On Technique for Generating Pareto Optimal Solutions of Multi-objective Linear Programming Problems

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Abstract: Subjective selection of weights in method of combining objective functions in a multi – objective programming problem may favour some objective functions and thus suppressing the impact of others in the overall analysis of the system. It may not be possible to generate all possible Pareto optimal solution as required in some cases. In this paper we develop a technique for selecting weights for converting a multi-objective linear programming problem into a single objective linear programming problem. The weights selected by our technique do not require interaction with the decision makers as is commonly the case. Also, we develop a technique to generate all possible Pareto optimal solutions in a multi-objective linear programming problem. Our technique is illustrated with two and three objective function problems.

Keywords: Multi-objective, Single Objective, Linear Programming, Pareto Optimal Solution, Weight, Non-inferior Solution

1. Introduction

There is increasing interest in research in the area of multi-objective programming. [1] presents an alternative method based on fuzzy programming for solving multi-objective linear bi-level multi-follower programming problem in which there is no sharing of information among followers; a multi-objective programming model for selecting third – party logistics companies and suppliers in a closed-looped supply chain was proposed in [2-3] proposed a fuzzy robust programming approach to multi-objective portfolio optimization problem under uncertainty and lot more.

A feasible solution to a multi-objective linear programming problem is considered to be optimal if it is better than any other feasible solution for all linear programming problems that constitute the multi-objective programming problem. But such an optimal solution to a multi-objective programming problem does not always exist and we must compromise in our analysis of the problem. We desire to obtain variety of good, but not necessarily optimal solutions.

A good but, not necessarily optimal solution to a multi-objective linear programming problem is known as efficient or non-inferior or Pareto optimal solution. In other words, a solution to a multi-objective linear programming problem is said to be efficient if it is not possible to improve some objective function values at expense of others. Such solutions are infinitely many and so interest is always on generating some of them.

Generally, solution methods of multi-objective linear programming problems may be classified into three groups, viz:priori, interactive, and posterior methods [4]. In a priori method, the decision maker states his preferences before selecting weights for converting several objective functions to form single objective function. The pitfall of this method is that it is not easy for the decision maker to accurately quantify his preferences prior to optimization [5].

In the interactive method, the full preference structure of the decision maker is not postulated a priors but is implicitly revealed in response to a simple question and answer procedure with the decision maker. Interactive method is characterized by phases of decision making alternating with phases of computation. The problem with this method is that the decision maker never sees the whole picture of the optimal solution set, so his decisions are dependent on what he already preferred at each stage of the optimization.
process. For detail interactive methods the reader is referred to [6-13].

In the posterior method, all the solutions are generated and presented before the decision maker who will either accept or reject it [14]. This method has advantage over the other two in the sense that the decision maker may or may not be present while the optimization procedure is ongoing and no potential optimal solution will be left out. A simplex based approach known as non-dominance subroutine to determine all non-inferior basic solutions to multi-objective programming problems was developed in [15]. The problems with the simplex based approach are that, it is too lengthy and requires a lot of bookkeeping.

In most cases, method of converting multi-objective linear programming problem into a single objective linear programming problem is often used because the solution procedure is already known. Subjective selection of weights in method of combining objective functions may favour some objective functions and thus suppressing the impact of others in the overall analysis of the system. It may not be possible to generate all possible Pareto optimal solution as required in some cases.

In this paper we present a technique for weights determination that does not involve interaction with the decision maker while the optimization process is ongoing, and also the procedure for the generation of all Pareto optimal solutions is presented.

