On the Approximability and Hardness of Minimum Topic Connected Overlay and Its Special Instances✩,✩✩

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Abstract

In the context of designing a scalable overlay network to support decentralized topic-based pub/sub communication, the Minimum Topic-Connected Overlay problem (Min-TCO in short) has been investigated: Given a set of \( t \) topics and a collection of \( n \) users together with the lists of topics they are interested in, the aim is to connect these users to a network by a minimum number of edges such that every graph induced by users interested in a common topic is connected. It is known that Min-TCO is \( \mathsf{NP} \)-hard and approximable within \( O(\log t) \) in polynomial time.

In this paper, we further investigate the problem and some of its special instances. We give various hardness results for instances where the number of topics in which an user is interested in is bounded by a constant, and also for the instances where the number of users interested in a common topic is constant. For the latter case, we present a first constant approximation algorithm. We also present some polynomial-time algorithms for very restricted instances of Min-TCO.

Keywords: topic-connected overlay, approximation algorithm, APX, hardness

1. Introduction

Recently, the spreading of social networks and other services based on sharing content allowed the development of many-to-many communication, often supported by these services. Publishers publish information through a logical
channel that is consumed by subscribed users. This environment is often modeled by publish/subscribe (pub/sub) systems that can be classified into two categories. When the channels are associated with a collection of attributes and the messages are delivered to a subscriber only if their attributes match user-defined constraints, we speak about content-based pub/sub systems. Each channel in topic-based pub/sub systems is associated with a single topic and the messages are distributed to the users via channels by his/her topic selection. There are numerous implementations of pub/sub systems, for details see [1, 4, 6, 7, 22, 23, 25].

In our paper, we focus on topic-based peer-to-peer pub/sub systems. In such a system, subscribers interested in a particular topic have to be connected without the use of intermediate agents (such as servers). Many aspects of such a system can be studied (see [9, 20]). Minimizing the diameter of the overlay network can minimize the overall time in which a message is distributed to all the subscribers. When minimizing the (average) degree of nodes in the network, the subscribers need to maintain a smaller number of connections. In this paper, we study the minimization of the overall number of connections in the system. A small number of connections may be necessary due to maintenance requirements or may be helpful since thus information aggregated into a single message can be broadcasted to the network and thus amortize the head count of otherwise small messages.

We study here the hardness of Minimum Topic-Connected Overlay (Min-TCO) which was studied in different scenarios in [2, 3, 17, 18]. In Min-TCO, we are given a collection of users, a set of topics, and a user-interest assignment, we want to connect users in an overlay network $G$ such that all users interested in a common topic are connected and the overall number of edges in $G$ is minimal. The hardness of the problem was studied in [9] and [2]. In [9], the inapproximability by a constant was proved and a logarithmic-factor approximation algorithm was presented. In [2], the lower bound on the approximability of Min-TCO was improved to $\Omega(\log(n))$, where $n$ is the number of users.

Moreover, we focus here on special instances of Min-TCO. We study the case where, for each topic, there is a constant number of users interested in it. We also consider the case where the number of topics in which any user is interested is bounded by a constant. We believe that such restrictions on the instances have wide practical applications such as when a publisher has a limited number of slots for users or the user’s application limits the number of topics that he/she can follow.

In the study of the general Min-TCO, we extend the method presented in [9] and design an approximation-preserving reduction from instances of the minimum hitting set problem to instances of Min-TCO. This reduction does not only prove a similar lower bound as in [2], but also shows that Min-TCO is \textbf{LOGAPX}-complete and thus, concerning approximability, equivalent with such a famous problem as the minimum set cover. As our reduction is not blowing up the number of users interested in a common topic, the reduction is also an approximation-preserving reduction for the case where the number of users interested in a common topic is limited to a constant. Furthermore, we
design a one-to-one reduction of these instances to special instances of the hitting set problem. As these special instances of the hitting set problem are constantly approximable, we immediately obtain the first approximation algorithm for our special instances. This, together with our approximation preserving reduction, shows that the restriction of Min-TCO to such special instances is \text{APX}-complete. Finally, due to the one-to-one reduction and the properties of the special instances of hitting set problem, we show the existence of a polynomial-size kernel and a non-trivial exact algorithm, all for the instances of Min-TCO where the number of users interested in a common topic is bounded by a constant.

For the case, where the number of topics of Min-TCO is bounded from above by \((1 + \varepsilon(n))^{-1} \cdot \log \log n\) for \(\varepsilon(n) \geq \frac{3}{\log \log n} - \frac{3}{2 \log \log \log n}\) (\(n\) is the number of users), we present a polynomial-time algorithm that computes the optimal solution.

In the study of instances where the number of topics any user is interested in is restricted to a constant, we show that, if this number is at most 6, Min-TCO cannot be approximated within a factor of \(694/693\) in polynomial time, unless \(P = NP\), even if any pair of two users is interested in at most three common topics.

The paper is organized as follows. Section 2 is devoted to the preliminaries and a summary of known results. The hardness, approximation results, kernelization and an exact algorithm for instances of Min-TCO, where we limit the number of users interested in a common topic by a constant, are discussed in Section 3. This section also provides the discussion about \text{LOGAPX}-completeness of the general Min-TCO. The results related to the instances of Min-TCO, where the number of topics that each user is interested in is constant, are presented in Section 4. Section 5 contains a polynomial-time algorithm that solves Min-TCO when the number of topics is small. The conclusion is provided in Section 6.

2. Preliminaries

In this section, we define basic notions used throughout the paper. We assume that the reader is familiar with notions of graph theory. Let \(G = (V, E)\) be an undirected graph, where \(V\) is the set of vertices and \(E\) is the set of edges. Let \(V(G)\) and \(E(G)\) denote the set of vertices and the set of edges of \(G\), respectively. We denote by \(E[S]\) the set of edges of \(G\) in the subgraph induced by the vertices from \(S \subseteq V\), i.e., \(E[S] = \{\{u, v\} \in E \mid u, v \in S\}\). The graph induced by \(S \subseteq V\) is denoted as \(G[S] = (S, E[S])\). By \(N[v]\) we denote the closed neighborhood of vertex \(v\), i.e., \(N[v] = \{u \in V \mid \{u, v\} \in E\} \cup \{v\}\). A graph \(G\) is called connected, if, for any \(u_1, u_\ell \in V\), there exists a path \((u_1, u_2, \ldots, u_\ell)\) such that \(\{u_i, u_{i+1}\} \in E\), for all \(1 \leq i < \ell\).

