Totally Asymmetric Torsion on Riemann-Cartan Manifold

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November 1, 2002

Abstract

A relativistic theory constructed on Riemann-Cartan manifold with a derived totally antisymmetric torsion is proposed. It follows the coincidence of the autoparallel curve and metric geodesic. The totally antisymmetric torsion $S_{[\lambda\mu\nu]}$ naturally appears in the theory without any ad hoc imposed on.

1 Introduction

Einstein-Cartan (EC) theory is one of the generalized Einstein’s General Relativity (GR) theories with Cartan’s affine connection. The antisymmetric part of affine connection namely torsion is introduced. Torsion is suggested to act as a source for gravitational field (Hehl et al 1976 and de Sabbata et al 1985), and could be an essential factor of quantization of spacetime (de Sabbata 1994) due to its interpretation of topological defect of spacetime manifold. However, at first glance the autoparallel curve

$$\frac{d^2x^\lambda}{ds^2} + \Gamma^\lambda_{\mu\nu} \frac{dx^\mu}{ds} \frac{dx^\nu}{ds} = 0 \quad (1.1)$$

with the presence of torsion and contorsion in the EC-theory does not seem to coincide to the metric geodesic

$$\frac{d^2x^\lambda}{ds^2} + \{\mu^\lambda_{\nu}\} \frac{dx^\mu}{ds} \frac{dx^\nu}{ds} = 0 \quad (1.2)$$

where

$$\Gamma^\lambda_{\mu\nu} = \{\mu^\lambda_{\nu}\} + S^\lambda_{\mu\nu} - (S^\lambda_{\mu\nu} + S^\lambda_{\nu\mu}) \quad (1.3)$$

is the component of the affine connection which is generally not symmetric, and $\{\mu^\lambda_{\nu}\}$ is the component of the metric connection known as Christoffel symbol. This paradox is so-called G-A problem which has recently been reviewed by Fiziev (1998).
Torsion with component $S_{\mu\nu}^\lambda$ is usually denoted by the antisymmetric part of the affine connection
\[ S_{\mu\nu}^\lambda = \frac{1}{2}(\Gamma_{\mu\nu}^\lambda - \Gamma_{\nu\mu}^\lambda). \tag{1.4} \]
or represented by torsion one-form. There would be many theoretical interesting phenomena if torsion happens to be totally antisymmetric as shown by de Sabbata and Gasperini (1985) and more recently developed by Hammond (1999). We attempt to show that torsion can reduce to a totally antisymmetric tensor, resulting the coincidence of the affine and metric geodesics. The totally antisymmetric torsion turns out to be a vector field or scalar field which appears on the RHS of the proposed field equation similar to many scalar-tensor theories as shown in the following sections.

2 The affine connection

We construct the theory on $U_4$ manifold as in EC-theory with the metricity condition
\[ \nabla g = 0 \]
and is assumed to satisfy the principle of equivalence. It should be noted that the $\nabla$ here is defined in terms of the affine connection which is similar to EC-theory (Hehl et al 1976), related to the metric connection by
\[ \Gamma_{\mu\nu}^\lambda = \{_{\mu}^\lambda_{\nu}\} + S_{\mu\nu}^\lambda - (S_{\lambda\mu\nu} + S_{\lambda\nu\mu}) \]
as stated in (1.3). At this moment we have to state a very useful theorem here which appears in every differential geometry books:

**Theorem** The exponential mapping $\exp_p$ is a diffeomorphism from a neighborhood of $0 \in T_p(M)$ to a neighborhood of $p \in M$.

According to Straumann’s analysis (Straumann 1984), if we choose a basis $e_1, \ldots, e_n$ of $T_p(M)$, then we can represent a neighborhood of $p$ uniquely by $\exp_p(x^i e_i)$. The set $(x^1, \ldots, x^n)$ are known as normal or Gaussian coordinates. Since $\exp_p(sv) = \gamma_v(s)$ (for some neighborhood $v \in V$ of $0 \in T_p(M)$, $\gamma$ is autoparallel along curve $\gamma$ and $s \in R$), the curve $\gamma_v(s)$ has normal coordinates $x^i = v^i t$, with $v = v^i e_i$. In terms of these coordinates, (1.1) becomes
\[ \Gamma_{\mu\nu}^\lambda \frac{dx^\mu}{ds} \frac{dx^\nu}{ds} = 0 \]
in $U_4$ manifold. Hence we have
\[ \Gamma_{\mu\nu}^\lambda(0) + \Gamma_{\nu\mu}^\lambda(0) = 0. \tag{2.1} \]
If the connection is symmetric, it follows that $\Gamma_{\mu\nu}^\lambda(0) = 0$. 

