TESSELLATIONS OF HYPERBOLIC SURFACES

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Abstract. A finite subset $S$ of a closed hyperbolic surface $F$ canonically determines a centered dual decomposition of $F$: a cell structure with vertex set $S$, geodesic edges, and 2-cells that are unions of the corresponding Delaunay polygons. Unlike a Delaunay polygon, a centered dual 2-cell $Q$ is not determined by its collection of edge lengths; but together with its combinatorics, these determine an admissible space parametrizing geometric possibilities for the Delaunay cells comprising $Q$. We illustrate its application by using the centered dual decomposition to extract combinatorial information about the Delaunay tessellation among certain genus-2 surfaces, and with this relate injectivity radius to covering radius here.

A finite subset $S$ of a closed hyperbolic surface $F$ canonically determines a Voronoi tessellation $V$ and Delaunay tessellation $P$, polygonal decompositions of $F$ that are dual in a certain sense. Let us briefly outline this construction. Fix a locally isometric universal covering $\pi: \mathbb{H}^2 \to F$ and let $\tilde{S} = \pi^{-1}(S)$. The Voronoi tessellation $\tilde{V}$ of $\mathbb{H}^2$ determined by $\tilde{S}$ is a cell complex structure where each $x \in S$ determines a polygonal 2-cell $V_x$ defined by:

$$V_x = \{ p \in \mathbb{H}^2 | d(p, x) \leq d(p, y) \text{ for each } y \in S - \{x\} \}$$

(0.0.1)

Then $\tilde{V}^{(1)} = \bigcup \{ V_x \cap V_y \mid x \in \tilde{S}, \ y \in \tilde{S} - \{x\} \}$, and each point of $\tilde{V}^{(0)}$ is equidistant from at least 3 points of $\tilde{S}$ (see Section 1). The geometric dual to an edge $V_x \cap V_y$ of $\tilde{V}$ is the geodesic arc $\gamma_{xy}$ in $\mathbb{H}^2$ joining $x$ to $y$, and the set of geometric duals to edges of $\tilde{V}$ is the edge set of the Delaunay tessellation $\tilde{P}$ determined by $\tilde{S}$. The covering action of $\pi_1 F$ on $\mathbb{H}^2$ leaves $\tilde{V}$ and $\tilde{P}$ invariant, and these descend to the tessellations $V$ and $P$ of $F$.

$P$ and $V$ are dual in the sense that their edge sets are canonically bijective, as is the vertex set of each with the face set of the other. However, in some cases an edge $e = V_x \cap V_y$ of $\tilde{V}$ is not centered (see Definition 3.1): int $e$ does not intersect the geometric dual $\gamma_{xy} \subset \tilde{P}$ to $e$.

We will regard this as a pathology of $P$, and “fix” it with the centered dual decomposition. Before we outline this construction, here is a sample application of our methods:

Theorem 0.1. Let $r_\beta = d_\beta/2 > 0$, where $\cosh d_\beta$ is the real root of $x^3 - 14x^2 - 15x - 4$. The Delaunay tessellation of a closed, orientable hyperbolic surface $F$ of genus 2 determined by $\{x\}$ has all edges centered if $F$ has injectivity radius $r \geq r_\beta$ at $x$. It is a triangulation unless $r = r_\beta$ and each edge has length $d_\beta$, in which case it has a single quadrilateral 2-cell.

The numerical value of $r_\beta$ is roughly 1.7006, whereas Boröczky’s theorem [1] implies a universal upper bound of $r_\alpha \approx 1.7191$ on the injectivity radius of a genus-2 hyperbolic surface at a point $x$ (see Lemma 2.3). Example 2.2 describes a surface $F_\alpha$ with injectivity radius $r_\alpha$.

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at some $x_\alpha \in F_\alpha$, showing that Boröczky’s upper bound is sharp. Example 2.4 describes a surface $F_\beta$ with injectivity radius $r_\beta$ at $x_\beta \in F_\beta$ and a quadrilateral 2-cell in the Delaunay tessellation determined by $\{x_\beta\}$, and Example 2.12 describes arbitrarily small deformations of $F_\beta$ with Delaunay tessellations that have non-centered edges.

For surfaces satisfying its hypotheses, Theorem 0.1 has the following geometric consequence:

**Theorem 0.2.** The space $\mathcal{M}_2(r_\beta)$ of closed, orientable hyperbolic surfaces $F$ with injectivity radius at least $r_\beta$ at some $x \in F$ is compact. If $F \in \mathcal{M}_2(r_\beta)$ has injectivity radius $r \geq r_\beta$ at $x$, the covering radius $J$ of $F$ at $x$ satisfies $\sinh J \leq \sqrt{2} \sinh r$.

We regard $\mathcal{M}_2(r_\beta)$ above as a subspace of the moduli space $\mathcal{M}_2$ of closed, orientable hyperbolic surfaces of genus 2, given its usual topology, see eg. [4]. By the covering radius of $F$ at $x$ we refer to the infimum of $r > 0$ such that $F$ is contained in the open $r$-neighborhood of $x$.

Let us briefly recall the well-known Mumford compactness criterion [5], that for any $r > 0$, the set of surfaces with injectivity radius at least $r$ at every point is compact in $\mathcal{M}_2$. The analogous generalization of Corollary 0.2 does not hold, since if $F$ has small enough injectivity radius at $x$ it can by deformed by making a distant curve arbitrarily short while keeping the injectivity radius at $x$ constant. Note that this increases the covering radius at $x$ to infinity.

The main “result” of the paper is really the construction of a centered dual tessellation, and the attachment of admissible spaces to its 2-cells, a process we now outline. In Section 1 we introduce terminology and define the Voronoi and Delaunay tessellations determined by a finite subset $S$ of a surface $F$. This material is standard. Section 2 gives a series of examples to motivate what follows, including a Delaunay tessellation that is not a triangulation (see Corollary 2.11), and another with a non-centered edge (see Lemma 2.13).

Section 3 gives deeper information on this failure of duality. If an edge $e$ of the Voronoi tessellation $V$ is not centered, one may orient it pointing “away” from $\gamma$. Lemma 3.3 asserts that a Delaunay 2-cell $P_v$ is centered if and only if the associated vertex $v \in V^{(0)}$ is not the initial vertex of any non-centered edge. Moreover each component of the union $V^{(1)}_n$ of non-centered edges is a tree with a canonical root vertex, by Lemma 3.6.

We define the centered dual graph $P^{(1)}_c$ to the Voronoi tessellation to be the union of edges of $P$ geometrically dual to centered edges of $V$, and show in the remainder of Section 3 that $P^{(1)}_c$ is the one-skeleton of a cell decomposition $P_c$, the centered dual decomposition of $F$, with vertex set $S$ (see Definition 3.18). By Proposition 3.16, each 2-cell $Q$ of $P_c$ is the union of Delaunay cells $P_v$ such that $v \in Q \cap V^{(0)}$. This is either $T^{(0)}$ for a component $T$ of $V^{(1)}_n$ or a vertex $v$ not contained in any such component, by Lemma 3.12.

Each 2-cell of the Delaunay tessellation is cyclic: all its vertices are equidistant from the center of the corresponding vertex of $V$ (see Lemma 1.2). It follows that such cells are each determined up to isometry by their side length collections [6] (cf. [7] or [3]). This does not hold for a centered dual 2-cell $Q$ containing a component $T$ of $V^{(1)}_n$. Instead, in Section 5 we will describe an admissible space $Ad(d_F)$, determined by $T$ and the side length collection.
d_{F} of \( Q \), that in some sense parametrizes all possible combinations of Delaunay cells that can comprise \( Q \) with side length collection \( d_{F} \). In particular see Lemma 5.4.

Our main application of the centered dual/admissible space construction is a machine for turning lower bounds on the side lengths of a centered dual 2-cell with few edges into a good lower bound on its area, described in Section 6. The corresponding problem for Delaunay 2-cells is complicated by non-centeredness: as we observed in [3], the area of a non-centered cyclic polygon decreases as the length of its longest side increases.

By Lemma 5.7, given a rooted tree \( T \) and side length collection \( d_{F} \), the sum of areas of the Delaunay polygons comprising the corresponding centered dual 2-cell determines a continuous function on the closure \( \overline{Ad}(d_{F}) \) of \( Ad(d_{F}) \). We show that if \( T \) has only one or two edges, the minimum of this function occurs at one of a few tightly-prescribed places. Section 6 describes an algorithm that produces lower bounds for the values at such locations, given lower bounds on the coordinates of \( d_{F} \).

In fact we work in Sections 5 and 6 with the radius-\( R \) defect, which in best cases records the area of the region in a polygon but outside the union of disks of radius \( R \) centered at its vertices. Section 4 is devoted to establishing Proposition 4.2, which asserts that this does hold for a centered dual 2-cell \( Q \). This proves convenient in applications.

In Section 7 we make some computations and prove Theorem 0.1. We prove Theorem 0.2 in Section 8.

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1. The Voronoi and Delaunay tessellations

This section gives a self-contained introduction to the Voronoi and Delaunay tessellations determined by a finite subset of a hyperbolic surface. Let us first establish some notation.

If \( \gamma \) is a geodesic in \( \mathbb{H}^2 \), a half-space bounded by \( \gamma \) is the closure of a component of \( \mathbb{H}^2 - \gamma \). We will say the frontier of \( K \subset \mathbb{H}^2 \) is \( fr(K) \equiv K \cap \overline{\mathbb{H}^2 - K} \). Thus for instance \( \gamma \) is the frontier of either half-space bounded by \( \gamma \). If \( \{ \mathcal{H}_i \} \) is a collection of half-spaces, each with bounding geodesic \( \gamma_i \), we say that \( P = \bigcap_i \mathcal{H}_i \) is a convex polygon if it is nonempty and the collection \( \{ \gamma_i \} \) is locally finite; ie, for each \( p \in P \) there is an open set \( U \) and a finite collection \( \{ \gamma_{i_1}, \ldots, \gamma_{i_n} \} \) of boundary geodesics such that \( U \cap (\bigcup \gamma_i) \subset \bigcup_{j=1}^n \gamma_{i_j} \).

An edge (or side) of \( P = \bigcap \mathcal{H}_i \) is \( \gamma_i \cap P \) for some \( i \) such that this intersection is non-empty or a singleton, and the boundary \( \partial P \) of \( P \) is the union of its edges. One finds that \( \partial P \) is the topological frontier \( P \cap \overline{\mathbb{H}^2 - P} \) of \( P \) in \( \mathbb{H}^2 \). A vertex of \( P \) is the nonempty intersection of two edges. We will say \( P \) is cyclic if all its vertices are equidistant from some \( v \in \mathbb{H}^2 \), the center of \( P \), and \( P \) is centered if \( v \in \text{int} P \). The radius of a cyclic polygon \( P \) is \( J \) such that \( d(v, x) = J \) for each vertex \( x \) of \( P \), where \( v \) is the center of \( P \).
By the injectivity radius of $S \subset \mathbb{H}^2$ we refer to the supremum of the set of $r \geq 0$ such that $d(x,y) > 2r$ for all distinct $x$ and $y$ in $S$. If $S$ has injectivity radius $R > 0$, then for any distinct $x$ and $y$ in $S$ the open disk $B_R(x) = \{p \in \mathbb{H}^2 | d(x,p) < R\}$ is disjoint from $B_R(y)$.

**Fact.** If $S \subset \mathbb{H}^2$ has injectivity radius $r > 0$ then $S \cap K$ is finite for any bounded set $K \subset \mathbb{H}^2$.

This is because the $R$-neighborhood of $K$ has finite area and so cannot contain infinitely many disjoint disks with a fixed positive area. It follows that if $S \subset \mathbb{H}^2$ has positive injectivity radius then it is closed and discrete. The converse is not true, but a closed and discrete set $S$ does satisfy the fact above. This will suffice to define the Voronoi and Delaunay tessellations.

For distinct $x$ and $y$ in $\mathbb{H}^2$, we will often refer by $\gamma_{xy}$ to the unique geodesic arc joining $x$ to $y$, and by $\gamma^\perp_{xy}$ to its perpendicular bisector: the hyperbolic geodesic intersecting $\gamma_{xy}$ at its midpoint $m$, at right angles. For each $p \in \gamma^\perp_{xy}$ the hyperbolic law of cosines gives:

$$\cosh d(x,p) = \cosh d(x,m) \cosh d(p,m) = \cosh d(y,p)$$

Thus the points of $\gamma^\perp_{xy}$ are equidistant from $x$ and $y$; in fact $\gamma^\perp_{xy} = \{p \in \mathbb{H}^2 | d(p,x) = d(p,y)\}$.

**Lemma 1.1.** If $S \subset \mathbb{H}^2$ is closed and discrete then for each $x \in S$, $V_x$ as defined in (0.0.1) is a convex polygon in $\mathbb{H}^2$, and if $S$ has injectivity radius $R > 0$ then $\overline{B_R(x)} \subset V_x$.

**Proof.** For $y \in S - \{x\}$, let $H_{xy}$ be the half-space containing $x$ and bounded by $\gamma^\perp_{xy}$. Then $H_{xy} = \{p | d(p,x) \leq d(p,y)\}$. It follows immediately that (0.0.1) may be rewritten as:

$$V_x = \bigcap_{y \in S - \{x\}} H_{xy}$$

Fix $p \in V_x$ and let $J = d(x,p)$. If $K = B_{3J}(p)$ then as we pointed out above the lemma, $K \cap S$ is a finite set $\{x,y_1,\ldots,y_n\}$. If $U = B_{J/2}(p)$, then for $q \in U$ the triangle inequality gives $d(x,q) < 3J/2$, so for $y$ outside of $B_{3J}(p)$ it follows that $\gamma^\perp_{xy} \cap U = \emptyset$. Therefore:

$$U \cap \left( \bigcup_{y \in S - \{x\}} \gamma^\perp_{xy} \right) \subset \bigcup_{i=1}^{n} \gamma^\perp_{xy_i},$$

and $V_x$ is a convex polygon.

If $S$ has injectivity radius $R > 0$, then since the open disk $B_R(x)$ does not intersect $B_R(y)$ for any $y \in S - \{x\}$, the points of $B_R(x)$ are closer to $x$ than any $y \in S - \{x\}$. Thus $B_R(x) \subset V_x$; in particular, $V_x$ is nonempty, and since it is closed it contains $\overline{B_R(x)}$. \[\square\]

It is easy to show that $int V_x = \{p | d(p,x) < d(p,y) \text{ for each } y \in S - \{x\}\}$, and that $\partial V_x = \bigcup_{y \in S - \{x\}} V_x \cap V_y$. Furthermore, for any $y \in S - \{x\}$ such that $V_x \cap V_y$ is nonempty, it is contained in the equidistant locus $\gamma^\perp_{xy}$. This gives:

**Fact.** If $S \subset \mathbb{H}^2$ is closed and discrete, then for distinct $x$, $y$, and $z$ in $S$, $V_x \cap V_y \cap V_z$ contains at most a single point.

This is because each point of $V_x \cap V_y \cap V_z$ is in both $\gamma^\perp_{xy}$ and $\gamma^\perp_{xz}$, and since $y \neq z$ these are distinct geodesics which therefore meet transversely in a single point (if at all).
Lemma 1.2. For \( S \subset \mathbb{H}^2 \) closed and discrete, define \( V^{(0)} = \{ V_x \cap V_y \cap V_z \mid x, y, z \in S \text{ distinct} \} \). For \( v \in V^{(0)} \), there exists \( J_v > 0 \) such that \( v \in V_x \) if and only if \( d(v, x) = J_v \) for each \( x \in S \). In particular, \( S \cap B_{J_v}(v) = \emptyset \).

Proof. Suppose \( x \in S \) has \( v \in V_x \), and let \( J_v = d(x, v) \). It follows directly from the definition (0.0.1) that \( d(v, y) \geq J_v \) for all \( y \in S - \{ x \} \). For some such \( y \), if \( v \in V_y \) then \( d(v, x) \geq d(v, y) \) by the definition of \( V_y \), so we must have \( d(v, y) = J_v \). This proves the lemma. □

Corollary 1.3. For \( S \subset \mathbb{H}^2 \) closed and discrete, \( V^{(0)} \) from Lemma 1.2 is closed and discrete.

Proof. For \( v \in V^{(0)} \) let \( J_v > 0 \) be prescribed by Lemma 1.2. Each point of \( B_{J_v}(v) \) is within \( 2J_v \) of a point of \( S \), so for \( v' \in V^{(0)} \cap B_{J_v}(v) \) we have \( J_{v'} < 2J_v \). Thus for such \( v' \), \( B_{3J_v}(v) \) contains the set of \( x \in S \) such that \( v' \in V_x \). The fact above Lemma 1.2 implies that \( v' \) is determined by this set, so since \( S \cap B_{3J_v}(v) \) is finite there can be only finitely many \( v' \in V^{(0)} \cap B_{J_v}(v) \). □

Fact. For \( S \subset \mathbb{H}^2 \) closed and discrete, \( x \in S \), and each edge \( e = V_x \cap V_y \) of \( V_x \), \( \text{int}(e) \cap V_z = \emptyset \) for each \( z \in \tilde{S} - \{ x, y \} \).

This is because \( v = e \cap V_z \) is an intersection of the geodesics \( \gamma_{xy} \) and \( \gamma_{xz} \), being equidistant from \( x \), \( y \), and \( z \), and so one interval of \( \gamma_{xy} - v \) consists entirely of points closer to \( z \) than \( x \).

By the fact above, the set of edges of Voronoi polygons has the structure of an embedded graph in \( \mathbb{H}^2 \) with vertex set \( V^{(0)} \).

Definition 1.4. For \( S \subset \mathbb{H}^2 \) closed and discrete, the Voronoi tessellation \( V \) determined by \( S \) is the cell complex structure with 2-cells of the form \( V_x \) for \( x \in S \), and with \( V^{(1)} = \bigcup \{ V_x \cap V_y \mid \text{distinct } x, y \in S \} \) and \( V^{(0)} = \bigcup \{ V_x \cap V_y \cap V_z \mid x, y, z \in S \text{ distinct} \} \).

We caution that this definition does not imply that the Voronoi tessellation has trivalent one-skeleton; only that each vertex is contained in at least three 2-cells.

Definition 1.5. Let \( V \) be the Voronoi tessellation determined by \( S \subset \mathbb{H}^2 \) closed and discrete. For \( v \in V^{(0)} \), say the collection \( \{ e_0, \ldots, e_{n-1} \} \) of edges of \( V \) containing \( v \) is cyclically ordered if for each \( i \) there exists \( x_i \in S \) so that \( e_i \) and \( e_{i+1} \) are edges of \( V_{x_i} \) (taking \( i + 1 \) modulo \( n \)).

Note that if the edges containing \( v \in V^{(0)} \) are cyclically ordered \( e_0, \ldots, e_{n-1} \) then \( e_i = V_{x_i} \cap V_{x_{i-1}} \) for each \( i \) (with \( i - 1 \) taken modulo \( n \)), where the \( x_i \) are as in the definition above.

Lemma 1.6. Let \( V \) be the Voronoi tessellation determined by \( S \subset \mathbb{H}^2 \) closed and discrete, and fix \( v \in V^{(0)} \). Let \( C = \{ p \in \mathbb{H}^2 \mid d(v, p) = J_v \} \), let the edges containing \( v \) be cyclically ordered \( \{ e_0, \ldots, e_{n-1} \} \) as in Definition 1.5, and let \( \{ x_i \} \subset S \) be the associated collection with \( e_i \) and \( e_{i+1} \subset V_{x_i} \) for each \( i \). Then \( \{ x_i \}_{i=0}^{n-1} = \{ x \in S \mid v \in V_x \} \) is cyclically ordered in the sense of [3, Definition 1.3].

Proof. For \( y \in S \), if \( d(v, y) = J_v \), then \( v \) is as close to \( y \) as to any other element of \( S \); hence \( v \in V_y \). Since \( d(v, y) = J_v = d(v, x_i) \) for each \( i \), \( v \) is in the frontier of \( V_y \) and hence is in an
edge $e$ of $V_y$. By hypothesis there is an $i$ such that $e = e_i$, so by the observation above the lemma $y = x_i$ or $x_{i-1}$. This shows that $\{x \in S \mid v \in V_x\} = \{x_i\}_{i=0}^{n-1}$.

For each $i$, since $V_{x_i}$ is convex it contains the geodesic arc $\lambda_i$ joining $x_i$ to $v$. Now fix some $i \in \{0, \ldots, n-1\}$ and a point $w \in e_i \cap B_{J_i}(v)$ near $v$. Then by convexity of $V_{x_i}$, the triangle $T_i$ determined by $v$, $w$, and $x_i$ is entirely contained in $V_{x_i}$. Also $T_i \subset \overline{B_{J_i}(v)}$, again by convexity (since $x_i \in C = \partial B_{J_i}(v)$). By the same argument, the triangle $T_{i-1}$ determined by $v$, $w$, and $x_{i-1}$ is contained in $V_{x_{i-1}} \cap \overline{B_{J_i}(v)}$. (See Figure 1.1.)

Let $\alpha_{i-1}$ be the vertex angle of $T_{i-1}$ at $v$; since $w \in \text{int}(e_i)$ this is the angle in $V_{x_{i-1}}$ between $\lambda_{i-1}$ and $e_i$. Similarly, the angle $\alpha_i$ of $T_i$ at $v$ is the angle in $V_{x_i}$ between $e_i$ and $\lambda_i$. If $\epsilon > 0$ is less than the distance from $v$ to the side $[x_i, w]$ of $T_i$ joining $x_i$ and $w$, then $T_i$ contains the entire sector of $B_\epsilon(v)$, with angle $\alpha_i$, determined by $e_i$ and $\lambda_i$. If $\epsilon < d(v, [x_{i-1}, w])$ then the analogous assertion holds for the sector of $B_\epsilon(v)$ determined by $\lambda_{i-1}$ and $e_i$.

Fix $\epsilon > 0$ satisfying the requirements of the paragraph above and let $C_\epsilon$ be the circle of radius $\epsilon$ centered at $v$. The above implies that $C_\epsilon \cap (T_{i-1} \cup T_i)$ is an interval of $C_\epsilon$ with angle measure $\alpha_{i-1} + \alpha_i$ and endpoints $\lambda_{i-1} \cap C_\epsilon$ and $\lambda_i \cap C_\epsilon$. There is a homeomorphism $C \rightarrow C_\epsilon$ that takes $x \in C$ to $C_\epsilon \cap \lambda_x$, where $\lambda_x$ is the geodesic arc joining $x$ to $v$. In particular, $x_j$ maps to $\lambda_j \cap C_\epsilon$ for each $j \in \{0, \ldots, n-1\}$. Let $I$ be the preimage of $C_\epsilon \cap (T_{i-1} \cup T_i)$ in $C$, a closed subinterval bounded by $x_{i-1}$ and $x_i$. For $j \neq i$ or $i-1$, $x_j$ maps to a point outside $C_\epsilon \cap (T_{i-1} \cup T_i)$ since $\lambda_j \subset V_{x_j}$, and so $x_j \in C - I$, a component of $C - \{x_{i-1}, x_i\}$.  

We will define the Delaunay tessellation $P$ determined by $S \subset \mathbb{H}^2$ as a sort of “dual” to the Voronoi tessellation determined by $S$. In particular we take $P^{(0)} = S$, in 1–1 correspondence with the set of 2-cells of $V$. The edges of $P$ are also determined by edges of $V$.

**Definition 1.7.** Let $V$ be the Voronoi tessellation determined by $S \subset \mathbb{H}^2$ closed and discrete. For an edge $e = V_x \cap V_y$ of $V$, the **geometric dual** to $e$ is the geodesic arc $\gamma_{xy}$ joining $x$ to $y$.

We define $P^{(1)}$ to be the union of geometric duals to edges of $V$. The lemma below establishes that $P^{(1)}$ has the structure of an embedded graph in $\mathbb{H}^2$ with vertex set $S$.

**Lemma 1.8.** Let $V$ be the Voronoi tessellation determined by $S \subset \mathbb{H}^2$ closed and discrete. If $e = V_x \cap V_y$ and $e' = V_{x'} \cap V_{y'}$ are distinct edges of $V$, then their geometric duals satisfy $\gamma_{xy} \cap \gamma_{x'y'} = \{x, y\} \cap \{x', y'\}$.
Proof. If \( x = x' \), say, then \( y \neq y' \) since \( e \) and \( e' \) are distinct, so since \( \gamma_{xy} \) and \( \gamma'_{x'y'} \) are geodesic arcs they intersect only at \( x \). We will thus assume that \( \{x, y\} \cap \{x', y'\} = \emptyset \).

If \( e \) and \( e' \) share a vertex \( v \), then upon cyclically ordering the edges containing \( v \) as \( e_0, \ldots, e_{n-1} \) as in Definition 1.5, we have \( e = e_i \) and \( e' = e_{i'} \) for distinct \( i \) and \( i' \) in \( \{0, \ldots, n-1\} \). Then \( \{x, y\} = \{x_i-1, x_i\} \) and \( \{x', y'\} = \{x_{i'-1}, x_{i'}\} \), as we observed above Lemma 1.6, and Lemma 1.2 implies that \( \gamma_{xy} \) and \( \gamma'_{x'y'} \) are chords of the circle \( C \) of radius \( J_v \) centered at \( v \).

Chords of \( C \) with distinct endpoints intersect if and only if the endpoints of one separate the endpoints of the other on \( C \). But Lemma 1.6 implies that \( x_{i'-1} \) and \( x_{i'} \) share a component of \( C - \{x_i, x_{i-1}\} \), so \( \gamma_{xy} \cap \gamma'_{x'y'} = \emptyset \) in this case. We therefore assume below that \( e \cap e' = \emptyset \).

Let \( v \) be the nearer of the two endpoints of \( e \) to \( x \) and \( y \), and let \( D_v \) be the disk of radius \( J_v \) centered at \( v \). The same construction yields \( v' \) and a disk \( D_{v'} \) of radius \( J_{v'} \) associated to \( \gamma'_{x'y'} \). By Lemma 1.2, \( \gamma_{xy} \) is a chord of the circle \( \partial D_v \), and \( \gamma'_{x'y'} \) is a chord of \( \partial D_{v'} \). If \( \gamma_{xy} \) intersects \( \gamma'_{x'y'} \), their intersection point is contained in \( D_v \cap D_{v'} \).

Claim 1.8.1. If distinct circles in \( \mathbb{H}^2 \) have intersecting chords with distinct endpoints, then one chord has an endpoint in the open disk in \( \mathbb{H}^2 \) complementary to the other circle.

Proof of claim. Let \( C \) and \( C' \) be distinct circles with chords \( \gamma \) and \( \gamma' \), respectively, that intersect. If \( C \) is contained in the open disk determined by \( C' \), then the claim is immediate. The same holds if \( C' \) is contained in the open disk determined by \( C \), so we will assume that neither of these possibilities occurs. Then \( C \) must intersect \( C' \), since each chord of \( C \) is contained in the disk that it bounds, and similarly for \( C' \).

If \( C \cap C' \) is a single point, this must also be \( \gamma \cap \gamma' \), an endpoint of each, so this cannot occur. It follows that \( C \cap C' \) consists of two points. We may assume that neither endpoint of \( \gamma \) is contained in the open disk complementary to \( C' \), since otherwise the claim holds. Since \( \gamma \) intersects \( \gamma' \), it nonetheless intersects \( C' \). If \( \gamma \cap C' \) is a single point, then this is also \( \gamma \cap \gamma' \), an endpoint of \( \gamma' \) and therefore not an endpoint of \( \gamma \). Since this endpoint of \( \gamma' \) is in the interior of \( \gamma \), the claim holds in this case.

Let us now suppose that \( \gamma \cap C' \) consists of two points, and let \( \gamma_0 \) be the closed subarc of \( \gamma \) bounded by \( \gamma \cap C' \). Then \( \gamma \cap \gamma' \subseteq \gamma_0 \). The geodesics \( \gamma \) and \( \gamma' \) intersect transversely, so \( \gamma' \) has one endpoint in each of the open sub-arcs of \( C' \) complementary to \( C' \cap \gamma \). Since one of these is contained in the open disk complementary to \( C \), the claim holds.

Using the claim, we may assume that the endpoint \( x \) of \( \gamma_{xy} \) is contained in the open disk with radius \( J_{v'} \) centered at \( v' \). But this contradicts Lemma 1.2, and the result follows.

The 2-cells of the Delaunay tessellation are associated to \( V^{(0)} \) by the lemma below. Recall that a compact, convex polygon \( P \) is cyclic if its vertices are equidistant from a fixed point, its center (see [3]), and that the radius of \( P \) is the distance from its center to the vertices.

Lemma 1.9. Let \( V \) be the Voronoi tessellation determined by \( S \subset \mathbb{H}^2 \) closed and discrete. For each \( v \in V^{(0)} \) there is a cyclic polygon \( P_v \) in \( \mathbb{H}^2 \) with center \( v \) and radius \( J_v \) (as supplied by Lemma 1.2), such that:
by construction the edge of $P$ determined by $S$. Suppose Definition 1.10. If the edges of $V$ containing $v$ are cyclically ordered $e_0, \ldots, e_{n-1}$, the vertex set of $P_v$ is the collection $\{x_i\}_{i=0}^{n-1}$ from Definition 1.5.

The edge set of $P_v$, cyclically ordered in the sense of [3, Definition 2.5], is $\{\gamma_i\}_{i=0}^{n-1}$, where $\gamma_i$ is the geometric dual to $e_i$ for each $i$. Furthermore, $P_v \cap P^{(1)} = \gamma_0 \cup \ldots \cup \gamma_{n-1}$. For $v \neq w$, $\text{int} P_v \cap P_w = \emptyset$, and $P_v$ and $P_w$ share an edge if and only if $v$ and $w$ are opposite endpoints of an edge of $V$.

Proof. Let $v$ and the collections $\{e_0, \ldots, e_{n-1}\}$, and $\{\gamma_0, \ldots, \gamma_{n-1}\}$ be as described in the hypotheses of the lemma. The observation above Lemma 1.6 implies that for each $i$, $\gamma_i$ joins $x_{i-1}$ to $x_i$, where $\{x_i\}_{i=0}^{n-1} \subseteq \mathcal{S}$ is the collection from Definition 1.5. Since the collection $\{x_i\}$ is cyclically ordered by Lemma 1.6, Lemma 1.4 of [3] asserts there is a cyclic $n$-gon $P_v$ center $v$, radius $J_v$, vertex set $\{x_i\}$ and edge set $\{\gamma_i\}$. Furthermore, since the $x_i$ are cyclically ordered, the $\gamma_i$ are as well (see [3, Definition 2.5]).

For any $x$ and $y \in \mathcal{S}$, since $V_x$ and $V_y$ are convex their intersection is connected. This implies in particular that for $i$ and $j \in \{0, \ldots, n-1\}$, if $V_{x_j}$ shares an edge $e$ with $V_{x_j}$ then $v \in e$. Since the only edges of $V_{x_j}$ that contain $v$ are $e_i$ and $e_{i+1}$, it follows that $V_{x_i} \cap V_{x_j} = \{v\}$ unless $j = i \pm 1$ or $i$. Therefore by definition, no edge of $P^{(1)}$ joins $x_i$ to $x_j$ for $j \neq i \pm 1$ (mod $n$). It thus follows from Lemma 1.8 that $P_v \cap P^{(1)} = \bigcup_{i=0}^{n-1} \gamma_i$.

If $p \in \text{int} P_v \cap P_w$, then since $\text{int} P_v \cap P^{(1)} = \emptyset$ and $\partial P_w \subseteq P^{(1)}$, $p \in \text{int} P_w$ and each geodesic ray from $p$ intersects $\partial P_v$ at or nearer to $p$ than its point of intersection with $\partial P_w$. But since $\text{int} P_w \cap P^{(1)} = \emptyset$ and $\partial P_v \subseteq P^{(1)}$, each such point is in $\partial P_w$. It follows that $\partial P_v = \partial P_w$, and hence that $P_v = P_w$ (again see [3, Lemma 1.4]). This implies that $v = w$, since $P_v$ is cyclic and a circle (and hence also its center) is determined by three points on it.

If $P_v$ shares the edge $\gamma$ of $P^{(1)}$ with $P_w$, then by construction the edge $e$ of $V$ dual to $\gamma$ contains $v$ and $w$. On the other hand, if $v$ and $w$ are vertices of an edge $e$ of $V$, then again by construction the edge of $P^{(1)}$ dual to $e$ is contained in $P_v$ and $P_w$. □

Definition 1.10. Suppose $\mathcal{S} \subset \mathbb{H}^2$ is closed and discrete. We take the Delaunay tessellation determined by $\mathcal{S}$ to be the 2-complex $P$ with vertex set $\mathcal{S}$, edge set the geometric duals to edges of the Voronoi tessellation $V$, and 2-cells $P_v$ supplied by Lemma 1.9, for $v \in V^{(0)}$. For such $v$ we will refer to $P_v$ as the associated vertex polygon.

