ON A SYSTEM OF DIFFERENCE EQUATIONS OF SECOND ORDER SOLVED IN CLOSED FORM

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Abstract. In this work we solve in closed form the system of difference equations

\[ x_{n+1} = \frac{ay_{n}x_{n-1} + bx_{n-1} + c}{y_{n}x_{n-1}}, \quad y_{n+1} = \frac{ax_{n}y_{n-1} + by_{n-1} + c}{x_{n}y_{n-1}}, \quad n = 0, 1, \ldots, \]

where the initial values \( x_{-1}, x_{0}, y_{-1} \) and \( y_{0} \) are arbitrary nonzero real numbers and the parameters \( a, b \) and \( c \) are arbitrary real numbers with \( c \neq 0 \). In particular we represent the solutions of some particular cases of this system in terms of Tribonacci and Padovan numbers and we prove the global stability of the corresponding positive equilibrium points. The results obtained here extend those obtained in some recent papers.

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1. INTRODUCTION

We find in the literature many studies that concern the representation of the solutions of some remarkable linear sequences such as Fibonacci, Lucas, Pell, Jacobsthal, Padovan, and Perrin (see, e.g., [1, 6, 9, 10, 12–14, 20]). Solving in closed form nonlinear difference equations and systems is a subject that highly attract the attention of researchers (see, e.g., [3–5, 7, 8, 11, 16–19, 21]) and the reference cited therein, where we find very interesting formulas of the solutions. A large range of these formulas are expressed in terms of famous numbers like Fibonacci and Padovan, (see, e.g., [8, 16, 18]). For solving in closed form nonlinear difference equations and systems generally we use some change of variables that transformed nonlinear equations and systems in linear ones. The paper of Stevic [15] has considerably motivated this line of research.

The difference equation

\[ x_{n+1} = a + \frac{b}{x_{n-1}} + \frac{c}{x_{n}x_{n-1}} \]

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was studied by Azizi in [2]. Noting that the same equation was the subject of a very recent paper by Stevic [17].

In [21] the authors studied the system
\[
\begin{align*}
    x_{n+1} &= \frac{1 + x_{n-1}}{y_n x_{n-1}}, \\
    y_{n+1} &= \frac{1 + y_{n-1}}{x_n y_{n-1}},
\end{align*}
\]
Motivated by [21], Halim et al. in [8], got the form of the solutions of the following difference equation
\[
x_{n+1} = \frac{a + b x_{n-1}}{x_n x_{n-1}},
\]
and the system
\[
x_{n+1} = \frac{a + b x_{n-1}}{y_n x_{n-1}}, \\
    y_{n+1} = \frac{a + b y_{n-1}}{x_n y_{n-1}},
\]
Here and motivated by the above mentioned papers we are interested in the following system of difference equations
\[
x_{n+1} = \frac{a y_n x_{n-1} + b x_{n-1} + c}{y_n x_{n-1}}, \\
    y_{n+1} = \frac{a x_n y_{n-1} + b y_{n-1} + c}{x_n y_{n-1}}, n = 0, 1, ..., (1.1)
\]
where \(x_{-1}, x_0, y_{-1}\) and \(y_0\) are arbitrary nonzero real numbers, \(a, b\) and \(c\) are arbitrary real numbers with \(c \neq 0\). Clearly our system generalized the equations and systems studied in [2, 8, 17] and [21].

2. THE HOMOGENOUS THIRD ORDER LINEAR DIFFERENCE EQUATION WITH
CONSTANT COEFFICIENTS.

Consider the homogenous third order linear difference equation
\[
R_{n+1} = a R_n + b R_{n-1} + c R_{n-2}, n = 0, 1, ..., (2.1)
\]
where the initial values \(R_0, R_{-1}\) and \(R_{-2}\) and the constant coefficients \(a, b\) and \(c\) are real numbers with \(c \neq 0\). This equation will be of great importance for our study, so we will solve it in closed form. As it is well known, the solution \((R_n)_{n=-2}^{+\infty}\) of equation (2.1) is usually expressed in terms of the roots \(\alpha, \beta\) and \(\gamma\) of the characteristic equation
\[
\lambda^3 - a\lambda^2 - b\lambda - c = 0. \tag{2.2}
\]
Here we express the solutions of the equation (2.1) using terms of the sequence \((J_n)_{n=0}^{+\infty}\) defined by the recurrent relation
\[
J_{n+3} = a J_{n+2} + b J_{n+1} + c J_n, \quad n \in \mathbb{N}, \tag{2.3}
\]
and the special initial values
\[
J_0 = 0, \quad J_1 = 1 \text{ and } J_2 = a. \tag{2.4}
\]
Noting that \((R_n)_{n=-2}^{+\infty}\) and \((J_n)_{n=0}^{+\infty}\) have the same characteristic equation. Also if \(a = b = c = 1\), then the equation (2.3) is nothing other than the famous Tribonacci sequence \((T_n)_{n=0}^{+\infty}\).

The closed form of the solutions of \(\{J_n\}_{n=0}^{+\infty}\) and many proprieties of them are well known in the literature, for the interest of the readers and for the purpose of our work, we show how we can get the formula of the solutions and we give also a result on the limit

\[
\lim_{n \to \infty} \frac{J_{n+1}}{J_n}.
\]

For the roots \(\alpha, \beta\) and \(\gamma\) of the characteristic equation (2.2), we have

\[
\begin{align*}
\alpha + \beta + \gamma &= a \\
\alpha \beta + \alpha \gamma + \beta \gamma &= -b \\
\alpha \beta \gamma &= c.
\end{align*}
\]  

We have:

**Case 1: If all roots are equal.** In this case

\[
J_n = (c_1 + c_2 n + c_3 n^2) \alpha^n.
\]

