Response of bubbles to diagnostic ultrasound: 
a unifying theoretical approach

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The scattering of ultrasound from bubbles of $\sim 1\mu m$ radius, such as used in contrast enhancers for ultrasound diagnostics, is studied. We show that sound scattering and “active” emission of sound from oscillating bubbles are not contradictory, but are just two different aspects derived from the same physics. Treating the bubble as a nonlinear oscillator, we arrive at general formulas for scattering and absorption cross sections. We show that several well-known formulas are recovered in the linear limit of this ansatz. In the case of strongly nonlinear oscillations, however, the cross sections can be larger than those for linear response by several orders of magnitude. The major part of the incident sound energy is then converted into emitted sound, unlike what happens in the linear case, where the absorption cross sections exceed the scattering cross sections.

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I. INTRODUCTION

In recent years, a new kind of contrast agent for use in ultrasound diagnostics has been developed: suspensions of gas filled microbubbles, i.e., bubbles of at most a few micrometers in diameter [1]. The enhancement of image brightness and contrast is mostly due to the well-known fact that microbubbles of this size can have tremendous scattering cross sections for the incident diagnostic ultrasound (with frequencies around $1 - 10\text{MHz}$) [2]. A number of different theoretical approaches are present in literature, resulting in formulas for the scattering and absorption cross sections that do not always seem compatible (see e.g. [1,3–5]). It is one of the main goals of this work to show that all of these results can be understood as special cases of a unified approach which treats the bubble as a (generally nonlinear) volume oscillator. The different appearance in literature is only due to the use of different formalisms (e.g. full-fledged scattering theory with partial wave decomposition [3] or linear oscillator theory [1]) and the validity of different limiting cases (e.g. neglecting surface tension [1,3]).
The other main goal of our present study is to go beyond previous work [6], where monochromatic driving was treated, and employ pulsed driving within our formalism, in order to achieve a more realistic modeling of the situation in diagnostic applications. The analysis of the emitted sound from the bubbles in terms of intensity and spectral distribution is of obvious importance to assess the signal quality of ultrasonography with bubble contrast agents. While a large number of publications have dealt with the sound emission of linearly oscillating bubbles (see e.g. [4,5] and references therein), and the weakly nonlinear case was treated by Prosperetti [7,8], a systematic study of cross sections for strongly nonlinear response to pulsed driving has, to our knowledge, not yet been performed. It is this fully nonlinear case of bubble oscillations which is encountered in ultrasound diagnostics as driving pressure amplitudes of up to $\sim 10 \text{ atm}$ are common, whereas strong nonlinearities occur already for amplitudes $\gtrsim 1 \text{ atm}$.

We present our general, unifying approach in Section II and show in Section III how it translates to a multitude of linear limiting cases, where analytical results can be obtained if monochromatic driving is assumed. Still in the linear limit, we then introduce pulsed driving in IV and finally present results for the full nonlinear case in Section V. A more detailed discussion, especially of spectral properties of the emitted sound for nonlinear response, will be postponed to another publication [9]. Section VI presents conclusions.

II. SOUND EMISSION AND ABSORPTION

A. Emitted sound pressure

We want to evaluate the pressure of emitted sound $P_s(r,t)$ from a body capable of volume oscillations (i.e., a bubble) driven by an incident pressure wave $P(t)$. First, we notice that there are two contributions to $P_s(r,t)$: (i) the active emission of sound, caused by the change of volume of the body, and (ii) the passive contribution due to the mere presence of the (maybe non-oscillating) body in the incident field. Thus, we can write

$$P_s(r,t) = P_s^a(r,t) + P_s^p(r,t).$$

(1)

For a body of volume $V_b(t)$ which is much smaller than the wavelength of the incident sound, the pressure $P_s^a(r,t)$ of actively emitted sound is given to leading order by [3,10]

$$P_s^a(r,t) = \frac{\rho_l}{4\pi r} \frac{d^2V_b}{dt^2},$$

(2)

Here, $\rho_l$ is the liquid density and we have adopted a spherical coordinate system with radius $r$. There is no angular dependence because we have assumed the long
wavelength limit (S wave scattering). For a spherical bubble with radius dynamics $R(t)$, (2) easily translates to

$$P_{as}(r, t) = \rho_l R(t) \left( 2\ddot{R}(t)^2 + R(t)\dddot{R}(t) \right) = \frac{1}{r} q_{as}^o(t),$$

where we have introduced $q_{as}^o(t) \equiv rP_{as}^o(r, t)$, thus separating the trivial (geometrical) $1/r$ spatial dependence of the radiation from the time-dependent part.

The second term $P_p^o(r, t)$ in (1) is the pressure of passively emitted sound due to the mere presence of the body. It arises from the perturbation of the density field in water: if the body was not present, the incident sound wave could induce density changes in the volume of liquid occupied by the body. As this cannot happen, the situation is equivalent to having an oscillator that compensates the effects of the sound wave; this oscillator has a (virtual) volume change

$$\frac{dV}{dt} = V_0 \frac{d\rho_l}{dt},$$

with the (now constant) volume $V_0$ of the body, see [3]. For a sound wave $P(t)$, we have $dP/d\rho_l = c_l^2$, where the derivative is taken at constant entropy. Then, in analogy to (2), replacing $V_0$ by $V$ and inserting $V_0 = 4\pi R^3/3$, we get the leading order pressure change due to the passive reaction to the sound wave

$$P_{ps}^o(r, t) = \frac{1}{3} c_l^2 R^3 \dot{P}(t) = \frac{1}{r} q_{ps}^o(t),$$

where $c_l$ is the speed of sound in the liquid. Note again that we are in the limit $R(t) \ll \lambda$, where $\lambda$ is the wavelength of incident sound. Therefore, the driving pressure $P(t)$ can be treated as spatially uniform, i.e., the pressure experienced by the bubble does not vary over its size. In analogy to (3), we have defined the quantity $q_{ps}^o(t)$.

