Conjugate Energy-Based Models

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Abstract

In this paper, we propose conjugate energy-based models (CEBMs), a new class of energy-based models that define a joint density over data and latent variables. The joint density of a CEBM decomposes into an intractable distribution over data and a tractable posterior over latent variables. CEBMs have similar use cases as variational autoencoders, in the sense that they learn an unsupervised mapping from data to latent variables. However, these models omit a generator network, which allows them to learn more flexible notions of similarity between data points. Our experiments demonstrate that conjugate EBMs achieve competitive results in terms of image modelling, predictive power of latent space, and out-of-domain detection on a variety of datasets.

1. Introduction

Deep generative models approximate a data distribution by combining a prior over latent variables with a neural generator, which maps latent variables to points on a data manifold. It is common to evaluate these models in terms of their ability to generate realistic examples, or their estimated densities for unseen data. However, an arguably more important use case for these models is unsupervised representation learning. If a generator can faithfully represent the data in terms of a lower-dimensional set of latent variables, then we hope that these variables will encode a set of semantically meaningful factors of variation that will be relevant to a broad range of downstream tasks.

Guiding a model towards a semantically meaningful representation requires some form of inductive bias. A large body of work on variational autoencoders (VAEs, (Kingma & Welling, 2013; Rezende et al., 2014)) has explored the use of priors as inductive biases. Relatively mild biases in the form of conditional independence are common in the literature on disentangled representations (Higgins et al., 2016; Kim & Mnih, 2018; Chen et al., 2018; Esmaeili et al., 2019). More generally, recent work has shown that defining priors that reflect the structure of the underlying data will lead to representations that are easier to interpret and generalize better. Examples include priors that represent objects in an image (Eslami et al., 2016; Lin et al., 2020b; Engelcke et al., 2019; Crawford & Pineau, 2019b), or moving objects in video (Crawford & Pineau, 2019a; Kosiorek et al., 2018; Wu et al., 2020; Lin et al., 2020a).

Despite steady progress, work on disentangled representations and structured VAEs still predominantly considers synthetic data. VAEs employ a neural generator that is optimized to reconstruct examples in the training set. For complex natural scenes, learning a generator that can produce pixel-perfect reconstructions poses fundamental challenges, given the combinatorial explosion of possible inputs. This is not only a problem for generation, but also from the perspective of the learned representation; a VAE must encode all factors of variation that give rise to large deviations in pixel space, regardless of whether these factors are semantically meaningful (e.g. presence and locations of objects) or not (e.g. shadows of objects in the background of the image).

The motivating question that we consider in this paper is whether it is possible to train latent-variable models without minimizing pixel-level discrepancies between an image and its reconstruction. Instead, we would like to design an objective that minimizes the discrepancy between the encoding of an image and the latent variables, which will in general be in a lower-dimensional space compared to the input. Our hope is that doing so will allow a model to learn more abstract representations, in the sense that it becomes easier to discard factors of variation that give rise to variation in pixel space, but should be considered noise.

In this paper, we consider energy-based models (EBMs) with latent variables as a particular instantiation of this general idea. EBMs with latent variables are by no means new; they have a long history in the context of restricted Boltzmann machines (RBMs) and related models (Smolensky, 1986; Hinton, 2002; Welling et al., 2004). Our motivation in the present work is to design a class of EBMs that retain the desirable features of VAEs, but employ a discriminative
energy function to model data at an intermediate level of representation that does not necessarily encode all features of an image at the pixel level.

Concretely, we propose conjugate EBMs (CEBMs), a new family of energy-based latent-variable models in which the energy function defines a neural exponential family. While the normalizer of CEBMs is intractable, we can nonetheless compute the posterior in closed form when we pair the generator network, \( \mu_\theta(z) \), and the output of an encoder network, \( \tilde{\mu}_\theta(x) \). See main text for details.

Our contributions can be summarized as follows:

1. We propose CEBMs, a class of energy-based models for unsupervised representation learning. The density of a CEBM factorizes into a tractable posterior and an energy-based marginal over data. This means that CEBMs can be trained using existing methods for EBMs, whilst inference is tractable at test time.

2. Unlike VAEs, CEBMs model data not at the pixel level, but at the level of the latent representation. We interpret the energy function of CEBMs in terms of a Bregman divergence in the latent space, and show that the density of a VAE can similarly be expressed in terms of a Bregman divergence in the data space.

3. We show that two of the most common inductive biases in VAEs can be incorporated in CEBMs: a spherical Gaussian and a mixture of Gaussians.

4. We evaluate how well CEBMs learned representations agree with class labels (which are not used during training). We show that neighbors are more likely to belong to the same class, which translates to increased performance in downstream classification tasks. Moreover, CEBMs perform competitively in out-of-domain detection. We do also note limitations; in particular we observe that CEBMs suffer from posterior collapse.

### 2. Background

#### 2.1. Energy-Based Models

An EBM (LeCun et al., 2006) defines a probability density for \( x \in \mathbb{R}^D \) via the Gibbs-Boltzmann distribution

\[
 p_\theta(x) = \frac{\exp \{ -E_\theta(x) \} }{Z_\theta}, \quad Z_\theta = \int dx \exp \{ -E_\theta(x) \}.
\]

The function \( E_\theta : \mathbb{R}^D \to \mathbb{R} \) is called the energy function which maps each configuration to a scalar value, the energy of the configuration. This type of model is widely used in statistical physics, for example in Ising models. The distribution can only be evaluated up to an unknown constant of proportionality, since computing the normalizing constant \( Z_\theta \) (also known as the partition function) requires an intractable integral with respect to all possible inputs \( x \).

Our goal is to learn a model \( p_\theta(x) \) that is close to the true data distribution \( p_{\text{data}}(x) \). A common strategy is to minimize the Kullback-Leibler divergence between the data distribution and the model, which is equivalent to maximizing the expected log-likelihood

\[
 \mathcal{L}(\theta) = \mathbb{E}_{p_{\text{data}}(x)} \left[ \log p_\theta(x) \right],
\]

\[
 = \mathbb{E}_{p_{\text{data}}(x)} \left[ -E_\theta(x) \right] - \log Z_\theta.
\]

The key difficulty when performing maximum likelihood estimation is that computing the gradient of \( \log Z_\theta \) is intractable. This gradient can be expressed as an expectation with respect to \( p_\theta(x) \),

\[
 \nabla \log Z_\theta = \mathbb{E}_{p_\theta(x')} \left[ -\nabla_\theta E_\theta(x') \right],
\]

which means that the gradient of \( \mathcal{L}(\theta) \) has the form:

\[
 \nabla_\theta \mathcal{L}(\theta) = -\mathbb{E}_{p_{\text{data}}(x)} \left[ \nabla_\theta E_\theta(x) \right] + \mathbb{E}_{p_\theta(x') \left[ \nabla_\theta E_\theta(x') \right].
\]

This corresponds to maximizing the probability of samples \( x \sim p_{\text{data}}(x) \) from the data distribution and minimizing the probability of samples \( x' \sim p_\theta(x') \) from the learned model.

