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PROBABILISTIC ANALYSIS OF THE UPWIND SCHEME FOR TRANSPORT

FRANÇOIS DELARUE$^{1,2}$ AND FRÉDÉRIC LAGOUTIÈRE$^{1,3}$

Abstract. We provide a probabilistic analysis of the upwind scheme for $d$-dimensional transport equations. We associate a Markov chain with the numerical scheme and then obtain a backward representation formula of Kolmogorov type for the numerical solution. We then understand that the error induced by the scheme is governed by the fluctuations of the Markov chain around the characteristics of the flow. We show, in various situations, that the fluctuations are of diffusive type. As a by-product, we recover recent results due to Merlet and Vovelle [13] and Merlet [12]: we prove that the scheme is of order $1/2$ in $L^\infty(\mathbb{R}^d)$ for an initial datum in BV($\mathbb{R}^d$) and of order $1/2 - \varepsilon$, for all $\varepsilon > 0$, in $L^\infty([0,T] \times \mathbb{R}^d)$ for an initial datum in $W^{1,\infty}(\mathbb{R}^d)$. Our analysis provides a new interpretation of the numerical diffusion phenomenon.

Résumé. Nous proposons une analyse probabiliste du schéma upwind pour les équations de transport en dimension $d$ quelconque. Pour cela, nous associons au schéma une chaîne de Markov qui nous permet d’obtenir une formule de représentation de type Kolmogorov pour la solution numérique. Nous comprenons alors que l’erreur due au schéma est gouvernée par les fluctuations de la chaîne de Markov autour des caractéristiques du transport. Nous montrons, dans des situations diverses, que ces fluctuations sont de type diffusif. Comme conséquence, nous retrouvons des résultats récents de Merlet et Vovelle [13] et Merlet [12]: nous montrons que le schéma upwind est d’ordre $1/2$ dans $L^\infty([0,T], L^1(\mathbb{R}^d))$ pour une donnée initiale dans $BV(\mathbb{R}^d)$, et d’ordre $1/2 - \varepsilon$ pour tout $\varepsilon > 0$ pour une donnée initiale dans $W^{1,\infty}(\mathbb{R}^d)$. Cette analyse donne une interprétation nouvelle du phénomène de diffusion numérique.

Key words and phrases. Upwind scheme; transport equation; Markov chain; backward Kolmogorov formula; central limit theorem; diffusive behavior; martingale.

MSC(2000). Primary : 35L45, 65M15; secondary: 60J10, 60G42, 60F05.

1. Introduction

This paper provides a new analysis of the upwind scheme for the transport problem in dimension $d \in \mathbb{N} \setminus \{0\}$

\begin{equation}
\left\{
\begin{array}{l}
\partial_t u(t, x) + \langle a(x), \nabla u(t, x) \rangle = 0, \quad (t, x) \in [0, T] \times \mathbb{R}^d, \\
u(0, x) = u^0(x), \quad x \in \mathbb{R}^d.
\end{array}
\right.
\end{equation}

$^1$ Université Paris Diderot-Paris 7. E-mail: delarue@math.jussieu.fr, lagoutie@math.jussieu.fr
$^2$ CNRS, UMR 7599, Laboratoire de Probabilité et Modèles Aléatoires, F-75252, Paris, France.
$^3$ CNRS, UMR 7598, Laboratoire Jacques-Louis Lions, F-75005, Paris, France.
We assume \( a \) to be Lipschitz continuous, so that (1.1) is well-posed. Several different regularity assumptions are made on \( u^0 \) in the following, among which \( u^0 \in W^{1,\infty}(\mathbb{R}^d) \) and \( u^0 \in BV(\mathbb{R}^d) \). In any case, the unique solution to (1.1) is \( u(t, x) = u^0(Z(t, x)) \) where \( Z \) is the backward characteristic, i.e. the solution of

\[
\begin{cases}
\partial_t Z(t, x) = -a(x), & (t, x) \in [0, T] \times \mathbb{R}^d, \\
Z(0, x) = x, & x \in \mathbb{R}^d.
\end{cases}
\]  

The upwind scheme is a standard method to solve this problem in an approximate way (see for instance [6]). It is derived and described in Section 2 below.

In dimension 1, the scheme is known to be first order consistent (with respect to the maximal cell diameter \( h \)) with the transport equation. Thus, it is first order convergent, for any \( u^0 \in C^2(\mathbb{R}^d) \), provided that a Courant-Friedrichs-Lewy (CFL) stability condition holds. For non-smooth initial data, the upwind scheme is just of order 1/2. This loss of convergence order is traditionally attributed to the dissipative character of the scheme. Up to now, the use of the word “dissipative” has been justified by the following fact: on a uniform mesh, the scheme is second order consistent with an advection-diffusion equation, the diffusion coefficient being first order with respect to \( h \); as a consequence, the numerical error at time \( t \) is proportional to \( \sqrt{th} \) for a non-smooth initial datum.

In this paper, we provide another explanation of the diffusive behavior, which is valid on any general mesh in dimension \( d \). We here interpret the numerical diffusion by means of a stochastic process. Let us briefly describe the basic idea. The approximate value given by the upwind scheme in a cell \( K \) at time step \( n+1 \) is a convex combination of the approximate values at time step \( n \) in the cells neighboring \( K \):

\[
u_{K}^{n+1} = \sum_{L \in T} p_{K,L} u_{L}^{n},
\]

where \( T \) is the set of cells, and \( p_{K,L} \in [0, 1] \) with \( \sum_{L \in T} p_{K,L} = 1 \) (see Section 2 for the complete definition of the scheme). This convex combination allows a probabilistic interpretation: we can define a random sequence of cells \( (K_n)_{n \in \mathbb{N}} \) as a Markov chain with probability transition, from \( K \) to \( L, p_{K,L} \). In this framework, the upwind scheme appears as the expectation of a random scheme associated with the chain \( (K_n)_{n \geq 0} \). Precisely, the value \( u_{K}^{n} \) is the expectation of the value of \( u^0 \) in the cell \( K_n \) when \( K \) is chosen as the starting cell of the chain. In a probabilistic way, we write:

\[
u_{K}^{n} = \mathbb{E}_{K} \left( u_{K_n}^{0} \right),
\]

the symbol \( K \) in the notation \( \mathbb{E}_{K} \) meaning that \( K_0 = K \). (See Theorems 3.1 and 4.1.) In the theory of stochastic processes, the above identity is a backward Kolmogorov formula: it is the analogue of the representation formula of the heat equation by the Brownian motion. We then understand the chain \( (K_n)_{n \geq 0} \) as a random backward characteristic.

Our main idea consists in analyzing the behavior of the random characteristic according to the following program. The first point is to show that the mean trend of the random characteristic coincides with the exact characteristic \( Z \), solution to (1.2). The next step is to understand that the error of the numerical scheme is governed by the fluctuations of the random characteristic around the exact one. Heuristically, the order of the fluctuations is given by the central limit theorem: therefore, we expect them to be controlled, in a suitable
sense, by $Ch^{1/2}$ where $C$ only depends on the datum $a$ and the time $t$. The final step is to derive the 1/2 order of the scheme.

Applying this program, we establish the 1/2 order in $L^\infty([0, T], L^1(\mathbb{R}^d))$ for $u^0 \in BV(\mathbb{R}^d)$. (See Theorem 5.10.) For $u^0 \in W^{1,\infty}(\mathbb{R}^d)$, we also prove that the scheme is of order $1/2 - \varepsilon$ in $L^\infty([0, T], L^\infty(\mathbb{R}^d))$ for all $\varepsilon > 0$. (See Theorem 5.9.) In this last case, it is clear that 1/2 is an upper bound (see [9], and [19] for the non-linear case), but the exact convergence order remains unknown. The reason why our estimate is better in the $L^1$-in space norm may be explained as follows. Estimating the error in $L^1$ amounts to average the initial cell of the random characteristic. This additional averaging reduces the weight of the trajectories of the chain that are away from $Z$.

Since the pioneering article of Kuznetsov [1], in which the 1/2 order is established in the Cartesian framework (for linear and non-linear scalar equations), many papers have dealt with the rate of convergence of the upwind scheme. Let us briefly review them.

For general scalar equations with a datum $u^0 \in BV(\mathbb{R}^d)$, Cockburn, Coquel and Le Floch [4], Vila [21], [2] and Chainais-Hillairet [3] prove the (non-optimal) 1/4 order in $L^\infty([0, T], L^1(\mathbb{R}^d))$ under slightly different hypotheses (and for several schemes, including the upwind one).

For hyperbolic Friedrichs systems, Vila and Villedieu [22] derive a 1/2 order estimate in the $L^2([0, T] \times \mathbb{R}^d)$ norm for $H^1(\mathbb{R}^d)$ initial data.

In the frame of the linear transport equation, which we are involved in, Desprès [5] proves a 1/2 order estimate in the $L^\infty([0, T], L^2(\mathbb{R}^d))$ norm in the case of $H^2(\mathbb{R}^d)$ data. His proof relies on a precise study of the consistency of the scheme after several time steps. (It is indeed known that the scheme is not consistent at each time step on a general mesh.) For $C^2$ initial data, Bouche, Ghidaglia and Pascal [1] show the order 1 in the $L^\infty$ norm, under a condition on the mesh that is related to consistency. At last, in recent works,

- for an initial datum in $BV(\mathbb{R}^d)$, Merlet and Vovelle [13] show the optimal estimate of order 1/2 in the $L^\infty([0, T], L^1(\mathbb{R}^d))$ norm,
- for a Lipschitz continuous initial datum, Merlet [12] shows the order $1/2 - \varepsilon$, for any $\varepsilon > 0$, in the $L^\infty$ norm.

It is thus understood that our paper provides a new proof of the results obtained in [13] and [12]. Actually, our framework is slightly different since we do not assume the velocity $a$ to be divergence-free, as done therein, but we assume it to be independent of time. We think that this does not make fundamental differences. Despite the similarity of our results, we insist on the fact that the arguments here are completely different. As said above, our proofs rely on the analysis of the stochastic characteristic $(K_n)_{n\geq 0}$ (that shall mimic the exact characteristic $Z$). In particular, we do not use energy estimates. (Except those of Desprès and Bouche et al. based on the consistency of the scheme, all the papers mentioned above are built on energy or entropy estimates).

Our paper is organized as follows. In Section 2, we state the framework of our analysis. In Section 3, we focus on the one-dimensional case to introduce, with great care, the notion of stochastic characteristic. By the way, we establish a refined estimate of the order of the scheme in the specific case where the velocity is constant and the mesh is regular. (See Proposition 3.3). In Section 4, we extend the probabilistic interpretation of the upwind scheme to the higher dimensional setting. We then provide a direct proof of the 1/2 order in $L^\infty([0, T], L^1(\mathbb{R}^d))$ in the following simple case: $u^0$ is assumed to be periodic, as well as
the mesh, and Lipschitz continuous. This section is the heart of the paper. Refining the strategy, we finally obtain in Section 6 the announced results. This last part is a bit more technical and relies on a concentration inequality for martingales, which is given in Annex, see Section 8.

2. Framework and useful notations

Let \( \{K\}_{K \in \mathcal{T}} \), the mesh, be a set of closed polygonal subsets of \( \mathbb{R}^d \) with non-empty disjoint interiors such that \( \mathbb{R}^d = \bigcup_{K \in \mathcal{T}} K \). The volume (\( d \)-Lebesgue measure) of a given cell \( K \in \mathcal{T} \) is denoted by \( |K| \). The supremum of the diameters of all the cells is denoted by \( h \), i.e. \( h = \sup_{K \in \mathcal{T}} \text{diam}(K) \). Two cells \( K \) and \( L \) are said adjacent if they aren’t disjoint but have disjoint interiors. In this case, we write \( K \sim L \). We assume that, for all pairs \((K, L)\) of adjacent cells, the intersection \( K \cap L \) is included in a hyperplane of \( \mathbb{R}^d \). The surface ((\( d - 1 \))-Lebesgue measure) of the face \( K \cap L \) is then denoted by \( |K \cap L| \).

Let \( \Delta t > 0 \) be the time step of the method. The value \( u^n_K \) intends to approximate the mean value of \( u(n\Delta t, \cdot) \) in the cell \( K \). The upwind scheme provides a way to compute such \( u^n_K \). It is easily obtained by integrating the divergence form of the PDE in (1.1), \( \partial_t u + \text{div}(au) - u\text{div}(a) = 0 \), over \([n\Delta t, (n+1)\Delta t] \times K \). We get

\[
(2.1) \quad \int_K u((n+1)\Delta t, x)dx - \int_K u(n\Delta t, x)dx + \sum_{L \sim K} \int_{K \cap L} \int_{n\Delta t}^{(n+1)\Delta t} \langle a(x), n_{K,L} \rangle u(t, x)dtdx - \int_K \int_{n\Delta t}^{(n+1)\Delta t} u(t, x)\text{div}(a)(x)dtdx = 0,
\]

where \( n_{K,L} \) is the unit normal vector on \( K \cap L \) outward from \( K \). From a numerical point of view, it then seems natural to compute both an approximate value \( u^n_K \) of the mean of \( u(n\Delta t, \cdot) \) in cell \( K \), i.e.

\[
u^n_K \approx |K|^{-1} \int_K u(n\Delta t, x)dx,
\]

and an approximate value \( u^n_{K,L} \) of the mean of \( u \) on the edge \( K \cap L \) between the time steps \( n \) and \( n + 1 \), i.e.

\[
u^n_{K,L} \approx \Delta t^{-1}|K \cap L|^{-1} \int_{K \cap L} \int_{n\Delta t}^{(n+1)\Delta t} u(t, x)dtdx.
\]

The quantity \( u^n_{K,L} \) is called the numerical flux. Defining \( a_{K,L} \) as the mean value of \( a \) on the edge \( K \cap L \), i.e.

\[
a_{K,L} = |K \cap L|^{-1} \int_{K \cap L} a(x)dx,
\]

we get the following approximate version of (2.1),

\[
|K| \frac{u^{n+1}_K - u^n_K}{\Delta t} + \sum_{L \sim K} \langle a_{K,L}, n_{K,L} \rangle |K \cap L|u^n_{K,L} - u^n_K \sum_{L \sim K} \langle a_{K,L}, n_{K,L} \rangle |K \cap L| = 0.
\]

The upwind scheme considers the numerical fluxes \( u^n_{K,L} \) as upwinded: \( u^n_{K,L} = u^n_K \) for \( L \in K^+ \) and \( u^n_{K,L} = u^n_L \) for \( L \in K^- \) with

\[K^+ = \{ L \sim K, \langle a_{K,L}, n_{K,L} \rangle > 0 \}, \]

\[K^- = \{ L \sim K, \langle a_{K,L}, n_{K,L} \rangle < 0 \}.
\]
This finally gives

\[
|K| \frac{u_{K}^{n+1} - u_{K}^{n}}{\Delta t} + \sum_{L \in K^{-}} \langle a_{K,L}, n_{K,L} \rangle |K \cap L| (u_{L}^{n} - u_{K}^{n}) = 0, \quad (n, K) \in \mathbb{N} \times \mathcal{T}.
\]

The numerical initial condition is usually taken as

\[
u_{0}^{K} = \frac{1}{\Delta x_{K}} \int_{K} u^{0}(x) \, dx.
\]

It is straightforward that the scheme satisfies the maximum principle under the condition

\[- \sum_{L \in K^{-}} \frac{\langle a_{K,L}, n_{K,L} \rangle |K \cap L|}{|K|} \leq 1, \quad K \in \mathcal{T}.
\]

This condition is called the Courant-Friedrichs-Lewy (CFL for short) condition and is assumed to be satisfied in all the paper.

