Presentations of Groups Acting Discontinuously on Direct Products of Hyperbolic Spaces*

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Abstract

The problem of describing the group of units $U(ZG)$ of the integral group ring $ZG$ of a finite group $G$ has attracted a lot of attention and providing presentations for such groups is a fundamental problem. Within the context of orders, a central problem is to describe a presentation of the unit group of an order $\mathcal{O}$ in the simple epimorphic images $A$ of the rational group algebra $\mathbb{Q}G$. Making use of the presentation part of Poincaré’s Polyhedron Theorem, Pita, del Río and Ruiz proposed such a method for a large family of finite groups $G$ and consequently Jespers, Pita, del Río, Ruiz and Zalesskii described the structure of $U(ZG)$ for a large family of finite groups $G$. In order to handle many more groups, one would like to extend Poincaré’s Method to discontinuous subgroups of the group of isometries of a direct product of hyperbolic spaces. If the algebra $A$ has degree 2 then via the Galois embeddings of the centre of the algebra $A$ one considers the group of reduced norm one elements of the order $\mathcal{O}$ as such a group and thus one would obtain a solution to the mentioned problem. This would provide presentations of the unit group of orders in the simple components of degree 2 of $\mathbb{Q}G$ and in particular describe the unit group of $ZG$ for every group $G$ with irreducible character degrees less than or equal to 2. The aim of this paper is to initiate this approach by executing this method on the Hilbert modular group, i.e. the projective linear group of degree two over the ring of integers in a real quadratic extension of the rationals. This group acts discontinuously on a direct product of two hyperbolic spaces of dimension two. The fundamental domain constructed is an analogue of the Ford domain of a Fuchsian or a Kleinian group.

1 Introduction

The aim of this work is to generalize the presentation part of Poincaré’s Polyhedron Theorem to a discontinuous group acting on a direct product of two copies of hyperbolic 2-space. Our motivation comes from the investigations on the unit group $U(ZG)$ of the integral group ring $ZG$. One of the important problems is to determine a presentation of this group (see [Seh93]). In order to

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more progress, there is a need for finding new methods to determine generators and next to deduce a presentation. In [PdRR05], Pita, del Río and Ruiz initiated in these investigations the use of actions on hyperbolic spaces. This allowed them to obtain presentations for subgroups of finite index in $\mathcal{U}(\mathbb{Z}G)$ for some new class of finite groups $G$, called groups of Kleinian type. The basic idea can be explained as follows. If $G$ is a finite group then $\mathbb{Z}G$ is an order in the rational group algebra $\mathbb{Q}G$ and it is well known that $\mathbb{Q}G = \prod_{i=1}^n M_{n_i}(D_i)$, where each $D_i$ is a division algebra. If $O_i$ is an order in $D_i$, for each $i$, then $O = \prod_{i=1}^n M_{n_i}(O_i)$ is an order in $\mathbb{Q}G$ and the group of units $\mathcal{U}(O)$ of $O$ is commensurable with $\mathcal{U}(\mathbb{Z}G)$. Recall that two subgroups of a given group are said to be commensurable if they have a common subgroup that is of finite index in both. The group $\mathcal{U}(O)$ is simply $\prod_{i=1}^n \text{GL}_{n_i}(O_i)$, the direct product of the groups $\mathcal{U}(M_{n_i}(O_i)) = \text{GL}_{n_i}(O_i)$. Moreover $\mathcal{U}(Z(O_i)) \times \text{SL}_{n_i}(O_i)$, the direct product of the central units in $O_i$ and the group consisting of the reduced norm one elements in $M_{n_i}(O_i)$, contains a subgroup of finite index isomorphic to a subgroup of finite index of $\text{GL}_{n_i}(O_i)$. The group $\prod_{i=1}^n \mathcal{U}(Z(O_i))$ may be determined from Dirichlet’s Unit Theorem and it is commensurable with $Z(\mathcal{U}(\mathbb{Z}G))$, the group of central units of $\mathbb{Z}G$. For a large class of finite groups $G$ one can describe generators of a subgroup of finite index in $\mathbb{Z}(\mathcal{U}(\mathbb{Z}G))$ [JOdRVG13] (see also [JdRVG14]). Hence, up to commensurability, the problem of finding generators and relations for $\mathcal{U}(\mathbb{Z}G)$ reduces to finding a presentation of $\text{SL}_{n_i}(O_i)$ for every $1 \leq i \leq n$. The congruence theorems allow to compute generators up to finite index for $\text{SL}_{n_i}(O_i)$ when $n_i \geq 3$ (without any further restrictions) and also for $n_i = 2$ but then provided $D_i$ is neither a totally definite rational quaternion algebra, nor a quadratic imaginary extension of $\mathbb{Q}$ and also not $\mathbb{Q}$. The case $n_i = 1$ can also be dealt with in case $D_i$ is commutative or when it is a totally definite quaternion algebra. In case each $M_{n_i}(D_i)$ is of one of these types and if, moreover, $G$ does not have non-commutative fixed point free epimorphic images, then concrete generators, the so called Bass units and bicyclic units, for a subgroup of finite index in $\mathcal{U}(\mathbb{Z}G)$ have been determined [Seh93, RS91a, RS91b, RS89, JL93]. A finite group $G$ is said to be of Kleinian type if each non-commutative simple factor $M_{n_i}(D_i)$ of $\mathbb{Q}G$ is a quaternion algebra over its centre, i.e. $n_i \leq 2$ and the natural image of $\text{SL}_{n_i}(O_i)$ in $\text{PSL}_2(\mathbb{C})$ (obtained by extending some embedding of the centre of $D_i$ in $\mathbb{C}$) is a Kleinian group. A Kleinian group is a subgroup of $\text{PSL}_2(\mathbb{C})$ which is discrete for the reduced topology, or equivalently, its action on the 3-dimensional hyperbolic space via the Poincaré extension of the action by Möbius transformations is discontinuous [Bea95, Theorem 5.3.2]. Poincaré introduced a technique to determine presentations for Kleinian groups via fundamental polyhedra (see e.g. [Bea95, EGM98, Mass88]). An alternative method, due to Swan [Swa71], gives a presentation from a connected open subset containing a fundamental domain. Thus, if $G$ is a finite group of Kleinian type then, in theory, one can obtain a presentation of a group commensurable with $\mathcal{U}(\mathbb{Z}G)$. In practice, it is difficult to execute this procedure because it is usually hard to compute a fundamental Poincaré polyhedron of a Kleinian group. Groups of Kleinian type have been classified in [JPdR07] and examples of how to find presentations of $\mathcal{U}(\mathbb{Z}G)$ for some groups of Kleinian type of small order are given in [PdRR05] and [PdR06]. A generalization to group rings over commutative orders is given in [OdR07]. Recently, in [JJK+15], an algorithm is given to compute a fundamental domain, and hence generators, for subgroups of finite index in groups that are contained in the unit group of orders in quaternion algebras over quadratic imaginary extensions of $\mathbb{Q}$, in particular for Bianchi groups. This work was in fact a generalization of [CJLdR04].
are quaternion algebras over a number field, say $F$. Every field homomorphism $\sigma : F \to \mathbb{C}$ naturally extends to an isomorphism $\mathbb{C} \otimes_{\sigma(F)} A \cong M_2(\mathbb{C})$ and thus to a homomorphism $\sigma : A \to M_2(\mathbb{C})$, via $a \mapsto 1 \otimes a$. This homomorphism maps $\text{SL}_1(A)$, the group consisting of reduced norm one elements, into $\text{SL}_2(\mathbb{C})$. Composing this with the action of $\text{SL}_2(\mathbb{C})$ on $\mathbb{H}^3$, by the Poincaré extension of Möbius transformations, yields an action of $\text{SL}_1(A)$ on $\mathbb{H}^3$. Note that if $\sigma(F) \subseteq \mathbb{R}$ and $A$ is unramified in $\sigma$ (i.e. $\mathbb{R} \otimes_{\sigma(F)} A \cong M_2(\mathbb{R})$), then $\sigma$ restricts to an action on $\mathbb{H}^2$. Let $\sigma_1, \ldots, \sigma_t$ be representatives (modulo complex conjugation) of the homomorphisms from $F$ to $\mathbb{C}$. If $r$ is the number of real embeddings of $F$ on which $A$ is unramified and $s = t - r$, then the action of $\sigma_i$ on the $i$-th component gives an action of $\text{SL}_1(A)$ on

$$\mathbb{H}_{r,s} = \mathbb{H}^2 \times \mathbb{H}^2 \times \mathbb{H}^3 \times \mathbb{H}^3.$$

More precisely the action is given by

$$a \cdot (x_1, \ldots, x_t) = (\sigma_1(a) \cdot x_1, \ldots, \sigma_t(a) \cdot x_t),$$

where $a \in \text{SL}_1(A)$ and $x_1, \ldots, x_r \in \mathbb{H}^2$, $x_{r+1}, \ldots, x_{r+s} \in \mathbb{H}^3$. If $\mathcal{O}$ is an order in $A$ then the image of $\mathcal{O}$ in $M_2(\mathbb{R})^r \times M_2(\mathbb{C})^{(t-r)}$ is discrete. This implies that the action of $\text{SL}_1(\mathcal{O})$ on $\mathbb{H}_{r,s}$ is discontinuous (see Proposition 2.1).

This suggests the following program to obtain a presentation of $U(ZG)$ (more precisely of a group commensurable with $U(ZG)$) for the finite groups $G$ such that $\mathbb{Q}G$ is a direct product of fields and quaternion algebras. (Equivalently, the degrees of the irreducible characters of $G$ are all either 1 or 2, or equivalently, by a result of Amitsur in [Ami61], $G$ is either abelian, or has an abelian subgroup of index 2 or $G/Z(G)$ is elementary abelian of order 8.) First determine the Wedderburn decomposition $\mathbb{Q}G \cong \prod_{i=1}^k A_i$. For each $i = 1, \ldots, k$, let $\mathcal{O}_i$ be an order in $A_i$ and calculate $U(Z(\mathcal{O}_i))$, using for example the Dirichlet Unit Theorem. Next, if $A_i$ is non-commutative and $\mathcal{O} = \mathcal{O}_i$ (in fact it is enough to consider the components which are not totally definite quaternion algebras) then calculate a fundamental domain for the action of $\text{SL}_1(\mathcal{O})$ on $\mathbb{H}_{r,s}$ and determine from this a presentation of $\text{SL}_1(\mathcal{O})$.

For this program to be successful one needs to solve at least the following problem.

1. Does Poincaré’s Method remain valid for discontinuous actions on $\mathbb{H}_{r,s}$?

The following problem is one of the first issues to deal with in order to answer the question.

2. Determine methods to calculate fundamental domains effectively.

Once this is done, the following problem arises.

3. The sides of the well-known fundamental polyhedra in $\mathbb{H}^2$ and $\mathbb{H}^3$ are geodesic hyperplanes i.e. lines and circles (respectively, planes and spheres) orthogonal to the border. How should one define the “sides” of some potential fundamental domain in $\mathbb{H}_{r,s}$?

In this paper we show that the three problems can be controlled in case the considered group acts on a direct product of two copies of $\mathbb{H}^2$. More precisely, we complete the outlined program for the Hilbert modular group $\text{PSL}_2(R)$, where $R$ is the ring of integers in $\mathbb{Q}(\sqrt{d})$, with $d > 0$, and $R$ is a principal ideal domain. The group $\text{PSL}_2(R)$ acts discontinuously on $\mathbb{H}^2 \times \mathbb{H}^2$, the direct product of 2 copies of hyperbolic 2-space. Hence, this group constitutes the “easiest” case of the outlined program and as such can be considered a relevant test case. For the construction of a fundamental
domain we will make use of some ideas in [Coh65a] and [Coh65b]. The construction is based on the classical construction of a Ford fundamental domain. For more details we refer the reader to [Voic99] or to [Bea95, Section 9.5], where the author calls such domains Generalized Dirichlet domains. The largest part of the paper is devoted to set up the machinery needed to prove an extension of the presentation part of Poincaré’s Polyhedron theorem so that we can extract a presentation from this domain. The assumption that $R$ is a principal ideal domain allows us to get a description of the fundamental domain $\mathcal{F}$ in terms of finitely many varieties. Note that this restriction is essentially only used in Lemma 3.7, Theorem 3.8, Lemma 4.12 and Corollary 5.8.

The method outlined allows computing a description of the unit group $U(ZG)$ for several classes of finite groups $G$. As a matter of example, we mention that this now easily can be done for the dihedral groups $D_{10}$ and $D_{16}$ of order 10 and 16 respectively, and the quaternion group $Q_{32}$ of order 32. The group $U(ZD_{10})$ is commensurable with $SL_2\left(\mathbb{Z}\left[\frac{1+\sqrt{5}}{2}\right]\right)$, the group $U(ZD_{16})$ is commensurable with a direct product of a non-abelian free group and the group $SL_2(\mathbb{Z}[\sqrt{3}])$. The group $U(ZQ_{32})$ is commensurable with a direct product of $U(ZD_{16})$ and an abelian group. Corollary 5.8 gives generators of the groups $SL_2(Z[1/2\sqrt{5}])$ and $SL_2(Z[\sqrt{2}])$ and the algorithm described in Theorem 6.24 yields a presentation of these groups. If one does not want to work up to commensurability then the Reidemeister-Schreier method allows to go down to the exact subgroup of the previous groups needed for the computation of the corresponding unit groups. In the case of $U(ZD_{16})$ this exact subgroup is described in [JP93].

An alternative method for computing a presentation for the group of units of an order in a semi-simple algebra over $\mathbb{Q}$ was recently given by Coulangeon, Nebe, Braun and Schnönenbeck in [CNBS]. The authors present a powerful algorithm that is based on a generalisation of Voronoï’s algorithm for computing perfect forms and is combined with Bass-Serre theory. The method differs essentially from the one presented here, as the authors use an action on a Euclidean space. To illustrate their algorithm, several computations are carried out completely in [CNBS]; including orders in division algebras of degree 3.

As mentioned above, in this paper we focus on groups that act discontinuously on direct products of two hyperbolic spaces and we extend the presentation part of Poincaré’s Polyhedron Theorem into this context. Developing such new methods are relevant in the bigger scheme of discovering new generic constructions of units that generate large subgroups in the unit group of an order of a rational division algebra and hence solving completely the problem of describing finitely many generic generators for a subgroup of finite index in $U(ZG)$ for any finite group (hence without any restriction on the rational group algebra $QG$).

The paper is organized as follows. In Section 2, we give some background on discontinuous group actions on direct products of copies of $\mathbb{H}^2$ and $\mathbb{H}^3$ and introduce some notation on the group of our interest, namely $PSL_2(R)$ with $R$ the ring of integers of a real quadratic field, and its action on $\mathbb{H}^2 \times \mathbb{H}^2$. In Section 3, we give a description of a fundamental domain $\mathcal{F}$ for this action, see Theorem 3.8. In Section 4, we prove some topological lemmas about the fundamental domain and they will be used in the two following sections. Finally, in Section 5, we describe the sides of the fundamental domain $\mathcal{F}$. In Theorem 5.3, we generalize the generating part of Poincaré’s Polyhedron Theorem to the case of $PSL_2(R)$ acting on $\mathbb{H}^2 \times \mathbb{H}^2$ and in Corollary 5.8, we give an effective description of the generators of $PSL_2(R)$. In Section 6, we describe the edges of $\mathcal{F}$ and in Theorem 6.24, we generalize the presentation part of Poincaré’s Polyhedron Theorem. Note that Theorem 5.3 and Theorem 6.24 could potentially have been deduced from [Mac64a, Corollary of Theorem 2]. However, in order to get an effective set of generators and relations as an application
of this theorem one needs all the lemmas in Section 5 and 6 anyway. Moreover, we think that
the proofs of Theorem 5.3 and Theorem 6.24, presented in this paper, are more intuitive from a
geometric point of view. Furthermore they are algorithmic in nature. For the convenience of the
reader we include an appendix on some needed algebraic topological results.

2 Background

The following definitions are mostly taken from [Bea95, Rat94]. Let \( \hat{\mathbb{C}} = \mathbb{C} \cup \{\infty\} \) and let \( \mathbb{H}^n \)
by Möbius transformations. We also let \( \text{SL}_2(\mathbb{C}) \) act by orientation-preserving
isometries on \( \hat{\mathbb{C}} \), by the Poincaré extension of Möbius transformations. The hyperbolic plane \( \mathbb{H}^2 \)
is invariant under the action of \( \text{SL}_2(\mathbb{R}) \). This defines an isomorphism between \( \text{PSL}_2(\mathbb{C}) \) (respectively
\( \text{PSL}_2(\mathbb{R}) \)) and the group of orientation-preserving isometries of \( \mathbb{H}^3 \) (respectively \( \mathbb{H}^2 \)).

Consider for non negative integers \( r \) and \( s \) the metric space \( \mathbb{H}_{r,s} = \mathbb{H}^2 \times \{\ell \} \times \mathbb{H}^2 \times \{\ell \} \times \mathbb{H}^3 \) and the group \( \mathcal{G}_{r,s} = \text{SL}_2(\mathbb{R}) \times \{\ell \} \times \text{SL}_2(\mathbb{R}) \times \text{SL}_2(\mathbb{C}) \times \{\ell \} \times \text{SL}_2(\mathbb{C}) \), a direct product of \( r \)
copies of \( \text{SL}_2(\mathbb{R}) \) and \( s \) copies of \( \text{SL}_2(\mathbb{C}) \). An element \( g \in \mathcal{G}_{r,s} \) will be written as an \( (r+s) \)-tuple \((g^{(1)}, \ldots, g^{(r+s)})\) and elements of \( \mathbb{H}_{r,s} \) will be written as \( (r+s) \)-tuples, say \( Z = (Z_1, \ldots, Z_{r+s}) \). The
metric \( \rho \) on this space is given by

\[
\rho(X, Y)^2 = \sum_{i=1}^{n} \rho^{(i)}(X_i, Y_i)^2,
\]

where \( \rho^{(i)} \) is the hyperbolic metric on the hyperbolic 2 or 3-space (see [Maa40, Paragraph 2]). The
action of \( \text{SL}_2(\mathbb{R}) \) and \( \text{SL}_2(\mathbb{C}) \) on \( \mathbb{H}^2 \) and \( \mathbb{H}^3 \) induces componentwise an action of \( \mathcal{G}_{r,s} \) by isometries on \( \mathbb{H}_{r,s} \):

\[
g \cdot Z = (g^{(1)} \cdot Z_1, \ldots, g^{(r+s)} \cdot Z_{r+s}).
\]

We consider \( M_n(\mathbb{C}) \) as an Euclidean \( 2n^2 \)-dimensional real space. This induces a structure of
topological group on \( \mathcal{G}_{r,s} \). Let \( G \) be a subgroup of \( \mathcal{G}_{r,s} \). One says that \( G \) is discrete if it is discrete
with respect to the induced topology. One says that \( G \) acts discontinuously on \( \mathbb{H}_{r,s} \) if and only if,
for every compact subset \( K \) of \( \mathbb{H}_{r,s} \), the set \( \{ g \in G : g(K) \cap K \neq \emptyset \} \) is finite.

The following proposition is well known and extends the fact that a subgroup of \( \text{SL}_2(\mathbb{C}) \) is
discrete if and only if its action on \( \mathbb{H}^3 \) is discontinuous.

**Proposition 2.1** [Rat94, Theorem 5.3.5.] A subgroup of \( \mathcal{G}_{r,s} \) is discrete if and only if it acts
discontinuously on \( \mathbb{H}_{r,s} \).

Let \( G \) be a group of isometries of \( \mathbb{H}_{r,s} \). A fundamental domain of \( G \) is a subset \( \mathcal{F} \) of \( \mathbb{H}_{r,s} \) whose
boundary has Lebesgue measure 0, such that \( \mathbb{H}_{r,s} = \bigcup_{g \in G} g(\mathcal{F}) \) and if \( 1 \neq g \in G \) and \( Z \in \mathbb{H}_{r,s} \),
then \( \{Z, g(Z)\} \) is not contained in the interior of \( \mathcal{F} \). The different sets \( g(\mathcal{F}) \), for \( g \in G \), are called
tiles given by \( G \) and \( \mathcal{F} \) and the set of tiles \( \mathcal{T} = \{g(\mathcal{F}) : g \in G\} \) is called the tessellation given by
\( G \) and \( \mathcal{F} \).

In this paper we study a presentation for the special linear group of degree 2 of the ring of
integers of real quadratic extensions. So throughout \( k \) is a square-free positive integer greater than
1 and

\[
\omega = \frac{1 + \sqrt{k}}{k_0}, \text{ with } k_0 = \begin{cases} 1, & \text{if } k \not\equiv 1 \mod 4; \\ 2, & \text{if } k \equiv 1 \mod 4. \end{cases}
\]  

(1)
Moreover, $K = \mathbb{Q}(\sqrt{K})$ and $R = \mathbb{Z}[\omega]$, the ring of integers of $K$. For $\alpha \in K$, let $\alpha'$ denote the algebraic conjugate of $\alpha$. Then $\omega' = \frac{1 - \sqrt{K}}{2\omega}$ and if $\alpha = \alpha_0 + \alpha_1 \omega$ with $\alpha_0, \alpha_1 \in \mathbb{Q}$, then $\alpha' = \alpha_0 + \alpha_1 \omega'$. Let $N$ denote the norm map of $K$ over $\mathbb{Q}$ and $\epsilon_0$ denote the fundamental unit of $K$, i.e. $\epsilon_0$ is the smallest unit $\epsilon_0$ of $R$ greater than 1. Then $\mathcal{U}(R) = \{\alpha \in R : N(\alpha) = \pm 1\}$, by Dirichlet’s Unit Theorem.

