Astroinformatics of galaxies and quasars: a new general method for photometric redshifts estimation

O. Laurino,1,2,⋆ R. D’Abrusco,2 G. Longo3,4† and G. Riccio3

1 Astronomical Observatory of Trieste, INAF, Trieste 34143, Italy
2 Harvard-Smithsonian Center for Astrophysics, Cambridge, MA 02138, USA
3 Department of Physical Sciences, University of Naples, Naples 80126, Italy
4 Department of Astronomy, California Institute of Technology, Pasadena, CA 90125, USA

Accepted 2011 July 10. Received 2011 June 17; in original form 2011 March 9

ABSTRACT

With the availability of the huge amounts of data produced by current and future large multi-band photometric surveys, photometric redshifts have become a crucial tool for extragalactic astronomy and cosmology. In this paper we present a novel method, called Weak Gated Experts (WGE), which allows us to derive photometric redshifts through a combination of data mining techniques. The WGE, like many other machine learning techniques, is based on the exploitation of a spectroscopic knowledge base composed by sources for which a spectroscopic value of the redshift is available. This method achieves a variance \( \sigma^2(\Delta z) = 2.3 \times 10^{-4} \) \([\sigma^2(\Delta z) = 0.08, \text{ where } \Delta z = z_{\text{phot}} - z_{\text{spec}}]\) for the reconstruction of the photometric redshifts for the optical galaxies from the Sloan Digital Sky Survey (SDSS) and for the optical quasars, respectively, while the root mean square (rms) of the \( \Delta z \) variable distributions for the two experiments is, respectively, equal to 0.021 and 0.35. The WGE provides also a mechanism for the estimation of the accuracy of each photometric redshift. We also present and discuss the catalogues obtained for the optical SDSS galaxies, for the optical candidate quasars extracted from the Data Release 7 of SDSS photometric data set (the sample of SDSS sources on which the accuracy of the reconstruction has been assessed is composed of bright sources, for a subset of which spectroscopic redshifts have been measured) and for optical SDSS candidate quasars observed by \( \text{GALEX} \) in the ultraviolet range. The WGE method exploits the new technological paradigm provided by the virtual observatory and the emerging field of astroinformatics.

Key words: methods: data analysis – techniques: photometric – catalogues – surveys – virtual observatory tools – cosmology: observations.

1 INTRODUCTION

The ever growing amount of astronomical data provided by the new large-scale digital surveys in a wide range of the expectation maximization (EM) spectrum has been challenging the way astronomers carry out their everyday analysis of astronomical sources. These new data sets, for their sheer size and complexity, have extended beyond the human ability to visualize and correlate complex data, thus triggering the birth of the new technological approach and methodology which is often labelled as ‘astroinformatics’, a new discipline which lies at the intersection of many others: data mining (DM), parallel and distributed computing, advanced visualization, web 2.0 technology, etc. (Ball & Brunner 2010; Borne 2010). X-informatics (where the X stands for any data rich discipline) is growingly being recognized as the fourth leg of scientific research after experiment, theory and simulations (see The Fourth Paradigm; Hey et al. 2009). In this paper we shall present a new method for the estimation of photometric redshifts which fully take advantage of many of these new methodologies.

In the past, for many tasks such as, for instance, classifying different types of sources, determining the redshifts of galaxies, etc. astronomers had to rely mainly on spectroscopic observations which are still very demanding in terms of precious telescope time. Even though spectroscopy is still fundamental to gain insights into many physical processes, the unprecedented abundance of accurate photometric observations for very large samples of sources has led to the development of what we can call candidates astronomy, i.e. the branch of astronomy which exploits photometry to accomplish tasks which in the past would have required spectroscopic data. This discipline stems from a long and rich tradition of astronomical techniques based on the use of photometric information in low-dimensional features space (e.g. colour–colour selection...
techniques). The main differences relative to these classical methodologies reside in the statistical techniques and the size of the data set considered (in terms of both the number of members and the dimensionality of the data sets). In those cases where a very accurate evaluation of the uncertainties affecting the estimate is possible, the loss of accuracy and effectiveness which is implicit in candidates astronomy is compensated by the possibility to obtain very extensive samples with limited effort. In the last few years, candidates astronomy has found many applications, such as, for instance, the determination of the spatial distribution of visible matter on very large scales through photometric redshifts (Arnalte-Mur et al. 2009). In such cases, the statistical tools used to characterize the description of the distribution of the sources are specifically designed to trade-off between the lower accuracy of the derived quantities (e.g. photometric redshifts with respect to spectroscopic ones) and the increased statistics arising from the significantly larger size of the samples of sources. Another example is the study of the distribution of quasars through the use of photometric redshifts and reliable catalogues of candidate quasars selected on the basis of their photometric properties rather than through spectroscopic confirmations.

The advantages of candidates astronomy over traditional astronomy are obvious: for instance, in the latter case, the number of quasars selected via spectroscopic identification in the Sloan Digital Sky Survey (SDSS) Data Release 7 (DR7) is $\sim 1.05 \times 10^6$ (Schneider et al. 2010), while the number of candidate quasars extracted from photometric data with effective methods involving the modelling of the distribution of sources in the colour space is almost an order of magnitude larger, ranging from $\sim 10^6$ found by Richards et al. (2009) to the higher $2.1 \times 10^6$ in D’Abrusco et al. (2009), the latter figures being much closer to the theoretically predicted number of quasars expected to lie within the limiting flux of the SDSS, $\sim 1.3 \times 10^6$ reported in Richards et al. (2009).

Photometric redshifts are important for a large spectrum of cosmological applications, such as, to quote just a few: weak lensing studies of galaxy clusters (Abdalla et al. 2008), the determination of the galaxy luminosity function (Subbarao et al. 1996), studies of specific types of cosmic structures like, for instance, the photometric redshifts derived in D’Abrusco et al. (2007) which were used to investigate the physical reality of the so-called Shakbibzhanian groups, to derive their physical characteristics as well as their relations with other galaxy structures of different compactness and richness (Capozzi et al. 2009).

Many different methods for the evaluation of photometric redshifts are available in literature. Without entering into much detail, it is worth reminding that all methods are based on the interpolation of a priori knowledge available for more or less large sets of templates and differ among themselves only in one or both of the following aspects: (i) the way in which the a priori knowledge base (KB; for a detailed definition of KB, see Section 2) is constructed [higher accuracy spectroscopic redshifts or empirically or theoretically derived spectral energy distributions (SEDs)l, and (ii) the interpolation algorithm or method employed. In this context, modern wide-field mixed surveys combining multiband photometry and fibre-based spectroscopy and thus providing both photometric data for a very large number of objects and spectroscopic information for a smaller but still significant subsample of the same population, provide all the information needed to constrain the fit of an interpolating function mapping the space of the photometric features. Most if not all photometric redshifts methods have been tested on the SDSS which is a remarkable example of these ‘mixed surveys’, which has allowed noticeable advancements in the field of extragalactic astronomy and, over the years, has also become a sort of standard benchmark to evaluate performances and biases of different methods. None the less, it should be noticed that the SDSS spectroscopic sample is not unbiased, since limited to a bright subset of galaxies and quasars observed in the optical range and selected according to spectroscopic methods. The peculiar characteristics of the source samples for which both photometric and spectroscopic measurements are available should always borne in mind when considering the effectiveness of the machine learning (ML) methods tested.

As it will become evident in Section 3, one of the main problems encountered in evaluating photometric redshifts is the critical dependence of the final accuracy on the parameters needed to fine-tune the method and the nature of the sources (i.e. galaxies or quasars). For example, in the template fitting methods, part of the degeneracy between the spectroscopic redshift and colours of the sources can be minimized by a wise choice of the SED templates (Bruzual 2010), at the cost of introducing biases in the final estimates of the photometric redshifts.

In other DM applications the same degeneracy can be minimized by applying priors derived from the distribution of the spectroscopic redshifts for the sources belonging to the KB, like in D’Abrusco et al. (2007).

In what follows, we shall just summarize some aspects which appear to be relevant for the class of the interpolative methods. Such methods differ in the way the interpolation is performed, and the main source of uncertainty is the fact that the fitting function is just an approximation of a more complex and unknown relation (if any) existing between colours and the redshift (e.g. see Csatari et al. 2003). Moreover, due to different observational effects and emission mechanisms, a single approximation can hold only in a given range of redshifts or in a limited region of the features space (D’Abrusco et al. 2007). In the last few years, in order to overcome the effects of the oversimplification of the relation between observables and spectroscopic redshifts, several methods based on statistical techniques for pattern recognition aimed at the accurate reconstruction of the photometric redshifts for both galaxies and quasars have been developed (and in most cases applied to SDSS data): polynomial fitting (Connolly et al. 1995; Budavari et al. 2001; Li & Yee 2008), nearest neighbours (Budavari et al. 2001; Csatari et al. 2003; Ball et al. 2008), neural networks (Firth, Lahav & Somerville 2003; Collister & Lahav 2004; Vanzella et al. 2004; Collister, Lahav & Blake 2007; D’Abrusco et al. 2007; Yeche et al. 2010), support vector machines (Wadadekar 2005), regression trees (Carliles et al. 2010), Gaussian processes (Way & Srivastava 2006; Bonfield et al. 2010), diffusions maps (Freeman et al. 2009) and Gaussian mixtures (Bovy et al. 2011).

These methods, when applied to SDSS galaxies in the local universe (i.e. $z < 0.5$), lead to similar results, with a dispersion $\text{rms}(\Delta z) \sim 0.02$. The extension of these methods to the intermediate-redshifts range ($z < 0.8$) is in theory possible for both quasars and galaxies and for the brightest sources in the SDSS data set, by adding near-infrared photometry to the Sloan optical photometry and by using as KB the large SDSS spectroscopic sample, sometimes combined with redshifts measured in other deeper surveys like, for instance, the 2dF-SDSS LRG and QSO (2SLAQ; Crook et al. 2004). Even though in this redshift range the estimated photometric redshifts seem not to be affected by any peculiar systematic effect, all these methods suffer from strong degeneracies in specific regions of the photometric features space when applied to sources, like quasars, which can be found at larger redshifts and whose spectra typically present strong emission and absorption features.
off and in the photometric filters adopted in a specific instrument (like shown for SDSS quasars in Ball et al. 2008).

Such degeneracies manifest themselves mainly through high local fractions of catastrophic outliers, i.e. sources with photometric redshifts estimates differing dramatically from the spectroscopic value. Some of the previously mentioned techniques address the problem of the catastrophic outliers by providing probabilistic estimates of the photometric redshifts (Ball et al. 2008), at the cost of an increased computational burden, which may lead to an overall worse scalability. The Weak Gated Experts (WGE) method described in this paper has been designed to be accurate, relatively fast when compared to the other approaches available in literature and easily scalable in order to allow the processing of very large throughputs (like those that will be produced by the large synoptic surveys of the future). As it will be discussed in what follows, the WGE method is general and comprehensive since it adapts to different types of sources without requiring a specific fine-tuning. The WGE is the second step of an automated ML method whose ultimate goal is to ease the exploitation of ongoing and planned multiband extragalactic surveys. While not completely removing the catastrophic outliers (task which is impossible to achieve due to the physical limitations, as mentioned above), WGE achieves a fair characterization of the regions of the photometric feature space where the degeneracies happen and is consistently able, as discussed in Section 9, to flag the photometric redshifts values which most likely are catastrophic outliers. It is worth noticing that in our analysis we never take into account possible time variability as it is done, for instance, in Salvato et al. (2009).

The paper is structured as follows. In Section 2, the general features and design principles of the WGE method are discussed. In Sections 3 and 4, more details of the specific implementation of the WGE used for the problem of photometric redshift reconstruction and of the algorithms employed are provided. The description of the data sets used for the experiments¹ and the feature selection criteria can be found in Section 5, while the experiments for the determination of photometric redshifts for galaxies and quasars are described in Section 6. The final catalogues of photometric redshifts for the SDSS galaxies and candidate quasars are presented in Sections 7.1, 7.2 and 7.3, respectively, together with details on the distribution of the catalogues to the community. A thorough discussion of the performances of the method for the reconstruction of the photometric redshifts can be found in Section 8, while the determination of the errors on the photometric redshifts estimates and the discussion of the catastrophic outliers are described in Section 9. The conclusion and a summary of the results can be found in Section 10.

2 THE UNDERLYING DATA MINING METHODOLOGY

The WGE method is a supervised DM model which aims at the reconstruction of a quantity, namely the target (in this case the redshift of the astronomical sources) through a local reconstruction of an empirical relation between the observed features of a sample of sources having otherwise measured targets (in this case, the spectroscopic redshifts). In the implementation discussed here, the WGE consists of a combination of clustering and regression techniques. In order to better explain how the WGE works, some DM concepts and definitions will be given in Sections 2.1, 2.2 and 2.3.

2.1 Supervised versus unsupervised

In the domain of ML methods, the problem of the extraction of knowledge from data can take place following two approaches: supervised and unsupervised learning. From this general point of view, the ML process can or cannot be derived from a set of well-known examples. In the case of supervised learning, an unknown mapping function (the model) between the features of a sample of sources and the corresponding targets can be determined using an a priori KB. This approach is useful when the relation is either unknown or too complex to be treated analytically, as it is often the case with astronomical data sets. The usage of supervised ML algorithms requires three basic steps.

(i) Training: in this phase, the algorithm is trained by examples extracted from the KB to derive a model.

(ii) Test: the model is tested against a set of data extracted from the KB but not used for training. Results are used to evaluate both the degree of generalization and the overall error on the reconstruction of the target values.

(iii) Run: the model is used to predict the values of the targets for new input patterns.

Optionally, a validation phase may be implemented in order to avoid overfitting on the training set. Validation works exactly like the test phase, the difference being that the model is chosen according to the minimum validation error instead of using the training error.

