Radial stability analysis of the continuous pressure gravastar

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Abstract
Radial stability of the continuous pressure gravastar is studied using the conventional Chandrasekhar method. The equation of state for the static gravastar solutions is derived and Einstein equations for small perturbations around the equilibrium are solved as an eigenvalue problem for radial pulsations. Within the model there exists a set of parameters leading to a stable fundamental mode, thus proving the radial stability of the continuous pressure gravastar. It is also shown that the central energy density possesses an extremum in $\rho_c(R)$ curve which represents a splitting point between stable and unstable gravastar configurations. As such the $\rho_c(R)$ curve for the gravastar mimics the famous $M(R)$ curve for a polytrope. Together with the former axial stability calculations this work completes the stability problem of the continuous pressure gravastar.

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(Some figures in this article are in colour only in the electronic version)

1. Introduction
Gravitational collapse as the stellar nuclear fuel is consumed could lead to black holes—objects which are accepted by the scientific community but their undesired and even paradoxical features (singularities, horizon) have motivated research in a direction of finding massive objects (stars) without singularities and without horizon. One of these alternatives is a gravastar.

Since the seminal work of Mazur and Mottola [1], the concept of the gravitational vacuum star—the gravastar—as an alternative to a black hole has attracted a plethora of interest. In this version of the gravastar a multilayered structure has been introduced: from the repulsive de Sitter core (where a negative pressure helps balance the collapsing matter) one crosses multiple
layers (shells) and without encountering a horizon one eventually reaches the (pressureless) exterior Schwarzschild spacetime. Later some simplifications [2, 3] and modifications [4] have been introduced in the original (multi)layer—onion-like picture.

An important step was done when it was shown that due to anisotropy of matter comprising the gravastar [5] one can eliminate layer(s) and, by a continuous stress–energy tensor, the transition from the interior de Sitter spacetime segment to the exterior Schwarzschild spacetime is possible [6] (see also [7]). The pressure anisotropy in the spherically symmetric geometry was perhaps first introduced by Lemaître [8] and suggested by Einstein (as quoted in [8]). The vanishing radial pressure with transversal pressure only was shown to be enough to support a stable object. Further development [9, 10] has brought different refinements to the original anisotropy notion. The pressure anisotropy, which is shown to be a necessary condition for the existence of a gravastar [5], is met also in boson star models [11] and wormholes [12]. The anisotropy (defined as a difference between the transversal and radial pressure) vanishes at the center (\( r = 0 \)) of the star as well as at its boundary (\( r = R \)). The gravastar has been confronted with its rivals—black holes [13, 14] and wormholes [12, 15, 16], and investigated with respect to energy conditions (violations) [17] and its charged properties [18, 19]. An interesting question has been posed several times: is it possible to distinguish the gravastar from a black hole [20–22]? In [20], it was shown that gravitational radiation could be used to tell a gravastar from a black hole. However, the definite answer to this question has not been given at the satisfactory level and the gravastar research is still a dynamic field with recent papers like [23–26] etc.

Almost every research mentioned above to some extent addresses the problem of the gravastar stability, since the stability problem is crucial for any object or situation to be considered as physically viable. In [1], it was first shown that such an object is thermodynamically stable, while axial stability of thin-shells gravastars was tested in [3, 4]. Stability within the thin-shell approach based on the Darmois–Israel formalism was recently reviewed in [27]. In [20], stability analysis of the thin-shell gravastar problem is closely related to an attempt to distinguish the gravastar from a black hole by analysis of quasi-normal modes produced by axial perturbations. Problem of stability of rotating the thin-shell gravastar was addressed in [28]. Stability in the (multi)layer version of the gravastar was also considered in [14, 26, 30, 31].

The axial stability of the continuous pressure gravastar was shown to be valid in [6]. This analysis was based on [32] where stability of objects with de Sitter centers was investigated.

