Soliton solutions of a Calogero model in a harmonic potential

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Abstract

A classical Calogero model in an external harmonic potential is known to be integrable for any number of particles. We consider here reductions which play a role of the ‘soliton’ solutions of the model. We obtain these solutions both for the model with finite number of particles and in a hydrodynamic limit. In the latter limit, the model is described by hydrodynamic equations on continuous density and velocity fields. Soliton solutions in this case are finite-dimensional reductions of the hydrodynamic model and describe the propagation of lumps of density and velocity in the nontrivial background.

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1. Introduction

The harmonic Calogero model (hCM) \cite{1, 2} describes one-dimensional particles moving in the presence of an external harmonic potential and interacting through an inverse-square potential. The Hamiltonian of the model reads

\begin{equation}
H_{hCM} = \frac{1}{2} \sum_{j=1}^{N} \left( p_j^2 + \omega^2 x_j^2 \right) + \frac{1}{2} \sum_{j,k=1; j \neq k}^{N} \frac{g^2}{(x_j - x_k)^2},
\end{equation}

\begin{equation}
= \frac{1}{2} \sum_{j=1}^{N} \left| p_j - i \omega x_j + ig \sum_{k=1; k \neq j}^{N} \frac{1}{x_j - x_k} \right|^2 + \frac{\omega g}{4} N(N-1),
\end{equation}

where $x_j$ are coordinates of $N$ particles, $p_j$ are their canonic momenta and $g$ is the coupling constant. We took the mass of the particles to be unity.
The model (classical and quantum) occupies an exceptional place in physics and mathematics and has been studied extensively [3–5]. The hCM similar to other Calogero–Moser systems can be obtained by the Hamiltonian reduction of the system of non-interacting Hermitian matrices moving in an external harmonic potential [3]. In this reduction, the $N$ coordinates of the particles $x_j$ appear as the eigenvalues of a simply evolving $N \times N$ matrix.

The model is completely integrable and its solutions can be presented in terms of the eigenvalue problem for a finite-dimensional matrix (see section 2 for details).

A remarkable fact is that the hydrodynamic limit $N \to \infty$ of the system (1) can be found exactly using the methods of collective field theory [6–8] or using the methods of [9, 10]. The hydrodynamic Hamiltonian can be written in terms of density and velocity fields as

$$ H = \int \! dx \rho \left[ \frac{v^2}{2} + \frac{g^2}{2}(\pi \rho_{H}^H - \partial_x \ln \sqrt{\rho})^2 + \frac{\omega^2 x^2}{2} \right] $$

(3)

$$ = \int \! dx \rho \left[ \frac{v^2}{2} |v - i\omega x + i g(\pi \rho_{H}^H - \partial_x \ln \sqrt{\rho})|^2 + \text{const}, \right] $$

(4)

where $\rho_{H}^H$ is Hilbert transform of $\rho$ defined as a principal value integral

$$ \rho_{H}^H = \frac{1}{\pi} \int_{-\infty}^{+\infty} \frac{\rho(y)}{y - x} dy. $$

(5)

The density and velocity fields have a Poisson’s bracket

$$ \{\rho(x), v(y)\} = 5'(x - y). $$

(6)

In this work, we stress that the hydrodynamic form (3), (6) can be used even for the finite number of particles $\int \rho(x) \, dx = N$ (see section 6).

A goal of this paper is to find the ‘soliton solutions’ of the system (3), (6). The corresponding soliton solutions of the Calogero model (CM) without an external potential ($\omega = 0$) are well known. A single-soliton solution was found in [11, 12], and generalized to multi-soliton solutions in [10].

Let us first explain what we mean by a soliton solution. Soliton is usually defined as ‘a pulse that maintains its shape while it travels at constant speed’. Obviously, this definition does not make any sense in the presence of an external harmonic potential. Instead, we should talk about the finite-dimensional reductions of an infinitely dimensional system (3), (6). Namely, if there is a solution of that system of the form $\rho(x,t) = \rho(x; \{z_j\})$ (and $v(x,t) = v(x; \{z_j\})$) so that the time dependence of $\rho$ and $v$ is reduced to $M$ complex parameters $z_j(t)$ ($j = 1, 2, \ldots, M$) with known time dependence, we call it an $M$-soliton solution. For example, in translationally invariant systems, a one-soliton solution has a form $\rho(x,t) = \rho(x - z(t))$ which is consistent with the standard soliton definition.

The main result of the paper is the $M$-soliton solutions of (3), (6). It is presented in section 7.3. The complex parameters $z_j(t)$ of this multi-soliton solution in turn satisfy a ‘dual’ CM (25). Therefore, the complicated dynamics of an infinite-dimensional hCM (3) is reduced to an $M$-dimensional dynamics of the complex Calogero system. We have to stress here that finding an explicit solution is still a non-trivial problem as one also has to relate initial conditions $z_j(t = 0)$ of a dual Calogero system (25) to initial density and velocity profiles of (3). This is done implicitly in (72) and (73). The derivations used in obtaining (72) and (73) are very close to the ones used in [10].

Remarkably, the finite-dimensional reduction can also be performed in the finite-dimensional hCM (1) with $N$ particles. The evolution of (1) with finely tuned initial conditions can be described as a motion of few complex parameters $z_j(t)$ ($j = 1, 2, \ldots, M$) with $M < N$. 

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This result is not published anywhere to the best of our knowledge and is another important result of this paper.

The organization of the paper is as follows. To introduce some notations and for the reader’s convenience, we start with a brief review of a solution of hCM (1) in section 2. We formulate a self-dual dynamical system which can be reduced to the hCM in section 3. A similar self-dual system has appeared before in [10] for the trigonometric CM. We extend it to the hCM. We show that this self-dual system allows for the reductions which correspond to the soliton solutions of the hCM. Several examples of such reductions are given in section 4. In section 5, we encode the positions of hCM particles and their momenta by poles of meromorphic functions and derive equations for those functions using the approach of [9, 10]. We use these equations to rewrite the dynamics of the hCM in a hydrodynamic form in section 6 and present soliton solutions in the hydrodynamic limit in section 7. In concluding section 8, we discuss the possible generalizations of this work and some open questions. Some details of calculations are delegated to the appendices.

2. Solution of the hCM with N particles

Here we briefly review the explicit solution of the hCM (see [3] for review). In this solution, the coordinates of the Calogero particles \( x_j(t) \) can be found at any time as the eigenvalues of a simple matrix \( Q(t) \). For the sake of brevity, we do not discuss here neither a geometric meaning of the solution nor how this solution could be obtained (see [3]). Instead, we just introduce notations and give explicit formulas that we use in this work.

Let us introduce the following \( N \times N \) matrices:

\[
X_{ij} = \delta_{ij} x_i, \quad (7)
\]

\[
L^\pm = L \pm i \omega X, \quad \text{where} \quad L_{ij} = p_i \delta_{ij} + (1 - \delta_{ij}) \frac{ig}{x_i - x_j}, \quad (8)
\]

\[
M_{ij} = g \left[ \delta_{ij} \sum_{l=1(l\neq i)}^{N} \frac{1}{(x_l - x_i)^2} - (1 - \delta_{ij}) \frac{1}{(x_i - x_j)^2} \right]. \quad (9)
\]

These matrices depend on time through \( x_j(t) \) and \( p_j(t) \) and satisfy important identities:

\[
[X, L] = ig(e \otimes e^T - 1), \quad (10)
\]

\[
Me = 0 \quad \text{and} \quad e^T M = 0. \quad (11)
\]

Here \( e^T = (1, 1, \ldots, 1) \).

