TIME SCALE SEPARATION AND DYNAMIC HETEROGENEITY IN THE LOW TEMPERATURE EAST MODEL

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ABSTRACT. We consider the non-equilibrium dynamics of the East model, a linear chain of 0-1 spins evolving under a simple Glauber dynamics in the presence of a kinetic constraint which forbids flips of those spins whose left neighbor is 1. We focus on the glassy effects caused by the kinetic constraint as $q \downarrow 0$, where $q$ is the equilibrium density of the 0’s. In the physical literature this limit is equivalent to the zero temperature limit. We first prove that, for any given $L = O(1/q)$, the divergence as $q \downarrow 0$ of three basic characteristic time scales of the East process of length $L$ is the same. Then we examine the problem of dynamic heterogeneity, i.e. non-trivial spatio-temporal fluctuations of the local relaxation to equilibrium, one of the central aspects of glassy dynamics. For any mesoscopic length scale $L = O(q^{-\gamma})$, $\gamma < 1$, we show that the characteristic time scale of two East processes of length $L$ and $\lambda L$ respectively are indeed separated by a factor $q^{-\alpha}$, $\alpha = \alpha(\gamma) > 0$, provided that $\lambda \geq 2$ is large enough (independent of $q$, $\lambda = 2$ for $\gamma < 1/2$). In particular, the evolution of mesoscopic domains, i.e. maximal blocks of the form $111...10$, occurs on a time scale which depends sharply on the size of the domain, a clear signature of dynamic heterogeneity. A key result for this part is a very precise computation of the relaxation time of the chain as a function of $(q, L)$, well beyond the current knowledge, which uses induction on length scales on one hand and a novel algorithmic lower bound on the other. Finally we show that no form of time scale separation occurs for $\gamma = 1$, i.e. at the equilibrium scale $L = 1/q$, contrary to what was assumed in the physical literature based on numerical simulations.

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1. Introduction

Kinetically constrained spin models (KCMs) are interacting 0-1 particle systems on general graphs evolving with a simple Glauber dynamics which can be described as follows. At every vertex $x$ the system tries to update the occupancy variable (or spin) at $x$ to the value 1 or 0 with probability $1-q$ and $q$ respectively. However the update at $x$ is accepted only if a certain local constraint is verified by the current spin configuration. That explains the wording “kinetically constrained”. The constraint at site $x$ is always assumed not to depend on the spin at $x$ and therefore the product Bernoulli($1-q$) measure $\pi$ is the reversible measure. Typical constraints require, for example, that a certain number of the neighboring spins are in state 0, or more restrictive, that certain preassigned neighboring spins are in state 0 (e.g. the children of $x$ when the underlying graph is a rooted tree).

The main interest in the physical literature for KCMs (see e.g. [4, 8, 18, 29, 31, 32]) stems from the fact that they display many key dynamical features of real glassy materials: ergodicity breaking transition at some critical value $q_c$, huge relaxation time for $q$ close to $q_c$, dynamic heterogeneity (non-trivial spatio-temporal fluctuations of the local relaxation to equilibrium) and aging just to mention a few. Mathematically, despite of their simple definition, KCMs pose very challenging and interesting problems because of the hardness of the constraint, with ramifications towards bootstrap percolation problems [33], combinatorics [12, 34], coalescence processes [15, 17] and random walks on triangular matrices [27]. Some of the mathematical tools developed for the analysis of the relaxation process of KCMs proved to be quite powerful also in other contexts such as card shuffling problems [5] and random evolution of surfaces [11].

In this paper we analyze one of the most popular KCMs namely, the East model (see e.g. [20, 31, 32] and [2, 9, 16]), which consists of a linear chain (finite or infinite) of 0-1 spins evolving under a simple Glauber dynamics in the presence of the kinetic constraint which forbids flips of those spins whose left neighbor is in state 1. To avoid trivial irreducibility issues when the chain is either finite or semi-infinite, one always assumes that the leftmost spin is unconstrained.

It is known that the relaxation time (cf. (2.2)) of the East model is uniformly bounded in the length $L$ of the chain [2, 9] and that, because of the constraints, it diverges very rapidly as $q \downarrow 0$ (cf. Prop. 1.4 below). The mixing time (cf. (2.3)) instead diverges linearly in $L$. It is also known [10] that, starting from a large class of initial laws (e.g. a non-trivial Bernoulli($1-q'$) product measure, $q' \neq q$), the expected value at time $t$ of a local function $f$ converges exponentially fast to $\pi(f)$, the mean of $f$ w.r.t. the reversible measure $\pi$. These results prove, in a broad sense, exponential relaxation to equilibrium for time scales larger than the relaxation time for the infinite chain.

However the most interesting and challenging dynamical behavior, featuring aging and dynamic heterogeneity, occurs for $q \ll 1$ on time scales shorter than the relaxation time. Building upon the non-rigorous picture in the physics literature [32] but going well beyond it, it was proved in [15] that, for all $N$ independent of $q$, the dynamics of the infinite East chain in a space window $[1, 2^N]$ and up to time scales $O(1/q^N)$ is well approximated, as $q \downarrow 0$, by a certain hierarchical coalescence process (HCP) [17]. In this HCP vacancies are isolated and domains (maximal blocks of the form 111..10) with cardinality between $2^{n-1}$ and $2^n$, $n \leq N$, coalesce with the domain at their right only at
time scale $\sim (1/q)^n$. As a result, aging and dynamic heterogeneity in the above regime emerge in a natural way, with a scaling limit for the relevant quantities in the same universality class as several other mean field coalescence models of statistical physics [13].

However the above result says nothing about the dynamics and its characteristic time scales at intermediate (mesoscopic) length scales $L = 1/q^\gamma$, $0 < \gamma < 1$, or at the typical inter-vacancy equilibrium scale $L_c = 1/q$. As clarified later on (cf. Section 2.1.1), at these length scales the low temperature dynamics of the East model is no longer predominantly driven by an effective energy landscape as in [15], but entropic effects become crucial and a subtle entropy/energy competition comes into play. In the physical literature these effects have been neglected and the characteristic time scale $t_n \approx 1/q^n$, appropriate for domains of length $L_n \approx 2^n$, $n = O(1)$, has been extrapolated up to the equilibrium scale $L_c = 2 \log_2(1/q)$ leading for example to the wrong prediction of a relaxation time $\sim (1/q) \log_2(1/q)$ (to be compared with the bounds given in Theorem 2).

In this paper we analyse the low temperature dynamics in the above setting. We first show (cf. Theorem 1) that three natural characteristic time scales of the East model of length $L = O(1/q)$ have a similar scaling as $q \downarrow 0$. This equivalence is important because of various notions of “relaxation time” which appear in the physical literature. Secondly we prove a sharp separation of time scales and dynamic heterogeneity (cf. Theorems 3 and 5) at mesoscopic length scale $L = 1/q^\gamma$, $0 < \gamma < 1$. A key ingredient for the above results is a novel and detailed computation of the relaxation time of finite East chains as $q \downarrow 0$, in which the entropic contributions in the upper and lower bounds are pinned down very precisely (cf. Theorem 2). The upper bound is obtained via a substantial refinement of the inductive technique first introduced in [9]. Instead the lower bound has been inspired by capacity methods and is obtained via a novel construction in the configuration space of a bottleneck. The equilibrium weight of the bottleneck is computed in an algorithmic fashion.

In Theorem 4 we also prove that no time scale separation occurs for $\gamma = 1$, i.e. at the equilibrium scale $L_c = 1/q$. This precludes the time scale separation hypothesis in [31, 32], put forward on the basis of numerical simulations, which was a keystone of the super-domain dynamics formulation. This is an example of a case in which numerical simulations can be misleading because of the extremely long time scales involved, emphasizing the need for rigorous work.

The above results combined with the hierarchical coalescence picture of [15] complete somehow the picture of the non-equilibrium dynamics of the East model up to the equilibrium scale $L_c = 1/q$. The question of a mathematically rigorous description of the stationary dynamics, for which the typical domain has length proportional to $L_c = 1/q$, remains open. In their seminal paper [2] Aldous and Diaconis proposed the following very appealing conjecture. As $q \downarrow 0$ the vacancies of the stationary East process in $[0, +\infty)$, after rescaling space by $q$ and speeding up the process by the relaxation time, converge to a limit point process $X_t$ on $[0, +\infty)$ which can be described as follows:

(i) At fixed time $t$, $X_t$ is a Poisson point process of rate 1.
(ii) For each $\ell > 0$, with a positive rate depending on $\ell$ each particle deletes all particles to its right up to a distance $\ell$ and replaces them by new sample of the Poisson process.
Proving the conjecture is certainly one of the challenging open problems for the model.

1.1. Model and notation. We will consider a reversible interacting particle system on finite intervals \( \Lambda \) of \( \mathbb{N} := \{1, 2, \ldots \} \) of the form \( \Lambda = [a, a + 1, \ldots, a + L - 1] \) (for shortness \( \Lambda = [a, a + L - 1] \) if clear from the context) with Glauber type dynamics on the configuration space \( \Omega_\Lambda := \{0, 1\}^\Lambda \), reversible with respect to the product probability measure \( \pi_\Lambda := \prod_{x \in \Lambda} \pi_x \), where \( \pi_x \) is the Bernoulli \((1 - q)\) measure. Since we are interested in the small \( q \) regime throughout the paper we will assume \( q < \frac{1}{2} \).

Remark 1.1. Sometimes in the physical literature the parameter \( q \) is written as \( q = \frac{e^{-\beta}}{1 + e^{-\beta}} \), \( \beta \) being proportional to the inverse temperature, so that the limit \( q \downarrow 0 \) corresponds to the zero temperature limit.

Elements of \( \Omega_\Lambda \) will usually be denoted by the Greek letters \( \sigma, \eta, \ldots \) and \( \sigma_x \) will denote the occupancy variable at the site \( x \). The configuration after flipping the spin on site \( x \) will be denoted by \( \sigma^x \),

\[
\sigma^x = \begin{cases} 
\sigma_y & \text{if } y \neq x, \\
1 - \sigma_y & \text{if } y = x.
\end{cases}
\] (1.1)

The restriction of a configuration \( \sigma \) to a subset \( V \) of \( \Lambda \) will be denoted by \( \sigma_V \). In the sequel it will be useful to use the convention that \( \sigma_{a-1} \equiv 0 \), i.e. there is a fixed vacancy on the left of the interval.

The East process (a continuous time Markov chain) can be informally described as follows. Each vertex \( x \neq a \) waits an independent mean one exponential time and then, provided that the current configuration \( \sigma \) satisfies the constraint \( \sigma_{x-1} = 0 \), the value of \( \sigma_x \) at \( x \) is refreshed and set equal to 1 with probability \( 1 - q \) and to 0 with probability \( q \). The leftmost vertex \( x = a \) is unconstrained. Two configurations \( \sigma, \sigma' \) are said to be neighbors under the East dynamics if there is a non-zero probability rate \( K(\sigma, \sigma') \) of making a transition directly between them. Therefore two configurations \( \sigma, \sigma' \) are neighbors if they differ only in a single coordinate \( x \) and for this coordinate \( \sigma_{x-1} = \sigma'_{x-1} = 0 \).

Remark 1.2. Sometimes in the literature one refers to the East process as the above process but with the constraint at \( x \) satisfied iff the vertex immediately to right of \( x \) is empty. Of course the two processes are equivalent under the mapping \( x \mapsto -x \). We refer to [16] and [29] for mathematical and physical background.

The associated infinitesimal Markov generator \( \mathcal{L}_\Lambda \) is given by

\[
\mathcal{L}_\Lambda f(\sigma) = \sum_{x \in \Lambda} c^\Lambda_x(\sigma) \left[ \pi_x(f) - f(\sigma) \right]
\] (1.2)

where

\[
c^\Lambda_x(\sigma) := \begin{cases} 
1 - \sigma_{x-1} & \text{if } x \neq a, \\
1 & \text{if } x = a.
\end{cases}
\] (1.3)

encodes the constraint and \( \pi_x(f) \) denotes the conditional mean \( \pi_\Lambda(f \mid \{\sigma_y\}_{y \neq x}) \).
The quadratic form or Dirichlet form associated to \(-\mathcal{L}_\Lambda\) will be denoted by \(\mathcal{D}_\Lambda\) and takes the form
\[
\mathcal{D}_\Lambda(f) = \pi_\Lambda(f(-\mathcal{L}_\Lambda f)) = \sum_{x \in \Lambda} \pi_\Lambda(c_x^\Lambda \text{Var}_x(f)) \tag{1.4}
\]
where \(\text{Var}_x(f)\) denotes the conditional variance \(\pi_x(f^2) - \pi_x(f)^2\) given \(\{\sigma_y\}_{y \neq x}\).

When the initial distribution at time \(t = 0\) is \(\nu\) the law and expectation of the process will be denoted by \(\mathbb{P}_\nu^\Lambda\) and \(\mathbb{E}_\nu^\Lambda\) respectively. If \(\nu = \delta_x\) we write \(\mathbb{P}_x^\Lambda, \mathbb{E}_x^\Lambda\).

In the sequel it will be quite useful to isolate some special configurations in \(\Omega_\Lambda\). We will denote by \(1\Theta\) the configuration with a single vacancy located at the right end of \(\Lambda\) and by \(\mathbb{1}\) the configuration with no vacancies. Also we define \(Z_n(\Lambda) \subset \Omega_\Lambda\) to be the set of configurations in \(\Omega_\Lambda\) with at most \(n\) vacancies.

### 1.2. Graphical construction and basic coupling

Here we recall a standard graphical construction which defines on the same probability space the finite volume East process for all initial conditions. Using a standard percolation argument \([14,23]\) together with the fact that the constraints \(c_x^\Lambda\) are uniformly bounded and of finite range, it is not difficult to see that the graphical construction can be extended without problems also to the infinite volume case.

To each \(x \in \Lambda\) we associate a mean one Poisson process and, independently, a family of independent Bernoulli \((1 - q)\) random variables \(\{s_{x,k} : k \in \mathbb{N}\}\). The occurrences of the Poisson process associated to \(x\) will be denoted by \(\{t_{x,k} : k \in \mathbb{N}\}\). We assume independence as \(x\) varies in \(\Lambda\). Notice that with probability one all the occurrences \(\{t_{x,k}\}_{k \in \mathbb{N}, x \in \Lambda}\) are different. This defines the probability space. The corresponding probability measure will be denoted by \(\mathbb{P}_\Lambda^\Lambda\).

Given \(\eta \in \Omega_\Lambda\) we construct a continuous time Markov chain \(\{\eta(s)\}_{s \geq 0}\) on the above probability space, starting at \(t = 0\) from \(\eta\), according to the following rules. At each time \(t = t_{x,n}\) the site \(x\) queries the state of its own constraint \(c_x^\Lambda\). If and only if the constraint is satisfied then \(t_{x,n}\) is called a legal ring and at time \(t\) the configuration resets its value at site \(x\) to the value of the corresponding Bernoulli variable \(s_{x,n}\). It is easy to check that the above construction actually gives a continuous time Markov chain with generator (1.2). We will refer in the sequel to the above construction as the basic coupling for the process.

**Remark 1.3.** Notice that the rings and coin tosses at \(x\) for \(s \leq t\) have no influence whatsoever on the evolution of the configuration at the site \(x - 1\) which determines the constraint \(c_{x-1}^\Lambda\) and thus they have no influence of whether a ring at \(x\) for \(s > t\) is legal or not.

A first immediate consequence of the construction is the following characterization of the coupling time of the chain. Starting from \(\xi \equiv \mathbb{1}\) define \(\tau(x)\) as the first legal ring in \(x \in \Lambda\). Then elementary induction gives that, for any \(x \in \Lambda\), any \(\eta\) and any \(t \geq \tau(x)\),
\[
\eta_y(t) = \xi_y(t) \quad \forall y \leq x.
\tag{1.5}
\]
In particular
\[
\mathbb{P}_\Lambda^\Lambda\left(\exists \eta, \eta' : \eta(t) \neq \eta'(t)\right) \leq \mathbb{P}_\xi^\Lambda(\tau(L) > t).
\]
The second consequence of the basic coupling is the following property (see [15, Lemma 2.2]). Fix $1 < b < c \leq L$ in $\mathbb{N}$ and let

$$\Lambda = \{1, 2, \ldots, L\}, \quad \Lambda_1 = \{1, 2, \ldots, b\}, \quad \Lambda_2 = \{b + 1, b + 2, \ldots, c\}.$$

For any $\eta \in \Omega_\Lambda$ take two events $A$ and $B$, belonging respectively to the $\sigma$–algebras generated by $\{\eta_x(s)\}_{s \leq t, x \in \Lambda_1}$ and $\{\eta_x(s)\}_{s \leq t, x \in \Lambda_2}$. Then,

$$\mathbb{P}_\eta^\Lambda(A) = \mathbb{P}_{\eta_{\Lambda_1}}^{\Lambda_1}(A) \mathbb{P}_{\eta_{\Lambda_2}}^{\Lambda_2}(B).$$

The last, simple but quite important consequence of the graphical construction is the following one. Assume that the zeros of the starting configuration $\sigma$ are labeled in increasing order as $x_0, x_1, \ldots, x_n$ and define $\tau$ as the first time at which one of the $x_i$’s is killed, i.e. the occupation variable there flips to one. Then, up to time $\tau$ the East dynamics factorizes over the East process in each interval $[x_i, x_{i+1})$.

1.3. Ergodicity and some background. The finite volume East process is trivially exponentially ergodic because the variable $\eta_a$ at the beginning of the interval $\Lambda$ is unconstrained ($c_{\Lambda}^\sigma(\sigma) \equiv 1$). The infinite volume process in $\mathbb{Z}$, which can be constructed by standard methods [22], is also ergodic in the sense that 0 is a simple eigenvalue of the corresponding generator $L$ thought of as a self adjoint operator on $L^2(\Omega, \pi)$ [9]. As far as more quantitative results are concerned we recall the following (see [9] for part (i) and [10] for part (ii)).

