Bianchi type A hyper-symplectic and hyper-Kähler metrics in 4D

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Abstract

We present a simple explicit construction of hyper-Kähler and hyper-symplectic (also known as neutral hyper-Kähler or hyper-para-Kähler) metrics in 4D using the Bianchi type groups of class A. The construction underlies a correspondence between hyper-Kähler and hyper-symplectic structures of dimension 4.

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1. Introduction

Manifolds carrying a hyper-symplectic structure are the pseudo-Riemannian counterpart to hyper-Kähler manifolds. They are defined as follows. An almost hyper-paracomplex structure on a $4n$-dimensional manifold $M$ is a triple $(J, P_1, P_2)$ of anti-commuting endomorphisms of the tangent bundle of $M$ satisfying the paraquaternionic identities

$$J^2 = -P_1^2 = -P_2^2 = -Id, \quad JP_1 = P_2.$$

In this case, $(M, J, P_1, P_2)$ is said to be an almost hyper-paracomplex manifold. Moreover, if $g$ is a pseudo-Riemannian metric on $(M, J, P_1, P_2)$ for which $J$ is an isometry while $P_1$ and $P_2$ are anti-isometries, then $g$ is called an almost hyper-para-Hermitian metric. Necessarily $g$ is a neutral metric, that is, of signature $(2n, 2n)$. Such a metric gives rise to three 2-forms on $M$ defined in a way similar to the Kähler forms in the positive definite case (see sections 2 and 3 for details). When these three forms are closed, the structure $(g, J, P_1, P_2)$ is called hyper-symplectic [28]. In this case, the structures $(J, P_1, P_2)$ are parallel with respect
to the Lévi-Cività connection of the neutral metric \( g \) and, in particular, integrable. Metrics associated with a hyper-symplectic structure are also called neutral hyper-Kähler [34], para-hyper-Kähler [6], hyper-para-Kähler [32], etc.

Manifolds with a hyper-symplectic structure have also a rich geometry. Indeed, the neutral metric is Kähler, Ricci flat, and its holonomy group is contained in \( Sp(2n, \mathbb{R}) \) [28]. Furthermore, in dimension 4, any hyper-symplectic structure underlies an anti-self-dual (ASD) and Ricci-flat neutral metric. For this reason such structures have been used in string theory [42, 30, 33, 3, 31, 10, 26] and integrable systems [16, 4, 17]. In fact, \( N = 2 \) superstring theory is considered in [42], and it is proved that the critical dimension of such a string is 4 and that the bosonic part of the \( N = 2 \) theory corresponds to self-dual (SD) metrics of signature \((2, 2)\).

There are not many known explicit hyper-symplectic metrics. In dimension 4, they were described in [14, 43, 35, 26]. In higher dimensions, hyper-symplectic structures on a class of compact quotients of two-step nilpotent Lie groups were exhibited [19]. Also, a procedure to construct hyper-symplectic structures on \( \mathbb{R}^{4n} \) with complete and not necessarily flat associated neutral metrics is given in [1].

On the other hand, Bourliot, Estes, Petropoulos and Spindel in [8] (see also [7]) showed a classification of SD four-dimensional gravitational instantons. Their classification is based on the algebra homomorphisms relating the Bianchi group and the \( SO(3) \) group. In [7], it is noted that the groups VI\(_0\) and VIII of Bianchi classification do not seem interesting for gravitational instantons taking into account their complex nature, but they may play a more physical role in the context of neutral hyper-Kähler metrics.

In this paper, following an idea originally proposed by Hitchin [29], we re-construct in a simple way the well-known (cohomogeneity-one) hyper-Kähler metrics of dimension 4 arising from the three-dimensional groups of Bianchi type A and give an explicit construction of hyper-symplectic metrics of signature \((2, 2)\) (that is, of signature \((+,-,+,+)\)), some of which seem to be new. We follow Hitchin’s idea [29] reducing the problem to a solution of a certain system of evolution equations applying two results of Hitchin, which assert that an almost hyper-Hermitian structure (resp. an almost para-hyper-Hermitian structure) is hyper-Kähler (resp. hyper-symplectic) exactly when the three Kähler forms are closed [27] (respectively [28]). In this way, we recover some of the known (Bianchi-type) hyper-Kähler metrics of dimension 4 [38, 39, 37, 18, 22, 5, 24, 20, 21, 25, 3, 40, 15, 12, 44]. Our approach seems to be particularly simple and leads quickly to the explicit form of the considered metrics. In [35] a correspondence between Bianchi-type IX hyper-Kähler metric and Bianchi-type VIII hyper-symplectic metric was discovered. Our construction shows that the system of evolution equations describing the hyper-Kähler metrics of Bianchi types IX, VIII, VII\(_0\), VI\(_0\), II coincides with the system describing hyper-symplectic metrics of Bianchi types VIII, IX, VI\(_0\), VII\(_0\), II, respectively. This extends the correspondence found in [35] between hyper-Kähler and hyper-symplectic metrics arising from three-dimensional groups \( SU(2) \) and \( SU(1, 1) \) to a correspondence between hyper-Kähler and hyper-symplectic metrics arising from the three-dimensional groups of Lorentzian and Euclidean motions and the Heisenberg group, respectively.

**Convention 1.1.** The triple \((i, j, k)\) denotes any cyclic permutation of \((1,2,3)\).

### 2. Hyper-Kähler metrics of dimension 4

In this section, we recover some of the known hyper-Kähler metrics of dimension 4. To this end, we lift the special structure on the non-Euclidean Bianchi-type groups of class A to a hyper-Kähler metric on its product with (an interval in) the real line.
Let us recall first that an almost hypercomplex structure on the 4n-dimensional manifold $M$ is a triple $(J_1, J_2, J_3)$ of almost complex structures on $M$ satisfying the quaternionic identities, that is,

$$J_1^2 = J_2^2 = J_3^2 = -1, \quad J_1J_2 = -J_2J_1 = J_3.$$ 

An almost hypercomplex manifold $(M, J_1, J_2, J_3)$ is said to be almost hyper-Hermitian if there exists a Riemannian metric $g$ on $M$ for which each of the almost complex structures $J_s$, $s = 1, 2, 3$, is an isometry, that is, they satisfy the compatibility conditions

$$g(J_s, J_s) = g(\cdot, \cdot), \quad s = 1, 2, 3.$$ 

In this case, we can define the fundamental 2-forms $F_s$ of the almost hyper-Hermitian manifold $(M, g, J_1, J_2, J_3)$ by

$$F_s(\cdot, \cdot) = g(J_s, \cdot), \quad s = 1, 2, 3.$$ \hspace{1cm} (2.1)

When the structures $J_s$, $s = 1, 2, 3$, are parallel with respect to the Lévi-Civitá connection, $(M, g, J_1, J_2, J_3)$ is said to be a hyper-Kähler manifold. A result of Hitchin [27] states that the fundamental 2-forms are closed exactly when the almost hyper-Hermitian structure is hyper-Kähler.

Let $G$ be a three-dimensional Lie group and $\{e^1(t), e^2(t), e^3(t)\}$ be a global basis of 1-forms on $G$ for each $t \in I$, where $I \subset \mathbb{R}$ is a connected interval in the real line. We consider the almost hyper-Hermitian structure on $G \times I$ defined by the following fundamental 2-forms:

$$F_1 = e^1(t) \wedge e^2(t) + e^3(t) \wedge f(t) \, dt,$$

$$F_2 = e^1(t) \wedge e^3(t) - e^2(t) \wedge f(t) \, dt,$$

$$F_3 = e^2(t) \wedge e^3(t) + e^1(t) \wedge f(t) \, dt.$$ \hspace{1cm} (2.2)

where $f(t)$ is a function of $t \in I$ which does not vanish. Using $\{e^1(t), e^2(t), e^3(t), f(t) \, dt\}$ as a positively oriented orthonormal basis the fundamental 2-forms are SD. When $M$ is hyper-Kähler it is necessarily ASD and Ricci flat. With the help of Hitchin’s theorem [27], it is straightforward to prove the next basic for our result.

