When Linear Stability Does Not Exclude Nonlinear Instability

P. G. Kevrekidis,1,2 D. E. Pelinovsky,3,4 and A. Saxena2

1Department of Mathematics and Statistics, University of Massachusetts, Amherst, Massachusetts 01003-4515, USA
2Center for Nonlinear Studies and Theoretical Division, Los Alamos National Laboratory, Los Alamos, New Mexico 87544, USA
3Department of Mathematics, McMaster University, Hamilton, Ontario, Canada L8S 4K1
4Department of Applied Mathematics, Nizhny Novgorod State Technical University, 24 Minin Street, Nizhny Novgorod, 603950, Russia

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We describe a mechanism that results in the nonlinear instability of stationary states even in the case where the stationary states are linearly stable. This instability is due to the nonlinearity-induced coupling of the linearization’s internal modes of negative energy with the continuous spectrum. In a broad class of nonlinear Schrödinger equations considered, the presence of such internal modes guarantees the nonlinear instability of the stationary states in the evolution dynamics. To corroborate this idea, we explore three prototypical case examples: (a) an antisymmetric soliton in a double-well potential, (b) a twisted localized mode in a one-dimensional lattice with cubic nonlinearity, and (c) a discrete vortex in a two-dimensional saturable lattice. In all cases, we observe a weak nonlinear instability, despite the linear stability of the respective states.

Introduction.—Among dispersive nonlinear partial differential equations, the nonlinear Schrödinger (NLS) model [1,2] stands out as a prototypical system that has proved to be essential in modeling and understanding features of numerous areas in nonlinear physics. The relevant fields of application vary from optics and the propagation of the electric field envelope in optical fibers [3,4] to the self-focusing and collapse of Langmuir waves in plasma physics [5,6]. It is also encountered in the modeling of deep water and freak or rogue waves in the ocean [7,8], as well as in atomic physics and the dynamics of superfluids and atomic Bose-Einstein condensates [9–11].

One of the most customary ways to approach the experimental observations of nonlinear dispersive waves in these different physical systems is to explore the standing wave solutions that NLS models may possess and to understand their spectral and dynamical stability characteristics [12]. This is accomplished not only in homogeneous continuous media, but also in inhomogeneous and discrete ones, not only in one but also in higher dimensions [13–15]. Then, the conventional wisdom suggests that should the solution in the NLS model be found to be linearly (spectrally) stable, then it should be expected to be dynamically stable as well and hence a suitable candidate for observations in physical experiments. By linear stability here, we imply the absence of eigenvalues with nonzero real parts, as well as the absence of multiple and embedded imaginary eigenvalues with the exception of the zero eigenvalue generated by the symmetries of the NLS models.

In the present work, we explore an important, as well as generic, nonlinear mechanism of instability of standing wave solutions, which are linearly stable. The instability is induced by the linearization’s internal modes of negative energy or negative Krein signature [16] that correspond to simple imaginary eigenvalues and represent negative “directions” of the NLS energy at the standing wave solutions. While perfectly innocuous in the linear setting, these internal modes of negative energy can be in resonance with the continuous spectrum (or other internal modes) due to nonlinearity, in which case they lead to the nonlinear instability of the standing wave solutions.

For a ground state, small amplitude excitations of the standing wave always increase the NLS energy so that the standing wave is an energetically stable minimum of the system, which is also dynamically stable. Internal modes for such ground states may only have positive energy or a positive Krein signature [17,18]. However, for many excited states, small amplitude excitations may decrease the NLS energy and still do not result in the appearance of linear instability. This has led to the widespread belief that energetic instability does not generically imply dynamical instability; instead “the energetic instability can only destabilize the system in the presence of dissipative terms which drive it towards configurations of lower energy” (p. 58 in Ref. [9]). Our aim herein is to challenge this conventional wisdom and to establish through a diverse array of case examples that, in fact, generically, excited states bearing an energetic instability will also manifest a dynamical one.