Now using (2.5) and the fact that \(J_0 = 0, J_1 = 1\) and \(J_2 = a\), we obtain

\[
J_n = \left( \frac{n}{2\alpha} + \frac{n^2}{2\alpha} \right) \alpha^n. \tag{2.6}
\]

**Case 2: If two roots are equal, say \(\beta = \gamma\).** In this case

\[
J_n = c_1 \alpha^n + (c_2 + c_3 n) \beta^n.
\]

Using (2.5) and the fact that \(J_0 = 0, J_1 = 1\) and \(J_2 = a\), we obtain

\[
J_n = \frac{\alpha}{(\beta - \alpha)^2} \alpha^n + \left( \frac{-\alpha}{(\beta - \alpha)^2} + \frac{n}{\beta - \alpha} \right) \beta^n. \tag{2.7}
\]

**Case 3: If the roots are all different.** In this case

\[
J_n = c_1 \alpha^n + c_2 \beta^n + c_3 \gamma^n.
\]

Again, using (2.5) and the fact that \(J_0 = 0, J_1 = 1\) and \(J_2 = a\), we obtain

\[
J_n = \frac{\alpha}{(\gamma - \alpha)(\beta - \alpha)} \alpha^n + \frac{-\beta}{(\gamma - \beta)(\beta - \alpha)} \beta^n + \frac{\gamma}{(\gamma - \alpha)(\gamma - \beta)} \gamma^n. \tag{2.8}
\]

In this case we can get two roots of (2.2) complex conjugates say \(\gamma = \overline{\beta}\) and the third one real and the formula of \(J_n\) will be

\[
J_n = \frac{\alpha}{(\beta - \alpha)(\beta - \alpha)} \alpha^n + \frac{-\beta}{(\beta - \beta)(\beta - \alpha)} \beta^n + \frac{\overline{\beta}}{(\beta - \alpha)(\beta - \beta)} \overline{\beta}^n. \tag{2.9}
\]

Consider the following linear third order difference equation

\[
S_{n+1} = -a S_n + b S_{n-1} - c S_{n-2}, \quad n = 0, 1, \ldots. \tag{2.10}
\]
the constant coefficients $a$, $b$ and $c$ and the initial values $S_0$, $S_{-1}$ and $S_{-2}$ are real numbers. As for the equation (2.1), we will express the solutions of (2.10) using terms of (2.3). To do this let us consider the difference equation

$$j_{n+3} = -aj_{n+2} + bj_{n+1} - cj_n, \quad n \in \mathbb{N},$$

(2.11)

and the special initial values

$$j_0 = 0, \quad j_1 = 1 \text{ and } j_2 = -a.$$  (2.12)

The characteristic equation of (2.10) and (2.11) is

$$\lambda^3 + a\lambda^2 - b\lambda + c = 0.$$  (2.13)

Clearly the roots of (2.13) are $-\alpha, -\beta$ and $-\gamma$. Now following the same procedure in solving $f(J(n))$, we get that

$$j(n) = (-1)^{n+1}f(n).$$

Lemma 1. Let $\alpha$, $\beta$ and $\gamma$ be the roots of (2.2), assume that $\alpha$ is a real root with $\max(|\alpha|, |\beta|, |\gamma|) = |\alpha|$. Then,

$$\lim_{n \to \infty} \frac{J_{n+1}}{J_n} = \alpha.$$

Proof. If $\alpha$, $\beta$ and $\gamma$ are real and distinct then,

$$\lim_{n \to \infty} \frac{J_{n+1}}{J_n} = \lim_{n \to \infty} \frac{\alpha}{(y-\alpha)(\beta-\alpha)} \frac{\alpha^{n+1}}{\alpha^n} + \frac{-\beta}{(y-\beta)(\beta-\alpha)} \frac{\beta^{n+1}}{\beta^n} + \frac{\gamma}{(y-\gamma)(\beta-\alpha)} \frac{\gamma^{n+1}}{\gamma^n}$$

$$= \frac{\alpha}{(y-\alpha)(\beta-\alpha)} + \frac{-\beta}{(y-\beta)(\beta-\alpha)} \frac{\beta}{\alpha} + \frac{\gamma}{(y-\gamma)(\beta-\alpha)} \frac{\gamma}{\alpha}$$

$$= \alpha.$$

The proof of the other cases of the roots, that is when $\alpha = \beta = \gamma$ or $\gamma$ are complex conjugate, is similar to the first one and will be omitted.

Remark 1. If $\alpha$ is a real root and $\beta$, $\gamma$ are complex conjugate with

$$\max(|\alpha|, |\beta|, |\beta|) = |\beta| = |\beta|,$$
then \( \lim_{n \to \infty} \frac{J_{n+1}}{J_n} \) doesn’t exist.

In the following result, we solve in closed form the equations (2.1) and (2.10) in terms of the sequence \((J_n)_{n=0}^{\infty}\). The obtained formula will be very useful to obtain the formula of the solutions of system (1.1).

**Lemma 2.** We have for all \( n \in \mathbb{N}_0 \),

\[
R_n = c J_n R_{-2} + (J_{n+2} - a J_{n+1}) R_{-1} + J_{n+1} R_0,
\]

\[
S_n = (-1)^n [c J_n S_{-2} + (-J_{n+2} + a J_{n+1}) S_{-1} + J_{n+1} S_0].
\]

**Proof.** Assume that \( \alpha, \beta \) and \( \gamma \) are the distinct roots of the characteristic equation (2.2), so

\[
R_n = c'_1 \alpha^n + c'_2 \beta^n + c'_3 \gamma^n, \quad n = -2, -1, 0, \ldots.
\]