However, the extraction of knowledge can also take place without using any a priori targets, i.e. using only the statistical properties of their features distribution. In this case, the approach is said to be unsupervised, and the knowledge extraction process is driven from the statistical properties of the data themselves. In practice, all these techniques are not driven by hypotheses, as it happens in more classical approaches, but are driven solely by the data. This means that, while allowing a large set of unprecedented analysis methods, the DM approach leads to its own hypotheses, which may be then validated through, for instance, subsequent analysis or additional observations (in the case of photometric redshifts estimation, for example, spectroscopic follow-up observations aimed at confirming the estimated values of $z_{\text{spec}}$).

2.2 Clustering

The most representative example of unsupervised analysis is the clustering of a population of data points associated to objects and defined by the so-called features vector, obtained by partitioning the data set into an arbitrary number of subsets. Each subset consists of objects that can be considered close to each other by some metric definition, and are far from objects belonging to other clusters. As before, clustering may be said to be supervised when the final number of clusters is assumed a priori, while unsupervised clustering applies in the case the algorithm itself determines the optimal number of clusters representing the spatial features of a data set in the features space. Different clustering algorithms tend to produce different sets of possible clusterings, associating each clustering with statistical figures so that the best or more efficient clustering can be determined off-line.

2.3 Regression

Regression is defined as the supervised search for the mapping from a domain in $\mathbb{R}^m$ to $\mathbb{R}^n$, with $m < n$; a regressor is thus a model that performs a mapping from a features space $X$ to a target space $Y$. In

1 Throughout this paper, the word experiment will refer to a complete run of the WGE method, as customary in the DM jargon.
order to find this mapping function without any prior assumption on its explicit form, one can train a supervised method, providing it with a set of examples. The problem can be formally stated as follows: given a set of training data (training set) \( \{(x_1, y_1), \ldots, (x_n, y_n)\} \) a regressor \( h: X \rightarrow Y \) maps a predictor variable \( x \in X \) to the response variable \( y \in Y \).

### 3 THE WEAK GATED EXPERTS METHOD

The WGE method is an example of how a combination of different DM techniques can prove very effective at overcoming some of the degeneracies that can be present in high-dimensional data sets which are typical of astronomical observations. As it was stated before, in a supervised method the first step is obtaining a predictor by training a model on a training set. Since the WGE is itself a supervised method, in order to obtain a predictor it has to be trained (a general definition for the concept of training, validation and test for supervised ML algorithms can be found in Section 2.1). At a high level of abstraction, the training of the WGE method (see Section 4 for a description of the actual implementation of the method) can be summarized in three distinct steps.

(i) Partitioning of the features space.

(ii) For each partition of the feature space, a model for a predictor is determined (an expert). This predictor maps each pattern of the features space to the target space. The outputs of the predictors associated to the various regions of the partition define a new features space.

(iii) A new gate predictor is trained to map the patterns extracted from the new feature space to the target values. This new space is an extension of the original one with the addition of the experts predictions.

Different partitions of the features space need to be tried in order to increase the accuracy of the redshift reconstruction and reduce the uncertainties. However, in this case, the results must be validated against a validation set in order to assess data overfitting (i.e. a particular decomposition of the features space may lead to an accidental improvement in the reconstruction which depends solely on the data set used to train the predictors). The whole model is then tested against the test set to measure the level of generalization achieved and to characterize the errors.

The gate predictor combines the responses from the experts in order to find patterns in the responses themselves, taking into account the input features as well. In this way, the gate predictor can resolve part of the degeneracies and provide better results.

The implementation of the WGE method which has been used for this work uses multilayer perceptron (MLP) neural networks as experts and will be described in the following sections where arguments justifying its application to the determination of the photometric redshifts for quasars with optical wide-band photometry will be provided. It will also be shown that the WGE can be used to improve the overall performance of the reconstruction of the photometric redshifts as well. In this regard, the WGE improves over some of the caveats of the method proposed in D’Abrusco et al. (2007) by providing a more robust approach, a large improvement in the accuracy of the redshifts determination according to most statistical diagnostics and a substantial refinement in the characterization of the uncertainty on the \( z_{\text{phot}} \) estimation and the determination of the outliers. In conclusion, the WGE is general and can be applied without any differences to the problem of the estimation of the photometric redshifts of all types of the extragalactic sources.

The training, validation and test sets for the three different experiments with the WGE method have been randomly drawn from the KB, composed, respectively, by the 60, 20 and 20 per cent of the total number of KB members.

#### 3.1 MLP predictors

Feed-forward neural networks provide a general framework for representing non-linear functional mappings between a set of input variables and a set of output variables (Bishop 1996). This goal can be achieved by representing the non-linear function of many variables as the composition of non-linear activation functions of one variable. A MLP may be schematically represented by a graph: the input layer is made of a number of perceptrons equal to the number of input variables, while the output layer will have as many neurons as the output variables (targets). The network may have an arbitrary number of hidden layers which in turn may have an arbitrary number of perceptrons. In a fully connected feed-forward network each node of a layer is connected to all the nodes in the adjacent layers. Each connection is represented by an adaptive weight representing the strength of the synaptic connection between neurons. In general, along with the regular units, a feed-forward network presents a bias parameter for each layer. The bias parameter of the \( k \)th layer is added to the activation function input of all the nodes in the \( k + 1 \)th layer. We consider a generic feed-forward network with \( d \) input units, \( c \) output units and \( M \) hidden units in a single hidden layer. This kind of network can also be defined as a two-layer network, counting the number of connection layers instead of the number of perceptron layers. The output of the \( j \)th hidden unit of the \( i \)th hidden layer is first obtained by calculating the weighted sum of the inputs:

\[
d_{ij}^{(k)} = \sum_{i=0}^{d} w_{ji}^{(k)} z_{i}^{(k-1)},
\]

where \( w_{ji}^{(k)} \) indicates the weight associated to the connection from the \( k - 1 \)th layer to the \( j \)th node of the \( k \)th layer, and \( z_{i} \) is the activation state of the unit, the sum running from 0 to \( d \) and including the bias parameter in the \( k - 1 \)th units as \( w_{ji}^{(k-1)} = b_{j-1} \) with a constant activation state \( z_{i}^{(k-1)} = 1 \). Then, the output of the \( j \)th unit of the \( k \)th layer is

\[
z_{j}^{(k)} = g \left( d_{ij}^{(k)} \right),
\]

where \( g() \) is the activation function. In general, different nodes may have different activation functions even in the same layer. Most of the times, two distinct activation functions are set for the hidden layers and the output layer. The output is obtained by combining these activation functions through the network. For the \( k \)th output unit,

\[
y_{k} = \frac{1}{\sum_{j=0}^{M} w_{kj}^{(2)} g \left( \sum_{i=0}^{d} w_{ji}^{(1)} x_{i} \right)}. \tag{3}
\]

If the output activation function is linear \((g(a) = a)\), the network output reduces to

\[
y_{k} = \frac{1}{\sum_{j=0}^{M} w_{kj}^{(2)} \left( \sum_{i=0}^{d} w_{ji}^{(1)} x_{i} \right)}. \tag{4}
\]

One of the most common differentiable activation functions, that is usually used to represent smooth mappings between continuous variables, is the logistic sigmoid function, defined as

\[
g(a) = \frac{1}{1 + e^{-a}}.
\]
where $\sigma$ is called steepness. The application of the logistic function requires the features to be normalized in the interval $[-1, 1]$. In what follows we shall refer to the topology of a MLP and to the weights matrix of its connections as to the model. In order to find the model that best fits the data, it is necessary to provide the network with a set of examples, i.e. the training set extracted from the KB. One of the methods for the determination of such model depends on the minimization of a cost function. The backpropagation (BP) is a common algorithm for cost function minimization implemented, in its simplest form, as an iterative gradient descent of the cost function itself. An important role in BP is played by the learning rate, which can be viewed as the ‘aggressiveness’ with which the algorithm updates the weights matrix in each iteration (or epoch). The BP halts when either an error threshold is hit or a maximum number of iterations is reached.

### 3.2 Regression with MLP

Photometric redshifts estimation is a regression problem. Regression, as already reminded in Section 2.3, is defined as the task of predicting the dependent variable $y \in \mathbb{R}^n$ from the input vector $x \in \mathbb{R}^m$ consisting of $M$ random variables. The input data $(x_i | k = 1, 2, \ldots, K)$ may be assumed to be selected independently with probability density $P(x)$. The outputs $(y_i | k = 1, 2, \ldots, K)$ are generated following the standard signal-plus-noise model:

$$y_i = f(x_i) + \epsilon_i,$$  

(5)

where $(\epsilon_i | k = 1, 2, \ldots, K)$ are zero-mean random variables with probability density $P(\epsilon)$. The learning procedure of a neural network aims at minimizing a cost function, for example the mean square error (MSE) defined as

$$\text{MSE} = \frac{1}{K} \sum_{k=1}^{K} (y_k - f(x_k))^2.$$  

(6)

In this way, the best regressor is represented by $E(y|x) = \int yP(y|x) \, dy = f(x)$, where $E$ stands for expectation. Unbiased neural networks asymptotically ($K \rightarrow \infty$) converge to the regressor. Uncertainties in the independent variable can be accounted for by assuming that it is not possible to sample any $x$ directly, and by instead sampling the random vector $z \in \mathbb{R}^n$ defined as

$$z_i = x_i + \delta_i,$$  

(7)

where $\delta_i$ are the independent random vectors extracted from the probability distribution $P_\delta(\delta)$. A neural network trained with data $\{(z_i, y_i) | k = 1, 2, \ldots, K\}$ approximates the function

$$E(y|z) = \frac{1}{P(z)} \int yP(y|x)P(z|x)P(x) \, dy \, dx$$  

$$= \frac{1}{P(z)} \int f(x)P(z-x)P(x) \, dx.$$  

(8)

This means that, in general, $E(y|z) \neq f(z)$. The equality holds only when there is no noise. If noise is assumed to be Gaussian, it can be shown (Tresp et al. 1994) that, in some cases, $E(y|z)$ is the convolution of $f$ with the noise process $P_\delta(z-x)$.

At a very high level of abstraction and in the light of the details of the approach discussed in the previous paragraphs, the WGE is a regressor trained to reproduce as accurately as possible the unknown correlation between features and targets. Moreover, as it will be shown, the implementation discussed here is based on MLP algorithm. In the training phase, the WGE learns how to map the features space into the target space (i.e. the photometric feature space to the redshift space):

$$\text{WGE}_{\text{train}} : p \rightarrow z_{\text{spec}},$$  

(9)

where $p$ is the vector representing a position in the photometric feature space and $z_{\text{spec}}$ is the corresponding value of the photometric redshift. Once trained, the WGE is used to evaluate photometric redshifts:

$$z_{\text{phot}} = \text{WGE}(p).$$  

(10)

### 3.3 The Gated Experts

In most cases involving the determination of photometric redshifts, there is not a continuous mapping function from the features space to the target space and, therefore, a single MLP cannot produce an accurate reconstruction of the colour–redshift relation (D’Abrusco et al. 2007). Furthermore, there is not a single global noise regime throughout the features space. Degeneracies are an example of how the noise regime changes in different colours intervals. Moreover, the input and target noises depend also on the measured magnitude of the sources and, in turn, on their distance from the observers which is the information encoded in the redshift itself. Since the arbitrary distribution of the sources depends on the distance, the noise will depend on the input as well. Finally, in the case of statistically undersampled populations of sources like, for instance, high-redshift quasars, the sparseness of the KB itself varies with the value of the colours, i.e. over the regions of the features space where the KB is defined. The attempt to learn the mapping function on different regions of the input space with different noise levels and different densities using a single network is likely to fail since the network can either extract features that do not generalize well in some regions (local overfitting), or cannot fully exploit all the information potentially contained in other regions (local underfitting).

In other terms, since the cost function is unique for a single network, a local overfitting in some regions may be compensated (in terms of contribution to the overall error) by a local underfitting in other regions. For this reasons, a more complex architecture, following the mixture of experts paradigm (Jordan & Jacobs 1994) turns out to be more effective.

The basic idea behind experts is in fact to learn different local models from data residing in different regions of the feature space. These experts are specialized over their subdomain and their outputs are linearly combined to form the overall output of the method. The gated experts are somehow different since they non-linearly combine non-linear experts. The input space is also non-linearly split into subspaces and one gating network$^1$ is trained to learn both the partitioning of the input space and the input-dependent coefficients $g_i(x)$ that are then combined to yield the system outputs $y_i(x)$:

$$y = \sum_{i=1}^{M} g_i(x)y_i(x).$$  

(11)

$^2$ Although a single global model can, at least in principle, approximate any function even if piecewise defined, in real world problems it is very difficult or impossible to extract such global model from the data. In these cases the error function is very complex and the BP process is likely to end in a local minimum.

$^3$ The gating network is, as a matter of fact, acted by a committee of neural networks. This approach is necessary in order to find the best bias-variance trade-off (Krogh & Vedelsby 1995).
where \( M \) is the number of experts. This problem cannot be addressed by means of supervised learning only because in general it is not possible to infer any a priori knowledge about the best partitioning of the input space. For this reason, a complex cost function has to be derived to take into account all the variables. The method for deriving this cost function is known (Weigend 1995), but it is necessary to bear in mind a few cautions.

(i) The cost function cannot be minimized with gradient descent but the problem itself can be reformulated and addressed by means of an EM algorithm.

(ii) In order to find a consistent solution, it is necessary to assume that one and only one expert is responsible for each pattern. In other terms, it is necessary to make sure that there is a way of isolating different subprocesses throughout the features space. As it will be shown in Section 4.1, for the reconstruction of the photometric redshifts of quasars, this assumption is false due to degeneracies.