Let \(x\) be an instance of an optimization problem (in this paper, Min-TCO, Min-VC or Min-HS), then by \(|x|\) we denote the size of this instance, i.e., the number of vertices and topics of an instance of Min-TCO and the number of elements and sets of an instance of Min-HS. For a set \(S\), \(|S|\) denotes the size of the set, i.e., the number of its elements.
The set of users or nodes of our network is denoted by \( U = \{ u_1, u_2, \ldots, u_n \} \). The topics are \( T = \{ t_1, t_2, \ldots, t_m \} \). Each user subscribes to several topics. This relation is expressed by the user interest function \( \text{INT} : U \rightarrow 2^T \). The set of all vertices of \( U \) interested in a topic \( t \) is denoted by \( U_t \). For a given set of users \( U \), a set of topics \( T \), and an interest function \( \text{INT} \), we say that a graph \( G = (U, E) \) is \( t \)-topic-connected, for \( t \in T \), if the subgraph \( G[U_t] \) is connected. We call the graph topic-connected if it is \( t \)-topic-connected for each topic \( t \in T \). Note that the topic-connectedness property implies that a message published for topic \( t \) is transmitted to all users interested in this topic without using non-interested users as intermediate nodes.

The most general problem that we study in this paper is called Minimum Topic Connected Overlay:

**Problem 1.** Min-TCO is the following optimization problem:

**Input:** A set of users \( U \), a set of topics \( T \), and an user interest function \( \text{INT} : U \rightarrow 2^T \).

**Feasible solutions:** Any set of edges \( E \subseteq \{ \{ u, v \} \mid u, v \in U \land u \neq v \} \) such that the graph \( (U, E) \) is topic-connected.

**Costs:** Size of \( E \).

**Goal:** Minimization.

In this paper we study also some of its special instances. We restrict the number of users that are interested in a common topic, i.e., the size of \( U_t \), to a constant. We also study the instances where each user is interested in a constant number of topics. The definitions necessary for these special instances are summarized in the beginning of the corresponding section.

We refer here to the famous minimum hitting set problem (Min-HS) and minimum set cover problem (Min-SC). In Min-HS, we are given a system of sets \( S = \{ S_1, \ldots, S_m \} \) on \( n \) elements \( X = \{ x_1, \ldots, x_n \} \) (i.e., \( S_j \subseteq X \)). A feasible solution of this problem is a set \( H \subseteq X \), such that \( S_j \cap H \neq \emptyset \) for all \( j \). Our goal is to minimize the size of \( H \). The Min-SC is the dual problem to Min-HS. In this problem, we are given a system of sets \( S = \{ S_1, \ldots, S_m \} \) on \( n \) elements \( X = \{ x_1, \ldots, x_n \} \), a feasible solution is a set \( S \subseteq \mathcal{S} \) of sets such that for all \( i \) there exists \( j \) such that \( x_i \in S_j \in S \) and the goal is the minimization of the size of \( S \).

There are many modifications and subproblems of the hitting set problem that are intensively studied. In our paper, we refer to the \( d \)-HS problem – a restriction of Min-HS to instances where \( |S_i| \leq d \) for all \( i \).

The Min-HS is equivalent to the Min-SC ([3]), thus all the properties of Min-SC carry over to Min-HS. Following from these properties, we have \( \text{LOGAPX} \)-completeness of Min-HS ([10]) and \( \text{APX} \)-completeness of \( d \)-HS ([21]). There is a well known \( d \)-approximation algorithm for \( d \)-HS ([3]), it can be approximated

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with ratio \( d - \frac{(d-1)\ln n}{\ln n} \) (12), it is \( \mathcal{NP} \)-hard to approximate it within a factor 
\( (d - 1 - \varepsilon) \) (11) and \( d \)-HS is not approximable within a factor better than \( d \), 
unless the unique games conjecture fails (15).

We use the standard definitions from complexity theory (for details see 13):

- For \( \mathcal{NP} \) problems in the class \( \mathcal{PTAS} \), there exists an algorithm that, 
  for arbitrary \( \varepsilon > 0 \), produces a solution in time polynomial in the input 
  size (but possibly exponential in \( 1/\varepsilon \)) that is within a factor \((1 + \varepsilon)\) from 
  optimal.

- The \( \mathcal{NP} \) problems in the class \( \mathcal{APX} \) are approximable by some constant-
  factor approximation algorithm in polynomial time.

- For \( \mathcal{NP} \) problems in the class \( \mathcal{LOGAPX} \), there exists a polynomial-time 
  logarithmic-factor approximation algorithm.

Thus

\[ \mathcal{PTAS} \subseteq \mathcal{APX} \subseteq \mathcal{LOGAPX}. \]

**Definition 1.** Let \( A \) and \( B \) be two \( \mathcal{NP} \) minimization problems. Let \( I_A \) and 
\( I_B \) be the sets of the instances of \( A \) and \( B \), respectively. Let \( S_A(x) \) and \( S_B(y) \) be 
the sets of the feasible solutions and let \( \text{cost}_A(x) \) and \( \text{cost}_B(y) \) be polynomially 
computable measures of the instances \( x \in I_A \) and \( y \in I_B \), respectively. We say 
that \( A \) is \( \mathcal{AP} \)-reducible to \( B \), if there exist functions \( f \) and \( g \) and a constant 
\( \alpha > 0 \) such that:

1. For any \( x \in I_A \) and any \( \varepsilon > 0 \), \( f(x, \varepsilon) \in I_B \).
2. For any \( x \in I_A \), for any \( \varepsilon > 0 \), and any \( y \in S_B(f(x, \varepsilon)) \), \( g(x, y, \varepsilon) \in S_A(x) \).
3. The functions \( f \) and \( g \) are computable in polynomial time with respect to 
   the sizes of instances \( x \) and \( y \), for any fixed \( \varepsilon \).
4. The time complexity of computing \( f \) and \( g \) is nonincreasing with \( \varepsilon \) for all 
   fixed instances of size \( |x| \) and \( |y| \).
5. For any \( x \in I_A \), for any \( \varepsilon > 0 \), and for any \( y \in S_B(f(x, \varepsilon)) \)

\[
\frac{\text{cost}_B(y)}{\min\{\text{cost}_B(z) \mid z \in S_B(f(x, \varepsilon))\}} \leq 1 + \varepsilon \text{ implies}
\]

\[
\frac{\text{cost}_A(g(x, y, \varepsilon))}{\min\{\text{cost}_A(z) \mid z \in S_A(x)\}} \leq 1 + \alpha \cdot \varepsilon.
\]

**3. Results for Min-TCO When The Number of Users Interested in a 
Common Topic is a Constant**

In this whole section, we denote by a triple \( (U, T, \text{INT}) \) an instance of Min-
TCO. We focus here on the case where the number of users that share a topic 
\( t \), i.e., \( \max_{t \in T} |U_t| \), is bounded.

We present here a lower bound on the approximability, a constant approximation 
algorithm and an \( \mathcal{APX} \)-completeness proof for these restricted instances 
of Min-TCO.
3.1. Hardness results

It is easy to see that, if \( \max_{i \in T} |U_i| \leq 2 \), then Min-TCO can be solved in linear time, because two users sharing a topic \( t \) should be directly connected by an edge, which is the unique minimum solution.