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Contrastive divergence methods (Hinton, 2002) compute a Monte Carlo estimate of this gradient, which requires a method for approximate inference to generate samples \( x' \sim p_\theta(x) \). A common method for generating samples from EBMs is Stochastic Gradient Langevin Dynamics (SGLD, (Welling & Teh, 2011)), which initializes a sample \( x'_0 \sim p_\theta(x) \) and performs a sequence of gradient updates with additional injected noise \( \epsilon \),

\[
x'_{i+1} = x'_i - \frac{\alpha}{2} \frac{\partial E_\theta(x'_i)}{\partial x'_i} + \epsilon, \quad \epsilon \sim N(0, \alpha). \tag{3}
\]

SGLD is motivated as a discretization of a stochastic differential equation whose stationary distribution is equal to the target distribution. It is correct in the limit \( i \to \infty \) and \( \alpha \to 0 \), but in practice will have a bias.

The initialization \( x'_0 \) is crucial because it determines the number of steps needed to converge to a high-quality sample. For this reason, EBMs are commonly trained using persistent contrastive divergence (PCD, (Du & Mordatch, 2019; Tieleman, 2008)), which initializes some samples from a replay buffer \( B \) of previously generated samples (Nijkamp et al., 2019a; Du & Mordatch, 2019; Xie et al., 2016).

### 2.2. Energy-Based Latent-Variable Models

Energy-based latent-variable models are a subclass of EBMs where the energy function defines joint density on observed data \( x \in \mathbb{R}^D \) and latent variable \( z \in \mathbb{R}^K \).

\[
p_\theta(x, z) = \frac{\exp \left\{ -E_\theta(x, z) \right\}}{Z_\theta}. \tag{4}
\]

Some of the most well-known examples of this family of models include restricted Boltzmann machines (RBMs, (Smolensky, 1986; Hinton, 2002)), deep belief nets (DBNs, (Hinton et al., 2006)), and deep Boltzmann machines (DBMs, (Salakhutdinov & Hinton, 2009)).

Similar to standard EBMs, energy-based latent-variable models can also be trained using contrastive divergence methods, where the gradient of \( \mathcal{L}(\theta) \) can be expressed as:

\[
-\mathbb{E}_{p_{\text{data}}(x)p_\theta(z|x)}[\nabla_\theta E_\theta(x, z)] + \mathbb{E}_{p_\theta(x', z')}[\nabla_\theta E_\theta(x', z')].
\]

Estimating this gradient has the additional problem of requiring samples from the posterior \( p_\theta(z|x) \) which is also intractable in general.

### 2.3. Conjugate Exponential Families

An exponential family is a set of distributions whose probability density can be expressed in the form

\[
p(x \mid \eta) = h(x) \exp \left\{ \langle t(x), \eta \rangle - A(\eta) \right\}, \tag{5}
\]

where \( h : \mathcal{X} \to \mathbb{R}^+ \) is a base measure, \( \eta \in \mathcal{H} \subseteq \mathbb{R}^K \) is a vector of natural parameters, \( t : \mathcal{X} \to \mathbb{R}^K \) is a vector of sufficient statistics, and \( A : \mathcal{H} \to \mathbb{R} \) is the log normalizer (or cumulant function),

\[
A(\eta) = \log Z(\eta) = \int dx \ h(x) \exp \left\{ \langle t(x), \eta \rangle \right\}. \tag{6}
\]

If a likelihood belongs to an exponential family, then there exists a conjugate prior that is itself an exponential family

\[
p(\eta \mid \lambda, \nu) = \exp \left\{ \langle \eta, \lambda \rangle - A(\eta)\nu - B(\lambda, \nu) \right\}. \tag{7}
\]

The convenient property of conjugate exponential families is that both the marginal likelihood \( p(x \mid \lambda, \nu) \) and the posterior \( p(\eta \mid x, \lambda, \nu) \) are tractable. If we define

\[
\hat{\lambda}(x) = \lambda + t(x), \quad \hat{\nu} = \nu + 1,
\]

then the posterior and marginal likelihood are

\[
p(\eta \mid x, \lambda, \nu) = p(\eta \mid \hat{\lambda}(x), \hat{\nu}),
\]

\[
p(x \mid \lambda, \nu) = h(x) \exp \left\{ B(\hat{\lambda}(x), \hat{\nu}) - B(\lambda, \nu) \right\}. \tag{9}
\]

### 2.4. Legendre Duality in Exponential Families

Two convex functions \( A : \mathcal{H} \to \mathbb{R}^+ \) and \( A^* : \mathcal{M} \to \mathbb{R}^+ \) on spaces \( \mathcal{H} \subseteq \mathbb{R}^K \) and \( \mathcal{M} \subseteq \mathbb{R}^K \) are conjugate duals when

\[
A^*(\mu) := \sup_{\eta \in \mathcal{H}} \{ \langle \mu, \eta \rangle - A(\eta) \}. \tag{10}
\]

When \( A \) is a function of Legendre type (see Rockafellar (1970) for details), the gradients of these functions define a bijection between conjugate spaces by mapping points to their corresponding suprema

\[
\eta(\mu) = \nabla A^*(\mu), \quad \mu(\eta) = \nabla A(\eta), \tag{11}
\]

such that we can express \( A^*(\mu) \) at the supremum as

\[
A^*(\mu) = \langle \mu, \eta(\mu) \rangle - A(\eta(\mu)). \tag{12}
\]

The log normalizer \( A(\eta) \) of an exponential family is of Legendre type when the family is regular and minimal (\( \mathcal{H} \) is an open set and sufficient statistics \( t(x) \) are linearly independent; see Wainwright & Jordan (2008) for details). We refer to \( \mathcal{M} \) as the mean parameter space, since we can express any \( \mu \in \mathcal{M} \) as the expected value of the sufficient statistics

\[
\mu(\eta) = \mathbb{E}_{p(x \mid \eta)}[t(x)]. \tag{13}
\]

### 2.5. Bregman Divergences and Exponential Families

A Bregman divergence for a function \( F : \mathcal{M} \to \mathbb{R} \) that is continuously-differentiable and strictly convex on a closed set \( \mathcal{M} \) has the form

\[
D_F(\mu', \mu) = F(\mu') - F(\mu) - \langle \mu' - \mu, \nabla F(\mu) \rangle. \tag{14}
\]
We are interested in learning a probabilistic model that de-
Well-known special cases of Bregman divergences include
will explore energy-based models as an alternative to VAEs.
would like to measure agreement between latent variables
E
in this energy function,
θ
level of individual pixels, where it may be more difficult to
distinguish informative features from noise. To this end, we
In other words, the log density of an exponential family can be expressed in terms of a bias term
A
conjugate dual of the log normalizer
F
log
∗
t
This form of the energy function has a convenient property:
It corresponds to a model
p
θ,λ
x,z
which plays the role of an encoder by mapping high-dimensional data to a lower-dimensional vector of neural sufficient statistics. The function
η
maps latent variables to a vector of natural parameters in the same space as the neural sufficient statistics. The function
E
serves as an inductive bias, with hyperparameters
λ
that plays a role analogous to the prior.

1
We here omit the base measure
h(x)
for notational simplicity.

2
Or
A
(15)
θ,λ
x
conjugate energy-based models (CEBMs).

3
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We are interested in learning a probabilistic model that de-
defines a joint density
p
θ,λ
x,z
over high-dimensional data
x ∈ R^D
and a lower-dimensional set of latent variables
z ∈ R^K.

