Stability analysis of heat transfer in nanomaterial flow of boundary layer towards a shrinking surface: Hybrid nanofluid versus nanofluid

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Abstract: Many boundary value problems (BVPs) have dual solutions in some cases containing one stable solution (upper branch) while other unstable (lower branch). In this paper, MHD flow and heat transfer past a shrinking sheet is studied for three distinct fluids: $AI_2O_3 - ZnO$ kerosene hybrid nanofluid, $AI_2O_3$ kerosene nanofluid, and $ZnO$ kerosene nanofluid. The partial differential equations (PDEs) are turned into ordinary differential equations (ODEs) using an appropriate transformation and then dual solutions are obtained analytically by employing the Least Square method (LSM). Moreover, stability analysis is implemented on the time-dependent case by calculating the least eigenvalues using Matlab routine bvp4c. It is noticed that negative eigenvalue is related to unstable solution i.e., it provides initial progress of disturbance and positive eigenvalue is related to stable solution i.e., the disturbance in solution decline initially. The impacts of various parameters, skin friction coefficient, and local Nusselt number for dual solutions are presented graphically. It is also noted that the results obtained for hybrid nanofluids are better than ordinary nanofluids.

Keywords: Stability analysis; hybrid nanofluid; shrinking sheet; dual solutions; analytical procedure.

| NOMENCLATURE |
|----------------|
| $f, \theta, F, G$ | Functions in dimensionless form |
| $q_w, q_r$ | Heat flux at the lower plate and radiative heat flux |

| Greek Symbols |
|----------------|
| $\tilde{u}, \tilde{v}$ | Components of velocity in $\tilde{x}$ and $\tilde{y}$ directions, respectively. |

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1. Introduction

The remarkable analysis in the flow of boundary layer past a stretching/shrinking sheet has been completed by many specialists as it has vast uses in industries and engineering. Some common examples are packaging of products, manufacturing of polymers, glass blowing, drawing of wires and aerospace coatings, etc. The real behavior of the surface depends on the rate of stretching/shrinking and cooling (exchange of heat) during the process of stretching/shrinking. Miklavcic and Wang [1] initiated the flow of fluid caused by a shrinking sheet and presented
numerical, exact, and close form solutions and they obtained dual solutions for the case of the shrinking sheet. The analysis of the flow of stagnation point past a shrinking sheet was studied by Wang [2]. He found dual solutions by taking some range of velocity ratio parameters. Ishak et al. [3] made an extension on the work of Wang [2] by taking micropolar fluid and finding multiple solutions. The solution in the analytical form for the flow of boundary layer caused by a shrinking sheet was given by Fang and Zhang [4]. They studied the close form solutions with special parameters. The MHD flow of fluid near the region of stagnation point towards a shrinking sheet was discussed by Lok et al. [5]. The study of flow problems through a permeable shrinking surface in the region of stagnation point having dual solutions was presented by Bhattacharyya and Layek [6] and they evaluated numerical solution by examining the impacts of suction/blowing and radiation. The slip effects on the flow of stagnation point caused by shrinking sheet were presented by Bhattacharyya et al. [7]. They also established dual solutions by employing shooting techniques to solve self-similar equations and they also noticed the increment in the range of dual solutions with slip parameter. Few other researchers [8–10] also found the dual solutions for shrinking sheets by using several physical effects.

In the 19th century, Maxwell [11] studied the influence of fluid’s thermal conductivity by taking various substances with improved conductivity. Latterly, to improve the fluid conductivity the idea of nanofluid as a new type of heat transfer fluid was given by Choi and Eastman [12]. They studied that nanofluid is formed when the nanoparticles are suspended in a base fluid. With the development in the process of nanotechnology-based transfer of heat, nanofluid is defined as a colloidal suspension of nanomaterials (1–100 nm) in a base fluid. By adding the nanoparticles like carbon material, metal oxides, and metals in base fluids, the outgrowth thermal conductivity of fluids increases in conventional heat transfer fluids and limits the ability of cooling. Nanofluids have vast applications in the manufacturing and engineering industries like fuel generators, cooling of electronics, and engine [13]. Therefore, nanofluids impact a great effort and interest to the researcher. Few other researchers have extended a great analysis of nanofluids [14–16].

In recent times, a new type of nanofluid called the hybrid nanofluid is introduced which is formed by suspension of assorted nanoparticles in the base fluid. Hybrid nanofluid enhances properties of heat transfer as well as provides extra substantial thermal, physical, and rheological features. This fluid captivated many researchers to extend the given problem for the transfer of heat. In this regard, an experimental analysis is conducted by Suresh et al. [17] on the synthesis,
characterization of $\text{Al}_2\text{O}_3 - \text{Cu}/\text{H}_2\text{O}$ nanocomposite powder by taking various percentages of volume concentrations. They determined the pH of nanofluids by studying the stability of nanofluids and found that the stability diminishes with increasing concentration of volume. Moreover, Suresh et al. [18] inspect the thermal and physical properties of $\text{Al}_2\text{O}_3 - \text{Cu}/\text{H}_2\text{O}$ hybrid nanofluid. They also showed that the reliability and efficiency of thermal conductivity are enhanced with $\text{Al}_2\text{O}_3 - \text{Cu}/\text{H}_2\text{O}$ hybrid nanofluid. The three-dimensional flow of $\text{Al}_2\text{O}_3 - \text{Cu}/\text{H}_2\text{O}$ a hybrid nanofluid past a stretching sheet with Lorentz force was numerically noticed by Devi and Devi [19]. Their findings reported that the optimal rate of heat transfer for hybrid nanofluid is gained by selecting different nanoparticles. Due to this regard, many investigators studied the hybrid nanofluids by taking physical assumptions over a stretching/shrinking sheet-like, Khashi’ie et al. [20], Zainal et al. [21], and Waini et al. [22].

