Solitons, boundary value problems and a nonlinear method of images

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Abstract

We characterize the soliton solutions of the nonlinear Schrödinger equation on the half-line with linearizable boundary conditions. Using an extension of the solution to the whole line and the corresponding symmetries of the scattering data, we identify the properties of the discrete spectrum of the scattering problem. We show that discrete eigenvalues appear in quartets as opposed to pairs in the initial value problem, and we obtain explicit relations for the norming constants associated with symmetric eigenvalues. The apparent reflection of each soliton at the boundary of the spatial domain is due to the presence of a ‘mirror’ soliton, with equal amplitude and opposite velocity, located beyond the boundary. We then calculate the position shift of the physical solitons as a result of the nonlinear reflection. These results provide a nonlinear analogue of the method of images that is used to solve boundary value problems in electrostatics.

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(Some figures in this article are in colour only in the electronic version)

1. Introduction

One of the hallmarks of integrability of a nonlinear evolution equation (NLEE) is the existence of exact N-soliton solutions. It is well known that each soliton is associated with a discrete eigenvalue for the scattering problem for the given NLEE via the inverse scattering transform (IST). This has long been known to be true for initial value problems (IVPs) posed on an infinitely extended spatial domain (e.g., see, [1, 3]). Recent developments on the IST for initial-boundary value problems (IBVPs), however, have shown that the same statement also applies for problems posed over a semi-infinite interval [4, 6–8, 10, 16, 17]. The purpose of this work is to characterize the soliton solutions of IBVPs for integrable NLEEs.

For concreteness, we consider the nonlinear Schrödinger (NLS) equation

\[ iq_t + q_{xx} - 2|q|^2q = 0. \]  (1.1)
where as usual $\nu = -1$ and $\nu = 1$ denote respectively the focusing and defocusing cases. The IST for (1.1) on $-\infty < x < \infty$ was formulated in [19], where the soliton solutions in the focusing case were also obtained, including the well-known one-soliton solution

$$q_s(x, t) = A e^{i[V x + (A^2 - V^2) t + \phi]} \text{sech}[A(x - 2Vt - \xi)],$$

(1.2)

where $k = (V + iA)/2$ is the discrete eigenvalue. The IBVP for (1.1) on $0 < x < \infty$ with homogeneous Dirichlet or Neumann boundary conditions (BCs) at the origin was studied in [4] using the IST on the whole line and an odd or even extension of the potential, respectively. The case of homogeneous Robin BCs,

$$q_x(0, t) - \alpha q(0, t) = 0,$$

(1.3)

with $\alpha \in \mathbb{R}$, was also studied in [5, 10, 18] using a clever extension of the potential to the whole line. Recently, a new spectral method was proposed for the solution of IBVPs for integrable NLEEs [11–13]. The method applies for generic BCs. In general, the solution of the IBVP requires solving a system of coupled nonlinear ordinary differential equations involving the spectral parameter in order to eliminate the unknown boundary data. The method, however, also identifies a class of linearizable BCs. These linearizable BCs, which for the NLS equation coincide with (1.3), allow one to completely linearize the problem and to express the solution of the IBVP as effectively as for the IVP.

Importantly, in all of the above methods the relation between solitons and discrete eigenvalues that exists in the IVP is preserved in the IBVP, yielding solutions of the form (1.2). This leads to an apparent paradox, however, since (1.2) does not satisfy the BCs (1.3). A further paradox is that numerical solutions of the IBVP for (1.1) show inequivalently that solitons are reflected at the boundary. But the soliton velocity is the real part of the discrete eigenvalue, which does not change in time. As we show below, the resolution of these paradoxes is that discrete eigenvalues in the IBVP appear in quartets, as opposed to pairs in the IVP. This means that, for each soliton in the physical domain (in our case, the positive $x$-axis), a symmetric counterpart exists (i.e., on the negative $x$-axis), with equal amplitude and opposite velocity, whose presence ensures that the whole solution satisfies the BCs. The ostensible reflection of the soliton at the boundary of the physical domain (here $x = 0$) then corresponds simply to the interchanging of roles between the ‘true’ and ‘mirror’ solitons.

It is worth noting that the method to obtain soliton solutions for the IBVP on the half-line is similar in spirit to the method of images that is used to solve boundary value problems in electrostatics [15]. Here, however, unlike the case of electrostatics, the reflection experienced by the solitons comes accompanied by a corresponding position shift, which is a reminder of the nonlinear nature of the problem.

The outline of this work is the following. In section 2 we discuss the IST for (1.1) on the half-line with linearizable BCs, and we derive the symmetries of the discrete eigenvalues for the scattering problem. In section 3 we obtain the precise relations between discrete eigenvalues and norming constants. In section 4 we discuss the behavior of the solitons and we compute the shift originating from the reflection at the boundary, showing that this shift depends on the BCs. Finally, section 5 concludes with some final remarks.

2. Soliton solutions of the NLS equation on the half-line

Consider the IBVP for the NLS equation on the half-line with linearizable BCs; that is, (1.1) on $0 < x < \infty$ and $t > 0$ and with (1.3) given. When $\alpha = 0$ or $\alpha \to \infty$, the BCs reduce to the Dirichlet or the Neumann BCs: $q(x, t) = 0$ and $q_x(x, t) = 0$, respectively. It is well known that the NLS equation is the compatibility condition of the matrix Lax pair [19, 10]

$$\mu_x = i k [\sigma_3, \mu] = Q \mu, \quad \mu_t + 2i k^2 [\sigma_3, \mu] = H \mu,$$

(2.1)
where \([A, B] = AB - BA\) is the matrix commutator, and
\[
Q(x, t) = \begin{pmatrix} 0 & q(x, t) \\ r(x, t) & 0 \end{pmatrix}, \quad \sigma_3 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix},
\]
\[
H(x, t, k) = -iqQ \sigma_3 - iQ \sigma_3 - 2kQ = \begin{pmatrix} -iqr & iq_1 - 2kq \\ -irx - 2kr & iq \end{pmatrix},
\]
with \(r(x, t) = vq^*(x, t)\) and where the asterisk denotes complex conjugation. As usual, we assume that \(q(x, 0)\) is sufficiently regular and decays sufficiently fast as \(x \to \infty\) that Jost solutions and other relevant quantities are well defined.

### 2.1. IST for the NLS equation on the whole line

In sections 2.2 and 2.3 we characterize the solution of the IBVP for the NLS equation on the half-line using the IST for the problem on the whole line and an appropriate extension of the potential. Here we therefore briefly introduce the relevant quantities that will be used later. We refer the reader to [2, 3, 6, 19] for all details.

