Equilibrium kinetics of self-assembling, semi-flexible polymers

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Abstract

Self-assembling, semi-flexible polymers are ubiquitous in biology and technology. However, conflicting accounts of the equilibrium kinetics remain for such an important system. Here, by focusing on a dynamical description of a minimal model in an overdamped environment, I identify the correct kinetic scheme that describes the system at equilibrium in the limits of high bonding energy and dilute concentration.

Keywords: statistical mechanics of self-assembly, semi-flexible polymers, equilibrium kinetics

(Some figures may appear in colour only in the online journal)

1. Introduction

Many polymerisation processes are in principle reversible—thermal fluctuations will inevitably break a polymer apart and two polymers can potentially join up upon encountering each other. Indeed, there are many examples of synthetic and natural polymers that remodel themselves by breakage and associations at an experimentally accessible scale [1–3]. Held at fixed temperature, these re-modelling systems will eventually reach thermal equilibrium. However, it is surprising that we still lack a dynamical picture that describes reversible polymerization at equilibrium based on first principles. In the literature, the kinetic schemes of polymerisation are typically postulated in ad hoc manners, with contradictory assumptions [4, 5]. Here, I will identify the physically correct kinetic scheme for a minimal model of self-assembling, semi-flexible polymers in the limits of high bonding energy and dilute polymer concentration.

2. A minimal model

At the simplest level, a self-assembling polymer system can be viewed as a collection of particles that can bind to each other due to some short-ranged potential energy function. To represent such a picture in a minimal way, I consider a collection of particles (monomers), each having two sticky patches at two polar ends (figure 1(a)). The sticky patches are assumed to be small so that branching is not possible. As a result, all polymers are linear. The interactions of the particles are described by two quadratic energy functions constraining the bond length and polymer rigidity, with the cut-off on the stretching given by \( L_c \) and that of bending by \( \Theta_c \), respectively (figure 1(a)). Specifically, the overall potential energy for a \( n \)-mer (a polymer consisting of \( n \) monomers) is

\[
E_n(\{r\}) = \Delta E \left\{ \sum_{k=1}^{n-1} \frac{\Delta r_k^2}{L_c^2} + \sum_{h=2}^{n-1} \frac{\Delta \theta_h^2}{\Theta_c^2} - (n - 1) \right\},
\]

where the distance between the \( k \)th bead and the \((k+1)\)th bead is denoted by \( l_k = \Delta l_k \), and the bending angle \( \Delta \theta_h \) at the \( h \)th bead is

\[
\Delta \theta_h = \arccos \left( \frac{\mathbf{r}_{h+1} - \mathbf{r}_h \cdot (\mathbf{r}_h - \mathbf{r}_{h-1})}{|\mathbf{r}_{h+1} - \mathbf{r}_h| |\mathbf{r}_h - \mathbf{r}_{h-1}|} \right),
\]

with \( \mathbf{r}_h \) being the position of the \( h \)th particle in the polymer. The first term in (1) controls the distances between the connected beads and the second term enforces the rigidity of the polymers, with \( \Theta_c \) small enough that loop formation in the system can be ignored (figure 1(a)). Note that the stretching part and the bending part of the potential energy are non-zero only if \( |\Delta l_k| < L_c \) for \( k = 1, \ldots, n - 1 \), and \( |\Delta \theta_h| < \Theta_c \) for \( h = 2, \ldots, n - 1 \). The last term in (1) leads to a lowering of the system’s energy by \( (n - 1)\Delta E \) when a \( n \)-mer forms. Increasing \( \Delta E \) thus promotes polymerisation. Note that additional volume exclusion interactions can be added to the...
system, however, the specificity of such interactions are unimportant to our discussion here.

