Orthogonal and Symplectic Quantum Matrix Algebras and Cayley-Hamilton Theorem for them

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Abstract

For families of orthogonal and symplectic types quantum matrix (QM-) algebras, we derive corresponding versions of the Cayley-Hamilton theorem. For a wider family of Birman-Murakami-Wenzl type QM-algebras, we investigate a structure of its characteristic subalgebra (the subalgebra in which the coefficients of characteristic polynomials take values). We define 3 sets of generating elements of the characteristic subalgebra and derive recursive Newton and Wronski relations between them. For the family of the orthogonal type QM-algebras, additional reciprocal relations for the generators of the characteristic subalgebra are obtained.

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1 Introduction

A notion of a quantum matrix group, also called the RTT-algebra, is implicit in structures of the quantum inverse scattering method. It has been given a formal definition in the works of V. Drinfel'd, L. Faddeev, N. Reshetikhin and L. Takhtajan [D1, RTF]. Since then, various aspects of the quantum matrix group theory have been elaborated, especially in attempts to define differential geometric structures on non-commutative spaces (see, e.g. [Man, SchWZ]). In particular, a different family of algebras generated by matrix components – so-called reflection equation (RE-) algebras [C, KS],

1Our bibliography on the subject is not exhaustive here and below. We give only those references, which are close in ideas and technique to our present work and may be considered as our sources of motivation.
has been brought into consideration. Soon it was realized that, for both the RTT- and the RE-algebras, some of the basic concepts of the classical matrix algebra, like the notion of the spectral invariants and the characteristic identity (the Cayley-Hamilton theorem) can be properly generalized (see [EOW, NT, PS, Zh]). So, it comes out that the matrix notation used for the definition of the RTT- and the RE-algebras is not only technically convenient, but it dictates certain structure properties for the algebras themselves. It is then natural to search for a possibly most general algebraic setting for the matrix-type objects. Such family of algebras was introduced in refs.[III] and [IOP1], and in the latter case the definition was dictated by a condition that the standard matrix theory statements should have their appropriate generalizations. These algebras were called quantum matrix (QM-) algebras although one should have in mind that the QM-algebras are generated by the matrix components rather than by the matrix itself.

The RTT- and the RE-algebras are probably the most important subfamilies from a variety of QM-algebras. They are distinguished both from the algebraic point of view (the presence of additional bi-algebra and bi-comodule structures) and from the geometric point of view (their interpretation as, respectively, the algebras of quantized functions and of quantized invariant differential operators on a group). However, for the generalization of the basic matrix algebra statements, it is not only possible but often more clarifying to use a weaker structure settings of the QM-algebras.

So far, the program of generalizing the Cayley-Hamilton theorem was fully accomplished for the linear type QM-algebras. For the $GL(m)$-type algebras, the results were described in [GPS1, IOPS, IOP1] and for the $GL(m|n)$-type algebras in [GPS2, GPS3]. These works generalize earlier results on characteristic identities by A.J. Bracken, M.D. Gould, H.S. Green, P.D. Jarvis and R.B. Zhang in the Lie (super)algebra case [BGr, Gr, JGr] and in the quantized universal enveloping algebra case [GZB], and by I. Kantor and I. Trishin in the matrix superalgebra case [KT1, KT2].

In the present work we are investigating the QM-algebras of the orthogonal and symplectic types. Our main goal is to derive, for the quantum matrices of these types, the characteristic identities, to use them for a description of the spectra of the quantum matrices and to establish analogs of the Newton and Wronski relations. To be able to do that, we have to carry out in the sections 2 and 3 some preparatory work.

In the section 2 we collect few basically known results about Birman-Murakami-Wenzl (BMW) algebras. The role that the BMW algebras play in the orthogonal/symplectic cases is similar to that of the Hecke algebras in the general linear case. Namely, given an R-matrix representation of the BMW-algebra, one can define the corresponding QM-algebra and then specific properties of the R-matrix representation define the type of the QM-algebra and hence control the form of the corresponding characteristic identity. In the subsection 2.2 we introduce three sets of the idempotents in the BMW algebra — called antisymmetrizers, symmetrizers and contractors — which are used later for an identification of a specific type of the R-matrix representation.

In the section 3 we consider the R-matrix representations of the BMW algebras. We define standard notions of an R-trace \(^2\), of a skew-invertibility, of a compatible pair of R-matrices (the subsection 3.1) and of a twisted R-matrix (the subsection 3.2). To investigate the skew-invertibility of the R-matrix after a twist, we derive an expression for the twisted R-matrix, which is different from the standard one.

\(^2\)This operation is also called a quantum trace or, shortly, a $q$-trace in the literature.
Next we describe the BMW type R-matrices (the subsection 3.3) and then the R-matrices of the orthogonal and symplectic subtypes (the subsection 3.4). Most part of a technical preparative work is done in the subsections 3.2, 3.3 and 3.5. Here we develop the R-matrix technique, which is later used in the main sections 4–6.

A very common (although not the only) source of the skew-invertible R-matrices and of their compatible pairs is provided by the theory of the quasitriangular Hopf algebras. In the appendix, we comment on the universal (i.e., quasitriangular Hopf algebraic) counterparts of the matrix relations derived in section 3.

In the beginning of the section 4 we introduce the QM-algebras of different (generic, BMW, orthogonal, symplectic) types. We then define the characteristic subalgebra of the QM-algebra. It is the subalgebra to which the coefficients of the Cayley-Hamilton identity belong. As it was shown in [IOP1], the characteristic subalgebra is abelian. In the subsection 4.2 we describe three generating sets for the characteristic subalgebra of the BMW-type QM-algebra. In the subsection 4.3 we derive reciprocal relations, which are specific to generators of the characteristic subalgebra in the orthogonal case. Particular examples (and for particular, so-called, ”standard” R-matrices) of the reciprocal equalities relating the quantum determinants and the 2-contractions were obtained for the RTT-algebras by T. Hayashi [Hay].

Next, in the subsection 4.4, we construct another important requisite of the Cayley-Hamilton theorem — the quantum matrix product ”⋆”. The definition is given for the generic QM-algebra. In general, the ⋆-product is different from the usual matrix product (however, for the subfamily of RE-algebras, the ⋆-product coincides with the matrix product) but it obeys the same algebraic properties. The ⋆-product is proven to be associative and hence the ⋆-powers of the same quantum matrix $M$ commute. We determine then the set of all different descendants of the quantum matrix $M$ in the BMW case and prove that this set is ⋆-commutative. It turns out that, unlike the general linear (Hecke) case, it is not possible to express all these descendants in terms of the ⋆-powers of $M$ only. The expressions include also a new operation ”⊺”, which can be treated as a ”matrix multiplication with a transposition”. This fact causes some technical complications in the proof of the Cayley-Hamilton theorem, but on the other hand, it gives rise to a diversity of the characteristic identities in the orthogonal and symplectic cases.

A construction of the inverse matrix of generators and a definition of two components of the orthogonal QM-algebra close the section 4.

Given all the definitions of the section 4, the derivation of the main theorems in the sections 5 and 6 becomes a rather technical task, with the tools developed in the sections 2 and 3. We prove the Cayley-Hamilton theorems separately for the symplectic case and for three different orthogonal cases in theorems 5.5, 5.7 and 5.9. We also define in each case a homomorphism from the characteristic subalgebra to the algebra of symmetric polynomials in some set of commuting variables (see the corollaries 5.6, 5.8 and 5.10). The Cayley-Hamilton identities under the action of these homomorphisms are completely factorized and hence the variables of the symmetric polynomials can be treated as quantum matrix eigenvalues.

The Newton and Wronski recursions relating three different generating sets of the characteristic subalgebra of the BMW-type QM-algebra are proven in the theorem 6.1. For the orthogonal and symplectic cases considered in the section 5, we use the homomorphic maps defined in the corollaries 5.6, 5.8 and 5.10 to calculate expressions for all three generating sets of the characteristic subalgebra.
in terms of quantum matrix eigenvalues (see the corollary 6.4). The latter calculation was initially aimed at comparing our results with expressions given for the power sums for the RE-algebras in a recent paper by A. Mudrov [Mudr] (see the subsection 8.3 there). Although the derivation methods are very different the results agree up to some obvious changes in a notation. Notice that compared to [Mudr] we are working in a more general setting. The generalization goes in several directions. First, we do not assume a “standard” Drinfel’d-Jimbo’s form for the R-matrices defining the algebra and, moreover, we do not use any deformation assumptions in our constructions. Next, we are working with a wider family of QM-algebras. And, finally, we are working directly in the algebra without passing to representations\(^3\).

Concluding the introduction let us comment on yet another generalization of the Cayley-Hamilton theorem, which was suggested by I.M. Gelfand, D. Krob, A. Lascoux, B. Leclerc, V.S. Retakh and J. Thibon in [G–T]. In the latter approach the authors used a notion of quasideterminants, which allowed them to write the Cayley-Hamilton identity in a very general setting of a free associative algebra generated by indeterminates. The matrix powers are usual (there is no R-matrix, which affects the definition of the matrix powers in our approach). The coefficients of the characteristic identity however become diagonal matrices rather than scalars and, moreover, the components of these diagonal matrices are rational functions rather than polynomials in generators. This is the price to be paid for the generality. The first examples [EOW, Zh] of the characteristic identities for the RTT-algebras constructed for the standard Drinfeld-Jimbo R-matrix were obtained namely in the form of [G–T]: the matrix powers were usual, the coefficients of the characteristic identity were diagonal matrices (however, the entries of these matrices are polynomials in the algebra generators, which shows a specific character of the RTT-algebras). In [OV] it was shown that the characteristic identities of [EOW, Zh] contain the same information as the characteristic identities obtained in our approach [IOPS]. Notice, that even for the subfamily of the RTT-algebras constructed for a generic Hecke-type R-matrix (not by the standard one), there is no hope to get the characteristic identity with the polynomial coefficients in the approach of [G–T].

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2 Some facts about Birman-Murakami-Wenzl algebras

In this preparatory section we collect definitions and derive few results on the Birman-Murakami-Wenzl algebras. We give a minimal information, which is required for the main part of the paper. The reader will find a more detailed presentation of the Birman-Murakami-Wenzl algebras in, e.g., papers [W] and [LR].

\(^3\)Passing to the representations level is hardly possible except in the RE-algebra case. The reason is that the characteristic subalgebra belongs to the center of the RE-algebra, which is not true for the general QM-algebra.
2.1 Definition

The braid group $B_n$, in Artin presentation, is defined by generators $\{\sigma_i\}_{i=1}^{n-1}$ and relations

$$\sigma_i \sigma_{i+1} \sigma_i = \sigma_{i+1} \sigma_i \sigma_{i+1} \quad \forall \ i = 1, 2, \ldots, n - 1$$

and

$$\sigma_i \sigma_j = \sigma_j \sigma_i \quad \forall \ i, j : |i-j| > 1.$$  (2.1.2)

The Birman-Murakami-Wenzl (BMW) algebra $W_n(q, \mu)$ [BW, Mur] is a finite dimensional quotient algebra of the group algebra $C[SB_n]$. It depends on two complex parameters $q$ and $\mu$. Let

$$\kappa_i := \frac{(q - 1 - \sigma_i)(q^{-1} - \sigma_i)}{\mu(q - q^{-1})}, \quad i = 1, 2, \ldots, n - 1.$$  (2.1.3)

The quotient algebra $W_n(q, \mu)$ is specified by conditions

$$\sigma_i \kappa_i = \kappa_i \sigma_i = \mu \kappa_i, \quad \kappa_i \sigma_{i+1} \kappa_i = \mu \sigma_{i+1} \kappa_i.$$  (2.1.4)

The relations (2.1.4) also imply

$$\kappa_i, \sigma_{i+1} = \kappa_i, \sigma_{i+1}, \kappa_i, \sigma_{i+1} = \kappa_i, \sigma_{i+1}.$$  (2.1.5)

The parameters $q$ and $\mu$ of the BMW algebra are taken in domains $q \in \mathbb{C}\setminus\{0, \pm 1\}$ and $\mu \in \mathbb{C}\setminus\{0, q, -q^{-1}\}$, so that the elements $\kappa_i$ are well defined and non-nilpotent. Further restrictions on $q$ and $\mu$ will be imposed in the subsections 2.2 and 3.4.

The braid groups and their quotient BMW algebras admit a chain of monomorphisms

$$B_2 \hookrightarrow \ldots \hookrightarrow B_n \hookrightarrow B_{n+1} \hookrightarrow \ldots,$$

$$W_2 \hookrightarrow \ldots \hookrightarrow W_n \hookrightarrow W_{n+1} \hookrightarrow \ldots.$$  (2.1.9)

defined on the generators as

$$B_n \ (\text{or } W_n) \ni \sigma_i \mapsto \sigma_{i+1} \in B_{n+1} \ (\text{or } W_{n+1}) \quad \forall \ i = 1, \ldots, n - 1.$$  (2.1.10)

We denote by $\alpha^{(n)}_i \in B_{n+i} \ (\text{or } W_{n+i})$ an image of an element $\alpha^{(n)} \in B_n \ (\text{or } W_n)$ under a composition of the mappings (2.1.9)-(2.1.10). Conversely, if for some $j < (n - 1)$, an element $\alpha^{(n)}$ belongs to the image of $B_{n-j} \ (\text{or } W_{n-j})$ in $B_n \ (\text{or } W_n)$ then by $\alpha^{(n)}_j$ we denote the preimage of $\alpha^{(n)}$ in $B_{n-j} \ (\text{or } W_{n-j})$.

This notation will be helpful in the next subsection where we discuss three distinguished sequences of idempotents in the BMW algebras.

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4For particular values $\mu = \pm q^i$, $i \in \mathbb{Z}$, the limiting cases $q \to \pm 1$ to the Brauer algebra [Br] can be consistently defined.
2.2 Baxterized elements, (anti)symmetrizers and contractors

A set of elements $\sigma_i(x)$, $i = 1, 2, \ldots, n-1$, depending on a complex parameter $x$, in a quotient of the group algebra $\mathbb{C}B_n$ is called a set of baxterized elements if

$$\sigma_i(x) \sigma_{i+1}(xy) \sigma_i(y) = \sigma_{i+1}(y) \sigma_i(xy) \sigma_{i+1}(x)$$

(2.2.1)

for $i = 1, 2, \ldots, n-1$ and

$$\sigma_i(x) \sigma_j(y) = \sigma_j(y) \sigma_i(x)$$

(2.2.2)

if $|i - j| > 1$.

**Lemma 2.1 [J, I]** For the algebra $\mathcal{W}_n(q, \mu)$, the baxterized elements exist. There are two sets of the baxterized elements $\{\sigma^\varepsilon_i\}$, $\varepsilon = \pm 1$, given by

$$\sigma^\varepsilon_i(x) := 1 + \frac{x - 1}{q - q^{-1}} \sigma_i + \frac{x - 1}{\alpha \varepsilon x + 1} \kappa_i,$$

(2.2.3)

where $\alpha_\varepsilon := -\varepsilon q^{-\varepsilon} \mu^{-1}$.

The complex argument $x$, traditionally called the spectral parameter, is chosen in a domain $\mathbb{C} \setminus \{-\alpha^{-1}\}$.

There exists an algebra isomorphism

$$\iota : \mathcal{W}_n(q, \mu) \rightarrow \mathcal{W}_n(-q^{-1}, \mu), \quad \sigma_i \mapsto \sigma_i.$$

(2.2.4)

The map $\iota$ interchanges the two sets in (2.2.3), $\iota(\sigma^\varepsilon_i(x)) = \sigma^{-\varepsilon}_i(x)$.

In terms of the baxterized generators we construct two series of elements $a^{(i)}$ and $s^{(i)}$, $i = 1, 2, \ldots, n$, in the algebra $\mathcal{W}_n(q, \mu)$. They are defined iteratively in two ways:

$$a^{(1)} := 1 \quad \text{and} \quad s^{(1)} := 1,$$

(2.2.5)

$$a^{(i+1)} := \frac{q^i}{(i+1)_q} a^{(i)} \sigma_i^- (q^{-2i}) a^{(i)} \quad \text{or} \quad a^{(i+1)} := \frac{q^i}{(i+1)_q} a^{(i)\uparrow} \sigma_i^+ (q^{-2i}) a^{(i)\uparrow},$$

(2.2.6)

$$s^{(i+1)} := \frac{q^{-i}}{(i+1)_q} s^{(i)} \sigma_i^+ (q^{2i}) s^{(i)} \quad \text{or} \quad s^{(i+1)} := \frac{q^{-i}}{(i+1)_q} s^{(i)\uparrow} \sigma_i^+ (q^{2i}) s^{(i)\uparrow},$$

(2.2.7)

where $i_q$ are usual $q$-numbers, $i_q := (q^i - q^{-i})/(q - q^{-1})$. Below we show that these two definitions coincide.

To avoid singularities in the definition of $a^{(i)}$ (respectively, $s^{(i)}$), $i = 1, 2, \ldots, n$, we impose further restrictions on the parameters of $\mathcal{W}_n(q, \mu)$:

$$j_q \neq 0, \quad \mu \neq -q^{-2j+3} \quad \text{(respectively,} \quad \mu \neq q^{2j-3} \quad \forall j = 2, 3, \ldots, n \quad \text{).}$$

(2.2.8)
The elements \( a^{(i)} \) and \( s^{(i)} \) are called an \( i \)-th order antisymmetrizer and an \( i \)-th order symmetrizer, respectively.

The second order antisymmetrizer and symmetrizer

\[
a^{(2)} = \frac{q}{2q} \sigma_1 (q^{-2}) = \frac{(q^2 - 1)(\mu + q)}{2q(\mu + 1)}, \quad s^{(2)} = \frac{q^{-1}}{2q} \sigma_1^+(q^2) = \frac{(q^{-2} + \sigma_1)(\mu - 1)}{2q(\mu - q)} \tag{2.2.9}
\]

are the idempotents participating in a resolution of unity in \( W_2(q, \mu) \) (c.f. with eq.(2.1.5)),

\[
1 = a^{(2)} + s^{(2)} + \eta^{-1}\kappa_1; \tag{2.2.10}
\]

the spectral decomposition of the generator \( \sigma_1 \) of \( W_2(q, \mu) \) is

\[
\sigma_1 = -q^{-1}a^{(2)} + qs^{(2)} + \mu\eta^{-1}\kappa_1; \tag{2.2.11}
\]

Under the map (2.2.4) one has \( \iota(a^{(2)}) = s^{(2)} \), \( \iota(s^{(2)}) = a^{(2)} \) and \( \iota(\kappa_1) = \kappa_1 \).

Likewise for \( a^{(2)} \) and \( s^{(2)} \), one can introduce higher order analogues for the third idempotent entering the resolution. Namely, define iteratively

\[
c^{(2)} := \eta^{-1}\kappa_1, \quad c^{(2i+2)} := c^{(2i)}\kappa_1\kappa_{2i+1}c^{(2i)}\kappa_1. \tag{2.2.12}
\]

The element \( c^{(2i)} \) is called an \((2i)\)-th order contractor. Main properties of the (anti)symmetrizers and contractors are summarized below.

**Proposition 2.2** Two expressions given for the antisymmetrizers and symmetrizers in eqs.(2.2.6) and (2.2.7) are identical. The elements \( a^{(n)} \) and \( s^{(n)} \) are central primitive idempotents in the algebra \( W_n(q, \mu) \). One has

\[
a^{(n)}\sigma_i = \sigma_i a^{(n)} = -q^{-1}a^{(n)}, \quad s^{(n)}\sigma_i = \sigma_i s^{(n)} = qs^{(n)} \quad \forall \ i = 1, 2, \ldots, n - 1 \tag{2.2.13}
\]

and

\[
a^{(n)}a^{(m)\kappa_i} = a^{(m)\kappa_i}a^{(n)} = a^{(n)}, \quad s^{(n)}s^{(m)\kappa_i} = s^{(m)\kappa_i}s^{(n)} = s^{(n)} \quad \text{if} \ m + i \leq n. \tag{2.2.14}
\]

The antisymmetrizers \( a^{(n)} \), for all \( n = 2, 3, \ldots \), are orthogonal to the symmetrizers \( s^{(m)} \), for all \( m = 2, 3, \ldots \).

The element \( c^{(2n)} \) is a primitive idempotent in the algebra \( W_{2n}(q, \mu) \) and in the algebra \( W_{2n+1}(q, \mu) \). One has

\[
c^{(2n)}c^{(2i)\kappa_n-i}c^{(2n)} = c^{(2n)} \quad \forall \ i = 1, 2, \ldots, n; \tag{2.2.15}
\]

\[
c^{(2n)}\kappa_i = c^{(2n)}\kappa_{2n-i}, \quad \kappa_i c^{(2n)} = c^{(2n)} \quad \forall \ i = 1, 2, \ldots, n - 1 \tag{2.2.16}
\]

and

\[
c^{(2n)}\kappa_n = \kappa_n c^{(2n)} = \mu c^{(2n)}. \tag{2.2.17}
\]

The contractors \( c^{(2n)} \) are orthogonal to the antisymmetrizers \( a^{(m)} \) and to the symmetrizers \( s^{(m)} \) for all \( m > n \).
Proof. The explicit formula (2.2.6) for idempotents, which we call antisymmetrizers here, appears in [TW], although without referring to the baxterized elements (see the proof of the lemma 7.6 in [TW]). Our proof of the formulas (2.2.13) and (2.2.14) relies on the relations (2.2.1) for the baxterized generators.

We first check that the elements \( a^{(i)} \) defined iteratively by the first formula in (2.2.6) satisfy eqs.(2.2.13) and (2.2.14). The equalities (2.2.13) for the antisymmetrizers are equivalent to

\[
a^{(n)} s^{(2)} \tau_i - 1 = s^{(2)} \tau_i - 1 a^{(n)} = a^{(n)} c^{(2)} \tau_i - 1 = c^{(2)} \tau_i - 1 a^{(n)} = 0 ,
\]

which, in turn, are equivalent to

\[
a^{(n)} \sigma_i^{-} (q^2) = \sigma_i^{-} (q^2) a^{(n)} = 0 \quad \forall \ i = 1, 2, \ldots n - 1 .
\]

(2.2.18)

Indeed, the spectral decomposition of \( \sigma_i^{-} (q^2) \) contains (with nonzero coefficients) only two idempotents, \( s^{(2)} \tau_i - 1 \) and \( c^{(2)} \tau_i - 1 \):

\[
\sigma_i^{-} (q^2) = q 2q \left( s^{(2)} \tau_i - 1 + \frac{1 + q \mu}{q^2 + \mu} c^{(2)} \tau_i - 1 \right) .
\]

To avoid a singularity in the expression for \( \sigma_i^{-} (q^2) \), we have to assume additionally \( \mu \neq -q^3 \) for the rest of the proof. However, the expressions entering the relations (2.2.13) and (2.2.14) are well defined and continuous at the point \( \mu = -q^3 \) (unless \( -q^3 \) coincides with one of the forbidden by eq.(2.2.8) values of \( \mu \)), so the validity of the relations (2.2.13) and (2.2.14) at the point \( \mu = -q^3 \) follows by the continuity.

Notice that the equalities \( a^{(n)} \sigma_i = -q^{-1} a^{(n)} \) are equivalent to the equalities \( \sigma_i a^{(n)} = -q^{-1} a^{(n)} \) due to an antiautomorphism

\[
\varsigma : \mathcal{W}_n (q, \mu) \rightarrow \mathcal{W}_n (q, \mu) , \quad \sigma_i \mapsto \sigma_i , \quad \varsigma (xy) = \varsigma (y) \varsigma (x) ,
\]

since \( \varsigma (a^{(n)}) = a^{(n)} \) by construction.

We now prove the equalities (2.2.13) and (2.2.14) by induction on \( n \).

For \( n = 2 \), \( a^{(2)} \sigma_1 = -q^{-1} a^{(2)} \), by (2.2.9) and (2.1.5).

Let us check the equalities for some fixed \( n > 2 \) assuming that they are valid for all smaller values of \( n \). Notice that as a byproduct of the definition (2.2.6) (the first equality) and the induction assumption, eqs.(2.2.18) and (2.2.14) are satisfied, respectively, for all \( i = 1, 2, \ldots, n - 2 \) and for all \( m, i : m + i \leq n - 1 \). It remains to check eq.(2.2.18) for \( i = n - 1 \) and eq.(2.2.14) for \( m = n - i \). Respectively, we calculate

\[
a^{(n)} \sigma_{n-1}^{-} (q^2) \sim a^{(n-1)} \sigma_{n-1}^{-} (q^{-2n+2}) a^{(n-1)} \sigma_{n-1}^{-} (q^2) \sim (a^{(n-1)} a^{(n-2)}) \sigma_{n-1}^{-} (q^{-2n+2}) \sigma_{n-2}^{-} (q^{-2n+4}) \sigma_{n-1}^{-} (q^2) a^{(n-2)} = (a^{(n-1)} \sigma_{n-2}^{-} (q^2)) \sigma_{n-1}^{-} (q^{-2n+4}) \sigma_{n-2}^{-} (q^{-2n+2}) a^{(n-2)} = 0 ,
\]

5Different expressions for the antisymmetrizers and symmetrizers, which are less suitable for our applications, were derived in [HSc].
"\sim \) means "proportional" and
\[
a^{(n)} a^{(n-i)\tau_i} = \frac{q^{n-i-1}}{(n-i)q} (a^{(n)} a^{(n-i-1)\tau_i}) \sigma_{n-1}^{-1} (q^{-2(n-i-1)}) a^{(n-i-1)\tau_i} = \frac{q^{n-i-1}}{(n-i)q} a^{(n)} (1 + q^i(n - i - 1)q^{-1}) a^{(n-i-1)\tau_i} = a^{(n)}.
\]

Here in both cases, the definition of antisymmetrizers (2.2.6) (the first equality), the induction assumption and eq.(2.2.1) were used. The centrality and primitivity of the idempotents \( a^{(n)} \in \mathcal{W}_n(q, \mu) \) follow then from eqs.(2.2.13).

To prove equivalence of the two expressions for antisymmetrizers given in eq.(2.2.6), consider an inner algebra automorphism
\[
\mathcal{W}_n(q, \mu) \to \mathcal{W}_n(q, \mu) : \sigma_i \mapsto \tau^{(n)} \sigma_i (\tau^{(n)})^{-1} = \sigma_{n-i}, \tag{2.2.19}
\]
where \( \tau^{(1)} = 1, \quad \tau^{(j+1)} = \tau^{(j)} \sigma_j \sigma_{j-1} \ldots \sigma_1. \)

Under this automorphism the first expression in eq.(2.2.6) transforms into the second one. However, the elements \( a^{(n)} \) are central, so they do not change under conjugation with \( \tau^{(n)} \), which proves consistency of the equalities (2.2.6).

All the assertions concerning the symmetrizers follow from the relations for the antisymmetrizers by an application of the map (2.2.4) because \( \iota(a^{(n)}) = s^{(n)} \) and \( \iota(s^{(n)}) = a^{(n)}. \)

The orthogonality of the antisymmetrizers and the symmetrizers is a byproduct of the relations (2.2.13):
\[
-q^{-1} a^{(n)} s^{(m)} = (a^{(n)} \sigma_1) s^{(m)} = a^{(n)} (\sigma_1 s^{(m)}) = qa^{(n)} s^{(m)}.
\]

The equalities (2.2.15) can be proved by induction on \( n \). They are obvious in the case \( n = 1 \). Let us check them for some fixed \( n \geq 2 \), assuming they are valid for all smaller values of \( n \). Notice that the iterative definition (2.2.12) together with the induction assumption approve eqs.(2.2.15) for all values of index \( i \), except \( i = n \). Checking the case \( i = n \) splits in two subcases: \( n = 2 \) and \( n > 2 \). In the subcase \( i = n = 2 \), we have \( c^{(4)} = \eta^{-2}\kappa_2\kappa_3\kappa_1\kappa_2 \) and
\[
(c^{(4)})^2 = \eta^{-4}\kappa_2\kappa_3\kappa_1\kappa_2^2 = \eta^{-3}\kappa_2\kappa_3(\kappa_1\kappa_2\kappa_1)\kappa_3\kappa_2 = \eta^{-3}\kappa_2\kappa_3\kappa_1\kappa_3\kappa_2 = \eta^{-2}\kappa_2\kappa_3\kappa_1\kappa_2 = c^{(4)},
\]
while in the subcase \( i = n > 2 \), the calculation is carried out as follows
\[
(c^{(2n)})^2 = c^{(2n-2)} (c^{(2n-2)})^\dagger (c^{(2n-2)})^\dagger = c^{(2n-2)} (c^{(2n-2)})^\dagger (c^{(2n-2)})^\dagger (c^{(2n-2)})^\dagger = c^{(2n-2)} (c^{(2n-2)})^\dagger (c^{(2n-2)})^\dagger = c^{(2n)}.
\]

\( a^{(n)} \) is the lift of the longest element of the symmetric group. The equality \( \tau^{(n)} \sigma_i (\tau^{(n)})^{-1} = \sigma_{n-i} \) holds already in the group algebra \( \mathbb{C}B_n \). It follows that \( (\tau^{(n)})^2 \) is central in \( \mathbb{C}B_n \).
Here in both calculations we used the definition (2.2.12), the induction assumption and the relations (2.1.8).