We define the Jost solutions of (2.1) as the simultaneous solutions of both parts of the Lax pair (2.1) that reduce to the identity matrix as \(x \to \pm \infty\): for all \(k \in \mathbb{R},
\[
\mu^{(1)}(x, t, k) = 1 + \int_{-\infty}^{\infty} e^{i(kx - t)\sigma_3} Q(x', t) \mu^{(1)}(x', t, k) e^{-i(kx - t)\sigma_3} \, dx',
\]
\[
\mu^{(2)}(x, t, k) = 1 - \int_{-\infty}^{\infty} e^{i(kx - t)\sigma_3} Q(x', t) \mu^{(2)}(x', t, k) e^{-i(kx - t)\sigma_3} \, dx'.
\]
We denote the columns of the eigenfunctions as \(\mu^{(m)}(x, t, k) = (\mu^{(m, L)}, \mu^{(m, R)}), m = 1, 2\). The regions of analyticity of the Jost solutions, as effected by the exponents in (2.3), are [2, 19]
\[
\mu^{(1, L)}, \mu^{(2, R)}: \quad \text{Im} \, k < 0, \quad \mu^{(1, R)}, \mu^{(2, L)}: \quad \text{Im} \, k > 0.
\]
Since \(\text{det} \, \mu^{(m)}(x, t, k) = 1\) for \(m = 1, 2\) and for all \(k \in \mathbb{R}, \mu^{(1)}(x, t, k)\) and \(\mu^{(2)}(x, t, k)\) are both fundamental solutions of (2.1). Hence, for all \(k \in \mathbb{R},\) we have the scattering relation
\[
\mu^{(1)}(x, t, k) = \mu^{(2)}(x, t, k) e^{i\theta(x, t, k)} A(k) e^{-i\theta(x, t, k)},
\]
where \(\theta(x, t, k) = kx - 2k^2 t\). The limit of (2.5) as \(x \to \infty\) yields, using (2.3), an integral representation for the scattering matrix \(A(k)\)
\[
A(k) = 1 + \int_{-\infty}^{\infty} e^{-i(kx - 2k^2 t)\sigma_3} Q(x, t) \mu^{(1)}(x, k) e^{i(kx - 2k^2 t)\sigma_3} \, dx.
\]
In turn, (2.6) can be used to establish that the elements \(a_{11}(k)\) and \(a_{22}(k)\) of \(A(k)\) can be analytically continued on \(\text{Im} \, k < 0\) and \(\text{Im} \, k > 0\), respectively. Note that with the above definitions, \(A(k)\) is independent of time.

The eigenfunctions and scattering coefficients obey the following symmetry relations:
\[
\mu^{(m, L)}(x, t, k) = \sigma_v \mu^{(m, R)}(x, t, k^*), \quad \mu^{(m, R)}(x, t, k) = v \sigma_v \mu^{(m, L)}(x, t, k^*),
\]
for \(m = 1, 2\), where
\[
\sigma_v = \begin{pmatrix} 0 & 1 \\ v & 0 \end{pmatrix},
\]
and with
\[
a_{22}(k) = a_{11}^*(k^*), \quad a_{21}(k) = va_{12}^*(k).
\]
Equations (2.7) hold for all values of $k$ for which all terms are well defined. As a result, one can write the coefficients of $A(k)$ as

$$A(k) = \begin{pmatrix} a^*(k^*) & b(k) \\ vb^*(k^*) & a(k) \end{pmatrix}. \quad (2.8)$$

Discrete eigenvalues occur when $a_{11}(k) = 0$ or $a_{22}(k) = 0$ [2]. Since in the defocusing case $\nu = 1$ with vanishing BCs at infinity there are no discrete eigenvalues [19], whenever we discuss the discrete spectrum we implicitly set $\nu = -1$. Assuming that $a_{11}(k)d_{22}(k) \neq 0 \forall k \in \mathbb{R}$, there exist a finite number of such zeros, since the scattering coefficients are sectionally analytic. We also assume such zeros are simple. Let us denote $k_j$ for $j = 1, \ldots, J$ and $\tilde{k}_j$ for $j = 1, \ldots, \tilde{J}$ the zeros of $a_{22}(k)$ and $a_{11}(k)$, respectively, where $\text{Im} k_j > 0$ and $\text{Im} \tilde{k}_j < 0$.

The asymptotic behavior of the Jost solutions implies that discrete eigenvalues occur when the decaying eigenfunctions as $x \to -\infty$ are proportional to those as $x \to \infty$. That is

$$\begin{align*}
\mu^{(1,R)}(x, t, k_j) &= b_j e^{2i\theta(x, t, k_j)} \mu^{(2,L)}(x, t, k_j), \\
\mu^{(1,L)}(x, t, \tilde{k}_j) &= \tilde{b}_j e^{-2i\theta(x, t, \tilde{k}_j)} \mu^{(2,R)}(x, t, \tilde{k}_j).
\end{align*} \quad (2.9)$$

One then obtains the following residue relations:

$$\begin{align*}
\text{Res}_{k = k_j} \left[ \frac{\mu^{(1,R)}(x, t, k)}{a_{22}} \right] &= C_j e^{2i\theta(x, t, k_j)} \mu^{(2,L)}(x, t, k), \\
\text{Res}_{k = \tilde{k}_j} \left[ \frac{\mu^{(1,L)}(x, t, k)}{a_{11}} \right] &= \tilde{C}_j e^{-2i\theta(x, t, \tilde{k}_j)} \mu^{(2,R)}(x, t, \tilde{k}_j),
\end{align*} \quad (2.10a)$$

where

$$C_j = b_j/A_{22}(k_j), \quad \tilde{C}_j = \tilde{b}_j/A_{11}(\tilde{k}_j), \quad (2.10b)$$

and the overdot denotes differentiation. As usual, $C_j$ and $\tilde{C}_j$ (or equivalently $b_j$ and $\tilde{b}_j$) are referred to as the norming constants. The symmetry relations (2.7) imply

$$\tilde{J} = J, \quad \tilde{k}_j = k_j^*, \quad \tilde{b}_j = -b_j^*, \quad \tilde{C}_j = -C_j^*. \quad (2.11)$$

To recover the potential from the scattering data one uses (2.5) to define the matrix Riemann–Hilbert problem (RHP)

$$M^+(x, t, k) - M^-(x, t, k) = M^+(x, t, k)R(x, t, k), \quad (2.12)$$

for all $k \in \mathbb{R}$, where the matrix-valued sectionally meromorphic functions $M^{\pm}(x, t, k)$ are

$$M^+(x, t, k) = \begin{pmatrix} \mu^{(2,L)}(x, t, k) & \mu^{(1,R)}(x, t, k) \\ \mu^{(1,L)}(x, t, k) & \mu^{(2,R)}(x, t, k) \end{pmatrix} / a(k), \quad (2.13)$$

the jump matrix is

$$R(x, t, k) = \begin{pmatrix} v|\rho(k)|^2 e^{2i\theta(x, t, k)} \rho^*(k) \\ -ve^{-2i\theta(x, t, k)} \rho^*(k) \end{pmatrix}, \quad (2.14)$$

and the reflection coefficient is $\rho(k) = b(k)/a(k)$ for all $k \in \mathbb{R}$. Since $\mu^{(m)}(x, t, k) = 1 + O(1/k)$ as $k \to \infty$ for $m = 1, 2$ [2], the RHP (2.12) is solved using standard Cauchy projectors, after regularizing by subtracting the pole contributions from the discrete spectrum

$$M(x, t, k) = 1 + \sum_{j=1}^{J} \left( \frac{1}{k - k_j} \text{Res}[M^+] + \frac{1}{k - k_j^*} \text{Res}[M^-] \right)$$

$$+ \frac{1}{2i\pi} \int_{-\infty}^{\infty} M^+(x, t, k') R(x, t, k') \frac{dk'}{k' - k}. \quad (2.15)$$

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The asymptotic behavior of $M^{\pm}(x, t, k)$ then yields the reconstruction formula for the potential as
\[ q(x, t) = -2i \lim_{k \to \infty} k M^{\pm}(x, t, k) \]
\[ q(x, t) = -2i \sum_{j=1}^{J} C_j \sum \mu_{11}^{(j)}(x, t, k_j) + \frac{1}{\pi} \int_{-\infty}^{\infty} e^{2i\theta(x, t, k)\rho(k)} \mu_{11}^{(2)}(x, t, k) \, dk. \] (2.16)

Hereafter we will often write the norming constants as $C_j = A_j e^{A_j \xi_j + i(\phi_j + \pi/2)}$ for $j = 1, \ldots, J$.

