Open-field $\Delta$-ambulation as a selection tool for bidirectional responses in maze learning in *Mus musculus* L.

S. BÉATRICE M. EWALDS-KVIST and RITVA-KAJSA SELANDER
Åbo Akademi University, Turku, Finland

and

MÄRTEN O. R. KVIST
University of Turku, Turku, Finland

This paper presents the results of a bidirectional selective breeding experiment involving 1,287 mice. It was conducted by means of $\Delta$-ambulation—that is, by summing positive and negative learning-associated alterations in open-field ambulation over a 5-day period of training. $\Delta$-ambulation remained constant, but a selection response was found in maze running times and error scores over generations and sexes in the two diverging, intralinearly homogenous, strains of mice.

In this paper, we report the first bidirectional selective breeding experiment by means of $\Delta$-ambulation (i.e., the summed average day-to-day acquisition-associated positive and negative alterations in open-field [OF] ambulation) conducted and administered on two lines of mice. This experiment served to illuminate the complex relationship between OF activity and spatial learning. Previously, the acquisition of a new stimulating task has been thought to be positively reflected in enhanced, measurable, overt movements in phylogenetically low organisms, such as rodents (K. Y. H. Lagerspetz, Tirri, & K. M. J. Lagerspetz, 1968). Thus, only increased motor activation pertaining to learning was, as a rule, reported. For example, Mitani, Ando, and Nagata (1972) trained white rats on a food-reinforced runway. The experienced rats enhanced their activity level in a running wheel relative to their untrained counterparts. Furthermore, Milkovic, Paunovic, and Joffe (1976) observed that OF activity was increased by prior avoidance conditioning. The possibility that a new acquisition experience modifies the motor activity bidirectionally was touched on in an experiment concerning the impact of familiarity with the environment when interindividual variations were noted in learning-induced ambulation (Kvist, 1983; K. Y. H. Lagerspetz, Kvist, & K. M. J. Lagerspetz, 1980). This notion was further supported by an OF-ambulation experiment conducted in conjunction with maze learning and passive-avoidance conditioning on outbred Swiss albino and NMRI mice and on inbred Balb/c, C3H/He, C57BL/6J, and DBA/2N animals. The outbred Swiss albino and NMRI mice reacted similarly to the inbred Balb/c animals, and hybrids of these strains reacted in the form of a positive OF activity response as opposed to that of, for example, C57BL/6J, which exhibited a negative learning-related motor discharge (Kvist, 1984). The training-modified motor responses of the hybrids (Swiss albino × NMRI; Swiss albino × Balb/c) suggested that there was a genetic basis for changing one's motor activity in relation to the mastering of a new task.

It is important in this context to give an account of a few classical experiments on rodents concerning OF activity and maze learning. First, Tuttle and Dykshorn (1929) combined learning with motor activity and discovered a strong positive relationship between revolving-cage activity and improved spatial learning in a circular maze in rats. Tryon (1940/1967) then successfully established a two-way selection for brightness and dullness with regard to T-maze learning in rats. DeFries, Wilson, and McClearn (1970) selected from hybrids of inbred (Balb/cJ × C57BL/6J) lines of mice for high and low OF activity. Nevertheless, Streng (1974) related mice selected for high and low OF activity to wheel-turn avoidance conditioning and the mastering of a Lashley III maze, and this study did not lend support to there being a simple correlation between learning and OF activity. Kvist (1985) systematically studied increased OF ambulation after several types of learning. Kvist's series of experiments gave the impetus to establish a unidirectionally selectively bred line for maze-learning-related increased OF ambulation (Kvist & Selander, 1990). Generation 6 of the selection was found to be superior in maze learning and in exhibiting an increased posttraining OF ambulation, relative to that of the unselected Swiss albino control mice.

By focusing on the relationship between maze learning and OF ambulation, the present study recognized the reciprocity, or interaction, between the two elements continuously determining each other throughout the experi...
mentation. The logical conclusion was that if one of two cooperating factors—learning or OF ambulation—remained stable over more than 10 generations, the expression of a selection response would be expected in the other. The aim of the present work was to verify this hypothesis.

