Compressed Shaping: Concept and FPGA Demonstration

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Abstract—Probabilistic shaping (PS) has been widely studied and applied to optical fiber communications. The encoder of PS expends the number of bit slots and controls the probability distribution of channel input symbols. Not only studies focused on PS but also most works on optical fiber communications have assumed source uniformity (i.e., equal probability of marks and spaces) so far. On the other hand, the source information is in general nonuniform, unless bit-scrambling or other source coding techniques to balance the bit probability is performed. Interestingly, one can exploit the source nonuniformity to reduce the entropy of the channel input symbols with the PS encoder, which leads to smaller required signal-to-noise ratio at a given input logic rate. This benefit is equivalent to a combination of data compression and PS, and thus we call this technique compressed shaping. In this work, we explain its theoretical background in detail, and verify the concept by both numerical simulation and a field programmable gate array (FPGA) implementation of such a system. In particular, we find that compressed shaping can reduce power consumption in forward error correction decoding by up to 90% in nonuniform source cases. The additional hardware resources required for compressed shaping are not significant compared with forward error correction coding, and an error insertion test is successfully demonstrated with the FPGA.

Index Terms—Coding, data compression, distribution matching, entropy, implementation, modulation, optical fiber communication, probabilistic shaping, source coding.

I. INTRODUCTION

Traffic demands are growing with deployments of mobile communication systems for the 5th generation and beyond, which is further accelerated by the pandemic [1]. Optical fiber communications take a key role in the communication infrastructure because of its high capacity. In the past, the modulation formats used in optical fiber communications were binary, e.g., on–off keying, binary, or quaternary phase-shift keying without forward error correction (FEC) or with hard-decision FEC [2]. However, the latest 400 Gb/s standards [3], [4] utilize 16-ary quadrature amplitude modulation (QAM) with soft-decision (SD) FEC under bit-interleaved coded modulation (BICM) [5]–[8]. Furthermore, constellation shaping [9], or more specifically, probabilistic shaping (PS) [10], [11], has attracted wide research interest due to its capacity-approaching performance [12]–[15]. Especially reverse concatenation, where the shaping encoding (also known as distribution matching, DM) [16]–[21], is done outside the FEC encoding [22]–[24], made PS deployable in terms of implementation capability.

An optimal encoder, which minimizes the rate loss in the conversion process, can be theoretically achieved in two steps if the block length is large enough; by applying source coding (often called “data compression”) first and channel coding (i.e., constellation shaping and FEC coding) next. Information-theoretic coding and modulation techniques have realized significant performance improvements in recent years, thus almost closing the gap to the Shannon channel capacity [25]. In contrast, coding for dynamically variable source information [1] has rarely been investigated for fiber-optic communication systems, which aggregates massive user traffic in frames. In the standard [25], simple bit scrambling (flipping bits by the exclusive OR operation with a pseudorandom bit sequence (PRBS)) has been implemented to balance the mark (logic ‘1’) and space (logic ‘0’) counts instead of applying any source coding. Often we tend to assume the source bits as just uniformly distributed and independent, although the true source entropy before bit scrambling is variable and dependent on the user traffic, e.g., due to the existence of idle frames in the media access control (MAC) protocol [26].

Data compression and shaping are almost inverse operations, i.e., the former converts a nonuniform information sequence into a shorter uniform one, while the latter does the opposite. Simultaneous realization of data compression and shaping is not only an interesting research topic but also a key technique for more efficient communications in practice. Thus in this paper, we propose and investigate compressed shaping, which combines the benefits from data compression and shaping. Similar ideas have been studied in the context of joint source–channel coding in communication theory [27], [28], but an application to fiber-optic communication is presented here, for the first time to the best of our knowledge.

Compressed shaping is enabled by a shaping encoding that is sensitive to the source entropy. As data compression allocates short bit patterns to frequently occurring source words, compressed shaping allocates amplitudes with small energy.
to such frequent source words. This compression feature is similar to burst signalling in time-domain multiple access [29], i.e., optical power variation depending on the traffic. Compressed shaping is a fixed-length to fixed-length conversion, and the average energy of channel input symbols is reduced for source information sequences having a small entropy. We do not need an operational mode change such as updating the source statistics based on prior knowledge, although this would be a kind of data compression. Our previously proposed look-up table (LUT)-based hierarchical DM [19] and following works [30], [31] can be applied for this purpose by reordering the LUT entries without significantly increased complexity. The proposed technique can reduce the rate losses associated with source and channel coding compared with state-of-the-art DM schemes such as constant-composition DM (CCDM) [16], or reduce the power consumption in the FEC at a given information rate and signal-to-noise ratio (SNR) by relaxing the FEC performance. We also report a field programmable gate array (FPGA) implementation, and the hardware demonstration results for compressed shaping 16- and 64-QAM at system throughput of 153 and 113 Gb/s, respectively.

