DISCOVERY OF A DISSOCIATIVE GALAXY CLUSTER MERGER WITH LARGE PHYSICAL SEPARATION

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Received 2011 October 19; accepted 2012 February 13; published 2012 February 24

ABSTRACT

We present DLSCL J0916.2+2951 (z = 0.53), a newly discovered major cluster merger in which the collisional cluster gas has become dissociated from the collisionless galaxies and dark matter (DM). We identified the cluster using optical and weak-lensing observations as part of the Deep Lens Survey. Our follow-up observations with Keck, Subaru, Hubble Space Telescope, and Chandra show that the cluster is a dissociative merger and constrain the DM self-interaction cross-section \( \sigma_{\text{DM}} \mu_{\text{DM}}^2 \lesssim 7 \, \text{cm}^2 \, \text{g}^{-1} \). The system is observed at least 0.7 ± 0.2 Gyr since first pass-through, thus providing a picture of cluster mergers 2–5 times further progressed than similar systems observed to date. This improved temporal leverage has implications for our understanding of merging clusters and their impact on galaxy evolution.

Key words: cosmic background radiation – dark matter – galaxies: clusters: individual (DLSCL J0916.2+2951) – gravitational lensing: weak – X-rays: galaxies: clusters

Online-only material: color figure

1. INTRODUCTION

During a major galaxy cluster merger the collisionless dark matter (DM) and galaxies become dissociated from the cluster gas (the principal baryonic component), a process that is observable for ~2 Gyr (Ricker & Sarazin 2001). These mergers have become important astrophysical probes providing a diagnostic of large-scale structure formation, empirical evidence favoring DM over modified gravity (Clowe et al. 2006), constraints on the DM self-interaction cross-section (Markevitch et al. 2004), and constraints on the large-scale matter–antimatter ratio (Steigman 2008). They are also a suspected source of extremely energetic cosmic rays (van Weeren et al. 2010). A special subclass of mergers are probes of all the aforementioned science. Such mergers (1) are between two subclusters of comparable mass, (2) have a small impact parameter, (3) are observed during the short period when the cluster gas is significantly offset from the galaxies and DM, and (4) occur mostly transverse to the line of sight so that the apparent angular separation of the cluster gas from the galaxies and DM is maximized. We term these systems dissociative mergers. Given these requirements it is not surprising that only six such systems have been confirmed: 1E 0576-56 (Clowe et al. 2006), MACS J0025.4-1222 (Bradac et al. 2008), A520 (Mahdavi et al. 2007; Okabe & Umetsu 2008), A2744 (Merten et al. 2011), A2163 (Okabe et al. 2011), and A1758 (Raguzzine et al. 2012). With such a small sample, which only probes a narrow temporal window (~0.17–0.25 Gyr post-collision\(^5\)), it is not surprising that we still do not completely understand merging systems. For example, Mahdavi et al. (2007) and Jee et al. (2012) find a “DM core” coincident with X-rays but not with any bright cluster galaxies in the merging system A520, and Merten et al. (2011) find a “ghost” clump of gas leading a DM clump in A2744; there is no accepted explanation for either of these observations. Simulations are needed to provide insight into these mysteries, but hydrodynamic simulations are complex and many assumptions are required (see, e.g., Springel & Farrar 2007; Poole et al. 2006); therefore, observations of new and different systems will play a crucial role in building confidence in these simulations.

We have identified a new dissociative merger, DLSCL J0916.2+2951, that probes an unexplored area of merger phase space. We originally detected the cluster in the Deep Lens Survey (DLS; Wittman et al. 2002) via its weak-lensing (WL) shear signal. It consists of two main subclusters spectroscopically confirmed to be at the same redshift (0.53). This cluster was also observed in the Sunyaev–Zel’dovich Array Survey (Muchovej et al. 2011) which provided evidence that the cluster gas is dissociated from the bulk of the mass and galaxies. Follow-up optical observations with Subaru and Hubble Space Telescope (HST) enable higher resolution mass maps and follow-up X-ray observations with Chandra ACIS-I confirm that the majority of the gas is offset between the north and south subclusters, the signature of a dissociative merger (Figure 1).