In the last two or more decades, researchers started to apply a stability analysis on problems having multiple solutions. Some of them are stable and others are unstable. Due to the existence of dual solutions, stability analysis in fluid dynamics problems plays an important role and is roughly linked with some numerical errors. In this era, Merkin [23] was the first who perform stability analysis to check the stable solution. He calculated eigenvalues and obtained a stable solution for positive eigenvalues and an unstable solution for negative eigenvalues. Later, many researchers have done stability analysis for dual solutions in stretching/shrinking flows or mixed convection flows. The influences of transpiration on boundary layer flow towards surfaces in motion were discussed by Weidman et al. [24]. They found dual solutions and reported that the range of dual solutions decreases or increases by considering suction/blowing effects for zero transpiration. Within a porous media, an unsteady flow of mixed convection towards a vertical sheet near a region of stagnation point was discussed by Merill et al. [25]. They noticed dual solutions on large values of time by performing stability analysis and proved that the lower branch solution is unstable whereas the upper branch solution is stable. Later on, various researchers [26–32] have performed good analyses on stability and found multiple solutions. They reported in their study that the stable solutions are physically substantial and unstable solutions are not.

For the flow of boundary layer past a shrinking sheet with nonlinear differential equations, analytical solutions have a significant role. But in the case of strictly nonlinear coupled equations, it is very challenging work to find an analytical solution. In this regard, various analytical methods
have been employed to find estimated solutions to such nonlinear differential equations. The analytical outcomes of very weak nonlinear BVP were found by Nayfeh [33]. He used perturbation methods for this purpose but for a certain range of parameters, this method is not so efficient. The homotopy perturbation method was applied by Khan et al. [34] for the influence of thermal conductivity on the transfer of heat inside a hollow sphere with heat generation. Some other analytical techniques have also been employed for solving the nonlinear problems like linearization methods [35], Lindstedt–Poincare method [36], differential transformation method [37], and optimal homotopy perturbation method [38]. Moreover, some other simple and more accurate analytical methods are available for solving differential equations namely: weighted residual methods which consist of the Least square method, method of Moments, Collocation method, and Galerkin method. The least-square method was initiated by Bouaziz and Aziz [39]. They employed this method for predicting the longitudinal fin performance and found this method more simple and accurate than others. Furthermore, the detailed study on the Least square method was completed by Hatami and Ganji [40–42] and they employed this method on different problems of fluid mechanics.

The main focus of the present paper is to use an analytical method namely: Least square method to find the dual solutions of MHD flow and heat transfer past a shrinking sheet for three distinct fluids. Also to check the reliable solution using stability analysis and evaluate the corresponding eigenvalues for both solutions.

2. Mathematical model

Consider a two-dimensional flow of boundary layer and heat transfer for three different fluids near a region of stagnation point caused by stretching/shrinking surface. Aluminum oxide (Al₂O₃) and zinc oxide (ZnO) are chosen as the nanomaterials with Kerosene oil as the base fluid. The surface is placed along a horizontal axis and the vertical axis is considered normal to the surface as displayed in Fig. 1. The surface is stretched or shrunk having velocity \( \tilde{u}_r(\bar{x}) = a \bar{x} \), here \( a < 0 \) determines shrinking and \( a > 0 \) determines stretching surface. For the orthogonal flow of stagnation point, fluid flow over the surface with velocity \( \tilde{u}_s(\bar{x}) = b \bar{x} \), here \( b > 0 \) determines the stagnation flow strength. An external magnetic field with strength \( B_0 \) is also taken in the normal
direction to the surface. Since it is an earlier assumption that the magnetic Reynolds number is too low, which causes the higher magnetic diffusion than magnetic advection, due to which induced magnetic field is ignored.

Under all assumptions stated above, the governing Navier–Stokes and energy equations for the case of steady flow with radiation are written as:

\[
\frac{\partial \vec{u}}{\partial \hat{x}} + \frac{\partial \vec{v}}{\partial \hat{y}} = 0, \tag{1}
\]

\[
\vec{u} \frac{\partial \vec{u}}{\partial \hat{x}} + \vec{v} \frac{\partial \vec{u}}{\partial \hat{y}} = -\frac{1}{\rho_{\text{hnf}}} \vec{u}_e \frac{d \vec{u}_e}{d \hat{x}} + \frac{\mu_{\text{hnf}}}{\rho_{\text{hnf}}} \frac{\partial^2 \vec{u}}{\partial \hat{y}^2} + \frac{\sigma_{\text{hnf}}}{\rho_{\text{hnf}}} B_0^2 (\vec{u}_e - \vec{u}), \tag{2}
\]

\[
\vec{u} \frac{\partial T}{\partial \hat{x}} + \vec{v} \frac{\partial T}{\partial \hat{y}} = \left( \frac{k}{\rho C_p}_{\text{hnf}} \right) \frac{\partial^2 T}{\partial \hat{y}^2} - \frac{1}{(\rho C_p)_{\text{hnf}}} \frac{\partial q_r}{\partial \hat{y}}, \tag{3}
\]

here \( \vec{u} \) and \( \vec{v} \) denotes velocity components of fluid along the horizontal and vertical axis, respectively, and \( T \) indicates temperature. The subscripts \( \text{hnf}, \text{nf} \) and \( f \) indicate hybrid nanofluid, nanofluid, and base fluid respectively. Physical meanings of all other parameters are given in nomenclature.

Associated boundary conditions (BCs) are:

For \( \hat{y} = 0 \):
\[
\vec{u} = \vec{u}_w, \quad \vec{v} = 0, \quad T = T_w.
\]

For \( \hat{y} \to \infty \):
\[
\vec{u} \to 0, \quad \vec{v} \to 0, \quad T \to T_\infty.
\]

Fig. 1: Problem’s geometry
Table 1: The physical and thermal properties of magnetic nanomaterials and base fluid [32]:

| Materials       | \( \rho \) \( (kg/m^3) \) | \( \sigma \) \( (\Omega \cdot m)^{-1} \) | \( k \) \( (W/(m \cdot K)) \) | \( C_p \) \( (J/(kg \cdot K)) \) |
|-----------------|-----------------|-----------------|-----------------|-----------------|
| \( Al_2O_3 \)   | 3970            | \( 1 \times 10^{-10} \) | 40              | 765             |
| \( ZnO \)       | 5700            | \( 10-1 \times 10^{-3} \) | 25              | 523             |
| kerosene oil    | 783             | \( 6 \times 10^{-10} \) | 0.15            | 2090            |

