Quantifying Adaptability in Pre-trained Language Models with 500 Tasks

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Abstract

When a neural language model (LM) is adapted to perform a new task, what aspects of the task predict the eventual performance of the model? In NLP, systematic features of LM generalization to individual examples are well characterized, but systematic aspects of LM adaptability to new tasks are not nearly as well understood. We present a large-scale empirical study of the features and limits of LM adaptability using a new benchmark, TASKBENCH500, built from 500 procedurally generated sequence modeling tasks. These tasks combine core aspects of language processing, including lexical semantics, sequence processing, memorization, logical reasoning, and world knowledge. Using TASKBENCH500, we evaluate three facets of adaptability, finding that: (1) adaptation procedures differ dramatically in their ability to memorize small datasets; (2) within a subset of task types, adaptation procedures exhibit compositional adaptability to complex tasks; and (3) failure to match training label distributions is explained by mismatches in the intrinsic difficulty of predicting individual labels. Our experiments show that adaptability to new tasks, like generalization to new examples, can be systematically described and understood, and we conclude with a discussion of additional aspects of adaptability that could be studied using the new benchmark.

1 Introduction

Much of the recent research effort in NLP has shifted from training task-specific models to adapting pre-trained language models (LMs) by fine-tuning their parameters or input prompts for downstream tasks (Devlin et al., 2019; Raffel et al., 2020; Li and Liang, 2021; Lester et al., 2021). This paradigm is general, in the sense that a large number of distinct NLP tasks benefit from pre-training (Peters et al., 2018; Devlin et al., 2019; Raffel et al., 2020). But many questions about the nature and limits of LM adaptation remain unanswered. For example: given a new task, can we predict how quickly (and how effectively) pre-trained LMs can be adapted to perform it? From among the variety of different adaptation techniques (e.g. fine-tuning or prompt-tuning), can we predict which one will be most effective? Today, new pre-training and adaptation schemes are evaluated using small suites of curated tasks, typically featuring classification, textual inference, and question answering (Wang et al., 2018, 2019). These benchmarks have been extremely successful in identifying new tools for adaptation, but they are poorly suited for answering larger, structural questions like the ones above.

We present a large-scale study of LM adaptability using a new suite of benchmark tasks called TASKBENCH500. TASKBENCH500 consists of 500 procedurally generated tasks involving lexical semantics, factual information, memorization of random relations, list processing, and logical composition (Figure 1). Analogous to past work that uses synthetic data to characterize LM performance on single examples (Weston et al., 2016; Lake and Baroni, 2018; Saxton et al., 2019; Kim and Linzen, 2020; Keysers et al., 2020; Liu et al., 2021), TASKBENCH500 enables systematic study of LM adaptability at the task level. In this paper, we use it to study three aspects of adaptability:

1 Data and code available at: https://github.com/belindal/TaskBench500
1) Define tasks

Atomic Tasks
- antonym
- translate
- is-noun

Composition Functions
- chaining
- union
- intersection
- filter

Compositional Tasks
- child
- occupation

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2) Make datasets for each task

| Parent Task | Child Task |
|-------------|------------|
| child       | occupation |
| is-noun     |             |

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3) Adapt model to each task

| Pre-trained Model | Fixed |
|-------------------|-------|
| Dataset           | Devlin et al., 2019 |

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Figure 1: Overview of our task creation process. We begin by defining a set of atomic tasks that all synthetic tasks are built upon. These include lexical tasks (blue text/outline), random tasks (green text/outline), and factual tasks (orange text/outline). They also include both predicates and relations. These tasks are combined using composition functions to form more complex, compositional tasks. Given a particular task specification, we synthetically create a dataset for each task. Finally, we fine-tune or prompt-tune a pre-trained language model on each task dataset.

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ing, which in standard configurations struggles to memorize even small random word pair lists.

**Composition:** Is LM performance on simple tasks predictive of their performance on compositions of those tasks? (If the father and occupation relations are easy to learn via adaptation, does this imply that the father’s occupation relation is also easy to learn?) We find a nuanced answer. LMs exhibit compositional adaptation to lexical and factual relations (like father’s occupation), with success on composed tasks strongly correlated ($r^2 > 0.5$) with success on atomic tasks. However, when composing these relations with sequence processing operations, success on the base task does not predict success on the composed task.

**Distribution matching:** In models fine-tuned on datasets exhibiting a distribution of acceptable answers (e.g., translating ungendered pronouns into gendered ones), do model predictions match these distributions? We find that LMs are often unable to match label distributions in datasets used for adaptation. In particular, when labels in the fine-tuning dataset are drawn from a uniform mixture of labels from two tasks (e.g., labeling half of the words with their antonym and half with their synonym), models disproportionately assign mass to labels from the task that is easier to learn.

Each of these forms of adaptability corresponds to a central challenge in NLP: reliable updating of deployed models, composition of previously learned skills, and fair and predictable output from models trained on curated data. Our study of composition has a direct analog in previous studies of generalization at the example level (Lake and Baroni, 2018; Ruis et al., 2020; Kim and Linzen, 2020; Keysers et al., 2020). Memorization and distribution matching, however, are nontrivial only in the context of adaptation, and are currently quite poorly studied. Our experiments highlight important qualitative differences between current adaptation paradigms; identify several novel challenges for LM adaptation, and offer a new benchmark for approaches aimed at meeting these challenges.

