Nonlocal and multiple-point fractional boundary value problem in the frame of a generalized Hilfer derivative

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Abstract

The aim of this manuscript is to handle the nonlocal boundary value problem for a specific kind of nonlinear fractional differential equations involving a $\xi$-Hilfer derivative. The used fractional operator is generated by the kernel of the kind $k(\vartheta, s) = \xi(\vartheta) - \xi(s)$ and the operator of differentiation $D_\xi = \left(\frac{1}{\xi'(\vartheta)}\right)$. The existence and uniqueness of solutions are established for the considered system. Our perspective relies on the properties of the generalized Hilfer derivative and the implementation of Krasnoselskii’s fixed point approach and Banach’s contraction principle with respect to the Bielecki norm to obtain the uniqueness of solution on a bounded domain in a Banach space. Besides, we discuss the Ulam–Hyers stability criteria for the main fractional system. Finally, some examples are given to illustrate the viability of the main theories.

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1 Introduction

Fractional calculus (FC) was introduced at the end of the seventeenth century as a branch of mathematical analysis that deals with the examinations of various possibilities to term real (or complex) number powers of the integration (and differentiation) operators. FC is the generalization of ordinary calculus concerned with operations of integration (and differentiation) of noninteger order. Fractional differential equations (FDEs) including Caputo, Riemann–Liouville (RL), Hilfer, Hadamard, and Erdelyi–Kober fractional derivatives (FDs) have been used in different areas of technological disciplines and concentrated on by numerous mathematicians, see the books [1–5] and the references given therein. Recently, using the generalized Mittag-Leffler function, Atanga and Baleanu [6] suggested a new formulation of the fractional derivative with a nonlocal and nonsingular kernel. Atangana [7] introduced a new differentiation which combines fractal differentiation and fractional differentiation. Very recently,
another methodology of FDs having a general kernel with respect to another function
known as the ψ-Caputo and ψ-Hilfer operator has been introduced by Almeida [8] and
Sousa and Oliveira [9], respectively, drawing on the idea of Kilbas et al. [1, 3] and Agrawal
[10] who made some generalizations to fractional integrals and derivatives with respect to
another function. Jarad and Abdeljawad [11] presented interesting properties of general-
ized operator with another function, including the generalized Laplace transform. A few
specialists were as of late occupied with the advancement of ξ-Caputo (or ξ-Hilfer)-type
FDEs, see [12–25] and the references therein. Impressive considerations have been pro-
vided to the investigation of the Ulam–Hyers (UH) stability of a wide range of FDEs, see
[26–32].

In this regard, we investigate the existence, uniqueness, and UH stability of solutions for
the following nonlocal boundary value problem:

\[ D_{a^+}^{\rho_1,\rho_2;\xi}\theta = \mathcal{F}(\theta, z(\theta)), \quad \theta \in \mathcal{J} := [a, b], \] (1.1)

\[ z(a) = z_a + p(z), \quad z_\xi(b) = z_b + \sum_{i=1}^{m-2} \lambda_i z_\xi(\kappa_i), \] (1.2)

where \( z_\xi = z_\xi \) and \( D_{a^+}^{\rho_1,\rho_2;\xi} \) is the ξ-Hilfer FD of order \( \rho_1 \in (1, 2) \) and type \( \rho_2 \in [0, 1] \), \( z_a, z_b \in \mathbb{R} \), \( \lambda_i > 0 \), \( a < \xi_i < \kappa_i \), \( i = 1, 2, \ldots, m - 2 \), \( \sum_{i=1}^{m-2} \lambda_i z_\xi(\kappa_i) = d < 1 \), and \( \mathcal{F} : \mathcal{J} \times \mathbb{R} \to \mathbb{R} \) and \( p : C(\mathcal{J}, \mathbb{R}) \to \mathbb{R} \) are continuous.

**Remark 1.1** Our results for problem (1.1)–(1.2) remain true for the following cases:

- RL-type problem for \( \xi(\theta) = \theta \) and \( \rho_2 = 0 \).
- Caputo-type problem for \( \xi(\theta) = \theta \) and \( \rho_2 = 1 \).
- ξ-RL-type problem for \( \rho_2 = 0 \).
- ξ-Caputo-type problem for \( \rho_2 = 1 \).
- Hilfer-type problem for \( \xi(\theta) = \theta \).
- Hilfer–Hadamard-type problem for \( \xi(\theta) = \log \theta \).
- Katugampola-type problem for \( \xi(\theta) = \theta^p \).

**Remark 1.2** Results acquired for problem (1.1)–(1.2) include the results of Zhong and Lin
[33] and Asawasamrit et al. [34], in particular:

1. For \( \xi(\theta) = \theta \) and \( \rho_2 = 1 \), the outcomes obtained in the present work incorporate
   the results of Zhong and Lin [33] for Caputo-type nonlocal and multiple-point BVP.
2. If, in problem (1.1)–(1.2), \( \xi(\theta) = \theta \) and replacing conditions
   \[ z(a) = 0, z(b) = \sum_{i=1}^{m} \lambda_i z_\xi(\kappa_i) \] (1.2), then our current results cover the results of
   Asawasamrit et al. [34] for Hilfer nonlocal BVP.

The main contribution of the current work is to determine the equivalent fractional inte-
gral equation to ξ-Hilfer type FDEs (1.1)–(1.2) and to explore the existence and uniqueness
results. Further, we discuss the Ulam–Hyers stability result to such equations. Observe
that, with the above discussions, problem (1.1)–(1.2) not just incorporates the previously
specified BVPs in the literature, yet additionally nontrivially extends the status to a more
comprehensive class of nonlocal BVPs, i.e., for various values of \( \rho_2 \) and \( \xi \), our considered
problem covers the problems referenced in Remark 1.1. Consequently, problem (1.1)–(1.2) studied in this paper is novel and is the first to investigate fractional nonlocal problems of $\xi$-Hilfer type.

Here is a brief outline of the paper. Section 2 provides the definitions and preliminary facts that we will need for our forthcoming analysis. In Sect. 3, we prove the existence, uniqueness, and UH stability results for problem (1.1)–(1.2). Two examples are given in Sect. 5. This work closes with a conclusion.

2 Preliminaries

In this section, we give some notions regarding the fractional integrals and derivatives with respect to another function $\xi$. For more details, we refer to [1–3, 5].

Let $\mathcal{J} = [a, b] \subset \mathbb{R}$. Denote by $C := C(\mathcal{J}, \mathbb{R})$ the Banach space of continuous functions $\omega: \mathcal{J} \to \mathbb{R}$ with the norm

$$
\|\omega\|_\infty = \sup_{\theta \in \mathcal{J}} \{|\omega(\theta)|, \theta \in \mathcal{J}\}.
$$

Let $\xi, \omega \in C^n$ such that $\xi$ is increasing and $\xi'(\theta) \neq 0$ for all $\theta \in \mathcal{J}$.