2. Methodology

2.1. General Multi-objective Linear Programming Problem

The general Multi-objective linear programming problem is stated as

\[
P_1 \quad \text{max } z_1 = \sum_{j=1}^{n} c_{1j} x_j
\]

\[
\text{max } z_2 = \sum_{j=1}^{n} c_{2j} x_j
\]

\[\vdots\]

\[
\text{max } z_p = \sum_{j=1}^{n} c_{pj} x_j
\]

Subject to:

\[
\sum_{j=1}^{n} a_{ij} x_j \leq b_i, \quad i = 1, 2, \ldots, m
\]

\[x_j \geq 0, \quad j = 1, 2, \ldots, n\]

2.2. Weights Determination

Selecting adequate weights in multi-objective linear programming problem is not always easy. One method of doing this is through the use of utility function. If utility function \(U(x)\) is known, one can select weight \(w_k\) through

\[
w_k = \frac{u^k(x)}{\sum_{k=1}^{p} u^k(x)}, \quad k = 1, 2, \ldots, p
\]

[16] proposed the following utility functions

\[
u(x) = \prod_{k=1}^{p} z_k
\]

\[
u(x) = \sum_{k=1}^{p} z_k
\]

\[
u(x) = e^{\sum_{k=1}^{p} z_k}
\]

\[
u(x) = \log \prod_{k=1}^{p} z_k
\]

Theorem 1:

Let \(x^k, k = 1, 2, \ldots, p\) be optimal solutions to \(p\) single objective linear programming problems \(LP_1, LP_2, \ldots, LP_p\), respectively. Let \((z_1^k, z_2^k, \ldots, z_p^k)\), \(k = 1, 2, \ldots, p\) be the corresponding points in the objective function space. Then the appropriate weights \(w_k, k = 1, 2, \ldots, p\) that will give additional Pareto optimal solution are given by

\[
w_k = \frac{|C_{1k}|}{\sum_{k=1}^{p} |C_{1k}|}, \quad k = 1, 2, \ldots, p
\]

Proof:

First, we consider a two objective functions case (i.e \(p = 2\)). Let \(x^1\) and \(x^2\) be the optimal solutions to single objective linear programming problems \(LP_1\) and \(LP_2\), respectively. Let \((z_1^1, z_2^1)\) and \((z_1^2, z_2^2)\) be the corresponding points in the objective function space. Then the line segment joining these points is given as

\[
z = \frac{z_2^2 - z_1^2}{z_1^2 - z_1^1} z_1^1 + z_2^1
\]

Now adding the coefficients of \(Z_1\) and \(Z_2\) in equation (7), we obtain

\[
\frac{z_2^2 - z_1^2}{z_1^2 - z_1^1} + 1 = \frac{(z_2^2 - z_1^1) + (z_2^1 - z_1^1)}{z_1^2 - z_1^1}
\]

After a little rearrangement, we obtain
\[
\frac{z_2^2 - z_1^2}{(z_2^2 - z_1^2) + (z_1^2 - z_3^1)} + \frac{z_1^2 - z_3^1}{(z_2^2 - z_1^2) + (z_1^2 - z_3^1)} = 1 \tag{8}
\]

Clearly,

\[
w_1 = \frac{z_2^2 - z_1^1}{(z_2^2 - z_1^2) + (z_1^2 - z_3^1)}
\]

\[
w_2 = \frac{z_1^2 - z_3^1}{(z_2^2 - z_1^2) + (z_1^2 - z_3^1)}
\]

To ensure that \(w_1\) and \(w_2\) are nonnegative, we set

\[
w_1 = \frac{z_2^2 - z_1^1}{z_2^2 - z_1^1 + z_1^2 - z_3^1} = \frac{C_{11}}{C_{11} + C_{12}} \tag{9}
\]

\[
w_2 = \frac{z_1^2 - z_3^1}{z_2^2 - z_1^1 + z_1^2 - z_3^1} = \frac{C_{12}}{C_{11} + C_{12}} \tag{10}
\]

Where \(C_{1k}, k = 1, 2\) are the cofactors of the elements in row 1 of the matrix

\[
Z = \begin{pmatrix}
  z_1 - z_1^1 & z_2 - z_2^1 & z_3 - z_3^1 \\
  z_1^1 - z_1 & z_2^1 - z_2 & z_3^1 - z_3
\end{pmatrix}
\]

Now, for \(p = 3\), let \(x_1^1, x_2^1\) and \(x_3^1\) be optimal solutions to the three single objective linear programming problems \(LP_1, LP_2\) and \(LP_3\), respectively.