One advantage of this minimal model is that the free energy of the system can be calculated in the dilute limit via a mean-field method (appendix A). The key results are that at thermal equilibrium, the concentration of 1-mers in the system is:

\[ c_1 = P \exp \left( -\frac{1}{n} \right), \quad \text{for } i > 1, \quad (3) \]

where \( n \) is the average size of the polymers in the system, while the monomeric concentration \( c_1 \) approaches the fixed threshold concentration \( C_c \) asymptotically as the total particle concentration \( C_{tot} \) increases. The expression of the threshold concentration is (A.12):

\[ C_c = \frac{4(\beta \Delta E)^{5/2}}{\pi^{3/2} l_0^2 \Theta_c^2} e^{-\beta \Delta E}. \quad (4) \]

These results are of course consistent with well-known analytical results in self-assembling polymeric systems [1, 6, 7], and have also been confirmed by direct simulation methods [6, 8, 9].

In the case of \( C_{tot} \gg C_c \), most particles are in the polymeric form. In this limit (A.11):

\[ \bar{n} = \frac{\pi^{3/4} l_0 L_c^{1/2} \Theta_c^2}{2(\beta \Delta E)^{3/4}} \sqrt{C_{tot} e^{\beta \Delta E}}. \quad (5) \]

This is again consistent with the well-known result that the average aggregate size \( \bar{n} \) scales like \( \sqrt{C_{tot} e^{\beta E / k_B T}} \) [1, 6, 7]. Note that the degree of polymerization is controlled by both the total concentration of particles in the system and the bonding energy.

Because of equation (5) and the overall particle number conservation, the prefactor in (3) has the following form:

\[ P = \frac{C_{tot}}{n} = \frac{4(\beta \Delta E)^{5/2}}{\pi^{3/2} l_0^2 \Theta_c^2} e^{-\beta \Delta E}. \quad (6) \]

Given (3) and (6), the polymer concentration \( C_{poly} \) in the system can be calculated to be:

\[ C_{poly} = P \int_0^\infty di \exp(-i/\bar{n}) = \bar{n} P \quad (7a) \]

\[ = \frac{2(\beta \Delta E)^{5/4}}{\pi^{3/2} l_0 L_c^{1/2} \Theta_c^2} \sqrt{C_{tot} e^{-\beta \Delta E}}. \quad (7b) \]

Here, besides concentrating on the regime of high level of polymerisation (\( C_{tot} \gg C_c \)), I will focus on the dilute regime in which the polymers are far apart [10]. Since the typical length of a polymer is \( n l_0 \), the dilute regime corresponds to \( n l_0^2 C_{poly} \ll 1 \). From (5) and (7b), the restriction can be rewritten as \( l_0^2 C_{tot} \ll e^{-\beta \Delta E / 2} \). Since \( l_0^2 C_c \sim e^{-\beta \Delta E} \) (4), the two restrictions of having a high degree of polymerisation and being in the dilute limit can be satisfied if

\[ e^{-\beta \Delta E} \ll l_0^2 C_{tot} \ll e^{-\beta \Delta E / 2}. \quad (8) \]

2.1. An example

Letting \( L_c = l_0/10, \Theta_c = 0.1 \text{ rad} \approx 5.7^\circ, \) and \( \Delta E = 40k_B T \), one finds that the threshold concentration \( C_c \) is \( 6.1 \times 10^{-13} l_0^{-3} \). If the total solute concentration of \( C_{tot} = 7.6 \times 10^{-5} l_0^{-3} \gg C_c \), which corresponds to the solute’s volume fraction of around \( 4.0 \times 10^{-5} \) (assuming each particle has a volume of \( \pi l_0^3 / 6 \)), the average size \( \bar{n} \) is then 50 and the polymer concentration \( C_{poly} \) is \( 1.5 \times 10^{-6} l_0^{-3} \). Since the typical length of the polymer is \( n l_0 = 50 l_0 \), each polymer in the isotropic phase will...
particle in an $i$-mer, the equation of motion is
\[ k_i \] for a single polymer, whether breakage is by extension [11] or by bending [12]. These results demonstrate that for a single polymer, \( B_{ij} \) is indeed independent of the indices \( i, j \). If the kinetics of polymerisation is correctly described by equation (10), then the above result clearly supports the uniform breakage scheme, at least in the asymptotic limit of high bonding energy. In the following, I will discuss why the Smoluchowski scheme is incorrect.

