GENERAL RELATIVITY AND WEYL FRAMES

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Abstract

We present the general theory of relativity in the language of a non-Riemannian geometry, namely, Weyl geometry. We show that the new mathematical formalism may lead to different pictures of the same gravitational phenomena, by making use of the concept of Weyl frames. We show that, in this formalism, it is possible to construct a scalar-tensor gravitational theory that is invariant with respect to the so-called Weyl transformations and reduces to general relativity in a particular frame, the Riemann frame. In this approach the Weyl geometry plays a fundamental role since it appears as the natural geometrical setting of the theory when viewed in an arbitrary frame. Our starting point is to build an action that is manifestly invariant with respect to Weyl transformations. When this action is expressed in more familiar terms of Riemannian geometry we find that the theory has some similarities with Brans-Dicke theory of gravity. We illustrate this point with an example in which a known Brans-Dicke vacuum solution may appear when reinterpreted in a particular Weyl frame.

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1 Introduction

It is a very well known fact that the principle of general covariance has played a major role in leading Einstein to the formulation of the theory of general relativity.[1] The idea underlying this principle is that coordinate systems are merely mathematical constructions to conveniently describe physical phenomena, and hence should not be an essential part of the fundamental laws of physics. In a more precise mathematical language, what is being required is that the equations of physics be expressed in terms of intrinsic geometrical objects, such as scalars, tensors or spinors, defined in the space-time manifold. This mathematical requirement is sufficient to guarantee the invariance of the form of the physical laws (or covariance of the equations) under arbitrary coordinate transformations.

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In field theories, one way of constructing covariant equations is to start with an action in which the Lagrangian density is a scalar function of the fields. In the case of general relativity, as we know, the covariance of the Einstein equations is a direct consequence of the invariance of the Einstein-Hilbert action.

A rather different kind of invariance that has been considered in some branches of physics is invariance under conformal transformations. These represent changes in the units of length and time that differ from point to point in the space-time manifold. Conformal transformations were first introduced in physics by H. Weyl in his attempt to formulate a unified theory of gravitation and electromagnetism. However, in order to introduce new degrees of freedom to account for the electromagnetic field Weyl had to assume that the space-time manifold is not Riemannian. This extension consists of introducing an extra geometrical entity in the space-time manifold, a 1-form field $\sigma$, in terms of which the Riemannian compatibility condition between the metric $g$ and the connection $\Gamma$ is redefined. Then, a group of transformations, which involves both $g$ and $\sigma$, is defined by requiring that under these transformations the new compatibility condition remain invariant. In a certain sense, this new invariance group, which we shall call the group of Weyl transformations, include the conformal transformations as subgroup.

It turns out that Einstein’s theory of gravity in its original formulation is not invariant neither under conformal transformations nor under Weyl transformations. One reason for this is that the geometrical language of Einstein’s theory is completely based on Riemannian geometry. Indeed, for a long time general relativity has been inextricably associated with the geometry of Riemann. Further developments, however, have led to the discovery of different geometrical structures, which we might generically call “non-Riemannian” geometries, Weyl geometry being one of the first examples. Many of these developments were closely related to attempts at unifying gravity with electromagnetism. While the new born non-Riemannian geometries were invariably associated with new gravity theories, one question that naturally arises is to what extent is Riemannian geometry the only possible geometrical setting for the formulation of general relativity. Our aim in this paper is to show that, surprisingly enough, one can formulate general relativity using the language of a non-Riemannian geometry, namely, the one known as Weyl integrable geometry. In this formulation, general relativity appears as a theory in which the gravitational field is described simultaneously by two geometrical fields: the metric tensor and the Weyl scalar field, the latter being an essential part of the geometry, manifesting its presence in almost all geometrical phenomena, such as curvature, geodesic motion, and so on. As we shall see, in this new geometrical setting general relativity exhibits a new kind of invariance, namely, the invariance under Weyl transformations.

