EXISTENCE OF MARTINGALE SOLUTIONS AND THE INCOMPRESSIBLE LIMIT FOR STOCHASTIC COMPRESSIBLE FLOWS ON THE WHOLE SPACE

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Abstract. We give an existence and asymptotic result for the so-called finite energy weak martingale solution of the compressible isentropic Navier–Stokes system driven by some random force in the whole spatial region. In particular, given a general nonlinear multiplicative noise, we establish the convergence to the incompressible system as the Mach number, representing the ratio between the average flow velocity and the speed of sound, approaches zero.

1. Introduction

In continuum mechanics, the motion of an isentropic compressible fluid is described by the density \( \rho = \rho(t, x) \) and velocity \( \mathbf{u} = \mathbf{u}(t, x) \) in a physical domain in \( \mathbb{R}^3 \) satisfying the mass and momentum balance equations given respectively by

\[
\begin{align*}
\partial_t \rho + \text{div}(\rho \mathbf{u}) &= 0, \\
\partial_t (\rho \mathbf{u}) + \text{div}(\rho \mathbf{u} \otimes \mathbf{u}) &= \text{div} \mathbf{T} + \rho \mathbf{f}.
\end{align*}
\]

Here \( \mathbf{f} \) is some external force and \( \mathbf{T} \) the stress tensor. By Stokes’ law, \( \mathbf{T} \) satisfies \( \mathbf{T} = \mathbf{S} - p \mathbf{I} \) where \( p = p(\rho) \) is the pressure and \( \mathbf{S} = \mathbf{S}(\nabla \mathbf{u}) \) the viscous stress tensor. In following Newton’s law of viscosity, we assume that \( \mathbf{S} \) satisfies

\[ \mathbf{S} = \nu (\nabla \mathbf{u} + \nabla^T \mathbf{u}) + \lambda \text{div} \mathbf{u} \mathbf{I} \]

with viscosity coefficients satisfying \( \nu > 0, \lambda + \frac{2}{3} \nu \geq 0 \). For the pressure, we suppose the \( \gamma \)-law

\[ p = \frac{1}{\text{Ma}^2} \rho^\gamma \]

where \( \text{Ma} > 0 \) is the Mach number and \( \gamma > \frac{3}{2} \), the adiabatic exponent. In order to study the existence of solutions to system (1.1), it has to be complemented by initial and boundary conditions (very common are periodic boundary conditions, no-slip boundary conditions and the whole space). The existence of weak solutions to (1.1) has been shown in the fundamental book by Lions [23] and extended to physical reasonable situations by Feireisl [11, 15], giving a compressible analogue of the pioneering work by Leray [22] on the incompressible case. These results involve the concept of weak solutions where derivatives have to be understood in the sense

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of distributions. This concept has since become an integral technique in the study of nonlinear PDE’s.

In recent years, there has been an increasing interest in random influences on fluid motions. It can take into account, for example, physical, empirical or numerical uncertainties and is commonly used to model turbulence in the fluid motion.

As far as we know, the first result on the existence of solution to the stochastic compressible system is due to [34]. This was done in 1-D and later for a special periodic 2-D case in [33]. The latter mostly relied on existence arguments developed in [35]. In [13], a semi-deterministic approach based on results on multi-valued functions is used and follows in line with the incompressible analogue shown in [1]. A fully stochastic theory has been developed in [5]. The existence of martingale solutions has been shown in the case of periodic boundary conditions. This has been extended to Dirichlet boundary conditions in [32].

Compared to the stochastic compressible model, the incompressible system has been studied much more intensively. It first appeared in the seminal paper by Benoussan and Temam [1] which is based on a semi-deterministic approach. Later, the concept of a martingale solution of this system was then introduced by Flandoli and Gatarek [16]. For a recent survey on the stochastic incompressible Navier–Stokes equations, we refer the reader to [30] or to [29] for the general survey including deterministic results.

The aim of this paper is to look at the situation on the whole space $\mathbb{R}^3$. This is particularly important for various applications and especially for those in which the comparative size of the fluids domain far exceeds the speed of sound accompanying the fluid. See [14] for more details. Difficulties arise due to the lack of certain compactness tools which are available in the case of bounded domains. We shall study the system

\begin{equation}
\begin{aligned}
\frac{d\rho}{dt} + \text{div}(\rho\mathbf{u}) &= 0, \\
\frac{d(\rho\mathbf{u})}{dt} + [\text{div}(\rho\mathbf{u} \otimes \mathbf{u} - \nabla \mathbf{u}) + \nabla p(\rho)] &= \Phi(\rho, \rho\mathbf{u})dW,
\end{aligned}
\end{equation}

in $Q_T = (0, T) \times \mathbb{R}^3$. A prototype for the stochastic forcing term will be given by

\begin{equation}
\begin{aligned}
\Phi(\rho, \rho\mathbf{u})dW &\approx \rho dW^1 + \rho\mathbf{u} dW^2
\end{aligned}
\end{equation}

where $W^1$ and $W^2$ is a pair of independent cylindrical Wiener processes. We refer to Sect. 2 for the precise assumptions on the noise and its coefficients.

The first main result of the present paper is the existence of finite energy weak martingale solutions to (1.2). The precise statement is given in Theorem 2.4. We approximate the system on the whole space by a sequence of periodic problems (where the period tends to infinity). After showing uniform a priori estimates, we use the stochastic compactness method based on the Jakubowski-Skorokhod representation theorem. In contrast to previous works, we adapt it to the situation on the whole space taking carefully into account, the lack of compact embeddings. In order to pass to the limit in the nonlinear pressure term, we use properties of the effective viscous flux originally introduced by Lions [23] similar to [5].

A fundamental question in compressible fluid mechanics is the relation to the incompressible model. If the Mach number is small, the fluid should behave asymptotically like an incompressible one, provided velocity and viscosity are small, and we are looking at large time scales, see [21]. The problem has been studied rigorously in the deterministic case in [24, 25, 26], as a singular limit problem. A major problem to overcome is the rapid oscillation of acoustic waves due to the
lack of compactness. A stochastic counterpart of this theory has very recently been established in [3]. The limit $\varepsilon$ of the system
\[ d\rho + \text{div}(\rho \mathbf{u})dt = 0, \]
\[ d(\rho \mathbf{u}) + [\text{div}(\rho \mathbf{u} \otimes \mathbf{u} - S(\nabla \mathbf{u})) + \nabla \frac{\rho^2}{\varepsilon}]dt = \Phi(\rho, \rho \mathbf{u})dW, \]
has been analyzed under periodic boundary conditions. Given a sequence of the so-called finite energy weak martingale solution for (1.4) (see next section for definition) where $\varepsilon \in (0,1)$, its limit (as $\varepsilon \to 0$) is indeed a weak martingale solution to the following incompressible system:
\[ \text{div}(\mathbf{u}) = 0, \]
\[ d(\mathbf{u}) + [\text{div}(\mathbf{u} \otimes \mathbf{u}) - \nu \Delta \mathbf{u} + \nabla \tilde{p}]dt = P\Phi(1, \mathbf{u})dW. \]
Here $\tilde{p}$ is the associated pressure and $P$ is the Helmholtz projection onto the space of solenoidal vector fields.

A major drawback in the approach in [3] is that the noise coefficient $\Phi(\rho, \rho \mathbf{u})$ has to be linear in the momentum $\rho \mathbf{u}$. This is due to the aforementioned lack of compactness of momentum when $\varepsilon$ passes to zero. This cannot even be improved in the deterministic case. The situation on the whole space, however, is much better as a consequence of dispersive estimates for the acoustic wave equations, see Proposition 1.8. We apply them to the stochastic wave equation and hence are able to prove strong convergence of the momentum, see Lemma 4.11. Based on this, we are able to prove the convergence of (1.4) to (1.5) under much more general assumptions on the noise coefficients. See Theorem 2.6 for details.

In Sect. 2 we state the required assumptions satisfied by the various quantities used in this paper, as well as some useful function space estimates. We define the concept of a solution, state the required boundary condition applicable in our setting and finally state the main results.

In Sect. 3 we are concerned with the proof of Theorem 2.4 giving existence of martingale solutions on the whole space. Based on this result, we devote Sect. 4 to the proof of Theorem 2.6 the low-Mach number limit on the whole space.

2. Preliminaries

Throughout this paper, the spatial dimension is $N = 3$ and we assume that $(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t \geq 0}, \mathbb{P})$ is a stochastic basis with a complete right-continuous filtration, $W$ is a $(\mathcal{F}_t)$-cylindrical Wiener process, that is, there exists a family of mutually independent real-valued Brownian motions $(\beta_k)_{k \in \mathbb{N}}$ and orthonormal basis $(e_k)_{k \in \mathbb{N}}$ of a separable Hilbert space $U$ such that
\[ W(t) = \sum_{k \in \mathbb{N}} \beta_k(t)e_k, \quad t \in [0, T]. \]
We also assume that $\varrho \in L^\gamma_\text{loc}(\mathbb{R}^3)$, $\varrho \geq 0$, and $\mathbf{u} \in L^2_\text{loc}(\mathbb{R}^3)$ so that $\sqrt{\varrho} \mathbf{u} \in L^2_\text{loc}(\mathbb{R}^3)$.

Now let set $\mathbf{q} = \varrho \mathbf{u}$ and assume that there exists a compact set $K \subset \mathbb{R}^3$ and some functions $g_k: \mathbb{R}^3 \times \mathbb{R} \times \mathbb{R}^3 \to \mathbb{R}^3$ such that
\[ g_k \in C^1_0(K), \quad \text{for any } k \in \mathbb{N}, \]
and in addition, satisfies the following growth conditions:
\[ \sum_{k \in \mathbb{N}} |g_k(x, \varrho, \mathbf{q})|^2 \leq c (\varrho^2 + |\mathbf{q}|^2), \quad \sum_{k \in \mathbb{N}} |\nabla \varrho, \mathbf{q} g_k(x, \varrho, \mathbf{q})|^2 \leq c. \]
Then if we define the map \( \Phi(\varrho, \varrho u) : \Omega \rightarrow L^1(\mathcal{K}) \) by \( \Phi(\varrho, \varrho u)e_k = g_k(\cdot, \varrho(\cdot), \varrho u(\cdot)) \), we can use the embedding \( L^1(\mathcal{K}) \hookrightarrow W^{-1,2}(\mathcal{K}) \) where \( l > \frac{3}{2} \), to show that \( \| \Phi(\varrho, \varrho u) \|_{L^2(\Omega; W^{-1,2}(\mathcal{K}))}^2 \) is uniformly bounded provided \( \varrho \in L^q_{\text{loc}}(\mathbb{R}^3) \) and \( \sqrt{\varrho}u \in L^2_{\text{loc}}(\mathbb{R}^3) \). See [5] Eq. 2.3. As such, the stochastic integral \( \int_0^\cdot \Phi(\varrho, \varrho u) \, dW \) is a well-defined \((\mathcal{F}_t)\)-martingale taking value in \( W^{-1,2}_{\text{loc}}(\mathbb{R}^3) \).

Lastly, we define the auxiliary space \( \mathcal{U}_0 \supset \mathcal{U} \) via

\[
\mathcal{U}_0 = \left\{ u = \sum_{k \geq 1} c_k e_k : \sum_{k \geq 1} \frac{c_k^2}{k^2} < \infty \right\}
\]

and endow it with the norm

\[
\| u \|_{\mathcal{U}_0} = \sum_{k \in \mathbb{N}} \frac{c_k^2}{k^2}, \quad u = \sum_{k \in \mathbb{N}} c_k e_k.
\]

Then it can be shown that \( W \) has \( \mathbb{P} \)-a.s. \( C([0, T]; \mathcal{U}_0) \) sample paths with the Hilbert–Schmidt embedding \( \mathcal{U} \hookrightarrow \mathcal{U}_0 \). See [7].

### 2.1. Sobolev inequalities for the homogeneous Sobolev space.

As we shall see shortly, the compactness techniques used in this paper involves certain estimates whose constants must necessarily be independent of the size of the domain. We therefore require the homogeneous Sobolev space

\[
D^{1,q}(\mathcal{O}) = \begin{cases} 
  u \in D'(\mathcal{O}) : u \in L^{\frac{3q}{q-1}}(\mathcal{O}), \nabla u \in L^q(\mathcal{O}) & \text{if } 1 \leq q < 3 \\
  u = \{\varphi + c\} \in \mathbb{R} : u \in L^q_{\text{loc}}(\mathcal{O}), \nabla u \in L^q(\mathcal{O}) & \text{if } q \geq 3
\end{cases}
\]

which gives such Sobolev-type estimates. Here \( \mathcal{O} \) is an exterior or an unbounded domain, for example \( \mathcal{O} = \mathbb{R}^3 \). In particular, given a function \( u \in D^{1,q}(\mathcal{O}) \), we have that for any \( 1 \leq q < 3 \),

\[
\| u \|_{L^{\frac{3q}{q-1}}(\mathcal{O})} \leq c_q \| \nabla u \|_{L^q(\mathcal{O})}
\]

See [17] Chapter II for more details. Note that the constant above is independent of the size of \( \mathcal{O} \), unlike in the case of the usual Sobolev–Poincaré’s inequality.

To continue, let us define the concept of a solution used in this paper.