METHOD

Subjects

A bidirectional selective breeding experiment on maze-learning-modified OF ambulation was initiated in July of 1988. The selected 12 generations are all descendants of a Swiss albino stock, which was normally distributed (N) with regard to OF ambulation. The outbred N stock originated from Malmö, Sweden (K. M. J. Lager- spetz, 1964). The two selected lines were named Increase Open Field Turku (10FT) and Decrease Open Field Turku (DOFT). Altogether, 1,287 mice were used. The parental generation (P) comprised 23 N females with an initial ambulatory activity score of \( M = 25.5 \) (SD = 13.5); for the 25 N males, the score was \( M = 35.1 \) (SD = 16.0). 10FT was composed of 331 females and 326 males, and DOFT was composed of 292 females and 310 males. All mice were bred and reared in the laboratory of the Department of Psychology at Åbo Akademi University. The animals were weaned at the age of 4 weeks before they reached sexual maturity. The mice participated in the experiment from the age of approximately 4 months when they were weighed and introduced to both the OF device and the maze device. On average, 10FT females weighed 25.1 g (SD = 0.6), and 10FT males weighed 31.9 g (SD = 0.9); DOFT females weighed 25.5 g (SD = 0.6), and males weighed 32.0 g (SD = 1.1). At the age of approximately 4.5 months, the animals were mated within lines. Average \( \Delta \)-ambulation, number of successful matings, and litter sizes are presented in Table 1.

Housing Conditions

The mice were individually housed on the day before the beginning of the experiment. The wire-topped laboratory aluminum cages measured 12.0 x 15.5 x 15.5 cm and were equipped with a sawdust bedding unchanged during the period of experimentation. The mice were maintained in an air-conditioned noiseless breeding room on a 12:12-h light:dark cycle, with artificial lights on at 7:00 a.m. The room temperature was approximately 22°C, and the humidity was 45%. Standard laboratory animal food pellets (R3, Lactamin, Sweden) and tap water were available ad lib. During maze learning, pellets were diurnally restricted to 3 g per mouse (i.e., approximately 10% of the animal’s body weight; Kvist, 1985, p. 30) in the home cage. The test recordings were performed by the same experimenter from 7:00 to 10:00 a.m. or 5:00 to 8:00 p.m. for each generation in an adjacent experimental room under conditions identical to those of the breeding room.

Apparatus

The OF consisted of a circular, flat, white, wooden arena (40 cm in diameter) with a 20-cm-high wall of flat, white iron plating. The field was marked with thin black lines to delineate three concentric circles, which were in turn divided by 12 lines radiating from the center. The floor was thereby subdivided into a total of 19 partitions (Figure 1). The track of the animal was marked on an identically divided map to provide raw scores for calculation of ambulation or wall-seeking behavior (Kvist & Selander, 1992a, 1992b). The arena was cleaned with a wet paper towel and dried with another paper towel between successive recordings, which is considered an adequate

| Selection | Number of Females | Number of Males | \( \Delta \)-Ambulation Female | \( \Delta \)-Ambulation Male | Successful Matings (%) | Litter Size |
|-----------|------------------|----------------|-----------------------------|-----------------------------|-----------------------|------------|
| P         | 10               | 6              | -12.3                       | -13.6                       | 82                    | 7.1        |
| S1        | 10               | 10             | -5.8                        | -2.5                        | 90                    | 7.6        |
| S2        | 10               | 10             | -5.3                        | -6.7                        | 70                    | 8.1        |
| S3        | 10               | 10             | -12.5                       | -13.5                       | 80                    | 7.5        |
| S4        | 10               | 10             | -14.5                       | -9.6                        | 70                    | 7.4        |
| S5        | 10               | 10             | -8.0                        | -8.6                        | 100                   | 7.5        |
| S6        | 10               | 10             | -6.8                        | -5.6                        | 90                    | 7.0        |
| S7        | 10               | 10             | -10.6                       | -9.4                        | 100                   | 6.4        |
| S8        | 8                | 8              | -8.7                        | -9.4                        | 100                   | 6.7        |
| S9        | 8                | 8              | -8.2                        | -9.5                        | 25                    | 0.8        |
| S10       | 4                | 1              | -3.4                        | -3.5                        | 100                   | 6.0        |
| S11       | 8                | 8              | -3.4                        | -3.5                        | 88                    | 4.6        |
Figure 1. Circular open field subdivided into a total of 19 partitions. Starting point (S) of the mouse and position of the experimenter (E) are depicted.

