A condition for blow-up solutions to discrete $p$-Laplacian parabolic equations under the mixed boundary conditions on networks

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Abstract

In this paper, we investigate the condition

$$(C_p)\quad \alpha \int_0^u f(s)\,ds \leq uf(u) + \beta u^p + \gamma, \quad u > 0$$

for some $\alpha > 2$, $\gamma > 0$, and $0 \leq \beta \leq \frac{(\alpha - p)\lambda_{p,0}}{p}$, where $p > 1$, and $\lambda_{p,0}$ is the first eigenvalue of the discrete $p$-Laplacian $\Delta_{p,\omega}$. Using this condition, we obtain blow-up solutions to discrete $p$-Laplacian parabolic equations

$$
\begin{align*}
&u_t(x, t) = \Delta_{p,\omega} u(x, t) + f(u(x, t)), \quad (x, t) \in S \times (0, +\infty), \\
&\mu(z) \frac{\partial u}{\partial \sigma}(x, t) + \sigma(z) |u(x, t)|^{p-2} u(x, t) = 0, \quad (x, t) \in \partial S \times [0, +\infty), \\
&u(x, 0) = u_0 \geq 0 \quad \text{(nontrivial)}, \quad x \in S,
\end{align*}
$$

on a discrete network $S$, where $\frac{\partial u}{\partial \sigma}$ denotes the discrete $p$-normal derivative. Here $\mu$ and $\sigma$ are nonnegative functions on the boundary $\partial S$ of $S$ with $\mu(z) + \sigma(z) > 0$, $z \in \partial S$. In fact, we will see that condition $(C_p)$ improves the conditions known so far.

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0 Introduction

These days the discrete version of differential equations has attracted attention of many researchers. In particular, the $p$-Laplacian $\Delta_{p,\omega}$ on networks (or weighted graphs) is used to observe various social and scientific phenomena (see [1–3] and references therein), which can be modeled by the discrete $p$-Laplacian parabolic equations

$$u_t = \sum_{y \in \mathcal{S}} |u(y, t) - u(x, t)|^{p-2} [u(y, t) - u(x, t)] \omega(x, y) + f(u)$$

with some boundary and initial conditions, where $p > 1$. Here $\mathcal{S}$ is the set of chemicals or networks, and $\omega$ is a weight function on $\mathcal{S}$.
Especially, many authors studied blow-up solutions for the reaction–diffusion equations, which contain $p$-Laplacian, Laplacian, and so on, in continuous and discrete analogues. For example, in 1973, Levine [4] considered formal parabolic equations of the form

$$\begin{align*}
P \frac{du}{dt} = -A(t)u + f(u(t)), & \quad t \in [0, +\infty), \\
u(0) = u_0,
\end{align*}$$

where $P$ and $A(t)$ are positive linear operators defined on a dense subdomain $D$ of a real or complex Hilbert space $H$. Here he first introduced the “concavity method” to obtained the blow-up solutions under abstract conditions

$$2(\alpha + 1)F(x) \leq \{x, f(x)\}, \quad F(u_0(x)) > \frac{1}{2} (u_0(x), Au_0(x))$$

for $x \in D$, where $F(x) = \int_{0}^{1} f(\rho x, x) \, d\rho$.

After this, Philippin and Proytcheva [5] have applied this method to the equations

$$u_t = \Delta u + f(u) \quad \text{in } \Omega \times (0, +\infty)$$

and obtained a blow-up solution under the Dirichlet boundary condition by using the condition

$$(A) : \quad (2 + \epsilon)F(u) \leq uf(u), \quad u > 0,$$

for some $\epsilon > 0$ and the initial data $u_0$ satisfying

$$-\frac{1}{2} \int_{\Omega} |\nabla u_0(x)|^2 \, dx + \int_{\Omega} F(u_0(x)) \, dx > 0.$$

For the $p$-Laplace operator, Messaoudi [6] obtained the blow-up solutions to the equation

$$u_t = \text{div}(|\nabla u|^{p-2} \nabla u) + f(u) \quad \text{in } \Omega \times (0, +\infty)$$

under the Dirichlet boundary condition by using the condition

$$(A_p) : \quad (p + \epsilon)F(u) \leq uf(u), \quad u > 0,$$

for some $\epsilon > 0$ and the initial data $u_0$ satisfying

$$-\frac{1}{p} \int_{\Omega} |\nabla u_0(x)|^p \, dx + \int_{\Omega} F(u_0(x)) \, dx > 0.$$