This is an evolitional work of [32]–[34], which are here extended by providing a more detailed theoretical background of compressed shaping. The system throughput is increased by separating the clock domain into data and controlling because the control circuitry was the bottleneck in the logical circuitry when making the clock frequency faster. The accuracy of the power consumption estimation is improved by introducing a dynamic simulation. Even if we consider shaping encoding only, there have been very few other reports on FPGA implementations [35], [36]. Furthermore, there are neither any reports on static/dynamic power consumption estimates nor any demonstrations by FPGA implementations including both shaping encoding and decoding, except [33].

The rest of the paper is organized as follows. The principle of compressed shaping is explained in Sec. II and its numerical simulations are shown in Sec. III. An FPGA implementation example of compressed shaping is presented in Sec. IV and the hardware-based demonstration results are summarized in Sec. V. Finally, Sec. VI concludes the paper.

II. COMPRESSED SHAPING—BASIC PRINCIPLES

While conventional PS systems employ full bit-scrambling and assume source uniformity, the proposed compressed shaping scrambles the sign bit only and applies source-sensitive amplitude shaping to realize better performance in the case of small source entropy. In this section, we firstly review the historical source uniformity assumption in conventional systems and discuss rate loss under either uniform or nonuniform source conditions. Then we compare compressed shaping with bit-sequence data compression and PS. Finally, we show the system model and characterize entropy bounds in compressed shaping systems.

A. Rate loss in conventional systems

Optical fiber communication systems gather many MAC frames from client traffic. When investigating coding and modulation techniques, source uniformity is usually assumed. It is because a 50% mark ratio is produced by line coding or bit scrambling, even if the true source information is nonuniform. This may be a reasonable model under the idealized assumption of a stable, uniform traffic flow. However, due to dynamically variable traffic volumes [1], there will be many idle frames. These are encoded by 64B/66B line coding into the zero codeword except for the sync header and block type field. Due to the existence of such idle frames, the source bits $S_i \in \{0, 1\}$ can have more than 50% ‘0’s, which makes the binary source entropy $H(S_i) < 1$, where $H(\cdot)$ denotes entropy. For example, when an 8-byte idle signal is encoded by 64B/66B, a 66-bit block consists of the 2-bit sync header 01, the 8-bit block type field 00011110, and eight 7-bit control bits 00000000 for the 8-byte idle signal, which results in a source mark ratio of $5/66 = 7.6\%$.

In conventional systems, the (serial) source bits $S_i$ are parallelized to form a source bit sequence $[S_1 \ldots S_{k_{ba}}]$, after which the bit scrambling converts $[S_1 \ldots S_{k_{ba}}]$ into a scrambled bit sequence $[U_1 \ldots U_{k_{ba}}]$. The sequence length $k_{ba}$ is chosen to match the applied bit-scrambling protocol. An arbitrary (randomly selected) bit in this scrambled sequence has the distribution $P_{U_i} = (1/k_{ba}) \sum_{i=1}^{k_{ba}} P_{U_i}$, which is assumed to be uniform and $H(U) = 1$, even when the corresponding (serial) unscrambled bit distribution $P_S = (1/k_{ba}) \sum_{i=1}^{k_{ba}} P_{S_i}$ yields an entropy $H(S) < 1$. The bit scrambling is essential in binary modulation for maintaining direct current levels in electronic devices and for recovering the clock signal at the receiver. Non-PS QAM systems also utilize bit scrambling to maintain the 50% mark ratio. In general, neither $S_i$, nor $U_i$ ($i = 1, 2, \ldots, k_{ba}$) is ensured to be identical and independent distributed (i.i.d.), so $H([S_1 \ldots S_{k_{ba}}]) \leq k_{ba} H(S)$ and $H([U_1 \ldots U_{k_{ba}}]) \leq k_{ba} H(U)$ by the concavity of entropy. However, $[U_1 \ldots U_{k_{ba}}]$ is assumed to be i.i.d. and uniform in most research works on channel coding.