The Delaunay tessellation $P$ is “dual” to the Voronoi tessellation $V$ in the sense that there is a canonical one-to-one correspondence between its $k$-cells and the $(2 - k)$-cells of $V$ for each $k \in \{0, 1, 2\}$. However, it is not necessarily dual in the sense of the intersection pairing: there is no reason in general that an edge of $V$ should intersect its geometric dual, or that $v \in V^{(0)}$ should be in $P_v$.

The Delaunay tessellation is sometimes defined using “circumscribed circles,” but this has its problems in the hyperbolic setting, as the example below will demonstrate.
Example 1.11. Let $x, y, z \in \mathbb{H}^2$ be distinct, and suppose that $d(y, z) \geq \max\{d(x, y), d(x, z)\}$. It follows from [3, Lemma 2.4] that $x, y, z$ lie on a circle in $\mathbb{H}^2$ if and only if

$$\sinh\left(\frac{d(y, z)}{2}\right) < \sinh\left(\frac{d(x, y)}{2}\right) + \sinh\left(\frac{d(x, z)}{2}\right)$$

We motivate this fact with Figure 1.2, which uses the “upper half-plane” model for $\mathbb{H}^2$: the set of complex numbers with positive imaginary coordinate, equipped with the hyperbolic Riemannian metric. It is well-known that in this model, each hyperbolic circle is also a Euclidean circle in $\mathbb{C}$, although with a different center and radius. However, some $x, y, z$ in $\mathbb{H}^2$ determine a Euclidean circle that does not lie entirely in $\mathbb{H}^2$, as illustrated on the right-hand side of the figure, even if they do not lie on a hyperbolic geodesic.

If (1.11.1) does not hold, then the equidistant locus $V_x \cap V_y$ does not intersect $V_z \cap V_y$, as on the right-hand side of Figure 1.2. In this case $V_x$ and $V_z$ are each a single half-plane, $V_y$ is bounded by two disjoint geodesics, and the Delaunay “tessellation” (as we have defined it) is the union of the dotted geodesic arcs $\gamma_{xy}$ and $\gamma_{xz}$. If (1.11.1) does hold, then the Euclidean circle $C$ containing $x, y, z$ lies in $\mathbb{H}^2$ and $V_x$, $V_y$, and $V_z$ intersect at its (hyperbolic) center $v$. This is pictured on the left side of Figure 1.2, with the vertex polygon $P_v$ shaded.

As in Example 1.11, the Delaunay tessellation determined by $\mathcal{S}$ does not necessarily cover $\mathbb{H}^2$; indeed, if $\mathcal{S}$ is finite then Lemma 1.9 implies that it is compact. However, we are primarily concerned here with tessellations that arise from closed hyperbolic surfaces — those which admit a locally isometric covering from $\mathbb{H}^2$.

Lemma 1.12. Let $F$ be a closed hyperbolic surface, $\mathcal{S} \subset F$ a finite set, and $\pi: \mathbb{H}^2 \to F$ a locally isometric universal covering. Then $\widetilde{\mathcal{S}} \doteq \pi^{-1}(\mathcal{S})$ has positive injectivity radius, and the Voronoi tessellation $\widetilde{V}$ and Delaunay tessellation $\widetilde{P}$ determined by $\widetilde{\mathcal{S}}$ are invariant under the $\pi_1 F$-action on $\mathbb{H}^2$ by covering transformations. Furthermore, $V_x$ as defined in (0.0.1) is a compact polygon for each $x \in \widetilde{\mathcal{S}}$, and $\widetilde{P}$ covers $\mathbb{H}^2$.

Proof. Since $\mathcal{S}$ is finite and $F$ is compact there is a lower bound $r > 0$ on the lengths of non-constant geodesic arcs in $F$ with endpoints in $\mathcal{S}$. The injectivity radius of $\widetilde{\mathcal{S}}$ is then $r/2 > 0$. Since $\widetilde{\mathcal{S}}$ is invariant under the action of $\pi_1 F$, and this action is by isometries, it follows from (0.0.1) that $p \in V_x$ if and only if $g.p \in V_{g.x}$ for $p \in \mathbb{H}^2$, $x \in \mathcal{S}$, and $g \in \pi_1 F$. Therefore $g.V_x = V_{g.x}$, and $g.(V_x \cap V_y) = V_{g.x} \cap V_{g.y}$ for $y \in \mathcal{S} - \{x\}$. It follows that $\widetilde{V}$ is $\pi_1 F$-invariant, and from this that $\widetilde{P}$ is as well.
Since \( F \) is compact, there exists \( R > 0 \) such that \( \bigcup_{y \in S} B(y, R) \) covers \( F \) (here \( B(y, R) \) is the open \( R \)-neighborhood of \( y \) in the hyperbolic metric on \( F \)). Then \( V_x \subset B(x, R) \subset \mathbb{H}^2 \) for each \( x \in \tilde{S} \), and hence it is compact. In particular, \( V_x \) has only finitely many edges and vertices.

We will show that \( \tilde{P} \) is open and closed in \( \mathbb{H}^2 \), and hence that it is all of \( \mathbb{H}^2 \). First we claim that the collection of vertex polygons is locally finite: for any given \( v \), Lemma 1.9 implies that \( \text{int}(P_v) \) is disjoint from any other vertex polygon, and that the interior of an edge intersects exactly one other vertex polygon. Each vertex of \( P_v \) is some \( x \in \tilde{S} \), and since \( V_x \) has only finitely many vertices \( x \) is in only finitely many \( P_v \). The claim follows, and therefore \( \tilde{P} = \bigcup_{v \in \tilde{V}(0)} P_v \) is closed in \( \mathbb{H}^2 \).

We claim that \( \tilde{P} \) contains an open neighborhood of each \( x \in \tilde{S} \). For such \( x \), enumerate the edges of \( V_x \) as \( e_0, \ldots, e_{n-1} \) so that \( e_i \) intersects \( e_{i+1} \) in a vertex \( v_i \) for each \( i \), taking \( i + 1 \) modulo \( n \). Then \( x \in P_{v_i} \) for each \( i \), and \( P_{v_i} \) intersects \( P_{v_{i-1}} \) along the geometric dual \( \gamma_i \) to \( e_i \) and \( P_{v_{i+1}} \) along the geometric dual \( \gamma_{i+1} \) to \( e_{i+1} \). For each \( i \) there exists \( \epsilon_i > 0 \) so that \( P_{v_i} \) intersects \( B_x(\epsilon_i) \) in the full sector determined by \( \gamma_i \) and \( \gamma_{i+1} \), and we define \( \epsilon = \min_i \{ \epsilon_i \} \) and \( C = \partial B_x(\epsilon) \). The claim follows from the fact that \( C = \bigcup_{i=0}^{n-1} (P_{v_i} \cap C) \), since by the above this set is itself open and closed in \( C \).

Edges of \( \tilde{V} \) are compact, so for each \( v \in \tilde{V}(0) \) and edge \( \gamma \) of \( P_v \), Lemma 1.9 gives \( \gamma = P_v \cap P_w \), where \( w \) is the other endpoint of the edge of \( \tilde{V} \) geometrically dual to \( \gamma \). Therefore any point in the interior of \( \gamma \) has an open neighborhood in \( \mathbb{H}^2 \) contained in \( P_v \cup P_w \). The claim above implies that each vertex of \( P_v \) also has an open neighborhood contained in \( \tilde{P} \), and it follows that \( \tilde{P} \) is open in \( \mathbb{H}^2 \).

**Definition 1.13.** For a closed hyperbolic surface \( F \), a locally isometric universal covering \( \pi: \mathbb{H}^2 \to F \), and \( \mathcal{S} \subset F \) finite, let \( \tilde{S} = \pi^{-1}(\mathcal{S}) \) and take \( V = \pi(\tilde{V}) \) and \( P = \pi(\tilde{P}) \) to be the Voronoi tessellation and Delaunay tessellation determined by \( \mathcal{S} \), respectively, where \( \tilde{V} \) and \( \tilde{P} \) are as in Lemma 1.12.

Since a convex polygon is homeomorphic to a disk, and \( \pi \) takes the interior of each edge or 2-cell of \( \tilde{V} \) or \( \tilde{P} \) isometrically to \( F \), \( V \) and \( P \) have the structure of cell decompositions of \( F \). Note also that \( \mathcal{S} = \pi(\tilde{S}) \) is the vertex set of \( P \).

## 2. Examples and tools for recognition

In this section we will take advantage of tools from [3] for understanding the geometry of cyclic polygons, so let us begin by recalling some of its notation.

**Definition 2.1** ([3], Definition 2.1). For \( n \geq 3 \), let \( \sigma: \mathbb{R}^n \to \mathbb{R}^n \) be given by \( \sigma(d_0, \ldots, d_{n-1}) = (d_1, \ldots, d_{n-1}, d_0) \), and refer by \( \mathbb{R}^n / \mathbb{Z}_n \) to the quotient by the action of \( \mathbb{Z}_n = \langle \sigma \rangle \), and by
Let \( d_0, \ldots, d_{n-1} \) to the equivalence class in \( \mathbb{R}^n/\mathbb{Z}_n \) of \( (d_0, \ldots, d_{n-1}) \). Define:

\[
\tilde{\mathcal{C}}_n = \begin{cases} 
(d_0, \ldots, d_{n-1}) \in (\mathbb{R}^+)^n & \text{sinh}(d_i/2) < \sum_{j \neq i} \sinh(d_j/2) \text{ for each } i \in \{0, \ldots, n-1\} 
\end{cases}
\]

\[
\tilde{\mathcal{C}}_n = \begin{cases} 
(d_0, \ldots, d_{n-1}) \in (\mathbb{R}^+)^n & \sum_{j=0}^{n-1} A_{d_j}(d_i/2) > 2\pi, \text{ where } d_i \geq d_j \forall j \in \{0, \ldots, n-1\} 
\end{cases}
\]

The point of this definition is that by [3, Proposition 2.7], each \( (d_0, \ldots, d_{n-1}) \in \tilde{\mathcal{C}}_n \) determines a cyclic \( n \)-gon with cyclically ordered side length collection given by its entries; this \( n \)-gon is unique up to isometry of \( \mathbb{H}^2 \); and two such points determine the same (oriented) \( n \)-gon if and only if they have the same class in \( \mathcal{A}_n \). We will say a cyclic \( n \)-gon is represented by \( (d_0, \ldots, d_{n-1}) \in \tilde{\mathcal{C}}_n \) if this tuple describes its cyclically ordered side length collection. [3, Proposition 2.7] further implies that each cyclic \( n \)-gon is represented by a point of \( \tilde{\mathcal{C}}_n \).

The function \( A_d(J) \) used in the definition of \( \tilde{\mathcal{C}}_n \) is defined in [3, Lemma 1.7]. Each point in \( \tilde{\mathcal{C}}_n \) determines a centered \( n \)-gon, a cyclic polygon \( P \) with center \( v \in \text{int} \, P \) (recall from the beginning of Section 1 that the center of \( P \) is the center of the circle containing its vertices). Conversely, if \( (d_0, \ldots, d_{n-1}) \in \tilde{\mathcal{C}}_n \) represents a centered \( n \)-gon then it is in \( \tilde{\mathcal{C}}_n \). (It is not immediately obvious that \( \tilde{\mathcal{C}}_n \subset \tilde{\mathcal{C}}_n \), but this is proved in [3, Lemma 2.3].)

**Example 2.2.** Taking \( D_0 : \tilde{\mathcal{C}}_3 \to \mathbb{R}^+ \) as in [3, Definition 5.1], determine \( d_\alpha > 0 \) by:

\[
4\pi = 6 \cdot D_0(d_\alpha, d_\alpha, d_\alpha) = 6 \cdot D_{0,3}(d_\alpha) = 6 \cdot \left[ \pi - 6 \sin^{-1} \left( \frac{1}{2 \cosh(d_\alpha/2)} \right) \right]
\]

The latter equalities above follow from [3, Lemma 6.6]. Let \( r_\alpha = d_\alpha/2 \). Rearranging the equation above and taking sines of both sides gives:

\[
cosh r_\alpha = \frac{1}{2 \sin(\pi/18)} \cong 2.8794 \quad \cosh d_\alpha = \frac{1}{1 - \cos(\pi/9)} - 1 \cong 15.5817
\]

By [3, Proposition 2.7] there is a centered triangle in \( \mathbb{H}^2 \), unique up to isometry, with all side lengths \( d_\alpha \). Six copies \( T_1, \ldots, T_6 \) of this triangle may be arranged in \( \mathbb{H}^2 \) so that they share a vertex and have disjoint interiors, and \( T_i \) shares an edge with \( T_{i+1} \) for \( 1 < i < 6 \). Their union is thus an octahedron \( O_\alpha \), with all side lengths \( d_\alpha \) and area \( 4\pi \) by construction. The Gauss-Bonnet formula implies that \( O_\alpha \) has total angle defect \( 2\pi \), so its quotient by some scheme for pairing edges that reverses boundary orientations and identifies all vertices is a genus-2 surface \( F_\alpha \). Let \( x_\alpha \in F_\alpha \) be the projection of the vertices of \( O_\alpha \).

Since the angle measures of the \( T_i \) total \( 2\pi \), each has angle \( \pi/9 \) at each vertex. For each \( i \), open disks of radius \( r_\alpha \) centered at the vertices of \( T_i \) do not intersect (see [3, Lemma 5.3]), and each intersects \( T_i \) in a full sector of angle measure \( \pi/9 \). Since the six non-overlapping \( T_i \) comprise \( O_\alpha \), a collection of open disks of radius \( r_\alpha \) centered at each vertex of \( O_\alpha \) intersects it in the non-overlapping union of 18 sectors of angle measure \( \pi/9 \). This projects to a
The latter equalities follow from [3, Lemma 6.6]. Applying the identity $2 \sin \alpha \cos \alpha = \cosh 2R$, since $O_\alpha$ has edge lengths $d_\alpha = 2r_\alpha$, $F_\alpha$ has injectivity radius $r_\alpha$ at $x_\alpha$.

Boroczky’s Theorem [1] implies that $r_\alpha$ is the largest injectivity radius possible at any point in any genus-two hyperbolic surface.

**Lemma 2.3.** A closed, orientable hyperbolic surface $F$ of genus 2 has injectivity radius at most $r_\alpha$ at any $x \in F$.

**Proof.** Fix a locally isometric universal covering map $p : \mathbb{H}^2 \to F$. If $F$ has injectivity radius $R$ at $x$, then by definition it contains an isometrically embedded open hyperbolic disk $D$, with radius $R$, centered at $x$. Each point of $p^{-1}(x)$ is contained in a lift of $D$ to $\mathbb{H}^2$, and since $D$ is embedded in $F$ two such lifts do not overlap unless they are identical. Thus $p^{-1}(D)$ is a packing of $\mathbb{H}^2$.

Let $\tilde{V}$ be the Voronoi decomposition of $\mathbb{H}^2$ determined by $p^{-1}(x)$. Since $p^{-1}(x)$ has injectivity radius $\alpha$, for any $\tilde{x} \in p^{-1}(x)$, $V_{\tilde{x}}$ contains the lift $\tilde{D}$ of $D$ centered at $\tilde{x}$ (see Lemma 1.1). The main theorem of [1] implies:

$$\frac{\text{area}(\tilde{D})}{\text{area}(V_{\tilde{x}})} \leq d(R) = \frac{3\alpha(R) \cdot (\cosh R - 1)}{\pi - 3\alpha(R)}$$

Here $\alpha(R)$ is the vertex angle of an equilateral triangle in $\mathbb{H}^2$ with sides of length $2R$. Since $V_{\tilde{x}}$ projects onto $F$, isometrically on its interior, and $\tilde{D}$ projects isometrically to $D$ we have:

$$\frac{\text{area}(D)}{\text{area}(F)} \leq \frac{3\alpha(R) \cdot (\cosh R - 1)}{\pi - 3\alpha(R)}$$

Since $F$ has area $4\pi$ and $D$ has area $2\pi(\cosh R - 1)$, the above inequality simplifies to $\alpha(R) \geq \pi/9$. The hyperbolic law of cosines implies:

$$\cos \alpha(R) = \frac{\cosh^2(2R) - \cosh(2R)}{\sinh^2(2R)} = \frac{\cosh(2R)}{\cosh(2R) + 1} = 1 - \frac{1}{\cosh(2R) + 1}$$

Solving for $\cosh(2R)$ and applying the “half-angle” identities for the sine and hyperbolic cosine functions gives $\cosh R = 1/2 \sin(\alpha(R)/2) \leq 1/2 \sin(\pi/18)$. The conclusion follows. \[\square\]

**Example 2.4.** Let $d_\beta > 0$ be determined by the following criterion:

$$4\pi = 4 \cdot D_0(d_\beta, d_\beta, d_\beta) + D_0(d_\beta, d_\beta, d_\beta, d_\beta) = 4 \cdot D_{0,3}(d_\beta) + D_{0,4}(d_\beta)$$

$$= 4 \cdot \left[ \pi - 6 \sin^{-1} \left( \frac{1}{2 \cosh(d_\beta/2)} \right) \right] + 2\pi - 8 \sin^{-1} \left( \frac{\sqrt{2}}{2 \cosh(d_\beta/2)} \right)$$

The latter equalities follow from [3, Lemma 6.6]. Applying the identity $2 \sin^{-1} x = \cos^{-1}(1 - 2x^2)$ and the half-angle identity for hyperbolic cosine, and re-arranging yields:

$$\frac{\pi}{2} = 3 \cos^{-1} \left( \frac{\cosh d_\beta}{\cosh d_\beta + 1} \right) + \cos^{-1} \left( \frac{\cosh d_\beta - 1}{\cosh d_\beta + 1} \right)$$
Thus \( m \) and \( r \)

\[
\frac{d}{2}
\]

\[
\text{After taking cosines of both sides and simplifying with trigonometric identities we find that } y = \cosh d_{\beta} + 1 \text{ satisfies } y^3 - 17y^2 + 16y - 4, \text{ and hence that } x = y - 1 \text{ is as described in Theorem 0.1. With } r_{\beta} = d_{\beta}/2 \text{ we have:}
\]

\[
\cosh d_{\beta} \cong 15.0166 \quad \cosh r_{\beta} \cong 2.8299
\]

Let \( Q \) be a centered quadrilateral and \( T_1, T_2, T_3, T_4 \) centered triangles, each with all side lengths \( d_{\beta} \). These exist by [3, Proposition 2.7]. Arrange them in \( \mathbb{H}^2 \) so that they are pairwise non-overlapping and \( T_i \) shares an edge with \( Q \) for each \( i \). Then \( O_{\beta} = Q \cup (\bigcup T_i) \) is a hyperbolic octahedron with area \( 4\pi \), and hence total angle defect \( 2\pi \). An edge-pairing scheme as in Example 2.2 yields a genus-2 surface \( F_{\beta} \), and arguing as in Example 2.2 we find that \( F_{\beta} \) has injectivity radius \( r_{\beta} \) at the point \( x_{\beta} \in F_{\beta} \) descended from the vertices of \( O_{\beta} \).

We now prove a few preliminary results that will allow us to pin down the Voronoi and Delaunay tessellations in Examples 2.2 and 2.4.

**Lemma 2.5.** Let \( V \) be the Voronoi tessellation determined by \( S \subset \mathbb{H}^2 \) with injectivity radius \( R > 0 \), and let \( B_0 = \cosh^{-1}(2 \cosh(2R) - 1) \). For \( x, y \in S \), if \( d(x, y) \leq B_0 \) then the midpoint \( m \) of the geodesic arc \( \gamma_{xy} \) joining \( x \) to \( y \) is in \( V_x \cap V_y \). If \( d(x, y) < B_0 \) then \( \gamma_{xy} \) is the geometric dual to an edge \( e = V_x \cap V_y \) of \( V \) with \( m = \gamma_{xy} \cap e \in \text{int}(e) \), and \( V_x \cup V_y \) contains an open neighborhood of \( \gamma_{xy} \).

**Proof.** For \( z \in S - \{x, y\} \), let \( \alpha_x \in [0, \pi] \) be the angle between \( z \) and \( x \) as measured from \( m \), and let \( \alpha_y \) be the angle from \( z \) to \( y \). Since \( m \) is in the interior of the geodesic arc \( \gamma_{xy} \) we have \( \alpha_x + \alpha_y = \pi \), so one of \( \alpha_x \) and \( \alpha_y \) is at most \( \pi/2 \). Assuming (without loss of generality) that \( \alpha_x \leq \pi/2 \), the hyperbolic law of cosines gives:

\[
\cosh d(x, z) = \cosh d(m, z) \cosh d(x, m) - \sinh d(m, z) \sinh d(x, m) \cos \alpha_x
\]

\[
\leq \cosh d(m, z) \cosh d(x, m)
\]

Let \( R_0 = B_0/2 \). The “half-angle identity” for hyperbolic cosine implies that \( R_0 \) satisfies

\[
\cosh R_0 = \sqrt{\frac{1}{2}(\cosh B_0 + 1)} = \sqrt{\cosh(2R)}
\]

If \( d(x, y) \leq B_0 \) then \( d(x, m) = \frac{1}{2}d(x, y) < R_0 \). Since \( d(x, z) \geq 2R \), combining expressions above yields:

\[
\cosh d(m, z) \geq \frac{\cosh d(x, z)}{\cosh d(x, m)} \geq \frac{\cosh(2R)}{\sqrt{\cosh(2R)}} = \cosh R_0
\]

Thus \( m \) is at least as close to \( x \) and \( y \) as to \( z \) and, since \( z \in S \) is arbitrary, \( m \in V_x \cap V_y \).

If \( d(x, y) < B_0 \), let \( \eta = \frac{\cosh R_0}{\operatorname{cosh} d(x, m)} > 1 \). The inequality above gives \( \cosh d(m, z) \geq \eta \cdot \cosh R_0 \) in this case. Thus if \( R_1 = \cosh^{-1}(\eta \cosh R_0) \) and \( \delta = R_1 - R_0 \), for \( p \in B_{\delta/2}(m) \) the triangle inequality gives:

\[
d(p, x) < R_0 + \delta/2 = R_1 - \delta/2 < d(p, z)
\]
Thus in this case $B_{\delta/2}(m) \subset V_x \cup V_y$, and if $\gamma_{xy}$ is the perpendicular bisector to $\gamma_{xy}$ then $\gamma_{xy} \cap B_{\delta/2}(m) \subset e = V_x \cap V_y$. In particular, $m = \gamma_{xy} \cap \gamma_{xy} \in \text{int}(e)$, and $\text{int}(V_x) \cup B_{\delta/2}(m) \cup \text{int}(V_y)$ is an open neighborhood of $\gamma_{xy}$ in $V_x \cup V_y$. \hfill \blacksquare

**Lemma 2.6.** Let $P$ be a centered polygon in $\mathbb{H}^2$ with center $v \in \text{int} P$. For a vertex $x$ of $P$, let $Q_x \subset P$ be the quadrilateral with vertices $v$, $x$, and the midpoints of the edges of $P$ containing $x$. Then $P = \bigcup Q_x$, taken over all vertices of $P$. For $y \in P$, $y \in Q_x$ if and only if $d(y, x) \leq d(y, x')$ for each vertex $x'$ of $P$.

**Proof.** Let $J$ be the radius of $P$ — ie, the distance from $v$ to the vertices of $P$ — and let $x_{\pm}$ be the vertices adjacent to $x$ on $\partial P$. The geodesic arc $e_+$ that joins $v$ to the midpoint $m_+$ of the edge $\gamma_+$ of $P$ containing $x$ and $x_+$ meets $\gamma_+$ at a right angle, since it is the fixed axis of a reflective involution of the isosceles triangle $\Delta_+$ with vertices $v$, $x$, and $x_+$. Thus $e_+$ is contained in the perpendicular bisector $\gamma_{xy}$. The same holds true for the other edge $e_-$ of $Q_x$ containing $v$, and it follows that points of $Q_x$ are at least as close to $x$ as to either of $x_{\pm}$.

The center $v$ is in $Q_x$ and satisfies $d(v, x) = J = d(v, x')$ for all other vertices $x'$ of $P$, so the conclusion holds for $v$. Fix $y \in Q_x \setminus \{v\}$. If $x'$ is a vertex of $P$ other than $x$, $x_+$ or $x_-$, then the geodesic arc from $y$ to $x'$ crosses one of $e_{\pm}$, say $e_+$. Let $T$ be the triangle with vertices $v$, $y$, and $x$, and let $T'$ have vertices $v$, $y$, and $x'$. Each of $T$ and $T'$ has an edge with length $d(y, v)$ and an edge with length $J = d(x, v) = d(x', v)$. We consider two cases.

If the geodesic arc from $y$ to $x'$ crosses the arc from $v$ to $x$, as on the left-hand side of Figure 2.1, then clearly the angle $\theta'$ of $T'$ at $v$ is larger than the angle $\theta$ of $T$ at $v$. Hence the hyperbolic law of cosines implies in this case that $d(x, y) < d(x', y)$.

If not, then $\theta \leq \theta_+/2$, where $\theta_+$ is the angle at $v$ of the isosceles triangle $\Delta_+$ determined by $v$, $x$, and $x_+$. This is because $y$ lies in $\Delta_+$ between its bisector $e_+$ and the edge joining $v$ to $x$ (see the right-hand side of Figure 2.1). On the other hand, the arc from $y$ to $x'$ exits $\Delta_+$ at a point in the edge joining $v$ to $x_+$, since it crosses $e_+$. Therefore $\theta' > \theta/2 \geq \theta$, and again by the hyperbolic law of cosines we have $d(x, y) < d(x', y)$.

For $y \neq v$, the geodesic ray from $v$ in the direction of $y$ exits $P$ at a point in some edge $\gamma$. By construction $\gamma \subset Q_x \cup Q_{x'}$, where $x$ and $x'$ are the endpoints of $\gamma$. Thus $y$ is in $Q_x$ or $Q_{x'}$, say $Q_x$, since $v \in Q_x \cap Q_{x'}$ and these are convex quadrilaterals. For another vertex $x''$,
if \( d(y,x'') \leq d(y,x) \) then \( d(y,x'') = d(y,x) \), by the property of \( Q_x \) that we showed above. It follows that \( x \) is adjacent to \( x'' \) on \( \partial P \), since we showed that \( d(x'',y) > d(x,y) \) otherwise. In this case \( Q_x \cap Q_{x''} \) is the intersection of \( Q_x \) with the equidistant locus of \( x \) and \( x'' \) by construction, so \( y \) is in \( Q_x \cap Q_{x''} \). The lemma follows.

\[ \square \]

**Lemma 2.7.** Let \( P \) be a centered polygon in \( \mathbb{H}^2 \) with radius \( J \) and center \( v \). For each \( y \in P - \{v\} \) there is a vertex \( x \) such that \( d(x,y) < J \).

**Proof.** Let \( \{x_i\}_{i=0}^n \) be the set of vertices of \( P \), enumerated so that for each \( i \) there is an edge of \( P \) containing \( x_i \) and \( x_{i+1} \) (with \( i + 1 \) taken modulo \( n \)), and for each \( i \) let \( Q_i \) be the quadrilateral associated to \( x_i \) by the construction of Lemma 2.6. It is clear by construction that \( P = \bigcup_{i=0}^{n-1} Q_i \), so for any \( y \in P - \{v\} \) there exists \( i \in \{0, \ldots, n-1\} \) so that \( y \in Q_i \). The conclusion of Lemma 2.6 implies that \( x_i \) is a closest vertex to \( y \).

**Claim 2.7.1.** For any \( i \in \{0,1,\ldots,n-1\} \) and \( y \in Q_i - \{v\} \), \( d(y,x_i) < J \).

**Proof.** The geodesic ray from \( x_i \) through \( y \) intersects one of the edges of \( Q_i \) containing \( v \) at a point \( y_0 \). If \( y_0 = v \), then since \( y \neq v \) is on the geodesic arc joining \( x_i \) to \( v \), the claim follows immediately. Otherwise let us consider the right triangle determined by \( x_i, y_0 \), and the other endpoint of the edge containing \( v \) and \( y_0 \), call it \( m \). The hyperbolic law of cosines gives:

\[
\cosh d(x_i, y_0) = \cosh d(x_i, m) \cosh d(m, y_0) = \cosh R \cosh d(m, y_0)
\]

Since \( y_0 \) is contained in the geodesic arc joining \( m \) to \( v \), and is not \( v \), we have \( d(m, y_0) < d(m, v) \). When applied to the triangle determined by \( x_i, v, \) and \( m \), the hyperbolic law of cosines gives \( \cosh R \cosh d(m, v) = \cosh J \). Thus by the above \( d(x_i, y_0) < J \), and since \( d(x_i, y) \leq d(x_i, y_0) \), the claim follows.

\[ \square \]

The lemma follows immediately.

\[ \square \]

**Proposition 2.8.** Let \( S \subset \mathbb{H}^2 \) have injectivity radius \( R > 0 \). If a centered \( n \)-gon \( P \) in \( \mathbb{H}^2 \) has vertices in \( S \), sides of length less than \( B_0 \) (from Lemma 2.5), and \( \text{int}(P) \cap S = \emptyset \), then:

1. \( P = P_v \) as in Lemma 1.9, where \( v \) is the center of \( P \); and
2. the Voronoi tessellation \( V \) determined by \( S \) satisfies \( V^{(0)} \cap P = \{v\} \), and \( V^{(1)} \cap P \) is the union of geodesic arcs joining \( v \) to the midpoint of each side of \( P \); and

**Proof.** Let the vertices of \( P \) be cyclically ordered \( x_0, \ldots, x_{n-1} \) in the sense of [3, Definition 1.3], and for each \( i \) let \( \gamma_i \) be the edge of \( P \) joining \( x_{i-1} \) to \( x_i \) (taking \( i - 1 \) modulo \( n \)). By Lemma 2.5, \( \gamma_i \) has an open neighborhood contained in \( V_{x_{i-1}} \cup V_{x_i} \) for each \( i \). Since \( \text{int} P \cap S = \emptyset \) and Voronoi cells are connected, it follows that \( P \subseteq \bigcup_{i=0}^{n-1} V_{x_i} \).

For each \( i \in \{0, \ldots, n-1\} \), Lemma 2.6 implies that the quadrilateral \( Q_{x_i} \) described there is contained in \( V_{x_i} \), since its points are as close to \( x_i \) as any \( x_j \) for \( j \neq i \). Since \( P = \bigcup_{i=0}^{n-1} Q_i \) it follows that \( Q_i = P \cap V_{x_i} \) for each \( i \). The description of the Voronoi tessellation follows immediately; in particular, \( Q_{x_{i-1}} \cap Q_{x_i} \) is contained in an edge \( e_i = V_{x_{i-1}} \cap V_{x_i} \) containing \( v \) for each \( i \). For each \( i \), \( \gamma_i \) is the geometric dual to \( e_i \), so Lemma 1.9 implies that \( P = P_v \). \[ \square \]
Corollary 2.9. Let $S \subset \mathbb{H}^2$ have injectivity radius $R > 0$. For $3 \leq n \leq 6$, a cyclic $n$-gon $P$ with vertices in $S$ and all sides of length $2R$ satisfies the conclusions of Proposition 2.8.

Proof. Since $B_0 > 2R$ by its definition in Lemma 2.5, the result will follow from Proposition 2.8 once we show that $P$ is centered and $\text{int} P \cap S = \emptyset$. $P$ is represented by $(d, \ldots, d) \in \tilde{\mathcal{AC}}_n$. [3, Lemma 6.6] implies that $(d, \ldots, d) \in \tilde{C}_n$, and hence that $P$ is centered, and furthermore that its radius $J = J_n(d)$ satisfies $\sinh J = \sinh(d/2)/\sin(\pi/n)$. If $n \leq 6$ then $\sin(\pi/n) \geq 1/2$, so $\sinh J \leq 2 \sinh R < \sinh(2R)$. Since the hyperbolic sine is increasing on $\mathbb{R}^+$ it follows that $J < 2R$. Thus since the points of $P$ have distance at most $J$ from $x$ by Lemma 2.7, and $J < 2R$ in this case, $P$ has no points of $S$ but the $x_i$. □

Corollary 2.10. Let $F_\alpha$ and $x_\alpha \in F_\alpha$ be as in Example 2.2. The Delaunay tessellation of $F_\alpha$ determined by $S = \{x_\alpha\}$ is the triangulation by the projections of $T_1, \ldots, T_6$ described there, and each edge intersects the interior of its geometric dual.