Besides, Junning [7] obtained the blow-up solutions to the equation

$$u_t = \text{div}(|\nabla u|^{p-2} \nabla u) + f(u) \quad \text{in } \Omega \times (0, +\infty)$$
under the Dirichlet boundary condition by using the condition

\[(A_p^1) : \quad pF(u) \leq uf(u), \quad u > 0.\]

Here the initial data \(u_0\) satisfies

\[-\frac{1}{p} \int \Omega |\nabla u_0(x)|^p \, dx + \int \Omega F(u_0(x)) \, dx > \frac{4(p-1)}{T(p-2)p} \int \Omega u_0^2(x) \, dx.\]

Recently, Ding and Hu [8] adopted condition \((A)\) to obtain the blow-up solutions to the equation

\[(g(u))_t = \nabla \cdot (\rho(|\nabla u|^2) \nabla u) + k(t)f(u)\]

with the nonnegative initial value and the null Dirichlet boundary condition.

On the other hand, condition \((A)\) was relaxed by Bandle and Brunner [9] as follows:

\[(B) : \quad (2+\epsilon)F(u) \leq uf(u) + \gamma, \quad u > 0,\]

for some \(\epsilon > 0\). Also, the initial data \(u_0\) satisfies

\[-\frac{1}{2} \int \Omega |\nabla u_0(x)|^2 \, dx + \int \Omega [F(u_0) - \gamma] \, dx > 0\]

for some \(\epsilon > 0\) and \(\gamma > 0\).

Finally, condition \((B)\) was improved by Chung and Choi [10] with the discrete analogue. They obtained the blow-up solutions to the equation

\[u_t = \Delta_\omega u(x,t) + f(u) \quad \text{in} \ S \times (0,+\infty)\]

under the Dirichlet boundary condition by using the condition

\[(C) : \quad (2+\epsilon)F(u) \leq uf(u) + u^2 + \gamma, \quad u > 0,\]

for some \(\epsilon > 0\), \(0 < \beta \leq \frac{\epsilon \lambda_0}{2}\), and \(\gamma > 0\) and the initial data \(u_0\) satisfying

\[-\frac{1}{2} \sum_{x \in S} |u_0(x) - u_0(y)|^2 \omega(x,y) + \sum_{x \in S} [F(u_0) - \gamma] \, dx > 0.\]

Here \(\lambda_0\) is the first eigenvalue for the discrete Laplace operator \(\Delta_\omega\).

In 2018, Chung and Choi [11] refines condition \((C)\) in continuous analogue. For \(p \geq 2\), they obtained the blow-up solutions to the equation

\[u_t = \text{div}(|\nabla u|^{p-2} \nabla u) + f(u) \quad \text{in} \ \Omega \times (0,+\infty)\]

under the Dirichlet boundary condition by using the condition

\[(C_p) : \quad (p+\epsilon)F(u) \leq uf(u) + \beta u^p + \gamma, \quad u > 0,\]
for some $\epsilon > 0$, $0 < \beta \leq \frac{\epsilon \lambda_{p,0}}{p}$, and $\gamma > 0$. Here the initial data $u_0$ satisfies

$$-\frac{1}{p} \int_{\Omega} |\nabla u_0(x)|^p \, dx + \int_{\Omega} F(u_0(x)) \, dx > 0.$$ 

Here $\lambda_{p,0}$ is the first eigenvalue for the $p$-Laplace operator.

It is clear that conditions $(A)$, $(A_p)$, $(B)$, and $(B_p)$ are independent of the eigenvalue of the Laplace operator, and conditions $(C)$ and $(C_p)$ depend on the eigenvalue. As a matter of fact, it is known that the first eigenvalue for the $p$-Laplace operator depends not only on the domain but also on the boundary conditions (see [12]).