2 Background

**Fine-tuning and prompt search** In languages for which large digitized corpora are available, most NLP system development today involves adaptation of a pre-trained model to a downstream task of interest. Pre-training typically involves re-construction of masked or corrupted text sampled from a large corpus (Devlin et al., 2019; Liu et al., 2019; Raffel et al., 2020). Adaptation to a new task typically involves one of three approaches: (1) fine-tuning of all of a pre-trained model’s parameters (possibly in conjunction with a specialized decoder) on a task-specific training set (Devlin et al., 2019); (2) manual prompt engineering of an input template that induces pre-trained model predictions to perform the task of interest (Brown et al., 2020; Petroni et al., 2019); or (3) automated prompt tuning of these templates, in either the discrete space of tokens (Shin et al., 2020) or continuous space of token embeddings (Li and Liang, 2021; Lester
The latter two approaches have grown more popular as pre-trained models have grown larger. The performance of both prompt-search approaches still lags fine-tuning (Raffel et al., 2020; Brown et al., 2020; Lester et al., 2021), though the difference between approaches appears to shrink as model size increases (Lester et al., 2021).

Measuring generalization and adaptability

The success of the training paradigm described above stems from its generality—a large number of NLP tasks appear to benefit from some combination of pre-training and adaptation. Previous attempts to quantify this generality have typically relied on benchmarks like GLUE (Wang et al., 2018) and SuperGLUE (Wang et al., 2019), each of which aggregates ten natural language processing tasks designed to probe different aspects of language understanding. Similar benchmarks have also been built for non-English languages (Xu et al., 2020; Kakwani et al., 2020; Park et al., 2021; Hu et al., 2020). However, the heterogeneity and small number of distinct tasks represented in existing benchmarks makes it difficult to make finer-grained predictions, e.g. by identifying specific features of tasks that contribute to the success or failure of adaptation.

This challenge has a direct analog to the problem of characterizing generalization at the example level in models trained for a single task. Model performance on natural test sets is often loosely correlated with accuracy on individual examples featuring rare syntactic constructions or word collocations (McCoy et al., 2019). A great deal of past work has focused on improving evaluation using synthetic evaluation sets (Jia and Liang, 2017; Naik et al., 2018; Lake and Baroni, 2018; Richardson et al., 2020). These datasets have been used to study long-range agreement (Marvin and Linzen, 2018), compositional generalization (Lake and Baroni, 2018; Ruis et al., 2020; Keysers et al., 2020), and mathematical reasoning (Saxton et al., 2019). But no analogous notion of systematicity, or tool for studying it, currently exists for tasks rather than examples.

Thus, building on this past work, we describe how to construct synthetic data distributions that enable systematic study of adaptation to new tasks rather than generalization to new examples. Like previous research that uses procedural data generation procedures to study models in NLP, we focus on coverage rather than naturalness, using datasets designed to complement, rather than replace, existing naturalistic benchmarks.

3 A 500-task benchmark

Our goal is to study the generalizability of task adaptation paradigms. In particular, we would like to identify which attributes of a task make it easy or difficult to learn, across different models and training schemes. While this work shares many of its high-level goals with existing benchmarks built from collections of real-world datasets, the makeup and difficulty of these datasets is often difficult to characterize precisely: differences in annotation standards, annotation quality, and dataset size mean that models often exhibit very different performance on datasets designed to evaluate model performance on the same abstract task. In addition, existing datasets cover an exceedingly small subset of the space of all tasks that future NLP practitioners might wish to perform. To account for all these limitations, we propose to generate tasks synthetically as described below.

The space of tasks

TaskBench500 is constructed compositionally: we begin by defining a space of atomic tasks, which are combined using a set of composition operators to produce more complex tasks. Every task takes as input one or more words, and outputs either a boolean value or a set of word sequences. We refer to any task that outputs booleans as a predicate task, and any task that outputs sets of word sequences as a relation task. A subset of relation tasks involve modeling relations between single words at the input and output; we refer to these as word-level tasks and the remaining relation tasks as sequential tasks.

The choice of atomic tasks and composition functions aims to capture aspects of real language processing tasks. Accordingly, the set of atomic tasks comprises:

1. Lexical tasks, which test knowledge of lexical semantics. These include lexical relations like synonym, or lexical predicates like is-noun. These tasks are constructed from WordNet relations (Fellbaum, 1998).

2. Factual tasks, which test factual knowledge. These include factual relations like father-of, or factual predicates like is-human. These tasks are constructed from Wikidata properties (Vrandečić and Krötzsch, 2014).
3. **Random relation tasks**, which test memorization ability. These are created by mapping a word in the vocabulary to a singleton set containing a random other word. We create 4 random relations with different random seeds.

To recursively create arbitrarily complex tasks, we define a set of **composition functions**. These take tasks as arguments and return other tasks. These functions fall into two categories:

1. **Word-level compositions**, which test ability to combine word-level information in different ways, such as through set or logical operations. These functions take word-level tasks and return other word-level tasks. Examples include intersection and chaining.

2. **Sequential compositions**, which test ability to operate on sequences. These functions convert word-level tasks to sequence-level tasks. There are two functions in this category: map takes a word-level relation task and returns a task that maps a sequence of n words to a set of all possible sequences resulting from applying \( f_{\text{map}} \) to each input word. \(^2\) filter takes word-level predicate tasks and returns a sequence consisting only of words for which the task returns true, preserving the original ordering of those words.

The full list of atomic tasks and composition function can be found in Appendix Tables 4 and 5. We surmise that typical NLP tasks may require some combination of lexical knowledge, factual knowledge, sequential processing, and other task-specific reasoning; our data distribution lets us evaluate all these aspects separately and in combination.

