Research on micro milling mechanism and surface roughness of high volume fraction SiCp/Al composites

Po Jin¹, Qi Gao¹, Quanzhao Wang², and Wenbo Li¹
¹School of Mechanical Engineering and Automation, Liaoning University of Technology, 121001
²Institute of Metal Research, Chinese Academy of Science, 110016
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Corresponding author: Qi Gao (qqonline@163.com).

Abstract: In this paper, the finite element simulation model of diamond tool milling SiCp/Al composites was established. The milling force, stress distribution and removal mechanism of SiC reinforced granular material were studied. The correctness of finite element simulation is verified by micro milling experiments. The results show that the maximum stress mainly occurs when the SiC particles are milled with PCD tool. The removal mechanism of particles is different when the tool is milling particles at different positions. The material surface defects are reduced and the surface quality is improved as the cutting speed is increased. The surface defects of SiCp/Al milling with single edge diamond milling tool mainly include cavities, microcracks, scratches and pits. According to the measurement results, it can be founded that the milling depth has the greatest influence on the surface roughness, followed by the spindle speed and the feed speed.

Keyword: SiCp/Al composite, Micro-milling, Milling mechanism, Surface roughness, Orthogonal experiment

1. Introduction

With the increasing demand for material properties in the fields of aerospace, automotive and optical precision instruments. Silicon Carbide particle aluminum matrix composites (SiCp/Al) have attracted more and more attention due to their excellent properties [1]. The SiCp/Al composites have excellent comprehensive properties such as high specific strength and modulus, high temperature resistance, etc. The SiCp/Al components are mainly used in satellite bearings, aircraft engines and inertial navigation systems [2]. As the urgent need of SiCp/Al composites in various projects, the processing technology of SiCp/Al composites has been widely concerned by scholars [3].

Song Min et al. [4-5] found that with the increase of SiC particle volume fraction, the yield strength and tensile strength increased, while the elongation decreased. Subsequently, Tao Wang et al. [6] established a two-dimensional finite element simulation model to study the milling process of SiCp/Al matrix composite materials. He founded that the main causes of surface defects were extrusion, pull-out and crushing of particles. Xiangyu Teng et al. [7] established a two-dimensional finite element simulation model considering the cutting edge radius, and analyzed the interaction between the cutter and particles and the process of chip formation. The distribution of cutting stress and strain in the workpiece under the influence of different cutting depth is studied. Zhichao Niu et al. [8] conducted a processing experiment with polycrystalline diamond (PCD) tool on a high-precision miniature milling machine. The surface roughness, morphology, texture and defect of workpiece were analyzed. And the optimum technological parameters are selected. Alokelesh Pramanik et al. [9] performed milling on nano-particle reinforced aluminum matrix composites. The results show that the surface roughness of the workpiece increases with the increase of feed speed. The surface roughness of the workpiece decreases with the increase of feed per tooth, at a higher feed rate (100-140m/min). Junwei Liu et al. [10] established a force prediction model for SiCp/Al composites. He founded that the maximum milling force increases with the increase of feed per tooth and milling depth. U. A. Dabade et al. [11] studied two kinds of SiC composites with volume fraction of 10%. The effects of feed rate and cutting depth on cutting force, surface roughness and preheating temperature are revealed. Ying Fei Ge et al. [12] studied the wear condition, chip formation and surface generation of the cutter when the low-body SiCp/2009Al composite material was processed at ultra-high speed. Junwei Liu et al. [13] conducted an experimental study on micro-milling of 45% SiCp/Al composites. And founded that the surface roughness decreases first and then increases with the increase of feed. Beibei Wang et al. [14] simulated the high speed milling process of SiCp/Al6063 composites with high volume fraction. The interaction among matrix, particle and tool during cutting was studied. The cutting mechanism of the material is also revealed. Tao Wang et al. [15] studied the milling process of SiCp/Al composites with high volume fraction and small particle size. The effects of milling speed, feed rate and particle size on tool wear are revealed. YanmingQuan et al. [16] studied the hardness and residual stress of SiCp/Al composites during processing. The results show that the residual stress on the surface of coarse-grained reinforced composites may be released due to structural defects. However, the residual stress on the surface of the composite reinforced by fine grains tends to compress. R. Bian et al. [17] conducted precision milling research on SiCp/Al composites with high volume fraction.
and large granularity. The cutting mechanism and wear characteristics of SiCp/Al composites are revealed. M. Bhuvaney Kumar et al. [18] fabricated SiC and B4C reinforced aluminum composites with three different components using agitation casting technique. Experiments were carried out on these materials with different machining parameters, and the most influential milling parameters were found. Xiangyu Teng et al. [19] investigated the cutting mechanism of two SiCp/Al composites with different particle sizes. It was found that the nanoscale particles remained intact during the cutting process without breaking, which may produce continuous chip. However, micron-sized particles are prone to fracture and tend to produce discontinuous chips. Compared with micron size, nanometer size materials can achieve better surface quality and fewer defects.