**Definition 2.1** ([9]) The $\xi$-Hilfer FD of a function $\omega$ of order $\varrho_1 \in (n-1, n]$ and type $\varrho_2 \in [0, 1]$ is defined by

$$
D_{\alpha^+}^{\varrho_1, \varrho_2} \omega(\theta) = I_{\alpha^+}^{\varrho_2(n-\varrho_1)} D_{\xi} D_{\alpha^+}^{n(1-\varrho_2)(n-\varrho_1)} \omega(\theta),
$$

where $n = [\varrho_1] + 1, n \in \mathbb{N}$, and $D_{\xi} = \left(\frac{1}{\xi'(\theta)} \frac{d}{d\theta}\right)^n$. Relation (2.1) can be written as

$$
D_{\alpha^+}^{\varrho_1, \varrho_2} \omega(\theta) = I_{\alpha^+} I^{-\varrho_1, \varrho_2}_{\mathcal{J}_\alpha} D_{\alpha^+}^{\varrho_1, \varrho_2} \omega(\theta),
$$

with $\gamma = \varrho_1 + \varrho_2(n-\varrho_1)$, $I_{\alpha^+}^{\varrho_1, \varrho_2}_{\mathcal{J}_\alpha}(\cdot)$ and $D^{\varrho_1, \varrho_2}_{\alpha^+}(\cdot)$ are the $\xi$-RL fractional integral and derivative defined by (see [1])

$$
I_{\alpha^+}^{\varrho_1, \varrho_2}_{\mathcal{J}_\alpha}(\theta) = \frac{1}{\Gamma(\gamma)} \int_a^\theta \xi'(s)\left(\xi(\theta) - \xi(s)\right)^{\varrho_1-1} \omega(s) \, ds,
$$

and

$$
D^{\varrho_1, \varrho_2}_{\alpha^+}(\theta) = D_{\xi} D_{\alpha^+}^{\varrho_1, \varrho_2} \omega(\theta),
$$

respectively. Furthermore, the $\xi$-Caputo FD is given by (see [8])

$$
C D_{\alpha^+}^{\varrho_1, \varrho_2} \omega(\theta) = I_{\alpha^+}^{\varrho_1, \varrho_2}_{\mathcal{J}_\alpha} D_{\xi}^n \omega(\theta),
$$

where $\theta \in (\gamma - \varrho_1, \gamma, \varrho_1)$.

**Remark 2.2** If we set $\xi(\theta) = \theta$ in relations (2.1), (2.3), (2.4), and (2.5), we obtain the classical fractional operators introduced in [1, 5, 35].
Lemma 2.3 ([1, 9]) Let \( q_1, q_2 > 0 \) and \( \omega \in C \). Then

\[
\mathcal{T}_{a^+}^{q_1 \varepsilon} \mathcal{T}_{a^+}^{q_2 \varepsilon} \omega(\theta) = \mathcal{T}_{a^+}^{q_1 + q_2 \varepsilon} \omega(\theta)
\]

and

\[
\mathcal{D}_{a^+}^{q_1 \varepsilon} \mathcal{T}_{a^+}^{q_1 \varepsilon} \omega(\theta) = \omega(\theta).
\]

Lemma 2.4 ([1, 9]) Let \( q_1, q_2 > 0 \) and \( \delta > 0 \). If \( \psi(\theta) := (\xi(\theta) - \xi(a))^{\delta-1} \), then

1. \( \mathcal{T}_{a^+}^{q_1 \varepsilon} \psi(\theta) = \frac{\Gamma(\delta)}{\Gamma(q_1+\delta)} (\xi(\theta) - \xi(a))^{q_1+\delta-1} \),
2. \( \mathcal{D}_{a^+}^{q_1 \varepsilon} \psi(\theta) = \frac{\Gamma(\delta)}{\Gamma(q_1+\delta)} (\xi(\theta) - \xi(a))^{q_1+\delta-1}, \delta > \gamma = q_1 + q_2(n-q_1); \)
3. \( \mathcal{T}_{a^+}^{q_1 \varepsilon} \psi(\theta) = 0 \) for \( \delta = \gamma \).

Lemma 2.5 ([9]) Let \( q_1 \in (n-1, n) \) \((n \in \mathbb{N})\), \( q_2 \in [0, 1] \) with \( \gamma = q_1 + q_2(n-q_1) \) and \( \omega \in C^n \). Then

\[
(\mathcal{T}_{a^+}^{q_1 \varepsilon} \mathcal{D}_{a^+}^{q_1 \varepsilon} \omega)(\theta) = \omega(\theta) - \sum_{k=1}^{n} \frac{(\xi(\theta) - \xi(a))^{\gamma-k}}{\Gamma(\gamma-k+1)} D_{a^+}^{\gamma-k \varepsilon} \omega(\theta).
\]

In particular, if \( 1 < q_1 \leq 2, 0 \leq q_2 \leq 1 \), where \( \gamma = q_1 + q_2(2-q_1) \), then

\[
(\mathcal{T}_{a^+}^{q_1 \varepsilon} \mathcal{D}_{a^+}^{q_1 \varepsilon} \omega)(\theta) = \omega(\theta) - \frac{(\xi(\theta) - \xi(a))^{\gamma-1}}{\Gamma(\gamma)} (\mathcal{T}_{a^+}^{1-q_1 \varepsilon} \omega(a))
\]

\[
- \frac{(\xi(\theta) - \xi(a))^{\gamma-2}}{\Gamma(\gamma-1)} (\mathcal{T}_{a^+}^{2-q_1 \varepsilon} \omega(a)).
\]

Lemma 2.6 ([1]) Let \( n-1 \leq q_1 < n \) and \( \omega \in C \). Then

\[
(\mathcal{T}_{a^+}^{q_1 \varepsilon} \omega)(a) = \lim_{\theta \to a^+} (\mathcal{T}_{a^+}^{q_1 \varepsilon} \omega)(\theta) = 0.
\]

Lemma 2.7 Let \( q_1, \theta > 0 \). Then, for all \( \theta \in \mathcal{F} \), we have

\[
\mathcal{T}_{a^+}^{q_1 \varepsilon} e^{\beta(\xi(\theta) - \xi(a))} \leq \frac{e^{\beta(\xi(\theta) - \xi(a))}}{\theta^{q_1}}.
\]

Proof From equation (2.3), we have

\[
\mathcal{T}_{a^+}^{q_1 \varepsilon} e^{\beta(\xi(\theta) - \xi(a))} = \frac{1}{\Gamma(q_1)} \int_{a}^{\theta} \xi'(s)(\xi(\theta) - \xi(a))^{q_1-1} e^{\beta(\xi(s) - \xi(a))} ds.
\]

By utilizing the change of variables \( y = \xi(\theta) - \xi(s) \), we obtain

\[
\mathcal{T}_{a^+}^{q_1 \varepsilon} e^{\beta(\xi(\theta) - \xi(a))} = \frac{e^{\beta(\xi(\theta) - \xi(a))}}{\Gamma(q_1)} \int_{0}^{\xi(\theta) - \xi(a)} y^{q_1-1} e^{-\beta y} dy.
\]
Again, by utilizing the change of variables \( v = \theta y \) in (2.6), we attain
\[
T_a^{\varrho_1, \xi} e^{\varrho \xi (\theta) - \xi (a)} = \frac{e^{\varrho \xi (\theta) - \xi (a)}}{\Gamma(\varrho_1) \varrho_1} \int_0^{\varrho_1} v^{\varrho_1 - 1} e^{-v} dv \\
\leq \frac{e^{\varrho \xi (\theta) - \xi (a)}}{\Gamma(\varrho_1) \varrho_1} \int_0^{\infty} v^{\varrho_1 - 1} e^{-v} dv \\
= \frac{e^{\varrho \xi (\theta) - \xi (a)}}{\theta \varrho_1}.
\]

This completes the proof. \(\Box\)

Let us now conclude this section by recalling the following fixed point theorems.

**Theorem 2.8** (Banach [36]) Let \( E \) be a nonempty closed subset of a Banach space \( X \) and \( \mathcal{H} : E \to E \) be a strict contraction mapping, i.e., \( \|\mathcal{H}z - \mathcal{H}y\| \leq k\|z - y\| \) for all \( z, y \in E \) and for some \( k \in (0, 1) \). Then \( \mathcal{H} \) possesses a unique fixed point.