**Datasets for tasks** We create datasets \( \mathcal{D}(f) = \{(x_i, y_i) : x \sim \mathcal{X}_f, y \sim \text{Unif}(f(x_i))\} \) for each task \( f \), where \( \mathcal{X}_f \) is the input distribution for the task, and recalling that \( f(x_i) \) returns a set of possible outputs associated with the input \( x_i \). For all tasks, we randomly partition the dataset into \( \mathcal{D}_{\text{train}}(f) \) and \( \mathcal{D}_{\text{eval}}(f) \) splits.

For **lexical atomic tasks** and their compositions, we directly use the most common words in the task’s input language for \( \mathcal{X}_f \). We use both English and Spanish as input languages. For **factual atomic tasks** and their compositions, we sample the entities from Wikidata that participate in the relation or predicate defined by the task (e.g. for the child task, we sample only entities that have children). For **sequential tasks**, we use a random sampler, which samples \( n \) random words from the vocabulary and concatenates them.

Figure 1 shows examples of tasks and associated datasets. More details on dataset construction can be found in Appendix A.

**4 Experimental Setup**

**Model & Training** For all experiments, we adapt a pre-trained T5-base model (Raffel et al., 2020). We examine two types of training paradigms: fine-tuning and prompt-tuning. During fine-tuning, we update all model parameters on the training set. During prompt-tuning, we follow Lester et al. (2021) and introduce a new set of prompt-tokens \( \{p_1, \cdots, p_n\} \) to the vocabulary, which will be prepended to every sample from the task during inference, i.e., each sample input \( x \) becomes \( p_1p_2\cdots p_nx \). Let \( \theta \) denote the parameters of the original pretrained LM. During training, the entire model is frozen and only the word embeddings of the new tokens \( \{p_1, \cdots, p_n\} \subset \theta \) are updated. We use prompts of length \( n = 100 \) for all experiments. We also study each paradigm on various quantities of training data, and separately evaluate their memorization and generalization adaptabilities. In particular, for word-level tasks the test-set words are disjoint from the train-set words, so evaluating on the test set will strictly measure generalization capacity. We optimize all models using AdamW. See Appendix B for full hyperparameters.

**Evaluation** For each task \( f \) and model \( M[\theta] \) (with parameters \( \theta \)), we measure the model’s average per-token accuracy on both training and test splits of the dataset \( \mathcal{D}(f) \). As each task defines multiple acceptable outputs for each input, we credit models for producing any acceptable output. Letting \( y_i^f = M(x) \), we measure the fraction of positions \( i \) at which any valid answer \( y_i \) matches the predicted \( y_i^f \):

\[
\text{acc}(M, \mathcal{D}(f)) = \max_{y \in f(x)} \sum_{(x,y) \in \mathcal{D}} \left( \frac{1}{n} \sum_{i=1}^{n} \mathbb{1}[y_i = y_i^f] \right)
\]

Further details can be found in Appendix B.

Given a pretrained model \( M[\theta_{\text{pretrain}}] \), an adaptation procedure \( \mathcal{T} \), and a task suite \( f \), let
Figure 2: Left: Overview of the memorization experiment, which evaluates how accurately models adapted via fine-tuning and prompt-tuning can memorize training data. Right: Memorization and generalization curves for fine-tuning and prompt-tuning on 1000 training examples. Memorization curves are shown by solid lines, while generalization curves are dashed. We average over all atomic tasks from each task category: lexical tasks, factual tasks, and random tasks. The region shows the standard error of the mean. Transparent lines are each individual task, colored by task category. In both paradigms, lexical tasks are easiest to memorize, followed by factual tasks, then random tasks. However, prompt-tuning has overall much less memorization capacity than fine-tuning, which can perfectly memorize even completely random relations.

\[ \mathcal{M}(\theta_{T,D(f)}) \] denote the model trained using \( T \) on training data \( D(f) \). We then define the adaptability of a (pretrained model, adaptation paradigm, task suite) as:

\[
adapt(\mathcal{M}(\theta_{\text{pretrain}}, T, f)) = \text{acc}(\mathcal{M}(\theta_{T,D_{\text{train}}(f)}), D_{\text{eval}}(f)) \tag{2}\]

We denote by \( \text{adapt}_{\text{mem}} \) the value of this metric over training data (\( D_{\text{eval}} = D_{\text{train}} \)), and by \( \text{adapt}_{\text{gen}} \) the metric over test data (\( D_{\text{eval}} = D_{\text{test}} \)).

5 Memorizing datasets

Our first experiment investigates the extent to which task adaptation paradigms can memorize different types of tasks. We are interested in memorization because many real NLP tasks involve some degree of memorization. For example, translation builds on memorizing lexical associations between words in various languages, and semantic similarity and paraphrasing require memorizing word meanings and/or groupings of semantically similar words.

Method We use training-set adaptability (\( \text{adapt}_{\text{mem}} \)) as an indicator of a model’s memorization ability (Figure 2). We train on a set of 1000 examples, and plot the value of Eq. 2 on each atomic task as models are adapted via fine-tuning or prompt-tuning. This allows us to visualize both the final training-set performance, as well as the time it took to achieve that performance, both of which we use to quantify memorization ability.

Results Figure 2 shows the training curves for fine-tuning (left) and prompt-tuning (right), on different types of tasks. Solid lines show \( \text{adapt}_{\text{mem}} \), while dashed lines show \( \text{adapt}_{\text{gen}} \).

Under both adaptation paradigms, we find that lexical tasks are easier to memorize than factual tasks, while random tasks are the hardest to memorize. However, for fine-tuning, we find that models can (eventually) learn to perfectly memorize all types of tasks—even entirely random word associations. However, different types of tasks converge at different rates—lexical tasks converge first, followed by factual tasks, followed by random tasks.