3. Analysis in Dimension 1

For pedagogical reasons, we first investigate the one-dimensional framework. As announced in Introduction, the velocity field \(a : \mathbb{R} \to \mathbb{R}\) is assumed to be bounded and to be \(\kappa\)-Lipschitz continuous. In particular, for any starting point \(x \in \mathbb{R}\), the characteristic equation starting from

\[
\frac{\partial}{\partial t} Z(t, x) = -a(Z(t, x)), \quad t \geq 0, \quad Z(0, x) = x,
\]

admits a unique solution. Denoting by \(u^{0}\) the initial condition of the transport equation, which is assumed to be \(\kappa\)-Lipschitz continuous in the whole section, the solution of the transport equation rewrites

\[
u(t, x) = u^{0}(Z(t, x)), \quad (t, x) \in \mathbb{R}_{+} \times \mathbb{R}.
\]

In this section devoted to dimension 1, for every cell \(K \in \mathcal{T}\), the volume (length) of \(K\) is denoted \(\Delta x_{K}\). The edge value of \(a\) is defined as \(a_{K,L} = a(K \cap L)\). The constants “\(C\)” and “\(c\)” used below only depend on \(\|a\|_{\infty}\) and \(\kappa\). They are always independent of \(\Delta t\), of \(h = \sup_{K \in \mathcal{T}} \Delta x_{K}\), of the time index \(n\) and of the random outcome \(\omega\). In particular, the notation \(O(x)\), for a given variable \(x\), denotes a quantity bounded by \(C x\) for some constant \(C\) only depending on \(\|a\|_{\infty}\) and \(\kappa\).

3.1. Probabilistic Interpretation. In the one-dimensional framework, the scheme has the form

\[
u_{0}^{K} = \frac{1}{\Delta x_{K}} \int_{K} u^{0}(x) \, dx, \quad K \in \mathcal{T},
\]

\[
u_{K}^{n+1} = - \sum_{L \in K^{-}} \frac{a_{K,L} \Delta t}{\Delta x_{K}} u_{L}^{n} + (1 + \sum_{L \in K^{-}} \frac{a_{K,L} \Delta t}{\Delta x_{K}}) u_{K}^{n}, \quad n \geq 0, \quad K \in \mathcal{T},
\]

and the following CFL condition is assumed to be in force

\[- \sum_{L \in K^{-}} \frac{a_{K,L} \Delta t}{\Delta x_{K}} \leq 1, \quad K \in \mathcal{T}.
\]

The geometry of the mesh is simple: each cell \(K\) has two neighbors. When the velocity field \(a\) is non-zero in the cell \(K\), there is one and only one cell \(L\) in \(K^{-}\). If \(a\) is positive in \(K\), it is the left one; of course, if \(a\) is negative, it is the right one.
We focus for a while on a given cell $K$. By the CFL condition (3.4), all the coefficients

$$p_{K,L} = -\frac{a_{K,L} \Delta t}{\Delta x_K} \quad \text{for } L \in K^{-},$$

$$p_{K,K} = 1 + \sum_{L \in K^{-}} \frac{a_{K,L} \Delta t}{\Delta x_K},$$

$$p_{K,L} = 0 \quad \text{for } L \in \mathcal{T} \setminus (K^{-} \cup K),$$

are non-negative and may be seen as probability weights. Henceforth, for a given time step $n \geq 0$, the right-hand side in (3.3) may be interpreted as an expectation with respect to these weights:

$$u_{K}^{n+1} = \sum_{L \sim K} p_{K,L} u_{L}^{n}.$$

Intuitively, this means that we are choosing one cell among $K \cup \{L \sim K\}$, $K$ being fixed, with the probability weights $p_{K,K}$ and $p_{K,L}$ for $L \sim K$. To make this idea rigorous, we introduce a probability space $(\Omega, \mathcal{A}, \mathbb{P})$ as well as a random variable $\xi : \Omega \rightarrow K \cup \{L \sim K\}$ such that $\mathbb{P}\{\xi = L\} = p_{K,L}$ for any $L \sim K$ and $\mathbb{P}\{\xi = K\} = p_{K,K}$. Then, the $(n+1)^{th}$ step of the numerical scheme on the cell $K$ can be written in the following way:

$$u_{K}^{n+1} = \sum_{L \sim K} p_{K,L} u_{L}^{n} = \mathbb{E}\left[u_{\xi}^{n}\right].$$

This relationship provides a probabilistic interpretation for the one step dynamics of the numerical scheme. We are to iterate this procedure.

The probabilistic dynamics between times $n$ and $n+1$ just depend on the starting cell $K$. In the theory of stochastic processes, this property is typical of Markovian dynamics. Indeed, the family of probability weights $(p_{K,L})_{K,L \in \mathcal{T}}$ defines a stochastic matrix of infinite dimension (all the entries of the matrix are non-negative and the sums of the entries of a same line are all equal to 1). This stochastic matrix corresponds to the transition matrix of a Markov chain. Up to a modification of the underlying probability space, there exists a sequence $(K_{n})_{n \geq 0}$ of random variables taking values into the set of cells as well as a collection of probability measures $(\mathbb{P}_{K})_{K \in \mathcal{T}}$, indexed by the cells, such that, under each $\mathbb{P}_{K}$, $(K_{n})_{n \geq 0}$ is a Markov chain with rates $(p_{K,L})_{K,L \in \mathcal{T}}$ starting from $K_{0} = K$. In other words,

$$\forall n \geq 0, \mathbb{P}_{K}\{K_{n+1} = L|K_{n} = K\} = p_{K,L}, \mathbb{P}_{K}\{K_{0} = K\} = 1.$$ 

The behavior of the chain $(K_{n})_{n \geq 0}$ is as follows: if the velocity is positive in the cell $K_{n}$, then the probability $p_{K_{n},L}$ vanishes if $L$ is the right neighbor of $K_{n}$, so that the chain can either stay in $K_{n}$ or jump to the left.

Now, we can interpret (3.3) in a different way:

$$u_{K}^{n+1} = \mathbb{E}_{K}\left[u_{K_{1}}^{n}\right],$$

where $\mathbb{E}_{K}$ denotes the expectation associated with $\mathbb{P}_{K}$. This means that $u_{K}^{n+1}$ is the expectation of $u^{n}$ in the random cell $K_{1}$ occupied by the Markov chain, which started one time step before in $K$. We can also write for any integer $i \geq 0$

$$u_{K_{i}}^{n+1} = \mathbb{E}_{K}\left[u_{K_{i+1}}^{n}|K_{0}, \ldots, K_{i}\right] \quad \mathbb{P}_{K}\text{–almost surely}.$$ 

(When conditioning with respect to $K_{0}, \ldots, K_{i}$, the past before $i - 1$ doesn’t play any role, and the chain restarts, afresh, at time $i$ from $K_{i}$.) In what follows, we denote the conditional
expectation $\mathbb{E}_K[\cdot|K_0,\ldots,K_n]$ by $\mathbb{E}^n_K[\cdot]$. We also omit to specify that such a conditional expectation is computed under $\mathbb{P}_K$. Now, we are able to iterate the procedure in (3.3):

$$u^{n+1}_K = \mathbb{E}_K[u^n_{K_1}] = \mathbb{E}_K[\mathbb{E}_K^{1}[u^{n-1}_{K_2}]]$$

$$= \cdots = \mathbb{E}_K[\mathbb{E}_K^{1}[\cdots \mathbb{E}_K^n[u^0_{K_{n+1}}]\cdots]] = \mathbb{E}_K[u^0_{K_{n+1}}].$$

We have proved the following representation for the numerical solution $u^n$:

**Theorem 3.1.** Under the above notations, the numerical solution $u^n_K$ at time $n$ and in the cell $K$ has the form:

$$u^n_K = \mathbb{E}_K[u^0_{K_n}].$$

The representation given by Theorem 3.1 is a backward Kolmogorov formula for the numerical scheme. Generally speaking, the backward Kolmogorov formula provides a representation for the solution of the heat equation in terms of the mean value of the initial condition computed with respect to the paths of the Brownian motion (or of a diffusion process). In this framework, the paths of the Brownian motion appear as random characteristics. In our own setting, the Markov chain $(K_n)_{n\geq 0}$ almost plays the same role.

We say “almost plays” because the sequence $(K_n)_{n\geq 0}$ is not a sequence of points as the Brownian motion is. Actually, we have to associate with each random cell $K_n$ a random point $X_n$ ($X_n$ being ideally in $K_n$) to obtain a random characteristic $(X_n)_{n\geq 0}$.

The choice of these points is crucial. In what follows, we choose $X_n$ as the entering point in the cell $K_n$. This means that

$$X_n = X_{n-1} \text{ if } K_n = K_{n-1}, \quad X_n = K_n \cap K_{n-1} \text{ if } K_n \neq K_{n-1}.$$  

The above definition holds for $n \geq 1$. The position of the initial point $X_0$ inside $K_0$ has to be specified. If $a(x) > 0$ for all $x \in K_0$, we choose $X_0$ as the right boundary of $K_0$. (Indeed, the right boundary plays in this case the role of the entering point since the velocity is positive.) If $a(x) < 0$ for all $x \in K_0$, we choose $X_0$ as the left boundary. If $\exists x \in K_0$ such that $a(x) = 0$, we choose $X_0$ as the middle of $K_0$.

What is important is that the sequence $(X_n)_{n\geq 0}$ is adapted to the filtration generated by $(K_n)_{n\geq 0}$, i.e. $(\sigma(K_0,\ldots,K_n))_{n\geq 0}$: knowing the paths $(K_0,\ldots,K_n)$, one knows the positions of the points $(X_0,\ldots,X_n)$.

The reader may wonder about this specific choice for the sequence $(X_n)_{n\geq 0}$. Assume that the velocity $a$ is non-zero, say for example positive, in the cell $K_n$. By continuity, it is positive in the neighborhood of $K_n$: the chain goes from the right to the left in this area of the space. As a by-product, the entering point in the cell $K_n$ is the right boundary of $K_n$. In this case, $X_{n+1}$ is either $X_n$ itself or the left boundary of $K_n$, which is the right boundary of $K_n^-$ (this set of cells is in the present case a singleton and we identify it with its element, as well as for $K_n^+$ in the following when the velocity is away from 0), so that

$$\mathbb{E}^n_K[X_{n+1} - X_n] = -\Delta x_{K_n} p_{K_n,K_n^-} = -a_{K_n,K_n} \Delta t.$$  

(Indeed, the probability that $X_{n+1}$ is the right boundary of $K_n^-$ is given by the probability of jumping from $K_n$ to $K_n^-$.) In other words, the mean displacement from $X_n$ to $X_{n+1}$, knowing the past, is exactly driven by the velocity field $-a$. This is very important: loosely speaking, the speed of the random characteristic is given by the velocity field of the characteristic equation itself! Here is a more precise statement.
Proposition 3.2. For every $n \geq 0$,
\[ \mathbb{E}_K^n [X_{n+1} - X_n] = -a(X_n) \Delta t + O(h \Delta t). \]

Proof. If $a(x) > 0$ for all $x \in K_n$, then $X_n$ has to be the right boundary of $K_n$. (By definition of $X_0$, this is true until the first jump of the chain. After the first jump, this is still true since the chain cannot come from the left by positivity of $a$.) Moreover, starting from $K_n$, the chain cannot move to the right since $a_{K_n,K_n^+} = a(X_n) > 0$. Hence, $X_{n+1}$ has to be either $X_n$ or the left boundary of $K_n$. As done above,
\[ \mathbb{E}_K^n [X_{n+1} - X_n] = -\Delta x_{K_n} p_{K_n,K_n^+} = -a_{K_n,K_n^+} \Delta t = -a(X_n) \Delta t + O(h \Delta t) \]
by the Lipschitz property of $a$. The same argument holds when $a(x) < 0$ for all $x \in K_n$.

If $a(x) = 0$ for some $x \in K_n$, then $a(X_n) = O(h \Delta t)$ by the Lipschitz property of $a$. Moreover, the probability of moving to the right is equal to $\max(a_{K_n,K_n^+},0) \times \Delta t / \Delta x_{K_n} = O(\Delta t)$. The same holds for the probability of moving to the left. When moving, the displacement is bounded by $h$ so that the result is still true. \hfill \Box

Remark. The necessity of choosing the point $X_n$ as the entering point in the cell $K_n$ is related to the well-known fact that the upwind scheme is consistent (in the finite difference sense) with the transport equation provided that the control points for every cell are chosen on the right if the velocity is positive and, conversely, on the left if the velocity is negative: see [6].

3.2. A First Example: $a$ and $\Delta x$ constant. To explain our strategy, we first focus on the very simple case where both $a$ and $\Delta x$ are constant: $a(x) = a$ for all $x \in \mathbb{R}$ and $\Delta x_K = h$ for all $K \in T$. Without loss of generality, we can assume that $a$ is positive so that the random characteristic goes from the right to the left. In this setting, the transition probabilities are of the form
\[ \forall K \in T, \quad p_{K,K^-} = \frac{a \Delta t}{h}, \quad p_{K,K} = 1 - \frac{a \Delta t}{h}. \]
The probability of jumping from one cell to another doesn’t depend on the current state of the random walk. From a probabilistic point of view, this amounts to say that the sequence $(X_{n+1} - X_n)_{n \geq 0}$ (with $X_0$ equal to the right boundary of the initial cell) is a sequence of Independent and Identically Distributed (IID in short) random variables under $\mathbb{P}_K$, whatever $K$ is. The common law of these variables is given by
\[ \mathbb{P}_K \{X_{n+1} - X_n = -h\} = 1 - \mathbb{P}_K \{X_{n+1} - X_n = 0\} = \frac{a \Delta t}{h}. \]
In particular, we recover a stronger version of Proposition 3.2 ("stronger" means that there is no $O(h \Delta t)$):
\[ \mathbb{E}_K^n [X_{n+1} - X_n] = -a \Delta t. \]
In particular, the mean trend of the random characteristic is exactly driven by the velocity $-a$, that is by the mapping $t \mapsto X_0 - at$, which corresponds to the characteristic of the transport equation with $X_0$ as initial condition, i.e. $Z(t, X_0)$ (see (3.1)). At this stage, we understand that the order of the numerical scheme is deeply related to the fluctuations of the random characteristic around its mean trend, that is around the deterministic characteristic. Indeed, for any starting cell $K$, we have
\[ u_R^n = \mathbb{E}_K^n [u_0^0] = \mathbb{E}_K^n [u_0^0(X_n)] + O(h), \]
where $O(h)$ only depends on the Lipschitz constant of the initial condition $u^0$ and is independent of the initial cell $K$. Thus

\[(3.6) \quad u^n_K = \mathbb{E}_K \left[ u^0 \left( X_0 - an\Delta t + \sum_{k=0}^{n-1} (X_{k+1} - X_k + a\Delta t) \right) \right] + O(h). \]

By (3.2), for all $x \in K$,

\[
u^n_K - u(n\Delta t, x) = \mathbb{E}_K \left[ u^0 \left( X_0 - an\Delta t + \sum_{k=0}^{n-1} (X_{k+1} - X_k + a\Delta t) \right) \right] - u(n\Delta t, x) + O(h) = \mathbb{E}_K \left[ u^0 \left( X_0 - an\Delta t + \sum_{k=0}^{n-1} (X_{k+1} - X_k + a\Delta t) \right) - u^0(X_0 - an\Delta t) \right] + O(h) = \mathbb{E}_K \left[ u^0 \left( X_0 - an\Delta t + \sum_{k=0}^{n-1} (X_{k+1} - X_k + a\Delta t) \right) - u^0(X_0 - an\Delta t) \right] + O(h).
\]

