Multiparametric amplification and qubit measurement with a Kerr-free Josephson ring modulator

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(Received 9 September 2019; accepted 1 April 2020; published 29 April 2020)

Josephson-junction based parametric amplifiers have become a ubiquitous component in superconducting quantum machines. Although parametric amplifiers regularly achieve near-quantum limited performance, they have many limitations, including low saturation powers, lack of directionality, and narrow bandwidth. The first is believed to stem from the higher order Hamiltonian terms endemic to Josephson junction circuits, and the latter two are direct consequences of the nature of the parametric interactions which power them. In this work, we attack both of these issues. First, we have designed a new, linearly shunted Josephson ring modulator (JRM), which nearly nullifies all fourth-order terms at a single flux bias point. Next, we achieve gain through a pair of balanced parametric drives. When applied separately, these drives produce phase-preserving gain (G) and gainless photon conversion (C); when applied together, the resultant amplifier (which we term GC) is a bidirectional, phase-sensitive, transmission-only amplifier with a large, gain-independent bandwidth. Finally, we have demonstrated the practical utility of the GC amplifier, as well as its quantum efficiency, by using it to read out a superconducting transmon qubit.

DOI: 10.1103/PhysRevA.101.042336

1. INTRODUCTION

In recent years, the potential of superconducting qubits as a quantum computing architecture has grown tremendously [1,2]. This is due in part to quantum limited, Josephson-junction based parametric amplifiers (JPAs), which are able to enhance qubit signals while adding the minimum amount of noise and backaction, allowed by quantum mechanics [3]. Because of these properties, JPAs have become a ubiquitous component in superconducting quantum machines. Although parametric amplifiers regularly achieve near-quantum limited performance, they have many limitations, including low saturation powers, lack of directionality, and narrow bandwidth. The first is believed to stem from the higher order Hamiltonian terms endemic to Josephson junction circuits, and the latter two are direct consequences of the nature of the parametric interactions which power them. In this work, we attack both of these issues. First, we have designed a new, linearly shunted Josephson ring modulator (JRM), which nearly nullifies all fourth-order terms at a single flux bias point. Next, we achieve gain through a pair of balanced parametric drives. When applied separately, these drives produce phase-preserving gain (G) and gainless photon conversion (C); when applied together, the resultant amplifier (which we term GC) is a bidirectional, phase-sensitive, transmission-only amplifier with a large, gain-independent bandwidth. Finally, we have demonstrated the practical utility of the GC amplifier, as well as its quantum efficiency, by using it to read out a superconducting transmon qubit.

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of higher order Hamiltonian terms in the JRM. Notably, unshunted [26] and Josephson-junction shunted JRMs [14,27] have fourth-order self- and/or cross-Kerr terms at all bias fluxes. These terms cause the amplifier’s mode frequencies to shift with applied pump power, making biasing the GC mode of operation, which requires far more intense pumps than G or C alone, extremely difficult. By operating our kinetic-inductance shunted JRM at a bias point which nearly nulls all Kerr terms in the device simultaneously, we have demonstrated 21 dB of phase-sensitive gain (15 dB of phase-preserving gain), with a greatly enhanced bandwidth. To demonstrate the viability of this mode of operation in practical quantum information experiments, we used the GC amplifier to measure a transmon qubit. By strongly measuring the qubit, we were able to perform high fidelity qubit readout. We also performed deliberately weak measurement experiments to determine the device’s quantum efficiency.

II. THEORY OF THE GC AMPLIFIER AND THE NULLING OF THE FOURTH-ORDER TERMS

The block diagram describing our scheme for qubit measurement and signal amplification is shown in Fig. 1(a). The qubit resides inside the measurement cavity, which has two ports, a strong port and a weak port. The weak port (on the left) is used for driving the cavity and qubit while the strong port (on the right) is used for measuring the qubit. The measurement signal is routed via two circulators, which ensure that the reverse amplified quantum noise and reflected signals from the amplifier do not travel backward to the qubit. The JPC’s output is further amplified by a cryogenic high-electron-mobility transistor (HEMT) amplifier before being recorded at room temperature. The scattering matrix of the GC amplifier is shown in Fig. 1(b). Signals entering a port are reflected with unity gain and transmitted with phase-sensitive gain, whose amplified quadrature is determined by the phases of the applied pumps.

The effective circuit diagram of our inductively shunted JRM is depicted in Fig. 2(a). The key ingredients of the model are (1) the Josephson junctions, (2) the shunt inductors labeled $L_{\text{shunt}}$, and (3) the stray inductance on the outer arms of the JRM, labeled $L_{\text{out}}$. In this setup, the outer ring of the JRM, which contains the Josephson junctions, is the source of the nonlinear couplings between the modes of the JPC. The shunt inductors are used to control the degeneracy of the ground state of the JPC at finite magnetic flux bias. They lift the energy of states in which current flows through the shunt inductors, thus preventing the device from switching to these undesired configurations. The stray inductors are an inherent property of the aluminum traces which we use to make the outer ring of our JRM.