It is straightforward to show that the equations of motion of hCM (1)

\[
\dot{x}_j = p_j, \quad (12)
\]

\[
\dot{p}_j = -\omega^2 x_j - g^2 \frac{\partial}{\partial x_j} \sum_{k=1(k\neq j)}^{N} \frac{1}{(x_j - x_k)^2} \quad (13)
\]

are equivalent to the following matrix equations:

\[
\dot{X} + i[M, X] = L, \quad (14)
\]

\[
\dot{L} + i[M, L] = -\omega^2 X \quad (15)
\]
or equivalently
\[ \dot{L}_\pm = -i[M, L_\pm] \pm i\omega L_\pm \] (16)
written in terms of the \( L \) and \( M \) matrices usually referred to as a Lax pair. It immediately follows from (16) (see also equation (B.1)) that the quantities
\[ I_k = \text{Tr}(L^L L^+)^k = \text{Tr}(L^+ L^-)^k \] (17)
are the integrals of motion of the hCM. \( I_0 \equiv \text{Tr}1 = N \) is the number of particles, while
\[ I_1 = \text{Tr}(L^L L^+) = 2H_{\text{hCM}} \] (18)
is Hamiltonian (1) itself. The higher integrals of motion \( I_k \), \( k = 2, 3, \ldots \), are in involution, i.e. have vanishing Poisson’s bracket with each other. The existence of a high number of conserved quantities is the result of the integrability of the hCM.

One can also write the solution of the hCM as an eigenvalue problem of a matrix which can be explicitly constructed from the initial positions and velocities of Calogero particles. Namely, the trajectories of particles are given by the eigenvalues of the following matrix:
\[ Q(t) = X(0) \cos(\omega t) + \omega^{-1} L(0) \sin(\omega t). \] (19)
Here the matrices \( X(0) \) and \( L(0) \) are constructed from the initial conditions \( x_j(0) \), \( p_j(0) \) using definitions (7) and (8).

3. Dual Calogero system and finite-dimensional reductions

In this section, we consider a complexified version of hCM (12), (13). We parametrize the complex momenta \( p_j \) by the complex numbers \( z_j \) so that the system (12), (13) is rewritten as equations symmetric in \( x_j \) and \( z_j \) (see (20) and (21) below). We refer to the obtained symmetric system as to a self-dual form of the hCM. The self-dual form of hCM (20), (21) makes explicit the duality between the particles \( x_j \) and excitations (parametrized by \( z_j \)) of the Calogero system. It is different from the action-coordinate duality explored previously in classical Calogero systems [13]. The self-dual system for the trigonometric Calogero–Sutherland model appeared previously in [10] (see appendix C). It is transparent in the Hirota form (42) as a symmetry between the tau-functions \( \tau^- \) and \( \tau^+ \) (see [9]).

After introducing the self-dual form of the hCM, we consider different reductions of this system: reductions of the number of points \( z_j \) in a dual model and a real reduction (\( x_j \)—real). Both of these reductions combined produce soliton solutions for an original hCM.

3.1. Self-dual Calogero system

Here we consider \( x_j, z_j \) as well as \( p_j = \dot{x}_j \) and \( \dot{z}_j \) as complex numbers. We introduce the following dynamic system:
\[ \dot{x}_j - i\omega x_j = -i g \sum_{k=1}^{N} \frac{1}{x_j - x_k} + i g \sum_{n=1}^{M} \frac{1}{x_j - z_n}, \] (20)
\[ \dot{z}_n - i\omega z_n = i g \sum_{m=1}^{M} \frac{1}{z_n - z_m} - i g \sum_{j=1}^{N} \frac{1}{z_n - x_j}, \] (21)
for \( x_j(t) \) with \( j = 1, 2, \ldots, N \) and \( z_n(t) \) with \( n = 1, 2, \ldots, M \). Let us note for future use that there is a connection between the motion of the center of masses of the points \( x_j \) and \( z_n \) obvious from (20) and (21)

\[
\sum_{j=1}^{N} (x_j - i\omega x_j) = \sum_{n=1}^{M} (z_n - i\omega z_n).
\]  

(22)

We start with the case \( M = N \). The system (20), (21) is Hamiltonian. It can be defined by its Hamiltonian given up to an additive constant \(-\omega gN(N+1)/4\) by

\[
H_{\text{hCM}} = -\frac{g^2}{2} \sum_{j=1}^{N} \left( \sum_{i=1}^{N} \frac{1}{x_j - x_i} \right)^2 - \frac{g^2}{2} \sum_{j=1}^{N} \left( \sum_{k=1}^{N} \frac{1}{z_j - z_k} \right)^2
\]

\[+
\frac{g^2}{2} \sum_{j,k=1}^{N} \left( \frac{1}{x_j - z_k} \right)^2 - \frac{g}{2} \sum_{j,k=1}^{N} \frac{x_j + z_k}{x_j - z_k}
\]  

(23)

and by a symplectic form \( \Omega = \sum_{j,k=1}^{N} S_{jk} dz_k \wedge dx_j \), where \( S_{jk} = ig(x_j - z_k)^{-2} \) and the corresponding Poisson’s bracket \( \{ z_k, x_j \} = \left( S^{-1}\right)_{kj} \). We note that the system (20), (21), (23) is symmetric under simultaneous exchange \( x_j \leftrightarrow z_j \) and \( g \rightarrow -g \).

Equations (20) and (21) are first-order differential equations. The dynamics is fully defined by the initial values of the complex \( x_j , z_j \), i.e. by \( 2N \) complex numbers.

Taking a time derivative of (20) (and similarly of (21)) and using (20) and (21), we exclude first time derivatives\(^3\). As a result, we obtain the decoupled systems of second-order differential equations

\[
\ddot{x}_j = -\frac{g^2}{2} \frac{\partial}{\partial x_i} \sum_{i\neq j}^{N} \frac{1}{(x_i - x_j)^2} - \omega^2 x_j, \quad j = 1, \ldots, N
\]  

(24)

\[
\ddot{z}_j = -\frac{g^2}{2} \frac{\partial}{\partial z_i} \sum_{i\neq j}^{M} \frac{1}{(z_i - z_j)^2} - \omega^2 z_j, \quad j = 1, \ldots, M.
\]  

(25)

The system (24) is a complex version of the system of the equations of motion obtained from \( h_{\text{CM}} (1) \), i.e. equivalent to (12) and (13). We refer to a system (25) as to the Calogero system dual to (24) or simply the dual Calogero system. We outline the Lax formalism for this dual system and its correspondence to the one for the original system of section 2 in appendixes A and B.

As soon as the initial values of \( x_i \) and \( \dot{x}_i \) are chosen, their evolution is defined by (24). Then the motion of the complex points \( z_j \) is, on one hand, defined by the motion of \( x_j \) through (20), (21), while on the other hand they evolve as the Calogero system (25). This shows that one can think of the transformation \( x_j(t) \rightarrow z_j(t) \) given by (20) as of the Bäcklund transformation from one solution of (24) to the other. We do not explore the connection of our results with Bäcklund transformations further in this work.

3.2. Reduction of the number of particles in a dual system

A remarkable fact is that the derivation of (24), (25) from (20), (21) also holds if \( M \neq N \) (we are interested here in \( M < N \)) and one can still think of (25) as of a dual system for (24)\(^3\) after excluding the first derivatives, one has to reorganize the products of fractions to exclude \( z_j \) from the first equation. For this purpose, the following identity comes in handy:

\[
\frac{1}{x_j - z_k} + \frac{1}{z_j - x_k} + \frac{1}{z_j - z_k} + \frac{1}{x_j - x_k} = 0.
\]
consisting of the smaller number \( M < N \) of particles. The difference with \( M = N \) is that in the case \( M < N \), one cannot generically solve (20) to find \( z_n \) for an arbitrary choice of \( x_j, \dot{x}_j \). Some fine tuning of the initial values of \( x_j, \dot{x}_j \) is necessary. Instead, one can specify \( N \) complex points \( x_j \) and \( M \) complex points \( z_n \) and then find \( \dot{x}_j \) from (20). Then by (21) the motion of \( N \) points \( x_j \) is reduced to a motion of \( M < N \) complex points \( z_n \) governed by a dual Calogero system (25) having fewer degrees of freedom than the original system (24). We refer to this reduction as to a dimensional reduction or to an \( M \)-soliton reduction of (24).

