Linear Response for a Family of Self-consistent Transfer Operators

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Abstract: We study a system of globally coupled uniformly expanding circle maps in the thermodynamic limit. The state of the system is described by a probability density and its evolution is given by the action of a nonlinear operator called the self-consistent transfer operator. Self-consistency is understood in the following sense: if $\varphi$ corresponds to the system’s state, then the evolution of $\varphi$ is given by the application of the transfer operator of the circle map $F_\varphi$. This is a $\varphi$—dependent map describing the dynamics of a single unit in the finite system where the interaction coming from all the nodes is replaced with the average of the interaction term with respect to the density $\varphi$. Assuming some level of smoothness of the coupled circle maps and of the coupling, we prove that when the coupling strength is sufficiently small, the system has a unique smooth stable state. We then show that this stable state is continuously differentiable as a function of the coupling strength. Finally, we prove that the derivative satisfies a linear response formula which at zero simplifies to a formula reminiscent to the one obtained for the linear transfer operators of perturbed expanding circle maps.

1. Introduction

A fundamental question in the theory of dynamical systems is how the statistical properties of a system change when it is subjected to perturbation. A system exhibits linear response if the invariant measure depends smoothly on the perturbation, and an expression for the derivative of the invariant measure (in the strong or in the dual sense) is called a linear response formula.

The rigorous study of linear response dates back to Ruelle, who proved linear response of uniformly hyperbolic Axiom A systems [29–31]. Similar results can be proved in some non-uniformly hyperbolic [12,37] or non-uniformly expanding cases.
such as intermittent maps [2,9,21] and piecewise expanding unimodal maps [7,8,32]. But caution is required, as examples for the lack of linear response are also well known [1,3,5,6] (see [4] for a more comprehensive collection of references). Deterministic systems subjected to random perturbations are also known to exhibit linear response in some cases [14,16]. In addition to theoretical works, linear response theory is successfully applied in geophysics, in particular climate science [24,25,27,28].

In this paper we rigorously prove a linear response formula for all-to-all weakly coupled uniformly expanding maps in the thermodynamic limit. To the best of our knowledge, there are few results available on linear response of complex systems with multiple interacting units. A program focusing on the control of statistical properties of extended systems by exploiting linear response was outlined by Mackay [26]. This question was further pursued in the case of a single dynamical unit defined by a uniformly expanding circle map [15] and by a smooth map of a compact smooth Riemannian manifold [20]. In case of coupled map lattices, the smooth dependence of the SRB measure and the linear response formula for was studied by Jiang and de la Llave [17,18]. Wormell and Gottwald [35,36] recently showcased numerical examples and some rigorous arguments for all-to-all coupled maps with mean-field interaction showing that it is possible for a high dimensional compound system to exhibit linear response, even if its units do not.

Our setup is based on the model studied by Fernandez [13]. The finite size model is described by \( M \) coordinates \((x_1, \ldots, x_M)\) with \( x_i \in \mathbb{T} \), whose evolution is given by

\[
    x_i(t + 1) = f \circ \Phi_\varepsilon (x_i(t); x_1(t), \ldots, x_M(t))
\]

(1)

where \( \Phi_\varepsilon : \mathbb{T} \times \mathbb{T}^M \rightarrow \mathbb{T} \),

\[
    \Phi_\varepsilon (x_i; x_1, \ldots, x_M) = x_i + \frac{\varepsilon}{M} \sum_{j=1}^{M} h \left(x_i, x_j\right),
\]

(2)

is a smooth mean-field all-to-all coupling between the coordinates (\( \varepsilon \) is the coupling strength\(^1\)), and \( f : \mathbb{T} \rightarrow \mathbb{T} \) is a sufficiently smooth map describing the uncoupled dynamics.

When taking the thermodynamic limit, \( M \rightarrow \infty \), one can replace the finite dimensional state space \( \mathbb{T}^M \) with the infinite-dimensional state space \( \mathbb{T}^\infty \), and the coupling term in (2) with

\[
    \lim_{M \rightarrow \infty} \frac{\varepsilon}{M} \sum_{j=1}^{M} h \left(x_i, x_j\right).
\]

The limit above might not exist. Let’s assume that for the initial condition \((x_i(0))_{i=1}^{\infty} \in \mathbb{T}^\infty \) there is a probability measure \( \mu \) such that

\[
    \lim_{M \rightarrow \infty} \frac{1}{M} \sum_{i=1}^{M} \delta_{x_i(0)} = \mu
\]

(3)

\(^1\) For example, when \( \varepsilon = 0 \), \( \Phi_0 \) equals the identity and the evolution of any coordinate \( i \) equals the uncoupled dynamics \( f \).
Linear Response for a Family of Self-consistent

where the limit is with respect to the weak convergence of measures. This assumption
ensures that for any continuous $h$,

$$
\lim_{M \to \infty} \frac{\varepsilon}{M} \sum_{j=1}^{M} h(x_i(0), x_j(0)) = \varepsilon \int h(x(0), y) d\mu(y),
$$

and the time evolution of each coordinate can be written as:

$$
x_i(1) = f \circ \Phi_{\varepsilon, \mu}(x_i(0)) \quad \text{where} \quad \Phi_{\varepsilon, \mu}(x) = x + \varepsilon \int h(x, y) d\mu(y).
$$

Calling $f_*$ and $(\Phi_{\varepsilon, \mu})_*$ the push-forwards of $f$ and $\Phi_{\varepsilon, \mu}$,

$$
\lim_{M \to \infty} \frac{1}{M} \sum_{i=1}^{M} \delta_{x_i(1)} = f_*(\Phi_{\varepsilon, \mu})_*(\mu)
$$

where the convergence is weak and follows from the continuity of the push forwards
(which only requires the continuity of $f$ and $\Phi_{\varepsilon, \mu}$). In case $\mu$ has a density $\varphi$ with
respect to a suitable reference measure (Lebesgue, for instance) it is sufficient to study
the evolution of the density. By the above argument, this is given by a transfer operator
that depends on the probability measure, thus $\varphi$ itself (for a precise definition, see (7)).
This nonlinear application is called a self-consistent transfer operator. This will be the
object under study in this paper.

Fernandez [13] studied the finite setting in the case of $h(x, y) = g(x - y)$ with $g : \mathbb{R} \to \mathbb{R}$ defined to be a specific discontinuous, but piecewise affine function. Studying
the thermodynamic limit of his setup in case of $\varepsilon$ sufficiently small, Bálint and Sélley [33]
first showed that when $f(x) = 2x \mod 1$, the constant function is the only smooth fixed
density. Expanding these results, in [10], they considered a general uniformly expanding
smooth circle map $f$, and showed that the invariant density is unique and a Lipschitz
continuous function of the coupling strength, with higher regularity being obstructed by
the discontinuity of the function $h$.

In this paper we present an approach based on convex cones of functions to study
self-consistent operators for general uniformly expanding $f$ and general $h$ satisfying
certain smoothness conditions. We show that in the weak coupling regime ($\varepsilon$ small), the
self-consistent operator has a unique fixed smooth density that depends in a differentiable
way on the coupling strength. Furthermore, we compute a linear response formula for
the density.

We believe that assuming stronger smoothness conditions on $h$ and $f$, higher
smoothness of the invariant density in terms of the coupling could be also achieved
and a quadratic response formula could be deduced, reminiscent of the formula obtained
in [16]. Another, more difficult, open question is whether one could apply ideas similar
to the one in this paper to treat the case where $h$ is not smooth. This would require
the definition of some suitable Banach spaces and cones playing analogous roles to the
spaces and cones of smooth functions that we consider here.

2 Notice that the existence of the limit and value of the limit in (3) depends, in general, on the ordering of
the coordinates.

Given a sequence of i.i.d. random variables $\{X_i\}_{i \in \mathbb{N}}$ such that the law of $X_i$ is given by $\mu$, then almost every
realization of the sequence $\{X_i\}_{i \in \mathbb{N}}$ satisfies (3). This is a consequence of the strong Law of Large Numbers
and the separability of continuous functions from $S^1$ to $\mathbb{R}$ with respect to the topology induced by the sup
norm.
1.1. Setup. Function spaces and norms

Let $S^1$ denote the unit circle and denote the Lebesgue (Haar) measure on $S^1$ by $\lambda$. Throughout this paper, we consider the representation of $S^1$ as the unit interval $[0, 1]$ with 0 and 1 identified. We denote by $L^1(S^1, \mathbb{R})$ the real valued functions on $S^1$ for which

$$\int_{S^1} |f| \, d\lambda < \infty$$

holds. Let $C^0(S^1, S^1)$ denote the space of continuous mappings of $S^1$, endowed with the norm

$$\|f\|_{C^0} = \max_{x \in S^1} |f(x)|.$$ 

For integers $k \geq 1$, let $C^k(S^1, S^1)$ denote the space of $k$-times continuously differentiable mappings of $S^1$, endowed with the norm

$$\|f\|_{C^k} = \max_{x \in S^1} |f(x)| + \sum_{\ell=1}^{k} \max_{x \in S^1} |f^{(\ell)}(x)|.$$ 

Uncoupled Dynamics

Let $f \in C^k(S^1, S^1)$ (with $k > 1$ to be specified later) be a uniformly expanding circle map, i.e. there exists an $\omega > 1$ such that $|f'(x)| > \omega$ for all $x \in S^1$, and denote by $P$ its transfer operator with respect to the Lebesgue measure. That is, $P : L^1(S^1, \mathbb{R}) \to L^1(S^1, \mathbb{R})$ is defined as

$$P \varphi(x) = \sum_{y \in f^{-1}(x)} \frac{\varphi(y)}{|f'(y)|}, \quad \varphi \in L^1(S^1, \mathbb{R}). \quad (4)$$

Mean-Field Coupling

Given $\varepsilon_0 > 0$, $t \in [-\varepsilon_0, \varepsilon_0]$, $h \in C^k(S^1 \times S^1, \mathbb{R})$ (with $k > 1$ to be specified later), and $\psi \in L^1(S^1, \mathbb{R}_0^+)^3$ with $\int_{S^1} \psi = 1$, define $\Phi_{t, \psi} : S^1 \to S^1$

$$\Phi_{t, \psi}(x) = x + t \int_{S^1} h(x, y) \psi(y) \, dy.$$ 

We assume that $\varepsilon_0 > 0$ is sufficiently small so that $\Phi_{t, \psi}$ is a diffeomorphism such that $\Phi'_{t, \psi} > 0$, and we denote by $Q_{t, \psi}$ its transfer operator. More precisely, similarly to (4), the operator $Q_{t, \psi} : L^1(S^1, \mathbb{R}) \to L^1(S^1, \mathbb{R})$ is defined as

$$Q_{t, \psi} \varphi(x) = \frac{\varphi}{\Phi_{t, \psi}^{-1}} \circ \Phi_{t, \psi}^{-1}(x), \quad \varphi \in L^1(S^1, \mathbb{R}). \quad (5)$$

The evolution of the density of states $\psi$ under the mean-field coupling is then given by the nonlinear application of $Q_t$ defined as $Q_t(\psi) := Q_{t, \psi} \psi$. In the following we use the short-hand notation $A_{\psi}(x) = \int_{S^1} h(x, y) \psi(y) \, dy$, so we write $\Phi_{t, \psi}(x) = x + t A_{\psi}(x)$. Thus substituting $\varphi = \psi$ in (5) gives the following expression for $Q_t$:

$$Q_t \psi(x) = \frac{\psi}{1 + t A_{\psi}} \circ \Phi_{t, \psi}^{-1}(x). \quad (6)$$

$\mathbb{R}_0^+$ is the set containing the positive real numbers together with 0.
**Coupled Dynamics** Define \( F_{t, \psi} := f \circ \Phi_{t, \psi} \), and let \( \mathcal{L}_{t, \psi} := PQ_{t, \psi} \) denote its transfer operator. Given \( t \in [-\varepsilon_0, \varepsilon_0] \), define the self-consistent transfer operator \( \mathcal{L}_t : L^1(S^1, \mathbb{R}) \to L^1(S^1, \mathbb{R}) \) as

\[
\mathcal{L}_t := PQ_t
\]

which describes the evolution of the all-to-all coupled system in the thermodynamic limit.