In PS, the goal is to reduce symbol entropy at a given information rate in order to reduce the required SNR for quasi-error-free operation over channels approximated by the Gaussian channel. The scrambled bit sequences $[U_1 \ldots U_{k_{ba}}]$ are rearranged into sequences of length $k$, and each such length-$k$ bit sequence is mapped into a sequence of amplitudes $[A_1 \ldots A_n]$. The sequence lengths $k$ and $n$ are selected to match the PS scheme, regardless of $k_{ba}$. Since $U_i$ is in general not i.i.d., neither is $A_i$, and thus $H([A_1 \ldots A_n]) \leq nH(A)$, where $P_A = (1/n) \sum_{i=1}^{n} P_{A_i}$. On the other hand, $A_i$ is assumed to be i.i.d. in a mismatched (memoryless) receiver.

The PS performance is typically quantified with a rate loss

$$R_{loss}(U, A) = H(A) - \frac{k}{n},$$

(1)

where $R_{loss}(\cdot, \cdot)$ denotes a rate loss in a sequence conversion, and $R_{loss}(U, A) \geq 0$ for i.i.d. $U_i$. The CCDM [16], which has been the state-of-the-art PS coding, has an almost negligible rate loss when $n$ is sufficiently large, e.g., 1000–10000. The CCDM generates a fixed probability mass function (PMF) $P_A$ of output amplitudes $A$ regardless of the DM encoder input bit sequence and its statistics. For a fixed PMF $P_A$ with a nonconstant-composition DM, $U_i$ is required to be
uniformly distributed in general, which can be achieved by bit scrambling.

B. Rate loss in source to amplitude conversion

The CCDM shows negligible rate loss $R_{\text{loss}}(U, A)$ in (1) with a sufficiently large block length in PS for a uniform source, but not for nonuniform sources, in which case the channel input symbol entropy or average symbol energy can be further reduced by exploiting nonconstant-composition DM.

During a conversion process from source bit sequence to amplitude symbol sequence, bit scrambling acts against the symbol entropy reduction because it maximizes binary entropy (symbol entropy reduction because it maximizes binary entropy amplitude symbol sequence, bit scrambling acts against the further reduced by exploiting nonconstant-composition DM. In the case of nonuniform sources, in which case the rate loss in the conversion from a nonuniform source bit sequence $[S_1 \ldots S_k]$ into an amplitude sequence $[A_1 \ldots A_n]$ can in general be expressed as

$$R_{\text{loss}}([S_1 \ldots S_k], A) = \frac{\mathbb{H}(A) - \mathbb{H}([S_1 \ldots S_k])}{n},$$

which is bounded as

$$R_{\text{loss}}([S_1 \ldots S_k], A) \geq R_{\text{loss}}(S, A),$$

$$R_{\text{loss}}(S, A) = \frac{\mathbb{H}(A) - \mathbb{H}(S)}{n}. \quad (4)$$

Obviously, CCDM is not optimum (with or without bit scrambling) because of the constant $P_A$ and $\mathbb{H}(A)$ regardless of the source distribution. The general rate loss bound $R_{\text{loss}}(S, A)$ in (4) becomes significantly larger than $R_{\text{loss}}(U, A)$ in (1) under a small $\mathbb{H}(S)$. A nonconstant-composition DM could be source sensitive, i.e., realizing a smaller output entropy $\mathbb{H}(A)$ for a smaller input entropy $\mathbb{H}(S)$, resulting in a smaller $R_{\text{loss}}(S, A)$ compared with CCDM. Even in such cases, at least the sign bits should be bit-scrambled for the direct current level management and clock recovery. To enhance the performance under nonuniform source information, data compression is another option, at the expense of, possibly large, digital signal processing circuit resources, since it has to adapt to the time variation of $\mathbb{H}(S)$.

C. Proposed bit sequence conversion

This section explains the principle of the proposed compressed shaping compared to well-known data compression and PS. Tab. (b) shows small examples of bit sequence conversions using (a) data compression, (b) PS, and (c) compressed shaping.