Prompt-tuning, with many fewer parameters than fine-tuning, is much less expressive. As shown in Figure 2, none of the tasks types converge to 100% accuracy across tasks. Prompt-tuning overall also takes significantly longer to converge; in particular, on random tasks, the finetuned model generally converges at \( \sim 20k \) updates, while the prompt-tuned model takes over 200k updates to even begin performing nontrivially.

However, despite being much worse at memorization, prompt-tuned models still generalize almost as well as fully fine-tuned models, at least on atomic tasks. This suggests that the inability to memorize arbitrary functions is not necessarily a problem for prompt-tuning in general, and more broadly that overfitting the training set—at least during fine-tuning—may not be necessary for generalization.
Evaluate on test
Evaluate on test
1/2( + )=
Evaluate on test
Evaluate on test
1/2( + )=
Evaluate on test
Evaluate on test
Model chaining
Model cooking
Model child
1. Evaluate compositional task
2. Evaluate constituent tasks
Legend Chaining
Union
Map Map (+separators)

Figure 3: Left: Overview of the composition experiment. We evaluate how well the adaptability on a compositional task can be predicted by the (averaged) adaptabilities of the atomic constituent tasks. Right: Correlation between compositional adaptability vs. averaged atomic adaptabilities, for the chaining, union, and map composition types, under each training paradigm. On word-level chaining and union compositions, compositional adaptability is observed: composed task performance is highly correlated with atomic task performance ($r^2 > 0.5$) under all training paradigms. However, on sequential map compositions, all models perform poorly, and thus non-compositionally. This results from challenges in segmenting input sequences; if token boundaries are explicitly marked (map (+separators)), compositional adaptability is again observed.

Table 1: Model (generalization) adaptabilities to atomic, word-level compositional, and sequential compositional tasks, under full fine-tuning (FFT), full prompt-tuning (FPT), 32-shot fine-tuning (32FT) and 32-shot prompt-tuning (32PT). Prompt-tuned models are comparable to fine-tuned models for atomic tasks, but not for compositional tasks. However, this distinction disappears under few-shot learning.

|               | Atomic | Word-level Comp | Seq Comp |
|---------------|--------|-----------------|----------|
| FFT           | 46.9±4.0 | 39.5±2.1        | 21.5±1.9 |
| FPT           | 42.6±4.3 | 28.1±2.4        | 11.5±1.4 |
| 32FT          | 33.6±3.8 | 22.2±1.8        | 5.7±0.9  |
| 32PT          | 32.4±3.6 | 21.7±1.7        | 6.9±1.1  |

6 Composing tasks

In the previous section, we found that while prompt-tuning cannot memorize arbitrary tasks like fine-tuning, it can still generalize well on simple atomic tasks, almost comparably to fine-tuning. In this section we investigate whether this finding extends to more complex tasks. Specifically, we examine the behavior of prompt-tuned and fine-tuned models when adapted to compositions of atomic tasks.

Many prior studies of compositionality focus on instance-level compositionality (Lake and Baroni, 2018; Keysers et al., 2020): they test whether models can generalize to new instances by combining information from previously-seen instances within the same task. For example, Lake and Baroni (2018) study whether models can learn to jump left, after learning to jump, run, and run left. In our work, we instead focus on task-level compositionality, studying whether models can adapt to new tasks that are compositions of simpler tasks on which they are known to perform well. Thus, while a model exhibiting compositional generalization will correctly compose fragments of previously observed training examples, a training procedure exhibiting compositional adaptability will perform well on tasks involving compositions of previously learned skills.

Method We study adaptation to complex tasks by relating performance on atomic tasks with performance on depth-2 compositional tasks. We also study each paradigm under few-shot learning, by creating a random 32-sample subset of each training dataset, and training on that subset. To mitigate the effect of the random seed, we report average performance over 4 different subsets.

What allows models to adapt to these complex tasks? We hypothesize that their adaptability is (in part) compositional—when they can adapt to
simple tasks, they can also adapt to compositions of those tasks. For each training paradigm $T$ and each composition function $C$, we estimate the Pearson correlation coefficient $r^2$ between adaptability to a compositional task $C(f_1, \cdots, f_n)$,

$$\text{adapt}_{\text{gen}}(M, T, C(f_1, \cdots, f_n)),$$

and average adaptability to the task’s atomic components,

$$\frac{1}{n} \sum_{i=1}^{n} \text{adapt}_{\text{gen}}(M, T, f_i).$$

Figure 3 depicts the procedure graphically.\(^3\)

Can language models learn compositional tasks? The average model adaptability to compositional and atomic tasks, under each training paradigm, is reported in Table 1. We observe that the gap between full-data prompt-tuned models and full-data fine-tuned ones is much larger on compositional tasks than atomic ones. Thus, prompt-tuned models can only generalize comparably to finetuned ones for sufficiently “simple” tasks.

Interestingly, this distinction disappears under few-shot learning. Though both adaptation paradigms generalize much worse in the few-shot setting compared to the full setting, they appear to be comparable to each other in the few-shot setting, even on compositional tasks. This may simply imply that few examples are insufficient to learn the nuances of complex tasks, and that simply learning a few prompt tokens is sufficient to capture what can be learned from the limited data samples.

