DYNAMICAL RANDOM WALK ON THE INTEGERS WITH A DRIFT

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ABSTRACT. We consider a particle which performs a dynamical random walk on \( \mathbb{Z} \) and whose local dynamics is given by expanding maps. We provide sufficient conditions for the position of the particle \( z_n \) to satisfy the Central Limit Theorem.

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1. Introduction

1.1. Motivation. Understanding transport in an inhomogeneous media is one of the classical problems in mathematical physics. The motion in homogeneous media is well understood and is described by the heat equation whose fundamental solution is given by the transition density of the Brownian Motion. The situation in the inhomogeneous case is more complicated.

One of the simplest models of inhomogeneous transport is given by random walks in random environment. In this model the particle moves on the lattice $\mathbb{Z}^d$ so that if the particle is in position $z$ it moves to $z + v$ for $v$ in a finite set $\Lambda$ with probability $p(z,v)$ where the vectors $\{p(z,\cdot)\}_{z \in \mathbb{Z}^d}$ are iid. This model is completely understood in dimension 1 while in higher dimensions only partial results are available. In the one dimensional setting the recurrent motion leads to Sinai behavior [39], where the particle at time $t$ is typically at the distance $O(\ln^2 t)$ from the origin. In the transient case a wide range of behaviors is possible [25]. In particular the transient walk can have either positive or zero speed ([40]). In the case of positive speed the fluctuations around the linear motion could be either Gaussian or described by stable laws of index $1 \leq s < 2$. In the case of zero speed the limit distributions are Mittag–Leffler (the results of [25, 39, 40] pertain to the nearest neighbor walks, we refer the readers to [7, 8, 15, 16, 21] for the extensions to the walks with bounded jumps). In contrast if the dimension is greater than 1, then the walk is expected to satisfy the Central Limit Theorem (at least, if the dimension is high enough). However, so far it has been proven only for systems satisfying some additional assumptions such as reversibility ([38, 5]), a sufficiently strong drift (see [43, 44, 4] and references therein) or a perturbative regime ([45]).

The progress in understanding of random walks in random environment naturally leads to a question about extending the results proven for that model to a more realistic systems. One particularly interesting question is to understand a deterministic motion in random environment. In particular, a number of papers concern Lorentz gas in random environment–a system, where a particle moves freely on a plane colliding elastically with a random array of convex scatterers ([1, 13, 14, 33, 46]). While the works above establish recurrence and the Law of Large Numbers for different models of random Lorentz gas, the limit theorems are currently unknown.

In order to obtain a more tractable model of deterministic motion in random environment, in [1] the authors proposed a model of Deterministic Walks in Random Environment (DWRE). By this one means a map $F$ defined on $M \times \mathbb{Z}^d$ where $M$ is the internal state of the walker. Namely, suppose that for each $n \in \mathbb{Z}^d$ we have a map $T_n : M \to M$ and a partition $M = \bigcup_v W_{v,n}$ (gate partition) where $v \in \{0, \pm e_1, \cdots \pm e_d\}$. Let

$$F(x,n) = \left(T_n x, n + \sum_v 1_{W_{v,n}} v \right).$$

Thus if the particle is at site $n$ then its internal state changes according to $T_n$, while the change of the location is prescribed by the gates.
One is then interested in statistical properties of \( z_n(x) = \pi_{Z^d}(F^n(x,0)) \). The randomness in the system comes from the random choice of the initial internal state \( x_0 \in M \).

In [1] the authors provide conditions under which \( z_n \) satisfies the law of large numbers. They show that their conditions are satisfied for a dynamical random walk whose local dynamics is given by a sufficiently expanding interval map, such as \( \beta \) transformations with large \( \beta \).

[1] show that the random Lorenz gas fits into the framework of DWRE. Moreover the class of DWRE contains several classical examples of random motion. As an example, consider the following system: let \( d = 1, M = \mathbb{T}^1 \), \( T_n(x) = 2x \) (mod 1) and \( W_{n,-1} = [0, \frac{1}{2}), W_{n,1} = [\frac{1}{2}, 1) \) for all \( n \in \mathbb{Z} \). One can see that if we choose the initial internal state uniformly on \( T \) then the DWRE defined this way is equivalent to the simple symmetric random walk on \( Z \). More generally it is shown in [1] that DWRE with linear expanding local dynamics and Markov gates can model random walks in random environment (RWRE). In particular, all types of behavior observed in RWRE, appear also in DWRE, so the particle can be transient with zero speed ([40]) or it can exhibit Sinai behavior ([39]). However, Markov condition on the gates is pretty restrictive, so it is of interest to develop tools to handle non Markovian dynamics.

The goal of the present article is to develop a robust method for proving CLT for one dimensional systems with strong drift (note that some assumptions on the system are necessary to get the CLT due to the non-Gaussian examples of [1]). Our approach has two types of ingredients: probabilistic and dynamical. The dynamical ingredient is the CLT theory for the composition of ladder maps \( G_n \). \( G_n \) describes the internal state of the particle starting at the level \( n \) when it arrives at level \( n + 1 \) for the first time. This part relies on the theory of sequential dynamical systems. The probabilistic ingredients consist of renewal theory which allows to pass from the CLT for hitting times to the CLT for the particle position and on the CLT for the quenched drift, which uses the central limit theory for weakly dependent random variables.

In order to describe the main ideas of our approach in the simplest possible settings we present two models. Model A is strongly ballistic. Namely among any three steps, at least two are to the right. In this case the dynamical part uses the CLT for bounded observables of sequential expanding maps available in the literature ([9]). Model B is more realistic, since the particle could move arbitrary far to the left, albeit with a small probability. In this case the dynamical part needs to be extended as well leading to more complicated arguments.

In a future work we plan to apply our method to Lorentz gas in the presence of random field. In this case the local dynamics and, hence, the ladder maps \( G_n \) are hyperbolic rather than expanding which requires a significant improvement of the existing dynamical results. Therefore this model will be a subject of a separate paper.

We note that our work is the first example, where the CLT is proven for an open class of deterministic systems in random environment as time tends to infinity (the results of [1] could be used to obtain examples of DRWE satisfying the CLT, however, the parameters need to be tuned very carefully to obtain the equivalence with RWRE). Before describing precisely our models (which will be done in §1.2) we mention the previous work where the CLT is obtained for the deterministic motion in random environment.
environment. We note that in the models described below the environment depends on an additional parameter $\varepsilon$ and the time scales as some power of $1/\varepsilon$, while in our work the environment is fixed and time tends to infinity.

The first model deals with a particle moving in a dilute random media (so called Boltzmann-Grad regime) where the time tends to zero and the sizes of the scatters go to zero at the same time. A selection of papers on this subject includes [6, 41, 42, 35]. While this topic is of great physical relevance, it is beyond the scope of the present work. We just mention that since the interactions happen rarely, it is easier to make use of the mixing properties of the environment.

Another problem dealing with deterministic motion in the random media is equations with rapidly oscillating coefficients. The study of the equation $\dot{x} = v(x, \xi_{t/\varepsilon})$, where $\xi_t$ is a rapidly mixing random process and $\varepsilon > 0$ is a small parameter, goes back to the work of Khasminskii ([28, 29]). Note that this system is non-autonomous but it can be converted to an autonomous form by rewriting it as

$$\dot{x} = v(x, \xi_{s/\varepsilon}), \quad \dot{s} = 1.$$ 

Khasminskii shows that the solutions of this equations are close to the solutions of the averaged equation $\dot{x} = \bar{v}(\bar{x})$ where $\bar{v}(\bar{x}) = \mathbb{E}(v(\bar{x}, \xi))$ and obtains the CLT for the fluctuations. More generally, the results similar to [28, 29] can be obtained for the systems in the form $\dot{x} = v(x/\varepsilon)$ where $v : \mathbb{R}^d \to \mathbb{R}^d$ is a rapidly mixing process and $v_d > \delta$ for some $\delta > 0$. (In this case $x_d$ plays the role of time), see [26]. Similar results are also available for the the second order equations with rapidly oscillating coefficients, see [27, 31, 32, 17] and references wherein.

A third subject is the billiard models where the reflections from the boundary are random to model microscopic roughness of the walls (see [10, 11, 12, 19]). While limit theorems are available for the random model, the derivation of the same laws from the underlying microscopic dynamics remains a challenging open problem.

1.2. Results. We consider a model of DRW defined by (1.1) where $d = 1$, $M = \mathbb{T}$ and $T_n : \mathbb{T} \to \mathbb{T}$ are smooth uniformly expanding maps. We will also assume that the particle’s coordinate changes every time, thus $\mathbb{T} = W_{n,-1} \cup W_{n,1}$. We consider the following models.

Model A. Let $\bar{T}$ be an expanding map and let $3 < \gamma \leq K$ and $K_1 > 0$ be constants, such that for all $n$ and all $x \in \mathbb{T}$ we have

$$\gamma \leq |\bar{T}'_n(x)| \leq K, \quad \sup_{x \in \mathbb{T}} |\bar{T}''_n(x)| \leq K_1. \tag{1.2}$$

Let $\bar{W} \subset \mathbb{T}$ be a segment such that

$$\bar{T}^p\bar{W} \cap \bar{W} = \emptyset \quad \text{for} \quad p = 1, 2. \tag{1.3}$$

We also suppose that for a sufficiently small $\delta_0$ we have that for all $n \|T_n - \bar{T}\|_{C^2(\mathbb{T})} \leq \delta_0$ and the Hausdorff distance between $W_{n,-1}$ and $\bar{W}$ is smaller than $\delta_0$.

Note that the condition $\bar{T}^p\bar{W} \cap \bar{W} = \emptyset$ for $p = 1, 2$, is a ballisticity condition ensuring that among every three moves of the particle at least two are to the right. Thus the particle moves to the right ballistically. Namely $z_n \geq n/3$ and $z_n \geq z_m - 1$ for $n > m$. 
**Model B.** Let $a$ be a large integer. Let $\bar{T}(x) = ax \pmod{1}$ and $\bar{W}_{-1} \subset \mathbb{T}$ be a segment with $|\bar{W}_{-1}| < \frac{1}{2}$. We suppose that for a sufficiently small $\delta_0$ and for all $n \in \mathbb{Z}$, $\|T_n - T\|_{C^2(\mathbb{T})} \leq \delta_0$ and the Hausdorff distance between $W_{n-1}$ and $\bar{W}$ is smaller than $\delta_0$.

Thus in this model the local dynamics enjoys a strong expansion, which makes this model similar to the one considered in [1]. (Note that in Model B the local dynamics is smooth while [1] consider $\beta$ transformations which have discontinuity on the circle. We believe that the method of our paper can be extended to maps with a finite number of discontinuities provided that slope is sufficiently large (depending on the number of discontinuity points) but to keep the presentation simple we restrict our attention to smooth maps.)

Our first result is the CLT for the hitting time. Namely let $\tau_n(x, k)$ be the smallest time $t$ such that $F^t(x, k) \in \mathbb{T} \times \{n\}$. Define the maps $G_n : \mathbb{T} \to \mathbb{T}$ by

$$G_n(x) = \pi_T F^{r_n(x)}(x, n)$$

where $r_n(x) = \tau_{n+1}(x, n)$ and $\pi_T$ denotes the projection on the first coordinate. Thus $G_n(x)$ describes the internal state of the walker, which starts at site $n$ with internal state $x$, at the first time when the walker reaches site $n + 1$. We shall also write $\tau_n(x) := \tau_n(x, 0)$. Note that for $n = 1$ we have

$$\tau_1(x) = r_0(x)$$

and for $n > 1$

$$\tau_n(x) = \sum_{k=0}^{n-1} r_k(G_{k-1} \circ \cdots \circ G_0 x).$$

Under the assumptions of Model A note that

$$\bar{T}^p \bar{W} \cap \bar{W} = \emptyset$$

for $p = 1, 2$. Recall that $T_n = \bar{T} + h_n$, where $h_n \in C^2(\mathbb{T})$, $\|h_n\|_{C^2} < \delta_0$ and $|\bar{W} \Delta W_n| < \delta_0$. By [1,3], for $\delta_0$ sufficiently small we will have

$$T_n(W_n) \cap W_{n-1} = \emptyset, \quad T_{n-1}(T_n(W_n)) \cap W_n = \emptyset.$$ 

This implies that

$$G_n(x) = \begin{cases} T_n(T_{n-1}(T_n(x))) & \text{if } x \in W_n, \\ T_n(x) & \text{if } x \in \mathbb{T} \setminus W_n. \end{cases}$$

Hence the hitting times are

$$r_n(x) = \begin{cases} 3 & \text{if } x \in W_n, \\ 1 & \text{for } x \in \mathbb{T} \setminus W_n. \end{cases}$$

Let $\bar{r}$ and $\bar{G}$ respectively be

$$\bar{r}(x) = \begin{cases} 3 & \text{if } x \in \bar{W}, \\ 1 & \text{if } x \in \mathbb{T} \setminus \bar{W}; \end{cases} \quad \bar{G}(x) = \begin{cases} \bar{T}(\bar{T}(\bar{T}(x))) & \text{if } x \in \bar{W}, \\ \bar{T}(x) & \text{if } x \notin \bar{W}. \end{cases}$$

In contrast the hitting time in Model B is unbounded and the map $G_n$ has infinitely many branches (in fact, it is a non-trivial fact that $G_n(x)$ is defined for almost every
We say that the DRW satisfies the CLT for hitting times if
\[ \frac{\tau_n - \mathbb{E}(\tau_n)}{\sqrt{\text{Var}(\tau_n)}} \Rightarrow \mathcal{N}(0,1) \text{ as } n \to \infty \]
where \( \mathcal{N}(a, \sigma^2) \) denotes the normal distribution with mean \( a \) and standard deviation \( \sigma \). Here and elsewhere in this article we assume (unless it is explicitly stated otherwise) that \( x \) is uniformly distributed on \( T \).

**Theorem 1.1.**

(a) Given \( \bar{T} \) there exist \( \bar{\delta}_0 \) such that if \( \delta_0 \leq \bar{\delta}_0 \) then the DRW from model A satisfies the CLT for hitting times.

(b) Assume that in model B, \( |\bar{W} - 1| < \frac{1}{2} \). Then there exists \( a_0 \in \mathbb{N} \) so that for all \( a \geq a_0 \), there exists \( \bar{\delta}(a) \) so that if \( \delta \leq \bar{\delta}(a) \) then the maps \( \{G_n\}_{n \in \mathbb{Z}} \) are well defined and the DRW satisfies the CLT for hitting times.

**Remark 1.2.** We can assume that in Model B \( |\bar{W} - 1| < \frac{1}{2} \) without loss of generality. Otherwise, we will switch \( \bar{W} - 1 \) with \( \bar{W}_1 \).

In order to obtain some information about the position of the particle \( z_n \) we need to choose the maps and the gates in an iid way.

Let \( \mathcal{E} = \{(T_1, W_1), \ldots, (T_m, W_m)\} \) be a collection of maps and gates, so that any sequence \( (T_n, W_{n-1})_{n \in \mathbb{Z}} \), with \( (T_n, W_n) \in \mathcal{E} \), \( \forall n \in \mathbb{Z} \), satisfies the conditions of Theorem 1.1 (that is either for all \( n \) the assumptions of model A are satisfied, or for all \( n \) the assumptions of model B are satisfied).

**Theorem 1.3.** Take \( \bar{\delta} \) so small that every realization \( \{(T_n, W_n)\}_{n \in \mathbb{Z}} \) from the collection \( \mathcal{E} \) satisfies the conditions of Theorem 1.1.

(a) (Quenched CLT) There are constants \( a, \sigma > 0 \) such that for almost all iid realizations of the pairs \( (T_n, W_n) \) there are constants \( b_n = b_n(\omega) \) such that if \( x \) is uniformly distributed on \( T \) then
\[ \frac{z_n - b_n}{(1/a^{3/2})\sigma/\sqrt{n}} \Rightarrow \mathcal{N}(0,1) \text{ as } n \to \infty. \]

(b) (Annealed CLT) There are constants \( v, \sigma \) such that if \( x \) and \( \{(T_n, W_n)\} \) are independent, \( x \) is uniformly distributed on \( T \) and \( (T_n, W_n) \) are chosen from \( \mathcal{E} \) in an iid fashion, then
\[ \frac{z_n - vn}{(1/a^{3/2})\sigma/\sqrt{n}} \Rightarrow \mathcal{N}(0,1) \text{ as } n \to \infty. \]

**Remark 1.4.** The ballisticity condition (1.3) ensures that the time needed to move to the right for Model A is in \( BV \) as a function of the initial condition \( x \). This allows us to apply existing results about the central limit theorem for non-autonomous dynamical systems, such as \([2, 9, 18, 22, 37]\). In case the return time is unbounded, as is the case for Model B, one needs to extend the existing result allowing much less regular functions. This extension is formulated in Theorem 3.1 and is proven in the appendix. This result is of independent interest.