In this paper, we analyze the radial stability of the continuous pressure gravastars [6] following the conventional Chandrasekhar method. Originally Chandrasekhar developed the method for testing the radial stability of the isotropic spheres [33] in terms of the radial pulsations. In [36] Chandrasekhar’s method was generalized to anisotropic spheres. Stability of anisotropic stars was investigated before in [37, 38] and radial stability analysis for anisotropic stars using the quasi-local equation of state (EoS) was given in [39]. The standard mathematical procedure is applied here to an object with a peculiar behavior of pressures (see below) and although the mathematical rigor was never abandoned, the analysis due to the character of the object could be considered as a toy model analysis of radial stability.

This paper is organized as follows. In section 2, the linearization of the Einstein equations is given. Static solutions are described, an EoS is derived and the pulsation equation is obtained. In section 3 the eigenvalue problem for the radial displacement is presented. Results and discussion are given in section 4.

Unless stated explicitly we shall work in units where \( G_N = 1 = c \).
2. Linearization of the Einstein equation

In this paper, the response of the continuous pressure gravastar model to small radial perturbations is considered. Assuming that the pulsating object retains its spherical symmetry, one can introduce the Schwarzschild coordinates:

\[ ds^2 = e^{\nu(r,t)} dt^2 - e^{\lambda(r,t)} dr^2 - r^2 d\theta^2 - r^2 \sin^2 \theta d\phi^2, \]

(1)

where \( \lambda \) and \( \nu \) are, in this dynamical setting, time-dependent metric functions.

The standard anisotropic energy–momentum tensor appropriate to describe continuous pressure gravastars is

\[ T^\nu_\mu = (\rho + p_r)u^\nu u_\mu - g^\nu_\mu p_r + l^\nu_\mu (p_t - p_r) + k^\nu_\mu (p_t - p_r), \]

(2)

where \( u^\mu \) is the fluid 4-velocity, \( u^\mu = \frac{dx^\mu}{ds} \), \( l^\mu \) and \( k^\mu \) are the unit 4-vectors in the \( \theta \) and \( \phi \) directions, respectively, \( l^\mu = -r \delta^\theta_\mu \), \( k^\mu = -r \sin \theta \delta^\phi_\mu \).

The velocity of the fluid element in the radial direction \( \xi \) is defined by

\[ \xi = \frac{dr}{dt} = \frac{u^r}{u^t}, \]

(3)

where \( \xi \) is the radial displacement of the fluid element, \( r \rightarrow r + \xi(r,t) \). The components of the 4-velocity are obtained by employing \( u^\mu u_\mu = 1 \) and equation (3):

\[ u^\mu = \left( e^{-\nu/2}, \frac{\dot{\xi} e^{-\nu/2}}{e^{-\lambda}}, 0, 0 \right). \]

(4)

The non-zero components of the energy–momentum tensor (2) linear in \( \xi \) are

\[ T^t_t = \rho, \quad T^r_r = -p_r, \quad T^\theta_\theta = T^\phi_\phi = -p_t, \]

\[ T^r_t = \ddot{\xi} (\rho + p_r) + e^{-\nu} \left( \frac{\ddot{\lambda}}{r} - \frac{\dot{\lambda}}{r^2} \right), \]

(5)

The components of the Einstein tensor for the metric (1) are

\[ G^\lambda_\lambda = e^{-\lambda} \left( \frac{\ddot{\lambda}}{r} - \frac{\dot{\lambda}^2}{r^2} \right) + \frac{1}{r^2}, \]

(6)

\[ G^\nu_\nu = -e^{-\lambda} \left( \frac{\ddot{\nu}}{r} + \frac{\dot{\nu}^2}{r^2} \right) + \frac{1}{r^2}, \]

(7)

\[ G^\lambda_r = -e^{-\lambda} \frac{\ddot{\nu}}{r}, \]

(8)

\[ G^\theta_\theta = G^\phi_\phi = -\frac{1}{2} e^{-\lambda} \left( -\frac{\ddot{\nu} \dot{\lambda}}{2} - \frac{\dot{\nu} \ddot{\lambda}}{2} - \frac{\dot{\nu}^2}{2} - \frac{\dot{\nu} \dot{\lambda}}{2} \right) + \frac{1}{2} e^{-\nu} \left( \ddot{\nu} + \frac{\dot{\nu}^2}{2} - \frac{\dot{\lambda} \ddot{\nu}}{2} \right). \]

(9)