In the reflectionless case (i.e., $\rho(k) = 0 \forall k \in \mathbb{R}$) with $\nu = -1$, (2.15) reduces to an algebraic system. In particular, if $J = 1$, with $k_1 = (V + iA)/2$ and $C_1 = A e^{A \xi_1 + i(\phi_1 + \pi/2)}$, one recovers the one-soliton solution (1.2). In the general reflectionless case with $J > 1$, (2.15) and (2.16) yield (taking into account (2.10) and (2.13)) the pure multi-soliton solution of the NLS equation as
\[ q(x, t) = \sum_{j=1}^{J} Z_j, \] (2.17a)
where $Z = (Z_1, \ldots, Z_J)^T$ solves the algebraic system of equations
\[ (I + G)Z = c, \] (2.17b)
with $G = (G_{j, j'})$, $c = (c_1, \ldots, c_J)^T$, the superscript $T$ denotes matrix transpose and
\[ G_{j, j'} = e^{-2i\theta(x, t, k_j)C_j} \sum_{p=1}^{J} C_p e^{-2i\theta(x, t, k_p')} \frac{1}{(k_j - k_p')(k_p' - k_j)}, \quad c_j = -2i e^{2i\theta(x, t, k_j)C_j}, \] (2.17c)
for all $j, j' = 1, \ldots, J$.

2.2. Dirichlet and Neumann BCs

When homogeneous Dirichlet or Neumann BCs are given, it was shown in [4] that the IBVP for the NLS equation can be solved via the IST for the whole line using an odd or even extension of the potential. In the case of Dirichlet BCs, one introduces the odd extension of $Q(x)$ as $Q_{\text{ext}}(x) = Q(x) - Q(-x)$, where $\Theta(x)$ is the Heaviside theta function, defined as $\Theta(x) = 1$ for $x > 0$ and $\Theta(x) = 0$ for $x < 0$. Then one defines $\mu^{(1)}(x, t, k)$ and $\mu^{(2)}(x, t, k)$ through (2.3) with $Q(x)$ replaced by $Q_{\text{ext}}(x)$.

It is straightforward to see that the following symmetries hold for the Jost solutions and, consequently, for the scattering matrix: $\forall x \in \mathbb{R}$ and $\forall k \in \mathbb{R}$
\[ \mu^{(1)}(x, t, k) = \mu^{(2)}(-x, t, -k), \quad A(-k) = A^{-1}(k). \] (2.19)
In particular, $a_{11}(-k) = a_{22}(k)$. From the above symmetry and (2.7), it then follows that
\[ a^*(-k^*) = a(k) \quad \text{and} \quad b(k) = -b(-k). \] (2.20)
Recall that $J$ is the number of discrete eigenvalues in either the upper-half or lower-half complex $k$-plane. The above relations imply that the discrete spectrum has the following properties: (i) $J$ is even; (ii) the discrete eigenvalues appear in quartets, namely
\[ \{ \pm k_n, \pm k_{n+1}^* \}_{n=1}^{N}, \] (2.21)
so that the number of discrete eigenvalues in each quadrant plane is $N = J/2$. Moreover, (iii) the above symmetry in the discrete eigenvalues also induces a relation between the
corresponding norming constants, as we show next. Throughout this work, we label the
discrete eigenvalue symmetric to \( k_n \) as
\[
\tilde{k}_n = -k_n^*.
\]
We also take \( \text{Re} \, k_n \neq 0 \) for \( n = 1, \ldots, N \) to avoid singular cases. Using (2.7) and
the symmetries (2.19), we have, for \( n = 1, \ldots, N \),
\[
b_n^*b_n^* = -1, \quad C_n^*C_n^* = 1/\tilde{a}^2(k_n).
\]

The relations between the norming constants take on a particularly simple form in the
reflectionless case. In particular, for reflectionless potentials and in the case \( N = 1 \) the trace
formula yields simply \( \tilde{a}(k_1) = V/[A(A + iV)] \), where \( k_1 = (V + iA)/2 \) (see section 3 for
details). Writing \( C_n = A_n e^{A_1x + \mu (\psi_n + \pi/2)} \) for \( n = 1, \ldots, 2N \), we then obtain the following
explicit relations:
\[
\xi_1 + \xi_2 = \frac{1}{A} \log \left( 1 + \frac{A^2}{V^2} \right), \quad \varphi_2 - \varphi_1 = 2 \text{arg}(A + iV).
\]

Next, consider the IBVP for (1.1) with Neumann BCs. In this case one can use the even
extension of the potential
\[
Q^\text{ext}(x) = Q(x)\Theta(x) + Q(-x)\Theta(-x)
\]
\( \forall \, x \in \mathbb{R} \). As before, one obtains symmetry relations for the eigenfunctions and scattering data
\[
\mu^{(1)}(x, t, k) = \sigma_3 \mu^{(2)}(-x, t, -k)\sigma_3, \quad A(-k) = \sigma_3 A^0(k)\sigma_3.
\]
For the scattering coefficients we therefore have
\[
a^*(-k^*) = a(k), \quad b(k) = b(-k).
\]
Thus, (2.22) still applies. Moreover, one can again obtain relations between the discrete
eigenvalues and the norming constants
\[
b_n^*b_n^* = 1, \quad C_n^*C_n^* = -1/\tilde{a}^2(k_n),
\]
for \( n = 1, \ldots, N \). In particular, for pure soliton solutions and \( N = 1 \) it is (cf section 3)
\[
\xi_1 + \xi_2 = \frac{1}{A} \log \left( 1 + \frac{A^2}{V^2} \right), \quad \varphi_2 - \varphi_1 = 2 \text{arg}(A + iV) + \pi,
\]
where \( C_n = A_n e^{A_1x + \mu (\psi_n + \pi/2)} \) as before.