4 WEAK GATED EXPERTS IMPLEMENTATION

In the implementation of the WGE used for the experiments described in this paper, each expert is a standard neural network that learns a function \( y_i(x) \) by means of a sigmoidal activation function hidden layer and a linear activation function output layer, as discussed in Section 3.1. The gating network, instead, has a classification flavour since its \( K \) nodes in the output layer have a softmax activation function:

\[
g_j = \frac{e^{u_j}}{\sum_{i=1}^{K} e^{u_i}},
\]

where \( s_j(x) \) is the output of the \( j \)th node in the hidden layer. The outputs of the gating network are normalized to unity and their values express the competition among different experts, which is meant to be a soft competition since each input pattern has a non-null probability of being in the domain of each expert (see Section 4.1).

The gated experts are combined through a non-linear superposition. This task, usually performed by an EM procedure together with the partition of the input space, in the WGE method is emulated by a ‘weak’ gating network, using a MLP network in a regression configuration and using the observed photometric features and the outputs of the experts as features. While trying to take advantage of the gated experts strengths, the WGE also takes into account the knowledge of the specific problem, from an astronomical point of view, as discussed in the following sections. A diagram of the implementation of the WGE method used in the paper is shown in Fig. 1. In this plot, for the sake of simplicity, only one gating network is shown.

4.1 Partitioning of the feature space

The gated experts method requires an unsupervised approach to the partitioning of the input space. It is well known that the colour distribution of extragalactic sources changes noticeably with the redshift, so that it is possible to determine distinct regions of the features space where the colour–redshift correlation follows different regimes. For instance, in Fig. 2 it is shown the distribution of the sample of quasars observed spectroscopically by the SDSS in the DR7 in the \( u - g \) versus \( g - r \) colour–colour plot, where the colour scale express the spectroscopic redshifts of the sources. Two main regions are clearly identified: a compact one where most of the objects lie, having redshifts in the interval \( z_{\text{spec}} = [0, \sim 2.5] \), and a vast region where the points are sparse and redshifts are larger than 2 with very few exceptions. From an astrophysical standpoint, this can be explained with the fact that the Lyman break at redshift \( \sim 3 \) enters the optical SDSS \( u \) filter, in turn yielding larger values of the \( u - g \) colour. The inset zooms in the densest region of the plot, where most of the degeneracies arise. Although this plot shows a bi-dimensional projection of the four-dimensional features space (where it is possible that some of the degeneracies are resolved), this particular window is characterized by sources with similar colours and very different redshifts. These facts suggest that it is possible to divide the input space into different regions, two or more inside the window and one or more outside. Even if it is unknown a priori whether the mapping function changes between these subdomains, as it will be shown in Section 5.1, the error and noise regimes are different in such regions and, in particular, the densest ones are heavily affected by degeneracies while the others are mostly characterized by sparseness in the distribution of the points. In order to partition the input space, the implementation of the WGE method used for determination of the photometric redshifts employs a fuzzy version of a simple but effective clustering algorithm, namely the fuzzy k-means, or \( \varepsilon \)-means (Dunn 1973). The classical \( k \)-means
Figure 2. Spectroscopically selected quasars in the SDSS DR7 data set in the \( u - g \) versus \( g - r \) plot. The colour of the symbols is associated to the spectroscopic redshift of the sources.

algorithm (hereafter ‘sharp’ \( k \)-means, opposed to the fuzzy counterpart), given the number of clusters \( k \) and a metric definition, finds the centroids that minimize the distance with the objects belonging to their clusters while maximizing the distance among them by an iterative method. When convergence is reached, each point in the input space belongs to one and only one cluster. A different version of the sharp \( k \)-means algorithm, namely the \( c \)-means, works exactly like its sharp counterpart for what finding cluster centroids is concerned, except that, in this case, each source belonging to the input sample has a non-null probability of being a member of every cluster found by the algorithm, even of very distant ones. In particular, each point \( x \) belongs to the \( k \)th cluster (identified with its centroid \( c_k \)) with a membership degree \( u_k(x) \) given by

\[
u_k(x) = \frac{1}{\sum_j[d(c_k, x)/d(c_j, x)]^2/(m-1)},\tag{13}\]

where \( d(c_k, x) \) is the distance of the point \( x \) from the \( k \)th cluster and \( m \) is a positive integer, which determines the normalization of the coefficients of the clustering. In this paper, the parameter has been fixed to \( m = 2 \) so that the ‘weights’ associated to each cluster are a linear function of the distance from the centre of the cluster and the sum of the coefficients is equal to 1. In practice, when partitioning the features space, all the points with membership degree larger than an arbitrary threshold have been assigned to each cluster. From a geometrical point of view, this allows to build clusters with soft boundaries, thus introducing some redundancy in the data sets and translates, in the case of the determination of photometric redshifts, into the fact that the same pattern is allowed to belong to different clusters, so that part of the information contained in each pattern is shared the different experts trained on each of these clusters. For a discussion on the choice of the optimal set of features, refer to Sections 5.1 and 6.

4.2 The gating network

Although the WGE architecture addresses by itself the bias variance trade-off problem, a MLP used as a gated network will introduce some variance and bias as well. This effect, mitigated by the WGE itself, is small but not negligible. In order to address this problem, we modelled the gating network as a committee of \( N \) identical MLPs trained on the same data set. Each network will produce a slightly different result. The final prediction is the average of all the predictions. The choice of the number of MLPs has been made by considering the bias and the variance of two randomly chosen distribution of photometric redshifts for each experiment and for several different numbers of trainings of the gating network. The bias and variance for each couple of determinations of the photometric redshifts have been estimated using the mean and the standard deviation of the residual variable \( \Delta z^{(phot)} \) between the two different determinations of the photometric redshifts:

\[
\text{bias} \left( z^{(1)}_{\text{phot}}, z^{(2)}_{\text{phot}} \right) = \langle \Delta z^{(phot)} \rangle = \left\langle \left( z^{(1)}_{\text{phot}} - z^{(2)}_{\text{phot}} \right) \right\rangle, \tag{14}\]

\[
\text{var} \left( z^{(1)}_{\text{phot}}, z^{(2)}_{\text{phot}} \right) = \sigma^{(phot)} = \sigma^{\prime2} \left( z^{(1)}_{\text{phot}} - z^{(2)}_{\text{phot}} \right). \tag{15}\]

These two variables (normalized to unity) are plotted against the number of trainings of networks in the committee in Fig. 3. The optimal number of networks for the three experiments has been chosen as those numbers for which the variations of the bias and variance were lower than 5 per cent from the preceding realization, i.e. 30 gating network trainings for optical galaxies, 20 for optical quasars and 50 gating networks for optical and ultraviolet (UV) quasars. The same procedure was used to determine the optimal number of networks of the gating network for the determination of the errors on the photometric redshifts for each experiment.
Figure 3. Normalized bias and variances for two randomly produced realizations of the photometric redshifts distributions as a function of the number of the trainings of the gating network. The values of the this number used for the experiments and the production of the catalogues are indicated by red horizontal lines. From top to bottom, optical quasars, optical+UV quasars and optical galaxies.

this case, the threshold is reached is reached at 20 trainings for all experiments.

5 THE KNOWLEDGE BASES AND FEATURES SELECTION

Three different KBs were employed during the training of the WGE method for the three classes of experiments performed, namely the evaluation of the photometric redshifts for

(i) optical galaxies with spectroscopic redshifts;
(ii) optical quasars with spectroscopic confirmation and redshift;
(iii) optical+UV quasars spectroscopically confirmed.

The optical data for these three groups of experiments have all been extracted from the SDSS DR7 data base (Abazajian et al. 2009). The confirmed spectroscopic quasars with both optical and UV photometry, used for the third class of experiments, have been retrieved from the data set of cross-matched sources from the SDSS and GALEX surveys (Budavari et al. 2009). A more detailed description of the three KBs can be found below.

(i) First KB (optical galaxies). It includes all primary extended SDSS sources classified as galaxies according to the SDSS specClass classification flag (specClass == {2}), having clean measured photometry in all filters (u, g, r, i, z), reliable spectroscopic redshifts estimates and brighter than the completeness limit of the SDSS spectroscopic survey, namely 19.7 in the r band. This sample, composed of ∼3.2 × 10⁵ sources, has been retrieved by querying the SDSS DR7 data base for sources belonging to both Galaxy and SpecObjAll tables.

(ii) Second KB (optical quasars). All spectroscopically confirmed SDSS quasars (specClass == {3, 4}), identified as point sources by any targeting program, with clean measured photometry in all filters (u, g, r, i, z) and reliable spectroscopic redshifts estimates (this sample, composed of ∼7.5 × 10⁴ sources, is a subset of the KB used for the extraction of candidate quasars described in Section 7.2.1). No specific cuts on the luminosity were performed.
This sample has been retrieved by querying the SDSS DR7 data base for sources belonging to the SpecObjAll table.

(iii) Third KB (optical+UV quasars). All spectroscopically confirmed optical SDSS quasars (∼2.7 × 10⁴ sources) associated to UV counterparts identified and observed by GALEX, with clean photometry in both optical (u, g, r, i, z) and near-UV and far-UV (NUV and FUV) bands and unambiguous positional cross-match (the sample of sources composing this KB is a proper subset of the second KB).

The queries used to extract the KBs from the SDSS and GALEX data bases are reported in the appendix.

5.1 Features selection

The selection process of the photometric features used for the training of the WGE method (i.e. the features of the experiment) was based on the assumption that most of the information needed to reconstruct the photometric redshifts of extragalactic sources is encoded in the observed magnitudes (D’Abrusco et al. 2007). However, since magnitudes are derived from fluxes, they tend to be correlated with each other and with the distance. Colours, instead, represent the ratio of fluxes measured in different filters and thus (once they have been corrected for extinction) they do not depend on the distance. Moreover, as it has already been discussed, the error regime changes with the redshift in the features space defined by the colours, thus encoding some information on the redshift which can be used to partially remove the degeneracy in the unknown colours–redshift relation. In Fig. 4, the distribution of the same sample of quasars spectroscopically selected in the SDSS DR7 used in Fig. 2 is plotted in the plane generated by the errors on the colours u − g and g − r evaluated by propagating the uncertainty on the individual magnitudes. Even if the correlation between the error distribution and spectroscopic redshifts is not as clear as in the case of the colour–colour plot shown before, also in this case low-redshift sources are almost completely contained in a window corresponding to errors generally smaller than 0.2 in both colours (the inset of the plots zooms into the high-density region located in the left bottom corner). The other points are instead distributed in an elongated feature corresponding to low and almost constant error on the σ_u−g parameter and varying σ_g−r. Finally, only a small number of sources is spread all over the plot and has significantly higher redshifts.

In order to exploit all information contained in both the photometric features and their uncertainties, the experiments discussed in this paper used the errors on the photometric colours to perform the clustering, and both colours and their uncertainties for the training of the experts. More combinations of features and associated uncertainties were tested for each distinct experiment described here. All different combinations of features produced less accurate reconstructions of the photometric redshifts. In particular, using as parameters of the clustering the colours only or the colours and their errors yielded, on average, 10 per cent larger median absolute deviation (MAD) of the variable Δz for all experiments.

For the first experiment involving the determination of the photometric redshifts for optical SDSS galaxies, the magnitudes used to derive the colours and their errors were the dereddened model magnitudes, i.e. the optimal estimates of the galaxy flux obtained by matching a spatial model to the source (Stoughton et al. 2002). In this specific case, two different models are fitted to the two-dimensional images of each extended source in each band, namely a De Vaucouleurs profile and an exponential profile, and the

Figure 4. Spectroscopically selected quasars in the SDSS DR7 data set in the σ_u−g versus σ_g−r plot. The colour of the symbols is associated to the spectroscopic redshift of the sources.

© 2011 The Authors, MNRAS 418, 2165–2195
Monthly Notices of the Royal Astronomical Society © 2011 RAS
best-fitting model is used to calculate the model magnitude. The model magnitudes are then corrected for extinction according to the maps of galactic dust provided in Schlegel et al. (1998). For the samples of quasars used in the second and third experiments, the SDSS point spread function (PSF) magnitudes corrected for extinction were used to calculate optical colours and their uncertainties, while the remaining colours were calculated using the NUV and FUV magnitudes in the PhotoObjAll table of the GALEX data base (Budavari et al. 2009), containing the photometric attributes measured for the sources detected in the GALEX imagery.

6 THE EXPERIMENTS

For each KB a distinct class of experiments was performed by varying some of the parameters of the WGE method, and the ones yielding the best results for each of those classes, in terms of the accuracy of the reconstruction of the photometric redshifts (according to the statistical diagnostics used to characterize the accuracy of the reconstruction and discussed in Section 8), are described in the next three paragraphs. The outputs of three the best experiments were also used to produce the catalogues of photometric redshifts for SDSS galaxies and candidate quasars, described, respectively, in Sections 7.1, 7.2 and 7.3. In this section, the accuracy of the reconstruction of the photometric redshifts will be expressed by the robust estimates of the scattering of the variable \( \Delta z \) as referred to as MAD (median absolute deviation), evaluated through its MAD. Given a univariate set of variables \( \{ \Delta z^1, \Delta z^2, \ldots, \Delta z^N \} \), the MAD of this sample is defined as

\[
\text{MAD}(\Delta z) = \text{median}(\Delta z - \text{median}(\Delta z)). \tag{16}
\]

In other words, MAD is the median of the absolute deviation of the residuals from the median of the residuals itself. A modified version of the standard MAD statistics (hereafter MAD') that can be used for the evaluation of the accuracy of the reconstruction of the photometric redshifts can be defined for the \( \Delta z \) variable as follows:

\[
\text{MAD}'(\Delta z) = \text{median}(|\Delta z|) \tag{17}
\]

A summary of the features used for the estimation of photometric redshifts and the errors on the photometric redshifts in these experiments is shown in Tables 1 and 7, respectively, while the physical motivation behind the selection of the features used to train the WGE method has been given in the Section 5.1. A more detailed characterization of the accuracy of the photometric redshifts reconstruction, obtained by means of distinct global and redshift-dependent statistical diagnostics, is discussed in Section 8.

