Article

Numerical Methods for Caputo–Hadamard Fractional Differential Equations with Graded and Non-Uniform Meshes

Charles Wing Ho Green 1,♦, Yanzhi Liu 2,♦ and Yubin Yan 1,♦,†

1 Department of Mathematical and Physical Sciences, University of Chester, Chester CH1 4BJ, UK; 1604518@chester.ac.uk
2 Department of Mathematics, Lvliang University, Lvliang 033000, China; 39036@llu.edu.cn
* Correspondence: y.yan@chester.ac.uk; Tel.: +44-1244-312-785
† These authors contributed equally to this work.

Abstract: We consider the predictor-corrector numerical methods for solving Caputo–Hadamard fractional differential equations with the graded meshes \(\log t_j = \log a + (\log \frac{a}{T}) j, j = 0, 1, 2, \ldots, N\) with \(a \geq 1\) and \(r \geq 1\), where \(\log a = \log t_0 < \log t_1 < \cdots < \log t_N = \log T\) is a partition of \([\log t_0, \log T]\). We also consider the rectangular and trapezoidal methods for solving Caputo–Hadamard fractional differential equations with the non-uniform meshes \(\log t_j = \log a + (\log \frac{a}{T}) \frac{j + 1}{N + 1}, j = 0, 1, 2, \ldots, N\). Under the weak smoothness assumptions of the Caputo–Hadamard fractional derivative, e.g., \(CH^D_{a,T}y(t) \notin C^1[a, T]\) with \(a \in (0, 2)\), the optimal convergence orders of the proposed numerical methods are obtained by choosing the suitable graded mesh ratio \(r \geq 1\). The numerical examples are given to show that the numerical results are consistent with the theoretical findings.

Keywords: predictor-corrector method; Caputo–Hadamard fractional derivative; graded meshes; error estimates

1. Introduction

Recently, fractional differential equations have become an active research area due to their applications in a wide range of fields including mechanics, computer science, and biology [1–4]. There are different kinds of fractional derivatives, e.g., Caputo, Riemman–Liouville, Riesz, which have been studied extensively in the literature. However, the Hadamard fractional derivative is also very important and used to model the different physical problems [5–11].

The Hadamard fractional derivative was suggested in early 1892 [12]. More recently, a new derivative which involved a Caputo-type modification on the Hadamard derivative known as the Caputo–Hadamard derivative was suggested [8]. The aim of this paper is to study and analyze some useful numerical methods for solving Caputo–Hadamard fractional differential equations with graded and non-uniform meshes under the weak smoothness assumptions of the Caputo–Hadamard fractional derivative, e.g., \(CH^D_{a,T}y(t) \notin C^1[a, T]\) with \(a \in (0, 2)\).

We thus consider the following Caputo–Hadamard fractional differential equation, with \(a > 0\) [8]

\[
\begin{align*}
CH^D_{a,T}y(t) &= f(t, y(t)), \quad 1 \leq a \leq t \leq T, \\
\delta^k y(a) &= y^{(k)}(a), \quad k = 0, 1, \ldots, [a] - 1,
\end{align*}
\]

where \(f(t, y)\) is a nonlinear function with respect to \(y \in \mathbb{R}\), and the initial values \(y^{(k)}(a)\) are given and \(n - 1 < a < n\), for \(n = 1, 2, 3, \ldots\). Here the fractional derivative \(CH^D_{a,T}y(t)\) denotes the Caputo–Hadamard derivative defined by

\[
CH^D_{a,T}y(t) = \frac{1}{\Gamma([a] - a)} \int_a^t (\log \frac{t}{s})^{[a] - a - 1} \delta^a y(s) \frac{ds}{s}, \quad t \geq a \geq 1,
\]
with \( \delta^n y(s) = (s \frac{d}{ds})^n y(s) \), and where \( \lceil a \rceil \) denotes the smallest integer greater than or equal to \( a \) \[8\].

To make sure that (1) has a unique solution, we assume that the function \( f \) is continuous and satisfies the following Lipschitz condition with respect to the second variable \( y \) \[7,13\]

\[
|f(t, y_1) - f(t, y_2)| \leq L|y_1 - y_2| \quad \text{for} \quad L > 0, \quad y_1, y_2 \in \mathbb{R}.
\]

For some recent existence and uniqueness results for Caputo–Hadamard fractional differential equations, the readers can refer to \[14–16\] and the references therein.

It is well known that the Equation (1) is equivalent to the following Volterra integral equation, with \( \alpha > 0 \), \[5\]

\[
y(t) = \sum_{v=0}^{\lceil a \rceil - 1} y_a^{(v)} \left( \frac{\log \frac{t}{n}}{v!} \right) + \frac{1}{\Gamma(a)} \int_a^t \left( \frac{\log \frac{s}{n}}{s} \right)^{a-1} f(s, y(s)) \frac{ds}{s}.
\]

Let us review some numerical methods for solving (1). Gohar et al. \[7\] studied the existence and uniqueness of the solution of (1) and Euler and predictor-corrector methods were considered. Gohar et al. \[13\] further considered the rectangular, trapezoidal, and predictor-corrector methods for solving (1) with uniform meshes under the smooth assumption of the fractional derivative, e.g., \( CH D^{\alpha}_{a,T} y(t) \in C^2[a, T] \) with \( \alpha \in (0, 1) \). There are also some numerical methods for solving Caputo–Hadamard time fractional partial differential equations \[7,17\]. In this paper, we shall assume that \( CH D^{\alpha}_{a,T} y(t) \notin C^2[a, T] \) with \( \alpha \in (0, 2) \) and assume that \( CH D^{\alpha}_{a,T} y(t) \) behaves as \( (\log \frac{t}{n})^\sigma \) with \( \sigma \in (0, 1) \) which implies that the derivatives of \( CH D^{\alpha}_{a,T} y(t) \) have the singularities at \( \log a \). In such case, we can not expect the numerical methods with uniform meshes have the optimal convergence orders.

To obtain the optimal convergence orders, we shall use the graded and non-uniform meshes as in Liu et al. \[18,19\] for solving Caputo fractional differential equations. We shall show that the predictor-corrector method has the optimal convergence orders with the graded meshes \( \log t_j = \log a + (\log \frac{a}{n}) \left( \frac{j}{N} \right)^r \), \( j = 0, 1, 2, \ldots, N \) for some suitable \( r \geq 1 \). We also show that the rectangular, trapezoidal methods also have the optimal convergence orders with some non-uniform meshes \( \log t_j = \log a + (\log \frac{a}{n}) \left( \frac{j+1}{N+1} \right) \), \( j = 0, 1, 2, \ldots, N \).

For some recent works for the numerical methods for solving fractional differential equations with graded and non-uniform meshes, we refer to \[17,20–22\]. In particular, Stynes et al. \[23,24\] applied a graded mesh on a finite difference method for solving subdiffusion equations when the solutions of the equations are not sufficiently smooth. Liu et al. \[18,19\] applied a graded mesh for solving Caputo fractional differential equation by using a fractional Adams method with the assumption that the solution was not sufficiently smooth. The aim of this work is to extend the ideas in Liu et al. \[18,19\] for solving Caputo fractional differential equations to solve the Caputo–Hadamard fractional differential equations.

The paper is organized as follows. In Section 2 we consider the error estimates of the predictor-corrector method for solving (1) with the graded meshes. In Section 3 we consider the error estimates of the rectangular, trapezoidal methods for solving (1) with non-uniform meshes. In Section 4 we will provide several numerical examples which support the theoretical conclusions made in Sections 2 and 3.

Throughout this paper, we denote by \( C \) a generic constant depending on \( y, T, \alpha \), but independent of \( t > 0 \) and \( N \), which could be different at different occurrences.

2. Predictor-Corrector Method with Graded Meshes

In this section, we shall consider the error estimates of the predictor-corrector method for solving (1) with graded meshes. We first recall the following smoothness properties of the solutions to (1).
Theorem 1 ([25]). Let \( \alpha > 0 \). Assume that \( f \in C^2(G) \) where \( G \) is a suitable set. Define 
\[ \vartheta = \left[ \frac{1}{\alpha} \right] - 1. \]
Then there exists a function \( \phi \in C^1[a, T] \) and some constants \( c_1, c_2, \ldots, c_s \in \mathbb{R} \) such that the solution \( y \) of (1) can be expressed in the following form
\[ y(t) = \phi(t) + c_1 \left( \log \frac{1}{a} \right)^a + c_2 \left( \log \frac{1}{a} \right)^{2a} + \cdots + c_s \left( \log \frac{1}{a} \right)^{sa}. \]

An example of this would be when \( 0 < \alpha < 1, f \in C^2(G) \). We would have \( \vartheta = \left[ \frac{1}{\alpha} \right] - 1 \geq 1 \) and
\[ y = c \left( \log \frac{1}{a} \right)^a + \text{smoother terms}. \]

This implies that the solution \( y \) of (1) would behave as \( (\log \frac{1}{a})^a \), \( 0 < \alpha < 1 \). As such the solution \( y \notin C^2[a, T] \).

Theorem 2 ([25]). If \( y \in C^m[a, T] \) for some \( m \in \mathbb{N} \) and \( 0 < \alpha < m \), then
\[ c_H D_{a,t}^\alpha y(t) = \Phi(t) + \sum_{l=0}^{m-|\alpha|-1} \frac{\delta^{l+|\alpha|} y(a)}{\Gamma(|\alpha| - l + 1)} \left( \log \frac{t}{a} \right)^{|\alpha| - l + 1}, \]
where \( \Phi \in C^{m-|\alpha|}[a, T] \) and \( \delta^n y(s) = (s \frac{d}{ds})^n y(s) \) with \( n \in \mathbb{N} \).

With the above two theorems, we can see that if one of \( y \) and \( c_H D_{a,t}^\alpha y(t) \) is sufficiently smooth then the other will not be sufficiently smooth unless some special conditions have been met.

Recall that, by (3), the solution of (1) can be written as the following form, with \( \alpha \in (0, 1) \) and \( y_a = y_a(0) \),
\[ y(t) = y_a + \frac{1}{\Gamma(\alpha)} \int_a^t \left( \log t - \log s \right)^{\alpha-1} \left[ c_H D_{a,t}^\alpha y(s) \right] \frac{ds}{s}. \] (4)

Therefore it is natural to introduce the following smoothness assumptions for the fractional derivative \( c_H D_{a,t}^\alpha y(t) \) in (1).

Assumption 1. Let \( 0 \leq \sigma \leq 1 \) and \( \alpha > 0 \). Let \( y \) be the solution of (1). Assume that \( c_H D_{a,t}^\alpha y(t) \) can be expressed as a function of \( \log t \), that is, there exists a smooth function \( G_a : [0, \infty) \to \mathbb{R} \) such that
\[ G_a(\log t) := c_H D_{a,t}^\alpha y(t) \in C^2(a, T). \] (5)

Further we assume that \( G_a(\cdot) \) satisfies the following smooth assumptions, with \( 1 \leq a \leq t \leq T \),
\[ |G_a'(\log t)| \leq C(\log t - \log a)^{\sigma-1}, \quad |G_a''(\log t)| \leq C(\log t - \log a)^{\sigma-2}, \] (6)

where \( G_a'(\cdot) \) and \( G_a''(\cdot) \) denote the first and second order derivatives of \( G_a \), respectively.

Denote
\[ g_a(t) := G_a(\log t), \quad 1 \leq a \leq t \leq T. \]

We then have
\[ \delta g_a(t) := \frac{d}{dt} g_a(t) = G_a'(\log t), \]
\[ \delta^2 g_a(t) := \left( \frac{d}{dt} \right)^2 g_a(t) = \left( \frac{d}{dt} \right)(t \frac{d}{dt} g_a) = G_a''(\log t). \] (7)

Hence the assumptions (6) is equivalent to, with \( 1 \leq a \leq t \leq T \),
\[ |\delta g_a(t)| \leq C \left( \log \frac{t}{a} \right)^{\sigma-1}, \quad |\delta^2 g_a(t)| \leq C \left( \log \frac{t}{a} \right)^{\sigma-2}, \tag{8} \]

which are similar to the smoothness assumptions given in Liu et al. [18] for the Caputo fractional derivative \( C D_{0+}^{\alpha} y(t) \).

**Remark 1.** Assumption 1 gives the behavior of \( g_a(t) \) near \( t = a \) and implies that \( g_a(t) \) has the singularity near \( t = a \). It is obvious that \( g_a \notin C^2[a, T] \). For example, we may choose \( g_a(t) = (\log \frac{t}{a})^\sigma \) with \( 0 < \sigma < 1 \).