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The metric connection \( \{ \mu^\lambda \nu \} \) of course fulfils this situation according to standard GR. Vanishing of \( \Gamma^\lambda_{\mu \nu} \) and \( \{ \mu^\lambda \nu \} \) of (1.3) in normal coordinates directly implies

\[
(S^\lambda_{\mu \nu} + S^\lambda_{\nu \mu})_{p=0} = 0. 
\]

(2.2)

This tensor relation is valid at all points \( p \in U \subset U_4 \). It implies \( S^\lambda_{\mu \nu} = S^\lambda_{[\mu \nu]} \). Hence, with the definition of torsion (1.4) we have

\[
S^\lambda_{\mu \nu} = S_{[\lambda \mu \nu]}. 
\]

(2.3)

It follows that torsion in fact is a totally antisymmetric tensor as a consequence of vanishing symmetric affine connection in local inertial frame (Einstein elevator). This relation was firstly proposed by Yu (1989), and the simplified torsion can reduce to an axial vector or a scalar field if appropriate physical conditions are imposed. Recently, this equation becomes the basic assumption for Hammond to construct his relativistic theory to relate the current issues of quantum gravity (Hammond 1999, Gruver et al 2001). However, the originality of this complete antisymmetric property does not seem to be shown explicitly.

Equation (2.2) implies that the symmetric and antisymmetric parts of the affine connection simply are related by

\[
\Gamma^\lambda_{\mu \nu} = \{ \lambda^\mu \nu \} + S^\lambda_{\mu \nu}. 
\]

It follows the equality of symmetric affine connection and metric connection, resulting the coincidence of the affine geodesic (1.1) and metric geodesic (1.2) in our approach. This naturally comes from (2.1), giving a simpler geometry than that original torsion-contorsion picture in EC-theory, with physical observational phenomenon.

3 The field equations

Having settled the relation (2.3), the derivation of the field equations are pretty straightforward. The derivation of the field equations can be started from Cartan’s structure equations

\[
\Theta^\mu = d\theta^\mu + \omega^\mu_{\nu} \wedge \theta^\nu \\
\Omega^\mu_{\nu} = d\omega^\mu_{\nu} + \omega^\mu_{\lambda} \wedge \omega^\lambda_{\nu}
\]

where \( \Theta^\mu \) and \( \Omega^\mu_{\nu} \) are the usual torsion one-form and curvature two-form, with the spin connection \( \omega^\mu_{\nu} \) and anholonomic basis one-form \( \theta^\mu \). And

\[
\Omega^\mu_{\nu} = \frac{1}{2} R^\mu_{\nu \lambda \gamma} (\Gamma) \theta^\lambda \wedge \theta^\gamma \\
\Theta^\lambda = \frac{1}{2} S^\lambda_{\mu \nu} \theta^\mu \wedge \theta^\nu
\]

(3.1)

are defined in terms of the components of Riemann tensor \( R^\mu_{\nu \lambda \gamma} (\Gamma) \) and torsion tensor \( S^\lambda_{\mu \nu} \) in orthonormal frame.
The component of Ricci tensor due to the contraction of the first and third indices is defined by

\[ R_{\mu\nu}(\Gamma) = R_{\mu\nu} - \nabla_{\lambda} S_{\nu\mu}^{\lambda} - S_{\lambda\rho}^{\mu} S_{\nu\rho}^{\lambda} \]

where \( \nabla \) is the covariant derivative defined in terms of the Christoffel symbol. From now on, all the \( R^\lambda_{\gamma\mu\nu}, R_{\mu\nu}, R \) and \( G_{\mu\nu} \) etc. are defined in terms of the Christofel symbols as in GR unless those tensors are specified by \( \Gamma \). Hence, we have a set of symmetric and antisymmetric Ricci tensors, with components (we interchanged the indices of the torsions, so they appear in positive signs here)

\[ R_{(\mu\nu)}(\Gamma) = R_{\mu\nu} + S_{\mu\lambda}^{\rho} S_{\nu\rho}^{\lambda} \]