Following the standard Chandrasekhar method, all matter and metric functions should only slightly deviate from their equilibrium solutions,

\[ \lambda(r,t) = \lambda_0(r) + \delta \lambda(r,t), \quad \nu(r,t) = \nu_0(r) + \delta \nu(r,t), \]

(10)

\[ \rho(r,t) = \rho_0(r) + \delta \rho(r,t), \quad p_r(r,t) = \rho_0(r) + \delta p_r(r,t), \]

(11)

The subscript 0 denotes the equilibrium functions and \( \delta f(r,t) \) are the so-called Eulerian perturbations, where \( f \in \{ \lambda, \nu, \rho, p_r, p_t \} \). The Eulerian perturbations measure a local departure from equilibrium in contrast to the Lagrangian perturbations, denoted as \( d f(r,t) \), which measure a departure from equilibrium in the co-moving system (fluid rest frame).
Lagrangian perturbations in the linear approximation play a role of a total differential and are linked to the Eulerian perturbations via the equation (see e.g. [40]):

$$df(r,t) = \delta f(r,t) + f'_0(r)\xi.$$  

(12)

A linearization of the Einstein equations $G^\mu_\nu = 8\pi T^\mu_\nu$ leads to the two sets of equations: one for the equilibrium (static) functions and the other for the perturbed functions. The equilibrium functions obey the following set of equations:

$$8\pi \rho_0 = e^{-\lambda_0} \left( \frac{\lambda'_0}{r} - \frac{1}{r^2} \right) + \frac{1}{r^2},$$  

(13)

$$8\pi p_{r0} = e^{-\lambda_0} \left( \frac{v'_{0r}}{r} + \frac{1}{r^2} \right) - \frac{1}{r^2},$$  

(14)

$$8\pi p_{t0} = \frac{1}{2} e^{-\lambda_0} \left( \frac{-v'_{0r}v'O'_{0r}}{2} - \frac{\lambda'_0}{r} + \frac{v'_{0r}}{r} + \frac{v''_{0r}}{2} \right).$$  

(15)

In practice, one usually combines these three equations with the Tolman–Oppenheimer–Volkoff (TOV) equation:

$$p'_r = -\frac{1}{2} \left( \rho_0 + p_{r0} \right) v'_0 + \frac{2}{r} \Pi_0,$$  

(16)

where $\Pi_0$ denotes the anisotropic term $\Pi_0 = p_{r0} - p_{t0}$. The other set of equations emerging from the linearization of the above Einstein equations yield the set of equations for the perturbed functions:

$$(re^{-\lambda_0}\delta\lambda)' = 8\pi r^2 \delta\rho,$$  

(17)

$$\delta v' = \left( v'_0 + \frac{1}{r} \right) \delta\lambda + 8\pi r e^{\lambda_0} \delta p_r,$$  

(18)

$$\delta\lambda e^{-\lambda_0} = -8\pi \xi (\rho_0 + p_{r0}),$$  

(19)

$$e^{\lambda_0-v_0} (\rho_0 + p_{r0}) \delta v' + \frac{1}{2} (\rho_0 + p_{r0}) \delta v' + \frac{1}{2} (\delta\rho + \delta p_r) v'_0 + \delta p'_r = \frac{2}{r} \delta\Pi = 0.$$  

(20)

Equation (20) is known as the pulsation equation [36] and it serves to probe the radial stability of the system of interest. It is actually the TOV equation for the perturbed functions which is obtained—analogously as the non-perturbed TOV—by combining Einstein equations for perturbed functions.

In order to solve the pulsation equation (20) for the gravastar all perturbed functions should be expressed in terms of the radial displacement $\xi$ (and its derivatives) and the equilibrium functions. In performing this, one first integrates equation (19) in time, yielding

$$\delta\lambda = -8\pi r e^{\lambda_0} \xi (\rho_0 + p_{r0}).$$  

(21)

Using this expression for $\delta\rho$ in equation (17) one obtains

$$\delta\rho = -\frac{1}{r^2} \left[ r^2 (\rho_0 + p_{r0}) \xi \right]'.$$  

(22)