Let \( N \) be a positive integer and let \( a = t_0 < t_1 < \cdots < t_N = T \) be the partition on \([a, T]\). We define the following graded mesh on \([\log(a), \log(T)]\) with

\[ \log a = \log t_0 < \log t_1 < \cdots < \log t_N = \log T, \]

such that, with \( r \geq 1 \),

\[ \frac{\log t_j - \log a}{\log t_N - \log a} = \left( \frac{j}{N} \right)^r, \]

which implies that

\[ \log t_j = \log a + \log t_N - \log a \left( \frac{j}{N} \right)^r. \]

When \( j = N \) we have \( \log t_N = \log T \). Further we have

\[ \log t_{j+1} - \log t_j = \log \frac{t_{j+1}}{t_j} = \log \frac{T}{a} \left( \frac{j+1}{N} \right)^r - \left( \frac{j}{N} \right)^r. \]

Denote \( y_k \approx y(t_k), \quad k = 0, 1, 2, \ldots, N \) the approximation of \( y(t_k) \). Let us introduce the different numerical methods for solving (3) with \( \alpha \in (0, 1) \) below. Similarly we may define the numerical methods for solving (3) with \( \alpha \geq 1 \). The fractional rectangular method for solving (3) is defined as

\[ y_{k+1} = y_0 + \sum_{j=0}^k b_{j,k+1} f(t_j, y_j), \tag{9} \]

where the weights \( b_{j,k+1} \) are defined as

\[ b_{j,k+1} = \frac{1}{\alpha + 1} \left[ \left( \log \frac{t_{j+1}}{t_j} \right)^{\alpha} - \left( \log \frac{t_{j+1}}{t_{j+1}} \right)^{\alpha} \right], \quad j = 0, 1, 2, \ldots, k. \tag{10} \]

The fractional trapezoidal method for solving (3) is defined as

\[ y_{k+1} = y_0 + \sum_{j=0}^{k+1} a_{j,k+1} f(t_j, y_j), \tag{11} \]

where the weights \( a_{j,k+1} \) for \( j = 0, 1, 2, \ldots, k + 1 \) are defined as

\[ a_{j,k+1} = \frac{1}{\Gamma(\alpha + 2)} \begin{cases} \frac{1}{\log \frac{t_j}{t_0}} A_0, & j = 0, \\ \frac{1}{\log \frac{t_j}{t_j-1}} A_j + \frac{1}{\log \frac{t_j}{t_j-1}} B_j, & j = 1, 2, \ldots, k, \\ \left( \log \frac{t_{j+1}}{t_j} \right)^{\alpha}, & j = k + 1, \end{cases} \tag{12} \]
\[ A_j = \left( \log \frac{t_{k+1}}{t_j} \right)^{a+1} - \left( \log \frac{t_{k+1}}{t_j-1} \right)^{a+1} + (\alpha + 1) \left( \log \frac{t_{j+1}}{t_j} \right) \left( \log \frac{t_{k+1}}{t_j} \right)^{a}, \quad j = 0, 1, \ldots, k, \]
\[ B_j = \left( \log \frac{t_{k+1}}{t_j} \right)^{a+1} - \left( \log \frac{t_{k+1}}{t_j-1} \right)^{a+1} + (\alpha + 1) \left( \log \frac{t_{j+1}}{t_j-1} \right) \left( \log \frac{t_{k+1}}{t_j-1} \right)^{a}, \quad j = 1, 2, \ldots, k. \]

The predictor-corrector Adams method for solving (3) is defined as, with \( \alpha \in (0, 1), k = 0, 1, \ldots, N - 1, \)
\[
\begin{align*}
\frac{y_{k+1}^p}{y_{k+1}} &= y_0 + \sum_{j=0}^{k} b_{j,k+1} f(t_j, y_j), \\
y_{k+1} &= y_0 + \sum_{j=0}^{k} a_{j,k+1} f(t_j, y_j) + a_{k+1} f(t_{k+1}, y_{k+1}),
\end{align*}
\]
(13)
where the weights \( b_{j,k+1} \) and \( a_{j,k+1} \) are defined as above.

If we assume that \( g_a(t) := \mathcal{CH} D_a^\alpha y(t) \) satisfies Assumption 1, we shall prove the following error estimate.

**Theorem 3.** Assume that \( g_a(t) := \mathcal{CH} D_a^\alpha y(t) \) satisfies Assumption 1. Further assume that \( y(t_j) \) and \( y_j \) are the solutions of (3) and (13), respectively.

1. **If** \( 0 < \alpha \leq 1 \), **then we have**
\[
\max_{0 \leq j \leq N} |y(t_j) - y_j| \leq \begin{cases} 
CN^{-r(\sigma + \alpha)}, & \text{if } r(\sigma + \alpha) < 1 + \alpha, \\
CN^{-r(\sigma + \alpha)} \log(N), & \text{if } r(\sigma + \alpha) = 1 + \alpha, \\
CN^{-(1+\alpha)}, & \text{if } r(\sigma + \alpha) > 1 + \alpha.
\end{cases}
\]

2. **If** \( \alpha > 1 \), **then we have**
\[
\max_{0 \leq j \leq N} |y(t_j) - y_j| \leq \begin{cases} 
CN^{-r(1+\sigma)}, & \text{if } r(1 + \sigma) < 2, \\
CN^{-2} \log(N), & \text{if } r(1 + \sigma) = 2, \\
CN^{-2}, & \text{if } r(1 + \sigma) > 2.
\end{cases}
\]

**Proof of Theorem 3**

In this subsection, we shall prove Theorem 3. To help with this we will start by proving some preliminary Lemmas. In Lemma 1 we will be finding the error estimate between \( g_a(s) \) and the piecewise linear function \( P_1(s) \) for both \( 0 < \alpha \leq 1 \) and \( \alpha > 1 \). This will be used to estimate one of the terms in our main proof.

**Lemma 1.** Assume that \( g_a(t) \) satisfies Assumption 1

1. **If** \( 0 < \alpha \leq 1 \), **then we have**
\[
\left| \int_a^{t_{k+1}} \left( \log \frac{t_{k+1}}{s} \right)^{a-1} (g_a(s) - P_1(s)) \frac{ds}{s} \right| \leq \begin{cases} 
CN^{-r(\sigma + \alpha)}, & \text{if } r(\sigma + \alpha) < 2, \\
CN^{-2} \log(N), & \text{if } r(\sigma + \alpha) = 2, \\
CN^{-2}, & \text{if } r(\sigma + \alpha) > 2.
\end{cases}
\]

2. **If** \( \alpha > 1 \), **then we have**
\[
\left| \int_a^{t_{k+1}} \left( \log \frac{t_{k+1}}{s} \right)^{a-1} (g_a(s) - P_1(s)) \frac{ds}{s} \right| \leq \begin{cases} 
CN^{-r(1+\sigma)}, & \text{if } r(1 + \sigma) < 2, \\
CN^{-2} \log(N), & \text{if } r(1 + \sigma) = 2, \\
CN^{-2}, & \text{if } r(1 + \sigma) > 2.
\end{cases}
\]

where \( P_1(s) \) is the piecewise linear function defined by,
\[
P_1(s) = \frac{\log \frac{s}{t_{j+1}}}{\log \frac{t_{j+1}}{t_j}} g(t_j) + \frac{\log \frac{s}{t_j}}{\log \frac{t_{j+1}}{t_j}} g(t_{j+1}), \quad s \in [t_j, t_{j+1}].
\]
Proof. Note that, with $k = 0, 1, 2, \ldots, N - 1$,

$$
\int_a^{l_{k+1}} \left( \log \frac{t_{k+1}}{s} \right)^{\alpha-1} \left( g_a(s) - P_1(s) \right) \frac{ds}{s}
= \left( \int_a^{l_1} + \sum_{j=1}^{k-1} \int_{l_j}^{l_{j+1}} + \int_{l_k}^{l_{k+1}} \right) \left( \log \frac{t_{k+1}}{s} \right)^{\alpha-1} \left( g_a(s) - P_1(s) \right) \frac{ds}{s}
= I_1 + I_2 + I_3.
$$

For $I_1$, we have

$$
I_1 = \int_a^{l_1} \left( \log \frac{t_{k+1}}{s} \right)^{\alpha-1} \left( g_a(s) - P_1(s) \right) \frac{ds}{s}.
$$

Note that, with $s \in [a, l_1]$,

$$
g_a(s) - P_1(s) = g_a(s) - \left[ \log s - \log t_1 \log a + \frac{g_a(a)}{\log t_1 - \log a} \log a - \log t_1 \right] = \log s - \log t_1 \left( \frac{g_a(s) - g_a(a)}{\log a - \log t_1} + \frac{g_a(a)}{\log t_1 - \log a} (g_a(s) - g_a(t_1)) \right) = \log s - \log t_1 \int_a^s \frac{g_a'(\log \tau) \, d\log \tau + \log s - \log a}{\log t_1 - \log a} \int_t^1 \frac{g_a'(\log \tau) \, d\log \tau}{\log a - \log t_1} \int_a^s g_a'(\log \tau) \, d\log \tau, \tag{14}
$$

which implies that, by Assumption 1,

$$
|g_a(s) - P_1(s)| \leq \int_a^s |G'_a(\log \tau)| \, d\log \tau + \int_t^1 |G'_a(\log \tau)| \, d\log \tau
\leq C \int_a^s \left( \log \frac{\tau}{a} \right)^{\sigma-1} \, d\log \frac{\tau}{a} + C \int_t^1 \left( \log \frac{\tau}{a} \right)^{\sigma-1} \, d\log \frac{\tau}{a}
\leq C \left( \log \frac{s}{a} \right)^{\sigma} + C \left( \log \frac{t_1}{a} \right)^{\sigma}. \tag{15}
$$

Thus we have, by (14),

$$
|I_1| \leq C \int_a^{l_1} \left( \log \frac{t_{k+1}}{s} \right)^{\alpha-1} \left( \log \frac{s}{a} \right)^{\sigma} \frac{ds}{s} + C \int_a^{l_1} \left( \log \frac{t_{k+1}}{s} \right)^{\alpha-1} \left( \log \frac{t_1}{a} \right)^{\sigma+1} \frac{ds}{s}.
$$

Note that there exists a constant $C > 0$ such that

$$
\log \frac{t_{k+1}}{a} \geq \log \frac{t_{k+1}}{l_1} \geq C \log \frac{t_{k+1}}{a}, \quad k = 1, 2, \ldots, N - 1,
$$

which follows from

$$
1 \leq \frac{\log \frac{t_{k+1}}{a}}{\log \frac{t_{k+1}}{l_1}} = \frac{\frac{k+1}{N} \tau}{\frac{k+1}{N} - \frac{1}{N}} = 1 + \frac{1}{(k+1)\gamma - 1} \leq 1 + \frac{1}{2\gamma - 1} \leq C.
$$

Thus we have, for $0 < \alpha \leq 1$,

$$
|I_1| \leq C \left( \log \frac{t_{k+1}}{l_1} \right)^{\alpha-1} \int_a^{l_1} \left( \log \frac{s}{a} \right)^{\sigma} \frac{ds}{s} + C \left( \log \frac{t_{k+1}}{l_1} \right)^{\alpha-1} \left( \log \frac{t_1}{a} \right)^{\sigma+1}
\leq C \left( \log \frac{t_{k+1}}{l_1} \right)^{\alpha-1} \left( \log \frac{t_1}{a} \right)^{\sigma+1} \leq C \left( \log \frac{t_{k+1}}{a} \right)^{\alpha-1} \left( \log \frac{T_1}{a} \right)^{\sigma+1}
\leq C \left( \log \frac{t_1}{a} \right)^{\alpha-1} \left( \log \frac{T_1}{a} \right)^{\sigma+1} + C \left( \log \frac{T_1}{a} \right)^{\alpha-1} \left( \log \frac{t_{k+1}}{a} \right)^{\sigma+1}
= C k^{\sigma+1} N^{-\sigma} \leq C N^{-\sigma}.
$$
For $\alpha > 1$, we have

$$|I_1| \leq C \left( \log \frac{t_{k+1}}{a} \right)^{a-1} \int_a^{t_1} \left( \frac{s}{a} \right)^{\sigma} ds + C \left( \log \frac{t_{k+1}}{a} \right)^{a-1} \left( \frac{t_1}{a} \right)^{\sigma+1}$$

$$\leq C \left( \log \frac{t_{k+1}}{a} \right)^{a-1} \left( \frac{t_1}{a} \right)^{\sigma+1} \leq C \left( \log \frac{T}{a} \right)^{\alpha-1} \left( \frac{t_1}{a} \right)^{\sigma+1}$$

$$= C \left( \log \frac{T}{a} \right)^{\alpha-1} \frac{k}{N} r^{(a-1)} \left( \log \frac{T}{a} \right)^{\sigma+1} \left( \frac{t_1}{a} \right)^{\sigma+1}$$

$$= C(k^{(a-1)}N^{-r(a+\sigma)}) \leq CN^{-r(1+\sigma)}.$$  

For $I_2$ we have, with $\xi_j \in (t_j, t_{j+1})$, $j = 1, 2, \ldots, k - 1$ and $k = 2, 3, \ldots, N - 1$,

$$|I_2| = \frac{1}{2} \left| \sum_{j=1}^{k-1} \int_{t_j}^{t_{j+1}} \left( \log \frac{t_{k+1}}{s} \right)^{a-1} \delta^2 g_a(\xi_j) \left( \log \frac{s}{t_j} \right)^{a-1} \left( \log \frac{s}{t_{j+1}} \right)^{a-1} ds \right|,$$

where we have used the following fact, with $s \in (t_j, t_{j+1})$,

$$g_a(s) = \frac{\log s - \log t_{j+1}}{\log t_j - \log t_{j+1}} g_a(t_j) + \frac{\log s - \log t_j}{\log t_{j+1} - \log t_j} g_a(t_{j+1})$$

$$= \frac{1}{2} \delta^2 g_a(\xi_j)(\log s - \log t_j)(\log s - \log t_{j+1}),$$

which can be seen easily by noting $g_a(s) = G_a(\log s)$ and (7).

