OPTIMAL REDUNDANCY ALLOCATION IN COHERENT SYSTEMS WITH HETEROGENEOUS DEPENDENT COMPONENTS

MARYAM KELKINNAMA,∗ Isfahan University of Technology
MAJID ASADI ⋆,** University of Isfahan

Abstract

This paper is concerned with the optimal number of redundant allocation to n-component coherent systems consisting of heterogeneous dependent components. We assume that the system is built up of L groups of different components, L ≥ 1, where there are ni components in group i, and \( \sum_{i=1}^{L} n_i = n \). The problem of interest is to allocate \( v_i \) active redundant components to each component of type \( i \), \( i = 1, \ldots, L \). To get the optimal values of \( v_i \) we propose two cost-based criteria. One of them is introduced based on the costs of renewing the failed components and the costs of refreshing the alive ones at the system failure time. The other criterion is proposed based on the costs of replacing the system at its failure time or at a predetermined time \( \tau \), whichever occurs first. The expressions for the proposed functions are derived using the mixture representation of the system reliability function based on the notion of survival signature. We assume that a given copula function models the dependency structure between the components. In the particular case that the system is a series-parallel structure, we provide the formulas for the proposed cost-based functions. The results are discussed numerically for some specific coherent systems.

Keywords: Reliability; cost optimality; system maintenance; survival signature; active redundancy; exchangeability

2020 Mathematics Subject Classification: Primary 90B25
Secondary 60K10; 62N05

1. Introduction

1.1. Motivation and related literature

In reliability engineering and system security, one of the most useful methods for enhancing the reliability characteristics of a system is to allocate redundant components to the system. The redundancy can be performed at the component level or the system level. In the former case some redundant components are connected to each component, while in the latter case the original coherent system fastens to some copies of itself. In a commonly used type of redundancy, called active redundancy, the original component and the redundant ones work simultaneously.

Received 14 April 2021; revision received 21 January 2022.
* Postal address: Department of Mathematical Sciences, Isfahan University of Technology, Isfahan 84156-83111, Iran. Email address: m.kelkinnama@iut.ac.ir
** Postal address: Department of Statistics, University of Isfahan, Isfahan 81744, Iran, & School of Mathematics, Institute of Research in Fundamental Sciences (IPM), PO Box 19395-5746, Tehran, Iran. Email address: m.asadi@sci.ui.ac.ir

© The Author(s), 2022. Published by Cambridge University Press on behalf of Applied Probability Trust.
in parallel. In this case, the lifetime of the resulting parallel subsystem equals the maximum lifetime of the connected components. This strategy is mostly applied when replacement of the components during the operation time of the system is impossible. As redundancy allocation is a widely used method for improving the performance of products, numerous researchers have paid attention to developing the theories and applications of this subject. For example, Li and Ding [21] investigated the allocation of active redundancies to a $k$-out-of-$n$ system in which the lifetimes of independent components are stochastically ordered. You et al. [32] studied $k$-out-of-$n$ redundant systems with dependent components. Eryilmaz and Ucum [8] determined the optimal number of spare components for a weighted $k$-out-of-$n$. Bayramoglu Kavlak [2] investigated the reliability and the mean residual life functions of coherent systems with active redundancies at the component and system levels. Zhang [34] investigated the optimal allocation of active redundancies for weighted $k$-out-of-$n$. Zhang et al. [35] compared the component redundancy versus system redundancy for coherent systems with dependent and identically distributed components. Fang and Li [12] studied the allocation of one active redundancy to coherent systems consisting of heterogeneous and statistically dependent components. Utilizing the minimal path decomposition, they proposed a necessary and sufficient condition identifying a better allocating strategy from two candidates. Fang and Li [13] investigated allocating multiple matched active redundant components to coherent systems. Fang and Li [14] studied the coherent systems with one active redundancy, using the minimal cut decomposition of the system. Torrado et al. [31] studied the redundancy allocation for a coherent system formed by modules, under different settings related to dependency and distribution of components. They stochastically compared the redundancies at the component level versus redundancies at the module level. Torrado [30] considered a coherent system having possibly dependent subsystems in which the components are connected in parallel or in series. It is assumed that a number of possibly dependent components in each subsystem are randomly selected from a heterogeneous population. Torrado stochastically compared such systems with different numbers of components, based on majorization orders, and determined the optimal numbers of components in each subsystem such that the system reliability is maximized. In particular, she examined the results for series-parallel systems. The redundancy allocation in a series-parallel system has also been considered by some authors, among which we refer to Soltani et al. [29], Karimi et al. [20], and Fang et al. [15].

It is worth noting that the redundant components can be added to the system as inactive (cold and warm standby) components. Systems with cold and warm standby redundancy have also been investigated in the reliability literature; see, for example, Eryilmaz [6], Finkelstein et al. [17], Shen et al. [28], and Behboudi et al. [3].

1.2. Survival signatures of coherent systems

The first main step to assess the reliability and stochastic characteristics of an $n$-component system is to get knowledge about the structure function of the system as well as the probability distribution of component lifetimes. In this regard, a useful concept for assessing the reliability of the system through the reliability of its components is the notion of survival signature. This concept is particularly significant for describing the structures of coherent systems with multiple types of components. Consider an $n$-component coherent system consisting of $L$ different types, such that there are $n_i$ components from the $i$th type, $i = 1, \ldots, L$, and $\sum_{i=1}^{L} n_i = n$. The reliability function of the system, at any time $t$, can be represented as follows:

$$\bar{F}_T(t) = \sum_{l_1=0}^{n_1} \cdots \sum_{l_L=0}^{n_L} \Phi(l_1, \ldots, l_L) \mathbb{P}(C_1(t) = l_1, \ldots, C_L(t) = l_L),$$

(1.1)
where $C_i(t)$ denotes the number of components of type $i$ working at time $t$, and $\Phi$ is called the survival signature and represents ‘the probability that the system is working when exactly $t_i$ components of type $i$ is working’; see Coolen and Coolen-Maturi [4].

Suppose that the lifetimes of the components of the same type are exchangeable dependent and the lifetimes of the components of different types are dependent. Commonly, the dependency structure is modeled using a survival copula. In other words, if $T_j^{(i)}$ denotes the lifetime of the $j$th component from type $i$, $j = 1, \ldots, n$, $i = 1, \ldots, L$, and $\bar{F}_i$, $i = 1, \ldots, L$ denotes the common reliability function for the components of the $i$th type, then there is a survival copula $\hat{C}$ such that the joint reliability of $T_j^{(i)}$ can be written as

$$
\mathbb{P}(T_1^{(1)} > t_1^{(1)}, \ldots, T_{n_1}^{(1)} > t_{n_1}^{(1)}, T_1^{(L)} > t_1^{(L)}, \ldots, T_{n_L}^{(L)} > t_{n_L}^{(L)}) = \hat{C}(\bar{F}_1(t_1^{(1)}), \ldots, \bar{F}_1(t_{n_1}^{(1)}), \ldots, \bar{F}_L(t_1^{(L)}), \ldots, \bar{F}_L(t_{n_L}^{(L)})).
$$

(1.2)

See, for example, Navarro [24], Navarro et al. [25], and Fang and Li [14]. In this case it can be shown that

$$
\bar{F}_T(t) = \sum_{l_1=0}^{n_1} \cdots \sum_{l_L=0}^{n_L} \frac{1}{n_1^{i_1} \cdots i_L^{i_L}} \Phi(l_1, \ldots, l_L, \frac{u}{m}) \hat{C}(\frac{1}{n_1^{i_1} \cdots i_L^{i_L}}, \ldots, \frac{1}{n_1^{i_1} \cdots i_L^{i_L}}),
$$

(1.3)

where

$$
\frac{u}{m}
$$

denotes the $m$ repetitions of $u$; see Eryilmaz et al. [9, 10]. If the components of the system are independent, then the representation (1.1) is converted to the following expression:

$$
\bar{F}_T(t) = \sum_{l_1=0}^{n_1} \cdots \sum_{l_L=0}^{n_L} \Phi(l_1, \ldots, l_L) \prod_{i=1}^{L} \left( \frac{n_i}{l_i} \right) [\bar{F}_i(t)]^{l_i} [F_i(t)]^{n_i-l_i}.
$$

(1.4)

Many authors have considered the reliability properties of a coherent system with multi-type components based on the survival signature, and for various applications. Among these we mention recent papers by Feng et al. [16], Samaniego and Navarro [27], and Eryilmaz et al. [9, 10]. Huang et al. [19] used the notion of survival signature for the formulation of the reliability-redundancy allocation problem. They considered the objective function to maximize the system reliability under some constraints.

Zarezadeh and Asadi [33] studied the reliability and preventive maintenance of coherent systems with multi-type components whose components are subject to failure according to multiple external shocks. Hashemi et al. [18] proposed two maintenance strategies for optimal preservation of coherent systems consisting of independent multi-type components.

1.3. Contributions of this paper

This paper aims to study the optimal number of redundancy allocation to $n$-component coherent systems consisting of different components. It is assumed that the components of the
system are dependent, where a given copula function models the dependency structure. We are interested in allocating $v_i$ active redundant components to each component of type $i$, under the constraint on the number of existing spare components. To get the optimal number of $v_i$, we propose two cost-based functions. More precisely, the contributions of the paper are as follows.

- We propose a mean cost rate function in terms of the costs of renewing the failed components and the costs of refreshing the alive components at the time of the system failure. Then we find the optimal number of redundant components, $v_i$, to be added to each component of type $i$, such that the proposed cost function is minimized.

- We introduce a mean cost rate function, relevant to an age replacement policy, in terms of the costs of renewing (refreshing) the failed (alive) components at the failure time of the system or at a predetermined time $\tau$, whichever occurs first. Then the optimal values of $v_i$ are obtained, such that the suggested cost-based function achieves its minimum value.

- In the particular important case that the system is a series-parallel system, we provide the formulas for the proposed mean cost rate functions. Then we investigate the optimal number of the components for each parallel subsystem such that the proposed functions are minimized.

The derivations of the paper are extensions of the results of Eryilmaz [7], who investigated the optimal number of components in the case that the structure function is $k$-out-of-$n$ with independent components.

1.4. Organization of the paper

The remainder of the paper is arranged as follows. In Section 2, using the settings of Section 1.2, we present the formulation of the system reliability function (1.3) in the case that $v_i$ components are added as active redundant to each component of type $i$, $i = 1, \ldots, L$. Then, utilizing this formulation, a mean cost rate function is introduced at the time of the system failure. Next, a mean cost rate function is established based on the costs of replacing the system at its failure time or at a predetermined time $\tau$, whichever occurs first. The expressions for the proposed mean cost rate functions are derived in terms of the reliability function (1.3). Some examples of coherent systems are presented to illustrate the applications of the proposed approaches; a 6-component system consisting of two types of dependent components, and an 8-component system composed of three types of components that are independent. The optimal number of redundant components, based on the proposed cost-based functions, are discussed for each system numerically. Section 3 is devoted to the particular case that the system is a series-parallel system. In Section 2 we provide the formulas for the proposed mean cost rate functions for such systems. Then we investigate the optimal number of the components for each parallel subsystem such that the proposed cost functions are minimized. The results of this section are numerically illustrated for a series-parallel system consisting of three parallel subsystems connected in series. Some concluding remarks in Section 4 finalize the paper. Detailed proofs are given in the Appendix.

2. Optimal number of redundant components

We consider an $n$-component coherent system consisting of multiple types of components with the following description. The system is built up of $L$ types of components, $L \geq 1$, such
that there are \( n_i \) components of type \( i \) and \( \sum_{i=1}^{L} n_i = n \). We assume that the common reliability function of the components of type \( i \) is \( \bar{F}_i(.) \), \( i = 1, 2, \ldots, L \). The lifetimes of the components of the same type are exchangeable dependent and the lifetimes of the components of different types are dependent. The assumed dependency structure is modeled by a survival copula given in (1.2). To increase the reliability of the system, we wish to add \( v_i \) active redundancies to each component of type \( i \), \( i = 1, \ldots, L \). Each original component in the system and its redundant components are assumed to be independent and identically distributed (i.i.d.). Let \( T_R \) denote the lifetime of the system incorporated by redundant components. Because an original component and its redundant ones make a parallel subsystem, one can easily show that the reliability function of \( T_R \) at time \( t \) can be represented as follows:

\[
\bar{F}_R(t) = \sum_{i_1=0}^{n_1} \cdots \sum_{i_L=0}^{n_L} (-1)^{i_1+\cdots+i_L} \left( \begin{array}{c} n_1 \\ i_1 \\ \vdots \\ i_L \\ n_L \end{array} \right) \phi_1^{i_1} \cdots \phi_L^{i_L} \prod_{i=1}^{L} \left[ 1 - F_i^{v_i+1}(t) \right]^{n_i-i_1} \left[ F_i^{v_i+1}(t) \right]^{n_i-i_L}.
\]

The problem of interest in this redundancy strategy is to determine the optimal number of spares allocated to each component. In this paper our approach is to find \( v \) based on the minimization of a kind of cost criterion. In this regard we set up two mean cost rate functions to obtain the optimal number of redundant components. One of them is imposed based on the cost of the system failure, which depends on the number of failed components when a system failure occurs. The other one is defined based on an age replacement policy. In the next subsections, we describe these two functions with details.

**Remark 2.1.** Although the system considered above is described in the general case that the component lifetimes of the same type are exchangeable dependent and the lifetimes of the components of different types are dependent, in allocating the redundant components we assumed that in the constructed parallel subsystem the components are i.i.d. This assumption seems to be a restriction in some practical cases, but it should be noted that if we drop the i.i.d. assumption for the redundant components, the computation of the system reliability would be a challenging problem and potentially involve complex calculations. We believe that considering the problem of optimal redundancy under i.i.d. components in each subsystem, as is done in this paper, could be a first step towards solving the more general cases; see also Samaniego [26, pp. 76–77].

