R}^2} \eta_\varepsilon^2 v_\varepsilon^2 \cos \varphi_\varepsilon = \alpha_1 - \alpha_2 + \frac{1}{2} r_\varepsilon + \mathcal{O}(\varepsilon^\beta),
\]

where \( \beta = \min\{1, \alpha, \gamma, 2\tau\} = \min\{\alpha, \gamma\} \in (1/2, 3/5) \). Hence, (6.2) gives

\[
\int_{\mathbb{R}^2} \eta_\varepsilon^2 v_\varepsilon^2 \cos \varphi_\varepsilon - (\alpha_1 - \alpha_2) = \left( \frac{1}{2} - (\alpha_1 - \alpha_2) \right) r_\varepsilon + \mathcal{O}(\varepsilon^\beta).
\]

Suppose now, without loss of generality, that \( \alpha_1 - \alpha_2 \leq 1/2 \). The definition of \( r_\varepsilon \) and \( \kappa_\varepsilon \), together with (2.4), (2.8) and \( B_0 \subset \subset A \cap D \), give then

\[
|r_\varepsilon| \geq 4 \inf_{B_0} \eta_\varepsilon^2 \int_{B_0} \kappa_\varepsilon^2 + \mathcal{O}(\varepsilon)
\]

\[
\geq 4 \inf_{B_0} \eta_\varepsilon^2 \left| \ell \right| \varepsilon^\tau \int_{B_{\varepsilon^2/2} \setminus B_0} \kappa_\varepsilon^2 + \mathcal{O}(\varepsilon)
\]

\[
\geq c |\ell| \varepsilon^\tau + \mathcal{O}(\varepsilon),
\]

for some \( c > 0 \) not depending on \( \varepsilon \). Hence, if we take \( \ell = 1 \) in the definition of \( \kappa_\varepsilon \), for \( \varepsilon \) small enough we have

\[
\int_{\mathbb{R}^2} \eta_\varepsilon^2 v_\varepsilon^2 \cos \varphi_\varepsilon - (\alpha_1 - \alpha_2) \geq c' \varepsilon^\tau (1 + \varepsilon^{1-\tau} - \varepsilon^{\beta-\tau}).
\]

Analogously, taking now \( \ell = -1 \), we get

\[
\int_{\mathbb{R}^2} \eta_\varepsilon^2 v_\varepsilon^2 \cos \varphi_\varepsilon - (\alpha_1 - \alpha_2) \leq c'' \varepsilon^\tau (-1 + \varepsilon^{1-\tau} + \varepsilon^{\beta-\tau}).
\]

Since \( \beta \in (1/2, 3/5) \), we can choose \( \tau \in (1/2, \beta) \) and obtain

\[
\int_{\mathbb{R}^2} \eta_\varepsilon^2 v_\varepsilon^2 \cos \varphi_\varepsilon > \alpha_1 - \alpha_2 \quad \text{if} \quad \ell = 1
\]
and
\[ \int_{\mathbb{R}^2} \eta_\epsilon^2 v_\epsilon^2 \cos \varphi_\epsilon < \alpha_1 - \alpha_2 \quad \text{if } \ell = -1. \]

Hence, there exists \( \ell_\epsilon \in (-1, 1) \) such that for \( \epsilon \) small enough, the associated pair \((v_\epsilon, \varphi_\epsilon)\) satisfy the second mass constraint in (1.8).

(Step 2: Computing the energy) We now compute the energy of \((v_\epsilon, \varphi_\epsilon)\). We recall that \( N_{\ell_\epsilon} \) is the transition zone of \( \varphi_\epsilon \) defined in (4.9). For the energy \( G_\epsilon \), we have that \( \varphi_\epsilon \) is constant out of \( N_{\ell_\epsilon} \), while \( v_\epsilon = c_\epsilon \tilde{v}_\epsilon \) in \( N_{\ell_\epsilon} \) with \( c_\epsilon = 1 + \mathcal{O}(\epsilon^2) \). Hence,
\[ \epsilon G_\epsilon(v_\epsilon, \varphi_\epsilon) = (1 + \mathcal{O}(\epsilon^2))\epsilon G_\epsilon(\tilde{v}_\epsilon, \varphi_\epsilon). \quad (6.9) \]