By Assumption 1 and by using [24] (Section 5.2), we have, with $k \geq 4$,

$$|I_2| \leq C \left| \sum_{j=1}^{k-1} \left( \log \frac{t_{j+1}}{t_j} \right)^2 \left( \log \frac{t_j}{a} \right)^{\sigma-2} \int_{t_j}^{t_{j+1}} \left( \log \frac{t_{k+1}}{t_j} \right)^{a-1} ds \right|$$

$$\leq C \left| \sum_{j=1}^{k-1} \left( \log \frac{t_{j+1}}{t_j} \right)^2 \left( \log \frac{t_j}{a} \right)^{\sigma-2} \int_{t_j}^{t_{j+1}} \left( \log \frac{t_{k+1}}{t_j} \right)^{a-1} ds \right|$$

$$+ C \left| \sum_{j=1}^{k-1} \left( \log \frac{t_{j+1}}{t_j} \right)^2 \left( \log \frac{t_j}{a} \right)^{\sigma-2} \int_{t_j}^{t_{j+1}} \left( \log \frac{t_{k+1}}{t_j} \right)^{a-1} ds \right|$$

$$= I_{21} + I_{22},$$

where $\left[ \frac{k-1}{2} \right]$ defines the ceiling function defined as before. For each of these integrals we shall consider the cases when $0 < a \leq 1$ and when $a > 1$.

For $I_{21}$, when $0 < a \leq 1$, we have, with $k \geq 4$,

$$I_{21} \leq C \left| \sum_{j=1}^{k-1} \left( \log \frac{t_{j+1}}{t_j} \right)^2 \left( \log \frac{t_j}{a} \right)^{\sigma-2} \left( \log \frac{t_{k+1}}{t_j} \right)^{a-1} \left( \log \frac{t_{j+1}}{t_j} \right) \right|$$

$$\leq C \left| \sum_{j=1}^{k-1} \left( \log \frac{t_{j+1}}{t_j} \right)^2 \left( \log \frac{t_j}{a} \right)^{\sigma-2} \left( \log \frac{t_{k+1}}{t_j} \right)^{a-1} \right|.$$

Note that, with $\xi_j \in [j, j+1]$, $j = 1, 2, \ldots, k - 1$,

$$\left( \log \frac{t_{j+1}}{t_j} \right) = \left( \log \frac{t_N}{a} \right)((j+1) - j^r) N^{-r} = Cr^{(a-1)}N^{-r} \leq Cr^{(j+1)^{r-1}}N^{-r} \leq C^{(r-1)}N^{-r},$$

(16)
and
\[
\left( \log \frac{t_{k+1}}{t_{j+1}} \right)^{a-1} = \left( \log \frac{I_N}{a} \right)^{a-1} \left( \frac{N^r}{(k+1)^r - (j+1)^r} \right)^{1-a} \\
\leq \left( \log \frac{I_N}{a} \right)^{a-1} \left( \frac{N^r}{(k+1)^r - \lfloor \frac{k+1}{a} \rfloor^r} \right)^{1-a} \\
\leq C(N^r(k+1)^r)^{-a} \leq C(N/k)^r(1-a). \tag{17}
\]

Thus, with \( k \geq 4, \)
\[
I_{21} \leq C \sum_{j=1}^{\lfloor \frac{k-1}{a} \rfloor - 1} (t^{-r}N^{-r})^3 (j/N)^{r(\sigma-2)} (N/k)^{r(1-a)} \\
= C \sum_{j=1}^{\lfloor \frac{k-1}{a} \rfloor - 1} j^{-r(\sigma+\alpha)-3} N^{-r(\sigma+\alpha)} (j/k)^{r(1-a)} = CN^{-r(\sigma+\alpha)} \sum_{j=1}^{\lfloor \frac{k-1}{a} \rfloor - 1} j^{-r(\sigma+\alpha)-3}.
\]

Case 1, If \( r(\sigma + \alpha) < 2, \) we have
\[
I_{21} \leq CN^{-r(\sigma+\alpha)} \sum_{j=1}^{\lfloor \frac{k-1}{a} \rfloor - 1} j^{-r(\sigma+\alpha)-3} \leq CN^{-r(\sigma+\alpha)}.
\]

Case 2, If \( r(\sigma + \alpha) = 2, \) we have
\[
I_{21} \leq CN^{-2} \sum_{j=1}^{\lfloor \frac{k-1}{a} \rfloor - 1} j^{-1} \leq CN^{-2} \left( 1 + \frac{1}{2} + \cdots + \frac{1}{N} \right) \leq CN^{-2} \log N.
\]

Case 3, If \( r(\sigma + \alpha) > 2, \) we have
\[
I_{21} \leq CN^{-r(\sigma+\alpha)} \sum_{j=1}^{\lfloor \frac{k-1}{a} \rfloor - 1} j^{-r(\sigma+\alpha)-3} \leq CN^{-r(\sigma+\alpha)} k^{-r(\sigma+\alpha)-2} = C(k/N)^{r(\sigma+\alpha)-2N^{-2}} \leq CN^{-2}.
\]

Thus, we have that for \( 0 < \alpha \leq 1 \)
\[
I_{21} \leq \begin{cases} 
CN^{-r(\sigma+\alpha)}, & \text{if } r(\sigma + \alpha) < 2, \\
CN^{-2} \log N, & \text{if } r(\sigma + \alpha) = 2, \\
CN^{-2}, & \text{if } r(\sigma + \alpha) > 2.
\end{cases}
\]

Next we will take the case for when \( \alpha > 1, \) we have, with \( k \geq 4, \)
\[
I_{21} \leq C \sum_{j=1}^{\lfloor \frac{k-1}{a} \rfloor - 1} \left( \log \frac{t_{j+1}}{t_j} \right)^2 \left( \log \frac{t_{j+1}}{t_j} \right)^{-2} \left( \log \frac{t_{k+1}}{t_{j+1}} \right)^{\alpha-1} \left( \log \frac{t_{j+1}}{t_j} \right)
\leq C \sum_{j=1}^{\lfloor \frac{k-1}{a} \rfloor - 1} \left( \log \frac{t_{j+1}}{t_j} \right)^3 \left( \log \frac{t_{j+1}}{a} \right)^{-2} \left( \log \frac{t_{k+1}}{a} \right)^{\alpha-1}
\leq C \sum_{j=1}^{\lfloor \frac{k-1}{a} \rfloor - 1} (t^{-r}N^{-r})^3 (j/N)^{r(\sigma-2)} (k/N)^{r(\alpha-1)}
\leq CN^{-r-\alpha} \sum_{j=1}^{\lfloor \frac{k-1}{a} \rfloor - 1} j^{-r(\sigma+\alpha)-3}.
\]

Thus, we have that for \( \alpha > 1, \)
which implies that

\[ k \leq 2 \]  

For \( I_{21} \), we have, noting that with \( \left\lfloor \frac{k+1}{2} \right\rfloor \leq j \leq k, k \geq 2 \),

\[ \left( \log \frac{t}{a} \right)^{\sigma-2} = \left( \log \frac{t}{a} \right)^{\sigma-2} (j/N)^{r(\sigma-2)} = \left( \log \frac{t}{a} \right) (N/j)^{r(\sigma-2)} \leq C(N/k)^{r(\sigma-2)}, \]

which implies that

\[ I_{22} \leq C \left( \sum_{j=\left\lfloor \frac{k+1}{2} \right\rfloor}^{k-1} (k-1)^{2}(N/k)^{r(\sigma-2)} \int_{t_j}^{t_{j+1}} \left( \log \frac{t_{j+1}}{s} \right)^{a-1} \frac{ds}{s} \right) \]

\[ \leq CK^{\sigma-2}N^{-\sigma} \int_{t_{k-1}}^{t_k} \left( \log \frac{t_{k+1}}{s} \right)^{a-1} \frac{ds}{s}. \]

Note that

\[ \int_{t_{k-1}}^{t_k} \left( \log \frac{t_{k+1}}{s} \right)^{a-1} \frac{ds}{s} = \frac{1}{a} \left[ \left( \log \frac{t_{k+1}}{t_{k+1}} \right)^{a} \right] - \left( \log \frac{t_{k+1}}{t_{k}} \right)^{a} \]

\[ \leq \frac{1}{a} \left( \log \frac{t_{k+1}}{t_{k+1}} \right)^{a} \leq \frac{1}{a} \left( \log \frac{t_{k+1}}{a} \right)^{a} \]

\[ \leq \frac{1}{a} \left( \log \frac{t_{k+1}}{a} \right)^{a} \leq C(k/N)^{a}, \quad \text{(18)} \]

we get, with \( k \geq 2 \) and \( a > 0 \),

\[ I_{22} \leq CK^{\sigma-2}N^{-\sigma}(k/N)^{a} \leq CN^{-r(\sigma+a)}k^{r(\sigma+a)}2 \]

\[ \leq \left\{ \begin{array}{ll} CN^{-r(\sigma+a)}, & \text{if } r(\sigma+a) < 2, \\ CN^{-2}, & \text{if } r(\sigma+a) \geq 2. \end{array} \right. \]

For \( I_3 \), we have, with \( \xi_k \in (t_k, t_{k+1}), k = 1, 2, \ldots, N-1 \),

\[ |I_3| = \left\| \int_{t_k}^{t_{k+1}} \left( \log \frac{t_{k+1}}{s} \right) g(s) - P_1(s) \frac{ds}{s} \right\| \]

\[ = \left\| \int_{t_k}^{t_{k+1}} \left( \log \frac{t_{k+1}}{s} \right) g(s) \left( \log \frac{s}{t_k} \right) \left( \log \frac{s}{t_{k+1}} \right) \frac{ds}{s} \right\|. \]

By Assumption 1, we then have, with \( a > 0 \),

\[ |I_3| \leq C \left( \log \frac{t_{k+1}}{t_k} \right)^{2} \left( \log \frac{t_{k+1}}{a} \right)^{\sigma-2} \int_{t_k}^{t_{k+1}} \left( \log \frac{t_{k+1}}{s} \right)^{a-1} \frac{ds}{s} \]

\[ = C \left( \log \frac{t_{k+1}}{t_k} \right)^{2} \left( \log \frac{t_{k+1}}{a} \right)^{\sigma-2} \left( \log \frac{t_{k+1}}{l_k} \right)^{a} \]

\[ = C \left( \log \frac{t_{k+1}}{t_k} \right)^{2+a} \left( \log \frac{t_{k+1}}{t_k} \right)^{\sigma-2} \]

\[ \leq C \left( \log \frac{t_{k+1}}{a} \right)^{2+a} \left( k^{r(\sigma-a)} \right)^{2+a} \left( \log \frac{t_{k+1}}{a} \right)^{\sigma-2} \]

\[ = CK^{(\alpha+a-2)N^{-r(a+\sigma)}} \]

\[ \leq \left\{ \begin{array}{ll} CN^{-r(\sigma+a)}, & \text{if } r(\sigma+a) < 2+a, \\ CN^{-(2+a)}, & \text{if } r(\sigma+a) \geq 2+a. \end{array} \right. \]
Obviously the bound for \( I_3 \) is stronger than the bound for \( I_{21} \). Together these estimates complete the proof of this lemma. □

In Lemma 2 below, we state that the weights \( a_{j,k+1} \) and \( b_{j,k+1} \) are positive for all values of \( j \).

**Lemma 2.** Let \( \alpha > 0 \). We have

1. \( a_{j,k+1} > 0, j = 0, 1, 2, \ldots, k + 1 \) where \( a_{j,k+1} \) are the weights defined in (12),
2. \( b_{j,k+1} > 0, j = 0, 1, 2, \ldots, k + 1 \) where \( a_{j,k+1} \) are the weights defined in (10).

**Proof.** The proof is obvious, we omit the proof here. □

For Lemma 3, we are attempting to find an upper bound for \( a_{k+1,k+1} \). This will be used in the main proof when addressing the \( a_{k+1,k+1} \) term.

