Flow equation of functional renormalization group for three-body scattering problems

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Functional renormalization group (FRG) is applied to the three-body scattering problem in the two-component fermionic system with an attractive contact interaction. We establish an exact flow equation on the basis of FRG and show that our flow equation is consistent with integral equations obtained from the Dyson–Schwinger equation. In particular, the relation of our flow equation and the Skornyakov and Ter-Martirosyan equation for the atom-dimer scattering is made clear.

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1. Introduction

Few-body physics often provides fruitful information for studying many-body physics. A typical example is the two-component fermionic system with an attractive contact interaction. At sufficiently low temperatures, the superfluid phase of this system shows crossover from the Bardeen–Cooper–Schrieffer (BCS)-type superfluidity to the Bose–Einstein condensation (BEC) as the attraction becomes stronger [1–4]. In the BEC region, existence of composite bosons, or dimers, implies that low-energy excitations must be described by those dimers. Therefore, the scattering property between two dimers has to be taken into account for quantitative understanding of BEC (see e.g. [5–7]). Furthermore, these studies can be related to other systems, such as nuclear matter or dense QCD [8,9]. In order to reflect knowledge of few-body physics in many-body theories, unified description for few-body and many-body physics is required. Since quantum field theory is a standard method for studies of many-body physics, it is important to establish a strategy of quantum field theory for few-body physics.

Functional renormalization group (FRG) [10–12], which has been recently developed as a non-perturbative method of quantum field theory, provides a unified description between few-body and many-body physics. Indeed, it has been applied not only to study few-body physics in many different contexts such as three-body or atom-dimer scattering problems [13,14], trion formation [15], dimer-dimer scattering problems [16,17], and Efimov physics [18–20], but also to study many-body physics, such as BCS–BEC crossover [21–23]. FRG is a formalism to calculate the one-particle-irreducible (1PI) effective action $\Gamma[\psi]$ of fields $\psi, \overline{\psi}$ in a non-perturbative way. In this formalism, we define the 1PI effective action $\Gamma_k[\psi]$ by adding the two-point function $\overline{\psi} R_k \psi$ to the classical action $S[\psi]$, where $k$ is a parameter controlling the scale. Then the functional $\Gamma_k[\psi]$ obeys the exact one-loop
flow equation \[10–12\]

\[
\partial_k \Gamma_k[\psi] = \frac{1}{2} \text{STr} \left[ \partial_k R_k (\Gamma_k^{(2)}[\psi] + R_k)^{-1} \right].
\] (1)

where \(\Gamma_k^{(2)}[\psi]\) is the second derivative with respect to the fields \(\psi\) and \(\overline{\psi}\). This equation is often called the Wetterich equation and holds an exact one-loop property. If the regulator term \(R_k\) vanishes as \(k \to 0\), then \(\Gamma_k\) reduces to the usual 1PI effective action \(\Gamma\), which contains all the information of quantum fluctuations.

FRG must be consistent with the Dyson–Schwinger equation, since both methods provide exact relations among Green functions. Theoretically, we can prove that the Dyson–Schwinger equation can be regarded as an integrated equation of the Wetterich equation [24]. However, in previous studies [13–20] on few-body physics with FRG, flow equations in general contradict Dyson–Schwinger equations, which indicates that some contributions in the flow equations are missed. Flow equations in previous studies were constructed based on observations that the Wetterich equation has an exact one-loop structure and the particle–hole loop vanishes in the vacuum for non-relativistic physics. However, some one-loop diagrams in the flow equation, which look like particle–hole loops at first sight, do not vanish even for non-relativistic scattering problems in the vacuum because of non-localities of 1PI effective vertices. As a result, a flow equation for a \(2n\)-point 1PI vertex depends on a \((2n + 2)\)-point 1PI vertex. This hierarchy of the flow equation can be solved in principle [25].