### 3.2. What’s wrong with the Smoluchowski scheme

In the Smoluchowski picture, the association of two polymers, of sizes \( i \) and \( j \), say, are assumed diffusion-limited and the rate can for instance be calculated as follows: the \( i \)-mer is held

occupy a typical volume of \( 4\pi(n_0/2)^3/3 \approx 6.5 \times 10^4 n_0^3 \). The polymeric system is therefore in the dilute phase since \( 5.2 \times 10^4 L_0^3 \times C_{\text{poly}} \approx 0.098 \). In this system, the monomer concentration \( c_1 \approx C_c \) is negligible (figure 2). Indeed, \( c_1 \) only surpasses \( c_i \) for \( i > 540 \).

### 3. Equilibrium kinetics

I have so far described the static configuration of the system. To consider the system’s kinetics, I will further assume that the particles are in an over-damped environment so that each particle exhibits Brownian motion. For instance, for the \( k \)th particle in an \( n \)-mer, the equation of motion is

\[
\frac{dr_k}{dt} = -\frac{1}{\zeta} \nabla r_k U_n + \sqrt{\frac{2k_B T}{\zeta}} f_k
\]

(9)

where the potential function \( U_n \) is described by (1), \( \zeta \) is the damping coefficient and \( f_k \) denotes three dimensional independent Gaussian noises with zero mean and unit variance.

Driven by thermal perturbations, the monomers’ positions fluctuate and a polymer will eventually be broken either because a particular angle goes beyond the threshold angle \( \Theta_n \), or because a particular length gets beyond the threshold length \( L_n \). On the other hand, two polymers can rejoin if one polymer’s end encounter the other’s at the right distance and angle. As a result, even though the exponential size distribution does not change with time, the breakage and association events happen continuously and the whole system is in a dynamical equilibrium.

In the dilute limit, the kinetic equations that describe the evolution of the set of concentrations \( \{c_i\} \) can be written generically as [5]

\[
\frac{dc_i}{dt} = \frac{1}{2} \sum_{i+j=k} A_{ij} c_i c_j - c_i \sum_{j \neq i} A_{ik} c_j + \sum_{j \neq i} B_{ij} c_j + c_k \sum_{i+j=k} B_{ij}
\]

(10)

where \( A_{ij} c_i c_j \) describe the association rates of pairs of \( i \)-mers and \( j \)-mers per unit volume, while \( B_{ij} \) corresponds to the breakage rate of a \((i+j)\)-mer into a \(i\)-mer and an \(j\)-mer (figure 1(b)). Note that the above set of kinetic equations is completely general and there are only two underlying assumptions: (1) third-body interactions can be ignored due to the dilute-limit condition \( (C_{\text{poly}} L_0^3 \ll 1) \), and (2) the breakage of a polymer is independent of the other polymers around it, which is again motivated by the dilute-limit condition.

To describe the kinetics of polymerization from first principles, one thus need to calculate the sets of \( \{A_{ij}\} \) and \( \{B_{ij}\} \) for \( i, j \in \mathbb{N} \). This task is drastically simplified at thermal equilibrium since the detailed balance conditions dictate that [5]:

\[
A_{ij} c_i c_j = B_{ij} c_{i+j}
\]

(11)

\[
P A_{ij} = B_{ij}
\]

(12)

where the second equality comes from using the equilibrium distribution of \( c_i \) (3). In other words, specifying \( \{A_{ij}\} \) or \( \{B_{ij}\} \) suffices to determine completely the kinetic scheme at thermal equilibrium.

#### 3.1. Two scenarios: Smoluchowski scheme versus uniform breakage scheme

There are two prevailing kinetic schemes of polymerization at equilibrium. The first one assumes that \( A_{ij} = A \) and \( B_{ij} = B \), i.e. both association and breakage events are independent of the sizes of the polymers involved [1, 5]. The uniform breakage scheme has been typically postulated in an ad hoc manner, motivated mainly by its analytical tractability.

In the second kinetic scenario [4], the rates of polymer association are calculated by assuming that association events are diffusion-limited (the Smoluchowski scheme). Using this approach, it is natural to conclude that \( A_{ij} \) would be smaller than \( A_{ik} \) if both \( i \) and \( j \) are greater than \( h \) and \( k \) since long polymers diffuse less quickly than shorter ones. In other words, \( \{A_{ij}\} \) and thus also \( \{B_{ij}\} \) depend on indices \( i \) and \( j \), which is of course incompatible with the uniform breakage scheme.