Figure 2. A linear 11-point uncovered maze made of galvanized iron plating (157 × 22 × 18 cm). The path of the maze was manually blocked with a cardboard gate (8 × 0.2 × 18 cm) in order to prevent the mouse from retracing its track.
prone the mouse was to remain in the inner OF area (Kvist & Selander, 1992a, 1992b).

**Maze learning.** The mice ran the maze once a day for 5 successive days. The running times (in seconds) and error scores (i.e., the sum of entrances to blind alleys) were recorded from the entrance gate to the goal box where standard laboratory food pellets were available ad lib for approximately 5 min. The maze path was blocked with a cardboard gate after each visit into a blind alley to prevent the animal from retracing its track. After training, the mouse was transferred to a glass container (3 l), where the animal was allowed access to an unlimited food supply for 20 min (Figure 2).

To sum up, the daily testing of each mouse was as follows: 2 min OF ambulation → maze trial → 5 min reward in the goal box → 20 min unlimited food supply in a glass container → 2 min OF ambulation. Each of these events followed in succession.

**Figure 3.** Linear regression curves for Δ-ambulation of IOFT and DOFT of both sexes. The levels of significance (p) of the regression coefficients are presented, as are the values of intercept (a) and slope (b).
**Table 2**

| Female  | Male  | Day | F     | p   | F     | p   |
|---------|-------|-----|-------|-----|-------|-----|
| Running Time |       |     |       |     |       |     |
| 1       | 7.38  | 6.34| .000  | 0.00| .000  | 0.00|
| 2       | 2.77  | 5.38| .002  | 0.00| .000  | 0.00|
| 3       | 4.64  | 4.39| .000  | 0.00| .000  | 0.00|
| Error Score |       |     |       |     |       |     |
| 1       | 4.68  | 3.68| .000  | 0.00| .000  | 0.00|
| 2       | 4.75  | 5.38| .000  | 0.00| .000  | 0.00|
| 3       | 11.62 | 5.44| .000  | 0.00| .000  | 0.00|
| 4       | 5.68  | 4.92| .000  | 0.00| .000  | 0.00|
| Ambulation Before Maze Learning |       |     |       |     |       |     |
| 1       | 5.73  | 4.45| .000  | 0.00| .000  | 0.00|
| 2       | 3.42  | 5.00| .000  | 0.00| .000  | 0.00|
| 3       | 3.25  | 3.83| .000  | 0.00| .000  | 0.00|
| 4       | 2.43  | 3.35| .000  | 0.00| .000  | 0.00|
| 5       | 5.68  | 4.92| .000  | 0.00| .000  | 0.00|
| Ambulation After Maze Learning |       |     |       |     |       |     |
| 1       | 4.48  | 5.21| .000  | 0.00| .000  | 0.00|
| 2       | 2.17  | 2.50| .000  | 0.00| .005  | 0.00|
| 3       | 3.72  | 3.47| .000  | 0.00| .000  | 0.00|
| 4       | 2.53  | 3.62| .000  | 0.00| .000  | 0.00|
| Thigmotaxis Before Maze Learning |       |     |       |     |       |     |
| 1       | 3.12  | 3.86| .001  | 0.00| .000  | 0.00|
| 3       | 3.25  | 3.02| .001  | 0.00| .000  | 0.00|
| 5       | 1.97  | 3.02| .004  | 0.00| .000  | 0.00|
| Thigmotaxis After Maze Learning |       |     |       |     |       |     |
| 4       | 2.07  | 3.32| .033  | 0.00| .000  | 0.00|
| 5       | 2.30  | 3.32| .001  | 0.00| .000  | 0.00|

Note—Females, n = 331; males, n = 326.

**Statistics.** Analyses of variance (ANOVAs) and t tests were computed by means of BMDP7D (1990, Statistical Software, Inc.). Regression analyses were computed by means of Wistat (1990).