The initial mathematical formulation of the nonlinear mechanism of instability of excited states was obtained by Cuccagna [19,20], but these results have not been confirmed in the physics literature by numerical or experimental evidence. In the present work, we give numerical evidence of the nonlinear instability due to the internal modes of negative energy based on three case examples involving continuous and discrete NLS models in one and
two dimensions. The discovery of this nonlinear mechanism may broadly impact researchers in nonlinear physics, enabling them to identify and to explain weak (nonlinear) instabilities of the standing waves observed in numerous experimental setups in atomic, optical, fluid, or plasma systems related to this general framework.

Theoretical formulation.—The cubic NLS model in a generalized form reads

\[ i\partial_t u = -\nabla^2 u + V(x)u + g|u|^2u, \]

where \( u \) is a complex field, \( V \) characterizes the external potential with a fast decay to zero at infinity, and \( g \) is a coefficient that characterizes the self-focusing \( (g < 0) \) or self-defocusing \( (g > 0) \) nature of the nonlinearity. The stationary state takes the form \( u(x, t) = e^{-i\omega t}\phi(x) \), where \( \omega \) is real.

The prototypical example of the nonlinear instability in the NLS model (1) occurs when the Schrödinger−NLS model, the continuous spectrum for a double zero eigenvalue due to the gauge symmetry of the \( \Omega \).

Hereafter, for simplicity, we assume that the correction term \( \psi \) is given by complex functions.

When considering the stability of the stationary state, we utilize the linearization, e.g., by means of

\[ u(x, t) = e^{-i\omega t}\left[ \phi(x) + \delta(a(x)e^{i\xi} + b(x)e^{-i\xi}) \right], \]

with small parameter \( \delta \) (independently of \( \epsilon \)), and obtain the spectral problem

\[ H\psi = i\lambda\sigma_3\psi, \]

where \( \psi = (a, b)^T \), \( \sigma_3 = \text{diag}(1, -1) \), and \( H \) is given by

\[ H = \begin{bmatrix} -\nabla^2 + V - \omega + 2g|\phi|^2 & g\phi^2 \\ g\phi^2 & -\nabla^2 + V - \omega + 2g|\phi|^2 \end{bmatrix}. \]

Hereafter, for simplicity, we assume that \( \phi \) is real. If \( \epsilon \) is small, it is easy to confirm that the spectral problem (3) has a double zero eigenvalue due to the gauge symmetry of the NLS model, the continuous spectrum for \( \lambda = i(-\infty, -|\omega|) \) and \( \Omega = E_1 - E_0 + \mathcal{O}(\epsilon^2) > 0 \), and a pair of internal modes at \( \lambda = \pm i\Omega \) with \( \Omega = E_1 - E_0 + \mathcal{O}(\epsilon^2) > 0 \). Assuming that the two negative energy levels of \( -\nabla^2 + V \) satisfy

\[ \frac{1}{2}|E_1| < |E_1 - E_0| < |E_1|, \]

we conclude that \( \Omega < |\omega| \) but \( 2\Omega > |\omega| \); hence, the internal mode eigenfrequency is isolated from the continuous spectrum but the second harmonic is embedded into the continuous spectrum. The second harmonic can be generated by the nonlinear terms beyond the linear approximation (2). Also, note that the mode energy is defined by

\[ K = \langle H\psi_\Omega, \psi_\Omega \rangle = -\Omega \int_{\mathbb{R}}(|a_\Omega|^2 - |b_\Omega|^2)dx, \]

where \( \psi_\Omega = (a_\Omega, b_\Omega)^T \) is the eigenvector for the eigenvalue \( \lambda = \pm i\Omega \). Since \( \Omega = E_1 - E_0 + \mathcal{O}(\epsilon^2) > 0 \) and \( \psi_\Omega = (u_0, 0)^T + \mathcal{O}(\epsilon^2) \), where \( u_0 \) is the \( L^2 \)-normalized eigensolution of \( -\nabla^2 + V \) for the lowest energy level \( E_0 \), it follows that the internal mode has negative energy, that is, \( K < 0 \). The sign of \( K \) is usually referred to as the Krein signature.