Motivated by the works mentioned, we study the blow-up solutions to the following discrete $p$-Laplacian parabolic equations:

$$
\begin{align*}
&u_t(x, t) = \Delta_{p,0} u(x, t) + f(u(x, t)), \quad (x, t) \in S \times (0, +\infty), \\
&B[u] = 0 \quad \text{on } \partial S \times [0, +\infty), \\
&u(x, 0) = u_0(x) \geq 0, \quad x \in S,
\end{align*}
$$

(2)

where $p > 1$, $f$ is a nonnegative locally Lipschitz continuous function on $\mathbb{R}$, and $B[u] = 0$ on $\partial S \times [0, +\infty)$ stands for the boundary condition

$$
\mu(z) \frac{\partial u}{\partial p_n}(z, t) + \sigma(z) |u(z, t)|^{p-2} u(z, t), \quad (z, t) \in \partial S \times [0, +\infty).
$$

(3)

Here $\mu, \sigma : \partial S \to [0, +\infty)$ are functions such that $\mu(z) + \sigma(z) > 0$, $z \in \partial S$, and $\frac{\partial u}{\partial p_n}$ denotes the discrete $p$-normal derivative (introduced in Sect. 1). It is easy to see that this boundary value problem includes various boundary value problems such as the Dirichlet boundary, Neumann boundary, and Robin boundary problems. Note that one of advantages of our result is a unified approach.

To obtain the blow-up solutions to equation (2), we introduce the following condition: For $p > 1$,

$$(C_p) : \quad \alpha F(u) \leq uf(u) + u^p + \gamma, \quad u > 0,$$

for some $\alpha > 2$, $0 \leq \beta \leq \frac{(\alpha-p)\mu_0}{p}$, and $\gamma \geq 0$.

We discuss condition $(C_p)$ in Section 3 to understand the constants $\alpha$, $\beta$, and $\gamma$ with respect to the boundary condition $B[u] = 0$ and the parameter $p > 1$, which are crucial points of our results.

It is worth noting that we obtained the blow-up solutions to equation (2) in the case $p > 1$, not in the case $p \geq 2$. In fact, there are interesting results in the case $1 < p < 2$ with respect to blow-up property (see [13–15]). Therefore we expect that under condition $(C_p)$, more interesting results can be obtained even in the continuous case, which will be our forthcoming work.

We organize this paper as follows. In Sect. 1, we briefly introduce the preliminary concepts on networks and comparison principles. Section 2 is the main section devoted to blow-up solutions using the concavity method with condition $(C_p)$. Finally, in Sect. 3, we discuss condition $(C_p)$, comparing it with conditions $(A_p)$ and $(B_p)$, together with the condition $B(0) > 0$, the parameter $p > 1$, and the initial data condition.
1 Preliminaries and discrete comparison principles

In this section, we start with the theoretic graph notions frequently used throughout this paper. For more detailed information on notations, notions, and conventions, we refer the reader to [16].

Definition 1.1
(i) A graph \( G = G(V, E) \) is a finite set \( V \) of vertices with a set \( E \) of edges (two-element subsets of \( V \)). Conventionally used, we denote by \( x \in V \) or \( x \in G \) the fact that \( x \) is a vertex in \( G \).

(ii) A graph \( G \) is called simple if it has neither multiple edges nor loops.

(iii) \( G \) is called connected if for all vertices \( x \) and \( y \), there exists a sequence of vertices \( x = x_0, x_1, \ldots, x_{n-1}, x_n = y \) such that \( x_{j-1} \) and \( x_j \) are connected by an edge for \( j = 1, \ldots, n \) (called adjacent).

(iv) A graph \( G' = G'(V', E') \) is called a subgraph of \( G(V, E) \) if \( V' \subset V \) and \( E' \subset E \). In this case, \( G \) is a host graph of \( G' \). If \( E' \) consists of all the edges from \( E \) that connect the vertices of \( V' \) in its host graph \( G \), then \( G' \) is called an induced subgraph.

Definition 1.2 For an induced subgraph \( S \) of a graph \( G = G(V, E) \), the (vertex) boundary \( \partial S \) of \( S \) is defined as

\[
\partial S := \{ z \in V \setminus S | z \sim y \text{ for some } y \in S \}.
\]

Here, \( x \sim y \) means that two vertices \( x \) and \( y \) are connected (adjacent) by an edge in \( E \).

Throughout this paper, the subgraph \( S \) is assumed to be induced, simple, and connected. Also, we denote by \( S \) the graph with vertices and edges in \( S \cup \partial S \). We note that by definition the set \( S \) is an induced subgraph of \( G \).