The criteria used for the choice of the best experiments for each class of experiments are the following, in order of decreasing priority.

(i) The total percentages of test-set sources with \( \| \Delta z \| < 0.1 \), \( \| \Delta z \| < 0.2 \) and \( \| \Delta z \| < 0.3 \), respectively (<0.3, <0.2 and <0.1 for the experiments involving quasars). These quantities, hereafter, will be referred to as \( \Delta z_1 \), \( \Delta z_2 \) and \( \Delta z_3 \) for galaxies and quasars as well.

(ii) The value of the MAD diagnostic of the \( \Delta z \) variable as defined in equation (16).

(iii) The value of the MAD' diagnostic of the \( \Delta z \) variable as defined in equation (17).

While the main criterion to select the best experiment is the first and the other two were used as tiebreakers in case of equal value of \( \Delta z_1 \), \( \Delta z_2 \) and \( \Delta z_3 \) (with a tolerance of 0.1 per cent), for all classes of experiments the best one has been unambiguously selected by each of these criteria separately, as shown in Fig. 5. In this plot, the values of the three diagnostics are shown, respectively, for all experiments of each class considered in this paper (optical galaxies, optical quasars and optical+UV quasars), as a function of the number of clusterings.

A first set of experiments was performed in order to set the steepness and the learning rate for all the experts in the whole features space. Once set, these values have not been treated as parameters of the WGE training but are considered fixed. Moreover, different values of the two parameters for the gating network have been explored, leading to a negligible variation in the final estimates of the photometric redshifts and associated errors. For this

| Parameters                          | Optical galaxies | Optical quasars | Optical+UV quasars |
|-------------------------------------|------------------|----------------|-------------------|
| Params. clustering                  | \( \sigma_{u-g}, \sigma_{g-r}, \sigma_{r-i}, \sigma_{i-z} \) | \( \sigma_{u-g}, \sigma_{g-r}, \sigma_{r-i}, \sigma_{i-z} \) | \( \sigma_{u-g}, \sigma_{g-r}, \sigma_{r-i}, \sigma_{i-z} \) |
| Min. # clusters                    | 5                | 2              | 2                 |
| Max. # clusters                    | 9                | 9              | 9                 |
| Opt. clusters                      | 7                | 7              | 3                 |
| Clusters threshold                 | 0.15             | 0.1            | 0.1               |
| Max. iterations clust.             | 500              | 500            | 500               |
| Params. experts                    | \( \sigma_{u-g}, \sigma_{g-r}, \sigma_{r-i}, \sigma_{i-z} \) | \( \sigma_{u-g}, \sigma_{g-r}, \sigma_{r-i}, \sigma_{i-z} \) | \( \sigma_{u-g}, \sigma_{g-r}, \sigma_{r-i}, \sigma_{i-z} \) |
| Hid. neurons                       | 30               | 20             | 20                |
| Max. epochs.                       | 500              | 500            | 500               |
| Learning rate                      | 0.01             | 0.01           | 0.01              |
| Steepness                          | 1.0              | 1.0            | 1.0               |
| Hid. neurons gate                  | 30               | 20             | 20                |
| Max. epochs. gate                  | 500              | 500            | 500               |
| Learning rate gate                 | 0.01             | 0.01           | 0.01              |
| Steepness                          | 1.0              | 1.0            | 1.0               |
| # training gates                   | 30               | 20             | 20                |
Astroinformatics of galaxies and quasars

6.1 Photometric redshifts of galaxies with optical photometry

The best experiment for the evaluation of the photometric redshifts of optical galaxies, retrieved from the SDSS photometric data base, has been performed using the four SDSS colours and the corresponding errors (obtained by propagating the errors on the single magnitudes) as features and the spectroscopic redshifts measured by the SDSS spectroscopic pipelines as target. The training of the WGE method, as described in detail in Section 3, is obtained by first performing a clustering in the features space and then training the single experts on each of the clusters, so that the final outcome of the method is evaluated by the gating network which combines the distinct outputs from the experts. For this experiment, the c-means clustering has been performed on the distribution of KB sources in the four-dimensional features space based on the uncertainties of the photometric colours \( \sigma_{u-g}, \sigma_{g-r}, \sigma_{r-i} \) and \( \sigma_{i-z} \), calculated by propagating the statistical uncertainties on the single magnitudes. The single experts have been trained on the different clusters determined by the fuzzy K-means algorithm in the eight-dimensional photometric features space obtained by adding the four colours \( u-g, g-r, g-r \) and \( i-z \) to their uncertainties \( \sigma_{u-g}, \sigma_{g-r}, \sigma_{r-i} \) and \( \sigma_{i-z} \).

After multiple experiments performed with different values of the parameters of the WGE method, the optimal value of the membership threshold on the fuzzy clustering has been fixed to 0.1, so that each source has been considered member only of the clusters which accounts for at least 10 per cent of its total membership. The global MAD of the \( \Delta z \) variable of this experiment is 0.017. The scatter plot showing the distribution of photometric redshifts against the corresponding spectroscopic redshifts for the members of the KB used for test the WGE method for the catalogue of galaxies extracted from the SDSS DR7 data base is shown in Fig. 6. The histograms of the distributions of both photometric and spectroscopic redshifts for the test set of this experiment are shown in Fig. 7.

Figure 5. Statistical diagnostics as a function of the number of fuzzy clusters for the three experiments described in this paper (from the upper to lower panel, the experiments for the determination of the photometric redshifts of optical galaxies, quasars with optical photometry and quasars with optical and UV photometry). The optimal number of clusters, as reported in Table 1, is marked with a red vertical line. In all cases, the optimal number of clusters is associated to the highest values of the per cent(\( \Delta z \)) variable and to the lowest values of the three diagnostics MAD, MAD' and median(\( \| \Delta z \| \)).

reason, the values determined for the experts were used for all experiments.
Figure 6. Scatter plot of the spectroscopic redshifts versus photometric redshifts with isodensity contours for the sample of SDSS galaxies with optical photometry, belonging to the KB used to train the WGE in the first experiment. The isodensity contours are drawn for the following sequence of density values: \{10, 20, 50, 100, 200, 500, 1000, 5000\}.

Figure 7. Histograms of the distribution of spectroscopic and photometric redshifts for the sample of SDSS galaxies with optical photometry, belonging to the KB used to train the WGE in the first experiment.
6.2 Photometric redshifts of quasars with optical photometry

The best experiment for the evaluation of the photometric redshifts of optical confirmed quasars extracted from the SDSS spectroscopic data base made use of the four SDSS colours and associated uncertainties as features, and of the SDSS spectroscopic redshifts as targets. Similarly to what was described for the first experiment, the first step of the WGE training involved the determination of the optimal clustering of the KB sources in the four-dimensional feature space consisting of the errors of the colours $\sigma_{g-r}$, $\sigma_{g-r}$, $\sigma_{r-i}$, and $\sigma_{i-z}$. On the other hand, the experts and the gating expert have been trained on the whole eight-dimensional feature space generated by the four optical colours and their uncertainties. After multiple runs of the WGE method with different values of the parameters, the optimal value of the threshold on the fuzzy clustering has been fixed to 0.15. The clustering of the experiment for the determination of the errors on the photometric redshifts was carried out using, as features, the whole set of eight photometric features mentioned above in addition to the photometric redshift $z_{\text{phot}}$ and the variable $\Delta z$. The global MAD of the $\Delta z$ variable of this experiment is 0.14. The scatter plot of the distribution of photometric redshifts against the spectroscopic redshifts for the sources of the KB used to train the WGE method in this experiment is shown in Fig. 8, while the histograms of both spectroscopic and photometric redshifts distribution are shown in Fig. 9.

6.3 Photometric redshifts of quasars with optical and ultraviolet photometry

The most accurate reconstruction of the photometric redshifts for the quasars with SDSS optical and GALEX UV photometric data was achieved using, as features for the clustering, the six uncertainties of the colours obtained by combining the five SDSS optical filters and the two UV filters and by propagating the statistical errors on the magnitudes.

The training of the experts and the gating expert was therefore carried out on the whole set of photometric features available, i.e. the errors $\sigma_{u-g}$, $\sigma_{g-r}$, $\sigma_{r-i}$, $\sigma_{i-z}$, $\sigma_{\text{FUV}-\text{NUV}}$, $\sigma_{\text{NUV}-u}$ and the colours $(u-g)$, $(g-r)$, $(r-i)$, $(i-z)$, $(\text{FUV-NUV})$, $(\text{NUV}-u)$. Also in this experiment, the clustering for the determination of the errors on the photometric redshifts was performed inside the feature space generated by the whole set of photometric features used for the estimation of the photometric redshifts in addition to the photometric redshift $z_{\text{phot}}$ itself and to the variable $\Delta z$. The MAD of the final $\Delta z$ variable in this experiment is 0.09, improving noticeably the accuracy of the photometric redshifts reconstruction obtained with the optical photometry only. As in the previous two experiments, the scatter plot of the distribution of photometric redshifts against the spectroscopic redshifts for the sources of the KB used to test the WGE method in this experiment is shown in Fig. 10.

Figure 8. Scatter plot of the spectroscopic redshifts versus photometric redshifts with isodensity contours for the sample of SDSS quasars with optical photometry, belonging to the KB used to train the WGE in the second experiment. The isodensity contours are drawn for the following sequence of density values: \{2, 5, 10, 20, 30, 50, 100, 200\}. © 2011 The Authors, MNRAS 418, 2165–2195 Monthly Notices of the Royal Astronomical Society © 2011 RAS
Figure 9. Histograms of the distribution of spectroscopic and photometric redshifts for the sample of SDSS quasars with optical photometry, belonging to the KB used to train the WGE in the second experiment.

Figure 10. Scatter plot of the spectroscopic redshifts versus photometric redshifts with isodensity contours for sample of quasars with optical and UV photometry, belonging to the KB used to train the WGE in the third experiment. The isodensity contours are drawn for the following sequence of density values: \{2, 5, 10, 20, 30, 50, 75, 100, 150, 200\}.
7 THE CATALOGUES

7.1 The catalogue of photometric redshifts for SDSS galaxies

A catalogue of photometric redshifts for a sample of galaxies extracted from the SDSS DR7 data base has been produced using the model obtained by training the WGE as described in Section 6.1. The photometric galaxies were extracted, in a similar way to what done for the KB used for the training experiment, by querying the Galaxy table of the SDSS data base for all primary extended sources with clean photometry in all filters (u, g, r, i, z), and brighter than 21.0 in the r band (the SQL query is shown in Appendix A).

In total, the catalogue contains photometric redshifts for $\sim 3.2 \times 10^7$ sources. The set of specific features used for the evaluation of photometric redshifts, the estimated photometric redshifts values, errors and diagnostics flag together with some of the most common observational parameters retrieved directly from the SDSS data base and useful for the identification of the sources in the SDSS data base have been included in the catalogue for the sake of completeness. More information about the 24 columns of the catalogue format is given in Table 2. The photometric redshifts and uncertainties from our catalogues will also be incorporated into the NASA/IPAC Extragalactic Database (NED) services.

### Table 2. Columns of the catalogue of galaxies extracted from the SDSS with photometric redshifts evaluated using optical photometry.

| #  | Name     | Type   | Description                        |
|----|----------|--------|------------------------------------|
| 1  | objID    | Long   | Unique SDSS object ID              |
| 2  | ra       | Double | Right ascension in degrees (J2000) |
| 3  | dec      | Double | Declination in degrees (J2000)      |
| 4  | dered_u  | Float  | SDSS dereddened u model mag         |
| 5  | dered_g  | Float  | SDSS dereddened g model mag         |
| 6  | dered_r  | Float  | SDSS dereddened r model mag         |
| 7  | dered_i  | Float  | SDSS dereddened i model mag         |
| 8  | dered_z  | Float  | SDSS dereddened z model mag         |
| 9  | modmagerr_u | Float | SDSS u model mag error              |
| 10 | modmagerr_g | Float | SDSS g model mag error              |
| 11 | modmagerr_r | Float | SDSS r model mag error              |
| 12 | modmagerr_i | Float | SDSS i model mag error              |
| 13 | modmagerr_z | Float | SDSS z model mag error              |
| 14 | extinction_u | Float | SDSS u mag extinction              |
| 15 | extinction_g | Float | SDSS g mag extinction              |
| 16 | extinction_r | Float | SDSS r mag extinction              |
| 17 | extinction_i | Float | SDSS i mag extinction              |
| 18 | extinction_z | Float | SDSS z mag extinction              |
| 19 | u-g      | Double | u – g colour                       |
| 20 | g-r      | Double | g – r colour                       |
| 21 | r-i      | Double | r – i colour                       |
| 22 | i-z      | Double | i – z colour                       |
| 23 | photoz   | Double | Photometric redshift               |
| 24 | photoz_err | Double | Photometric redshift error         |