(3.2)

\[ R_{[\mu\nu]}(\Gamma) = \nabla_{\lambda} S_{\mu\nu}^{\lambda} \]

(3.3)

The component of the totally antisymmetric torsion \( S_{[\lambda\mu\nu]} \) in (2.3) implies the existence of a 4-vector \( P^\lambda \) such that

\[ S_{\lambda\mu\nu} = \varepsilon_{\lambda\mu\nu\rho} P^\rho \]

\[ S^{\lambda\mu\nu} = \varepsilon^{\lambda\mu\nu\rho} P_\rho \]

(3.4)

where \( \varepsilon_{\lambda\mu\nu\rho} \) is an unit alternating tensor, the covariant derivative of it is zero (Schouten 1954)

\[ \nabla_{\alpha} \varepsilon_{\lambda\mu\nu\rho} = 0. \]

Substituting (3.4) into (3.2), having simplified gives

\[ R_{(\mu\nu)}(\Gamma) = R_{\mu\nu} + 2 g_{\mu\nu} P_\alpha P^\alpha - 2 P_\mu P_\nu \]

(3.5)

and the required Ricci scalar by contraction is

\[ R(\Gamma) = R + 6 P_\alpha P^\alpha. \]

(3.6)

The divergence free field equation cannot simply be made by adding these two terms together with a \( -\frac{1}{2} g_{\mu\nu} \) factor of (3.6), since the second contracted Bianchi identity of the generalized Einstein tensor does not vanish. Our approach is different from Yu’s derivation of the field equation (Yu 1989), he first proposed the existence of the “generalized full field equation” such as

\[ R_{\mu\nu}(\Gamma) - \frac{1}{2} g_{\mu\nu} R(\Gamma) = \frac{8\pi G}{c^4} T_{\mu\nu} \]

where \( T_{\mu\nu} \) is defined as the generalized energy momentum tensor with the antisymmetric matter. Afterwards, he imposed the condition (2.3) on this to simplify the suggested field equation resulting a different scalar field terms from ours (the sign and coefficient of the scalar field terms) (see (3.15)). Here, we suggest that the field equation should be derived from the variational principle with the Ricci scalar (3.6) for a clear picture.
Before doing this let us first consider the antisymmetric Ricci tensor \( R_{[\mu\nu]}(\Gamma) \) with the assumption relating to the antisymmetric matter

\[
R_{[\mu\nu]} = \nabla_\lambda S_{\mu\nu}^\lambda = \chi T_{[\mu\nu]}
\]

(3.7)

where \( T_{[\mu\nu]} \) is suggested to be interpreted as the energy momentum tensor of intrinsic angular momentum of matter, or the intrinsic spin (Hehl et al. 1976 and de Sabbata et al. 1985), and \( \chi \) is the corresponding coupling constant. According to Eddington’s principle of identification in GR (Eddington 1924), \( T_{[\mu\nu]} \) should be related to both of the orbital angular momentum and spin of matter \( M_{\mu\nu}^\lambda \), giving the conservation law for the total angular momentum of field and matter via:

\[
\nabla_\lambda (S_{\mu\nu}^\lambda + M_{\mu\nu}^\lambda) = 0.
\]

(3.8)

When outside the source i.e. \( M_{\mu\nu}^\lambda = 0 \), torsion does not vanish in general according to this equation. This may be interpreted as the inherent intrinsic spin of spacetime structure.

Using condition (3.4) again, (3.7) gives the antisymmetric field equation in terms of the vector field \( h_\alpha \)

\[
\partial_\mu P_\nu - \partial_\nu P_\mu = -\frac{\chi}{2} \varepsilon_{\mu\nu\alpha\beta} T^{[\alpha\beta]}.
\]

(3.9)

This equation can be rewritten in terms of the dual of antisymmetric Ricci tensor \( \tilde{R}_{[\mu\nu]} \) where \( P^\lambda \) looks like the gauge potential in electromagnetic theory

\[
\partial_\mu P_\nu - \partial_\nu P_\mu = \tilde{R}_{[\mu\nu]}
\]

and \( \tilde{R}_{[\mu\nu]} \) becomes the field strength.

If there is no antisymmetric matter \( T_{[\mu\nu]} = 0 \), (3.9) gives two solutions

\[
P_\nu = 0 \quad \text{or} \quad P_\nu = \partial_\nu \phi
\]

(3.10)

in a star-shaped region, where \( \phi \) is a scalar (field).