Let \((z_1^1, z_2^1, z_3^1), (z_1^2, z_2^2, z_3^2)\) and \((z_1^3, z_2^3, z_3^3)\) be the corresponding points in the objective function space. Then the plane passing through these points is given by the equation

\[
\begin{vmatrix}
  z_1 - z_1^1 & z_2 - z_2^1 & z_3 - z_3^1 \\
  z_1^2 - z_1 & z_2^2 - z_2 & z_3^2 - z_3 \\
  z_1^3 - z_1 & z_2^3 - z_2 & z_3^3 - z_3
\end{vmatrix} = 0 \tag{11}
\]

Evaluating the determinant in equation (11), we obtain the equation of the plane as

\[
c_{11}z_1 + c_{12}z_2 + c_{13}z_3 = d \tag{12}
\]

Where

\[
d = c_{11}z_1^1 + c_{12}z_2^1 + c_{13}z_3^1
\]

and \(C_{1k}, k = 1, 2, 3\) are the cofactors of the elements in row 1 of the matrix

\[
Z = \begin{pmatrix}
  z_1 - z_1^1 & z_2 - z_2^1 & z_3 - z_3^1 \\
  z_1^1 - z_1 & z_2^1 - z_2 & z_3^1 - z_3 \\
  z_1^3 - z_1 & z_2^3 - z_2 & z_3^3 - z_3
\end{pmatrix}
\]

Dividing equation (10) through by \((c_{11} + c_{12} + c_{13})\), we obtain

\[
w_1z_1 + w_2z_2 + w_3z_3 = d' \tag{13}
\]

Where

\[
w_2 = \frac{c_{1k}}{c_{11} + c_{12} + c_{13}} \quad \text{and} \quad d' = \frac{d}{c_{11} + c_{12} + c_{13}}
\]

To ensure that \(w_k\) is nonnegative, we set

\[
w_k = \frac{C_{1k}}{\sum_{k=1}^{p} C_{1k}}, \quad k = 1, 2, \ldots, p
\]

The above results can easily be extended to \(p \geq 3\) objective functions problem as follows:

2.3. Finding Additional Pareto Optimal Solution in a Two–Objective Problem

In order to find additional Pareto optimal solution (if one exists) in a two–objective linear programming problem, we could try to move the line segment joining \(x_1^1\) and \(x_2^1\) in the direction of arrow in figure 1. Algebraically, this means solving the single objective function problem \(P_3\).

\[
P_3: \max \{z = w_1z_1 + w_2z_2\}
\]

Subject to:

\[
\sum_{j=1}^{n} a_{ij}x_j \leq b_i, \quad i = 1, 2, \ldots, m
\]

\[
x_j \geq 0, \quad j = 1, 2, \ldots, n
\]

Lemma 1:

The set of non-inferior points is connected [17]

Lemma 2:

If \(x_1^1\) and \(x_2^1\) are two adjacent non-inferior points, then their convex combination is non-inferior [17]

Lemma 3:

If \(x_1^1\) and \(x_2^1\) are two non–adjacent non-inferior points, then there exists at least one non–inferior point in the range \((x_1^1, x_2^1)\) [17]

Theorem 2:

If \(x_1^1\) and \(x_2^1\) are nonadjacent Pareto optimal solutions, then the solution of problem \(P_3\) is an additional Pareto optimal solution of problem \(P_1\).

Proof:

By connectivity of Pareto optimal solutions, if \(x_1^1\) and \(x_2^1\) are nonadjacent, then there exists at least one Pareto optimal solution between them. The objective function in problem \(P_3\) is a line joining \(x_1^1\) and \(x_2^1\) in the objective space; hence the
optimal solution of problem P3 is a Pareto optimal solution of problem P1. Figure 1 illustrates theorem 2.

**Theorem 3:**
If $x_1$ and $x_2$ are adjacent Pareto optimal solutions, then the optimal solutions of problem P3 will be on the line segment joining $x_1$ and $x_2$ in which case $x_1$ and $x_2$ are the only Pareto optimal solution.