Using again the Lipschitz continuity of $u^0$, we deduce by the Cauchy-Schwarz inequality that,

\[
\left| u^n_K - u(n\Delta t, x) \right| \leq \kappa \mathbb{E}_K \left[ \sum_{k=0}^{n-1} (X_{k+1} - X_k + a\Delta t) \right] + O(h) \leq \kappa \mathbb{E}_K \left[ \sum_{k=0}^{n-1} (X_{k+1} - X_k + a\Delta t) \right]^{1/2} + O(h)
\]

for all $x \in K$. The last expectation is nothing but the variance of the sum of the random variables $(X_{k+1} - X_k)_{0 \leq k \leq n-1}$ under $\mathbb{P}_K$, i.e.

\[
\mathbb{E}_K \left[ \sum_{k=0}^{n-1} (X_{k+1} - X_k + a\Delta t) \right]^{1/2} = \mathbb{V}_K \left[ \sum_{k=0}^{n-1} (X_{k+1} - X_k) \right].
\]

It is well-known that the variance of the sum of independent random variables is equal to the sum of the variances of the variables. We deduce that, for all $x \in K$,

\[
\left| u^n_K - u(n\Delta t, x) \right| \leq \kappa \left[ \mathbb{V}_K(X_1 - X_0) \right]^{1/2} + O(h).
\]

The common variance is equal to

\[
\mathbb{V}_K(X_1 - X_0) = h^2 p_{K,K} - a^2 \Delta t^2 = a\Delta t(h - a\Delta t).
\]

Note that the CFL condition guarantees that the right-hand side above is non-negative, which ensures that the equality is meaningful. We thus recover a well-known estimate for the $L^\infty$-error induced by the upwind scheme:

**Proposition 3.3.** Assume that $a(x) = a$ and $\Delta x_K$ are constant and that $u^0$ is bounded and $\kappa$-Lipschitz continuous. Then, at any time $n \geq 0$,

\[
\sup_{K \in T} \left\| u^n_K - u(n\Delta t, \cdot) \right\|_{L^\infty(K)} \leq \kappa \left( na\Delta t(h - a\Delta t) \right)^{1/2} + O(h).
\]
3.3. **General Case: \(a(x)\) and \(\Delta x_K\) non constant.** Our strategy is sharp enough to obtain the analogue of Proposition 3.3 when \(a\) does depend on \(x\) and \(\Delta x_K\) on \(K\). The main difference here is that \(X_0\) can be either the right boundary of \(K_0\) or the left boundary or the barycenter of \(K_0\), according to the sign of the velocity in \(K_0\). Following the previous subsection, the difference between the numerical and the true solutions at time \(n \geq 0\) on a cell \(K\) is given by

\[
u_K^n - u(n \Delta t, x) = \mathbb{E}_K[u_{K_n}^0] - u^0(Z(n \Delta t, x)) = \mathbb{E}_K[u_{K_n}^0 - u^0(Z(n \Delta t, x))] \]

for all \(x \in K\). As above, the Lipschitz property yields

\[
u_{K_n}^0 = u^0(X_n) + O(h).
\]

Again, the term \(O(h)\) is uniform with respect to the starting cell \(K\), to the time index \(n\), to the parameters \(\Delta t\) and \(h\) and to the underlying draw \(\omega \in \Omega\). By Gronwall’s lemma, we control the distance between \(Z(n \Delta t, x)\) and \(Z(n \Delta t, X_0)\), so that

\[
|u_K^n - u(n \Delta t, x)| \leq \kappa \mathbb{E}_K[|X_n - Z(n \Delta t, x)|] + O(h)
\]

\[
= \kappa \mathbb{E}_K[|X_n - Z(n \Delta t, X_0)|] + O(h) \exp(\kappa n \Delta t).
\]

We have

\[
X_n - Z(n \Delta t, X_0) = X_n - X_0 + \sum_{k=0}^{n-1} \int_{k \Delta t}^{(k+1) \Delta t} a(Z(s, X_0)) ds.
\]

By Proposition 3.2,

\[
X_n - X_0 = \sum_{k=0}^{n-1} (X_{k+1} - X_k) = -\Delta t \sum_{k=0}^{n-1} a(X_k) + M_n + O(n h \Delta t),
\]

with

\[
M_n = \sum_{k=0}^{n-1} (X_{k+1} - X_k - \mathbb{E}_K^k(X_{k+1} - X_k)) \quad (M_0 = 0).
\]

By the boundedness and the Lipschitz continuity of \(a\),

\[
\sum_{k=0}^{n-1} \int_{k \Delta t}^{(k+1) \Delta t} a(Z(s, X_0)) ds = \Delta t \sum_{k=0}^{n-1} a(Z(k \Delta t, X_0)) + O(n \Delta t^2).
\]

Plugging (3.9) and (3.11) into (3.8), we obtain

\[
|X_n - Z(n \Delta t, X_0)| \leq \kappa \Delta t \sum_{k=0}^{n-1} |X_k - Z(k \Delta t, X_0)| + |M_n| + O(n h \Delta t + n \Delta t^2).
\]

Taking the expectation of each term and applying Gronwall’s lemma,

\[
\mathbb{E}_K[|X_n - Z(n \Delta t, X_0)|] \leq [\mathbb{E}_K[|M_n|] + O(n h \Delta t + n \Delta t^2)] \exp(\kappa n \Delta t).
\]

As in the case where both the velocity and the spatial step are constant, the process \((M_n)_{n \geq 0}\) represents the fluctuations of the random characteristic around a discretized version of the deterministic characteristic. (See (3.10).) In the probabilistic theory, it is a martingale on \((\Omega, \mathcal{A}, \mathbb{P}_K)\), i.e., at any time \(n \geq 0\), \(M_n\) is \(\sigma(K_0, \ldots, K_n)\)-measurable and \(\mathbb{E}_K^n[M_{n+1}] = M_n\). This property just follows from (3.10).
Since \( M_0 = 0 \), the expectation of \( M_n \), for \( n \geq 1 \), is given by \( \mathbb{E}_K[M_n] = \mathbb{E}_K[\mathbb{E}^{n-1}_K(M_n)] = \mathbb{E}_K[M_{n-1}] = \cdots = M_0 = 0 \). The mean trend of a martingale starting from zero is null. To estimate the fluctuations, we compute the second order moment. Setting \( \Delta M_j = M_{j+1} - M_j \) for all \( j \geq 0 \), the martingale property yields \( \mathbb{E}_K[\Delta M_j] = 0 \), so that, for all \( n \geq 1 \),

\[
\mathbb{E}_K(M_n^2) = \sum_{k=0}^{n-1} \mathbb{E}_K[\Delta M_k^2] + 2 \sum_{0 \leq i < j \leq n-1} \mathbb{E}_K[\Delta M_i \Delta M_j]
\]

\[
= \sum_{k=0}^{n-1} \mathbb{E}_K[\Delta M_k^2] + 2 \sum_{0 \leq i < j \leq n-1} \mathbb{E}_K[\mathbb{E}^i_k(\Delta M_i \Delta M_j)]
\]

\[
= \sum_{k=0}^{n-1} \mathbb{E}_K[\Delta M_k^2] + 2 \sum_{0 \leq i < j \leq n-1} \mathbb{E}_K[\Delta M_i \mathbb{E}^i_k(\Delta M_j)]
\]

\[
= \sum_{k=0}^{n-1} \mathbb{E}_K[\Delta M_k^2].
\]

(3.13)

It remains to compute the expectation of the increments \( (\Delta M_k^2)_{k \geq 1} \).

We first prove that \( \mathbb{E}^k_K[\Delta M_k^2] = O(h \Delta t) \). Since \( \Delta M_k = X_{k+1} - X_k - \mathbb{E}^k_K(X_{k+1} - X_k) \), we have (\( \mathbb{V}^k_K \) denotes the conditional variance knowing \( K_0, \ldots, K_n \) under \( \mathbb{P}_K \))

\[
\mathbb{E}^k_K[\Delta M_k^2] = \mathbb{V}^k_K[X_{k+1} - X_k] = \mathbb{E}^k_K[(X_{k+1} - X_k)^2] - \left( \mathbb{E}^k_K[X_{k+1} - X_k] \right)^2
\]

\[
\leq \mathbb{E}^k_K[(X_{k+1} - X_k)^2].
\]

(3.14)

Knowing the position of the chain at time step \( k \), the conditional probability of jumping is bounded by \( (\max(a_{K_k,K_k^-}^-,0) + \max(a_{K_k,K_k^+},0)) \Delta t / \Delta x_{K_n} \). When jumping, the distance between \( X_k \) and \( X_{k+1} \) is always bounded by \( \Delta x_{K_k} \). Hence, \( \mathbb{E}^k_K[(X_{k+1} - X_k)^2] = O(h \Delta t) \). Taking the expectation, we deduce that \( \mathbb{E}_K[\Delta M_k^2] = O(h \Delta t) \).

By (3.13), we deduce

\[
\mathbb{E}_K(M_n^2) = O(nh \Delta t).
\]

By (3.7) and (3.12) and by the Cauchy-Schwarz inequality, we deduce

**Proposition 3.4.** Under the assumptions introduced in the beginning of Section 3, there exists a constant \( C \geq 0 \), such that at any time \( n \geq 0 \),

\[
\sup_{K \in \mathcal{T}} \| u^n_K - u(n \Delta t, \cdot) \|_{L^\infty(K)} \leq C((nh \Delta t)^{1/2} + nh \Delta t + n \Delta t^2 + h) \exp(\kappa n \Delta t).
\]

3.4. **Interpretation by the Central Limit Theorem.** This section only concerns the special case with constant velocity on a uniform mesh. It provides a finer result in this simplified case, by the use of the central limit theorem. This analysis will not be performed in higher dimension. We again assume that \( a(x) = a > 0 \) and \( \Delta x_K \) is constant. We also reinforce the CFL condition, asking \( a \Delta t < h \). (This is not a restriction. When \( a \Delta t = h \), the term of order 1/2 vanishes in Proposition 3.3 and the error is of order 1: this case is trivial.) As explained above, the order of the numerical scheme is given by the order of the fluctuations of the random characteristic around its mean trend. In the specific setting where both \( a \) and \( \Delta x \) are constant, the random characteristic corresponds to a random walk with IID increments: by the elementary theory of stochastic processes, we know that the
fluctuations of the walk around its mean trend are governed by the Central Limit Theorem (CLT in short). (See [18, Chapter III, §3] for the standard version of the CLT and [11, Chapter 2, Theorem 4.20] for the functional version in the case of a simple random walk.) We deduce that the fluctuations are of diffusive type, that is they correspond, asymptotically, to the fluctuations of a Brownian motion around the origin. This means that the random characteristics can be seen, asymptotically, as the paths of a Brownian motion, with a non-standard variance. (That is, the variance of the Brownian motion at time \(t\) isn’t equal to \(t\), but to a constant times \(t\), the constant being independent of \(t\). In our framework, the constant is proportional to \(h\).) From an analytical point of view, we are saying that the numerical solution is very close to the solution of a second order parabolic equation: this is nothing but the numerical diffusive effect.

We specify this idea. The variables \((X_{n+1} - X_n + a\Delta t)_{n \geq 0}\) are IID, with zero as mean and \(a\Delta t(h - a\Delta t)\) as variance. By the CLT, we know that

\[
(3.15) \quad (na\Delta t(h - a\Delta t))^{-1/2} \sum_{k=0}^{n-1} (X_{k+1} - X_k + a\Delta t) \Rightarrow \mathcal{N}(0, 1) \quad \text{as } n \to +\infty,
\]

on each \((\Omega, \mathcal{A}, \mathbb{P}_K), K \in T\). The notation \(\Rightarrow\) stands for the convergence in distribution. (In short, for a family of random variables \((W_n)_{n \in \{0, \ldots, +\infty\}}\) on \((\Omega, \mathcal{A}, \mathbb{P})\), we say that \(W_n \Rightarrow W_\infty\) if \(\mathbb{E}[\varphi(W_n)] \to \mathbb{E}[\varphi(W_\infty)]\) for any bounded continuous function \(\varphi\).) The notation \(\mathcal{N}(0, 1)\) stands for the reduced centered Gaussian law.

Plugging \((3.15)\) into \((3.4)\), we deduce that

\[
w^n_K \approx \mathbb{E}_K \left[ u^0(X_0 - an\Delta t + (na\Delta t(h - a\Delta t))^{1/2}W) \right] + O(h)
\]

for \(n\) large. Above, \(W\) denotes a reduced centered Gaussian random variable. The symbol \(\approx\) means that both sides are close. This point will be specified below.

Expliciting the density of the Gaussian law, we can write

\[
(3.16) \quad \mathbb{E}_K \left[ u^0(X_0 - an\Delta t + (na\Delta t(h - a\Delta t))^{1/2}W) \right] = \int_{\mathbb{R}} u^0(x_{K,K^+} - y) \exp \left[ -\frac{(y - an\Delta t)^2}{2a(h - a\Delta t)n\Delta t} \right] \frac{dy}{[2\pi a(h - a\Delta t)n\Delta t]^{1/2}},
\]

where \(x_{K,K^+}\) stands for the unique point in the intersection of \(K\) and \(K^+\), i.e. the right boundary of the cell \(K\) when \(a > 0\). According to [8, Chapter 1] (with \(a = 0\), the generalization to \(a \neq 0\) being trivial), we recognize the value at time \(n\Delta t\) and at point \(x_{K,K^+}\) of the solution \(v\) to the Cauchy problem:

\[
(3.17) \quad \partial_t v + a\partial_x v - \frac{a(h - a\Delta t)}{2}\partial_{xx} v = 0, \quad t \geq 0, \quad x \in \mathbb{R},
\]

with \(u^0\) as initial condition. Finally, we can say that \(u^n_K\) is close to \(v(n\Delta t, \cdot)\) in the cell \(K\).

Of course, we have to say what “close” means! This question is related to the rapidity of convergence in the CLT, that is the rapidity of convergence in \((3.15)\). The main result in this direction is the Berry-Esseen Theorem. (See [18, Chapter III, §11].) In what follows, we use a refined version of it. (See [13, Chapter V, §4, Theorem 14].) Denoting by \(F_n\) the cumulative distribution function

\[
\forall z \in \mathbb{R}, \quad F_n(z) = \mathbb{P}_K \left\{ \left( na\Delta t(h - a\Delta t) \right)^{-1/2} \sum_{k=0}^{n-1} (X_{k+1} - X_k + a\Delta t) \leq z \right\},
\]

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and by \( \Phi \) the cumulative distribution function of the \( \mathcal{N}(0, 1) \) law, we have, for all \( z \in \mathbb{R} \),

\[
|F_n(z) - \Phi(z)| \leq C n^{-1/2} (a \Delta t(h - a \Delta t))^{-3/2} \mathbb{E}_K [|X_1 - X_0 + a \Delta t|^3] (1 + |z|)^{-3},
\]

for some universal constant \( C > 0 \). The moment of order three is given by

\[
\mathbb{E}_K [|X_1 - X_0 + a \Delta t|^3] = \frac{a \Delta t}{h} (h - a \Delta t)^3 + \left(1 - \frac{a \Delta t}{h}\right)(a \Delta t)^3
\]

\[
= a \Delta t \left(1 - \frac{a \Delta t}{h}\right) [(h - a \Delta t)^2 + (a \Delta t)^2].
\]

Hence, for all \( z \in \mathbb{R} \),

\[
(3.18) \quad |F_n(z) - \Phi(z)| \leq C (na \Delta t(h - a \Delta t))^{-1/2} h^{-1} [(h - a \Delta t)^2 + (a \Delta t)^2] (1 + |z|)^{-3}.
\]

By (3.6),

\[
u^n_K = \int_{\mathbb{R}} u^0(x_{K,K+} - an \Delta t + (na \Delta t(h - a \Delta t))^{1/2} y) dF_n(y) + O(h),
\]

where the integral in the right-hand side is a Lebesgue-Stieltjes integral. (See [18, Chapter II, §6].)