**Proposition 1.4.** (i) The generator $L$ has a positive spectral gap $\lambda = \lambda(q)$. Moreover

$$\lim_{q \downarrow 0} \log(\lambda^{-1}) / (\log(1/q))^2 = (2 \log 2)^{-1}.$$  

and for any interval $\Lambda$ the spectral gap of the finite volume generator (1.2) is not smaller than $\lambda$.

(ii) Assume that the initial distribution $\nu$ is a product Bernoulli($\alpha$) measure, $\alpha \in (0, 1)$. Then there exists $m \in (0, \lambda]$ and for any function $f$ depending on finitely many variables there exists a constant $C_f$ such that

$$|E_\nu[f(\sigma(t))] - \pi(f)| \leq C_f e^{-mt}.$$

The above results show that relaxation to equilibrium is indeed taking place at an exponential rate on a time scale $T_{rel} = \lambda^{-1}$ which is very large and of the order of $e^{c \log(1/q)^2}$, $c = (2 \log 2)^{-1}$, for small values of $q$.

2. Main results

In order to state our main findings we first need to define some appropriate characteristic time scales associated to the East process on the interval $\Lambda = [a, a + L - 1]$. Without loss of generality we take $a = 1$. As is apparent from their definition, they are all non-decreasing in $L$ (see Lemma 3.1).

The first one will be the relaxation time.
Definition 2.1 (Relaxation time). The spectral gap, \( \text{gap}(\mathcal{L}_\Lambda) \), of the infinitesimal generator is the smallest positive eigenvalue of \( -\mathcal{L}_\Lambda \) and it is given by the variational principle

\[
\text{gap}(\mathcal{L}_\Lambda) := \inf_{f \text{ non constant}} \frac{\mathcal{D}_\Lambda(f)}{\text{Var}_\Lambda(f)}.
\]  

(2.1)

The relaxation time \( T_{rel}(\mathcal{L}) \) is defined as the inverse of the spectral gap:

\[
T_{rel}(\mathcal{L}) = \frac{1}{\text{gap}(\mathcal{L}_\Lambda)}.
\]  

(2.2)

Our second time scale is the mixing time of the process in \( \Lambda \).

Definition 2.2 (Mixing time). Writing \( \| \cdot \|_{TV} \) for the total variation distance, the mixing time \( T_{mix}(\mathcal{L}) \) is defined as

\[
T_{mix}(\mathcal{L}) = \inf \left\{ t \geq 0 : \max_{\eta} \| \mathbb{P}^\Lambda_{\eta_t}(\eta_t = \cdot) - \pi_\Lambda(\cdot) \|_{TV} \leq 1/4 \right\}.
\]  

(2.3)

It is well known (see e.g. [30]) that

\[
T_{rel}(\mathcal{L}) \leq T_{mix}(\mathcal{L}) \leq T_{rel}(\mathcal{L}) \left( 1 + \frac{1}{2} \log(\frac{1}{\pi^*}) \right)
\]

where \( \pi^* := \min_\sigma \pi_\Lambda(\sigma) \). The last important characteristic time is an expected hitting time.

Definition 2.3 (Mean hitting time). Let \( \tau_{\eta_L=1} \) be the hitting time of the set \( \{ \eta : \eta_L = 1 \} \). Then

\[
T_{hit}(\mathcal{L}) := \mathbb{E}_{\eta_L=1}^\Lambda [\tau_{\eta_L=1}] .
\]  

(2.4)

To understand the relevance of the last time scale, let us suppose to start the process from a generic configuration \( \eta \) such that, for some \( x < y \in \Lambda \), \( \eta_x = \eta_y = 0 \) while \( \eta_z = 1 \) for all \( z \in (x, y) \). The configuration at \( x + 1 \) is unconstrained until the first time the vacancy at \( x \) disappears. In particular, the vacancy at \( x \) can create waves of vacancies to its right which could remove the vacancy at \( y \). Conditioned on the vacancy at \( x \) surviving, the expected time to remove (or kill) the vacancy at \( y \) is given by \( T_{hit}(\mathcal{L}) \) with \( \ell = y - x \). Thus the time scales \( T_{hit}(\cdot) \) can be used as a first attempt to measure the lifetime of the domains.

Remark 2.4. In the sequel we will be interested in the above time scales as functions of the facilitating density \( q \) as \( q \downarrow 0 \). The dependence on \( q \) will, in general, be twofold: that due to the East dynamics and that due to a (possible) dependence of the length scale \( L \) on \( q \).

2.1. Bounds on the characteristic times. Roughly speaking our first result states that, for \( q \ll 1 \) and for all length scales \( L \leq \text{const} \times 1/q \), the above time scales are all of the same order as a function of \( q \).

Definition 2.5. Given two positive functions \( f, h \) on the interval \((0, 1)\) we will write \( f \asymp h \) if

\[
0 < \liminf_{q \downarrow 0} \frac{f(q)}{h(q)} \leq \limsup_{q \downarrow 0} \frac{f(q)}{h(q)} < +\infty.
\]
If instead there exists a positive constant $\beta$ such that
\[ \liminf_{q \downarrow 0} q^\beta \frac{f(q)}{h(q)} > 0 \]
then we will write $f > h$.

**Remark 2.6.** Notice that the relation $\succ$ requires a rather strong divergence of the ratio $f(q)/h(q)$ as $q \downarrow 0$. Such a choice was motivated by some work on the topics discussed here which appeared in the physical literature (see [31, 32]).

**Theorem 1** (Equivalence of characteristic times up to scale $O(1/q)$). For each $L$

\[ (1 - q)L T_{\text{hit}}(L) \leq T_{\text{rel}}(L) \leq T_{\text{mix}}(L) \leq 4T_{\text{hit}}(L) \tag{2.5} \]

In particular, if $L = O(1/q)$, then $T_{\text{rel}}(L) \asymp T_{\text{mix}}(L) \asymp T_{\text{hit}}(L)$.

**Remark 2.7.** The equivalence between $T_{\text{mix}}(L)$ and $T_{\text{hit}}(L)$ agrees with a recent general result [25, 28] roughly saying that the mixing time of a Markov chain coincides with the mean hitting time of some likely (w.r.t. $\pi_\Lambda$) set. In our case, the likely set is simply the event \{\$\eta_L = 1\$. Further information on $T_{\text{hit}}(L)$ is given in Section 3, where also its equivalence with another hitting time is established.

Having established the above equivalence, the next important question concerns the dependence of the time scales on the length scale $L$. In particular it is of interest to know when $T_{\text{rel}}(L) \succ T_{\text{rel}}(L')$, for $L > L'$ up to the equilibrium scale $1/q$. It turns out that this problem is quite non-trivial because of a rather subtle interplay between the contribution to the relaxation time coming from energy barriers and the contribution due to the entropy (i.e. the number of ways of overcoming the energy barrier).

It is useful to first recall some known previous bounds on $T_{\text{rel}}(L)$. In the sequel, for any $L \geq 1$, we will define $n = n(L) := \lceil \log_2 L \rceil$ where \$x\rceil$ denotes the ceiling of $x$, i.e. the smallest integer number equal to or larger than $x$. In particular $2^{n-1} \leq L \leq 2^n$. If clear from the context the dependence on $L$ of the integer $n$ will be omitted.

Using rather simple energetic considerations together with a key combinatorial result for the East model [12], it holds that, for all small enough $q$,

\[ \frac{c(n)}{q^n} \leq T_{\text{rel}}(L) \leq \frac{c'(n)}{q^n} \tag{2.6} \]

for suitable positive constants $c(n), c'(n)$ depending only on $n$ and satisfying
\[ \lim_{n \to \infty} c(n) = \lim_{n \to \infty} c'(n) = +\infty. \]

The upper bound was proved in [15] while the lower bound follows from Lemma 5.5. The above bounds turn out to be quite precise for $n$ (i.e. $L$) fixed and $q \downarrow 0$. If instead $n = n(q)$ depends on $q$ and it diverges as $q \downarrow 0$, then the above estimates deteriorate quite a bit and a more refined analysis is required.

It was shown in [2] firstly and then in [9] that $\sup_L T_{\text{rel}}(L) < \infty$ for all $q \in (0, 1)$. In particular, in [9, 10] it was proved that, for each $\delta > 0$, there exists a positive constant $C$ such that, for all small enough $q$,

\[ C^{-1} q^{2-q^{-n/2}} \leq T_{\text{rel}}(L) \leq C q^{-n_*/(2-\delta)}, \quad n_* = \log_2(1/q) \tag{2.7} \]

\footnote{We recall that $f = O(g)$ means that there exists a constant $C > 0$ such that $|f| \leq C g$.}
Remark 2.8. Of course the same result does not apply to the mixing time $T_{\text{mix}}(L)$ or to the mean hitting time $T_{\text{hit}}(L)$. Using the fact that the jump rates of the process are uniformly bounded together with , it is quite simple to show that the latter time scales grow at least linearly with $L$ when $L \gg 1/q$. On the other hand, using $\sup_L T_{\text{rel}}(L) < \infty$ one immediately concludes that $\sup_L L^{-1}T_{\text{mix}}(L) < \infty$ and similarly for $T_{\text{hit}}(L)$. That is of course not in contradiction with the equivalence with $T_{\text{rel}}(L)$ for scale $L$ up to equilibrium scale $1/q$.

Unfortunately none of the above estimates is able to settle the question of whether $T_{\text{rel}}(L) \succ T_{\text{rel}}(L')$ or not in a satisfactory way and much more refined bounds are required. Our second result is a step forward in this direction.

Theorem 2 (Bounds on the relaxation time). Given $d > 0$ there exist constants $\alpha, \alpha'$ depending only on $d$ such that, for all $L \in [1, d/q]$,

$$
\frac{n!}{q^{n^2/2}} q^n \leq T_{\text{rel}}(L) \leq \frac{n!}{q^{n^2/2}} q^{-\alpha'}, \quad n = \lceil \log_2 L \rceil.
$$

2.1.1. Some heuristics behind (2.8). Since the equilibrium vacancy density $q$ is very small, most of the non-equilibrium evolution will try to remove the excess of vacancies present in the initial distribution and will thus be dominated by the coalescence of domains (intervals separating two consecutive vacancies). Of course this process must necessarily occur in a kind of cooperative way because, in order to remove a vacancy, other vacancies must be created nearby (to its left). Since the creation of vacancies requires the overcoming of an energy barrier, in a first approximation the non-equilibrium dynamics of the East model for $q \ll 1$ is driven by a non-trivial energy landscape.

In order to better explain the structure of this landscape suppose that we start from the configuration $\mathbb{1}$0 with only a vacancy at the right end of the interval $\Lambda$. In this case a nice combinatorial argument (see [12] and also [31, 32]) shows that, in order to remove the vacancy within time $t$, there must exist $s \leq t$ such that the number of vacancies inside $\Lambda \setminus \{L\}$ at time $s$ is at least $n$. A simple comparison with the stationary East model, using the fact that $\pi(\mathbb{1}) = 1 + o(1)$, shows that at any given time $s$ the probability of observing $n$ vacancies in $\Lambda \setminus \{L\}$ is $O(q^n)$. Therefore, in order to have a non negligible probability of observing the disappearance of the vacancy at $L$, one expects to have to wait an activation time $t_n = O(1/q^n)$. In a more physical language the energy barrier which the system must overcome has height $n$.

The above heuristics in a sense explains the first main contribution $(1/q)^n$ appearing in (2.8). The other main contribution, $n!/2^{n^2/2}$, is much more subtle and more difficult to justify heuristically. It is an entropic term related, in some sense, to the cardinality of the set $V(n)$ of configurations on $\Lambda \setminus \{L\}$ which can be reached from the configuration $\mathbb{1}$ using at most $n$ vacancies in $\Lambda \setminus \{L\}$. Equivalently, $V(n)$ is given by the configurations in $\Lambda \setminus \{L\}$ that can be reached from $\mathbb{1}$ through a path in $Z_n(\Lambda \setminus \{L\})$. The cardinality $|V(n)|$ satisfies the inequalities (see [12])

$$
c_1 n!2^{n^2/2} \leq |V(n)| \leq c_2 n!2^{n^2/2}
$$

where $c_1, c_2$ are positive constants in $(0, 1)$.

A first naive guess would be that the actual relaxation time is the activation time $t_n$ reduced by a factor proportional to $|V(n)|^{-1}$ (see [10] for a rigorous lower bound
on $T_{\text{rel}}(L)$ based on this idea). Notice however that the true reduction factor in (2.8) is much smaller and equal to $2(n^2)/n!$. Thus only a tiny fraction of the configurations reachable with $n$ vacancies actually belong to the energy barrier. Many configurations with $n$ vacancies will return quickly to 10 before removing the vacancy at $L$, and are therefore not typically visited during an excursion which overcomes the energy barrier.

2.2. Time scale separation and dynamic heterogeneity. Theorems 1 and 2 have some interesting consequences on two basic and strongly interlaced questions concerning the non-equilibrium dynamics of the East model at low $q$. The first one is whether the characteristic time scales corresponding to different length scales have the same scaling, as $q \downarrow 0$, or not. As we will see numerical simulations in this case can be quite misleading. The second question is whether and to what extent we should expect dynamic heterogeneity in the model. To simplify the notation we do not write explicitly the integer part when the meaning is clear.

**Theorem 3** (time scale separation up to mesoscopic scales). The following holds:

(i) Given $L'$, $L$ independent of $q$, $T_{\text{rel}}(L') \gg T_{\text{rel}}(L)$ if and only if $\lceil \log_2 L' \rceil > \lceil \log_2 L \rceil$.

(ii) Given $\gamma \in (0,1)$, there exists $\lambda = \lambda(\gamma) > 1$ such that, for all $L = d/q^\gamma$, $d > 0$,

$$T_{\text{rel}}(\lambda L) \gg T_{\text{rel}}(L).$$

Moreover $\lambda = 2$ when $\gamma < 1/2$.

While at finite lengths (i.e. independent of $q$) the question of time scale separation is completely characterized (see (i) above), for mesoscopic lengths of order $O(1/q^\gamma)$, $\gamma \in (0,1)$, our knowledge is less detailed. Although time scale separation occurs between length scales whose ratio is above a certain threshold $\lambda$ (see (ii) above), we would like to know, for example, if it occurs in a “continuous” fashion. By that we mean the following.

**Definition 2.9** (Continuous time scale separation). Given $\gamma \in (0,1]$ we say that continuous time scale separation occurs at length scale $1/q^\gamma$ if $T_{\text{rel}}(d'/q^\gamma) > T_{\text{rel}}(d/q^\gamma)$ whenever $d' > d$.

In [31, 32] a continuous time scale separation was conjectured for $\gamma = 1$, i.e. for length scales of the order of the equilibrium inter-vacancy distance. The following hypothesis was put forward in [31, 32] on the basis of numerical simulations and was the base of the so-called super-domain dynamics proposed by Evans and Sollich to describe the time evolution of the stationary East model.

**Time scaling hypothesis.** Continuous time scale separation occurs at length scale $1/q$. Moreover there exists a strictly increasing positive function $f : (0, +\infty) \mapsto \mathbb{R}$ such that, as $q \downarrow 0$,

$$T_{\text{rel}}(d/q) = (1/q)^{f(d)+o(1)} T_{\text{rel}}(1/q)$$

**Remark 2.10.** Strictly speaking the above hypothesis was formulated with $T_{\text{hit}}(L)$ in place of $T_{\text{rel}}(L)$. However, thanks to Theorem 1, the two formulations are completely equivalent.

The next result shows that the above hypothesis is false.
**Theorem 4** (Absence of time scale separation on scale $1/q$). There is no time scale separation at the equilibrium scale. More precisely

$$T_{rel}(d/q) \asymp T_{rel}(d'/q) \quad \forall d, d' > 0.$$  \hspace{1cm} (2.11)

In particular

$$\lim_{q \downarrow 0} \left( \frac{T_{rel}(d'/q)}{T_{rel}(d/q)} \right)^{\frac{1}{\log(q)}} = 1, \quad \forall d' > d,$$  \hspace{1cm} (2.12)

so $f$ in (2.10) is identically zero.

Our last result concerns dynamic heterogeneity. Roughly speaking it says that the following holds for $\gamma \in [0,1), d > 0$:

- Domains much shorter than $d/q^\gamma$ are very unlikely to be present at time $T_{rel}(d/q^\gamma)$.
- An initial domain larger than $d/q^\gamma$ is likely to still be present at time $T_{rel}(\epsilon d/q^\gamma)$ for some $\epsilon$ small enough.

**Theorem 5.** Let $\Lambda = [1, L]$ and fix $\gamma \in [0, 1), d > 0$.

(i) Assume $L = o(1/q)$. Then, as $q \downarrow 0$ and with $t = T_{rel}(d/q^\gamma)$,

$$\sup_{\eta} \mathbb{P}^\Lambda_\eta \left( \exists z_1 < z_2 : z_2 - z_1 \leq \epsilon d/q^\gamma \text{ and } \eta_{z_1}(t) = \eta_{z_2}(t) = 0 \right) = o(1)$$

for all $\epsilon$ small enough.

(ii) Let $d/q^\gamma \leq L \leq 1/q$. Choose an initial configuration $\eta$ such that $\eta_L = 0$ and $\eta_x = 1$ for all $L - d/q^\gamma \leq x < L$. Then, as $q \downarrow 0$ and with $t = T_{rel}(\epsilon d/q^\gamma)$,

$$\mathbb{P}^\Lambda_\eta \left( \eta_L(t) = 0 \right) = 1 - o(1)$$

for all $\epsilon$ small enough.

3. Preliminary results on hitting times

With $\Lambda = [1, L]$ we prove some preliminary results about the hitting time $\tau_{\eta_L=1}$ under $\mathbb{P}^\Lambda_{\mathbb{I}0}$ as well as the hitting time $\tau_{\eta_L=0}$ under $\mathbb{P}^\Lambda_{\mathbb{I}1}$. The last one was also analyzed in [31, 32] by simulations and assumed to be equivalent to $\tau_{\eta_L=1}$. We also show that all the relevant time scales are non-decreasing as a function of $L$. To simplify notation we write $\tau_L := \tau_{\eta_L=1}$ and $\tilde{\tau}_L := \tau_{\eta_L=0}$.