### 2.1. Cost function at system failure

Suppose that the system starts working at \( t = 0 \) and fails at a random time after \( t = 0 \). Assume that when the system fails we have a cost \( c_i \) for each failed component of type \( i \) to replace it with a new one and a cost \( c_i^* \) for each unfailed component to refresh it so that it becomes as good as new, where we assume that \( c_i \geq c_i^* \), \( i = 1, \ldots, L \). Furthermore, we assume that \( c^{**} \) denotes the fixed overall cost for system failure. With \( T_R \) as the lifetime of the system
after redundancy, let the random variable $X_i(T_R)$ denote the number of failed components of type $i$ at the time of system failure, $i = 1, \ldots, L$. Then the mean cost rate function for a failed system is defined as

$$
\text{Cost}_1(v) = \frac{\sum_{i=1}^L c_i E(X_i(T_R)) + \sum_{i=1}^L c_i^*(v_i + 1) - X_i(T_R)) + e^{**}}{E(T_R)}, \tag{2.1}
$$

where $v = (v_1, \ldots, v_L)$. The numerator is the expected cost of the system failure, and the denominator is the mean time to failure (MTTF) of the system, so $\text{Cost}_1$ becomes the mean cost per unit of time. Note that in the system after redundancy, there are altogether $n_i(v_i + 1)$ components of type $i$, $i = 1, 2, \ldots, L$. The relation (2.1) can be rewritten in terms of the lifetime of the original system without any redundancy, $T$, as

$$
\text{Cost}_1(v) = \frac{\sum_{i=1}^L c_i(v_i + 1)E(X_i(T)) + \sum_{i=1}^L c_i^*(v_i + 1) - X_i(T) + e^{**}}{E(T_R)}, \tag{2.2}
$$

**Lemma 2.1.** The quantity $E(X_i(T))$ in (2.2) can be expressed as follows:

$$
E(X_i(T)) = n_i \int_0^\infty \lim_{\delta \to 0} \frac{1}{\delta} \sum_{m_1=0}^{n_1} \cdots \sum_{m_{i-1}=0}^{n_{i-1}} \sum_{m_i=0}^{n_i} \sum_{m_{i+1}=0}^{n_{i+1}} \sum_{m_L=0}^{n_L} \Phi(m_1, \ldots, m_{i-1}, m_i + 1, m_{i+1}, \ldots, m_L) \times \left(\frac{n_1}{m_1}\right) \cdots \left(\frac{n_i - 1}{m_i}\right) \cdots \left(\frac{n_L}{m_L}\right) A_m(t, \delta) dt,
$$

where

$$
A_m(t, \delta) = P(T_1^{(1)} > t, \ldots, T_m^{(1)} > t, T_{m+1}^{(1)} \leq t, \ldots, T_{n_i}^{(1)} \leq t, \ldots, T_2^{(1)} \leq t + \delta, T_2^{(1)} > t, \ldots, T_{m+1}^{(1)} > t, T_{m+2}^{(1)} \leq t, \ldots, T_{n_i}^{(1)} \leq t, \ldots, T_1^{(L)} > t, \ldots, T_{m_L}^{(L)} > t, T_{m_L+1}^{(L)} \leq t, \ldots, T_{n_L}^{(L)} \leq t). \tag{2.3}
$$

**Proof.**

$$
E(X_i(T)) = E\left(\sum_{j=1}^{n_i} I(T_j^{(i)} \leq T)\right) = \sum_{j=1}^{n_i} P(T_j^{(i)} \leq T) = n_i P(T_1^{(i)} \leq T)
$$

$$
= n_i \int_0^\infty \lim_{\delta \to 0} \frac{P(T > t, t < T_1^{(i)} \leq t + \delta)}{\delta} dt,
$$
where the third equality follows from the exchangeability of the components of type \( i \), \( i = 1, \ldots, L \). By conditioning on the number of live components of each type, we obtain

\[
\mathbb{P}(T > t, t < T_1^{(i)} \leq t + \delta)
\]

\[
= \sum_{m_1=0}^{n_1} \cdots \sum_{m_i=0}^{n_i-1} \cdots \sum_{m_L=0}^{n_L} \mathbb{P}(T > t, t < T_1^{(i)} \leq t + \delta, C_j(t) = m_j, j = 1, \ldots, L)
\]

\[
= \sum_{m_1=0}^{n_1} \cdots \sum_{m_i=0}^{n_i-1} \cdots \sum_{m_L=0}^{n_L} \Phi(m_1, \ldots, m_{i-1}, m_i + 1, m_{i+1}, \ldots, m_L) \left( \frac{n_1}{m_1} \right) \cdots \left( \frac{n_i - 1}{m_i} \right) \cdots \left( \frac{n_L}{m_L} \right)
\]

\[
\times A_m^{(i)}(t, \delta).
\] (2.4)

The last equality in (2.4) holds because the components of the same type have a common failure time distribution. □

In the following theorem, (2.3) is represented based on the survival copula of the component lifetimes.

**Theorem 2.1.** Using the inclusion–exclusion rule, \( A_m^{(i)}(t, \delta) \) can be represented as follows:

\[
A_m^{(i)}(t, \delta)
\]

\[
= \sum_{j_1=0}^{n_1-m_1} \cdots \sum_{j_i=0}^{n_i-m_i} \cdots \sum_{j_L=0}^{n_L-m_L} (-1)^{j_1 + \cdots + j_L} \left( \frac{n_1 - m_1}{j_1} \right) \cdots \left( \frac{n_i - m_i - 1}{j_i} \right) \cdots \left( \frac{n_L - m_L}{j_L} \right)
\]

\[
\times \left[ \hat{C} \left( F_{1(t)}^{(i)}, \frac{1}{m_1+j_1}, \ldots, F_{i(t)}^{(i)}, \frac{1}{m_i+j_i}, \ldots, F_L(t), \frac{1}{m_L+j_L} \right) \right.
\]

\[
- \hat{C} \left( F_{1(t)}^{(i)}, \frac{1}{m_1+j_1}, \ldots, F_{i(t)}^{(i)}, \frac{1}{m_i+j_i}, \ldots, F_L(t), \frac{1}{m_L+j_L} \right) \right].
\]

**Proof.** See Appendix A. □

Note that in the particular case of independence of all components, we get

\[
\mathbb{E}(X_i(T))
\]

\[
= n_i \sum_{m_1=0}^{n_1} \cdots \sum_{m_i=0}^{n_i-1} \cdots \sum_{m_L=0}^{n_L} \Phi(m_1, \ldots, m_{i-1}, m_i + 1, m_{i+1}, \ldots, m_L)
\]

\[
\times \left( \frac{n_1}{m_1} \right) \cdots \left( \frac{n_i - 1}{m_i} \right) \cdots \left( \frac{n_L}{m_L} \right)
\]

\[
\times \int_0^{\infty} F_i^{m_1(t)} F_{i-1}^{m_1(t)} \cdots F_i^{m_i(t)} F_{i-1}^{m_i(t)} \cdots F_L^{m_L(t)} \, dF_i(t).
\] (2.5)
In order to minimize the mean cost rate function $\text{Cost}_1(v)$, we impose the constraint that there are at most $M_i$ components of type $i$ as spares, $i = 1, \ldots, L$. This means that the number of the components that can be connected in parallel at the $i$th group satisfies the inequality $n_i v_i \leq M_i$, $i = 1, \ldots, L$. To determine the optimal values of $v_i$, we do the following: for given values of $n_i$, $c_i$, $c^*_i$, and $M_i$, $i = 1, \ldots, L$, and $c^{**}$, we evaluate $\text{Cost}_1(v)$ for all possible choices of $v_1, \ldots, v_L$ such that for all $i, n_i v_i \leq M_i$. Then the optimal values of $v_1, \ldots, v_L$ can be determined as the values for which the corresponding mean cost rate function $\text{Cost}_1(v)$ is minimum.

Remark 2.2. If the system has a $k$-out-of-$n$ structure with independent components from multiple type components, then (2.5) reduces to the result of Eryilmaz [7]. This is so because for such systems the survival signature is obviously given by

$$\Phi(l_1, \ldots, l_L) = \begin{cases} 1, & \sum_{j=1}^L l_j \geq k, \\ 0, & \text{otherwise,} \end{cases}$$

i.e. the system works if at least $k$ components are alive.

2.2. Cost function based on preventive replacement

In this section we propose a kind of age replacement preventive maintenance policy for the system with multiple types of components described in Section 1.2. The policy of renewing the system performed by the operator is such that it is replaced at failure time or at a predetermined time $\tau$, whichever occurs first. There are many papers on age replacement strategy; the interested reader can refer to Zhao et al. [36], Ashrafi and Asadi [1], and Mizutani et al. [23], for example. Mannai and Gasmi [22] found the optimal configuration of a $k$-out-of-$n$ system so that the expected total costs of the system under some generalized age replacement policies are minimized.

Here, suppose that the operator has $M_i$ components of type $i$ available as spares, and he/she decides to add $v_i$ components to each of the components of type $i$, where $n_i v_i \leq M_i$. Under the implemented policy here, the aim is to find the optimal number of $v$ such that the mean cost rate we impose below is minimized.

If the replacement occurs after the system failure, i.e. $T_R \leq \tau$, then, considering the costs $c_i$, $c^*_i$, and $c^{**}$ as defined in the previous subsection, the average cost of renewing the system is obtained as

$$M_1(v) = \sum_{i=1}^L c_i \mathbb{E}(X_i(T_R) \mid T_R \leq \tau) + \sum_{i=1}^L c^*_i \mathbb{E}(n_i(v_i + 1) - X_i(T_R) \mid T_R \leq \tau) + c^{**}$$

$$= \sum_{i=1}^L (v_i + 1)c_i \mathbb{E}(X_i(T) \mid T \leq \tau) + \sum_{i=1}^L (v_i + 1)c^*_i \mathbb{E}(n_i - X_i(T) \mid T \leq \tau) + c^{**}$$

$$= \sum_{i=1}^L (c_i - c^*_i)(v_i + 1)\mathbb{E}(X_i(T) \mid T \leq \tau) + \sum_{i=1}^L (v_i + 1)c^*_i n_i + c^{**},$$

where $T$ is the lifetime of the system before redundancy allocation.
If the system is replaced before failure, i.e. $T_R > \tau$, then, by the costs $c_i$ and $c_i^*, i = 1, \ldots, L$ for renewing the failed components and refreshing the alive components of type $i$, respectively, the system will be as good as the new condition. Let $N_i(\tau)$ be the number of failed components of type $i$ on $[0, \tau]$. Then the average cost of renewing the system is defined as

$$M_2(v) = \sum_{i=1}^{L} c_i \mathbb{E}(N_i(\tau) \mid T_R > \tau) + \sum_{i=1}^{L} c_i^* \mathbb{E}(n_i(\tau) \mid T_R > \tau)$$

$$= \sum_{i=1}^{L} (c_i - c_i^*)(\tau + 1) \mathbb{E}(N_i(\tau) \mid T > \tau) + \sum_{i=1}^{L} (\tau + 1)c_i^* n_i.$$ 

Consequently, the mean cost rate function of the system renewing at time min$(\tau, T_R)$ is achieved as

$$\text{Cost}_2(v) = \frac{M_1(v) \mathbb{P}(T_R \leq \tau) + M_2(v) \mathbb{P}(T_R > \tau)}{\mathbb{E}(\min(\tau, T_R))},$$

(2.6)

where it is attained that

$$\mathbb{E}(\min(\tau, T_R)) = \int_{0}^{\tau} \bar{F}_T(y) \, dy.$$ 

To compute (2.6), we need to calculate $\mathbb{E}(N_i(\tau) \mid T > \tau)$ and $\mathbb{E}(X_i(T) \mid T \leq \tau)$. For the first one, we have

$$\mathbb{E}(N_i(\tau) \mid T > \tau)$$

$$= \frac{1}{\bar{F}_T(\tau)} \sum_{j_i=0}^{n_i} j_i \mathbb{P}(N_i(\tau) = j_i, T > \tau)$$

$$= \frac{1}{\bar{F}_T(\tau)} \sum_{j_1=0}^{n_1} \cdots \sum_{j_L=0}^{n_L} j_1 \mathbb{P}(T > \tau \mid N_1(\tau) = j_1, \ldots, N_L(\tau) = j_L) \mathbb{P}(N_1(\tau) = j_1, \ldots, N_L(\tau) = j_L)$$

$$= \frac{1}{\bar{F}_T(\tau)} \sum_{j_1=0}^{n_1} \cdots \sum_{j_L=0}^{n_L} j_1 \Phi(n_1 - j_1, \ldots, n_L - j_L) \left( \binom{n_1}{j_1} \cdots \binom{n_L}{j_L} B(\tau, j_1, \ldots, j_L), \right),$$

(2.7)

where

$$B(\tau, j_1, \ldots, j_L) = \mathbb{P}(T_1^{(1)} \leq \tau, \ldots, T_{j_1}^{(1)} \leq \tau, T_{j_1+1}^{(1)} > \tau, \ldots, T_{n_1}^{(1)} > \tau, \ldots, T_{j_L}^{(L)} \leq \tau, \ldots, T_{j_{L+1}}^{(L)} > \tau, \ldots, T_{n_L}^{(L)} > \tau).$$

(2.8)

Using a method similar to that used in Lemma 2.1, we can calculate $\mathbb{E}(X_i(T) \mid T \leq \tau)$, $i = 1, \ldots, L$ as follows:

$$\mathbb{E}(X_i(T) \mid T \leq \tau) = n_i \mathbb{P}(T_i \leq \tau \mid T \leq \tau) = n_i \frac{\mathbb{P}(T_i^{(1)} \leq T, T \leq \tau)}{1 - \mathbb{P}(T > \tau)}, \quad j = 1, \ldots, L.$$
Now we can write

\[
\mathbb{P}(T_1^{(i)} \leq T, T \leq \tau) = \int_0^\tau \lim_{\delta \to 0} \frac{\mathbb{P}(s < T \leq \tau, s < T_1^{(i)} \leq s + \delta)}{\delta} \, ds, \quad i = 1, \ldots, L,
\]

for which we have

\[
\mathbb{P}(s < T \leq \tau, s < T_1^{(i)} \leq s + \delta)
= \sum_{m_1=0}^{n_1-1} \cdots \sum_{m_L=0}^{n_L-1} \sum_{l_1=0}^{m_1} \cdots \sum_{l_L=0}^{m_L} \mathbb{P}(s < T \leq \tau \mid s < T_1^{(i)} \leq s + \delta, C_1(\tau) = l_1, \ldots, C_l(\tau) = l_L, C_1(s) = m_1, \ldots, C_l(s) = m_l, \ldots, C_L(s) = m_L)
\times \mathbb{P}(s < T_1^{(i)} \leq s + \delta, C_1(\tau) = l_1, \ldots, C_l(\tau) = l_L, C_1(s) = m_1, \ldots, C_l(s) = m_l, \ldots, C_L(s) = m_L)
\]

\[
= \sum_{m_1=0}^{n_1-1} \cdots \sum_{m_L=0}^{n_L-1} \sum_{l_1=0}^{m_1} \cdots \sum_{l_L=0}^{m_L} [\Phi(m_1, \ldots, m_L) - \Phi(l_1, \ldots, l_L)] \prod_{j=1, j \neq i}^L \left( \frac{n_j}{m_j} \right) \left( \frac{m_j}{l_j} \right)
\]

\[\times \left( \frac{n_i - 1}{m_i} \right) \left( \frac{m_i}{l_i} \right) A_{m,1}^{(i)}(s, s + \delta, \tau),\]

where

\[
A_{m,1}^{(i)}(s, s + \delta, \tau)
= \mathbb{P}(T_1^{(1)} > \tau, \ldots, T_{l_1}^{(1)} > \tau, s < T_1^{(1)} \leq \tau, \ldots, s < T_{m_1}^{(1)} \leq \tau, T_{m_1+1}^{(1)} \leq s, \ldots, T_{n_1}^{(1)} \leq s, \ldots)
\]

\[
T_1^{(i)} > \tau, \ldots, T_{l_i}^{(i)} > \tau, s < T_1^{(i)} \leq \tau, \ldots, s < T_{m_i}^{(i)} \leq \tau, s < T_{m_i+1}^{(i)} \leq s + \delta,
\]

\[
T_{m_i+2}^{(i)} \leq s, \ldots, T_{n_i}^{(i)} \leq s, \ldots, T_1^{(L)} > \tau, \ldots, T_{l_L}^{(L)} > \tau, s < T_1^{(L)} \leq \tau, \ldots, s < T_{m_L}^{(L)} \leq \tau,
\]

\[
T_{m_L+1}^{(L)} \leq s, s \ldots, T_{n_L}^{(L)} \leq s). \quad (2.9)
\]

In the following theorem, the probabilities in (2.8) and (2.9) are represented based on the survival copula of component lifetimes.

