Model of Globally Coupled Duffing Flows

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A Duffing oscillator in a certain parameter range shows period-doubling that shares the same Feigenbaum ratio with the logistic map, which is an important issue in the universality in chaos. In this paper a globally coupled lattice of Duffing flows (GCFL), which is a natural extension of the globally coupled logistic map lattice (GCML), is constructed. It is observed that GCFL inherits various intriguing properties of GCML and that universality at the level of elements is thus lifted to that of systems. Phase diagrams of GCFL are determined, which are essentially the same with those of GCML. Similar to the two-clustered periodic attractor of GCML, the GCFL two-clustered attractor exhibits a successive period-doubling with an increase of population imbalance between the clusters. A non-trivial distinction between the GCML and GCFL attractors that originates from the symmetry in the Duffing equation is investigated in detail.

I. INTRODUCTION

A globally coupled map lattice (GCML) is a system of generally a large number ($N$) of maps that iteratively evolve in discrete time ($n$) and interact via their mean field. One typical example is a homogeneous GCML of logistic maps [1,2]:

$$x_i(n + 1) = (1 - \varepsilon) f_a(x_i(n)) + \frac{\varepsilon}{N} \sum_{j=1}^{N} f_a(x_j(n)) \quad (1)$$

$$f_a(x) = 1 - a x^2, \quad i = 1, \cdots, N$$

This evolution can be regarded as an iteration of a two-step process. The first step involves parallel mapping

$$x_i^{\text{mid}} = f(x_i(n)), \quad i = 1, \cdots, N \quad (2)$$

where randomness is introduced in the system if the non-linearity parameter ($a$) of the map is set to be large. The second step involves interaction with a coupling constant $\varepsilon$ via the mean field:

$$x_i(n + 1) = (1 - \varepsilon) x_i^{\text{mid}} + \varepsilon h(n), \quad i = 1, \cdots, N$$

$$h(n) \equiv \frac{1}{N} \sum_{i=1}^{N} x_i^{\text{mid}}. \quad (3)$$

Here the distribution of maps is contracted to the mean field $h(n)$ at the rate of $1 - \varepsilon$ by similarity transformation, and all the maps are forced to respect their average. Hence, by this averaging step, coherence is introduced into the system. Note that the relation $\sum_{i=1}^{N} x_i(n + 1)/N = h(n)$ holds and the average is kept invariant at the interaction step in this model. This is important for the stability of the model. This GCML is simple but it shows us how the conflict between randomness and coherence produces various interesting phases. (Kaneko [3]).

However, in a way, GCML is oversimplified. The real physical process (say, pattern recognition in the brain) occurs in continuous time. At this point, it is tempting to construct a concise model of the globally coupled flows (GCFL) and study to what extent it inherits various intriguing properties of GCML. This study aims to search universality in complex systems (GCML and GCFL).

How to choose the flow (as an element of GCFL) that replaces the logistic map (as an element of GCML)? According to the Poincaré-Bendixon theorem, we must consider a three- or higher-dimensional flow as an element to exhibit a chaotic behavior at the element level if the flow is autonomous, or alternatively, one may consider a two-dimensional flow under an external force. In this paper, we choose, for simplicity, a two-dimensional Duffing oscillator under an external periodic force

$$\frac{dx}{dt} = y, \quad \frac{dy}{dt} = -ky - x^3 + A \cos t \quad (4)$$

with $A = 7.5$. Indeed, it is known that the Duffing flow shares the same period-doubling bifurcation to chaos with logistic maps, sharing the same Feigenbaum ratio 4.6692016... [6,7]. The reason for this universality is as follows: the two-dimensional flow of this model produces a one-dimensional iterated map on the Poincaré section and, therefore, the bifurcation of this model is in one-to-one correspondence with the bifurcation of the one-dimensional iterated map. Besides, all the one-dimensional maps (with a singly peaked function) are governed by a universal function at the limiting bifurcation. The above scenario is crucial in the universality in chaos [6]. In this paper, we numerically study to what

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1 This simple parametrization is studied by Yoshisuke Ueda [2], who found chaos in nonlinear oscillators by analog computer simulation. In addition, Feigenbaum discusses the Duffing oscillator in this form [3]. We have verified that our findings are essentially independent of the choice of the potential shape. The double-well potential Duffing model also follows the symmetry [6], and similar to our single-well Duffing GCFL, the double-well Duffing GCFL also exhibits two-clustered attractor under the symmetry [11].
extent the universality at the element level (the universality between the logistic map and the Duffing oscillator with respect to the bifurcation to chaos) extends to the similarity between the systems, i.e., the logistic GCML and the Duffing GCFL.

In fact, the above universality (at the element level) extends to a certain higher-dimensional flow and relates it down to a one-dimensional map. For instance, the three-dimensional Lorenz model \[ 8 \] (with \( \sigma = 10 \) and \( b = 8/3 \)) has three prominent \( r \) bands, in which it shows period doubling \[ 9 \]. The key to this issue is that the Lorenz system is dissipative. Hence, the effective dimension of the orbit reduces to two in this regime, and on the Poincaré section, it is equivalent to a one-dimensional iterated map \[ 8, 7 \]. Our preliminary analysis of the coupled Lorenz system shows intriguing results: (1) For strong coupling, the transformation \[ L \] of the coupled Lorenz GCFL to a forthcoming paper.

This type of topology change is known to occur for a single Lorenz attractor \[ 10 \]. We defer the discussion of the attractors of coupled models and we will discuss this in Sec. IIIA. (Fig. 6–8). Only after considering this issue in Sec. IIIA. (Fig. 6–8). Only after considering this distinction can we fully understand both similarity and dissimilarity of nonlinearity reduction in GCML and GCFL, as discussed in Sec. IIIID (Fig. 8 and 10).

