CONVERGENCE ANALYSIS OF STRUCTURE-PRESERVING NUMERICAL METHODS BASED ON SLOTBOOM TRANSFORMATION FOR THE POISSON–NERNST–PLANCK EQUATIONS∗

JIE DING†, CHENG WANG‡, AND SHENGGAO ZHOU.§

Abstract. The analysis of structure-preserving numerical methods for the Poisson–Nernst–Planck (PNP) system has attracted growing interests in recent years. A class of numerical algorithms have been developed based on the Slotboom reformulation, and the mass conservation, ionic concentration positivity, free-energy dissipation have been proved at a discrete level. Nonetheless, a rigorous convergence analysis for these Slotboom reformulation-based, structure-preserving schemes has been an open problem for a long time. In this work, we provide an optimal rate convergence analysis and error estimate for finite difference schemes based on the Slotboom reformulation. Different options of mobility average at the staggered mesh points are considered in the finite-difference spatial discretization, such as the harmonic mean, geometric mean, arithmetic mean, and entropic mean. A semi-implicit temporal discretization is applied, which in turn results in a non-constant coefficient, positive-definite linear system at each time step. A higher order asymptotic expansion is applied in the consistency analysis, and such a higher order consistency estimate is necessary to control the discrete maximum norm of the concentration variables. In convergence estimate, the harmonic mean for the mobility average, which turns out to bring lots of convenience in the theoretical analysis, is taken for simplicity, while other options of mobility average would also lead to the desired error estimate, with more technical details involved. As a result, an optimal rate convergence analysis on concentrations, electric potential, and ionic fluxes is derived, which is the first such result for the structure-preserving numerical schemes based on the Slotboom reformulation. It is remarked that the convergence analysis leads to a theoretical justification of the conditional energy dissipation analysis, which relies on the maximum norm bounds of the concentration and the gradient of the electric potential. Some numerical results are also presented to demonstrate the accuracy and structure-preserving performance of the associated schemes.

Keywords. Poisson–Nernst–Planck equations; Slotboom reformulation; mobility average; convergence analysis and error estimate; higher order consistency estimate.

AMS subject classifications. 35K55; 35K61; 65M06; 65M12.

1. Introduction The Poisson–Nernst–Planck (PNP) equations are widely used to describe charge transport in many applications, e.g., transmembrane ion channels [52], electrochemical devices [3], and semiconductors [30]. Such a system of equations can be formulated in a dimensionless form as

\[
\begin{align*}
\partial_t c^l &= \nabla \cdot (\nabla c^l + q^l c^l \nabla \psi), \quad l = 1, \cdots, M, \quad \text{in } \Omega, \\
-\kappa \Delta \psi &= \sum_{l=1}^{M} q^l c^l + \rho^f, \quad \text{in } \Omega,
\end{align*}
\]

(1.1)

where \(c^l = c^l(x,t)\) and \(q^l\) are the ionic concentration and valence for the \(l\)-th species, \(\kappa\) stands for the coefficient arising from nondimensionalization, \(\psi = \psi(x,t)\) is the electric potential, and \(\rho^f = \rho^f(x)\) is the distribution of fixed charge density. For simplicity of
presentation, we consider a cubic \( \Omega \) with periodic boundary conditions. An extension to the model with homogeneous Neumann boundary conditions is straightforward. The initial condition for ionic concentrations is given by \( c^l(x,0) = c^l_{\text{in}}(x) \), where \( c^l_{\text{in}} \) is the initial data. With periodic boundary conditions, the total mass of ions is conservative in \( \Omega \) for each species.

The evolution of ionic concentrations and electric potential described by the PNP equations can be regarded as a gradient flow of an electrostatic free energy

\[
F = \sum_{l=1}^{M} \int_{\Omega} \left[ c^l \ln c^l + \frac{1}{2} (q^l c^l + \rho^f) \psi \right] dV. \tag{1.2}
\]

In fact, one can derive the free-energy dissipation law

\[
\frac{dF}{dt} = \sum_{l=1}^{M} \int_{\Omega} \frac{\partial c^l}{\partial t} \frac{\delta F}{\delta c^l} dV = -\sum_{l=1}^{M} \int_{\Omega} \frac{1}{c^l} \left| \nabla c^l + q^l c^l \nabla \psi \right|^2 dV \leq 0. \tag{1.3}
\]

Much effort has been devoted to the development of numerical methods for the PNP equations, such as finite difference, finite volume, and finite element methods \([1, 4–8, 13, 14, 19, 24–26, 28, 29, 31–34, 36, 40, 41, 43, 53]\). Many existing works focus on the development of numerical algorithms that are able to preserve desirable physical structure properties, including mass conservation, free-energy dissipation, and positivity of ionic concentrations at discrete level. For instance, a second-order accurate, mass conservative, and energy dissipative finite difference method was proposed for the 1-D PNP equations \([25]\). A finite element scheme that ensures positivity of ionic concentration via a variable transformation was developed for the PNP-type equations \([31]\). A discontinuous Galerkin (DG) method was also developed in the work \([26]\), in which the positivity of the numerical solution was not theoretically proved, while such a property was enforced by an accuracy-preserving limiter. The preservation of positivity in DG method was theoretically addressed later in the work \([27]\). An implicit finite difference method that guarantees numerical positivity and energy dissipation was developed in the work \([19]\). A set of numerical schemes that unconditionally ensure positivity, unique solvability, and energy dissipation was proposed in \([40]\). Recently, a mass conservative, positivity-preserving, and energy stable finite difference scheme, based on a gradient-flow formulation, was proposed and analyzed, and an optimal rate convergence analysis has also been established \([22]\). Keeping the structure-preserving properties, it has been extended to second-order accuracy, both in space and time, with corresponding convergence analysis in a more recent work \([23]\).

The above-mentioned progress on structure-preserving numerical methods can be sorted into two categories. One is based on the observation that the dynamics described by the PNP equations is the gradient flow of the free energy \((1.2)\) \([22, 35, 40]\). Implicit discretization based on the gradient-flow structure naturally respects energy dissipation due to the convexity of the free energy. The existence of positive concentration solution is enforced by using the singularity of the logarithmic function at zero. Convergence analysis and error estimate have been rigorously established for first-order and second-order temporal discretization schemes in \([22]\) and \([23]\), respectively. The other category is based on the Slotboom transformation \([9, 10, 19, 24, 25, 41]\), which converts the Nernst–Planck (NP) equations into

\[
\partial_t c^l = \nabla \cdot (e^{-S^l} \nabla g^l), \quad S^l = q^l \psi, \quad l = 1, \cdots, M. \tag{1.4}
\]
Here $g_i^l = c_i^l e^S_i$ is a generalized Slotboom variable [42]. The advantage of such a reformulation is associated with the combination of the diffusion and convection into a self-adjoint operator, which greatly facilitates the design of discretization schemes that are able to preserve the discrete maximum principle. Conditional free-energy dissipation can be achieved if the electric potential is explicitly treated, and unconditional dissipation can be proved with an implicit treatment of the electric potential. However, rigorous convergence analysis as well as error estimate is still an open problem for structure-preserving numerical methods based on the Slotboom transformation.

In this work, we provide a theoretical proof of convergence analysis and error estimate for structure-preserving numerical schemes based on the Slotboom transformation. After the transformation, the PNP equations are spatially discretized with central differencing approximations, and a semi-implicit treatment is considered for temporal discretization. This in turn results in a non-constant coefficient, positive-definite linear system at each time step. Moreover, a discrete average of mobility functions is needed at the staggered mesh points, and four different options are considered: the harmonic mean, geometric mean, arithmetic mean, and entropic mean. The mass conservative, positivity-preserving, and energy dissipative properties of the finite difference scheme with various mobility averages have already been established in a few recent works [9, 10, 24, 25]. In particular, the energy dissipation analysis relies on the maximum norm bounds of the concentration, as well as the gradient of the electric potential, while these bounds have to be established through an optimal rate convergence analysis. We perform the error estimate by employing a higher order asymptotic expansion in the consistency analysis, which is necessary to control the discrete maximum norm of the concentration variables. This approach has been reported for a wide class of nonlinear PDEs; see the related works [2, 11, 12, 15, 21, 38, 39, 44–46]. In the convergence estimate, the harmonic mean for the mobility average, which turns out to bring lots of convenience in the theoretical analysis, is shown as an example, while other options of mobility average would also lead to the desired error estimate, with more technical details involved. As a result, an optimal rate convergence analysis is derived for ionic concentrations, electric potential, and fluxes, which is the first such result for structure-preserving numerical methods for the PNP equations that are based on the Slotboom transformation.

The rest of the paper is organized as follows. In Section 2, we present the fully discrete finite difference numerical scheme based on the Slotboom reformulation. The mass conservative, positivity-preserving, and energy dissipative properties of the numerical schemes are recalled in Section 3. Subsequently, the optimal rate convergence analysis is presented in Section 4. Some numerical results are provided in Section 5. Finally, conclusions and discussions are given in Section 6.

2. Numerical schemes

2.1. Discretization and notations. The PNP system (1.1) is discretized based on the Slotboom transformation (1.4). For simplicity, a rectangular computational domain $\Omega = (a, b)^3$ with periodic boundary conditions is considered. Let $N \in \mathbb{N}^*$ be the number of grid points along each dimension, and $h = (b - a)/N$ be the uniform grid spacing. The computational domain is covered by the grid points

$$\{x_i, y_j, z_k\} = \left\{a + \left( i - \frac{1}{2}\right) h, a + \left( j - \frac{1}{2}\right) h, a + \left( k - \frac{1}{2}\right) h \right\},$$

for $i, j, k = 1, \cdots, N$. Denote by $c_i^{l'}, g_i^{l'},$ and $\psi_i$ the discrete approximations of $c^l(x_i, y_j, z_k, \cdot)$, $g^l(x_i, y_j, z_k, \cdot)$, and $\psi(x_i, y_j, z_k, \cdot)$, respectively.
We recall the following standard discrete operators and notations for finite difference discretization [47, 48]. The following space of periodic grid functions is introduced:

\[ \mathcal{C}_{\text{per}} := \left\{ u \mid u_{i,j,k} = u_{i+N,j,k} = u_{i,j+k} = u_{i,j,k} \right\}, \]

\[ \mathcal{E}^\nu_{\text{per}} := \left\{ \nu \mid \nu_{i+\frac{1}{2},j,k} = \nu_{i+\frac{1}{2},j,k+N} = \nu_{i,j+k} = \nu_{i,j,k} \right\}, \]

and

\[ \mathcal{E}^\nu_{\text{per}} := \left\{ u \in \mathcal{C}_{\text{per}} \mid \nu = 0 \right\}, \quad \mathcal{C} = \frac{\hbar^3}{|\Omega|} \sum_{i,j,k=1}^N u_{i,j,k}. \]

Analogously, we define the spaces \( \mathcal{E}^\nu_{\text{per}} \) and \( \mathcal{E}^x_{\text{per}} \), and denote \( \mathcal{E}^\nu_{\text{per}} := \mathcal{E}^\nu_{\text{per}} \times \mathcal{E}^\nu_{\text{per}} \times \mathcal{E}^x_{\text{per}} \). We also introduce the following average and difference operators in \( x \)-direction:

\[ A_x f_{i+1/2,j,k} := \frac{1}{2} (f_{i+1,j,k} + f_{i,j,k}), \quad D_x f_{i+1/2,j,k} := \frac{1}{h} (f_{i+1,j,k} - f_{i,j,k}), \]

\[ a_x f_{i,j,k} := \frac{1}{2} (f_{i+1,j,k} + f_{i-1,j,k}), \quad d_x f_{i,j,k} := \frac{1}{h} (f_{i+1,j,k} - f_{i-1,j,k}). \]

Average and difference operators in \( y \) and \( z \) directions, denoted as \( A_y, A_z, D_y, D_z, a_y, a_z, d_y, \) and \( d_z \), can be analogously defined. The discrete gradient and discrete divergence are given by

\[ \nabla_h f_{i,j,k} := \left( D_x f_{i,j+1/2,k}, D_y f_{i,j,k+1/2}, D_z f_{i,j,k+1/2} \right), \]

\[ \nabla_h \cdot f_{i,j,k} = d_x (D_x f)_{i,j,k} + d_y (D_y f)_{i,j,k} + d_z (D_z f)_{i,j,k}, \]

where \( f = (f^x, f^y, f^z) \in \mathcal{E}_\text{per} \). The standard discrete Laplacian becomes

\[ \Delta_h f_{i,j,k} := \nabla_h \cdot \left( \nabla_h f \right)_{i,j,k} = d_x (D_x f)_{i,j,k} + d_y (D_y f)_{i,j,k} + d_z (D_z f)_{i,j,k}. \]