**Smooth densities** Throughout the paper we are going to work with the restrictions of \( P, Q_t \) and \( \mathcal{L}_t \) to some appropriate spaces of smoothly differentiable functions. These restrictions are well-defined: on the one hand, \( \phi \in C^\ell \) implies \( P\phi \in C^\ell \) for \( \ell < k \) supposing \( f \in C^k(S^1, S^1) \). On the other, if \( h \in C^{k'}(S^1 \times S^1, \mathbb{R}) \) then \( \Phi_{t, \psi} \in C^{k'}(S^1, S^1) \) for sufficiently small values of \( t \), thus \( Q_t \phi \in C^\ell \) for \( \ell < k' \).

By continuity, \( f \) is an \( N \)-fold covering map of \( S^1 \) for some \( N \in \mathbb{N} \). We make a technical assumption on \( f \) ensuring that the expansion is large enough and the distortion is small enough, more precisely

\[
N \left( \frac{\max |f''|}{\omega^3} + \frac{1}{\omega^2} \right) < 1.
\]

Note that for example the map \( f(x) = kx \mod 1 \) (where \( k \) is an integer) and moderate perturbations satisfy this condition. We remark that we could exclude this condition by working with higher iterates of the self-consistent transfer operator. However, this would complicate the calculations a great deal and we will assume (8) for the sake of clarity of the presentation. From now on, \( K > 0 \) will denote an unspecified positive number that depends on \( h \) and bounds of its derivatives only, while \( \tilde{K} > 0 \) is another unspecified constant depending also on \( f \), unless otherwise specified.

1.2. Summary of the results and outline of the paper. The first theorem of this paper claims that for \( t \) sufficiently small, the system has a unique equilibrium density \( \rho(t) \), and any sufficiently smooth initial state will evolve towards \( \rho(t) \).

**Theorem 1.1.** Assume \( f \in C^2(S^1, S^1) \) and \( h \in C^2(S^1 \times S^1, \mathbb{R}) \). Then, there is \( \varepsilon_0 > 0 \) sufficiently small such that for any \( t \in [-\varepsilon_0, \varepsilon_0] \), \( \mathcal{L}_t \) has a unique fixed non-negative probability density \( \rho(t) \in \text{Lip}(S^1, \mathbb{R}^+) \). Furthermore, there exist constants \( \tilde{K} > 0 \) and \( \Lambda < 1 \) such that for any non-negative \( \phi \in \text{Lip}(S^1, \mathbb{R}) \) with \( \int \phi = 1 \) it holds that

\[
\| \mathcal{L}_t^n \phi - \rho(t) \|_{C^0} \leq \tilde{K} \Lambda^n \quad \text{for all } n \in \mathbb{N}.
\]

**Remark 1.1.** A very similar result was stated by [19, Theorem 4]. However the coupling mechanism there is different in the sense that an integral average is computed from the current system statistic which feeds into the dynamics as a constant. Our coupling is more complicated: it varies from point to point due to the \( x \)-dependence of the function \( h \). However, the results and the methods that can be used to prove them are essentially the same. We view this statement as a preparatory result for the next theorem, our main result.

The second theorem claims that taking \( f \) and \( h \) sufficiently smooth, the dependence of \( \rho(t) \) on \( t \) is \( C^1 \) in a strong sense.

**Theorem 1.2.** Assume \( f \in C^5(S^1, S^1) \) and \( h \in C^5(S^1 \times S^1, \mathbb{R}) \). Then
There is an $\epsilon_1 > 0$, $\epsilon_1 \leq \epsilon_0$ such that $\rho(t) \in C^3(S^1, \mathbb{R})$ for all $t \in [-\epsilon_1, \epsilon_1]$;

(ii) There is an $\epsilon_2 > 0$, $\epsilon_2 \leq \epsilon_1$ such that $t \mapsto \rho(t)$ belongs to $C^1([-\epsilon_2, \epsilon_2], C^1(S^1, \mathbb{R}))$;

(iii) There is an $\epsilon_3 > 0$, $\epsilon_3 \leq \epsilon_2$ such that the following linear response formula holds for $|t| < \epsilon_3$:

$$\partial_t \rho(t)|_{t=i} = -\left(1 - P_{\hat{i}} + \hat{P}K_{\hat{i}}\right)^{-1} \hat{P}K_{\hat{i}}(\rho(\hat{i})),$$

where $P_{\hat{i}} = P_{Q_{\hat{i}, \rho(\hat{i})}}$ and the operator $K_{\hat{i}}$ is given by (10).

Remark 1.2. Both theorems depend intimately on the fact that when the coupling strength is sufficiently weak, the operators satisfy uniform Lasota-Yorke type inequalities implying uniform spectral properties. However, standard perturbation theory arguments are insufficient to obtain the results above due to the nonlinear character of the operators $\mathcal{L}_t$. Getting around the nonlinearity of the operators is where the main novelty of our approach lies.

We break down the proof of the above theorems into several propositions listed below and proved in the following sections.

In Sect. 2 we study existence, uniqueness and regularity of the fixed point for the self-consistent transfer operator $\mathcal{L}_t$ (7). To this end, we consider the cone of log-Lipschitz functions

$$\mathcal{V}_a := \left\{ \varphi : S^1 \to \mathbb{R}^+ : \frac{\varphi(x)}{\varphi(y)} \leq \exp(a|x - y|) \right\},$$

where $|x - y|$ denotes the Euclidean distance between $x$ and $y$ on the unit circle, and show that for large enough $a$, $\mathcal{L}_t$ keeps $\mathcal{V}_a$ invariant. Most importantly, we can also show that $\mathcal{L}_t$ is a contraction with respect to the Hilbert metric $\theta_a$ (see (11) below) on $\mathcal{V}_a$.

Remark 1.3. Cones of functions and the Hilbert metric are common tools to prove uniqueness of the invariant density for some linear transfer operators [23]. The standard approach uses the fact that a linear operator mapping a cone with finite diameter strictly inside itself is a contraction in the Hilbert metric. Unlike the standard case, $\mathcal{L}_t$ is a nonlinear operator, and one has to prove explicitly that $\mathcal{L}_t$ is a contraction.

Proposition 1.1. There is $a_0 > 0$ sufficiently large such that for $a > a_0$, there is $\epsilon_0 > 0$ sufficiently small such that for $t \in [-\epsilon_0, \epsilon_0]$, $\mathcal{L}_t$ keeps $\mathcal{V}_a$ invariant. Furthermore, there are $a > 0$, and $\epsilon_0 > 0$ small such that $\mathcal{L}_t$ is a contraction on $(\mathcal{V}_a, \theta_a)$ for any $t \in [-\epsilon_0, \epsilon_0]$.

The proof of Theorem 1.1 then follows by standard arguments showing that under repeated application of $\mathcal{L}_t$, all the elements in the cone $\mathcal{V}_a$ converge exponentially fast to the fixed point $\rho(t)$ (in the $C^0$ norm).

To show that the $C^5$-smoothness of $f$ and $h$ implies that $\rho(t) \in C^3(S^1, \mathbb{R})$, define the following set for the quadruple $\mathcal{C} = (C_1, C_2, C_3, C_4) \in (\mathbb{R}^+)^4$:

$$\mathcal{C}_C := \left\{ \varphi \in C^4(S^1, \mathbb{R}^+) : \int \varphi = 1, \left\| \frac{d^i \varphi}{dx^i} \right\|_{C^0} < C_i \quad i = 1, \ldots, 4 \right\}.$$

We show that

Proposition 1.2. There is $\epsilon_1 > 0$ and $C_1, C_2, C_3, C_4 > 0$ such that for $t \in [-\epsilon_1, \epsilon_1]$ $\mathcal{L}_t \mathcal{C}_C \subset \mathcal{C}_C$. 
The existence of a fixed point in \( C^3 \) is then implied by the fact that \( \mathcal{L}_f \) is continuous (Lemma 2.3 below), \( \mathcal{C}_C \) is relatively compact in \( C^3 \), and the Schauder fixed-point theorem. Since one can find \( \varphi \in \mathcal{C}_C \cap \mathcal{V}_a \) (for example take \( \varphi = 1 \)), the fixed point \( \rho \in \mathcal{V}_a \), whose existence was argued above, must belong to the closure of \( \mathcal{C}_C \) and therefore is in \( C^3 \), that will prove point (i) of Theorem 1.2.

In Sect. 3 we show that, when \( f \) and \( h \) are \( C^5 \), the curve of fixed points \( t \mapsto \rho(t) \) found above is \( C^1 \) from \([-\varepsilon_2, \varepsilon_2]\) to \( C^1(S^1, \mathbb{R}) \) for some \( \varepsilon_2 > 0 \).

**Remark 1.4.** In the case of a one-parameter family \( \{f_t\} \), of sufficiently smooth uniformly expanding maps, the strong differentiability in \( t \) follows from the spectral properties of the associated transfer operators and the smoothness of \( t \mapsto f_t \) [4]. Here, since the one-parameter family depends on the fixed density itself, i.e. \( \rho(t) \) is the fixed density of \( f_t = F_{t, \rho(t)} \) (self-consistent relation), the usual arguments do not apply since there is no a priori knowledge of the regularity of \( t \mapsto f_t \) that has to be established first.

This is achieved by showing that the set of curves

\[
\hat{\mathcal{C}}_{\varepsilon_2, K_1, K_2} := \left\{ \gamma : [-\varepsilon_2, \varepsilon_2] \to \mathcal{C}_C \text{ s.t.} \sup_{t, x} \left\| \frac{\partial}{\partial x} \gamma(t) \right\|_{C^3 < K_1}, \sup_{t, x} \left\| \frac{\partial^2}{\partial x^2} \gamma(t) \right\|_{C^2 < K_2} \right\}
\]

is invariant for suitably chosen \( K_1 \) and \( K_2 \) greater than zero under the mapping

\[
(L \gamma)(t) = L(t \gamma(t)) \quad \text{for all } t \in [-\varepsilon_2, \varepsilon_2]
\]

naturally defined by the family of operators on a curve.