**Theorem 1.** If \( \max_{i \in T} |U_i| \leq 2 \), then Min-TCO can be solved in linear time.

We extend the methods from [9] and design an AP-reduction from \( d \)-HS to Min-TCO, where \( \max_{i \in T} |U_i| \leq d + 1 \).

**Theorem 2.** For arbitrary \( d \geq 2 \), there exists an AP-reduction from \( d \)-HS to Min-TCO, where \( \max_{i \in T} |U_i| \leq d + 1 \).

**Proof.** Let \( I_{HS} = (X, S) \) be an instance of \( d \)-HS and let \( \varepsilon > 0 \) be arbitrary. We omit the subscript in the functions \( \text{cost}_{d-HS} \) and \( \text{cost}_{\text{Min-TCO}} \) as they are unambiguous. For the instance \( I_{HS} \), we create an instance \( I_{TCO} = (U, T, \text{INT}) \) of Min-TCO with \( \max_{i \in T} |U_i| \leq d + 1 \) with \(|X| + k \) users, where \( k = |X|^2 \cdot \left\lceil \frac{\varepsilon d + 1}{\varepsilon} \right\rceil \), as follows (the function \( f \) in the definition of AP-reduction).

\[
\begin{align*}
U &= X \cup \{p_i \mid p_i \notin X \land 1 \leq i \leq k\}, \\
T &= \{t_{S_j}^i \mid S_j \in S \land 1 \leq i \leq k\}, \\
\text{INT}(x) &= \begin{cases} \\
\{t_{S_j}^i \mid x \in S_j \land S_j \in S \land 1 \leq i \leq k\} & \text{for } x \in X \\
\{t_{S_j}^i \mid S_j \in S\} & \text{for } x = p_i
\end{cases}
\end{align*}
\]

Observe that the instance contains \( k \cdot |S| \) topics and its size is polynomial in the size of \( I_{HS} \). The users interested in a topic \( t_{S_j}^i \) (\( S_j \in S \)) are exactly the elements that are members of set \( S_j \) in \( d \)-HS plus a special user \( p_i \) (\( 1 \leq i \leq k \)). Let \( \text{Sol}_{TCO} \) be a feasible solution of Min-TCO on instance \( I_{TCO} \). We partition the solution into levels. Level \( i \) is a set \( L_i \) of the edges of \( \text{Sol}_{TCO} \) that are incident with the special user \( p_i \). In addition, we denote by \( L_0 \) the set of edges of \( \text{Sol}_{TCO} \) that are not incident with any special user. Therefore, \( \text{Sol}_{TCO} = \bigcup_{i=0}^k L_i \) and \( L_i \cap L_j = \emptyset \) (\( 0 \leq i < j \leq k \)).

We claim that, for any \( L_i \) (\( 1 \leq i \leq k \)), the set of the non-special users incident with edges of \( L_i \) is a feasible solution of the instance \( I_{HS} \) of \( d \)-HS. This is true since, if a set \( S_j \in S \) is not hit, none of the edges \( \{x, p_i\} \) (\( x \in S_j \)) is in \( L_i \). But then the users interested in topic \( t_{S_j}^i \) are not interconnected as user \( p_i \) is disconnected.

Let \( j \) be chosen such that \( L_j \) is the smallest of all sets \( L_i \), for \( 1 \leq i \leq k \). We construct \( \text{Sol}_{HS} \) by picking all the non-special users that are incident to some edge from \( L_j \) (the function \( g \) in the definition of AP-reduction). Denote an optimal solution of \( d \)-HS and Min-TCO for \( I_{HS} \) and \( I_{TCO} \) by \( \text{Opt}_{HS} \) and \( \text{Opt}_{TCO} \), respectively.

If we knew \( \text{Opt}_{HS} \), we would be able to construct a feasible solution of Min-TCO on \( I_{TCO} \) as follows. First, we pick the edges \( \{x, p_i\}, x \in \text{Opt}_{HS} \), for all special users \( p_i \), and include them in the solution. This way, for any topic
$t \in \text{INT}(p_i)$, we connect $p_i$ to some element of $X$ that is interested in $t$, too. To have a feasible solution, we could miss some edges between some elements of $X$. So, we pick all the edges between elements from $X$. The feasible solution of Min-TCO on $I_{TCO}$ that we obtain has roughly cost

$$k \cdot \text{cost}(\text{Opt}_{HS}) + |X|^2 \geq \text{cost}(\text{Opt}_{TCO}).$$

On the other hand, if we replace all levels $L_i$ ($1 \leq i \leq k$) by level $L_j$ in $\text{Sol}_{TCO}$, we still have a feasible solution of Min-TCO on $I_{TCO}$, with cost possibly smaller. Thus

$$k \cdot \text{cost}(\text{Sol}_{HS}) \leq \text{cost}(\text{Sol}_{TCO}).$$

We use these two inequalities to bound the cost of $\text{Sol}_{HS}$:

$$k \cdot \text{cost}(\text{Sol}_{HS}) \leq \frac{\text{cost}(\text{Sol}_{TCO})}{\text{cost}(\text{Opt}_{TCO})} \cdot (k \cdot \text{cost}(\text{Opt}_{HS}) + |X|^2)$$

and thus

$$\frac{\text{cost}(\text{Sol}_{HS})}{\text{cost}(\text{Opt}_{HS})} \leq \frac{\text{cost}(\text{Sol}_{TCO})}{\text{cost}(\text{Opt}_{TCO})} \cdot \left(1 + \frac{|X|^2}{k}\right).$$

If $\text{cost}(\text{Sol}_{TCO})/\text{cost}(\text{Opt}_{TCO}) \leq 1 + \varepsilon$ and $\alpha := 2$, then we have

$$\frac{\text{cost}(\text{Sol}_{HS})}{\text{cost}(\text{Opt}_{HS})} \leq (1 + \varepsilon) \cdot \left(1 + \frac{|X|^2}{k}\right) \leq (1 + \varepsilon) \cdot \left(1 + \frac{\varepsilon}{1 + \varepsilon}\right) = 1 + 2\varepsilon.$$

It is easy to see that the five conditions of Definition 1 are satisfied and thus we have an AP-reduction.

**Corollary 1.** For any $\delta > 0$ and polynomial-time $\alpha$-approximation algorithm of Min-TCO with $\max_{t \in T} |U_t| \leq d + 1$, there exists a polynomial-time $(\alpha + \delta)$-approximation algorithm of $d$-HS.

**Proof.** The approximation algorithm for $d$-HS would use Theorem 2 with $k := \lfloor \frac{|X|^2}{\alpha} \rfloor$. □

Our theorem also implies the following negative results on approximability. One of them holds if unique games conjecture is true. This conjecture is discussed, for example, in [24] and was introduced by Khot in [14].