Assume for a while that the support of \( u^0 \) is compact. Performing an integration by parts (see [18, Chapter II, §6, Theorem 11]), we obtain (since \( u^0 \) is Lipschitz continuous)

\[
u^n_K = (na \Delta t(h - a \Delta t))^{1/2} \int_{\mathbb{R}} \frac{du^0}{dy}(x_{K,K+} - an \Delta t + (na \Delta t(h - a \Delta t))^{1/2} y) F_n(y) dy + O(h),
\]

Plugging (3.18) in this equality, we obtain

\[
|u^n_K - (na \Delta t(h - a \Delta t))^{1/2} \int_{\mathbb{R}} \frac{du^0}{dy}(x_{K,K+} - an \Delta t + (na \Delta t(h - a \Delta t))^{1/2} y) \Phi(y) dy|
\]

\[
\leq C \kappa h^{-1} [(h - a \Delta t)^2 + (a \Delta t)^2] \int_{\mathbb{R}} (1 + |y|)^{-3} dy + O(h).
\]

Performing a new integration by parts and then a change of variable, we see that the left-hand side is equal to \( |u^n_K - v(n \Delta t, x_{K,K+})| \), where \( v \) is the solution of the Cauchy problem (3.17). Using a standard truncature argument, we can easily get rid of the assumption made on the support of \( u^0 \). We finally claim

**Proposition 3.5.** Assume that \( a(x) \) and \( \Delta x_K \) are constant and that \( u^0 \) is \( \kappa \)-Lipschitz continuous. Then, there exists a constant \( C > 0 \) such that, at time any time \( n \geq 0 \),

\[
\sup_{K \in T} ||u^n_K - v(n \Delta t, \cdot)||_{L^\infty(K)} \leq Ch,
\]

where \( v \) stands for the solution of the Cauchy problem (3.17) with \( u^0 \) as initial condition.

It is remarkable that the bound doesn’t depend on \( (n, \Delta t) \). The result is still true for \( a \Delta t = h \). (See Proposition 3.3.)
4. Principle of the Analysis in higher dimension. Application to a Simple Case

We here present the basic ingredients for the analysis in dimension $d$ greater than two.

As above, the velocity field $a$ is assumed to be bounded and $\kappa$-Lipschitz continuous. The regularity of the initial condition $u^0$ will be specified below.

The characteristics of the transport equation are still denoted by $(Z(t, x))_{t \geq 0}$, $x \in \mathbb{R}^d$, see Equation (1.2).

As in [13], the cells are assumed to be uniformly non flat, i.e. they satisfy, in a strong sense, the converse of the isoperimetric inequality:

\[
\exists \alpha > 0, \forall K \in T, \sum_{L \sim K} |K \cap L| \leq \alpha |K|h^{-1}.
\]

By the standard isoperimetric inequality, this is equivalent to the existence of $\beta > 1$ such that $|K| \geq \beta^{-1} h^d$ and $\sum_{L \sim K} |K \cap L| \leq \beta h^{d-1}$ for all $K \in T$.

The mean velocity on a cell $K$ is denoted by $a_K = \frac{|K|^{-1}}{\int_K a(x)dx} \int_K a(x)dx$.

The constants “$C$” and “$c$” below may depend on $\|a\|_{\infty}$, $\alpha$, $\beta$, $\kappa$ and $d$. As in dimension one, they are always independent of $\Delta t$, of $h$, of the current time index $n$ and of the random outcome $\omega$.

4.1. Stochastic Representation of the Scheme. The expression of $u^n_{K+1}$ given by the upwind Scheme is (see (2.2))

\[
u^n_{K+1} = -\sum_{L \in K^-} \frac{\langle a_{K,L}, n_{K,L} \rangle \Delta t |K \cap L|}{|K|} u^n_L + \left(1 + \sum_{L \in K^-} \frac{\langle a_{K,L}, n_{K,L} \rangle \Delta t |K \cap L|}{|K|} \right) u^n_K,
\]

where $K^- = \{L \sim K, \langle a_{K,L}, n_{K,L} \rangle < 0\}$, $u^0_K$ being given by

\[
u^0_K = \frac{|K|^{-1}}{\int_K u^0(x)dx} \int_K u^0(x)dx.
\]

In this framework, the CFL condition has the form

\[
\forall K \in T, -\sum_{L \in K^-} \frac{\langle a_{K,L}, n_{K,L} \rangle \Delta t |K \cap L|}{|K|} \leq 1
\]

and is assumed to be satisfied in all the following.

As in dimension one, the coefficients

\[
p_{K,L} = -\frac{\langle a_{K,L}, n_{K,L} \rangle \Delta t |K \cap L|}{|K|} \text{ for } L \in K^-,
\]

\[
p_{K,K} = 1 + \sum_{L \in K^-} \frac{\langle a_{K,L}, n_{K,L} \rangle \Delta t |K \cap L|}{|K|},
\]

\[
p_{K,L} = 0 \text{ for } L \in T \setminus (K^- \cup K),
\]

can be interpreted as the probability transitions of a Markov chain with values in the set of cells. Again, we can find a measurable space $(\Omega, \mathcal{A})$, a sequence $(K_n)_{n \geq 0}$ of measurable
mappings from \((\Omega, \mathcal{A})\) into \(\mathcal{T}\) as well as a family \((\mathbb{P}_K)_{K \in \mathcal{T}}\) of probability measures on \((\Omega, \mathcal{A})\), indexed by the cells, such that, for every cell \(K \in \mathcal{T}\), \((K_n)_{n \geq 0}\) is a Markov chain with \(K\) as initial condition and \((p_{K,L})_{K,L \in \mathcal{T}}\) as transition probabilities. As in dimension one, the chain \((K_n)_{n \geq 0}\) goes against the velocity field \(a\): for \(n \geq 0\), either \(K_{n+1}\) is equal to \(K_n\) or \(K_{n+1}\) belongs to \(K_n^\circ\). Similarly, for \(n \geq 1\), either \(K_{n-1}\) is equal to \(K_n\) or \(K_{n-1}\) belongs to \(K_n^\circ\).

Following the analysis performed in dimension 1, we can prove the backward Kolmogorov formula:

**Theorem 4.1.** Under the above notations, the numerical solution \(u^n_K\) at time \(n\) and in the cell \(K\) has the form:

\[
u^n_K = \mathbb{E}_K[u^n_{K_0}].
\]

Due to the strong similarity with the one-dimensional frame, we do not repeat here the proof.

In what follows, for \(K \in \mathcal{T}\), we denote by \(\mathbb{E}^n_K\) the conditional expectation \(\mathbb{E}_K[\cdot | K_0, \ldots, K_n]\).

### 4.2. Random Characteristics

To follow the one-dimensional strategy, we have to associate a sequence \((X_n)_{n \geq 0}\) of (random) points with each path of the Markov chain. In dimension one, the point \(X_n\) is defined as the entering point in the cell \(K_n\). Two points may play this role in the higher dimensional setting: either the barycenter of the entering face \(K_{n-1} \cap K_n\) or the barycenter, with suitable weights, of all the possible entering faces in the cell \(K_n\). For a given cell \(K\), we thus define \(x_{K,L}\) as the barycenter of the face \(K \cap L\) if \(K\) and \(L\) are adjacent:

\[
x_{K,L} = |K \cap L|^{-1} \int_{K \cap L} x\,dx,
\]

and \(e_K\) as the following convex combination of \((x_{K,J})_{J \in K^+}\):

\[
e_K = \left(\sum_{J \in K^+} q_{K,J}\right)^{-1} \sum_{J \in K^+} q_{K,J} x_{K,J},
\]

with

\[
q_{K,J} = \frac{\langle a_{K,J}, n_{K,J}\rangle \Delta t |K \cap J|}{|K|} \quad \text{for } J \in K^+,
\]

\[
q_{K,K} = 1 - \sum_{J \in K^+} \frac{\langle a_{K,J}, n_{K,J}\rangle \Delta t |K \cap J|}{|K|},
\]

\[
q_{K,J} = 0 \quad \text{for } J \in \mathcal{T} \setminus (K^+ \cup K).
\]

We emphasize that the \((q_{K,J})_{J \in \mathcal{T}}\) are, at least in a formal way, the weights associated with the scheme for the velocity \(-a\). We will specify this correspondence below. We also notice that \(e_K\) might be outside \(K\) if \(K\) is not convex. This does not matter for the analysis.

With these notations at hand, we define the random characteristic \(X_n\) as

\[
X_0 = e_{K_0},
\]

\[
X_n = e_{K_n} \text{ if } K_n = K_{n-1}, n \geq 1,
\]

\[
X_n = x_{K_{n-1},K_n} \text{ if } K_n \neq K_{n-1}, n \geq 1.
\]
This definition is quite natural. When \( n = 0 \) or \( K_n = K_{n-1} \), \( n \geq 1 \), \( X_n \) is chosen as a remarkable point of the cell \( K_n \), independently of the past before \( n \). When \( K_n \neq K_{n-1} \), the choice of \( X_n \) expresses the jump from \( K_{n-1} \) to \( K_n \).

4.3. **Green’s Formula.** The result given below explains why the barycenters of the faces are involved in our analysis. The main argument of the proof relies on the Green formula, which has a crucial role in the whole story, as easily guessed from the specific form of the transition probabilities. (See also [1, Proposition 3.1].)

**Proposition 4.2.** Consider a cell \( K \). For any point \( x_0 \) in the convex envelope of the cell (we say convex envelope because of \( e_K \), defined as a barycenter),

\[
a_K \Delta t = - \sum_{L \in K^-} p_{K,L} (x_{K,L} - x_0) + \sum_{J \in K^+} q_{K,J} (x_{K,J} - x_0) + O(h \Delta t).
\]

**Proof.** For an index \( 1 \leq i \leq d \), the Green formula, see [14, Chapter 3, (3.54)], yields \((a_i \text{ and } x_i \text{ stand for the } i^{\text{th}} \text{ coordinate of } a \text{ and } x)\).

\[
\int_K a_i(x) \, dx = - \int_K (x_i - (x_0)_i) \text{div}(a)(x) \, dx + \sum_{L \sim K} \int_{K \cap L} (x_i - (x_0)_i) \langle a(x), n_{K,L} \rangle \, dx.
\]

The left-hand side is equal to \(|K| \langle a_K \rangle_i \). By the regularity of \( a \), the first term in the right-hand side is bounded by \( O(h|K|) \). Similarly, the last term in the right-hand side writes

\[
\sum_{L \sim K} \int_{K \cap L} (x_i - (x_0)_i) \langle a(x), n_{K,L} \rangle \, dx
\]

\[
= \sum_{L \sim K} \langle a_{K,L}, n_{K,L} \rangle \int_{K \cap L} (x_i - (x_0)_i) \, dx + \sum_{L \sim K} \int_{K \cap L} (x_i - (x_0)_i) \langle a(x) - a_{K,L}, n_{K,L} \rangle \, dx
\]

\[
= \sum_{L \sim K} \langle a_{K,L}, n_{K,L} \rangle \int_{K \cap L} (x_i - (x_0)_i) \, dx + O(h^2) \sum_{L \sim K} |K \cap L|.
\]

With (4.1) and (4.2) at hand, we deduce that

\[
\sum_{L \sim K} \int_{K \cap L} (x_i - (x_0)_i) \langle a(x), n_{K,L} \rangle \, dx
\]

\[
= \sum_{L \sim K} \langle a_{K,L}, n_{K,L} \rangle |K \cap L|[x_{K,L} - x_0]_i + O(h|K|).
\]

From (4.0) and (4.7), we claim

\[
a_K \Delta t = \sum_{L \sim K} \langle a_{K,L}, n_{K,L} \rangle \Delta t |K \cap L| (x_{K,L} - x_0) + O(h \Delta t).
\]

This completes the proof. \( \square \)

The following corollary is the multi-dimensional counterpart of Proposition 3.2.

**Corollary 4.3.** For any starting cell \( K \in \mathcal{T} \) (so that we work under \( \mathbb{P}_K \)) and any \( n \geq 0 \),

\[
\mathbb{E}^n_K [X_{n+1} - e_{K_n}] = -a(X_n) \Delta t + O(h \Delta t).
\]
As a simple consequence, when the cell $K_n$ has only one possible entering face (entering means entering for the random characteristic), as it is the case in dimension 1 with $a > 0$, $e_{K_n} = X_n$ and the conditional expectation of the mean displacement $X_{n+1} - X_n$ knowing the past before $n$ is driven by $-a$, as stated in Proposition 3.2.

**Proof.** For $K \in T$ and $n \geq 0$,

\begin{equation}
\mathbb{E}_K^n [X_{n+1} - e_{K_n}] = \sum_{L \in K_n^-} p_{K_n,L} (x_{K_n,L} - e_{K_n}).
\end{equation}

(Indeed, if $K_{n+1} = K_n$, $X_{n+1} = e_{K_n}$.) Applying Proposition 4.2 with $x_0 = e_{K_n}$, we obtain

\begin{equation}
a_{K_n} \Delta t = -\sum_{L \in K_n^-} p_{K_n,L} (x_{K_n,L} - e_{K_n}) + \sum_{J \in K_n^+} q_{K_n,J} (x_{K_n,J} - e_{K_n}) + O(h \Delta t).
\end{equation}

By the very definition of $e_{K_n}$, the second sum in the above right-hand side is zero. Identifying (4.8) and (4.9), we complete the proof. \qed

4.4. **Set of Problems.** Keeping the one-dimensional strategy in mind, we understand that the whole problem now consists in estimating the gap $e_{K_n} - X_n$ for $n \geq 1$. (For $n = 0$, it is zero.)

As said above, $e_{K_n} - X_n$ vanishes when the cell $K_n$ admits only one entering face. Unfortunately, there is no hope to obtain a similar result, or an estimate of the form $e_{K_n} - X_n = O(h \Delta t)$, for a cell $K_n$ of general shape.

The reason is purely geometric and is well-understood on a two-dimensional triangular mesh. Except specific cases, the cardinality of $K^+$, $K$ being a triangle, is either one or two. (See Figure 1 below.)

![Figure 1. Example for the gap $e_{K_n} - X_n$](image-url)

In this picture, the velocity $a$ is constant, oriented from the top to the bottom. The triangles $J_1$, $J_2$ and $L$ have only one entering edge and the triangle $K$ has two entering edges. By Corollary 4.3, the mean displacements in the triangles $J_1$, $J_2$ and $L$ are driven by $-a$. The story is different for $K$. 17
The position of \( e_K \) is determined in the following way: \( e_K \) belongs to the segment \([x_{K,1}, x_{K,2}]\) and, by Proposition 4.2, \( x_{K,L} - e_K \) is parallel to \( a \) (the term \( O(h \Delta t) \) in Proposition 4.2 is zero since \( a \) is constant). Assuming that at time \( n-1 \), \( K_{n-1} = J_1 \) and that, at time \( n \), \( K_n = K \), \( X_n \) is the middle of the edge \( K \cap J_1 \). We understand that, in this case, \( e_{K_n} - X_n \) is of the same order as \( h \).

The key point in our analysis follows from a simple observation: when reversing the velocity field \( a \) in Figure 1, i.e. when changing \( a \) into \( -a \), the triangles with one entering edge turn into triangles with two entering edges and the triangle with two entering edges turns into a triangle with one entering edge. Said in a very naive way, the bad triangle \( K \) for \( a \) becomes a good triangle for \( -a \).

Here is another simple fact: the deterministic characteristics for \( -a \) correspond to the characteristics for \( a \), but reversed in time.

These two observations lead to the following idea: in what follows, we hope to get rid of the remaining gaps \( (e_{K_n} - X_n)_{n \geq 1} \) by reversing the random characteristics.

4.5. Reversing the Markov Chain in the Divergence-Free Setting. As announced above, the weights \( (q_{K,J})_{K,J \in T} \) in (4.4) correspond, at least in a formal sense, to the scheme associated with the velocity field \( -a \). We say “formally” because the CFL condition for the field \( -a \) may fail: as shown below, the term \( q_{K,K} \) may be negative.