**Lemma 3.1.** The time scales $T_{rel}(L), T_{mix}(L), T_{hit}(L)$ are non-decreasing in $L$.

**Proof.** Fix an integer $L$ and consider the East model in $\Lambda = [1, L]$. Clearly the restriction of the process to the first $L - 1$ sites coincides with the East model in $[1, L - 1]$. Hence $T_{rel}(L) \geq T_{rel}(L - 1)$ and similarly for $T_{mix}(L)$. As far as the mean hitting time is concerned we just observe that, in order to remove the last vacancy at $L$ starting from $\mathbb{I}0$, we need to wait at least the first time $\tilde{\tau}_{L-1}$ for the process to remove the initial particle at $L - 1$. Thus

$$T_{hit}(L) = \mathbb{E}^\Lambda_{\mathbb{I}0}[\tau_L] \geq \mathbb{E}^\Lambda_{\mathbb{I}1}[\tilde{\tau}_{L-1}].$$

Let $\Lambda' = [1, L - 1]$, then as shown in Proposition 3.2 below $\mathbb{E}^\Lambda_{\mathbb{I}1}[\tilde{\tau}_{L-1}] \geq \mathbb{E}^\Lambda_{\mathbb{I}0}[\tau_{L-1}] = T_{hit}(L - 1)$. \hfill $\square$
Proposition 3.2. The hitting time $\tau_L$ under $\mathbb{P}_{10}^A$ is stochastically dominated by the hitting time $\hat{\tau}_L$ under $\mathbb{P}_1^A$ and stochastically dominates $\hat{\tau}_{L-1}$ under $\mathbb{P}_1^A$. Moreover

$$\mathbb{E}_1^A [\hat{\tau}_{L-1}] \leq \mathbb{E}_{10}^A [\tau_L] \leq 5 \mathbb{E}_1^A [\hat{\tau}_{L-1}],$$

(3.1)

$$\mathbb{P}_{10}^A (\tau_L > t) \leq (1/4)^{t/T(L)},$$

(3.2)

$$\mathbb{P}_{10}^A (\tau_L < t) \leq et/\text{hit}(L),$$

(3.3)

where $T(L)$ is characterized by the identity $P_{10}^A (\tau_L > T(L)) = 1/4$. In addition, $T(L)$ is bounded below by $T_{\text{mix}}(L)$ and satisfies

$$(1/4)T_{\text{hit}}(L) \leq T(L) \leq 4T_{\text{hit}}(L),$$

(3.4)

Remark 3.3. Results similar to (3.2), (3.3) and (3.4) hold for the hitting time $\hat{\tau}_L$ under $\mathbb{P}_1^A$.

Proof. We first prove the stochastic domination. The fact that $\hat{\tau}_{L-1}$ is stochastically dominated by $\tau_L$ is trivial, since in order to create a particle at $L$ starting from $10$, one first has to create a zero at $L - 1$. In particular $\mathbb{E}_1^A [\hat{\tau}_{L-1}] \leq \mathbb{E}_{10}^A [\tau_L]$. We now prove that $\tau_L$ starting from $\xi := 10$ is stochastically dominated by $\hat{\tau}_L$ starting from $\hat{\xi} := 1$. We couple the two evolutions $\xi(t)$ and $\hat{\xi}(t)$, starting from $10$ and $1$ respectively, as follows:

- For all sites $x \in [1, L - 1]$ use the basic coupling described in Section 1.2, so that $\hat{\xi}_x(t) = \xi_x(t)$.

- If at time $t$ there is a legal ring at site $L$ then, setting $p = 1 - q$,

$$\begin{cases} 
\xi_L(t) = 0, & \hat{\xi}_L(t) = 1 \quad \text{with probability } q, \\
\xi_L(t) = 1, & \hat{\xi}_L(t) = 1 \quad \text{with probability } p - q, \\
\xi_L(t) = 1, & \hat{\xi}_L(t) = 0 \quad \text{with probability } q.
\end{cases}$$

We now observe that for both processes the legal rings at site $L$ coincide and both processes restricted to $[1, L - 1]$ are identical. Suppose $t$ is the first time that $\hat{\xi}_L(t) = 0$, i.e. $t = \hat{\tau}_L$. Then the third case in the above list happens, in particular $\xi_L(t) = 1$. This implies that $t \geq \tau_L$. This concludes our proof of the stochastic domination.

We now prove the second upper bound in (3.1). Equivalently, we need to prove that $\mathbb{E}_{10}^A [\tau_L] \leq 5 \mathbb{E}_{10}^A [\hat{\tau}_{L-1}]$, hence we consider the East process on $A$ starting from $10$. Let $\tau$ be the waiting time after $\hat{\tau}_{L-1}$ for the first ring on site $L - 1$ or $L$ (note that this is not necessarily legal if the first ring occurs at $L - 1$), then $\tau \sim \text{Exp}(2)$ and is independent of $\hat{\tau}_{L-1}$. Let $A$ be the event that this ring occurs on site $L$, not $L - 1$, and it updates to a 1, so that $A := \{\eta_L (\hat{\tau}_{L-1} + \tau) = 1\}$. Then $\chi := 1_A \sim \text{Binomial}(p/2)$ and is independent of $\tau$ and $\hat{\tau}_{L-1}$ (see the graphical construction in Section 1.2). If $\chi = 0$ then we couple the process started from $\eta (\hat{\tau}_{L-1} + \tau)$ with that started from $10$ according to the basic coupling. Then by (1.5) the hitting time of $\{\eta : \eta_L = 1\}$ starting from $\eta (\hat{\tau}_{L-1} + \tau)$ is dominated by the hitting time of $\{\eta : \eta_L = 1\}$ started from $10$, call this $\tau'$. Clearly $\tau'$ is independent of $\chi$. It follows that

$$\tau_L \leq \hat{\tau}_{L-1} + \chi \tau + (1 - \chi) \tau'.$$
Taking expectation (where $E^\Lambda$ refers to the basic coupling) we have,
\[
E^\Lambda_{10}[\tau_L] \leq E^\Lambda_{10}[\hat{\tau}_L - 1] + E^\Lambda[\chi \tau] + E^\Lambda((1 - \chi) \tau')
\]
\[
\leq E^\Lambda_{10}[\hat{\tau}_L - 1] + \frac{p}{4} + \left(1 - \frac{p}{2}\right) E^\Lambda_{10}[\tau_L]
\]
so,
\[
E^\Lambda_{10}[\tau_L] \leq \frac{2}{p} E^\Lambda_{10}[\hat{\tau}_L - 1] + \frac{1}{2} \leq \left(\frac{2}{p} + \frac{1}{2}\right) E^\Lambda_{10}[\hat{\tau}_L - 1]
\]
which clearly leads to the second upper bound in (3.1) (recall that $q \leq 1/2$).

In order to prove (3.2) it is enough to show that, given $t, s \geq 0$,
\[
\mathbb{P}^\Lambda_{10}(\tau_L > t + s) \leq \mathbb{P}^\Lambda_{10}(\tau_L > t)\mathbb{P}^\Lambda_{10}(\tau_L > s).
\] (3.5)

Indeed, by the Markov property we can write
\[
\mathbb{P}^\Lambda_{10}(\tau_L > t + s) = E^\Lambda_{10} \left[ \mathbb{1}_{\{\tau_L > t\}} \right] \mathbb{P}_\eta^\Lambda(\tau_L > s)
\]
\[
\leq \mathbb{P}^\Lambda_{10}(\tau_L > t) \sup_{\eta \in \Omega^\Lambda} \mathbb{P}^\Lambda_{\eta}(\tau_L > s).
\]

To conclude we observe that the last supremum is realized by $\eta = 10$, which follows from the basic coupling described in Section 1.2 (cf. (1.5)). Note that by the same arguments (3.5) holds replacing $\mathbb{P}^\Lambda_{10}$ and $\tau_L$ by $\mathbb{P}^\Lambda_t$ and $\hat{\tau}_L$, thus leading to the same result (3.2) for the other hitting time. Therefore, from now on we concentrate only on $\tau_L$ under $\mathbb{P}^\Lambda_{10}$ (the other hitting time can be treated similarly). Integrating (3.2) one gets the left bound in (3.4), while one derives the right bound directly by the definition of $T(L)$. The fact that $T(L) \geq T_{\text{mix}}(L)$ is proved in (4.3). At this point it remains to prove (3.3) which follows from a general fact, Lemma 3.4 below, and (3.5).

**Lemma 3.4.** Let $\tau$ be a positive random variable such that $t \mapsto \mathbb{P}(\tau \geq t)$ is continuous and sub-multiplicative:

\[
\mathbb{P}(\tau > t + s) \leq \mathbb{P}(\tau > t)\mathbb{P}(\tau > s), \quad \forall t, s \geq 0.
\]

Then
\[
\mathbb{P}(\tau < t) \leq e t / E(\tau), \quad \forall t > 0.
\]

**Proof.** Let $t$ be such that $\mathbb{P}(\tau > t) < 1$. The sub-multiplicative property implies that
\[
\mathbb{P}(\tau > s) \leq \mathbb{P}(\tau > t)^{s/t} \leq \mathbb{P}(\tau > t)^{s/1}, \quad \forall s \geq 0.
\]

Integrating over $s$ we get
\[
E(\tau) \leq t \left[ \mathbb{P}(\tau > t) \log \frac{1}{\mathbb{P}(\tau > t)} \right]^{-1}.
\]

In particular $E(\tau) \leq e t_s$ where $t_s$ is such that $\mathbb{P}(\tau \geq t_s) = e^{-1}$. Assume now $t \leq t_s$. Then $\mathbb{P}(\tau \geq t) \geq e^{-1}$ and
\[
\mathbb{P}(\tau \leq t) \leq \log \left(\frac{1}{1 - \mathbb{P}(\tau \leq t)}\right) \leq e \mathbb{P}(\tau \geq t) \log \left(\frac{1}{1 - \mathbb{P}(\tau \leq t)}\right) \leq e t / E(\tau).
\]

Note that in the first inequality we have used that $x \leq \log \frac{1}{1-x}$ for all $x \in (0, 1)$. If instead $t \geq t^*$ then $e t / E(\tau) \geq 1$ and there is nothing to prove. \qed
For system sizes which are much shorter than the equilibrium length scale we observe a loss of memory property, that leads to $\tau_L$ being approximately exponentially distributed, a phenomena which is typically associated with metastable dynamics.

**Lemma 3.5.** If $L = d/q^\gamma$ for some $d > 0$ and $\gamma \in [0, 1)$, then
\[
\lim_{q \searrow 0} \mathbb{P}_{10}^A \left( \frac{\tau_L}{\mathbb{E}_{10}^A[\tau_L]} > t \right) = e^{-t}.
\]  

**Proof.** Let $f(t) := \mathbb{P}_{10}^A (\tau_L/E > t \mid \tau_L/E > s) f(s)$, we show that
\[
|f(t + s) - f(t)f(s)| \leq cq^{1-\gamma},
\]
for some $c > 0$ independent of $q$. The result then follows by standard arguments (for example see [26, Lemma 4.34]). For brevity of notation let $E := \mathbb{E}_{10}^A[\tau_L]$. For any $s, t > 0$ we have
\[
f(t + s) = \mathbb{P}_{10}^A (\tau_L/E > t + s \mid \tau_L/E > s) f(s),
\]
and by the Markov property,
\[
\mathbb{P}_{10}^A (\tau_L/E > t + s \mid \tau_L/E > s) = f(t)\mathbb{P}_{10}^A (\eta(sE) = 10 \mid \tau_L/E > s) + \mathbb{P}_{10}^A (\{\tau_L/E > t + s\} \cap \{\eta(sE) \neq 10\} \mid \tau_L/E > s).
\]
It follows that
\[
|f(t + s) - f(t)f(s)| \leq 2\mathbb{P}_{10}^A (\{\tau_L/E > s\} \cap \{\eta(sE) \neq 10\}) \leq \sum_{x \in A \setminus \{L\}} \mathbb{P}_{10}^A (\eta_x(sE) = 0) \leq dq^{1-\gamma},
\]
where for the last inequality we use that for $t > 0$ and $\eta_x(0) = 1$ we have $\mathbb{P}_{10}^A (\eta_x(t) = 0) \leq q$, which is a simple consequence of the graphical construction (see for example [15, Lemma 4.2]). \[\square\]

4. **Proof of Theorem 1**

The fact that $T_{rel}(L) \asymp T_{mix}(L) \asymp T_{hit}(L)$ for $L = O(1/q)$ follows trivially from (2.5) since $p^{d/q} \sim e^{-d}$ as $q \downarrow 0$. Thus it is enough to prove (2.5).

We begin by recalling a general result about hitting times (see Proposition 21 in [1]).

**Lemma 4.1.** Let $A \subset \Omega_L$ and $\sigma \in \Omega_L$. Let $\tau_A$ denotes the hitting time of the set $A$. Then
\[
\mathbb{P}_\sigma^A (\tau_A > t) \leq \frac{\pi(A)}{\pi(\sigma)} e^{-t \pi(A)/T_{rel}(L)}.
\]  

We can now prove the first bound $(1 - q)^LT_{hit}(L) \leq T_{rel}(L)$. As a special case of Lemma 4.1 we have
\[
\mathbb{P}_{10}^A (\tau_{\eta L} = 1 > t) \leq p^{-(L-1)} e^{-tp/T_{rel}(L)}.
\]
Thus
\[
T_{hit}(L) = \mathbb{E}_{10}^A [\tau_{\eta L} = 1] = \int_0^\infty \mathbb{P}_{10}^A (\tau_{\eta L} = 1 > t) dt \leq (1 - q)^{-(L-1)} \int_0^\infty e^{-t(1-q)/T_{rel}(L)} dt = (1 - q)^{-L} T_{rel}(L).
\]
The second bound $T_{\text{rel}}(L) \leq T_{\text{mix}}(L)$ is a general fact for reversible Markov chains (see e.g. [30]).

To prove the last bound $T_{\text{mix}}(L) \leq 4T_{\text{hit}}(L)$ we use a coupling argument. To this aim recall the basic coupling described in Section 1.2 together with the definition of the “legal times” starting from $1$, $\tau^{(x)}$, $x \in \Lambda$. A standard result (see e.g. [21, Cor. 5.3]) gives

$$\Delta(t) := \max_{\eta} \|\mathbb{P}^{\Lambda}_{\eta}(\eta(t) = \cdot) - \pi(\cdot)\|_{TV} \leq \max_{\sigma,\sigma'} \mathbb{P}^{\Lambda}_{\sigma} \left( \sigma(s) \neq \sigma'(s) \forall s \in [0, t] \right). \quad (4.2)$$

Using (1.5) together with (4.2) we get

$$1/4 = \Delta(T_{\text{mix}}(L)) \leq \mathbb{P}^{\Lambda}_{1}(\tau^{(L)} > T_{\text{mix}}(L)). \quad (4.3)$$

Hence

$$T_{\text{hit}}(L) \geq T_{\text{mix}}(L) \mathbb{P}^{\Lambda}_{1}(\tau_{\eta_L = 1} \geq T_{\text{mix}}(L))$$

$$\geq T_{\text{mix}}(L) \mathbb{P}^{\Lambda}_{1}(\tau^{(L)} > T_{\text{mix}}(L)) \geq \frac{1}{4} T_{\text{mix}}(L).$$

where we used the following elementary observations; the time of the first legal ring at $L$ does not depend on the initial value $\eta_L$ and starting from $10$ the hitting time $\tau_{\eta_L = 1}$ is not smaller than $\tau^{(L)}$.

5. PROOF OF THEOREM 2

5.1. Upper bound on the relaxation time. The proof of the upper bound in (2.8) is based on the iterative procedure developed in [9], although refinements are necessary. We first need the following claim.

Lemma 5.1. Given an integer $r > 2$ let $\{\ell_i\}_{i=1}^r$ be defined by the inductive scheme

$$\begin{cases} 
\ell_1 = 3, \\
\ell_i = 2\ell_{i-1} - \lceil \delta \ell_{i-1} \rceil, & \text{for } 2 \leq i \leq r,
\end{cases} \quad (5.1)$$

with $\delta = 1/r$. Let also $\gamma_i := T_{\text{rel}}(\ell_i)$. Then

$$\gamma_i \leq \frac{2}{1 - \sqrt{\ell_{i-1}}} \gamma_{i-1}, \quad 2 \leq i \leq r, \quad (5.2)$$

where $\epsilon_i = (1 - q)^{[\delta \ell_i]}$.