The soliton reduction can also be understood as a limit in which some coordinates of dual particles go to infinity. Indeed, let us consider the self-dual system (20), (21) with \( M = N \). We choose the initial positions \( x_j \) arbitrarily and the initial positions \( z_n \) so that the latter are divided into two groups. The coordinates \( z_n \) \((n = 1, 2, \ldots, M)\) are arbitrary, while the coordinates \( z_k \) \((k = M + 1, \ldots, N)\) are very far away from the origin so that for \( k > M \), \( |z_k| \gg |x_j| \) for any \( j \) and \( |z_k| \gg |z_n| \) for any \( n \leq M \). We are interested in the limit \( z_k \rightarrow \infty \) for \( k > M \). One can see that in this limit only \( M \) coordinates \( z_n, n \leq M \), enter the equations for \( \dot{x}_j \) as is written in (20) with \( M < N \). The equations for \( \dot{z}_j \) are divided in this limit into \( M \) equations for \( \dot{z}_n \) with \( n \leq M \) (see (21)) and to a completely decoupled system of \( N - M \) points \( z_k \) \((k = M + 1, \ldots, N)\). The latter system is not important for us, while the system (20), (21) with \( M < N \) gives an \( M \)-soliton reduction as the dynamics of \( z_n \) with \( n \leq M \) is given by (25) having less degrees of freedom than (24).

3.3. Real reduction

So far we considered \( x_j \) as complex numbers. It is clear, however, from (24) that once the initial values of \( x_j \) and \( \dot{x}_j \) are chosen to be real, they stay real at later times, even though \( z_j \) are moving in a complex plane. Let us specify some arbitrary real values of \( x_j(t = 0) \) and \( \dot{x}_j(t = 0) \). For \( M = N \), one can generically solve the algebraic system (20) \((N\) algebraic equations with \( M = N \) unknowns \( z_j \)) and find corresponding initial complex \( z_j(t = 0) \) and then using (21) initial \( \dot{z}_j(t = 0) \). This procedure defines a real reduction of the complex system (20), (21). We can think of (20), (21) as an alternative way to write the system (12), (13) or equivalently (24) understanding that the initial complex values of \( z_j \) and \( \dot{z}_j \) are not arbitrary but constrained by the reality of \( x_j \) and \( \dot{x}_j \).

We note here that a true symmetry between (24) and (25) exists only for the complex variables \( x_j \) and for \( M = N \). Imposing reality conditions on \( x_j, \dot{x}_j \), one explicitly breaks the symmetry between (real) \( x_j \) and (complex) \( z_n \).

4. Soliton solutions of the hCM with \( N \) particles

Now we consider the case when both real and soliton reductions are applied simultaneously. In this case one can take the real and imaginary parts of complex equations (20) and write the following real equations:

\[
\omega x_j = g \sum_{k=1(k\neq j)}^{N} \frac{1}{x_j - x_k} - \frac{g}{2} \sum_{n=1}^{M} \left( \frac{1}{x_j - z_n} + \frac{1}{x_j - \bar{z}_n} \right),
\]

\[
p_j = \frac{g}{2} \sum_{n=1}^{M} \left( \frac{1}{x_j - z_n} - \frac{1}{x_j - \bar{z}_n} \right).
\]

If \( M \) complex positions \( z_n \) are given at any time, one can find both \( N \) real positions \( x_j \) and corresponding real momenta \( p_j \). The data \( x_j, p_j \) are not independent but ‘tuned’, i.e. related by (26) and (27) through the values of \( M \) complex parameters \( z_n \) \((2M \) real parameters).
Equations (26) have an electrostatic interpretation. Indeed, (26) can be obtained as extrema conditions for the following function:

\[
E = \sum_{j=1}^{N} \frac{\alpha x_j^2}{2g} - \sum_{j<k} \ln|x_j - x_k| + \frac{1}{2} \sum_{j=1}^{N} \sum_{n=1}^{M} \ln|x_j - z_n|^2.
\]  

(28)

This function coincides with an ‘electrostatic energy’ of \( N \) particles with unit charges interacting through a logarithmic potential (2d Coulomb potential). The particles are restricted to move along a straight line (a real axis) and are in the presence of \( 2M \) external charges \(-\frac{1}{2}\) placed at \( z_n, \bar{z}_n \) and an external harmonic potential. We note here that the solution of (26) is not necessarily a minimum of (28). Soliton solutions correspond to any extremum (maximum, minimum or saddle point) of (28). It is important to stress that here and in the following we choose the signs \( \omega > 0 \) and \( g > 0 \) which guarantees that the harmonic potential in (28) is confining.

4.1. Background

As an ultimate case of \( M \)-soliton reduction, we consider \( M = 0 \) which gives a static solution. Indeed, (26), (27) in the limit \( z_n \to \infty \) for all \( n \) becomes \( p_j = 0 \) for all \( j \) and the coordinate of particles in equilibrium are defined by (26) as

\[
\alpha x_j = g \sum_{k=1, (k \neq j)}^{N} \frac{1}{x_j - x_k}.
\]

(29)

It is well known that a solution of this system of algebraic equations is given by the roots of the \( N \)th Hermite polynomial (Stieltjes formula [14, 15]). Namely,

\[
x_j(t) = \sqrt{\frac{g}{\omega}} h_j, \quad H_N(h_j) = 0, \quad j = 1, 2, \ldots, N.
\]

(30)

4.2. One-soliton solution

Consider the case \( M = 1 \). Equations (26) and (27) give

\[
\alpha x_j = g \sum_{k=1, (k \neq j)}^{N} \frac{1}{x_j - x_k} - \frac{g}{2} \left( \frac{1}{x_j - z_1} + \frac{1}{x_j - \bar{z}_1} \right),
\]

(31)

\[
p_j = i g \left( \frac{1}{x_j - z_1} - \frac{1}{x_j - \bar{z}_1} \right).
\]

(32)

Equations (31) can be viewed as a new generalization to the Stieltjes problem (29) (see [14, 16, 17]). To the best of our knowledge, this generalization to the Stieltjes problem has not been studied and the exact solutions of (31) are not known. One can think of (31) as the definition of some polynomials \( P_N(x, z_1) = \prod_j (x_j - x_j) \) such that \( P_N(x_j, z_1) = 0 \) for \( j = 1, 2, \ldots, N \). In the limit \( z_1 \to \infty \), we have \( P_N(x, z_1) \to H_N(x \sqrt{\omega/g}) \). We make some progress in describing these solutions in the limit \( N \gg 1 \) in section 7.

Equation (25) in the case \( M = 1 \) takes an especially simple form

\[
\bar{z}_1 = -\alpha^2 z_1
\]

(33)

and can be easily solved

\[
z_1(t) = A e^{i\omega t} + B e^{-i\omega t},
\]

(34)
i.e. the trajectory of $z_1$ is an ellipse in the complex plane. Using (22) for $M = 1$, we obtain the parameters of this ellipse:

$$z_1(t) = z_1(0) e^{i\omega t} + \frac{\sin\omega t}{\omega} [P(0) - i\omega X(0)],$$

where $z_1(0)$ is the initial position of $z_1$ in the complex plane, and $X = \sum_{j=1}^{N} x_j$ and $P = \sum_{j=1}^{N} p_j$ are the center of mass and the total momentum of the system at $t = 0$, respectively. Both $X(0)$ and $P(0)$ are in turn defined by $z_1(0)$ through (31), (32).

Let us consider for simplicity a particular initial value $z_1(0) = ib$ with $b > 0$. Then the solution of (31) gives $X = 0$. The equation of the ellipse in this case is

$$z(t) = ib \cos(\omega t) - (b - P(0)/\omega) \sin(\omega t),$$

where we find from (32),

$$P(0) = -b \sum_j \frac{g}{x_j^2 + b^2} < 0.$$  

The inequality means that $a = b - P(0)/\omega > b$ so that the major semiaxis $a$ of the ellipse is always along the real axis. In the limit $b \rightarrow \infty$, $P(0) \sim -\frac{gN}{\omega}$, and major and minor semiaxes are $a \approx b + \frac{g}{2\omega}$ and $b$, respectively. The eccentricity of the ellipse goes to zero (ellipse becomes a circle) as $b \rightarrow \infty$. In the opposite limit $b \rightarrow 0$, we have $P(0) \sim -\frac{g}{b}$ giving $a \sim \frac{g}{ab}$. In this limit, the ellipse has a large eccentricity with the major semiaxis $a \sim b^{-1} \rightarrow \infty$ as the minor semiaxis $b \rightarrow 0$.