**Definition 2.1.** If \( \Lambda \) is a Borel probability measure on \( L^7(\mathbb{R}^3) \times L^{\frac{2}{1+\gamma}}(\mathbb{R}^3) \), then we say that

\[
[(\Omega, \mathcal{F}, (\mathcal{F}_t), \mathbb{P}; \varrho, u, W)]
\]

is a **finite energy weak martingale solution** of Eq. (1.3) with initial law \( \Lambda \) provided:

1. \((\Omega, \mathcal{F}, (\mathcal{F}_t), \mathbb{P})\) is a stochastic basis with a complete right-continuous filtration,
2. \( W \) is a \((\mathcal{F}_t)\)-cylindrical Wiener process,
3. the density \( \varrho \) satisfies \( \varrho \geq 0, t \mapsto (\varrho(t, \cdot), \phi) \in C[0, T] \) for any \( \phi \in C_0^\infty(\mathbb{R}^3) \) \( \mathbb{P} \)-a.s., the function \( t \mapsto (\varrho(t, \cdot), \phi) \) is progressively measurable, and

\[
\mathbb{E} \left[ \sup_{t \in [0, T]} \| \varrho(t, \cdot) \|^p L^7(\mathcal{K}) \right] < \infty \quad \text{for all } 1 \leq p < \infty,
\]

and for all \( \mathcal{K} \subset \mathbb{R}^3 \) with \( \mathcal{K} \) compact,
(4) the momentum \( gu \) satisfies \( t \to \langle gu, \phi \rangle \in C[0, T] \) for any \( \phi \in C^\infty_c(\mathbb{R}^3) \)
\( \mathbb{P} \)-a.s., the function \( t \to \langle gu, \phi \rangle \) is progressively measurable, and for all \( 1 \leq p < \infty \)
\[ \mathbb{E} \left[ \sup_{t \in [0, T]} \| \sqrt{\rho} u \|_{L^2(K)}^p \right] < \infty, \quad \mathbb{E} \left[ \sup_{t \in [0, T]} \| gu \|_{L^{\frac{p}{2}}(\mathbb{R}^3)}^p \right] < \infty, \]
for all \( K \subset \mathbb{R}^3 \), \( K \) compact,

(5) the velocity field \( u \) is \((\mathcal{F}_t)\)-adapted, \( u \in L^p \left( \Omega; L^2 \left( 0, T; W^{1,2}_{\text{loc}}(\mathbb{R}^3) \right) \right) \) and,
\[ \mathbb{E} \left[ \left( \int_0^T \| u \|_{W^{1,2}(K)}^2 dt \right)^{\frac{p}{2}} \right] < \infty \text{ for all } 1 \leq p < \infty, \]
for all \( K \subset \mathbb{R}^3 \), \( K \) compact,

(6) \( \Lambda = \mathbb{P} \circ (\rho(0), gu(0))^{-1} \),

(7) for all \( \psi \in C^\infty_c(\mathbb{R}^3) \) and \( \phi \in C^\infty_c(\mathbb{R}^3) \) and all \( t \in [0, T] \), it holds \( \mathbb{P} \)-a.s.
\[ \langle gu(t), \psi \rangle = \langle gu(0), \psi \rangle + \int_0^t \langle gu, \nabla \psi \rangle ds, \]
\[ \langle gu(t), \phi \rangle = \langle gu(0), \phi \rangle + \int_0^t \langle gu \otimes u, \nabla \phi \rangle ds - \nu \int_0^t \langle \nabla u, \nabla \phi \rangle ds \]
\[ - (\lambda + \nu) \int_0^t \langle \text{div } u, \text{div } \phi \rangle ds + \frac{1}{\text{Ma}^2} \int_0^t \langle q, \text{div } \phi \rangle ds \]
\[ + \int_0^t \langle \tilde{\Phi}(\rho, gu) dW, \phi \rangle, \]

(8) for any \( 1 \leq p < \infty \), the energy estimate
\[ \mathbb{E} \left[ \sup_{t \in [0, T]} \int_{\mathbb{R}^3} \left( \frac{\rho |u|^2}{2} + H(\rho) \right) (t) dx \right]^{\frac{p}{2}} + \mathbb{E} \left[ \int_{Q_T} S(\nabla u) : \nabla u dx ds \right]^{\frac{p}{2}} \]
\[ \leq c_p \left( 1 + \mathbb{E} \left[ \int_{\mathbb{R}^3} \left( \frac{\rho |u|^2}{2\rho_0} + H(\rho, \cdot) \right) dx \right]^{\frac{p}{2}} \right), \]
holds where \( Q_T := (0, T) \times \mathbb{R}^3 \) and where
\[ H(\rho) = \frac{a}{\gamma - 1} (\tilde{\rho}^\gamma - \gamma \tilde{\rho}^{\gamma - 1} (\rho - \tilde{\rho}) - \tilde{\rho}^\gamma). \]
is the pressure potential for constants \( a, \tilde{\rho} > 0 \).

(9) In addition, \( (2.2) \) holds in the renormalized sense. That is, for any \( \phi \in \mathcal{D}'(\mathbb{R}^3) \) and \( b \in C^0(0, \infty) \cap C^1(0, \infty) \) such that \( |b'(t)| \leq c t^{-\lambda_0}, t \in (0, 1], \lambda_0 < 1 \) and \( |b'(t)| \leq c t^{\lambda_1}, t \geq 1 \) where \( c > 0 \) and \(-1 < \lambda_1 < \infty \), we have that
\[ d \langle b(\rho), \phi \rangle = \langle b(\rho) u, \nabla \phi \rangle dt - \langle (b(\rho) - b'(\rho) \phi) \text{div } u, \phi \rangle dt. \]

Remark 2.2. The definition above also holds for functions defined on the periodic space \( T^3_L := ([-L, L]_L)^3 = (\mathbb{R} \times 2L\mathbb{Z})^3 \) for any \( L \geq 1 \), rather than on the whole space \( \mathbb{R}^3 \). In that case, it even suffices to consider just smooth test functions which are not necessarily compactly supported. See for example [4, 3, 5].
Definition 2.3. If $\Lambda$ is a Borel probability measure on $L^2_{div}(\mathbb{R}^3)$, then we say that $[(\Omega, \mathcal{F}, (\mathcal{F}_t), \mathbb{P}), u, W]$ is a weak martingale solution of Eq. (1.5) with initial law $\Lambda$ provided:

1. $(\Omega, \mathcal{F}, (\mathcal{F}_t), \mathbb{P})$ is a stochastic basis with a complete right-continuous filtration,
2. $W$ is a $(\mathcal{F}_t)$-cylindrical Wiener process,
3. $u$ is $(\mathcal{F}_t)$-adapted, $u \in C^w([0, T]; L^2_{div}(\mathbb{R}^3)) \cap L^2(0, T; W^{1,2}_{div}(\mathbb{R}^3)) \mathbb{P}$-a.s.

and,

$$\mathbb{E}\left[\sup_{0 \leq t \leq T} \|u\|^2_{L^2(\mathbb{R}^3)}\right]^p + \mathbb{E}\left[\left(\int_0^T \|u\|^p_{W^{1,2}(\mathbb{R}^3)} dt\right)^p\right] < \infty \text{ for all } 1 \leq p < \infty,$$

4. $\Lambda = \mathbb{P} \circ (u(0))^{-1},$

5. for all $\phi \in C^\infty_c(\mathbb{R}^3)$ and all $t \in [0, T]$, it holds $\mathbb{P}$-a.s.

$$\langle u(t), \phi \rangle = \langle u(0), \phi \rangle + \int_0^t \left[\langle u \otimes u, \nabla \phi \rangle - \nu \langle \nabla u, \nabla \phi \rangle\right] ds + \int_0^t \langle P\Phi(1, u) dW, \phi \rangle.$$

Existence of weak martingale solutions as defined in Definition 2.3 has been shown to exist under suitable growth conditions on the noise term. We refer the reader to [27], albeit stated in the Stratonovich sense. A global-in-space existence result stated in the Itô form appears to be absent from the literature although it is certainly expected. However, this is a by product of the singular limit problem that we study in this paper. See Theorem 2.6 below. For bounded domains, see for example, [6, 16].

2.2. Prescribed boundary conditions. Let assume that the right-hand side of the energy inequality (2.5) is finite. Then we can deduce from (2.6) that

$$\lim_{|x| \to \infty} \varrho(x) = \overline{\varrho}$$

for some $\overline{\varrho} > 0$. This is because if we apply Taylor’s expansion around the constant $\overline{\varrho}$ for the function $f(\varrho) = \varrho^2$, we can rewrite (2.6) as

$$H(\varrho) = \frac{\alpha \gamma z^{1-2}}{2} (\varrho - \overline{\varrho})^2, \quad z \in [\varrho, \overline{\varrho}] \text{ or } z \in [\overline{\varrho}, \varrho]$$

and so the boundedness of the left-hand side of (2.6) means that the difference $\varrho - \overline{\varrho} \in L^p(\Omega; L^\infty(0, T; L^{\min(2, \gamma)}(\mathbb{R}^3)))$ when (2.9) is substituted into (2.5).

Furthermore, we also have that $\varrho \|u\|^2 \in L^1(\Omega; L^\infty(0, T; L^1(\mathbb{R}^3)))$ and as such,

$$\lim_{|x| \to \infty} \varrho(x) \|u(x)\|^2 = 0.$$

By combining (2.8) and (2.10) (keeping in mind that $\overline{\varrho} \neq 0$), it is reasonable to impose the boundary condition

$$\lim_{|x| \to \infty} u(x) = 0.$$

2.3. Main results. We now state the main results of this paper.
Theorem 2.4. Let $\gamma > \frac{1}{2}$ and let $\Lambda$ be a probability law on $L^\gamma(\mathbb{R}^3) \times L^{\frac{2\gamma}{\gamma+1}}(\mathbb{R}^3)$ satisfying

$$
\Lambda\{(\rho, q) \in L^\gamma(\mathbb{R}^3) \times L^{\frac{2\gamma}{\gamma+1}}(\mathbb{R}^3) : \rho \geq 0,
M_1^K \leq \int_K \rho \, dx \leq M_2^K, q|_{t=0} = 0, \left| \frac{\rho - 1}{\varepsilon} \right| \leq M_1^K \} = 1,$n
$$
\int_{L^3 \times L^{\frac{2\gamma}{\gamma+1}}} \left\| \frac{1}{2} \frac{|q|^2}{\rho} + H(q) \right\|_{L_3^p}^p \, d\Lambda(\rho, q) \leq c_p < \infty,$n

for all $0 \leq p < \infty$ and any compact set $K \subset \mathbb{R}^3$ with constants $0 < M_1^K < M_2^K$ which are independent of $\varepsilon \in (0, 1)$. Also assume that (2.1) and (2.2) holds. Then there exists a finite energy weak martingale solution of (1.3) in the sense of Definition 2.3 with initial law $\Lambda$.

Remark 2.5. The assumption $|\frac{\rho - 1}{\varepsilon}| \leq M_1^K$ given in the law above is not restrictive and can actually be dropped. However, it is needed in the proof of Theorem 2.6 below.

Theorem 2.6. Let $\Lambda$ be a given Borel probability measure on $L^2(\mathbb{R}^3)$ and for $\varepsilon \in (0, 1)$, we let $\Lambda_\varepsilon$ be a Borel probability measure on $L^\gamma(\mathbb{R}^3) \times L^{\frac{2\gamma}{\gamma+1}}(\mathbb{R}^3)$ where $\gamma > 3/2$ is such that the initial law in Theorem 2.4 holds and where the marginal law of $\Lambda_\varepsilon$ corresponding to the second component converges to $\Lambda$ weakly in the sense of measures on $L^{\frac{2\gamma}{\gamma+1}}(\mathbb{R}^3)$. If $[(\Omega^\varepsilon, \mathcal{F}^\varepsilon, (\mathcal{F}^\varepsilon_t), \mathbb{P}^\varepsilon); \rho_\varepsilon, u_\varepsilon, \omega_\varepsilon]$ is a finite energy weak martingale solution of (1.3) with initial law $\Lambda_\varepsilon$, then

$$(\rho_\varepsilon - 1) \to 0 \quad \text{in law in} \quad L^\infty(0, T; L^{\min\{2, \gamma\}}(\mathbb{R}^3))$$
$$u_\varepsilon \to u \quad \text{in law in} \quad \left( L^2(0, T; W^{1,2}(\mathbb{R}^3)), W \right)$$
$$\rho_\varepsilon u_\varepsilon \to u \quad \text{in law in} \quad L^2(0, T; L^{\min\{2, \gamma\}}(\mathbb{R}^3))$$

where $u$ is a weak martingale solution of (1.5) in the sense of Definition 2.3 with the initial law $\Lambda$ and $r \in (\frac{3}{2}, 6)$.

3. Proof of Theorem 2.4

Let $\rho_L$ and $u_L$ be some density and velocity fields defined $d\mathbb{P} \times dt$ a.e. $(\omega, t) \in \Omega \times [0, T]$ on the space $\mathbb{T}^3_L$ such that $\rho_L$ and $u_L$ satisfies the so-called dissipative estimate; existence of which is shown in [11, Eq. 3.2] for the particular choice of $L = 1$.

We observe that [11, Eq. 3.2] is translation invariant and as such, holds true for any fixed $L \geq 1$. Also, the inequality is preserved if we replace $H_\delta(\rho)$ by $H(\rho)$. As such if we consider $\psi = \chi_{[0, t]}$, then we obtain the inequality:

$$
\int_0^t \int_{\mathbb{T}^3_L} \mathcal{S}(\nabla u_L) : \nabla u_L \, dx \, ds + \int_{\mathbb{T}^3_L} \left[ \frac{\rho_L(t)|u_L(t)|^2}{2} + H(\rho_L(t)) \right] \, dx \leq 
$$
$$
\int_{\mathbb{T}^3_L} \left[ \frac{(|\rho_L u_L(0)|^2)}{2\rho_L(0)} + H(\rho_L(0)) \right] \, dx + \int_0^t \int_{\mathbb{T}^3_L} u_L : \mathbf{\Phi}(\rho_L, \rho_L u_L) \, dx \, dW 
$$
$$
+ \int_0^t \sum_{k \in \mathbb{N}} \left| \frac{\rho_L(t)|u_L(t)|^2}{2\rho_L} \right| \, dx \, ds
$$

(3.1)
However, due to (2.1), there is a compact set $K \subset \mathbb{R}^3$ such that for any $1 \leq p < \infty$, we have that

$$
\begin{align*}
E \sup_{t \in [0,T]} \left| \int_0^t \int_{T_L} \sum_{k \in \mathbb{N}} \frac{|g_k(\varrho_L, \varrho_L u_L)|^2}{2\varrho_L} dx \, ds \right|^p \\
\leq E \left( \int_0^T \int_{T_L} \sum_{k \in \mathbb{N}} \frac{|g_k(\varrho_L, \varrho_L u_L)|^2}{2\varrho_L} dx \, ds \right)^p \\
\leq c \left( \int_0^T \int_K (\varrho_L^{-1} (\varrho_L^2 + |\varrho_L u_L|^2) \, dx \, ds \right)^p \\
\leq c_p \int_0^T \left( \int_K (1 + \varrho_L^2 + \varrho_L |u_L|^2) \, dx \right) ds
\end{align*}
$$

where $c_p$ is independent of both $k$ and $L$ and where we have used $\varrho_L \leq 1 + \varrho_L^2$.