The circuit is described by the Hamiltonian $H_{\text{JRM}} = H_{\text{shunt}} + H_{\text{out}}$, composed of the shunt Hamiltonian

$$H_{\text{shunt}} = \sum_{i=1}^{4} \frac{\phi_{0}^2}{2L_{\text{shunt}}} (\varphi_i - \varphi_E)^2,$$

(1)

and the outer ring Hamiltonian

$$H_{\text{out}} = \sum_{i=1}^{4} H_{\text{seg}}(\varphi_{i+1} - \varphi_i - \varphi_{\text{ext}}/4).$$

(2)

Here, $\varphi_i$ is the superconducting phase at the $i$th vertex of the JRM [see Fig. 2(a)], we use the notation $\varphi = \varphi_1$ [28], and $\varphi_E$ is the phase at the middle point which is constrained by the outer node phase by $\varphi_E = \sum_{j=1}^{4} \varphi_j/4$. The phase gain due to the externally applied flux bias in each of the four outer arms of the JRM is $\varphi_{\text{ext}}/4 = (2e/h) \Phi_{\text{ext}}/4$. The energy of an outer ring segment phase biased to $\varphi$ is

$$H_{\text{seg}}(\varphi) = \min_{\chi} \frac{\phi_{0}^2}{2L_{\text{out}}} (\varphi - \chi)^2 - E_J \cos(\chi).$$

(3)

and the minimization with respect to $\chi$ results in a transcendental equation that ensures that the current in the outer inductor is identical to the current in the Josephson junction.

Next, we analyze the nonlinear couplings between the JPC modes. Here, we focus on the case in which the JPC has a nondegenerate ground state centered on $\varphi_1 = \varphi_2 = \cdots = 0$. In this case, the phases at the JRM vertices can be expressed in terms of the canonical variables $\varphi_a, \varphi_b,$ and $\varphi_c$ that correspond to the $a, b,$ and $c$ eigenmodes of the JPC:

$$\{\varphi_1, \varphi_2, \varphi_3, \varphi_4\} = \{\varphi_a + \lambda_1 \varphi_c, \varphi_b - \lambda_2 \varphi_c, -\varphi_a + \lambda_1 \varphi_c, -\varphi_b - \lambda_2 \varphi_c\}.$$
respectively. The two cancellation points (where the plot remains white for all pump powers) are indicated with vertical dashed black lines.

The coefficients \( \lambda_1 = C_1/\sqrt{C_1^2 + C_2^2} \) and \( \lambda_2 = C_1/\sqrt{C_1^2 + C_2^2} \) come from the JPC eigenmode analysis and their values depend on the capacitors added to the JRM to make the JPC; see Appendix B. We obtain the nonlinear couplings between the normal modes of the JPC by taking derivatives of \( H_{\text{JRM}} \) with respect to the canonical variables. For the self- and cross-Kerr terms, we find

\[
K_{aa} = \frac{1}{4!} \frac{\partial^4 H_{\text{JRM}}}{\partial \varphi_a^4} = \frac{1}{6} \frac{H_{\text{seg}}^{(4)}(\varphi_{\text{ext}}/4)}{C_{\text{seg}}} = K_{bb} = K_{cc}, \tag{5}
\]

\[
K_{ab} = \frac{1}{4} \frac{\partial^2 H_{\text{JRM}}}{\partial \varphi_a \partial \varphi_b} = \frac{H_{\text{seg}}^{(4)}(\varphi_{\text{ext}}/4)}{C_{\text{seg}}} = K_{ac} = K_{bc}. \tag{6}
\]

Observe that all of the Kerr terms are proportional to the fourth derivative of \( H_{\text{seg}}(\varphi) \) with respect to \( \varphi \) evaluated at \( \varphi = \varphi_{\text{ext}}/4 \). The cosine Hamiltonian of the junction means that the Kerr naturally passes through zero, if the desired flux configuration holds to the required flux. Moreover, all six Kerr terms vanish identically at a single null point. In the absence of stray inductance (i.e., \( L_{\text{out}} \to 0 \)), the null occurs at \( \varphi_{\text{ext}} = 2\pi \); the null point persists and shifts toward \( \varphi_{\text{ext}} = 4\pi \) as \( L_{\text{out}} \to 0 \) increases (see Appendix A).

We now introduce two dimensionless parameters that we will use to characterize our circuits. The first parameter, \( \beta = E_{\text{shunt}}/E_J = L_J/L_{\text{shunt}} = \phi_0^2/L_{\text{shunt}} E_J \), measures the strength of the shunt inductors relative to the effective inductance of Josephson junctions [28]. We note that \( \beta = 0 \) is the case when the JRM is unshunted. To see this, in an unshunted-JRM model, the center node and the inner shunted linear inductance are fictitious; i.e., there should be no energy contribution from these linear inductors, which means \( E_{\text{shunt}} = 0, \beta = 0 \).