Taking into account the relations (2.2.15), one can derive an alternative expression for the contractors

\[
c^{(2i)} = c^{(2i-2)} \kappa_1 \kappa_{2i-1} c^{(2i-2)} = c^{(2i-2)} \kappa_1 \kappa_{2i-1} c^{(2i-4)} \kappa_2 \kappa_{2i-2} c^{(2i-4)}
\]
\[
= (c^{(2i-2)} \kappa_1 \kappa_{2i-1} \kappa_2 \kappa_{2i-2} c^{(2i-4)} \kappa_2 \kappa_{2i-2} c^{(2i-4)}) = c^{(2i-2)} \kappa_1 \kappa_{2i-1} \kappa_2 \kappa_{2i-2} c^{(2i-4)} \kappa_2 \kappa_{2i-2} c^{(2i-4)}
\]
\[
= \ldots = c^{(2i-2)} \kappa_{2i-1} \kappa_{2i-2} \kappa_{i+1} \kappa_1 \kappa_{2i} \kappa_{i-1} c^{(2i-1)}
\]
\[
= \aleph^{-1} c^{(2i-2)} \kappa_{2i-1} \kappa_{2i-2} \kappa_{i+1} \kappa_1 \kappa_{2i} \kappa_{i-1} c^{(2i-1)}
\]

Now, using this expression and noticing that, by eqs.(2.2.7),

\[
\kappa_{i+1} \kappa_{i-1} \kappa_i \sigma_i = \kappa_{i+1} \kappa_{i-1} \sigma_i^{-1} = \kappa_{i-1} \kappa_{i+1} \sigma_i^{-1} = \kappa_{i+1} \kappa_{i-1} \kappa_i \sigma_i + 1
\]

we conclude that the equality (2.2.16) is satisfied for \( i = n - 1 \). In particular, (2.2.16) holds for \( n = 2 \) and \( i = 1 \). It is enough (by induction on \( n \)) to prove (2.2.16) for \( i = 1 \). Then observe, again by eq.(2.1.7), that

\[
\kappa_{i+1} \kappa_{i-1} \kappa_i \sigma_i = \kappa_{i+1} \kappa_{i-1} \sigma_i = \kappa_i \sigma_i^{-1} = \sigma_i = \kappa_i \kappa_{i+1} \kappa_i \sigma_i + 1
\]

Now, for \( n > 2 \),

\[
c^{(2n)} \sigma_i = \aleph^{-1} c^{(2n-2)} \sigma_i (\kappa_{2n-1} \kappa_{2n-2} \kappa_{2n-3} \kappa_{i-1} \kappa_1 \kappa_{i+1} \kappa_{2n}) \sigma_i
\]
\[
= \aleph^{-1} c^{(2n-2)} \sigma_i (\kappa_{2n-1} \kappa_{2n-2} \kappa_{2n-3} \kappa_{i-1} \kappa_1 \kappa_{i+1} \kappa_{2n}) \sigma_i
\]
\[
= \aleph^{-1} c^{(2n-2)} \sigma_i (\kappa_{2n-1} \kappa_{2n-2} \kappa_{2n-3} \kappa_{i-1} \kappa_1 \kappa_{i+1} \kappa_{2n}) \sigma_i
\]
\[
= \aleph^{-1} c^{(2n-2)} \sigma_i (\kappa_{2n-1} \kappa_{2n-2} \kappa_{2n-3} \kappa_{i-1} \kappa_1 \kappa_{i+1} \kappa_{2n}) \sigma_i
\]
\[
= \aleph^{-1} c^{(2n-2)} \sigma_i (\kappa_{2n-1} \kappa_{2n-2} \kappa_{2n-3} \kappa_{i-1} \kappa_1 \kappa_{i+1} \kappa_{2n}) \sigma_i
\]
\[
= \aleph^{-1} c^{(2n-2)} \sigma_i (\kappa_{2n-1} \kappa_{2n-2} \kappa_{2n-3} \kappa_{i-1} \kappa_1 \kappa_{i+1} \kappa_{2n}) \sigma_i
\]

The relation (2.2.17) follows from eq.(2.1.4) and eq.(2.2.20) with \( i = n \). Then, orthogonality of the contractors \( c^{(2n)} \) and the (anti)symmetrizers \( c^{(m)} \), \( s^{(m)} \), \( m > n \) is a corollary of eqs.(2.2.13) and (2.2.17).

A statement of the primitivity of the idempotent \( c^{(2n)} \in W(q, \mu) \), \( i = 2n, 2n + 1 \), goes beyond the needs of the present paper and we mention it for a sake of completeness only. To prove the primitivity, one has to check, using the equalities (2.2.15)–(2.2.17), that a relation \( c^{(2n)} \sigma^{(2n+1)} c^{(2n)} \sim c^{(2n)} \) is fulfilled for any element \( \sigma^{(2n+1)} \in W_{2n+1}(q, \mu) \).
3 R-matrices

Let $V$ denote a finite dimensional $\mathbb{C}$-linear space, $\dim V = n$. Fixing some basis $\{v_i\}_{i=1}^n$ in $V$ we identify elements $X \in \text{End}(V^\otimes n)$ with matrices $X_{i_1i_2...i_n}^{j_1j_2...j_n}$.

In this section we investigate properties of certain elements in $\text{Aut}(V^\otimes 2)$ generating representations of the braid groups $B_n$ or, more specifically, of the Birman-Murakami-Wenzl algebras $W_n(q, \mu)$ on the spaces $V^\otimes n$. Traditionally such operators are called “R-matrices”.

3.1 Definition and notation

Let $X \in \text{End}(V^\otimes 2)$. For any $n = 2, 3, \ldots$ and $1 \leq m \leq n-1$, denote by $X_m$ an operator whose action on the space $V^\otimes n$ is given by the matrix

$$(X_m)_{i_1...i_n}^{j_1...j_n} := I_{i_1...i_{m-1}}^{j_1...j_{m-1}} X_{i_{m+1}i_1...i_{m-1}}^{j_{m+1}j_1...j_{m-1}} I_{i_{m+2}...i_n}^{j_{m+2}...j_n}.$$ (3.1.1)

Here $I$ denotes the identity operator. In some cases below (see, e.g., eq.(3.1.3)) we will also use a notation $X_{mr} \in \text{End}(V^\otimes n)$, $1 \leq m < r \leq n-1$, referring to an operator given by a matrix

$$(X_{mr})_{i_1...i_n}^{j_1...j_n} := X_{i_{m+1}i_1...i_{m-1}}^{j_{m+1}j_1...j_{m-1}} I_{i_{m+2}...i_r}^{j_{m+2}...j_r} I_{i_{r+1}i_{m+1}...i_{m+1}}^{j_{r+1}...j_{r+1}} I_{i_{r+2}...i_n}^{j_{r+2}...j_n}.$$ (3.1.2)

Clearly, $X_m = X_{m,m+1}$.

We reserve the symbol $P$ for the permutation operator: $P(u \otimes v) = v \otimes u \ \forall \ u, v \in V$. Below we repeatedly make use of relations

$$P^2 = I; \quad P_{12}X_{12} = X_{21}P_{12} \ \forall \ X \in \text{End}(V \otimes V); \quad \text{Tr}_{(1)} P_{12} = \text{Tr}_{(3)} P_{23} = I_2,$$

where the symbol $\text{Tr}_{(i)}$ stands for the trace over an $i$-th component space in the tensor power of the space $V$.

An operator $X \in \text{End}(V^\otimes 2)$ is called skew invertible if there exists an operator $\Psi_X \in \text{End}(V^\otimes 2)$ such that

$$\text{Tr}_{(2)} X_{12} \Psi_{X_{23}} = \text{Tr}_{(2)} \Psi_{X_{12}} X_{23} = P_{13}.$$ (3.1.3)

Define two elements of $\text{End}(V)$

$$C_X := \text{Tr}_{(1)} \Psi_{X_{12}}, \quad D_X := \text{Tr}_{(2)} \Psi_{X_{12}}.$$ (3.1.4)

By (3.1.3),

$$\text{Tr}_{(1)} C_X X_{12} = I_2, \quad \text{Tr}_{(2)} D_X X_{12} = I_1.$$ (3.1.5)

A skew invertible operator $X$ is called strict skew invertible if one of the matrices, $C_X$ or $D_X$, is invertible (by the lemma 3.5, if $C_X$ or $D_X$ is invertible then they are both invertible).

An element $R \in \text{Aut}(V^\otimes 2)$ that fulfills condition

$$R_1 R_2 R_1 = R_2 R_1 R_2.$$ (3.1.6)
is called an $R$-matrix. Eq.(3.1.6) is called the Yang-Baxter equation. Clearly, $P$ is the $R$-matrix; $R^{-1}$ is the $R$-matrix iff $R$ is. Any $R$-matrix $R$ generates representations $\rho_R$ of the series of braid groups $B_n$, $n = 2, 3, \ldots$

$$\rho_R : B_n \to \text{Aut}(V^\otimes n), \quad \sigma_i \mapsto \rho_R(\sigma_i) = R_i, \quad 1 \leq i \leq n - 1. \tag{3.1.7}$$

If additionally the $R$-matrix $R$ satisfies a third order minimal characteristic polynomial (c.f. with eq.(2.1.5))

$$(qI - R)(q^{-1}I + R)(\mu I - R) = 0 , \tag{3.1.8}$$

and an element

$$K := \mu^{-1}(q - q^{-1})^{-1}(qI - R)(q^{-1}I + R) \tag{3.1.9}$$

fulfills conditions

$$K_2 K_1 = R_1^{\pm 1} R_2^{\pm 1} K_1, \quad K_1 K_2 K_1 = K_1 , \tag{3.1.10}$$

then we call $R$ an $R$-matrix of a BMW-type (c.f. with eqs.(2.1.3)–(2.1.8); we make a different but equivalent choice of defining relations).

For an $R$-matrix of the BMW-type, the formulas (3.1.7) define representations of the algebras $W_n(q, \mu) \to \text{End}(V^\otimes n)$, $n = 2, 3, \ldots$. In particular, $\rho_R(\kappa_i) = K_i$.

An ordered pair $\{R, F\}$ of two operators $R$ and $F$ from $\text{End}(V^\otimes 2)$ is called a compatible pair if conditions

$$R_1 F_2 F_1 = F_2 F_1 R_2 , \quad R_2 F_1 F_2 = F_1 F_2 R_1 , \tag{3.1.11}$$

are satisfied. If, in addition, $R$ and $F$ are $R$-matrices, the pair $\{R, F\}$ is called a compatible pair of $R$-matrices. The equalities (3.1.11) are called twist relations (on the notion of the twist see [D2, Resh2, IOP2]). Clearly, $\{R, P\}$ and $\{R, R\}$ are compatible pairs of $R$-matrices; pairs $\{R^{-1}, F\}$ and $\{R, F^{-1}\}$ are compatible iff the pair $\{R, F\}$ is.

**Definition 3.1** Consider a space of $n \times n$ matrices $\text{Mat}_n(W)$, whose entries belong to some $\mathbb{C}$-linear space $W$. Let $R$ be a skew invertible $R$-matrix. A linear map

$$\text{Tr}_R : \text{Mat}_n(W) \to W, \quad \text{Tr}_R(M) = \sum_{i,j=1}^{n} (D_R)^j_i M^i_j, \quad M \in \text{Mat}_n(W), \tag{3.1.12}$$

is called an $R$-trace.

The relation (3.1.5) in this notation reads

$$\text{Tr}_{R^{(2)}} R_{12} = I_1 , \tag{3.1.13}$$

which determines $D_R$ in (3.1.12) uniquely provided $R$ is skew invertible.
3.2 R-technique

In this subsection we develop a technique for dealing with the R-matrices, their compatible pairs and the R-trace. Most of results reported here, like the lemma 3.5 and, in a particular case of a compatible pair \( \{ R, R \} \) – the lemmas 3.2 and 3.3 and the corollary 3.4 – are rather well known (see, e.g., [I, O]). However, we often use them in a more general settings and so, when necessary, we present sketches of proofs.

The lemma 3.6 contains some new results. Here we derive a different, from the standard one, expression for the twisted R-matrix, which helps to investigate its skew-invertibility.

A universal (i.e., quasi-triangular Hopf algebraic) content of the matrix relations derived in this subsection is discussed in the appendix.

Lemma 3.2 Let \( \{ X, F \} \) be a compatible pair, where \( X \) is skew invertible. Let \( \text{Mat}_N(W) \) be as in the definition 3.1. For any \( M \in \text{Mat}_N(W) \), one has

\[
\text{Tr}_1 \left( C_{X1} F_{12}^\varepsilon M_2 F_{12}^{-\varepsilon} \right) = I_2 \text{Tr}(C_X M), \quad (3.2.1)
\]

\[
\text{Tr}_2 \left( D_{X2} F_{12}^{-\varepsilon} M_1 F_{12}^\varepsilon \right) = I_1 \text{Tr}(D_X M) \quad \text{for } \varepsilon = \pm 1. \quad (3.2.2)
\]

Proof. We use the twist relations (3.1.11) in a form

\[
F_{23}^\varepsilon X_{34} F_{23}^{-\varepsilon} = F_{34}^{-\varepsilon} X_{23} F_{34}^\varepsilon, \quad \varepsilon = \pm 1.
\]

Multiplying it by \( \Psi_{X12} \Psi_{X45} \) and taking the traces in the spaces 2 and 4, we get

\[
\text{Tr}_2 \left( \Psi_{X12} F_{23}^\varepsilon P_{35} F_{23}^{-\varepsilon} \right) = \text{Tr}_4 \left( \Psi_{X45} F_{34}^{-\varepsilon} P_{13} F_{34}^\varepsilon \right). \quad (3.2.3)
\]

Here eq. (3.1.3) was applied to calculate the traces. Now taking the trace in the space number 1 or number 5, we obtain (after relabeling)

\[
\text{Tr}_1 \left( C_{X1} F_{12}^\varepsilon P_{23} F_{12}^{-\varepsilon} \right) = C_X I_2, \quad (3.2.4)
\]

\[
\text{Tr}_3 \left( D_{X3} F_{23}^{-\varepsilon} P_{12} F_{23}^\varepsilon \right) = D_X I_2. \quad (3.2.5)
\]

These two relations are equivalent forms of eqs.(3.2.1) and (3.2.2). E.g., the formula (3.2.1) is obtained by multiplying eq.(3.2.4) by \( M_3 \) and taking the trace in the space 3. \( \blacksquare \)

Lemma 3.3 Let \( \{ X, F \} \) be a compatible pair of skew invertible operators \( X \) and \( F \). Then following relations

\[
C_{X1} \Psi_{F12} = F_{21}^{-1} C_{X2}, \quad \Psi_{F12} C_{X1} = C_{X2} F_{21}^{-1}, \quad (3.2.6)
\]

\[
\Psi_{F12} D_{X2} = D_{X1} F_{21}^{-1}, \quad D_{X2} \Psi_{F12} = F_{21}^{-1} D_{X1} \quad (3.2.7)
\]

hold.

Proof. For a skew invertible \( F \), eqs.(3.2.6) and (3.2.7) are equivalent to eqs.(3.2.4) and (3.2.5). Let us demonstrate how the left one of eqs.(3.2.6) is derived from eq.(3.2.4) with \( \varepsilon = 1 \).
Multiply eq.(3.2.4) by \( (P_{23}\Psi_{F24}) \) from the right, take the trace in the space 2 and simplify the result using eq.(3.1.3) for \( X = F \) and properties of the permutation

\[
\text{Tr}_1(CX_1 P_{14} F_{13}^{-1}) = CX_3 \text{Tr}_2(P_{23} \Psi_{F24}) = CX_3 \Psi_{F34}.
\]

Then simplify the left hand side of the equality using the cyclic property of the trace

\[
\text{Tr}_1(CX_1 P_{14} F_{13}^{-1}) = \text{Tr}_1(P_{14} F_{13}^{-1} CX_1) = F_{43}^{-1} CX_4 \text{Tr}_1 P_{14} = F_{43}^{-1} CX_4.
\]

This proves the left relation in (3.2.6).

\[\Box\]

**Corollary 3.4** Let \( \{X, F\} \) and \( \{Y, F\} \) be compatible pairs of skew invertible operators \( X, Y \) and \( F \). Then following relations

\[
F_{12} CX_1 CY_2 = CY_1 CX_2 F_{12}, \quad F_{12} DY_1 DY_2 = DY_1 DY_2 F_{12}, \quad (3.2.8)
\]

\[
F_{12}(CX DY)_2 = (CX DY)_1 F_{12}, \quad F_{12}(DY CX)_1 = (DY CX)_2 F_{12}, \quad (3.2.9)
\]

\[
\text{Tr}_1(CX_1 F_{12}^{-1}) = (CX DY)_2 = (DY CX)_2, \quad (3.2.10)
\]

\[
\text{Tr}_2(DY_2 F_{12}^{-1}) = (DY CX)_1 = (DX CY)_1. \quad (3.2.11)
\]

hold.

**Proof.** A calculation \( (F_{12}^{-1} CY_1) CX_2 = CY_2(\Psi_{F21} CX_2) = CY_2 CX_1 F_{12}^{-1} = CX_1 CY_2 F_{12}^{-1} \) proves the left one of eqs.(3.2.8). Here the relations (3.2.6) were applied.

A calculation \( (F_{12}^{-1} CX_1) DY_1 = CX_2(\Psi_{F21} CY_1) = CX_2 CY_2 F_{12}^{-1} \) proves the left one of eqs.(3.2.9). Here one uses subsequently the left equations from (3.2.6) and (3.2.7).

The relations (3.2.10) follow by taking \( \text{Tr}_2 \) of the equations (3.2.6).

The rest of the relations in (3.2.8)--(3.2.11) are derived in a similar way. \[\Box\]

**Lemma 3.5** Let \( X \) be a skew invertible R-matrix. Then statements

a) the R-matrix \( X^{-1} \) is skew invertible;

b) the R-matrix \( X \) is strict skew invertible,

are equivalent.

Provided these statements are satisfied, both \( C_X \) and \( D_X \) are invertible and one has

\[
C_{X^{-1}} = D_X^{-1}, \quad D_{X^{-1}} = C_X^{-1}. \quad (3.2.12)
\]

**Proof.** See [O], the section 4.1, statements after eq.(4.1.77), or [I], the proposition 2 in the section 3.1.

Under an assumption of an existence, for an R-matrix \( X \), of the operators \( X^{-1}, \Psi_X \) and \( \Psi_{X^{-1}} \), the relations (3.2.12) were proved in [Resh]. \[\Box\]

Since, for a compatible pair \( \{X, F\} \), the pair \( \{X, F^{-1}\} \) is also compatible, eqs.(3.2.12) together with eqs.(3.2.10-3.2.11) imply that \( C_X CF = CF CX \) and \( D_X DF = DF DX \).
Let \( \{ R, F \} \) be a compatible pair of R-matrices. Define a \textit{twisted} operator
\[
R_f := F^{-1}RF.
\] (3.2.13)

It is well known that \( R_f \) is an R-matrix and the pair \( \{ R_f, F \} \) is compatible. Therefore, one can twist again; in [IOP1] it was shown that if \( F \) is skew invertible then
\[
D_{F1}D_{F2}((R_f)_{f})_{12} = R_{12}D_{F1}D_{F2};
\] (3.2.14)

\textbf{Lemma 3.6} Let \( \{ R, F \} \) be a compatible pair of R-matrices. Following statements hold.

\begin{enumerate}
  \item[a)] if \( F \) is strict skew invertible then \( R_f \) (3.2.13) can be expressed in a form
  \[
  R_{f12} = \text{Tr}_{(34)} \left( F_{32}^{-1}C_{F^{-1}3}R_{34}D_{F4}F_{14} \right);
  \] (3.2.15)

  \item[b)] if \( R \) is skew invertible and \( F \) is strict skew invertible then \( R_f \) is skew invertible; its skew inverse is
  \[
  \Psi_{R_f12} = C_{F^{-1}2} \text{Tr}_{(34)} \left( F_{23}^{-1}\Psi_{R34}F_{41} \right) D_{F1};
  \] (3.2.16)

  moreover, \( \Psi_{R_f} \) can be expressed in a form
  \[
  \Psi_{R_f12} = C_{F^{-1}2}F_{21}D_{F^{-1}2}\Psi_{R12}C_{F1}F_{21}^{-1}D_{F1};
  \] (3.2.17)

  \item[c)] under the conditions in b),
  \[
  C_{R_f} = C_{F^{-1}1}D_RC_F, \quad D_{R_f} = D_{F^{-1}1}C_RD_F
  \] (3.2.18)

  (thus, if, in addition to the conditions in b), \( R \) is strict skew invertible then \( R_f \) is strict skew invertible as well)
\end{enumerate}

\textbf{Proof.} To verify the assertion a) we calculate
\[
R_{f12} = (F^{-1}RF)_{12} = F_{12}^{-1} \left( \text{Tr}_{(4)} F_{41}^{-1}C_{F^{-1}4} \right) (RF)_{12}
\]
\[
= \text{Tr}_{(4)} \left( (RF)_{41}F_{12}^{-1}F_{41}^{-1}C_{F^{-1}4} \right) = \left( \text{Tr}_{(3)} P_{13} \right) \text{Tr}_{(4)} \left( (RF)_{41}F_{12}^{-1}C_{F^{-1}1}F_{14} \right)
\]
\[
= \text{Tr}_{(34)} \left( (RF)_{43}F_{32}^{-1}C_{F^{-1}3}P_{13}\Psi_{F14} \right) = \text{Tr}_{(3)} \left( F_{32}^{-1}C_{F^{-1}3}P_{13} \text{Tr}_{(4)} \Psi_{F14}(RF)_{43} \right),
\] (3.2.19)

where in the second equality we used the relation (3.1.5) for \( X = F^{-1} \); in the third equality we applied the twist relations; in the fourth equality we applied eq.(3.2.6) for \( X = F^{-1} \) and inserted the identity operator \( \text{Tr}_{(3)} P_{13} \); in the fifth equality we permuted \( P_{13} \) rightwards and then, in the sixth equality, used the cyclic property of the trace to move \( (RF)_{43} \) to the right.

To complete the transformation, we derive an alternative form for the underlined expression in the last line in (3.2.19). Multiplying the twist relation \( R_2F_3F_2 = F_3F_2R_3 \) by \( (\Psi_{F12}D_{F4}) \) and taking the traces in the spaces 2 and 4, we obtain (using eqs.(3.1.3) and (3.1.5) for \( X = F \))
\[
\text{Tr}_{(2)} \left( \Psi_{F12}(RF)_{23} \right) = \text{Tr}_{(4)} \left( D_{F4}F_{34}P_{13}R_{34} \right),
\]
which is equivalent (multiply by $P_{13}$ from the left and use the cyclic property of the trace) to
\[
P_{13} \text{Tr}_2 (\Psi_{F21} RF_{23}) = \text{Tr}_4 (R_{34} D_{F4} F_{14}) .
\] (3.2.20)

Now, substituting (3.2.20) into (3.2.19), we finish the transformation and obtain (3.2.15).

Given the formula for $R_f$, the calculation of $\Psi_{RF}$ becomes straightforward and one finds the formula (3.2.16).

Thus, the skew invertibility of $R_f$ is established.

Now we derive the expression (3.2.17) for $\Psi_{RF}$. Multiplying (3.2.3) with $\varepsilon = 1$ by $P_{35} D_{F-15}$ from the right and taking the trace in the space 5, we obtain
\[
\text{Tr}_2 (\Psi_{RF12} F_{23}) = \text{Tr}_4 (F_{34}^{-1} P_{13} F_{34} D_{F-15} P_{45} D_{F-13} \Psi_{RF43}) .
\]
Substituting this into the expression (3.2.16), we find
\[
\Psi_{RF12} = C_{RF12} \text{Tr}_4 \left( F_{23}^{-1} F_{14}^{-1} P_{13} F_{14} D_{F-11} \Psi_{RF41} \right) D_{F1} \\
= C_{RF12} \text{Tr}_4 \left( F_{14}^{-1} \text{Tr}_3 (F_{23}^{-1} P_{13}) F_{14} D_{F-11} \Psi_{RF41} \right) D_{F1} \\
= C_{RF12} \text{Tr}_4 \left( F_{14}^{-1} F_{21}^{-1} D_{F-11} \Psi_{RF41} \right) D_{F1} \\
= C_{RF12} F_{21} D_{F-12} \text{Tr}_4 \left( F_{14}^{-1} \Psi_{F12} \Psi_{RF41} \right) D_{F1} .
\] (3.2.21)

We used the Yang-Baxter equation for the operator $F$ in the fourth equality and eqs.(3.2.6) in the fifth equality.

Multiplying eq.(3.2.3) with $\varepsilon = -1$ by $\Psi_{F01} P_{13}$ from the left and by $P_{35} \Psi_{F56}$ from the right and taking the traces in the spaces 1 and 5, we find
\[
F_{14}^{-1} \Psi_{F12} \Psi_{RF41} = \Psi_{RF12} \Psi_{F41} F_{21}^{-1} .
\]
Substituting this into the last line of (3.2.21), we obtain the equality (3.2.17).

Finally, expressions (3.2.18) for $C_{RF}$ and $D_{RF}$ are obtained by taking the trace in the space 1 or the space 2 of eq.(3.2.16) and the subsequent use of eq.(3.1.5) for $X = F^{\pm 1}$ and eqs.(3.1.4), (3.2.10) and (3.2.11) for $X = R$.

\section{3.3 BMW type R-matrices}

In this subsection we discuss the R-matrices of the BMW-type in more detail.

In the lemma 3.7 we collect additional relations specific to the BMW-type R-matrices. Based on these formulas, we introduce, in the lemmas 3.8 and 3.10, an invertible operator $G \in \text{Aut}(V)$ and linear maps $\phi$ and $\xi$, which will be used in the section 4 for a definition of a product of quantum matrices and for a quantum matrix inversion.
Lemma 3.7 Let $R$ be a skew invertible R-matrix of the BMW-type. Then

- the operator $R$ is strict skew invertible;
- the rank of the operator $K$ equals one, $\text{rk} K = 1$;
- following relations
  \begin{align}
  \text{Tr} (2) K_{12} &= \mu^{-1} D_{R1}, \quad \text{Tr} (1) K_{12} = \mu^{-1} C_{R2}, \quad (3.3.1) \\
  \text{Tr}_R K_{12} &= \mu I_1, \quad (3.3.2) \\
  \text{Tr}_R I &= \mu \eta \equiv \frac{(q-\mu)(q^{-1}+\mu)}{(q-q^{-1})}, \quad (3.3.3) \\
  C_R D_R &= \mu^2 I, \quad (3.3.4) \\
  K_{12} D_{R1} D_{R2} &= D_{R1} D_{R2} K_{12} = \mu^2 K_{12} \quad (3.3.5)
  \end{align}

hold.

Proof. The proof of all the statements in the lemma but the last one is given in [IOP3]. The last relation (3.3.5) (which, in another form, figures in [IOP3], in the proposition 2) can be established in a following way.

The first equality in (3.3.5) is a consequence of a relation

\begin{equation}
R_{12} D_{R1} D_{R2} = D_{R1} D_{R2} R_{12}, \quad (3.3.6)
\end{equation}

which is just the equality (3.2.8) written for the pair $\{R,R\}$. Then the conditions $K^2 \sim K$ and $\text{rk} K = 1$ together imply $K_{12} D_{R1} D_{R2} \sim K_{12} D_{R1} D_{R2} K_{12} \sim K_{12}$. A coefficient of proportionality in this relation is recovered by taking the trace of it in the space 2 and the subsequent use of eqs.(3.3.1) and (3.3.2).

In [IOP3], a pair of mutually inverse matrices

\begin{equation}
E_2 := \text{Tr} (1)(K_{12} P_{12}) \quad \text{and} \quad E_1^{-1} := \text{Tr} (2)(K_{12} P_{12}) \quad (3.3.7)
\end{equation}

were introduced (see eqs.(32) and (33) and the proposition 2 in [IOP3]). In the following lemma, we define analogues of the matrices $E$ and $E^{-1}$ for a compatible pair $\{R,F\}$ of R-matrices. When the operator $F$ is the permutation operator, $F = P$, the matrix $G$ of the definition-lemma 3.8 coincides with the matrix $E$.