We consider $\text{SL}_2(R)$ as a discrete subgroup of $\text{SL}_2(\mathbb{R}) \times \text{SL}_2(\mathbb{R})$ by identifying a matrix $A \in \text{SL}_2(R)$ with the pair $(A, A')$, where $A'$ is the result of applying the algebraic conjugate $'$ in each entry of $A$. Thus we consider $\text{SL}_2(R)$ acting on $\mathbb{H} \times \mathbb{H}$. More precisely, if $\gamma = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \in \text{SL}_2(K)$, $Z = (x_1 + y_1 i, x_2 + y_2 i)$ and $\gamma(Z) = (\hat{x}_1 + \hat{y}_1 i, \hat{x}_2 + \hat{y}_2 i)$ then a straightforward calculation yields

$$
\hat{x}_1 = \frac{(ax_1 + b)(cx_1 + d) + acy_1^2}{(cx_1 + d)^2 + c^2 y_1^2}, \quad \hat{y}_1 = \frac{y_1}{(cx_1 + d)^2 + c^2 y_1^2}.
$$

(2)

and

$$
\hat{x}_2 = \frac{(a'x_2 + b')(c'x_2 + d') + a'c'y_2^2}{(c'x_2 + d')^2 + c'^2 y_2^2}, \quad \hat{y}_2 = \frac{y_2}{(c'x_2 + d')^2 + c'^2 y_2^2}.
$$

(3)

If $Z = (Z_1, Z_2) \in \mathbb{H} \times \mathbb{H}$ then we write $Z_j = x_j + y_j i$, where $x_j, y_j \in \mathbb{R}$ and $y_j > 0$ $(j = 1, 2)$.

Then the four tuples $(x_1, x_2, y_1, y_2) \in \mathbb{R}^2 \times (\mathbb{R}^+)^2$ form a system of coordinates of elements of $\mathbb{H} \times \mathbb{H}$.

If $Z = (x_1 + y_1 i, x_2 + y_2 i)$ then we use the following notation

$$
\|cZ + d\| = ((cx_1 + d)^2 + c^2 y_1^2)((c'x_2 + d')^2 + c'^2 y_2^2)).
$$

We introduce another system of coordinates $(s_1, s_2, r, h) \in \mathbb{R}^2 \times (\mathbb{R}^+)^2$ by setting

$$
x_1 = s_1 + s_2 \omega, \quad x_2 = s_1 + s_2 \omega', \quad y_1^2 = \frac{h}{r}, \quad y_2^2 = rh
$$

(5)

or equivalently

$$
s_1 = \frac{\omega'x_1 - \omega x_2}{\omega' - \omega}, \quad s_2 = \frac{x_1 - x_2}{\omega - \omega'}, \quad r = \frac{y_1}{y_2}, \quad h = y_1 y_2.
$$

(6)

So, each element $Z$ of $\mathbb{H} \times \mathbb{H}$ is represented by either $(x_1, x_2, y_1, y_2) \in \mathbb{R}^2 \times (\mathbb{R}^+)^2$, or $(s_1, s_2, r, h) \in \mathbb{R}^2 \times (\mathbb{R}^+)^2$, or $(x_1, x_2, r, h) \in \mathbb{R}^2 \times (\mathbb{R}^+)^2$. Then the norm, ratio and height of $Z$ are defined respectively by

$$
\|Z\| = (x_1^2 + y_1^2)(x_2^2 + y_2^2), \quad r(Z) = r = \frac{y_1}{y_2}, \quad h(Z) = h = y_1 y_2.
$$

Using (2) and (3), we get

$$
h(\gamma(Z)) = \frac{h(Z)}{\|cZ + d\|}.
$$

(7)

Let

$$
\Gamma = \text{PSL}_2(R),
$$

(8)
the Hilbert modular group, and we consider it as a discontinuous group of isometries of $\mathbb{H}^2 \times \mathbb{H}^2$. Let $\Gamma_\infty$ denote the stabilizer of $\infty$ by the action of $\Gamma$ (on $\hat{\mathbb{C}}$). The elements of $\Gamma_\infty$ are represented by the matrices $\begin{pmatrix} \epsilon_0^m & b \\ 0 & \epsilon_0^{-m} \end{pmatrix}$ with $m \in \mathbb{Z}$ and $b \in \mathbb{R}$. Abusing notation, if $\gamma \in \Gamma$ is represented by $\begin{pmatrix} a & b \\ c & d \end{pmatrix}$ then we simply write $\gamma = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$. Hence, (2), (3) and (7) imply

$$h(\gamma(Z)) = h(Z) \quad \text{and} \quad r(\gamma(Z)) = \epsilon_0^{4m} r(Z).$$

The second rows of the elements of $\Gamma$ form the following set

$$S = \{(c, d) \in \mathbb{R}^2 : cR + dR = R\}.$$  

3 Fundamental Domain

In this section we compute a fundamental domain for the group $\Gamma = \text{PSL}_2(\mathbb{R})$ via methods analogue to those used for computing a Ford fundamental domain of a discrete group acting on the hyperbolic 2-space. This part of our work is based on the ideas of H. Cohn in [Coh65b, Coh65a].

We start introducing the following subsets of $\mathbb{H}^2 \times \mathbb{H}^2$, expressed in the $(s_1, s_2, r, h)$ coordinates:

$$V_{i}^{+, \geq} = \left\{ (s_1, s_2, r, h) \in \mathbb{H}^2 \times \mathbb{H}^2 : s_i \geq \frac{1}{2} \right\},$$

$$V_{i}^{-, \geq} = \left\{ (s_1, s_2, r, h) \in \mathbb{H}^2 \times \mathbb{H}^2 : s_i \geq -\frac{1}{2} \right\},$$

for $i = 1, 2$ and

$$V_{3}^{+, \geq} = \left\{ (s_1, s_2, r, h) \in \mathbb{H}^2 \times \mathbb{H}^2 : r \geq \epsilon_0^2 \right\},$$

$$V_{3}^{-, \geq} = \left\{ (s_1, s_2, r, h) \in \mathbb{H}^2 \times \mathbb{H}^2 : r \geq \epsilon_0^{-2} \right\}.$$

Moreover, for every $c, d \in S$ with $c \neq 0$, let

$$V_{c,d}^{\geq} = \left\{ Z \in \mathbb{H}^2 \times \mathbb{H}^2 : \|cZ + d\| \geq 1 \right\}.$$

We also define the sets $V_{i}^{+, \leq}$ and $V_{c,d}^{\leq}$ (respectively, $V_{i}^{\pm}$ and $V_{c,d}$) by replacing $\geq$ by $\leq$ (respectively, $=$) in the previous definitions.

For every $(c, d) \in S$ with $c \neq 0$ and $\gamma = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \in \Gamma$ we have

$$\|c \gamma(Z) + a\| = \frac{1}{\|cZ + d\|},$$

and therefore

$$\gamma \left( V_{c,d}^{\geq} \right) = V_{c,a}^{\leq}.$$
We define
\[ F_∞ = V_1^{+} \cap V_1^{-} \cap V_2^{+} \cap V_2^{-} \cap V_3^{+} \cap V_3^{-} \]
\[ = \{ (s_1, s_2, r, h) \in \mathbb{R}^2 \times (\mathbb{R}^+) : |s_1|, |s_2| \leq \frac{1}{2}, \epsilon_0^2 \leq r \leq \epsilon_0^2 \}; \]
\[ F_0 = \bigcap_{(c, d) \in \mathcal{S}} V_{c,d}^Z = \{ Z \in \mathbb{H}^2 \times \mathbb{H}^2 : ||cZ + d|| \geq 1 \text{ for all } (c, d) \in \mathcal{S} \}; \]
\[ F = F_∞ \cap F_0. \]

**Lemma 3.1** $F_∞$ is a fundamental domain of $\Gamma_∞$.

**Proof.** We first prove that if $1 \neq \gamma \in \Gamma_∞$ and $Z = (Z_1, Z_2) = (x_1 + y_1i, x_2 + y_2i) = (s_1, s_2, r, h)$ then $\{ Z, \gamma(Z) \}$ cannot be contained in the interior of $F_∞$. Let
\[ \gamma = \begin{pmatrix} e^m & b \\ 0 & e^{-m} \end{pmatrix}. \]
By (9), $r(\gamma(Z)) = e_0^m r$. If $Z$ and $\gamma(Z)$ belong to the interior of $\Gamma_∞$ then $\epsilon_0^{-2} < r, e_0^m r < \epsilon_0^2$ and therefore $m = 0$. Therefore the transformation $\gamma$ is simply a translation by the parameter $(b, b')$ with $b \in R$. Now $b = b_1 + b_2\omega$, with $b_1, b_2 \in Z$. As $Z$ and $\gamma(Z)$ belong to the interior of $F_∞$, then $|s_1|, |s_2|, |s_1 + b_1|, |s_2 + b_2| < \frac{1}{2}$. Thus $b = 0$ and hence $\gamma = 1$, as desired.

Let $Z = (x_1 + y_1\omega, x_2 + y_2\omega')$ be an arbitrary point in $\mathbb{H}^2 \times \mathbb{H}^2$, with $x_i, y_i \in \mathbb{R}$. We will show that there exists $\gamma \in \Gamma_∞$ such that $\gamma(Z) \in F_∞$. As $\epsilon_0 > 1$, $\lim_{n \to +\infty} \epsilon_0^n = \infty$ and $\lim_{n \to -\infty} \epsilon_0^n = 0$ and hence there exists $n \in \mathbb{Z}$ such that
\[ \epsilon_0^{4n-2} \leq r \leq \epsilon_0^{4n+2}. \]
Let $\gamma = \begin{pmatrix} e^{-n} & b \\ 0 & e^n \end{pmatrix}$. By (9), $\epsilon_0^{-2} \leq r(\gamma(Z)) = \epsilon_0^{4n} r \leq \epsilon_0^2$. So we may assume that $\epsilon_0^{-2} \leq r \leq \epsilon_0^2$.

Now consider $\gamma = \begin{pmatrix} 1 & b \\ 0 & 1 \end{pmatrix}$, with $b = b_1 + b_2\omega$, $b_1, b_2 \in \mathbb{Z}$ and $|x_i + b_i| \leq \frac{1}{2}$. Again by (9), the $(s_1, s_2, r, h)$ coordinates of $\gamma(Z)$ are $(s_1 + b_1, s_2 + b_2, r, h)$ and hence $\gamma(Z) \in F_∞$, as desired.

Moreover the boundary of $F_∞$ is included in $\bigcup_{i=1}^3 V_i^{+} \cup \bigcup_{i=1}^3 V_i^{-}$. This clearly has Lebesgue measure 0. \[ \square \]

For a subset $C$ of $\mathbb{H}^2 \times \mathbb{H}^2$ and $\mu > 0$ let
\[ V_{C,\mu} = \{ (c, d) \in R \times R : ||cZ + d|| \leq \mu \text{ for some } Z \in C \}. \] \[ (11) \]

We say that a subset $C$ of $\mathbb{H}^2 \times \mathbb{H}^2$ is hyperbolically bounded if it is bounded in the metric of $\mathbb{H}^2 \times \mathbb{H}^2$ or equivalently if it is bounded in the Euclidean metric and there is a positive number $\epsilon$ such that $y_1, y_2 > \epsilon$ for every $(x_1 + y_1i, x_2 + y_2i) \in C$.

**Lemma 3.2** Let $C$ be a hyperbolically bounded subset of $\mathbb{H}^2 \times \mathbb{H}^2$ and let $\mu > 0$. Then there are finitely many elements $(c_1, d_1), \ldots, (c_k, d_k)$ of $R \times R$ such that $V_{C,\mu} = \{ (uc_i, ud_i) : i = 1, \ldots, k, u \in U(R) \}$. 

Proof. As \( \{d \in R : N(d) \leq \mu \} \) is finite up to units, it is clear that \( V_{C, \mu} \) has finitely many elements of the form \((0, d)\) with \(d \in R\). As \( C \) is hyperbolically bounded there is \(s > 0\) such that \(h(Z) \geq s\) for every \(Z \in C\). As the number of elements of \( R \) of a given norm is finite modulo units, there are \(c_1, \ldots, c_k \in R \setminus \{0\}\) such that if \(c \in R \setminus \{0\}\) with \(N(c)^2 \leq \frac{\mu}{s^2}\) then \(c = uc_i\) for some \(i = 1, \ldots, k\) and some \(u \in U(R)\). Moreover, for every \(i = 1, \ldots, k\), the set \(C_i = \{ (x, y) \in \mathbb{R}^2 : (c_i x + x)^2 \gamma^2 + (c_i x + x + y)^2 \gamma^2 \leq r \} \) for some \(Z = (x_1 + y_1 i, x_2 + y_2 i) \in C\) is a bounded subset of \(\mathbb{R}^2\). As \(\{ (d, d') : d \in R \} \) is a discrete subset of \(\mathbb{R}^2\), there are \(e_1, \ldots, e_{ij} \in R\) such that if \(d \in R\) and \((d, d') \in C_i\) then \(d = e_{ii}\) for some \(1 \leq i \leq j_i\). Assume that \(\|cZ + d\| \leq \mu\) for some \(Z = (x_1 + y_1 i, x_2 + y_2 i) \in C\). Then \(N(c) s^2 \leq N(c)^2 h(Z)^2 = c^2 c^2 y_1^2 y_2^2 \leq ((c x_1 + d)^2 + c^2 y_1^2)((c x_2 + d')^2 + c^2 y_2^2) = \|cZ + d\| \leq \mu\). Hence \(c = uc_i\) for some \(i = 1, \ldots, k\) and \(u \in U(R)\). Moreover, as \(N(u) = uu' = \pm 1\), we have

\[
(c_i x_1 + u^{-1} d)^2 c_i^2 y_2^2 + (c_i x_2 + (u^{-1} d'))^2 c_i^2 y_2^2 = (c x_1 + d)^2 c^2 y_1^2 + (c x_2 + d')^2 c^2 y_2^2 \leq \|cZ + d\| \leq \mu.
\]

Therefore \((u^{-1} d, (u^{-1} d')) \in C_i\). Thus \(u^{-1} d = e_{il}\) for some \(1 \leq l \leq j_i\). This proves that there are finitely many elements \((c_1, d_1), \ldots, (c_k, d_k) \in (R \setminus \{0\}) \times R\) such that \(V_{C, \mu}\) is contained in \\(\{ u(c_i, d_i) : i = 1, \ldots, k, u \in U(R) \}\). Note that if \(u \in U(R)\) then \(\|uc_i Z + ud_i\| = \|c_i Z + d_i\|\). Hence, the result follows. 

Lemma 3.3 \( \mathcal{F}_0 = \{ Z \in \mathbb{H}^2 \times \mathbb{H}^2 : Z \) has maximal height in its \( \Gamma \)-orbit}. \]

Proof. We first claim that for a fixed \(Z \in \mathbb{H}^2 \times \mathbb{H}^2\), the set \(\{ \|cZ + d\| : (c, d) \in S \}\) has a minimum. Indeed, let \(\pi = \|Z\|\). Clearly \(V_{(Z), \pi} \cap S \neq \emptyset\) as it contains \((1, 0)\). By Lemma 3.2, \(V_{(Z), \pi} \cap S = \{ u(c_i, d_i) : i = 1, \ldots, k, u \in U(R) \}\) for some \((c_1, d_1), \ldots, (c_k, d_k) \in S\). Let \(0 \neq m = \min \{ \|c_i Z + d_i\| : i = 1, \ldots, k \}\). If \(\|cZ + d\| < m \leq \pi\), with \((c, d) \in S\) then \((c, d) = u(c_i, d_i)\) for some \(i\) and some \(u \in U(R)\). Then \(m > \|cZ + d\| = N(u)^2 \|c_i Z + d_i\| \geq m\), a contradiction. Hence the claim follows. Consequently, by (7), the \(\Gamma\)-orbit of \(Z\) has an element of maximum height.

Consider a \(\Gamma\)-orbit and let \(Z\) be an element in this orbit with maximal height. Hence for every \(g \in \Gamma\), \(h(g(Z)) \leq h(Z)\) and hence by (7), \(\|cZ + d\| \geq 1\), for every \((c, d) \in S\). Thus \(Z \in \mathcal{F}_0\).

To prove the other inclusion, let \(Z \in \mathcal{F}_0\). Then \(\|cZ + d\| \geq 1\), for every \((c, d) \in S\) and hence for every \(g \in \Gamma\), \(h(g(Z)) \leq h(Z)\). Thus every element of \(\mathcal{F}_0\) reaches the maximum height in its orbit. 

Lemma 3.4 [Coh65b, Coh65a] \( \mathcal{F} \) is fundamental domain for \( \Gamma \).

Proof. We first show that \( \mathcal{F} \) contains a point of every \( \Gamma \)-orbit. To prove this, consider an orbit and let \(Z\) be an element in this orbit with maximal height. By Lemma 3.1, there is \(W \in \mathcal{F}_\infty\) and \(g \in \Gamma_\infty\) such that \(W = g(Z)\). By (9), \(h(Z) = h(W)\) and hence we may assume that \(Z \in \mathcal{F}_\infty\). Thus, by Lemma 3.3, \(Z \in \mathcal{F}_0\) and so \(Z \in \mathcal{F}\).

Now we will show that if two points of the same orbit are in \( \mathcal{F} \) then they necessarily are on the border of \( \mathcal{F} \). Suppose that \(Z, \gamma(Z) \in \mathcal{F}\), for some \(1 \neq \gamma \in \Gamma\). If \(\gamma \in \Gamma_\infty\) then, by Lemma 3.1, \(Z\) belongs to the border of \(\mathcal{F}_\infty\) and hence it belongs to the border of \(\mathcal{F}\). Otherwise \(\gamma = \left(\begin{array}{cc} a & b \\ c & d \end{array}\right)\) with \(c \neq 0\) and, by (7) we have

\[
h(Z) = h(\gamma(Z)) = \frac{h(Z)}{\|cZ + d\|}.
\]
Therefore \( \|cZ + d\| = 1 \) and thus \( Z \) lies on the border of \( \mathcal{F}_0 \) and thus on the border of \( \mathcal{F} \).

Finally the boundary of \( \mathcal{F} \) is contained in \( \bigcup_{i=1}^{3} V_i^+ \cup \bigcup_{i=1}^{3} V_i^- \cup \bigcup_{(c,d) \in S} V_{c,d} \) with \( c \neq 0 \). As \( S \) is countable, the boundary of \( \mathcal{F} \) has measure 0. \( \blacksquare \)

Let

\[
B = \left\{ (s_1, s_2, r) : |s_1|, |s_2| \leq \frac{1}{2}, \ e_0^2 \leq r \leq e_0^2 \right\}
\]

Observe that

\[
\mathcal{F}_\infty = B \times \mathbb{R}^+.
\]

We can think of \( \mathcal{F} \) as the region above a “floor”, which is given by the sets \( V_{c,d} \) for \( (c, d) \in S \) and limited by “six walls”, which are given by the sets \( V_i^\pm \) for \( i = 1, 2, 3 \).

We now give an alternative description of \( \mathcal{F} \) on which the “floor” is given by the graph of a function \( h_0 \) defined on \( B \).

For each \( c, d \in R \) we define the function \( f_{c,d} : \mathbb{R}^4 \to \mathbb{R} \) by

\[
f_{c,d}(x_1, x_2, y_1, y_2) = \left[ (cx_1 + d)^2 + c^2y_1^2 \right] \left[ (c'x_2 + d')^2 + c'^2y_2^2 \right].
\]

Observe that if \( Z \in \mathbb{H}^2 \times \mathbb{H}^2 \) then \( f_{c,d}(Z) = \|cZ + d\| \) and if \( d \in \mathcal{U}(R) \) then \( f_{0,d}(Z) = 1 \). Thus

\[
\mathcal{F}_0 = \{ Z \in \mathbb{H}^2 \times \mathbb{H}^2 : f_{c,d}(Z) \geq 1, \text{ for all } (c, d) \in S \}. \tag{12}
\]

We use the mixed coordinate system described in Section 2 and write

\[
f_{c,d}(x_1, x_2, r, h) = \left[ (cx_1 + d)(c'x_2 + d') \right]^2 + \left( (cx_1 + d)^2c^2r + (c'x_2 + d')^2c'^2 \right) v + N(c)^2v^2.
\]

If \( c, d \in R, (x_1, x_2, r) \in \mathbb{R}^2 \times \mathbb{R}^+ \) and \( v \in \mathbb{R} \), then we define

\[
f_{c,d,x_1,x_2,r}(v) = \left[ (cx_1 + d)(c'x_2 + d') \right]^2 + \left[ (cx_1 + d)^2c^2r + (c'x_2 + d')^2c'^2 \right] v + N(c)^2v^2. \tag{13}
\]

and if \( c \neq 0 \) then we set

\[
h_1(c, d, x_1, x_2, r) = \sqrt{\frac{1}{N(c)^2} + \frac{1}{4} \left( \frac{x_1 + d}{c} \right)^2 r - \left( \frac{x_2 + d'}{c'} \right)^2 \frac{1}{r} \left\{ \left( \frac{x_1 + d}{c} \right)^2 r + \left( \frac{x_2 + d'}{c'} \right)^2 \frac{1}{r} \right\}},
\]

If \( u \in \mathcal{U}(R) \) then the following statements hold (throughout the paper we will use these without explicit reference):

\[
f_{uc,ud} = f_{c,d}, \tag{14}
\]

\[
h_1(uc, ud, x_1, x_2, r) = h_1(c, d, x_1, x_2, r), \tag{15}
\]

\[
(c, d) \in S \iff (uc, ud) \in S \tag{16}
\]

\[
V_{uc,ud}^\geq = V_{c,d}^\geq, \tag{17}
\]

\[
V_{uc,ud} = V_{c,d}. \tag{18}
\]
Set $\mathcal{C} = \{(x_1, x_2) \in \mathbb{R}^2 : -1 < (cx_1 + d)(c'x_2 + d') < 1\}$. An easy calculation shows that if $c \neq 0$ then

$$V_{c,d} = \{(x_1, x_2, r, h_1(c,d, x_1, x_2, r)) : (x_1, x_2, r) \in \mathcal{C} \times \mathbb{R}^+\}.$$ 

As $\mathcal{C}$ is path-connected, $V_{c,d}$ is path-connected. Moreover, if $f = f_{c,d,x_1, x_2, r}$ then

$$f'(h) = \left[(cx_1 + d)^2 c^2 r + (c'x_2 + d')^2 \frac{c^2}{r}\right] + 2N(c)^2 h.$$ 

and hence $f$ is strictly increasing on $[\min(0, h_1), \infty)$.