Do language models adapt compositionally? We visualize each regression model in Figure 3. Higher $r^2$ indicates higher correlation between atomic and compositional versions of tasks. Note that all model training paradigms demonstrate some degree of word-level compositionality ($r^2 > 0.5$)—when they succeed at word-level compositional tasks (union, chaining), they succeed at the atomic constituents to those tasks, and vice versa. However, this does not appear to be the case for sequential map. In the full-data regime, both fine-tuning and prompt-tuning have near-zero $r^2$ values. In the few-shot regime, the $r^2$ value, while nontrivial, is also quite low. Note the slopes of the learned regression lines—the model appears to be unable to learn the sequential versions of tasks, despite succeeding at their atomic versions.

To explain this result, we hypothesize that a major obstacle to sequence-level compositional adaptability is segmentation of sequences into atomic units. This is especially the case for factual tasks: for example, the sequence Pauline Payne Whitney Charles Lloyd could be segmented as [Pauline Payne Whitney] [Charles Lloyd] or [Pauline Payne] [Whitney Charles Lloyd], etc. To test whether segmentation is a bottleneck, we train on a version of sequential tasks where we give the language model explicit markers of word/entity boundaries (e.g. the language model is given Pauline Payne Whitney # Charles Lloyd as input). We found that, with separators, performance on the map tasks increases substantially and the model demonstrates compositional adaptability ($r^2 > 0.5$) to these tasks in 3 of the 4 adaptation paradigms. This setting is plotted in Fig. 3 as $\text{Map} (+\text{separators})$.

7 Learning new distributions

Previous sections investigated the degree to which models could fit particular tasks using a binary metric that assigned credit to any acceptable answer. Our final set of experiments explores a finer-grained notion of correctness: when there are multiple acceptable answers, as is often the case in real NLP tasks, when does the output distribution of a model match the distribution empirically observed during adaptation?

Method We specifically investigate whether models are biased towards predicting “easy” labels, in the sense measured in Section 5. We consider all possible pairs of atomic tasks $f_1, f_2$ within the same category. Let $f_e$ be the easier task in this pair and $f_h$ be the harder task, relative to a model $\mathcal{M}$ and training paradigm $T$, in the sense that, $\text{adapt}_{\text{gen}}(\mathcal{M}, T, f_e) > \text{adapt}_{\text{gen}}(\mathcal{M}, T, f_h)$. We compose $f_e$ and $f_h$ using union to create compositional task $\cup(f_e, f_h)$, and construct the training dataset for this task to be balanced — such that the model sees an equal number of examples of form $(x, f_e(x))$ as $(x, f_h(x))$. Now let $\mathcal{M}_{\cup(f_e, f_h)}$ denote a model adapted to this task. During test-time, we provide $\mathcal{M}_{\cup(f_e, f_h)}$ with novel inputs $x'$ from the domain of both $f_e$ and $f_h$, and record the average probability mass it assigns
to all $y_e^i \in f_e(x')$ versus all $y_h^i \in f_h(x')$.

Finally, we average these dataset-wide probabilities over all pairs of tasks, to get an aggregated probability mass assigned to all easier tasks and all harder tasks in a task pair, invariant of the actual underlying task identity. More details on this procedure can be found in Appendix D.

**Results** Overall, as seen in Figure 4, across all tasks and training paradigms, the model tends to assign a higher probability to the easier relation. As a concrete example, when trained to predict either antonyms or lexical entailments, the average probability mass placed on the antonyms of a word from the held-out set (easier relation) is 13%, while the average probability mass placed on the entailments of a word (harder relation) is 8%.

Thus, despite having a perfectly balanced fine-tuning set, pretrained models still predict label distributions in a way that align with their inductive biases (measured via the “intrinsic difficulty” of individual labels). This holds for all task adaptation methods, including full fine-tuning, meaning even paradigms and models that can fit more complex tasks still have residual biases from pretraining that affect their predictions. This also suggests wider-reaching consequences for model fairness and equity: simply debiasing a fine-tuning dataset is insufficient to overcome biases from pretraining.

### 8 Conclusion

In this paper, we construct **TASKBENCH500**, a synthetic task set which serves as a testbed for task adaptability. We focus on three axes of adaptability: ability to memorize, ability to (compositionally) generalize, and ability to fit to novel distributions. We study two adaptation paradigms: fine-tuning and prompt-tuning, finding that: 1. unlike fine-tuning, prompt-tuning cannot memorize completely arbitrary tasks beyond a small number of examples, 2. all adaptation paradigms demonstrate compositional adaptation to word-level compositions, but not sequence-level compositions, and 3. no paradigm is able to perfectly replicate the downstream distribution—all paradigms learn output distributions that align with its inductive biases.

In future work, **TASKBENCH500** can be used to study other factors that may affect adaptability, such as length of the prompt in prompt-tuning, similarity between the task distribution and the pretraining distribution, or finer-grained distinctions between tasks (beyond lexical/factual/random, or composition type) that predict task adaptability. **TASKBENCH500** can also be used to explore the limitations of prompt engineering on a GPT3-scale model. Finally, the current set of tasks and primitives in **TASKBENCH500** are by no means complete. Future work can expand on these primitives and study the relationships between the tasks put forth here and real NLP tasks.
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A  More details on TaskBench500 creation procedure

A.1  Task creation details

For atomic lexical tasks, we take a subset of relations specified in either Wordnet (Fellbaum, 1998) or SentiWordNet (Esuli and Sebastiani, 2006). For atomic factual tasks, we take a subset of tasks from Wikidata (Vrandečić and Krötzsch, 2014). We also have 3 broad categories of composition functions: set operations, logical operations, and sequential operations. The full list of atomic tasks can be found in Table 4 and the list of composition functions can be found in 5.