Using the initial values \( R_0, R_{-1} \) and \( R_{-2} \), we get

\[
\begin{align*}
\frac{1}{\alpha^2} c'_1 + \frac{1}{\beta^2} c'_2 + \frac{1}{\gamma^2} c'_3 &= R_{-2} \\
\frac{1}{\alpha} c'_1 + \frac{1}{\beta} c'_2 + \frac{1}{\gamma} c'_3 &= R_{-1} \\
 c'_1 + c'_2 + c'_3 &= R_0
\end{align*}
\]

after some calculations we get

\[
\begin{align*}
c'_1 &= \frac{\alpha^2 \beta \gamma}{(\gamma - \alpha)(\beta - \alpha)} R_{-2} - \frac{(\gamma + \beta) \alpha^2}{(\gamma - \alpha)(\beta - \alpha)} R_{-1} + \frac{\alpha^2}{(\gamma - \alpha)(\beta - \alpha)} R_0 \\
c'_2 &= -\frac{\alpha \beta \gamma}{(\gamma - \beta)(\beta - \alpha)} R_{-2} + \frac{(\alpha + \gamma) \beta^2}{(\gamma - \beta)(\beta - \alpha)} R_{-1} - \frac{\beta^2}{(\gamma - \beta)(\beta - \alpha)} R_0 \\
c'_3 &= \frac{\alpha \beta \gamma}{(\gamma - \alpha)(\gamma - \beta)} R_{-2} - \frac{(\alpha + \beta) \gamma^2}{(\gamma - \alpha)(\gamma - \beta)} R_{-1} + \frac{\gamma^2}{(\gamma - \alpha)(\gamma - \beta)} R_0
\end{align*}
\]

that is,

\[
R_n = \left( \frac{\alpha^2 \beta \gamma}{(\gamma - \alpha)(\beta - \alpha)} \alpha^n - \frac{\alpha \beta \gamma}{(\gamma - \beta)(\beta - \alpha)} \beta^n + \frac{\alpha \beta \gamma}{(\gamma - \alpha)(\gamma - \beta)} \gamma^n \right) R_{-2} \\
+ \left( -\frac{(\gamma + \beta) \alpha^2}{(\gamma - \beta)(\beta - \alpha)} \alpha^n + \frac{(\alpha + \gamma) \beta^2}{(\gamma - \beta)(\beta - \alpha)} \beta^n - \frac{(\alpha + \beta) \gamma^2}{(\gamma - \alpha)(\gamma - \beta)} \gamma^n \right) R_{-1} \\
+ \left( \frac{\alpha^2}{(\gamma - \alpha)(\beta - \alpha)} \alpha^n - \frac{\beta^2}{(\gamma - \beta)(\beta - \alpha)} \beta^n + \frac{\gamma^2}{(\gamma - \alpha)(\gamma - \beta)} \gamma^n \right) R_0
\]

\[
R_n = c J_n R_{-2} + (J_{n+2} - a J_{n+1}) R_{-1} + J_{n+1} R_0.
\]

The proof of the other cases is similar and will be omitted.
Let \( A := -a \) and \( B := b, C := -c \), then equation (2.10) takes the form of (2.1) and the equation (2.11) takes the form of (2.3). Then analogous to the formula of (2.1) we obtain

\[
S_n = C_j n S_{-2} + (j_{n+2} - A j_{n+1}) S_{-1} + j_{n+1} S_0.
\]

Using the fact that \( j(n) = (-1)^{n+1} f(n), A = -a \) and \( C := -c \) we get

\[
S_n = (-1)^n (c J_n S_{-2} - (J_{n+2} - a J_{n+1}) S_{-1} + J_{n+1} S_0).
\]

3. CLOSED FORM OF WELL DEFINED SOLUTIONS OF SYSTEM (1.1)

In this section, we solve through an analytical approach the system (1.1) with \( c \neq 0 \) in closed form. By a well defined solution of system (1.1), we mean a solution that satisfies \( x_n y_n \neq 0, n = -1, 0, \ldots \). Clearly if we choose the initial values and the parameters \( a, b \) and \( c \) positif, then every solution of (1.1) will be well defined.

The following result give an explicit formula for well defined solutions of the system (1.1).

**Theorem 1.** Let \( \{x_n, y_n\}_{n \geq -1} \) be a well defined solution of (1.1). Then, for \( n = 0, 1, \ldots \), we have

\[
x_{2n+1} = \frac{c J_{2n+1} + (J_{2n+3} - a J_{2n+2}) x_{-1} + J_{2n+2} x_{-1} y_0}{c J_{2n} + (J_{2n+2} - a J_{2n+1}) x_{-1} + J_{2n+1} x_{-1} y_0},
\]

\[
x_{2n+2} = \frac{c J_{2n+2} + (J_{2n+4} - a J_{2n+3}) y_{-1} + J_{2n+3} x_{0} y_{-1}}{c J_{2n+1} + (J_{2n+3} - a J_{2n+2}) y_{-1} + J_{2n+2} x_{0} y_{-1}},
\]

\[
y_{2n+1} = \frac{c J_{2n+1} + (J_{2n+3} - a J_{2n+2}) y_{-1} + J_{2n+2} x_{0} y_{-1}}{c J_{2n} + (J_{2n+2} - a J_{2n+1}) y_{-1} + J_{2n+1} x_{0} y_{-1}},
\]

\[
y_{2n+2} = \frac{c J_{2n+2} + (J_{2n+4} - a J_{2n+3}) x_{-1} + J_{2n+3} x_{-1} y_0}{c J_{2n+1} + (J_{2n+3} - a J_{2n+2}) x_{-1} + J_{2n+2} x_{-1} y_0},
\]

where the initial conditions \( x_{-1}, x_{0}, y_{-1} \) and \( y_0 \in (\mathbb{R} - \{0\}) \) – \( F \), with \( F \) is the Forbidden set of system (1.1) given by

\[
F = \bigcup_{n=0}^{\infty} \{(x_{-1}, x_{0}, y_{-1}, y_0) \in (\mathbb{R} - \{0\}) : A_n = 0 or B_n = 0\}.
\]

where

\[
A_n = J_{n+1} y_0 x_{-1} + (J_{n+2} - a J_{n+1}) x_{-1} + c J_{n},
\]