In this study, we consider three-body problems for a contact and attractive interaction of two-component fermions, and establish the correct flow equation of FRG in a concrete way. In order to construct the closed flow equation without any approximations, we combine diagrammatic techniques with FRG so as to identify feedback from higher-point vertices. Our flow equation is a closed equation and can be shown to be equivalent to the integral equation for the three-body problem originally derived by Skornyakov and Ter-Martirosyan [26]. Through this example, we can observe the relationship between flow equations and Dyson–Schwinger equations for few-body scattering problems. We also apply that relation to the model with an auxiliary dimer field in order to observe the change of structure of the flow equation due to the introduction of the dimer field.

An outline of this paper is as follows. In Sect. 2, we fix our notation and briefly review the result on the two-body scattering problem with an attractive contact interaction of two-component fermions. In Sect. 3, we consider its three-body scattering problem using FRG without introducing auxiliary fields and analyze the detailed structure of the flow equation. There we will find that feedback from higher-point vertices do not necessarily vanish; however, diagrammatic considerations will open a way to solving this hierarchy problem. As a result, we establish a new and correct flow equation for three-body problems in non-relativistic few-body physics. In Sect. 4, we discuss the relation between our flow equation derived in Sect. 3 and the Skornyakov and Ter-Martirosyan equation. This makes clear the connection between few-body physics in FRG and other conventional methods for scattering problems. In Sect. 5, we briefly discuss the flow of few-body physics when an auxiliary dimer field is introduced, and suggest that our previous observation is quite general. Finally, we summarize our result and comment on some perspectives in Sect. 6.

2. Two-body scattering problem

Before going into the three-body scattering problem, we need to consider and solve two-body scattering physics in the vacuum. We consider two-component fermionic systems with a contact interaction,
where the bare classical Lagrangian of that model is given by

$$\overline{\psi} \left( \partial_\tau - \frac{\nabla^2}{2m} - \mu \right) \psi(x) + g \overline{\psi}_\uparrow \psi_\downarrow \psi_\uparrow (x).$$

In (2), $\psi$ represents a two-component fermionic field, $\overline{\psi}$ its conjugate, $\tau$ the imaginary time, $m$ the mass of particles, and $\mu$ the chemical potential. In order to treat scattering physics in this way, we need to put the system in the vacuum (the temperature $T = 0$, and the particle number density $\rho = 0$).

In the effective action $\Gamma[\psi]$, all possible terms allowed by symmetries can appear in general. We introduce vertex functions as coefficients of the expansion in terms of the fields:

$$\Gamma[\psi] = \sum_{n=1}^{\infty} \frac{1}{(n!)^2} \int_{p_1,\ldots,p_n;q_1,\ldots,q_n} (2\pi)^4 \delta^4 \left( \sum_i p_i - \sum_j q_j \right) \times \Gamma^{\alpha_1,\ldots,\alpha_n}_{\beta_1,\ldots,\beta_n}(\{p_i\};\{q_j\}) \overline{\psi}_{p_1,\alpha_1} \cdots \overline{\psi}_{p_n,\alpha_n} \psi_{q_n,\beta_n} \cdots \psi_{q_1,\beta_1},$$

where $\int_p = \int d^4p/(2\pi)^4$, $\psi_p$, $\overline{\psi}_p$ are Fourier components of $\psi(x)$, $\overline{\psi}(x)$, and $\alpha_i$, $\beta_i$ denote spin indices. In particular, the four-point vertex $\Gamma^{\uparrow \downarrow \uparrow \downarrow}$ consists of a spin-singlet part and a spin-triplet part due to spin-$SU(2)$ symmetry. Since the contact interaction does not have relative momentum dependence, only the spin-singlet part $\Gamma^S_k(P)$ survives, where $P$ denotes the center-of-mass momentum.