Due to the strengthening effect of silicon carbide particles in the material, SiCp/Al composites have excellent properties. At the same time, the surface quality of the processed material is difficult to control, which is a typical refractory material [20]. Micro milling is an important machining method in the field of mechanical processing, which has many advantages, such as high machining accuracy, low machining cost and so on. Therefore, the micro milling technology is applied to the processing of composite materials to realize the flexible and precision processing of composite parts [21-22].

The removal characteristics of composites are different from those of conventional machining. Both the size effect of plastic material and the removal of brittle material affect the surface formation of composite materials. In this paper, finite element simulation and micro milling experiments are combined to study the material milling mechanism and surface defect formation mechanism of SiCp/Al composites in micro cutting. The influence of spindle speed, feed speed and milling depth on surface quality is analyzed. Furthermore, the optimization of the combination of process parameters is carried out to further improve the surface quality of the material and promote its industrial application.

2. Simulation analysis based on particle random distribution model

SiCp/Al matrix composite is a two-phase heterogeneous material composed of aluminum alloy matrix and micron grade silicon carbide particles. Because the characteristics of two-phase materials are different, the model of particle random distribution is constructed and the simulation experiment is carried out.

2.1 Establishment of random particle distribution model

The finite element model of SiCp/Al composites with different particle size distribution was established. In order to observe the particle removal mechanism in the cutting process more clearly, and avoid non-convergence in the simulation process. The 3D micro-milling model is simplified to a 2D orthogonal simulation experiment. Schematic diagram of milling model is shown in Fig.1. The particle volume fraction of composites is 60%. The particle diameter is mainly composed of 20 m and 60 m particles. The average particle size is 40 m, and the matrix material is Al2024. It is assumed that the particle shape is circular and the particles are randomly distributed in the matrix without overlapping. The random distribution of particles is obtained, as shown in Fig.2.

2.2 Material characteristics and failure criteria

The matrix of the composite is Al2024 and the reinforcement is SiC particles. The elastic phase of the material is mainly determined by elastic modulus and Poisson's ratio. Some parameters are shown in Table 1. The deformation mode and chip formation form of aluminum matrix and silicon carbide particles were set respectively.

| Table 1 Material parameters of Al2024 and SiC |
|---------------------------------------------|
| Material | Matrix: Al2024 | Particles: SiC |
| Density (g/cm³) | 2.77 | 3.13 |
| Elastic modulus (GPa) | 73 | 427.5 |
| Poisson's ratio | 0.33 | 0.14 |
| Thermal conductivity(W/(mk)) | 190 | 81 |
| Specific heat (J/(kgK)) | 875 | 427 |
Aluminum is a typical plastic material. Johnson cook (J-C) model is used to characterize its plastic deformation stage [23], and J-C model is often characterized as shown:

\[ \sigma = (A + B \varepsilon^p)(1 + C \ln \left( \frac{\dot{\varepsilon}}{\dot{\varepsilon}_0} \right)\left[ 1 - \left( \frac{T - T_0}{T_m - T_0} \right)^{n} \right] \]  

(1)

where \( \sigma \) -- flow stress (MPa); \( \varepsilon \) -- Effective plastic strain; \( \dot{\varepsilon} \) -- Effective plastic strain rate; \( \dot{\varepsilon}_0 \) -- Reference plastic strain rate; \( T \) -- Environment temperature (°C); \( T_m \) -- Melting point temperature of the material (MPa); \( A \) -- Yield stress of the material (MPa); \( B \) -- Work hardening parameters of the material (MPa); \( C \) -- Strain rate enhancement index; \( m \) -- Temperature change rate index; \( n \) -- Strain hardening index.