**Theorem 2.2.** Using the inclusion–exclusion rule, we obtain the following expressions for \(B(\tau, j_1, \ldots, j_L)\) and \(A_{m,1}^{(i)}(s, s + \delta, \tau)\), respectively:

\[
B(\tau, j_1, \ldots, j_L)
= \sum_{b_1=0}^{j_1} \cdots \sum_{b_L=0}^{j_L} (-1)^{b_1 + \cdots + b_L} \binom{j_1}{b_1} \cdots \binom{j_L}{b_L} \hat{C}\left(\frac{\tilde{F}_1(\tau)}{n_1-j_1+b_1} \cdot \frac{1}{j_1-b_1}, \ldots, \frac{\tilde{F}_L(\tau)}{n_L-j_L+b_L} \cdot \frac{1}{j_L-b_L}\right)
\]

\[
A_{m,1}^{(i)}(s, s + \delta, \tau)
= \mathbb{P}(T_1^{(1)} > \tau, \ldots, T_{l_1}^{(1)} > \tau, s < T_1^{(1)} \leq \tau, \ldots, s < T_{m_1}^{(1)} \leq \tau, T_{m_1+1}^{(1)} \leq s, \ldots, T_{n_1}^{(1)} \leq s, \ldots)
\]

\[
T_1^{(i)} > \tau, \ldots, T_{l_i}^{(i)} > \tau, s < T_1^{(i)} \leq \tau, \ldots, s < T_{m_i}^{(i)} \leq \tau, s < T_{m_i+1}^{(i)} \leq s + \delta,
\]

\[
T_{m_i+2}^{(i)} \leq s, \ldots, T_{n_i}^{(i)} \leq s, \ldots, T_1^{(L)} > \tau, \ldots, T_{l_L}^{(L)} > \tau, s < T_1^{(L)} \leq \tau, \ldots, s < T_{m_L}^{(L)} \leq \tau,
\]

\[
T_{m_L+1}^{(L)} \leq s, \ldots, T_{n_L}^{(L)} \leq s). \quad (2.9)
\]
Also, in this case we have

\[
A_{m,1}^{(i)}(s, s + \delta, \tau) = \sum_{j_1=0}^{m_1-l_1} \cdots \sum_{j_L=0}^{m_L-l_L} (1)^{j_1+\cdots+j_L} \left( \sum_{d_1=0}^{m_1-l_1} \cdots \sum_{d_L=0}^{m_L-l_L} (-1)^{d_1+\cdots+d_L} \right) \times \left[ \hat{C}\left( \tilde{F}_k(\tau), \tilde{F}_k(s), \cdots, 1 \right) \right]
\]

For the particular case of independent components, it can be deduced that

\[
\mathbb{E}(N_i(\tau) \mid T > \tau) = \frac{1}{\tilde{F}(\tau)} \sum_{j_1=0}^{n_1} \cdots \sum_{j_L=0}^{n_L} \left( \sum_{j_1=0}^{n_1} \cdots \sum_{j_L=0}^{n_L} \right) F_{n_1-j_1, \ldots, n_L-j_L} \prod_{l=1}^{L} \left( \frac{n_l}{j_l} \right) \tilde{F}_l(\tau) \tilde{F}_l^{n_l-j_l}(\tau).
\]

(2.10)

Also, in this case we have

\[
A_{m,1}^{(i)}(s, s + \delta, \tau) = \left\{ \prod_{j=1, j \neq i}^{L} F_j^{n_i-m_i}(s) \left[ \tilde{F}_i(\tau) - \tilde{F}_i(s) \right] \right\} \times [\tilde{F}_i(s) - \tilde{F}_i(s + \delta)] \tilde{F}_i^{m_i-l_i}(\tau),
\]

which in turn implies that

\[
\mathbb{E}(X_i(T) \mid T \leq \tau) = \frac{n_i}{1 - \tilde{F}_i(T)} \sum_{m_1=0}^{n_1} \cdots \sum_{m_L=0}^{n_L} \left[ \prod_{j=1}^{L} \left( \frac{n_j}{m_j} \right) \left( \frac{m_j}{l_j} \right) \right] \times \left[ \prod_{j=1}^{L} \left( \frac{n_l}{m_l} \right) \left( \frac{m_l}{l_l} \right) \right] \times \int_0^\tau \left\{ \prod_{j=1, j \neq i}^{L} F_j^{n_i-m_i}(s) \left[ \tilde{F}_i(\tau) - \tilde{F}_i(s) \right] \right\} \tilde{F}_i^{n_i-m_i-1}(s) \tilde{F}_i(l_i) \tilde{F}_i^{l_i}(s) \ dF_i(s).
\]

(2.11)
It is worth noting that if the structure of the system is $k$-out-of-$n$ whose components are independent, then (2.10) and (2.11) are reduced to the results that appeared in Eryilmaz [7].

For given values $n_i$, $c_i$, $c_i^*$, $M_i$, $i = 1, \ldots, L$, $c^{**}$ and $\tau$, we aim to determine the optimal values of $v_i$ under the constraints $n_i v_i \leq M_i$, $i = 1, \ldots, L$, such that the mean cost rate function $\text{Cost}_2$ is minimized.

In the following, we present two examples to examine the aforementioned theoretical results.

**Example 2.1.** Consider the system depicted in Figure 1, given in Feng et al. [16] and Eryilmaz et al. [10]. The system consists of six components in which components 1, 2, and 5 are of type 1 and components 3, 4, and 6 are of type 2. The survival signature of the system is presented in Table 1. Assume that the dependency structure of the component lifetimes is modeled by a parametric family of copulas known as the Gumbel–Hougaard family, defined as

$$\hat{C}(u_1, \ldots, u_n) = \exp\left(-\left[-(\ln u_1)^{\alpha} + \cdots + (\ln u_n)^{\alpha}\right]^{1/\alpha}\right),$$

where $\alpha \geq 1$ is the dependency parameter in the family. The value $\alpha = 1$ corresponds to the independent condition. Let the component lifetimes of the two types follow exponential distributions with reliability functions $\bar{F}_i(t) = e^{-t \theta_i}$, where we assume that $\theta_1 = 0.2$ and $\theta_2 = 0.3$. If there are $M_1 = 9$ and $M_2 = 6$ components from type 1 and type 2, respectively, as spares, then $v_1 \in \{0, 1, 2, 3\}$ and $v_2 \in \{0, 1, 2\}$. To find the optimal number of redundant components for each type, we use the following values for the replacement costs: $c_1 = 3$, $c_2 = 2$, $c_1^* = 1.5$, $c_2^* = 1$, and $c^{**} = 10$. To compute the numerator of (2.2), we need to compute $\mathbb{E}(X_1(T))$, $i = 1, 2$. From Lemma 2.1 and Theorem 2.1, we have

$$\mathbb{E}(X_1(T)) = n_1 \int_0^\infty \lim_{\delta \to 0} \frac{1}{\delta} \sum_{m_1 = 0}^{n_1 - 1} \sum_{m_2 = 0}^{n_2} \Phi(m_1 + 1, m_2) \binom{n_1 - 1}{m_1} \binom{n_2}{m_2} A_{m}^{(1)}(t, \delta) \, dt,$$

where

$$A_{m}^{(1)}(t, \delta) = \sum_{j_1 = 0}^{n_1 - m_1 - 1} \sum_{j_2 = 0}^{n_2 - m_2} (-1)^{j_1 + j_2} \binom{n_1 - m_1 - 1}{j_1} \binom{n_2 - m_2}{j_2} \times \left[e^{-[(m_1 + j_1)(\theta_1)^\alpha + (m_2 + j_2)(\theta_2)^\alpha]^{1/\alpha}} - e^{-[(m_1 + j_1)(\theta_1)^\alpha + (m_2 + j_2)(\theta_2)^\alpha]^{1/\alpha}}\right].$$

**Figure 1.** The system in Example 2.1 with two types of components.
TABLE 1. Survival signature of the system in Figure 1.

| $l_1$ | $l_2$ | $\Phi(l_1, l_2)$ | $l_1$ | $l_2$ | $\Phi(l_1, l_2)$ |
|-------|-------|------------------|-------|-------|------------------|
| 0     | 0     | 0                | 2     | 0     | 0                |
| 0     | 1     | 0                | 2     | 1     | 0                |
| 0     | 2     | 0                | 2     | 2     | $4/9$            |
| 0     | 3     | 0                | 2     | 3     | $2/3$            |
| 1     | 0     | 0                | 3     | 0     | 1                |
| 1     | 1     | 0                | 3     | 1     | 1                |
| 1     | 2     | $1/9$            | 3     | 2     | 1                |
| 1     | 3     | $1/3$            | 3     | 3     | 1                |

Thus we get

$$\mathbb{E}(X_1(T)) = n_1 \sum_{m_1=0}^{n_1-1} \sum_{m_2=0}^{n_2} \binom{n_1-1}{m_1} \binom{n_2}{m_2} \Phi(m_1 + 1, m_2)$$

$$\times \sum_{j_1=0}^{n_1-m_1-1} \sum_{j_2=0}^{n_2-m_2-1} (-1)^{j_1+j_2} \binom{n_1-m_1-1}{j_1} \binom{n_2-m_2}{j_2} \times \theta_1^\alpha \left[(m_1 + j_1 + 1)\theta_1^\alpha + (m_2 + j_2)\theta_2^\alpha \right]^{-1}.$$ 

Similarly, we have

$$\mathbb{E}(X_2(T)) = n_2 \sum_{m_1=0}^{n_1-1} \sum_{m_2=0}^{n_2} \binom{n_1}{m_1} \binom{n_2-1}{m_2} \Phi(m_1, m_2 + 1)$$

$$\times \sum_{j_1=0}^{n_1-m_1-1} \sum_{j_2=0}^{n_2-m_2-1} (-1)^{j_1+j_2} \binom{n_1-m_1}{j_1} \binom{n_2-m_2-1}{j_2} \times \theta_2^\alpha \left[(m_1 + j_1)\theta_1^\alpha + (m_2 + j_2 + 1)\theta_2^\alpha \right]^{-1}.$$ 

Also, the denominator of (2.2) can be written as follows:

$$\mathbb{E}(T_R) = \int_0^\infty \tilde{F}_{T_R}(t) \, dt$$

$$= \sum_{l_1=0}^{n_1} \sum_{l_2=0}^{n_2} \binom{n_1}{l_1} \binom{n_2}{l_2} \Phi(l_1, l_2) \sum_{i_1=0}^{n_1-l_1} \sum_{i_2=0}^{n_2-l_2} (-1)^{i_1+i_2} \binom{n_1-l_1}{i_1} \binom{n_2-l_2}{i_2}$$

$$\times \int_0^\infty e^{-[(i_1+l_1)\ln(1-(1-\exp[-\theta_1^\alpha])^\alpha)]+(i_2+l_2)\ln(1-(1-\exp[-\theta_2^\alpha])^\alpha)]^{1/\alpha}} \, dt.$$
which should be evaluated numerically by suitable softwares such as Mathematica. The values of Cost\(_1(v)\) for different combinations of \(v_1\) and \(v_2\) are presented in Table 2 for two values \(\alpha = 2\) (dependent components) and \(\alpha = 1\) (independent components). It is seen that \(v_1 = 2\) and \(v_2 = 0\) are the optimal choices for the number of redundant components of types 1 and 2, respectively, under the criterion Cost\(_1\) in the case \(\alpha = 2\), and \(v_1 = 3\) and \(v_2 = 0\) are the optimal numbers in the case \(\alpha = 1\).