**Proposition 1.3.** Choose \( C_1, C_2, C_3, C_4 > 0 \) so that Proposition 1.2 holds. Then there is \( \varepsilon_2 > 0 \) sufficiently small and \( K_1, K_2 > 0 \) such that

\[
\mathcal{L} \hat{\mathcal{C}}_{\varepsilon_2, K_1, K_2} \subset \hat{\mathcal{C}}_{\varepsilon_2, K_1, K_2}.
\]

Since \( \hat{\mathcal{C}}_{\varepsilon_2, K_1, K_2} \) is relatively compact in \( C^1([-\varepsilon_2, \varepsilon_2], C^1(S^1, \mathbb{R})) \), for any \( \gamma \in \hat{\mathcal{C}} \), there is an increasing sequence \( \{n_k\} \in \mathbb{N} \) and \( \overline{\gamma} \in C^1([-\varepsilon_2, \varepsilon_2], C^2(S^1, \mathbb{R})) \) such that \( \mathcal{L}^{n_k} \gamma \to \overline{\gamma} \), and since by Proposition (1.3) \( \mathcal{L}^{n_k}_t(\gamma(t)) \to \rho(t) \) for every \( t, \overline{\gamma}(t) = \rho(t) \). This proves point (ii) of Theorem 1.2.

In Sect. 4, we prove point (iii) of Theorem 1.2 by calculating a linear response formula. To ease the notation, we denote \( P_t := \mathcal{L}_{t, \rho(t)} \).

**Proposition 1.4.** We have the formula

\[
\partial_t \rho|_{t=0} = -(1 - P)^{-1} P(\rho(0) A_{\rho(0)})', \quad (9)
\]

where \( \partial_t \) is understood as \( \partial_t : C^1([-\varepsilon_3, \varepsilon_3], C^1(S^1, \mathbb{R})) \to C^0([-\varepsilon_3, \varepsilon_3], C^1(S^1, \mathbb{R})) \). More generally, for any \( \hat{t} \in (-\varepsilon_3, \varepsilon_3) \) where \( \varepsilon_3 \leq \varepsilon_2 \) as in Proposition 1.3,

\[
\partial_t \rho|_{t=\hat{t}} = -(1 - P_{\hat{t}} + \hat{t} P K_{\hat{t}})^{-1} P(K_{\hat{t}}(\rho(\hat{t})))
\]

where \( P_{\hat{t}} = P Q_{\hat{t}, \rho(\hat{t})} \) and

\[
K_{\hat{t}}(g) = \left( \left( \frac{\rho(t)}{\Phi_{\hat{t}, \rho(t)}^{-1}} A_g \right) \circ \Phi_{\hat{t}, \rho(t)}^{-1} \right)', \quad g \in C^1(S^1, \mathbb{R}). \quad (10)
\]

The formula in (9) is reminiscent of the one obtained in [4, Theorem 2.2] for perturbations of expanding circle maps. This is not surprising, since for \( t \) approaching 0 the operator is very close to linear.

At the end of the paper, “Appendix A” gathers some elementary formulae used throughout our calculations.
2. Invariant Densities for the Self-consistent Transfer Operators

We now show that the fixed point found above is unique using an invariant cone argument and the Hilbert metric. We remind the reader of our definition

\[ V_a := \{ \varphi : S^1 \to \mathbb{R}^+ : \frac{\varphi(x)}{\varphi(y)} \leq \exp(a|x - y|) \} . \]

and of the Hilbert metric

\[ \theta_a(\varphi, \psi) = \log \frac{1}{\alpha_a(\varphi, \psi) \alpha_a(\psi, \varphi)} \]

where

\[ \alpha_a(\psi, \varphi) = \inf \left\{ \varphi(x) e^{a|x-y|} \psi(x) - \varphi(y) \psi(y) : x \neq y \right\} . \]  

It is a known important fact that \( P \) is a contraction with respect to this metric (see e.g. [23, 34]). In the following we show that for suitable values of \( t \) and \( a > 0 \), the operator \( L_t \) is also a contraction. The lemmas below gather a few useful inequalities.

**Lemma 2.1.** There is \( \varepsilon_0 > 0 \) sufficiently small such that for every \( a > 0 \), every \( t \in (-\varepsilon_0, \varepsilon_0) \), and \( \varphi, \psi \in V_a \) with \( \int \varphi = \int \psi = 1 \),

\[ \left| \Phi_{t,\psi}(x) - \Phi_{t,\varphi}(x) \right| \leq K |t| ||\psi - \varphi||_{C^0} \]  

**Proof.** Notice that

\[ \left| \Phi_{t,\psi}(x) - \Phi_{t,\varphi}(x) \right| = |t| \left| \int \partial_1 h(x, y)(\psi(y) - \varphi(y)) \right| \leq |t| K ||\psi - \varphi||_{C^0} \]

By the mean value theorem, for any \( x \)

\[ \min |\Phi'_{t,\psi}| \leq \frac{|\Phi_{t,\psi}(\Phi_{t,\psi}(x)) - \Phi_{t,\psi}(\Phi_{t,\varphi}(x))|}{|\Phi_{t,\psi}(x) - \Phi_{t,\varphi}(x)|} \leq \frac{|\Phi_{t,\varphi}(\Phi_{t,\varphi}(x)) - \Phi_{t,\varphi}(\Phi_{t,\varphi}(x))|}{|\Phi_{t,\psi}(x) - \Phi_{t,\varphi}(x)|} \leq K |t||\psi - \varphi||_{C^0} |\Phi_{t,\psi}(x) - \Phi_{t,\psi}(x)| . \]

Since by assumption \( \min |\Phi'_{t,\varphi}| \geq 1 - K|t| > 0 \) for any \( \varphi \), (12) follows. \( \square \)

**Lemma 2.2.** There is \( \varepsilon_0 > 0 \) sufficiently small such that for every \( a > 0 \) there is \( K_a > 0 \) such that for every \( t \in (-\varepsilon_0, \varepsilon_0) \) and \( \varphi, \psi \in V_a \) with \( \int \varphi = \int \psi = 1 \), the following holds:

\[ \left| \Phi_{t,\psi}(x) - \Phi_{t,\varphi}(x) \right| \leq K_a |t| \max \left| 1 - \frac{\varphi}{\psi} \right| \]  

\[ \left| \Phi_{t,\varphi}(x) - \Phi_{t,\varphi}(y) \right| \leq (1 + K|t|)|x - y| \]

\[ \max \left| 1 - \frac{\varphi}{\psi} \right| \geq K_a \log \alpha(\varphi, \psi) \]
**Proof.** The proof of (13) follows along the same lines of the proof of Lemma 2.1 after noticing that
\[
\left| \int \partial_1 h(x, y)(\psi(y) - \varphi(y)) \right| \leq \max \psi \cdot \max \left| 1 - \frac{\varphi}{\psi} \right| \leq e^a K \cdot \max \left| 1 - \frac{\varphi}{\psi} \right|.
\]

Since \( \psi \in \mathcal{V}_a \) and has integral equal to one, \( \max \psi \leq e^a \). To prove (14), notice that for \( t \) sufficiently small \(|(\Phi_{t,\varphi}^{-1})'| < 1 + Kt\). To prove (15), pick \( x_0 \in \mathbb{T} \) such that \( \max |1 - \frac{\varphi}{\psi}| = 1 - \frac{\varphi}{\psi}(x_0) \). Then the inequality is implied by
\[
\log \alpha(\varphi, \psi) \leq \log \left( \frac{\varphi}{\psi}(x_0) \right) = \log \left[ 1 - \left( 1 - \frac{\varphi}{\psi}(x_0) \right) \right] \leq K_a^{-1} \left( 1 - \frac{\varphi}{\psi}(x_0) \right)
\]
as \( \varphi/\psi \) is lower bounded by \( e^{-\frac{a}{\psi}} \). Analogous conclusion holds if \( \max_{x \in \mathbb{T}} |1 - \frac{\varphi}{\psi}(x)| = \frac{\varphi}{\psi}(x_0) - 1 \) for some \( x_0 \in \mathbb{T} \).

We are now ready to prove Proposition 1.1.

**Proof of Proposition 1.1. Step 1 There is \( \lambda < 1 \) such that \( \mathcal{L}_t \mathcal{V}_a \subset \mathcal{V}_{\lambda a} \)**

First of all, we show that there is \( K \) such that \( Q_t \mathcal{V}_a \subset \mathcal{V}_{a + K(a+1)|t|} \) for \( t \) sufficiently small and \( a > 0 \). In fact, we show more. Pick \( \varepsilon_0 > 0 \) such that \( 1 - |t| \max |\partial_1 h| > 0 \) for \( t \in [-\varepsilon_0, \varepsilon_0] \). For any \( \varphi, \psi \in \mathcal{V}_a \) we have
\[
\frac{\varphi \circ \Phi_{t,\psi}^{-1}(x)}{\varphi \circ \Phi_{t,\psi}^{-1}(y)} \leq e^{a(1+K|t|)|x-y|} \quad \text{and} \quad \frac{(1 + t \partial_1 A_{\psi}) \circ \Phi_{t,\psi}^{-1}(y)}{(1 + t \partial_1 A_{\psi}) \circ \Phi_{t,\psi}^{-1}(x)} \leq e^{K|t||x-y|},
\]
where the bound on the first expression follows from \( \varphi \in \mathcal{V}_a \) and (14), while that on the second expression follows from the smoothness of \( h \) (in particular \( K \) depends on the norms of the derivatives of \( h \)). Thus
\[
\frac{Q_t \psi(x)}{Q_t \psi(y)} = \frac{\varphi \circ \Phi_{t,\psi}^{-1}(x)}{\varphi \circ \Phi_{t,\psi}^{-1}(y)} \frac{(1 + t \partial_1 A_{\psi}) \circ \Phi_{t,\psi}^{-1}(y)}{(1 + t \partial_1 A_{\psi}) \circ \Phi_{t,\psi}^{-1}(x)} \leq e^{(a+(a+1)K|t|)|x-y|}.
\]

Analogously, it is easy to check (by noticing that \( \left| \frac{f'(x)}{f'(y)} \right| \leq e^{\frac{1}{\omega} \max |f''||x-y|} \)) that if \( \varphi \in \mathcal{V}_a \) then \( P\varphi \in \mathcal{V}_{a/\omega + \max |f''|/\omega^2} \).

Picking
\[
a_0 := \frac{\max \{|f''|\}}{\omega(\omega - 1)}
\]
one has that for any \( a > a_0 \)
\[
a/\omega + \max |f''|/\omega^2 < a.
\]
Therefore, for any $a > a_0$ there is $\varepsilon_0 > 0$ and $a_1, a_2$ satisfying

$$a < a + (a + 1)K|\varepsilon_0| =: a_1 < a_2 < \omega \left( a - \frac{\max |f''|}{\omega^2} \right).$$

With this choice of $a_1$ and $a_2$ we have: $Q_tV_a \subset V_{a_1} \subset V_{a_2}$ for $t \in (-\varepsilon_0, \varepsilon_0)$, and $P\lambda_{a_2} \subset V_{\left( \frac{a_2 + \max |f''|}{\omega^2} \right)} \subset V_a$. More precisely, $\lambda_{a_2} \subset V_{\lambda a}$ with $\lambda < 1$ depending on $a$.\footnote{If $L_t$ were a linear operator, this would be enough to conclude that $L_t$ is a contraction with respect to the Hilbert metric. Since it is nonlinear, we need to show it directly by estimating the Hilbert distance.}

From now on, $a > a_0$ is considered to be fixed.

\textbf{Step 2} For $t$ small, $L_t: V_a \to V_a$ is a contraction with respect to $\theta_a$.