The intuition that guides our work is that we would like to measure agreement between latent variables and data at a high level of representation, rather than at the level of individual pixels, where it may be more difficult to distinguish informative features from noise. To this end, we will explore energy-based models as an alternative to VAEs.

Concretely, we propose to consider models of the form

\[ p_{\theta,\lambda}(x, z) = \frac{1}{Z_{\theta,\lambda}} \exp \left\{-E_{\theta,\lambda}(x, z)\right\}, \] (16)

where the energy function takes a form that is inspired by exponential family distributions

\[ E_{\theta,\lambda}(x, z) = -\langle \theta(x), \eta(z) \rangle + E_{\lambda}(z). \] (17)

In this energy function, \( \theta \) are the weights of a network
\( t_\theta : R^D \rightarrow R^H \), which plays the role of an encoder by mapping high-dimensional data to a lower-dimensional vector of neural sufficient statistics. The function
\( \eta : R^K \rightarrow R^H \) maps latent variables to a vector of natural parameters in the same space as the neural sufficient statistics. The function
\( E_{\lambda} : R^K \rightarrow R \) serves as an inductive bias, with hyperparameters \( \lambda \) that plays a role analogous to the prior.

We will consider a bias
\( E_{\lambda}(z) \) in form of a tractable exponential family with sufficient statistics \( \eta(z) \)

\[ E_{\lambda}(z) = -\log p_{\lambda}(z) = -\langle \eta(z), \lambda \rangle + B(\lambda). \] (18)

We can then express the energy function as

\[ E_{\theta,\lambda}(x, z) = -\langle \eta + t_\theta(x), \eta(z) \rangle + B(\lambda). \] (19)

This form of the energy function has a convenient property: It corresponds to a model
\( p_{\theta,\lambda}(x, z) \) in which the posterior
\( p_{\theta,\lambda}(z | x) \) is tractable. To see this, we make a substitution
\( \hat{\lambda}(x) = \lambda + t_\theta(x) \) analogous to the one in Equation 8, which allows us to express the energy as

\[ E_{\theta,\lambda}(x, z) = -\langle \eta(z), \hat{\lambda}(x) \rangle + B(\hat{\lambda}(x)) + E_{\theta,\lambda}(x), \] (20)

\[ E_{\theta,\lambda}(x) = -B(\hat{\lambda}(x)) + B(\lambda). \] (21)

We see that we can factorize the corresponding density

\[ p_{\theta,\lambda}(x, z) = p_{\theta,\lambda}(x) p_{\theta,\lambda}(z | x), \] (22)

which yields a posterior and marginal that are analogous to the distributions in Equation 9

\[ p_{\theta,\lambda}(z | x) = p(z | \hat{\lambda}(x)), \] (23)

\[ p_{\theta,\lambda}(x) = \frac{1}{Z_{\theta,\lambda}} \exp \left\{-E_{\theta,\lambda}(x)\right\}, \]

\[ = \frac{1}{Z_{\theta,\lambda}} \exp \left\{B(\hat{\lambda}(x)) - B(\lambda)\right\}. \] (24)

In other words, the joint density of this model factorizes into a tractable posterior
\( p_{\theta,\lambda}(z | x) \) and an intractable energy-based marginal likelihood
\( p_{\theta,\lambda}(x) \). This posterior is conjugate, in the sense that it is in the same exponential family as the bias. For this reason, we refer to this class of models as conjugate energy-based models (CEBMs).

4. Relationship to VAEs

CEBMs differ from VAEs in that they lack a generator network. Instead, the density is fully specified by the encoder network
\( t_\theta(x) \), which defines a notion of agreement
\( \langle \hat{\lambda}(x), \eta(z) \rangle \) between data and latent variables in the latent space. As with other exponential families, we can make this notion of agreement explicit by expressing the conjugate posterior in terms of a Bregman divergence using the decomposition in Equation 15

\[ E_{\theta,\lambda}(x, z) = D_{B_\star}(\eta(z), \hat{\mu}_\theta(x)) - B_\star(\eta(z)) + E_{\theta,\lambda}(x). \] (25)

Here
\( B_\star(\mu) \) is the conjugate dual of the log normalizer
\( B(\lambda) \), and we use
\( \hat{\mu}_\theta(x) = \mu(\hat{\lambda}(x)) \) as a shorthand for the mean-space posterior parameters. We see that maximizing the density corresponds to minimizing a Bregman divergence in the space of sufficient statistics of the bias.
In Figure 1, we compare CEBMs to VAEs in terms of the energy function for the log density of the generative model. In making this comparison, we have to keep in mind that these models are trained using different methods, and that VAEs have a tractable density \( p_\theta(x, z) \). That said, the objectives in both models maximize the marginal likelihood, so we believe that it is instructive to write down the corresponding Bregman divergence in the VAE likelihood. This likelihood is typically a Gaussian with known variance, or a Bernoulli distribution (when modeling binarized images). Both distributions have sufficient statistics \( t(x) = x \). Once again omitting the base measure \( h(x) \) for expediency, we can express the log density of a VAE as an energy

\[
E_{\theta, \lambda}(x, z) = -\log p_\theta(x|z) - \log p_\lambda(z),
\]

\[
= -(x, \eta_\theta(z)) + A(\eta_\theta(z)) - \log p_\lambda(z). \tag{26}
\]

Here \( A^*(x) \) is the conjugate dual of the log normalizer \( A(\eta) \), and we use \( \eta_\theta(z) \) and \( \mu_\theta(z) \) to refer to the output of the generator network in the natural-parameter and the mean-parameter space respectively. To reduce clutter and accommodate the case where a base measure \( h(x) \) is needed (e.g. that of a Gaussian likelihood with known variance), we will introduce the additional shorthands

\[
E(x) = -A(x) - \log h(x), \quad E_\lambda(z) = -\log p_\lambda(z). \tag{27}
\]

We then see that the energy function of a VAE has the form

\[
E_{\theta, \lambda}(x, z) = D_{A^*}(x, \mu_\theta(z)) + E(x) + E_\lambda(z). \tag{28}
\]

Like that of a CEBM, the energy function of a VAE contains a Bregman divergence, as well as two terms that depend only on \( x \) and \( z \). However, whereas the Bregman divergence in CEBM is defined in the mean-parameter space of the latent variables, that of a VAE is computed in the data space.

### 5. Inductive Biases

CEBM\(^1\)s have a property that is somewhat counter-intuitive. While the posterior \( p_{\theta, \lambda}(z | x) \) in this class of models is tractable, the prior is in general not tractable. In particular, although the bias \( -E_\lambda(z) \) is the logarithm of a tractable exponential family, it is not the case that \( p_{\theta, \lambda}(z) = p_\lambda(z) \).

Rather the prior \( p_{\theta, \lambda}(z) \) has the form,

\[
p_{\theta, \lambda}(z) = \frac{\exp\{-E_\lambda(z)\}}{Z_{\theta, \lambda}} \int dx \exp\{t_\theta(x), \eta(z)\}.
\]

In other words, \( E_\lambda(z) \) defines an inductive bias, but this bias is different from the tractable prior in a VAE\(^2\), in the sense that it imposes only a soft constraint on the geometry of the latent space.