Let us now fix some large value of the major semiaxis $a$ by taking $z_1(0) = a > 0$. It is clear from this analysis that there are two different solutions of (31) corresponding to the large and small values of the minor semiaxis of the ellipse. These two solutions correspond to two different extrema of electrostatic energy (28). For one of them all $N$ particles (‘cloud’) are located around the origin, far from the external negative ‘soliton’ charge placed at $a$. For the other extremum, the cloud around the origin consists of $N - 1$ particles. One more particle is far away from the cloud, close to the external charge. The former solution corresponds to the large minor semiaxis $b \approx a$, while the latter corresponds to $b \sim g/a$. If we decrease $a$, two corresponding values of $b$ approach each other and become equal to some ‘critical’ value $b = b_c$. At this value the major semiaxis $a$ has a minimum value $a_c$. For $a < a_c$, there are no real solutions of (31). Later in section 7 we will show that in the limit of large $N$, this minimum occurs at $b_c \sim N^{1/6}$ and corresponds to a minimal major semiaxis $a_c - R \sim N^{-1/6}$, where $R = \sqrt{2gN/\omega}$ is the radius of the ‘cloud’ of particles. A world-line diagram of a typical single-soliton solution for $b < b_c$ is shown in figure 1. In this regime the soliton solution looks like a Newton’s cradle. The soliton is essentially a single particle when its position is outside of the ‘cloud’. This particle transfers its momentum all the way through the system with the other particle being kicked out from the other side of the system. Due to the interactions (in contrast to the actual Newton’s cradle), the particle is dressed by other particles when inside of the cloud. This picture was qualitatively described by Polychronakos [18].

5. Particles as poles of meromorphic functions

In this section, following the approach of [9, 10], we consider the particles of the hCM as poles of meromorphic functions and derive dynamic equations satisfied by those functions.

\footnote{4 We do not know how to prove this statement. Equations (31) have a symmetry $x_j \rightarrow -x_j$ and numerical solutions suggest that this symmetry is unbroken resulting in $X = 0$.}
Figure 1. World-line diagram for a single-soliton solution of the hCM is shown for $N = 40$ and the value $b \approx 0.84 < b_\text{c} \approx 1.67$. Lines are the world lines of individual Calogero particles. There are no crossings of world lines. However, the lump of density corresponding to a soliton travels all the way through the system. It becomes an isolated particle outside of the ‘cloud’ of other particles.

(This figure is in colour only in the electronic version)

We start by introducing two meromorphic functions $u^\pm(x)$ of a complex variable $x$,

$$u^-(x) = -ig \sum_{j=1}^{N} \frac{1}{x - x_j} + i\omega x,$$  \hspace{2cm} (38)

$$u^+(x) = ig \sum_{n=1}^{M} \frac{1}{x - z_n}.$$  \hspace{2cm} (39)

These functions are completely defined by their poles $x_j$ and $z_n$ which move as Calogero particles (24), (25). The function $u^-(x)$ is defined by its poles—the coordinates of the hCM particles $x_j$. The function $u^+(x)$ is defined by the coordinates of the dual model $z_n$ or alternatively by its values at $x_j$ given by

$$u^+(x_j) = p_j - i\omega x_j + ig \sum_{k=1(k \neq j)}^{N} \frac{1}{x_j - x_k}.$$  \hspace{2cm} (40)

Conditions (40) are equivalent to (20). Note that the rhs of (40) appears in the factorized form of the hCM Hamiltonian (2).

Having defined $u^\pm(x)$ by (38), (39), we can rewrite the system (20), (21) as a single equation

$$ut + \left[ \frac{u^2}{2} + i \frac{g}{2} (u^+ - u^-) x + \frac{\omega^2 x^2}{2} \right] = 0$$  \hspace{2cm} (41)

with $u \equiv u^+ + u^-$. Indeed, assuming the form (38), (39) and taking the residues of (41) at points $x_j$, $z_n$, we reproduce (20) and (21), respectively. Equation (41) is a version of a bidirectional Benjamin–Ono equation [10] modified for the hCM. A key advantage of (41) is that the number of particles $N$ does not enter the equation explicitly and, therefore, this form is well suited for taking the hydrodynamic limit $N \to \infty$. Before discussing this limit in section 6, we also give a bilinear Hirota form of (41)

$$\left( iD_t^+ + \frac{g}{2} D_t^2 - \omega x D_x - \frac{\omega^2 t}{2} \right) \tau^- \cdot \tau^+ = 0,$$  \hspace{2cm} (42)
where \( \tau^\pm \) are given by
\[
\tau^+ = \imath g \partial_x \ln \tau^+ , \tag{43}
\]
\[
\tau^- = -\imath g \partial_x \ln \tau^- , \tag{44}
\]
and, e.g., \( D_f \cdot g \) denotes Hirota derivative. We note here that up to trivial time-dependent factors, the tau-functions are given by
\[
\tau^-(x) = N \prod_{j=1}^N (x - x_j) = \det(x - Q), \tag{45}
\]
\[
\tau^+(x) = M \prod_{n=1}^M (x - z_n) = \det(x - \tilde{Q}), \tag{46}
\]
where the \( N \times N \) matrix \( Q \) is given by (19) and \( \tilde{Q} \) is the corresponding dual \( M \times M \) matrix (A.6). The self-duality of the hCM is expressed then as an obvious symmetry of (42) under the exchange of the tau-functions \( \tau^- \leftrightarrow \tau^+ , \ g \rightarrow -g \).

6. Equations of motion in a hydrodynamic form and the hydrodynamic limit

Here we rewrite the equations of motion for the hCM in a hydrodynamic form for finite \( N \) and then consider the hydrodynamic limit of those equations, i.e. the limit of infinitely many particles \( N \rightarrow \infty \). We start with equations for \( u^\pm (x) \) and with corresponding analyticity and reality conditions and then present the equations of motion in a hydrodynamic form, i.e. written for particle density and velocity fields. We again follow the approach of [10].

Let us start by rewriting hCM (1) in terms of the fields \( u^\pm \). One can show that (1) is identical to
\[
\mathcal{H}_{\text{hCM}} = \frac{1}{4 \pi g} \oint dz \left( \frac{u^3}{3} + \frac{\imath g}{2} u^+ \partial_x u^- + \omega^2 z^2 u^- \right) = \frac{1}{4 \pi g} \oint dz \left( u^{12} u^- + u^+ u^- + \frac{\imath g}{2} u^+ \partial_x u^- + \omega^2 z^2 u^- \right) \tag{47}
\]
by using definition (38) and property (40). The contour of integration in (47) goes around the real poles \( x_j \) of \( u^- (z) \) counter-clockwise and does not encircle any of complex poles \( z_n \) of \( u^+ (z) \). The equations of motion (41) are equivalent to (12) and (13).

The poles of \( u^- (z) \) are real and one can parameterize the real analytic function \( \imath u^- (z) \) by a real function of a real variable \( \rho (x) \)—a particle density field. We introduce
\[
\rho (x) = \sum_{j=1}^N \delta (x - x_j) \tag{48}
\]
and rewrite (38) as a Cauchy transform of \( \rho (x) \):
\[
u^-(z) = \imath \omega z - \imath g \int_{-\infty}^{\infty} \frac{dx}{z - x} \frac{\rho (x)}{z - x}, \tag{49}
\]
where \( z \) is a complex number not coinciding with any of poles of \( u^- (z) \) (e.g., \( \text{Im}(z) \neq 0 \)).