The paper is organized as follows. In Sec. 2, we present the basic mathematical facts of Weyl geometry and the concept of Weyl frames. In Sec. 3, we show how to recast general relativity in the language of Weyl integrable geometry. In this formulation, we shall see that the theory is manifestly invariant under the group of Weyl transformations. We proceed, in Sec. 4, to obtain the field equations and interpret the new form of theory with Brans-Dicke scalar-tensor gravity. We conclude with some final remarks in Sec. 5.
2 Weyl Geometry

Broadly speaking, we can say that the geometry conceived by Weyl is a simple generalization of Riemannian. Indeed, instead of postulating that the covariant derivative of the metric tensor $g$ is zero, we assume the more general condition\(^1\)[2]

$$\nabla_\alpha g_{\mu\nu} = \sigma_\alpha g_{\mu\nu} \quad (1)$$

where $\sigma_\alpha$ denotes the components with respect to a local coordinate basis $\{\frac{\partial}{\partial x^\alpha}\}$ of a one-form field $\sigma$ defined on $M$. This, in fact, represents a generalization of the Riemannian condition of compatibility between the connection $\nabla$ and $g$, namely, the requirement that the length of a vector remain unaltered by parallel transport\(^2\). If $\sigma = d\phi$, where $\phi$ is a scalar field, then we have what is called an integrable Weyl geometry. The set $(M, g, \phi)$ consisting of a differentiable manifold $M$ endowed with a metric $g$ and a Weyl scalar field $\phi$ is usually referred to as a Weyl frame. It is interesting to note that the Weyl condition (1) remains unchanged when we go to another Weyl frame $(M, \overline{g}, \overline{\phi})$ by performing the following simultaneous transformations in $g$ and $\phi$:

$$\overline{g} = e^f g \quad (2)$$

$$\overline{\phi} = \phi + f \quad (3)$$

where $f$ is a scalar function defined on $M$\(^3\).

Quite analogously to Riemannian geometry, the condition (1) is sufficient to determine the Weyl connection $\nabla$ in terms of the metric $g$ and the Weyl one-form field $\sigma$. Indeed, a straightforward calculation shows that one can express the components of the affine connection with respect to an arbitrary vector basis completely in terms of the components of $g$ and $\sigma$:

$$\Gamma^\alpha_{\mu\nu} = \{^\alpha_{\mu\nu}\} - \frac{1}{2} g^{\alpha\beta}[g_{\beta\mu}\sigma_\nu + g_{\beta\nu}\sigma_\mu - g_{\mu\nu}\sigma_\beta] \quad (4)$$

where $\{^\alpha_{\mu\nu}\} = \frac{1}{2} g^{\alpha\beta}[g_{\beta\mu,\nu} + g_{\beta\nu,\mu} - g_{\mu\nu,\beta}]$ represents the Christoffel symbols, i.e., the components of the Levi-Civita connection\(^2\).

A clear geometrical insight on the properties of Weyl parallel transport is given by the following proposition: Let $M$ be a differentiable manifold with an affine connection $\nabla$, a metric $g$ and a Weyl field of one-forms $\sigma$. If $\nabla$ is compatible with $g$ in the Weyl sense, i.e., if (1) holds, then for any smooth curve $C = C(\lambda)$ and any pair of two parallel vector fields $V$ and $U$ along $C$, we have

$$\frac{d}{d\lambda} g(V, U) = \sigma(\frac{d}{d\lambda}) g(V, U) \quad (5)$$

where $\frac{d}{d\lambda}$ denotes the vector tangent to $C$ and $\sigma(\frac{d}{d\lambda})$ indicates the application of the 1-form $\sigma$ on $\frac{d}{d\lambda}$. (In a coordinate basis, putting $\frac{d}{d\lambda} = \frac{dx^\alpha}{d\lambda} \frac{\partial}{\partial x^\alpha}$, $V = V^\mu \frac{\partial}{\partial x^\mu}$, $U = U^\nu \frac{\partial}{\partial x^\nu}$, $\sigma = \sigma_d \frac{dx^d}{d\lambda}$, the above equation reads $\frac{d}{d\lambda}(g_{\alpha\mu} V^\alpha U^\mu) = \sigma_d \frac{dx^d}{d\lambda} g_{\alpha\mu} V^\alpha U^\mu$.)

If we integrate the equation (5) along the curve $C$, starting from a point $P_0 = C(\lambda_0)$, then we obtain

$$g(V(\lambda), U(\lambda)) = g(V(\lambda_0), U(\lambda_0)) e^{\int_{\lambda_0}^\lambda \sigma(\frac{d}{d\rho}) d\rho} \quad (6)$$

\(^1\)As one can easily check, that the Weyl compatibility condition between $\nabla$ and $g$ is equivalent to the Riemannian compatibility between $\nabla$ and $\overline{g} = e^{-\phi} g$.

\(^2\)Throughout this paper our convention is that Greek indices take values from 0 to $n - 1$. 