**Theorem 2.9** (Krasnoselskii [37]) Let \( X \) be a Banach space. Let \( S \) be a nonempty convex, closed, and bounded subset of \( X \), and let \( \mathcal{H}_1, \mathcal{H}_2 \) be mappings from \( S \) to \( X \) such that:

(i) \( \mathcal{H}_1 z + \mathcal{H}_2 y \in S \) whenever \( z, y \in S \);

(ii) \( \mathcal{H}_1 \) is continuous and compact;

(iii) \( \mathcal{H}_2 \) is a strict contraction. Then there exists \( z \in S \) such that \( z = \mathcal{H}_1 z + \mathcal{H}_2 z \).

## 3 Main result

The next lemma transacts with a linear form associated with problem (1.1)--(1.2).

**Lemma 3.1** Let \( 1 < \varrho_1 \leq 2, 0 < \varrho_2 \leq 1 \), where \( \gamma = \varrho_1 + \varrho_2(2 - \varrho_1) \) and \( h \in C \). If
\[
A = \left[ \frac{[\xi (b) - \xi (a)]^{\gamma - 2}}{\Gamma(\gamma - 1)} - \sum_{i=1}^{m-2} \frac{\xi' (\sigma_i) - \xi (a))^{\gamma - 2}}{\Gamma(\gamma - 1)} \right] \neq 0, \tag{3.1}
\]

then the function \( z \in C \) is a solution of the linear-type problem
\[
\begin{cases}
D_a^{\varrho_1, \varrho_2} z (\theta) = h (\theta), & \theta \in (1, 2), \ \theta \in \mathcal{J} := [a, b], \\
z (a) = z_a + p (z), & z'_b = z_b + \sum_{i=1}^{m-2} \lambda_i z'_i (\sigma_i) \tag{3.2}
\end{cases}
\]

if and only if
\[
z (\theta) = T_a^{\varrho_1, \varrho_2} h (\theta) + \frac{[\xi (\theta) - \xi (a))^{\gamma - 1}}{A \Gamma(\gamma)} \left[ z_b + T_a^{\varrho_1, \varrho_2} h (b) + \sum_{i=1}^{m-2} \lambda_i T_a^{\varrho_1, \varrho_2} h (\sigma_i) \right] \\
+ \frac{[z_a + p (z)]}{A} \left[ \frac{[\xi (b) - \xi (a))]^{\gamma - 3} + \sum_{i=1}^{m-2} \lambda_i [\xi (\sigma_i) - \xi (a))]^{\gamma - 3}}{\Gamma(\gamma - 1)} \right] \\
+ \frac{[\xi (\theta) - \xi (a))]^{\gamma - 2}}{\Gamma(\gamma - 1)} \right] \tag{3.3}
\]

**Proof** The first equation of (3.2) can be written as
\[
T_a^{\varrho_1, \varrho_2} D_a^{\varrho_1, \varrho_2} T_a^{\varrho_1, \varrho_2} z (\theta) = h (\theta).
\]
Applying the operator $T_a^{0;1\xi}$, we get

$$T_a^{0;1\xi} T_a^{(-1)\xi} T_a^\xi \varphi = T_a^{0;1\xi} h(\theta),$$

which implies

$$T_a^{\gamma\xi} T_a^\xi z(\theta) = T_a^{0;1\xi} h(\theta), \quad \gamma = \varphi_1 + \varphi_2(2 - \varphi_1).$$

By Lemma 2.5 and setting $I_a^{2-\gamma\xi} z(a) = c_1$, $I_a^{1-\gamma\xi} z(a) = c_2$, we have

$$z(\theta) = \frac{c_2}{\Gamma(\gamma)} \left[ (\xi(\theta) - \xi(a))^{-\gamma - 1} + \frac{c_1}{\Gamma(\gamma - 1)} \left[ (\xi(\theta) - \xi(a))^{-\gamma - 2} + I_a^{0;1\xi} h(\theta) \right] \right].$$

(3.4)

Differentiation of (3.4) with the fact that $D_a^{\xi} T_a^{\gamma\xi} T_a^{\sigma\xi} = T_a^{\sigma-k\xi}$ for $k = 0, 1, \ldots, n - 1$, $\sigma > k$ (see [12]) leads to

$$z^{(\xi)}(\theta) = \frac{z^{(\xi)}(\theta)}{\xi^{(\xi)}(\theta)} = \frac{c_2}{\Gamma(\gamma)} \left[ (\xi(\theta) - \xi(a))^{-\gamma - 2} + \frac{c_1}{\Gamma(\gamma - 1)} \left[ (\xi(\theta) - \xi(a))^{-\gamma - 3} + I_a^{0;1\xi} h(\theta) \right] \right].$$

From the boundary conditions of (3.2), we obtain $c_1 = z_a + \varphi(z)$ and

$$\frac{c_2}{\Gamma(\gamma - 1)} \left[ (\xi(b) - \xi(a))^{-\gamma - 2} + \frac{[z_a + \varphi(z)]}{\Gamma(\gamma - 2)} \left[ (\xi(b) - \xi(a))^{-\gamma - 3} + I_a^{0;1\xi} h(b) \right] \right]
= z_b + \sum_{i=1}^{m-2} \lambda_i \left[ \frac{c_2}{\Gamma(\gamma)} \left[ (\xi(\xi_i) - \xi(a))^{-\gamma - 2} + \frac{[z_a + \varphi(z)]}{\Gamma(\gamma - 2)} \left[ (\xi(\xi_i) - \xi(a))^{-\gamma - 3} + I_a^{0;1\xi} h(\xi_i) \right] \right] \right] + I_a^{0;1\xi} h(\xi_0) + I_a^{0;1\xi} h(\xi_1) + \cdots + I_a^{0;1\xi} h(\xi_{m-2}).$$

It follows that

$$c_2 \left[ \frac{[\xi(b) - \xi(a)]^{-\gamma - 2}}{\Gamma(\gamma - 1)} - \sum_{i=1}^{m-2} \lambda_i \left[ (\xi(\xi_i) - \xi(a))^{-\gamma - 2} \right] \right]
= \frac{[z_a + \varphi(z)]}{\Gamma(\gamma - 2)} \sum_{i=1}^{m-2} \lambda_i \left[ (\xi(\xi_i) - \xi(a))^{-\gamma - 3} - [\xi(b) - \xi(a)]^{-\gamma - 3} \right]
+ z_b + \sum_{i=1}^{m-2} \lambda_i I_a^{0;1\xi} h(\xi_i) - I_a^{0;1\xi} h(b).$$

Therefore,

$$c_2 = \frac{1}{A} \left[ z_b + \sum_{i=1}^{m-2} \lambda_i I_a^{0;1\xi} h(\xi_i) - I_a^{0;1\xi} h(b)
+ \frac{[z_a + \varphi(z)]}{\Gamma(\gamma - 2)} \left( \sum_{i=1}^{m-2} \lambda_i [ (\xi(\xi_i) - \xi(a))^{-\gamma - 3} - [\xi(b) - \xi(a)]^{-\gamma - 3} \right) \right].$$
Substituting the values of \( c_1, c_2 \) into (3.4), we get

\[
z(\theta) = T_{a^+}^{\theta^+} h(\theta) + \frac{[\xi(\theta) - \xi(a)]^{p_1-1}}{A \Gamma(p_1)} \left[ z_b + \sum_{i=1}^{m-2} \lambda_i \mathcal{I}_{a^+}^{\theta_{i+1}^+} h(x_i) - \mathcal{I}_{a^+}^{\theta_{i+1}^+} h(b) \right] + \frac{[\xi(\theta) - \xi(a)]^{p_2-2}}{A \Gamma(p_2)} \left[ z_a + \sum_{i=1}^{m-2} \lambda_i \mathcal{I}_{a^+}^{\theta_{i+1}^+} [\xi(x_i) - \xi(a)]^{\gamma-2} - [\xi(b) - \xi(a)]^{\gamma-3} \right] \frac{[\xi(\theta) - \xi(a)]^{p_2-2}}{A \Gamma(p_2)} \left[ z_a + \sum_{i=1}^{m-2} \lambda_i \mathcal{I}_{a^+}^{\theta_{i+1}^+} [\xi(x_i) - \xi(a)]^{\gamma-2} - [\xi(b) - \xi(a)]^{\gamma-3} \right]
\]

(3.5)

Note that

\[
\mathcal{I}_{a^+}^{\theta^+} h(\theta) = \frac{1}{\Gamma(\theta)} \int_{a^+}^{x} \frac{[\xi'(s) - \xi(s)]^{\gamma-1} h(s)}{s^{\gamma-2}} ds, \quad \theta \in [q_1, q_1 - 1], \quad \text{and} \quad x \in [a^+, b, x_i].
\]

The converse follows by direct calculation with the aid of the results in Lemmas 2.4, 2.5. This finishes the proof. \( \square \)

To follow up, we need the following assumptions.