Suppose that the described system is maintained under the aforementioned age replacement policy, where we assume that \(\tau = 2\), i.e. the replacement time of the system is \(\min(T_R, 2)\). From equations (2.7) and (2.8) the mean number of failed components of \(i\)th type at time \(\tau\), before system failure, is evaluated by the following expression:

\[
\mathbb{E}(N_i(\tau) \mid T > \tau) = \frac{1}{\bar{F}(\tau)} \sum_{j_1=0}^{n_1} \sum_{j_2=0}^{n_2} j_1 \Phi(n_1 - j_1, n_2 - j_2) \binom{n_1}{j_1} \binom{n_2}{j_2} \sum_{b_1=0}^{j_1} \sum_{b_2=0}^{j_2} (-1)^{b_1+b_2} \binom{j_1}{b_1} \binom{j_2}{b_2} \\
\times \exp[- \tau \left( \theta_1^\alpha (n_1 - j_1 + b_1) + \theta_2^\alpha (n_2 - j_2 + b_2) \right)^{1/\alpha}], \quad i = 1, 2,
\]

where from (1.3) we get

\[
\bar{F}(\tau) = \sum_{l_1=0}^{n_1} \sum_{l_2=0}^{n_2} (l_1 + l_2) \Phi(l_1, l_2) \\
\times \exp[- \tau ((i_1 + l_1) \theta_1^\alpha + (i_2 + l_2) \theta_2^\alpha)^{1/\alpha}].
\]

### Table 2. The values of Cost\(_1(v)\) and Cost\(_2(v)\) in Example 2.1 in the case of dependent components (\(\alpha = 2\)) and independent components (\(\alpha = 1\)).

| \(v_1\) | \(v_2\) | Cost\(_1(v_1, v_2)\) \(\alpha = 2\) | Cost\(_2(v_1, v_2)\) \(\alpha = 2\) | Cost\(_1(v_1, v_2)\) \(\alpha = 1\) | Cost\(_2(v_1, v_2)\) \(\alpha = 1\) |
|---|---|---|---|---|---|
| 0 | 0 | 6.33927 | 8.2455 | 9.36071 | 9.70214 |
| 0 | 1 | 6.81922 | 9.44774 | 9.38725 | 10.3790 |
| 0 | 2 | 7.5289 | 11.3022 | 9.87544 | 11.9363 |
| 1 | 0 | 5.20719 | 7.77258 | 7.09069 | 8.48716 |
| 1 | 1 | 5.82298 | 9.2981 | 7.51217 | 9.7885 |
| 1 | 2 | 6.35331 | 10.7302 | 7.98448 | 11.3693 |
| 2 | 0 | 4.99041 | 9.13115 | 6.56325 | 9.88167 |
| 2 | 1 | 5.58924 | 10.7299 | 7.06002 | 11.4307 |
| 2 | 2 | 6.13251 | 12.2892 | 7.53562 | 13.0756 |
| 3 | 0 | 5.04518 | 11.137 | 6.98476 | 13.6766 |
| 3 | 1 | 5.59315 | 12.7178 | 6.98476 | 13.6766 |
| 3 | 2 | 6.11375 | 14.2941 | 7.53562 | 15.3508 |
Next, for the mean number of failed components at the time of the system failure given that the system has failed before \( \tau \), we have

\[
\mathbb{E}(X_1(T) \mid T \leq \tau) = \frac{n_1}{1 - F_T(\tau)} \sum_{m_1=0}^{n_1-1} \sum_{m_2=0}^{n_2-1} \sum_{l_1=0}^{m_1} \sum_{l_2=0}^{m_2} [\Phi(m_1, m_2) - \Phi(l_1, l_2)] \left( \begin{array}{c} n_1 - 1 \\ m_1 \end{array} \right) \left( \begin{array}{c} n_2 - 1 \\ m_2 \end{array} \right) \left( \begin{array}{c} l_1 \\ \frac{m_1}{l_1} \end{array} \right) \left( \begin{array}{c} l_2 \\ \frac{m_2}{l_2} \end{array} \right)
\]

\[
\times \sum_{j_1=0}^{n_1-m_1-1} \sum_{j_2=0}^{n_2-m_2-1} (-1)^{j_1+j_2} \left( \begin{array}{c} n_1 - m_1 - 1 \\ j_1 \end{array} \right) \left( \begin{array}{c} n_2 - m_2 - 1 \\ j_2 \end{array} \right)
\]

\[
\times \sum_{d_1=0}^{m_1-l_1} \sum_{d_2=0}^{m_2-l_2} (-1)^{d_1+d_2} \left( \begin{array}{c} m_1 - l_1 \\ d_1 \end{array} \right) \left( \begin{array}{c} m_2 - l_2 \\ d_2 \end{array} \right) \]

\[
\times \theta_1^\alpha \left[ e^{-\tau(l_1+d_1)\theta_1^\alpha + (l_2+d_2)\theta_2^\alpha}/\alpha - e^{-\tau((m_1+l_1+1)\theta_1^\alpha + (m_2+l_2+1)\theta_2^\alpha)/\alpha} \right]
\]

\[
(m_1 - l_1 + j_1 - d_1 + 1)\theta_1^\alpha + (m_2 - l_2 + j_2 - d_2)\theta_2^\alpha
\]

and

\[
\mathbb{E}(X_2(T) \mid T \leq \tau) = \frac{n_2}{1 - F_T(\tau)} \sum_{m_1=0}^{n_1-1} \sum_{m_2=0}^{n_2-1} \sum_{l_1=0}^{m_1} \sum_{l_2=0}^{m_2} [\Phi(m_1, m_2) - \Phi(l_1, l_2)] \left( \begin{array}{c} n_1 - 1 \\ m_1 \end{array} \right) \left( \begin{array}{c} n_2 - 1 \\ m_2 \end{array} \right) \left( \begin{array}{c} l_1 \\ \frac{m_1}{l_1} \end{array} \right) \left( \begin{array}{c} l_2 \\ \frac{m_2}{l_2} \end{array} \right)
\]

\[
\times \sum_{j_1=0}^{n_1-m_1-1} \sum_{j_2=0}^{n_2-m_2-1} (-1)^{j_1+j_2} \left( \begin{array}{c} n_1 - m_1 - 1 \\ j_1 \end{array} \right) \left( \begin{array}{c} n_2 - m_2 - 1 \\ j_2 \end{array} \right)
\]

\[
\times \sum_{d_1=0}^{m_1-l_1} \sum_{d_2=0}^{m_2-l_2} (-1)^{d_1+d_2} \left( \begin{array}{c} m_1 - l_1 \\ d_1 \end{array} \right) \left( \begin{array}{c} m_2 - l_2 \\ d_2 \end{array} \right) \]

\[
\times \theta_2^\alpha \left[ e^{-\tau((l_1+d_1)\theta_1^\alpha + (l_2+d_2)\theta_2^\alpha)/\alpha - e^{-\tau((m_1+l_1+1)\theta_1^\alpha + (m_2+l_2+1)\theta_2^\alpha)/\alpha} \right]
\]

\[
(m_1 - l_1 + j_1 - d_1)\theta_1^\alpha + (m_2 - l_2 + j_2 - d_2)\theta_2^\alpha
\]

By substituting these results in (2.6), the mean cost rate of replacement strategy can be evaluated. In Table 2 the values of Cost2(\( v \)) are calculated for different combinations of \( v_1 \) and \( v_2 \), for both dependent and independent situations. It follows from the results of the table that for \( v_1 = 1 \) and \( v_2 = 0 \), the mean cost rate Cost2(\( v \)) is minimized, in both cases \( \alpha = 1, 2 \).

In order to investigate the robustness of our strategies concerning the model parameters, we calculate some numerical results based on these parameters. The results in Table 3 shows the effect of the dependency parameter \( \alpha \) on the optimal values of \( v_1 \) and \( v_2 \), for different values of \( \alpha \). As can be seen, when \( \alpha \) increases (i.e. we get far from independence), the number of redundant components decreases based on the objective function Cost1(\( v_1, v_2 \)) but remain unchanged under the Cost2(\( v_1, v_2 \)). This makes sense since under more dependency the MTTF is increased and the need to spare components reduces. Also, it should be noted that the higher the \( \alpha \), the lower the mean cost rates. To explore the sensitivity of the proposed models with respect to component costs, \( c = (c_1, c_2) \) and \( c^* = (c_1^*, c_2^*) \), we have provided some numerical
TABLE 3. The optimum values of $v$ by minimizing $\text{Cost}_i(v_1, v_2)$, $i = 1, 2$, for different $\alpha$ in Example 2.1.

| $\alpha$ | 1 | 1.2 | 1.4 | 1.6 | 1.8 | 2 | 2.2 | 2.4 | 2.6 | 2.8 | 3 |
|----------|---|-----|-----|-----|-----|---|-----|-----|-----|-----|---|
| $v_1$    | 3 | 3   | 2   | 2   | 2   | 2 | 2   | 2   | 2   | 2   | 2 |
| $v_2$    | 0 | 0   | 0   | 0   | 0   | 0 | 0   | 0   | 0   | 0   | 0 |
| $\text{Cost}_1(v_1, v_2)$ | 6.48 | 5.98 | 5.63 | 5.36 | 5.15 | 4.99 | 4.86 | 4.75 | 4.66 | 4.58 | 4.52 |
| $v_1$    | 1 | 1   | 1   | 1   | 1   | 1 | 1   | 1   | 1   | 1   | 1 |
| $v_2$    | 0 | 0   | 0   | 0   | 0   | 0 | 0   | 0   | 0   | 0   | 0 |
| $\text{Cost}_2(v_1, v_2)$ | 8.48 | 8.28 | 8.11 | 7.98 | 7.87 | 7.77 | 7.69 | 7.62 | 7.57 | 7.50 | 7.46 |

TABLE 4. The optimum values of $v$ by minimizing $\text{Cost}_1$ for different costs in Example 2.1.

| $c$       | $c^*$ | $v_1$ | $v_2$ | $\text{Cost}_1$ | $c$       | $c^*$ | $v_1$ | $v_2$ | $\text{Cost}_1$ |
|-----------|-------|-------|-------|------------------|-----------|-------|-------|-------|------------------|
| (1.6, 1.1)| (1.5, 1)| 3     | 0     | 4.0492          | (6, 5.5)  | (5.9, 5.4) | 1     | 0     | 11.9478         |
| (1.7, 1.2)| (1.5, 1)| 3     | 0     | 4.1278          | (6, 5.5)  | (5.7, 5.2) | 1     | 0     | 11.7509         |
| (1.8, 1.3)| (1.5, 1)| 3     | 0     | 4.2065          | (6, 5.5)  | (5.5, 5.0) | 1     | 0     | 11.5540         |
| (1.9, 1.4)| (1.5, 1)| 2     | 0     | 4.2845          | (6, 5.5)  | (5.3, 4.8) | 1     | 0     | 11.3571         |
| (2, 1.5)  | (1.5, 1)| 2     | 0     | 4.3599          | (6, 5.5)  | (5.1, 4.6) | 2     | 0     | 11.1543         |
| (2.5, 2)  | (1.5, 1)| 2     | 0     | 4.7369          | (6, 5.5)  | (5.4, 4.5) | 2     | 0     | 11.0493         |
| (3, 2.5)  | (1.5, 1)| 2     | 0     | 5.1139          | (6, 5.5)  | (4.5, 4.5) | 2     | 0     | 10.5245         |
| (3.5, 3)  | (1.5, 1)| 2     | 0     | 5.4908          | (6, 5.5)  | (4.3, 4.5) | 2     | 0     | 9.9997          |
| (4, 3.5)  | (1.5, 1)| 2     | 0     | 5.8678          | (6, 5.5)  | (3.5, 3.5) | 2     | 0     | 9.4750          |
| (4.5, 4)  | (1.5, 1)| 2     | 0     | 6.2448          | (6, 5.5)  | (3.2, 3.5) | 2     | 0     | 8.9502          |
| (1.5, 2)  | (1, 1.5)| 3     | 0     | 3.7874          | (5.5, 6)  | (5.5, 5.5) | 2     | 0     | 11.1232         |
| (2, 2.5)  | (1, 1.5)| 3     | 0     | 4.1807          | (5.5, 6)  | (4.5, 5.5) | 2     | 0     | 10.5984         |
| (2.5, 3)  | (1, 1.5)| 3     | 0     | 4.5740          | (5.5, 6)  | (4.5, 4.5) | 2     | 0     | 10.0737         |
| (3, 3.5)  | (1, 1.5)| 3     | 0     | 4.9673          | (5.5, 6)  | (3.5, 4)  | 2     | 0     | 9.5489          |
| (3.5, 4)  | (1, 1.5)| 3     | 0     | 5.3606          | (5.5, 6)  | (3.5, 3.5)| 2     | 0     | 9.0241          |
| (4, 4.5)  | (1, 1.5)| 3     | 0     | 5.7539          | (5.5, 6)  | (2.5, 3)  | 2     | 0     | 8.4992          |
| (4.5, 5)  | (1, 1.5)| 3     | 0     | 6.1472          | (5.5, 6)  | (2.2, 5)  | 2     | 0     | 7.9745          |
| (5, 5.5)  | (1, 1.5)| 3     | 0     | 6.5405          | (5.5, 6)  | (1.5, 2)  | 2     | 0     | 7.4497          |
| (5.5, 6)  | (1, 1.5)| 2     | 0     | 6.9249          | (5.5, 6)  | (1.1, 5)  | 2     | 0     | 6.9249          |
| (6, 6.5)  | (1, 1.5)| 2     | 0     | 7.0550          | (5.5, 6)  | (0.5, 1)  | 3     | 0     | 6.3664          |
| (6.5, 7)  | (1, 1.5)| 2     | 0     | 7.4320          | (5.5, 6)  | (0, 0.5)  | 3     | 0     | 5.7991          |

results in Table 4 for $\alpha = 2$. In the top left panel of the table, we observe that for fixed values of $c_i^* = 1.5$ and $c_2^* = 1$, the increase in costs $c_1$ and $c_2$ results in a reduction in the number of optimal values of $v_1$ and $v_2$. In the bottom left panel of the table, the costs $c_i$ and $c_i^*$, $i = 1, 2$, of the two types are swapped. In this case, when the costs $c_i^*$ and $c_i^*$ are fixed as $c_i^* = 1$ and $c_i^* = 1.5$, we again observe that the increase in the costs $c_1$ and $c_2$ results in a decline in the number of optimal values of $v_1$ and $v_2$. In the top right panel of the table it can be seen that for fixed values of renewing failed components as $c_1 = 6$, $c_2 = 5.5$, the decrease in the costs $c_i^*$ and $c_i^*$ results in an increase to the number of optimal values of $v_1$ and $v_2$. As shown in the
Table 5. The optimum values of $v$ by minimizing $\text{Cost}_1$ for different costs in Example 2.1.