Going back to the construction of (symmetric) field equation, substituting \( P_\nu = 0 \) into (3.6) gives the usual Ricci scalar in GR. For \( P_\nu = \partial_\nu \phi \), the Ricci scalar can be expressed in terms of the scalar field

\[
R(\Gamma) = R + 6 \partial_\alpha \phi \partial^\alpha \phi.
\]

(3.11)

According to Tupper (1974), the variational principle in such form

\[
\delta \int_D (R + \lambda \partial_\alpha \phi \partial^\alpha \phi + L_M) \sqrt{-g} \, d^4x = 0
\]

(3.12)

always gives the field equation

\[
G_{\mu\nu} = -\lambda \left( \partial_\mu \phi \partial_\nu \phi - \frac{1}{2} g_{\mu\nu} \partial_\alpha \phi \partial^\alpha \phi \right) + \kappa T_{\mu\nu}
\]

(3.13)
with the requirement of
\[ \nabla_\alpha \partial^\alpha \phi = 0 \] (3.14)
where \( \lambda \) is any real number, \( \kappa = 8\pi G/c^4 \), \( G_{\mu\nu} \) is the usual Einstein tensor defined in terms of the Christoffel symbol and \( T_{\mu\nu} \) is the energy momentum tensor of matter excluding the gravitational field. The derivation of the vacuum field equation is shown in Appendix. Tupper (1974) and many others have shown that any relativistic field equations in this form always predict the three classical tests of GR. It is indicated that the Lagrangian of matter \( L_M \) includes all physical field except gravity. The assumption that \( \phi \) satisfies (3.14) in order to the paths of test particles be geodesics implies that the scalar field does not couple with (symmetric) matter. Actually it has been demonstrated for the coincidence of the affine and metric geodesics in the previous section. By varying the Lagrangian \( L_M \) in (3.12) with respect to \( g_{\mu\nu} \), we have the usual energy momentum tensor of matter in (3.13). Putting \( \lambda = 6 \), we obtain the full field equation
\[ G_{\mu\nu} = -6 \left( \partial_\mu \phi \partial_\nu \phi - \frac{1}{2} g_{\mu\nu} \partial_\alpha \phi \partial^\alpha \phi \right) + \kappa T_{\mu\nu} \] (3.15)
for outside or non-existence of antisymmetric matter \( T_{[\mu\nu]} \). Nevertheless, we still have to justify the requirement (3.14). Taking the second contracted Bianchi identity \( \nabla_\nu G^{\mu\nu} = 0 \), (3.15) becomes
\[ (\nabla_\nu \partial^\nu \phi) \partial^\mu \phi + \kappa \nabla_\nu T^{\mu\nu} = 0. \]
For satisfying the covariant conservation law of matter and field, i.e. \( \nabla_\nu T^{\mu\nu} = 0 \), implies
\[ (\nabla_\nu \partial^\nu \phi) \partial^\mu \phi = 0 \]
giving the non-trivial result (3.14) as \( \partial^\mu \phi \neq 0 \).

The extra scalar field terms in most scalar-tensor theory or EC-theory might be interpreted as the “energy momentum of gravitational field”. However, the scalar terms in (3.13) seem to have counter-contribution of gravity, it contradicts to our common sense that gravity should be universal attractive. After all we do not find any anti-gravity matter. It should be noticed that the scalar field here does not come from (symmetric) matter, which is simply derived from the Riemann-Cartan geometry from the LHS. Or more appropriate it could be interpreted as the consequence of the inherent spacetime fabric translation due to torsion (Parallelly transporting a vector around a closed loop results the misfit to the original vector. The rotation of the transformed vector reveals curvature and the displacement reveals torsion). We might think such topological defect acts like a repulsive gravity at the very structure of spacetime, i.e. the quantum nature of spacetime. Having this idea singularities might be removed here, and it might act as a low energy limit cut-off in the (super)string and supergravity theory.
4 Conformal to Brans-Dicke theory

The vacuum field equation of (3.13) can be constructed from

\[ R_{\mu\nu} = -\lambda \partial_\mu \phi \partial_\nu \phi \]  \hspace{1cm} (4.1)

where it is the usual Ricci tensor defined in terms of the Christoffel symbols, contrary to the generalized Ricci tensor (3.3).