Also, by the use of the Burkholder–Davis–Gundy inequality, Hölder inequality and Young’s inequality, we have that

$$
E \left[ \sup_{t \in [0,T]} \left| \int_0^t \int_{T_L} u_L \cdot \Phi(\varrho_L, q_L) dx \, dW \right|^p \right]
$$

$$
= E \left[ \sup_{t \in [0,T]} \left| \int_0^t \sum_{k \in \mathbb{N}} \int_{T_L} u_L \cdot g_k(\varrho_L, q_L) dx \, d\beta_k \right|^p \right]
$$

$$
\leq c_p E \left[ \int_0^T \sum_{k \in \mathbb{N}} \left( \int_{T_L} u_L \cdot g_k(\varrho_L, q_L) dx \right)^2 ds \right]^\frac{p}{2}
$$

$$
\leq c_p E \left[ \int_0^T \sum_{k \in \mathbb{N}} \left( \int_{T_L} \sqrt{\varrho_L} u_L^2 dx \right)^2 \left( \int_{T_L} \frac{|g_k(\varrho_L, q_L)|^2}{\sqrt{\varrho_L}} dx \right) ds \right]^\frac{p}{2}
$$

$$
\leq c \left( \sup_{t \in [0,T]} \int_{T_L} |\sqrt{\varrho_L} u_L|^2 dx \right)^p + c_{p,\epsilon} \int_0^T \left( \int_K (1 + \varrho_L^2 + \varrho_L |u_L|^2) dx \right) ds
$$

for an arbitrarily small $\epsilon > 0$.

By taking the $p$th-moment of the supremum in (3.1) and applying Gronwall’s lemma, we obtain the inequality

$$
E \left[ \sup_{t \in [0,T]} \int_{T_L} \left( \frac{\varrho_L u_L^2}{2} + H(\varrho_L) \right) dx \right]^p + E \left[ \int_0^T \int_{T_L} S(\nabla u_L) : \nabla u_L dx \, ds \right]^p
\leq c_{p,\epsilon, \text{vol}(K)} \left( 1 + E \left[ \int_{T_L} \left( \frac{|q_L|}{2\varrho_L} + H(\varrho_L(0, \cdot)) \right) dx \right]^p \right)
$$

where $c_{p,\epsilon, \text{vol}(K)}$ is in particular, independent of $L$. Now by the assumptions on $\Lambda$, the right hand side of (3.2) is finite. As such, we obtain the following uniform
However, we only obtain the estimate locally in space because of the constant term uniformly in (3.6) 

In view of the bounds established in (3.3), (3.4) and the assumptions on the initial and, consequently, (3.5) 

Note that the estimates in (3.3) are global but unfortunately, do not include all necessary quantities. In the following, we derive local estimates with respect to balls \( B_r \) which will depend on the radius \( r > 0 \). A consequence of (3.3) is 

(3.4) 

uniformly in \( L \) (but depending on \( r \)). If \( B_r \subset \mathbb{T}^3_1 \), this follows in an obvious way from the definition of \( H \). Otherwise we cover \( B_r \subset \mathbb{R}^3 \) by tori to which \( \varrho_L \) is extended by means of periodicity. The number of necessary tori depends on \( r \) but is independent of \( L \). To see this, we notice that since \( \text{vol}(B_r) \approx c(\pi) r^3 \) and \( \text{vol}(\mathbb{T}^3_1) \approx c(\pi) L^3 \), we will require \( o(\frac{c}{L}) \) number of tori to cover \( B_r \). But since \( L \geq 1 \), we in fact require \( o(r^3) \) (which is independent of \( L \)) number of such tori to cover \( B_r \).

**Remark 3.1.** We get (3.4) by making it the subject in (2.4) and using (3.3). However, we only obtain the estimate locally in space because of the constant term \( \mathbf{7} \) in the pressure potential (2.0). This will blow up with the size of the torus if we try obtaining a global estimate.

We observe that none of the bounds in (3.3) directly controls the amplitude of \( \mathbf{u}_L \). However using the Sobolev-Poincaré’s inequality and \( \gamma > \frac{2}{3} \), the following holds 

\[
\| \varrho_0 \|_{L^1(B_r)} \| (\mathbf{u}_L)_{B_r} \| = \left| \int_{B_r} \varrho (\mathbf{u}_L)_{B_r} \, dx \right| 
\leq c \int_{B_r} | \varrho | (| \mathbf{u}_L |)_{B_r} \, dx + \int_{B_r} \varrho | | \mathbf{u}_L | | \, dx 
\leq c \| \varrho \|_{L^\gamma(B_r)} \| (\mathbf{u}_L)_{B_r} - \mathbf{u}_L \|_{L^\alpha(B_r)} + c \| \varrho \|_{L^{\gamma}(B_r)} \| \mathbf{u}_L \|_{L^2(B_r)} 
\leq c(r) \| \varrho \|_{L^\gamma(B_r)} \| (\mathbf{u}_L)_{B_r} - \mathbf{u}_L \|_{L^6(B_r)} + c \| \varrho \|_{L^{\gamma}(B_r)} \| \mathbf{u}_L \|_{L^2(B_r)} 
\leq c(r) \| \mathbf{u}_L \|_{L^2(B_r)} \| \nabla \mathbf{u}_L \|_{L^2(B_r)} + c \| \varrho \|_{L^\gamma(B_r)} + c \| \varrho \|_{L^2(B_r)}^2 
\| \mathbf{u}_L \|_{L^1(B_r)} \| 
\]

and, consequently,

\[
\| \varrho_0 \|_{L^1(B_r)}^2 \int_0^T (| (\mathbf{u}_L)_{B_r} |^2 \, dt \leq c(r) \sup_{t \in [0,T]} \| \varrho \|_{L^\gamma(B_r)}^2 \int_0^T \| \nabla \mathbf{u}_L \|_{L^2(B_r)}^2 \, dt 
+ c \tau \sup_{t \in (0,T)} \left( \| \varrho \|_{L^\gamma(B_r)} + \| \varrho \|_{L^2(B_r)}^2 \right)^2 .
\]

(3.5)

In view of the bounds established in (3.3), (3.4) and the assumptions on the initial law, we can conclude that

(3.6) 

\( \mathbf{u}_L \in L^p(\Omega; L^2(0,T; W^{1,2}(B_r))) \),

uniformly in \( L \).
Furthermore, for \( r > 0 \), we can use the (uniform in \( L \) but not in \( r \)) continuous embedding \( W^{1,2}(B_r) \hookrightarrow L^6(B_r) \) and Hölder’s inequality, to get for \( \mathbb{dP} \times dt \) a.e. \((\omega, t) \in \Omega \times [0, T],\)

\[
\|\varrho_L u_L\|_{L^{\frac{3}{2-\sigma}}(B_r)} \leq \|\sqrt{\varrho_L}\|_{L^2(B_r)} \|\sqrt{\varrho_L} u_L\|_{L^2(B_r)} \leq \|\varrho_L\|_{L^\infty(B_r)} \|\sqrt{\varrho_L u_L}\|_{L^2(B_r)}.
\]

Therefore follows from the fact that the constant \( c \) in (3.10) is independent of \( L \) (but depends on \( r \)).

**Lemma 3.2.** Let \( B_r \subset \mathbb{R}^3 \) be a ball of radius \( r > 0 \). Then for all \( \Theta \leq \frac{2}{\gamma} - 1 \), we have that

\[
\mathbb{E} \int_0^T \int_{B_r} a\varrho_L^{\gamma + \Theta} \, dx \, dt \leq c
\]

where the constant \( c \), is independent of \( L \) (but depends on \( r \)).

**Proof.** If we set \( B_{r,L}^3 := B_r \cap \mathbb{T}_L^3 \), then it is enough to prove that

\[
\mathbb{E} \int_0^T \int_{B_{r,L}^3} a\varrho_L^{\gamma + \Theta} \, dx \, dt \leq c
\]

independently of \( L \). The general case then follows by covering \( B_r \) by sets of the form \( B \cap \mathbb{T}_L^3 \) for a ball \( B \). First notice that by combining (2.3) with the continuity property of the Bogovski operator \( \mathcal{B}(\varrho_L^{\Theta}) = \mathcal{B} [\varrho_L^{\Theta} - \int \varrho_L^{\Theta} \, dx] \), where \( \mathcal{B} = \mathcal{B}_{r,L} \) is as defined in [9] Theorem 5.2] for the set \( B_{r,L}^3 \), we ensure that

\[
\|\mathcal{B}(\varrho_L^{\Theta})\|_{L^{\frac{6}{5-\gamma}}(B_{r,L}^3)} \leq c\|\varrho_L^{\Theta}\|_{L^6(B_{r,L}^3)}, \quad r > 0
\]

holds uniformly in \( L \) for \( 1 \leq q < 3 \).

**Remark 3.3.** Note that in fact the set \( B_{r,L}^3 \) is a bounded John domain and hence satisfies the emanating chain condition with some constants \( \sigma_1 \) and \( \sigma_2 \) which are independent of the size of the torus. The fact that the constant \( c \) in (3.10) is independent of \( L \) therefore follows from the fact that the constant \( c \) in [9] Theorem 5.2] only depends on \( \sigma_1 \), \( \sigma_2 \) and \( q \) as well as the fact that \( c_q \) is independent of \( L \).

The idea now is to test the momentum equation with \( \mathbb{B}(\varrho^{\Theta}) \). To do this however, we first replace the map \( \varrho \mapsto \varrho^{\Theta} \) with the function \( b(\varrho) \in C^1(\mathbb{R}) \) and apply Itô formula to the function \( f(b, q) = \int_{B_{r,L}^3} q : \mathbb{B}(b(\varrho)) \, dx \) where \( \mathbb{B}(b(\varrho)) = \mathcal{B} [b(\varrho) - \int b(\varrho) \, dx] \). Since \( f \) is linear in \( q \), no second-order derivative in this component exits. Also, the quadratic variance of \( b(\varrho) \) is zero since the renormalized continuity equation is deterministic.
Now, notice that the Bogovskii operator commutes with the time derivative (but not with the spatial derivative) and since the continuity equation is satisfied in the renormalized sense, we have that
\[
\int_0^t f_{QL}(b_L, q_L) \, db_L = \int q_L \cdot \partial_{b_L}(\mathbb{B}(b_L)) \, db_L \, dx = \int q_L \cdot \mathbb{B} \left[ \text{div}(b_L u_L) - (b'_{QL} b_L - b_Q L) \text{div} u_L \right] \, dx.
\]
As such for \( b_L := b(Q_L) \), the following holds in expectation:
\[
\int_0^t f_{QL}(b_L, q_L) \, db_L = \int q_L \cdot \mathbb{B} \left[ \text{div}(b_L u_L) \right] \, dx.
\]
\[
= -\int q_L \cdot \mathbb{B} \left[ \text{div}(b_L u_L) \right] \, dx ds - \int q_L \cdot \mathbb{B} \left[ (b_L b'_L - b_L) \text{div} u_L \right] \, dx ds
\]
\[
= \int \mathbb{B}(b_L) \left[ -\text{div}(b_L u_L \otimes u_L) + \nu \Delta u_L + \left( \lambda + \nu \right) \nabla \text{div} u_L - a \nabla \varphi_L \right] \, dx ds
\]
\[
+ \int \mathbb{B}(b_L) \Phi(Q_L, \varphi_L u_L) \, dB (L) \, dx
\]
\[
= \int \left[ (b_L u_L \otimes u_L) \nabla \mathbb{B}(b_L) \, dx ds - \nu \nabla u_L : \nabla \mathbb{B}(b_L) - (\lambda + \nu) b_L \text{div} u_L \right] \, dx ds
\]
\[
+ \int a \varphi^2_L \, dl \, ds + \int \mathbb{B}(b_L) \Phi(Q_L, \varphi_L u_L) \, dB (L) \, dx
\]
\[
\int_0^t f_{QL}(b_L, q_L) \, dB (L) = \int f_{QL}(b_L, q_L) \, dB (L) = 0 \quad \text{since } dB (L) = f_{QL} q_L = 0
\]
where we have integrated by parts and used the fact that \( \mathbb{B}(f) \) solves the equation \( \text{div} \mathbf{v} = f \). It therefore follows that
\[
\mathbb{E} \int_{B^3_{t,r}} \mathbf{q} \cdot \mathbb{B}(b_L) \, dx = \mathbb{E} \int_{B^3_{t,r}} \mathbf{q}_L(0) \cdot \mathbb{B}(b_L(0)) \, dx
\]
\[
- \mathbb{E} \int_0^t \int_{B^3_{t,r}} \mathbf{q} \cdot \mathbb{B} \left[ \text{div}(b_L u_L) \right] \, dx ds
\]
\[
- \mathbb{E} \int_0^t \int_{B^3_{t,r}} \mathbf{q} \cdot \mathbb{B} \left[ \partial_{b_L} b'_L \text{div} u_L \right] \, dx ds + \mathbb{E} \int_0^t \int_{B^3_{t,r}} \mathbf{q} \cdot \mathbb{B} \left[ b_L \text{div} u_L \right] \, dx ds
\]
\[
+ \mathbb{E} \int_0^t \int_{B^3_{t,r}} (b_L u_L \otimes u_L) \nabla \mathbb{B}(b_L) \, dx ds - \mathbb{E} \int_0^t \int_{B^3_{t,r}} \nu \nabla u_L : \nabla \mathbb{B}(b_L) \, dx ds
\]
\[
- \mathbb{E} \int_0^t \int_{B^3_{t,r}} (\lambda + \nu) b_L \text{div} u_L \, dx ds + \mathbb{E} \int_0^t \int_{B^3_{t,r}} a \varphi^2_L \, dl \, dx ds
\]
\[
+ \mathbb{E} \int_0^t \int_{B^3_{t,r}} \mathbb{B}(b_L) \Phi(Q_L, \varphi_L u_L) \, dB (L) \, dx =: \mathbb{E} \sum_{i=1}^9 J_i.
\]

To improve the regularity of \( Q \), we aim at estimating \( J_8 \) in terms of the rest. To do this, we first set the left-hand side of (3.11) to \( \mathbb{E} J_0 \). Then using (2.3), (3.3), (3.6), (3.7) and heavy reliance on Hölder inequalities, we can show just as in [2] Propositions 5.1, 6.1] for \( \delta = 0 \) and noting that \( \Delta^{-1} \nabla \) and \( \mathcal{B} \) enjoys the same
continuity properties;
\[ E \varepsilon_i \leq c, \quad \text{for all } i \in \{0, 1, \ldots, 9\} \setminus \{8\} \]
for some constants \( c = c_{0, \gamma} \) which are in particular, independent of \( L \).