Johnson-cook fracture criterion and damage parameter \( D \) was used to judge the material removal. \( D \) was set to be 1, and the unit was separated and removed. The expression is

\[ D = \sum \frac{\Delta \varepsilon_i}{\varepsilon_i'} \]  

(2)

where \( \varepsilon_i' \) -- failure strain; \( \Delta \varepsilon_i \) -- The effective plastic strain increment under load unit increase.

Johnson-cook fracture criterion [24], the calculation formula of equivalent plastic strain is

\[ \varepsilon' = \left[ d_1 + d_2 \exp \left( \frac{d_3}{d_4} \right) \right] \left[ 1 + d_3 \ln \left( \frac{\dot{\varepsilon}}{\dot{\varepsilon}_0} \right) \right] \left[ 1 + d_2 \left( \frac{T - T_0}{T_m - T_0} \right)^{n} \right] \]  

(3)

where \( \varepsilon' \) -- equivalent plastic strain; \( \delta_m \) -- Average value of positive pressure (MPa); \( \delta \) -- Effective stress (MPa); \( d_1, d_2 \) -- material failure parameters. The following Table 2 shows the J-C model and J-C fracture model parameters of 2024 aluminum alloy.

| Table 2 Some parameters of matrix J-C model and J-C fracture model [25] |
|--------------------------|--------------------------|
| A (MPa)                  | 369                     |
| B (MPa)                  | 684                     |
| C                        | 0.0083                  |
| m                        | 1.7                     |
| n                        | 0.73                    |
| d_i                      | 0.112                   |
| d_i                      | 0.123                   |
| d_i                      | 1.5                     |
| d_i                      | 0.007                   |
| d_i                      | 0                      |
| T_m (°C)                 | 502                     |
| T_l(°C)                  | 20                      |

2.3. Criteria for chip separation

The characteristics of aluminum matrix also adopt J-C and J-C fracture models [26], adopt brittleness removal criteria for SiC particles, and select a tensile stress standard to judge, and its characterization is as follows:

\[ \text{max}(\delta_1', \delta_2', \delta_3') = \delta_0 \]  

(4)

where \( \delta_1', \delta_2', \delta_3' \) -- principal stress (MPa); \( \delta_0 \) -- crushing stress of SiC material (MPa).

In the failure criterion of Brittle materials, the standard model of energy is used to measure the cracking and crack expansion of silicon carbide. The crack displacement during failure can be expressed by

\[ u_{\text{rel}} = 2G_J/\delta_0^2 \]  

(5)

where \( u_{\text{rel}} \) -- Nominal displacement (μm); \( G_J \) -- mode I fracture energy (J/m²); \( \delta_0^2 \) -- critical stress of mode I fracture (MPa). The stress retention model is used to describe crack propagation due to shear stress. The shear modulus \( G \) after cracking can be calculated by the following formula

\[ G = \left( 1 - \frac{\varepsilon_{\text{max}}^p}{\varepsilon_{\text{max}}^\text{e}} \right) G \]  

(6)

where \( p, \varepsilon_{\text{max}}^p \) -- material parameters; \( G \) -- Shear modulus of the material (MPa); \( \varepsilon_{\text{max}}^\text{e} \) -- Crack propagation strain. The brittle fracture parameters of SiC materials standards as shown in Table 3.

| Table 3 Parameters of material brittleness removal [26, 27] |
|-------------------------|-------------------------|
| \( \delta_0 \)          | \( G \)               |
| 1500                    | 30                      |
| \( p \)                 | 1                       |
| \( e_{\text{max}}^\text{e} \) | 0.001                 |

2.4. The relationship between experiment and simulation

In the experiment, the maximum milling depth was 50μm, which was very small compared with the tool diameter of 1000μm, as shown in Fig. 3. In this case, the effect of helix Angle on chip formation and cutting force can be ignored. Therefore, the 3D micro-milling process is simplified to 2D micro-orthogonal cutting path. It is assumed that the uncut thickness is the same as the chip thickness. (a) Schematic diagram of a two-dimensional milling process; (b) The relationship between milling and orthogonal milling models.