(G1) \( \mathcal{F} : \mathcal{J} \times \mathcal{R} \to \mathcal{R} \) and \( \mathcal{P} : \mathcal{C} \to \mathcal{R} \) are continuous.

(G2) There exist constants \( \mathcal{L}_1, \mathcal{L}_2 > 0 \) such that

\[
|\mathcal{F}(\theta, z) - \mathcal{F}(\theta, \bar{z})| \leq \mathcal{L}_1 |z - \bar{z}|, \quad z, \bar{z} \in \mathcal{R},
\]

and

\[
|\mathcal{P}(z) - \mathcal{P}(\bar{z})| \leq \mathcal{L}_2 |z - \bar{z}|, \quad z, \bar{z} \in \mathcal{C}.
\]

(G3) There exist positive functions \( \psi, \phi \) with bounds \( \|\psi\| \) and \( \|\phi\| \), respectively, such that:

\[
|\mathcal{F}(\theta, z)| \leq \psi(\theta), \quad \forall (\theta, z) \in \mathcal{J} \times \mathcal{R},
\]

\[
|\mathcal{P}(z)| \leq \phi(\theta), \quad \forall (\theta, z) \in \mathcal{J} \times \mathcal{C}.
\]

For simplicity, we denote

\[
\mathcal{M} := \sup_{\theta \in [a, b]} |\mathcal{F}(\theta, 0)|, \quad |\mathcal{P}(0)| := p_0,
\]

\[
\Delta := \mathcal{L}_1 \left( \frac{(\xi(b) - \xi(a))^{\psi_1}}{\Gamma(q_1 + 1)} + \frac{[\xi(b) - \xi(a)]^{\gamma-1}}{A \Gamma(p_1)} \left[ \xi(b) - \xi(a) \right]^{\gamma-2} \right)
\]

\[
\times \left[ \frac{[\xi(b) - \xi(a)]^{\gamma-2}}{\Gamma(q_1)} + \sum_{i=1}^{m-2} \lambda_i \frac{[\xi(x_i) - \xi(a)]^{\gamma-1}}{\Gamma(q_1)} \right] \left[ \xi(b) - \xi(a) \right]^{\gamma-2} \frac{[\xi(b) - \xi(a)]^{\gamma-3}}{A \Gamma(p_2)} \left[ \xi(b) - \xi(a) \right]^{\gamma-2} \right)
\]

\[
\mathcal{L}_2 \left[ \frac{[\xi(b) - \xi(a)]^{\gamma-3}}{A \Gamma(p_2)} \left[ \xi(b) - \xi(a) \right]^{\gamma-2} + \sum_{i=1}^{m-2} \lambda_i \frac{[\xi(x_i) - \xi(a)]^{\gamma-3}}{\Gamma(q_1)} \right] \left[ \xi(b) - \xi(a) \right]^{\gamma-2} \frac{[\xi(b) - \xi(a)]^{\gamma-3}}{A \Gamma(p_2)} \left[ \xi(b) - \xi(a) \right]^{\gamma-2} \right)
\]

(3.6)

\[
\Theta := \mathcal{L}_1 \left( \frac{(\xi(b) - \xi(a))^{\psi_1}}{\Gamma(p_1)} \left[ \xi(b) - \xi(a) \right]^{\gamma-1} \right)
\]

\[
\times \left[ \frac{[\xi(b) - \xi(a)]^{\gamma-1}}{\Gamma(p_1)} + \sum_{i=1}^{m-2} \lambda_i \frac{[\xi(x_i) - \xi(a)]^{\gamma-1}}{\Gamma(q_1)} \right] \left[ \xi(b) - \xi(a) \right]^{\gamma-1} \frac{[\xi(b) - \xi(a)]^{\gamma-2}}{A \Gamma(p_2)} \left[ \xi(b) - \xi(a) \right]^{\gamma-2} \right)
\]
solves system (1.1)–(1.2).

According to Lemma 3.1, we consider the operator

$$\mu(\theta) := \frac{[\xi(\theta) - \xi(a)]^{\gamma-1}}{A(\gamma-2)} \Gamma(\gamma)$$

$$v(\theta) := \frac{[\xi(b) - \xi(a)]^{\gamma-3}}{A(\gamma-2)} \Gamma(\gamma) + \frac{[\xi(\theta) - \xi(a)]^{\gamma-2}}{A(\gamma-1)}$$

$$\Lambda_1 := \left[ \frac{[\xi(b) - \xi(a)]^{\gamma-1}}{\Gamma(\gamma-1)} + \mu^* \left( \frac{[\xi(b) - \xi(a)]^{\gamma-1}}{\Gamma(\gamma-1)} + \sum_{i=1}^{m-2} \lambda_i \frac{[\xi(\theta) - \xi(\alpha)]^{\gamma-1}}{\Gamma(\gamma-1)} \right) \right]$$

$$\Lambda_2 := v^*, \quad \Lambda_3 := \mu^* |z_b| + v^* |z_a|,$$

$$G^*_s(\theta, s) = \frac{\xi'(s)(\xi(s) - \xi(s))^{\gamma-1}}{\Gamma(\chi)}$$

$$\mu^* = \max_{0 \leq \theta \leq b} |\mu(\theta)|,$$

$$v^* = \max_{0 \leq \theta \leq b} |v(\theta)|.$$

In what follows, we present the needful lemma that represents the equivalent solution to problem (1.1)–(1.2).

**Lemma 3.2** Assume that \(F : J \times \mathbb{R} \rightarrow \mathbb{R}, p : C \rightarrow \mathbb{R}\) are continuous. A function \(z(\theta)\) solves system (1.1)–(1.2) if and only if it is a fixed point of the operator \(H : C \rightarrow C\) defined by

$$Hz(\theta) = F_0^{\alpha_1, \gamma} F(\theta, z(\theta)) + \mu(\theta) \left[ z_b + F_0^{\alpha_1, \gamma} F(b, z(b)) + \sum_{i=1}^{m-2} \lambda_i F_0^{\alpha_i, \gamma} F(x_i, z(x_i)) \right]$$

$$+ v(\theta) \left[ z_a + p(z) \right].$$

(3.12)

**3.1 Uniqueness results via Theorem 2.8**

**Theorem 3.3** Assume that \((G1)-(G2)\) hold. If

$$\Delta := 1 - \Lambda_1 \Lambda_1 + \Lambda_2 \Lambda_2 < 1,$$

(3.13)

then there exists a unique solution for (1.1)–(1.2) on \(J\), where \(\Delta\) is given by (3.6).