### B. Bubble oscillation

To evaluate (3) or (5), we need a formula for $R(t)$. The oscillatory behavior of the radius $R$ of a gas bubble in a liquid is well described by the Rayleigh-Plesset equation [11,10]. Many variants of this equation have been presented (see e.g. [12–18]); the following form has proved to be robust and close to experiment even in situations of massively nonlinear bubble behavior, as e.g. in sonoluminescence experiments [19]:

$$R\dddot{R} + \frac{3}{2}\dot{R}^2 = \frac{1}{\rho_l} (p(R, t) - P(t) - P_0) + \frac{R}{\rho_l c_l} \frac{d}{dt} p(R, t) - 4\nu_l \dot{R} - 2\zeta \frac{\dot{R}}{\rho_l \dot{R}}.$$  

We have introduced the liquid viscosity $\nu_l$ and surface tension $\zeta$ here, as well as the ambient pressure $P_0$ taken to be 1 atm in this work. All liquid parameters assume
the values of water, except for $\nu$, which is multiplied by three to mimic the viscosity of blood \cite{20}. $p(R, t)$ stands for the gas pressure inside the bubble and is modeled by a polytropic process equation with van der Waals hard core and parameters for air. The polytropic exponent is taken to be one, because bubbles of the sizes we treat here ($\sim 1 \mu m$) are smaller than the thermal diffusion length on the time scales of the oscillation, and can therefore be regarded as isothermal \cite{21,22}.

C. Scattering cross sections

In general, the scattering cross section $\sigma_{sc}$ is related to the incident intensity (energy/area/time) $I_{inc}$ and the scattered power $W_{sc}$ (energy/time) via

$$W_{sc} = \sigma_{sc} I_{inc},$$

and has thus the dimensions of an area. $I_{inc}$ is determined by the incident pressure wave $P(t)$, namely (see, e.g., \cite{3}, §65)

$$I_{inc} = \frac{1}{\rho l c l} \langle P^2(t) \rangle_t,$$

and $W_{sc}$ follows from $P_s(r,t)$ through

$$W_{sc} = \frac{4\pi}{\rho l c l} \langle r^2 P_s^2(r,t) \rangle_t = \frac{4\pi}{\rho l c l} \langle q_s^2(t) \rangle_t.$$

Here, $\langle \cdot \rangle_t$ denotes a time mean; we have exploited the virial theorem to express intensities and powers solely in terms of pressures (the “potential” part of the energy of the wave). The integral

$$E_{sc} = \frac{4\pi}{\rho l c l} \int_0^\tau q_s^2(t) dt$$

gives the total scattered energy over a time span $\tau$ (e.g. the duration of an incident sound pulse).

From these definitions, it is clear that the general formula for the scattering cross section is

$$\sigma_{sc} = \frac{4\pi}{\langle P^2(t) \rangle_t} \langle q_s^2(t) \rangle_t = \frac{4\pi}{\langle P_s^2(t) \rangle_t} \langle \left[ q_s^2(t) + q_p^2(t) \right]^2 \rangle_t.$$

We notice that the active and passive parts interfere. It is therefore, strictly speaking, wrong to divide $\sigma_{sc}$ into an active and a passive part, as it is sometimes done in literature. Nevertheless, it will be shown below that in the case of diagnostic bubbles the total scattering cross section is almost exclusively due to the active part $P_s^a$ of (1), while the passive contribution can safely be neglected.
There are other possible contributions to $P_s(r, t)$, e.g. direct or indirect results of bubble shape oscillations. These are not analyzed here because perfect sphericity is assumed. Also, there is a contribution if the bubble (or the body in general) can be translated as a whole by the incident sound. This term is orthogonal to those treated above (i.e., the interference terms vanish) and results in a well-defined additional scattering cross section (cf. [3] §78 or [1]) with a characteristic angular dependence. As it is (for the case of a gas bubble in a liquid) always of the same order of magnitude as the passive contribution, and is therefore equally negligible, we do not treat it here in detail. Finally, if two or more bubbles come close to each other, they will change the emitted sound field either by direct secondary scattering or indirectly by modifying their modes of oscillation (e.g. via secondary Bjerknes forces [23,24]). We will not try to incorporate these effects, but restrict ourselves to the case of a single bubble.