(a)

![Diagram](image-url)
2.5. Analysis of cutting mechanism and results

In the simulation, the cutting speed is set to 37.68 m/min, which is equivalent to the spindle speed of 12000 r/min, and the milling depth is 40 μm. After the simulation, the particle removal and surface defects are analyzed, it can be founded that the removal forms of milling particles are also different at different positions, as shown in Fig. 4.

It can be seen from Fig. 4 that when micro-milling SiCp/Al composites, the main removal forms of particles are peeling, shedding, crushing and pressing, because the particle size and position are randomly selected when the model is established, the removal of particles is also different when the tool is milling different positions of particles.

In Fig. 4 (c), (d) when milling the upper part of the particle, part of the interface between the particle and the aluminum matrix is destroyed, the point where the particle contacts the front Angle of the blade and the part above the point is removed, and the following part is pressed into the matrix.
The tool first cuts the aluminum matrix, and the Al matrix is plastically deformed. With the milling, the tool nose gradually approaches the particles, which makes the constraint between the particles and the matrix fail, and the aluminum matrix is plastically removed, the tool continues to milling particles, resulting in an increase in the stress on the upper part of the particles. When the milling stress is greater than the strength limit value of the particle material, the particles will produce brittle deformation. With the progress of milling, the deformation will continue to expand, the upper part of the particle is peeled off, and cracks and pits are generated on the surface of the workpiece.

In Fig. 4(a), (b), when the tool milling particles near the middle position, under the extrusion of the tool, most of the particle interface fails, A small part of the particles are directly pressed into the matrix. When the tool is milling the middle part of the particle, due to the front and rear extrusion of the particle and the tool, the aluminum matrix produces plastic deformation and is extruded to the upper and lower parts of the particle. At this time, the constraint fails and changes into the milling process of silicon carbide particles, when the milling stress is greater than the strength limit value of the particle material, the brittle deformation of the particle is removed.

Fig. 4(d), (e) show the situation of the lower half and bottom of the milling particle with the cutter. The interface fails completely and the particle is directly pulled out. Under the cutting of the tool, the particles are squeezed with each other, which will also break and remove the particles. When the tool is milling the lower half of the particle, the constraint gradually fails when the rake angle of the tool contacts with the particle. With the milling of the tool, the milling stress is greater than the strength limit value of the particle material, and the interface fails sharply, the lower half of the particles is crushed, most of the particles are pulled out, and larger pits are generated on the processed surface. When the tool is milling the bottom of the particle, the contact surface near the bottom of the particle and the matrix will cause constraint failure when the particle is in contact with the front angle of the tool. With the milling of the tool, it can be seen that the actual cutting position of tool nose is aluminum matrix, so the cutting position of tool edge diameter is aluminum matrix. With the progress of milling, particles are completely removed and the processing surface quality is better.

In Fig. 4(m), it can be seen that in the cutting process, the stress concentration area is mainly the plane where the matrix and the particle contact, while the irregular stress distribution area is mainly the location area where the tool interacts with the particle and the matrix material. It can be judged that stress concentration and irregular stress distribution lead to particle breakage, peeling, shedding, the main causes of extrusion and surface defects.

The particle removal and surface defects after the simulation are shown in Fig. 5.

It can be seen from Fig. 5, as the cutting speed increases, the cracks and defects of particles decrease, and the surface quality of the material becomes better. This is mainly because as the cutting speed increases, the cutting stress in the system increases, so the strain rate increases. According to the J-C failure criterion, the increase of stress and strain rate makes the Matrix easy to remove. For Silicon carbide particles, when the tool is milling particles, the cutting stress on the particles increases rapidly, but the cutting speed increases, resulting in a decrease in the time used to cut particles. Compared with the low cutting speed, the interaction time between tool and particle is shorter, and the stress transfer time is shorter, thus reducing crack propagation and defect formation. Therefore, in high-speed cutting, the surface defects of the material are less and the surface morphology is smoother.

3. Experimental study on micro milling
3.1. The experimental scheme
The experiment mainly studies and analyzes the surface defects formed by PCD end mill milling groove processing particle reinforced aluminum matrix composite SiCp/Al, and the influence of milling dosage on the surface quality. The material used in the experiment is SiCp/Al composite
material composed of Al2024 aluminum alloy and SiC particles. The volume fraction of particles is 60%. The particle part is mainly composed of 20 µm and 60 µm particles with an average size of 40 µm. Diamond end mill is selected as the experimental tool. The tool diameter is 1 mm, the edge radius is 10 µm, the rake angle is 7° and the rake angle is 20°.