However, when \( a \) is divergence-free, the CFL condition holds for \( -a \) and \( q \) is the analogue of \( p \) for the field \( -a \):

**Proposition 4.4.** Assume that \( a \) is divergence-free. Then,

\[
\forall K \in T, \quad \sum_{J \sim K} q_{K,J} = \sum_{L \sim K} p_{K,L},
\]

so that \( q_{K,K} = p_{K,K} \) for every cell \( K \). In particular, the CFL condition holds for \( -a \) and \( q \) is a Markovian kernel, i.e. \( q_{K,J} \geq 0 \) for all \( K, J \in T \) and \( \sum_{J \in T} q_{K,J} = 1 \).

**Proof.** The proof follows again from Green’s formula. Indeed, for every cell \( K \),

\[
(4.10) \quad \int_K \text{div}(a)(x)dx = 0 = \sum_{L \sim K} |K \cap L| \langle a_{K,L}, n_{K,L} \rangle.
\]

The terms in the right-hand side are equal to \(-p_{K,L}|K|/\Delta t\) if \( L \in K^- \) and \( q_{K,L}|K|/\Delta t\) if \( L \in K^+ \). This completes the proof. \( \square \)

In the rest of this section, we assume \( a \) to be divergence-free. The point is to understand the connection between the original Markov chain \( (K_n)_{n \geq 0} \), associated with \( a \), and the Markovian kernel \( (q_{K,J})_{K,J \in T} \). In what follows, we show that, under suitable conditions, the random process obtained by reversing the chain \( (K_n)_{n \geq 0} \) is a Markov chain with \( (q_{K,J})_{K,J \in T} \) as probability transitions.

Reversing a Markov chain is a standard procedure in probability theory. (See e.g. Section 1.9.) The reversed process is always a Markov chain, but the transition probabilities may be highly non trivial and do depend, in almost every case, on time. Anyhow, the law of the reversed chain is easily computable when the chain is initialized with an invariant probability.
Assume for the moment that the chain \((K_n)_{n \geq 0}\) admits an invariant probability \(\nu\), i.e.
there exists a probability \(\nu\) on the set of cells such that
\[
\forall K \in \mathcal{T}, \quad \nu(K) = \sum_{J \in \mathcal{T}} \nu(J)p_{J,K},
\]
and pick the initial cell of the Markov chain randomly, with respect to the probability measure \(\nu\). We then denote the corresponding probability measure on \((\Omega, \mathcal{A})\) by \(P_\nu\) as we did for a deterministic starting cell. Under \(P_\nu\), \(K_0\) is random and its distribution is given by \(\nu\) itself.

The measure \(P_\nu\) may be decomposed along the measures \((P_K)_{K \in \mathcal{T}}\) according to the formula
\[
P_\nu = \sum_{K \in \mathcal{T}} \nu(K)P_K.
\]
By invariance of \(\nu\), \(K_n\) follows, for each \(n \geq 0\), the law \(\nu\), i.e.
\[
\forall n \geq 0, \quad \forall K \in \mathcal{T}, \quad P_\nu\{K_n = K\} = \nu(K).
\]
(See [13, Section 1.7].) Denoting by \((\preceq K^N_0, \ldots, \preceq K^N_N) = (K_N, \ldots, K_0)\) the reversed chain from time \(N\) to time 0, we have, for \(K, J \in \mathcal{T}\) and \(0 \leq n \leq N - 1\),
\[
P_\nu\{\preceq K^N_{n+1} = J|\preceq K^N_n = K\} = \frac{P_\nu\{K^N_{n-n-1} = J, K^N_{n-n} = K\}}{P_\nu\{K^N_{n-n} = K\}} = \frac{\nu(J)}{\nu(K)}p_{J,K},
\]
so that the reversed chain is homogeneous (i.e. the transition probabilities don’t depend on time).

Since the velocity field \(a\) is divergence-free, the transport equation conserves the mass with respect to the Lebesgue measure. In this framework, the Lebesgue measure is invariant for the Markov chain \((K_n)_{n \geq 0}\):

**Proposition 4.5.** Assume that \(a\) is divergence-free. Then, the Lebesgue measure is invariant for the Markov chain, i.e.
\[
\forall K \in \mathcal{T}, \quad |K| = \sum_{J \in \mathcal{T}} |J|p_{J,K}.
\]

**Proof.** For a given cell \(K\), we have
\[
\sum_{J \in \mathcal{T}} |J|p_{J,K} = \sum_{J \in K^+} \langle a_{J,K}, n_{J,K} \rangle \Delta t |J \cap K| + |K| + \sum_{J \in K^-} \langle a_{J,K}, n_{J,K} \rangle \Delta t |J \cap K|.
\]
By (4.10),
\[
\sum_{J \sim K} |K \cap J| \langle a_{J,K}, n_{J,K} \rangle = 0,
\]
since \(a\) is divergence-free. Returning to (4.12), we obtain \(\sum_{J \in \mathcal{T}} |J|p_{J,K} = |K|\).

4.6. **Analysis in the Divergence-Free and Periodic Setting.** The Lebesgue measure is not of finite mass on \(\mathbb{R}^d\), but it is a probability measure on the torus \(\mathbb{R}^d/\mathbb{Z}^d\).

To explain how we make use of time reversal, we thus assume, for the moment, that the problem is periodic, of period one in each direction. (Since the transport is of finite speed, this is not a big deal. Anyhow, the proofs of the main results of the paper, given in the next section, are performed without any periodicity assumption. The current paragraph is purely pedagogical.) This means that both the velocity \(a\) and the mesh are periodic, of period one in each direction of the space.

As a consequence, we can see the Markov chain \((K_n)_{n \geq 0}\) as a Markov chain with values in the set \(\mathcal{T}/\mathbb{Z}^d\), i.e. in the space of classes of cells for the equivalence relation induced by the periodicity. The probability of jumping from the class of the cell \(K\) to the class of the cell
$L$ is given by the rate $p_{K,L}$: by periodicity, this rate doesn’t depend on the choices of $K$ and $L$.

**Proposition 4.6.** Assume that $a$ is divergence-free and that both $a$ and the mesh are periodic of period one in each direction of the space, then the Lebesgue measure on the torus induces an invariant probability for the Markov chain, i.e.

$$\forall K \in \mathcal{T}/\mathbb{Z}^d, \ |K| = \sum_{J \in \mathcal{T}/\mathbb{Z}^d, J \sim K} |J|p_{J,K}.$$  

(For $J \in \mathcal{T}/\mathbb{Z}^d$, we denote by $|J|$ the common volume of all the cells of $J$.)

In particular, by (4.11), the reversed chain has the following transition probabilities

$$\mathbb{P}_\mu \{ \tilde{K}^N_{n+1} = J | \tilde{K}^N_n = K \} = q_{K,J}.$$  

(In the above equality, $\mu$ denotes the Lebesgue measure on the torus. Under $\mathbb{P}_\mu$, the starting class of cells of the chain is chosen according to the Lebesgue measure.)

**Proof.** To check the last assertion, we note that, for two adjacent cells $J$ and $K$, $p_{J,K} > 0$ if and only if $K \in J^-$, that is $J \in K^+$. Hence, $p_{J,K} > 0 \iff q_{K,J} > 0$ and in this case

$$(4.13) \quad q_{K,J} = \frac{|J|}{|K|}p_{J,K},$$

so that the relation is always true (even if one term vanishes). \hfill \Box

We recall the interpretation of Proposition 4.6: the reversed chain (seen as a chain with values in $\mathcal{T}/\mathbb{Z}^d$), when the chain $(K_n)_{n \geq 0}$ is initialized with the Lebesgue measure, is nothing but the chain associated with $-a$.

Before applying Proposition 4.6 to the analysis of the numerical scheme, we have to specify the construction of the random characteristic $(X_n)_{n \geq 0}$ in the periodic setting. In this case, $(X_n)_{n \geq 0}$ is seen as a path in $\mathbb{R}^d$ and not in $\mathbb{R}^d/\mathbb{Z}^d$. This amounts to consider a sequence of representatives $(\hat{K}_n)_{n \geq 0}$ for the chain $(K_n)_{n \geq 0}$. We choose $\hat{K}_0$ as the only representative $K_0^0$ of $K_0$ such that $e_{K_0^0}$ has coordinates in $[0,1)$, that is $\hat{K}_0 = K_0^0$ (and $X_0 = e_{K_0^0}$). For any $n \geq 0$, $\hat{K}_{n+1}$ is the unique representative of $K_{n+1}$ such that $\hat{K}_{n+1} \in (\hat{K}_n)^-$. With this sequence of representatives at hand, we can build up the sequence $(X_n)_{n \geq 0}$ according to (4.13). We are now in position to estimate the gap $e_{\hat{K}_n} - X_n$, $n \geq 1$:

**Proposition 4.7.** Under the assumptions of Proposition 4.6, for any $N \geq 0$ and any $n \in \{0, \ldots, N\}$,

$$\mathbb{E}_\mu [e_{\hat{K}_n} - X_n | K_n, \ldots, K_N] = 0,$$

$\mathbb{E}_\mu$ denoting the expectation under $\mathbb{P}_\mu$. In particular, under $\mathbb{P}_\mu$, the sequence $(\tilde{M}^N_n)_{0 \leq n \leq N}$, given by

$$\tilde{M}^N_0 = \tilde{M}^N_1 = 0, \quad \tilde{M}^N_n = \sum_{k=N-n+1}^{N-1} (e_{\hat{K}_k} - X_k), \quad 2 \leq n \leq N,$$

is a martingale for the backward filtration $(\sigma(K_{N-n}, \ldots, K_N) = \sigma(\hat{K}_N^0, \ldots, \hat{K}_n^0))_{0 \leq n \leq N}$.

**Proof.** We can assume that $1 \leq n \leq N$, since $e_{\hat{K}_0} - X_0 = 0$. We then emphasize that $\hat{K}_n$ isn’t measurable with respect to $\sigma(K_n, \ldots, K_N)$. This is the main difficulty of the proof.
Indeed, \( \hat{K}_n \) depends both on \( K_n \) and on the initial representative of \( K_0 \). Anyhow, the difference \( e_{K_0} - X_n \) doesn’t depend on the representatives chosen for \( K_{n-1} \) and \( \hat{K}_n \).

Indeed, recalling that \( K_0^N \) is the unique representative of \( K_n \) such that \( e_{K_0} \) has coordinates in \([0, 1)\), we can always write

\[
(4.14) \quad e_{K_n} - X_n = \sum_{J \in (K_n)^+} \left( e_{K_n} - x_{K_n,J} \right) 1_{\{K_{n-1} = J\}} = \sum_{J \in (K_0^N)^+} \left( e_{K_0} - x_{K_0,J} \right) 1_{\{K_{n-1} \ni J\}}.
\]

(Above, \( K_{n-1} \ni J \) means that \( J \) is a representative of \( K_{n-1} \).) Hence,

\[
\mathbb{E}_\mu [e_{K_n} - X_n | K_n, \ldots, K_{N}] = \sum_{J \in (K_0^N)^+} \left( e_{K_0} - x_{K_0,J} \right) \mathbb{P}_\mu \{K_{n-1} \ni J | K_n, \ldots, K_N\}.
\]

The probability \( \mathbb{P}_\mu \{K_{n-1} \ni J | K_n, \ldots, K_N\} \) is also \( \mathbb{P}_\mu \{\overline{K}_{n-1}^N \ni J | \overline{K}_0^N, \ldots, \overline{K}_{N-1}^N\} \). By Proposition 4.6, it is equal to \( q_{K_0,J} \). By (1.3), we deduce that \( \mathbb{E}_\mu [e_{\hat{K}_n} - X_n | K_n, \ldots, K_N] = 0 \). By (4.14), we know that \( e_{\hat{K}_{n-1}} - X_{n-1} \) is \( \sigma(K_n, \ldots, K_N) \)-measurable for \( 0 \leq n \leq N - 1 \). We easily deduce the martingale property.

Following (3.12), (3.13), (3.14), we complete the analysis by estimating, under \( \mathbb{P}_\mu \), the fluctuations of the random characteristic around the deterministic characteristic.

**Proposition 4.8.** There exists a constant \( C \geq 0 \) such that, for any \( N \geq 1 \),

\[
\mathbb{E}_\mu \left[ |X_N - Z(N\Delta t, X_0)| \right] \leq C \left[ (N\Delta t)^{1/2} + N\Delta t + N\Delta t^2 \right] \exp(\kappa N\Delta t).
\]

**Proof.** Following the proof of (3.12) and keeping the identity \( e_{K_0} - X_0 = 0 \) in mind, it is sufficient to focus on

\[
X_N - X_0 + \sum_{k=0}^{N-1} a(X_k) \Delta t = \sum_{k=0}^{N-1} (X_{k+1} - e_{\hat{K}_k} + a(X_k) \Delta t) + \sum_{k=1}^{N-1} (e_{\hat{K}_k} - X_k).
\]

It is plain to see that Corollary 4.3 is still true under \( \mathbb{P}_\mu \) (and not under \( \mathbb{P}_K \)), so that

\[
X_N - X_0 + \sum_{k=0}^{N-1} a(X_k) \Delta t = \sum_{k=0}^{N-1} (X_{k+1} - e_{\hat{K}_k} - \mathbb{E}_\mu^k (X_{k+1} - e_{\hat{K}_k})) + \sum_{k=1}^{N-1} (e_{\hat{K}_k} - X_k) + O(N\Delta t).
\]

(Above, \( \mathbb{E}_\mu^k [\cdot] = \mathbb{E}_\mu [\cdot | K_0, \ldots, K_k] \).) Setting, for all \( 0 \leq n \leq N \), \( M_n = \sum_{k=0}^{n-1} (X_{k+1} - e_{\hat{K}_k} - \mathbb{E}_\mu^k (X_{k+1} - X_k)) \) (with \( M_0 = 0 \)), and using the notation introduced in Proposition 4.7, we write

\[
X_N - X_0 + \sum_{k=0}^{N-1} a(X_k) \Delta t = M_N + \overline{M}_N^N + O(N\Delta t).
\]

We let the reader check that \( (M_n)_{0 \leq n \leq N} \) is a martingale with respect to the (forward) filtration \( (\sigma(K_0, \ldots, K_n))_{0 \leq n \leq N} \). By Proposition 4.7, \( (\overline{M}_n^N)_{0 \leq n \leq N} \) is a martingale with respect to the backward filtration.

