Coarse-graining two-dimensional turbulence via dynamical optimization

Bruce Turkington, Qian-Yong Chen and Simon Thalabard

Department of Mathematics and Statistics, University of Massachusetts, Amherst, MA 01003, USA

E-mail: turk@math.umass.edu

Received 16 September 2015, revised 12 June 2016
Accepted for publication 25 July 2016
Published 17 August 2016

Recommended by Dr Keith A Julien

Abstract
A model reduction technique based on an optimization principle is employed to coarse-grain inviscid, incompressible fluid dynamics in two dimensions. In this reduction the spectrally-truncated vorticity equation defines the microdynamics, while the macroscopic state space consists of quasi-equilibrium trial probability densities on the microscopic phase space, which are parameterized by the means and variances of the low modes of the vorticity. A macroscopic path therefore represents a coarse-grained approximation to the evolution of a nonequilibrium ensemble of microscopic solutions. Closure in terms of the vector of resolved variables, namely, the means and variances of the low modes, is achieved by minimizing over all feasible paths the time integral of their mean-squared residual with respect to the Liouville equation. The equations governing the optimal path are deduced from Hamilton–Jacobi theory. The coarse-grained dynamics derived by this optimization technique contains a scale-dependent eddy viscosity, modified nonlinear interactions between the low mode means, and a nonlinear coupling between the mean and variance of each low mode. The predictive skill of this optimal closure is validated quantitatively by comparing it against direct numerical simulations. These tests show that good agreement is achieved without adjusting any closure parameters.

Keywords: model reduction, turbulence closure, nonequilibrium statistical mechanics, Hamilton–Jacobi theory
Mathematics Subject Classification numbers: 76F55, 82C05, 49L99

(Some figures may appear in colour only in the online journal)
1. Introduction

The phenomenology of two-dimensional turbulence has been extensively studied in many numerical simulations and physical experiments [4, 20, 25, 38]. At high Reynolds number, free-decaying turbulence in two dimensions exhibits both the emergence of coherent structures on large scales and the development of vorticity fluctuations on small scales. This generic behavior is consistent with the conceptual picture of the dual cascade for forced, two-dimensional turbulence, in which energy fluxes toward low wavenumbers while enstrophy fluxes toward high wavenumbers. In either the free-decaying or forced scenarios, there is significant dynamical interaction between the large and small scales—coherent vortices emerge out of a background of vorticity fluctuations, while vortex coalescence expels filamentary vorticity into the vicinity. As is well known, this typical behavior of two-dimensional flow is shared by the important asymptotic models of geophysical fluid dynamics, notably, quasi-geostrophic flow [5, 24, 30, 37, 41]. Indeed, the geophysical equations are perhaps even more interesting from this point of view, since their Reynolds numbers are huge, and the effects of a nonzero Coriolis gradient or a nontrivial bottom topography introduces spatial inhomogeneities into the dynamics and consequent organization of the mean flow.

From the perspective of both theoretical understanding and practical applications, therefore, it is highly desirable to develop a methodology for modeling the evolution of the coherent part of a two-dimensional, or quasi-geostrophic, flow without resorting to full simulation of all its active scales of motion. Moreover, greater insight into behavior of such a complex system is gained from ensemble-averaged, coarse-grained descriptions than from the full integration of its chaotic dynamics [16]. Briefly put, one seeks a robust closure model for the low wavenumber behavior. Of course, turbulence closures have a long history, beginning with Reynolds’ identification of the effective stress due to fluctuations, followed by Boussinesq’s concept of eddy viscosity and Prandtl’s mixing length [32]. Nowadays there are numerous semi-empirical models of the effect of the small-scale eddies on the large-scale flow, which represent the dissipation due to subgrid-scale motion via effective viscosities [26]. In the classic Smagorinsky model the turbulent viscosity depends on the grid scale and the gradients of the mean flow, while in more refined theories eddy viscosities may also include estimates of the subgrid-scale kinetic energy or energy dissipation.

The usefulness of these phenomenological models has stimulated numerous efforts to derive them as statistical-mechanical reductions of the underlying fluid dynamics [25, 27, 33, 34, 42]. This historical development has been dominated by the issue of terminating the hierarchy of equations for the successively higher moments generated by the quadratic nonlinearity of hydrodynamics. Seemingly natural closure hypotheses, such as the quasi-normal approximation for the fourth-order moments, have long ago been known to be unrealizable, resulting in recourse to eddy damping and markovianization, with the attendant empirically fit parameters and heuristic arguments [34]. Even though great efforts have been made in this line of investigation, a statistical theory of turbulence remains a challenging open problem. Nonetheless, this body of knowledge supports the notion that a closure involves some generalized notion of eddy viscosity, which may vary with the resolution scale and may depend nonlinearly on various resolved quantities, such as the mean flow or turbulent kinetic energy [19].

Unlike much of the general theory of turbulent flows, which tends to focus on homogeneous turbulence, the primary concern of two-dimensional and quasi-geostrophic turbulence is to model spatially inhomogeneous or anisotropic flows. Some fundamental work has included inhomogeneity as a key feature of statistical closures of two-dimensional flows [14]. Moreover, some of the main difficulties of moment-closures can be avoided in flow regimes relevant to geophysical applications, because the linear dynamics of waves is dominant and
nonlinear interactions are primarily between eddies and the mean flow [8, 13]. Stochastic parameterization of eddy–eddy interactions forms the basis for a closure at second order for inhomogeneous, quasi-geostrophic turbulence that captures many of the salient features of low-wavenumber flow behavior [31]. Conceptually, this approach follows the traditional method of terminating the hierarchy of moments in order to obtain a direct statistical simulation of the coarse-grained state.

In this paper we develop a different approach to turbulence closure in the context of two-dimensional, incompressible, inviscid fluid flow. Our goal is to derive closed reduced equations for the statistics of a coarse-grained vorticity field directly from the underlying fluid dynamics without generating and terminating a moment hierarchy. To do so we combine some basic principles in nonequilibrium statistical mechanics with an alternative model reduction technique developed by one of the authors in a general setting of finite-dimensional Hamiltonian systems [40]. For the underlying microscopic dynamics we adopt a spectral truncation of ideal vorticity transport equation; specifically, the Fourier–Galerkin truncation of ideal flow on a two-dimensional torus, $x = (x_1, x_2) \in [0, 2\pi]^2$, using modal wavevectors $k = (k_1, k_2)$ with $k_1, k_2 = 0, \pm 1, \ldots, \pm n$, for $n \gg 1$. In this sense our work is conceptually aligned with recent work on the inviscid Burgers equation [1, 28, 29] and three-dimensional Euler dynamics [7, 21], which investigate the turbulent behavior and thermalization of truncated conservative systems. The coarse-grained description retains only the low wavenumber modes, having $-m \leq k_1, k_2 \leq m$, for a fixed $m \ll n$, and reduction is achieved by imposing a quasi-equilibrium statistical model, in which the means and variances of the low modes are the resolved variables, while the unresolved modes have equilibrium statistics determined by energy and enstrophy conservation.

Rather than proceeding along the traditional lines of closing a hierarchy of moments, our reduction method characterizes that coarse-grained macrodynamics which is optimally compatible with the fully-resolved microdynamics. Optimality is quantified by minimizing a cost functional over paths of macrostates, the cost being an information loss rate incurred by reduction from the full deterministic dynamics to the reduced statistical model. The closed reduced equations derived from this optimization principle have a generic thermodynamical structure, in which the reversible and irreversible parts of the reduced equations are separately identified, and the optimal cost of reduction is related to entropy production [35]. These properties give the optimal closure a clear physical interpretation and a natural mathematical structure.

The choice of quasi-equilibrium probability densities in the optimization principle makes a systematic derivation of an optimal closure feasible. With respect to these statistical states all modes are uncorrelated and Gaussian, properties shared by the well-studied canonical statistical equilibria for the truncated two-dimensional Euler equations [20]. Statistical models based on these distributions and their refinements have been shown to describe the long-time, large-scale organization of two-dimensional, and especially quasi-geostrophic, turbulence [5, 30, 37, 41]. Besides tractability, the justification for using quasi-equilibrium densities relies on the rapid relaxation of the unresolved modes to equilibrium, and the near-normality of the resolved modes. Since simulations and observations of two-dimensional turbulence show some non-normality in the higher modes of vorticity as well as no sharp separation in time scales between a set of low modes and the remaining higher modes, we necessarily introduce some error in our closure by choosing these convenient trial probability densities. Our optimization principle produces the best closure that can be obtained under these simplifications.

The present paper is closely related to recent work by Kleeman and one of the authors on the truncated inviscid Burgers equation [18], a prototype having a hydrodynamical nonlinearity and exhibiting chaotic and mixing dynamics. The general model reduction technique developed in [40] is applied to the low modes of this system, and a closure in terms of their
means is obtained. The reduced model predicts that the decay rate of the resolved mode with wavenumber $k$ scales as $|k| \sqrt{ \log |k| }$, a prediction that matches the scaling observed in direct numerical simulations. Moreover, the reduced equations include modifications to the quadratic nonlinearity in the Burgers equation involving a nonlocal bilinear operator acting on the mean resolved modes.

In the context of two-dimensional turbulence, our optimal closure predicts that the rates of the decay to equilibrium of the means and variance perturbations scale with $k \log |k|$, where $k = (k_1, k_2)$ is the wavevector and $|k| = \sqrt{k_1^2 + k_2^2}$. Thus, within the quasi-equilibrium model in which the the unresolved modes have equilibrium statistics, the dissipative mechanism acting on the coarse-grained flow is found to be a particular, scale-dependent, eddy viscosity. In addition, the optimal coarse-grained dynamics has two novel nonlinearities: (1) modifications to the interactions between resolved modes resulting from the collective effect of interactions via unresolved modes; and (2) a dynamical coupling between the mean and variance of each mode. Most significantly, this optimal closure is found to be universal and intrinsic in the sense that it contains no adjustable parameters.

Our dynamically optimal Gaussian closure is developed in sections 2 through 5. The quasi-equilibrium statistical model is defined in section 2, and then in section 3 the optimization principle over paths is articulated. Section 4 explains how Hamilton–Jacobi theory produces the equations governing optimal paths. Section 5 completes the derivation of the closure by solving the Hamilton–Jacobi equation approximately using a near-equilibrium perturbation analysis. This development pertains to arbitrary truncation wavenumbers, $m$ and $n$, for the macroscopic and microscopic descriptions, respectively, provided that $m \ll n$. In section 6 the model equations are validated numerically against direct simulations of ensembles propagated by the fully-resolved dynamics. To ensure statistical convergence, this comparison is conducted on very large ensembles of a modestly truncated system, for which $m = 4$ and $n = 32$; this coarse-graining projects $2112$ degrees of freedom onto $40$ resolved modes. The magnitude of the relative error incurred by the optimal closure, and its dependence on the amplitude of the nonequilibrium initial state, are revealed at this resolution. Benchmarking the model against direct statistical solutions on resolutions typical in fluid dynamics, where $m$ and $n$ are much larger, is not attempted here due to the computational cost. Nonetheless, our test results suggest that the predictive skill of the optimal closure would be comparable at higher resolution.

2. Dynamics and statistics

We study the dynamics of ideal flow in $\mathbb{R}^2$, for which the continuum governing equations are

$$
\frac{\partial u}{\partial t} + u \cdot \nabla u = -\nabla p, \quad \nabla \cdot u = 0.
$$

This dynamics is most conveniently represented in terms of the vorticity field, $\zeta = \zeta(x,t)$, and the streamfunction $\psi = \psi(x,t)$, for which

$$
\zeta = \frac{\partial u_2}{\partial x_1} - \frac{\partial u_1}{\partial x_2}, \quad u = \left( \frac{\partial \psi}{\partial x_2} - \frac{\partial \psi}{\partial x_1} \right).
$$

Then (1) is equivalent to the pair of scalar equations

$$
\frac{\partial \zeta}{\partial t} + [ \zeta, \psi ] = 0, \quad -\Delta \psi = \zeta,
$$

(2)
where \([\phi, \psi] = \partial \phi / \partial x_1 \partial \psi / \partial x_2 - \partial \phi / \partial x_2 \partial \psi / \partial x_1\) denotes the Poisson bracket of scalar fields on \(\mathbb{R}^2\).