Table 2: The effective properties of nanofluid and hybrid nanofluid are defined below [32]:

|                  | Nanofluid                  | Hybrid nanofluid                  |
|------------------|----------------------------|----------------------------------|
| Dynamic viscosity| \( \mu_{nf} = \frac{\mu_f}{(1-\phi_f)^{2\frac{1}{5}}} \) | \( \mu_{hnf} = \frac{\mu_{nf}}{(1-\phi_2)^{2\frac{1}{5}}} \) |
| Density          | \( \rho_{nf} = (1-\phi_f)\rho_f + \rho_s \phi_f \) | \( \rho_{hnf} = (1-\phi_2)\rho_{nf} + \rho_s \phi_2 \) |
| Electrical conductivity | \( \sigma_{nf} = \sigma_f \left( \frac{\sigma_s (1+2\phi_f) + 2\sigma_f (1-\phi_f)}{\sigma_s (1-\phi_f) + \sigma_f (2+\phi_f)} \right) \) | \( \sigma_{hnf} = \sigma_{nf} \left( \frac{2(1-\phi_2)\sigma_f + (2\phi_2 + 1)\sigma_s}{(\phi_2 + 2)\sigma_f + (1-\phi_2)\sigma_s} \right) \) |
| Thermal conductivity | \( k_{nf} = k_f \left( \frac{2k_f + k_s - 2(k_f - k_s)\phi_f}{2k_f + k_s + (k_f - k_s)\phi_f} \right) \) | \( k_{hnf} = k_{nf} \left( \frac{2k_{nf} + k_{s2} - 2(k_{nf} - k_{s2})\phi_2}{2k_{nf} + k_{s2} + (k_{nf} - k_{s2})\phi_2} \right) \) |
| Heat capacity    | \( (\rho C_p)_{nf} = (\rho C_p) (1-\phi_f) + (\rho C_p) s \phi_f \) | \( (\rho C_p)_{hnf} = (1-\phi_2)(\rho C_p)_{nf} + \phi_2(\rho C_p)_{s2} \) |

The radiative heat flux is denoted by \( q_r \) and is given by Rosseland approximation [43]:

\[
q_r = -\frac{4\sigma_1}{3k_1} \frac{\partial T^4}{\partial \tilde{y}}.
\]

The variation of temperature \( (T^4) \) is taken as Taylor’s expansion, then ignoring the terms of higher-order and after that, the expansion of \( (T^4) \) about \( T_\infty \) gives \( T^4 \approx 4T_\infty^3 T - 3T_\infty^4 \) and

\[
\frac{\partial q_r}{\partial \tilde{y}} = -\frac{16\sigma_1}{3k_1} T_\infty^3 \frac{\partial^2 T}{\partial \tilde{y}^2}.
\]

Eq. (3) then becomes

\[
\tilde{u} \frac{\partial T}{\partial \tilde{x}} + \tilde{v} \frac{\partial T}{\partial \tilde{y}} = \frac{k_{hnf}}{(\rho C_p)_{hnf}} \frac{\partial^2 T}{\partial \tilde{y}^2} + \frac{1}{3k_1} \frac{16\sigma_1 T_\infty^3}{\rho C_p} \frac{\partial^2 T}{\partial \tilde{y}^2}.
\]
Now the similarity transformations are introduced in the following forms:

\[ \tilde{u} = f' (\eta) \, b \, x, \quad \tilde{v} = -f (\eta) \sqrt{\nu_f \, b}, \quad \theta (\eta) = \frac{T - T_\infty}{T_w - T_\infty}, \quad \eta = \frac{b}{\nu_f} \, \tilde{y}, \]  

(7)

here prime specifies differentiation of function with respect to variable \( \eta \). The dimensionless form of governing equations are presented as follows:

\[ \frac{A_1}{A_2} f''' + 1 - f''^2 + f f'' + M \frac{A_3}{A_2} (1 - f' ) = 0, \]  

(8)

\[ (A_4 + R) \theta'' + A_5 \, P_r \, f \, \theta' = 0, \]  

(9)

where the magnetic number \( M \), Prandtl number \( P_r \) and radiation parameter \( R \) are given as

\[ M = \frac{\sigma_f B_0^2}{b \rho_f}, \quad P_r = \left( \frac{\mu \rho}{k} \right), \quad R = \frac{16 \sigma_i T_\infty^3}{3 k_i k_f}. \]  

(10)

And the constant parameters \( A_1, A_2, A_3, A_4 \) and \( A_5 \) are:

\[ A_1 = \frac{\mu h_{nf}}{\mu_f}, \quad A_2 = \frac{\rho h_{nf}}{\rho_f}, \quad A_3 = \frac{\sigma h_{nf}}{\sigma_f}, \quad A_4 = \frac{k_{nf}}{k_f}, \quad A_5 = \frac{\left( \rho C_p \right)_{h_{nf}}}{\left( \rho C_p \right)_{f}}. \]  

(11)

BCs:

For \( \eta = 0 \): \( f = 0, \quad f' = \lambda, \quad \theta = 1 \),

For \( \eta \to \infty \): \( f' \to 1, \quad \theta \to 0 \).  

(12)

Here, \( \lambda = \frac{a}{b} \) represents the velocity ratio parameter.

The physical terms of attention are coefficient of skin friction \( C_f \) and local Nusselt number \( Nu_x \) and both of them are given below:

\[ Re_x^{1/2} C_f = A_1 f'' (0), \quad Re_x^{3/2} Nu_x = -A_4 \theta' (0), \]  

(13)

here \( Re_x = \tilde{u} \tilde{x} / \nu_f \) indicates the local Reynolds number.

3. Stability analysis

Stability analysis has been performed by many researchers like Awaludin et al. [28], Hamid et al. [29], and Waini et al. [30] to check the stable and unstable solutions. For this purpose, an additional dimensionless time variable \( \tau = b \tilde{t} \) is considered, due to which the flow problem
becomes unsteady. Prandtl theory is utilized and pressure gradient is eliminated from component forms and then equations for unsteady flow are gained as

\[
\frac{\partial \tilde{u}}{\partial \tilde{t}} + \tilde{u} \frac{\partial \tilde{u}}{\partial \tilde{x}} + \tilde{v} \frac{\partial \tilde{u}}{\partial \tilde{y}} = -\frac{1}{\rho_{h\kappa}} \tilde{u}_\epsilon \frac{d \tilde{u}_\epsilon}{d \tilde{x}} + \frac{\mu_{h\kappa}}{\rho_{h\kappa}} \frac{\partial^2 \tilde{u}}{\partial \tilde{y}^2} + \frac{\sigma_{h\kappa}}{\rho_{h\kappa}} B_0^2 (\tilde{u}_\epsilon - \tilde{u}), \tag{14}
\]

\[
\frac{\partial T}{\partial \tilde{t}} + \tilde{u} \frac{\partial T}{\partial \tilde{x}} + \tilde{v} \frac{\partial T}{\partial \tilde{y}} = \frac{k_{h\kappa}}{(\rho C_p)_{h\kappa}} \frac{\partial^2 T}{\partial \tilde{y}^2} + \frac{1}{(\rho C_p)_{h\kappa}} \frac{16 \sigma T_0^3}{3k_1} \frac{\partial^2 T}{\partial \tilde{y}^2}. \tag{15}
\]