Definition 1.3 A weight on a graph \( G \) is a symmetric function \( \omega : V \times V \rightarrow [0, +\infty) \) satisfying the following:
(i) \( \omega(x, x) = 0, x \in V \),
(ii) \( \omega(x, y) = \omega(y, x) \) if \( x \sim y \),
(iii) \( \omega(x, y) > 0 \) if and only if \( \{x, y\} \in E \),
and a graph \( G \) with weight \( \omega \) is called a network.

Definition 1.4 The degree \( d_{\omega}x \) of a vertex \( x \) in a network \( S \) (with boundary \( \partial S \)) is defined as

\[
d_{\omega}x := \sum_{y \in S} \omega(x, y).
\]

Definition 1.5 For \( p > 1 \) and a function \( u : S \rightarrow \mathbb{R} \), the discrete \( p \)-Laplacian \( \Delta_{p,\omega} \) on \( S \) is defined by

\[
\Delta_{p,\omega}u(x) := \sum_{y \in S} |u(y) - u(x)|^{p-2}[u(y) - u(x)]\omega(x, y)
\]

for \( x \in S \).
**Definition 1.6** For \( p > 1 \) and a function \( u : \mathcal{S} \rightarrow \mathbb{R} \), the discrete \( p \)-normal derivative \( \frac{\partial u}{\partial p n} \) on \( \partial S \) is defined by

\[
\frac{\partial u}{\partial p n}(z) := \sum_{x \in S} |u(z) - u(x)|^{p-2}[u(z) - u(x)]\omega(x, z)
\]

for \( z \in \partial S \).

The following two lemmas are used throughout this paper.

**Lemma 1.7** (See [17]) Let \( p > 1 \). For functions \( f, g : \mathcal{S} \rightarrow \mathbb{R} \), the discrete \( p \)-Laplacian \( \Delta_{p,0} \) satisfies

\[
2 \sum_{x \in \mathcal{S}} g(x)\left[-\Delta_{p,0} f(x)\right] = \sum_{x, y \in \mathcal{S}} \left| f(y) - f(x) \right|^{p-2}\left[ f(y) - f(x) \right] \left[ g(y) - g(x) \right] \omega(x, y).
\]

In particular, in the case \( g = f \), we have

\[
2 \sum_{x \in \mathcal{S}} f(x)\left[-\Delta_{p,0} f(x)\right] = \sum_{x, y \in \mathcal{S}} \left| f(x) - f(y) \right|^{p} \omega(x, y).
\]

**Lemma 1.8** (See [12]) For \( p > 1 \), there exist \( \lambda_{p,0} > 0 \) and a function \( \phi_{0}(x) > 0, x \in \mathcal{S} \cup \Gamma^* \), such that

\[
\left\{
\begin{array}{l}
-\Delta_{p,0} \phi_{0}(x) = \lambda_{p,0} f_{0}(x) \phi_{0}(x), \quad x \in \mathcal{S}, \\
B[\phi_{0}] = 0 \quad \text{on } \partial \mathcal{S},
\end{array}
\right.
\]

where \( B[\phi_{0}] \) on \( \partial \mathcal{S} \) stands for

\[
\mu(z) \frac{\partial \phi_{0}}{\partial p n}(z) + \sigma(z)|\phi_{0}(z)|^{p-2}\phi_{0}(z), \quad z \in \partial \mathcal{S}.
\]

Here \( \Gamma^* := \{ z \in \partial \mathcal{S} \mid \mu(z) > 0 \} \), and \( \mu, \sigma : \partial \mathcal{S} \rightarrow [0, +\infty) \) are functions such that \( \mu(z) + \sigma(z) > 0 \) for \( z \in \partial \mathcal{S} \). Moreover, \( \lambda_{p,0} \) is given by

\[
\lambda_{p,0} = \min_{u \in A, u \neq 0} \frac{\frac{1}{2}\sum_{x, y \in \mathcal{S}} |u(x) - u(y)|^p \omega(x, y) + \sum_{z \in \Gamma^*} \frac{\sigma(z)}{\mu(z)} |u(z)|^p}{\sum_{x \in \mathcal{S}} |u(x)|^p},
\]

where \( A := \{ u : \mathcal{S} \rightarrow \mathbb{R} \mid u \neq 0 \text{ in } \mathcal{S}, u = 0 \text{ on } \partial \mathcal{S} \setminus \Gamma \} \).

