Bonded Tri-Material Specimen Subjected to Shear-Off Testing: Predicted Interfacial Stresses

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Abstract

A physically meaningful and easy-to-use analytical model based on the concept of the interfacial compliance is developed for the evaluation of the interfacial shearing stresses at failure from the measured shear off force. The level of these stresses characterizes the adhesive strength of the bonding material of interest. A tri-material test specimen rigidly attached to an ideally strong immovable base is considered. The shear-off force is applied to its upper (“free”) component. It is assumed that the shear-off mechanical stresses are significantly higher than the residual thermally induced stresses, and therefore the latter do not have to be considered. The objective of the analysis is to determine the interfacial strength of the bonding material. It is shown that the distributions of the shearing stresses at the interfaces of this material with the bonded components mimic the shearing stress at the immovable base. The general concept is illustrated by a numerical example carried out for electronic silicon-copper assembly bonded using sintered silver. In this example the predicted stresses are higher at the interface of the bonding material with the upper, “free”, component than at its interface with the component attached to the immovable base. The suggested model can be used when there is an intent to select, during product development testing, the most feasible bonding material from the standpoint of its interfacial strength. Future work should include, first of all, experimental data and finite-element confirmation of the analytical suggested analytical model.

Introduction

The objective of the analysis that follows is to develop a simple, physically meaningful and easy-to-use analytical model for the prediction of stresses from the measured shear-off force. This is a typical product-development test in microelectronic packaging engineering (see, e.g., [1,2]). The model is based on the concept of the interfacial compliance. This concept was first applied in [3] and recently addressed in detail in [4]. The numerical example is carried out for the case of a sintered silver bond [5-14]. Sintered silver is, as is known, a good candidate for die bonding as an alternative to lead alloys. Little is known, however, about its mechanical properties, and shear off testing can shed important light on the macroscopic characteristics of this material and, first of all, on its bonding strength. It should be emphasized that actual experimentation, which is considered as future work, should be based on the data obtained on the basis of the suggested analytical model. It is desirable; of course, that the data obtained using the developed model is confirmed by finite-element-analysis (FEA). Another point that should be made in connection with the suggested model and the numerical analysis below is that the suggested tri-material body considers that the axial compliance of the adhesive layer (zero component in Figure 1) does not have to be by orders of magnitude larger than the axial compliances of the two other components (in our numerical analysis this compliance is about 7-9 times larger than the compliances of the two other components). This means that the suggested model can be used to decide if a simplified bi-material model (of the type suggested in Ref.3 in application to thermal stresses) could be used in the addressed problem.

Analysis

The distributed longitudinal force $T(x)$ acting in the cross-sections of the tri-material test-specimen (assembly) in...
Figure 1 can be sought in the form
\[
T(x) = C_0 + C_1 \sinh kx + C_2 \cosh kx \tag{1}
\]

where \( k \) is the parameter of the sought shearing stress. This parameter is loading independent and, for a stiff enough assembly that does not experience bending deformation can be evaluated as follows [15].

\[
k = \sqrt{\frac{k_{01}^2 + k_{02}^2}{2}} \left[ 1 + \sqrt{1 + \delta^2 \left( \frac{k_{01}^2}{k_{01}^2 + k_{02}^2} \right)^2} \right] \tag{2}
\]

where the following notation is used:

\[
k_{01} = \sqrt{\frac{\lambda_0 + \lambda_1}{\kappa_0 + \kappa_1}}, \quad k_{02} = \sqrt{\frac{\lambda_0 + \lambda_2}{\kappa_0 + \kappa_2}}, \quad \delta = \frac{\lambda_0^2}{(\lambda_0 + \lambda_1) + (\lambda_0 + \lambda_2)}
\]

\[
\lambda_0 = \frac{1 - \nu_0}{E_0 h_0}, \quad \lambda_1 = \frac{1 - \nu_1}{E_1 h_1}, \quad \lambda_2 = \frac{1 - \nu_2}{E_2 h_2}, \quad \kappa_0 = \frac{h_0}{G_0},
\]

\[
\kappa_1 = \frac{h_1}{3G_1}, \quad \kappa_2 = \frac{h_2}{G_2}
\]

\[
G_0 = \frac{E_0}{2(1 + \nu_0)}, \quad G_1 = \frac{E_1}{2(1 + \nu_1)}, \quad G_2 = \frac{E_2}{2(1 + \nu_2)}
\]

The partial parameters \( k_{01} \) and \( k_{02} \) refer to bi-material assemblies comprised of “zero” (bonding) and #1 components or of “zero” and #2 components; \( \lambda_0 \) \( \lambda_1 \) and \( \lambda_2 \) are axial compliances of the assembly components; \( \kappa_0 \) \( \kappa_1 \) and \( \kappa_2 \) are their interfacial compliances; \( G_0 \) \( G_1 \) and \( G_2 \) are the shear moduli of the component materials; \( E_0 \) \( E_1 \) and \( E_2 \) are their Young’s moduli; \( \nu_0 \) and \( \nu_1 \) are their Poisson’s ratios; and \( \delta \) is the parameter that characterizes the role of the relative axial compliances of the assembly components: when the “zero” component is considerably more compliant than the two outer components, this parameter is equal to 1. If all the three components have the same axial compliance, this parameter is equal to 0.25. When the “zero” component is very stiff, this parameter is zero.