| $c$     | $c^*$   | $v_1$ | $v_2$ | $\text{Cost}_1$ | $c$     | $c^*$   | $v_1$ | $v_2$ | $\text{Cost}_1$ |
|---------|---------|-------|-------|------------------|---------|---------|-------|-------|------------------|
| (3,2)   | (1.5,1) | 2     | 0     | 4.9904           | (2,3)   | (1.5,1) | 3     | 0     | 4.2857           |
| (4,2)   | (2,1)   | 2     | 0     | 5.9203           | (2,4)   | (1,2)   | 3     | 0     | 4.5832           |
| (6,2)   | (3,1)   | 1     | 0     | 7.5921           | (2,6)   | (1,3)   | 3     | 0     | 5.1778           |
| (8,2)   | (4,1)   | 1     | 0     | 9.1824           | (2,8)   | (1,4)   | 3     | 0     | 5.7725           |
| (10,2)  | (5,1)   | 0     | 1     | 10.6840          | (2,10)  | (1,5)   | 3     | 0     | 6.3671           |
| (12,2)  | (6,1)   | 0     | 1     | 11.7883          | (2,12)  | (1,6)   | 3     | 0     | 6.9617           |
| (14,2)  | (7,1)   | 0     | 1     | 12.8925          | (2,14)  | (1,7)   | 3     | 0     | 7.5563           |
| (16,2)  | (8,1)   | 0     | 1     | 13.9967          | (2,16)  | (1,8)   | 3     | 0     | 8.1509           |
| (18,2)  | (9,1)   | 0     | 1     | 15.1009          | (2,18)  | (1,9)   | 3     | 0     | 8.7456           |
| (20,2)  | (10,1)  | 0     | 1     | 16.2052          | (2,20)  | (1,10)  | 3     | 0     | 9.3402           |

bottom right panel, the same result holds by swapping the costs of the components of type 1 and type 2. It is seen that in all four parts of Table 4 the value of costs and the numbers of spare components are inversely related to each other. Table 5 shows the behavior of the number of redundant components from another point of view. In the left panel of the table we have kept $c_2(c_2^*)$ constant and have increased the values of $c_1(c_1^*)$. In fact, we have assumed that $c_1 = \omega c_2$ and $c_1^* = \omega c_2^*$ for $\omega = 1.5, 2, 3, \ldots, 10$. As seen, when $\omega$ increases the optimal value of the redundant component $v_1$ decreases and the optimal value of $v_2$ increases. In the right panel of the table we exchange the costs of type 1 and type 2, i.e. we assume $c_2 = \omega c_1$ and $c_2^* = \omega c_1^*$. In this case we observe no changes in the number of redundant components $v_1, v_2$ when $\omega$ increases.

In this example the distributions of the component lifetimes are ordered such that $\bar{F}_1(t) \geq \bar{F}_2(t)$, for all $t > 0$, i.e. the reliability (and subsequently the MTTF) of the components of type 1 is more than type 2. Note that according to the system structure, it is revealed that the components of type 1 are generally in more critical positions than those of type 2. Hence one should intuitively expect that the optimal solution, according to the cost criterion, would be the case in which one allocates more components of type 1 than type 2.

To see whether this fact affects the number of $v_i$, we let $\tilde{F}_2(t) = e^{-0.07t^2}$, $t > 0$, be the reliability function of the components of type 2. In this case the two reliability functions cross each other such that $\tilde{F}_1(t) < \tilde{F}_2(t)$ for $t < 2.86$ and $\tilde{F}_1(t) > \tilde{F}_2(t)$ for $t > 2.86$. Note that the MTTF for components of type 2 in this new case is the same as the previous one. By fixing the other parameters as before, we get the results given in Table 6. We see that although the distributions cross each other, the optimal numbers of components in Table 6 are mostly the same as those in Table 3, perhaps since the MTTFs have not been changed in either case.

As a final point, to see the effect of the survival copula on the optimal numbers of $v_1$ and $v_2$, we suppose that the dependency structure is followed by the Clayton copula with the following form:

$$\hat{C}(u_1, \ldots, u_n) = \left(u_1^{-1/\alpha} + \cdots + u_n^{-1/\alpha} - n + 1\right)^{-\alpha}, \quad \alpha > 0.$$ 

The parameter $\alpha$ manages the dependency degree of the copula, and the limiting case $\alpha = 0$ gives the independence. We obtain the optimal values of redundant components for some values of $\alpha$ in Table 7. As can be seen, by increasing $\alpha$, the values of $v_1$ and $v_2$ and also the mean cost rate show increase, which is in contradiction to the results in Table 3. Hence the output of
TABLE 6. The optimum values of $v$ by minimizing $\text{Cost}_1(v_1, v_2)$, for different values of $\alpha$ in Example 2.1.

| $\alpha$ | 1 | 1.2 | 1.4 | 1.6 | 1.8 | 2 | 2.2 | 2.4 | 2.6 | 2.8 | 3 |
|----------|---|-----|-----|-----|-----|---|-----|-----|-----|-----|---|
| $v_1$    | 3 | 2   | 2   | 2   | 2   | 2 | 2   | 2   | 2   | 2   | 2 |
| $v_2$    | 0 | 0   | 0   | 0   | 0   | 0 | 0   | 0   | 0   | 0   | 0 |
| $\text{Cost}_1(v_1, v_2)$ | 6.53 | 6.06 | 5.71 | 5.45 | 5.25 | 5.08 | 4.95 | 4.85 | 4.76 | 4.68 | 4.62 |

TABLE 7. The optimum values of $v$ by minimizing $\text{Cost}_1(v_1, v_2)$ for different $\alpha$ under the Clayton copula in Example 2.1.

| $\alpha$ | 0.001 | 0.1 | 1 | 2 | 3 | 4 |
|----------|-------|-----|---|---|---|---|
| $v_1$    | 2     | 2   | 2 | 2 | 3 | 3 |
| $v_2$    | 0     | 0   | 0 | 0 | 0 | 0 |
| $\text{Cost}_1(v_1, v_2)$ | 3.71 | 3.97 | 5.26 | 5.75 | 5.98 | 6.09 |

FIGURE 2. The system in Example 2.2.

the optimization problem strongly pertains to the functional structure of dependence, not only to the dependency parameter.

In the following example we consider an 8-component system consisting of three types of components. For fixed values of $v_i$, we minimize the function $\text{Cost}_1$ and also the function $\text{Cost}_2$ in the case that the replacement time of the unfailed system, $\tau$, is considered as the variable of interest.

Example 2.2. Consider the system depicted in Figure 2, given in Huang et al. [19]. The system has eight components from which three components (1, 2, and 3) are of type 1, three components (4, 5, and 7) are of type 2, and two components (6 and 8) are of type 3. The values of the system survival signature are computed in [19], to which we refer the reader for the details.

Suppose here that all the components are independent, where the components of type $i$ have common Weibull reliability functions $F_i(t) = e^{-\beta_i t^{\alpha_i}}$, $\alpha_i, \beta_i > 0$ for $i = 1, 2, 3$. In Table 8 we present the mean cost rate $\text{Cost}_1(v_1, v_2, v_3)$ for given values of $\beta_1 = 3, \beta_2 = 4, \beta_3 = 2, \alpha_1 = 2, \alpha_2 = 3, \alpha_3 = 1$ when the cost parameters are $c_1 = 1.5, c_2 = 1, c_3 = 2, c_1^* = 0.75, c_2^* = 0.4, c_3^* = 1$, and $c^{**} = 10$. Assume that we have $M_1 = 7, M_2 = 4$, and $M_3 = 5$ components from types 1, 2, and 3, respectively, as spares. Hence we can choose $v_1 \in \{0, 1, 2\}, v_2 \in \{0, 1\}$, and $v_3 \in \{0, 1, 2\}$ as the redundancy for each type, respectively.
In the left panel of Table 8, the values of Cost1 are computed for different combinations of \( v_i \). As can be seen, by adding \( v_1 = 0, v_2 = 1, \) and \( v_3 = 0 \) as the redundant components to groups 1, 2, and 3, respectively, we get the minimum value for the mean cost rate Cost1(\( v_1, v_2, v_3 \)).

Under the assumption that \( \tau \) is the variable of interest, in the right panel of the table we have minimized Cost2(\( v_1, v_2, v_3 \)) in terms of \( \tau \) and have reported the optimum value of \( \tau \), in the case that the values of \( v_i \) are kept fixed and known. It is observed that among all minimized values of Cost2, the least value is obtained for the case that the number of redundant components are \( v_1 = 0, v_2 = 1, \) and \( v_3 = 0 \), for which we have \( \tau = 0.375 \).

### 3. Optimal number of components in series-parallel systems

An important subclass of coherent systems is the class of series-parallel systems. A series-parallel system is a series structure of \( L \) parallel subsystems, \( L \geq 1 \); see e.g. Figure 3. The purpose here is to find the optimal number of the components in the \( l \)th parallel subsystem, under the condition that there are available \( M_l \) components of type \( l \), where the components in the \( l \)th subsystem are exchangeable dependent having common reliability function \( \bar{F}_l \), \( l = 1, \ldots, L \). Furthermore, suppose that the random failure times of the components of different types are dependent. The dependency structure in the system is built with a copula function \( \hat{C} \), as described in Section 2. Under the mean cost rate criteria defined in Section 2, the problem of optimal allocation is to find the optimal values of \( n_l \) for each subsystem so that (2.1) or (2.6) is minimized.

| \( v_1 \) | \( v_2 \) | \( v_3 \) | Cost1(\( v_1, v_2, v_3 \)) | \( \tau_{opt} \) | Cost2(\( v_1, v_2, v_3 \)) |
|---|---|---|---|---|---|
| 0  | 0  | 0  | 39.0424 | 0.300 | 29.5929 |
| 0  | 1  | 0  | 37.4142 | 0.375 | 28.9959 |
| 1  | 0  | 0  | 42.1779 | 0.365 | 34.7858 |
| 1  | 1  | 0  | 39.0422 | 0.450 | 31.1106 |
| 2  | 0  | 0  | 47.4998 | 0.405 | 42.0378 |
| 2  | 1  | 0  | 43.0531 | 0.490 | 36.3495 |
| 0  | 0  | 1  | 42.2553 | 0.326 | 38.2377 |
| 0  | 1  | 1  | 41.2034 | 0.367 | 37.6403 |
| 1  | 0  | 1  | 44.1149 | 0.391 | 41.3141 |
| 1  | 1  | 1  | 41.9973 | 0.463 | 37.8883 |
| 2  | 0  | 1  | 48.5362 | 0.445 | 47.7900 |
| 2  | 1  | 1  | 45.5179 | 0.503 | 42.4445 |
| 0  | 0  | 2  | 45.5246 | 0.350 | 46.7613 |
| 0  | 1  | 2  | 44.8865 | 0.410 | 46.1258 |
| 1  | 0  | 2  | 46.1353 | 0.412 | 47.6364 |
| 1  | 1  | 2  | 44.8022 | 0.480 | 44.4306 |
| 2  | 0  | 2  | 49.7090 | 0.455 | 53.1287 |
| 2  | 1  | 2  | 47.7961 | 0.520 | 48.2148 |
In the following we provide the corresponding expressions for the cost-based functions in a series-parallel system. First note that for this system we have
\[
\Phi(l_1, \ldots, l_L) = \begin{cases} 
1 & \text{for all } j \in \{1, \ldots, L\} : l_j \geq 1, \\
0 & \text{otherwise.}
\end{cases}
\]
Hence from (1.3) we get
\[
\bar{F}_T(t) = \sum_{i_1=1}^{n_1} \cdots \sum_{i_l=1}^{n_l} \sum_{i_{l+1}=0}^{n_{l+1}} \cdots \sum_{i_L=0}^{n_L} (-1)^{i_1 + \cdots + i_L} \binom{n_1}{l_1} \cdots \binom{n_L}{i_L} \binom{n_1 - 1}{i_1} \cdots \binom{n_L - l_L}{i_L}
\]
\[
\times \hat{C}\left(\bar{F}_{i_1}(t), \frac{1}{n_1 - (i_1 + l_1)} , \ldots, \bar{F}_{i_L}(t), \frac{1}{n_L - (i_L + l_L)} \right).
\]
and in the special case of independent components, we derive from (1.4)
\[
\bar{F}_T(t) = \prod_{l=1}^{L} (1 - [1 - \bar{F}_l(t)]^{n_l}).
\]

3.1. Cost function at system failure

In a similar manner to Section 2.1, the mean cost rate function for system failure is defined as
\[
\text{Cost}_3(n) = \frac{\sum_{i=1}^{L} c_i \mathbb{E}(X_i(T)) + \sum_{i=1}^{L} c_i^* \mathbb{E}(n_i - X_i(T)) + c^{**}}{\mathbb{E}(T)},
\]
where \(n = (n_1, \ldots, n_L)\), and
\[
\mathbb{E}(X_i(T)) = n_i \sum_{m_1=1}^{n_1} \cdots \sum_{m_l=1}^{n_l} \binom{n_1}{m_1} \cdots \binom{n_l - 1}{m_l} \cdots \binom{n_L}{m_L} \int_0^\infty \lim_{\delta \to 0} \frac{A_m(t, \delta)}{\delta} \, dt,
\]
\[
\text{Cost}_3(n) = \frac{\sum_{i=1}^{L} c_i \mathbb{E}(X_i(T)) + \sum_{i=1}^{L} c_i^* \mathbb{E}(n_i - X_i(T)) + c^{**}}{\mathbb{E}(T)},
\]
where \(n = (n_1, \ldots, n_L)\), and
\[
\mathbb{E}(X_i(T)) = n_i \sum_{m_1=1}^{n_1} \cdots \sum_{m_l=1}^{n_l} \binom{n_1}{m_1} \cdots \binom{n_l - 1}{m_l} \cdots \binom{n_L}{m_L} \int_0^\infty \lim_{\delta \to 0} \frac{A_m(t, \delta)}{\delta} \, dt,
\]
in which \( A^{(i)}_{m}(t, \delta) \) is introduced in (2.3). For the independent components, (3.2) reduces to the following expression:

\[
\mathbb{E}(X_i(T)) = n_i \int_0^\infty \prod_{l=1, l \neq i}^L (1 - (1 - \bar{F}_l(t))^{m_l}) \, dF_i(t). \tag{3.3}
\]

If \( L = 1 \) then the system becomes a parallel system with \( n_1 \) components, and hence in this case \( \mathbb{E}(X_1(T)) = n_1 \).