**Lemma 3.** Let \( \alpha > 0 \). We have, with \( k = 0, 1, 2, \ldots, N - 1 \),

\[
a_{k+1,k+1} \leq CN^{-\alpha k(r-1)\alpha},
\]

where \( a_{k+1,k+1} \) is defined in (12).

**Proof.** We have, by (12), with \( \xi_k \in (k, k + 1) \),

\[
a_{k+1,k+1} \leq \frac{1}{\Gamma(\alpha + 2)} \left( \log \frac{t_{k+1}}{t_k} \right)^a \leq C \left( \log \frac{t_N}{t_k} \right)^a N^{-\alpha} ((k + 1)^r - k^r)^a
\]

\[
= CN^{-\alpha} (r_{k+1}^{r-1})^a = CN^{-\alpha} (r(k + 1)^{r-1})^a = CN^{-\alpha k(r-1)\alpha}.
\]

□

In Lemma 4 we will be finding the error estimate between \( g_\alpha(s) \) and the piecewise constant function \( P_0(s) \) for both \( 0 < \alpha \leq 1 \) and \( \alpha > 1 \). This will be used to estimate one of the terms in our main proof.

**Lemma 4.** Assume that \( g_\alpha(t) \) satisfies Assumption 1.

1. \( \alpha \leq 1 \), then we have

\[
\left| a_{k+1,k+1} \int_a^{t_{k+1}} \left( \log \frac{t_{k+1}}{s} \right)^{a-1} (g_\alpha(s) - P_0(s)) \frac{ds}{s} \right| \leq \begin{cases} CN^{-r(\sigma+\alpha)}, & \text{if } r(\sigma + \alpha) < 1 + \alpha, \\ CN^{-\alpha} \log N, & \text{if } r(\sigma + \alpha) = 1 + \alpha, \\ CN^{-1-a}, & \text{if } r(\sigma + \alpha) > 1 + \alpha. \\ \end{cases} \tag{19}
\]

2. \( \alpha > 1 \), then we have

\[
\left| a_{k+1,k+1} \int_a^{t_{k+1}} \left( \log \frac{t_{k+1}}{s} \right)^{a-1} (g_\alpha(s) - P_0(s)) \frac{ds}{s} \right| \leq \begin{cases} CN^{-r(\sigma+\alpha)}, & \text{if } r(\sigma + \alpha) < 1 + \alpha, \\ CN^{-1-a}, & \text{if } r(\sigma + \alpha) \geq 1 + \alpha, \\ \end{cases} \tag{20}
\]

where \( P_0(s) \) is the piecewise constant function defined as below, with \( j = 0, 1, 2, \ldots, k \)

\[
P_0(s) = g_\alpha(t_j), \quad s \in [t_j, t_{j+1}].
\]
Proof. The proof is similar to the proof of Lemma 1. Note that
\[
\begin{align*}
& a_{k+1,k+1} \int_a^{t_{k+1}} \left( \log \frac{t_{k+1}}{s} \right)^{a-1} (g_a(s) - P_0(s)) \frac{ds}{s} \\
& = a_{k+1,k+1} \left( \int_a^{t_1} + \sum_{j=1}^{k-1} \int_{t_j}^{t_{j+1}} + \int_{t_k}^{t_{k+1}} \right) \left( \log \frac{t_{k+1}}{s} \right)^{a-1} (g_a(s) - P_0(s)) \frac{ds}{s} \\
& = I'_1 + I'_2 + I'_3.
\end{align*}
\]

For \( I'_1 \), by Assumption 1, we have
\[
|g_a(s)| = |G_a(\log s)| \leq C \left( \log \frac{s}{a} \right)^\sigma, \quad |P_0(s)| = |g_a(a)| = 0.
\]
Hence we get
\[
|I'_1| \leq a_{k+1,k+1} \left( \int_a^{t_1} \left( \log \frac{t_{k+1}}{s} \right)^{a-1} |g_a(s)| \frac{ds}{s} + \int_a^{t_1} \left( \log \frac{t_{k+1}}{s} \right)^{a-1} |P_0(s)| \frac{ds}{s} \right) \\
\leq (CN^{-ra_k(r-1)a}) \left( \int_a^{t_1} \left( \log \frac{t_{k+1}}{s} \right)^{a-1} \left( \log \frac{s}{a} \right)^\sigma ds + \int_a^{t_1} \left( \log \frac{t_{k+1}}{s} \right)^{a-1} 0 \frac{ds}{s} \right) \\
= (CN^{-ra_k(r-1)a}) \left( \int_a^{t_1} \left( \log \frac{t_{k+1}}{s} \right)^{a-1} \left( \log \frac{s}{a} \right)^\sigma ds \right).
\]

If \( 0 < \alpha \leq 1 \), we have
\[
|I'_1| \leq (CN^{-ra_k(r-1)a}) \left( \log \frac{t_{k+1}}{t_1} \right)^{a-1} \left( \log \frac{t_1}{a} \right)^{\sigma+1} \\
\leq (CN^{-ra_k(r-1)a}) \left( \log \frac{t_{k+1}}{a} \right)^{a-1} \left( \log \frac{t_1}{a} \right)^{\sigma+1} \\
= (CN^{-ra_k(r-1)a}) \left( \log \frac{T}{\alpha} \right)^{a-1} \left( \frac{k+1}{N} \right)^{r(a-1)} \left( \log \frac{T}{\alpha} \right)^{\sigma+1} \left( \frac{1}{N} \right)^{r(\sigma+1)} \\
\leq (CN^{-ra_k(r-1)a})(CN^{-r(a+\sigma)}) = C(k/N)^{ra_k-a}(CN^{-r(a+\sigma)}) \leq CN^{-r(a+\sigma)}.
\]

If \( \alpha > 1 \), we have
\[
|I'_1| \leq (CN^{-ra_k(r-1)a}) \left( \log \frac{t_{k+1}}{a} \right)^{a-1} \left( \log \frac{t_1}{a} \right)^{\sigma+1} \\
= (CN^{-ra_k(r-1)a}) \left( \log \frac{T}{\alpha} \right)^{a-1} \left( \frac{k+1}{N} \right)^{r(a-1)} \left( \log \frac{T}{\alpha} \right)^{\sigma+1} \left( \frac{1}{N} \right)^{r(\sigma+1)} \\
\leq (CN^{-ra_k(r-1)a})(CN^{-r(1+\sigma)}) \leq C(k/N)^{ra_k-a}(N^{-a}N^{-r(1+\sigma)}) \\
\leq CN^{-r(1+\sigma)-a} \leq CN^{-a}.
\]

For \( I'_2 \), we have, with \( \xi_j \in (t_j, t_{j+1}), \quad j = 1, 2, \ldots, k-1, \)
\[
|I'_2| \leq a_{k+1,k+1} \sum_{j=1}^{k-1} \int_{t_j}^{t_{j+1}} \left( \log \frac{t_{k+1}}{s} \right)^{a-1} |g_a(\xi_j)| \left( \log \frac{s}{t_j} \right) \frac{ds}{s}.
\]
Hence, by Assumption 1,
\[
|I'_2| \leq C a_{k+1,k+1} \left( \sum_{j=1}^{k-1} \int_{t_j}^{t_{j+1}} \left( \log \frac{t_{k+1}}{t_j} \right)^{a-1} \left( \log \frac{t_j}{a} \right)^{\sigma+1} \left( \log \frac{t_{k+1}}{s} \right)^{a-1} \frac{ds}{s} \right) \\
= I'_{21} + I'_{22}.
\]
For $l'_{21}$, if $0 < \alpha \leq 1$, then we have, with $k \geq 2$,

\[
\begin{align*}
l'_{21} &\leq (CN^{-\alpha}k^{(r-1)\alpha}) \sum_{j=1}^{\left[\frac{k}{r}\right]-1} \left( \log \frac{t_j+1}{t_j} \right)^2 \left( \log \frac{t_j}{a} \right)^{\sigma-1} \left( \log \frac{t_{k+1}}{t_{j+1}} \right)^{a-1} \\
&= (CN^{-\alpha}k^{(r-1)\alpha}) \sum_{j=1}^{\left[\frac{k}{r}\right]-1} (j^{-1}N^{-r})^2 (j/N)^{r(\sigma-1)} (N/k)^{r(1-\alpha)} \\
&\leq C(k/N)^{\alpha} \sum_{j=1}^{\left[\frac{k}{r}\right]-1} j^{r(\alpha+\sigma)-2-\alpha} (j/k)^{r(1-\alpha)} N^{-r(a+\sigma)} \\
&\leq CN^{-r(a+\sigma)} \sum_{j=1}^{\left[\frac{k}{r}\right]-1} j^{r(\alpha+\sigma)-2-\alpha} \leq \begin{cases} 
CN^{-r(a+\sigma)}, & \text{if } r(\alpha+\sigma) < 1 + \alpha, \\
CN^{-r(a+\sigma)} \log N, & \text{if } r(\alpha+\sigma) = 1 + \alpha, \\
CN^{-1-\alpha}, & \text{if } r(\alpha+\sigma) > 1 + \alpha.
\end{cases}
\end{align*}
\]

If $\alpha > 1$, we have

\[
\begin{align*}
l'_{21} &\leq (CN^{-\alpha}k^{(r-1)\alpha}) \sum_{j=1}^{\left[\frac{k}{r}\right]-1} \left( \log \frac{t_j+1}{t_j} \right)^2 \left( \log \frac{t_j}{a} \right)^{\sigma-1} \left( \log \frac{t_{k+1}}{a} \right)^{a-1} \\
&\leq (CN^{-\alpha}k^{(r-1)\alpha}) \sum_{j=1}^{\left[\frac{k}{r}\right]-1} (j^{-1}N^{-r})^2 (j/N)^{r(\sigma-1)} (N/k)^{r(1-\alpha)} \\
&= C(k/N)^{(r-1)\alpha} N^{-\alpha} N^{-r\sigma-r} \sum_{j=1}^{\left[\frac{k}{r}\right]-1} j^{r+\sigma-2} \\
&\leq CN^{-\alpha-r\sigma-\alpha} \sum_{j=1}^{\left[\frac{k}{r}\right]-1} j^{r+\sigma-2}.
\end{align*}
\]

Note that $r + r\sigma - 2 > -1$ for any $r \geq 1$. Hence, we have

\[
l'_{21} \leq CN^{-\alpha-r\sigma-\alpha} k^{r+\sigma-1} N^{-1-\alpha} \leq CN^{-1-\alpha}.
\]

For $l'_{22}$, we have

\[
\begin{align*}
l'_{22} &\leq (CN^{-\alpha}k^{(r-1)\alpha}) \sum_{j=1}^{\left[\frac{k}{r}\right]-1} \left( \log \frac{t_j+1}{t_j} \right) \left( \log \frac{t_j}{a} \right)^{\sigma-1} \int_{t_j}^{t_{j+1}} \left( \log \frac{t_{k+1}}{s} \right)^{a-1} ds \\
&\leq \left( \log \frac{t_j}{a} \right)^{\sigma-1} (j/N)^{r(\sigma-1)} = \left( \log \frac{t_N}{a} \right)^{\sigma-1} (N/j)^{r(\sigma-1)} \leq C(N/k)^{r(1-\sigma)}.
\end{align*}
\]

Noting that, with $\left[\frac{k}{r}\right] \leq j \leq k - 1$, $k \geq 2$,

\[
\left( \log \frac{t_j}{a} \right)^{\sigma-1} = \left( \log \frac{t_N}{a} \right)^{\sigma-1} (j/N)^{r(\sigma-1)} = \left( \log \frac{t_N}{a} \right)^{\sigma-1} (N/j)^{r(\sigma-1)} \leq C(N/k)^{r(1-\sigma)},
\]

we have, with $\alpha > 0$,

\[
\begin{align*}
l'_{22} &\leq (CN^{-\alpha}k^{(r-1)\alpha}) \sum_{j=1}^{\left[\frac{k}{r}\right]-1} \left( (Ck^{-1}N^{-r})(N/k)^{r(1-\sigma)} \int_{t_j}^{t_{j+1}} \left( \log \frac{t_{k+1}}{s} \right)^{a-1} ds \right) \\
&\leq \left( CN^{-r(\sigma+\alpha)} \right) k^{-1-r\sigma} N^{-r-r\sigma} (k/N)^{ra} \leq Ck^{r(\sigma+\alpha)-1-\alpha} N^{-r(\sigma+\alpha)} \\
&\leq \begin{cases} 
CN^{-r(\sigma+\alpha)}, & \text{if } r(\sigma+\alpha) < 1 + \alpha, \\
CN^{-1-\alpha}, & \text{if } r(\sigma+\alpha) \geq 1 + \alpha.
\end{cases}
\end{align*}
\]
For $t_3'$, we have, with $\alpha > 0$,
\[
|t_3'| \leq (CN^{-\alpha}k^{(r-1)a})(\log \frac{t_{k+1}}{t_k})(\log \frac{t_k}{\alpha})^{\alpha-1}(\log \frac{t_{k+1}}{t_k})^\alpha \leq (CN^{-\alpha}k^{(r-1)a})(\log \frac{t_{k+1}}{t_k})^{\alpha+1}(\log \frac{t_k}{\alpha})^{\alpha-1}.
\]

Further we have
\[
|t_3'| \leq (CN^{-\alpha}k^{(r-1)a})(k^{r-1}N^{-r})^{1+a}(k/N)^{(c-1)} = C(k/N)^{\alpha}k^{(\alpha+c)-\alpha-1}N^{-r(\alpha+c)} \leq Ck^{(\alpha+c)-\alpha-1}N^{-r(\alpha+c)}.
\]

Together these estimates complete the proof of this Lemma. \(\square\)

For Lemma 5, we are attempting to find an upper bound for the sum of our weights. This will be used in the main proof when simplifying several terms.