Proof. Let $O_\alpha = T_1 \cup \ldots \cup T_6 \subset \mathbb{H}^2$, as described in Example 2.2. Given a scheme for isometrically pairing edges of $O_\alpha$ to produce $F_\alpha$ as in Example 2.2, for each pair of edges $e$ and $e'$, there is an orientation–preserving isometry $f$ of $\mathbb{H}^2$ with $f(e) = e'$ and $f(O_\alpha) \cap O_\alpha = e'$. The Poincaré polyhedron theorem asserts that the set of these edge pairings generates a discrete group $\Pi$ of isometries with fundamental domain $O_\alpha$, and that the quotient map $\mathbb{H}^2 \to \mathbb{H}^2/\Pi = F_\alpha$ is a locally isometric universal covering. In particular, $\Pi$-translates of $O_\alpha$ tessellate $\mathbb{H}^2$.

Since $O_\alpha$ is itself tessellated by the $T_i$, $\mathbb{H}^2$ is tessellated by $\Pi$-translates of these six triangles. The preimage $\tilde{S}$ of $S$ in $\mathbb{H}^2$ is the set of vertices of $\Pi$-translates of $O_\alpha$, so the vertices of any $\Pi$-translate of any $T_i$ are in $\tilde{S}$. $F_\alpha$ has injectivity radius $r_\alpha$ at $x_\alpha$, so $\tilde{S}$ also has injectivity radius $r_\alpha$. Thus since $T_i$ has edge length $d_\alpha = 2r_\alpha$ for each $i$, Corollary 2.9 implies that each translate of each $T_i$ is a two-cell of the Delaunay tessellation of $\mathbb{H}^2$ determined by $\tilde{S}$. Lemma 2.5 further implies that each edge of each $T_i$ intersects the interior of its geometric dual, and the conclusion for $F_\alpha$ follows from Definition 1.13. □

The Voronoi tessellation from Example 2.2 is easily described. A similar proof establishes:

Corollary 2.11. Let $T_\beta$, $Q$, $F_\beta$, and $x_\beta \in F_\beta$ be as in Example 2.4. The Delaunay tessellation of $F_\beta$ determined by $\{x_\beta\}$ is the decomposition described there, into $T_1, \ldots, T_4$ and $Q$, all with side lengths $d_\beta$. Each edge intersects the interior of its geometric dual.

In particular, the Delaunay tessellation of $F_\beta$ is not a triangulation. The example below shows that the conclusion of Theorem 0.1 fails upon slightly relaxing the hypothesis $r \geq r_\beta$.

Example 2.12. We will produce a family of surfaces $F_\epsilon$ by perturbing the surface $F_\beta$ from Example 2.4. By [3, Lemma 6.8], the equation determining $d_\beta$ can be rewritten as

$$4\pi = 4 \cdot D_{0,3}(d_\beta) + 2 \cdot D_0(b_\beta, d_\beta, d_\beta),$$

where $b_\beta = \cosh^{-1}(2 \cosh d_\beta - 1) = b_0(d_\beta, d_\beta)$. This reflects the geometric observation, also in [3, Lemma 6.8], that the quadrilateral $Q$ from Example 2.4 has a diagonal that contains
its center and divides it into triangles $T_0$ and $T'_0$, each with side length collection $(b_\beta, d_\beta, d_\beta)$. Re-naming if necessary, we will assume that $T'_0$ shares an edge with $T_1$ from Example 2.4.

For $t$ near 0 let $d_t = d_\beta + t$, $b_t = \cosh^{-1}(2 \cosh d_t - 1)$, and let $d_1(t)$ satisfy $d_1(0) = d_\beta$ and $f(t, d_1(t)) = 4\pi$, where:

$$f(t, d) = 3 \cdot D_0(d) + D_0(d, d_t, d_t) + D_0(b_t, d, b_t, d, d_t)$$

We note that $d_0 = d_\beta$ and $b_0 = b_\beta$, and by comparing with the equation above one finds that $f(0, d_\beta) = 4\pi$. To produce $d_1(t)$ we note that [3, Proposition 5.5] implies:

$$\frac{\partial f}{\partial d}(0, d_\beta) = \frac{1}{\cosh^2(d_\beta/2)} - \frac{1}{\cosh^2 J_3(d_\beta)} > 0,$$

since $(d_\beta, d_\beta, d_\beta) \in \mathcal{C}_3$ by [3, Lemma 6.6], and $J_3(d_\beta) < d_\beta/2$. Therefore the implicit function theorem yields $\epsilon > 0$ and a function $d_1$ on $(-\epsilon, \epsilon)$ with $d_1(0) = d_\beta$ and $f(t, d_1(t)) = 4\pi$ for each $t \in (\epsilon, \epsilon)$.

By [3, Lemma 6.6], $(d_t, d_t, d_t) \in \mathcal{C}_3$ for each $t$ such that $d_t > 0$; we may as well assume this is all of $(-\epsilon, \epsilon)$. Moreover, $(b_t, d_t, d_t) \in \mathcal{BC}_3$ for each such $t$ by the definition of $b_t$ and [3, Lemma 6.2]. We may also assume that for each $t \in (-\epsilon, \epsilon)$, each of $(b_t, d_t, d_1(t))$, and $(d_1(t), d_t, d_t)$ is in $\mathcal{AC}_3$, since this set is open in $\mathbb{R}^3$.

For each $t$, let $T_2(t)$, $T_3(t)$, and $T_4(t)$ be centered triangles with all side lengths $d_t$. Let $T_0(t)$ be a cyclic triangle with cyclically ordered side length collection $(b_t, d_t, d_t)$, let $T'_0(t)$ have side length collection $(b_t, d_t, d_1(t))$, and let $T_1(t)$ have side length collection $(d_1(t), d_t, d_t)$. That these exist follows from [3, Definition 3.1] and [3, Proposition 2.7].

Note that $T_i(0) = T_i$ for $0 \leq i \leq 4$, and $T'_0(0) = T'_0$. Arranging the triangles in $\mathbb{H}^2$ so that at time 0 their union is $O_\beta$, and they have the same combinatorial pattern of intersection for all time, their union at each time $t$ is an octagon $O_t$ with all side lengths $d_t$ and area $4\pi$ by construction. The total angle defect of $O_t$ is thus $2\pi$, so an isometric edge-pairing scheme that is combinatorially identical to that for $O_\beta$ produces a surface $F_t$. Let $x_t \in F_t$ be the quotient of the vertices of $O_t$. One can show as in the previous examples that for each $t < 0$, $F_t$ has injectivity radius $r_t = d_t/2$ at $x_t$. Since $d_1$ decreases in $t$, $d_1(t) < d_t$ for $t > 0$, so $F_t$ has injectivity radius at most $d_1(t)/2$ for such $t$.

We prove in the lemma below that for $t < 0$, the conclusion of Theorem 0.1 does not apply to the surfaces $F_t$ from Example 2.12, though the Delaunay tessellation is a triangulation. Recall from the example that for such $t$, $F_t$ has injectivity radius $r(t) < r_\beta$ at $x_t$.

**Lemma 2.13.** For $O_t$, $F_t$, and $x_t \in F_t$ as in Example 2.12, and $t < 0$ but near to it, the triangulation that $F_t$ inherits from $O_t$ is its Delaunay tessellation determined by $\{x_t\}$. Each edge of this triangulation intersects the interior of its geometric dual edge except for $T_0(t) \cap T'_0(t)$, which intersects an endpoint of its geometric dual.
Therefore for reference we have depicted the open neighborhood contained in the union of the Voronoi cells determined by its endpoints. 

\[ \text{Figure 2.2. } P = T_0 \cup T_1(\delta) \cup T_2(\delta) \text{ and its intersection with } \tilde{V}(1). \]

**Proof.** For each \( t \), the Poincaré polyhedron theorem implies that \( \Pi_t \)-translates of \( O_t \) tessellate \( \mathbb{H}^2 \), where \( \Pi_t \) is the group generated by the edge-pairing isometries of \( O_t \) yielding \( F_t \). It follows that \( \mathbb{H}^2 \) is triangulated by \( \Pi_t \)-translates of \( T_0'(t) \) and the \( T_i(t) \) for \( 0 \leq i \leq 4 \). The preimage \( \tilde{S}_t \) of \( x_t \) in \( \mathbb{H}^2 \) is the set of vertices of \( \Pi_t \)-translates of \( O_t \).

For \( i = 2, 3, \) or \( 4 \), since \( T_i(t) \) has all side lengths equal to \( d_t = 2r_t \), Corollary 2.9 implies that each of its \( \Pi_t \)-translates is a 2-cell of the Delaunay tessellation \( \tilde{P} \) of \( \mathbb{H}^2 \) determined by \( \tilde{S} \). Lemma 2.5 applies to the edges of these polygons, and asserting in particular that each intersects the interior of its geometric dual.

For reference we have depicted \( T_0(t) \cup T_0'(t) \cup T_1(t) \) in Figure 2.2, and labeled its vertices. By construction, each \( x_t \) is in \( \tilde{S}_t \), and each frontier edge has length \( d_t \). Lemma 2.5 thus implies that each frontier edge is in \( \tilde{P}^{(1)} \), intersects the interior of its geometric dual, and has an open neighborhood contained in the union of the Voronoi cells determined by its endpoints.

The edge \( T_0'(t) \cap T_1(t) \), joining \( x_0 \) to \( x_3 \) in the figure, has length \( d_1(t) \). Since \( b_1(0) = d_\beta = b_0 \), the inequality \( d_1(t) < b_t \) holds for \( t \) near to 0. For such \( t \), since \( d_1(t) < b_t = \cosh^{-1}(2\cosh d_t - 1) \), Lemma 2.5 asserts that \( T_0'(t) \cap T_1(t) \) is in \( \tilde{P}^{(1)} \) and intersects the interior of its geometric dual, and [3, Lemma 6.2] implies that \( (d_1(t), d_t, d_t) \in \tilde{C}_3 \). Therefore \( T_1(t) \) is centered, and since it intersects \( \tilde{S} \) in its vertex set, Proposition 2.8 implies it is a Delaunay 2-cell intersecting \( \tilde{V}^{(1)} \) as illustrated in Figure 2.2.

It remains to consider \( T_0(t) \cup T_0'(t) \). We have already showed that its frontier is in \( P^{(1)} \), and moreover has an open neighborhood contained in \( V_{x_0} \cup V_{x_1} \cup V_{x_2} \cup V_{x_3} \). Since \( T_0(t) \cup T_0'(t) \cap \tilde{S} = \{x_0, x_1, x_2, x_3\} \) and Voronoi cells are connected, \( T_0(t) \cup T_0'(t) \) is entirely contained in \( V_{x_0} \cup V_{x_1} \cup V_{x_2} \cup V_{x_3} \). We claim that \( V_{x_0} \) intersects \( V_{x_2} \) in an edge \( e \), whose geometric dual \( T_0(t) \cap T_0'(t) \) is thus in \( \tilde{P}^{(1)} \) and furthermore intersects \( e \) in an endpoint. It will follow immediately that \( T_0(t) \) and \( T_0'(t) \) are each Delaunay 2-cells.

Since \( \cosh b_t = 2\cosh d_t - 1 \) by construction, [3, Lemma 6.2] implies that \( (b_t, d_t, d_t) \in \tilde{BC}_3 \). Therefore \( T_0(t) \) has its center \( v_0 \) at the midpoint of its longest edge \( T_0(t) \cap T_0'(t) \) by [3, Lemma 3.9]. On the other hand, we pointed out below (2.12.2) that \( d_1 \) is decreasing in \( t \), so \( d_1(t) > d_1(0) = d_\beta > d_t \) for \( t < 0 \). Therefore \( \cosh b_t < \cosh d_t + \cosh d_1(t) - 1 \), so \( (b_t, d_t, d_1(t)) \in \tilde{C}_3 \) by [3, Lemma 6.2] again. Thus \( T_0'(t) \) has its center \( v_1 \) in its interior.
By definition \( v_0 \) is equidistant from \( x_0, x_1 \) and \( x_2, x_1 \), and \( v_1 \) is equidistant from \( x_0, x_2 \), and \( x_3 \). The quadrilaterals \( Q_{x_0} \) and \( Q_{x_2} \) in \( T_0'(t) \) supplied by Lemma 2.6 contain \( v_0 \) in their intersection, so since \( v_0 \neq v_1 \) it is not contained in \( Q_{x_3} \). Lemma 2.6 thus implies that \( d(v_0, x_3) > d(v_0, x_0) \), and hence that \( v_0 = V_{x_0} \cap V_{x_1} \cap V_{x_2} \).

Since \( T_0(t) \) is isosceles, the geodesic arc \( \gamma \) from \( x_1 \) to \( v_0 \) intersects \( T_0(t) \cap T_0'(t) \) at a right angle. Since the geodesic arc \( \gamma' \) from \( v_1 \) to \( v_0 \) also meets \( T_0(t) \cap T_0'(t) \), their union is geodesic. It follows that \( d(x_1, v_1) = d(x_1, v_0) + d(v_0, v_1) \). On the other hand, \( d(x_2, v_1) \) satisfies

\[
\cosh d(x_2, v_1) = \cosh d(x_2, v_0) \cosh d(v_0, v_1) = \cosh d(x_1, v_0) \cosh d(v_0, v_1)
\]

by the hyperbolic law of cosines. The angle addition formula for hyperbolic cosine therefore implies that \( d(x_1, v_1) > d(x_2, v_1) \), so \( v_1 = V_{x_0} \cap V_{x_2} \cap V_{x_3} \), and it follows that \( V_{x_0} \cap V_{x_2} \) contains an edge joining \( v_0 \) to \( v_1 \). The lemma follows. \( \square \)

**Remark 2.14.** The construction of Example 2.12 may be modified, by increasing \( d_0 \) and reducing \( \delta \), to produce deformations of \( F_\beta \) in which an edge of the Delaunay tesselation does not intersect its geometric dual at all.

### 3. The centered dual to the Voronoi tesselation

Our task in this section is to understand the “pathology” described in Lemma 2.13, in which an edge of \( V \) does not intersect the interior of its geometric dual. We will say that such an edge of \( V \) is “non-centered,” and relate (non-)centeredness of edges to (non-)centeredness of vertex polygons in Lemma 3.3. The set of non-centered edges has restricted combinatorics: its components are sub-trees of \( P^{(1)} \), each with a canonical root vertex (Lemma 3.6). We organize the Delaunay polygons corresponding to vertices of such a component into a 2-cell of the “centered dual decomposition” \( P_c \), in Definition 3.18.

**Definition 3.1.** Let \( V \) be the Voronoi tessellation determined by \( S \subset \mathbb{H}^2 \) closed and discrete. We will say an edge \( e \) of \( V \) is centered if \( e \) intersects its geometric dual \( \gamma_{xy} \) at a point in \( \text{int } e \). If \( e \) is not centered, orient it pointing away from \( \gamma_{xy} \).

If \( V \) is the Voronoi tessellation of a closed surface \( F \) determined by a finite set \( S \), we say an edge \( e \) of \( V \) is centered if and only if one (and hence all) of its lifts to \( \tilde{V} \) is centered, where \( \tilde{V} = \pi^{-1}(V) \subset \mathbb{H}^2 \) is the Voronoi tessellation of \( \mathbb{H}^2 \) determined by \( \tilde{S} = \pi^{-1}(S) \). If \( e \) is not centered, let it inherit an orientation from a lift \( \tilde{e} \).

As indicated above, the action of \( \pi_1 F \) on \( \tilde{V}^{(1)} \) preserves (non-)centeredness of edges, and also the orientation of non-centered edges.

**Fact.** Let \( V \) be the Voronoi tessellation determined by \( S \subset \mathbb{H}^2 \) closed and discrete. For \( x \in S \), an edge \( e \) of \( V_x \) is non-centered with initial vertex \( v \) if and only if the angle \( \alpha \) at \( v \), measured in \( V_x \) between \( e \) and the geodesic segment joining \( v \) to \( x \), is at least \( \pi / 2 \).

This is because there is a right triangle with vertices at \( x \) and \( v \) and edges contained in \( \gamma_{xy} \) and \( \gamma_{xy}^{-1} \), where \( \gamma_{xy} \) is the geometric dual to \( e \); i.e., \( e = V_x \cap V_y \). This triangle has angle equal to either \( \alpha \) or \( \pi - \alpha \) at \( v \), depending on the case above; see Figure 3.1.
If \( w \) is the other endpoint of \( e \) then since \( x \in P_v \cap P_w \), the fact above and the hyperbolic law of cosines imply:

\[
\cosh J_w = \cosh \ell(e) \cosh J_v - \sinh \ell(e) \sinh J_v \cos \alpha
\]

Because \( \cos \alpha \leq 0 \) if \( \alpha \geq \pi/2 \), we have:

**Lemma 3.2.** Let \( V \) be the Voronoi tesselation determined by \( S \subset \mathbb{H}^2 \) closed and discrete. For \( x \in S \), if \( e \) is a non-centered edge of \( V_x \) oriented as prescribed in Definition 3.1, with initial vertex \( v \) and terminal vertex \( w \), then \( J_v < J_w \).

Below we relate centeredness of edges of \( V \) to that of 2-cells of the Delaunay tessellation.

**Lemma 3.3.** Let \( V \) be the Voronoi tesselation determined by \( S \subset \mathbb{H}^2 \) closed and discrete. For \( v \in V^{(0)} \), \( P_v \) is non-centered if and only if \( v \) is the initial vertex of a non-centered edge \( e \) of \( V \). If this is so, the geometric dual \( \gamma \) to \( e \) is the unique longest edge of \( P_v \), and \( P \cup T(e,v) \) is a convex polygon, where \( T(e,v) \) is the triangle determined by \( v \) and \( \partial \gamma \).

**Proof.** Suppose first that \( v \) is the initial vertex of a non-centered edge \( e = V_x \cap V_y \), and let \( \mathcal{H}' \) be the half-space containing \( e \) and bounded by the geodesic containing \( x \) and \( y \). The circle \( C \) with radius \( J_v \) and center \( v \) intersects \( \partial \mathcal{H}' \) in \( \{x,y\} \). If \( \alpha \) is the angle at \( v \) between \( e \) and the geodesic arc to \( x \), then by the Fact above, \( \alpha \geq \pi/2 \). The hyperbolic law of cosines implies that \( z \in C \) is in the interior of \( \mathcal{H}' \) if and only if the angle \( \alpha' \) at \( v \) between \( e \) and the geodesic arc to \( z \) is less than \( \alpha \). Thus if \( w \) is the other endpoint of \( e \) for such \( z \):

\[
\cosh d(z, w) = \cosh \ell(e) \cosh J_v - \sinh \ell(e) \sinh J_v \cos \alpha'
\]

Since \( \alpha' < \alpha \), comparing with (3.1.1) we find that \( d(z, w) < J_w \), so the intersection of \( C \) with the interior of \( \mathcal{H} \) is entirely contained in \( B_{J_w}(w) \). Therefore by Lemma 1.2 it contains no points of \( S \). Since all vertices of \( P_v \) are on \( C \), it follows that \( P_v \) is contained in the half-plane \( \mathcal{H} \) opposite \( \mathcal{H}' \), and hence that \( v \notin \text{int} P_v \). Thus \( P_v \) is non-centered by [3, Definition 1.1].

Assume now that \( P_v \) is not centered and apply [3, Lemma 1.5]. This produces an edge \( \gamma \) of \( P_v \) and a half-space \( \mathcal{H} \) containing \( P_v \) and bounded by the geodesic containing \( \gamma \), such that \( v \) is in the half-space \( \mathcal{H}' \) opposite \( \mathcal{H} \). [3, Lemma 1.5] further asserts that \( P \cup T(e,v) \) is a convex polygon; also, \( \gamma \) is the unique longest edge of \( P_v \), by [3, Corollary 1.11]. We claim that the other endpoint \( w \) of the geometric dual \( e \) to \( \gamma \) is further from \( \mathcal{H} \) than \( v \), and hence that \( e \) is non-centered with initial vertex \( v \).
Each component of $T$.

Proof. Suppose that a component $F$ of $\gamma = e_0 \cup e_1 \cup \ldots \cup e_{n-1}$ is an edge path if $e_i$ is an edge of $G$ for each $i$ and $e_i \cap e_{i-1} \neq \emptyset$ for $i > 0$. An edge path $\gamma$ as above is reduced if $e_i \neq e_{i-1}$ for each $i > 0$, and $\gamma$ is closed if $e_0 \cap e_{n-1} \neq \emptyset$.

Lemma 3.6. Let $V$ be the Voronoi tessellation determined by $S \subset \mathbb{H}^2$ closed and discrete. No $v \in V^{(0)}$ is the initial vertex of more than one non-centered edge.

Let $V_{n(1)}$ be the union of the non-centered edges. If $F$ is a closed surface, we define $V_{n(1)}$ in the same way for the Voronoi tessellation $V$ determined by $S \subset F$ finite.

Below, given a graph $G$ we will say that $\gamma = e_0 \cup e_1 \cup \ldots \cup e_{n-1}$ is an edge path if $e_i$ is an edge of $G$ for each $i$ and $e_i \cap e_{i-1} \neq \emptyset$ for $i > 0$. An edge path $\gamma$ as above is reduced if $e_i \neq e_{i-1}$ for each $i > 0$, and $\gamma$ is closed if $e_0 \cap e_{n-1} \neq \emptyset$.

Corollary 3.4. Let $V$ be the Voronoi tessellation determined by $S \subset \mathbb{H}^2$ closed and discrete. No $v \in V^{(0)}$ is the initial vertex of more than one non-centered edge.

Definition 3.5. If $V$ is the Voronoi tessellation determined by $S \subset \mathbb{H}^2$ closed and discrete, let $V_{n(1)} \subset V^{(1)}$ be the union of the non-centered edges. If $F$ is a closed surface, we define $V_{n(1)}$ in the same way for the Voronoi tessellation $V$ determined by $S \subset F$ finite.

Lemma 3.6. Let $\tilde{V}$ be the Voronoi tessellation determined by $\tilde{S} \subset \mathbb{H}^2$ closed and discrete. Each component $T$ of $\tilde{V}_{n(1)}$ is a tree. If $\tilde{S} = \pi^{-1}(S)$, where $\pi : \mathbb{H}^2 \to F$ is the universal cover to a closed surface $F$, and $S \subset F$ is finite, then $T$ is finite, with a unique vertex $v_T$ such that $J_{v_T} > J_v$ for all $v \in T^{(0)} - \{v_T\}$, and $T$ projects homeomorphically to $F$.

Proof. Suppose that a component $T$ of $\tilde{V}_{n(1)}$ admits closed, reduced edge paths, and let $\gamma = e_0 \cup e_1 \cup \ldots \cup e_{n-1}$ be a shortest such. Orienting the $e_i$ as in Definition 3.1, we may assume (after re-numbering if necessary) that $e_0$ points toward $e_0 \cap e_{n-1}$. We claim that then $e_i$ points to $e_i \cap e_{i-1}$ for each $i > 0$ as well. Otherwise, for the minimal $i > 0$ such that $e_i$ points toward $e_{i+1}$ it would follow that the vertex $e_i \cap e_{i-1}$ was the initial vertex of both $e_i$ and $e_{i-1}$, contradicting Corollary 3.4.

Let $v_0 = e_0 \cap e_{n-1} \in V^{(0)}$, and for $i > 1$ take $v_i = e_i \cap e_{i-1}$. Applying Lemma 3.2 to $e_i$ for each $i$, we find that $J_{v_i} > J_{v_{i+1}}$. By induction this gives $J_{v_0} > J_{v_{n-1}}$; but since $e_{n-1}$ points to $v_{n-1}$ Lemma 3.2 implies that $J_{v_{n-1}}$ must exceed $J_{v_0}$, a contradiction. Thus no component of $\tilde{V}_{n(1)}$ admits closed, reduced edge paths, so each is a tree.

If $\tilde{S} = \pi^{-1}(S)$ as in the hypotheses then the set $\{J_v : v \in T^{(0)}\}$ has only finitely many distinct elements, since $J_v = J_v'$ if $v$ and $v'$ project to the same point of $S$. Thus take $v_T \in T^{(0)}$ with $J_{v_T}$ maximal. We claim that $J_T < J_{v_T}$ for each $v \in T^{(0)} - \{v_T\}$.

If there exists $v \in T^{(0)} - \{v_T\}$ with $J_v = J_{v_T}$, let $\gamma = e_0 \cup \ldots \cup e_{n-1}$ be a reduced edge path joining $v_T$ to $v$. We may assume that $v_T$ is the endpoint of $e_0$ not in $e_1$, and $v \in e_{n-1} - e_{n-2}$. Lemma 3.2 implies that $e_0$ points toward $v_T$ and $e_{n-1}$ towards $v$. Thus if $i > 0$ is minimal such that $e_i$ does not point toward $e_{i-1}$, $v_i = e_i \cap e_{i-1}$ is the initial endpoint of $e_i$ and $e_{i-1}$, contradicting Corollary 3.4. This proves the claim.
Lemma 3.7. Let \( T \) be a component of \( V_n^{(1)} \). For \( v_T \in T(0) \) as in Lemma 3.6, \( P_{v_T} \) is centered. For \( v \in T(0) \setminus \{v_T\} \), \( P_v \) is not centered, and the reduced edge path joining \( v \) to \( v_T \) inherits an orientation from each of its constituent edges, pointing from \( v \) to \( v_T \).

**Proof.** Since \( v_T \) has maximal radius among \( v \in T(0) \), Lemma 3.2 implies that it is the terminal endpoint of each edge of \( T \) containing it. Since every other edge of \( V \) containing \( v_T \) is centered, Lemma 3.3 implies that \( P_{v_T} \) is centered.

For \( v \in T(0) \setminus \{v_T\} \), let \( e_0 \cup \ldots \cup e_{n-1} \) be the reduced edge path joining \( v \) to \( v_T \), take \( e_i = e_i \cap e_{i-1} \) for \( 1 \leq i \leq n-1 \), and let \( v_0 \) and \( v_n \) be the endpoints of \( e_0 \) and \( e_{n-1} \) not equal to \( v_1 \) and \( v_{n-1} \), respectively. Re-numbering if necessary, we may assume that \( v_0 = v \) and \( v_n = v_T \). Then \( e_{n-1} \) has terminal endpoint \( v_n \). If \( e_i \) does not point toward \( v_{i+1} \) for some \( i < n-1 \) then for the maximal such \( i \), \( v_i \) is the initial vertex of \( e_i \) and \( e_{i+1} \), contradicting Corollary 3.4. The \( e_i \) thus agree with the orientation on the edge path that points toward \( v_T \). In particular, \( v \) is the initial vertex of \( e_0 \), so \( P_v \) is not centered by Lemma 3.3. \( \square \)

**Definition 3.8.** Let \( V \) be the Voronoi tessellation of a closed hyperbolic surface \( F \) determined by \( S \subset F \) finite. Define the centered dual graph \( P_c^{(1)} \) to \( V^{(1)} \) as:

\[
P_c^{(1)} = \bigcup \{ \gamma_{xy} \mid \gamma_{xy} \text{ is the geometric dual to a centered edge } e \subset V^{(1)} \} \subset P^{(1)}
\]

Let \( \tilde{P}_c^{(1)} \subset \tilde{V}^{(1)} \) be the preimage of \( P_c^{(1)} \) in the universal cover.

It is easy to see that \( \tilde{P}_c^{(1)} \) is the union of geometric duals to centered edges of \( \tilde{V} \) (cf. Definition 3.1). The centered dual graph has the structure of a subgraph of the one-skeleton \( P^{(1)} \) of the Delaunay tessellation. It exhibits the behavior that one expects from a dual:

**Lemma 3.9.** Let \( V \) be the Voronoi tessellation of a closed hyperbolic surface \( F \) determined by a finite set \( S \subset F \). If \( e \) is a centered edge of \( V \) and \( \gamma \subset P_c^{(1)} \) its geometric dual, then \( \gamma \cap V^{(1)} = \gamma \cap e \) is a single point. Furthermore, \( e \cap P_c^{(1)} = e \cap \gamma \).

**Proof.** Let \( \tilde{e} \) be a lift of \( e \) to \( \mathbb{H}^2 \), and let \( x \) and \( y \in \tilde{S} \) be such that \( \tilde{e} = V_x \cap V_y \). Then the geodesic arc \( \gamma_{xy} \) joining \( x \) to \( y \) projects to \( \gamma \). Let \( p = e \cap \gamma_{xy} \), and let \([x, p] \) and \([y, p] \) be the sub-arcs of \( \gamma_{xy} \) joining \( x \) and \( y \), respectively, to \( p \). Since \( V_x \) is convex with \( x \) in its interior, it contains \([x, p] \), and \([x, p] \cap \partial V_x = \{p\} \). The analogous assertion holds for \( V_y \) and \([y, p] \), and so \( \gamma_{xy} \cap \tilde{V}^{(1)} = \{p\} \). Since this holds for any lift of \( e \), the first claim follows.
The second claim follows from the first, since the set of centered edges of $V^{(1)}$ is in bijective correspondence with the edge set of $P_c^{(1)}$ by associating a centered edge to its dual. $\square$

Figure 3.1 shows that the conclusion of Lemma 3.9 does not hold for non-centered edges.

Lemma 3.6 implies that each cell $V_x$ of $V$ has at least one centered edge $e$, for otherwise some component of $V_n^{(1)}$ would contain the closed loop $\partial V_x$. Since the geometric dual of such an edge $e$ is of the form $\gamma_{xy}$, it follows that the vertex set of $P_c^{(1)}$ is all of $S$.

The interior of each Voronoi cell $V_x$ is isometric to the interior of a compact, convex polygon in $\mathbb{H}^2$. Therefore there is a “geometric” deformation retract $V_x - \{x\} \to \partial V_x \subset V^{(1)}$ along geodesic arcs connecting $x$ to points on $\partial V_x$. Since $P_c^{(1)}$ intersects each $V_x$ in a collection of such arcs, we have:

**Lemma 3.10.** Let $V$ be the Voronoi tessellation of a closed hyperbolic surface $F$ determined by $S \subset F$ finite, and let $P_c^{(1)}$ be the centered dual graph to $V^{(1)}$. There is a deformation retract $\rho_S : F - P_c^{(1)} \to V^{(1)} - (V^{(1)} \cap P_c^{(1)})$ such that for each $x \in S$, $\rho_S$ restricts on $V_x - P_c^{(1)}$ to the restriction of the corresponding geometric deformation retract.

Since $\rho_S$ is a deformation retract, it determines a one-to-one correspondence between the set of components of $F - P_c^{(1)}$ and the set of components of $V^{(1)} - (V^{(1)} \cap \Gamma)$. We use this to give an initial description of the components of $F - \Gamma$. It will be convenient to first introduce another definition.

**Definition 3.11.** If $V$ is a graph and $T$ a subgraph, we define the *frontier* $F$ of $T$ in $V$ to be the set of pairs $(e, v)$ where $e$ is an edge of $V$ that is not in $T$ and $v \in e \cap T$.

We may refer just to “an edge” of the frontier of $T$, without reference to its vertices, but note that $F$ has two elements for each $e$ not in $T$ with both endpoints in $T$.

**Lemma 3.12.** Let $V$ be the Voronoi tessellation of a closed hyperbolic surface $F$ determined by $S \subset F$ finite, and let $P_c^{(1)}$ be the centered dual graph to $V^{(1)}$. Each component $U$ of $F - P_c^{(1)}$ is homeomorphic to an open disk, and either:

1. there is a unique $v \in V^{(0)} \cap U$, each edge of $V$ containing $v$ is centered, and the universal cover maps $P_{\tilde{v}}$ to $\overline{U}$ for (any) $\tilde{v} \in \pi^{-1}(V)$; or
2. $U$ contains a unique component $T$ of $V_n^{(1)}$, and $V^{(0)} \cap U = T^{(0)}$.