For a periodic scalar function \( D \) that is defined at face center points and \( \bar{f} \in \mathcal{E}_{\text{per}} \), then \( D \bar{f} \in \mathcal{E}_{\text{per}} \), in the sense of point-wise multiplication, and we denote

\[ \nabla_h \cdot (D \bar{f})_{i,j,k} = d_x (D f^x)_{i,j,k} + d_y (D f^y)_{i,j,k} + d_z (D f^z)_{i,j,k}. \]

If \( f \in \mathcal{C}_{\text{per}} \), then \( \nabla_h \cdot (D \nabla_h f) : \mathcal{C}_{\text{per}} \to \mathcal{C}_{\text{per}} \) is defined as

\[ \nabla_h \cdot (D \nabla_h f)_{i,j,k} = d_x (D D_x f)_{i,j,k} + d_y (D D_y f)_{i,j,k} + d_z (D D_z f)_{i,j,k}. \]

In addition, we introduce the following grid inner products

\[ \langle f, \xi \rangle := h^3 \sum_{i,j,k=1}^N f_{i,j,k} \xi_{i,j,k}, \quad f, \xi \in \mathcal{C}_{\text{per}}, \quad [f, \xi]_x := \langle a_x (f \xi), 1 \rangle, \quad f, \xi \in \mathcal{E}^x_{\text{per}}, \]

\[ [f, \xi]_y := \langle a_y (f \xi), 1 \rangle, \quad f, \xi \in \mathcal{E}^y_{\text{per}}, \quad [f, \xi]_z := \langle a_z (f \xi), 1 \rangle, \quad f, \xi \in \mathcal{E}^x_{\text{per}}. \]

\[ [\bar{f}_1, \bar{f}_2] : = [f^x_1, f^x_2]_x + [f^y_1, f^y_2]_y + [f^z_1, f^z_2]_z, \quad \bar{f}_i = (f^x_i, f^y_i, f^z_i) \in \mathcal{E}_{\text{per}}, \quad i = 1, 2. \]

Then, the following norms can be defined for grid functions. If \( f \in \mathcal{C}_{\text{per}} \), then \( \| f \|_2^2 := \langle f, f \rangle, \quad \| f \|_p^2 := \langle f^p, 1 \rangle, \quad 1 \leq p < \infty, \) and \( \| f \|_\infty := \max_{1 \leq i,j,k \leq N} | f_{i,j,k} |. \) The gradient norms are given by

\[ \| \nabla_h f \|_2^2 := [\nabla_h f, \nabla_h f] = [D_x f, D_x f]_x + [D_y f, D_y f]_y + [D_z f, D_z f]_z, \quad \forall f \in \mathcal{C}_{\text{per}}, \]

\[ \| \nabla_h f \|_p^2 := \langle [\nabla_h f, \nabla_h f]_p, 1 \rangle, \quad 1 \leq p < \infty, \]
\[ \| \nabla_h f \|_p^p := \| D_x f \|_1^p, y + \| D_y f \|_1^p + \| D_z f \|_1^p, z, \quad \forall f \in C_{\text{per}}, \quad 1 \leq p < \infty. \]

The higher-order norms can be similarly defined:
\[ \| f \|_{H_h^2}^2 := \| f \|_2^2 + \| \nabla_h f \|_2^2, \quad \| f \|_{H_h^1}^2 := \| f \|_{H_h^1}^2 + \| \Delta_h f \|_2^2, \quad \forall f \in C_{\text{per}}. \]

In addition, we recall the following inequalities that shall be used in the convergence analysis.

**Lemma 2.1 ([16, 17]).** For any \( f \in \mathcal{C}_{\text{per}} \), we have
\[ \| f \|_2 + \| \nabla_h f \|_2 \leq C \| \Delta_h f \|_2, \tag{2.2} \]
where \( C \) is a positive constant independent of \( h \). In addition, the following estimates are available:
\[ \| f \|_\infty \leq C(\| f \|_2 + \| \Delta_h f \|_2), \quad \forall f \in C_{\text{per}}, \tag{2.3} \]
\[ \| \nabla_h f \|_\infty \leq C h^{-1} \| f \|_\infty \leq C h^{-1} \| \Delta_h f \|_2, \quad \forall f \in \mathcal{C}_{\text{per}}. \tag{2.4} \]

**2.2. Numerical schemes.** Based on the Slotboom reformulation (1.4), spatial discretization at \((x_i, y_j, z_k)\) leads to a semi-discrete scheme [9, 24, 25]
\[ \frac{d}{dt} \mathcal{J}_{i,j,k} = \nabla_h \cdot \left( e^{-S^t} \mathcal{g}^l \right)_{i,j,k}, \tag{2.5} \]
where \( e^{-S^t} \mathcal{g}^l = (e^{-S^t} \mathcal{g}^l_x, e^{-S^t} \mathcal{g}^l_y, e^{-S^t} \mathcal{g}^l_z) \in \mathcal{C}_{\text{per}} \) with
\[ \mathcal{g}^l_{x,i+j,k} = D_x \left( c^l e^{S^t} \right)_{i+j+1, j, k}, \quad \mathcal{g}^l_{y,i+j,k} = D_y \left( c^l e^{S^t} \right)_{i, j, k+1/2,}, \quad \mathcal{g}^l_{z,i+j,k+1/2} = D_z \left( c^l e^{S^t} \right)_{i, j, k+1/2}. \]

In terms of numerical approximation of the mobility function \( e^{-S^t} \) on the half-grid points, there are several options:

- **Harmonic mean:**
  \[ e^{-S^t_{i+j+1, j, k}} = \frac{2 e^{-S^t_{i+1, j, k}} e^{-S^t_{i, j, k}}}{e^{-S^t_{i+1, j, k}} + e^{-S^t_{i, j, k}}} = \left( \frac{e^{S^t_{i+1, j, k}} + e^{S^t_{i, j, k}}}{2} \right)^{-1}, \]

- **Geometric mean:**
  \[ e^{-S^t_{i+j+1, j, k}} = e^{S^t_{i+1, j, k} + S^t_{i, j, k}} \]

- **Arithmetic mean:**
  \[ e^{-S^t_{i+j+1, j, k}} = \frac{e^{-S^t_{i+1, j, k}} + e^{-S^t_{i, j, k}}}{2}, \]

- **Entropic mean:**
  \[ e^{-S^t_{i+j+1, j, k}} = \frac{S^t_{i+1, j, k} - S^t_{i, j, k}}{e^{S^t_{i+1, j, k}} - e^{S^t_{i, j, k}}}. \]

The approximation of \( e^{-S^t_{i+j+1/2, k}} \) and \( e^{-S^t_{i+j, k+1/2}} \) can be analogously defined. Similar average of mobility functions in discretization cells have been implemented in the literature [18, 50, 51]. The periodic boundary conditions are imposed at a discrete level:
\[ c^t_{1/2, j, k} = c^t_{N+1/2, j, k}, \quad c^t_{1/2, i, k} = c^t_{i+N+1/2, k}, \quad c^t_{1/2, i, j, k} = c^t_{i, j, N+1/2} \quad \text{for} \ i, j, k = 1, \cdots, N. \tag{2.7} \]

**Remark 2.1.** The spatial discretization with the harmonic mean of mobility functions on half-grid points can lead to a coefficient matrix that has been proved to have an upper
bound on the condition number [9]. The discretization with entropic mean, which leads
to the well-known Scharfetter–Gummel scheme, is the only one, among those four means,
that can reduce to an upwind scheme when the convection is large.

Given the semi-discrete approximations $c_{i,j,k}^l$, the Poisson’s equation is discretized as

$$-\kappa \Delta_h \psi_{i,j,k} = \sum_{l=1}^{M} q_l^i c_{i,j,k}^l + \rho_f^i$$ for $i,j,k = 1,\ldots,N$. \hfill (2.8)

The periodic boundary conditions could be formulated as

$$\psi_{i+\frac{1}{2},j,k} = \psi_{i+\frac{1}{2},j,k}, \psi_{i,j+\frac{1}{2},k} = \psi_{i,j+\frac{1}{2},k}, \psi_{i,j,k+\frac{1}{2}} = \psi_{i,j,k+\frac{1}{2}}$$ for $i,j,k = 1,\ldots,N$. \hfill (2.9)

Remark 2.2. To guarantee the existence of a solution to (2.8), it is assumed that the
initial conditions and fixed charge distribution satisfy

$$\sum_{l=1}^{M} q_l^i c_{i,j,k}^n + \rho_f^i \in \bar{C}_{\text{per}}. \quad \text{In addition, we consider a zero-average constraint for } \psi, \text{ i.e., } \psi \in \bar{C}_{\text{per}}, \text{ to make the solution to the discrete Poisson’s equation unique.}$$

With a uniform time step size $\Delta t$ and $t^n = n \Delta t$, a semi-implicit scheme is proposed:
Given $\psi^n \in \bar{C}_{\text{per}}$ and $c_{i,j,k}^n \in \bar{C}_{\text{per}}, l = 1,\ldots,M$, find $c_{i,j,k}^{n+1} \in \bar{C}_{\text{per}}$, $\psi^{n+1} \in \bar{C}_{\text{per}}$ by solving

$$\begin{cases}
    \frac{c_{i,j,k}^{l,n+1} - c_{i,j,k}^{l,n}}{\Delta t} = \nabla_h \cdot \left( e^{-q_l^i \psi^n} \nabla_h (c_{i,j,k}^{l,n+1} e^{q_l^i \psi^n}) \right), & l = 1,\ldots,M, \\
    -\kappa \Delta_h \psi^{n+1} = \sum_{l=1}^{M} q_l^i c_{i,j,k}^{l,n+1} + \rho_f, & \psi^{n+1} = 0.
\end{cases} \hfill (2.10)
$$

We shall refer the fully discrete scheme (2.10) as the “Slotboom scheme” in the following
sections.

3. Theoretical properties

In this section, we recall several important properties of the semi-implicit
scheme (2.10) in preserving mass conservation, ionic positivity, and energy dissipation
at a discrete level. The detailed proof could be found in the works [9,10,24,25].

Theorem 3.1 (Mass conservation). The semi-implicit scheme (2.10) conserves total
ionic mass, i.e.,

$$h^3 \sum_{i,j,k=1}^{N} c_{i,j,k}^{l,n+1} = h^3 \sum_{i,j,k=1}^{N} c_{i,j,k}^{l,n}. \hfill (3.1)$$

Theorem 3.2 (Positivity preserving). The semi-implicit scheme (2.10) is positivity-
preserving in the sense that if $c_{i,j,k}^{l,n} > 0$, then

$$c_{i,j,k}^{l,n+1} > 0 \text{ for } i,j,k = 1,\ldots,N.$$ The fully discrete free energy is given by

$$F_h^n = \sum_{l=1}^{M} \sum_{i,j,k=1}^{N} h^3 \left[ c_{i,j,k}^{l,n} \log c_{i,j,k}^{l,n} + \frac{1}{2} (q_l^i c_{i,j,k}^{l,n} + \rho_f^i) \psi_{i,j,k}^{n} \right], \hfill (3.2)$$
which is a second-order accurate approximation of $F$ in (1.2) in space. It has been proved that the semi-implicit scheme (2.10) respects free-energy dissipation at a discrete level conditionally [24].

**Theorem 3.3 (Energy dissipation).** If the time step size $\Delta t$ satisfies the sufficient condition $0 < \Delta t \leq \tau^*$, where

$$
\tau^* = \frac{k}{C_1} e^{-h|q|^2\|\nabla_h \psi^n\|_\infty}, \quad \text{with } C_1 = \sum_{l=1}^M |q_l|^2 \max_{1 \leq i \leq M} \{||c_i^{n+1}||_\infty\},
$$

then the discrete free energy $F_h^n$ is non-increasing, in the sense that

$$
F_h^{n+1} - F_h^n \leq -\frac{\Delta t}{2} I^n,
$$

where

$$
I^n = \sum_{l=1}^M \sum_{i,j,k=1}^N h^3 e^{-S_{i,j,k}^n} D_x \left( c_i^{n+1} e^{S_{i,j,k}^n} \right)_{i+j,k} D_y \left( \log \left( c_i^{n+1} e^{S_{i,j,k}^n} \right) \right)_{i+j,k} + \frac{1}{2} \sum_{l=1}^M \sum_{i,j,k=1}^N h^3 e^{-S_{i,j,k}^n} D_y \left( c_i^{n+1} e^{S_{i,j,k}^n} \right)_{i,j+k} D_z \left( \log \left( c_i^{n+1} e^{S_{i,j,k}^n} \right) \right)_{i,j+k+\frac{1}{2}} \geq 0.
$$

Following the proof given in the work [24], we prove this theorem for the semi-implicit scheme (2.10) with the entropic mean in the Appendix.