The shearing stress \( \tau(x) \) can be found from (1) by differentiation:

\[
\tau(x) = T'(x) = k \left( C_1 \cosh kx + C_2 \sinh kx \right) \tag{2}
\]

For large enough \( x \) values one can put \( \cosh kx \approx \sinh kx \). It is clear also that the shearing stress is zero for cross-sections remote from the left end of the assembly, where the force \( T \) is applied. Then the equation (2) yields: \( C_1 = C_2 \) and the formulas (1) and (2) result in the following relationships for the total axial force acting in the assembly cross-sections and for the corresponding shearing stress:

\[
T(x) = C_0 + C_1 \left( \sinh kx - \cosh kx \right),
\]

\[
\tau(x) = T'(x) = kC_1 \left( \cosh kx - \sinh kx \right) \tag{3}
\]

The force \( T(x) \) should satisfy the boundary conditions:

\[
T(0) = T', \quad T(L) = 0. \tag{4}
\]

Then the expression (1) results in the following equations for the constants \( C_0 \) and \( C_1 \):

\[
C_0 - C_1 = T, \quad C_0 + \left( \sinh kL - \cosh kL \right)C_1 = 0, \tag{5}
\]

so that

\[
C_0 = T \frac{\sinh kL - \cosh kL}{\sinh kL - \cosh kL + 1}, \tag{6}
\]

and

\[
C_1 = T \frac{1}{\sinh kL - \cosh kL + 1}
\]

\[
T(x) = T \frac{\sinh kL - \cosh kL - \sinh kx + \cosh kx}{\sinh kL - \cosh kL + 1}
\]

\[
\tau(x) = -kT \frac{\cosh kx - \sinh kx}{\sinh kL - \cosh kL + 1} \tag{7}
\]

The maximum shearing stress takes place at the origin:

\[
\tau_{\text{max}} = \tau_2(0) = \frac{kT}{\sinh kL - \cosh kL + 1} \tag{8}
\]
This stress changes from infinity to \(-kT\), when the length \(L\) of the specimen changes from zero to a large enough value.

Let us determine now the shearing stresses acting at other interfaces of the assembly.

The longitudinal interfacial displacements can be sought, in accordance with the concept of the interfacial compliance [3], as

\[ u_{01}(x) = \lambda_0 \int_0^x T_0(\xi) d\xi - k_0 \tau_0(x) \]

\[ u_{10}(x) = \lambda_0 \int_0^x T_1(\xi) d\xi + k_1 \tau_1(x) \]

\[ u_{02}(x) = \lambda_0 \int_0^x T_0(\xi) d\xi - k_0 \tau_0(x) \]

\[ u_{20}(x) = \lambda_0 \int_0^x T_2(\xi) d\xi + k_2 \tau_2(x) \]

(9)

Where \( u_{01}(x) \) is the displacement of the “zero” component at its interface with the component #1; \( u_{10}(x) \) is the displacement of the component #1 at its interface with the “zero” component; \( u_{02}(x) \) is the displacement of the “zero” component at its interface with the component #2; \( u_{20}(x) \) is the displacement of the component #2 at its interface with the “zero” component; \( T_0(x), T_1(x) \) and \( T_2(x) \) are the forces acting in the cross-sections of the assembly components; \( \tau_0(x) \) is the shearing stress acting at the interface of the “zero” component with the component #2; \( \tau_1(x) \) is the shearing stress acting at the interface of the “zero” component with the component #1; \( k_0 = \frac{h_0}{G_0} \) is the interfacial compliance of the “zero” component; \( k_1 = \frac{h_1}{3G_1} \) is the interfacial compliance of the component #1; \( k_2 = \frac{h_2}{G_2} \) is the interfacial compliance of the component #2 (the formulas for the interfacial compliances are obtained based on the Ribière solution for a long-and-narrow strip [3,16] loaded over its long sides the way that the components in question are); \( G_0 = \frac{E_0}{2(1 + \nu_0)}, G_1 = \frac{E_1}{2(1 + \nu_1)} \) and \( G_2 = \frac{E_2}{2(1 + \nu_2)} \) are the shear moduli of the assembly component materials; \( E_0, E_1, E_2 \) and \( \nu_0, \nu_1, \nu_2 \) are their Young’s moduli and Poisson’s ratios; \( h_0, h_1, h_2 \) are the component thicknesses; \( \lambda_0 = \frac{1 - \nu_0}{E_0 h_0}, \lambda_1 = \frac{1 - \nu_1}{E_1 h_1} \) and \( \lambda_2 = \frac{1 - \nu_2}{E_2 h_2} \) are the axial stresses.