In our investigations we consider doubly-periodic boundary conditions in the space variable \(x = (x_1, x_2)\). Normalizing the periods we assume that \(\zeta\) and \(\psi\) are \(2\pi\)-periodic in \(x_1\) and \(x_2\), and we write \(x \in \mathbb{T}^2 = [0, 2\pi)^2\), the two-dimensional torus. Under these conditions it is necessary that

\[
\int_{\mathbb{T}^2} \zeta \, dx = \int_{\mathbb{T}^2} u \cdot dx = 0.
\]

We seek a coarse-graining of the dynamics (1), in which the small scales of motion, or the fine-grained fluctuations in vorticity, are represented by a dynamically consistent, statistical model. The methods of statistical mechanics that we shall use are applicable to dynamical systems with a large, but finite, number of degrees of freedom. We therefore replace the continuum dynamics (1) by its Fourier–Galerkin truncation. Any doubly-periodic solution \(\zeta\) of (2) is represented in terms of its complex Fourier coefficients

\[
\z_k = z_k(t) = \frac{1}{(2\pi)^2} \int_{\mathbb{T}^2} \zeta(x, t) e^{-ik \cdot x} \, dx \in \mathbb{C},
\]

for wavevectors \(k = (k_1, k_2) \in \mathbb{Z}^2\), with \(z(0,0) = 0\). Truncation is imposed for \(|k_1|, |k_2| \leq n\), for a fixed cut-off wavenumber \(n \gg 1\). The vorticity field is then

\[
\zeta(x, t) = \sum_{k \in \mathbb{K}_n} z_k(t) e^{ik \cdot x},
\]

where this sum (and others to follow) extends over the lattice of nonzero wavevectors

\[
\mathbb{K}_n = \{k = (k_1, k_2) \in \mathbb{Z}^2 : k_1, k_2 = 0, \pm 1, \ldots, \pm n, \ k \neq (0, 0)\}.
\]

Since \(\zeta\) is real-valued, \(z_k = z_k^*\) (star denotes complex conjugate). Hence we may consider the microstate \(z\) to be a point in the phase space \(\Gamma_n = \mathbb{C}^d\), having \(d_n = [(2n + 1)^2 - 1]/2 = 2n(n + 1)\) degrees of freedom. The independent components of \(z \in \Gamma_n\) correspond to wavevectors belonging to half of the lattice, \(\mathbb{K}_n\), which may be partitioned into equal halves, \(\mathbb{K}_n = \mathbb{K}_n^+ \cup \mathbb{K}_n^-\), with \(\mathbb{K}_n^- = -\mathbb{K}_n^+\) in many ways. For convenience we shall continue to write \(z = (z_k)\) for \(k \in \mathbb{K}_n\) for a microstate, understanding that only half of these variables are independent.

By applying the identity \([e^{ip \cdot x}, e^{iq \cdot x}] = -(p \times q) e^{ip \cdot q + q \cdot x}\), where \(p \times q \neq p_1q_2 - p_2q_1\), for any wavevectors \(p, q \in \mathbb{K}_n\) and using that the 4th Fourier coefficient of \(\psi\) is \(|k|^{-2}z_k\), the continuum equation (2) project onto the identities

\[
\sum_{k \in \mathbb{K}_n} \left[ \frac{dz_k}{dt} - \sum_{p+q-k} \frac{p \times q}{|q|^2} z_{p+q} e^{ik \cdot x} \right] e^{ik \cdot x} = 0, \quad \text{for all} \quad k \in \mathbb{K}_n.
\]

The spectrally truncated microdynamics on the phase space \(\Gamma_n\) is therefore governed by the system of ordinary differential equations

\[
\frac{dz_k}{dt} + \sum_{p+q-k} c(p, q) z_{p+q} = 0 \quad (k, p, q \in \mathbb{K}_n),
\]

where we introduce the symmetrized interaction coefficients

\[
c(p, q) \equiv \frac{1}{2} (p \times q) \left( \frac{1}{|p|^2} - \frac{1}{|q|^2} \right) = c(q, p) \quad (p, q \in \mathbb{K}_n).
\]
These coefficients are real, and \( c(-p, q) = c(p, -q) = -c(p, q) \). This symmetrized form of the microdynamics is convenient in many of the subsequent calculations and hence will be employed throughout the sequel.

The dynamics (4) conserves both energy and enstrophy, respectively,

\[
H(z) = \frac{1}{2} \sum_{k \in K_n} |k|^{-2} |z_k|^2,
\]

\[
Z(z) = \frac{1}{2} \sum_{k \in K_n} |z_k|^2.
\]

The invariance of \( H \) and \( Z \) are consequences, respectively, of the two identities

\[
c(p, q)|k|^{-2} = c(q, k)|p|^{-2} + c(k, p)|q|^{-2}, \quad c(p, q) = c(q, k) + c(k, p).
\]

Though we will refer to \( Z \) as the enstrophy, it is actually the quadratic enstrophy. For the continuum dynamics there are infinitely many independent enstrophy integrals, \( Z_f = \int f(\zeta) \, dx \), for any (regular) real function \( f \) on the (invariant) range of the vorticity field. But only the quadratic entropy (7) survives Fourier modal truncation as an exact invariant [20, 25, 30].

The Liouville theorem holds for the (noncanonical Hamiltonian) dynamics (4); that is, the phase volume \( \pi \) is dynamically invariant under the phase flow [20, 25]. Among the equilibrium statistical distributions on \( \Gamma_n \) determined by the energy and enstrophy invariants is the canonical probability density

\[
\rho_{eq}(z) = \exp(-\beta Z - \theta H - \Phi(\beta, \theta)),
\]

where

\[
\Phi(\beta, \theta) = \log \int_{\Gamma_n} \exp(-\beta Z - \theta H) \, dz.
\]

The parameters \( \beta \) and \( \theta \) conjugate to mean enstrophy and energy, respectively, are required to satisfy \( \beta > 0 \) and \( \theta > -\beta \), so that \( \beta + \theta |k|^{-2} \) is positive for all \( k \in K_n \). For these admissible values, the Fourier coefficients \( z_k \) are complex Gaussian random variables with first and (isotropic) second moments

\[
\langle z_k \rangle_{eq} = 0, \quad \langle |z_k|^2 \rangle_{eq} = \frac{1}{\beta_k} \quad \text{where} \quad \beta_k = \beta + \theta |k|^{-2}.
\]

The invariance of \( \rho_{eq} \) under the microdynamics (4) is a consequence of the identity

\[
c(p, q)|k|^{-2} = c(q, k)|p|^{-2} + c(k, p)|q|^{-2}, \quad c(p, q) = c(q, k) + c(k, p).
\]

The equilibrium macrostate (9) furnishes the most convenient and natural reference distribution for our nonequilibrium statistical theory. This distribution is not intended to be a realistic representation of developed two-dimensional Navier–Stokes turbulence in either a freely-decaying or forced scenario. Far-from-equilibrium phenomena arising from viscous dissipation, such as cascades, require much more complicated statistical descriptions. In the present paper, we endeavor to coarse-grain the spectrally-truncated, inviscid Euler dynamics, and hence we construct our nonequilibrium distributions from \( \rho_{eq} \), rather than introducing nonequilibrium behavior into the unresolved fluctuations. A more elaborate theory might derive a coarse-grained effective equations for the low modes with respect to a background
of vorticity fluctuations that have a nonequilibrium spectrum. Such a theory is a worthwhile goal for future research.

The nonequilibrium statistics of the full dynamics (4) is exactly represented by the propagation of probability density \( \rho(z, t) \) with respect to \( dz \) under the Liouville equation,

\[
0 = \frac{\partial \rho}{\partial t} + \sum_{k \in K_n} \frac{dx_k}{dt} \frac{\partial \rho}{\partial x_k} + \frac{dy_k}{dt} \frac{\partial \rho}{\partial y_k} = \frac{\partial \rho}{\partial t} + \sum_{k \in K_n} \frac{dz_k}{dt} \frac{\partial \rho}{\partial z_k}.
\]

As is universally recognized throughout statistical mechanics, the complete determination of the evolving density \( \rho(z, t) \) is not feasible or desirable for high-dimensional systems [2, 3, 39, 44]. Indeed, the full complexity of \( \rho(z, t) \) is not needed to approximate the statistics of coarse-grained observables. In this light we contract the solution space of (12) to a space of approximations, which we call trial probability densities and denote by \( \tilde{\rho}(z, t) \). Our reduction employs the Gaussian trial densities

\[
\tilde{\rho}(z; a, b) = \prod_{k \in K_n^+} \frac{b_k}{\pi} e^{-b_k |z_k - a_k|^2},
\]

which are parameterized by \( a_k \in \mathbb{C}, b_k \in (0, \infty) \). That is, we impose a parametric statistical model with independent Gaussian modes, having means and variances

\[
\langle z_k \mid \tilde{\rho}(a, b) \rangle = a_k, \quad \langle |z_k - a_k|^2 \mid \tilde{\rho}(a, b) \rangle = \frac{1}{b_k}.
\]

Throughout the paper the expectation of any observable \( F \) on the phase space \( \Gamma_n \) with respect to a probability density \( \rho \) is denoted by \( \langle F \mid \rho \rangle = \int_{\Gamma_n} F(z) \rho(z) dz \). For convenience in all subsequent expansions over modes, we extend the statistical parameters \( a_k, b_k \) to the entire lattice of wavevectors \( K_n \), by setting \( a_{-k} = a^*_k, b_{-k} = b_k \), for \( k \in K_n^+ \).

We coarse-grain the statistical dynamics by fixing a low wavenumber cutoff, \( m \ll n \), and setting the parameters \( a_k \) and \( b_k \) to equilibrium values for \( \max\{|k|, |k| \} > m \). That is, in the trial densities (13) we put \( a_k = 0 \) and \( b_k = \beta_k = \beta + \theta|k|^2 \) for wavevectors \( k \in K_n \setminus K_m \) of the unresolved modes, and we adopt the parameters \( a_k \) and \( b_k \) for wavevectors \( k \in K_m^+ \) of the low modes as the resolved variables in our reduced model. The equilibrium density, \( \rho_{eq} \), itself belongs to the statistical model and corresponds to \( a_k = 0, b_k = \beta_k \) for all \( k \in K_n \). The trial densities (13) are quasi-equilibrium statistical states in which the low modes are disequilibrated, while the remaining higher modes are equilibrated. These densities may be realized as maximum entropy states, in the sense that \( \tilde{\rho}(z; a, b) \) is the unique solution of the constrained maximization problem:

\[
\max_{\rho} -\langle \log \rho \mid \rho \rangle \quad \text{over} \quad \langle z_k \mid \rho \rangle = a_k, \quad \langle |z_k - a_k|^2 \mid \rho \rangle = \frac{1}{b_k}.
\]

The traditional justification for using quasi-equilibrium states in a nonequilibrium statistical model rests on the supposition that the unresolved modes decorrelate and relax toward equilibrium more rapidly than the resolved modes [43]. In the context of turbulence closure, however, the division between the resolved and unresolved modes does not rest on some wide separation of time scales. Consequently, we expect that our reduced model will entail irreducible errors arising from memory effects as well as errors associated with the Gaussian approximation [16, 44]. In section 6 we test the quality of the quasi-equilibrium assumption against direct numerical simulations of ensembles. It is important, though, to recognize that the simplicity of the trial densities (13) in our optimization principle does not imply that there
are no effective interactions between modes in the resulting closure or that dissipation necessarily vanishes in the reduced dynamics. This crucial property of our optimization-based closure contrasts with moment-hierarchy closure approaches, which would be trivial under such simplified distributions and hence must be based on more elaborate statistical assumptions.