In this Letter, we introduce DLSCL J0916.2+2951 and summarize our survey of its three dominant components (galaxies, DM, and gas) and the cluster’s astrophysical implications. A more thorough exposition of the survey and analysis will be presented in W. A. Dawson et al. (2012, in preparation). Throughout this Letter we assume \( \Omega_\Lambda = 0.7 \), \( \Omega_m = 0.3 \), and \( H = 70 \, \text{km} \, \text{s}^{-1} \, \text{Mpc}^{-1} \).

2. OPTICAL ANALYSIS

We obtained spectroscopic redshifts for 20 cluster members with Keck LRIS (2007 January 16) and 634 unique spectroscopic redshifts (0 < z < 1.2) in a ~15′ × 15′ area centered on the cluster with Keck DEIMOS (2011 March 2–3), including 132 members at the cluster redshift. We reduced the LRIS spectra using a...
Dawson et al.

Figure 1. Merging cluster DLSCL J0916.2+2951 and its three matter components. Overlaid on the HST color image of the galaxies is the total mass distribution (blue) based on WL analysis of the HST images and the cluster gas distribution (red) based on Chandra X-ray observations. The bulk of the collisional gas is located between the two collisionless galaxy and mass concentrations, indicative of a dissociative merger. The image is 5′ × 5′ (∼1.9 × 1.9 Mpc at $z = 0.53$).

scripted sequence of standard IRAF reduction tasks, and the DEIMOS spectra using a modified version of the DEEP2 spec2d package (Davis et al. 2003; Gal et al. 2008; Lemaux et al. 2009).

We use our full sample of 654 spectroscopic redshifts as well as photometric redshifts to identify potential line-of-sight structures which may confuse our results. We find no evidence for significant line-of-sight structure (Figure 2).

We estimate each subcluster’s redshift and velocity dispersion (Table 1) using the biweight-statistic and bias-corrected 68% confidence limits (Beers et al. 1990) applied to 100,000 bootstrap samples of each subcluster’s spectroscopic redshifts. Our redshift estimates indicate a line-of-sight velocity difference of $v_{\text{los}} = 670^{+270}_{-130}$ km s$^{-1}$ between the north and south subclusters, using the galaxies within a 0.5 Mpc radius centered on the HST WL mass peaks and within a velocity range of ±3000 km s$^{-1}$ of $z = 0.53$ (~3× the expected velocity dispersion), corresponding to 38 and 35 galaxies for the north and south subclusters, respectively. These results are robust against varying the velocity range ±1000 km s$^{-1}$ and using the Subaru WL or galaxy number density peaks as the apertures’ centers, provided the aperture radius is ≤0.5 Mpc: larger radii lead to significant subcluster membership confusion. Additionally, we report the velocity dispersion mass estimates based on the scaling relation of Evrard et al. (2008) in Table 1.

We obtained $B, V, R,$ and $z'$ photometric data (12, 12, 18, and 12 ks, respectively) with Mosaic 1 on the KPNO 4 m Mayall telescope as part of the DLS. To improve the accuracy of our photometric redshifts we also observed the cluster in three medium-width optical bands ($g$, $h$, and $i$ from the BATC filter set), bracketing the redshifted 4000 Å feature, using the upgraded Mosaic 1.1 imager on the KPNO Mayall with exposure times of 6 ks per filter (2011 April 22–24). We estimate colors using ColorPro (Coe et al. 2006) and redshifts using BPZ (Benítez 2000). We replace the standard templates with a set “tweaked” in a method similar to that described in Ilbert et al. (2006), using spectroscopic samples from SHELS (Geller et al. 2005) and the PRIMUS survey (Coil et al. 2011) which overlap the DLS. Figure 2 shows the density isopleths of galaxies with $0.43 < z_{\text{phot}} < 0.63$ (roughly the cluster redshift ±σ$_{z_{\text{phot}}}$). This map agrees well with the distribution of spectroscopically confirmed cluster members.