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**Figure 2:** Rationale behind the interfacial compliance model.
compliances of the components. These formulas consider the two-dimensional state of stress.

The first terms in the formulas (9) are based on the Hooke’s law and reflect an assumption that the longitudinal (axial) displacements are uniformly distributed over the cross-sections of the given assembly component. The second terms are corrections to this assumption. They consider that the interfacial displacements are somewhat different from the cross-sections (Figure 2).

The structure of these terms reflects an assumption that the interfacial shearing stresses acting in the cross-sections are somewhat different from the cross-sections of the given assembly component. The second terms are corrections to this assumption. They are products of the interfacial compliances and thus far un

\[ \tau_{\xi\xi} \int_0^\lambda \tau_{\xi}(\xi)d\xi - \lambda \int_0^\lambda \tau_{\xi}(\xi)d\xi = 0 \]

Obviously,

\[ T_0(x) = T - T_1(x) - T_2(x) \]

Then the equations (10) results in following system of equations:

\[ \frac{\kappa_0 + \kappa_1}{\tau_{\xi}(x)} - \frac{\lambda_0 + \lambda_1}{\int_0^\lambda \tau_{\xi}(\xi)d\xi - \lambda \int_0^\lambda \tau_{\xi}(\xi)d\xi} = \frac{\tau_0}{\tau_1}(x) \]

\[ \frac{\kappa_0 + \kappa_1}{\tau_{\xi}(x)} - \frac{\lambda_0 + \lambda_1}{\int_0^\lambda \tau_{\xi}(\xi)d\xi - \lambda \int_0^\lambda \tau_{\xi}(\xi)d\xi} = \frac{\tau_0}{\tau_1}(x) \]

The equations of equilibrium require that

\[ T_1(x) = \frac{\tau_0}{\tau_1}(x) + \frac{\tau_0}{\tau_1}(x) + \frac{\tau_0}{\tau_1}(x) + \frac{\lambda_0 + \lambda_1}{\int_0^\lambda \tau_{\xi}(\xi)d\xi - \lambda \int_0^\lambda \tau_{\xi}(\xi)d\xi} = \frac{\tau_0}{\tau_1}(x) \]

and therefore

\[ T_0(x) = \frac{\tau_0}{\tau_1}(x) \]

Then the equations (12) yield:

\[ (\kappa_0 + \kappa_1)\tau_{\xi}(x) + (\lambda_0 + \lambda_1)\tau_{\xi}(x) + \lambda_0\tau_0 = \lambda_0\tau_0 \]

As one could see from the second formula in (7),

\[ \tau_0''(x) = \kappa_2\tau_2(x) \]

Assuming that a similar relationship holds for the sought shearing stresses \( \tau_{\xi}(x) \) and \( \tau_0(x) \) the following system of algebraic equations for the shearing stress functions \( \tau_{\xi}(x) \) and \( \tau_0(x) \) could be obtained:

\[ \lambda_0\tau_0 + \left[ k^2(\kappa_0 + \kappa_1) + \lambda_0 + \lambda_1 \right] \tau_1(x) = \lambda_0\tau_1(x) \]

These equations have the following solutions:

\[ \tau_0(x) = -\frac{k^2}{k^2 + k_{k_{11}} + k_{k_{12}}} \tau_1(x) \]

Here some of the notations (3) were used. As one could see from the solutions (17) and (18), all the interfacial stresses have similar distributions, only their ordinates are, of course, different.

### Numerical Example

#### Input data

| Structural element                  | #1 (silicon) | #2 (copper) | 0 (bond) |
|-------------------------------------|--------------|-------------|----------|
| Thickness, mm                       | 0.5          | 1.0         | 0.20     |
| Young’s modulus, kg/mm²             | 19500        | 12000       | 6000     |
| Poisson’s ratio                      | 0.24         | 0.32        | 0.35     |
| Shear modulus, kg/mm²               | 7863         | 4545        | 2222     |
| Assembly length, L = 10.0 mm;       |              |             |          |
| Measured shear-off force, T = 1.0 kg/mm |          |             |          |

#### Calculated data

**Axial compliances:**

Silicon (Component #1)

\[ \lambda_1 = \frac{1 - \nu_1}{E_1h_1} = \frac{1 - 0.24}{19500 \times 0.5} = 7.7949 \times 10^{-5} \text{ mm/kg} \]