Let us start by showing how assuming

$$\theta_{a_2}(Q_t \varphi, Q_t \psi) \leq [1 + O(|t|)] \theta_a(\varphi, \psi) \tag{16}$$

yields the proof of the claim in Step 2. Recall that with the choice of $a$ and $a_2$ as in Step 1, $P: (V_{a_2}, \theta_{a_2}) \to (V_a, \theta_a)$ is a contraction as implied by the linearity of $P$ and the fact that $V_a \subset V_{a_2}$. Call $\sigma < 1$ the contraction rate, i.e. $\theta_a(P \varphi, P \psi) \leq \sigma \theta_{a_2}(\varphi, \psi)$ for any $\varphi, \psi \in V_{a_2}$. This and (16) imply that $\theta_a(L_t \varphi, L_t \psi) \leq \sigma [1 + O(t)] \theta_a(\varphi, \psi)$. Picking $|t|$ sufficiently small, equation (16) implies that $L_t$ is also a contraction.

Now we proceed with the proof of (16). Notice that by the triangle inequality

$$\theta_{a_2}(Q_t \varphi, Q_t \psi) \leq \theta_{a_2}(Q_t \varphi \varphi, Q_t \psi) + \theta_{a_2}(Q_t \psi \psi, Q_t \psi).$$

For the first term, the operator $Q_t \varphi$ is linear and maps the cone $V_a$ to $V_{a_1}$. $V_{a_1}$ is strictly inside the cone $V_{a_2}$. Since $Q_t(\varphi(\psi))$ is strictly contained in $V_{a_2}$ and its diameter in $(V_{a_2}, \theta_{a_2})$ is finite [34, Proposition 2.5], the mapping $Q_t: (V_a, \theta_a) \to (V_{a_2}, \theta_{a_2})$ is a contraction [34]. Therefore,

$$\theta_{a_2}(Q_t \varphi \varphi, Q_t \psi) \leq \theta_a(\varphi, \psi).$$

For the second term, computations are lengthier and occupy the rest of the proof. Recall that

$$\theta_{a_2}(Q_t \varphi, Q_t \psi) = \log \frac{1}{\theta_{a_2}(\varphi, \psi) \theta_{a_2}(\psi, \varphi)}$$

where $\alpha$ is the infimum of two expressions as defined in (11). For the first expression in the definition of $\alpha_{a_2}$:

$$\frac{Q_t \psi (x)}{Q_t \varphi (x)} = \frac{\psi \circ \Phi_{t, \varphi}^{-1}(x)}{\psi \circ \Phi_{t, \varphi}^{-1}(x)} \cdot \frac{(1 + t \partial_\varphi A_\psi) \circ \Phi_{t, \varphi}^{-1}(x)}{(1 + t \partial_\varphi A_\psi) \circ \Phi_{t, \varphi}^{-1}(x)} = \frac{\psi \circ \Phi_{t, \varphi}^{-1}(x)}{\psi \circ \Phi_{t, \varphi}^{-1}(x)} \cdot \frac{(1 + t \partial_\varphi A_\psi) \circ \Phi_{t, \varphi}^{-1}(x)}{(1 + t \partial_\varphi A_\psi) \circ \Phi_{t, \varphi}^{-1}(x)} \cdot \frac{(1 + t \partial_\psi A_\psi) \circ \Phi_{t, \psi}^{-1}(x)}{(1 + t \partial_\psi A_\psi) \circ \Phi_{t, \psi}^{-1}(x)}.$$

The bound on the first two factors follows from $\psi, \varphi \in V_a, (1 + t A_\varphi) \psi \in V_K|t|$ (again $K$ depends on bounds on $h$ and its derivatives), and from inequality (13) that give

$$\frac{\psi \circ \Phi_{t, \varphi}^{-1}(x)}{\psi \circ \Phi_{t, \varphi}^{-1}(x)} \cdot \frac{(1 + t \partial_\varphi A_\psi) \circ \Phi_{t, \varphi}^{-1}(x)}{(1 + t \partial_\varphi A_\psi) \circ \Phi_{t, \varphi}^{-1}(x)} \geq e^{-\left( a + K|t| \right) \Phi_{t, \varphi}^{-1}(x) - \Phi_{t, \varphi}^{-1}(x)} \geq e^{-a K|t| \max \left| 1 - \frac{\varphi}{\psi} \right|}.$$
For the third factor

\[
\frac{(1 + t \partial_x A \varphi)(x)}{(1 + t \partial_x A \varphi)(x)} = \frac{1 + t \int \partial_1 h(x, y) \psi(y) dy}{1 + t \int \partial_1 h(x, y) \varphi(y) dy} \geq 1 + t \int \partial_1 h(x, y) \varphi(y) dy + t \left( \min\left\{ \frac{\psi}{\varphi} \right\} - 1 \right) \int |\partial_1 h(x, y)| \varphi(y) dy
\]

\[
\geq 1 - K |t| \max \left| \frac{\psi}{\varphi} - 1 \right|
\]

\[
\geq \alpha_a(\varphi, \psi) K_a |t|.
\]

(17)

Putting all the estimates together and using (15) one obtains

\[
\frac{Q_{t, \varphi} \psi(x)}{Q_{t, \varphi} \varphi(x)} \geq \alpha_a(\varphi, \psi) K_a |t|.
\]

where \( K_a > 0 \) indicates a constant depending on \( h \) and on \( a \) only.

For the second expression in the definition of \( \alpha \) we need to estimate

\[
\frac{e^{a_2|x-y|} Q_{t, \varphi} \psi(x) - Q_{t, \varphi} \psi(y)}{e^{a_2|x-y|} Q_{t, \varphi} \psi(x) - Q_{t, \varphi} \psi(y)} = \frac{e^{a_2|x-y|} \psi \Phi_{t, \varphi}^{-1}(x) - \psi \Phi_{t, \varphi}^{-1}(y)}{e^{a_2|x-y|} \psi \Phi_{t, \varphi}^{-1}(x) - \psi \Phi_{t, \varphi}^{-1}(y)} = A \cdot B
\]

where

\[
A := e^{a_2|x-y|} \psi \Phi_{t, \varphi}^{-1}(x) - \psi \Phi_{t, \varphi}^{-1}(y)
\]

\[
B := e^{a_2|x-y|} \psi \Phi_{t, \varphi}^{-1}(x) - \psi \Phi_{t, \varphi}^{-1}(y)
\]

\[
A \geq \frac{e^{a_2|x-y|} \psi \Phi_{t, \varphi}^{-1}(x) - \psi \Phi_{t, \varphi}^{-1}(y)}{e^{a_2|x-y|} \psi \Phi_{t, \varphi}^{-1}(x) - \psi \Phi_{t, \varphi}^{-1}(y)} \geq e^{a_2|x-y|} |K_a| \max \left| 1 - \frac{\psi}{\varphi} \right| \geq e^{a_2|x-y|} |K_a| \max \left| 1 - \frac{\psi}{\varphi} \right|
\]

(18)

\[
\geq e^{a_2|x-y|} |K_a| \max \left| 1 - \frac{\psi}{\varphi} \right| \left( 1 + \frac{e^{-2K'|t|} \max \left| 1 - \frac{\psi}{\varphi} \right| - 1}{e^{a_2|x-y|} \psi \Phi_{t, \varphi}^{-1}(x) - \psi \Phi_{t, \varphi}^{-1}(y)} \right)
\]

(19)

\[
\geq e^{a_2|x-y|} |K_a| \max \left| 1 - \frac{\psi}{\varphi} \right| \geq \alpha_a(\varphi, \psi) K_a |t|
\]

(20)

where (18) follows from (13), (20) follows from the fact that the denominator in (19) is bounded since \( \psi \Phi_{t, \varphi}^{-1} \psi \) belongs to \( \mathcal{V}_a \) with \( a_1 < a_2 \), and \( K_a, K_a' \) and \( K_a'' \) are constants depending on \( a \). The factor \( B \) can be bounded in a similar way:

\[
B \geq \alpha_a(\varphi, \psi) K_a |t|.
\]
Putting together all the previous estimates one obtains
\[ \alpha_{a_2}(Q_{t,\varphi}, Q_{t,\psi}) \geq \alpha_a(\varphi, \psi)2^{K_a|t|}, \]
and analogously
\[ \alpha_{a_2}(Q_{t,\psi}, Q_{t,\varphi}) \geq \alpha_a(\psi, \varphi)2^{K_a|t|} \]
which implies
\[ \theta_{a_2}(Q_{t,\varphi}, Q_{t,\psi}) = \log \frac{1}{\alpha_{a_2}(Q_{t,\varphi}, Q_{t,\psi})\alpha_{a_2}(Q_{t,\psi}, Q_{t,\varphi})} \leq 2K_a|t|\theta_a(\varphi, \psi). \]

\[ \square \]

We are now ready to conclude the proof of Theorem 1.1

Proof of Theorem 1.1. The proof can be finished by standard arguments. The existence of an invariant density \( \rho(t) \) in \( \text{Lip}(S^1, \mathbb{R}^+) \) follows for example by the argument presented in [34, Section 2.3] and the exponential convergence of \( L^\alpha \phi \) to \( \rho(t) \) in the \( C^0 \) norm, hence uniqueness of \( \rho(t) \) can be argued as in [34, Section 2.4]. \( \square \)

From now on let us assume that \( f \in C^5(S^1, S^1) \) and \( h \in C^5(S^1 \times S^1, \mathbb{R}) \), and prove point (i) of Theorem 1.2, i.e. we show that in this case \( \rho(t) \in C^3(S^1, \mathbb{R}^+) \). Recall that \( \| \cdot \|_{C^0} \) denotes the supremum norm on \( C^0(S^1, \mathbb{R}) \), and
\[ C_C := \left\{ \phi \in C^4(S^1, \mathbb{R}^+) : \int \phi = 1, \left\| \frac{d^i\phi}{dx^i} \right\|_{C^0} < C_i \text{ for } i = 1, \ldots, 4 \right\}. \]

Proof of Proposition 1.2. Let \( t \in [-\varepsilon_0, \varepsilon_0] \) and \( \varphi \in C^4(S^1, \mathbb{R}^+) \). We remind the reader that \( F_{t,\varphi} \) is defined as \( F_{t,\varphi} = f \circ \Phi_{t,\varphi} \). By (43)–(45) of the “Appendix” and some elementary bounds, we obtain
\[ |F'_{t,\varphi}| \geq \omega(1 - K_0|t|), \]
\[ |F''_{t,\varphi}| \leq c((1 + K_0|t|)^2 + K_1)|t|, \]
\[ |F'''_{t,\varphi}| \leq c((1 + K_0|t|)^3 + (1 + K_0|t|)K_1|t| + K_2|t|), \]
where \( K_i = \max|h^{(i)}| \) and \( c = \max\{\max |f'''|, 3 \max |f''|, \max |f'|\} \).