Recently, I have proved mathematically that in the asymptotic limit of high bonding energy, the breakage propensity of each bond in a freely diffusing polymer is independent of the location and the length of the polymer, irrespectively of whether breakage is by extension [11] or by bending [12]. These results demonstrate that for a single polymer, \( B_{ij} \) is indeed independent of the indices \( i, j \). If the kinetics of polymerisation is correctly described by equation (10), then the above result clearly supports the uniform breakage scheme, at least in the asymptotic limit of high bonding energy. In the following, I will discuss why the Smoluchowski scheme is incorrect.
stationary at the origin and the concentration profile of the $j$-mer results from solving the diffusive equation such that the concentration is zero if the configurations allow the two polymers to join up; while the concentration is non-varying and equal to $c_j$ far from the origin [4, 13].

I will now show that such an approximation is problematic because it turns out that in the high $\Delta E$ limit, almost all polymers will break and re-join with their fragments many times over before diffusion takes them to other polymers far away. To demonstrate this, I will first consider the association kernel for polymers $i$ and $j$ ($A_{ij}^{\text{Smol}}$), and then obtain the corresponding breakage rate ($B_{ij}^{\text{Smol}}$) via the detailed balance condition (12). This will be compared with the correct asymptotic ($\Delta E \to \infty$) breakage rate $B = B_{ij}$ calculated previously [11, 12].

Starting with the Smoluchowski picture, the association rate per unit volume has been calculated by Hill [4]:

$$A_{ij}^{\text{Smol}} c_i c_j = \frac{\pi k_B T L_c^2 \Theta_i^2}{4 l_0^2} \frac{j \log i + i \log j}{ij(i+j)} c_i c_j,$$

(13)

which gives, via the detailed balance condition in (12), the breakage rate as follows:

$$B_{ij}^{\text{Smol}} = A_{ij}^{\text{Smol}} P = \frac{\pi^3 L_c^2}{4 l_0^2 \Theta_i^2} \frac{j \log i + i \log j}{ij(i+j)} (\beta \Delta E)^{3/2} e^{-\beta \Delta E}.$$

(14)

On the other hand, the breakage rate by bending due to thermal perturbations in the limit $\Delta E \to \infty$ is [12]:

$$B_{ij}^{\text{bend}} = \frac{24 k_B T}{l_0^2 \Theta_i^2} (\beta \Delta E)^2 e^{-\beta \Delta E},$$

(15)

and the corresponding breakage rate by extension is [11]:

$$B_{ij}^{\text{ext}} = \frac{8 k_B T}{\sqrt{\pi} L_c^3} (\beta \Delta E)^{3/2} e^{-\beta \Delta E}.$$

(16)

Let us now consider the following ratios:

$$\frac{B_{ij}^{\text{Smol}}}{B_{ij}^{\text{bend}}} = \frac{\pi^3 L_c^2}{24 l_0^2} \frac{i \log j + j \log i}{ij(i+j)} \sqrt{\beta \Delta E},$$

(17a)

$$\frac{B_{ij}^{\text{Smol}}}{B_{ij}^{\text{ext}}} = \frac{\pi^3 L_c^2}{8 l_0^2 \Theta_i^2} \frac{i \log j + j \log i}{ij(i+j)} \beta \Delta E.$$

(17b)

Superficially, $B_{ij}^{\text{Smol}}$ dominates over $B_{ij}^{\text{bend, ext}}$ when $\Delta E$ becomes large, however since the typical polymer length also grows exponentially with $\Delta E$, the ratios in equation (17) for almost all pairs of polymers go to zero exponentially rapidly as $\Delta E$ grows. For instance, for two polymers of the average size $n$:

$$\frac{B_{ij}^{\text{Smol}}}{B_{ij}^{\text{bend}}} = \frac{\pi^3 L_c^2 \sqrt{\beta \Delta E} \log n}{24 l_0^2} \frac{\log n}{n^2} \sim (\beta \Delta E)^2 e^{-\beta \Delta E} \to \Delta E \to \infty 0,$$

(18a)

where (18b) follows from (5).