Copper (Component #2)

\[ \lambda_2 = \frac{1 - \nu_2}{E_2h_2} = \frac{1 - 0.24}{12000 \times 1.0} = 5.6667 \times 10^{-5} \text{ mm/kg} \]

Adhesive (“zero” component)

\[ \lambda_0 = \frac{1 - \nu_0}{E_0h_0} = \frac{1 - 0.35}{6000 \times 0.2} = 54.1667 \times 10^{-5} \text{ mm/kg} \]

**Interfacial compliances:**

Silicon (Component #1)

\[ \kappa_1 = \frac{h_1}{G_1} = \frac{0.5}{7863} = 6.3589 \times 10^{-5} \text{ mm/kg} \]

Copper (Component #2)

\[ \kappa_2 = \frac{h_2}{G_2} = \frac{1.0}{4545} = 22.0022 \times 10^{-5} \text{ mm/kg} \]

Adhesive (“zero” component)

\[ \kappa_0 = \frac{h_0}{3G_0} = \frac{0.2}{3 \times 2222} = 3.0003 \times 10^{-5} \text{ mm/kg} \]

**Partial parameters of the interfacial shearing stress:**
\[ k_0 = \frac{\lambda_0 + \lambda_1}{\sqrt{\kappa_0 + \kappa_1}} = \frac{54.1667 \times 10^{-7} + 7.7949 \times 10^{-8}}{3.0003 \times 10^{-7} + 6.3589 \times 10^{-7}} = 61.9616 \times \frac{9.3592}{2.5730} = 2.5730 \text{ mm}^{-1} \]

\[ k_2 = \frac{\lambda_2 + \lambda_3}{\sqrt{\kappa_2 + \kappa_3}} = \frac{54.1667 \times 10^{-7} + 5.6667 \times 10^{-7}}{3.0003 \times 10^{-7} + 22.0622 \times 10^{-7}} = 59.8334 \times \frac{25.0025}{4.7609} = 1.5470 \text{ mm}^{-1} \]

Parameter of the relative axial compliances:

\[ \delta = \frac{\lambda^2}{(\lambda_0 + \lambda_1)(\lambda_2 + \lambda_3)} = \frac{(54.1667 \times 10^{-7})^2}{(61.9616 \times 10^{-7})(59.8334 \times 10^{-7})} = 0.7914 \]

Parameter of the interfacial shearing stresses:

\[ k = \frac{\kappa^2}{2} \left [ 1 + \frac{24}{\lambda(\lambda_0 + \lambda_2)} \right ] = \frac{6.6203 + 2.3932}{2} \left [ 1 + \frac{1 + 0.7914}{2 \times 2.5730} \right ] = 3.1997 \text{ mm}^{-1} \]

The maximum stress in the bonding material is

\[ \frac{\tau_0(x)}{\tau_2(x)} \text{ ratio:} \]

\[ \frac{\left( \frac{k}{k_0} \right)^2 + 1}{10.2381} = \frac{6.6203 + 2.3932}{10.2381 + 2.5730} = 0.2047 \]

\[ \frac{\tau_1(x)}{\tau_2(x)} \text{ ratio:} \]

\[ \frac{\left( \frac{k}{k_0} \right)^2 + \frac{1}{\lambda_0} + \frac{1}{\lambda_2}}{0.7914 \times 1.1046 \times 4.2781} = \frac{6.6203 + 1.5465 + 4.2781}{6.6161 + 1.5465 + 4.2781} = 0.3006 \]

Thus, the shearing stresses at the bonding layer (“zero” component) interface with the lower component (component #2) are about 20.5% of the distributed shearing stresses at the interface of the component #2 with an immovable base, and the shearing stresses at the interface of the bonding layer with the upper component (component #1) are about 30% of the distributed shearing stresses of the of the component #2 with an immovable base.

With the measured shearing off force per unit assembly width of \( T = 1.0 \text{ kg/mm} \) the maximum shearing stress at the left end of the test specimen at its interface with the immovable base is

\[ \tau_{\max} = \tau_2(0) \approx -kT = -3.1997 \times 1.0 = -3.1997 \text{ kg/mm}^2 \]

The maximum stress in the bonding material is

\[ \tau_0(0) \approx -3.1997(-0.2047) = 0.6550 \text{ kg/mm}^2 \]

at its interface with the lower component (component #2) and is

\[ \tau_2(0) \approx -3.1997(-0.3006) = 0.9618 \text{ kg/mm}^2 \]

at its interface with the upper component (component #1).

**Conclusion**

A simple, easy-to-use and physically meaningful methodology has been developed for the evaluation of the interfacial stresses in a tri-material bonded test specimen from the measured shear-off force. Future work should include FEA, but, most importantly, experimental investigations based on the developed analytical technique.

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