Now, we will explain why the internal mode of negative energy, when coupled with the continuous spectrum due to the second harmonic, leads to the nonlinear instability of the stationary state. We shall consider the expansion in amplitudes of the internal mode

\[ u(x, t) = e^{-i\omega t}\left[ \phi(x) + \delta u_1(x, t) + \delta^2 u_2(x, t) + \mathcal{O}(\delta^3) \right] \]

with \( u_1(x, t) = c(t)a_\Omega(x)e^{i\Omega t} + \bar{c}(t)b_\Omega(x)e^{-i\Omega t} \), where \( c(t) \) is the complex amplitude of the internal mode evolving in slow time. Due to \( H + \Omega\sigma_3 \) being a self-adjoint operator, we can choose the internal mode \( \psi_\Omega = (a_\Omega, b_\Omega)^T \) to be real. Using the expansion above, similarly to what was done in the case of internal modes of positive energy [18], we obtain the explicit representation of the second-order correction term

\[ u_2(x, t) = c^2a_\Omega(x)e^{2\Omega t} + |c|^2a_\Omega(x) + c\bar{c}b_\Omega(x)e^{-2\Omega t}, \]

where \( \psi_2 = (a_\Omega, b_\Omega)^T \) and \( \psi_0 = (a_0, a_0)^T \) are obtained from bounded solutions of the inhomogeneous problems

\[ (H + 2\Omega\sigma_3)\psi_2 = -\bar{g}\phi\left[ \begin{array}{c} a_\Omega + 2b_\Omega \alpha a_\Omega \\ 2a_\Omega + b_\Omega b_\Omega \alpha b_\Omega \end{array} \right] \]

and

\[ H\psi_0 = -2\bar{g}\phi\left[ \begin{array}{c} a_\Omega^2 + a_\Omega b_\Omega + b_\Omega^2 \frac{1}{2} \\ 1 \end{array} \right]. \]

Since the kernel of \( H \) is spanned by the eigenvector \( (\phi, -\phi)^T \) due to the gauge symmetry, there is a real solution of Eq. (7) decaying at infinity. On the other hand, because \( 2\Omega > |\omega| \), the correction term \( \psi_2 \) is bounded but not decaying at infinity. We apply the Sommerfeld radiation condition

\[ \psi_2(x) \rightarrow R_\Omega e^{\mp ik_\Omega x} \text{ as } x \rightarrow \pm \infty, \]

where \( \epsilon_\Omega = (0, 1) \), \( k_\Omega = \sqrt{2\Omega - |\omega|} \), and the radiation tail amplitude \( R_\Omega \) is a uniquely determined complex coefficient. Because of the Sommerfeld radiation condition (8), the second harmonic \((a_\Omega, b_\Omega)^T \) is given by complex functions.

Proceeding to the third-order correction term, as in Ref. [18], we obtain the evolution equation for the amplitude \( c(t) \) in slow time \( \tau = \delta^2 t \).
\[ iK \frac{dc}{d\tau} + \Omega \beta |c|^2 c = 0, \]  

where \( K \) is given by Eq. (5) and \( \beta \) is found from the projection of the inhomogeneous problem for the third-order correction term on the internal mode \( (a_\Omega, b_\Omega)^T \).

A long but straightforward computation yields
\[ 2i \text{Im}(\beta) = 2(\bar{a}_2 a_2 + \bar{b}_2 b_2 - a_2 a_2 - b_2 b_2)|_{a_\Omega, b_\Omega}^{\frac{\pi}{2}+\infty} = 8ik_\Omega |R_\Omega|^2. \]

Introducing the square amplitude \( Q(\tau) = |c(\tau)|^2 \), we obtain a simple differential equation
\[ K \frac{dQ}{d\tau} = -8\Omega k_\Omega |R_\Omega|^2 Q^2, \tag{11} \]

starting with the positive initial value \( Q(0) \). For the internal mode of positive energy with \( K > 0 \), this equation leads to the slow (i.e., power-law) decay of the internal mode in time \[24]. For the internal mode of negative energy \( K < 0 \), this equation guarantees the power-law growth of the internal mode in time and eventual blowup of the quadratic approximation in Eq. (11), although this growth is typically saturated by the nonlinearity. Mathematical justification of the normal form equation (11) can be found in Refs. [19,20].