More generally, the expressions in (17) indicates that both ratios are negligible if $\min(i, j) \gg \beta \Delta E$. Since given any integer $k$, the fraction of polymers of sizes smaller than $k$ is

$$\frac{1}{c_{\text{poly}}} \int_0^k c_i di = 1 - e^{-k/n} \approx k/n \sim ke^{-\beta \Delta E/2},$$

we see that as $\beta \Delta E \to \infty$, most polymers in the system are of sizes of order $e^{-\beta \Delta E/2}$. In other words, the ratios in (17) go to zero.
expontially quickly for almost all pairs of polymers in the system. Rephrasing this more mathematically, for any small and positive number \( \epsilon \), there exists a threshold \( \beta \Delta E \) beyond which the ratios in (17) are smaller than \( \epsilon \) for \( (1 - \epsilon) \) fraction of all polymer pairs in the systems. This result shows that the breakage rate as obtained in the Smoluchowski picture is typically negligible in the high bonding energy limit compared to the actual breakage rate. Importantly, this does not merely suggests that the contribution from the Smoluchowski scenario can be ignored, instead, it points to the fact that in an association event, the far field limit being the dominant source is incorrect. Rather, the dominant source originates from the very ends of the polymers concerned. I will illustrate this dynamical picture in a simplified model in section 4.

To summarise this section, by comparing the relative magnitude of the breakage rates calculated from the Smoluchowski and the uniform breakage schemes, I have demonstrated that the equilibrium kinetics of the minimal system considered here is correctly described by the uniform breakage scheme, in the asymptotic limit of \( \beta \Delta E \to \infty \).

### 3.3. Equilibrium kinetics of example

As an example, I will now consider the ratios in (17) with the concrete example introduced in section 2.1. Using again the parameters in section 2.1, \( B^{\text{bend}}/B^{\text{ext}} \approx 34 \) and so the breakage of a free polymer is predominantly via bending. In particular, if we assume the system is a collection of colloid of diameters \( l_0 = 10 \text{ nm} \) in water, the damping coefficient \( \zeta \) is, via the Einstein–Stokes relation, \( 6 \pi \eta l_0 \) where \( \eta \) is the dynamic viscosity of water, the resulting breakage rate is then \( B^{\text{bend}} \approx 8.0 \times 10^{-6} \) per second at \( T = 300 \text{ K} \). The expression (17a) is shown in figure 3, demonstrating that the ratio \( c_n/c_{n+2} \) is expected to be smaller than the actual particle separation \( l_0 \). \( \beta \Delta E \) generically has to be very large in order for the ratios in equation (18) to be greater than 1. For instance, in the present case where \( L_c/l_0 = 0.1 \) and \( \Theta_0 = 0.1 \), even for \( i = j = 2 \), the ratios are greater than 1 only if \( \beta \Delta E > 147 \) in (18b).

### 4. A simplified three-species model

To clarify the dynamics of breakage and association, I will now consider a simplified model where there are only three types of polymers in the system: dimers, n-mers where \( n \gg 1 \), and \( (n + 2) \)-mers. In this simplified three-species model, one can again minimise the free energy of the system, similar to what is done in appendix A, in order to calculate the concentrations of three distinct types of polymers: \( c_2 \), \( c_n \) and \( c_{n+2} \). I will now use one of the end beads of the n-mer as our reference frame, i.e. our reference frame diffuses with the end bead. We have seen that as far as the association event is concerned, the source of the dimer is not from the far field, but rather from the breakage of the \( (n + 2) \)-mer that created the two polymers in the first place. As a result, the source of the dimer is in fact at the ends of the n-mer, and upon breaking away, it diffuses around until it gets reabsorbed by the n-mer to form a \( (n + 2) \)-mer, or potentially less likely,diffuses to the surrounding of another n-mer far away and gets reabsorb there. The actual concentration field of the dimer will of course be highly dependent on the specific model used, such as how the steric interactions are modelled, however the underlying physics is universal: the concentration field at equilibrium of a dimer around an n-mer corresponds to solving the diffusion equation subject to the following boundary conditions: (1) the source comes from the breakage point at the two ends of the n-mer centred in a box of volume \( 1/c_n \) with no-flux boundary condition at the boundary; (2) there is a absorbing boundary that corresponds to the event when the dimer and the n-mer can re-join to form an \( (n + 2) \)-mer; and (3) any further boundary conditions due to the steric interactions between the two polymers.