Definition-Lemma 3.8 Let $\{R,F\}$ be a compatible pair of R-matrices, where $R$ is skew-invertible of the BMW-type and $F$ is strict skew-invertible. Define an element $G \in \text{End}(V)$ by

\begin{equation}
G_1 := \text{Tr} (23) K_2 F_1^{-1} F_2^{-1}. \quad (3.3.8)
\end{equation}

The operator $G$ is invertible, the inverse operator reads

\begin{equation}
G_1^{-1} = \text{Tr} (23) F_2 F_1 K_2. \quad (3.3.9)
\end{equation}
Following relations

\[ R_{12}G_1G_2 = G_1G_2R_{12}, \quad F_{12}^\varepsilon G_1 = G_2F_{12}^\varepsilon \quad \text{for } \varepsilon = \pm 1, \quad (3.3.10) \]

\[ [D_R, G] = [C_F, G] = [D_F, G] = 0 \quad (3.3.11) \]

are satisfied.

**Proof.** A check of the invertibility of \( G \) is a direct calculation

\[ G_1^{-1} = \frac{\langle \psi | A | \zeta \rangle}{\langle \psi | A | \zeta \rangle} \quad (3.3.8) \]

\[ G_2 = \frac{\langle \psi | A | \zeta \rangle}{\langle \psi | A | \zeta \rangle} \quad (3.3.9) \]

\[ \text{for any } A \quad \text{and } \quad B; \quad \text{in the second line of (3.3.12) we passed from } \ K \text{ to } K_f = F^{-1}KF \text{ and applied the twist relations (for } K_f \text{ and } F)\text{ and the cyclic property of the trace. In the last equality of (3.3.12) we evaluated the traces using the relations (3.3.1) and then the relation (3.3.2) for } K_f \text{ (we are allowed to use these relations because } R_f \text{ is skew-invertible by the lemma 3.6).} \]

Notice that, in view of eq.(3.3.5), we can rewrite the formula for \( G \) using the R-traces instead of the ordinary ones

\[ G_1 = \mu^{-2} \text{Tr}_{R(34)} K_2 F_1^{-1} F_2^{-1}. \quad (3.3.13) \]

Applying the formula (3.2.2) (written for \( F^X = X = R \)) twice to this equality, we begin our next calculation

\[ G_1I_2 = \mu^{-2} \text{Tr}_{R(34)} (R_2 R_3) K_2 F_1^{-1} F_2^{-1} (R_3^{-1} R_2^{-1}) = \mu^{-2} \text{Tr}_{R(34)} K_2 K_3 F_1^{-1} F_2^{-1} R_3^{-1} R_2^{-1} \]

\[ = \mu^{-2} \text{Tr}_{R(34)} K_2 F_1^{-1} F_2^{-1} K_3 = \mu^{-2} \text{Tr}_{R(34)} K_2 F_1^{-1} F_2^{-1} K_2. \quad (3.3.14) \]

Here we used eq.(3.1.10) in the last equality of the first line. In the second line we again applied eq.(3.1.10) after moving \( K_3 \) to the right (for that we need eq.(3.3.5) and the cyclic property of the trace) and then we evaluated one R-trace with the help of eq.(3.3.2).

Now we use the formula (3.3.14) for the product \( G_1G_2 \) in a transformation

\[ G_1G_2R_1 = \mu^{-2} \text{Tr}_{R(34)} (K_3 F_2^{-1} F_3^{-1} K_3) (K_2 F_1^{-1} F_2^{-1} K_2) R_1 \]

\[ = \mu^{-2} \text{Tr}_{R(34)} F_2^{-1} F_3^{-1} K_2 K_3 F_1^{-1} F_2^{-1} K_2 R_1 = \mu^{-2} \text{Tr}_{R(34)} F_2^{-1} F_3^{-1} F_1^{-1} F_2^{-1} K_1 K_2 R_1 \]

\[ = \mu^{-2} \text{Tr}_{R(34)} F_2^{-1} F_3^{-1} F_1^{-1} F_2^{-1} K_1 R_2^{-1} = \mu^{-2} \text{Tr}_{R(34)} K_3 F_2^{-1} F_3^{-1} F_1^{-1} F_2^{-1} R_2^{-1} \]

\[ = \mu^{-2} \text{Tr}_{R(34)} F_2^{-1} F_3^{-1} F_1^{-1} F_2^{-1} R_3 K_2 K_3 = \mu^{-2} R_1 \text{Tr}_{R(34)} F_2^{-1} F_3^{-1} F_1^{-1} F_2^{-1} K_2 K_3 \]

\[ = \mu^{-2} R_1 \text{Tr}_{R(34)} K_3 F_2^{-1} F_3^{-1} F_1^{-1} F_2^{-1} K_2 = R_1 G_1 G_2, \]
which demonstrates the first of the relations in (3.3.10). While doing this calculation, we repeatedly used the twist relations for the pairs \( \{K, F^{-1}\} \) and \( \{R, F^{-1}\} \), applied the formulas (3.1.10) and exploited the cyclic property of the trace to move the operator \( K_3 \) to the right/left in the fourth/fifth line, respectively.

The second relation in (3.3.10) is proved as follows

\[
G_1 F^\varepsilon_1 = \mu^{-2} \text{Tr}_{R(23)} \left( K_2 F_1^{-1} F_2^{-1} \right) F^\varepsilon_1 = \mu^{-2} \text{Tr}_{R(34)} \left( (F_2^{-\varepsilon} F_3^{\varepsilon}) K_2 F_1^{-1} F_2^{-1} (F_3^{\varepsilon} F_2^{-\varepsilon}) \right) F^\varepsilon_1 = \mu^{-2} \text{Tr}_{R(34)} (F_2^{-\varepsilon} F_3^{\varepsilon}) F_3^{\varepsilon} F_2^{-\varepsilon} F_1 K_3 F_2^{-1} F_3^{-1} = F^\varepsilon_1 F_1^{-2} \mu^{-2} \text{Tr}_{R(34)} K_3 F_2^{-1} F_3^{-1} = F^\varepsilon_1 G_2 .
\]

(3.3.15)

Here we subsequently used eqs.(3.3.13) and (3.2.2) for \( X = R \), the twist relations for the pair \( \{K, F^\varepsilon\} \), the Yang-Baxter equations for \( X \) and again eq.(3.3.13).

Vanishing of the last two commutators in eq.(3.3.11) follow from the above proved equality. To find these commutators, transform eq.(3.3.15) to

\[
G_1 \Psi_{F12} = \Psi_{F12} G_2 , \quad G_2 \Psi_{F12} = \Psi_{F12} G_1 ,
\]

(3.3.16)

(multiply (3.3.15) by \( \Psi_{F41} \Psi_{F23} \) and take \( \text{Tr}_{(12)} \)) and then apply the trace in the space 1 or the space 2 to these relations and compare results.

The first of the relations (3.3.11) is approved by a calculation

\[
G_1 D_{R1} = \mu^{-2} \text{Tr}_{R(23)} K_2 F_1^{-1} F_2^{-1} D_{R1} = \mu^{-2} \text{Tr}_{(23)} K_2 F_1^{-1} F_2^{-1} D_{R1} D_{R2} D_{R3} = \mu^{-2} \text{Tr}_{(23)} D_{R1} D_{R2} D_{R3} K_2 F_1^{-1} F_2^{-1} = D_{R1} G_1 .
\]

Here eqs.(3.3.13) and (3.2.8) for \( X = Y = R \) and eq.(3.3.5) were used.

\[\square\]

**Remark 3.9** One can rewrite further the expression (3.3.13) for \( G \):

\[
G_1 = \mu^{-2} \text{Tr}_{R(23)} F_1^{-1} F_2^{-1} K_1 = \mu^{-2} \text{Tr}_{R(2)} F_1^{-1} C_{F2} D_{R2} K_1 = \text{Tr}_{R(2)} F_1^{-1} C_{F2} D_{R1}^{-1} K_1 = \mu^{-2} \text{Tr}_{R(2)} F_1^{-1} C_{F2} C_{R1} K_1
\]

(3.3.17)

Here we used subsequently: the twist relation, the relations (3.2.11), (3.3.5), (3.3.4), (3.2.8) and then again (3.3.4).

**Definition-Lemma 3.10** Let \( \{R, F\} \) be a compatible pair of skew invertible \( R \)-matrices, where the operator \( R \) is of the BMW-type and the operator \( F \) is strict skew invertible. Define two endomorphisms \( \phi \) and \( \xi \) of the space Mat\(_N(W)\):

\[
\phi(M)_{1} := \text{Tr}_{R(2)} \left( F_{12} M_{1} F_{12}^{-1} R_{12} \right) , \quad M \in \text{Mat}_N(W),
\]

(3.3.18)

and

\[
\xi(M)_{1} := \text{Tr}_{R(2)} \left( F_{12} M_{1} F_{12}^{-1} K_{12} \right) , \quad M \in \text{Mat}_N(W).
\]

(3.3.19)
The mappings $\phi$ and $\xi$ are invertible; their inverse mappings read

$$\phi^{-1}(M)_{1} = \mu^{-2} Tr_{Rf}^{(2)} (F_{12}^{-1} M_{1} R_{12}^{-1} F_{12})$$

(3.3.20)

and

$$\xi^{-1}(M)_{1} = \mu^{-2} Tr_{Rf}^{(2)} (F_{12}^{-1} M_{1} K_{12} F_{12}) .$$

(3.3.21)

Following relations for the R-traces

$$Tr_{Rf} \phi(M) = Tr_{R} M , \quad Tr_{Rf} \xi(M) = \mu Tr_{R} M .$$

(3.3.22)

are satisfied.

**Proof.** The expressions in the right hand sides of eqs.(3.3.20) and (3.3.21) are well defined, since, by the lemma 3.6 b), the R-matrix $R_{f}$ is skew invertible.

Let us check the relation $\phi^{-1}(\phi(M)) = M$ directly.

Using the formulas (3.3.18) and (3.3.20) and applying the relation (3.2.2) for the pair $\{R, F\}$ we begin a calculation

$$\phi^{-1}(\phi(M))_{1} = \mu^{-2} Tr_{Rf}^{(2)} \left( F_{12}^{-1} (Tr_{Rf}^{(2')} F_{12'} M_{1} F_{12}^{-1} R_{12'}) R_{12}^{-1} F_{12} \right)$$

$$= \mu^{-2} Tr_{Rf}^{(2)} Tr_{R}^{(3)} \left( F_{1}^{-1} F_{2}^{-1} F_{1}^{-1} M_{1} F_{1}^{-1} R_{1} F_{2} R^{-1} F_{1} \right) .$$

In the next step we move the element $F_{1}$ underlined in the expression above to the left and then transport it to the right hand side using the cyclic property of the trace (when $F_{2}$ moves cyclically, $Tr_{Rf}^{(2)} Tr_{R}^{(3)}$ becomes $Tr_{Rf}^{(2)} Tr_{Rf}^{(3)}$ due to eq.(3.2.8)). Applying the Yang-Baxter equation for $F$ and the relation (3.2.8) in the case $X = R$ and $Y = R_{f}$, we continue

$$\phi^{-1}(\phi(M))_{1} = \mu^{-2} Tr_{Rf}^{(2)} Tr_{Rf}^{(3)} \left( F_{1}^{-1} F_{2}^{-1} F_{1}^{-1} M_{1} F_{1}^{-1} R_{1} F_{2} R_{f}^{-1} F_{1} F_{2} \right)$$

$$= \mu^{-2} Tr_{Rf}^{(2)} Tr_{Rf}^{(3)} \left( F_{1}^{-1} M_{1} F_{2}^{-1} R_{f_{1}} F_{2} R_{f_{1}}^{-1} F_{2} F_{1} F_{2} R_{f_{1}}^{-1} F_{2} \right)$$

$$= \mu^{-2} Tr_{Rf}^{(2)} Tr_{Rf}^{(3)} \left( F_{1}^{-1} M_{1} F_{2}^{-1} R_{f_{1}} F_{2} R_{f_{1}}^{-1} F_{2} F_{1} F_{2} R_{f_{1}}^{-1} F_{2} \right)$$

$$= \mu^{-2} Tr_{Rf}^{(2)} \left( F_{1}^{-1} M_{1} F_{1} (Tr_{Rf}^{(3)} R_{f_{2}} F_{1} R_{f_{2}}^{-1} F_{1}) F_{1}^{-1} \right) .$$

(3.3.23)

Here we consequently transformed the underlined expressions using the definition of $R_{f}$, the Yang-Baxter equation for $F$ and the twist relations for the pair $\{R_{f}, F\}$. To calculate the trace underlined in the last line of (3.3.23), we apply the relation (3.2.2) for the pair $\{R_{f}, R_{f}\}$ and then use the relation (3.2.11) written for the pair $\{R_{f}, F^{-1}\}$. The result reads

$$\phi^{-1}(\phi(M))_{1} = \mu^{-2} Tr_{Rf}^{(2)} \left( F_{1}^{-1} M_{1} F_{1} (D_{Rf} C_{F^{-1}}) F_{1}^{-1} \right) .$$

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Now, using eq.(3.2.9), written for the pairs \( \{R_f, F\} \) and \( \{F^{-1}, F\} \), the relations (3.2.18) and (3.2.12) for \( X = F \), eq.(3.3.4) and the relation (3.1.5) for \( X = F^{-1} \), we complete the calculation
\[
\phi^{-1}(\phi(M))_1 = \mu^{-2} \text{Tr}_{(2)} \left( (D_{R_f}C_{F^{-1}}D_R)_2 F_1^{-1} \right) M_1
\]
\[
= \mu^{-2} \text{Tr}_{(2)} \left( (D_{F^{-1}}C_RD_RC_{F^{-1}}D_R)_2 F_1^{-1} \right) M_1 = \text{Tr}_{(2)} (D_{F^{-1}} F_1^{-1}) M_1 = M_1. \tag{3.2.24}
\]

A proof of the equality \( \xi^{-1}(\xi(M)) = M \) proceeds quite similarly until the line (3.3.23), where one has to use a relation
\[
\text{Tr}_{R(2)}(K_1 M_1 K_1) = (\text{Tr}_R M) I_1 \quad \forall M \in \text{Mat}_N(W) \tag{3.3.25}
\]
instead of the relation (3.2.2). This in turn follows from eqs.(3.3.1) and (3.3.2) and the property \( \text{rk} K = 1 \).

The relations (3.3.22) can be directly checked starting from the definitions (3.3.18) and (3.3.19), applying the relation (3.2.8) in the case \( X = R \) and \( Y = R_f \) and then using the formulas (3.1.13) and (3.3.2).

\[ \blacksquare \]

**Remark 3.11** For the mapping \( \phi \), the statement of the lemma 3.10 remains valid if one weakens the conditions, imposed on the R-matrix \( R \), replacing the BMW-type condition by the strict skew invertibility. In this case, one should substitute the term \( \mu^{-2}D_{R_f} \) by \( D_{R_f}^{-1} \) in the expression (3.3.20) for the inverse mapping \( \phi^{-1} \). The proof repeats the proof of the formula (3.3.20).

### 3.4 Orthogonal and symplectic type R-matrices

Most of results of this paper will be derived for two particular families of the BMW-type R-matrices. We are going to describe them now.

Consider R-matrix realizations \( \rho_R(a^{(i)}) \) of the antisymmetrizers (2.2.6). We impose additional constraints on a skew invertible BMW-type R-matrix \( R \) demanding that
\[
\text{rk} \rho_R(a^{(i)}) \neq 0 \quad \forall \ i = 2, 3, \ldots, k \quad \text{and} \quad \rho_R \left( a^{(k)^{\dagger}} \sigma_1 (q^{-2k}) a^{(k)^{\dagger}} \right) \equiv 0 \tag{3.4.1}
\]
for some \( k \geq 2 \). Here we assume that parameters \( q \) and \( \mu \) fulfill conditions (c.f. with eq.(2.2.8))
\[
i_q \neq 0 \quad \forall \ i = 2, 3, \ldots, k; \quad \mu \neq -q^{-2i+1} \quad \forall \ i = 1, 2, \ldots, k. \tag{3.4.2}
\]
Notice that, in the last condition in eq.(3.4.1), the unnormalized form of the \((k+1)\) order antisymmetrizer \( a^{(k+1)} \) is used and so there is no need to demand \((k+1)_q \neq 0 \).

Let us derive some consequences of the relations (3.4.1). Applying \( \text{Tr}_{R(i)} \) to \( \rho_R(a^{(i)}) \) and using the relations (2.2.6), (3.1.13), (3.3.1) and (3.3.3), we calculate
\[
\text{Tr}_{R(i)} \rho_R(a^{(i)}) = \delta_i \rho_R(a^{(i-1)}), \quad \text{where} \quad \delta_i \equiv \delta_i(q, \mu) := \frac{-q^{i-1}(\mu + q^{1-2i})(\mu^2 - q^{4-2i})}{(\mu + q^{3-2i})(q - q^{-1})i_q}. \tag{3.4.3}
\]
In view of eqs.(3.4.3), the conditions (3.4.1) imply, in particular, \( \delta_{k+1} = 0 \), wherefrom one specifies three admissible values of \( \mu \): \( \mu \in \{-q^{-1-2k}, \pm q^{1-k}\} \).
Notice that the choice $\mu = -q^{1-k}$ contradicts the conditions (3.4.2) in the case when the number $k$ is even.

In the case when $k$ is odd, the choices $\mu = -q^{1-k}$ and $\mu = q^{1-k}$ are related by a substitution $R \mapsto -R$. On the algebra level, this corresponds to an algebra isomorphism $W_n(q, \mu) \to W_n(-q, -\mu)$: $\sigma_i \mapsto -\sigma_i$, $i = 1, \ldots, n - 1$. The (anti)symmetrizers are invariant under this map: $s^{(i)} \mapsto s^{(i)}$ and $a^{(i)} \mapsto a^{(i)}$.

Therefore we are left with only two essentially different choices of the parameter $\mu$: either $\mu = -q^{1-k}$ or $\mu = q^{1-k}$.

Notice that, with these choices, the consistency of the conditions on $\mu$ in eq.(3.4.2) follows from the conditions on $q$.

\textbf{Definition 3.12} Let $R$ be a skew invertible BMW-type R-matrix defining representations $\rho_R$ of the algebras $W_i(q, \mu)$. Assume that $R$ additionally satisfies the conditions (3.4.1) for some $k \geq 2$. This implies, in particular, restrictions on $q$: $i_q \neq 0$ for $i = 2, \ldots, k$. Then

a) $R$ is called a $\text{Sp}(2k)$-type R-matrix in the case when $\mu = -q^{1-2k}$;

b) $R$ is called an $\text{O}(k)$-type R-matrix in the case when $\mu = q^{1-k}$ and $rk\rho_R(a^{(k)}) = 1$.

For the standard R-matrices related to the quantum groups of the series $\text{Sp}_q(2k)$ and $\text{SO}_q(k)$ [RTF], the conditions a) and b), respectively, as well as the relations (3.4.1) are fulfilled. This explains our notation.

\textbf{Remark 3.13} Functions

$$\Delta^{(i)}(q, \mu) := \text{Tr}_{R(1, 2, \ldots, i)}\rho_R(a^{(i)}) = \prod_{j=1}^{i} \delta_j(q, \mu)$$

are (up to an overall factor) particular elements of a set of rational functions $Q_{\lambda}(\mu^{-1}, q)$ labelled by partitions $\lambda \vdash i$. The functions (3.4.4) were introduced in the theorem 5.5 in [W] ($\Delta(q, \mu) = \mu^iQ_{[1^i]}(\mu^{-1}, q)$). These functions describe the q-dimensions of the highest weight modules $V_{\lambda}$ for the orthogonal and symplectic quantum groups (see [W], the section 5 and [OrW], the lemma 3.1). E.g., in the orthogonal case, the q-dimensions of the highest weight modules $V_{[1^i]}$ are (up to an overall factor) given by a formula

$$\Delta^{(i)}(q, q^{1-k}) = q^{i(1-k)} \frac{q^i + q^{k-i}}{q^k + 1} \frac{k_q!}{i_q!(k-i)_q!},$$

which we shall several times use below.

\textbf{Remark 3.14} We note, without going into details, particular values of $k$ for the R-matrices of the orthogonal and symplectic types.

For the symplectic type, the case $k = 1$ is particular: the antisymmetrizer $\rho_R(a^{(2)})$ vanishes and the spectral decomposition of $R$ contains only two projectors:

$$R = q\rho_R(s^{(2)}) - q^{-3}\rho_R(c^{(2)}).$$

\textsuperscript{7}We stress again that the cases $q = \pm 1$ can be consistently treated as the limiting cases $q \to \pm 1$.  

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This R-matrix is of the Hecke type $GL(2)$ (to normalize the eigenvalues, multiply by $q$ and replace $q^2$ by $q$), which is a manifestation of the accidental isomorphism $SL(2) \sim Sp(2)$.

Accidental isomorphisms for quantum groups, corresponding to the standard deformation, are discussed in [JO].

For the orthogonal type, the case $k = 4$ is particular. We just mention that in this case the antisymmetrizer $\rho_R(a^{(2)})$ splits into two projectors (the self-dual and anti-self-dual parts), $\rho_R(a^{(2)}) = \rho_R(a^{(2)})^{(+)} + \rho_R(a^{(2)})^{(-)}$. They satisfy

$$\rho_R(a^{(2)})_{12}^{(+)} R_{23} R_{12} = R_{23} R_{12} \rho_R(a^{(2)})_{23}^{(+)}$$

and

$$\rho_R(a^{(2)})_{23}^{(+)} R_{12} R_{23} = R_{12} R_{23} \rho_R(a^{(2)})_{12}^{(+)}.$$ 

This shows that, in this case, the structure of the centralizer algebra is not of the BMW type.

The geometry of the four-dimensional euclidean and Minkowski spaces is considered, for the standard deformation, in [OSWZ].

### 3.5 Rank-one projectors

In the definition of type $O(k)$ R-matrices we demanded the operator $\rho_R(a^{(k)}) \in \text{End}(V^\otimes k)$ to be of rank one. In this subsection we investigate specific consequences the rank-one condition results in.

We first observe that any skew invertible BMW-type R-matrix gives rise to a series of rank-one projectors.

**Lemma 3.15** Assume that $R$ is a skew invertible R-matrix of the BMW-type. Then $\rho_R(c^{(2i)}) \in \text{End}(V^\otimes 2i)$ (for the definition of the idempotents $c^{(2i)}$, see eqs.(2.2.12)) are rank-one operators fulfilling relations

$$\text{Tr}_{R(2i)} \rho_R(c^{(2i)}) = \eta^{-1} \mu I_1 \rho_R(c^{(2i-2)} \rho_R) \forall i \geq 1,$$  

(3.5.1)

$$\text{Tr}_{R(i+1,i+2,\ldots,2i)} \rho_R(c^{(2i)}) = (\eta^{-1} \mu)^i I_{1,2,\ldots,i}.$$  

(3.5.2)

**Proof.** We will prove eq.(3.5.1) performing induction on $i$. For $i = 1$, the relation (3.5.1) is just the equality (3.3.2). Assuming that the equation (3.5.1) is valid for all $i = 1, 2, \ldots j - 1$, we check the case $i = j$

$$\text{Tr}_{R(2j)} \rho_R(c^{(2j)}) = \eta^{-1} \mu \rho_R(c^{(2j-2)} \rho_R) \left( \text{Tr}_{R(2j)} K_{2j-1} \right) \rho_R((K_{2j-2}K_{2j-3} \ldots K_{j+1})(K_{2j-2} \ldots K_j))$$

$$= \eta^{-1} \mu \rho_R(c^{(2j-2)} \rho_R) \left( \text{Tr}_{R(2j)} K_{2j-1} \right) \rho_R((K_{2j-2}K_{2j-3} \ldots K_{j+1})(K_{2j-2} \ldots K_j))$$

$$= \eta^{-1} \mu \rho_R(c^{(2j-2)} \rho_R) \left( \text{Tr}_{R(2j)} K_{2j-1} \right) \rho_R((K_{2j-2}K_{2j-3} \ldots K_{j+1})(K_{2j-2} \ldots K_j))$$

$$= \eta^{-1} \mu \rho_R(c^{(2j-2)} \rho_R) \left( \text{Tr}_{R(2j)} K_{2j-1} \right) \rho_R((K_{2j-2}K_{2j-3} \ldots K_{j+1})(K_{2j-2} \ldots K_j))$$

$$= \eta^{-1} \mu I_1 \rho_R(c^{(2j-2)} \rho_R) \left( \text{Tr}_{R(2j)} K_{2j-1} \right) \rho_R((K_{2j-2}K_{2j-3} \ldots K_{j+1})(K_{2j-2} \ldots K_j)).$$

Here in the first line we substituted the expression (2.2.20) for $2i$-th order contractors; in the second line we used eq.(3.3.2); in the third line we applied repeatedly eq.(2.2.16) for $\kappa$’s (they are quadratic

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polynomials in $\sigma$’s); in the last line we used eq.(2.1.8) several times. Then, noticing that $\kappa_i$ divides (from both left and right sides) $c^{(2j)}$, we complete the transformation.

The relation (3.5.2) follows by a repeated application of eq.(3.5.1).

To calculate the rank of the operators $\rho_R(c^{(2i)})$, we notice that by eqs.(2.2.12) and (2.2.15) one can rewrite the formula (2.2.12) for the contractors in a form

$$c^{(2i)} = c^{(2i-2)\uparrow 1} \left( \prod_{j=1}^{i} \kappa_{2j-1} \right) c^{(2i-2)\uparrow 1}. \quad (3.5.3)$$

By the rank-one property of operators $K_i \in \text{End}(V^{\otimes 2})$, a composite operator $\rho_R(\prod_{j=1}^{i} \kappa_{2j-1}) = \prod_{j=1}^{i} K_{2j-1}$ also has rank one. Hence, the operator $\rho_R(c^{(2i)})$ is either of rank-one or identically vanishes. The latter possibility contradicts eq.(3.5.2).

We next describe specific properties of the rank-one projectors.

**Lemma 3.16** Let an $R$-matrix $R$ be of either skew invertible BMW-type or $O(k)$-type. Then, respectively,

$$\left( \prod_{j=1}^{2i} D_{Rj} \right) \rho_R(c^{(2i)}) = \mu^{2i} \rho_R(c^{(2i)}) \quad (3.5.4)$$

in the BMW case and

$$\left( \prod_{j=1}^{k} D_{Rj} \right) \rho_R(a^{(k)}) = q^{k(1-k)} \rho_R(a^{(k)}) \quad (3.5.5)$$

in the $O(k)$ case.

Let additionally $F$ be a strict skew invertible $R$-matrix and assume that $\{R, F\}$ is a compatible pair. Then one has, respectively,

$$\left( \prod_{j=1}^{2i} D_{R_fj} \right) \rho_R(c^{(2i)}) = \mu^{2i} \rho_R(c^{(2i)}) ; \quad (3.5.6)$$

in the BMW case and

$$\left( \prod_{j=1}^{k} D_{R_fj} \right) \rho_R(a^{(k)}) = q^{k(1-k)} \rho_R(a^{(k)}) \quad (3.5.7)$$

in the $O(k)$ case.

**Proof.** To prove the equality (3.5.4), take the expression (3.5.3) for the $2i$-th order contractor, change the order of commuting (by eq.(3.3.6)) operators $\rho_R(c^{(2i-2)\uparrow 1})$ and $\prod_{j=1}^{2i} D_{Rj}$, and evaluate the factor $\prod_{j=1}^{2i} D_{Rj}$ on $\rho_R(\prod_{j=1}^{i} \kappa_{2j-1}) = \prod_{j=1}^{i} K_{2j-1}$ using the relation (3.3.5).

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The idempotency of \( \rho \), its commutativity with \( \prod_{j=1}^{k} D_{R_j} \) and its rank-one property were taken into account in the first line; eqs. (3.4.4)–(3.4.5) were used for the evaluation of the \( R \)-traces in (3.5.4) and (3.5.5) are satisfied for \( \rho \).

Here we used the twist relation for the pair \( \rho \).

The conditions of the second part of the proposition guarantee that the twisted \( R \)-matrix \( R_f = F^{-1}RF \) is of the same type as \( R \) and is skew invertible (see the lemma 3.6b). Hence, the relations (3.5.4) and (3.5.5) are satisfied for \( R_f \) as well. Now, to prove the equalities (3.5.6) and (3.5.7), it is enough to demonstrate that the two operators \( \rho_{R_f}(c^{(2i)}) \) and \( \rho_{R_f}(c^{(2i)}) \) (respectively, \( \rho_{R_f}(a^{(k)}) \) and \( \rho_{R_f}(a^{(k)}) \)) are related by a similarity transformation, which commutes with \( \prod_{j=1}^{k} D_{R_{f_j}} \) (respectively, \( \prod_{j=1}^{k} D_{R_{f_j}} \)).

Define a set of operators \( Z^{(i)} \in \text{Aut}(V^\otimes i), i = 1, 2, \ldots, \) by an iteration

\[
Z^{(1)} := I, \quad Z^{(2)} := F_{1}, \quad Z^{(i+1)} := (F_{1}F_{2}\ldots F_{i})Z^{(i)} = Z^{(i)}(F_{i}\ldots F_{2}F_{1})
\]

(two expressions for the element \( Z^{(i+1)} \) in eq. (3.5.8) are two different decompositions of the lift, to the braid group, of the longest element of the symmetric group).