**Proposition 2.1.** The almost hyper-Hermitian structure $(F_1, F_2, F_3)$ is hyper-Kähler if and only if

$$d\epsilon^{12}(t_0) = d\epsilon^{13}(t_0) = d\epsilon^{23}(t_0) = 0,$$ \hspace{1cm} (2.3)

for some $t_0 \in I$, and the following evolution equations hold:

$$\frac{d}{dt} \epsilon^{ij}(t) = -f(t) \, d\epsilon^i(t).$$ \hspace{1cm} (2.4)

Here, $(i, j, k)$ denotes an even permutation of $(1, 2, 3)$ and $\epsilon^j(t) = e^j(t) \wedge e^i(t)$.

The hyper-Kähler metric is given by

$$g = (e^1(t))^2 + (e^2(t))^2 + (e^3(t))^2 + f^2(t) \, dt^2.$$ \hspace{1cm} (2.5)

**Proof.** Taking the exterior derivatives in (2.2) and separating the variables, we obtain

$$dF_1 = d\epsilon^{12}(t) + \left[ \frac{d}{dt} \epsilon^{12}(t) + f(t) \, d\epsilon^1(t) \right] \wedge dt,$$

$$dF_2 = d\epsilon^{13}(t) + \left[ \frac{d}{dt} \epsilon^{13}(t) - f(t) \, d\epsilon^2(t) \right] \wedge dt,$$

$$dF_3 = d\epsilon^{23}(t) + \left[ \frac{d}{dt} \epsilon^{23}(t) + f(t) \, d\epsilon^1(t) \right] \wedge dt.$$ \hspace{1cm} (2.6)
Equations (2.6) imply that all the three 2-forms $F_i$ are closed precisely when (2.4) holds and $d\omega^{12}(t) = d\omega^{13}(t) = d\omega^{23}(t) = 0$ for all $t \in I$. The latter condition is equivalent to (2.3) because by (2.4) we have that \( \frac{d}{dt}(d\omega^{ij}(t)) = d(f(t)\omega^{ik}(t)) = f(t)d^2\omega^{kj}(t) = 0 \) for all $t$, that is, $d\omega^{ij}(t)$ is constant on the connected interval $I$. Finally, Hitchin theorem [27] completes the proof. □

In Table 1, we recall the Bianchi classification [36] (up to isomorphism) of the three-dimensional Lie algebras using $d\mathfrak{e}^1 = -b_1\mathfrak{e}^{23}, d\mathfrak{e}^2 = -a_1\mathfrak{e}^{12} - b_2\mathfrak{e}^{31}$ and $d\mathfrak{e}^3 = -b_3\mathfrak{e}^{12} + a_e\mathfrak{e}^{31}$.

Our goal is to seek the explicit solution of the system given in the previous proposition for each of the three-dimensional Bianchi-type groups. We will consider the class of left-invariant evolutions, that is to say, \( \{e^1(t), e^2(t), e^3(t)\} \) is a basis of $\mathfrak{g}^*$ for all $t \in I$, $\mathfrak{g}$ being the Lie algebra of $G$, i.e. for some function $c^i_j(t)$ we have

\[
e^i(t) = c^i_1(t) e^1 + c^i_2(t) e^2 + c^i_3(t) e^3, \quad i = 1, 2, 3,
\]

(2.7)\]  

with four-dimensional metric (2.5) taking the form $g = f^2(t) dr^2 + c^i_j(t) c^j_k(t) e^i \otimes e^j$. This special class of evolutions restricts the applicability of our method to the groups of type A.

**Lemma 2.2.** Let \( \{e^1(t), e^2(t), e^3(t)\} \) be a basis of left-invariant 1-forms on $G$ for each $t \in I$. Then, (2.3) is satisfied if and only if the Lie group $G$ is of Bianchi type A.

**Proof.** Let us fix the basis \( \{e^1(t_0), e^2(t_0), e^3(t_0)\} \) of $\mathfrak{g}^*$. Then, there are constants $c^i_j \in \mathbb{R}$ such that

\[
e^i(t_0) = c^i_1 e^1 + c^i_2 e^2 + c^i_3 e^3, \quad i = 1, 2, 3,
\]

where \( \{e^1, e^2, e^3\} \) denotes the basis of $\mathfrak{g}^*$ given in Table 1, i.e. satisfying $d\mathfrak{e}^1 = -b_1\mathfrak{e}^{23}, d\mathfrak{e}^2 = -a_1\mathfrak{e}^{12} - b_2\mathfrak{e}^{31}$ and $d\mathfrak{e}^3 = -b_3\mathfrak{e}^{12} + a_e\mathfrak{e}^{31}$. Thus $e^{ij}(t_0) = c^{ij}_1 e^{12} + c^{ij}_2 e^{13} + c^{ij}_3 e^{23}$, where $c^{ij}_i = c^i_j - c^j_i$.

Since $d\mathfrak{e}^{12} = d\mathfrak{e}^{13} = 0$ and $d\mathfrak{e}^{23} = -2ae e^{31}$, we have that condition (2.3) is equivalent to

\[
0 = d\omega^{ij}(t_0) = c^{ij}_1 d\mathfrak{e}^{12} + c^{ij}_2 d\mathfrak{e}^{13} + c^{ij}_3 d\mathfrak{e}^{23}
\]

for $(i, j) = (1, 2), (1, 3)$ and $(2, 3)$. Now, $G$ is of Bianchi type B if and only if $a \neq 0$, and therefore (2.3) is satisfied if and only if $c^{12}_1 = c^{13}_1 = c^{23}_1 = 0$. But the latter condition implies $\det(c^i_j) = 0$, which contradicts the fact that \( \{e^1(t_0), e^2(t_0), e^3(t_0)\} \) is a basis. □

In the following subsections for each of the Bianchi type A groups, we explicitly solve the system of proposition 2.1 under the restrictive assumption that the evolution of the invariant 1-forms is diagonal. Specifically, given a basis \( \{e^1, e^2, e^3\} \) of $\mathfrak{g}^*$, we will consider the ‘diagonal’ evolution

\[
e^1(t) = f_1(t) e^1, \quad e^2(t) = f_2(t) e^2, \quad e^3(t) = f_3(t) e^3,
\]

(2.8)\]  

where $f_1, f_2$ and $f_3$ are the non-vanishing functions of $t \in I$. The corresponding ‘diagonal’ metric is given by

\[
g = f_1^2(e^1)^2 + f_2^2(e^2)^2 + f_3^2(e^3)^2 + f^2 dt^2.
\]

(2.9)\]  

The function $f$ is introduced for convenience in order to identify the metrics obtained by our method with the known explicit examples of four-dimensional hyper-Kähler metrics. We note explicitly that according to [43] a cohomogeneity-one Einstein metric, whose general form is

\[
g = dT^2 + h_{ij}(T) e^i \otimes e^j,
\]

can be assumed to be diagonal, $h_{ij} = 0$ for $i \neq j$, when \( \{e^i\} \) are the left-invariant forms of a Bianchi type VIII or IX group—first one diagonalizes $(h_{ij})$ at a time $T_0$ and then shows
Table 1. Bianchi classification.