The field \( u^- (z) \) is discontinuous on the real axis with the discontinuity related to the density of particles. More precisely,
\[
u^- (x \pm \imath 0) = \mp \pi g \rho + \imath (\pi g \rho^R + \omega x) \tag{50}
\]
with the discontinuity
\[
u^- (x + \imath 0) - \nu^- (x - \imath 0) = -2 \pi g \rho (x). \tag{51}
\]
Using (38), (39) as well as (20), (21) and (50), (51) after some calculations, we obtain that on the real axis
\[ \rho(x)u^+(x) = -ig \left( \pi \rho(x) \rho^H(x) - \frac{1}{2} \partial_x \rho \middle| + i \omega x \rho(x) + \sum_{j=1}^{N} \dot{x}_j \delta(x - x_j) \middle| \right). \] (52)

We identify the last term of the rhs as a momentum density of the system
\[ \rho(x)v(x) = \sum_{j=1}^{N} \dot{x}_j \delta(x - x_j), \] (53)
where \( v(x) \) is the velocity field. We divide (52) by \( \rho(x) \) and obtain
\[ u^+(x) = v - ig(\pi \rho^H - \partial_x \log \sqrt{\rho}) + i \omega x. \] (54)

Equations (50) and (54) give the relation between the fields \( u^\pm(x) \) and microscopic density and velocity fields. We note here that these relations are exact even in the case of the finite number of particles \( N \). The density and velocity fields have a conventional Poisson’s bracket (6). Substituting (50) and (54) into Hamiltonian (47), we arrive to the Hamiltonian of the hCM in a hydrodynamic form (3).

Hamilton equations following from (3) and (6) are the Euler and the continuity equations for density and velocity fields:
\[ \rho_t + \partial_x (\rho v) = 0, \] (55)
\[ v_t + \partial_x \left( \frac{v^2}{2} + w(\rho) + \frac{\omega^2 x^2}{2} \right) = 0, \] (56)
where the chemical potential \( w(\rho) \) is given by
\[ w(\rho) = \frac{1}{2} (\pi g \rho^2) + \pi g^2 \rho^H - \frac{\rho^2}{2} \frac{1}{\sqrt{\rho}} \frac{1}{\sqrt{\rho}}. \] (57)

We remark here that although the equations in this section are written in a hydrodynamic form, they are still valid for a finite number of particles \( N \) and are equivalent to the corresponding equations for the hCM. In the case of finite \( N \), the density and velocity fields are singular functions given by their microscopic definitions (48), (53). All expressions involving these fields and their products should be properly regularized as is explained above. The key point of the regularization is to use definitions (38) and (39) of \( u^\pm \) as meromorphic functions.

Let us now go to a hydrodynamic limit. This simply means that from now on, we treat \( \rho(x) \) and \( v(x) \) as continuous (even smooth) fields forgetting the discrete nature of hCM particles. Note that the information about the total number of particles is still preserved in the relation \( \int \rho \, dx = N \) and one should do some rescaling of fields when going to the large \( N \) limit (see section 7.2). Having specified an initial configuration \( \rho(x, t = 0), v(x, t = 0) \), one can in principle solve (55) and (56) and find density and velocity fields at all times. An interesting class of solutions (multi-soliton solutions) of (55) and (56) is realized for a fine-tuned initial configurations of fields. As the number of particles \( N \) and the number of poles \( M \) of the field \( u_\pm(x) \) are independent parameters, one can take a hydrodynamic limit \( N \rightarrow \infty \) keeping \( M \) finite and fixed. As a result, one obtains solutions in which the dynamics of the continuous fields \( \rho(x, t) \) and \( v(x, t) \) is reduced to a motion of \( M \) points \( z_n(t) \) in a complex plane. This is a finite-dimensional reduction of an infinitely dimensional hydrodynamic system. We refer to this reduction as to an \( M \)-soliton solution.

In the following section, we consider several examples of soliton solutions in the large \( N \) limit.
7. Soliton solutions of the hCM in the hydrodynamic limit

7.1. Background

Let us find the configuration \( \rho(x) \) and \( v(x) \) with given \( \int \rho(x) \, dx = N \) that minimizes the energy (3). We rewrite (3) in a manifestly positive form

\[
H = \int dx \rho \left[ \frac{v^2}{2} + \frac{1}{2} (\pi g \rho H - g \partial_x \log \sqrt{\rho} - \omega x)^2 \right] + \text{const}
\]

\[
= \int dx \rho \frac{1}{2} |u^+(x)|^2 + \text{const},
\]

where we used (54) to obtain the last line. It is easy to see that the minimal energy condition is

\[
u^+(x) = 0,
\]

or writing it separately for real and imaginary parts and using (54),

\[
g(\pi \rho H - \partial_x \log \sqrt{\rho}) - \omega x = 0,
\]

\[
v(x) = 0.
\]

Equation (60) is the hydrodynamic form of equation (29). It describes the distribution of the zeros of the Hermite polynomials \( H_N(x \sqrt{\omega/g}) \). In the limit \( N \to \infty \), we think of \( \rho(x) \) and \( v(x) \) as of continuous fields. In this limit, the solution of (60) is given by a Wigner’s semi-circle law

\[
\rho_0(x) = \frac{\omega}{\pi g} \sqrt{R^2 - x^2}, \quad R = \sqrt{\frac{2gN}{\omega}}.
\]

Equation (60) also appears in the context of random matrix theory (see, for example, [19, 20]). We note here that both the density at the origin \( \rho_0(0) = \tilde{\rho} = \frac{1}{\sqrt{\pi}} \sqrt{\frac{2gN}{\omega}} \) and the radius of the cloud of particles \( R \) are proportional to \( N^{1/2} \). The main correction to (62) in the next to leading order in \( 1/N \) comes from the fact that the largest zero of \( H_N(x \sqrt{\omega/g}) \) is not \( R \) but is given asymptotically by \( x_{\text{max}} \approx R - \gamma_1 R^{-1/6} \), where the constant \( \gamma_1 \approx 1.8557 \ldots \) is related to the zeros of Airy functions. It is also notable that the distance between neighbor roots goes as \( x_{n+1} - x_n \sim \tilde{\rho}^{-1} \sim N^{-1/2} \) close to the origin and \( x_N - x_{N-1} \sim R^{-2} \) near the boundary of the cloud [14].

7.2. One-soliton solution

The one-soliton solution is given by

\[
u^+(x) = \frac{ig}{x - z_1(t)},
\]

with \( z_1(t) \) satisfying (25) for \( M = 1 \) or (33). Using (54), we rewrite (63) as

\[
v - i\omega x = \frac{ig}{x - z_1} + ig(\pi \rho H - \partial_x \log \sqrt{\rho}).
\]

This relation allows one, in principle, to find density and velocity fields from the position \( z_1 \) at any moment of time. The soliton parameter \( z_1(t) \) is moving in a complex plane along ellipse (35). Therefore, (64) gives a one-dimensional reduction of an infinite-dimensional Calogero system in the hydrodynamic limit defined by (3), (6). Equation (64) is a hydrodynamic analog of (20) with \( M = 1 \).
Taking the real and imaginary parts of (64), we obtain the hydrodynamic counterparts of (31) and (32)

\[ g(\pi \rho H - \partial_x \log \sqrt{\rho}) - \omega x = \frac{g}{2} \left( \frac{1}{x - z_1} + \frac{1}{x - \bar{z}_1} \right), \]  
(65)

\[ v = \frac{ig}{2} \left( \frac{1}{x - z_1} - \frac{1}{x - \bar{z}_1} \right). \]  
(66)

It is remarkable that the velocity field of a one-soliton solution is given explicitly by a simple expression (66). Equation (65) defines, albeit implicitly, the density field for a one-soliton solution. Comparing (65) and (66) with the corresponding background equations (60) and (61), we see that the fields for a one-soliton solution are obtained by perturbing the background configurations by terms \( \sim 1/z_1 \). In particular, in the limit \( z_1 \to \infty \), we go back to the equilibrium configuration (60), (61). In the large \( N \) limit, the term \( \partial_x \log \sqrt{\rho} \) and the right-hand side of (65) are both suppressed by \( 1/N \) with respect to other two terms. We also note here that the solution of (33) for \( z_1(t) \) is given by (35), where

\[ P = \int dx \rho v, \quad X = \int dx \rho x \]  
(67)

are the total momentum and the center of mass of the system, respectively. Of course, finding \( P(0) \) and \( X(0) \) from \( z_1(0) \) using (65), (66) is still a non-trivial problem.