**Proof** According to Lemma 3.1, we consider the operator \(H : C \rightarrow C\) defined by (3.12). Then we prove that \(H\) has a fixed point due to Theorem 2.8. First, we define the closed ball \(B_R = \{ z \in C : \|z\| \leq R \} \subset C\) with \(R > \frac{\Lambda_1 + \Lambda_2}{4(\Lambda_1 + \Lambda_2)^2}\). Then, for \(z \in B_R\), we have

$$|F(s, z(s))| = |F(s, z(s)) - F(s, 0) + F(s, 0)|$$

$$\leq |F(s, z(s)) - F(s, 0)| + |F(s, 0)|$$

$$\leq (L_1 \|z(s)\| + |F(s, 0)|)$$

$$\leq L_1 R + M.$$
Similarly, we obtain
\[ |p(z)| \leq L_2 R. \]

Hence
\[
\begin{align*}
|H(z(\theta))| &= v(\theta)\left[|z_a| + |p(z)|\right] + \int_a^b G_{\xi}^{01}(\theta, s)|F(s, z(s))| \, ds \\
&\quad + \mu(\theta) \left[|z_b| + \int_a^b G_{\xi}^{01-1}(b, s)|F(s, z(s))| \, ds \right] \\
&\quad + \sum_{i=1}^{m-2} \lambda_i \int_a^{\xi_i} G_{\xi}^{01-1}(x_i, s)|F(s, z(s))| \, ds \\
&\leq v(\theta)\left[|z_a| + L_2 R\right] + (L_1 R + M) \int_a^b G_{\xi}^{01}(\theta, s) \, ds \\
&\quad + \mu(\theta) \left[|z_b| + (L_1 R + M) \left(\int_a^b G_{\xi}^{01-1}(b, s) \, ds + \sum_{i=1}^{m-2} \lambda_i \int_a^{\xi_i} G_{\xi}^{01-1}(x_i, s) \, ds\right)\right] \\
&\leq v^*\left[|z_a| + L_2 R\right] + (L_1 R + M) \frac{(\xi(b) - \xi(a))^{\alpha_1}}{\Gamma(\alpha_1 + 1)} \\
&\quad + \mu^* \left[|z_b| + (L_1 R + M) \left(\frac{(\xi(b) - \xi(a))^{\alpha_1-1}}{\Gamma(\alpha_1)} + \sum_{i=1}^{m-2} \lambda_i \frac{(\xi(x_i) - \xi(a))^{\alpha_1-1}}{\Gamma(\alpha_1)}\right)\right] \\
&\quad + v^*|z_b| + v^*|z_a| \\
&\leq (L_1 R + M) A_1 + (L_2 R) A_2 + A_3 \leq R,
\end{align*}
\]

which implies that \( \|Hz\| \leq R, \) i.e., \( \mathcal{H}B_R \subseteq B_R. \)

Now, we show that \( H \) is a contraction. Let \( z, y \in C. \) Then, for every \( \theta \in \mathcal{F}, \)
\[
\begin{align*}
\|(Hy)(\theta) - (Hz)(\theta)\| &= v(\theta)\left[|p(y) - p(z)|\right] + \int_a^b G_{\xi}^{01}(\theta, s)|F(s, y(s)) - F(s, z(s))| \, ds \\
&\quad + \mu(\theta) \left[\int_a^b G_{\xi}^{01-1}(b, s)|F(s, y(s)) - F(s, z(s))| \, ds \right] \\
&\quad + \sum_{i=1}^{m-2} \lambda_i \int_a^{\xi_i} G_{\xi}^{01-1}(x_i, s)|F(s, y(s)) - F(s, z(s))| \, ds \\
&\leq v(\theta)\left[|z_a| - |z_b|\right] + \int_a^b G_{\xi}^{01}(\theta, s)\mathcal{L}_1 |y(s) - z(s)| \, ds \\
&\quad + \mu(\theta) \left[\int_a^b G_{\xi}^{01-1}(b, s)\mathcal{L}_1 |y(s) - z(s)| \, ds \right]
\end{align*}
\]
\[
\begin{align*}
&\sum_{i=1}^{m-2} \lambda_i \int_a^{\xi_i} G_\xi^{0i-1}(\xi_i, s) \mathcal{L}_1 |y(s) - z(s)| ds \\
&\leq \|y - z\| \left[ L_2 v(\theta) + L_1 \left( \int_a^\beta G_\xi^{0i}(\theta, s) ds + \mu(\theta) \right) \right. \\
&\left. \times \left[ \int_a^\beta G_\xi^{0i-1}(b, s) ds + \sum_{i=1}^{m-2} \lambda_i \int_a^{\xi_i} G_\xi^{0i-1}(\xi_i, s) ds \right] \right].
\end{align*}
\]

Also note that

\[
\int_a^\beta G_\xi^{\alpha}(\theta, s) ds \leq \frac{(\xi(b) - \xi(a))^{\alpha}}{\Gamma(\alpha + 1)}, \quad \chi > 0.
\]

Using the above arguments, we get

\[
\begin{align*}
&\|\mathcal{H}y - \mathcal{H}z\|_\infty \\
&\leq \|y - z\| \left[ L_2 v(\theta) + L_1 \left( \frac{(\xi(b) - \xi(a))^{\alpha}}{\Gamma(\alpha + 1)} \right) \right. \\
&\left. + \mu(\theta) \left[ \int_a^\beta G_\xi^{0i-1}(b, s) |\mathcal{F}(s, y(s)) - \mathcal{F}(s, z(s))| ds \right. \\
&\left. + \sum_{i=1}^{m-2} \lambda_i \int_a^{\xi_i} G_\xi^{0i-1}(\xi_i, s) |\mathcal{F}(s, y(s)) - \mathcal{F}(s, z(s))| ds \right] \right].
\end{align*}
\]

As \(\Delta < 1\), we deduce that \(\mathcal{H}\) is a contraction. Hence, Theorem 2.8 shows that BVP (1.1)–(1.2) has a unique solution. This completes the proof. \(\square\)

\textbf{Remark 3.4} We would like to point out that the strong condition \(\Delta < 1\) can be removed if we use the well-known Bielecki norm.

In fact, just like the discussion in Theorem 3.3, we only prove that \(\mathcal{H}\) defined as before is a contraction on \(\mathcal{C}\) via the Bielecki norm. Given \(z, y \in \mathcal{C}\) and \(\theta \in \mathcal{J}\), using (G2) and Lemma 2.7, we have

\[
\begin{align*}
&|\langle \mathcal{H}y|\theta\rangle| |\langle \mathcal{H}z|\theta\rangle| \\
&\leq v(\theta) \left[ |p(y) - p(z)| + \int_a^\beta G_\xi^{0i}(\theta, s) |\mathcal{F}(s, y(s)) - \mathcal{F}(s, z(s))| ds \right. \\
&\left. + \mu(\theta) \left[ \int_a^\beta G_\xi^{0i-1}(b, s) |\mathcal{F}(s, y(s)) - \mathcal{F}(s, z(s))| ds \right. \\
&\left. + \sum_{i=1}^{m-2} \lambda_i \int_a^{\xi_i} G_\xi^{0i-1}(\xi_i, s) |\mathcal{F}(s, y(s)) - \mathcal{F}(s, z(s))| ds \right\rangle \\
&\leq v(\theta) \left[ \frac{\mathcal{L}_2 |y(\theta) - z(\theta)|}{e^{\theta(\xi(b) - \xi(a))} - e^{\theta(\xi(\theta) - \xi(a))}} \right] \\
&\left. + \int_a^\beta G_\xi^{0i}(\theta, s) \mathcal{L}_1 |y(s) - z(s)| e^{\theta(\xi(s) - \xi(a))} ds \right].
\end{align*}
\]
\begin{equation}
+ \mu(\vartheta) \left[ \int_a^b G_{\xi}^{q_{i-1}}(b, s) \frac{L_1 |y(s) - z(s)|}{e^{\theta(\xi(b)) - \xi(a)}} ds \right.
+ \sum_{i=1}^{m-2} \lambda_i \int_a^b G_{\xi}^{q_{i-1}}(\xi_i, s) \frac{L_1 |y(s) - z(s)|}{e^{\theta(\xi(b)) - \xi(a)}} ds \left. \right] \leq \left[ \nu(\vartheta) L_2 e^{\theta(\xi(b)) - \xi(a)} \right] + L_1 \int_a^b G_{\xi}^{q_{i-1}}(\vartheta, s) e^{\theta(\xi(b)) - \xi(a)} ds
+ \mu(\vartheta) L_1 \left[ \int_a^b G_{\xi}^{q_{i-1}}(b, s) e^{\theta(\xi(b)) - \xi(a)} ds \right]
+ \sum_{i=1}^{m-2} \lambda_i \int_a^b G_{\xi}^{q_{i-1}}(\xi_i, s) e^{\theta(\xi(b)) - \xi(a)} ds \right] \|y - z\|_{\vartheta},
\end{equation}