An example of the equilibrium spatial distribution of a dimer around an n-mer is illustrated in figure 2. Here, the system is two-dimensional (2D) and the reference frame is chosen such that the long n-mer \( (n \gg 1) \) is held fixed vertically. As aforementioned, the dominant source of the dimer is at the end of the n-mer, i.e. the dimer is produced through breakage off from the n-mer. It then diffuses around within the bounding box until it re-attaches with the n-mer to form a \( (n + 2) \)-mer. The average orientation of the dimer around the n-mer is also shown in figure 2(b).

### 5. Summary and outlook

By focusing on an analytically tractable model of a self-assembling polymeric system, I have demonstrated that the equilibrium kinetics of the system in the limits of high bonding energy and dilute concentration is well described by the uniform breakage scheme. Although the model considered assumes a specific form of the potential energy functions for simplicity, the same conclusion is expected to hold for more general energy functions since the breakage propensity remain uniform even when the binding energy functions are not quadratic [11, 12].

Shifting down from the high bonding energy regime, the picture is unclear. First, the breakage propensity may no longer be uniform across a polymer [11, 12]; second, the ratios in (17) may no longer be negligible for the majority of the polymer pairs in the system. Therefore, what the quantitative model in this regime is regarding the equilibrium kinetics remains an interesting open problem.

### Appendix A. Equilibrium configuration

In this appendix, I will review how the equilibrium configuration can be obtained from minimising the free energy of the system, which is a summary of the analytical calculations presented in [14]. Note that a similar calculation has also been performed for self-assembling, flexible polymers in [6].

To calculate the polymer length distribution at thermal equilibrium, I will start with the total partition function.
\[ Z_{\text{tot}} = \prod_{i} \left( \frac{1}{N_i!} \left( \frac{V_{c,i}}{\Lambda^3} \right)^{N_i} \right), \tag{A.1} \]

where \( N_i \) is the number of \( i \)-mers in the system with volume \( V \), and \( \Lambda \) is an immaterial constant of dimension \( V^{1/3} \) to render the partition function dimensionless. The prime above the product sign refers to the particle number conservation condition: \( \sum \delta_i N_i = N_{\text{tot}} \) where \( N_{\text{tot}} \) is the total number of particles in the system. Furthermore, \( z_i \) is the configurational partition function of an \( i \)-mer such that the position of the first particle in the polymer is fixed, which I will calculate later.

To study the equilibrium configuration of the system, I minimise the total free energy density:

\[ f_{\text{tot}} = \frac{F_{\text{tot}}}{V} = -\frac{1}{3V} \ln Z_{\text{tot}}, \tag{A.2} \]

with respect to the polymer number distribution \( \{N_i\} \) conditional on the overall conservation of particle number.

Focusing on a polymeric system with a large average size, one can approximate \( f_{\text{tot}} \) as a functional of \( \{n_i\} \):

\[ f_{\text{tot}}[\{n_i\}] \approx \beta^{-1} \int_0^\infty n_i \left[ \ln(n_L) - \chi_i + \xi - 1 \right] \, \mathrm{d}i, \tag{A.3} \]

where \( n_i \equiv N_i/V \) and

\[ \ln z_i = \chi i - \xi. \tag{A.4} \]

By minimizing the above functional subject to the number conservation condition \( \int_0^\infty n_i \, \mathrm{d}i = N_{\text{tot}}/V \equiv C_{\text{tot}} \), one finds

\[ n_i = \frac{e^{-i/n}}{\Lambda^3 \xi} \tag{A.5} \]

where

\[ \bar{n} = \sqrt{\Lambda^3 \xi C_{\text{tot}}}. \tag{A.6} \]