The second parameter, \( \alpha = L_{\text{out}}/L_J = L_{\text{out}} E_J/\phi_0^2 \), measures the strength of the Josephson junction with respect to the stray inductance, preferably \( \alpha \ll 1 \) to ensure that the Josephson energy dominates the stray inductance. At the same time, \( \beta \) should be sufficiently large to ensure that \( \varphi_1 = \varphi_2 = \cdots = 0 \) is the global minimum of \( H_{\text{JRM}} \) and hence the JPC has a single, well-defined ground state at the null point. For the case \( \alpha = 0 \), the nondegeneracy of the ground state for all values of \( \varphi_{\text{ext}} \) is ensured by setting \( \beta > 4 \). As \( \alpha \) increases, so does the minimum required value of \( \beta \) (we address these requirements by analyzing the degeneracy of the ground state in Appendix A).

A similar analysis of the JRM with Josephson-junction-based shunts (as in Refs. [14,27]) shows that the cross-Kerr terms null together at a similar point to our linearly shunted JRM, but the self-Kerr null point is shifted to a larger flux. As the behaviors of the various Kerr terms are very similar in their effect on device performance, the junction-shunted JRM ring will not realize the benefits of a linearly shunted JRM but will instead perform essentially no differently from the unshunted version. We have also found, in both theory and experiment, that asymmetries in junction critical current and applied bias flux to the JRM’s four loops must be minimized, as they can cause substantial difference in the flux response, and hence Kerr nulling, of the JRM.

III. EXPERIMENT

We form a JPC by embedding the JRM at the intersection of two, single-ended microstrip resonators, as in Ref. [14]. The target parameters, junction \( I_0 = 2 \mu A \beta > 4 \) and \( \alpha \ll 1 \), were fabricated using either meandering shunt inductances [29,30] or kinetic-inductance shunts. We achieved superior control using kinetic-inductance shunts, due to the smaller physical size, and hence smaller \( \alpha \) due to reduced stray inductance on the outer arms of the JRM.

To fabricate our JRM, we first sputter a film of 10-nm-thick NbTiN onto a polymethyl methacrylate (PMMA) mask on which a cross with arm widths and lengths of 2 and 15 \( \mu m \) respectively, has been patterned. The PMMA layer is subsequently lifted off with acetone. The resulting shunt inductors have \( L_{\text{shunt}} \approx 75 \, \mu H \), about five times their geometric value.

Next, standard double-angle aluminum deposition is used to create the outer ring of the JRM. As NbTiN does not form a native oxide, good contact to the upper (aluminum) portion of the circuit is achieved with only a standard, gentle argon-oxygen cleaning step prior to deposition of the first layer of aluminum.
In order to characterize the self- and cross-Kerr terms for a given mode or pair of modes, a pump tone is applied that is fixed 5 line widths away from the resonant frequency, while a second, weak tone is swept through the mode’s resonant frequency with a vector network analyzer (VNA) (see Appendix C). The Kerr amplitude is seen as a shift in resonant frequency with increasing pump power [16]. The cancellation points at which the resonant frequency remains fixed is shown in Fig. 2(c). In subsequent qubit measurements, the frequency of the qubit cavity was tuned with an aluminum screw to align with the most fourth-order free point of our JPC.

Next, we identified the mode $a$ and $b$ frequencies, which are 7.4668 and 4.8715 GHz respectively, and pumped at their sum, tuning the applied pump power to achieve 20-dB gain in reflection (G). We repeated the process with the pump at the difference frequency (C), tuning the applied pump power to find a 20-dB dip in reflection. These bias powers are each very close to the critical values and tell us the room-temperature ratio of applied microwave powers required to balance the G and C processes. We next tuned the applied pump frequencies until they linked to identical idler frequencies in transmission through the device.

Turning on both drives simultaneously achieves GC amplification. We control GC gain by increasing or decreasing both pumps simultaneously while maintaining the ratio established above. Measured GC amplification gain strengths between 8 and 15 dB, along with reflection performance, are shown in Fig. 3(a). All transmission gain curves are measured with a VNA. An external mixer at the difference frequency converts device outputs from the idler mode back to the input, signal-mode, frequency. The VNA is sensitive only to a single frequency, thus all gains shown are phase preserving, and so for large gains, the phase-preserving gain peak sits about 6 dB below the phase-sensitive gain of the device, so that the maximum phase-sensitive gain for the 15.5-dB curve (which we will use for qubit readout) is 21.5 dB. Above 10-dB gain, the frequency of the pump tones had to be adjusted slightly to account for the imperfectly nulled higher order terms, which shifted the device’s modes, and hence, the frequency of peak gain, to lower frequencies. At the same time, the reflection curves at this higher power start to show small disturbances away from unity [see Fig. 3(a)]. For clarity in these experiments, the amplifier is shifted slightly below the cavity frequency, which is evident as a notch to the right of the gain peaks.