We also hope that our approach will be useful for other models of motions in random media, and this will be a subject of a future work.
2. Notations and definitions

For the sequence of maps \( \{ G_n \}_{n \in \mathbb{Z}} \) and \( k \leq m \) we define maps \( G_{k,m} \) as follows

\[
G_{k,m}(x) = G_m \circ \cdots \circ G_k(x).
\]

If above we have only one map, i.e. \( G_m = G \), for all \( m \in \mathbb{Z} \), then \( G_{k,m} = G^{m-k+1} \).

Let

\[
D_n^{(2)} = \{(t_1, t_2, \ldots, t_n) : t_k \in \{-1, 1\}, 1 \leq k \leq n\}.
\]

**Definition 2.1.** For \( n \geq 1 \), \( t \in D_n^{(2)} \), let

\[
s_k(t) = t_1 + \cdots + t_k, \quad 1 \leq k \leq n, \quad \text{and} \quad s_0(t) = 0.
\]

We will also be interested in the following subset of \( D_n^{(2)} \)

**Definition 2.2.** Let \( R_n^{(2)} \subset D_n^{(2)} \), be the set of all \( t = (t_1, \ldots, t_n) \), for which

\[
s_k(t) \leq 0, \quad 1 \leq k \leq n-1, \quad \text{and} \quad s_n(t) = 1.
\]

**Remark 2.3.** For even \( n \) we have \( R_n^{(2)} = \emptyset \).

**Definition 2.4.** Let \( A \subset \mathbb{T} \) be a set such that there is a collection of closed and disjoint intervals \( \{ I_k \}_{k=1}^m \) so that \( \bigcup_{k=1}^m I_k \subset \bar{A} \) and \( \left| A \setminus \bigcup_{k=1}^m I_k \right| = 0 \). Denote

\[
\mathcal{I}(A) = \{ I_1, \ldots, I_n \}.
\]

Note that if \( \mathcal{I}(A) \) exists, then it is unique.

We now recall some definitions and facts from [9]. Denote by \( BV \) the space of all functions with bounded variation and by \( V(f) \) the variation of the function \( f \in BV \). The space \( BV \) is equipped with the norm

\[
|f|_{BV} := V(f) + ||f||_1,
\]

where \( ||f||_L^1 \) is relative to the Lebesgue measure. For \( f \in BV \), we have: \( ||f||_{\infty} \leq |f|_{BV} \). Throughout the paper \( ||f||_p \) will stand for \( ||f||_{L^p}, p > 1 \).

Define also \( BV_0 = \{ f \in BV : \int_T f dx = 0 \} \).

We will be interested in maps satisfying

**Hypothesis 2.5.** Let \( G : \mathbb{T} \to \mathbb{T} \) be such that there exists a finite or countable partition \( \{ I_j \} \) of \([0, 1]\) or \( \mathbb{T} \) such that the restriction of the map to each interval \( I_j \) is strictly monotone and \( G|_{I_j} \in C^2(I_j) \). We also assume that

\[
\gamma := \inf_j \inf_{x \in I_j} |G'(x)| > 2, \quad \text{and} \quad \sup_j \sup_{x \in I_j} \left| \frac{(G(x))''}{(G(x))'} \right| < \infty.
\]

Given a map \( G \) as above define

\[
K := \sup_j \sup_{x \in I_j} |G'(x)| \quad \text{and} \quad K_1 := \sup_j \sup_{x \in I_j} |G''(x)|.
\]

Note that we can have \( K, K_1 = \infty \).
**Definition 2.6.** We say that a collection of intervals \( \{I_k\}_{k=1}^m \), with 
\[
\bigcup_{k=1}^m I_k = \mathbb{T}
\]
is a Markov partition for a map \( G \) satisfying Hypothesis 2.5, if 
\[
G(I_k) = \mathbb{T}, \quad 1 \leq k \leq m,
\]
and \( G \) is injective and continuous on each \( I_k \).

Let \((\mathbb{T}, \mathcal{A}, dx)\) be the Lebesgue \(\sigma\)-algebra. Consider the backward algebras
\[(2.1)\]
\[
\mathcal{A}_k = G_{-1,k}^{-1}(\mathcal{A})
\]
The sequence of \(\sigma\)-algebras \((\mathcal{A}_k)\) is strictly decreasing if the transformations \(G_n\) are non-invertible.

The transfer operator of a map satisfying Hypothesis 2.5 is given by
\[(2.2)\]
\[
P_G f(x) = \sum_j f(\sigma_j x) \frac{1}{|G'(\sigma_j x)|} 1_{G(I_j)}(x),
\]
where \(\sigma_j\) is the inverse function of the restriction of \(G\) on \(I_j\). It is well known that
\[
\int_{\mathbb{T}} (P_G f) g dx = \int_{\mathbb{T}} f(x) g(Gx) dx, \quad \forall f \in L^1, g \in L^\infty.
\]

Note also the following form of the transfer operator
\[
P_G(f)(x) = \sum_{y: G(y) = x} \frac{f(y)}{|G'(y)|}.
\]

**Lemma 2.7.** Let \( f \in L^2(\mathbb{T}) \). Then
\[
\left\| Pf \right\|_2 \leq \sqrt{|P1|_\infty} \| f \|_2.
\]

**Proof.** By Hölder’s inequality
\[
\left( \sum_{y: G(y) = x} \frac{f(y)}{|G'(y)|} \right)^2 \leq \left( \sum_{y: G(y) = x} \frac{f^2(y)}{|G'(y)|} \right) \left( \sum_{y: G(y) = x} \frac{1}{|G'(y)|} \right).
\]
Integrating this inequality we obtain
\[
\int_{\mathbb{T}} (Pf)^2 dx \leq \int_{\mathbb{T}} Pf^2 dx |P1|_\infty = |P1|_\infty \int_{\mathbb{T}} f^2 dx.
\]
Taking square root on both sides we get the required estimate. \(\square\)

Let \( \mathcal{P} \) be a set of contractions on \( L^1 \) (a set of linear operators satisfying \( \| Pf \|_1 \leq \| f \|_1 \), for every \( P \in \mathcal{P} \)). Following [9] the \( p \) distance between two transfer operators \( R, R' \) will be defined as follows
\[(2.3)\]
\[
d_p(R, R') = \sup_{\{f \in BV : |f|_BV \leq 1\}} \| Rf - R' f \|_p.
\]
When \( p = 1 \), we will drop the index and denote it by \( d \). For \( P \in \mathcal{P} \), we denote its \( \delta \) neighborhood by \( B(P, \delta) := \{ R \in \mathcal{P} : d(R, P) < \delta \} \).

We say that the collection \( \mathcal{P} \) satisfies the Lasota-Yorke property \((LY)\), if there exists \( \rho \in (0, 1) \) and \( C > 0 \), so that for any \( P \in \mathcal{P} \) we have
\[(LY)\]
\[
\forall f \in BV, \quad V(Pf) \leq \rho V(f) + C \| f \|_1.
\]
We say the subset $\mathcal{P}_0 \subset \mathcal{P}$ satisfies the exponential decay of correlations property (Dec) in $\text{BV}_0$ if there exist $\theta < 1$ and $K > 0$ such that, for all integers $l \geq 1$, all $l$-tuples of operators $P_1, \ldots, P_l$ in $\mathcal{P}_0$ we have

\begin{equation}
(\text{Dec}) \quad \forall f \in \text{BV}_0, \quad |P_l \cdots P_1 f|_{\text{BV}} \leq K \theta^l |f|_{\text{BV}}.
\end{equation}

It follows from (LY) (see [9, Lemma 2.4]) that there exists $M > 0$, so that for any $P_n, \ldots, P_1 \in \mathcal{P}$ and $f \in \text{BV}$

\begin{equation}
(2.4) \quad |P_n \cdots P_1 f|_{\text{BV}} \leq M |f|_{\text{BV}}, \quad \text{for all } n \geq 1.
\end{equation}

We say that the sequence of operators $\{P_n\}_{n \geq 1}$ satisfies the condition (Min), if there exists $\sigma > 0$ such that

\begin{equation}
(\text{Min}) \quad P_n P_{n-1} \ldots P_1 1(x) \geq \sigma, \quad \forall x \in \mathbb{T}, \forall n \in \mathbb{N}.
\end{equation}

We say that the collection $\mathcal{P}$ satisfies conditions (Min) if any sequence in $\mathcal{P}$ satisfies the property (Min) with the same constant $\sigma$. In the sequel we will use the notation $\mathcal{P}^n 1 = P_n P_{n-1} \cdots P_1 1$.

We recall a criterion for verifying the condition (Dec):

**Proposition 2.8.** ([9, Proposition 2.10]) Let $\mathcal{P}$ be a collection of contractions satisfying (LY) and $P \in \mathcal{P}$ that satisfies (Dec), i.e.

\begin{equation}
(2.5) \quad |P^n f|_{\text{BV}} \leq C \gamma^n |f|_{\text{BV}}, \quad \forall f \in \text{BV}_0.
\end{equation}

Then there exists $\delta_0 > 0$, such that the set $\mathcal{P}_0 = B(P, \delta_0) \cap \mathcal{P}$ satisfies (Dec) in $\text{BV}_0$.

The relevance of the properties introduced above comes from the following result.

**Theorem 2.9.** ([9, Theorem 5.1]) Let $(f_n)$ be a sequence of observables, such that $\sup_n |f_n|_{\text{BV}} < \infty$. Assume that for the sequence of transformations $\{T_n\}_{n \geq 1}$ the corresponding set of transfer operators $\{P_{T_n}\}_{n \geq 1}$ satisfy (Min) and (Dec). Let

\[ S_n(x) = \sum_{k=0}^{n-1} f_n(T_{1,n}(x)) - \int_{\mathbb{T}} f_n(T_{1,n}(x)) \, dx \]

where $T_{1,n} = T_n \circ \cdots \circ T_1$. If the norms $\|S_n\|_2$ are unbounded as $n \to \infty$ then

\[ \frac{S_n}{\|S_n\|_2} \Rightarrow \mathcal{N}(0,1). \]

Theorem 2.9 is sufficient to handle Model A. For Model B we need an extension of this result, namely, Theorem 3.1 formulated in §3.1 and proven in Appendix A. Theorem 3.1 allows to handle unbounded observable and is of independent interest.

**Definition 2.10.** We say that the observable $\varphi$ is cohomologous to zero for the map $T$ if there exist an observable $H \in L^2$ and $c \in \mathbb{R}$ such that

\[ \varphi + c = H - H \circ T. \]
3. Some auxiliary results

3.1. An extension of a result of Conze-Raugi. In Appendix A we prove the following extension of Theorem 2.9. Observe that the functions \(\{f_n\}\) below can also be unbounded.

**Theorem 3.1.** Assume the operators \(\{P_n\}_{n \geq 0}\) fulfill the conditions \((\text{Dec})\) and \((\text{Min})\) on \(BV\) and let \(\{f_n\}_{n \geq 1}\) be a sequence of observables, such that there exists \(D > 0\), so that

\[
\sup_{\{g \in BV : |g|_{BV} \leq 1\}} |P_n(f_{n-1}g)|_{BV} < D \quad \text{and} \quad \sup_{\{g \in BV : |g|_{BV} \leq 1\}} |P_n(f_n^2g)|_{BV} < D,
\]

for all \(n \geq 1\). Consider the sum

\[
S_n(x) = \sum_{k=0}^{n-1} \tilde{f}_k, \quad \text{where} \quad \tilde{f}_k = f_k(G_{1,k}(x)) - \int f_k(G_{1,k}(x)) \, dx.
\]

If the sequence of variances \(\sigma_n = \|S_n\|_2\) is unbounded and for every \(\varepsilon > 0\) we have

\[
\lim_{n \to \infty} \frac{\sum_{k=1}^{n} \int \tilde{f}_k^2(x)1_{[\varepsilon \sigma_n, \infty)}(\tilde{f}_k^2(x)) \, dx}{\sigma_n^2} = 0,
\]

then \(\frac{S_n}{\sigma_n} \Rightarrow \mathcal{N}(0, 1)\) as \(n \to \infty\).

**Remark 3.2.** Let \(\mathbb{T}_n = \mathbb{T} \times \{n\}\). Note that in several results in Sections 2 and 3 including Theorems 2.9 and 3.1 we consider maps \(G_{1,k}\) with domain \(\mathbb{T}_1\) and range \(\mathbb{T}_{k+1}\). In particular \(f_k\) are defined on \(\mathbb{T}_{k+1}\). This is done to have the same notation as in [9]. However, in applications we will deal with maps \(G_{0,k-1}\) with domain \(\mathbb{T}_0\) and range \(\mathbb{T}_k\). This is done since it is natural to consider the walk started at the origin rather than site 1.

3.2. Lasota-Yorke inequality. We need the following standard fact whose proofs could be found in [9], page 105.

**Lemma 3.3.** (a) Let \([u, v] \subset [c, d] \subset [0, 1]\), and \(f\) be of bounded variation. Then

\[
|f(u)| + |f(v)| \leq V_{c,d}(f) + \frac{2}{(d-c)} \int_c^d |f(t)| \, dt.
\]

(b) In particular

\[
|f(u)| + |f(v)| \leq V_{[u,v]}(f) + \frac{2}{(v-u)} \int_u^v |f(t)| \, dt.
\]

**Lemma 3.4.** Let \(G\) be a map satisfying hypothesis \((2.3)\) and suppose that there is an interval \(W \subset \mathbb{T}\) such that \(G\) is \(C^2\) everywhere except, possibly, at the endpoints of \(W\). Assume also there is \(K > 0\) such that \(\sup_{x \in \mathbb{T}\setminus \partial W} |G'(x)| \leq K\). Then there is \(C = C(\gamma, K, K_1) > 0\) such that

\[
V(P_gf) \leq \frac{3}{\gamma} V(f) + C\|f\|_1.
\]
Proof. Recall that

$$P_G f(x) = \sum_j f(\sigma_j x) \frac{1}{|G'(\sigma_j x)|} 1_{G(I_j)}(x),$$

where $\sigma_j$ is the inverse function of $G$ on its intervals of monotonicity ($I_j$). It is clear from the assumptions that $G$ can have at most two discontinuities at the endpoints of $W$ and the partition in Hypothesis 2.5 is finite. We can assume that $|W| \leq \frac{1}{2}$. Otherwise, instead of $W$ we can consider $W^c$. Since $G$ has only two discontinuity points, the partition ($I_j$) can be chosen in such a way that there will be at most one interval $I \in (I_j)$, with $|I| < \frac{1}{2(|I|+1)}$. Indeed, we can define the partition ($I_j$) on $W^c$ so that $|I_j| = \frac{|W^c|}{|I|+1}$, $j = 1, \ldots, [K] + 1$. Since $\frac{1}{2(|I|+1)} < |I_j| < \frac{1}{K}$, then $G|_{I_j}$ will be one-to-one on each one of these intervals. If now $|W| < \frac{1}{2(|I|+1)}$, then we will take $W$ to be one of the partition intervals, otherwise we divide $W$ into intervals of size $\frac{1}{2(|I|+1)}$ and a reminder interval $I$, so that $|I| < \frac{1}{2(|I|+1)}$.

Note that

$$V(P_G f) \leq \sum_j V\left(f(\sigma_j x) \frac{1}{|G'(\sigma_j x)|} 1_{G(I_j)}(x)\right) \leq$$

$$\sum_j \left(V(G(I_j)) \left(\frac{f}{G'} \circ \sigma_j\right) + \left|\frac{f}{G'}(\sigma_j \alpha_j) + \frac{f}{G'}(\sigma_j \beta_j)\right|\right) =: I + II$$

where $G(I_j) = [\alpha_j, \beta_j]$. By an inequality in [9], page 106, we have

$$V_G(I_j) \left(\frac{f}{G'} \circ \sigma_j\right) = V_{I_j} \left(\frac{f}{G'}\right) \leq \frac{V_{I_j}(f)}{\gamma} + \frac{K_1}{\gamma^2} \int_{I_j} |f(t)|dt.$$  \hspace{1cm} (3.5)

Summing over $j$ we get

$$I \leq \frac{V(f)}{\gamma} + \frac{K_1}{\gamma^2} \|f\|_1. \hspace{1cm} (3.6)$$

Next for all monotonicity intervals with $|I_j| > \frac{1}{2(|I|+1)}$ we use Lemma 3.3(b) obtaining

$$\left|\frac{f}{G'}(\sigma_j \alpha_j) + \frac{f}{G'}(\sigma_j \beta_j)\right| \leq \frac{1}{\gamma} |f|(\sigma_j \alpha_j) + |f|(\sigma_j \beta_j) \hspace{1cm} (3.7)$$

$$\leq \frac{V_{I_j}(f)}{\gamma} + \frac{2}{\gamma |I_j|} \int_{I_j} |f(x)|dx \leq \frac{V_{I_j}(f)}{\gamma} + \frac{4([K] + 1)}{\gamma} \int_{I_j} |f(x)|dx.$$  \hspace{1cm} (3.7)

It remains to handle the shortest interval $I_i$. Let $I_{i+1}$ be a partition element adjacent to $I_i$ and set $I = I_i \cup I_{i+1}$. Then $|I| > \frac{1}{2(|I|+1)}$ and by (3.3), applied to $I_i \subset I = [c,d]$, we have

$$\left|\left(\frac{f}{G'}\right)(\sigma_i \alpha_i)\right| + \left|\left(\frac{f}{G'}\right)(\sigma_i \beta_i)\right| \leq \frac{1}{\gamma} |f|(\sigma_i \alpha_i) + |f|(\sigma_i \beta_i) \hspace{1cm} (3.8)$$

Summing the above estimates we obtain

$$V(P_G f) \leq \frac{3}{\gamma} V(f) + C\|f\|_1.$$
where the factor $\frac{3}{\gamma}$ is the sum of three terms of size $\frac{1}{\gamma}$ coming from (3.6), (3.7), and (3.8) respectively. This completes the proof.