II. DUFFING GCFL

A. Construction of Duffing GCFL

We construct the Duffing GCFL by replacing the maps in GCML by Duffing flows. The first step \[ 2 \] now becomes

\[
\dot{x}^{mid}_i(t + \Delta t) = x_i(t) + y_i(t)\Delta t
\]

\[
y^{mid}_i(t + \Delta t) = y_i(t) + \left[-ky_i(t) - (x_i(t))^3 + A\cos(t)\right] \Delta t
\]

\( i = 1, \cdots, N \)

and the second \[ 3 \] becomes

\[
x_i(t + \Delta t) = (1 - \varepsilon_D)x_i^{mid}(t + \Delta t) + \varepsilon_D h_x,
\]

\[
y_i(t + \Delta t) = (1 - \varepsilon_D)y_i^{mid}(t + \Delta t) + \varepsilon_D h_y,
\]

\( i = 1, \cdots, N \)

\[
h_x \equiv \frac{1}{N} \sum_{i=1}^{N} x_i^{mid}(t + \Delta t), \quad h_y \equiv \frac{1}{N} \sum_{i=1}^{N} y_i^{mid}(t + \Delta t).
\]

The interaction in this step is via the mean field of the system and the change in the coordinates is directly calculated by a similarity contraction, similar to that in GCML. Hence, let us designate this model as GCFL. A similar model was investigated in the earliest stage of the chaos synchronization study \[ 14, 15 \] (Eq.(5) in 13). There, the synchronization of the chaotic elements was the main concern, while in this study, our interest lies in how various synchronizing phases appear from the originally chaotic flows via nonlinearity reduction due to averaging interaction. Interesting studies have also been conducted on phase synchronization (the amplitude may
be left unsynchronized). Here we study cluster formation (synchronization in both phase and amplitude). An extensive account on the synchronization can be viewed in [13].

To investigate the phase structure of the Duffing GCFL, we need some rough guide of the regions to explore the vast \((k, \varepsilon)\) parameter space.

Let us first discuss the case of nonlinearity parameters. To study nonlinearity reduction (i.e., the battle between chaos and coherence), the nonlinearity parameter of the elements should be set high in the random chaotic regime. For a logistic map, the threshold to chaos is \(a_{\text{th}} = 1.401\), so let us choose \(a = 1.7, 1.8, 1.9\) as typical values. As for a Duffing flow, note that the parameter \(k\), the friction constant, is an \textit{anti}-nonlinear parameter. From \textit{universality in chaos} [6], in the sense that two elements in the same universality class have the same bifurcation trees, a natural choice for comparison is to align the bifurcation tree of a Duffing flow with that of a logistic map, as shown in Fig. 1.

In fact, there is a subtlety in the Duffing flow. At very low nonlinearity (very large friction constant \(k\)), the periodic orbit is self-symmetric in the \(xy\) plane, and with an increase in nonlinearity, it changes the topology, splitting into two periodic orbits \((A_+\) and \(A_-)\) at \((k \approx 0.66)\), which are mirror symmetric of each other (see insets in Fig. 1). We consider that each of the \(A_\pm\) corresponds to a fixed point of a logistic map and align the Duffing tree with the logistic tree such that the second and third bifurcation points match between the two trees.

It is interesting to test how the Lyapunov exponents compare between two models after matching the bifurcation trees. The Duffing flow induces a Floquet map at the Poincaré shot, which is taken at every period of the external force. Therefore, we expect a correspondence

\[
e^{\lambda_{\text{flow}}} \times 2\pi \approx e^{\lambda_{\text{map}}}. \tag{9}
\]

The agreement between the exponents is remarkably good except for the details of windows, as observed in Fig. 2.

Up to now, we have been considering matching at the level of the basic elements of two models. Now, let us consider the coupling \(\varepsilon_D\). In GCML, the similarity contraction by \(1 - \varepsilon_{\text{map}}\) occurs at each interaction step. On the other hand, in the Duffing GCFL [7,8], the contraction by \(1 - \varepsilon_D\) occurs at each \(\Delta t\), and \(\Delta t\), in turn, has to be chosen sufficiently small to guarantee finite difference approximation. (We typically use \(\Delta t = 10^{-3}\).) Therefore, the coupling \(\varepsilon_D\) must be chosen to be small enough such that the accumulation of the contraction effect in GCFL roughly amounts to the contraction in GCML. That is, very crudely

\[
1 - \varepsilon_{\text{map}} \approx (1 - \varepsilon_D)^t, \tag{10}
\]

where \(t_c\) is a certain time scale of order one. If one may simply carry over the correspondence at the level of elements to that of the systems, one iteration step of a map corresponds to a \(2\pi\) evolution of the flow so that

\[
\lambda_{\text{flow}} \times 2\pi \approx \lambda_{\text{map}},
\]

Figure 1. (a) Bifurcation tree of a logistic map. (b) Bifurcation tree of a Duffing flow. For \(k > k_0 = 0.660\), the Duffing attractor is unique and left-right symmetric (not shown), while for \(k_0 > k > k_1 = 0.380\), it becomes bivalent (either \(A_+\) or \(A_-\)), each being chiral (see insets). With a further decrease in \(k\), each of \(A_+\) or \(A_-\) bifurcates. The threshold for \(A_{\pm}^{(2n-1)} \rightarrow A_{\pm}^{(2n)}\) is denoted as \(k_n\). Arrowed dashed lines connecting (a) and (b) indicate that the second and third bifurcation points are chosen for the matching of \(a\) and \(k\). Solid lines show A, B, and C points, which are used for the comparison of GCML and GCFL.

\[\text{FIG. 1.} \quad \text{FIG. 2.}\]
one might assume $t_c = 2\pi$. However, the systems are evolving while interacting in nontrivial ways (the crucial point is the existence of a pairing attractor structure in the Duffing flow) and the above naive expectation is unjustified.