For $(s_1, s_2, r) \in B$ let

$$h_0(s_1, s_2, r) = \sup\{h_1 > 0 : f_{c,d,x_1, x_2, r}(h_1) = 1, \text{ for some } (c, d) \in \mathcal{S}, \text{ with } c \neq 0\},$$

where we understand that the supremum of the empty set is 0. If $(c, d) \in \mathcal{S}$, $c \neq 0$, $h_1 > 0$ and $f_{c,d,x_1, x_2, r}(h_1) = 1$ then $h_1^2 \leq \frac{1}{N(c)^2} \leq 1$. Hence the supremum defining $h_0(s_1, s_2, r)$ exists and

$$h_0(s_1, s_2, r) \leq 1. \quad (19)$$

By (12) and the monotonicity $f_{c,d,x_1, x_2, r}$ we have

$$\mathcal{F}_0 = \{(s_1, s_2, r, h) \in \mathbb{R}^2 \times (\mathbb{R}^+)^2 : h \geq h_0(s_1, s_2, r)\} \quad \text{and}$$

$$\mathcal{F} = \{(s_1, s_2, r, h) \in \mathbb{R}^2 \times (\mathbb{R}^+)^2 : (s_1, s_2, r) \in B \text{ and } h \geq h_0(s_1, s_2, r)\}. \quad (20)$$

From (19) and (21) the following lemmas easily follow.

**Lemma 3.5** If $Z = (s_1, s_2, r, h) \in \mathbb{H}^2 \times \mathbb{H}^2$ with $|s_1| \leq \frac{1}{2}$, $|s_2| \leq \frac{1}{2}$, $c^{-2} \leq r \leq c_0^2$ and $h \geq 1$, then $Z \in \mathcal{F}$. Moreover, if the inequalities are strict then $Z \in \mathcal{F}^0$.

**Lemma 3.6** $\mathcal{F}$ is path-connected.

In order to have a finite procedure to calculate the fundamental domain $\mathcal{F}$ of Lemma 3.4 we need to replace $\mathcal{S}$ in the definition of $\mathcal{F}$ by a suitable finite set. In our next result we obtain this for $R$ a principal ideal domain (PID, for short). For that we need the following lemma, which is proved in [Coh65b, Paragraph 5].

**Lemma 3.7** If $R$ is a PID and $(s_1, s_2, r, h) \in \mathcal{F}_0$ then $h > \frac{k_0^2}{2k}$.

**Theorem 3.8** Let $k$ be a square-free integer greater than 1. Let $k_0$ and $\omega$ be as in (1), $R = \mathbb{Z} [\omega]$, $\Gamma = \text{PSL}_2(R)$ and $\mathcal{F}$ the fundamental domain of $\Gamma$ given in Lemma 3.4. Let $S_1$ be a set of representatives, up to multiplication by units in $R$, of the couples $(c,d) \in \mathbb{R}^2$ satisfying the following conditions:

$$c \neq 0, \quad cR + dR = R, \quad |N(c)| \leq \frac{2k}{k_0},$$

$$\left|\frac{d}{c}\right| < \epsilon_0 \sqrt{\frac{2k}{N(c)^2 k_0^2 k_0^2} - \frac{k_0^2}{2k} + \frac{1 + \omega}{2}} \quad \text{and} \quad \left|\frac{d'}{c'}\right| < \epsilon_0 \sqrt{\frac{2k}{N(c)^2 k_0^2 k_0^2} - \frac{k_0^2}{2k} + \frac{1 - \omega'}{2}}. \quad (22)$$

Then $S_1$ is finite and if $R$ is a principal ideal domain then $\mathcal{F} = \mathcal{F} \cap \bigcap_{(c,d) \in S_1} V_{c,d}^\omega$. In particular, $V_{c,d} \cap \mathcal{F} \neq \emptyset$ if and only if $(c, d) \in S_1$. 

11
Proof. That \( \mathcal{S}_1 \) is finite is a consequence of the well known fact that the set of elements of \( R \) with a given norm is finite modulo multiplication by units and that the image of \( R \) by the map \( x \mapsto (x, x') \) is a discrete additive subgroup of \( \mathbb{R}^2 \), so that it intersects every compact subset in finitely many elements.

Assume now that \( R \) is a PID. Then, by Lemma 3.7, \( h_0(s_1, s_2, r) \geq \frac{k_0^2}{2k} > 0 \). Therefore the set

\[
\mathcal{S}_{s_1, s_2, r} = \left\{ (c, d) \in \mathcal{S} : c \neq 0 \text{ and } h_1(c, d, s_1, s_2, r) \geq \frac{k_0^2}{2k} \right\}
\]
is not empty and

\[
h_0(s_1, s_2, r) = \sup \{ h_1(c, d, s_1, s_2, r) : (c, d) \in \mathcal{S}_{s_1, s_2, r} \}. \tag{23}
\]

We claim that if \((s_1, s_2, r) \in B \) and \((c, d) \in \mathcal{S}_{s_1, s_2, r} \) then \((c, d)\) satisfies the conditions of (22). Indeed, clearly \((c, d)\) satisfies the first two conditions. It satisfies the third condition since

\[
N(c)^2 \left( \frac{k_0^2}{2k} \right)^2 \leq N(c)^2 h_1^2 \leq f_{c,d,x_1,x_2,r}(h_1) = 1.
\]

To prove that it satisfies the last two conditions of (22) let \( x_1 = s_1 + s_2 \omega \), \( x_2 = s_1 + s_2 \omega' \) and \( h_1 = h_1(c, d, s_1, s_2, r) \). Recall that \(|s_1|, |s_2| \leq \frac{1}{2}\) and hence

\[
-\frac{1 - \omega}{2} \leq x_1 \leq \frac{1 + \omega}{2} \quad \text{and} \quad -\frac{1 + \omega'}{2} \leq x_2 \leq \frac{1 - \omega'}{2}. \tag{24}
\]

Furthermore

\[
N(c)^2 \left( \frac{k_0^2}{2k} \right)^2 + \left( (c x_1 + d)^2 e^2 r + (c' x_2 + d')^2 e^2 \left( \frac{1}{r} \right) \right) k_0^2 \leq N(c)^2 h_1^2 + (c x_1 + d)^2 e^2 r + (c' x_2 + d')^2 e^2 \frac{1}{r} \]

This, together with \( \epsilon_0^2 \leq r \leq \epsilon_0^2 \) implies

\[
\begin{align*}
|x_1 + \frac{d}{e}| &< \frac{1}{\sqrt{r}} \sqrt{\frac{2k}{N(c)^2 k_0^2}} - \frac{k_0^2}{2k} \leq \epsilon_0 \sqrt{\frac{1}{N(c)^2 k_1^2} - k_1}, \\
|x_2 + \frac{d'}{e'}| &< \frac{1}{\sqrt{r}} \sqrt{\frac{2k}{N(c)^2 k_0^2}} - \frac{k_0^2}{2k} \leq \epsilon_0 \sqrt{\frac{1}{N(c)^2 k_1^2} - k_1}.
\end{align*}
\]

Combining this with (24) we also have

\[
\begin{align*}
|\frac{d}{e}| &< \epsilon_0 \sqrt{\frac{2k}{N(c)^2 k_0^2}} - \frac{k_0^2}{2k} + \frac{1 + \omega}{2}, \\
|\frac{d'}{e'}| &< \epsilon_0 \sqrt{\frac{2k}{N(c)^2 k_0^2}} - \frac{k_0^2}{2k} + \frac{1 - \omega'}{2}.
\end{align*}
\]

This proves the claim.

Combining the claim with (15) and (23) we deduce that if \((s_1, s_2, r) \in B \) then \( h_0(s_1, s_2, r) = \sup \{ h_1(c, d, s_1, s_2, r) : (c, d) \in \mathcal{S}_1 \cap \mathcal{S}_{s_1, s_2, r} \}. \) As \( \mathcal{S}_1 \) is finite, this implies that \( h_0(s_1, s_2, r) = \)
\( h_1(c, d, s_1, s_2, r) \) for some \((c_0, d_0) \in S_1\). Then \((s_1, s_2, r, h) \in \mathcal{F}\) if and only if \((s_1, s_2, r, h) \in V_{c_0, d_0}^c\) if and only if \((s_1, s_2, r, h) \in V_{c,d}^c\) for every \((c, d) \in S\). Therefore \(\mathcal{F} = \mathcal{F}_\infty \cap \bigcap_{(c,d) \in S} V_{c,d}^c\) as desired.

To get the second part of the theorem, notice that \(\mathcal{F} \cap V_{c,d} \subseteq \partial \mathcal{F}_0\) for \((c, d) \in S\), \(c \neq 0\). Moreover, similarly as in (20),

\[
\partial \mathcal{F}_0 = \{ (s_1, s_2, r, h) \in \mathbb{R}^2 \times (\mathbb{R}^+)^2 : h = h_0(s_1, s_2, r) \}.
\]

Thus by the same reasoning as above, \(\mathcal{F}_0 \cap V_{c,d} \neq \emptyset\) if and only if \((c, d) \in S_1\) and hence the result follows.

Recall that a collection of subsets of a topological space \(X\) is said to be locally finite if every point of \(X\) has a neighbourhood intersecting only finitely many elements of the collection. As \(\mathbb{H}_{r,s}\) is locally compact, a collection of subsets of \(\mathbb{H}_{r,s}\) is locally finite if every compact subset of \(\mathbb{H}_{r,s}\) intersects only finitely many elements of the collection. A fundamental domain \(\mathcal{F}\) of a group \(\Gamma\) acting on \(\mathbb{H}_{r,s}\) is said to be locally finite if \(\{g(\mathcal{F}) : g \in \Gamma\}\) is locally finite.

**Lemma 3.9** The fundamental domains \(\mathcal{F}\) of \(\Gamma\) and \(\mathcal{F}_\infty\) of \(\Gamma_\infty\) are locally finite.

**Proof.** Let \(C\) be a compact subset of \(\mathbb{H}^2 \times \mathbb{H}^2\) and let \(\gamma \in \Gamma_\infty\) such that \(C \cap \gamma(\mathcal{F}) \neq \emptyset\). Let \(Z = (x_1, x_2, y_1, y_2) \in C \cap \gamma(\mathcal{F}_\infty)\). As \(C\) is compact, the coordinates of \(Z\) are bounded. As \(\gamma^{-1} \in \Gamma_\infty\), \(\gamma^{-1} = \left(\frac{e^n}{e^m} \ b \ 0 \ e^m\right)\) for some \(m \in \mathbb{Z}\) and \(b \in \mathbb{R}\), and hence \(\gamma^{-1}(Z) = (e^{2m}x_1 + b, e^{-2m}x_2 + b^1, x_2, e^{-2m}y_2).\) As \(y_1\) and \(y_2\) are bounded, there are only finitely many \(m \in \mathbb{Z}\) such that \(\gamma^{-1}(Z) \in \mathcal{F}_\infty\), or equivalently \(Z \in \gamma^{-1}(\mathcal{F}_\infty)\), and this for every \(Z \in C\). Moreover as the first two coordinates of \(Z\) are bounded and \(\{(b, b') : b \in R\}\) is a discrete subset of \(R^2\) for each \(m\) only finitely many \(b\)'s in \(R\) satisfy that \(e^{2m}x_1 + b\) and \(e^{-2m}x_2 + b\) satisfy the conditions imposed on \(x_1\) and \(x_2\) for \(Z\) to be in \(\mathcal{F}_\infty\). Thus there are only finitely many \(\gamma \in \Gamma_\infty\) such that \(C \cap \gamma(\mathcal{F}_\infty) \neq \emptyset\) and therefore \(\mathcal{F}_\infty\) is locally finite.

Now suppose \(C \cap \gamma(\mathcal{F}) \neq \emptyset\) for \(C\) a compact subset of \(\mathbb{H}^2 \times \mathbb{H}^2\) and \(\gamma \in \Gamma_\infty\). If \(\gamma \in \Gamma_\infty\), then we are done by the first part. So we may suppose that \(\gamma = \left(\begin{array}{cc} a & b \\ c & d \end{array}\right)\) with \(c \neq 0\). If \(Z \in C \cap \gamma(\mathcal{F})\) and \(c \neq 0\) then, by (10),

\[
\frac{1}{|cZ + a|} = |c\gamma^{-1}(Z) + d| \geq 1\quad \text{and therefore } |cZ + a| \leq 1,
\]

in other words \((-c, a) \in V_{c,1}\), where \(V_{c,1}\) is defined as in Lemma 3.2. Using Lemma 3.2 we deduce that \((-c, a)\) belongs to a finite subset, up to units in \(R\). So suppose \(\gamma = \left(\begin{array}{cc} a & b \\ c & d \end{array}\right)\) and \(\gamma_u = \left(\begin{array}{cc} ua & u^{-1}b \\ uc & u^{-1}d \end{array}\right)\) are such that \(C \cap \gamma(\mathcal{F}) \neq \emptyset\) and \(C \cap \gamma_u(\mathcal{F}) \neq \emptyset\) respectively for some \(u \in U(R)\). Then

\[
\gamma_u^{-1} \gamma = \left(\begin{array}{cc} u^{-1} & * \\ 0 & u \end{array}\right),
\]

where * denotes some element of \(R\). Denote the latter matrix by \(U\). Then \(\gamma = \gamma_u U\) and \(U \in \Gamma_\infty\). Hence we also have \(C \cap \gamma_u U(\mathcal{F}) \neq \emptyset\) or equivalently \(\gamma^{-1}_u(C) \cap U(\mathcal{F}) \neq \emptyset\). As \(\gamma^{-1}_u(C)\) is still a compact subset of \(\mathbb{H}^2 \times \mathbb{H}^2\) and \(U(\mathcal{F}) \subseteq U(\mathcal{F}_\infty)\), by the first part of the proof there are only finitely many units \(u\) such that \(\gamma_u\) satisfies \(C \cap \gamma_u(\mathcal{F}) \neq \emptyset\) for every fixed \(\gamma = \left(\begin{array}{cc} a & b \\ c & d \end{array}\right)\). For every \((-c, a) \in V_{c,1}\), fix a matrix \(\gamma_{-c,a} = \left(\begin{array}{cc} a & b-c,a \\ c & d-c,a \end{array}\right)\) in \(\Gamma\). Now consider an arbitrary matrix \(\gamma = \left(\begin{array}{cc} a & b \\ c & d \end{array}\right)\) in \(\Gamma\) and set
\[ h = \gamma^{-1}_{c,d} \gamma. \text{ Then } h \in \Gamma_{\infty} \text{ and } h^{-1}(\gamma^{-1}_{c,d}(C)) \cap \mathcal{F}_{\infty} \neq \emptyset \text{ if and only if } (\gamma^{-1}_{c,d}(C)) \cap h(\mathcal{F}_{\infty}) \neq \emptyset. \text{ As } \\
\gamma^{-1}_{c,d}(C) \text{ is compact, by the first part of the proof there are only finitely many } h \in \Gamma_{\infty} \text{ that satisfy }
\text{this and hence there are also only finitely many } \gamma \in \Gamma \text{ satisfying } C \cap \gamma(\mathcal{F}) \neq \emptyset. \]  

**Corollary 3.10** For every \( Z \in \mathbb{H}^2 \times \mathbb{H}^2 \), there exists \( \lambda > 0 \) such that if \( B(Z, \lambda) \cap g(\mathcal{F}) \neq \emptyset \), then \( Z \in g(\mathcal{F}) \) for \( g \in \Gamma \).

**Proof.** Let \( Z \in \mathbb{H}^2 \times \mathbb{H}^2 \). Take some \( \lambda' > 0 \) randomly. As the closed ball \( \overline{B(Z, \lambda')} \) is compact, \( B(Z, \lambda') \cap g(\mathcal{F}) \neq \emptyset \) for only finitely many \( g \in \Gamma \). Hence also \( B(Z, \lambda') \cap g(\mathcal{F}) \neq \emptyset \) for only finitely many \( g \in \Gamma \). Set \( \lambda_0 = \min\{d(Z, g(\mathcal{F})) : g \in \Gamma \text{ such that } B(Z, \lambda') \cap g(\mathcal{F}) \neq \emptyset \text{ and } Z \notin g(\mathcal{F})\} \), where \( d(Z, g(\mathcal{F})) \) denotes the Euclidean distance from \( Z \) to the the set \( g(\mathcal{F}) \). Take \( \lambda = \frac{\lambda_0}{2} \) and the corollary is proven.

The following corollary is now easy to prove.

**Corollary 3.11** \( \partial \mathcal{F} = \bigcup_{g \neq 1} \mathcal{F} \cap g(\mathcal{F}) \).

### 4 Some topological and geometrical properties of the fundamental domain

In order to determine a presentation of \( \Gamma \), we need to obtain more information on the fundamental domain \( \mathcal{F} \) of \( \Gamma \) constructed in the previous section. Thus in this section we will study some properties of \( \mathcal{F} \). First we recall some notions from real algebraic geometry (for more details see [BCR98]). Recall that a real algebraic set is the set of zeros in \( \mathbb{R}^n \) of some subset of \( \mathbb{R}[X_1, \ldots, X_n] \). An algebraic variety is an irreducible algebraic set, i.e. one which is not the union of two proper real algebraic subsets. Moreover, a real semi-algebraic set is a set of the form \( \bigcup_{i=1}^s \cap_{j=1}^n \{x \in \mathbb{R}^n : f_{i,j}(x) \leq 0\} \), where \( f_{i,j}(x) \in \mathbb{R}[X_1, \ldots, X_n] \) and \( *_{i,j} \) is either \( = \) or \( < \), for \( i = 1, \ldots, s \) and \( j = 1, \ldots, n \). We will use the notion of dimension and local dimension of semi-algebraic sets as given in [BCR98]. For example the sets \( V_i^{+, s} \) and \( V_i^{-, s} \) are real semi-algebraic sets and the sets \( V_i^{+, s} \) and \( V_{c,d} \) are real algebraic sets and in fact, we will prove that they are real algebraic varieties.

The following lemma describes when two sets \( V_{c_1,d_1} \) and \( V_{c_2,d_2} \) are equal.

**Lemma 4.1** Let \( (c_1, d_1), (c_2, d_2) \in \mathcal{S} \). Then \( V_{c_1,d_1} = V_{c_2,d_2} \) if and only if \( (c_2, d_2) = (uc_1, ud_1) \) for some \( u \in \mathcal{U}(R) \). Moreover if \( c_1d_2 = c_2d_1 \) and \( N(c_1)^2 \neq N(c_2)^2 \) then \( V_{c_1,d_1} \cap V_{c_2,d_2} = \emptyset \).

**Proof.** One implication has already been given in (18). For the other implication, suppose that \( V_{c_1,d_1} = V_{c_2,d_2} \). The case \( c_1c_2 = 0 \) follows from the fact that if \( (c, d) \in \mathcal{S} \) then \( c = 0 \) if and only if \( V_{c,d} = \mathbb{H}^2 \times \mathbb{H}^2 \). So assume \( c_1c_2 \neq 0 \). We can then rewrite \( f_{c,d} \) as

\[
 f_{c,d}(x_1, x_2, y_1, y_2) = N(c)^2 \left[ \left( x_1 + \frac{d}{c} \right)^2 + y_1^2 \right] \left[ \left( x_2 + \frac{d}{c} \right)^2 + y_2^2 \right].
\]

In particular, if \( c \neq 0 \) then the intersection of \( V_{c,d} \) with \( A = \{(x, 0, y, 1) : x \in \mathbb{R}, y \in \mathbb{R}^+\} \) is formed by the points \((x, 0, y, 1)\) such that \((x, y)\) belongs to the ball with centre \(\left(\frac{d}{c}, 0\right)\) and radius
Therefore, if $V_{c_1,d_1} = V_{c_2,d_2}$ then \( \frac{d_1}{c_1} = \frac{d_2}{c_2} \), or equivalently, \( c_1d_2 = c_2d_1 \), and $N(c_1) = N(c_2)$. As $(c_1,d_1),(c_2,d_2) \in \mathcal{S}$, \( g_1 = \left( \begin{array}{c} a_1 \\ c_1 \\ b_1 \\ d_1 \end{array} \right) \in \Gamma \) and \( g_2 = \left( \begin{array}{c} a_2 \\ c_2 \\ b_2 \\ d_2 \end{array} \right) \in \Gamma \) and $g_2g_1^{-1} \in \Gamma_\infty$. Thus \( g_2 = \left( \begin{array}{cc} u^{-1} & b \\ 0 & u \end{array} \right) g_1 \) for some \( u \in \mathcal{U}(R) \) and \( b \in R \) and so \( (c_2,d_2) = (uc_1, ud_1) \).

The second part follows easily. \( \blacksquare \)

Let

\[
\mathcal{V}_\infty = \left\{ V_i^+, V_i^- : 1 \leq i \leq 3 \right\},
\mathcal{V} = \left\{ V_{c,d} : (c,d) \in \mathcal{S}, c \neq 0 \right\} \quad \text{and} \quad \mathcal{M} = \left\{ \gamma(M) : \gamma \in \Gamma \right\}.
\]

Observe that

\[
\partial \mathcal{F}_0 \subseteq \bigcup_{V \in \mathcal{V}} V, \quad \partial \mathcal{F}_{\infty} \subseteq \bigcup_{V \in \mathcal{V}_{\infty}} V \quad \text{and} \quad \partial \mathcal{F} \subseteq \bigcup_{V \in \mathcal{V}_{\infty}} V.
\]

Let \( V \in \mathcal{V} \cup \mathcal{V}_{\infty} \). If \( V = V_i^\pm \) (respectively, \( V = V_{c,d} \)) then let \( V^\gamma = V_i^{\pm,\gamma} \) (respectively, \( V^\gamma = V_{c,d}^\gamma \)). Define \( V^\gamma \) in a similar way. Clearly, each \( V^\leq \) and \( V^\geq \) are real semi-algebraic sets, \( V \) is the intersection with \( \mathbb{H}^2 \times \mathbb{H}^2 \) of a real algebraic set and it is the boundary of \( V^\leq \) and \( V^\geq \) and its intersection. Thus \( \mathcal{F}_{\infty}, \mathcal{F}_0 \) and \( \mathcal{F} \) and their boundaries are real semi-algebraic sets.