For the energy \( F_\epsilon \), we have that \( v_\epsilon = c_\epsilon(1 + \kappa_\epsilon) \) in \( B_0 \). The definition of \( \kappa_\epsilon \) gives then, \( |\nabla v_\epsilon|^2 = \mathcal{O}(\epsilon^{2\tau}) \) and \( |1 - v_\epsilon|^2 = \mathcal{O}(\epsilon^{2\tau}) \). Hence,
\[ \epsilon F_\epsilon(v_\epsilon; B_0) = \mathcal{O}(\epsilon^{2\tau-1}) = o_{\epsilon \to 0}(1). \quad (6.10) \]

In \( \mathbb{R}^2 \setminus (N_\epsilon \cap B_0) \), we have that \( v_\epsilon = c_\epsilon \), so \( |\nabla v_\epsilon| = 0 \) and \( |1 - v_\epsilon|^2 = \mathcal{O}(\epsilon^{2\tau}) \). As before we get
\[ \epsilon F_\epsilon(v_\epsilon; \mathbb{R}^2 \setminus (N_\epsilon \cap B_0)) = \mathcal{O}(\epsilon^{2\tau-1}) = o_{\epsilon \to 0}(1). \quad (6.11) \]

In \( N_\epsilon \), we have that \( v_\epsilon = c_\epsilon \tilde{v}_\epsilon \). Hence, \( |\nabla v_\epsilon|^2 = (1 + \mathcal{O}(\epsilon^{\tau}))|\nabla \tilde{v}_\epsilon|^2 \) and \( |1 - v_\epsilon|^2 = (1 + \mathcal{O}(\epsilon^{\tau}))(1 - \tilde{v}_\epsilon^2) + \mathcal{O}(\epsilon^{\tau}) \), which gives
\[ \epsilon F_\epsilon(v_\epsilon; N_\epsilon) = (1 + \mathcal{O}(\epsilon^{\tau}))\epsilon F_\epsilon(\tilde{v}_\epsilon; N_\epsilon) + \mathcal{O}(\epsilon^{\tau})\epsilon^{-1} L^2(N_\epsilon) \]
\[ = (1 + \mathcal{O}(\epsilon^{\tau}))\epsilon F_\epsilon(\tilde{v}_\epsilon; N_\epsilon) + o_{\epsilon \to 0}(1). \quad (6.12) \]

Since \( \tilde{v}_\epsilon \) is constant out of \( N_\epsilon \), we have \( F_\epsilon(\tilde{v}_\epsilon; N_\epsilon) = F_\epsilon(\tilde{v}_\epsilon; N_\epsilon) \). Putting together (6.1) and (6.9)–(6.12), we obtain
\[ \limsup_{\epsilon \to 0} \epsilon F_\epsilon(v_\epsilon, \varphi_\epsilon) = \limsup_{\epsilon \to 0} \epsilon F_\epsilon(\tilde{v}_\epsilon, \varphi_\epsilon) \leq \mathcal{F}(\varphi). \quad (6.13) \]

(Step 3: identification of \((v_\epsilon, \varphi_\epsilon)\)) The pairs of test functions satisfies the hypothesis from Proposition 3.1(ii), so defining \((u_{1,\epsilon}, u_{2,\epsilon})\) by (3.4) we have \((u_{1,\epsilon}, u_{2,\epsilon}) \in \mathcal{H} \) and \( u_{1,\epsilon}^2 + u_{2,\epsilon}^2 > 0 \). Hence, from Proposition (3.2) relation (1.9) holds, and (6.13) yield
\[ \limsup_{\epsilon \to 0} \epsilon \left( \mathcal{E}_\epsilon(u_{1,\epsilon}, u_{2,\epsilon}) - \mathcal{E}_\epsilon(\eta_\epsilon) \right) = \limsup_{\epsilon \to 0} \epsilon F_\epsilon(v_\epsilon, \varphi_\epsilon) \leq \mathcal{F}(\varphi). \]

Corollary 1.2 is a standard consequence of the properties of Theorem 1.1.