After inserting $\delta\lambda$ in equation (18) a dependence on $\delta p_r$ remains, which should be expressed in terms of the displacement function (and its derivatives) and the equilibrium functions. To accomplish this, one ought to explore the system at hand in more detail.
One of the possibilities, as suggested firstly by Chandrasekhar for isotropic structures [33] and more recently by Dev and Gleiser for anisotropic objects [36], is to make use of the baryon density conservation to express the radial pressure perturbation in terms of the displacement function and the static solutions. In this approach, the adiabatic index appears as a free parameter. Chandrasekhar used this method to establish limiting values of the adiabatic index leading to an (un)stable isotropic object of a constant energy density. He showed that there were no stable stars of this kind if the adiabatic index was less than \(4/3 + \kappa M/R\) (\(\kappa\) is a constant of order unity depending on the structure of the star, \(M\) and \(R\) are the star’s mass and radius). In [36], the Chandrasekhar method was extended to various anisotropic star models and showed that the limiting value of the adiabatic index is shifted to lower values, i.e. anisotropic stars can approach the stability region with smaller adiabatic index than in Chandrasekhar’s case.

In this paper, our primary concern is to probe the radial stability of one particular anisotropic object—the gravastar. Due to the peculiar character of the gravastar (especially its radial pressure—see below) one cannot expect the adiabatic index to be constant along the whole object. In fact, the adiabatic index is a function of the energy density and pressure(s). This is the main reason why in this paper stability will not be tested by fixing the appropriate values of the adiabatic index that guarantee stability. The required information will rather be extracted from a given static solution by constructing the EoS.

2.1. Static solution

The procedure discussed so far is applicable to all spherically symmetric structures. To apply it to gravastar configurations one has to recall the basic characteristics of gravastars in the continuous pressure picture [6]. The energy density \(\rho_0(r)\) is positive and monotonically decreases from the center to the surface. Gravastars have a de Sitter-like interior, \(p_0(0) = -\rho_0(0)\), and a Schwarzschild-like exterior. Furthermore, the atmosphere of the gravastar is defined as an outer region, near to the surface, where ‘normal’ physics is valid [5], i.e. where both the energy density and the radial pressure are positive and monotonically decreasing functions of the radius. In the gravastar’s atmosphere the sound velocity \(v_s\), with

\[ v_s^2 = \frac{d p_0}{d \rho_0}, \tag{23} \]

is real \((v_s^2 > 0)\) and subluminal \((v_s < 1)\).

From the peculiar shape of the gravastar’s (radial) pressure one can immediately infer that the sound velocity ought to be real only in the gravastar’s atmosphere, whilst in the gravastar’s interior it is imaginary, \(v_s^2 < 0\). This is the main reason why, in probing the radial stability, we shall be primarily concerned with the physical processes occurring in the gravastar’s atmosphere.

To construct a static gravastar, the energy density profile and the anisotropic term are adopted from the previous work [6, 18]:

\[ \rho_0(r) = \rho_c(1 - (r/R)^n), \tag{24} \]

\[ \Pi_0(r) = \beta \rho_0(r)^m \mu_0(r). \tag{25} \]

Here \(n\) and \(m\) are (free) parameters and \(\rho_c = \rho_0(0)\) is the central energy density. \(\beta\) is the anisotropy strength measure and \(R\) is the radius of the gravastar for which \(p_0(R) = 0\). \(\mu_0(r)\) is the compactness function defined by \(\mu_0(r) = 2m_0(r)/r\), where \(m_0(r)\) is the mass function \(m_0(r) = 4\pi \int_0^r \rho_0(r)r^2 dr\). The radial pressure \(p_0\) is a solution of the TOV (16) and the tangential pressure is readily obtained from the anisotropy and the radial pressure by
The energy density $\rho_0/\rho_c$, radial pressure $p_{r0}/\rho_c$, tangential pressure $p_{t0}/\rho_c$, and compactness $\mu_0$ as a function of radius $r/R$ for $\{R, n, m\} = \{1, 2, 3\}$. Three different values of the central energy density $\rho_c = \{0.190, 0.202, 0.210\}$ and their anisotropy strengths $\beta = \{92.905, 81.410, 76.110\}$ correspond to the lower, middle and upper curves, respectively. $r_0$ denotes the radius at which the sound velocity (23) vanishes (for the central curve).