The number \( \lambda_{p,0} \) is called the first eigenvalue of \( \Delta_{p,0} \) on a network \( \mathcal{S} \) with corresponding eigenfunction \( \phi_{0} \) (see [18] and [19] for the spectral theory of the Laplacian operators). In fact, we note that if \( \Gamma^* \) is the empty set, then \( \sum_{z \in \Gamma^*} \frac{\sigma(z)}{\mu(z)} |u(z)|^p \) is 0.

**Remark 1.9** It is clear that the first eigenvalue \( \lambda_{p,0} \) is nonnegative. Moreover, we note here that the first eigenvalue \( \lambda_{p,0} \) satisfies the following statements:
(i) If $\sigma \equiv 0$, then $\lambda_{p,0} = 0$.
(ii) If $\sigma \not\equiv 0$, then $\lambda_{p,0} > 0$.

We now discuss the local existence of a solution to equation (2). To discuss the local existence, we would like to investigate the relationship between the boundary condition $B[u] = 0$ and the initial data $u_0$.

**Remark 1.10** Consider the function $\psi : \mathbb{R} \rightarrow \mathbb{R}$ defined as
\[
\psi(\gamma) := \sum_{x \in S} |\gamma - u(x,t)|^{p-2}[\gamma - u(x,t)]a(x) + b|\gamma|^{p-2},
\]
where $a(x) \geq 0$ for $x \in S$, and $b \geq 0$ with $a(x) + b > 0$ for some $x \in S$. Then it is easy to see that $\psi$ is a continuous function that is strictly increasing and bijective on $\mathbb{R}$. Therefore there exists a unique $\rho \in \mathbb{R}$ such that $\psi(\rho) = 0$. It means that for all $z \in \partial S$, we can uniquely define the value of $u(z,0)$ according to the given boundary condition $B[u] = 0$ and initial data $u_0$, that is, for every $z \in \partial S$, $u(z,0)$ is determined such that
\[
\mu(z) \frac{\partial u}{\partial n}(z,0) + \sigma(z)|u(z,0)|^{p-2}u(z,0) = 0, \quad z \in \partial S,
\]
where $\mu, \sigma : \partial S \rightarrow [0, +\infty)$ are given functions with $\mu(z) + \sigma(z) > 0$ for all $z \in \partial S$. Therefore we have a compatible condition such that the initial data $u_0$ satisfies
\[
\mu(z) \frac{\partial u_0}{\partial n}(z) + \sigma(z)|u_0(z)|^{p-2}u_0(z) = 0, \quad z \in \partial S.
\]

We will prove the existence of the solution to equation (2) using the Schauder fixed point theorem. For this reason, we first define the set $C(S \times I)$ for a compact interval $I$:
\[
C(S \times I) := \{ u : S \times I \rightarrow \mathbb{R} | u(x, \cdot) \in C(I) \text{ for each } x \in S \}.
\]

Also, we need the following modified version of the Arzelà–Ascoli theorem.

**Lemma 1.11** (Modified version of the Arzelà–Ascoli theorem) Let $F$ be a compact subset of $\mathbb{R}$, and let $S$ be a network. Consider the Banach space $C(S \times F)$ with the maximum norm $\|u\|_{S,F} := \max_{x \in S} \max_{t \in F} |u(x,t)|$. Then a subset $A$ of $C(S \times F)$ is relatively compact if $A$ is uniformly bounded on $S \times F$ and equicontinuous on $F$ for each $x \in S$.

**Proof** This lemma is already proved by Chung and Hwang [14].

**Theorem 1.12** (Local existence) There exists $t_0 > 0$ such that equation (2) admits at least one bounded solution $u$ such that $u(x, \cdot)$ is continuous on $[0, t_0]$ and differentiable in $(0, t_0)$ for each $x \in S$.