| Type  | I   | II  | VI₀ | VII₀ | VIII | IX | V | IV | VII₀, α > 0 | III | VII₀, 0 < α ≠ 1 |
|-------|-----|-----|-----|------|------|----|---|----|-------------|-----|-----------------|
| a     | 0   | 0   | 0   | 0    | 0    | 0  | 1 | 1  | a           | 1   | a               |
| b₁    | 0   | 0   | 0   | 0    | 1    | 1  | 0 | 0  | 0           | 0   | 0               |
| b₂    | 0   | 0   | 1   | 1    | 1    | 1  | 0 | 0  | 1           | 1   | 1               |
| b₃    | 0   | 1   | -1  | 1    | -1   | 1  | 0 | 1  | -1          | -1  | -1              |
| G     | Abelian | Heisenberg | Poincare | Euclidean | Lorentz | Rotations |
| a.k.a. | Lorentzian motions | SU(1, 1) | SU(2) |
| Nil   | (unimodular) | Type A | Type B |
|       | (non-unimodular) |         |        |
that the Ricci flatness implies the vanishing of all off-diagonal terms. On the other hand, a diagonalization of \((h_{ij})\) corresponds to a rotation of the matrix \((c^j_i)\) which in turn becomes a rotation of the fundamental 2-forms (2.1). Such a rotation might lead to non-closed 2-forms. Thus, our assumption of a diagonal evolution is restrictive in all cases. Our next task is to consider case by case the Bianchi type A groups.

2.1. The group SU(2), Bianchi type IX

Let \(G = SU(2) = S^3\) be described by the structure equations
\[
de^\prime = -e^i d^i.
\]
(2.10)

In terms of Euler angles, the left-invariant 1-forms \(e^i\) are given by
\[
e^1 = \sin \psi \, d\theta - \cos \psi \sin \theta \, d\phi, \quad e^2 = \cos \psi \, d\theta + \sin \psi \sin \theta \, d\phi, \quad e^3 = d\psi + \cos \theta \, d\phi.
\]
(2.11)

We evolve the \(SU(2)\) structure as in (2.8). Using (2.10), we reduce the evolution equations (2.4) to the following system of ODEs (ordinary differential equations):
\[
\frac{d}{dt}(f_1 f_2) = f_1 f_3, \quad \frac{d}{dt}(f_1 f_3) = f_2 f_3, \quad \frac{d}{dt}(f_2 f_3) = f_1 f_2.
\]
(2.12)

The system (2.12) is equivalent to the following ‘BGPP’ system (see [5]):
\[
\frac{d}{dt} f_1 = f_2 f_3 - f_2^2, \quad \frac{d}{dt} f_2 = f_1 f_3 - f_2 f_3, \quad \frac{d}{dt} f_3 = f_1 f_2 - f_2 f_3.
\]
(2.13)

The system (2.13) admits the triaxial Bianchi IX BGPP [5] hyper-Kähler metrics by taking \(f = f_1 f_2 f_3\) and all \(f_i\) different (see also [24]), and the Eguchi–Hanson [18] hyper-Kähler metric by letting two of the functions \(f_1, f_2, f_3\) equal to each other.

2.1.1. The general solution. With the substitution \(x_i = (f_j f_k)^2\), the system (2.12) becomes
\[
\frac{dx_i}{dr} = 2(x_1 x_2 x_3)^{1/4},
\]
in terms of the parameter \(dr = f \, dt\). Hence the functions \(x_i\) differ by a constant, i.e. there is a function \(x(r)\) such that \(x(r) = x_1 + a_1 = x_2 + a_2 = x_3 + a_3\). The equation for \(x(r)\) is
\[
\frac{dx}{dr} = 2 \frac{(x - a_1)(x - a_2)(x - a_3)^{1/4}}{x}, \quad \text{i.e.} \quad dr = \frac{1}{2} \frac{1}{((x - a_1)(x - a_2)(x - a_3)^{1/4})} \, dx.
\]
(2.14)

If we let \(h(x) = \frac{1}{2} \frac{(x - a_1)(x - a_2)(x - a_3)^{1/4}}{x}\) and take into account \(x_i = (f_j f_k)^2\), we see from (2.12) that the functions \(f_j(x)\) satisfy
\[
\frac{df_j}{dx} ((x - a_i)^{1/2}) = h(x) f_j.
\]

Solving for \(f_j\) we showed that the general solution of (2.12) is
\[
f_j(x) = \frac{(x - a_j)^{1/4}(x - a_k)^{1/4}}{(x - a_i)^{1/4}}, \quad f(t) = h(x(t)) \, x'(t),
\]
\[
h(x) = \frac{1}{2} \frac{1}{((x - a_1)(x - a_2)(x - a_3)^{1/4})},
\]
(2.15)

where \(a_1, a_2, a_3\) are constants, and \(x\) is an auxiliary independent variable (substituting any function \(x = x(t)\) gives a solution of (2.12) in terms of \(t\) in an interval where \(f\) and \(f_i\), with \(i = 1, 2, 3\), do not vanish).

The resulting hyper-Kähler metric is given by (2.9) where the forms \(e^1, e^2\) and \(e^3\) and the functions \(f_1, f_2, f_3\) and \(f\) are given by (2.11) and (2.15), respectively.
2.1.2. Eguchi–Hanson instantons. A particular solution to (2.12) is obtained by taking $x = (t/2)^4$ and $a_1 = a_2 = \frac{1}{16}a$, $a_3 = 0$, which gives

\begin{align}
  f_1 &= f_2 = \frac{t}{2}, \\
  f_3 &= \frac{1}{2t}(t^4 - a)^{\frac{1}{2}}, \\
  f &= \sqrt{\frac{t^4}{t^4 - a}},
\end{align}

(2.16)

where $t \in (0, \infty)$ if $a \leq 0$ and $t \in (a^{\frac{1}{4}}, \infty)$ if $a > 0$. This is the Eguchi–Hanson instanton [18] with the metric given by

\begin{equation}
  g = \frac{t^2}{4}((e^1)^2 + (e^2)^2) + \frac{t^4 - a}{4t^2} (e^3)^2 + \frac{t^4}{t^4 - a} (dt)^2,
\end{equation}

where the 1-forms $e^1$, $e^2$ and $e^3$ can be found in (2.11).

2.1.3. Triaxial Bianchi type IX BGPP metrics [5]. If we perform the substitution $x = t^4$, $a_1 = a^4$, $a_2 = b^4$ and $a_3 = c^4$ the metric of (2.15) turns into the triaxial Bianchi IX metrics discovered in [5] (see also [24, 20, 21]):

\begin{align}
  f_1(t) &= \frac{(t^4 - b^4)^{\frac{1}{2}}(t^4 - c^4)^{\frac{1}{2}}}{(t^4 - a^4)^{\frac{1}{2}}}, \\
  f_2(t) &= \frac{(t^4 - a^4)^{\frac{1}{2}}(t^4 - c^4)^{\frac{1}{2}}}{(t^4 - b^4)^{\frac{1}{2}}}, \\
  f_3(t) &= \frac{(t^4 - b^4)^{\frac{1}{2}}(t^4 - c^4)^{\frac{1}{2}}}{(t^4 - a^4)^{\frac{1}{2}}}, \\
  f &= \frac{2t^4}{(t^4 - b^4)^{\frac{1}{2}}(t^4 - c^4)^{\frac{1}{2}}(t^4 - a^4)^{\frac{1}{2}}}.
\end{align}

(2.17)

By [5] the above metrics are all singular (cannot be completed) with the only exception being the Euclidean flat space (when $a_1 = a_2 = a_3$) and the Eguchi–Hanson instanton, whose completion is the cotangent bundle of the complex projective line $\mathbb{C}P^1$. The latter example was extended to higher dimensions by Calabi [9]. In the derivation above we avoided the use of elliptic functions.