**Corollary 2.** Min-TCO with $\max_{t \in T} |U_t| \leq d$ ($d \geq 3$) is $\mathcal{NP}$-hard to approximate within a factor of $(d - 1 - \varepsilon)$, for any $\varepsilon > 0$, and, if the unique games conjecture holds, there is no polynomial-time $(d - \varepsilon)$-approximation algorithm for it.

**Proof.** Otherwise, the reduction described in the proof of Theorem 2 would imply an approximation algorithm for $d$-HS with a ratio better than $d - 1$ and $d$ respectively. This would directly contradict theorems proven in [11] and [13]. □
The following corollary is an improvement of the already known results of [9] where an $O(\log |T|)$-approximation algorithm is presented, and of [2] where a lower bound of $\Omega(\log(n))$ on the approximability is shown. We close the gap by designing a reduction that can reduce any problem from class $\text{LOGAPX}$ to $\text{Min-TCO}$ preserving the approximation ratio up to a constant.

**Corollary 3.** $\text{Min-TCO}$ is $\text{LOGAPX}$-complete.

**Proof.** $\text{Min-TCO}$ is in the class $\text{LOGAPX}$ since it admits a logarithmic approximation algorithm as presented in [9]. Our reduction from the proof of Theorem 2 is independent of $d$ and thus an AP-reduction from $\text{LOGAPX}$-complete $\text{Min-HS}$ to $\text{Min-TCO}$. $\square$

### 3.2. A Constant Approximation Algorithm

In this subsection, we present a reduction from $\text{Min-TCO}$ with $\max_{t \in T} |U_t| \leq d$ to $O(d^2)$-$\text{HS}$ thus showing that there exists a constant approximation algorithm for $\text{Min-TCO}$ with $\max_{t \in T} |U_t| \leq d$ as $d$-$\text{HS}$ is constantly approximable. Moreover, the constant approximation algorithm classifies this problem to be a member of the class $\text{APX}$ and thus, since the $\text{APX}$-hardness was proven in Subsection 3.1, we conclude that $\text{Min-TCO}$ with $\max_{t \in T} |U_t| \leq d$ is $\text{APX}$-complete.

Recall that a partition of vertices $V$ in graph $G$ is a tuple $(A, B)$, such that $A \subseteq V$, $B \subseteq V$, $A \cap B = \emptyset$, and $A \cup B = V$.

**Definition 2.** Let $V = \{v_1, \ldots, v_n\}$ be a set of vertices and for every partition $(A_i, B_i)$ of $V$, let $E_i = \{\{u, v\} \mid u \in A_i \land v \in B_i\}$. Then we call the system $S = \{E_1, \ldots, E_m\}$ of all sets of edges between vertices of all the partitions of $V$ a characteristic system of edges on $V$. In other words, $S$ contains all sets of edges that form a maximum bipartite graph on $V$.

In the following lemma, we show the basic properties of characteristic systems of edges.

**Lemma 1.** Let $S = \{E_1, \ldots, E_m\}$ be a characteristic system of edges on the set $V$ of $n$ vertices. Then

1. $m = 2^{n-1} - 1$.
2. $|E_j| \leq \lfloor n/2 \rfloor \cdot \lceil n/2 \rceil$, for all $j$, $1 \leq j \leq m$.
3. Any two sets $E_i$ and $E_j$ differ in at least $n - 1$ elements ($1 \leq i < j \leq m$).
4. $H \subseteq \{\{u, v\} \mid u, v \in V \land u \neq v\}$ is a hitting set of $((\{u, v\} \mid u, v \in V \land u \neq v), S)$ if and only if $(V, H)$ is connected.
5. The size of $S$ is minimal such that part 4 holds.

**Proof.** Observe that the complementary graph $(V, F_j)$ ($F_j = \{\{u, v\} \mid u, v \in V \land u \neq v\} \setminus E_j$) contains two complete graphs – one on the vertices of $A_j$ and other on the vertices of $B_j$, and it is a maximal graph (in the number of edges) that is not connected. We use this observation to prove the last two parts of our lemma.
Part 1. We count the different partitions \((A_j, B_j)\) of the vertices \(V\) as each such partition determines a different set \(E_j\) of edges. There are \(2^n\) ways how to distribute vertices from \(V\) into partitions. We have to subtract 2 possibilities for the cases where one of \(A_j\) or \(B_j\) is empty. Each of the other possibilities is counted twice – once when the vertices are present in \(A_j\) and once when they are present in \(B_j\).

Part 2. Let the two sets of vertices \(A_j\) and \(B_j\) of a partition contain \(k > 0\) and \(n - k\) vertices. Then the size of \(E_j\) is \(k \cdot (n - k)\). This function reaches its maximum for \(k = n/2\) and thus we can conclude that, for all \(j, 1 \leq j \leq m\), we have \(|E_j| \leq \lfloor n/2 \rfloor \cdot (n - \lfloor n/2 \rfloor) = \lfloor n/2 \rfloor \cdot \lceil n/2 \rceil\).

Part 3. Let us consider two different partitions \((A_i, B_i)\) and \((A_j, B_j)\) of the vertices \(V\). The sets \(A_i\) and \(A_j\) must differ by at least one vertex. W.l.o.g., let the vertex \(v \in A_i\) and \(v \notin A_j\). Then, due to the transition of the vertex \(v\) from \(A_i\) to \(B_j\), there are \(|B_j|\) edges that are in \(E_i\) but cannot be in \(E_j\), and there are \(|A_i| - 1\) edges that are not in \(E_i\), but are in \(E_j\). Thus, the overall difference in the number of elements between the sets \(E_i\) and \(E_j\) is at least \(|A_i| + |B_j| - 1 = n - 1\).

Part 4. First, we prove the if case. Suppose that \((V, H)\) is not connected. Since \(S\) contains complements of all maximal sets of edges that induce a disconnected graph, there exists \(j (1 \leq j \leq m)\) such that \(H \subseteq E_j\). But then, since \(E_j\) is complementary to \(F_j\), it follows that \(E_j \cap H = \emptyset\). Thus, \(H\) cannot be a hitting set as \(E_j\) is not hit.

For the only-if case, suppose that \((V, H)\) is connected, but \(H\) is not a hitting set of \((\{\{u, v\} \mid u, v \in V \wedge u \neq v\}, S)\). Then there exists \(j\) such that \(E_j\) is not hit by \(H\) and thus \(H \subseteq F_j\). Yet in such a case, by our assumption, \((V, F_j)\) is not connected and thus \((V, H)\) cannot be connected as well.