To obtain an analytical expression for \( \xi \), we need to calculate the \( i \)-mer partition function \( z_i \), which is of the form:

\[ z_i = \frac{4\pi\beta L_0^2 \beta \Delta E}{\Lambda^{3(i-1)}} \exp \left[ \int_{-L}^{L} \left( -\frac{\beta \Delta E \Delta E^2}{L_0^2} \right) \, \mathrm{d}L \right] \]

\[ \times \left[ 2\pi L_0^2 \int_0^{\theta_i} \sin(\Delta \theta) \exp \left( -\frac{\beta \Delta E \Delta E^2}{\Theta_0^2} \right) \, \mathrm{d}\Delta \theta \right]^{-2}, \tag{A.7} \]

where the term \( 4\pi\beta L_0^2 \beta \Delta E \) comes from the surface area swept out by the second bead connected to the first bead which is assumed fixed in position, and the exponential term results from the \( (i-1) \) bonds in the \( i \)-mer. The term in the first squared brackets comes from the extensible degree of freedom in each bond, and the term in the second squared brackets comes from the bending degree of freedom between every pair of consecutive bonds.

Since \( \beta \Delta E \) is assumed to be large, I will approximate \( z_i \) by extending the limits of the integrals as follows:

\[ z_i \approx \frac{4\pi\beta L_0^2 \beta \Delta E}{\Lambda^{3(i-1)}} \left[ \int_{-\infty}^{\infty} \exp \left( -\frac{\beta \Delta E \Delta E^2}{L_0^2} \right) \, \mathrm{d}\Delta L \right]^{-1} \]

\[ \times \left[ 2\pi L_0^2 \int_0^{\theta_i} \sin(\Delta \theta) \exp \left( -\frac{\beta \Delta E \Delta E^2}{\Theta_0^2} \right) \, \mathrm{d}\Delta \theta \right]^{-2}. \tag{A.9a} \]

where in \( (A.9b) \), only the leading order term in \( \beta \Delta E^{-1} \) is kept for the integral w.r.t. \( \Delta \theta \).

Since \( \ln z_i = \chi i - \xi \) by definition \( (A.4) \), one can see that

\[ \xi = \beta \Delta E - \ln \frac{4\Lambda^3 (\beta \Delta E)^{5/2}}{\pi^{7/2} L_0^2 \theta_0^2}. \tag{A.10} \]

Given this expression, we can finally find from \( (A.6) \) that

\[ \bar{n} = \frac{\pi^{3/4} L_0^2 L_{\Delta E}^{1/2} \theta_0^2}{2(\beta \Delta E)^{5/4}} \sqrt{\text{C}_{\text{tot}} e^{\beta \Delta E}}. \tag{A.11} \]

The monomer threshold concentration \( C_c \) corresponds to the concentration \( C_{\text{tot}} \) at which \( \bar{n} = 1 \) \[14] \). Therefore,

\[ C_c = \frac{4(\Delta E)^{5/2}}{\pi^{7/2} L_0^2 \theta_0^2} \bar{n} e^{-\beta \Delta E}. \tag{A.12} \]

Note that when \( C_{\text{tot}} \gg C_c \), we can ignore the monomer concentration and \( \bar{n} \) corresponds to the mean size of the polymers in the system \( (A.5) \). However, when \( C_{\text{tot}} \ll C_c, \bar{n} < 1 \) and it signifies that most particles are in the monomeric form \[6, 14\].

### Appendix B. Details of simulation

For the dimer, the longitudinal diffusion coefficient \( (DC) \) is taken to be \( 2/4\pi \), the horizontal DC \( 2/8\pi \), and the rotational DC \( 3/(8\pi 2) \) \[10\]. Simulation is done in 2D and the dimension of the system is \([-4, 4] \times [-4, 4]\), with periodic boundary condition in the \( x \)-direction and hard wall boundary condition in the \( y \)-direction. The dimer is initiated at the breakage point and then allowed to diffuse until reabsorbed by the \( n \)-mer, upon which it is immediately re-positioned to the breakage point. Results are from a simulation of \( 5 \times 10^6 \) time units. The model parameters are: \( l_0 = 1, \Delta_c = 0.2, \Theta_c = 0.5 \) rad.

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