The flow equation for the four-point coupling $\Gamma^S_k(P)$ is

$$- \partial_k \Gamma^S_k(P) = \tilde{\partial}_k \int_l \frac{[-\Gamma^S_k(P)]^2}{[G^{-1}_0 + R_k](l)[G^{-1}_0 + R_k](P - l)}.$$  (4)

Here we introduced the $k$-derivative $\tilde{\partial}_k$ which acts only on an explicit $k$-dependence of $R_k$ in propagators and $G^{-1}_0(l) = il^0 + l^2/2m - \mu$ is the free inverse propagator. A diagrammatic expression of (4) is given in Fig. 1.

Since the four-point couplings do not depend on relative momenta at the bare scale, relative momentum dependence of $\Gamma^S_k$ does not appear at any scale $k$. The renormalization condition of the four-point vertex is given by

$$\Gamma^S(P^0 = -2i\mu, P = 0) = 4\pi a_S/m,$$  (5)

where $a_S$ is the $s$-wave scattering length. For an attractive contact interaction, the condition $a_S < 0$ implies the absence of bound states and we can put $\mu = 0$ in realizing $\rho = 0$ at $T = 0$. If $a_S > 0$, there exists a bound state with the binding energy $1/ma_S^2$ and we should put $\mu = -1/2ma_S^2$ to realize $\rho = 0$ and $T = 0$.

If the bound state exits, we can identify the boson propagator by looking at its pole in the effective vertex function. Then, we can regard the fermion four-point vertex as in Fig. 2: In the left-hand side,
Fig. 2. Identification of the four-point coupling $\Gamma^S(P)$ and the bound-state propagator $D(P)$. This diagrammatic identification is meaningful even without the bound state.

Fig. 3. Flow equation of the six-point 1PI vertex. Each square vertex represents the negative of the corresponding 1PI vertex. External legs of each diagram are totally antisymmetrized.

The flow equation of $\Gamma_k^S$ (4), and the graphical notations introduced in Figs. 1 and 2 will be used in the following sections.

3. Three-body scattering problems in FRG

Let us go into three-body scattering problems. In the case where the bosonic bound state exists, calculating six-point 1PI vertices is necessary for solving the atom-dimer scattering problem in a purely fermionic framework. The following discussion works well even when the dimer does not exist.

Let us start with the flow equation of a six-point 1PI vertex $\Gamma_k^{\uparrow\uparrow\downarrow\downarrow\uparrow\uparrow}$. The diagrammatic expression of its flow equation can be found in Fig. 3, and its analytic expression will be given in Appendix A. There are two other diagrams in the right-hand side of Fig. 3 when we expand the Wetterich equation (1) in terms of fields $\psi, \bar{\psi}$, but diagrammatic consideration shows that they vanish because they necessarily contain particle–hole loops. The last diagram in the right-hand side of Fig. 3 may seem to vanish at first sight since it also looks like a particle–hole loop, but it can contribute due to non-local dependence of effective vertices on energies. We will find in the next section that the flow equation for the three-body problem can be consistent with the Dyson–Schwinger equation only when this term is taken into account.

If we use the flow equation in Fig. 3, it depends on eight-point 1PI vertices and the flow equation of eight-point vertices again depends on ten-point vertices. In this way, the hierarchy of the Wetterich equation (1) appears even for non-relativistic few-body problems. On the other hand, as a general property of non-relativistic few-body physics, we can solve $n$-body problems without considering $(n + 1)$-body problems. These two seemingly conflicting statements can be consistent, and the diagram containing eight-point 1PI vertices in Fig. 3 turns out to be written down within three-body scattering matrix elements, as we will see.

It is convenient to introduce the decomposition of the six-point 1PI vertex $\Gamma_k^{\uparrow\uparrow\downarrow\downarrow\uparrow\uparrow}$ by amputating external two-body $T$-matrices. A diagrammatic representation of this decomposition is given in
Fig. 4. Decomposition of the six-point vertex $\Gamma_{kk\uparrow\uparrow\downarrow\downarrow}$ by extracting the external two-body scattering part $\Gamma_{kS}$.

