Performance Analysis of FFH/MFSK Using Division Combining Receiver in GPS System

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Abstract: In this paper, a new kind of nonlinear combining receiver of fast frequency hopping/multiple frequency shift keying (FFH/MFSK) modulation in GPS system is proposed. The performance of the receiver is analyzed in the effects of partial band noise jamming over additive white Gaussian noise channel and Ricean fading channel. The diversity of the system is performed using multiple hops per data bit. The non-central F distribution is found in the random variable of the division combining algorithm under the partial-band noise jamming in the additive white Gaussian noise channel. The mathematical results of the bit error ratio of the division combining system are achieved in both fading and non-fading channels. The numerical results are achieved by the simulation environment of the signal transmission while the signal to noise ratio was relatively small and the partial band noise jamming factor is relatively large. It was shown that the GPS system using division combining receiver has better performance under the strong partial band interference than the system without diversity and self-normalized combining receiver. This performance gain is because that the interference signal is scattered into several hops and partly diminished by the operation of division algorithm. As its simple structure to be implemented and anti-interference property, the proposed combining algorithm is useful for GPS signal transmission in the strong partial band noise jamming environment.

Keywords: FFH, MFSK, Division Combining, Fading Channel

1. Introduction

In this paper the transmission characteristic of the proposed FFH/MFSK receiver in the GPS system named division combining receiver \cite{1, 2} is analyzed. According to the signal transition environment of GPS channel, the performance is analyzed with multiple hops per data bit under the fading channel \cite{3, 4} with partial band noise jamming (PBNJ) and AWGN. The error probability density function (pdf) is derived by the diversity level from one (no diversity) to three. It was shown that when the signal to jamming ratio is relatively low, the proposed MFSK system performances better than the system without diversity and self-normalized combining receiver \cite{5, 6} while the diversity level increases. This performance gain is because of the interference signal which is scattered into several hops and partly diminished by the division operations of the system. The combining algorithm is interpreted in the section two and the system performance is analyzed in the following sections. Then the numerical results are shown for comparing the proposed algorithm with the self-normalized combining algorithm which is commonly used in the FFH GPS systems.

2. System Model

The structure of the proposed receiver in GPS system is shown in Figure 1. The signal in the GPS antenna is fed to the BPF filter and then disposed by the FFH/MFSK receiver. After that, the signal is combined with division algorithm to shape the decision signal \( z \) and finish the demodulation of the GPS system.
The GPS signal is assumed to transmit in L hop/bit FHH/MFSK mode with total bandwidth W, and the baseband frequency \( f_1, f_2, \) and \( f_3 \) \((f_1, f_2, f_3)\) which leads to \( M=3 \), are transmitted at the rate of \( R=1/T_b, \) \(|f_1-f_2|=B\) which is the cell bandwidth \([7, 8]\) equal to hopping rate \( R_b \). The received signal was passed through the ratio frequency band pass filter and then down converted with the frequency synthesizer (FS) controlled by the PN generator \([9, 10]\) coincident with the transmitting end. The dehopped signal \( r(t) \) is fed into three channels as shown. The mark and space channels employ square-law envelope detectors whose outputs are sampled every hopping period to produce the quantities \( x_{1k}, x_{2k}, \) and \( x_{3k} \). After that, the signal is brought into the divider whose outputs are \( z_{1k}, z_{2k}, \) and \( z_{3k} \) where \( z_{1k}=x_{1k}/x_{2k}, \) \( z_{2k}=x_{2k}/x_{1k}, \) and \( z_{3k}=x_{3k}/x_{1k}. \) Because of the presence of the system's thermal noise, the \( x_{1k}, x_{2k}, \) and \( x_{3k} \) will always have positive values (which can not be zeros), so that \( z_{1k}, z_{2k}, \) and \( z_{3k} \) have finite values. Further more, when the power of additive noise is relatively low, the output power is relatively strong, so it looks like that the \( E_b/N_0 \) is enlarged by the algorithm. Then \( z_{1k}, z_{2k}, \) and \( z_{3k} \) are summed to form the decision statistics \( z_1, z_2, \) and \( z_3. \) At last, \( z_1, z_2, \) and \( z_3 \) are compared to make a bit decision. It was assumed that the two adjacent frequency cells of the modulation band are jammed simultaneously with probability \( \gamma \) or unjammed simultaneously with probability \( 1-\gamma \) as in \([11]\). As a result, when a hop contains very strong interference, the value of \( z_{1k}, z_{2k}, \) and \( z_{3k} \) will be approximately close to the value “1”.