**RESULTS**

**Accomplished Breeding**

The results of the IOFT and DOFT animals of both sexes (selected for continuation on the basis of their most positive or negative ∆-ambulation scores) of the two lines are shown in Table 1. Furthermore, Table 1 indicates that both selected lines displayed a normal average litter size (Kvist, Selander, & Viemerö, 1995): IOFT gave birth to 6.92 pups (SD = 1.36), and DOFT gave birth to 6.33 pups (SD = 2.07), with an acceptable level of successful matings with the exception of selection 9 DOFT animals.

**Quantitative Open-Field Motor Activity**

Delta ambulation linear regression curves in association with the maze learning of both sexes of the IOFT and DOFT lines are depicted in Figure 3. The regression coefficients of the slopes comprising S1 to S12 generations are nonsignificant—that is, the ∆-ambulation neither increased nor decreased over selections. However, for the males, the average ∆-ambulation of IOFT was significantly (p < .0005) variant from that of DOFT. The results of the learning-related ambulation were analyzed in detail between each of the 5 experimental days, although the mice were selected on the basis of their average summed difference or ∆-ambulation as measured before and after learning (Table 1). The significant results of the daily difference between generations computed by means of an ANOVA are presented in Tables 2 and 3. As a general rule, significant daily differences were found with regard to ambulation before and after maze learning between the 12 selections. The IOFT females were the exceptions rather than the rule: Regardless of generation, they displayed a similar pattern of ambulation after maze learning on the 3rd day of experimentation (Table 2). With regard to DOFT animals (Table 3), the females diverged between selections before learning on Experimental Days 2 to 5 and after learning on the 1st day. On the other
Table 4