3. Optimal paths

Our interest centers on predicting the evolution of the means and variances of the lowest modes, that is, the statistical parameter vector, \((a_k(t), b_k(t))\), for \(k \in K^+_m\) via a closed dynamics in these resolved variables alone. We do so by considering all admissible paths \((a(t), b(t))\) in the statistical parameter space, \(C^{d_m} \times (0, \infty)^{d_m}\), where \(d_m = 2m(m + 1)\) is the cardinality of the reduced half-lattice \(K^+_m\) of resolved modes. Since our attention is focused on relaxation of a nonequilibrium initial state toward equilibrium, we introduce a cost functional designed to quantify the compatibility of a path of trial densities \(\tilde{\rho}(z; a(t), b(t))\) to the underlying microdynamics, and we minimize the time integral of the cost function over \(t \in [0, \infty)\). The construction of the appropriate cost functional is as follows.

The fundamental statistic associated with an admissible path \((a(t), b(t))\) is its residual with respect to the Liouville equation (12), namely,

\[
R \equiv \left( \frac{\partial}{\partial t} + \sum_{k \in K_m} \frac{d z_k}{d t} \frac{\partial}{\partial z_k} \right) \log \tilde{\rho}(\cdot; a(t), b(t)) = \sum_{k \in K_m} \tilde{a}_k U_k + \frac{1}{2} b_k V_k - U_k' \frac{d z_k}{d t}. \tag{15}
\]

In this expression, \(\tilde{a}_k = d a_k/dt, \tilde{b}_k = d b_k/dt,\) and

\[
\begin{align*}
U_k &= \frac{\partial}{\partial a_k} \log \tilde{\rho}(\cdot; a, b) = b_k (z_k - a_k), \\
V_k &= \frac{\partial}{\partial b_k} \log \tilde{\rho}(\cdot; a, b) = \frac{1}{b_k} - |z_k - a_k|^2.
\end{align*}
\tag{16}
\]

\(dz_k/dt\) is given by the microdynamics (4). For \(k \in K_m\), \(U_k, V_k\) denote the score functions associated with the parametric statistical model [6]. They satisfy \(\langle U_k | \tilde{\rho} \rangle = \langle V_k | \tilde{\rho} \rangle = 0\), and

\[
\begin{align*}
\langle U_k U_k^* \tilde{\rho} \rangle &= b_k \delta_{k,k'}, \\
\langle V_k V_k^* \tilde{\rho} \rangle &= \frac{1}{b_k^2} [ \delta_{k,k'} + \delta_{k,-k'} ], \\
\langle U_k V_{k'} \tilde{\rho} \rangle &= \langle U_{k'} V_k \tilde{\rho} \rangle = 0.
\end{align*}
\tag{17}
\]

We refer to the span of the score functions (16) for \(k \in K^+_m\) as the resolved subspace of \(L^2(\mathbb{R}, \tilde{\rho}(a, b))\). For convenience in the calculations to follow we note that \(U_k = U_k^*\) and \(V_{-k} = V_k\) for all \(k \in K_m\), and we extend \(U_k\) and \(V_k\) to \(k \in K_m \setminus K_m\) consistently with the extension \(a_k = 0, b_k = \beta_k\).

Two interpretations of the function \(R = R(z; a, a, b, b)\) are given in [40]. First, \(R\) represents the rate of information loss due to reduction via the statistical model (13), being the leading term in the local time expansion of the log-likelihood ratio between the evolved trial density and the exactly propagated density. Second, \(R\) satisfies the family of identities

\[
\frac{d}{d t} \langle F | \tilde{\rho}(t) \rangle = \left\langle \frac{dF}{d t} \right| \tilde{\rho}(t) \right\rangle = \langle FR | \tilde{\rho}(t) \rangle,
\]

for all observables \(F\) with \(\partial F/\partial t = 0\); \(dF/dt\) denotes the microscopic dynamics applied to \(F\). Since \(\langle R | \tilde{\rho}(t) \rangle = 0\), the covariance between the observable \(F\) and the Liouville residual
\( R \) quantifies the deficiency of the path of trial densities \( \tilde{\rho}(a(t), b(t)) \) to propagate the expectation of \( F \). Together these properties motivate our choice of the \( L^2(\Gamma_n, \tilde{\rho}(a,b)) \) squared norm of \( R \) as the cost function to measure the loss rate along paths in the reduced model. These concepts are more fully discussed in [17, 40].

The projection of \( R \) onto the resolved space and its complement, the unresolved subspace, defines the natural separation of the reduced dynamics into its reversible and irreversible components [35, 40]. The orthogonal projection of any observable \( F \) in \( L^2(\Gamma_n, \tilde{\rho}) \) with \( (F \mid \tilde{\rho}) = 0 \) onto the resolved subspace spanned by \( U, V \) is denoted by \( P_{a,b} F \); the complementary projection operator onto the unresolved subspace is \( Q_{a,b} = I - P_{a,b} \). The separation of the Liouville residual, \( R \), into its resolved and unresolved components is facilitated by the fact that \( R \) is a linear combination of the functions, \( U_k, V_k \), and the products, \( U_p U_q \), with \( p + q = 0 \), and \( U_p U_q U_k \), with \( p + q = k \). The restrictions on the indexing wavevectors together with the independence of the score functions implies that all these functions are mutually orthogonal (uncorrelated) in \( L^2(\Gamma_n, \tilde{\rho}) \). Thus, it suffices to exhibit \( R \) as the following linear combination:

\[
R = \sum_{k \in K} \left[ a_k + \sum_{p + q = k} c(p, q) a_p a_q \right] U_k + \frac{1}{2} b_k V_k
- \sum_{k \in K} a_k^* \sum_{p + q = k} c(q, k, b_q) + c(k, p, b_p) U_p U_q
+ \frac{1}{3} \sum_{k \in K} \sum_{p + q = k} c(q, p, b_q b_p + c(k, p, b_k b_p) U_p U_q U_k^*.
\tag{18}
\]

In these sums the wavevectors \( p \) and \( q \) run over the entire spectrum \( K_n \).

The calculations leading from (15) to (18) are as follows. The two terms in (15) involving \( a_k \) and \( b_k \) appear in (18) without manipulation. The third term in (15) is calculated by substituting the governing equations (4) into it and then separating the terms which involve single, double and triple products of the score functions; namely,

\[
- \sum_{k \in K} U_k \frac{dV_k}{dt} = \sum_{k \in K} \sum_{p + q = k} c(p, q) \left( a_p + \frac{1}{b_p} U_p \right) \left( a_q + \frac{1}{b_q} U_q \right) U_k
= S_I + S_H + S_{II}.
\tag{19}
\]

where

\[
S_I = \sum_k \sum_{p + q = k} c(p, q) a_p a_q U_k^* = \sum_k \left[ \sum_{p + q = k} c(p, q) a_p a_q \right] U_k,
\]

\[
S_{II} = \sum_k \sum_{p + q = k} c(p, q) \left( \frac{a_p U_q + a_q U_p}{b_q b_p} \right) U_k^* = - \sum_k a_k^* \sum_{p + q = k} \left[ \frac{c(q, k, b_q) + c(k, p, b_p)}{b_q b_p} \right] U_p U_q,
\]

\[
S_{III} = \sum_k \sum_{p + q = k} c(p, q) U_p U_q U_k^* = \frac{1}{3} \sum_k \sum_{p + q = k} \left[ \frac{c(p, q, b_q b_p + c(k, p, b_k b_p) U_p U_q U_k^*}{b_q b_p} \right] U_p U_q U_k^*.
\]

\( S_I \) is a linear combination of \( U_k \) for \( k \in K_m \) and \( k \in K_n \setminus K_m \), and thus involves both resolved and unresolved components. The expression for \( S_{II} \) follows from reindexing and then
symmetrization over wavevector indices. The expression for $S_{III}$ requires only symmetrization over the triply-indexed sum. Both $S_{II}$ and $S_{III}$ consist entirely of unresolved components, since $S_{II}$ is a linear combination of products $U_p U_q$, and $S_{III}$ is a linear combination of the triple produces $U_p U_q U_{k}^*$, for which $p + q = k = 0$.

The cost function for our optimization principle is declared to be

$$\mathcal{L}(a, \dot{a}, b, \dot{b}) = \frac{1}{2} \left( \langle P_{a,b} R(a, \dot{a}, b, \dot{b}) \rangle^2 \right) + \frac{1}{2} \left( \langle W Q_{a,b} R(a, \dot{a}, b, \dot{b}) \rangle^2 \right) \left\langle \bar{\rho}(a, b) \right\rangle. \quad (20)$$

In the unresolved component of this expression we include a weight operator $W$, which is a self-adjoint, linear operator on $L^2(\mathbb{C}^n, \bar{\rho})$ satisfying $WQ = QW$. The unresolved subspace is therefore invariant under $W$, and the effect of $W$ in (20) is to assign weight to the unresolved component of the residual $R$ relative to the resolved component. The weight operator contains all the primitive free parameters in our closure scheme. These primitive weights may be viewed as encoding the influence of the unresolved modes on the resolved modes [40].

The simplest choice is $W = 1$, resulting in a cost function (20) equal to half the $L^2(\mathbb{C}^n, \bar{\rho})$-norm squared of the residual $R$. In [17] Kleeman advocates for this universal choice arguing that then the cost function represents the leading contribution to the relative entropy increment between an exactly propagated density and the evolved trial density over a short time interval. An attractive feature of this choice is that the resulting optimal closure then involves no adjustable parameters.

To test this information-theoretic argument, we consider a class of weight operators $W$, and in section 6, when quantifying the error between model predictions and direct numerical simulations of ensembles, we assess the choice $W = 1$ against best-fit weights within the class. Since the unresolved subspace is spanned by products of the score variables $U_k$, it suffices to define $W$ on these products. A natural choice of the weight operator $W$ is therefore

$$W(U_k) = \lambda_k U_k, \quad W(U_p U_q) = \mu_{p,q} U_p U_q, \quad W(U_p U_q U_{k}^*) = \nu_{p,q} U_p U_q U_{k}^*, \quad (21)$$

using weight factors $\lambda_k$, $\mu_{p,q}$ and $\nu_{p,q}$ that are arbitrary non-negative constants symmetric in their wavevector indices, $p, q \in K_n$ with $p + q = k$. For this class of weight operators the many constants $\lambda_k, \mu_{p,q}$ and $\nu_{p,q}$ are the primitive free parameters in the closure. We remark, however, that even when general weights are retained in the optimal closure theory, there are far fewer adjustable parameters in the ensuing reduced equations, because only certain collective combinations of the primitive weights enter into those equations.

The evaluation of the cost function (20) requires calculating moments up to order 6. The centered variables $U_k$ are Gaussian and uncorrelated, their second moments are given by (17), and all their odd moments vanish. It suffices therefore to calculate

$$\langle U_{k_1} U_{k_2} U_{k_3} U_{k_4}^* | \bar{\rho} \rangle = b_{k_1} b_{k_2} [\delta_{k_1 k_2} \delta_{k_3 k_4} + \delta_{k_1 k_4} \delta_{k_2 k_3}],$$

$$\langle U_{k_1} U_{k_2} U_{k_3} U_{k_4}^* | \bar{\rho} \rangle = b_{k_1} b_{k_2} b_{k_3} [\delta_{k_1 k_3} \delta_{k_2 k_4} \delta_{k_4 k_1} + \text{permutations}]. \quad (22)$$

Using the properties (17) and (22), we obtain the resolved and unresolved components of the cost function (20), respectively,

$$\langle P_{a,b} R^2 | \bar{\rho} \rangle = \sum_{k \in K_n} d_k + \sum_{p+q=k} c(p,q) a_p a_q \left| b_k + \frac{b_{k}^2}{2b_k^2} \right|^2 \quad (23)$$

2970
The optimal closure is defined by minimizing the time integral of the cost function (20) over all macroscopic paths connecting a given initial macrostate at time $t = 0$ to equilibrium as $t \to \infty$; namely,

$$v(a^0, b^0) = \min_{(a(t), b(t)) \in (a^0, b^0)} \int_0^{+\infty} \mathcal{L}(a, \dot{a}, b, \dot{b}) \, dt. \quad (25)$$

The admissible paths $(a(t), b(t)), 0 \leq t < +\infty$, are constrained to start at a given initial non-equilibrium state $a^0, b^0$ at time $t = 0$.