3.3. Positivity of density. We say that the sequence of expanding maps $\{G_n\}_{n \geq 1}$ satisfies property (C) if for every $\varepsilon > 0$, there exists $s \geq 1$ and $M > 0$ such that for every $x \in \mathbb{T}$, $n \in \mathbb{N}$ and any interval $I \subset \mathbb{T}$, with $|I| > \varepsilon$, there exists $y = y(n, I, x) \in I$ so that

$$G_{n, n+s}(y) = x, \quad |D_y G_{n, n+s}| \leq M.$$ 

Lemma 3.5. Assume there exists $K > 0$, such that for every $n \geq 1$,

$$\sup_j \sup_{x \in I^{(n)}} |G_n'(x)| \leq K.$$

If for every interval $I$ there exist a number $s \in \mathbb{N}$, such that for every $n \geq 1$, $G_{n, n+s}(I) = \mathbb{T}$ then property (C) holds.

Proof. Take a partition of $\mathbb{T}$ into intervals $\{J_k\}$ of lengths in $[\frac{a}{2}, \frac{a}{3}]$. For each $J_k$ we can find its own covering number $s_k$. Note that any number $s$ larger than $s_k$ is again a covering number for $J_k$. Let $s$ be the largest number in the set $\{s_k\}$. Now observe that any interval $J$ of length larger than $\varepsilon$ contains an interval from $\{J_k\}$ in its interior. Hence we will have $G_{n, n+s}(I) = \mathbb{T}$. It remains to notice that $|D_y G_{n, n+s}| \leq K^s$. □

We say the map $G$ satisfies property (C) if the sequence $G, G, \ldots$ satisfies this property.

The following proposition extends several classical results for a single expanding map (see [34]) to a sequence of expanding maps satisfying property (C).

Proposition 3.6. Let $\mathcal{G} = \{G_n\}_{n \geq 1}$, be a sequence of expanding maps so that for each $n \geq 1$ there is an interval $J_n \subset \mathbb{T}$ such that $G_n(J_n) = \mathbb{T}$ and $\sup_{n \geq 1, x \in J_n} |G_n'(x)| \leq K_0$, for some finite $K_0$. Assume also the set of associated transfer operators $\{P_n\}_{n \geq 1}$ satisfies property (LY). Then

(a) If $\mathcal{G}$ satisfies property (C) then there exists $\sigma > 0$ so that for any $n \geq 1$ and $x \in \mathbb{T}$

$$P_n P_{n-1} \cdots P_1 1(x) \geq \sigma.$$

(b) Let $G \in \mathcal{G}$ be an expanding map which satisfies property (C). Then $P$ also satisfies property (Dec).

Proof. (a) We follow the proof of [2, Proposition 2]. For $a > 0$, let

$$\mathcal{E}_a = \left\{ f \in BV : f \geq 0, \quad V(f) \leq a \int f \right\}.$$

By Lemma 3.2 in [34], for any $f \in \mathcal{E}_a$ there exist an interval $I$, with $|I| = \frac{1}{2a}$, so that $f(x) \geq \frac{1}{2} \int f$ for all $x \in I$. Note that by the Lasota-Yorke inequality (LY) we have

$$V(P_r \cdots P_1 f) \leq \rho^r V(f) + C_r \|f\|_1 \leq (a \rho^r + C_r) \int f.$$ 

Hence, for $a \geq \frac{C_r}{1-\rho^r}$, we have $(P_r \cdots P_1)(\mathcal{E}_a) \subset \mathcal{E}_a$ for any choice of $P_1, \ldots, P_r$. In order also to have $1 \in \mathcal{E}_a$, we will actually choose $a = \max \left\{ 1, \frac{C_r}{1-\rho^r} \right\}$. By Property
(C), for $\varepsilon = 1/2a$ we can find $s \geq 1$, $M < \infty$ so that for any $x \in \mathbb{T}$ and any $n \in \mathbb{Z}$ one can find $\zeta \in I$, with $G_{n,n+s}(\zeta) = x$ and $|D_\varepsilon G_{n,n+m}| \leq M$.

Let $m \geq 0$. We have $P_{1,m+1}1 = P_{m+1,m+s}P_{1,m}1$. Write $m = p_mr + q_m$, with $0 \leq q_m < r$. Note that for $k \leq q_m$ we have

$$P_{1,k}1(x) \geq K_0^{-k},$$

since all the maps $G_m$ have intervals $J_n$ so that $G_m(J_n) = \mathbb{T}$ and $|G_m'(x)| \leq K_0$, for all $x \in J_n$. As a consequence, we have $P_{1,m+1}1 \geq K_0^{-q_m}P_{m+1,m+s}g_m$, with $g_m = P_{q_m+1,m}1$. Since $P_{q_m+1,m}1$ is a concatenation of $p_m$ blocks of $r$ operators applied to a function in $\mathcal{E}_a$, we obtain that $g_m$ belongs to $\mathcal{E}_a$. Then, there exists an interval $I$, with $|I| = \frac{1}{2^a}$, on which $g_m \geq \frac{1}{2}$.

This implies

$$P_{1,m+s}1(x) \geq K_0^{-q_m}P_{m+1,m+s}1f(x) = K_0^{-q_m} \sum_{G_{m+1,m+s}(y) = x} \frac{1f(y)}{|(D_\sigma G_{m+1,m+s})|} \geq \frac{K_0^{-q_m}}{M},$$

completing the proof.

(b) By part (a) for a proper choice of the parameter $a$ we have that $P^n(\mathcal{E}_a) \subset \mathcal{E}_a$. Then by the discussion at the beginning of the proof of (a), for every $g \in \mathcal{E}$ we have

$$\left(P^n g\right)(x) = \sum_{y \in G^{-n}(x)} g(y) |D_\sigma G^n| \geq \frac{1}{2^n} g(y).$$

Next, to show that the image has a finite diameter under the Hilbert metric we repeat the proof of Lemma 3.5 of [34], taking into account the estimate (3.9). Thus $\text{diam} P^n(\mathcal{E}_a) < \infty$. Given this inclusion the proof of (Dec) goes along the same lines as in [34, Section 3] or [37, §3.2] so we omit it.

Lemma 3.7. Let $\{G_n\}_{n \geq 1}$ be a map satisfying hypothesis [2,3] and intervals $\{W_n\}_{n \geq 1}$ such that for each $n \geq 1$ $G_n$ is $C^2$ everywhere on $\mathbb{T}$, except possibly at the endpoints of $W_n$. Assume also we have $|G_n(x')| \leq K$ at all points $x$ away from discontinuity points. Then there exists $\sigma > 0$ such that

$$\left(P_n \cdots P_1\right)(x) \geq \sigma, \quad \forall x \in \mathbb{T}, \, n \geq 1,$$

where $P_n$ is the transfer operator for $G_n$.

Proof. We verify the conditions of Proposition [3.6(a)]. First note that since $\gamma > 3$ then one can find an interval $J_n \subset W_n$ or $J_n \subset W_n^c$ so that $G_n(J_n) = \mathbb{T}$ and we obviously have $|D_\sigma G_n| \leq K < \infty$. Property (LY) follows from Lemma 3.4. To verify property (C), in view of Lemma 3.5, it is sufficient to show that $\{G_n\}_{n \geq 1}$ satisfies the covering property: for each $I \subset \mathbb{T}$, there exists $N = N(|I|)$ so that $G_{1,N}(I) = \mathbb{T}$.

If $W_1 \cap I \neq \emptyset$, then the intersection with $\partial W_1$ divide $I$ into at most three components. Let $I_1$ be the largest component. Then $|I_1| \geq |I|/3$. Consider the image $G_1(I_1)$. Then $|G_1(I_1)| \geq \gamma |I_1|$, since $G_1$ is continuous both inside and outside of $W_1$. Next, we choose the largest interval $I_2 \subset G_1(I_1)$, so that either $I_2 \subset W_2$ or $I_2 \cap W_2 = \emptyset$. Hence, $|I_2| \geq |G_1(I_1)|/3 > \frac{\gamma}{3} |I_1|$. Repeating this argument, we will obtain a sequence of intervals $(I_n)_{n \geq 1}$, so that

$$|I_{n+1}| > \left(\frac{\gamma}{3}\right)^n |I_n|.$$
Since $\frac{2}{3} > 1$, the image of $I_1$ covers the circle in time $O \left( \ln \left( \frac{1}{|I_1|} \right) \right)$. □

4. The growth of variance.

In this section we study the behavior of the variance of $\tau_n$ (see (1.5))

$$\tau_n(x) = \sum_{k=0}^{n-1} r_k( G_{k-1} \circ \cdots \circ G_0 x).$$

For convenience we start the counting from $i = 1$ in the following

$$\sigma^2_n = \text{Var}(\tau_n) = \int_T \left( \sum_{i=1}^{n} \left[ r_i(G_1(x)) - \int_T r_i(G_1(y)) dy \right] \right)^2 dx.$$

The next proposition shows that the linear growth of variance is stable under small perturbations. Note that the observables $r_n$ and $r$ may be unbounded. Recall (2.3).

**Proposition 4.1.** Let $\mathcal{G}$ be a collection of maps satisfying Hypothesis [2.3] such that its associated set of transfer operators satisfies [Dec]. Assume $G \in \mathcal{G}$, $r \in L^2(\mathbb{T})$ are such that the acim $h$ of $G$ is bounded away from zero and $r$ is not cohomologous to a constant for $G$. Let $P$ be the transfer operator of $G$. Then for each $L > 0$ there exists $\delta_0 > 0$ such that the following holds. Let $\{G_n\}_{n \geq 1} \subset \mathcal{G}$ and $r_n \in L^2(\mathbb{T})$ be such that denoting by $P_n$ the transfer operators of $G_n$ we have that for all $n \geq 1$

$$|P_n(r_{n-1}f)|_{BV} \leq L|f|_{BV}, \quad |P(rf)|_{BV} \leq L|f|_{BV}, \quad f \in BV.$$ 

and

$$d_2(P_n, P) \leq \delta_0, \quad d_2(P_n(r_{n-1} \cdot), P(r \cdot)) \leq \delta_0, \quad \|r - r_n\|_2 \leq \delta_0.$$

Then there is a constant $C = C(\delta_0, r, G, L) > 0$ such that

$$\sigma^2_n \geq Cn.$$

**Proof.** Define

$$\tilde{r}_k = r_k - \int_T r_k(G_{1,k}(x)) dx, \quad \tilde{r} = r - \int_T r(G^k(x)) dx.$$

By assumption $r$ is not cohomologous to zero and $h(x) \geq c$ for almost all $x \in \mathbb{T}$ and some $c > 0$. By Proposition A.1 proven in the appendix there exists $C > 0$ so that

$$\tilde{\sigma}^2_n \geq Cn,$$

where

$$\tilde{\sigma}^2_n = n \sum_{i=1}^{n} \int_T \tilde{r}^2 h dx + 2 \sum_{k=1}^{n} (n - k) \int_T \tilde{r}(x) \tilde{r}(G^k(x)) dx$$

is the variance of the unperturbed system.

Similarly for the general case

$$\sigma^2_n = \sum_{i=1}^{n} \int_T \tilde{r}_i^2(G_{1,i}(x)) dx + 2 \sum_{1 \leq i < j \leq n} \int_T \tilde{r}_i(G_{1,i}(x)) \tilde{r}_j(G_{1,j}(x)) dx.$$
We now show that for each $\varepsilon > 0$, $\delta_0$ can be taken so small that for all large $n \geq 1$
\[ |\sigma_n^2 - \sigma_n^2| \leq \varepsilon n. \]

To this end we note that
\[ \left| \int_T \tilde{r}_i (G_{1,i}(x)) \tilde{r}_j (G_{1,j}(x)) \, dx \right| = \left| \int_T \tilde{r}_i P_1 \cdots P_{j+1} (\tilde{r}_j \mathcal{P}_1) \, dx \right| \leq \]
\[ \leq K \theta |i-j| \left( P_{j+1}(\tilde{r}_j \mathcal{P}_1) \right)_{BV} \left\| \tilde{r}_i \right\|_1 \leq D' \theta |i-j|, \]
where in the last line we used (Dec) and the estimate
\[ (4.5) \quad \left| P_{j+1}(\tilde{r}_j \mathcal{P}_1) \right|_{BV} \leq \left| P_{j+1}(r_j \mathcal{P}_1) \right|_{BV} + \left| \int_T r_j (G_{1,j}) \, dx \right| \left| \mathcal{P}_{j+1} \right|_{BV} \]
\[ \leq L \left| \mathcal{P}_1 \right|_{BV} + \left\| r_j \right\|_1 \left\| \mathcal{P}_1 \right\|_{\infty} \left| \mathcal{P}_{j+1} \right|_{BV} \leq LM + LM^2, \]
which relies on the fact that $\left\| P_{j+1}(r_j) \right\|_1 = \left\| r_j \right\|_1 \leq L$. Therefore
\[ \left| \sum_{i,j \leq n; |i-j| \geq N} \int_T \tilde{r}_i (G_{1,i}x) \tilde{r}_j (G_{1,j}x) \, dx \right| \leq \sum_{N \leq i \leq n} (n-i) D' \theta^i \leq D' \sum_{N \leq i \leq n} n \theta^i \leq D'n \theta^n \frac{1}{1 - \theta}. \]

In a similar way for $\bar{\sigma}_n$ we have
\[ (4.6) \quad \left| 2 \sum_{k=1}^{n} (n-k) \int_T \tilde{r}(x) \tilde{r}(G^k(x)) h(x) \, dx \right| \leq D'n \theta^n \frac{1}{1 - \theta}. \]

Next, we take $N$ so large that
\[ (4.7) \quad D'n \theta^n \frac{1}{1 - \theta} \leq n \frac{C}{4}, \]
where $C$ is from (4.3). We now consider the terms with $|i-j| < N$ and show that for arbitrary $\varepsilon > 0$, $\delta_0$ can be taken so small that the following bound holds
\[ (4.8) \quad \left| \int_T \tilde{r}_i P_1 \cdots P_{j+1} (\tilde{r}_j \mathcal{P}_1) \, dx - \int_T \tilde{r}(x) P_{j+1} (\tilde{r}_j \mathcal{P}_1) \, dx \right| \leq C_0 \varepsilon, \]
for some $C_0 > 0$. For this it is enough to show that for arbitrary $\varepsilon > 0$, $\delta_0$ can be taken so small that if $\delta \leq \delta_0$ then
\[ (4.9) \quad \left\| \tilde{r}_i - \tilde{r} \right\|_2 \leq \varepsilon, \]
and
\[ (4.10) \quad \left\| P_i \cdots P_{j+1} (\tilde{r}_j \mathcal{P}_1) - P_{j+1} (\tilde{r}_j \mathcal{P}_1) \right\|_2 \leq \varepsilon. \]

By Lemma 2.13 of [9], for any $p \leq n$ we have that
\[ (4.11) \quad \left\| \mathcal{P}^n_1 - P^n_1 \right\|_1 \leq C' \left( p \delta_0 + (1 - \theta)^{-1} \theta^p \right). \]

Taking $p = \left[ \frac{1}{\sqrt{n}} \right] + 1$, we see that for small $\delta_0$
\[ (4.12) \quad \left\| \mathcal{P}^n_1 - P^n_1 \right\|_1 \leq C' \sqrt{\delta}. \]

Since, $P^n_1 \to L^1 h$, as $n \to \infty$, then for $n$ sufficiently large $\left\| \mathcal{P}^n_1 - h \right\|_1 \leq 2C' \sqrt{\delta}$. Thus
\[ \left\| \mathcal{P}^n_1 - h \right\|_2 \leq \sqrt{2M} \left\| \mathcal{P}^n_1 - h \right\|_1 \leq C_1 \delta^{\frac{1}{2}}. \]
Next, observe that

\[
\left| \int_T (r_k(G_{1,k}) - r(G^k))\,dx \right| = \left| \int_T (P^k r_k - P^k r)\,dx \right| 
\leq \left| \int_T P^n (r_k - r) + (P^n - P^k) r\,dx \right| 
\leq M\|r_k - r\|_1 + \|P^n - P^k\|_2 \|r\|_2 \leq M\delta_0 + \|r\|_2 L^2 \delta_0^{1/2}.
\]

It then follows that for all \(n \geq 1\) and \(\delta, \varepsilon\) small we will have

\[
\|\tilde{r} - \tilde{r}_n\|_2 \leq M\delta_0 + \|r\|_2 L^2 \delta_0^{1/2} + \|r - r_n\|_2 \leq (M + 1)\delta_0 + \|r\|_2 L^2 \delta_0^{1/2},
\]

since by assumption \(\|r - r_n\|_2 \leq \delta_0\). Thus we obtain (4.9).