2.3. Robin BCs

It was shown in [10] that, even in the case of Robin BCs (1.3), one can still reduce the IBVP
to the solution of an IVP on the whole line. Motivated by the linear problem (see appendix),
one introduces the extension of \( Q(x) \) as
\[
Q^\text{ext}(x, t, k) = Q(x, t)\Theta(x) + F(k)Q(-x, t)\Theta(-x) \quad x \in \mathbb{R},
\]
where \( F(k) = \text{diag}(f(k), f(-k)) \), with
\[
f(k) = (2k - \alpha)/2(k + \alpha).
\]
(The factors of 2 in (2.31) are chosen for consideration of the linear limit, discussed later.)
Since \( F(k) = 1 \) when \( \alpha = 0 \), and \( F(k) \to -1 \) as \( \alpha \to \infty \), (2.30) reduces to the odd/even
extensions of the potential in the case of the IBVP with Dirichlet/Neumann BCs, (2.18)
and (2.25), respectively. More generally, the extended potential \( Q^\text{ext}(x, t, k) \) satisfies the
symmetries
\[ Q^\text{ext}(-x, t, k) = F(-k)Q^\text{ext}(x, t, k), \]  
\[ \Sigma(k)F(-k)Q^\text{ext}(x, t, k) = -Q^\text{ext}(x, t, k)\Sigma(k), \]

where \( \Sigma(k) = \text{diag}(f(k), -1) \).

Let \( \mu^{(m)}(x, t, k) \) for \( m = 1, 2 \) be the Jost solutions defined via (2.3) with \( Q(x, t) \) replaced by \( Q^\text{ext}(x, t, k) \), as before. Additional care is necessary for the case of Robin BCs compared to Dirichlet and Neumann BCs, because, for all \( \alpha \neq 0 \): (i) \( Q^\text{ext}(x, t, k) \) is discontinuous at \( x = 0 \); (ii) for all \( x < 0 \), \( Q^\text{ext}(x, t, k) \) has simple poles at \( k = \pm i\alpha/2 \) (since \( F(k) \) does). Similar issues arise in the linear case. When \( r(x, t) = vq^*(x, t) \), the compatibility of the extended Lax pair (2.1) with \( Q(x, t) \) replaced by \( Q^\text{ext}(x, t, k) \) implies that \( q^\text{ext}(x, t, k) \) solves the NLS equation for all \( x \neq 0 \), since \( f(k)f(-k) = 1 \). But a forcing term of distribution type appears in the right-hand-side of the NLS equation at \( x = 0 \) (cf [10] and appendix). As in the linear case, even though \( Q^\text{ext}(x, t, k) \) is discontinuous at \( x = 0 \), the BCs (1.3) are satisfied from the right.

From the symmetries (2.32) one obtains
\[ \mu^{(1)}(x, t, k) = \Sigma(k)\mu^{(2)}(-x, -t, -k)\Sigma(-k), \]  
\[ A(-k) = \Sigma(-k)A^{-1}(k)\Sigma(k). \]

In particular,
\[ a(k) = a^*(-k^*), \quad b(k) = f(k)b(-k). \]  

Equations (2.33) and (2.34) generalize the relations found for Dirichlet and Neumann BCs (namely (2.19), (2.26) and (2.20), (2.27), respectively.)

Regarding the analyticity of the eigenfunctions, note first that \( \mu^{(2)}(x, t, k) \) is the same as that of IVP for all \( x > 0 \), and therefore enjoys the same properties there. Using (2.33a) and definition of \( \mu^{(1)} \), one can obtain the regions of analyticity of \( \mu^{(1)}(x, t, k) \) for \( x > 0 \):

- \( \mu^{(1,L)} \) is analytic for \( \text{Im} k < 0 \), except for a simple pole at \( k = i\alpha/2 \) when \( \alpha < 0 \);
- \( \mu^{(1,R)} \) is analytic for \( \text{Im} k > 0 \), except for a simple pole at \( k = -i\alpha/2 \) when \( \alpha < 0 \).

(The analyticity properties for \( x < 0 \) can be obtained using the symmetries (2.32), (2.33) and the integral equations (2.3). These properties are not necessary for our purposes, however, since we are only interested in reconstructing the extended potential for \( x > 0 \).) The integral representation of the scattering matrix obtained from (2.5) in the limit \( x \to \infty \) and the symmetry (2.32) imply
\[ a(k) = 1 - f(k)\int_0^\infty \mu^{(2)}_{21}(-x, t, -k)r(x, t)\,dx - \int_0^\infty \mu^{(2)}_{21}(x, t, -k)r(x, t)\,dx. \]

Thus, \( a(k) \) is analytic for \( \text{Im} k > 0 \), except for a simple pole at \( k = -i\alpha/2 \) when \( \alpha < 0 \). Thus \( \mu^{(1,R)}(x, t, k)/a(k) \) in (2.12) has a removable singularity at \( k = -i\alpha/2 \). By symmetry, the same applies for \( \mu^{(1,L)}(x, t, k)/a^*(k^*) \) in the lower-half plane. Therefore, the RHP defined in section 2.1 also applies to the case of Robin BCs (1.3), and for all \( x > 0 \), the potential \( q(x, t) \) is also reconstructed in the same way.

Equation (2.34) implies that the symmetry property (2.22) of the discrete spectrum applies in the case of Robin BCs as well. Moreover, similar symmetries as before exist for the norming constants (again, cf section 3)
\[ b_n b_n^* = f(k_n), \quad C_n C_n^* = -\frac{f(k_n)}{\alpha^2(k_n)}. \]
for \( n = 1, \ldots, N \). In particular, for pure soliton solutions with \( N = 1 \), the following relations exist between the norming constants associated with symmetric eigenvalues:

\[
\bar{\xi}_1 + \bar{\xi}_2 = \frac{1}{A} \log \left( 1 + \frac{A^2}{V^2} \right) + \frac{1}{2A} \log \left[ \frac{V^2 + (A - \alpha)^2}{V^2 + (A + \alpha)^2} \right], \tag{2.37a}
\]

\[
\bar{\varphi}_2 - \varphi_1 = 2 \arg (A + iV) - \arg \left[ \frac{V + i(A - \alpha)}{V + i(A + \alpha)} \right] + \pi. \tag{2.37b}
\]

Equations (2.36) and (2.37) reduce respectively to (2.23) and (2.24) as \( \alpha \to \infty \) and to (2.28) and (2.29) as \( \alpha \to 0 \). In section 4 we discuss what (2.22) and (2.36) imply about the physical behavior of the solitons in the IBVP.

3. Relations between discrete eigenvalues and norming constants

We now derive the relations between the discrete eigenvalues and the norming constants we presented in section 2, together with their generalization for multi-soliton solutions and solutions with a nonzero reflection coefficient. We discuss explicitly the case of Robin BCs (namely (2.36) and (2.37)). The corresponding relations in the case of Dirichlet and Neumann BCs (namely, (2.23), (2.24), (2.28) and (2.29)) follow from (2.36) and (2.37) by taking the limits \( \alpha \to \infty \) and \( \alpha \to 0 \), respectively.

Recall first that the discrete eigenvalues and norming constants obey the symmetries (2.11) and (2.21). From (2.7a) and (2.33a) we have, for all \( n = 1, \ldots, N \),

\[
\mu^{(1, R)}(x, t, k_n) = b_n e^{2i \theta(x, t, k_n)} \mu^{(2, L)}(x, t, k_n), \tag{3.1a}
\]

as well as

\[
\mu^{(1, R)}(x, t, k_n) = -\bar{b}_n e^{2i \theta(-x, t, k_n)} \mu^{(1, L)}(-x, t, \bar{k}_n), \tag{3.1b}
\]

where \( k_n = -k_n^* \) as before. Also, using (2.33a) we can write

\[
\mu^{(2, L)}(x, t, k_n) = f(k_n) \mathcal{S}^{-1}(-k_n) \mu^{(1, L)}(-x, t, \bar{k}_n). \tag{3.2}
\]

Inserting (3.2) into (3.1) leads to

\[
\mathcal{S}(k_n) \mu^{(1, L)}(-x, t, \bar{k}_n) = -\bar{b}_n b_{n'} f(k_n) \mathcal{S}^{-1}(k_n) \mu^{(1, L)}(-x, t, \bar{k}_n). \tag{3.3}
\]

Since \( f(k_n) = 1/f(k_n) \) and \( f(k_n') = f^*(k_n) \), we then have \( \bar{b}_n b_{n'} = -f^*(k_n) \) for all \( n = 1, \ldots, N \), which in turn, using (2.11), yields the first of (2.36).