D. Absorption cross section

We have so far regarded the scattering cross section as an indicator of the acoustic energy deflected by the scatterer. Likewise, the absorption cross section $\sigma_{abs}^\nu$ stands for the energy loss induced by the viscous term in the RP equation (6). In this case the energy is directly converted into heat and will, in general, be of little use to the experimenter, whereas the scattered sound can be detected much more easily. Nevertheless, $\sigma_{abs}^\nu$ is important in order to assess the energy balance of the scattering process. The liquid viscosity exerts a stress

$$p_{vis} = \frac{4\nu_l \rho_l \dot{R}}{R}$$

over the bubble surface of size $A = 4\pi R^2$ (this can be read off directly from the RP equation). As the bubble wall moves with velocity $\dot{R}$, the dissipated power is

$$W_{dis}^\nu = p_{vis} A \dot{R} = 16\pi \nu_l \rho_l \dot{R} \dot{R}^2.$$  \hspace{1cm} (13)

The absorption cross section is determined in analogy to $\sigma_{sc}$ via

$$W_{dis}^\nu = \sigma_{abs}^\nu I_{inc}.$$ \hspace{1cm} (14)

III. SMALL DRIVING: THE LINEAR CASE

The formulas given in the previous sections can be applied to all cases of bubble motion and subsequent sound emission. For small driving, they reduce to the linear case and almost all quantities can be calculated analytically. First of all, the RP equation can be linearized: we set $R(t) = R_0(1 + x(t))$ ($R_0$ is the radius of the undriven bubble under ambient conditions) and get
\[ \ddot{x} + 2\gamma \dot{x} + \omega_0^2 x = \frac{P(t)}{\rho_l R_0^2} \]  

(15)

with the viscous damping constant \( \gamma = \frac{2\nu}{\rho_l R_0^2} \) and the bubble eigenfrequency

\[ \omega_0^2 = \frac{3\kappa_g P_0}{\rho_l R_0^2} + \frac{4\zeta}{\rho_l R_0^2}. \]  

(16)

This latter quantity consists of two distinct terms, the first due to the gas pressure \( p(R, t) \), and the second governed by surface tension \( \zeta \). For \( p(R, t) \), a polytropic ideal gas formula was chosen. While it is advisable to employ a more elaborate formula (e.g. a van der Waals gas with hard core) if the bubble oscillation is violent, the ideal gas is a very good approximation in the linear limit. The polytropic exponent \( \kappa_g \) measures the gas compressibility (\( p(R, t) \propto \rho_g^{\kappa_g} \)); it is 1 for isothermal behavior and equal to the adiabatic exponent for adiabatic behavior of an ideal gas (e.g. 7/5 for air). In deriving Eq. (15), we note that effects of thermal damping are neglected (as they have not been present in (6), either), and also radiation damping (caused in (8) by the term involving \( c_l \)) is not present. Both of these damping effects are very small in the parameter range of our interest; thus, \( \gamma \) only contains viscous damping contributions.

To get explicit solutions, let us assume monochromatic driving \( P(t) = P_a \cos \omega_d t \) in (15). \( P_a \) is the driving pressure amplitude, \( \omega_d = 2\pi f_d \) the angular driving frequency. This yields

\[ x(t) = \varepsilon \cos(\omega_d t + \delta) \]  

(17)

with the amplitude

\[ \varepsilon = -\frac{P_a}{\rho_l R_0^2} \frac{1}{\sqrt{\left(\omega_0^2 - \omega_d^2\right)^2 + 4\gamma^2 \omega_d^2}}. \]  

(18)

and the phase shift

\[ \delta = \arctan \left( \frac{2\gamma \omega_d}{\omega_d^2 - \omega_0^2} \right). \]  

(19)

Obviously, in the monochromatic case \( I_{inc} = \frac{P_a^2}{2\rho_l c_l} \). With \( R(t) \) from \( x(t) \), (3), (5), and (11) we get

\[ \sigma_{sc}^{lin} = 4\pi R_0^2 \left\langle \left[ \frac{\sqrt{2}\omega_d^2 \cos(\omega_d t + \delta)}{\sqrt{\left(\omega_0^2 - \omega_d^2\right)^2 + 4\gamma^2 \omega_d^2}} - \frac{\sqrt{2}}{3c_l^2} R_0^2 \omega_0^2 \cos \omega_d t \right] \right\rangle_t. \]  

(20)

Note that \( \sigma_{sc}^{lin} \) does not depend on the absolute size of \( P_a \), as long as the oscillation stays linear. Fortunately, in all cases of interest to bubble ultrasound diagnostics, i.e.,
FIG. 1. Numerical computation (solid line) and scaling behaviors of the normalized scattering cross section for bubbles driven with a monochromatic 50kHz sound wave at small drive amplitudes (linear case). We chose a representation similar to that of Nishi [5], displaying $\sigma_{sc}$ divided by the geometrical cross section $\pi R_0^2$ on a double logarithmic plot. To the right of the resonance peak (for large $R_0$), $\sigma_{sc}/(\pi R_0^2)$ relaxes to 4 (dot-dashed line). In the opposite limit of small $R_0$, it scales $\propto R_0^4$ (dashed) for an interval, but becomes steeper again for very small $R_0$, reaching an asymptote $\propto R_0^6$ (long dashed). These scaling laws correspond to the $R_0^6$ and $R_0^8$ behaviors of the unnormalized $\sigma_{sc}$, respectively (cf. Eqs. (23),(24)).