\(^3\)This process is called a Weyl frame.
Putting \( U = V \) and denoting by \( L(\lambda) \) the length of the vector \( V(\lambda) \) at an arbitrary point \( P = C(\lambda) \) of the curve, then it is easy to see that in a local coordinate system \( \{x^\alpha\} \) the equation (5) reduces to

\[
\frac{dL}{d\lambda} = \frac{\sigma_\alpha}{2} \frac{dx^\alpha}{d\lambda} L.
\]

Consider the set of all closed curves \( C : [a, b] \in R \rightarrow M \), i.e., with \( C(a) = C(b) \). Then, we have the equation

\[
g(V(b), U(b)) = g(V(a), U(a)) e^{\int_a^b \sigma(\frac{d}{d\lambda}) d\lambda}.
\]

It follows from Stokes’ theorem that if \( \sigma \) is an exact form, that is, if there exists a scalar function \( \sigma \), such that \( \sigma = d\phi \), then

\[
\oint \sigma(\frac{d}{d\lambda}) d\lambda = 0
\]

for any loop. In other words, in this case the integral \( e^{\int_a^b \sigma(\frac{d}{d\lambda}) d\lambda} \) does not depend on the path.

Let us conclude this section with a few historical comments on Weyl gravitational theory. Weyl developed an entirely new geometrical framework to formulate his theory, the main goal of which was to unify gravity and electromagnetism. As is well known, although admirably ingenious, Weyl’s gravitational theory turned out to be unacceptable as a physical theory, as was immediately realized by Einstein, who raised objections to the theory.[4, 5] Einstein’s argument was that in a non-integrable Weyl geometry the existence of sharp spectral lines in the presence of an electromagnetic field would not be possible since atomic clocks would depend on their past history.[4] However, it has been shown that a variant of Weyl geometries, known as Weyl integrable geometry, does not suffer from the drawback pointed out by Einstein. Indeed, it is the integral \( I(a, b) = \int_a^b \sigma(\frac{d}{d\lambda}) d\lambda \) that is responsible for the difference between the readings of two identical atomic clocks following different paths. Because in Weyl integrable geometry \( I(a, b) \) is not path-dependent it has attracted the attention of many cosmologists in recent years.[6]

### 3 General Relativity and a New Kind of Invariance

We have seen in the previous section that the Weyl compatibility condition (1) is preserved when we go from a frame \((M, g, \phi)\) to another frame \((M, \bar{g}, \bar{\phi})\) through the transformations (2) and (3). This has the consequence that the components \( \Gamma^\alpha_{\mu\nu} \) of the affine connection are invariant under Weyl transformations, which, in turn, implies the invariance of the affine geodesics. Now, as is well known, geodesics play a fundamental role in general relativity (GR) as well as in most metric theories of gravity. Indeed, an elegant aspect of the geometrization of the gravitational field lies in the geodesics postulate, i.e., the statement that light rays and particles moving under the influence of gravity alone follow space-time geodesics. Therefore a great deal of information about the motion of particles in a given space-time is promptly available once one knows its geodesics. The fact that geodesics are invariant under (2) and (3) and that Riemannian geometry is a particular case of Weyl geometry seems to suggest that it should be possible to express general relativity in a more general geometrical setting, namely, one in which the form of the field...
equations is also invariant under Weyl transformations. In this section, we shall show that this is indeed possible, and we shall proceed through the following steps. First we shall assume that the space-time manifold which represents the arena of physical phenomena may be described by a Weyl integrable geometry, which means that now gravity will be described by two geometric entities: a metric and a scalar field. The second step is to set up an action $S$ invariant under Weyl transformations. We shall require that $S$ be chosen such that there exists a unique frame in which it reduces to the Einstein-Hilbert action. The third step consists of extending Einstein’s geodesic postulate to arbitrary frames, such that in the Riemann frame it should describe the motion of test particles and light exactly in the same way as predicted by general relativity. Finally, the fourth step is to define proper time in an arbitrary frame. This definition should be invariant under Weyl transformations and coincide with the definition of GR’s proper time in the Riemann frame. It turns out then that the simplest action that can be built under these conditions is

$$S = \int d^4x \sqrt{-g} e^{-\phi} \left\{ R + 2\Lambda e^{-\phi} + \kappa e^{-\phi} L_m \right\}, \quad (7)$$

where $R$ denotes the scalar curvature defined in terms of the Weyl connection, $\Lambda$ is the cosmological constant, $L_m$ stands for the Lagrangian of the matter fields and $\kappa$ is the Einstein’s constant. In $n$-dimensions we would have

$$S_n = \int d^n x \sqrt{-g} e^{(1-\frac{n}{2})\phi} \left\{ R + 2\Lambda e^{-\phi} + \kappa e^{-\phi} L_m \right\}. \quad (8)$$