Part 5. Let \(S' = S \setminus E_j, (\{\{u, v\} \mid u, v \in V \wedge u \neq v\}, S')\) be an instance of Min-HS. Then we claim that \(F_j\) is a hitting set of \((\{\{u, v\} \mid u, v \in V \wedge u \neq v\}, S')\). First, observe that \(F_j \neq \emptyset\) since \(E_j\) cannot contain all the edges. Moreover, there exists \(e \in E_i\) \((E_i \in S')\) such that \(e \notin E_j\). Then \(e \in \{\{u, v\} \mid u, v \in V \wedge u \neq v\} \setminus E_j = F_j\) and thus \(F_j\) is a hitting set. However, by the definition of \(F_j\), \((V, F_j)\) cannot be connected and thus, the if case of part 4 does not hold.

Now we are ready to present a simple one-to-one reduction of Min-TCO with \(\max_{t \in T} |U_t| \leq d\) to \(O(d^2)\)-HS. The core concept is to construct a system of sets that has to be hit in \(O(d^2)\)-HS as a union over all the topics of the characteristic systems of edges on the vertices interested in the topic.

**Theorem 3.** There exists a one-to-one reduction of instances of Min-TCO with \(\max_{t \in T} |U_t| \leq d\) to instance of \(O(d^2)\)-HS.

**Proof.** Let \(I_{TCO} = (U, T, INT)\) be an instance of Min-TCO with \(\max_{t \in T} |U_t| \leq d\). For each topic \(t \in T\) we define \(S_t\) to be the characteristic system of edges on vertices in \(U_t\). Note that Lemma 1 holds for each \(S_t\) with \(n := d\). We construct
an $O(d^2)$-HS instance $I_{HS} = (X, S)$ as follows:

$$X = \{\{u, v\} \mid u, v \in U \land u \neq v\}$$

$$S = \bigcup_{t \in T} S_t.$$ 

The system contains $\binom{|U|}{2}$ elements and at most $|T| \cdot (2^{d-1} - 1)$ sets in $S$ and thus has a size polynomial in $|I_{TCO}|$. Obviously, the construction of $I_{HS}$ takes time polynomial in $|I_{TCO}|$, too. We now show that a feasible solution of $I_{TCO}$ corresponds to a feasible solution of $I_{HS}$ and vice versa.

First, consider a feasible solution $Sol_{HS}$ of $I_{HS}$ and a topic $t \in T$. Due to our construction, the system $S$ contains the characteristic system $S_t$ on vertices $U_t$. Therefore, by Lemma 1 part 4 and the fact that $Sol_{HS}$ is a hitting set, we know that the graph induced by the edges in $Sol_{HS}$ on vertices $U_t$ is connected.

Now, consider a feasible solution $Sol_{TCO}$ of $I_{TCO}$. By the following argument, we can easily see that $Sol_{TCO}$ hits all the sets in $S$. Let $P \in S$ be a set that is not hit by $Sol_{TCO}$. Then there exists $t$ such that $P \in S_t$ and thus a set of the characteristic system was not hit and $Sol_{TCO}$ is not a hitting set of $S_t$. Yet in such a case, considering Lemma 1 part 4, the subgraph induced on vertices $U_t$ by edges from $Sol_{TCO}$ cannot be connected and that is in contradiction with the definition of $Min-TCO$ with $\max_{t \in T} |U_t| \leq d$.

**Theorem 4.** There exists a polynomial-time $(\lfloor d/2 \rfloor \cdot \lceil d/2 \rceil)$-approximation algorithm for $Min-TCO$ with $\max_{t \in T} |U_t| \leq d$.

**Proof.** We employ the reduction from Theorem 3 together with the well-known $d$-approximation algorithm for $d$-HS. Since the size of each set in $S$ is at most $\lfloor d/2 \rfloor \cdot \lceil d/2 \rceil$ (Lemma 1 part 2), by application of this approximation algorithm on $O(d^2)$-HS instance $(X, S)$ we obtain a $\lfloor d/2 \rfloor \cdot \lceil d/2 \rceil$ approximate solution of our $Min-TCO$ instance with $\max_{t \in T} |U_t| \leq d$.

Note that our reduction is tight in the size of $S$ as it is minimal (Lemma 1 part 5), thus to achieve an improvement in the approximation algorithm, a different method has to be developed.

**Corollary 4.** $Min-TCO$ with $\max_{t \in T} |U_t| \leq 3$ inherits the approximation hardness of $Min-VC$.

**Corollary 5.** $Min-TCO$ with $\max_{t \in T} |U_t| \leq d$ is APX-complete, for arbitrary $d \geq 3$.

**Proof.** The APX-hardness follows from the APX-hardness of $d$-HS ([21]). Due to our reduction the problem belongs to the class APX.

### 3.3. Min-TCO and Parametrized Complexity Theory

In this subsection, we shortly summarize the consequences of our reduction from Theorem 3 for the field of parametrized complexity, namely we present an
exact algorithm and a kernelization for Min-TCO with \( \max_{t \in T} |U_t| \) bounded by a constant.

In the research area of exact algorithm design, one searches for an exact solution in exponential time. The main goal is to make the base of the exponentiation as small as possible.

A kernelization is a process in which an instance is reduced to a smaller instance in polynomial time. Then, instead of solving the original instance, it is sufficient to solve the problem on the smaller one and then, in polynomial time, transform its solution back to the initial instance.

**Problem 2.** Min-\(d\)-TCO\((k)\) is the following parametrized problem:

**Input:** Instance of Min-TCO with \( \max_{t \in T} |U_t| \leq d \) and a parameter \( k \).

**Goal:** A feasible solution of the Min-TCO instance of size at most \( k \).

**Problem 3.** \(d\)-HS\((k)\) is the following parametrized problem:

**Input:** Instance of \(d\)-HS and a parameter \( k \).

**Goal:** A feasible solution of the \(d\)-HS instance of size at most \( k \).

We first transform the given instance of Min-TCO with \( \max_{t \in T} |U_t| \leq d \) into an instance of \( O(d^2)\)-HS as in Theorem 3 and then we apply the kernelization from [16] to obtain a kernel of Min-\(d\)-TCO\((k)\) or the exact algorithm from [19] to obtain the first nontrivial exact algorithm for solving Min-\(d\)-TCO\((k)\).

**Theorem 5.** Min-\(d\)-TCO\((k)\) has a kernel of size \((2c - 1) \cdot k^{c-1} + k\) with \( c = \lfloor d/2 \rfloor \cdot \lceil d/2 \rceil \).

**Theorem 6.** Min-\(d\)-TCO\((k)\) on \( n \) vertices can be solved in time \( O(c^k + n^2) \) with \( c = \lfloor d/2 \rfloor \cdot \lceil d/2 \rceil - 1 + O(d^{-2}) \).