6.3 Proof of Corollary 1.3

We start proving that when \( \alpha_1 \) is not to close to 0 or 1, the minimizers of \( \mathcal{F} \) in \( X \) are not radially symmetric. We show that for any radially symmetric \( \varphi \in X \), \( \mathcal{F}(\varphi) > \mathcal{F}(\varphi_{ds}) \), where the support of \( \varphi_{ds} \in X \) is a disk sector. We first prove this for functions such that \( \{\varphi = 0\} \) is a disk or an annulus. Then, we generalize by induction the result to radial functions such that \( \{\varphi = 0\} \) is composed of a finite number of connected components. We conclude then by approximating any radially symmetric \( \varphi \in X \) by this kind of functions.
We recall that $\rho$ is given in (1.3) and that $X$ is the space of functions $\varphi \in BV_{loc}(D; [0, \pi])$ such that

$$\int_{\{\varphi = 0\}} \rho = \alpha_1. \quad (6.14)$$

If $\varphi_{ds} \in X$ is such that $\{\varphi_{ds} = 0\}$ is a disk sector, we easily compute

$$\mathcal{F}(\varphi_{ds}) = \frac{3}{16}. \quad (6.15)$$

For $0 \leq R^- \leq R^+ \leq \lambda$ we call $A(R^-, R^+)$ the annulus of center the origin, inner radius $R^-$ and outer radius $R^+$.

If $\varphi_{\alpha} \in X$ is such that $\{\varphi = 0\} = A(0, R_{\alpha})$ and $\int_{A(0, R_{\alpha})} \rho = \alpha$, then $R_{\alpha} = \lambda (1 - \sqrt{\alpha})^{1/2}$ and

$$\mathcal{F}(\varphi_{\alpha}) = f(\alpha). \quad (6.15)$$

where $f : [0, 1] \to \mathbb{R}_+$ is the concave function $f(\alpha) = (1 - \alpha)^{3/4} (1 - \sqrt{1 - \alpha})^{1/2}$. We see that there exists

$$\delta_0 \approx 0.1486$$

such that if $\alpha \in [\delta_0, 1 - \delta_0]$, then $f(\alpha) > 3/16$.

**Proposition 6.1** If $\alpha_1 \in [\delta_0, 1 - \delta_0]$, then the minimizers of $\mathcal{F}$ in $X$ are not radially symmetric.

**Proof (Step 1)** Let $R \in (0, \lambda)$ and consider $\varphi_1^d \in X$ such that $\{\varphi_1^d = 0\} = A(0, R)$. From (6.14), we have that $\mathcal{F}(\varphi_1^d) / 8\sigma = f(\alpha_1)$ so (6.15) yields

$$\mathcal{F}(\varphi_1^d) > \mathcal{F}(\varphi_{ds}). \quad (6.16)$$

Since $\alpha_2 = 1 - \alpha_1 \in [\delta_0, 1 - \delta_0]$, the similar inequality holds if $\{\varphi_1^d = 0\} = A(R, \lambda)$.

Consider now $\varphi_i^d \in X$ such that $\{\varphi_i^d = 0\} = A(R_1, R_2)$, with $0 < R_1 < R_2 < \lambda$. Writing

$$\beta_1 = \int_{A(0, R_1)} \rho, \quad \beta_2 = \int_{A(R_1, R_2)} \rho \quad \text{and} \quad \beta_3 = \int_{A(R_2, \lambda)} \rho,$$

we compute

$$\mathcal{F}(\varphi_i^d) / 8\sigma = f(\beta_1) + f(\beta_1 + \beta_2).$$

From (6.14), we have that $\beta_2 = \alpha_1$ and $\beta_1 + \beta_3 = \alpha_2$ so

$$\mathcal{F}(\varphi_i^d) / 8\sigma = f(\beta_1) + f(\beta_1 + \alpha_1). \quad (6.17)$$