Now for a dimensionless form of the above equations, new transformations with time-variable \( \tau \) are used as

\[
\tilde{u} = f'(\eta, \tau) b \tilde{x}, \quad \tilde{v} = -f(\eta, \tau) \sqrt{\nu_j b}, \quad \theta(\eta, \tau) = \frac{T - T_\infty}{T_\infty - T_w}, \quad \eta = \frac{b}{\nu_f} \tilde{y}, \quad \tau = b \tilde{t}. \tag{16}
\]

Using the above transformation (16) in Eqs. (14) and (15) gives

\[
\frac{A_1}{A_2} \frac{\partial^3 f}{\partial \eta^3} + \frac{1}{A_2} \left( \frac{\partial f}{\partial \eta} \right)^2 + f \frac{\partial^2 f}{\partial \eta^2} + M \frac{A_3}{A_2} \left( 1 - \frac{\partial f}{\partial \eta} \right) - \frac{\partial^2 f}{\partial \eta \partial \tau} = 0, \tag{17}
\]

\[
\left( A_4 + R \right) \frac{\partial^2 \theta}{\partial \eta^2} + A_5 P F \frac{\partial \theta}{\partial \eta} - A_5 P \frac{\partial \theta}{\partial \tau} = 0, \tag{18}
\]

and the associated boundary conditions in the case of unsteady flow are:

For \( \eta = 0 \):

\[
f(0, \tau) = 0, \quad \frac{\partial f}{\partial \eta}(0, \tau) = \lambda, \quad \theta(0, \tau) = 1. \tag{19}
\]

For \( \eta \to \infty \):

\[
\frac{\partial f}{\partial \eta}(\eta, \tau) \to 1, \quad \theta(\eta, \tau) \to 0.
\]

Following Awaludin et al. [28], Hamid et al. [29] and Waini et al. [30], the unknown functions are:

\[
f(\eta, \tau) = f_0(\eta) + F(\eta, \tau) e^{-\gamma \tau}, \quad \theta(\eta, \tau) = \theta_0(\eta) + G(\eta, \tau) e^{-\gamma \tau}. \tag{20}
\]

Here, \( \gamma \) is the unidentified eigenvalue parameter, \( f_0(\eta) \) and \( \theta_0(\eta) \) are steady solutions of a problem given in Eqs. (8)–(9) and both are larger than the functions \( F(\eta, \tau) \) and \( G(\eta, \tau) \).

Substituting Eq. (20) into Eqs. (17)–(18), the following linearized problem is obtained:

\[
\frac{A_1}{A_2} \frac{\partial^3 F}{\partial \eta^3} + f_0 \frac{\partial^2 F}{\partial \eta^2} + f''_0 F - (2f'_0 - \gamma) \frac{\partial F}{\partial \eta} = M \frac{A_3}{A_2} \frac{\partial F}{\partial \eta} - \frac{\partial^2 F}{\partial \eta \partial \tau} = 0, \tag{21}
\]
\[
\left( A_4 + R \right) \frac{\partial^2 G}{\partial \eta^2} + A_5 P \left( f_0 \frac{\partial G}{\partial \eta} + F \theta'_0 + \gamma G - \frac{\partial G}{\partial \tau} \right) = 0, \tag{22}
\]

along with BCs:

For \( \eta = 0 \): \( F(0, \tau) = 0, \quad \frac{\partial F}{\partial \eta}(0, \tau) = 0, \quad G(0, \tau) = 0, \)

For \( \eta \to \infty \): \( \frac{\partial F}{\partial \eta}(\eta, \tau) \to 0, \quad G(\eta, \tau) \to 0. \tag{23} \)

To investigate the stability of steady flow solutions \( f_0(\eta) \) and \( \theta_0(\eta) \), set \( \tau = 0 \) in Eqs. (21)–(23). Hence \( F(\eta, \tau) = F_0(\eta) \) and \( G(\eta, \tau) = G_0(\eta) \) represents the initial growth or decay of the solution. In this regard, the following linear eigenvalue problem is to be solved

\[
\frac{A_1}{A_2} F_0'''' + \left( \gamma - 2 f_0' \right) F_0'' + f_0'' F_0 + A_2 \frac{M F_0'}{A_2} = 0, \tag{24}
\]

\[
\left( A_4 + R \right) G_0'' + A_5 P \left( f_0 \theta_0' + f_0' G_0' + \gamma G_0 \right) = 0, \tag{25}
\]

with BCs:

For \( \eta = 0 \): \( F_0(0) = 0, \quad F_0'(0) = 0, \quad G_0(0) = 0, \)

For \( \eta \to \infty \): \( F_0'(\eta) \to 0, \quad G_0(\eta) \to 0. \tag{26} \)

By finding the smallest eigenvalues, stability of the dual solutions is applied for certain values of parameters like: \( \lambda, M, P_r \) and \( R \). Harris et al. [26] stated in their study that to calculate the eigenvalues, an extra boundary condition is used. For this purpose, \( F_0''(0) = 1 \) a condition is applied to the problem and then it is solved using the bvp4c function in Matlab software.

4. Least square method

The Weighted Residual technique such as the Least square method is an approximation technique that gives the most useable procedure that applies to nonlinear dynamical models. The central idea of this method is to obtain an estimated solution of the differential equation. Consider a differential equation

\[
D(\tilde{F}) = \tilde{f}, \tag{27}
\]

subjected to the boundary conditions

\[
B_j \tilde{F} = \tilde{g}_j. \tag{28}
\]
In order to discover an estimated solution to the given problem, consider a linear combination set (linearly independent) of a basis functions. That is,
\[
\hat{F} = \tilde{F}_0 + \sum_{j=1}^{m} c_j \phi_j.
\] (29)

Here \(\tilde{F}_0\) is selected in a manner that the boundary conditions are satisfied, exactly if possible. \(\phi_j\) are the linearly independent functions, also called trial functions, and are supposed to be known. The coefficients \(c_j\) are unknowns and can be obtained by solving a system of equations.