The other notable property of GC amplification is that unlike a single parametric process, the gain of GC is a linear function of the (matched) pump powers for each parametric process. We have compared the theory of pump power for each parametric to the actual pump power applied to the device as shown in Fig. 12.

The other crucial feature of these gain curves is that they demonstrate the same bandwidth regardless of gain [see Fig. 3(b)]. We compare these bandwidths with the standard 20 dB for one single pump amplification process represented by the black dashed curve. The GC amplifier shows 14 MHz of phase-preserving bandwidth. In contrast, a singly pumped gain response of 20 dB only has a bandwidth of 2.33 MHz in the same device. This bandwidth is approximately 6 times larger, in good agreement with theory.

We also show a spectrum analyzer (received power) trace when the GC amplifier is driven with a fixed tone 5 MHz detuned above its center frequency in Fig. 3(c). The presence of a symmetrically detuned idler tone below the center frequency is a clear demonstration of the phase-sensitive nature of this device’s gain.

The performance of dynamic range (see Fig. 11 in Appendix E) still experiences the effect of fourth-order terms and this might be due to having residual inherent Kerr terms and dynamic Kerrs generated by pumps as mentioned in Ref. [17,32]. Furthermore, the saturation power can still be
affect by even higher order terms even though we operate the device at the nulling points.

To demonstrate that our Kerr-nulled, GC pumped device is a practical, quantum-limited amplifier, we also performed phase-sensitive strong or projective measurements on a superconducting transmon qubit. All further qubit measurements are performed in the configuration shown in Fig. 1(a). The qubit is first prepared in the superposition state $|\Psi\rangle = (|g\rangle + |e\rangle)/\sqrt{2}$, and we determined the optimal alignment of the device’s amplified quadrature by finding the largest separation between ground and excited states when projective measurement is performed, as shown in Fig. 4(a). Rotating the relative pump phase by 180 deg from this optimal point moves the signal to the squeezed quadrature, so that the $|g\rangle$ and $|e\rangle$ states overlap, as seen in Fig. 4(b). Both histograms contain 80,000 measurements. We also measured spontaneous quantum jumps between the $|g\rangle$ and $|e\rangle$ state when the phase was rotated to the optimal alignment and the cavity was driven for 7.5 $\mu$s, as shown in Fig. 4(c).

Finally, we calculate the quantum efficiency of our amplifier via the back-action of deliberately weak measurements on the qubit’s state, as in Refs. [6,31]. The pulse sequence is detailed in Appendix D. For phase-sensitive amplification, only one microwave quadrature can be received at room temperature. In a qubit measurement, this confines the back-action to a single plane on the Bloch sphere, determined by which quadrature is amplified. To calibrate our quantum efficiency ($\eta$), we use the amplifier aligned as in Fig. 4(b), resulting in a pure back-action on the qubit’s phase, shown in Fig. 5. We found that our quantum efficiency was $\eta = 55\%$, in good agreement with the efficiency of the device when operated as a singly pumped, phase-preserving amplifier. We quote efficiency, rather than readout fidelity, as the figure of merit for the amplifier as the latter quantity involves a number of factors (such as qubit $T_1$ and insertion loss between cavity and amplifier), which are unrelated to virtues of GC amplification. The device used in this work was also chosen to have a modest bandwidth ($\approx 20$ MHz) to reduce the required pump powers for GC operation. Although the bandwidth was more than sufficient to amplify our qubit cavity, in future work we will open the bandwidth allow for multiple qubits to be read out in a single device.

This work suggests numerous avenues for future improvements of parametric amplifiers. First, by extending the number of pumps to six, while keeping the number of modes at three, we can retain the benefits of GC pumping scheme and achieve directional amplification [18]. Second, we should continue to explore the wealth of potential parametric driving schemes, which may yield devices with further improved performance. Finally, by continuing to fine-tune the engineered Hamiltonian of our JRMs we can enhance the saturation power of our device [16,32].

ACKNOWLEDGMENTS

C.L. acknowledges support from a Pittsburgh Quantum Institute graduate student fellowship. This work was supported by NSF Grant No. PIRE-1743717. Research was also sponsored by the Army Research Office and was accomplished under Grants No. W911NF-18-1-0144 and 042336-5.
FIG. 5. (a) Histogram of weak measurement protocol with orthogonal alignment (Q-quadrature amplified) to determine quantum efficiency of the GC amplifier. Each plot contains 80 000 measurements. (b)–(d) Conditional expectation values of $X/Y/Z$ after weak measurement plotted vs measurement outcomes. Sinusoidal oscillation in both $X$ and $Y$ are a nonclassical stochastic Ramsey process. Together with the nearly constant outcomes for $Z$, these plots show how an orthogonally aligned measurement provides a “kick” around the equator of the Bloch sphere.

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APPENDIX A: THE DEGENERACY OF THE GROUND STATE OF THE JPC

In this section, we analyze the degeneracy of the ground states of the shunted JPC for two cases: without and with the stray inductors. Specifically, to find the degeneracy of the ground state we count the number of global minima of $H_{\text{JRM}}$.