Tab. (a) assumes a nonuniform source input bit sequence $S = [S_1 S_2]$, which is separated into a source sign bit sequence $S_s = [S_{s1} \ldots S_{sk}]$, and a source amplitude bit sequence $S_a = [S_{a1} \ldots S_{ak}]$. The source sign bit sequence $S_s$ is bit-scrambled into $U_s = [U_{s1} \ldots U_{sk}]$ by taking the exclusive OR with a PRBS, to balance the numbers of ‘1’s and ‘0’s. The source amplitude bit sequence $S_a$ is processed by a bit-flipping function, which flips all input bits if there are more ‘1’s than ‘0’s and adds a parity bit ‘1’, otherwise just adds a parity bit ‘0’, because a large mark ratio is not desirable in the compressed shaping scheme. Then the bit-flipping encoding

\footnote{There may be situations with a predominance of ‘0’s (due to many idle frames) or ‘1’s (due to an alarm indication signal) \cite{25}. In both cases, the source entropy is small.}
TABLE I
Bit sequence conversions.

| (a) Data compression | Input | Output |
|----------------------|-------|--------|
| Bits | Probability | Bits | Probability | Length |
| $S$ | $P_S$ | $C$ | $P_C$ | $n_C$ |
| 00 | 0.50 | 1 | 0.50 | 1 |
| 01 | 0.30 | 01 | 0.30 | 2 |
| 10 | 0.15 | 001 | 0.15 | 3 |
| 11 | 0.05 | 000 | 0.05 | 3 |
| Average | | | | 1.7 |

(b) PS

| Input | Output |
|-------|--------|
| Bits | Probability | Amplitudes | Probability | Avg. energy $E_A$ |
| $U$ | $P_U$ | $A$ | $P_A$ | $E_A$ |
| 00 | 0.25 | 111 | 0.25 | 1 |
| 01 | 0.25 | 113 | 0.25 | 3.67 |
| 10 | 0.25 | 131 | 0.25 | 3.67 |
| 11 | 0.25 | 311 | 0.25 | 3.67 |
| Average | | | | 3 |

(c) Compressed shaping

| Input | Output |
|-------|--------|
| Bits | Probability | Amplitudes | Probability | Avg. energy $E_A$ |
| $S$ | $P_S$ | $A$ | $P_A$ | $E_A$ |
| 00 | 0.50 | 111 | 0.50 | 1 |
| 01 | 0.30 | 113 | 0.30 | 3.67 |
| 10 | 0.15 | 131 | 0.15 | 3.67 |
| 11 | 0.05 | 311 | 0.05 | 3.67 |
| Average | | | | 2.33 |

Output bit sequence $F = [F_1 \ldots F_{k+1}]$ contains at least as many ‘0’s as ‘1’s. The sequence $F$ is then processed in a hierarchical DM, which consists of hierarchically connected small look-up tables (LUTs) as shown in Fig. [19]. There are $L$ layers and $T_ℓ$ LUTs in each layer $ℓ$. Each LUT in a layer $ℓ$ receives $s_ℓ$ bits from the input interface of the DM and sends $t_ℓ$ bits to each of the $T_ℓ$ LUTs in layer $ℓ+1$, and it transmits $r_ℓ$ bits to the input interface of the DM. To determine the one-to-one correspondence of input and output words in each small LUT, we sort the input words in ascending order of the number of ‘0’s and the output amplitudes in ascending order of average energy, as in the small example shown in Tab. (c). The output amplitude sequence from the hierarchical DM is $A = [A_{c,1} \ldots A_{c,n}]$, where each element is a two-dimensional vector $A_{c,i} \in \{1, 3, \ldots, 2^{m_a/2-1}\}$. $m_a$ is the number of bit tributaries for a two-dimensional amplitude, and $P_{A_c} = (1/n) \sum_{i=1}^n P_{A_{c,i}}$. The amplitude sequence $A$ is represented by a bit sequence $B_a = [B_{a,1} \ldots B_{a,n,m_a}]$. From $B_a$ and $U_a$, an FEC parity bit sequence $B_{fp}$ is generated by a systematic FEC encoder with an FEC code rate $R_c$. Then $U_a$ and $B_{fp}$ are concatenated into a sign bit sequence $B_s = [B_{s,1} \ldots B_{s,n,m_s}]$, where $m_s$ denotes the number of sign-bit tributaries. The number of elements in $S_s$ or $U_s$ is $k_{bs} = n(m_s R_c - m_a(1 - R_c))$ and that in $B_{fp}$ is $(1 - R_c)n(m_a + m_s)$. Finally channel input QAM symbols $X = [X_{c,1} \ldots X_{c,n}]$ are generated from $B_s$ and $B_a$, where $P_{X_c} = (1/n) \sum_{i=1}^n P_{X_{c,i}}$. The channel output QAM symbols $Y = [Y_{c,1} \ldots Y_{c,n}]$ are demapped into an L-value sequence $L_{c} = [L_{c,1} \ldots L_{c,n}]$ by memoryless bit-metric decoding [12], where $Y_{c,i} \in \mathbb{R}^2$ and $\mathbb{R}$ denotes the real number set. The receiver-side process-
averaging of dynamic variations of the source mark ratio due to idle MAC frames. Such granular base constellation and shallow shaping help to avoid excessive increases of peak-to-average power ratio and power consumption \cite{38}, \cite{39} and penalties from nonideal FEC performance \cite{40}. As the 8-QAM constellation, \( C_3 \) in \cite{41} was used to make the constellation symmetric around the imaginary axis \( \bar{X} \) so that the uniformly distributed FEC parity bits could be placed on the sign bits without changing \( P_{X_c} \). The bit labelling for 128-QAM was based on \cite{42} Fig. 3. For comparison, CCDM-based PS-16-QAM and PS-64-QAM were also evaluated, using the same PS overhead and codeword length as with compressed shaping. We also evaluated the performance of PS-4096-QAM with an ideal Maxwell–Boltzmann input distribution and perfect data compression.