When substituted Eq. (29) in Eq. (27), it will not satisfy the equation. Hence an error or residual \(\tilde{R}\), which is a continuous function of spatial coordinates, exists and is written as
\[
\tilde{R} = D(\hat{F}) - \tilde{f} \neq 0.
\] (30)

In one spatial coordinate, the approximating functions may be the trigonometric functions or the polynomials of the form
\[
\tilde{\phi}_j(\varepsilon) = e^{i\varepsilon} \quad \text{or} \quad \tilde{\phi}_j(\eta) = \sin j\pi \varepsilon.
\] (31)

The notion in the least square method is to make the error (residual) equal to zero over the entire domain (say) \(X\) in an average sense.
\[
\int_X \tilde{R}(\varepsilon) W_j(\varepsilon) d\varepsilon = 0, \quad j = 1, 2, 3, \ldots m.
\] (32)

Where weight functions and the unknown coefficients \(c_j\) are exactly equal. We take the sum of the squares of residuals rather than the sum of residuals. So, this sum is minimized and given as
\[
E = \int_X \tilde{R}(\varepsilon) \tilde{R}(\varepsilon) d\varepsilon = \int_X \tilde{R}^2(\varepsilon) d\varepsilon.
\] (33)

Now to get the minimum of the given function, the derivative of Eq. (33) concerning the unknown coefficients \(c_j\) is set to be zero. That is,
\[
\frac{\partial E}{\partial c_j} = 2 \int_X \tilde{R}(\varepsilon) \frac{\partial \tilde{R}}{\partial c_j} d\varepsilon = 0, \quad j = 1, 2, 3, \ldots m.
\] (34)

Comparing Eq. (34) with Eq. (32), the weight functions become
\[
W_j = 2 \frac{\partial \tilde{R}}{\partial c_j}.
\] (35)
Since the coefficient ‘2’ can be ignored as it vanishes in the given equation. Thus, the weight functions are given by

\[ W_j = \frac{\partial \tilde{R}}{\partial c_j}. \]  

(36)

5. Solutions

The domain of the problem under consideration is \([0, \infty]\). To convert this domain into a finite domain \([0,1]\), a transformation \(\varepsilon = \eta/\eta_\infty\) is needed [46]. \(\varepsilon\) is called a similarity variable and \(\eta_\infty\) indicates the edge of the boundary layer or physical infinity. Using the above transformation, BVP has given in Eq. (8)–(9) with Eq. (12) now becomes:

\[ \frac{A_1}{A_2} \frac{d^3 f(\varepsilon)}{d\varepsilon^3} + \eta_\infty^3 - \eta_\infty \left( \frac{df(\varepsilon)}{d\varepsilon} \right)^2 + \eta_\infty f(\varepsilon) \frac{d^2 f(\varepsilon)}{d\varepsilon^2} - M \frac{A_3}{A_2} \left( \eta_\infty \frac{df(\varepsilon)}{d\varepsilon} - \eta_\infty^3 \right) = 0, \]  

(37)

\[ \left( A_4 + R \right) \frac{d^2 \theta(\varepsilon)}{d\varepsilon^2} + \eta_\infty A_5 P_r f(\varepsilon) \frac{d\theta(\varepsilon)}{d\varepsilon} = 0. \]  

(38)

BCs:

For \(\varepsilon = 0\): \(f(\varepsilon) = 0, \quad \frac{df(\varepsilon)}{d\varepsilon} = \eta_\infty \lambda, \quad \theta(\varepsilon) = 1,\) 

For \(\varepsilon = 1\): \(\frac{df(\varepsilon)}{d\varepsilon} = \eta_\infty, \quad \theta(\varepsilon) = 0.\)  

(39)

Using Eq. (29), trial functions satisfying the boundary conditions given in Eq. (39) take the form:

\[ \hat{f}(\eta) = \eta_\infty \lambda \varepsilon + \frac{\eta_\infty (1-\lambda)}{2} \varepsilon^2 + c_1 \left( \frac{-3\varepsilon^2}{2} + \varepsilon^3 \right) + c_2 \left( \frac{-4\varepsilon^3}{3} + \varepsilon^4 \right) + c_3 \left( \frac{-5\varepsilon^4}{4} + \varepsilon^5 \right) + c_4 \left( \frac{-6\varepsilon^5}{5} + \varepsilon^6 \right), \]

\[ \hat{\theta}(\eta) = 1 - \varepsilon + c_5 (-\varepsilon + \varepsilon^2) + c_6 (-\varepsilon + \varepsilon^3). \]  

(40)

Substitution of Eq. (40) in Eqs. (37)–(38) give the two residuals:
\[
\tilde{R}_1(c_1 - c_4, \varepsilon) = 6c_1 + 30c_3 \varepsilon (2\varepsilon - 1) + 8c_2(3\varepsilon - 1) + 24c_4 \varepsilon^2 (5\varepsilon - 3) - \frac{A_1}{A_4} M \eta_\infty^2 (\varepsilon - 1) (3c_1 \varepsilon + 4c_2 \varepsilon^2 + 5c_4 \varepsilon^3 + 6c_4 \varepsilon^4 + 8c_2 \varepsilon^5) + \eta_\infty - \eta_\infty \lambda + \frac{A_1}{A_4} (\eta_\infty + \frac{\eta_\infty \varepsilon}{A_1}) (20c_3 \varepsilon^3 - 24c_4 \varepsilon^3 + 30c_4 \varepsilon^4 - 15c_3 \varepsilon^2 + 4c_2 (3\varepsilon - 2) + c_1 (6\varepsilon - 3) + \eta_\infty - \eta_\infty \lambda) (60c_3 \varepsilon^4 - 72c_4 \varepsilon^4 + 60c_4 \varepsilon^5 - 75c_3 \varepsilon^3 + 30c_1 \varepsilon (2\varepsilon - 3) + 20c_2 \varepsilon^2 (3\varepsilon - 4) + 30 \eta_\infty \varepsilon + 60 \eta_\infty \lambda - 30 \eta_\infty \lambda \varepsilon) - \eta_\infty (3c_1 \varepsilon (\varepsilon - 1) + 4c_2 \varepsilon^2 (\varepsilon - 1) - 5c_3 \varepsilon^3 + 5c_4 \varepsilon^4 - 6c_4 \varepsilon^5 + \eta_\infty \varepsilon + \eta_\infty \lambda - \eta_\infty \lambda \varepsilon)^2),
\]