Following (3.13), we have

\[
\mathbb{E}_\mu [\overline{M}_N^N] = \sum_{n=0}^{N-1} \mathbb{E}_\mu [\overline{M}_{n+1}^N - M_n^N], \quad \mathbb{E}_\mu [\overline{M}_N^N] = \sum_{n=0}^{N-1} \mathbb{E}_\mu [\overline{M}_{n+1}^N - \overline{M}_n^N].
\]
Following (3.14), we have, for all $0 \leq n \leq N - 1$,
\[
E_u[|M_{n+1} - M_n|^2] \leq E_u[|X_{n+1} - e_{K_n}|^2] \\
\leq E_u\left[\sum_{L \in (K_n)^-} p_{K_n,L}|e_{K_n,L} - e_{K_n}|^2\right] \\
\leq h^2 \sup_K \sum_{L \sim K} p_{K,L} \leq \|a\|_\infty \sup_K [\|K\|^{-1} \sum_{L \sim K} |K \cap L|] h^2 \Delta t.
\]
(4.15)

By (4.1), we deduce $E_u[|M_{n+1} - M_n|^2] \leq \alpha \|a\|_\infty h \Delta t$. By a similar argument, we obtain
\[
E_u[|M_{n+1}^N - M_n|^2] \leq \alpha \|a\|_\infty h \Delta t. 
\]
We deduce
\[
E_u[|M_N|^2] = O(hN \Delta t), \quad E_u[|\tilde{M}_N^N|^2] = O(hN \Delta t).
\]

We then complete the proof as in the one-dimensional case. □

4.7. $L^1$-Error in the Divergence-Free and Periodic Setting with $u^0$ Lipschitz continuous. As a by-product, we obtain the following estimate for the error of the numerical scheme when $u^0$ is Lipschitz continuous:

**Theorem 4.9.** Assume that the hypotheses of the beginning of Section 4 are satisfied. Assume moreover that $a$ is divergence-free and that both the velocity $a$ and the mesh are periodic of period one in each direction of the space. Assume also that $u^0$ is $\kappa$-Lipschitz continuous. Then, there exists a constant $C \geq 0$ such that
\[
\sum_{K \in T/Z^d} \int_K |u_N^0 - u(N \Delta t, x)| dx \leq C((hN \Delta t)^{1/2} + hN \Delta t + N \Delta t^2) \exp(\kappa N \Delta t).
\]

**Proof.** Consider a cell $K$. We know that $u_N^0$ is nothing but
\[
u_N^0 = E_K[u_K^0] = E_K[u^0(X_N)] + O(h).
\]
Moreover, for all $x \in K$, $|X_0 - x| \leq h$ with probability one under $P_K$. By stability of the solutions of (3.2), $|Z(N \Delta t, x) - Z(N \Delta t, X_0)| \leq h \exp(\kappa N \Delta t)$ under $P_K$. We deduce
\[
\forall x \in K, \quad u(N \Delta t, x) = u^0(Z(N \Delta t, x)) = E_K[u^0(Z(N \Delta t, X_0))] + O(h \exp(\kappa N \Delta t)).
\]
Hence,
\[
\sum_{K \in T/Z^d} \int_K |u_N^0 - u(N \Delta t, x)| dx \leq \kappa \sum_{K \in T/Z^d} |K|E_K[|X_N - Z(N \Delta t, X_0)|] + O(h \exp(\kappa N \Delta t)) \\
\leq \kappa E_p[|X_N - Z(N \Delta t, X_0)|] + O(h \exp(\kappa N \Delta t)).
\]
This completes the proof. □

5. Analysis in the General Setting

We now turn to the general case and analyze the error of the numerical scheme, both in the $L^1$ sense and in the $L^\infty$ sense, $u^0$ being respectively of bounded variation and Lipschitz continuous. We thus forget the periodic setting and the divergence-free condition. Anyhow, for technical reasons explained below, the time step $\Delta t$ is required to be small when the divergence of $a$ is large, i.e.
\[
\exists \eta \in (0, 1), \quad \|\text{div}(a)\|_\infty \Delta t < 1 - \eta.
\]
We keep the notations of Section 3. To simplify the form of the final bounds, we assume that $h \leq 1$ and that $\Delta t \leq \theta h$ for some $\theta > 0$. The constants $C$, $C'$ and $c$ below may depend on the parameters specified in Section 3 on $\eta$ and on $\theta$. The values of these “constants” may vary from line to line.

5.1. Strategy. In dimension one, we were able to analyze the error in the $L^\infty$ sense by investigating the distance between $X_N$ and $X_0 - \Delta t \sum_{n=0}^{N-1} a(X_n)$ for any arbitrary initial cell $K$ of the mesh. In the previous section, the result was given in the $L^1$ norm since the chain was initialized with the Lebesgue measure. In what follows, the approach is halfway.

The idea is the following. We pick up the starting cell of the chain with respect to the Lebesgue measure among the cells included in a ball of radius $h^{1/2}$ and centered at the origin (or at any other arbitrarily prescribed point). The bounds we then obtain for the error of the numerical scheme hold in the $L^1$ sense, but locally in the ball. In other words, we manage to bound

$$h^{-d/2} \sup_{x \in \mathbb{R}^d} \int_{B(x,h^{1/2})} |u^N(y) - u(N\Delta t,y)|dy$$

by a constant times $h^{1/2}$ (up to remaining terms in $N$ and $\Delta t$), $u^0$ being Lipschitz continuous. (In the above expression, $u^N(y)$ stands for $u_K^N$ when $y$ belongs to the interior of $K$.) By an approximation procedure, we deduce that the scheme is of order $1/2$ for the (global) $L^1$ norm when $u^0$ is of bounded variation.

Actually, we can perform the same analysis by replacing the local $L^1$ norm by the local $L^p$ norm, $p$ being greater than one. We then derive that, for any small positive $\varepsilon$, the scheme is of order $1/2 - \varepsilon$ for the $L^\infty$ norm when $u^0$ is Lipschitz continuous. Moreover, by translation, it is sufficient to prove this estimate for $x = 0$.

For all these reasons, the quantities of interest are

$$Q^N_p = h^{d/2} \sum_{K \in \mathcal{T}_0} \mathbb{E}_K \left[ \left| X_N - X_0 + \Delta t \sum_{n=0}^{N-1} a(X_n) \right|^p \right], \quad N, p \geq 1,$$

where $\mathcal{T}_0$ stands for the set of cells $K$ such that $|e_K| \leq h^{1/2}$. By (3.1), the cardinality of $\mathcal{T}_0$ is bounded by $C h^{-d/2}$ for some positive constant $C$.

For given $N, p \geq 1$, we are going to decompose $Q^N_p$ along all the possible paths of the chain. To do so, we distinguish the paths according to their fluctuations around the velocity field $-a$. We write

$$Q^N_p \leq h^{(d+p)/2} \sum_{K \in \mathcal{T}_0} \sum_{k \geq 0} (k+1)^p \mathbb{P}_K \left\{ kh^{1/2} \leq \sup_{1 \leq n \leq N} \left| X_n - X_0 + \Delta t \sum_{i=0}^{n-1} a(X_i) \right| < (k+1)h^{1/2} \right\}.$$  

To estimate the above right-hand side, we will use a time reversal argument, as in Section 4. Therefore, we are mainly interested in the location of the arrival cell $K_N$ on the event

$$\{ kh^{1/2} \leq \sup_{1 \leq n \leq N} |X_n - X_0 + \Delta t \sum_{i=0}^{n-1} a(X_i)| < (k+1)h^{1/2} \}.$$  

Thus, for any $k \geq 0$, we denote by $\mathcal{T}^N_k$ the set of cells $J_N$ such that there exists an $N$-tuple $(J_0, \ldots, J_{N-1})$, with $J_0 \in \mathcal{T}_0$, satisfying, for all $i \in \{0, \ldots, N-1\}$, either $J_{i+1} = J_i$ or $J_{i+1} \neq J_i$, and

$$kh^{1/2} \leq \sup_{1 \leq n \leq N} |y_{J_{n-1},J_n} - e_{J_0} + \Delta t \sum_{i=0}^{n-1} a(y_{J_{i-1},J_i})| < (k+1)h^{1/2},$$

which is satisfied by

$$\begin{array}{l}
\frac{1}{2} < \sup_{1 \leq n \leq N} \left| y_{x,J_1} - y_{x,J_0} + \Delta t \sum_{i=0}^{n-1} a(y_{J_{i-1},J_i}) \right| \leq (k+1)h^{1/2},
\end{array}$$

and

$$\begin{array}{l}
\frac{1}{2} < \left| y_{x,J_N} - y_{x,J_{N-1}} + \Delta t \sum_{i=0}^{n-1} a(y_{J_{i-1},J_i}) \right| \leq (k+1)h^{1/2}.
\end{array}$$
with \( y_{i,J_{i+1}} = e_J \) if \( J_i = J_{i+1} \) and \( y_{i,J_{i+1}} = x_{J_i,J_{i+1}} \) if \( J_i \neq J_{i+1} \) (and \( y_{J_{-1},J_0} = e_{J_0} \)). Under \( \mathbb{P}_K \), for \( K \in T_0 \), we have \( K_N \in T^N_k \) on the event \( \{kh^{1/2} \leq \sup_{1 \leq n \leq N} |X_n - X_0 + \Delta t \sum_{i=0}^{n-1} a(X_i)| < (k + 1)h^{1/2}\} \).

Thus,

\[
Q^N_p \leq h^{(d+p)/2} \sum_{k \geq 0} \sum_{K \in T_0} \sum_{L \in T^N_k} \left[ (k + 1)^p \times \mathbb{P}_K \left\{ kh^{1/2} \leq \sup_{1 \leq n \leq N} |X_n - X_0 + \Delta t \sum_{i=0}^{n-1} a(X_i)| < (k + 1)h^{1/2}, K_N = L \right\} \right].
\]

(5.3)

In the next lemma, we estimate the cardinality of \( T^N_k \). Because of the translation action of the transport equation, \( \#[T^N_k] \) is of the same order as \( \#[T_0] \):

**Lemma 5.1.** There exists a constant \( C > 0 \) such that, for all \( k \geq 0 \),

\[
\#[T^N_k] \leq C \exp(CN\Delta t)(k + 1)^d h^{-d/2}.
\]

**Proof.** We fix \( k \geq 0 \) and we consider a sequence of cells \((J_0, \ldots, J_N)\), \( J_0 \in T_0 \), satisfying (5.2). Setting \((y^0, \ldots, y^N) = (e_{J_0}, y_{J_0,J_1}, \ldots, y_{J_{N-1},J_N})\),

\[
\sup_{1 \leq n \leq N} |y^n - y^0 + \Delta t \sum_{i=0}^{n-1} a(y^i)| \leq (k + 1)h^{1/2}.
\]

Plugging the characteristic of the transport equation (see (1.2)), we deduce (recall that \( h \leq 1 \) and \( \Delta t \leq \theta h \) by assumption)

\[
\sup_{1 \leq n \leq N} \left| y^n - Z(n\Delta t, y^0) + \Delta t \sum_{i=0}^{n-1} [a(y^i) - a(Z(i\Delta t, y^0))] \right|
\leq (k + 1)h^{1/2} + CN\Delta t^2 \leq (k + 1)h^{1/2}(1 + CN\Delta t),
\]

for some constant \( C > 0 \). By the Lipschitz property of \( a \) and the Gronwall lemma, it is plain to deduce (up to a new value of \( C \))

\[
|y^N - Z(N\Delta t, y^0)| \leq C \exp(CN\Delta t)(k + 1)h^{1/2}.
\]

Since \( |y^0| \leq h^{1/2} \) \((J_0 \in T_0)\), we deduce, by stability of the solutions to (1.2), that

\[
|y^N - Z(N\Delta t, 0)| \leq C \exp(CN\Delta t)(k + 1)h^{1/2}.
\]

Every point \( x \in J_N \) satisfies the same property since the diameter of \( J_N \) is bounded by \( h \). We deduce that there exists a constant \( C \) such that \( J_N \) is included in the ball of center \( Z(N\Delta t, 0) \) and of radius \( C \exp(CN\Delta t)(k + 1)h^{1/2} \). In other words, all the cells in \( T^N_k \) are included in this ball. Up to a modification of \( C \), the volume of the ball is \( C \exp(CN\Delta t)(k + 1)^d h^{d/2} \). Since the volume of a given cell is greater than \( \beta^{-1}h^d \) (see Assumption (4.1)), the cardinality of \( T^N_k \) is bounded by \( C \exp(CN\Delta t)(k + 1)^d h^{d/2} \) for a new value of the constant \( C \). \( \square \)
5.2. Application of Section 4. In light of Section 4, we introduce the following decomposition

\[ X_N - X_0 + \Delta t \sum_{n=0}^{N-1} a(X_n) = S_N + R_N, \]

with

\[ S_0 = R_0 = 0, \quad S_n = \sum_{i=0}^{n-1} [X_{i+1} - e_{K_i} + \Delta t a(X_i)], \quad R_n = \sum_{i=0}^{n-1} [e_{K_i} - X_i], \quad n \geq 1. \]

On the event \( \{ kh^{1/2} \leq \sup_{0 \leq n \leq N} |X_n - X_0 + \Delta t \sum_{i=0}^{n-1} a(X_i)| < (k + 1)h^{1/2} \} \), we have \( \sup_{0 \leq n \leq N} |S_n| \geq (k/2)h^{1/2} \) or \( \sup_{0 \leq n \leq N} |R_n| \geq (k/2)h^{1/2} \). By (5.3), we obtain

\[ h^{-(d+p)/2} Q^N_p \leq \sum_{k \geq 0} \sum_{K \in \mathcal{T}_k} \sum_{L \in \mathcal{T}_k^N} \frac{(k + 1)^p}{k!} \mathbb{P}_K \{ \sup_{0 \leq n \leq N} |S_n| \geq \frac{k}{2} h^{1/2}, K_N = L \} \]

\[ + \sum_{k \geq 0} \sum_{K \in \mathcal{T}_k} \sum_{L \in \mathcal{T}_k^N} \frac{(k + 1)^p}{k!} \mathbb{P}_K \{ \sup_{0 \leq n \leq N} |R_n| \geq \frac{k}{2} h^{1/2}, K_N = L \}. \]

We wish to apply Corollary 4.3 to treat the first term in the above right-hand side. Since \( \mathbb{I}[\mathcal{T}_0] \leq C h^{-d/2} \), we have

\[ \sum_{k \geq 0} \sum_{K \in \mathcal{T}_k} \sum_{L \in \mathcal{T}_k^N} \frac{(k + 1)^p}{k!} \mathbb{P}_K \{ \sup_{0 \leq n \leq N} |S_n| \geq \frac{k}{2} h^{1/2}, K_N = L \} \]

\[ \leq C h^{-d/2} \sum_{k \geq 0} \frac{(k + 1)^p}{k!} \mathbb{P}_K \{ \sup_{0 \leq n \leq N} |S_n| \geq \frac{k}{2} h^{1/2} \} \]

\[ \leq C h^{-d/2} \left[ h^{1/2} N \Delta t (1 + C N \Delta t)^p + \sum_{k \geq 0} \frac{(k + 1)^p}{k!} \left[ \exp\left(-\frac{k^2}{CN \Delta t}\right) + \exp\left(-\frac{k}{Ch^{1/2}}\right) \right] \right], \]

the last line following from

**Lemma 5.2.** There exists a constant \( C > 0 \) such that, for \( k > CN \Delta t h^{1/2} \),

\[ \sup_{K \in \mathcal{T}} \mathbb{P}_K \{ \sup_{0 \leq n \leq N} |S_n| \geq \frac{k}{2} h^{1/2} \} \leq C \left[ \exp\left(-\frac{k^2}{CN \Delta t}\right) + \exp\left(-\frac{k}{Ch^{1/2}}\right) \right]. \]

**Proof of Lemma 5.2.** We fix the starting cell \( K \in \mathcal{T} \). (We thus work under \( \mathbb{P}_K \).) Following the proof of Proposition 4.8, we introduce the sequence

\[ M_0 = 0, \quad M_n = \sum_{i=0}^{n-1} (X_{i+1} - e_{K_i} - \mathbb{E}_K [X_{i+1} - e_{K_i}]), \quad n \geq 1. \]

It is a martingale with respect to the filtration \( (\sigma(K_0, \ldots, K_n))_{n \geq 0} \) (under \( \mathbb{P}_K \)). By Corollary 4.3, we have

\[ \sup_{0 \leq n \leq N} |M_n - S_n| \leq CN \Delta t h, \]

for a positive constant \( C \). Thus, on the event \( \{ \sup_{0 \leq n \leq N} |S_n| \geq (k/2)h^{1/2} \} \), \( \sup_{0 \leq n \leq N} |M_n| \geq (k/4)h^{1/2} \) or \( CN h \Delta t \geq (k/4)h^{1/2} \). The latter is impossible if \( k > 4CN h^{1/2} \Delta t \). We deduce
that
\[ \mathbb{P}_K \left\{ \sup_{0 \leq n \leq N} |S_n| \geq \frac{k}{2} h^{1/2} \right\} \leq \mathbb{P}_K \left\{ \sup_{0 \leq n \leq N} |M_n| \geq \frac{k}{4} h^{1/2} \right\}, \]
for \( k > 4CN\Delta t h^{1/2} \). As in (4.13), the conditional variance of the martingale \((M_n)_{n \geq 0}\) may be bounded by \(C\Delta t h\) for a possibly new value of \(C\):
\[ \forall n \geq 0, \quad \mathbb{E}_K^n [ |M_{n+1} - M_n|^2 ] \leq C\Delta t h. \]
Moreover, the jumps of the martingale are bounded by \(h\), i.e. \(|M_{n+1} - M_n| \leq h\) for all \(n \geq 0\).
Applying Proposition 6.1 given in Annex to \((h^{-1}M_n)_{n \geq 0}\), we obtain
\[ \mathbb{P}_K \left\{ \sup_{0 \leq n \leq N} |M_n| \geq \frac{k}{4} h^{1/2} \right\} \leq C \left[ \exp \left( -\frac{k^2}{C N \Delta t} \right) + \exp \left( -\frac{k}{C h^{1/2}} \right) \right]. \]
(Pay attention, the value of \(v\) in Proposition 6.1 is \(v = C\Delta t h^{-1}\) since we divide \((M_n)_{n \geq 0}\) by \(h\).)