where

\[ \|z\|_{\vartheta} := \sup_{\vartheta \in \mathcal{J}} \frac{|z(\vartheta)|}{e^{\theta(\xi(b)) - \xi(a)}}, \quad \vartheta > 0, \]
denotes the Bielecki-type norm on the Banach space \( C \). Thus, we obtain

\[ \| \mathcal{H}y - \mathcal{H}z \|_{\vartheta} \leq \left[ L_2 v^* + \mathcal{L} \left( \frac{1}{\theta q_1} + \frac{\mu^*}{\theta q_1 - 1} + \sum_{i=1}^{m-2} \lambda_i \frac{\mu^*}{\theta q_1 - 1} \right) \right] \|y - z\|_{\vartheta}. \]

Taking \( \vartheta > 0 \) large enough such that

\[ \left[ L_2 v^* + \mathcal{L} \left( \frac{1}{\theta q_1} + \frac{\mu^*}{\theta q_1 - 1} + \sum_{i=1}^{m-2} \lambda_i \frac{\mu^*}{\theta q_1 - 1} \right) \right] < 1, \]
it follows that

\[ \| \mathcal{H}y - \mathcal{H}z \|_{\vartheta} < \|y - z\|_{\vartheta}. \]

This means that \( \mathcal{H} \) is a contraction with respect to the Bielecki norm. Hence, Theorem 2.8 shows that BVP (1.1)–(1.2) has a unique solution.

### 3.2 Existence result via Theorem 2.9

**Theorem 3.5** Assume that (G1)–(G3) hold. Then (1.1)–(1.2) has at least one solution on \( \mathcal{J} \), provided

\[ \Theta < 1, \tag{3.14} \]

where \( \Theta \) is given by (3.7).
Proof By assumption (G3), we can fix

\[ \rho \geq \| \phi \| \Lambda_1 + \| \phi \| \Lambda_2 + \Lambda_3, \]

where \( B_\rho = \{ z \in \mathbb{C} : \| z \| \leq \rho \} \). Let us split the operator \( \mathcal{H} : \mathbb{C} \rightarrow \mathbb{C} \) defined by (3.12) as \( \mathcal{H} = \mathcal{H}_1 + \mathcal{H}_2 \), where \( \mathcal{H}_1 \) and \( \mathcal{H}_2 \) are given by

\[ \mathcal{H}_1(z)(\vartheta) = \int_a^\vartheta G_{\xi_1}(\vartheta, s) F(s, z(s)) \, ds, \]

\[ \mathcal{H}_2(z)(\vartheta) = \mu(\vartheta) \left[ z_b + \int_a^b G_{\xi_1}(b, s) F(s, z(s)) \, ds + \sum_{i=1}^{m-2} \lambda_i \int_a^{\kappa_i} G_{\xi_i}(\kappa_i, s) F(s, z(s)) \, ds \right] \]

\[ + \nu(\vartheta) \left[ z_a + p(z) \right]. \]

The proof will be split into numerous steps.

Step 1: \( \mathcal{H}_1(z) + \mathcal{H}_2(z_1) \in B_\rho \). Indeed, for each \( z, z_1 \in B_\rho \) and \( \vartheta \in J \), then

\[ \| \mathcal{H}_1 z + \mathcal{H}_2 z_1 \| \]

\[ = \sup_{\vartheta \in J} \| (\mathcal{H}_1 z)(\vartheta) + (\mathcal{H}_2 z_1)(\vartheta) \| \]

\[ \leq \int_a^\vartheta \left\| G_{\xi_1}(\vartheta, s) F(s, z(s)) \right\| \, ds + \mu(\vartheta) \]

\[ \times \left[ |z_b| + \int_a^b \left\| G_{\xi_1}^{-1}(b, s) F(s, z(s)) \right\| \, ds \right. \]

\[ + \sum_{i=1}^{m-2} \lambda_i \int_a^{\kappa_i} \left\| G_{\xi_i}^{-1}(\kappa_i, s) F(s, z(s)) \right\| \, ds \]

\[ + \nu(\vartheta) \left[ |z_a| + |p(z)| \right] \]

\[ \leq \| \varphi \left[ \left( \frac{\xi(b) - \xi(a)}{\Gamma(\xi_1 + 1)} + \mu^{*} \left( \frac{\xi(b) - \xi(a)}{\Gamma(\xi_1)} + \sum_{i=1}^{m-2} \frac{\xi(\kappa_i) - \xi(a)}{\Gamma(\kappa_i)} \right) \right) \]

\[ + \| \phi \| v^{*} + |z_a| v^{*} + \mu^{*} |z_b| \]

\[ \leq \| \varphi \| \Lambda_1 + \| \phi \| \Lambda_2 + \Lambda_3 \leq \rho. \]

Hence

\[ \| \mathcal{H}_1 z + \mathcal{H}_2 z_1 \| \leq \rho, \]

which shows that \( \mathcal{H}_1 z + \mathcal{H}_2 z_1 \in B_\rho \).

Step 2: \( \mathcal{H}_2 \) is a contraction map on \( B_\rho \).

Due to the contractility of \( \mathcal{H} \) as in Theorem 3.3, \( \mathcal{H}_2 \) is a contraction map too.

Step 3: \( \mathcal{H}_1 \) is completely continuous on \( B_\rho \).

From the continuity of \( F(\cdot, z(\cdot)) \) it follows that \( \mathcal{H}_1 \) is continuous.
Since
\[
\|H_1z\| = \sup_{s \in J} |H_1z(s)| \leq \int_a^b G^{01}_\xi(\theta, s) |F(s, z(s))| \, ds
\]
\[
\leq \|\phi\| \frac{(\xi(b) - \xi(a))^{01}}{\Gamma(\varrho_1 + 1)} := p, \quad z \in B_\rho,
\]
we get \(\|H_1z\| \leq p\), which emphasizes that \(H_1\) uniformly bounded on \(B_\rho\).

Finally, we prove the compactness of \(H_1\).

For \(z \in B_\rho\) and \(\vartheta \in J\), we can estimate the operator derivative as follows:
\[
|H_1^{(1)}(\vartheta)| \leq \int_{\vartheta}^b \frac{G^{01-1}(\theta, s) |F(s, z(s))|}{\Gamma(\varrho_1)} \, ds
\]
\[
\leq \|\phi\| \frac{(\xi(b) - \xi(a))^{01-1}}{\Gamma(\varrho_1)} := \ell,
\]
where we used the fact
\[
D^k_x T_{a^+}^{\varrho_1 - k, \xi} = T_{a^+}^{\varrho_1 - k, \xi}, \quad \omega^{(k)}(\theta) = \left( \frac{1}{\xi^{(k)}(\theta)} \frac{d}{d\theta} \right)^k \omega(\theta) \quad \text{for } k = 0, 1, \ldots, n - 1.
\]

Hence, for each \(\vartheta_1, \vartheta_2 \in J\) with \(a < \vartheta_1 < \vartheta_2 < b\) and for \(z \in B_\rho\), we get
\[
|H_1(z)(\vartheta_2) - H_1(z)(\vartheta_1)| = \int_{\vartheta_1}^{\vartheta_2} |H_1(z)'(s)| \, ds \leq \ell(\vartheta_2 - \vartheta_1),
\]
where \((\vartheta_2 - \vartheta_1)\) tends to zero independent of \(z\). So, \(H_1\) is equicontinuous. In light of the previous arguments along with the Arzela–Ascoli theorem, we derive that \(H_1\) is compact on \(B_\rho\). Thus, the hypotheses of Theorem 2.9 hold. So there exists at least one solution of (1.1)–(1.2) on \(J\).