**Lemma 5.** Let $\alpha > 0$. There exists a positive constant $C$ such that
\[
\sum_{j=0}^{k} a_{j,k+1} \leq C \left( \log \frac{T}{a} \right)^{\alpha}, \quad (21)
\]
\[
\sum_{j=0}^{k} b_{j,k+1} \leq C \left( \log \frac{T}{a} \right)^{\alpha}, \quad (22)
\]
where $a_{j,k+1}$ and $b_{j,k+1}$, $j = 0, 1, 2, \ldots, k$ are defined by (12) and (10), respectively.

**Proof.** We only prove (21). The proof of (22) is similar. Note that
\[
\int_{a}^{t_{k+1}} \left( \log \frac{t_{k+1}}{s} \right)^{\alpha-1} g_a(s) \frac{ds}{s} = \sum_{j=0}^{k+1} a_{j,k+1} g(t_j) + R_1,
\]
where $R_1$ is the remainder term. Let $g_a(s) = 1$, we have
\[
\sum_{j=0}^{k+1} a_{j,k+1} = \int_{a}^{t_{k+1}} \left( \log \frac{t_{k+1}}{s} \right)^{\alpha-1} \frac{ds}{s} = \frac{1}{\alpha} \left( \log \frac{t_{k+1}}{a} \right)^\alpha \leq C \left( \log \frac{T}{a} \right)^\alpha.
\]

Thus, (21) follows by the fact $a_{k+1,k+1} > 0$ in Lemma 2. \(\square\)

We will now use the above lemmas to prove the error estimates of Theorem 3.

**Proof of Theorem 3.** Subtracting (13) from (3), we have
\[
y(t_{k+1}) - y_{k+1} = \frac{1}{\Gamma(\alpha)} \left\{ \int_{a}^{t_{k+1}} \left( \log \frac{t_{k+1}}{s} \right)^{\alpha-1} \left( f(s,y(s)) - P_1(s) \right) \frac{ds}{s} + \sum_{j=0}^{k} a_{j,k+1} (f(t_j,y(t_j)) - f(t_j,y_j)) + a_{k+1,k+1} (f(t_{k+1},y(t_{k+1})) - f(t_{k+1},y_{k+1})) \right\} \leq \frac{1}{\Gamma(\alpha)} (I + II + III).
\]
The term $I$ is estimated by Lemma 1. For II, we have, by Lemma 2 and the Lipschitz condition of $f$,

$$|II| = \left| \sum_{j=0}^{k} a_{j,k+1}(f(t_j, y(t_j)) - f(t_j, y_j)) \right|$$

$$\leq \sum_{j=0}^{k} a_{j,k+1} |f(t_j, y(t_j)) - f(t_j, y_j)|$$

$$\leq L \sum_{j=0}^{k} a_{j,k+1} |y(t_j) - y_j|.$$  

For III, we have, by Lemma 2 and the Lipschitz condition for $f$,

$$|III| = |a_{k+1,k+1}(f(t_{k+1}, y(t_{k+1})) - f(t_{k+1}, y_{k+1}))| \leq a_{k+1,k+1} L |y(t_{k+1}) - y_{k+1}|.$$  

Note that

$$y(t_{k+1}) - y_{k+1} = \frac{1}{\Gamma(\alpha)} \left\{ \int_a^{t_{k+1}} \left( \log \frac{t_{k+1}}{s} \right)^{a-1} (f(s, y(s)) - P_0(s)) \frac{ds}{s} \right. \right. + \sum_{j=0}^{k} b_{j,k+1}(f(t_j, y(t_j)) - f(t_j, y_j)) \right\}.$$  

Thus,

$$|III| \leq Ca_{k+1,k+1} L \int_a^{t_{k+1}} \left( \log \frac{t_{k+1}}{s} \right)^{a-1} |f(s, y(s)) - P_0(s)| \frac{ds}{s}$$

$$+ Ca_{k+1,k+1} L \sum_{j=0}^{k} b_{j,k+1} |f(t_j, y(t_j)) - f(t_j, y_j)|$$

$$= III_1 + III_2.$$  

The term $III_1$ is estimated by Lemma 4. For $III_2$, we have, by Lemma 2,

$$III_2 \leq Ca_{k+1,k+1} L \sum_{j=0}^{k} b_{j,k+1} |y(t_j) - y_j| \leq (CN^{-r}k^{(r-1)a}) \sum_{j=0}^{k} b_{j,k+1} |y(t_j) - y_j|$$

$$\leq C(k/N)^{(r-1)a} N^{-a} \sum_{j=0}^{k} b_{j,k+1} |y(t_j) - y_j|$$

$$\leq CN^{-a} \sum_{j=0}^{k} b_{j,k+1} |y(t_j) - y_j|.$$  

Hence, we obtain

$$|y(t_{k+1}) - y_{k+1}| \leq C|I| + C \sum_{j=0}^{k} b_{j,k+1} |y(t_j) - y_j|$$

$$+ C|III_1| + CN^{-a} \sum_{j=0}^{k} b_{j,k+1} |y(t_j) - y_j|.$$  

The rest of the proof is exactly the same as the proof of [18] (Theorem 1.4). The proof of Theorem 3 is complete.  

$\square$
3. Rectangular and Trapezoidal Methods with Non-Uniform Meshes

In this section, we will consider the error estimates for the fractional rectangular and trapezoidal methods for solving (1). These results are based on the error estimates proposed by Liu et al. [19]. First, we will introduce the non-uniform meshes for solving (1).

Let \( N \) be a positive integer and let \( a = t_0 < t_1 < \cdots < t_N = T \) be the partition on \( [a, T] \). We define the following non-uniform mesh on \( [\log(a), \log(T)] \) with

\[
\log a = \log t_0 < \log t_1 < \cdots < \log t_N = \log T,
\]

such that

\[
\frac{\log t_j - \log a}{\log t_N - \log a} = \frac{j(j + 1)}{N(N + 1)},
\]

which implies that

\[
\log t_j = \log a + \left( \log t_N - \log a \right) \frac{j(j + 1)}{N(N + 1)}.
\]

Now we see when \( j = 0 \), we have \( \log t_0 = \log a \). When \( j = N \) we have \( \log t_N = \log T \). Further we have

\[
\tau_j := \log t_{j+1} - \log t_j = \frac{t_{j+1}}{t_j} = \frac{2(j + 1)}{N(N + 1)} \log \frac{t_N}{a}.
\]

3.1. Rectangular Method

In this subsection, we prove the following error estimate for the rectangular method over the given non-uniform mesh.

**Theorem 4.** Assume that \( g_a(t) := C_H D_a^{\alpha} y(t) \) satisfies Assumption 1. Further assume that \( y(t_j) \) and \( y_j \) are the solutions of (3) and (9), respectively.

1. If \( 0 < \alpha \leq 1 \), then we have

\[
\max_{0 \leq j \leq N} |y(t_j) - y_j| \leq \begin{cases} 
CN^{-2(\sigma + \alpha)}, & \text{if } 0 < 2(\sigma + \alpha) < 1, \\
CN^{-2(\sigma + \alpha)} \log(N), & \text{if } 2(\sigma + \alpha) = 1, \\
CN^{-1}, & \text{if } 2(\sigma + \alpha) > 1.
\end{cases}
\]

2. If \( \alpha > 1 \), then we have

\[
\max_{0 \leq j \leq N} |y(t_j) - y_j| \leq CN^{-1}.
\]

To prove Theorem 4, we need some preliminary lemmas. Here we only state the lemmas without proofs since the proofs are similar as in Liu et al. [19]. In Lemma 6 we will be defining a key estimate which we will be using in our main proof.

**Lemma 6.** Assume that \( g_a(t) := C_H D_a^{\alpha} y(t) \) satisfies Assumption 1.

1. If \( 0 < \alpha \leq 1 \), then we have, with \( k = 0, 1, 2, \ldots, N - 1, \ N \geq 1, \)

\[
\left| \frac{1}{\Gamma(\alpha)} \sum_{j=0}^{k} \int_{t_j}^{t_{j+1}} (\log \frac{t_{k+1}}{s})^{\alpha-1} g_a(s) \frac{ds}{s} - \frac{1}{\Gamma(\alpha)} \sum_{j=0}^{k} b_{j,k+1} g(t_j) \right| \leq \begin{cases} 
CN^{-2(\sigma + \alpha)}, & \text{if } 0 < 2(\sigma + \alpha) < 1, \\
CN^{-2(\sigma + \alpha)} \log(N), & \text{if } 2(\sigma + \alpha) = 1, \\
CN^{-2(\sigma + \alpha)} \log(N), & \text{if } 2(\sigma + \alpha) > 1.
\end{cases}
\]

2. If \( 1 < \alpha < 2 \), then we have

\[
\sum_{j=0}^{k} \int_{t_j}^{t_{j+1}} (\log \frac{t_k}{s})^{\alpha-1} g_a(s) \frac{ds}{s} \leq CN^{-2(\sigma + \alpha)},
\]

with

\[
\frac{1}{\Gamma(\alpha)} \sum_{j=0}^{k} \int_{t_j}^{t_{j+1}} (\log \frac{t_k}{s})^{\alpha-1} g_a(s) \frac{ds}{s} - \frac{1}{\Gamma(\alpha)} \sum_{j=0}^{k} b_{j,k+1} g(t_j) \]

\[
\leq \begin{cases} 
CN^{-2(\sigma + \alpha)}, & \text{if } 0 < 2(\sigma + \alpha) < 1, \\
CN^{-2(\sigma + \alpha)} \log(N), & \text{if } 2(\sigma + \alpha) = 1, \\
CN^{-2(\sigma + \alpha)} \log(N), & \text{if } 2(\sigma + \alpha) > 1.
\end{cases}
\]
\[
\left| \frac{1}{\Gamma(a)} \sum_{j=0}^{k} \int_{t_j}^{t_{j+1}} \left( \log \frac{t_{k+1}}{s} \right)^{a-1} g_a(s) \frac{ds}{s} - \sum_{j=0}^{k} b_{j,k+1} g(t_j) \right| \leq C N^{-1}.
\]

In Lemma 7 we will find some upper bounds for our weights \( b_{j,k+1} \) and \( a_{j,k+1} \).

**Lemma 7.** If \( \alpha > 0 \), \( k \) is a non-negative integer and \( \tau_j \leq \tau_{j+1}, j = 0, 1, \ldots, k-1 \), then the weights \( b_{j,k+1} \) and \( a_{j,k+1} \) defined by equations (10) and (12), have the following estimates:

\[
b_{j,k+1} \leq C_0 \tau_j \left( \log \frac{t_{k+1}}{t_j} \right)^{a-1}, \quad j = 0, 1, 2, \ldots, k,
\]

and

\[
a_{j,k+1} \leq C_0 \begin{cases} 
\tau_0 \left( \log \frac{b_{j+1}}{b_j} \right)^{a-1}, & j = 0, \\
\tau_j \left( \log \frac{b_{j+1}}{b_j} \right)^{a-1} + \tau_{j-1} \left( \log \frac{b_{j+1}}{b_{j-1}} \right)^{a-1}, & j = 1, 2, \ldots, k+1,
\end{cases}
\]

where \( C_0 = \frac{1}{\Gamma(a+1)} \max \{ 2, a \} \).

In Lemma 8 we will give an adapted Gronwall inequality to be used in the main results.