**Proof:**
Since Pareto optimal solutions are connected and if $x_1$ and $x_2$ are adjacent there does not exist any Pareto optimal solution between them; hence solutions of problem P3 are $x_1$ and $x_2$. Figure 2 illustrates theorem 3.

**Remark 1:**
Supposing an additional Pareto optimal solution $x_3$ has been found using known solutions $x_1$ and $x_2$, one can investigate the existence of another Pareto optimal solution by using known solutions $x_1$ and $x_3$ as well as $x_2$ and $x_3$. We can continue this process until all the Pareto optimal solutions are found.

**Remark 2:**
In order to find an additional Pareto optimal solution (if one exists) given $p$ Pareto optimal solutions $x_k$, $k = 1, 2, \ldots, p$ in a $p$ - objective linear programming problem, we solve the scalar problem P4.

\[
P4: \text{max} \{z = \sum_{k=1}^{p} w_k z_k \}
\]

Subject to:

\[
\sum_{j=1}^{n} a_{ij} x_j \leq b_i, \quad i = 1, 2, \ldots, m
\]

\[
x_j \geq 0, \quad j = 1, 2, \ldots, n
\]

**Remark 3:**
If the solution $x^{p+1}$ of P4 is an additional Pareto optimal solution to problem P1, then one can investigate the existence of another Pareto optimal solution by replacing one of the previous $p$ Pareto optimal solutions with $x^{p+1}$ and solving problem P4 again. The process continues until all the Pareto optimal solutions are found.

**Example 1:** (illustrating two objective functions problem)

LP1 Maximize $Z_1 = -8x_1 + x_2$

LP2 Maximize $Z_2 = 10x_1 + 3x_2$

Subject to:

\[
5x_1 + 3x_2 \leq 15
\]

\[-4x_1 + 2x_2 \leq 8
\]

\[x_1 \leq 2\]

\[x_2 \leq 4.2\]

\[x_1, x_2 \geq 0\]

First, we solve single objective function problems LP1 and LP2 to obtain two extreme Pareto optimal solutions shown in the Table 1.

| $x_1$ | $x_2$  | $Z_1$  | $Z_2$  | $w_1 Z_1 + w_2 Z_2$ |
|-------|--------|--------|--------|---------------------|
| 0     | 4      | 4      | 12     | 2.44x_1 + 2.16x_2   |
| 2     | 1.7    | -14.3  | 25.1   |                     |

We then solve the following scalar problem

Maximize $Z = 2.44x_1 + 2.16x_2$

Subject to:

\[
5x_1 + 3x_2 \leq 15
\]

\[-4x_1 + 2x_2 \leq 8
\]

\[x_1 \leq 2\]

\[x_2 \leq 4.2\]

\[x_1, x_2 \geq 0\]

The solution of the scalar problem is $x_3 = (0.48, 4.2)$ which is additional Pareto optimal solution. Now, we investigate the existence of another Pareto optimal solution by considering $(x_1, x_3)$ and $(x_2, x_3)$. Using $(x_1, x_3)$ we obtain the results in Table 2.

| $x_1$ | $x_3$  | $Z_1$  | $Z_2$  | $w_1 Z_1 + w_2 Z_2$ |
|-------|--------|--------|--------|---------------------|
| 0     | 4.8    | -0.8   | 1.8    |                     |
| 0.48  | 4.2    | 0.36   | 17.4   |                     |

The scalar problem is

Maximize $Z = -0.8x_1 + 1.8x_2$

Subject to:

\[
5x_1 + 3x_2 \leq 15
\]

\[-4x_1 + 2x_2 \leq 8
\]

\[x_1 \leq 2\]
The solution of the scalar problem is $x^4 = (0.1, 4.2)$ which is additional Pareto optimal solution. Now, we investigate the existence of another Pareto optimal solution by considering $(x^2, x^4)$.