employing the identity $p_{t0} = p_{r0} + \Pi_0$. The particular form of the anisotropic term is dictated by the behavior of pressures at de Sitter core, since at $r = 0$ the anisotropy should vanish as seen from (16). Also, the above form of the anisotropy term ensures that the radial pressure vanishes at $r = R$. The transversal pressure vanishes as well although it is not necessary to be the case (see [6] for the gravastar model with the non-vanishing transverse pressure.). The anisotropy strength measure is controlled as well by the energy conditions which have to be met.

One such solution for fixed $(R, n, m) = (1, 2, 3)$ is shown in figure 1 for three different values of the central energy density $\rho_c$ corresponding to three different values of the anisotropy strength $\beta$. Since the radius $R$ is fixed, there is an interplay between the central energy density $\rho_c$ and anisotropy strength $\beta$—a higher central energy density $\rho_c$ requires a smaller anisotropy strength $\beta$. We shall elaborate on this particular choice of parameters in section 4, where the radial stability of these three gravastar configurations will be tested.

In the inset of figure 1, the radial pressure close to the surface is extracted in order to show important features of the gravastar’s atmosphere. At the radius $r_0$ the sound velocity of the fluid vanishes $\left(\frac{dp_{r0}}{d\rho_0}\bigg|_{r=r_0} = 0\right)$ and hence $r_0$ serves as a division point of the propagating (or physically reasonable) $(r > r_0, v_s^2 > 0)$ and non-propagating regions $(r < r_0, v_s^2 < 0)$ when probing radial pulsations of the gravastar.

The dominant energy condition, i.e. $p_{r0}, p_{t0} \leq \rho_0$, is obeyed by both radial and tangential pressure throughout the gravastar. The compactness function has also been shown in figure 1.

2.2. Equation of state

In this subsection, we note that the EoS appropriate to describe the gravastar (inferred from the input functions (24) and (25)) is actually a functional of the energy density (only), parameterized by the anisotropy strength $\beta$. Next, this result is used to compute the Eulerian perturbation of the radial pressure $\delta p_r$ from the EoS, by perturbing the energy density only. Ultimately, this completes the task to express all perturbed functions in terms of the displacement (and its derivatives) and the static solutions.
Figure 2. The radial pressure $p_r/\rho_c$ is plotted against the energy density $\rho_0/\rho_c$ (EoS) for $\{R,n,m\} = \{1,2,3\}$. Three different values of the central energy density $\rho_c = \{0.190, 0.202, 0.210\}$ and their anisotropy strengths $\beta = \{92.905, 81.410, 76.110\}$ correspond to the lower, middle and upper curves, respectively.

Generally, for isotropic structures, before solving the TOV, one assumes that the pressure $p$ and the energy density $\rho$ are functions of the specific entropy $s$ and the baryon density $n$. If a system is described by the one-fluid model, then in static and dynamic settings it exhibits isentropic behavior (constant $s$), in which case one can set $s = 0$. Thus, it is possible to eliminate the baryon density $n$ and express the pressure in terms of the energy density only, leading to a barotropic EoS $p = p(\rho)$. It is rather a simple task now to perturb this EoS and express the perturbed pressure in terms of the perturbed energy density.

For anisotropic objects, the EoS is highly dependent on the anisotropic term model (see e.g. the TOV (16)). The particular choice of the anisotropic term used here (25) is a functional (or a quasi-local variable1) of the energy density. This means that for a fixed anisotropy strength $\beta$ there is a two-parameter family of values $\{\rho_c, R\}$ belonging to the same EoS (see figure 2). As a consequence, one can obtain perturbed (radial) pressure by perturbing the energy density only, and keeping the anisotropy strength $\beta$ fixed.

To illustrate this in more detail let us introduce an analytic form of the EoS which, to a good approximation, describes the gravastar configuration defined by (24) and (25)2:

$$p_{\rho_0}[\rho_0] = -\rho_0^2 \left( \frac{1}{\rho_c} - \alpha \mu_0[\rho_0] \right).$$  \hspace{1cm} (26)

Here, $\alpha$ is closely related to the anisotropy strength $\beta$, $\mu_0[\rho_0]$ is the compactness function which is a functional of the energy density. Now, it is clear that for a fixed $\alpha$ the (radial) pressure is fully determined by the energy density.