**Remark 3.4.** In estimating \( J_2 \), we use instead, the Bogovskiĭ operator in negative spaces which can be found in [18 Proposition 2.1], [2] or [10]. Also, note the comment just after [18 Remark 2.2] about carrying over the properties of the Bogovskiĭ operator from a star shaped domain onto more common domains treated in the analysis of PDE’s.

The result follows by making \( E \varepsilon_8 \) the subject and estimating it from above by the estimates given by the rest. \( \square \)

### 3.2. Compactness

We now show that not only are our earlier estimates bounded uniformly on the torus \( T^d \) but due to the fact that each constants obtained are uniform in \( L \), they are indeed bounded locally on the whole space \( \mathbb{R}^3 \). We then proceed to show the usual compactness arguments.

**Lemma 3.5.** For any \( L \geq 1 \), we have that
\[
\begin{align*}
\mathbf{u}_L &\in L^p(\Omega; L^2(0, T; W^{1,2}_{\text{loc}}(\mathbb{R}^3))), \\
\varepsilon L \mathbf{u}_L &\in L^p(\Omega; L^\infty(0, T; L^2_{\text{loc}}(\mathbb{R}^3))), \\
\varepsilon L \mathbf{u}_L &\in L^p(\Omega; L^\infty(0, T; L^{2\gamma}_{\text{loc}}(\mathbb{R}^3))), \\
\varepsilon L \mathbf{u}_L &\in L^p(\Omega; L^\infty(0, T; L^{\gamma+\Theta}_{\text{loc}}(\mathbb{R}^3))),
\end{align*}
\]
it uniformly in \( L \).

**Proof.** We will only show the first uniform estimate as the rest can be done in a similar manner in conjunction with \( \text{(3.3)}, \text{(5.7)} \) and Lemma \( \text{(3.2)} \).

Let \( L, r \in \mathbb{N} \) and let \( B_r \subset \mathbb{R}^3 \) be the ball of radius \( r \) centered at the origin. If \( B_r \subset T^d \), then we notice that we can directly deduce from \( \text{(3.3)} \) that
\[ u_L \in L^p(\Omega; L^2(0, T; W^{1,2}(B_r))) \]
it uniformly in \( L \). Otherwise, we can use the same argument as in the justification of \( \text{(3.3)} \) above to get from \( \text{(3.3)} \)
\[ \|u_L\|_{L^p(\Omega; L^2(0, T; W^{1,2}(B_r)))} \leq c(p, r), \quad \forall r \in \mathbb{N} \]
it uniformly in \( L \). That is, for any \( r \in \mathbb{N} \) and any \( B_r \subset \mathbb{R}^3 \), \( \text{(3.13)} \) holds. By combining \( \text{(3.12)} \) and \( \text{(3.13)} \), we can deduce that
\[ u_L \in L^p(\Omega; L^2(0, T; W^{1,2}_{\text{loc}}(\mathbb{R}^3))) \]
it uniformly in \( L \). \( \square \)

For the compactness result, let define the following path space \( \chi = \chi_u \times \chi_v \times \chi_w \) where
\[
\begin{align*}
\chi_u &= \left(L^2(0, T; W^{1,2}_{\text{loc}}(\mathbb{R}^3)), \omega\right), \\
\chi_v &= C_\omega \left([0, T]; L^{\gamma+\Theta}_{\text{loc}}(\mathbb{R}^3)\right) \cap \left(L^\gamma(0, T; L^{\gamma+\Theta}_{\text{loc}}(\mathbb{R}^3)), \omega\right), \\
\chi_{\varepsilon u} &= C_\omega \left([0, T]; L^{\gamma+\Theta}_{\text{loc}}(\mathbb{R}^3)\right), \\
\chi_w &= C \left([0, T]; \omega\right),
\end{align*}
\]
and let

1. \( \mu_{u_L} \) be the law of \( u_L \) on \( \chi_u \),
2. \( \mu_{\theta_L} \) be the law of \( \theta_L \) on the space \( \chi_\theta \),
3. \( \mu_{g_L,u_L} \) be the law of \( g_L,u_L \) on the space \( \chi_{eu} \),
4. \( \mu_W \) be the law of \( W \) on the space \( \chi_W \),
5. \( \mu^L \) be the joint law of \( u_L, \theta_L, g_L u_L \) and \( W \) on the space \( \chi \).

**Proposition 3.6.** For an arbitrary constant \( c \), which is uniform in \( r \in \mathbb{N}, L \geq 1 \) and \( R > 0 \), let us define the set

\[
A_R := \{ u_L \in L^2(0,T;W^{1,2}_{\text{loc}}(\mathbb{R}^3)) : \| u_L \|_{L^2(0,T;W^{1,2}(B_r))} \leq c(r)R, \quad \forall r \in \mathbb{N} \}.
\]

Then \( A_R \) is compact in \( \chi_u \).

**Proof.** To see this, fix \( R > 0 \) and consider the subsequence \( \{ u_n \}_{n \in \mathbb{N}} \subset A_R \) so that

\[
\| u_n \|_{L^2(0,T;W^{1,2}(B_r))} \leq c(r)R, \quad \forall n \in \mathbb{N} \quad \text{and} \quad \forall r \in \mathbb{N}.
\]

Then by the use of a diagonal argument, we can construct the sequence \( \{ u_n^m \}_{n,m \in \mathbb{N}} \subset A_R \) that is a common subsequence of all the sequences \( \{ u_n^m \}_{n \in \mathbb{N}} \) for all \( m \in \{ 0 \} \cup \mathbb{N} \) where \( u_n^0 := u_n \). And by uniqueness of limits, we can therefore conclude that

\[
u_n^m \rightarrow u \quad \text{in} \quad L^2(0,T;W^{1,2}(B_r)) \quad \text{for every} \quad r \in \mathbb{N}.
\]

This finishes the proof. \( \square \)

**Proposition 3.7.** The family of measures \( \{ \mu^L ; L \geq 1 \} \) is tight on \( \chi \).

**Proof.** We first show that \( \{ \mu_{u_L} ; L \geq 1 \} \) is tight on \( \chi_u \). To do this, we let \( R > 0 \), then by Proposition 3.6 there exists a compact subset \( A_R \subset \chi_u \). Now since \( (A_R)^C := \{ u_L \in L^2(0,T;W^{1,2}_{\text{loc}}(\mathbb{R}^3)) : \| u_L \|_{L^2(0,T;W^{1,2}(B_r))} > c(r)R, \quad \forall r \in \mathbb{N} \} \),

for any measure \( \mu_{u_L} \in \{ \mu_{u_L} ; L \geq 1 \} \), there exists a \( r \in \mathbb{N} \) such that:

\[
\mu_{u_L} \left( (A_R)^C \right) = \mathbb{P} \left( \| u_L \|_{L^2(0,T;W^{1,2}(B_r))} > c(r)R \right)
\]

\[
< \frac{1}{c(r)R} \mathbb{E} \left( \| u_L \|_{L^2(0,T;W^{1,2}(B_r))} \right) \leq \frac{1}{R} \rightarrow 0.
\]

as \( R \rightarrow \infty \), where we have used (3.13) in the last inequality. This implies that \( \{ \mu_{u_L} ; L \geq 1 \} \) is tight on \( \chi_u \).

By using a similar argument adapted to suit the compactness arguments in Sect. 6) we can show that \( \{ \mu_{\theta_L} ; L \geq 1 \} \) and \( \{ \mu_{g_L,u_L} ; L \geq 1 \} \) are also tight on \( \chi_\theta \) and \( \chi_{eu} \) respectively. Furthermore, \( \mu_W \) is tight since its a Radon measure on the Polish space \( \chi_W \). This finishes the proof. \( \square \)

From Proposition 3.7 we cannot immediately use Skorokhod representation theorem to deduce that \( \{ \mu^L ; L \geq 1 \} \) is relatively compact (i.e. Prokhorov theorem), since the path space \( \chi \) is not metrizable. However, we may use instead the Jakubowski–Skorokhod representation theorem which gives a similar result but for more general spaces including quasi-Polish spaces, the space in which these locally in space Sobolev functions live. Applying this yields the following result:

**Proposition 3.8.** There exists a subsequence \( \mu^n := \mu^{L_n} \) for \( n \in \mathbb{N} \), a probability space \( (\bar{\Omega}, \bar{\mathcal{F}}, \bar{\mathbb{P}}) \) with \( \chi \)-valued random variables \( (\bar{u}_n, \bar{\theta}_n, \bar{q}_n, \bar{W}_n) \), and their corresponding ‘limit’ variables \( (\tilde{u}, \tilde{\theta}, \tilde{q}, \tilde{W}) \) such that
• the law of \((\bar{u}_n, \bar{\varrho}_n, \bar{q}_n, \bar{W}_n)\) is given by \(\mu^n = \text{Law}(u_{L_n}, \varrho_{L_n}, q_{L_n}, u_{L_n}, W)\), \(n \in \mathbb{N}\),
• the law of \((\bar{u}, \bar{\varrho}, \bar{q}, \bar{W})\), denoted by \(\mu = \text{Law}(u, \varrho, u, W)\) is a Random measure,
• \((\bar{u}_n, \bar{\varrho}_n, \bar{q}_n, \bar{W}_n)\) converges \(\bar{P}\)-a.s to \((\bar{u}, \bar{\varrho}, \bar{q}, \bar{W})\) in the topology of \(\chi\).

To extend this new probability space \((\bar{\Omega}, \bar{\mathcal{F}}, \bar{\mathbb{P}})\) into a stochastic basis, we endow it with a filtration. To do this, let us first define a restriction operator \(r_t\) define by
\[
\mathcal{F}_t^n = \sigma \left( \sigma \left( r_t \bar{\varrho}_n, r_t \bar{u}_n, r_t \bar{W}_n \right) \cup \{N \in \mathcal{F}; \bar{\mathbb{P}}(N) = 0\} \right), \quad t \in [0, T],
\]
\[
\mathcal{F}_t = \sigma \left( \sigma (r_t \bar{\varrho}, r_t \bar{u}, r_t \bar{W}) \cup \{N \in \mathcal{F}; \bar{\mathbb{P}}(N) = 0\} \right), \quad t \in [0, T].
\]

The following result thus follows:

**Lemma 3.9.** For any \(n > 0\), \([\bar{\Omega}, \bar{\mathcal{F}}, (\mathcal{F}_t^n)_{t \geq 0}, \bar{\mathbb{P}}, \bar{\varrho}_n, \bar{u}_n, \bar{W}_n]\) is a weak martingale solution of \((1.3)\) with initial law \(\Lambda\). Furthermore, there exists \(b > \frac{3}{2}\) and a \(W^{-b,2}(\mathbb{R}^3)\)-valued continuous square integrable \((\mathcal{F}_t)\)-martingale \(M\) and \(\hat{p} \in L^\infty([0, T])\) such that \([\bar{\Omega}, \bar{\mathcal{F}}, (\mathcal{F}_t)_{t \geq 0}, \bar{\mathbb{P}}, \hat{\varrho}, \hat{u}, \hat{p}, \hat{M}\) is a weak martingale solution of
\[
d\hat{\varrho} + \text{div}(\hat{\varrho}\hat{u}) + |\hat{\varrho}\varDelta \hat{u} - (\lambda + \nu)\text{div}\hat{u} + \nabla \hat{p}|dt = d\hat{M}, \quad \text{in } \bar{\Omega} \times Q
\]
with initial law \(\Lambda\). Furthermore, \((3.16)\) is satisfied in the renormalized sense.

**Proof.** This follows in exactly the same manner as in [5, Proposition 5.6].

**Corollary 3.10.** The following \(\bar{\mathbb{P}}\)-a.s. convergence holds:
\[
\bar{u}_n \to \bar{u} \quad \text{in } L^2(0, T; W_{\text{loc}}^{1,2}(\mathbb{R}^3)),
\]
\[
\bar{\varrho}_n \to \bar{\varrho} \quad \text{in } C_{\text{loc}}([0, T]; L_{\text{loc}}^7(\mathbb{R}^3)),
\]
\[
\hat{\varrho}_n \to \hat{\varrho} \quad \text{in } L^{1+\Theta}(0, T; L_{\text{loc}}^{1+\Theta}(\mathbb{R}^3)),
\]
\[
\hat{\varrho}_n \bar{u}_n \to \hat{\varrho} \hat{u} \quad \text{in } C_{\text{loc}}([0, T]; \bar{u}_0),
\]
\[
\bar{W}_n \to \bar{W} \quad \text{in } C([0, T]; \bar{u}_0).
\]

**Proof.** The first three and the last is exactly contained in Proposition 3.8. For \((3.17)\), see [5, Lemma 5.5, Proposition 6.3].

**Proposition 3.11.** The limit process \(\bar{u}\) in \((3.17)\) is globally defined in space, i.e., \(\bar{u} \in L^2(0, T; W^{1,2}(\mathbb{R}^3))\).

**Proof.** Let \(B_r \subset \mathbb{R}^3\) be an arbitrary ball of radius \(r > 0\). Then from \((3.17)\), we have that for \(\bar{\mathbb{P}}\)-a.s.,
\[
\bar{u}_n \to \bar{u} \quad \text{in } L^2(0, T; W^{1,2}(B_r)), \quad \text{for } r > 0.
\]
However, lower semicontinuity of norms means that for any such $r > 0$,
\[
\| \chi_{B_r} \nabla \tilde{u} \|_{L^2(0,T;L^2(\mathbb{R}^3))} = \| \nabla \tilde{u} \|_{L^2(0,T;L^2(B_r))} \leq \liminf_{n \to \infty} \| \nabla \tilde{u}_n \|_{L^2(0,T;L^2(B_r))}
\]
\(\tilde{P}\)-a.s. Passing to the limit $r \to \infty$ on either side of this inequality finishes the proof since by the Gagliardo–Nirenberg–Sobolev inequality, (2.3) then follows for $q = 2$. \qed

### 3.3. The effective viscous flux.
This section combines ideas from [15, 28] and [28, Chapter 7].

Let $\Delta^{-1}$ be the inverse Laplacian on $\mathbb{R}^3$ and let the global-in-space operators $A_i = \Delta^{-1}[\partial_{x_i} u]$, $i = 1, 2, 3$ be as defined in [28, Sect. 4.4.1] or [15, Sect. 3.4].