Now recall the definition of the norming constants (2.10) and the symmetry (2.11). Using the symmetries of the scattering coefficients (2.7b) and (2.34), we obtain \( \check{a}_{11}(k_n) = -\check{a}_{22}(-k_n) \) for all \( n = 1, \ldots, 2N \). Hence \( C_n = b_n^* \check{a}_{22}(k_n) \), and then, noting that \( \check{a}(k_n') = -\check{a}^*(k_n) \), we obtain the second of (2.36). Note also that, when \( C_j = \lambda_j e^{i \theta_j + i \phi_j + i \tau_j / 2} \), the second of (2.36) implies

\[
\xi_n + \xi_{n'} = (\log |f(k_n)| - 2 \log |\check{a}(k_n)| - 2 \log A_n)/A_n, \tag{3.4a}
\]

\[
\varphi_n - \varphi_{n'} = 2 \arg [f(k_n)] - 2 \arg [\check{a}(k_n)] + \pi. \tag{3.4b}
\]

We now derive (2.37) and its generalization to arbitrary solutions of the IBVP. It is well known that the analytic scattering coefficients obey trace formulae. Explicitly, for the NLS equation, \( a(k) = a_{22}(k) \) is given by [2]

\[
\log a(k) = \sum_{j=1}^{J} \log \left( k - k_j \right) + \frac{1}{2 \pi i} \int_{-\infty}^{\infty} \frac{\log |a(k')|^2}{k' - k} \, dk', \tag{3.5}
\]
for all \( \text{Im} \, k > 0 \). Using (3.5) in (3.4) then yields half of the norming constants in terms of the other half. In particular, for reflectionless solutions the integral in (3.5) vanishes, and (3.5) yields simply

\[
\hat{a}(k_j) = \prod_{m=1}^{J} (k_j - k_m^*) \prod_{m=1}^{J} (k_j - k_m'),
\]

(3.6)

for all \( j = 1, \ldots, J \), where the prime indicates that the term with \( m = j \) is omitted from the product. Using the symmetry of the discrete eigenvalues, (3.6) becomes

\[
\hat{a}(k_n) = \frac{k_n + k_n^*}{2k_n} \prod_{m=1}^{N} \frac{(k_n - k_m^*)(k_n + k_m^*)}{(k_n + k_m^*)(k_n - k_m^*)} 
\]

\[
= \frac{V_n}{iA_n(V_n + iA_n)} \prod_{m=1}^{N} \frac{[V_n - V_m + i(A_m - A_n)][V_n + V_m + i(A_m - A_n)]}{[V_n + V_m + i(A_m + A_n)][V_n - V_m + i(A_m + A_n)]},
\]

(3.7)

for all \( n = 1, \ldots, N \). One can now substitute (3.7) into (3.4) to obtain the generalization of (2.37) as

\[
\xi_n + \xi_n' = \frac{1}{A_n} \log \left( 1 + \frac{A_n^2}{V_n^2} \right) + \frac{1}{2A_n} \log \left[ \frac{V_n^2 + (A_n - \alpha)^2}{V_n^2 + (A_n + \alpha)^2} \right] 
\]

\[
- \frac{1}{A_n} \sum_{m=1}^{N} \log \left[ \frac{(V_n - V_m)^2 + (A_n - A_m)^2}{(V_n + V_m)^2 + (A_n + A_m)^2} \right] \left[ \frac{(V_n + V_m)^2 + (A_n + A_m)^2}{(V_n - V_m)^2 + (A_n - A_m)^2} \right]
\]

(3.8a)

\[
\varphi_n - \varphi_n' = -2 \arg (A_n + iV_n) + \arg \left[ \frac{V_n + i(A_n - \alpha)}{V_n + i(A_n + \alpha)} \right] + \pi 
\]

\[
- 2 \sum_{m=1}^{N} \arg \left[ \frac{V_n - V_m + i(A_m - A_n)}{V_n + V_m + i(A_n + A_m)} \right] \left[ \frac{V_n + V_m + i(A_n + A_m)}{V_n - V_m + i(A_n + A_m)} \right].
\]

(3.8b)

In the simplest case \( N = 1 \) there is no product in (3.7), and the relations between the norming constants become especially simple

\[
C_1 C_2^* = (\alpha - A + iV)(A - iV)^2 A^2 / [(\alpha + A - iV)V^2]
\]

(where \( k_1 = (V + iA)/2 \) as before), which, when inserted in (2.36), yields (2.37).

Note from (3.4) and (3.7) that, when \( N \geq 2 \), the norming constants of a given mirror soliton are affected by the presence of all the physical solitons. This is due to the fact that every soliton interaction produces a position and phase shift, as we discuss next.

4. Soliton behavior

We now discuss the behavior of the soliton solutions of the NLS equation on the half-line. We refer to the solitons located to the right of the boundary (i.e., at \( x > 0 \)) as the physical solitons, and to the counterparts of the physical solitons to the left of the boundary as the mirror solitons, since they can be considered as a reflected image of the physical solitons, as we will see. Equation (2.21) obviously implies that the number of physical solitons equals that of mirror solitons, and, with the above notations, this number is \( N = J/2 \).
4.1. Soliton reflection

We first discuss the case $N = 1$ for simplicity. Solving the algebraic system (2.17) one obtains the two-soliton solution of the NLS equation, and the solution of the IBVP is then obtained by choosing the norming constants of the mirror solitons as explained earlier.

Let $k_1 = (V + iA)/2$ be the discrete eigenvalue of the scattering problem corresponding to the physical soliton. Recall from (1.2) that the real part and imaginary part of the discrete eigenvalue determine, respectively, the velocity and the amplitude of the soliton. By the symmetry (2.22) of the discrete spectrum, we know that $k_2 = -k_1^* = (-V + iA)/2$ is also an eigenvalue, corresponding to the mirror soliton. Hence, the mirror soliton has the same amplitude as, and opposite velocity to, the physical soliton.

Figure 1 shows (left) the soliton reflection at the boundary in the case of Dirichlet BCs, together with a contour plot (right) that includes the mirror soliton (dashed lines). The above results imply that the soliton reflection at $x = 0$ is simply a particular case of an elastic two-soliton interaction of the NLS equation, in which the norming constant of the mirror soliton is chosen so as to make the whole solution zero at the origin. As usual in a soliton interaction, the solitons re-emerge intact after the collision, except that in our case the roles of the physical and mirror solitons are now swapped. A similar scenario occurs in the case of Neumann and Robin BCs, as shown respectively in figures 2 and 3, except that the norming constant of the mirror soliton in each case is such that the appropriate BCs are satisfied.

