A New Analytical Model for Calculating Transient Temperature Response of Vertical Ground Heat Exchangers with a Single U-Shaped Tube

Shichen Gao 1, Changfu Tang 2, Wanjing Luo 3, Jiaqiang Han 3 and Bailu Teng 3,*

1 School of Science, China University of Geosciences (Beijing), Beijing 100083, China; gsc2039@cugb.edu.cn
2 Exploration Research Institute, Anhui Provincial Bureau of Coal Geology, Hefei 230088, China; cftang@mail.ustc.edu.cn
3 School of Energy Resources, China University of Geosciences (Beijing), Beijing 100083, China; luowanjing@cugb.edu.cn (W.L.); 1006161217@cugb.edu.cn (J.H.)

* Correspondence: bailu@cugb.edu.cn

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Abstract: The transient temperature response is of great importance for evaluating the thermal capacity of ground heat exchangers (GHE). Based on the composition line source theory and superposition principle, we have developed a novel analytical model in Laplace space for calculating the temperature transient response. In comparison to the existing models, this proposed model can account for the fluid thermal storage effect and heat rate difference between the two legs of the single U-tube. With the aid of this proposed model, we conduct a thorough sensitivity analysis to investigate the effects of different influencing factors on the thermal transient response. The calculated results show that fluid thermal storage and the rate difference can significantly influence the thermal response during the early studied period. Therefore, the effect of fluid thermal storage should not be neglected when the early-time thermal response is investigated. The thermal interference between the two legs will reduce the heat capacity of GHEs. A large distance between these two legs can be favorable for practical use.

Keywords: analytical model; transient temperature response; U-shaped tube

1. Introduction

Heat transfer models have been used for thermal performance analysis for the ground heat exchangers (GHE), such as in-situ test, borehole length calculation, ground heat pump management [1–3]. In recent years, developing accurate heat transfer models of the ground heat pump system has attracted more and more attention [1]. Figure 1 presents a schematic of vertical ground heat exchangers with a single U-tube in a borehole. As shown in this figure, the U-tube can be divided as a descending leg and an ascending leg. A traditional approach to model the heat transfer of borehole GHEs is to decompose the thermal process into a steady part and an unsteady part [1,2]. The space between the borehole and tube is filled with grout, whose thermal properties are different from those of the soil outside the borehole. During the early period, the heat mainly influences the space inside the borehole and the effect of fluid thermal storage can cause a lag in temperature change. As time proceeds, the thermal behavior will expand to the area outside of the borehole and will be affected by the properties of the soil. In addition to the fluid thermal storage, the thermal behavior inside the borehole can be affected by the properties of the grout, the geometries of the two legs of the U-tube, and the fluid flow in the legs; hence, it can be very difficult to accurately characterize the thermal behavior. Furthermore, in the tube the convective heat transfer dominates, and the average fluid

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temperature in the descending leg is always higher than that in the ascending leg. Hence, the average heat rates of the two legs are always different, which can also influence the thermal behavior of GHE.

![Figure 1. Schematic of a borehole GHE with a single U-shape tube.](image)

At present, both the numerical method and analytical method have been widely utilized in studying the thermal performance of GHE [2–9]. Compared with the analytical models, the numerical models are normally much more computationally demanding. Therefore, when it is required to conduct numerous simulation runs, the analytical models can be preferred to be utilized. The classical analytical solution for modeling heat transfer of borehole GHEs is based on the infinite line source model. As suggested by Ingersoll [7], the borehole can be considered as a line source or cylinder source, while heat transfer in the borehole is assumed to be steady. According to the infinite lines source model, we can have [1]:

\[
T_f = q \cdot T_u(t, r_b) + q \cdot R_b / H
\]

where \( q \) is heat rate, \( H \) is length of borehole, \( t \) is time, \( r_b \) is borehole radius, \( T_u \) is the line source function. The average temperature \( T_f \) can be approximated with the average value of the inlet fluid temperature \( T_{in} \) and outlet fluid temperature \( T_{out} \):

\[
T_f = \frac{T_{in} + T_{out}}{2}
\]

Many models have been presented for calculating the steady borehole resistance \( R_b \).