In order to see that the above action is, in fact, invariant with respect to Weyl transformations, we just need to recall that under (2) and (3) we have

$$\mathcal{F}^\mu{}_{\nu} = e^{-f} g^\mu{}_{\nu}, \quad \sqrt{-g} = e^{\frac{\phi}{2}} \sqrt{-\mathcal{F}}, \quad R^\mu{}_{\nu\alpha\beta} = R^\mu{}_{\nu\alpha\beta}, \quad \mathcal{R}^\mu{}_{\nu} = R^\mu{}_{\nu}, \quad \mathcal{R} = g^{\alpha\beta} R_{\alpha\beta} = e^{-f} R_{\alpha\beta} = e^{-f} R. \quad (\text{It will be assumed that } L_m \text{ generally depends on } \phi, g^\mu{}_{\nu} \text{ and the matter fields, its form being obtained from the special theory of relativity through the prescription } \eta^\mu{}_{\nu} \rightarrow e^{-\phi} g^\mu{}_{\nu} \text{ and } \partial^\mu \rightarrow \nabla^\mu, \text{ where } \nabla^\mu \text{ denotes the covariant derivative with respect to the affine connection. As it can be easily seen, these rules assure the invariance under Weyl transformations of part of the action that is responsible for the coupling of matter with the gravitational field, and, at the same time, reduce to the principle of minimal coupling adopted in general relativity when we set } \phi = 0, \text{ that is, in the Riemann frame.})$$

We now turn our attention to the motion of test particles and light rays. Here, our task is to extend GR’s geodesic postulate in such a way that it is invariant under Weyl transformations. The extension is straightforward and may be stated as follows: if we represent parametrically a timelike curve as $x^\mu = x^\mu(\lambda)$, then this curve will correspond to the world line of a particle free from all non-gravitational forces, passing through the events $x^\mu(a)$ and $x^\mu(b)$, if and only if it extremizes the functional

$$\Delta \tau = \int_a^b e^{-\frac{\phi}{2}} \left( g^\mu{}_{\nu} \frac{dx^\mu}{d\lambda} \frac{dx^\nu}{d\lambda} \right)^{\frac{1}{2}} d\lambda, \quad (9)$$

which is obtained from the special relativistic expression of proper time by using the prescription $\eta^\mu{}_{\nu} \rightarrow e^{-\phi} g^\mu{}_{\nu}$. Clearly, the right-hand side of this equation is invariant under Weyl transformations and reduces to the known expression of the propertime in general relativity in the Riemann frame. We take $\Delta \tau$, as given above, as the extension to an arbitrary Weyl frame the clock hypothesis, i.e., the assumption that $\Delta \tau$ measures the proper time measured by a clock attached to the particle. [7]
It is not difficult to verify that the extremization condition of the functional (9) leads to the equations

\[
\frac{d^2 x^\mu}{d \lambda^2} + \left( \{^\mu_{\alpha\beta} \} - \frac{1}{2} g^{\mu\nu}(g_{\alpha\nu} \phi_{,\beta} + g_{\beta\nu} \phi_{,\alpha} - g_{\alpha\beta} \phi_{,\nu}) \right) \frac{dx^\alpha}{d \lambda} \frac{dx^\beta}{d \lambda} = 0
\]

where \( \{^\mu_{\alpha\beta} \} \) denotes the Christoffel symbols calculated with \( g_{\mu\nu} \). Let us recall that in the derivation of the above equations the parameter \( \lambda \) has chosen such that

\[
e^{-\phi} g_{\alpha\beta} \frac{dx^\alpha}{d \lambda} \frac{dx^\beta}{d \lambda} = K = \text{const.}
\]

(10)

along the curve, which, up to an affine transformation, permits the identification of \( \lambda \) with the proper time \( \tau \). It turns out that these equations are exactly those that yield the affine geodesics in a Weyl integrable space-time as they can be rewritten as

\[
\frac{d^2 x^\mu}{d \tau^2} + \Gamma^\mu_{\alpha\beta} \frac{dx^\alpha}{d \tau} \frac{dx^\beta}{d \tau} = 0,
\]