7.1.1 Contamination of the catalogue of photometric redshifts for SDSS galaxies

The redshift distribution of the sources belonging to the KB used to train the WGE for the determination of the catalogue of photometric redshifts for the galaxies extracted from the SDSS DR7 is shown in Fig. 7. Even though no constraints on the redshift of the sources were explicitly required (as it is clear from the SQL version of the query in Appendix A), all galaxies belonging to this...
KB have spectroscopic redshift $z < 0.6$. A certain degree of contamination from galaxies at redshift $z > 0.6$ (and for this reason, not represented in the KB used for the WGE training) is expected in the catalogue of photometric redshifts evaluated for the photometric galaxies extracted from the SDSS data base. These galaxies could be mistakenly assigned a wrong value of their photometric redshift, in some case significantly lower than their real redshift. The number and distribution of such galaxies, hereafter called contaminants, can be statistically evaluated either by using the luminosity function of the same galaxy population in the same band, similarly to what has been done in D’Abrusco et al. (2007), or by employing a deeper catalogue of galaxies with reliable measures of the redshifts. In the case of the catalogue discussed in this section, the second method has been chosen to evaluate the contamination from high-redshift galaxies, using data from the Deep Extragalactic Evolutionary Probe 2 (DEEP2) survey (Davis et al. 2007). DEEP2 is a spectroscopic survey that provides the most detailed census of the galaxy distribution at $z_{\text{spec}} \sim 1$, targeting $\sim 5.0 \times 10^5$ galaxies in the redshift range $0 < z < 1.4$. The last data release (DR3) includes redshifts spanning four survey fields overlapping with the SDSS sky coverage. The SDSS galaxies with photometric redshifts estimated with the WGE method have been positionally cross-matched with the catalogue DEEP2 DR3 catalogue of sources. The sample of point-like sources in the table PhotoObjAll of the SDSS DR7 data base from which the candidate quasars were extracted is composed of all the primary photometric stellar sources (using the SDSS 'type' flag, which provides a morphological classification of the sources by classifying them as extended or point-like) with clean photometry in all the filters ($u, g, r, i, z$) and brighter than 21.3 in the $i$ band, for consistency with the sample of sources selected in Richards et al. (2009). The SQL query used to retrieve the data is given in Appendix B. The catalogue retains the same basic structure of the catalogue of photometric redshifts of galaxies, with few changes. This catalogue contains $\sim 2.1 \times 10^6$ candidate quasars, and consists of the list of candidate quasars with a small set of photometric features used for the extraction process, with additional quantities derived by the method for the extraction of the candidates and the evaluation of photometric redshifts. Also in this case, some of the most common observational parameters available in the SDSS data base were retrieved and added to the catalogue.
Table 3. Columns of the catalogue of candidate quasars with photometric redshifts evaluated using optical photometry.

| #  | Name             | Type   | Description                                      |
|----|------------------|--------|--------------------------------------------------|
| 1  | catID            | Long   | Unique catalogue object ID                       |
| 2  | objID            | Long   | Unique SDSS object ID                            |
| 3  | ra               | Double | Right ascension in degrees (J2000)               |
| 4  | dec              | Double | Declination in degrees (J2000)                   |
| 5  | psfMag_u         | Float  | SDSS PSF $u$ model mag                           |
| 6  | psfMag_g         | Float  | SDSS PSF $g$ model mag                           |
| 7  | psfMag_r         | Float  | SDSS PSF $r$ model mag                           |
| 8  | psfMag_i         | Float  | SDSS PSF $i$ model mag                           |
| 9  | psfMag_z         | Float  | SDSS PSF $z$ model mag                           |
| 10 | psfmagerr_u      | Float  | SDSS $u$ PSF mag error                           |
| 11 | psfmagerr_g      | Float  | SDSS $g$ PSF mag error                           |
| 12 | psfmagerr_r      | Float  | SDSS $r$ PSF mag error                           |
| 13 | psfmagerr_i      | Float  | SDSS $i$ PSF mag error                           |
| 14 | psfmagerr_z      | Float  | SDSS $z$ PSF mag error                           |
| 15 | extinction_u     | Float  | SDSS $u$ mag extinction                         |
| 16 | extinction_g     | Float  | SDSS $g$ mag extinction                         |
| 17 | extinction_r     | Float  | SDSS $r$ mag extinction                         |
| 18 | extinction_i     | Float  | SDSS $i$ mag extinction                         |
| 19 | extinction_z     | Float  | SDSS $z$ mag extinction                         |
| 20 | strID            | Long   | SDSS stripe ID                                   |
| 21 | u-g              | Double | $u - g$ colour                                   |
| 22 | g-r              | Double | $g - r$ colour                                   |
| 23 | r-i              | Double | $r - i$ colour                                   |
| 24 | i-z              | Double | $i - z$ colour                                   |
| 25 | cluID            | Integer| Cluster ID                                      |
| 26 | densKDEqsos      | Double | KDE estimated pdf relative to quasars distr.     |
| 27 | densKDEnotqsos   | Double | KDE estimated pdf relative to not-quasars distr. |
| 28 | densKDERatio     | Double | KDE estimated pdf for quasars distr. to KDE esti |
|    |                  |        | mated pdf for not quasars distr. ratio           |
| 29 | photoz           | Double | Photometric redshift (optical+UV)                |
| 30 | photoz_err       | Double | Photometric redshift error                       |
| 31 | photoz_flag      | Short  | Photometric redshift flag                        |

7.2.1 Candidate quasars

The WGE method has been used to estimate photometric redshifts for the members of an updated version of the SDSS catalogue of optical candidate quasars described in D’Abrusco et al. (2009). While referring to the original work for a detailed description of the statistical method employed for the extraction of the candidate quasars, here we shall shortly summarize its basic facts in order to introduce some additional parameters included in the catalogue. The method used to produce the catalogue of candidate quasars relies on the geometrical characterization of the distribution of spectroscopically confirmed quasars in the optical photometric features space and employs a combination of clustering techniques to achieve the best possible separation between regions of the features space dominated by stars and quasars, respectively. The method is based on the combination of different DM algorithms since it includes a dimensionality reduction phase obtained via probabilistic principle surfaces (PPS) followed by a clustering performed using the negative entropy clustering (NEC), respectively. The method allows us to determine the salient correlations between the distribution of confirmed quasars in the photometric features space and to use this information to extract new photometric candidate quasars. Given the original KB (a sample of point-like sources with spectroscopic classification), the extraction of the candidate quasars is performed by associating each photometric source to the closest cluster and retaining as candidates only those sources associated to clusters dominated by confirmed quasars. In the revised version of the catalogue, the information provided for each candidate quasar has been completed by three parameters, namely the probabilities of each candidate quasar of being extracted from the underlying distributions of confirmed quasars or stars, and the ratio of these two probabilities. The first two values have been extracted from the probability density functions (pdf) associated to the two distinct distributions of stars and quasars, obtained by applying the kernel density estimation (KDE) method. These parameters can be used to further refine the efficiency of the selection, at the cost of reducing the completeness of the sample. The catalogue has been extracted from the SDSS DR7 data base, thus yielding $\sim$15 per cent more sources than the first version of the catalogue.

7.3 The catalogue of photometric redshifts for SDSS optical and ultraviolet candidate quasars

A third catalogue containing photometric redshifts estimates for a subsample of optical candidate quasars described in Section 7.2.1...
Table 4. Columns of the catalogue of candidate quasars with photometric redshifts evaluated using optical and UV photometry.

| #  | Name      | Type | Description                        |
|----|-----------|------|------------------------------------|
| 1  | catjID    | Long | Unique catalogue object ID         |
| 2  | objIDsdss | Long | Unique SDSS object ID              |
| 3  | objIDgal  | Long | Unique GALEX object ID             |
| 4  | ra        | Double | Right ascension in degrees (J2000) |
| 5  | dec       | Double | Declination in degrees (J2000)     |
| 6  | nuv       | Float | GALEX NUV mag                      |
| 7  | fuv       | Float | GALEX FUV mag                      |
| 8  | psfMag_u  | Float | SDSS PSF u model mag               |
| 9  | psfMag_g  | Float | SDSS PSF g model mag               |
| 10 | psfMag_r  | Float | SDSS PSF r model mag               |
| 11 | psfMag_i  | Float | SDSS PSF i model mag               |
| 12 | psfMag_z  | Float | SDSS PSF z model mag               |
| 13 | magerr_nuv| Float | GALEX NUV mag error                |
| 14 | magerr_fuv| Float | GALEX FUV mag error                |
| 15 | psfmagerr_u| Float | SDSS u PSF mag error              |
| 16 | psfmagerr_g| Float | SDSS g PSF mag error              |
| 17 | psfmagerr_r| Float | SDSS r PSF mag error              |
| 18 | psfmagerr_i| Float | SDSS i PSF mag error              |
| 19 | psfmagerr_z| Float | SDSS z PSF mag error              |
| 20 | extinction_u| Float | SDSS u mag extinction             |
| 21 | extinction_g| Float | SDSS g mag extinction             |
| 22 | extinction_r| Float | SDSS r mag extinction             |
| 23 | extinction_i| Float | SDSS i mag extinction             |
| 24 | extinction_z| Float | SDSS z mag extinction             |
| 25 | strID     | Long | SDSS stripe ID                     |
| 26 | fuv-nuv   | Double | FUV-NUV colour                    |
| 27 | nuv-u     | Double | NUV − u colour                    |
| 28 | u-g       | Double | u − g colour                      |
| 29 | u-g       | Double | u − g colour                      |
| 30 | g-r       | Double | g − r colour                      |
| 31 | r-i       | Double | r − i colour                      |
| 32 | i-z       | Double | i − z colour                      |
| 33 | cluID     | Integer | Cluster ID                       |
| 34 | densKDEqsos| Double | KDE estimated pdf relative to quasars distr. |
| 35 | densKDEnotqsos| Double | KDE estimated pdf relative to not-quasars distr. |
| 36 | densKDERatio| Double | KDE estimated pdf for quasars distr. to KDE estimated pdf for not quasars distr. ratio |
| 37 | photoz    | Double | Photometric redshift (optical+UV)  |
| 38 | photoz_err| Double | Photometric redshift error         |
| 39 | photoz_flag| Short | Photometric redshift flag          |

for which UV photometry from GALEX is available has been produced by using the results of the WGE training experiment described in the Section 6.3. The photometric redshifts for quasars with both optical and UV photometry are significantly more accurate that those evaluated using optical photometry only, and the fraction of catastrophic outliers is reduced as well (as will be described in detail in Section 8). This catalogue contains \( \sim 1.6 \times 10^5 \) sources. The query used to retrieve the UV photometry of the sources with reliable GALEX counterparts is shown in Appendix C. The columns contained in the catalogue are described in Table 4. Also in this case, the catalogue will be available through a cone search service.

8 ACCURACY OF THE PHOTOMETRIC REDSHIFT RECONSTRUCTION

Many different statistical diagnostics have been used in the literature to characterize the reconstruction of photometric redshifts as a function of the observational features used to evaluate the quality of the redshifts. In this section, a thorough statistical description of the performance of the WGE method will be given, in terms of the accuracy of the reconstruction, the biases of the reconstructed distribution of photometric redshifts and the fraction of outliers. A comparison of our results with others drawn from the literature is also provided in Table 5, along with a comprehensive set of statistical diagnostics evaluated for the three different classes of experiments performed with the WGE method. All statistics have been calculated for the variables \( \Delta z \) and \( \Delta z_{\text{norm}} = \Delta z/(1+z_{\text{spec}}) \).

The statistical diagnostics evaluated for the results of the three experiments are the following.

(i) The averages \( \langle \Delta z \rangle \) and \( \langle \Delta z_{\text{norm}} \rangle \) of both \( \Delta z \) and \( \Delta z_{\text{norm}} \) variables, which accounts for the overall bias of the photometric redshifts distribution.

(ii) The root mean square (rms) of both variables \( \Delta z \) and \( \Delta z_{\text{norm}} \) defined, respectively, as

\[
\text{rms}(\Delta z) = \sqrt{\frac{\sum (\Delta z)^2}{N}},
\]

where \( N \) is the total number of data points.
Table 5. Statistical diagnostics of photometric redshifts reconstruction for all the experiments discussed in this paper and for relevant papers in the literature. Column ‘Exp. 1’ contains the diagnostics for the experiment for the determination of the photometric redshifts of the optical galaxies from the SDSS catalogue described in Section 6.1, while columns ‘Exp. 2’ and ‘Exp. 3’ describe the diagnostics for the experiments concerning the determination of the photometric redshifts for quasars with optical and optical+UV photometry, respectively (the details can be found in Sections 6.2 and 6.3). The same statistical diagnostics are shown for some papers from the literature, respectively, D’Abrusco et al. (2007) for optical galaxies in column (1) and both Ball et al. (2008) and Richards et al. (2009) for optical and optical+UV quasars in the columns (2) and (3), respectively (as reported in Ball et al. 2008). The definitions of the statistical diagnostics and other relevant results of the literature are discussed in Section 8.

| Diagnostic | Exp. 1 | (1) | Exp. 2 | (2) | Exp. 3 | (2) | (3) |
|------------|--------|-----|--------|-----|--------|-----|-----|
| (Δz)       | 0.115  | 0.21 | 0.21   | –   | –      | 0.13| –   |
| rms(Δz)    | 0.021  | 0.074| 0.35   | –   | –      | 0.25| –   |
| σ²(Δz)     | 2.3 × 10⁻⁴| 5.0 × 10⁻⁴| 0.08 | 0.123| 0.27  | 0.044| 0.054| 0.136 |
| MAD(Δz)    | 0.011  | 0.012| 0.11   | –   | –      | 0.061| –   | –   |
| MAD'(Δz)   | 0.012  | –    | 0.098  | –   | –      | 0.062| –   | –   |
| Per cent(Δz₁) | 43.4 | 41.1| 50.7   | 54.9 | 63.9  | 68.1 | 70.8| 74.9 |
| Per cent(Δz₂) | 72.4 | 68.4| 72.3   | 73.3 | 80.2  | 86.5 | 85.8| 86.9 |
| Per cent(Δz₃) | 86.9 | 83.4| 80.5   | 80.7 | 85.7  | 91.4 | 90.8| 91.0 |
| σ²(Δz₁)   | 8.2 × 10⁻⁶| 8.2 × 10⁻⁶| 7.9 × 10⁻⁴| – | – | 7.6 × 10⁻⁴| – | – |
| σ²(Δz₂)   | 3.0 × 10⁻⁵| 3.1 × 10⁻⁵| 0.003  | – | – | 0.023 | – | – |
| σ²(Δz₃)   | 6.1 × 10⁻⁵| 6.3 × 10⁻⁵| 0.005  | – | – | 0.039 | – | – |
| (Δzₙorm)  | 0.014  | 0.017| 0.095  | 0.115| 0.115 | 0.058| 0.06| 0.071 |
| rms(Δzₙorm) | 0.019 | 0.037| 0.19   | –   | –      | 0.11| –   | –   |
| σ²(Δzₙorm) | 1.8 × 10⁻⁴| 1.1 × 10⁻³| 0.025 | 0.034| 0.079 | 0.086| 0.014| 0.031 |
| MAD(Δzₙorm) | 0.009 | 0.011| 0.041  | –   | –      | 0.029| –   | –   |
| MAD'(Δzₙorm) | 0.010 | –    | 0.040  | –   | –      | 0.031| –   | –   |
| Per cent(Δzₙorm,1) | 48.3 | 45.6| 77.3   | –   | –      | 87.4| –   | –   |
| Per cent(Δzₙorm,2) | 77.2 | 73.5| 87.3   | –   | –      | 94.0| –   | –   |
| Per cent(Δzₙorm,3) | 90.1 | 87.0| 91.8   | –   | –      | 96.4| –   | –   |
| σ²(Δzₙorm,1) | 8.3 × 10⁻⁶| 8.2 × 10⁻⁶| 6.2 × 10⁻⁴| – | – | 5.6 × 10⁻⁴| – | – |
| σ²(Δzₙorm,2) | 3.0 × 10⁻⁵| 3.0 × 10⁻⁵| 0.002 | – | – | 0.001 | – | – |
| σ²(Δzₙorm,3) | 5.8 × 10⁻⁵| 6.0 × 10⁻⁵| 0.004 | – | – | 0.002 | – | – |

\[ \text{rms}(\Delta z_{\text{norm}}) = \sqrt{\frac{\sum (\Delta z_{\text{norm}})^2}{N}}, \]

where \( N \) is the total number of values. The rms accounts for the overall variation of the photometric redshifts distribution compared to the spectroscopic redshifts distribution.