By lumping the two legs of the U-tube together as an equivalent tube, Claesson and Dunand [10], Kavanaugh [9], and Gu and O’Neal [11] developed different methods for calculating the value of \( R_b \) with the concept of equivalent diameter. Paul [12] utilized the shape factor to account for the borehole resistance. The value of the shape factor can be obtained by conducting numerical simulation or experimental study [12,13]. Both the equivalent diameter and shape factor method are simple and easy to be implemented for practical use. However, they cannot consider the thermal interference between the two legs. By using the multipole method, the Sweden research group [8,14] proposed a more accurate borehole resistance model, which can account for the effect of the geometry of the two legs on the borehole resistance \( R_b \).

The traditional line-source model is simple and has been widely used in ground heat pump engineering [1–3]. However, in the traditional model Equation (1), the heat transfer inside the borehole
is simply assumed to be steady which can be oversimplified, thus these methods cannot provide sufficiently accurate results for characterizing the thermal behavior at the early period. This will lead to the fact that when one conducts the thermal response test analysis using the line source theory, the simulated results cannot agree well with the measured data of the early period. Thus, a sufficiently long testing duration is required in order to obtain a reliable estimation of ground thermal properties [15].

In recent years, the early thermal behavior of GHEs has attracted more and more attention from researchers, and various models, including numerical models [4–6] and analytical models [6,15–20], have been proposed to investigate the early thermal behavior. In the analytical models, The U-tube configuration is approximated as concentric cylinders to account for the variation of thermal property from grout to soil. Beier and Smith [15] developed an analytical solution in the Laplace domain for the in-situ test. By utilizing the generalized orthogonal expansion technique, Gu and O’Neal [16] presented an approximate composite line source solution in which the two legs of U-tube is represented by a single pipe together with an effective diameter. Based on the equivalent diameter approach, Lamarche and Beauchamp [17] developed an analytical solution for short-time temperature analysis of geothermal vertical boreholes. Their model [15–17] considered fluid thermal storage capacity and the thermal properties of the grout. However, since the U-tube is simplified as a single line source in these models, the geometry effect of the two legs and the heat rate difference between the two legs are neglected.

In order to overcome the shortcomings of the 1-D models, Li et al. [18,19] proposed a 2-D composite line source model, in which each leg of the U-tube is taken as a separate line source in the composite medium, therefore the interference between the two legs can be characterized with the superposition principle. However, in Li’s work, the thermal storage effect of fluid is neglected and the heat rates of the two legs are assumed to have the same value, which can induce inaccurate simulation outputs for real applications. In this work, we attempted to develop a 2-D composite line source model considering the thermal storage effect of fluid and the heat rate difference between the two legs.

2. Analytical Composite Line Source Model

In this section, we will construct a new 2-D composite line source model for GHEs with a single U-tube. This model is constructed in the Laplace-domain.

2.1. Assumptions

As shown in Figure 1, the U-tube locates in a composite medium consisting of a part inside of the borehole and a part outside of the borehole. Both legs of the U-tube are considered as line sources inside the composite medium. The other assumptions are as follows:

1. The radius of the borehole is \( r_b \), and depth is \( H \). The properties of the grout and soil are homogeneous and isotropic. These properties include soil thermal conductivity \( \lambda_s \), soil volume heat capacity \( c_s \), grout thermal conductivity \( \lambda_g \), and volume heat capacity \( c_q \).
2. The two legs of the U-tube are symmetrically arranged with respect to the center of the borehole. The distance between the two legs is 2D. The fluid is pumped into the descending leg with an inlet temperature \( T_{in} \), and flows out of the ascending leg with an outlet temperature \( T_{out} \). The temperature at the bottom of the U-tube is \( T_m \). The average heat rates of the descending leg and ascending leg are \( q_{p1} \) and \( q_{p2} \), respectively.
3. The total heat rate of the GHE \( q_G \) is assumed to be a constant. The fluid flows in the tube with a constant volumetric flow rate \( w_f \), the volume heat capacity of the fluid is \( c_f \), and the average heat rates of fluid in the two legs are \( q_{f1} \) and \( q_{f2} \), respectively. Thus, we can have:

\[
q_G = q_{f1} + q_{f2}
\]
The fluid flow in the tubes is turbulent, and the heat transfer along the vertical direction can be neglected.