for frequencies in the MHz range and $R_0$ between a few tenths of a micron and a few microns, the second (passive) term of this formula is negligible compared to the first (active) part. We will show in detail below that the dominance of the active emission is so overwhelming that the relative errors in neglecting the passive contribution never exceed 0.25% in the parameter range of this study. Dropping the passive term, we get the considerably simplified expression (reproducing results presented e.g. in Leighton [4] in Section 4.1)

$$\sigma_{sc}^{\text{lin}} \approx 4\pi R_0^2 \omega_0^4 \left(\frac{\omega_d^2}{\omega_0^2} - \frac{\omega_0^2}{\omega_d^2}\right) + 4\gamma^2 \omega_d^2. \quad (21)$$

This formula can also be translated into the S wave scattering limit of the complete scattering analysis by Nishi [3]. In equation (47) of that work, there are additional contributions to $\gamma$ due to thermal and radiation damping, as well as modifications involving the stiffness of the bubble. In certain limiting cases, (21) gets further simplified. Moreover, a rich variety of scaling behaviors, especially in $R_0$, can be
found. The richness (as compared to “ordinary” linear oscillators) is due to the fact that in (15), the damping, driving frequency and dimensionless driving all depend on $R_0$. In Fig. 1 $\sigma_{sc}^{lin}$ is presented for a 50kHz-driven bubble, a frequency chosen such that most of the limiting cases treated in the following subsections can be illustrated by the graph. Note that all cross section graphs in this work were computed with the full numerical formulas presented in Section [1].

A. Small bubbles: dominance of gas pressure or surface tension

For small bubbles (such that $\omega_0 \gg \omega_d$) the denominator of the active contribution in (20) simplifies to $\omega_0^2$. It is crucial here to verify which of the two contributions to $\omega_0$ in (16) is dominant. If surface tension is very small (and $R_0$ is not extremely tiny), $\omega_0$ will be governed by the first term, i.e., the one due to the internal gas pressure. With the polytropic ansatz, we can use $c_g^2 = \kappa_g P_0/\rho_g$ for the speed of sound in the gas $c_g$ and from (20) the limiting behavior for small $R_0$ is then

$$\sigma_{sc}^{lin} \to \frac{4\pi R_0^6 \omega_d^4}{9 c_l^4} \left(1 - \frac{K_g}{K_l}\right)^2 \quad (22)$$

with the compressibilities $K_i = 1/(\rho_i c_i^2)$ for the bubble interior ($i = g$) and exterior ($i = l$). This reproduces the equations presented e.g. by Landau §78, deJong [25] or Meerbaum in Nanda/Schlief [1] (apart from the translational contribution mentioned in [1C] above). Note that in the case of gas bubbles in a liquid, $K_g$ will be much greater than $K_l$, so that to very good approximation

$$\sigma_{sc}^{lin} \to \frac{4\pi R_0^6 \omega_d^4}{9 c_l^4} \left(\frac{K_g}{K_l}\right)^2 \quad (23)$$

and the dominance of the active scattering is again confirmed. In fact, as for typical materials $\rho_l \approx 1000 \rho_g$ and $c_l \approx 5 c_g$, the active emission can surmount what would be expected from a purely passive scatterer by more than eight orders of magnitude! This is why oscillating bubbles are so much superior to (completely passive) hard spheres in terms of ultrasound scattering capability. In Fig. 1 there is indeed a region where the $\propto R_0^6$ behavior of $\sigma_{sc}^{lin}$ is observed. Note, however, that the validity of (22) and (23) for bubbles is limited, especially as surface tension is explicitly neglected.

If surface tension is taken into account and the parameters for water are inserted into (10), we see that for $R_0 \leq 0.96 \mu$m the surface tension term dominates $\omega_0$, so that $\omega_0^2 \to 4\zeta/\rho_l R_0^3$. As a consequence, the active scattering cross section will acquire a different limit, namely

$$\sigma_{sc}^{lin} \to \frac{\pi R_0^8 \omega_d^4 \rho_l^2}{4\zeta^2} \quad (24)$$

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The steeper $\propto R_0^8$ behavior takes over in Fig. 1 for very small bubbles, as expected. As the passive contributions scale like $R_0^6$, there has to be a (small) radius where the latter become dominant. This radius is easily calculated to be

$$R_0^p = \frac{4\zeta}{3\rho c_l^2}, \quad (25)$$

which, for the material constants of the water/air (blood/air) system, is $\approx 4.4 \cdot 10^{-11} m$, i.e., on a subatomic scale which is not described by the physics discussed here.

### B. Linear resonance

When $R_0$ is such that $\omega_0 \sim \omega_d$, the bubble is near resonance, i.e., its oscillation amplitude $\epsilon$ and thus $\sigma_{sc}^{lin}$ become much larger than for neighboring $R_0$. E.g., for the case of air bubbles in blood driven with $\omega_d = 2\pi \cdot 3$ MHz, it reaches values of about 15 times the geometrical cross section $\pi R_0^2$ (cf. Fig. 2 below), i.e., the normalized cross section $\sigma_{sc}^{lin}/(\pi R_0^2)$ is larger than for any other radius. From (21), it is easy to get

$$\sigma_{sc}^{lin, res} \approx \frac{\pi (R_0^{res})^6 \omega_d^2}{4\nu^2}, \quad (26)$$

where $R_0^{res}$ is determined by the condition $\omega_0(R_0^{res}) = \omega_d$. The height of the resonance peak is thus mainly determined by the strength of damping, i.e., the viscosity of the liquid. In water with its three times lower viscosity, the maximum cross section is therefore 9 times higher than in blood. The (Lorentz shaped) resonance peak is the hallmark of the classical pictures of linear bubble scattering cross sections (see [1,4,5]). We will see that this shape changes considerably in the nonlinear case.