The value function $v(a^0, b^0)$ for the minimization problem (25) measures the total lack-of-fit of the optimal path emanating from the initial conditions $(a^0, b^0)$ that ensures the optimal path tends to equilibrium as $t \to +\infty$; at equilibrium $a_k = 0$ and $b_k = \beta$ for all $k$ and hence the Liouville residual $R$ and its weighted mean square $L$ both vanish. As shown in the general theory paper [40], the value function (25) is intimately related to the entropy production along the optimal path.

4. Closure via Hamilton–Jacobi theory

The closed reduced equations satisfied by the optimal paths for (25) are most effectively derived by invoking Hamilton–Jacobi theory of the calculus of variations [12, 15, 23, 36]. In a more compact form the cost-function (20) is

$$\mathcal{L}(a, \dot{a}, b, \dot{b}) = \sum_{k \in \mathbb{K}_n} |a_k - f_k(a)|^2 b_k + \frac{b_k^2}{2b_k^2} + w(a, b), \quad (26)$$

introducing the shorthand notation

$$f_k(a) = \left( \frac{d}{dt} | \bar{a}(a, b) \right) = - \sum_{p+q=k} c(p, q) a_p a_q, \quad (27)$$

$$w(a, b) = \frac{1}{2} \langle [WQ_{a,b}R]^2 \mid \bar{p} \rangle, \quad (28)$$

where the last expression is given in (24). By analogy to classical mechanics, $\mathcal{L}$ in (26) may be considered a Lagrangian for the reduced dynamics, in which $-w(a, b)$ plays the role of the potential. But in making this analogy, it is essential to restrict the admissible trajectories to be only those which tend to equilibrium $(a, b) = (0, \beta)$ as $t \to +\infty$.

The Legendre transform supplies the Hamiltonian $\mathcal{H}(a, \phi, b, \psi)$ conjugate to $\mathcal{L}(a, \dot{a}, b, \dot{b})$. The conjugate variables are
\[
\phi_k = \frac{\partial \mathcal{L}}{\partial \dot{a}_k} = [\dot{a}_k - f_k(a)]b_k, \quad \psi_k = \frac{\partial \mathcal{L}}{\partial \dot{b}_k} = \frac{\dot{b}_k}{b_k^2},
\]

and the Hamiltonian function is

\[
\mathcal{H}(a, \phi, b, \psi) = \sum_{k \in K_m} \phi_k^* \dot{a}_k + \dot{\phi}_k \phi_k + \psi_k \dot{b}_k - \mathcal{L} = \sum_{k \in K_m} \left| \frac{\phi_k}{b_k} \right|^2 + \phi_k^* f_k(a) + f_k(a) \phi_k + b_k^2 \frac{\psi_k^2}{2} - w(a, b).
\]

In appendix C these expressions are shown to be the appropriate complexifications of the real Legendre transform.

The value function, \( v(a, b) \), defined in (25) is analogous to an action integral, and hence it solves the stationary Hamilton–Jacobi equation,

\[
\mathcal{H}\left(a, -\frac{\partial v}{\partial a}, b, -\frac{\partial v}{\partial b}\right) = 0;
\]

the minus signs in (31) are due to imposing the constraints in (25) on the initial state \((a(0), b(0))\). The value function also satisfies the equilibrium conditions

\[
v(0, \beta) = 0, \quad \frac{\partial v}{\partial a}(0, \beta) = 0, \quad \frac{\partial v}{\partial b}(0, \beta) = 0.
\]

Hamilton–Jacobi theory dictates that along an optimal path \((a(t), b(t))\) the conjugate variables are given by the canonical relations

\[
\phi_k(t) = -\frac{\partial v}{\partial \dot{a}_k}(a(t), b(t)), \quad \psi_k(t) = -\frac{\partial v}{\partial \dot{b}_k}(a(t), b(t))
\]

These relations then close the reduced dynamics along the optimal path in terms of the value function; that is, (29) and (32) combine to form the closed system

\[
\frac{d a_k}{d t} = f_k(a) - \frac{1}{b_k} \frac{\partial v}{\partial \dot{a}_k}(a, b), \quad \frac{d b_k}{d t} = -b_k^2 \frac{\partial v}{\partial \dot{b}_k}(a, b).
\]

The optimal closure (33) is thus completed once the value function \( v(a, b) \) is determined, at least to some suitable approximation. This calculation is the content of the next section.

5. Derivation of the closed reduced equations

5.1 Linear response approximations

Solving the Hamilton–Jacobi equation (31) is difficult in general, especially for a closure potential \( w \) as complicated as that defined by (24) and (28). We therefore resort to a perturbation analysis to obtain approximate solutions \( v(a, b) \) in a neighborhood of statistical equilibrium. Before presenting a full perturbation calculation, it is helpful to consider two simpler cases in which only quadratic terms in the cost function, \( \mathcal{L} \), or equivalently the Hamiltonian, \( \mathcal{H} \), are retained; this approximation leads to dissipative linear equations for the resolved variables, which are valid nearby statistical equilibrium, as in linear irreversible thermodynamics [10]. We first consider the case when \( b_k = \beta_k \) for all \( k \in K_m \) and derive the linear response of the mean amplitudes, \( a_k \) \( (k \in K_m) \). This case represents a further reduction of the general
formulation, in which the variances of the low modes are frozen at their equilibrium values. We then consider the alternate case when $a_k = 0$ for all $k \in K_m$, and derive the linear equations for the relaxation of the normalized perturbations, $\gamma_k = (b_k - \beta_k)/\beta_k$ ($k \in K_m$), of the inverse variances. This case represents the thermalization of the enstrophy spectrum near equilibrium, with vanishing mean vorticity field.

Setting $b_k = \beta_k$ for all $k \in K_m$ and retaining only quadratic order terms yields a cost function

$$\mathcal{L}(a, \dot{a}) = \sum_{k \in K_m^+} \beta_k |\dot{a}_k|^2 + \gamma_k |a_k|^2,$$

where

$$\gamma_k \equiv 2 \sum_{p+q=k} \mu_{p,q}^2 c(p,q)^2 \frac{\beta_k^2}{\beta_{p,q}^2} ;$$

this formula for the dimensionless coefficients $\gamma_k$ follows from (11). The associated Hamilton–Jacobi equation (31) for $v = v(a)$ is then

$$\sum_k \beta_k^{-1} \left[ \frac{\partial v}{\partial a_k} \right]^2 - \gamma_k |a_k|^2 = 0, \quad \text{with} \quad v(0) = \frac{\partial v}{\partial a^*}(0) = 0.$$

Since this Hamilton–Jacobi equation is both separable and quadratic, its solution is a quadratic form

$$v(a) = \sum_k M_k |a_k|^2.$$

It follows immediately that $M_k = \sqrt{\gamma_k/\beta_k}$. In this case the conjugate variables are $\phi_k = \beta_k \dot{a}_k$, and hence the near-equilibrium linear relaxation equations for the mean amplitudes are simply

$$\frac{d a_k}{d t} = -\sqrt{\gamma_k/\beta_k} \dot{a}_k \quad (k \in K_m^+). \quad (35)$$

The key consequence of the decoupled system (35) is that the linear dissipative term in the reduced equations for the coarse-grained, mean vorticity, $\tilde{\xi}(x, t) = \sum_k a_k(t) e^{ikx}$, is given by a pseudo-differential operator with symbol

$$\alpha_k = \sqrt{\frac{\gamma_k}{\beta_k}} \quad \text{where} \quad \gamma_k \approx C_1 |k|^2 \log C_2 |k| + C_3,$$  

(36)

for certain dimensionless positive constants $C_1, C_2, C_3$. The approximate $k$-dependence displayed here is demonstrated analytically in appendix A under the restriction that the sequences of primitive weights is constant, $\mu_{p,q} = \mu$, and $\beta_k = \beta$ (that is, $\theta = 0$), and $1 \ll m \ll n$ with $|k| \sim m$. Numerical evaluation of the sum (34) shows that this behavior holds quite generally under mild conditions on the weight sequence, and for nonzero $\theta$. The notable feature of this dissipation operator is that it is not a standard diffusion, since $\alpha_k$ scales with $|k| \sqrt{\log|k|}$ for large $|k|$, rather than with $|k|^2$.

Alternatively, setting $a_k = 0$ for all $k \in K_m$, and retaining only the quadratic terms in the normalized perturbations, $\gamma_k = (b_k - \beta_k)/\beta_k$, of inverse variances yields the cost function

$$\mathcal{L}(y, \dot{y}) = \sum_{k \in K_m^+} \frac{\gamma_k^2}{2} + \frac{1}{3} \sum_{k \in K_m, p+q=k} \sum_{p+q=k} \mu_{p,q}^2 \frac{[c(q,k)\beta_p y_p + c(k,p)\beta_q y_q - c(p,q)\beta_{p,q}^2 y_p y_q]}{\beta_{p,q}^2 \beta_{p,q}}.$$
The closure potential in this cost function is expressible as a quadratic form in \( y \in K \), namely,

\[
L(y, \dot{y}) = \frac{1}{2} \sum_{k \in K} \dot{y}_k^2 + \frac{1}{2} \sum_{j, k \in K} D_{j,k} y_j \dot{y}_k.
\]

introducing the matrix of coefficients, \( D_{j,k} = (\gamma j/\beta_k) \delta_{j,k} + G_{j,k} \), where

\[
\gamma j_k = 4 \sum_{p+q=k} \nu^2_{p,q} c(p,q)^2 \frac{\beta_k^2}{\beta_p \beta_q},
\]

and

\[
G_{j,k} = 4 \nu^2_{j,k} c(k, 2k)^2/\beta_{2k}.
\]

The desired solution of the Hamilton–Jacobi equation for this case is a quadratic form, \( v = v(a, b) \), whose matrix \( R = (R_{j,k}) \) satisfies the matrix Riccati equation, \( R^2 = D \). Since \( D \) is a symmetric, positive-definite matrix, its has a unique symmetric, positive definite square root, \( R = \sqrt{D} \). The relaxation of the inverse variances, \( b_k = \beta_k(1 + y_k) \), to equilibrium for this case of optimal closure is therefore governed by the linear system

\[
\frac{dy_k}{dt} = -\sum_j R_{k,j} y_j.
\]

The essential content of (38) is readily grasped once we notice that the diagonal elements in the matrix \( D \) are large in comparison with the elements in the matrix \( G \). Indeed, each \( \gamma j/\beta_k \) given by (37) is the sum of \( O(n) \) positive terms, while each element \( G_{j,k} \) is either one term for \( j = k \), or a sum of 2 terms for \( j \neq k \), having similar structure and scaling properties. Since \( D \) is a \( d_m \times d_m \) matrix we therefore expect that it will be diagonally dominant when \( n \gg m \). When we neglect \( G_{j,k} \) in favor of the diagonal, \( D_{k,k} \), we get simply

\[
R_{k,k} \approx \sigma_k' \approx \sqrt{\gamma j/\beta_k}, \quad \text{and} \quad R_{j,k} \approx 0 \quad \text{for} \quad j \neq k.
\]

These approximate relaxation rates, \( \sigma_k' \), of the inverse variances to equilibrium are entirely analogous to those obtained for the mean amplitudes in (35), and hence their scaling with \( |k| \) is also represented by (36).

5.2. Perturbation analysis

In this section we approximate the solution of the Hamilton–Jacobi equation up to cubic order terms in a regular perturbation expansion around statistical equilibrium. The partial derivatives of the solution \( v = v(a, b) \) that define the irreversible terms in the closed reduced equation (33) are thereby expanded up to quadratic terms. In this way the dominant nonlinearity in the optimal closure is revealed at the same order as the quadratic nonlinearity in the Euler equation itself. This Taylor expansion is valid under the conditions

\[
\sqrt{\beta_k} |a_k| \ll 1, \quad \frac{|b_k - \beta_k|}{\beta_k} \ll 1.
\]
These near-equilibrium requirements normalize the mean amplitude and inverse variance perturbations relative to the equilibrium state, for which mode $k$ has variance $1/\beta_k$.