and
\[
\tilde{R}_2(c_1 - c_6, \varepsilon) = 2c_5 + 6c_6 \varepsilon + \frac{A_5 P \eta_\infty}{(A_4 + R)} (-1 + c_5 (2\varepsilon - 1) + c_6 (3\varepsilon^2 - 1)){}\times
\[
\left(c_1 \left(\varepsilon^3 - \frac{3\varepsilon^2}{2}\right) + c_2 \left(\varepsilon^4 - \frac{4\varepsilon^3}{3}\right) + c_3 \left(\varepsilon^5 - \frac{5\varepsilon^4}{4}\right) + c_4 \left(\varepsilon^6 - \frac{6\varepsilon^5}{5}\right) + \frac{\eta_\infty \varepsilon^2 (1 - \lambda)}{2} + \eta_\infty \lambda \varepsilon\right).
\]

Using Eq. (36), the weight functions are obtained:
\[
W_1 = \frac{\partial \tilde{R}_1}{\partial c_1}, \quad W_2 = \frac{\partial \tilde{R}_1}{\partial c_2}, \quad W_3 = \frac{\partial \tilde{R}_1}{\partial c_3}, \quad W_4 = \frac{\partial \tilde{R}_1}{\partial c_4}, \quad W_5 = \frac{\partial \tilde{R}_2}{\partial c_5}, \quad W_6 = \frac{\partial \tilde{R}_2}{\partial c_6}.
\]

Substitution of the weights along with the residuals in Eq. (32) gives a system of six nonlinear equations in six unknowns \((c_1 - c_6)\). By applying Newton’s method [34], the unknowns \((c_1 - c_6)\) are evaluated. Finally, \(\hat{f}(\eta)\) and \(\hat{\theta}(\eta)\) for dual solutions are obtained in the following forms:

For \(Al_2O_3 - ZnO / kerosene\) hybrid nanofluid:

**The first solution** \((\lambda = -1.2, P_r = 1, R = 0.5, \phi_1 = \phi_2 = 0.1\) and \(M = 0.01\))

\[
\hat{f}(\varepsilon) = -7.2\varepsilon + 6.6\varepsilon^2 + 1.90699 \left(\varepsilon^3 - \frac{3\varepsilon^2}{2}\right) - 12.76200 \left(\varepsilon^4 - \frac{4\varepsilon^3}{3}\right) + 6.76692 \left(\varepsilon^5 - \frac{5\varepsilon^4}{4}\right) - 0.10759 \left(\varepsilon^6 - \frac{6\varepsilon^5}{5}\right),
\]

\[
\hat{\theta}(\varepsilon) = 1 - \varepsilon - 1.20773(\varepsilon^2 - \varepsilon) + 0.31052(\varepsilon^3 - \varepsilon).
\]

**The second solution** \((\lambda = -1.2, P_r = 1, R = 0.5, \phi_1 = \phi_2 = 0.1\) and \(M = 0.01\))
\[
\hat{f}(\varepsilon) = -12\varepsilon + 11\varepsilon^2 - 33.9765 \left( \varepsilon^3 - \frac{3\varepsilon^2}{2} \right) + 31.434 \left( \varepsilon^4 - \frac{4\varepsilon^3}{3} \right) - 0.564293 \left( \varepsilon^5 - \frac{5\varepsilon^4}{4} \right) - 7.57447 \left( \varepsilon^6 - \frac{6\varepsilon^5}{5} \right), \quad (43)
\]

\[
\hat{\theta}(\varepsilon) = 1 - \varepsilon + 2.82165(\varepsilon^2 - \varepsilon) - 0.889414(\varepsilon^3 - \varepsilon).
\]

For ZnO/kerosene nanofluid:

The first solution (\(\lambda = -1.2, P_r = 1, R = 0.5, \phi_1 = 0, \phi_2 = 0.1\) and \(M = 0.01\))

\[
\hat{f}(\varepsilon) = -7.2\varepsilon + 6.6\varepsilon^2 + 1.92462 \left( \varepsilon^3 - \frac{3\varepsilon^2}{2} \right) - 13.6033 \left( \varepsilon^4 - \frac{4\varepsilon^3}{3} \right) + 7.68807 \left( \varepsilon^5 - \frac{5\varepsilon^4}{4} \right) - 0.355034 \left( \varepsilon^6 - \frac{6\varepsilon^5}{5} \right), \quad (44)
\]

\[
\hat{\theta}(\varepsilon) = 1 - \varepsilon - 1.3207(\varepsilon^2 - \varepsilon) + 0.42405(\varepsilon^3 - \varepsilon).
\]

The second solution (\(\lambda = -1.2, P_r = 1, R = 0.5, \phi_1 = 0, \phi_2 = 0.1\) and \(M = 0.01\))

\[
\hat{f}(\varepsilon) = -12\varepsilon + 11\varepsilon^2 + 2.62652 \left( \varepsilon^3 - \frac{3\varepsilon^2}{2} \right) - 66.9822 \left( \varepsilon^4 - \frac{4\varepsilon^3}{3} \right) + 90.6693 \left( \varepsilon^5 - \frac{5\varepsilon^4}{4} \right) - 36.0774 \left( \varepsilon^6 - \frac{6\varepsilon^5}{5} \right), \quad (45)
\]

\[
\hat{\theta}(\varepsilon) = 1 - \varepsilon - 2.66095(\varepsilon^2 - \varepsilon) + 1.89097(\varepsilon^3 - \varepsilon).
\]

For Al_{2}O_{3}/kerosene nanofluid:

The first solution (\(\lambda = -1.2, P_r = 1, R = 0.5, \phi_1 = 0.1, \phi_2 = 0\) and \(M = 0.01\))

\[
\hat{f}(\varepsilon) = -7.2\varepsilon + 6.6\varepsilon^2 + 1.95054 \left( \varepsilon^3 - \frac{3\varepsilon^2}{2} \right) - 11.3837 \left( \varepsilon^4 - \frac{4\varepsilon^3}{3} \right) + 5.24249 \left( \varepsilon^5 - \frac{5\varepsilon^4}{4} \right) + 0.30265 \left( \varepsilon^6 - \frac{6\varepsilon^5}{5} \right), \quad (46)
\]

\[
\hat{\theta}(\varepsilon) = 1 - \varepsilon - 0.932766(\varepsilon^2 - \varepsilon) + 0.010247(\varepsilon^3 - \varepsilon).
\]

The second solution (\(\lambda = -1.2, P_r = 1, R = 0.5, \phi_1 = 0.1, \phi_2 = 0\) and \(M = 0.01\))
\[
\hat{f}(\varepsilon) = -12\varepsilon + 11\varepsilon^2 - 23.9419\left(\varepsilon^3 - \frac{3\varepsilon^2}{2}\right) - 3.15035\left(\varepsilon^4 - \frac{4\varepsilon^3}{3}\right) + 40.1955\left(\varepsilon^5 - \frac{5\varepsilon^4}{4}\right) \\
- 23.6605\left(\varepsilon^6 - \frac{6\varepsilon^5}{5}\right), \quad (47)
\]

\[
\hat{\theta}(\varepsilon) = 1 - \varepsilon + 2.29968(\varepsilon^2 - \varepsilon) - 0.610238(\varepsilon^3 - \varepsilon).
\]

6. Results and Discussion

An analytical method namely the Least square method [45] is applied to a nonlinear system of ODEs. Newton's method [44] is used to linearize the system. Dual solutions are obtained for \(\text{Al}_2\text{O}_3 - \text{ZnO}/\text{kerosene hybrid nanofluid, Al}_2\text{O}_3/\text{kerosene nanofluid, and ZnO/kerosene nanofluid. Furthermore, a stability analysis is applied to the time-dependent problem to determine a reliable solution. The comparison of three distinct fluids such as } \text{Al}_2\text{O}_3 - \text{ZnO}/\text{kerosene hybrid nanofluid, Al}_2\text{O}_3/\text{kerosene nanofluid, and ZnO/kerosene nanofluid is also made and displayed in graphs. Dual solutions occur for a shrinking case } (\lambda < 0) \text{ which is displayed in the methodology section. For the validation of numerical outcomes, a comparison of skin friction coefficient is done with the work of Wang [2] and presented in Table 3. This table depicts that the numerical findings are in good agreement, where the values in brackets specify the second solution.}

The results of the coefficient of skin friction and the local Nusselt number in graphical form are presented in Figs. 2 and 3 to give a range of dual solutions. In these figures, the solid lines correspond to 1st solution and dotted lines correspond to 2nd solution. The main focus of this paper is to implement stability analysis on the problem to check stable or physically reliable solutions. For this purpose, Tables 4 and 5 show the least eigenvalues which are found for distinct values of parameters. Positive eigenvalues correspond to the stable solution (1st solution) due to initial decline in solution and negative eigenvalues correspond to an unstable solution (2nd solution) due to initial progress of disturbance in solution. To validate the results, a comparison is made with the published work of Awaludin et al. [28] for the eigenvalues with \(M = R = \phi_1 = \phi_2 = 0\) and depicted in Table 4. Clearly, this table shows that both results are in good agreement. Processing
time is also noted and presented in this table to ensure that the Least square method converges fast as other analytical techniques such as the Homotopy analysis method (HAM).

Table 5 displays the calculated eigenvalues of the present BVP for both solutions under the effects of MHD and radiation. This table gives the comparison of three different fluids. The smallest positive and smallest negative eigenvalues are found to give 1st stable and 2nd unstable solution as described earlier. From this table, it is noticed that the increment in the values of parameters results from higher eigenvalues.

Figs. 2 and 3 depict the plots of the coefficient of skin friction and the local Nusselt number against \( \lambda \) for dual solutions with three distinct fluids when \( Pr = 1, M = 0.1 \) and \( R = 0.5 \). It is noticed that the coefficient of skin friction and the local Nusselt number for \( Al_2O_3-ZnO \)/kerosene hybrid nanofluid \( (\phi_1 = \phi_2 = 0.1) \) is higher than \( Al_2O_3 \)/kerosene nanofluid \( (\phi_1 = 0.1, \phi_2 = 0) \) and lower than \( ZnO \)/kerosene nanofluid \( (\phi_1 = 0, \phi_2 = 0.1) \). A significant change is observed in 1st solution whereas a very small variation is observed in 2nd solution. From Fig. 2, it is noted that values of the coefficient of skin friction increases for \( \lambda < 1 \) up to a certain value and then begin to decrease after this value. Fig. 3 illustrates that the rate of heat transfer for the first solution is enhanced by increasing \( \lambda \) while the second solution is very close to zero. The dual solutions range for \( Al_2O_3-ZnO \)/kerosene hybrid nanofluid is \(-1.3172 < \lambda < -1.13\), \( Al_2O_3 \)/kerosene nanofluid is \(-1.3312 < \lambda < -1.13\) and \( ZnO \)/kerosene nanofluid is \(-1.3188 < \lambda < -1.13\). Hence a larger range of dual solutions is observed with \( Al_2O_3 \)/kerosene nanofluid.

The comparison of \( Al_2O_3-ZnO \)/kerosene hybrid nanofluid \( (\phi_1 = \phi_2 = 0.1) \), \( Al_2O_3 \)/kerosene nanofluid \( (\phi_1 = 0, \phi_2 = 0.1) \), and \( ZnO \)/kerosene nanofluid \( (\phi_1 = 0, \phi_2 = 0.1) \) with \( Pr = 1, M = 0.2, \lambda = -1.35 \) and \( R = 0.5 \) is shown in Figs. 4 (a, b) and 5 (a, b), where Figs. 4a and 4b display the graph of a velocity profile \( f' (\eta) \) for the first and second solution, respectively whereas Fig. 5a represents the first and Fig.5b represents the second solution for the temperature profile \( \theta (\eta) \). It is determined from Fig. 4(a,b) that the velocity profile \( f' (\eta) \) becomes higher with \( ZnO \)/kerosene nanofluid and lower with \( Al_2O_3 \)/kerosene nanofluid while it lies in between for hybrid nanofluid. And for \( \theta (\eta) \), an opposite trend is noticed in Figs 5a and 5b such that the
temperature profile $\theta(\eta)$ for hybrid nanofluid is smaller than $Al_2O_3/kerosene$ nanofluid but larger than $ZnO/kerosene$ nanofluid.