3. WEAK-LENSING ANALYSIS

To map the total mass distribution we use a version of the Fischer & Tyson (1997) method modified to include a novel tomographic signal-matched filter. The cluster’s WL shear...
signal, γ, depends not only on the projected surface mass overdensity of the cluster, ΔΣ, but also on the relative distances of the observer, the mass, and the background galaxies:

\[ \gamma = \frac{\Delta \Sigma}{\Sigma_{cr}} = \frac{\Delta \Sigma 4\pi G D_{ls}(z_l, z_s) D_{ls}(z_s)}{c^2} \frac{D_{ls}(z_s)}{D_{ls}(z_l)} \left( \frac{z_s}{z_l} - 1 \right), \]

where \( \Sigma_{cr} \) is the critical surface density, \( H \) is the Heaviside step function, and \( D_l, D_s, \) and \( D_{ls} \) are the angular diameter distances to the lens, source, and between the lens and source, respectively.

Since we do not have exact redshift measurements of the source galaxies we use each galaxy’s photometric redshift probability distribution function, \( p(z) \), to estimate a respective \( \Sigma_{cr} \) for a given lens redshift,

\[ \Sigma_{cr}(z_l) \approx \langle \Sigma_{cr}(z_l) \rangle = \int \Sigma_{cr}(z_l, z_s) p(z_s) dz_s. \]

In addition to weights based on shape measurement errors, we also weight the shear of each galaxy based on its \( p(z) \),

\[ w_{\gamma}(z_l) = \frac{1}{\int [\Sigma_{cr}(z_l, z_s) - \langle \Sigma_{cr}(z_l) \rangle]^2 p(z_s) dz_s}. \]

This method increases the signal to noise of the measurement (see, e.g., Hennawi & Spergel 2005) and more accurately accounts for the errors inherent in the photometric redshift estimates, compared to single-point estimates. We estimate uncertainties using 100 bootstrap resamplings.

Encouraged by the DLS mass and galaxy maps, we obtained higher-resolution ground- and space-based observations. Subaru Suprime-Cam \( i'-\)band coverage of the cluster was provided by engineering-time observations of DLS Field 2 (2008 January 8). We use the Suprime-Cam data reduction software SDFRED (Yagi et al. 2002; Ouchi et al. 2004) followed by SCAMP and SWARP (Bertin et al. 2002; Bertin 2006) to refine the astrometry and make the final mosaic. DLSCL J0916.2+2951 was also observed with HST ACS/WFC using F606W and F814W filters (GO-12377, PI: W. Dawson) in a 2 × 1 pointing mosaic that covers the subclusters (Figure 1). The exposure times for F606W and F814W are 2520 s and 4947 s per pointing, respectively. We reduce these data following a method similar to that presented in Jee & Tyson (2009). We measure the point spread function (PSF) of both data sets using the Principal Component Analysis method presented in Jee et al. (2007).

We perform our WL analysis independently on both the Subaru and HST F814W data. The Subaru data have 0′72 seeing and 49 WL-quality source galaxies (i.e., background galaxies with measured ellipticity error <0.3) per arcmin\(^2\). For the mass map we use an apodizing kernel radius of 0′5, which can be interpreted as the effective resolution of the WL mass map. We are able to cross-match most of the detected objects with the DLS and use the \( p(z) \)'s discussed in the previous section.

Cross-matching is more problematic with the higher-resolution HST data, so we use a color–magnitude cut (F606W–F814W < 0.8 and 24 < F814W < 28.5) to select source galaxies and exclude cluster red sequence and bright foreground galaxies. For the WL analysis of the HST F814W image, which has a 0′1 PSF and 136 WL-quality source galaxies per arcmin\(^2\), we use an apodizing kernel radius of 3′6. We find no significant spatial correlation between source density and subcluster position, suggesting that our source galaxy population is not significantly contaminated with cluster galaxies. We estimate the \( p(z) \) of our HST source galaxy sample by assuming the photometric redshift distribution of the Coe et al. (2006) HUDF catalog after applying our color–magnitude cut. Figure 3 shows agreement between the Subaru and HST WL mass, and galaxy density maps.