We proceed below without any assumption on the value of the $\varepsilon$ (and $t_c$). We regard $\varepsilon$ as a free parameter of the model and only use (10) as a guide to explore the GCFL phase diagram. We will find below that in the Duffing GCFL, phases quite similar to those of the logistic GCML are realized and the proper choice of $t_c$ is as given in (14).

Now, we are ready to investigate the Duffing GCFL. Fig. 3 shows a typical run in the Duffing GCFL with $N = 100$. Here the model ($k = 0.241$ (case A) and $\varepsilon = 1.1 \times 10^{-4}$) is started at a random initial configuration, and after about 10 cycles of external periodic force, the flows divide themselves into two synchronizing periodic clusters. This is a typical run for the two-clustered regime of the Duffing GCFL. Let us now compare the overall phase structures between the two models.

B. Phase diagrams

1. GCML phase diagram

The phase structure of GCML [1] is explored by Kaneko; refer to [1] for a detailed phase diagram in the $(a, \varepsilon)$ plane. To facilitate a comparison with the GCFL phases, we reproduce in Fig. 4 the GCML phases at A, B, and C points. There are three outstanding phases:

(1) The coherent chaos state at large $\varepsilon$. The maps are strongly bunched together in one cluster $(x_i(n) = X(n), i = 1, \cdots, N)$. Then, $h(n) = X(n)$ and, therefore, the interaction (3) becomes immaterial. All the maps evolve in a bunch just as a single logistic map at the original $a$.

(2) The two-clustered phase at intermediate $\varepsilon$. The final maps divide into two clusters $(x_i^1(n) = X^1(n), i = 1, \cdots, N_1)$ and the two clusters, with populations $N_1$ and $N_2$, respectively, oscillate periodically opposite in phase to each other, thus keeping the fluctuation of the mean field $h(n)$

B, and C points. There are three outstanding phases:

(1) The coherent chaos state at large $\varepsilon$. The maps are strongly bunched together in one cluster $(x_i(n) = X(n), i = 1, \cdots, N)$. Then, $h(n) = X(n)$ and, therefore, the interaction (3) becomes immaterial. All the maps evolve in a bunch just as a single logistic map at the original $a$.

(2) The two-clustered phase at intermediate $\varepsilon$. The final maps divide into two clusters $(x_i^\mu(n) = X^\mu(n), i = 1, \cdots, N_\mu)$, and the two clusters, with populations $N_1$ and $N_2$, respectively, oscillate periodically opposite in phase to each other, thus keeping the fluctuation of the mean field $h(n)$

We have cross-checked these phase structures.
small. This opposite phase motion is a solution for stability. A remarkable property found by Kaneko [1] is that the population ratio \( \vartheta = \frac{N_1}{N_1 + N_2} \) acts as a new bifurcation parameter.

(3) The turbulent phase at very small \( \varepsilon \). In general, the number of clusters is proportional to \( N \) and maps evolve almost independently of the randomness of the original \( a \).

In addition, in a region marked as periodic clusters, several clusters ((2, 3), (2, 3, 4), (3, 4), \ldots) are formed with decreasing \( \varepsilon \), and in partially ordered phases, the basin volume is partitioned by the dynamics of two surrounding regions.

2. GCFL phase diagram

Fig. 5 shows the phase diagrams of the Duffing GCFL for three choices of the friction coefficient, \( k = 0.241, 0.228, \) and 0.215 corresponding to A, B, and C, respectively, in Fig. 1. In the figure, basin volume ratios of the final attractors are exhibited by the partition of the bar width. The attractor of the type coherent-chaos at the strong coupling regime changes its topology. At the low nonlinearity side of the element flow (case A), the attractor is chiral, while at the high nonlinearity side (B and C), it is self-dual. With increasing nonlinearity (decreasing \( k \)), a larger coupling \( \varepsilon \) is required to maintain the same dynamics.

4 However, statistical analysis reveals hidden coherence— a long-time-scale correlation [2]. Furthermore, there occur drastic periodic motions of maps in stable clusters at specific \( \varepsilon \) values tuned with a’s—periodicity manifestations such as \( p3c3 \) and \( p6c2117 \). The reflection of these manifest cluster formations dominates all over the turbulent regime of GCML. These are due to the foliation of periodic window dynamics of the element maps [19]. We refer to [22], where the foliation at the small \( \varepsilon \) region is caught as a tongue-like structure.
The three basic phases of GCML, namely (1) the coherent chaos, (2) the two-clustered phase, and (3) the turbulent phase, are also realized in the Duffing GCFL and in the same order as coupling strength. Moreover, the tendency that the regimes shift to the higher coupling with increasing nonlinearity is also the same. (Note that the lower friction \( k \) implies higher nonlinearity.) The agreement in the basic phase structure implies that the Duffing GCFL inherits the intriguing properties of the logistic GCML and that the universality at the element level may be lifted to that at the level of globally coupled systems.

Below, we list the nontrivial properties of the Duffing GCFL that are not present in GCML:

1. Symmetry of the Duffing equation under \( \vartheta \) leads to an attractor consisting of pairwise clusters. The clusters may be called mirror pairs (but with a shift of \( \pi \) in time.) (On the other hand, in the GCML, a two-clustered regime, clusters evolve in essentially the same orbit with a shift of one step.)

2. As an intriguing consequence of (1), we observe not only the \( P \otimes P \) state but also the \( C \otimes C \) and \( C \otimes P \) states.