### 2.2. Composite Line Source Model

The detailed formulation of the 2-D composite line source model is presented in Appendices A and B. In order to account for the fluid storage effect, both heat rates of the two legs, \( q_f1 \) and \( q_f2 \), will vary with time. Therefore, it can be more convenient to develop the model in the Laplace domain [15,17]. The Laplace transform of function \( f(t) \) is given as [20,21]:

\[
\mathcal{F}(s) = \int_0^t f(t)e^{-st}dt
\]  

(4)

where the overbar “.̄” denotes functions in Laplace space, and \( s \) is Laplace transform variable.

Based on the average fluid temperature equations (Equations (A6) and (A7)) of the two legs, we can obtain the following equations for characterizing the heat rates of the descending leg and the ascending leg:

\[
\bar{q}_f1 - \bar{q}_f2 = \left(1 + \frac{s\omega_f\alpha}{\alpha}\right)(\bar{T}_f1 - \bar{T}_f2)
\]  

(5)

\[
\bar{q}_f1 + \bar{q}_f2 = \left(1 + \frac{s\omega_f\beta}{\beta}\right)(\bar{T}_f1 + \bar{T}_f2)
\]  

(6)

where \( s \) is the Laplace variable and \( \omega_f \) is the fluid thermal storage coefficient. The coefficients \( \alpha \) and \( \beta \) are defined as:

\[
\left\{ \begin{array}{l}
\alpha = s\bar{T}_{u11} - s\bar{T}_{u12} + \frac{R_i}{H} \\
\beta = s\bar{T}_{u11} + s\bar{T}_{u12} + \frac{R_i}{H}
\end{array} \right.
\]  

(7)

Substituting Equation (A12) into Equation (5), we can obtain the heat rate difference between the two legs:

\[
\bar{q}_f1 - \bar{q}_f2 = \frac{q_G}{s} \left(1 + \frac{s\omega_f\alpha}{2\alpha}\right)
\]  

(8)

With the aid of Equation (3), the heat rates for the descending and ascending legs can be written as:

\[
\begin{align*}
\bar{q}_f1 &= \frac{q_G}{s} \left(1 + \frac{1}{\bar{c}_f\omega_f} \frac{1 + s\omega_f\alpha}{2\alpha}\right) \\
\bar{q}_f2 &= \frac{q_G}{s} \left(1 - \frac{1}{\bar{c}_f\omega_f} \frac{1 + s\omega_f\alpha}{2\alpha}\right)
\end{align*}
\]  

(9)

Substituting the heat rates Equation (9) and Equation (8) into Equation (A13), we can readily obtain the average fluid temperature of the GHE:

\[
\bar{T}_f = \frac{\bar{T}_{in} + \bar{T}_{out}}{2} = \frac{q_G}{2s} \left(\frac{\beta}{1 + s\omega_f\beta} + \frac{1}{4(\bar{c}_f\omega_f)^2} \frac{1 + s\omega_f\alpha}{\alpha}\right)
\]  

(10)

Although the above solutions are formulated in Laplace-domain, we can easily obtain the time-domain solutions with the Stehfest numerical inversion method [22].