5.3. **Time Reversal.** To treat the gap term \(R_N\) in (5.4), we are to reverse the chain \((K_n)_{n \geq 0}\) as done in Section 4 and then to compare the law of the reversed chain with the law of the chain associated with \(-a\).
Because of (4.11), we emphasize that the CFL condition may fail for \(-a\), so that we cannot associate a Markov chain with the weights \((q_{K,J})_{K,J \in T}\). The following proposition says how to modify them to obtain a Markovian kernel:

**Proposition 5.3.** Set
\[ \forall K \in T, \quad \delta_K = |K|^{-1} \int_K \text{div}(a)(x)dx. \]
Then, under Condition (5.1), the kernel
\[ \gamma_{K,J} = (1 + \delta_K \Delta t)^{-1} q_{K,J} \text{ for } J \in K^+, \]
\[ \gamma_{K,K} = 1 - \sum_{J \in K^+} (1 + \delta_K \Delta t)^{-1} q_{K,J}, \]
\[ \gamma_{K,J} = 0 \text{ for } J \in T \setminus (K^+ \cup K), \]
satisfies \(\gamma_{K,K} = (1 + \delta_K \Delta t)^{-1} p_{K,K}\). In particular, it is Markovian, i.e. \(\gamma_{K,J} \geq 0\) for all \(K, J \in T\) and \(\sum_{J \in T} \gamma_{K,J} = 1\).

By (5.1), we emphasize that \(\gamma_{K,J} \leq \eta^{-1} q_{K,J}\) for \(J \in K^+\) and \(\gamma_{K,J} \leq \eta^{-1} p_{K,K}\).

**Proof.** Consider a cell \(K\). By (5.1), we have \(1 + \delta_K \Delta t > 0\). We compute \(\gamma_{K,K}\). By integrating by parts the expression of \(\delta_K\), as in (4.10), we get
\[ -\sum_{L \sim K} p_{K,L} + \sum_{J \sim K} q_{K,J} = \delta_K \Delta t, \]
that is \(p_{K,K} - 1 + (1 + \delta_K \Delta t)(1 - \gamma_{K,K}) = \delta_K \Delta t\). We deduce that \(\gamma_{K,K} = (1 + \delta_K \Delta t)^{-1} p_{K,K}\). \(\square\)

The chain associated with the kernel \(\gamma\) is denoted by the pair \((Q_K)_{K \in T}, (\Gamma_n)_{n \geq 0}\); \((\Gamma_n)_{n \geq 0}\) is a sequence of measurable mappings from \((\Omega, \mathcal{A})\) into the set of cells and \((Q_K)_{K \in T}\) is a family of probability measures on \((\Omega, \mathcal{A})\), such that \((\Gamma_n)_{n \geq 0}\) is, under \(Q_K\), a Markov chain with \(K\) as initial condition and \(\gamma\) as kernel. The expectation under \(Q_K\) is denoted by \(\mathbb{E}_K^{Q}\).
The link between the chain \((\Gamma_n)_{n \geq 0}\) and the reversed chain \((\bar{K}_n^N = K_{N-n})_{0 \leq n \leq N}\) is given by

**Proposition 5.4.** There exists a constant \(C > 1\), such that, for any pair of cells \((K, L)\) and any function \(\Psi : \mathcal{T}^{N+1} \to \mathbb{R}_+\),

\[
C^{-1}[1 - \| \text{div}(a) \|_{\infty} \Delta t]^{N} E_L^Q \left[ \Psi(\Gamma_0, \ldots, \Gamma_N) 1_{\{\Gamma_N = K\}} \right] \\
\leq E_K \left[ \Psi(\bar{K}_0^N, \ldots, \bar{K}_N^N) 1_{\{K_N = L\}} \right] \\
\leq C \left[ 1 + \| \text{div}(a) \|_{\infty} \Delta t \right]^{N} E_L^Q \left[ \Psi(\Gamma_0, \ldots, \Gamma_N) 1_{\{\Gamma_N = K\}} \right].
\]

Of course, Proposition 5.4 is weaker than Proposition 4.6. Above, we are just able to compare the law of \((\Gamma_0, \ldots, \Gamma_N)\) under the measure \(1_{\{\Gamma_N = K\}} \cdot \mathbb{Q}_L\) with the law of \((K_N, \ldots, K_0)\) under the measure \(1_{\{K_N = L\}} \cdot \mathbb{P}_K\). They are equivalent and the resulting density is bounded from above and from below by positive deterministic constants.

**Proof.** Without loss of generality, we can assume that \(\Psi = 1_{\{J_0, \ldots, J_N\}}\), with \((J_0, \ldots, J_N) \in \mathcal{T}^{N+1}\), \(J_0 = L\) and \(J_N = K\). Then,

\[
E_K \left[ \Psi(\bar{K}_0^N, \ldots, \bar{K}_N^N) 1_{\{K_N = L\}} \right] = \mathbb{P}_J \{ \bar{K}_0^N = J_0, \ldots, \bar{K}_{N-1}^N = J_{N-1}^N, \bar{K}_N^N = J_N \} \\
= \mathbb{P}_J \{ J_0 = J_N^N, J_1 = J_{N-1}^N, \ldots, J_{N} = J_0 \} \\
= \mathbb{P}_{J_N,J_{N-1},J_{N-2}, \ldots, J_0}. 
\]

By Proposition 5.3 and (4.13), we know that

\[
\gamma_{J_n, J_{n+1}} = \frac{|J_{n+1}|}{|J_n|(1 + J_n \Delta t)} p_{J_{n+1}, J_n}, 0 \leq n \leq N - 1,
\]
even if \(J_n = J_{n+1}\). Plugging this relationship in (5.7), we deduce that

\[
E_K \left[ \Psi(\bar{K}_0^N, \ldots, \bar{K}_N^N) 1_{\{K_N = L\}} \right] = \prod_{n=0}^{N-1} \left( 1 + J_n \Delta t \right) \frac{|J_0|}{|J_N|} \gamma_{J_0,J_1} \cdots \gamma_{J_{N-1},J_N} \\
= \prod_{n=0}^{N} \left( 1 + J_n \Delta t \right) \frac{|J_0|}{|J_N|} E_L^Q \left[ \Psi(\Gamma_0, \ldots, \Gamma_N) 1_{\{\Gamma_N = K\}} \right].
\]

By (5.1) and (4.1) (recall that (4.1) implies \(\beta^{-1} h^d \leq |J| \leq h^d\) for all \(J \in \mathcal{T}\) and for some \(\beta > 1\)), we complete the proof.

**5.4. Analysis of the Gap.** Using the previous subsection, we analyze the term \(R_N\) in (5.4). For \(N \geq 1\), we emphasize that

\[
\sup_{1 \leq n \leq N} |R_n| = \sup_{1 \leq n \leq N} \left| \sum_{i=1}^{n-1} [(e_{K_i} - x_{K_{i-1}, K_i}) 1_{\{K_{i-1} \neq K_i\}}] \right| \\
\leq 2 \sup_{1 \leq n \leq N} \left| \sum_{i=n}^{N} [(e_{K_i} - x_{K_{i-1}, K_i}) 1_{\{K_{i-1} \neq K_i\}}] \right| \\
= 2 \sup_{1 \leq n \leq N} \left| \sum_{i=0}^{n-1} [(e_{\bar{K}_i} - x_{\bar{K}_{i+1}, \bar{K}_i}) 1_{\{\bar{K}_{i+1} \neq \bar{K}_i\}}] \right|.
\]

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Proof. The proof is quite obvious. For each \( \sigma \)

Keeping Proposition 5.4 in mind, we define the analogue, but for the chain \( (\Gamma_n)_{n \geq 0} \), that is

\[
\Xi_0 = 0, \quad \Xi_n = \sum_{i=0}^{n-1} \left[ (e_{\Gamma_i} - x_{\Gamma_i, \Gamma_{i+1}}) 1_{\{\Gamma_{i+1} \neq \Gamma_i\}} \right], \quad n \geq 1,
\]

By Proposition 5.4, we deduce that, for any starting cell \( K \), for any terminal cell \( L \) and for any \( k \geq 0 \),

\[
(5.7) \quad \mathbb{P}_K \left\{ \sup_{1 \leq n \leq N} |R_n| \geq \frac{k}{2} h^{1/2}, K_N = L \right\} \leq C(1 + \Delta t)^N \mathbb{Q}_L \left\{ \sup_{1 \leq n \leq N} |\Xi_n| \geq \frac{k}{4} h^{1/2}, \Gamma_N = K \right\}
\]

Here is the main argument of the analysis.

**Proposition 5.5.** For a given cell \( L \in T \), the process \( (\Xi_n)_{n \geq 0} \) is a martingale under \( \mathbb{Q}_L \) with respect to the filtration \( (\sigma(\Gamma_0, \ldots, \Gamma_n))_{n \geq 0} \).

**Proof.** The proof is quite obvious. For each \( n \geq 0 \), \( \Xi_n \) is measurable with respect to \( \sigma(\Gamma_0, \ldots, \Gamma_n) \) and

\[
\mathbb{E}^\mathbb{Q}_L [e_{\Gamma_n} - x_{\Gamma_{n+1}, \Gamma_n} | \Gamma_0, \ldots, \Gamma_n] = \sum_{J \in \Gamma_n^+} \gamma_{\Gamma_n, J}(e_{\Gamma_n} - x_{J, \Gamma_n})
\]

\[
= (1 + \delta_{\Gamma_n \Delta t})^{-1} \sum_{J \in \Gamma_n^+} q_{\Gamma_n, J}(e_{\Gamma_n} - x_{J, \Gamma_n}) = 0. \quad \Box
\]

Following the proof of Lemma 5.2 and making use of (5.4) to bound the conditional variances of the increments of \( (\Xi_n)_{n \geq 0} \), we deduce

**Lemma 5.6.** There exists a constant \( C > 0 \) such that for any \( k \geq 0 \)

\[
\sup_L \mathbb{Q}_L \left\{ \sup_{0 \leq n \leq N} |\Xi_n| > \frac{k}{4} h^{1/2} \right\} \leq C \left[ \exp\left(-\frac{k^2}{4CN\Delta t}\right) + \exp\left(-\frac{k}{Ch^{1/2}}\right) \right].
\]

Gathering (5.7) and Lemmas 5.1 and 5.6, we deduce (by modifying if necessary the constant \( C \) from line to line)

\[
\sum_{k \geq 0} \sum_{K \in T_0} \sum_{L \in T_0^N} (k + 1)^p \mathbb{P}_K \left\{ \sup_{0 \leq n \leq N} |R_n| \geq \frac{k}{2} h^{1/2}, K_N = L \right\}
\]

\[
\leq C(1 + \Delta t)^N \sum_{k \geq 0} \sum_{L \in T_0^N} \sum_{K \in T_0} (k + 1)^p \mathbb{Q}_L \left\{ \sup_{1 \leq n \leq N} |\Xi_n| \geq \frac{k}{4} h^{1/2}, \Gamma_N = K \right\}
\]

\[
\leq C(1 + \Delta t)^N \sum_{k \geq 0} \frac{h^{d/2}}{h^{d/2}} \exp(CN\Delta t) \sum_{k \geq 0} (k + 1)^{d+p} \left[ \exp\left(-\frac{k^2}{CN\Delta t}\right) + \exp\left(-\frac{k}{Ch^{1/2}}\right) \right].
\]

By (5.4) and (5.5), we deduce (up to a new value of \( C \))

\[
\mathbb{Q}_p^N \leq Ch^{(p+1)/2} N\Delta t (1 + N\Delta t)^p
\]

\[
+ Ch^{p/2} \exp(CN\Delta t) \sum_{k \geq 0} (k + 1)^{d+p} \left[ \exp\left(-\frac{k^2}{CN\Delta t}\right) + \exp\left(-\frac{k}{Ch^{1/2}}\right) \right].
\]
Keeping the inequality $h \leq 1$ in mind and comparing the left-hand side below to an integral, there exists a positive constant $C_p$, only depending on $p$ and on the same parameters as $C$, such that

$$\sum_{k \geq 0} (k + 1)^{d+p} \left[ \exp \left( -\frac{k^2}{CN\Delta t} \right) + \exp \left( -\frac{k}{Ch^{1/2}} \right) \right] \leq C_p(1 + N\Delta t)^{(p+d+1)/2}. $$

Finally,

**Theorem 5.7.** Assume $\|u\|_\infty, \alpha, d, \kappa, \eta, \theta$ and $p$, such that, for all $N \geq 1$,

$$h^{d/2} \sum_{K \in T_0} \mathbb{E}_K \left[ \|X_N - X_0 + \Delta t \sum_{n=0}^{N-1} a(X_n)\|_p^p \right] \leq C_p h^{p/2} \exp(C_p N\Delta t).$$

5.5. **Analysis of the Numerical Scheme.** We now prove the main results of the paper.

**Proposition 5.8.** In addition to the assumptions of Theorem 5.7, assume that $u^0$ is $\kappa$-Lipschitz continuous. Then, for any $p \geq 1$, there exists a constant $C_p > 0$, only depending on $\|a\|_\infty, \alpha, d, \kappa, \eta, \theta$ and $p$, such that, for all $N \geq 1$,

$$\sup_{x \in \mathbb{R}^d} \left[ h^{-d/2} \sum_{K:|e_K - x| \leq h^{1/2}} \|u^N_K - u(N\Delta t, \cdot)\|_{L^p(K)}^{p} \right]^{1/p} \leq C_p h^{1/2} \exp(C_p N\Delta t).$$

**Proof.** By translation, it is sufficient to prove the bound for $x = 0$. To simplify the notations, we set for any random variable $Y$ with values in $\mathbb{R}^d$:

$$\|Y\|_{p,T_0} = \left[ h^{d/2} \sum_{K \in T_0} \mathbb{E}_K \left[ |Y|^p \right] \right]^{1/p}. $$

(Above, $T_0$ is the set of cells $K$ such that $|e_K| \leq h^{1/2}$.) Of course, $\| \cdot \|_{p,T_0}$ is a norm on the space of $\mathbb{R}^d$-valued random variables with a finite moment of order $p$ under every $P_K$, $K \in T_0$. By Theorem 5.7 and by the properties $h \leq 1$ and $\Delta t \leq \theta h$, we have

$$\forall N \geq 1, \left\| X_N - Z(N\Delta t, X_0) + \Delta t \sum_{n=0}^{N-1} [a(X_n) - a(Z(n\Delta t, X_0))] \right\|_{p,T_0} \leq C_p h^{1/2} \exp(C_p N\Delta t),$$

up to a new value of $C_p$. Following the proof of Proposition 3.4, Gronwall’s lemma yields

$$\forall N \geq 1, \left\| X_N - Z(N\Delta t, X_0) \right\|_{p,T_0} \leq C_p h^{1/2} \exp(C_p N\Delta t),$$

again for a new value of the constant $C_p$. Following the proof of Theorem 4.9,

$$\left[ h^{-d/2} \sum_{K \in T_0} \|u^N_K - u(N\Delta t, \cdot)\|_{L^p(K)}^{p} \right]^{1/p} \leq C \left\| X_N - Z(N\Delta t, X_0) \right\|_{p,T_0} + C \exp(CN\Delta t)h,$$

for some $C > 0$. This completes the proof.