Fig. 5. All possible diagrams for the three-body sector in eight-point 1PI vertices.

Fig. 4, and according to this decomposition we define a new vertex function $\lambda_k$ so that

$$
\begin{align*}
\Gamma_{kk\uparrow\uparrow\downarrow\downarrow}(p_1, p_2, p_3; p'_3, p'_2, p'_1) &= -\Gamma_{kS}(p_{2+3})\lambda_k(p_1, p_{2+3}; p'_2, p'_1)\Gamma_{kS}(p'_{2+3}) + \Gamma_{kS}(p_{1+3})\lambda_k(p_2, p_{1+3}; p'_2, p'_1)\Gamma_{kS}(p'_{2+3}) \\
&+ \Gamma_{kS}(p_{2+3})\lambda_k(p_1, p_{2+3}; p'_1, p'_2)\Gamma_{kS}(p'_{1+3}) - \Gamma_{kS}(p_{1+3})\lambda_k(p_2, p_{1+3}; p'_1, p'_2)\Gamma_{kS}(p'_{1+3}).
\end{align*}
$$

(6)

Here we denote $p_{i+j} = p_i + p_j$. Indeed, we can show that this decomposition is possible directly from a formal diagrammatic expansion of the six-point vertex in terms of the scattering length $a_S$. When a dimer exists, this vertex $\lambda_k$ represents the scattering processes between atom and dimer.

With this decomposition, we can extract the three-body sector in eight-point vertices, which can contribute the last diagram in the right-hand side of Fig. 3. All possible 1PI diagrams in the eight-point vertex, which can contribute as feedback, are listed in Fig. 5. In order to obtain this result, we performed the perturbative expansion of the 1PI effective vertices in terms of the bare coupling $g$ and the fermion propagator ($G^{-1}_0 + R_k)^{-1}$ at the scale $k$. After that, we took a resummation of the formal power series for the eight-point 1PI vertices in order to express them with 1PI vertices at the scale $k$ with fewer external legs. Notice that all nine diagrams in Fig. 5 are one-particle irreducible, with eight external lines, and belonging to a three-body sector. The diagrams in Fig. 5 are called “1-closable” diagrams in Ref. [25].

The diagrammatic expression of eight-point vertices in Fig. 5 gives an expression for the feedback term in the flow equation of $\lambda_k$. In order to obtain the feedback terms, we just have to do the following procedures (see also Fig. 6):

1. amputate the external bosonic lines in each graph, and
2. close two fermion lines with the two-point function $\partial_k R_k$ so as not to make particle–hole loops.
Fig. 6. Diagrammatic procedures to get feedback terms from the diagrams in Fig. 5.

\[ \partial_k \rightarrow \bar{\partial}_k \left( \begin{array}{c} + \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \end{array} \right) + 9 \text{ feedback terms} \]

Fig. 7. Flow equation of \( \lambda_k \). Here, the 9 feedback terms can be found from Fig. 5.

\[ \lambda = \quad G = \quad K = \]

Fig. 8. Diagrammatic definition of symbols in (7), (8), and (9).

This procedure is clearly possible in each diagram in Fig. 5, and then we explicitly show here that feedback from higher-point vertices is possible even in the vacuum. Furthermore, this procedure closes the hierarchy of the Wetterich equation (1), and we need not consider four-body problems in discussing three-body scattering physics.