### 3. Results and Discussion

#### 3.1. Model Verification

Beier [23] obtained reference data from a sandbox experiment which can be used to verify the developed heat transfer model. Moreover, this proposed model is validated against the analytical
method from Li et al. [18], as well as the numerical model from Yang et al. [5]. The values of the
Parameters of the sandbox experiment are listed in Table 1.

| Parameters                                | Symbol | Value                |
|-------------------------------------------|--------|----------------------|
| Initial ground temperature                | $T_0$  | 22 °C                |
| Borehole radius                           | $r_b$  | 0.063 m              |
| Length of borehole                        | $H$    | 18.3 m               |
| Outer radius of U-tube                    | $r_{po}$ | 0.0167 m           |
| Inner radius of U-tube                    | $r_{pi}$ | 0.013665 m       |
| Distance between centers of pipe          | $2D$   | 0.053 m              |
| Thermal conductivity of pipe              | $\lambda_p$ | 0.39 W/(K⋅m) |
| Thermal conductivity of soil              | $\lambda_s$ | 2.82 W/(K⋅m) |
| Volumetric heat capacity of soil          | $c_s$  | $3.2 \times 10^6$ J/(K⋅m$^3$) |
| Thermal conductivity of grout             | $\lambda_g$ | 0.73 W/(K⋅m) |
| Volumetric heat capacity of grout         | $c_g$  | $3.8 \times 10^6$ J/(K⋅m$^3$) |
| Volumetric heat capacity of the fluid     | $c_f$  | $4.19 \times 10^6$ J/(K⋅m$^3$) |
| GHE heat rate                             | $q_G$  | 1053 W               |
| Fluid volumetric flow rate                | $w_f$  | 0.197 L/s            |

Figure 2 presents the comparison between the results of our model and those of the other models, as well as the reference data. It can be observed in this figure, compared with the results of the two existing models, this new model has a better agreement with the reference data during the early period. While for the late period, the results from the new model illustrate a similar trend to those from Li’s model and Yang’s model. Besides, as suggested by Beier et al. [24], the distance between the legs can be a function of depth rather than a constant. As shown in Figure 2, a better agreement can be achieved for the entire test duration with a modified average distance $2D = 6.97 \times 10^{-2}$ m. Therefore, the excellent agreements imply that this proposed model is reliable for simulating the thermal behavior of the single U-tubes.

![Figure 2](image_url)

Figure 2. Comparisons of the average fluid temperatures between the results of the proposed model and those of Li’s model, Yang’s model, and experimental data.
3.2. Early Thermal Response Analysis

In this section, the effects of fluid thermal storage, fluid flow rate, and the distance between the two legs are examined with the new composite-medium line source model. The benchmark values of the parameters are listed in Table 2.

Table 2. Benchmark values of the parameters of GHE with a single U-tube.

| Parameters                        | Symbol | Value       |
|-----------------------------------|--------|-------------|
| Initial ground temperature        | $T_0$  | 18 $^\circ$C|
| Borehole radius                   | $r_b$  | 0.75 m      |
| Length of borehole                | $H$    | 120 m       |
| Outer radius of U-tube            | $r_{po}$ | 0.016 m    |
| Inner radius of U-tube            | $r_{pi}$ | 0.013 m    |
| Distance between centers of pipe  | $2D$   | 0.050 m     |
| Thermal conductivity of pipe      | $\lambda_p$ | 0.4 W/(K m) |
| Thermal conductivity of soil      | $\lambda_s$ | 1.5 W/(K m) |
| Volumetric heat capacity of soil  | $c_s$  | $2 \times 10^6$ J/(K m$^3$) |
| Thermal conductivity of grout     | $\lambda_g$ | 0.9 W/(K m) |
| Volumetric heat capacity of grout | $c_g$  | $2 \times 10^6$ J/(K m$^3$) |
| Volumetric heat capacity of the fluid | $c_f$    | $4.19 \times 10^6$ J/(K m$^3$) |
| GHE heat rate                     | $q_G$  | 6000 W      |
| Fluid volumetric flow rate        | $w_f$  | $2.5 \times 10^{-7}$ m$^3$/s |

3.2.1. Effect of Fluid Thermal Storage

Figure 3 compares the calculated temperature and heat ratio that consider the fluid thermal storage to the calculated temperature and heat ratio that neglect the fluid thermal storage. As shown in Figure 3a, the fluid thermal storage mainly exhibits its influence at the early time. The calculated temperature that considers fluid thermal storage is lower than that of those neglecting the fluid thermal storage. The difference between the two temperature plots becomes more pronounced at the early time. This is because the heat rate mainly contributes to the temperature promotion of the fluid inside the tube at the early stage. As time proceeds, the effect of fluid thermal storage fades.