### C. Large bubbles: the “soft sphere” limit

For large bubbles (but still obeying $R \ll \lambda$), $\omega_d \gg \omega_0$ and

$$\sigma_{sc}^{lin} \to 4\pi R_0^2, \quad (27)$$

i.e., the scattering cross section becomes four times the geometrical cross section, which is also reproduced in Fig. 1. Equation (27) describes the behavior for all $R_0$ if the bubble interior is arbitrarily compressible while surface tension is absent ($\zeta = 0$). This can be seen if we imagine $\kappa_g \to 0$ (implying $c_g \to 0$ and $K_g \to \infty$) and thus $\omega_0 \to 0$: the resonance peak is shifted to very small $R_0$ and every larger ambient radius results in the “soft sphere limit” cross section (27).

In reality, for large bubbles there are of course still the interference contributions with the passive term $\propto R_0^6$. But the influence of $P^p$ can only outweigh the active
emission for $R_0 > \sqrt{\frac{\sqrt{3}}{2\pi}} \lambda$ (which is again easy to prove); this is already in a region where the assumption $R_0 \ll \lambda$ is dubious. In fact, for diagnostic ultrasound with $\omega_d = 2\pi \cdot 3\text{MHz}$, $\lambda \approx 500\mu m$, resulting in a critical radius for passive influence of $R_0 \gtrsim 140\mu m$. Thus, there is at most a very small region of transition until the scattering cross section has to be described by completely different formulas (Mie scattering theory), and the bubbles in this region are of no interest to ultrasound diagnostics because of their size.

D. Other limits

There are a number of limiting cases of (20) and (21) that go beyond the parameter space of this study; they are given here for completeness:

- In the limit of $R_0 \gg \lambda$, the cross section relaxes to the limit $\sigma_{sc} = 2\pi R_0^2$. This is only relevant for mm-sized or even larger bubbles.

- If we apply our formulas to solid spheres in a liquid rather than bubbles, i.e., we make the interior of the “bubble” much more stiff than the liquid, the main contribution in (22) is the passive scattering, as $K_g/K_l \ll 1$. The resulting cross section is the “hard sphere” Rayleigh limit

$$\sigma_{Ra}^{sc} = \frac{4\pi}{9} \frac{R_0^6 \omega_d^4}{c_l^4}.$$  (28)

In analogy to the case of the “soft sphere” above, the resonance peak is shifted to arbitrarily large radii for an arbitrarily stiff bubble, so that here (28) is valid for every finite $R_0$.

E. The regime of ultrasound diagnostics

It is important to note that for the typical $\mu m$ size bubbles of ultrasound diagnostics applications, the relevant limiting cases of the linear formulas (20), (21) are (24), (26), and (27). The case of $\sigma_{sc}^{lin} \propto R_0^6$ given by (22) does not occur, because the resonance radii $R_{0}^{res}$ are – for MHz driven bubbles – in the range of the crossover ambient radius $R_0 \approx 0.96 \mu m$ between gas pressure and surface tension dominated resonances. Thus, the oscillations of bubbles with $R_0 < R_{0}^{res}$ are all surface tension dominated, and never show the $R_0^6$ behavior. This is obvious in Fig. 4, which shows the linear cross sections for 3MHz driven bubbles in blood. In contrast to Fig. 4 there is a direct transition from the resonance peak to a curve $\sigma_{sc}^{lin} \propto R_0^8$. 

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FIG. 2. Numerical computation (solid lines) and scaling behaviors of the normalized linear scattering (thick lines) and absorption (thin lines) cross sections for bubbles driven with a monochromatic 3MHz sound wave (diagnostic frequency). The resonance features as well as the large $R_0$ limit of 4 (dot-dashed) are again present in $\sigma_{sc}/(\pi R_0^2)$. Of the small $R_0$ limits, only the surface tension governed $\sigma_{sc}^{lin} \propto R_0^5$ remains (long dashed). The corresponding scaling laws for $\sigma_{abs}^{lin}/(\pi R_0^2)$ are $\propto R_0^{-1}$ (dashed) for large and $\propto R_0^3$ (long dashed) for small $R_0$.

F. Linear absorption cross sections

The linear analysis is naturally extended to absorption cross sections; the analytical formula for $\sigma_{abs}^{\nu}$ in the case of monochromatic driving is easily found via (14) and (11)–(13) to be

$$
\sigma_{abs}^{\nu,lin} = \frac{16\pi \nu \ell c_l}{R_0} \frac{\omega_d^2}{(\omega_0^2 - \omega_d^2)^2 + 4\gamma^2 \omega_d^4}.
$$

Here, the limiting cases for small bubbles show $\sigma_{abs}^{\nu,lin} \propto R_0^3$ for small $R_0$ for gas pressure dominated $\omega_0$ and $\sigma_{abs}^{\nu,lin} \propto R_0^5$ for the surface tension dominated case (see Fig. 2). Thus, $\sigma_{abs}^{\nu,lin} \gg \sigma_{sc}^{lin}$ for small bubbles, i.e., most of the energy incident on the bubble is converted into heat through viscous damping, whereas only a small part is available for sound emission. The already surprisingly high scattering cross section for microbubbles is outnumbered considerably by the absorption cross section. The same is true in resonance, where
\[
\frac{\sigma_{abs}^{\nu,lin,res}}{\sigma_{sc}^{lin,res}} \approx \frac{4\nu_c c_l}{(P_{res}^{0})^3 \omega_d^2} \approx 23
\]

can be calculated for \( f_d = 3 \text{MHz} \) and the material constants of blood, in very good agreement with numerical computation (cf. Fig. 4).