**Case example 1: antisymmetric soliton in double-well potentials.**—The dynamics of the antisymmetric (so-called \( \pi \)) solitons in a double-well potential has been explored extensively in the recent physical literature (see, e.g., Ref. [21]) motivated by experiments in atomic \[22-24] and optical \[25,26] physics. In comparison to the work presented herein, such solitons were realized experimentally for short dynamical time scales, for which no dynamical instability was detected \[24]. Here, we report on the weak (nonlinear) instability of the antisymmetric solitons in the NLS model (1) with the repulsive interaction \( g = 1 \) and the potential
\[ V(x) = V_0(\text{sech}^2(x-x_0) + \text{sech}^2(x+x_0)). \tag{12} \]

We take \( V_0 = -1 \) and \( x_0 = 2 \) to ensure that \( V \) is the double-well potential. For \( \omega = -0.4 \), the frequency of the internal mode of the antisymmetric soliton is \( \Omega \approx 0.203 \) (i.e., \( \Omega < |\omega| \) but \( 2\Omega > |\omega| \)), ensuring the second harmonic occurs inside the continuous spectrum.

In Fig. 1, we monitor the dynamical evolution of the antisymmetric soliton, perturbed by the internal mode (see the Supplemental Material [27] for further details). We observe the slow manifestation of a dynamical instability, both in the space-time evolution in the top panel, as well as more concretely in the time evolution of the maximal amplitudes in the two potential wells in the bottom panel.

The longer term dynamics shows that the growing oscillatory dynamics of the internal mode eventually returns to the initial state leading to recurrent dynamics.

**Case example 2: the twisted localized mode in a one-dimensional lattice with cubic nonlinearity.**—We examine a twisted localized mode in the one-dimensional cubic NLS lattice [15]. Such states have been previously explored in both one-dimensional \[28] and two-dimensional \[29] optical experiments. The discrete NLS equation is a prototypical model of optical waveguide arrays in nonlinear optics [30]. We take the discrete NLS equation in the standard form:
\[ iu_n = -C \Delta u_n - |u_n|^2 u_n. \tag{13} \]

Here, \( u_n \) plays the role of the envelope of the electric field at the \( n \)th waveguide and \( C \) represents the strength of the evanescent coupling between the waveguides, while \( \Delta \) stands for the standard 3-point stencil in the one-dimensional lattice.

The twisted localized modes can be exactly represented in the limit of \( C = 0 \) (so-called anticontinuum limit) as \( u_n(t) = e^{i\delta_n} e^{-\frac{1}{2} \delta_n^2} \), setting \( \omega = -1 \) without loss of generality. As \( C \neq 0 \) increases, as shown in Ref. [31], the solution is linearly stable but it has one internal mode of negative energy with the frequency \( \Omega = O(C^{1/2}) \) as \( C \to 0 \). For small \( C \), this frequency is isolated from the continuous spectrum, which corresponds to the frequencies in the interval \([1, 1 + 4C]\). For \( C = 0.01 \), the internal mode frequency is \( \Omega \approx 0.204 \) so that the condition \( 2\Omega > |\omega| \) is not satisfied. While this case is unstable too via the proposed mechanism, the instability only arises through a higher harmonic (the fifth harmonic, in fact) of the mode frequency. That is why the
FIG. 2 (color online). Evolution of twisted localized modes in the discrete NLS model (13). Top: time evolution of the four centermost sites (i.e., the two central ones 0 and 1, with a square amplitude of ≈1.3 shown also by solid and dashed line in the left inset, and their immediate neighbors, sites −1 and 2, with a square amplitude of ≈0.01 shown also by solid and dashed line in the right inset) of the structure for \( C = 0.01 \); no instability is manifested. The insets show a zoom in of the relevant sites revealing their oscillatory behavior. Bottom: the evolution of one of the central sites for \( C = 0.07 \) (the inset shows its envelope illustrating the unstable evolution). In both panels \( n_0 = 0 \).

instability is not visible on the time scale of our dynamical simulations shown in the top panel of Fig. 2.