Let \( \gamma = \left( \begin{array}{cc} a \\ c \\ b \\ d \end{array} \right) \in \Gamma \setminus \{1\} \) such that if \( c = 0 \) then \( a > 0 \) and if moreover \( a = 1 \) then \( b = s_1 + s_2 \omega \) with \( s_1, s_2 \in \mathbb{Z} \). Then let

\[
E_\gamma = \left\{ \begin{array}{ll}
V_{c,d}^\geq & \text{if } c \neq 0; \\
V_{c,d}^{\pm,\leq} & \text{if } c = 0 \text{ and } a < 1; \\
V_{c,d}^{\pm,\geq} & \text{if } c = 0 \text{ and } a > 1; \\
V_{3,1}^{\pm,\leq} & \text{if } c = 0, a = 1 \text{ and } b = s_1 + s_2 \omega \text{ with } s_1 < 0; \\
V_{3,1}^{\pm,\geq} & \text{if } c = 0, a = 1 \text{ and } b = s_1 + s_2 \omega \text{ with } s_1 > 0; \\
V_{2,2}^{\pm,\leq} & \text{if } c = 0, a = 1 \text{ and } b = s_2 \omega \text{ with } s_2 < 0; \\
V_{2,2}^{\pm,\geq} & \text{if } c = 0, a = 1 \text{ and } b = s_2 \omega \text{ with } s_2 > 0.
\end{array} \right.
\]

Let \( E_\gamma' \) be the set obtained by interchanging in the definition of \( E_\gamma \) the roles of \( \leq \) and \( \geq \) and let

\[ V_\gamma = \partial E_\gamma = E_\gamma \cap E_\gamma'. \]

The following lemma follows by straightforward calculations.

**Lemma 4.2** If \( \gamma \in \Gamma \setminus \{1\} \) then \( V_\gamma \in \mathcal{V}_{\infty} \cup \mathcal{V} \), \( \mathcal{F} \subseteq E_\gamma \), \( \gamma^{-1}(\mathcal{F}) \subseteq E_\gamma' \) and hence \( \mathcal{F} \cap \gamma^{-1}(\mathcal{F}) \subseteq V_\gamma \).

Using (18) it is easy to prove the following lemma.

**Lemma 4.3** The set \( \mathcal{V} \cup \mathcal{V}_{\infty} \) is locally finite.

We first calculate the local dimensions of \( \mathcal{F} \) and \( \partial \mathcal{F} \).
Lemma 4.4 The fundamental domain $F$ has local dimension 4 at every point and its boundary $\partial F$ has local dimension 3 at every point.

Proof. Let $Z \in F$. We have to prove that for every $\lambda > 0$, $B(Z, \lambda) \cap F$ is of dimension 4. This is obvious for $Z \in F^\circ$. So suppose $Z \in \partial F$. If $Z \notin \partial F_0$, then $Z \in V$ for some $V \in \mathcal{V}_\infty$. As $\partial F_0$ is closed, there is $\lambda_0 > 0$ such that $B(Z, \lambda_0) \cap \partial F_0 = \emptyset$. We may assume without loss of generality that $\lambda_0$ is smaller than 1 and $2\epsilon_0$. If $Z = (s_1, s_2, r = s_3, h)$ then let $Z' = (s'_1, s'_2, r' = s'_3, h)$ where

$$s'_i = \begin{cases} s_i - \frac{\lambda_0}{\sqrt{2}}, & \text{if } Z \in V_i^+; \\ s_i + \frac{\lambda_0}{\sqrt{2}}, & \text{if } Z \in V_i^-; \\ s_i, & \text{otherwise.} \end{cases}$$

Then $Z' \in B(Z, \lambda_0) \cap F_\infty \cap F_0'$ and thus there exists $\lambda' > 0$ such that $B(Z', \lambda') \subseteq F^\circ \cap B(Z, \lambda_0)$. Hence $B(Z, \lambda_0) \cap F$ is of dimension 4. By the choice of $\lambda_0$, this is true for any $\lambda < \lambda_0$ and of course also for any $\lambda > \lambda_0$. Finally suppose $Z \in \partial F \cap \partial F_0$. By (20) and (21) $Z$ is of the form $(s_1, s_2, r, h_0(s_1, s_2, r))$ with $(s_1, s_2, r) \in B$. Let $\lambda > 0$. By (20) the point $Z' = (s_1, s_2, r, h_0(s_1, s_2, r) + \frac{\lambda}{2})$ is in $B(Z, \lambda) \cap F_0'$. If $Z' \in F^\circ$, then there exists $\lambda' > 0$ such that $B(Z', \lambda') \subseteq B(Z, \lambda) \cap F^\circ$ and hence $B(Z, \lambda) \cap F$ has dimension 4. If not, then $Z' \in \partial F \cap F_0'$ and hence by the above there exists $\lambda' > 0$ such that $B(Z', \lambda') \subseteq B(Z, \lambda)$ and $B(Z', \lambda') \cap F$ has dimension 4. Thus also $B(Z, \lambda) \cap F$ has dimension 4.

To prove the second part, take $Z \in \partial F$, $\lambda > 0$ and set $\overline{B} = B(Z, \lambda)$, $U_1 = \overline{B} \cap F$ and $U_2 = \overline{B \cap (F^\circ \cup \partial F)}$, where $F^\circ$ denotes the complementary of $F$ in $\mathbb{H}^2 \times \mathbb{H}^2$. Then $\overline{B}$, $U_1$ and $U_2$ satisfy the conditions of Lemma A.3 and hence $B(Z, \lambda) \cap \partial F = U_1 \cap U_2$ has dimension 3. 

The next three lemmas give more details on the elements of $\mathcal{V} \cup \mathcal{V}_\infty$.

Lemma 4.5 The elements of $\mathcal{V} \cup \mathcal{V}_\infty$ are non-singular irreducible real algebraic varieties of dimension 3. Moreover if two different varieties $M_1$ and $M_2$ intersect non-trivially, with $M_1, M_2 \in \mathcal{V} \cup \mathcal{V}_\infty$, then their intersection has local dimension 2 at every point.

Proof. Applying the general implicit function theorem to the following functions

$$f_{c,d}(x_1, x_2, y_1, y_2) = \left[ (cx_1 + d)^2 + c^2y_1^2 \right] \left[ (cx_2 + d)^2 + c^2y_2^2 \right],$$

$$F(x_1, x_2, y_1, y_2) = (f_{c_1,d_1}(x_1, x_2, y_1, y_2), f_{c_2,d_2}(x_1, x_2, y_1, y_2)),$$

for $(c, d), (c_1, d_1), (c_2, d_2) \in S$ with $c, c_1, c_2 \neq 0$ and $V_{c_1,d_1} \neq V_{c_2,d_2}$, one gets that $V_{c,d} \cap V_{c_1,d_1} \cap V_{c_2,d_2}$ are $C^\infty$-manifolds of dimension 3 and 2 respectively. The fact that the elements of $\mathcal{V}$ are path-connected together with [BCR98, Proposition 3.3.10] yield the desired property. The same argument works for the elements of $\mathcal{V}_\infty$ or the combination of an element of $\mathcal{V}$ and an element of $\mathcal{V}_\infty$. 

Lemma 4.6 The elements of $\mathcal{M}$ are non-singular irreducible real algebraic varieties of dimension 3 and the intersection of two different elements of $\mathcal{M}$ is of dimension at most 2.

Proof. The first part follows easily from Lemma 4.5 and [BCR98, Theorem 2.8.8] and the fact that the action of $\text{PSL}_2(R)$ on $\mathbb{H}^2 \times \mathbb{H}^2$ is a bijective semi-algebraic map. The second part follows trivially from the irreducibility. 

16
Lemma 4.7 Let $M_1, M_2, M_3$ be pairwise different elements of $V \cup V_\infty$ with $M_1 \cap M_2 \cap M_3 \neq \emptyset$. Then $V_{c_1,d_1} \cap V_{c_2,d_2} \cap V_{c_3,d_3}$ is a real algebraic set of local dimension $1$ at every point and with at most one singular point.

Proof. Suppose that $M_i = V_{c_i,d_i}$ for $i = 1, 2, 3$. Similar, as in the proof of Lemma 4.5, we apply the implicit function theorem to the function $F: \mathbb{R}^4 \to \mathbb{R}^3$ defined by

$$(x_1, x_2, y_1, y_2) \mapsto (f_{c_1,d_1}(x_1, x_2, y_1, y_2), f_{c_2,d_2}(x_1, x_2, y_1, y_2), f_{c_3,d_3}(x_1, x_2, y_1, y_2)).$$

So $V_{c_1,d_1} \cap V_{c_2,d_2} \cap V_{c_3,d_3} = F^{-1}(1,1,1)$. It is sufficient to prove that the Jacobian matrix of $F$ is of rank $3$ except possibly for at most one point. The Jacobian matrix of $F$ has the following form

$$2 \begin{pmatrix}
    c_1(c_1 x_1 + d_1) \alpha_1 & c_2(c_2 x_1 + d_2) \alpha_2 & c_3(c_3 x_1 + d_3) \alpha_3 \\
    c'_1(c'_1 x_2 + d'_1) \beta_1 & c'_2(c'_2 x_2 + d'_2) \beta_2 & c'_3(c'_3 x_2 + d'_3) \beta_3 \\
    c_i y_1 \alpha_1 & c_i y_1 \alpha_2 & c_i y_1 \alpha_3 \\
    c_i^2 y_2 \beta_1 & c_i^2 y_2 \beta_2 & c_i^2 y_2 \beta_3
\end{pmatrix},$$

(27)

where $\alpha_i = (c'_i x_2 + d'_i)^2 + c_i^2 y_2^2$ and $\beta_i = (c_i x_1 + d_i)^2 + c_i^2 y_1^2$. Note that $\beta_i = \alpha_i^{-1}$ because $(x_1, x_2, y_1, y_2) \in V_{c_1,d_1} \cap V_{c_2,d_2} \cap V_{c_3,d_3}$. In particular $\alpha_i$ is nonzero for every $i = 1, \ldots, 3$. The determinant $det_1$ of the submatrix of (27) formed by the first three rows is

$$det_1 = (\gamma_1(c'_1 x_2 + d'_1) + \gamma_2(c'_2 x_2 + d'_2) + \gamma_3(c'_3 x_2 + d'_3)) y_1,$$

with $\gamma_i = c_i' c_{i+1} c_{i+2} \alpha_i^{-1} \alpha_{i+1} \alpha_{i+2} (c_{i+1} d_{i+2} - c_{i+2} d_{i+1})$, where the indexes are to be interpreted modulo $3$. Note that each $\gamma_i \neq 0$ because of Corollary 4.1 and the assumption that the three varieties considered are distinct. Similar calculations show that the determinant $det_2$ of the submatrix of (27) formed by the rows $1, 3$ and $4$ is:

$$det_2 = (-\gamma_1 c'_1 - \gamma_2 c'_2 - \gamma_3 c'_3) y_1 y_2.$$

If both determinants are $0$, then (because $y_1 \neq 0$ and $y_2 \neq 0$)

$$\begin{cases}
    \gamma_1 c'_1 + \gamma_2 c'_2 + \gamma_3 c'_3 = 0 \\
    \gamma_1 d'_1 + \gamma_2 d'_2 + \gamma_3 d'_3 = 0.
\end{cases}$$

Hence the vector $(\gamma_1, \gamma_2, \gamma_3)$ is perpendicular to the vectors $(c'_1, c'_2, c'_3)$ and $(d'_1, d'_2, d'_3)$ and thus

$$(\gamma_1, \gamma_2, \gamma_3) = t((c'_1, c'_2, c'_3) \times (d'_1, d'_2, d'_3))$$

for some $t \in \mathbb{R}$. So

$$\begin{pmatrix}
    c'_1 c'_2 c'_3 c_i^{-1} \alpha_2 \alpha_3 (c_2 d_3 - c_3 d_2) \\
    c'_2 c'_3 c'_1 c_i^{-1} \alpha_3 \alpha_1 (c_3 d_1 - c_1 d_3) \\
    c'_3 c'_1 c'_2 c_i^{-1} \alpha_1 \alpha_2 (c_1 d_2 - c_2 d_1)
\end{pmatrix} = t \begin{pmatrix}
    c'_3 d'_1 - c'_1 d'_3 \\
    c'_1 d'_2 - c'_2 d'_1 \\
    c'_2 d'_3 - c'_3 d'_2
\end{pmatrix}.$$
for some \( \mu_2 \) and \( \mu_3 \) depending only on \( c_i \) and \( d_i \) for \( 1 \leq i \leq 3 \). Because \( \alpha_i^{-1} \) can be interpreted as \( c_i^2 \) times the square of the Euclidean distance from the point \((x_1, y_1)\) to the point \((-\frac{d_i}{c_i}, 0)\), equations (28) and (29) take the form

\[
d \left( (x_1, y_1), \left( -\frac{d_i}{c_i}, 0 \right) \right) = \lambda_i d \left( (x_1, y_1), \left( -\frac{d_i}{c_i}, 0 \right) \right)
\]

with \( \lambda_i = \frac{d_i}{c_i} \sqrt{\mu_i} \) for \( i = 2, 3 \). Hence, modulo a translation \((x_1, y_1)\) is a solution for \((x, y)\) of the system

\[
\begin{align*}
    x^2 + y^2 &= \lambda_2^2 ((x - a)^2 + y^2) \\
    x^2 + y^2 &= \lambda_3^2 ((x - b)^2 + y^2),
\end{align*}
\]

when \( a \) and \( b \) are different non-zero real numbers. If \( \lambda_i = 1 \) for \( i = 2 \) or \( i = 3 \), then the corresponding equation represents the bisector (which is a line) of \((0, 0)\) and \((a, 0)\) or of \((0, 0)\) and \((b, 0)\). Otherwise, the equation represents the circle \( C_i \) with centre \((-\frac{\lambda_i a}{\lambda_i^2 - \lambda_i^2}, 0)\) and radius \( \frac{\lambda_i b}{\lambda_i^2 - \lambda_i^2} \) (because \( y > 0 \) and \( a \neq b \), the case \( \lambda_1 = 1 = \lambda_3 \) is impossible). Such two different lines, two different circles or a circle and a line intersect in at most one point. So, if there are more than two points in \( \mathbb{H}^2 \times \mathbb{H}^2 \) satisfying the two equations then \( \lambda_i \neq 1 \) for \( i \neq 2, 3 \) and the equations represent the same circles. In this case

\[
\begin{align*}
    \frac{\lambda_2 a}{1 - \lambda_2^2} &= \frac{\lambda_3 b}{1 - \lambda_3^2} \\
    \frac{\lambda_2 a}{1 - \lambda_2^2} &= \frac{\lambda_3 b}{1 - \lambda_3^2}
\end{align*}
\]

Dividing the first equation by the second we conclude that \( \lambda_2 = \lambda_3 \) thus \( a = b \), a contradiction.

So we have shown that there exists at most one possible couple \((x_1, y_1)\) which can be completed to a point \((x_1, x_2, y_1, y_2)\) in the intersection and such that \( det_1 = det_2 = 0 \). Therefore, the condition that the rank of the Jacobian matrix in \((x_1, x_2, y_1, y_2)\) is less than 3 determines the coordinates \( x_1 \) and \( y_1 \). By symmetry, it also determines the coordinates \( x_2 \) and \( y_2 \). This means that the intersection \( V_{c_1, d_1} \cap V_{c_2, d_2} \cap V_{c_3, d_3} \) is a real algebraic variety of dimension at most 1.

A similar argument shows that the result remains true if one of several of \( M_1, M_2 \) and \( M_3 \) are elements of \( \mathcal{V}_\infty \).

In order to determine the border of \( \mathcal{F} \), we need the following definition.

**Definition 4.8** An essential hypersurface of \( \mathcal{F} \) is an element \( M \in \mathcal{V} \cup \mathcal{V}_\infty \) such that \( M \cap \mathcal{F} \) is of dimension 3. Let \( \mathcal{V}_e \) denote the set of essential hypersurfaces of \( \mathcal{F} \).

Following the notation of [BCR98], for \( A \) a real semi-algebraic set, we denote by \( A^{(d)} \) the set of points of \( A \) with local dimension \( d \), i.e.

\[
A^{(d)} = \{ Z \in A : \forall \lambda > 0, \ dim(B(Z, \lambda) \cap A) = d \}. \tag{30}
\]

**Lemma 4.9**

\[
\partial \mathcal{F} = \bigcup_{M \in \mathcal{V}_e} (M \cap \mathcal{F}) = \bigcup_{M \in \mathcal{V}_e} (M \cap \mathcal{F})^{(3)},
\]

18
Proof. Clearly \( \bigcup_{M \in \mathcal{V}} (M \cap F)^{(3)} \subseteq \bigcup_{M \in \mathcal{V}} (M \cap F) \subseteq \partial F \). Let \( Z \in \partial F \) and \( \mathcal{V}_Z = \{ M \in \mathcal{V} \cup \mathcal{V}_\infty : \ Z \in M \} \). We have to prove that \( M \cap F \) has local dimension 3 at \( Z \) for some \( M \in \mathcal{V}_Z \). By (25) and Lemma 4.3, \( \mathcal{V}_Z \) is a non-empty finite set. Thus there is an open ball \( B = B(Z, \lambda_0) \) such that for every \( M \in \mathcal{V} \cup \mathcal{V}_\infty \), \( B \cap M \neq \emptyset \) if and only if \( M \in \mathcal{V}_Z \). Thus, if \( 0 < \lambda \leq \lambda_0 \), then \( \partial F \cap B(Z, \lambda) = \bigcup_{M \in \mathcal{V}_Z} F \cap B \cap M \) and by Lemma 4.5, \( \partial F \cap B(Z, \lambda) \) has dimension 3. Thus \( F \cap B(Z, \lambda) \cap M \) has dimension 3 for some \( M \in \mathcal{V}_Z \). Therefore \( M \cap F \) has local dimension 3 at \( Z \).

Lemma 4.10 If \( V \in \mathcal{V}_\infty \), then \( V \cap F \) has local dimension 3 at every point, i.e. \( (V \cap F)^{(3)} = V \cap F \).

Proof. This follows by arguments similar to those used in the proof of Lemma 4.4.

The following proposition gives information about essential hypersurfaces and will be important in the next two sections.

Proposition 4.11 Assume \( Z \in \partial F \) and \( Z \) is contained in at most two elements \( M \) and \( M' \) of \( \mathcal{V} \cup \mathcal{V}_\infty \). Then \( M \) and \( M' \) are essential and for every \( \lambda > 0 \), the intersections \( B(Z, \lambda) \cap M \cap F \) and \( B(Z, \lambda) \cap M' \cap F \) are of dimension 3.

Proof. If \( Z \) is contained in a single element \( M \) of \( \mathcal{V} \cup \mathcal{V}_\infty \), then the statement is obvious. So suppose that \( Z \in M \cap M' \) for some \( M, M' \in \mathcal{V} \cup \mathcal{V}_\infty \) with \( M \neq M' \) and \( Z \) is contained in no other element of \( \mathcal{V} \cup \mathcal{V}_\infty \). By Lemma 4.5, \( M \cap M' \) is of dimension 2. Moreover \( M = (M \cap M^c) \cup (M \cap M') \cup (M \cap M'^c) \) and, as by the proof of Lemma 4.5, both varieties \( M \) and \( M' \) are not tangent in \( Z \) the first and the third intersections are of dimension 3. Thus \( B(Z, \lambda) \cap M \cap M'^c \) is of dimension 3 and is contained in the boundary of \( F \). Hence \( M \) is an essential hypersurface and \( B(Z, \lambda) \cap M \cap F \) is of dimension 3. Inverting the role of \( M \) and \( M' \), we get the same result for \( M' \).

Finally, if \( R \) is a PID, we can prove compactness of the intersection of \( F \) with the elements of \( \mathcal{V} \).

Lemma 4.12 Assume \( R \) is PID and let \( V_{c,d} \), for \( (c, d) \in S \) with \( c \neq 0 \). Then \( V_{c,d} \cap F \) is compact.

Proof. Let \( Z = (s_1, s_2, r, h) \in V_{c,d} \cap F \). As \( V_{c,d} \cap F \subseteq F_{\infty} \), \( |s_1| \leq \frac{1}{2}, |s_2| \leq \frac{1}{2} \) and \( \epsilon_0^2 \leq r \leq \epsilon_2^2 \). Moreover \( V_{c,d} \cap F \subseteq F_{h} \) and hence, by Lemma 3.7, \( h > \frac{\epsilon_0^2}{2} \). As \( Z \in \partial F \), Lemma 3.5 yields that \( h \leq 1 \). Thus \( V_{c,d} \cap F \) is hyperbolically bounded and closed in \( \mathbb{H}^2 \times \mathbb{H}^2 \) and hence it is compact.

5 Generators of \( \Gamma \)

In the remainder of the paper, \( \mathcal{T} \) denotes the tessellation of \( \mathbb{H}^2 \times \mathbb{H}^2 \) given by \( \Gamma \) and \( F \), i.e \( \mathcal{T} = \{ \gamma(F) : \gamma \in \Gamma \} \). In order to get generators for \( \Gamma \), we have to analyse the intersections between elements of \( \mathcal{T} \). The next lemma is crucial.

Lemma 5.1 Let \( T_1, T_2 \) and \( T_3 \) be three different elements of \( \mathcal{T} \). Then \( T_1 \cap T_2 \cap T_3 \subseteq M_1 \cap M_2 \) for \( M_1, M_2 \) two different elements of \( \mathcal{M} \). In particular the intersection of three different tiles has dimension at most 2.
For every \( i = 1,2,3 \), let \( \gamma_i \in \Gamma \) with \( T_i = \gamma_i(\mathcal{F}) \). Let \( \mathcal{N} = \{ M \in \mathcal{M} : T_i \cap T_j \subseteq M \text{ for some } 1 \leq i \leq j \leq 3 \} \). By Lemma 4.2, for every \( 1 \leq i < j \leq 3 \), we have \( T_i \cap T_j \subseteq \gamma_i(V_{\gamma_j^{-1}}) \). Hence the pairing transformations “pair” the sides of \( \Gamma \). Let \( \mathcal{N} \neq \emptyset \) and it is enough to show that \( \mathcal{N} \) has at least two different elements. By means of contradiction, assume that \( \mathcal{N} = \{ M = \gamma(V) \} \) for some \( V \in V_\infty \cap \mathcal{V} \) and \( \gamma \in \Gamma \). Let \( M^\perp = \gamma(V^\perp) \) and \( M^\parallel = \gamma(V^\parallel) \). Then \( M = \gamma_i\left(V_{\gamma_j^{-1}}\right) \) and, by Lemma 4.2, for each \( 1 \leq i < j \leq 3 \) either \( T_i \subseteq M^\parallel \) and \( T_j \subseteq M^\parallel \) or vice versa. By symmetry one may assume that \( T_1 \subseteq M^\parallel \). Then \( T_2 \subseteq M^\parallel \) and hence \( T_3 \subseteq M^\parallel \cap M^\parallel = M \), a contradiction because \( \dim(T_3) = 4 \) and \( \dim(M) = 3 \).