4. **Hardness of Min-TCO When the Number of Connections of a User is Constant**

It is natural to consider Min-TCO with bounded number of connections per user, i.e., to bound \( \max_{u \in U} |\text{INT}(u)| \), since the number of topics in which one user is interested in is usually not too large. We show that, sadly, Min-TCO is APX-hard even if \( \max_{u \in U} |\text{INT}(u)| \leq 6 \). To show this, we design a reduction from minimum vertex cover (Min-VC) to Min-TCO. The minimum vertex cover problem is just a different name for \(d\)-HS with \( d = 2 \). For a better presentation, in this section, we refer to Min-VC instead of \(2\)-HS.

Given is a graph \( G = (V', E') \) and a positive integer \( k \) as an instance of Min-VC, where the goal is to decide whether the given graph has a solution of size at most \( k \). We construct an instance of Min-TCO as follows. Let \( V = V^{(1)} \cup V^{(2)} \) be the set of users, where \( V^{(1)} = \{v^{(1)} \mid v \in V'\} \) and \( V^{(2)} = \{v^{(2)} \mid v \in V'\} \). For
each edge $e \in E'$, we prepare three topics, $t^e(0), t^e(1)$ and $t^e(2)$. The set of topics is
the union of all these topics, i.e., $T = \bigcup_{e \in E'} \{ t^e(0), t^e(1), t^e(2) \}$. The user interest
function $\text{INT}$ is defined as

$$\text{INT}(u^{(1)}) = \bigcup_{e \in E'[N[u]]} \{ t^e(0), t^e(1) \}$$
$$\text{INT}(u^{(2)}) = \bigcup_{e \in E'[N[u]]} \{ t^e(0), t^e(2) \}.$$  

The following lemma shows the relation between the solutions of the two problems.

Lemma 2. The instance $(V, T, \text{INT})$ of $\text{Min-TCO}$ defined as above has an optimal solution of cost $k + 2|E'|$ if and only if the instance $(V', E')$ of $\text{Min-VC}$ has an optimal solution of cost $k$.
Moreover, any feasible solution $H$ of $(V, T, \text{INT})$ can be transformed into a feasible solution of $(V', E')$ of cost at most $|H| - 2|E'|$.

Proof. It is obvious that any feasible solution $H$ of the instance of $\text{Min-TCO}$ contains the edge $\{u^{(i)}, v^{(i)}\}$ $(i \in \{1, 2\})$, for every edge $e = \{u, v\}$, because only $u^{(1)}$ and $v^{(1)}$ (resp., $u^{(2)}$ and $v^{(2)}$) are interested in topic $t^e(1)$ (resp., $t^e(2)$).

Since each feasible solution $H$ of $(V, T, \text{INT})$ must contain the edges $\{u^{(1)}, v^{(1)}\}$ and $\{u^{(2)}, v^{(2)}\}$, for every edge $e = \{u, v\} \in E'$, it is sufficient to consider only the topics $t^e(0)$. The number of edges in $H$ connecting a vertex from $V^{(1)}$ with a vertex from $V^{(2)}$ is at most $|H| - 2|E'|$.

For an edge $e = \{u, v\}$, the vertices that are interested in $t^e(0)$ are $u^{(1)}, v^{(2)}, v^{(1)}$ and $u^{(2)}$. Since these four vertices have to be connected, $H$ contains at least one edge of $\{u^{(1)}, u^{(2)}\}, \{v^{(1)}, v^{(2)}\}, \{u^{(1)}, v^{(2)}\}$ and $\{v^{(1)}, u^{(2)}\}$.

The optimal solution of $(V, T, \text{INT})$ contains at most two of these four edges, namely the edges $\{u^{(1)}, u^{(2)}\}$ and $\{v^{(1)}, v^{(2)}\}$. Observe that, for each edge $f$ that is incident with vertex $u$ in $G$, the edge $\{u^{(1)}, u^{(2)}\}$ connects the solution to be $t^{(0)}$-connected. The only topic that the other two edges connect is $t^{(0)}_{f(u,v)}$ and thus they can be replaced by $\{u^{(1)}, u^{(2)}\}$ or $\{v^{(1)}, v^{(2)}\}$.

In any non-optimal solution, more than two of the four edges may be present and the replacement of edges $\{u^{(1)}, v^{(2)}\}$ and $\{v^{(1)}, v^{(2)}\}$ by $\{u^{(1)}, u^{(2)}\}$ and $\{v^{(1)}, v^{(2)}\}$, respectively, may lead to a decrease of the cost of the solution.

We assume that the solution of $(V, T, \text{INT})$ has been transformed so that it does not contain cross edges between $u^{(1)}$ and $v^{(3-i)}$ $(i \in \{1, 2\})$. The vertices that correspond to the edges between the two layers $V^{(1)}$ and $V^{(2)}$ form a feasible solution of $\text{Min-VC}$. As discussed above, its size is at most $|H| - 2|E'|$ for a feasible solution $H$ and exactly $|H| - 2|E'|$ for an optimal solution $H$. This proves one implication of the first claim and the second claim.

We show that, if $\text{Min-VC}$ has an optimal solution of size $k$, then the instance of $\text{Min-TCO}$ has an optimal solution of size $k + 2|E'|$. From an optimal solution $W \subseteq V'$ of $\text{Min-VC}$, we construct the optimal solution of $\text{Min-TCO}$ as $H = \bigcup_{e \in W} \{ t^e(0), t^e(1), t^e(2) \}$. :
We use the Min-VC on degree-bounded graphs, which is APX-hard, to show lower bounds for our restricted Min-TCO. By the above reduction and the lemma, we prove the following theorem.

Theorem 7. Min-TCO with \( \max_{v \in U} |\text{INT}(v)| \leq 6 \) cannot be approximated within a factor of \( 694/693 \) in polynomial time, unless \( P = NP \), even if \( |\text{INT}(v) \cap \text{INT}(u)| \leq 3 \) holds for every pair of different users \( u, v \in U \).

Proof. We prove the statement by contradiction. Suppose that there exists an approximation algorithm \( A \) for Min-TCO with the above stated restrictions that has the ratio \( (1 + \delta) \).

Let \( G = (V', E') \) be an instance of Min-VC and let \( G \) be cubic and regular (i.e., each vertex is incident with exactly three edges). We construct an instance \( I_{\text{TCO}} \) of Min-TCO as stated above and we apply our algorithm \( A \) to it to obtain a feasible solution \( \text{Sol}_{\text{TCO}} \). From such a solution, by Lemma 2, we create a feasible solution of the original Min-VC instance \( \text{Sol}_{\text{VC}} \). We denote by \( \text{Opt}_{\text{TCO}} \) and \( \text{Opt}_{\text{VC}} \) the optimal solutions of \( I_{\text{TCO}} \) and \( G \), respectively.