**Remark 3.6** In Theorem 3.5, we can exchange the roles of the operators \(H_1\) and \(H_2\) to obtain a second result by replacing (3.14) with the following condition:
\[
\mathcal{L}_1 \left( \frac{(\xi(b) - \xi(a))^{01}}{\Gamma(\varrho_1 + 1)} \right) < 1.
\]

### 4 UH stability analysis

In this section, we discuss UH and generalized UH stability of (1.1)–(1.2). Let \(\varepsilon > 0\). We consider the following inequality:
\[
|D_{a^+}^{01-\vartheta_1, \xi} z(\theta) - F(\theta, z(\theta))| \leq \varepsilon, \quad \theta \in J.
\]

**Definition 4.1** FDE (1.1)–(1.2) is UH stable if there exists \(c_\mathcal{F} \in \mathbb{R}^+\) such that, for any \(\varepsilon > 0\) and for each solution \(\tilde{z} \in C\) of inequality (4.1), there exists a solution \(z \in \mathcal{U}\) of (1.1)–(1.2) with
\[
|\tilde{z}(\theta) - z(\theta)| \leq \varepsilon c_\mathcal{F}, \quad \theta \in J.
\]

For a given solution \(z \in \mathcal{U}\) of FDE (1.1)–(1.2), by using the Gronwall inequality, the following inequality holds:
\[
|\tilde{z}(\theta) - z(\theta)| \leq c_\mathcal{F} \varepsilon, \quad \theta \in J.
\]

Hence, for each \(\vartheta_1, \vartheta_2 \in J\) with \(a < \vartheta_1 < \vartheta_2 < b\) and for \(z \in B_\rho\), we get
\[
|H_1(z)(\vartheta_2) - H_1(z)(\vartheta_1)| = \int_{\vartheta_1}^{\vartheta_2} |H_1(z)'(s)| \, ds \leq \ell(\vartheta_2 - \vartheta_1),
\]
where \((\vartheta_2 - \vartheta_1)\) tends to zero independent of \(z\). So, \(H_1\) is equicontinuous. In light of the previous arguments along with the Arzela–Ascoli theorem, we derive that \(H_1\) is compact on \(B_\rho\). Thus, the hypotheses of Theorem 2.9 hold. So there exists at least one solution of (1.1)–(1.2) on \(J\).
Definition 4.2 FDE (1.1)–(1.2) is called generalized UH stable if there exists $\varphi_F \in C(\mathbb{R}_+, \mathbb{R}_+)$ along with $\varphi_F(0) = 0$ if, for any $\varepsilon > 0$ and for each solution $\tilde{z} \in C$ of inequality (4.1), a solution $z \in C$ of (1.1)–(1.2) exists uniquely for which

$$|\tilde{z}(\theta) - z(\theta)| \leq \varphi_F(\varepsilon), \quad \theta \in J.$$

Remark 4.3 A function $\tilde{z} \in C$ is a solution of (4.1) iff there exists a function $\upsilon \in C$ (which depends on solution $\tilde{z}$) such that

1. $|\upsilon(\theta)| \leq \varepsilon, \theta \in J.$
2. $D^{\alpha_1, \alpha_2}_a \tilde{z}(\theta) = F(\theta, \tilde{z}(\theta)) + \upsilon(\theta), \theta \in J.$

Theorem 4.4 Let $\Delta < 1$ and hypotheses (G1) and (G2) be satisfied. Then FDE (1.1)–(1.2) is UH stable on $J$ and consequently generalized UH stable.

Proof Let $\varepsilon > 0$ and $\tilde{z} \in C$ satisfy inequality (4.1), and let $z \in C$ be the unique solution of the following problem:

$$\begin{align*}
D^{\alpha_1, \alpha_2}_a z(\theta) &= F(\theta, z(\theta)), \quad \theta \in J := [a, b], \\
z(a) &= z_a + p(z), \quad z'_b(b) = z_b + \sum_{i=1}^{m-2} \lambda_i \tilde{z}'(\xi_i).
\end{align*}$$

By Lemma 3.1, we have

$$\begin{align*}
z(\theta) &= T^{\alpha_1}_a h(\theta) + \mu(\theta) \left[ z_b + T^{\alpha_1-1}_a h(b) + \sum_{i=1}^{m-2} \lambda_i T^{\alpha_1-1}_a h(\xi_i) \right] + \upsilon(\theta) \left[ z_a + p(z) \right] \\
&= \int_a^\theta G^{\alpha_1}_a(\theta, s) F(s, z(s)) \, ds \\
&\quad + \mu(\theta) \left[ z_b + \int_a^b G^{\alpha_1-1}(b, s) F(s, z(s)) \, ds + \sum_{i=1}^{m-2} \lambda_i \int_a^b G^{\alpha_1-1}(\xi_i, s) F(s, z(s)) \, ds \right] \\
&\quad + \upsilon(\theta) \left[ z_a + p(z) \right].
\end{align*}$$

(4.3)

Since we have assumed that $\tilde{z}$ is a solution of (4.1), we have by Remark 4.3

$$\begin{align*}
D^{\alpha_1, \alpha_2}_a \tilde{z}(\theta) &= F(\theta, \tilde{z}(\theta)) + \upsilon(\theta), \quad \theta \in J := [a, b], \\
\tilde{z}(a) &= z_a + p(\tilde{z}), \quad \tilde{z}'(b) = z_b + \sum_{i=1}^{m-2} \lambda_i \tilde{z}'(\xi_i).
\end{align*}$$

(4.4)

Again by Lemma 3.1, we have

$$\begin{align*}
\tilde{z}(\theta) &= \int_a^\theta G^{\alpha_1}_a(\theta, s) F(s, \tilde{z}(s)) \, ds + \int_a^\theta G^{\alpha_1}_a(\theta, s) \upsilon(s) \, ds \\
&\quad + \mu(\theta) \left[ z_b + \int_a^b G^{\alpha_1-1}(b, s) F(s, \tilde{z}(s)) \, ds + \int_a^b G^{\alpha_1-1}(b, s) \upsilon(s) \, ds \right] \\
&\quad + \sum_{i=1}^{m-2} \lambda_i \int_a^\theta G^{\alpha_1-1}(\xi_i, s) F(s, \tilde{z}(s)) \, ds + \sum_{i=1}^{m-2} \lambda_i \int_a^\theta G^{\alpha_1-1}(\xi_i, s) \upsilon(s) \, ds.
\end{align*}$$
\[ + v(\vartheta)\big[z_a + p(\tilde{z})\big]. \]