**Proof.** Suppose for $v \in V^{(0)} \cap U$ that every edge of $V$ containing $v$ is centered. The same holds for $\tilde{v} \in \pi^{-1}(v)$, so Lemma 3.3 implies that the vertex polygon $P_{\tilde{v}}$ is centered, and hence that $\tilde{v} \in \text{int } P_{\tilde{v}}$. By Lemma 1.9, each edge of $P_{\tilde{v}}$ is the geometric dual to an edge containing $\tilde{v}$. Thus $\partial P_{\tilde{v}} \subset \overline{P_c^{(1)}}$, so $\text{int } P_{\tilde{v}}$ is a component of $\mathbb{H}^2 - \overline{P_c^{(1)}}$ containing $\tilde{v}$. Since $\pi$ maps $\partial P_{\tilde{v}}$ into $P_c^{(1)}$ and $\text{int } P_{\tilde{v}}$ homeomorphically, $U = \pi(\text{int } P_{\tilde{v}})$.

In particular, since $\text{int } P_{\tilde{v}}$ is homeomorphic to an open disk, the same holds for $U$. Let the edges of $\overline{V}$ containing $\tilde{v}$ by cyclically ordered $e_0, \ldots, e_{n-1}$ as in Lemma 1.9, with geometric dual $\gamma_i$ for each $i$, and let $m_i = e_i \cap \gamma_i \in \text{int } e_i$. For each the quadrilateral $Q_{2i}$ constructed
in Lemma 2.6 is contained in \( V_{i_1} \), since its vertices are (cf. Definition 1.5), so the conclusion there implies that \( P_c \subset \bigcup_{i=0}^{n-1} Q_{x_i} \subset \bigcup_{i=0}^{n-1} V_{x_i} \). Since \( Q_{x_i} \cap \partial V_{x_i} = (e_i \cap P_c) \cup (e_{i+1} \cap P_c) \) it follows that \( v = V^{(0)} \cap U \).

If \( v \in V^{(0)} \cap U \) is a vertex of a non-centered edge, then \( U \) contains the entire component \( T \) of \( V^{(1)}_n \) containing \( v \), since \( T \) does not intersect \( P^{(1)}_c \). Let \( \tilde{T} \) be a lift of \( T \) to the universal cover. For each \((e,v)\) in the frontier \( \mathcal{F} \) of \( \tilde{T} \), \( e \) is centered, so its geometric dual \( \gamma \) intersects it and lies in \( \tilde{P}^{(1)}_c \). For \( v \in e \cap \tilde{T} \), let \([v,e \cap \gamma]\) refer to the component of \( e - \gamma \) containing \( v \). Then

\[
S_T = T \cup \left( \bigcup \{ [v, e \cap \gamma] | (e, v) \in \mathcal{F} \} \right)
\]

is a connected open subset of \( \tilde{V}^{(1)} - \tilde{P}^{(1)}_c \) with frontier in \( \tilde{P}^{(1)}_c \), and hence is a component of \( \tilde{V}^{(1)} - \tilde{P}^{(1)}_c \). Again we find that by construction, \( S_T \) deformation retracts to \( \tilde{T} \) (thus in particular is simply connected) and that \( S_T \cap \tilde{V}^{(0)} = \tilde{T}^{(0)} \). Therefore \( S_T \) projects homeomorphically to the component \( S_T \) of \( V^{(1)} - P^{(1)}_c \) containing \( T \).

Since \( S_T \) is a component of \( V^{(1)} - P^{(1)}_c \) contained in \( U \), and \( U \) is a component of \( F - P^{(1)}_c \), \( U = \rho^{-1}_S(S_T) \); in particular, \( T^{(0)} = S_T \cap V^{(0)} = U \cap V^{(0)} \). Since \( \rho_S \) is a deformation retract, \( U \) is simply connected and hence lifts homeomorphically to the component \( \tilde{U} \) of \( \mathbb{H}^2 - \tilde{P}^{(1)}_c \) containing \( S_T \). This is homeomorphic to a disk by, say, the Riemann mapping theorem, and therefore so is \( U \).

To better understand the structure of complementary components to \( P^{(1)}_c \) that contain points of \( V^{(1)}_n \), we introduce a new tool.

**Definition 3.13.** Let \( V \) be the Voronoi tessellation of \( \mathbb{H}^2 \) determined by \( \mathcal{S} \subset \mathcal{F} \) closed and discrete. For \( v \in V^{(0)} \), an edge \( e \) of \( V \) containing \( v \), and \( x, y \in \mathcal{S} \) such that \( e = V_x \cap V_y \), let \( T(e, v) \) be the isosceles triangle with vertices \( v, x \) and \( y \).

If \( V \) is the Voronoi tessellation of a closed hyperbolic surface \( F \) determined by \( \mathcal{S} \subset \mathcal{F} \) finite, let \( T(e, v) = \pi(T(e, \tilde{v})) \), where \( \tilde{v} \in \pi^{-1}(v) \).

The edges of \( T(e, v) \) that join \( v \) to \( x \) and \( y \), respectively, each have length \( J_e \), and the third edge of \( (e, v) \) is the geometric dual \( \gamma_{xy} \) to \( e \). If \( v \) and \( w \) are opposite endpoints of \( e \), then \( T(e, v) \) and \( T(e, w) \) share the edge \( \gamma_{xy} \). Whether their intersection is larger than this depends on whether \( e \) is centered — see Figure 3.2. In particular:

**Lemma 3.14.** Let \( V \) be the Voronoi tessellation determined by \( \mathcal{S} \subset \mathbb{H}^2 \) closed and discrete. If \( e \) is a non-centered edge of \( V \) with initial vertex \( v \) and terminal vertex \( w \), then \( T(e, v) \subset T(e, w) \) and \( T(e, v) \cap \partial T(e, w) \) is the geometric dual of \( e \).

**Proof.** Since \( e \) is non-centered it is contained on one side of the geodesic in \( \mathbb{H}^2 \) containing its geometric dual \( \gamma \), so the nearer vertex \( v \) on \( e \) to \( \gamma \) is in the interior of \( T(e, w) \). The result now follows from convexity.

**Lemma 3.15.** Let \( V \) be the Voronoi tessellation determined by \( \mathcal{S} \subset \mathbb{H}^2 \) closed and discrete. For \( v \in V^{(0)} \):
of a neighborhood of $U$ that is centered, the desired conclusion is proved there, so we will assume an analogous argument gives the analogous result for $T$.

Let $\gamma$ and $\gamma'$ be the respective geometric duals to $e$ and $e' \neq e$ containing $v$. In case (1), $T(e,v) \cap T(e',v) = \{v\}$ if $\gamma \cap \gamma' = \emptyset$, and otherwise is an edge joining $v$ to $\gamma \cap \gamma'$. This holds in case (2) for $e,e' \neq e_v$.

**Proof.** If the edges of $P_v$ are enumerated $\gamma_0, \ldots, \gamma_i$, for each $i$ the triangle $T_i$ described in the hypothesis of [3, Lemma 1.6] is identical to $T(e_i,v)$, where $e_i$ is the geometric dual to $\gamma_i$. If $P_v$ is non-centered then Lemma 3.3 implies that $\gamma_v$ as defined above is its unique longest edge, so [3, Corollary 1.11] and [3, Lemma 1.5] imply that $T(e_v,v) \cap P_v = \gamma_v$. The decompositions of $P_v$ and $P_v \cup T(e,v)$ described above follow directly from [3, Lemma 1.6].

**Proposition 3.16.** Let $V$ be the Voronoi decomposition of a closed hyperbolic surface $F$ determined by $S \subset F$ finite, and let $P^{(1)}_c$ be the centered dual graph to $V^{(1)}$. For each component $U$ of $F - P^{(1)}_c$, $U = \bigcup_{e \in \mathcal{Q} \cap \mathcal{V}^{(0)}} P_v$.

**Proof.** In case (1) of Lemma 3.12, the desired conclusion is proved there, so we will assume that $U$ contains a component $T$ of $V^{(1)}_n$. Let $\widetilde{T}$ be a lift of $T$ to $\mathbb{H}^2$, let $\widetilde{U}$ be the component of $\mathbb{H}^2 - \partial \widetilde{T}$ containing $\widetilde{T}$, and let $\widetilde{Q}$ be the closure of $\widetilde{U}$ in $\mathbb{H}^2$. Let $\mathcal{F}$ be the frontier of $\widetilde{T}$ in $\mathcal{V}^{(1)}$. For $(e,v) \in \mathcal{F}$, we claim that $T(e,v)$ is contained in $\widetilde{Q}$.

Let $x$ and $y \in \widetilde{S}$ be such that $e = V_x \cap V_y$. Then the side of $T(e,v)$ opposite $v$ is $\gamma_{xy} \subset \widetilde{P}_c^{(1)}$, since $e$ is centered, and $T(e,v)$ is equal to the union of its intersections with $V_x$ and $V_y$. Let $[v,\gamma_{xy}]$ be the sub-arc of $e$ running from $v$ to $e \cap \gamma_{xy}$. Lemma 3.9 implies that $[v,\gamma_{xy}] \cap \widetilde{P}_c^{(1)} = \{e \cap \gamma_{xy}\}$, so since $v \in \widetilde{T} \subset \widetilde{U}$ it follows that $[v,\gamma_{xy}] \subset \widetilde{Q}$.

$T(e,v) \cap V_x$ is the union of geodesic arcs in $V_x$ joining $x$ to points on $[v,\gamma_{xy}]$. Since $\widetilde{P}_c^{(1)} \cap V_x$ is a union of geodesic arcs joining $x$ to points of $\widetilde{P}_c^{(1)} \cap \partial V_x$, and the only such point in $[v,\gamma_{xy}]$ is $e \cap \gamma_{xy}$, it follows that $T(e,v) \cap V_x$ intersects $\widetilde{P}_c^{(1)}$ only in $\gamma_{xy} \cap V_x$. Since $\widetilde{U}$ contains a neighborhood of $v$ and has its frontier in $\widetilde{P}_c^{(1)}$, this implies that $T(e,v) \cap V_x \subset \widetilde{Q}$. The analogous argument gives the analogous result for $T(e,v) \cap V_y$, and the claim is proved.
Lemma 3.15 implies that the interior of $P_v$ intersects that of $T(e,v)$, so the claim above implies that the interior of $P_v$ intersects $\tilde{U}$. By Lemma 1.9, the interior of $P_v$ is a component of $\mathbb{H}^2 - \tilde{P}(1)$. Therefore since $\tilde{P}_c(1) \subset \tilde{P}(1)$, $int P_v \subset \tilde{U}$, and hence $P_v \subset \tilde{Q}$.

If $v$ and $w$ are adjacent in $\tilde{T}$, then the corresponding vertex polygons $P_v$ and $P_w$ share an edge $e$ of $\tilde{P}$, the geometric dual to the edge of $T$ joining $v$ to $w$. Since this edge is non-centered, $\gamma$ intersects $\tilde{P}_c(1)$ only at its endpoints. Since $\text{int } P_v$ and $\text{int } P_w$ are each components of $\mathbb{H}^2 - \tilde{P}_c(1)$, it follows that $P_v \subset \tilde{Q}$ if and only if $P_w \subset \tilde{Q}$.

We have already proved that $P_v \subset \tilde{Q}$ for any $v \in \tilde{T}(0)$ such that $(e,v) \in \mathcal{F}$ for some edge $e$, so since $\tilde{T}$ is connected, the previous paragraph and an inductive argument show that $\bigcup_{v \in \tilde{T}(0)} P_v \subset \tilde{Q}$. Projecting to $F$ it follows that $\bigcup_{v \in T(0)} P_v \subset \tilde{U}$.

It remains to show that $\bigcup_{v \in T(0)} P_v$ is not properly contained in $\tilde{U}$. If it were, then there would exist $v' \notin T(0)$ such that $P_{v'} \subset \tilde{U}$. But then Lemma 3.12 implies that $v'$ is contained in a different component $U'$ of $F - \tilde{P}_c(1)$, so by the above $P_{v'} \subset \tilde{U}'$. But since $P_{v'}$ has non-empty interior, this is a contradiction. 

\textbf{Corollary 3.17.} Let $V$ be the Voronoi decomposition of a closed hyperbolic surface $F$ determined by $S \subset F$ finite, and let $P_c(1)$ be the centered dual graph to $V(1)$. For each component $U$ of $F - P_c(1)$, the completion $\tilde{Q}$ of the induced path metric on $U$ is homeomorphic to a closed disk. If $U$ contains a component $T$ of $V_n(1)$ with frontier $\mathcal{F}$ in $V(1)$, then:

$$\tilde{Q} - U = \bigcup \{ \gamma(e,v) \mid (e,v) \in \mathcal{F} \},$$

where $\gamma(e,v)$ is isometric to the geometric dual to $e$ for each $(e,v) \in \mathcal{F}$.

A brief proof sketch: $\tilde{Q}$ is homeomorphic to the complement in $U$ of a small neighborhood of its frontier, itself a closed disk. If $e$ is an edge of $V$ that is not in $T$ but has both endpoints in it, then its geometric dual $\gamma$ contributes two edges to $\tilde{Q}$ — one for each side — but only one to the closure $Q$ of $U$. This is why we use the induced path metric. It holds even in $\mathbb{H}^2$: a lift of $U$ to $\tilde{U} \subset \mathbb{H}^2 - \tilde{P}_c(1)$ determines a map from $\tilde{Q}$ to the closure $\tilde{Q}$ of $\tilde{U}$ that is two-to-one over each edge of $\tilde{P}_c(1)$ geometrically dual to a lift of $e$ as above, and injective elsewhere.

\textbf{Definition 3.18.} Let $V$ be the Voronoi tessellation of a closed hyperbolic surface $F$ determined by $S \subset F$ finite. Define the \textit{centered dual decomposition} $P_c$ of $F$ to be the cell complex with $P_c(0) = S$, $P_c(1)$ as described in Definition 3.8, and 2-cells as in Corollary 3.17.

If $U$ is a component of $F - P_c(1)$ containing a component $T$ of $V_n(1)$, we will refer to its closure $Q$ as a 2-cell of $P_c$ with \textit{vertex set} $Q \cap S = \bigcup_{v \in T(0)} P_v \cap T(0)$, and \textit{edge set} $Q - U = \bigcup_{v \in \mathcal{F}} \{ \gamma \text{ geometrically dual to } e \}$, where $\mathcal{F}$ is the frontier of $T$ in $V(1)$ and “$e \in \mathcal{F}$” means that $e$ has an endpoint $v$ such that $(e,v) \in \mathcal{F}$.

\section{The Centered Dual Versus a Disk Packing}

We show in this section that the centered dual decomposition determined by $S$ interacts well with a set of disjoint open hyperbolic disks of equal radius isometrically embedded about the points of $S$. Recall from the beginning of [3, §5] that a polygon $P$ determines a sector
of a disk $U$ centered at one of its vertices $x$, with angle measure equal to $\angle_x P$, and that this sector contains $P \cap U$. Figure 4.1 illustrates an instance in which containment is proper, with the “bad” region shaded.

The radius-$R$ defect $D_R(d_0, \ldots, d_{n-1})$, as defined in [3, Definition 5.1], describes the area of the region of a cyclic $n$-gon $P$ represented by $(d_0, \ldots, d_{n-1}) \in \tilde{AC}_n$ outside the union of a collection of disjoint radius-$R$ disks centered at its vertices, if each disk intersects $P$ in a full sector. If $P$ is centered then by [3, Lemma 5.3], the full sectors hypothesis holds, and by [3, Lemma 5.4] the area in question is $D_R(P)$. For non-centered cyclic polygons the pathology of Figure 4.1 may occur, but we show here that it does not for centered dual 2-cells.

**Definition 4.1.** For $\mathcal{S} \subset F$ finite, where $F$ is a closed hyperbolic surface, define the injectivity radius $i(\mathcal{S})$ of $F$ at $\mathcal{S}$ to be the injectivity radius of the preimage $\tilde{\mathcal{S}} \subset \mathbb{H}^2$, as defined above Lemma 1.1, of $\mathcal{S}$ under the universal cover $\mathbb{H}^2 \to F$.

It is easy to see that $i(\mathcal{S})$ is the maximal $R$ such that a collection of open, radius-$R$ hyperbolic disks may be isometrically embedded in $F$ without overlapping, centered at the points of $\mathcal{S}$. In particular, if $\mathcal{S} = \{x\}$ is a singleton, then $i(\mathcal{S})$ is the usual injectivity radius of $F$ at $x$.

**Proposition 4.2.** Let $V$ be the Voronoi tessellation and $P_c$ the centered dual decomposition determined by $\mathcal{S} \subset F$ finite, where $F$ is a closed hyperbolic surface. If $\{U_x\}$ is a set of open hyperbolic disks of radius $R \leq i(\mathcal{S})$ centered at the points of $\mathcal{S}$, then for a 2-cell $Q$ of $P_c$:

$$\text{area}\left(Q - \bigcup_{x \in \mathcal{S}} (U_x \cap Q)\right) = D_R(Q) \doteq \sum_{v \in Q \cap V^{(0)}} D_R(d_v),$$

where $d_v$ represents $P_v$ in $\tilde{AC}_{n_v}$ for each $v$ (with $n_v$ the valence of $v$ in $V^{(1)}$).

As we remarked above, this does not necessarily hold for Delaunay 2-cells that are non-centered; however, for those that are it follows directly from [3, Lemma 5.4]. Lemma 3.12 implies that each 2-cell of $P_c$ is either a centered Delaunay polygon or contains a component $T$ of $V^{(1)}_n$, so it is this latter case that we will address in the remainder of the section.

A centered dual 2-cell is by definition equal to the union of vertex polygons $P_v$ for $v \in Q \cap V^{(0)}$. It will be convenient for our purposes to re-tile $Q$ by a new set of “polygons.”
Definition 4.3. Let $\bar{V}$ be the Voronoi tessellation determined by $\bar{S} \subset \mathbb{H}^2$ closed and discrete, and let $T$ be a component of $\bar{V}_n(1)$. For $v \in T(0) - \{v_T\}$, let $e_v$ be the edge of $T$ with initial vertex $v$. For $v \in T(0)$, define $v + 1$ to be the set of $w \in T(0)$ such that $v$ is the terminal vertex of $e_w$ (oriented as in Definition 3.1).

Define $P'_v = P_v - \left( \bigcup_{w \in v+1} T(e_w, w) \right)$, where $T(e_w, w)$ is as in Definition 3.13, and if $v \neq v_T$ let $P_v = (P_v \cup T(e_v, v)) - \left( \bigcup_{w \in v+1} T(e_w, w) \right)$ (here the overline denotes the closure in $\mathbb{H}^2$).

Although $P'_v$ is not necessarily convex, its angle at a vertex $x$ of $P_v$ is clearly at most that of $P_v \cup T(e_v, v)$, since $P_v \cup T(e_v, v)$ is convex (cf. Lemma 3.3) it makes sense to talk about “the sector determined by $P'_v$” of a disk $U$ centered at $x$. The key advantage of the $P'_v$ is that they behave well with respect to such disks.

Lemma 4.4. Let $V$ be the Voronoi tessellation and $P_c$ the centered dual decomposition determined by $\bar{S} = \pi^{-1}(S)$, where $\pi: \mathbb{H}^2 \to F$ is the universal cover of a closed hyperbolic surface and $\bar{S} \subset F$ is finite. Fix a component $T$ of $V_n(1)$, $v \in T(0)$, and $R \leq i(S)$. A disk $U_x$ of radius $R$ centered at a vertex $x$ of $P$ intersects $P'_v$ in the sector determined by $P'_v$. For $w \in v + 1$, $U_x \cap T(e_w, w) \neq \emptyset$ if and only if $x$ is in the geometric dual $\gamma_w$ to $e_w$.

Let us recall that for $v$ as above and $w \in v + 1$, $T(e_w, w) \subset T(e_w, v)$ and $T(e_w, v) \cap \partial T(e_w, v)$ is the edge $\gamma_w$ geometrically dual to $e_w$, by Lemma 3.14. Thus Lemma 3.15 implies that $T(e_w, v)$ is entirely contained in $P_v \cup T(e_v, v)$, for $v \neq v_T$, or in $P_v$ if $v = v_T$; and furthermore that $T(e_w, v) \cap \partial (P_v \cup T(e_v, v)) = \gamma_w$ (or that $T(e_w, v) \cap \partial P_v = \gamma_w$ if $v = v_T$).

Proof. For now take $v = v_T$. Lemma 3.15 implies that a vertex $x$ of $P$ is contained in $T(e, v)$, for some edge $e$ containing $v$, if and only if $x$ is an endpoint of the edge $\gamma$ of $P_v$ that is geometrically dual to $e$. Thus a small-enough disk $U$ around $x$ has the property that $U \cap P_v = (U \cap T(e, v)) \cup (U \cap T(e', v))$, where $e$ and $e'$ are the edges containing $v$ with geometric duals $\gamma$ and $\gamma'$ meeting at $x$ (this also uses Lemma 3.15).

For $U_x$ as described above, [3, Lemma 5.2] implies that $U_x \cap T(e, v)$ is the sector determined by $T(e, v)$, and likewise for $T(e', v)$. Since $U_x \cap P_v$ is contained in the sector determined by $P_v$, and this is the union of those determined by $T(e, v)$ and $T(e', v)$ by the above, it follows that $U_x \cap P_v = (U_x \cap T(e, v)) \cup (U_x \cap T(e', v))$. For $w \in v + 1$ such that $e_w \neq e, e'$, since $T(e_w, w) \subset T(e_w, v)$ it follows that $T(e_w, v) \cap U_x = \emptyset$. On the other hand, if $e_w = e$ (say), then $\gamma_w = \gamma$ and $U_x$ clearly intersects $T(e_w, v)$ in the sector that it determines (by [3, Lemma 5.2] again). The final assertion of the lemma follows.

Since $v = v_T$, the definition of $P'_v$ implies that $U_x \cap P'_v = (U_x \cap P_v) - \left( \bigcup_{w \in v+1} (U_x \cap T(e_w, w)) \right)$. By the above, $U_x \cap P_v$ is a sector, and for each $w \in v + 1$, $U_x \cap T(e_w, w)$ is empty unless $x \in \gamma_w$, in which case it is a sector containing the boundary edge $U_x \cap \gamma_w$ of $U_x \cap P_v$. It thus easily follows from the description above that $U_x \cap P'_v$ is also a sector.

We have proved the lemma for $v = v_T$. The proof for $v \in T(0) - \{v_T\}$ is similar, but with two important differences. First, $P_v$ should be replaced above by $P_v \cup T(e_v, v)$, and second, the case of $x \in \partial \gamma_v$ must be treated separately. For such $x$ it turns out that
Proof. For each $v \in T^{(0)}$ and $w \in v + 1$, $P'_v \cap T(e_w, w)$ is the union of edges of $T(e_w, w)$ containing $w$. For $v \in T^{(0)} - \{v_T\}$, if $\gamma_v$ is the geometric dual to $e_v$ then:

$$int P'_v = \left( int P_v \cup int T(e_v, v) \cup int \gamma_v \right) - \left( \bigcup_{w \in v + 1} T(e_w, w) \right)$$

Similarly, $int P'_{vt} = int P_{vt} - \left( \bigcup_{w \in v + 1} T(e_w, w) \right)$.

Lemma 4.5. Let $V$ be the Voronoi tesselation and $P_c$ the centered dual decomposition determined by $\tilde{S} = \pi^{-1}(S)$, where $\pi: \mathbb{H}^2 \to F$ is the universal cover of a closed hyperbolic surface and $S \subset F$ is finite. If $Q$ is a 2-cell of $P_c$ containing a component $T$ of $V_n^{(1)}$ then $Q = \bigcup_{v \in T^{(0)}} P'_v$, for $P'_v$ as in Definition 4.3. For distinct $v$ and $w$ in $T^{(0)}$, $int P'_v \cap P'_w = \emptyset$.

Proof. For $x \in Q$ let $v_0$ be such that $x \in P_{v_0}$. If $x \notin T(e_v, v)$ for any $v \in v_0 + 1$, then $x \in P'_{v_0}$. If there exists $v_1 \in v_0 + 1$ such that $x \in T(e_v, v_1)$, we choose $v \in T^{(0)}$ to satisfy three criteria: $x \in T(e_v, v)$, the reduced edge path from $v_0$ to $v$ contains $v_1$, and this edge path is longest among all of those joining $v_0$ to vertices satisfying the first two criteria. Since $v_1$ satisfies the first two criteria there is some such $v$, and by construction $x \in T(e_v, v)$ but not in $T(e_w, w)$ for any $w \in v + 1$ (the reduced edge path from $v_0$ to such a $w$ is the union of the reduced edge path to $v$ with $e_w$). Therefore $x \in P'_{v_0}$.

Our goal in the remainder is to prove that $int P'_v \cap P'_w = \emptyset$ for distinct $v$ and $w$ in $T^{(0)}$. For $v \in T^{(0)} - \{v_T\}$, let $e_0 \cup \ldots \cup e_{n-1}$ be the reduced edge path in $T$ joining $v_T$ to $v$, numbered so that $v_T$ is a vertex of $e_0$ and $v$ is a vertex of $e_{n-1}$. Upon orienting this path and its edges as described in Lemma 3.7, $v_T$ is the terminal vertex of $e_0$ and $v$ the initial vertex of $e_{n-1}$. For $0 \leq i \leq n - 1$ let $v_i$ be the terminal vertex of $e_i$, so in particular $v_T = v_0$, and let $v_n = v$. Then $v_i$ is the initial vertex of $e_{i-1}$ for $i > 0$, so for each $i < n$, $e_i = e_{v_{i+1}}$ as defined in 4.3.

Claim 4.5.1. For $0 < i \leq n$, $T(e_{i-1}, v_i) \subset \bigcup_{j=0}^{i-1} P_{v_j}$; and if $\gamma_j$ is the geometric dual to $e_j$ for each $j$, we have $T(e_{i-1}, v_i) \cap \partial P_{v_0} \subset \gamma_0$, and $T(e_{i-1}, v_i) \cap \partial P_{v_j} \subset \gamma_{j-1} \cup \gamma_j$ for $0 < j \leq i - 1$.

First take $i = 1$. Lemma 3.14 implies that $T(e_0, v_1) \subset T(e_0, v_0)$, and Lemma 3.15 implies that $T(e_0, v_0) \subset P_{v_0}$. (Recall from Lemma 3.7 that $P_{v_T} = P_{v_0}$ is centered.) By Definition 3.13, $\gamma_0$ is the edge of $T(e_0, v_0)$ opposite $v_0$. Any other edge $\gamma'$ of $P_{v_0}$ is contained in $T(e', v_0)$, where $e'$ is the geometric dual to $\gamma'$, and Lemma 3.15 implies that $T(e_0, v_0) \cap \gamma' \subset T(e_0, v_0) \cap T(e', v_0)$ is at most the endpoint $\gamma_0 \cap \gamma'$. Thus $T(e_0, v_0) \cap \partial P_{v_0} \subset \gamma_0$.

For $1 < i \leq n$, the combination of Lemmas 3.14 and 3.15 implies:

$$T(e_{i-1}, v_i) \subset T(e_{i-1}, v_{i-1}) \subset P_{v_{i-1}} \cup T(e_{i-2}, v_{i-1})$$

We assume by induction that $T(e_{i-2}, v_{i-1}) \subset \bigcup_{j=0}^{i-2} P_{v_j}$, so by the above $T(e_{i-1}, v_i) \subset \bigcup_{j=0}^{i-1} P_{v_j}$.
To prove the claim it remains to show that $T(e_{i-1}, v_i)$ has reasonable intersections with the $P_{v_j}$. We assume by induction that $T(e_{i-2}, v_{i-1}) \cap \partial P_{v_0} \subset \gamma_0$ and $T(e_{i-2}, v_{i-1}) \cap \partial P_{v_j} \subset \gamma_{j-1} \cup \gamma_j$ for $0 < j \leq i - 2$. Thus by (4.5.2) it suffices to show that $T(e_{i-1}, v_{i-1}) \cap \partial P_{v_{i-1}} \subset \gamma_{i-2} \cup \gamma_{i-1}$. This follows as in the base case, but using the non-centered case of Lemma 3.15.

Below we will obtain different information from essentially the same sequence of observations.

**Claim 4.5.3.** For $n > 1$ and $0 < j < i \leq n$, $T(e_{i-1}, v_i) \subset T(e_{j-1}, v_j) \cup \left( \bigcup_{k=j}^{i-1} P_{v_k} \right)$.

We again prove the claim by induction, this time on $n$. For $n = 2$ the only case above is with $i = n = 2$ and $j = 1$. Applying (4.5.2) immediately implies the conclusion in this case. Let us now take $n > 2$ and suppose that the claim holds for $n - 1$. The only new cases to consider are $i = n$, since for $i \leq n - 1$ the conclusion follows from the induction hypothesis.

Fixing $i = n$, the conclusion for $j = n - 1$ is a direct application of (4.5.2). For $j < n - 1$, (4.5.2) gives $T(e_{n-1}, v_n) \subset T(e_{n-2}, v_{n-1}) \cup P_{v_{n-1}}$, so induction produces:

$$T(e_{n-1}, v_n) \subset T(e_{j-1}, v_j) \cup \left( \bigcup_{k=j}^{n-2} P_{v_k} \right) \cup P_{v_{n-1}} = T(e_{j-1}, v_j) \cup \left( \bigcup_{k=j}^{n-1} P_{v_k} \right)$$

This proves the claim.

We first fix $w = v_T$ and $v \in T^{(0)} - \{v_T\}$, and prove $\text{int} \, P'_v \cap P_w = P'_v \cap \text{int} \, P_w = \emptyset$. Let $e_0 \cup \ldots e_{n-1}$ be the reduced edge path joining $v_T$ to $v$ in $T$, numbered and oriented as above, so that $w = v_T$ is the terminal vertex of $e_0$ and $v$ is the initial vertex of $e_{n-1}$. With the $v_j$ also numbered as above for $0 \leq j \leq n$, we apply Claim 4.5.3 with $i = n$ and $j = 1$. Taking a union with $P_v$ on each side of the result yields:

$$P_v \cup T(e_{n-1}, v) \subset T(e_0, v_1) \cup \left( \bigcup_{k=1}^{n} P_{v_k} \right)$$

This is because $v = v_n$. Since $v_1 \in v_T + 1$ and $e_0 = e_{v_1}$, the fact above the lemma implies that $\text{int} \, P'_{v_T} \cap T(e_0, v_1) = \emptyset$. By Lemma 1.9, $\text{int} \, P_{v_T} \cap P_{v_k} = \emptyset$ for $1 \leq k \leq n$. Since $P'_v \subset P_T \cup T(e_{n-1}, v)$, it follows from (4.5.4) that $P'_v \cap \text{int} \, P'_{v_T} = \emptyset$.

Since $P'_v \subset P_T \cup T(e_{n-1}, v)$, $\text{int} \, P'_v \subset \text{int} \, (P_T \cup T(e_{n-1}, v)) = \text{int} \, P_v \cup \text{int} \, T(e_{n-1}, v) \cup \text{int} \, \gamma_{n-1}$. The latter equality here follows from Lemma 3.15, which asserts that $T(e_{n-1}, v)$ intersects $P_v$ in precisely the edge $\gamma_{n-1}$ geometrically dual to $e_{n-1}$. Similarly:

**Claim 4.5.5.** For $0 < i \leq n$,

$$\text{int} \, (P_v \cup T(e_{n-1}, v)) \subset \text{int} \, T(e_{i-1}, v_i) \cup \left( \bigcup_{k=i}^{n} \text{int} \, P_{v_k} \right) \cup \left( \bigcup_{k=i-1}^{n-1} \text{int} \, \gamma_k \right),$$

where $\gamma_k$ is the geometric dual to $e_k$ for each $k$.

This uses Claim 4.5.3, also noting that $T(e_{i-1}, v) \cap \partial P_{v_k} \subset \gamma_{k-1} \cup \gamma_k$ for $i \leq k < n$, by Claim 4.5.1. Thus by the fact above the lemma, $\text{int} \, P'_v \cap P'_{v_T} = \emptyset$. 

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For distinct $v$ and $w$ in $T^{(0)} - \{v_T\}$, let $e_0 \cup \ldots \cup e_{n-1}$ and $f_0 \cup \ldots \cup f_{m-1}$ be reduced edge paths joining $v_T$ to $v$ and $w$, respectively. Let the $e_i$ be numbered and oriented as in the case $w = v_T$ above, and number the vertices $v_i$ accordingly. Similarly, number the $f_i$ so that $v_T$ is an endpoint of $f_0$ and $w$ an endpoint of $f_{m-1}$, and orient them as in Lemma 3.7. Let $w_i$ be the terminal vertex of $f_i$ for each $i$, so $v_T = w_0$ in particular, and take $w = w_m$.

Because $T$ is a tree, there are three cases to consider: either these paths have no edges in common, meeting only at $v_T$; or one is an initial segment of the other; or they share an initial segment that is proper in each. We will address the third case in detail. The others are similar, and we will indicate afterwards how to approach them.