3. If the coupling is high enough, the flows are bunched in a cluster and the cluster evolves with the original high nonlinearity of the elements (coherent chaos). At this point, the case is the same as that for GCML. However, the Duffing flow at high nonlinearity shows two types of attractors. If the nonlinearity is not so high, the chaotic flow is confined in either the left or right polarized orbit (chiral type), while at the higher nonlinearity, the chaotic flow extends over the joint of the above two orbits (self-dual type). This is reflected in the coherent chaos state. (Compare the coherent chaos in \( A \) with that in \( B \) and \( C \)).

Hereafter, we focus on the interesting two-clustered phase, which is realized in both GCFL and Duffing GCFL.

III. TWO-CLUSTERED DYNAMICS OF THE DUFFING GCFL

A. Attractor \( \vartheta \)-bifurcation

1. \( \vartheta \)-bifurcation in GCML

In the two-clustered regime, the GCML attractor consists of two clusters mutually oscillating opposite in phase. Let \( N_+ \) be the number of maps in the positive cluster (the one consisting of maps with \( x_i(n) > h(n) \) at even iteration step \( n \)). Kaneko found that with an increase (or decrease) in the population ratio \( \vartheta \equiv N_+/\left(N_+ + N_-\right) \), the cluster attractor repeats successive bifurcations until the imbalance reaches a certain threshold beyond which the system goes into chaotic transients \([1, 3]\). Let us call this phenomenon \( \vartheta \)-bifurcation. It implies that the cluster attractor is labeled by three parameters \((a, \varepsilon, \vartheta)\) and it may lead to a possible new approach of information processing.

2. Attractor symmetry and \( \vartheta \)-bifurcation in GCFL

Let us investigate if our Duffing GCFL inherits this intriguing property. The answer is yes, but, in order to fully understand the \( \vartheta \)-bifurcation in GCFL, we have to take account of an attractor symmetry coming from the symmetry \([5]\) of the Duffing equation.

In Fig. 6, we show three typical events in the GCFL two-clustered regime. The central event is basic. It is \( \vartheta = 0.5 \) and is of period one. If a time translation of \( \pi \) is applied on one of the two clusters, its position becomes exactly mirror symmetric to that of the other cluster. The other two events are \( \vartheta = 0.77 \) and \( \vartheta = 0.23 \). The cluster orbits are indeed bifurcated and are of period two \((T = 4\pi)\). Let us call the attractors type A and type B if \( \vartheta > 0.5 \) and \( \vartheta < 0.5 \), respectively, and two attractors as partner attractors if \( \vartheta_A + \vartheta_B = 1 \). The attractors shown at the right and the left of the basic attractor, respectively, are thus partner attractors. Inspecting the motion of clusters in Fig. 6, we find an interesting symmetry that holds between the partner attractors:

\[
(T_\pi \otimes P)(X_A(t),Y_A(t))^C) = (-X_A(t + \pi),-Y_A(t + \pi))^C
\]

\[
= (X_B(t),Y_B(t))^C \quad (C = L,S), \quad (11)
\]

where \( C = L, S \) denote the large (majority) and small (minority) clusters, respectively. This symmetry holds...
for majority and minority clusters separately. Note that at the limit \( \theta \to 0.5 \), this relation reduces to the symmetry observed in the central event. This, in turn, implies that we also have an approximate symmetry relation

\[
((X_A(t), Y_A(t)))^{(L,S)} \approx (X_B(t), Y_B(t)))^{(S,L)},
\]

as confirmed by Fig. 6.

Given that the dynamics of the \( N \) flows is reduced by synchronization to that of two clusters, that is, assuming the two-clustered configuration, it can be seen that the symmetry (6) of the single Duffing oscillator is lifted to (11). We show below that if (11) holds at time \( t \), then it also holds at time \( t + \Delta t \).

The GCFL evolution is an iteration of the two-step process, so let us start with the first step. For the two-clustered configuration, this leads to

\[
\begin{align*}
X^{mid}(t + \Delta t) &= F(X(t), Y(t)) = X(t) + Y(t)\Delta t, \\
Y^{mid}(t + \Delta t) &= G(X(t), Y(t), t) \\
&= Y(t) + [-KY(t) - X(t)^3 + A\cos t]\Delta t.
\end{align*}
\]

This applies to both majority and minority clusters and to both type A and B attractors. First, let us examine \( Y^{mid} \), where \( G \) has an explicit \( t \) dependence. We have

\[
Y^{mid}_A(t + \Delta t) = G(X_A(t), Y_A(t), t) \\
= G(-X_B(t + \pi), -Y_B(t + \pi), t) \\
= -G(X_B(t + \pi), Y_B(t + \pi, t + \pi) \\
= -Y^{mid}_B(t + \pi + \Delta t).
\]

The first and forth equalities are from (13), the second follows from the assumption at \( t \), and the third from the symmetry of the Duffing equation (6) used in the first step. Thus, we obtain \( Y^{mid}_A(t + \Delta t) = -Y^{mid}_B(t + \pi + \Delta t) \).

The next step is the interaction through the mean field. For the two-clustered configuration, for the \( X \) coordinates, we have

\[
\begin{align*}
X(L)(t + \Delta t) &= (1 - \varepsilon_D\varphi_S)X^{mid}(L,mid) + \varepsilon_D\varphi_S X^{mid}(S,mid), \\
X(S)(t + \Delta t) &= (1 - \varepsilon_D\varphi_L)X^{mid}(S,mid) + \varepsilon_D\varphi_L X^{mid}(L,mid)
\end{align*}
\]

and the same also holds for the \( Y \) coordinates. As these are a linear mapping, (11) is apparently kept. Thus, we have shown that (11) is the symmetry of the GCFL evolution.