The right-hand size of the previous equality is a concave function of $\beta_1$ and the value of $\beta_1$ may vary between 0 and $\alpha_2$. If $\beta_1 = 0$ then $\mathcal{F}(\varphi_i^d) / 8\sigma = f(\alpha_1)$. If $\beta_1 = \alpha_2$, since $\alpha_1 + \alpha_2 = 1$ we find $\mathcal{F}(\varphi_i^d) / 8\sigma = f(\alpha_2)$. We derive

$$\mathcal{F}(\varphi_i^d) > \mathcal{F}(\varphi_{ds}).$$

**(Step 2)** Let $n \in \mathbb{N}^n$ and consider $\varphi_n \in X$ such that

$$\{\varphi_n = 0\} = \bigcup_{j=1}^n A_{2j}.$$
with $A_{2j} = A(R_{2j}^- , R_{2j}^+ )$ and

$$0 \leq R_{2j-2}^- < R_{2j-2}^+ < R_{2j}^- < R_{2j}^+ \leq \lambda$$

for $2 \leq j \leq n$. We write $\beta_{2j} = \int_{A_{2j}} \rho$, $\beta_1 = \int_{A(0,R_{2j}^- )} \rho$, $\beta_{2n+1} = \int_{A(R_{2n}^+ ,\lambda )} \rho$ and

$$\beta_{2j+1} = \int_{A(R_{2j}^+ ,R_{2j+2}^- )} \rho$$

for $1 \leq j \leq n - 1$. Notice that we allow $A(0, R_{2n}^- )$ or $A(R_{2n}^+ ,\lambda )$ to be empty, but this only implies that $\beta_1 = 0$ or $\beta_{2n+1} = 0$. With this notation, we have

$$\sum_{i=1}^{n} \beta_{2i} = \alpha_1, \quad \sum_{i=1}^{n} \beta_{2i+1} = \alpha_2 \quad (6.18)$$

and

$$\frac{\mathcal{F}(\varphi_n)}{8\sigma} = \sum_{j=1}^{2n} f \left( \sum_{i=1}^{j} \beta_i \right) =: g_n(\beta_1, \ldots , \beta_{2n}).$$

By induction, we are going to prove the following property:

$$(\mathcal{P}_n) \quad \forall \beta_1 , \ldots , \beta_{2n+1} \in [0,1] \text{ such that } \sum_{i=1}^{n} \beta_{2i} = \alpha_1 \text{ and } \sum_{i=1}^{n} \beta_{2i+1} = \alpha_2 ,$$

$$g_n(\beta_1, \ldots , \beta_{2n}) > \frac{\mathcal{F}(\varphi_{ds})}{8\sigma}.$$ 

If $n = 1$ we are in one of the three cases analyzed in Step 1, so (6.16) and (6.17) yield $(\mathcal{P}_1)$. Let us assume that $(\mathcal{P}_n)$ holds and consider $\beta_1 , \ldots , \beta_{2n+3} \in [0,1]$ such that

$$\sum_{i=1}^{n+1} \beta_{2i} = \alpha_1 \quad \text{and} \quad \sum_{i=1}^{n+1} \beta_{2i+1} = \alpha_2. \quad (6.19)$$

We have

$$g_{n+1}(\beta_1, \ldots , \beta_{2n+2}) = \sum_{j=1}^{2n} f \left( \sum_{i=1}^{j} \beta_i \right) + f \left( \sum_{i=1}^{2n+1} \beta_i \right) + f \left( \sum_{i=1}^{2n+2} \beta_i \right).$$

The right hand side of the previous equality is a concave function of $\beta_{2n+2}$. The value of $\beta_{2n+2}$ may vary between 0 and $\alpha_1$. Suppose first that $\beta_{2n+2} = 0$. Then, defining

$$\tilde{\beta}_j = \beta_j \quad \text{if} \quad j = 1, \ldots , 2n \quad \text{and} \quad \tilde{\beta}_{2n+1} = \beta_{2n+1} + \beta_{2n+3},$$

the $\tilde{\beta}_i$’s satisfy (6.18) and we have

$$g_{n+1}(\beta_1, \ldots , \beta_{2n+2}) \geq \sum_{j=1}^{2n} f \left( \sum_{i=1}^{j} \beta_i \right) = g_n(\tilde{\beta}_1, \ldots , \tilde{\beta}_{2n}).$$

Hence, $(\mathcal{P}_n)$ yields $g_{n+1}(\beta_1, \ldots , \beta_{2n+2}) > \mathcal{F}(\varphi_{ds})/8\sigma$. 