Then by using the convention $\partial_k := \partial_{x_i}$ and for some cutoff functions $\phi(x), \bar{\phi}(x) \in C_c^\infty(\mathbb{R}^3)$, we may do a similar computation as in (3.11). That is, we apply Itô’s formula to the function $f(g, \bar{\phi}) = \int_{\mathbb{R}^3} \bar{\phi}(x) A_i[\phi(x)g] \, dx$ where $g = T_k(\bar{\phi})$ and $T_k : [0, \infty) \to [0, \infty)$ is given by
\[
T_k(t) = \begin{cases} t & \text{if } 0 \leq t < k, \\ k & \text{if } k \leq t < \infty. \end{cases}
\]

Or equivalently, by testing the momentum equation satisfied by the sequence of weak martingale solution in Lemma 3.11 by $\varphi(x) = \phi(x) A_i[\bar{\phi}(x) T_k(\bar{\phi})]$. We obtain the following (by assuming that $L$ is large enough such that $spt \phi \subset T^L_k$)

\[
\tilde{E} \int_{\mathbb{R}^3} \phi \partial_n \tilde{u}_n A_i[\phi T_k(\bar{\phi})] \, dx = \tilde{E} \int_{\mathbb{R}^3} \phi \partial_n \tilde{u}_n(0) A_i[\phi T_k(\bar{\phi}(0))] \, dx
\]
\[
- \tilde{E} \int_0^t \int_{\mathbb{R}^3} \phi \partial_n \tilde{u}_n A_i[\partial_j (T_k(\bar{\phi}) \tilde{u}_n)] \, dx \, ds
\]
\[
- \tilde{E} \int_0^t \int_{\mathbb{R}^3} \phi \partial_n \tilde{u}_n A_i[\phi (T_k(\bar{\phi}) \tilde{u}_n - T_k(\bar{\phi})) \, \text{div} \, \tilde{u}_n] \, dx \, ds
\]
\[
+ \tilde{E} \int_0^t \int_{\mathbb{R}^3} \partial_i \tilde{u}_n \tilde{u}_n \tilde{u}_n \partial_j (\phi A_i[\phi T_k(\bar{\phi})]) \, dx \, ds
\]
\[
+ \nu \tilde{E} \int_0^t \int_{\mathbb{R}^3} \phi A_i[\phi T_k(\bar{\phi})] \Delta \tilde{u}_n \, dx \, ds
\]
\[
+ \tilde{E} \int_0^t \int_{\mathbb{R}^3} [a \tilde{\phi} \partial_n - (\lambda + \nu) \text{div} \tilde{u}_n] \partial_i (\phi A_i[\phi T_k(\bar{\phi})]) \, dx \, ds
\]
\[
= \tilde{E} \sum_{k=1}^6 J_k, \quad i = 1, 2, 3.
\]

where $T_k$, as defined above, replaces $b$ in the definition of the renormalized equation given by (3.14).

**Remark 3.12.** Notice that since the approximate quantities in (3.14) are only defined locally in space, to apply this globally defined operators $A_i$, it is essentially to pre-multiply our functions by some $\bar{\phi} \in C_c^\infty(\mathbb{R})$.

Also, we observe that since our noise term is a martingale, it vanishes when we take its expectation, as martingales are constant on average.
Now notice that by integration by parts and the use of the properties of the operators $A_i$ and $R_{ij} = \partial_i A_j$, we may rewrite $J_2, J_4, J_5$ and $J_6$ so that (3.18) becomes:

$$
\mathbb{E} \int_0^t \int_{\mathbb{R}^3} [a\tilde{\varphi}_n - (\lambda + 2\nu)\text{div}\tilde{u}_n] \phi \tilde{T}_k(\tilde{\varphi}_n) \, dx \, ds
= \mathbb{E} \int_{\mathbb{R}^3} \phi \tilde{\varphi}_n \tilde{u}_n^i A_i [\phi \tilde{T}_k(\tilde{\varphi}_n)] \, dx
- \mathbb{E} \int_{\mathbb{R}^3} \phi \tilde{\varphi}_n \tilde{u}_n^i(0) A_i [\phi \tilde{T}_k(\tilde{\varphi}_n(0))] \, dx + \nu \mathbb{E} \int_0^t \int_{\mathbb{R}^3} \phi \tilde{u}_n^i \tilde{T}_k(\tilde{\varphi}_n) \partial_i \phi \, dx \, ds
- \mathbb{E} \int_{\mathbb{R}^3} [a\tilde{\varphi}_n - (\lambda + \nu)\text{div}\tilde{u}_n] A_i [\phi \tilde{T}_k(\tilde{\varphi}_n)] \partial_i \phi \, dx \, ds

(3.19)
$$

$$
+ \mathbb{E} \int_0^t \int_{\mathbb{R}^3} \phi \tilde{\varphi}_n \tilde{u}_n^i A_i [\phi \tilde{T}_k(\tilde{\varphi}_n) - T_k(\tilde{\varphi}_n)] \text{div}\tilde{u}_n \, dx \, ds
+ \mathbb{E} \int_0^t \int_{\mathbb{R}^3} \tilde{u}_n^i (R_{ij} [\phi \tilde{\varphi}_n \tilde{u}_n^j]) \phi \tilde{T}_k(\tilde{\varphi}_n) - \phi \tilde{\varphi}_n \tilde{u}_n^j R_{ij} [\phi \tilde{T}_k(\tilde{\varphi}_n)] \, dx \, ds
+ \mathbb{E} \int_0^t \int_{\mathbb{R}^3} \tilde{u}_n^i (A_i [\phi \tilde{\varphi}_n \tilde{u}_n^j] T_k(\tilde{\varphi}_n) \partial_j \phi - \tilde{\varphi}_n \tilde{u}_n^j A_i [\phi \tilde{T}_k(\tilde{\varphi}_n)] \partial_j \phi) \, dx \, ds
=: \mathbb{E} \sum_{k=1}^7 K_k, \quad i = 1, 2, 3.
$$

Remark 3.13. If we set the left-hand side of (3.19) to $\mathbb{E} I_0$, then we point the reader to the difference in the viscosity constant in $I_0$ and $I_4$. Similarly for the limit processes, we obtain

$$
\mathbb{E} \int_0^t \int_{\mathbb{R}^3} [a\tilde{\varphi} - (\lambda + 2\nu)\text{div}\tilde{u}] \phi \tilde{T}_k(\tilde{\varphi}) \, dx \, ds = \mathbb{E} \int_{\mathbb{R}^3} \phi \tilde{\varphi} \tilde{u}^i A_i [\phi \tilde{T}_k(\tilde{\varphi})] \, dx
- \mathbb{E} \int_{\mathbb{R}^3} \phi \tilde{\varphi} \tilde{u}^i(0) A_i [\phi \tilde{T}_k(\tilde{\varphi}(0))] \, dx + \nu \mathbb{E} \int_0^t \int_{\mathbb{R}^3} \phi \tilde{u}^i \tilde{T}_k(\tilde{\varphi}) \partial_i \phi \, dx \, ds
- \mathbb{E} \int_{\mathbb{R}^3} [a\tilde{\varphi} - (\lambda + \nu)\text{div}\tilde{u}] A_i [\phi \tilde{T}_k(\tilde{\varphi})] \partial_i \phi \, dx \, ds

(3.20)
$$

$$
+ \mathbb{E} \int_0^t \int_{\mathbb{R}^3} \phi \tilde{\varphi} \tilde{u}^i A_i [\phi \tilde{T}_k(\tilde{\varphi}) - T_k(\tilde{\varphi})] \text{div}\tilde{u} \, dx \, ds
+ \mathbb{E} \int_0^t \int_{\mathbb{R}^3} \tilde{u}^i (R_{ij} [\phi \tilde{\varphi} \tilde{u}^j]) \phi \tilde{T}_k(\tilde{\varphi}) - \phi \tilde{\varphi} \tilde{u}^j R_{ij} [\phi \tilde{T}_k(\tilde{\varphi})] \, dx \, ds
+ \mathbb{E} \int_0^t \int_{\mathbb{R}^3} \tilde{u}^i (A_i [\phi \tilde{\varphi} \tilde{u}^j] T_k(\tilde{\varphi}) \partial_j \phi - \tilde{\varphi} \tilde{u}^j A_i [\phi \tilde{T}_k(\tilde{\varphi})] \partial_j \phi) \, dx \, ds
=: \mathbb{E} \sum_{k=1}^7 K_k, \quad i = 1, 2, 3.
$$

where a ‘bar’ above a function represents the limit of the corresponding approximate sequence of functions.

Lemma 3.14. Let $\phi(x), \tilde{\phi}(x) \in C_c^\infty(\mathbb{R}^3)$. Then the strong convergence

$$
R[\phi \tilde{\varphi}_n \tilde{u}_n^i] \tilde{T}_k(\tilde{\varphi}_n) - \phi \tilde{\varphi}_n \tilde{u}_n^i R[\phi \tilde{T}_k(\tilde{\varphi}_n)] \to R[\phi \tilde{\varphi} \tilde{u}^i] \tilde{T}_k(\tilde{\varphi}) - \phi \tilde{\varphi} \tilde{u}^i R[\phi \tilde{T}_k(\tilde{\varphi})]
$$
exists in \( L^2(\hat{\Omega} \times (0,T); W^{-1,2}(\mathbb{R}^3)) \) where \( \mathcal{R} := \mathcal{R}_{ij} \).

**Proof.** See [5, Sect. 6.1] or the deterministic counterpart in [28, Eq. 7.5.23]. \( \square \)

Now by using the weak-strong pair: (3.17) and Lemma 3.14, we can pass to the limit in the crucial term \( I_6 \) to get \( \tilde{\mathbb{E}} I_6 \to \tilde{\mathbb{E}} K_6 \).

All other terms can be treated in a similar manner as in [5, Sect. 6.1] keeping in mind that the terms involving derivatives and cutoff functions are of lower order and hence easier to handle. In particular, we obtain the convergence \( \tilde{\mathbb{E}} I_7 \to \tilde{\mathbb{E}} K_7 \) by observing that \( R = \partial_j A_i \).

We have therefore shown that

\[
\lim_{n \to 0} \tilde{\mathbb{E}} \int_Q \left[ a\tilde{\rho}_n^{\gamma} - (\lambda + 2\nu)\text{div} \tilde{u}_n \right] \phi \phi T_k(\tilde{\rho}_n) \, dx \, dt = \tilde{\mathbb{E}} \int_Q \left[ a\tilde{p} - (\lambda + 2\nu)\text{div} \tilde{u} \right] \phi \phi T_k(\tilde{\rho}) \, dx \, dt
\]

(3.21)

### 3.4. Identification of the pressure limit.

Showing that indeed \( \tilde{\rho} = \tilde{\rho}^{\gamma} \) or equivalently that \( \tilde{\rho}_n \to \tilde{\rho} \) strongly in \( L^p(\hat{\Omega} \times Q) \) for all \( p \in [1, \gamma + \Theta] \) follows Feireisl’s approach via the use of the so-called oscillation defect measure. This is a purely deterministic argument even in our stochastic settings since it relies on the renormalized continuity equation. To avoid repetition, we refer the reader to [28, Sect. 7.3.7.3] or [11]. To confirm that it indeed applies in the stochastic setting, the reader may also refer to [5, Sect. 6.2 and 6.3].

We now conclude with the following lemma which completes the proof of Theorem 2.4.

**Lemma 3.15.** \( \{\hat{\Omega}, \hat{\mathcal{F}}, (\hat{\mathcal{F}}_t)_{t \geq 0}, \hat{\mathbb{P}}, \hat{\rho}, \hat{u}, \hat{W}\} \) is a finite energy weak martingale solution of \( (1.4) \) with initial law \( \Lambda \). Furthermore, \( (1.4)_1 \) is satisfied in the renormalized sense.

### 4. Proof of Theorem 2.6

For every \( \varepsilon > 0 \), let assume there exits a finite energy weak martingale solution of Eq. (1.4) given by

\[
\{(\Omega^\varepsilon, \mathcal{F}^\varepsilon, (\mathcal{F}_t^\varepsilon), \mathbb{P}^\varepsilon), \rho^\varepsilon, u^\varepsilon, W^\varepsilon\}.
\]

Then by setting \( \bar{\rho} = 1 \) and \( a = \frac{1}{\varepsilon} \) in (2.4), and applying Taylor expansion to the function \( f(q) = q^{\gamma} \) around \( q = 1 \), we get

\[
\mathbb{E} \left[ \int_{\mathbb{R}^3} \left( \frac{|q^\varepsilon(0)|^2}{2q^\varepsilon(0)} + H(q^\varepsilon(0)) \right) \, dx \right]^p \leq c_{p,T}
\]

where

\[
\int L^\gamma L^\frac{2\gamma}{2\gamma - 2} \left\| \frac{|q^\varepsilon|^2}{2q^\varepsilon} + \frac{\gamma^{\gamma-2}}{2\varepsilon^2}(q^\varepsilon - 1)^2 \right\|_{L^1(\mathbb{R}^3)}^p \, d\Lambda(q^\varepsilon, q^\varepsilon) \leq c_{p,T}
\]
for \( z \in [\rho, 1] \) or \( z \in [1, \rho] \) and \( s \) where we have used initial data in Theorem 2.4. Similar to Section 3, we can now collect the following uniform (in \( \varepsilon \)) bounds

\[
\begin{align*}
\varphi_\varepsilon &\in L^p(\Omega; L^\infty(0, T; L^{\min(2, \gamma)}(\mathbb{R}^3))), \\
\nabla \mathbf{u}_\varepsilon &\in L^p(\Omega; L^2(0, T; L^2(\mathbb{R}^3))), \\
\sqrt{\varrho}_\varepsilon \mathbf{u}_\varepsilon &\in L^p(\Omega; L^\infty(0, T; L^2(\mathbb{R}^3))), \\
\varrho_\varepsilon \mathbf{u}_\varepsilon &\in L^p(\Omega; L^\infty(0, T; L^{\frac{2\gamma}{\gamma-1}}(\mathbb{R}^3))), \\
\varrho_\varepsilon \mathbf{u}_\varepsilon \otimes \mathbf{u}_\varepsilon &\in L^p(\Omega; L^2(0, T; L^{\frac{\gamma}{\gamma-1}}(\mathbb{R}^3))),
\end{align*}
\]

(4.1)

where \( \varphi_\varepsilon := \frac{\varrho_\varepsilon - 1}{\varepsilon} \) and

\[
\varrho_\varepsilon \to 1 \quad \text{in} \ L^p(\Omega; L^\infty(0, T; L^\gamma_{\text{loc}}(\mathbb{R}^3))).
\]

(4.2)

cf. (3.3) (with \( \widetilde{\varrho} = 1 \)), (3.7) and [3] eqn. 3.6.