Proof. Let $i \geq 2$. Since $\ell_2 = 5 > \ell_1$ one can easily prove by induction that $\ell_i > \ell_{i-1}$ as follows:

$$\ell_i - \ell_{i-1} \geq \ell_{i-1} - (\delta \ell_{i-1} + 1) = \ell_{i-1}(1 - \delta) - 1 > \ell_1(1 - 1/3) - 1 > 0.$$ 

Let $\Lambda^{(i)} = [1, \ell_i]$. Each interval $\Lambda^{(i)}$ can be divided into two overlapping intervals of size $\ell_{i-1}$;

$$\Lambda_1 = [1, \ell_{i-1}], \quad \Lambda_2 = [\ell_i - \ell_{i-1} + 1, \ell_i]. \quad (5.3)$$

The overlap $\Delta = \Lambda_1 \cap \Lambda_2$ then contains $N_i = [\delta \ell_{i-1}] \geq \ell_{i-1}/r$ sites. Furthermore $\Lambda^{(i)}$ can be divided into two disjoint intervals $\Lambda_1$ and $\Lambda_2 := \Lambda_2 \setminus \Delta$. Since the cardinalities of $\Lambda_1$ and $\Lambda_2$ are both $\ell_{i-1}$, we have

$$T_{\text{rel}}(\Lambda_1) = T_{\text{rel}}(\Lambda_2) = \gamma_{i-1}.$$
Apply now the block chain in which $\Lambda_1$ goes to equilibrium with rate one and $\tilde{\Lambda}_2$ does the same if and only if there is a zero in $\Delta \neq \emptyset$. More precisely, the block chain has configuration space $\Omega_{\Lambda(i)}$ and generator

$$L_f = (\pi_{\Lambda_1}(f) - f) + c_{\tilde{\Lambda}_2}(\pi_{\tilde{\Lambda}_2}(f) - f), \quad f : \Omega_{\Lambda(i)} \to \mathbb{R}$$

where the new constraint $c_{\tilde{\Lambda}_2}$ is defined as $c_{\tilde{\Lambda}_2}(\eta) = 1\{\exists x \in \Delta : \eta_x = 0\}$. It is simple to check that the associated Dirichlet form is given by

$$\mathcal{D}(f) = \pi(\text{Var}_{\Lambda_1}(f) + c_{\tilde{\Lambda}_2}\text{Var}_{\tilde{\Lambda}_2}(f)).$$

As proven in [9][p. 480] the block chain has spectral gap $(1 - \sqrt{\epsilon_{i-1}})$ and therefore it satisfies the Poincaré inequality

$$\text{Var}(f) \leq \frac{1}{1 - \sqrt{\epsilon_{i-1}}} \pi\left(\text{Var}_{\Lambda_1}(f) + c_{\tilde{\Lambda}_2}\text{Var}_{\tilde{\Lambda}_2}(f)\right).$$

It was proved in [9, Sect. 4] that (recall (1.3))

$$\pi(c_{\tilde{\Lambda}_2}\text{Var}_{\tilde{\Lambda}_2}(f)) \leq \gamma_{i-1} \sum_{x \in \Lambda_2} \pi(c_x^2\text{Var}_{\Lambda_2}(f)),
\pi(\text{Var}_{\Lambda_1}(f)) \leq \gamma_{i-1} \sum_{x \in \Lambda_1} \pi(c_x^1\text{Var}_{\Lambda_1}(f)).$$

Therefore

$$\text{Var}(f) \leq \frac{\gamma_{i-1}}{1 - \sqrt{\epsilon_{i-1}}} \pi\left(\sum_{x \in \Lambda_1} c_x^1\text{Var}_{\Lambda_1}(f) + \sum_{x \in \Lambda_2} c_x^2\text{Var}_{\tilde{\Lambda}_2}(f)\right)
\leq \frac{2\gamma_{i-1}}{1 - \sqrt{\epsilon_{i-1}}} \mathcal{D}_{\Lambda(i)}(f)$$

where the factor 2 comes from the double counting of the points in $\Delta$. In conclusion

$$\gamma_i \leq \frac{2}{1 - \sqrt{\epsilon_{i-1}}} \gamma_{i-1}.$$

This proves (5.2). \hfill \square

Next we show an important property of the length scales $\{\ell_i\}_{1 \leq i \leq r}$ appearing in Lemma 5.1.

**Lemma 5.2.** For all $i \leq r$ it holds that $2^i(1 - 1/r)^i \leq \ell_i \leq 2^{i+1}$.

**Proof.** The upper bound follows immediately by induction. For the lower bound, it is simple to derive from (5.1) that $\ell_i = 2^i + 1$ if $i \leq k := 1 + \lfloor \log_2(r - 1) \rfloor$. Indeed, let $\tilde{k} = \max\{i : \ell_{i-1} \leq r\}$. Then, $\forall i : 2 \leq i \leq \tilde{k}$ (5.1) becomes $\ell_i = 2\ell_{i-1} - 1$ and the solution of this iterative system is $\ell_i = 2^{i-1} + 1$. In particular, it follows that $\tilde{k} = k$. If $i \geq k$ then $\ell_{i-1}/r \geq 1$, together with (5.1) this implies $\ell_i \geq 2(1 - 1/r)\ell_{i-1}$. The rest of the proof is straightforward. \hfill \square

**Lemma 5.3.** Given $r \geq 1$ such that $2^r \leq d/q$ it holds that $\gamma_r \leq q^{-c(d)} \frac{r^d}{q^{2r}(2^r)}$ for some constant $c(d)$ depending only on $d$. 

Proof. Recall the definition of $\varepsilon_i$ in Lemma 5.1. Using the bounds $(1 - x) \leq e^{-x}$ and $(1 - e^{-x}) \geq e^{-x}x$ for all $x > 0$ we get
\[
\frac{2}{1 - \sqrt{\varepsilon_{i-1}}} = \frac{2}{1 - (1 - q)|\ell_{i-1}/r|/2} \leq \frac{2}{1 - e^{-q|\ell_{i-1}/r|}/2} \leq \frac{4}{q|\ell_{i-1}/r|} e^{q|\ell_{i-1}/r|}/2, \tag{5.4}
\]
for $i \leq r$. Due to Lemma 5.2 we have $\ell_i \leq 2^{i+1}$. Hence, using the monotonicity of $\ell_j$ and that $2^r \leq d/q$, we get $\ell_i \leq 2d/q$. This allows us to conclude that $q|\ell_{i-1}/r| \leq q(\ell_{i-1}/r + 1) \leq 2d/r + q$. This bound together with (5.4) implies that $2\sqrt{\varepsilon_{i-1}} \leq \frac{c(d)r}{q\ell_{i-1}}$. Coming back to (5.2) we conclude that
\[
\gamma_r \leq \gamma_1 \frac{c(d)r^r}{q^r \prod_{i=1}^{r-1} \ell_i}, \tag{5.5}
\]
Due to Lemma 5.2 and since $1 - x \geq e^{-2x}$ for $x$ small, we have
\[
\prod_{i=1}^{r-1} \ell_i \geq 2^{i}(1 - 1/r)^{(i/2)} \geq 2^{i}(1 - 1/r)^{2} \geq 2^{i}e^{-r} \tag{5.6}
\]
for $r$ sufficiently large. Since $e^r = 2^{r \log_2 e} \leq (d/q)^{\log_2 e}$ and since by Stirling’s formula $r! \leq C r! e^r$, combining (5.5) and (5.6) we get the result. \qed

We now have the necessary tools to conclude the proof of the upper bound in Theorem 2. Fix $L \leq d/q$ and set $n = \lceil \log_2 L \rceil$. Let $c_0 := \inf\{(1 - 1/k) : k \geq 1\}$. Note that $c_0 \in (0, 1)$. We now choose $r = r_0 := n + \lceil \log_2 (1/c_0) \rceil$, so that $2^{r_0}c_0 \geq L$. By Lemma 5.2, $\ell_{r_0} \geq L$. Since $2^{r_0} \leq 4d/c_0$, by monotonicity and Lemma 5.3 we conclude
\[
T_{rel}(L) \leq \gamma_{r_0} \leq q^{-c(d/c_0)} \frac{r_0!}{q^{r_0} 2^2(r_0)} \leq q^{-c'(d/c_0)} \frac{n_1!}{q^n 2^2(n_1)}.
\]
5.2. Lower bound on the relaxation time. A general strategy to find a lower bound on the relaxation time is to look for a set $A$ whose boundary $\partial A$ forms a small bottleneck in the state space $\Omega_A$ [21, 30]. One can upper bound the spectral gap (i.e., lower bound the relaxation time) by restricting the variational formula (2.1) to indicator functions of sets in $\Omega_A$. In this way one gets
\[
T_{rel}(L) \geq \max_{A \subset \Omega_A} \frac{\pi(A)\pi(A^c)}{D_A(\mathbb{1}_A)} \geq \frac{1}{2\Phi_*}, \tag{5.7}
\]
where $\Phi_*$ is the bottleneck ratio (also known as the Cheeger or Isoperimetric constant) given by
\[
\Phi_* = \min_{A : \pi(A) \leq \frac{1}{2}} \frac{D_A(\mathbb{1}_A)}{\pi(A)},
\]
where for a given set $A$ the ratio $D_A(\mathbb{1}_A)/\pi(A)$ is referred to as the bottleneck ratio of the set $A$. Due to reversibility, $D_A(\mathbb{1}_A)$ (called the boundary measure of the set $A$) can be written as
\[
D_A(\mathbb{1}_A) = \sum_{\eta \in A, \sigma \in A^c} \pi(\eta)K(\eta, \sigma) = \sum_{\eta \in \partial A} \pi(\eta)K(\eta, A^c) \tag{5.8}
\]
where
\[ \partial A := \{ \eta \in A : \exists \sigma \in A^c \text{ such that } \eta, \sigma \text{ are neighbors, i.e. } K(\eta, \sigma) > 0 \} \]
is the internal boundary of \( A \) and
\[
K(\eta, A^c) = \sum_{\sigma \in A^c} K(\eta, \sigma) = \sum_{x \in [1, L]} \{ q\eta_x + p(1 - \eta_x) \}
\]
is the total rate with which the East dynamics starting from \( \eta \) escapes from \( A \). Notice that \( K(\eta, A^c) \leq (\#\{ \text{zeros in } \eta \}) + 1 \leq L + 1 \), so that sets \( A \) for which the boundary has very small equilibrium measure with respect to the full set, \( \pi(\partial A) / \pi(A) \ll 1 / L \), admit small bottleneck ratios, which are \( o(1) \).

5.2.1. A first attempt for the choice of the set \( A \). As explained in Appendix A, we expect that there exist good choices of \( A \) in (5.7) such that the boundary \( \partial A \) separates the singleton \( \emptyset \) from \( \{ \eta_L = 1 \} \), i.e. \( \emptyset \in A \) and \( \{ \eta_L = 1 \} \subset A^c \). In what follows we show that for certain \( A \) featuring this property, \( \pi(\partial A) \ll 1 \) giving rise to a large relaxation time.

Our first candidate for the set \( A \) is inspired by the combinatorial work in [12] and it is defined as the set of configurations that are connected to \( \emptyset \) by paths in the set \( Z_{n+1}(A) \) (the set of configurations with at most \( n + 1 \) zeros) under the East dynamics. In order compute the bottleneck ratio for this set we first define an auxiliary set \( U_n \) which will turn out to be the internal boundary of our set \( A \).

Let \( V_n \) be the set of configurations in \( \{0, 1\}^N \) with exactly \( n \) zeros that can be obtained from \( \emptyset \) by the East dynamics and by using at most \( n \) simultaneous zeros, i.e. that can be reached from \( \emptyset \) by a path in \( Z_n(N) \). As proven in [12], for all \( \eta \in V_n \) the zeros of \( \eta \) are included in \( [1, 2^n - 1] \). Then, for any \( L \geq 2^n \), the set \( U_n \) is defined as the set of configurations \( \eta \) which are obtained from the configurations in \( V_n \) by flipping to zero the spin at \( L \).

The following lemma follows immediately from the bounds given in [12]:

**Lemma 5.4.** There exist constants \( c, c' \in (0, 1) \) such that, for all \( L \geq 2^n \),
\[
q^{n+1}pL^{n-1}2^{(\frac{n}{2})}n!(c')^n \leq \pi(U_n) \leq q^{n+1}pL^{n-1}2^{(\frac{n}{2})}n!c^n.
\]

The connection between the set \( A \) and \( U_n \) is as follows.

**Lemma 5.5.** Let \( L > 2^n \) and \( A \in \Omega_A \) be the set of configurations that are connected to \( \emptyset \) by paths in the set \( Z_{n+1}(A) \) under the East dynamics. Then \( \partial A \) is a bottleneck separating \( \emptyset \) from \( \{ \eta_L = 1 \} \) and \( \partial A = U_n \). Moreover there exists \( C > 1 \) such that
\[
T_{rel}(L) \geq \frac{\pi(A)}{2D_A(\emptyset_A)} \geq Cn^pL^n q^{n+1}2^{(\frac{n}{2})}n!.
\]

**Proof.** Clearly \( \emptyset \in A. \) The fact that \( \{ \eta : \eta_L = 1 \} \subset A^c \) follows from the above property of the vacancies of configurations in \( V_n \). In fact, to have \( \{ \eta : \eta_L = 1 \} \cap A \neq \emptyset \) there would be a path \( \emptyset = \eta^{(1)}, \eta^{(2)}, \ldots, \eta^{(k)} \in A \) with \( \eta^{(k)}_L = 1 \), with \( \eta^{(i)}_L = 0 \) for \( 1 \leq i < k \) and with \( \eta^{(k-1)}_x = 0 \) for \( x = L - 1 > 2^n - 1 \). In particular, defining \( \xi_x = \eta^{(k-1)}_x \) for \( 1 \leq x < L \) and \( \xi_L = 1 \) for \( x \geq L \), one would get a configuration \( \xi \in Z_n(N) \) with a vacancy on the right of \( 2^n - 1 \), which gives rise to a contradiction.
We now show that \( \partial A = U_n \) and \( A \) admits a small bottleneck ratio. \( U_n \) is the set of configurations in \( A \) with exactly \( n + 1 \) vacancy, since starting from 10 the East dynamics restricted to paths in \( Z_{n+1}(\Lambda) \) can not remove the vacancy at \( L \). It is trivial to check that this last set corresponds to \( \partial A \). Indeed, if \( \eta \in A \) has strictly less than \( n + 1 \) zeros, adding or removing a zero to \( \eta \) by a legal flip will bring us to a new configuration inside \( A \) by the definition of \( A \). If \( \eta \in A \) has \( n + 1 \) zeros, adding a zero to \( \eta \) by a legal flip will take the configuration outside \( A \), thus implying \( \eta \in \partial A \) (note that such a transition is possible since \( n < 2^n < L \) and therefore \( \eta \) cannot be given by the empty configuration). This completes the proof that \( \partial A = U_n \).

Take \( \eta \in A \) with \( n + 1 \) zeros. If we remove a zero from \( \eta \) by a legal flip we remain inside \( A \). Hence

\[
\mathcal{D}_\Lambda(1_A) = \sum_{\eta \in U_n \subset \Omega_\Lambda} \pi(\eta) \sum_{x \in [1, L]: \eta_x = 1, c_2^\Lambda(\eta) = 1} q \leq \pi(U_n)(n + 2)q.
\]

Since \( 10 \in A \), \( \pi(A) \geq \pi(10) = pL^{-1}q \). On the other hand, we know that \( \{\eta : \eta_L = 1\} \subset A^c \) and therefore \( \pi(A^c) \geq p > 1/2 \). At this point it is enough to apply (5.7) and (5.10) in order to get (5.11).

Taking \( n = \lceil \log_2 1/q \rceil \) and \( L > 2^n \), (5.11) together with the monotonicity in \( L \) of the relaxation time gives a lower bound on the infinite volume relaxation time similar to that previously obtained in [10]. However the bound is quite different from the actual bound claimed in Theorem 2. There in fact the large term \( n! \) appears in the numerator while in (5.11) it sits in the denominator. To correct this fact we need to find a different set, call it \( A_* \), giving rise to a smaller bottleneck ratio.

### 5.2.2. Definition of \( A_* \) by means of deterministic dynamics on \( \Omega_\Lambda \)

The construction of the set \( A_* \) has been inspired by capacity theory explained in Appendix A. One wants to choose the set \( A_* \) such that \( 1_{A_*} \) is `close' to the minimiser in the Dirichlet principle (A.3), which is given by \( f(\eta) = \mathbb{P}_\eta(\tau_{10} < \tau_0) \), where \( B = \{\eta_L = 1\} \) and \( \tau_{10} \) is the hitting time of 10 in \( \Omega_\Lambda \). The dynamics at small \( q \), on length scales which are much smaller than the equilibrium separation of vacancies, typically act by removing vacancies. Also (following [17] and [32]) we expect vacancies with the smallest distance to their neighbouring vacancy on the left (smallest domains) to be removed first. Following this idea, we essential say \( \eta \in A_* \) if starting from \( \eta \) and removing vacancies in order of their domain size we hit 10 before removing a vacancy at \( L \). We now proceed by giving a formal definition of \( A_* \) in terms of an algorithm, which we call the deterministic dynamics because it will approximate the order in which vacancies are typically removed by the East process for small \( q \).

For each configuration \( \eta \in \Omega_\Lambda \) we define the gap at \( x \in \Lambda \), denoted \( g_x(\eta) \), as the distance from \( x \) to the nearest vacancy on the left (including the origin where the frozen zero is located):

\[
g_x(\eta) := \min\{d > 0 : \eta_{x-d} = 0\}.
\]

Given \( \eta \in \Omega_\Lambda, 1 \leq d \leq L \) and \( x \in [1, L] \), we define \( \phi_{d,x}(\eta) \in \Omega_\Lambda \) as the configuration obtained from \( \eta \) by removing a vacancy at \( x \) if one is present with gap exactly \( d \), and
doing nothing otherwise:

\[
\phi_{d,x}(\eta)_y = \begin{cases} 
  1 & \text{if } y = x, \; \eta_x = 0, \; g_x(\eta) = d \\
  \eta_y & \text{otherwise}.
\end{cases}
\]  

(5.13)

The deterministic dynamics will be defined recursively by removing vacancies firstly with gap size one, starting from the right of the system and proceeding towards the origin, then removing those with gaps size two from right to left and continuing in this way. It is therefore convenient to endow the set \([1, L]^2\) with the following total order:

\[(d_1, x_1) \prec (d_2, x_2) \iff d_1 < d_2 \quad \text{or} \quad d_1 = d_2 \quad \text{and} \quad x_1 > x_2 .\]

Hence, we can order the elements of \([1, L]^2\) as \(\alpha_1 \prec \alpha_2 \prec \cdots \prec \alpha_{L^2}\). Notice \(\alpha\) gives rise to a bijection between \([1, L]^2\) and \([1, L]^2\) given explicitly by \(\alpha_k = ([k/L], (L - k \mod L) + 1)\) (where we identify \(\mathbb{Z}/L\mathbb{Z}\) with \(\{0, 1, \ldots, L - 1\}\) in the usual way).

We are now ready to define our deterministic dynamics in discrete time \(0, 1, 2, \ldots, L^2\).