For large \( R_0 \) above the resonance radius we have \( \sigma_{abs}^{\nu,lin} \propto R_0^{-1} \); as \( \sigma_{sc}^{lin} \) grows like \( R_0^2 \), we have in this range \( \sigma_{abs}^{\nu,lin} \ll \sigma_{sc}^{lin} \), and the major part of the energy goes into sound emission.

IV. PULSED DRIVING

A. The incident pulse

One assumption that allowed us to give simple analytical formulas was the monochromaticity of the driving. In reality, bubbles in ultrasound diagnostics are driven by the signal of a diagnostic transducer, which is almost always pulsed, and quite often (e.g. in pulse wave doppler mode) the pulses are only a few wavelengths long.

In closer agreement with experimental reality, we therefore model the pressure pulse \( P(t) \) as

\[
P(t) = P_a \cos(\omega_d(t - t_c)) \exp\left(-\frac{h^2 \omega_d^2}{4}(t - t_c)^2\right),
\]

centered around \( t_c \) with relative width \( h \). We choose \( h = 1/3 \) here. After Fourier transform, the frequency space representation is

\[
P(\omega) = \frac{P_a}{h \omega_d} \left[ \exp\left(-\frac{(\omega - \omega_d)^2}{h^2 \omega_d^2}\right) + \exp\left(-\frac{(\omega + \omega_d)^2}{h^2 \omega_d^2}\right) \right].
\]

This spectrum is (almost) Gaussian in shape; the corresponding power \( \propto |P(\omega)|^2 \) decays to \( 1/e^2 \) of its maximum value within a distance of \( \pm h \omega_d \) around \( \omega_d \) (cf. Fig. 3). Thus, the reciprocal \( 1/h \) of the relative width is an approximate measure for the spatial extension of the pulse (in wavelengths). In our example, the pulse is about 3 wavelengths long and corresponds to the shortest pulses routinely available in medical applications of diagnostic ultrasound.

B. Effects on the cross sections

As we are still in the linear limit, the pulsed driving can be understood as a superposition of monochromatic waves of frequency \( \omega \) with amplitudes proportional to the Fourier components \( P(\omega) \) in (32). The response will be therefore obtained
FIG. 3. Modeled ultrasound diagnostics driving pulse. The upper part of the figure shows the time series $P(t)$ ($t$ normalized to $T \equiv 1/f_d$), the lower part the normalized Fourier spectrum of the acoustic power given by $P(t)$. It is centered around the mean frequency $f_d = 3$ MHz and decays to $1/e^2$ of its maximum value within $hf_d = f_d/3 = 1$ MHz above and below $f_d$. This corresponds to the effective spatial extent of the pulse of $\approx 3$ wavelengths.

from a convolution of the monochromatic response discussed above and the spectrum $P(\omega)$.

Figure 4 shows the cross sections $\sigma_{ac}(R_0)$ and $\sigma_{abs}(R_0)$ for monochromatic and pulsed driving in comparison. The figure is a blow-up of the region near $R_0^{res}$, which is the only area where there are marked differences between the responses to the different drivings. As it may have been expected, the response curves for polychromatic driving are broader, because unlike the monochromatic case, where the single frequency $\omega_d$ corresponds to a single, well-defined $R_0^{res}$, there are a number of $R_0$ for which the bubbles react strongly to the most intense frequency components in $P(\omega)$. Correspondingly, a bubble driven at resonance by a monochromatic wave is a more effective scatterer than for pulsed driving, so that the maximum height of the cross section curves is smaller in the latter case.

Moreover, with pulsed driving there is a slight, but significant shift in the maximum of both cross sections towards larger $R_0$. This is due to the asymmetry in the response curve around the resonance radius that is apparent already in the monochro-
matic case (cf. Fig. 4): on increasing $R_0$ from $R_0^{res}$, the cross sections do not drop as rapidly as when $R_0$ is decreased from the maximum of the curves. Therefore, the contributions in $P(\omega)$ with $\omega$ slightly smaller than $\omega_d$ (which correspond to $R_0(\omega) > R_0^{res}(\omega_d)$) will have a larger effect on $\sigma_{sc}$ and $\sigma_{abs}^\nu$ than the contributions with $\omega$ slightly smaller than $\omega_d$, even if they are represented with the same weight in $P(\omega)$. Consequently, upon convolution of the spectrum, the cross sections are increased for the larger $R_0$ and the maximum of the curves is shifted towards $R_0 > R_0^{res}(\omega_d)$.

![Graph](image)

**FIG. 4.** Scattering (thick lines) and absorption (thin lines) cross sections for bubbles driven by a monochromatic 3 MHz sound wave (dashed) and a diagnostic pulse according to (31) with center frequency 3 MHz (solid). The response to the polychromatic driving displays a broader, lower resonance peak, which is shifted towards larger $R_0$. Further away from resonance, the differences to the monochromatic case soon become negligible.