Hence, following the reasoning outlined above and making use of equation (12), in the linear approximation the Eulerian perturbation for the radial pressure is

$$\delta p_r = -p'_r \xi + \frac{d p_{\rho_0}[\rho_0]}{d\rho_0}(\delta \rho + \rho'_0 \xi).$$  \hspace{1cm} (27)

1 By the quasi-local variable we mean a function which is an integral in space of some local function—for example, the mass function $m_0(r)$ is a quasi-local variable of the energy density (which is a local function) as it is the volume integral of the energy density (the same holds for the compactness function). For a discussion of quasi-local variables and quasi-local EoS see e.g. [34, 35] and [39].

2 It is worth noting that the analytic form of the EoS (26) is not restricted to the chosen energy density (24). For example, it is also appropriate to describe a gravastar with the energy density of the form $\rho_0(r) = \rho_c e^{-\eta r^2}$. 

Here, \( \frac{d}{d\rho_0} \frac{d\rho_0}{dr} \) denotes functional derivative of the radial pressure with respect to the energy density. This is equal to \( \frac{\delta P_r}{\delta \rho_0} \) as both the radial pressure and the energy density are functions of radius \( r \) only.

Similarly, the Eulerian perturbation of the anisotropy \( \delta \Pi \) assumes the form

\[
\delta \Pi = -\Pi_0' \xi + \frac{d\Pi_0[\rho_0]}{d\rho_0} (\delta \rho + \rho_0') \xi.
\]

(28)

With the above two expressions the pulsation equation (20) is fully determined. However, before proceeding to solve the pulsation equation it is useful to rewrite equation (27) in a slightly different form in order to compare the result in this paper with that of Chandrasekhar’s for isotropic, and Dev and Gleiser’s for anisotropic stars. By means of the TOV (16), the perturbed energy density (22) can be written as

\[
\delta \rho = -\rho_0' \xi - (\rho_0 + p_0') \frac{d\rho_0[\rho_0]}{d\rho_0} \frac{e^{\nu_0/2}}{r^2} (r^2 e^{-\nu_0/2} \xi)' - \frac{2}{r} \Pi_0 \xi.
\]

(29)

Inserting this result in equation (27), the radial pressure perturbation becomes

\[
\delta p_r = -p_0' \xi - (\rho_0 + p_0') \frac{d\rho_0[\rho_0]}{d\rho_0} \frac{e^{\nu_0/2}}{r^2} (r^2 e^{-\nu_0/2} \xi)' - \frac{2}{r} \Pi_0 \frac{d\rho_0[\rho_0]}{d\rho_0} \xi.
\]

(30)

If one now identifies the adiabatic ‘index’ as

\[
\gamma = \frac{\rho_0 + p_0}{p_0'} \frac{d\rho_0[\rho_0]}{d\rho_0},
\]

(31)

the result derived in equation (30) reduces to that of Dev and Gleiser [36], equation (86). However, the expressions for \( \gamma \) differ. Moreover, if one turns off anisotropy (\( \Pi_0 = 0 \)) Chandrasekhar’s result is obtained.

3. The pulsation equation as an eigenvalue problem

As in the Chandrasekhar method all matter and metric functions exhibit oscillatory behavior in time, \( f(r, t) = e^{i\omega t} f(r) \). Hence, the pulsation equation assumes the form

\[
P_0 \xi'' + P_1 \xi' + P_2 \xi = -\omega^2 \xi,
\]

(32)

where \( P_0, P_1, P_2 \) and \( P_0 \) are polynomial functions of \( r \), depending on the static solutions only (see figure 3). Equation (32) represents an eigenvalue equation for the radial displacement \( \xi \) (with \( \omega^2 \) being an eigenvalue). Solutions of this differential equation are obtained by specifying boundary conditions in the center and at the surface of the gravastar:

\[
\xi = 0 \quad \text{at} \quad r = 0,
\]