We note that the Atiyah–Hitchin class of complete hyper-Kähler metrics is not included in our derivation. In fact, by construction, the natural action of $SU(2)$ extends to a trivial action on the fundamental 2-forms, while it is known that in the Atiyah–Hitchin class, the group $SU(2)$ rotates the SD forms [2].

2.2. The group $SU(1, 1)$. Bianchi type VIII

Bianchi type VIII were investigated in [38, 39, 37]. Let $G = SU(1, 1)$ be described by the structure equations

\begin{equation}
  de^1 = -e^{23}, \quad de^2 = -e^{31}, \quad de^3 = e^{12}.
\end{equation}

(2.18)

In terms of local coordinates, the left-invariant forms $e^i$ are given by

\begin{equation}
  e^1 = d\psi - \cos \theta \, d\phi, \quad e^2 = \sinh \psi \, d\theta + \cosh \psi \, \sin \theta \, d\phi, \quad e^3 = \cosh \psi \, d\theta + \sinh \psi \, \sin \theta \, d\phi.
\end{equation}

(2.19)

We evolve the $SU(1, 1)$ structure as in (2.8). Using the structure equations (2.19), we reduce the evolution equations (2.4) to the following system of ODEs:

\begin{align}
  \frac{d}{dt}(f_1f_2) &= -ff_3, \\
  \frac{d}{dt}(f_1f_3) &= fff_2, \\
  \frac{d}{dt}(f_2f_3) &= fff_1.
\end{align}

(2.20)

Solutions to the above system yield the hyper-Kähler metrics (2.5) found in [5].
2.2.1. Triaxial Bianchi type VIII metrics. Working as in subsection 2.1.1, we obtain the next system for the functions $x_i$:  
\[ \frac{dx_i}{dr} = \frac{dx_1}{dr} = 2(x_1x_2x_3)^{1/4}, \quad \frac{dx_2}{dr} = -2(x_1x_2x_3)^{1/4}. \]
Solving for $f_i$, as in the derivation (2.15), we find that the general solution of (2.20) is  
\[ f_1(x) = \frac{(x - a_2)^{1/4}(a_3 - x)^{1/4}}{(x - a_1)^{1/4}}, \quad f_2(x) = \frac{(x - a_1)^{1/4}(a_3 - x)^{1/4}}{(x - a_2)^{1/4}}, \]
\[ f_3(x) = \frac{(x - a_1)^{1/4}(x - a_2)^{1/4}}{(a_3 - x)^{1/4}}, \quad f(t) = h(x(t)) x'(t), \]
\[ h(x) = \frac{1}{2} ((x - a_1)(x - a_2)(a_3 - x))^{-1/4}, \]
where $a_1, a_2$ and $a_3$ are constants, and $x$ is an auxiliary independent variable (substituting any function $x = x(t)$ gives a solution of (2.12) in terms of $t$ in an interval where $f$ and $f_i$, $i = 1, 2, 3$, do not vanish).

The resulting hyper-Kähler metric is given by (2.9) where the forms $e^1, e^2$ and $e^3$ and the functions $f_1, f_2, f_3$ and $f$ are given by (2.19) and (2.21), respectively.

Taking $f = f_1f_2f_3$ and all $f_i$ different into (2.9), we obtain an explicit expression of the triaxial Bianchi VIII solutions indicated in [5].

A particular solution is obtained by letting $a_1 = a_2 = 0, a_3 = \frac{a}{16}, x = (t/2)^4$ which gives  
\[ f_1 = f_2 = \frac{1}{2}(a - t^4)^{1/2}, \quad f_3 = \frac{t^2}{2}(a - t^4)^{-1/2}, \quad f = t(a - t^4)^{-1/2}, \quad 0 < t^4 < a. \]
The resulting hyper-Kähler metric is  
\[ g = \frac{\sqrt{a - t^2}}{4} (e^1)^2 + \frac{t^4}{4\sqrt{a - t^2}} (e^3)^2 + \frac{t^2}{\sqrt{a - t^2}} dr^2, \]
where the forms $e^i$ are given by (2.19).

2.3. The Heisenberg group $H^3$, Bianchi type II, Gibbons–Hawking class

Consider the two-step nilpotent Heisenberg group $H^3$ defined by the structure equations  
\[ de^1 = de^2 = 0, \quad de^3 = -e^1, \]
where we can consider  
\[ e^1 = dx, \quad e^2 = dy, \quad e^3 = dz - \frac{1}{2} x dy + \frac{1}{2} y dx, \]
with $x, y$ and $z$ being the global coordinates functions of $H^3$. Now, we evolve the structure of $H^3$ according to (2.8). The structure equations (2.22) reduce the evolution equations (2.4) to the following system of ODEs:
\[ \frac{d}{dt}(f_1f_2) = f_3f, \quad \frac{d}{dt}(f_1f_3) = 0, \quad \frac{d}{dt}(f_2f_3) = 0. \]
Working as in the previous example, i.e. using the same substitutions, we see that the function $x_i$ satisfies  
\[ \frac{dx_1}{dr} = 2(x_1x_2x_3)^{1/4}, \quad \frac{dx_2}{dr} = 0. \]
The general solution of this system is  
\[ x_1 = a, \quad x_2 = b, \quad x_3 = \left(\frac{a}{2}\right)^{1/4} r + c, \]
where $a, b, c$ are constants.
where \( a, b \) and \( c \) are constants. Therefore, using again \( f_i = \left( \frac{a_i}{x_i} \right)^{1/4} \), the general solution of (2.24) is

\[
\begin{align*}
    f_1 &= \left( \frac{b}{a} \right)^{1/4} \left( \frac{3}{2} (ab)^{1/4} r + c \right)^{1/3}, \\
    f_2 &= \left( \frac{a}{b} \right)^{1/4} \left( \frac{3}{2} (ab)^{1/4} r + c \right)^{1/3}, \\
    f_3 &= \frac{(ab)^{1/4}}{\left( \frac{3}{2} (ab)^{1/4} r + c \right)^{1/3}}, \\
    f &= r'(t),
\end{align*}
\]

(2.26)

where \( r = r(t) \) is an arbitrary function for \( t \) in an interval where \( f \) and \( f_i, i = 1, 2, 3 \) do not vanish.

The resulting hyper-Kähler metric is given by (2.9) where the forms \( e^1, e^2 \) and \( e^3 \) and the functions \( f_1, f_2, f_3 \) are given by (2.23) and (2.26), respectively.

A particular solution is obtained by taking \( c = 0 \) and \( a = b = 1 \) into (2.26), which gives

\[
    f_1 = f_2 = \lambda r^{1/3}, \quad f_3 = f_1^{-1},
\]

with \( \lambda = \left( \frac{3}{2} \right)^{1/3} \). The substitution \( t = \lambda^2 r^{2/3} \) gives \( f_1 = f_2 = f = r^2, \quad f_3 = r^{-2} \), with \( t > 0 \). This is the hyper-Kähler metric, first written in [37, 38],

\[
g = t (dr^2 + dx^2 + dy^2) + \frac{1}{r} \left( dz - \frac{1}{2} x dy + \frac{1}{2} y dx \right)^2,
\]

belonging to the Gibbons–Hawking class [22] with an \( S^1 \)-action and also known as the Heisenberg metric [25] (see also [3, 40, 15, 12, 44]).