If $e_0 \cup \ldots \cup e_{n-1}$ and $f_0 \cup \ldots \cup f_{m-1}$ share an initial segment that is proper in each, then $m$ and $n$ are each at least 2. Let $i_0 > 0$ but less than $\min\{m, n\}$ be such that $e_i = f_i$ for $i < i_0$ but $e_{i_0} \neq f_{i_0}$. It follows that $v_i = w_i$ for $i \leq i_0$, but that $\{v_{i_0+1}, \ldots, v_n\}$ is disjoint from $\{w_{i_0+1}, \ldots, w_m\}$, since $T$ is a tree.

Applying Claim 4.5.3 to $e_0 \cup \ldots \cup e_{n-1}$ with $i = n$ and $j = i_0 + 1$, then taking the union with $P_v = P_{v_0}$ on both sides, we have:

\[
(4.5.6) \quad P_v \cup T(e_{n-1}, v) \subset T(e_{i_0}, v_{i_0+1}) \cup \left( \bigcup_{k= i_0+1}^{n} P_{v_k} \right)
\]

Using Claim 4.5.3 on $f_0 \cup \ldots \cup f_{m-1}$ with $i = m$ and $j = i_0 + 1$, arguing as above yields:

\[
(4.5.7) \quad P_w \cup T(f_{m-1}, w) \subset T(f_{i_0}, w_{i_0+1}) \cup \left( \bigcup_{k= i_0+1}^{m} P_{w_k} \right)
\]

We will use Claim 4.5.5 with $i = i_0 + 1$ to show that $\text{int}(P_v \cup T(e_{n-1}, v_n))$ is disjoint from $P_w \cup T(f_{m-1}, w)$, from which it immediately follows that $\text{int} P_v' \cap P_w' = \emptyset$.

Lemma 1.9 implies that $\text{int} P_{v_k} \cap P_{w_i} = \emptyset$ for each $k \in \{i_0+1, \ldots, n\}$ and $l \in \{i_0+1, \ldots, m\}$, and also that $\text{int} \gamma_k \cap P_{w_i} = \emptyset$ for $k \in \{i_0, \ldots, n-1\}$ and the same $l$. This is because $\gamma_k = P_{v_k} \cap P_{w_{k+1}}$ for each such $k$, and so its interior is disjoint from all $P_v$ but these two. In the particular case $k = i_0, \gamma_{i_0}$ is a different edge of $P_{v_0}$ than its edge of intersection with $P_{w_{i_0+1}}$, since $w_{i_0+1} \neq v_{i_0+1}$, so it is still true that $\text{int} \gamma_{i_0} \cap P_{w_{i_0+1}} = \emptyset$.

Lemma 3.14 implies that $T(e_{i_0}, v_{i_0+1}) \subset T(e_{i_0}, v_{i_0})$ and $T(f_{i_0}, w_{i_0+1}) = T(f_{i_0}, v_{i_0})$ (recall that $w_{i_0} = v_{i_0}$), and by Lemma 3.15 these are each contained in $P_{v_0} \cup T(e_{i_0-1}, v_{i_0})$. It further implies that $T(e_{i_0}, v_{i_0}) \cap T(f_{i_0}, v_{i_0})$ is at most an edge of each containing $v_{i_0}$; hence in particular $\text{int} T(e_{i_0}, v_{i_0+1}) \cap T(f_{i_0}, w_{i_0+1}) = \emptyset$.

We will finally show that $\text{int} T(e_{i_0}, v_{i_0+1}) \cap P_{w_l} = \emptyset$ for each $l \in \{i_0 + 1, \ldots, m\}$. Claim 4.5.1 implies that $T(e_{i_0}, v_{i_0+1}) \subset \bigcup_{j=0}^{i_0} P_{v_j}$, and the second part of that claim implies that its interior is contained in $\left( \bigcup_{j=0}^{i_0} \text{int} P_{v_j} \right) \cup \left( \bigcup_{j=0}^{i_0-1} \text{int} \gamma_j \right)$. It thus follows as above that $\text{int} T(e_{i_0}, v_{i_0+1}) \cap P_{w_l} = \emptyset$ for each $l$ under consideration. This completes the proof that $\text{int} P_v' \cap P_w' = \emptyset$ when the edge paths joining each to $v_T$ share a proper initial segment.

The case when the edge paths meet at $v_T$ and nowhere else is similar to the above but with $i_0 = 0$. Then $T(e_0, v_1)$ and $T(f_0, w_1)$ are each contained in $P_{v_T}$, and it is immediate that
int $T(e_0, v_1)$ is disjoint from $P_{v_l}$ for each $l > 0$. The case when $e_0 \cup \ldots \cup e_{n-1}$ (say) is a proper initial segment of $f_0 \cup \ldots \cup f_{m-1}$ is similar to the case $v = v_T$ that we first addressed. An extra argument is required in this case to show that $T(e_v, v) = T(e_{n-1}, v_n)$ has interior disjoint from the $P_{v_l}$; this proceeds as in the paragraph directly above. □

**Definition 4.6.** Let $V$ be the Voronoi tessellation and $P_c$ the centered dual decomposition determined by $\tilde{S} = \pi^{-1}(S)$, where $\pi: \mathbb{H}^2 \to F$ is the universal cover of a closed hyperbolic surface and $S \subset F$ is finite, and fix a 2-cell $Q$ of $P_c$ containing a component $T$ of $V_n^{(1)}$. Define $\mathcal{Q}_0 = \{v_T\}$ and $Q_0 = P_{v_T}$, and for $k > 0$ let $T_k^{(0)}$ consist of vertices of $T$ joined to $v_T$ by a path of at most $k$ edges, and $Q_k' = \bigcup_{v \in T_k^{(0)}} P_v'$. The restriction $U_x|Q_k'$ of $U_x$ to $Q_k'$ as the union of sectors:

$$U_x|Q_k' = \bigcup \{U_x \cap P_v' \mid v \in T_k^{(0)}, x \in P_v\}$$

Let the restriction $U_x|Q_k'$ of $U_x$ to $Q_k'$ be the union of its restrictions to $Q_k'$ over all $k \geq 0$.

The point of defining the restriction is to exclude an incidental component of intersection with $Q_k'$ as in Figure 4.1, where a disk $U_x$ protrudes from a polygon that does not entirely contain the sector that it determines, intersecting one that does not have $x$ as a vertex.

**Lemma 4.7.** Let $V$ be the Voronoi tessellation and $P_c$ the centered dual decomposition determined by $\tilde{S} = \pi^{-1}(S)$, where $\pi: \mathbb{H}^2 \to F$ is the universal cover of a closed hyperbolic surface and $S \subset F$ is finite. If $\{U_x\}$ is a set of open hyperbolic disks of radius $R \leq i(S)$ centered at the vertices of a 2-cell $Q$ of $P_c$ containing a component $T$ of $V_n^{(1)}$, for each $k \geq 0$:

$$\text{area}\left(Q_k - \bigcup_{x \in S} U_x|Q_k'\right) = \sum_{v \in T_k^{(0)}} D_R(d_v) - \sum_{w \in T_{k+1}^{(0)} - T_k^{(0)}} D_R(d_{e_w}, J_w),$$

where $d_v$ represents $P_v$ in $\tilde{\mathcal{A}}_{n_v}$ for each $v$ (with $n_v$ the valence of $v$ in $V^{(1)}$), and $D_R(d_{e_w}, J_w)$ is as in [3, Lemma 5.2] (with $d_{e_w}$ the length of the geometric dual to $e_w$).

Proof. We prove this by induction on $k$. By definition, $P_{v_T} = P_{v_T}' \cup \bigcup_{w \in v_T + 1} T(e_w, w))$. For each vertex $x$ of $P_{v_T}$, $U_x \cap P_{v_T}$ is a sector (by [3, Lemma 5.3]) that is a non-overlapping union of sectors $(U_x \cap P_{v_T}') \cup (U_x \cap T(e_w, w))$ (by Lemma 4.4 and [3, Lemma 5.2], respectively). By Lemma 4.4, $T(e_w, w)$ does not intersect $U_x$ unless $x$ is one of its vertices. Thus:

$$\text{area}\left(P_{v_T}' - \bigcup_{x \in S} U_x|Q_0\right) = D_R(d_{v_T}) - \sum_{w \in v_T + 1} D_R(d_{e_w}, J_w),$$

This is because [3, Lemma 5.4] implies that $D_R(d_{v_T})$ is the area of the region in $P_{v_T}$ outside the $U_x$, and [3, Lemma 5.2] implies that $D_R(d_{e_w}, J_w)$ is the area of the region of $T(e_w, w)$ outside the disks centered at its endpoint. Since $T^{(0)} = \{v_T\}$ and $v_T + 1 = T_1^{(0)} - T_0^{(0)}$, the $k = 0$ case follows.

For $k > 0$, we note that for any $v \in T_k^{(0)}$, $\text{int}P_{v_T}'$ intersects $U_x|Q_k'$ if and only if $x$ is a vertex of $P_v$. This by definition of the $U_x|Q_k'$, since by Lemma 4.4 for a vertex $x'$ of $P_{v_T}'$ for some $w \neq v$, $P_w'$ contains the sector of $U_{x'}$ that it determines, and $\text{int}P_{v_T}' \cap P_{v_T}' = \emptyset$ by Lemma 4.5.
For $k > 0$, assume the conclusion holds for $k - 1$. Writing $Q'_k = Q'_{k-1} \cup \left( \bigcup_{v \in T^{(0)}_{k-1} - T^{(0)}_{k-1}} P'_v \right)$ yields:

$$\text{area} \left( Q'_k - \bigcup_{x \in S} U_x | Q'_k \right) = \sum_{v \in T^{(0)}_{k-1}} D_R(d_v) - \sum_{w \in T^{(0)}_{k-1} - T^{(0)}_{k-1}} D_R(d_{e_w}, J_w),$$

$$+ \sum_{v \in T^{(0)}_{k-1} - T^{(0)}_{k-1}} \left( D_R(d_v) + D_R(d_{e_v}, J_v) - \sum_{w \in v+1} D_R(d_{e_w}, J_w) \right)$$

The first line above follows from the inductive hypothesis, and the second by an argument analogous to the base case. The sum above telescopes, and since $T^{(0)}_{k+1} - T^{(0)}_k = \bigcup \left\{ v + 1 \mid v \in T^{(0)}_k - T^{(0)}_{k-1} \right\}$, the lemma follows by induction. \qed

The main result of the section follows quickly.

**Proof of Proposition 4.2.** The result follows from Lemma 4.7 and two observations.

First, for a 2-cell $Q$ of $P_c$ containing a component $T$ of $V_n^{(1)}$, let $\tilde{Q}$ be a lift to $\mathbb{H}^2$ and $\tilde{T}$ the lift of $T$ that it contains. Because $\tilde{T}$ is finite, there exists $k > 0$ such that $\tilde{T} = \tilde{T}^{(0)}_k$, and hence $\tilde{Q} = \tilde{Q}'_k$ (by Lemma 4.5) and $\tilde{T}^{(0)}_{k+1} - \tilde{T}^{(0)}_k = \emptyset$. Thus Lemma 4.7 implies:

$$\text{area} \left( \tilde{Q} - \bigcup_{x \in \tilde{S}} U_x | \tilde{Q} \right) = \sum_{v \in T^{(0)}} D_R(d_v)$$

The first observation above, combined with Lemma 4.4, implies for each 2-cell $\tilde{Q}$ of $\tilde{P}_c$ that contains a component $\tilde{T}$ of $\tilde{V}_n^{1}$, and each $x \in \tilde{S}$ that is the vertex of $P_v$ for some $v \in \tilde{T}^{(0)}$, that $\tilde{Q}$ contains the union of sectors of $U_x$ determined by the $P_v$ over all $v \in T^{(0)}$. The same holds for 2-cells $\tilde{Q}$ that are centered polygons, by [3, Lemma 5.3]. It follows that for each $x \in \tilde{S}$, $U_x \subset \bigcup_{i=1}^n Q_i$, where $\{Q_i\}_{i=1}^n$ is the collection of 2-cells of $\tilde{P}_c$ containing $x$. This in turn implies the second observation: that $U_x \cap \tilde{Q} = U_x | \tilde{Q}$ for each $x \in \tilde{S}$. \qed

### 5. Admissible spaces

This section is devoted to abstracting the data provided by a 2-cell $Q$ of the centered dual and lower bounds for its edge lengths, turning this into a parameter space and a function on it whose minimum bounds the defect below. We will show that this defect function attains a minimum on the closure of the parameter space, and in the second half of the section restrict the location of such a minimum for low-complexity cells.

**Definition 5.1.** Let $T \subset V$ be finite graphs such that $T$ is a rooted tree with root vertex $v_T$. Partially order $T^{(0)}$ by setting $v < v_T$ for each $v \in T^{(0)} - \{v_T\}$ and $w < v$ if the edge arc in $T$ joining $w \in T^{(0)} - \{v_T\}$ to $v_T$ runs through $v$. A vertex $v$ is minimal if there is no $w \in T^{(0)}$ such that $w < v$; ie, so that $v + 1$ (as in Definition 4.3) is empty. For $v \in T^{(0)} - \{v_T\}$, say “$e \to v$” for each edge $e \neq e_v$ of $V$ containing $v$, where $e_v$ is as in Definition 4.3.
Definition 5.2. Let $T \subset V$ be finite graphs such that $T$ is a rooted tree with root vertex $v_T$ and each vertex of $V$ has valence at least three. Let $E$ be the set of edges of $T$ and $F$ the frontier of $T$ in $V$, fix an ordering on $E \cup F$ and for some choice of $d_e > 0$ for each $e \in F$, let $d_F = (d_e) \in \mathbb{R}^F$. For any $d_E = (d_e) \in \mathbb{R}^E$, let $d = (d_E, d_F)$ and $P_v(d) = (d_{e_0}, \ldots, d_{e_{n_1}})$ for $v \in T^{(0)}$, where the edges of $V$ containing $v$ are cyclically ordered as $e_0, \ldots, e_{n_1}$. We will say $d_E$ is in the admissible set $Ad(d_F)$ determined by $d_F$ if the following criteria hold:

1. For $v \in T^{(0)} \setminus \{v_T\}$ with valence $n_v$ in $V$, $P_v(d) \in A_C_{n_v} \subset C_{n_v}$ has largest entry $d_{e_v}$.
2. $P_{v_T}(d) \in C_{n_T}$, where $v_T$ has valence $n_T$ in $V$.
3. $J(P_v(d)) > J(P_w(d))$ for each $w \in v - 1$, where $J(P_v(d))$ and $J(P_w(d))$ are the respective radii of $P_v(d)$ and $P_w(d)$.

(Note that the final condition above is vacuous for minimal $v$.)

Definition 5.3. Let $T \subset V$ be finite graphs such that $T$ is a rooted tree with root vertex $v_T$ and each vertex of $V$ has valence at least three. Let $E$ be the set of edges of $T$ and $F$ the frontier of $T$ in $V$, and fix $d_F = (d_e) \in \mathbb{R}^F$ such that $Ad(d_F) \neq \emptyset$. For each $d_E \in Ad(d_F)$, let $d = (d_E, d_F)$ and for $R \leq \min\{d_e/2 \mid e \in F\}$, define:

$$D_R(T, d) = \sum_{v \in T^{(0)}} D_R(P_v(d)),$$

where $P_v(d)$ is as in Definition 5.2 and $D_R(T)$ is as defined in [3, Lemma 5.4].

Lemma 5.4. Let $V$ be the Voronoi decomposition of a closed hyperbolic surface $F$ determined by a finite set $S \subset F$, and let $Q$ be a centered dual 2-cell containing a component $T$ of $V_1^{(1)}$. Let $E$ be the edge set of $T$ and $F$ its frontier in $V$, and for each $e \in E$ or such that $(e, v) \in F$ for some $v$, let $d_e$ be the length of the geometric dual to $e$. Then $d_E \in Ad(d_F)$ and $D_R(Q) = D_R(T, d)$ for $d = (d_E, d_F)$ and $R \leq \min\{d_e/2 \mid e \in F\}$.

Proof. For each $v \in T^{(0)}$, Lemma 1.9 implies that the vertex polygon $P_v$ is a cyclic polygon with cyclically ordered side length collection $(d_{e_0}, \ldots, d_{e_{n_1}})$, where $e_0, \ldots, e_{n_1}$ is the cyclically ordered collection of edges of $V$ containing $v$. Recall from Definition 3.1 that each edge of $T$ is oriented. Lemma 3.6 asserts that the root vertex $v_T$ of $T$ is the terminal endpoint of every edge of $T$ that contains it. Since every other edge of $V$ containing $v_T$ is centered, Lemma 3.3 implies that $P_{v_T} \in C_n$. This establishes (2) from Definition 5.2.

Lemma 3.3 also implies that for $v \in T^{(0)} \setminus \{v_T\}$, $P_v$ is non-centered with longest side length $d_{e_v}$, yielding (1) from Definition 5.2. For $v \in T^{(0)}$ and $w \in v - 1$, Lemma 3.7 implies that $w$ is the initial vertex of $e_w$, and the definition (in 5.1 above) implies that $v$ is its terminal vertex. Therefore Lemma 3.2 yields $J_v > J_w$ and hence, by Lemma 1.9, that $J(P_v) > J(P_w)$. This establishes (3) from Definition 5.2.

That $D_R(Q) = D_R(T, d)$ is a direct consequence of Definition 5.3 and Proposition 4.2. □

The lemma below implies in particular that the admissible set of $d_E$ is a bounded subset of $\mathbb{R}^F$, so that it has compact closure.
Lemma 5.5. Let \( T \subset V \) be finite graphs such that \( T \) is a rooted tree with root vertex \( v_T \) and each vertex of \( V \) has valence at least three. Let \( E \) be the set of edges of \( T \) and \( F \) the frontier of \( T \) in \( V \). There exist collections \( \{ b_e : (\mathbb{R}^+)^F \to \mathbb{R}^+ \mid e \in E \} \) and \( \{ h_e : (\mathbb{R}^+)^F \to \mathbb{R}^+ \mid e \in E \} \) characterized by the following properties:

- \( P_v(d) \in \overline{BC}_{n_v} \), with largest entry \( d_e \), for each \( v \in T^{(0)} - \{ v_T \} \), where \( v \) has valence \( n_v \) in \( V \) and \( d = (d_E, d_F) \), if and only if \( d_e = b_e(d_F) \) for each \( e \in E \).
- \( P_v(d) \in \overline{HC}_{n_v} \), with largest entry \( d_{e_v} \), for each \( v \in T^{(0)} - \{ v_T \} \) if and only if \( d_e = h_e(d_F) \) for each \( e \in E \).

For fixed \( d_F \), if \( d_E = (d_e \mid e \in E) \in Ad(d_F) \) then \( b_e(d_F) \leq d_e < h_e(d_F) \) for each \( e \in E \); and for \( d_F' = (d'_e \mid e \in F) \) such that \( d'_e \geq d_e \) for each \( e \in F \), \( b_e(d_F') \geq b_e(d_F) \) for each \( e \in E \).

Proof. The proof is by induction, the key point being that for \( v \in T^{(0)} - \{ v_T \} \), \( b_{e_v}(d_F) \) is determined by the set of \( b_{e_w}(d_F) \) for \( w < v \), and similarly for \( h_{e_v}(d_F) \). Fix \( d_F \in (\mathbb{R}^+)^F \).

Suppose first that \( v \in T^{(0)} \) is minimal, so each \( e \to v \) is in \( F \). Cyclically enumerate the edges of \( V \) containing \( v \) as \( e_0, \ldots, e_{n-1} \) so that \( e_0 = e_v \), and for each \( i > 0 \) let \( d_i = d_{e_i} \).

Then \([3, \text{Lemma 3.4}]\) implies that \( b_{e_v}(d_F) = b_0(d_1, \ldots, d_{n-1}) \) is the unique number such that \( (b_{e_v}(d_F), d_1, \ldots, d_{n-1}) \in U_n \cap \overline{BC}_n \), where \( U_n \) is as in \([3, \text{Lemma 3.2}]\). That is, \( b_{e_v}(d_F) \) is unique with the property that the tuple above is in \( \overline{BC}_n \) and has its largest entry first. \([3, \text{Lemma 3.10}]\) implies the analogous conclusion for \( b_{e_v}(d_F) = h_0(d_1, \ldots, d_{n-1}) \) and \( \overline{HC}_n \).

Let us also note that by \([3, \text{Corollary 3.11}]\), \( (d_0, d_1, \ldots, d_{n-1}) \in U_n \) is in \( \overline{AC}_n - \overline{C}_n \) if and only if \( b_{e_v}(d_F) \leq d_0 < h_{e_v}(d_F) \). If \( d_E \in Ad(d_F) \) then for \( d = (d_E, d_F) \) \([\text{Definition 5.2 (1)}]\) implies that \( P_v(d) = (d_{e_v}, d_1, \ldots, d_{n-1}) \in U_n \cap (\overline{AC}_n - \overline{C}_n) \), so \( b_{e_v}(d_F) \leq d_{e_v} < h_{e_v}(d_F) \).

Now fix \( v \in T^{(0)} - \{ v_T \} \) non-minimal, and suppose that we \( b_{e_v}(d_F) \) and \( h_{e_v}(d_F) \) are defined for each \( w < v \), satisfying the following inductive hypotheses:

- \( P_w(d) \in \overline{BC}_{n_w} \), with largest entry \( d_{e_w} \), for each \( w < v \), where \( d = (d_E, d_F) \), if and only if \( d_{e_w} = b_{e_w}(d_F) \) for each \( w < v \).
- \( P_w(d) \in \overline{HC}_{n_w} \), with largest entry \( d_{e_w} \), for each \( w < v \), where \( d = (d_E, d_F) \), if and only if \( d_{e_w} = b_{e_w}(d_F) \) for each \( w < v \).
- For each \( d_E \in Ad(d_F) \), \( b_{e_w}(d_F) \leq d_{e_w} < h_{e_w}(d_F) \) for each \( w < v \).

Cyclically enumerate the edges containing \( v \) as \( e_0, \ldots, e_{n-1} \) so that \( e_0 = e_v \), and for \( i > 0 \) define:

\[
    d_i = \begin{cases} 
    d_{e_i} & e_i \in F \\
    b_{e_i}(d_F) & e_i \in E
    \end{cases}
\]

\[
    d'_i = \begin{cases} 
    d_{e_i} & e_i \in F \\
    h_{e_i}(d_F) & e_i \in E
    \end{cases}
\]

Then \([3, \text{Lemma 3.4}]\) again implies that \( b_{e_v}(d_F) = b_0(d_1, \ldots, d_{n-1}) \) is the unique number such that \( (b_{e_v}(d_F), d_1, \ldots, d_{n-1}) \in U_n \cap \overline{BC}_n \), and \([3, \text{Lemma 3.10}]\) gives the analogous conclusion for \( h_{e_v}(d_F) = h_0(d'_1, \ldots, d'_{n-1}) \).

For \( d_E \in d_F \), by hypothesis \( d_i \leq d_{e_i} \) for each \( i \in \{1, \ldots, n-1\} \), so \([3, \text{Lemma 3.4}]\) implies that \( b_{e_v}(d_F) \leq b_0(d_{e_1}, \ldots, d_{e_{n-1}}) \). We also have \( d_{e_i} < d_i \) for each \( i \) such that \( e_i \in E \) by hypothesis.
Lemma 5.5 implies that 

\[ b_0(d_1, \ldots, d_{n-1}) \leq d_v < h_0(d_1, \ldots, d_{n-1}), \]

and it follows that \( b_v(d_F) \leq d_v < h_v(d_F) \). We have thus proved the three hypotheses above for \( \{v\} \cup \{w < v\} \), so it follows by induction that they hold on all of \( T^{(0)} - \{v_T\} \).

(Recall in particular that there is a unique \( e_v \) for each \( v \in T^{(0)} - \{v_T\} \), and that \( \mathcal{E} \) is the set of all such \( e_v \).

The final claim of the lemma, that \( b_v \) is “increasing” in \( d_F \) for each \( e \), follows from an inductive argument and [3, Lemma 3.4], which asserts that \( b_0(d_1, \ldots, d_{n-1}) \leq b_0(d_1', \ldots, d'_{n-1}) \) when \( d_i \leq d_i' \) for each \( i \).

**Remark 5.6.** For any given tree \( T \) with frontier \( F \), the proof of Lemma 5.5 is easily adapted (using formulas from [3]) to produce a recursive algorithm that takes \( d_F \in (\mathbb{R}^+)^F \) and computes the values \( b_v(d_F) \) or \( h_v(d_F) \) from the “outside in.”

**Lemma 5.7.** Let \( T \subset V \) be finite graphs such that \( T \) is a rooted tree with root vertex \( v_T \) and each vertex of \( V \) has valence at least three. Let \( \mathcal{E} \) be the set of edges of \( T \) and \( F \) the frontier of \( T \) in \( V \), and fix \( d_F = (d_e \mid e \in \mathcal{E}) \in \mathbb{R}^F \). If \( Ad(d_F) \neq \emptyset \), then for each \( d_E \) in its closure \( \overline{Ad}(d_F) \), \( d = (d_E, d_F) \) satisfies:

1. For \( v \in T^{(0)} - \{v_T\} \) with valence \( n_v \) in \( V \), \( P_v(d) \in \widehat{AC}_{n_v} - \tilde{C}_{n_v} \) has largest entry \( d_v \).
2. \( P_{v_T}(d) \in \widehat{C}_{n_{v_T}} \cup \tilde{B}C_{n_{v_T}} \), where \( v_T \) has valence \( n_{v_T} \) in \( V \).
3. \( J(P_v(d)) \geq J(P_w(d)) \) for each \( w \in v - 1 \), where \( J(P_v(d)) \) and \( J(P_w(d)) \) are the respective radii of \( P_v(d) \) and \( P_w(d) \).

**Proof.** Lemma 5.5 implies that \( Ad(d_F) \) is bounded in \( \mathbb{R}^\mathcal{E} \) and therefore has compact closure. Since \( P_{v_T}(d) \in \mathcal{C}_n \) for each \( d \in Ad(d_F) \times \{d_F\} \), for \( d \) in the closure it must be the case that \( P_{v_T}(d) \in \tilde{C}_n \), establishing (2). [3, Proposition 4.1] implies that for each \( v \in T^{(0)} \), \( J(P_v(d)) \) varies continuously with \( d \) on \( Ad(d_F) \times \{d_F\} \). Thus since \( J(P_v(d)) > J(P_w(d)) \) for each such \( d \) and \( w \in v - 1 \), \( J(P_v(d)) \geq J(P_w(d)) \) for each \( d \in \overline{Ad}(d_F) \times \{d_F\} \), so (3) holds.

Now suppose that (1) does not hold, so there exist \( d \in \overline{Ad}(d_F) \times \{d_F\} \) and \( v \in T^{(0)} - \{v_T\} \) such that \( P_v(d) \in \mathcal{AC}_n - \mathcal{AC}_n \). Let us take \( v \) to be maximal with this property, so that in particular \( P_w(d) \in \mathcal{AC}_n \) for the endpoint \( w \) of \( e_v \). If \( \{d_n\} \) is a sequence in \( Ad(d_F) \times \{d_F\} \) approaching \( d \), then \( P_w(d_n) \rightharpoonup P_w(d) \), and so there is a universal upper bound on \( J(P_w(d_n)) \). On the other hand, [3, Lemma 4.7] implies that \( J(P_v(d_n)) \to \infty \), contradicting criterion (3) of Definition 5.2 for some \( d_n \). Therefore (1) holds.

**Lemma 5.8.** Let \( T \subset V \) be finite graphs such that \( T \) is a rooted tree with root vertex \( v_T \) and each vertex of \( V \) has valence at least three. Let \( \mathcal{E} \) be the set of edges of \( T \) and \( F \) the frontier of \( T \) in \( V \), and fix \( d_F = (d_e \mid e \in \mathcal{E}) \in \mathbb{R}^F \) such that \( Ad(d_F) \neq \emptyset \). Then \( D_R(T, d) \) is continuous on \( \overline{Ad}(d_F) \times \{d_F\} \) and attains a minimum there.

**Proof.** Since \( P \mapsto D_R(P) \) is continuous on \( \mathcal{AC}_n \) (by [3, Proposition 5.5]), and by the above \( P_v(d) \in \mathcal{AC}_n \) for each \( d \in \overline{Ad}(d_F) \times \{d_F\} \), \( D_R(T, d) \) is continuous on \( \overline{Ad}(d_F) \times \{d_F\} \). This
set is closed and, by Lemma 5.5, bounded, so it is compact and \( D_R(T, \mathbf{d}) \) attains a minimum on it.

For an arbitrary finite tree \( T \) and \( \mathbf{d}_F \in \mathbb{R}^F \) as above, it seems difficult to precisely describe \( Ad(\mathbf{d}_F) \) or determine the point in \( \overline{Ad}(\mathbf{d}_F) \) at which \( D_R(T, \mathbf{d}) \) attains its minimum. Here we will identify an alternative that such a minimum point must satisfy, at least for very simple \( T \): those with one or two edges. In the second half of the section, we will turn this into an algorithm that produces lower bounds on the minimum of \( D_R(T, \mathbf{d}) \), given lower bounds on the entries of \( \mathbf{d}_F \).

We first address the case that \( T \) has a single edge. In this case, uniquely, we are able to describe the topology of \( Ad(\mathbf{d}_F) \) and locate the minimum of \( D_R \).

**Lemma 5.9.** Let \( V \) be a graph and \( T \) a subgraph with one edge \( e_T \) and root vertex \( v_T \), and let \( F \) be the frontier of \( T \) in \( V \). For \( \mathbf{d}_F \in \mathbb{R}^F \), if \( Ad(\mathbf{d}_F) \neq \emptyset \) it is an interval: \((d^-, d^+)\) or \([d^+, d^-]\). For \( R \geq 0 \), \( D_R(T, \mathbf{d}) \) attains its minimum at \( \mathbf{d} = (d^-, \mathbf{d}_F) \), which satisfies one of:

1. \( P_v(\mathbf{d}) \in \overline{BC_n} \), where \( n \) is the valence in \( V \) of the initial vertex \( v \) of \( e_T \); or
2. \( P_{v_T}(\mathbf{d}) \in \overline{BC_{n_T}} \), where \( n_T \) is the valence of \( v_T \) in \( V \).

In case (2) above, \( d^- \) is not the largest side length of \( P_{v_T}(\mathbf{d}) \).

**Proof.** By Definition 5.2 \( Ad(\mathbf{d}_F) \) is contained in a subset of \( \mathbb{R}^+ \) consisting of possible values for \( d_{v_T} \). By Lemma 5.5, if criterion (1) is satisfied then \( d_{v_T} \in [b_{v_T}, h_{v_T}] \), where \( b_{v_T} = b_{v_T}(\mathbf{d}_F) \) and \( h_{v_T} = h_{v_T}(\mathbf{d}_F) \) as in Lemma 5.5. In fact, \( P_v(\mathbf{d}) \in AC_n - \mathcal{C}_n \) if and only if \( d_{v_T} \in [b_{v_T}, h_{v_T}] \), where \( \mathbf{d} = (d_{v_T}, \mathbf{d}_F) \). This follows from [3, Corollary 3.11], as pointed out in the base case of the proof of Lemma 5.5, and it follows that (1) is satisfied if and only if \( d_{v_T} \in [b_{v_T}, h_{v_T}] \).

Now consider criterion (2). Let the edges of \( V \) containing \( v_T \) be cyclically enumerated \( e_0, e_1, \ldots, e_{n_T} \) so that \( e_0 = e_T \). Then \( e_i \in F \) for \( 1 \leq i < n_T \). Let \( d = d_{e_T} \) and \( d_i = d_{e_i} \) for \( i > 0 \), and for \( \mathbf{d} = (d, \mathbf{d}_F) \) recall that from Definition 5.2 that:

\[
P_{v_T}(\mathbf{d}) = (d, d_1, \ldots, d_{n_T} - 1) \in (\mathbb{R}^+)^n
\]

Let \( M = \max\{d_i\}^{-n_T}_{i=1} \). The inequality of [3, Definition 3.1], determining whether \( P_{v_T}(\mathbf{d}) \in \overline{C}_n \), takes different forms depending on the relation of \( d \) to \( M \). For \( d \geq M \), \( P_{v_T}(\mathbf{d}) \in \overline{C}_{n_T} \) if and only if \( A_d(d/2) + \sum_{i=1}^{n_T-1} A_{d_i}(d/2) > 2\pi \), where \( A_d(J) \) is from [3, Lemma 1.7]. By [3, Lemma 1.8], \( A_d(d/2) = \pi \) and \( \sum_{i=1}^{n_T-1} A_{d_i}(J) \) decreases in \( J \) to a horizontal asymptote of 0, so the criterion of [3, Definition 3.1] is satisfied at \( d = M \) and there exists \( D_0^+ > M \) such that \( A_d(d/2) + \sum_{i=1}^{n_T-1} A_{d_i}(d/2) > 2\pi \) if and only if \( d < D_0^+ \).