\[
B_n = J_{n+1} x_{0} y_{-1} + (J_{n+2} - a J_{n+1}) y_{-1} + c J_{n}.
\]
Proof. Putting
\[ x_n = \frac{u_n}{v_{n-1}}, \quad y_n = \frac{v_n}{u_{n-1}}, \quad n = -1, 0, 1, \ldots, \] (3.1)
we get the following linear third order system of difference equations
\[ u_{n+1} = a v_n + b u_{n-1} + c v_{n-2}, \quad v_{n+1} = a u_n + b v_{n-1} + c u_{n-2}, \quad n = 0, 1, \ldots, \] (3.2)
where the initial values \( u_{-2}, u_{-1}, u_0, v_{-2}, v_{-1}, v_0 \) are nonzero real numbers.
From (3.2) we have for \( n = 0, 1, \ldots, \)
\[
\begin{cases}
  u_{n+1} + v_{n+1} &= a(v_n + u_n) + b(u_{n-1} + v_{n-1}) + c(v_{n-2} + u_{n-2}), \\
  u_{n+1} - v_{n+1} &= a(v_n - u_n) + b(u_{n-1} - v_{n-1}) + c(v_{n-2} - u_{n-2}).
\end{cases}
\]
Putting again
\[ R_n = u_n + v_n, \quad S_n = u_n - v_n, \quad n = -2, -1, 0, \ldots, \] (3.3)
we obtain two homogenous linear difference equations of third order:
\[ R_{n+1} = aR_n + bR_{n-1} + cR_{n-2}, \quad n = 0, 1, \ldots, \]
and
\[ S_{n+1} = -aS_n + bS_{n-1} - cS_{n-2}, \quad n = 0, 1, \ldots. \] (3.4)
Using (3.3), we get for \( n = -2, -1, 0, \ldots, \)
\[ u_n = \frac{1}{2}(R_n + S_n), \quad v_n = \frac{1}{2}(R_n - S_n). \]
From Lemma 2 we obtain,
\[
\begin{align*}
  u_{2n-1} &= \frac{1}{2}[cJ_{2n-1}(R_{-2} - S_{-2}) + (J_{2n-1} - aJ_{2n})(R_{-1} + S_{-1}) + J_{2n}(R_0 - S_0)], \quad n = 1, 2, \ldots, \\
  u_{2n} &= \frac{1}{2}[cJ_{2n}(R_{-2} + S_{-2}) + (J_{2n} + aJ_{2n+1})(R_{-1} - S_{-1}) + J_{2n+1}(R_0 + S_0)], \quad n = 0, 1, \ldots, \\
  v_{2n-1} &= \frac{1}{2}[cJ_{2n-1}(R_{-2} + S_{-2}) + (J_{2n-1} + aJ_{2n})(R_{-1} - S_{-1}) + J_{2n}(R_0 + S_0)], \quad n = 1, 2, \ldots, \\
  v_{2n} &= \frac{1}{2}[cJ_{2n}(R_{-2} - S_{-2}) + (J_{2n} - aJ_{2n+1})(R_{-1} + S_{-1}) + J_{2n+1}(R_0 - S_0)], \quad n = 0, 1, \ldots, \\
\end{align*}
\] (3.5) (3.6)
Substituting (3.5) and (3.6) in (3.1), we get for \( n = 0, 1, \ldots, \)
\[
\begin{align*}
  x_{2n+1} &= \frac{cJ_{2n+1}(R_{-2} - S_{-2}) + (J_{2n+3} - aJ_{2n+2})(R_{-1} + S_{-1}) + J_{2n+2}(R_0 - S_0)}{cJ_{2n+1}(R_{-2} - S_{-2}) + (J_{2n+3} - aJ_{2n+2})(R_{-1} + S_{-1}) + J_{2n+2}(R_0 - S_0)}, \\
  x_{2n+2} &= \frac{cJ_{2n+2}(R_{-2} + S_{-2}) + (J_{2n+4} - aJ_{2n+3})(R_{-1} - S_{-1}) + J_{2n+3}(R_0 + S_0)}{cJ_{2n+2}(R_{-2} + S_{-2}) + (J_{2n+4} - aJ_{2n+3})(R_{-1} - S_{-1}) + J_{2n+3}(R_0 + S_0)}, \\
  y_{2n+1} &= \frac{cJ_{2n+1}(R_{-2} + S_{-2}) + (J_{2n+3} - aJ_{2n+2})(R_{-1} - S_{-1}) + J_{2n+2}(R_0 + S_0)}{cJ_{2n+1}(R_{-2} + S_{-2}) + (J_{2n+3} - aJ_{2n+2})(R_{-1} - S_{-1}) + J_{2n+2}(R_0 + S_0)}, \\
  y_{2n+2} &= \frac{cJ_{2n+2}(R_{-2} - S_{-2}) + (J_{2n+4} - aJ_{2n+3})(R_{-1} + S_{-1}) + J_{2n+3}(R_0 - S_0)}{cJ_{2n+2}(R_{-2} - S_{-2}) + (J_{2n+4} - aJ_{2n+3})(R_{-1} + S_{-1}) + J_{2n+3}(R_0 - S_0)}, \\
\end{align*}
\] (3.7) (3.8)
Then,

\[
\begin{align*}
x_{2n+1} &= cJ_{2n+1} + (J_{2n+3} - aJ_{2n+2}) \frac{R_{-1} + S_{-1}}{R_{-2} - S_{-2}} + J_{2n+2} \frac{R_0 - S_0}{R_{-2} - S_{-2}}, \\
x_{2n+2} &= cJ_{2n} + (J_{2n+2} - aJ_{2n+1}) \frac{R_{-1} + S_{-1}}{R_{-2} - S_{-2}} + J_{2n+1} \frac{R_0 + S_0}{R_{-2} - S_{-2}}, \\
y_{2n+1} &= cJ_{2n+1} + (J_{2n+3} - aJ_{2n+2}) \frac{R_{-1} - S_{-1}}{R_{-2} + S_{-2}} + J_{2n+2} \frac{R_0 + S_0}{R_{-2} + S_{-2}}, \\
y_{2n+2} &= cJ_{2n} + (J_{2n+2} - aJ_{2n+1}) \frac{R_{-1} - S_{-1}}{R_{-2} + S_{-2}} + J_{2n+1} \frac{R_0 - S_0}{R_{-2} + S_{-2}},
\end{align*}
\]  