Diagrammatically, the flow equation for \( \lambda_k \) can be represented as in Fig. 7. The “9 feedback terms” in Fig. 7 are immediately obtainable from Fig. 5 by following the procedure described above. Using momentum conservation, \( P := p_1 + p_{2+3} = p_1' + p_{2+3}' \), we can reduce the number of variables in \( \lambda_k \). Let us introduce a matrix notation so that the matrix elements of \( \lambda, G, \) and \( K \) are given by

\[ \begin{align*}
(\lambda)_{q,q'} &= \lambda_k(P + q, -q; -q', P + q'), \\
(G)_{q,l} &= [G_0^{-1} + R_k]^{-1}(-l - P - q),
\end{align*} \]

and

\[ (K)_{l',l} = \frac{(2\pi)^4 \delta^4(l - l') \Gamma_k^S(-l)}{[G_0^{-1} + R_k](l + P)}. \]

Here we omit the \( k \)-dependence just for simplicity of notation.

Using the matrix notation, we can write down the analytic expression of the flow equation in Fig. 7 as

\[ \partial_k \lambda_k = \bar{\partial}_k (G \cdot K \cdot \lambda + \lambda \cdot K \cdot G + G \cdot K \cdot G) + 9 \text{ feedback terms}. \] (10)

From the diagrams in Fig. 5, the 9 feedback terms are given as follows:

9 feedback terms

\[ = G \cdot (\partial_k - \bar{\partial}_k)K \cdot G + \lambda \cdot K \cdot \partial_k G \cdot K \cdot G + G \cdot \partial_k G \cdot K \cdot \lambda + \lambda \cdot \partial_k G \cdot K \cdot G + \lambda \cdot (\partial_k - \bar{\partial}_k)K \cdot \lambda \]

\[ + \lambda \cdot (\partial_k - \bar{\partial}_k)K \cdot \lambda + \lambda \cdot K \cdot \partial_k G \cdot K \cdot \lambda + \lambda \cdot \partial_k G \cdot K \cdot \lambda. \] (11)
Here we used the flow equation for the four-point coupling $\Gamma_k^S$, and then $(\partial_k - \tilde{\partial}_k)\Gamma$ represent the self-energy correction of the dimer propagator in Eq. (11). Substituting (11) into (10), we find that

$$\partial_k \lambda_k = \partial_k (G \cdot K \cdot G) + \partial_k (G \cdot K) \cdot \lambda_k + \lambda_k \cdot \partial_k (K \cdot G)$$

$$+ G \cdot K \cdot \partial_k G \cdot K \cdot G + G \cdot K \cdot \partial_k G \cdot K \cdot \lambda_k$$

$$+ \lambda_k \cdot K \cdot \partial_k G \cdot K \cdot G + \lambda_k \cdot K \cdot \partial_k G \cdot K \cdot \lambda_k$$

$$+ \lambda_k \cdot \partial_k K \cdot \lambda_k. \quad (12)$$

This is the closed form of the flow equation for three-body scattering problems.

In the case of the two-body scattering problem with a contact interaction, such feedbacks are absent. This can be understood again most easily from diagrammatic considerations. The diagrams for six-point vertices do not have any structures like those in Fig. 5, because such six-point diagrams cannot be 1PI. The absence of the self-energy correction can also be understood through similar reasoning.

4. Formal solutions of three-body scattering problems

In order to find a formal solution for the atom-dimer scattering vertex $\lambda_k$, let us consider Dyson–Schwinger equations for the six-point vertex functions. We should point out that the Dyson–Schwinger equation must hold even for theories with an IR regulator $R_k$, and it can also be interpreted as an integrated flow of the Wetterich equation [24]. For the six-point vertex $\Gamma_{k}^{↑↑↓↓}$ in our model, we have two Dyson–Schwinger equations for the scattering problem. Their diagrammatic expressions can be found in Fig. 9. In deriving the second Dyson–Schwinger equation for the six-point vertex in Fig. 9, we use the Dyson–Schwinger equation for the four-point vertex $\Gamma_k^S$. This second expression of the Dyson–Schwinger equation is equivalent to the integral equation for three-body scattering problems derived by S. Weinberg in Ref. [27].