**Lemma 8.** Assume that \( \alpha, C_0, T > 0 \) and \( b_{j,k} = C_0 \tau_j \left( \log \frac{b_{j+1}}{b_j} \right)^{a-1}, j = 0, 1, 2, \ldots, k-1 \) for \( 0 = t_0 < t_1 < \cdots < t_k < \cdots < t_N = T, k = 1, 2, \ldots, N \) where \( N \) is a positive integer and \( \tau_j = \log \frac{t_{j+1}}{t_j} \). Let \( g_0 \) be positive and the sequence \( \{ \psi_k \} \) meet

\[
\begin{cases} 
\psi_0 \leq g_0, \\
\psi_k \leq \sum_{j=1}^{k-1} b_{j,k} \psi_j + g_0
\end{cases}
\]

then

\[
\psi_k \leq C g_0, \quad k = 1, 2, \ldots, N.
\]

**Proof of Theorem 4.** For \( k = 0, 1, 2, \ldots, N-1 \), we have

\[
|y(t_{k+1}) - y_{k+1}| = \left| \frac{1}{\Gamma(a)} \int_{t_k}^{t_{k+1}} \left( \log \frac{t_{k+1}}{s} \right)^{a-1} g_a(s) \frac{ds}{s} - \sum_{j=0}^{k} b_{j,k+1} f(t_j, y_j) \right|
\]

\[
\leq \frac{1}{\Gamma(a)} \sum_{j=0}^{k} \int_{t_j}^{t_{j+1}} \left( \log \frac{t_{k+1}}{s} \right)^{a-1} (g_a(s) - g(t_j)) \frac{ds}{s}
\]

\[
+ \left| \sum_{j=0}^{k} b_{j,k+1} (g(t_j) - f(t_j, y_j)) \right| = I + II.
\]

The first term \( I \) can be estimated by Lemma 6. For \( II \), we can apply Lemma 2 and the Lipschitz condition of \( f \),

\[
II = \left| \sum_{j=0}^{k} b_{j,k+1} (g(t_j) - f(t_j, y_j)) \right| \leq L \sum_{j=0}^{k} b_{j,k+1} |y(t_j) - y_j|.
\]

Substituting into the original we get

\[
|y(t_{k+1}) - y_{k+1}| \leq I + L \sum_{j=0}^{k} b_{j,k+1} |y(t_j) - y_j|.
\]
By applying Lemma 8, we get

$$|y(t_{k+1}) - y_k| \leq C I.$$  

This completes the proof of Theorem 4. □

3.2. Trapezoid Formula

In this subsection we will consider the error estimates of the trapezoid method over the non-uniform mesh. We shall prove the following theorem

**Theorem 5.** Assume that $g_a(t) := c_H D_{a,t}^α y(t)$ satisfies Assumption 1. Further assume that $y(t_j)$ and $y_j$ are the solutions of (3) and (11), respectively.

1. If $0 < α \leq 1$, then we have

$$\max_{0 \leq j \leq N} |y(t_j) - y_j| \leq \begin{cases} CN^{-2(σ + α)}, & \text{if } 0 < 2(σ + α) < 2, \\ CN^{-2(σ + α)} \log(N), & \text{if } 2(σ + α) = 2, \\ CN^{-2}, & \text{if } 2(σ + α) > 2. \end{cases}$$

2. If $1 < α < 2$, then we have

$$\max_{0 \leq j \leq N} |y(t_j) - y_j| \leq CN^{-2}.$$

To prove Theorem 5, we need the following lemma. In Lemma 9 we will be defining a key estimate which we will be using in our main proof.

**Lemma 9.** Assume that $g_a(t) := c_H D_{a,t}^α y(t)$ satisfies Assumption 1.

1. If $0 < α \leq 1$, then we have, with $k = 0, 1, 2, \ldots, N - 1, N \geq 1$,

$$|\frac{1}{Γ(α)} \sum_{j=0}^{k} \int_{t_j}^{t_{j+1}} \left( \log \frac{t_{k+1}}{s} \right)^{α-1} g_a(s) \frac{ds}{s} - \sum_{j=0}^{k} a_{j,k+1} g(t_j)| \leq \begin{cases} CN^{-2(σ + α)}, & \text{if } 0 < 2(σ + α) < 2, \\ CN^{-2(σ + α)} \log(N), & \text{if } 2(σ + α) = 2, \\ CN^{-2}, & \text{if } 2(σ + α) > 2. \end{cases}$$

2. If $1 < α < 2$, then we have

$$|\frac{1}{Γ(α)} \sum_{j=0}^{k} \int_{t_j}^{t_{j+1}} \left( \log \frac{t_{k+1}}{s} \right)^{α-1} g_a(s) \frac{ds}{s} - \sum_{j=0}^{k} a_{j,k+1} g(t_j)| \leq CN^{-2}.$$

**Proof of Theorem 5.** For $k = 0, 1, 2, \ldots, N - 1$, we have

$$|y(t_{k+1}) - y_k| = \left| \frac{1}{Γ(α)} \int_{t_j}^{t_{j+1}} \left( \log \frac{t_{k+1}}{s} \right)^{α-1} g_a(s) \frac{ds}{s} - \sum_{j=0}^{k+1} a_{j,k+1} f(t_j, y_j) \right|$$

$$\leq \left| \frac{1}{Γ(α)} \sum_{j=0}^{k} \int_{t_j}^{t_{j+1}} \left( \log \frac{t_{k+1}}{s} \right)^{α-1} \left( g_a(s) - \frac{\log s - \log t_{j+1}}{\log t_j - \log t_{j+1}} g(t_j) - \frac{\log s - \log t_j}{\log t_{j+1} - \log t_j} g(t_{j+1}) \right) \frac{ds}{s} \right|$$

$$+ \sum_{j=0}^{k+1} a_{j,k+1}(g(t_j) - f(t_j, y_j)) |$$

$$= I + II.$$
The term I is estimated by Lemma 9. For II we can apply Lemma 7 and the Lipschitz condition of f, 
\[ II = \left| \sum_{j=0}^{k+1} a_{j,k+1}(g(t_j) - f(t_j, y_j)) \right| \leq L \sum_{j=0}^{k+1} a_{j,k+1}|y(t_j) - y_j|. \]

Thus we obtain 
\[ |y(t_{k+1}) - y_{k+1}| \leq I + L \sum_{j=0}^{k+1} a_{j,k+1}|y(t_j) - y_j|. \]

By using the corresponding Gronwall Lemma 8 we have \(|y(t_{k+1}) - y_{k+1}| \leq CI\). This completes the proof of Theorem 5. \(\Box\)

4. Numerical Examples

In this section, we will consider some numerical examples to confirm the theoretical results obtained in the previous sections. For simplicity, all the examples below will take \(0 < \alpha < 1\). All the following results may be adapted for all \(\alpha > 1\).

Example 1. Consider the following nonlinear fractional differential equation, with \(a \in (0,1)\) and \(a = 1\),
\[
\begin{cases}
CH^{\alpha}_{a,l}y(t) = f(t,y), & 0 \leq t \leq T, \\
y(0) = 0,
\end{cases}
\] (23)

where
\[
f(t,y) = \frac{\Gamma(6)}{\Gamma(6-a)}(\log t)^{5-a} + \frac{\Gamma(5)}{\Gamma(5-a)}(\log t)^{4-a} + \frac{2\Gamma(4)}{\Gamma(4-a)}(\log t)^{3-a} - y^2 + (\log t)^5 - (\log t)^4 + 2(\log t)^3.\]

The exact solution of this equation is \(y(t) = (\log t)^5 - (\log t)^4 + 2(\log t)^3\). We will be solving Example 1 over the interval \([1,2]\). Let \(N\) be a positive integer and let \(\log a = \log t_0 < \log t_1 < \cdots < \log t_N = \log T\) be the graded mesh on the interval \([\log a, \log T]\). This mesh is defines as \(\log t_j = \log a + \left(\frac{\log T}{2}\right)/j\) for \(j = 0, 1, 2, \ldots, N\) with \(r \geq 1\). Therefore, we have by Theorem 3,
\[
||e_N|| := \max_{0 \leq j \leq N} |y(t_j) - y_j| \leq CN^{-(1+\alpha)}. \quad (24)
\]

In Table 1 we can see the maximum absolute error and experimental order of convergence (EOC) for the predictor-corrector method at varying \(a\) and \(N\) values. For our different \(0 < \alpha < 1\), we have chosen \(N\) values as \(N = 10 \times 2^l, l = 0, 1, 2, \ldots, 7\). For this example we have taken \(r = 1\). The maximum absolute errors \(||e_N|||_\infty\) were obtained as shown above with respect to \(N\) and we calculate the experimental order of convergence or EOC as \(\log \left(\frac{||e_N||_\infty}{||e_{2N}||_\infty}\right)\).

As we can see, the EOCs for this example are almost \(O(N^{-(1+\alpha)})\) which was predicted by Theorem 3. Due to the solution of the FODE being sufficiently smooth, any value of \(r\) will give the optimal convergence order given above. As we are using \(r = 1\), this means that we are using a uniform mesh and so can compare these results with the methods introduced by Gohar et al. [13]. We can see, we have obtained a similar result.
Table 1. Table showing the maximum absolute error and EOC for solving (23) using the predictor-corrector method.

| N   | $\alpha = 0.4$ EOC | $\alpha = 0.6$ EOC | $\alpha = 0.8$ EOC | $\alpha = 0.8$ EOC |
|-----|--------------------|--------------------|--------------------|--------------------|
| 10  | $3.475 \times 10^{-2}$ | $1.734 \times 10^{-2}$ | $9.660 \times 10^{-3}$ |                     |
| 20  | $1.263 \times 10^{-2}$ | $5.427 \times 10^{-3}$ | $2.761 \times 10^{-3}$ | $1.851$ |
| 40  | $4.446 \times 10^{-3}$ | $1.686 \times 10^{-3}$ | $7.617 \times 10^{-4}$ | $1.858$ |
| 80  | $1.562 \times 10^{-3}$ | $5.275 \times 10^{-4}$ | $2.106 \times 10^{-4}$ | $1.854$ |
| 160 | $5.543 \times 10^{-4}$ | $1.668 \times 10^{-4}$ | $5.850 \times 10^{-5}$ | $1.848$ |
| 320 | $1.992 \times 10^{-4}$ | $5.328 \times 10^{-5}$ | $1.632 \times 10^{-5}$ | $1.842$ |
| 640 | $7.241 \times 10^{-5}$ | $1.716 \times 10^{-5}$ | $4.568 \times 10^{-6}$ | $1.837$ |
| 1280| $2.657 \times 10^{-5}$| $5.562 \times 10^{-6}$ | $1.283 \times 10^{-6}$ | $1.832$ |

In Figure 1, we have plotted the order of convergence for Example 1. From Equation (24) we have, with $h = 1/N$,

$$\left(\log_2 ||e_N||\right) \leq (\log_2 C) + \left(\log_2 N^{-(1+\alpha)}\right) \leq (\log_2 C) + (1 + \alpha)\left(\log_2 h\right).$$

Let $y = \left(\log_2 ||e_N||\right)$ and let $x = \left(\log_2 h\right)$. We then plotted a graph for $y$ against $x$ for $h = \frac{1}{2^l}, l = 0, 1, \ldots, 7$. Doing this, we get that the gradient of the graph would equal the EOC. To compare this to the theoretical order of convergence, we have also plotted the straight line $y = (1 + \alpha)x$. For Figure 1 we choose $\alpha = 0.8$. We can observe that the two lines drawn are parallel. Therefore we can conclude that the order of convergence of this predictor-corrector method is $O(h^{1+\alpha})$.

![Graph showing the experimental order of convergence (EOC) at T = 2 in Example 1 with $\alpha = 0.8$.](image)

Figure 1. Graph showing the experimental order of convergence (EOC) at $T = 2$ in Example 1 with $\alpha = 0.8$.

Example 2. Consider the following nonlinear fractional differential equation, with $\alpha, \beta \in (0, 1)$ and $a = 1$,

$$\begin{cases} 
\mathcal{C}D^\alpha_{a,T}y(t) = f(t, y), & 1 \leq a < t \leq T, \\
y(a) = 0,
\end{cases}$$

where

$$f(t, y) = \frac{\Gamma(1+\beta)}{\Gamma(1+\beta-\alpha)} (\log t)^{\beta-\alpha} + (\log t)^{2\beta} - y^2.$$
We will be solving Example 2 over the interval $[1, 2]$. The exact solution of this equation is $y = (\log \frac{t}{\alpha})^{\beta}$ and $CHD_{\alpha}^{\beta}y(t) = \frac{\Gamma(1+\beta)}{t^{1+\beta-\alpha}}(\log t)^{\beta-\alpha}$. This implies that the regularity of $CHD_{\alpha}^{\beta}y(t)$ behaves as $(\log t)^{\beta-\alpha}$. This means that $CHD_{\alpha}^{\beta}y(t)$ satisfies Assumption 1. We will be using the same graded mesh as in Example 1. Therefore, we have by Theorem 3, with $\sigma = \beta - \alpha$,

$$||e_N|| := \max_{0 \leq j \leq N} |y(t_j) - y_j| \leq \begin{cases} CN^{-r\beta}, & \text{if } r < \frac{1+\alpha}{\beta}, \\
CN^{-r\beta} \log N, & \text{if } r = \frac{1+\alpha}{\beta}, \\
CN^{-(1+\alpha)}, & \text{if } r > \frac{1+\alpha}{\beta}. \end{cases} \quad (26)$$

In Tables 2–4 we can see the EOC for the predictor-corrector method with varying values of $\alpha$ and with $r$ values at $r = 1$ and $r = \frac{1+\alpha}{\beta}$. With a fixed $\beta = 0.9$ we have obtain the EOC and maximum absolute error for increasing values of $N$. By doing so we can see that the EOC are almost $O(N^{-r\beta}) = 0.9$ when $r = 1$ and the EOC are almost $O(N^{-(1+\alpha)}) = 1 + \alpha$ when $r = \frac{1+\alpha}{\beta}$.