By induction, one can readily prove relations

\[
R_{i}Z^{(k)} = Z^{(k)}R_{f(k-i)} \quad \forall i = 1, 2, \ldots, k - 1
\]

(compare with the formulas in eq. (2.2.19); they correspond to a particular case, when \( F = R \), of the relations (3.5.9)).

E.g., for \( i = 2, \ldots, k - 1 \), one has, by induction on \( k \),

\[
R_{i}Z^{(k)} = R_{i}F_{1}F_{2}\ldots F_{k-1}Z^{(k-1)} = F_{1}F_{2}\ldots F_{k-1}R_{i-1}Z^{(k-1)} = F_{1}F_{2}\ldots F_{k-1}Z^{(k-1)}R_{f(k-i)} = Z^{(k)}R_{f(k-i)}.
\]

Here we used the twist relation for the pair \( \{R, F\} \) and the first iterative definition of the element \( Z^{(k)} \) in eq. (3.5.8).

For \( i = 1 \), one has, again by induction on \( k \),

\[
R_{1}Z^{(k)} = R_{1}Z^{(k-1)}F_{k-1}\ldots F_{2}F_{1} = Z^{(k-1)}R_{f(k-2)}F_{k-1}\ldots F_{2}F_{1} = Z^{(k-1)}F_{k-1}\ldots F_{2}F_{1}R_{f(k-1)} = Z^{(k)}R_{f(k-1)}.
\]

Here we used the twist relation for the pair \( \{R_{f}, F\} \) and the second iterative definition of the element \( Z^{(k)} \) in eq. (3.5.8).
The relations eq. (3.5.9) imply following equalities
\begin{equation}
\rho_R(a^{(k)})Z^{(k)} = Z^{(k)}\rho_R(a^{(k)});
\rho_R(c^{(2i)})Z^{(2i)} = Z^{(2i)}\rho_R(c^{(2i)}) \quad \forall \ i = 1, 2, \ldots \tag{3.5.10}
\end{equation}

To derive these equalities, substitute two different expressions from eq. (2.2.6) for the antisymmetrizers in terms \(\rho_R(a^{(k)})\) and \(\rho_R(f^{(k)})\); for the contractors, the same expression (2.2.12) is used in both sides of eq. (3.5.10) since it is invariant with respect to the reflection \(\sigma_j \leftrightarrow \sigma_{i-j}\).

By eq. (3.2.8) (for \(X = Y = R_f\)), the operators \(Z^{(i)}\) and \(\prod_{j=1}^i D_{R_{ij}}\) commute and, hence, \(Z^{(2i)}\) (respectively, \(Z^{(k)}\)) realizes the similarity transformation we are looking for. \(\blacksquare\)

Due to the rank one property of the operator \(K\), there is an expression for the idempotents \(\rho_R(c^{(2i)})\), which is shorter than their original expression (2.2.12) and which fits well with the diagrammatic representation (see, e.g., [BW]) of the elements of the Birman-Murakami-Wenzl algebras.

**Lemma 3.17** Let \(E\) be the matrix defined by eq. (3.3.7). We have
\begin{equation}
\rho_R(c^{(2i)}) = \prod_{s=1}^j \left( \eta^{-1} (E_s)^{s-j} K_{s,2j+1-s} (E_s)^{j-s} \right) \tag{3.5.11}
\end{equation}

(\(the\ factors, \ corresponding\ to\ different\ values\ of\ \(s\)\ in\ the\ right\ hand\ side\ of\ eq.\ (3.5.11),\ live\ in\ different\ spaces,\ they\ thus\ commute,\ so\ we\ don't\ need\ to\ specify\ the\ order\ of\ the\ product\)).

**Proof.** An identity
\begin{equation}
K_{12}K_{23} = E_3 K_{12}P_{12}P_{13} \tag{3.5.12}
\end{equation}
follows from the rank one property of the operator \(K\) (written explicitly, with indices, the relation (3.5.12) becomes evident; we have, similarly, \(K_{12}K_{31} = E_3^{-1} K_{12}P_{23}P_{13}\), \(K_{13}K_{23} = \mu^{-1} D_{R_2} K_{13}P_{12}\) and \(K_{12}K_{13} = \mu^{-1} C_{R_3} K_{12}P_{23}\)).

An identity
\begin{equation}
K_{23}K_{14}P_{12}P_{34} = K_{23}K_{14} \tag{3.5.13}
\end{equation}
is again a consequence of the rank one property of the operator \(K\).

Next, we have
\begin{equation}
K_{12}E_1E_2 = E_1E_2K_{12} = K_{12} \tag{3.5.14}
\end{equation}
To verify, for instance, that \(K_{12}E_1^{-1}E_2^{-1} = K_{12}\), use the definition (3.3.7) of the matrix \(E_2^{-1}\), \(E_2^{-1} = Tr(3)(K_{23}P_{23})\), and then the relation (3.5.12) to remove the trace.

The proof of the lemma is based on a following calculation
\begin{equation}
K_{23}E_2^m K_{12}K_{34}E_2^{-m}K_{23} = K_{23}K_{34}E_2^m K_{12}E_1^m K_{23}
= E_4 K_{23}P_{23}P_{24}E_2^m E_{12} P_{12} P_{13} E_1^m = E_4^{m+1} K_{23}K_{14}P_{23}P_{24}P_{12}P_{13}E_1^{m+1}
= E_4^{m+1} K_{23}K_{14}P_{12}P_{34}E_1^{m+1} = E_4^{m+1} K_{23}K_{14}E_1^{m+1} = K_{23} \left( E_1^{-(m+1)} K_{14}E_1^{m+1} \right) \tag{3.5.15}
\end{equation}
Here in the first equality we moved \(K_{34}\) leftwards to \(K_{23}\) and replaced \(K_{12}E_2^{-m}\) by \(K_{12}E_1^m\) by eq.(3.5.14); in the second equality we moved \(E_1^m\) to the right and used eq.(3.5.12) to rewrite products.
$K_{23}K_{34}$ and $K_{12}K_{23};$ in the third equality we collected together all the permutation matrices as well as the powers of $E_4$ and $E_1;$ in the fourth equality we replaced $P_{23}P_{24}P_{12}P_{13}$ by $P_{12}P_{34};$ in the fifth equality we used eq.(3.5.13); in the sixth equality we moved $E_4^{m+1}$ to $K_{14}$ and replaced $E_4^{m+1}K_{14}$ by $E_1^{-(m+1)}K_{14}.$

Now we prove eq.(3.5.11) by induction on $j$ (the case when $j = 1$ is just the definition of the element $c^{(2)}$).

Denote by $U[j, s]$ the $s$-th factor in the product in the left hand side of eq.(3.5.11), $U[j, s] = \eta^{-1} E_{s}^{j-s} K_{s, 2j+1-s} E_{s}^{j-s}$. Assume that $\rho_R(c^{(2j)}) = \prod_{s=1}^{j} U[j, s]$ holds. By the recursive definition (2.2.12),

$$\rho_R(c^{(2j+2)}) = \left( \prod_{s=1}^{j+1} (U[j, s])^{\uparrow 1} \right) K_{12}K_{2j+1, 2j+2} \left( \prod_{s=1}^{j} (U[j, s])^{\uparrow 1} \right).$$ (3.5.16)

Each factor $(U[j, s])^{\uparrow 1}$ is a projector, the factors $(U[j, s])^{\uparrow 1}$ pairwise commute and there is only one factor, namely $(U[j, 1])^{\uparrow 1}$, in each product in the right hand side of eq.(3.5.16), which does not commute with the operator $K_{12}K_{2j+1, 2j+2}$. We have $U[j+1, s] = (U[j, s])^{\uparrow 1}$ thus the expression (3.5.16) reduces to

$$\rho_R(c^{(2j+2)}) = \left( \prod_{s=3}^{j+1} U[j+1, s] \right) U[j+1, 2] K_{12}K_{2j+1, 2j+2} U[j+1, 2].$$ (3.5.17)

Now use the calculation (3.5.15) (with the needed relabeling) to rewrite the underlined expression $X[j] = U[j+1, 2] K_{12}K_{2j+1, 2j+2} U[j+1, 2]$ in the right hand side of eq.(3.5.17):

$$X[j] = \eta^{-2}E_2^{1-j} \left( K_{2, 2j+1} E_2^{j-1} K_{12} K_{2j+1, 2j+2} E_2^{1-j} K_{2, 2j+1} \right) E_2^{j-1}
= \eta^{-2}E_2^{1-j} K_{2, 2j+1} \left( E_1^{j-} K_{1, 2j+2} E_1^{j} \right) E_2^{j-1} = U[j+1, 1] U[j+1, 2]$$ (3.5.18)

and to finish the proof. 

**Remark 3.18** The operator $K$ is skew invertible; we leave, as an exercise for the reader, to verify that $\Psi_{K_{12}} = E_1K_{12}E_1^{-1} = \mu^{-2}C_{R2}K_{21}C_{R2}$.

### 4 Quantum matrix algebra

In this section we deal with the main objects of our study, the quantum matrix algebras, and construct the $*$-product for them. We mainly discuss the quantum matrix algebras of the type BMW (and of the subtypes $O$ and $Sp$).

#### 4.1 Definition

Consider a linear space Mat$_N(W)$, introduced in the definition 3.1. For a fixed element $F \in \text{Aut}(V \otimes V)$, we consider series of "copies" $M^i$, $i = 1, 2, \ldots, n,$ of a matrix $M \in \text{Mat}_N(W)$. They are defined recursively by

$$M^i := M_1, \quad M^i := F_{i-1}M_{i-1}F_{i-1}^{-1}.$$ (4.1.1)
For $F = P$, these are usual copies, $M_i = M_i$, but, in general, $M_i$ can be nontrivial in all the spaces $1, \ldots, i$.

We shall, slightly abusing notation, denote by the same symbol $M_i$ an element in $\text{Mat}_N(W)^{\otimes k}$ for any $k \geq i$, which is defined by an inclusion of the spaces

$$\text{Mat}_N(W)^{\otimes j} \rightarrow \text{Mat}_N(W)^{\otimes (j+1)} : \text{Mat}_N(W)^{\otimes j} \ni X \mapsto X \otimes I \in \text{Mat}_N(W)^{\otimes (j+1)}.$$  

(4.1.2)

From now on we specify $W = \mathbb{C}\langle 1, M_{ab}^b \rangle$, $1 \leq a, b \leq n$, — an associative $\mathbb{C}$-algebra freely generated by the unity and by $n^2$ elements $M_{ab}^b$.

**Definition 4.1** Let $\{R, F\}$ be a compatible pair of strict skew invertible $R$-matrices (see the section 3.1). A quantum matrix algebra $\mathcal{M}(R, F)$ is a quotient algebra of the algebra $\mathbb{C}\langle M_i^j \rangle$ by a two-sided ideal generated by entries of the matrix relation

$$R_i M_i M_j = M_i M_j R_i,$$  

(4.1.3)

where $M = \|M_{ab}^b\|_{a,b=1}^N$ is a matrix of the generators of the algebra $\mathcal{M}(R, F)$ and the matrix copies $M_i$ are constructed with the help of the $R$-matrix $F$ as in eq. (4.1.1).

If $R$ is a BMW-type $R$-matrix (see (3.1.8)-(3.1.10)) then $\mathcal{M}(R, F)$ is called a BMW-type quantum matrix algebra.

If $R$ is a $Sp(2k)$-type, respectively, an $O(k)$-type $R$-matrix (see the definition 3.12) then $\mathcal{M}(R, F)$ is called a $Sp(2k)$-type, respectively, an $O(k)$-type quantum matrix algebra.

**Remark 4.2** The quantum matrix algebras were introduced in Ref. [HI] under the name "quantized braided groups". In the context of the present paper they have been first investigated in [IOP1]. The matrix $M'$ of the generators of the algebra $\mathcal{M}(R, F)$ used in [IOP1] is different from the matrix $M$ that we use here. A relation between these two matrices is explained in the section 3 of [IOP2]:

$$M' = D_R M (D_F)^{-1}.$$  

**Lemma 4.3** [IOP1] The matrix copies of the matrix $M = \|M_{ab}^b\|_{a,b=1}^N$ of the generators of the algebra $\mathcal{M}(R, F)$ satisfy relations

$$F_i M_i = M_i F_i \quad \text{for } j \neq i, i + 1,$$  

(4.1.4)

$$R_i M_i = M_i R_i \quad \text{for } j \neq i, i + 1,$$  

(4.1.5)

$$R_j M_j M_{j+1} = M_j M_{j+1} R_j \quad \text{for } j = 1, 2, \ldots.$$  

(4.1.6)

4.2 Characteristic subalgebra

From now on we assume that $M$ is the matrix of generators of the quantum matrix algebra $\mathcal{M}(R, F)$ and its copies $M_i$ are calculated by the rule (4.1.1).

Denote by $\mathcal{C}(R, F)$ a vector subspace of the quantum matrix algebra $\mathcal{M}(R, F)$ linearly spanned by the unity and elements

$$\text{ch}(\alpha^{(n)}) := \text{Tr}_{R(1, \ldots, n)} (M_{1} \ldots M_{2} \rho_R(\alpha^{(n)})), \quad n = 1, 2, \ldots,$$  

(4.2.1)
where \( \alpha^{(n)} \) is an arbitrary element of the group algebra \( \mathbb{C}B_n \) of the braid group \( B_n \) (we put, by definition, \( B_1 := \{1\} \)).

Notice that elements of the space \( C(R, F) \) satisfy a cyclic property

\[
ch(\alpha^{(n)} \beta^{(n)}) = ch(\beta^{(n)} \alpha^{(n)}) \quad \forall \alpha^{(n)}, \beta^{(n)} \in \mathbb{C}B_n, \quad n = 1, 2, \ldots ,
\]

which is a direct consequence of the relations (4.1.5), (4.1.6) and (3.3.6) and the cyclic property of the trace.

**Definition-Proposition 4.4 [IOP1]** The space \( C(R, F) \) is a commutative subalgebra of the quantum matrix algebra \( \mathcal{M}(R, F) \), the multiplication rule is

\[
ch(\alpha^{(n)}) ch(\beta^{(i)}) = ch(\alpha^{(n)} \beta^{(i)}) = ch(\alpha^{(n)} \beta^{(i)}).
\]

Recall that \( \alpha^{(n)} \beta^{(i)} \) denotes the image of an element \( \alpha^{(n)} \) under the embedding \( B_n \hookrightarrow B_{n+i} \) defined in (2.1.10). We shall call \( C(R, F) \) the characteristic subalgebra of \( \mathcal{M}(R, F) \).

A proof of the proposition given in [IOP1] is based in particular on the following lemma:

**Lemma 4.5 [IOP1]** Consider an arbitrary element \( \alpha^{(n)} \) of the braid group \( B_n \). Let \( \{R,F\} \) be a compatible pair of R-matrices, where \( R \) is skew invertible. Then relations

\[
\operatorname{Tr}_{R(i+1,\ldots,i+n)}(M_{i+1}^{-1} \cdots M_{i+n}^{-1} \rho_R(\alpha^{(n)} \beta^{(i)})) = I_{1,2,\ldots,i} ch(\alpha^{(n)})
\]

hold for any matrix \( M \in \text{Mat}_N(W)^8 \).

We will make use of the lemma 4.5 several times below.

Let us introduce a shorthand notation for certain elements of \( C(R, F) \)

\[
p_0 := \operatorname{Tr}_R I (= \mu \eta \text{ in the BMW case}), \quad p_1 := \operatorname{Tr}_R M, \quad p_i := ch(\sigma_{i-1} \ldots \sigma_2 \sigma_1) = ch(\sigma_1 \sigma_2 \ldots \sigma_{i-1}), \quad i = 2, 3, \ldots .
\]

(the last equality in eq.(4.2.6) is due to the inner automorphism (2.2.19) and the cyclic property (4.2.2)).

The elements \( p_i \) are called *traces of powers of \( M \)* or, shortly, *power sums*.

From now on in this subsection we assume the R-matrix \( R \) and, hence, the algebra \( \mathcal{M}(R, F) \) to be of the BMW-type. Denote

\[
g := ch(e(2)) \equiv \eta^{-1}ch(\kappa_1) \equiv \eta^{-1} \operatorname{Tr}_R(1, 2) (M_T K K_1).
\]

The notation used here was introduced in eqs.(2.1.3), (2.1.8), (2.2.12) and (3.1.9). We call \( g \) a *contraction of two matrices \( M \)* or, simply, a *2-contraction*.

---

8Here there is no need to specify \( M \) to be the matrix of the generators of the algebra \( \mathcal{M}(R, F) \).
Lemma 4.6 Let $M$ be the matrix of generators of the BMW-type quantum matrix algebra $\mathcal{M}(R, F)$. Then its copies, defined in eq.(4.1.1), fulfill relations

$$K_n M_{\pi} M_{n+1}^{-\pi} = M_{\pi} M_{n+1}^{-\pi} K_n = \mu^{-2} K_n g \quad \forall \ n \geq 1.$$  \hspace{1cm} (4.2.8)

Proof. We employ induction on $n$. Due to the property $\text{rk} K = 1$, one has

$$K_1 M_{\pi} M_{2}^{-\pi} = M_{\pi} M_{2}^{-\pi} K_1 = K_1 t,$$  \hspace{1cm} (4.2.9)

where $t \in \mathcal{M}(R, F)$ is a scalar. Evaluating the R-trace of eq.(4.2.9) in the spaces 1 and 2 and using eqs.(3.3.2) and (3.3.3), one finds $t = \mu^{-2} g$, which proves the relation (4.2.8) in the case $i = 1$. It remains to check an induction step $n \to (n + 1)$:

$$K_{n+1} M_{n+1} M_{n+2}^{-\pi} = K_{n+1} (F_n M_{n+1}^{-1} F_{n+1}^{-1} M_{n+2}^{-\pi}) = K_{n+1} F_n M_{n+1}^{-1} F_{n+1}^{-1} F_n^{-1} = K_{n+1} F_n F_{n+1}^{-1} K_{n+1} F_{n+1}^{-1} F_n^{-1} = \mu^{-2} F_n F_{n+1}^{-1} K_{n+1} F_{n+1}^{-1} F_n^{-1} g = \mu^{-2} K_{n+1} g.$$  \hspace{1cm}

Here eqs.(4.1.1) and (4.1.4), the twist relation (3.1.11) for the pair $\{K, F\}$ and the induction assumption were used for the transformation.

Proposition 4.7 Let $\mathcal{M}(R, F)$ be the quantum matrix algebra of the BMW-type. Its characteristic subalgebra $\mathcal{C}(R, F)$ is generated by the set $\{g, p_i\}_{i \geq 0}$.

Proof. Consider the chain of the BMW algebras monomorphisms (2.1.9)–(2.1.10). We adapt, for $n \geq 3$, a following presentation for an element $\alpha^{(n)} \in W_n$

$$\alpha^{(n)} = \beta \sigma_1 \beta' + \gamma \kappa_1 \gamma' + \delta,$$  \hspace{1cm} (4.2.10)

where $\beta, \beta', \gamma, \gamma', \delta \in \text{Im}(W_{n-1}) \subset W_n$. For $n = 3$, the formula (4.2.10) follows from the relations (2.1.1)–(2.1.6). For $n > 3$, it can be proved by induction on $n$.

Using the expression (4.2.10) for $\alpha^{(n)}$ and the cyclic property (4.2.2), we conclude that, in the BMW case, any element (4.2.1) of the characteristic subalgebra can be expressed as a linear combination of terms

$$ch(\alpha_1 \alpha_2 \ldots \alpha_{n-1}), \quad \text{where} \quad \alpha_i \in \{1, \sigma_i, \kappa_i\}.$$  \hspace{1cm} (4.2.11)

Let us analyze the expressions (4.2.11) for different choices of $\alpha_i$.

i) If $\alpha_i = 1$ for some value of $i$, then, applying the relation (4.2.4), we get

$$ch(\alpha_1 \ldots \alpha_{i-1} \alpha_{i+1} \ldots \alpha_{n-1}) = ch(\alpha_1 \ldots \alpha_{i-1}) ch((\alpha_{i+1} \ldots \alpha_{n-1})^{\dagger}),$$  \hspace{1cm} (4.2.12)

where $(\alpha_{i+1} \ldots \alpha_{n-1})^{\dagger} \in W_{n-i}$ is the preimage of $(\alpha_{i+1} \ldots \alpha_{n-1}) \in W_n$.

ii) In the case when $\alpha_{n-1} = \kappa_{n-1}$, we apply eq.(4.2.8) and then eqs.(3.1.13), (3.3.2) or (3.3.3) to reduce the expression (4.2.11) to

$$ch(\alpha_1 \ldots \alpha_{n-2} \kappa_{n-1}) = f(\alpha_{n-2}) ch(\alpha_1 \ldots \alpha_{n-3}) g,$$  \hspace{1cm} (4.2.13)
where \( f(\sigma_{n-2}) = \mu^{-1}, f(\kappa_{n-2}) = 1 \) and \( f(1) = \eta \).

iii) In the case when \( \alpha_i = \kappa_i \) for some \( i \), and \( \alpha_j = \sigma_j \) for all \( j = i + 1, \ldots, n - 1 \), we perform following transformations

\[
\begin{align*}
ch(\alpha_1 \ldots \alpha_{i-1}\kappa_i\sigma_{i+1}\sigma_{i+2} \ldots \sigma_{n-1}) &= ch(\alpha_1 \ldots \alpha_{i-2}\sigma_{i}^{-1}\alpha_{i-1}\kappa_i\kappa_{i+1}\sigma_{i+2} \ldots \sigma_{n-1}) \\
&= \ldots = ch(\alpha_1 \ldots \alpha_{i-2}(\sigma_{i-1}^{-1}\sigma_{i}^{-1})\alpha_{i-1}\kappa_i\kappa_{i+1} \ldots \kappa_{n-1}).
\end{align*}
\]

(4.2.14)

Here the relations (2.1.7) and the cyclic property (4.2.2) are repeatedly used; expressions suffering a transformation are underlined.

Now, depending on a value of \( \alpha_{i-1} \), we proceed in different ways. If \( \alpha_{i-1} = \kappa_{i-1} \) then by eqs.(2.1.7) and (4.2.13) we have

\[
\begin{align*}
(4.2.14) &= ch(\alpha_1 \ldots \alpha_{i-2}\sigma_{i-1}\sigma_i \ldots \sigma_{n-3}\kappa_{n-2}\kappa_{n-1}) \\
&= ch(\alpha_1 \ldots \alpha_{i-2}\sigma_{i-1}\sigma_i \ldots \sigma_{n-3}) g.
\end{align*}
\]

If \( \alpha_{i-1} = \sigma_{i-1} = \sigma_{i-1}^{-1} + (q - q^{-1})(1 - \kappa_{i-1}) \) then, using the relations \( \sigma_{i-1}^{-1}\sigma_{i-1}^{-1}\kappa_i = \kappa_{i-1}\kappa_i \) and applying the previous results (4.2.13) and (4.2.12), we obtain

\[
\begin{align*}
(4.2.14) &= ch(\alpha_1 \ldots \alpha_{i-2}\kappa_{i-1}\sigma_i \ldots \sigma_{n-3}) g \\
&+ (q - q^{-1})\mu^{-1}ch(\alpha_1 \ldots \alpha_{i-2})p_{n-i-1}g \\
&- (q - q^{-1})ch(\alpha_1 \ldots \alpha_{i-2}\sigma_{i-1}\sigma_i \ldots \sigma_{n-3}) g.
\end{align*}
\]

(4.2.16)

Iterating transformations i)—iii) finitely many times, we eventually prove the assertion of the proposition.

We keep considering the BMW-type quantum matrix algebra \( \mathcal{M}(R, F) \) with the R-matrix \( R \) generating representations of the algebras \( \mathcal{W}_n(q, \mu), n = 1, 2, \ldots \). Assume that the antisymmetrizers \( a^{(i)} \) and symmetrizers \( s^{(i)} \) in these latter algebras are consistently defined (see eqs.(2.2.6), (2.2.7) and (2.2.8)). In this case, we can introduce two following sets of elements in the characteristic subalgebra \( \mathcal{C}(R, F) \)

\[
\begin{align*}
a_0 &:= 1 \quad \text{and} \quad s_0 := 1; \\
\alpha_i &:= ch(a^{(i)}) \quad \text{and} \quad s_i := ch(s^{(i)}), \quad i = 1, 2, \ldots.
\end{align*}
\]

(4.2.17)

(4.2.18)

**Proposition 4.8** Let \( \mathcal{M}(R, F) \) be the quantum matrix algebra of the BMW-type. Assume that \( j_q \neq 0, \mu \neq -q^{-2j+3} \) (respectively, \( j_q \neq 0, \mu \neq q^{2j-3} \)) for all \( j = 2, 3, \ldots \). Then the characteristic subalgebra \( \mathcal{C}(R, F) \) is generated by the set \{\( g, a_i \}_{i \geq 0} \) (respectively, \{\( g, s_i \}_{i \geq 0} \)).

Let the quantum matrix algebra \( \mathcal{M}(R, F) \) be of the types either \( Sp(2k) \) or \( O(k) \) (this implies restrictions on \( q \): \( j_q \neq 0 \) for all \( j = 2, 3, \ldots, k \)). Then the characteristic subalgebra \( \mathcal{C}(R, F) \) is generated by the set \{\( g, a_i \}_{i=0}^k \).

**Proof.** These statements are byproducts of the previous proposition and the Newton relations, which are proved in the section 6, the theorem 6.1 (the proof of the theorem relies on the basic identities from the lemma 5.1).
4.3 Reciprocal relations in $\mathcal{C}(R, F)$ in orthogonal case

For the orthogonal $O(k)$-type quantum matrix algebras, the rank-one condition on the operator $\rho_R(a^{(k)}) \in \text{End}(V^\otimes k)$ gives rise to algebraic dependencies among $a_i$ and the 2-contraction $g$. In this subsection we construct explicitly a family of equalities — we call them reciprocal relations — for the set of generators of the characteristic subalgebra.

**Theorem 4.9** Let the quantum matrix algebra $\mathcal{M}(R, F)$ be of the orthogonal $O(k)$-type. Then following reciprocal relations for the generators of its characteristic subalgebra $\{g, a_i\}_{i=0}^k$ (see the proposition 4.8)

\[ g^{k-i} a_i = a_k a_{k-i} \quad \forall \, i = 0, 1, \ldots, k \quad (4.3.1) \]

are satisfied.

**Proof.** For the proof, we use two auxiliary statements.

**Lemma 4.10** Let the quantum matrix algebra $\mathcal{M}(R, F)$ be of the BMW-type, respectively, of the $O(k)$-type. Then we have, respectively,

\[ M_1 M_2 \ldots M_k \rho_R(c^{(2i)}) = (\mu^{-i} g) \rho_R(c^{(2i)}) \quad (4.3.2) \]

in the BMW case and

\[ M_1 M_2 \ldots M_k \rho_R(a^{(k)}) = q^{k(k-1)} a_k \rho_R(a^{(k)}) \quad (4.3.3) \]

in the $O(k)$ case.

**Proof.** The relations (4.3.2) and (4.3.3) are proved in exactly the same way as eqs.(3.5.4) and (3.5.5) of the lemma 3.16. One has to use additionally a relation (4.2.8) for the proof of eq.(4.3.2). For eq.(4.3.3), an equality

\[ \text{Tr}(1, 2, \ldots, k)(M_1 M_2 \ldots M_k \rho_R(a^{(k)})) = q^{k(k-1)} \text{Tr}(1, 2, \ldots, k)(M_1 M_2 \ldots M_k \rho_R(a^{(k)})) = q^{k(k-1)} a_k, \]

following from eq.(3.5.5), also should be taken into account. ■

**Lemma 4.11** Let the operators $Z^{(i)} \in \text{Aut}(V^\otimes i)$ be defined as in the formulas (3.5.8). For a given matrix $M \in \text{Mat}_N(W)$, consider one more set of its “copies” defined as (c.f. with eq.(4.1.1))

\[ M_1 := M_1, \quad M_{i+1} := F_i^{-1} M_1 F_i, \quad i = 2, 3, \ldots. \quad (4.3.4) \]

Then relations

\[ M_1 Z^{(i)} = Z^{(i)} M_{i-j+1} \quad (4.3.5) \]

hold for any $i = 1, 2, \ldots$ and for any $j = 1, 2, \ldots, i$. 

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Proof. The equalities (4.3.5) can be proved by induction. First, one considers the case $j = i$ and carries out induction on $i$. Then, performing induction on $(i-j)$, one proves eqs.(4.3.5) in a full generality.

Now, we will prove the relations (4.3.1) by expressing an element $\chi(c^{(2k-2i)}a^{(k)\uparrow k-i}) \in C(R,F)$ in terms of elementary generators in two different ways.