Consider two conformally related spacetime manifolds \( \bar{M} \) and \( M \) such that their metric satisfy

\[ g_{\mu\nu} = e^{2\phi} \bar{g}_{\mu\nu}. \]

The components of the Ricci tensors of \( \bar{M} \) and \( M \) are related by (Einsenhart 1925)

\[ R_{\mu\nu} = \bar{R}_{\mu\nu} + 2\nabla_\mu \partial_\nu \phi - 2\partial_\mu \phi \partial_\nu \phi + \bar{g}_{\mu\nu} \partial_\alpha \phi \partial^\alpha \phi + 2\bar{g}_{\mu\nu} \partial_\alpha \phi \partial^\alpha \phi \]  \hspace{1cm} (4.2)

where \( \phi \) denotes the scalar field in (4.1), \( R_{\mu\nu} \) and \( \bar{R}_{\mu\nu} \) are the corresponding Ricci tensors in the spacetime manifolds \( M \) and \( \bar{M} \), respectively.

Substituting (4.1) into (4.2) we have the field equation in the spacetime manifold \( \bar{M} \)

\[ \bar{R}_{\mu\nu} + 2\nabla_\mu \partial_\nu \phi + (\lambda - 2)\partial_\mu \phi \partial_\nu \phi + \bar{g}_{\mu\nu} \partial_\alpha \phi \partial^\alpha \phi + 2\bar{g}_{\mu\nu} \partial_\alpha \phi \partial^\alpha \phi = 0. \]  \hspace{1cm} (4.3)

If we put

\[ \phi = \frac{1}{2} \ln \varphi \]

(4.3) becomes

\[ \bar{R}_{\mu\nu} + \frac{1}{\varphi} (\nabla_\mu \partial_\nu \varphi + \frac{1}{2} \bar{g}_{\mu\nu} \partial_\alpha \varphi \partial^\alpha \varphi) + \frac{1}{4} (\lambda - 6) \frac{1}{\varphi^2} \partial_\mu \varphi \partial_\nu \varphi = 0. \]  \hspace{1cm} (4.4)

This equation is identical with the vacuum field equation of Brans-Dicke theory with the identification

\[ \lambda = 4\omega + 6 \]

where \( \omega \) is the Brans-Dicke parameter.

It can be shown that if \( \nabla_\alpha \partial^\alpha \phi = 0 \) in \( M \), the scalar field satisfies

\[ \nabla_\alpha \partial^\alpha \varphi = 0 \]

in the spacetime manifold \( \bar{M} \).

It is clearly seen that the proposed theory with \( \lambda = 6 \) is conformally related to the Brans-Dicke theory in vacuum. This leads to a vanishing Brans-Dicke parameter \( \omega \) for the conformal relation.
5 Conclusion

The construction and derivation of this theory is nothing new which is just based on the Riemann-Cartan spacetime manifold, however, with the importance of the vanishing affine connection property in local inertia frame. Nevertheless, it is not a special case of EC-theory with a totally antisymmetric torsion tensor where the vector field (or scalar field) interacts to the Lagrangian of matter \(L_M\). The derived scalar field \(\phi\) here does not couple to matter field in the variational principle (3.12). This assumption is due to a test particle always moving along a geodesic as stated before.

On the other hand, the scalar field \(\phi\) originates from (3.9) when \(T^{[\mu\nu]} = 0\). It is safe to put \(T^{[\mu\nu]}\) equal to zero even the suggestion of the relationship between antisymmetric matter and intrinsic spin is controversial. Down to the worst case, we still have one of the solution in (3.10) with \(P^\lambda = 0\), this gives the usual Einstein’s GR. It should be noted that torsion and contorsion need to vanish if EC-theory reduces to GR. However, we do not pre-suppose the vanishing of them as mentioned above.

The extra scalar term with a negative sign in (3.15) has some interesting features mentioned in section 3. We think that it is worth to further investigate for quantum geometry.