**Proof** We first start with the Banach space
\[
C(S \times [0, t_0]) := \{ u : S \times [0, t_0] \rightarrow \mathbb{R} | u(x, \cdot) \in C([0, t_0]) \text{ for each } x \in S \}.
\]
with the maximum norm \( \|u\|_{S,t_0} := \max_{x \in S} \max_{0 \leq t \leq t_0} |u(x,t)| \), where \( t_0 \in \mathbb{R} \) is a positive constant, which will be defined later. Now consider the subspace

\[
B_{t_0} := \{ u \in C(S \times [0,t_0]) \mid \|u\|_{S,t_0} \leq 2\|u_0\|_{S,t_0} \}
\]

of a Banach space \( C(S \times [0,t_0]) \). Then it is clear that \( B_{t_0} \) is convex. To apply the Schauder fixed point theorem, we have to show that \( B_{t_0} \) is closed. Let \( g_n \) be a sequence in \( B_{t_0} \) that converges to \( g \). Since the convergence is uniform, \( g \) is continuous. Moreover, \( \|g_n\|_{S,t_0} - \|g\|_{S,t_0} \leq \|g_n - g\|_{S,t_0} \) implies that \( g \in B_{t_0} \), Hence \( B_{t_0} \) is closed.

On the other hand, for every \( u \in B_{t_0} \), we can uniquely define the value of \( u(z,t) \) according to the boundary condition \( B[u] = 0 \) in a similar way to Remark 1.10, that is, for every \( u \in B_{t_0} \), \( u(z,t) \) satisfies

\[
\mu(z) \frac{\partial u}{\partial n}(z,t) + \sigma(z)|u(z,t)|^{p-2}u(z,t) = 0, \quad (z,t) \in \partial S \times [0,t_0]
\]

for all \((z,t) \in \partial S \times [0,t_0] \), where \( \mu, \sigma : \partial S \to [0, +\infty) \) are given functions with \( \mu(z) + \sigma(z) > 0 \) for all \( z \in \partial S \). Then by the boundary condition it is clear that \( u(z,t) \) satisfies \( |u(z,t)| \leq \|u\|_{S,t_0} \), \((z,t) \in \partial S \times [0,t_0]\).

Let us define the operator \( D : B_{t_0} \to B_{t_0} \) by

\[
D[u](x,t) := u_0(x) + \int_0^t \Delta_{p,n} u(x,s) + f(u(x,s)) \, ds, \quad (x,t) \in S \times [0,t_0],
\]

where \( u_0 : S \to \mathbb{R} \) is a given function.

Since \( f \) is locally Lipschitz continuous on \( \mathbb{R} \), there exists \( L > 0 \) such that

\[
|f(a) - f(b)| \leq L|a - b|, \quad a, b \in [-m,m],
\]

where \( m = 2\|u_0\|_{S,t_0} \). Now put

\[
t_0 := \frac{\|u_0\|_{S,t_0}}{\omega_0(4\|u_0\|_{S,t_0})^{p-1} + 4L\|u_0\|_{S,t_0}},
\]

where \( \omega_0 := \max_{x \in S} \sum_{y \in S} \omega(x,y) \). Then it is easy to see that the operator \( D \) is well-defined. Now we will show that \( D \) is continuous. The verification of the continuity is divided into two cases as follows:

(i) \( 1 < p < 2 \).

For \( u \) and \( v \) in \( B_{t_0} \), it follows that

\[
|D[u](x,t) - D[v](x,t)| \leq \int_0^t \sum_{y \in S} 2^{2-p} \|u - v\|_{S,t_0}^{p-1} \omega(x,y) + L\|u - v\|_{S,t_0} \, ds
\]

\[
\leq t_0 \left[ 2^{2-p} \omega_0 \|u - v\|_{S,t_0}^{p-1} + L\|u - v\|_{S,t_0} \right].
\]

(ii) \( p \geq 2 \).
For \( u \) and \( v \) in \( B_{t_0} \), by the mean value theorem we have

\[
|D[u](x, t) - D[v](x, t)| \\
\leq \left| \int_0^{t_0} \sum_{j \in S} (p - 1) \| 2u_0 \|_{S, t_0}^{p-2} | u - v | S, t_0 \, \omega(x, y) + L \| u - v \|_{S, t_0} \, ds \right| \\
\leq \left| \int_0^{t_0} \sum_{j \in S} 2^{2p-3}(p - 1) \| u_0 \|_{S, t_0}^{p-2} | u - v | S, t_0 \, \omega(x, y) + L \| u - v \|_{S, t_0} \, ds \right| \\
\leq t_0 \left[ 2^{2p-3}(p - 1) \| u_0 \|_{S, t_0}^{p-2} \omega_0 \| u - v \|_{S, t_0} + L \| u - v \|_{S, t_0} \right].
\]

Consequently, for each \( p > 1 \), we obtain

\[
\| D[u] - D[v] \|_{S, t_0} \leq C_1 \| u - v \|_{S, t_0}^{p-1} + C_2 \| u - v \|_{S, t_0},
\]

where \( C_1 \) and \( C_2 \) are constants depending only on \( u_0, t_0, p, L, \) and \( \omega_0 \). Therefore we obtain the continuity of \( D \).