\(\square\) Springer
Suppose now that $\beta_{2n+2} = \alpha_1$. From (6.19) this implies $\beta_{2j} = 0$ for every $j = 1, \ldots, n$. Then, defining

$$\tilde{\beta}_1 = \sum_{j=1}^{2n+1} \beta_j, \quad \tilde{\beta}_2 = \beta_{2n+2} \quad \text{and} \quad \tilde{\beta}_3 = \beta_{2n+3},$$

the $\tilde{\beta}_i$'s satisfy (6.18) and we have

$$g_{n+1}(\beta_1, \ldots, \beta_{2n+2}) \geq f \left( \sum_{i=1}^{2n+1} \beta_i \right) + f \left( \sum_{i=1}^{2n+2} \beta_i \right)$$
$$= f(\tilde{\beta}_1) + f(\tilde{\beta}_1 + \tilde{\beta}_2)$$
$$= g_1(\tilde{\beta}_1, \tilde{\beta}_2).$$

Hence, (P1) yields $g_{n+1}(\beta_1, \ldots, \beta_{2n+2}) > F(\varphi_{ds})/8\sigma$. We derive that the result holds for all the possible values of $\beta_{2n+2}$.

We have proved that if $\varphi_n \in X$ is radial and its support has a finite number of connected components, then

$$F(\varphi_n) > F(\varphi_{ds}). \quad (6.20)$$

(Step 3) Suppose now that $\varphi \in X$ is a radially symmetric function such that $\{\varphi = 0\}$ has an infinite number of connected components. Since $\varphi$ has locally finite perimeter in $D$, $\{\varphi = 0\}$ is the union of a countable family of disjoint annuli. We write

$$\{\varphi = 0\} = \bigcup_{j \in \mathbb{Z}} A_{2j},$$

with $A_{2j} = A(R^-_{2j}, R^+_{2j})$ such that

$$0 < R^-_{2j} < R^+_{2j} < R^-_{2j+2} < R^+_{2j+2} < \lambda. \quad (6.21)$$

For every $n \in \mathbb{N}$, we define a function $\varphi_n : D \to [0, \pi]$ by

$$\{\varphi_n = 0\} = \bigcup_{j=-n}^{n} A_{2j} \bigcup \tilde{A}_{2n+2} \bigcup \tilde{A}_{-2n-2},$$

such that

$$\tilde{A}_{2n+2} = A(L^+_n, \lambda) \quad \text{and} \quad \tilde{A}_{-2n-2} = A(0, L^-_n)$$

with $L^-_n, L^+_n$ to be chosen next. If $(L^-_n, L^+_n) = (0, \lambda)$, then (6.21) gives

$$\int_{\{\varphi_n = 0\}} \rho = \sum_{j=-n}^{n} \int_{A_{2j}} \rho < \int_{\{\varphi = 0\}} \rho.$$

Similarly if $(L^-_n, L^+_n) = (R^-_{2n}, R^+_{2n})$, then

$$\int_{\{\varphi_n = 0\}} \rho = \sum_{j \in \mathbb{Z}} \int_{A_{2j}} \rho + \sum_{j \geq n} \int_{A(R^+_j, R^-_{j+2})} \rho + \sum_{j \leq -n} \int_{A(R^+_j, R^-_{j})} \rho > \int_{\{\varphi = 0\}} \rho.$$
Hence, by continuity there is a pair \((L_n^-, L_n^+)\in (0, R_{-2n}^-)\times (R_{2n}^+, \lambda)\) such that \(\int_{\{\varphi_n=0\}} \rho = \int_{\{\varphi=0\}} \rho = \alpha_1\). Clearly \(\varphi_n\in BV_{loc}(D)\), so \(\varphi_n\in X\). Moreover, (6.21) yields
\[
\lim_{n\to \infty} L_n^- = 0 \quad \text{and} \quad \lim_{n\to \infty} L_n^+ = \lambda.
\]
(6.22)