The experiment was carried out on the Carver400 of Beijing carved vertical machining center. The experimental site is shown in Fig. 6. The surface roughness value of material cutting is measured by real color scanning microscope. The surface micro-morphology of material cutting is observed by Zeiss SIGMA 500 field emission scanning electron microscope, and the experimental equipment is shown in Fig. 7.

![Carver400GA Machine tool](image)

**FIGURE 6.** Experimental site

![PCD tool](image)

![SICp/Al2024 composite](image)

**Figure 7.** Experimental measurement equipment (a) True color confocal microscope; (b) Zeiss SIGMA 500 field emission scanning electron microscope

This micro milling experiment mainly studies the influence of process parameters on surface roughness. The processing parameters used in milling test as shown in Table 4.

| Parameters | 1 | 2 | 3 | 4 |
|------------|---|---|---|---|
| Spindle speed N (r/min) | A | 12000 | 14000 | 16000 | 18000 |
| Feed rate $V_f$ (mm/min) | B | 6 | 8 | 10 | 12 |
| Milling depth $a_p$ (µm) | C | 20 | 30 | 40 | 50 |

Orthogonal experiments are adopted to judge the influence degree of each parameter so as to optimize the parameters. According to the spindle rotation speed, feed speed and milling depth of the three process parameters, a three-factor and four-level experiment is designed, ignoring the interaction, L16 orthogonal experiment table is selected, and the process parameters and their levels are shown in Table 5.

The schematic diagram of micro-milling is shown in Fig. 8. Under the action of load, the sharp milling edge is cut into the surface of the material at a certain speed, causing the plastic deformation of the latter and forming a milling groove on its surface.

![Figure 8. Schematic diagram of milling](image)

3.2. Analysis of experimental results

Due to the existence of reinforced silicon carbide particles in particle reinforced aluminum matrix composites, the effects of the micro-morphology, formation rule and cutting parameters on the machined surface quality of the composites are different from the one-way material of the workpiece.

The micro-morphology of the milling surface of particle reinforced aluminum matrix composites was detected by real color scanning microscope, and four groups of experiments with obvious and representative surface micro-morphology characteristics were selected for analysis, the three-dimensional features of surface topography are shown in Fig 9.
Figure 9. Three-dimensional feature map of surface morphology; (a) \( N = 14000 \) r/min, \( V_f = 0.012 \) m/min, \( a_p = 50 \) \( \mu \)m; (b) \( N = 14000 \) r/min, \( V_f = 0.01 \) m/min, \( a_p = 50 \) \( \mu \)m; (c) \( N = 16000 \) r/min, \( V_f = 0.006 \) m/min, \( a_p = 40 \) \( \mu \)m; (d) \( N = 18000 \) r/min, \( V_f = 0.012 \) m/min, \( a_p = 20 \) \( \mu \)m

The three-dimensional features according to the observed surface topography are shown in Fig. 9. It can be seen that the machining surface in Fig. 9 (c) is relatively smooth, that is, when the spindle speed is 16000 r/min, the feed speed is 6mm/min and the milling depth is 40 \( \mu \)m, the surface morphology of the material is relatively good, \( R_a \) is 0.385 \( \mu \)m.

There are two main reasons: (1) because the milling thickness is greater than the minimum cutting thickness of the aluminum matrix, so the removal effect of the aluminum matrix is better, and the resistance to the milling tool is reduced at the same time, so that the surface is relatively smooth; (2) the milling volume of particles is small and the broken particles are few, so the milling force is small and the amplitude of the spindle is small, which makes the surface quality better. The feed per tooth will increase, the milling volume of aluminum matrix and particles will increase in unit time, the material size effect will be weakened, and most of the particles will be broken and removed, when the spindle speed remains unchanged and the feed speed increases. The broken tiny particles will scratch the surface under the extrusion of the tool. The formation of small cavities and scratches is shown in Fig. 9 (a), (b) and (d), the surface defects increase. In addition, a large number of scratches and small cavities were also found on the surface of the material by scanning electron microscopy (SEM), as shown in Fig. 10 (a).