For the considered series-parallel system in which the components of subsystems are independent, Eryilmaz et al. [11] gained a similar result for \( \mathbb{E}(X_i(T)) \) in (3.3). Subsequently, they found the optimal numbers of components in each subsystem based on the minimization of cost function (3.1) under the constraints on the total allotted cost for replacing failed components and the total allotted cost for rejuvenation of unfailed ones. Hence our results in this subsection may be considered as an extension of their work to the case of dependent components. Also, Dembinska and Eryilmaz [5] discussed a similar problem for the case that the lifetime distributions of components are discrete; in particular, they obtained some results for discrete phase-type distribution.

### 3.2. Cost function based on preventive replacement

The mean cost rate function of the system for age replacement at time \( \min(\tau, T) \) is defined as

\[
\text{Cost}_4(n) = \frac{M_1(n) \mathbb{P}(T \leq \tau) + M_2(n) \mathbb{P}(T > \tau)}{\mathbb{E}(\min(\tau, T))},
\]

where

\[
M_1(n) = \sum_{i=1}^L c_i \mathbb{E}(X_i(T) \mid T \leq \tau) + \sum_{i=1}^L c_i^* \mathbb{E}(n_i - X_i(T) \mid T \leq \tau) + c^{**}
\]

and

\[
M_2(n) = \sum_{i=1}^L c_i \mathbb{E}(N_i(\tau) \mid T > \tau) + \sum_{i=1}^L c_i^* \mathbb{E}(n_i - N_i(\tau) \mid T > \tau).
\]

Using the formula for the survival signature of the series-parallel system, from the results given in Section 2.2, we get the following expressions:

\[
\mathbb{E}(N_i(\tau) \mid T > \tau) = \frac{1}{\bar{F}(\tau)} \sum_{j_1=0}^{n_1-1} \cdots \sum_{j_L=0}^{n_L-1} \binom{n_1}{j_1} \cdots \binom{n_L}{j_L} B(\tau, j_1, \ldots, j_L)
\]

and for \( n_i \geq 2 \)

\[
\mathbb{E}(X_i(T) \mid T \leq \tau) = \frac{n_i}{1 - \bar{F}_T(\tau)} \left[ \sum_{m_1=1}^{n_1} \cdots \sum_{m_L=1}^{n_L} \sum_{l_1=0}^{m_1} \cdots \sum_{l_L=0}^{m_L} \left[ \prod_{l=1, l \neq i}^L \binom{m_{j_l}}{l_{j_l}} \right] \right]
\]
Optimal redundancy allocation in coherent systems

1165

multivariate Pareto model given by

\[ C_i(t) = \int_0^\infty \lim_{\delta \to 0} \frac{1}{\delta} A_m(s + \delta, \tau) ds \]

If \( n_i = 1 \) then it is easily deduced that

\[ \mathbb{E}(X_i(T) | T \leq \tau) = \frac{F_i(\tau)}{1 - F_T(\tau)}. \]

Example 3.1. Consider a series-parallel system with \( L = 3 \) subsystems and assume that there are \( M_1 = 2, M_2 = 3, \) and \( M_3 = 3 \) components from types 1, 2, and 3, respectively, to construct the system. Suppose that the joint reliability function of the component lifetimes follow the multivariate Pareto model given by

\[ \mathbb{P}(T_1^{(1)} > t_1^{(1)}, \ldots, T_n^{(1)} > t_n^{(1)}, \ldots, T_1^{(L)} > t_1^{(L)}, \ldots, T_n^{(L)} > t_n^{(L)}) \]

for \( \theta_i > 0, i = 1, \ldots, L, \) and \( \alpha > 0. \) In fact the corresponding survival copula is

\[ \hat{C}(u_1, \ldots, u_n) = (u_1^{-1/\alpha} + \cdots + u_n^{-1/\alpha} - n + 1)^{-\alpha}, \]

and the marginal reliability functions of the components in the subsystems are \( \hat{F}_i(t) = (1 + \theta_i t)^{-\alpha}, i = 1, 2, \ldots, L. \)

First note that for the described system we have

\[ \int_0^\infty \frac{A_m(t, \delta)}{\delta} dt \]

\[ = \sum_{j_1=0}^{n_1-m_1} \cdots \sum_{j_i=0}^{n_i-m_i} \cdots \sum_{j_L=0}^{n_L-m_L} (-1)^{j_1+\cdots+j_L} \binom{n_1-m_1}{j_1} \cdots \binom{n_i-m_i-1}{j_i} \cdots \binom{n_L-m_L}{j_L} \]

\[ \times \frac{\theta_i}{\theta_i(m_i + j_i + 1) + \sum_{k=1, k \neq i}^L \theta_k(m_k + j_k)}. \]

By replacing these expressions in (3.2), \( \mathbb{E}(X_i(T)), i = 1, 2, 3 \) are obtained.

Let \( \theta = (0.4, 0.2, 0.3), c = (1.5, 2, 3), c^* = (0.3, 0.75, 1), c^{**} = 8, \) and \( \alpha = 2. \) The values of the mean cost rate function \( \text{Cost}_3 \) are obtained for all combinations of \( n_1, n_2, \) and \( n_3, \) such that \( n_1 \in \{1, 2\}, n_2 \in \{1, 2, 3\}, \) and \( n_3 \in \{1, 2, 3\}. \) Also, under the age replacement strategy in \( \tau = 1, \) the values of mean cost rate function \( \text{Cost}_4 \) are calculated for different values \( n_1, n_2, \) and \( n_3. \)
To compute $\text{Cost}_4(\tau)$, we use the following simplified expressions:

$$
\mathbb{E}(N_i(\tau) \mid T > \tau) = \frac{1}{\bar{F}_T(\tau)} \sum_{j_1=0}^{n_1-1} \sum_{j_2=0}^{n_2-1} \sum_{j_3=0}^{n_3-1} j_i \binom{n_1}{j_1} \binom{n_2}{j_2} \binom{n_3}{j_3} \sum_{b_1=0}^{j_1} \sum_{b_2=0}^{j_2} \sum_{b_3=0}^{j_3} (-1)^{b_1+b_2+b_3} \binom{j_1}{b_1} \binom{j_2}{b_2} \binom{j_3}{b_3} [1 + \theta_1 \tau(j_1 + l_1) + \theta_2 \tau(j_2 + l_2) + \theta_3 \tau(j_3 + l_3)]^{-\alpha},
$$

for $i = 1, 2, 3$, where

$$
\bar{F}_T(\tau) = \sum_{l_1=1}^{n_1} \sum_{l_2=1}^{n_2} \sum_{l_3=1}^{n_3} \sum_{i_1=0}^{l_1-1} \sum_{i_2=0}^{l_2-1} \sum_{i_3=0}^{l_3-1} (-1)^{i_1+i_2+i_3} \binom{n_1}{l_1} \binom{n_2}{l_2} \binom{n_3}{l_3} \binom{n_1-l_1}{i_1} \binom{n_2-l_2}{i_2} \binom{n_3-l_3}{i_3} (1 + \theta_1 \tau(i_1 + l_1) + \theta_2 \tau(i_2 + l_2) + \theta_3 \tau(i_3 + l_3))^{-\alpha}.
$$

Also, we obtain $\mathbb{E}(X_i(T) \mid T \leq \tau), i = 1, 2, 3$ by placing the following quantity in (3.4):

$$
\int_0^\tau \lim_{\delta \to 0} \frac{1}{\delta} A^{(i)}_{m,1}(s, s + \delta, \tau) \, ds
$$

### Table 9. The values of $\text{Cost}_3(n)$ and $\text{Cost}_4(n)$ in Example 3.1.

| $n_1$ | $n_2$ | $n_3$ | $\text{Cost}_3(n_1, n_2, n_3)$ | $\text{Cost}_4(n_1, n_2, n_3)$ |
|-------|-------|-------|-----------------------------|-----------------------------|
| 1     | 1     | 1     | 10.3750                     | 18.2784                     |
| 1     | 1     | 2     | 9.6460                      | 18.6515                     |
| 1     | 1     | 3     | 10.0967                     | 21.2331                     |
| 1     | 2     | 1     | 9.7277                      | 18.1732                     |
| 1     | 2     | 2     | 8.8857                      | 18.1463                     |
| 1     | 2     | 3     | 9.1886                      | 20.4388                     |
| 1     | 3     | 1     | 10.0842                     | 19.8532                     |
| 1     | 3     | 2     | 9.0989                      | 19.5615                     |
| 1     | 3     | 3     | 9.3157                      | 21.7702                     |
| 2     | 1     | 1     | 8.7073                      | 16.2100                     |
| 2     | 1     | 2     | 7.9885                      | 16.1742                     |
| 2     | 1     | 3     | 8.2879                      | 18.3280                     |
| 2     | 2     | 1     | 8.0593                      | 15.8127                     |
| 2     | 2     | 2     | 7.4747                      | 12.2278                     |
| 2     | 2     | 3     | 7.4835                      | 13.5080                     |
| 2     | 3     | 1     | 8.2888                      | 17.1959                     |
| 2     | 3     | 2     | 7.4068                      | 13.0874                     |
| 2     | 3     | 3     | 7.5279                      | 14.2977                     |
Optimal redundancy allocation in coherent systems

\[
\begin{align*}
&= \sum_{j_1=0}^{n_1-m_1} \cdots \sum_{j_i=0}^{m_i-1} \cdots \sum_{j_L=0}^{m_L-m_L} (-1)^{j_1+\cdots+j_L} (\frac{n_1-m_1}{j_1}) \cdots (\frac{n_i-m_i-1}{j_i}) \cdots (\frac{n_L-m_L}{j_L}) \\
&\times \sum_{d_1=0}^{m_1-l_1} \cdots \sum_{d_i=0}^{m_i-l_i} \cdots \sum_{d_L=0}^{m_L-l_L} (-1)^{d_1+\cdots+d_L} (\frac{m_1-l_1}{d_1}) \cdots (\frac{m_L-l_L}{d_L}) \\
&\quad \times \theta_1 \left[ (1 + \tau (\sum_{k=1}^{L} \theta_k(l_k + d_k)))^{-\alpha} - (1 + \tau (\theta_i(m_i + j_i + 1) + \sum_{k=1, \neq i}^{L} \theta_k(m_k + j_k)))^{-\alpha} \right] \\
&\quad \times \theta_i(m_i - l_i + j_i - d_i + 1) + \sum_{k=1, \neq i}^{L} \theta_k(m_k - l_k + j_k - d_k).
\end{align*}
\]

The results are given in Table 9. It is seen from the results that based on the objective function Cost3(.) the optimal series-parallel system has \(n_1 = 2\), \(n_2 = 3\), \(n_3 = 2\) components. Since the reliability of type 2 is greater than the other two types, it is expected that more components for the second subsystem will lead to a reduction in the mean cost rate of system failure. Also, \(n_1 = 2\), \(n_2 = 2\), \(n_3 = 2\) are the optimal number of components in the subsystems so as to minimize the average cost rate of the age replacement policy.

4. Conclusions

In this paper we have studied the optimal number of redundancy allocation in an \(n\)-component coherent system consisting of heterogeneous components. We assumed that the system has been built up of \(L\) different types of components, \(L \geq 1\), where there are \(n_i\) components of type \(i\) and \(\sum_{i=1}^{L} n_i = n\). We assumed that the components of the different types in the system are statistically dependent. The system reliability function was modeled by the notion of survival signature in terms of a given survival copula function. We further assumed \(M_i\) components available as spares for the components of type \(i\). We investigated the number of active redundant components \(v_i\), \(nv_i \leq M_i\), that can be added to each component of type \(i\) such that the imposed cost functions are minimized, \(i = 1, \ldots, L\). We first proposed a cost function in terms of the costs of renewing the failed components and the costs of refreshing the alive components at the time of the system failure. Subsequently, we proposed a cost-based function in terms of the costs of the renewing (refreshing) the failed (alive) components at the system failure time or at a predetermined time \(\tau\), whichever occurs first. In the last part of the paper, using the settings of the first part, we studied the particular case that the system is a series-parallel system. We derived the formulas for the proposed cost functions and used them to investigate the optimal number of the components in each parallel subsystem. The expressions for the proposed cost functions were derived using the mixture representation of the system reliability function based on the notion of survival signature. The results were examined numerically for some particular coherent systems. The proposed mean cost rate functions simultaneously consider the cost of the system and its MTTF (which is directly related to its reliability). Hence this optimization problem can be viewed as a bi-objective reliability–redundancy allocation problem but with a more comfortable setup. In this study we considered the general case that the components of the same group are exchangeable and the components of different groups and dependent. Although these assumptions are more realistic and hence increase the range of applications of our results, they obviously lead to greater complexity of the formulas. An even more realistic case is the situation that the components in each group are dependent in a more general sense than that of exchangeability. Developing results in this direction may be considered for future study. Here we assumed active redundancy for components. Allocating the other variants of spares, i.e. cold and warm standby, for coherent systems may be investigated as interesting problems for future studies.
Appendix A. Proof of Theorem 2.1

Define the events $M$, $N^c$, and $L^c$ as follows:

\[ M \equiv \{ T_1^{(1)} > t, \ldots, T_{m_1}^{(1)} > t, T_2^{(i)} > t, \ldots, T_{m_i+1}^{(i)} > t, T_1^{(L)} > t, \ldots, T_{m_L}^{(L)} > t \}, \]

\[ N^c \equiv \{ T_{m_1+1}^{(1)} < t, \ldots, T_{n_1}^{(1)} < t, T_{m_i+2}^{(i)} < t, \ldots, T_{n_i}^{(i)} < t, T_{m_L+1}^{(L)} < t, \ldots, T_{n_L}^{(L)} < t \}, \]

\[ L^c \equiv \{ t < T_1^{(i)} < t + \delta \}. \]

Then $A_m^{(i)}(t, \delta)$ is equal to the following:

\[ A_m^{(i)}(t, \delta) = \mathbb{P}(M \cap N^c \cap L^c) = \mathbb{P}(M) - \mathbb{P}(M \cap N) - \mathbb{P}(M \cap L) + \mathbb{P}(M \cap N \cap L). \quad (A.1) \]