In principle, the bias in a CEBM can take the form of any exponential family distribution. Since products of exponential families are also in the exponential family, this covers a broad range of possible biases. For purposes of evaluation in this paper, we will constrain ourselves to two cases:

1. **Spherical Gaussian.** As a bias that is analogous to the standard prior in VAEs, we consider a spherical Gaussian with fixed hyperparameters \( (\mu, \sigma) = (0, 1) \) for each dimension of \( z \in \mathbb{R}^K \).

\[
E_\lambda(z) = -\sum_k \left( (\eta(z_k), \lambda_k) - B(\lambda_k) \right).
\]

Each term has sufficient statistics \( \eta(z_k) = (z_k, z_k^2) \), natural parameters \( \lambda_k \), and log normalizer \( B(\lambda_k) \) as

\[
\lambda_k = \left( \frac{\mu}{\sigma^2}, -\frac{1}{2\sigma^2} \right) = \left( 0, -\frac{1}{2} \right),
\]

\[
B(\lambda_k) = -\frac{\lambda_k^2}{4\lambda_2} - \frac{1}{2} \log(-2\lambda_2).
\]

The marginal likelihood of the CEBM is then

\[
p_{\theta, \lambda}(x) = \frac{1}{Z_{\theta, \lambda}} \exp\left\{ \sum_k \left( B(\tilde{\lambda}_{\theta,k}(x)) - B(\lambda_k) \right) \right\},
\]

where \( \tilde{\lambda}_{\theta,k}(x) = \lambda + t_{\theta,k}(x) \) and \( t_{\theta,k}(x) \) is the sufficient statistics that corresponds to \( z_k \).

2. **Mixture of Gaussians.** In our experiments, we will consider datasets that are normally used for classification. These datasets, by design, exhibit multimodal structure that we would like to see reflected in the learned representation. In order to design a model that is amenable to uncovering this structure, we will extend the energy function in Equation 17 to contain a mixture component \( y \)

\[
E_{\theta, \lambda}(x, y, z) = -\{t_\theta(x), \eta(y, z)\} + E_\lambda(y, z).
\]

As an inductive bias, we will consider a bias in the form of a mixture of \( L \) Gaussians,

\[
E_\lambda(y, z) = -\sum_{k,l} I[y = l] \left( \langle \eta(z_k), \lambda_{l,k} \rangle - B(\lambda_{l,k}) \right).
\]

Here \( z \in \mathbb{R}^K \) is a vector of features and \( y \in \{1, \ldots, L\} \) is a categorical assignment variable. The bias for each component \( l \) is a spherical Gaussian with hyperparameters \( \lambda_{l,k} \) for each dimension \( k \). Again, using the notation \( \tilde{\lambda}_{\theta,l,k} = \lambda_{l,k} + t_{\theta,k}(x) \) to refer to the posterior parameters, then we obtain an energy

\[
E_{\theta, \lambda}(x, y, z) = -\sum_{k,l} I[y = l] \left( \langle \eta(z_k), \tilde{\lambda}_{\theta,l,k} \rangle - B(\lambda_{l,k}) \right).
\]
We can then define a joint probability over data $x$ and the assignment $y$ in terms of the log normalizer $B(\cdot)$,

\[ p_{\theta,\lambda}(x, y) = \frac{1}{Z_{\theta,\lambda}} \exp \left\{ \sum_{k,l} I[y = l] \left( B(\hat{\lambda}_{\theta,l,k}) - B(\lambda_{l,k}) \right) \right\}, \]

which then allows us to compute the marginal $p_{\theta,\lambda}(x)$ by summing over $y$. We optimize this marginal with respect hyperparameters $\lambda_{l,k}$ as well as the weights $\theta$.

6. Related Work

Energy-Based Latent-Variable Models. The idea of using EBMs to jointly model data and latent variables has a long history in the machine learning literature. Examples of this class of models include restricted Boltzmann machines (RBMs, (Smolensky, 1986; Hinton, 2002)), deep belief nets (DBNs, (Hinton et al., 2006)), and deep Boltzmann machines (DBMs, (Salakhutdinov & Hinton, 2009)). The idea of extending RBMs in exponential families and exploiting conjugacy to yield a tractable posterior is also not new and has been explored in Exponential Family Harmoniums (EFHs; (Welling et al., 2004)). These models differ from CEBMs in that they employ a bilinear interaction term $x^TWz$, which ensures that both the likelihood $p(x \mid z)$ and $p(z \mid x)$ are tractable. In CEBMs, the corresponding term $t_{\theta}(x)^TWz$ is nonlinear, which means that the posterior is tractable, but the likelihood is not. We provide a more detailed discussion regarding the connection of our work to this class of models in Appendix A.

EBMs for Image Modelling. Recent work has shown that EBMs with convolutional energy functions can accurately model distributions over images (Xie et al., 2016; Nijkamp et al., 2019a;b; Du & Mordatch, 2019; Xie et al., 2021a). This line of work typically focuses on generation and not on unsupervised representation learning as we do here. A line of work, which is similar to ours in spirit, employs EBMs as priors in the latent space of deep generative models (Pang et al., 2020; Aneja et al., 2020). These approaches, unlike our work, require a generator.

Interpretation of other models as EBMs. Grathwohl et al. (2019); Liu & Abbeel (2020); Xie et al. (2016) have proposed to interpret a classifier as an EBM that defines a joint energy function on the data and labels. CEBMs with a discrete bias can interpreted as the unsupervised variant of this model class. Che et al. (2020) interpret a GAN as an EBM defined by both the generator and discriminator.

Training EBMs. A commonly used training method is PCD (Tieleman, 2008), where the MCMC is initialized from a replay buffer that stores the previously generated samples (Du & Mordatch, 2019), or from a generator (Xie et al., 2018; 2020; 2021a). Nijkamp et al. (2019a;b) comprehensively investigate the convergence of PCD based on a variety of factors such as MCMC initialization, network architecture, and the optimizer. They find that the difference between the energy of the data and model samples is a good diagnostic of training stability. Many of these findings were helpful during the training and evaluation in our work.

There is a large literature on alternative training methods. Gao et al. (2020) propose to use the noise contrastive estimation (NCE, (Gutmann & Hyvärinen, 2010)), where they pretrain a flow-based noise model and then train the EBM to discriminate between the real data examples and the ones generated from the noise model. Another popular approach is the score matching (SM, Vértes et al. (2016); Hyvärinen & Dayan (2005); Vincent (2011); Song et al. (2020); Bao et al. (2020)), which learns EBMs by matching the gradient of the log probability density of the model distribution to that of the data distribution. Bao et al. (2020) propose a bi-level version of this method where it is also applicable to latent-variable models. To sidestep the need or MCMC sampling, Han et al. (2019; 2020); Xie et al. (2021b) jointly train an EBM with a VAE in an adversarial manner; Grathwohl et al. (2021) learn a generator by entropy regularization. We refer the readers to Song & Kingma (2021) for a more comprehensive discussion on training methods for EBMs.

7. Experiments

Our experiments evaluate to what extent CEBMs can learn representations that encode meaningful factors of variation, whilst discarding details about the input that we would consider noise. This question is difficult to answer in generality, and in some sense not well-posed; whether a factor of variation should be considered signal or noise can depend on context. For this reason, our experiments primarily focus on the extent to which representations in CEBMs can recover the multimodal structure in datasets that are normally used for classification. While class labels are an imperfect proxy, in the sense that they do not reflect all factors of variation that we may want to encode in a representation, they provide a means of quantifying differences between representations that were learned in an unsupervised manner.