### 4.1. Acoustic wave equation

Let \( \Delta^{-1} \) represent the inverse of the Laplace operator on \( \mathbb{R}^3 \) and let \( \mathcal{Q} = \nabla \Delta^{-1} \text{div} \) and \( \mathcal{P} \) be, respectively, the gradient and solenoidal parts according to Helmholtz decomposition. Then referring again to [3], we observe that by setting \( \varphi_\varepsilon = \frac{\varrho_\varepsilon - 1}{\varepsilon} \) and \( \text{Id} = \mathcal{Q} + \mathcal{P} \), we derive from equation (1.4):

\[
\begin{align*}
\varepsilon d\varphi + \text{div} \mathcal{Q}(\varrho_\varepsilon \mathbf{u}_\varepsilon)dt &= 0, \\
\varepsilon \Phi(\varrho_\varepsilon, \varrho_\varepsilon \mathbf{u}_\varepsilon)dt &= \varepsilon d\mathcal{Q}(\varrho_\varepsilon \mathbf{u}_\varepsilon) - \varepsilon \mathbf{F}_\varepsilon dt,
\end{align*}
\]

(4.3)

where

\[
\mathbf{F}_\varepsilon = \text{div} \mathcal{Q}(\varrho_\varepsilon \mathbf{u}_\varepsilon \otimes \mathbf{u}_\varepsilon) - \nu \Delta \mathcal{Q} \mathbf{u}_\varepsilon - (\lambda + \nu) \nabla \text{div} \mathbf{u}_\varepsilon + \frac{1}{\varepsilon^2} \nabla [\varrho_\varepsilon^\gamma - 1 - \gamma(\varrho_\varepsilon - 1)].
\]

Now let us observe that from (4.1) and the continuity of \( \mathcal{Q} \), we have that

\[
\text{div} \mathcal{Q}(\varrho_\varepsilon \mathbf{u}_\varepsilon \otimes \mathbf{u}_\varepsilon) \in L^p(\Omega; L^2(0, T; W_{\text{loc}}^{1, \frac{\gamma}{\gamma-1}}(\mathbb{R}^3)))
\]

(4.4)

independently of \( \varepsilon \). And that

\[
\nu \Delta \mathcal{Q} \mathbf{u}_\varepsilon + (\lambda + \nu) \nabla \text{div} \mathbf{u}_\varepsilon \in L^p(\Omega; L^2(0, T; W_{\text{loc}}^{-1, 2}(\mathbb{R}^3)))
\]

(4.5)

uniformly in \( \varepsilon \) by virtue of (4.1). Lastly, the choice of \( a = \frac{1}{\varepsilon^2} \) and \( \widetilde{\varrho}_\varepsilon = 1 \) in the pressure potential (2.6) of the energy estimate (2.6) and Taylor’s theorem means that for \( s := \min\{2, \gamma\} > 1 \),

\[
\frac{1}{\varepsilon^2} \nabla [\varrho_\varepsilon^\gamma - 1 - \gamma(\varrho_\varepsilon - 1)] \in L^p(\Omega; L^\infty(0, T; W_{\text{loc}}^{-1, s}(\mathbb{R}^3))).
\]

(4.6)

uniformly in \( \varepsilon \). cf. (2.5) for \( \widetilde{\varrho} = 1 \) and (1.1). By combining (4.1), (4.5) and (4.6) with the embeddings \( W_{\text{loc}}^{-1, \frac{\gamma}{\gamma-1}}(B_r) \hookrightarrow W_{\text{loc}}^{-1, 2}(B_r) \) and \( W_{\text{loc}}^{-1, s}(B_r) \hookrightarrow W_{\text{loc}}^{-1, 2}(B_r) \), where \( B_r \) is a ball of radius \( r > 0 \), it holds that for \( l > 5/2 \),

\[
\mathbf{F}_\varepsilon \in L^p(\Omega; L^2(0, T; W_{\text{loc}}^{-l, 2}(\mathbb{R}^3)))
\]

(4.7)

uniformly in \( \varepsilon \).
4.2. Compactness. To explore compactness for the acoustic equation, let first define the path space \( \chi = \chi_\varepsilon \times \chi_u \times \chi_{\varepsilon u} \times \chi_W \) where
\[
\chi_\varepsilon = \mathcal{C}_\omega \left( [0, T]; L^\infty_{\text{loc}}(\mathbb{R}^3) \right), \\
\chi_u = \left( L^2(0, T; W_{\text{loc}}^{1,2}(\mathbb{R}^3)), \omega \right), \\
\chi_{\varepsilon u} = \mathcal{C}_\omega \left( [0, T]; L^\infty_{\text{loc}}(\mathbb{R}^3) \right), \\
\chi_W = C \left( [0, T]; \mathcal{U}_0 \right),
\]
and let
\[
(1) \ \mu_0 \varepsilon \text{ be the law of } \varrho_\varepsilon \text{ on the space } \chi_\varepsilon, \\
(2) \ \mu_u \varepsilon \text{ be the law of } u_\varepsilon \text{ on } \chi_u, \\
(3) \ \mu_{P(\varrho_\varepsilon u_\varepsilon)} \text{ be the law of } P(\varrho_\varepsilon u_\varepsilon) \text{ on the space } \chi_{\varepsilon u}, \\
(4) \ \mu_W \varepsilon \text{ be the law of } W \text{ on the space } \chi_W, \\
(5) \ \mu^\varepsilon \varepsilon \text{ be the joint law of } \varrho_\varepsilon, u_\varepsilon, P(\varrho_\varepsilon u_\varepsilon), \text{ and } W \text{ on the space } \chi.
\]
Then the following lemma, the proof of which is similar to \cite[Corollary 3.7]{3}, holds true.

**Lemma 4.1.** The sets \( \{ \mu^\varepsilon; \varepsilon \in (0, 1) \} \) is tight on \( \chi \).

Now similar to Proposition 4.3 we apply the Jakubowski–Skorokhod representation theorem \cite{20} to get the following proposition.

**Proposition 4.2.** There exists a subsequence \( \mu^\varepsilon \) (not relabelled), a probability space \( (\tilde{\Omega}, \tilde{\mathcal{F}}, \tilde{P}) \) with \( \chi \)-valued Borel measurable random variables \( (\tilde{\varrho}_\varepsilon, \tilde{u}_\varepsilon, \tilde{q}_\varepsilon, \tilde{W}_\varepsilon), n \in \mathbb{N} \), and \( (\tilde{\varrho}, \tilde{u}, \tilde{q}, \tilde{W}) \) such that
- the law of \( (\tilde{\varrho}_\varepsilon, \tilde{u}_\varepsilon, \tilde{q}_\varepsilon, \tilde{W}_\varepsilon) \) is given by \( \mu^\varepsilon \), \( \varepsilon \in (0, 1) \),
- the law of \( (\tilde{\varrho}, \tilde{u}, \tilde{q}, \tilde{W}) \), denoted by \( \mu \) is a Random measure,
- \( (\tilde{\varrho}_\varepsilon, \tilde{u}_\varepsilon, \tilde{q}_\varepsilon, \tilde{W}_\varepsilon) \) converges \( \tilde{P} \)-a.s to \( (\tilde{\varrho}, \tilde{u}, \tilde{q}, \tilde{W}) \) in the topology of \( \chi \).

To extend this new probability space \( (\tilde{\Omega}, \tilde{\mathcal{F}}, \tilde{P}) \) into a stochastic basis, we endow it with the \( \tilde{P} \)-augmented canonical filtrations for \( (\tilde{\varrho}_\varepsilon, \tilde{u}_\varepsilon, \tilde{W}_\varepsilon) \) and \( (\tilde{\varrho}, \tilde{u}, \tilde{W}) \), respectively, by setting
\[
\tilde{\mathcal{F}}_t^\varepsilon = \sigma \left( \sigma(\mathbf{r}_t \tilde{\varrho}_\varepsilon, \mathbf{r}_t \tilde{u}_\varepsilon, \mathbf{r}_t \tilde{W}_\varepsilon) \cup \{ N \in \mathcal{F}; \tilde{P}(N) = 0 \} \right), \quad t \in [0, T], \\
\tilde{\mathcal{F}}_t = \sigma \left( \sigma(\mathbf{r}_t \tilde{\varrho}, \mathbf{r}_t \tilde{u}, \mathbf{r}_t \tilde{W}) \cup \{ N \in \mathcal{F}; \tilde{P}(N) = 0 \} \right), \quad t \in [0, T],
\]
where \( \mathbf{r}_t \) is the continuous function defined in \( \text{(5.15)} \) above adapted to the spaces defined in this section.

4.3. Identification of the limit. We now verify that on this new probability space, our new processes
\[
[ (\tilde{\Omega}, \tilde{\mathcal{F}}, (\tilde{\mathcal{F}}_t^\varepsilon), \tilde{P}), \tilde{\varrho}_\varepsilon, \tilde{u}_\varepsilon, \tilde{W}_\varepsilon ] \text{ and } [ (\tilde{\Omega}, \tilde{\mathcal{F}}, (\tilde{\mathcal{F}}_t), \tilde{P}), \tilde{\varrho}, \tilde{u}, \tilde{W} ]
\]
are indeed finite energy weak martingale solutions and a weak martingale solution respectively for Eqs. \( \text{(1.4)} \) and \( \text{(1.3)} \).

**Proposition 4.3.** \( [ (\tilde{\Omega}, \tilde{\mathcal{F}}, (\tilde{\mathcal{F}}_t^\varepsilon)_{t \geq 0}, \tilde{P}), \tilde{\varrho}_\varepsilon, \tilde{u}_\varepsilon, \tilde{W}_\varepsilon ] \) is a finite energy weak martingale solution of Eq. \( \text{(1.4)} \) with initial law \( \Lambda_\varepsilon \) for \( \varepsilon \in (0, 1) \).

The proof of this proposition is similar to \cite[Proposition 3.10]{3}.
Consequently, the uniform bounds shown in (1.5), (4.8) and (1.7) earlier hold for these corresponding random processes on this new space. In particular, we have

\[
\begin{align*}
\hat{\varphi}_\varepsilon &\in L^p \left( \Omega; L^\infty(0, T; L^{\min\{2, \gamma\}}(\mathbb{R}^3)) \right), \\
\hat{F}_\varepsilon &\in L^p \left( \Omega; L^2(0, T; W^{-l, 2}_{\text{loc}}(\mathbb{R}^3)) \right), \\
\tilde{u}_\varepsilon &\in L^p \left( \Omega; L^2(0, T; W^{1, 2}_{\text{loc}}(\mathbb{R}^3)) \right), \\
\hat{\varphi}_\varepsilon \tilde{u}_\varepsilon &\in L^p(\Omega; L^\infty(0, T; L^{2, 2}_{\text{loc}}(\mathbb{R}^3)))
\end{align*}
\]

holds uniformly in \( \varepsilon \) for \( p \in [1, \infty) \) and where \( l > 5/2 \), \( \hat{\varphi}_\varepsilon = \frac{\hat{\varphi}_\varepsilon - 1}{\varepsilon} \) and

\[
\hat{F}_\varepsilon = \text{div} Q(\hat{\varphi}_\varepsilon \tilde{u}_\varepsilon \otimes \tilde{u}_\varepsilon) - \nu \Delta Q \tilde{u}_\varepsilon - (\lambda + \nu) \nabla \text{div} \tilde{u}_\varepsilon + \frac{1}{\varepsilon^2} \nabla [\hat{\varphi}_\varepsilon - 1 - \gamma(\hat{\varphi}_\varepsilon - 1)]
\]

We now verify that indeed the limit process satisfies Definition 2.3. This will complete the proof of Theorem 2.6.

**Remark 4.7.** Henceforth, we write ‘\( \lesssim \)’ for ‘\( \leq \)’ and ‘\( \simeq \)’ for ‘\( = \)’ where \( c \), which may vary from line to line is some universal constant that is independent of \( \varepsilon \) but may depend on other variables.

**Proposition 4.8.** The strong convergence below holds.

\[
\begin{align*}
Q(\hat{\varphi}_\varepsilon \tilde{u}_\varepsilon) &\to 0 \quad \text{in} \quad L^2(0, T; L^{2, 2}_{\text{loc}}(\mathbb{R}^3)) \quad \hat{\varepsilon} - \text{a.s.}
\end{align*}
\]
Proof. Let define the function \( \tilde{\Psi}_\varepsilon = \Delta^{-1} \text{div}(\tilde{\varphi}_\varepsilon \tilde{u}_\varepsilon) \) such that \( \nabla \tilde{\Psi}_\varepsilon = Q(\tilde{\varphi}_\varepsilon \tilde{u}_\varepsilon) \). Then equation (4.3) becomes

\[
\varepsilon \frac{d}{dt}(\tilde{\varphi}_\varepsilon) + \Delta \tilde{\Psi}_\varepsilon dt = 0,
\]

\[
\varepsilon \frac{d}{dt} \nabla \tilde{\Psi}_\varepsilon + \gamma \nabla \tilde{\varphi}_\varepsilon dt = \varepsilon \tilde{F}_\varepsilon dt + \varepsilon Q(\tilde{\varphi}_\varepsilon \tilde{u}_\varepsilon) d\tilde{W}_\varepsilon.
\]

We however observe that Eq. (4.12) is equivalent to

\[
\varepsilon \frac{d}{dt}(\tilde{\varphi}_\varepsilon) + \Delta \tilde{\Psi}_\varepsilon dt = 0,
\]

where the usual wave operator

\[
A = \begin{bmatrix}
0 & -\text{div} \\
\gamma \nabla & 0
\end{bmatrix}
\]

is an infinitesimal generator of a strongly continuous semigroup \( S(\cdot) = \exp(A \cdot) \). See for example [8]. Also since \( \Phi := \Phi(\tilde{\varphi}, \tilde{u}) \) is the Hilbert–Schmidt operator and equation (4.12) is satisfied weakly in the probabilistic sense, it follows that this weak solution is also a mild solution. See for example [7, Theorem 6.5]. As such after rescaling, we obtain the mild equation

\[
S(t) \left[ \begin{array}{c}
\tilde{\varphi}_0 \\
\nabla \tilde{\Psi}_0
\end{array} \right] = \left[ \begin{array}{c}
\tilde{\varphi} \\
\nabla \tilde{\Psi}
\end{array} \right] (t)
\]

where the semigroup \( S(t) \) is such that

\[
d(\tilde{\varphi}) + \Delta \tilde{\Psi} dt = 0,
\]

\[
d \nabla \tilde{\Psi} + \gamma \nabla \tilde{\varphi} dt = 0,
\]

\( \tilde{\varphi}(0) = \tilde{\varphi}_0; \quad \nabla \tilde{\Psi}(0) = \nabla \tilde{\Psi}_0. \)

Using Fourier transforms (in space), we obtain solution of Eq. (4.17) which is given by the pair

\[
\nabla \tilde{\Psi}(t,x) = \frac{e^{i \sqrt{-\gamma} \Delta t}}{2} \left( \nabla \tilde{\Psi}_0(x) - \frac{i \sqrt{\gamma}}{\sqrt{-\Delta}} \tilde{\varphi}_0(x) \right) + \frac{e^{-i \sqrt{-\gamma} \Delta t}}{2} \left( \nabla \tilde{\Psi}_0(x) + \frac{i \sqrt{\gamma}}{\sqrt{-\Delta}} \tilde{\varphi}_0(x) \right),
\]

\[
\tilde{\varphi}(t,x) = \frac{e^{i \sqrt{-\Delta} \Delta t}}{2} \left( \frac{i \sqrt{-\Delta}}{\sqrt{\gamma}} \nabla \tilde{\Psi}_0(x) + \tilde{\varphi}_0(x) \right) - \frac{e^{-i \sqrt{-\Delta} \Delta t}}{2} \left( \frac{i \sqrt{-\Delta}}{\sqrt{\gamma}} \nabla \tilde{\Psi}_0(x) - \tilde{\varphi}_0(x) \right).
\]

The lemma below is crucial to the proof of Proposition 4.8 and is an adaptation of [31] Lemma 2.2 to our setting. cf. [12] Lemma 3.1.
Lemma 4.9. Let \( \phi(x) \in C_c^\infty(\mathbb{R}^3) \), we have
\[
\int_\mathbb{R} \| e^{i \sqrt{-1} \Delta t} [v \phi] \|_{L^2(\mathbb{R}^3)}^2 \, dt \leq c(\phi) \| v \|_{L^2(\mathbb{R}^3)}^2
\]
for any \( v \in L^2(\mathbb{R}^3) \).