Finally, we will show that \( D(B_{t_0}) \) is relatively compact. By Lemma 1.11 it suffices to show that \( D(B_{t_0}) \) is uniformly bounded on \( S \times [0, t_0] \) and equicontinuous on \([0, t_0]. \) Since \( D(B_{t_0}) \in B(t_0), \) it is trivial that \( D(B_{t_0}) \) is uniformly bounded. On the other hand, it follows that for each \( x \in S, \)

\[
|D[u](x, t_1) - D[u](x, t_2)| \leq |t_1 - t_2| \left[ \omega_0(4 \| u_0 \|_{S, t_0})^{p-1} + 4L \| u_0 \|_{S, t_0} \right]
\]

for all \( t_1, t_2 \in [0, t_0] \) and \( u \in B_{t_0} \), which implies that \( D(B_{t_0}) \) is equicontinuous on \([0, t_0]. \) Hence \( D(B_{t_0}) \) is relatively compact by Lemma 1.11. Therefore by the Schauder fixed point theorem there exists \( u \in B(t_0) \) satisfying \( D[u] = u \) and the boundary condition \( B[u] = 0. \) It is clear that \( u \) is the solution to equation (2). On the other hand, it is easy to see that \( u \) is bounded. Moreover, \( u(x, \cdot) \) is continuous on \([0, t_0] \) and differentiable in \((0, t_0) \) for each \( x \in S \) by the definition of \( D \) and the boundary condition \( B[u] = 0. \)

Now we state two types of comparison principles.

**Theorem 1.13** (Comparison principle) Let \( T > 0 \) (\( T \) may be \( +\infty \)) and \( p > 1, \) and let \( f \) be locally Lipschitz continuous on \( \mathbb{R}. \) Suppose that real-valued functions \( u(x, \cdot), v(x, \cdot) \in C[0, T) \) are differentiable in \((0, T) \) for each \( x \in \overline{S} \) and satisfy

\[
\begin{align*}
&u(t, t) - \Delta_{p, \omega} u(x, t) - f(u(x, t)) \\
&\geq v(t, t) - \Delta_{p, \omega} v(x, t) - f(v(x, t)), \quad (x, t) \in S \times (0, T), \\
&B[u] \geq B[v] \quad \text{on} \ \partial S \times [0, T), \\
&u(x, 0) \geq v(x, 0), \quad x \in \overline{S}.
\end{align*}
\]

Then \( u(x, t) \geq v(x, t) \) for all \( (x, t) \in \overline{S} \times [0, T). \)

**Proof** Let \( T' > 0 \) be arbitrarily given with \( T' < T. \) Since \( f \) is locally Lipschitz continuous on \( \mathbb{R}, \) there exists \( L > 0 \) such that

\[
|f(a) - f(b)| \leq L|a - b|, \quad a, b \in [-m, m],
\]

\[ (5) \]
where \( m = \max_{x \in S} \max_{0 \leq t \leq T} \{ |u(x,t)|, |v(x,t)| \} \). Let \( \tilde{u}, \tilde{v} : S \times [0, T^*] \rightarrow \mathbb{R} \) be the functions defined by
\[
\tilde{u}(x,t) := e^{-2Lt}u(x,t), \quad (x,t) \in S \times [0, T^*].
\]
\[
\tilde{v}(x,t) := e^{-2Lt}v(x,t), \quad (x,t) \in S \times [0, T^*].
\]

Then from (4) we have
\[
\begin{align*}
\left[ \tilde{u}_t(x,t) - \tilde{v}_t(x,t) \right] &= e^{2L} \left[ \Delta_{p,v} \tilde{u}(x,t) - \Delta_{p,v} \tilde{v}(x,t) \right] \\
&+ 2Le^{2L} \left[ \tilde{u}(x,t) - \tilde{v}(x,t) \right] - e^{2L} \left[ f(u(x,t)) - f(v(x,t)) \right] \geq 0
\end{align*}
\]
for all \((x,t) \in S \times (0, T^*)\).