We begin with a qualitative evaluation by visualizing samples and latent representation. We then demonstrate that learned representations align with class structure, in the sense that nearest neighbors in the latent space are more likely to belong to the same class (section 7.2). Next, we evaluate performance on out-of-distribution detection (OOD) tasks which, although not our primary focus in this paper, are a common use case for EBMs (Section 7.3). We then quantify the extent to which the learned representations can improve performance in downstream task, we measure few-label classification accuracy for representations that
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Figure 2. Samples generated from a CEBM trained on MNIST, Fashion-MNIST, SVHN and CIFAR-10.

Figure 3. (Left) Samples from CIFAR-10 along with the top 2-nearest-neighbors in pixel space, the latent space of a VAE, and the latent space of a CEBM. (Right) Confusion matrices of 1-nearest-neighbor classification on CIFAR-10 based on L2 distance in the latent space. On average, CEBM representations more closely align with class labels compared to VAE.

were pre-trained without supervision (Section 7.4). Finally, we perform a more in-depth study of the latent space where we investigate to what extend the aggregate posterior distribution is close to the inductive bias as well how vulnerable CEBMs are to posterior collapse (Section 7.5).

7.1. Network Architectures and Training

Architectures & Optimization. The CEBMs in our experiments employ an encoder network $t_\theta(x)$ in the form of 4-layer CNN (as proposed by Nijkamp et al. (2019a)), followed by an MLP output layer. We choose the dimension of latent variables to be 128. We found that the optimization becomes difficult with smaller dimensions. We train our models using 60 SGLD steps, 90k gradient steps, batch size 128, Adam optimizer with learning rate 1e-4. For training stability, we L2 regularize energy magnitudes (proposed by Du & Mordatch (2019)). See Appendix C for details.

Hyperparameter Sensitivity. As observed in previous work (Du & Mordatch, 2019; Grathwohl et al., 2019), training EBMs is challenging and often requires a thorough hyperparameters search. We found that the choices of activation function, learning rate, number of SGLD steps, and regularization will all affect training stability. Models regularly diverge during training, and it is difficult to perform diagnostics given that $\log p_{\theta,\lambda}(x)$ cannot be computed. As suggested by (Nijkamp et al., 2019a), we found checking the difference in energy between data and model samples can help to verify training stability. In general we also observed a trade-off between sample quality and the predictive power of latent variables in our experiments. We leave investigation of the source of this trade-off to future work, but we suspect that this is because SGLD has more difficulty converging when the latent space is more disjoint.

7.2. Samples and Latent Space

We begin with a qualitative evaluation by visualizing samples from the model. While generation is not our intended use case in this paper, such samples do serve as a diagnostic that allows us to visually inspect what characteristics of the input data are captured by the learned representation.

Figure 2 shows samples from CEBMs trained on MNIST, Fashion-MNIST, SVHN, and CIFAR-10. We initialize the samples with uniform noise and run 500 SGLD steps. We observe that the distribution over images is diverse and captures the main characteristics of the dataset. Sample quality is roughly on par with samples from other EBMs (Nijkamp et al., 2019a), although it is possible to generate samples with higher visual quality using class-conditional EBMs (Du & Mordatch, 2019; Grathwohl et al., 2019; Liu & Abbeel, 2020) (which assume access to labels).

To assess to whether the representation in CEBMs aligns with classes in each dataset, we look at the agreement between the label of an input and that of its nearest neighbor in the latent space. The latent representations are inferred by
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Table 1. AUROC scores in OOD Detection. We use $\log p_{\theta}(x)$ and $\|\nabla_x \log p_{\theta}(x)\|$ as score functions. The left block shows results of the models trained on F-MNIST and tested on MNIST, E-MNIST, Constant (C); The right block shows results of the models trained on CIFAR-10 and tested on SVHN, Texture and Constant (C).

|                      | Fashion-MNIST |                      | CIFAR-10 |
|----------------------|---------------|----------------------|----------|
|                      | $\log p_{\theta}(x)$ | $\|\nabla_x \log p_{\theta}(x)\|$ | $\log p_{\theta}(x)$ | $\|\nabla_x \log p_{\theta}(x)\|$ |
|                      | MNIST          | E-MNIST              | C        | SVHN          | Texture        | C        | SVHN          | Texture        | C        |
| VAE                  | .50            | .39                  | .09      | .61           | .57            | .01      | .42           | .58            | .41      | .38           | .51            | .37      |
| IGEBM                | .35            | .36                  | .90      | .78           | .82            | .96      | .45           | .31            | .64      | .33           | .17            | .62      |
| CEBM                 | .37            | .34                  | .90      | .82           | .89            | .98      | .47           | .32            | .66      | .31           | .17            | .54      |
| GMM-CEBM             | **.56**        | **.56**              | **.92**  | .56           | .80            | .95      | **.55**       | **.50**        | .62      | **.40**       | **.23**        | **.62** |

Table 2. Average classification accuracy on the test set. We train a variety of deep generative models on MNIST, Fashion-MNIST, CIFAR-10, and SVHN in an unsupervised way. Then we use the learned latent representations to train logistic classifiers with 1, 10, 100 training examples per class, and the full training set. We train each classifier 10 times on randomly drawn training examples.

| Models   | MNIST | Fashion-MNIST | CIFAR-10 | SVHN |
|----------|-------|---------------|----------|------|
|          | 1     | 10            | 100      | 1    | 10            | 100      | 1    | 10            | 100      | 1    |
| VAE      | 42    | 85            | 92       | 95   | 41            | 63        | 72   | 81   | 16            | 22        | 31   | 38   | 13            | 13        | 16   | 36   |
| GMM-VAE  | 53    | 86            | 93       | 97   | 49            | 68        | 79   | 84   | 19            | 23        | 33   | 39   | 13            | 14        | 23   | 56   |
| BIGAN    | 33    | 67            | 85       | 91   | 46            | 65        | 75   | 81   | 18            | 30        | 43   | 52   | 11            | 20        | 42   | 56   |
| IGEBM    | 63    | 89            | 95       | 97   | 50            | 70        | 79   | 83   | 16            | 26        | 33   | 42   | 10            | 16        | 35   | 49   |
| CEBM     | 67    | 89            | 95       | 97   | 52            | 70        | 77   | 83   | **19**        | **30**     | 42   | **53** | **12**        | **25**     | **48** | **70** |
| GMM-CEBM | **67**| **91**        | **97**   | **98**| **52**        | **70**    | **80**| **85**| 16            | 29        | 42   | 52   | 10            | 17        | 39   | 60   |

computing the mean of the posterior $p_{\theta,\lambda}(z|x)$. In Figure 3, we show samples from CIFAR-10, along with the images that correspond to the nearest neighbors in pixel space, the latent space of a VAE, and the latent space of a CEBM. The distance in pixel space is a poor measure of similarity in this dataset, whereas proximity in the latent space is more likely to agree with class labels in both VAEs and CEBMs. We additionally show visualization of the latent space with UMAP (McInnes et al., 2018) in Figure 5.