### 3. A comparison between the GCML and GCFL \( \vartheta \)-bifurcations

With this symmetry in mind, let us compare the \( \vartheta \)-bifurcation in GCML and that in GCFL in detail in Fig. 7. We use a representation devised by Kaneko [3]. As for GCML, we draw all values of the maps at \( \vartheta \) in the final cluster attractor at all even time steps. First, consider an event of a two-clustered attractor with \( \vartheta = 0.5 \) (the evolution is not drawn). This is the basic attractor in the GCML two-cluster regime, in the sense that it is free from \( \vartheta \)-bifurcation. The two clusters oscillate mutually opposite in phase around their mean field, and each one returns to its previous position at every two steps. Thus, the basic motion produces two points at \( \vartheta = 0.5 \). In Fig. 7 (a) a sample event with \( \vartheta = 0.41 \) is exhibited. The orbits are bifurcated to period four for high population imbalance, and they contribute four points (two for each cluster) to the \( \vartheta \)-bifurcation diagram (1b). The omission of odd step data serves to display the \( \vartheta \)-bifurcation of two clusters separately in one diagram.

As for the Duffing GCFL, the basic motion at \( \vartheta = 0.5 \) is period one \( (T = 2\pi) \), as discussed in Fig. 6. Therefore, we take the Poincaré shot of all flows at every multiple of \( 2\pi \) and plot them at the \( \vartheta \) to construct the \( \vartheta \)-bifurcation diagram. In Fig. 7 (c) and (e), we show a sample event with \( \vartheta = 0.23 \). Due to the population imbalance, the two-clustered attractor is bifurcated to period two \( (T = 4\pi) \), and the cluster orbits again contribute four points in the \( \vartheta \)-bifurcation diagram. In GCFL, the mean field \( h_{x,y}(t) \) oscillates because of the external periodic force and the two clusters mutually oscillate around this oscillating \( h_{x,y}(t) \). However, at the Poincaré shot, we clearly observe that the two-clustered attractor in GCFL shows a remarkable \( \vartheta \)-bifurcation, which is quite similar to that in GCML.

It is worth summarizing two clear distinctions between the GCML and GCFL \( \vartheta \)-bifurcation.

(i) The basic motion at \( \vartheta = 0.5 \) in the two-clustered attractor regime is period two in GCML and period one \( (T = 2\pi) \) in GCFL. That is, two iteration steps in GCML correspond to one rotation in the Duffing GCFL:

\[
\begin{align*}
\text{GCML} &\quad n \to n + 2 \\
\text{Duffing GCFL} &\quad t \to t + 2\pi.
\end{align*}
\]

The \( \vartheta \)-bifurcation occurs successively from this basic attractor with increasing population imbalance.

The matching of the nonlinearity between the elements is fixed in (11A) on the basis that one iteration of a free map corresponds to one rotation \( (T = 2\pi) \) of a free Duffing flow. There is no contradiction because in (11B), the correspondence between two systems is considered, where interaction is in action and system nonlinearities are reduced. We discuss this point in detail in the following subsection.

(ii) In GCML, each of the two clusters evolves in its one-dimensional orbit and two orbits of the clusters approximately agree with each other (precisely if \( \vartheta = 0.5 \)) modulo a shift of one step. In the Duffing GCFL, on the other hand, the cluster attractor is two dimensional under the \( T \otimes P_{\pi} \) symmetry (11). Both (i) and (ii) together realize quite similar \( \vartheta \)-bifurcation diagrams for GCML and GCFL.
4. Polarization of the $\vartheta$-bifurcation tree in GCFL

Let us add a brief remark here. The GCFL $\vartheta$-bifurcation diagram is strongly polarized (the larger $\vartheta$ forks are missing) in contrast to the unpolarized GCML diagram. This is possible since the external oscillatory force may favor type-B rather than type-A attractors in the formation process, while GCML is autonomous. In order to overcome unwelcome missing bifurcation trees in the larger $\vartheta$ side, we can use the relation (11). If we measure the type-B event (with some $\vartheta = \vartheta_{0}$) at every odd multiple of $\pi$, it supplies equivalent data for the type-A event (with $\vartheta = 1 - \vartheta_{0}$) at every even multiple of $\pi$. 

FIG. 7. The $\vartheta$-bifurcation diagrams (right) associated with the evolution plots of the sample events (left) illustrate how diagrams are calculated. The logistic GCML $[a, b]$ and the Duffing GCFL $x$-coordinates $[c,d]$, $y$-coordinates $[e,f]$. In the evolution plot, majority and minority cluster orbits are depicted by solid and dashed lines, respectively. Their positions, at every even step for GCML and at every even multiple of $\pi$ for GCFL, are depicted by white and black circles for the majority and minority clusters, respectively, and they contribute to the $\vartheta$-bifurcation diagrams altogether four points (two for each cluster), as indicated by horizontal fine dotted lines.
FIG. 8. GCFL ϑ-bifurcation diagrams. (a) is the same with Fig. 7(d) (flows at every even multiple of 2π) except that the number of initial configurations is limited to $10^4$ to show ϑ polarization. In the event formation probability below, one observes that type B is clearly more frequently produced. (b) is deduced via (5) from the same $10^4$ data, but orbits at odd multiples of 2π are converted by the relation (11). (c) is our final GCFL ϑ-bifurcation tree constructed from a total of $6.4 \times 10^5$ events; both even and odd steps data are combined).

Fig. 8 presents the GCFL polarization-free ϑ-bifurcation diagram thus obtained. To our knowledge, this is the first observation of ϑ-bifurcation in the globally coupled Duffing flows and its comparison with ϑ-bifurcation in GCML.