Given the starting configuration \(\eta \in \Omega_\Lambda\), the new configuration \(\eta[k]\) at time \(k = 0, 1, 2, \ldots, L^2\) is recursively defined by the rule

\[
\begin{align*}
\eta[0] &= \eta, \\
\eta[k] &= \phi_{\alpha_k}(\eta[k - 1]) \quad \text{for } k = 1, 2, \ldots, L^2.
\end{align*}
\]

To more easily identify the stage of the deterministic dynamics we will use the following notation:

\[\Phi_{d,x}(\eta) := \eta[k] \quad \text{if} \quad \alpha_k = (d, x).\]

**Remark 5.6.** It is simple to check that the following procedure gives an equivalent definition of the deterministic dynamics. \(\Phi_{d,x}(\eta)\) is simply the configuration obtained from \(\eta\) as follows:

1. Erase all the vacancies of gap 1 from \(\eta\) (from the right to the left or simultaneously is equivalent). Call \(\eta^{(1)}\) the resulting configuration.
2. In general, for \(1 < i \leq d - 1\) erase from \(\eta^{(i-1)}\) all the vacancies with gap \(i\) and call the resulting configuration \(\eta^{(i)}\).
3. Erase from \(\eta^{(d-1)}\) all the vacancies of gap \(d\) located at \(y \geq x\). The resulting configuration is \(\Phi_{d,x}(\eta)\).

Having described the deterministic dynamics on \(\Omega_\Lambda\) we can define our set \(A_*\):

**Definition 5.7.** The set \(A_* \subset \Omega_\Lambda\) is given by the configurations \(\eta \in \Omega_\Lambda\) such that

\[\Phi_{L-1,1}(\eta) = \mathbb{1} 0 .\]

\[\Phi_{L-1,1}(\eta) = \mathbb{1} 0 .\]  

(5.14)

Equivalently, \(A_*\) is the set of all configurations \(\eta\) such that the deterministic dynamics hits \(\mathbb{1} 0\) before \(\{\eta_{L} = 1\}\).

**Remark 5.8.** It is simple to check that \(\mathbb{1} 0\) belongs to \(A_*\) and that \(\{\eta_{L} = 1\} \subset A_*^c\). An example of \(\eta \in \partial A_*\) is shown in Fig. 1.

We proceed by showing that \(A_*\) admits a very small bottleneck ratio.
\[\eta \in A^* \] \[\Phi_d, x(\eta) \]

\[\Phi_2, 11(\eta) \]

\[\Phi_2, 9(\eta) \]

\[\Phi_3, 7(\eta) \]

\[\Phi_4, 4(\eta) \]

\[\Phi_5, 16(\eta) \]

\[\eta^z \in A^* \]

\[\Phi_1, 9(\eta^z) \]

\[\Phi_1, 8(\eta^z) \]

\[\Phi_3, 7(\eta^z) \]

\[\Phi_4, 4(\eta^z) \]

\[\Phi_5, 16(\eta^z) \]

5.2.3. Key properties of \(A^*\) and proof of the lower bound in Theorem 2. Our key result is the following:

**Proposition 5.9.** Let \(2 \leq L \leq d/q\) and set \(n := \lceil \log_2 L \rceil\). Then

\[
D_{\Lambda}(\mathbb{1}_{A^*}) \leq \frac{q^n 2^n}{n!} q^{-\alpha}
\]

for some positive constant \(\alpha\) depending only on \(d\).

The following consequence will be useful to prove Theorem 5.

**Corollary 5.10.** Under the same assumptions of Proposition 5.9

\[
\pi(\partial A^*) \leq \frac{q^n 2^n}{n!} q^{-(1+\alpha)}.
\]

**Proof of the Corollary.** It follows immediately from Proposition 5.9 together with (5.8) if we observe that the escape rate \(K(\eta, A^*_c) \geq q\) for all \(\eta \in \partial A^*\) (cf. (5.9)). \qed

We have now all the ingredients to prove the lower bound in Theorem 2. As already observed \(10 \in A^*_c\) and \(\{\eta_L = 1\} \subset A^*_c\), so \(\pi(A^*_c) \geq p^{L-1}q\) and \(\pi(A^*_c) \geq p\). At this point
the lower bound on the relaxation time follows at once from (5.7) together with Proposition 5.9. The proof of Theorem 2 is now complete modulo the proof of Proposition 5.9 which is the subject of the following section.

5.2.4. Proof of Proposition 5.9. We first collect some properties which follow immediately from the definition of the deterministic dynamics:

(P1) The deterministic dynamics can only remove vacancies, hence gaps are increasing under the dynamics. Also, if \( \eta \) has a vacancy at \( x \) with gap \( d \), then such a vacancy is still present in the configurations \( \Phi_{d',x'}(\eta) \) with \( (d', x') \prec (d, x) \).

(P2) \( \Phi_{d,x}(\eta) \) contains no vacancies with gaps smaller than \( d \) and all vacancies right of \( x \) (including \( x \)) have gaps no smaller than \( d + 1 \).

(P3) Whether the deterministic dynamics removes a vacancy or not at a site \( x \) only depends on the configuration to the left of \( x \), so for all \( d, x, y \in [1, L] \) the value \( \Phi_{d,y}(\eta)_x \) is independent of \( \eta_{[x,y]} \).

(P4) Once the deterministic dynamics started from two different initial configurations are the same, then they remain the same. Equivalently, for two configurations \( \eta \) and \( \eta' \) if there exists \( (d, x) \) such that \( \Phi_{d,x}(\eta) = \Phi_{d,x}(\eta') \) then \( \Phi_{d,x}(\eta) = \Phi_{d,x}(\eta') \) for all \( (d, x') \succ (d, x) \). In this case we say that the two dynamics, starting from \( \eta \) and \( \eta' \) respectively, couple.

In what follows, we set \( \eta_0 := 0 \) to denote the frozen zero at the origin. To simplify the notation we continue to write \( \Lambda \) for \( [1, L] \) and introduce \( \Lambda^0 = [0, L] \) (note \( \Lambda^0 \) includes the origin on which there will always be a fixed vacancy).

Lemma 5.11. Let \( \eta \in \partial A_\ast \) and let \( z \in \Lambda \) be such that \( c_\ast^\Lambda(\eta) = 1 \) and \( \eta^x \not\subset A_\ast \). Take an interval \( I = [a, b] \subseteq \Lambda^0 \) containing \( z \) and \( z - 1 \). Define \( \ell := b - a = |I| - 1 \) and

\[
I_- := (a - \ell, a) \cap \Lambda^0, \\
I_+ := (b, b + \ell) \cap \Lambda^0.
\] (5.16)

Then \( I = \Lambda^0 \) or \( \eta \) has at least one vacancy in \( (I_- \cup I_+) \subset \Lambda^0 \).

Remark 5.12. If \( \eta \in \partial A_\ast \subset A_\ast \) then \( \eta_L = 0 \) since vacancies can only be removed by the deterministic dynamics. If \( I \neq \Lambda^0 \) then \( (I_- \cup I_+) \subset \Lambda^0 \) may contain the origin or the site \( L \) on which \( \eta \) is necessarily zero for all \( \eta \in \partial A_\ast \). This case is not excluded from the lemma. Fig. 2 shows an illustrated application of the lemma.
Proof. Fix $\eta \in \partial A_*$ and let $z \in \Lambda$ be such that $c_z^\Lambda(\eta) = 1$ and $\eta^z \notin A_*$. We first note that $z - 1 \in I$ and $\eta_{z-1} = 0$ because $c_z^\Lambda(\eta) = 1$. Also $z < L$, otherwise $\Phi_{\ell,L}(\eta)_L = 1$ which contradicts $\eta \in A_*$. Suppose for contradiction that $I \neq \Lambda^0$ and $\eta_y = 1$ for all $y \in I_- \cup I_+$. Since $I \neq \Lambda^0$ we have $\ell < L$. We will prove that

$$\Phi_{\ell,a+1}(\eta)_y = \Phi_{\ell,a+1}(\eta^z)_y \quad \forall y \in \Lambda_L,$$  \hfill (5.17)

which leads to a contradiction by property (P4) and the definition of $A_*$. Observe that $I \neq \Lambda^0$ implies $(I_- \cup I_+) \neq \emptyset$ since $1 \leq \ell < L$ and $z < L$.

Claim: (5.17) holds for all $y \in \Lambda$ with $y < z$. This follows immediately from property (P3) and the fact that $\eta$ and $\eta^z$ coincide on $[1,z)$.

Claim: (5.17) holds for all $y \in \Lambda$ with $y \geq b + 1$. Our supposition, $\eta_y = 1$ for all $y \in I_- \cup I_+$, implies $b + \ell < L$ since $\eta$ necessarily has a vacancy at $L$ for each $\eta \in A$. Since $z \leq b$, $\eta$ and $\eta^z$ coincide on $[b + 1, L]$. Since $\eta_L = 0$ there is at least one vacancy on $[b + 1, L]$, call $u$ the position of the leftmost vacancy of $\eta$ on $[b + 1, L]$. By hypothesis $\eta_y = 1$ for all $y \in [b + 1, b + \ell]$ so the vacancy at $u$ has gap $g_u(\eta) > \ell$ and $g_u(\eta^z) > \ell$. By property (P1) the vacancy at $u$ is still present in $\Phi_{\ell,a+1}(\eta)$, $\Phi_{\ell,a+1}(\eta^z)$. Since $\eta$ and $\eta^z$ coincide on the right of $u$, it is trivial to check that the deterministic dynamics starting from $\eta$ and $\eta^z$ coincides on $[u, L]$ until the vacancy at $u$ is removed. This proves (5.17) for $y \geq u$. Since $\eta$ and $\eta^z$ have no vacancy in $[b + 1, u)$, from property (P1) we derive (5.17) for $y \in [b + 1, u)$. This concludes the proof of our claim.

Claim: (5.17) holds for all $y \in \Lambda$ with $z \leq y \leq b$. We define the gap of the frozen vacancy at the origin as infinite, since it remains under the dynamics for all times, $g_0(\eta) = g_0(\eta^z) := \infty$. Let $u$ be the leftmost zero of $\eta$ and $\eta^z$ that is contained in $I$, $u$ is well defined since $\eta_{z-1} = \eta^z_{z-1} = 0$ and $\eta$ and $\eta^z$ coincide outside of $z$. By assumption $g_u(\eta) = g_u(\eta^z) \geq \ell$. Due to (P1) and (P2) we conclude that $\Phi_{\ell,u+1}(\eta)$ and $\Phi_{\ell,u+1}(\eta^z)$ still have a vacancy at $u$. This fact implies that both $\Phi_{\ell,u+1}(\eta)$ and $\Phi_{\ell,u+1}(\eta^z)$ have no vacancy in $[u + 1, b]$, otherwise they would have some vacancy of gap at most $b - u \leq \ell$ in contradiction with (P2).

The above Lemma 5.11 allows us to isolate a special subset of vacancies for a generic configuration $\eta \in \partial A_*$. This special subset will be defined iteratively. To this aim we first associate to $\eta \in \partial A_*$ an increasing family of subsets $\Delta_1 \subset \Delta_2 \subset \ldots \subset \Delta_K$ in $\Lambda^0$, where $\Delta_i$ contains at least $i$ vacancies, by the algorithm described below.

For clarity we first describe the algorithm in words. Take $\eta \in \partial A_*$ and define $z_0$ by choosing a site $z \in \Lambda$ such that $c_z^\Lambda(\eta) = 1$ and $\eta^z \notin A_*$. We know that $\eta_{z_0 - 1} = 0$ since $c_z^\Lambda(\eta) = 1$, set $\Delta_1 = [z_0 - 1, z_0]$. Let $a := z_0 - 1$, $b := z_0$, suppose $L > 1$ so that $\Delta_1 \neq \Lambda^0$, we know by Lemma 5.11 that there is a vacancy of $\eta$ in $I_- \cup I_+ \subset \Lambda^0$ (where $I_-$ and $I_+$ are defined as in Lemma 5.11), and since $\ell = 1$ we have $I_- = \emptyset$ and $I_+ = \{z_0 + 1\}$. Let $x_1 = z_0 + 1$ and make $\Delta_2$ the extension of $\Delta_1$ to include $x_1$, $\Delta_2 := [a, x_1]$. We now proceed by induction, defining $I = \Delta_k$ then $\Delta_{k+1}$ is the extension of $\Delta_k$ having $x_k$ as extreme, where $x_k$ is a vacancy of $\eta$ in $I_- \cup I_+$, by applying Lemma 5.11, until $\Delta_K = \Lambda^0$ (if there is more than one vacancy, fix a rule to specify $x_k$ uniquely). At a certain moment we will cover $\Lambda^0$, that is we arrive at a set $\Delta_K$ such that $\Delta_K = \Lambda^0$, and the algorithm will stop. In this way we show that $\eta$ contains at least a certain number of vacancies which must also satisfy certain geometric constraints.
5.11

This implies that for \( 2 \leq d \leq \ell \) as the set \([a, x]\) if \( x > b \) and as the set \([x, b]\) if \( x < a \). We assume that \( L > 1 \). The input of the algorithm is given by the pair \((\eta, z_0)\) where \( \eta \in \partial A_* \) and \( z_0 \in \Lambda \) is such that \( c_{z_0}^\Lambda (\eta) = 1 \) and \( \eta z_0 \not\in A_* \).

Algorithm to determine \( K, \Delta_1, \Delta_2, \ldots, \Delta_K \) given \((\eta, z_0)\).

- **STEP 0:** Set \( z_1 = z_0 - 1 \) and \( \Delta_1 := [z_1, z_0] \).

- **INDUCTIVE STEP.** Suppose we have defined \( \Delta_1, \Delta_2, \ldots, \Delta_k \), let \( I = \Delta_k \). Define \( \ell, I_- \) and \( I_+ \) as in Lemma 5.11.
  - **Case 1:** If \( \Delta_k = \Lambda^0 \) set \( K = k \) and STOP.
  - **Case 2:** If \( \Delta_k \neq \Lambda^0 \) then let \( z_{k+1} \) be the position of the vacancy of \( \eta \) in \( I_- \cup I_+ \) which is nearest to the border of \( \Delta_k \) (take the leftmost one if two are of equal distance). Such a vacancy at \( z_{k+1} \) exists due to Lemma 5.11. Set \( \Delta_{k+1} := \Delta_k \times z_{k+1} \).

Since \( \Delta_{k+1} \) is obtained from \( \Delta_k \) by enlarging it, the above algorithm always stops. Note that each interval \( \Delta_{k+1} \) is obtained by extending \( \Delta_k \) either on the left or on the right. Hence \( \Delta_{k+1} \) has one extreme in common with \( \Delta_k \) and one extreme not belonging to \( \Delta_k \). The following observation is fundamental and follows immediately from the definition of the algorithm (we omit its proof):

**Lemma 5.13.** The vacancies of \( \eta \in \partial A_* \) in \( \Lambda^0 \setminus \{z_0\} \) are located at \( \{z_1, z_2, \ldots, z_K\} \), moreover

\[ |\Lambda \cap \{z_1, z_2, \ldots, z_K\}| = K - 1. \]

In particular the number of vacancies of \( \eta \in \partial A_* \) is \( K - 1 \) or \( K \), if \( \eta z_0 = 1 \) or \( 0 \) respectively.

We recall that the set \( \{z_1, z_2, \ldots, z_K\} \) depends on \( \eta \in \partial A_* \), although it certainly contains the origin, on which there is a frozen vacancy, and \( L \) since \( \eta_L = 0 \) for each \( \eta \in \partial A_* \subset A_* \).

We now isolate some geometric properties of \( z_0, z_1, z_2, \ldots, z_K \). First note that given \( z_0, z_1, \ldots, z_K \) we can recover \( \Delta_1, \Delta_2, \ldots, \Delta_K \). Given \( z_0 \) the first two positions of vacancies \( z_1, z_2 \) are determined by Lemma 5.11 (\( z_1 = z_0 - 1 \) and \( z_2 = z_0 + 1 \)). To describe the points \( z_0, z_1, z_2, \ldots, z_K \) we can use the following formalism. For each \( 2 \leq k \leq K \) we set \( \varepsilon_k = -1 \) if \( z_k \) is on the left of \( \Delta_{k-1} \) and \( \varepsilon_k = +1 \) otherwise; while we define \( d_k \) as the Euclidean distance of \( z_k \) from \( \Delta_{k-1} \). Hence, writing \( \Delta_{k-1} = [a, b] \), we have \( z_k = a - d_k \) if \( \varepsilon_k = -1 \) and \( z_k = b + d_k \) if \( \varepsilon_k = +1 \). Writing \( \ell_k \) for the length of \( \Delta_k \) (\( \ell_k = |\Delta_k| - 1 \)), note that

\[
\begin{align*}
\ell_1 &= 1, \\
d_k &\leq \ell_{k-1} \quad \forall k : 2 \leq k \leq K, \\
\ell_k &= \ell_{k-1} + d_k \quad \forall k : 2 \leq k \leq K.
\end{align*}
\]

This implies that \( \ell_k = d_1 + d_2 + d_3 + \cdots + d_k \) (where \( d_1 := 1 \)) and \( \ell_k = \ell_{k-1} + d_k \leq 2 \ell_{k-1} \) for \( 2 \leq k \leq K \). In particular,

\[ \ell_k \leq 2^{k-1} \quad \forall k : 1 \leq k \leq K. \]
When the algorithm stops $\Delta_K = \Lambda^0$ and $\ell_k = L$, so $L \leq 2^{K-1}$ which implies $K \geq n + 1$ where $n = \lceil \log_2 L \rceil$.