We enumerate all possible depth-2 word level compositions of each task, and the sequential versions of them (i.e. if the task is a relation, inserting it into a map, or if the task is a predicate, inserting it into a filter), up to 500 tasks. We also apply some basic heuristics to filter identical tasks: for example, we filter symmetric relations, e.g. union(B,A) is identical to union(A,B), or avoid the use of logical operations alongside set operations, e.g. lor(in(x,A), in(x,B)) is identical to in(x,union(A,B)). Our full list of tasks can be found in Tables 4, 6, 7, and 8.

Sequential compositions  Sequential composition functions convert word-wise tasks to sequence-level tasks. We specifically consider only two sequential functions: map and filter. Note that compositions of multiple maps or multiple filters can instead be expressed as compositions of multiple word-level functions. For example,

\[
\text{map}\{\lambda x. \text{occupation}(x)\}(\text{map}\{\lambda x. \text{father}(x)\}(S))
\]

(for an input sequence S) is equivalent to

\[
\text{map}\{\lambda x. \text{occupation}(\text{father}(x))\}(S)
\]

Specifically, we define the following top-level sequential operator

\[
\text{map-filter}\{f_M, f_F\} = \text{map}\{f_M\}(\text{filter}\{f_F\})
\] (5)

where \(f_M\) is a word-wise relation and \(f_F\) is a word-wise predicate. All recursively-defined sequential operators follow this form. The following are the recursive rules for mapping nested maps and filters into a function of this form: in the base cases,

\[
\text{map}\{f_M\} = \text{map-filter}\{f_M, \lambda x. \text{true}\}
\]

\[
\text{filter}\{f_F\} = \text{map-filter}\{\lambda x. x, f_F\};
\] (6)

in the recursive cases,

\[
\text{map}\{f_M\}(\text{map-filter}\{f_M, f_F\}) = \text{map-filter}\{f_M(f_M), f_F\}
\]

\[
\text{filter}\{f_F\}(\text{map-filter}\{f_M, f_F\}) = \text{map-filter}\{f_M, f_F \wedge f_F(f_M)\}.
\] (7)

A.2  Dataset creation details

Note that many tasks created through composition will be degenerate or identical to other tasks, even with our heuristic filters. We do a preliminary filter for degenerate tasks by removing tasks for which we have less than 100 samples. We also manually inspect all depth-2 word-level lexical compositions to ensure they are nontrivial and unique.

Word-level lexical tasks  For English lexical tasks, we use words that appeared more than 5 times in the Brown corpus (Francis and Kucera, 1979) for our inputs \(x\). For Spanish lexical tasks, we use words that appeared at least once in the CESS Spanish Treebank (Martí et al., 2007) for our inputs. This results in a total of 9143 English words and 5298 Spanish words. We then construct outputs for each input word using either WordNet or SentiWordNet. We filter out inputs for which the relations map to an empty set—thus, for a task like intersection\(\text{synonym}(x), \text{antonym}(x)\), most inputs will be filtered out as the set of synonyms are usually disjoint from the set of antonyms. (This task ends up getting filtered out entirely, as the final number of inputs is under 100.)

Word-level factual tasks  We use a dump of Wikidata from 2017, taken from (Sorokin and Gurevych, 2018).\(^5\) We convert each word-level factual task into SPARQL queries which returns a set of input-output data pairs from Wikidata.

For factual relations \(R\), we create two queries: a sample query which gives us a set of entities that participate in the relation, from which the inputs \(x\) are derived, and a function query that maps specific inputs \(x\) to its set of output entities \(R(x)\). For factual predicates \(P\), we create three queries: a positive sample query which gives samples \(x\) for which \(P(x) = \text{true}\), a negative sample query which gives samples \(x\) for which \(P(x) = \text{false}\), and a function query that maps specific inputs \(x\) to its output boolean value \(P(x)\).

\(^5\)https://public.ukp.informatik.tu-darmstadt.de/wikidata-dump/wikidata-virtuoso-dump-2017.zip
Table 2: Rules for mapping word-level factual tasks to SPARQL conditional statements. Blue substrings represent recursive calls to this set of rules, which are to be replaced with their output SPARQL fragments. Note the second argument to the `sparql` function represents the variable name to output to.

The SPARQL query is generated recursively given the specification of the task. We define a function `task2sparql(T(x), y)` which converts tasks `T(x)` to SPARQL fragments (where the second argument to the function is the variable name we define for the output). We then convert the output of this function into a well-formed query using:

```sql
SELECT ?x WHERE <task2sparql(T(x), y)>
```

for sample queries and

```sql
SELECT ?y WHERE <task2sparql(T(x), y)>
```

for functions queries. Note for function queries that the input `x` is provided to us (and is not a variable).

The general rules specifying the `task2sparql` function are given in Table 2.

### Sequential tasks
In practice, naively concatenating outputs from a random word sampler to create sequences will return degenerate or trivial sequences for many functions (for example, `map{λ x. child(x)}` is not meaningful for sequences consisting of words that don’t refer to humans). Thus, we define a sequence sampler that takes in a sequential function (given in the form from eq. 5), an input length `n` and an output length `m ≤ n`, which will always sample sequences with length `n` such that the output, when the function is applied to the sequence, is of length `m`.

```sql
function seq_sampler(map-filter(f_M, f_F), n, m): seq ← "";
for i = 1 · · · n do
    word ∼ Unif(domain(f_M) ∩ {x : f_F(x) = true});
    seq ← seq + word
end
for j = n · · · m do
    word ∼ Unif({x : f_F(x) = false});
    seq ← seq + word
end
seq ← permute-words(seq)
```

At a high level, this algorithm samples `n` input words which are in the domain of the map relation, and for which the filter predicate returns `true`, and `m − n` input words for which the filter predicate returns `false`, then permutes and concatenates them.