### 2.4. Rigid motions of Euclidean 2-plane-Bianchi VII\(_0\)

We consider the group \( E_2 \) of rigid motions of Euclidean 2-plane defined by the structure equations

\[
de^1 = 0, \quad de^2 = e^3, \quad de^3 = -e^2, \quad \text{where we can consider}
\]

\[
e^1 = d\phi, \quad e^2 = \sin \phi \ dx - \cos \phi \ dy, \quad e^3 = \cos \phi \ dx + \sin \phi \ dy.
\]

(2.27)

We evolve the structure as in (2.8). Using the structure equations (2.27), we reduce the evolution equations (2.4) to the following system of ODEs:

\[
\frac{d}{dr}(f_1 f_2) = ff_3, \quad \frac{d}{dr}(f_1 f_3) = ff_2, \quad \frac{d}{dr}(f_2 f_3) = 0.
\]

(2.28)

With the substitution \( x_i = (f_i f_i)^2 \), the above system becomes

\[
\frac{dx_1}{dr} = 0, \quad \frac{dx_2}{dr} = \frac{dx_3}{dr} = 2(x_1 x_2 x_3)^{1/4},
\]

in terms of the parameter \( dr = f dr \). Hence, there is a function \( x(r) \) and three constants \( a_1, a_2 \) and \( a_3 \), such that, \( x(r) = x_2 + a_2 = x_3 + a_3, x_1 = a_1 \). The equation for \( x(r) \) is

\[
\frac{dx}{dr} = 2 \left( a_1 (x - a_2) (x - a_3) \right)^{1/4}, \quad \text{i.e.} \quad dr = \frac{1}{2} \left( a_1 (x - a_2) (x - a_3) \right)^{-1/4} \ dx.
\]

(2.29)

If we let \( h(x) = \frac{1}{2} (a_1 (x - a_2) (x - a_3))^{-1/4} \) and take into account \( x_i = (f_i f_i)^2 \), we see from (2.28) that the functions \( f_i(x) \) satisfy

\[
\frac{d}{dx} \left( (x - a_i)^{1/2} \right) = h(x) f_i, \quad i = 2, 3.
\]

Solving for \( f_i \), we show that the general solution of (2.12) is

\[
\begin{align*}
    f_1(x) &= \left( \frac{x - a_2}{a_1} \right)^{1/4} \left( x - a_3 \right)^{1/4}, \\
    f_2(x) &= \frac{a_1^{1/4} (x - a_2)^{1/4}}{\left( x - a_3 \right)^{1/4}}, \\
    f_3(x) &= \frac{a_1^{1/4} (x - a_2)^{1/4}}{(x - a_3)^{1/4}}, \\
    f(t) &= h(x(t)) x'(t), \quad h(x) = \frac{1}{2} \left( (a_1 (x - a_2) (x - a_3))^{-1/4} \right),
\end{align*}
\]

(2.30)
any function $x$ gives a solution of (2.28) in terms of $t$ in an interval where $f$ and $f_i$, $i = 1, 2, 3$, do not vanish.

The resulting hyper-Kähler metric is given by (2.9) where the forms $e^1, e^2$ and $e^3$ and the functions $f_1, f_2, f_3$ and $f$ are given by (2.27) and (2.30), respectively.

A particular vacuum solutions of Bianchi type VII$_0$ is obtained by letting $f_2 = f_3^{-1}$ and $f_1 = f$, which gives

$$\frac{d}{dt}(ff_3^{-1}) = ff_3, \quad \frac{d}{dt}(ff_3) = ff_3^{-1},$$

with a general solution of the form $ff_3 + ff_3^{-1} = Ae^t, ff_3^{-1} - ff_3 = Be^{-t}$. Hence,

$$f = f_1 = \frac{1}{2}(Ae^t + Be^{-t})^{-\frac{1}{2}}(Ae^t - Be^{-t})^{\frac{1}{2}}, \quad f_2 = f_3^{-1} = (Ae^t + Be^{-t})^{-\frac{1}{2}}(Ae^t - Be^{-t})^{\frac{1}{2}},$$

where $t > \frac{1}{2} \log \left| \frac{B}{A} \right|$ since $A^2e^{2t} - B^2e^{-2t} > 0$. The resulting hyper-Kähler metric is

$$g = \frac{1}{4}(A^2e^{-2t} - B^2e^{2t})(d^2x + d\phi^2 + \frac{4}{(Ae^t - Be^{-t})^2}(e^2)^2 + \frac{4}{(Ae^t + Be^{-t})^2}(e^3)^2),$$

(2.31)

where $e^2$ and $e^3$ are given by (2.27). In particular, setting $A = B$ in (2.31) we obtain

$$g = \frac{A^2}{2}\sinh 2t(dx^2 + d\phi^2) + \coth t(e^2)^2 + \tanh t(e^3)^2,$$

which is the vacuum solutions of Bianchi type VII$_0$ [37, 38] with a group of isometries $E_4$ [25] (see also [44]).

2.5. Rigid motions of Lorentzian 2-plane-Bianchi type V$_0$

Now we consider the group of rigid motions $E(1, 1)$ of Lorentzian 2-plane defined by the structure equations and coordinates as follows:

$$de^1 = 0, \quad de^2 = e^3^1, \quad de^3 = e^3^2,$$

$$e^1 = d\phi, \quad e^2 = \sinh \phi dx + \cosh \phi dy, \quad e^3 = \cosh \phi dx + \sinh \phi dy.$$  (2.32)

We evolve the structure as in (2.8). Using the structure equations (2.32), the evolution equations (2.4) give the following system of ODEs:

$$\frac{d}{dt}(f_1f_2) = -ff_3, \quad \frac{d}{dt}(f_1f_3) = ff_2, \quad \frac{d}{dt}(f_2f_3) = 0.$$  (2.33)

The general solution of (2.33) is

$$f_1(x) = \frac{x - a_2^{1/4}(a_3 - x)^{1/4}}{a_1^{1/4}}, \quad f_2(x) = a_1^{1/4}(a_3 - x)^{1/4}, \quad f_3(x) = a_1^{1/4}(x - a_2)^{1/4},$$

$$f(t) = h(x(t))x'(t), \quad h(x) = \frac{1}{2}((a_1(x - a_2)(a_3 - x))^{-1/4},$$  (2.34)

where $a_1, a_2$ and $a_3$ are constants, and $x$ is an auxiliary independent variable (substituting any function $x = x(t)$ gives a solution of (2.28) in terms of $t$ in an interval where $f$ and $f_i$, $i = 1, 2, 3$, do not vanish).

The resulting hyper-Kähler metric is given by (2.9) where the forms $e^1, e^2$ and $e^3$ and the functions $f_1, f_2, f_3$ and $f$ are given by (2.32) and (2.34), respectively.