We have
\[
F(\varphi) = \sum_{j\in 2n} \int_{B(0,R_{2n}^j)} \rho^{3/2} d\mathcal{H}^1,
\]
and since \(\rho\) is radially symmetric
\[
F(\varphi_n) = \sum_{j=-n}^n \int_{B(0,R_{2n}^j)} \rho^{3/2} d\mathcal{H}^1 + 2\pi \left( \rho^{3/2}(L_n^+)L_n^- + \rho^{3/2}(L_n^-)L_n^- \right).
\]
From (6.22), the last term in the previous equality goes to zero as \(n\to +\infty\), so
\[
\lim_{n\to \infty} F(\varphi_n) = F(\varphi).
\]
Hence, since \(\{\varphi_n = 0\}\) has a finite number of connected components, (6.20) yields \(F(\varphi) > F(\varphi_{ds})\), which ends the proof.

\(\square\)

**Proof of Corollary 1.3** Suppose that \(\alpha_1 \in [\delta_0, 1 - \delta_0]\) and that \((\{u_{1,e}, u_{2,e}\})_{e>0}\) is a sequence of radially symmetric pairs such that \((u_{1,e}, u_{2,e})\) minimizes \(E_\epsilon\) under the mass constraints (1.5). Then, \(\varphi_\epsilon\) defined by (3.7) is also radially symmetric. Consider \(\varphi_{\epsilon,0}\), the restriction of \(\varphi_\epsilon\) to a slice of \(D\) passing through 0. From Proposition 5.2, \(\varphi_{\epsilon,0}\) belongs to \(BV_{loc}(\{0, \lambda\} \times [0, \pi])\) and converges in \(L^1_{loc}(\{0, \lambda\})\) to \(\varphi_0\). Hence, \(\varphi_\epsilon\) converges in \(L^1_{loc}(D)\) to the radial function \(\varphi\) given by \(\varphi(x) = \varphi_0(|x|)\). From Corollary 1.2, we know that \(\varphi\) minimizes \(F\) over \(X\), which yields a contradiction to Proposition 6.1.

\(\square\)

**Acknowledgments** The second author would like to acknowledge discussions with Guy Bouchitté, Michael Goldman, Duvan Henao and Pierre Seppecher. We would like to thank Clément Gallo.

**References**

1. Aftalion, A.: Vortices in Bose-Einstein Condensates. Progress in Nonlinear Differential Equations and Their Applications, vol. 67. Birkhäuser, Boston (2006)
2. Aftalion, A., Jerrard, R.L., Royo-Letelier, J.: Non-existence of vortices in the small density region of a condensate. J. Funct. Anal. 260, 2387–2406 (2011)
3. Alberti, G.: Variational Models for Phase Transitions, an Approach Via \(\Gamma\)-Convergence. Calculus of Variations and Differential Equations. Springer, Berlin (2000)
4. Alberti, G., Bouchitté, G., Seppecher, P.: Phase transition with the line-tension effect. Arch. Ration. Mech. Anal. 144(1), 1–46 (1998)
5. Ambrosio, L., Fusco, N., Pallara, D.: Functions of bounded variation and free discontinuity problems. Clarendon Press, Oxford (2000)
6. Ambrosio, L., Tortorelli, V.M.: Approximation of functionals depending on jumps by elliptic functionals via \(\Gamma\)-convergence. Commun. Pure Appl. Math. 43(8), 999–1036 (1990)
7. Berestycki, H., Lin, T.-C., Wei, J., Zhao, C.: On phase-separation model: Asymptotics and qualitative properties. Arch. Ration. Mech. Anal. 208, 163–200 (2013)
8. Berestycki, H., Terracini, S., Wang, K., Wei, J.: On entire solutions of an elliptic system modeling phase separations. Adv. Math. 243, 102–126 (2013)
9. Bouchitté, G.: Singular perturbations of variational problems arising from a two-phase transition model. Appl. Math. Optim. 21(3), 289–314 (1990)
10. Braides, A.: Approximation of Free-Discontinuity Problems. Lecture Notes in Mathematics, vol. 1694. Springer, Berlin (1998)
11. Braides, A.: \( \Gamma \)-Convergence for Beginners. Oxford Lecture Series in Mathematics and its Applications, vol. 22. Oxford University Press, Oxford (2002)