Consequently, for each \( \vartheta \in \mathcal{J} \), we have

\[
\big| \tilde{z}(\vartheta) - z(\vartheta) \big| \\
= \int_a^\vartheta G^{q_1}_{q_1}(\vartheta, s)\big| \mathcal{F}(s, \tilde{z}(s)) - \mathcal{F}(s, z(s)) \big| \, ds + \int_a^\vartheta G^{q_1}_{q_1}(\vartheta, s)\psi(s) \, ds \\
+ \mu(\vartheta) \left[ \int_a^b G^{q_1-1}_{q_1}(b, s)\big| \mathcal{F}(s, \tilde{z}(s)) - \mathcal{F}(s, z(s)) \big| \, ds + \int_a^b G^{q_1-1}_{q_1}(b, s)\psi(s) \, ds \\
+ \sum_{i=1}^{m-2} \lambda_i \int_a^{\xi_i} G^{q_1-1}_{q_1}(\xi_i, s)\big| \mathcal{F}(s, \tilde{z}(s)) - \mathcal{F}(s, z(s)) \big| \, ds \right] \\
+ \nu(\vartheta)\big| p(\tilde{z}) - p(z) \big|. \tag{4.5} \]

From Remark 4.3 and (G2), we derive

\[
\big| \tilde{z}(\vartheta) - z(\vartheta) \big| \\
\leq \Delta \| \tilde{z} - z \| \\
+ \left( \frac{\xi(b) - \xi(a)q_1}{\Gamma(q_1 + 1)} + \mu \left[ \frac{\xi(b) - \xi(a)q_1+1}{\Gamma(q_1)} + \sum_{i=1}^{m-2} \lambda_i \frac{\xi(\xi_i) - \xi(a)q_1+1}{\Gamma(q_1)} \right] \right) \varepsilon \\
:= \Delta \| \tilde{z} - z \| + \Lambda \varepsilon,
\]

where \( \Delta \) is defined in (3.6). In consequence, it follows that

\[
\| \tilde{z} - z \|_{\infty} \leq \frac{\Lambda \varepsilon}{(1 - \Delta)}.
\]

If we set \( c_{\mathcal{F}} = \frac{\Delta}{1 - \Delta} \), then the UH stability condition holds. Moreover, for \( \varphi_{\mathcal{F}}(\varepsilon) = \frac{\Lambda \varepsilon}{(1 - \Delta)} \) with \( \varphi_{\mathcal{F}}(0) = 0 \), the generalized UH stability condition holds too. This completes the proof. \( \square \)

5 Examples

In this section, we consider two examples to better illustrate our main results.

**Example 5.1** Consider the following BVP for FDE:

\[
\begin{aligned}
D^{3,0}_{q_2} z(\vartheta) &= \mathcal{F}(\vartheta, z(\vartheta)), \quad \vartheta \in \mathcal{J} := [0, 1], \\
z(0) &= \frac{3}{5} + \sum_{j=1}^n c_j z(\vartheta_j), \quad z'(1) = \frac{7}{10} + \frac{1}{15} z'(\frac{1}{2}) + \frac{1}{15} z'(\frac{3}{2}),
\end{aligned} \tag{5.1}
\]

where

\[
q_1 = \gamma = \frac{3}{2}, \quad q_2 = 0, \quad b = 1, \quad a = 0, \quad \xi(\vartheta) = \vartheta,
\]
Using the given data, we find that
\[
A = \left[ \frac{(b - a)^{\gamma - 2}}{\Gamma(\gamma - 1)} - \sum_{i=1}^{m-2} \lambda_i \frac{[\varphi_i - a]^{\gamma - 2}}{\Gamma(\gamma - 1)} \right] \approx 0.3462 \neq 0.
\]

In order to illustrate Theorem 3.3 and Theorem 3.5, we take
\[
f(\theta, z(\theta)) = \frac{\theta^2 - 1}{(2 - \sin^2 \pi \theta)^2} \left( \frac{|z(\theta)|}{1 + |z(\theta)|} \right),
\]
\[
p(z) = \sum_{j=1}^{n} c_j z(\varphi_j),
\]
in (1.1), where \(0 < \vartheta_1 < \vartheta_2 < \cdots < \vartheta_n < \varpi, j = 1, \ldots, n\), are given positive constants with \(\sum_{j=1}^{n} c_j < \frac{\gamma}{3}\), and note that
\[
\|f(\theta, z) - f(\theta, v)\| \leq \frac{1}{8} \|z - v\|,
\]
\[
\|p(z) - p(v)\| = \sum_{j=1}^{n} c_j \|z - v\|.
\]
Hence conditions (G1)–(G3) hold with \(L_1 = \frac{1}{8}, L_2 = \frac{\gamma}{3}\). Further, from the above given data it is easy to calculate
\[
\Theta \simeq 0.1325 < 1.
\]

By Theorem 3.5, problem (5.1) with data (5.2) and (5.3) has at least a solution \(z\). Furthermore \(\Delta \simeq 0.2265 < 1\). Hence, by Theorem 3.3, problem (5.1) with data (5.2) and (5.3) has a unique solution.

**Example 5.2** Let us consider BVP for FDE (1.1)–(1.2) with
\[
\xi(\theta) = 2^\theta, \quad \varphi_1 = \frac{5}{3}, \quad \varphi_2 = \frac{1}{3}, \quad \gamma = \frac{16}{9},
\]
\[
z_a = \frac{1}{5}; \quad z_b = \frac{2}{7}; \quad \lambda_1 = \frac{1}{5}, \quad \lambda_2 = \frac{2}{7},
\]
\[
\varphi_1 = \frac{3}{4}, \quad \varphi_2 = \frac{2}{5}, \quad b = 1, \quad a = 0.
\]
In order to illustrate Theorem 3.3 and Theorem 3.5, we take
\[
f(\theta, z(\theta)) = \frac{e^{-2\theta}}{(\theta^4 + 25)} (\sin |z(\theta)|),
\]
\[
p(z) = \sum_{j=1}^{n} c_j z(\varphi_j)
\]
in (1.1), where $0 < \vartheta_1 < \vartheta_2 < \cdots < \vartheta_n < \vartheta_n$, $i = 1, \ldots, n$, are given positive constants with $\sum_{j=1}^{n} c_j < \frac{2}{15}$, and note that

$$
\|f(\vartheta, z) - f(\vartheta, v)\| \leq \frac{1}{25} \|z - v\|,
$$

$$
\|p(z) - p(v)\| = \sum_{j=1}^{n} c_j \|z - v\|.
$$

Hence conditions (G1)–(G3) hold with $L_1 = \frac{1}{25}$ and $L_1 = \frac{1}{15}$. Further, from the above given data, it is easy to calculate

$$\Theta \simeq 0.7967 < 1.$$

Using the given values of the parameters in (3.1), by the Matlab program, we find that

$$A = \left[\frac{[2 \beta - 2 \alpha]^{\gamma-2}}{\Gamma(\gamma - 1)} - \sum_{i=1}^{m-1} \lambda_i \frac{[2 \gamma_i - 2 \alpha]^{\gamma-2}}{\Gamma(\gamma - 1)}\right] \simeq 0.3449 \neq 0.$$

Hence condition (G2) holds with $L_1 = \frac{1}{15}$, $L_2 = \frac{1}{24}$. We shall check that condition (3.13) is satisfied. Indeed, using simple calculations, we can find

$$\Delta \simeq 0.8811 < 1.$$

Hence, by Theorem 3.3, BVP (1.1)–(1.2) has a unique solution on $\mathcal{J}$. Moreover, Theorem 4.4 ensures that BVP (1.1)–(1.2) is HU stable and generalized HU stable.

6 Conclusion

By using standard fixed point techniques, we have established some advantageous results about the existence, uniqueness, and stability of the Ulam–Hyers type of the BVP for nonlinear FDEs involving a $\xi$-Hilfer FD under nonlocal boundary conditions. The acquired results have been justified by two examples. Furthermore, problem (1.1)–(1.2) not just incorporates the formerly specified BVPs in the literature, but it does cover as many problems as special cases for various values of $\vartheta_2$ and $\xi$, as referenced in Remarks 1.1, 1.2. Consequently, the fixed point technique is a powerful approach to investigate diverse nonlinear problems, which is very important in many theoretical and applied fields.

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Competing interests

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