For \( d \leq M \), [3, Definition 3.1] requires \( A_d(M/2) + \sum_{i=1}^{n_T-1} A_{d_i}(M/2) > 2\pi \) for \( P_v(\mathbf{d}) \in \overline{C}_n \). Since \( A_d(J) \) is continuous and increases in \( d \) there is an open interval of positive \( d < M \), with left endpoint \( D_0^- \geq 0 \), on which this inequality holds. Thus \( \{d | P_{v_T}(\mathbf{d}) \in \overline{C}_n \} = (D_0^-, D_0^+) \). If \( D_0^- > 0 \) then \( A_{D_0^-}(M/2) + \sum_{i=1}^{n_T-1} A_{d_i}(M/2) = 2\pi \). In this case, for \( \mathbf{d} = (D_0^-, \mathbf{d}_F) \) [3, Lemma 3.3] implies \( P_{v_T}(\mathbf{d}) \) is in the closure of \( \overline{C}_{n_T} \). It is not in \( \overline{C}_{n_T} \), so \( P_{v_T}(\mathbf{d}) \in \overline{BC}_{n_T} \) by [3, Lemma 3.4]. Furthermore, its longest side length is \( M > D_0^- \), since \( M = d_i \) for some \( i > 0 \).
If $Ad(d_F) \neq \emptyset$ then $[b_{e_T}, h_{e_T}] \cap (D_0^-, D_0^+)$ is non-empty. We claim that $f(d) = J(P_{v_T}(d)) - J(P_v(d))$ decreases in $d$ on $[b_{e_T}, h_{e_T}] \cap (D_0^-, D_0^+)$, where $J: \mathcal{AC}_n \to \mathbb{R}^+$ is as in [3, Lemma 3.6]. This follows directly from [3, Lemma 4.5], which implies that on this interval:

$$
\left| \frac{\partial}{\partial d} J(P_{v_T}(d)) \right| < \frac{1}{2} < \left| \frac{\partial}{\partial d} J(P_v(d)) \right|
$$

By criterion (3) of Definition 5.2, $Ad(d_F) = f^{-1}(\mathbb{R}^+) \cap ([b_{e_T}, h_{e_T}] \cap (D_0^-, D_0^+))$, so since $f$ is decreasing $Ad(d_F)$ is a subinterval containing the left endpoint of $[b_{e_T}, h_{e_T}] \cap (D_0^-, D_0^+)$, if it is non-empty. If $b_{e_T} \leq D_0^-$ then $Ad(d_F) = (d^-, d^+)$ for $d^- = D_0^-$; otherwise $Ad(d_F) = [d^-, d^+]$ for $d^- = b_{e_T}$. By [3, Proposition 5.5], for $d$ in this interval the derivative $\frac{\partial}{\partial d} D_R(T, d)$ is:

$$
\cosh R \left[ \sqrt{\frac{1}{\cosh^2(d/2)} - \frac{1}{\cosh^2 J(P_{v_T}(d))}} - \sqrt{\frac{1}{\cosh^2(d/2)} - \frac{1}{\cosh^2 J(P_v(d))}} \right]
$$

Since $J(P_{v_T}(d)) > J(P_v(d))$, this quantity is positive, and it follows that the defect sum increases with $d$. Therefore its minimum is at $d^-$. If $d^- = b_e$ then $P_v(d) \in \mathcal{BC}_n$ for $d = (d^-, d_F)$, by Lemma 5.5, and condition (2) above holds. If $d^- = D_0^-$ then since $D_0^+ \geq b_{e_T} > 0$ in this case, $P_{v_T}(d) \in \mathcal{BC}_{n_T}$ for $d = (d^-, d_F)$ as we observed above, and condition (1) holds. We also noted above that $d^- = D_0^-$ is not the longest edge of $P_{v_T}(d)$ in this case. 

A two-edged tree is homeomorphic to an interval, but up to symmetry there are two possibilities for a root vertex: the intersection of the two edges, or one of the two boundary vertices. Although these two possibilities have different admissible spaces, the locations at which the associated defect function may be minimized satisfy the same criteria.

**Proposition 5.10.** Let $V$ be a graph and $T$ a subtree of $V$ with two edges and root vertex $v_T$. Let $F$ be the frontier of $T$ in $V$ and fix $d_F \in \mathbb{R}^F$ with $Ad(d_F) \neq \emptyset$. For $R \geq 0$, $D_R(T, d)$ attains a minimum at $d = (d_F, d_F)$ satisfying one of:

1. $P_v(d) \in \mathcal{BC}_{n_v}$ for each $v \in T^{(0)} - \{v_T\}$, where $v$ has valence $n_v$ in $V$; or
2. $P_{v_T}(d) \in \mathcal{BC}_{n_T}$, where $v_T$ has valence $n_T$ in $V$; or
3. $J(P_v(d)) = J(P_{v_T}(d))$ for each $v \in T^{(0)} - \{v_T\}$.

Proposition 5.10 follows directly from the two lemmas below, which separately address the possible locations for the root vertex of $T$.

**Lemma 5.11.** Let $V$ be a graph and $T$ a subtree of $V$ with two edges that share its root vertex $v_T$. With $F$, $d_F \in \mathbb{R}^F$, and $R \geq 0$ as in Proposition 5.10, its conclusions hold.

**Proof.** Lemma 5.7 describes $\overline{Ad}(d_F)$ and asserts that $\sum_{v \in T^{(0)}} D_R(P_v(d))$ attains a minimum somewhere on $\overline{Ad}(d_F) \times \{d_F\}$. We will show that if $d = (d_F, d_F)$ satisfies none of the criteria of Proposition 5.10, then $d_F$ may be deformed in $\overline{Ad}(d_F)$ to reduce $\sum_{v \in T^{(0)}} D_R(P_v(d))$. 


Let $\epsilon_1 = e_{v_1}$ and $\epsilon_2 = e_{v_2}$, and let $d_1$ and $d_2$ be the respective lengths of their geometric duals. Then $d_{\epsilon} = (d_1, d_2)$. We note that as long as $d = (d_{\epsilon}, d_{\mathcal{F}}) \in \overline{Ad}(d_{\mathcal{F}})$, then reducing either of $d_1$ or $d_2$ does not increase the defect sum, since (say) $\frac{\partial}{\partial d_1} \sum_{v \in T^{(0)}} D_R(P_v(d))$ is:

$$\cosh R \left[ \sqrt{\frac{1}{\cosh^2(d_1/2)} - \frac{1}{\cosh^2 J(P_{v_T}(d))}} - \sqrt{\frac{1}{\cosh^2(d_1/2)} - \frac{1}{\cosh^2 J(P_{v_1}(d))}} \right] \geq 0$$

This follows from [3, Proposition 5.5] because $d_{\epsilon} \in \overline{Ad}(d_{\mathcal{F}})$ implies that $P_{v_T}(d) \in \overline{C}_{n_T}, d_1$ is the largest side length of $P_{v_1}(d) \in \mathcal{AC}_{n_1} - C_{n_1}$, and $J(P_{v_T}(d)) \geq J(P_{v_1}(d))$.

Now assume that $d_{\epsilon} = (d_1, d_2)$ does not satisfy any of criteria (1) – (3) from Proposition 5.10. Thus $P_{v_T}(d) \in \mathcal{C}_n$ by (2), and by (3) we may assume that (say) $J(P_{v_T}(d)) > J(P_{v_1}(d))$.

If $P_{v_2}(d) \in \overline{C}_{n_2}$, then $P_{v_1}(d) \notin \overline{C}_{n_1}$ by (1). In this case, addressed in the paragraph below, we also have $J(P_{v_T}(d)) > d_2/2 = J(P_{v_2}(d))$, by [3, Lemma 3.9].

Since the radius varies continuously with $d$ (see [3, Proposition 4.1]), and $P_{v_1}(d)$ is in the open set $\mathcal{AC}_{n_1} - \overline{C}_{n_1}$, and $P_{v_T}(d)$ is in the open set $\mathcal{C}_n$ there exists $\epsilon > 0$ such that for $d_1 - \epsilon < d'_1 < d_1$ and $d'_{\epsilon} = (d'_1, d_2)$, $P_{v_1}(d') \in \mathcal{AC}_{n_1} - \overline{C}_{n_1}, P_{v_T}(d') \in \mathcal{C}_n$, and $J(P_{v_T}(d')) > J(P_{v_1}(d'))$ for $i = 1$ or 2, where $d' = (d'_{\epsilon}, d_{\mathcal{F}})$. Note that $P_{v_2}(d') = P_{v_2}(d) \in \mathcal{AC}_{n_2} - \overline{C}_{n_2}$.

Therefore each $d'_{\epsilon} \in \overline{Ad}(d_{\mathcal{F}})$, and the defect computation above gives:

$$\sum_{v \in T^{(0)}} D_R(P_v(d')) < \sum_{v \in T^{(0)}} D_R(P_v(d))$$

(In particular, since $J(P_{v_T}(d)) > J(P_{v_1}(d)) > d_1/2$, the inequality is strict.)

Continuing to assume that (1) – (3) do not hold, and in particular that $J(P_{v_T}(d)) > J(P_{v_1}(d))$, let us now suppose that $P_{v_2}(d) \notin \overline{C}_{n_2}$. In this case it is possible that $J(P_{v_T}(d)) = J(P_{v_2}(d))$. We will reduce $d_2$ instead of $d_1$, yielding $d'_{\epsilon} = (d_1, d'_2)$ for $d'_2 < d_2$, and $d' = (d_{\epsilon}, d_{\mathcal{F}})$. Note that [3, Lemma 4.5] implies that $\frac{\partial}{\partial d_2} J(P_{v_2}(d)) > \frac{1}{2} > \frac{\partial}{\partial d_2} J(P_{v_1}(d))$, and indeed this estimate holds at $d'$ for as long as $P_{v_T}(d') \in \mathcal{C}_{n_T}$ and $P_{v_2}(d') \in \mathcal{AC}_{n_2} - \overline{C}_{n_2}$.

Let $\epsilon > 0$ be small enough that if $d_2 - \epsilon < d'_2 < d_2$ and $d'_{\epsilon} = (d_1, d'_2)$, then $P_{v_T}(d') \in \mathcal{C}_{n_T}$, $P_{v_1}(d') \in \mathcal{AC}_{n_2} - \overline{C}_{n_2}$ and $J(P_{v_1}(d')) > J(P_{v_1}(d'))$, where $d' = (d'_{\epsilon}, d_{\mathcal{F}})$. By the paragraph above, $J(P_{v_T}(d')) > J(P_{v_2}(d'))$ for such $d'$, and since $P_{v_1}(d') = P_{v_1}(d) \in \mathcal{AC}_{n_1} - C_{n_1}$ it follows that $d' \in \overline{Ad}(d_{\mathcal{F}})$. Furthermore, the change-of-defect computation using [3, Proposition 5.5] again implies a strict decrease in defect. □

Lemma 5.12. Let $V$ be a graph and $T$ a rooted subtree with two edges, only one containing the root vertex $v_T$, and other vertices $v_1$ and $v_2$. With $\mathcal{F}$, $d_{\mathcal{F}} \in \mathbb{R}_{\mathcal{F}}$, and $R \leq \min\{d_e/2 | e \in \mathcal{F}\}$ as in Proposition 5.10, the conclusions of the proposition hold.

Proof. Lemma 5.7 describes $\overline{Ad}(d_{\mathcal{F}})$ and asserts that $\sum_{v \in T^{(0)}} D_R(P_v(d))$ attains a minimum somewhere on $\overline{Ad}(d_{\mathcal{F}}) \times \{d_{\mathcal{F}}\}$. We will show that if $d = (d_{\epsilon}, d_{\mathcal{F}})$ satisfies none of the criteria above, then $d_{\epsilon}$ may be deformed in $\overline{Ad}(d_{\mathcal{F}})$ to reduce $\sum_{v \in T^{(0)}} D_R(P_v(d))$.

Take $v_2$ to be the opposite endpoint of the edge $e_2 = e_{v_2}$ containing $v_T$, let $v_1$ be the far endpoint of the other edge $e_1 = e_{v_1}$, and let $d_1$ and $d_2$ be the lengths of the geometric
duals to $e_1$ and $e_2$, respectively, so that $d_\mathcal{E} = (d_1, d_2)$. Assume now that $d = (d_\mathcal{E}, d_\mathcal{F}) \in \overline{Ad}(d_\mathcal{F}) \times \{d_\mathcal{F}\}$ does not satisfy any of (1) – (3) from Proposition 5.10.

Since $d_\mathcal{E} \in \overline{Ad}(d_\mathcal{F})$ we have $J(P_{v_1}(d)) \leq J(P_{v_2}(d)) \leq J(P_{v_2}(d))$. Since $d$ does not satisfy (3), at least one of these inequalities is strict. Let us suppose first that $J(P_{v_2}(d)) < J(P_{v_2}(d))$. If $P_{v_1}(d) \in \mathcal{C}_{n_1}$, then “not (1)” implies that $\partial d_\mathcal{E} \notin \mathcal{C}_{n_2}$, and furthermore:

$$J(P_{v_2}(d)) > d_2/2 > d_1/2 = J(P_{v_1}(d))$$

Therefore there exists $\epsilon > 0$ such that for all $d'_2$ with $d_2 - \epsilon < d'_2 < d_2$, taking $d'_\mathcal{E} = (d_1, d'_2)$ and $d' = (d'_\mathcal{E}, d_\mathcal{F})$ we have $P_{v_2}(d') \notin \mathcal{C}_{n_2}$, $P_{v_2}(d') \in \mathcal{C}_n$, and $J(P_{v_2}(d')) > J(P_{v_2}(d'))$. We note that $P_{v_1}(d') = P_{v_1}(d)$ for all such $d'$. [3, Proposition 5.5] implies that $\partial d_\mathcal{E} \sum_{v \in T^{(0)}} D_R(P_v(d))$: is:

$$\cosh R \left[ \sqrt{\frac{1}{\cosh^2(d_2/2)} - \frac{1}{\cosh^2 J(P_{v_2}(d))}} - \sqrt{\frac{1}{\cosh^2(d_2/2)} - \frac{1}{\cosh^2 J(P_{v_2}(d))}} \right]$$

As long as $J(P_{v_2}(d)) > J(P_{v_2}(d))$, this quantity is positive, so decreasing $d_2$ decreases the defect sum. Thus with $d'$ as above we have $\sum_{v \in T^{(0)}} D_R(P_v(d')) < \sum_{v \in T^{(0)}} D_R(P_v(d))$.

Continuing to suppose that $J(P_{v_2}(d)) < J(P_{v_2}(d))$, let us now also assume that $P_{v_1}(d) \notin \mathcal{C}_{n_1}$. [3, Lemma 4.5] implies that decreasing $d_1$ has the effect of decreasing $J(P_{v_2}(d))$ but increasing $J(P_{v_2}(d))$, since $P_{v_2}(d) \in \mathcal{AC}_{n_2} - \mathcal{C}_{n_2}$ has longest side $d_2$. Thus there exists $\epsilon > 0$ such that for $d_1 = \epsilon < d'_1 < d_1$, taking $d'_\mathcal{E} = (d'_1, d_2)$ and $d' = (d'_\mathcal{E}, d_\mathcal{F})$ we have $P_{v_1}(d') \notin \mathcal{C}_{n_1}$, $P_{v_2}(d') \in \mathcal{AC}_{n_2} - \mathcal{C}_{n_2}$, and $J(P_{v_2}(d')) < J(P_{v_2}(d'))$. Furthermore, $P_{v_2}(d') = P_{v_2}(d) \in \mathcal{C}_n$ for all such $d'$, so $\frac{\partial}{\partial d_1} \sum_{v \in T^{(0)}} D_R(P_v(d'))$ is:

$$\cosh R \left[ \sqrt{\frac{1}{\cosh^2(d'_1/2)} - \frac{1}{\cosh^2 J(P_{v_2}(d'))}} - \sqrt{\frac{1}{\cosh^2(d'_1/2)} - \frac{1}{\cosh^2 J(P_{v_2}(d'))}} \right]$$

Thus we again find that $\sum_{v \in T^{(0)}} D_R(P_v(d')) < \sum_{v \in T^{(0)}} D_R(P_v(d))$ for $d'_1 < d_1$. (Note that even if $J(P_{v_1}(d)) = J(P_{v_2}(d))$, strict inequality holds for $d'$ by the above, and so the strict inequality of defect sums is also accurate.)

Let us finally suppose that $J(P_{v_2}(d)) = J(P_{v_2}(d))$. Then since (3) does not hold, $J(P_{v_1}(d)) < J(P_{v_2}(d))$. Since (2) does not hold we have $P_{v_2}(d) \in \mathcal{C}_n$, so $J(P_{v_2}(d)) = J(P_{v_2}(d)) > d_2/2$ and so also $P_{v_2}(d) \notin \mathcal{C}_{n_2}$. [3, Lemma 4.5] implies that reducing $d_2$ reduces the radius of $P_{v_2}(d)$ faster than that of $P_{v_2}(d)$, and it follows that $d_2$ may be reduced slightly keeping $d_\mathcal{E} \in \overline{Ad}(d_\mathcal{F})$. A derivative computation as above shows that this reduces the defect. 

6. Defect bounds from side length bounds

**Definition 6.1.** For $\mathcal{F}$ finite and $b_\mathcal{F}, d_\mathcal{F} \in \mathbb{R}^\mathcal{F}$, say $d_\mathcal{F} \geq b_\mathcal{F}$ if $d_f \geq b_f$ for each $f \in \mathcal{F}$, where $b_\mathcal{F} = (b_f \mid f \in \mathcal{F})$ and $d_\mathcal{F} = (d_f \mid f \in \mathcal{F})$.

This section describes an algorithm with the following:

**Input:** A rooted tree $T$ with frontier $\mathcal{F}$, $R \geq 0$, and $b_\mathcal{F} \in (\mathbb{R}^+)^\mathcal{F}$.

**Output:** $D > 0$ such that $D_R(T, (d_\mathcal{E}, d_\mathcal{F})) \geq D$ for all $d_\mathcal{F} \geq b_\mathcal{F}$ and $d_\mathcal{E} \in \overline{Ad}(d_\mathcal{F})$. 
We begin with some \textit{a priori} bounds.

**Lemma 6.2.** Let $T$ be a rooted tree with root vertex $v_T$, edge set $\mathcal{E}$, and frontier $\mathcal{F}$ such that each $v \in T^{(0)}$ is at least three-valent in $T \cup \{e \mid (e, v) \in \mathcal{F}\}$. Fix $b_\mathcal{F} \in \mathbb{R}^\mathcal{F}$. For $v \in T^{(0)} - \{v_T\}$ let $e_0, \ldots, e_{n-1}$ be the set of edges containing $v$, with $e_v = e_0$, and define $P_{v}^h(b_\mathcal{F}) = (h_0(b_1, \ldots, b_{n-1}), b_1, \ldots, b_{n-1}) \in \mathcal{HC}_n$, where $h_0$ is as in [3, Lemma 3.10] and:

$$b_i = \begin{cases} b_{e_i}(b_\mathcal{F}) & e_i \in \mathcal{E} \\ b_{e_i} & e_i \in \mathcal{F} \end{cases}$$

Then for $R \geq 0$, $d_\mathcal{F} \geq b_\mathcal{F}$, $d_\mathcal{E} \in \overline{Ad}(d_\mathcal{F})$ and $d = (d_\mathcal{E}, d_\mathcal{F})$, $D_R(P_v(d)) > D_R(P_v^h(b_\mathcal{F}))$, where $P_v(d)$ is as in Definition 5.2.

*Proof.* Fix $d_\mathcal{F} \geq b_\mathcal{F}$ and $d_\mathcal{E} = (d_e \mid e \in \mathcal{E}) \in \overline{Ad}(d_\mathcal{F})$. By Lemma 5.5, $d_e \geq b_e(d_\mathcal{F}) \geq b_e(b_\mathcal{F})$ for each $e \in \mathcal{E}$. Thus for $v \in T^{(0)} - \{v_T\}$ and $e_0, \ldots, e_{n-1}$ as described in the hypotheses above, $b_i \leq d_{e_i}$ for each $i > 0$. Criterion (1) of Lemma 5.7 implies that $P_v(d) \in \mathcal{AC}_n - \mathcal{C}_n$ has longest edge $d_{e_v}$, so [3, Corollary 5.11] implies $D_R(P_v(d)) > D_R(P_v^h(b_\mathcal{F}))$. \hfill \Box

**Proposition 6.3.** Let $T$ be a rooted tree with root vertex $v_T$, edge set $\mathcal{E}$, and frontier $\mathcal{F}$ such that each $v \in T^{(0)}$ is at least three-valent in $T \cup \{e \mid (e, v) \in \mathcal{F}\}$. Fix $b_\mathcal{F} \in (\mathbb{R}^+)$. For a subtree $T_0$ of $T$ with $v_T \in T_0$, let $\mathcal{E}_0$ and $\mathcal{F}_0$ be the edge set and frontier (in $T \cup \{e \mid (e, v) \in \mathcal{F}\}$) of $T_0$, respectively, and define $b_{\mathcal{F}_0} = (b_e \mid e \in \mathcal{F}_0)$ by:

$$b_e = \begin{cases} b_e & e \in \mathcal{F} \\ b_e(b_\mathcal{F}) & e \in \mathcal{E} \end{cases}$$

Let $D_0 = \inf\{D_R(T_0, (d_{\mathcal{E}_0}, d_{\mathcal{F}_0})) \mid d_{\mathcal{E}_0} \in \overline{Ad}(d_{\mathcal{F}_0}), d_{\mathcal{F}_0} \geq b_{\mathcal{F}_0}\}$. Then for any $d_\mathcal{F} \geq b_\mathcal{F}$ and $d_\mathcal{E} \in \overline{Ad}(d_\mathcal{F})$,

$$D_R(T, d_\mathcal{F}) > D_0 + \sum_{v \in T^{(0)} - T_0^{(0)}} D_R(P_v^h(b_\mathcal{F}))$$

where $P_v^h(b_\mathcal{F})$ is as in Lemma 6.2.

*Proof.* A fixed pair $d_\mathcal{F} = (d_e \mid e \in \mathcal{F}) \geq b_\mathcal{F}$ and $d_\mathcal{E} = (d_e \mid e \in \mathcal{E}) \in \overline{Ad}(d_\mathcal{F})$ determines $d_{\mathcal{F}_0}$ and $d_{\mathcal{E}_0}$ simply by taking the appropriate entries of $d_\mathcal{F}$ or $d_\mathcal{E}$. Lemma 5.5 and the construction of $b_{\mathcal{F}_0}$ then imply that $d_{\mathcal{F}_0} \geq b_{\mathcal{F}_0}$.

Taking $d_0 = (d_{\mathcal{E}_0}, d_{\mathcal{F}_0})$, it is clear by Definition 5.2 and the construction of $d_{\mathcal{E}_0}$ and $d_{\mathcal{F}_0}$ that for each $v \in T_0$, $P_v(T_0, d_0) = P_v(T, d)$, where $d = (d_{\mathcal{E}}, d_{\mathcal{F}})$. Definition 5.2 thus implies:

$$D_R(T, d) = D_R(T_0, d_0) + \sum_{v \in T^{(0)} - T_0^{(0)}} D_R(P_v(d))$$

Lemma 5.7 implies that $d_{\mathcal{E}_0} \in \overline{Ad}(d_{\mathcal{F}_0})$, since $d_{\mathcal{E}} \in d_\mathcal{F}$ by hypothesis, so $D_R(T_0, d_0) \geq d_0$ and the result follows from Lemma 6.2. \hfill \Box

Proposition 6.3 can be used in conjunction with the result below to give \textit{a priori} bounds.
Lemma 6.4. Let $T$ be a rooted tree with root vertex $v_T$, edge set $E$, and frontier $F$ such that each $v \in T^{(0)}$ is at least three-valent in $T \cup \{e \mid (e,v) \in F\}$. For $b_F \in (\mathbb{R}^+)^F$, let $b_E = (b_e(b_F) \mid e \in E) \in \mathbb{R}^E$ and take $b = (b_E, b_F)$. Enumerate the edges of $V$ containing $v_T$ as $e_0, \ldots, e_{n-1}$ so that $b_{e_0}$ is largest. With $b_0 : (\mathbb{R}^+)^{n-1} \to \mathbb{R}^+$ as in [3, Lemma 3.4], define

$$B_{e_0} = \begin{cases} b_0(b_{e_1}, \ldots, b_{e_{n-1}}) & \text{if } b_{e_0} > b_0(b_{e_1}, \ldots, b_{e_{n-1}}) \\ b_{e_0} & \text{otherwise} \end{cases}$$

For $R \geq 0$, let $M_R(v_T, b_F) = D_R(B_{e_0}, b_{e_1}, \ldots, b_{e_{n-1}})$. Then $D_R(P_{v_T}(d_E, d_F)) \geq M_R(v_T, b_F)$ for each $d_F \geq b_F$, and $d_E \in \overline{Ad}(d_F)$.

Proof. Given $d_E$ and $d_F$ as above, Lemma 5.5 implies that $d_{e_i} \geq b_{e_i}$ for each $i \in \{0, \ldots, n-1\}$, and therefore also that $d_{e_0} \geq B_{e_0}$. Since $P_{v_T}(d_E, d_F) \in \overline{C}_n \cup \overline{BC}_n$ by Lemma 5.7, and $(B_{e_0}, b_{e_1}, \ldots, b_{e_{n-1}}) \in \overline{C}_n \cup \overline{BC}_n$ by construction, [3, Lemma 6.6] implies the result. \qed

Remark 6.5. With the hypotheses of Lemma 6.4, if $v_T$ is three-valent in $V$ and $b_{e_0} > b_0(b_{e_1}, b_{e_2})$, the conclusion may be improved, using [3, Lemma 6.9], taking:

$$M_R(v_T, b_F) = \min\{D_R(b_{e_0}, b_{e_1}, b_{e_2}), D_R(b_{e_0}, b_1', b_2')\},$$

where $\cosh b_{e_0} = \cosh b_1' + \cosh b_2' - 1 = \cosh b_{e_1} + \cosh b_2' - 1$.

Given a rooted tree $T$ with root vertex $v_T$, edge set $E$, and frontier $F$ such that each vertex of $T$ is at least three-valent in $T \cup \bigcup_{e \in F} e$, for $b_F \in (\mathbb{R}^+)^F$ and $R \geq 0$, the procedure below can be algorithmically implemented:

1. For each $e \in E$, compute $b_e(b_F)$ as in Lemma 5.5 (see Remark 5.6).
2. For each $v \in T^{(0)} - \{v_T\}$, compute $D_R(P_v^h(b_F))$ for $P_v^h(b_F)$ as in Lemma 6.2.
3. Compute $M_R(v_T, b_F)$ with Lemma 6.4, or if $v_T$ has valence three, with Remark 6.5.
4. Let $D = M_R(v_T, b_F) + \sum_{v \in T^{(0)} - \{v_T\}} D_R(P_v^h(b_F))$.

By Proposition 6.3 (taking $T_0 = \{v_T\}$) and Lemma 6.4, $D$ as defined above is a lower bound on $D_R(T, (d_E, d_F))$ for any $d_F \geq b_F$, and $d_E \in \overline{Ad}(d_F)$.

Below we will describe how to improve the procedure above under the assumption that $D_R(T, d)$ attains its minimum at a point of $Ad(d_F)$ satisfying one of the three criteria of Proposition 5.10. We will treat these cases separately.

6.1. Case (1): $P_v(d) \in \overline{BC}_{n_v}$ for all $v \in T^{(0)} - \{v_T\}$. Lemma 5.5 implies that each $d_F \in \mathbb{R}^F$ determines a unique $d_E \in \overline{Ad}(d_F)$ such that $d = (d_E, d_F)$ falls into this case. For such $d$, [3, Corollary 5.8] implies:

Lemma 6.6. Let $T$ be a rooted tree with root vertex $v_T$, edge set $E$, and frontier $F$ such that each $v \in T^{(0)}$ is at least three-valent in $T \cup \bigcup\{e \mid (e,v) \in F\}$. Fix $b_F \in \mathbb{R}^F$, let $b_E = (b_e(b_F) \mid e \in E)$, and for $v \in T^{(0)} - \{v_T\}$ define $P_v^b(b_F) = P_v(b_E, b_F) \in \overline{BC}_{n_v}$. Then for $R \geq 0$, $d_F \geq b_F$, $d_E \in \overline{Ad}(d_F)$ and $d = (d_E, d_F)$ such that $P_v(d) \in \overline{BC}_{n_v}$ for all $v \in T^{(0)} - \{v_T\}$, $D_R(P_v(d)) > D_R(P_v^b(b_F))$ for each such $v$. 
Using Lemma 6.6, we may improve the basic algorithm in this case by replacing the computation of \( D_R(P^h_v(b_F)) \) in step (2) with that of \( D_R(P^h_v(b_F)) \), and in step (4) taking \( D = M_R(v_T, b_F) + \sum_{v \in \mathcal{T}(v) - \{v_T\}} D_R(P^h_v(b_F)) \).

6.2. Case (2): \( P_{v_T}(d) \in \tilde{BC}_{n_T} \). Our main advantage in this case is the following improved version of Lemma 6.4.

Lemma 6.7. Let \( T \) be a rooted tree with root vertex \( v_T \), edge set \( \mathcal{E} \), and frontier \( \mathcal{F} \) such that each \( v \in \mathcal{T}(0) \) is at least three-valent in \( T \cup \bigcup \{e \mid (e, v) \in \mathcal{F}\} \). For \( b_F \in (\mathbb{R}^+)^{\mathcal{F}} \), let \( b_\mathcal{E} = (b_e(b_F) \mid e \in \mathcal{E}) \in \mathbb{R}^\mathcal{E} \) and take \( b = (b_\mathcal{E}, b_F) \), and enumerate the edges of \( V \) containing \( v_T \) as \( e_0, \ldots, e_{n-1} \). With \( b_0: (\mathbb{R}^+)^{n-1} \to \mathbb{R}^+ \) as in [3, Lemma 3.4], for each \( i \) define
\[
B_{e_i} = b_0(b_{e_0}, \ldots, \hat{b}_{e_i}, \ldots, b_{e_{n-1}})
\]
Then for \( R \geq 0, d_F \geq b_F \), and \( d_\mathcal{E} \in \overline{AD}(d_F) \) such that \( P_{v_T}(d_\mathcal{E}, d_F) \in \tilde{BC}_{n_T} \) has longest side dual to \( e_i \), \( D_R(P_{v_T}(d_\mathcal{E}, d_F)) \geq D_R(b_0, \ldots, B_{e_i}, \ldots, b_{e_{n-1}}) \).

This follows from Lemma 5.5 and [3, Corollary 5.8] as in the proof of Lemma 6.4. If the longest edge of \( P_{v_T}(d) \) is dual to an element of \( \mathcal{E} \), we may further augment Lemma 6.4:

Lemma 6.8. Let \( T \) be a rooted tree with root vertex \( v_T \), edge set \( \mathcal{E} \), and frontier \( \mathcal{F} \) such that each \( v \in \mathcal{T}(0) \) is at least three-valent in \( T \cup \bigcup \{e \mid (e, v) \in \mathcal{F}\} \). For \( d_F \in (\mathbb{R}^+)^{\mathcal{F}} \) and \( d_\mathcal{E} \in \overline{AD}(d_F) \) such that \( P_{v_T}(d_\mathcal{E}, d_F) \in \tilde{BC}_{n_T} \) has longest side dual to \( e \in \mathcal{E} \), \( P_v(d_\mathcal{E}, d_F) \in \tilde{BC}_{n_v} \), where \( v \) is the initial vertex of \( e \).