We first consider the JPC without stray inductors, i.e., $L_{\text{out}} = 0$, $\alpha = 0$. We numerically find the global minima of the JRM Hamiltonian by forming a set of possible minimum points by randomly seeding a numerical minimum with initial values of $\varphi_1$, $\varphi_2$, $\varphi_3$, and $\varphi_4$. From this set, we select the minima that correspond to smallest values of $H_{\text{JRM}}$, and finally throw away repeated points. In Fig. 6(a), we plot the degeneracy of the JRM ground state as we sweep the external magnetic flux and the shunting parameter $\beta$. The blue region in the plots corresponds to conditions under which the JRM has a single global minimum (the JPC has a nondegenerate ground state), while the orange and red regions corresponds to doubly and quadruply degenerate ground states.

As we decrease the inductance of the shunts, states with circulating currents move up in energy, and hence the ground-state degeneracy is lifted. In other words, larger $\beta$ corresponds to less degeneracy. In the absence of stray inductors, all even-order terms (beyond second order) in $H_{\text{JRM}}$ become zero when the external magnetic flux bias is set to $2\pi$. We find that at this flux bias the ground state is nondegenerate for $\beta > 1.0$ (minimum requirement for operation of the nulled JPC). Additionally, we find that the ground state is nondegenerate for all values of the magnetic flux bias when $\beta > 4.0$.

Next, we take stray inductance into account. The stray inductors increase the inductance of the segments of the

FIG. 6. (a) The degeneracy of the ground state without stray inductance. In this figure, we sweep the shunt parameter $\beta$ and external magnetic flux $\varphi$. The blue, orange, and red regions show the parameter regimes that the JRM ground state is nondegenerate, twofold degenerate, and fourfold degenerate, respectively. The nondegenerate regime is considered as stable. The red, blue, and black lines show the phase boundaries between stable and twofold regions, stable and fourfold regions, and twofold and fourfold regimes, respectively. Also, without stray inductance, all nulling points are at $\pm 2\pi$. (b) The JRM’s ground-state degeneracy with stray inductors. We fix $\beta = 4.5$, and calculate the ground-state degeneracy as we sweep the stray parameter $\alpha$ and external magnetic flux $\varphi_{\text{ext}}$. The green line in panel (b) shows the position of the nulling point. The nulling point shifts (denoted by the green line) to higher external magnetic flux as we increase the stray parameter $\alpha$ and finally hit the unstable regime. (See discussion in the main text.)
Eigenmodes: The modes connections is shown in Fig. 7(a). In order to simplify our analysis, we begin by making the assumption that \( \alpha \) (close to our experimental parameters) and sweep the parameter \( \beta \) (as compared the case \( \alpha = 0 \)). In Fig. 6(b), we fix \( \beta = 4.5 \) (close to our experimental parameters) and sweep the parameter \( \alpha \) and external magnetic flux \( \varphi_{\text{ext}} \). We notice that as we increase \( \alpha \), the region of degenerate ground states reappears (near maximal magnetic flux bias). Further, we observe that as we increase \( \alpha \) the Kerr nulling point moves from \( \varphi_{\text{ext}} = 2\pi \) toward \( \varphi_{\text{ext}} = 3.5\pi \), at which point it hits the degenerate ground-state region (corresponding to \( \alpha \approx 0.4 \)).

**APPENDIX B: THE EIGENMODES OF THE JPC**

In this subsection, we discuss the JPC circuit and identify its eigenmodes. The effective circuit diagram without input-output connections is shown in Fig. 7(a). In order to simplify our analysis, we begin by making the assumption that \( L_{\text{shunt}} \to 0 \). We will lift this assumption at the end.

In order to find the eigenmodes of the JPC, we construct the equations of motion (EOM) by applying Kirchhoff’s law to the circuit. We follow the standard prescription for superconducting circuits: relating voltage to the normalized flux (i.e., the superconducting phase) on each of the nodes via

\[
\dot{\varphi}_j = \frac{1}{\phi_0} V_j(t) \Leftrightarrow \varphi_j(t) = \frac{1}{\phi_0} \int_{-\infty}^t [V_j(t')]dt',
\]

and the supercurrent to the normalized flux via

\[
J_j = \frac{1}{\phi_0} \frac{\partial H_{\text{JRM}}}{\partial \varphi_j},
\]

where \( \phi_0 = \hbar/(2e) \) is the reduced magnetic flux quantum. The resulting equations of motion are