(3.9)

We have

\[
\begin{align*}
x_{-1} &= \frac{u_0 - 1}{v_{-2}} = \frac{R_{-1} + S_{-1}}{R_{-2} - S_{-2}}, & x_0 &= \frac{u_0}{v_{-1}} = \frac{R_0 + S_0}{R_{-1} - S_{-1}}, \\
y_{-1} &= \frac{u_2 - 1}{u_{-2}} = \frac{R_{-1} - S_{-1}}{R_{-2} + S_{-2}}, & y_0 &= \frac{v_0}{u_{-1}} = \frac{R_0 - S_0}{R_{-1} + S_{-1}}.
\end{align*}
\]  

(3.11)

(3.12)

From (3.11), (3.12) it follows that,

\[
\begin{align*}
\begin{cases}
\frac{R_0 - S_0}{R_{-2} - S_{-2}} &= \frac{R_{-1} + S_{-1}}{R_{-2} - S_{-2}} \times \frac{R_0 - S_0}{R_{-1} - S_{-1}} = x_{-1}y_0 \\
\frac{R_0 + S_0}{R_{-2} + S_{-2}} &= \frac{R_{-1} - S_{-1}}{R_{-2} + S_{-2}} \times \frac{R_0 + S_0}{R_{-1} + S_{-1}} = x_0y_{-1}
\end{cases}
\end{align*}
\]  

(3.13)

Using (3.9), (3.10), (3.11), (3.12) and (3.13), we obtain the closed form of the solutions of (1.1), that is for \( n = 0, 1, \ldots \), we have

\[
\begin{align*}
x_{2n+1} &= \frac{cJ_{2n+1} + (J_{2n+3} - aJ_{2n+2})x_{-1} + J_{2n+2}x_{-1}y_0}{cJ_{2n} + (J_{2n+2} - aJ_{2n+1})x_{-1} + J_{2n+1}x_{-1}y_0}, \\
x_{2n+2} &= \frac{cJ_{2n+2} + (J_{2n+4} - aJ_{2n+3})y_{-1} + J_{2n+3}x_0y_{-1}}{cJ_{2n+1} + (J_{2n+3} - aJ_{2n+2})y_{-1} + J_{2n+2}x_0y_{-1}}.
\end{align*}
\]
\[
\begin{aligned}
\begin{cases}
y_{2n+1} &= \frac{c J_{2n+1} + (J_{2n+3} - a J_{2n+2}) y_{-1} + J_{2n+2} x_0 y_{-1}}{c J_{2n} + (J_{2n+2} - a J_{2n+1}) y_{-1} + J_{2n+1} x_0 y_{-1}}, \\
y_{2n+2} &= \frac{c J_{2n+2} + (J_{2n+4} - a J_{2n+3}) x_{-1} + J_{2n+3} x_{-1} y_0}{c J_{2n+1} + (J_{2n+3} - a J_{2n+2}) x_{-1} + J_{2n+2} x_{-1} y_0}.
\end{cases}
\end{aligned}
\]

\[\square\]

Remark 2. Writing system (1.1) in the form
\[
\begin{aligned}
\begin{cases}
x_{n+1} &= f(x_n, x_{n-1}, y_n, y_{n-1}) = \frac{a y_n x_{n-1} + b x_n + c}{y_n x_{n-1}}, \\
y_{n+1} &= g(x_n, x_{n-1}, y_n, y_{n-1}) = \frac{a x_n y_{n-1} + b y_{n-1} + c}{x_n y_{n-1}}.
\end{cases}
\end{aligned}
\]

So it follows that points \((\alpha, \alpha), (\beta, \beta)\) and \((\gamma, \gamma)\) are solutions of the of system
\[
\begin{aligned}
\begin{cases}
\bar{x} &= \frac{\alpha \bar{x} + b \bar{x} + c}{\bar{y}}, \\
\bar{y} &= \frac{\alpha \bar{y} + b \bar{y} + c}{\bar{x}}
\end{cases}
\end{aligned}
\]

where \(\alpha, \beta\) and \(\gamma\) are the roots of (2.2).

Theorem 2. Under the same conditions in Lemma 1, for every well defined solution of system (1.1), we have
\[
\lim_{n \to +\infty} x_{2n+1} = \lim_{n \to +\infty} x_{2n+2} = \lim_{n \to +\infty} y_{2n+1} = \lim_{n \to +\infty} y_{2n+2} = \alpha.
\]

Proof. We have
\[
\begin{aligned}
\lim_{n \to +\infty} x_{2n+1} &= \lim_{n \to +\infty} \frac{c J_{2n+1} + (J_{2n+3} - a J_{2n+2}) x_{-1} + J_{2n+2} y_{-1}}{c J_{2n} + (J_{2n+2} - a J_{2n+1}) x_{-1} + J_{2n+1} y_{-1}}, \\
\lim_{n \to +\infty} x_{2n+2} &= \lim_{n \to +\infty} \frac{c J_{2n+2} + (J_{2n+4} - a J_{2n+3}) x_{-1} + J_{2n+3} y_{-1}}{c J_{2n+1} + (J_{2n+3} - a J_{2n+2}) x_{-1} + J_{2n+2} y_{-1}}
\end{aligned}
\]

In the same way we show that
\[
\lim_{n \to +\infty} x_{2n+2} = \lim_{n \to +\infty} y_{2n+1} = \lim_{n \to +\infty} y_{2n+1} = \alpha.
\]

\[\square\]

4. Particular cases

Here we are interested in some particular cases of system (1.1). Some of these particular cases were been the subject of some recent papers.
4.1. The solutions of the equation $x_{n+1} = \frac{ax_n x_{n-1} + bx_{n-1} + c}{x_n x_{n-1}}$

If we choose $y_1 = x_1$ and $y_0 = x_0$, then system (1.1) is reduced to the equation

$$x_{n+1} = \frac{a x_n x_{n-1} + b x_{n-1} + c}{x_n x_{n-1}}, \quad n \in \mathbb{N}_0.$$  \hspace{1cm} (4.1)

The following results are respectively direct consequences of Theorem 1 and Theorem 2.