![Figure 3. Thermal response plots calculated with the proposed model with different $\omega_f$: (a) average temperature of the fluid; and (b) ratio of the heat rate of the descending leg.](image)

Figure 3b presents the ratio of the heat rate of the descending leg to the total heat rate. As one can see in this figure, the heat rates of the two legs are different. The heat ratio is larger than 0.5 throughout the entire simulation period, which indicates that the heat rate of the descending leg is higher than that of the ascending leg. The value of the ratio decreases and it approaches a constant value in the...
late period. In addition, it can be found that the difference between these two plots is negligible, which implies that the fluid thermal storage exerts a slight effect on the heat rate distribution.

3.2.2. Effect of Fluid Flow Rate

Figure 4 presents the effect of flow rate on the thermal behavior of a single U-tube. In Figure 4a, the difference between the average temperature with different flow rates is not significant during the late period. A more noticeable difference can be observed during the early period. This is because the second term in Equation (10) is very sensitive to the flow rate, which is reciprocal to the square flow rate. In Figure 4b, one can see that the flow rate can significantly influence the heat rate distribution between these two legs. As shown in Figure 4b, with a higher flow rate, the descending leg will contribute less to the GHE and the change of ratio is less significant on each plot.

![Figure 4. Thermal response plots of the U-tube with different flow rates: (a) average temperature of the fluid; and (b) ratio of the heat rate of the descending leg.](image)

3.2.3. Effect of Distance between the Two Legs

The distance between the two legs can affect the thermal behavior of the GHEs. Three typical cases [12] for different distances between the center of the two legs are studied with the new composite-medium line source model. Figure 5 presents the calculated results of the three cases with the proposed model. In Figure 5, one can see that the distance between the two legs has a negligible effect during the early time when the fluid thermal storage effect dominates. However, the differences become significant at late simulation time. Since a smaller distance between the two legs can lead to a higher thermal interference, the fluid temperature is decreased as the case is varied from A to C. This implies the two legs should be installed as far as possible to reduce the thermal interference between two legs.
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Nomenclature

- 2D: Distance between centers of pipe, m
- H: Length of borehole, m
- t: time, s
- s: Laplace variable with respect to time t
- \( \bar{s} \): Laplace variable with respect to dimensionless time \( tD \)
- r: radius or radial distance, m
- R: thermal resistance, m·K/W
Appendix A. Composite-Medium Line Source Model for Ground Heat Exchangers with a Single U-Tube

Appendix A.1. The Average Temperature of the Fluid Inside the Two Legs

In the new analytical models, the two legs of the single U-tube are treated as two separate infinite line sources in the composite medium. The interference between the two legs can be described with the superposition principle. In order to account for the fluid thermal storage and heat rate difference between the two legs, the heat rates $q_{f1}$ and $q_{f2}$ are not constant. Therefore, the fluid temperatures $T_{fi}$ inside the two legs should be written in the following convolution form

$$ T_{fi}(t) = \int_0^t q_{p1}(\tau) \cdot \frac{dT_{u1}}{dT}(t-\tau)d\tau + \int_0^t q_{p2}(\tau) \cdot \frac{dT_{u2}}{dT}(t-\tau)d\tau + q_{pi}(t) \cdot R_t, \quad i = 1, 2 \quad (A1) $$

where $T_u$ is the temperature response with respect to the composite-medium line source model. Subscript “ij” denotes the effect of $i$-th to the $j$-th leg. The thermal resistance $R_t$ inside the tube can be written as:

$$ R_t = R_{tp} + R_{th} \quad (A2) $$

where $R_{tp}$ is the conductivity thermal resistance of pipe, $R_{th}$ denotes the convective thermal resistance between the fluid and pipe wall. Beier and Smith [15] presented detailed algorithms for calculating $R_{tp}$ and $R_{th}$. In the Laplace domain, Equation (A1) with convolution, integrals can be rewritten as:

$$ T_{fi}(s) = \tilde{q}_{p1}(s) \cdot sT_{u1}(s) + \tilde{q}_{p2}(s) \cdot sT_{u2}(s) + \tilde{q}_{pi}(s) \cdot \frac{R_t}{\Pi}, \quad i = 1, 2 \quad (A3) $$

Furthermore, the heat rates of the pipe walls are given as:

$$ q_{pi} = q_{fi} - \omega_f \cdot dT_{fi} / dt \quad (A4) $$
Considering the fluid thermal storage coefficient:

$$\omega_f = \pi r^2 H \cdot c_f$$  \hspace{1cm} (A5) \]

Transforming Equation (A4) into Laplace space and substituting it into (A3) we can obtain fluid temperature equations. For the descending leg we can have:

$$\left[1 + s \omega_f \left(s T_{in1} + \frac{R_i}{H}\right)\right] T_{f1} + s \omega_f s T_{u12} T_{f2} = \bar{q}_{f1} \bar{s} T_{in1} + \bar{q}_{f2} T_{u12} + \bar{q}_{f1} \frac{R_i}{H}$$  \hspace{1cm} (A6) \]

For the ascending leg, we can have:

$$s \omega_f s T_{u12} T_{f1} + \left[1 + s \omega_f \left(s T_{in1} + \frac{R_i}{H}\right)\right] T_{f2} = \bar{q}_{f1} \bar{s} T_{u12} T_{f1} + \bar{q}_{f2} T_{in1} + \bar{q}_{f2} \frac{R_i}{H}$$  \hspace{1cm} (A7) \]

In addition, with the infinite line source assumption, the average fluid temperatures for the two legs can be written as

$$\begin{cases} T_{f1} = \frac{T_{in} - T_{out}}{2} \\ T_{f2} = \frac{T_{in} - T_{out}}{2} \end{cases}$$  \hspace{1cm} (A8) \]

**Appendix A.2. Equations of Inlet and Outlet Fluid Temperature**

According to the conservation law, we can have the following equations of inlet and outlet fluid temperature. For the GHE:

$$c_f w_f (T_{in} - T_{out}) = q_c$$  \hspace{1cm} (A9) \]

for the descending leg:

$$c_f w_f (T_{in} - T_{out}) = q_{f1}$$  \hspace{1cm} (A10) \]

for the ascending leg:

$$c_f w_f (T_{out} - T_{in}) = q_{f2}$$  \hspace{1cm} (A11) \]

Combined Equation (A8) with Equations (A10) and (A11), we can obtain following average fluid temperature equation:

$$T_f = \frac{T_{in} - T_{out}}{2} = \frac{T_{f1} + T_{f2}}{2} + \frac{q_{f1} - q_{f2}}{4c_f w_f}$$  \hspace{1cm} (A12) \]

**Appendix B. Temperature Response Function in a Composite Medium**

Figure A1 shows an infinite composite cylinder consisting of two regions with depth H, the inner region \(r < r_b\) with \(\lambda_1\) and \(c_1\), and the outer region \(r > r_b\) with \(\lambda_2\) and \(c_2\). The initial temperature of the medium is 0 °C. An infinite line source of heat is located at \((r_b, \theta_b)\), where \(r < r_b\) and continuously releases heat into the composite medium from \(t = 0\). Chen and Raghavan [25] provided an analogous pressure response functions for oil well in an infinite composite medium. The Laplace transformation of the temperature responses at a point \((r, \theta)\) located in the inner and outer regions are given by Equations (A13) and (A14), respectively.