The first way is

$$
\chi(c^{(2k-2i)}a^{(k)\uparrow k-i}) = (\mu^{-2}g)^{k-i} \operatorname{Tr}_{R,1,2,k-i} \left( M_{\overline{2k-2i+1}} \cdots M_{\overline{2k-1}} \rho_R(c^{(2k-2i)}a^{(k)\uparrow k-i}) \right)
$$

$$
= (\mu^{-2}g)^{k-i} \operatorname{Tr}_{R,1,2,k-i} \left( Z^{(2k-i)} M_{\overline{2}} \cdots M_{\overline{2}} \rho_R(c^{(2k-2i)}a^{(k)}) (Z^{(2k-i)})^{-1} \right)
$$

$$
= (\mu^{-2}g)^{k-i} \operatorname{Tr}_{R,1,2,k-i} \left( \rho_R(c^{(2k-2i)}a^{(k)}) \right)
$$

$$
= (\eta^{-1}\mu^{-1}g)^{k-i} \operatorname{Tr}_{R,1,2,k-i} \left( (Z^{(i)})^{-1} M_{\overline{1}} \cdots M_{\overline{2}} \rho_R(a^{(i)}) Z^{(i)} \right)
$$

$$
= (\eta^{-1}\mu^{-1}g)^{k-i} \operatorname{Tr}_{R,1,2,k-i} \left( \prod_{j=1}^{k-i} \eta^{-1}\mu^{-1} \delta_{k-j+1} g \right)
$$

Here eq.(4.3.2) was applied in the first line; eqs.(4.3.5) and direct generalizations

$$
\rho_R(c^{(2j)}Z^{(j)}) = Z^{(j)} \rho_R(c^{(2j)\uparrow j-2i}) \quad \forall \ j \geq 2i \geq 0,
$$

$$
\rho_R(a^{(i)\uparrow j-i})Z^{(j)} = Z^{(j)} \rho_R(a^{(i)}) \quad \forall \ j \geq i \geq 0
$$

of eqs.(3.5.10) were used in the second line; the commutativity of $\prod_{j=1}^{2k-i} D_{Rj}$ with $Z^{(2k-i)}$ allows to cancel the latter when passing to third line; eqs.(3.5.4) and (3.5.6) were used to substitute the R-trace $\operatorname{Tr}_{R}$ by the R-trace $\operatorname{Tr}_{Rj}$ in the spaces with labels $i+1,i+2,\ldots,2k-i$ in the third line; eqs.(3.5.2) and (3.4.3) were applied for the evaluation of the R-traces in the fourth and fifth lines; a similarity transformation by $Z^{(i)}$ was performed in the argument of the R-trace and, then, the relations (4.3.5) and (3.5.10) were used to complete the transformation.

The second way is

$$
\chi(c^{(2k-2i)}a^{(k)\uparrow k-i}) = q^{k(k-1)} \operatorname{Tr}_{R,1,2,k-i} \left( M_{\overline{1}} \cdots M_{\overline{1}} \rho_R(a^{(k)\uparrow k-i}) \right) a_k
$$

$$
= q^{k(k-1)} \left( \prod_{j=k-i+1}^{k} \delta_j \right) \operatorname{Tr}_{R,1,2,k-i} \left( M_{\overline{1}} \cdots M_{\overline{1}} \rho_R(a^{(k)\uparrow k-i}) \right) a_k
$$

$$
= q^{k(k-1)} \left( \prod_{j=k-i+1}^{k} \delta_j \right) (\eta^{-1}\mu)^{k-i} \operatorname{Tr}_{R,1,2,k-i} \left( M_{\overline{1}} \cdots M_{\overline{1}} \rho_R(a^{(k)\uparrow k-i}) \right) a_k
$$

$$
= \left( \prod_{j=1}^{k-i} \eta^{-1}\mu^{-1} \delta_j^{-1} \right) a_{k-i} a_k.
$$

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Here (a version of) eq.(4.3.3) was used in the first line; eq.(3.4.3) was applied for the evaluation of the R-traces in the second line; there also, using eqs.(2.2.16) and (2.2.6), we substituted \( a^{(k-i)\tau_{k-i}} e^{(2k-2i)} \) by \( a^{(k-i)} e^{(2k-2i)} \) in the argument of \( \rho_R \); in the third line, some R-traces were evaluated with the help of eq.(3.5.2); the relations (3.4.4) and (3.4.5) were used to transform the expression to its final form in the fourth line.

Comparing the results of these two calculations and substituting the values, which \( \mu \) and \( \delta_j \) take in the \( O(k) \) case (see the definition 3.12 and eq.(3.4.3)), we verify eq.(4.3.1).

\[ \square \]

### 4.4 Matrix \( \star \)-product

Consider the quantum matrix algebra \( \mathcal{M}(R,F) \) of the generic type (no additional conditions on an R-matrix \( R \)).

Denote by \( \mathcal{P}(R,F) \) a linear subspace of \( \text{Mat}_N(\mathcal{M}(R,F)) \) spanned by \( \mathcal{C}(R,F) \)-multiples of the identity matrix, \( I ch \forall ch \in \mathcal{C}(R,F) \), and by elements

\[
M^1 := M, \quad (M^{\alpha(n)})_1 := \text{Tr}_{R(2,\ldots,n)}(M_T \ldots M_\pi \rho_R(\alpha^{(n)})), \quad n = 2,3,\ldots , \tag{4.4.1}
\]

where \( \alpha^{(n)} \) belongs to the group algebra of the braid group \( \mathcal{B}_n \). The space \( \mathcal{P}(R,F) \) inherits a structure of a right \( \mathcal{C}(R,F) \)-module

\[
M^{\alpha(n)} ch(\beta^{(i)}) = M^{(\alpha(n)\beta^{(i)}\tau_{\tau})} \quad \forall \alpha^{(n)} \in \mathcal{B}_n, \beta^{(i)} \in \mathcal{B}_i, \quad n, i = 1,2,\ldots , \tag{4.4.2}
\]

which is just a component-wise multiplication of the matrix \( M^{\alpha(n)} \) by \( ch(\beta^{(i)}) \) (use eq.(4.2.4) to check this). The \( \mathcal{C}(R,F) \)-module structure agrees with an R-trace map \( \text{Tr}_R \) (which means that \( \text{Tr}_R(Xa) = \text{Tr}_R(X)a \ \forall X \in \mathcal{P}(R,F) \) and \( \forall a \in \mathcal{C}(R,F) \))

\[
\mathcal{P}(R,F) \xrightarrow{\text{Tr}_R} \mathcal{C}(R,F) : \left\{ \begin{array}{c}
M^{\alpha(n)} \mapsto ch(\alpha^{(n)}), \\
I ch(\alpha^{(n)}) \mapsto (\text{Tr}_R I) ch(\alpha^{(n)}),
\end{array} \right. \tag{4.4.3}
\]

where \( \alpha^{(n)} \in \mathcal{B}_n, \quad n = 1,2,\ldots \)

Besides, elements of the space \( \mathcal{P}(R,F) \) satisfy a reduced cyclic property

\[
M^{(\alpha(n)\beta^{(n-1)}\tau_{\tau})} = M^{(\beta^{(n-1)}\tau_{\tau}\alpha^{(n)})} \quad \forall \alpha^{(n)} \in \mathcal{B}_n, \beta^{(n-1)} \in \mathcal{B}_{n-1}, \quad n = 2,3,\ldots . \tag{4.4.4}
\]

**Definition-Proposition 4.12** Formulas

\[
M^{\alpha(n)} \star M^{\beta(i)} := M^{(\alpha(n)\star \beta^{(i)})} , \tag{4.4.5}
\]

where

\[
\alpha^{(n)} \star \beta^{(i)} := \alpha^{(n)} \beta^{(i)} \tau_{\tau}(\sigma_n \ldots \sigma_2 \sigma_1 \sigma_2^{-1} \ldots \sigma_n^{-1}) , \tag{4.4.6}
\]

\[
(I ch(\beta^{(i)})) \star M^{\alpha(n)} := M^{\alpha(n)} \star (I ch(\beta^{(i)})) := M^{\alpha(n)} ch(\beta^{(i)}) , \tag{4.4.7}
\]

\[
(I ch(\alpha^{(i)})) \star (I ch(\beta^{(n)})) := I (ch(\alpha^{(i)}) ch(\beta^{(n)})) , \tag{4.4.8}
\]

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define an associative multiplication on the space \( \mathcal{P}(R, F) \), which agrees with the \( \mathcal{C}(R, F) \)-module structure (4.4.2).\(^9\)

**Proof.** To prove the associativity of the multiplication (4.4.5), it is enough to check

\[
(\alpha^{(n)} \star \beta^{(i)}) \star \gamma^{(m)} = \alpha^{(n)} \star (\beta^{(i)} \star \gamma^{(m)}),
\]

which is a straightforward exercise in an application of eqs. (2.1.1) and (2.1.2). It is less trivial to prove a compatibility condition for eqs. (4.4.5) and (4.4.7)

\[
\left\{ M^{\alpha^{(n)}} \star (I \text{ch}(\beta^{(i)})) \right\} \star M^{\gamma^{(m)}} = M^{\alpha^{(n)}} \star \left\{ (I \text{ch}(\beta^{(i)})) \star M^{\gamma^{(m)}} \right\},
\]

which, in terms of the matrix “exponents”, amounts to

\[
\alpha^{(n)} \beta^{(i)^{\gamma(n)} \gamma^{(m)^{\gamma(n)}} (\sigma_{i+n} \ldots \sigma_{2} \sigma_{1} \sigma_{2}^{-1} \ldots \sigma_{i+n}^{-1})}
\]

\[
\quad \quad \quad \quad \quad \mod (4.4.4) \equiv \alpha^{(n)} \gamma^{(n)} \beta^{(i)^{\gamma(n)} \gamma^{(n)}} (\sigma_{n} \ldots \sigma_{2} \sigma_{1} \sigma_{2}^{-1} \ldots \sigma_{n}^{-1}).
\]

Here the symbol \( \equiv \mod (4.4.4) \) means the equality modulo the reduced cyclic property (4.4.4).

To check eq. (4.4.9), we apply a technique, which was used in [IOP1] to prove the commutativity of the characteristic subalgebra. Consider an element

\[
\begin{align*}
\alpha^{(i+m)} u_{i,m} &:= (\sigma_{i} \ldots \sigma_{2} \sigma_{1}) (\sigma_{i+1} \ldots \sigma_{3} \sigma_{2}) \ldots (\sigma_{i+m-1} \ldots \sigma_{m+1} \sigma_{m}) \\
&= (\sigma_{i} \sigma_{i+1} \ldots \sigma_{i+m-1}) (\sigma_{i+1} \sigma_{i} \ldots \sigma_{i+m-2}) \ldots (\sigma_{i} \sigma_{i+1} \ldots \sigma_{m}),
\end{align*}
\]

(4.4.10)

which intertwines certain elements of the braid group \( \mathcal{B}_{(i+m)} \):

\[
\beta^{(i)} u_{i,m}^{(i+m)} = u_{i,m}^{(i+m)} \beta^{(i)^{\gamma(n)}}, \quad \gamma^{(m)^{\gamma(m)}} u_{i,m}^{(i+m)} = u_{i,m}^{(i+m)} \gamma^{(m)}. \quad (4.4.11)
\]

Substitute an expression \( u_{i,m}^{(i+m)^{\gamma(m)^{\gamma(m)^{\gamma(n)}} (i+m)}} \) for the factor \( (\beta^{(i)^{\gamma(n)} \gamma^{(m)^{\gamma(n)}}}) \) in the left hand side of the equation (4.4.9), move the element \( u_{i,m}^{(i+m)^{\gamma(n)}} \) cyclically to the right and then use an equality

\[
(\sigma_{1}^{-1} \sigma_{2}^{-1} \ldots \sigma_{i}^{-1} \sigma_{i} u_{i,m}^{(i+m)}) = u_{i,m-1}^{(i+m)} \quad (4.4.12)
\]

to cancel it on the right hand side. Such transformation results in the right hand side of the equation (4.4.9).

Consistency of the multiplication and the \( \mathcal{C}(R, F) \)-module structures on \( \mathcal{P}(R, F) \) follows obviously from the last equality in (4.4.7).

To illustrate the relation between the \( \star \)-product and the usual matrix multiplication, we present the formulas (4.4.5) and (4.4.6) in the case \( n = 1 \) (\( \alpha^{(1)} \equiv 1 \)) in a form

\[
M \star N = M \cdot \phi(N) \quad \forall N \in \mathcal{P}(R, F),
\]

(4.4.13)

---

\(^9\)In other words, a map \( \text{ch}(\alpha^{(n)}) \mapsto I \text{ch}(\alpha^{(n)}) \) is an algebra monomorphism \( \mathcal{C}(R, F) \hookrightarrow \mathcal{P}(R, F) \).
where "·" denotes the usual matrix multiplication and the map \( \phi \) is defined by eq.(3.3.18).

The noncommutative analogue of the matrix power is given by a repeated \( \star \)-multiplication by the matrix \( M \)

\[
M^\overline{0} := I, \quad M^\overline{n} := \underbrace{M \star M \star \ldots \star M}_{n \text{ times}} = M^{(\sigma_1 \sigma_2 \ldots \sigma_{n-1})} = M^{(\sigma_{n-1} \ldots \sigma_2 \sigma_1)}. \tag{4.4.14}
\]

Here we introduce symbol \( M^\overline{n} \) for the \( n \)-th power of the matrix \( M \). The standard matrix powers multiplication formula follows immediately from the definition

\[
M^\overline{n} \star M^\overline{i} = M^{\overline{n+i}}. \tag{4.4.15}
\]

**Proposition 4.13** A \( \mathcal{C}(R,F) \)-module, generated by the matrix powers \( M^\overline{n} \), \( n = 0,1,\ldots \), belongs to the center of the algebra \( \mathcal{P}(R,F) \).

**Proof.** It is sufficient to check a relation \( M \star M^{\alpha(i)} = M^{\alpha(i)} \star M \), which, in turn, follows from a calculation

\[
\alpha(i)\sigma_i \ldots \sigma_2 \sigma_1 \sigma_i^{-1} \ldots \sigma_i^{-1} = \sigma_i \ldots \sigma_2 \sigma_1 \sigma(i)^\dagger \sigma_2^{-1} \ldots \sigma_i^{-1} \mod (4.4.4) \alpha(i)^\dagger \sigma_1. \tag*{\blacksquare}
\]

It is natural to expect that the algebra \( \mathcal{P}(R,F) \) is commutative as all of its elements are generated by the matrix \( M \) alone. We can prove the commutativity in the BMW case. Notice that (unlike in the Hecke case), in the BMW case, the algebra \( \mathcal{P}(R,F) \) can not be generated by the \( \star \)-powers of \( M \) only.

By an analogy with the formula (4.4.13), we define a \( \mathcal{C}(R,F) \)-module map \( M^\dagger : \mathcal{P}(R,F) \to \mathcal{P}(R,F) \)

\[
M^\dagger(N) := M \cdot \xi(N), \quad N \in \mathcal{P}(R,F), \tag{4.4.16}
\]

where the endomorphism \( \xi \) is defined by eq.(3.3.19). Equivalently, we can write

\[
M^\dagger(M^{\alpha(n)}) = M^{(\alpha(n)^\dagger \sigma_1)} \quad \forall \alpha^{(n)} \in \mathcal{W}_n, \quad n = 1,2,\ldots \tag{4.4.17}
\]

**Proposition 4.14** Let the quantum matrix algebra \( \mathcal{M}(R,F) \) be of the BMW-type. Then the algebra \( \mathcal{P}(R,F) \) is commutative. As a \( \mathcal{C}(R,F) \)-module, it is spanned by matrices

\[
M^\overline{n} \quad \text{and} \quad M^\overline{n+2}, \quad n = 0,1,\ldots \tag{4.4.18}
\]

**Proof.** A proof of the last statement of the proposition goes essentially along the same lines as the proof of the proposition 4.7 and we will not repeat it. The only modification is a reduction of the cyclic property (c.f., eqs.(4.2.2) and (4.4.4)), which finally leads to an appearance of the additional elements \( \{M^\dagger(M^\overline{n})\}_{n \geq 2} \) in the generating set.

To prove the commutativity of \( \mathcal{P}(R,F) \), we derive an alternative expression for the exponent in the matrix product formula (4.4.5)

\[
\alpha^{(n)} \star \beta^{(i)} = (\sigma_i^{-1} \ldots \sigma_2^{-1} \sigma_1 \sigma_2 \ldots \sigma_i) \alpha^{(n)^\dagger} \beta^{(i)}. \tag{4.4.19}
\]
The calculation proceeds as follows

\[ \alpha^{(n)} \star \beta^{(i)} = \alpha^{(n)} \beta^{(i)} \tau_n (\sigma_n \cdots \sigma_1 \sigma_2^{-1} \cdots \sigma_n^{-1}) = u_{n,i}^{(n+i)} \alpha^{(n)} \tau_i \beta^{(i)} (u_{n,i}^{(n+i)})^{-1} (\sigma_n \cdots \sigma_1 \sigma_2^{-1} \cdots \sigma_n^{-1}) \]

\[ \text{mod}(4.4.4) \quad (u_{n,i-1}^{(n+i-1)} \tau_i^{-1} (\sigma_2^{-1} \cdots \sigma_n^{-1}) u_{n,i}^{(n+i)} \alpha^{(n)} \tau_i \beta^{(i)} = (u_{n,i-1}^{(n+i-1)} \tau_i^{-1} \tau_i \alpha^{(n)} \tau_i \beta^{(i)} \]

\[ = (\sigma_i^{-1} \cdots \sigma_2^{-1})(u_{n-1,i-1}^{(n+i-2)} \tau_2^{-1} \sigma_1 u_{n-1,i-1}^{(n+i-2)} \tau_2 \cdots \sigma_i \alpha^{(n)} \tau_i \beta^{(i)} = \text{right hand side of eq.}(4.4.19). \]

Here we applied again the intertwining operators \((4.4.10)\) and used their properties \((4.4.11)\) and \((4.4.12)\) and the reduced cyclic property. One more property

\[ u_{n,i}^{(n+i)} = u_{n-1,i}^{(n+i-1)} (\sigma_1 \sigma_2 \cdots \sigma_i) \quad (4.4.20) \]

is used in the last line of the calculation.

Due to the proposition 4.13, to prove the commutativity of the algebra \(\mathcal{P}(R,F)\), it remains to check the commutativity of the set \(\{MT(M^\tau)\}_{n \geq 2}\).

Notice that the factors of the exponents of the matrices \(MT(M^\tau)\) can be taken in an opposite order, \(MT(M^\tau) = M^{(\kappa_1 \kappa_2 \sigma_3 \cdots \sigma_n)} = M^{(\sigma_n \cdots \sigma_3 \kappa_2 \kappa_1)}\). This observation, together with the formula \((4.4.19)\), allows us to choose the exponents of two matrices \(MT(M^\tau) \star MT(M^\tau)\) and \(MT(M^\tau) \star MT(M^\tau)\) to be mirror (left-right) images of each other. Finally, the exponentiation of the matrix \(M\) with mirror symmetric arguments gives the identical results since they can be expanded into linear combinations of the generators \((4.4.18)\), which are invariant with respect to the mirror reflection of their exponents, and since the expansion rules (that is, the defining relations for the BMW algebras) are mirror symmetric as well.

**Lemma 4.15** For the BMW-type quantum matrix algebra \(\mathcal{M}(R,F)\), one has

\[ MT(I) = \mu M, \quad MT(M) = \mu^{-1} I g, \quad (4.4.21) \]

\[ MT(MN) = NG \quad \forall N \in \mathcal{P}(R,F). \quad (4.4.22) \]

**Proof.** The relations \((4.4.21)\) follow immediately from eqs.\((4.2.8)\) and \((3.3.2)\) and the definitions \((4.4.16)\) and \((3.3.19)\).

As for the equality \((4.4.22)\), it is enough to check it in the case when the matrix \(N\) is a power of the matrix \(M\).

To evaluate the expression \(MT(MTN) = M^{(\kappa_1 \kappa_2 \sigma_3 \cdots \sigma_{n+1})}\), we transform its exponent, using the relations \((2.1.7)\) in the BMW algebra and the reduced cyclic property, to

\[ \kappa_1 \kappa_2 \sigma_3 \cdots \sigma_{n+1} = \kappa_1 (\kappa_2 \sigma_3 \sigma_2^{-1}) \sigma_4 \cdots \sigma_{n+1} \quad \text{mod}(4.4.4) = (\sigma_2^{-1} \kappa_1 \kappa_2) \kappa_3 \sigma_4 \cdots \sigma_{n+1} \]

\[ = \sigma_1 \kappa_2 \kappa_3 \sigma_4 \cdots \sigma_{n+1} = \cdots \quad \text{mod}(4.4.4) = \sigma_1 \sigma_2 \cdots \sigma_{n-1} \kappa_n \kappa_{n+1}. \quad (4.4.23) \]

For the exponent \((4.4.23)\), the matrix power is easily calculated, again with the help of eqs.\((4.2.8)\) and \((3.3.2)\), and gives the expression \(MT^\tau g\).

The last relation in \((4.4.21)\) shows that to introduce the inverse matrix to the matrix \(M\) it is sufficient to add the inverse \(g^{-1}\) of the 2-contraction \(g\) to the algebra \(\mathcal{M}(R,F)\). This is realized in the next subsection.
4.5 Matrix inversion

In this subsection we define an extended quantum matrix algebra, to which the inverse of the quantum matrix belongs. Then we solve the reciprocal relations from the subsection 4.3.

**Lemma 4.16** Let $\mathcal{M}(R, F)$ be the BMW-type quantum matrix algebra. Its 2-contraction $g$ fulfills a relation

$$M g = g (G^{-1}MG), \quad (4.5.1)$$

where $G$ is defined by eq.(3.3.8).

**Proof.** The proof consists of a calculation

$$M_1 (g K_2) = \mu^2 M_1 M_2 M_3 K_2 = \mu^2 M_1 M_2 M_3 K_2 K_1 K_2 = \mu^2 K_2 (M_1 M_2 K_1) M_3 K_2$$

$$= g K_2 K_1 M_3 K_2 = (g K_2) \text{Tr}_{(2,3)} (K_2 K_1 M_3)$$

$$= (g K_2) \text{Tr}_{(2,3)} \left( K_2 F_2 F_1 K_2 M_1 F_1^{-1} F_2^{-1} \right)$$

$$= (g K_2) \text{Tr}_{(2,3)} (F_2 F_1 K_2) M_1 \text{Tr}_{(2,3)} (K_2 F_1^{-1} F_2^{-1}) = (g K_2) (G^{-1}MG)_1. \quad (4.5.2)$$

Here the relations (4.2.8) and (2.1.8) were used in the first two lines; the property $\text{rk}K = 1$ was used in the last/first equality of the second/fourth line; the definition of $M_3$ was substituted and the twist relation for the pair $\{K,F\}$ was used in the third line; the formulas (3.3.8) and (3.3.9) for $G$ and $G^{-1}$ were substituted in the last equality.

**Definition-Proposition 4.17** Let $\mathcal{M}(R, F)$ be the BMW-type quantum matrix algebra. Consider an extension of $\mathcal{M}(R, F)$ by a generator $g^{-1}$ subject to relations

$$g^{-1} g = g g^{-1} = 1, \quad g^{-1} M = (G^{-1}MG) g^{-1}. \quad (4.5.3)$$

The extended algebra, which we shall further denote by $\mathcal{M}^\ast(R, F)$, contains an inverse matrix to the matrix $M$

$$M^{-1} := \mu \xi(M) g^{-1} : \quad M \cdot M^{-1} = M^{-1} \cdot M = I. \quad (4.5.4)$$

**Proof.** The lemma 4.16 ensures the consistency of the relations (4.5.3). The equality $M \cdot M^{-1} = I$ for the inverse matrix (4.5.4) follows immediately from eqs.(4.4.21) and (4.4.16). To prove the equality $M^{-1} \cdot M = I$, consider a mirror partner of the map $\xi$:

$$\theta(M) := \mu^{-2} \text{Tr}_{R(2)} K_1 M_7. \quad (4.5.5)$$

By the (left-right) symmetry arguments in the assumptions of the lemma 3.10, the map $\theta$ is invertible and the inverse map reads

$$\theta^{-1}(M) = \text{Tr}_{R(2)} \left( F_1^{-1} K_1 M_1 F_1 \right). \quad (4.5.6)$$

Applying in a standard way the transformation formula (3.2.2), we calculate a composition of the maps $\xi$ and $\theta$,

$$\xi(\theta(M))_1 = \theta(\xi(M))_1 = \mu^{-2} \text{Tr}_{R(2,3)} K_2 K_1 M_7 = \text{Tr}_{(2,3)} K_2 K_1 M_7 = (G^{-1}MG)_1. \quad (4.5.7)$$
Here eq.(3.3.5) was used to substitute the R-traces by the usual traces; the last equality follows from a comparison of the second and the last lines in the calculation (4.5.2).

Now we observe that, in view of eqs.(4.2.8) and (3.3.2), a matrix \((-1)M := \mu g^{-1} \theta^{-1}(M)\) fulfills the relation \((-1)M \cdot M = I\). The identity \((-1)M = M^{-1}\) follows then from the relations (4.5.7) and (4.5.1).

**Remark 4.18** One can generalize the definitions of the characteristic subalgebra and of the matrix powers to the case of the extended quantum matrix algebra \(\mathcal{M}^\ell(R,F)\). Not going into details, we just mention that the extended characteristic subalgebra \(\mathcal{C}^\ell(R,F)\) is generated by the set \(\{g, g^{-1}, p_i \}_{i \geq 0}\) and the extended algebra \(\mathcal{P}^\ell(R,F)\), as a \(\mathcal{C}^\ell(R,F)\)-module, is spanned by matrices

\[
\begin{align*}
M^n & \quad \text{and} \quad M^n(M^n) \quad \forall n \in \mathbb{Z}.
\end{align*}
\]

Here inverse powers of \(M\) are defined through the repeated \(*\)-multiplication by \(M^{-1}\), which is given by

\[
M^{-n} := \underbrace{M^{-1} \ast \ldots \ast M^{-1}}_{\text{n times}} I = \text{Tr}_{R^{-1},(2,\ldots,n+1)} \left( M_2^{-1} M_3^{-1} \ldots M_{n+1}^{-1} \rho R^{-1}_{\ell}(\sigma_n \ldots \sigma_2 \sigma_1) \right);
\]

the copies \(M_i^{-1}\) of the matrix \(M^{-1}\) were introduced earlier in the lemma 4.11 (see eqs.(4.3.4)). Notice that in general \(M^{-1} = \phi^{-1}(M^{-1}) \neq M^{-1}\). Here are some particular examples of the multiplication by \(M^{-1}\)

\[
M^{-n} \ast M^i = M^{i-n}, \quad M^{-1} \ast M^{\alpha(n)+1} = \text{ch}(\alpha(n)) I.
\]

Let us employ the invertibility of the 2-contraction to solve the reciprocal relations derived in the subsection 4.3.

**Definition-Proposition 4.19** For the \(O(2\ell)\)-type extended quantum matrix algebra \(\mathcal{M}^\ell(R,F)\), its quotient algebra by a relation

\[
a_{2\ell} = +g^\ell \quad \text{or, respectively,} \quad a_{2\ell} = -g^\ell \quad (4.5.9)
\]

we call a component, which we shall denote by \(O^+(2\ell)\) or \(O^-(2\ell)\), respectively.

In a similar manner, the corresponding quotients of the extended algebra \(\mathcal{P}^\ell(R,F)\) we shall denote by \(\mathcal{P}^\ell(R,F)\) and the corresponding quotients of the extended characteristic subalgebra \(\mathcal{C}^\ell(R,F)\) — by \(\mathcal{C}^\ell(R,F)\).

The reciprocal relations (4.3.1) for the components \(O^\pm(2\ell)\) reduce, respectively, to

\[
a_{\ell+i} = \pm g^i a_{\ell-i} \quad \forall i = 0,1,\ldots,\ell, \quad (4.5.10)
\]

which, in the \(O^-(2\ell)\) case, implies \(a_{\ell} = 0\).
For the $O(2\ell - 1)$-type extended quantum matrix algebra $\mathcal{M}(R, F)$, which we further refer to as the $O^\bullet(2\ell - 1)$-type quantum matrix algebra, the reciprocal relations (4.3.1) are resolved in the following way
\[
a_{\ell+i} = g^{i+1/2} a_{\ell-1-i} \quad \forall \ i = 0, 1, \ldots, \ell - 1,
\]
where a notation
\[
g^{1/2} := g^{1-\ell} a_{2\ell-1} \quad \left( \text{so that } (g^{1/2})^2 = g \text{ and } g^{\ell-1/2} = a_{2\ell-1} \right)
\]
is used.