Proof. Let \( d = (d_\mathcal{E}, d_F) \). Since \( P_{v_T}(d) \in \tilde{BC}_{n_T} \) by hypothesis, [3, Lemma 3.9] implies that \( J(P_{v_T}(d)) = d_i/2 \), where \( d_i \) is the length of the geometric dual to \( e_i \). On the other hand, \( P_{v_i}(d) \) also has longest side dual to \( e_i \) by Lemma 5.7, which further implies that \( J(P_{v_i}(d)) \leq J(P_{v_T}(d)) \). Since \( J(P_{v_0}(d)) \geq d_1/2 \) by [3, Lemma 3.6], it is equal to \( d_i/2 \), and therefore the Lemma holds by [3, Lemma 3.9]. \( \square \)

From Lemma 5.5 and [3, Corollary 5.8] we thus directly obtain:

Corollary 6.9. With the hypotheses of Lemma 6.7, for \( R \geq 0, d_F \geq b_F \), and \( d_\mathcal{E} \in \overline{AD}(d_F) \) such that \( P_{v_T}(d_\mathcal{E}, d_F) \in \tilde{BC}_{n_T} \) has longest side dual to \( e_i \in \mathcal{E} \), \( D_R(P_{v_T}(d)) \geq D_R(P^h_{v_i}(b_F)) \), where \( d = (d_\mathcal{E}, d_F) \), \( v_i \) is the initial vertex of \( e_i \), and \( P^h_{v_i}(b_F) \) is as in Lemma 6.6.

Remark 6.10. With the hypotheses of Corollary 6.9, if \( v_i \) is trivalent in \( T \cup \bigcup \{e \mid (e, v) \in \mathcal{F}\} \) and \( b_{e_i}(b_F) < B_{e_i} \), then using [3, Lemma 6.9] as in Remark 6.5 we have:
\[
D_R(P_{v_i}(d)) \geq \min\{D_R(B_{e_i}, b_{f_1}, b_{f_2}), D_R(b_{e_0}, b'_1, b_{f_2})\}
\]
Here \( f_1 \) and \( f_2 \) are the other edges containing \( v_i \), \( b_{f_1} \) and \( b_{f_2} \) are as in Lemma 6.6, and \( \cosh B_{e_i} = \cosh b'_1 + \cosh b_{f_2} - 1 = \cosh b_{f_1} + \cosh b'_{f_2} - 1 \).

In order to improve the basic algorithm in this case, enumerate the edges containing \( v_T \) as \( e_0, \ldots, e_{n-1} \), and in step (3) of the basic algorithm replace the computation of \( M_R(v_T, b_F) \) with those of \( M_R^{(i)}(v_T, b_F) = D_R(b_{e_0}, \ldots, B_{e_i}, \ldots, b_{e_{n-1}}) \) for each \( i \), where \( B_{e_i} \) is as in Lemma 6.7. It is useful now to divide into two subcases:
Case (2)(A): In step (4) of the basic algorithm, replace $D$ with:

$$D_A = \min \left\{ M_R^{(i)}(v_T, b_F) | e_i \in F \right\} + \sum_{v \in T^{(0)} - \{v_T\}} D_R(P_v^h(b_F))$$

Case (2)(B): In step (2) of the basic algorithm, also compute $D_R(P_{v_i}(b_F))$ for each $i$ such that $e_i \in \mathcal{E}$, where $v_i$ is the initial vertex of $e_i$, and in step (4) replace $D$ with:

$$D_B = \min_{e_i \in \mathcal{E}} \left\{ M_R^{(i)}(v_T, b_F) + D_R(P_{v_i}(b_F)) + \sum_{v \in T^{(0)} - \{v_T, v_i\}} D_R(P_v^h(b_F)) \right\}$$

For each $i$ such that $v_i$ is trivalent, $D_R(P_{v_i}^h(b_F))$ can be replaced by the computation from Remark 6.10 if $b_{e_i}(b_F) < b_{e_i}$.

By the results above, $D = \min\{D_A, D_B\}$ bounds $D_R(T, (d_F, d_{\mathcal{F}}))$ below for any $d_F \geq b_F$ and $d_{\mathcal{F}} \in \overline{Ad}(d_F)$.

6.3. Case (3): $J(P_v(d)) = J(P_v^t(d))$ for all $v \in T^{(0)} - \{v_T\}$. Here we have:

Lemma 6.11. Let $T$ be a rooted tree with root vertex $v_T$, edge set $\mathcal{E}$, and frontier $\mathcal{F}$ such that each $v \in T^{(0)}$ is at least three-valent in $T \cup \{e \mid (e, v) \in \mathcal{F}\}$. For $d_F \in (\mathbb{R}^+)^{\mathcal{F}}$ and $d_{\mathcal{F}} \in \overline{Ad}(d_F)$ such that $J(P_v(d)) = J(P_v^t(d))$ for each $v \in T^{(0)} - \{v_T\}$, where $d = (d_{\mathcal{F}}, d_F)$, there exists $P \in \overline{C}_{|\mathcal{F}|} \cup \overline{BC}_{|\mathcal{F}|}$ such that $D_R(T, d) = D_R(P)$ for any $R \geq 0$.

Proof. For $d = (d_{\mathcal{F}}, d_F)$, note that $P_v^t(d) \in \overline{C}_{v_T} \cup \overline{BC}_{v_T}$ by Lemma 5.7. Now fix a subtree $T_0$ of $T$ with $v_T \in T_0$ and $T = T_0 \cup e_0$ for some $e_0 \in \mathcal{E}$, and assume that the following holds for $T_0$: there is a cyclic polygon $P_0$ in $\mathbb{H}^2$ that contains a copy of $P_v(d)$ for each $v \in T_0^{(0)}$, such that $P_0 = \bigcup_{v \in T_0^{(0)}} P_v(d)$ and $P_v(d) \cap P_w(d)$ contains more than one point if and only if $v$ and $w$ bound an edge $e$ of $T_0$, in which case $P_v(d) \cap P_w(d)$ is the geometric dual to $e$.

The edge set of $P_0$ is in one-to-one correspondence with the frontier $\mathcal{F}_0$ of $T_0$ in $V$, and we will assume that $P_0$ has the same center $x_0$ and radius $J$ as $P_v(d) \subset P_0$ for each $v \in T_0^{(0)}$. Thus in particular, $P_0 \in \overline{C}_{|\mathcal{F}_0|} \cup \overline{BC}_{|\mathcal{F}_0|}$ by [3, Lemma 3.9], since this implies that $x_0 \in P_v^t(d) \subset P_0$.

Let $\{v_0\} = T^{(0)} - T_0^{(0)}$, and enumerate the edges of $V$ containing $v_0$ as $e_0, \ldots, e_{n-1}$, where $e_0$ is described above. Then $e_i \in \mathcal{F}$ for each $i > 0$, since $T = T_0 \cup e_0$, and $\mathcal{F}_0 = \{e_0\} \cup (\mathcal{F} - \{e_i\}_{i=1}^{n-1})$. Since $e_0$ is necessarily the first edge of the path in $T$ joining $v_0$ to $v_T$, $v_0$ is its initial vertex with the orientation from Lemma 3.7.

Since $e_0 \in \mathcal{F}_0$, $P_0$ has an edge corresponding to its geometric dual $\gamma_0$. Arrange a copy of $P_{v_0}(d)$ so that it intersects $P_0$ in $\gamma_0$. The isosceles triangle $T_0$ determined by $\gamma_0$ and the center of $P_{v_0}(d)$ has equal sides of length $J(P_{v_0}(d)) = J(P_{v_T}(d)) = J$ by hypothesis. Furthermore, Lemma 5.7 implies that $P_{v_0}(d) \in \overline{AC}_n - \overline{C}_n$ has longest side $\gamma_0$, so $\gamma_0 = T_0 \cap P_{v_0}(d)$ by [3, Lemma 1.6]. It follows that $T_0$ intersects the interior of $P_0$.

On the other hand, the triangle determined by $\gamma_0$ and the center $x_0$ of $P_0$ has two sides of length $J$ and by [3, Lemma 1.6] is contained in $P_0$, since $P_0 \in \overline{C}_{|\mathcal{F}_0|} \cup \overline{BC}_{|\mathcal{F}_0|}$. Since this triangle has the same side length collection as $T_0$, share $\gamma_0$ with it, and is on the same side of $\gamma_0$ it is.
identical to $T_0$. Therefore $x_0$ is the center of $P_{v_0}(d)$, so by [3, Lemma 1.4], $P = P_0 \cup P_{v_0}(d)$ is a cyclic polygon with center $x_0$ and radius $J$.

If $w_0$ is the terminal endpoint of $e_0$, then $P_{v_0}(d) \subset P_0$ contains $\gamma_0$, so $\gamma_0 = P_{v_0}(d) \cap P_{w_0}(d)$ and $P$ satisfies the hypotheses for $T$ that $P_0$ satisfied for $T_0$. It is easy to see that $D_R(P) = D_R(P_0) + D_R(P_{v_0}(d))$, so the result follows by an inductive argument.

The corollary below thus follows directly from [3, Corollary 5.8], and supplies the required lower bound without appeal to the basic algorithm.

**Corollary 6.12.** Let $T$ be a rooted tree with root vertex $v_T$, edge set $\mathcal{E}$, and frontier $\mathcal{F}$ such that each $v \in T^{(0)}$ is at least three-valent in $T \cup \{e \mid (e, v) \in \mathcal{F}\}$. Fix $b_{\mathcal{F}} \in (\mathbb{R}^+)^{\mathcal{F}}$, and enumerate the edges in $\mathcal{F}$ as $\{e_0, \ldots, e_{n-1}\}$ so that $b_{e_0}$ is maximal. Define:

$$B_{e_0} = \begin{cases} b_0(b_{e_1}, \ldots, b_{e_{n-1}}) & \text{if } b_{e_0} > b_0(b_{e_1}, \ldots, b_{e_{n-1}}), \\ b_{e_0} & \text{otherwise.} \end{cases}$$

Then for $R \geq 0$, $d_{\mathcal{F}} \geq b_{\mathcal{F}}$, $d_{\mathcal{F}} \geq b_{\mathcal{F}}$, and $d_{\mathcal{E}} \in \overline{Ad}(d_{\mathcal{F}})$ such that $J(P_v(d)) = J(P_{v_T}(d))$ for each $v \in T^{(0)} - \{v_T\}$, where $d = (d_{\mathcal{E}}, d_{\mathcal{F}})$, $D_R(T, d) \geq D_R(B_{e_0}, b_{e_1}, \ldots, b_{e_{n-1}})$.

**7. Computations**

This section is devoted to applying our previous results to prove Theorem 0.1. For $r_\beta$ as described in the theorem, $2.8298 < \cosh r_\beta < 2.8299$, and if $d_\beta = 2r_\beta$ then $15.0166 < \cosh d_\beta < 15.0167$. Let $r_1$ and $d_1$ satisfy $\cosh r_1 = 2.8298$ and $\cosh d_1 = 15.0166$, respectively. Then $r_1 < r_\beta$ and $d_1 < d_\beta$, and it is easy to show that $d_1 > 2r_1$.

Table 1 records the radius-$r_1$ defect of the symmetric, centered $n$-gons $P_n(d_1)$ for $n = 3$ through 6. These computations use [3, Lemma 6.6]. In each case we have truncated the result after five decimal places, so the actual defect value is greater than what is displayed.

| $n$ | $D_{r_1}(P_n(d_1))$ | $n$ | $D_{r_1}(P_n(d_1))$ | $n$ | $D_{r_1}(P_n(d_1))$ | $n$ | $D_{r_1}(P_n(d_1))$ |
|-----|---------------------|-----|---------------------|-----|---------------------|-----|---------------------|
| 3   | 0.12586             | 4   | 0.56593             | 5   | 1.22041             | 6   | 2.00496             |

Table 1. Radius-$r_1$ defects of highly symmetric polygons.

We will perform an analogous computation for centered dual 2-cells, but initially focus only on those with five frontier edges. To begin, let us note that an Euler characteristic computation implies:

**Remark 7.1.** If $T$ is a tree with edge set $\mathcal{E}$ and frontier $\mathcal{F}$, such that each vertex of $T$ is at least three-valent in $T \cup \{e \mid (e, v) \in \mathcal{F} \text{ for some } v \in T^{(0)}\}$, then $|\mathcal{F}| \geq |\mathcal{E}| + 3$.

This implies in particular that for a 2-cell $Q$ of the centered dual decomposition containing a component $T$ of $V_n^{(1)}$, if $Q$ has five edges then $T$ has at most two. Carrying the same argument further, we find that the possibilities for such $Q$ are exactly those showed in Figure 7.1. In the figure, Voronoi edges are dashed and black, and centered dual edges are solid and red.
Figure 7.1. Possibilities for (non-Delaunay) 5-edged centered dual 2-cells.

We have labeled the possibilities by the corresponding components of $V_n^{(1)}$ (in bold), where subscripts describe the valence of each vertex, with the root vertex in bold.

| $D_{r_1}(T, b)$ | Basic | Case (1) | Case (2)(A) | Case (2)(B) | Case (3) |
|-----------------|-------|----------|--------------|--------------|----------|
| $D_{r_1}(T_{3,4}, b)$ | 1.00510 | 1.17816 | 1.57569 | N/A | N/A |
| $D_{r_1}(T_{4,3}, b)$ | 1.63705 | 1.77971 | 1.71113 | N/A | N/A |
| $D_{r_1}(T_{3,3,3}, b)$ | 0.80915 | 1.15527 | 1.28432 | 1.38738 | 1.22041 |
| $D_{r_1}(T_{3,3,3}, b)$ | 1.24735 | 1.56044 | 1.38585 | 1.38738 | 1.22041 |

Table 2. $D_{r_1}(T, b)$ for the $T$ from Figure 7.1, where $b = (d_1, d_1, d_1, d_1, d_1)$.

Table 2 records the output of computer programs implementing the algorithms of Section 6 for the trees of Figure 7.1. (The programs are in the supplementary materials.) Each tree falls under the purview of the improvements to the basic algorithm described in the second half of the section, by Lemma 5.9 for the one-edged trees and Proposition 5.10 for the others. Since Lemma 5.9 does not allow Case (2)(B) or (3) of Proposition 5.10, we placed “N/A”s in the corresponding table entries. We have boxed the best bound for each tree: the basic algorithm’s output or the minimum of the improvements’ (whichever is larger).

**Corollary 7.2.** If a closed orientable hyperbolic surface $F$ of genus 2 has injectivity radius at least $d_1/2$, where $\cosh d_1 = 15.0166$, at $x \in F$, then no two-cell of the centered dual tessellation of $F$ determined by $x$ has more than four edges.

**Proof.** If $F$ has injectivity radius at least $d_1/2$ at $x$, then since $r_1 < d_1/2$ a hyperbolic disk $U$ of radius $r_1$ is embedded in $F$, centered at $x$. The area of $U$ is $2\pi(\cosh r_1 - 1) > 2\pi \cdot 1.8298$, so the area of its complement in $F$ is less than $2\pi \cdot 0.1702 < 1.07$.

For each 2-cell $P$ of the centered dual decomposition of $F$ determined by $\{x\}$, Proposition 4.2 implies that $D_{r_1}(P)$ is the area of $P - (P \cap U)$. Let us first assume that $P$ has five edges. Each is a geodesic arc that begins and ends at $x$, so its length is at least $d_1$. If $P$ is centered, then [3, Corollary 5.8] implies that $D_{r_1}(P) > D_{r_1}(P_n(d_1)) > 1.22$, by Table 1. This contradicts the fact that the total area complementary to $U$ in $F$ is less than 1.07.

If $P$ contains a component $T$ of $V_n^{(1)}$, where $V$ is the Voronoi tessellation determined by $\{x\}$, then $T$ is one of the possibilities pictured in Figure 7.1. Let $F$ be the frontier of $T$ in $V$. Lemma 5.4 implies that $D_{r_1}(P) = D_{r_1}(T, (d_F, d_F))$, where $d_F$ and $d_F \in Ad(d_F)$ are defined.
there. By the construction there and our hypothesis, \( d_e \geq d_1 \) for each \( e \) with \((e, v) \in \mathcal{F} \) for some \( v \), so appealing to Table 2, we find that \( D_{r_1}(P) > 1.15527 \). This again contradicts the fact that \( F - U \) has area less than 1.07.

By the above, no 2-cell of the centered dual decomposition has five edges. If a centered dual 2-cell \( Q \) with \( n > 5 \) edges is a centered Delaunay polygon, then by [3, Corollary 5.8] \( D_{r_1}(Q) = D_{r_1}(P_n(d_1)) \). This increases with \( n \), by [3, Lemma 6.6], so an appeal to Table 1 establishes a contradiction as above. Now assume that \( Q \) contains a component \( T \) of \( V_n^{(1)} \), let \( \mathcal{F} \) be the frontier of \( T \) in \( V^{(1)} \), and define \( d_F \) and \( d_E \in \text{Ad}(d_F) \) as in Lemma 5.4.

Again \( d_e \geq d_1 \) for each \( e \in \mathcal{E} \) or such that \((e, v) \in \mathcal{F} \) for some \( v \). Thus if the root vertex \( v_T \) of \( T \) has valence at least 5 in \( V^{(1)} \) then:

\[
D_{r_1}(T, d) \geq D_{r_1}(P_{v_T}(d_E, d_F)) \geq D_{r_1}(P_5(d_1)) > 1.22
\]

If \( v_T \) has valence four in \( V^{(1)} \) and a vertex \( v \) of \( T \) adjacent to \( v_T \) has valence at least four, let \( T_0 = e_v \subset T \) have frontier \( \mathcal{F}_0 \) in \( V^{(1)} \). Applying the basic algorithm with \( b_{\mathcal{F}_0} = (d_1, \ldots, d_1) \) yields a bound of 1.8623. Proposition 6.3 thus implies that \( D_{r_1}(T, d) > 1.8623 \).

If \( v_T \) has valence three in \( V^{(1)} \), so does a vertex \( v \) adjacent to \( v_T \) in \( T \), and a vertex \( w \neq v_T \) adjacent to \( v \) in \( T \) has valence at least four, applying the basic algorithm to \( T_0 = e_v \cup e_w \) with \( b_{\mathcal{F}_0} = (d_1, \ldots, d_1) \) yields a bound of 2.46104, so Proposition 6.3 implies that \( D_{r_1}(T, d) > 2.46104 \). In all other cases \( T \) has a subtree \( T_0 \), containing \( v_T \), with the same combinatorics and frontier in \( V^{(1)} \) as a tree from Figure 7.1, so as above \( D_{r_1}(T, d) > 1.15 \). In all cases we obtain a contradiction.

\[ \square \]

**Lemma 7.3.** Let \( T = e \) have frontier \( \mathcal{F} = \{(e_0, v), (e_1, v), (e_2, v_T), (e_3, v_T)\} \), where \( v_T \) is the root vertex and \( v \) is the other. For \( d_\beta \) as in Example 2.4 and \( d_F \geq (d_\beta, d_\beta, d_\beta, d_\beta) \), \( D_{r_\beta}(T, (d_E, d_F)) > D_{r_\beta}(P_4(d_\beta)) \) for each \( d_E \in \text{Ad}(d_F) \), where \( r_\beta = d_\beta/2 \).

**Proof.** We first note that if \( \text{Ad}(d_F) \neq \emptyset \), where \( d_F = (d_0, d_1, d_2, d_3) \), then for \( d_E = d_e \in \text{Ad}(d_F) \), \( P_e(d) = (d_e, d_0, d_1) \in \mathcal{AC}_3 - \mathcal{C}_3 \) and \( P_{v_T}(d) = (d_e, d_2, d_3) \in \mathcal{C}_3 \) by Definition 5.2. Thus [3, Corollary 3.11] and [3, Lemma 6.2] imply that:

\[
\cosh d_0 + \cosh d_1 - 1 = b_0(d_0, d_1) = \cosh d_2 + \cosh d_3 - 1
\]

In particular, \( \cosh d_0 + \cosh d_1 < \cosh d_2 + \cosh d_3 \), so if \( d_F \geq (d_\beta, d_\beta, d_\beta, d_\beta) \) then at least one of \( d_2 \) or \( d_3 \) is properly larger than \( d_\beta \).

For \( d_F \geq (d_\beta, d_\beta, d_\beta, d_\beta) \) with \( \text{Ad}(d_F) \neq \emptyset \), let us first suppose that the minimum of \( D_{r_\beta}(T, (d_e, d_F)) \) over \( \text{Ad}(d_F) \) occurs at \((d^-, d_F)\) satisfying Case (2) of Lemma 5.9. The corresponding improvement of the basic algorithm, found in Section 6.2, outputs 0.74844 given \( R = r_2 \) satisfying \( \cosh r_2 = 2.8299 \) and \( b_F = (d_1, d_1, d_1) \). Since \( r_2 > r_\beta \) and \( d_1 < d_\beta \), it follows that \( D_{r_\beta}(d_e, d_F) > 0.74844 \) for each \( d_e \in \text{Ad}(d_F) \). On the other hand, \( D_{r_\beta}(P_4(d_\beta)) < D_{r_\beta}(P_4(d_2)) < 0.56596 \), where \( \cosh d_2 = 15.0167 \), so \( D_{r_\beta}(d_e, d_F) > D_{r_\beta}(P_4(d_\beta)) \) in this case.

Now suppose that the minimum of \( D_{r_\beta}(T, (d_e, d_F)) \) over \( \text{Ad}(d_F) \) occurs at \((d^-, d_F)\) satisfying Case (1) of Lemma 5.9. Then \( d^- = b_0(d_0, d_1) < b_0(d_2, d_3) \) by the first paragraph above, so \( M_{r_\beta}(v_T, d_F) \) as defined in Lemma 6.4 is equal to \( D_{r_\beta}(d^-, d_2, d_3) \). Given \( R = r_\beta \) and
the complementary area to $U_d$ of Corollary 7.2). Each edge of the centered dual decomposition has length at least $P_r d$.

[3, Lemma 6.8] implies that $D_{r_\beta}(P_4(d_\beta)) = 2 D_{r_\beta}(B_0, d_\beta, d_\beta)$, where $B_0 = b_0(d_\beta, d_\beta)$. Since $d_F \geq (d_\beta, d_\beta, d_\beta, d_\beta)$, the monotonicity property of $b_0$ recorded in [3, Lemma 3.4] implies that $d^- \geq B_0$. Therefore $(d^-, d_0, d_1) \geq (B_0, d_\beta, d_\beta)$ and $(d^-, d_2, d_3) \geq (B_0, d_\beta, d_\beta)$ in the sense of [3, Definition 5.7], and by the first paragraph above the latter inequality is proper. Thus [3, Corollary 5.8] implies the lemma.

\begin{theorem}
Let $r_\beta = d_\beta/2 > 0$, where $\cosh d_\beta$ is the real root of $x^3 - 14x^2 - 15x - 4$. The Delaunay tessellation of a closed, orientable hyperbolic surface $F$ of genus 2 determined by $\{x\}$ has all edges centered if $F$ has injectivity radius $r \geq r_\beta$ at $x$. It is a triangulation unless $r = r_\beta$ and each edge has length $d_\beta$, in which case it has a single quadrilateral 2-cell.
\end{theorem}

\begin{proof}
Suppose that a genus-two surface $F$ has injectivity radius at least $r_\beta$ at a point $x$. Since $2r_\beta = d_\beta > d_1$, Corollary 7.2 implies that no 2-cell of the centered dual tessellation determined by $\{x\}$ has more than four edges.

A hyperbolic disk $U$ with radius $r_\beta$ is embedded in $F$ centered at $x$, and since $r_\beta > r_1$, the complementary area to $U$ in $F$ is less than 1.07 (see the first paragraph of the proof of Corollary 7.2). Each edge of the centered dual decomposition has length at least $d_\beta$, so if $P$ is a centered quadrilateral 2-cell of this decomposition then $P \geq P_4(d_\beta)$ in the sense of [3, Definition 5.7], and by [3, Corollary 5.8] $D_{r_\beta}(P) \geq D_{r_\beta}(P_4(d_\beta))$.

For a quadrilateral 2-cell $P$ containing a component $T$ of $V_n^{(1)}$, where $V$ is the Voronoi tessellation determined by $\{x\}$, an argument like that for Remark 7.1 implies that $T$ and its frontier $\mathcal{F}$ are as described in Lemma 7.3. The conclusion there and Lemma 5.4 thus imply that $D_{r_\beta}(P) > D_{r_\beta}(P_4(d_\beta))$ in this case.

If $r_2$ satisfies $\cosh r_2 = 2.8299$ then $r_2 > r_\beta$, so since $d_\beta > d_1$ we have $D_{r_\beta}(P_4(d_\beta)) > D_{r_\beta}(P_4(d_1)) > 0.56573$. Thus by the above the centered dual tessellation has at most one quadrilateral 2-cell, since $0.56573 \cdot 2 = 1.13146 > 1.07$ and by Proposition 4.2, $D_{r_\beta}(P)$ is the area of $P - (P \cap U)$ for each 2-cell $P$.

An Euler characteristic calculation now reveals that the centered dual tessellation of $F$ determined by $\{x\}$ consists of either six triangles or a quadrilateral and four triangles. Recall that the tessellated surface $F_\beta$ of Example 2.4 has the latter combinatorics and all edges of length $d_\beta$. By Corollary 2.11 this is the Delaunay tessellation of $F_\beta$ determined by $\{x_\beta\}$, and since each polygon is centered by construction, it is also the centered dual tessellation. Since $F_\beta$ has area $4\pi$, Proposition 4.2 thus gives:

$$D_{r_\beta}(P_4(d_\beta)) + 4 \cdot D_{r_\beta}(P_3(d_\beta)) = 4\pi - 2\pi(\cosh r_\beta - 1)$$

If the centered dual tessellation of $F$ determined by $\{x\}$ has a quadrilateral 2-cell $P$, let $T_1$, $T_2$, $T_3$, and $T_4$ be its triangular 2-cells. Remark 7.1 implies that no triangular 2-cell of the centered dual decomposition contains a component of $V_n^{(1)}$; hence each is a centered Delaunay polygon. Therefore since each edge of the centered dual tessellation has length at least $d_\beta$,
Let us make a few initial observations:

For an edge-pairing $\iota$ define \[ \mathcal{P}_\iota = \left\{ (d_0, \ldots, d_{17}) \in (\hat{\mathcal{AC}}_3)^6 \mid d_i = d_{i(\iota)} \forall i, \sum_{j=0}^5 D_0(d_{3j}, d_{3j+1}, d_{3j+2}) = 4\pi \right\} \]

For $(d_0, \ldots, d_{17}) \in \mathcal{P}_\iota$ and $j \in \{0, \ldots, 5\}$, let $T_j \subset \mathbb{H}^2$ be represented by $(d_{3j}, d_{3j+1}, d_{3j+2})$ in the sense of [3, Definition 3.1], with sides $\gamma_i$ such that $\ell(\gamma_i) = d_i$ for $i \in \{3j, 3j+1, 3j+2\}$. Let $F_i(d_0, \ldots, d_{17})$ be obtained from $\bigcup_{j=0}^5 T_j$ by isometrically identifying $\gamma_i$ with $\gamma_{i(\iota)}$ for each $i$ so that $x_{i-1} \to x_{i(\iota)}$ and $x_i \to x_{i(\iota)-1}$ for each $i \in \{3j, 3j+1, 3j+2\}$, and induce a metric on $F_i(d_0, \ldots, d_{17})$ from those on the $T_j$ (in the sense of, say, [2, Ch. I.7]).

Let us make a few initial observations:

- By the definition of $d_\alpha$ in Example 2.2, $(d_\alpha, \ldots, d_\alpha) \in \mathcal{P}_\iota$ for each edge-pairing $\iota$.
- The cellular isomorphism type of $F_i(d_0, \ldots, d_{17})$ does not depend on the choice of $(d_0, \ldots, d_{17}) \in \mathcal{P}_\iota$. We say $\iota$ is one-vertex if (say) $F_i(d_\alpha, \ldots, d_\alpha)$ has one vertex.
- For each one-vertex edge-pairing $\iota$ and $(d_0, \ldots, d_{17}) \in \mathcal{P}_\iota$, $F_\iota(d_0, \ldots, d_{17})$ is isometric to a closed, orientable hyperbolic surface of genus 2.

The final observation above follows from the fact that the triangles $T_j$ have total angle sum $2\pi$, so the single vertex of $F_i(d_0, \ldots, d_{17})$ has a neighborhood isometric to one in $\mathbb{H}^2$. We may thus take $(d_0, \ldots, d_{17}) \mapsto F_i(d_0, \ldots, d_{17})$ as defining a map $F_\iota: \mathcal{P}_\iota \to \mathcal{M}_2$. To show continuity of this map we will lift it to $\mathcal{T}_2$. 

\[ D_{r_3}(T_i) \geq D_{r_3}(P_3(d_3)) \] for each $i$ by [3, Corollary 5.8]. By the above $D_{r_3}(P) \geq D_{r_3}(P_4(d_3))$, with strict inequality if $P$ contains a component of $V^{(1)}_n$. In the latter case:

\[ D_{r_3}(P) + \sum_{i=1}^4 D_{r_3}(T_i) > 4\pi - 2\pi \cdot (\cosh r_3 - 1) \]  

But this contradicts Proposition 4.2 and the fact that $F$ has area $4\pi$. It follows that each 2-cell of the centered dual decomposition determined by $\{x\}$ is centered, and hence that this is also the Delaunay tessellation. If $F$ has injectivity radius greater than $r_3$ at $x$ then each edge of the Delaunay tessellation has length greater than $d_3$. Thus if the Delaunay tessellation had quadrilateral component $P$ in this case, we would again have the inequality (7.3.1). This is again a contradiction, and the theorem follows. \hfill \Box

8. Geometric consequences

This section describes the geometric consequences of Theorem 0.1 for hyperbolic surfaces of genus 2 that have large injectivity radius at some point. It will be convenient to work with a model space that we may regard as parametrizing the set of pairs $(F, x)$, for $F$ in $\mathcal{M}_2$ and $x \in F$, using the Delaunay tessellation determined by $\{x\}$.

**Definition 8.1.** We will say that an edge-pairing is a fixed point-free involution $\iota \in S_{18}$. For an edge-pairing $\iota$, define \[ \mathcal{P}_\iota = \left\{ (d_0, \ldots, d_{17}) \in (\hat{\mathcal{AC}}_3)^6 \mid d_i = d_{i(\iota)} \forall i, \sum_{j=0}^5 D_0(d_{3j}, d_{3j+1}, d_{3j+2}) = 4\pi \right\} \]

Let us make a few initial observations:

- By the definition of $d_\alpha$ in Example 2.2, $(d_\alpha, \ldots, d_\alpha) \in \mathcal{P}_\iota$ for each edge-pairing $\iota$.
- The cellular isomorphism type of $F_i(d_0, \ldots, d_{17})$ does not depend on the choice of $(d_0, \ldots, d_{17}) \in \mathcal{P}_\iota$. We say $\iota$ is one-vertex if (say) $F_i(d_\alpha, \ldots, d_\alpha)$ has one vertex.
- For each one-vertex edge-pairing $\iota$ and $(d_0, \ldots, d_{17}) \in \mathcal{P}_\iota$, $F_\iota(d_0, \ldots, d_{17})$ is isometric to a closed, orientable hyperbolic surface of genus 2.

The final observation above follows from the fact that the triangles $T_j$ have total angle sum $2\pi$, so the single vertex of $F_i(d_0, \ldots, d_{17})$ has a neighborhood isometric to one in $\mathbb{H}^2$. We may thus take $(d_0, \ldots, d_{17}) \mapsto F_\iota(d_0, \ldots, d_{17})$ as defining a map $F_\iota: \mathcal{P}_\iota \to \mathcal{M}_2$. To show continuity of this map we will lift it to $\mathcal{T}_2$. 

\[ D_{r_3}(T_i) \geq D_{r_3}(P_3(d_3)) \] for each $i$ by [3, Corollary 5.8]. By the above $D_{r_3}(P) \geq D_{r_3}(P_4(d_3))$, with strict inequality if $P$ contains a component of $V^{(1)}_n$. In the latter case:
Definition 8.2. For a one-vertex edge-pairing \( \iota \), fix a maximal subtree \( S \) of the one-skeleton of the abstract dual to \( F_\iota = F_\iota(d_1, \ldots, d_{17}) \), and let \( [\gamma_0], [\gamma_{i_1}], [\gamma_{i_2}], [\gamma_{i_3}] \) be the edges of \( F_\iota^{(1)} \) not dual to edges of \( S \). Further fix \( v \in \mathbb{H}^2 \) and a geodesic ray \( \delta \) from \( v \).