5. A comment on a posi-nega switch

It would be interesting to investigate if a posi-nega switch found in the GCML [1] can also be realized in GCFL, but we defer this for the following reasons. In
GCML, the two periodic clusters have negative Lyapunov exponents. In several steps of iteration, the variance of map coordinates in each cluster becomes less than the machine epsilon. One could introduce low level noises to avoid numerical collisions, but then the analysis of the positive switch will involve technical subtleties. The GCFL attractors have also negative Lyapunov exponents and share the same difficulty in the numerical analysis. Furthermore, we have checked that the GCFL two-clustered attractors are robust in the sense that the threshold value $\vartheta_{th}$ to the decay into a chaotic transient process is quite high ($\vartheta_{th} \approx 0.9$) or quite low $\vartheta_{th} \approx 0.1$. This is a negative indication for an implementation of the interaction if the interaction would be switched off. However, at the switch, because, in order to enhance the population imbalance beyond the threshold, many elements must be transferred from the minority to the majority cluster and, then, the above collision problem becomes more severe in the GCFL than in the GCML.

IV. TWO-CLUSTERED DYNAMICS OF THE DUFFING GCFL

A. Nonlinearity reduction

The periodic attractor in the two-clustered regime is a consequence of the reduction in the high nonlinearity of the elements caused by the averaging interaction via the mean field. We first recapitulate this issue in GCML, where some quantitative understanding is possible on the basis of the Perez-Cerdeira transformation for the quadratic map. We then numerically investigate the case of GCFL in some detail.

1. Case of GCML; foliation curves of periodic window dynamics of element maps into the $(a, \varepsilon)$ plane

In GCML, all element maps have high nonlinearity, and the maps would evolve independently in random motion if the interaction would be switched off. However, at every iteration step, the map coordinates are uniformly contracted to the mean field and coherence is introduced. The nonlinearity of the system is effectively reduced and the periodic clustered attractors are formed.

Now, interestingly, there is a case in which this reduction can be quantitatively estimated. This is the case of the maximally symmetric cluster attractors (MSCAs) formed in the turbulent regime. We refer to [17] for a detailed account. In the MSCA, the maps synchronize in almost equally populated $c$ clusters that oscillate in period $p = c$ around their mean field. The most prominent one is the $p3c3$ MSCA. In such an MSCA, the mean field is almost constant because of the population symmetry, and hence, it is possible to estimate to what extent the nonlinearity of the element maps is reduced. In fact, as the mean field is approximately a constant $h_0 \approx h^*$, the GCML evolution equation leads to

$$x_i(n+1) = (1 - \varepsilon) [1 - a(x_i(n))^2] + \varepsilon h^*, \quad i = 1, \cdots, N.$$  

(15)

Then, the scaled maps defined by the Perez-Cerdeira transformation

$$y_i(n) = \frac{x_i(n)}{1 - \varepsilon + \varepsilon h^*},$$

(16)

all equally follow the same scaled map

$$y_i(n+1) = 1 - b(x_i(n))^2, \quad i = 1, \cdots, N.$$  

(17)

The nonlinearity is reduced from $a$ to $b = ra$, where

$$r = (1 - \varepsilon) [1 - \varepsilon (1 - h^*)] < 1$$

(18)

is the rate of nonlinearity reduction. A good rule of thumb is $r \approx 1 - 2\varepsilon$.

We can go a step further. Taking the average of (16) over the elements, we obtain

$$\frac{h^*}{1 - \varepsilon + \varepsilon h^*} = \langle y \rangle = y_0^*$$

(19)

, where $y_0^*$ is the long-time average of a single map $y_b(n)$ with nonlinearity $b$. Solving (18) and (19) for $a$ and $\varepsilon$ at a given $b$ and $r$, one obtains the parametric form of a curve (labeled by $b$ and develops with $r$) that describes the foliation of dynamics of a period $p$ window into the $(a, \varepsilon)$ plane.

$$a^{(b)}(r) = \frac{b}{r},$$

(20)

$$\varepsilon^{(b)}(r) = 1 - \frac{r y_0^*}{2} - \sqrt{r(1 - y_0^*) + \left(\frac{r y_0^*}{2}\right)^2}$$

(21)

We generally observe the period $p$ MSCA ($r \gtrsim 0.95$) and its remnant state ($r \lesssim 0.95$) in the $(a, \varepsilon)$ region, which lie between the two foliation curves emanating from $b_1$ and

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5 Precisely, for the two-clustered attractor state with populations $N_1$ and $N_2$, the Lyapunov exponents generally divide into two sets. The first one consists of two exponents, $N_1 - 1$ and $N_2 - 1$ fold degenerate, respectively. These are responsible for the contraction of the maps to the center of the respective cluster. For the two clusters of concern, we have measured these as negative [21]. The second consists of two exponents that are responsible for the stability of the cluster orbits and they are also negative.

6 $\langle y \rangle$ is, for the MSCA, an equal-weight average of the cluster orbits over $p = c$ clusters. But, again for the MSCA, this is nothing but the average of the cluster orbit points $Y_I(n)$ over period $p$. This, in turn, is also the case with $y_0^*$. Namely, $\langle y \rangle = \sum_{n=1}^{p-1} y_I(n)/\langle Y \rangle = \sum_{n=1}^{p-1} Y_I(n)/\langle Y \rangle = y_0^* = \lim_{T \to \infty} \sum_{n=1}^{T_0+f} Y_I(n)/\langle Y \rangle [16]$.