Note that the symmetry of the discrete spectrum and the relations between eigenvalues and norming constants apply independently of whether the physical soliton has a positive or negative velocity. In other words, they apply whether the discrete eigenvalue associated with the physical soliton is located in the first or second quadrant of the complex $k$-plane (recall $V_n = 2 \text{Re} k_n$). Of course, if the physical soliton has a positive velocity, no soliton reflection occurs for $t > 0$, and the solution is exponentially small at the origin for all $t > 0$. Nonetheless, a mirror soliton is still needed to satisfy the BCs at the origin, as shown in figure 4.

The location of the mirror soliton is the same for Dirichlet and Neumann BCs, and in those two cases only the phase difference between the solitons contributes to satisfying the BCs (cf (2.24) and (2.29)). The same is not true, however, for the more general BCs (1.3) with $\alpha \neq 0$ (cf (2.37)).

Finally, figure 5 displays the reflection of two physical solitons in the case of Dirichlet BCs, demonstrating that our results are not limited to the case $N = 1$. Similarly, figure 6 displays the reflection of a two-soliton bound state, also in the case of Dirichlet BCs. As before, when $N > 1$ one first solves the algebraic system (2.17) to obtain the $2N$-soliton solution of the NLS equation. The solution of the IBVP is then obtained by appropriately choosing the norming constants of the mirror solitons. The generalizations of (2.37) to obtain the norming constants for solutions with $N \geq 2$ and for solutions with nonzero reflection coefficients are described in section 3.

It is convenient to label the discrete eigenvalues such that $\text{Re} k_1 \leq \text{Re} k_2 \leq \cdots \leq \text{Re} k_{2N}$. With this convention, as $t \to -\infty$ all physical solitons correspond to the $N$ discrete eigenvalues in the second quadrant of the complex $k$-plane (i.e., those with $\text{Re} k_n < 0$). Then, as each soliton is reflected in succession, the corresponding discrete eigenvalue associated with the physical soliton switches role with its symmetric counterpart, until, as $t \to \infty$, all physical solitons correspond to the $N$ discrete eigenvalues in the first quadrant (i.e., with $\text{Re} k_n > 0$). Consequently, as $t \to -\infty$ the discrete eigenvalues associated with the physical solitons are $k_1, \ldots, k_N$, and the corresponding mirror solitons are given respectively by $k_{2N}, \ldots, k_{N+1}$. That is, $n' = 2N - n + 1$ for all $n = 1, \ldots, N$. Conversely, as $t \to \infty$ the eigenvalues
Figure 1. Soliton reflection at the boundary in the case of Dirichlet BCs, with $A = 2$, $V = -2$, $\xi = 5$ and $\phi = 0$. Left: three-dimensional (3D) plot of $|q(x, t)|$. Right: contour plot showing the mirror soliton (dashed) to the left of the boundary.

Figure 2. Soliton reflection at the boundary in the case of Neumann BCs, with $A = 2$, $V = -2$, $\xi = 5$ and $\phi = 0$. Left: 3D plot. Right: contour plot showing the mirror soliton.

Figure 3. Soliton reflection at the boundary in the case of Robin BCs with $\alpha = 3$, and with $A = 2$, $V = -2$, $\xi = 5$ and $\phi = 0$. Left: 3D plot. Right: contour plot showing the mirror soliton.
Figure 4. Reflection at the boundary in the case of Robin BCs and positive velocity: $\alpha = 3$, $A = 2$, $V = 1$, $\xi = 3$ and $\varphi = 0$. Left: 3D plot. Right: contour plot showing the mirror soliton. In this case the solution with Dirichlet and Neumann BCs is visually undistinguishable from the above.

Figure 5. Reflection at the boundary of two physical solitons: $A_1 = 2$, $A_2 = 3/2$, $V_1 = -3$, $V_2 = -1$, $\xi_1 = 12$, $\xi_2 = 8$ and $\varphi_1 = \varphi_2 = 0$. Left: 3D plot. Right: contour plot.

Figure 6. Reflection at the boundary of two physical solitons: $A_1 = 1$, $A_2 = 3$, $V_1 = V_2 = -1$, $\xi_1 = \xi_2 = 10$ and $\varphi_1 = \varphi_2 = 0$. Left: 3D plot. Right: contour plot.
associated with the physical solitons are $k_{N+1}, \ldots, k_{2N}$, and the corresponding mirror solitons are given respectively by $k_N, \ldots, k_1$. That is, $n' = 2N - n + 1$ for all $n = N + 1, \ldots, 2N$.

4.2. Reflection-induced shift

Recall that the soliton reflection at the boundary is effectively the interaction between the physical soliton and its mirror image. Since any soliton interaction results in a position shift, it follows that the soliton reflection at the boundary also produces such a shift. As we show next, however, a second contribution also exists to the total reflection-induced shift. In fact, depending on the soliton parameters, this second contribution can even make the total shift zero as if the whole process were purely linear.

It is well known that, as $t \to \infty$, a multi-soliton solution becomes asymptotically a linear superposition of one-soliton solutions [2, 19]. That is

$$q(x, t) \sim \sum_{j=1}^{J} q^\pm_j (x, t)$$

as $t \to \pm \infty$, where $q^\pm_j (x, t)$ is of the form (1.2), but with the soliton parameters $A, V, \xi, \phi$ replaced by $A_j, V_j, \xi_j^\pm, \phi_j^\pm$ for $j = 1, \ldots, J$. The fact that $\xi_j^\pm$ and $\phi_j^\pm$ do not coincide with each other is the manifestation of the interaction-induced shift. Define as usual the interaction-induced position shift of the $j$th soliton as

$$\delta \xi_j = \xi_j^+ - \xi_j^- = \frac{A_j \xi_j}{k_j - k_j^*} - \sum_{m=1}^{j-1} \sigma_{m,j} \log |a_{m}(k_j)|,$$

where $a_j(k) = (k - k_j)/(k - k_j^*)$ is the transmission coefficient for a one-soliton solution (cf (3.5)), $\sigma_{m,j} = -1$ for $m = 1, \ldots, j - 1$ and $\sigma_{m,j} = 1$ for $m = j + 1, \ldots, J$, and as before the sum is taken over all $m \neq j$. Comparing the asymptotic results as $t \to \pm \infty$, we then obtain the position shift for multi-soliton solutions of the NLS equation as

$$\delta \xi_j = \frac{2}{A_j} \sum_{m=1}^{j} \sigma_{m,j} \log \left| \frac{k_j - k_m}{k_j - k_m^*} \right|.$$ (4.3)

Note that the position shifts are pairwise additive. That is, $\delta \xi_j = \sum_{m=1}^{j} \delta \xi_{j,m}$, where $\delta \xi_{j,m}$ is the position shift of the $j$th soliton arising from its interaction with the $m$th soliton. In particular, if $k_n = (V_n + iA_n)/2$ with $V_n < 0$ is the eigenvalue associated with the physical soliton at $t = 0$, and $k_n' = -k_n^*$ is the mirror eigenvalue, (4.3) yields the position shift resulting from the interaction of the physical soliton with its mirror:

$$\delta \xi_{n,n'} = -\frac{1}{A_n} \log \left( 1 + \frac{A_n^2}{V_n^2} \right) = -\delta \xi_{n',n}.$$ (4.4)