In Figure 3 (right), we quantify this agreement by computing the fraction of neighbors in each class conditioned on the class of the original image. We see a stronger alignment between classes and the latent representation in CEBMs, which is reflected in higher numbers on the diagonal of the matrix. On average, a fraction of 0.38 of the nearest neighbors are in the same class in the CEBM, whereas 0.45 of the neighbors are in the same class in the VAE, whereas 0.45 of the neighbors are in the same class in the VAE, whereas 0.45 of the neighbors are in the same class in the VAE, whereas 0.45 of the neighbors are in the same class in the VAE, whereas 0.45 of the neighbors are in the same class in the VAE, whereas 0.45 of the neighbors are in the same class in the VAE. On average, a fraction of 0.38 of the nearest neighbors are in the same class in the CEBM. This suggest that the representation in CEBMs should lead to higher performance in downstream classification tasks. We will evaluate this performance in Section 7.4.

7.3. Out-of-Distribution Detection

EBMs have formed the basis for encouraging results in out-of-distribution (OOD) detection (Du & Mordatch, 2019; Grathwohl et al., 2019). While not our focus in this paper, OOD detection is a benchmark that helps evaluate whether a learned model accurately characterizes the data distribution. In Table 1, we report results in terms of two metrics. The first is the area under the receiver-operator curve (AUROC) when thresholding the log marginal $\log p_{\theta,\lambda}(x)$.

7.4. Few-label Classification

To evaluate performance in settings where few labels are available, we use pre-trained representations (which were learned without supervision) to train logistic classifiers with 1, 10, 100 training examples per class, as well as the full training set. We evaluate classification performance for a spherical Gaussian bias (CEBM) and the mixture of Gaussians bias (GMM-CEBM). We compare our models against the IGEBM (Du & Mordatch, 2019), a standard VAE with the spherical Gaussian prior, GMM-VAE (Tomczak & Welling, 2018) where the prior is a mixture of Gaussians (GMM), and BIGAN (Donahue et al., 2016).

We report the classification accuracy on the test set in Table 2. CEBMs overall achieve a higher accuracy compared to VAEs in particular for CIFAR-10 and SVHN where the

4Since the IGEBM does not explicitly have latent representations, we extract features from the last layer of the energy function.
Table 3. KL divergence between aggregate posterior and prior and the mutual information between data and latent variables.

| Dataset  | VAE | CEBM | GMM-CEBM |
|----------|-----|------|----------|
|          | KL  | MI   | KL       | MI     |
| MNIST    | 11.5| 9.1  | 0.9      | 0.3    | 18.7 | 4.7 |
| FMNIST   | 3.5 | 9.0  | 0.6      | 0.4    | 8.1  | 3.9 |
| CIFAR10  | 21.5| 9.2  | 0.1      | 0.2    | 4.5  | 2.7 |
| SVHN     | 8.6 | 10.1 | 0.1      | 0.1    | 5.6  | 2.2 |

pixel distance is not good measure for similarity. Moreover, we observe that CEBMs outperform the IGEBM. This suggests that the inductive biases in CEBMs can lead to increased performance in downstream tasks. The performance between BIGANs and CEBMs is not as distinguishable which we suspect is due the fact BIGANs, just like CEBMs, do not define a likelihood that measure similarity at the pixel level. We also observe that the CEBM with the GMM inductive bias does not always outperform the one with the Gaussian inductive bias, which we suspect is due to GMM-CEBM having more difficulty to converge.

7.5. Limitations: Posterior Collapse

While our experiments demonstrate that CEBMs are able to reasonably approximate the data distribution and learn latent representations that are in closer agreement with class labels, they do not evaluate the learned notion of posterior uncertainty, and more generally the role of inductive bias. In this subsection, we ask the following two questions: (1) Does the aggregate posterior distribution of the training data live close to the inductive bias \(p_\lambda(z)\)? (2) What is the mutual information between latent variables and the training data?

To evaluate whether encoded examples are distributed according to the bias \(p_\lambda(z)\), we compute the divergence KL \((\theta, \lambda) \rvert p_\lambda(z)\) between the bias and the aggregate posterior, which is a mixture over training data

\[
\hat{p}_{\theta, \lambda}(z) = \frac{1}{N} \sum_n p_{\theta, \lambda}(z|\mathbf{x}_n), \quad \mathbf{x}_n \sim p_{\text{data}}(x).
\]

There are two reasons to consider this distribution, rather than the marginal \(p_{\theta, \lambda}(z)\) of the CEBM. The first is computational expedience; it is easier to approximate \(\hat{p}_{\theta, \lambda}(z)\) than it is to approximate \(p_{\theta, \lambda}(z)\), since the latter requires samples \(x \sim p_{\theta, \lambda}(x)\) from the marginal of the CEBM. The second reason is that \(\hat{p}_{\theta, \lambda}(z)\) reflects the distribution over features that we might use in a downstream task.

We approximate \(\hat{p}_{\theta, \lambda}(z)\) with a Monte Carlo estimate over batches of size 1k (see Esmaeili et al. (2019)), which we use to estimate both the KL and the mutual information (see Table 3). Because the marginal KL in CEBMs is significantly lower compared to VAEs across datasets, we conclude that CEBMs indeed attempted to place the aggregate posterior distribution close to the inductive bias.

Our evaluation of the mutual information proved more surprising; CEBMs learn a representation that has a very low mutual information between \(x\) and \(z\). The reason for this is that the posterior parameters \(\lambda_\theta(x) = \lambda + t_\theta(x)\) are dominated by the parameters of the bias \(\lambda\), which means that model essentially ignores the sufficient statistics \(t_\theta(x)\), which tend to have a small magnitude relative to \(\lambda\). This phenomenon could be interpreted as an instance of posterior collapse (Alemi et al., 2017), which has been observed in a variety of contexts when training variational autoencoders by maximizing the marginal likelihood, which in itself is not an objective that guarantees a high mutual information.

8. Discussion

In this paper, we introduced CEBMs, a class of latent-variable models that factorize into an energy-based distribution over data and a tractable posterior over latent variables. CEBMs can be trained using standard methods for EBMs and in this sense have a small “edit distance” relative to existing approaches, whilst also providing a mechanism for incorporating inductive biases for latent variables.

Our experimental results are encouraging but also raise questions. We observe a closer agreement between the unsupervised representation and class labels than in VAEs, which translates into improved performance in downstream classification tasks. At the same time, we observe that CEBMs do not learn a meaningful notion of uncertainty; the CEBM posterior is typically dominated by the inductive bias, which means that there is a very low mutual information between data and latent variables.

This work opens up a number of lines of future research. First and foremost, this work raises the question what objectives would be most suitable for learning energy-based latent-variable models in a manner maximizes agreement with respect to both the data distribution and the inductive bias terms, whilst also ensuring a sufficiently high mutual information between data and latent variables. More generally, we see opportunities to develop CEBMs with structured bias terms as an alternative to models based on VAEs in settings where we are hoping to reason about structured representations with little or no supervision.

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A. Connection to Exponential Family Harmoniums

As mentioned in Section 6, there is a long history of incorporating latent variables in EBMs, particularly in the context of restricted Boltzmann machines (RBMs) (Smolensky, 1986; Hinton, 2002), deep belief nets (Hinton et al., 2006), and deep Boltzmann machines (Salakhutdinov & Hinton, 2009). Moreover, the idea of formulating EBMs into the exponential family is also not new; Welling et al. (2004) proposed a new class of models called Exponential Family Harmoniums (EFHs) by extending RBMs into the exponential family. In this Section, we discuss the connection between our approach to these models. Concretely, we show that EFHs can be recovered a special case of CEBMs.