**Table 2.** Table showing the maximum absolute error and EOC for solving (25) using the predictor-corrector method for $\alpha = 0.4$, $\beta = 0.9$.

| $N$  | $r = 1$          | EOC           | $r = \frac{1+\alpha}{\beta}$ | EOC           |
|------|------------------|---------------|-------------------------------|---------------|
| 10   | $1.100 \times 10^{-2}$ | 1.858 $\times 10^{-2}$ |                             |               |
| 20   | $5.635 \times 10^{-3}$ | 0.965         | 6.141 $\times 10^{-3}$       | 1.598         |
| 40   | $3.177 \times 10^{-3}$ | 0.827         | 2.048 $\times 10^{-3}$       | 1.584         |
| 80   | $1.737 \times 10^{-3}$ | 0.871         | 7.009 $\times 10^{-4}$       | 1.547         |
| 160  | $9.380 \times 10^{-4}$ | 0.889         | 2.457 $\times 10^{-4}$       | 1.512         |
| 320  | $5.064 \times 10^{-4}$ | 0.895         | 8.780 $\times 10^{-5}$       | 1.485         |
| 640  | $2.706 \times 10^{-4}$ | 0.898         | 3.184 $\times 10^{-5}$       | 1.464         |
| 1280 | $1.451 \times 10^{-4}$ | 0.899         | 1.167 $\times 10^{-5}$       | 1.448         |

**Table 3.** Table showing the maximum absolute error and EOC for solving (25) using the predictor-corrector scheme for $\alpha = 0.6$, $\beta = 0.9$.

| $N$  | $r = 1$          | EOC           | $r = \frac{1+\alpha}{\beta}$ | EOC           |
|------|------------------|---------------|-------------------------------|---------------|
| 10   | $2.151 \times 10^{-2}$ | 6.370 $\times 10^{-3}$ |                             |               |
| 20   | $1.193 \times 10^{-2}$ | 0.851         | 1.922 $\times 10^{-3}$       | 1.728         |
| 40   | $6.468 \times 10^{-3}$ | 0.883         | 5.954 $\times 10^{-4}$       | 1.691         |
| 80   | $3.480 \times 10^{-3}$ | 0.894         | 1.888 $\times 10^{-4}$       | 1.657         |
| 160  | $1.868 \times 10^{-3}$ | 0.898         | 6.083 $\times 10^{-5}$       | 1.634         |
| 320  | $1.001 \times 10^{-3}$ | 0.899         | 1.980 $\times 10^{-5}$       | 1.620         |
| 640  | $5.368 \times 10^{-4}$ | 0.900         | 6.482 $\times 10^{-6}$       | 1.611         |
| 1280 | $2.877 \times 10^{-4}$ | 0.900         | 2.130 $\times 10^{-6}$       | 1.605         |

**Table 4.** Table showing the maximum absolute error and EOC for solving (25) using the predictor-corrector method for $\alpha = 0.8$, $\beta = 0.9$.

| $N$  | $r = 1$          | EOC           | $r = \frac{1+\alpha}{\beta}$ | EOC           |
|------|------------------|---------------|-------------------------------|---------------|
| 10   | $3.536 \times 10^{-2}$ | 4.523 $\times 10^{-3}$ |                             |               |
| 20   | $1.916 \times 10^{-2}$ | 0.884         | 1.299 $\times 10^{-3}$       | 1.800         |
| 40   | $1.030 \times 10^{-2}$ | 0.895         | 3.731 $\times 10^{-4}$       | 1.800         |
| 80   | $5.528 \times 10^{-3}$ | 0.898         | 1.071 $\times 10^{-4}$       | 1.800         |
| 160  | $2.963 \times 10^{-3}$ | 0.900         | 3.077 $\times 10^{-5}$       | 1.800         |
| 320  | $1.588 \times 10^{-3}$ | 0.900         | 8.836 $\times 10^{-6}$       | 1.800         |
| 640  | $8.510 \times 10^{-4}$ | 0.900         | 2.537 $\times 10^{-6}$       | 1.800         |
| 1280 | $4.561 \times 10^{-4}$ | 0.900         | 7.287 $\times 10^{-7}$       | 1.800         |
When \( r = 1 \), we are using a uniform mesh and we can see that the EOC obtained is the same as those obtained by Gohar et al. [13]. Comparing these to the results of the graded mesh when \( r = \frac{1 + \alpha}{\beta} \) we can see that a higher EOC has been obtained and an optimal order of convergence is recovered.

In Figure 2, we have plotted the order of convergence for Example 2 when \( r = \frac{1 + \alpha}{\beta} \) and \( \alpha = 0.8 \). This plot is the same as for Figure 1. We have also plotted the straight line \( y = (1 + \alpha) x \). We can observe that the two lines drawn are parallel. Therefore we can conclude that the order of convergence of this predictor-corrector method is \( O(h^{1+\alpha}) \).

![Figure 2. Graph showing the experimental order of convergence (EOC) at \( T = 2 \) in Example 2 with \( \alpha = 0.8 \) and \( r = \frac{1 + \alpha}{\beta} \).](image)

Example 3. Consider the following nonlinear fractional differential equation, with \( \alpha, \beta \in (0, 1) \) and \( a = 1 \),

\[
\begin{cases}
CHD_{a,t}^\alpha y(t) + y(t) = 0, & 1 \leq a < t \leq T, \\
y(a) = 1,
\end{cases}
\quad (27)
\]

The exact solution of this FODE is \( y(t) = E_{\alpha,1}(- \log t) \). Therefore \( CHD_{a,t}^\alpha y(t) = -E_{\alpha,1}(-( \log t)^\alpha) \), where \( E_{\alpha,\gamma}(z) \) is defined as the Mittag–Leffler function

\[
E_{\alpha,\gamma}(z) = \sum_{k=0}^{\infty} \frac{z^k}{\Gamma(ak + \gamma)}, \quad \alpha, \gamma > 0.
\]

Therefore

\[
CHD_{a,t}^\alpha y(t) = -\sum_{k=0}^{\infty} \frac{(- \log t)^{ak}}{\Gamma(ak + \gamma)} = -1 - \frac{(- \log t)\Gamma(a+1)}{\Gamma(1+1)} - \frac{(\log t)^{2\alpha}}{\Gamma(\alpha+1)} - \cdots, \quad \alpha > 0.
\]

This shows that \( CHD_{a,t}^\alpha y(t) \) behaves as \( c + c(\log t)^\alpha \). This means that \( CHD_{a,t}^\alpha y(t) \) satisfies Assumption 1. Therefore, with \( \sigma = \alpha \), we have by Theorem 3,

\[
\|e_N\| := \max_{0 \leq j \leq N} |y(t_j) - y_j| \leq \begin{cases} 
CN^{-r(2\alpha)}, & \text{if } r < \frac{1+\alpha}{2\alpha}, \\
CN^{-r(2\alpha)} \log N, & \text{if } r = \frac{1+\alpha}{2\alpha}, \\
CN^{-(1+\alpha)}, & \text{if } r > \frac{1+\alpha}{2\alpha}.
\end{cases}
\quad (28)
\]

We will be solving this equation over the same graded mesh as in Example 1 with varying \( r \) values. In Tables 5–7, we have calculated the EOC and maximum absolute

---

To continue, it seems there might be a missing equation or table reference. Could you provide the missing information or check the completeness of the text?
error with respect to increasing $N$ values and with $r$ values at $r = 1$ and $r = \frac{1 + \alpha}{\Delta t}$. The experimental orders of convergence are shown to be almost $O(N^{(2\alpha)})$ if we choose $r = 1$ and almost $O(N^{(1 + \alpha)})$ if we choose $r = \frac{1 + \alpha}{\Delta t}$. Once again it is shown when we use a graded mesh at the optimal $r$ value, we get a higher order of convergence to that obtained by the uniform mesh at $r = 1$.

Table 5. Table showing the maximum absolute error and EOC for solving (27) using the predictor-corrector method for $\alpha = 0.4$.

| $N$  | $r = 1$    | EOC  | $r = \frac{1 + \alpha}{\Delta t}$ | EOC  |
|------|------------|------|-----------------------------------|------|
| 10   | $9.399 \times 10^{-3}$ | 3.677 $\times 10^{-3}$ | 1.575 |
| 20   | $2.049 \times 10^{-3}$ | 2.197 | 1.234 $\times 10^{-3}$ | 1.575 |
| 40   | $4.752 \times 10^{-4}$ | 2.108 | 4.687 $\times 10^{-4}$ | 1.397 |
| 80   | $1.000 \times 10^{-3}$ | -1.074 | 2.116 $\times 10^{-4}$ | 1.147 |
| 160  | $9.226 \times 10^{-4}$ | 0.116 | 8.834 $\times 10^{-5}$ | 1.260 |
| 320  | $6.885 \times 10^{-4}$ | 0.422 | 3.542 $\times 10^{-5}$ | 1.319 |
| 640  | $4.670 \times 10^{-4}$ | 0.560 | 1.388 $\times 10^{-5}$ | 1.352 |
| 1280 | $3.002 \times 10^{-4}$ | 0.637 | 5.367 $\times 10^{-6}$ | 1.371 |

Table 6. Table showing the maximum absolute error and EOC for solving (27) using the predictor-corrector method for $\alpha = 0.6$.

| $N$  | $r = 1$    | EOC  | $r = \frac{1 + \alpha}{\Delta t}$ | EOC  |
|------|------------|------|-----------------------------------|------|
| 10   | $6.864 \times 10^{-4}$ | 1.512 $\times 10^{-3}$ | 1.669 |
| 20   | $9.020 \times 10^{-4}$ | -0.394 | 4.756 $\times 10^{-4}$ | 1.429 |
| 40   | $5.967 \times 10^{-4}$ | 0.645 | 1.766 $\times 10^{-4}$ | 1.459 |
| 80   | $3.767 \times 10^{-4}$ | 0.914 | 6.423 $\times 10^{-5}$ | 1.524 |
| 160  | $1.495 \times 10^{-4}$ | 1.034 | 2.233 $\times 10^{-5}$ | 1.558 |
| 320  | $6.982 \times 10^{-5}$ | 1.098 | 7.587 $\times 10^{-6}$ | 1.576 |
| 640  | $3.177 \times 10^{-5}$ | 1.136 | 2.545 $\times 10^{-6}$ | 1.586 |
| 1280 | $1.423 \times 10^{-5}$ | 1.159 | 8.473 $\times 10^{-7}$ | 1.586 |

Table 7. Table showing the maximum absolute error and EOC for solving (27) using the predictor-corrector method for $\alpha = 0.8$.

| $N$  | $r = 1$    | EOC  | $r = \frac{1 + \alpha}{\Delta t}$ | EOC  |
|------|------------|------|-----------------------------------|------|
| 10   | $4.175 \times 10^{-4}$ | 6.100 $\times 10^{-4}$ | 1.829 |
| 20   | $1.700 \times 10^{-4}$ | 1.297 | 1.717 $\times 10^{-4}$ | 1.829 |
| 40   | $7.021 \times 10^{-5}$ | 1.275 | 4.972 $\times 10^{-5}$ | 1.788 |
| 80   | $2.589 \times 10^{-5}$ | 1.439 | 1.459 $\times 10^{-5}$ | 1.769 |
| 160  | $9.062 \times 10^{-6}$ | 1.514 | 4.308 $\times 10^{-6}$ | 1.760 |
| 320  | $3.089 \times 10^{-6}$ | 1.553 | 1.274 $\times 10^{-6}$ | 1.758 |
| 640  | $1.038 \times 10^{-6}$ | 1.574 | 3.766 $\times 10^{-7}$ | 1.758 |
| 1280 | $3.459 \times 10^{-7}$ | 1.585 | 1.111 $\times 10^{-7}$ | 1.760 |

In Figure 3, we have plotted the order of convergence for Example 3 when $r = \frac{1 + \alpha}{\Delta t}$ and $\alpha = 0.8$. This plot is the same as for Figure 1. We have also plotted the straight line $y = (1 + \alpha)x$. We can observe that the two lines drawn are parallel. Therefore we can conclude that the order of convergence of this predictor-corrector method is $O(h^{1+\alpha})$ for choosing the suitable graded mesh ratio $r$. 