(iii) The variances \( \sigma^2(\Delta z) \) and \( \sigma^2(\Delta z_{\text{norm}}) \) and the MAD of both \( \Delta z \) and \( \Delta z_{\text{norm}} \) variables accounting for the accuracy of the reconstruction measured as the spread of the two different variables.

(iv) The values of the MAD’ for both \( \Delta z \) and \( \Delta z_{\text{norm}} \) variables.

(v) The percentage of sources with \( \Delta z < \{ \Delta z_1 = 0.01, \Delta z_2 = 0.02, \Delta z_3 = 0.03 \} \) and \( \Delta z < \{ \Delta z_1 = 0.1, \Delta z_2 = 0.2, \Delta z_3 = 0.3 \} \) for the experiments involving galaxy and quasars, respectively (hereafter \( \Delta z_1, \Delta z_2 \) and \( \Delta z_3 \) will be used for both galaxies and quasars, while \( \Delta z_{\text{norm},1}, \Delta z_{\text{norm},2} \) and \( \Delta z_{\text{norm},3} \) will be used with the same meaning for the \( \Delta z_{\text{norm}} \) variable), which provide estimates of the performances of the reconstruction process at different levels of accuracy.

(vi) The variance for the sources at \( \Delta z_1, \Delta z_2 \) and \( \Delta z_3 \) (\( \Delta z_{\text{norm},1}, \Delta z_{\text{norm},2} \) and \( \Delta z_{\text{norm},3} \)) that represents an alternative measure of the performance of the reconstruction at three different levels of the accuracy.

In Table 5 we show the values of such diagnostics for the three experiments described in this paper and for a few other relevant papers in the literature that apply different methods to similar KBs and photometric data sets (wide band photometry from ground-based surveys in the optical and UV surveys). Namely, the results from Ball et al. (2008) and Richards et al. (2009) for quasars with either optical or optical+UV photometry, and D’Abrusco et al. (2007) for optical galaxies are reported in the table. The WGE method noticeably improves over the accuracy achieved by D’Abrusco et al. (2007) in the reconstruction of the photometric redshifts for SDSS galaxies according to all the diagnostics, with only slightly smaller fractions of sources within \( \Delta z_1, \Delta z_2 \) and \( \Delta z_3 \). In the case of the determination of the photometric redshifts for optical quasars, the k-nearest neighbour (kNN) method used in Ball et al. (2008) (column 2) achieves a much larger variance for the \( \Delta z \) variable while performing very similarly at the WGE method in terms of \( \Delta z_1, \Delta z_2 \) and \( \Delta z_3 \), bias and variance of the distribution of \( \Delta z_{\text{norm}} \) variable. Similar results are achieved by the two methods also for the reconstruction of the photometric redshifts of quasars extracted from the SDSS with both optical and UV photometry, except for the fact that kNN achieves a much better variance for the distribution of the variable \( \Delta z_{\text{norm}} \). A different approach, not based on ML techniques, but similarly aimed at the determination of the empirical correlation between the colours and redshifts of the sources for the evaluation of the photometric redshifts is adopted in Richards et al. (2009) (CZR method). Some of the diagnostics available for the application of this method to SDSS quasars with both optical and optical+UV photometry show that such mock method achieves consistently lower accuracy relative to both WGE and kNN methods (with the exception of the normalized variance for optical+UV experiment), while providing slightly larger fraction of sources within \( \Delta z_1, \Delta z_2 \) and \( \Delta z_3 \) in the case of optical quasars.

The accuracy of the reconstruction of the photometric redshifts depends on the number of sources belonging to the KB and on how well the KB samples the features space defined by the photometric features. As a general statement, it is possible to state that the
larger is the sample and the more homogeneous is the coverage of the features space, the more accurate is the reconstruction of the target values. Fig. 13 shows the dependence of the robust sigma of the $\Delta z$ variable for all experiments discussed in this paper as a function of the number of sources of the KB. In more details, Fig. 13 shows (on the left y-axis) the MAD of the $\Delta z$ variable and the percentage of sources of the KB with $\Delta z < \Delta z_3$ as functions of the number of sources of the training sets for the three experiments involving optical galaxies and quasars and optical+UV quasars. The members of the training sets are extracted randomly from the whole KBs of the three experiments. The WGE method has been trained on such randomly drawn subsample of the original KBs in order to minimize the effects of all the other possible sources of variance. Both diagnostics of the performance of the WGE method considered show a common behaviour, reaching a plateau after some characteristic threshold which apparently depends on the number of features and the complexity of the experiment. The $\Delta z_3$ variable shows a steep increase at low cardinalities for all experiments, while the accuracy of the reconstruction appears to improve much more slowly with the number of sources in the training set.

The data used to create the plot in Fig. 13 are presented in Table 6.

### Table 6. Accuracy of the reconstruction of the photometric redshifts for the three experiments described in this paper as a function of the number of sources composing the training set, randomly drawn from the whole KBs. Robust estimates of the robust standard deviation of the $\Delta z$ variable, obtained with the MAD algorithm are provided together with the percentages of sources with $\Delta z < 0.3$ and $< 0.03$ for the experiments involving the quasars and the galaxy, respectively.

| # sources KB | $\sigma_{rob}$ Exp. 1 | $\sigma_{rob}$ Exp. 2 | $\sigma_{rob}$ Exp. 3 | Per cent($\Delta z_3$) Exp. 1 | Per cent($\Delta z_3$) Exp. 2 | Per cent($\Delta z_3$) Exp. 3 |
|--------------|------------------------|------------------------|------------------------|-----------------------------|-----------------------------|-----------------------------|
| $5 \times 10^2$ | 0.035 | 0.392 | 0.201 | 68.3 | 60.3 | 79.2 |
| $10^3$ | 0.027 | 0.245 | 0.167 | 71.1 | 70.1 | 85.6 |
| $5 \times 10^3$ | 0.019 | 0.181 | 0.102 | 82.9 | 74.2 | 91.6 |
| $10^4$ | 0.018 | 0.165 | 0.100 | 83.2 | 78.4 | 90.4 |
| $5 \times 10^4$ | 0.017 | 0.143 | – | 86.3 | 81.6 | – |
| $10^5$ | 0.018 | – | – | 87.6 | – | – |
| $5 \times 10^5$ | 0.018 | – | – | 88.9 | – | – |
| Whole KB | 0.017 | 0.143 | 0.089 | 90.1 | 79.4 | 91.3 |

### 9 PHOTOMETRIC REDSHIFTS ERRORS AND CATASTROPHIC OUTLIERS

The determination of the uncertainty affecting the photometric redshifts has always been an open issue (Quadri & Williams 2010). For instance, some methods in the past have provided a unique value of the error for all redshifts, based on the global evaluation of the accuracy of the evaluated redshifts themselves (see D’Abrusco et al. 2007). A further advantage of the WGE algorithm over other methods is the ability to evaluate errors for each individual photometric redshift, based on the same features used to train the WGE and on the value of the redshifts. While the evaluation of the statistical error is quite difficult and would not provide useful information for the scientific applications of the photometric redshifts, an estimate of the maximum error affecting each photometric redshift is represented by the value of the associated variable $\Delta z$, i.e. the difference between the photometric redshift and the corresponding value of the spectroscopic redshifts. The WGE has been trained to evaluate the uncertainty $\sigma_z$ for each photometric redshift as

$$WGE_{train}(p, z_{phot}) \rightarrow \| \Delta z \|,$$

where, as in equation (9), $p$ is the vector associated to a given collection of feature values (i.e. a given set of colours or magnitudes), $z_{phot}$ is the photometric redshift evaluated by the WGE in the first phase.
and $|\Delta z|$ is the absolute value of the $\Delta z$ variable. Once trained, the WGE provides an estimated value of the error as a function of the features and of the reconstructed targets, i.e. of the photometric features and redshifts:

$$\sigma_{\text{phot}} = \text{WGE}(p, z_{\text{phot}}).$$

(21)

The evaluation of the errors on the photometric redshifts estimates with the WGE for the experiments described in Sections 6.1–6.3 has been carried out with a similar approach to the one described in the above sections for the evaluation of the photometric redshifts, except for the slightly different choice of the features. For all three classes of experiments, the photometric features used for the evaluation of the photometric redshifts, the photometric redshifts $z_{\text{phot}}$ and the difference between photometric and spectroscopic redshifts $\Delta z$ have been used as features for the clustering. The training of the experts has been performed on the same set of features, except for the $\Delta z$ variable that has been employed as target of the training. A detailed list of the WGE parameters for the experiments for the evaluation of the errors on the photometric redshifts is shown in Table 7. Figs 14–16 show the distribution of errors for the reconstructed photometric redshifts of the sources belonging to the KBs of the three distinct experiments. In these plots, the scatter plots of the variable $\Delta z$ and the spectroscopic redshifts $z_{\text{spec}}$ are shown in the lower panels. Points in both panels are coloured according to the value of the $\sigma_{\text{phot}}$ variable.

The distribution of the errors on the photometric redshifts $\sigma_{\text{phot}}$ as function of the spectroscopic redshifts, the photometric redshift and the variable $\Delta z$ are shown for the two experiments involving the samples of quasars in the Fig. 17. As it was to be expected, in general, the WGE produces larger error estimates for the photometric redshifts of the sources lying inside the high degeneracy regions of the $z_{\text{spec}}$ versus $z_{\text{phot}}$ plots. As shown by the vertical dashed lines (upper panels), most of these regions occur at redshifts at which the most luminous emission lines characterizing SDSS quasars spectra shift off the filters of the SDSS or GALEX photometric systems. The shape of the average distribution of the error $\sigma_{\text{phot}}$ as a function of the variable $\Delta z$, while not globally linear as should have been expected in the case of perfect reconstruction of the errors by the WGE method, is compatible with a linear relation close to the diagonal of the plot for $\Delta z \lesssim 0.3$ for both experiments and represent an acceptable approximation since in this range lies a very high percentage of the total number of sources (from $\sim 80$ to $\sim 90$ per cent of the points).

In the case of the reconstruction of the photometric redshifts for the candidate quasars using both the optical or the optical+UV photometry, the characterization of the accuracy of the reconstruction of the photometric redshifts provided by the errors is not complete since, similarly to what happens for the $z_{\text{phot}}$ values, the errors on such values are statistical estimates of the real uncertainty and are affected, to some extent, by the same degeneracies and systematic biases found in the $z_{\text{phot}}$ reconstruction. This effect is noticeable in the scatter plots in Figs 8 and 10, where consistent features of the plot deviate heavily from the ideal diagonal distribution. The degeneracies yielding such large effects cannot be completely resolved by the WGE during the phase of photometric redshifts estimation, but the same WGE generates information useful to flag the sources located in these regions of the plot (which cannot be recognized exactly in absence of spectroscopic redshifts, i.e. for all the sources belonging to the catalogues of photometric redshifts). For this reason, another measure of the reliability of the redshifts, hereafter called quality flag $q$, is provided for each object belonging to the catalogue of photometric redshifts for optical candidate quasars. Unlike the photometric redshift value itself $z_{\text{phot}}$ and the error on such value $\sigma_{\text{phot}}$, the quality flag $q$ is evaluated on the basis of the global distributions of both photometric redshifts and photometric redshift errors, i.e. after the evaluation of photometric redshifts and of the corresponding errors for all sources in a given sample. The steps for the evaluation of the quality flags are the following.