The complicated dependence on $b$ of the closure potential, $w = w(a, b)$, in (28) and (24) makes the derivation of the nonlinear reduced equations cumbersome. For this reason we invoke a simplification which rests on the insight gained in the preceding section that the diagonal terms in the linear relaxation system (38) are dominant. To define this approximation, we write the closure potential (28) as

$$w(a, b) = \Sigma_I + \Sigma_{II} + \Sigma_{III},$$

introducing a shorthand for the three sums appearing in (24), corresponding to the three independent sets of primitive weights $\lambda_k, \nu_{p,q}, \nu_{p,q}$ respectively. Since $\Sigma_I$ is homogeneous to degree four in $a$, it contributes quartic terms in $a$ to the Hamilton–Jacobi equation (31), which are one order higher than the retained order of our perturbation expansion; $\Sigma_I$ is therefore dropped from the closure potential. In $\Sigma_{II}$ and $\Sigma_{III}$ we observe that when both $p \in K_n \setminus K_m$ and $q \in K_n \setminus K_m$, then $b_p = \beta_p$ and $b_q = \beta_q$, and hence the complicated terms in those sums greatly simplify thanks to the relation (11). For $n \gg m$, this case occurs for the majority of the indices $p, q$; indeed, for each $k$ the relative proportion of the index pairs, $(p, q)$, with $p + q = k$, for which it does not hold is bounded by $Cm/n \ll 1$. On this basis we set $b_p = \beta_p, b_q = \beta_q$ in $\Sigma_{II}$ and $\Sigma_{III}$. Under this approximation the inverse variance for each resolved mode $k$ effectively interacts with an equilibrium ‘bath’ of other modes via triads, $p + q = k$, and hence the effective closure potential becomes separable over $k$. Specifically,

$$w(a, b) \approx \sum_{k \in K_n} \gamma_k |a_k|^2 + \gamma'_k \left(\frac{(b_k - \beta_k)^2}{2\beta_k^2 b_k}\right),$$

where $\gamma_k$ and $\gamma'_k$ are given by (34) and (37), respectively.

In appendix B the Hamilton–Jacobi equation (31) with closure potential (39) is solved up to cubic order in the mean amplitudes, $a_k$, and the inverse variance perturbations, $y_k = (b_k - \beta_k)/\beta_k$, and the governing equations for the optimal closure (33) are thereby calculated to this order of approximation. The result is as follows. In terms of the derived constants

$$\sigma_\gamma = \sqrt{\gamma_k/\beta_k}, \quad \sigma'_\gamma = \sqrt{\gamma'_k/\beta_k}, \quad \chi_k \doteq \sqrt{\gamma_k} \over 2\sqrt{\beta_k} + \sqrt{\gamma'_k},$$

and the modifying interaction coefficients

$$d(p, q) \doteq \frac{c(q, k)\beta_p \sigma_p + c(k, p)\beta_q \sigma_q - c(p, q)\beta_k \sigma_k}{(\sigma_p + \sigma_q + \sigma_k)\beta_k},$$

the governing equations for the approximated optimal closure are

$$\frac{da_k}{dr} + \sum_{p + q = k} \left[c(p, q) + d(p, q)\right] a_p a_q = -\sigma_\gamma \left[1 - (1 - \chi_k) y_k\right] a_k \tag{40}$$

$$\frac{dy_k}{dr} = -\sigma_\gamma \chi_k \beta_k |a_k|^2 - \sigma'_\gamma \left[1 + \frac{\chi_k}{2}\right] y_k \tag{41}.$$ 

This closed system of reduced equations for the means and inverse variances of the resolved low modes is the main result of the paper.
5.3. Some properties of the closure

The dominant dissipative mechanisms in the reduced equations (40) and (41) are the linear terms for the mean and inverse variance perturbation of mode \(k\), which are scaled by \(\beta_k\) and \(\sigma_k\). In order to clarify the dissipative structure of the closure (40) and (41) it is worthwhile to calculate the entropy production of the macroscopic dynamics. The entropy relativized to equilibrium is given by

\[
s(a, b) = -\left\{ \frac{\log \tilde{\beta}(a, b)}{\rho_{eq}} \right\} = -\sum_{k \in K_n} \beta_k |a_k|^2 + \log \frac{b_k}{\beta_k} - 1 + \frac{\beta_k}{b_k} \approx -\sum_{k \in K_n} \beta_k |a_k|^2 + \frac{(b_k - \beta_k)^2}{2\beta_k^2},
\]

where the final expression is an expansion in \(b - \beta\) that neglects terms \(O(b^3)\). Substituting the closed reduced equations (40) and (41) into the time derivative of this entropy yields

\[
\frac{ds}{dt} = -\sum_{k \in K_n} \beta_k a_k^2 \frac{da_k}{dt} + \frac{(b_k - \beta_k)}{2b_k^2} db_k \approx \sum_{k \in K_n} \sigma_k |a_k|^2 + \sigma_k^2 \frac{(b_k - \beta_k)^2}{2\beta_k^2}.
\]

retaining only the leading order terms in this expression for entropy production. Thus, we verify that entropy is monotonically increasing in forward time, within the range of validity of the perturbation analysis. The entropy production formula also reveals the relative contributions from the nonequilibrium mean, via \(|a_k|^2\), and nonequilibrium variance, via \((b_k - \beta_k)^2\), of the various modes \(k\).

The closure (40) and (41) contains two nonlinearities in its irreversible terms, beyond the dependence of the dissipation rates on the nonequilibrium variance perturbation. Namely, there are modified triad interactions between the mean amplitudes regulated by \(d(p, q)\), and couplings between the mean and variances of each mode \(k\) scaled by \(\chi\).

The coupling between the variance and mean captured by the first term of (41) is a noteworthy prediction of the optimal closure. Recalling that \(b_k\) is the inverse of variance in the statistical model, the negative term in (41) that is proportional to \(|a_k|^2\) represents a positive source of variance in the presence of a nonequilibrium (nonzero) mean \(a_k\), and this term can counteract the relaxation of the variance disturbance. It is sometimes observed in simulations, such as those documented in section 6, that the variance of a mode with substantial mean perturbation can overshoot its equilibrium value during relaxation. This effect is revealed when we ignore the modal interactions in (40) and (41) and form the \(2 \times 2\) system of first-order ordinary differential equations in the variables \(|a_k|^2\) and \(y_k\) for each particular mode \(k\). In this phase plane some orbits with initially large enough \(\beta_k|a_k|^2\) and positive \(y_k\) cross \(y_k = 0\) before relaxing to 0; that is, a mode with relatively large mean and small variance may exceed equilibrium variance in the process of its relaxation to equilibrium.

The modified interactions between the mean resolved modes may be put into a more illuminating form as follows. We calculate

\[
\tilde{c}(p, q) + \tilde{d}(p, q) = \frac{\sigma_p c(p, q)\beta_p + c(q, k)\beta_q + c(k, p)\beta_q}{(\sigma_p + \sigma_q + \sigma_k)\beta_k}.
\]

and we observe symmetry between \(p\) and \(q\) in the terms of this expression. On this basis we introduce asymmetric interaction coefficients
\[
\bar{c}(p, q) = \frac{2\sigma_p}{\sigma_p + \sigma_q + \sigma_k} \left[ c(p, q) + c(q, k)\frac{\beta_p}{\beta_k} \right] \quad \text{for } p + q = k \quad (44)
\]

and we rewrite the interaction terms in the reduced equation (40) in the simpler form:

\[
\sum_{p+q=k} \left[ c(p, q) + d(p, q) \right] a_p a_q = \sum_{p+q=k} \bar{c}(p, q) a_p a_q
\]

A further calculation exhibits the relationship of \( \bar{c}(p, q) \) to the primitive interactions in the vorticity dynamics (4) itself; namely,

\[
\bar{c}(p, q) = -\frac{p \times q}{|q|^2} \cdot \frac{\sigma_p}{\sigma_p + \sigma_q + \sigma_k} \left[ 1 - \frac{|q|^2}{|p|^2} + \frac{\beta_p}{\beta_k} \left( 1 - \frac{|q|^2}{|k|^2} \right) \right].
\]

When \( |q| \ll |p| \) and hence these interaction terms are relatively large, the factor multiplying the primitive interaction coefficient is nearly unity, since in that case \( |q| \ll |k|, |p| \sim |k|, \beta_p \sim 1, \gamma_q \ll \gamma_p \sim \gamma_k \) for these triads of wavevectors, \( \bar{c}(p, q) \approx c(p, q) \), suggesting that the modification of the interactions is weak. Recalling that \( p \) is the wavevector associated with the advected mean vorticity field and \( q \) is the wavevector associated with the mean streamfunction, this heuristic result suggests that the mean vorticity is strained by the mean flow in much the same way as vorticity is strained by its induced flow in the deterministic dynamics itself. This rough argument notwithstanding, the optimal closure theory makes a definite prediction about how averaging over the unresolved fluctuations in vorticity leads to modified interactions between the modes of the mean vorticity field.

### 6. Comparison with direct numerical simulations

In this section we present the results of some numerical experiments designed to test the predictive skill of the optimal coarse-grained dynamics. These simulations are carried out on a modestly truncated system, in which \( n = 32 \) and \( m = 4 \). Thus, a microdynamics with \( d_n = 2112 \) degrees of freedom is reduced to a macrodynamics in \( d_m = 40 \) resolved variables. Such a truncation may appear to be severe from the point of view of computational fluid dynamics. Nonetheless, it serves as a valid platform for testing the optimal closure, since this model reduction technique is applicable to the statistical evolution to any (isolated) Hamiltonian dynamical system of high dimension [40]. Furthermore, the requirement that the ensembles of fully-resolved solutions should be statistically converged requires that the number of realizations, \( N \), in the ensembles be very large, which puts a practical constraint on \( n \).

For the direct numerical simulations we employ the dealiased Fourier pseudospectral method with 96\(^2\) collocation points. The fourth-order Runge–Kutta method is used with fixed time step, \( \Delta t = 0.002 \), chosen to ensure conservation of energy and enstrophy. The code is parallelized with OpenMP in order to handle the large ensemble size. The optimal closure itself is computed by the Runge–Kutta method applied to the low-dimensional system of closed reduced equations (40) and (41).

#### 6.1. Initializing the ensembles

To generate an initial ensemble, \( \rho^0 = \tilde{\rho}(z; a^0, b^0) \), with specified (complex) means \( \sigma_k^0 \) and variances \( 1b_k^2 \) for the resolved modes \( k \in K_m^+ \), together with equilibrium means and variances for
the unresolved modes, we proceed as follows. The energy and enstrophy contained in the resolved modes are

\[
E_m^0 = \frac{1}{2} \sum_{k \in K_m} |k|^{-2} \left( |a_k|^2 + \frac{1}{b_k^2} \right), \quad Q_m^0 = \frac{1}{2} \sum_{k \in K_m} |a_k|^2 + \frac{1}{b_k^2}.
\]  

(45)

Since the energy content and enstrophy content of each unresolved mode \(k \in K_n \setminus K_m\) are identical in the equilibrium state, \(\rho_{eq}\) and the initial state, \(\rho^0\), the specified initial state is guaranteed to be dynamically compatible under statistical relaxation with the equilibrium state provided that

\[
E_m^0 = \frac{1}{2} \sum_{k \in K_n} \frac{1}{\beta |k|^2 + \theta}, \quad Q_m^0 = \frac{1}{2} \sum_{k \in K_n} \frac{1}{\beta + \theta |k|^2}.
\]  

(46)

These two equations determine the equilibrium parameters, \(\beta\) and \(\theta\), subject to \(\beta > 0\) and \(\theta > -\beta\). A unique pair \((\beta, \theta)\) exists by virtue of the fact that these equations are the critical point conditions for the strictly convex minimization

\[
\min_{\beta, \theta} E_m^0 \beta + Q_m^0 \theta - \frac{1}{2} \sum_{k \in K_n} \log(\beta + \theta |k|^2).
\]

Thus, when constructing a nonequilibrium initial state for a statistical relaxation experiment, the means and variances of the resolved (low) modes may be chosen arbitrarily, within the near-equilibrium limitations of the perturbation analysis of section 5, and from them the compatible equilibrium parameters \(\beta\) and \(\theta\) may be calculated.