**Remark 3.1.** It is noticed that, the sufficient condition for the time step size (3.3) relies on the $\| \cdot \|_\infty$ norm of the concentration variable, as well as the $W^{1,\infty}_h$ norm of the electrostatic potential variable, at both the previous and next time steps. Nonetheless, both quantities (for the numerical solutions) are not automatically available; these quantities have to be justified by the convergence estimate of the numerical solution and the corresponding bounds for the exact solution. The details of these estimates shall be presented in the next section. Afterward, a theoretical justification of the discrete energy dissipation is complete.

### 4. Convergence analysis

Let $(\psi_c, c^1_c, c^2_c, \cdots, c^M_c)$ be the exact solutions for the PNP system (1.1). Define $c^l_N := \mathcal{P}_N c^l_c(\cdot, t)$, $\psi_N := \mathcal{P}_N \psi_c(\cdot, t)$, $\rho^l_N := \mathcal{P}_N \rho^l(\cdot)$, the Fourier projection of the exact solution into $\mathcal{B}^K$, which is the space of trigonometric polynomials of the degree to and including $K$ (with $N = 2K + 1$). The following projection approximation is standard: if $(c^l_c, \psi_c) \in L^\infty(0, T; H^{m}_m(\Omega))$, for any $m \in \mathbb{N}$ with $0 \leq k \leq m$,

$$
\|\psi_N - \psi_c\|_{L^\infty(0, T; H^k)} \leq Ch^{m-k}\|\psi_c\|_{L^\infty(0, T; H^m)},
$$

$$
\|c^l_N - c^l_c\|_{L^\infty(0, T; H^k)} \leq Ch^{m-k}\|c^l_c\|_{L^\infty(0, T; H^m)}, \quad l = 1, 2, \cdots, M.
$$

(4.1)

Denote by $\psi_N^n = \psi_N(\cdot, t^n)$ and $c^l_N^n = c^l_N(\cdot, t^n)$ for $l = 1, \cdots, M$. In addition, we define restriction operators

$$(\mathcal{P}_h \psi_N^n)_{i,j,k} := \psi_N^n(x_i, y_j, z_k) \quad \text{for } i, j, k = 1, 2, \cdots, N.$$
Therefore, the mass conservative projections for the initial data are $\psi^0 = \mathcal{P}_h \psi_N(\cdot, t = 0)$, $c_1^0 = \mathcal{P}_h c_N^1(\cdot, t = 0)$ for $l = 1, \ldots, M$.

The error grid function is defined as

$$e^\psi_n := \mathcal{P}_h \psi_N^e - \psi^n, \quad e^l,n := \mathcal{P}_h c_N^l - c^l,n, \quad l = 1, \ldots, M, \quad n \in \mathbb{N}^*.$$ \hfill (4.2)

As indicated above, one can verify that $\bar{e}^\psi_n = 0$, $e^l,n = 0$, for $l = 1, \ldots, M$, $n \in \mathbb{N}^*$.

**Theorem 4.1.** Let $e^\psi_n$ and $e^l,n$ be the error grid functions defined in (4.2). Then, under the linear refinement requirement $C_1 h \leq \Delta t \leq C_2 h$, the following convergence result is available as $\Delta t, h \to 0$:

$$\sum_{l=1}^M \|e^l,n\|^2_2 + \left(\Delta t \sum_{l=1}^M \sum_{k=1}^n \|\nabla_h e^l,n_k\|^2_2\right)^{\frac{1}{2}} + \|e^\psi_n\|_{H^2_h} \leq C(\Delta t + h^2),$$ \hfill (4.3)

where the constant $C > 0$ is independent of $\Delta t$ and $h$.

**4.1. Higher-order consistency analysis.** It follows from the truncation error analysis that the numerical solution to the Slotboom scheme (2.10) approximates the projection solution $(\psi_N, c_N^1, \ldots, c_N^M)$ with only first order accuracy in time and second order accuracy in space. Such a first order accuracy in time is not sufficient to recover an a-priori $\ell^\infty$ bound to ensure the energy stability analysis. Instead, a higher order consistency analysis is performed by adding perturbation terms to recover such a bound. We first construct auxiliary variables, $c_N^l, \psi_N, c^l, \hat{\psi},$ and $\hat{\rho}$:

$$\hat{\psi} = \psi_N + \Delta t \mathcal{P}_N \psi_N, \quad \hat{\rho} = \rho_N, \quad c^l = \psi_N^l + \Delta t \mathcal{P}_N c_N^l, \quad l = 1, \ldots, M,$$ \hfill (4.4)

so that the higher $O(\Delta t^2 + h^2)$ consistency is achieved between the numerical solution and the constructed solution $(\hat{\psi}, c^l)$. The constructed variables $\psi_N, c_N^l, l = 1, \ldots, M$, which solely depend on the exact solutions $c^l_e$ and $\psi_e$, can be found by a perturbation expansion.

It follows from the Taylor expansion for the temporal discretization and the estimate for the projection solution that

$$\frac{c_N^{l,n+1} - c_N^{l,n}}{\Delta t} = \nabla \cdot \left(e^{-q^l e^q \psi_N} \nabla (c_N^{l,n+1} e^q \psi_N)\right) + \Delta t G^{l,n}_{(0)} + O(\Delta t^2), \quad l = 1, \ldots, M,$$ \hfill (4.5)

$$-\kappa \psi_N^{l,n+1} = \sum_{l=1}^M q^l c_N^{l,n+1} + \rho_N^f, \quad \int_{\Omega} \psi_N^{l,n+1} d\mathbf{x} = 0,$$

where the functions $G^{l,n}_{(0)}$, $l = 1, \ldots, M$, are smooth enough in the sense that the temporal and spatial derivatives are bounded. In addition, $G^{l,n}_{(0)}$ is a spatial function with sufficient regularity for a fixed time step $t^n$.

The temporal perturbation variables $(\psi_N, c_N^1, \ldots, c_N^M)$ can be found by solving

$$\partial_t c_N^l = \nabla \cdot \left(e^{-q^l \psi_N} \nabla (q^l c_N^l e^q \psi_N \psi_N) + e^{-q^l \psi_N} \nabla (e^q \psi_N c_N^l) - q^l e^{-q^l \psi_N} \psi_N^l \nabla (c_N^l e^q \psi_N)\right) - G^{l}_{(0)},$$
After spatial discretization, one can obtain by the Taylor expansion for \( \hat{\psi}_t \)
\[ -\kappa \Delta \chi_t = \sum_{l=1}^{M} q^l c^l_{\Delta t}, \quad \int_{\Omega} \chi_t d\mathbf{x} = 0. \]

This is a linear PDE system that depends on the projection solutions \((\psi_N, c^1_N, \cdots, c^M_N)\)
and the existence of its solution is straightforward. In addition, the derivatives of \((\chi_t, c^1_{\Delta t}, \cdots, c^M_{\Delta t})\)
in various orders are bounded. A semi-implicit discretization leads to
\[ \frac{c^{l,n+1}_{\Delta t} - c^{l,n}_{\Delta t}}{\Delta t} = \nabla \cdot \left( e^{-q^l_{\Delta t}} \nabla (q^l_{\Delta t} c^{l,n+1}_{\Delta t} e^{q^l_{\Delta t}} \chi_t) + e^{-q^l_{\Delta t}} \nabla (e^{q^l_{\Delta t}} c^{l,n+1}_{\Delta t}) \right) - G^{l,n}_{(0)} + O(\Delta t), \quad l = 1, \cdots, M, \]

\[ -\kappa \Delta \chi^{n+1}_t = \sum_{l=1}^{M} q^l c^{l,n+1}_{\Delta t}, \quad \int_{\Omega} \chi^{n+1}_t d\mathbf{x} = 0. \]

Therefore, a combination of (4.5) and (4.6) gives the temporal truncation error for \( \hat{c}^l \)
and \( \hat{\psi}_t \):
\[ \frac{\hat{c}^{l,n+1} - \hat{c}^{l,n}}{\Delta t} = \nabla \cdot \left( e^{-q^l_{\Delta t}} \nabla (e^{q^l_{\Delta t}} \hat{c}^{l,n+1}) \right) + O(\Delta t^2), \quad l = 1, \cdots, M, \]

\[ -\kappa \Delta \hat{\psi}^{n+1} = \sum_{l=1}^{M} q^l \hat{c}^{l,n+1} + \hat{\rho}_f, \quad \int_{\Omega} \hat{\psi}^{n+1} d\mathbf{x} = 0. \]

In fact, the following linearized expansions have been used in the derivation of (4.7):
\[ e^{q^l_{\Delta t}} \hat{\psi}_t = e^{q^l_{\Delta t}} (\psi_{N} + \Delta t q^l_{\Delta t} \mathcal{P}_N \chi_t) = e^{q^l_{\Delta t}} \psi_{N} + \Delta t q^l_{\Delta t} \mathcal{P}_N \chi_t e^{q^l_{\Delta t}} \psi_{N} + O(\Delta t^2), \]
\[ e^{-q^l_{\Delta t}} \hat{\psi}_t = e^{-q^l_{\Delta t}} (\psi_{N} + \Delta t q^l_{\Delta t} \mathcal{P}_N \chi_t) = e^{-q^l_{\Delta t}} \psi_{N} - \Delta t q^l_{\Delta t} \mathcal{P}_N \chi_t e^{-q^l_{\Delta t}} \psi_{N} + O(\Delta t^2). \]

After spatial discretization, one can obtain by the Taylor expansion for \((\hat{\psi}, \hat{c}^1, \cdots, \hat{c}^M)\):
\[ \frac{\hat{c}^{l,n+1} - \hat{c}^{l,n}}{\Delta t} = \nabla_h \cdot \left( e^{-q^l_{\Delta t}} \nabla_h (e^{q^l_{\Delta t}} \hat{c}^{l,n}) \right) + \tau^{l,n+1}, \quad l = 1, \cdots, M, \]

\[ -\kappa \Delta_h \hat{\psi}^{n+1} = \sum_{l=1}^{M} q^l \hat{c}^{l,n+1} + \hat{\rho}_f, \quad \hat{\psi}^{n+1} = 0, \]

where
\[ \|\tau^{l,n+1}\|_2 \leq C(\Delta t^2 + h^2). \]

**Remark 4.1.** Since the correction functions only depend on \((\psi_N, c^1_N, c^2_N, \cdots, c^M_N)\)
and the exact solution, we can obtain discrete \(W^{1,\infty}\) bounds from the regularity of the constructed solutions:
\[ \|\hat{c}^{l,n}\|_\infty \leq C^*_0, \quad \|\nabla_h \hat{c}^{l,n}\|_\infty \leq C^*_0, \quad l = 1, \cdots, M, \]
\[ \|\hat{\psi}^n\|_\infty \leq C^*_0, \quad \|\nabla_h \hat{\psi}^n\|_\infty \leq C^*_0, \]

at any time step \(t^n\).
4.2. Error estimate. Instead of working on the original numerical error functions defined in (4.2), we first consider the following ones
\[ \tilde{\psi}^n := \mathcal{P}_h \tilde{\psi}^n - \psi^n, \quad \tilde{c}^{l,n} := \mathcal{P}_h \tilde{c}^{l,n} - c^{l,n}, \quad l = 1, 2, \cdots, M, \ N \in \mathbb{N}^*. \] (4.10)

By the consistency estimate (4.8), a higher-order truncation accuracy is available for these numerical error functions.

Subtracting the numerical scheme (2.10) from the consistency estimate (4.8) yields
\[ \frac{c^{l,n+1} - c^{l,n}}{\Delta t} = \nabla_h \cdot \left( - q \tilde{\psi}^n \nabla_h (c^{l,n+1} e^q \tilde{\psi}^n) \right) + \nabla_h \cdot \left( - q \psi^n \nabla_h (c^{l,n+1} e^q \psi^n) \right) + \tau l,n+1, \quad l = 1, \cdots, M, \]
\[ -\kappa \Delta_h \tilde{\psi}^{n+1} = \sum_{l=1}^M q^l c^{l,n+1}, \quad \tilde{\psi}^{n+1} = 0, \] (4.11)
where \( \tilde{\psi}^{n+1}, \ c^{l,n+1} \in \tilde{C}_{\text{per}}, \ l = 1, 2, \cdots, M. \) As an example, we now take the harmonic mean for the evaluation of the nonlinear mobility functions \( e^{-q'} \psi^n \) (or \( e^{-q'} \tilde{\psi}^n \)) over the staggered mesh points.