(i) The distribution of photometric redshifts evaluated by the WGE for the training set is binned, inside the interval covered by

### Table 7. Parameters of the best experiments for the evaluation of the error on the photometric redshifts for optical galaxies, optical candidate quasars and optical+UV candidate quasars.

| Params. clustering ($\sigma_z$) | $\sigma_{u-g}$, $\sigma_{g-r}$, $\sigma_{r-i}$, $\sigma_{i-z}$, $\Delta z$ | $\sigma_{u-g}$, $\sigma_{g-r}$, $\sigma_{r-i}$, $\sigma_{i-z}$, $\Delta z$ |
|-------------------------------|---------------------------------|---------------------------------|
| Min. # clusters ($\sigma_z$)  | 2                               | 2                               |
| Max. # clusters ($\sigma_z$)  | 9                               | 9                               |
| Opt. # clusters ($\sigma_z$)  | 2                               | 2                               |
| Clusters threshold ($\sigma_z$)| 0.1                             | 0.1                             |
| Max. iterations clust. ($\sigma_z$) | 500                         | 500                             |
| Params. experts ($\sigma_z$)  | $\sigma_{u-g}$, $\sigma_{g-r}$, $\sigma_{r-i}$, $\sigma_{i-z}$, $\Delta z$ | $\sigma_{u-g}$, $\sigma_{g-r}$, $\sigma_{r-i}$, $\sigma_{i-z}$, $\Delta z$ |
| Hid. neurons experts ($\sigma_z$) | 30                             | 20                             |
| Max. epochs. experts ($\sigma_z$) | 500                         | 500                             |
| Learning rate experts ($\sigma_z$) | 0.01                          | 0.01                           |
| Steepness experts ($\sigma_z$)  | 1.0                             | 1.0                             |
| Hid. neurons gate ($\sigma_z$)  | 30                              | 20                              |
| Max. epochs. gate ($\sigma_z$)  | 500                             | 500                             |
| Learning rate gate ($\sigma_z$)  | 0.01                            | 0.01                            |
| Steepness gate ($\sigma_z$)    | 1.0                             | 1.0                             |
| # training gates ($\sigma_z$)   | 20                              | 20                              |
| MAD ($\sigma_z$)               | 0.01                            | 0.086                           |

© 2011 The Authors, MNRAS 418, 2165–2195

Monthly Notices of the Royal Astronomical Society © 2011 RAS

Astroinformatics of galaxies and quasars

2185
the distribution of spectroscopic redshifts of the KB, in \( n_{\text{bin}}(z_{\text{phot}}) \) equally spaced intervals.

(ii) For each bin in the distribution of photometric redshifts, the associated set of errors on the estimates of the \( z_{\text{phot}} \) is binned in \( n_{\text{bin}}(\sigma_{z_{\text{phot}}}) \) equally spaced intervals.

(iii) The value of the quality flag of a given photometric redshift \( z_{\text{phot}} \) is assigned according to the position of its uncertainty relatively to the overall presence of peaked features of the distribution: if the error \( \sigma_{z_{\text{phot}}} \) lies inside a bin belonging to the most prominent feature of the histogram (i.e. the component of the histogram containing the highest peak of the overall distribution), the quality flag of the corresponding photometric redshift estimate \( q \) is set to 1, otherwise to 0.

(iv) The sources with \( q = 1 \) are considered reliable, while the sources flagged by \( q = 0 \) are considered unreliable, i.e. potential catastrophic outliers.

The effectiveness of the quality flag in selecting the outliers of the photometric redshifts reconstruction depends critically on the value of the two parameters \( n_{\text{bin}}(z_{\text{phot}}) \) and \( n_{\text{bin}}(\sigma_{z_{\text{phot}}}) \) associated to the total number of bins for the photometric redshifts and the error on the photometric redshifts distribution, respectively, of the process described above. The optimal values of these two parameters have been determined by exploring the \( n_{\text{bin}}(z_{\text{phot}}) \) versus \( n_{\text{bin}}(\sigma_{z_{\text{phot}}}) \) space. Two different empirical diagnostics, based on the knowledge of the spectroscopic and photometric redshifts of the sources of the KBs, of the accuracy of the determination of the quality flags have been used, namely the efficiency and the completeness of the separation between reliable sources and unreliable sources. The efficiency \( e \) is defined as the ratio of ‘reliable’ sources \( (q = 1) \) with \( \Delta z < 0.3 \) to the total number of ‘reliable’ sources \( (q = 1) \), while the completeness \( c \) is defined as the ratio of ‘reliable’ sources \( (q = 1) \) with \( \Delta z < 0.3 \) to the total number of sources, independently from the value of the quality flag, with \( \Delta z < 0.3 \).

The efficiency and completeness for the second and third experiments as functions of the \( n_{\text{bin}}(z_{\text{phot}}) \) and \( n_{\text{bin}}(\sigma_{z_{\text{phot}}}) \) parameters are shown in Fig. 18. The optimal values of the two parameters \( n_{\text{bin}}(z_{\text{phot}}) \) and \( n_{\text{bin}}(\sigma_{z_{\text{phot}}}) \) have been chosen to maximize at the same time the efficiency and completeness, i.e. the product of the efficiency and completeness \( t = e \cdot c \), and in the case of equal values, priority has been given to the couple of values associated to the larger efficiency.

The optimal values of the parameters for the second experiment, i.e. the determination of the photometric redshifts of the optical SDSS quasars, are \( n_{\text{bin}}(z_{\text{phot}}) = 18 \) and \( n_{\text{bin}}(\sigma_{z_{\text{phot}}}) = 34 \), respectively. For the third experiment, involving the evaluation of the photometric redshifts for SDSS quasars with optical and UV photometry, the optimal parameters are \( n_{\text{bin}}(z_{\text{phot}}) = 17 \) and \( n_{\text{bin}}(\sigma_{z_{\text{phot}}}) = 32 \). The values of the flags associated to the high-redshift quasars \( (z_{\text{spec}} \geq 4.5) \) have all been fixed to 1 (reliable photometric redshifts estimates) since, because of low total number of sources in such redshift interval, the method described above for the evaluation of the determination of the outliers based on the overall shape of the binned \( z_{\text{phot}} \) distribution in bins of spectroscopic redshifts cannot be applied. The decision to retain all such sources as reliable is based on the eye inspection of the \( z_{\text{spec}} \) versus \( z_{\text{phot}} \) scatter plot in Fig. 19.
The scatter plot of the distribution of photometric redshifts as function of the spectroscopic redshifts for the KB associated to the second experiment performed by the WGE (quasars with optical photometry) with different colour of the symbol associated to the two different values of the quality flags is shown in Fig. 19, with marginal histograms of the distribution of the different subsets according to $q$. In order to highlight the differences in the distributions of the sources with reliable or unreliable photometric redshifts values, the $z_{\text{phot}}$ versus $z_{\text{spec}}$ scatter plots for the two samples with $q = 1$ and $0$, respectively, are shown in Fig. 20. These same plots for the experiment concerning the estimation of the photometric redshifts of quasars with optical and UV photometry are shown in Figs 21 and 22, respectively. The set of statistical diagnostics calculated for the whole KBs of the three experiments discussed in this paper and shown in Table 5 has been evaluated for the KBs of the second and third experiments separately for sources with $q = 1$ and 0 (see Table 8).

The accuracy of the reconstruction of the photometric redshifts for the reliable sources ($q = 1$) increases with a factor from 1.2 to 2 in terms of both the variables $\text{rms}(\Delta z)$ and $\text{MAD}(\Delta z)$ for both experiments involving the determination of the photometric redshifts of quasars. While a significant contamination from photometric redshifts with $||\Delta z|| > 0.1$ is still present in the subsets of reliable sources in both experiments (per cent($||\Delta z|| < 0.1$) = 61.9 and 71.4 for exp. 2 and exp. 3, respectively), the fraction of accurate $z_{\text{phot}}$ ($||\Delta z|| < 0.1$) selected as unreliable ($q = 0$) at the $||\Delta z|| = 0.1$ level is very low (5.9 and 8.5 per cent, respectively).

10 CONCLUSIONS

The WGE is an original method for the determination of the photometric redshifts capable of working on both galaxies and quasars. The WGE, which is based on a combination of clustering and regression techniques, is able to mitigate most of the degeneracies which arise from the distribution of KB templates in the features space, and to derive accurate estimates of both the photometric redshifts values and of their errors. Besides giving a detailed description of how the WGE works, in this paper we have also presented an application of the WGE to the determination of photometric redshifts of optical galaxies and to the candidate quasars with optical and UV photometry, both extracted from the SDSS DR7 data base. The accuracy of the reconstruction of the redshifts for optical galaxies, obtained by comparing photometric and spectroscopic redshifts, can be expressed a robust estimate of the dispersion of the $\Delta z$ variable, which is equal to $\text{MAD}(\Delta z) = 0.011$ with $\sim 86.9$ per cent of the sources within $\Delta z_3$. The same diagnostics for the estimation of $z_{\text{phot}}$ for candidate quasars are $\text{MAD}(\Delta z) = 0.11$ and per cent($\Delta z_3$) = 80.5 when only optical photometry is used, reaching $\text{MAD}(\Delta z) = 0.061$ and per cent($\Delta z_3$) = 91.4 when the photometric redshifts are evaluated using both optical and UV photometry. A thorough
Figure 16. In the upper panel, it is shown the scatter plot of the spectroscopic versus photometric redshifts evaluated with the WGE method for the members of the KB of the experiment for the quasars extracted from the SDSS catalogue with optical and UV photometry, while in the lower panel the scatter plot of the spectroscopic redshift $z_{\text{spec}}$ versus $\Delta z$ variable is shown for the same sources. All points are colour coded according to the value of the errors $\sigma_{z_{\text{spec}}}$ as evaluated by the WGE. The vertical dashed lines represent the redshift at which the most luminous emission lines characterizing quasars spectra shift off the SDSS and GALEX photometric filters due to redshift. Similarly to what is shown in Fig. 15, most of the features of the plot are associated to one or more of these lines. Moreover, the lines associated to the GALEX filters resolve some of the degeneracies at low redshift.

Discussion and a comparison of the WGE with several other methods applied to the same or similar data is also provided in the paper. To perform such comparison, a large set of statistical diagnostics shows that the WGE performs better than or similarly to all the other methods. The results of the best experiments with the WGE for optical galaxies and quasars have been used to produce the catalogues of photometric redshifts of $\sim 3.2 \times 10^7$ galaxies photometrically selected, a sample of $\sim 2.1 \times 10^6$ optical candidate quasars from D’Abrusco et al. (2009) with photometric redshifts estimated using optical only photometry and a smaller catalogue of more accurate photometric redshifts derived from optical and UV photometry for a subset of $\sim 1.6 \times 10^5$ optical candidate quasars, respectively. All catalogues will be publicly available and a complete description of the parameters associated to each photometric redshift estimates is available (see Sections 7.1–7.3 for details on the catalogues). In this paper, we have also shown the results of the application of the WGE method to a relatively small sample of spectroscopically selected optical SDSS quasars for which also the UV (GALEX) photometry was available. Since the largest computational load is in the training phase, once the WGE has been trained and has achieved the required accuracy (either by matching some a priori constraint or by convergence), it can be ‘frozen’ and newly acquired data falling in the same region of the features space sampled by the KB can be processed without the need for a re-training of the method. This implies that, regardless the rate at which data are acquired, the WGE can produce estimates of photometric redshifts in real-time. If needed, a new training of the method can be performed off-line when a larger/improved KB becomes available. This requirement is becoming of the utmost importance for DM techniques in order for them to cope with the data streams foreseen for the current and future optical synoptic surveys [such as Pan-STARRS or the Large Synoptic Sky Telescope (LSST)] that will produce overnight an amount of data (images and catalogue) similar or even larger than the total amount of data collected by the SDSS. It is worth stressing that the WGE is part of the larger realms of astroinformatics and DM. As a data-driven discipline, through the application of DM methods, astroinformatics can provide astronomy and astrophysics with a framework for tackling new problems or old problems with a novel approach: in particular, where the traditional approach uses data from observations in order to prove or disprove a hypothesis, with DM we want data itself to provide hypotheses that can be then proved or disproved with more accurate follow-up observation. For example, using a catalogue of photometric redshifts for galaxies of the SDSS DR7 survey, Capozzi et al. (2009) put constraints on the nature of the so-called Shakbazian groups by studying the properties of such groups as they appeared to be in the de-projected space. This data-driven approach is well described also by the fact that by using ML methods many assumptions can be dropped in favour of a more agnostic approach: for instance, by employing ML techniques to the photometric redshift problem, one can drop any
Figure 17. From the upper to the lower plots, the distributions of the errors on the photometric redshifts $\sigma_{\text{zphot}}$ as function of the spectroscopic redshifts $z_{\text{spec}}$, the photometric redshift $z_{\text{phot}}$ and the variable $|\Delta z|$, respectively, are shown for the two experiments regarding quasars with optical only photometry (left-hand column) and quasars with optical and UV photometry (right-hand column) discussed in this paper. The average profiles of the distribution of error on the photometric redshifts are shown as a black line in all plots. In the upper plots, the redshifted emission lines are shown similarly to what is done in Figs 15 and 16, as lines overplotted to the $z_{\text{spec}}$ versus $\sigma_{\text{zphot}}$ scatter plots. Also in these cases, most of the features in these two plot can be associated to one or more of the lines. In the lower two plots, the insets show the densest regions of the plots. For the optical quasars (lower left-hand plot), $\sim$82 per cent of the sample is contained in the inset, while for the optical and UV quasars (lower right-hand plot), $\sim$90 per cent of the sample is contained in the zoomed region.
assumptions on the form of the SED of the source, so that it is up to the model, for example a neural network, to find a representation of the highly non-linear relation between the photometric information and the spectroscopic redshift, instead of fitting the data with a set of SED templates. However, since the hypothesis-driven approach of template fitting has noticeable advantages, it can be useful to underline an interesting feature offered by the WGE: it is possible, through the WGE, to link together different experts employed in complex architectures, in which different predictors can be integrated to take advantage of the peculiar strengths of each of them. Even an algorithm which does not belong to the domain of the DM techniques could be consistently used together with ML experts. In this case, however, the predictors not based on DM techniques will not be trained in the first step of the training algorithm and will only participate to the training of the gate predictor. This feature was not exploited in this work, but a likely outcome of such a hybrid approach will be the creation of mixed WGE architectures in which empirical ML algorithms cooperate with more traditional algorithms based on physical knowledge, for instance neural networks and SED template fitting.\footnote{For a review of the most used template fitting methods in the literature see Hildebrandt et al. (2010).}

One interesting feature of this approach is the generalization offered by the WGE: linking together different experts can lead to complex architectures in which different predictors can be integrated to take advantage of the peculiar strengths of each of them. Even an algorithm which does not belong to the domain of the DM techniques can be consistently used together with ML experts.
Figure 19. Scatter plot of the spectroscopic versus photometric redshifts for the KB of the second experiment (quasars with optical photometry), with marginal histograms for reliable ($q = 1$) and unreliable ($q = 0$) photometric redshift estimates according to the quality flag $q$. In the vertical marginal panel, the histograms of the distributions of reliable and unreliable photometric redshifts are, respectively, plotted with black and red dotted lines, while the histogram of the spectroscopic redshifts distribution is shown as a solid black line in both marginal panels.