We construct a joint catalog from the HST and Subaru data, using the HST data where available and Subaru for the surrounding area. Using a tomography-based MCMC analysis we simultaneously fit NFW halos centered on the north and south HST WL peaks, and use the Gelman & Rubin (1992) convergence test applied to eight independent chains. In order to reduce the number of free parameters we use the Duffy et al. (2008) empirical relation between \( M_{200} \) and concentration. We present the most likely masses for each halo along with the bias-corrected 68% confidence limits in Table 1. We also compare the integrated projected surface mass density of the NFW halos with the measured WL aperture mass (Fahlman et al. 1994) of each subcluster and find agreement within a radius of 0.5 Mpc of each subcluster.

### Table 1

| Subcluster | Redshift | \( \sigma_0 \) (km s\(^{-1}\)) | \( \sigma_0 \) M\(_{200} \) (10\(^{14}\) M\(_\odot\)) | WL M\(_{200} \) (10\(^{14}\) M\(_\odot\)) | \( L_{X_0,5-1keV} \) (10\(^{43}\) erg s\(^{-1}\)) | \( T_X \) (keV) | X-Ray S/\( N \) | Joint WL S/\( N \) |
|------------|---------|----------------|----------------|----------------|----------------|-------------|-------------|-------------|
| North      | 0.53074 | \( 1.000 \pm 0.001 \) | \( 740^{130}_{-190} \) | \( 3.7 \pm 2.3 \) | \( 1.7^{+0.6}_{-0.72} \) | 0.63 | ··· | 3.2 | 3.0 |
| South      | 0.53414 | \( 1.000 \pm 0.001 \) | \( 770^{110}_{-92} \) | \( 4.1 \pm 1.6 \) | \( 3.1^{+1.2}_{-0.79} \) | 2.1 | \( 2.7^{+1.2}_{-0.7} \) | 7.0 | 6.7 |
| Central    | ···      | ···             | ···             | ···             | ···             | 2.8 | \( 2.2^{+1.4}_{-0.6} \) | 9.1 | \(-3.3^a\) |

Note. \(^a\) The negative WL S/\( N \) indicates a projected surface mass local underdensity.

4. X-RAY ANALYSIS

We acquired X-ray spectral imaging of the cluster with 40 ks of Chandra ACIS-I time (GO-12800854), and reduce it using Ciao version 4.2 and CALDB version 4.4.1. We manually identify X-ray point sources and mask them before adaptively smoothing the diffuse emission; we present the resulting map in Figure 3. We estimate source counts and their error using the dmexct tool of CIAO. We use an 8′ radius background region which encloses the subcluster regions and rests ~90% on ACIS-I3 (on which the subclusters are observed); yet excludes subcluster, chip gaps, and point sources. For the south and central X-ray concentrations (120 ± 17 and 170 ± 19 detected 0.5–2 keV photons, respectively) we use the Xspec X-ray spectral fitting tool (Arnaud 1996) to fit a Mewe–Kaastra–Liedahl plus photoelectric absorption model (fixed to the Leiden/Argentine/Bonn value; Kalberla et al. 2005) to the X-ray spectrum of each X-ray concentration. For the north concentration there are not enough detected X-ray photons (38 ± 12) to fit a meaningful spectrum. We report the results of this analysis in Table 1.

5. CLUSTER MERGER SCENARIO

The peak of the gas distribution (09′16′′15′′ ± 5.5′′, 29′50′′59′′ ± 5.0′′) derived from X-rays is offset 1′4 ± 0.49 from...
the north HST WL mass peak (09:16\textquoteleft10\textquoteleft, 29:52\textquoteleft10\textquoteleft, 30\textquoteleft), and 1\textquoteleft4 ± 0\textquoteleft14 from the south HST WL mass peak (09:16\textquoteleft15\textquoteleft, 29:49\textquoteleft34\textquoteleft, 6\textquoteleft9), and is located near a local minimum in the mass, suggesting that the subclusters have a small impact parameter and have experienced at least their first pass-through along a north–northwest merger direction (see Figure 3). Further evidence for the merger scenario is provided by the morphology of the gas. Simulations (Schindler & Mueller 1993; Poole et al. 2006) predict that the gas morphology elongates transverse to the merger direction after pass-through for mergers with small impact parameters. The central gas concentration appears to be oblate and roughly perpendicular to the axis connecting the north and south mass peaks. This is consistent with the interpretation that these two subclusters have experienced their first pass-through and that the merger axis being roughly in the plane of the sky.