If the width of the pulse is varied, the peak shift and peak broadening vary correspondingly: thus, if the pulse becomes very short (shorter than one wavelength), the resonance structure is almost completely lost. Using longer and longer wave-trains (smaller $h$), on the other hand, leads to successively sharper resonance peaks, while the repetitive oscillations of the bubble allow for the occurrence of subharmonic resonances, provided that the bubbles remain shape stable (cf. [4]).

**V. RESULTS OF FULL NONLINEAR COMPUTATIONS**

Let us now come back to the general formulas presented in Section II and drop the assumption of linear response. We will find that the features of the nonlinear case can
be quite different from the linear results presented above. Not surprisingly, the cross sections now depend on the driving pressure amplitude $P_a$, which is not the case for linear driving. It should be noted that, in order to compare these results with experimental measurements, they have to be convoluted with the bubble size distribution, as in virtually all experiments the bubble suspensions are not monodisperse.

A. Scattering cross sections

With $P(t)$ given by (31), $I_{inc}$ can be computed, so that with (4), (8) and (7–9), $\sigma_{sc}$ results. Let us first convince ourselves that the passive part of (4) is tiny in the nonlinear case, too. In Fig. 5 we present the relative errors made in determining scattering cross sections from $P^a_s(r,t)$ (or $q^a_s(t)$) alone rather than from the full interference formula (11). It is easy to see that these errors are nowhere greater than about 0.25%, and in most cases much smaller. The huge advantage of (actively emitting) bubbles as scatterers compared to stiff solid bodies of similar size is here once more strikingly demonstrated. For computational simplicity, the cross sections presented in the following figures were computed using only the active emission part.

![Figure 5](image)

**FIG. 5.** Relative error of scattering cross section computations with and without passive emission taken into account. The numerical calculations were performed using the complete formula (11) with or without the passive contribution and driving with an ultrasound diagnostics pulse according to (31). The curves correspond to driving pressure amplitudes $P_a$ of $1 - 10$ atm, in steps of 1 atm. The error is nowhere greater than about 0.25%.

Fig. 6 shows the normalized cross sections for various $R_0 \in \{0.1 \mu m, 5.0 \mu m\}$ and
$P_a = 1 - 10 \text{atm}$ (in 1 atm intervals). These values represent typical bubble sizes found in diagnostic bubble suspensions (often the size distribution shows a peak around $R_0 \approx 1 \mu m$) and typical sound pressure amplitudes in the focus of clinical ultrasound devices. From linear analysis, we know what the cross sections for $P_a \to 0$ look like. This curve is readily reproduced for small $P_a$. While the curve for 1 atm is still essentially unaltered compared to the linear case, there are dramatic changes in $\sigma_{sc}(R_0)$ with higher $P_a$. E.g., the resonance radius $R_{0}^{\text{res}}$ undergoes a shift away from its linear value to smaller $R_0$, i.e., in the opposite direction of the shift induced by the polychromatic pulse. This shift is explained by the nonlinearity of the oscillator (cf. [26]): when expanding the RP equation up to nonlinearities of third order, one obtains for the nonlinear eigenfrequency

$$\omega_{0}^{NL} = \omega_{0} + a^2 \left( \frac{3\beta}{8\omega_0} - \frac{5a^2}{12\omega_0^3} \right),$$

with the amplitude $a$ of the oscillation and

$$\alpha = -\left( 2\omega_0^2 - \frac{2\zeta}{\rho l R_0} \right), \quad \beta = \frac{10}{3}\omega_0^2 + \frac{14\zeta}{3\rho l R_0}. \quad (34)$$

It is easy to see that with these values we always have $\omega_0^{NL} < \omega_0$, i.e., the bubble is an oscillator with a soft potential. With stronger nonlinearity, $\omega_{0}^{NL}$ becomes smaller for a given $R_0$; in order to be in resonance, we require $\omega_d = \omega_{0}^{NL}$ with constant $\omega_d$. Therefore, $R_0$ must be decreased in order to increase $\omega_0$ beyond $\omega_d$ to ensure that the resonance condition $\omega_d = \omega_{0}^{NL}$ is again fulfilled. Thus, the nonlinear resonance radius $R_0^{\text{res,NL}}$ is smaller than its linear counterpart. Note also that the resonance structure is blurred especially for high driving; this is in contrast to the case of monochromatic driving [6], where well-defined resonance radii can be recognized up to the highest $P_a$.

A most striking feature of Fig. 6 is the tremendously enlarged scattering cross section, especially at radii smaller than the linear resonance radius (i.e., in the region of nonlinear resonance). Sometimes, $\sigma_{sc}$ is greater by several orders of magnitude compared to the linear case (note the logarithmic scale). Only for $R_0 \gg R_0^{\text{res,lin}}$ is the shape of the curve virtually unaltered. Thus, the scattering cross sections for small bubbles (below $\approx R_0 = 1 \mu m$) are severely underestimated by the linear theory.

The reason for this effect is found in the typical $R(t)$ radius dynamics of nonlinearly driven bubbles: when $P_a$ is sufficiently high, they undergo violent collapsing instead of just a smooth oscillation. This leads to high velocities and extraordinarily high accelerations of the bubble wall, exceeding $10^9 g$ in the solutions of (6) for the highest $P_a$ of our study (even larger accelerations are known in other contexts of bubble dynamics, see [19]). These values of $\dot{R}$ and especially $\ddot{R}$, which far exceed those expected for linear response, lead to very high active emission pressures (cf. Eq. (3)) and thus to a huge $\sigma_{sc}$. 