With CCDM, the energy \( E_{2d} \) in Fig. 5 is constant for various \( P_S(1) \) cases, because its output PMF \( P_A \) does not depend on incoming bits. With compressed shaping, on the other hand, \( E_{2d} \) decreases with decreasing \( P_S(1) \) and \( H(S) \) for each base constellation, although there are significant performance gaps to the ideal case (black solid line in Fig. 3), especially for high-order QAM. This gap comes from the fixed compressed shaping regardless of the source statistics. While an adaptive compressed shaping would bring the performance closer to the ideal case, it would lead to a high complexity and is out of scope of this work. Fig. 4 exemplifies the PMF \( P_A \) for compressed shaping 64-QAM with source mark ratios \( P_S(1) = 0.5-0.05 \). Higher source nonuniformity (i.e., smaller \( P_S(1) \)) makes deeper PS. Under such source nonuniformity, we observed reduced \( P_A(3), P_A(5), \) and \( P_A(7) \) and increased \( P_A(1) \) compared with the uniform source case. The transmitted PMFs of one-dimensional amplitudes \( A \) and two-dimensional channel input symbols \( X_c \) at a given source mark ratio \( P_S(1) \) are denoted as \( P_A(P_S(1)) \) and \( P_{X_c}(P_S(1)) \), respectively.

We then simulated the required SNR over the Gaussian channel with the DVB-S2 low-density parity check code \cite{43} having a code rate of 5/6, with a maximum number of

2The signal points are \((\pm 1, 0), (\pm 1, \pm 2), \) and \((\pm 3, 0)\).
compressed shaping, in contrast to the fixed required SNR. As shown in Fig. 5, the required SNR can be reduced by circuitry. The vertical axis in Fig. 6 is normalized by the which is almost proportional to the toggle rate in logical be proportional to the average number of decoding iterations, as explained in the text.

Fig. 4. An example of a one-dimensional amplitude PMF $P_X$ by compressed shaping 64-QAM, for various source mark ratios $P_S(1)$. In situations with dynamically variable $P_S(1)$, the demapper assumes a constant $P_S(1) = 0.5$, as explained in the text.