Let \( d \) be a constant such that \( d \cdot \text{cost}(\text{Opt}_{\text{VC}}) = 3|V'| \). Since \( G \) is cubic and regular, \( \text{cost}(\text{Opt}_{\text{VC}}) \geq |E'|/3 = |V'|/2 \) and thus \( d \leq 6 \).

Observe that, due to Lemma 2, \( \text{cost}(\text{Opt}_{\text{TCO}}) = \text{cost}(\text{Opt}_{\text{VC}}) + 2|E'| = \text{cost}(\text{Opt}_{\text{VC}}) + d \cdot \text{cost}(\text{Opt}_{\text{VC}}) \) and \( \text{cost}(\text{Sol}_{\text{TCO}}) \geq \text{cost}(\text{Sol}_{\text{VC}}) + 2|E'| = \text{cost}(\text{Sol}_{\text{VC}}) + d \cdot \text{cost}(\text{Opt}_{\text{VC}}) \). These two estimations give us the following bound

\[
\frac{\text{cost}(\text{Sol}_{\text{VC}}) + d \cdot \text{cost}(\text{Opt}_{\text{VC}})}{\text{cost}(\text{Sol}_{\text{VC}}) + d \cdot \text{cost}(\text{Opt}_{\text{VC}})} \leq \frac{\text{cost}(\text{Opt}_{\text{TCO}})}{\text{cost}(\text{Opt}_{\text{TCO}})} \leq 1 + \delta.
\]

The above inequality allows us to bound the ratio of our Min-VC solution \( \text{Sol}_{\text{VC}} \) and the optimal solution \( \text{Opt}_{\text{VC}} \):

\[
\frac{\text{cost}(\text{Sol}_{\text{VC}})}{\text{cost}(\text{Opt}_{\text{VC}})} \leq (1 + \delta) \cdot (d + 1) - d = 1 + \delta(d + 1) \leq 1 + 7\delta.
\]

For \( \delta := \frac{1}{693} \), we obtain a \( \frac{100}{99} \)-approximation algorithm for Min-VC on 3-regular graphs which is directly in contradiction with a theorem proven in [3].

\[ \square \]

Corollary 6. Min-TCO with \( \max_{v \in U} |\text{INT}(v)| \leq 6 \) is APX-hard.

Corollary 7. Min-TCO with \( |\text{INT}(v) \cap \text{INT}(u)| \leq 3 \), for all users \( u, v \in U \), is APX-hard.
This result is almost tight, the case when $|\text{INT}(v) \cap \text{INT}(u)| \leq 2$ is still open. The following theorem shows that Min-TCO with $|\text{INT}(v) \cap \text{INT}(u)| \leq 1$, for every pair of distinct users $u, v \in U$, can be solved in linear time.

**Theorem 8.** Min-TCO can be solved in linear time, if $|\text{INT}(v) \cap \text{INT}(u)| \leq 1$ holds for every pair of users $u, v \in U$, $u \neq v$.

**Proof.** We execute the following simple algorithm. First set the solution $E := \emptyset$. Then sequentially, for each topic $t$, choose its representative $v^* \in U$ ($t \in \text{INT}(v^*)$) and add edges $\{\{v^*, u\} \mid u \in U \setminus \{v^*\}\}$ to the solution $E$. We show that, if $|\text{INT}(v) \cap \text{INT}(u)| \leq 1$, for all distinct $u, v \in U$, then the solution $E$ is optimal.

Observe that, in our case, any edge in any feasible solution is present because of a unique topic. We cannot find an edge $e = \{u, v\}$ of the solution that belongs to the subgraphs for two different topics. (Otherwise $|\text{INT}(v) \cap \text{INT}(u)| > 1$ and our assumption would be wrong for the two endpoints of the edge $e$.) Thus, any solution consisting of spanning trees for every topic is feasible and optimal. Note that its size is $|T| \cdot (|U| - 1)$.

**Corollary 8.** Min-TCO with $\max_{u \in U} |\text{INT}(u)| \leq 2$ can be solved in linear time.

5. A Polynomial-Time Algorithm for Min-TCO with Bounded Number of Topics

In this section, we present a simple brute-force algorithm that achieves a polynomial running time when the number of topics is bounded by $|T| \leq \log \log |U| - \frac{3}{2} \log \log \log |U|$.

**Theorem 9.** The optimal solution of Min-TCO can be computed in polynomial time if $|T| \leq (1 + \varepsilon(|U|))^{-1} \cdot \log \log |U|$, for a function

$$\varepsilon(n) \geq \frac{3/2 \log \log n}{\log \log n - 3/2 \log \log \log n}.$$ 

**Proof.** Let $(U, T, \text{INT})$ be an instance of Min-TCO such that $|T| \leq (1 + \varepsilon(|U|))^{-1} \cdot \log \log |U|$. Moreover, $|T| > 2$, otherwise the problem is solvable in polynomial time. We shorten the notation by setting $t = |T|$ and $n = |U|$.

First observe that, if $u, v \in U$ and $\text{INT}(u) \subseteq \text{INT}(v)$, instead of solving instance $(U, T, \text{INT})$, we can solve Min-TCO on instance $(U \setminus \{u\}, T, \text{INT})$ and add to such solution the direct edge $\{u, v\}$. Note that $u$ has to be incident with at least one edge in any solution. Thus, the addition of the edge $\{u, v\}$ cannot increase the cost. Moreover, any other user that would be connected to $u$ in some solution can be also connected to $v$. Thus, we can remove $u$, solve the smaller instance and then add $u$ by a single edge. Such a solution is feasible and its size is unchanged. We say that vertex $u$ is dominated by the vertex $v$ if $\text{INT}(u) \subseteq \text{INT}(v)$.

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Therefore, before applying our simple algorithm, we remove from the instance all the users that are dominated by some other user. We denote the set of remaining users (i. e., those with incomparable sets of interesting topics) by $M$. The largest system of incomparable sets on $n$ elements is called a Sperner system and it is a well known fact that its size is at most $\binom{n}{\lfloor n/2 \rfloor}$. Since every user in $M$ must have different set of interesting topics and these sets are all incomparable, we have

$$m = |M| \leq \left( \frac{t}{\lfloor t/2 \rfloor} \right) \leq \frac{2^t}{\sqrt{t}}.$$

(To verify the bound, consider $t$ to be odd or even and use $\binom{2n}{n} \leq \frac{4^n}{\sqrt{n+1}}, n \geq 1$.)

Our simple algorithm exhaustively searches over all the possible solutions on instance $(M, T, \text{INT})$ and then reconnects each of the removed users $U \setminus M$ by a single edge. The transformation to set $M$ and the connection of the removed users is clearly polynomial. Thus, we only need to show that our exhaustive search is polynomial.