|            | S1       |            | S6       |            | S12      |            |
|------------|----------|------------|----------|------------|----------|------------|
|            | Female   | Male       | Female   | Male       | Female   | Male       |
| Day        | Avg. SE  | Avg. SE    | Avg. SE  | Avg. SE    | Avg. SE  | Avg. SE    |
| Running    |          |            |          |            |          |            |
| Time       |          |            |          |            |          |            |
| 1          | 66.5 3.4 | 66.1 4.1   | 51.2 1.8 | 49.7 1.8   | 56.9 2.7 | 53.0 2.4   |
| 2          | 48.3 4.0 | 49.5 2.8   | 43.5 1.2 | 41.3 1.3   | 43.6 2.0 | 42.8 1.9   |
| 3          | 37.8 3.4 | 38.9 2.3   | 35.5 1.3 | 35.6 1.6   | 38.6 2.0 | 38.3 1.1   |
| 4          | 33.6 2.7 | 33.1 2.0   | 34.1 1.4 | 31.5 1.5   | 39.1 1.6 | 37.2 1.3   |
| 5          | 28.3 1.7 | 28.2 1.9   | 28.1 1.4 | 25.0 1.2   | 34.8 1.9 | 32.5 1.2   |
| Error      |          |            |          |            |          |            |
| Score      |          |            |          |            |          |            |
| 1          | 3.5 0.3  | 3.9 0.4    | 6.6 0.5  | 5.4 0.4    | 6.5 0.5  | 6.3 0.5    |
| 2          | 3.2 0.4  | 3.1 0.3    | 5.5 0.4  | 5.2 0.4    | 5.5 0.6  | 5.4 0.4    |
| 3          | 2.4 0.3  | 2.7 0.4    | 4.5 0.3  | 4.0 0.3    | 5.3 0.4  | 5.0 0.3    |
| 4          | 2.5 0.4  | 2.2 0.2    | 3.7 0.3  | 3.5 0.3    | 6.6 0.4  | 5.3 0.4    |
| 5          | 2.1 0.3  | 1.6 0.2    | 2.7 0.2  | 2.5 0.2    | 4.8 0.4  | 3.3 0.3    |
| Ambulation |          |            |          |            |          |            |
| Before     |          |            |          |            |          |            |
| Maze      | 1        | 13.1 1.6   | 12.6 1.4 | 18.4 2.0   | 12.7 1.4 | 20.1 2.5   | 22.3 2.8   |
| Learning   | 2        | 11.8 1.8   | 11.8 1.9 | 9.0 1.3    | 11.0 2.1 | 11.6 1.4   | 14.7 2.4   |
| 3          | 12.4 1.6 | 13.4 1.8   | 10.5 1.7 | 10.8 1.8   | 14.8 1.8 | 11.3 1.7   |
| 4          | 11.6 1.3 | 14.2 2.1   | 13.4 2.0 | 14.5 2.4   | 10.7 1.2 | 11.7 1.5   |
| 5          | 13.2 1.9 | 12.2 2.1   | 17.8 2.3 | 17.7 2.2   | 11.7 1.8 | 14.0 1.5   |
| After      |          |            |          |            |          |            |
| Maze      | 1        | 18.5 2.0   | 20.5 2.1 | 19.1 2.5   | 17.6 2.0 | 13.0 2.3   | 16.8 2.8   |
| Learning   | 2        | 13.6 1.9   | 13.3 1.8 | 13.1 1.3   | 13.6 1.7 | 13.1 2.6   | 13.7 2.4   |
| 3          | 13.1 1.4 | 13.6 1.6   | 15.3 2.4 | 17.6 1.9   | 15.0 2.9 | 15.2 1.6   |
| 4          | 12.5 1.2 | 16.1 1.7   | 18.8 2.2 | 18.1 2.2   | 15.5 2.4 | 17.9 2.0   |
| 5          | 13.4 1.6 | 14.3 1.5   | 19.5 2.3 | 21.5 2.2   | 15.7 2.6 | 17.4 1.4   |
| Thigmotaxis|          |            |          |            |          |            |
| Before     |          |            |          |            |          |            |
| Maze      | 1        | .36 .05    | .38 .04  | .26 .04    | .32 .04  | .39 .04    | .33 .05    |
| Learning   | 2        | .19 .03    | .23 .04  | .29 .05    | .23 .04  | .21 .03    | .31 .03    |
| 3          | .18 .03  | .23 .05    | .25 .03  | .28 .04    | .29 .05  | .31 .04    |
| 4          | .24 .03  | .20 .03    | .27 .05  | .29 .04    | .32 .06  | .32 .05    |
| 5          | .27 .04  | .35 .05    | .29 .03  | .26 .03    | .34 .04  | .29 .03    |
| After      |          |            |          |            |          |            |
| Maze      | 1        | .23 .04    | .25 .04  | .27 .04    | .27 .04  | .36 .05    | .38 .03    |
| Learning   | 2        | .26 .03    | .26 .03  | .24 .03    | .27 .04  | .42 .06    | .35 .03    |
| 3          | .30 .04  | .24 .03    | .28 .04  | .30 .04    | .43 .06  | .26 .04    |
| 4          | .34 .04  | .32 .04    | .32 .04  | .36 .04    | .30 .04  | .34 .03    |
| 5          | .44 .04  | .45 .05    | .39 .05  | .39 .04    | .33 .04  | .32 .03    |

Note—S1 females, n = 28; S1 males, n = 26. S6 females, n = 25; S6 males, n = 31. S12 females, n = 16; S12 males, n = 24.

hand, DOFT males always conformed to the rule and differed between the 12 selections in their learning-related ambulation.

**Qualitative Open-Field Motor Activity**

Wall-seeking behavior, or thigmotaxis, exhibited by IOFT and DOFT animals before and after maze learning was analyzed by means of an ANOVA for each of the 5 experimental days (see Tables 2, 3, 4, and 5). Before the learning session, the IOFT females differed between generations on Days 1, 3, and 5, in contrast to the IOFT males, who diverged only the 1st day of experimentation. After maze learning, the IOFT females varied on the last day, but the IOFT males varied on Days 4 and 5 (Table 2). With regard to DOFT animals, the females differed before learning between selections on the 1st and 2nd days and after maze training on the 1st day. The DOFT males varied between selections before learning on Days 1, 3, 4, and 5, as well as after maze training on the 1st and the last day (Tables 2, 3, 4, and 5). Thus, the wall-seeking behavior displayed by lines and sexes in conjunction with maze learning did not conform to any general rule.