A particular case is obtained by letting $f_2 = f_3^{-1}$ and $f_1 = f$, which turns the system (2.34) in the form $\frac{df_1}{df_3} = -ff_3, \frac{df_2}{df_3} = ff_3^{-1}$. This system is integrated trivially,

$$ff_3^{-1} = a\cos t + b\sin t \quad \text{and} \quad ff_3 = a\sin t - b\cos t;$$
hence
\[ f^2 = (a \cos t + b \sin t)(a \sin t - b \cos t), \quad f_3 = (a \sin t - b \cos t)f^{-1}. \]

Therefore,
\[
\begin{align*}
    f &= f_1 = (a \cos t + b \sin t)^{1/2}(a \sin t - b \cos t)^{1/2}, \\
    f^{-1} &= f_3 = (a \cos t + b \sin t)^{-1/2}(a \sin t - b \cos t)^{-1/2},
\end{align*}
\]

and the hyper-Kähler metric is given by
\[
g = (a \sin t - b \cos t)(a \cos t + b \sin t)(dr^2 + d\phi^2) + a\cos t + b\sin t(e^2)^2 + a\sin t - b\cos t(e^3)^2,
\]

(2.35)

where \(e^2\) and \(e^3\) are defined in (2.32). Introducing \(t_0\) and \(r_0\) by letting \(r_0 = \sqrt{a^2 + b^2}\),
\[ \cos t_0 = a/\sqrt{a^2 + b^2} \text{ and } \sin t_0 = b/\sqrt{a^2 + b^2}, \]
we have that \(t \in (t_0, t_0 + \pi/2)\), and the above metric can be put in the form
\[
g = \frac{1}{r_0^2} \sin 2(t - t_0)(dr^2 + d\phi^2) + \cot(t - t_0)(e^2)^2 + \tan(t - t_0)(e^3)^2.
\]

(2.36)

After an obvious re-parametrization, the metric (2.36) takes a familiar form
\[
g = a^2 \sin 2r (dr^2 + d\phi^2) + \cot t (e^2)^2 + \tan t (e^3)^2,
\]

which is the vacuum solutions of Bianchi type VI0 [37, 38] with a group of isometries \(E_{6(1)}\) [25] (see also [44]).

As a consequence of the previous subsections we have the following simple fact.

**Proposition 2.3.** Let \(G\) be a three-dimensional Lie group of Bianchi type A. Then, there exists a complete metric on \(G \times \mathbb{R}\) that is globally conformal to a hyper-Kähler metric on \(G \times \mathbb{R}\).

**Proof.** In the previous subsections, for each three-dimensional Lie group \(G\) of Bianchi type A, we have constructed a hyper-Kähler metric of the form \(g = g_r + (f(t)dt)^2\) on \(G \times (a_0, b_0)\), for some open interval \((a_0, b_0) \subset \mathbb{R}\), such that the metric \(g_r = \sum_{j=1}^{3} f_j(t)(e^j)^2\) is a left-invariant metric on \(G\) for each \(t \in (a_0, b_0)\). By a suitable change of variables \(t = \tau(r)\) we can assume that \(r\) changes from \(-\infty\) to \(+\infty\) as \(t\) changes from \(a_0\) to \(b_0\). Thus, the considered metrics take the form
\[
g = \sum_{j=1}^{3} (f_j(r))^2 (e^j)^2 + (\varphi(r))^2 dr^2,
\]

where \(\varphi(r)dr = f(t)dr\), \(\varphi > 0\), for the fixed \(t = \tau(r)\). This allows us to put \(g\) in the form \(g = \varphi(r)^2 \hat{g}\), where
\[
\hat{g} = dr^2 + \sum_{j=1}^{3} (f_j/\varphi(r))^2 (e^j)^2 = dr^2 + g_r.
\]

An adaptation of the proof of completeness of a doubly warped product of complete Riemannian manifolds [41] shows that \(\hat{g}\) is complete. In fact, following [41] consider a Cauchy sequence \(\{(p_i, r_i)\}_{i=1}^\infty\) in \(G \times \mathbb{R}\). From the form of the metric it follows for any curve \(\gamma\) in \(G \times \mathbb{R}\) we have \(L(\gamma) \geq L(\pi_2 \circ \gamma)\) for the corresponding lengths of the curve and its projection, where \(\pi_2\) is the projection from \(G \times \mathbb{R}\) to \(\mathbb{R}\). This implies
\[
d_{\hat{g}} ((p_i, r_i), (p_k, r_k)) \geq |r_i - r_k|;
\]

hence \(\{r_i\}\) is a Cauchy sequence in \(\mathbb{R}\). Therefore, the numbers \(r_i\) belong to a fixed compact interval, \(|r_i| \leq R\). Thus, \(\inf_{|r| \leq R} |f_j/\varphi(r)| = \sigma > 0\) for \(j = 1, 2, 3\) and for any curve \(\gamma\) with
\[|\pi_2 \circ \gamma| \leq R, \text{ we have } L(\gamma) \geq \sigma L(\pi_1 \circ \gamma), \text{ where } \pi_1 \text{ is the projection from } G \times \mathbb{R} \text{ to } G. \text{ Since for any curve } \alpha(s), s \in [0,1] \text{ in } G \text{ we can consider its lift to } G \times \mathbb{R} \text{ defined by } \gamma(s) = (\alpha(s), sr' + (1-s)r), \]

for which we have $\alpha = \pi_1 \circ \gamma$ and $\pi_2 \circ \gamma$ has an arbitrarily fixed beginning $r$ and end $r'$ with $|r - r'| \leq R$, it follows

\[d_g((p_i, r_i), (p_k, r_k)) \geq \sigma d_g(p_i, p_k).\]

where $g_0 = \sum_{j=1}^{3}(e^j)^2$; hence $\{p_i\}_{i=1}^{\infty}$ is a Cauchy sequence in $(G, g_0)$ (use $r = r_i$ and $r' = r_k$ in the above constriction). Noting that the metric $g_0$ is a left-invariant metric on the group $G$ it follows that $\{p_i\}_{i=1}^{\infty}$ is a convergent sequence in $G$. Thus, $(\{p_i, r_i\}_{i=1}^{\infty})$ is a convergent sequence in $(G \times \mathbb{R}, g)$. By the Hopf–Rinow theorem, the latter is a complete Riemannian manifold. \hfill \Box

2.6. Contractions

It is worth observing that the hyper-Kähler metrics constructed from the Bianchi groups of type II, VI₀ and VII₀ (and the trivial Abelian case) can also be obtained using the well-known contractions of the Lie algebras $su(2)$ (i.e. type IX) and $su(1, 1)$ (i.e. type VIII) to any of the former four. In [11] and [23], this idea of exploiting Lie algebra contractions was used to construct explicit metrics of special holonomy. For our purposes, consider the contraction corresponding to the following scaling of $su(2)$:

\[e^1 = \hat{e}^3, \quad e^2 = \hat{e}^3, \quad e^3 = \lambda \hat{e}^3,\]

where $e^1$, $e^2$ and $e^3$ are the generators of $su(2)$ as in (2.10). Clearly, we have

\[\text{de}^1 = -\lambda^2 \hat{e}^2 \wedge \hat{e}^3, \quad \text{de}^2 = -\hat{e}^3 \wedge \hat{e}^1, \quad \text{de}^3 = -\hat{e}^1 \wedge \hat{e}^2,\]

which as $\lambda \to 0^+$ corresponds to a contraction to the Lie algebra VI₀ given in (2.32). For each $\lambda > 0$, we have that the metric $\hat{g} = \hat{f}_1^2 (\hat{e}^1)^2 + \hat{f}_2^2 (\hat{e}^2)^2 + \hat{f}_3^2 (\hat{e}^3)^2 + \hat{h}(x)^2 \text{d}x^2, \hat{f}_i = \hat{f}_i(x)$ for $i = 1, 2, 3$ is a hyper-Kähler metric provided the following system of ODEs holds true:

\[
\begin{align*}
\frac{d}{dx}(\hat{f}_1 \hat{f}_2) &= \hat{f}_3, & \frac{d}{dx}(\hat{f}_1 \hat{f}_3) &= \hat{f}_2, & \frac{d}{dx}(\hat{f}_2 \hat{f}_3) &= \lambda^2 \hat{f}_1.
\end{align*}
\]

Letting $\lambda \to 0^+$ we obtain the system (2.33). In this sense, the metric given by (2.35) is obtained from the metric defined by (2.9) and (2.15) using the contraction between the corresponding Lie algebras. The other possible contractions can be treated analogously.