Proof. For simplicity, we assume that \( \gamma = 1 \). General \( \gamma > 1 \) will then follow by rescaling \( \delta \) below.

Using Plancherel’s theorem in \( t \) and \( x \), we have that
\[
\int_\mathbb{R} \| e^{i \sqrt{-1} \Delta t} [v \phi] \|_{L^2(\mathbb{R}^3)}^2 \, dt = c(\pi) \int_\mathbb{R} \int_{\mathbb{R}^3} \left| \int_{\{ \tau = |\eta| \}} \hat{\phi} (\xi - \eta) \delta(\tau - |\eta|) \hat{v} (\eta) \, d\eta \right|^2 \, d\xi \, d\tau
\]
\[
= c(\pi) \int_\mathbb{R} \int_{\mathbb{R}^3} \left( \int_{\{ \tau = |\eta| \}} |\hat{\phi} (\xi - \eta)| \, dS_\eta \right)^2 \, d\xi \, d\tau
\]
\[
\leq c(\pi) \int_\mathbb{R} \int_{\mathbb{R}^3} \left( \int_{\{ \tau = |\eta| \}} |\hat{\phi} (\xi - \eta)| \, dS_\eta \right) \left( \int_{\{ \tau = |\eta| \}} |\hat{\phi} (\xi - \eta)| \, dS_\eta \right) \, d\xi \, d\tau
\]
\[
\leq c(\pi, \phi) \int_\mathbb{R} \int_{\mathbb{R}^3} |\hat{\phi} (\xi - \eta)| \, dS_\eta \, d\xi \, d\tau
\]
\[
\leq c(\pi, \phi) \int_\mathbb{R} \int_{\mathbb{R}^3} |\hat{\phi} (\xi - \eta)| \, dS_\eta \, d\xi \, d\tau \leq c(\pi, \phi) \| v \|_{L^2(\mathbb{R}^3)}^2
\]
where we have used the Cauchy-Schwartz inequality.

Moving on, we now consider a smooth cut-off function (with expanding support) \( \eta_r \in C_c^\infty (B_{2r}) \) with \( \eta_r \equiv 1 \) in \( B_r \) for \( r > 0 \) and zero elsewhere. We now mollify the product of this cut-off function and our functions in (4.12) by means of spatial convolution with the standard mollifier. That is, if \( v \) is one of the functions in (4.12), we set
\[
v^\kappa = (\eta_r v) \ast \varphi^\kappa
\]
where \( \varphi^\kappa \) is the standard mollifier. This we do to ensure that the regularized functions are globally integrable. First off, we note that since (4.8) holds uniformly in \( \epsilon \), for an arbitrary small \( \delta > 0 \), we can find a \( \kappa(\delta) \) such that
\[
(4.19) \quad \hat{E} \sup_{t \in [0, T]} \| (\hat{\varphi}^\kappa \hat{u}_v) - (\hat{\varphi}^\kappa \hat{u}_c) \|_{L^{2, \infty}(B)} \leq \delta
\]
for any \( 1 \leq p < \infty \) and an arbitrary ball \( B \subset B_r \) for \( r > 0 \). Then using (4.10), (4.13) and Lemma 4.9, we obtain
\[
(4.20) \quad \hat{E} \left\| S(t) \left[ \begin{array}{c} \varphi^\kappa_0 \\ \nabla \Psi^\kappa_0 \end{array} \right] \right\|_{L^2(B \times \mathbb{R}^3)}^2 \leq c_{h, \gamma} \hat{E} \left\| \left[ \begin{array}{c} \varphi^\kappa_0 \\ \nabla \Psi^\kappa_0 \end{array} \right] \right\|_{L^2(\mathbb{R}^3)}^2
\]
for any ball \( B \subset \mathbb{R}^3 \) and where in particular, the constant is independent of \( \kappa \). So by rescaling in time, i.e., setting \( s = \frac{t}{\epsilon} \) so that \( ds = \frac{dt}{\epsilon} \), we get
\[
(4.21) \quad \hat{E} \left\| S \left( \frac{t}{\epsilon} \right) \left[ \begin{array}{c} \varphi^\kappa_{c_0} (0) \\ \nabla \Psi^\kappa_{c_0} (0) \end{array} \right] \right\|_{L^2((0, T) \times B \times \mathbb{R}^3)}^2 \leq \hat{E} \left\| S \left( \frac{t}{\epsilon} \right) \left[ \begin{array}{c} \varphi^\kappa_{c_0} (0) \\ \nabla \Psi^\kappa_{c_0} (0) \end{array} \right] \right\|_{L^2(\mathbb{R}^3)}^2
\]
\[
\leq \epsilon \hat{E} \left\| \left[ \begin{array}{c} \varphi^\kappa_{c_0} (0) \\ \nabla \Psi^\kappa_{c_0} (0) \end{array} \right] \right\|_{L^2(\mathbb{R}^3)}^2
\]
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with a constant that is independent of ε. Now by the continuity of Q, and the initial law defined in the statement of Theorem 2.4, we conclude that

\begin{equation}
\tilde{\mathcal{E}} \left\| S \left( \frac{t}{\varepsilon} \right) \left[ \frac{\tilde{\varphi}^\kappa(0)}{\nabla \tilde{\Psi}^\kappa(0)} \right] \right\|^2_{L^2((0,T) \times B)} \lesssim \varepsilon \tilde{\mathcal{E}} \left( \left\| \tilde{\varphi}^\kappa(0) \right\|^2_{L^{\min(2,\gamma)}(\mathbb{R}^3)} + \left\| \tilde{q}^\kappa(0) \right\|^2_{L^{\frac{2}{\gamma+1}}(\mathbb{R}^3)} \right) \leq \varepsilon \kappa, M.
\end{equation}

Similarly we have that for any ball \( B \subset \mathbb{R}^3 \),

\begin{equation}
\tilde{\mathcal{E}} \left\| \int_0^t S \left( \frac{t-s}{\varepsilon} \right) \tilde{F}^\kappa ds \right\|^2_{L^2((0,T) \times B)} \leq \tilde{\mathcal{E}} \left\| S \left( \frac{t-s}{\varepsilon} \right) \tilde{F}^\kappa \right\|^2_{L^2((0,0) \times (0,T) \times B)}
\end{equation}

\begin{equation}
\leq \tilde{\mathcal{E}} \left\| S \left( \frac{t}{\varepsilon} \right) S \left( \frac{-s}{\varepsilon} \right) \tilde{F}^\kappa \right\|^2_{L^2(\mathbb{R} \times (0,T) \times B)}
\leq \varepsilon c_\kappa \tilde{\mathcal{E}} \left\| \tilde{F}^\kappa \right\|^2_{L^2((0,T) \times B)}
\approx \varepsilon \tilde{\mathcal{E}} \left\| \tilde{F}^\kappa \right\|^2_{L^2((0,T) \times \mathbb{R}^3)} \leq \varepsilon \gamma, \kappa
\end{equation}

Where we have used Jensen’s inequality and Fubini’s theorem in the first inequality, extended (0, t) to \( \mathbb{R} \) and used the semigroup property in the second inequality, applied similar reasoning as in (4.21) in the third inequality and then used that \( (S(t))_t \) is a group of isometries on \( L^2 \) (extended by zero outside of the ball) in the last line above.

We have therefore obtained the following bounds

\begin{equation}
\tilde{\mathcal{E}} \left\| S \left( \frac{t}{\varepsilon} \right) \left[ \frac{\tilde{\varphi}^\kappa(0)}{\nabla \tilde{\Psi}^\kappa(0)} \right] \right\|^2_{L^2(0,T; L^2(B))} \lesssim \varepsilon,
\end{equation}

\begin{equation}
\tilde{\mathcal{E}} \left\| \int_0^t S \left( \frac{t-s}{\varepsilon} \right) \left[ \frac{0}{\tilde{F}^\kappa} \right] ds \right\|^2_{L^2(0,T; L^2(B))} \lesssim \varepsilon
\end{equation}

for any ball \( B \subset \mathbb{R}^3 \). Now let make the notation \( \tilde{\varphi}^\kappa(\xi) := q_i(\cdot, \tilde{\varphi}^\kappa(\cdot)) =: \tilde{\varphi}^{\kappa, \kappa} \). We notice that for a continuous function \( S(t) \) and a continuous operator \( Q \), the quantity \( S(t)Q\Phi \) is Hilbert–Schmidt if \( \Phi \) is Hilbert–Schmidt. As such, it follows
from Itô isometry that

\[
\mathbb{E} \left\| \int_0^t S\left( \frac{t-s}{\varepsilon} \right) \left[ \begin{array}{c} 0 \\ Q\tilde{\Phi}^\kappa_s \end{array} \right] d\tilde{W}_s(s) \right\|^2_{L^2((0,T) \times B)}
\]

\[
= \mathbb{E} \int_0^t \left\| S\left( \frac{t-s}{\varepsilon} \right) Q\tilde{\Phi}^\kappa_s \right\|^2_{L^2((0,T) \times B)} ds
\]

\[
= \mathbb{E} \int_0^t \sum_{i \in \mathbb{N}} \left\| S\left( \frac{t-s}{\varepsilon} \right) Q\tilde{g}_i^{\varepsilon,\kappa} \right\|^2_{L^2((0,T) \times B)} ds
\]

\[
\leq \int_0^T \sum_{i \in \mathbb{N}} \mathbb{E} \int_{\mathbb{R}} \left\| S\left( \frac{t-s}{\varepsilon} \right) Q\tilde{g}_i^{\varepsilon,\kappa} \right\|^2_{L^2(B)} ds dt
\]

where the above involved extending \( s \) from \( (0, t) \) to \( \mathbb{R} \) as well as Fubini’s theorem.

Now using the semigroup property and similar estimate as in equation (4.20) and (4.21), followed by the fact that the semigroup is an isometry with respect to the \( L^2 \)-norm, we get that

\[
\leq \int_0^T \sum_{i \in \mathbb{N}} \mathbb{E} \left\| Q\tilde{g}_i^{\varepsilon,\kappa} \right\|^2_{L^2(\mathbb{R}^3)} dt \leq \varepsilon \int_0^T \sum_{i \in \mathbb{N}} \mathbb{E} \left\| g_i^{\varepsilon,\kappa} \right\|^2_{L^2(\mathbb{R}^3)} dt \leq \varepsilon.
\]

The last inequality follows because the noise term is assumed to be compactly supported in \( \mathbb{R}^3 \). See (2.1). We have therefore shown that

\[
\mathbb{E} \left\| \int_0^t S\left( \frac{t-s}{\varepsilon} \right) Q\tilde{\phi}_s^\kappa d\tilde{W}_s(s) \right\|^2_{L^2((0,T) \times B)} \leq \varepsilon C_{h,\gamma,\kappa}
\]
where the constant is independent of $\varepsilon$. Combining this with the estimates from (4.24), we get from (4.15) that

$$
\mathbb{E}\left[\int_{0}^{t} S\left(\frac{t-s}{\varepsilon}\right) \nabla \Psi_{\varepsilon}(s) \right]_{L^{2}((0,T) \times B)}^{2} = \mathbb{E}\left[\int_{0}^{t} S\left(\frac{t-s}{\varepsilon}\right) \nabla \Psi_{\varepsilon}(s) \right]_{L^{2}((0,T) \times B)}^{2} + \mathbb{E}\left[\int_{0}^{t} S\left(\frac{t-s}{\varepsilon}\right) F_{\varepsilon} \right]_{L^{2}((0,T) \times B)}^{2} \\
\lesssim I_{1} + I_{2} + I_{3} \leq \varepsilon c_{h,\gamma,\kappa},
$$

where we have set

$$
I_{1} := \mathbb{E}\left[\int_{0}^{t} S\left(\frac{t-s}{\varepsilon}\right) \nabla \Psi_{\varepsilon}(s) \right]_{L^{2}((0,T) \times B)}^{2},
$$

$$
I_{2} := \mathbb{E}\left[\int_{0}^{t} S\left(\frac{t-s}{\varepsilon}\right) F_{\varepsilon} \right]_{L^{2}((0,T) \times B)}^{2},
$$

$$
I_{3} := \mathbb{E}\left[\int_{0}^{t} S\left(\frac{t-s}{\varepsilon}\right) Q \Phi dW_{\varepsilon,\gamma} \right]_{L^{2}((0,T) \times B)}^{2},
$$