**Maze Learning**

The change of behavior during maze learning exhibited by both sexes of the IOFT and DOFT lines from S1 to S12 was recorded in the forms of running times and error scores per generation. Linear regression curves for these two measures of maze learning were computed for the 1st and the last day of training, which yielded a dif-
Table 5

| Table 5: Daily Average Maze-Learning and Open-Field Recordings of Behavior Displayed by DOFT Mice of Selections S1, S6, and S12 |
|-----------------------------------------------|---------------|---------------|---------------|---------------|---------------|---------------|---------------|---------------|---------------|
|                                              | Female          | Male           | Female          | Male           | Female          | Male           | Female          | Male           |
| Day                                           | Avg. | SE  | Avg. | SE  | Avg. | SE  | Avg. | SE  | Avg. | SE  | Avg. | SE  |
| Running Time                                  |      |     |      |     |      |     |      |     |      |     |      |     |
| 1                                             | 69.6 | 3.7 | 81.9 | 2.5 | 59.8 | 1.7 | 58.8 | 1.4 | 43.6 | 1.2 | 41.7 | 1.9 |
| 2                                             | 48.6 | 4.3 | 62.6 | 4.0 | 48.6 | 1.6 | 51.0 | 1.6 | 36.7 | 1.7 | 37.1 | 1.6 |
| 3                                             | 37.9 | 3.4 | 55.7 | 4.3 | 42.0 | 1.9 | 43.4 | 1.4 | 32.2 | 1.7 | 31.7 | 1.5 |
| 4                                             | 31.6 | 2.7 | 44.9 | 3.8 | 37.0 | 2.4 | 37.1 | 1.4 | 32.1 | 2.1 | 30.7 | 1.1 |
| 5                                             | 28.0 | 2.1 | 35.7 | 2.5 | 31.5 | 1.5 | 31.9 | 1.3 | 31.8 | 2.0 | 29.3 | 1.4 |
| Error Score                                   |      |     |      |     |      |     |      |     |      |     |      |     |
| 1                                             | 5.1  | 0.5 | 5.2  | 0.4 | 5.7  | 0.4 | 5.7  | 0.3 | 4.8  | 0.3 | 5.1  | 0.3 |
| 2                                             | 3.6  | 0.4 | 3.4  | 0.3 | 5.1  | 0.3 | 4.8  | 0.3 | 4.0  | 0.4 | 4.3  | 0.4 |
| 3                                             | 3.2  | 0.4 | 3.2  | 0.3 | 4.7  | 0.3 | 4.8  | 0.2 | 4.1  | 0.4 | 3.1  | 0.4 |
| 4                                             | 3.1  | 0.4 | 2.7  | 0.3 | 4.3  | 0.4 | 4.2  | 0.2 | 3.7  | 0.4 | 3.7  | 0.3 |
| 5                                             | 3.0  | 0.4 | 2.4  | 0.3 | 3.7  | 0.3 | 3.9  | 0.3 | 3.9  | 0.4 | 3.1  | 0.4 |
| Ambulation Before Maze Learning                |      |     |      |     |      |     |      |     |      |     |      |     |
| 1                                             | 21.6 | 3.1 | 13.5 | 1.9 | 22.0 | 2.7 | 20.6 | 1.6 | 28.8 | 3.6 | 36.7 | 4.3 |
| 2                                             | 18.4 | 2.2 | 14.2 | 2.1 | 13.0 | 1.4 | 12.7 | 1.4 | 11.2 | 1.8 | 29.6 | 4.3 |
| 3                                             | 12.5 | 1.6 | 10.6 | 1.7 | 11.4 | 1.5 | 11.8 | 1.2 | 17.6 | 2.9 | 29.3 | 4.6 |
| 4                                             | 13.3 | 1.7 | 11.3 | 1.6 | 13.0 | 1.6 | 15.8 | 2.0 | 21.8 | 4.1 | 28.9 | 3.8 |
| 5                                             | 12.0 | 1.5 | 11.6 | 1.1 | 17.7 | 2.2 | 21.5 | 2.6 | 19.7 | 2.6 | 20.6 | 3.4 |
| Ambulation After Maze Learning                 |      |     |      |     |      |     |      |     |      |     |      |     |
| 1                                             | 20.9 | 1.7 | 17.6 | 2.0 | 14.3 | 1.6 | 17.3 | 1.7 | 14.0 | 2.3 | 28.4 | 4.5 |
| 2                                             | 13.7 | 1.9 | 13.0 | 1.7 | 10.7 | 1.4 | 12.3 | 1.2 | 10.2 | 2.9 | 19.3 | 4.1 |
| 3                                             | 13.2 | 1.7 | 11.1 | 1.7 | 12.7 | 1.6 | 15.8 | 1.7 | 12.5 | 2.4 | 23.6 | 4.2 |
| 4                                             | 12.5 | 1.5 | 12.9 | 1.2 | 14.4 | 1.7 | 15.7 | 1.5 | 12.5 | 2.6 | 21.1 | 3.9 |
| 5                                             | 12.4 | 1.4 | 12.5 | 1.4 | 17.5 | 2.1 | 20.9 | 2.6 | 16.7 | 2.6 | 18.8 | 3.1 |
| Thigmotaxis Before Maze Learning               |      |     |      |     |      |     |      |     |      |     |      |     |
| 1                                             | .26  | .03 | .34  | .04 | .29  | .04 | .42  | .04 | .22  | .03 | .28  | .03 |
| 2                                             | .20  | .03 | .20  | .03 | .29  | .04 | .30  | .04 | .22  | .05 | .25  | .03 |
| 3                                             | .22  | .03 | .22  | .04 | .31  | .04 | .34  | .04 | .33  | .05 | .27  | .04 |
| 4                                             | .21  | .03 | .26  | .04 | .31  | .04 | .33  | .04 | .26  | .04 | .23  | .05 |
| 5                                             | .24  | .03 | .29  | .03 | .33  | .05 | .41  | .04 | .23  | .03 | .31  | .04 |
| Thigmotaxis After Maze Learning                |      |     |      |     |      |     |      |     |      |     |      |     |
| 1                                             | .24  | .04 | .33  | .04 | .29  | .03 | .34  | .04 | .29  | .05 | .31  | .03 |
| 2                                             | .27  | .03 | .25  | .03 | .27  | .04 | .34  | .05 | .36  | .05 | .35  | .05 |
| 3                                             | .23  | .03 | .29  | .04 | .37  | .04 | .35  | .04 | .26  | .03 | .36  | .06 |
| 4                                             | .33  | .04 | .34  | .03 | .38  | .05 | .36  | .04 | .34  | .04 | .27  | .05 |
| 5                                             | .39  | .04 | .48  | .05 | .47  | .05 | .44  | .04 | .35  | .05 | .34  | .06 |