On the other hand, for the case of \( C = 0.07 \), the internal mode frequency is \( \Omega \approx 0.598 \) and \( 2\Omega > |\omega| \) is satisfied. In the dynamics of the bottom panel of Fig. 2, we thus initialize with such a solution, perturbed by this internal mode. We can clearly see in this panel (showing the evolution of one of the two central amplitudes at \( n_0 = 0 \)) that there is very slow growth reminiscent of a power law. After this instability manifests itself, it eventually saturates. The theory does not reveal any information about the ultimate fate of the dynamics. The numerics suggest a resulting genuinely periodic state for the modulus, hence a genuinely quasiperiodic (or breather-on-breather [32,33]) state for the system. This, in turn, suggests that it would be quite worthwhile to further explore such states dynamically.

Case example 3: a discrete vortex in a two-dimensional saturable lattice.—Our third example is also highly motivated physically: we inspect discrete vortices in two-dimensional lattices that were robust enough dynamically to also be accessible in the optical observations within photorefractive optical crystals [34,35]. Here, to comply with the photorefractive nature of the nonlinearity and to illustrate the genericity of our results, a saturable nonlinearity has been implemented [36] (although the results would still hold in the cubic case). The discrete saturable NLS equation takes the form

\[
i\dot{u}_{n,m} = -C\Delta_2 u_{n,m} - \frac{|u_{n,m}|^2 u_{n,m}}{1 + |u_{n,m}|^2},
\]

where \( \Delta_2 \) in this case stands for the standard 5-point stencil in the two-dimensional square lattice.

Our example shown in Fig. 3 corresponds to the case of \( C = 0.09 \). In this case, the continuous spectrum covers the frequencies in the interval \([-\omega, -\omega + 8\Omega]\). The discrete vortex consisting of four excited principal sites at the center of the lattice with phases of approximately 0, \( \pi / 2 \), \( \pi \), and \( 3\pi / 2 \) is found for \( \omega = -0.35 \) to possess three internal modes with frequencies \( \Omega = 0.012 \), 0.167, and 0.191. Among the three, the last frequency \( \Omega = 0.191 \) has its second harmonic lying within the linear mode band; hence, we anticipate its destabilization by the mechanism reported herein. Indeed, this is what we observe in Fig. 3. However, the instability in this case appears to be far more “detrimental” for the state in comparison to the previous examples. In particular, the slow growth of the instability eventually gives rise to a dramatic event through which one among the four vortex principal nodes picks up most of the power in the system, while the other three considerably decrease in power. The resulting
dynamics effectively leads to a single-site ground state configuration of the two-dimensional lattice.

Conclusions.—In the present work, we examined a mechanism for nonlinear instability that is generic for excited states of nonlinear Schrödinger systems. The generality and potential experimental ramifications (through numerical experiments herein) of our findings were also discussed. It was shown that the mechanism occurs independently of the discrete or continuum, one- or multidimensional, cubic or saturable nature of the underlying NLS models, as long as the excited nature of the state is manifested via the internal modes of negative energy. The mechanism is found to give rise to a weak (power-law in its apparent manifestation) instability that eventually deforms, or in some cases (e.g., the discrete vortex) completely destroys the configuration.

While the mechanism presented herein is explicitly established, there are numerous questions that are worthy of further investigation, in addition to its potential experimental demonstration. The latter seems within reach, of further investigation, in addition to its potential experimental ramifications (through numerical experiments herein) of our findings were also discussed. It was shown that the mechanism occurs independently of the discrete or continuum, one- or multidimensional, cubic or saturable nature of the underlying NLS models, as long as the excited nature of the state is manifested via the internal modes of negative energy. The mechanism is found to give rise to a weak (power-law in its apparent manifestation) instability that eventually deforms, or in some cases (e.g., the discrete vortex) completely destroys the configuration.

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