\[
\begin{align*}
2C_1 \phi_0^2 \dot{\varphi}_1 + E_1 \left[ \sin \left( \varphi_1 - \varphi_2 + \frac{\varphi_{\text{ext}}}{4} \right) - \sin \left( \varphi_4 - \varphi_1 + \frac{\varphi_{\text{ext}}}{4} \right) \right] + \frac{\phi_0^2}{L_{\text{shunt}}} (\varphi_1 - \varphi_5) &= 0, \\
2C_4 \phi_0^2 \dot{\varphi}_2 + E_1 \left[ \sin \left( \varphi_2 - \varphi_3 + \frac{\varphi_{\text{ext}}}{4} \right) - \sin \left( \varphi_1 - \varphi_2 + \frac{\varphi_{\text{ext}}}{4} \right) \right] + \frac{\phi_0^2}{L_{\text{shunt}}} (\varphi_2 - \varphi_5) &= 0, \\
2C_2 \phi_0^2 \dot{\varphi}_3 + E_1 \left[ \sin \left( \varphi_3 - \varphi_4 + \frac{\varphi_{\text{ext}}}{4} \right) - \sin \left( \varphi_2 - \varphi_3 + \frac{\varphi_{\text{ext}}}{4} \right) \right] + \frac{\phi_0^2}{L_{\text{shunt}}} (\varphi_3 - \varphi_5) &= 0, \\
2C_3 \phi_0^2 \dot{\varphi}_4 + E_1 \left[ \sin \left( \varphi_4 - \varphi_1 + \frac{\varphi_{\text{ext}}}{4} \right) - \sin \left( \varphi_3 - \varphi_4 + \frac{\varphi_{\text{ext}}}{4} \right) \right] + \frac{\phi_0^2}{L_{\text{shunt}}} (\varphi_4 - \varphi_5) &= 0, \\
\varphi_5 &= \frac{1}{4} (\varphi_1 + \varphi_2 + \varphi_3 + \varphi_4).
\end{align*}
\]

We can linearize the EOMs by expanding around the minimum energy configuration of the JRM (that we found in previous section). We now focusing on the nondegenerate configurations of interest: \( \varphi_1 = \varphi_2 = \varphi_3 = \varphi_4 = \varphi_5 = 0 \). In this case, \( \varphi_i \)’s can...
be regarded as small perturbations away from the JRM minimum point. The resulting linearized equations of motion are

\[
\begin{align*}
\ddot{\varphi}_1 + \frac{E_j}{2C_1\phi_0^2} \cos\left(\frac{\varphi_{\text{ext}}}{4}\right)[2\varphi_1 - \varphi_2 - \varphi_4] + \frac{1}{8C_1L_{\text{shunt}}}(3\varphi_1 - \varphi_2 - \varphi_3 - \varphi_4) &= 0, \\
\ddot{\varphi}_2 + \frac{E_j}{2C_2\phi_0^2} \cos\left(\frac{\varphi_{\text{ext}}}{4}\right)[2\varphi_2 - \varphi_3 - \varphi_1] + \frac{1}{8C_2L_{\text{shunt}}}(3\varphi_2 - \varphi_1 - \varphi_3 - \varphi_4) &= 0, \\
\ddot{\varphi}_3 + \frac{E_j}{2C_3\phi_0^2} \cos\left(\frac{\varphi_{\text{ext}}}{4}\right)[2\varphi_3 - \varphi_4 - \varphi_2] + \frac{1}{8C_3L_{\text{shunt}}}(3\varphi_3 - \varphi_1 - \varphi_2 - \varphi_4) &= 0, \\
\ddot{\varphi}_4 + \frac{E_j}{2C_4\phi_0^2} \cos\left(\frac{\varphi_{\text{ext}}}{4}\right)[2\varphi_4 - \varphi_1 - \varphi_3] + \frac{1}{8C_4L_{\text{shunt}}}(3\varphi_4 - \varphi_1 - \varphi_2 - \varphi_3) &= 0.
\end{align*}
\]

(B4)

Making the additional assumption that \(C_1 = C_2\) and \(C_3 = C_4\), we find that the resulting eigenvalue and eigenstate pairs are

\[
\omega_0^2 = 0 \{1, 1, 1, 1\},
\]

(B5)

\[
\omega_2^2 = \frac{E_j}{C_1\phi_0^2} \cos\left(\frac{\varphi_{\text{ext}}}{4}\right) + \frac{1}{2C_1L_{\text{shunt}}} \{1, 0, -1, 0\},
\]

(B6)

\[
\omega_0^2 = \frac{E_j}{C_3\phi_0^2} \cos\left(\frac{\varphi_{\text{ext}}}{4}\right) + \frac{1}{2C_3L_{\text{shunt}}} \{0, 1, 0, -1\},
\]

(B7)

\[
\omega_0^2 = \left(\frac{1}{C_1} + \frac{1}{C_3}\right) \frac{E_j}{\phi_0^2} \cos\left(\frac{\varphi_{\text{ext}}}{4}\right) + \frac{1}{4L_{\text{shunt}}} \frac{[C_3, -C_1, C_3, C_1]}{\sqrt{C_1^2 + C_3^2}},
\]

(B8)

where \(\omega_0\) is a zero mode that does not couple with the rest of the modes in the Hamiltonian. The nontrivial modes \(\varphi_a, \varphi_b,\) and \(\varphi_c\) are sketched in Fig. 7(b).