Large pits and cracks appear in Fig. 9 (a) and (b), because the milling volume of aluminum matrix and particles increases per unit time, resulting in the increase of milling force, the vibration of the spindle is intensified, and the particle size of the material is relatively large in the experiment. It will appear cracks and cavities caused by particles being crushed and broken, as well as defects such as pits caused by particles being pulled out, when the milling depth is deep enough or the feed beam per tooth.

The micro-morphology of the milling surface of particle reinforced aluminum matrix composite was detected by Zeiss SIGMA 500 field emission scanning electron microscope, and the surface defects of the material were shown in Fig. 10.
The surface roughness values corresponding to the four sets of cutting parameters (a), (b), (c) and (d) are shown in Fig. 11 in turn.

The detection energy spectrum of the surface of the processed material is shown in Fig. 12, while the spindle speed is 12000 r/min, the feed speed is 0.006 m/min and the milling depth is 40 μm.

Fig. 10 shows the cracks and cavities generated by the particles being crushed and broken during the cutting process of composite materials, the scratches caused by the crushed particles being crushed, and the holes caused by the particles being pulled out, etc, these defects have been clearly displayed in the finite element simulation model, and the experimental pictures verify the correctness of the finite element simulation model to some extent.

Combining Fig. 10 and Fig. 11, these can be founded that when the feed per tooth increases, the surface defects of the processed material first increase rapidly, then decrease rapidly and then increase slowly, and the surface quality first increases rapidly, then decreases rapidly and then increases slowly. Milling process, the milling depth unchanged, with the increase of each tooth feeding, surface roughness parameter $R_a$ to decrease rapidly after increase rapidly, it shows that when the $f_t$ is 0.5 μm is likely to occur the phenomenon of plough and $R_a$ value is bigger. The increase of feed rate per tooth leads to the increase of milling volume per unit time. At the same time, milling force and tool vibration increase, which makes the surface defects increase. The falling particles will roll and slide along with the tool on the machined surface, which will cause scratches on the workpiece surface, make the surface quality worse.

With the increase of each tooth feed, the milling force increases, the friction is serious, the temperature rises rapidly, the residual aluminum matrix on the surface of the workpiece melts and binds to the material surface, resulting in the decrease of surface roughness.

The voids and cracks in Fig. 10 are randomly distributed, and Fig. 12 shows the energy spectrum of material element detection obtained by scanning e-sports, which can prove this problem. According to the detection results in Fig. 12 (a), the Si element contained in point b is 89.20%, the Al element is 3.68%, and the Si element contained in point c is 68.85.20%. The Al element is 5.19%. According to the detection results in Fig.12 (b), the position of point b is SiC particles, which indicates that the particles are broken and pulled out from a
part, point b is the hole caused by the particles being pulled out. According to the detection result, the Al element contained in point a is 67.23% and the Si element is 16.59%. In combination with Fig. 12 (b), an aluminum matrix can be attached to the SiC particles. This is because the formed aluminum matrix chip cannot be completely removed during milling, resulting in a small amount of residue melting and remaining on the surface of the workpiece under high temperature conditions. With the progress of milling, the friction heat generation increases, as a result, more aluminum matrix remains on the processing surface after melting, surface defects of materials can be made up and surface quality can be improved.

4. Orthogonal experimental analysis and parameter optimization

The evaluation method of surface roughness selected in this paper is the centerline method, which is mainly used for \( R_a \) evaluation. \( R_a \) represents the arithmetic mean of the absolute value of the distance of contour offset from the undulating center line along the measured direction within the sampling length, and its calculation formula is shown:

\[
R_a = \frac{1}{n} \sum_{i=1}^{n} |y_i|  \tag{7}
\]

where \( y_i \) represents the distance between the point on the contour line and the center line in the measured direction.

In order to analyze the influence of spindle speed, feed speed and milling depth on surface quality, L16 orthogonal experiment table is selected to plan orthogonal experiment. Combined with the measurement results in the previous section, the process parameters determined, the level and its measurement results are shown in Fig. 13.