We now choose the constants \( C_i, i = 1, \ldots, 4 \), starting with the choice of \( C_1 \). We denote the inverse branches of \( F_{t,\varphi} \) by \( F_{t,\varphi, i}^{-1}, i = 1, \ldots, N \).
\[ \left\| (L_t\phi)' \right\|_{C^0} = \left\| \left( \sum_{i=1}^{N} \frac{\phi}{F_{t,\varphi}^{-1} \circ F_{t,\varphi, i}} \right)' \right\|_{C^0} \leq N \left\| \frac{\phi'}{(F_{t,\varphi})^2} \left( \frac{\varphi F''_{t,\varphi}}{(F_{t,\varphi})^3} \right) \right\|_{C^0} \leq N \left( \frac{1}{\omega^2(1 - K_0t)^2} \|\phi'\|_{C^0} + \max |f'''| \frac{(1 + K_0t)^2 + cK_1t}{\omega^3(1 - K_0t)^3} \|\phi\|_{C^0} \right) \]
by the bounds (21)–(22). Since \( \varphi \) is continuous and has unit integral, we have \( \| \varphi \|_{C^0} \leq 1 + \| \varphi' \|_{C^0} \) giving us

\[
\|(L_t \varphi)'\|_{C^0} \leq N \left( \frac{1}{\omega^2(1 - K_0 t)^2} + \frac{\max |f''|(1 + K t)^2 + c K_1 t}{\omega^3(1 - K_0 t)^3} \right) \| \varphi' \|_{C^0} \\
+ \frac{N(\max |f''|(1 + K_0 t)^2 + c K_1 t)}{\omega^3(1 - K_0 t)^3} \| \varphi' \|_{C^0}
\]

\[
= \sigma_1 \| \varphi' \|_{C^0} + R_1. \tag{24}
\]

By the assumption (8) on \( f \), we can choose \( t \) small enough (by potentially decreasing \( \varepsilon_0 \)) such that \( \sigma_1 < 1 \). Choose \( C_1 \) such that

\[
\frac{R_1}{1 - \sigma_1} \leq C_1,
\]

and then \( \| \varphi' \|_{C^0} \leq C_1 \) implies \( \| (L_t \varphi)' \|_{C^0} \leq C_1 \).

We move on to the choice of \( C_2 \).

\[
\|(L_t \varphi)''\|_{C^0} = \left\| \left( \sum_{i=1}^{N} \frac{\varphi}{F_{t,\varphi} - F_{t,\varphi,i}^{-1}} \right)'' \right\|_{C^0}
\]

\[
\leq N \left\| \frac{\varphi''}{(F_{t,\varphi})^3} - 3 \frac{\varphi' F''_{t,\varphi}}{(F_{t,\varphi})^4} + \frac{\varphi F'''_{t,\varphi}}{(F_{t,\varphi})^4} + 3 \frac{(F''_{t,\varphi})^2}{(F_{t,\varphi})^5} \right\|_{C^0}
\]

\[
\leq N \frac{1}{\omega^3(1 - K_0 t)^3} \| \varphi'' \|_{C^0} + N \left\| 3 \frac{F''_{t,\varphi}}{(F_{t,\varphi})^4} + \frac{F'''_{t,\varphi}}{(F_{t,\varphi})^4} - 3 \frac{(F''_{t,\varphi})^2}{(F_{t,\varphi})^5} \right\|_{C^0} \| \varphi' \|_{C^0}
\]

\[
= : \sigma_2 \| \varphi'' \|_{C^0} + R_2^{(1)} \| \varphi' \|_{C^0} + R_2^{(2)}. \tag{25}
\]

For sufficiently small \( t \) we have \( \sigma_2 < 1 \) by assumption (8) and by (21)–(23) \( R_2^{(1)}, R_2^{(2)} \) are bounded uniformly in \( \varphi \) and in \( t \) if \( t \) is in some fixed neighborhood of zero, so choosing

\[
\frac{R_2^{(1)} C_1 + R_2^{(2)}}{1 - \sigma_2} \leq C_2
\]

will be sufficient.

Similar calculations can be done for the third and fourth derivative. We can conclude that

\[
\|(L_t \varphi)'''\|_{C^0} \leq \sigma_3 \| \varphi''' \|_{C^0} + R_3^{(1)} \| \varphi'' \|_{C^0} + R_3^{(2)} \| \varphi' \|_{C^0} + R_3^{(3)}
\]

\[
\|(L_t \varphi)'^{(4)}\|_{C^0} \leq \sigma_4 \| \varphi'''' \|_{C^0} + R_4^{(1)} \| \varphi''' \|_{C^0} + R_4^{(2)} \| \varphi'' \|_{C^0} + R_4^{(3)} \| \varphi' \|_{C^0} + R_4^{(4)}
\]

where \( \sigma_3, \sigma_4 < 1 \) for sufficiently small \( t \) and \( R_i^{(j)} \) only depend on the derivatives of \( f \) and \( h \) and on \( t \) (such that they are bounded uniformly in \( t \) if \( t \) is in some fixed neighborhood
of zero). Choosing

\[
\frac{R_3^{(1)} C_2 + R_3^{(2)} C_1 + R_3^{(3)}}{1 - \sigma_3} \leq C_3 \\
\frac{R_4^{(1)} C_3 + R_4^{(2)} C_2 + R_4^{(3)} C_1 + R_4^{(4)}}{1 - \sigma_4} \leq C_4
\]

will be sufficient for our purposes. \qed

Lemma 2.3. If \( f \in C^5(S^1, S^1) \) and \( h \in C^5(S^1 \times S^1, \mathbb{R}) \), then for \( 1 \leq k \leq 3 \), \( Q_t : C \to C \) is continuous with respect to the \( C^k \) distance.

Proof. Fix \( k \in \{1, 2, 3\} \). For any \( \varphi, \psi \in C^k(S^1, \mathbb{R}) \), using expression (6) for \( Q_t \) one obtains

\[
Q_t \varphi - Q_t \psi = \frac{\varphi - \psi}{1 + tA'_\varphi} \circ \Phi_{t, \varphi}^{-1}(x) \\
\quad + \left[ \frac{\psi}{1 + tA'_\psi} - \frac{\psi}{1 + tA'_\varphi} \right] \circ \Phi_{t, \varphi}^{-1}(x) \\
\quad + \frac{\psi}{1 + tA'_\psi} \circ \Phi_{t, \psi}^{-1}(x) - \frac{\psi}{1 + tA'_\varphi} \circ \Phi_{t, \varphi}^{-1}(x).
\]

For \( t \) sufficiently, small \( \frac{1}{1 + tA'} \) and \( \Phi_{t, \varphi}^{-1} \) belong to \( C^4 \). Then it follows that

\[
\left\| \frac{\varphi - \psi}{1 + tA'_\varphi} \circ \Phi_{t, \varphi}^{-1}(x) \right\|_{C^k} \leq M \left\| \frac{1}{1 + tA'_\varphi} \circ \Phi_{t, \varphi}^{-1}(x) \right\|_{C^k} \left\| (\varphi - \psi) \circ \Phi_{t, \varphi}^{-1}(x) \right\|_{C^k}
\]

\[
\leq M' \left\| \frac{1}{1 + tA'_\varphi} \right\|_{C^k} \left( \max_{\ell=1,...,k} \left\| \Phi_{t, \varphi}^{-1}(x) \right\|_{C^k} \right)^2 \left\| \varphi - \psi \right\|_{C^k}
\]

\[
\leq \tilde{K} \left\| \varphi - \psi \right\|_{C^k},
\]

where the first two inequalities hold by (42) and (47) of the “Appendix”, respectively. The third inequality can be proved by using (52) of the “Appendix” and some standard bounds on the derivatives of \( \Phi_{t, \varphi} \). To bound the second term, notice that

\[
\frac{1}{1 + tA'_\varphi} - \frac{1}{1 + tA'_\psi} = \frac{A'_\psi - A'_\varphi}{(1 + tA'_\varphi)(1 + tA'_\psi)}
\]

\[
\left\| \left[ \frac{\psi}{1 + tA'_\psi} - \frac{\psi}{1 + tA'_\varphi} \right] \circ \Phi_{t, \varphi}^{-1}(x) \right\|_{C^k}
\]

\[
\leq M \left\| \frac{t}{(1 + tA'_\varphi)(1 + tA'_\psi)} \circ \Phi_{t, \varphi}^{-1}(x) \right\|_{C^k} \left\| (\varphi - \psi) \circ \Phi_{t, \varphi}^{-1}(x) \right\|_{C^k}
\]

\[
\leq M' \left\| \frac{t}{(1 + tA'_\varphi)(1 + tA'_\psi)} \right\|_{C^k} \left( \max_{\ell=1,...,k} \left\| \Phi_{t, \varphi}^{-1}(x) \right\|_{C^k} \right)^2 \left\| \varphi - \psi \right\|_{C^k}
\]

\[
\leq \tilde{K}_C \left\| \varphi - \psi \right\|_{C^k},
\]
where the last inequality also exploits that \( \psi \in \mathcal{C}_C \). Using (38)–(41) of the “Appendix” we can compute that there exists an explicit polynomial function \( p \) such that

\[
\left\| \frac{\psi}{1 + t A_\psi} \circ \Phi_{t,\psi}^{-1}(x) - \frac{\psi}{1 + t A_\psi} \circ \Phi_{t,\psi}^{-1}(x) \right\|_{C^k} \leq p \left( \left\| \frac{\psi}{1 + t A_\psi} \right\|_{C^{k+1}}, \| \Phi_{t,\psi}^{-1} \|_{C^k}, \| \Phi_{t,\psi}^{-1} \|_{C^k} \right) \| \varphi - \psi \|_{C^k}.
\]

Since \( \frac{\psi}{1 + t A_\psi} \in C^4 \), simple calculations as before give us

\[
\left\| \frac{\psi}{1 + t A_\psi} \circ \Phi_{t,\psi}^{-1}(x) - \frac{\psi}{1 + t A_\psi} \circ \Phi_{t,\psi}^{-1}(x) \right\|_{C^k} \leq \tilde{K}_C \| \varphi - \psi \|_{C^k}.
\]

By triangle inequality one can bound \( \| Q_t \varphi - Q_t \psi \|_{C^k} \) and the thesis follows. \( \square \)

We can finally prove that \( \rho(t) \in C^3(S^1, \mathbb{R}) \).

**Proof of Theorem 1.2** Point (i). \( \mathcal{C}_C \subset C^4(S^1, \mathbb{R}) \) is convex and relatively compact in \( C^3(S^1, \mathbb{R}) \). The invariance of the set \( \mathcal{C}_C \) under the action of \( L_t \), as claimed in Proposition 1.2 and the continuity of \( L_t \) restricted to \( \mathcal{C}_C \) as stated in Lemma 2.3 implies by the Schauder fixed point theorem that \( L_t \) has a fixed density in \( C^3(S^1, \mathbb{R}) \). By Theorem 1.1 this density must be the unique Lipschitz density \( \rho(t) \). \( \square \)

3. Smooth Dependence of the Invariant Densities on the Coupling Strength

Given \( t \in [-\varepsilon_1, \varepsilon_1] \), the relation \( t \mapsto \rho(t) \) defines a curve of fixed densities, that is, for each \( t \) the density \( \rho(t) \) is such that \( L_t \rho(t) = \rho(t) \). Recall the definition of \( \hat{\mathcal{C}}_{\varepsilon, K_1, K_2} \)

\[
\hat{\mathcal{C}}_{\varepsilon, K_1, K_2} := \left\{ \gamma : [-\varepsilon, \varepsilon] \rightarrow \mathcal{C}_C \text{ s.t. } \sup_{t} \left\| \frac{d}{dt} \gamma(t) \right\|_{C^2} < K_1, \sup_{t} \left\| \frac{d^2}{dt^2} \gamma(t) \right\|_{C^1} < K_2 \right\}
\]

and the operator \( L \)

\[
(L \gamma)(t) = L_t(\gamma(t)) \text{ for all } t \in [-\varepsilon, \varepsilon]
\]

for \( \gamma \in \hat{\mathcal{C}}_{\varepsilon, K_1, K_2} \). The strategy consists of (i) showing that there are \( \varepsilon_2, K_1, \) and \( K_2 \) such that \( L \) keeps \( \hat{\mathcal{C}}_{\varepsilon_2, K_1, K_2} \) invariant, and (ii) using Proposition 1.1 to show that this implies that \( t \mapsto \rho(t) \) is \( C^1 \).