### 6.2. Testing the Gaussian trial densities

Before evaluating the error between fully-resolved ensembles and the optimal closed reduced dynamics, we first check the normality assumption of the model. To do so we calculate the correlation coefficients of any two modes, as well as the skewness and excess kurtosis of each individual mode, in light of the basic assumption of our model reduction that all of these quantities vanish with respect to the trial densities (13). An initial ensemble is generated by random sampling a quasi-equilibrium density with \(\beta = 1\) and \(\theta = 0\), and having perturbations in mean and variance, namely, \(|a_k|\) and \(|b_k^2 - \beta_k|\) that vary from 0.07 to 0.98 and from 0.10 to 0.14, respectively; the ensemble contains 40000 realizations. For the fully-resolved nonequilibrium ensemble with this initial condition, the correlations between resolved modes is found to remain very small throughout its relaxation to equilibrium. For example, the four correlations between the real and imaginary parts of modes \((-4, 0)\) and \((-3, 1)\) all lie in the interval \([-0.05, +0.05]\) uniformly over the computed relaxation. Over the same time interval, the skewness of mode \((-4, 0)\) never exceeds 0.03 in magnitude, and the excess kurtosis of mode \((-4, 0)\) never exceeds 0.06. These ranges are typical for the other resolved modes. Similarly, the departures from normality of the unresolved modes, which the model sets to equilibrium statistics, are found to be small under the spectrally-truncated microdynamics (4). These tests support the choice of the trial densities (13) to approximate the true statistics of the evolving nonequilibrium statistical state.

### 6.3. Quantifying the error between model and DNS

To quantify the goodness-of-fit between a reduced model trajectory and the corresponding ensemble of fully-resolved solutions, a natural criterion is supplied by the relative entropy.


Namely, the Kullback–Leibler divergence [9, 22] between the evolving quasi-equilibrium density, \( \rho(\alpha(t), b(t)) \), and the exactly propagated density, \( \rho_{\text{dns}}(\alpha(t)) \), is

\[
D(\rho_{\text{dns}} \mid \tilde{\rho}) = \left\langle \log \frac{\rho_{\text{dns}}}{\tilde{\rho}} \right\rangle = \sum_{k \in K_+^m} b_k |a^\text{dns}_k - a_k|^2 + \log \frac{b_k^\text{dns}}{b_k^\text{eq}} + \frac{b_k}{b_k^\text{dns}} - 1 \approx \sum_{k \in K_+^m} b_k |a^\text{dns}_k - a_k|^2 + \frac{(b_k^\text{dns} - b_k)^2}{2(b_k^\text{dns})^2},
\]

where the approximation holds when \( b_k \approx b_k^\text{dns} \); \( a_k^\text{dns} \) and \( b_k^\text{dns} \) denote the means and variances derived from \( \rho_{\text{dns}} \). Motivated by this calculation, we use the following nondimensional squared norm to assess the fit between model predictions and direct numerical simulations of ensembles:

\[
\Delta_m(\rho^0 \mid \rho_{eq}) \doteq \frac{1}{d_m} \sum_{k \in K_+^m} \beta_k |a^0_k|^2 + \frac{|b_k^0 - \beta_k|^2}{2\beta_k^2}.
\]

This squared error per mode retains the intrinsic weighting between mean and variance deviations dictated by the relative entropy formula (47), but for simplicity it replaces the nonequilibrium inverse variances that scale the squared differences by their equilibrium values. It pertains to the \( d_m = 2m(m + 1) \) resolved modes and does not include any errors in the unresolved modes; as such it measures the skill of the optimal closure to predict the evolution of the coarse-grained vorticity field. The mean squared error averaged over some time interval, \( 0 \leq t \leq T \), is denoted by \( \Delta_m(\rho_{\text{dns}} \mid \tilde{\rho}) \). This time-averaged, relative-entropy based, squared norm is our principal metric for quantifying the goodness-of-fit of the optimal closure.

Table 1 gives the parameters for a set of 5 initial conditions having positive inverse temperatures, \( \theta \); across the columns \( \beta \) decreases from 0.99 to 0.76, while \( \theta \) increases from 0.013 to 0.61. Table 2 shows the parameters for a similar set of 5 initial conditions having negative inverse temperatures, \( \theta \); across the columns \( \beta \) decreases from 1.21 to 0.61, while \( \theta \) decreases from \(-0.025\) to \(-0.15\). In each of these tables the magnitude of the initial perturbation increases across the columns; these magnitudes are quantified by

\[
\Delta_m(\rho^0 \mid \rho_{eq}) \doteq \frac{1}{d_m} \sum_{k \in K_+^m} |a_k^0|^2 \beta_k + \frac{|b_k^0 - \beta_k|^2}{2\beta_k^2},
\]

which, as in (42), is the approximated relative entropy per mode between the initial density and the equilibrium density. These tables also list the maximum relativized perturbations in the mean and inverse variances over the disturbed modes \( k \in K_+^m \).
In figure 1 the time-averaged squared error, $\Delta_{\text{dns}}(\rho^0 | \rho_0)$, is plotted against the squared norm of the initial perturbation, $m_0^{\text{eq}}()$. For all the cases displayed in figure 1 the time averaging is taken over the interval, $t_0 \leq t \leq 3$, since the slowest modes almost completely relax by this time. The left panel of this figure demonstrates the necessity of taking large ensembles, in that it contrasts the computed error for $N = 4500$ random realizations against $N = 45000$ and $N = 90000$. The larger errors associated with smaller $N$ are attributable to sampling error rather than model error. Statistical convergence is obtained at $N = 90000$, in that the resulting error hardly decreases with further increased sampling. We therefore take the results for $N = 90000$ as representative of the true discrepancy between ensemble DNS and the optimal closure model.

The coarse-grained dynamics (40) and (41) used to propagate the model solution, $\tilde{\rho}(a(t), b(t))$, for the tests in figure 1 contain two adjustable parameters $\mu$ and $\nu$, which scale $\gamma_k$ and $\gamma_k'$, appearing in (34) and (37), respectively. We set $\mu_{pq} = \mu$ over the wavevector indices $p, q \in \mathbb{K}_n$, with $p + q = k$, in the sum defining $\gamma_k$, and similarly $\nu_{pq} = \nu$ for $\gamma_k'$, and we seek those parameters, $\mu$ and $\nu$, that minimize the time-averaged squared error between the optimal closure model and DNS. Numerical evaluations of the sums $\gamma_k$ and $\gamma_k'$ for various sequences of primitive weights $\mu_{pq}, \nu_{pq}$ shows that they are relatively insensitive to variations of the primitive weights over their indices $p$ and $q$. It is therefore doubtful that a much better fit between the model and DNS could be achieved by considering more complicated choices of the primitive weights. In the next section, the universal choice, $\mu_{pq} = \nu_{pq} = 1$ for all $p$ and $q$, is discussed, and the results for $\mu = \nu = 1$ are also plotted in figure 1.

We find excellent agreement for small initial perturbations. For instance, the first data column of table 1 gives $\Delta_{\text{dns}}(\rho^0 | \rho_0) = 0.018$, and we may ascribe almost all this squared error to the mean, since the variance perturbation is very small in this case. The initial mean perturbation averaged over all disturbed modes is thus 13%, while the maximum initial perturbation among those disturbed modes is 30%. On the one hand, when we ascribe all the time-averaged squared-norm error, $\Delta_{\text{dns}}(\rho^0 | \rho_0) = 8.4 \times 10^{-5}$, to the mean, we obtain a relative error in mean of less than 1%. On the other hand, when we ascribe the error to the variance alone, we obtain a relative error in variance of less than 2%. These small percentages provide upper bounds on the relative error in means and variances averaged over the resolved modes and the time interval of relaxation.

Good agreement between the large-ensemble DNS and the optimal closure persists for perturbations in mean and variance of the resolved modes having magnitudes up to order unity with respect to the equilibrium ensemble. For instance, in the fourth data column of table 1 the initial perturbation has roughly equal parts in the mean and variance and these correspond to 67% and 83%, respectively, relative to equilibrium. In this case, when we ascribe equal

| Table 2. Parameters used for five negative temperature ensembles with increasing perturbation magnitudes. |
|-----------------------------------------------|
| Total energy | 23 | 23 | 24 | 34 | 44 |
| Total enstrophy | $7.7 \times 10^3$ | $7.5 \times 10^3$ | $8.1 \times 10^3$ | $1.1 \times 10^4$ | $1.4 \times 10^4$ |
| max$|a^0_k|/\sqrt{\beta_k}$ | 0.38 | 0.57 | 0.92 | 1.3 | 1.4 |
| max$|b^0_k - \beta_k|/\beta_k$ | 0.08 | 0.20 | 0.66 | 2.1 | 3.7 |
| $\Delta_{\text{dns}}(\rho^0 | \rho_0)$ | 0.058 | 0.140 | 0.454 | 1.87 | 4.68 |

*Note: The initial perturbation is quantified by the relative-entropy-based squared norm $\Delta_{\text{dns}}(\rho^0 | \rho_0)$.*
parts of the squared error, \( \bar{\Delta}_m(\rho^{\text{DNS}} | \rho) = 2.4 \times 10^{-3} \), to mean and variance, we infer relative errors in mean of 3.4% and in variance of 4.8%. The fifth data column of table 1 is included to indicate the limitation of the theory for much larger amplitudes, as is anticipated in light of the derivation of the optimal closure via a perturbation expansion in amplitude around statistical equilibrium. In this case the maximum mean and variance perturbations are around twice the normalizing values for equilibrium, and an estimate ascribing equal parts of the squared error to the means and variances yields roughly 6% and 8% for the mean and variance errors, respectively.

Analogous results are obtained for the set of comparisons given in table 2, where the initial conditions are taken so that the inverse temperatures are negative. As is well known in the statistical equilibrium context, negative temperature states occur when energy concentrates in the low modes [20]. In an equilibrium theory in which the energy invariant is treated microcanonically, negative temperature states develop large-scale mean flows, identified as coherent structures in the fluctuating vorticity field [30]. It is known that the equivalence of ensembles with respect to the energy breaks down in the negative temperature regime, so that the canonical ensemble does not produce stable coherent structures [5, 11, 41]. In the current paper, both the energy and enstrophy invariants are treated canonically to avoid distracting complications in the development of the closure theory. Consequently, the reference statistical equilibrium states have increasingly large variance in the lowest modes as \( \theta \) becomes increasingly negative, while the mean of all modes is zero. The comparisons given in table 2 pertain to relaxation toward states of this kind from initial perturbations in the resolved modes with increasing magnitude, especially in the variance. For instance, in the third data column the initial perturbation relativized to equilibrium and averaged over the resolved modes is about 57% in mean and 49% in variance. If the relative-entropy-based squared error is ascribed equally to mean and variance, the mean and variance errors are approximately 3% and 4%, respectively. From this agreement we conclude that the optimal closure continues to give a good approximation to the actual statistical evolution in the negative temperature regime. The relative errors in the negative temperature regime, however, grow more rapidly with increasing perturbation magnitude than in the positive temperature regime. For the final two data columns in table 2 the disturbances in mean and, especially, variance are quite large, resulting in substantial
disagreement. To what extent these deviations are due to the nature of the negative temperature states as opposed to the limitations of the perturbation analysis is not clear.