### B Experimental Setup Details

#### Hyperparameters
We adapt a pre-trained T5-base model (24-layer, 220M parameters) to our tasks. We use an AdamW optimizer with a learning rate of 1.0 for all prompt-tuning experiments, and learning rate of 1e-3 for all fine-tuning experiments. We use batch sizes of 64 for word-level tasks, and 32 for sequential tasks. We run all experiments up to 100 epochs, and run 3–4 trials for each few-shot experiment to estimate average performance over possible choices of few-shot training samples.

#### Infrastructure and Reproducibility
For each task, we adapt our model using a single 32GB NVIDIA V100 GPU, or a single 40GB NVIDIA A100 GPU. Training time varies by training dataset size and maximum number of epochs, but on average (using the hyperparameters specified above) is less than a few hours per task. Prompt-tuning is also more efficient than fine-tuning, updating the parameters of only 100 prompt tokens vs. the full 220M parameters in the model.

#### Evaluation of Sequential Tasks
When evaluating accuracies of sequential tasks (equation 1), note that we must align words in the generated sequence `y′ i` with words in the ground-truth sequence `y i`. However, this can be nontrivial, especially under the setting where word and entity boundaries are not explicitly generated by the model. We cannot rely on whitespaces to segment words as a single word can span multiple white-spaces; for example, an entity Will Smith constitutes a single word. Instead, given a ground-truth sequence of `n` words (note ground-truth segmentations are present in the dataset), we optimize over all possible length-`n` segmentations of the generated sequence.
Figure 5: Compositionality of map function, when token separators are explicitly provided in the input and output. All adaptation paradigms demonstrate compositionality except for full fine-tuning, where there seems to be a large proportion of tasks for which the model can adapt to sequentially but not atomically.

C Compositionality Experiment: Additional Results

Additional results for the compositionality experiment, including all composition functions, and the formula for the best-fit regression line in each case, are reported in Table 3.

Note for the map task that under the explicit segmentation setting (+separators), full fine-tuning is the only training paradigm that doesn’t demonstrate compositional adaptability. This experiment is plotted in isolation in Figure 5. Note the distribution of points in the full fine-tuning case: for a significant number of tasks, the model seems to be able to adapt to their sequential versions despite failing at their atomic version. This suggests that in these cases, the model does not simply adapt compositionally, but can take advantage of additional information present in sequences (e.g., seeing more tokens, more examples of the word-level function) to outperform compositional adaptation.

D Prediction distribution experiment: Additional details

We adapt the model to the task $\bigcup(f_e, f_h)$, constructing the training dataset for $\bigcup(f_e, f_h)$ to be balanced — such that the model sees an equal number of examples of form $(x, f_e(x))$ as $(x, f_h(x))$.

Let $M_{\bigcup(f_e, f_h)}$ denote a model adapted to this task. Note that the domains of either function are not always identical, for example the set of entities in the domain of political-party-of(x) (mostly politicians) is different from the set of entities in the domain of position-played-on-sports-team(x) (mostly athletes). We create a balanced training set by first taking all items in the intersection of both domains, then sampling an equal number number of items in either domain. Furthermore, to minimize the effect of the order seen during training, we shuffle the entire dataset after creating all example-label pairs. Thus on average, we would expect half the examples to have $(x, f_e(x))$ preceding $(x, f_h(x))$, and half to have $(x, f_e(x))$ preceding $(x, f_h(x))$.

During test-time, we give $M_{\bigcup(f_e, f_h)}$ a novel input $x'$ and record the average probability mass it assigned to all $y_e \in f_e(x')$ vs. all $y_h \in f_h(x')$. Note we evaluate only on inputs $x'$ which are in the domain of both $f_e$ and $f_h$. Under the rare scenario that a prediction is in both target tasks for a particular word (i.e. $y$ is in both $f_e(x')$ and $f_h(x')$), we count that towards both tasks, and increment the probability mass on either task by the probability the model assigned to $y$.

Instead of averaging across outputs in either set $f_e(x'), f_h(x')$, we also looked at the probabilities assigned to highest-scoring predictions from each set. The overall trends were similar: the model tends to assign greater mass to the highest-scoring prediction from the easier task compared to highest-scoring prediction from the harder task.
Table 3: We study the correlation between the atomic word-level functions and their compositions, under various training paradigms. We train a linear regressor to predict a model’s generalization adaptability on a composite function based on its adaptabilities on the atomic constituents. Finally, we report the average generalization adaptability of composite tasks, for each training paradigm, under each type of composition.

* indicates composition function has less than 20 tasks, thus reported numbers may not be significant.