**Proof of Proposition 1.3.** Let us start by noticing that the implicit function theorem implies that the function \( g : [-\varepsilon_1, \varepsilon_1] \times S^1 \rightarrow S^1 \), defined as \( g(t, \gamma) := (\Phi_{t,\psi})^{-1}(\gamma) \), is differentiable and \( C^5 \). Furthermore, its \( C^5 \) norm can be uniformly bounded with respect to \( \varphi \).\(^5\) Let \( \varepsilon \leq \varepsilon_1 \) and pick \( \gamma \in \hat{\mathcal{C}}_{\varepsilon, K_1, K_2} \).

\[
\frac{d}{dt} (L \gamma)(t) = \left( \frac{d}{ds} L_s \right) \gamma(t) + \lim_{\delta \to 0} \frac{L_t \gamma(t + \delta) - L_t \gamma(t)}{\delta}.
\]

\(^5\) This is a consequence of the fact that the function to which we apply the implicit function theorem, \( F(t, y, x) = \Phi_{t,\psi}(x) - y \), has \( C^5 \) norm uniformly bounded varying \( \varphi \).
For the first term in the right hand side of (26)

\[
\left( \frac{d}{ds} \mathcal{L}_s \right) = \varphi = P \left( \lim_{\delta \to 0} \frac{Q_{t+\delta} - Q_t}{\delta} \right) \\
= P \frac{d}{ds} \left( \frac{\varphi}{\partial_x \Phi_{s,\varphi}} \circ \Phi_{s,\varphi}^{-1} \right) \\
= P \left( \frac{\varphi'}{\partial_x \Phi_{t,\varphi}} \circ \Phi_{t,\varphi}^{-1} \partial_t \Phi_{t,\varphi} - \frac{\varphi}{(\partial_x \Phi_{t,\varphi})^2} \circ \Phi_{t,\varphi}^{-1} \partial_t \left[ \partial_x \Phi_{t,\varphi} \circ \Phi_{t,\varphi}^{-1} \right] \right) \\
= P \left( \frac{\varphi'}{\partial_x \Phi_{t,\varphi}} \circ \Phi_{t,\varphi}^{-1} \partial_t \Phi_{t,\varphi} \\
- \frac{\varphi}{(\partial_x \Phi_{t,\varphi})^2} \circ \Phi_{t,\varphi}^{-1} \partial_t \left[ \partial_x \Phi_{t,\varphi} \circ \Phi_{t,\varphi}^{-1} \right] \right). \quad (27)
\]

Therefore, putting \( \varphi = \gamma(t) \) and recalling that \( \gamma(t) \in C \), for \( t \) sufficiently small all the functions above have bounded norm in \( C^3(S^1, \mathbb{R}) \), and therefore there is a constant \( \tilde{K} \) depending on \( f, h \) and \( C \) such that

\[
\left\| \left( \frac{d}{ds} \mathcal{L}_s \right) \varphi \right\|_{C^3} \leq \tilde{K}. \quad (28)
\]

The second term in the RHS of (26) equals

\[
\Xi(t) := P \lim_{\delta \to 0} \frac{Q_{t,\gamma(t+\delta)} - Q_{t,\gamma(t)}}{\delta} \\
= P \lim_{\delta \to 0} \frac{1}{\delta} \left[ \gamma(t + \delta) \circ \Phi_{t,\gamma(t+\delta)}^{-1} - \frac{\gamma(t)}{1 + t A'_{\gamma(t)}} \circ \Phi_{t,\gamma(t)}^{-1} \right] \\
= P \lim_{\delta \to 0} \frac{\gamma(t + \delta) - \gamma(t)}{\delta (1 + A'_{\gamma(t+\delta)})} \circ \Phi_{t,\gamma(t+\delta)}^{-1} \\
+ P \lim_{\delta \to 0} \frac{1}{\delta} \left[ \gamma(t) \left( \frac{1}{1 + t A'_{\gamma(t+\delta)}} - \frac{1}{1 + t A'_{\gamma(t)}} \right) \right] \circ \Phi_{t,\gamma(t+\delta)}^{-1} \\
+ P \lim_{\delta \to 0} \frac{1}{\delta} \left[ \gamma(t) \circ \Phi_{t,\gamma(t+\delta)}^{-1} - \gamma(t) \circ \Phi_{t,\gamma(t)}^{-1} \right],
\]

giving

\[
\Xi(t) \quad (29)
\]

\[
= P Q_{t,\gamma(t)} \frac{d}{dt} \gamma(t) \\
+ P \left[ \left( \frac{1}{1 + t A'_{\gamma(t)}} \right) \circ \Phi_{t,\gamma(t)}^{-1} \right] \circ \partial_s \left( Q_{t,\gamma(t)} \gamma(t) \right) \frac{d}{ds} \left( \Phi_{t,\gamma(s)}^{-1} \right)_{s=t}. \quad (30)
\]
For the first term of the sum, one can argue in a way similar to the proof of Proposition 1.2 and obtain the inequality

\[ \left\| PQ_{t,y}(t) \frac{d}{dt} y(t) \right\|_{C^3} \leq \sigma \left\| \frac{d}{dt} y(t) \right\|_{C^3} + \tilde{K} \]

(31)

with \( \sigma < 1 \) and \( \tilde{K} > 0 \) (in general different from the \( \tilde{K} \) above). To see this, notice that in the referenced calculations we use uniform bounds for \( F_{t,\varphi} \) in \( \varphi \), only exploiting its unit integral. Furthermore, since \( \int \frac{d}{dt} y(t) = 0 \), the bound \( \| \varphi \|_{C^0} \leq 1 + \| \varphi' \|_{C^0} \) simplifies to \( \| \frac{d}{dt} y(t) \|_{C^0} \leq \| (\frac{d}{dt} y(t))' \|_{C^0} \).

The regularity assumptions allow to deduce that the \( C^3 \) norm of the other terms is uniformly bounded. With computations similar to those in the proof of Proposition 1.2, one can deduce there are \( \sigma < 1 \) (by possibly decreasing \( \varepsilon_1 \)) and \( \tilde{K} > 0 \) such that \( \| \Xi \|_{C^3} \leq \sigma \| \frac{d}{dt} y \|_{C^3} + \tilde{K} \). Putting this estimate together with the one in (28) we get

\[
\left\| \frac{d}{dt} (L y)(t) \right\|_{C^3} \leq \left\| (\frac{d}{ds} L_s)_{s=t} y(t) \right\|_{C^3} + \| \Xi(t) \|_{C^3}
\leq \sigma \left\| \frac{d}{dt} y(t) \right\|_{C^3} + \tilde{K}.
\]

We conclude that there is a \( K_1 \) sufficiently large such that if \( \| \frac{d}{dt} y(t) \|_{C^3} < K_1 \) for all \( t \) values sufficiently small, \( \| \frac{d}{dt} (L y)(t) \|_{C^3} \leq K_1 \).

Now, assuming that \( \| \frac{d}{dt} y \|_{C^3} < K_1 \), we carry out similar computations in order to bound \( \| \frac{d^2}{dt^2} (L y)(t) \|_{C^2} \).

\[
\begin{align*}
\frac{d^2}{dt^2} (L y)(t) &= \frac{d}{dt} \left( \frac{d}{ds} L_s \right)_{s=t} y(t) + \frac{d}{dt} \Xi(t) \\
&= \frac{d}{dt} \left( \frac{d}{ds} L_s \right)_{s=t} y(t) + \frac{d}{dt} \Xi(t)
\end{align*}
\]

The first term corresponds to the derivative with respect to \( t \) of (27) when \( \varphi = y(t) \), which in turn is a combination of the functions

\[
\frac{\partial_x \left( \frac{y(t)}{\partial_x \Phi_{t,y(t)}} \right)}{\partial_x \Phi_{t,y(t)}} \circ \Phi_{t,y(t)}^{-1} \circ \partial_x \Phi_{s,y(t)}^{-1} |_{s=t},
\]

\[
\frac{\partial_x \left( \frac{y(t)}{\partial_x \Phi_{t,y(t)}} \right)}{\partial_x \Phi_{t,y(t)}} \circ \Phi_{t,y(t)}^{-1} \circ \partial_x \partial_x \Phi_{s,y(t)}^{-1} |_{s=t} \circ \Phi_{t,y(t)}^{-1} \circ \partial_x^2 \Phi_{t,y(t)} \circ \Phi_{t,y(t)}^{-1}.
\]

With the given regularity hypotheses all the derivatives with respect to \( t \) of the above terms are continuous in the variable \( x \). In particular, for the first term notice that the assumed regularity of all the terms implies

\[
\frac{d}{dt} \partial_x \left( \frac{y(t)}{\partial_x \Phi_{t,y(t)}} \right) = \partial_x \frac{d}{dt} \left( \frac{y(t)}{\partial_x \Phi_{t,y(t)}} \right).\]

We conclude that there exists a \( \tilde{K} > 0 \) such that \( \| \frac{d}{dt} \left( \frac{d}{ds} L_s \right)_{s=t} y(t) \|_{C^2} < \tilde{K} \).
As for \( \frac{d}{dt} \mathcal{E}(t) \), consider the decomposition of \( \mathcal{E}(t) \) given by (29)–(30). The derivative of \( P Q_{t, \gamma}(t) \frac{d}{dt} \gamma(t) \) is

\[
\frac{d}{ds} \left( P Q_{s, \gamma(s)} \frac{d}{ds} \gamma(s) \right)_{s=t} = P \lim_{\delta \to 0} \frac{(Q_{t+\delta, \gamma(t+\delta)} - Q_{t, \gamma(t)}) \frac{d}{dt} \gamma(t + \delta)}{\delta} + P \lim_{\delta \to 0} \frac{(Q_{t, \gamma(t+\delta)} - Q_{t, \gamma(t)}) \frac{d}{dt} \gamma(t + \delta)}{\delta} + P \lim_{\delta \to 0} \frac{Q_{t, \gamma(t)}(\frac{d}{dt} \gamma(t + \delta) - \frac{d}{dt} \gamma(t))}{\delta}.
\]

The first term in the sum on the RHS can be treated with computations similar to those leading to (27), and equals

\[
P \lim_{\delta \to 0} \frac{(Q_{t+\delta, \gamma(t)} - Q_{t, \gamma(t)}) \frac{d}{dt} \gamma(t)}{\delta} = P \left( \partial_x \left( \frac{d \gamma(t)}{dt} \right) \circ \Phi_{t, \gamma(t)}^{-1} \partial_x \Phi_{s, \gamma(t)} \big|_{s=t} - \frac{d \gamma(t)}{dt} \circ \Phi_{t, \gamma(t)}^{-1} \partial_x \Phi_{s, \gamma(t)} \big|_{s=t} \right)
\]

which can be verified to have uniformly bounded \( C^2 \) norm.