Due to (5.8) and (5.9) we have
\begin{equation}
D_{\Lambda}(I_{A_*}) = \sum_{z_0 \in A} \left[ p \pi (\partial A_{z_0}^0) + q \pi (\partial A_{z_0}^1) \right],
\end{equation}
where
\begin{align*}
\partial A_{z_0}^0 := & \{ \eta \in \partial A : e_{z_0}^\Lambda (\eta) = 1, \eta_{z_0} = 0 \text{ and } \eta^{z_0} \notin A_\ast \}, \\
\partial A_{z_0}^1 := & \{ \eta \in \partial A : e_{z_0}^\Lambda (\eta) = 1, \eta_{z_0} = 0 \text{ and } \eta^{z_0} \notin A_\ast \}.
\end{align*}

Collecting all the above geometric considerations we have the following result:

**Lemma 5.14.** The boundary $\partial A_\ast$ satisfies $\partial A_\ast = \bigcup_{z_0 \in A} \bigcup_{i \in \{0, 1\}} \partial A_{z_0}^{i}$ and
\begin{equation}
\partial A_{z_0}^i \subset \{ \eta \in \Omega_\Lambda : \eta_{z_0} = i \text{ and } \eta_{z} = 0 \forall z \in W \cap \Lambda \text{ for some } W \in \Gamma_{z_0} \}
\end{equation}
where the set $\Gamma_{z_0}$ is given by the families $\{z_1, \ldots, z_{n+1}\}$ of distinct points in $\Lambda^0$ such that
- the position of $z_1 = z_0 - 1$ is uniquely determined by $z_0 \in \Lambda$,
- $\{z_1, \ldots, z_{n+1}\} \cap \Lambda \geq n$,
- there exist positive integers $d_1, \ldots, d_{n+1}$ such that
  \begin{equation}
  \begin{cases}
  d_1 = 1, \\
  d_k \leq d_1 + d_2 + \cdots + d_{k-1} & \forall k : 2 \leq k \leq n+1.
  \end{cases}
  \end{equation}
- there exist $\varepsilon_2, \ldots, \varepsilon_{n+1} \in \{-1, +1\}$ such that, setting $\Delta_1 := [z_1, z_0]$, the following recursive identities are satisfied for $k = 2, \ldots, n+1$
  \begin{equation}
  \begin{cases}
  z_k = a - d_k & \text{if } \varepsilon_k = -1, \\
  z_k = b + d_k & \text{if } \varepsilon_k = 1,
  \end{cases}
  \end{equation}
where $\Delta_{k-1} = [a, b]$ and $\Delta_k := \Delta_{k-1} \ast z_k$.

As immediate consequence of the above lemma we get, for $i = 1$ or 0
\begin{equation}
q^i \pi (\partial A_{z_0}^i) \leq q^i \sum_{W \in \Gamma_{z_0}} \pi(\eta_{z_0} = i \text{ and } \eta_{z} = 0 \forall z \in W \cap \Lambda) \leq q^{n+1} |\Gamma_{z_0}|.
\end{equation}

To estimate $|\Gamma_{z_0}|$ we use the following result:

**Lemma 5.15.** The numbers of strings $(d_2, d_3, \ldots, d_{n+1})$ of positive integers satisfying (5.22) is bounded from above by $\frac{2^{\binom{n}{2}}}{n!}$, hence
\begin{equation}
|\Gamma_{z_0}| \leq \frac{2^{\binom{n}{2}}}{n!}.
\end{equation}

**Proof.** We give an iterative bound. Given an integer $j$ we define
\begin{equation}
U(j) := \{ (x_1, x_2, \ldots, x_j) : 0 \leq x_1 \leq 1 \text{ and } 0 \leq x_k \leq x_1 + \cdots + x_{k-1} \forall k : 2 \leq k \leq j \}.
\end{equation}

Setting $M_j := x_1 + x_2 + x_3 + \cdots + x_j$, integrating on the last variable we get
\begin{equation}
\int_{U(j)} dx_1 dx_2 \cdots dx_j = \int_{U(j-1)} dx_1 dx_2 \cdots dx_{j-1} M_{j-1}.
\end{equation}
We now prove by induction that
\[
\int_{U(j-m)} dx_1 dx_2 \cdots dx_{j-m} M^m_{j-m} \leq \frac{2^{m+1}}{m+1} \int_{U(j-m-1)} dx_1 dx_2 \cdots dx_{j-m-1} M^{m+1}_{j-m-1},
\]
for all \( m \geq 1 \) and \( j - m - 1 \geq 1 \). By integrating on the last variable we get
\[
\int_{U(j-m)} dx_1 dx_2 \cdots dx_{j-m} M^m_{j-m} = \int_{U(j-m)} dx_1 dx_2 \cdots dx_{j-m-1} (M_{j-m-1} + x_{j-m})^m
\]
\[
= \int_{U(j-m-1)} dx_1 dx_2 \cdots dx_{j-m-1} \left[ \frac{(M_{j-m-1} + x_{j-m})^{m+1}}{m+1} \right]_{x_{j-m}=0}^{x_{j-m}=M_{j-m-1}}
\]
\[
\leq \frac{2^{m+1}}{m+1} \int_{U(j-m-1)} dx_1 dx_2 \cdots dx_{j-m-1} M^{m+1}_{j-m-1}.
\]
Combining (5.26) and (5.27) we conclude that
\[
\int_{U(j)} dx_1 dx_2 \cdots dx_j \leq \frac{2^2 \cdot 2^3 \cdots 2^{j-1}}{2 \cdot 3 \cdots (j-1)} \int_{U(1)} dx_1 M_j^{j-1}
\]
\[
\leq \frac{2^{(j-1)}}{(j-1)!}.
\]
The result then follows from this bound by observing that the number of strings we want to estimate is bounded from above by \( \int_{U(n+1)} dx_1 dx_2 \cdots dx_{n+1} \), and observing that there at most \( 2^n \) ways to choose \( \varepsilon_2, \ldots, \varepsilon_{n+1} \). \( \square \)

Combining (5.20), (5.21), (5.25), and observing that there are \( L \) choices for \( z_0 \) we find
\[
D_{\Lambda} (1_{A_*}) \leq \frac{q^{n+1} L 2^{\binom{n}{2}}}{n!}.
\]
thus implying Proposition 5.9 (recall that \( L \leq d/q \)). Since \( 10 \in A \) and \( \{ \eta_L = 1 \} \in A^c \) we have \( \pi(A) \geq p^{L-1} q \) and \( \pi(A^c) \geq p \), so (5.7) gives rise to the lower bound
\[
T_{rel}(L) \geq \frac{n!}{q^{n/2(\binom{n}{2})}} \frac{p^L}{2^{n+1} L} \text{ where } n = \lceil \log_2 L \rceil.
\]

6. Time scale separation and dynamic heterogeneity: proofs

6.1. Proof of Theorem 3. Point (i) of Theorem 3 is an immediate consequence of the bound (2.6). The time scale separation expressed by (2.9) is a corollary of (2.8), as follows. Let \( L = d/q^\gamma \) with \( \gamma \in (0, 1) \), \( d > 0 \), and \( L' = \lambda L \) with \( \lambda > 1 \). Then \( L, L' \in [1, 1/q] \) for \( q \) sufficiently small, so Theorem 2 implies there exists some universal constant \( \alpha > 0 \) such that,
\[
\frac{T_{rel}(L')}{T_{rel}(L)} \geq \frac{n'! 2^{\binom{n'}{2}}}{n! 2^{\binom{n}{2}}} \left( \frac{\alpha}{n - n'} \right)^{n - n' + \alpha}, \quad n = \lceil \log_2 L \rceil, \quad n' = \lceil \log_2 L' \rceil.
\]
Let $k := (n' - n) \geq \lceil \log_2 \lambda \rceil$ which is independent of $q, d$ and $\gamma$. Since $\frac{d}{q} \leq 2^\alpha \leq 2d$, the above bound (6.1) and some straightforward algebra lead to,

$$\frac{T_{\text{rel}}(L')}{T_{\text{rel}}(L)} \geq Cn' q^{\alpha - (1 - \gamma)k}$$

for some $C$ independent of $q$. The result follows by choosing $\lambda$ large enough.

It remains to show that, for $\gamma < 1/2$ and $L = d/q^\gamma$, $T_{\text{rel}}(2L) \geq T_{\text{rel}}(L)$. For this purpose define $L' := 2L$ and set $t = q^\beta T_{\text{rel}}(L)$ with $0 < \beta < 1 - \gamma$. A union bound shows that, for any integer $N$,

$$P_{10}^{\Lambda'}(\eta_x(s) = 1 \forall x \neq 2L, \forall s = it, i = 1, \ldots, N) \geq 1 - \sum_{i=1}^N \sum_{x=1}^{2L-1} \frac{1}{\pi_{\Lambda' \setminus \{2L\}}(1)} P_{\pi}^{\Lambda'}(\eta_x(it) = 0) \geq 1 - \frac{2dN}{(1 - \gamma)2L - 1} q^{1 - \gamma} = 1 - 2dNq^{1 - \gamma}(1 + o(1)), \quad (6.2)$$

where $\Lambda' = \{1, 2, \ldots, L'\}$. Consider now the East model in $\Lambda'$ starting from $10 \in \Omega_{\Lambda'}$ and let $\tau_L$ be the first time that there is a legal ring at $x = L$ with the corresponding coin toss equal to one. Clearly $\tau_L$ has the same law as the hitting time $\tau_{\eta_L=1}$ under the measure $P_{10}^\Lambda$. Define the auxiliary Markov time $\tilde{\tau}$ by

$$\tilde{\tau} = \inf \{s > \tau_L : \eta(s) = 10 \text{ or } \eta_{2L}(s) = 1\}.$$

Writing

$$P_{10}^{\Lambda'}(\tilde{\tau} - \tau_L \geq t) \leq P_{10}^{\Lambda'}(\tau_L \geq q^{-\epsilon} T_{\text{rel}}(L)) + P_{10}^{\Lambda'}(\tilde{\tau} - \tau_L \geq t ; \tau_L \leq q^{-\epsilon} T_{\text{rel}}(L)),$$

we can bound the first probability on the right hand side by $O(q^\epsilon)$ using Proposition 3.2. We may bound the second probability by using (6.2) with $N = \lceil q^{-\epsilon} T_{\text{rel}}(L)/t \rceil$ and $\epsilon = (1 - \gamma - \beta)/2$, so that

$$P_{10}^{\Lambda'}(\tilde{\tau} - \tau_L \geq t) = O(q^{(1 - \gamma - \beta)/2}). \quad (6.3)$$

**Claim 6.1.** For any $\gamma < 1/2$,

$$P_{10}^{\Lambda'}(\eta(\tilde{\tau}) = 10) = 1 - O(q^\delta)$$

for some $\delta > 0$.

**Proof of the Claim.** We write

$$P_{10}^{\Lambda'}(\eta_{2L}(\tilde{\tau}) = 1) \leq P_{10}^{\Lambda'}(\eta_{2L}(\tilde{\tau}) = 1 ; \tilde{\tau} - \tau_L \leq t) + P_{10}^{\Lambda'}(\eta_{2L}(\tilde{\tau}) = 1 ; \tilde{\tau} - \tau_L \geq t) \quad (6.4)$$

The last term in the r.h.s. of (6.4) is $O(q^{(1 - \gamma - \beta)/2}$ because of (6.3). Let us examine the first term. The strong Markov property gives

$$P_{10}^{\Lambda'}(\eta_{2L}(\tilde{\tau}) = 1 ; \tilde{\tau} - \tau_L \leq t) \leq \max_{\eta \in \Omega_{L-1,2L}} P_{\eta}^{\Lambda'}(\eta_{2L}=1 - \tau_L \leq t)$$

where $\Omega_{L-1,2L} = \{\eta \in \Omega_{\Lambda'} : \eta_{L-1} = \eta_{2L} = 0, \eta_x = 1 \forall x \in [L, 2L - 1]\}$.

Choose $\eta \in \Omega_{L-1,2L}$ and declare the vacancy at $x = L - 1$ to be the distinguished zero at time zero (see e.g. [2] or [10]). At any later time $s > 0$ the position $\xi(s)$ of the
distinguished zero is determined according to the following iterative rule:

(i) If \( \xi(s) > 0 \) then \( \xi(s') = \xi(s) \) for all times \( s' > s \) which are strictly smaller than the time \( s_1 \) of the first legal ring at \( \xi(s) \);

(ii) at time \( s_1 \) the distinguished zero \( \xi(s) \) jumps to \( \xi(s) - 1 \);

(iii) if \( \xi(s) = 0 \) then \( \xi(s') = 0 \) for all \( s' > s \).

Thus, with probability one, the path \( \{\xi(s)\}_{s \leq t} \) is right-continuous, piecewise constant, non increasing, with possibly \( n \in \{0, 1, \ldots, L - 1\} \) discontinuities at times \( s_1 < s_2 < \cdots < s_n \), at which it decreases by one. In the sequel we will adopt the standard notation \( \xi_{s-} := \lim_{s \downarrow 0} \xi_{s-} \), and set \( s_0 := 0 \).

**Remark 6.2.** Because of the orientation of the East constraint, fixing the path \( \{\xi(s)\}_{s \leq t} \) has no influence whatsoever on the Poisson rings and coin tosses to the right of the path itself. Thus the evolution to the right of the path \( \{\xi(s)\}_{s \leq t} \) is still an East evolution in a domain whose left boundary jumps by one site to the left at the jumps of the path.

The key property of the distinguished zero is the following [2, Lemma 4]. Suppose that the configuration \( \eta \) to the right of \( L - 1 \) and to the left of \( 2L \) was chosen according to the reversible measure \( \pi \) (instead of being identically equal to 1). Then, at any given time \( s > 0 \) and conditionally on the path \( \{\xi(s)\}_{s' \leq s} \), the law of the restriction of \( \eta(s) \) to the interval \( \{\xi(s) + 1, \ldots, 2L - 1\} \) is again \( \pi \).

Using the same argument leading to (6.2) together with the above property, if

\[
\Omega_s = \{ \eta \in \Omega_{\Lambda'} : \eta_x = 1 \text{ for all } x \in [\xi(s) + 1, 2L - 1] \},
\]

then

\[
P_{\eta}^{\Lambda'}(\exists i \leq n : \eta(s_i) \notin \Omega_{s_i} | \{\xi_s\}_s \leq t) = O(n q^{1-\gamma}) = O(q^{1-2\gamma}).
\]

As a consequence

\[
P_{\eta}^{\Lambda'}(\tau_{\eta_{2L}=1} \leq t | \{\xi_s\}_s \leq t) \leq \sum_{i=0}^{n} P_{\eta}^{\Lambda'}(\tau_{\eta_{2L}=1} \in (s_i, s_{i+1}) | \eta(s_i) \in \Omega_{s_i} \setminus \{\xi_s\}_s \leq t)
\]

\[
+ P_{\eta}^{\Lambda'}(\tau_{\eta_{2L}=1} \in (s_n, t) | \eta(s_n) \in \Omega_{s_n} \setminus \{\xi_s\}_s \leq t) + O(q^{1-2\gamma}).
\]

Let us examine a generic term \( P_{\eta}^{\Lambda'}(\tau_{\eta_{2L}=1} \in (s_i, s_{i+1}) | \eta(s_i) \in \Omega_{s_i} \setminus \{\xi_s\}_s \leq t) \). Since (i) the distinguished zero does not move in the time interval \([s_i, s_{i+1})\), (ii) the interval \( \{\xi(s_i) + 1, \ldots, 2L\} \) has length at least \( L \) and (iii) \( \eta(s_i) \in \Omega_{s_i} \), the above probability is smaller than \( P_{\eta}^{A_{L}}(\tau_{\eta_{L}=1} \leq s_{i+1} - s_i) \). Due to Proposition 3.2 together with Theorem 1 we have

\[
P_{\eta}^{A_{L}}(\tau_{\eta_{L}=1} \leq s_{i+1} - s_i) \leq c(s_{i+1} - s_i) / T_{hit}(L) \leq c(s_{i+1} - s_i) / T_{rel}(L).
\]

Thus

\[
\sum_{i=0}^{n} P_{\eta}^{\Lambda'}(\tau_{\eta_{2L}=1} \in (s_i, s_{i+1}) | \eta(s_i) \in \Omega_{s_i} \setminus \{\xi_s\}_s \leq t)
\]

\[
+ P_{\eta}^{\Lambda'}(\tau_{\eta_{2L}=1} \in (s_n, t) | \eta(s_n) \in \Omega_{s_n} \setminus \{\xi_s\}_s \leq t)
\]

\[
\leq c t / T_{rel}(L) = O(q^{\beta})
\]

In conclusion

\[
\max_{\eta \in \Omega_{L-1,L}} P_{\eta}(\tau_{\eta_{2L}=1} \leq t) = O(q^{\beta}) + O(q^{1-2\gamma})
\]
and the claim follows with \( \delta = \min (\beta, 1 - 2\gamma, (1 - \gamma - \beta)/2) \).

Back to the proof of \( T_{\text{rel}}(2L) \geq T_{\text{rel}}(L) \) we observe that, on the event \( \{ \eta_\tau = 0 \} \), the hitting time \( \tau_{\eta_\tau = 1} \) is larger than \( \tau_L + \tau' \), where \( \tau' \) is distributed as \( \tau_{\eta_\tau = 1} \) and it is independent of \( \tilde{\tau} \). Hence, using Claim 6.1 and Proposition 3.2,

\[
T_{\text{hit}}(2L) = \mathbb{E}^\Lambda_1(\tau_{\eta_{2L} = 1}) \geq \mathbb{E}^\Lambda_1(\tau_{\eta_{2L} = 1} \mathbb{1}_{\eta_\tau = 10}) \geq T(L) \mathbb{P}^\Lambda_1(\tau_L \geq T(L) \mathbb{1}_{\eta_\tau = 10}) \geq T(L) \left[ 1/4 - \mathbb{P}^\Lambda_1(\eta_\tau = 10) \right] + (1 - O(q^\delta)) T_{\text{hit}}(2L)
\]

which implies

\[
T_{\text{hit}}(2L) \geq cq^{-\delta} T(L).
\]

Here \( T(L) \) is such that \( \mathbb{P}^\Lambda_1(\tau_L \geq T(L)) = 1/4 \). Using that \( T(L) \ll T_{\text{hit}}(L) \approx T_{\text{rel}}(L) \) we conclude the proof.

6.2. Proof of Theorem 4. We prove (2.11) then (2.12) is a trivial consequence. It is enough to compare the scale \( d/q \) with \( 1/q \) (recall that we write \( d/q \) instead of \( [d/q] \)). In particular, if for any \( \delta > 0 \) we can show that

\[
T_{\text{rel}}(1/q) \leq T_{\text{rel}}(d/q) \leq CT_{\text{rel}}(1/q), \quad \forall d \in [1, 1/\delta], \tag{6.5}
\]

\[
T_{\text{rel}}(d/q) \leq T_{\text{rel}}(1/q) \leq C' T_{\text{rel}}(d/q), \quad \forall d \in [\delta, 1]. \tag{6.6}
\]

for suitable constants \( C, C' \) depending only \( \delta \), then we immediate get (2.11). Notice that the first bound in (6.5) and the second bound in (6.6) trivially follow from the monotonicity of the relaxation time w.r.t. the interval length (see Lemma 3.1).