**Corollary 1.** Let $\{x_n\}_{n \geq -1}$ be a well defined solution of the equation (4.1). Then for $n = 0, 1, \ldots$, we have

$$x_{2n+1} = \frac{c J_{2n+1} + (J_{2n+3} - a J_{2n+2}) x_{-1} + J_{2n+2} x_{-1} x_0}{c J_{2n} + (J_{2n+2} - a J_{2n+1}) x_{-1} + J_{2n+1} x_{-1} x_0},$$

$$x_{2n+2} = \frac{c J_{2n+2} + (J_{2n+4} - a J_{2n+3}) x_{-1} + J_{2n+3} x_{-1} x_0}{c J_{2n+1} + (J_{2n+3} - a J_{2n+2}) x_{-1} + J_{2n+2} x_{-1} x_0}.$$

**Corollary 2.** Under the same conditions in Lemma 1, for every well defined solution of equation (4.1), we have

$$\lim_{n \to +\infty} x_{2n+1} = \lim_{n \to +\infty} x_{2n+2} = \alpha.$$

The equation (4.1) was been studied by Azizi in [2] and Stevic in [17].

4.2. The solutions of the system

$$x_{n+1} = \frac{y_n x_{n-1} + x_{n-1} + 1}{y_n x_{n-1}}, \quad y_{n+1} = \frac{x_n y_{n-1} + y_{n-1} + 1}{x_n y_{n-1}},$$

Consider the system

$$x_{n+1} = \frac{y_n x_{n-1} + x_{n-1} + 1}{y_n x_{n-1}}, \quad y_{n+1} = \frac{x_n y_{n-1} + y_{n-1} + 1}{x_n y_{n-1}} \quad n \in \mathbb{N}_0.$$  \hspace{1cm} (4.2)

Clearly the system (4.2) is particular of the system (1.1) with $a = b = c = 1$. In this case the sequence $\{J_n\}$ is the famous classical sequence of Tribonacci numbers $\{T_n\}$, that is

$$T_{n+3} = T_{n+2} + T_{n+1} + T_n, \quad n \in \mathbb{N}, \text{ where } T_0 = 0, T_1 = 1 \text{ and } T_2 = 1,$$

and we have

$$T_n = \frac{a^{n+1}}{(\beta - \alpha)(\gamma - \alpha)} - \frac{\beta^{n+1}}{(\beta - \alpha)(\gamma - \beta)} + \frac{\gamma^{n+1}}{(\gamma - \alpha)(\gamma - \beta)}, \quad n = 0, 1, \ldots,$$

with

$$\alpha = \frac{1 + \sqrt[3]{19} + 3\sqrt[3]{33} + \sqrt[3]{19-3\sqrt[3]{33}}}{3},$$
\[ \beta = \frac{1 + \omega \sqrt[3]{19 + 3\sqrt{33}} + \omega^2 \sqrt[3]{19 - 3\sqrt{33}}}{3}, \]
\[ \gamma = \frac{1 + \omega^2 \sqrt[3]{19 + 3\sqrt{33}} + \omega \sqrt[3]{19 - 3\sqrt{33}}}{3}, \quad \omega = -1 + i\sqrt{3}. \]

Numerically we have \( \alpha = 1.839286755 \) and the two complex conjugate are
\[-0.4196433777 + 0.6062907300i, -0.4196433777 - 0.6062907300i\]
with \( i^2 = -1. \)

The following results follows respectively from Theorem 1 and Theorem 2.

**Corollary 3.** Let \( \{x_n, y_n\}_{n\geq 1} \) be a well defined solution of (4.2). Then, for \( n = 0, 1, 2, 3, \ldots \), we have
\[
\begin{align*}
x_{2n+1} &= \frac{cT_{2n+1} + (T_{2n+3} - aT_{2n+2})x_{-1} + T_{2n+2}x_{-1}y_0}{cT_{2n} + (T_{2n+2} - aT_{2n+1})x_{-1} + T_{2n+1}x_{-1}y_0}, \\
x_{2n+2} &= \frac{cT_{2n+2} + (T_{2n+4} - aT_{2n+3})y_{-1} + T_{2n+3}y_{-1}}{cT_{2n+1} + (T_{2n+3} - aT_{2n+2})y_{-1} + T_{2n+2}y_{-1}}, \\
y_{2n+1} &= \frac{cT_{2n+1} + (T_{2n+3} - aT_{2n+2})y_{-1} + T_{2n+2}y_{-1}}{cT_{2n} + (T_{2n+2} - aT_{2n+1})y_{-1} + T_{2n+1}y_{-1}}, \\
y_{2n+2} &= \frac{cT_{2n+2} + (T_{2n+4} - aT_{2n+3})y_{-1} + T_{2n+3}y_{-1}}{cT_{2n+1} + (T_{2n+3} - aT_{2n+2})y_{-1} + T_{2n+2}y_{-1}}.
\end{align*}
\]

**Corollary 4.** For every well defined solution of system (1.1), we have
\[ \lim_{n \to +\infty} x_{2n+1} = \lim_{n \to +\infty} x_{2n+2} = \lim_{n \to +\infty} y_{2n+1} = \lim_{n \to +\infty} y_{2n+2} = \alpha. \]

For the equation
\[ x_{n+1} = \frac{x_n x_{n-1} + x_{n-1} + 1}{x_n x_{n-1}}, \quad n \in \mathbb{N}_0. \quad (4.3) \]

we have the following results.