Combining these two Dyson–Schwinger equations in Fig. 9 and applying the decomposition of the six-point 1PI vertex in (6) or in Fig. 4, we obtain the integral equation for the atom-dimer scattering vertex $\lambda_k$. Diagrammatically, $\lambda_k$ satisfies the integral equation in Fig. 10, and its analytical expression is given by

$$\lambda = G \cdot K \cdot \lambda + G \cdot K \cdot G. \quad (13)$$

At $k = 0$, this integral equation is equivalent to the integral equation for the atom-dimer scattering $T$-matrix, which was originally derived by G. Skornyakov and K. Ter-Martirosyan [26]. We should emphasize that the integral equation (13) holds for any values of the parameter $k$. Furthermore, the solution of this integral equation (13) must satisfy the flow equation (12).

Let us explicitly show that the solution of this integral equation satisfies the flow equation (12). We can formally write down the solution of (13):

$$\lambda = G \cdot K \cdot G + G \cdot K \cdot G \cdot K \cdot G + \cdots. \quad (14)$$

To derive the flow equation, let us take the derivative with respect to $k$ of the both sides of (14), which gives

$$\partial_k \lambda = \partial_k (G \cdot K \cdot G) + \partial_k (G \cdot K) \cdot (G \cdot K \cdot G + \cdots)$$

$$+ (G \cdot K \cdot G + \cdots) \cdot \partial_k (K \cdot G)$$

$$+ (G + G \cdot K \cdot G + \cdots) \cdot \partial_k G \cdot K \cdot (G + G \cdot K \cdot G + \cdots)$$

$$+ (G \cdot K \cdot G + \cdots) \cdot \partial_k K \cdot (G \cdot K \cdot G + \cdots). \quad (15)$$
Fig. 9. Dyson–Schwinger equations for six-point 1PI vertices. The blobs represent bare couplings.

Fig. 10. Diagrammatic expression of the integral equation for $\lambda_k$.

Combining (14) and (15), we obtain

$$\partial_k \lambda = \partial_k (G \cdot K \cdot G) + \partial_k (G \cdot K) \cdot \lambda + \lambda \cdot \partial_k (K \cdot G)$$

$$+ (G + \lambda) \cdot K \cdot \partial_k G \cdot K \cdot (G + \lambda) + \lambda \cdot \partial_k K \cdot \lambda.$$ (16)

Now Eqs. (12) and (16) are the same, and the flow equation of FRG for few-body physics is explicitly shown to be equivalent to the Dyson–Schwinger equation. The procedure discussed here can provide a convenient way to obtain the closed flow equation of few-body physics.

5. Flow equation with auxiliary fields

So far, we have discussed few-body physics using FRG only with fermions. In this section, we introduce an auxiliary field describing dimers and briefly discuss the flow of the atom-dimer scattering vertex. We consider the model specified by the classical Lagrangian

$$\psi^G_f \phi^G_b - \frac{1}{2} \mu \psi \phi + h \phi \psi \psi \psi + h^* \phi \psi \psi,$$ (17)

where $G_f$ and $G_b$ are free propagators of $\psi$ and $\phi$, respectively, and $h$ is a coupling constant of the Yukawa-type interaction. Here $\psi$ is a Grassmannian field and $\phi$ represents a bosonic field. The Lagrangian in (17) is equivalent to the one in (2) via the Hubbard–Stratonovich transformation by putting $G_f^{-1} = (\partial_t - \nabla^2/2m - \mu)$, $G_b^{-1} = -1/g$, and $h = i$. Since there are two different degrees of freedom $\psi$ and $\phi$ in this model, we introduce two regulating functions $R_k^{(f)}$ and $R_k^{(b)}$, so that the IR regulating term is given by

$$\overline{\psi} R_k^{(f)} \psi + \phi^* R_k^{(b)} \phi.$$ (18)

These two regulating functions can be chosen independently, and we can go back to the model in the previous sections by putting $R_k^{(b)} = 0$, which corresponds to integration out of the bosonic degrees of freedom.