Setting aside time-averaging in the goodness-of-fit metric, figure 2 plots the time evolution of the relative-entropy-based squared errors, $\Delta\rho(\rho_{\text{dns}}(t)|\hat{\rho}(t))$, for the three test cases with the smallest disturbances, in both the positive and negative temperature regimes. The conspicuous feature of all these plots is the short period of adjustment from the initial nonequilibrium state during which the squared error grows rapidly and then saturates before decaying almost exponentially as both the DNS ensemble and the optimal closure equilibrate. The transient phase during which the instantaneous squared errors are near their peak values is shorter in the positive temperature cases than in the negative temperature cases. For all the cases shown in figure 2 the squared error peaks at about 4 times its time-averaged value over the interval $0 \leq t \leq 3$. Thus, the maximum instantaneous root-mean-square errors in either mean or variance are about twice as large as the time-averaged errors discussed above. A likely explanation of this behavior is the ‘plateau’ effect discussed in [17, 40], in which the dissipation initially increases from zero before saturating. This transient effect results from imposing an initial state that is a trial density. The stationary optimal closure developed in the present paper does not account for this transient effect. Closer agreement during the transient phase might therefore be expected from the nonstationary version of the closure described in [40] and implemented for the truncated Burgers–Hopf equation in [18].

6.4. Eliminating the adjustable parameters

Figure 1 displays a striking agreement between the prediction of the optimal closure with best-fit parameters, $\mu$ and $\nu$, and the optimal closure in which both of these adjustable parameters are set to unity. In other words, it is found that the adjustable parameters that determine a closed reduced dynamics that is closest to DNS are $\mu, \nu \approx 1$. This result holds for all the test cases in which the optimal closure agrees well with DNS, in both the positive and negative temperature regimes. We conclude that the weights in the lack-of-fit Lagrangian (20) may be set equal to unity, or equivalently, that the weight operator $W$ may be taken to be the identity.
Then the Lagrangian is simply the $L^2(\Gamma_\theta, \tilde{\rho})$ squared norm of the Liouville residual, without separate treatment of its resolved and unresolved components.

With $\mu_{p,q} = \nu_{p,q} = 1$ for all $p$, $q$, we obtain closed reduced equations (40) and (41) that are entirely free of adjustable parameters. In this intrinsic closure $\gamma'_k = 2\gamma_k$, and hence the constants appearing in the coarse-grained equations (40) and (41) satisfy $\sigma'_k = \sqrt{2}\sigma_k$ and $\chi'_k = 1/(2 + \sqrt{2})$. The dissipative structure of the closure is therefore entirely determined by the sequence of constants $\gamma_k$ defined in (34). These constants $\gamma_k$ scale with $|k|$ according to the analytical formula (A.1), as is shown analytically in a special case in appendix A and can be verified numerically more generally.

7. Conclusions

A dynamically optimal coarse-graining of two-dimensional turbulence has been derived using the general statistical-mechanical reduction procedure proposed in [40], and its predictions have been validated against fully-resolved direct numerical simulations of large ensembles. Specifically, the evolution of statistical states for a spectral truncation of incompressible, inviscid fluid dynamics onto many Fourier modes has been approximated by a Gaussian statistical model that is parameterized by the means and variances of a set of low modes. Unlike traditional closure schemes, which typically rely on moment hierarchies and eddy damping strategies, this reduction procedure is based on an optimization principle, in which a cost functional that quantifies the residual due to coarse-graining is minimized. We have included arbitrary nondimensional parameters in the cost functional to weight the unresolved components of the residual relative to the resolved components. Information-theoretic considerations [17] suggest that all such weights can be set to unity, resulting in an optimal closure that is free of any adjustable parameters. This conjecture has been tested in section 6, where it has been found that the optimal closure with unit weights on all components is essentially indistinguishable from that obtained by best-fitting those weights against benchmark numerical solutions. One conclusion of this study, therefore, is that the weights can be set to unity from the outset—that is, $W = 1$ in (20)—making the reduction procedure conceptually and technically simpler, and yielding a system of closed reduced equations that is completely intrinsic. This universal coarse-grained dynamics pertains to the statistics of spectrally-truncated ideal flow in which the unresolved modes are taken to be in statistical equilibrium, and the resolved modes are relatively near equilibrium. Specifically, the tests documented in section 6 show good agreement with DNS for perturbations of the means up to about one equilibrium standard deviation and of the variances up to about one equilibrium variance.

While this paper has presented quantitative tests of the optimal closure for the near equilibrium regime, and for a spectrally-truncated dynamics having a modest resolution, our analytical derivation of the closed reduced equations for the Gaussian closure is formally valid for arbitrary high resolution and far from equilibrium. That is, the reduced equation (33) give the dynamically optimal evolution of the means and variances of the resolved modes within the class of Gaussian models (13) for any resolutions $n$ and $m$ of the fine and coarse scales, respectively, and without restriction on the amplitudes of the resolved variables. Moreover, they have a generic thermodynamic structure and associated properties, such as an entropy production inequality [35, 40]. These attractive features of the optimal Gaussian closure contrast with the properties of standard moment-based closures, which may not be self-consistent or realizable without suitable amendments or adjustments [27, 31, 34]. The reduced equations for the optimal closure, however, require solving the Hamilton–Jacobi equation (31) to determine
the dissipation potential $v(a, b)$. As is recognized in the calculus of variations and optimal control theory, Hamilton–Jacobi equations are not often analytically tractable, and hence one must rely on some approximations (such as the perturbative analysis used in this paper) or numerical solutions of the optimization problem itself. Investigations of realistic turbulence phenomena, which are naturally far from equilibrium, therefore would require techniques to handle this Hamilton–Jacobi equation beyond those invoked in this paper.

**Acknowledgments**

In the course of this work the authors benefited from conversations with Richard Kleeman. The work reported in this paper was partially supported by the National Science Foundation under grant DMS-1312576.

**Appendix A**

The closure constants $\gamma_k$ and $\gamma'_k$ occurring in the cost function (26) are given by the lattice sums (34) and (37). As mentioned in the analysis, it is useful to replace these exact expressions by approximations that capture their $k$-dependence.

When all the weights $\mu_{p,q}$ determining $\gamma_k$ are equal a common value and the inverse temperature $\theta$ vanishes, so that $\mu_{p,q} = \mu$ and $\beta_k = \beta$, independently of the wavevector indices $p$, $q$, $k$, a simple formula can be deduced for the dependence of $\gamma_k$ on $|k|$, over $k \in K_m$, provided that $1 \ll m \ll n$ and $|k| \sim m$. In this analytically tractable case, the lattice sum (34) equals the unsymmetrized sum

$$
\gamma = \frac{\mu^2}{2} \sum_{p+q=k} \frac{(p \times q)^2}{|q|^2} \left( \frac{1}{|q|^2} - \frac{1}{|p|^2} \right) = \frac{\mu^2}{2} \sum_{q \in K_m} \frac{(k \times q)^2}{|q|^2} \left( \frac{1}{|q|^2} - \frac{1}{|q|^2 - |k|^2} \right).
$$

The desired approximation results from replacing this lattice sum over $q \in K_n$ by an integral over $q \in \mathbb{R}^2$. For the fixed $k$, introduce the polar coordinates, $\rho = |q|$, and $\theta$, the angle between $q$ and $k$. For $\rho \gg |k|,

$$
\frac{1}{|q|^2} - \frac{1}{|q|^2 - |k|^2} = \frac{1}{\rho^2} - \frac{1}{\rho^2 + |k|^2 - 2\rho |k| \cos \theta} = - \frac{2 |k| \cos \theta}{\rho^3} + O \left( \frac{|k|^2}{\rho^3} \right).
$$

The finite sum over the lattice $K_n$ therefore approaches the convergent infinite sum over $\mathbb{Z}^2$ as $n \to \infty$. Given that $n \gg m$, this infinite lattice sum is approximated by the corresponding double integral,

$$
\gamma \approx \frac{\mu^2}{2} |k|^2 \int_{\mathbb{Z}^2} \int_0^{2\pi} \sin^2 \theta \left[ \frac{1}{\rho^2} - \frac{1}{\rho^2 + |k|^2 - 2\rho |k| \cos \theta} \right] \rho \, d\rho \, d\theta.
$$

Since the inner integral can be evaluated exactly, using

$$
I(\alpha) = \int_0^{2\pi} \frac{\sin^2 \theta \, d\theta}{1 + \alpha^2 - 2\alpha \cos \theta} = \begin{cases} 
\pi & \text{for } 0 < \alpha < 1 \\
\pi/\alpha^2 & \text{for } \alpha > 1
\end{cases},
$$

it follows that
In light of the conclusion of the section 6 that the weights can be set to unity, this approximation suggests a universal model for the $k$-dependence of $\gamma_k$, and likewise of $\gamma'_k = 2\gamma_k$; namely,

$$
\gamma_k = C_1|k|^2 \log C_2|k| + C_3, \quad \text{with } C_1 \approx 1.6, \ C_2 \approx 1.2, \ C_3 \approx 0.20. \quad (A.1)
$$

While the above derivation of this approximate dependence uses $\theta = 0$, it remains a good representation of $\gamma_k$, for the range of inverse temperature $\theta$ encountered in the simulations considered in this paper, except for the lowest wavenumbers. In general, the variation of $\gamma_k$ with $\theta$ is very weak.

### Appendix B

This appendix contains the calculations needed to derive the closed reduced equations (33) by a perturbation expansion of the Hamilton–Jacobi equation (31) up to cubic order in the resolved variables $a_k$ and $y_k = (b_k - \beta_k)/\beta_k$. To simplify the algebra, the approximation (39) is imposed throughout this derivation. Under this simplification, and replacing $b_k = \beta_k(1 + y_k)$ by $y_k$, and correspondingly $\psi_k$ by $\theta_k = \beta_k \psi_k$, the Hamiltonian (30) is

$$
\mathcal{H}(a, \phi, y, \eta) = \sum_{k \in K_k} \frac{|\phi_k|^2}{\beta_k(1 + y_k)} + \phi_k^* f_k(a) + f_k(a)^* \phi_k \\
+ \frac{(1 + y_k)^2 \eta_k^2}{2} - \gamma_k |a_k|^2 - \frac{\gamma'_k y_k^2}{2\beta_k(1 + y_k)} \\
\approx \sum_{k \in K_k} \frac{|\phi_k|^2}{\beta_k}(1 - y_k) + \phi_k^* f_k(a) + f_k(a)^* \phi_k \\
+ \frac{\eta_k^2}{2}(1 + 2y_k) - \gamma_k |a_k|^2 - \frac{\gamma'_k y_k^2}{2\beta_k}(1 - y_k), \quad (B.1)
$$

where the second expression is the Taylor approximation of $\mathcal{H}$ up to cubic terms.

The Hamiltonian (B.1) is separable over $k$ except for the terms involving $f_k(a)$. This special structure of the associated Hamilton–Jacobi (31) allows us to seek a solution in the power series form:

$$
v(a, y) = \sum_{k \in K_k} [M_k + C_k y_k]|a_k|^2 + \frac{1}{2} R_k y_k^2 + \frac{1}{3} S_k y_k^3 \\
+ \frac{1}{3} \sum_{k \in K_k} \sum_{p + q = k} N_{pq} \alpha_p \alpha_q \alpha_k^* + \cdots. \quad (B.2)
$$

The undetermined coefficients, $M_k, C_k, R_k, S_k$, are real, while the coefficients, $N_{pq}$ for $p, q \in K_m$, are complex, satisfying $N_{k,p} = N_{p,k}$ and $N_{p,-q} = N_{-p,q}^*$. The conjugate variables $\phi_k$ and $\eta_k$ satisfy the derived expansions:
Upon substituting these expressions into the Hamilton–Jacobi equation for the approximate Hamiltonian (B.1), and equating like terms in the series, we obtain the following equations for the undetermined coefficients in the expansion (B.2):

\[ M_k^2 - \beta k \gamma_k = 0 \quad [a_k^2 \text{ terms}] \]
\[ R_k^2 - \frac{\gamma_k}{\beta_k} = 0 \quad [y_k^2 \text{ terms}] \]
\[ 2M_kC_k + \beta k R_k C_k - M_k^2 = 0 \quad [a_k^2 y_k \text{ terms}] \]
\[ R_k S_k + R_k^2 + \frac{\gamma_k}{2\beta_k} = 0 \quad [y_k^3 \text{ terms}] \]

\[ \left( \frac{M_p}{\beta_p} + \frac{M_q}{\beta_q} + \frac{M_k}{\beta_k} \right) N_{p,q} - c(q,k)M_p - c(k,p)M_q + c(p,q)M_k = 0 \quad [a_p a_q a_k \text{ terms}] \]

Solving the first four of these equations yields

\[ M_k = \sqrt{\beta k \gamma_k}, \quad R_k = \frac{\gamma_k}{\sqrt{\beta_k}}, \quad C_k = \frac{\sqrt{\beta k \gamma_k}}{2 \sqrt{\gamma_k} + \sqrt{\gamma_k}^2}, \quad S_k = -\frac{3}{2} \sqrt{\frac{\gamma_k}{\beta_k}}. \]

The fifth equation yields the coefficients \( N_{p,q} \) in terms of the coefficients \( M_k \), and eventually the formula

\[ N_{p,q} = \frac{c(q,k) \sqrt{\beta_p \gamma_q} + c(k,p) \sqrt{\beta_k \gamma_q} - c(p,q) \sqrt{\beta_k \gamma_q}}{\sqrt{\gamma_p / \beta_p} + \sqrt{\gamma_q / \beta_q} + \sqrt{\gamma_k / \beta_k}} \quad [\text{for } p + q = k]. \]

These coefficients determine \( v(a, y) \) up to cubic terms, and consequently the desired reduced equations of the optimal closure are obtained up to quadratic order in \( (a, y) \) via the substitutions

\[ \phi_k = \frac{\partial L}{\partial a_k} = \beta k (1 + y_k)[a_k - f_k(a)], \quad \eta_k = \frac{\partial L}{\partial \eta_k} = \frac{y_k}{(1 + y_k)^2}. \]

That is, the closed reduced equations (40) and (41) for \( a_k \) and \( y_k \), respectively, follow upon eliminating \( \phi_k \) and \( \eta_k \).