Appendix

Hamilton’s principle for the vacuum field equation

The hamiltonian variational principle for the field equations in vacuum is

\[
\delta \int_D R(\Gamma) \sqrt{-g} \, d^4x = 0 \tag{A.1}
\]

where \(R\) is the Ricci scalar given in (3.11), \(D\) is a compact region having a smooth boundary \(\partial D\). The variation of the metric are assumed vanish on \(\partial D\). (A.1) becomes

\[
\int_D \delta R_{\mu\nu}(\Gamma) g^{\mu\nu} \sqrt{-g} \, d^4x + \int_D R_{\mu\nu}(\Gamma) \delta (g^{\mu\nu} \sqrt{-g}) \, d^4x = 0. \tag{A.2}
\]

The component of the Ricci tensor is defined by (from (3.5))

\[
R_{\mu\nu}(\Gamma) = R_{\mu\nu} + 2(g_{\mu\nu} \partial_{\lambda} \phi \partial^{\lambda} \phi - \partial_{\mu} \phi \partial_{\nu} \phi). \tag{A.3}
\]

Similar to GR, \(g^{\mu\nu} \delta R_{\mu\nu}\) vanishes on the boundary of \(D\). Hence, from (A.3), after calculated we have

\[
g^{\mu\nu} \delta R_{\mu\nu}(\Gamma) = 2g^{\mu\nu} \delta g_{\mu\nu} \partial_{\lambda} \phi \partial^{\lambda} \phi + 8\delta g^{\mu\nu} \partial_{\mu} \phi \partial_{\nu} \phi + 6g^{\mu\nu} \delta (\partial_{\mu} \phi \partial_{\nu} \phi). \tag{A.4}
\]
However, the last term of above equation can be written in terms of the divergence

\[ 6g^{\mu\nu}\delta(\partial_\mu \phi \partial_\nu \phi) = 6g^{\mu\nu}\delta \partial_\mu (\phi \partial_\nu \phi) \]

where an assumed condition \( \partial_\lambda \partial^\lambda \phi = 0 \) is imposed. This vanishes on the boundary of \( D \) by Gauss’ theorem. Hence (A.4) is simplified as

\[ g^{\mu\nu}\delta R_{\mu\nu}(\Gamma) = 2g^{\mu\nu}\delta g_{\mu\nu}\partial_\lambda \phi \partial^\lambda \phi + \frac{8}{\sqrt{-g}}\delta g_{\alpha\beta}\partial^\alpha \phi \partial^\beta \phi. \]  \hspace{1cm} (A.5)

Using the relations

\[ \delta g^{\mu\nu} = -g^{\mu\alpha}g^{\nu\beta}\delta g_{\alpha\beta} \]

\[ \delta (g^{\mu\nu}\sqrt{-g}) = \sqrt{-g}\left(\frac{1}{2}g^{\mu\nu}g^{\alpha\beta} - g^{\mu\alpha}g^{\nu\beta}\right)\delta g_{\alpha\beta} \]

and substituting (A.3) and (A.5) into (A.2), having simplified we obtain

\[ \delta \int_D R(\Gamma)\sqrt{-g}\,d^4x \]

\[ = -\int_D (R^{\mu\nu} - \frac{1}{2}g^{\mu\nu}R)\delta g_{\mu\nu}\sqrt{-g}\,d^4x \]

\[ + \int_D 2(g_{\mu\nu}\partial_\lambda \phi \partial^\lambda \phi - \partial_\mu \phi \partial_\nu \phi)\left(\frac{1}{2}g^{\mu\nu}g^{\alpha\beta} - g^{\mu\alpha}g^{\nu\beta}\right)\delta g_{\alpha\beta}\sqrt{-g}\,d^4x \]

\[ + \int_D (2g^{\alpha\beta}\delta g_{\alpha\beta}\partial_\lambda \phi \partial^\lambda \phi - 8\delta g_{\alpha\beta}\partial^\alpha \phi \partial^\beta \phi)\sqrt{-g}\,d^4x \]

\[ = -\int_D \left[G^{\mu\nu} + 6 \left(\partial^\mu \phi \partial^\nu \phi - \frac{1}{2}g^{\mu\nu}\partial_\alpha \phi \partial^\alpha \phi\right)\right]\delta g_{\mu\nu}\sqrt{-g}\,d^4x. \]

It follows the vacuum field equation in covariant form

\[ G_{\mu\nu} = -6 \left(\partial_\mu \phi \partial_\nu \phi - \frac{1}{2}g_{\mu\nu}\partial_\alpha \phi \partial^\alpha \phi\right) \]

where \( G_{\mu\nu} \) is the component of the usual Einstein tensor defined in terms of the Christoffel symbol.

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