Since the physical and mirror solitons interchange roles in the reflection, however, the total reflection-induced shift is not simply due to the soliton interaction. More precisely, define the reflection-induced position shift $\Delta \xi$ as the displacement of the soliton center from where
Figure 7. Left: schematic diagram of the reflection-induced shift $\Delta \xi$. The displacement from the origin of the interaction center has been exaggerated for illustration purposes. Right: a soliton reflection with a large, boundary-induced shift: $\alpha = -2$, $A = 2$, $V = -1$, $\xi = 5$ and $\psi = 0$.

it would be had it followed a purely piecewise linear path (cf figure 7). A simple calculation shows that such a position shift is given by

$$\Delta \xi_n = \xi_n - n + \xi'_n - \delta \xi_n,$$

where as before $\delta \xi_n$ the interaction-induced shift, obtained from (4.3), and the index $n'$ labels the mirror soliton of the $n$th soliton. As is evident from (4.2), the asymptotic soliton parameters $\xi_j^\pm$ and $\psi_j^+$ do not coincide with the constants $\xi_j$ and $\psi_j$ appearing in the exact $J$-soliton solution (2.17). In particular, using the symmetry of the discrete eigenvalues, after some tedious but straightforward algebra (4.2) yields simply

$$\xi_n^\pm + \xi'_n = \xi_n + \xi_n' + 2 \log |a(k_n)| = \log |f(k_n)| - 2 \log A_n$$

where (3.4) was used. The reflection-induced shift $\Delta \xi$ is then obtained inserting (4.4) and (4.6) into (4.5). In particular, for $N = 1$, it is

$$\Delta \xi = \frac{1}{A} \log \left( \frac{V^2 + (A - \alpha)^2}{V^2 + (A + \alpha)^2} \right).$$

(4.7)

Importantly, the reflection-induced shift depends on the BCs. Indeed, such a dependence is evident in figures 1, 2, 3 and 7. It should also be clear than $\Delta \xi$ can be either positive or negative depending on the soliton parameters and BCs. Note also that, if the physical soliton has a positive velocity (i.e., if $V > 0$), the reflection at the boundary and the corresponding position shift obviously occur at $t < 0$.

The above results are easily generalized to the case $N \geq 2$. Indeed, (4.6) holds for all $N$. Also, taking $n \leq N$ (i.e., $V_n < 0$), using the symmetry of the eigenvalues, (4.2) yields

$$\delta \xi_n = -\frac{1}{A_n} \log \left( 1 + \frac{A_n^2}{V_n^2} \right) + \frac{1}{A_n} \sum_{m=1}^{N} \log \left[ \frac{(V_n - V_m)^2 + (A_n - A_m)^2}{(V_n - V_m)^2 + (A_n + A_m)^2} \right]$$

$$+ \frac{1}{A_n} \sum_{m=1}^{N} \sigma_{m,n} \log \left[ \frac{(V_n + V_m)^2 + (A_n - A_m)^2}{(V_n + V_m)^2 + (A_n + A_m)^2} \right].$$

(4.8)

One can then combine (4.6) and (4.8) into (4.5) to obtain the generalization of (4.7).
Note that, when $N \geq 2$, the interaction shifts $\delta \xi_n$ compare the soliton positions before and after all interactions have occurred. Similarly, the constants $\xi_\pm$ and $\varphi_\pm$ apply for times, respectively, before and after all soliton interactions (and thus reflections) have occurred. So (4.5) applies in that limit. But equations (2.36) allow one to obtain the $N$-soliton solution of the IBVP given the $N$ discrete eigenvalues and norming constants associated with the physical solitons at any value of $t$, whichever these may be, and independently of how many reflections may already have occurred.

5. Discussion

Since many physical situations naturally give rise to IBVPs for the NLS equation, we expect that our characterization of the soliton solutions of the IBVP will have a broad range of applicability. On the technical side we note that the approach we used for the IBVP—namely, extension of the potential and use of the IST for the IVP [4, 10]—is fundamentally different from the new method for IBVPs presented in [11], which is based on the simultaneous spectral analysis of both parts of the Lax pair. We also note that the symmetries of the scattering coefficients had been derived in [4] for Dirichlet and Neumann BCs and in [10] for Robin BCs (see, also [5, 18]). None of those works, however, discussed the symmetries of the discrete spectrum, norming constants and the corresponding implications on the soliton behavior.

We should also emphasize that the symmetries of the scattering data and the discrete spectrum only apply to linearizable BCs. In fact, a trivial counterexample in the case of other BCs is given by (1.2), which provides a perfectly valid solution to the IBVP for the NLS equation on the half-line with the non-homogeneous Dirichlet BC $q(0, t) = q_s(0, t)$.

Finally, we note that, similarly to the traditional method of images, one could in principle assume that the symmetry (2.21) of the discrete eigenvalues holds, require that the solution satisfies the given BCs and then obtain the relation between the norming constants by solving a system of algebraic equations. We did not do so here, however. On one hand, the resulting equations are transcendental, and finding their solution without any a priori knowledge is highly nontrivial, which would make the method impractical. Moreover, exploiting the symmetry of the scattering coefficients enabled us to prove that all solutions of the IBVP possess the symmetry (2.21) and to find the relations between norming constants, regardless of the number of physical solitons and of whether the reflection coefficient is zero.

The present results open up a number of interesting questions. An obvious one is what happens for other integrable NLEEs. We expect that similar results will apply to equations such as the sine-Gordon equation [9] and the Ablowitz–Ladik lattice [6]. Less clear, however, is what happens for the Korteweg–deVries equation, since in this case all solitons travel to the right (or to the left depending on the sign of the nonlinear term), and no obvious symmetry exists. It might be that the nonlinear method of images only applies as presented to equations that admit some reflection symmetry, or such that the linear limit can be solved with Fourier methods [14]. (Note that even the traditional method of images has similar restrictions.)

Another nontrivial question is what happens on finite domains. Numerical simulations show that in this case the solitons experience an infinite number of reflections at each boundary. After two reflections, however, any soliton recovers its original velocity. The initial soliton and its twice-reflected copy must thus be associated with the same discrete eigenvalue. Moreover, since the soliton experiences an infinite number of reflections, the extension of the solution to the whole line would require an infinite number of mirror copies. Finally, such a solution would not possess decaying or even constant BCs as $x \to \pm \infty$. Therefore, its characterization seems to be outside the current capabilities of IST-based methods.
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Appendix. IBVP for the linear Schrödinger equation with Robin BCs

For comparison purposes, here we solve the IBVP for the linear Schrödinger (LS) equation
\[ i \partial_t q + \partial_{xx} q = 0, \]  
for \( x > 0 \), with the homogeneous Robin BCs (1.3) at the origin, using the IST for the IVP
and an extension of the potential to the negative real \( x \)-axis. (See [6, 11] for an alternative
method.)