To show (4.10), observe that by the triangle inequality

\[
\left\| P^{[i-j+1]}(\tilde{r}h) - P_i \cdots P_{j+1}(\tilde{r}_j P^j 1) \right\|_2 \leq \left\| P^{[i-j]}(P(\tilde{r}h)) - P^{[i-j-1]}(P_{j+1}(\tilde{r}_j P^j 1)) \right\|_2 + \left\| P^{[i-j]}(P_{j+1}(\tilde{r}_j P^j 1)) - P_i \cdots P_{j+1}(\tilde{r}_j P^j 1) \right\|_2 = I + II.
\]

By Lemma 2.4 of [9] we have that

\[
d_2(P_1 \cdots P_n, P^n) \leq \sum_{k=1}^n d_2(P_k, P).
\]

Hence, by assumptions of the proposition and in view of (4.5)

\[
I \leq d_2(P_i \cdots P_j, P^{[i-j-1]}(P_{j+1}(\tilde{r}_j P^j 1)) \leq (LM + LM^2) \sum_{k=1}^{[i-j]} d_2(P_k, P) \leq NC_3\delta_0.
\]

For II we have by Lemma 2.7 and the assumptions of our proposition that

\[
II \leq \left\| P^{[i-j-1]}(P_{j+1}(\tilde{r}_j P^j 1)) \right\|_2 + \left\| P_{j+1}(\tilde{r}_j P^j 1) - P(\tilde{r}h) \right\|_2 \leq C_4 M^{[i-j-1]/2} \delta_0.
\]

Taking \(\delta_0\) small enough we arrive at (4.10). Combining (4.9) and (4.10) we get (4.8). Summing (4.8) for all \(i - j \leq N\) we get

\[
\sum_{i,j \leq n, |i-j| \leq N} \left| \int_T \tilde{r}_i(G_{1,i}(x))\tilde{r}_j(G_{1,j}(x))\,dx - \sum_{k=1}^{N} \left( (n - k) \int_T r(x)r(G^k(x))\,dx \right) \right| \leq C'Nn\varepsilon + C''N\varepsilon.
\]

Thus by (4.6), (4.7) and (4.16) we can write

\[
|\sigma_n^2 - \tilde{\sigma}_n^2| \leq N \frac{2C}{4} + C'Nn\varepsilon + C''N\varepsilon.
\]

Therefore

\[
\sigma_n^2 \geq Cn - 2C \frac{n}{4} - C'Nn\varepsilon - C''N\varepsilon \geq \left( \frac{C}{2} - C'N\varepsilon \right)n - C''N\varepsilon \geq C_1 n
\]

if \(\varepsilon\) is small enough. This finishes the proof. \(\square\)
Lemma 4.2. Let \( \bar{G} \) be an expanding map satisfying Hypothesis 2.5 so that for some \( x_0 \in \mathbb{T} \) we have \( \bar{G}(x_0) = x_0 \) and \( \bar{G} \) is continuous at a neighborhood of \( x_0 \). Assume for \( \bar{r} \in L^2 \) we have \( \bar{r} = C \) in an open neighborhood of \( x_0 \) and \( C \not\equiv \int_{\mathbb{T}} \bar{r} \, dx \). Assume further that \( \bar{P} \bar{r} \in BV \). Then \( \bar{r} \) is not cohomologous to a constant under \( \bar{G} \).

Proof. Assume \( \bar{r} \) is a coboundary for \( \bar{G} \). Since \( \bar{P} \bar{r} \in BV \), then by Proposition A.1 there exists \( g \in BV \), such that the equality

\[
\bar{r}(x) - \int_{\mathbb{T}} \bar{r}(x) h(x) \, dx = g(x) - g(\bar{G}(x))
\]

holds almost surely. Let \( A' \subset \mathbb{T} \) be the set of all \( x \in A' \) for which the equation above holds for all the forward and backward images of \( x \) under \( \bar{G} \). Clearly \( |A'| = 1 \).

By assumption \( \bar{G}(x_0) = x_0 \). Take \( x \in A' \). Then

\[
\sum_{k=0}^{n} \bar{r}(\bar{G}^k(x)) - n \int_{\mathbb{T}} \bar{r}(x) h(x) \, dx = g(x) - g(\bar{G}^n(x))
\]

Observe that \( \bar{r}(x) = \bar{r}(x_0) \) for \( x \) sufficiently close to \( x_0 \). Hence

\[
|n \bar{r}(x) - n \int_{\mathbb{T}} \bar{r}(x) h(x) \, dx| = n|C - \int_{\mathbb{T}} \bar{r}(x) h(x) \, dx| \leq 2\|g\|_{\infty}.
\]

By assumption \( C - \int_{\mathbb{T}} \bar{r}(x) h(x) \, dx \neq 0 \) Hence, for large \( n \), (4.17) can not take place. This finishes the proof. \( \square \)

5. Proof of the main results for Model A.

5.1. Proof of Theorem 1.1(a). Recall that (see (1.6) and (1.7))

\[
G_n(x) = \begin{cases} 
T_n(T_{n-1}(T_n(x))) & \text{if } x \in W_n, \\
T_n(x) & \text{if } x \in \mathbb{T} \setminus W_n.
\end{cases}
\]

and

\[
r_n(x) = \begin{cases} 
3 & \text{if } x \in W_n, \\
1 & \text{for } x \in \mathbb{T} \setminus W_n.
\end{cases}
\]

And also

\[
\bar{r}(x) = \begin{cases} 
3 & \text{if } x \in \bar{W}, \\
1 & \text{if } x \in \mathbb{T} \setminus \bar{W}.
\end{cases}
\]

\[
\bar{G}(x) = \begin{cases} 
\bar{T}(\bar{T}(\bar{T}(x))) & \text{if } x \in \bar{W}, \\
\bar{T}(x) & \text{if } x \notin \mathbb{T} \setminus \bar{W}.
\end{cases}
\]

We denote by \( P_n \) and \( \bar{P} \) the transfer operators of \( G_n \) and \( \bar{G} \) respectively.

To prove Theorem 1.1(a) we will verify that the collection \( \{P_n\} \) satisfies the conditions of Theorem 2.9.

Next, we show that the sequence \( \{P_n\} \) satisfies \( \text{(Dec)} \) if \( \delta_0 \) is sufficiently small. Note that \( \text{(Dec)} \) for the unperturbed map \( \bar{P} \) follows from Proposition 3.6(b). Applying Proposition 2.3 to \( \bar{P} \), we can find a neighborhood of \( \bar{P} \), where \( \text{(Dec)} \) property is preserved. Hence, to establish \( \text{(Dec)} \) for the collection \( \{P_n\}_{n \geq 1} \) for \( \delta_0 \) small, it suffices to show that the norms \( d_1(P_n, \bar{P}) \) are small when \( \delta_0 \) is small. Thus \( \text{(Dec)} \) is a consequence of the following result whose proof will be given in §5.2.
Lemma 5.1. For $\delta_0$ sufficiently small there exists $L > 0$ such that
\[ \| P_n f - \tilde{P} f \|_1 \leq L\delta_0 \| f \|_{BV}, \quad \forall f \in BV. \]

The (Min) condition for $\mathcal{P}^n 1$ follows from Lemma 3.7. Thus, we have established (Dec) and (Min) for the sequence $\{ P_n \}$.

Note that for Model A, $1 < \int_{\mathbb{T}} \tilde{r} dx < 3$. Hence by Lemma 4.2, $\tilde{r}$ is not cohomologous to a constant for $G$. Thus, Proposition 4.1 gives the linear growth of the variance for the sequence
\[ \tau_n(x) = \sum_{k=0}^{n-1} r_k(G_{k-1} \circ \cdots \circ G_0 x) \]
if $\delta_0$ sufficiently small. Now Theorem 1.1(a) follows from Theorem 2.9 \hfill \Box

5.2. Proof of Lemma 5.1. We recall the following fact from [9]. Let
\begin{equation}
\tilde{w}(f, t) = \int_{0}^{1} \sup_{|y-x| \leq t} |f(y) - f(x)| dx.
\end{equation}

Then
\begin{equation}
\tilde{w}(f, t) \leq 2tV(f).
\end{equation}

As earlier, we need to estimate the norms
\[ \| P_n f - \tilde{P} f \|_1 = \int_{\mathbb{T}} | P_n f - \tilde{P} f | dx. \]

For $x \in W_n \cap \tilde{W}$ we have that
\[ G_n(x) = T_n(T_{n-1}(T_n(x))) = \tilde{T}(\tilde{T}(T(x))) + g_n(x), \]
where $\| g_n \|_{C^1 + \text{Lip}(W_n \cap \tilde{W})} < C\delta_0$. Hence, away from a set $A \subset \mathbb{T}$ of measure $O(\delta_0)$ we have $\| G - G_n \|_{C^1 + \text{Lip}(\mathbb{T} \setminus A)} < L\delta_0, \forall n \in \mathbb{Z}$. As both $G$ and $G_n$ are continuous everywhere away from the endpoints of the intervals $\tilde{W}$ and $W_n$, there is a set $B$ of measure $O(\delta_0)$ such that for each $x$ outside of $B$ for every preimage $y_1$, with $G^{-1}(x) = y_1$, there is a preimage $y_2$, $G_n^{-1}(x) = y_2$ close to $y_1$. Since $|G_n| \leq K^3$, for each $x$ there are at most $[K^3] + 1$ inverse branches of $G_n$. One can also see that $|y_1 - y_2| \leq L\delta_0 / \gamma$. Next,
\[ P_{G_n} f(x) - P_G f(x) = E_0(x) + \sum_{y_1, G_n(y_1) = x} \frac{f(y_1)}{G'(y_1)} - \sum_{y_2, G(y_2) = x} \frac{f(y_2)}{G'(y_2)} \]
\[ = E_0(x) + \sum_{y_1, y_2} \left[ \frac{f(y_1)}{G'(y_1)} - \frac{f(y_2)}{G'(y_2)} \right] + \sum_{y_1, y_2} \left[ \frac{f(y_2)}{G'(y_1)} - \frac{f(y_2)}{G'(y_2)} \right]. \]

where $E_0$ is supported on $B$. In particular $\| E_0 \|_1 \leq C\delta_0$. Next,
\begin{equation}
\left| \frac{1}{G'(y_1)} - \frac{1}{G_n'(y_2)} \right| \leq \left| \frac{K_1(y_1 - y_2)}{G'(y_1) G'(y_2)} \right| + \left| \frac{1}{G'(y_2)} - \frac{1}{G_n'(y_2)} \right| \leq L \left( \frac{K_1 \delta_0}{\gamma^3} + \frac{\delta_0}{\gamma^2} \right).
\end{equation}

Note that we have $K_1 < \infty$. By the triangle inequality
\[ \int_{\mathbb{T} \setminus B} \left| \frac{f(y_1)}{G'(y_1)} - \frac{f(y_2)}{G_n'(y_2)} \right| dx \leq \int_{\mathbb{T} \setminus B} \left| \frac{f(y_1)}{G'(y_1)} - \frac{f(y_2)}{G(y_1)} \right| dx + \int_{\mathbb{T} \setminus B} \left| \frac{f(y_2)}{G'(y_1)} - \frac{f(y_2)}{G_n'(y_2)} \right| dx. \]
For the first term on the right, we have by (5.4)
\[
\int_{T \setminus B} \left| \frac{f(y_1)}{G'(y_1)} - \frac{f(y_2)}{G'(y_2)} \right| \, dx \leq \frac{1}{\gamma} \int_{T \setminus B} |f(y_1) - f(y_2)| \, dx \\
\leq \frac{2}{\gamma} \sup |y_1 - y_2| |V_T(f) \leq \frac{2L\delta_0}{\gamma^2} V_T(f).
\]
By (5.5)
\[
\int_{T \setminus B} \left| \frac{f(y_2)}{G'(y_1)} - \frac{f(y_2)}{G'(y_2)} \right| \, dx \leq \|f\|_\infty L \left( \frac{K}{\gamma^3} + \frac{1}{\gamma^2} \right).
\]
Since the measure of $B$ is of order $O(\delta_0)$, we also have
\[
\int_B |P_n f - \bar{P} f| \, dx \leq L_1 \|f\|_\infty |B| \leq L_2 \delta_0 \|f\|_\infty.
\]
Recall that $\|f\|_\infty \leq |f|_v$. Summarizing the estimates above, we finally obtain
$\|P_n f - \bar{P} f\|_1 \leq L' \delta_0 |f|_v$. □

5.3. Quenched drift and variance. For $k < m$, let
\[
a_{m,k} = \int_T [r_m(G_{m-1} \circ \cdots \circ G_{m-k}(x)) \, dx].
\]
For $k = m - 1$ we set $a_m = \int_T r_m(G_{1,m-1}x) \, dx$.

The properties of $a_m$ are summarized below.

**Lemma 5.2.** There are constants $C_1, C_2, C_3 > 0$ $0 < \theta_1, \theta_2, \theta_3 < 1$ such that
(a) For each $k$ the sequence $m \rightarrow a_{m,k}$ is stationary and $|a_{m,k} - a_m| < C_1 \theta_1^k$.
(b) There exists the limit $a = \lim_{m \rightarrow \infty} E(a_m)$ and moreover $|E(a_m) - a| \leq C_2 \theta_2^m$.
(c) $\text{Cov}(a_{n_1}, a_{n_2}) \leq C_3 \theta_3^{n_2-n_1}$.
(d) There exists $D^2 \geq 0$ such that $\left[ \int_T \tau_m(x) \, dx \right] - ma \leq N(0, D^2)$ as $m \rightarrow \infty$.
(e) For each $\varepsilon > 0$ there exists $C(\omega)$ such that for each $n_1, n_2 < 10N$ such that $|n_2 - n_1| \leq N^{3/4}$ we have
\[
\left| \int_T \tau_{n_2} \, dx - \int_T \tau_{n_1} \, dx - a(n_2 - n_1) \right| \leq C(\omega)N^{3/8+\varepsilon}.
\]

**Remark 5.3.** Note that we do not claim that $D$ in part (d) is not equal to zero.

**Proof.** (a) Note that for $m > k$
\[
\left| \int_T f_m(G_{m-1} \circ \cdots \circ G_{m-k}x) \, dx - \int_T f_m(G_{m-1} \circ \cdots \circ G_1x) \, dx \right| \\
\leq \int_T f_m[P_m \cdots P_{m-k}[1 - P_{m-k-1} \cdots P_1]1] \, dx \leq C_1 \theta^k,
\]
where the last estimate is due to the exponential mixing condition (Dec).
(b) By part (a)
\[
E(a_m) = E(a_{m,k}) + O(\theta^k) = E(a_{k,0}) + O(\theta^k).
\]
Hence, $|E(a_n) - E(a_m)| < C\theta^k$, for $n > m > k$, which shows that the sequence $\{E(a_n)\}_{n\geq 1}$ is a Cauchy sequence. Thus, we have the limit $a = \lim_{m\to\infty} E(a_m)$. Next, by letting $m \to \infty$ in (5.6) we get (b).

(c) Assume $n_1 > n_2$. By (b) we can write $|a_{n_1} - a_{n_1,n_1-n_2}| \leq C_1\theta^{n_2-n_1}$. Hence

$$E[(a_{n_1} - E[a_{n_1}]) (a_{n_2} - E[a_{n_2}])] = E[(a_{n_1,n_1-n_2} - E[a_{n_1}]) (a_{n_2} - E[a_{n_2}])] + C'\theta^{n_1-n_2}$$

where the last equality is due to that fact that $a_{n_1,n_1-n_2}$ and $a_{n_2}$ are independent random variables and $E[(a_{n_2} - E[a_{n_2}])] = 0$.

(d) follows from (c), see [24, Chapter XVIII].

(e) also follows from (c) as is shown in [20].

We also need the following result

Lemma 5.4 ([30]). There is a constant $\sigma$ such that $\lim_{n\to\infty} \frac{Var(\tau_n)}{n} = \sigma^2$ with probability 1.