**Definition 5.2** For each \( \gamma \in \Gamma \setminus \{1\} \), set

\[
S_\gamma = \mathcal{F} \cap \gamma^{-1}(\mathcal{F}).
\]

A side of \( \mathcal{F} \) with respect to \( \Gamma \) is a set of the form \( S_\gamma \) that has dimension 3.

In that case, we say that \( \gamma \) is a side pairing transformation of \( \Gamma \) with respect to \( \mathcal{F} \), or simply a pairing transformation. Observe that if \( \gamma \) is a pairing transformation then so is \( \gamma^{-1} \) and \( \gamma(S_\gamma) = S_{\gamma^{-1}} \).

Hence the pairing transformations “pair” the sides of \( \mathcal{F} \). More generally, a side of \( \mathcal{T} \) is a side of \( \gamma(\mathcal{F}) \) for some \( \gamma \in \Gamma \). Equivalently, the sides of \( \mathcal{T} \) are the sets of dimension 3 of the form \( \gamma(\mathcal{F}) \cap \phi(\mathcal{F}) \), with \( \gamma, \phi \in \Gamma \).

We now can state the main result of this section.

**Theorem 5.3** Let \( \mathcal{F} \) be the fundamental domain of \( \Gamma = \text{PSL}_2(R) \) described in Theorem 3.4. Then \( \Gamma \) is generated by the pairing transformations of \( \mathcal{F} \) with respect to \( \Gamma \).

**Proof.** Let \( L = \{ \bigcap_{i \in I} \gamma_i(\mathcal{F}) : \dim(\bigcap_{i \in I} \gamma_i(\mathcal{F})) \leq 2 \} \) and consider the set

\[
\Omega = \mathbb{H}^2 \times \mathbb{H}^2 \setminus \bigcup_{Y \in L} Y.
\]

This is a set of elements \( Z \in \mathbb{H}^2 \times \mathbb{H}^2 \) that belong either to the interior of a tile of \( \mathcal{F} \) or to a unique side of \( \mathcal{T} \). Indeed, let \( Z \in \Omega \) and suppose \( Z \) is not contained in the interior of a tile of \( \mathcal{F} \). Then \( Z \in \gamma_1(\mathcal{F}) \cap \gamma_2(\mathcal{F}) \) for at least two distinct elements \( \gamma_1 \neq \gamma_2 \in \Gamma \). Because of Lemma 5.1, \( \gamma_1(\mathcal{F}) \) and \( \gamma_2(\mathcal{F}) \) are the only tiles containing \( Z \). Thus, \( Z \in \gamma_1(\mathcal{F}) \cap \gamma_2(\mathcal{F}) \) and \( Z \notin \gamma(\mathcal{F}) \) for \( \gamma \in \Gamma \setminus \{ \gamma_1, \gamma_2 \} \). By the definition of \( \Omega \), \( \dim(\gamma_1(\mathcal{F}) \cap \gamma_2(\mathcal{F})) = 3 \) and hence \( \gamma_1(\mathcal{F}) \cap \gamma_2(\mathcal{F}) \) is the unique side containing \( Z \).

Note that \( X = \mathbb{H}^2 \times \mathbb{H}^2 \) and \( L \) satisfy the hypotheses of Lemma A.1 and hence \( \Omega \) is path-connected. Let \( \gamma \in \Gamma \) and \( Z \in \mathcal{F}^o \). Put \( W = \gamma(Z) \in \gamma(\mathcal{F})^o \). There exists a path \( p \) in \( \Omega \) joining \( Z \) and \( W \). Let \( A = \{ h \in \Gamma : p \cap h(\mathcal{F}) \neq \emptyset \} \). As \( p \) is compact and \( \mathcal{F} \) is locally finite by Lemma 3.9, \( A \) is finite. We define recursively a sequence of subsets of \( A \) by setting \( A_0 = \{ 1 \} \) and if \( i \geq 1 \) then \( A_i = \{ h \in A : h(\mathcal{F}) \cap k(\mathcal{F}) \text{ is a side for some } k \in A_{i-1} \setminus \bigcup_{j<i} A_j \} \). Let \( B = \bigcup_{i \geq 0} A_i \). We claim that \( B = A \). Otherwise let \( \alpha : [0,1] \to p \subseteq \Omega \) be a continuous function with image \( p \) and such that \( \alpha(0) = Z \) and \( \alpha(1) = \gamma(Z) \) and let \( a = \min \{ t \in [0,1] : \alpha(t) \in h(\mathcal{F}) \text{ for some } h \in A \setminus B \} \). This minimum exists because \( A \setminus B \) is non-empty and \( \bigcup_{h \in A \setminus B} k(h) \) is closed. Moreover \( a > 0 \) because \( \alpha(0) = Z \in \mathcal{F}^o \) and \( 1 \in B \), so that \( Z \notin h(\mathcal{F}) \) for each \( h \in A \setminus B \). Then \( \alpha(0,a) \subseteq \bigcup_{h \in B} h(\mathcal{F}) \) and as this union is closed, \( \alpha(a) \in h(\mathcal{F}) \cap k(\mathcal{F}) \) for some \( h \in B \) and \( k \in A \setminus B \). As \( \alpha(a) \in \Omega \),
\( h(\mathcal{F}) \cap k(\mathcal{F}) \) has dimension 3 and hence it is a side. This contradicts the definition of \( B \). Hence \( A = B \) and in particular \( \gamma \in B \). By using the sets \( A_i \), we create a sequence \( \gamma_0 = 1, \gamma_1, \ldots, \gamma_k = g \) such that for every \( 1 \leq j \), \( \gamma_j^{-1}(\mathcal{F}) \) or \( \gamma_j(\mathcal{F}) \) is a side. Hence \( \mathcal{F} \cap \gamma_j^{-1}(\mathcal{F}) \) or \( \mathcal{F} \cap \gamma_j(\mathcal{F}) \) is a side of \( \mathcal{F} \) and thus \( \gamma_j^{-1} \gamma_j \) is one of the proposed generators. As \( \gamma = (\gamma_0^{-1} \gamma_{i_1})(\gamma_{i_1}^{-1} \gamma_{i_2}) \cdots (\gamma_{i_k}^{-1} \gamma_{i_k}) \), the result follows.

Recall that the border of \( \mathcal{F} \) is covered by the essential hypersurfaces of \( \mathcal{F} \). In fact it is also covered by the sides of \( \mathcal{F} \).

**Lemma 5.4** The border of \( \mathcal{F} \) is the union of the sides of \( \mathcal{F} \).

**Proof.** Since the sides of \( \mathcal{F} \) are contained in \( \partial \mathcal{F} \), we only have to prove that if \( Z \in \partial \mathcal{F} \), then \( Z \) belongs to a side of \( \mathcal{F} \). As \( Z \) is in \( \partial \mathcal{F} \) and \( \mathcal{F} \) is a locally finite a fundamental domain, \( Z \in \gamma(\mathcal{F}) \) for only finitely many \( \gamma \in \Gamma \), say \( \gamma_1 = 1, \ldots, \gamma_k \). Choose \( \lambda_0 > 0 \) such that the closed ball \( B(Z, \lambda_0) \) intersects \( \gamma_i(\mathcal{F}) \) if and only if \( Z \in \gamma_i(\mathcal{F}) \) (this is possible by Corollary 3.10). Then

\[
Z \in B(Z, \lambda_0) = \left( B(Z, \lambda_0) \cap \mathcal{F} \right) \cup \left( B(Z, \lambda_0) \cap \cup_{i=2}^k \gamma_i(\mathcal{F}) \right).
\]

Thus by Lemma A.3, \( \mathcal{F} \cap \gamma_i(\mathcal{F}) \) is of dimension 3, for at least one \( 1 \leq i \leq k \) and hence \( Z \) is contained in a side of \( \mathcal{F} \).

In order to give more precise information on the generators of \( \Gamma \) described in Theorem 5.3, we need to analyse the relationship between pairing transformations and essential hypersurfaces. By Lemma 4.9, \( \partial \mathcal{F} \) is the union of the sets of the form \( (\mathcal{F} \cap V)^{(3)} \) with \( V \) running through the essential hypersurfaces and by Lemma 5.4, \( \partial \mathcal{F} \) also is the union of the sides of \( \mathcal{F} \) with respect to \( \Gamma \). Moreover, if \( \gamma \) is a pairing transformation then \( S_\gamma \subset \mathcal{F} \cap V_\gamma \), by Lemma 4.2. Hence \( V_\gamma \) is an essential hypersurface of \( \mathcal{F} \) and it is the unique essential hypersurface of \( \mathcal{F} \) containing \( S_\gamma \). Conversely, let \( V \) be an essential hypersurface and let

\[ \Gamma_V = \{ \gamma : \gamma \text{ is a pairing transformation such that } S_\gamma \subseteq V \}. \]

Clearly, \( \gamma \in \Gamma_V \) if and only if \( \dim S_\gamma = 3 \) and \( V = V_\gamma \). Moreover,

\[ (V \cap \mathcal{F})^{(3)} \subseteq \bigcup_{\gamma \in \Gamma_V} S_\gamma. \]

Each pairing transformation belongs to \( \Gamma_V \) for some essential hypersurface \( V \). We will show that, in order to generate \( \Gamma \) it is enough to take one element of \( \Gamma_V \) for each essential hypersurface.

We start dealing with the elements of \( \mathcal{V}_\infty \). Clearly \( \Gamma_\infty \) is generated by the following elements:

\[
P_1 = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}, \quad P_2 = \begin{pmatrix} 1 & \omega \\ 0 & 1 \end{pmatrix}, \quad P_3 = \begin{pmatrix} \epsilon_0 & 0 \\ 0 & \epsilon_0^{-1} \end{pmatrix}. \]

Using (19) and (21) it is easy to see that the six sets \( V_i^{\pm} \), with \( i = 1, 2, 3 \), are essential hypersurfaces. Moreover, a straightforward calculation shows that if \( i = 1 \) then

\[ \Gamma_{V_i^{\pm}} = \{ P_i^{\mp 1} \} \quad (\text{with opposite signs on both sides}). \]

Thus, for \( i = 1, 2 \), \( P_i \) (respectively, \( P_i^{-1} \)) is a pairing transformation and its side covers the part of the boundary given by \( V_i^{\pm} \cap \mathcal{F} \) (respectively, \( V_i^{-} \cap \mathcal{F} \)).

However to cover \( \mathcal{F} \cap V_3 \) with sides, we may need more than one side.
Lemma 5.5 If \( g \in \Gamma_{V_3^+} \) then \( g = QP_{\mathbb{Z}}^+ \) (with opposite signs on both sides) for some \( Q \in \langle P_1, P_2 \rangle \) and the inversion map is a bijection \( \Gamma_{V_3^+} \to \Gamma_{V_3^-} \). Moreover \( \Gamma_{V_3^+} \) and \( \Gamma_{V_3^-} \) are finite.

Proof. The first statement follows from Lemma 4.2, Lemma 4.5, (26) and some easy computations. If \( \gamma \in \Gamma_{V_3^+} \) then \( \gamma = \left( \begin{array}{cc} e_0^{-1} & b \\ 0 & e_0 \end{array} \right) \) with \( b \in R \). Moreover, by (2) and (3), \( F \cap \gamma(F) \) is a non-empty subset formed by elements of the form \( (x_1, x_2, y_1, y_2) \) such that \( (x_1, x_2) \) and \( (\tilde{x}_1, \tilde{x}_2) = (e_0^{-2}x_1 + e_0^{-1}b, e_0^2x_2 + e_0b') \). belong to a compact set. As \( \{(b, b') : \ b \in R\} \) is discrete, we deduce that \( b \) belongs to a finite subset of \( R \). Thus \( \Gamma_{V_3^+} \) is finite. Hence \( \Gamma_{V_3^-} \) is finite too.

We now deal with the essential hypersurfaces of the form \( V_{c,d} \) with \( (c, d) \in S \) (and necessarily \( c \neq 0 \)).

Lemma 5.6 Let \( (c, d) \in S \) with \( c \neq 0 \). Then the second row of every element of \( \Gamma_{V_{c,d}} \) is of the form \( (uc, ud) \) for some \( u \in \mathcal{U}(R) \). Equivalently, if the second row of \( \gamma \in \Gamma \) is \( (c, d) \) then \( \Gamma_{V_{c,d}} \subseteq \gamma \Gamma_{\infty} \).

Proof. Let \( \gamma \in \Gamma_{V_{c,d}} \) and let \( v \in R^2 \) be the second row of \( \gamma \). Then \( S_\gamma \subseteq V_\gamma \cap V_{c,d} \), by Lemma 4.2, and hence \( V_\gamma = V_{c,d} \), by Lemma 4.6. Then \( v = (uc, ud) \) for some \( u \in \mathcal{U}(R) \), by Lemma 4.1.

Let \( S_c \) denote the set of \( (c, d) \in S \) such that \( V_{c,d} \) is an essential hypersurface of \( F \).

Corollary 5.7 For every \( (c, d) \in S_c \) choose \( a, b \in R \) with \( P_{c,d} = \left( \begin{array}{cc} a & b \\ c & d \end{array} \right) \) \( \in \Gamma \). Then \( \Gamma = \langle P_1, P_2, P_3, P_{c,d} : (c, d) \in S_c \rangle \).

Proof. By Theorem 5.3, \( \Gamma \) is generated by \( \cup_{V \in V_c} \Gamma V \) and hence it is enough to show that \( \langle P_1, P_2, P_3, \gamma_{c,d} : (c, d) \in S \rangle \) contains \( \Gamma V \) for each \( V \in V_c \). This is a consequence of (31), Lemma 5.5, Lemma 5.6 and the fact that \( \Gamma_{\infty} \) is generated by \( P_1, P_2 \) and \( P_3 \).

In case \( R \) is a PID we can combine Theorem 3.8 and Corollary 5.7 to get the following

Corollary 5.8 Suppose that \( R \) is a PID and let \( S_1 \) be as in Theorem 3.8. For each \( (c, d) \in S_1 \) choose \( a, b \in R \) such that \( P_{c,d} = \left( \begin{array}{cc} a & b \\ c & d \end{array} \right) \) \( \in \Gamma \). Then \( \Gamma = \langle P_1, P_2, P_3, P_{c,d} : (c, d) \in S_1 \rangle \).

6 Defining Relations of \( \Gamma \)

In this section we construct the relations associated to the pairing transformations, and hence we obtain a presentation of the group \( \Gamma \). As in the classical case, there are two types of relations. These will be called the pairing relations and the cycle relations. The pairing relations are quite obvious to establish.

Notation 6.1 Given a side \( S \) of \( F \), let \( \gamma_{S} \) denote the unique element of \( \Gamma \) such that \( S = F \cap \gamma_{S}^{-1}(F) \) and let \( S^* = F \cap \gamma_{s}(F) \).
Observe that if $S$ is a side then $\gamma_S(S) = S^\ast$. Moreover $S \mapsto \gamma_S$ and $\gamma \mapsto S_\gamma$ define mutually inverse bijections between the sides of $F$ and the pairing transformations such that $\gamma_S^{-1} = \gamma_S^\ast$, or equivalently $S_{\gamma}^\ast = S_{\gamma^{-1}}$. The pairing relation given by $S$ is then simply $\gamma_S \gamma_{S^\ast} = 1$. Note that in case $S = S^\ast$, we get as pairing relation $\gamma_S^2 = 1$.

We will now turn to the cycle relations. For this we need to introduce the following definition.

**Definition 6.2** A cell $C$ of $T$ is a non-empty intersection of tiles of $F$ satisfying the following property: for every $\gamma \in \Gamma$, either $C \subseteq \gamma(F)$ or $\dim(C \cap \gamma(F)) \leq \dim(C) - 1$. Clearly, the cells of dimension 4 are the tiles. By Lemma 5.1, the sides of $T$ are the cells of dimension 3. A cell of dimension 2 is called an edge. If a cell or edge is contained in a tile $T$, then it is called a cell or an edge of $T$.

Observe that a cell is always a finite intersection of tiles. Indeed, consider $Z \in C$. As $\{Z\}$ is compact, $Z$ is contained in only finitely many tiles of $F$, and hence so is $C$. The following proposition generalizes in some sense the notion of relative interior of a cell.

**Proposition 6.3** Let $C$ be a cell of $T$. Then there exists $Z \in C$, such that, for every $\gamma \in \Gamma$, $Z \in \gamma(F)$ if and only if $C \subseteq \gamma(F)$.

**Proof.** Let $\gamma_1, \ldots, \gamma_n$ be the elements $\gamma \in \Gamma$ such that $C \subseteq \gamma(F)$. Suppose, by contradiction, that there do not exist $Z \in C$ that satisfy the statement of the proposition. Then, for every $Z \in C$, there exists $\gamma_Z \in (\Gamma \setminus \{\gamma_i : 1 \leq i \leq n\})$ such that $Z \in \gamma_Z(F)$. Put $\Gamma^* = \{\gamma_Z : Z \in C\}$. This is a countable set because $\Gamma$ is countable, and clearly $C \subseteq \bigcup_{\gamma \in \Gamma^*} \gamma(F)$. Thus

$$C = \bigcup_{\gamma \in \Gamma^*} (\gamma(F) \cap C).$$

As $C \nsubseteq \gamma(F)$ for $\gamma \in \Gamma^*$ and because $C$ is a cell, $\dim(C \cap \gamma(F)) \leq \dim(C) - 1$ and hence $C = \bigcup_{\gamma \in \Gamma^*} (\gamma(F) \cap C)$ has dimension at most $\dim(C) - 1$, a contradiction.

The next lemma is an obvious consequence of the definition of an edge.

**Lemma 6.4** Let $\gamma \in \Gamma$. If $E$ is an edge then $\gamma(E)$ is an edge. In particular, if $E$ is an edge of $F$ contained in some side $S_\gamma = F \cap \gamma^{-1}(F)$, with $\gamma \in \Gamma$, then $\gamma(E)$ is an edge of $F$.

In order to prove more results on the edges of $F$, we first have to analyse the sides a bit more in detail.

**Lemma 6.5** Let $(c, d) \in S$ with $c \neq 0$. If $t \in \Gamma_\infty$ then there exists $(c_0, d_0) \in S$, $c_0 \neq 0$, such that $t(V_{c,d}) = V_{c_0,d_0}$.

**Proof.** Let $Z \in V_{c,d}$. Fix $\alpha, \beta \in R$ such that $\alpha c + \beta d = 1$. Write $t = \begin{pmatrix} \epsilon & b \\ 0 & \epsilon^{-1} \end{pmatrix}$. Let $c_0 = \epsilon^{-2} c \in R$ and $d_0 = d - \epsilon^{-1} bc \in R$. Then $(c_0, d_0) \in S$, because $\alpha' c_0 + \beta' d_0 = 1$ for $\alpha' = \epsilon \beta b + \epsilon^2 \alpha \in R$ and $\beta' = \beta \in R$. Moreover, for every $Z \in \mathbb{H}^2 \times \mathbb{H}^2$, we have

$$\|c_0 t(Z) + d_0\| = \|\epsilon^{-2} (c Z + c b) + d - \epsilon^{-1} bc\| = \|c Z + d\|$$

Hence $t(V_{c,d}) = V_{c_0,d_0}$. □

Similarly to Lemma 5.1, one may analyse the intersection of three sides.
Lemma 6.6 The intersection of three distinct sides of $F$ is of dimension at most 1.

Proof. Let $S_1, S_2, S_3$ be three distinct sides of $F$ and let $\gamma_i = \gamma_{S_i}$. By Lemma 4.2, each $S_i \subseteq V_{\gamma_i}$ and hence $V_{\gamma_i}$ is an essential hypersurface of $F$. If $V_{\gamma_i} \neq V_{\gamma_j}$ for every $1 \leq i < j \leq 3$, then by Lemma 4.7, $S_1 \cap S_2 \cap S_3$ is of dimension at most 1. Assume now that $V_{\gamma_1} = V_{\gamma_2} = V_{\gamma_3} = V_{c,d}$ for some $(c, d) \in S, c \neq 0$. Then, by Lemma 5.6 and Lemma 4.2, $\gamma_1(S_1 \cap S_2 \cap S_3) = F \cap \gamma_1(F) \cap t_2^{-1}(F) \cap t_3^{-1}(F) \subseteq V_{c,a} \cap V_{t_2} \cap V_{t_3}$, for some $a \in R$. If $V_{t_2} \neq V_{t_3}$, then by Lemma 4.7, the last intersection is of dimension at most 1 as desired. Suppose that $V_{t_2} = V_{t_3} = V_{t_1}$. Using that $t_2 \neq t_3$ it is easy to prove that $i = 3$ and hence $t_2, t_3 \not\in \langle P_1, P_2 \rangle$. By Lemma 5.5, $t_3 = Q t_2$ for $Q \in \langle P_1, P_2 \rangle$. Thus $t_2 \gamma_1(S_1 \cap S_2 \cap S_3) \subseteq t_2(V_{c,a}) \cap F \cap Q^{-1}(F) \cap t_2(F)$. By Lemma 6.5, $t_2(V_{c,a}) = V_{c',d'}$ for some $(c', d') \in S, c' \neq 0$ and by Lemma 4.2 and the fact that $t_2 \not\in \langle P_1, P_2 \rangle$, $t_2(F) \cap F \subseteq V_{t_3}$ and $Q^{-1}(F) \cap F_{\infty} \subseteq V_{t_3}$ with $i = 1$ or 2. Hence Lemma 4.7 allows to conclude.