Note—S1 females, n = 33; S1 males, n = 30; S6 females, n = 35; S6 males, n = 40. S12 females, n = 21; S12 males, n = 16.

ference between the 2 days always at the same level of significance (p < .0005; see Figures 4 and 5). The IOFT females and males ran the maze significantly faster but accumulated more error scores over generations on Day 1. On Day 5, a curve similar to that of Day 1, with regard to error scores, was displayed by the IOFT females (Figure 4). Accordingly, both DOFT females and males of S12 ran the maze faster on Day 1 than the animals of S1. Both sexes of the DOFT line, however, accumulated more error scores over generations on the last day of experimentation (Figure 5).

DISCUSSION

Daily learning-related activity increases have previously been observed after several types of learning (K. Y. H. Lagerspetz et al., 1980). However, a learning-related activity decrease was also observed in an experiment designed to examine whether this phenomenon occurs independently of the environment or results only from the stimulation of novel cues (Kvist, 1983). Furthermore, it has previously been established that the activation of motor responses per se was not enough to cause the same amount of motor activation as a learning task did (Kvist, 1985, p. 87). Also the possibility that an OF-activity increase generated by the learning process had a hereditary basis was addressed in an experiment aimed at assessing the extent to which this kind of activity enhancement could be generalized from Swiss albino to other strains of mice (Kvist, 1984). Accordingly, a unidirectional selection experiment was successfully conducted and reported (Kvist & Selander, 1990). Conse-
Figure 4. The maze-learning running times and error scores for IOFT females and males as a selection response expressed in a linear regression curve with levels of significance (p) of the regression coefficients. Values of intercept (a) and slope (b) are presented.

sequently, it remained to be proved whether this type of selection experiment could be conducted bidirectionally. The results of such a bidirectional selection are presented in this paper.