In order to derive the flow equation describing the few-body physics of this model, we use the technology developed in Sect. 4: we derive Dyson–Schwinger equations of the IR-regularized theory at first and take the $k$-derivative of the formal solution of that integral equation. In this model, fermion propagators and the Yukawa coupling do not get quantum correction, and thus they do not flow under the change of $k$. Also, the 1PI vertex describing scattering between atoms remains zero at any $k$. On the other hand, the bosonic dimer propagator acquires the quantum correction and its Dyson–Schwinger equation is given in Fig. 11. This immediately gives the same flow equation given in Fig. 1, and we find that the effective boson propagator is given by $-(\Gamma_k^{S^{-1}} - R_k^{(b)})^{-1}$. Apart from
Fig. 11. The Dyson–Schwinger equation for the dimer propagator. Here, dashed lines describe dimer propagators, the square box on the left-hand side is the self-energy correction of dimer fields, the blobs in the right-hand side are Yukawa couplings $h, h^*$, and the solid lines describe fermion propagators at the scale $k$: $(G_f^{-1} + R_k^{(f)})^{-1}$. As usual, external lines are amputated.

Fig. 12. Dyson–Schwinger equation for the atom-dimer 1PI vertex.

Fig. 13. Flow equation of the atom-dimer 1PI vertex $\lambda_k$.

the existence of $R^{(b)}_k$, we can identify the double lines of the diagrams in the previous sections with the dashed lines in this section.

Now we can discuss scattering processes between an atom and a dimer using this model. The 1PI vertex involving one atom and one dimer satisfies the Dyson–Schwinger equation shown in Fig. 12, which corresponds to the integral equation in Fig. 10. Writing the atom-dimer 1PI vertex as $\lambda_k$ again, its formal solution is given by the series in (14), in which $G$ and $K$ should be replaced by

$$(G)_{q,l} = [G_f^{-1} + R_k^{(f)}]^{-1}(-l - P - q),$$

and

$$(K)_{l',l} = (2\pi)^4\delta^4(l - l')[\Gamma_k^{-1} - R_k^{(b)}]^{-1}(-l)/[G_f^{-1} + R_k^{(f)}](l + P),$$

instead of (8) and (9). Now we find the flow equation of $\lambda_k$ for the model with auxiliary fields with any regulators, which is given by (16).

Let us interpret this result from the viewpoint of the Wetterich equation (1). By separating the $k$-derivative $\partial_k$ in the right-hand side of (16) into the derivative $\tilde{\partial}_k$ of $k$-dependence of regulators $R^{(f,b)}_k$ and the other parts, we find four terms, which can be directly obtained from the expansion of Wetterich equation, and another eight terms, which correspond to feedback from higher-point vertices. Therefore, the Wetterich equation of $\lambda_k$ takes the form given in Fig. 13, where the last feedback term completely corresponds to the first eight diagrams shown in Fig. 5. In the model with auxiliary fields, the contribution from the last diagram in Fig. 5 appears in the original one-loop contribution, but the structure of the other eight feedback terms is the same as before.
6. Conclusion

In this paper, we showed that some one-loop diagrams in the flow equation, which look like particle–hole loops at first sight, do not vanish even for non-relativistic scattering problems in the vacuum. This can happen due to non-localities of the effective vertices, and this fact causes the hierarchy problem of the Wetterich equation for few-body physics. In order to construct the closed flow equation for those problems, we need to write down possible diagrams for higher-point vertices. We also suggest that Dyson–Schwinger equations can provide a convenient way to construct the closed flow equation, as discussed in Sects. 4 and 5.

In order to construct a new flow equation of FRG for three-body physics, we identified all Feynman diagrams for eight-point vertices which contribute to the flow equation for three-body scattering problems. Combining the flow equation of FRG with diagrammatic considerations, we derived a closed flow equation for the three-body scattering problem. Furthermore, we proved consistency between our flow equation for the three-body problems and the corresponding Dyson–Schwinger equation, and the relation of our method with the Skornyakov and Ter-Martirosyan equation is unveiled.