For observed variable $x$ and latent variable $z$, the energy of an RBM is defined as

$$E_{\theta}^{\text{RBM}}(x, z) = -\langle x^\top \theta_{xz}, z \rangle - \langle x, \theta_x \rangle - \langle z, \theta_z \rangle,$$

(29)

where $\theta_x \in \mathbb{R}^D$, $\theta_z \in \mathbb{R}^K$, and $\theta_{xz} \in \mathbb{R}^{D \times K}$. In RBMs, the conditional distributions $p_\theta(x|z)$ and $p_\theta(z|x)$ are both tractable which means that during contrastive divergence, we can sample $x \sim p_\theta(x)$ using Gibbs sampling.

EFHs extend these models into the exponential family by incorporating the sufficient statistics of $x$ and $z$ in the energy,

$$E_{\theta}^{\text{EFH}}(x, z) = -\langle t_x(x)^\top \theta_{xz}, t_z(z) \rangle - \langle t_x(x), \theta_x \rangle - \langle t_z(z), \theta_z \rangle,$$

(30)

where $t_x(\cdot)$ and $t_z(\cdot)$ are the sufficient statistics for variables $x$ and $z$ respectively. Welling et al. (2004) show that this energy function yields the following conditional distributions:

Likelihood

$$p_\theta(x|z) = \text{exp}\left\{\langle t_x(x), \tilde{\theta}_x \rangle - A(\tilde{\theta}_x)\right\}, \quad \tilde{\theta}_x = \theta_x + \theta_{xz}t_z(z),$$

(31)

Posterior

$$p_\theta(z|x) = \text{exp}\left\{\langle t_z(z), \tilde{\theta}_z \rangle - B(\tilde{\theta}_z)\right\}, \quad \tilde{\theta}_z = \theta_z + \theta_{zx}t_x(x),$$

(32)

where $\tilde{\theta}_x$ and $\tilde{\theta}_z$ are the canonical parameters, and $A(\cdot)$ and $B(\cdot)$ are the log normalizer of the models $p_\theta(x|z)$ and $p_\theta(z|x)$ respectively. Given that both conditional distributions are tractable, EFHs have the same advantage as RBMs: We can use a Gibbs sampler for sampling $x \sim p_\theta(x)$.

CEBMs can be considered an extension of EFHs. In Equation 17, we recover the energy function for an EFH by setting

$$t_\theta(x) = [t_x(x)^\top \theta_{xz}, \langle \theta_x, t_x(x) \rangle], \quad \eta(z) = [t_z(z), 1], \quad E_\theta(z) = -\langle t_z(z), \theta_z \rangle.$$

(33)

Perhaps the most crucial difference between CEBMs and EFHs (and other RBM-based models) is the non-linearity relationship between the observed and latent variables. The non-linearity in $t_\theta(\cdot)$ has the benefit of providing the flexibility to learn more complex structures in the data. This modelling choice however comes with a cost. In CEBMs, while the posterior is still tractable, the likelihood model is not. As a consequence, we lose the ability to use Gibbs sampling to sample $x \sim p_\theta(x)$. However, given that our motivation here is not to generate high quality samples at test time but to learn good representations representations, we believe giving up the ability to easily sample $x$ in order to learn more complex structures while keeping the posterior tractable is an appropriate trade-off.
Table 4. Comparison of energies in generative models. The functions $f_\theta(\cdot)$, $\eta_\theta(\cdot)$, and $t_\theta(\cdot)$ are typically deep neural networks (DNNs). In EBMs defined on only the data space (type $E_\theta(x)$) such as IGEBM, the DNN outputs a scalar value $f_\theta(x) : \mathbb{R}^D \to \mathbb{R}$. In EBMs defined on the data space as well as labels (type $E_\theta(x, y)$) such as JEM, the DNN outputs a vector of length $L$ corresponding to the number of classes $f_\theta(x) : \mathbb{R}^D \to \mathbb{R}^L$. In GAN, $D_\theta(x)$ refers to the discriminator.

### B. Derivation of Prior and Likelihood in a CEBM

**B.1. Prior**

\[
p_{\theta,\lambda}(z) = \int dx \frac{1}{Z_{\theta,\lambda}} \exp\{-E_{\theta,\lambda}(x, z)\} \\
= \frac{1}{Z_{\theta,\lambda}} \int dx \exp\{-E_{\theta,\lambda}(x, z)\} \\
= \frac{1}{Z_{\theta,\lambda}} \int dx \exp\{t_\theta(x), \eta(z)\} - E_\lambda(z)\}
\]

(34)\hspace{1cm} (35)\hspace{1cm} (36)

**B.2. Likelihood**

\[
p_{\theta,\lambda}(x|z) = \frac{p_{\theta,\lambda}(x, z)}{p_{\theta,\lambda}(z)} \\
= \frac{1}{Z_{\theta,\lambda}} \exp\{-E_{\theta,\lambda}(x, z)\} \\
= \frac{\exp(-E_\lambda(z))}{Z_{\theta,\lambda}} \int dx \exp\{t_\theta(x), \eta(z)\} \\
= \frac{\exp(-E_\lambda(z))}{Z_{\theta,\lambda}} \int dx \exp\{t_\theta(x), \eta(z)\} \\
= \int dx \exp\{t_\theta(x), \eta(z)\}
\]

(38)\hspace{1cm} (39)\hspace{1cm} (40)\hspace{1cm} (41)

### C. Training Details

In CEBMs and VAEs, we choose the dimension of latent variables to be 128. For CEBMS, we found that the optimization becomes difficult with smaller dimensions. We L2 regularize energy magnitudes (proposed by Du & Mordatch (2019)), where the coefficient of the L2 regularization term is 0.1. We empirically found that the training would become unstable
without this regularization. We train our models using 60 SGLD steps where we initialize samples from the replay buffer with 0.95 probability, and initialize from uniform noise with 0.05 probability. We train all the models with 90k gradient steps, batch size 128, Adam optimizer with learning rate $1e^{-4}$. When doing PCD, we used a reply buffer of size 5000. We set the $\alpha$ in the SGLD steps to be 0.075. Similar to Du & Mordatch (2019), we found it useful to add some noise to the image before encoding. In our experiments, we used Gaussian noise with $\sigma^2 = 0.03$. We used 50 GMM components for GMM-VAE and 10 GMM components for GMM-CEBM.
D. Model Architectures

Table 5, Table 7, and Table 6 show the architectures used for CEBM, VAE, and IGEBM, respectively.