Since \( c^{l,n+1} \) and \( c^{l,n+1} e^q \tilde{\psi}^n \) only depend on the exact solutions and the constructed variables, one can assume a discrete \( W^{1,\infty} \) bound
\[ \| \nabla_h (c^{l,n+1} e^q \tilde{\psi}^n) \|_\infty, \| c^{l,n+1} \|_\infty, \| \nabla_h c^{l,n+1} \|_\infty \leq C_0^* . \] (4.12)

In addition, the following a-priori assumption is made, so that the nonlinear analysis could be accomplished by an induction argument:
\[ \| c^{l,n} \|_2 \leq \Delta t^\frac{15}{8} + h^\frac{15}{8}, \quad l = 1, 2, \cdots, M. \] (4.13)

This a-priori assumption will be recovered by the optimal rate convergence analysis at the next time step, as will be demonstrated later. With the error equation for \( \tilde{\psi}^{n+1} \) in (4.11), we apply the preliminary inequalities (2.3), (2.4) in Lemma 2.1 and obtain
\[ \| \tilde{\psi}^{n+1} \|_\infty \leq C \| \Delta_h \tilde{\psi}^n \|_2 \leq C \sum_{l=1}^M q^l \| c^{l,n} \|_2 \leq C (\Delta t^\frac{15}{8} + h^\frac{15}{8}) \leq \frac{1}{4}, \] (4.14)
\[ \| \nabla_h \tilde{\psi}^n \|_\infty \leq C \| \tilde{\psi}^n \|_\infty \leq C (\Delta t^\frac{15}{8} + h^\frac{15}{8}) \leq C (\Delta t^\frac{17}{8} + h^\frac{17}{8}) \leq \frac{1}{4}, \] (4.15)
in which the fact that \( \tilde{\psi}^n \in \tilde{C}_{\text{per}} \) has been applied. Therefore, its combination with the regularity Assumption (4.9) gives a \( W^{1,\infty}_h \) bound for the numerical solution \( \psi^n \) at the previous time step:
\[ \| \psi^n \|_\infty \leq \| \tilde{\psi}^n \|_\infty + \| \tilde{\psi}^n \|_\infty \leq C_3 := C_0^* + \frac{1}{4}, \quad \| \nabla_h \psi^n \|_\infty \leq \| \nabla_h \tilde{\psi}^n \|_\infty + \| \nabla_h \tilde{\psi}^n \|_\infty \leq C_3. \] (4.16)

Before proceeding with the convergence analysis, the following preliminary results are needed.

**Proposition 4.1.** Under the a-priori Assumption (4.13) for the numerical error function at the previous time step, we have
\[ \| e^{-q'} \psi^n \|_\infty, \| \nabla_h (e^q \tilde{\psi}^n) \|_\infty \leq C_4, \] (4.17)
\[ \|e^{-q^l\tilde{\psi}^n} - e^{-q^{l+1}\tilde{\psi}^n}\|_2 \leq \tilde{C}_b \|\tilde{\psi}^n\|_2, \]  
\[ \|e^{q^l\tilde{\psi}^n} - e^{q^{l+1}\tilde{\psi}^n}\|_2 \leq \tilde{C}_b \|\tilde{\psi}^n\|_2, \]  
\[ \|\|\nabla_h(e^{q^l\tilde{\psi}^n} - e^{q^{l+1}\tilde{\psi}^n})\||_2 \leq \tilde{C}_7(\|\tilde{\psi}^n\|_2 + \|\nabla_h\tilde{\psi}^n\|_2), \]  
for any \( l = 1, \ldots, M \), in which the harmonic mean formula in (2.6) has been applied in the evaluation of \( e^{-q^l\tilde{\psi}^n} \) and \( e^{-q^{l+1}\tilde{\psi}^n} \) at the staggered grid points. Notice that the constants \( \tilde{C}_j \) (4 \( \leq j \leq 7 \)) are independent of \( \Delta t \) and \( h \).

**Proof.** By the harmonic mean formula for \( e^{-q^l\tilde{\psi}^n} \) (in (2.6)), we find that

\[ |e^{-q^l\psi_{i+\frac{1}{2},j,k}}| = \left( \frac{e^{q^l\psi_{i+1,j,k}} + e^{q^l\psi_{i,j,k}}}{2} \right)^{-1} \leq \left( e^{q^l|\xi|(-\tilde{C}_3)} \right)^{-1} = e^{q^l|\tilde{C}_3|}, \]  

at each staggered grid point \((i + \frac{1}{2},j,k)\), in which the \( \|\cdot\|_\infty \) bound (4.16) has been used. Similar derivations could be applied at the staggered grid points in the \( y \) and \( z \) directions. Then we get \( \|e^{-q^l\tilde{\psi}^n}\|_\infty \leq e^{q^l|\tilde{C}_3|} \). Using similar argument, we are able to prove that \( \|e^{-q^l\tilde{\psi}^n}\|_\infty \leq e^{q^l|\tilde{C}_b|} \).

For the second inequality in (4.17), we observe the following expansion at each numerical mesh cell, from \((i,j,k)\) to \((i+1,j,k)\):

\[ D_x(e^{q^l\psi^n})_{i+\frac{1}{2},j,k} = \frac{e^{q^l\psi^n_{i+1,j,k}} - e^{q^l\psi^n_{i,j,k}}}{\Delta x} = q^l e^{q^l\xi^{(1)}(i,j,k)}, \]  
in which the intermediate value theorem has been applied, and \( \xi^{(1)} \) is between \( \psi^n_{i,j,k} \) and \( \psi^n_{i+1,j,k} \). Then we conclude that

\[ \|e^{q^l\xi^{(1)}}\|_\infty \leq e^{q^l|\psi^n|\|\psi^n\|_\infty} \leq e^{q^l|\tilde{C}_3|}. \]  

As a consequence, an application of discrete Hölder inequality gives

\[ \|D_x(e^{q^l\psi^n})\|_\infty \leq \|e^{q^l\xi^{(1)}}\|_\infty \cdot \|D_x\psi^n\|_\infty \leq |q^l|e^{q^l|\tilde{C}_3|} \tilde{C}_3, \]

in which the a-priori estimate (4.16) has been applied in the last step. Similar bounds could be derived for \( \|D_y(e^{q^l\psi^n})\|_\infty \), \( \|D_z(e^{q^l\psi^n})\|_\infty \), respectively. Then we obtain \( \|\nabla_h(e^{q^l\psi^n})\|_\infty \leq |q^l|e^{q^l|\tilde{C}_3|} \tilde{C}_3 \). As a result, both inequalities in (4.17) have been proved, by taking \( \tilde{C}_3 = \max(e^{q^l|\tilde{C}_3|}, |q^l|e^{q^l|\tilde{C}_3|} \tilde{C}_3) \).

To prove the inequality (4.18), we see that the expansion (4.20) indicates the following identity:

\[ e^{-q^l\tilde{\psi}^n_{i+\frac{1}{2},j,k}} - e^{-q^l\tilde{\psi}^n_{i+\frac{1}{2},j,k}} \]

\[ = -\frac{1}{2} e^{-q^l\tilde{\psi}^n_{i+\frac{1}{2},j,k}} e^{-q^l\tilde{\psi}^n_{i+\frac{1}{2},j,k}} \left( e^{q^l\tilde{\psi}^n_{i+1,j,k}} + e^{q^l\tilde{\psi}^n_{i,j,k}} \right) \]

\[ = -\frac{1}{2} e^{-q^l\tilde{\psi}^n_{i+\frac{1}{2},j,k}} e^{-q^l\tilde{\psi}^n_{i+\frac{1}{2},j,k}} \left( e^{q^l\tilde{\psi}^n_{i+1,j,k}} + e^{q^l\tilde{\psi}^n_{i,j,k}} \right) \]

\[ = -\frac{1}{2} e^{-q^l\tilde{\psi}^n_{i+\frac{1}{2},j,k}} e^{-q^l\tilde{\psi}^n_{i+\frac{1}{2},j,k}} \left( e^{q^l\xi^{(2)}} \gamma^n_{i+1,j,k} + e^{q^l\xi^{(3)}} \gamma^n_{i,j,k} \right), \]

in which the intermediate value theorem has been applied, \( \xi^{(2)} \) is between \( \psi^n_{i+1,j,k} \) and \( \psi^n_{i+1,j,k} \), \( \xi^{(3)} \) is between \( \psi^n_{i,j,k} \) and \( \psi^n_{i,j,k} \), respectively. By the regularity Assumption (4.9) and the a-priori \( \|\cdot\|_\infty \) bound (4.16), we see that

\[ \|e^{q^l\xi^{(2)}}\|_\infty, \|e^{q^l\xi^{(3)}}\|_\infty \leq e^{q^l|\tilde{C}_3|}. \]

(4.25)
Therefore, an application of discrete H"older inequality reveals that
\[
\| e^{-q_i \hat{\psi}^n} - e^{-q_i \psi^n} \|_2 \leq \frac{|q_i|}{2} \| e^{-q_i \hat{\psi}^n} \|_\infty \cdot \| e^{-q_i \psi^n} \|_\infty \left( \| e^{q_i \xi^{(2)}} \|_\infty \cdot \| \hat{\psi}^n \|_2 + \| e^{q_i \xi^{(3)}} \|_\infty \cdot \| \tilde{\psi}^n \|_2 \right) 
\leq \frac{|q_i|}{2} e^{q_i |\tilde{C}_3|} \cdot e^{q_i |\tilde{C}_0^*|} \cdot 2e^{q_i |\tilde{C}_3|} \| \hat{\psi}^n \|_2 \leq |q_i| e^{3q_i |\tilde{C}_3|} \| \tilde{\psi}^n \|_2,
\] (4.26)
in which (4.17) is recalled. This proves the inequality (4.18), by taking \( \tilde{C}_5 = |q_i| e^{3q_i |\tilde{C}_3|} \).

To prove the inequalities (4.19), we begin with the following difference formula at each grid point:
\[
e^{q_i \hat{\psi}^n_{i,j,k}} - e^{q_i \psi^n_{i,j,k}} = q_i e^{q_i \xi^{(4)}_{i,j,k}} \hat{\psi}^n_{i,j,k}, \tag{4.27}
\] using the intermediate value theorem, with \( \xi^{(4)}_{i,j,k} \) being between \( \psi^n_{i,j,k} \) and \( \tilde{\psi}^n_{i,j,k} \). Therefore, we have
\[
\| \xi^{(4)} \|_\infty \leq \max(\| \psi^n \|_\infty, \| \hat{\psi}^n \|_\infty) \leq \max(\tilde{C}_3, C_0^*) = \tilde{C}_3, \quad \| e^{q_i \xi^{(4)}} \|_\infty \leq |q_i| e^{q_i |\tilde{C}_3|} \| \tilde{\psi}^n \|_2, \tag{4.28}
\]
In turn, an application of discrete H"older inequality gives
\[
\| e^{q_i \hat{\psi}^n} - e^{q_i \psi^n} \|_2 \leq \| e^{q_i \xi^{(4)}} \|_\infty \cdot \| \hat{\psi}^n \|_2 \leq \| q_i | e^{q_i |\tilde{C}_3|} \| \tilde{\psi}^n \|_2, \tag{4.29}
\]
so that the first inequality in (4.19) is proved, by taking \( \tilde{C}_6 = |q_i| e^{q_i |\tilde{C}_3|} \).