Evidently we have

\[ \mathbb{P}(M) = \hat{C} \left( \frac{\tilde{F}_1(t)}{m_1}, \frac{1}{n_1-m_1}, \ldots, \frac{\tilde{F}_i(t)}{m_i}, \frac{1}{n_i-m_i}, \ldots, \frac{\tilde{F}_L(t)}{m_L}, \frac{1}{n_L-m_L} \right) \]

and

\[ \mathbb{P}(M \cap L) = \hat{C} \left( \frac{\tilde{F}_1(t)}{m_1}, \frac{1}{n_1-m_1}, \ldots, \frac{\tilde{F}_i(t)}{m_i}, \tilde{F}_i(t + \delta), \frac{1}{n_i-m_i}, \ldots, \frac{\tilde{F}_L(t)}{m_L}, \frac{1}{n_L-m_L} \right). \]

Note that we can write

\[ N = \bigcup_{j=m_1+1}^{n_1} \{ T_j^{(1)} > t \} \cup \cdots \cup \bigcup_{j=m_i+1}^{n_i} \{ T_j^{(i)} > t \} \cup \cdots \cup \bigcup_{j=m_L+1}^{n_L} \{ T_j^{(L)} > t \}. \]

Therefore we can easily see that

\[ \mathbb{P}(M \cap N) \]

\[ = \sum_{l=1}^{n-\sum_{j=1}^{L} m_j-1} (-1)^{l+1} \sum_{j_1=0}^{n_1-m_1-1} \sum_{j_2=0}^{n_2-m_2} \cdots \sum_{j_L=0}^{n_L-m_L} \left( \frac{n_1-m_1}{j_1} \right) \cdots \left( \frac{n_i-m_i-1}{j_i} \right) \cdots \left( \frac{n_L-m_L}{j_L} \right) \]

\[ \times \hat{C} \left( \frac{\tilde{F}_1(t)}{m_1+j_1}, \frac{1}{n_1-m_1-j_1}, \ldots, \frac{\tilde{F}_i(t)}{m_i+j_1}, \frac{1}{n_i-m_i-j_1}, \ldots, \frac{\tilde{F}_L(t)}{m_L+j_1}, \frac{1}{n_L-m_L-j_1} \right). \]

If we subtract $\mathbb{P}(M)$ from both sides of this equation, then we have

\[ \mathbb{P}(M \cap N) - \mathbb{P}(M) \]

\[ = \sum_{l=1}^{n-\sum_{j=1}^{L} m_j-1} (-1)^{l+1} \sum_{j_1=0}^{n_1-m_1-1} \sum_{j_2=0}^{n_2-m_2} \cdots \sum_{j_L=0}^{n_L-m_L} \left( \frac{n_1-m_1}{j_1} \right) \cdots \left( \frac{n_i-m_i-1}{j_i} \right) \cdots \left( \frac{n_L-m_L}{j_L} \right) \]

If we subtract $\mathbb{P}(M)$ from both sides of this equation, then we have
Optimal redundancy allocation in coherent systems

\[ P = \bigcap_{i=1}^{n} F_i(t) \]

\[ = - \sum_{l=1}^{n-1} m_l - 1 \sum_{j_1=0}^{n_1-m_1-1} \sum_{j_i=0}^{n_i-m_i-1} \sum_{j_L=0}^{n_L-m_L-1} \left( \begin{array} {c} n_1-m_1 \\ j_1 \\ \vdots \\ n_L-m_L \\ j_L \end{array} \right) \]

Similarly we have

\[ P(M \cap N \cap L) \]

\[ = - \sum_{l=1}^{n-1} m_l - 1 \sum_{j_1=0}^{n_1-m_1-1} \sum_{j_i=0}^{n_i-m_i-1} \sum_{j_L=0}^{n_L-m_L-1} \left( \begin{array} {c} n_1-m_1 \\ j_1 \\ \vdots \\ n_L-m_L \\ j_L \end{array} \right) \]

\[ \times \hat{C} \left( \tilde{F}_i(t), 1, \ldots, \tilde{F}_i(t), \tilde{F}_i(t+\delta), 1, \ldots, \tilde{F}_i(t), 1 \right) \]

\[ \mathbb{P}(M \cap N \cap L) = \mathbb{P}(M \cap N) - \mathbb{P}(M \cap L) \]

\[ = - \sum_{l=1}^{n-1} m_l - 1 \sum_{j_1=0}^{n_1-m_1-1} \sum_{j_i=0}^{n_i-m_i-1} \sum_{j_L=0}^{n_L-m_L-1} \left( \begin{array} {c} n_1-m_1 \\ j_1 \\ \vdots \\ n_L-m_L \\ j_L \end{array} \right) \]

\[ \times \hat{C} \left( \tilde{F}_i(t), 1, \ldots, \tilde{F}_i(t), \tilde{F}_i(t+\delta), 1, \ldots, \tilde{F}_i(t), 1 \right) \]

\[ = \sum_{j_1=0}^{n_1-m_1-1} \sum_{j_i=0}^{n_i-m_i-1} \sum_{j_L=0}^{n_L-m_L-1} \left( \begin{array} {c} n_1-m_1 \\ j_1 \\ \vdots \\ n_L-m_L \\ j_L \end{array} \right) \]

\[ \times \hat{C} \left( \tilde{F}_i(t), 1, \ldots, \tilde{F}_i(t), \tilde{F}_i(t+\delta), 1, \ldots, \tilde{F}_i(t), 1 \right). \]
Then, replacing (A.2) and (A.3) in (A.1), we have

\[ A_m^{(i)}(t, \delta) = - \sum_{j_1=0}^{n_1-m_1} \sum_{j_i=0}^{n_i-m_i} \sum_{j_L=0}^{n_L-m_L} (-1)^{j_1+\cdots+j_L+1} \binom{n_1-m_1}{j_1} \cdots \binom{n_i-m_i-1}{j_i} \cdots \binom{n_L-m_L}{j_L} \]

\[ \times \mathcal{C} \left( \tilde{F}_1(t), \frac{1}{m_1+j_1}, \ldots, \frac{1}{m_i+j_i}, \ldots, \frac{1}{m_L+j_L} \right) \]

\[ + \sum_{j_1=0}^{n_1-m_1} \sum_{j_i=0}^{n_i-m_i} \sum_{j_L=0}^{n_L-m_L} (-1)^{j_1+\cdots+j_L+1} \binom{n_1-m_1}{j_1} \cdots \binom{n_i-m_i-1}{j_i} \cdots \binom{n_L-m_L}{j_L} \]

\[ \times \mathcal{C} \left( \tilde{F}_1(t), \frac{1}{m_1+j_1}, \ldots, \frac{1}{m_i+j_i}, \ldots, \frac{1}{m_L+j_L} \right) \]

\[ = \sum_{j_1=0}^{n_1-m_1} \sum_{j_i=0}^{n_i-m_i} \sum_{j_L=0}^{n_L-m_L} (-1)^{j_1+\cdots+j_L+1} \binom{n_1-m_1}{j_1} \cdots \binom{n_i-m_i-1}{j_i} \cdots \binom{n_L-m_L}{j_L} \]

\[ \times \left[ \mathcal{C} \left( \tilde{F}_1(t), \frac{1}{m_1+j_1}, \ldots, \frac{1}{m_i+j_i}, \ldots, \frac{1}{m_L+j_L} \right) \right] \]

\[ - \mathcal{C} \left( \tilde{F}_1(t), \frac{1}{m_1+j_1}, \ldots, \frac{1}{m_i+j_i}, \ldots, \frac{1}{m_L+j_L} \right) \]
It can be easily shown that

\[
\mathbb{P}(M) = \hat{C} \left( \overline{F}_j(\tau), \overline{F}_j(s), \frac{1}{l_j - m_j} \right), \quad 1 \leq j \leq L, j \neq i, \overline{F}_i(\tau), \overline{F}_i(s), \frac{1}{l_i - m_i + 1} \nabla \frac{1}{n_i - m_i - 1}
\]

\[
\mathbb{P}(M \cap K) = \mathbb{P}(M \cap \{ T_{m_j+1}^i > s + \delta \}) = \hat{C} \left( \overline{F}_j(\tau), \overline{F}_j(s), \frac{1}{l_j - m_j} \right), \quad 1 \leq j \leq L, j \neq i, \overline{F}_i(\tau), \overline{F}_i(s), \overline{F}_i(s + \delta), \frac{1}{n_i - m_i - 1}
\]

Note also that the event \( N \) (the complement of \( N^c \)) can be represented as

\[
N = \bigcup_{j=1}^L \bigcup_{j \neq i} \bigcup_{k_j = m_j+1}^{n_j} \{ T_{k_j}^j > s \} \cup \bigcup_{k_i = m_i+2}^{n_i} \{ T_{k_i}^i > s \},
\]

Thus we get

\[
\mathbb{P}(M \cap N)
\]

\[
= \sum_{l=1}^{n-m_1} (-1)^{l+1} \sum_{r_l=0}^{n_l-m_l} \ldots \sum_{r_1=0}^{n_1-m_1} \left( \frac{n_1-m_1}{r_1} \right) \ldots \left( \frac{n_{L-m_L}}{r_L} \right)
\]

\[
\times \hat{C} \left( \overline{F}_j(\tau), \overline{F}_j(s), \frac{1}{l_j - m_j + r_j} \right), \quad 1 \leq j \leq L, j \neq i, \overline{F}_i(\tau), \overline{F}_i(s), \frac{1}{n_i - m_i - r_i - 1}
\]

and hence

\[
\mathbb{P}(M \cap N) - \mathbb{P}(M)
\]

\[
= \sum_{l=0}^{n-m_1} (-1)^{l+1} \sum_{r_l=0}^{n_l-m_l} \ldots \sum_{r_1=0}^{n_1-m_1} \left( \frac{n_1-m_1}{r_1} \right) \ldots \left( \frac{n_{L-m_L}}{r_L} \right)
\]

\[
\times \hat{C} \left( \overline{F}_j(\tau), \overline{F}_j(s), \frac{1}{l_j - m_j + r_j} \right), \quad 1 \leq j \leq L, j \neq i, \overline{F}_i(\tau), \overline{F}_i(s), \frac{1}{n_i - m_i - r_i - 1}
\]

\[
= \sum_{r_l=0}^{n_l-m_l} \ldots \sum_{r_1=0}^{n_1-m_1} (-1)^{r_1+\ldots+r_l+1} \left( \frac{n_1-m_1}{r_1} \right) \ldots \left( \frac{n_{L-m_L}}{r_L} \right)
\]

\[
\times \hat{C} \left( \overline{F}_j(\tau), \overline{F}_j(s), \frac{1}{l_j - m_j + r_j} \right), \quad 1 \leq j \leq L, j \neq i, \overline{F}_i(\tau), \overline{F}_i(s), \frac{1}{n_i - m_i - r_i - 1}
\]
Therefore we get

\[
\mathbb{P}(M \cap N \cap K) = 
\sum_{l=1}^{n-m_l-1} (-1)^{l+1} \frac{n-m_l-1}{l} \cdot \frac{n-m_l-1}{l} \cdot \frac{n-m_{l-m_L}}{l-m_L} \cdot \sum_{r_1=0}^{n-m_l-1} \sum_{r_2=0}^{n-m_{l-m_L}} \left( \frac{n_1-m_1}{r_1} \cdot \frac{n_i-m_i-1}{r_i} \cdot \frac{n_L-m_L}{r_L} \right) \\
\times \hat{C}\left( \bar{F}_j(\tau), \bar{F}_j(s), 1 \leq j \leq L, j \neq i, \bar{F}_i(\tau), \bar{F}_i(s+\delta), 1 \right)
\]

Similarly, we have

\[
L = \{ \cup_{j=1}^{L} \cup_{s=j+1}^{m_j} \{ T_{kj}^{(i)} > \tau \} \}
\]

Therefore we get

\[
\mathbb{P}(M \cap L) = 
\sum_{y=1}^{\sum_{l=1}^{n-m_l-1} (m_l-l_j)} (-1)^{y+1} \frac{m_l-l_j}{d_1} \cdot \frac{m_l-l_j}{d_2} \cdot \frac{m_l-l_J}{d_L} \cdot \sum_{d_1=0}^{m_l-l_j} \sum_{d_2=0}^{m_l-l_j} \sum_{d_L=0}^{m_l-l_J} \left( \frac{m_l-1}{d_1} \cdot \frac{n_i-m_i-1}{d_i} \cdot \frac{n_L-m_L}{d_L} \right) \\
\times \hat{C}\left( \bar{F}_j(\tau), \bar{F}_j(s), 1 \leq j \leq L, j \neq i, \bar{F}_i(\tau), \bar{F}_i(s), 1 \right)
\]

and

\[
\mathbb{P}(M \cap L \cap K) = 
\sum_{l=1}^{n-m_l-1} (-1)^{l+1} \frac{n-m_l-1}{l} \cdot \frac{n-m_l-1}{l} \cdot \frac{n-m_{l-m_L}}{l-m_L} \cdot \sum_{r_1=0}^{n-m_l-1} \sum_{r_2=0}^{n-m_{l-m_L}} \left( \frac{n_1-m_1}{r_1} \cdot \frac{n_i-m_i-1}{r_i} \cdot \frac{n_L-m_L}{r_L} \right) \\
\times \hat{C}\left( \bar{F}_j(\tau), \bar{F}_j(s), 1 \leq j \leq L, j \neq i, \bar{F}_i(\tau), \bar{F}_i(s+\delta), 1 \right).
\]
Also, after some manipulations, one can verify that \( \mathbb{P}(M \cap N \cap L) \) and \( \mathbb{P}(M \cap N \cap L \cap K) \), respectively, can be written as