**Proof.** The relations (4.5.9) are the two factors of the reciprocal relation (4.3.1) in the case $k = 2\ell$ and $i = \ell$: $0 = g^{2\ell} - a^2_{2\ell} = (g^{\ell} + a_{2\ell}) (g^{\ell} - a_{2\ell})$.

A check of the proposition is straightforward.

5 Cayley-Hamilton theorem

In this section we derive, using auxiliary results from the subsection 5.1, the characteristic identities (the theorems 5.5, 5.7 and 5.9) for the quantum matrix algebras $\mathcal{M}(R, F)$ of the types $Sp(2k)$ and $O(k)$.

We begin by assuming that $\{R, F\}$ is a compatible pair of R-matrices, in which the operator $F$ is strict skew invertible and the operator $R$ is skew invertible of the BMW-type (and, hence, strict skew invertible). Specific $Sp(2k)$ and $O(k)$-type conditions are imposed in the subsections 5.2 and 5.3, 5.4, respectively.

Next, in the corollaries 5.6, 5.8 and 5.10, we parameterize the coefficients of the characteristic polynomials by means of a $\mathbb{C}$-algebra $\mathcal{E}_{2i}$ of polynomials in $2i + 1$ pairwise commuting variables $\nu_j$, $j = 0, 1, \ldots, 2i$, satisfying conditions
\[
\nu_{i+j} \nu_{i+1-j} = \nu_0^2 \quad \forall \ j = 1, 2, \ldots, i.
\]
We call $\nu_i, i = 0, 1, \ldots$, orthosymplectic spectral variables (below we shall be writing "spectral variables" for short, always assuming that the relations (5.0.1) are satisfied).

For the classical groups $Sp(2k)$, $O^+(2k)$, $O^-(2k + 2)$ and $O(2k + 1)$, the functions $a_i, i = 1, \ldots, k$ on the group manifolds are functionally independent. This justifies, at least perturbatively, the corresponding assumptions about the independence of the elements $a_i$ in the corollaries 5.6, 5.8 and 5.10.

5.1 Basic identities

Let the eigenvalues $q$ and $\mu$ of the R-matrix $R$ (i.e., the parameters of the BMW algebras, whose representations are generated by the matrix $R$) satisfy conditions $i_q \neq 0, \mu \neq -q^{3-2i} \forall i = 2, 3, \ldots, n$. Then the matrices $M^{a(i)}$ are well defined for $0 \leq i \leq n$. 
In this subsection we establish relations between “descendants” of the matrices \( M^{a(i)} \) in the algebra \( \mathcal{P}(R, F) \). These relations are used later in a derivation of the Cayley-Hamilton theorem and the Newton relations.

For \( 1 \leq i \leq n \) and \( m \geq 0 \), denote

\[
A^{(m,i)} := i_q M^{\overline{m}} \star M^{a(i)} , \quad B^{(m+1,i)} := i_q M^{\overline{m}} \star M \ell(M^{a(i)}) .
\]

(5.1.1)

It is suitable to define \( A^{m,i} \) and \( B^{m,i} \) for boundary values of their indices

\[
A^{(-1,i)} := i_q \phi^{-1} \left( \text{Tr}_{R(2,3,\ldots,i)} M^{a(i)} \right) , \quad B^{(0,i)} := i_q \phi^{-1}(\xi(M^{a(i)}))
\]

(5.1.2)

and

\[
A^{(m,0)} := 0 \quad \text{and} \quad B^{(m,0)} := 0 \quad \forall \ m \geq 0.
\]

(5.1.3)

Notice that although the elements \( A^{(-1,i)} \) and \( B^{(0,i)} \) do not, in general, belong to the algebra \( \mathcal{P}(R, F) \), their descendants \( A^{(-1,i)} g \) and \( B^{(0,i)} g \) do (see eqs. (5.1.4) and (5.1.5) in the case \( m = 0 \)).

In the case when the contraction \( g \) (and, hence, the matrix \( M \)) is invertible, the formulas (5.1.1), with \( m \) now an arbitrary integer, can be used to define descendants of \( M^{a(i)} \) in the extended algebra \( \mathcal{P}^*(R, F) \) (see the remark 4.18). In this case, the matrices \( A^{(-1,i)} \) and \( B^{(0,i)} \) are expressed uniformly:

\[
A^{(-1,i)} = i_q M^{-1} \star M^{a(i)} , \quad B^{(0,i)} = i_q M^{-1} \star M \ell(M^{a(i)}).
\]

Lemma 5.1 For \( 0 \leq i \leq n-1 \) and \( m \geq 0 \), the matrices \( A^{(m-1,i+1)} \) and \( B^{(m+1,i+1)} \) satisfy recurrent relations

\[
A^{(m-1,i+1)} = q^i M^{\overline{m}} a_i - A^{(m,i)} - \frac{\mu q^{2i-1}(q - q^{-1})}{1 + \mu q^{2i-1}} B^{(m,i)},
\]

(5.1.4)

\[
B^{(m+1,i+1)} = \left( \mu^{-1} q^{-i} M^{\overline{m}} a_i + \frac{q - q^{-1}}{1 + \mu q^{2i-1}} A^{(m,i)} - B^{(m,i)} \right) g.
\]

(5.1.5)

Proof. We prove eqs. (5.1.4) and (5.1.5) by induction on \( i \). Using the equalities (4.4.15) and (4.4.21), we find

\[
A^{(m-1,1)} = M^{\overline{m}}, \quad B^{(m+1,1)} = \mu^{-1} M^{\overline{m}} g.
\]

(5.1.6)

These formulas, in the setting (5.1.3), coincide with the formulas (5.1.4) and (5.1.5) for \( i = 0 \).

Let us check eqs. (5.1.4) and (5.1.5) for some fixed \( i > 0 \) assuming that they are satisfied for all smaller values of the index \( i \).

For \( A^{(m,i+1)} \) and \( m \geq 0 \), we calculate

\[
A^{(m,i+1)} = (i + 1)q M^{a(i+1)\tau m} = q^i M^{a(i)(m+1)\tau m}(q^{-2i}) a_{m+1} \sigma_m \ldots \sigma_2 \sigma_1
\]

\[
= q^i M^{\overline{m+1}} a_i - A^{(m+1,i)} - \frac{\mu q^{2i-1}(q - q^{-1})}{1 + \mu q^{2i-1}} B^{(m+1,i)}.
\]

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Here in the first line we used the second formula from (2.2.6) for \( a^{(i+1)t_m} \) and applied the reduced cyclic property (4.4.4) and eq.(2.2.13) to cancel one of two terms \( a^{(i)t_m} \). In the second line we substituted the formula (2.2.3) for the Baxterized elements \( \sigma_{m+1}(q^{-2k}) \) and applied eq.(4.2.4) to simplify the first term in the sum.

For \( A^{(-1,i+1)} \), the relations (5.1.4) are verified similarly

\[
A^{(-1,i+1)} = q^i \phi^{-1} \left( \text{Tr}_{R(2,3,\ldots i+1)} M \cdots M \rho_R \left( a^{(i)} \sigma_1^-(q^{-2i}) \right) \right)
\]

\[
= q^i \phi^{-1} (I) a_i - i q \phi^{-1} (\phi(M^{a(i)})) - \frac{\mu q^{2i-1}}{1 + \mu q^{1+i}} \phi^{-1} (\xi(M^{a(i)}))
\]

\[
= q^i I \ a_i - A^{(0,i)} - \frac{\mu q^{2i-1}}{1+q^{1+i}} B^{(0,i)}
\]

Here the definitions (3.3.18) and (3.3.19) of the endomorphisms \( \phi \) and \( \xi \) were additionally taken into account.

For the matrices \( B^{(m+1,i+1)} \), the calculation starts similarly to the case of the matrices \( A^{(m,i+1)} \), \( m \geq 0 \),

\[
B^{(m+1,i+1)} = (i+1) q M^{a^{(i+1)t_m+1} \kappa_{m+1} \sigma_1} = q^i M^{(a^{(i)}t_m+2) \sigma_{m+2}^{-1} \phi_{m+2}(q^{-2i})} \kappa_{m+1} \sigma_1
\]

\[
= q^{-i} M \sigma^\infty_1 M \phi(M) a_i - i q M^{(a^{(i)}t_{m+2} \sigma_{m+2}^{-1} \kappa_{m+1} \sigma_1)} + \frac{q^i - q^{-i}}{1 + \mu q^{1+i}} M \sigma^\infty_1 M \phi(M) a^{(i)} \quad (5.1.7)
\]

Here in the second line we used another expression for the Baxterized generators

\[
\sigma^x_i(x) = x 1 + \frac{x-1}{q-q^{-1}} \sigma_i^{-1} = \frac{\alpha_x x}{\alpha_x x + 1} \kappa_i
\]

which follows by a substitution \( \sigma_i = \sigma_i^{-1} + (q-q^{-1})(1 - \kappa_i) \) into the original expression (2.2.3).

Now, notice that

\[
\sigma_3^{-1} \kappa_2 \sigma_1 = \sigma_3^{-1} \kappa_2 \sigma_1 \sigma_2^{-1} \mod (4.4.4) \quad \sigma_2^{-1} \sigma_3^{-1} \kappa_2 \kappa_1 = \kappa_3 \kappa_2 \kappa_1, \quad (5.1.8)
\]

and, hence, in the case \( m \geq 1 \), the second term in (5.1.7) can be expressed as

\[
- i q M^{(a^{(i)}t_{m+2} \sigma_{m+2}^{-1} \kappa_{m+1} \sigma_1)} = - i q M^{\sigma_1^\infty_1} \phi(M) a^{(i)} \quad (5.1.9)
\]

Applying then the formulas (4.4.21) and (4.4.22) to the expressions (5.1.7) and (5.1.9), we obtain the recurrent relation (5.1.5).

In the case \( m = 0 \), the transformation of the second term in (5.1.7) suffers a slight modification. Notice that by eq.(5.1.8),

\[
\phi(M^{a^{(i)}t_1 \sigma_2^{-1} \kappa_1}) = \xi(M) M \phi(M^{a^{(i)}})
\]

Inverting the endomorphism \( \phi \) in this formula and using the relation (4.4.22) and the definition (5.1.2) of the matrices \( B^{(0,i)} \), we can complete the transformation of the second term in (5.1.7) and, again, get the equality (5.1.5).
In two corollaries below we use the recurrent relations (5.1.4) and (5.1.5) to derive expansions, in terms of the matrix powers $M^j$, of the matrices $A^{(i,m)}$ and $B^{(i,m)}$ and of their certain linear combinations, for some particular values of the indices $i$ and $m$. Notice that, by the proposition 4.14, one could expect an appearance of the terms $M^j(M^j)$ in the expansions. Our aim is to prepare such combinations of the matrices $A^{(i,m)}$ and $B^{(i,m)}$, whose expansions do not contain these unwanted terms.

**Corollary 5.2** For $1 \leq i \leq n$ and $m \geq i - 2$, one has

$$A^{(m,i)} = (-1)^{i-1} \sum_{j=0}^{i-1} (-q)^j \left\{ \frac{1 - q^{-2}}{1 + \mu q^{2i-3}} \sum_{r=1}^{i-j-1} M^{m+i-j-2r} (q^2 g)^r \right\} a_j. \quad (5.1.10)$$

For $1 \leq i \leq n$ and $m \geq i$, one has

$$B^{(m,i)} = (-1)^{i-1} \sum_{j=0}^{i-1} (-q)^j \left\{ \mu^{-1} q^{-2j} M^{m+i-j} g^{-j} - \frac{q^{-1}(1 - q^{-2})}{1 + \mu q^{2i-3}} \sum_{r=1}^{i-j-1} M^{m+i-j-2r} (q^2 g)^r \right\} a_j. \quad (5.1.11)$$

**Proof.** We employ induction on $i$.

In the case $i = 1$, the relations (5.1.10) and (5.1.11) reproduce the formulas (5.1.6).

It is then straightforward to verify the induction step $i \to i + 1$ with the help of the relations (5.1.4) and (5.1.5).

**Remark 5.3** In the Hecke case, the relation (5.1.10) simplifies drastically, the terms with $g$ disappear and the condition $m \geq i - 2$ weakens to $m \geq -1$. For $m = 0$, eq.(5.1.10) reproduces the Cayley–Hamilton–Newton identities found in [IOP, IOP1]. The R-trace maps (4.4.3) of these identities are the Newton relations. In the $GL(k)$-case (that is, if $\rho_R(a^{(k+1)}) = 0$), for $m = -1$ and $i = k + 1$, the left hand side of eq.(5.1.10) vanishes and (5.1.10) becomes the Cayley–Hamilton identity.

For $m < i$, only linear combinations of the matrices $A^{(m-2,i)}$ and $B^{(m,i)}$ can be expanded in the matrix powers $M^j$. To prepare such combinations we introduce a family of $\mathcal{P}(R,F)$-valued $2 \times 2$ matrices

$$Q^{(i)} := \frac{1}{1 + \mu q^{2i-5}} \begin{pmatrix} (1 + \mu q^{2i-3}) gI, & \mu q^{2i-3} (q - q^{-1}) I \\ -q^{-1} (q - q^{-1}) g M^\Sigma, & -(1 + \mu q^{2i-3}) M^\Sigma \end{pmatrix}, \quad i = 1, 2, \ldots, n, \quad (5.1.12)$$

\[10\] When $m \geq i - 2$ (respectively, $m \geq i$), all the $*$-powers of $M$ in the right hand side of eq.(5.1.10) (respectively, eq.(5.1.11)) are non-negative. This is why we specify these restrictions on $m$. For an invertible matrix $M$, the restrictions on $m$ can be removed.
and define $A^{(m,i|s)}$ and $B^{(m,i|s)}$ — linear combinations of $A^{(m+2j,i)}$ and $B^{(m+2j,i)}$, $j = 0, \ldots, s$ — recursively

$$A^{(m,i|0)} := A^{(m,i)}, \quad B^{(m,i|0)} := B^{(m,i)},$$

$$\begin{pmatrix} A^{(m-1,i|s+1)} \\ B^{(m+1,i|s+1)} \end{pmatrix} := Q^{(i-s)} \ast \begin{pmatrix} A^{(m-1,i|s)} \\ B^{(m+1,i|s)} \end{pmatrix}, \quad s = 0, 1, \ldots, i - 1. \quad (5.1.13)$$

**Corollary 5.4** For $1 \leq i \leq n$, $m \geq 0$ and for $s = 1, 2, \ldots, i$, one has

$$\begin{pmatrix} A^{(m-1,i|s)} \\ B^{(m+1,i|s)} \end{pmatrix} = (-1)^{s+1} \frac{1 + \mu q^{2i-1}}{1 + \mu q^{2i-2s-3}} \sum_{j=1}^{s} (-q)^{j} \begin{pmatrix} q^{i-2j-2} M_{m+j-1} a_{i-j} g^s \\ \mu^{-1} q^{-i} M^{m+2s-j+1} a_{i-j} g^{j} \end{pmatrix}$$

$$+ (-1)^{s} \frac{q^{i-2s-2}(1-q^{-2})(1 + \mu q^{2i-1})}{(1 + \mu q^{2i-2s-1})(1 + \mu q^{2i-2s-3})} \sum_{j=1}^{s-1} \sum_{r=1}^{s-j} (-q)^{j+2r} M^{m+2s-j+2r} a_{i-j} g^{j+r-1} \ast \begin{pmatrix} I \\ -q g I \end{pmatrix}$$

$$+ \frac{1 + \mu q^{2i-1}}{1 + \mu q^{2i-2s-1}} \begin{pmatrix} A^{(m+s-1,i-s)} \\ B^{(m+s+1,i-s)} \end{pmatrix} g^{s}. \quad (5.1.14)$$

**Proof.** For $s = 0$, the relation (5.1.14) is tautological. For $s = 1$, it reads

$$Q^{(i)} \ast \begin{pmatrix} A^{(m-1,i)} \\ B^{(m+1,i)} \end{pmatrix} = - \frac{1 + \mu q^{2i-1}}{1 + \mu q^{2i-5}} \begin{pmatrix} q^{i-3} M_{m} \\ \mu^{-1} q^{1-i} M_{m+2} \end{pmatrix} a_{i-1} g + \frac{1 + \mu q^{2i-1}}{1 + \mu q^{2i-3}} \begin{pmatrix} A^{(m,i-1)} \\ B^{(m+2,i-1)} \end{pmatrix} g. \quad (5.1.15)$$

This relation can be directly verified with the use of the definition (5.1.12) and of the recurrent formulas (5.1.4) and (5.1.5) for $A^{(m-1,i)}$ and $B^{(m+1,i)}$.

To prove eq. (5.1.14) in general, one carries out an induction on $s$, using the relation (5.1.15) at each step of the induction. Notice that

$$Q^{(i)} \ast \begin{pmatrix} I \\ -q g I \end{pmatrix} = - \frac{1 + \mu q^{2i-1}}{1 + \mu q^{2i-5}} \begin{pmatrix} -I \\ q^{-1} M_{m} \end{pmatrix} g,$$

which makes calculations more comfortable.

### 5.2 Cayley-Hamilton theorem: type $Sp(2k)$

Specifying to the case of the $Sp(2k)$-type quantum matrix algebra, we observe that the matrices $A^{(m-1,i)}$ and $B^{(m+1,i)}$ are well defined for the values $i = 1, 2, \ldots, k$ and $m \geq 0$ of their indices. The condition (3.4.1) implies

$$A^{(m-1,k+1)} = 0, \quad B^{(m+1,k+1)} = 0 \quad \forall m \geq 0. \quad (5.2.1)$$
However, these latter equalities are not independent. Indeed, taking $i = k + 1$ and $\mu = -q^{-1-2k}$ in eq.(5.1.15) and using the expression (5.1.12) for $Q^{(k+1)}$, we find

$$(B^{(m+1,k+1)} + qA^{(m-1,k+1)})|_{\mu = -q^{-1-2k}} = 0 \quad \forall m \geq 0.$$  

Consider now one particular condition from the set (5.2.1):

$$A^{(k-1,k+1)} = 0.$$  

(5.2.2)

By the corollary 5.2, its left hand side can be expanded in the powers of the matrix $M$ only (i.e., the expansion does not contain terms of the form $M^TM$). As we argued above, all the other relations in (5.2.1), which can be expressed as $\ast$-polynomials in the matrix $M$, are consequences of the equality (5.2.2).

Substituting $\mu = -q^{-1-2k}$ into the condition (5.2.2), using the relation (5.1.10) and reassembling it in a suitable way, we obtain:

**Theorem 5.5** Let $\mathcal{M}(R,F)$ be the $Sp(2k)$-type quantum matrix algebra (see the definition 4.1). Then the matrix $M$ of the algebra generators satisfies the Cayley-Hamilton identity

$$\sum_{i=0}^{2k}(-q)^iM^{2k-i}e_i = 0,$$  

(5.2.3)

where

$$\epsilon_i := \sum_{j=0}^{[i/2]} a_{i-2j}g^j, \quad \epsilon_{k+i} := \epsilon_{k-i}g^i \quad \forall i = 1, 2, \ldots, k.$$  

(5.2.4)

Let us now use the Cayley-Hamilton identity to introduce "eigenvalues" of the matrix $M$. In other words, we are going to factorize the polynomial in the left hand side of eq.(5.2.3). To this end, we realize elements of the characteristic subalgebra $\mathcal{C}(R,F)$ as polynomials in the spectral variables (see eq.(5.0.1)) and construct a corresponding extension of the algebra $\mathcal{P}(R,F)$.

**Corollary 5.6** In the setting of the theorem 5.5, assume that the elements $a_i$, $i = 1, 2, \ldots, k$, are algebraically independent.

Consider an algebra homomorphism of the characteristic subalgebra $\mathcal{C}(R,F)$ to the algebra of the spectral variables $\mathcal{E}_{2k}$,

$$\pi_{Sp(2k)} : \mathcal{C}(R,F) \rightarrow \mathcal{E}_{2k},$$  

(5.2.5)

defined on the generators by

$$g \mapsto \nu_0^2, \quad a_i \mapsto e_i(\nu_0, -\nu_0, \nu_1, \nu_2, \ldots, \nu_{2k}) \quad \forall i = 1, 2, \ldots, k,$$  

(5.2.6)

where $e_i(\ldots)$ are the elementary symmetric functions of their arguments (for the symmetric functions we adopt a notation of [Mac]). The map $\pi_{Sp(2k)}$ defines naturally a, say, left $\mathcal{C}(R,F)$-module structure on the algebra $\mathcal{E}_{2k}$. Consider a corresponding completion of the algebra $\mathcal{P}(R,F)$,

$$\mathcal{P}_{Sp(2k)}(R,F) := \mathcal{P}(R,F) \otimes_{\mathcal{C}(R,F)} \mathcal{E}_{2k},$$  

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where the $\star$-product on the completed space is given by a formula

\[
(N \otimes_c \nu) \star (N' \otimes_c \nu') := (N \star N') \otimes_c (\nu \nu') \quad \forall \, N, N' \in P(R, F) \quad \text{and} \quad \forall \, \nu, \nu' \in E_{2k}.
\] (5.2.7)

Then, in the completed algebra $P_{Sp(2k)}(R, F)$, the Cayley-Hamilton identity (5.2.3) acquires a factorized form

\[
\prod_{i=1}^{2k} (M - \nu_i I) = 0,
\] (5.2.8)

where the symbol $\prod$ denotes the product with respect to the $\star$-multiplication (5.2.7).

**Proof.** Using the equalities

\[
e_i(\nu_0, -\nu_0, \nu_1, \nu_2, \ldots, \nu_{2k}) = e_i(\nu_1, \nu_2, \ldots, \nu_{2k}) - \nu_i^2 e_{i-2}(\nu_1, \nu_2, \ldots, \nu_{2k}) \quad \forall \, i \geq 0
\] (5.2.9)

and

\[
e_{k+i}(\nu_1, \nu_2, \ldots, \nu_{2k}) = \nu_i^2 e_{k-i}(\nu_1, \nu_2, \ldots, \nu_{2k}) \quad \forall \, i = 1, 2, \ldots, k
\] (5.2.10)

(if $\{\nu_j\}_{j=0}^{2k}$ verifies eq.(5.0.1)), it is straightforward to check that the map $\pi_{Sp(2k)}$ sends the coefficients (5.2.4) of the Cayley-Hamilton identity to the elementary symmetric functions in the spectral variables:

\[
e_i \mapsto e_i(\nu_1, \nu_2, \ldots, \nu_{2k}) \quad \forall \, i = 1, 2, \ldots, 2k.
\]

\[\blacksquare\]

### 5.3 Cayley-Hamilton theorem: type $O(k)$, $k$ even

In this subsection we set $k = 2\ell$, $\ell = 1, 2, \ldots$.

Let us gradually impose conditions making the R-matrix $R$ orthogonal. In this way we observe effects, which different orthogonality restrictions have for the Cayley-Hamilton identities.

First, assume that the conditions (3.4.1) and (3.4.2) are satisfied and the R-matrix $R$ is not of the symplectic type, $\mu \neq -q^{-1} - 2k$. Hence, $\mu = q_1^{-k}$ and $q^{k+2} \neq -1$.

We have again the relations (5.2.1), but this time they imply nontrivial (contrary to the symplectic case) consequences

\[
A^{(m-1, k+1|s)} = B^{(m+1, k+1|s)} = 0 \quad \forall \, m \geq 0 \quad \text{and} \quad \forall \, 1 \leq s \leq k-1.
\] (5.3.1)

Let us take $s = \ell$, $m = 0$, $\mu = q^{1-k}$ and substitute the expression (5.1.10) for $A^{(-\ell, \ell|\ell+1)}$ into the formula (5.1.14) for $A^{(-1, k+1|\ell)}$. After some recollections of summands, we get

\[
A^{(-1, k+1|\ell)} = (-1)^\ell \frac{1 + q^{k+2}}{1 + q^2} \left( \sum_{j=0}^{k} (-q)^j M^{k-j} a_j g^\ell + \frac{1}{2} U_k \right),
\] (5.3.2)

where

\[
U_k := (1 - q^{-2}) \sum_{j=0}^{\ell-1} \sum_{r=1}^{\ell-j} (-q)^{j+2r} M^{k-j-2r} (a_j g^\ell - a_{k-j} g^j) g^r.
\] (5.3.3)
Opening the bracket \((1-q^{-2})\), we represent the matrix \(U_k\) as a difference of two double sums. Changing the summation index \(r \to r-1\) in the second double sum (the one with the common factor \(-q^{-2}\)), one can rewrite the expression for \(U_k\) in a form

\[
U_k = -\sum_{j=0}^{k} (-q)^j M^{k-j}(a_j g^\ell - a_{k-j} g^j)
+ (M^{\overline{2}} - gI) \sum_{j=0}^{k-2} \sum_{r=0}^{\ell-1 \ell-j-1} (q^{-1} (1 + q^{k+2}) (\sum_{j=0}^{k} (-q)^j M^{k-j} a_{k-j} g^{j+1} - \frac{1}{2} M^{\overline{2}} U_k) g^r).
\]  

Now, substituting this formula back into eq.(5.3.2), we obtain

\[
A^{(-1,k+1|\ell)} = (-1)^\ell \frac{q^{-1}(1 + q^{k+2})}{1 + q^2} \left( \sum_{j=0}^{k} (-q)^j M^{k-j} a_{k-j} g^{j+1} - \frac{1}{2} M^{\overline{2}} U_k \right),
\]  

and then, using another expression for \(U_k\)

\[
M^{\overline{2}} U_k = -\sum_{j=0}^{k} (-q)^j M^{k-j}(a_j g^\ell - a_{k-j} g^j)g
+ q^2 (M^{\overline{2}} - gI) \sum_{j=0}^{k-2} \sum_{r=0}^{\ell-1 \ell-j-1} (q^{-1} (1 + q^{k+2}) (\sum_{j=0}^{k} (-q)^j M^{k-j} a_{k-j} g^{j+1} - \frac{1}{2} M^{\overline{2}} U_k) g^r),
\]  

we obtain

\[
B^{(1,k+1|\ell)} = (-1)^\ell \frac{q^{-1}(1 + q^{k+2})}{2(1 + q^2)} \left( \sum_{j=0}^{k} (-q)^j M^{k-j} (a_j g^\ell + a_{k-j} g^j) \right)
- q^2 (M^{\overline{2}} - gI) \sum_{j=0}^{k-2} (-q)^j M^{k-j-2} \sum_{r=\text{max}(0,j+1-\ell)}^{[j/2]} (a_{j-2r} g^\ell - a_{k-j+2r} g^{j-2r}) g^r g^r.
\]  

Comparing the expressions (5.3.3) and (5.3.6), we conclude that the relations (5.3.1) imply following identities

\[
\sum_{j=0}^{k} (-q)^j M^{k-j}(a_j g^\ell + a_{k-j} g^j) g = 0
\]  

(5.3.7)
and
\[
(M^2 - gI) \star \sum_{j=0}^{k-2} (-q)^j M^{k-j-2} \sum_{r=\max\{0,j+1-\ell\}}^{[j/2]} (a_{j-2r} g^r - a_{k-j+2r} g^{j-2r}) g^{r+1} = 0. \tag{5.3.8}
\]

Up to now, these were effects of the conditions (3.4.1). Next, imposing additionally the rank-one condition \( \text{rk}(\rho(a^{(k)})) = 1 \) and using the consequent reciprocal relations (4.3.1), we can convert eqs.
\[
\left\{ \sum_{j=0}^{k} (-q)^j M^{k-j} a_j \right\} (g^\ell + a_k) g = 0 \tag{5.3.9}
\]

and
\[
\left\{ (M^2 - gI) \star \sum_{j=0}^{k-2} (-q)^j M^{k-j-2} \sum_{r=\max\{0,j+1-\ell\}}^{[j/2]} a_{j-2r} g^r \right\} (g^\ell - a_k) g = 0. \tag{5.3.10}
\]

The equations (5.3.10) are the Cayley-Hamilton identities for the quantum matrix algebra of the \( O(2\ell) \)-type.

Finally, assuming the invertibility of the 2-contraction \( g \) and specifying to the components \( O^\pm(2\ell) \) (see the definition-proposition 4.19), we obtain the Cayley-Hamilton identities for the components in a more familiar form:

**Theorem 5.7** Consider the components \( O^\pm(2\ell) \) of the extended orthogonal type quantum matrix algebra \( M^*(R,F) \). Assume, in addition to the standard restrictions on \( q \) (see the definition 3.12), that \( q^{2\ell+2} \neq -1 \). Then the matrix \( M \) of the algebra generators satisfies the Cayley-Hamilton identity, which reads
\[
\sum_{i=0}^{2\ell} (-q)^i M^{2\ell-i} a_i = 0 \tag{5.3.11}
\]

for the \( O^+(2\ell) \) component and
\[
\left( M^2 - gI \right) \star \sum_{i=0}^{2\ell-2} (-q)^i M^{2\ell-i-2} \epsilon_i = 0 \tag{5.3.12}
\]

for the \( O^-(2\ell) \) component.