According to Ulbrich and Palmer (1996), each animal exhibits a range of individual strategies in an experimental situation every day. Until now, only day-to-day learning-related alterations in activity from small samples of rodents have been reported (Kvist, 1985; Milkovic et al., 1976; Mitani et al., 1972). However, it is possible to minimize the intraindividual variation by abandoning the day-to-day recordings in favor of aggregating data across experimental days. In general, aggregation can reduce error variance associated with the unrepresentativeness of individual stimuli, situations, and subjects. It enhances the reliability and validity while establishing the range of generality of a phenomenon by means of averaging over many measurements (Epstein, 1983). Aggregation enhances the reliability of scores in the OF test (Tachibana, 1985). The relationship between learning and quantitative motor activity—in the form of maze-learning necessitating spatial ability, as well as OF-ambulation, calling for an animal’s whole body movements—was thus investigated in a more reliable way. In other words, the present artificial selection procedure was conducted on the basis of the new measure, OF Δ-ambulation, comprising the average summed day-to-day variations in learning-related motor activity to counterbalance extreme values between experimental days. Daily nonaggregated inter- and intraanimal variations in ambulation in conjunction with learning lead to the false conclusion of there being a lack of conformity to a rule with regard to a selection response that can be translated into testable predictions about an interaction between learning and motor activity.

The range of the calculated Δ-ambulation in the huge sample of mice at hand was maintained over sex, generation, and strain. Two homogenous lines were thus established with regard to positive (IOFT) and negative (DOFT) Δ-ambulation in males. Females tended to display similar, but nonsignificant, Δ-ambulation linear regression curves; the latter outcome may at least in part be explained by their estrous cycles or metabolism (Ewalds-Kvist, Selander, & Sandnabba, 1997; Kvist & Selander, 1994). Female
mice are known to be less reliable experimental animals in research on motor activity; hence, researchers are reluctant to use them (e.g., Kvist, 1985; Kvist & Selander, 1987).

It was hypothesized that if one of the two reciprocal variables remains stable over several generations, it would be expected that a selection response would be expressed in the other parameter (cf. Strijbosch, Does, & Albers, 1990). In other words, the Δ-ambulation was stable, and the maze learning varied. A response of heredity with reference to maze running time was most obvious during the 1st experimental day, as depicted in linear regression curves, the slopes of which are all significant over sex, generation, and strain. By the completion of the experimental period (Day 5), the results of the maze running were considered to be a product of the training process per se. This response of heredity appears to be stronger in DOFT males than in those of IOFT, as depicted in the form of a steeper linear regression curve of their 1st day running time; the DOFT males, on the other hand, accumulated more error scores. This fact suggests the possibility that increased maze speed can lead to an increase in the number of error scores or to the conclusion that IOFT males are brighter than DOFT animals with regard to their spatial ability. The latter speculation has to be verified by means of several types of learning tasks (cf. K. Y. H. Lagerspetz et al., 1980).

With regard to daily qualitative OF motor activity, Kvist and Selander (1992a) previously indicated by means of factor analysis that maze-learning-related OF wall-seeking behavior loaded on two factors, which they called spontaneous and learning-related thigmotaxis; the latter type of wall seeking expresses itself first after three or four trials out of five after mastering a spatial task (Kvist & Selander, 1992b). IOFT males, as opposed to those of the DOFT line, displayed a learning-related thigmotaxis homogeneously over several generations, which supports the idea that these males are more susceptible to the effects of this type of learning. In agreement with summed daily measures of learning-related quantitative motor activity (Δ-ambulation), a corresponding day-to-day qualitative measure is unacceptable as a tool for selective breeding unless the data are aggregated and transformed into a spontaneous and a learning-related Δ-measure of thigmotaxis.

In conclusion, the following hypothesis was confirmed: If one of two cooperating elements—OF activity or learning—remains stable over generations, the expression of a selection response is to be expected in the other. Accordingly, by means of the new selection tool, Δ-ambulation,
two intralinearly homogenous strains, diverging with regard to maze learning, were successfully established. The present results strengthen the relationship between learning and activity and will contribute to the resolution of the debate on the existence of such a relationship.

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