Next assume that $V_{\gamma_1} = V_{\gamma_2} = V_{\gamma_3} = V_{t_3}$ with $i = 1, 2$ or 3. By Lemma 4.2 and the fact that the $\gamma_i$’s are different we conclude that $i = 3$ and hence $\gamma_1, \gamma_2, \gamma_3 \in \Gamma_{\infty} \setminus \langle P_1, P_2 \rangle$. Then, again by the same argument as above, $\gamma_2 = Q_2 \gamma_1$ and $\gamma_3 = Q_3 \gamma_1$ for $Q_2, Q_3 \in \langle P_1, P_2 \rangle$. Thus $\gamma_1(S_1 \cap S_2 \cap S_3) \subseteq F \cap \gamma_1(F) \cap t_2^{-1}(F) \cap t_3^{-1}(F) \subseteq V_{t_3} \cap V_{c,a} \cap V_{t_3} \cap V_{t_3} \cap V_{t_3}$. However, as $Q_2 \neq Q_3$, $V_{t_3} \neq V_{t_3}$ and again Lemma 4.7 allows to conclude.

So up to permutations of the sides, we are left to deal with the case $V_{\gamma_1} = V_{\gamma_3} \neq V_{\gamma_3}$ and four possible subcases:

1. $V_{\gamma_1} = V_{c_1,d_1}$ and $V_{\gamma_3} = V_{c_3,d_3}$ with $(c_1, d_1), (c_3, d_3) \in S$ and $c_1$ and $c_3$ different from 0;
2. $V_{\gamma_1} = V_{c_1,d_1}$ and $V_{\gamma_3} \in V_{\infty}$ with $(c_1, d_1) \in S$ and $c_1 \neq 0$;
3. $V_{\gamma_1} \in V_{\infty}$ and $V_{\gamma_3} = V_{c_3,d_3}$ for $(c_3, d_3) \in S$ and $c_3 \neq 0$.
4. $V_{\gamma_1}, V_{\gamma_3} \in V_{\infty}$.

We deal with each case separately.

In the first case, by Lemma 5.6, $\gamma_2 = t_\gamma_1$, for some $1 \neq t \in \Gamma_{\infty}$. Thus $\gamma_1(S_1 \cap S_2 \cap S_3) = \gamma_1(F) \cap F \cap t^{-1}(F) \cap \gamma_3^{-1}(F) \subseteq V_{\gamma_3} \cap V_{t_3} \cap V_{\gamma_3} \gamma_1$. We claim that $V_{\gamma_3 \gamma_1}$, $V_3$ and $V_{\gamma_3 \gamma_1}$ are pairwise different. On the one side $V_{\gamma_3 \gamma_1} \subseteq V_{\gamma_3} \setminus V_{\gamma_3}$ and hence $V_{\gamma_3 \gamma_1} \neq V_3$. On the other side, since $V_{\gamma_3} = V_{c_1,d_1}$, the last row of $\gamma_1$ is of the form $(u c_1, u d_1)$ with $u \in U(R)$, by Lemma 4.1. If $\gamma_3 \gamma_1 \not\in \Gamma_{\infty}$, then the last row of $\gamma_3$ is of the same form and hence $V_{c_1,d_1} = V_{c_3,d_3}$ contradicting the hypothesis. Thus $\gamma_3 \gamma_1 \not\in \Gamma_{\infty}$ and therefore $V_{\gamma_3 \gamma_1} \neq V_3$. Finally, if $V_{\gamma_3 \gamma_1} = V_{\gamma_3 \gamma_1}$, then the last rows of $\gamma_3^{-1}$ and $\gamma_3 \gamma_1^{-1}$ differs in a unit and hence $\gamma_3 \not\in \Gamma_{\infty}$.

In the second case, again by the same reasoning, $\gamma_2 = t_\gamma_3$ for some $t \in \Gamma_{\infty}$ and $\gamma_3 \in \Gamma_{\infty}$. Thus $S_1 \cap S_2 \cap S_3 = F \cap \gamma_1^{-1}(F) \cap \gamma_3^{-1} t^{-1}(F) \cap \gamma_3^{-1}(F) \subseteq V_{\gamma_1} \cap V \cap (\gamma_1^{-1}(F) \cap \gamma_3^{-1} t^{-1}(F))$ with $V$ an element of $V_{\infty}$. Observe that $\gamma_1 (\gamma_1^{-1}(F) \cap \gamma_3^{-1} t^{-1}(F)) = F \cap t^{-1}(F) \subseteq V'$ for some element $V' \subseteq V_{\infty}$. Hence $S_1 \cap S_2 \cap S_3 \subseteq V_{\gamma_1} \cap V \cap \gamma_3^{-1}(V')$. By applying the implicit function theorem, as in the proof of Lemma 4.5 and distinguishing between the different cases for $V$ and $V'$, it is now a matter of a straightforward tedious calculation to prove that $V_{\gamma_1} \cap V \cap \gamma_1^{-1}(V')$ has dimension at most 1.

In the third case $V_{\gamma_1} = V_{t_3}$ by (31), and $\gamma_2 = Q \gamma_1 \in \langle P_1, P_2 \rangle P_{3}$ for some $Q \in \langle P_1, P_2 \rangle$. Then $\gamma_1(S_1 \cap S_2 \cap S_3) = F \cap \gamma_1^{-1}(F) \cap Q^{-1}(F) \cap \gamma_3^{-1}(F) \subseteq V_{\gamma_3} \cap V_Q \cap V_{\gamma_3 \gamma_1}$. Since $\gamma_3 \gamma_1^{-1} \not\in \Gamma_{\infty}$ and $\gamma_1^{-1} \not\in \langle P_1, P_2 \rangle$ we deduce that $V_{\gamma_3 \gamma_1}$, $V_Q$ and $V_{\gamma_3 \gamma_1}$ are different and hence the result follows from Lemma 4.7.
In the fourth case, again \( V_1 = V_2 = V_{±}^1 \) and \( γ_2 = Qγ_1 \), as above. Moreover \( S_1 \cap S_2 \cap S_3 = \mathcal{F} \cap γ_1^{-1}(\mathcal{F}) \cap Q^{-1}γ_2^{-1}(\mathcal{F}) \subseteq V_1 \cap V_2 \cap γ_1^{-1}(\mathcal{F}) \cap Q^{-1}γ_2^{-1}(\mathcal{F}) \), with \( V_1 \) and \( V_2 \) two different elements of \( V_∞ \). As in case 2, \( (γ_1^{-1}(\mathcal{F}) \cap Q^{-1}γ_2^{-1}(\mathcal{F})) = γ_1^{-1}(V') \) for some \( V' \in \{ V_1^±, V_2^± \} \). Again the implicit function theorem gives the desired result.

We now describe \( \mathcal{F} \cap V \) for \( V ∈ V \cup V_∞ \) in terms of intersection of tiles.

**Lemma 6.7** Let \( V ∈ V \cup V_∞ \) and set \( Γ_V = \{ γ ∈ Γ : \mathcal{F} \cap γ(\mathcal{F}) ⊆ V \cap \mathcal{F} \} \). Then

\[
V ∩ \mathcal{F} = \bigcup_{γ ∈ Γ_V} (\mathcal{F} ∩ γ(\mathcal{F})).
\]

**Proof.** One inclusion is obvious. To prove the other one, take \( Z ∈ V \cap \mathcal{F} \). Suppose \( V ∈ \mathcal{V} \), i.e. \( V = V_{c,d} \) for some \( (c, d) ∈ \mathcal{S} \). Take \( γ = \left(\begin{array}{cc} a & b \\ c & d \end{array}\right) \) in \( Γ \) for some \( a, b ∈ R \). By (7), \( h(γ(Z)) = h(Z) \) and hence by Lemma 3.3, \( γ(Z) ∈ \mathcal{F}_0 \). As \( \mathcal{F}_∞ \) is a fundamental domain for \( Γ_∞ \), there exists \( τ ∈ Γ_∞ \) such that \( τγ(Z) ∈ \mathcal{F}_∞ \). As, by (9), \( h(τγ(Z)) = h(γ(Z)) = h(Z) \), we have \( τγ(Z) ∈ \mathcal{F} \) and thus \( Z ∈ \mathcal{F} \cap γ^{-1}τ^{-1}(\mathcal{F}) \). By Lemma 4.2, \( \mathcal{F} ∩ γ^{-1}τ^{-1}(\mathcal{F}) ⊆ V_{c,d} ∩ \mathcal{F} \).

If \( V ∈ V_∞ \) a similar reasoning may be applied.

Next we show that every edge is contained in precisely two sides. To prove this we will make use of the following lemma.

**Lemma 6.8** Let \( Z ∈ \mathcal{F} \) and let \( C \) denote the intersection of the tiles of \( \mathcal{T} \) containing \( Z \) (i.e. \( C = \bigcap_{Z ∈ γ(\mathcal{T})} γ(\mathcal{T}) \)). If \( \dim(C) = 2 \), then the number of sides of \( \mathcal{F} \) containing \( C \) is exactly 2.

**Proof.** By Lemma 6.6, \( C \) is not contained in three different sides. So we only have to show that \( C \) is contained in two different sides.

Clearly, every intersection of tiles containing \( Z \) also contains \( C \). We claim that a similar property holds for the elements \( M ∈ \mathcal{M} \). Indeed, if \( M ∈ \mathcal{M} \) then \( M = γ(V) \) for some \( V ∈ \mathcal{V} \cap V_∞ \) and some \( γ ∈ Γ \). If \( Z ∈ M \) then \( γ^{-1}(Z) ∈ V \) and hence, by Lemma 6.7, there is \( γ_1 ∈ Γ \) such that \( γ^{-1}(Z) ∈ \mathcal{F} ∩ γ_1(\mathcal{F}) \). Therefore \( Z ∈ \mathcal{F} ∩ γ_1(\mathcal{F}) \) and hence \( C ⊆ \mathcal{F} \cap γ_1(\mathcal{F}) \) as desired. We claim that a similar property holds for the elements \( V ∈ \mathcal{V} \cap V_∞ \). Indeed, if \( Z ∈ V \) then by Lemma 6.7, there is \( γ_1 ∈ Γ \) such that \( Z ∈ \mathcal{F} ∩ γ_1(\mathcal{F}) \). Hence \( C ∩ \mathcal{F} ∩ γ_1(\mathcal{F}) ⊆ V \), as desired.

By Lemma 4.9, \( Z \) is contained in at least one essential hypersurface \( W \). Since \( C \) has dimension 2, \( Z \) cannot be contained in more than two elements of \( \mathcal{V} \cup V_∞ \), by Lemma 4.7. Then, the elements of \( \mathcal{V} \cup V_∞ \) containing \( Z \) are essential hypersurfaces of \( \mathcal{F} \) by Proposition 4.11. Take \( λ > 0 \) such that \( B(Z, λ) ∩ γ(\mathcal{F}) = \emptyset \) for every \( γ \) with \( Z ∉ γ(\mathcal{F}) \) and \( B(Z, λ) ∩ W = \emptyset \) for every essential hypersurface \( W \) of \( \mathcal{F} \) not containing \( Z \). Again by Proposition 4.11, if \( W \) is an essential hypersurface of \( \mathcal{F} \) containing \( Z \) then \( B(Z, λ) ∩ W ∩ \mathcal{F} \) is of dimension 3 and \( B(Z, λ) ∩ W ∩ \mathcal{F} ⊆ \bigcup_{γ \in Γ, Z ∈ γ(\mathcal{F})} (\mathcal{F} ∩ γ(\mathcal{F}) ∩ W) \) and thus one of these intersections is of dimension 3. Therefore, if \( W \) is an essential hypersurface of \( \mathcal{F} \) containing \( C \) then it contains a side containing \( Z \). Thus, if \( C \) is contained in exactly two elements of \( \mathcal{V} \cup V_∞ \) then each contains one side containing \( Z \) and these two sides have to be different by Lemma 4.5.

Hence we may assume that \( Z \) is contained in exactly one element \( W \) of \( \mathcal{V} \cup V_∞ \). Then \( C \) is contained in at least one side \( S_1 \) and \( S_1 ⊆ W \). Let \( γ_1 ∈ Γ_{S_1} \) (i.e. \( S_1 = \mathcal{F} ∩ γ_1^{-1}(\mathcal{F}) \)). Then, by
Lemma 4.2. \( W = V_{1\gamma} \). As \( \dim(C) = 2 \), \( \dim(S_{1\gamma}) = 3 \) and \( C \subseteq F \cap S_1 \) there is \( \gamma_2 \in \Gamma \setminus \{1, \gamma_1\} \) with \( Z \in \gamma_2^{-1}(F) \). Thus \( \gamma_2 = t_{\gamma_1} \) with \( t \in \Gamma_\infty \setminus \{1\} \) and if \( \gamma_1 \in \Gamma_\infty \) then \( t \in \langle P_1, P_2 \rangle \), by Lemma 5.5 and Lemma 5.6. We consider separately two cases.

First assume that \( W = V_i^\pm \) with \( i = 1 \) or \( 2 \) and without loss of generality, we may assume that \( W = V_1^+ \). Then \( \gamma_1 = P_1^{-1} \) by (31) and \( \gamma_2 = P_1^\alpha P_2^\beta \) for some integers \( \alpha \) and \( \beta \). Moreover \( Z = (\frac{1}{2}, s_2, r, h) \) and \( (\alpha + \frac{1}{2}, s_2 + \beta, r, h) = \gamma_2(Z) \in F \). Thus \( \alpha \in \{0, -1\} \). However, if \( \alpha = 0 \) then \( V_2 = V_2^\pm \neq W \). Thus \( \alpha = -1 \) and hence \( \beta = \pm 1 \), because \( \gamma_1 \neq \gamma_2 \). Then \( Z \in V_2^\pm \), a contradiction.

Assume now that either \( W \in V \) or \( W = V_3^\pm \). In both cases \( V_i \neq V_{1\gamma} \), because in the first case \( V_{1\gamma} \in V \) and \( V_i \in V_\infty \) and in the second case \( V_i = V_i^\pm \) with \( i = 1 \) or \( 2 \). Moreover \( \gamma_1(C) \subseteq F \cap \gamma_1(F) \cap t^{-1}(F) \subseteq V_{1\gamma} \cap V_i \). As \( F \subseteq E_1, \gamma_1(S_{1\gamma}) = S_{1\gamma} \subseteq E_1 \). Let \( M = \gamma_1^{-1}(V_i), M^2 = \gamma_1^{-1}(E_i) \) and \( M^\pm = \gamma_1^{-1}(E_i) \). Then, by the previous, \( S_{1\gamma} \subseteq M^2 \). By the choice of \( \lambda \) and Lemma 4.5, \( B(Z, \lambda) \cap W \cap F \cap M^\pm \) has dimension 3. Thus, by Lemma 5.4, \( Z \in S \) for some side \( S \subseteq W \) and different from \( S_{1\gamma} \). Hence also \( C \) is contained in two different sides. 

The following is a consequence of Proposition 6.3 and Lemma 6.8.

**Corollary 6.9** If \( E \) is an edge of the fundamental domain \( F \), then there are precisely two sides that contain \( E \).

The following lemma is obvious.

**Lemma 6.10** Let \( E_1 \) and \( E_2 \) be two different edges of some tile. Then the intersection \( E_1 \cap E_2 \) is of dimension at most 1.

Finally, in order to be able to describe the relations, we need two more lemmas.

**Lemma 6.11** Let \( \gamma_1, \gamma_2 \in \Gamma \). Assume \( \gamma_1(F) \cap \gamma_2(F) \) has dimension 2. Then,

1. there exists \( Z_0 \in \gamma_1(F) \cap \gamma_2(F) \) such that \( \bigcap_{Z_0 \in \gamma_1(F) \cap \gamma_2(F)} \gamma(F) \) is of dimension 2; and
2. for every such \( Z_0 \), the set \( \bigcap_{Z_0 \in \gamma_1(F) \cap \gamma_2(F)} \gamma(F) \) is an edge contained in \( \gamma_1(F) \cap \gamma_2(F) \).

**Proof.** 1. We first show the existence of a point \( Z_0 \in \gamma_1(F) \cap \gamma_2(F) \) such that \( \bigcap_{Z_0 \in \gamma_1(F) \cap \gamma_2(F)} \gamma(F) \) is of dimension 2. For every \( Z \in \gamma_1(F) \cap \gamma_2(F) \), let \( \Gamma_Z = \{ \gamma \in \Gamma \setminus \{ \gamma_1, \gamma_2 \} : Z \in \gamma(F) \} \). We claim that \( \Gamma_Z \neq \emptyset \) for every \( Z \in \gamma_1(F) \cap \gamma_2(F) \). Otherwise there is a \( \lambda > 0 \) such that \( B(Z, \lambda) \cap \gamma(F) = \emptyset \) for every \( \gamma \in \Gamma \setminus \{ \gamma_1, \gamma_2 \} \). Then \( B(Z, \lambda) \subseteq \gamma_1(F) \cup \gamma_2(F) \), which is in contradiction with Lemma A.3.

This proves the claim. Thus \( \gamma_1(F) \cap \gamma_2(F) = \bigcup_{Z \in \gamma_1(F) \cap \gamma_2(F)} \bigcap_{\gamma \in \Gamma_Z} \gamma(F) \). As, by assumption, \( \gamma_1(F) \cap \gamma_2(F) \) has dimension 2 and \( \Gamma \) is countable, it follows that there exists \( Z_0 \in \gamma_1(F) \cap \gamma_2(F) \) with \( \bigcap_{Z_0 \in \gamma_1(F) \cap \gamma_2(F)} \gamma(F) \) of dimension 2.

2. Since \( Z_0 \) belongs to only finitely many tiles (by Lemma 3.9), say \( \gamma_1(F), \gamma_2(F), \ldots, \gamma_n(F) \), we have that \( Z_0 \in \bigcap_{i=1}^n \gamma_i(F) \) and \( \bigcap_{i=1}^n \gamma_i(F) \) has dimension 2. We want to prove that this intersection is an edge. Let \( \gamma_0 \in \Gamma \setminus \{ \gamma_1, \ldots, \gamma_n \} \). As \( Z_0 \notin \gamma_0(F) \), it is clear that \( \bigcap_{i=1}^n \gamma_i(F) \nsubseteq \gamma_0(F) \). Hence it remains to prove that \( \bigcap_{i=1}^n \gamma_i(F) \) intersects \( \gamma_0(F) \) in dimension at most 1. Suppose this is not the case, i.e. \( \bigcap_{i=1}^n \gamma_i(F) \) is of dimension 2. As in the first part of the proof, there exists \( Z_1 \in \bigcap_{i=1}^n \gamma_i(F) \) such that \( \bigcap_{Z_1 \in \gamma_1(F)} \gamma(F) \) is of dimension 2. Let \( \gamma_0, \ldots, \gamma_m \) be all elements of \( \Gamma \) (with \( m \geq n \)) such that \( Z_1 \in \gamma_i(F) \). So \( \bigcap_{i=0}^m \gamma_i(F) \) is of dimension 2. By Corollary 3.10, let \( \lambda_1 > 0 \) and \( B = B(Z_1, \lambda_1) \) be such that \( B \cap \gamma(F) \neq \emptyset \) if and only if \( Z_1 \in \gamma(F) \). Then \( B = (B \cap \bigcup_{i=1}^m \gamma_i(F)) \cup \).
\( (B \cap (\bigcup_{i=0}^{m} \gamma_i(F)) \cup \gamma_0(F)) \), where both factors are closed sets of dimension 4 (by Lemma 4.4). Hence by Lemma A.3, \((B \cap (\bigcup_{i=1}^{m} \gamma_i(F)) \cap (B \cap (\bigcup_{i=n+1}^{m} \gamma_i(F)) \cup \gamma_0(F)))\) is of dimension 3. Thus there exists \(1 \leq j_1 \leq n\) and \(n+1 \leq j_2 \leq m\) or \(j_2 = 0\) such that \(Z_1 \in \gamma_{j_1}(F) \cap \gamma_{j_2}(F)\) and the latter intersection is of dimension 3. Hence \(\gamma_{j_1}(F) \cap \gamma_{j_2}(F)\) is a side of the tile \(\gamma_j(F)\). We now come back to \(Z_0\). Let \(\lambda_0 = 0\) and \(B' = \overline{B(Z_0, \lambda_0)}\) be such that \(\cap \gamma(F) \neq 0\) if and only if \(Z_0 \in \gamma(F)\). Thus \(B' = (B' \cap \gamma_{j_1}(F)) \cup \bigcup_{i=1,i \neq j_1}(B' \cap \gamma_i(F))\) and again by Lemma A.3, there exists \(1 \leq j_3 \leq n\) and \(j_3 \neq j_1\) such that \(\gamma_{j_1}(F) \cap \gamma_{j_3}(F)\) is of dimension 3. Thus it is a side of the tile \(\gamma_j(F)\). Hence \(Z_0 \in \partial \gamma_{j_1}(F)\), such that \(\bigcap_{i \in \gamma(F)} \gamma(F)\) is of dimension 2. Moreover the latter is contained in \(\gamma_{j_1}(F) \cap \gamma_{j_3}(F)\), which is a side. Hence by Lemma 6.8, there exists a second side of \(\gamma_{j_1}(F)\), which contains \(\bigcap_{i \in \gamma(F)} \gamma(F)\). Thus this side also contains \(Z_0\) and hence there exists \(1 \leq j_4 \leq n\) with \(j_4 \neq j_1\) and \(j_4 \neq j_3\) such that \(\gamma_{j_1}(F) \cap \gamma_{j_4}(F)\) is a side. Thus the tile \(\gamma_{j_1}(F)\) contains three sides, \(\gamma_{j_1}(F) \cap \gamma_{j_2}(F), \gamma_{j_1}(F) \cap \gamma_{j_3}(F)\) and \(\gamma_{j_1}(F) \cap \gamma_{j_4}(F)\) and their intersection contains \(\bigcap_{i \in \gamma(F)} \gamma(F)\), which is of dimension 2. This contradicts Lemma 6.6. Hence \(\bigcap_{i=1}^{m} \gamma_i(F)\) is an edge and it contains \(Z_0\).

Lemma 6.12 Let \(E\) be an edge. The finitely many elements \(\gamma \in \Gamma\) with \(E \subset \gamma(F)\) can be ordered, say as \(\gamma_0, \gamma_1, \ldots, \gamma_m = \gamma_0\), such that \(\gamma_{j-1}(F) \cap \gamma_j(F)\) is a side (containing \(E\)) for every \(1 \leq j \leq m\). Moreover, up to cyclic permutations and reversing the ordering, there is only one possible ordering with this property.