12. Brezis, H.: Semilinear equations in \( R^N \) without condition at infinity. Appl. Math. Optim. 12(3), 271–282 (1984)

13. Caffarelli, L.A., Lin, F.-H.: Singularly perturbed elliptic systems and multi-valued harmonic functions with free boundaries. J. Am. Math. Soc. 21(3), 847–862 (2008)

14. Conti, M., Terracini, S., Verzini, G.: On a class of optimal partition problem related to the Fučík spectrum and to the monotonicity formulae. Calc. Var. Partial Differ. Equ. 22(1), 45–72 (2005)

15. Gallo, C.: Expansion of the energy of the ground state of the Gross–Pitaevskii equation in the Thomas–Fermi limit. ArXiv e-prints (2012)

16. Gallo, C., Pelinovsky, D.: On the Thomas-Fermi ground state in a harmonic potential. Asymptot. Anal. 73, 53–96 (2011)

17. Hall, D.S., Matthews, M.R., Wieman, C.E., Cornell, E.A.: Measurements of relative phase in binary mixtures of Bose–Einstein condensates. Phys. Rev. Lett. 81, 1543–1547 (1998)

18. Ignat, R., Millot, V.: The critical velocity for vortex existence in a two-dimensional rotating Bose–Einstein condensate. J. Funct. Anal. 233, 260–306 (2006)

19. Karali, G.D., Sourdis, C.: The ground state of a Gross–Pitaevskii energy with general potential in the Thomas–Fermi limit. ArXiv e-prints (2012)

20. Lassoued, L., Mironescu, P.: Ginzburg–Landau type energy with discontinuous constraint. J. Anal. Math. 77, 1–26 (1999)

21. Maso, G.D.: Integral representation on \( BV(\omega) \) of \( \Gamma \)-limits of variational integrals. Manuscr. Math. 30(4), 387–416 (1979)

22. Mason, P., Aftalion, A.: Classification of the ground states and topological defects in a rotating two-component Bose–Einstein condensate. Phys. Rev. A 84(3), 033611 (2011)

23. McCarron, D.J., Cho, H.W., Jenkin, D.L., Köppinger, M.P., Cornish, S.L.: Dual-species Bose-Einstein condensate of \(^{87}\text{Rb}\) and \(^{133}\text{Cs}\). Phys. Rev. A 84, 011603 (2011)

24. Modica, L.: The gradient theory of phase transitions and the minimal interface criterion. Arch. Ration. Mech. Anal. 98(2), 123–142 (1987)

25. Modugno, G., Modugno, M., Riboli, F., Roati, G., Inguscio, M.: A two atomic species superfluid. Phys. Rev. Lett. 89, 190404–190408 (2002)

26. Noris, B., Tavares, H., Terracini, S., Verzini, G.: Uniform Hölder bounds for nonlinear Schrödinger systems with strong competition. Commun Pure Appl Math 63(3), 267–302 (2010)

27. Royo-Letelier, J.: Segregation and symmetry breaking of strongly coupled two-component Bose-Einstein condensates in a harmonic trap. Calc. Var. Partial Differ. Equ. 49, 103–124 (2014)

28. Wei, J., Weth, T.: Asymptotic behaviour of solutions of planar elliptic systems with strong competition. Nonlinearity 21(2), 305–317 (2008)