To prove the second inequality in (4.19), we recall the point-wise expansion (4.27), and look at the numerical mesh cell from \((i,j,k)\) to \((i+1,j,k)\):
\[
e^{q_i \hat{\psi}^n_{i,j,k}} - e^{q_i \psi^n_{i,j,k}} = q_i e^{q_i \xi^{(4)}_{i,j,k}} \hat{\psi}^n_{i,j,k}, \quad e^{q_i \psi^n_{i+1,j,k}} - e^{q_i \psi^n_{i,j,k}} = q_i e^{q_i \xi^{(4)}_{i+1,j,k}} \psi^n_{i+1,j,k}, \tag{4.30}
\]
in which turn leads to the gradient expansion in the \( x \) direction:
\[
D_x(e^{q_i \hat{\psi}^n} - e^{q_i \psi^n})_{i+\frac{1}{2},j,k} = q_i e^{q_i \xi^{(4)}_{i,j,k}} (D_x \hat{\psi}^n)_{i+\frac{1}{2},j,k} + \frac{e^{q_i \xi^{(4)}_{i+1,j,k}} - e^{q_i \xi^{(4)}_{i,j,k}}}{h} \tilde{\psi}^n_{i+1,j,k}. \tag{4.31}
\]
With the \( \| \cdot \|_\infty \) bound in (4.28), it is straightforward to get an \( \| \cdot \|_2 \) estimate for the first term. For the second term, we begin with the following observation:
\[
e^{q_i \xi^{(4)}_{i,j,k}} - e^{q_i \psi^n_{i,j,k}} = q_i e^{q_i \xi^{(5)}_{i,j,k}} (\xi^{(4)}_{i,j,k} - \psi^n_{i,j,k}), \quad \text{with } \xi^{(5)}_{i,j,k} \text{ between } \xi^{(4)}_{i,j,k} \text{ and } \psi^n_{i,j,k}. \tag{4.32}
\]
Moreover, by the fact that \( \xi^{(4)}_{i,j,k} \) is between \( \psi^n_{i,j,k} \) and \( \tilde{\psi}^n_{i,j,k} \), we conclude that
\[
\| \xi^{(5)} \|_\infty \leq \max(\| \psi^n \|_\infty, \| \tilde{\psi}^n \|_\infty) \leq \max(\tilde{C}_3, C_0^*) = \tilde{C}_3, \quad |e^{q_i \xi^{(5)}_{i,j,k}}| \leq |e^{q_i |\tilde{C}_3|} \| \tilde{\psi}^n \|_2, \tag{4.33}
\]
\[
|\xi^{(4)}_{i,j,k} - \psi^n_{i,j,k}| \leq |\tilde{\psi}^n_{i,j,k} - \psi^n_{i,j,k}| = |\tilde{\psi}^n_{i,j,k}|, \tag{4.34}
\]
so that
\[
|e^{q_i \xi^{(4)}_{i,j,k}} - e^{q_i \psi^n_{i,j,k}}| \leq C e^{q_i |\tilde{C}_3|} (\Delta t^{\frac{15}{2}} + h^{\frac{15}{2}}), \tag{4.35}
\]
in which the a-priori \( \| \cdot \|_\infty \) estimate (4.14) has been applied. Using similar arguments, the following estimate is also available:
\[
|e^{q_i \xi^{(4)}_{i+1,j,k}} - e^{q_i \psi^n_{i+1,j,k}}| \leq C e^{q_i |\tilde{C}_3|} (\Delta t^{\frac{15}{2}} + h^{\frac{15}{2}}). \tag{4.36}
\]
Then we arrive at
\[
\left| \frac{e^q \xi^{(4)}_{i+1,j,k} - e^q \xi^{(4)}_{i,j,k}}{h} \right| \leq \left| \frac{e^q \psi^n_{i+1,j,k} - e^q \psi^n_{i,j,k}}{h} \right| + C e^q |\tilde{C}_3| \left( \frac{\Delta t}{8} + h \right)
\]
\[
\leq \| \nabla_h (e^q \psi^n) \|_\infty + \frac{1}{4} \leq \tilde{C}_4 + \frac{1}{4},
\]
(4.37)
under the linear refinement constraint \( C_1 h \leq \Delta t \leq C_2 h \), and the bound (4.17) has been recalled in the last step. Since this inequality is valid at any numerical mesh, we get
\[
\| D_x (e^q \xi^{(4)}) \|_\infty \leq \tilde{C}_4 + \frac{1}{4}.
\]
(4.38)

Therefore, an application of discrete Hölder inequality to the expansion formula (4.31) indicates that
\[
\| D_x (e^q \cdot \tilde{\psi} - e^q \psi^n) \|_2 \leq |q| \cdot \| e^q \xi^{(4)} \|_\infty \cdot \| D_x \tilde{\psi} \|_2 + |q| \cdot \| D_x (e^q \xi^{(4)}) \|_\infty \cdot \| \tilde{\psi} \|_2
\]
\[
\leq |q| \cdot |\tilde{C}_3| \| D_x \tilde{\psi} \|_2 + |q| \left( \tilde{C}_4 + \frac{1}{4} \right) \| \tilde{\psi} \|_2.
\]
(4.39)

Similar estimates could be derived for the discrete gradient in the \( y \) and \( z \) directions, and we are able to obtain the following inequality:
\[
\| \nabla_h (e^q \psi^n - e^q \psi^n) \|_2 \leq |q| \cdot |\tilde{C}_3| \| \nabla_h \tilde{\psi} \|_2 + \sqrt{3} |q| \left( \tilde{C}_4 + \frac{1}{4} \right) \| \tilde{\psi} \|_2.
\]
(4.40)

As a result, the second inequality of (4.19) is established, by taking \( \tilde{C}_7 = |q| \max(e^q|\tilde{C}_3|, \sqrt{3} (\tilde{C}_4 + \frac{1}{4})) \). This finishes the proof of Proposition 4.1.

Now we proceed with the error estimate. Taking a discrete inner product with \( 2\tilde{c}_{l,n+1} \) leads to
\[
\frac{1}{\Delta t} \left( \| \tilde{c}_{l,n+1} \|_2^2 - \| \tilde{c}_{l,n} \|_2^2 + \| \tilde{c}_{l,n+1} - \tilde{c}_{l,n} \|_2^2 \right) + 2 \left( e^{-q \tilde{\psi}} \nabla_h (e^{q \psi} \tilde{c}_{l,n+1}), \nabla_h \tilde{c}_{l,n+1} \right)
\]
\[
= -2 \left( e^{-q \tilde{\psi}} - e^{-q \tilde{\psi}} \nabla_h (e^{q \psi} \tilde{c}_{l,n+1}), \nabla_h \tilde{c}_{l,n+1} \right)
\]
\[
-2 \left( e^{-q \tilde{\psi}} \nabla_h (e^{q \psi} \tilde{c}_{l,n+1} - e^{q \psi} \tilde{c}_{l,n}), \nabla_h \tilde{c}_{l,n+1} \right) + 2 \left( \tau^{l,n+1}, \tilde{c}_{l,n+1} \right).
\]
(4.41)

The bound for the local truncation error term is straightforward:
\[
2 \left( \tau^{l,n+1}, \tilde{c}_{l,n+1} \right) \leq \| \tau^{l,n+1} \|_2^2 + \| \tilde{c}_{l,n+1} \|_2^2.
\]
(4.42)

For the nonlinear term on the left-hand side, we examine a single numerical mesh cell, from \((i,j,k)\) to \((i+1,j,k)\), and observe the following expansion identity:
\[
D_x (f g)_{i,j,k} = (A_x f)_{i,j,k} (D_x g)_{i,j,k} + (A_x g)_{i,j,k} (D_x f)_{i,j,k},
\]
(4.43)

Thus, we get
\[
D_x (e^{q \psi} \tilde{c}_{l,n+1}) = A_x \tilde{c}_{l,n+1} \cdot D_x e^{q \psi} + A_x e^{q \psi} \cdot D_x \tilde{c}_{l,n+1},
\]
(4.44)

\[
e^{-q \psi} D_x (e^{q \psi} \tilde{c}_{l,n+1}) = A_x \tilde{c}_{l,n+1} \cdot D_x e^{q \psi} \cdot e^{-q \psi} + D_x \tilde{c}_{l,n+1},
\]
(4.45)
in which the following point-wise identity has been applied in the derivation:
\[
e^{-q^i \psi^n_k} (A_x e^{q^j \psi^n_k})_{i+\frac{1}{2},j,k} = \left(\frac{e^{q^i \psi^n_{i+1,j,k}} + e^{q^i \psi^n_{i,j,k}}}{2}\right)^{-1} \cdot \frac{e^{q^i \psi^n_{i+1,j,k}} + e^{q^i \psi^n_{i,j,k}}}{2} = 1, \text{ (by (2.6))}. \tag{4.46}
\]

Then we arrive at
\[
\begin{align*}
\langle e^{-q^i \psi^n} D_x (c^{l,n+1} e^{q^j \psi^n}), D_x c^{l,n+1} \rangle &= \| D_x c^{l,n+1} \|_2^2 + \langle A_x c^{l,n+1} (D_x e^{q^j \psi^n}) e^{-q^j \psi^n}, D_x c^{l,n+1} \rangle \\
&\geq \| D_x c^{l,n+1} \|_2^2 - \| A_x c^{l,n+1} \|_2 \cdot \| D_x e^{q^j \psi^n} \|_\infty \cdot \| e^{-q^j \psi^n} \|_\infty \cdot \| D_x c^{l,n+1} \|_2 \\
&\geq \| D_x c^{l,n+1} \|_2^2 - \tilde{C}_1^2 \| c^{l,n+1} \|_2 \cdot \| D_x c^{l,n+1} \|_2, \tag{4.47}
\end{align*}
\]

in which the preliminary \( \| \cdot \|_\infty \) bound (4.17) (in Proposition 4.1) has been applied in the last step. Similar inequalities could be derived in the \( y \) and \( z \) directions, respectively:
\[
\begin{align*}
\langle e^{-q^i \psi^n} D_y (c^{l,n+1} e^{q^j \psi^n}), D_y c^{l,n+1} \rangle &\geq \| D_y c^{l,n+1} \|_2^2 - \tilde{C}_2^2 \| c^{l,n+1} \|_2 \cdot \| D_y c^{l,n+1} \|_2, \tag{4.48}
\end{align*}
\]
\[
\begin{align*}
\langle e^{-q^i \psi^n} D_z (c^{l,n+1} e^{q^j \psi^n}), D_z c^{l,n+1} \rangle &\geq \| D_z c^{l,n+1} \|_2^2 - \tilde{C}_3^2 \| c^{l,n+1} \|_2 \cdot \| D_z c^{l,n+1} \|_2. \tag{4.49}
\end{align*}
\]

As a result, the following estimate becomes available for the nonlinear inner product on the left-hand side:
\[
\begin{align*}
\langle e^{-q^i \psi^n} \nabla_h (c^{l,n+1} e^{q^j \psi^n}), \nabla_h c^{l,n+1} \rangle \\
&\geq \| \nabla_h c^{l,n+1} \|_2^2 - \tilde{C}_4^2 \| c^{l,n+1} \|_2 \cdot (\| D_x \nabla_h c^{l,n+1} \|_2 + \| D_y \nabla_h c^{l,n+1} \|_2 + \| D_z \nabla_h c^{l,n+1} \|_2) \\
&\geq \| \nabla_h c^{l,n+1} \|_2^2 - \sqrt{3} \tilde{C}_4^2 \| c^{l,n+1} \|_2 \cdot \| \nabla_h c^{l,n+1} \|_2 \\
&\geq \| \nabla_h c^{l,n+1} \|_2^2 - \frac{1}{4} \| \nabla_h c^{l,n+1} \|_2^2 - 3 \tilde{C}_4^2 \| c^{l,n+1} \|_2^2 - \frac{3}{4} \| \nabla_h c^{l,n+1} \|_2^2 - 3 \tilde{C}_4^2 \| c^{l,n+1} \|_2^2. \tag{4.50}
\end{align*}
\]

The first nonlinear inner product term on the right-hand side could be analyzed with the help of the \( W_{1,\infty}^h \) regularity Assumption (4.12):
\[
\begin{align*}
- \langle (e^{-q^i \psi^n} - e^{-q^i \psi^n}) \nabla_h (c^{l,n+1} e^{q^j \psi^n}), \nabla_h c^{l,n+1} \rangle \\
&\leq \| \nabla_h (c^{l,n+1} e^{q^j \psi^n}) \|_\infty \cdot \| e^{-q^i \psi^n} - e^{-q^i \psi^n} \|_2 \cdot \| \nabla_h c^{l,n+1} \|_2 \\
&\leq C_0^2 \cdot \tilde{C}_5 \| \psi^n \|_2 \cdot \| \nabla_h c^{l,n+1} \|_2 \leq \frac{1}{4} \| \nabla_h c^{l,n+1} \|_2^2 + (C_0^2 \tilde{C}_5 \| \psi^n \|_2, \tag{4.51}
\end{align*}
\]
in which the preliminary \( \| \cdot \|_2 \) estimate (4.18) (in Proposition 4.1) has been recalled.