For \( (d_0, \ldots, d_{17}) \in \mathcal{P}_\iota \) embed \( T_0 \) in \( \mathbb{H}^2 \) with its center at \( v \) and \( x_0 = \gamma_0 \cap \gamma_1 \in \delta \), and for \( j > 0 \) embed \( T_j \) in \( \mathbb{H}^2 \) so that \( T_j \cap T_j' = \gamma_i \) for each \( i \in \{3j, 3j+1, 3j+2\} \) such that \( [\gamma_i] \subset F_\iota(d_0, \ldots, d_{17}) \) is dual to an edge of \( S \), where \( \iota(i) \in \{3j', 3j'+1, 3j'+2\} \). Let \( O = \bigcup_{j=0}^3 T_j \subset \mathbb{H}^2 \). For \( j \in \{0, 1, 2, 3\} \) let \( f_j \in \text{Isom}^+(\mathbb{H}^2) \) satisfy \( f(\gamma_{i(j)}) = \gamma_i \) and \( f(x_{i(j)}) = x_{i,j-1} \), and let \( \widetilde{F}_i(d_0, \ldots, d_{17}) = (f_0, f_1, f_2, f_3) \subset (\text{Isom}^+(\mathbb{H}^2))^4 \).

That an embedding of \( T_0 \) is prescribed by the choice of \( v \) and \( \delta \), given \( (d_0, d_1, d_2) \in \widetilde{\mathcal{AC}}_3 \), follows from [3, Proposition 4.10]. Since \( S \) is a tree the embedding of \( T_0 \) and the criteria of Definition 8.2 determine embeddings of the other \( T_j \). Then \( O = \bigcup_{j=0}^3 T_j \) is an octagon with edge set \( \{\gamma_i(\iota(j))\}_{j=0}^3 \), and the Poincaré polygon theorem implies that \( \langle f_j \rangle_{j=0}^3 \) is a discrete subgroup of \( \text{Isom}^+(\mathbb{H}^2) \) with fundamental domain \( O \) and quotient isometric to \( F_\iota(d_0, \ldots, d_{17}) \).

Fixing generators \( g_0, g_1, g_2, g_3 \) for \( \pi_1 F_\iota \), an embedding \( \text{Hom}(\pi_1 F_\iota, \text{Isom}^+(\mathbb{H}^2)) \hookrightarrow (\text{Isom}^+(\mathbb{H}^2))^4 \) is given by \( \rho \mapsto (\rho(g_0), \rho(g_1), \rho(g_2), \rho(g_3)) \). \( \mathcal{T}_2 \) inherits the algebraic topology as the subspace topology from this embedding, when it is identified with the set of discrete, faithful representations in \( \text{Hom}(\pi_1 F_\iota, \text{Isom}^+(\mathbb{H}^2)) \) (see [4, §10.3]). The paragraph above implies that \( \widetilde{F}_i(d_0, \ldots, d_{17}) \in \widetilde{\mathcal{T}}_2 \). Therefore \( (d_0, \ldots, d_{17}) \mapsto \widetilde{F}_i(d_0, \ldots, d_{17}) \) determines a map \( \widetilde{F}_i : \mathcal{P}_\iota \to \mathcal{T}_2 \). Since \( F_\iota(d_0, \ldots, d_{17}) \) is the quotient of \( \mathbb{H}^2 \) by \( \langle f_j \rangle_{j=0}^3 \), \( \widetilde{F}_i \) lifts \( F_\iota \).

Lemma 8.3. For each one-vertex edge-pairing \( \iota \), \( \widetilde{F}_i : \mathcal{P}_\iota \to \mathcal{T}_2 \) is continuous, where \( \mathcal{T}_2 \) has the algebraic topology.

Proof. It is well known that an orientation-preserving isometry of \( \mathbb{H}^2 \) is determined by its values on distinct \( x, y \in \mathbb{H}^2 \), and that the isometry so-determined varies continuously with the destinations of \( x \) and \( y \). The following claim thus implies the lemma: the vertices of the octagon \( O \) from Definition 8.2 vary continuously with \( (d_0, \ldots, d_{17}) \in \mathcal{P}_\iota \).

We will show that the vertices of each \( T_j \), embedded as prescribed in Definition 8.2, vary continuously with \( (d_0, \ldots, d_{17}) \). We use induction, outward on the tree \( S \) from its vertex corresponding to \( T_0 \). The base case follows directly from [3, Proposition 4.10], which implies that the vertices of \( T_0 \) vary continuously with \( (d_0, d_1, d_2) \).

At least one edge of \( T_0 \), say \( \gamma_0 \), is dual to an edge of \( S \). Then for \( j \) such that \( T_j \) contains \( \gamma_0(0) \), we embed \( T_j \) in \( \mathbb{H}^2 \) as prescribed in Definition 8.2 in two steps: first embed \( T_j \) with center \( v \), \( x_{i(0)} \in \delta \), and \( \gamma_{i(0)} \subset \mathcal{H} \), then move it via an isometry so that \( \gamma_{i(0)} = \gamma_0 \) and \( x_{i(0)} = x_1 \). By [3, Proposition 4.10], the vertices of the initial embedding vary continuously with \( (d_0, \ldots, d_{17}) \), so by the base case and the observation at the beginning of this proof, the vertices of the second do as well. The general inductive step is no more complicated.

Since the moduli space \( \mathcal{M}_2 \) inherits its usual topology as the quotient of a discontinuous group action on \( \mathcal{T}_2 \) (again see [4, §10.3]), Lemma 8.3 implies that \( F_\iota : \mathcal{P}_\iota \to \mathcal{M}_2 \) is continuous for each one-vertex edge-pairing \( \iota \).
Lemma 8.4. For \( r \in [\beta, \alpha] \), where \( \alpha \) is as in Example 2.2, let \( d_r = 2r \). There is a unique \( d_1(r) \in [d_r, b_0(d_r, d_r)] \), where \( b_0 \) is as in [3, Lemma 3.4], so that:

\[
4\pi = 4 \cdot D_{0,3}(d_1(r)) + 2 \cdot D_0(d_1(r), d_r, d_r)
\]

This satisfies \( d_1(r) = b_0(d_\beta, d_\beta), d_1(r_\alpha) = d_\alpha \), and \( d_1(r) \in (d_r, b_0(d_r, d_r)) \) for \( r \in (\beta, \alpha) \).

For a one-vertex edge-pairing \( \iota \) and \((d_0, \ldots, d_{17}) \in P_\iota \cap (\tilde{C}_3 \cup \tilde{BC}_3)^6 \) such that \( d_i \geq d_r \) for each \( i \), \( d_i \leq d_1(r) \) for each \( i \).

**Proof.** For each \( d \in [d_r, b_0(d_r, d_r)] \), [3, Corollary 3.11] implies that \((d, d_r, d_r) \in \tilde{C}_3 \cup \tilde{BC}_3 \). [3, Proposition 5.5] thus implies that \( D_0(d, d_r, d_r) \) increases with \( d \) on this interval, so:

\[
6 \cdot D_{0,3}(d_r) \leq 4 \cdot D_{0,3}(d_r) + 2 \cdot D_0(d, d_r, d_r) \leq 4 \cdot D_{0,3}(d_r) + 2 \cdot D_0(b_0(d_r, d_r), d_r, d_r)
\]

Since \( d_r \leq d_\alpha \), [3, Proposition 5.5] and the construction of \( d_\alpha \) (see Example 2.2) imply that \( 6 \cdot D_{0,3}(d_r) \leq 4\pi \), with equality if and only if \( d_r = d_\alpha \). As we observed in Example 2.12, for \( d_\beta \) as defined in Example 2.4, [3, Lemma 6.8] implies that \( 4 \cdot D_{0,3}(d_\beta) + 2 \cdot D_0(b_\beta, d_\beta, d_\beta) = 4\pi \), where \( b_\beta = b_0(d_\beta, d_\beta) \). Therefore since \( d_\beta \leq d_r \), [3, Proposition 5.5] gives:

\[
4\pi = 4 \cdot D_{0,3}(d_\beta) + 2 \cdot D_0(b_\beta, d_\beta, d_\beta) \leq 4 \cdot D_{0,3}(d_r) + 2 \cdot D_0(b_0(d_r, d_r), d_r, d_r),
\]

with equality if and only if \( d_r = d_\beta \). The continuity and monotonicity of \( D_0 \) imply that \( d_1(r) \) exists and is unique for each \( r \). Furthermore, by the above \( d_r < d_1(r) \) unless \( r = r_\beta \) or \( r = r_\alpha \), and \( d_1(r_\beta) = d_\beta \) and \( d_1(r_\alpha) = d_\alpha \).

For a one-vertex edge-pairing \( \iota \) and \((d_0, \ldots, d_{17}) \in P_\iota \cap (\tilde{C}_3 \cup \tilde{BC}_3)^6 \) such that \( d_i \geq d_r \) for each \( i \), [3, Corollary 5.8] implies that \( D_0(d_{3j}, d_{3j+1}, d_{3j+2}) \geq D_{0,3}(d_r) \) for each \( j \) between 0 and 5, where \( D_{0,3} \) is as in [3, Lemma 6.6]. If \( d = \max\{d_i\}_{i=0}^{17} \) then another application of [3, Corollary 5.8] gives:

\[
\sum_{i=1}^{6} D_0(T_i) \geq 4 \cdot D_{0,3}(d_r) + 2 \cdot D_0(d, d_r, d_r)
\]

To justify the “2” above, note that if \( d_i = d \) then \( d_{\iota(i)} = d \) as well, and there is no \( j \) such that \( i, \iota(i) \in \{3j, 3j + 1, 3j + 2\} \) since \( \iota \) is one-vertex. If \( d > d_1(r) \), then by construction (and [3, Corollary 5.8]) it would follow that \( \sum_{i=1}^{6} D_0(T_i) > 4\pi \), contradicting \((d_0, \ldots, d_{17}) \in P_\iota \).

**Lemma 8.5.** If \( F \in \mathcal{M}_2 \) has injectivity radius \( r \geq \beta \) at \( x \), then there is a one-vertex edge-pairing \( \iota \) and \((d_0, \ldots, d_{17}) \in P_\iota \cap (\tilde{C}_3 \cup \tilde{BC}_3)^6 \cap [d_\beta, b_0(d_\alpha, d_\alpha)]^{18} \), such that \( F \) is isometric to \( F_\iota(d_0, \ldots, d_{17}) \), taking \( x \) to its vertex.

**Proof.** For such \( F \in \mathcal{M}_2^{(r_\beta)} \) and \( x \) in \( F \), let \( P \) be the Delaunay tessellation of \( F \) determined by \( \{x\} \). By Theorem 0.1 and Lemma 3.3, each 2-cell of \( P \) is centered. If \( P \) is a triangulation then it has 2-cells \( T_0, \ldots, T_5 \). Cyclically ordering the sides of each \( T_j \) and recording their lengths,
determines a one-vertex edge-pairing \( \iota \) and \((d_0, \ldots, d_{17}) \in \mathcal{P}_i\) with \( F = F_i(d_0, \ldots, d_{17}) \) and \((d_{3j}, d_{3j+1}, d_{3j+2}) \in \tilde{C}_3\) for each \( j \).

If \( P \) has a quadrilateral 2-cell \( O \), a diagonal of \( O \) divides it into two cyclic triangles. Then making choices as above yields \( \iota \) and \((d_0, \ldots, d_{17}) \) with \( F = F_i(d_0, \ldots, d_{17}) \). In this case, however, for each \( j \) corresponding to a triangle in \( O \) the corresponding triple \((d_{3j}, d_{3j+1}, d_{3j+2})\) is in \( \tilde{BC}_3 \).

For each \( i, \ d_i \geq d_\beta = 2r_\beta \) since it is an edge length of \( P \), so Lemma 8.4 implies that \( d_i \leq d_i(r) \leq b_0(d_r, d_r) \) for each \( i \). Furthermore, \( b_0(d_r, d_r) \leq b_0(d_\alpha, d_\alpha) \) by [3, Lemma 3.4], since \( d_r \leq d_\alpha \) by Lemma 2.3. □

**Lemma 8.6.** For each one-vertex edge-pairing \( \iota \) and \((d_0, \ldots, d_{17}) \in \mathcal{P}_i \cap (\tilde{C} \cup \tilde{BC}_3)^6, F = F_i(d_0, \ldots, d_{17}) \) has injectivity radius \( r = \min\{\nicefrac{d_i}{2}\}_{i=0}^{17} \) at its vertex \( x \).

**Proof.** We argue as in Examples 2.2 and 2.4, using [3, Lemma 5.3]. Of course \( F \) has injectivity radius at most \( r \) at \( x \). Since each \((d_{3j}, d_{3j+1}, d_{3j+2}) \in \tilde{C}_3 \cup \tilde{BC}_3\) for each \( j \), each \( T_j \) contains the entire sector that it determines in a disk with radius \( r \) centered at any of its vertices. Since the \( T_j \) have total angle measure \( 2\pi \), a disk with radius \( r \) is embedded in \( F \), centered at \( x \). □

**Corollary 8.7.** \( M_2^{(r_\beta)} \) is compact.

**Proof.** Lemmas 8.5 and 8.6 together imply that \( M_2^{(r_\beta)} \) is the union, taken over the finite collection of one-vertex edge-pairings \( \iota \), of the image of \( \mathcal{P}_i \cap (\tilde{C} \cup \tilde{BC}_3)^6 \cap [d_\beta, b_0(d_\alpha, d_\alpha)] \) under \( F_i \). Each such \( F_i \) is continuous by Lemma 8.3. \( \tilde{C}_3 \cup \tilde{BC}_3 \) is closed in \( \mathbb{R}^+ \) by [3, Lemma 3.3] and [3, Lemma 3.4], so since \( d_\beta > 0 \) its intersection with \([d_\beta, b_0(d_\alpha, d_\alpha)]\) is compact. The Corollary follows. □

**Definition 8.8.** Say the covering radius of \( \mathcal{S} \subset \mathbb{H}^2 \) is inf \( \{r \leq \infty | \mathbb{H}^2 \subset \bigcup_{x \in \mathcal{S}} B_r(x)\} \).

**Lemma 8.9.** Let \( F \) be a closed surface with universal cover \( p: \mathbb{H}^2 \to F \), fix \( \mathcal{S} \subset F \) finite, and let \( V \) be the Voronoi tessellation of \( F \) determined by \( \mathcal{S} \). Then \( \tilde{\mathcal{S}} \equiv p^{-1}(\mathcal{S}) \) has covering radius equal to \( \max \{J_v | v \in V^{(0)}\} \), where \( J_v \) is as in Lemma 1.2.

**Proof.** It is clear that the covering radius of \( \tilde{\mathcal{S}} \) is at least the quantity above, since for any \( v \in V^{(0)} \), \( d(x, v) \geq J_p(v) \) for each \( x \in \tilde{\mathcal{S}} \), where \( \tilde{V} = p^{-1}(V) \). We will prove equality by showing that \( P_v \subset \bigcup_{i=0}^{n-1} \overline{B}_{J_p(v)}(x_i) \) for each such \( v \), where \( P_v \) as in Lemma 1.9 has vertex set \( \{x_i\}_{i=0}^{n-1} \), and \( \overline{B}_r(x) \) is the closed ball of radius \( r \) about \( x \).

Let us assume that the \( \{x_i\} \) are cyclically ordered in the sense of Definition 1.5, and for each \( i \) let \( \gamma_i \) be the side of \( P_v \) bounded by \( x_{i-1} \) and \( x_i \) (with \( i - 1 \) taken modulo \( n \)). Since each endpoint of \( \gamma_i \) lies on a circle with radius \( J_p(v) \), \( f(\gamma_i) \leq 2J_p(v) \). Therefore the midpoint \( m_i \) of \( \gamma_i \) is in \( \overline{B}_{J_p(v)}(x_{i-1}) \cap \overline{B}_{J_p(v)}(x_i) \).

Since the convex set \( \overline{B}_{J_p(v)}(x_i) \) contains \( x_i, m_i, \) and \( v \), it contains the right triangle in \( \mathbb{H}^2 \) that they determine. Similarly, \( \overline{B}_{J_p(v)}(x_{i-1}) \) contains the triangle determined by \( x_{i-1}, m_i, \) and \( v \).
The union of these triangles is \( T_i \) as defined in [3, Lemma 1.6], so \( T_i \subset \mathcal{B}_{p(v)}(x_{i-1}) \cup \mathcal{B}_{p(v)}(x_i) \). Since this holds for each \( i \), [3, Lemma 1.6] implies that \( P_v \subset \bigcup_{i=0}^{n-1} \mathcal{B}_{p(v)}(x_i) \). 

For a surface \( F \) with universal cover \( \mathbb{H}^2 \to F \) and \( x \in F \), it is clear that the covering radius of \( F \) at \( x \) (as defined below Theorem 0.2) is equal to the covering radius of \( \tilde{S} \equiv p^{-1}(x) \).

**Definition 8.10.** For a one-vertex edge-pairing \( \iota \), say \((d_0, \ldots, d_{17}) \in \mathcal{P}_\iota \) is exceptional if \( d_i = d_\beta \) for all but two \( i \in \{0, \ldots, 17\} \). (In this case \( d_{i_0} = d_{\iota(i_0)} = b_0(d_\beta, d_\beta) \) for some \( i_0 \).

**Lemma 8.11.** For a one-vertex edge-pairing \( \iota \), if \((d_0, \ldots, d_{17}) \in \mathcal{P}_\iota \) is exceptional there exists \( i_0 \) such that \( d_{i_0} = d_{\iota(i_0)} = b_0(d_\beta, d_\beta) \). For \( j_0 \) with \( i_0 \in \{3j_0, 3j_0 + 1, 3j_0 + 2\} \) and \( j_1 \) with \( \iota(i_0) \in \{3j_1, 3j_1 + 1, 3j_1 + 2\} \), \( T_{j_0} \cup T_{j_1} \) is a 2-cell of the Delaunay tessellation \( P_\iota \) of \( F_\iota(d_0, \ldots, d_{17}) \) determined by \( \{x\} \), where \( x \) is the vertex. For \( j \neq j_0, j_1 \), \( T_j \) is a 2-cell of \( P_\iota \).

**Proof.** [3, Proposition 5.5] implies that \( x \mapsto D_0(x, d_\beta, d_\beta) \) achieves a unique maximum at \( x = b_0(d_\beta, d_\beta) \). Since \( 4 \cdot D_0(d_\beta) + 2 \cdot D_0(b_0(d_\beta, d_\beta)) = 4\pi \) by construction (see Example 2.12), it follows by definition of \( \mathcal{P}_\iota \) that if \((d_0, \ldots, d_{n-1}) \in \mathcal{P}_\iota \) is exceptional it must have two entries equal to \( b_0(d_\beta, d_\beta) \). That they are exchanged by \( \iota \) also follows by definition.

Note that \( j_0 \) and \( j_1 \) defined above are distinct, since \( \iota \) is one-vertex. [3, Lemma 3.9] implies that \( T_{j_0} \) has its center in \( \gamma_{i_0} \), and \( T_{j_1} \) has its in \( \gamma_{\iota(i_0)} \), so their union is a centered quadrilateral with all edges of length \( d_\beta \). Corollary 2.9 thus implies that \( T_{j_0} \cup T_{j_1} \) is a 2-cell of \( P_\iota \). It implies the same for \( T_j \), \( j \neq j_0, j_1 \).

**Lemma 8.12.** For each one-vertex edge-pairing \( \iota \) and non-exceptional \((d_0, \ldots, d_{17}) \in \mathcal{P}_\iota \cap (\tilde{C}_3 \cup \tilde{\mathcal{B}C}_3)^6 \cap [d_\beta, b_0(d_\alpha, d_\alpha)]^{18} \), each \( T_j \) from Definition 8.1 is a 2-cell of the Delaunay tessellation of \( F_\iota(d_0, \ldots, d_{17}) \) determined by \( \{x\} \) where \( x \) is the vertex.

**Proof.** By Lemma 8.6, \( F \equiv F_\iota(d_0, \ldots, d_{17}) \) has injectivity radius \( r = \min\{d_i/2\} \) at its vertex \( x \). By hypothesis \( d_r = 2r = \min\{d_i\} \) at least \( d_\beta \), so Lemma 8.4 implies that \( d_i \leq d_1(r) \leq b_0(d_r, d_r) \) for each \( i \). If \( d_{i_0} = b_0(d_r, d_r) \) for some \( i_0 \), we claim that \((d_0, \ldots, d_{17}) \) is exceptional.

If \( d_{i_0} = b_0(d_r, d_r) \) for some \( i_0 \) then in particular \( d_1(r) = b_0(d_r, d_r) \), so \( r = r_\beta \) by Lemma 8.4. Fix \( j_0 \) such that \( i_0 \in \{3j_0, 3j_0 + 1, 3j_0 + 2\} \). Since \( \iota \) is one-vertex, \( j_0 \neq j'_0 \) such that \( \iota(i_0) \in \{3j'_0, 3j'_0 + 1, 3j'_0 + 2\} \). Applying [3, Corollary 5.8], we have:

\[
\sum_{j=0}^{5} D_0(3j, 3j + 1, 3j + 2) \geq 4 \cdot D_0(d_\beta) + D_0(b_0(d_\beta, d_\beta)) = 4\pi
\]

The latter equality is by construction (see Example 2.4). If there were \( i \notin \{i_0, \iota(i_0)\} \) with \( d_i > d_\beta \) then by [3, Corollary 5.8] the above inequality would be strict, contradicting \((d_0, \ldots, d_{17}) \in \mathcal{P}_\iota \). The claim follows.

For non-exceptional \((d_0, \ldots, d_{17}) \in \mathcal{P}_\iota \), the claim implies that \( d_i < b_0(d_r, d_r) \) for each \( i \). Thus \((d_{3j}, d_{3j+1}, d_{3j+2}) \in \tilde{C}_3 \) for each \( j \), since for instance \( d_{3j} < b_0(d_r, d_r) \leq b_0(d_{3j+1}, d_{3j+2}) \) (the latter inequality follows from [3, Lemma 3.4]). Since \( B_0 = b_0(d_r, d_r) \) satisfies \( \cosh B_0 = \)
For each one-vertex edge-pairing \( \ell \) define \( J_\ell : \mathcal{P}_\ell \to \mathbb{R}^+ \) by \( J_\ell (d_0, \ldots, d_{17}) = \max \{ J(d_{3j}, d_{3j+1}, d_{3j+2}) \}_{j=0}^5 \), where \( J \) is as in [3, Lemma 3.6]. For \( (d_0, \ldots, d_{17}) \in \mathcal{P}_\ell \cap (\tilde{C} \cup \tilde{B}\mathbb{C}_3)^6 \cap [d_\beta, b_0(d_\alpha, d_\alpha)^{18}, F_i(d_0, \ldots, d_{17}) \) has covering radius \( J_\ell (d_0, \ldots, d_{17}) \) at its vertex \( x \).

**Proof.** For non-exceptional \( (d_0, \ldots, d_{17}) \in \mathcal{P}_\ell \cap (\tilde{C} \cup \tilde{B}\mathbb{C}_3)^6 \cap [d_\beta, b_0(d_\alpha, d_\alpha)^{18}, \) let \( r = \min \{ d_i/2 \} \). If for each \( i, d_i < d_1(r), \) as defined in Lemma 8.4, then \( (d_0, \ldots, d_{n-1}) \) deforms preserving \( \min \{ d_i \}_{i=0}^{17} \) but increasing \( J_\ell (d_0, \ldots, d_{17}) \).

**Lemma 8.14.** For a one-vertex edge-pairing \( \ell \) and \( (d_0, \ldots, d_{17}) \in \mathcal{P}_\ell \cap (\tilde{C} \cup \tilde{B}\mathbb{C}_3)^6 \cap [d_\beta, b_0(d_\alpha, d_\alpha)^{18}, \) then \( \sum_{j=0}^5 D_0(d_{3j}, d_{3j+1}, d_{3j+2}) = 4 \cdot D_0(d_3, d_4) + 2 \cdot D_0(d_1, d_1, d_1) < 4\pi \)

This would contradict \( (d_0, \ldots, d_{17}) \in \mathcal{P}_\ell \). Fix \( j_0 \) with \( i_0 \in \{ 3j_0, 3j_0 + 1, 3j_0 + 2 \} \) and \( j'_0 \) with \( \ell(i_0) \in \{ 3j'_0, 3j'_0 + 1, 3j'_0 + 2 \} \), and note as above that \( j_0 \neq j'_0 \). We will deform \( (d_0, \ldots, d_{n-1}) \) changing only \( d_{i_0} = d_{i(i_0)} \) and \( d_{i_1} = d_{i(i_1)} \).

Suppose first that \( \{ j_1, j'_1 \} = \{ j_0, j'_0 \} \). (In this case \( T_{j_1} \) and \( T_{j'_1} \) share edges corresponding to \( \gamma_{i_1} \) and \( \gamma_{i_0} \) in \( F_i(d_0, \ldots, d_{17}) \).) Let \( d' \) be the element of \( \{ d_{3j_1}, d_{3j_1+1}, d_{3j_1+2} \} \) not equal to \( d_{i_1} \) or \( d_{i_0} \), and let \( d'' \) be the corresponding element of \( \{ d_{3j'_1}, d_{3j'_1+1}, d_{3j'_1+2} \} \). For small \( t \geq 0 \), we will take \( d_{i_1}(t) = d_{i(i_1)}(t) = d_{i_1} + t \) and choose \( d_{i_0}(t) = d_{i(i_0)}(t) \) so that \( D_0(d_{i_1} + t, d_{i_0}(t), d') + D_0(d_{i_1} + t, d_{i_0}(t), d'') \) is constant. By [3, Proposition 5.5], \( d_{i_0}(t) \) must satisfy:

\[
\frac{d}{dt}(d_{i_0}(t)) = -\sqrt{\frac{1}{\cosh^2(d_{i_0}(t)/2)} - \frac{1}{\cosh^2 J_1(t)}} + \sqrt{\frac{1}{\cosh^2(d_{i_0}(t)/2)} - \frac{1}{\cosh^2 J'_1(t)}}
\]

Above \( J_1(t) = J(d_{i_1} + t, d_{i_0}(t), d') \) and \( J'_1(t) = J(d_{i_1} + t, d_{i_0}(t), d'') \). The existence theorem for ordinary differential equations implies that a unique differentiable function \( d_{i_0}(t) \), defined on \([0, \epsilon)\) for some \( \epsilon > 0 \), satisfies the equation above. Using this equation we find that \( d_{i_0}(t) \) decreases in \( t \), and also that \( |d_{i_0}(t)| < 1 \), since it follows that \( d_{i_0}(t) < d_{i_1} + t \) for all \( t \in [0, \epsilon) \).

Since \( d_{i_0}(t) < d_{i_1} + t \) for all \( t > 0 \), [3, Lemma 4.5] implies that \( \left| \frac{\partial J_1}{\partial d_{i_0}(t)} \right| < \left| \frac{\partial J}{\partial (d_{i_1} + t)} \right| \), and since \( |d'_{i_0}(t)| < 1 \) the chain rule implies that \( J_1(t) \), and hence also \( J_\ell \), increases with \( t \) in this case.
There are three other possibilities for \{j_1, j'_1, j_0, j'_0\}: one in which all four of its elements are distinct and two in which it has only three distinct elements (we do not distinguish the case \(j_1 = j_0\) from \(j_1 = j'_0\), or \(j'_1 = j_0\) from \(j'_1 = j'_0\)). In each case we change each element of this set by increasing \(d_i\) and decreasing \(d_{i_0}\), leaving all other entries constant while keeping the defect sum unchanged.

As long as \(i_0 \notin \{3j_1, 3j_1 + 1, 3j_1 + 2\}\) (equivalently, \(j_1 \notin \{j_0, j'_0\}\)) it is clear by [3, Lemma 4.5] that \(J_t\) increases with \(t\), so it only remains to consider the case that \(j_1 = j'_0\) but \(j'_1 \neq j_0\). Taking \(d_{i_1}(t) = d_{i_1} + t\), in this case \(d_{i_0}(t)\) must satisfy the following differential equation:

\[
\frac{d}{dt} (d_{i_0}(t)) = -\frac{1}{\cosh^4(d_{i_1}(t)/2)} - \frac{1}{\cosh^2 J(t)} + \frac{1}{\cosh^4((d_{i_1} + t)/2)} - \frac{1}{\cosh^2 J(t)}
\]

Here \(J(t) = J(d_{i_0}(t), d_{i_1} + t, d')\), \(J'_1(t) = J(d_{i_1} + t, d_{3j'_1 + 1}, d_{3j'_1 + 2})\) (assuming for simplicity that \(\iota(i_1) = 3j'_1\)), and \(J_0(t) = J(d_{i_0}(t), d_{3j_0 + 1}, d_{3j_0 + 2})\) (assuming that \(i_0 = 3j_0\)). We may assume that all entries not in \{\(d_{3j_1}, d_{3j_1 + 1}, d_{3j_1 + 2}\)\} equal \(d_r\), since otherwise replacing \(d_{i_0}\) by an entry not in the set above allows appeal to another case. Thus in this case \(J_0(t) = J(d_{i_0}(t), d_r, d_r)\) and \(J'_1(t) = J(d_{i_1} + t, d_r, d_r)\).

Unlike the first case we considered, it is not immediately obvious here that \(|d'_{i_0}(t)| < 1|:\) the problem is that the defect derivative function \(\sqrt{\frac{1}{\cosh^4(d_{i_0}(t)/2)} - \frac{1}{\cosh^2 J(t)}}\) decreases in \(d\) but increases in \(J\), and [3, Lemma 4.5] implies that \(J_0(t) < J_1(t)\). However we have the following:

**Claim 8.14.1.** For fixed \(d > 0\) and \(x\) such that \((x, d, d) \in C_3\), the function

\[
x \mapsto \frac{1}{\cosh^2(x/2)} - \frac{1}{\cosh^2 J(x, d, d)}
\]

decreases in \(x\).

**Proof of claim.** Simplifying the formula of [3, Lemma 6.1] gives:

\[
\sinh J(x) = \frac{2\sinh^2(d/2)}{\sqrt{4\sinh^2(d/2) - \sinh^2(x/2)}}
\]

Let us take \(X = \cosh^2(x/2)\) and \(D = \cosh^2(d/2)\). Inserting the formula above into the function in question, after some more simplification we obtain:

\[
\frac{1}{X} - \frac{1}{\cosh^2 J(x, d, d)} = \frac{[2D - 1 - X]^2}{X([2D - 1 - X]^2 - X)} = \left[\frac{2D - 1}{X} - 1\right] \left[1 - \frac{2(D - 1)(2D - 1)}{(2D - 1)^2 - X}\right]
\]

By [3, Lemma 6.2], \((x, d, d) \in C_3\) if and only if \(X < 2D - 1\), thus for such \(x\) the functions in brackets on the right-hand side are positive-valued. Since they also clearly decrease with \(X\), their product is decreasing. Since \(X\) increases with \(x\), the claim is proved. \(\square\)

Since \(d_{i_0}(t) < d_{i_1} + t\), the claim implies that \(|d'_{i_0}(t)| < 1|\), so as in the first case considered it follows that \(J(d_{i_0}(t), d_{i_1} + t, d')\), and hence also \(J_t\) increases with \(t\). In each case above we have thus produced deformations through \(\mathcal{P}_t\) so that no entries change but \(d_{i_0} = d_{i(t_0)}\) and
Theorem 0.2. For each $r \in [r_\beta, r_\alpha]$ and one-vertex edge-pairing $\iota$, $J_\iota$ is a continuous function on $P_r$, being the maximum of functions which are themselves continuous by [3, Proposition 4.1]. Hence it attains a maximum on the following compact subset:

$$\bigcup_{j=0}^{17} P_\iota \cap (\tilde{C}_3 \cup \tilde{B}C_3)^6 \cap \left( \{d_r, b_0(d_r, d_r)\}^j \times \{d_r\} \times \{d_r, b_0(d_r, d_r)\}^{17-j} \right)$$

By Lemma 8.6, this consists of those $(d_0, \ldots, d_{17}) \in P_\iota \cap (\tilde{C}_3 \cup \tilde{B}C_3)^6$ such that $F_\iota(d_0, \ldots, d_{17})$ has injectivity radius $r$ at its vertex $F$. Lemma 8.14 implies that $J_\iota$ attains its maximum at such a point as described in Lemma 8.15, and the maximum is as described there. Since $d_1(r) \leq b_0(d_r, d_r)$ by Lemma 8.4, and $B_0 = b_0(d_r, d_r)$ satisfies $\sinh(B_0/2) = \sqrt{2}\sinh r$ by [3, Lemma 6.1], a simplification gives $\sinh J_\iota(d_0, \ldots, d_{17}) \leq \sqrt{2}\sinh r$ for each $(d_0, \ldots, d_{17})$ in the set above. The result now follows directly from Lemma 8.5 and Corollary 8.13.

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