7 Our formulation of the foliation curves [17] was inspired by [21].
FIG. 9. The band of the two-clustered dynamics of GCML (left) and GCFL (right) in the parameter spaces \((a, \varepsilon_{\text{map}})\) and \((k, \varepsilon_D)\), respectively. (For comparison, the \(\varepsilon_D\)-axis is adjusted to the \(\varepsilon_{\text{map}}\)-axis using the relation (22).) In the black band, the formation probability of the two-clustered periodic attractor is more than 90\% while in the adjacent gray regions, the basin volume is shared more by nearby dynamics (coherent chaos in \(Z_1\) and \(Z_3\), multiclustered attractors in \(Z_2\), \(C \otimes C\) in \(Z_4\)), and toward the outer edges of the gray bands, the partition of the two-clustered periodic attractor decreases down to 10\% (Fig. 5).

The judgment of final states is performed by inspection after \(10^5\) iteration steps from an initial random start. If it is performed after \(10^2\) steps, \(Z_1\) is partially ordered. For GCML, the foliation curves of the dominant windows are also shown; in particular, \(b_1\) and \(b_2\), respectively, emanate from the first and second bifurcation points \((p_1 \rightarrow p_2\) and \(p_2 \rightarrow p_4\) \(\text{ref. [17, 20]}\)).

\(b_2\) (indicating nonlinearity at the \(p\) window’s opening and at the first bifurcation in the \(p\) window, respectively).\(^8\)

\(^8\) In the adjacent region (with larger \(\varepsilon\)), period \(p\), \(c\)-clustered states (with \(p > c\)) are formed. The foliation curves are exhibited in Fig. 9-GCML.

We should now clarify the logic. The foliation curves are derived assuming the existence of the MSCAs. If a \(p = c\) MSCA is formed, it must be within the \((a, \varepsilon)\) region dictated by the foliation curves of the period \(p\) window. Furthermore, we can prove that at the MSCA, all the Lyapunov exponents are negative and the MSCA is a stable attractor \(\text{ref. [17]}\). However, the converse is not necessarily true. There is no guarantee that the MSCA is formed everywhere in the range specified by the foliation curves; indeed for \(r \lesssim 0.95\), we observe only the remnants of MSCAs \((p > c\) clustered attractors) as the valleys (peaks) in the distribution of the mean squared deviation of the mean field \(h(n)\) \(\text{ref. [17, 18]}\).

Now, in the two-clustered regime of concern, the maps divide themselves into two clusters, and the two clus-
ters oscillate mutually around the mean field. Here the attractor is robust in that it allows the population imbalance accompanied by the attractor bifurcation. However, in the particular case of \( \vartheta = 0.5 \), we can regard it just as a \( p = c = 2 \) MCA. With this concept, we can apply the above formulation to predict the possible region in which the two-clustered attractor may be formed.

In Table II we compare the observed \( \varepsilon \) range of the two-clustered regime with the predicted bounds from the foliation of the period-two window dynamics. For the latter, the two curves from \( b_1 = 0.75 \) and \( b_2 = 1.25 \) are used, which are the opening point of the \( p2 \) window (the threshold of \( p1 \rightarrow p2 \)) and the threshold of \( p2 \rightarrow p4 \), respectively. Table II shows that the observed range \( (\varepsilon_3, \varepsilon_4) \) is inside the predicted bounds. Moreover, Fig. 9 shows that the observed band for the formation of two-clustered attractors runs just in the center of the above two foliation curves.

### Table I. Two-clustered regime in GCML

| Nonlinearity\( ^a \) | observed \( \varepsilon \)-range\( ^b \) | Prediction(bounds)\( ^c \) |
|----------------------|------------------|------------------|
| \( a = 1.70 \)       | 0.16 - 0.19 - 0.25 - 0.30 | 0.17 - 0.44 |
| \( a = 1.80 \)       | 0.18 - 0.23 - 0.28 - 0.32 | 0.20 - 0.46 |
| \( a = 1.90 \)       | 0.21 - 0.27 - 0.30 - 0.34 | 0.23 - 0.48 |

\( ^a \) Matching points A, B, and C with the corresponding nonlinear parameter \( a \) in the parenthesis (see Fig. 4(a)).

\( ^b \) Period two, two-clustered attractor (\( p2c2 \)) formation occupies more than 90% of the basin volume in \( \varepsilon_2 - \varepsilon_3 \), and the fraction decreases down to 10% toward \( \varepsilon_1 \) and \( \varepsilon_4 \). The rest of the basin volume is occupied by the formation of three or four clusters in random motion in \( \varepsilon_1 - \varepsilon_2 \), and single-clustered chaos in \( \varepsilon_3 - \varepsilon_4 \), respectively.

\( ^c \) The prediction for the bounds based on \( p2c2 \) foliation curves. The upper (lower) bound from \( p1 \rightarrow p2 \) (\( p2 \rightarrow p4 \)) bifurcation threshold of the element map.

#### 2. Case of the Duffing GCFL

Comparing Fig. 4 and Fig. 5, one clearly observes that, as is the case for GCML, the Duffing GCFL reduces the system nonlinearity caused by the averaging interaction via the mean field. The \( \varepsilon \) ranges for the two-clustered regime at A,B, and C are listed in Table II. Again, with increasing nonlinearity, the \( \varepsilon \) necessary to maintain the two-clustered attractor shifts toward the higher end.

Let us examine how the observed parameter range in GCFL compares with that in GCML.

Since two steps in GCML correspond to one cycle \( (2\pi) \) in GCFL (see 14), one may roughly predict the range of \( \varepsilon \) in GCFL via the data of \( \varepsilon \) in GCFL by a relation

\[
(1 - \varepsilon_D^{\text{estimation}})^{2\pi/\Delta t} \approx (1 - \varepsilon_{\text{map}})^2, \tag{22}
\]

each side expressing the contraction rate in respective models. Note that the matching of \( k \) and \( a \) is considered between a free flow and a free map and then one period \( (2\pi) \) of a flow naturally corresponds to one iteration step of a map. On the other hand, \( (22) \) is considered between flows and maps in actual interaction, realizing the correspondence \( (14) \). Table II shows that the prediction for the two-clustered attractor range roughly agrees with the observed \( \varepsilon_D \) range, although generally, the latter turns out to be somewhat higher than the former simple prediction.