decoding iterations of 50. Fig. 5 shows the simulated required SNR with the maximum number of FEC decoding iterations. The required SNR is defined at an asymmetric information [44], [45] of 0.87, which corresponds to a pre-FEC BER of about $3.4 \cdot 10^{-2}$. We observed no residual bit errors in more than $2.5 \cdot 10^6$ information bits after FEC decoding in the SNR regime larger than the required SNR for each case. We simulated both mismatched and matched decoding. The true transmitted two-dimensional symbol PMF is denoted by $P_{X_c}(P_S(1))$ and the transmitted symbol PMF assumed in the soft demapping by $Q_{X_c}(P_S(1))$. In the matched case, $Q_{X_c}(P_S(1))$ was set to $P_{X_c}(P_S(1))$ for all $P_S(1)$, while in the mismatched case, $Q_{X_c}(P_S(1))$ was set to a fixed PMF of $P_{X_c}(0.5)$ regardless of the true $P_S(1)$. This is because under dynamically variable source situations, the true transmitted symbol PMF $P_{X_c}(P_S(1))$ is hard to track in deployable systems. As shown in Fig. 5, the required SNR can be reduced by compressed shaping, in contrast to the fixed required SNR by CCDM and uniform QAM with bit scrambling due to the fixed $P_{X_c}(= P_{X_c}(0.5))$. The SNR penalty by the mismatch between $P_{X_c}(P_S(1))$ and $Q_{X_c}(P_S(1))$ is not significant except at very small $P_S(1)$.

The better performance of compressed shaping compared with conventional PS can be converted into lower power consumption. We quantified the power consumption in FEC decoding.

![Image](https://via.placeholder.com/150)

Fig. 5. Simulated required SNR for compressed shaping QAM under matched (dotted lines) and mismatched decoding (solid lines). In the mismatched case, we set the transmitted PMF assumed in the demapper to the one for a uniform source ($P_S(1) = 0.5$), for every source mark ratio $P_S(1)$. Dashed and long-dashed lines correspond to CCDM and uniform QAM, respectively.

![Image](https://via.placeholder.com/150)

Fig. 6. Simulated relative power consumption of the FEC decoding, which is assumed to be proportional to average number of decoding iterations, as a function of SNR for PS-QAM. Solid and black dashed lines correspond to compressed shaping and CCDM, respectively.

with bit scrambling, but not shown in Fig. 6, compressed shaping significantly reduces the power to about 10% for highly nonuniform source probabilities, because of the smaller required SNR, which leads to a smaller number of decoding iterations than with conventional bit-scrambled PS.

While in this work, the source mark ratio is assumed to be constant, dynamic variations thereof were simulated in Sec. 5.4. Source mark ratios were linearly varied, e.g., from 20% to 40% or from 10% to 50%, and compared with a constant 30% as a benchmark. For a larger range of variation, the performance improved slightly, even if the average source mark ratio over many blocks was the same. Note that additional complexity in compressed shaping is not significant when hierarchical DM is employed for shaping encoding/decoding, which will be shown in the next section.

IV. FPGA IMPLEMENTATION

We implemented compressed shaping in a single FPGA chip on an evaluation board Xilinx® Virtex® Ultrascale+™ VCU118 XCVU9P. Fig. 7 shows the functional block diagram of the implemented circuitry. The source generator outputs

3The asymmetric information is equivalent to normalized generalized mutual information [15], [40] and achievable FEC rate [14] under matched decoding.
source information bits based on a given target mark ratio $P_S(1)$. The schematic of the source generator is illustrated in Fig. 8. Each source information bit is selected from one of three possible candidates; 0) the logic bit ‘0’, 1) a PRBS of length $2^{31} - 1$ bits, and 2) the logic bit ‘1’. The mask signal, used for the selection, is generated from the target source mark ratio $P_S(1)$, which is given by the user. If $P_S(1) \leq 0.5$, the mask signal takes on values 0 or 1 such that the average fraction of logic ‘1’s in $S$ is $P_S(1)$, and if $P_S(1) > 0.5$, the mask similarly is 1 or 2. Fig. 9 shows an exemplified mask signal when the target $P_S(1)$ is 0.4. For simplicity, we classified source bits into 20 groups (32 bits per group), provided a ‘0’ mask window for four groups, and slid the window in every clock cycle.

The bit-flipping encoder counts the numbers of ‘0’s and ‘1’s. When the number of ‘1’s is larger than that of ‘0’s, it flips all bits at the clock cycle and adds a parity bit ‘1’. Otherwise it just adds a parity bit ‘0’. The shaping encoding/decoding is realized by hierarchical DM having a total codeword length of 404 bits for the shaped two-dimensional amplitudes. The number of shaped information bits per two-dimensional amplitude $k/n$ for compressed shaping employing hierarchical DM is generally flexible, and is in this implementation fixed to 372/202 and 372/101 for 16-QAM and 64-QAM, respectively, with compressed shaping. Before the receiver-side processing, we have an error insertion function, which inserts bit errors based on a given bit error rate (BER) before the shaping decoder. The shaping decoder is also implemented with a hierarchical DM decoder, and the bit-flipping decoder recovers the source bits. When the parity bit is ‘1’, it flips all bits at the clock cycle and removes the parity bit. Otherwise, it just removes the parity bit.