### Table 5. Architecture of CEBM and GMM-CEBM

| Encoder | (a) MNIST and Fashion-MNIST. | Encoder | (b) CIFAR10 and SVHN. |
|---------|-------------------------------|---------|-----------------------|
| Input 28 × 28 × 1 images | 3 × 3 conv. 64 stride 1. padding 1. Swish. | Input 32 × 32 × 3 images | 3 × 3 conv. 64 stride 1. padding 1. Swish. |
| 3 × 3 conv. 64 stride 2. padding 1. Swish. | 4 × 4 conv. 64 stride 2. padding 1. Swish. | 4 × 4 conv. 128 stride 2. padding 1. Swish. |
| 4 × 4 conv. 32 stride 2. padding 1. Swish. | 4 × 4 conv. 32 stride 2. padding 1. Swish. | 4 × 4 conv. 256 stride 2. padding 1. Swish. |
| 4 × 4 conv. 32 stride 2. padding 1. Swish. | FC. 128 Swish. | 4 × 4 conv. 512 stride 2. padding 1. Swish. |
| FC. 128 Swish. | FC. 2 × 128 | FC. 1024 Swish. |
| FC. 128 Swish. | FC. 128 Swish. | FC. 128 Swish. |

### Table 6. Architecture of IGEBM

| Encoder | (a) MNIST and Fashion-MNIST. | Encoder | (b) CIFAR10 and SVHN. |
|---------|-------------------------------|---------|-----------------------|
| Input 28 × 28 × 1 images | 3 × 3 conv. 64 stride 1. padding 1. Swish. | Input 32 × 32 × 3 images | 3 × 3 conv. 64 stride 1. padding 1. Swish. |
| 3 × 3 conv. 64 stride 2. padding 1. Swish. | 4 × 4 conv. 64 stride 2. padding 1. Swish. | 4 × 4 conv. 128 stride 2. padding 1. Swish. |
| 4 × 4 conv. 32 stride 2. padding 1. Swish. | 4 × 4 conv. 32 stride 2. padding 1. Swish. | 4 × 4 conv. 256 stride 2. padding 1. Swish. |
| 4 × 4 conv. 32 stride 2. padding 1. Swish. | FC. 128 Swish. | 4 × 4 conv. 512 stride 2. padding 1. Swish. |
| FC. 128 Swish. | FC. 2 × 128 | FC. 1024 Swish. |
| FC. 128 Swish. | FC. 128 Swish. | FC. 128 Swish. |

### Table 7. Architecture of VAE and GMM-VAE

| Encoder | (a) MNIST and Fashion-MNIST. | Decoder | (b) CIFAR10 and SVHN. |
|---------|-------------------------------|---------|-----------------------|
| Input 28 × 28 × 1 images | 3 × 3 conv. 64 stride 1. padding 1. ReLU. | Input z ∈ ℝ^{128} latent variables | FC. 128 ReLU. FC. 3 × 3 × 32 ReLU. |
| 3 × 3 conv. 64 stride 1. padding 1. ReLU. | 4 × 4 conv. 64 stride 2. padding 1. ReLU. | 4 × 4 upconv. 32 stride 2. padding 1. ReLU. |
| 4 × 4 conv. 32 stride 2. padding 1. ReLU. | 4 × 4 conv. 32 stride 2. padding 1. ReLU. | 4 × 4 upconv. 64 stride 2. padding 1. ReLU. |
| 4 × 4 conv. 32 stride 2. padding 1. ReLU. | FC. 128 ReLU. FC. 2 × 128. | 4 × 4 upconv. 64 stride 2. padding 0. ReLU. |
| FC. 128 ReLU. FC. 2 × 128. | | 3 × 3 upconv. 1 stride 1. padding 0 |
| (b) CIFAR10 and SVHN. | | |
| Input 32 × 32 × 3 images | 3 × 3 conv. 64 stride 1. padding 1. ReLU. | Input z ∈ ℝ^{128} latent variables | FC. 128 ReLU. FC. 4 × 4 × 512 ReLU. |
| 3 × 3 conv. 64 stride 1. padding 1. ReLU. | 4 × 4 conv. 128 stride 2. padding 1. ReLU. | 4 × 4 upconv. 32 stride 2. padding 1. ReLU. |
| 4 × 4 conv. 128 stride 2. padding 1. ReLU. | 4 × 4 conv. 256 stride 2. padding 1. ReLU. | 4 × 4 upconv. 64 stride 2. padding 1. ReLU. |
| 4 × 4 conv. 512 stride 2. padding 1. ReLU. | 4 × 4 conv. 512 stride 2. padding 1. ReLU. | 3 × 3 upconv. 64 stride 2. padding 1. ReLU. |
| FC. 1024 ReLU. FC. 2 × 128. | | |
| | | 3 × 3 upconv. 1 stride 1. padding 1 |
### Table 8. Architecture of BIGAN for MNIST and Fashion-MNIST.

(a) MNIST and Fashion-MNIST.

| Discriminator | Encoder |
|---------------|---------|
| **Input**     | **Input** |
| $28 \times 28 \times 1$ images | $28 \times 28 \times 1$ images |
| $3 \times 3$ conv. 64 stride 1. padding 1. BN. LeakyReLU. | $3 \times 3$ conv. 64 stride 1. padding 1. BN. LeakyReLU. |
| $4 \times 4$ conv. 64 stride 2. padding 1. BN. LeakyReLU. | $4 \times 4$ conv. 64 stride 2. padding 1. BN. LeakyReLU. |
| $4 \times 4$ conv. 32 stride 2. padding 1. BN. LeakyReLU. | $4 \times 4$ conv. 32 stride 2. padding 1. BN. LeakyReLU. |
| $4 \times 4$ conv. 32 stride 2. padding 1. BN. LeakyReLU. | $4 \times 4$ conv. 32 stride 2. padding 1. BN. LeakyReLU. |
| **FC.** 128 LeakyReLU. | **256.** FC 128 LeakyReLU. FC. 1. Sigmoid. |

(b) CIFAR10 and SVHN.

| Generator | Encoder |
|-----------|---------|
| **Input** | **Input** |
| $z \in \mathbb{R}^{128}$ latent variables | $28 \times 28 \times 1$ images |
| $4 \times 4$ upconv. 64 stride 1. padding 1. BN. ReLU. | $3 \times 3$ conv. 64 stride 1. padding 1. BN. LeakyReLU. |
| $4 \times 4$ upconv. 64 stride 2. padding 1. BN. ReLU. | $4 \times 4$ conv. 64 stride 2. padding 1. BN. LeakyReLU. |
| $3 \times 3$ upconv. 32 stride 2. padding 1. BN. ReLU. | $4 \times 4$ conv. 32 stride 2. padding 1. BN. LeakyReLU. |
| $4 \times 4$ upconv. 32 stride 2. padding 1. BN. ReLU. | $4 \times 4$ conv. 32 stride 2. padding 1. BN. LeakyReLU. |
| $4 \times 4$ upconv. 1 stride 2. padding 1. Tanh. | $4 \times 4$ conv. 32 stride 2. padding 1. BN. LeakyReLU. |
| **FC.** 128 LeakyReLU. FC. 2 × 128. | **256 FC 128 LeakyReLU. FC. 1. Sigmoid.** |

### E. Additional Results

#### E.1. Confusion Matrices on 1-NN Classification

We perform 1-nearest-neighbor classification task for MNIST, Fashion-MNIST, SVHN, CIFAR10. We compute the L2 distance in the latent space of VAE, IGEBM and CEBM, and also in pixel space. We visualize the confusion matrices...
Conjugate Energy-Based Models

(a) MNIST

(b) Fashion-MNIST

(c) SVHN

(d) CIFAR10
Figure 5. CEBMs latent space visualized with UMAP for MNIST (Left) and FashionMNIST (Right).