\[
\begin{align*}
\mathbb{P}(M \cap N \cap L) &= \sum_{l=1}^{n-\sum_{j=1}^L m_j-1} (-1)^{l+1} \sum_{r_1=0}^{n_1-m_{1_l}} \cdots \sum_{r_i=0}^{n_i-m_{1_l}} \cdots \sum_{r_L=0}^{n_L-m_{1_L}} \left( \frac{n_1-m_{1_l}}{r_1} \right) \cdots \left( \frac{n_i-m_{1_l}}{r_i} \right) \cdots \left( \frac{n_L-m_{1_L}}{r_L} \right) \\
&\times \sum_{y=1}^{\sum_{j=1}^L (m_j-l_j)} (-1)^{y+1} \sum_{d_1=0}^{m_1-l_1} \cdots \sum_{d_L=0}^{m_L-l_L} \left( \frac{m_1-l_1}{d_1} \right) \cdots \left( \frac{m_L-l_L}{d_L} \right) \\
&\times \hat{C} \left( \bar{F}_j(\tau), \bar{F}_j(s), \frac{1}{l_j+d_j} \right), 1 \leq j \leq L, j \neq i, \bar{F}_i(\tau), \bar{F}_i(s), \frac{1}{l_i+d_i} \\
\mathbb{P}(M \cap N \cap L \cap K) &= \sum_{l=0}^{n-\sum_{j=1}^L m_j-1} (-1)^{l+1} \sum_{r_1=0}^{n_1-m_{1_l}} \cdots \sum_{r_i=0}^{n_i-m_{1_l}} \cdots \sum_{r_L=0}^{n_L-m_{1_L}} \left( \frac{n_1-m_{1_l}}{r_1} \right) \cdots \left( \frac{n_i-m_{1_l}}{r_i} \right) \cdots \left( \frac{n_L-m_{1_L}}{r_L} \right) \\
&\times \sum_{y=0}^{\sum_{j=1}^L (m_j-l_j)} (-1)^{y+1} \sum_{d_1=0}^{m_1-l_1} \cdots \sum_{d_L=0}^{m_L-l_L} \left( \frac{m_1-l_1}{d_1} \right) \cdots \left( \frac{m_L-l_L}{d_L} \right) \\
&\times \hat{C} \left( \bar{F}_j(\tau), \bar{F}_j(s), \frac{1}{l_j+d_j} \right), 1 \leq j \leq L, j \neq i, \bar{F}_i(\tau), \bar{F}_i(s), \frac{1}{l_i+d_i} \\
&+ \mathbb{P}(M \cap L)
\end{align*}
\]
and

\[ P(M \cap N \cap L \cap K) \]

\[ = \sum_{l=0}^{L} \left( \sum_{r_{1}=0}^{n_{1}-m_{1}} \cdots \sum_{r_{L}=0}^{n_{L}-m_{L}} \left( \sum_{r_{1}+\cdots+r_{L}=l} \left( n_{1}-m_{1} \right) \cdots \left( n_{L}-m_{L} \right) \right) \right) \]

\[ \times \sum_{y=1}^{L} \left( \sum_{d_{1}=0}^{m_{1}-l_{1}} \cdots \sum_{d_{L}=0}^{m_{L}-l_{L}} \left( \sum_{d_{1}+\cdots+d_{L}=y} \left( m_{1}-l_{1} \right) \cdots \left( m_{L}-l_{L} \right) \right) \right) \]

\[ \times \mathcal{C} \left( \mathcal{F}_{j}(\tau), \mathcal{F}_{j}(s), 1, 1 \leq j \leq L, j \neq i, \mathcal{F}_{i}(\tau), \mathcal{F}_{i}(s), \mathcal{F}_{i}(s+\delta), 1 \right) \]

\[ + P(M \cap L \cap K) \]

\[ = \sum_{l=0}^{L} \left( \sum_{r_{1}=0}^{n_{1}-m_{1}} \cdots \sum_{r_{L}=0}^{n_{L}-m_{L}} \left( \sum_{r_{1}+\cdots+r_{L}=l} \left( n_{1}-m_{1} \right) \cdots \left( n_{L}-m_{L} \right) \right) \right) \]

\[ \times \sum_{y=1}^{L} \left( \sum_{d_{1}=0}^{m_{1}-l_{1}} \cdots \sum_{d_{L}=0}^{m_{L}-l_{L}} \left( \sum_{d_{1}+\cdots+d_{L}=y} \left( m_{1}-l_{1} \right) \cdots \left( m_{L}-l_{L} \right) \right) \right) \]

\[ \times \mathcal{C} \left( \mathcal{F}_{j}(\tau), \mathcal{F}_{j}(s), 1, 1 \leq j \leq L, j \neq i, \mathcal{F}_{i}(\tau), \mathcal{F}_{i}(s), \mathcal{F}_{i}(s+\delta), 1 \right) \]

\[ + \sum_{l=0}^{L} \left( \sum_{r_{1}=0}^{n_{1}-m_{1}} \cdots \sum_{r_{L}=0}^{n_{L}-m_{L}} \left( \sum_{r_{1}+\cdots+r_{L}=l} \left( n_{1}-m_{1} \right) \cdots \left( n_{L}-m_{L} \right) \right) \right) \]

\[ \times \mathcal{C} \left( \mathcal{F}_{j}(\tau), \mathcal{F}_{j}(s), 1, 1 \leq j \leq L, j \neq i, \mathcal{F}_{i}(\tau), \mathcal{F}_{i}(s), \mathcal{F}_{i}(s+\delta), 1 \right) \]

\[ + P(M \cap L \cap K). \]
Finally, by replacing the obtained expressions in (B.1), we have

\[ A^{(i)}_{mL}(s, s + \delta, \tau) \]

\[ = \sum_{l=0}^{n-\sum_{j=1}^{L} m_j - 1} (-1)^{l+1} \sum_{r_1=0}^{n_1-m_1} \cdots \sum_{r_l=0}^{n_l-m_l} (n_1-m_1) \cdots (n_i-m_i-1) \]

\[ \cdots (n_L-m_L) \times \sum_{y=0}^{n-\sum_{j=1}^{L} (m_j-l_j)} (n_1-m_1) \cdots (n_i-m_i-1) \cdots (n_L-m_L) \]

\[ \times \tilde{C}\left(\bar{F}_j(\tau), \bar{F}_j(s), \frac{1}{l_j+d_j}, n_j-m_j-r_j \quad l_i+d_i, \frac{1}{m_i-l_i+r_i+1-d_i}, \frac{1}{n_i-m_i-r_i-1}\right) \]

\[ = \sum_{r_1=0}^{n_1-m_1} \cdots \sum_{r_l=0}^{n_l-m_l} (-1)^{l_1+\cdots+l_r} (n_1-m_1) \cdots (n_i-m_i-1) \cdots (n_L-m_L) \]

\[ \times \sum_{d_1=0}^{m_1-l_1} \cdots \sum_{d_L=0}^{m_L-l_L} (m_1-l_1) \cdots (m_L-l_L) \]

\[ \times \tilde{C}\left(\bar{F}_j(\tau), \bar{F}_j(s), \frac{1}{l_j+d_j}, n_j-m_j-r_j \quad l_i+d_i, \frac{1}{m_i-l_i+r_i+1-d_i}, \frac{1}{n_i-m_i-r_i-1}\right) \]

\[ \tilde{C}\left(\bar{F}_j(\tau), \bar{F}_j(s), \frac{1}{l_j+d_j}, n_j-m_j-r_j \quad l_i+d_i, \frac{1}{m_i-l_i+r_i+1-d_i}, \frac{1}{n_i-m_i-r_i-1}\right) \]

Acknowledgements

We would like to thank the Associate Editor and two anonymous referees for their constructive comments and suggestions, which led to improvements in the presentation of the paper.
Funding information

Asadi’s research work was performed in IPM Isfahan branch and was in part supported by a grant from IPM (no. 1400620212).

Competing interests

There were no competing interests to declare which arose during the preparation or publication process of this article.

References

[1] Ashrafi, S. and Asadi, M. (2017). The failure probability of components in three-state networks with applications to age replacement policy. J. Appl. Prob. 54, 1051–1070.
[2] Bayramoglu Kavlak, K. (2017). Reliability and mean residual life functions of coherent systems in an active redundancy. Naval Res. Logist. 64, 19–28.
[3] Behboudi, Z., Borzadaran, G. M. and Asadi, M. (2021). Reliability modeling of two-unit cold standby systems: a periodic switching approach. Appl. Math. Model. 92, 176–195.
[4] Coolen, F. P. A. and Cooleen-Maturi, T. (2013). Generalizing the signature to systems with multiple types of components. In Complex Systems and Dependability (Advances in Intelligent and Soft Computing 170), pp. 115–130. Springer, Berlin and Heidelberg.
[5] Dembinska, A. and Eryilmaz, S. (2021). Discrete time series-parallel system and its optimal configuration. Reliab. Eng. Syst. Saf. 215, 107832.
[6] Eryilmaz, S. (2017). The effectiveness of adding cold standby redundancy to a coherent system at system and component levels. Reliab. Eng. Syst. Saf. 165, 331–335.
[7] Eryılmaz, S. (2018). The number of failed components in a \( k \)-out-of-\( n \) system consisting of multiple types of components. Reliab. Eng. Syst. Saf. 175, 246–250.
[8] Eryilmaz, S. and Ucum, K. A. (2021). The lost capacity by the weighted \( k \)-out-of-\( n \) system upon system failure. Reliab. Eng. Syst. Saf. 216, 107914.
[9] Eryılmaz, S., Coolen, F. P. A. and Cooleen-Maturi, T. (2018). Marginal and joint reliability importance based on survival signature. Reliab. Eng. Syst. Saf. 172, 118–128.
[10] Eryilmaz, S., Coolen, F. P. A. and Cooleen-Maturi, T. (2018). Mean residual life of coherent systems consisting of multiple types of dependent components, applications to coherent systems. Naval Res. Logist. 65, 86–97.
[11] Eryilmaz, S., Özkurt, F. Y. and Rekan, T. E. (2020). The number of failed components in series-parallel system and its application to optimal design. Comput. Ind. Eng. 150, 106879.
[12] Fang, R. and Li, X. (2016). On allocating one active redundancy to coherent systems with dependent and heterogeneous components’ lifetimes. Naval Res. Logist. 63, 335–345.
[13] Fang, R. and Li, X. (2017). On matched active redundancy allocation for coherent systems with statistically dependent component lifetimes. Naval Res. Logist. 64, 580–598.
[14] Fang, R. and Li, X. (2018). On active redundancy allocation for coherent systems: from the viewpoint of minimal cut decomposition. Operat. Res. Lett. 46, 233–239.
[15] Fang, L., Balakrishnan, N. and Jin, Q. (2020). Optimal grouping of heterogeneous components in series-parallel and parallel-series systems under Archimedean copula dependence. J. Comput. Appl. Math. 377, 112916.
[16] Feng, G., Patelli, E., Beer, M. and Coolen, F. P. A. (2016). Imprecise system reliability and component importance based on survival signature. Reliab. Eng. Syst. Saf. 150, 116–125.
[17] Finkelstein, M., Hazra, N. K. and Cha, J. H. (2018). On optimal operational sequence of components in a warm standby system. J. Appl. Prob. 55, 1014–1024.
[18] Hashemi, M., Asadi, M. and Zarezadeh, S. (2020). Optimal maintenance policies for coherent systems with multi-type components. Reliab. Eng. Syst. Saf. 195, 106674.
[19] Huang, X., Coolen, F. P. A. and Cooleen-Maturi, T. (2019). A heuristic survival signature based approach for reliability–redundancy allocation. Reliab. Eng. Syst. Saf. 185, 511–517.
[20] Karimi, B., Niaki, S. T. A., Mirha, S. M., Ghare Hasanzuo, M. and Javanmard, S. (2019). A weighted \( K \)-means clustering approach to solve the redundancy allocation problem of systems having components with different failures. J. Risk. Reliab. 233, 925–942.
[21] Li, X. and Ding, W. (2010). Optimal allocation of active redundancies to \( k \)-out-of-\( n \) systems with heterogeneous components. J. Appl. Prob. 47, 254–263.
Optimal redundancy allocation in coherent systems

[22] MANNAI, N. AND GASMI, S. (2020). Optimal design of \( k \)-out-of-\( n \) system under first and last replacement in reliability theory. *Operat. Res.* **20**, 1353–1368.

[23] MIZUTANI, S., ZHAO, X. AND NAKAGAWA, T. (2019). Random age replacement policies with periodic planning times. *Internat. J. Reliab. Qual. Saf. Eng.* **26**, 1950023.

[24] NAVARRO, J. (2018). Distribution-free comparisons of residual lifetimes of coherent systems based on copula properties. *Statist. Papers* **59**, 781–800.

[25] NAVARRO, J., PELLEREY, F. AND DI CRESCENZO, A. (2015). Orderings of coherent systems with randomized dependent components. *Europ. J. Operat. Res.* **240**, 127–139.

[26] SAMANIEGO, F. J. (2007). *System Signatures and their Applications in Engineering Reliability*. Springer Science & Business Media.

[27] SAMANIEGO, F. J. AND NAVARRO, J. (2016). On comparing coherent systems with heterogenous components. *Adv. Appl. Prob.* **48**, 88–111.

[28] SHEN, J., HU, J. AND YE, Z. S. (2020). Optimal switching policy for warm standby systems subjected to standby failure mode. *IISE Trans.* **52**, 1262–1274.

[29] SOLTANI, R., SADJADI, S. J. AND TAVAKKOLI-MOGHADDAM, R. (2014). Robust cold standby redundancy allocation for nonrepairable series-parallel systems through Min-Max regret formulation and Benders’ decomposition method. *J. Risk. Reliab.* **228**, 254–264.

[30] TORRADO, N. (2021). On allocation policies in systems with dependence structure and random selection of components. *J. Comput. Appl. Math.* **388**, 113274.

[31] TORRADO, N., ARRIAZA, A. AND NAVARRO, J. (2021). A study on multi-level redundancy allocation in coherent systems formed by modules. *Reliab. Eng. Syst. Saf.* **213**, 107694.

[32] YOU, Y., FANG, R. AND LI, X. (2016). Allocating active redundancies to \( k \)-out-of-\( n \) reliability systems with permutation monotone component lifetimes. *Appl. Stoch. Models Business Industry* **32**, 607–620.

[33] ZAREZADEH, S. AND ASADI, M. (2019). Coherent systems subject to multiple shocks with applications to preventative maintenance. *Reliab. Eng. Syst. Saf.* **185**, 124–132.

[34] ZHANG, Y. (2018). Optimal allocation of active redundancies in weighted \( k \)-out-of-\( n \) systems. *Statist. Prob. Lett.* **135**, 110–117.

[35] ZHANG, Y., AMINI SERESHT, E. AND DING, W. (2017). Component and system active redundancies for coherent systems with dependent components. *Appl. Stoch. Models Business Industry* **33**, 409–421.

[36] ZHAO, X., AL-KHALIFA, K. N., HAMOUDA, A. M. AND NAKAGAWA, T. (2015). First and last triggering event approaches for replacement with minimal repairs. *IEEE Trans. Reliab.* **65**, 197–207.