5.4. Proof of Theorem 1.3 for Model A. Define $S(n) = E(\tau_n)$. This function is monotone so we consider an inverse function

$$(5.7) \quad Z(s) = \max(n: S(n) \leq s).$$

Denote

$$\hat{\sigma}_n = \sqrt{Var(\tau_{Z(n)})}, \quad z^*_n = \max_{0 \leq k \leq n} z_k, \quad b_n = Z(n).$$

Lemma 5.5. $S(n)$, $b_n$, and $\hat{\sigma}_n^2$ have linear growth. That is, there is a constant $C$ such that

$$\frac{1}{C} \leq \frac{S(n)}{n} \leq C, \quad \frac{1}{C} \leq \frac{b_n}{n} \leq C, \quad \frac{1}{C} \leq \frac{\hat{\sigma}_n^2}{n} \leq C.$$

Proof. Since $n \leq \tau_n \leq 3n$ we have $n \leq S(n) \leq 3n$. Therefore $n/3 \leq b_n \leq n$.

The lower bound on $\hat{\sigma}_n^2$ follows from Proposition 4.1, see the proof of Theorem 1.1.

The upper bound on $\hat{\sigma}_n^2$ follows from (Dec) since

$$\hat{\sigma}_n^2 = \sum_{n_1, n_2 \leq n} Cov(r_{n_1}, r_{n_2}) \leq \sum_{n_1, n_2 \leq n} C_1\theta^{n_2-n_1} \leq C_2n.$$

Let $a$ be as in Lemma 5.2 and consider

$$P \left( \frac{z^*_n - b_n}{(1/a)\hat{\sigma}_n} > t \right) = P \left( z^*_n > b_n + (1/a)t\hat{\sigma}_n \right).$$

By definition of $z^*_n$ for every $t \in \mathbb{R}$ we have

$$P(z^*_n > t) = P(\tau_t < n).$$

Hence

$$P \left( z^*_n > b_n + u\hat{\sigma}_n \right) = P(\tau_{b_n + u\hat{\sigma}_n} < n) = P \left( \frac{\tau_{[b_n + u\hat{\sigma}_n]} - E[\tau_{[b_n + u\hat{\sigma}_n]}]}{\sqrt{Var[\tau_{[b_n + u\hat{\sigma}_n]}]}} > \frac{n - E[\tau_{[b_n + u\hat{\sigma}_n]}]}{\sqrt{Var[\tau_{[b_n + u\hat{\sigma}_n]}]}} \right)$$

where

$$u = t/a.$$
We claim that
\[ \lim_{n \to \infty} \frac{n - \mathbb{E}[\tau_{[b_n + u\sigma_n]}]}{\sqrt{\text{Var}[\tau_{[b_n + u\sigma_n]}]}} = -t. \]

Indeed using Lemma 5.2(e) and the linear growth on \( b_n \) (Lemma 5.5) we obtain
\[ \mathbb{E}[\tau_{[b_n + u\sigma_n]}] = n + [au\sigma_n] + O(n^{0.4}) = n + [t\sigma_n] + O(n^{0.4}). \]

Hence the numerator of (5.8) is asymptotic to \( t\sigma_n \).

To analyze the denominator denote \( \tau_{m,n} = \sum_{k=m,n-1} r_k \) for \( m < n \). Then
\[ \text{Var}(\tau_n) = \text{Var}(\tau_m) + \text{Var}(\tau_{m,n}) + \text{Cov}(\tau_m, \tau_{m,n}) = \text{Var}(\tau_m) + \text{Var}(\tau_{m,n}) + O(1). \]

By the linear growth of variance we obtain \( \text{Var}(\tau_n) = \text{Var}(\tau_m) + O(|m - n|) \). It follows that the denominator of (5.8) is \( \sqrt{\sigma_n^2 + O(\sigma_n)} = \hat{\sigma}_n + O(1) \).

Combining the estimates for the numerator and denominator we obtain (5.8).

Combining (5.8) and Theorem 1.1 we arrive at
\[ \lim_{n \to \infty} P\left( \frac{z_n^* - b_n}{(1/a^{3/2})\sigma \sqrt{n}} > t \right) = \int_{-\infty}^{t} \frac{1}{\sqrt{2\pi}} e^{-u^2/2} du = \int_{-\infty}^{t} \frac{1}{\sqrt{2\pi}} e^{-u^2/2} du. \]

From the definition (5.7) it follows that \( \mathbb{E}(\tau_{Z(n)})/n \to 1 \), as \( n \to \infty \). Then consider
\[ \mathbb{E}\left( \frac{\tau_{Z(n)}}{Z(n)} \right) \mathbb{E}\left( \frac{Z(n)}{n} \right). \]

By Lemma 5.2 for almost all environments \( \lim_{n \to \infty} \mathbb{E}\left( \frac{\tau_{Z(n)}}{Z(n)} \right) = a \). Hence for almost all environments we also have
\[ \lim_{n \to \infty} \frac{Z(n)}{n} = \left( \lim_{n \to \infty} \mathbb{E}\left( \frac{Z(n)}{n} \right) \right) \left( \lim_{n \to \infty} \frac{\tau_{Z(n)}}{n} \right) = \frac{1}{a}. \]

Thus
\[ \lim_{n \to \infty} \frac{\hat{\sigma}_n^2}{n} = \lim_{n \to \infty} \frac{\text{Var}[\tau_{Z(n)}]}{n} = \lim_{n \to \infty} \frac{\text{Var}[\tau_{Z(n)}]}{Z(n)} \frac{Z(n)}{n} = \frac{\sigma^2}{a}. \]

Therefore (5.9) can be rewritten as
\[ \lim_{n \to \infty} P\left( \frac{z_n^* - b_n}{(1/a^{3/2})\sigma \sqrt{n}} > t \right) = \int_{-\infty}^{t} \frac{1}{\sqrt{2\pi}} e^{-u^2/2} du. \]

Splitting
\[ \frac{z_n - b_n}{\sqrt{n}} = \frac{z_n - z_n^*}{\sqrt{n}} + \frac{z_n^* - b_n}{\sqrt{n}} \]

and using that
\[ z_n^* - 1 \leq z_n \leq z_n^* \]

we obtain part (a).

(b) We write
\[ \frac{\tau_n - na}{\sqrt{n}} = \frac{\tau_n - \mathbb{E}[\tau_n]}{\sqrt{n}} + \frac{\mathbb{E}[\tau_n] - na}{\sqrt{n}} \]

By part (a), the first term is asymptotically normal. By Lemma 5.2 the second term is also asymptotically normal. Moreover, those terms are asymptotically independent since the second term depends only on the environment, while the distribution of the first term is asymptotically independent of the environment due to part (a). Since the
sum of two independent normal random variables is normal, \( \frac{\tau_n - na}{\sqrt{n}} \) is asymptotically normal with zero mean and variance
\[
\sigma^2 = \sigma^2 + D^2
\]
where \( \sigma \) is from Theorem 1.3(a) and \( D \) is from Lemma 5.2(d).

Let \( v = 1/a \). Then for \( x(n, t) := \left[ nv + v^3/2 \sqrt{n} \right] \) we have
\[
\text{(5.11)} \quad \mathbb{P} \left( \frac{z^*_n - nv}{v^3/2 \sqrt{n}} < t \right) = \mathbb{P} \left( \frac{\tau_{x(n, t)} - x(n, t)/v}{\sigma \sqrt{x(n, t)}} > \frac{n - x(n, t)/v}{\sigma \sqrt{x(n, t)}} \right).
\]

It follows from the above definition of \( x(n, t) \) that
\[
\lim_{n \to \infty} \frac{n - x(n, t)1/v}{\sigma \sqrt{x(n, t)}} = -t.
\]
Hence the CLT for \( z^*_n \) in the annealed case follows from the discussion above. Using (5.10) we obtain the annealed CLT for \( z_n \).

\[\square\]

6. Auxiliary results for Model B

We now turn to the proof of Theorem 1.1 (b). Due to the complexity of the dynamics the maps \( G_n \) will be more complicated. In particular, the walker can make arbitrary large number of backward steps before moving from site \( n \) to site \( n + 1 \). Thus for Model B the maps \( G_n \) have infinitely many branches and the first hitting times maps \( \tau_n \) are unbounded. So we can no longer apply Theorem 2.9. In the rest of the paper we verify that the transformations \( \{G_n\} \) and the maps \( \{\tau_n\}_{n \geq 1} \) satisfy the conditions of Theorem 3.1 which extends Theorem 2.9 to the case of unbounded observables.

6.1. Long itineraries. For each \( n \geq 1 \) and \( t \in D_n^{(2)} \) we consider the set of all \( x \in \mathbb{T} \) for which the walker, starting its journey from \((x, m)\), subsequently visits the sites \( m + s_1(t), m + s_2(t), \ldots, m + s_n(t) \), i.e. for all \( 0 \leq k \leq n \) we have

\[
\pi_\mathbb{Z}(F^k(m, x)) = m + \sum_{\ell=0}^{k} s_\ell(t),
\]

where \( F^0(m, x) = (m, x) \). We denote the set of all such \( x \) by \( A_{t,n,m} \). Observe that, for large values of \( a \) this set is not empty for arbitrary \( m, t \). Indeed, for large values of \( a \) any point \((z, x)\) will have a preimage inside any of the four intervals \((z - 1, W_{z-1}^c), (z - 1, W_{z-1}^c), (z + 1, W_{z+1}^c) \) and \((z + 1, W_{z+1}^c) \). This means that at each step, by choosing the backward image in an appropriate way, we can make the walker travel in an arbitrary prescribed way. This proves that any trajectory is possible in Model B.

Note that \( A_{t,n,m} \) can be written in the following way. For \( n = 1 \) \( A_{t,n,m} = W_{m,t_1} \), and for \( n > 1 \)

\[
x \in W_{s_0(t)+m,t_1},
\]

(6.1)

\[
T_{s_0(t)+m}(x) \in W_{s_1(t)+m,t_2},
\]

\[
\ldots
\]

\[
T_{s_{n-2}(t)+m} \circ T_{s_{n-3}(t)+m} \circ \cdots \circ T_{m}(x) \in W_{s_{n-1}(t)+m,t_n}.
\]
If $G_m$ in (1.4) is well defined for almost all $x \in \mathbb{T}$, then one can see that

$$G_m(x) = \sum_{n=1}^{\infty} \sum_{t \in R_n^{(2)}} T_{s_n-1}(t)+m \circ T_{s_n-1}(t)+m \circ \cdots \circ T_{s_0}(t)+m(x) \mathbb{I}_{A_{t,n,m}}(x).$$

Note that in (6.1) the maps $T_{s_k}(t)$ and the gates $W_{s_k(t),t_{k+1}}$ are perturbations of the map $\bar{T}(x) = ax \mod 1$ and the gates $\bar{W}_\pm$ (depending on the sign of $t_{k+1}$), so due to the general nature of our argument, we will assume that the walker starts at 0, that is $m = 0$, and replace the maps $T_{s_k}(t)$ and the gates $W_{s_k(t),t_{k+1}}$ with maps $T_k(x) = (ax + h_k(x)) \mod 1$ and gates $\bar{W}_{k,t_{k+1}}$ respectively. Thus the index $k$ in $\bar{W}_{k,t_{k+1}}$ no longer represents the position of the walker, but rather is a numbering parameter. However, we leave the sequence $\{t_k\}_{k=1}^n$ the same. Hence, for all $n \geq 1$ and $t \in D_n^{(2)}$ we can write

$$A_{t,n} = \bigcap_{\ell=0}^{n-1} (T_{1,\ell})^{-1}(W_{\ell,t_{\ell+1}}),$$

where $T_{0,0}^n(x) = x$.

Since the sets $(T_{1,\ell})^{-1}(W_{\ell,t_{\ell+1}})$ consist of finitely many disjoint intervals, one can check that the set $A_{t,n}$ satisfies the conditions of Definition 2.4. Thus the collection $\mathcal{I}(A_{t,n})$ is well defined.

**Lemma 6.1.** Let $\ell_1 < \ell_2$ and let $P_{\ell_1}$ and $P_{\ell_2}$ be Markov partitions of $T_{1,\ell_1}$ and $T_{1,\ell_2}$ respectively (see Definition 2.6). Then any interval from $P_{\ell_2}$ can intersect at most two intervals from $P_{\ell_1}$.

**Proof.** If some $p \in P_{\ell_2}$ intersected more than two elements from $P_{\ell_1}$ there would exist an element $p' \in P_{\ell_2}$ so that $p' \subset p$. Note that, by definition $T_{1,\ell_1}(p) = \mathbb{T}$. However

$$T_{1,\ell_2}(p) \neq \mathbb{T},$$

but since $p' \subset p$ and $\ell_1 < \ell_2$, we have $\mathbb{T} = T_{1,\ell_1}(p') \subset T_{1,\ell_2}(p)$ contradicting (6.3). \qed

The next propositions helps us to understand the long trajectories. Although it may not be visible at first glance, the argument is close to and was inspired by the classical growth lemma that is fundamental in the study of billiard maps.

**Proposition 6.2.** Let $t \in D_n^{(2)}$ and $\ell \geq 0$ be the number of $-1$s in $t$. Then, for all $a \in \mathbb{N}$ sufficiently large, there exists $k = k(a) \in \mathbb{N}$ and $\delta(a) > 0$ so that if $\delta \leq \delta(a)$ then there is a Markov partition $P_{n+1}$ of $T_{1,n+1}$ so that the number of Markov partition elements required to cover the set $A_{t,n}$ can be estimated as follows

$$\{p \in P_{n+1} : p \cap A_{t,n} \neq \emptyset\} \leq (k + 1)^l(a - k + 4)^{n-l}.$$  

Furthermore, each partition element contains at most one interval from $A_{t,n}$, i.e. for any $p \in P_n$

$$\# \{I \in \mathcal{I}(A_{t,n}) : I \cap p \neq \emptyset\} \leq 1,$$

and the following two bounds take place

$$a|\bar{W}_{-1}| \leq k \leq a|\bar{W}_{-1}| + 2,$$
and 
\begin{equation}
|A_{t,n}| \leq \frac{(k + 1)(a - k + 4)^{n-t}}{(a - \delta)^n}.
\end{equation}

**Proof.** The Markov partition of $T_\ell$ (see (2.6)) will be denoted by 
\begin{equation}
\mathcal{P}_\ell = \{P^\ell_{i,j} \}_{i=0}^{a-1}, \quad \ell \geq 1.
\end{equation}
To make it unique we assume that for all $\ell \geq 1$, $0 \leq i \leq a-1$ we have $T_\ell(\partial P^\ell_i) = \{0, 1\}$. The Markov partition of $\bar{T}$ will be denoted by $\{P^\ell_i\}_{i=0}^{a-1}$.