(11)

where \( \Gamma^\mu_{\alpha\beta} = \{^\mu_{\alpha\beta} \} - \frac{1}{2} g^{\mu\nu}(g_{\alpha\nu} \phi_{,\beta} + g_{\beta\nu} \phi_{,\alpha} - g_{\alpha\beta} \phi_{,\nu}) \), according to (4), may be identified with the Weyl connection when \( \sigma_{(\alpha} = \phi_{,\alpha} \). Therefore, the extension of the geodesic postulate by requiring that the functional (9) be an extremum is equivalent to postulating that the particle motion must follow affine geodesics defined by the Weyl connection \( \Gamma^\mu_{\alpha\beta} \). It will be noted that, as a consequence of the Weyl compatibility condition (1) between the connection and the metric, (10) holds automatically along any affine geodesic determined by (11). Because both the connection components \( \Gamma^\mu_{\alpha\beta} \) and the proper time \( \tau \) are invariant when we switch from one Weyl frame to the other, the equations (11) are manifestly covariant under Weyl transformations.

As we know, the geodesic postulate not only makes a statement with respect to the motion of particles, but also regulates the propagation of light rays in space-time. Because the path of light rays are null curves, one cannot use proper time as a parameter to describe them. In fact, light rays are supposed to follow null affine geodesics, which cannot be defined in terms of the functional (9), but, instead, they must be characterized by their behaviour with respect to parallel transport. We shall extend this postulate by simply assuming that light rays follow Weyl null affine geodesics.

It is well known that null geodesics are preserved under conformal transformations, although one needs to reparametrize the curve in the new gauge. In the case of Weyl transformations null geodesics are also invariant with no need of reparametrization, since, again, the connection components \( \Gamma^\mu_{\alpha\beta} \) do not change under (2) and (3), while the condition (10) is obviously not altered. As a consequence, the causal structure of space-time remains unchanged in all Weyl frames. This seems to complete our program of formulating general relativity in a geometrical setting that exhibits a new kind of invariance, namely, that with respect to Weyl transformations.

4 General Relativity as a Scalar-Tensor Theory

In the new formalism it is interesting to rewrite the action (8) in Riemannian terms. This is done by expressing the Weyl scalar curvature \( R \) in terms of the Riemannian scalar curvature

\[
R = \frac{1}{2} g^{\mu\nu} \frac{\partial g_{\mu\nu}}{\partial \sigma_{(\alpha}} \frac{\partial g_{\nu\beta)}}{\partial \sigma_{(\beta}} - \frac{1}{2} \frac{\partial g_{\alpha\beta}}{\partial \sigma_{(\alpha}} \frac{\partial g_{\nu\beta)}}{\partial \sigma_{(\beta}} - \frac{1}{2} \frac{\partial g_{\mu\nu}}{\partial \sigma_{(\mu}} \frac{\partial g_{\alpha\beta}}{\partial \sigma_{(\alpha}} \frac{\partial g_{\nu\beta)}}{\partial \sigma_{(\beta}} - \frac{1}{2} \frac{\partial g_{\mu\nu}}{\partial \sigma_{(\mu}} \frac{\partial g_{\mu\nu}}{\partial \sigma_{(\nu}} \frac{\partial g_{\alpha\beta}}{\partial \sigma_{(\alpha}} \frac{\partial g_{\alpha\beta}}{\partial \sigma_{(\beta}} + \frac{1}{2} \frac{\partial g_{\alpha\beta}}{\partial \sigma_{(\alpha}} \frac{\partial g_{\alpha\beta}}{\partial \sigma_{(\beta}} \frac{\partial g_{\mu\nu}}{\partial \sigma_{(\mu}} \frac{\partial g_{\mu\nu}}{\partial \sigma_{(\nu}})
\]
curvature $\tilde{R}$ and the scalar field $\phi$, which gives

$$R = \tilde{R} - (n - 1)\Box \phi + \frac{(n - 1)(n - 2)}{4} \phi_{\mu,\nu} \phi_{,\mu,\nu}$$

where $\Box \phi$ denotes the Laplace-Beltrami. It is easily shown that, by inserting $R$ as given above into Eq. (8) and using Stokes’ theorem to neglect divergence terms in the integral, one obtains

$$S_n = \int d^n x \sqrt{-g} e^{(1 - \frac{n}{2})\phi} \left\{ \tilde{R} + \omega \phi_{,\mu,\nu} + 2\Lambda e^{-\phi} + \kappa e^{-\phi} L_m \right\},$$