Equation (A.1) is the compatibility condition of the scalar Lax pair [6]
\[ \phi_x - ik \phi = q, \quad \phi_t + i k^2 \phi = i \partial_x q - kq. \]  
When (A.1) is posed on \(-\infty < x < \infty\), the Jost solutions of (A.2) are
\[ \phi^+(x, t, k) = \int_{-\infty}^x e^{ik(x-x')}q(x', t) \, dx', \quad \phi^-(x, t, k) = -\int_{x}^{\infty} e^{ik(x-x')}q(x', t) \, dx'. \]  
It is easily shown that \( \phi^\pm(x, t, k) \) can be analytically continued on \( \text{Im} \, k \gtrless 0 \), and
\( \phi^\pm(x, t, k) = O(1/k) \) as \( k \to \infty \). Moreover, on \( \text{Im} \, k = 0 \) one has the following jump
condition:
\[ \phi^+(x, t, k) - \phi^-(x, t, k) = e^{ikx} \hat{q}(k, t), \]  
with \( \hat{q}(k, t) \) given by the first of (A.6) below. Equation (A.4) defines a scalar RHP that is
solved with standard Cauchy projectors. Moreover, the jump data satisfies
\[ \hat{q}(k, t) = e^{-ik^2t} \hat{q}(k, 0). \]  
and the solution of the RHP leads to the direct and inverse Fourier transform pair
\[ \hat{q}(k, t) = \int_{-\infty}^{\infty} e^{-ikx}q(x, t) \, dx, \quad q(x, t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{ikx} \hat{q}(k, t) \, dk. \]  
Now consider the IBVP for (A.1) on \( x > 0 \) with BCs (1.3). It is trivial to see that, if
\( q(x, t) \) is given by the second of (A.6) for \( x > 0 \), the BCs (1.3) are satisfied provided that
\[ \hat{q}(k, t) = f_o(k) \hat{q}(-k, t), \]  
where
\[ f_o(k) = (k - i\alpha)/(k + i\alpha). \]  
This motivates the following extension of \( q(x, t) \):
\[ q^\text{ext}(x, t, k) = q(x, t) \Theta(x) + f_o(k)q(-x, t) \Theta(-x), \]  
for all \( x \in \mathbb{R} \). The corresponding Fourier transform \( \hat{q}^\text{ext}(k, t) \) (defined by the first of (A.6)
with \( q(x, t) \) replaced by \( q^\text{ext}(x, t) \)) is related to the one-sided Fourier transform \( \hat{q}_o(k, t) \)
\[ \hat{q}_o(k, t) = \int_{0}^{\infty} e^{-ikx}q(x, t) \, dx, \]  
by \( \hat{q}^\text{ext}(k, t) = \hat{q}_o(k, t) + f_o(k)\hat{q}_o(-k, t) \). It is then easily verified that \( \hat{q}^\text{ext}(k, t) \) satisfies (A.7)
(note \( f_o(k)f_o(-k) = 1 \)). We then consider an extended Lax pair obtained by replacing \( q(x, t) \)
with \( q_e(x, t, k) \) in (A.2). Note however that \( q_e(x, t, k) \) is in general discontinuous at \( x = 0 \), and in a distributional sense it solves
\[
\i q_{e,x} + q_e^2 = [f_o(k) + 1]q_e(0, t)\delta(x) - [f_o(k) - 1]q(0, t)\delta(x),
\]
where \( \delta(x) \) is the Dirac delta. Thus the Lax pair (A.2) with \( q(x, t) \) replaced by the extended potential is not compatible at \( x = 0 \). The compatibility is restored if the \( t \)-part of (A.2) is replaced by
\[
\phi_t + ik^2\phi = iq_{e,x} - kq_e^2 + i[f_o(k) - 1]q(0, t)\delta(x).
\]
One now defines \( \phi^\pm(x, t, k) \) as the Jost solutions of this new Lax pair. Since the \( x \)-part is formally the same as before, they are simply given by (A.3) with \( q(x, t) \) replaced by \( q_e(x, t, k) \). For \( x > 0 \), \( \phi^-(x, t, k) \) is analytic on \( \text{Im } k < 0 \). Also, for \( x > 0 \), \( \phi^+(x, t, k) \) is analytic on \( \text{Im } k > 0 \) when \( \text{Re } \alpha \geq 0 \) and is meromorphic on \( \text{Im } k > 0 \) with a simple pole at \( k = -i\alpha \) when \( \text{Re } \alpha < 0 \). (When \( \text{Re } \alpha > 0 \), the pole at \( k = -i\alpha \) is in the lower-half plane.) The jump condition (A.4) still holds with \( \hat{q}(k, 0) \) replaced by \( \hat{q}_e(k, 0) \). Moreover, using (A.11) with \( q(x, t) \to 0 \) as \( x \to \infty \), we obtain that the scattering data \( \hat{q}_e(k, t) \) still evolves according to (A.5). After subtracting the pole contribution, one solves the RHP (A.4) using Cauchy projectors, obtaining
\[
\phi(x, t, k) = \frac{1}{2\pi i} \int_{-\infty}^{\infty} e^{i(kx - k^2t)} \hat{q}_e(k', 0) \frac{dk'}{k' - k} + \frac{1}{k + i\alpha} v_o'_{k=\pm i\alpha} \text{Res } [\phi^+],
\]
where \( v_o' = 0 \) for \( \text{Re } \alpha > 0 \), \( v_o' = 1/2 \) for \( \text{Re } \alpha = 0 \) and \( v_o' = 1 \) for \( \text{Re } \alpha < 0 \). Note that \( \text{Res } [\phi^+] = -2i\alpha e^{ax+ixt} \hat{q}(i\alpha, 0) \). Substituting the above into (A.2) we have, for all \( x > 0 \)
\[
q(x, t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{i(kx - k^2t)} \hat{q}_e(k, 0) dk - 2v_o'\alpha e^{ax+ixt} \hat{q}_o(i\alpha, 0).
\]
Note that, even though \( q_e(x, t, k) \) is discontinuous at \( x = 0 \), the BCs (1.3) are satisfied from the right.

One can compare the above solution to the linear limit of the solution of the IBVP for the NLS equation. To do so, let \( Q_e(x, t, k) \equiv Q_e(x, t, k; \varepsilon) = O(\varepsilon) \) in (2.1). As \( \varepsilon \to 0 \), it is
\[
a(k) = 1 + O(\varepsilon^2), \quad b(k) = \int_{-\infty}^{\infty} e^{2ikx} q_e(x, t) dx + O(\varepsilon^2), \quad (A.13a)
\]
\[
\mu_{12}^{(1)}(x, t, k) = \int_{0}^{\infty} e^{2ik(x-x')} q(x', t) dx' + f(k) \int_{0}^{\infty} e^{2ik(x+x')} q(x', t) dx' + O(\varepsilon^2). \quad (A.13b)
\]
Since \( \mu^{(1,R)}(x, t, k) \) has a pole at \( k = -i\alpha/2 \) when \( \alpha < 0 \) but \( a(k) = 1 \) to leading order, the solution of the RHP (2.12) acquires an additional term generated by the residue of \( \mu^{(1,R)}(x, t, k)/a(k) \). Taking the pole contribution into account, and performing the change of variable, \( 2k \to k' \), one then obtains, to \( O(\varepsilon) \), (A.12). That is, in the linear limit, the solution of the IBVP for the NLS equation coincides with solution of the IBVP for the linear Schrödinger equation.

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