We now take $a$ so large and $\delta(a)$ so small that for any $\ell \geq 1$, there is $0 \leq i, j \leq a-1$ such that

$P^\ell_i \subset \text{Int } W_{\ell,1} \quad P^\ell_j \subset \text{Int } W_{\ell,-1},$

where Int stands for the interior of the set. Let $C_1$ and $C_{-1}$ be the minimal subsets of indexes $\{0, \ldots, a-1\}$ such that for all $\ell, k \geq 0$

\begin{equation}
\bar{W}_{k,1} \subset \text{Int } \left( \bigcup_{i \in C_1} P^\ell_i \right) \quad \bar{W}_{k,-1} \subset \text{Int } \left( \bigcup_{i \in C_{-1}} P^\ell_i \right).
\end{equation}

One can check that
\begin{equation}
\#\{C_1 \cap C_{-1}\} \leq 4.
\end{equation}

Note that we have equality in (6.10) iff $\bar{W}_{-1} = \left( \bigcup_{i \in C_{-1}} P_i \right)$, where $P_i$ are from the Markov partition of $\bar{T}$ defined in (6.8). Therefore, if

\begin{equation}
k(a) = k = \#C_{-1}
\end{equation}

then
\begin{equation}
\#C_1 \leq a - (k - 4).
\end{equation}

One can also check that
\begin{equation}
|\bar{W}_{-1}| \leq \frac{k}{a} \leq |\bar{W}_{-1}| + \frac{2}{a}.
\end{equation}

We now consider the set of all $x \in \mathbb{T}$ for which

\[x \in \bigcup_{i \in C_1} P^1_i, \quad T_1(x) \in \bigcup_{i \in C_2} P^2_i, \ldots, T_{1,n-1}(x) = T_{n-1}(T_{n-1}(\cdots (T_1(x)) \in \bigcup_{i \in C_n} P^n_i,\]

where $t = (t_1, \ldots, t_n)$. Set

\[B_n = \bigcap_{k=0}^{n-1} T_{1,k}^{-1} \left( \bigcup_{i \in C_{k+1}} P^{k+1}_i \right),\]

where $T_{1,0}(x) = x$. By (6.9) we have that $A_{t,n} \subset B_n$. Observe that for $1 < k < n - 1$ the collections $\mathcal{P}_k = \{T_{1,k}^{-1}(P^{k+1}_i) : i = 0, \ldots, a-1\}$ (we have $k$ preimages and each preimage is counted separately) constitutes a Markov partition for $T_{1,k+1}$. Indeed, for any $p \in \mathcal{P}_k$

\[T_{1,k+1}(p) = T_{k+1}(T_{1,k}(p)) = T_{k+1}(P^{k+1}_i) = \mathbb{T}.
\]

By assumption for each $0 \leq k \leq n$ there exists $P^k_i, P^k_j$ so that $P^k_i \subset W_{k,-1}$ and also $P^k_j \subset W_{k,1}$. This means that for $t = \pm 1$, $T_{1,k}^{-1}(W_{k,t})$ contains an element from $\mathcal{P}_k$ in
Then there exists two intervals $I_a$ and a Markov partition element from $P_n$ for which we have that for all $k = 0, \ldots, n$

$$T_{1,k}(p) \subset P_{k+1}, \text{for some } i \in C_{t_k}.$$  

Note that in term of the indexes $i$, this is the set of elements such that

$$\{i_1, \ldots, i_n : i_k \in C_{t_k}, 0 \leq k \leq n - 1\}.$$ 

The cardinality of this set can be bounded from above as follows

$$(\#C_{1})^\ell (\#C_{1})^{n-\ell} \leq k^\ell(a - (k - 4))^{n-\ell}.$$ 

Next, by the mean value theorem if $p = [a, b]$ then

$$1 = T_{1,n}(a) - T_{1,n}(b) = (T_{1,n})'(\zeta)(a - b).$$

Thus

$$1 = |(T_{1,n})'(\zeta)||p|.$$ 

Hence

$$|p| = \frac{1}{|(T_{1,n})'(\zeta)|} \leq \frac{1}{|a + h_n(T_{1,n-1}(\zeta)) \cdots (a + h_1(T_{1}(\zeta)))|} \leq \frac{1}{(a - \delta)^n}. $$

This implies

$$|A_{t,n}| \leq \frac{(k + 1)^\ell(a - k + 3)^{n-\ell}}{(a - \delta)^n}.$$ 

Next note that (6.6) follows from (6.13).

We now show (6.5). For this we observe that each interval $I \in \mathcal{I}(A_{t,n})$ contains a Markov partition element from $P_{n-1}$ in its interior. Indeed, assume the opposite. Then there exists two intervals $I_1, I_2 \in \mathcal{I}(A_{n,\ell})$, so that for some $p \in P_{n-1}$ we have

$$I_1 \cap p \neq \emptyset \text{ and } I_2 \cap p \neq \emptyset.$$ 

Then there would exist $\ell < n$ and two disjoint intervals $J_1, J_2 \in \mathcal{I}((T_{1,\ell})^{-1}(W_{t,n+1}))$, so that

$$I_1 \subset J_1 \text{ and } I_2 \subset J_2.$$ 

Then clearly dist$(J_1, J_2) < |p|$, since one of their endpoints belongs to $p$. Next, by construction there should be a Markov partition element $p' \in P_{\ell}$ such that $p'$ is between $J_1$ and $J_2$. This means that $p' \subset p$. However this is not possible, since $p$ will also intersect the partition elements that are neighboring with $p'$. But this means that $p$ intersect at least 3 partition element from $P_{\ell}$ which is not possible due to Lemma 6.1. This proves (6.5). \hfill \Box

**Proposition 6.3.** Assume $|W_{-1}| < 1/2$. Then there exists $\rho < 1$ and $C > 0$ such that for every $t = (t_1, \ldots, t_n) \in D_{n}^{(2)}$, with $t_1 + \cdots + t_n \leq 1$, we have

$$|A_{t,n}| \leq C\rho^n 2^{-n}.$$ 

**Proof.** Let $l$ be the number of times the walker goes left during his journey. By (6.7)

$$|A_{t,n}| \leq \frac{(k + 1)^\ell(a - k + 4)^{n-\ell}}{(a - \delta)^n}.$$
Next, due to $l \geq \frac{n-1}{2}$ we have that

\[
\frac{(k + 1)^l(a - k + 4)^{n-l}}{(a - \delta)^n} \leq C \frac{(k + 1)^{\frac{3}{2}}(a - k + 4)^{\frac{3}{2}}}{(a - \delta)^n}
\]

where we have used that $k < a - k + 4$ for large $a$, which holds since $|W_{-1}| < |W_1|$. Rewrite

\[
2^n \frac{(k + 1)^{\frac{3}{2}}(a - k + 4)^{\frac{3}{2}}}{(a - \delta)^n} = \left( \frac{4(k + 1)^{1/2}(a - k + 4)^{1/2}}{(a - \delta)} \right)^n.
\]

Next

\[
\lim_{a \to \infty, \delta \to 0} \frac{4(k + 1)^{1/2}(a - k + 4)^{1/2}}{(a - \delta)} = 4|W_{-1}|(1 - |W_{-1}|) < 1
\]

where the last inequality is due to $|W_{-1}| < \frac{1}{2}$.

Thus (6.15) holds with $\rho = \frac{4(k + 1)^{1/2}(a - k + 4)^{1/2}}{(a - \delta)}$. □

Lemma 6.4. If $|\bar{W}_{-1}| < 1/2$, then for $a \in \mathbb{N}$ sufficiently large and $\delta = \delta(a)$ small, the maps $\{G_n\}_{n \in \mathbb{Z}}$ are defined almost everywhere.

Proof. We need to show that

\[
\text{mes} \{x : z_n(x) \leq 0, \forall n \geq 0\} = 0.
\]

Since the number of all trajectories of length $n$ is equal to $2^n$, then in view of Proposition 6.3 we can write

(6.16) \[
\text{mes} \{x : z_n(x) \leq 0\} \leq 2^n \rho^n \leq \rho^n.
\]

This completes the proof. □

6.2. Short itineraries. For $t \in D_n^2$ and gates $\{W_{k,t_{k+1}}\}_{k=0}^n$. Recall (6.2). Let

(6.17) \[
H_{t,n} = \bigcap_{k=0}^{n-1} (\bar{T}^k)^{-1}(\bar{W}_{t_{k+1}}),
\]

where $\bar{T} = ax \ (\text{mod} \ 1)$.

Proposition 6.5. Given $n \geq 1$ and $t \in D_n^{(2)}$, we have that

(a) $\#\mathcal{I}(A_{t,n}) \leq 4a^{n-1}$.

(b) For every $\varepsilon > 0$ there exists $\bar{\delta}(a)$ such that if $\delta \leq \bar{\delta} = \bar{\delta}(a)$ for every closed interval $I$ in the collection $\mathcal{I}(H_{t,n})$ there is a unique $J \in \mathcal{I}(A_{t,n})$, so that $|I \triangle J| < \varepsilon$. Moreover, $\bar{\delta}$ can be taken so small that if $\delta < \bar{\delta}$ then for every $x \in I \cap J$ we have

(6.18) \[
|T_{1,n}(x) - T^n(x)| \leq \varepsilon, \quad \left| \frac{1}{(T_{1,n}(x))'} - \frac{1}{(T^n(x))'} \right| \leq \varepsilon,
\]

and

\[
|A_{t,n} \triangle H_{t,n}| \leq \varepsilon.
\]
Proof. It follows from the definition that the boundary of $A_{t,n}$ consists of

$$\partial A_{t,n} \subset \bigcup_{k=0}^{n-1} (T_{1,k})^{-1}(\partial W_{k,t_{k+1}})).$$

In the same way

$$\partial H_{t,n} \subset \bigcup_{k=0}^{n-1} (\bar{T}^k)^{-1}(\partial \bar{W}_{t_{k+1}}).$$

Note that $\#(T_1^k)^{-1}(W_{k,t_{k+1}}) \leq 2a^k$. Hence

$$\#\partial A_{t,n} \leq 2 + 2a + \cdots + 2a^{n-1} = \frac{a^n - 1}{a - 1} \leq 4a^{n-1},$$

for $a \geq 2$. This proofs part (a).

Given an arbitrary $\varepsilon > 0$ we can take $\delta$ so small that $|T_{1,n}(x) - \bar{T}^n(x)| < \varepsilon$ for all $x \in \mathbb{T}$ (the second statement in (6.18) is also similar). Clearly the sets $\partial(\partial(W_{k,t_{k+1}}))$ and $\partial(\bar{T}^k)^{-1}(\partial \bar{W}_{t_{k+1}})$ will be close to each other under small perturbations and for given $k$. Hence, for each $I \in \mathcal{I}(H_{t,n})$ its endpoints will change a little under small perturbations of $\bar{T}$. Thus we obtain that for some $J \in \mathcal{I}(A_{t,n})$ we have $|I \triangle J| < \varepsilon$. Observe, that $\mathcal{I}(A_{t,n})$ may contain other intervals too, that come into existence under small perturbations of the maps $\bar{T}^k$. However these intervals occupy a set of small measure. Note that for any $k \geq 0$

$$A_{t,n} \triangle H_{t,n} \subset (T_{1,k})^{-1}(W_{k,t_{k+1}})) \triangle ((\bar{T}^k)^{-1}(\bar{W}_{t_{k+1}})).$$

Thus for $\delta$ sufficiently small $|A_n \triangle A| < \varepsilon$. \qed

Lemma 6.6. If $a$ is sufficiently large and $\delta(a)$ is small enough then

$$\left| \left( \frac{1}{(T_{1,n}(x))'} \right)' \right| = \left| \frac{(T_{1,n}(x))''}{(T_{1,n}(x))'}^2 \right| < D,$$

where $D := \sup_{k \geq 1} \sup_{x \in \mathbb{T}} |h''_k(x)| < \infty$.

Proof. We have

$$(T_{1,n}(x))' = T'_n(T_{1,n-1}(x))T'_{n-1}(T_{1,n-2}(x)) \cdots T'_1(x).$$

Hence

$$(T_{1,n}(x))'' = \sum_{k=1}^{n} T'_n(T_{1,n-1}(x)) \cdots T''_k(T_{1,k-1}(x))(T_{1,k-1}(x))' = \sum_{k=1}^{n} T'_n(T_{1,n-1}(x)) \cdots T''_k(T_{1,k-1}(x))(T_{1,k-1}(x))' 2.$$ 

We rewrite this as follows

$$(T_{1,n}(x))'' = \sum_{k=1}^{n} \frac{(T_{1,n}(x))'}{T_n'(T_{1,k-1})} T''_k(T_{1,k-1})T_{1,k-1}(x)'.$$ 

Thus

$$|\frac{(T_{1,n}(x))''}{(a - \delta)} D |T_{1,k-1}(x)'|.$$
Hence
\[
\left| \frac{(T_{1,n}(x))''}{(T_{1,n}(x))'} \right| \leq \sum_{k=1}^{n} \frac{D}{(a-\delta)} \frac{|T_{1,k-1}(x)'|}{|T_{1,n}(x)'|} \leq \sum_{k=1}^{n} \frac{D}{(a-\delta)^{n-k+1}} \leq \sum_{m=1}^{\infty} \frac{D}{(a-\delta)^{m}} = \frac{D}{a+1-\delta}
\]
The last sum is smaller than \(D\) if \(\bar{\delta} < 1\).

\[\square\]

7. Properties of transfer operators

Proposition 7.1. Let \(a\) be as in Lemma 6.4. Then there is \(\bar{\delta}(a)\), such that if \(\delta < \bar{\delta}(a)\), then the collection \(\{P_n\}_{n \geq 1}\) satisfies property (LY): there exists a constant \(C(a, \bar{\delta}) > 0\) such that for every \(n \geq 1\)

\[(7.1) \quad V(P_n \alpha) \leq \frac{3}{4} V(f) + C \|f\|_1,\]

Proof. Throughout the proof, instead of the notations \(G_n\) and \(P_n\), we will use the generic notations \(G\) and \(P\). As earlier, for \(A_{t,n}\) let \(\mathcal{I}(A_{t,n})\) be the set defined in Definition 2.4.

As in the proof of Lemma 3.4, \(V(Pf) \leq I + II\) where \(I\) and \(II\) are given by (3.5).

Similarly to the proof of (3.4)

\[(7.2) \quad I \leq \frac{V(f)}{a-\delta} + L\|f\|_1 \quad \text{where} \quad L = \sup_{x \in \mathbb{T}} \frac{|G''(x)|}{|(G'(x))^2|}.\]

By Proposition 6.6 \(L \leq D\).

Note that for \(x \in A_{t,n}\) we have \((a-\bar{\delta})^n \leq |G'(x)| \leq (a+\bar{\delta})^n\). For large values of \(n\) we estimate \(II\) using (3.8) taking \(I = \mathbb{T}\). Then for each interval \(I_j \in \mathcal{I}(A_{t,n})\) we have

\[(7.3) \quad \left| \left( \frac{f}{G'} \right)(\sigma_i \alpha_i) \right| + \left| \left( \frac{f}{G'} \right)(\sigma_i \beta_i) \right| \leq \frac{1}{(a-\delta)^n} V_T(f) + \frac{2}{(a-\delta)^n} \int_{\mathbb{T}} |f|dx \leq \frac{2}{(a-\delta)^n} (V(f) + \|f\|_1) = \frac{2}{(a-\delta)^n} |f|_{BV}.
\]

Hence, by Proposition 6.3

\[(7.4) \quad \sum_{n=N}^{\infty} \sum_{t \in K_{n}^{(2)}} \sum_{I \in \mathcal{I}(A_{t,n})} \left| \left( \frac{f}{G'} \right)(\sigma_i \alpha_i) \right| + \left| \left( \frac{f}{G'} \right)(\sigma_i \beta_i) \right| \leq \sum_{n=N}^{\infty} \frac{\# \mathcal{I}(A_{t,n})}{(a-\delta)^{n+1}} |f|_{BV} \leq \sum_{n=N}^{\infty} \rho^n |f|_{BV}.
\]

We now consider the terms \(n < N\). First, for \(I \in \mathcal{I}(A_{t,n})\) with \(|I| > \frac{1}{(a-\delta)^n}\) we repeat the argument from the proof of Lemma 3.4 and divide \(I\) into intervals \(\{J\}\) of length \(\frac{1}{2(a-\delta)^{n+1}}\) and an interval \(J'\) with \(\frac{1}{2(a-\delta)^{n+1}} < |J'| < \frac{1}{(a-\delta)^{n+1}}\). Then, we use the estimate (3.7) with \(\gamma \geq (a-\delta)^n\) to obtain

\[
\left| \frac{f}{G'} \right|(\sigma_j \alpha_j) + \left| \frac{f}{G'} \right|(\sigma_j \beta_j) \leq \frac{V_J(f)}{(a-\delta)^n} + \frac{4(a-\delta)^{n+1}}{(a-\delta)^n} \int_{I_J} |f(x)|dx.
\]
Summing over all such intervals \( I \in \mathcal{I}(A_{t,n}) \), for all \( n \leq N \) and \( t \in \mathbb{R}_n^2 \) we get

\[
\left( \frac{a}{a - \delta} \right) V_t(f) + C_N(a, \delta) \| f \|_1.
\]

Now it remains to deal with intervals with lengths \( |I| < \frac{1}{a - \delta} \). To this end we again use the bound (7.3). Then, in view of Proposition 6.5(a)

\[
\sum_{n \leq N} \sum_{I: |I| \leq \frac{1}{a - \delta}^n} V(f(\sigma_j x) \frac{1}{|G'(\sigma_j x)|} 1_{G(I)}) \leq \frac{4a^{n-1}}{(a - \delta)^n} \| f \|_{BV}.
\]

Summing over \( n < N \)

\[
\sum_{n \leq N} \sum_{I: |I| \leq \frac{1}{a - \delta}^n} V(f(\sigma_j x) \frac{1}{|G'(\sigma_j x)|} 1_{G(I)}) \leq \frac{4}{(a - \delta)} \sum_{n \leq N} 2^n \left( \frac{a}{a - \delta} \right)^{n-1} \| f \|_{BV} \leq \frac{2^{N+3}}{(a - \delta)} \| f \|_{BV}
\]

if \( \delta \) is small enough.

Now, taking \( N \) large in (7.4), the slope \( a \) large in (7.6) and taking (7.5), (7.2) into account we obtain (7.1). \( \Box \)

Recall the definition of \( r_n \) in (1.4). Observe now that for any \( t \in \mathbb{R}_n^2 \) and \( k \geq 0 \) we have

\[
r_m(x) = 2k + 1 \quad \text{for any} \quad x \in A_{t,2k+1,m}.
\]

Below \( P \) and \( r \) will stand for a generic transfer operator \( P_m \) and the first hitting times map \( r_m \) for \( m \in \mathbb{Z} \). As earlier we will drop the index \( m \).