(12)

where $\omega = \frac{(n - 1)(2 - n)}{4}$. For $n = 4$ we have $\omega = \frac{3}{2}$ and the action becomes

$$S = \int d^4 x \sqrt{-g} e^{-\phi} \left\{ \frac{3}{2} \phi_{,\mu,\nu} + 2\Lambda e^{-\phi} + \kappa e^{-\phi} L_m \right\}.$$

(13)

At this point, it is convenient to change the scalar field variable $\phi$ by defining $\Phi = e^{\phi}$. In terms of the new field $\Phi$ the action (13) takes the form

$$S = \int d^4 x \sqrt{-g} \left\{ \frac{3}{2\Phi} \phi_{,\mu,\nu} + 2\Lambda \Phi^2 + \kappa \Phi^2 L_m \right\}.$$

(14)

We then see that in the vacuum case and vanishing cosmological constant (14) is identical to the action of Brans-Dicke theory for $\omega = \frac{3}{2}$. This fact has been pointed out by some authors in similar contexts, although it will be noted that the analogy is not perfect since in the Weyl frame the geodesics are not Riemannian.

Finally, the field equations in an arbitrary Weyl frame are obtained by taking variations of $S$ in (13) with respect to $g_{\mu\nu}$ and $\Phi$, these being considered as independent fields. This will give us, respectively,

$$\tilde{G}_{\mu\nu} - (\phi_{,\mu,\nu} - g_{\mu\nu} \Box \phi) - \frac{1}{2} (\phi_{,\mu} \phi_{,\nu} + \frac{1}{2} g_{\mu\nu} \phi_{,\alpha} \phi_{,\alpha}) = -e^\phi (\kappa T_{\mu\nu} - \Lambda g_{\mu\nu})$$

(15)

$$\tilde{R} - 3\Box \phi + \frac{3}{2} \phi_{,\alpha} \phi_{,\alpha} = e^\phi (\kappa T - 4\Lambda),$$

(16)

where $\tilde{G}_{\mu\nu}$ denotes the Einstein tensor calculated with the Riemannian connection, and $T = g^{\mu\nu} T_{\mu\nu}$. It should be noted that (16) is just the trace of (15), and so, the field equations are not independent. This is consistent with the fact that we have complete freedom in the choice of the Weyl frame. It also means that $\phi$ may be viewed as an arbitrary function and not a dynamical field.

## 5 Final Remarks

As we have seen, in this scenario the gravitational field is not associated only with the metric tensor, but with the combination of both the metric $g_{\mu\nu}$ and the geometrical scalar field $\phi$. We can get some insight in the amount of physical information carried by the scalar field by investigating conformally-flat solutions of general relativity. Consider, for instance, homogeneous and isotropic cosmological models. All these have a conformally-flat geometry. It implies that there is a frame in which the geometry of these models
becomes that of flat Minkowski space-time. Thus, in the Riemann frame the space-time manifold is endowed with a metric that leads to Riemannian curvature, while in the Weyl frame space-time is flat. In this case, we see that all information about the gravitational field is encoded by the scalar field. Clearly, this leads, in distinct frames, to different pictures of the same gravitational phenomena. For instance, consider O’Hanlon-Tupper vacuum solution in Brans-Dicke theory with $\omega = -\frac{3}{2}$. [10] Surely, as far as the metric is concerned it can be regarded as a solution of general relativity in a Weyl frame. In fact, it is equivalent to Minkowski space-time in the Riemann frame, although test particles follow affine geodesics, which do not coincide with the metric geodesics of Minkowski space-time.

An important conclusion to be drawn from what has been shown in this paper is that general relativity can perfectly “survive” in a non-Riemannian environment. Moreover, as far as physical observations are concerned, all Weyl frames, each one determining a specific geometry, are completely equivalent. This conclusion seems to give some support to the view conceived by H. Poincaré that the geometry of space-time is perhaps a convention that can be freely chosen by the theoretician. [11] In particular, according to this view, general relativity may be rewritten in terms an arbitrary conventional geometry. [12]

Finally, it should be said that while at the classical level we have complete equivalence of frames, in the quantum context this may not be true. Indeed, as in the case of conformal transformations, quantization and Weyl transformations may not always commute. [?]  

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6 References

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