(33)

\[
\Delta p_r = 0 \quad \text{at} \quad r = R.
\]

(34)

The boundary condition in the center demands that there is no displacement of the fluid in the center of the gravastar. The boundary condition at the surface follows from the requirement that the Lagrangian radial pressure perturbation has to vanish at the surface [40–42]. In the model presented here where \( \Delta p_r = (d\rho_0[\rho_0]/d\rho_0) \Delta \rho_0 \), the sound velocity vanishes at the surface, \( d\rho_0[\rho_0]/d\rho_0 \mid_{r=R} = 0 \). This means that, apart from being finite, there are no further restrictions on \( \Delta \rho_0(R) \). This also implies that it is sufficient to demand that \( \xi(R) \) and \( \xi'(R) \) are bounded in order to satisfy the boundary condition at the surface [41]. The choice

\[
\xi'(R) = 0
\]

(35)

enables one to compare the results in the gravastar’s atmosphere with the radial oscillations of the polytropes. This can be relevant as the EoS of the gravastar’s atmosphere close to the
surface can be approximated by the polytropic EoS $p_r \propto \rho^{1+1/n_p}$, where $n_p$ is a polytropic index [6, 18].

In order to study the radial stability of the system described by equation (20) subject to the boundary conditions (33) and (34), it is plausible to recast the pulsation equation into the standard Sturm–Liouville form (see e.g. [40]):

\[(P\xi)' + Q\xi = -\omega^2 W\xi,\]

where
\[P = e^\int \frac{P_1}{P_0} \, dr\]
and
\[Q = \frac{P_2}{P_0} P, \quad W = \frac{P_0}{P_0}.\]

The leading coefficient in the pulsation equation $P_0$ has three zeros—two at the ends $0, R$ and one in the interior region $r_0$ (\(d(p_{r}/d\rho)|_{r_0} = 0\)); hence, $P_1/P_0$ has three singular points (see figure 3), though all three are regular singular points or Fuchsian singularities [43].

In order to obtain $P$, the integral \(\int P_1/P_0 \, dr\) should be calculated, and since the interior singularity arises at $r_0$ which is a division point between propagating and non-propagating domains, it is reasonable to divide the whole interval $I = [0, R]$ in two parts: $I_1 = (0, r_0)$ and $I_2 = (r_0, R)$. In performing the integration numerically infinitesimally small regions around all three singular points \(0, r_0, R\) are excluded, so that both integrals are rendered convergent and finite. As a consequence, the leading coefficient in the Sturm–Liouville equation $P$ is a positive function on the (whole) interval $I$, whilst the weight function $W$ is negative on the interval $I_1$ and positive on the interval $I_2$. As elucidated in the previous section, the interesting region is the gravastar’s atmosphere, i.e. the second interval, $I_2$. In this region, the standard Sturm–Liouville eigenvalue problem formalism (see e.g. [41]) is applied, since $P > 0$ and $W > 0$. Therefore if $\omega^2$ is positive, $\omega$ itself is real and the solution is oscillatory. If on the other hand $\omega^2$ is negative, $\omega$ is imaginary and the solution is exponentially growing or decaying in time, thus signaling instabilities. The number of nodes of the eigenvector $\xi$ for a given eigenvalue $\omega^2$ is closely related to the stability criteria. To be more precise, if for $\omega^2 = 0$ eigenvector $\xi$ has no nodes, then all higher frequency radial modes are stable. Otherwise, if

A singular point $r^*$ is regular (or Fuchsian) if the function $P_1/P_0$ has a pole of at most first order, and the function $P_2/P_0$ has a pole of at most second order at the singular point $r = r^*$.
for $\omega^2 = 0$ eigenvector $\xi$ exhibits nodes, then all radial modes are unstable. Furthermore, if the system is stable, then the following relations hold

$$\omega_0^2 < \omega_1^2 < \cdots < \omega_n^2 < \cdots,$$

where $n$ equals the number of nodes.