Proof. Recall that there are only finitely many \(\gamma \in \Gamma\) with \(E \subset \gamma(F)\). Let \(\gamma_0\) be such an element. Then \(E\) is an edge of \(\gamma_0(F)\) and hence, by Corollary 6.9, there exists two sides, say \(\gamma_0(F) \cap \gamma_1(F)\) and \(\gamma_0(F) \cap \gamma_{m-1}(F)\) of \(\gamma_0(F)\) containing \(E\). Now \(E\) also is an edge of \(\gamma_1(F)\) and \(\gamma_0(F) \cap \gamma_1(F)\) is one of the two sides of \(\gamma_1(F)\) containing \(E\). Hence there exists a third tile, say \(\gamma_2(F)\), such that \(\gamma_1(F) \cap \gamma_0(F)\) and \(\gamma_2(F) \cap \gamma_0(F)\) are the two different sides of \(\gamma_1(F)\) containing \(E\). So \(\gamma_2 \notin \{\gamma_0, \gamma_1\}\). One may continue this process and have a sequence \(\gamma_{j-1}, \gamma_0, \gamma_1, \gamma_2, \ldots\) of elements of \(\Gamma\) such that \(\gamma_{j-1}(F) \cap \gamma_j(F)\) and \(\gamma_i(F) \cap \gamma_{i+1}(F)\) are the two sides of \(\gamma_i(F)\) containing \(E\) for every \(i \geq 0\). In particular every three consecutive elements of the list of \(\gamma_i\)'s are different. As there are only finitely many tiles containing \(E\), after finitely many steps we obtain \(\gamma_j \in \Gamma\) with \(\gamma_i = \gamma_j\) and \(0 \leq i < j\). Let \(i\) be minimal with this property. We claim that \(i = 0\). Indeed, if \(0 < i\), then by construction, \(\gamma_i(F) \cap \gamma_{i-1}(F)\), \(\gamma_i(F) \cap \gamma_{i+1}(F)\), \(\gamma_j(F) \cap \gamma_{j-1}(F)\) and \(\gamma_j(F) \cap \gamma_{j+1}(F)\) are all containing \(E\). By Corollary 6.9, \(\gamma_{j-1} = \gamma_{j+1}\) and \(\gamma_{j+1} = \gamma_{j-1}\) or \(\gamma_{j+1} = \gamma_{j-1}\) and \(\gamma_{j-1} = \gamma_{j+1}\). Both cases contradict the minimality of \(i\). It remains to prove that \(\{\gamma_0, \ldots, \gamma_{j-1}\} = \{\gamma \in \Gamma : E \subset \gamma(F)\}\). This may be easily done by arguments similar as the arguments used in the end of the proof of Lemma 6.11.

To prove the last part, notice that instead of starting with the chosen element \(\gamma_0\) one could have started with any of the finitely many elements \(\gamma \in \Gamma\) such that \(E \subset \gamma(F)\). Second, note that once the element \(\gamma_0\) is fixed, there exists two unique tiles \(\gamma_{m-1}(F)\) and \(\gamma_1(F)\) such that \(\gamma_0(F) \cap \gamma_{m-1}(F)\) and \(\gamma_0(F) \cap \gamma_1(F)\) are sides. Hence, up to a choice of the first element \(\gamma_0\), thus up to a cyclic permutations, and up to a choice of a second element, thus up to reversing ordering, there is only one possible ordering.

Based on the previous lemma, we give the following new definition.

Definition 6.13 Let \(E\) be an edge. We call an ordering \((\gamma_0, \ldots, \gamma_{m-1}, \gamma_0)\) of the elements \(\gamma \in \Gamma\) such that \(E \subset \gamma(F)\) as in Lemma 6.12 an edge loop of \(E\).
We now come to a description of the relations of $\Gamma$. We first define what is called a cycle. To do so, we fix some notations.

**Definition 6.14** Let $E$ be an edge of $\mathcal{F}$ and $S$ a side of $\mathcal{F}$ containing $E$. Then define recursively the sequence $(E_1, S_1, E_2, S_2, \ldots)$ as follows:

1. $E_1 = E$ and $S_1 = S$,
2. $E_{i+1} = \gamma_{S_i}(E_i)$,
3. $S_{i+1}$ is the only side of $\mathcal{F}$ different from $S_i^*$ that contains $E_{i+1}$.

Note that parts 2 and 3 are justified by Lemma 6.4 and Corollary 6.9. For every $i$, clearly $E_i \subseteq S_i$ and $E_{i+1} \subseteq S_i^*$, as $\gamma_{S_i}(S_i) = S_i^*$. Moreover, each pair $(E_i, S_i)$ determines the pairs $(E_{i-1}, S_{i-1})$ and $(E_{i+1}, S_{i+1})$. This is clear for the subsequent pair $(E_{i+1}, S_{i+1})$ but also for the previous one $(E_{i-1}, S_{i-1})$ because if $i \geq 2$, then $S_{i-1}^*$ is the only side of $\mathcal{F}$ containing $E_i$ and different from $S_i$ and $E_{i-1} = \gamma_{S_{i-1}}^{-1}(E_i) = \gamma_{S_{i-1}}^{-1}(E_i)$. Thus each pair $(E_i, S_i)$ determines the sequence $(E_1, S_1, \ldots)$.

Now we relate the sequence $(E_1, S_1, E_2, S_2, \ldots)$ with an edge loop of $E$. Let $L_E = \{ \gamma \in \Gamma : E \subseteq \gamma(\mathcal{F}) \}$. Clearly $1, \gamma_{S_1}^{-1} \in L_E$ and as $S_1$ is a side of $\mathcal{F}$, there is a unique edge loop of $E$ of the form $(\gamma_0 = 1, \gamma_1 = \gamma_{S_1}, \gamma_2, \ldots, \gamma_m, \gamma_0)$. As $S_2^* = S_1$ and $S_2$ are the two sides of $\mathcal{F}$ containing $E_2$, $S_1 = \gamma_{S_1}^{-1}(S_1)^*$ and $\gamma_{S_1}^{-1}(S_2)$ are the two sides of $\gamma_{S_1}^{-1}(\mathcal{F})$ containing $\gamma_{S_1}^{-1}(E_2) = E$. Therefore $\gamma_2^{-1}(S_2) = \gamma_1^{-1}(\mathcal{F}) \cap \gamma_2(\mathcal{F})$ and hence $S_2 = \mathcal{F} \cap \gamma_1 \gamma_2(\mathcal{F})$. A similar argument shows that $S_i = \mathcal{F} \cap \gamma_1 \gamma_2 \ldots \gamma_i(\mathcal{F})$ for every $i$. In particular, the sequence $(E_1, S_1, E_2, S_2, \ldots)$ is periodic, i.e. there is $n > 0$ such that $(E_{i+n}, S_{i+n}) = (E_i, S_i)$ for every $i$. If $n$ is minimal with this property, then $(E_i, S_i) \neq (E_j, S_j)$ for $1 \leq i < j \leq n$. We call $(E_1, S_1, E_2, S_2, \ldots)$ the *cycle* determined by $(E_1, S_1)$.

Hence this proves the following lemma.

**Lemma 6.15** Let $E_1$ be an edge of $\mathcal{F}$ and $S_1$ a side of $\mathcal{F}$ containing the edge $E_1$. The cycle starting with $(E_1, S_1, \ldots)$ is a finite cycle.

Note that $S_1$ and $S_n^*$ are the two different sides of $\mathcal{F}$ containing $E_1$ and thus there are two cycles starting with the edge $E_1$, namely $(E_1, S_1, \ldots, E_n, S_n)$ and $(E_1, S_n^*, E_n, S_{n-1}^*, \ldots, E_2, S_1^*)$.

It is now also clear that if $E$ is an edge and $S$ is a side containing $E$, then all the cycles containing $E$ are cyclic permutations of the cycle starting with $(E, S)$ and the cycles obtained by replacing in those the sides by their paired sides and reversing the order. In particular, if $E_i = E_j$ with $1 \leq i < j \leq n$, then $S_i \neq S_j$ and hence

\[
(E_1, S_1, E_{i+1}, S_{i+1}, \ldots, E_n, S_n, E_1, S_1, \ldots, E_{i-1}, S_{i-1}) = (E_j, S_j^*, E_{j-1}, S_{j-1}^*, \ldots, S_2^*, E_1, S_1^*, E_n, S_{n-1}^*, \ldots, E_{j+1}, S_{j+1}^*).
\]

**Lemma 6.16** If $(E_1, S_1, E_2, S_2, \ldots, E_n, S_n)$ is a cycle of $\mathcal{F}$ then $\gamma_S \gamma_{S_n} \cdots \gamma_{S_1}$ has finite order.

**Proof.** Let $\gamma = \gamma_{S_n} \gamma_{S_{n-1}} \ldots \gamma_{S_1}$. Clearly $\gamma(E_1) = E_1$ and thus $\gamma^k(E_1) = E_1$ for all non-negative integers $k$. Hence $E_1 \subseteq \gamma^k(\mathcal{F})$ and because every edge is contained in only finitely many tiles, $\gamma$ has finite order. \[\square\]

Because of Theorem 5.3, we thus obtain a natural group epimorphism

\[
\varphi : \Delta \to \Gamma : [\gamma_S] \mapsto \gamma_S
\]

where $\Delta$ is the group given by the following presentation
• Generators: a generator $[\gamma_S]$ for each side $S$ of $F$

• Relations: $[\gamma_S][\gamma_{S^*}] = 1$ if the sides $S$ and $S^*$ are paired and $([\gamma_{S_1}] \cdots [\gamma_{S_l}])^m = 1$ if $(E_1, S_1, E_2, S_2, \ldots, E_n, S_n)$ is a cycle and $m$ is the order of $\gamma_{S_1} \cdots \gamma_{S_l}$.

Our next aim is to show that $\varphi$ is also injective and thus we obtain a presentation for $\Gamma$. To that end we introduce the following definition.

**Definition 6.17** A loop of tiles is a finite list of tiles $(h_0(F), h_1(F), \ldots, h_n(F))$ with $h_i \in \Gamma$ such that $h_0(F) = h_n(F)$ and $h_{i-1}(F) \cap h_i(F)$ is of dimension 3, for every $i = 1, \ldots, n$.

The last condition means that $F \cap h_{i-1}^{-1}h_{i-1}(F)$ is of dimension 3, which is equivalent to $\gamma_i = h_{i-1}^{-1}h_i$ being a side-paring transformation. Moreover we get the relation $\gamma_1 \gamma_2 \cdots \gamma_n = 1$ which is called a loop relation. In Theorem 6.24 we will show that these relations form a complete set of relations of $\Gamma$.

It is easy to see that the pairing and cycle relations are determined by loop relations. Indeed, let $S$ and $S^*$ be two paired sides of $F$. Then $(F, \gamma_S(F), \gamma_{S^*}(F)) = F$ is a loop of tiles which gives as loop relation the pairing relation. Let $(E_1, S_1, E_2, S_2, \ldots, E_n, S_n)$ be a cycle. We have seen that there exists a positive integer $m$ such that $(\gamma_{S_1} \gamma_{S_2} \cdots \gamma_{S_l})^m = 1$. Set $h_0 = 1$ and $h_{i-1} = h_{i-1}^{-1}h_i$, where $j \equiv i \mod (n)$ and $i \in \{1, \ldots, mn\}$. Consider $(h_0(F), \ldots, h_mn(F))$. Clearly $h_mn = 1$ and hence $h_mn(F) = F = h_0(F)$. Also, for every $i \in \{1, \ldots, mn\}$, $h_{i-1}(F) \cap h_i(F) = h_{i-1}(F \cap \gamma_{S_i}(F))$, where $\gamma_S$ is a side-paring transformation and hence $F \cap \gamma_{S_i}(F)$ and thus also $h_{i-1}(F) \cap h_i(F)$ is of dimension 3. So, by definition, $(h_0(F), \ldots, h_mn(F))$ is a loop of tiles and the associated loop relation is the cycle relation.

Consider the union of intersections of varieties of $\mathcal{M}$ such that these intersections have dimension at most 1. Let $\Omega$ denote the complement of this set in $\mathbb{H}^2 \times \mathbb{H}^2$. Note that by Lemma A.1, $\Omega$ is path-connected.

In the remainder we fix $\alpha$ to be a continuous map

$$\alpha : [0, 1] \to \Omega,$$

such that

$$\alpha(0) \in g(F)^{\circ} \text{ and } \alpha(1) \in g'(F)^{\circ},$$

for some $g, g' \in \Gamma$ and such that $\alpha$ is made up of a finite number of line segments, which are parametrized by a polynomials of degree at most one. Moreover, for each line segment forming $\alpha$, we suppose that at least one of its end-points does not belong to any element in $\mathcal{M}$. Note that such a map exists. Indeed, let $\mathcal{M}_n$ denote the set consisting of the elements of $\mathcal{M}$ that have non-empty intersection with (the image of) $\alpha$. Then it is easy to see that $\Omega \setminus \bigcup_{M \in \mathcal{M}_n} M$ is dense in $\Omega$. Hence, by Lemma A.4, such a map $\alpha$ indeed exists.

**Lemma 6.18** The set $\{ t \in [0, 1] : \alpha(t) \in \partial g(F) \text{ for some } g \in \Gamma \}$ is finite.

**Proof.** We know from Lemma 3.9 that the compact set $\alpha([0, 1])$ only intersects finitely many tiles and thus also only finitely many sides. By Lemma 4.2, for every side $S$ of some tile $g(F)$, $g(F) \cap S$ is contained in a precise variety $M \in \mathcal{M}$. As the elements of $\mathcal{M}$ are real semi-algebraic varieties, which are given by polynomials, a line segment is either contained in such a variety or it intersects it in finitely many points. The path $\alpha$ consists of finitely many line segments, such that at least one of the end-points of these line segments does not belong to any element in $\mathcal{M}$. If such a line
As we call a \( M \) then there exists a unique ordered list \( L \) such that \( l \leq F \). For each \( i \in t \) absorbing on \( M \) and \( l \cap M = \emptyset \) for every \( M \in \mathcal{M} \). Thus \( \alpha(t) \) belongs to a side for only finitely many \( t \). Hence the lemma follows by Lemma 5.4.

**Lemma 6.19** Let \( \alpha \) be a continuous map \([0, 1] \to \Omega\) such that

1. \( \alpha(0) \in g(\mathcal{F})^\circ \) and \( \alpha(1) \in g'(\mathcal{F})^\circ \) for some \( g, g' \in \Gamma \),
2. \( \alpha \) is made up of a finite number of line segments,
3. for each of these line segments at least one of its two end-points does not belong to any element in \( \mathcal{M} \).

Then there exists a unique ordered list \( L = (a_0, g_1, a_1, g_2, a_2, \ldots, g_n, a_n) \), where \( g_i \in \Gamma \), \( 0 = a_0 < a_1 < \ldots < a_n = 1 \), and for every \( 1 \leq i \leq n \),

(i) \( g_{i-1} \not= g_i \),
(ii) \( \alpha([a_{i-1}, a_i]) \subseteq g_i(\mathcal{F}) \) and
(iii) there exists \( \epsilon_0 > 0 \), such that \( \alpha((a_i, a_i + \epsilon)) \cap g_i(\mathcal{F}) = \emptyset \).

We call \( L \) the partition of \( \alpha \).

**Proof.** As \( \alpha(0) \in g(\mathcal{F})^\circ \), we set \( g_1 = g \) and \( a_0 = 0 \). By Lemma 6.18, there are only finitely many \( t \in [0, 1] \) such that \( \alpha(t) \in \partial g(\mathcal{F}) \) for some \( g \in \Gamma \), say \( t_1 < t_2 < \ldots < t_m \). Put \( t_0 = 0 \) and \( t_{m+1} = 1 \). For each \( 1 \leq i \leq m + 1 \), the set \( \alpha(t_{i-1}, t_i) \) is contained in the interior of only one tile, say \( h_i(\mathcal{F}) \) with \( h_i \in \Gamma \). We now construct recursively \((a_0 = 0 = t_0, g_1 = g, a_1, g_1, \ldots, g_n, a_n)\). Let \( a_1 = t_1 \) with \( t_i \) maximal such that \( \alpha([0, t_1]) \subseteq g_1(\mathcal{F}) \). Then \( h_1 = \ldots = h_i = g_1, \alpha([t_i, t_{i+1}]) \subseteq h_{i+1}(\mathcal{F}) \) and we set \( g_2 = h_{i+1} \). Assume we have constructed \((a_0, g_1, a_1, \ldots, a_k, g_k)\) satisfying conditions (i)-(iii) and such that \( a_k = t_i \) for some \( i \) and \( g_k = h_{i+1} \). Then let \( a_{k+1} = t_j \) with \( j \) maximal with \( \alpha([t_i, t_j]) \subseteq g_k(\mathcal{F}) \) and \( g_{k+1} = h_{j+1} \). After finitely many steps, we obtain an ordered list \((a_0 = 0 = t_0, g_1 = g, a_1, g_1, \ldots, g_n, a_n)\) satisfying conditions (i)-(iii). Clearly such a sequence is unique.

**Remark 6.20** As by assumption, \( \alpha(0) \in g(\mathcal{F})^\circ \) and \( \alpha(1) \in g'(\mathcal{F})^\circ \) for some \( g, g' \in \Gamma \), the first element \( g_1 \) of the partition of \( \alpha \) equals \( g \) and the last element \( g_n \) equals \( g' \).

The reminder of the paper is based on ideas from a recent proof of the presentation part of the classical Poincaré theorem [JKDR15]. Let \( g, h \in \Gamma \). Let \( C \) be a cell of \( \mathcal{T} \) of dimension \( m \geq 2 \) and that is contained in \( g(\mathcal{F}) \cap h(\mathcal{F}) \). We define \( \kappa_C(g, h) \in \Delta \) as follows.

- If \( m = 4 \) then \( \kappa_C(g, h) = 1 \).
- If \( m = 3 \) then \( \kappa_C(g, h) = [g^{-1}h] \).

30
• If \( m = 2 \) then \( C \) is an edge contained in \( g(\mathcal{F}) \cap h(\mathcal{F}) \) and thus, by Lemma 6.12, \( g \) and \( h \) belong to an edge loop of \( C \). Up to a cyclic permutation, we can write the edge loop of \( C \) as \((g = k_0, \ldots, k_t = h, k_{t+1}, \ldots, k_m = g)\) (or the equivalent edge loop \((g = k_m, k_{m-1}, \ldots, k_t = h, k_{t-1}, \ldots, k_0 = g)\)) and we set
\[
\kappa_C(g, h) = [k_0^{-1}k_1][k_1^{-1}k_2] \cdots [k_{t-1}^{-1}k_t] = [k_m^{-1}k_{m-1}] \cdots [k_{t+1}^{-1}k_t].
\]

Observe that \( \kappa_C(g, h) = 1 \) in the three cases.

Lemma 6.21 Let \( g, h \in \Gamma \) and let \( C \) be a cell of \( \mathcal{T} \) of dimension \( m \geq 2 \) and that is contained in \( g(\mathcal{F}) \cap h(\mathcal{F}) \). The following properties hold.

1. \( \kappa_C(g, h) = \kappa_C(h, g)^{-1} \).

2. If \( D \) is cell of \( \mathcal{T} \) contained in \( C \) and of dimension at least \( 2 \) then \( \kappa_D(g, h) = \kappa_C(g, h) \).

3. If \( g_1, \ldots, g_n \in \Gamma \) and \( C \subseteq \bigcap_{i=1}^n g_i(\mathcal{F}) \) then \( \kappa_C(g_1, g_n) = \kappa_C(g_1, g_2)\kappa_C(g_2, g_3) \cdots \kappa_C(g_{n-1}, g_n) \).

Proof. 1. If \( m = 4 \), then \( g = h \) and there is nothing to prove. If \( m = 3 \) then \( g^{-1}h \) and \( h^{-1}g \) are pairing transformations and hence by the pairing relations of the group \( \Delta \), \( \kappa_C(g, h)\kappa_C(h, g) = 1 \). Finally, if \( m = 2 \), then we can write the edge loop of \( C \) as \((g = k_0, \ldots, k_t = h, k_{t+1}, \ldots, k_m = g)\) and thus
\[
\kappa_C(g, h) = [k_0^{-1}k_1][k_1^{-1}k_2] \cdots [k_{t-1}^{-1}k_t],
\]
\[
\kappa_C(h, g) = [k_t^{-1}k_{t+1}][k_{t+1}^{-1}k_{t+2}] \cdots [k_{m-1}^{-1}k_m].
\]

It is now easy to see that \( \kappa_C(g, h)\kappa_C(h, g) = 1 \) and hence the result follows.

2. If \( C = D \) then there is nothing to prove. So assume that \( C \neq D \). If \( C \) is a side then \( D \) is an edge and \( g \) and \( h \) are two consecutive elements of the edge loop of \( D \). Then \( \kappa_D(g, h) = [g^{-1}h] = \kappa_C(g, h) \). Otherwise, \( C \) is a tile and hence \( g = h \). Thus \( \kappa_D(g, h) = 1 = \kappa_C(g, h) \).