Let us prove that \( T_{\text{rel}}(d/q) \leq C T_{\text{rel}}(1/q) \) for all \( d \in [1, 1/\delta] \). To this aim we use the block dynamics as in the proof of the upper bound in Theorem 2. Given an integer length \( \ell \in [1/q, 1/\delta q] \) consider the block dynamics on \( [1, \ell] \) in which the left half \( \Lambda_1 := [1, \lfloor \ell/2 \rfloor] \) goes to equilibrium with rate 1, while the second half \( \Lambda_2 := [\lceil \ell/2 \rceil, 1] \) does the same but only if there is a zero in \( \Delta := [\lfloor \ell/4 \rfloor, \lfloor \ell/2 \rfloor] \). As proven in [9][p. 480] this dynamics has the spectral gap

\[
\lambda := 1 - \sqrt{(1-q)|\Delta|} \sim 1 - e^{-q\ell/8} \sim q\ell/8 \geq 1/8.
\]

On the other hand, as proven in [9] (see also the proof of the upper bound in Theorem 2), we have

\[
T_{\text{rel}}(\ell) \leq \frac{2}{\lambda} \max\{T_{\text{rel}}(\Lambda_1), T_{\text{rel}}(\Delta \cup \Lambda_2)\} \leq 16T_{\text{rel}}(\lfloor (3/4)\ell \rfloor).
\]

To conclude, one has to apply iteratively the above bound \( T_{\text{rel}}(\ell) \leq 16T_{\text{rel}}(\lfloor (3/4)\ell \rfloor) \) starting from \( \ell_1 := d/q \) and going from \( \ell_i \) to \( \ell_{i+1} := \lfloor (3/4)\ell_i \rfloor \). Clearly the number \( m \) of steps necessary to get to \( \ell_m < 1/q \) is \( O(\ln d/\ln(4/3)) \) and it can be bounded from above by some constant \( c(\delta) \). Hence, by the monotonicity of the relaxation time in the length, we obtain

\[
T_{\text{rel}}(d/q) \leq 16^{m-1}T_{\text{rel}}(\ell_m) \leq 16^{m-1}T_{\text{rel}}(1/q),
\]
thus proving our claim (6.5). The proof of (6.6) is analogous.

6.3. Proof of Theorem 5.

Proof of (i). Without loss of generality we take \( d = 1 \). Let \( t := T_{\text{rel}}(1/q \gamma) \) and let also \( \epsilon \in (0,1) \) be a small constant to be fixed later on. The same proof of [15, Lemma 4.2] shows that

\[
\sup_{\eta} \mathbb{P}^{\Lambda}_{\eta}\left( \exists z : \eta_z(t) = 0 \text{ and } \exists s \leq t : \eta_z(s) = 1 \right) = O(qL) = o(1). \quad (6.7)
\]

Thus

\[
\sup_{\eta} \mathbb{P}^{\Lambda}_{\eta}\left( \exists z, z' : |z - z'| \leq \epsilon/q \gamma, \eta_z(t) = \eta_{z'}(t) = 0 \right)
= \sup_{\eta} \mathbb{P}^{\Lambda}_{\eta}\left( \exists z, z' : |z - z'| \leq \epsilon/q \gamma, \eta_z(s) = \eta_{z'}(s) = 0 \forall s \leq t \right) + o(1).
\]

Moreover

\[
\sup_{\eta} \mathbb{P}^{\Lambda}_{\eta}\left( \exists z, z' : |z - z'| \leq \epsilon/q \gamma, \eta_z(s) = \eta_{z'}(s) = 0 \forall s \leq t \right)
\leq \sum_{z < z'} \sup_{|z-z'| \leq \epsilon/q \gamma} \mathbb{P}^{\Lambda}_{\eta}\left( \eta_{z'}(s) = 0 \forall s \leq t | \eta_z(s) = 0 \forall s \leq t \right)
\leq \sum_{z < z'} \mathbb{P}^{\Lambda_{z,z'}}_{\mathbb{I}_{10}}(\tau_{\sigma_{z'} = 1} > t)
\quad (6.8)
\]

where \( \Lambda_{z,z'} = [z + 1, z'] \). Due to Proposition 3.2

\[
\mathbb{P}^{\Lambda_{z,z'}}_{\mathbb{I}_{10}}(\tau_{\sigma_{z'} = 1} > t) \leq e^{-ct/\text{hit}(z'-z)}
\]

for some constant \( c \) independent of \( z, z' \). If we now combine Theorem 1, Lemma 3.1 and (2.9) we get

\[
\min \frac{t}{\text{hit}(z' - z)} \geq c T_{\text{rel}}(1/q \gamma)/T_{\text{rel}}(\epsilon/q \gamma) \geq 1/q^\delta
\]

for some \( \delta > 0 \) and for all \( \epsilon \) small enough. Thus the r.h.s. of (6.8) is \( o(1) \). \( \square \)

Proof of (ii). Let \( t := T_{\text{rel}}(\epsilon/q \gamma) \) and fix \( \eta \) such that: (i) \( \eta_L = 0 \) and (ii) \( L - z \geq 1/q \gamma \)

where \( z := \max\{y \in [1, L - 1] : \eta_y = 0\} \) if the set is non-empty and \( z := 0 \) otherwise.

If \( z = 0 \) then \( \eta = \mathbb{1}_0 \) and

\[
\mathbb{P}^{\Lambda}_{\eta}(\eta_L(t) = 0) \geq \mathbb{P}^{\Lambda}_{\mathbb{I}_{10}}(\tau_{\eta_L = 1} > t)
\geq 1 - \epsilon t/\text{hit}(L) = 1 - o(1)
\]

for \( \epsilon \) small enough. Above we used Proposition 3.2 and Theorem 3 to bound from above \( t/\text{hit}(L) \).

Assume now \( z \neq 0 \) and let \( \Lambda' := [z + 1, L] \). Let \( A_* \subset \Omega_{\Lambda'} \) be the set given in Definition 5.7 with \( \Lambda \) replaced by \( \Lambda' \) and \( L \) replaced by the cardinality \( L - z \) of \( \Lambda' \). With a small abuse of notation, from now on we denote by \( A_* \) the subset of \( \Omega_{\Lambda} \) given by
\{ \sigma \in \Omega_\Lambda : \sigma_{\Lambda'} \in A_\sigma \}. \) To \( A_\sigma \) we can associate two inner boundaries, \( \partial^A A_\sigma \) and \( \partial^{A'} A_\sigma \), as follows:
\[
\partial^A A_\sigma = \{ \sigma \in A_\sigma : \exists x \in \Lambda' \text{ with } c^A_x(\sigma) = 1 \text{ and } \sigma^x \not\in A_\sigma \} \quad (6.9)
\]
\[
\partial^{A'} A_\sigma = \{ \sigma \in A_\sigma : \exists x \in \Lambda' \text{ with } c'^{A'}_{x}(\sigma) = 1 \text{ and } \sigma^x \not\in A_\sigma \} \quad (6.10)
\]
Clearly \( \partial^A A_\sigma \subset \partial^{A'} A_\sigma \) because \( c^A_x \leq c'^{A'}_{x} \). Moreover (see Remark 5.8) \( \eta \in A_\sigma \) since \( \eta_\sigma = 1 \) for \( x \in [z, 1, L - 1] \). Thus, if \( \eta_L(t) = 1 \) then necessarily \( \eta(s) \in \partial^A A_\sigma \) at some intermediate time \( s \leq t \). In conclusion
\[
\mathbb{P}_\eta^A(\eta_L(t) = 0) \geq 1 - \mathbb{P}_\eta^A(\exists s < t : \eta(s) \in \partial^A A_\sigma)
\]
We first bound from above \( \mathbb{P}_\eta^A(\eta(s) \in \partial^A A_\sigma) \) using the following observation. If the restriction \( \eta_{\Lambda'} \) to \( \Lambda' \) was distributed according to the stationary measure \( \pi \) rather than being identically equal to \( 1 \), then this property would be preserved at any later time.
To prove it is enough to observe that between any two updates of the site \( z \) the dynamics in \( \Lambda' \) is reversible w.r.t. \( \pi \) irrespectively of the actual value of the spin at \( z \) and that the updates at \( z \) do not depend on the configuration in \( \Lambda' \). Therefore
\[
\mathbb{P}_\eta^A(\eta(s) \in \partial^A A_\sigma) \leq \frac{1}{\pi(\eta_{\Lambda'})} \sum_{\sigma: \sigma_{\Lambda' \setminus \Lambda} = \eta_{\Lambda' \setminus \Lambda}} \pi(\sigma_{\Lambda'}) \mathbb{P}_\sigma^A(\sigma(s) \in \partial^A A_\sigma)
\]
\[
\leq \frac{e}{q} \pi(\partial^A A_\sigma).
\]
Corollary 5.10 now implies that
\[
\pi(\partial^A A_\sigma) \leq \pi(\partial^{A'} A_\sigma) \leq \frac{q^{n2(z)}(2)}{n!} q^{-(1+\alpha)}
\]
where \( n = \lfloor \log_2 L \rfloor \). Thus
\[
\mathbb{P}_\eta^A(\eta(s) \in \partial^A A_\sigma) \leq \frac{e q^{n2(z)}(2)}{n!} q^{-(2+\alpha)}.
\]
In conclusion, a simple union bound over all possible rings in \( \Lambda \) within time \( t \) (see e.g. [16, after (5.12)]) gives
\[
\mathbb{P}_\eta^A(\exists s < t : \eta(s) \in \partial^A A_\sigma) \leq e L t \frac{q^{n2(z)}(2)}{n!} q^{-(2+\alpha)} + e^{-Lt} = o(1)
\]
for all \( \epsilon \) small enough. The last identity follows from Theorem 3 (ii) and the fact that \( t = T_{rel}(\epsilon/q^\gamma) \). \( \square \)

**Appendix A. Capacity methods**

In this section we summarize some known results on potential theory for reversible Markov process, which can be found for example in [6, 7, 19, 24], in the context of the East process. In Appendix A.1 we give a more detailed motivation for the construction used to prove the lower bound of Theorem 2 and we provide an alternative proof of the upper bound in Appendix A.2.

We recall the definition of the *electrical network* associated to the interval \( \Lambda = [1, L] \). We consider the undirected graph \( G_\Lambda \) with vertex set \( \Omega_\Lambda := \{0,1\}^\Lambda \) and with edges
given by \( \{\sigma, \sigma^x\} \) with \( \sigma \in \Omega_\Lambda, x \in \Lambda \) and \( c_\lambda^+(\sigma) = 1 \). That is, there is an edge between two states if and only if there exists a transition between them under the East dynamics. We denote the edge set by \( E_\Lambda \). Since the East process is reversible we may associate with each edge \( \{\sigma, \xi\} \in E_\Lambda \) a conductance \( c(\sigma, \xi) = c(\xi, \sigma) \), generating a weighted graph (or network) in the usual way,

\[
c(\sigma, \xi) := \pi(\sigma)K(\sigma, \xi) = \pi(\sigma)c_\lambda^+(\sigma)[p(1-\sigma_x) + q\sigma_x], \quad \text{if} \; \xi = \sigma^x, \; x \in \Lambda.
\]

Equivalently, the resistance is defined as the reciprocal of the conductance \( r(\sigma, \xi) = 1/c(\sigma, \xi) \). Note that if \( (\sigma, \xi) \notin E_\Lambda \) then the conductance and resistance are defined as zero and \(+\infty\) respectively. The definition is well posed since \( c(\sigma, \xi) = c(\xi, \sigma) \geq 0 \).

With the above notation the generator of the East process (1.2) can be expressed as

\[
\mathcal{L}_\Lambda f(\sigma) = \sum_{x \in \Lambda} \frac{c(\sigma, \sigma^x)}{\pi(\sigma)} [f(\sigma^x) - f(\sigma)].
\]

Given \( B \subset \Omega_\Lambda \) we denote by \( \tau_B \) the hitting time of the set \( B \) for the East process \( \eta(t) \):

\[
\tau_B = \inf\{t > 0 : \eta(t) \in B\},
\]

and denote by \( \tau_B^+ \) the first return time to \( B \):

\[
\tau_B^+ = \inf\{t > 0 : \eta(t) \in B, \eta(s) \neq \eta(0) \; \text{for some} \; 0 < s < t\}.
\]

We denote by \( C_{A,B} \) the capacity between two disjoint subsets \( A, B \) of \( \Omega_\Lambda \) given by (see for example [3] or (3.6) in [7]):

\[
C_{A,B} = \sum_{a \in A} \pi(a)\mathcal{R}(a)p_\Lambda^A(\tau_A^+ > \tau_B), \quad (A.1)
\]

where \( \mathcal{R}(a) = \sum_{\sigma \neq a} K(a, \sigma) \) is the holding rate of state \( a \). With slight abuse of notation we write \( C_{a,B} \) if \( a \notin B \) is a singleton. The mean hitting time of \( B \) for the East process starting from \( a \in \Omega_\Lambda \) can be expressed in the following way (see for example formula (3.22) in [7]):

\[
\mathbb{E}_a^\Lambda[\tau_B] = \frac{1}{C_{a,B}} \sum_{\sigma \notin B} \pi(\sigma)p_\Lambda^A(\tau_a < \tau_B). \quad (A.2)
\]

The capacity can also be characterized in terms of variational principles, which are useful for making estimates of \( C_{A,B} \). The following variation principle, useful for finding upper bounds on the capacity, is known as the Dirichlet principle (see (3.12) in [19] or Theorem 3.2 in [6]):

\[
C_{A,B} = \inf\{D_\Lambda(f) : f : \Omega_\Lambda \to \mathbb{R}, f|_A = 1, f|_B = 0\}, \quad (A.3)
\]

where the Dirichlet form \( D_\Lambda(f) \) is given in (1.4).

For an alternative proof of the upper bound in Theorem 2 using a capacity argument we introduce the following definitions and results which can be found in [21] and [19]. We consider the same capacity network described above, \( \mathcal{G}_\Lambda = (\Omega_\Lambda, E_\Lambda) \), only now to each edge \( \{\sigma, \eta\} \in E_\Lambda \) we associate two oriented edges \( (\sigma, \eta) \) and \( (\eta, \sigma) \) (the set of
oriented edges will be written $\tilde{E}_\Lambda$. For any real valued function $\theta$ on oriented edges we define the divergence at a point $\sigma \in \Omega_\Lambda$ by

$$\text{div} \, \theta(\sigma) = \sum_{\eta : \eta \sim \sigma} \theta(\sigma, \eta),$$

where $\eta \sim \sigma$ if and only if there exists an edge between them in $E_\Lambda$.

**Definition A.1** (Flow from $A$ to $B$). A flow from the set $A \subset \Omega_\Lambda$ to a disjoint set $B \subset \Omega_\Lambda$, is a real valued function $\theta$ on $\tilde{E}_\Lambda$ that is antisymmetric (i.e. $\theta(\sigma, \eta) = -\theta(\eta, \sigma)$) and satisfies,

$$\text{div} \, \theta(\sigma) = 0 \quad \text{if} \quad \sigma \notin A \cup B,$$

$$\text{div} \, \theta(\sigma) \geq 0 \quad \text{if} \quad \sigma \in A,$$

$$\text{div} \, \theta(\sigma) \leq 0 \quad \text{if} \quad \sigma \in B.$$

The strength of the flow is defined as $|\theta| = \sum_{a \in A} \text{div} \, \theta(a)$. A flow of strength 1 is called a unit flow.

**Definition A.2** (The energy of a flow). The energy associated with a flow $\theta$ is given by

$$E(\theta) = \sum_{e \in E_\Lambda} r(e)\theta(e)^2. \quad (A.4)$$

**Remark A.3.** The sum in $E(\theta)$ is over unoriented edges, so each edge $\{\sigma, \eta\}$ is only considered once in the definition of energy. Although $\theta$ is defined on oriented edges, it is antisymmetric and hence $\theta(e)^2$ with $e \in E_\Lambda$ is unambiguous.

With the above notation Thomson's Principle holds, which gives a variational principle for the resistance, useful for finding lower bounds on the capacity:

$$R(A, B) := \frac{1}{C_{A,B}} = \inf \{E(\theta) : \theta \text{ a unit flow from } A \text{ to } B\}, \quad (A.5)$$

and, for any finite connected graph, the above infimum is attained by a unique minimiser which we call the equilibrium flow.

**A.1 Motivation for the proof of the lower bound in Theorem 2.** We now use the above tools to justify our choice of the test function $1_A$ in Section 5.2.2. It turns out that on the mesoscopic scale, $L = d/q^\gamma$, the hitting time $T_{\text{hit}}(L)$ (see Equation (2.4)) is equivalent, up to constants, to $q$ times $R(10, B)$ where $B = \{\eta_L = 1\}$. So to estimate $T_{\text{hit}}(L)$ it is sufficient to find bounds on the capacity $C_{10,B}$. This is the content of the following lemma.

**Lemma A.4.** Suppose that $L = 1/q^\gamma$ with $\gamma \in (0, 1]$ and $q < 1/2$. Then there a universal constants $c > 0$ such that

$$\frac{qc}{C_{10,B}} \leq T_{\text{hit}}(L) \leq \frac{q}{C_{10,B}}, \quad \text{where} \quad B = \{\eta_L = 1\}. \quad (A.6)$$

**Proof.** If $B = \{\eta_L = 1\}$ then $\mathbb{E}_{10}[\tau_B] = T_{\text{hit}}(L)$. Since $q < 1/2$ there exists a positive $c := (1/2)^{1/\gamma} \leq (1 - q)^{1/q^\gamma}$. We observe that

$$cq \leq q(1 - q)^{L-1} = \pi(10) \leq \sum_{\sigma \in B} \pi(\sigma)\mathbb{P}^\Lambda_\sigma(\tau_{10} < \tau_B) \leq \pi(B^c) = q,$$
The result follows from (A.2).