Observe that the size of the optimal solution is at most $t(m - 1)$, as merged spanning trees, for all the topics, form a feasible solution. Our algorithm exhaustively searches over all possible solutions, i. e., it tries every possible set of $i$ edges for $1 \leq i \leq t(m - 1)$ and verifies the topic-connectivity requirements for such sets of edges. The verification of each set can be done in polynomial time.

The number of sets it checks can be bounded as follows:

$$\sum_{i=1}^{t(m-1)} \binom{\binom{m}{i}}{i} \leq \sum_{i=1}^{tm} \binom{m^2}{i} \leq tm \cdot \binom{m^2}{tm} \leq tm \cdot m^{tm} \leq m^{tm} \cdot O(\log^2 n)$$

(Note that $tm \leq m^2/2$ and thus the binomial coefficient is maximal in $tm$. Otherwise the number of all possible choices of edges into a solution is polynomial in $n$.)

To check a polynomial number of sets, it is sufficient to bound the factor $m^{tm}$ by a polynomial, i. e., by at most $n^c$ for some $c > 0$. (In all our calculations, log stands for the binary logarithm, however any other logarithm can be used as the change will effect the exponent by a constant.) We consider two cases:

A: First assume that $t \leq \frac{\log \log n}{1+2\varepsilon(n)},$ then $m \leq 2^t \leq (\log n)^{(1+2\varepsilon(n))^{-1}}.$

We use the upper bounds on $t$ and $m$ to estimate the number of sets our exhaustive search has to check:

$$m^{tm} \leq (\log n)^{(1+2\varepsilon(n))^{-1} \log \log n - (\log n)^{(1+2\varepsilon(n))^{-1}}} \leq n^c.$$
Then we take the logarithm of the inequality, leading to

\[(1 + 2 \varepsilon(n))^{-2} \cdot \log \log^2 n \leq c \cdot (\log n)^{\frac{2\varepsilon(n)}{1+2\varepsilon(n)}}.\]

After another logarithm operation, we obtain the following inequality:

\[-2 \log(1 + 2 \varepsilon(n)) + 2 \log \log \log n \leq \frac{2\varepsilon(n)}{1+2\varepsilon(n)} \cdot \log \log n + \log c.\]

We prove inequality (1) instead. In the end, we will see that the function \(\varepsilon(n)\) is positive, except for the first few values. Thus, for large inputs, \(2 \log(1 + 2 \varepsilon(n))\) is positive and thus the above inequalities will hold, too.

\[2 \log \log \log n \leq \frac{2\varepsilon(n)}{1+2\varepsilon(n)} \cdot \log \log n\]  \hspace{1cm} (1)

We are now able to estimate the function \(\varepsilon(n)\):

\[\varepsilon(n) \geq \frac{\log \log n}{\log \log n - 2 \log \log \log n}.\]  \hspace{1cm} (2)

Due to the following case, we use \(\varepsilon(n) \geq \frac{3/2 \log \log \log n}{\log \log n - 3/2 \log \log \log n}\) that also satisfies (2) and is positive for \(n \geq 16\).

**B:** To conclude the proof, assume that \(\log \log n \leq t \leq \frac{\log \log n}{1+\varepsilon(n)}\). Since we have both an upper and a lower bound on \(t\), we can refine the estimation of \(m\):

\[m \leq \frac{2^t}{\sqrt{t}} \leq (\log n)^{(1+\varepsilon(n))^{-1}} \cdot (1 + 2\varepsilon(n))^{1/2} \cdot (\log n)^{-1/2}.\]

We show that \(m^{tm}\) is polynomial in \(n\) similarly as in the previous case:

\[(\log n)^{(1+\varepsilon(n))^{-2}} \cdot (\log \log n)^{1/2} \cdot (\log n)^{(1+\varepsilon(n))^{-1}} \cdot (1 + 2\varepsilon(n))^{1/2} \leq m^{tm} \leq n^c.\]

Then we take the logarithm of the inequality, leading to

\[(1 + \varepsilon(n))^{-2} \cdot (\log \log n)^{3/2} \leq (1 + 2\varepsilon(n))^{1/2} \leq c \cdot (\log n)^{\frac{\varepsilon(n)}{1+\varepsilon(n)}}.\]

Assume that \((1 + 2\varepsilon(n))^{1/2} \leq 1 + \varepsilon(n)\), except for the first few values, then it is sufficient to prove a simpler inequality:

\[(1 + \varepsilon(n))^{-1} \cdot (\log \log n)^{3/2} \leq c \cdot (\log n)^{\frac{\varepsilon(n)}{1+\varepsilon(n)}}.\]

After another logarithm operation, we obtain the following inequality:

\[- \log(1 + \varepsilon(n)) + 3/2 \cdot \log \log \log n \leq \frac{\varepsilon(n)}{1+\varepsilon(n)} \cdot \log \log n + \log c.\]
Again, assuming that \( \log(1 + \varepsilon(n)) > 0 \) if \( n \) tends to infinity, to prove the above inequality, it is sufficient to show that

\[
\frac{3}{2} \log \log n \leq \frac{\varepsilon(n)}{1 + \varepsilon(n)} \cdot \log \log n.
\]

Thus we are able to bound the function \( \varepsilon(n) \) as

\[
\varepsilon(n) \geq \frac{3/2 \log \log n}{\log \log n - 3/2 \log \log \log n}.
\]

Observe that \( \varepsilon(n) > 0 \) for \( n \geq 16 \), thus both assumptions that we made hold for \( |U| \geq 16 \) which concludes the proof.

\[\square\]

6. Conclusion

In this paper, we have closed the gap in the approximation hardness of Min-TCO by showing its \( \text{LOGAPX} \)-completeness. We studied a subproblem of Min-TCO where the number of users interested in a common topic is bounded by a constant \( d \). We showed that, if \( d \leq 2 \), the restricted Min-TCO is in \( \mathcal{P} \) and, if \( d \geq 3 \), it is \( \mathcal{APX} \)-complete. The latter result, together with the constant approximation algorithm we presented, allows us to prove lower bounds on approximability of these special instances that match any lower bound known for any problem from the class \( \mathcal{APX} \). Furthermore, we studied instances of Min-TCO where the number of topics in which a single user is interested in is bounded by a constant \( d \). We presented a reduction that shows that such instances are \( \mathcal{APX} \)-hard for \( d = 6 \). In this reduction, any two users have at most three common topics, thus the reduction shows also that Min-TCO restricted in this way is \( \mathcal{APX} \)-hard. We also investigated Min-TCO with a bounded number of topics. Here we presented a polynomial-time algorithm for \( |T| \leq (1 + \varepsilon(|U|))^{-1} \cdot \log \log |U| \) and a function \( \varepsilon(n) \geq \frac{3/2 \log \log n}{\log \log n - 3/2 \log \log \log n} \). The case where \( t = \omega(\log \log n) \) and \( t = o(n) \) remains to be a challenging open problem.

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