To analyze this issue globally in quantitative terms, we show in the lower panel of Fig. 9 the band of two-clustered dynamics on the \((k, \varepsilon_D)\) plane, where the \( \varepsilon_D \) axis is adjusted using the relation \( (22) \) to facilitate the comparison with the GCML case in the left panel. We find that the two-cluster band in the Duffing GCFL runs in the \((k, \varepsilon_D)\) plane roughly like the foliation band of \( p2c2 \) attractor in GCML in the \((a, \varepsilon_{\text{map}})\) plane but with two notable differences:

1. the GCFL band turns out with a somewhat higher coupling,
2. the GCFL band is less tilted than the GCML one.

These differences can be understood as follows. For simplicity, let us consider the basic two-clustered attractor with \( \vartheta = 0.5 \), which is free from \( \vartheta \)-bifurcation. In GCML, this is period two \( (p2c2) \), while in the Duffing GCFL, it is period one, as discussed in [14] (see especially 13). Pairwise clusters in GCFL \((\text{each period one})\) emulate the GCML \( p2c2 \) attractor. Therefore, while the nonlinearity is reduced from chaos to period two in GCML, it should be reduced deeply down to period one in GCFL, which requires higher coupling at the equivalent nonlinearity.

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*Note: The table and figure symbols are placeholders and should be replaced with actual content.*

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9 We are aware that this is only a crude approximation because all the \( 2\pi/\Delta t \) of the one-step contraction \((1 - \varepsilon_D)\) factors are gathered and multiplied into a single factor after (unjustifiably) commuting them through all the small time \( (\Delta t) \) evolution steps. However, we have checked, varying \( \Delta t \) from \( 10^{-3} \) down to \( 10^{-5} \), that numerically measured \( \varepsilon_D \) keeps the left hand side of \( (22) \) almost invariant. This supports the above approximation to some extent.
To quantitatively verify this explanation, we have extended the range of $k$ (a) (Fig. 10) such that it covers the periodic regime of the element flow (map). In the extended region, the elements are already periodic and hence, if the coupling is sufficiently strong to maintain overall coherence, a single clustered attractor is formed, which evolves with the same periodicity as that of the element ($Z'_2$) for GCML and GCFL, respectively.) If, on the other hand, the coupling becomes sufficiently small, a multicentered periodic attractor is formed in GCML ($Z'_2$), while in GCFL, the periodic external force compels the flows to synchronize in two clusters, one subject to $A^{(2)}_+(A_+)$ and the other to $A^{(2)}_-(A_-)$ depending on the bifurcation state of the element flows ($Z'_2$, $Z'_4$). In the intermediate coupling, the extension of the central band of Fig. 9 is formed for both GCML and GCFL. We clearly observe that the two-cluster band of GCFL is smoothly connected to the period-one window of the element flow at $\varepsilon \to 0$, just as the GCML two-clustered band flows along foliation curves to the period-two window.
V. CONCLUSION

We have constructed a Duffing GCFL as a natural extension of the logistic GCML and investigated to what extent the intriguing features of the logistic GCML are inherited by our model. This, in turn, amounts to an explanation of the extended universality at the level of the complex systems. To compare GCFL with GCML, we have worked in a scheme where the element flow is adjusted to have the same nonlinearity as that of the element map, in the sense that their locations in the (universal) bifurcation trees match each other, while the coupling \( \varepsilon_D \) is varied as a free parameter to seek if GCFL realizes the corresponding phenomena in GCML. As a byproduct, we have observed that the bifurcation-tree matching leads to remarkable agreement between the Lyapunov exponents of the elements over the entire non-linearity parameter value range.

The phase diagram presented in Fig. 7 clearly exhibits that in the Duffing GCFL, the same phases as those in the logistic GCML are realized in the same order with increasing \( \varepsilon \). Furthermore, the extensive analysis of the Duffing two-clustered dynamics shows that the Duffing GCFL has the ability of \( \vartheta \)-bifurcation just as GCML does (Fig. 8). We believe that this is the first systematic observation of \( \vartheta \)-bifurcation in coupled flow systems. This clearly shows that the universality between a map and a flow is basically extended to the level of universality between the systems.

However, we have found that there is an important distinction between the two models that comes from the fact that a Duffing flow admits a pair of possible attractors under the symmetry \( \overline{\vartheta} \). As a consequence, the GCFL attractor in the two-clustered regime consists of pairwise clusters (Fig. 9) under a symmetry relation \( \overline{\vartheta} \) and each in period one (returns the same phase-space point at every \( 2\pi \), modulo \( \vartheta \)-bifurcation). In the logistic GCML, on the other hand, the element map has a unique attractor and the two-clustered attractor consists of two clusters, each evolving in period two but mutually shifted by one step (i.e., in opposite phase). This distinction depicted in Fig. 4 means that the nonlinearity reduction in GCML is only down to period two, while in GCFL, it is reduced deeply down to period one. To verify this, we have numerically measured (extending the element nonlinearity from chaotic to periodic regime) how the band of the two-clustered dynamics in GCFL runs in the \((k - \varepsilon)\) space. It is clearly observed (Fig. 10) that the GCFL band flows into the period-one window, just as the GCML band flows into the period-two window. To summarize, the Duffing GCFL basically shares the same phases and the same \( \vartheta \)-bifurcation property with the logistic GCML; however, detailed examination has revealed that there is a distinction because of the difference in the basin structures of the elements. Finally, we are now investigating a GCFL of three-dimensional flows in detail.\[10\]

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