![Figure 13. Measurement results of surface roughness of milling groove](image)

According to the measurement results, the range analysis of the arithmetic mean deviation of contour is shown in Table 6.

| Experiment number | Spindle speed (μm) | Feed rate B (μm) | Milling depth C (μm) |
|-------------------|-------------------|------------------|---------------------|
| \( K_1 \)         | 2.42              | 2.049            | 3.097               |
| \( K_2 \)         | 1.888             | 2.345            | 2.787               |
| \( K_3 \)         | 2.882             | 2.713            | 2.013               |
| \( K_4 \)         | 2.75              | 2.833            | 2.043               |
| \( k_1 \)         | 0.605             | 0.51225          | 0.77425             |
| \( k_2 \)         | 0.472             | 0.58625          | 0.69675             |
| \( k_3 \)         | 0.7025            | 0.67825          | 0.50325             |
| \( k_4 \)         | 0.6875            | 0.70825          | 0.5015              |
| Range             | 0.2305            | 0.196            | 0.27275             |

Primary and Optimal levels:

- \( A_2 \)
- \( B_1 \)
- \( C_3 \)

Optimal combination: \( A_2B_1C_3 \)

The greater the range, the greater the influence degree of this factor. It can be seen from Table 6 that the milling depth has the greatest influence on the average deviation \( R_a \) of contour arithmetic, followed by the spindle speed and the feed speed. The optimal process parameter combination of contour arithmetic average deviation \( R_a \) is mainly the shaft speed 14000 r/min, feed speed 6 mm/min and milling depth 40 μm, and the influence degree of each parameter is very small, it shows that the surface morphology characteristics of the processed surface are relatively consistent. When these parameters are selected for milling, the average deviation \( R_a \) of the surface contour arithmetic obtained is the smallest, and the surface defects are the least as shown in Fig. 14.

![Figure 14. Surface 3D morphology characteristics of \( N=14000 \text{ r/min, } \dot{V}=0.006 \text{ m/min and } a_p=50 \mu\text{m} \)](image)

Through the optimization of cut parameters, it can be found that when using diamond end mill with smaller diameter and blade diameter to process large particle high-volume silicon carbide metal composite. Milling parameters such as spindle speed 14000 r/min, feed speed 0.006 m/min and milling depth 40 μm were selected. The surface quality was good, and the average arithmetic deviation of surface roughness \( R_a \) is 0.238 μm.
5. Conclusion
From the simulation and experimental results, these were concluded that:

When micro-milling Silicon Carbide aluminum matrix metal composites, the main removal forms of particles are peeling, shedding, crushing and pressing, and the removal of particles is also different at different positions of milling particles. During the milling process, keep the spindle speed and feed speed unchanged, and increase the milling depth eventually leads to the deterioration of the surface quality of the material being processed.

The milling depth is kept constant during the milling process. With the increase of each tooth feed, the surface roughness value decreases rapidly and then increases rapidly. This indicates that ploughing may occur when $f_r$ is 50 μm, so the surface roughness value is large. With the increase of each tooth feed, the milling force increases, the friction is serious, and the temperature rises rapidly, which leads to the melting and solidification of the residual aluminum metal on the workpiece surface, leading to better surface quality.

During the cutting process of composite materials, cracks and cavities caused by particles being crushed and broken, scratches caused by crushed particles being crushed, holes caused by particles being pulled out, etc. Rolling and sliding of shedding particles on the processing surface under the action of cutting tools is one of the important reasons for scratches and pits on the surface of workpieces. Through the optimization of milling parameters, it is found that the milling depth has the greatest influence on the surface roughness $R_a$, followed by the spindle speed and feed speed when the milling tool with small cutting edge radius is used to mill the SiCp/Al composite with large particles. The optimal combination of process parameters of the surface roughness $R_a$ is mainly the shaft speed 14000 r/min, the feed speed is 6 mm/min and the milling depth is 40 μm; At this time, the surface quality is better, $R_a$ is 0.238 μm.

Ethical Approval
This research project has been approved by the Ethics Committee of Liaoning University of Technology.

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Conflicts of interest/Competing interests
The authors have declared that no conflict of interest exists.

Availability of data and material
The data used to support the findings of this study are available from the corresponding author upon request.

Authors’ contributions
The finite element simulation experiment of micromilling of SiCp/Al composites was established. The milling process of SiCp/Al composites with high volume fraction and large grain size was studied. The distribution of stress and strain of SiC reinforced particles and the material removal mechanism were analyzed. The influence degree of each influencing factor on surface roughness.

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