The performance of this kind of receiver under the partial-band-noise jamming in the AWGN channel is analyzed. The average spectral power density of the PBNJ is \( N_0 \) \((N_0=W), \) where \( J \) is the total jamming power. The average spectral power of AWGN is \( N_b. \) Therefore when a hop is jammed, the power of interference is \((\gamma N_0), \) \((1-\gamma)N_b. \) While it is \( N_b \) when there is no jamming. It is assumed that the total useful signal power is constant which is equally distributed to \( L \) hops where \( L \) is the diversity level.

Since when the average power of the signal and the interference are relatively of great disparity, the abscissa axis of the bit error ratio (BER) curve is chosen from -10dB to 10dB to avoid the chance of specific value \( z_{1k}, z_{2k}, \) and \( z_{3k} \) to be a very large number or a quite small number. The performance in the AWGN and the fading channel is discussed below.

### 3. Performance Analysis

A. Performance under the PBNJ in the AWGN channel

Without loss in generality, it was assumed that \( f_1 \) was transmitted in the subsequent analysis. The random variables \( x_{1k}, x_{2k}, \) and \( x_{3k} \) can be represented as follows. \([12]\)

\[
x_{1k} = \sigma_x^2 \left[ \left( \frac{2S}{\sigma^2} \cos \theta_k + v_{1k} \right)^2 + \left( \frac{2S}{\sigma^2} \sin \theta_k + v_{2k} \right)^2 \right]
\]

\[
x_{2k} = \sigma_x^2 \left[ v_{3k}^2 + v_{4k}^2 \right]
\]

\[
x_{3k} = \sigma_x^2 \left[ v_{5k}^2 + v_{6k}^2 \right]
\]

Where

\[
\sigma_x^2 = \begin{cases} N_b B, & \text{with probability } 1-\gamma \\ (N_0 + N_b / \gamma) B, & \text{with probability } \gamma \end{cases}
\]

\( S \) is the signal power and \( \theta_k \) is the uniform phase random variables. \( v_{ik} \), \( i=1,2,3,4,5,6 \) are independent Gaussian random variables with zero means and unit variance.

Thus, \( z_{1k} \) can be expressed as

\[
z_{1k} = \frac{\left( \frac{2S}{\sigma^2} \cos \theta_k + v_{1k} \right)^2 + \left( \frac{2S}{\sigma^2} \sin \theta_k + v_{2k} \right)^2}{v_{3k}^2 + v_{4k}^2}
\]

As noticed in paper \([1]\), \( z_{1k} \) is a non-central F distributed random variable with two degrees of freedom with non-central parameter \( 2S(\sigma_x^2) \). According to the structure of the algorithm, the value of \( z_{1k} \) has no relationship with the value of \( x_{3k} \), so \( z_{1k} \) will not be contaminated while the \( x_{3k} \) is interfered by the noise signal. Such the probability density function of \( z_{1k} \) can be obtained \([13]\) as below.

\[
f_{z_{1k}}(z_{1k}) = e^{-\frac{z_{1k}}{2}} \sum_{n=0}^{\infty} \frac{\lambda^n (z_{1k}+1)^{n+1}}{2^n n!} U(z_{1k})
\]
Where \( \lambda = 2S/\sigma^2 \) is the non-central parameter of \( z_{ik} \). \( U(\cdot) \) is the unit step function. And the probability density function of \( z_{ik} \) and \( z_{ik} \) can be calculated as below:

\[
f_{z_{ik}}(z_{ik}) = \frac{2^\lambda}{\Gamma((\lambda+1)/2)} \frac{\lambda^{(\lambda+1)/2}}{2^\lambda}\frac{\sigma^2}{\sigma^2_k} \exp\left(-\frac{x_{ik}^2 + 2S}{\sigma_k^2} - \frac{x_{ik}}{\sigma_k^2}\right) \mathcal{I}_0\left(\frac{\sqrt{2S} x_{ik}}{\sigma_k^2}\right)
\]