### Appendix C

Here we collect some standard conventions and calculations for functions of several complex variables used in the body of the paper.

For any smooth function, \( f(z) \), of \( n \) complex variables, \( z = (z_1, \ldots, z_n) \in \mathbb{C}^n \), with \( z_k = x_k + iy_k \), the usual derivatives are defined by
\[
\frac{\partial f}{\partial z_k} = \frac{1}{2} \left( \frac{\partial f}{\partial x_k} - i \frac{\partial f}{\partial y_k} \right), \quad \frac{\partial f}{\partial \bar{z}_k} = \frac{1}{2} \left( \frac{\partial f}{\partial x_k} + i \frac{\partial f}{\partial y_k} \right);
\]

the notation \( z_k^* = x_k - iy_k \) is used for complex conjugate. In terms of these, the chain rule for the composite function \( f(z(t)) \), where \( t \) is a real variable, is simply

\[
\frac{df}{dt} = \sum_{k=-n}^{n} \frac{\partial f}{\partial z_k} \frac{dz_k}{dt} + \frac{\partial f}{\partial \bar{z}_k} \frac{d\bar{z}_k}{dt} = \sum_{k=-n}^{n} \frac{\partial f}{\partial z_k} \frac{dz_k}{dt}.
\]

The last equality invokes the convention that \( z^* \). In this notation Taylor’s expansion may be written as

\[
f(z) = f(0) + \sum_{k=-n}^{n} L_k z_k + \frac{1}{2} \sum_{k_1,k_2=-n}^{n} M_{k_1 k_2} z_{k_1} z_{k_2} + \frac{1}{6} \sum_{k_1,k_2,k_3=-n}^{n} N_{k_1 k_2 k_3} z_{k_1} z_{k_2} z_{k_3} + O(|z|^4),
\]

with coefficients

\[
L_k = \frac{\partial f}{\partial z_k}(0), \quad M_{k_1 k_2} = \frac{\partial^2 f}{\partial z_{k_1} \partial z_{k_2}}(0), \quad N_{k_1 k_2 k_3} = \frac{\partial^3 f}{\partial z_{k_1} \partial z_{k_2} \partial z_{k_3}}(0).
\]

This expansion is used in the perturbation analysis of the value function in section 5 and appendix B.

The Lagrangian \( \mathcal{L}(a, \dot{a}, b, \dot{b}) \) defined in section 3, and the Hamiltonian \( \mathcal{H}(a, \phi, b, \psi) \) and Hamilton–Jacobi equation in section 4, involve complex conjugate variables, \( a, \phi \in \mathbb{C}^m \) and \( \phi \in \mathbb{C}^n \), related by the complexified Legendre transform. This conjugacy can be seen to be equivalent to the usual real Legendre transform as follows. In a generic notation, consider a Lagrangian \( \mathcal{L}(z, \dot{z}) \) of a complex state vector, \( z = x + iy \in \mathbb{C}^n \), and define the canonically conjugate vector \( \zeta = \xi + i\eta \in \mathbb{C}^n \) by

\[
\zeta_k = \frac{\partial \mathcal{L}}{\partial \dot{z}_k} = \frac{1}{2} \left( \frac{\partial \mathcal{L}}{\partial x_k} + i \frac{\partial \mathcal{L}}{\partial y_k} \right) (k = 1, \ldots, n),
\]

and the associated Hamiltonian \( \mathcal{H}(z, \zeta) \) by

\[
\mathcal{H}(z, \zeta) = \sum_{k=1}^{n} \zeta_k^* \dot{z}_k + \dot{z}_k^* \zeta_k - \mathcal{L}.
\]

Then

\[
\zeta_k = \frac{\partial \mathcal{L}}{\partial \dot{z}_k} = \frac{\partial \mathcal{H}}{\partial \dot{z}_k}, \quad \eta_k = \frac{\partial \mathcal{H}}{\partial \dot{\zeta}_k} = \frac{\partial \mathcal{L}}{\partial \zeta_k}, \quad \mathcal{H} = \sum_{k=1}^{n} \zeta_k \dot{z}_k + \eta_k \dot{\zeta}_k - \frac{\mathcal{L}}{2}.
\]

Thus, the Legendre transform between \( \mathcal{L} \) and \( \mathcal{H} \) with \( n \) complex degrees of freedom is identical with the real transform between \( \mathcal{L}/2 \) and \( \mathcal{H}/2 \) with \( 2n \) real degrees of freedom.

Similarly, the complex Hamilton–Jacobi equation

\[
\mathcal{H}\left(z, -\frac{\partial \mathcal{L}}{\partial \dot{z}_k}\right) = 0,
\]

for a value function, \( v(z) \in \mathbb{R} \), is equivalent to its real counterpart, and the conjugacy relations between \( \zeta \) and \( z \) along any extremal path are
\[ \zeta_k = -\frac{\partial v}{\partial \xi_k} = -\frac{\partial v}{\partial x_k} - i\frac{\partial v}{\partial y_k} \]

Thus, this complex Hamilton–Jacobi theory is identical with the usual real Hamilton–Jacobi theory applied to the Hamiltonian \( H(x, \zeta, y, \eta)/2 \) and the value function \( \nu(x, y)/2 \). The relevant factor \( 1/2 \) merely scales \( L \).

References

[1] Abramov R, Kovacic G and Majda A J 2003 Hamiltonian structure and statistically relevant conserved quantities for the truncated Burgers–Hopf equation Commun. Pure Appl. Math. 56 1–46
[2] Balescu R 1975 Equilibrium and Non-Equilibrium Statistical Mechanics (New York: Wiley)
[3] Balian R 1991 From Microphysics to Macrophysics: Methods and Applications of Statistical Physics vol I (Berlin: Springer)
[4] Bouchet F and Venaille A 2012 Statistical mechanics of two-dimensional and geophysical flows Phys. Rep. 515 227–95
[5] Casella G and Berger R L 1991 Statistical Inference (Belmont, CA: Duxbury Press)
[6] Cichowlas C, Bonaiti P, Debbasch F and Brachet M 2005 Effective dissipation and turbulence in spectrally truncated Euler flows Phys. Rev. Lett. 95 264502
[7] Constantinou N C, Farrell B F and Ioannou P J 2016 Statistical state dynamics of jet-wave coexistence in barotropic beta-plane turbulence J. Atmos. Sci. 73 2229–53
[8] Cover T and Thomas J 1991 Elements of Information Theory (New York: Wiley)
[9] de Groot S R and Mazur P 1962 Non-Equilibrium Thermodynamics (Amsterdam: North-Holland)
[10] Ellis R S, Haven K and Turkington B 2002 Nonequivalent statistical equilibrium ensembles and refined stability theorems for most probable flows Nonlinearity 15 239–55
[11] Evans L C 1998 Partial Differential Equations (Providence, RI: American Mathematical Society)
[12] Farrell B F and Ioannou P J 2003 Structural stability of turbulent jets J. Atmos. Sci. 60 2101–18
[13] Fredericksen J S and O’Kane T J 2008 Entropy, closures and subgrid modeling Entropy 10 635–83
[14] Givon D, Kupferman R and Stuart A 2004 Extracting macroscopic dynamics: model problems and algorithms Nonlinearity 17 55–127
[15] Kleeman R 2015 A path integral formalism for non-equilibrium Hamiltonian statistical systems J. Stat. Phys. 158 1271–97
[16] Kleeman R and Turkington B 2014 A nonequilibrium statistical model of spectrally truncated Burgers–Hopf dynamics Commun. Pure Appl. Math 67 1905–46
[17] Kraichnan R H 1976 Eddy viscosity in two and three dimensions J. Atmos. Sci. 33 1521–36
[18] Kraichnan R H and Montgomery D 1980 Two-dimensional turbulence Rep. Prog. Phys. 43 547–619
[19] Krstulovic G, Mininni P D, Brachet M E and Pouquet A 2009 Cascades, thermalization, and eddy viscosity in helical Galerkin truncated Euler flows Phys. Rev. E 79 056304
[20] Leith C E 1971 Atmospheric predictability and two-dimensional turbulence J. Atmos. Sci. 28 145–61
[21] Lesieur M 1990 Turbulence in Fluids (Dordrecht: Kluwer)
[22] Lesieur M, Metais O and Comte P 2005 Large-Eddy Simulation of Turbulence (Cambridge: Cambridge University Press)
[23] Lesieur M, Metais O and Comte P 2005 Large-Eddy Simulation of Turbulence (Cambridge: Cambridge University Press)
[31] Marston J B 2012 Planetary atmospheres as nonequilibrium condensed matter Annu. Rev. Condens. Matter Phys. 3 285–310
[32] Monin A S and Yaglom A M 1971 Statistical Fluid Mechanics vol 1 (Cambridge, MA: MIT Press)
[33] Monin A S and Yaglom A M 1975 Statistical Fluid Mechanics vol 2 (Cambridge, MA: MIT Press)
[34] Orszag S A 1970 Analytical theories of turbulence J. Fluid Mech. 41 363–86
[35] Öttinger H C 2005 Beyond Equilibrium Thermodynamics (Hoboken, NJ: Wiley-Interscience)
[36] Sagan H 1969 Introduction to the Calculus of Variations (New York: McGraw-Hill)
[37] Salmon R 1998 Lectures on Geophysical Fluid Dynamics (Oxford: Oxford University Press)
[38] Tabeling P 2002 Two-dimensional turbulence: a physicist approach Phys. Rep. 362 1–62
[39] Tuckerman M E 2010 Statistical Mechanics: Theory and Molecular Simulation (Oxford: Oxford University Press)
[40] Turkington B 2013 An optimization principle for deriving nonequilibrium statistical models of Hamiltonian dynamics J. Stat. Phys. 152 569–97
[41] Turkington B 2009 Statistical mechanics of two-dimensional and quasi-geostrophic turbulence Long-Range Interacting Systems (Lecture Notes of the Les Houches Summer School vol 90) ed T Dauxois et al (Oxford: Oxford University Press) pp 159–209
[42] Yakhot V and Orszag S A 1986 Renormalization group analysis of turbulence. I. Basic theory J. Sci. Comput. 1 3–51
[43] Zubarev D N 1974 Nonequilibrium Statistical Thermodynamics (New York: Plenum)
[44] Zwanzig R 2001 Nonequilibrium Statistical Mechanics (New York: Oxford University Press)