Figure 20. Scatter plots of the spectroscopic versus photometric redshifts distributions for the KB of the second experiment (quasars with optical photometry) separately for reliable and unreliable estimations of the photometric redshifts according to the quality flag $q$. The sources with reliable $z_{\text{phot}}$ values ($q = 1$) are shown in the plot on the left, while sources with unreliable $z_{\text{phot}}$ values ($q = 0$) are shown in the plot on the right.
Figure 21. Scatter plot of the spectroscopic versus photometric redshifts for the KB of the third experiment (quasars with optical and UV photometry), with marginal histograms for reliable and unreliable photometric redshift estimates according to the quality flag \( q \). In the vertical marginal panel, the histograms of the distributions of reliable and unreliable photometric redshifts are, respectively, plotted with black and red dotted lines, while the histogram of the spectroscopic redshifts distribution is shown as a solid black line in both marginal panels.

Figure 22. Scatter plots of the spectroscopic versus photometric redshifts distributions for the KB of the third experiment (quasars with optical and UV photometry) separately for reliable and unreliable estimations of the photometric redshifts according to the quality flag \( q \). The sources with reliable \( z_{\text{phot}} \) values (\( q = 1 \)) are shown in the plot on the left, while sources with unreliable \( z_{\text{phot}} \) values (\( q = 0 \)) are shown in the plot on the right.
Table 8. Statistical diagnostics of the accuracy of the photometric redshifts reconstruction for the second and third experiments, evaluated for reliable and unreliable $z_{\text{phot}}$ estimates according to the quality flag $q$. For the definition of the statistical diagnostics see Section 8.

| Diagnostic                  | All          | Exp. 2 $q = 1$ | All $q = 0$ | Exp. 3 $q = 1$ | All $q = 0$ |
|-----------------------------|--------------|---------------|-------------|----------------|-------------|
| $\langle \Delta z \rangle$  | 0.21         | 0.13          | 0.53        | 0.13           | 0.10        | 0.52        |
| rms($\Delta z$)             | 0.35         | 0.24          | 0.62        | 0.25           | 0.20        | 0.63        |
| $\sigma^2(\Delta z)$        | 0.08         | 0.04          | 0.11        | 0.044          | 0.031       | 0.12        |
| MAD($\Delta z$)             | 0.11         | 0.07          | 0.32        | 0.061          | 0.056       | 0.34        |
| MAD($\Delta z_{\text{norm}}$) | 0.098      | 0.064         | 0.41        | 0.062          | 0.047       | 0.29        |
| Per cent($\Delta z_1$)      | 50.7         | 61.9          | 5.9         | 68.1           | 71.4        | 8.5         |
| Per cent($\Delta z_2$)      | 72.3         | 86.6          | 15.2        | 86.5           | 90.4        | 18.2        |
| Per cent($\Delta z_3$)      | 80.5         | 90.6          | 27.5        | 91.4           | 95.0        | 28.6        |
| $\sigma^2(\Delta z_{\text{norm},1})$ | $7.9 \times 10^{-4}$ | $7.9 \times 10^{-4}$ | $8.3 \times 10^{-4}$ | $7.6 \times 10^{-4}$ | $7.6 \times 10^{-4}$ | $8.4 \times 10^{-4}$ |
| $\sigma^2(\Delta z_{\text{norm},2})$ | 0.003         | 0.003         | 0.003       | 0.023          | 0.002       | 0.003       |
| $\sigma^2(\Delta z_{\text{norm},3})$ | 0.005         | 0.004         | 0.007       | 0.039          | 0.004       | 0.007       |
| $\langle \Delta z_{\text{norm}} \rangle$ | 0.095         | 0.056         | 0.25        | 0.058          | 0.049       | 0.23        |
| rms($\Delta z_{\text{norm}}$) | 0.19         | 0.13          | 0.32        | 0.11           | 0.09        | 0.29        |
| $\sigma^2(\Delta z_{\text{norm}})$ | 0.025         | 0.014         | 0.036       | 0.086          | 0.006       | 0.03        |
| MAD($\Delta z_{\text{norm}}$) | 0.041         | 0.028         | 0.14        | 0.029          | 0.027       | 0.16        |
| MAD($\Delta z_{\text{norm}}$) | 0.04         | 0.030         | 0.19        | 0.031          | 0.029       | 0.204       |
| Per cent($\Delta z_{\text{norm},1}$) | 77.3         | 92.2          | 17.5        | 87.4           | 91.0        | 23.3        |
| Per cent($\Delta z_{\text{norm},2}$) | 87.3         | 96.8          | 49.3        | 94.0           | 96.6        | 49.1        |
| Per cent($\Delta z_{\text{norm},3}$) | 91.8         | 97.1          | 70.3        | 96.4           | 97.8        | 71.2        |
| $\sigma^2(\Delta z_{\text{norm},1})$ | $6.2 \times 10^{-4}$ | $5.7 \times 10^{-4}$ | $8.4 \times 10^{-4}$ | $5.6 \times 10^{-4}$ | $5.5 \times 10^{-4}$ | $8.2 \times 10^{-4}$ |
| $\sigma^2(\Delta z_{\text{norm},2})$ | 0.002         | 0.001         | 0.003       | 0.001          | 0.001       | 0.003       |
| $\sigma^2(\Delta z_{\text{norm},3})$ | 0.004         | 0.001         | 0.006       | 0.002          | 0.002       | 0.007       |

In this case, however, the predictors not based on DM techniques will not be trained in the first step of the training algorithm and will only participate to the training of the gate predictor. A likely outcome of such hybrid approach will be the creation of mixed WGE architectures in which empirical ML algorithms cooperate with more classical algorithms based on physical consideration or models typical of the specific domain. For instance, for the particular problem of the estimation of photometric redshifts, the WGE method could be used to integrate ML algorithms and the empirical methods based on SED template fitting (for a review of the most used template fitting methods in the literature see Hildebrandt et al. 2010).

**ACKNOWLEDGMENTS**

This work was made possible by the financial support of the US Virtual Astronomical Observatory, which is sponsored by the National Science Foundation and the National Aeronautics and Space Administration. This paper is based on work that took advantage of several technologies the authors would like to acknowledge. The WGE code is mostly based on the Fast Artificial Neural Network library. Most of the statistical code is implemented in R, while for data retrieval, analysis and publication, multiple tools, services and protocols developed by the International Virtual Observatory Alliance were used. In particular, all the catalogues derived from this publication will be published as standard Cone Search services through the VODance service hosted at the Italian Center for Astronomical Archives (IA2), Trieste Astronomical Observatory. TOPCAT (Taylor 2005) was used extensively in both its desktop version and its command line counterpart STILTS (Taylor 2006). The authors thank the anonymous reviewer for insightful comments that have helped to improve the paper.

**REFERENCES**

Abazajian K. N. et al., 2009, ApJS, 182, 543
Abdalla F. B., Amara A., Capak P., Cypriano E. S., Lahav O., Rhodes J., 2008, MNRAS, 387, 969
Arnalte-Mur P., Fernández-Soto A., Martínez V. J., Saar E., Heinämäki P., Suuronen I., 2009, MNRAS, 394, 1631
Ball N. M., Brunner R. J., 2010, Int. J. Modern Phys. D, 99, 1049
Barnard T., 2005, MNRAS, 387, 969
Ball N. M., Brunner R. J., Myers A. D., Strand N. E., Alberts S. L., Tcheng C., 2008, ApJ, 683, 12
Bishop C. M., 1996, Neural Networks for Pattern Recognition. Oxford Univ. Press, Oxford
Bonfield D. G., Sun Y., Davey N., Jarvis M. J., Abdalla F. B., Banerji M., Adams R. G., 2010, MNRAS, 405, 987
Borne K., 2010, J. Earth Sci. Inf., 3, 5
Bovy J. et al., 2011, ApJ, submitted
Bruzual A. G., 2010, in Bruzual A. G., Charlot S., eds, Proc. IAU Symp. 262, Stellar Populations: Planning for the Next Decade. Cambridge Univ. Press, Cambridge, p. 55
Budavari T. et al., 2001, AJ, 122, 1163
Budavari T. et al., 2009, ApJ, 694, 1281
Capozzi D., De Filippis E., Paolillo M., D’Abrasco R., Longo G., 2008, MNRAS, 396, 900
Carliles S., Budavari T., Heinis S., Priebe C., Szalay A. S., 2010, ApJ, 712, 511

© 2011 The Authors, MNRAS 418, 2165–2195
Monthly Notices of the Royal Astronomical Society © 2011 RAS
APPENDIX A: SQL QUERY FOR SDSS GALAXIES

This is an example of the SQL queries used to retrieve the galaxies in the SDSS photometric data set whose redshifts have been evaluated using the results of the WGE experiment described in Section 7.1. The queries were run on the SDSS DR7 data base through the SDSS Catalog Archive Server Jobs System (CASJobs).

```sql
SELECT
g.objID,
g.ra, g.dec,
g.dered_u, g.dered_g, g.dered_r, g.dered_i, g.dered_z,
g.modelmagerr_u, g.modelmagerr_g, g.modelmagerr_r,
g.modelmagerr_i, g.modelmagerr_z,
g.extinction_u, g.extinction_g, g.extinction_r,
g.extinction_i, g.extinction_z,
g.petror50_u, g.petror50_g, g.petror50_r,
g.petroR50_u, g.petroR50_g, g.petroR50_r,
g.petroR90_u, g.petroR90_g, g.petroR90_r,
g.lndeV_u, g.lndeV_g, g.lndeV_r,
g.lnLExp_u, g.lnLExp_g, g.lnLExp_r,
g.lnLStar_u, g.lnLStar_r
FROM
Galaxy AS g, Segment AS seg, Field AS f
WHERE
g.mode = 1 AND
seg.segmentID = f.segmentID AND
f.fieldID = g.fieldID AND
seg.stripe = 16 AND
g.dered_r < 21.5 AND
doбо.fPhotoFlags('BAD_COUNTS_ERROR') != 0 AND
doбо.fPhotoFlags('PSF_FLUX_INTERP') != 0 AND
doбо.fPhotoFlags('BAD_COUNTS_ERROR') != 0 AND
doбо.fPhotoFlags('INTERP_CENTER') != 0
```

APPENDIX B: SQL QUERY FOR OPTICAL SDSS STELLAR SOURCES

This is an example of the SQL queries used to retrieve the stellar sources in the SDSS photometric data set from which the candidate quasars have been extracted with the method described in Section 7.2.1 and the photometric redshifts have been evaluated using the results of the WGE experiment described in Section 7.2. The queries were run on the SDSS DR7 data base through the SDSS CASJobs.

```sql
SELECT
p.objID,
p.ra, p.dec,
p.psfMag_u, p.psfMag_g, p.psfMag_r,
p.psfMag_i, p.psfMag_z,
p.psfMagerr_u, p.psfMagerr_g, p.psfMagerr_r,
p.psfMagerr_i, p.psfMagerr_z,
p.extinction_u, p.extinction_g, p.extinction_r,
p.extinction_i, p.extinction_z
FROM
PhotoObjAll AS p, Segment AS seg, Field AS f
WHERE
p.mode = 1 AND
p.type = 6 AND
seg.segmentID = f.segmentID AND
f.fieldID = p.fieldID AND
seg.stripe = 11 AND
p.psfMag_i > 14.5 AND
(p.psfMag_i - p.extinction_i) < 21.3 AND
p.psfMagErr_i < 0.2 AND
doбо.fPhotoFlags('BAD_COUNTS_ERROR') != 0 AND
doбо.fPhotoFlags('PSF_FLUX_INTERP') != 0 AND
doбо.fPhotoFlags('BAD_COUNTS_ERROR') != 0 AND
doбо.fPhotoFlags('INTERP_CENTER') != 0
```
APPENDIX C: SQL QUERY FOR ULTRAVIOLET GALEX COUNTERPARTS OF OPTICAL CANDIDATE QUASARS

This is an example of the SQL queries used to retrieve the UV GALEX counterparts of the optical candidate quasars composing the catalogue described in Section 7.3, whose photometric redshifts have been evaluated using the results of the WGE experiment described in Section 6.3.

```
SELECT p.objid AS galex_objid,
      my.objID AS sdss_objid,
      p.nuv_mag as nuv, p.nuv_magErr as nuv_err,
      p.fuv_mag as fuv, p.fuv_magErr as fuv_err,
      p.e_bv,
      x.distance,
      x.distanceRank,
      x.reverseDistanceRank,
      x.multipleMatchCount,
      x.reverseMultipleMatchCount
FROM MYDB.candidate_quasars_objid AS my
     INNER JOIN xSDSSDR7 AS x ON my.objID = x.SDSSobjid
     INNER JOIN photoobjall AS p ON x.objid = p.objid
WHERE x.distanceRank = 1
  AND x.reverseDistanceRank = 1
  AND x.distance < 2
  AND p.nuv_mag > 0
  AND p.fuv_mag > 0
```

This paper has been typeset from a \TeX/\LaTeX file prepared by the author.