Here
\[
\epsilon_i := \sum_{j=0}^{[i/2]} a_{i-2j} g^j, \quad \epsilon_{\ell-1+i} := \epsilon_{\ell-1-i} g^i \quad \forall \ i = 0, 1, \ldots, \ell - 1. \tag{5.3.13}
\]

**Corollary 5.8** In the setting of the theorem 5.7, assume that the elements \( a_i, i = 1, 2, \ldots, 2\ell \), do not satisfy any other algebraic relations except for the relations (4.5.10).
Consider following algebra homomorphisms of the characteristic subalgebras $C^\pm(R,F)$ to the algebras of the spectral variables:

$$\pi_{O^-(2\ell)} : C^-(R,F) \to E^\bullet_{2\ell-2},$$

$$g \mapsto \nu_0^2, \quad a_i \mapsto e_i(\nu_0, -\nu_0, \nu_1, \nu_2, \ldots, \nu_{2\ell-2}) \quad \forall \ i = 1, 2, \ldots 2\ell$$

and

$$\pi_{O^+(2\ell)} : C^+(R,F) \to E^\bullet_{2\ell},$$

$$g \mapsto \nu_0^2, \quad a_i \mapsto e_i(\nu_1, \nu_2, \ldots, \nu_{2\ell}) \quad \forall \ i = 1, 2, \ldots 2\ell,$$

where by $E^\bullet_i$ we understand an extension of the algebra $E_i$ by an element $\nu_i^{-1}$, inverse to the element $\nu_0: \nu_0 \nu_0^{-1} = 1$.

The maps $\pi_{O^-(2\ell)}$ and $\pi_{O^+(2\ell)}$ define a left module structure on the algebras $E^\bullet_{2\ell-2}$ and $E^\bullet_{2\ell}$, respectively.

Then, in the corresponding completions of the algebras $\mathcal{P}^\pm(R,F)$,

$$\mathcal{P}^+_{O^+(2\ell)}(R,F) := \mathcal{P}^+(R,F) \otimes_{C^+(R,F)} E^\bullet_{2\ell}$$

and

$$\mathcal{P}^-_{O^-(2\ell)}(R,F) := \mathcal{P}^-(R,F) \otimes_{C^-(R,F)} E^\bullet_{2\ell-2},$$

where the $\ast$-product is given by a formula repeating eq.(5.2.7), the Cayley-Hamilton identities (5.3.11) and (5.3.12) acquire factorized forms

$$\prod_{i=1}^{2\ell}(M - q\nu_i I) = 0 \quad (5.3.16)$$

for the $O^+(2\ell)$ component and

$$(M - \nu_0 I) \ast (M + \nu_0 I) \ast \prod_{i=1}^{2\ell-2}(M - q\nu_i I) = 0. \quad (5.3.17)$$

for the $O^-(2\ell)$ component.

Proof. Similar to the proof of the corollary 5.6.

5.4 Cayley-Hamilton theorem: type $O(k)$, $k$ odd

In this subsection we set $k = 2\ell - 1, \ell = 2, \ldots$.

Here again we analyze the expressions for $A^{(-1,k+1|\ell)}$ and $B^{(1,k+1|\ell)}$. Setting $\mu = q^{1-k}$ and using the reciprocal relations (4.3.1) (thus, assuming that the rank-one condition is satisfied), we obtain eventually

$$A^{(-1,k+1|\ell)} = (-1)^{\ell} \frac{1 + q^{k+2}}{1+q} \sum_{j=0}^{\ell-1} \sum_{r=0}^{\ell-j-1} (-q)^{j+2r} M^{k-j-2r-1} g^r \left( a_j(a_k gI - g^\ell M) + ga_{j-1}(a_k M - g^\ell I) \right).$$
The matrix $B^{(1,k+1)}$ is algebraically dependent: $B^{(1,k+1)}g^{k-1} = A^{(0,k+1)}a_k$. Thus, the Cayley-Hamilton identities in the case $O(2\ell - 1)$ and $q^{k+2} \neq -1$ read

$$
\sum_{j=0}^{\ell-1} \sum_{r=0}^{\ell-j-1} (-q)^{j+2r} M^{k-j-2r-1} g^{r+1} \left( a_j(a_k I - g^{\ell-1} I) + a_{j-1}(a_k M - g^{\ell} I) \right) = 0.
$$

(5.4.1)

Here we have set $a_{-1} = 0$. Assuming then the invertibility of the 2-contraction $g$ and using the notation (4.5.12), we obtain the Cayley-Hamilton identities in a familiar form:

**Theorem 5.9** Consider the extended $O(2\ell - 1)$-type quantum matrix algebra $M^\bullet(R,F)$. Assume, in addition to standard restrictions on $q$ (see the definition 3.12), that $q^{2\ell+1} \neq -1$. Then the matrix $M$ of the algebra generators satisfies the Cayley-Hamilton identity

$$
(M - g^{1/2} I) \star \sum_{i=0}^{2\ell-2} (-q)^i M^{2\ell-1-2} \epsilon_i = 0,
$$

(5.4.2)

where

$$
\epsilon_i := \sum_{j=0}^i a_{i-j} (-g^{1/2})^j, \quad \epsilon_{\ell-1+i} := \epsilon_{\ell-1-i} g^i \quad \forall \ i = 0,1,\ldots,\ell-1.
$$

(5.4.3)

**Corollary 5.10** In the setting of the theorem 5.9, assume that the elements $a_i$, $i = 1,2,\ldots,2\ell - 1$, do not satisfy any other algebraic relations except for the reciprocal relations (4.3.1).

Consider a following algebra homomorphism of the characteristic subalgebra $C^\bullet(R,F)$ to the algebra of the spectral variables:

$$
\pi_{O^\bullet(2\ell-1)} : C^\bullet(R,F) \to E^\bullet_{2\ell-2},
$$

(5.4.4)

$$
g^{1/2} \mapsto \nu_0, \quad a_i \mapsto e_i(\nu_0, \nu_1, \nu_2, \ldots, \nu_{2\ell-2}) \quad \forall \ i = 1,2,\ldots,2\ell - 1.
$$

The map $\pi_{O^\bullet(2\ell-1)}$ defines a left module structure on the algebra $E^\bullet_{2\ell-2}$.

Then, in the corresponding completion of the algebra $P^\bullet(R,F)$,

$$
P_{O^\bullet(2\ell-1)}(R,F) := P^\bullet(R,F) \otimes_{C^\bullet(R,F)} E^\bullet_{2\ell-2},
$$

where the $\star$-product is given by a formula repeating eq.(5.2.7), the Cayley-Hamilton identity (5.4.2), acquires a factorized form

$$
(M - \nu_0 I) \star \prod_{i=1}^{2\ell-2} (M - q\nu_i I) = 0,
$$

(5.4.5)

**Proof.** Use relations

$$
e_i(\nu_0, \nu_1, \nu_2, \ldots, \nu_{2\ell-1}) = e_i(\nu_1, \nu_2, \ldots, \nu_{2\ell-1}) + \nu_0 e_{i-1}(\nu_1, \nu_2, \ldots, \nu_{2\ell-1}) \quad \forall \ i \geq 0,
$$

and the equations (5.2.10) to check that the map $\pi_{O^\bullet(2\ell-1)}$ sends the coefficients (5.4.3) of the Cayley-Hamilton identity to the elementary symmetric functions in the spectral variables: $\epsilon_i \mapsto e_i(\nu_1, \nu_2, \ldots, \nu_{2\ell-2}) \quad \forall \ i = 0,1,\ldots,2\ell - 2$. 

$\blacksquare$
6 Newton relations

In this last section we use the basic identities from the subsection 5.1 to establish relations between the three sets of elements in the characteristic subalgebra — \{a_i\}_{i\geq0}, \{s_i\}_{i\geq0} and the power sums \{p_i\}_{i\geq0}. In particular, we approve the statement of the proposition 4.8.

For the theorem 6.1, we do not need to specify the subtype (symplectic or orthogonal) of the quantum matrix algebra and the value of the parameter \(\mu\). The results of this theorem are valid for any BMW-type quantum matrix algebra. Next, in the corollary 6.4, we parameterize the power sums \(p_n\) and the elements \(s_n\) in terms of the spectral variables.

Below, \([x]\) denotes the integer part of the number \(x\).

**Theorem 6.1** Let \(\mathcal{M}(R,F)\) be a BMW-type quantum matrix algebra. Assume that its two parameters \(q\) and \(\mu\) satisfy the conditions (2.2.8), which allow to introduce either the set \(\{a_i\}_{i=0}^n\) or, respectively, the set \(\{s_i\}_{i=0}^n\) in the characteristic subalgebra \(C(R,F)\) (see eqs.(4.2.17) and (4.2.18)). Then, respectively, the following Newton recurrent formulas relating these sets to the set of the power sums (see eq.(4.2.5) and (4.2.6))

\[
\sum_{i=0}^{n-1} (-q)^i a_i p_{n-i} = (-1)^{n-1} n q a_n + (-1)^n \left[ \mu q^{n-2i} - q^{1-n+2i} \right] a_{n-2i} g^i
\]

and

\[
\sum_{i=0}^{n-1} q^{-i} s_i p_{n-i} = n q s_n + \sum_{i=1}^{[n/2]} \left( \mu q^{2i-n} + q^{n-2i-1} \right) s_{n-2i} g^i
\]

are fulfilled.

In the case, when both sets \(\{a_i\}_{i=0}^n\) and \(\{s_i\}_{i=0}^n\) are consistently defined, they satisfy the Wronski relations

\[
\sum_{i=0}^{n} (-1)^i a_i s_{n-i} = \delta_{n,0} - \delta_{n,2} g,
\]

where \(\delta_{i,j}\) is a Kronecker symbol.

**Remark 6.2** One can use the formulas (6.1) and (6.2) for an iterative definition of the elements \(a_i\) and \(s_i\) for \(i \geq 1\), with initial conditions \(a_0 = s_0 = 1\). In this case, the elements \(a_n\) and \(s_n\) are well defined, assuming that \(i_q \neq 0\) \(\forall i = 2,3,\ldots,n\). The additional restrictions on the parameter \(\mu\), which appeared in their initial definition (4.2.18), are artifacts of the use of the antisymmetrizers and symmetrizers \(a^{(n)}, s^{(n)} \in W_n(q)\).

**Proof.** We prove the relation (6.1). Denote

\[
J^{(0)} := 0, \quad J^{(i)} := \sum_{j=0}^{i-1} (-q)^j M^{i-j} a_j, \quad i = 1, 2, \ldots, n.
\]

We are going to find an expression for the matrix \(J^{(n)}\) in terms of the matrices \(A^{(0,i)}\) and \(B^{(0,i)}\), \(1 \leq i \leq n\).
As we shall see, there exist matrices $H^{(i)}$, which fulfill equations

$$(1 - q^2)H^{(i)} g = \left( J^{(i)} + (-1)^i A^{(0,i)} \right), \quad i = 0, 1, \ldots, n. \tag{6.5}$$

To calculate $H^{(i)}$, we substitute repeatedly eqs.(5.1.4) for $A^{(0,i)}, A^{(1,i-1)}, \ldots, A^{(i-1,1)}$ in the right hand side of eq.(6.5). It then transforms to

$$H^{(i)} g = -\mu q^{-1} \sum_{j=1}^{i-1} (-1)^j \frac{q^{2j-1}}{1 + \mu q^{2j-1}} B^{(i-j,j)}. \tag{6.6}$$

Now, using the expressions (5.1.5) for $B^{(i-j,j)}$, we see that matrices

$$H^{(i)} := \sum_{j=0}^{i-2} \frac{(-q)^j}{1 + \mu q^{2j+1}} \left( M^{i-j-2} a_j + \frac{\mu q^j (q - q^{-1})}{1 + \mu q^{2j-1}} a^{(i-j-2,i)} - \mu q^j B^{(i-j-2,j)} \right) \tag{6.7}$$

satisfy eq.(6.5) for $i \geq 2$. In the cases $i = 0, 1$, solutions are trivial: $H^{(0)} = H^{(1)} = 0$.

Next, consider a combination $(H^{(i+2)} - H^{(i)}) g$. Using eq.(6.7) for the first term and eq.(6.6) for the second term, we calculate

$$H^{(i+2)} - H^{(i)} g = \sum_{j=0}^{i-1} \frac{(-q)^j}{1 + \mu q^{2j+1}} \left( M^{i-j-2} a_j + \frac{\mu q^j (q - q^{-1})}{1 + \mu q^{2j-1}} a^{(i-j-2,i)} - \mu q^j B^{(i-j-2,j)} \right)$$

$$+ \frac{(-q)^i}{1 + \mu q^{2i+1}} \left( I a_i + \frac{\mu q^i (q - q^{-1})}{1 + \mu q^{2i-1}} a^{(0,i)} - \mu q^i B^{(0,i)} \right).$$

To continue, we need a following auxiliary result:

**Lemma 6.3** For $1 \leq i \leq n$, one has

$$\frac{(-1)^i A^{(0,i)}}{1 + \mu q^{2i-1}} = \sum_{j=0}^{i-1} \frac{(-q)^j}{1 + \mu q^{2j+1}} \left( M^{i-j-2} a_j + \frac{\mu q^j (q - q^{-1})}{1 + \mu q^{2j-1}} a^{(i-j-2,i)} - \mu q^j B^{(i-j-2,j)} \right). \tag{6.8}$$

**Proof.** Use the recursion (5.1.4) for $A^{(i-j-1,j+1)}$ to calculate

$$\frac{A^{(i-j-1,j+1)}}{1 + \mu q^{2j+1}} + \frac{A^{(i-j,j)}}{1 + \mu q^{2j-1}} = \frac{q^j}{1 + \mu q^{2j+1}} \left( M^{i-j-1,j} a_j + \frac{\mu q^j (q - q^{-1})}{1 + \mu q^{2j-1}} a^{(i-j,j)} - \mu q^j B^{(i-j,j)} \right).$$

Compose an alternating sum of the above relations for $0 \leq j \leq i - 1$ and take into account the condition $A^{(i,0)} = 0$.

Using the relation (6.8), we finish the calculation

$$H^{(i+2)} - H^{(i)} g = (1 + \mu q^{2i+1})^{-1} \left( (-q)^i I a_i + (-1)^{i+1} (A^{(0,i)} + \mu q^2 B^{(0,i)}) \right) \quad \forall i = 0, 1, \ldots, n-2. \tag{6.9}$$
Now it is straightforward to get

\[ H^{(i)} = \sum_{j=1}^{[i/2]} \frac{(-1)^{j-1}}{1 + \mu q^{2(i-2j)+1}} \left( A^{(0,i-2j)} + \mu q^{2(i-2j)} B^{(0,i-2j)} - q^{i-2j} I a_{i-2j} \right) g^{j-1}, \quad i = 2, 3, \ldots, n. \tag{6.10} \]

Finally, substituting the expression (6.10) back into eq.(6.5), we obtain a formula

\[ J^{(i)} = (-1)^{i-1} A^{(0,i)} + \sum_{j=1}^{[i/2]} \frac{(-1)^{j-1}(1 - q^2)}{1 + \mu q^{2(i-2j)+1}} \left( A^{(0,i-2j)} + \mu q^{2(i-2j)} B^{(0,i-2j)} - q^{i-2j} I a_{i-2j} \right) g^{j}, \tag{6.11} \]

which is valid for 0 \leq i \leq n (the cases i = 0, 1 can be easily checked).

Taking the R-trace of eq.(6.11), we obtain the Newton relations (6.1). Here, in the calculation of the R-trace of \( B^{(0,i-2j)} \), we took into account the formulas (3.3.22).

The formulas (6.2) can be deduced from the relations (6.1) by a substitution \( q \rightarrow -q^{-1}, \quad a_j \rightarrow s_j \), this is justified by the existence of the BMW algebras homomorphism \( (2.2.4) \ W_n(q, \mu) \rightarrow W_n(-q^{-1}, \mu) \) and a fact that one and the same R-matrix \( R \) generates representations of both algebras \( W_n(q, \mu) \) and \( W_n(-q^{-1}, \mu) \).

The relation (6.3) is proved by induction on \( n \). The cases \( n = 0, 1, 2 \) are easily checked with the use of eqs.(6.1) and (6.2). Then, making an induction assumption, we derive the Wronski relations for arbitrary \( n > 2 \). To this end, we take a difference of eqs.(6.2) and (6.1)

\[ \sum_{i=0}^{n-1} (q^{-i} s_i p_{n-i} - (-q)^i a_i p_{n-i}) = n_q (s_n + (-1)^n a_n) + \text{terms proportional to} \ g \]

and substitute for \( p_{n-i} \) in the first/second term of the left hand side its expression from the Newton relation (6.1)/(6.2) (with \( n \) replaced by \( n - i \)). As a result, all terms, containing the power sums, cancel and, after rearranging the summations, we get

\[ n_q \sum_{i=0}^{n} (-1)^i a_i s_{n-i} = - \sum_{i=1}^{[n/2]} (q^{1-n+2i} + q^{n-1-2i}) \sum_{j=0}^{n-2i} (-1)^j a_j s_{n-2i-j}. \]

By the induction assumption, the double sum in the right hand side of this relation vanishes identically (when \( n \) is odd, the second sum vanishes for all values of the index \( i \); when \( n \) is even, the second sum is different from zero only for two values of the index \( i, i = n/2 \) and \( i = n/2 - 1 \), and these two summands cancel).

**Corollary 6.4** Let \( M(R, F) \) belong to one of the four specific series \( Sp(2k), O^\pm(2\ell) \) or \( O^*(2\ell-1) \) of the BMW-type quantum matrix algebras. Assume that the algebra parameter \( q \) fulfills the conditions \( i_q \neq 0, i = 2, 3, \ldots, n \) for some \( n \) \(^{11}\) and define the elements \( a_n \) and \( s_n \) of the characteristic subalgebra

\(^{11}\)For up to, respectively, \( n = k, n = 2\ell \) and \( n = (2\ell - 1) \), these conditions enter the initial settings for the algebras of the types \( Sp(2k), O^+(2\ell) \) and \( O^*(2\ell-1) \) (see the definitions 3.12 and 4.1). For the algebras of the orthogonal \( O^-(2\ell) \) and \( O^*(2\ell-1) \)-types, the additional restrictions, \( q^{2\ell+1} \neq -1 \) and, respectively, \( q^{2\ell+1} \neq -1 \), were imposed in the theorems 5.7 and 5.9. Formally, they are not used in the proof of the corollary. However, they are necessary if one wants to establish a relation between the spectral variables \( \nu_i \) and the eigenvalues of the matrix \( M \).
(respectively, \(C(R, F)\), \(C^\pm(R, F)\) or \(C^*(R, F)\)) with the help of the Newton recurrent relations (6.1) and (6.2) (see the remark 6.2). Then the elements \(s_n\) and \(p_n\) have following images under the respective homomorphism \(\pi_{Sp(2k)}\), \(\pi_{O^\pm(2\ell)}\) or \(\pi_{O^*(2\ell-1)}\) of the corresponding characteristic algebra to the algebra of the spectral variables (for the definitions of these homomorphisms, see the corollaries 5.6, 5.8 and 5.10):

the type \(Sp(2k)\)

\[
\pi_{Sp(2k)} : \quad s_n \mapsto h_n(\nu_1, \nu_2, \ldots, \nu_{2k}), \quad p_n \mapsto q^{n-1} \sum_{i=1}^{2k} d_i \nu_i^n, \quad (6.12)
\]

where

\[
d_i := \frac{\nu_i - q^{-4} \nu_{2k+1-i} \prod_{j \neq i, 2k+1-i}^{2k} \nu_i - q^{-2} \nu_j}{\nu_i - \nu_{2k+1-i}}; \quad (6.13)
\]

the type \(O^\pm(2\ell)\)

\[
\pi_{O^\pm(2\ell)} : \quad s_n \mapsto h_n(\nu_1, \ldots, \nu_{2\ell}) - \nu_0^2 h_{n-2}(\nu_1, \ldots, \nu_{2\ell}), \quad p_n \mapsto q^{n-1} \sum_{i=1}^{2\ell} d_i \nu_i^n, \quad (6.14)
\]

where

\[
d_i := \prod_{j \neq i, 2\ell+1-i}^{2\ell} \frac{\nu_i - q^{-2} \nu_j}{\nu_i - \nu_j}; \quad (6.15)
\]

the type \(O^-(2\ell)\)

\[
\pi_{O^-(2\ell)} : \quad s_n \mapsto h_n(\nu_1, \ldots, \nu_{2\ell-2}), \quad p_n \mapsto q^{n-1} \sum_{i=1}^{2\ell-2} d_i \nu_i^n + (1 + (-1)^n)q^{1-2\ell} \nu_0^n, \quad (6.16)
\]

where

\[
d_i := \frac{\nu_i - q^{-4} \nu_{2\ell-1-i} \prod_{j \neq i, 2\ell-1-i}^{2\ell-2} \nu_i - q^{-2} \nu_j}{\nu_i - \nu_{2\ell-1-i}}; \quad (6.17)
\]

the type \(O^*(2\ell-1)\)

\[
\pi_{O^*(2\ell-1)} : \quad s_n \mapsto h_n(\nu_1, \ldots, \nu_{2\ell-2}) + \nu_0 h_{n-1}(\nu_1, \ldots, \nu_{2\ell-2}), \quad p_n \mapsto q^{n-1} \sum_{i=1}^{2\ell-2} d_i \nu_i^n + q^{2-2\ell} \nu_0^n, \quad (6.18)
\]

where

\[
d_i := \frac{\nu_i - q^{-2} \nu_0 \prod_{j \neq i, 2\ell-1-i}^{2\ell-2} \nu_i - q^{-2} \nu_j}{\nu_i - \nu_0}; \quad (6.19)
\]
Here, in eqs. (6.12), (6.14), (6.16) and (6.18), $h_n(\ldots)$ denotes the complete symmetric function in its arguments.

The power sums contain the rational functions $d_i$ in the spectral variables and are themselves rational functions in $\{\nu_i\}$. However, as it follows from the Newton recursion (6.1), the power sums simplify, modulo the relations (5.0.1), to polynomials in the spectral variables.

**Proof.** For the proof, we use a following auxiliary statement:

**Lemma 6.5** In the assumptions of the remark 6.2 consider iterations

\[
a'_0 = a_0, \quad a'_1 = a_1, \quad a'_i = a_i + a'_{i-2}g; \quad (6.20)
\]

\[
s'_0 = s_0, \quad s'_1 = s_1, \quad s'_i = s_i + s'_{i-2}g; \quad (6.21)
\]

\[
p'_0 = (1 - \mu^2 q^{-2})/(q - q^{-1}), \quad p'_1 = p_1, \quad p'_i = p_i + (q^2 p'_{i-2} - p_{i-2})g; \quad (6.22)
\]

\[
p''_0 = (1 - \mu^2 q^2)/(q - q^{-1}), \quad p''_1 = p_1, \quad p''_i = p_i + (q^{-2} p''_{i-2} - p_{i-2})g \quad \text{for } i \geq 2. \quad (6.23)
\]

The modified sequences $\{a'_i\}_{i=0}^n$ and $\{s'_i\}_{i=0}^n$ and the two modified sequences of the power sums, $\{p'_i\}_{i=0}^n$ and $\{p''_i\}_{i=0}^n$, satisfy following versions of the Newton and Wronski relations

\[
\sum_{i=0}^{n-1} (-q)^i a_i p'_{n-i} = (-1)^{n-1} n_q a_n, \quad \sum_{i=0}^{n-1} q^{-i} s_i p''_{n-i} = n_q s_n \quad \forall \ n \geq 1; \quad (6.24)
\]

\[
\sum_{i=0}^{n} (-1)^i a'_i s_{n-i} = \sum_{i=0}^{n} (-1)^i a_i s'_{n-i} = \delta_{n,0} \quad \forall \ n \geq 0. \quad (6.25)
\]

**Proof.** For $n < 2$, the equalities (6.24)–(6.25) are clearly satisfied. For $n \geq 2$, one can check them inductively, applying the iterative formulas (6.20)–(6.23). E.g., the relations (6.25) follow from a calculation

\[
\sum_{i=0}^{n} (-1)^i a'_i s_{n-i} = \sum_{i=0}^{n} (-1)^i (a_i + a'_{i-2}g) s_{n-i} = \delta_{n,0} - \delta_{n,2} g + \sum_{i=0}^{n-2} (-1)^i a'_i s_{n-2-i} g = \delta_{n,0},
\]

where the relations (6.20) and (6.3) and the induction assumption were successively used.

For the modified Newton relations (6.24), arguing in the same way, one finally finds conditions on the zero-th modified power sums

\[
p'_0 = q^{-2}(p_0 - \mu + q), \quad p''_0 = q^2(p_0 - \mu - q^{-1}),
\]

which fix the initial settings for the iterations (6.22) and (6.23).

We now notice that in all four cases, considered in the corollary, the images of the elements $a_i$, $i = 1, \ldots, n$, are given by the elementary symmetric functions (see eqs. (5.2.5), (5.3.14), (5.3.15) and (5.4.4)). Hence, by the Wronski relations, (6.25) the images of the modified elements $s'_i$, $i = 1, \ldots, n$, are
are the complete symmetric functions in the same arguments. Using then eq.(6.21) and taking into
account the relation $h_n(\nu_0, \nu_1, \ldots) = \sum_{i=0}^n \nu_0^i h_{n-i}(\nu_1, \ldots)$, it is easy to check the formulas for
the images of the elements $s_n$, which are given in eqs.(6.12)--(6.18).

To check the formulas for the power sums, we use a following statement, which was proved in [GS]:
if the elements $a_i$ (respectively, $s_i$) for $i = 0, 1, \ldots, n \geq 1$ are realized as the elementary symmetric
polynomials $e_i$ (respectively, the complete symmetric polynomials $h_i$) in some set of variables \( \{\nu_i\}_{i=1}^n \),
then the elements $p'_n$ (respectively, $p''_n$), defined by eqs.(6.24), have following expressions in terms of
the variables $\nu_i$

$$p'_n(\text{respectively, } p''_n) = q^{n-1} \sum_{i=1}^n \widehat{d}_i \nu_i^n,$$

where \( \widehat{d}_i := \prod_{j \neq i} \frac{\nu_i - q^{-2}\nu_j}{\nu_i - \nu_j} \).

(6.26)
The latter formulas for $p'_i$ (respectively, for $p''_i$) suit better for the calculation of the images of $p_i$
in the cases $O^+(2\ell)$ and $O^-(2\ell - 1)$ (respectively, $Sp(2k)$ and $O^-(2\ell)$). In all cases, the calculation goes
essentially in the same way. Below we shall describe it in the $Sp(2k)$ case.

Assuming that the relation (6.26) stays valid for $p''_0$ (note, $p''_0$ is not fixed by the recursion (6.24) )
and taking the ansatz (6.12) for the power sums $p_i$ for $i = 0, 1, \ldots, n$, we make use of the recursion
(6.23). Upon substitutions, we find that the relations (6.23) hold valid provided that

$$d_i = \frac{\nu_i^2 - q^{-4}\nu_0^2}{\nu_i^2 - q^{-2}\nu_0^2} \widehat{d}_i.$$

(6.27)

Taking into account the relations (5.0.1), which are imposed on $\nu_i \in \mathcal{E}_{2k}$ in the $Sp(2k)$-case, we observe
that the conditions (6.27) dictate the choice (6.13) for $d_i$.

It remains to check the initial settings for the recursion (6.23). They are:

$$p''_0 = q^{-1} \sum_{i=1}^{2k} \widehat{d}_i = \frac{1 - \mu^2 q^2}{q - q^{-1}}|_{\mu=-q^{-1}} = q^{-2k}(2k)_q$$

(6.28)
from eq.(6.24);

$$p_0 = q^{-1} \sum_{i=1}^{2k} d_i = \text{Tr}_RI|_{\mu=-q^{-1}} = q^{-1-2k}((2k+1)_q - 1)$$

(6.29)
from eq.(4.2.5); and

$$p_1 = p''_1 \implies \sum_{i=1}^{2k} \nu_i(d_i - \widehat{d}_i) = 0$$

(6.30)
from eq.(6.24).