We gain further insight into the dynamics of the system by studying the spectroscopic redshifts of the subcluster galaxies. The observed line-of-sight velocity difference, \( v_{\text{los}}(t_{\text{observed}}) = 670\pm270\ \text{km s}^{-1} \), between the north and south subclusters does not explicitly determine the dynamics or orientation of the system since there is a degeneracy between the three-dimensional relative peculiar velocity, \( v_{\text{relative}} \), and angle of the pair with respect to the plane of the sky, \( \alpha \). In order to constrain this degeneracy we perform a Monte Carlo analysis of the system assuming the clusters to be uniform-density spheres with \( R_{200} \) radii. We draw randomly from each subcluster’s mass probability distribution as determined by the NFW MCMC analysis, the redshift distribution of the spectroscopic bootstrap analysis, and the centroid distribution as determined by the bootstrap sample of the HST WL mass map. From these parameters we calculate a conservative upper bound on the time-since-collision, \( t_{\text{relative}}(t_{\text{collision}}) \), by assuming that the two subclusters freely fell from an infinite separation and zero relative velocity yet began with their current mass. To determine a conservative lower bound we calculate \( t_{\text{relative}}(t_{\text{collision}}) \) assuming the subclusters had reached their observed separation with \( t_{\text{relative}}(t_{\text{observed}}) = 0 \). Implicit in our analysis is that the merger occurs with an impact parameter of zero. Including a moderate impact parameter of \( \sim0.1\ R_{200} \) should have less than a 1\% effect on the merger velocity (Mastropietro & Burkert 2008). As can be seen from Figure 4 the derived time-since-collision is relatively insensitive to moderate changes in \( t_{\text{relative}}(t_{\text{collision}}) \). For a consistency check we compare our analytic estimate of the Bullet Cluster’s time-since-collision with the numerical model results of Springel & Farrar (2007) and find agreement within 20\% (compare the square and diamond points of Figure 4). While we attempt to be conservative in our analysis, we disregard many complexities of the merger. Further insight will require deeper X-ray observations and/or hydrodynamic numerical simulations.

Using our analytic model we calculate that \( t_{\text{relative}}(t_{\text{collision}}) = 1700\pm500\ \text{km s}^{-1} \); given the sound speed of the gas \( \sim600\ \text{km s}^{-1} \), this corresponds to a Mach number of \( \sim3 \). With a projected separation of \( 1.0^{+0.11}_{-0.14} \) Mpc and estimated \( \alpha = 34^{+20}_{-14} \) degrees we find a physical separation of \( 1.3^{+0.18}_{-0.16} \) Mpc between the north and south subclusters. This is the largest physical offset for a dissociative merger observed to date. This translates into a time-since-collision \( (t_{\text{observed}}−t_{\text{collision}}) \) of \( 0.7^{+1.2}_{-0.9} \) Gyr. Given the collision velocities of the other dissociative mergers (Bradač et al. 2008; Markevitch et al. 2005; Springel & Farrar 2007; Merten et al. 2011) we calculate their times-since-collision using our analytic model and find that DLSCL J0916.2+2951 is probing a merger stage \( \gtrsim2−5 \) times further progressed than any other known dissociative merger (Figure 4).

6. DARK MATTER IMPLICATIONS

Given the evident merger scenario we are able to use the first method of Markevitch et al. (2004) and place a rough limit on the
Figure 4. Phase space of DLSCL J0916.2+2951 calculated from a Monte Carlo analytical treatment of the system assuming the clusters to be uniform-density spheres with $R_{200}$ radii. The measured velocities of the other mergers (with the exception of “Bullet SF07”; Bradac et al. 2008; Markovich et al. 2005; Springel & Farrar 2007; Merten et al. 2011) were input into the model to calculate their time-since-collision. It is clear that DLSCL J0916.2+2951 probes a significantly different epoch from the existing dissociative mergers. The close agreement between our analytical estimate, “Bullet Analytic,” and the $N$-body simulation (Springel & Farrar 2007), “Bullet SF07,” lends confidence to the results of our analytical treatment.