Figure 3. Graph showing the experimental order of convergence (EOC) at T = 2 in Example 3 with \( \alpha = 0.8 \) and \( r = \frac{1 + \alpha}{2\alpha} \).

**Example 4.** In this example we will be applying the rectangular and trapezoidal methods for solving (27). Let \( N \) be a positive integer and let \( \log t_j = \log a + (\log t_N - \log a) \frac{j+1}{N^2(N+1)} \) be the graded mesh on the interval \( [\log a, \log T] \) for \( j = 0, 1, \ldots, N \). We will be using \( a = 1 \) and \( T = 2 \).

In Table 8, we have calculated the EOC and maximum absolute error with respect to increasing \( N \) values and with \( \alpha = 0.2, 0.4, 0.6 \) for the rectangular method. By once again using the fact that \( \sigma = \alpha \) and applying Theorem 4 we can say

\[
\max_{0 \leq j \leq N} |y(t_j) - y_j| \leq \begin{cases} 
CN^{-4\alpha}, & \text{if } 0 < 4\alpha < 1, \\
CN^{-4\alpha} \log(N), & \text{if } 4\alpha = 1, \\
CN^{-1}, & \text{if } 4\alpha > 1.
\end{cases}
\]

The experimental orders of convergence are shown to be almost \( O(N^{-4\alpha}) \) if we choose \( \alpha < 0.25 \) and almost \( O(N^{-1}) \) if we choose \( \alpha \geq 0.25 \). This confirms the theoretical error estimates calculated in Section 4. In Table 9, we have used the same method to solve (27) but using the uniform mesh. This shows how a larger EOC is achieved when using non-uniform mesh over a uniform mesh.

In Table 10, we have calculated the EOC and maximum absolute error with respect to increasing \( N \) values and with \( \alpha = 0.2, 0.4, 0.6 \) for the trapezoidal method. By once again using the fact that \( \sigma = \alpha \) and applying Theorem 4 we can say

\[
\max_{0 \leq j \leq N} |y(t_j) - y_j| \leq \begin{cases} 
CN^{-4\alpha}, & \text{if } 0 < 4\alpha < 2, \\
CN^{-4\alpha} \log(N), & \text{if } 4\alpha = 2, \\
CN^{-2}, & \text{if } 4\alpha > 2.
\end{cases}
\]

The experimental orders of convergence are shown to be almost \( O(N^{-4\alpha}) \) if we choose \( \alpha < 0.5 \) and almost \( O(N^{-2}) \) if we choose \( \alpha \geq 0.5 \). This confirms the theoretical error estimates calculated in Section 4. In Table 11, we have used the same method to solve (27) but using the uniform mesh. This shows how a larger EOC is achieved when using graded mesh over a uniform mesh.
Table 8. Table showing the maximum absolute error and EOC for solving (27) using the rectangular method on a graded mesh.

| N    | α = 0.2 | EOC     | α = 0.4 | EOC     | α = 0.6 | EOC     |
|------|---------|---------|---------|---------|---------|---------|
| 40   | 7.919 × 10^{-2} | 8.348 × 10^{-3} | 2.852 × 10^{-3} |       |         |         |
| 80   | 4.843 × 10^{-2} | 2.869 × 10^{-3} | 1.404 × 10^{-3} | 1.023 |         |         |
| 160  | 2.921 × 10^{-2} | 9.688 × 10^{-4} | 6.951 × 10^{-4} | 1.014 |         |         |
| 320  | 1.742 × 10^{-2} | 3.239 × 10^{-4} | 3.454 × 10^{-4} | 1.009 |         |         |
| 640  | 1.030 × 10^{-2} | 1.491 × 10^{-4} | 1.720 × 10^{-4} | 1.006 |         |         |
| 1280 | 6.053 × 10^{-3} | 7.336 × 10^{-5} | 8.577 × 10^{-5} | 1.004 |         |         |

Table 9. Table showing the maximum absolute error and EOC for solving (27) using the rectangular method on a uniform mesh.

| N    | α = 0.2 | EOC     | α = 0.4 | EOC     | α = 0.6 | EOC     |
|------|---------|---------|---------|---------|---------|---------|
| 40   | 1.734 × 10^{-1} | 4.650 × 10^{-2} | 9.971 × 10^{-3} |       |         |         |
| 80   | 1.375 × 10^{-1} | 2.795 × 10^{-2} | 4.475 × 10^{-3} | 1.156 |         |         |
| 160  | 1.085 × 10^{-1} | 1.661 × 10^{-2} | 1.986 × 10^{-3} | 1.172 |         |         |
| 320  | 8.519 × 10^{-2} | 9.793 × 10^{-3} | 8.750 × 10^{-4} | 1.182 |         |         |
| 640  | 6.667 × 10^{-2} | 5.737 × 10^{-3} | 3.839 × 10^{-4} | 1.189 |         |         |
| 1280 | 5.199 × 10^{-2} | 3.345 × 10^{-3} | 1.728 × 10^{-4} | 1.152 |         |         |

Table 10. Table showing the maximum absolute error and EOC for solving (27) using the trapezoidal method on a graded mesh.

| N    | α = 0.2 | EOC     | α = 0.4 | EOC     | α = 0.6 | EOC     |
|------|---------|---------|---------|---------|---------|---------|
| 40   | 8.193 × 10^{-3} | 1.266 × 10^{-3} | 9.466 × 10^{-5} |       |         |         |
| 80   | 5.211 × 10^{-3} | 4.391 × 10^{-4} | 1.832 × 10^{-5} | 2.370 |         |         |
| 160  | 3.241 × 10^{-3} | 1.491 × 10^{-4} | 3.506 × 10^{-6} | 2.385 |         |         |
| 320  | 1.981 × 10^{-3} | 5.000 × 10^{-5} | 6.675 × 10^{-7} | 2.393 |         |         |
| 640  | 1.193 × 10^{-3} | 1.664 × 10^{-5} | 1.321 × 10^{-7} | 2.338 |         |         |
| 1280 | 7.110 × 10^{-4} | 5.517 × 10^{-6} | 3.300 × 10^{-8} | 2.003 |         |         |

Table 11. Table showing the maximum absolute error and EOC for solving (27) using the trapezoidal method on a uniform mesh.

| N    | α = 0.2 | EOC     | α = 0.4 | EOC     | α = 0.6 | EOC     |
|------|---------|---------|---------|---------|---------|---------|
| 40   | 1.640 × 10^{-2} | 6.803 × 10^{-3} | 7.617 × 10^{-4} |       |         |         |
| 80   | 1.341 × 10^{-2} | 4.150 × 10^{-3} | 2.106 × 10^{-4} | 1.854 |         |         |
| 160  | 1.087 × 10^{-2} | 2.494 × 10^{-3} | 5.850 × 10^{-5} | 1.848 |         |         |
| 320  | 8.754 × 10^{-3} | 1.482 × 10^{-3} | 1.632 × 10^{-5} | 1.842 |         |         |
| 640  | 7.001 × 10^{-3} | 8.733 × 10^{-4} | 4.568 × 10^{-6} | 1.837 |         |         |
| 1280 | 5.567 × 10^{-3} | 5.115 × 10^{-4} | 1.283 × 10^{-6} | 1.832 |         |         |

5. Conclusions
In this paper we propose several numerical methods for solving Caputo–Hadamard fractional differential equations with graded and non-uniform meshes. We first introduce a predictor-corrector method and calculate the convergence and error estimates over a graded mesh so to show that the optimal convergence orders can be recovered when the solutions are not sufficiently smooth. We then introduce the error estimates on the fractional rectangle and fractional trapezoidal methods with some non-uniform meshes. Finally, we consider several numerical simulations to support the theoretical results made for the above methods on the convergence orders and error estimates.
**Author Contributions:** We have equal contributions to this work. C.W.H.G. considered the theoretical analysis and wrote the original version of the work. Y.L. considered the theoretical analysis and performed the numerical simulation. Y.Y. introduced and guided this research topic. All authors have read and agreed to the published version of the manuscript.

**Funding:** This research received no external funding.

**Institutional Review Board Statement:** Not applicable.

**Informed Consent Statement:** Not applicable.

**Conflicts of Interest:** The authors declare no conflict of interest.

**References**

1. Diethelm, K. *The Analysis of Fractional Differential Equations*; Lecture Notes in Mathematics; Springer: Berlin/Heidelberg, Germany, 2010.
2. Kilbas, A.A.; Srivastava, H.M.; Trujillo, J.J. *Theory and Applications of Fractional Differential Equations*; North-Holland Mathematics Studies; Elsevier: Amsterdam, The Netherlands, 2006; Volume 204.
3. Oldman, B.K.; Spanier, J. *The Fractional Calculus*; Academic Press: New York, NY, USA, 1974.
4. Podlubny, I. *Fractional Differential Equations; Math, Science and Engineering*; Academic Press: San Diego, CA, USA, 1999.
5. Adali, Y.; Jarad, F.; Baleanu, D. On Cauchy problems with Caputo Hadamard fractional derivatives. *J. Comput. Anal. Appl.* 2016, 21, 661–681.
6. Garra, R.; Mainardi, F.; Spada, G. A generalization of the Lomnitz logarithmic creep law via Hadamard fractional calculus. *Chaos Solitons Fractals* 2017, 102, 333–338. [CrossRef]
7. Gohar, M.; Li, C.; Yin, C. On Caputo Hadamard fractional differential equations. *Int. J. Comput. Math.* 2020, 97, 1459–1483. [CrossRef]
8. Jarad, F.; Abdeljawad, T. Caputo-type modification of the Hadamard fractional derivatives. *Adv. Differ. Equ.* 2012, 2012, 142. [CrossRef]
9. Kilbas, A.A. Hadamard-type fractional calculus. *J. Korean Math. Soc.* 2001, 38, 1191–1204.
10. Li, C.; Cai, M. *Theory and Numerical Approximations of Fractional Integrals and Derivatives*; SIAM: Philadelphia, PA, USA, 2019.
11. Ma, L. On the kinetics of Hadamard-type fractional differential systems. *Fract. Calc. Appl. Anal.* 2020, 23, 553–570. [CrossRef]
12. Hadamard, J. Essai sur l’étude des fonctions données par leur développement de Taylor. *J. Pure Appl. Math.* 1892, 4, 101–186.
13. Gohar, M.; Li, C.; Li, Z. Finite Difference Methods for Caputo-Hadamard Fractional Differential Equations. *Mediterr. J. Math.* 2020, 17, 194. [CrossRef]
14. Abbas, S.; Benchohra, M.; Hamidi, N.; Henderson, J. Caputo-Hadamard fractional differential equations in Banach spaces. *Fract. Calc. Appl. Anal.* 2018, 21, 1027–1045. [CrossRef]
15. Samei, M.E.; Hedayati, V.; Rezapour, S. Existence results for a fraction hybrid differential inclusion with Caputo–Hadamard type fractional derivative. *Adv. Differ. Equ.* 2019, 2019, 163. [CrossRef]
16. Ardjouni, A. Existence and uniqueness of positive solutions for nonlinear Caputo-Hadamard fractional differential equations. *Proyecciones* 2021, 40, 139–152. [CrossRef]
17. Li, C.; Li, Z.; Wang, M. Mathematical Analysis and the Local Discontinuous Galerkin Method for Caputo-Hadamard Fractional Partial Differential Equation. *J. Sci. Comput.* 2020, 85, 41. [CrossRef]
18. Liu, Y.; Roberts, J.; Yan, Y. A detailed error analysis for a fractional Adams method with graded meshes. *Numer. Algorithms* 2018, 78, 1195–1216. [CrossRef]
19. Liu, Y.; Roberts, J.; Yan, Y. A note on finite difference methods for nonlinear fractional differential equations with non-uniform meshes. *Int. J. Comput. Math.* 2018, 95, 1151–1169. [CrossRef]
20. Li, C.; Yi, Q.; Chen, A. Finite difference methods with non-uniform meshes for nonlinear fractional differential equations. *J. Comput. Phys.* 2016, 316, 614–631. [CrossRef]
21. Diethelm, K. Generalized compound quadrature formulae for finite-part integrals. *IMA J. Numer. Anal.* 1997, 17, 479–493. [CrossRef]
22. Zhang, Y.; Sun, Z.; Liao, H. Finite difference methods for the time fractional diffusion equation on non-uniform meshes. *Int. J. Comput. Math.* 2014, 265, 195–210. [CrossRef]
23. Stynes, M. Too much regularity may force too much uniqueness. *Fract. Calc. Appl. Anal.* 2016, 19, 1554–1562. [CrossRef]
24. Stynes, M.; O’Riordan, E.; Gracia, J.L. Error analysis of a finite difference method on graded meshes for a time-fractional diffusion equation. *SIAM J. Numer. Anal.* 2017, 55, 1057–1079. [CrossRef]
25. Lubich, C. Runge-Kutta theory for Volterra and Abel integral equations of the second kind. *Math. Comput.* 1983, 41, 87–102. [CrossRef]