To analyze the second nonlinear inner product term on the right-hand side, we make use of the expansion identity (4.43) and observe that
\[
D_x (c^{l,n+1} (e^{q^i \psi^n} - e^{q^i \psi^n})) = A_x c^{l,n+1} \cdot D_x (e^{q^i \psi^n} - e^{q^i \psi^n}) + A_x (e^{q^i \psi^n} - e^{q^i \psi^n}) \cdot D_x c^{l,n+1}. \tag{4.52}
\]

This in turn implies that
\[
- \langle e^{-q^i \psi^n} D_x (c^{l,n+1} (e^{q^i \psi^n} - e^{q^i \psi^n})), D_x c^{l,n+1} \rangle
\]
\[
\begin{align*}
\langle e^{-q^l \psi^n} (A_x e_x^{l,n+1} \cdot D_x (e^{q^l \psi^n} - e^{q^l \psi^n}) + A_x (e^{q^l \psi^n} - e^{q^l \psi^n}) \cdot D_x e_x^{l,n+1}) \rangle_{\mathbb{E}} \\
\leq \|e^{-q^l \psi^n}\|_{\infty} \cdot \|e_x^{l,n+1}\|_{\infty} \cdot \|D_x (e^{q^l \psi^n} - e^{q^l \psi^n})\|_2 \cdot \|D_x e_x^{l,n+1}\|_2 \\
+ \|e^{-q^l \psi^n}\|_{\infty} \cdot \|D_x e_x^{l,n+1}\|_{\infty} \cdot \|e^{q^l \psi^n} - e^{q^l \psi^n}\|_2 \cdot \|D_x e_x^{l,n+1}\|_2 \\
\leq \tilde{C}_4 \tilde{C}_6 \left( \tilde{C}_6 \|\tilde{\psi}^n\|_2 + \tilde{C}_7 (\|\tilde{\psi}^n\|_2 + \|\nabla_h \tilde{\psi}^n\|_2) \right) \|D_x e_x^{l,n+1}\|_2 \\
\leq \frac{1}{4} \|D_x e_x^{l,n+1}\|_2^2 + 2 \tilde{C}_4^2 (\tilde{C}_6)^2 \left( \tilde{C}_6 + \tilde{C}_7 \right)^2 \|\tilde{\psi}^n\|_2^2 + \tilde{C}_7^2 \|\nabla_h \tilde{\psi}^n\|_2^2.
\end{align*}
\]

in which the preliminary estimates (4.17), (4.19) (in Proposition 4.1), as well as the regularity Assumption (4.9), have been extensively used. The inequalities in the \( y \) and \( z \) directions could be derived in a similar manner. Then we are able to obtain

\[
\begin{align*}
- \langle e^{-q^l \psi^n} \nabla_h (e_x^{l,n+1} (e^{q^l \psi^n} - e^{q^l \psi^n})) \rangle_{\mathbb{E}} & \\
& \leq \frac{1}{4} \|\nabla_h e_x^{l,n+1}\|_2^2 + 6 \tilde{C}_4^2 (\tilde{C}_6)^2 \left( \tilde{C}_6 + \tilde{C}_7 \right)^2 \|\tilde{\psi}^n\|_2^2 + \tilde{C}_7^2 \|\nabla_h \tilde{\psi}^n\|_2^2.
\end{align*}
\]

Finally, a substitution of (4.42), (4.50), (4.51) and (4.54) into (4.41) leads to

\[
\begin{align*}
\frac{1}{\Delta t} (\|\tilde{c}^{l,n+1}\|_2^2 - \|\tilde{c}^{l,n}\|_2^2) + \frac{1}{2} \|\nabla_h \tilde{c}^{l,n+1}\|_2^2 & \\
& \leq \|\tilde{\tau}^{l,n+1}\|_2^2 + (6 \tilde{C}_4^4 + 1) \|\tilde{c}^{l,n+1}\|_2^2 + \tilde{C}_9 \|\nabla_h \tilde{\psi}^n\|_2^2,
\end{align*}
\]

with \( \tilde{C}_8 = (\tilde{C}_6)^2 \left( 2 \tilde{C}_4^2 + 12 \tilde{C}_4^2 (\tilde{C}_6 + \tilde{C}_7)^2 \right) \), \( \tilde{C}_9 = 12 (\tilde{C}_6)^2 \tilde{C}_4^2 \tilde{C}_7^2 \). Meanwhile, the discrete elliptic regularity inequality (2.2) (in Lemma 2.1) indicates that

\[
\tilde{C}_8 \|\tilde{\psi}^n\|_2 + \tilde{C}_9 \|\nabla_h \tilde{\psi}^n\|_2 \leq C (\tilde{C}_8 + \tilde{C}_9) \|\Delta_h \tilde{\psi}^n\|_2 \leq C (\tilde{C}_8 + \tilde{C}_9) \left( \sum_{l=1}^{M} (q^l)^2 \|\tilde{c}^{l,n}\|_2^2 \right)
\]

\[
\leq CM(\tilde{C}_8 + \tilde{C}_9) \sum_{l=1}^{M} (q^l)^2 \|\tilde{c}^{l,n}\|_2^2.
\]

Its substitution into (4.55) yields

\[
\begin{align*}
\frac{1}{\Delta t} (\|\tilde{c}^{l,n+1}\|_2^2 - \|\tilde{c}^{l,n}\|_2^2) + \frac{1}{2} \|\nabla_h \tilde{c}^{l,n+1}\|_2^2 & \\
& \leq \|\tilde{\tau}^{l,n+1}\|_2^2 + (6 \tilde{C}_4^4 + 1) \|\tilde{c}^{l,n+1}\|_2^2 + CM(\tilde{C}_8 + \tilde{C}_9) \sum_{l=1}^{M} (q^l)^2 \|\tilde{c}^{l,n}\|_2^2.
\end{align*}
\]

Subsequently, a summation over all ionic species gives

\[
\sum_{l=1}^{M} \left( \frac{1}{\Delta t} (\|\tilde{c}^{l,n+1}\|_2^2 - \|\tilde{c}^{l,n}\|_2^2) + \frac{1}{2} \|\nabla_h \tilde{c}^{l,n+1}\|_2^2 \right) \\
\leq \sum_{l=1}^{M} \left( \|\tilde{\tau}^{l,n+1}\|_2^2 + (6 \tilde{C}_4^4 + 1) \|\tilde{c}^{l,n+1}\|_2^2 \right) + CM^2(\tilde{C}_8 + \tilde{C}_9) \sum_{l=1}^{M} (q^l)^2 \|\tilde{c}^{l,n}\|_2^2.
\]

An application of discrete Gronwall inequality leads to

\[
\sum_{l=1}^{M} \|\tilde{c}^{l,n+1}\|_2 + (\Delta t \sum_{l=1}^{M} \sum_{k=1}^{n+1} \|\nabla_h \tilde{c}^{l,k}\|_2) \leq \tilde{C} (\Delta t^2 + h^2),
\]

where \( J. DING, C. WANG, AND S. ZHOU \).
based on the higher order truncation error accuracy, \( \| \tau^{l,n+1} \|_2 \leq C(\Delta t^2 + h^2), \ l = 1, \cdots, M. \)

With this higher order error estimate, we notice that the a-priori Assumption (4.13) is satisfied at the next time step \( t^{n+1} \):

\[
\| \tilde{c}^{l,n+1} \|_2 \leq \tilde{C}(\Delta t^2 + h^2) \leq \frac{\Delta t^{15}}{\pi} + \frac{h^{15}}{\pi}, \quad 1 \leq l \leq M,
\]

provided that \( \Delta t \) and \( h \) are sufficiently small. Therefore, an induction analysis could be applied. This finishes the higher order convergence analysis.

As a result, the convergence estimate (4.3) for the variable \( (c^l, \cdots, c^M) \) is a direct consequence of (4.59), combined with the definition (4.4) of the constructed approximate solution \( (c^l_N, c^2_N, \cdots, c^M_N) \), as well as the projection estimate (4.2).

In terms of the convergence estimate for the electric potential \( \psi \), we recall the definition for \( \tilde{\psi}^{n+1} \) and observe that

\[
\| \tilde{\psi}^{n+1} \|_{H^2_h} \leq C\| \Delta_h \tilde{\psi}^{n+1} \|_2 \leq \frac{C}{\kappa} \sum_{l=1}^M |q^l| \| \tilde{c}^{l,n+1} \|_2 \leq \tilde{C}_2(\Delta t^2 + h^2),
\]

in which the discrete elliptic regularity estimate (2.2) (in Lemma 2.1) has been applied in the first step. Meanwhile, the following inequality is available:

\[
\| \tilde{\psi}^{n+1} - e^{n+1}_\psi \|_{H^2_h} \leq C\| \Delta_h (\tilde{\psi}^{n+1} - e^{n+1}_\psi) \|_2 \leq \tilde{C}_3 \Delta t,
\]

since

\[
(-\Delta_h)(\tilde{\psi}^{n+1} - e^{n+1}_\psi) = \sum_{l=1}^M q^l (\tilde{c}^{l,n+1} - c^{l,n+1}_N) = \sum_{l=1}^M q^l (\Delta t P_N c^{l,n+1}_t).
\]

Finally, we arrive at

\[
\| e^{n+1}_\psi \|_{H^2_h} \leq \| \tilde{\psi}^{n+1} \|_{H^2_h} + \| \tilde{\psi}^{n+1} - e^{n+1}_\psi \|_{H^2_h} \leq \tilde{C}_4(\Delta t + h^2).
\]

This completes the proof of Theorem 4.1.

**4.3. Theoretical justification of energy dissipation.** By the estimate (4.59), the \( \| \cdot \|_\infty \) error bound for the concentration variable at the next time step is available:

\[
\| c^{l,n+1} \|_\infty \leq \frac{C\| \tilde{c}^{l,n+1} \|_2}{h^{3/2}} \leq \frac{C(\Delta t^{15}/\pi + h^{15}/\pi)}{h^{3/2}} \leq C(\Delta t^3 + h^3) \leq \frac{1}{4}, \quad l = 1, 2, \cdots, M.
\]

(4.61)

Again, with the help of the regularity Assumption (4.9), an \( \ell^\infty \) bound for the numerical solution can be derived at the next time step:

\[
\| c^{l,n+1} \|_\infty \leq \| c^{l,n+1} \|_\infty + \| \tilde{c}^{l,n+1} \|_\infty \leq \tilde{C}_3, \quad l = 1, 2, \cdots, M.
\]

(4.62)

Therefore, with the \( \| \cdot \|_\infty \) bounds (4.62) and (4.16) for the numerical solutions, \( c^{l,n+1} \) (evaluated at the next time step) and \( \nabla_h \tilde{\psi}^n \) (evaluated at the previous time step), a lower bound of \( \tau^* \) in (3.3) can be established:

\[
\tau^* \geq \tau^*_\min := \frac{\kappa}{\tilde{C}_3 \sum_{l=1}^M |q^l|^2} e^{-|q^l| h \tilde{C}_3}.
\]

As a result, the proof of Theorem 3.3 can be theoretically justified, as long as the time step size satisfies \( 0 < \Delta t \leq \tau^*_\min. \)
4.4. Error analysis with other mobility means. The convergence analysis presented above focuses on the harmonic mean for the mobility average. We remark that the convergence estimate will still go through for the other options, such as the geometric mean, arithmetic mean, or entropic mean (formulated in (2.6)).

In fact, the asymptotic expansion (4.4) and the higher order consistency estimate (4.8) take the same form, which in turn give the same error evolutionary equation (4.11). The a-priori Assumption (4.13) and the a-priori estimates (4.14)-(4.16) are not affected by the choices of the mobility average. Proposition 4.1 is still valid, in which the inequalities (4.17) and (4.18) are defined in a similar manner, for different options of $e^{-q^i\psi^n}$ at staggered grid points.

The only essential difference will be the corresponding estimate (4.46), in which the exact identity is not valid any more. Meanwhile, the $\|\cdot\|_\infty$ bound (4.16) for $\psi^n$ implies that

$$e^{-q^i\psi^n_{i+\frac{1}{2},j,k}} (A_x e^{q^i\psi^n})_{i+\frac{1}{2},j,k} \geq B_0 > 0, \quad B_0 \text{ dependent on } \tilde{C}_3. \quad (4.63)$$

In turn, the corresponding estimates in (4.47) and (4.50) become

$$\left\langle e^{-q^i\psi^n} D_x (\tilde{c}^{l,n+1} e^{q^i\psi^n}), D_x \tilde{c}^{l,n+1} \right\rangle
= B_0 \| D_x \tilde{c}^{l,n+1} \|_2^2 + \left\langle A_x \tilde{c}^{l,n+1} (D_x e^{q^i\psi^n}) e^{-q^i\psi^n}, D_x \tilde{c}^{l,n+1} \right\rangle
\geq B_0 \| D_x \tilde{c}^{l,n+1} \|_2^2 - \| A_x \tilde{c}^{l,n+1} \|_2 \cdot \| D_x e^{q^i\psi^n} \|_\infty \cdot \| e^{-q^i\psi^n} \|_\infty \cdot \| D_x \tilde{c}^{l,n+1} \|_2
\geq B_0 \| D_x \tilde{c}^{l,n+1} \|_2^2 - \tilde{C}_4^2 \| \tilde{c}^{l,n+1} \|_2 \cdot \| D_x \tilde{c}^{l,n+1} \|_2, \quad (4.64)$$

$$\left\langle e^{-q^i\psi^n} \nabla_h (\tilde{c}^{l,n+1} e^{q^i\psi^n}), \nabla_h \tilde{c}^{l,n+1} \right\rangle
\geq B_0 \| \nabla_h \tilde{c}^{l,n+1} \|_2^2 - \tilde{C}_4^2 \| \tilde{c}^{l,n+1} \|_2 \cdot (\| D_x \tilde{c}^{l,n+1} \|_2 + \| D_y \tilde{c}^{l,n+1} \|_2 + \| D_z \tilde{c}^{l,n+1} \|_2)
\geq B_0 \| \nabla_h \tilde{c}^{l,n+1} \|_2^2 - \sqrt{3} \tilde{C}_4^2 \| \tilde{c}^{l,n+1} \|_2 \cdot \| \nabla_h \tilde{c}^{l,n+1} \|_2
\geq B_0 \| \nabla_h \tilde{c}^{l,n+1} \|_2^2 - \frac{1}{4} B_0 \| \nabla_h \tilde{c}^{l,n+1} \|_2^2 - 3 \tilde{C}_4^2 B_0^{-1} \| \tilde{c}^{l,n+1} \|_2^2
= -\frac{3}{4} B_0 \| \nabla_h \tilde{c}^{l,n+1} \|_2^2 - 3 \tilde{C}_4^2 B_0^{-1} \| \tilde{c}^{l,n+1} \|_2^2. \quad (4.65)$$