| Function type | Training type | Avg. adaptability | Optimal formula | $r^2$ value |
|---------------|---------------|-------------------|-----------------|-------------|
| Chaining      | Full Fine-tuning | 37.43±1.18       | 1.27$x + 0.14$ | 0.56        |
| $f_2(f_1)$    | Full Prompt-tuning | 22.37±1.03       | 1.32$x + 0.05$ | 0.65        |
|                | 32-shot Fine-tuning | 18.59±1.21       | 1.34$x + 0.07$ | 0.57        |
|                | 32-shot Prompt-tuning | 18.19±1.21       | 1.32$x + 0.07$ | 0.6         |
| Union         | Full Fine-tuning | 31.18±0.02       | 1.24$x + 0.02$ | 0.73        |
| $f_2 \cup f_1$ | Full Prompt-tuning | 25.05±1.11       | 1.4$x - 0.01$  | 0.83        |
|                | 32-shot Fine-tuning | 17.28±1.52       | 1.37$x + 0.02$ | 0.8         |
|                | 32-shot Prompt-tuning | 18.43±1.55       | 1.35$x + 0.02$ | 0.8         |
| Intersection  | Full Fine-tuning | 43.31±2.42       | 2.25$x - 0.12*$ | 0.97*       |
| $f_2 \cap f_1$ | Full Prompt-tuning | 16.68±1.78       | 1.64$x - 0.04*$ | 0.98*       |
|                | 32-shot Fine-tuning | 22.77±1.63       | 5.93$x - 0.12*$ | 0.91*       |
|                | 32-shot Prompt-tuning | 25.91±1.93       | 6.81$x - 0.12*$ | 0.94*       |
| Logical And   | Full Fine-tuning | 78.39±2.53       | 2.15$x - 0.85*$ | 0.8*        |
| $f_1 \land f_2$ | Full Prompt-tuning | 79.25±2.37       | 1.27$x - 0.18*$ | 0.58*       |
|                | 32-shot Fine-tuning | 66.49±2.55       | 4.75$x - 2.13*$ | 0.88*       |
|                | 32-shot Prompt-tuning | 55.86±1.22       | 0.48$x + 0.3*$  | 0.05*       |
| Logical Or    | Full Fine-tuning | 72.41±1.97       | 1.39$x - 0.37*$ | 0.54*       |
| $f_1 \lor f_2$ | Full Prompt-tuning | 74.71±2.01       | 1.15$x - 0.18*$ | 0.48*       |
|                | 32-shot Fine-tuning | 58.04±1.11       | 1.52$x - 0.35*$ | 0.63*       |
|                | 32-shot Prompt-tuning | 53.91±0.48       | 0.8$x + 0.1*$   | 0.33*       |
| Map           | Full Fine-tuning | 13.44±1.73       | 0.15$x + 0.09$  | 0.03        |
| $\text{map}(\lambda x. f_M(x))$ | Full Prompt-tuning | 5.39±0.93       | 0.13$x + 0.03$  | 0.07        |
|                | 32-shot Fine-tuning | 3.59±0.70       | 0.21$x + 0.0$   | 0.2         |
|                | 32-shot Prompt-tuning | 3.77±0.85       | 0.3$x - 0.01$   | 0.29        |
| Map (+separators) | Full Fine-tuning | 67.40±2.51       | 0.49$x + 0.52$  | 0.17        |
| $\text{map}(\lambda x. f_M(x))$ | Full Prompt-tuning | 18.02±1.96       | 0.83$x + 0.02$  | 0.64        |
|                | 32-shot Fine-tuning | 10.66±1.34      | 0.79$x - 0.01$  | 0.86        |
|                | 32-shot Prompt-tuning | 5.22±1.14       | 0.57$x - 0.04$  | 0.64        |
| Filter        | Full Fine-tuning | 82.08±5.92      | 1.59$x - 0.58*$ | 0.95*       |
| $\text{filter}(\lambda x.f_F(x))$ | Full Prompt-tuning | 78.58±5.43      | 1.38$x - 0.43*$ | 0.95*       |
|                | 32-shot Fine-tuning | 38.39±3.27      | 0.81$x - 0.24*$ | 0.87*       |
|                | 32-shot Prompt-tuning | 51.58±4.99      | 1.19$x - 0.43*$ | 0.87*       |
Table 4: Full list of atomic tasks in TaskBench500. The content inside brackets specifies task input and output languages (eng for English and spa for Spanish). \{inv\} indicates the task is inverted, e.g. creator takes creations as input and returns their creators, while creator{inv} takes creators as input and returns their creations.

| Category | Function | Example Tasks | Example Data |
|----------|----------|---------------|--------------|
| Lexical  | is-POS-noun[eng] | synonyms[eng] | synonyms[spa] |
|          | is-POS-verb[eng] | antonyms[eng] | antonyms[spa] |
|          | is-POS-adjective[eng] | hyponyms[eng] | hyponyms[spa] |
|          | is-POS-adverb[eng] | entailments[eng] | entailments[spa] |
|          | is-sentiment-positive[eng] | translate[eng->spa] | translate[spa->eng] |
|          | is-sentiment-negative[eng] | | |
|          | is-sentiment-neutral[eng] | | |
| Factual  | is-instance-human | child | location{inv} |
|          | is-instance-film | child{inv} | manufacturer |
|          | is-instance-book | continent | member of political party |
|          | is-instance-city | country of citizenship | member of sports team |
|          | is-instance-taxon | country of origin | mother |
|          | is-occupation-actor | country | mother{inv} |
|          | is-occupation-politician | creator | named after |
|          | is-occupation-writer | creator{inv} | native language |
|          | is-occupation-journalist | developer | occupation |
|          | is-occupation-teacher | diplomatic relation | official language |
|          | is-occupation-composer | father | original language of film or TV show |
|          | is-birthplace-london | father{inv} | owned by |
|          | is-birthplace-nyc | genre | performer |
|          | is-birthplace-la | has part | place of birth |
|          | is-birthplace-buenosaires | head of state | place of death |
|          | | head of state{inv} | position held |
|          | | influenced by | position played on team |
|          | | languages spoken written or signed | record label |
|          | | location | sex or gender |

Table 5: Full list of composition functions used in TaskBench500, with examples.
Table 6: Full list of word-level compositional tasks in TASKBench500, organized by composition type.
Table 7: Full list of sequential compositional tasks in TASKBENCH1500, organized by composition type.
Table 8: Full list of sequential compositional tasks in TASKBENCH500, organized by composition type (continued from previous page).