3. Hyper-symplectic metrics of dimension 4

In this section, following the method of the preceding section, we present explicit hyper-symplectic (also called hyper-para-Kähler) metrics of dimension 4 of signature (2, 2). For this, we lift the special structure on the non-Euclidean Bianchi type groups of class A, discovered in the preceding section (proposition 2.1), to a hyper-symplectic metric on its product with the real line. The construction extends the correspondence between Bianchi type IX hyper-Kähler metrics and Bianchi type VIII hyper-para-Kähler structures discovered in [35].

First, we recall that an almost hyper-paracomplex structure on the 4n-dimensional manifold $M$ is a triple $(J, P_1, P_2)$ of endomorphisms of the tangent bundle of $M$ satisfying the paraquaternionic identities, namely

\[J^2 = -P_1^2 = -P_2^2 = -1, \quad JP_1 = -P_1J = P_2.\]
If in addition, \( J, P_1, \) and \( P_2 \) are integrable (that is, its corresponding Nijenhuis tensor vanishes), the almost hyper-paracomplex structure \((J, P_1, P_2)\) on \( M \) is called hyper-paracomplex structure. (The Nijenhuis tensor of an endomorphism \( P \) of the tangent bundle of \( M \) is given by
\[
N_P(X, Y) = [PX, PY] - P[PX, Y] - P[X, PY] + P^2[X, Y],
\]
for all vector fields \( X, Y \) on \( M \).

An almost hyper-paracomplex manifold \((M, J, P_1, P_2)\) is said to be almost hyper-Hermitian if there exists a pseudo-Riemannian metric \( g \) satisfying the compatibility conditions
\[
g(J\cdot, J\cdot) = -g(P_1\cdot, P_1\cdot) = -g(P_2\cdot, P_2\cdot) = g(\cdot, \cdot).
\]
The compatible metric \( g \) is necessarily of neutral signature \((2n, 2n)\) because, at each point of \( M \), there is a local pseudo-orthonormal frame of vector fields given by
\[
\{E_1, \ldots, E_n, J E_1, \ldots, J E_n, P_1 E_1, \ldots, P_1 E_n, P_2 E_1, \ldots, P_2 E_n\}. \tag{3.1}
\]
The fundamental 2-forms are the differential 2-forms on \( M \) defined by
\[
\Omega_1 = g(\cdot, J\cdot), \quad \Omega_2 = g(\cdot, P_1\cdot), \quad \Omega_3 = g(\cdot, P_2\cdot). \tag{3.2}
\]
When these forms are closed the almost hyper-Hermitian structure \((g, J, P_1, P_2)\) is said to be hyper-symplectic \cite{28} or hyper-para-Kähler \cite{32}. This implies (adapting the computations of Atiyah–Hitchin \cite{2} for hyper-Kähler manifolds) that the structures \( J, P_1 \) and \( P_2 \) are integrable and parallel with respect to the Lévi-Civitá connection \cite{28, 13}. In dimension 4, an almost hyper-paracomplex structure is locally equivalent to an oriented neutral conformal structure (or an \( SP(1, \mathbb{R}) \) structure) and the integrability implies the anti-self-duality of the corresponding neutral conformal structure \cite{34}. In particular, a four-dimensional hyper-symplectic structure is equivalent to an ASD and Ricci-flat neutral metric. For this reason, such structures have been used in string theory \cite{42, 30, 33, 3, 31, 10} and integrable systems \cite{16, 4, 17}.

Let \( G \) be a three-dimensional Lie group and \( \{e^1(t), e^2(t), e^3(t)\} \) be a global basis of 1-forms on \( G \) for each \( t \in I \), where \( I \subset \mathbb{R} \) is a connected interval in the real line. We consider the almost hyper-Hermitian structure (or \( SP(1, \mathbb{R}) \)-structure) on \( G \times I \) defined by the following 2-forms:
\[
\begin{align*}
\Omega_1 &= -e^1(t) \wedge e^2(t) + e^3(t) \wedge f(t) \, dt, \\
\Omega_2 &= e^1(t) \wedge e^3(t) - e^2(t) \wedge f(t) \, dt, \\
\Omega_3 &= e^2(t) \wedge e^3(t) + e^1(t) \wedge f(t) \, dt,
\end{align*} \tag{3.3}
\]
where \( f(t) \) is a function of \( t \in I \) which does not vanish.

We use the ordered pseudo-orthonormal basis given by (3.1) to orient negatively the manifold \( M = G \times I \). Then, the fundamental 2-forms (3.3) constitute a basis of the SD 2-forms and a hyper-symplectic structure of the form (3.3) is equivalent to an ASD and Ricci-flat neutral metric.

With the help of Hitchin’s theorem \cite{28}, which states that an almost hyper-para-Hermitian structure is hyper-symplectic exactly when the fundamental 2-forms are closed, \( d\Omega_s = 0, \) \( s = 1, 2, 3 \), it is straightforward to prove similar to proposition 2.1 the following important fact.

**Proposition 3.1.** The almost hyper-para-Hermitian structure \((\Omega_1, \Omega_2, \Omega_3)\) is hyper-symplectic if and only if conditions (2.3) are satisfied and the following evolution equations hold:
\[
\frac{d}{dt} e^{12}(t) = f(t) e^1(t), \quad \frac{d}{dt} e^{13}(t) = f(t) e^2(t), \quad \frac{d}{dt} e^{23}(t) = -f(t) e^3(t). \tag{3.4}
\]
The hyper-symplectic metric is given by
\[
g = (e^1(t))^2 + (e^2(t))^2 - (e^3(t))^2 - f^2(t) \, dt^2. \tag{3.5}
\]
As in the previous section, from lemma 2.2 it follows that the above proposition can be applied to the evolution (2.8) in the case of the Bianchi type A groups only. For each of the Bianchi type A groups, we shall construct explicitly the general triaxial hyper-symplectic metric, which is of the form

\[ g = f_1^2(e_1)^2 + f_2^2(e_2)^2 - f_3^2(e_3)^2 - f^2 dt^2, \]  

(3.6)

by solving the corresponding system for the functions \( f_1, f_2, f_3 \) and \( f \). We shall see that in each case, we obtain a system identical to one of the systems encountered in the hyper-Kähler case.

### 3.1. Bianchi type IX hyper-symplectic metrics and Bianchi type VIII hyper-Kähler metrics

Let \( G = SU(2) = S^3 \) be described by the structure equations (2.10). We evolve the \( SU(2) \) structure according to (2.8).

Using (2.10), we reduce the evolution equations (3.4) to the already considered system (2.20). This establishes a correspondence between triaxial Bianchi type IX hyper-symplectic metrics and triaxial Bianchi type VIII hyper-Kähler metrics.

The general solution is given by (2.21). Taking \( f = f_1f_2f_3 \) in (2.21) and all \( f_i \) different we obtain an explicit expression of a triaxial hyper-symplectic metric (3.6), where the forms \( e^1, e^2 \) and \( e^3 \) and the functions \( f_1, f_2, f_3 \) and \( f \) are given by (2.11) and (2.21), respectively.