We now put the stray inductors back into the circuit. In doing so, we introduce four nodes between the stray inductors and the Josephson junctions on each arm. Because there are no kinetic terms associated with these nodes (as we neglect the capacitances to these nodes), the resulting Kirchhoff equations give us four more constraints:

\[
\frac{E_j}{\phi_0} \sin\left(\varphi_j - \delta_j + \frac{\varphi_{\text{ext}}}{4}\right) = \frac{\phi_0}{L_{\text{ext}}} \delta_j - \varphi_{j+1},
\]

(B9)

where \(\delta_j\) is the phase at the node between the stray inductor and the Josephson junction on the \(j\)th arm of the JRM (see Fig. 2).

In order to linearize the equations of motion, we must first find the values of \(\delta_j\)s at the minimum energy configuration of the JRM. These correspond to the solution of the transcendental equation

\[
\frac{E_j}{\phi_0} \sin\left(-\delta_j^{(0)} + \frac{\varphi_{\text{ext}}}{4}\right) = \frac{\phi_0}{L_{\text{ext}}} \delta_j^{(0)}.
\]

(B10)

We set \(\Delta = -\delta_j^{(0)} + \frac{\varphi_{\text{ext}}}{4}\) and use Eq. (B9) to obtain an expression for the first order correction to \(\delta_j\) in terms of \(\varphi_j\) and \(\varphi_{j+1}\):

\[
\delta_j^{(1)} = \frac{\varphi_j \alpha \cos(\Delta) + \varphi_{j+1}}{1 + \alpha \cos(\Delta)}.
\]

(B11)

We now eliminate \(\delta_j^{(1)}\) from the linearized equations of motion to obtain

\[
\begin{align*}
\ddot{\delta}\varphi_1 + \frac{E_j}{2C_1\phi_0^2} \cos\Delta(2\delta\varphi_1 - \delta\varphi_2 - \delta\varphi_4) + \frac{1}{8C_1L_{\text{shunt}}}(3\delta\varphi_1 - \delta\varphi_2 - \delta\varphi_3 - \delta\varphi_4) &= 0, \\
\ddot{\delta}\varphi_2 + \frac{E_j}{2C_2\phi_0^2} \cos\Delta(2\delta\varphi_2 - \delta\varphi_1 - \delta\varphi_3) + \frac{1}{8C_2L_{\text{shunt}}}(3\delta\varphi_2 - \delta\varphi_1 - \delta\varphi_3 - \delta\varphi_4) &= 0, \\
\ddot{\delta}\varphi_3 + \frac{E_j}{2C_3\phi_0^2} \cos\Delta(2\delta\varphi_3 - \delta\varphi_2 - \delta\varphi_4) + \frac{1}{8C_3L_{\text{shunt}}}(3\delta\varphi_3 - \delta\varphi_2 - \delta\varphi_3 - \delta\varphi_4) &= 0, \\
\ddot{\delta}\varphi_4 + \frac{E_j}{2C_4\phi_0^2} \cos\Delta(2\delta\varphi_4 - \delta\varphi_1 - \delta\varphi_3) + \frac{1}{8C_4L_{\text{shunt}}}(3\delta\varphi_4 - \delta\varphi_1 - \delta\varphi_2 - \delta\varphi_3) &= 0.
\end{align*}
\]

(B12)

Comparing Eqs. (B4) and (B12), we observe that the effect of stray inductors is a renormalization of the Josephson energy \(E_j \rightarrow E_j (1 + \alpha \cos(\Delta))\). This renormalization results in a shift of the eigenfrequencies but the eigenmodes remain identical.
FIG. 8. (a) Visualization of how to measure self-Kerr. We prepare a pump tone that is five times the linewidth away from the mode frequency and observe the shift of the mode frequency. (b) Visualization of how to measure cross-Kerr. Similarly, for the cross-Kerr, we monitor the change of mode frequency on mode \( a \) while varying the strength on the pump tone which is five linewidths away from mode \( b \). (c) Effective Kerr terms. We fit the data acquired in this protocol to a polynomial function of applied drive power, and the linear coefficient of the function, which we recorded as MHz/Watt of driving power at room temperature, is proportional to the relevant Kerr term of the Hamiltonian.