The second term can be expressed as

\[
P \lim_{\delta \to 0} \frac{(Q_{t, \gamma(t+\delta)} - Q_{t, \gamma(t)}) \frac{d}{dt} \gamma(t + \delta)}{\delta} = \frac{d}{ds} \left( \frac{d \gamma(t)}{dt} \circ \Phi_{t, \gamma(s)}^{-1} \right)_{s=t}
\]

and noticing that

\[
\frac{d}{ds} \partial_x \Phi_{t, \gamma(s)} = -\frac{1}{(\partial_x \Phi_{t, \gamma(s)})^2} \frac{d}{ds} \partial_x \Phi_{t, \gamma(s)}, \quad \frac{d}{ds} \left( \frac{d \gamma(t)}{dt} \right), \quad \text{and} \quad \partial_x \Phi_{t, \gamma(s)}^{-1}
\]

have uniformly bounded \( C^2 \) norm, it follows from straightforward computations that the whole of (32) has bounded norm.\(^6\)

For the third term we can find an inequality with a similar argument that leads to (31):

\[
\left\| P Q_{t, \gamma(t)} \frac{d^2}{dt^2} \gamma(t) \right\|_{C^2} \leq \sigma \left\| \frac{d^2}{dt^2} \gamma(t) \right\|_{C^2} + \tilde{K}
\]

For what concerns the derivative of (30), it involves the same terms listed above. Most of the factors appearing have been previously treated apart from

\[
\frac{d}{ds} \left( \frac{1}{1 + t A'_{\gamma(s)}} \right)_{s=t} \quad \text{and} \quad \partial_x \left( Q_{t, \gamma(t)} \gamma(t) \right).
\]

\(^6\) Notice that in the expression above the factor \( \partial_x \left( \frac{d \gamma}{dt} \right) \) appears, and it is for this kinds of factors that the choice of controlling two different norms for \( \frac{d \gamma}{dt} \) and \( \frac{d^2 \gamma}{dt^2} \) becomes crucial.
For the first one is easy to see that all the derivatives in $t$ of $1 + t A'_y(x)$ have bounded $C^2$ norm in $x$. For the second one, it follows from previous computations that $Q_{t,y}(t)y(t)$ is at least $C^1((-\epsilon, \epsilon), S^1)$ and this implies

$$d dt \partial_x Q_{t,y(t)}y(t) = \partial_x d dt Q_{t,y(t)}y(t).$$

$d dt Q_{t,y(t)}y(t)$ can be shown to have uniformly bounded $C^3$ norm in the variable $x$ with the same computations used to control (26), and therefore $\|\partial_x d dt Q_{t,y(t)}y(t)\|_{C^2} \leq \tilde{K}$. Therefore,

$$\left\| \frac{d^2}{dt^2} (L y) (t) \right\|_{C^2} \leq \sigma \left\| \frac{d^2}{dt^2} y(t) \right\|_{C^2} + \tilde{K}$$

so we can find $K_2$ sufficiently large so that $\|\frac{d^2}{dt^2} y(t)\|_{C^2} < K_1$, with $K_1$ as above, and $\|\frac{d^2}{dt^2} y(t)\|_{C^2} < K_2$ implies $\|\frac{d^2}{dt^2} (L y)(t)\|_{C^2} < K_2$.

Proof of Theorem 1.2 Point (ii). Given any $y \in \hat{C}_{\varepsilon_2,K_1,K_2}$, it follows from Proposition 1.3 that $\{L^n y\}_{n \in \mathbb{N}_0} \in \hat{C}_{\varepsilon_2,K_1,K_2}$. Since $\hat{C}_{\varepsilon_2,K_1,K_2} \subset C^2([-\varepsilon_2, \varepsilon_2], C^2(S^1, \mathbb{R}))$ is relatively compact in $C^1([-\varepsilon_2, \varepsilon_2], C^1(S^1, \mathbb{R}))$, there is a strictly increasing sequence $n_k$ and $\overline{y} \in C^1([-\varepsilon_2, \varepsilon_2], C^1(S^1, \mathbb{R}))$ such that $L^{n_k} y \to \overline{y}$ in the $C^1$ topology. In particular, for every $t$, $\|L^n y(t) - \overline{y}(t)\|_{C^0} \to 0$ for $k \to \infty$. However, from Proposition 1.1 we know that for every $t$, $\|L^n y(t) - \rho(t)\|_{C^0} \to 0$ for $n \to \infty$ from which we deduce that $\overline{y}(t) = \rho(t)$, and therefore $t \mapsto \rho(t)$ belongs to $C^1([-\varepsilon_2, \varepsilon_2], C^1(S^1, \mathbb{R}))$. □

4. Linear Response Formula

In this section we derive a linear response formula for the curve $t \mapsto \rho(t)$ of fixed densities. We proceed to prove the proposition in an analogous way to [4, Theorem 2.2] and apply perturbation arguments to deal with the self-consistency.

Lemma 4.1. Considering $\{P_t\}_{t \in [-\varepsilon_2, \varepsilon_2]}$ as bounded operators from $C^2(S^1, \mathbb{R})$ to $C^1(S^1, \mathbb{R})$, we claim that the map $t \mapsto P_t$ is differentiable at $\hat{t} \in (-\varepsilon_2, \varepsilon_2)$ and

$$\partial_t P_t|_{t=\hat{t}}(\varphi) = -P \left( \left( \frac{\varphi}{\Phi_{t,\rho(\hat{t})}^{-1}} (A_{\rho(\hat{t})} + \hat{T} A_{\hat{t},\rho(\hat{t})}|_{t=\hat{t}}) \right) \circ \Phi_{t,\rho(\hat{t})}^{-1} \right)'$$

7 Recall that $C^2(S^1, \mathbb{R})$ is compactly embedded in $C^1(S^1, \mathbb{R})$, and thus given a bounded ball $B' \subset C^2(S^1, \mathbb{R})$ and any $\delta > 0$ there are $F_\delta := \{\varphi_i\}_{i=1}^{N_\delta} \subset C^1(S^1, \mathbb{R})$ such that the union of the $\delta/2$ $C^1$-balls centered at the functions in $F_\delta$ covers $B'$. Fix a bounded ball $B \subset C^2([-\varepsilon_2, \varepsilon_2], C^2(S^1, \mathbb{R}))$, there is $B' \subset C^2(S^1, \mathbb{R})$ such that $\gamma([-\varepsilon_2, \varepsilon_2]) \in B'$ for any $\gamma \in B$. Now fix $\delta > 0$ and pick points $\{t_i\}_{i=1}^M$ partitioning $[-\varepsilon_2, \varepsilon_2]$ such that $\|\gamma(t_1) - \gamma(t_2)\|_{C^0} < \delta/2$ whenever $t_1, t_2 \in [t_i, t_{i+1}]$ for some $i$. Then, for any $(i_1, \ldots, i_M) \in \{1, \ldots, N\}^M$ fix a $C^1$ function $\gamma_{(i_1,\ldots,i_M)} \cdot [-\varepsilon_2, \varepsilon_2] \to C^1(S^1, \mathbb{R})$ such that $\gamma_{(i_1,\ldots,i_M)}(t_j) = \varphi_{i_j}$. It is then easy to check that for every $\gamma \in B$ there is $(i_1, \ldots, i_M) \in \{1, \ldots, N\}^M$ such that $\gamma$ is at $C^1$ distance no more than $\delta$ from $\gamma_{(i_1,\ldots,i_M)}$. 
Proof. Recall that $P_t = P Q_{t, \rho(t)}$ which implies that

$$\partial_t P_t = P \partial_t Q_{t, \rho(t)}.$$  \hfill (33)

Recall also that for $t \in [-\varepsilon_0, \varepsilon_0]$, $\Phi_{t, \rho(t)}$ is a diffeomorphism of $S^1$ and $t \mapsto \Phi_{t, \rho(t)}$ is $C^2$. Let $\varphi \in C^2$.

$$Q_{t, \rho(t)}(\varphi) - Q_{t', \rho(t')}(\varphi)$$

$$= \frac{\varphi}{\Phi_{t, \rho(t)}} \circ \Phi_{t, \rho(t)}^{-1} - \frac{\varphi}{\Phi_{t', \rho(t')}} \circ \Phi_{t', \rho(t')}^{-1}$$

$$= -(t - \hat{t})(\partial_t \Phi_{t, \rho(t)}|_{t=t^*} \circ \Phi_{t^*, \rho(t^*)}^{-1})' \left( \frac{\varphi}{\Phi_{t^*, \rho(t^*)}'} \circ \Phi_{t^*, \rho(t^*)}^{-1} \right)$$

$$- (t - \hat{t}) \partial_t \Phi_{t, \rho(t)}|_{t=t^*} \circ \Phi_{t^*, \rho(t^*)}^{-1} \left( \frac{\varphi'}{\Phi_{t^*, \rho(t^*)}^2} \circ \Phi_{t^*, \rho(t^*)}^{-1} - \frac{\varphi' \cdot \Phi''_{t^*, \rho(t^*)}}{(\Phi_{t^*, \rho(t^*)}'^2)^3} \circ \Phi_{t^*, \rho(t^*)}^{-1} \right).$$

for some $t^* \in (t, \hat{t})$. Notice that

$$(\partial_t \Phi_{t, \rho(t)}|_{t=t^*} \circ \Phi_{t^*, \rho(t^*)}^{-1})' \left( \frac{\varphi}{\Phi_{t^*, \rho(t^*)}'} \circ \Phi_{t^*, \rho(t^*)}^{-1} \right)$$

$$= \left( \frac{\varphi}{(\Phi_{t^*, \rho(t^*)}')^2} \circ \Phi_{t^*, \rho(t^*)}^{-1} \right) \partial_t \Phi_{t, \rho(t)}|_{t=t^*} \circ \Phi_{t^*, \rho(t^*)}^{-1}$$

implying that

$$\partial_t Q_{t, \rho(t)}|_{t=\hat{t}}(\varphi) = - \left( \frac{\varphi}{(\Phi_{t, \rho(t)}')^2} \partial_t \Phi_{t, \rho(t)}|_{t=t} \circ \Phi_{t, \rho(t)}^{-1} \right) \circ \Phi_{t, \rho(t)}^{-1}$$

$$- \left( \left( \frac{\varphi'}{(\Phi_{t, \rho(t)}')^2} - \frac{\varphi' \cdot \Phi''_{t, \rho(t)}}{(\Phi_{t, \rho(t)}')^3} \right) \partial_t \Phi_{t, \rho(t)}|_{t=t} \right) \circ \Phi_{t, \rho(t)}^{-1}$$

and by (33)

$$\partial_t P_t|_{t=\hat{t}}(\varphi) = - P \left( \left( \frac{\varphi}{\Phi_{t, \rho(t)'}'} \partial_t \Phi_{t, \rho(t)}|_{t=t} \circ \Phi_{t, \rho(t)}^{-1} \right) \right)'$$

$$= - P \left( \left( \frac{\varphi}{\Phi_{t, \rho(t)'}'} \left( A_{\rho(t)} + \hat{t} A_{\partial_t \rho(t)}|_{t=\hat{t}} \right) \right) \circ \Phi_{t, \rho(t)}^{-1} \right)'$$

$$\square$$

Notice that this lemma implies that

$$\partial_t P_t|_{t=\hat{t}}\rho(\hat{t}) = - P[K_{t}(\rho(\hat{t})) + \hat{t} \mathcal{K}_{t}(\partial_t \rho|_{t=\hat{t}})],$$

where $K_{t}$ is given by (10).
Proof of Proposition 1.4. Recall that $P_t$ is the transfer operator of $f \circ \Phi_{t, \rho(t)}$ which is an at least $C^3$ transformation of $S^1$. Furthermore, there is $K > 0$ such that $|\Phi'_{t, \rho(t)}| > 1 - Kt$ and thus $f \circ \Phi_{t, \rho(t)}$ is uniformly expanding for any $t$ with $|t| < \varepsilon$ for some sufficiently small $\varepsilon$. Standard results on uniformly expanding maps (see [11]) imply that $P_t$ has a spectral gap in $C^2(S^1, \mathbb{R})$. In particular, 1 is an isolated and simple eigenvalue and $\mathbb{R}\rho(t)$ is the corresponding eigenspace. Because of the uniform Lasota-Yorke type inequalities (24)–(25), a uniform bound can be given on the spectral gap of all $P_t$ such that $t$ is small enough. This implies that we can find a positively oriented curve $\gamma$ on the complex plane around 1 such that no other element of the spectrum of any $P_t$ is contained inside of it, and the projection formula
\[
\rho(t) = \frac{1}{2\pi i} \int_{\gamma} (z - P_t)^{-1} \varphi(z) dz
\]
holds for any $\varphi \in C^2$ such that $\int_{S^1} \varphi = 1$. One can prove this using the decomposition of $\mathcal{L}_{t, \rho(t)}$ as stated in [11, Theorem 7.1.1] (exploiting the fact that $F_{t, \rho(t)}$ is $C^2$ and uniformly expanding which properties by [22] imply that $F_{t, \rho(t)}$ mixing) and a residue computation.