Similarly, the estimates in (4.51) and (4.54) could be derived as

$$-\left\langle (e^{-q^i\tilde{\psi}^n} - e^{-q^i\psi^n}) \nabla_h (\tilde{c}^{l,n+1} e^{q^i\tilde{\psi}^n}), \nabla_h \tilde{c}^{l,n+1} \right\rangle
\leq \| \nabla_h (\tilde{c}^{l,n+1} e^{q^i\tilde{\psi}^n}) \|_\infty \cdot \| e^{-q^i\tilde{\psi}^n} - e^{-q^i\psi^n} \|_2 \cdot \| \nabla_h \tilde{c}^{l,n+1} \|_2
\leq C_6^* \cdot \tilde{C}_5 \| \tilde{\psi}^n \|_2 \cdot \| \nabla_h \tilde{c}^{l,n+1} \|_2 \leq \frac{1}{4} B_0 \| \nabla_h \tilde{c}^{l,n+1} \|_2^2 + (C_6^*)^2 \tilde{C}_5^2 B_0^{-1} \| \tilde{\psi}^n \|_2^2, \quad (4.66)$$

and

$$-\left\langle e^{-q^i\psi^n} \nabla_h (\tilde{c}^{l,n+1} (e^{q^i\psi^n} - e^{q^i\psi^n})), \nabla_h \tilde{c}^{l,n+1} \right\rangle
\leq \frac{1}{4} B_0 \| \nabla_h \tilde{c}^{l,n+1} \|_2^2 + 6 \tilde{C}_4^2 (C_6^*)^2 B_0^{-1} \left( (\tilde{C}_6 + \tilde{C}_7)^2 \| \tilde{\psi}^n \|_2^2 + \tilde{C}_7^2 \| \nabla_h \tilde{\psi}^n \|_2^2 \right), \quad (4.67)$$

respectively.
Analogous to (4.55), we arrive at
\[
\frac{1}{\Delta t} \left( \|c_l^{t,n+1}\|^2 - \|c_l^{t,n}\|^2 \right) + \frac{1}{2} B_0 \| \nabla_h c_l^{t,n+1} \|^2 \\
\leq \| \tau_l^{t,n+1} \|^2 + (6 \tilde{C}_4 B_0^{-1} + 1) \|c_l^{t,n+1}\|^2 + \tilde{C}_8 \| \psi^n \|^2 + \tilde{C}_0 \| \nabla_h \psi^n \|^2,
\]
with \( \tilde{C}_8 = (C_0^*)^2 B_0^{-1} \left( 2 \tilde{C}_2^2 + 12 \tilde{C}_2^2 (\tilde{C}_0 + \tilde{C}_7)^2 \right), \tilde{C}_0 = 12 (C_0^*)^2 \tilde{C}_2^2 \tilde{C}_4^2 B_0^{-1}. \) With similar arguments, we are able to establish the convergence estimate (4.59). The technical details are left to interested readers.

### 4.5. Convergence estimate on fluxes.

It is of practical significance to accurately approximate the ionic fluxes in many applications. For instance, the accuracy of ionic fluxes through a transmembrane channel is extremely important to the calculation of the current-voltage characteristic curves. We here consider the convergence estimate of the flux vector, defined as \( J_l := \nabla c^l + q^l c^l \nabla \psi, \) \( 1 \leq l \leq M. \) In more detail, we denote the following profiles:
\[
J_l^I = \nabla c^l_e + q^l c^l_e \nabla \psi_e, \quad \text{(the exact profile)}, \\
J_N^I = \nabla h c^l_N + q^l c^l_N \nabla h \psi_N, \quad \text{(the approximate profile)}, \\
J_l^I = \nabla h c^l + q^l c^l \nabla h \psi, \quad \text{(the numerical profile)}.
\]

By the projection estimate (4.1), combined with the standard truncation error estimate for the finite-difference spatial discretization, we get
\[
\| J_e^I - J_N^I \|_2 \leq C h^2.
\]

In turn, the error grid function for the flux vector is defined as
\[
e_n^L := J_N^I - J^I, \quad l = 1, \ldots, M, \ n \in \mathbb{N}^+.
\]

An \( \ell^2(0,T;\ell^2) \) error estimate can be established for the flux vector.

**Corollary 4.1.** Let \( e_n^L \) be the error grid functions defined in (4.71). Then, under the linear refinement requirement \( C_1 h \leq \Delta t \leq C_2 h, \) the following convergence result is available as \( \Delta t, h \to 0: \)
\[
\left( \Delta t \sum_{l=1}^{M} \sum_{k=1}^{n} \| e_{j_l}^k \|_2^2 \right)^{1/2} \leq C (\Delta t + h^2),
\]
where the constant \( C > 0 \) is independent of \( \Delta t \) and \( h. \)

**Proof.** A detailed expansion implies that
\[
e_{j_l}^n = \nabla h e_{j_l}^{l,n} + q^l (e_{j_l}^{l,n} \nabla h \psi_e + e_{j_l}^{l,n} \nabla h \psi_N), \quad l = 1, \ldots, M.
\]

Then
\[
\| e_{j_l}^n \|_2 \leq \| \nabla h e_{j_l}^{l,n} \|_2 + |q^l| (\| e_{j_l}^{l,n} \|_\infty \cdot \| \nabla h \psi_e \|_2 + \| e_{j_l}^{l,n} \|_2 \cdot \| \nabla h \psi_N \|_\infty) \\
\leq \| \nabla h e_{j_l}^{l,n} \|_2 + \tilde{C}_3 |q^l| (\| \nabla h \psi_e \|_2 + \| e_{j_l}^{l,n} \|_2),
\]
(4.73)
in which the regularity Assumption (4.9), the a-priori \( \| \cdot \|_{W^\infty} \) estimate (4.16), and an estimate on \( e^{l,n} \) that is derived analogously to (4.62) have been applied. This in turn leads to

\[
\left( \Delta t \sum_{l=1}^{M} \sum_{k=1}^{n} \| e^{l,k}_j \|_2^2 \right)^{\frac{1}{2}} \leq \left( \Delta t \sum_{l=1}^{M} \sum_{k=1}^{n} \| \nabla_h e^{l,k}_j \|_2^2 \right)^{\frac{1}{2}} + C|q_j^i| \left( \Delta t \sum_{l=1}^{M} \sum_{k=1}^{n} (\| \nabla_h e^{l,k}_j \|_2^2 + \| e^{l,k}_j \|_2^2) \right)^{\frac{1}{2}}. \tag{4.74}
\]

Moreover, with an application of the discrete Sobolev inequality (2.2) (in Lemma 2.1) and (4.3) (in Theorem 4.1), we see that

\[
\left( \Delta t \sum_{l=1}^{M} \sum_{k=1}^{n} \| \nabla_h e^{l,k}_j \|_2^2 \right)^{\frac{1}{2}} \leq C(\Delta t + h^2), \tag{4.75}
\]

\[
\| \nabla_h e^{l,k}_j \|_2 \leq C \| \Delta_h e^{l,k}_j \|_2 \leq C \| e^{l,k}_j \|_{H^2} \leq C(\Delta t + h^2), \quad \text{(by (4.2))},
\]

so that

\[
\left( \Delta t \sum_{l=1}^{M} \sum_{k=1}^{n} \| \nabla_h e^{l,k}_j \|_2^2 \right)^{\frac{1}{2}} \leq C(\Delta t + h^2), \tag{4.76}
\]

\[
\| e^{l,k}_j \|_2 \leq C(\Delta t + h^2), \quad \text{(by (4.3))}, \quad \text{so that} \quad \left( \Delta t \sum_{l=1}^{M} \sum_{k=1}^{n} \| e^{l,k}_j \|_2^2 \right)^{\frac{1}{2}} \leq C(\Delta t + h^2). \tag{4.77}
\]

Finally, a substitution of (4.75)-(4.77) into (4.74) yields the desired error estimate (4.72) for the flux vector. This finishes the proof of Corollary 4.1.

**Remark 4.2.** Since the gradient operator is involved in the flux vector, an \( \ell^\infty(0,T;\ell^2) \) error estimate for \( e^{l,n} \) is not directly available. On the other hand, such an optimal rate error estimate in the \( \ell^\infty(0,T;\ell^2) \) norm can be established for the flux vector, if an even higher order consistency analysis is performed. The details are left to interested readers.

5. Numerical results

Numerical simulations are conducted to demonstrate numerical accuracy of the developed numerical method and its effectiveness in preserving mass conservation, positivity, and free-energy dissipation. Unless stated otherwise, we take the characteristic concentration \( c_0 = 1M \) and characteristic length \( L = 1nm \).

5.1. Accuracy test. Consider an electrolyte solution with binary symmetric monovalent ions. Let \( \kappa = 1 \). To test the accuracy of the numerical method, we consider the following problem in 2D:

\[
\begin{aligned}
\partial_t c^1 &= \nabla \cdot (\nabla c^1 + c^1 \nabla \psi) + f_1, \\
\partial_t c^2 &= \nabla \cdot (\nabla c^2 - c^2 \nabla \psi) + f_2, \\
-\kappa \Delta \psi &= c^1 - c^2 + \rho^f,
\end{aligned}
\]

where the source terms \( f_1, f_2, \) and \( \rho^f \), as well as the initial and boundary conditions, are determined by the following exact periodic solution

\[
\begin{aligned}
c^1(x,y,t) &= e^{-t} \cos(2\pi x) \sin(2\pi y) + 2, \\
c^2(x,y,t) &= e^{-t} \cos(2\pi x) \sin(2\pi y) + 2, \\
\psi(x,y,t) &= e^{-t} \cos(2\pi x) \sin(2\pi y).
\end{aligned}
\]

\[
\begin{aligned}
\nabla \cdot (\nabla c^1 + c^1 \nabla \psi) + f_1, \\
\nabla \cdot (\nabla c^2 - c^2 \nabla \psi) + f_2, \\
-\kappa \Delta \psi &= c^1 - c^2 + \rho^f,
\end{aligned}
\]

\[
\begin{aligned}
\nabla \cdot (\nabla c^1 + c^1 \nabla \psi) + f_1, \\
\nabla \cdot (\nabla c^2 - c^2 \nabla \psi) + f_2, \\
-\kappa \Delta \psi &= c^1 - c^2 + \rho^f,
\end{aligned}
\]
Table 5.1. Numerical error and convergence order of numerical solutions at time $T = 0.1$ with a mesh ratio $\Delta t = h^2$.

| $h$   | $\ell^\infty$ error in $c^1$ | Order | $\ell^\infty$ error in $c^2$ | Order | $\ell^\infty$ error in $\psi$ | Order |
|-------|-------------------------------|-------|-------------------------------|-------|-------------------------------|-------|
| Harmonic mean |
| $\frac{1}{50}$ | 2.00e-03 | - | 1.80e-03 | - | 1.20e-03 | - |
| $\frac{1}{60}$ | 1.40e-03 | 2.01 | 1.20e-03 | 2.01 | 8.37e-04 | 2.01 |
| $\frac{1}{70}$ | 1.00e-03 | 1.99 | 9.19e-04 | 1.98 | 6.16e-04 | 1.99 |
| $\frac{1}{80}$ | 7.65e-04 | 2.01 | 7.03e-04 | 2.01 | 4.71e-04 | 2.00 |
| $\frac{1}{90}$ | 6.05e-04 | 2.00 | 5.56e-04 | 1.99 | 3.73e-04 | 1.99 |
| Geometric mean |
| $\frac{1}{50}$ | 2.00e-03 | - | 1.80e-03 | - | 1.20e-03 | - |
| $\frac{1}{60}$ | 1.40e-03 | 2.01 | 1.20e-03 | 2.01 | 8.37e-04 | 2.01 |
| $\frac{1}{70}$ | 1.00e-03 | 1.99 | 9.19e-04 | 1.98 | 6.16e-04 | 1.99 |
| $\frac{1}{80}$ | 7.65e-04 | 2.01 | 7.03e-04 | 2.01 | 4.71e-04 | 2.00 |
| $\frac{1}{90}$ | 6.05e-04 | 2.00 | 5.56e-04 | 1.99 | 3.73e-04 | 1.99 |
| Arithmetic mean |
| $\frac{1}{50}$ | 4.90e-03 | - | 2.40e-03 | - | 1.10e-03 | - |
| $\frac{1}{60}$ | 3.40e-03 | 2.01 | 1.60e-03 | 2.01 | 7.84e-04 | 2.01 |
| $\frac{1}{70}$ | 2.50e-03 | 1.99 | 1.20e-03 | 1.99 | 5.77e-04 | 1.99 |
| $\frac{1}{80}$ | 1.90e-03 | 2.01 | 9.24e-04 | 2.01 | 4.41e-04 | 2.00 |
| $\frac{1}{90}$ | 1.50e-03 | 1.99 | 7.30e-04 | 1.99 | 3.49e-04 | 1.99 |
| Entropic mean |
| $\frac{1}{50}$ | 8.04e-04 | 2.02 | 1.40e-03 | 2.01 | 8.37e-04 | 2.01 |
| $\frac{1}{60}$ | 5.93e-04 | 1.98 | 1.00e-04 | 1.99 | 6.03e-04 | 1.99 |
| $\frac{1}{70}$ | 4.53e-04 | 2.01 | 7.77e-04 | 2.00 | 4.61e-04 | 2.00 |
| $\frac{1}{80}$ | 3.59e-04 | 1.99 | 6.15e-04 | 1.99 | 3.65e-04 | 1.99 |

To probe the discretization error, we apply the proposed numerical method to solve the problem using various spatial step sizes $h$ with a fixed mesh ratio $\Delta t = h^2$. Table 5.1 lists the $\ell^\infty$ errors and convergence orders for ionic concentration and electrostatic potential at time $T = 0.1$. Obviously, we can observe that the error decreases as the mesh refines, and the convergence orders for ion concentrations and the electric potential are both perfectly about 2. This indicates that the semi-implicit scheme (2.10) has expected convergence rate, i.e., first-order and second-order accurate in time and spatial discretization, respectively. Notice that the mesh ratio, $\Delta t = h^2$, adopted here is for the purpose of numerical accuracy test, not for the enforcement of the numerical stability or positivity.