Figs. 6 and 7 show the impacts of velocity ratio parameter $\lambda$ on $f'(\eta)$ and $\theta(\eta)$, respectively for $Al_2O_3-ZnO/kerosene$ hybrid nanofluid ($\phi_1 = \phi_2 = 0.1$), $Al_2O_3/kerosene$ nanofluid ($\phi_1 = 0.1, \phi_2 = 0$), and $ZnO/kerosene$ nanofluid ($\phi_1 = 0, \phi_2 = 0.1$) with $Pr = 1$, $M = 0.05$ and $R = 0.5$. It is examined from Fig. 6 that the velocity profile increases $\lambda$ while Fig. 7 depicts that the temperature profile decreases when $\lambda$ is increased. It is concluded from these figures that the behavior of $\lambda$ is the same for all three types of fluid.

Fig. 8 displays the influence of radiation parameter $R$ on $\theta(\eta)$ in case of hybrid nanofluid for dual solutions at $\phi_1 = \phi_2 = 0.1, P = 1, \lambda = -1.25$ and $M = 0.1$. It is observed that the increment in the values of radiation parameter increases $\theta(\eta)$ for 1st solution but in the case of 2nd solution $\theta(\eta)$ decreases initially and then after a certain point, it begins to increase.

**Table 3** Comparison of coefficient of skin friction $f''(0)$ with $R = M = \phi_1 = \phi_2 = 0$.

| $\lambda$ | Wang [2] | Present study |
|-----------|----------|---------------|
| 1         | 0        | 0             |
| 0.5       | 0.71330  | 0.71330       |
| 0         | 1.23258  | 1.23258       |
| -0.25     | 1.40224  | 1.40224       |
| -0.5      | 1.49567  | 1.49567       |
| -0.75     | 1.48930  | 1.48930       |
| -1        | [0]      | [0]           |
| -1.15     | [0.11670]| [0.11670]     |

**Table 4:** Comparison for smallest eigenvalues $\gamma$ with $M = R = \phi_1 = \phi_2 = 0$ and $Pr = 1$.

| $\lambda$ | Awaludin et al. [28] | Present study | CPU time (s) |
|-----------|----------------------|---------------|--------------|
|           | 1st solution | 2nd solution | 1st solution | 2nd solution |               |
| -1        | 1.3690       | ---          | 1.3690       | ---          | 22.801        |
| -1.1      | 1.0463       | -0.8437      | 1.0463       | -0.8437      | 23.701        |
| -1.2      | 0.5780       | -0.5173      | 0.5780       | -0.5173      | 23.167        |
1.24  0.2121  -0.2036  0.2121  -0.2036  23.366
-1.245  0.1030  -0.1010  0.1030  -0.1010  23.790
-1.246  0.0622  -0.0614  0.0622  -0.0614  23.303

Table 5: Comparison of smallest eigenvalues $\gamma$ for three fluids with $M = 0.1$, $R = 0.5$ and $P_r = 1$

| $\lambda$ | $A_l_2O_3 - ZnO / kerosene$ ($\phi_1 = \phi_2 = 0.1$) | $A_l_2O_3 / kerosene$ ($\phi_1 = 0.1, \phi_2 = 0$) | $ZnO / kerosene$ ($\phi_1 = 0, \phi_2 = 0.1$) |
|-----------|---------------------------------|---------------------------------|---------------------------------|
|           | 1$^{st}$ solution  | 2$^{nd}$ solution  | 1$^{st}$ solution  | 2$^{nd}$ solution  | 1$^{st}$ solution  | 2$^{nd}$ solution  |
| -1.18     | 1.0182  | -0.8281  | 1.0723  | -0.8614  | 1.0247  | -0.8323  |
| -1.20     | 0.9381  | 0.7787   | 0.9963  | -0.8152  | 0.9457  | -0.7821  |
| -1.21     | 0.8952  | -0.7501  | 0.9562  | -0.7907  | 0.9032  | -0.7551  |
| -1.23     | 0.8059  | -0.6874  | 0.8712  | -0.7344  | 0.8131  | -0.6931  |
| -1.25     | 0.7033  | -0.6141  | 0.8724  | -0.6681  | 0.7982  | -0.6215  |
| -1.27     | 0.5851  | -0.5237  | 0.6713  | -0.5901  | 0.5961  | -0.5324  |
| -1.29     | 0.4416  | -0.4053  | 0.5472  | -0.4932  | 0.4551  | -0.4170  |
| -1.30     | 0.3480  | -0.3268  | 0.4756  | -0.4331  | 0.3651  | -0.3410  |
| -1.31     | 0.2234  | -0.2141  | 0.3892  | -0.3612  | 0.2486  | -0.2373  |

Fig. 2. Comparison of three distinct fluids for $f''(0)$. 
Fig. 3. Comparison of three distinct fluids for \(-\theta'(0)\).

Fig. 4a. Comparison of three distinct fluids for 1st solution of \(f'\).  

Fig. 4b. Comparison of three distinct fluids for 2nd solution of \(f'\)
Fig. 5a. Comparison of three distinct fluids for 1st solution of $\theta(\eta)$.

Fig. 5b. Comparison of three distinct fluids for 2nd solution of $\theta(\eta)$.

Fig. 6. Variations of $\lambda$ on $f'(\eta)$ for three distinct fluids.
7. Conclusion

The BVP presented in Eqs. (8) – (9) and Eq. (12) are solved analytically using the Least square method (LSM). This analytical method is so simple and easy that it can be applied to any BVP. This method takes less time for finding solutions than the homotopy analysis method (HAM). Dual solutions are computed with the influence of MHD and radiation for three different fluids and the range of dual solutions is larger with $Al_2O_3$ / kerosene nanofluid. Moreover, stability analysis is applied to check stable or physically reliable solutions. The eigenvalues are evaluated for various parameters, where the positive eigenvalues are related to stable solutions and negative eigenvalues
are related to the unstable solution. Higher eigenvalues are found with the effects of MHD. \( \theta(\eta) \) enhances with the enhancement of radiation parameter \( R \) for 1st solution but declines initially for 2nd solution and then after a certain value, it begins to increase.

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