There are several monitoring functions, i.e., the PMF $P_{Ak}$ at the shaping encoder output, the assumed post-FEC BER, and the system output BER. Note that hierarchical DM mainly consists of LUTs, which are implemented with random access memory (RAM). Because it is sensitive to unwanted bit-flipping due to radiation-induced soft errors, we implemented soft error protection circuitry.

The clock domain was initially single and the clock frequency $f_{\text{clk}}$ for the fitting (FPGA synthesis) was 90 MHz [33]. Later we found a bottleneck in making the clock frequency higher inside the soft error protection circuitry (consisting of flip-flops and a selector tree for refreshing RAM contents), so we separated the clock domain into one for data processing and one for control. We then achieved $f_{\text{clk}} = 240$ MHz for the data processing for higher throughput. Assuming a suitable FEC concatenation (not implemented here), the system throughputs for compressed shaping 16- and 64-QAM would be 57 and 42 Gb/s at $f_{\text{clk}} = 90$ MHz, and 153 and 113 Gb/s at $f_{\text{clk}} = 240$ MHz, respectively. The number of bits per PS codeword were the same in both cases, i.e., there were half as many PS-64-QAM symbols as PS-16-QAM symbols.

Tab. III shows the utilized hardware resources at a clock frequency of the data signals $f_{\text{clk}} = 90$ or 240 MHz. Fig. 10 depicts the utilized area of the FPGA chip having three dies. The used resource elements were mainly located in the left and right dies, and the center die was mainly used for connection between the two dies. The register elements were mainly used by the soft error protection circuitry for storing the RAM contents. Out of the about 290,000 utilized LUT as logic elements, 70% were provided to external functions such as source generator and BER/PMF monitors, 10% were for bit-flipping encoding, and the rest was for other combinational logics. The data processing of the hierarchical DM used totally 3.5 Mb block RAM elements. No ultra RAM or DSP slice elements were used.

As a benchmark, 400 ZR FEC was implemented in 50 Xilinx® Virtex® Ultrascale™ FPGAs [47]. The clock frequency was 125 MHz and the system throughput was 200 Gb/s with

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1. A flexible choice of $(n, k)$ in an FPGA implementation of hierarchical DM is left as potential future work. The LUT contents can be reconfigured in software or firmware without increasing the RAM size.
external functions, i.e., source generation, mapping, demapping, interleaver, de-interleaver, and noise loading. Even considering that this reference includes many external functions, compressed shaping utilizes a very small amount of hardware resources.

Tab. III shows the estimated dynamic power consumption for compressed shaping 64-QAM at $f_{\text{clk}} = 240 \text{ MHz}$. While we estimated a static power consumption based on a default toggle rate of 12.5% in our previous report [33], we now improved the estimation accuracy by taking realistic node switching activities into account based on register transfer level simulation waveform (a so-called switching activity interchange format) over 4000 clock cycles, where the source mark ratio $P_S(1)$ was set to 0.5.

The blocks of Tx data and Rx data in Tab. III are essential for data communications. Among them, the preprocessing (including bit-flipping encoding) and DM encoder core in the Tx data block, and the DM decoder core in the Rx data block, consumed most of the power. The DM encoder and decoder cores mainly consisted of block RAMs for LUTs. The bit-flipping encoding counted the logic ‘1’s using adders, leading to a relatively large power consumption. Other pre- and postprocessing functions including the lane reorder consumed little power. Note that the power consumption of either the Tx or the Rx data block was smaller than that of external functions, e.g., source generation and BER monitoring. We had nonnegligible power consumption in the control blocks. They had soft error protection functions for the DM encoder and decoder cores by holding copies of the entire RAM contents in registers and refreshing the RAM intermittently. These powers can be expected to be less in an ASIC implementation by making the activation ratio small.