In the limit \( \omega \to 0, N \to \infty \) and \( \bar{\rho} = \rho_0(0) = \frac{1}{\pi} \sqrt{\frac{2\omega N}{g}} = \text{const} \), equation (65) gives rise to Lorenzian-shaped solitons in agreement with solitons obtained by Polychronakos [11] and Andr\'ic et al [12] for a model without harmonic potential and with the background density \( \bar{\rho} \).

As the exact solution of (31), (65) is not available, we briefly discuss the solution in the limit of large \( N \) in the next to leading order in \( 1/N \).

Rescaling the variables \( (\rho, x, z_1, v) \to (\rho, x, z_1, v)\sqrt{N} \) in (65) and (66), one can easily see that the right-hand sides of (65) and (66) are of the order of \( 1/N \). Therefore, in the leading order in \( N \), one has density and velocity given by (61) and (62).

The correction to (60) consists of two parts: the correction to the background solution without soliton and to the correction caused by the presence of the soliton, i.e. by the right-hand side of (65). Here we are interested only in the latter.

First, let us assume that the solution of (65) is given by a smooth function \( \rho(x) \). Then we have

\[ \rho(x, t) = \rho_0(x) + \frac{1}{\pi} \frac{y_1}{(x - x_1)^2 + y_1^2} \]  
(68)

\[ v(x, t) = -g \frac{y_1}{(x - x_1)^2 + y_1^2}, \]  
(69)

where we denoted \( z_1(t) = x_1(t) + iy_1(t) \). Solution (68), (69) describes a lump of the density of the changing width \( \sim y_1(t) \) located at the moving point \( x_1(t) \). The point \( z_1(t) \) moves according to (35). Let us start with \( z_1(0) = ib \). Using (68), (69) and (67), we find the parameters \( X(0) = 0 \) and \( P(0) \approx -\frac{g}{2b} + \omega b - \omega \sqrt{R^2 + b^2} \). The major semiaxis of the ellipse is given (see section 4.2) by

\[ a = b - \omega^{-1} P(0) \approx \frac{g}{2ab} + \sqrt{R^2 + b^2}. \]  
(70)

As a function of time, \( z_1(t) = ib \cos \omega t - a \sin \omega t \). We can identify several interesting limits corresponding to different values of \( b \).
Large: $b \gg R \sim \sqrt{N}$. In this case we have $a \approx b + R^2/(2b)$. The trajectory of $z_1$ is close to a circle of a very large radius $b$. The width $b$ of the soliton is bigger than the size of the cloud. In this case, there is no pronounced lump of the density. Instead the whole cloud oscillates slightly around the origin.

Intermediate I: $N^{1/6} \ll b \ll \sqrt{N}$. For $b \ll R$ we obtain from (70) $a \approx R + \frac{g}{\omega b} + \frac{b^2}{2R}$. The major semiaxis $a$ has a minimum at $b \approx (gR/\omega)^{1/3} \sim N^{1/6} \sqrt{g/2\omega}$. The width of the soliton is $b$ at $t = 0$. It is much smaller than the size of the system and one can see a very well pronounced lump of density while soliton travels through the system. The width of the soliton somewhat changes in time but remains much larger than an interparticle distance inside the cloud. Therefore, the continuous approximation is still valid in this regime at all times. The soliton in this regime is a well-pronounced lump of density which oscillates inside the cloud of particles.

Intermediate II: $N^{-1/2} \ll b \ll N^{1/6}$. This is, probably, the most interesting regime. For an initial configuration, the width of the soliton $b$ is still much bigger than an interparticle distance $N^{-1/2}$ in the middle of the harmonic trap. Therefore, we still can use a continuous approximation and the value $a \approx R + \frac{g}{\omega b} + \frac{b^2}{2R}$. However, as a function of time, $y_1(t)$ decreases and at some point becomes of the order of an interparticle distance at the point $x_1(t)$. Starting from this time we cannot use the continuous approximation. Instead, we assume that the density can be divided into a delta function corresponding to a single particle plus a continuous background with $N - 1$ particles. In the limit when $y_1$ is much smaller than an interparticle distance, we have simply

$$\rho(x, t) = \rho_0(x) + \delta(x - x_1(t)). \quad (71)$$

The evolution of density in this case is shown in figure 2 and is a continuous analog of a world-line diagram for a finite number of particles shown in figure 1. Note that in this regime a boundary particle is kicked out of the cloud and travels outside of the cloud for some fraction of the period of the motion.

Small: $b \ll N^{-1/2}$. In this limit, the continuous approximation is invalid already at $t = 0$ and we consider an isolated particle at the origin with other $N - 1$ particles forming a continuous cloud (71) for all times. The value of $P(0)$ is given by a microscopic formula (37) which is dominated in this case by a particle at the origin $P(0) \approx -g/b$. It gives $a \approx b + g/(\omega b)$. The density evolution is given by a particle moving in the semicircle background (71), (62).

7.3. Multi-soliton solution

Here we briefly list equations describing the $M$-soliton solutions of (55) and (56). The density and velocity fields are completely defined by the complex coordinates $z_n$ through (39) which can be rewritten using (54) as

$$v - i\omega x = \frac{1}{x - z_k} + ig(\pi \rho^H - \partial_x \log \sqrt{\rho}). \quad (72)$$

A maximal interparticle distance is at the edge of the cloud and is of the order $N^{-1/6}$ [14].
Figure 2. Time evolution ($t_1 < t_2 < t_3 < t_4$) of a one-soliton solution in the hCM is shown schematically in the large $N$ limit. The figure corresponds to the regime intermediate II. As the soliton moves to the left, its width decreases and becomes of the order of the interparticle distance at some $x$ (shown by the dashed line). After this point, the continuum approximation is not valid and the soliton is represented by the delta-function (shown by an arrow). This figure is a continuous analog of figure 1.

An initial configuration of $M$ complex numbers $z_n$ defines initial velocity and density fields through (72). After density and velocity fields are found, one can easily determine initial $z$-velocities using a hydrodynamic analog of (21) which has a form

$$\dot{z}_n - i\omega z_n = ig \sum_{m=1,m\neq n}^M \frac{1}{z_n - z_m} + \pi g (\rho + i\rho H).$$

After the initial velocities $\dot{z}_n$ are obtained, the dynamics of $z_n$ is defined by (25) so that $z_n$ can be found as the eigenvalues of the matrix $\hat{Q}$ (A.6).

The dynamical problem of finding a multi-soliton solution of (55) and (56) is reduced to finding the density $\rho(x, \{z_n\})$ from (72). The latter is still complicated, albeit time-independent, integral equation.

8. Conclusion

In this work, we used a self-dual formulation (20), (21) of a harmonic Calogero system (hCM) (1) to find an $M$-soliton reduction of an hCM with $N$ particles $M < N$. Soliton solutions can be obtained by fine tuning the initial conditions $x_i$, $\dot{x}_i$ for Calogero particles. We found a hydrodynamic formulation of this reduction and then took a hydrodynamic limit $N \to \infty$ keeping $M$ finite. As a result, we obtained an $M$-soliton solution of an infinitely dimensional hydrodynamic system.

The derivations of this paper are based on the similar derivations of [10] made for the Calogero–Sutherland model. We emphasized in this work that the soliton reductions
are possible even for the finite number of particles while [10] considers only the finite soliton solutions of an infinite-dimensional translationally invariant model. We gave the generalizations of finite-dimensional reduction to the cases of trigonometric and rational Calogero–Moser systems in appendix C and appendix D, respectively. The generalization of finite-dimensional reductions to the elliptic CM is also rather straightforward and will be given elsewhere. We also expect that the generalizations of our results to more general Calogero–Moser systems related to Lie algebras are possible.

In this work we did not discuss the meaning of the presented soliton reductions of the hCM neither within the projection method of solving the hCM (see [3, 23]) nor within the inverse scattering formalism [21]. It is interesting to find the corresponding descriptions of both the self-dual formulation of the hCM and of the soliton reductions.

The self-duality of the hCM given by (20), (21) and used in this work is different from the known dualities of CM [13, 22]. It would be interesting to have a precise relation between those dualities as well as the connection with the known bispectral property of Calogero–Moser systems [24–26].