5.2. Properties test. Consider a closed, neutral system that consists of symmetric monovalent ions with $\kappa = 1e-3$. The fixed charge density

$$
\rho^f(x,y) = -e^{-100[(x-\frac{1}{4})^2+(y-\frac{1}{4})^2]} + e^{-100[(x-\frac{3}{4})^2+(y-\frac{1}{4})^2]}
$$

$$
+ e^{-100[(x-\frac{1}{4})^2+(y-\frac{3}{4})^2]} - e^{-100[(x-\frac{3}{4})^2+(y-\frac{3}{4})^2]}
$$

is prescribed to approximate two positive and two negative point charges located in four quadrants, using Gaussian functions with small local supports. The initial distributions are given by

$$
c^1(x,y,0) = 0.1 \quad \text{and} \quad c^2(x,y,0) = 0.1. \quad (5.3)
$$

In this test, we assess the performance of the Slotboom scheme in preserving physical properties with four different means: the harmonic mean, geometric mean, arithmetic mean, and entropic mean. As displayed in Figure 5.1, the Slotboom schemes with four different means perfectly conserve the total ion concentration. The profiles of discrete
free energy (3.2) are shown to decay monotonically and robustly, and numerical solutions of concentrations remain positive all the time. Such results are consistent with the theoretical analysis.

6. Conclusions

Structure-preserving numerical methods for the Poisson–Nernst–Planck (PNP) equations have attracted lots of attention recently. Based on the Slotboom transformation, a class of numerical methods that can be proved to preserve mass conservation, ionic concentration positivity, and free-energy dissipation at discrete level have been derived in literature. However, rigorous convergence analysis for such structure-preserving schemes has been still open. This work has provided optimal rate convergence analysis for such structure-preserving schemes based on the Slotboom reformulation. Different options of mobility average at the staggered mesh points have been considered for spatial finite-difference discretization, such as the harmonic mean, geometric mean, arithmetic mean, and entropic mean. A semi-implicit temporal discretization has been employed, therefore only a non-constant coefficient, positive-definite linear system has to be solved at each time step. A higher order asymptotic expansion has been used in the consistency analysis, so that the discrete maximum norm of the concentration variables can be controlled. The harmonic mean for the mobility average has been taken in the convergence estimate for simplicity, while the desired error estimate for other options of mobility average has been elaborated as well with more technical details. An optimal rate convergence analysis for the ionic concentrations, electric potential, and fluxes has been established, which is the first such result for the structure-preserving numerical schemes based on the Slotboom reformulation. With such convergence analysis, the conditional energy dissipation analysis that relies on the maximum norm bounds of the concentration and the gradient of the electric potential has been further validated. Numerical results have also been presented to demonstrate the accuracy and structure-preserving performance of the numerical schemes.

We now discuss several possible further refinements of our work. The current convergence analysis could be extended to consider the fully implicit schemes that can unconditionally preserve energy dissipation. The unconditional energy dissipation would
help establish upper bounds that are useful in the error estimate. In addition, it is of practical interest to consider convergence analysis of structure-preserving schemes for modified PNP equations based on the Slotboom reformulation. For modified PNP equations, the corresponding structure-preserving numerical methods can be analogously proposed based on (1.4) with

\[ S^l = q^l \psi + \mu^l_{\text{excess}}, \]

where the excess chemical potential \( \mu^l_{\text{excess}} \) can be introduced to consider various effects that are neglected by the classical PNP models. For instance, the excess chemical potential can describe ionic steric effects either by hard-sphere repulsion described by the fundamental measure theory [37,49] or by the incorporation of the entropy of solvent molecules [20,54].

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Appendix. Proof of Theorem 3.3. For completeness, we present the following proof which is based on the proof of Theorem 3.4 in the work [24], with modifications due to the entropic mean under consideration.

Proof. Let \( \rho = \sum_{l=1}^{M} q^l c^l + \rho^I \). By (3.2), we have

\[ F_{h}^{n+1} - F_{h}^{n} = \sum_{l=1}^{M} \left( c^{l,n+1} \log c^{l,n+1} - c^{l,n} \log c^{l,n} \right) + \frac{1}{2} \left( \rho^{n+1} \psi^{n+1} - \rho^n \psi^n \right) - \frac{1}{2} \left( \rho^{n+1} - \rho^n \right) \psi^n - \mu^l_{\text{excess}} \]

\[ := - \Delta t I_1 + ( \Delta t )^2 I_2, \tag{A.1} \]

where

\[ I_1 = - \frac{1}{\Delta t} \sum_{l=1}^{M} \left[ \left( c^{l,n+1} \log c^{l,n+1} - c^{l,n} \log c^{l,n} \right) + \left( c^{l,n+1} - c^{l,n} \right) q^l \psi^n \right] \]

\[ I_2 = \frac{1}{2(\Delta t)^2} \left[ \left( \rho^{n+1} \psi^{n+1} - \rho^n \psi^n \right) - 2 \left( \rho^{n+1} - \rho^n \right) \psi^n \right]. \tag{A.2} \]

Thus, the energy dissipation inequality is satisfied if

\[ \Delta t \leq \tau^* \leq \frac{I_1}{2I_2}. \]

By the discretization scheme (2.10) and periodic boundary conditions, we have

\[ I_1 \geq - \sum_{l=1}^{M} \left( c^{l,n+1} - c^{l,n} \right) \frac{\log g^{l,n+1}}{\Delta t} \geq \sum_{l=1}^{M} e^{-q^l \psi^n} \nabla_h g^{l,n+1} \nabla_h \log g^{l,n+1} \geq 0, \]

where \( g^{l,n+1} = c^{l,n+1} e^{q^l \psi^n} \), the summation by parts, and \((\log X - \log Y)(X - Y) > 0\) for \(X,Y > 0\) have been used. In addition, one can easily verify that

\[ \left( \rho^{n+1} \psi^{n+1} \right) = \left( \rho^n \psi^n \right), \]
which further implies that
\[ I_2 = \frac{1}{2(\Delta t)^2} \langle \rho^{n+1} - \rho^n, \psi^{n+1} - \psi^n \rangle. \]

By summation by parts, one can show by the Cauchy inequality that
\[
I_2 = -\sum_{l=1}^M \frac{q^l}{2\Delta t} \left\langle e^{-q^l \psi^n} \nabla_h g^{l,n+1}, \nabla_h (\psi^{n+1} - \psi^n) \right\rangle \\
\leq \sum_{l=1}^M \frac{|q^l|}{2\Delta t} \left\| e^{-q^l \psi^n} \nabla_h g^{l,n+1} \right\|_2 \left\| \nabla_h (\psi^{n+1} - \psi^n) \right\|_2. \tag{A.3}
\]

On the other hand, it follows from the discrete Poisson’s equation (2.8) that
\[
I_2 = \frac{\kappa}{2(\Delta t)^2} \left\langle \Delta_h \psi^n - \Delta_h \psi^{n+1}, \psi^{n+1} - \psi^n \right\rangle = \frac{\kappa}{2(\Delta t)^2} \left\| \nabla_h (\psi^{n+1} - \psi^n) \right\|_2^2. \tag{A.4}
\]

Combination of (A.3) and (A.4) yields
\[
\left\| \nabla_h (\psi^{n+1} - \psi^n) \right\|_2^2 \leq \frac{\Delta t^2}{\kappa^2} \left( \sum_{l=1}^M |q^l| \left\| e^{-q^l \psi^n} \nabla_h g^{l,n+1} \right\|_2 \right)^2 \\
\leq \frac{\Delta t^2}{\kappa^2} \sum_{l=1}^M |q^l|^2 \left\| e^{-q^l \psi^n} \nabla_h g^{l,n+1} \right\|_2^2.
\]

Thus, we have
\[
I_2 \leq C_0 \sum_{l=1}^M \left\| e^{-q^l \psi^n} \nabla_h g^{l,n+1} \right\|_2^2,
\]
where \( C_0 = \frac{\sum_{l=1}^M (q^l)^2}{2\kappa}. \) Therefore,
\[
\frac{I_1}{2I_2} \geq \frac{1}{2C_0} \sum_{l,i,j,k} \left\langle e^{-q^l \psi^n} \nabla_h g^{l,n+1}, \nabla_h \log g^{l,n+1} \right\rangle \\
\geq \frac{1}{2C_0} \min_{l,i,j,k} \left\{ \frac{\log g^{l,n+1}_{i+1,j,k} - \log g^{l,n+1}_{i,j,k}}{e^{-q^l \psi^n_{i+1,j,k}} \left( g^{l,n+1}_{i+1,j,k} - g^{l,n+1}_{i,j,k} \right)}, \frac{\log g^{l,n+1}_{i,j,k} - \log g^{l,n+1}_{i,j,k+1}}{e^{-q^l \psi^n_{i,j,k+1}} \left( g^{l,n+1}_{i,j,k+1} - g^{l,n+1}_{i,j,k} \right)}, \frac{1}{\left( g^{l,n+1}_{i,j,k+1} \right)^\theta \left( g^{l,n+1}_{i,j,k} \right)^{(1-\theta)} e^{-q^l \psi^n_{i,j,k+1} + \frac{1}{2} k}}, \frac{1}{\left( g^{l,n+1}_{i,j,k} \right)^\theta \left( g^{l,n+1}_{i,j,k+1} \right)^{(1-\theta)} e^{-q^l \psi^n_{i,j,k} + \frac{1}{2} k}} \right\}.
\]
where
\[
\frac{X - Y}{e^X - e^Y} = \frac{1}{e^{\theta X + (1-\theta)Y}} \quad \text{for} \quad \theta \in (0, 1)
\]
has been used in the second inequality. Using the entropic mean in the x direction
\[
e^{-q^l \psi^n_{i+\frac{1}{2},j,k}} = \frac{q^l (\psi^n_{i+1,j,k} - \psi^n_{i,j,k})}{q^l (\psi^n_{i+1,j,k} - \psi^n_{i,j,k})},
\]
we obtain
\[
1 \geq \frac{e^{q^l \psi^n_{i+\frac{1}{2},j,k}}}{\left( g_{i+1,j,k}^{l,n+1} \right)^{1-\theta} \left( c_{i+1,j,k}^{l,n+1} \right)^{\theta}} \frac{e^{q^l (1-\theta)\psi^n_{i+1,j,k} \psi^n_{i,j,k}}}{e^{q^l (1-\theta)\psi^n_{i+1,j,k} \psi^n_{i,j,k}}}
\]
\[
\geq \frac{e^{-|q^l| \% \h \% \n \% \psi^n}}{M_1},
\]
where \( M_1 = \max_{1 \leq l \leq M} \% c^{l,n+1} \% \). Similarly, we have
\[
1 \geq \frac{e^{-|q^l| \% \h \% \n \% \psi^n}}{M_1},
\]
\[
(A.5)
\]
Therefore, we obtain
\[
\frac{I_1}{2I_2} \geq \frac{e^{-|q^l| \% \h \% \n \% \psi^n}}{2C_0M_1}.
\]
This completes the proof.

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