![Figure A1](image_url)  
**Figure A1.** Schematic layout of a line source positioned in an infinite composite medium.
For $0 < r \leq r_b$,

$$
T_{a1}(\tilde{s}, \theta, r_D) = \frac{1}{s} \sum_{n=1}^{\infty} \frac{B_n}{s^{n \lambda_1}} K_0(s \sqrt{\frac{\tilde{S}}{\lambda_D}}) I_0(s \sqrt{\frac{\tilde{S}}{\lambda_D}}) - 2 \sum_{n=1}^{\infty} B_n(r_D \sqrt{\frac{\tilde{S}}{\lambda_D}}) I_n(s \sqrt{\frac{\tilde{S}}{\lambda_D}}) \cos(n(\theta - \theta_b))
$$

(A13)

For $r > r_b$,

$$
T_{a2}(\tilde{s}, \theta, r_D) = \frac{1}{s} \sum_{n=1}^{\infty} \frac{B_n}{s^{n \lambda_1}} K_0(r_D \sqrt{\tilde{S}}) I_0(r_D \sqrt{\tilde{S}}) + 2 \sum_{n=1}^{\infty} B_n(r_D \sqrt{\tilde{S}}) I_n(r_D \sqrt{\tilde{S}}) \cos(n(\theta - \theta_b))
$$

(A14)

where

$$\begin{align*}
A_n &= \sqrt{\frac{c_D}{\lambda_D}} K_n(r_D \sqrt{\tilde{S}}) I_n(s \sqrt{\frac{\tilde{S}}{\lambda_D}}) - \frac{1}{n} K_n(r_D \sqrt{\frac{\tilde{S}}{\lambda_D}}) K'_n(r_D \sqrt{\tilde{S}}) \\
B_n &= \sqrt{\frac{c_D}{\lambda_D}} K_n(r_D \sqrt{\tilde{S}}) I'_n(s \sqrt{\frac{\tilde{S}}{\lambda_D}}) - I_n(s \sqrt{\frac{\tilde{S}}{\lambda_D}}) K'_n(r_D \sqrt{\tilde{S}}) \\
E_n &= \sqrt{\frac{c_D}{\lambda_D}} K_n(r_D \sqrt{\tilde{S}}) I'_n(s \sqrt{\frac{\tilde{S}}{\lambda_D}}) - I_n(s \sqrt{\frac{\tilde{S}}{\lambda_D}}) K'_n(r_D \sqrt{\tilde{S}})
\end{align*}$$

(A15) (A16) (A17)

and the dimensionless parameters as defined as:

$$\lambda_D = \frac{\lambda_1}{\lambda_2}, \quad c_D = \frac{c_1}{c_2}, \quad r_D = \frac{r}{r_{po}}, \quad r_D = \frac{r_b}{r_{po}}, \quad r_D = \frac{r_b}{r_{po}}, \quad S_D = \frac{S}{r_{po}}$$

In Equations (A13)–(A17), $\tilde{s}$ is the Laplace variable with respect to dimensionless time $t_D$,

$$t_D = \frac{\lambda_2}{c_2 r_{po}}$$

(A19)

The subscripts 1 and 2 denote inner regions ($r < r_b$) and outer regions ($r > r_b$); $I_n$ and $K_n$ are the modified Bessel functions of the $n$th order of the first and second kinds, respectively. The symbol $'$ denotes derivatives. The modified Bessel functions have following equations,

$$K_{n-1}(z) = -(2n/z) K_n(z) + K_{n+1}(z)$$

(A20)

$$I_{n-1}(z) = (2n/z) I_n(z) + I_{n+1}(z)$$

(A21)

Therefore, the functions $K_n(z)$ and $I_n(z)$ are computed recursively after computing $K_0(z), K_1(z), I_0(z)$ and $I_1(z)$. Moreover, their derivatives can be calculated with the following equations,

$$K'_{n} = -\frac{K_{n-1} + K_{n+1}}{2}, \quad K_{-n} = K_n$$

(A22)

$$I'_{n} = \frac{I_{n-1} + I_{n+1}}{2}, \quad I_{-n} = I_n$$

(A23)

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