**Corollary 5.** Let \( \{x_n\}_{n\geq 1} \) be a well defined solution of the equation (4.3). Then for \( n = 0, 1, \ldots \), we have
\[
\begin{align*}
x_{2n+1} &= \frac{T_{2n+1} + (T_{2n+3} - T_{2n+2})x_{-1} + T_{2n+2}x_{-1}y_0}{T_{2n} + (T_{2n+2} - T_{2n+1})x_{-1} + T_{2n+1}x_{-1}y_0}, \\
x_{2n+2} &= \frac{T_{2n+2} + (T_{2n+4} - T_{2n+3})x_{-1} + T_{2n+3}x_{-1}}{T_{2n+1} + (T_{2n+3} - T_{2n+2})x_{-1} + T_{2n+2}x_{-1}}.
\end{align*}
\]
Corollary 6. Under the same conditions in Lemma 1, for every well defined solution of the equation (4.3), we have

\[ \lim_{n \to +\infty} x_{2n+1} = \lim_{n \to +\infty} x_{2n+2} = \alpha. \]

Let \( I = (0, +\infty) \), \( J = (0, +\infty) \) and choosing \( x_-1, x_0, y_-1 \) and \( y_0 \in (0, +\infty) \). Then clearly the system

\[
\begin{align*}
\bar{x} &= f(\bar{x}, \bar{y}) = \frac{\bar{xy} + \bar{x} + 1}{\bar{xy}}, \\
\bar{y} &= g(\bar{x}, \bar{y}) = \frac{\bar{xy} + \bar{y} + 1}{\bar{xy}}
\end{align*}
\]

has a unique solution \((\alpha, \alpha) \in I \times J\), that is \((\alpha, \alpha)\) is the unique equilibrium point (fixed point) of our system

\[
\begin{align*}
x_{n+1} &= f(x_n, x_{n-1}, y_n, y_{n-1}) = \frac{y_n x_{n-1} + x_{n-1} + 1}{y_n x_{n-1}}, \\
y_{n+1} &= g(x_n, x_{n-1}, y_n, y_{n-1}) = \frac{x_n y_{n-1} + y_{n-1} + 1}{x_n y_{n-1}}.
\end{align*}
\]

Clearly the functions

\[ f : I^2 \times J^2 \to I \quad \text{and} \quad g : I^2 \times J^2 \to I \]

defined by

\[ f(u_0; u_1; v_0; v_1) = \frac{v_0 u_1 + u_1 + 1}{v_0 u_1} \quad \text{and} \quad g(u_0; u_1; v_0; v_1) = \frac{u_0 v_1 + v_1 + 1}{u_0 v_1} \]

are continuously differentiable.

In the following result we prove that the unique equilibrium point \((\alpha, \alpha)\) of (4.2) is locally asymptotically stable.

Theorem 3. The equilibrium point \((\alpha, \alpha)\) is locally asymptotically stable.

Proof. The Jacobian matrix associated to the system (4.2) around the equilibrium point \((\alpha, \alpha)\), is given by

\[
A = \begin{pmatrix}
0 & -\frac{1}{\alpha^3} & -\frac{\alpha + 1}{\alpha^3} & 0 \\
1 & 0 & 0 & 0 \\
-\frac{\alpha + 1}{\alpha^3} & 0 & 0 & -\frac{1}{\alpha^3} \\
0 & 0 & 0 & 1
\end{pmatrix}.
\]

Then, the characteristic polynomial of \(A\) is

\[ P(\lambda) = \lambda^4 + \frac{(2\alpha^3 - \alpha^2 - 2\alpha - 1)}{\alpha^6} \lambda^2 + \frac{1}{\alpha^6} \]
and the roots of $P(\lambda)$ are

\[
\lambda_1 = \frac{1}{2} \times \frac{1 + \alpha + \sqrt{-4\alpha^3 + \alpha^2 + 2\alpha + 1}}{\alpha^3},
\]

\[
\lambda_2 = -\frac{1}{2} \times \frac{1 + \alpha + \sqrt{-4\alpha^3 + \alpha^2 + 2\alpha + 1}}{\alpha^3},
\]

\[
\lambda_3 = \frac{1}{2} \times \frac{-1 - \alpha + \sqrt{-4\alpha^3 + \alpha^2 + 2\alpha + 1}}{\alpha^3},
\]

\[
\lambda_4 = -\frac{1}{2} \times \frac{-1 - \alpha + \sqrt{-4\alpha^3 + \alpha^2 + 2\alpha + 1}}{\alpha^3}.
\]

We have $|\lambda_i| < 1$, $i = 1, 2, 3, 4$, so the equilibrium point $(\alpha, \alpha)$ is locally asymptotically stable. \[\square\]

The following result is a direct consequence of Theorem 3 and Corollary 4.