**Proposition 7.2.** There exists \( \delta_0 \) so that if \( \delta < \delta_0 \) then there exists \( D > 0 \) such that

\[
|P(f)|_{BV} \leq D|f|_{BV},
\]

and

\[
|P(rf)|_{BV} \leq D|r|_{BV}, \quad |P(r^2 f)|_{BV} \leq D|f|_{BV}, \quad \forall f \in BV.
\]

**Proof.** We follow the argument of Proposition 7.1. If in (7.4) instead of \( f \) we consider the function \( rf \), then using an identity \( V_I(af) = a V_I(f) \), valid for \( a \in \mathbb{R} \) and an interval \( I \), and in view of (7.7) we obtain

\[
V(P(rf)) \leq \sum_{n=1}^{\infty} C_n a^n |f|_{BV}.
\]

Thus

\[
V(P(rf)) \leq C_2 |f|_{BV}.
\]

Observe also that

\[
\int_T |P(rf)| dx \leq \int_T P(r|f|) dx = \int_T r|f| dx \leq |f|_{BV} \int_T r dx.
\]
Thus by (6.7)
\[ \int_T rdx \leq \sum_{\ell=0}^{\infty} \sum_{t \in P^{(2)}_{2\ell+1}} (2\ell + 1)A_{t,2\ell+1} < C_1 \sum_{\ell=0}^{\infty} (2\ell + 1)\rho^\ell < \infty. \]

Combining the above estimates we get
\[ |P(rf)|_{BV} = V(P(rf)) + \| P(rf) \|_1 \leq D|f|_{BV}. \]
The estimates for \( |P(r^2f)|_{BV} \) and \( |P(f)|_{BV} \) are similar. \( \square \)

Let \( P, r \) and \( \bar{P}, \bar{r} \) be the transfer operator and the first hitting times map of the perturbed and unperturbed cases respectively.

**Proposition 7.3.** Given \( \varepsilon > 0, \delta_0(a) \) can be taken so small that if \( \delta \leq \delta_0(a) \), then
\begin{align*}
(7.9) & \quad \| P(f) - \bar{P}(f) \|_1 \leq \varepsilon|f|_{BV}, \quad \| P(f) - \bar{P}(f) \|_2 \leq \varepsilon|f|_{BV} \quad f \in BV \\
(7.10) & \quad \| P(rf) - \bar{P}(\bar{r}f) \|_1 \leq \varepsilon|f|_{BV}, \quad \| P(rf) - \bar{P}(\bar{r}f) \|_2 \leq \varepsilon|f|_{BV} \quad f \in BV.
\end{align*}
For \( \delta \) small, we will also have
\begin{equation}
(7.11) \quad \| r - \bar{r} \|_2 \leq \varepsilon.
\end{equation}

**Proof.** Note that if we have the first statement in (7.9), then by Proposition 7.2
\[ \| \bar{P}(\bar{r}f) - P(rf) \|_2 \leq \sqrt{\| P(\bar{r}f) - P(rf) \|_{BV} \| P(\bar{r}f) - P(rf) \|_1} \]
\[ \leq \sqrt{2D|f|_{BV} \int_T |\bar{P}(rf) - \bar{P}(\bar{r}f)|dx \leq \sqrt{2D\varepsilon|f|_{BV}}. \]

Hence, the second statement in (7.9) follows from the first. In a similar way we can show that the second statement in (7.10) follows from the first.

We will show the first estimate in (7.10), the proof of (7.9) is similar. We have
\[ P(rf)(x) = \sum_{y:G(y)=x} \frac{r(y)f(y)}{|G'(y)|}. \]

For given \( N \in \mathbb{N} \) we write
\[ \| P(rf) - \bar{P}(\bar{r}f) \|_1 \leq \| P(1_{[1,N]}(r)f) - \bar{P}(1_{[1,N]}(\bar{r})f) \|_1 \]
\[ + \| P(1_{(N,\infty)}(r)f) \|_1 + \| \bar{P}(1_{(N,\infty)}(\bar{r})f) \|_1. \]
By Lemma 2.7
\[ \| P(1_{(N,\infty)}(r)f) \|_1 = \| 1_{(N,\infty)}(r)f \|_1 \leq |f|_{BV} \| 1_{[N,\infty)}(r) \|_1. \]
For the last expression we have by (6.16)
\[ \| 1_{(N,\infty)}(r) \|_1 \leq C \sum_{n>N} n\rho^n. \]
Hence
\begin{equation}
(7.12) \quad \| 1_{(N,\infty)}(r)fP(rf) - 1_{(N,\infty)}(\bar{r})\bar{P}(\bar{r}f) \|_1 \leq 2C \sum_{n>N} n\rho^n |f|_{BV}.
\end{equation}
Take \( N \) so large that \( 2C \sum_{n>N} np^n \leq \varepsilon \). Then it remains to study the term
\[
\| P(1_{[1,N]}(r)f) - P(1_{[1,N]}(\bar{r})f) \|_1.
\]

For each \( n \in \mathbb{N} \) and \( t \in R^{(2)}_{n} \) consider the sets \( A_{t,n} \) and \( H_{t,n} \) defined in (6.2) and (6.17). By Proposition 6.5, we have that for any \( I \in \mathcal{I}(H_{t,n}) \) there exists \( J \in \mathcal{I}(A_{t,n}) \) such that for any \( \varepsilon > 0 \), \( \delta_0 \) can be taken so small that if \( \delta < \delta_0 \), then for all \( x \in I \cap J \)
\[
|G(x) - \bar{G}(x)| \leq \varepsilon.
\]

We now consider the restrictions of transfer operators \( P \) and \( \bar{P} \) onto the set \( I \cap J \). Analogous to the proof of Lemma 5.1 we can consider a pairing of the preimages of \( x \). On the set \( A \) of \( x \) for which there is pairing, we can write
\[
(7.13) \quad (Pf(x) - \bar{P}f(x)) \bigg|_{x \in A} = \left( \sum_{y_1 \in \triangle \cap G(y_1) = x} \frac{\bar{r}f(y_1)}{G'(y_1)} - \sum_{y_2 \in \triangle \cap G(y_2) = x} \frac{rf(y_2)}{G'(y_2)} \right)
\]

We have that \( \gamma = (a - \delta_0) \leq G'(x) |_{A_{t,n}} \). Then by Proposition 6.6,
\[
|G''(x)| \leq D|G'(x)| \leq D(a + \delta)^n = K_1(n)
\]
and noting that \( |y_1 - y_2| < \frac{L_\delta}{\gamma} \), we can repeat the computations of Lemma 5.1 and obtain
\[
(7.14) \quad \int_A \left| \frac{\bar{r}f(y_2)}{G'(y_1)} - \frac{rf(y_2)}{G'(y_2)} \right| dx \leq n\|f\|_\infty \delta_0 L \left( \frac{K_1(n)}{\gamma^3} + \frac{1}{\gamma^2} \right).
\]

If there is no pairing between the preimages of \( x \), then the preimage of \( x \) lies in the set \( A_{t,n} \cap H_{t,n} \).

By Proposition 6.5(b) we have that \( |A_{t,k} \Delta H_{t,k}| < \varepsilon \), for \( k \leq N \), if \( \delta \leq \delta_0 \). Hence, the measure of the points in \( x \in T \) which have a preimage in \( A_{t,k} \Delta H_{t,k} \), with \( k \leq N \), can be estimated as follows
\[
|G(A_{t,k} \setminus H_{t,k})| \leq |T_{1,k}(A_{t,k} \setminus H_{t,k})| \leq (a + \delta_0)^k |A_{t,k} \setminus H_{t,k}| \leq \varepsilon (a + \delta_0)^N
\]
and respectively
\[
|\bar{G}(H_{t,k} \setminus A_{t,k})| \leq a^k |H_{t,k} \setminus A_{t,k}| \leq \varepsilon a^N.
\]
Since for fixed \( k \) and \( t \) every \( x \) can have at most \( a^k \) many preimages under \( T_{1,k} \), \( k \leq a \), then we can estimate the measure of the points \( x \) for which there is no pairing between its preimages as follows
\[
(7.15) \quad \left\| \sum_{\{x : \exists y, \text{ such that } y \in A_{t,k} \setminus H_{t,k}, G(y) = x\}} \frac{r(y)f(y)}{|G'(y)|} \right\|_1 \leq \frac{N\|f\|_\infty}{(a - \delta_0)^n} a^k (a + \delta_0)^N \varepsilon,
\]
in a similar way
\[
(7.16) \quad \left\| \sum_{\{x : \exists y, \text{ such that } y \in H_{t,k} \setminus A_{t,k}, G(y) = x\}} \frac{\bar{r}(y)f(y)}{|G'(y)|} \right\|_1 \leq \frac{N\|f\|_\infty}{(a - \delta_0)^n} a^k a^N \varepsilon.
\]

Summing the above for all \( k \leq N \), \( t \in R^{(2)}_k \) and considering (7.12) and (7.14) we arrive at the estimate
\[
\| \bar{P}(\bar{r}f) - P(rf) \|_1 \leq C\varepsilon |f|_{BV}.
\]
Since $\varepsilon$ was arbitrary, (7.10) follows.

To see (7.11), note that for $x \in I \cap J$ we have that

$$\tilde{\tau}(x) = \tau(x) = n.$$ 

Hence

$$\|\tilde{\tau} - \tau\|_2 \leq \|1_{(N, \infty)}(\tau)\|_2 + \|1_{(N, \infty)}(\tilde{\tau})\|_2 + \|1_{[1,N]}(\tilde{\tau}) - 1_{[1,N]}(\tau)\|_2$$

$$\leq 2C_1 \sum_{\ell=N}^\infty \ell^2 \rho^\ell + \sum_{n=1}^N 2^n N \sqrt{|A_{t,n} \triangle H_{t,n}|}.$$ 

Taking $N$ large and $\delta_0$ sufficiently small, we get (7.11). \qed

**Proposition 7.4.** Let

$$\tilde{r}_k = r_k(G_{1,k-1}(x)) - \int_T r_k(G_{1,k-1}(x))dx, \quad S_n(x) = \sum_{k=1}^{n-1} \tilde{r}_k.$$ 

Assume that $\|S_n\|^2 = \sigma_n^2 \geq Dn$, for all $n \geq 1$. Then for arbitrary $\varepsilon > 0$

$$\lim_{n \to \infty} \frac{\sum_{k=1}^n \int_T \tilde{r}_k^2(x) 1_{[\varepsilon \sigma_n, \infty)}(\tilde{r}_k^2(x)) dx}{\sigma_n^2} = 0.$$ 

**Proof.** We have

$$\sup_{k \geq 1} \int_T r_k(G_{k-1} \circ \cdots \circ G_1(x))dx \leq \sup_{k \geq 1} \left( \|P_{1,k-1}1\|_\infty \int_T r_k(x)dx \right) = R < \infty.$$ 

Note that

$$\tilde{r}_k^2(x) \leq 2(r_k^2(x) + R^2).$$ 

Also, if $2R \leq r_k(x)$ then $\tilde{r}_k^2(x) \geq (r_k(x) - R)^2 \geq \frac{r_k^2(x)}{4}$. Since $\sigma_n$ tends to infinity as $n \to \infty$, then

$$\int_T \tilde{r}_k^2(x) 1_{[\varepsilon \sigma_n, \infty)}(\tilde{r}_k^2(x)) dx \leq 2 \int_T \left( r_k^2(x) + R^2 \right) 1_{[4\sqrt{\varepsilon \sigma_n}, \infty)}(r_k^2(x)) dx$$

$$\leq 2 \sum_{k=[2\sqrt{\varepsilon \sigma_n}]}^{\infty} \sum_{t \in R_k^{(2)}} (k^2 + R^2) |A_{t,k}|.$$ 

For large $k$ we can write $k^2 + R^2 \leq 2k^2$. Then

$$2 \sum_{k=[2\sqrt{\varepsilon \sigma_n}]}^{\infty} \sum_{t \in R_k^{(2)}} (k^2 + R^2) |A_{t,k}| \leq C \sum_{k=[\sqrt{2\varepsilon \sigma_n}]} k^2 \rho^k.$$ 

Since $\sigma_n^2 \geq Dn$, the sum in the numerator of (7.17) tends to 0 uniformly in $k$ as $n \to \infty$. This finishes the proof of proposition. \qed

**Lemma 7.5.** (a) The maps $\{G_n\}_{n \in \mathbb{Z}}$ for Model B satisfy property (C) from §3.3.

(b) for each $n \in \mathbb{Z}$ there is an interval $J_n \subseteq \mathbb{T}$ such that $G_n(J_n) = \mathbb{T}$ and sup $\sup_{n \geq 1, x \in J_n} |G_n'(x)| \leq K_0$, for some finite $K_0.$
(c) There exists \( \sigma > 0 \) such that
\[
P_n \ldots P_1 1(x) \geq \sigma,
\]
for any \( x \in \mathbb{T} \), and all \( n \geq 1 \).

**Proof.** First note that by the choice of slope \( a > 1 \) for every \( n \geq 1 \) we have that the the gate \( W_{n,1} \) contains a Markov partition element of \( T_n \). Since \( G_n|_{W_{n,1}} = T_n|_{W_{n,1}} \), we obtain part (b) choosing \( J_n = W_{n,1} \).

Since part (c) follows from parts (a) and (b) due to Proposition 3.6(a), it only remains to prove property (C).

We first show that there is \( k = k(|I|) \), so that
\[
\pi_T(F^k(I, 0)) = \mathbb{T}.
\]

The idea of the proof of this fact is analogous to Lemma 3.7 and is based on complexity estimates. Without loss of generality we can assume that \( n = 1 \) and that \( I \subset W_{1,1} \) or \( I \subset W_{1,-1} \). We now construct a sequence of intervals \( \{I_n\}_{n \geq 1} \) and positions \( \{z_n\}_{n \geq 1} \), \( z_n \in \mathbb{Z} \) \( n \geq 1 \), such that \( I_n \subset W_{z_n,1} \) or \( I_n \subset W_{z_n,-1} \) and \( \pi_T(F(z_n, I_n)) = z_{n+1} \). \( \pi_T(F(z_n, I_n)) \) is divided by the singularity points \( \partial W_{z_{n+1}} \) into continuity components and \( I_n+1 \) is chosen to be the largest component. Similar to Lemma 3.7 we have that
\[
|I_{n+1}| \geq \frac{(a - \delta_0)|I_n|}{3}.
\]
Hence, if \( (a - \delta_0) > 3 \) then the lengths of \( |I_n| \) will grow exponentially fast. Hence, for some \( n \), the interval \( \pi_T(F(z_n, I_n)) \) will cover two singularity points at once, i.e. we will have
\[
W_{z_{n+1},1} \subset \pi_T(F(z_n, I_n)) \text{ or } W_{z_{n+1},-1} \subset \pi_T(F(z_n, I_n)).
\]
This means that \( \pi_T(F(z_n, I_n)) \) will contain a gate partition in its interior. Note also that \( n < C \ln(1/|I|) \). If now as \( I_{n+1} \) we chose the corresponding gate interval and take into account that each gate contains a Markov partition element of \( T_{z_n} \) in its interior, it will follow that \( \pi_T(F(z_{n+1}, I_{n+1})) = \mathbb{T} \), implying (7.19).