The hCM and many other CM remain integrable after quantization. Moreover, many results obtained for classical CM have direct analogs for their quantum counterparts. In particular, the pole ansatz can be extended to the quantum case [9]. The classical soliton solutions of CM correspond to the quasi-particle excitations of the corresponding quantum models [5]. It would be interesting to give the quantum analogs of the results presented here.

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Appendix A. Lax formalism for a dual Calogero system

In this appendix, we describe Lax matrices for a dual Calogero system. The formalism is almost identical to the one presented in section 2 for an original hCM. In addition, we introduce an intertwining matrix \( F \) relating corresponding matrices between dual systems.

Let us define the matrices dual to (7)–(9) as

\[
\hat{Z}_{mn} = \delta_{mn} z_m(t),
\]

\[
\hat{L}^\pm = \hat{L} \pm i\alpha \hat{Z},
\]

where \( \hat{L}_{mn} = \dot{z}_m \delta_{mn} + (1 - \delta_{mn}) \frac{ig}{z_m - z_n} \),

\[
\hat{M}_{mn} = g \left[ \delta_{mn} \sum_{l=1(l\neq m)}^{M} \frac{1}{(z_m - z_l)^2} - (1 - \delta_{mn}) \frac{1}{(z_m - z_n)^2} \right],
\]

Similar to (10) and (11), we have

\[
[\hat{Z}, \hat{L}] = ig e_M \otimes e_M^T - 1_M.
\]

\[
\hat{M} e_M = 0 \quad \text{and} \quad e_M^T \hat{M} = 0.
\]

Here \( e_M^T = (1, 1, \ldots, 1) \) is a row vector made out of \( M \) ones and \( 1_M \) is a unit \( M \times M \) matrix. To avoid confusion, we will denote the vector \( e \) from (11) by \( e_N \) here.
It is obvious that other formulas of section 2 can also be written in terms of dual variables and matrices. For example, similar to $x_j(t)$ the values of $z_n(t)$ at any time can be found as the eigenvalues of a $\hat{Q}$ matrix

$$\hat{Q}(t) = \hat{Z}(0) \cos(\omega t) + \omega^{-1} \hat{L}(0) \sin(\omega t).$$

(A.6)

The dual variables $z_j$ are related to the original variables $x_j$ through (20), (21) and the natural question is how the corresponding matrices and, in particular, the integrals of motion for the dual system are related to the ones for an original system. Here we relate matrices (7), (8) to (A.1), (A.2). Then in appendix B we find the relations between the corresponding integrals of motion.

In the following, we consider matrices (7), (8), (A.1) and (A.2) as the functions of the parameters $x_j$, $z_n$ only, with time derivatives expressed in terms of these parameters using (20) and (21). We introduce one more ‘intertwining’ rectangular matrix $F$ of the size $N \times M$,

$$F_{ijn} = \frac{ig}{x_j - z_n}.$$  \hspace{1cm} (A.7)

The matrix $F$ depends on both direct and dual variables and provides a connection between dual systems as we will see below. It is straightforward to show that the following identity holds for both upper and lower signs:

$$L^\pm F = F \hat{L}^\pm - \omega g(1 \pm 1)e_N \otimes e_M^T,$$

(A.8)

where multiplication is the matrix multiplication. We also find the identities

$$L^- e_N = F e_M,$$

(A.9)

$$e_M^T F = e_M^T \hat{L}^-,$$

(A.10)

which are equivalent to the equations of motion (20), (21).

We conclude this appendix by stating that the matrix $F$ obeys a simple matrix evolution equation

$$F = -i\omega F - iM F + i\hat{M},$$

(A.11)

while $\hat{L}^\pm$ satisfy equations fully analogous to (16),

$$\dot{\hat{L}}^\pm = -i[\hat{M}, \hat{L}^\pm] \pm i\omega \hat{L}^\pm.$$  \hspace{1cm} (A.12)

A derivation of (A.11) is based on (20) and (21) and is rather straightforward albeit somewhat cumbersome.

Appendix B. Integrals of motion

It follows from (16) that

$$\partial_t(L^- L^*) = -i[M, L^- L^*]$$  \hspace{1cm} (B.1)

and, therefore, (17) are the integrals of motion. In fact, time evolution (B.1) does not change the eigenvalues of $L^- L^*$ and describes an isospectral deformation of this matrix. A similar conclusion can be derived for the matrices $\hat{L}^- \hat{L}^*$ and $\hat{L}^* \hat{L}^-$ using (A.12). Here we relate the integrals of motion (17) to analogous expressions for the dual system.

Let us start with an easily verifiable identity

$$[\hat{L}^*, \hat{L}^-] = 2i\omega [\hat{Z}, \hat{L}] = -2\omega g (e_M \otimes e_M^T - 1_M).$$
We proceed as
\[ F \hat{L}^+ \hat{L}^- = F \hat{L}^- \hat{L}^+ - 2 \omega g F (e_M \otimes e_M^T - 1_M) \]
\[ = L^- (L^+ F + 2 \omega g e_N \otimes e_M^T) - 2 \omega g F (e_M \otimes e_M^T - 1_M) \]
\[ = L^- L^+ F + 2 \omega g F, \]
where we used (A.8) and (A.9). If \( f \) is an eigenvector of \( \hat{L}^+ \hat{L}^- \) and \( \lambda \) is a corresponding eigenvalue, i.e. \( \hat{L}^+ \hat{L}^- f = \lambda f \), it follows from (B.2) that \( L^- L^+ \) has an eigenvalue \( \lambda + 2 \omega g \) with the corresponding eigenvector \( F f \). We conclude that \( M \) eigenvalues of \( \hat{L}^+ \hat{L}^- \) are identical (after the shift by \( 2 \omega g \)) to \( M \) eigenvalues of \( L^+ L^- \). We show below that the remaining \( N-M \) eigenvalues of \( L^+ L^- \) are constants given by (B.6). Therefore, the integrals of motion of the original and dual hCM are simply related.

We start with the relation between the integrals of motion of dual systems for the case \( M = N \). In this case, the matrix \( F \) is square and invertible (we assume that \( z_j \neq x_k \) for any \( j, k = 1, \ldots, N \)). Then one can find the matrices \( \hat{L}^\pm \) for the dual system from (A.8), etc. In particular, (B.2) can be written as
\[ L^- L^+ = F (\hat{L}^+ \hat{L}^- - 2 \omega g 1_N) F^{-1}. \]
One immediately concludes that the integrals of motion of dual systems are connected by a very simple relation
\[ I_k = \text{Tr}(L^- L^+)^k = \text{Tr}(\hat{L}^+ \hat{L}^- - 2 \omega g 1_N)^k. \]

To consider the case \( M < N \), we exploit the fact that the dimensional reduction to the \( M \)-soliton solution can be obtained by taking some of \( z_j \) to infinity as is described in section 3.2. We divide \( z_1, \ldots, z_M \) into two groups. We keep \( z_1, \ldots, z_M \) finite and take \( z_{M+k} = \tilde{z}_k \) for \( k = 1, \ldots, (N-M) \) to infinity. We take this limit for the matrix \( \hat{L}^+ \hat{L}^- = (\hat{L}^-)^2 + 2 i \omega g \tilde{Z} \hat{L}^- \) and leave only non-vanishing matrix elements. We use the fact that all \( x_i \) are chosen to be finite. The matrix obtained in the limit has a block-triangular form and its eigenvalues are given by the eigenvalues of \( (\hat{L}^- L^+)_M \) reduced to the size \( M \times M \) and to the eigenvalues of the \( (N-M) \times (N-M) \) matrix \( 2 \omega g B \) defined as
\[ B_{ij} = \begin{pmatrix} N - M - \sum_{k=1}^{N-M} \frac{\tilde{z}_k}{\tilde{z}_j - \tilde{z}_k} \end{pmatrix} \delta_{ij} + (1 - \delta_{ij}) \frac{\tilde{z}_i}{\tilde{z}_i - \tilde{z}_j}. \]
It is easy to show\(^6\) that the eigenvalues of \( B \) are 1, 2, 3, \ldots, \( N-M \). Therefore, the first \( N-M \) eigenvalues of \( L^- L^+ \) are trivial and given by \( \lambda_s = 2 \omega g s \), \( s = 0, 1, 2, \ldots, (N-M-1) \). The remaining \( M \) eigenvalues are not trivial and coincide with those of the \( M \times M \) matrix of the dual model \( \hat{L}^+ \hat{L}^- \) shifted by \( 2 \omega g \). This fact illustrates the meaning of \( M \)-dimensional reduction for the integrals of motion. In particular, for the background solution \( M = 0 \), all \( N \) eigenvalues of \( L^- L^+ \) are given by \( 2 \omega g s \), \( s = 0, 1, 2, \ldots, (N-1) \). The latter result is known and can be obtained directly from the properties of Hermite polynomials (see equations (10a) and (10b) of [27]).