3. By induction it is enough to prove the statement for \( n = 3 \). So assume \( n = 3 \). If either \( g_1 = g_2 \) or \( g_2 = g_3 \) then the desired equality is obvious. So assume that \( g_1 \neq g_2 \) and \( g_2 \neq g_3 \). If \( C \) is an edge then, up to a cyclic permutation, possibly reversing the order and making use of Lemma 6.12, the edge loop of \( C \) is of the form \((g_1 = k_0, \ldots, g_2 = k_t, \ldots, g_3 = k_l, \ldots, k_m = g_1)\). Then,
\[
\kappa_C(g_1, g_3) = [k_0^{-1}k_1][k_1^{-1}k_2] \cdots [k_{t-1}^{-1}k_t]
= (([k_0^{-1}k_1][k_1^{-1}k_2] \cdots [k_{t-1}^{-1}k_t]) ([k_t^{-1}k_{t+1}] \cdots [k_{m-1}^{-1}k_m])
= \kappa_C(g_1, g_2)\kappa_C(g_2, g_3)
\]
Otherwise, \( S = g_1^{-1}(C) \) is a side of \( \mathcal{F} \), \( g_S = g_1^{-1}g_2 \), \( g_{S'} = g_2^{-1}g_1 \) and \( g_1 = g_3 \). Then,
\[
\kappa_C(g_1, g_3) = 1 = [g_S][g_{S'}] = \kappa_C(g_1, g_2)\kappa_C(g_2, g_3).
\]

Let \( Z \in \Omega \), \( g, h \in \Gamma \) and \( Z \subseteq C \subseteq g(\mathcal{F}) \cap h(\mathcal{F}) \) for some cell \( C \). Then, by the definition of \( \Omega \), the dimension of \( C \) is at least 2 and we define
\[
\kappa_Z(g, h) = \kappa_C(g, h).
\]
This is well defined. Indeed, suppose \( D \) is another cell containing \( Z \) and contained in \( g(\mathcal{F}) \cap h(\mathcal{F}) \) with \( \kappa_C(g, h) \neq \kappa_D(g, h) \). Then \( g \neq h \) and \( C \neq D \). Hence neither \( C \) nor \( D \) is a tile. Both are not edges, because otherwise \( Z \in C \cap D \), where the latter is an intersection of tiles and it has dimension 1, which contradicts the definition of \( \Omega \). Thus either \( C \) or \( D \) is a side and contains the other. Therefore, \( g(\mathcal{F}) \cap h(\mathcal{F}) \) is a side and hence, by part 2 of Lemma 6.21, \( \kappa_C(g, h) = [g^{-1}h] = \kappa_D(g, h) \), a contradiction. This proves that indeed \( \kappa_Z(g, h) \) is well defined. By parts 1 and 3 of Lemma 6.21 we have \( \kappa_Z(g, h) = \kappa_Z(h, g)^{-1} \) and if \( Z \in \cap_{i=1}^n g_i(\mathcal{F}) \) with \( g_1, \ldots, g_n \in \Gamma \) then

\[
\kappa_Z(g_1, g_n) = \kappa_Z(g_1, g_2) \cdots \kappa_Z(g_{n-1}, g_n).
\]

**Definition 6.22** Let \( \alpha \) be a continuous map \([0, 1] \to \Omega \) as in Lemma 6.19 and let \( \mathcal{L} = (a_0, g_1, a_1, g_2, a_2, \ldots, g_n, a_n) \) be the partition of \( \alpha \). We define

\[
\Phi(\mathcal{L}) = \kappa_{\alpha(a_1)}(g_1, g_2) \kappa_{\alpha(a_2)}(g_2, g_3) \cdots \kappa_{\alpha(a_{n-1})}(g_{n-1}, g_n),
\]

if \( n \neq 1 \). If \( n = 1 \), we set \( \Phi(\mathcal{L}) = 1 \).

Observe that if \( i \in \{1, \ldots, n\} \) then \( \alpha(a_i) \in g_i(\mathcal{F}) \cap g_{i+1}(\mathcal{F}) \). By the definition of \( \Omega \), \( g_i(\mathcal{F}) \cap g_{i+1}(\mathcal{F}) \) has dimension 2 or 3. If it has dimension 3, then \( g_i(\mathcal{F}) \cap g_{i+1}(\mathcal{F}) \) is a side containing \( \alpha(a_i) \). If \( g_i(\mathcal{F}) \cap g_{i+1}(\mathcal{F}) \) has dimension 2, then \( \bigcap_{g_i} \mathcal{G}(\mathcal{F}) \cap g_i(\mathcal{F}) \) has dimension 2 by the definition of \( \Omega \) and thus, by Lemma 6.11, \( g_i(\mathcal{F}) \cap g_{i+1}(\mathcal{F}) \) contains an edge that contains \( \alpha(a_i) \). Hence \( \alpha(a_i) \in C \subseteq g_i(\mathcal{F}) \cap g_{i+1}(\mathcal{F}) \), for some cell \( C \) and thus \( \kappa_{\alpha(a_i)}(g_i, g_{i+1}) \) is well defined.

Let \( Z, W \in \Omega \) and let \( \mathbb{P} \) be the set of all the continuous maps \( \alpha : [0, 1] \to \Omega \) with \( \alpha(0) = Z \) and \( \alpha(1) = W \), and such that \( \alpha \) verifies the conditions of Lemma 6.19. The set \( \mathbb{P} \) may be considered as a metric space with the metric determined by the infinite norm: \( ||\alpha||_\infty = \max\{||\alpha(t)|| : t \in [0, 1]\} \). We define the map

\[
\Phi : \mathbb{P} \to \Delta
\]

by \( \Phi(\alpha) = \Phi(\mathcal{L}) \), where \( \mathcal{L} \) is the partition of \( \alpha \). This is well defined as by Lemma 6.19 the partition of \( \alpha \) exists and is unique. The next lemma will be a crucial part in the proof of the injectivity of the map \( \varphi \) defined in (32).

**Lemma 6.23** If both \( Z \) and \( W \) belong to the interior of some tile then \( \Phi : \mathbb{P} \to \Delta \) is constant.

**Proof.** We claim that it is sufficient to show that \( \Phi \) is locally constant. Indeed, assume this is the case and let \( \alpha, \beta \in \mathbb{P} \). By Lemma A.2, \( \alpha \) and \( \beta \) are homotopic in \( \Omega \) and by Lemma A.5, there is a homotopy \( H(t, -) \) in \( \mathbb{P} \) from \( \alpha \) to \( \beta \). Let \( c \) denote the supremum of the \( s \in [0, 1] \) for which \( \Phi(H(s, -)) = \Phi(\alpha) \). Since, by assumption, \( \Phi \) is constant in a neighbourhood of \( H(x, -) \), it easily follows that \( c = 1 \) and thus \( \Phi(\alpha) = \Phi(\beta) \).

To prove that \( \Phi \) is locally constant, let \( \alpha, \beta \in \mathbb{P} \) and let \( \mathcal{L}_1 = (a_0, g_1, a_1, \ldots, g_n, a_n) \) and \( \mathcal{L}_2 \) be the partition of \( \alpha \) and \( \beta \) respectively. Moreover we denote by \( d(\cdot, \cdot) \) the Euclidean distance. Let \( \{0 < d_1 < d_2 < \cdots < d_m < 1\} \) be the sets of elements \( d \in [0, 1] \) such that \( \alpha(d) \in \partial g(\mathcal{F}) \) for some \( g \in \Gamma \) for every \( 1 \leq i \leq m \). Lemma 6.18 ensures that this set is finite. Denote by \( k_1, \ldots, k_{m+1} \) the elements in \( \Gamma \), such that \( \alpha(d_{i-1}, d_i) \subseteq k_i(\mathcal{F}) \) for \( 1 \leq i \leq m + 1 \), where we set \( d_0 = a_0 = 0 \) and \( d_{m+1} = a_n = 1 \). Observe that \( k_1 = g_1, k_{m+1} = g_n \) and \( \{k_1, \ldots, k_{m+1}\} = \{g_1, \ldots, g_n\} \). Since \( \mathcal{F} \) is locally finite, there is \( \delta_1 > 0 \) such that for every \( i \in \{0, 1, \ldots, m + 1\} \) and every \( g \in \Gamma \), if \( B(\alpha(d_i), 2\delta_1) \cap g(\mathcal{F}) \neq \emptyset \) then \( \alpha(d_i) \in g(\mathcal{F}) \). Since \( \alpha \) is continuous there is \( \epsilon < \min \left\{ \frac{d_i - d_{i-1}}{2} : i \in \{1, \ldots, m + 1\} \right\} \) such that, for every \( i \in \{0, 1, \ldots, m + 1\} \), \( d(\alpha(t), \alpha(d_i)) < \delta_1 \) for every \( t \) with \( |t - d_i| < \epsilon \). For every \( i \in \{1, \ldots, m\} \),
let \( d'_i = d_i - \epsilon \) and \( d''_i = d_i + \epsilon \). We also set \( d''_{m+1} = 1 \) and \( d''_0 = 0 \). Observe that \( d''_i \leq d''_{i+1} \) for every \( i \in \{0, \ldots, m+1\} \). Each \( \alpha([d''_{i-1}, d''_i]) \) is compact and it is contained in \( k_i(F)^\circ \). Again using that \( F \) is locally finite we obtain a positive number \( \delta_2 \) such that for every \( i \in \{0, 1, \ldots, m+1\} \),

\[
\delta_2 > d''(t, g(F)) > \delta_2 \quad \text{for every} \quad t \in [d''_{i-1}, d''_i] \quad \text{and every} \quad g \in \Gamma \quad \text{with} \quad g \neq k_i. \quad \text{Let} \quad \delta = \min \{\delta_1, \delta_2\}.
\]

We will prove that if \( \beta \in B_\| \|_\infty (\alpha, \delta) \), then \( \Phi(\alpha) = \Phi(\beta) \). So assume \( \beta \in \mathcal{P} \) with \( \| \alpha - \beta \|_\infty < \delta \). Then \( \delta(t, \beta(t)) < \delta \) for every \( t \in [0, 1] \). In particular, as \( \delta(t, \alpha(d_i)) < 2\delta_2 \),

\[
\text{if} \quad t \in (d'_i, d''_i) \quad \text{and} \quad \beta(t) \in g(F) \quad \text{then} \quad \alpha(d_i) \in g(F).
\]

Moreover, since \( \delta(t, \beta(t)) < \delta_2 \),

\[
\text{if} \quad t \in [d''_{i-1}, d'_i] \quad \text{and} \quad \beta(t) \in g(F) \quad \text{then} \quad g = k_i.
\]

The interval \([0,1]\) may be written as

\[
[0, d'_1) \cup [d'_1, d''_1] \cup [d''_1, d'_2] \cup \ldots \cup [d''_m, d''_{m+1}].
\]

Based on this information, we construct \( \mathcal{L}_2 \) and prove that \( \Phi(\mathcal{L}_1) = \Phi(\mathcal{L}_2) \). By (34), the elements \( k_1, \ldots, k_{m+1} \) appear in that order in \( \mathcal{L}_2 \). Between those elements may appear other elements \( h \in \Gamma \). For each \( 1 \leq i \leq m+1 \), there are two possibilities: \( k_i \) and \( k_{i+1} \) are equal or they are different. If \( k_i = k_{i+1} \) and \( k_{i+1} = k_i \), then \( k_i \) and \( k_{i+1} \) are two consecutive elements in \( \mathcal{L}_2 \), then \( \beta([d''_{i-1}, d''_{i+1}]) \subseteq k_i(F) = k_{i+1}(F) \). According to the definition of the partition of \( \beta \), \( k_i \) and \( k_{i+1} \) are represented by just one element in \( \mathcal{L}_2 \). Hence we may suppose, without loss of generality, that if \( k_i \) and \( k_{i+1} \) are two consecutive elements of \( \mathcal{L}_2 \), then they are different. Thus

\[
\mathcal{L}_2 = (0, k_1, b_1, *_1, k_2, b_2, *_2, \ldots, k_m, b_m, *_m, k_{m+1}, 1),
\]

where \( d'_1 < b_1 < d''_1 \) and \( *_i \) represents a possibly empty sequence \((h_{i1}, b_{i1}, h_{i2}, g_{i2}, \ldots, h_{in_i}, b_{in_i})\) with \( h_{ij} \in \Gamma \) and \( d'_1 < b_{ij} < d''_1 \) for every \( 1 \leq j \leq n_i \). As stated above, if \( *_i \) is empty, then \( k_i \neq k_{i+1} \).

In that case \( k_i = g_j \) and \( k_{i+1} = g_{j+1} \) are two consecutive elements in \( \mathcal{L}_1 \) and \( b_i = a_j \). Moreover

\[
\beta([d''_{i-1}, d''_i]) \subseteq k_i(F),
\]

\[
\beta([d'_i, d''_i]) \subseteq k_{i+1}(F),
\]

\[
\beta(b_i) \subseteq k_i(F) \cap k_{i+1}(F).
\]

By (33) and the fact that \( b_i \in [d'_i, d''_i] \), for every \( g \in \Gamma \) such that \( \beta(b_i) \in g(F) \) we have that \( \alpha(d_i) = \alpha(a_j) \in g(F) \). Hence, by Lemma 6.11, \( \bigcap_{g, \alpha(a_j) \in \beta(F)} g(F) \) is a cell, which is contained in every cell containing \( \beta(b_i) \). Thus both \( \alpha(a_j) \) and \( \beta(b_i) \) are included in a same cell \( C \) contained in \( g_j(F) \cap g_{j+1}(F) \). Thus,

\[
\kappa_{\alpha(a_j)}(g_j, g_{j+1}) = \kappa_C(g_j, g_{j+1}) = \kappa_C(k_i, k_{i+1}) = \kappa_{\beta(b_i)}(k_i, k_{i+1}).
\]

Suppose now that \( *_i \) is not empty. We will analyse the subsequence

\[
(k_i, b_i, h_{i1}, b_{i1}, h_{i2}, b_{i2}, \ldots, h_{in_i}, b_{in_i}, k_{i+1}, b_{i+1}).
\]

By Lemma 6.11, \( \alpha(d_i) \in C, \beta(b_i) \in C_i \) and \( \beta(b_{ij}) \in C_{ij} \) for \( C, C_i \) and \( C_{ij} \) cells for \( 1 \leq j \leq n_i \). As \( b_i \in (d'_i, d''_i) \) and also \( b_{ij} \in (d'_j, d''_j) \) for every \( 1 \leq j \leq n_i \), by (33) we have that \( \alpha(d_i) \in \)
This shows that $\Phi(L_1) = \Phi(L_2)$. □

We are now ready to prove that $\varphi : \Delta \to \Gamma$ (see (32)) is injective. Proving the injectivity is equivalent to proving that if $g_1 \ldots g_n = 1$ with each $g_i \in \Gamma$ and $\mathcal{F} \cap g_i(\mathcal{F})$ a side, then $[g_1] \ldots [g_n] = 1$ in $\Delta$. So, suppose that $g_1 \ldots g_n = 1$ with each $g_i \in \Gamma$ and $\mathcal{F} \cap g_i(\mathcal{F})$ a side. For every $i = 0, 1, \ldots, n$, put $h_i = g_i \ldots g_1$ and put $h_0 = 1$. Choose $Z \in \mathcal{F}^o$ and, for every $i = 1, \ldots, n$, choose a path from $h_{i-1}(Z)$ to $h_i(Z)$ which is only contained in $h_{i-1}(\mathcal{F}) \cup h_i(\mathcal{F})$ and which is made up of a finite number of line segments, whose end-points do not belong to any element in $\mathcal{M}$. This is possible by Lemma 3.6 and Lemma A.4. Let $\alpha$ be the path obtained by juxtaposing those paths. So $\alpha(0) = Z = \alpha(1)$ and $\alpha$ is contained in the space $\mathcal{P}$. Let $L_1 = (a_0 = 0, h_0, a_1, \ldots, h_n, a_{n+1} = 1)$ be the partition of $\alpha$. Let $\beta$ be the constant path $\beta(t) = Z$ for every $t \in [0, 1]$ and let $L_2 = (0, 1, 1)$ be the partition of $\beta$. Clearly $\beta$ is also contained in $\mathcal{P}$. Now we have that

\[
[g_1] \ldots [g_n] = [h_0^{-1} h_1][h_1^{-1} h_2] \ldots [h_n^{-1} h_n] = \kappa_{a_1}(h_0, h_1) \kappa_{a_2}(h_1, h_2) \ldots \kappa_{a_n}(h_{n-1}, h_n) = \Phi(L_1) = \Phi(\alpha).
\]

By Lemma 6.23, $\Phi(\alpha) = \Phi(\beta)$. However $\Phi(\beta) = \Phi(L_2) = \kappa_1(1, 1) = 1$ and hence $[g_1] \ldots [g_n] = 1$.

To sum up we have proven the following theorem.

**Theorem 6.24** Let $\mathcal{F}$ be the fundamental domain of $\Gamma$ as defined above. Then the following is a presentation of $\Gamma$:

- **Generators:** the pairing transformations of $\mathcal{F}$,
- **Relations:** the pairing relations and the cycle relations.

It is well known that $\Gamma$ is finitely presented. However it is not clear whether the presentation given in Theorem 6.24 is finite. The following proposition implies that at least the presentation is finite in case $R$ is a PID.
Lemma 6.25 If $R$ is a PID then every tile of $\mathcal{F}$ intersects only finitely many other tiles. In particular the fundamental domain $\mathcal{F}$ has finitely many cells and thus finitely many sides and edges.

Proof. It is enough to prove that $\mathcal{F}$ intersects only finitely many other tiles. Moreover, if $1 \neq \gamma \in \Gamma$ then $\mathcal{F} \cap \gamma(\mathcal{F}) \subseteq \cup V \in \mathcal{V}, \mathcal{F} \cap V$ and $\mathcal{V}_e$ is finite by Theorem 3.8. Thus it is enough to prove that if $V \in \mathcal{V} \cap \mathcal{V}_e$ then $X_V = \{ \gamma \in \Gamma : V \cap \mathcal{F} \cap \gamma(\mathcal{F}) \neq \emptyset \}$ is finite. If $V \in \mathcal{V}$ then $V \cap \mathcal{F}$ is compact, by Lemma 4.12. Since $\mathcal{F}$ is locally finite (Lemma 3.9), $X_V$ is finite. So assume that $V \in \mathcal{V}_e$. By (19), (21) and Lemma 3.7, there are positive real numbers $a < b$ such that $B \times (b, +\infty) \subseteq \mathcal{F} \subseteq B \times (a, +\infty)$ (in the $(s_0, s_1, r, h)$-coordinates). Let $K = B \times [a, b]$. If $\gamma \in X_V$ then either $K \cap \gamma(\mathcal{F}) \neq \emptyset$ or $V \cap (B \times (b, +\infty)) \cap \gamma(\mathcal{F}) \neq \emptyset$. As $K$ is compact and $\mathcal{F}$ is locally finite, only finitely many $\gamma \in \Gamma$ satisfy the first condition. On the other hand it is easy to see that $\mathbb{R}^2 \times \mathbb{R}^+ \times (b, \infty) = \cup_{\gamma \in \Gamma} \gamma(B \times (b, +\infty))$ (in the $(s_1, s_2, r, h)$-coordinates). Thus if $\gamma$ satisfies the second condition then $\gamma \in \Gamma$ and $\mathcal{F} \cap \gamma(\mathcal{F}) \neq \emptyset$. It remains to prove that only finitely many elements of $\Gamma$ satisfy the last condition. Fix $h_0 > 0$. Assume that $Z_1 = \gamma(Z_2) \in \mathcal{F}_\infty \cap \gamma(\mathcal{F}_\infty)$ with $\gamma \in \Gamma$. Let $Z'_1$ and $Z'_2$ be the elements of $\mathbb{R}^2 \times \mathbb{R}^2$ obtained by replacing the last coordinate of $Z_1$ and $Z_2$ by $h_0$. Then $Z'_1 = \gamma(Z'_2) \in (B \times \{h_0\}) \cap \mathcal{F}_\infty \cap \gamma(\mathcal{F}_\infty)$. Thus $(B \times \{h_0\}) \cap \gamma(\mathcal{F}_\infty) \neq \emptyset$. As $B \times \{h_0\}$ is compact and $\mathcal{F}_\infty$ is a locally finite fundamental domain of $\Gamma_\infty$, only finitely many elements satisfies the last condition. This finishes the proof. □

A Appendix: Topological Lemmas

For completeness’ sake we state some results on real algebraic topology that have been used in the previous sections. The proofs of these are probably well known to the specialists. We would like to thank Florian Eisele for making us aware of these and for providing us proofs. Some of these results can be stated in greater generality for arbitrary differential manifolds, but their proofs need more sophisticated algebraic topology methods.

Lemma A.1 Let $\mathcal{X}$ be a path-connected open subset of $\mathbb{R}^n$. Assume that if $Z_0$ and $Z_1$ are distinct points in $\mathcal{X}$, then there exists $\epsilon > 0$ such that the open cylinder with axis $[Z_0, Z_1]$ and radius $\epsilon$ is contained $\mathcal{X}$. If $L$ is a locally finite collection of semi-algebraic varieties of dimension at most $n - 2$ in $\mathcal{X}$ then $\mathcal{X} \setminus L$ is path-connected.

Lemma A.2 Let $n \geq 3$ and let $\mathcal{X}$ be a connected open subset of $\mathbb{R}^n$. Assume $\pi_1(\mathcal{X}) = 1$. If $\{T_i\}_i$ is a locally finite family of algebraic varieties in $\mathcal{X}$ of co-dimension at least 3 then

$$\pi_1\left(\mathcal{X} \setminus \bigcup_i T_i\right) = 1.$$

Lemma A.3 Let $\mathcal{B}$ be a Euclidean closed ball in $\mathbb{R}^n$. If $\mathcal{B} = U_1 \cup U_2$, where $U_1$ and $U_2$ are closed semi-algebraic sets, with $U_1 \not\subseteq U_2$ and $U_2 \not\subseteq U_1$, then $\dim(U_1 \cap U_2) \geq n - 1$.

Lemma A.4 Let $\mathcal{X}$ be a connected open subset of $\mathbb{R}^n$. If $Z$ and $W$ are points in $\mathcal{X}$ then there exists a path $\alpha : [0, 1] \to \mathcal{X}$ with $\alpha(0) = Z$ and $\alpha(1) = W$ and such that it is built from of a finite number of line segments that are parametrized by polynomials of degree at most 1. Moreover, if $\mathcal{Y}$ is a subset of $\mathcal{X}$ with dense complement in $\mathcal{X}$ and such that $Z, W \not\in \mathcal{Y}$ then we can choose the end-points of the line segments in $\mathcal{X} \setminus \mathcal{Y}$. 35
Lemma A.5 Let $X$ be a connected open subset of $\mathbb{R}^n$. Let $\gamma$ and $\gamma'$ be two homotopic paths in $X$ starting and ending at $x_0$ which are built from line segments that are parametrized by polynomials of degree at most 1. Assume we are additionally given a subset $Y \subset X$ with dense complement in $X$ and which satisfies the property that a line which is not wholly contained in $Y$ has finite intersection with it. If $x_0 \notin Y$ then there is an integer $N$ and a homotopy $H : [0,1] \times [0,1] \to X$
 from $\gamma$ to $\gamma'$ such that each loop $H(t, -)$ for $t \in [0,1]$ starts and ends in $x_0$ and there exist $0 = \tau_1 < \tau_2 < \ldots < \tau_N = 1$ such that $H(t, -)|_{[\tau_i, \tau_{i+1}]}$ is a line segment for each, $t \in (0,1)$, which is parametrized by polynomials of degree at most 1 and at least one of the two points $H(t, \tau_i)$ and $H(t, \tau_{i+1})$ lies outside $Y$.

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