V. HARDWARE DEMONSTRATION

We demonstrated compressed shaping by employing the FPGA evaluation board at $f_{\text{clk}} = 90 \text{ MHz}$. First, the transmitter-side functions were verified. Histograms of the two-dimensional amplitude $A_c$ for compressed shaping 16- and 64-QAM were measured over $10^{10}$ two-dimensional amplitude samples for various source mark ratios $P_S(1)$. The obtained histograms were interpreted as PMFs $P_{A_c}$ and their entropies were computed. Fig. 11 shows $H(S)$ as a function of $P_S(1)$. The entropy $H(A_c)$ is maximum for $P_S(1) = 0.5$. The two-dimensional PS rate losses $R_{\text{loss}}(U, A_c)$ are 0.034 and 0.064 bpcu for the exemplified PS-16-QAM and PS-64-QAM schemes, respectively. When $P_S(1)$ deviates from 0.5, i.e., $H(S)$ decreases, $H(A_c)$ also decreases monotonically. Because of the bit-flipping encoding, $H(A_c)$ is symmetric around $P_S(1) = 0.5$. In contrast, the CCDM-based schemes show a constant $H(A_c)$, which is independent of the source distribution. Scaled binary entropy functions $H(S)$ are also depicted in Fig. 11 with black dotted lines for the two cases. The gap between $H(A_c)$ and $H(S)$ for $P_S(1)$ is a data compression rate loss. The data compression rate loss is ideally zero but is larger here for smaller $H(S)$, due to the nonideal simple processing of compressed shaping. Here the bit sequence conversion loss in compressed shaping $R_{\text{loss}}(S, A_c)$ is given by the sum of rate losses in PS and data compression. Regardless of the rate loss increase in data compression, $H(A_c)$ itself is reduced to help reduce the required SNR substantially.

Next, the receiver-side functions were verified. We turned the error insertion function on to provide sparse bit errors between the transmitter and the receiver. As reported in [19], sparse errors creates the worst system output BER at a given post-FEC BER. We swept the assumed post-FEC BER from $10^{-5}$ to $10^{-15}$ and examined $P_S(1)$ of 0.3, 0.5, and 0.7 for compressed shaping 16- and 64-QAM. After the receiver-side processing, the system output BER was measured. Fig. 12 shows the system output BER as a function of assumed post-FEC BER in the back-to-back error insertion test. The BER increase due to compressed shaping decoding was only around 10 times because hierarchical DM can partially decode correctly even if there are incoming bit errors. As predicted in [19], the BER increase factor is significantly smaller than...
for other DM techniques. For example, CCDM decoding having a PS codeword length of around 400 bits results in more than 100 times higher BER, though we could not implement CCDM in the FPGA due to its high complexity. We performed 70 hours of long-term measurement only in the case of $P_S(1) = 0.5$, due to time constraints. The number of observed bit errors after compressed shaping decoding were more than 250. The system output BER was $1.5 \cdot 10^{-14}$ at a post-FEC BER of $1.6 \cdot 10^{-15}$. This proves that the proposed compressed shaping does not cause an error floor or excessive error increase, so the required post-FEC BER remains around $10^{-15}$ to satisfy a required system output BER of $10^{-15}$.

VI. SUMMARY

We proposed and demonstrated compressed shaping, i.e., the application of hierarchical DM to simultaneous source data compression and probabilistic shaping, which is an example of joint source–channel coding. Under a reduced source entropy, compressed shaping reduces channel input symbol entropy, symbol energy, and required SNR. Simulation results showed its smaller required SNR, as well as reduced power consumption compared with CCDM. We implemented compressed shaping, which are mainly hierarchical DM encoding/decoding, into a single FPGA and estimated the dynamic power consumption based on simulated waveforms. The system throughput reached 153 and 113 Gb/s for compressed shaping 16- and 64-QAM, respectively. Real-time evaluation results showed expected performance in both encoding and decoding. Compressed shaping works at a very small BER of around $10^{-15}$ without any error floor, and its decoding increases the BER only around 10 times, which is small compared to other DM schemes.

The time-varying symbol energy in compressed shaping causes practical issues with respect to electrical amplitude, optical power, and SNR control in fiber-optic communication systems, although such a variation per channel can be statistically relaxed by multiplexing many channels. One example can be found in a wavelength-division-multiplexed system operated at a given total launch power. Without any control of the average symbol energy per channel, the average optical power in some channels can temporarily be reduced when the source entropy becomes small. This leads to a larger average optical power and thus higher nonlinearity impairments in other copropagating channels. Analyses of such issues and development of appropriate control methods are deferred to a future work. We can also potentially explore the adaptation of compressed shaping to mass trends of source and channel variations.

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