We can use Lemma A.4 and the Dirichlet principle (A.3) to get lower bounds on \( T_{\text{hit}}(L) \). Indeed, for each \( f : \Omega \Lambda \to \mathbb{R} \) such that \( f(10) = 1 \) and \( f|_B = 0 \) we have

\[
T_{\text{hit}}(L) \geq \frac{cq}{C_{10,B}} \geq \frac{cq}{D_A(f)}.
\]

(A.7)

It is known that the function \( f \) that realizes the minimum in (A.3) is

\[
f(\eta) := \mathbb{P}^\Lambda_{\eta}(\tau_{\Xi 0} < \tau_B),
\]

(A.8)

and so we shall choose a test function for which it is possible to bound from above the Dirichlet form, and is in someway ‘close’ to \( \mathbb{P}^\Lambda_{\eta}(\tau_{\Xi 0} < \tau_B) \). This motivates the choice of the deterministic dynamics in Section 5.2.

**A.2 An alternative proof of the upper bound in Theorem 2.** We now give an alternative proof of the upper bound in Theorem 2 using a recursive argument, with the same inductive scheme as used for the block dynamics proof (see Section 5.1), applied to flows on the electrical network.

Firstly we recall some notation from the inductive scheme used in Section 5.1. We consider a sequence \( \{\ell_i\}_{i=1}^r \) of increasing lengths satisfying (5.1), and let \( N_{i+1} = \lceil \ell_i / r \rceil \) (see Fig. (3)).

**Proposition A.5.** Let \( L' = \ell_r \), consider the electrical network associated with \([1, L']\) and let \( R_i \) be the resistance \( R(1, B_{\ell_i}) \) where \( B_{\ell_i} := \{\eta : \eta_{\ell_i} = 0, \eta_x = 1 \text{ for } x > \ell_i \} \). Then

\[
R_{i+1} \leq 4R_i + \frac{6}{qN_{i+1}}R_i, \quad \forall \ i < r.
\]

The proof of the upper bound now follows as a corollary from this proposition together with the results on the inductive scheme contained in Section 5.1. We fix
$L \leq d/q$ and choose $r = r_0$ as defined at the end of Section 5.1. Since (recall $\ell_{r_0} \leq 2^{r_0+1}$)

$$qn_{i+1} = q[\ell_i/r_0] \leq q\ell_i + 1 \leq q\ell_{r_0} + 1 \leq 8d/c_0 + 1$$

we have $4R_i \leq (c(d) - 6)R_i/(qN_{i+1})$ for some positive constant $c(d)$ depending only on $d$. The proposition above therefore implies that

$$R_{i+1} \leq \frac{c(d)}{qn_{i+1}} R_i, \quad \forall i < r_0,$$

hence

$$R_r \leq R_1 \frac{c(d)^r r^r}{q^r \prod_{i=1}^{r-1} \ell_i}, \quad \text{where } r = r_0.$$

Comparing with (5.5) and using the arguments at the end of Section 5.1 this gives rise to

$$R(1, B_{\ell_{r_0}}) = R_{r_0} \leq q^{-c(d)} \frac{n!}{q^{n^2/2}}.$$  \hfill (A.9)

Recall that $\ell_{r_0} \geq L$. We observe from (A.1) that

$$R(1, B_{\ell}) \leq R(1, B_{\ell_{r_0}}),$$  \hfill (A.10)

since starting from 1 the East dynamics must cross $B_{\ell}$ to reach $B_{\ell_{r_0}}$. The same proof as for Lemma A.4 shows that $E_{\ell}^A[\tau_{\ell_{r_0}=0}] \leq R(1, B_{\ell})$, and by Proposition 3.2 we have $T_{\text{hit}}(L) \leq E_{\ell}^A[\tau_{\ell_{r_0}=0}]$, so the upper bound on the relaxation time in Theorem 2 follows as a consequence of the equivalence of the characteristic times in Theorem 1 together with (A.9) and (A.10).

**Proof of Proposition A.5.** Fix $i < r$, similarly to Section 5.1 we consider the interval $\Lambda_{i+1} = [1, \ell_{i+1}]$ divided into two overlapping intervals

$$\Lambda_1 := [1, \ell_i] \quad \Lambda_2 := [\ell_{i+1} - \ell_i + 1, \ell_{i+1}].$$

The intersection $\Delta := \Lambda_1 \cap \Lambda_2 = [\ell_{i+1} - \ell_i + 1, \ell_i]$ contains $N_{i+1} \geq 1$ sites by (5.1) (see Fig. 3). To reduce notation throughout the proof we fix $N := N_{i+1}$.

Let $\ell(j) = (\ell_i - N + j) \in \Delta$ for $j \in \{1, \ldots, N\}$ and define $\ell(0) := \ell_i - N$. For $0 \leq j \leq N$ let $\phi_j$ be the equilibrium unit flow from 1 to $B_{\ell(j)}$. By Thomson’s Principle and the same argument leading to (A.10) we have

$$\max_{j \in \{0, 1, \ldots, N\}} \mathcal{E}(\phi_j) = \mathcal{E}(\phi_N) = R_i.$$

Fix $j \in \{1, \ldots, N\}$. We now define $\tilde{\phi}_j$, an antisymmetric function on oriented edges, with support on edges between elements of $B_{\ell(j)}$, such that $\phi_j + \tilde{\phi}_j$ is a unit flow from 1 to the configuration $10j1 := \{\eta : \eta_{\ell(j)} = 0, \eta_x = 1, \text{for } x \neq \ell(j)\}$. The East dynamics on the first $\ell(j) - 1$ sites is not influenced by the spin on site $\ell(j)$, so the structure of the electrical network between configurations in $B_{\ell(j)}$ is identical to that on $\{\eta : \eta_x = 1 \text{ for } x \geq \ell(j)\}$ up to a factor of $p/q$ in the edge resistance (see Fig. 4). We
therefore define $\hat{\phi}_j$ by ‘reversing’ $\phi_j$ on edges which are equivalent under a projection onto the first $\ell_j - 1$ sites,

$$
\hat{\phi}_j(\sigma, \eta) := \begin{cases} 
\phi_j(\eta^{\ell_j}, \sigma^{\ell_j}) & \text{if } \sigma, \eta \in B_{\ell_j}, \\
0 & \text{otherwise}.
\end{cases}
$$

(A.11)

Recall from (1.1) that $\eta^{\ell_j}$ is the configuration $\eta$ with the spin at site $\ell_j$ flipped (in this case flipped to 1). It is straightforward to check that $\phi_j + \hat{\phi}_j$ defines a unit flow from 1 to the point 1011, we postpone the proof until the end.

We now define $\tilde{\phi}_j$ as a unit flow from 1011 to $B_{\ell_{i+1}}$. Observe that $\ell_{i+1} - \ell_j = \ell(N-j) < \ell_i$, see Fig. 3. So we define $\tilde{\phi}_j$ by keeping the vacancy at $\ell_j$ fixed and ‘shifting’ the equilibrium flow from 1 to $B_{\ell(N-j)}$ (given by $\phi_{N-j}$) onto the lattice $[\ell_j + 1, \ell_{i+1}]$, where the constraint on the site $\ell_j + 1$ is always satisfied because of the fixed vacancy. Define $C_{\ell_j} := \{ \eta : \eta^{\ell_j} = 0 \text{ and } \eta_x = 1 \text{ for } x < \ell_j \}$ then

$$
\tilde{\phi}_j(\sigma, \eta) := \begin{cases} 
\phi_{N-j}(\sigma, \eta) & \text{if } \sigma, \eta \in C_{\ell_j}, \\
0 & \text{otherwise},
\end{cases}
$$

Figure 4. The construction of the flow $\phi_1 + \hat{\phi}_1 + \tilde{\phi}_1$ in the first step ($i = 1$) of the inductive scheme used in the proof of Prop. A.5. Note $\ell_1 = 3$, $\ell_2 = 5$, $\Delta = \{3\}$ and $N = 1$, for all $r > 2$ (see (5.1)). $\phi_1$, $\hat{\phi}_1$ and $\tilde{\phi}_1$ have disjoint support. Arrows show the direction of the flow and the labels indicate which flow is non-zero on each edge. The flow $\hat{\phi}_1$ is obtained from $\phi_1$ by a projection and inversion, the ticks indicate edges with equal flow strength. $\tilde{\phi}_1$ is obtained via association with $\phi_0$ under a shift. The left and right images join on the common vertex shown by the ‘◦’.
where the shift is given by
\[ \tilde{\eta}_x = \begin{cases} \eta_{x+t(j)} & \text{if } x \leqslant t(N-j) , \\ 1 & \text{otherwise.} \end{cases} \]

**Claim A.6.** For each \( j \in \{1, \ldots, N\} \), \( \phi_j + \hat{\phi}_j + \tilde{\phi}_j \) is a unit flow from \( \mathbb{I} \) to \( B_{\ell_{i+1}} \).

In light of this claim, now define \( \Theta \) as the normalised sum of the unit flows from \( \mathbb{I} \) to \( B_{\ell_{i+1}} \) over \( j \in \{1, \ldots, N\} \);
\[
\Theta = \frac{1}{N} \sum_{j=1}^{N} (\phi_j + \hat{\phi}_j + \tilde{\phi}_j)
\]
and
\[
\Phi = \frac{1}{N} \sum_{j=1}^{N} \phi_j, \quad \hat{\Phi} = \frac{1}{N} \sum_{j=1}^{N} \hat{\phi}_j, \quad \tilde{\Phi} = \frac{1}{N} \sum_{j=1}^{N} \tilde{\phi}_j.
\]

Since \( B_{\ell_{i+1}} \cap B_{\ell_{(j)}} = \emptyset \), for \( i \neq j \), \( \{\hat{\phi}_j\}_{j=1}^{N} \) have disjoint support, also \( C_{\ell_{(i)}} \cap C_{\ell_{(j)}} = \emptyset \) for \( i \neq j \), so the same holds for \( \{\hat{\phi}_j\}_{j=1}^{N} \), therefore by iterating Lemma A.7 (3) we have
\[
\mathcal{E}(\tilde{\Phi}) = \frac{1}{N} \sum_{j} \mathcal{E}(\hat{\phi}_j) \quad \text{(and similarly for } \tilde{\phi}_j) \text{). It follows, again from Lemma A.7, that}
\]
\[
\mathcal{E}(\Theta) \leq 4 \left( \mathcal{E}(\Phi) + \mathcal{E}(\tilde{\Phi}) \right) + 2 \mathcal{E}(\tilde{\Phi})
\]
\[
\leq 4 \left( \max_j \mathcal{E}(\phi_j) + \frac{1}{N} \max_j \mathcal{E}(\hat{\phi}_j) \right) + \frac{2}{N} \max_j \mathcal{E}(\tilde{\phi}_j). \quad (A.12)
\]

Also for each \((\sigma, \eta)\) with \( \hat{\phi}_j(\sigma, \eta) > 0 \) there exists a unique edge \((\sigma^{(j)}, \eta^{(j)})\) such that \( \phi_j(\sigma^{(j)}, \eta^{(j)}) > 0 \) and \( r(\sigma, \eta) = pr(\sigma^{(j)}, \eta^{(j)})/q \) (similarly for \( \tilde{\phi}_j \)), so
\[
\max_j \mathcal{E}(\hat{\phi}_j) \leq \frac{p}{q} \max_j \mathcal{E}(\phi_j) \leq \frac{\mathcal{E}(\phi_N)}{q} = \frac{R_3}{q},
\]
\[
\max_j \mathcal{E}(\tilde{\phi}_j) \leq \frac{p}{q} \max_j \mathcal{E}(\phi_j) \leq \frac{\mathcal{E}(\phi_N)}{q} = \frac{R_3}{q}, \quad (A.12)
\]

The result now follows by combining the above bounds with (A.12) and applying Thomson’s Principle (A.5), since \( \Theta \) is a unit flow from \( \mathbb{I} \) to \( B_{\ell_{i+1}} \) (combine Claim A.6 with Lemma A.7 part (1)). \( \square \)

**Proof of Claim A.6.** Fix \( j \in \{1, \ldots, N\} \), we show that \( \theta = \phi_j + \hat{\phi}_j + \tilde{\phi}_j \) is a unit flow from \( \mathbb{I} \) to \( B_{\ell_{i+1}} \). Firstly observe that \( \phi_j, \hat{\phi}_j \) and \( \tilde{\phi}_j \) have support on three disjoint edge sets;
\[
\begin{cases}
\phi_j(\sigma, \eta) > 0 \Rightarrow (\sigma, \eta) \in E_1, \\
\hat{\phi}_j(\sigma, \eta) > 0 \Rightarrow (\sigma, \eta) \in E_2, \\
\tilde{\phi}_j(\sigma, \eta) > 0 \Rightarrow (\sigma, \eta) \in E_3,
\end{cases}
\]
where, setting $\Lambda = [1, \ell_r]$,

\[ E_1 = \{ (\sigma, \eta) \in \tilde{E}_\Lambda : \sigma_x = \eta_x = 1 \forall x > \ell(j) \}, \] and at most one of $\sigma, \eta$ have a vacancy at $\ell(j)$; 

\[ E_2 = \{ (\sigma, \eta) \in \tilde{E}_\Lambda : \sigma_x = \eta_x = 1 \forall x > \ell(j), \ \sigma_{\ell(j)} = \eta_{\ell(j)} = 0 \} \] and finally, 

\[ E_3 = \{ (\sigma, \eta) \in \tilde{E}_\Lambda : \sigma_x = \eta_x = 1 \forall x < \ell(j), \ \sigma_{\ell(j)} = \eta_{\ell(j)} = 0 \}. \]

$\text{div} \theta(1) = 1$ since there exists only a single edge connected to the state $1$, and this edge belongs to $E_1$, then since $\phi_j$ is a unit flow from $\{1\}$ we must have $\text{div} \phi_j(1) = 1$.

We now check that $\text{div} \theta(\sigma) = 0$ for $\sigma \in B^c_{i+1} \setminus \{1\}$. If $\sigma \in \{ \eta : \eta_x = 1 \forall x > \ell(j) \}$, then $\text{div} \theta(\sigma) = \text{div} \phi_j(\sigma) = 0$. Now fix $\sigma \in B^c_{\ell(j)} \setminus \{10j\}$, so that $\sigma_{\ell(j)} = 0, \sigma_x = 1$ for $x > \ell(j)$ and $\sigma_y = 0$ for some $y < \ell(j)$, then $\theta(\sigma, \sigma^x) > 0$ implies $(\sigma, \sigma^x) \in E_1 \cup E_2$. In particular $\theta(\sigma, \sigma^x) > 0$ implies $x \leq \ell(j)$, so

\[
\text{div} \theta(\sigma) = \sum_{x \in \ell(j), \sigma_{x-1} = 0} \theta(\sigma, \sigma^x) - \sum_{x < \ell(j), \sigma_{x-1} = 0} \phi_j(\sigma, \sigma^x) = -\phi_j(\sigma^x, \sigma) I_{\{ \ell(j) = 0 \}}(\sigma) - \sum_{x < \ell(j), \sigma_{x-1} = 0} \phi_j(\sigma^x, \sigma) I_{\{ \ell(j) = 0 \}}(\sigma) = -\text{div} \phi_j(\sigma^x) = 0.
\]

Finally it is simple to check directly that the divergence on the configuration $10j$ is zero since there are only two configurations which are reachable from here under the East dynamics, by flipping the spin on site 1 or on site $\ell(j) + 1$

\[
\text{div} \Theta(10j) = \text{div} \phi_j(10j, 10j1^{\ell(j)+1}) = \phi_{N-j}(1, 1^1) - \phi_j(1, 1^1) = 1 - 1 = 0.
\]

The remaining relevant configurations are given by $\{ \eta : \eta_x = 1 \text{ for } x < \ell(j), \eta_{\ell(j)} = 0 \}$, but on this set the flow is simply given by the unit flow from 1 to $\{ \eta : \eta_{\ell(j)} = 0 \}$ on the lattice $[\ell(j) + 1, \ell_{i+1}]$ with a zero boundary condition at $\ell(j)$ and therefore zero divergence is inherited from $\phi_{N-j}$. Non-positive divergence on $B^c_{i+1}$ is also inherited from $\phi_{N-j}$.

\[ \square \]

**Lemma A.7.** The following three results are used in the proof of the upper bound using flows:

1. If $\{ \theta_i \}_{i=1}^N$ are unit flows from $A$ to $B_i$, then $\frac{1}{N} \sum_{i=1}^N \theta_i$ is a unit flow from $A$ to $\bigcup_i B_i$ and

\[ \mathcal{E} \left( \frac{1}{N} \sum_{i=1}^N \theta_i \right) \leq \max_{i \in \{1, \ldots, N\}} \mathcal{E}(\theta_i). \] (A.13)

2. For two flows $\theta_1$ and $\theta_2$,

\[ \mathcal{E}(\theta_1 + \theta_2) \leq 2(\mathcal{E}(\theta_1) + \mathcal{E}(\theta_2)). \] (A.14)

3. Suppose $\Theta = \theta_1 + \theta_2$ is a flow from $A$ to $B$ and $\theta_1(e) \neq 0$ implies $\theta_2(e) = 0$. Then

\[ \mathcal{E}(\Theta) = \mathcal{E}(\theta_1) + \mathcal{E}(\theta_2). \] (A.15)
Proof. Let $\Theta(x, y) := \frac{1}{N} \sum_{i=1}^{N} \theta_i(x, y)$, since each $\theta_i$ is antisymmetric and a linear combination of antisymmetric functions is antisymmetric so is $\Theta$. Zero divergence on $(A \cup B)^c$, non-negative divergence on $A$ and non-positive on $B$, and unit strength all follow from linearity of the divergence. So $\Theta$ is a unit flow from $A$ to $\bigcup_i B_i$. Inequality (A.13) and (A.14) both follow from simple applications of the Cauchy-Schwarz inequality.

Part (3) is immediate from the definition of the energy, by decomposing the sum in (A.4) over two non-intersecting sets, one on which $\theta_1$ is non-zero and another on which $\theta_2$ is non-zero. □

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