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FIG. 6. Total scattering cross sections of bubbles driven by ultrasound pulses. From bottom to top: $P_a = 1 - 10$ atm in steps of 1 atm. The linear profile of $\sigma_{sc}$ is drastically changed for high $P_a$, the resonance radius shifts to smaller $R_0$ due to nonlinearities and the cross sections are much larger around the resonance radius than in the linear case (up to 3-4 orders of magnitude).

B. Absorption cross sections

In Fig. 7 the viscous absorption cross section $\sigma_{abs}'$ computed from (13) and (14) is shown for the same parameter combinations as for $\sigma_{sc}$ in Fig. 6. As expected, the resonance peak undergoes similar nonlinear shifting. However, although $\sigma_{abs}'$ also shows a tendency to grow for higher $P_a$, it is obvious that its dependence on driving pressure amplitude is nowhere near as dramatic as in the case of the scattering cross section. This is because in the computation of $W_{dis}'$ via (13), only the velocity $\dot{R}$ is present, but not the acceleration, which is responsible for the tremendous sound emission, as argued in the previous section. As usual, the radiative processes are connected with acceleration, while the dissipative processes are governed by velocity. For high $P_a$ we can therefore conclude that – regardless of the size of the bubble – most of the incident sound energy is scattered again into sound, and not dissipated via viscous forces.
FIG. 7. Total viscous absorption cross sections of bubbles driven by ultrasound pulses. From bottom to top: \( P_a = 1 - 10 \text{ atm} \) in steps of 1 atm. The change in shape with growing \( P_a \) is not as drastic as for the scattering cross sections. \( \sigma_{\text{abs}}' \) is considerably smaller than \( \sigma_{\text{sc}} \) for the highest \( P_a \), while it is much larger in the linear case of small driving.

C. Secondary absorption

It is tempting to conclude that for the highest \( P_a \) we have the optimal situation for detection of scattered sound. This is not necessarily so, however, because of the spectrum of the emitted acoustic radiation. We show in a separate paper [29] that the most strongly driven bubbles emit sound in a spectrum of immense bandwidth, with a large portion of the energy in the ultra high frequency part (GHz). These frequencies are readily absorbed (on a length scale of cm or less) by water or other media (blood, tissue) frequently encountered in diagnostic applications (cf. e.g. [27,28]). With this absorption, most of the sound energy is converted into heat. Fig. 8 shows the example of the effectively detected scattered sound after the pulses have traveled through a 5 cm layer of water. The absorption properties of water are well known: the energy contained in every Fourier component (frequency \( f = \omega/2\pi \)) of the emitted sound signal decays over a distance \( r \) like

\[
E_s(r, f) = E_s(0, f) \exp(-\alpha_w f^2 r),
\]

(35)

with the known characteristic absorption coefficient of water \( \alpha_w \approx 1.5 \times 10^{-14} \text{s}^2/\text{m} \) [29]. Thus, the highest frequency components experience the strongest damping, and it is especially the high-power, high-frequency emission of scatterers at small \( R_0 \) which
is radically diminished by this process, although the cross sections do not drop to or near their linear values. The implications for diagnostics, such as possible risks of the heat deposition connected with the absorption, are dealt with in separate work [9].

![Figure 8](image_url)

**FIG. 8.** Effective scattering cross sections of bubbles driven by ultrasound pulses and separated from the detector by a water layer of 5cm width, which acts to damp out high frequency sound according to (35). From bottom to top: \( P_a = 1 - 10 \) atm in steps of 1 atm. The growth for large \( P_a \) is much diminished here as compared to Fig. 6. The high frequency components of the sound emitted by the small bubbles at high \( P_a \) are absorbed in water and thus the major part of the emitted sound energy is lost to the detector.

VI. SUMMARY AND CONCLUSIONS

We have presented a unified view of gas bubble sound scattering and absorption. Starting from the description of the bubble as a nonlinear oscillator, general formulas have been developed that can be shown to transform, in certain limiting cases, into a number of apparently discrepant formulas found in literature, whether they be derived from oscillator theory [4], scattering theory [5] or the theory of solid body sound scattering [3]. It is important to state that there is no antagonism between “scattering” and “active sound emission”. Both terms refer to the sound that can be detected after incident sound has hit a gas bubble. The total scattering cross section does contain a contribution of passive sound emission, but this contribution is tiny and can always be neglected for situations in ultrasound diagnostics. Bubbles driven in the nonlinear range show a much larger scattering cross section than in the linear case and
are more “actively” emitting sound in the sense that the incident energy is primarily converted into sound and not into viscous heating, as is the case for linear driving. The most prodigiously radiating bubbles, at small radii and large driving amplitude, emit such high frequency sound that it is again absorbed by the surrounding medium and leads to secondary heating. The effective yield of scattered sound energy is therefore much smaller than what would be expected without taking absorption into account. Still, the ultrasound scattering capabilities of bubbles and therefore their effectiveness as a contrast agent in diagnostics are considerably enhanced due to the nonlinearity of the oscillations.

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