We also observed the structure of the flow equation when auxiliary dimer fields are introduced. Starting from the Dyson–Schwinger equation, we systematically derived the flow equation of FRG without any approximations and showed that even with the auxiliary fields there exists feedback from higher-point vertices for atom-dimer, or three-body, scattering problems.

Let us compare our studies with previous works on few-body physics in FRG. In Ref. [14], the authors discussed the atom-dimer scattering with FRG by introducing bosonic fields via the Hubbard–Stratonovich transformation as in (17). They showed that their flow equation for the atom-dimer scattering is consistent with the Skornyakov and Ter-Martirosyan equation if \( R_k^{(f)} = 0 \) in (18), in which fermions are integrated out at first so that the only dynamical degrees of freedom are bosonic dimers. We have formally proved the consistency for more general cases, and, furthermore, we have constructed concrete procedures to treat three-body scattering problems using FRG.

FRG has also been applied to few-body physics in order to reveal its universality, especially in the context of Efimov physics with the help of dimer fields [18–20]. In these studies, atoms are integrated out at first so that the Skornyakov and Ter-Martirosyan equation holds. In the context of renormalization group methods, Efimov physics can be interpreted as a limit cycle solution of the renormalization group transformations [28]. Limit cycles can appear only when the flow equation of \( \lambda_k \) depends on itself quadratically, and such quadratic terms of \( \lambda_k \) appear through feedback from higher-point vertices if dimer fields are not introduced. Therefore, in order to discuss Efimov physics using FRG without dimer fields, use of our formalism would be inevitable.

We expect that a formulation for four-body scattering problems within FRG can also be given in a similar way, but this task would be for future work. Even though we can solve such problems by deriving integral equations directly from the Dyson–Schwinger equation, formulating that problem in the context of FRG is important for revealing many-body properties of physical systems, since FRG provides a unified description both for few-body and many-body physics.

\[^{1}\] To see this fact clearly, let us treat \( \lambda \) as a constant coupling. Then the flow equation of \( \lambda \) takes the form
\[
\frac{d}{dk}\lambda = A(k)\lambda^2 + B(k)\lambda + C(k),
\]
where \( A, B, \) and \( C \) are some coefficients. In order to realize a limit cycle, \( \lambda \) must repeat to run from \(-\infty\) to \(+\infty\). Therefore, it is necessary that \( B(k)^2 - 4A(k)C(k) < 0 \) in order for a limit cycle, but this is impossible if \( A = 0 \).
Appendix A. Supplement for the flow equation of six-point vertex functions

An analytic expression for the flow equation in Fig. 3 is given by

\[
- \partial_k \Gamma_k \frac{\Gamma^\prime_{k_{1+3}}(p_1, p_2, p_3; p_3', p_2', p_1')}{[G^{-1}_0 + R_k](l)} = \tilde{\partial}_k \int \left( \frac{\Gamma^\prime_{k_{1+2}}(p_1, p_2, l, p_3; p_3', p_2', p_1')}{[G^{-1}_0 + R_k](l)} + \frac{\Gamma^\prime_{k_{1+2}}(p_1, p_2, p_3, l; l, p_3', p_2', p_1')}{R_k}\right) \frac{1}{[G^{-1}_0 + R_k](l)}
\]

where we have introduced the abbreviation \( p_{2+3} = p_2 + p_3, \ p_{1-1}' = p_1 - p_1', \) etc. In Sect. 3, we found physical meanings of each term when we consider atom-dimer scattering problems with the model given by (2). The first two terms in the right-hand side of (A1) represent dissociation of dimers, and they become two-loop diagrams when we represent then using atom-dimer scattering vertex \( \lambda_k \). The other terms in (A1) represent rescattering between atom and dimer.

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