As a by-product, we obtain the $L^\infty$ estimate announced in Introduction:
Theorem 5.9. In addition to the assumptions of Theorem 5.7, assume that \( u^0 \) is \( \kappa \)-Lipschitz continuous. Then, for any \( p \geq 1 \), there exists a constant \( C_p > 0 \), only depending on \( \|a\|_\infty, \alpha, d, \kappa, \eta, \theta \) and \( p \), such that, for all \( N \geq 1 \),
\[
\sup_{K \in T} \sup_{1 \leq x < K} \|u^N_K - u(N\Delta t, x)\| \leq C_p h^{(1-1/p)/2} \exp(C_p N\Delta t).
\]

Proof. Consider a given cell \( K \). By Proposition 5.8,
\[
h^{d/2p} \inf_{y \in K} |u^N_K - u(N\Delta t, y)| \leq \left[ 3h^{-d/2} \|u^N_K - u(N\Delta t, \cdot)\|_{L^p(K)} \right]^{1/p} \leq C_p h^{1/2} \exp(C_p N\Delta t).
\]

Since \( u(N\Delta t, \cdot) \) is Lipschitz continuous with \( \kappa \exp(\kappa N\Delta t) \) as Lipschitz constant, we complete the proof. □

By a regularization argument, we manage to weaken the required assumption on \( u^0 \) in Proposition 5.8.

Theorem 5.10. In addition to the assumptions of Theorem 5.7, assume that \( u^0 \) belongs to \( BV(\mathbb{R}^d) \). Then, there exists a constant \( C > 0 \), only depending on \( \|a\|_\infty, \alpha, d, \kappa, \eta, \theta \) and the \( BV \) semi-norm of \( u^0 \), such that, for all \( N \geq 1 \),
\[
\sum_{K \in T} \|u^N_K - u(N\Delta t, \cdot)\|_{L^1(K)} \leq C h^{1/2} \exp(C N\Delta t).
\]

Proof. The parameters \( h \) and \( N \) are fixed for the whole proof (with \( h \leq 1 \)). The constants "\( C_n \)" and "\( C''_n \)" appearing below may depend on the \( BV \) semi-norm of \( u^0 \). By [23, Chapter 5], we know that the semi-norm \( BV \), denoted by \( \| \cdot \|_{BV(\mathbb{R}^d)} \), decreases by convolution. In particular, we can find a smooth function \( u^0_h : \mathbb{R}^d \to \mathbb{R} \), such that \( \|u^0 - u^0_h\|_{L^1(\mathbb{R}^d)} \leq h^{1/2} \) and \( \|\nabla u^0_h\|_{L^1(\mathbb{R}^d)} \leq \|u^0\|_{BV(\mathbb{R}^d)} \). We then set, for all \( x \in \mathbb{R}^d \), \( \bar{u}^0(x) = |B(0, h^{1/2})|^{-1} \int_{B(0, h^{1/2})} u^0_h(x - y)dy \). We let the reader check that
\[
\|u^0 - \bar{u}^0\|_{L^1(\mathbb{R}^d)} \leq h^{1/2} \left( 1 + \|u^0\|_{BV(\mathbb{R}^d)} \right), \quad \|\nabla \bar{u}^0\|_{L^1(\mathbb{R}^d)} \leq \|u^0\|_{BV(\mathbb{R}^d)}.
\]

The reason why we introduce \( \bar{u}^0 \) is the following: the gradient of \( \bar{u}^0 \) may be locally bounded, in the \( L^\infty \) sense, by local \( L^1 \) norms of \( \nabla u^0_h \). Indeed, for any \( x \in \mathbb{R}^d \) and \( R > 0 \),
\[
\sup_{y \in B(x, R)} |\nabla \bar{u}^0(y)| \leq |B(0, h^{1/2})|^{-1} \|\nabla u^0_h\|_{L^1(B(x, R + h^{1/2}))}.
\]

We denote by \( \bar{u}(t, x) = \bar{u}^0(Z(t, x)) \) the solution, at \( (t, x) \), of the transport problem with \( \bar{u}^0 \) as initial condition and by \( \bar{u}^N = E_K(\bar{u}^0(K_N)) \) the corresponding approximate solution at time step \( N \) in cell \( K \). It is clear that there exists a constant \( C > 0 \) such that
\[
\forall t \geq 0, \quad \|\bar{u}(t, \cdot) - u(t, \cdot)\|_{L^1(\mathbb{R}^d)} \leq \exp(Ct)\|u^0 - u^0\|_{L^1(\mathbb{R}^d)}.
\]

Similarly, with Proposition 5.3 at hand,
\[
\sum_{K \in T} |K| |u^N_K - \bar{u}^N_K| \leq \sum_{K \in T} |K| \sum_{L \in T} |p_{K,L}| |u^0_L - \bar{u}^0_L| = \sum_{L \in T} |L|(1 + \delta_L \Delta t) \sum_{K \in T} \gamma_{L,K} |u^0_L - \bar{u}^0_L| \leq (1 + C\Delta t) \sum_{L \in T} |L| ||u^0_L - \bar{u}^0_L||_{L^1(\mathbb{R}^d)}.
\]

Iterating the procedure, we obtain
\[
\sum_{K \in T} |K| |u^N_K - \bar{u}^N_K| \leq (1 + C\Delta t)^N \sum_{K \in T} |K| ||u^0_K - \bar{u}^0_K|| \leq (1 + C\Delta t)^N \|u^0 - u^0\|_{L^1(\mathbb{R}^d)}.
\]
By (5.9), (5.11) and (5.12), it is sufficient to investigate

\[ \| \bar{u}^N_N - \bar{u}(N \Delta t, \cdot) \|_{L^1(K)} \]

for a cell \( K \), we obtain by (5.10) and by stability of the solutions to (1.2), for all \( y \in K \),

\[
| \bar{u}(N \Delta t, y) - \bar{u}(N \Delta t, e_K) | = | \bar{u}^0(Z(N \Delta t, y)) - \bar{u}^0(Z(N \Delta t, e_K)) | \\
\leq C \exp(C N \Delta t) h \sup_{|z - Z(N \Delta t, e_K)| \leq C \exp(C N \Delta t) h} | \nabla \bar{u}^0(z) | \\
\leq C \exp(C N \Delta t) h^{1+d/2} \| \nabla u_h^0 \|_{L^1(B(Z(N \Delta t, e_K), C \exp(C N \Delta t) h^{1/2}))},
\]

for some \( C > 0 \) (which may vary from line to line). Integrating with respect to \( y \), we have by inversion of the flow \( Z(N \Delta t, \cdot) \)

\[
\sum_{K \in T} \| \bar{u}(N \Delta t, \cdot) - \bar{u}(N \Delta t, e_K) \|_{L^1(K)} \\
\leq C \exp(C N \Delta t) h^{1+d/2} \int_{\mathbb{R}^d} \left[ | \nabla u_h^0(z) | \sum_{K \in T} 1_{|z - Z(N \Delta t, e_K)| \leq C \exp(C N \Delta t) h^{1/2}} \right] dz \\
\leq C' \exp(C' N \Delta t) h \| \nabla u_h^0 \|_{L^1(\mathbb{R}^d)}.
\]

It is thus sufficient to analyse \( \sum_{K \in T} |K| \| \bar{u}^N_K - \bar{u}(N \Delta t, e_K) | \). In what follows, we fix a point \( x \in \mathbb{R}^d \) and we consider a cell \( K \in T_x \), the set of cells \( L \) such that \( |e_L - x| \leq h^{1/2} \). The triangular inequality yields (remind that \( X_0 = e_K \) under \( P_K )

\[
| \bar{u}^N_K - \bar{u}(N \Delta t, e_K) | \\
\leq \sum_{k \geq 0} \mathbb{E}_K \left[ | \bar{u}_K^0 - \bar{u}^0(Z(N \Delta t, X_0)) | \right] \cdot 1_{|kh^{1/2} - |X_N - Z(N \Delta t, X_0)| < (k+1)h^{1/2}}.
\]

We are to bound, under \( P_K \), the difference \( | \bar{u}_K^0 - \bar{u}^0(Z(N \Delta t, X_0)) | \) on the set \{ \( kh^{1/2} \leq |X_N - Z(N \Delta t, X_0)| < (k+1)h^{1/2} \} by the gradient of \( \bar{u}^0 \) and by \( (k+2)h^{1/2} \). (On this set, every point in \( K_N \) is at distance less than \( (k+1)h^{1/2} + h \leq (k+2)h^{1/2} \) from \( Z(N \Delta t, X_0) \).) Since \( X_0 = e_K \) under \( P_K \), we know by stability of the solutions to (1.2) that \( |Z(N \Delta t, X_0) - Z(N \Delta t, x)| \leq C \exp(C N \Delta t) h^{1/2} \) for some constant \( C > 0 \). Therefore, up to a modification of \( C \), the ball \( B(Z(N \Delta t, X_0), (k + 3)h^{1/2}) \) is included in the ball \( B^{h^{1/2}} = B(Z(N \Delta t, x), C \exp(C N \Delta t)(k + 1)h^{1/2}) \). By (5.10), we obtain (under \( P_K )

\[
\sup_{|z - Z(N \Delta t, X_0)| \leq (k+2)h^{1/2}} | \nabla \bar{u}^0(z) | \leq C h^{-d/2} \| \nabla u_h^0 \|_{L^1(B^{h^{1/2}})}.
\]

By (5.13) and (5.14),

\[
\sum_{K \in T_x} |K| \| \bar{u}_K^N - \bar{u}(N \Delta t, e_K) | \\
\leq C h^{(1+d)/2} \sum_{k \geq 0} \left[ (k + 2) \| \nabla u_h^0 \|_{L^1(B^{h^{1/2}})} \sum_{K \in T_x} \mathbb{P}_K \{ |X_N - Z(N \Delta t, X_0)| \geq kh^{1/2} \} \right].
\]

Recall the Markov inequality: for a nonnegative random variable \( Y \) and two reals \( a, p > 0 \), \( \mathbb{P}_K \{ Y > a \} \leq a^{-p} \mathbb{E}_K [Y^p] \). Choosing \( Y = h^{-1/2}|X_N - Z(N \Delta t, X_0)|, a = k \) and \( p = d + 3 \),
and referring to the proof of Proposition 5.8 (see (5.8)), we obtain for \( k \geq 1 \):

\[
\sum_{K \in T_x} \mathbb{P}\{ |X_N - Z(N \Delta t, X_0)| \geq kh^{1/2} \} \leq k^{-(d+3)} \sum_{K \in T_x} \mathbb{E}\left[ (h^{-1/2} |X_N - Z(N \Delta t, X_0)|)^{d+3} \right]
\]

\[
= k^{-(d+3)} h^{-d/2} \|h^{-1/2} (X_N - Z(N \Delta t, X_0))\|_{d+3, T_x}^{d+3}
\]

\[
\leq C(k + 1)^{-(d+3)} h^{-d/2} \exp(CN \Delta t).
\]

The modification of \( k \) into \( k + 1 \) in the last line permits to recover the case \( k = 0 \). Finally,

\[
\sum_{K \in T_x} |K| \|\bar{u}_K^N - \bar{u}(N \Delta t, e_K)| \leq C h^{1/2} \exp(CN \Delta t) \sum_{k \geq 0} [(k + 2)(k + 1)^{-(d+3)} \|\nabla u_k^0\|_{L^1(\mathbb{R}^d)}].
\]

When integrating the left-hand side with respect to \( x \) over \( \mathbb{R}^d \), we obtain by Fubini’s Theorem a term equal to a constant times \( h^{d/2} \sum_{K \in T} |K| \|\bar{u}_K^N - \bar{u}(N \Delta t, e_K)| \). When integrating the right-hand side, we have by inversion of the flow \( Z(N \Delta t, \cdot) \)

\[
\int_{\mathbb{R}^d} \|\nabla u_k^0\|_{L^1(\mathbb{R}^d)} dx = \int_{\mathbb{R}^d} \int_{B(Z(N \Delta t, x), C \exp(CN \Delta t)(k+1)h^{1/2})} \|\nabla u_k^0\|_{L^1(\mathbb{R}^d)}(z) dz dx
\]

\[
\leq C' \exp(C'N \Delta t) \int_{\mathbb{R}^d} \int_{B(x, C \exp(CN \Delta t)(k+1)h^{1/2})} \|\nabla u_k^0\|_{L^1(\mathbb{R}^d)}(z) dz dx
\]

\[
\leq C'(k + 1)^d h^{d/2} \exp(C'N \Delta t) \|\nabla u_k^0\|_{L^1(\mathbb{R}^d)}.
\]

This completes the proof. \( \square \)

6. ANNEX

We now show the concentration inequality used to prove Lemmas 5.3 and 5.6.

**Proposition 6.1.** Let \((\Omega, \mathcal{A}, \mathbb{P})\) be a probability space and \( d \in \mathbb{N} \setminus \{0\} \). Then, there exists a constant \( c > 0 \), only depending on \( d \), such that, for any \( \mathbb{R}^d \)-valued martingale \((Y_n)_{n \geq 0}\) with respect to a given filtration \((\mathcal{H}_n)_{n \geq 0}\) satisfying \( Y_0 = 0 \) and, for all \( n \geq 0 \), \( |Y_{n+1} - Y_n| \leq 1 \) and \( \mathbb{E}[|Y_{n+1} - Y_n|^2 | \mathcal{H}_n] \leq v \) for a deterministic real \( v > 0 \), the following holds for all \( n \geq 0 \):

\[
\forall u > 0, \quad \mathbb{P}\left\{ \sup_{0 \leq k \leq n} |Y_k| \geq u \right\} \leq c \left[ \exp\left(-\frac{u^2}{cn} \right) + \exp\left(-\frac{u}{c} \right) \right].
\]

**Proof.** Without loss of generality, we can assume that \( d = 1 \). Indeed,

\[
\forall u > 0, \quad \mathbb{P}\left\{ \sup_{0 \leq k \leq n} |Y_k| \geq u \right\} \leq \sum_{i=1}^{d} \mathbb{P}\left\{ \sup_{0 \leq k \leq n} |(Y_k)_i| \geq ud^{-1/2} \right\}.
\]

In the one-dimensional case, it is sufficient to investigate \( \mathbb{P}\{\sup_{0 \leq k \leq n} Y_k \geq u\} \), the lower bound following from an obvious change of sign. We then apply [5, Proposition 1.6] (choose \( X_k = 0 \) for \( k > n \), \( a = u \) and \( b = nv \) in the statement of [5, Proposition 1.6])

\[
\mathbb{P}\{ \sup_{0 \leq k \leq n} Y_k \geq u \} \leq \exp\left(-\frac{u^2}{2(u + nv)} \right).
\]

There are two cases: either \( u \leq nv \) or \( u > nv \). We obtain

\[
\mathbb{P}\{ \sup_{0 \leq k \leq n} Y_k \geq u \} \leq \exp\left(-\frac{u^2}{4nv} \right) + \exp\left(-\frac{u}{4} \right).
\]
This completes the proof. □

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