Observe now that from this time onward, we can choose the interval \( I_{n+k} \) to be the forward gate of \( z_{n+k} \), i.e. \( I_{n+k} = W_{z_{n+k},1} \). But then \( z_{n+k} = z_{n+1} + k \), for \( k \geq 2 \) and \( \pi_T(F(z_{n+k}, I_{n+k})) = \mathbb{T} \). Hence, there will be a time \( \ell \) and a position \( m > 1 \) which will be visited by the walker for the first time and to reach there the walker will have to make no more then \( C' \ln(1/|I|) \) steps. We will then have \( \pi_T(F^d(1, I)) = \mathbb{T} \) and
\[
G_{1,m}(I) = \mathbb{T}.
\]
This proves the claim. Clearly \( m < C \ln(1/|I|) \). Observe that by taking \( m \) large we can also make the time \( m \) in (7.21) uniform for all intervals \( I \) with the given length. It also follows from our discussion that for every \( x \in \mathbb{T} \) there exists \( y \in I \) such that \( G_{1,m}(y) = x \) and
\[
|G'(y)| \leq (a + \bar{\delta})^s,
\]
where \( s \leq C' \ln(1/|I|) \). This finishes the proof of property (C).

\[\square\]

**Proposition 7.6.** The transfer operator \( \bar{P} \) of \( \bar{G} \) satisfies property [Dec].

**Proof.** This follows from Proposition 3.6(b), Lemma 7.5 and Proposition 7.1. \[\square\]

**Proposition 7.7.** The variance of \( \tau_n \) grows linearly.
Proof. According to the discussion at the beginning of Lemma 7.5, there exists $x_0$, such that $\bar{G}(x_0) = x_0$ and $\bar{r}(x_0) = 1$. Then $\int_T \bar{r}hdx > \int_T hdx = 1 = \bar{r}(x_0)$. By Proposition 7.2 $\bar{P} \in BV$. Thus, by Lemma 4.2 $\bar{r}$ is not cohomologous to zero and Proposition 4.1 gives the result. □

8. PROOF OF THE MAIN RESULTS FOR MODEL B.

8.1. Proof of Theorem 1.1(b). We will check the conditions of Theorem 3.1 for the sequence $\{G_n\}_{n=1}^\infty$. Recall that

$$\tau_n(x) = \sum_{k=0}^{n-1} r_k(G_{k-1} \circ \cdots \circ G_0x).$$

By Proposition 7.1 both $\bar{P}$ and $P_n$, $n \geq 1$ satisfy (LY) for all $\delta$ sufficiently small and $a$ large. By Proposition 7.3 $P_n$ and $\bar{P}$ are close in $d_1$ norm, when $\delta$ is small. By Proposition 7.6 $\bar{P}$ satisfies (Dec). Hence, by Proposition 2.8 (Dec) holds in a $d_1$ neighborhood of $\bar{P}$. Thus, we have (Dec) for the collection $\{P_n\}_{n \in \mathbb{Z}}$ for sufficiently small $\delta$. (Min) for $P^n1$ follows from Lemma 7.5. Next, (3.1) follows from Proposition 7.7 the variance of $\tau_n$ grows linearly. Finally, (3.2) follows from Proposition 7.4. Now Theorem 1.1(b) follows from Theorem 3.1. □

8.2. Backtracking.

Lemma 8.1. (a) Denote $z^*_n = \max_{0 \leq k \leq n} z_k$. Then for Model B we have $\lim_{n \to \infty} \frac{z^*_n - \bar{z}_n}{\sqrt{n}} = 0$, almost surely.

(b) There are constants $C > 0, \theta < 1$ such that

$$\Pr(z(\cdot) \text{ visits } n - k \text{ after reaching } n) \leq C \theta^k$$

where $\Pr$ denotes the Lebesgue measure.

Proof. (a) Without the loss of generality we can assume $z_0 = 0$. By Borel-Cantelli Lemma it suffices to show that for each $t > 0$

$$\sum_{n=1}^{\infty} \Pr\left( x : \frac{z^*_n(x) - z_n(x)}{\sqrt{n}} > t \right) < \infty.$$

Let $\ell_n(x) = \min\{k : 0 \leq k \leq n, z_k(x) = z^*_n(x)\}$. One can see that if $z^*_n - z_n > t\sqrt{n}$ then $\ell_n(x) \leq n - t\sqrt{n}$. Hence

$$\Pr(z^*_n - z_n > t\sqrt{n}) \leq \Pr(\ell_n(x) \leq n - t\sqrt{n} + 1) = \sum_{k=1}^{[n-t\sqrt{n}]+1} \Pr(\ell_n(x) = k).$$

Next consider the sets

$$B_{m,k} = \{x : z_k(x) \leq m | z_0 = m\}.$$

This is the set of points, for which the walker starting its walk at $z_0 = m$ will be located to the left of $m$ after $k$ steps. By (6.16) we have that for every $m \in \mathbb{Z}, k \geq 1$

$$|B_{m,k}| \leq C \rho^k,$$
for some $\rho < 1$. Next, note that
\[
\Pr(\ell_n(x) = k) \leq \sum_{s=1}^{k} \int_{\mathbb{T}} \chi_{B_{s,n-k}}(G_{s-1} \circ \cdots \circ G_0(x)) \, dx
\]
\[
= \sum_{s=1}^{k} \int_{\mathbb{T}} \chi_{B_{s,n-k}}(x) P_{s-1} \cdots P_0 \, dx \leq Mk \sup_{s \leq k} |B_{s,n-k}| \leq CMk \rho^{n-k}
\]
where $M$ is from (2.4). Hence, by (8.1) and due to $k \leq n - t\sqrt{n} + 1$, we can write
\[
\Pr(z^*_n - z_n > t\sqrt{n}) \leq MC \sum_{n \geq 1} n^2 \rho^{t\sqrt{n}-1} < \infty.
\]
To finish the proof of part (a) it is enough to notice that
\[
\sum_{n \geq 1} \Pr \left( z^*_n - z_n \geq t\sqrt{n} \right) < MC \sum_{n \geq 1} \frac{n^2 \rho^{t\sqrt{n}-1}}{n} < \infty.
\]
Part (b) also follows from (6.16) and the fact that upon first time reaching level $n$ the internal state of the walker is distributed with the bounded density $P^n_1$. $\square$

8.3. **Proof of Theorem 1.3 for Model B.** Given the results of §§8.1–8.2 the proof of Theorem 1.3 for Model B is similar to the proof for Model A and requires only minor modifications which we presently describe.

(1) (5.10) no longer holds, however Lemma 8.1(a) is sufficient for replacing $z^*_n$ by $z_n$ in our limit theorems.

(2) The proof of Lemma 5.2(c) needs to be modified since $a_{n,k}$ is no longer independent. However, one can replace $a_{n,k}$ by
\[
\tilde{a}_{m,k} = \int_{\mathbb{T}} r_m(\tilde{G}_{m-1} \circ \cdots \circ \tilde{G}_{m-k/2}(x)) \, dx
\]
where $\tilde{G}_\ell$ are obtained by motion in the environment where $W_{m-k,1} = \mathbb{T}$. In other words, upon reaching level $m - k$ the particle makes the next step to the right with probability 1. Then $\tilde{a}_{n_1,n_1-n_2}$ and $a_{n_2}$ are independent. On the other hand
\[
a_m - \tilde{a}_{m,k} = [a_m - a_{m,k/2}] + [a_{m,k/2} - \tilde{a}_{m,k}].
\]
The first term is exponentially small due to (Dec), while the second term equals to
\[
\int_{\mathbb{T}} [r_m(\tilde{G}_{m-1} \circ \cdots \circ \tilde{G}_{m-k/2}(x)) - r_m(G_{m-1} \circ \cdots \circ G_{m-k/2}(x))] \, dx
\]
and it is exponentially small since the integrand is non-zero only if the walker starting from level $m - k/2$ backtracks to level $m - k$ which happens with exponentially small probability due to (6.16).

(3) It is no longer true that $\tau_n \leq 3n$ so the proof of Lemma 5.5 needs to be modified.

As before the estimate for $b_n$ follows from the estimate for $S(n)$. The lower bound on $S(n)$ still holds because $\tau_n \geq n$. The upper bound follows from the uniform integrability of $r_m$ which is ensured by (6.16).

The lower bound on $\tilde{\sigma}_n^2$ follows from Proposition 7.7 while the upper bound follows from (Dec). Namely, while it is no longer true for Model B that $r_m \in BV$ the fact that $P_m r_m$ is uniformly bounded in $BV$ suffices to get the exponentially decay of
Cov\( (r_{n_1}, r_{n_2}) \). Indeed denoting \( \tilde{r}_k(x) = r_k(x) - \int_T r_k(G_{k-1} \circ \cdots \circ G_0 y) dy \) we get that for \( n_1 > n_2 \)

\[
\int_T \tilde{r}_{n_1} (G_{n_1-1} \circ \cdots \circ G_0 x) \tilde{r}_{n_2} (G_{n_2-1} \circ \cdots \circ G_0 x) dx
\]

\[
= \int_T \tilde{r}_{n_1} P_{n_1-1} \cdots P_{n_2} (\tilde{r}_{n_2} P^n 1) dx
\]

which is exponentially small since \( P_{n_2} (\tilde{r}_{n_2} P^n 1) \in BV_0 \).

With the changes (1)–(3) discussed above the proof of Theorem 1.3 for Model B proceeds by the same arguments as for Model A.

**Appendix A. Sequential CLT for unbounded observables.**

**Proof of Theorem 3.1.** Note that in general \( \tilde{f}_n \notin BV \), but by (3.1) and (2.4)

\[
|P_k (f_{k-1} P^{k-1} 1)|_{BV} \leq D|P^{k-1} 1|_{BV} \leq MD.
\]

Hence, by (Dec)

\[
|P_n P_{n-1} \cdots P_{n-k} (\tilde{f}_{n-k} P^{n-k-1} 1)|_{BV} \leq K\theta^k MD.
\]

Thus, we can consider the martingale co-boundary decomposition defined in \([9]\) (A.1)

\[
H_n = \frac{1}{P^n 1} \left[ P_n (\tilde{f}_{n-1} P^{n-1} 1) + P_n P_{n-1} (\tilde{f}_{n-2} P^{n-2} 1) + \cdots + P_n P_{n-1} \cdots P_1 (\tilde{f}_{0} P^0 1) \right]
\]

and set

(A.2)

\[
\psi_n = \tilde{f}_n + H_n - H_{n+1} \circ G_{n+1}
\]

\[
U_n = \psi_n (G_n \circ \cdots \circ G_1).
\]

Clearly

\[
|H_n|_{BV} \leq \frac{KMD}{\sigma} \sum_{j=1}^n \theta^k
\]

where \( \sigma \) is from (Min). Since \( P^n 1 \in BV \), and by (Min) we also have \( \frac{1}{P^n 1} \in BV \), then \( H_n \in BV \), for all \( n \geq 1 \). Moreover

\[
\sup_n |H_n|_{BV} < \infty.
\]

Next note that

\[
|P_n (\psi_{n-1} P^{n-1} 1)|_{BV} \leq |P_n (\tilde{f}_{n-1} P^{n-1} 1)|_{BV} + |P_n ((H_n - H_{n+1} \circ G_{n+1}) P^{n-1} 1)|_{BV} < \infty.
\]

It then follows that

(A.3)

\[
\sup_{n \geq 1} |P_n (\psi_{n-1} P^{n-1} 1)|_{BV} < \infty, \quad \sup_{n \geq 1} |P_n (\psi_{n-1}^2 P^{n-1} 1)|_{BV} < \infty.
\]

It is shown in \([9]\), that \( U_n \) is a sequence of reversed martingale and one has

\[
\sum_{k=0}^{n-1} \tilde{f}_k (G^k_1) = \sum_{k=0}^{n-1} U_k (G^k_1) + H_n (G^k_1).
\]
We recall the following estimate from \[9\]
\[\|S_n\|_2 - \\left\| \sum_{k=0}^{n-1} U_k \right\|_2 = \left| \|S_n\|_2 - \left( \sum_{k=0}^{n-1} \int U_k^2(x) dx \right) \right|^{\frac{1}{2}} \leq \|S_n - \sum_{k=0}^{n-1} U_k\|_2 \leq \sup_{n \geq 1} |H_n|_{BV} < \infty.\]

Thus, \(\sigma_n\) is unbounded if and only if \(\sum_{k=0}^{n-1} \int U_k^2(x) dx\) is. The last expression is monotone. Hence, if \(\sigma_n\) is unbounded, then it tends to infinity as \(n \to \infty\).

We now define (recall definition \[2.1\])
\[\sigma_n^2 = \sum_{k=0}^{n-1} \int U_k^2 dx, \quad V_n = \sum_{k=0}^{n-1} \int [U_k^2|A_{k+1}] dx.\]

Following \[9\], Theorem 5.1, we need to check the following two conditions of Theorem 5.8 of \[9\], which is an extension of a result of B.M. Brown \[3\]

(i) for every \(\varepsilon > 0\), \(\lim_{n \to +\infty} \sigma_n^{-2} \sum_{k=0}^{n-1} \int \left[ U_k^2 1_{\{|U_k|>\varepsilon \sigma_n\}} \right] = 0.\)

(ii) the sequence \(\sigma_n^{-2}V_n\) converges to 1 in probability.

For (i) we have from \[9\], page 115 and the estimate \(\|P^n 1\|_{\infty} \leq M\), that for all \(n \geq 1\)
\[\int U_k^2 1_{\{|U_k|>\varepsilon \sigma_n\}} dx = \int \left[ \psi_k^2(G_1^n)1_{\{\varepsilon \sigma_n, \infty\}}(\psi_k^2(G_1^n)) \right] dx = \int \left[ \psi_k^2(x)1_{\{\varepsilon \sigma_n, \infty\}}(\psi_k^2(x))P^n 1 \right] dx \leq M \int \left[ \psi_k^2(x)1_{\{\varepsilon \sigma_n, \infty\}}(\psi_k^2(x)) \right] dx.\]

By \[A.2\], \(\psi_k^2(x) \leq 2(f_k^2(x))^2 + 8 \sup_{k \geq 1} |H_k|^2.\) Hence, if \(\varepsilon \sigma_n \leq \psi_k^2(x),\) then for \(n\) large
\[\frac{\varepsilon \sigma_n}{8} \leq (f_k^2(x))^2.\]

Take \(n\) so large that \(4 \sup_{k \geq 1} |H_k|^2 \leq \frac{\varepsilon \sigma_n}{8}.\) Then
\[M \int \left[ \psi_k^2(x)1_{\{\varepsilon \sigma_n, \infty\}}(\psi_k^2(x)) \right] dx \leq 2M \int \left[ (f_k^2(x) + 4 \sup_{k \geq 1} |H_k|^2 \cdot 1_{\{\varepsilon \sigma_n/8, \infty\}}(f_k^2(x))) \right] \leq 4M \int \left[ f_k^2(x)1_{\{\varepsilon \sigma_n/8, \infty\}}(f_k^2(x)) \right].\]

Hence (i) follows from \[3.2\].

As for (ii) we have by \[9\], page 115
\[\int [U_k^2|A_{k+1}] = \left( \frac{P_{k+1}(\psi_k^2 P^k 1)}{P^{k+1}} \right) \circ (G_n \circ \cdots \circ G_{k+1}).\]
By (Min) and (A.3) we have that
\[
\sup_k \left| \left( \frac{P_{k+1} \psi_k^2 P_k^1}{P_k^1} \right) \right|_{BV} < \infty.
\]
Given these estimates, the rest of the proof of (ii) is the same as in the proof of [9, Theorem 5.1].

To verify the growth of the variance assumption in Theorem 3.1, the following fact will be helpful.

**Proposition A.1.** Let \( \bar{G} \) be such that \( \bar{P} \) satisfies (Dec) and for its acim we almost surely have that \( h(x) \geq c > 0 \). Assume that \( P\bar{\tau} \in BV \). Let
\[
H = \frac{1}{h} \sum_{n=1}^{\infty} P^n \left( h \left( \bar{\tau} - \int \bar{\tau} h dx \right) \right),
\]

Then \( H \in BV \). Moreover, if
\[
(A.5) \quad \psi := \bar{\tau} - \int_T \bar{\tau} h dx + H - H \circ \bar{G},
\]
does not vanish almost surely then
\[
\hat{\sigma}^2_n = \text{Var} \left( \sum_{k=1}^{n} \bar{\tau} \circ \bar{G}^k \right) \geq C n
\]
for some \( C > 0 \).

**Proof.** Consider the coboundary decomposition (A.1)–(A.2). We take \( P_n = \bar{P} \) and \( f_n = \tau \) for all \( n \geq 1 \). Then
\[
H_{n,P} = \frac{1}{P^n 1} \left[ \bar{P} (\bar{\tau} \bar{P}^{n-1} 1) + P^2 (\bar{\tau} \bar{P}^{n-2} 1) + \cdots + P^n (\bar{\tau} \bar{P} 1) \right]
\]
and respectively
\[
\psi_n = \bar{\tau} + H_{n,P} - H_{n,P} \circ G.
\]

We now show that
\[
(A.6) \quad H_{n,P} \to_{L^2} H
\]
as \( n \to \infty \). For this note that \( \int_T h \left( \tau - \int \tau h dx \right) dx = 0 \). Hence
\[
\left| P^n \left( h \left( \tau - \int \tau h dx \right) \right) \right|_{BV} \leq K \theta^{n-1} \left| P \left( h \left( \tau - \int \tau h dx \right) \right) \right|_{BV}.
\]
Thus the general term in (A.6) decays exponentially fast. Note that for each fixed \( k \), \( \bar{P}^{n-k} \bar{1} \to_{BV} h \), as \( n \to \infty \). In particular \( \bar{P}^n \bar{1} \to_{BV} h \). Since \( h \) is bounded away from zero, we also have that \( \frac{1}{\bar{P}^n \bar{1}} \to_{BV} \frac{1}{h} \) (A.6) follows.

Now assume that \( \|\psi\|_2 > 0 \). Then by (A.4)
\[
\left| \hat{\sigma}_n - \left( \sum_{k=0}^{n-1} \int_T U_k^2(x)dx \right)^{\frac{1}{2}} \right| = \left| \hat{\sigma}_n - \left( n \int_T \psi^2 h dx \right)^{\frac{1}{2}} \right| \leq |H|_{BV} < \infty
\]
completing the proof of the proposition.
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