(A color version of this figure is available in the online journal.)

DM self-interaction cross-section, $\sigma_{DM}$. This method compares the scattering depth of the dark matter, $\tau_{DM} = \sigma_{DM} n_{DM} \Sigma_{DM}$, with that of the intracluster medium (ICM) gas, $\tau_{ICM} \approx 1$, where $n_{DM}$ is the DM particle mass and $\Sigma_{DM}$ is the surface mass density of the DM particles. $\Sigma_{DM}$ is approximately the WL measured surface mass density, $\Sigma$, since ~80% of a typical cluster’s mass is DM (Diaferio et al. 2008). For ease of comparison with the results of Markevitch et al. (2004) and Merten et al. (2011) we examine the surface density averaged over the face of the subcluster within $r = 125$ kpc, which is $\Sigma \approx 0.15 \, \text{g cm}^{-2}$; thus we find $\sigma_{DM} n_{DM} \lesssim 7 \, \text{cm}^{-2}$ g$^{-1}$. Note that we cannot apply the velocity-dependent $\sigma_{DM}$ constraint methods outlined by Markovich et al. (2004) since our analytic model assumes $\sigma_{DM} = 0$.

7. DISCUSSION

While we use DLSCL J0916.2+2951 to provide further evidence for the canonical DM model and independently constrain $\sigma_{DM} n_{DM}^{-1}$, we believe that its greatest value is as a probe for a new and special phase of cluster formation. It provides a greatly improved temporal lever arm with which to guide numerical simulations that explore the major merger phase. This is potentially important given that much of our knowledge of the cluster merger process comes from numerical hydrodynamic simulations (e.g., Poole et al. 2006), which are used to place the tightest constraints on $\sigma_{DM} n_{DM}^{-1} < 0.7 \, \text{cm}^{-2}$ g$^{-1}$; Randall et al. 2008) and bring observed merger velocities (inferred from the observed shock velocity) more in line with the expectations of $\Lambda$CDM (Springel & Farrar 2007; Lee & Komatsu 2010). Second, the large projected separation relative to the virial radii of the subclusters ($R_{200} \sim 1$ Mpc) enables the deconvolution of the subclusters from the central region and direct comparison of the physical properties of each. This will provide new insight into the behavior of the cluster constituents (gas, galaxies, and DM) during a major merger. For example, it is well established that galaxy clusters play an important role in the evolution of their member galaxies, but it is still unclear whether cluster mergers trigger star formation (e.g., Miller & Owen 2003; Owen et al. 2005; Ferrari et al. 2005; Hwang & Lee 2009), quench it (Poggianti et al. 2004), or have no immediate effect (Chung et al. 2010). This cluster, with its estimated time-since-collision approximately equal to the lifetime of A-stars, holds promise for discriminating between slow-working processes (e.g., galaxy harassment or strangulation) and fast-acting processes (e.g., ram pressure stripping).

We thank Daniel P. Marrone, Stephen Muchovej, John E. Carlstrom, and Tony Mroczkowski of the SZA collaboration for sharing the results of the SZA Survey, which helped motivate the detailed follow-up campaign of DLSCL J0916.2+2951. Support for this work was provided by NASA through Chandra Award Number GO1-12171X issued by CXO Center, which is operated by the SAO for and on behalf of NASA under contract NAS8-03060. Support for program number GO-12377 was provided by NASA through a grant from STScI, which is operated by the Association of Universities for Research in Astronomy, Inc., under NASA contract NAS5-26555.

Facilities: CXO (ACIS-I), HST (ACS), Keck:I (LRIS), Keck:II (DEIMOS), Mayall (MOSAIC 1 & 1.1), Subaru (Suprime-Cam), SZA

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