For $z \in \gamma$ we have
\[
(z - P_t)^{-1} - (z - P_t^{-1}) = (z - P_t)^{-1}(P_t - t)(z - P_t)^{-1}
\]
where we view $(z - P_t)^{-1}$ as an operator acting on $C^2(S^1, \mathbb{R})$, $(P_t - P_t)$ as an operator from $C^2(S^1, \mathbb{R})$ to $C^1(S^1, \mathbb{R})$ and $(z - P_t)^{-1}$ as acting on $C^1(S^1, \mathbb{R})$.

Letting $t \to \hat{t}$ in (35) by Lemma 4.1 we have that
\[
\partial_{\hat{t}} (z - P_t)^{-1}|_{t=\hat{t}} = (z - P_t)^{-1} \partial_{\hat{t}} P_t|_{t=\hat{t}} (z - P_t)^{-1}.
\]
Substituting $\varphi = \rho(\hat{t})$ in (34) and differentiating both sides we get
\[
\partial_{\hat{t}} \rho(t)|_{t=\hat{t}} = \frac{1}{2\pi i} \int_{\gamma} (z - P_t)^{-1} \partial_{\hat{t}} P_t|_{t=0} (z - P_t)^{-1} \rho(\hat{t})(z) dz
\]
\[
= \frac{1}{2\pi i} \int_{\gamma} (z - P_t)^{-1} \partial_{\hat{t}} P_t|_{t=\hat{t}} \rho(\hat{t})(z) \frac{1}{z - 1} dz
\]
\[
= -\frac{1}{2\pi i} \int_{\gamma} (z - P_t)^{-1} P(K_t(\rho(\hat{t}))) + iK_t(\partial_{\hat{t}} \rho(t)|_{t=\hat{t}})(z)\frac{1}{z - 1} dz
\]
\[
= -(1 - P_t)^{-1} P(K_t(\rho(\hat{t}))) + iK_t(\partial_{\hat{t}} \rho(t)|_{t=\hat{t}}),
\]
where the last step is a residue computation.

Thus we can write
\[
(1 - P_t + iPK_t)\partial_{\hat{t}} \rho(t)|_{t=\hat{t}} = -PK_t(\rho(\hat{t})).
\]
It is a well-known fact that invertible operators form an open set in the space of bounded linear operators between normed spaces. More precisely, if an operator $T$ is invertible, then any operator $S$ such that $\|T - S\| \leq \|T^{-1}\|^{-1}$ is also invertible. Since $1 - P_t$ is invertible as an operator from $C^2(S^1, \mathbb{R})$ to $C^1(S^1, \mathbb{R})$, the invertibility of $1 - P_t + iPK_t$ follows if we are able to choose $\hat{t}$ so small that
\[
\|iPK_t\|_{C^2 \to C^1} \leq \|(1 - P_t)^{-1}\|_{C^2 \to C^1}^{-1} \|PK_t\|_{C^2 \to C^1} (1 - P_t)^{-1} \|_{C^2 \to C^1} \Leftrightarrow \hat{t} \leq \frac{1}{\|PK_t\|_{C^2 \to C^1} \|(1 - P_t)^{-1}\|_{C^2 \to C^1}^{-1}}.
\]
For this it suffices to show that $t \mapsto \| P K_t \|_{C^2 \to C^1} \|(1 - P_t)^{-1}\|_{C^2 \to C^1}$ is uniformly bounded in a small interval around zero. The norm $\|(1 - P_t)^{-1}\|_{C^2 \to C^1}$ is finite for all sufficiently small $t$ (because of the above mentioned spectral gap), so it can be uniformly bounded in an interval $[-\varepsilon_2, \varepsilon_2]$. As for $K_t$, we can compute that

$$
\sup_{x \in S^1} |K_t \varphi(x)| = \sup_{x \in S^1} \left| \left( \frac{\rho(t)}{\Phi_{t, \rho(t)}} A \varphi \right) \circ \Phi_{t, \rho(t)}^{-1} (x) \right|
= \sup_{x \in S^1} \left| \frac{\rho'(t) A \Phi_{t, \rho(t)}' + \rho(t) A \Phi_{t, \rho(t)}'}{\Phi_{t, \rho(t)}^2} - \rho(t) A \Phi_{t, \rho(t)}'' \right| \circ \Phi_{t, \rho(t)}^{-1} (x) \cdot \left( \Phi_{t, \rho(t)}^{-1}(x) \right)'
\leq \frac{1}{(1 - t K)^3} \left( K (1 + t K) \sup_{x \in S^1} |\rho'(t)| + (K (1 + t K) + t K^2) \sup_{x \in S^1} |\rho(t)| \right)
$$

and a similar formula for $\sup_{x \in S^1} |(K_t \varphi)'(x)|$ depending smoothly on $\rho, \rho', \rho''$ and $t$. Since $(t, x) \mapsto \rho(t)(x)$ is $C^2$, $\|K_t\|_{C^2 \to C^1}$ is uniformly bounded for $t \in [-\varepsilon_2, \varepsilon_2]$.

Thus we can choose $\varepsilon_3$ further decreasing $\varepsilon_2$ such that $1 - P_t + \hat{t} PK_t$ is invertible for $t \in [-\varepsilon_3, \varepsilon_3]$ and

$$
\partial_t \rho(t)|_{t=i} = -(1 - P_t + \hat{t} PK_t)^{-1} PK_t(\rho(i)). \quad \Box
$$

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A. Appendix

In this appendix we recall some simple formulae on derivatives that have been used extensively throughout the document. First of all higher derivatives of a product: Assume $\Phi, \Psi \in C^4$, then

\[
(\Phi \Psi)' = \Phi' \Psi + \Phi \Psi' \\
(\Phi \Psi)'' = \Phi'' \Psi + 2\Phi' \Psi' + \Phi \Psi'' \\
(\Phi \Psi)''' = \Phi''' \Psi + 3\Phi'' \Psi' + 3\Phi' \Psi'' + \Psi \Phi''' \\
(\Phi \Psi)'''' = \Phi'''' \Psi + 4\Phi''' \Psi' + 6\Phi'' \Psi'' + 4\Phi' \Psi''' + \Psi \Phi'''
\]

which implies that there is a constant $M > 0$ such that

$$
\|\Phi \Psi\|_{C^k} \leq M \|\Phi\|_{C^k} \|\Psi\|_{C^k}, \quad k = 1, \ldots, 4.
$$
Higher derivatives of a composition: Assume \( \Phi, \Psi \in C^4 \), then

\[
(\Phi \circ \Psi)' = \Phi' \circ \Psi' \quad (43)
\]

\[
(\Phi \circ \Psi)'' = \Phi'' \circ (\Psi')^2 + \Phi' \circ \Psi'' \quad (44)
\]

\[
(\Phi \circ \Psi)''' = \Phi''' \circ (\Psi')^3 + 2\Phi'' \circ \Psi\Psi'\Psi'' + \Phi'' \circ \Psi\Psi''\Psi' + \Phi' \circ \Psi''' 
\]

\[
(\Phi \circ \Psi)'''' = \Phi'''' \circ (\Psi')^4 + \Phi''' \circ \Psi \left[ 3(\Psi')^2\Psi'' + \Psi''(\Psi')^2 + 2(\Psi')^2\Psi'' \right] 
\]

\[
+ \Phi'' \circ \Psi \left[ 3(\Psi')^2 + 4\Psi'\Psi'' \right] + \Phi' \circ \Psi(\Psi''') 
\]

which implies that there is a numerical constant \( M \) such that

\[
\| \Phi \circ \Psi \|_{C^k} \leq M \| \Phi \|_{C^k} \cdot \max_{\ell=1,\ldots,k} \| \Psi \|_{C^\ell}, \quad k = 1, \ldots, 4. \quad (47)
\]

We also give the formulae for the higher derivatives of the inverse function. Let \( \Phi \in C^4 \) be invertible and such that \( \min |\Phi'| > 0 \), then

\[
(\Phi^{-1})' = \frac{1}{\Phi'} \circ \Phi^{-1} \quad (48)
\]

\[
(\Phi^{-1})'' = -\frac{\Phi''}{(\Phi')^2} \circ \Phi^{-1}(\Phi^{-1})' = -\frac{\Phi''}{(\Phi')^3} \circ \Phi^{-1} \quad (49)
\]

\[
(\Phi^{-1})''' = \left[ 2 \left( \frac{(\Phi'')^2}{(\Phi')^3} - \frac{\Phi'''}{(\Phi')^2} \right) \circ \Phi^{-1}(\Phi^{-1})' - \frac{\Phi''}{(\Phi')^2} \circ \Phi^{-1}(\Phi^{-1})'' \right] 
\]

\[
= \left[ 2 \left( \frac{(\Phi'')^2}{(\Phi')^4} - \frac{\Phi'''}{(\Phi')^3} - \frac{(\Phi''')^2}{(\Phi')^5} \right) \circ \Phi^{-1} \right] \quad (50)
\]

\[
(\Phi^{-1})'''' = \left[ 4 \left( \frac{\Phi''''}{(\Phi')^5} - 8 \frac{\Phi'''^3}{(\Phi')^6} - \frac{\Phi''''}{(\Phi')^4} + 3 \frac{\Phi'''^2}{(\Phi')^5} - 2 \frac{\Phi''''}{(\Phi')^6} + 5 \frac{(\Phi''')^3}{(\Phi')^7} \right) \circ \Phi^{-1} \right] \quad (51)
\]

and so there exists an \( M > 0 \) such that

\[
\| \Phi^{-1} \|_{C^k} \leq M \cdot \max_{n=1,\ldots,7} (\min |\Phi'|)^{-n} \cdot \max_{\ell=1,\ldots,3} \| \Phi \|_{C^\ell}, \quad k = 1, \ldots, 4. \quad (52)
\]

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