APPENDIX C: MEASUREMENT OF KERR TERMS

We need to quantify the strength of the Kerr terms inherent to our amplifier in order to find when they go to zero. To do this, we perform self-Kerr and cross-Kerr duffing sweeps across a wide range of flux. The self-Kerr terms, \( a \dagger a a \dagger a \) and \( b \dagger b b \dagger b \), can be measured by applying a strong pump tone five linewidths (here 125 MHz from the mode \( a \) and 100 MHz from the mode \( b \)) away from the respective resonant frequencies as shown in Fig. 8(a). We then sweep the flux and the pump power and measure the detuning from the resonant frequencies. In Fig. 2(c), we plot negative detuning in red and positive in blue which allows us to quickly identify where these terms go to zero, since zero detuning, representing no fourth-order effects, is plotted in white. The cross-Kerr, \( a \dagger ab \dagger b \), is measured similarly, but this time we apply a tone five linewidths away from the mode \( a \) and measure the effect of the mode \( b \), as seen in Fig. 8(b). With a high enough pump power, it becomes easy to distinguish the red and blue regions, and thus, the crossing zone in the middle where the specific fourth-order term goes to zero. This flux bias point as shown Fig. 2(c), is represented by a dotted black line. For each bias current result, we can fit it to the polynomial function and the linear term of the fitting result is proportional to the Kerr. By fitting all bias currents, all Kerr terms as a function of the bias current can be extracted and is shown in Fig. 8(c).

Our recent work in Ref. [32] has complicated this picture. When the geometric inductance introduced from microstrips that form the \( \lambda/2 \) resonators is taking into account, nulling points for the self- and cross-Kerrs appear at slightly different points. Moreover, the dynamic Kerr which is generated by strong pump tones also affects the measurement of Kerr [17]. However, we can still use this method and identify the best operating point where all Kerr terms are minimized.

APPENDIX D: BACK-ACTION ON THE QUBIT FOR WEAK AMPLIFICATION

In addition to being an essential component to the measurement chain used to read out superconducting qubits, parametric amplification can be used to manipulate them as well. For instance, the back-action associated with parametric amplification can perform the essential function of remotely entangling distant qubits. It can also be used as an accurate, self-calibrating way to determine measurement efficiency. These types of measurements will be vital in identifying and eliminating the effects which limit our ability to manipulate quantum systems.

FIG. 9. (a) Histogram of weak measurement protocol with optimal alignment (\( I \) quadrature amplified) to determine quantum efficiency of the GC amplifier. Each plot contains 80 000 measurements. [(b)-(d)] Conditional expectation values of \( X/Y/Z \) after weak measurement plotted vs measurement outcomes. These plots show how an optimally aligned measurement provides a “kick” around the \( Y-Z \) plane of the Bloch sphere.
FIG. 10. Pulse sequence for quantifying measurement back-action. We first strongly read out the qubit and record the outcome, which will be used to prepare the qubit in the ground state by postselection. Then, the qubit is rotated by the +y axis and measured with a variable measurement strength, and the outcome is recorded. The final tomographs, phase measures the $x$, $y$, or $z$ component of the qubit Bloch vector with a strong measurement pulse.

In Fig. 5, we apply second measurement strength to be five times (in voltage) smaller than that of strong measurement while GC is operated at orthogonal phase. The histogram shows sinusoidal oscillation in both $X$ and $Y$ are a nonclassical stochastic Ramsey processes. The expectation value of $Z$ is affected by qubit’s relaxation and leads to the slightly red color instead of complete white. With the same procedure but squeezing the $Q$ quadrature instead, we change the qubit’s motion to be confined to the $Y$-$Z$ plane; see Fig. 9.

The standard way to perform back-action measurement is shown in Fig. 10. We first strongly read out the qubit and record the outcome, which will be used to prepare the qubit in the ground state with state selection. Then the qubit is rotated by the $+y$ axis and measured with a variable measurement strength, and the outcome is recorded again. For the final tomography, phase measures the $x$, $y$, or $z$ component of the qubit with a strong measurement pulse.

If we take the qubit to originally be oriented along the $Y$ axis and the $I$ quadrature to be perfectly squeezed, the back-action corresponds to stochastic, trackable motion of the qubit state in the $x$-$y$ plane, with the extent of the motion varying with the strength of the measurement. For weak strength, the back-action looks like a stochastic rotation in the $x$-$y$ plane with the degree of rotation encoded in $Q_m$.

APPENDIX E: SATURATION POWER

The amplifier’s saturation behavior was measured as shown in Fig. 11. Although operated with much higher pump powers, this dynamic range is virtually identical to singly pumped phase-preserving and phase-sensitive gain at the same Kerr nulling point. This points to conventional pump depletion not limiting the device. In a separate work, we have concluded that still higher order nonlinearities can contribute strongly to gain saturation and must be controlled to realize amplifiers with superior dynamic range [32].

APPENDIX F: GAIN VERSUS PUMP POWER

Here we record the pump power used to achieve gain on resonance for different parametric processes, as shown in Fig. 12. The pump power is normalized to the critical power, $P_\infty$, which point where the gain of a singly pumped, phase-preserving gain diverges [12]. The curved dashed line is the single pump process theory prediction that allowed us
to extract $P_{\infty}$. The red dots are the experimental pump power applied to the device for different gains. In contrast, the linear dashed line is the prediction of GC amplification as a function of pump power for individual (matched) pumps G and C.

We note it shows no divergence. For 5-dB GC gain, G and C pump strength have to be about $P_{\infty}$. To reach 20-dB GC gain, each pump power has to be around 10 times stronger than $P_{\infty}$.

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