**Appendix C. Solitons as finite-dimensional reductions of the \( N \)-particle Sutherland model**

Here, for the sake of completeness, we give a self-dual form of the Calogero–Sutherland model (trigonometric case of the CM) as it appeared in [10]. Then we give formulas for soliton reductions.

\(^6\) The matrix \( B \) is triangular in the basis of \( f^{(k)} \), \( k = 0, 1, \ldots, (N-M-1) \), defined by \( (f^{(k)})_i = (\tilde{z}_i)^k \).
The Calogero–Sutherland model describes particles on a circle interacting with inverse sine-squared (chord-distance) interactions

\[ H = \frac{1}{2} \sum_{j=1}^{N} p_j^2 + \frac{1}{2} \left( \frac{\pi}{L} \right)^2 \sum_{j,k=1, j \neq k}^{N} \frac{g^2}{\sqrt{\frac{\pi}{L} (x_j - x_k)}} \],

(C.1)

where \( L \) is the circumference of the circle. The positions and momenta of particles on a circle can be characterized by

\[ w_j = e^{2 \pi i x_j / L} \quad \text{and} \quad p_j = -i (L/2 \pi) \frac{\dot{w}_j}{w_j} \],

where \( 0 \leq x_j < L \).

The self-dual form of the Sutherland model analogous to (20), (21) is

\[ \frac{i \dot{w}_j}{w_j} = \frac{g}{2} \left( \frac{2 \pi}{L} \right)^2 \left( \sum_{k=1}^{M} \frac{w_j + u_k}{w_j - u_k} - \sum_{k=1}^{N} \frac{w_j + w_k}{w_j - w_k} \right), \]

(C.2)

\[ -\frac{i \dot{u}_j}{u_j} = \frac{g}{2} \left( \frac{2 \pi}{L} \right)^2 \left( \sum_{k=1}^{N} \frac{u_j + w_k}{u_j - w_k} - \sum_{k=1}^{M} \frac{u_j + u_k}{u_j - u_k} \right), \]

(C.3)

for \( M = N \). Here the ‘positions of solitons’ are labeled by the complex numbers \( u_j \) with \( |u_j| \neq 1 \). The finite-dimensional reductions of the Sutherland model, i.e. \( M \)-soliton solutions, are given by (C.2) and (C.3) with \( M < N \).

Taking the real and imaginary parts of (C.2), we obtain the following relations between soliton positions and the positions and momenta of particles:

\[ \sum_{k=1}^{N} \frac{w_j + w_k}{w_j - w_k} + \frac{1}{2} \sum_{k=1}^{M} \left( \frac{w_j + u_k}{w_j - u_k} + \frac{\frac{1}{w_j} + \frac{1}{u_k}}{\frac{1}{w_j} - \frac{1}{u_k}} \right) = 0, \]

(C.4)

\[ p_j = -\frac{\pi g}{2L} \sum_{k=1}^{M} \left( \frac{w_j + u_k}{w_j - u_k} - \frac{\frac{1}{w_j} + \frac{1}{u_k}}{\frac{1}{w_j} - \frac{1}{u_k}} \right). \]

(C.5)

Here we used that \( \bar{w}_j = w_j^{-1} \) for particles on a circle. The static solution is obtained for \( M = 0 \). It is easy to check that up to translation, it is given by \( p_j = 0, x_j = jL/N \) (or \( w_j = e^{i \frac{2 \pi j}{N}} \)).

Appendix D. Soliton reduction of the CM (rational case)

Here we discuss how the soliton reduction can be implemented for the rational Calogero–Moser system or the CM. This model is given by Hamiltonian (1) with \( \omega = 0 \). It can be written in a self-dual form by taking \( \omega = 0 \) in (20) and (21). Then an \( M \)-soliton reduction can be obtained by taking \( M < N \) in (20) and (21). Although this reduction is well defined for a complexified system, applying it to the original real CM, we run into the following difficulty. The real equations (26) do not have solutions for \( M < N \) if \( \omega = 0 \). It is easy to understand from the electrostatic interpretation. Indeed, it is not possible to keep \( N \) repelling charges within some finite interval on a line using the negative charge \( M < N \) in the absence of an additional harmonic potential (see (28) with \( \omega = 0 \)). We show here how to overcome this difficulty and obtain an \( M \)-soliton reduction for the CM.

Let us consider the following change of variables:

\[ x'_j = \frac{x_j}{\cos(\omega t)}, \]

(D.1)

\[ \omega t' = \tan(\omega t). \]

(D.2)
It is known that this transformation ‘removes harmonic potential’ [3]. Namely, if \( x_j(t) \) is a solution of the hCM, the transformed functions \( x'_j(t') \) defined by (D.1) and (D.2) give a solution of the CM.

It is clear that an \( M \)-soliton reduction of the hCM gives through the change of variables (D.1) and (D.2) a corresponding reduction of the CM.

Let us apply the change of variables (D.1) and (D.2) to the self-dual form of the hCM (20), (21). We obtain

\[
\dot{x}'_j = \frac{1 \omega x'_j}{1 + i \omega t'} = -ig \sum_{k=1(k \neq j)}^N \frac{1}{x'_j - x'_k} + ig \sum_{n=1}^M \frac{1}{x'_j - z'_n},
\]

\[
\dot{z}'_n = \frac{1 \omega z'_n}{1 + i \omega t'} = ig \sum_{m=1(m \neq n)}^M \frac{1}{z'_n - z'_m} - ig \sum_{j=1}^N \frac{1}{z'_n - x'_j},
\]

where we also changed \( z_n \rightarrow z'_n \) similar to (D.1). We consider (D.3), (D.4) as a modified or deformed self-dual form of the CM. \( \omega \) is just a parameter of the deformation (there is no time scale \( \omega \) in the CM). At the value \( \omega = 0 \), equations (D.3) and (D.4) give an unmodified self-dual form of the CM. At \( \omega = 0 \), there are no real solutions \( x_j(t) \) for \( M < N \) as was explained above. However, for \( \omega \neq 0 \) one obtains all soliton reductions corresponding to the ones for the hCM. The obtained soliton solutions will have an explicit time dependence additional to the time dependence of the parameters \( z_n(t) \).

Before giving an example of the reduction, we stress that excluding \( z_n \)’s from (D.3) and (D.4) one arrives to the system of second-order differential equations for the CM. The parameter \( \omega \) does not enter these equations. Similarly, excluding \( x_j \)’s one finds that the parameters \( z_n(t) \) form a dual CM, that is, also move according to CM equations.

Let us consider the simplest example of soliton solutions for the CM. Namely, we consider the \( M = 0 \)-soliton reduction of the rational CM corresponding to a static (background) solution of hCM (30). This solution is mapped to

\[
x'_j(t') = \frac{\gamma}{\omega} \sqrt{h_j \sqrt{1 + \omega^2 t'^2}}.
\]

This equation gives a zero-dimensional reduction of the CM system. It is easy to check that, indeed, (D.5) solves (D.3) for \( M = 0 \). The parameter \( \omega \) enters the initial conditions (\( t' = 0 \)) of (D.5) and defines the time scale. The limit \( \omega \rightarrow 0 \) is singular and does not correspond to a physical solution of the CM. In this appendix, we showed that the soliton reduction of the rational CM can be implemented via mapping the soliton solutions of the hCM onto the solutions of the CM using (D.1) and (D.2). The same kind of mapping can be done between two hCM with different frequencies which will result in new soliton solutions that will have additional explicit time dependence.

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