So in particular,

$$
(4.25) \quad \mathbb{E}\|\nabla \Psi_{\varepsilon}^{c}(t)\|_{L^{2}((0,T) \times B)}^{2} \leq \varepsilon c_{h,\gamma,\kappa}
$$

holds for any ball $B \subset \mathbb{R}^{3}$. We also deduce from Eq. (4.19) together with the embedding $L^{\infty}(0, T; L^{r}(B)) \hookrightarrow L^{2}(0, T; L^{r}(B))$ where $r = \frac{2\gamma}{\gamma + 1}$, and the continuity of $Q$ that

$$
(4.26) \quad \mathbb{E}\|\nabla \Psi_{\varepsilon}^{c} - \nabla \Psi_{\varepsilon}\|_{L^{2}(0,T; L^{r}(B))}^{2} \leq c_{\delta}, \quad \mathbb{E}\|\Psi_{\varepsilon}^{c} - \Psi_{\varepsilon}\|_{L^{2}(0,T; L^{r}(B))}^{2} \leq c_{\delta},
$$

where $\delta$ is the arbitrarily constant from (4.19) which is independent of $\kappa$ and $\varepsilon$. As such, the constant $c_{\delta}$ can be made arbitrarily small for an arbitrary choice of $\delta$ so that

$$
\lim_{\kappa \downarrow 0} \mathbb{E}\|\nabla \Psi_{\varepsilon}^{c} - \nabla \Psi_{\varepsilon}\|_{L^{2}(0,T; L^{r}(B))}^{2} = 0, \quad r = \frac{2\gamma}{\gamma + 1}.
$$

Thus, it follows from (4.25) and the uniform bound (4.26) that we may exchange the order of taking limits in (4.26). As such for any ball $B \subset \mathbb{R}^{3}$, we have that

$$
0 \leq \lim_{\varepsilon \downarrow 0} \mathbb{E}\|\nabla \Psi_{\varepsilon}^{c}(t)\|_{L^{2}(0,T; L^{r}(B))}^{2} = \lim_{\kappa \downarrow 0} \lim_{\varepsilon \downarrow 0} \mathbb{E}\|\nabla \Psi_{\varepsilon}^{c}\|_{L^{2}(0,T; L^{r}(B))}^{2}
$$

$$
(4.27) \quad \leq 2 \lim_{\varepsilon \downarrow 0} \lim_{\kappa \downarrow 0} \mathbb{E}\|\nabla \Psi_{\varepsilon}^{c} - \nabla \Psi_{\varepsilon}\|_{L^{2}(0,T; L^{r}(B))}^{2} + 2 \lim_{\kappa \downarrow 0} \lim_{\varepsilon \downarrow 0} \mathbb{E}\|\nabla \Psi_{\varepsilon}^{c}\|_{L^{2}(0,T; L^{r}(B))}^{2}
$$

$$
\leq c \lim_{\kappa \downarrow 0} \lim_{\varepsilon \downarrow 0} \mathbb{E}\|\nabla \Psi_{\varepsilon}^{c} - \nabla \Psi_{\varepsilon}\|_{L^{2}(0,T; L^{r}(B))}^{2} + \lim_{\varepsilon \downarrow 0} \mathbb{E}\|\nabla \Psi_{\varepsilon}^{c}\|_{L^{2}(0,T; L^{r}(B))}^{2} = 0
$$

hence our claim. \hfill \square

Remark 4.10. We observe that by combining (4.10) and Proposition 4.8 we can only conclude that

$$
(4.28) \quad \tilde{\varphi}_{\varepsilon} \tilde{u}_{\varepsilon} \to \tilde{u} \quad \text{in} \quad L^{2}(0, T; W_{\text{loc}}^{-1,2}(\mathbb{R}^{3})),
$$

$\tilde{P}$–a.s.

However, we can improve this spatial regularity. We give this as part of the lemma below.
Lemma 4.11. Let \( \gamma > \frac{3}{2}, \ q < 6 \) and \( l > \frac{3}{2} \). Then for all \( r \in (\frac{3}{2}, 6) \), we have that

\[
\begin{align*}
(4.29) \quad \text{div}(\tilde{\varphi}_\varepsilon \tilde{u}_\varepsilon \otimes \tilde{u}_\varepsilon) & \to \text{div}(\tilde{u} \otimes \tilde{u}) \quad \text{in} \quad L^1(0, T; W^{-1,2}_{\text{div}}(B)), \\
(4.30) \quad \tilde{\varphi}_\varepsilon \tilde{u}_\varepsilon & \to \tilde{u} \quad \text{in} \quad L^2(0, T; L^r(B))
\end{align*}
\]

\( \tilde{P} - \text{a.s.} \) for any ball \( B \subset \mathbb{R}^3 \).

Proof. To avoid repetition, we refer the reader to [3, Proposition 3.13] for the proof of (4.29). However, we prove (4.30) below.

By using the identity \( P(\tilde{\varphi}_\varepsilon \tilde{u}_\varepsilon) = P(\tilde{\varphi}_\varepsilon - 1) \tilde{u}_\varepsilon + P \tilde{u}_\varepsilon \), the reverse triangle inequality and then the triangle inequality, we have that for any ball \( B \subset \mathbb{R}^3 \),

\[
\begin{align*}
\left\| P(\tilde{\varphi}_\varepsilon \tilde{u}_\varepsilon) \right\|_{L^2(0, T; L^r(B))} & \leq \left\| P(\tilde{\varphi}_\varepsilon - 1) \tilde{u}_\varepsilon + P \tilde{u}_\varepsilon - \tilde{u} \right\|_{L^2(0, T; L^r(B))} + \left\| P \tilde{u}_\varepsilon - \tilde{u} \right\|_{L^2(0, T; L^r(B))} \\
& \leq c \left\{ \left\| \tilde{\varphi}_\varepsilon - 1 \right\|_{L^\infty(0, T; L^{\min(2, \gamma)}(\mathbb{R}^3))} \left\| \tilde{u}_\varepsilon \right\|_{L^2(0, T; L^{\frac{6}{\gamma}}(B))} + \left\| P \tilde{u}_\varepsilon - \tilde{u} \right\|_{L^2(0, T; L^{\frac{6}{\gamma}}(B))} \right\} \\
& \to 0
\end{align*}
\]

where we have used (4.15), (4.3), (4.11) and the continuity of \( P \).

Combining this with Proposition 4.8 finishes the proof. \( \square \)

By combining (4.9) with Lemma 4.11 we finish the proof of Lemma 4.5. \( \square \)

The following lemma now completes the proof of Proposition 4.4.

Lemma 4.12. For all \( t \in [0, T] \) and \( \phi \in C^c_\infty(\mathbb{R}^3) \), we define

\[
N(t, q)_t = \sum_{k \in \mathbb{N}} \int_0^t |g_k(\varphi, q, \phi)|^2 ds, \quad N_k(t, q)_t = \int_0^t |g_k(\varphi, q, \phi)| ds.
\]

Then we have that for \( \varepsilon \in (0, 1) \)

\[
N(\tilde{\varphi}_\varepsilon, \tilde{\varphi}_\varepsilon \tilde{u}_\varepsilon)_t \to N(1, \tilde{u})_t \quad \tilde{P} - \text{a.s.},
\]

\[
N_k(\tilde{\varphi}_\varepsilon, \tilde{\varphi}_\varepsilon \tilde{u}_\varepsilon)_t \to N_k(1, \tilde{u})_t \quad \tilde{P} - \text{a.s.}
\]

as \( \varepsilon \to 0 \).

Proof. By Minkowski’s inequality, we have that

\[
\begin{align*}
\left\| \langle \Phi(\tilde{\varphi}_\varepsilon, \tilde{\varphi}_\varepsilon \tilde{u}_\varepsilon), \phi \rangle - \langle \Phi(1, \tilde{u}), \phi \rangle \right\|_{L^2(\mathcal{U}; \mathbb{R})} & = \left( \sum_{k \in \mathbb{N}} |\langle \Phi(\tilde{\varphi}_\varepsilon, \tilde{\varphi}_\varepsilon \tilde{u}_\varepsilon) - \Phi(1, \tilde{u}), (c_k), \phi \rangle|^2 \right)^{\frac{1}{2}} \\
& \leq c(\phi) \left( \sum_{k \in \mathbb{N}} \left\| \int_{\text{supp}(\phi)} (g_k(\tilde{\varphi}_\varepsilon, \tilde{\varphi}_\varepsilon \tilde{u}_\varepsilon) - g_k(1, \tilde{u})) dx \right\|^2 \right)^{\frac{1}{2}} \\
& \leq c \int_{\text{supp}(\phi)} \left( \sum_{k \in \mathbb{N}} |g_k(\tilde{\varphi}_\varepsilon, \tilde{\varphi}_\varepsilon \tilde{u}_\varepsilon) - g_k(1, \tilde{u})|^2 \right)^{\frac{1}{2}} dx
\end{align*}
\]

where \( \int_{\text{supp}(\phi)} f dx \) is the restriction of the integral of \( f \) to the support of \( \phi \).
Now let \( \mathbf{x} := (\hat{\varphi}, \hat{x}, \hat{\mathbf{u}}_t) \) and \( \mathbf{y} := (1, \hat{\mathbf{u}}) \) be vectors in \( \mathbb{R}^4 \) and define the line segment joining them by
\[
L(\mathbf{x}, \mathbf{y}) = \{ t\mathbf{x} + (1 + t)\mathbf{y} : 0 \leq t \leq 1 \}.
\]
Then by the Mean value inequality, we can find \( (\hat{\varphi}, \hat{q}) \in L(\mathbf{x}, \mathbf{y}) \) such that
\[
\int_{\text{supp}(\phi)} \left( \sum_{k \in \mathbb{N}} |g_k(\hat{\varphi}, \hat{x}, \hat{\mathbf{u}}_t) - g_k(1, \hat{\mathbf{u}})|^2 \right)^{\frac{1}{2}} \, dx
\leq \int_{\text{supp}(\phi)} \left( |(\hat{\varphi}, \hat{x}, \hat{\mathbf{u}}_t) - (1, \hat{\mathbf{u}})|^2 \sum_{k \in \mathbb{N}} \left| \nabla_{\hat{\varphi}, \hat{q}} g_k(\hat{\varphi}, \hat{q}) \right|^2 \right)^{\frac{1}{2}} \, dx
\leq c \left( \int_{\text{supp}(\phi)} |\hat{\varphi} - 1| \, dx + \int_{\text{supp}(\phi)} |\hat{x} - \hat{\mathbf{u}}_t| \, dx \right)
=: I_1 + I_2
\]
where we have used \([22,19] \) and \([19] \) Eq. 6.13.6 in the last inequality.

Hence by using the embeddings \( L^{\min(2, \gamma)} \hookrightarrow L^1 \) and \( L^r \hookrightarrow L^1 \), which holds true for any compact set or ball in \( \mathbb{R}^3 \) and where \( r \) is as defined in Lemma 4.11, we get that \( I_1 \to 0 \) and \( I_2 \to 0 \) for a.e. \((\omega, t) \in \tilde{\Omega} \times (0, T)\). This is due to (4.19) and (4.30).

Hence
\[
\langle \Phi(\hat{\varphi}, \hat{x}, \hat{\mathbf{u}}_t), \phi \rangle \to \langle \Phi(1, \hat{\mathbf{u}}), \phi \rangle \quad \text{in} \quad L_2(\tilde{\Omega}; \tilde{\mathbb{P}}) \times \mathcal{L} - a.e.
\]
which implies that
\[
N(\hat{\varphi}, \hat{x}, \hat{\mathbf{u}}_t) \to N(1, \hat{\mathbf{u}}) \quad \text{in} \quad L_2(\tilde{\Omega}; \tilde{\mathbb{P}}) \times \mathcal{L} - a.e.
\]
Similar argument holds for \( N_k(\hat{\varphi}, \hat{x}, \hat{\mathbf{u}}_t) \to N_k(1, \hat{\mathbf{u}}) \) \( \tilde{\mathbb{P}} - a.s. \) \( \blacksquare \)

Using Lemmata [15,16] and Lemma 4.12, we can now pass to the limit in equation \([3] \) Eq. 3.14-3.16 to get that:
\[
\begin{aligned}
\mathbb{E} h(\mathbf{r}, \mathbf{u}, \mathbf{r}, \hat{W}) \left[ M(1, \hat{\mathbf{u}}) \right]_{s,t} &= 0, \\
\mathbb{E} h(\mathbf{r}, \mathbf{u}, \mathbf{r}, \hat{W}) \left[ \left[ M(1, \hat{\mathbf{u}}) \right]^2 \right]_{s,t} - N(1, \hat{\mathbf{u}})_{s,t} &= 0, \\
\mathbb{E} h(\mathbf{r}, \mathbf{u}, \mathbf{r}, \hat{W}) \left[ \left[ M(1, \hat{\mathbf{u}}) \right] \hat{\beta}_k \right]_{s,t} - N(1, \hat{\mathbf{u}})_{s,t} &= 0.
\end{aligned}
\]
Equation (4.31) means that \( M(1, \hat{\mathbf{u}}) \) is an \((\mathcal{F}_t)\)-martingale. Moreover, using (4.31), we get the quadratic and cross-variation of \( M(1, \hat{\mathbf{u}}) \) as
\[
\begin{aligned}
\langle \langle M(1, \hat{\mathbf{u}}) \rangle \rangle(t) &= N(1, \hat{\mathbf{u}}), \\
\langle \langle M(1, \hat{\mathbf{u}}) \rangle \rangle(t) \hat{\beta}_k(t) &= N_k(1, \hat{\mathbf{u}})
\end{aligned}
\]
which yields
\[
\langle \langle M(1, \hat{\mathbf{u}}) \rangle \rangle(t) - \int_0^t \langle \Phi(1, \hat{\mathbf{u}}) \rangle d\hat{W}(t, \phi) \rangle = 0.
\]
That is, for \( \phi \in C_c^{\infty}(\mathbb{R}^3) \) and \( t \in [0, T] \), we have that
\[
\langle \hat{\mathbf{u}}(t), \phi \rangle = \langle \hat{\mathbf{u}}(0), \phi \rangle + \int_0^t \langle \hat{\mathbf{u}}(t) \rangle d\hat{W}(t, \phi) \]
\[
- \nu \int_0^t \langle \nabla \hat{\mathbf{u}}(t), \nabla \phi \rangle dt + \int_0^t \langle \Phi(1, \hat{\mathbf{u}}) \rangle d\hat{W}(t, \phi).\]
\( \hat{P} \)-a.s. keeping in mind that \( \text{div}\phi = 0 \).

\[ \blacksquare \]

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