**Theorem 4.** The equilibrium point $(\alpha, \alpha)$ is globally asymptotically stable.

Let $I = (0, +\infty)$ and choosing $x_{-1}, x_0 \in (0, +\infty)$. Writing the equation (4.3) as

\[
x_{n+1} = h(x_n, x_{n-1}) = \frac{x_n x_{n-1} + x_{n-1} + 1}{x_n x_{n-1}} \tag{4.4}
\]

where

\[
h : I^2 \longrightarrow I
\]

is defined by

\[
h(u_0; u_1) = \frac{u_0 u_1 + u_1 + 1}{u_0 u_1}.
\]

The function $h$ is continuously differentiable. The equation $\bar{x} = h(\bar{x}, \bar{x})$ has the unique solution $\bar{x} = \alpha$ in $(0, +\infty)$. The linear equation associated to the equation (4.4) about the equilibrium point $x = \alpha$ is given by

\[
y_{n+1} = \frac{\partial h}{\partial u_0}(\alpha, \alpha) y_n + \frac{\partial h}{\partial u_1}(\alpha, \alpha) y_{n-1},
\]

the last equation has as characteristic polynomial

\[
Q(\lambda) = \lambda^2 - \frac{\partial h}{\partial u_0}(\alpha, \alpha) \lambda - \frac{\partial h}{\partial u_1}(\alpha, \alpha).
\]

In the following result we show that the unique equilibrium point $\bar{x} = \alpha$ is globally stable.

**Theorem 5.** The equilibrium point $\bar{x} = \alpha$ is globally stable.
Proof. The linear equation associated to (4.3) about the equilibrium point $\bar{x} = \alpha$ is

$$y_{n+1} = -\frac{\alpha + 1}{\alpha^3} y_n - \frac{1}{\alpha^3} y_{n-1}$$

and the characteristic polynomial is

$$Q(\lambda) = \lambda^2 + \left(\frac{\alpha + 1}{\alpha^3}\right) \lambda + \left(\frac{1}{\alpha^3}\right).$$

We have

$$\left|\frac{\alpha + 1}{\alpha^3} - \lambda + \frac{1}{\alpha^3}\right| \leq \left|\frac{\alpha + 1}{\alpha^3}\right| + \frac{1}{\alpha^3} < 1 = |\lambda|^2, \forall \lambda \in \mathbb{C} : |\lambda| = 1.$$

So, by Rouché’s theorem the roots of the characteristic polynomial $Q(\lambda)$ lie in the open unit disk. Then the equilibrium point $\bar{x} = \alpha$ is locally asymptotically stable. Now, from this and Corollary 6 the result holds. □

4.3. The system

$$x_{n+1} = \frac{bx_{n-1} + c}{y_n x_{n-1}}, \quad y_{n+1} = \frac{by_{n-1} + c}{x_n y_{n-1}}$$

When $a = 0$, the system (1.1) takes the form

$$x_{n+1} = \frac{bx_{n-1} + c}{y_n x_{n-1}}, \quad y_{n+1} = \frac{by_{n-1} + c}{x_n y_{n-1}} \quad n \in \mathbb{N}_0. \quad (4.5)$$

From Theorem (1), we get the following result.

Corollary 7. Let $\{x_n, y_n\}_{n \geq -1}$ be a well defined solution of (4.5). Then, for $n = 0, 1, \ldots$, we have

$$x_{2n+1} = \frac{cP_{2n+1} + P_{2n+3}x_{-1} + P_{2n+2}x_{-1}y_0}{cP_{2n} + P_{2n+2}x_{-1} + P_{2n+1}x_{-1}y_0},$$

$$y_{2n+2} = \frac{cP_{2n+2} + P_{2n+4}y_{-1} + P_{2n+3}y_{0}y_{-1}}{cP_{2n+1} + P_{2n+3}y_{-1} + P_{2n+2}y_{0}y_{-1}},$$

$$x_{2n+2} = \frac{cP_{2n+2} + P_{2n+4}x_{-1} + P_{2n+3}x_{-1}y_0}{cP_{2n+1} + P_{2n+3}x_{-1} + P_{2n+2}x_{-1}y_0}.$$

Here we have write $\{P_n\}_n$ instead of $\{J_n\}_n$, as in this case $\{J_n\}_n$ takes the form of a generalized (Padovan) sequence, that is

$$P_{n+3} = bP_{n+1} + cP_n, \quad n \in \mathbb{N}.$$
with special values \( P_0 = 0, P_1 = 1 \) and \( P_2 = 0 \). The system (4.5) was been investigated by Halim et al. in [8] and by Yazlik et al. in [21] with \( b = 1 \) and \( c = \pm 1 \). The one dimensional version of system (4.5), that is the equation
\[
x_{n+1} = \frac{bx_{n-1} + c}{x_n x_{n-1}}, \quad n \in \mathbb{N}_0.
\]
was been also investigated by Halim et al. in [8]. From Corollary (7), we get that the well defined solutions of equation (4.6) are given for \( n = 0, 1, \ldots \), by
\[
x_{2n+1} = \frac{cP_{2n+1} + P_{2n+2}x_{n-1} + P_{2n+3}x_{n-1}x_0}{cP_{2n} + P_{2n+1}x_{n}x_0},
\]
\[
x_{2n+2} = \frac{cP_{2n+2} + P_{2n+3}x_{n} + P_{2n+4}x_{n-1}}{cP_{2n+1} + P_{2n+2}x_{n}x_0}.
\]
In [21] and [8] we can find additional results on the stability of some equilibrium points.

**Remark 3.** If \( c = 0 \), The system (1.1) become
\[
x_{n+1} = \frac{ay_n + b}{y_n}, \quad y_{n+1} = \frac{ax_n + b}{x_n}, \quad n \in \mathbb{N}_0.
\]
We note that if also \( b = 0 \), then the solutions of the system (4.7) are given by
\[
\{(x_0, y_0), (a, a), (a, a), \ldots \}.
\]
The system (4.7) is a particular case of the more general system
\[
x_{n+1} = \frac{ay_n + b}{cy_n + d}, \quad y_{n+1} = \frac{ax_n + \beta}{y_n x_n + \gamma}, \quad n \in \mathbb{N}_0
\]
which was been completely solved by Stevic in [16]. So, we refer to this paper for the readers interested in the form of the solutions of the system (4.8) and its particular case system (4.7). As it was proved in [16], the solutions are expressed using the terms of a corresponding generalized Fibonacci sequence. Noting that the papers [11], [18] and [19] deals also with particular cases of the system (4.8) or its one dimensional version.

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