Table 3. Combing objective functions of LP1 and LP2 using $(x^2, x^3)$.

| $x^1 = (x_1, x_2)$ | $(Z_1, Z_2)$ | $(w_1, w_2)$ | $Z = w_1Z_1 + w_2Z_2$ |
|---------------------|-------------|-------------|----------------------|
| $(2, 1.7)$          | (-14.3, 25.1) | (0.34, 0.66) | $Z = 3.88x_1 + 2.32x_2$ |
| $(0.48, 4.2)$       | (0.36, 17.4)  |             |                      |

The solution of the scalar problem is $x^4 = (0.1, 4.2)$ which is additional Pareto optimal solution. Now, we investigate the existence of another Pareto optimal solution by considering $(x^2, x^4)$.

Table 3. Combing objective functions of LP1 and LP2 using $(x^2, x^3)$.

| $x^1 = (x_1, x_2)$ | $(Z_1, Z_2)$ | $(w_1, w_2)$ | $Z = w_1Z_1 + w_2Z_2$ |
|---------------------|-------------|-------------|----------------------|
| $(2, 1.7)$          | (-14.3, 25.1) | (0.34, 0.66) | $Z = 3.88x_1 + 2.32x_2$ |
| $(0.48, 4.2)$       | (0.36, 17.4)  |             |                      |

The solution of the scalar problem is $x^4 = (0.1, 4.2)$ which is additional Pareto optimal solution. Now, we investigate the existence of another Pareto optimal solution by considering $(x^2, x^4)$.

Table 4. Combing objective functions of LP1 and LP2 using $(x^1, x^2, x^3)$.

| $x^1 = (x_1, x_2)$ | $(Z_1, Z_2, Z_3)$ | $(w_1, w_2, w_3)$ | $Z = w_1Z_1 + w_2Z_2 + w_3Z_3$ |
|---------------------|---------------------|---------------------|-----------------------|
| $(0, 4)$            | (4, 12, 7.2)        | (0.241, 0.235, 0.525) | $Z = 0.002x_1 + 8.236x_2$ |
| $(2, 1.7)$          | (-14.3, 25.1, 4.66) |                      |                      |
| $(0.48, 4.2)$       | (3.4, 13.6, 7.64)   |                      |                      |

We compute the cofactors $c_{1k}$ from the determinant in equation (9) thus:

\[
\begin{align*}
c_{11} &= \left[ \begin{array}{cc}
Z_1^2 - Z_2^1 & Z_3^2 - Z_3^1 \\
Z_2^2 - Z_2^1 & Z_3^2 - Z_3^1
\end{array} \right] = \begin{bmatrix} 13.1 & -2.54 \\ 1.6 & 0.44 \end{bmatrix} = 9.83 \\
c_{12} &= \left[ \begin{array}{cc}
Z_1^2 - Z_2^1 & Z_3^2 - Z_3^1 \\
Z_2^2 - Z_2^1 & Z_3^2 - Z_3^1
\end{array} \right] = \begin{bmatrix} -18.3 & -2.54 \\ -0.6 & 0.44 \end{bmatrix} = -9.58 \\
c_{13} &= \left[ \begin{array}{cc}
Z_1^2 - Z_2^1 & Z_3^2 - Z_3^1 \\
Z_2^2 - Z_2^1 & Z_3^2 - Z_3^1
\end{array} \right] = \begin{bmatrix} -18.3 & 13.1 \\ -0.6 & 1.6 \end{bmatrix} = -21.42
\end{align*}
\]

Then from equation (8) we obtain the weights: $w_1 = 0.241$, $w_2 = 0.235$, $w_3 = 0.525$.

The solution of the scalar problem is $x^4 = (0.1, 4.2)$. We now investigate the existence of additional Pareto optimal solution by considering the solutions $(x^1, x^2, x^3)$, $(x^1, x^2, x^4)$ and $(x^2, x^3, x^4)$. None of these give additional solution.

3. Conclusion

We have developed formulas for determining appropriate weights for combining objective functions in multi-objective linear programming problems. A solution scheme for generating all Pareto optimal solutions is provided. For the purposes of ascertaining the appropriateness of our formulas and solution scheme, two and three objective functions problems are formulated and
solved. Even though simplex method can find all basic Pareto optimal solutions like ours it is too lengthy and requires a lot of bookkeeping. Our method is simple and easy to understand compared to the simplex method and other existing methods.

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