To verify them, we use expansions of following rational functions

$$w_1(z) := \prod_{i=1}^{2k} \frac{z - q^{-2}\nu_i}{z - \nu_i}, \quad w_2(z) := \frac{\nu_0^2 w_1(z)}{z^2 - q^{-2}\nu_0^2}, \quad w_3(z) := zw_2(z).$$

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in simple ratios. Expanding \( w_1(z) \) and evaluating the result at \( z = 0 \), we prove immediately the condition (6.28). We make one more comment on a less trivial check of the condition (6.29). Expanding \( w_2(z) \), we obtain

\[
w_2(z) = \sum_{i=1}^{2k} q^2 (d_i - \tilde{d}_i) \frac{\nu_i}{z - \nu_i} + \frac{q\nu_0}{2} \left( \frac{w_1(q^{-1}\nu_0)}{z - q^{-1}\nu_0} - \frac{w_1(-q^{-1}\nu_0)}{z + q^{-1}\nu_0} \right).
\]

Here, for the transformation of the first term in the right hand side, we used the formulas (6.26) and (6.27) and applied the relations (5.0.1), which confine variables \( \nu_i \in \mathcal{E}_{2k} \) in the \( Sp(2k) \) case. The relations (5.0.1) also allow us to calculate \( w_1(\pm q^{-1}\nu_0) = q^{-2k} \). Thus, evaluating \( w_2(z) \) at \( z = 0 \), we obtain

\[
w_2(0) = -q^{2-4k} - q^{-3}(p_0 - p_0^\prime) - q^{2-2k},
\]

wherefrom the condition (6.29) follows. A check of the condition (6.30), by the expansion and evaluation of \( w_3(z) \) at \( z = 0 \), is a similar calculation.

A On twists in quasitriangular Hopf algebras

Here we shall discuss universal (i.e., quasi-triangular Hopf algebraic) counterparts of relations from the subsection 3.2, especially from the lemma 3.6: we shall see, in the part 7 of the appendix, that these relations have a quite transparent meaning, they reflect the properties of the twisted universal R-matrix.

We don’t give an introduction to the theory of quasitriangular Hopf algebras assuming that the reader has some basic knowledge on the subject (see, e.g., [CP], the chapter 4).

1. Let \( \mathcal{A} \) be a Hopf algebra; \( m, \Delta, \epsilon \) and \( S \) denote the multiplication, comultiplication, counit and antipode, respectively.

Assume that \( \mathcal{A} \) is quasitriangular with a universal R-matrix \( \mathcal{R} = a \otimes b \) (this is a symbolic notation, instead of \( \sum a_i \otimes b_j \)). One has \( (S \otimes S)\mathcal{R} = \mathcal{R} \). The universal R-matrix \( \mathcal{R} \) is invertible, its inverse is related to \( \mathcal{R} \) by formulas \( \mathcal{R}^{-1} = S(a) \otimes b \) or \( (id \otimes S)(\mathcal{R}^{-1}) = \mathcal{R} \).

For elements in \( \mathcal{A} \otimes \mathcal{A} \), the ”skew” product \( \odot \) is defined as the product in \( \mathcal{A}^{\text{op}} \otimes \mathcal{A} \), where \( \mathcal{A}^{\text{op}} \) denotes the algebra with the opposite multiplication. In other words, the skew product of two elements, \( x \otimes y \) and \( \tilde{x} \otimes \tilde{y} \) is \( (x \otimes y) \odot (\tilde{x} \otimes \tilde{y}) = \tilde{x} x \otimes y \tilde{y} \). For a skew invertible element \( \mathcal{X} \in \mathcal{A} \otimes \mathcal{A} \), we shall denote its skew inverse by \( \psi_{\mathcal{X}} \). The universal R-matrix \( \mathcal{R} \) has a skew inverse, \( \psi_{\mathcal{R}} = a \otimes S(b) \). The element \( \psi_{\mathcal{R}} \) is invertible, \( (\psi_{\mathcal{R}})^{-1} = a \otimes S^2(b) \). The element \( \mathcal{R}^{-1} \) is skew invertible as well, its skew inverse is \( \psi_{(\mathcal{R}^{-1})} = S^2(a) \otimes b \). All these formulas are present in [D3]. We shall see below that there are similar formulas for the twisting element \( \mathcal{F} \). However, the properties of the twisting element \( \mathcal{F} \) and of the universal R-matrix \( \mathcal{R} \) are different, for instance, the square of the antipode is given by \( S^2(x) = u_{\mathcal{R}} x (u_{\mathcal{R}})^{-1} \), where \( u_{\mathcal{R}} = S(b) a \), but there is no analogue of such formula for \( \mathcal{F} \). Because of this difference, we felt obliged to give some proofs of the relations for \( \mathcal{F} \).

Let \( p \) be a representation of the algebra \( \mathcal{A} \) in a vector space \( V \). For an element \( \mathcal{X} \in \mathcal{A} \otimes \mathcal{A} \), denote by \( \hat{\rho}(\mathcal{X}) \in \text{End}(V \otimes^2) \) an operator \( \hat{\rho}(\mathcal{X}) = P \cdot (\rho \otimes \rho)(\mathcal{X}) \) (recall that \( P \) is the permutation operator). The skew product \( \odot \) translates into a following product \( \hat{\odot} \) for the elements of \( \text{End}(V \otimes^2) \):
\((X \otimes Y)_{13} = \text{Tr}_2(X_{12}Y_{23})\). In other words, if \(X \odot Y = Z\) then \(\hat{\rho}(X) \odot \hat{\rho}(Y) = \hat{\rho}(Z)\). For an operator \(X \in \text{End}(V \otimes 2)\), its skew inverse \(\Psi_X\), in the sense explained in the subsection 3.1, is precisely the inverse with respect to the product \(\odot\).

2. A following lemma is well known (see, e.g., [CP], the chapter 4, and references therein).

**Lemma A.1** Consider an invertible element \(F = \alpha \otimes \beta \in A \otimes A\) (we use the symbolic notation, \(\alpha \otimes \beta = \sum_i \alpha_i \otimes \beta_i\), like for the universal \(R\)-matrix) and let \(F^{-1} = \gamma \otimes \delta\). Assume that the element \(F\) satisfies

\[
F_{12} (\Delta \otimes \text{id})(F) = F_{23} (\text{id} \otimes \Delta)(F). \tag{A.1}
\]

Assume also that

\[
\epsilon(\alpha) \beta = \alpha \epsilon(\beta) = 1. \tag{A.2}
\]

Then an element \(v_F = \alpha S(\beta)\) is invertible, its inverse is

\[
(v_F)^{-1} = S(\gamma) \delta. \tag{A.3}
\]

One also has

\[
S(\alpha) (v_F)^{-1} \beta = 1 \quad \text{and} \quad \gamma v_F S(\delta) = 1. \tag{A.4}
\]

Twisting the coproduct by the element \(F\),

\[
\Delta_F(a) = F \Delta(a) F^{-1}, \tag{A.5}
\]

one obtains another quasitriangular structure on \(A\) with

\[
R_F = F_{21} R F^{-1} \tag{A.6}
\]

and

\[
S_F(a) = v_F S(a) (v_F)^{-1} \tag{A.7}
\]

(the counit does not change).

An element \(F\), satisfying conditions (A.1) and (A.2) is called *twisting* element. We shall denote by \(A_F\) the resulting "twisted" quasitriangular Hopf algebra.

**Remark A.2** On the representation level, the formula (A.6) transforms (compare with eq.(3.2.13)) into \(\hat{\rho}(R_F) = \hat{\rho}(F)_{21} \hat{\rho}(R)_{21} \hat{\rho}(F)_{21}^{-1}\). Below, when we talk about matrix counterparts of universal formulas, one should keep in mind this difference in conventions.

3. Assume, in addition to eq.(A.1), that

\[
(\Delta \otimes \text{id})(F) = F_{13} F_{23} \tag{A.8}
\]

and

\[
(\text{id} \otimes \Delta)(F) = F_{13} F_{12}. \tag{A.9}
\]
Now the conditions (A.2) follow from eqs.(A.8) and (A.9) and the invertibility of the twisting element \( \mathcal{F} \): applying \( \epsilon \otimes \text{id} \otimes \text{id} \) to eq.(A.8), we find \((\epsilon \otimes \text{id})(\mathcal{F}) = 1\); applying \( \text{id} \otimes \epsilon \otimes \text{id} \) to eq.(A.9), we find \((\text{id} \otimes \epsilon)(\mathcal{F}) = 1\).

Since \( \Delta^{\text{op}}(x)\mathcal{R} = \mathcal{R} \Delta(x) \) for any element \( x \in \mathcal{A} \) (where \( \Delta^{\text{op}} \) is the opposite comultiplication), it follows from eq.(A.8) that
\[
\mathcal{R}_{12} \mathcal{F}_{13} \mathcal{F}_{23} = \mathcal{F}_{23} \mathcal{F}_{13} \mathcal{R}_{12} .
\] (A.10)

Similarly, eq.(A.9) implies
\[
\mathcal{R}_{23} \mathcal{F}_{13} \mathcal{F}_{12} = \mathcal{F}_{12} \mathcal{F}_{13} \mathcal{R}_{23} .
\] (A.11)

When both relations (A.8) and (A.9) are satisfied, the relation (A.1) is equivalent to the Yang–Baxter equation for the twisting element \( \mathcal{F} \):
\[
\mathcal{F}_{12} \mathcal{F}_{13} \mathcal{F}_{23} = \mathcal{F}_{23} \mathcal{F}_{13} \mathcal{F}_{12} .
\] (A.12)

**Remark A.3** One also has
\[
(\Delta_\mathcal{F} \otimes \text{id})(\mathcal{F}_{21}) = \mathcal{F}_{31} \mathcal{F}_{32} \quad \text{and} \quad (\text{id} \otimes \Delta_\mathcal{F})(\mathcal{F}_{21}) = \mathcal{F}_{31} \mathcal{F}_{21} .
\] (A.13)

Therefore, one can twist \( \Delta_\mathcal{F} \) again, now by the element \( \mathcal{F}_{21} \).

On the matrix level, this corresponds to the second conjugation of \( \hat{\rho}(\mathcal{R}) \) by \( \hat{\rho}(\mathcal{F}) \),
\[
\hat{\rho}( (\mathcal{R}_\mathcal{F})\mathcal{F}_{21} ) = \hat{\rho}(\mathcal{F})^2 \hat{\rho}(\mathcal{R}) \hat{\rho}(\mathcal{F})^{-2} .
\]

**Remark A.4** The element \( \mathcal{F}^{-1}_{21} \) satisfies the conditions (A.1), (A.8) and (A.9) if the element \( \mathcal{F} \) does. Thus, one can twist the coproduct \( \Delta \) by the element \( \mathcal{F}^{-1}_{21} \) as well.

4. The conditions (A.2), (A.8), (A.9) imply the invertibility and skew-invertibility of the element \( \mathcal{F} \). The formulas for its inverse and skew inverse are similar to the corresponding formulas for the universal \( \mathcal{R} \)-matrix \( \mathcal{R} \) (in particular, we reproduce the standard formulas for \( \mathcal{R} \) since we can take \( \mathcal{F} = \mathcal{R} \)).

**Lemma A.5** Assume that the conditions (A.2) and (A.8) are satisfied. Then the element \( \mathcal{F} \) is invertible, its inverse is
\[
\mathcal{F}^{-1} = S(\alpha) \otimes \beta .
\] (A.14)

Assume that the conditions (A.2) and (A.9) are satisfied. Then the element \( \mathcal{F} \) is skew invertible, with the skew inverse
\[
\psi_\mathcal{F} = \alpha \otimes S(\beta) .
\] (A.15)

Assume that the conditions (A.2), (A.8) and (A.9) are satisfied. Then
\[
(S \otimes S)(\mathcal{F}) = \mathcal{F} .
\] (A.16)
Moreover, the element $\psi_\mathcal{F}$ is invertible, its inverse is

$$(\psi_\mathcal{F})^{-1} = \alpha \otimes S^2(\beta)$$

and the element $\mathcal{F}^{-1}$ is skew-invertible, its skew inverse reads

$$\psi_{(\mathcal{F}^{-1})} = S^2(\alpha) \otimes \beta.$$  \hfill (A.17)

**Proof.** The calculations are similar to those, from textbooks, for the universal R-matrix. We include this proof for a completeness only.

Applications of $m_{12} \circ S_1$ and $m_{12} \circ S_2$ to eq.(A.8) imply eq.(A.14) (here $m_{12}$ is the multiplication of the first and the second tensor arguments; $S_1$ is an operation of taking the antipode of the first tensor argument, etc.).

Applications of $m_{23} \circ S_2$ and $m_{23} \circ S_3$ to eq.(A.9) establish eq.(A.15).

Given eq.(A.15), the statement, that the element $\psi_\mathcal{F}$ is a left skew inverse of the element $\mathcal{F}$, reads in components:

$$\alpha \alpha' \otimes S(\beta') \beta = 1,$$ \hfill (A.19)

where primes are used to distinguish different summation terms, the expression $\alpha \alpha' \otimes S(\beta') \beta$ stands for $\sum_{i,j} \alpha_i \alpha_j \otimes S(\beta_i) \beta_j$. Applying $S_1$ to this equation, we find $(S(\alpha') \otimes S(\beta')) \cdot (S(\alpha) \otimes \beta) = 1$ which means that the element $S(\alpha') \otimes S(\beta')$ is a left inverse of the element $S(\alpha) \otimes \beta$. However, the latter element is, by eq.(A.14), the inverse of $\mathcal{F}$. Therefore, eq.(A.16) follows.

Applying $S_2$ to eq.(A.19), we find that $\alpha \otimes S^2(\beta)$ is a right inverse of the element $\psi_\mathcal{F}$.

Applying $S_2^2$ to eq.(A.19) and using eq.(A.16), we find that $S^2(\alpha) \otimes \beta$ is a right skew inverse of the element $\mathcal{F}^{-1}$.

We shall not repeat details for the left inverse of the element $\psi_\mathcal{F}$ and the left skew inverse of the element $\mathcal{F}^{-1}$; calculations are analogous.  \hfill ■

**Remark A.6** There is a further generalization of the formulas from the lemma A.5. Start with the element $\mathcal{F}$ and alternate operations "take an inverse" and "take a skew inverse". Then the next operation is always possible, the result is always invertible and skew invertible. One arrives, after $n$ steps, at $S^n(\alpha) \otimes \beta$ if the first operation was "take an inverse"; if the first operation was "take a skew inverse" then one arrives at $\alpha \otimes S^n(\beta)$ (see [D3], the section 8).

From now on, we shall assume that the twisting element $\mathcal{F}$ is invertible and satisfies the conditions (A.1), (A.8) and (A.9).

5. We turn now to the Hopf algebraic meaning of relations from the subsection 3.2.

The square of the antipode in an almost cocommutative Hopf algebra, with a universal R-matrix $\mathcal{R} = a \otimes b$, satisfies the property $S^2(x) = u_\mathcal{R} x(u_\mathcal{R})^{-1}$, where $u_\mathcal{R} = S(b)a$, for any element $x \in \mathcal{A}$. In a matrix representation of an algebra $\mathcal{A}$, the element $u_\mathcal{R}$ maps to the matrix $D_{\hat{\beta}(\mathcal{R})}$ (and the element $S(u_\mathcal{R})$ maps to the matrix $C_{\hat{\beta}(\mathcal{R})}$), so an identity (which follows from eq.(A.16))

$$(1 \otimes u_\mathcal{R}) \mathcal{F}^{-1} (1 \otimes (u_\mathcal{R})^{-1}) \equiv (1 \otimes u_\mathcal{R})(S(\alpha) \otimes \beta)(1 \otimes (u_\mathcal{R})^{-1}) = S(\alpha) \otimes S^2(\beta)$$

$$= \alpha \otimes S(\beta) \equiv \psi_\mathcal{F}$$

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becomes one of the relations from the lemma 3.3. In a similar manner, one can interpret other relations from the lemma 3.3.

Such an interpretation is not, however, unique. For instance, applying \( m_{12} \circ S_2 \) to eq.(A.12) and using eq.(A.14), one finds

\[
v_F \otimes 1 = \alpha' v_F S(\alpha) \otimes \beta',
\]

which, after an application of \( S_2 \), becomes, due to eqs.(A.15) and (A.16),

\[
v_F \otimes 1 = \psi_F (v_F \otimes 1) F.
\]

Similarly, applying \((\text{id} \otimes S) \circ m_{23} \circ \tau_{23} \circ S_3\) (where \( \tau \) is the flip, \( \tau(x \otimes y) = y \otimes x \)) to eq.(A.12) and using eqs.(A.16) and (A.17), one finds

\[
1 \otimes v_F = \alpha \alpha' \otimes S(\beta') v_F S^2(\beta),
\]

which, after an application of \( S_1 \), becomes, with the help of eq.(A.16),

\[
1 \otimes v_F = F (1 \otimes v_F ) \psi_F.
\]

In the matrix picture, eqs.(A.20) and (A.21) are also equivalent to particular cases of the relations from the lemma 3.3 – but this time we did not use the fact that the square of the antipode is given by the conjugation by the element \( u_R \).

Below we shall make use of another version of eqs.(A.20) and (A.21).

Writing eqs.(A.20) and (A.21) as

\[
(v_F \otimes 1) F^{-1} = \psi_F (v_F \otimes 1) \quad \text{and} \quad F^{-1} (1 \otimes v_F ) = (1 \otimes v_F ) \psi_F,
\]

respectively, and using the expressions for \( \psi_F \), \( (\psi_F)^{-1} \) and \( F^{-1} \) from the lemma A.5, we find, in components:

\[
v_F S(\alpha) \otimes \beta = \alpha v_F \otimes S(\beta)
\]

(A.22)

and, respectively,

\[
S(\alpha) \otimes \beta v_F = \alpha \otimes v_F S(\beta).
\]

(A.23)

Applying \( S_1 \) or \( S_2 \) to eqs.(A.22) and (A.23), we obtain corresponding formulas with \( v_F \) replaced by \( S(v_F) \). These formulas, together with eqs.(A.22) and (A.23), imply

\[
F \cdot (v_F S(v_F) \otimes 1) = (v_F S(v_F) \otimes 1) \cdot F,
\]

(A.24)

\[
F \cdot (1 \otimes v_F S(v_F)) = (1 \otimes v_F S(v_F)) \cdot F.
\]

It follows, from a compatibility of eqs.(A.20) and (A.21) (express the element \( \psi_F \) in terms of \( F \) and \( v_F \) in two ways), that

\[
F_{12} \cdot (v_F \otimes v_F) = (v_F \otimes v_F) \cdot F_{12}.
\]

(A.25)

The relations (A.24) and (A.25) are universal analogues of the matrix equalities (3.2.9) and (3.2.8) (for certain choices of the compatible pairs of the R-matrices) from the corollary 3.4.
6. We shall now establish a Hopf algebraic counterpart of the relation (3.2.14).

We need some information about the element \( v_x \). The inverse to the element \( v_x \) is given by eq.(A.3); it follows from the lemma A.5 that \((v_x)^{-1} = S^2(\alpha)\beta \).

By eq.(A.16), one has \( S(v_x) = S(\beta)\alpha \) and, then, \( S^2(v_x) = v_x \). Since \( S^2(x) = u_R x(u_R)^{-1} \) for any element \( x \in A \), we conclude that the element \( u_R \) commutes with the element \( v_x \) and, similarly, with the element \( S(v_x) \).

Making the flip in the relations (A.22) and (A.23), multiplying them out and comparing, we find that the elements \( v_x \) and \( S(v_x) \) commute.

**Remark A.7** In fact, more is true. Applying \( id \otimes S^j \) to eq.(A.22), we obtain \( v_x \alpha \otimes S^{j-1}(\beta) = \alpha v_x \otimes S^{j+1}(\beta) \) (we used eq.(A.16) to rearrange the powers of the antipode). In a similar way, applying \( S^{-j} \otimes id \) to eq.(A.23), we obtain \( \alpha \otimes S^{j-1}(\beta)v_x = \alpha \otimes v_x S^{j+1}(\beta) \). Multiplying out and comparing the right hand sides, we find that the element \( v_x \) commutes with the elements \( S^k(\alpha)\beta \forall k \in \mathbb{Z} \).

The same procedure, applied to the flipped versions of eqs.(A.22) and (A.23) shows that the element \( v_x \) commutes with the elements \( S^k(\alpha)\beta \) and \( S^k(\beta)\alpha \forall k \in \mathbb{Z} \) as well.

Applying the antipode to these commutativity relations, we find that the element \( S(v_x) \) commutes with the elements \( S^k(\alpha)\beta \) and \( S^k(\beta)\alpha \forall k \in \mathbb{Z} \) as well.

There is a closed formula for the coproduct of the element \( v_x \), again similar to the standard formula for the coproduct of the element \( u_R \).

**Lemma A.8** One has

\[
\Delta(v_x) = F_{12}^{-1} F_{21}^{-1} \cdot (v_x \otimes v_x) .
\]

**Proof.** Together, eqs.(A.8) and (A.9) imply

\[
(\Delta \otimes \Delta)(\mathcal{F}) = F_{14}F_{13}F_{24}F_{23} .
\]

Therefore, the coproduct of \( v_x \) can be written in a form

\[
\Delta(v_x) = \alpha(1)S(\beta(2)) \otimes \alpha(2)S(\beta(1)) = \alpha \alpha' S(\beta \beta'') \otimes \alpha'' v_x S(\beta')
\]

(we use the Sweedler notation for the coproduct, \( S(\beta) = \alpha \otimes \beta \alpha') \).

Using eq.(A.23), we continue to rewrite the expression (A.28):

\[
\Delta(v_x) = \alpha S(\alpha') S(\beta \beta'') \otimes \alpha'' \beta' v_x .
\]

The relation (A.12), in a form \( F_{13}F_{23}F_{12}^{-1} = F_{12}^{-1} F_{23}F_{13} \), reads, in components,

\[
\alpha S(\alpha') \otimes \alpha'' \beta' \otimes \beta \beta'' = S(\alpha) \alpha'' \otimes \beta \alpha' \otimes \beta \beta'' .
\]

Using eq.(A.30), we transform the right hand side of eq.(A.29) to a form

\[
\Delta(v_x) = S(\alpha) \alpha'' S(\beta') (S(\beta') \otimes \beta \alpha' v_x = S(\alpha) v_x S(\beta') \otimes \beta \alpha' v_x .
\]
Using again eq.(A.23), we obtain

\[ \Delta(v_F) = S(\alpha)\beta' v_F \otimes \beta S(\alpha') v_F , \]

(A.32)

which, by eq.(A.14), is a component form of eq.(A.26).

Applying the flip to eq.(A.26), we find \( \Delta^{\text{op}}(v_F) = f^{21}_2 \cdot f^{-1}_{12} \cdot (v_F \otimes v_F) \). Since \( \Delta^{\text{op}}(v_F) = R \Delta(v_F) \), we conclude

\[ (R_F)_{21} (v_F \otimes v_F) = (v_F \otimes v_F) R . \]

(A.33)

The translation of the equality (A.33) into the matrix language is equivalent to the relation (3.2.14) (see the remarks A.2 and A.3).

**Remark A.9** It follows from eq.(A.26) that

\[ \Delta(S(v_F)) = (S(v_F) \otimes S(v_F)) \cdot f^{-1}_{12} f^{-1}_{21} . \]

Eq. (A.25), together with eqs.(A.26) and (A.34), implies that an element

\[ \varphi := v_F S(v_F)^{-1} \]

is group-like, \( \Delta(\varphi) = \varphi \otimes \varphi \). Therefore, \( S(\varphi) = \varphi^{-1} = S(v_F)(v_F)^{-1} \) but \( S(\varphi) = S(v_F S(v_F)^{-1}) = (v_F)^{-1} S(v_F) \), which shows again that \( v_F \) commutes with \( S(v_F) \).

7. The twisted Hopf algebra \( A_F \) is quasitriangular, so we can write the usual identities for its universal R-matrix \( R_F = f^{21}_2 R F^{-1} \). The relations from the lemma 3.6 are the matrix counterparts of some of these identities.

For the twisted Hopf algebra \( A_F \), one finds, with the help of the first of eqs.(A.4), that \( u_{(R_F)} = \varphi u_R \), where the element \( \varphi \) is defined in eq.(A.35) (on the matrix level, this becomes one of the relations (3.2.18)). In particular,

\[ (S_F)^2(x) = \varphi S^2(x) \varphi^{-1} . \]

(A.36)

(i) The relation (3.2.15) is a consequence of, for example, the identity

\[ (\text{id} \otimes S_F)((R_F)^{-1}) = R_F . \]

(A.37)

We have

\[ R_F = (\text{id} \otimes S_F)((R_F)^{-1}) = (\text{id} \otimes S_F)(F R^{-1} F^{-1}) = (\text{id} \otimes S_F)(\alpha S(a) \beta' \otimes \beta b S(\alpha')) \]

\[ = \alpha S(a) \beta' \otimes v_F S^2(\alpha') S(b) S(\beta)(v_F)^{-1} = \alpha a \beta' \otimes v_F S^2(\alpha') b S(\beta)(v_F)^{-1} . \]

(A.38)

Here we used eq.(A.7) and the identities from the lemma A.5 for \( F \) and \( R \). Applying \( S^2 \otimes S \) to eq.(A.22), we find

\[ v_F S^2(\alpha) \otimes \beta = \alpha v_F \otimes \beta , \]

(A.39)

since \( S^2(v_F) = v_F \). Using the relation (A.39) and the relation (A.23) in a form \( S(\alpha) \otimes (v_F)^{-1} \beta = \alpha \otimes S(\beta)(v_F)^{-1} \), we rewrite the last expression in eq.(A.38):

\[ R_F = S(\alpha) a \beta' \otimes \alpha' v_F b(v_F)^{-1} \beta \]
or
\[ R_F = F_{21} \odot \left( (1 \otimes v_F) R(1 \otimes v_F)^{-1} \right) \odot F^{-1}, \quad \text{(A.40)} \]
which, on the matrix level, is equivalent to the relation (3.2.15).

(ii) Next,
\[
\psi_{(R_F)} = (\text{id} \otimes S_F)(R_F) = (\text{id} \otimes S_F)(F_{21} R F^{-1}) = (\text{id} \otimes S_F)(\beta a S(\alpha') \otimes ab')
\]
\[ = \beta a S(\alpha') \otimes v_F S(\beta') S(b) S(\alpha)(v_F)^{-1} = \beta a \alpha' \otimes v_F \beta' S(b) S(\alpha)(v_F)^{-1} \]
or
\[ (1 \otimes v_F)^{-1} \psi_{(R_F)} (1 \otimes v_F) = F \odot \psi_R \odot F_{21}^{-1}, \quad \text{(A.41)} \]
which, on the matrix level, is equivalent to the relation (3.2.16).

(iii) To obtain another formula for \( \psi_{(R_F)} \), we start with the identity \( \psi_{(R_F)} = (\text{id} \otimes (S_F)^2)((R_F)^{-1}) \),
which is a direct consequence of the identities from the lemma A.5:
\[
\psi_{(R_F)} = (\text{id} \otimes (S_F)^2)(R F^{-1} F_{21}^{-1}) = (\text{id} \otimes (S_F)^2)\left( \alpha S(\alpha) \beta' \otimes \beta b S(\alpha') \right)
\]
\[ = \alpha S(\alpha) \beta' \otimes \varphi S^2(\beta) S^3(\alpha') \varphi^{-1} = \alpha a \beta' \otimes \varphi S^2(\beta) S^3(\alpha') \varphi^{-1} \quad \text{(A.42)} \]
\[ = \alpha a \beta' \otimes S(v_F)^{-1} \beta v_F S(b)(v_F)^{-1} S(\alpha') S(v_F). \]
Here we used the identities from the lemma A.5, relations \( \alpha \otimes v_F S^2(\beta) = \alpha \otimes v_F \beta = (v_F)^{-1} S(\alpha) \otimes \beta \), which follow from eqs.(A.22) and (A.23), and the formula (A.36) for the square of the twisted antipode.

Eq.(A.42) can be rewritten as
\[ (1 \otimes S(v_F)) \psi_{(R_F)} (1 \otimes S(v_F)^{-1}) = F (1 \otimes v_F) \psi_R (1 \otimes (v_F)^{-1}) F_{21}^{-1}, \quad \text{(A.43)} \]
which, in the matrix picture, is equivalent to eq.(3.2.17).

(iv) The property \( (S_F \otimes S_F)(R_F) = R_F \) leads to
\[ (v_F \otimes v_F) F^{-1} R F_{21} = F_{21} R F^{-1} (v_F \otimes v_F). \quad \text{(A.44)} \]
Since the twisting element \( F \) commutes with \( v_F \otimes v_F \), the formula (A.44) is another manifestation of the relation (3.2.14).

**Remark A.10** We conclude the appendix with several more properties of the group-like element \( \varphi \)
defined in eq.(A.35).

We have \( R \cdot (\varphi \otimes \varphi) = (\varphi \otimes \varphi) \cdot R \). To see this, apply the antipode to the relation (A.33) and compare with the same relation (A.33).

Recall that a quasitriangular Hopf algebra \( A \) is called a ribbon Hopf algebra if it contains a ribbon element \( r \), that is, a central element such that \( r^2 = u_R S(u_R) \) and \( \Delta(r) = R_{12} R_{21}^{-1} \cdot (r \otimes r) \) (see [Resh], or [CP], the chapter 4). The twisted algebra \( A_F \) is a ribbon Hopf algebra if the algebra \( A \) is; for the ribbon element of the algebra \( A_F \), one can choose \( r_F = \varphi r \).
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