(11)

The probability density function of \( z_{1k}, z_{2k} \) and \( z_{3k} \) can be calculated as below:

\[
f_{z_{1k}}(z_{1k}) = \int_0^\infty f_{z_{1k}}(z_{1k} - x_{2k}) f_{x_{2k}}(\frac{1}{x_{2k}}) \frac{1}{x_{2k}^2} dx_{2k}
\]

(14)

\[
f_{z_{2k}}(z_{2k}) = \int_0^\infty f_{z_{2k}}(z_{2k} - x_{1k}) f_{x_{1k}}(\frac{1}{x_{1k}}) \frac{1}{x_{1k}^2} dx_{1k}
\]

(15)

After this the close-form of the probability density functions of \( z_{1k} \) and \( z_{2k} \) are:

\[
f_{z_{1k}}(z_{1k}) = \frac{\alpha^2 \sigma_{z_{1k}}^2}{\sigma_{z_{1k}}^2 + \alpha^2} \exp\left(-\frac{z_{1k}^2}{\sigma_{z_{1k}}^2 + \alpha^2}\right)
\]

(16)

\[
f_{z_{2k}}(z_{2k}) = \frac{\alpha^2 \sigma_{z_{2k}}^2}{\sigma_{z_{2k}}^2 + \alpha^2} \exp\left(-\frac{z_{2k}^2}{\sigma_{z_{2k}}^2 + \alpha^2}\right)
\]

(17)

The probability of bit error in the fading channel can be get through equation (9) and (10).

### 4. Numerical Results

The following figure 2 and figure 3 show the bit errors of the FFH/MFSK system in the AWGN channel with the PBNJ interference. Figure 2 shows the performance of the GPS system with \( E_b/N_0 = 13.35 \) dB. One can see that in the presence of strong PBNJ (\( E_b/N_0 \) from -10 to 3 dB), the diversity receiver performances better than the receiver without the diversity when the jamming factor \( \gamma \) is 0.5 and 0.1. The performance becomes much better when \( \gamma \) decreases.

![Figure 2. BER under PBNJ in the AWGN channel with different gama.](image)
Figure 3 shows the comparison between division combining and self-normalized combining receiver in the AWGN channel with the jamming factor $\gamma=0.1$ at different PBNJ ratio. The results show the proposed receiver has better performance at the same diversity level with the increasing of $E_b/N_0$. When the diversity level increase, both two kinds of receiver have better BER performance.

Figure 4 and figure 5 show the system performance under the PBNJ in frequency non-selective slowly Ricean fading channel with different partial band noise jamming factor $\gamma$ while the $E_b/N_0$ ratio is 0 dB.

It can be observed that in the Ricean fading channel, the bit error performance becomes insensitive to the $E_b/N_0$ ratio when the jamming factor $\gamma$ gets larger. However, in the presence of strong PBNJ, the division combining receiver has better performance than the receiver without the diversity and the self-normalized combining receiver. While the jamming factor $\gamma$ is relatively small as in figure 5, the diversity system gets better algorithms gain with the increasing of $E_b/N_0$ ratio.

5. Conclusion

In this paper the performance of division combining receiver of FFH/MFSK in GPS system is analyzed in the presence of strong interference ($E_b/N_0<10$ dB) while the hop $L=3$. The results show that the diversity receiver has better performance than the system without diversity and self-normalized combining receiver [15] in the AWGN channel and Ricean fading channel under partial-band-noise jamming. It was shown the proposed combining algorithm performances better than the self-normalized combining method at the lower $E_b/N_0$ ratio (<10 dB) with the same $E_b/N_0$ ratio while the $L$ increases. The division combining receiver has simpler structure than the self-normalized combining receiver and has easy way to be implemented. It will be useful for GPS signal transmission in the strong partial-band-noise jamming environment. However, when the dividing hops increase the computation complexity of the algorithm will also increase a lot. Meanwhile all of the random variety $z_1, z_2, \ldots, z_L$ will depends on the quantity of $x_{ik}$ which may be randomly interfered by the partial band jamming. So without loss of generality, the random i of the $x_{ik}$ can be chosen for dispatching the interference to every hop of the random variety in the further research works.

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