A particular solution is obtained by letting \( a_1 = a_2 = 0, a_3 = \frac{a}{2} \) in (2.21) which gives

\[ f_1 = f_2 = \frac{1}{2}(a - t^4)^{1/4}, \quad f_3 = \frac{t^2}{2}(a - t^4)^{-1/4}, \quad f = t(a - t^4)^{-1/4}, \quad 0 < t^4 < a. \]

The resulting hyper-symplectic metric is given by

\[ g = \frac{1}{4}(a - t^4)^{1/4}(d\theta^2 + \sin^2 \theta \, d\phi^2) - \frac{t^4}{4(a - t^4)^{1/4}}(d\psi + \cos \theta \, d\phi)^2 - \frac{t^2}{(a - t^4)^{1/4}} dt^2. \]

### 3.2. Bianchi type VIII hyper-symplectic metrics and Bianchi type IX hyper-Kähler metrics

Let \( G = SU(1, 1) \) be defined by the structure equations (2.18). We evolve the \( SU(1, 1) \) structure as in (2.8). Using the structure equations (2.18), the evolution equations (3.4) reduce to the already solved system (2.12). The general solution is of the form (2.15) which has also expression (2.17). Substitution of (2.17) and (2.19) into (3.6) gives the corresponding triaxial hyper-symplectic metrics.

This establishes a correspondence between triaxial Bianchi type IX hyper-Kähler metrics and triaxial Bianchi type VIII hyper-symplectic metrics discovered in [35].

A particular solution to (2.12) is given by (2.16), which results in a hyper-symplectic metric of the Eguchi–Hanson form [14, 43, 35] given by

\[ g = \frac{t^2}{4}[(d\psi - \cos \theta \, d\phi)^2 + (\sinh \psi \, d\theta + \cosh \psi \sin \theta \, d\phi)^2] - \frac{t^2}{4} \left(1 - \frac{a}{t^4}\right)(\cosh \psi \, d\theta + \sinh \psi \sin \theta \, d\phi)^2 - \left(1 - \frac{a}{t^4}\right)^{-1} (dt)^2. \]

Setting \( f = -\frac{t}{t} \) one obtains another hyper-symplectic metric.
Consider the two-step nilpotent Heisenberg group $H^3$ defined by the structure equations (2.22). We evolve the structure as in (2.8). The structure equations (2.22) reduce the evolution equations (3.4) to the already solved system (2.24) taking $-f_3$ instead of $f_3$. This is equivalent to considering the two-step nilpotent Heisenberg group $H^3$ defined by the structure equations

$$
de^1 = dx^2 = 0, \quad \text{and} \quad \text{evolution equations (3.4) take the form of the already solved system of ODEs (2.24)}.$$

The general solution is of the form (2.26). This establishes the corresponding form of the general triaxial hyper-symplectic metric (3.6) where the functions $f_1, f_2, -f_3$ and $f$ and the 1-forms $e^1, e^2$ and $e^3$ are given by (2.26) and (2.23), respectively.

A particular solution is $f_1 = f_2 = f = t^2$, $f_3 = -t^{-1}$, with $t > 0$. This is the hyper-symplectic metric

$$g = t(-dr^2 + dx^2 + dy^2) - \frac{1}{t}(dz - \frac{1}{2}x dy + \frac{1}{2}y dx)^2.$$

### 3.4. Bianchi type VIL0 hyper-symplectic metrics and hyper-Kähler Bianchi type VIL0 metrics

We consider the group $E_2$ of rigid motions of Euclidean 2-plane defined by the structure equations (2.27). We evolve the structure as in (2.8). Using the structure equations (2.27), the evolution equations (3.4) take the form of the already solved system of ODEs (2.33) with a general solution (2.34) giving a correspondence with Bianchi VIL0 hyper-Kähler metrics.

When $f_2 = f_3^{-1}, f_1 = f$, we have

$$f = f_1 = (a \cos t + b \sin t)^{1/2}(a \sin t - b \cos t)^{1/2},$$

$$f_3 = f_2^{-1} = (a \sin t - b \cos t)^{1/2}(a \cos t + b \sin t)^{-1/2}.$$ 

Introducing $t_0$ and $r_0$ by letting $r_0 = \sqrt{a^2 + b^2}$, $\cos t_0 = a/\sqrt{a^2 + b^2}$ and $\sin t_0 = b/\sqrt{a^2 + b^2}$, the resulting hyper-symplectic metric can be put in the form

$$g = \frac{1}{2} r_0^2 \sin 2(t-t_0)(-dr^2 + d\phi^2) + \cot(t-t_0)(e^2)^2 - \tan(t-t_0)(e^3)^2,$$

where $e^2$ and $e^3$ are given by (2.27). After an obvious reparametrization, this metric can be written as

$$g = \frac{1}{2} r_0^2 \sin 2\tau (-dr^2 + d\phi^2) + \cot \tau (\sin \phi \, dx - \cos \phi \, dy)^2 - \tan \tau (\cos \phi \, dx + \sin \phi \, dy)^2.$$

### 3.5. Bianchi type VIL0 hyper-symplectic metrics and hyper-Kähler Bianchi type VIL0 metrics

Now we consider the group of rigid motions $E(1, 1)$ of Lorentzian 2-plane defined by the structure equations (2.32). We evolve the structure as in (2.8). Using the structure equations (2.32), the evolution equations (3.4) turn into the solved system of ODEs (2.28) with the general solution given by (2.30) establishing a correspondence with Bianchi VIL0 hyper-Kähler metrics.

When $f_2 = f_3^{-1}, f_1 = f$, we have

$$f = f_1 = \frac{1}{2}(Ae^t + Be^{-t})^{1/2}(Ae^t - Be^{-t})^{1/2}, \quad f_3 = f_2^{-1} = (Ae^t + Be^{-t})^{-1/2}(Ae^t - Be^{-t})^{1/2},$$

$$f_2$$
and the hyper-symplectic metric is
\[ g = \frac{1}{4}(A^2 e^{2t} - B^2 e^{-2t})(-dt^2 + d\phi^2 + \frac{4}{(Ae^t - Be^{-t})^2}(e^t)^2 - \frac{4}{(Ae^t + Be^{-t})^2}(e^t)^2), \]
where \(e^2\) and \(e^3\) are given by (2.32), and \(t > \frac{1}{2} \log |B/A|\) since \(A^2 e^{2t} - B^2 e^{-2t} > 0\). In particular, letting \(A = B\) in (3.8) we obtain
\[ g = \frac{A^2}{2} \sinh 2t(-dt^2 + d\phi^2) + \coth t(\sinh \phi dx + \cosh \phi dy)^2 - \tanh t(\cosh \phi dx + \sinh \phi dy)^2. \]

4. Conclusions

Several explicit cohomogeneity-one hyper-Kähler (local) metrics of Riemannian and neutral signature were found on four-dimensional manifolds \(M = G \times I, I = (a, b)\). The group \(G\) was assumed to be the three-dimensional Bianchi-type group, which acts on \(M\) by left translations of the first factor of \(M\). By considering a time-dependent evolution of a fixed left-invariant basis of 1-forms on \(G\) we defined an almost hyper-Hermitian structure on \(M\). The action of \(G\) extends to a trivial action on the fundamental 2-forms of the hyper-Hermitian structure. The hyper-Hermitian structure is hyper-Kähler if the defined fundamental 2-forms are closed. It was found that the latter condition can be fulfilled only in the case of Bianchi type A groups. Restricting the evolution to one of diagonal type we obtained a system of ODEs whose solutions give a hyper-Kähler metric. For each of the Bianchi type A groups we found the explicit solution of the system of ODEs. The hyper-Kähler metrics of neutral signature, called hyper-symplectic metrics, were found to be in correspondence with the Riemannian hyper-Kähler metrics based on the type of the system of ODEs. Thus, we give new examples of hyper-symplectic metrics and extend the correspondence between classes of hyper-symplectic metrics and hyper-Kähler metrics given in [35] in the Bianchi VIII and IX cases to all Bianchi type A cohomogeneity-one (with trivial action on the fundamental 2-forms) metrics.

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