4. Results and discussion

In testing the stability of certain configurations in general, it seems natural that one attempts to find critical values of the parameters for which the system is marginally stable. Marginal stability means here that there exists a set of parameters for which the system exhibits the stable fundamental mode ($n = 0$) for $\omega_0^2 = 0$. Then, for the given set of parameters all higher frequency modes are radially stable. For example, in the case of neutron stars (described by the polytropic equation of state (EoS)), there exists a critical value of the central energy density for which the stellar mass $M$ as a function of radius $R$ is extremal. For such a critical value of the central energy density the star exhibits stable fundamental mode with $\omega_0^2 = 0$, which implies that all higher frequency modes with the given central energy density are then radially stable. Furthermore, at the account of the $M(R)$ curve one can then read off which configuration of the EoS will produce a stable star and which will not.

The continuous pressure gravastar model described here displays a quite similar behavior. For each EoS (fixed $\beta$), the extremum of the $\rho_c(R)$ curve represents critical values of the parameters $\{\rho_c, R\}$ for which the system exhibits a stable fundamental mode, $\omega_0^2 = 0$ (see figure 4). Then, for such critical set of parameters all higher frequency modes are radially stable. Moreover, for smaller radii the system exhibits stability, whereas for larger radii (than the critical one) it reveals instability (see figure 4). In this sense, the $\rho_c(R)$ curve for the gravastar mimics the well-known $M(R)$ curve for a polytrope. To prove these statements, the behavior of the displacement function $\xi$ is shown in figure 5 for three different cases. The radius $R$ is, for simplicity, fixed (for all three cases) to be the critical radius of the central curve in figure 4. According to figure 4 one then expects that the radial displacements $\xi$
The displacement function $\xi(r)$ for $\{R, n, m\} = \{1, 2, 3\}$ and $\omega^2 = 0$. Three different values of the central energy density $\rho_c = \{0.190, 0.202, 0.210\}$ and their respective anisotropy strengths $\beta = \{92.905, 81.410, 76.110\}$ correspond to the lower (unstable), middle (marginally stable) and upper (stable) curves, respectively.

The central (solid) curve in figure 5 represents the marginally stable fundamental mode—an eigenvector $\xi$ is obtained for $\omega^2 = 0$. The upper (short-dashed) curve clearly shows stability of all radial modes as for $\omega^2 = 0$ there are no nodes, while the lower (long-dashed) curve reveals instabilities of all radial modes as there is a node in the fundamental mode. The lower, middle and upper curves in figure 5 correspond to the upper, middle and lower curves in figures 1 and 2, respectively. Here, again one is able to relate this result to that of [36]; from figure 5, according to the values of the anisotropy strengths $\beta$, one can conclude that the anisotropy enhances stability.

Albeit from the viewpoint of radial pulsations, the gravastar’s inner region does not seem to be physically attractive as the sound velocity is imaginary there, it is important to add a couple of comments on the radial displacement’s behavior in that region. Pulsations are strongly attenuated in the gravastar’s interior (see figure 5). This holds for all $\omega^2 > 0$. Therefore, the radial pulsations of the gravastar as a whole can be seen as occurring prevalently in the gravastar’s atmosphere whereas entering the interior region, they are exponentially (but smoothly) attenuated. This is actually what one would intuitively expect from the repulsive gravitation caused by the de Sitter-like interior$^4$.

In this paper, the focus was set on one very specific star model—the gravastar. Therefore, standard stability analysis which has been applied here in every detail could be considered as a toy model of the radial stability analysis. However, it could be extended to a broader class of anisotropic stars with the anisotropy being a functional of the energy density. In this way, the adiabatic ‘index’ does not have to be set to a constant but calculated from the static configurations. This comprises one of the main results of this paper.

The main result of this work is the observation that the continuous pressure gravastar model presented here exhibits the radial stability as illustrated in figures 4 and 5. This result is

$^4$ A good example of such a space is an inflationary Universe. The electric and magnetic fields of free photons in such an inflationary (quasi-de Sitter) space get (exponentially) damped as $\propto 1/a^2$, while the physical wavelength gets stretched as $\propto a$. Here, $a$ denotes the scale factor of the Universe, which during inflation grows nearly exponentially in time.
important as it, along with the axial stability analysis, suggests that gravastars, although not yet fully understood at the fundamental level, may be viable physical compact object candidates.

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