We recall that \( \tilde{u}(x,\cdot) \) and \( \tilde{v}(x,\cdot) \) are continuous on \([0, T^*]\) for each \( x \in \overline{S} \) and \( \overline{S} \) is finite. Hence we can find \((x_0, t_0) \in \overline{S} \times [0, T^*]\) such that
\[
(\tilde{u} - \tilde{v})(x_0, t_0) = \min_{x \in S} \min_{0 \leq t \leq T^*} (\tilde{u} - \tilde{v})(x,t),
\]
which implies that
\[
\tilde{v}(y,t_0) - \tilde{v}(x_0,t_0) \leq \tilde{u}(y,t_0) - \tilde{u}(x_0,t_0), \quad y \in \overline{S}.
\]

Then now we have only to show that \((\tilde{u} - \tilde{v})(x_0,t_0) \geq 0\).

Suppose that, on the contrary, \((\tilde{u} - \tilde{v})(x_0,t_0) < 0\). Assume that \( x_0 \in \partial S \). Then we see that
\[
0 \leq \mu(x_0) \sum_{x \in S} \left| \left[ \tilde{u}(x_0,t_0) - \tilde{u}(x,t_0) \right] - \left[ \tilde{v}(x_0,t_0) - \tilde{v}(x,t_0) \right] \right|^p \omega(x_0, x)
\]
\[
+ \sigma(x_0) \left( \tilde{u}(x_0,t_0) - \tilde{v}(x_0,t_0) \right).
\]

Therefore, if \( \sigma(x_0) > 0 \), then equation (8) is negative, which leads to a contradiction. If \( \sigma(x_0) = 0 \), then we have
\[
\tilde{u}(x_0,t_0) - \tilde{v}(x_0,t_0) = \tilde{u}(x_0,t_0) - \tilde{v}(x_0,t_0)
\]
for all \( x \in S \). Hence there exists \( x_1 \in S \) such that
\[
\tilde{u}(x_0,t_0) - \tilde{v}(x_0,t_0) = \tilde{u}(x_1,t_0) - \tilde{v}(x_1,t_0).
\]

Hence we may choose \( x_0 \in S \). Moreover, since \( \tilde{u}(x,0) - \tilde{v}(x,0) \geq 0 \) on \( \overline{S} \), we have \((x_0, t_0) \in S \times (0, T^*]\). Then we obtain from (7) that
\[
\Delta_{p,u} \tilde{u}(x_0,t_0) - \Delta_{p,v} \tilde{v}(x_0,t_0) \geq 0,
\]
and from the differentiability of \((\tilde{u} - \tilde{v})(x,t)\) in \((0, T^*]\) for each \( x \in \overline{S} \) it follows that
\[
(\tilde{u}_t - \tilde{v}_t)(x_0,t_0) \leq 0.
\]
According to (5), we have
\[
2L\left[\tilde{u}(x_0, t_0) - \tilde{v}(x_0, t_0) - e^{-2Lt}f(u(x_0, t_0))\right] \\
\leq 2L\left[\tilde{u}(x_0, t_0) - \tilde{v}(x_0, t_0) + Le^{-2Lt}|u(x_0, t_0) - v(x_0, t_0)|\right] \\
= 2L\left[\tilde{u}(x_0, t_0) - \tilde{v}(x_0, t_0) + L\tilde{f}(x_0, t_0) - \tilde{f}(v(x_0, t_0))\right] \\
= L\left[\tilde{u}(x_0, t_0) - \tilde{v}(x_0, t_0)\right] < 0,
\]
(11)
since \(\tilde{u}(x_0, t_0) < \tilde{v}(x_0, t_0)\). Combining (9), (10), and (11), we obtain that
\[
\tilde{u}(x_0, t_0) - \tilde{v}(x_0, t_0) - \left[\Delta_{p,0} \tilde{u}(x_0, t_0) - \Delta_{p,0} \tilde{v}(x_0, t_0)\right] \\
+ 2L\left[\tilde{u}(x_0, t_0) - \tilde{v}(x_0, t_0) - e^{-2Lt}f(u(x_0, t_0)) - f(v(x_0, t_0))\right] < 0,
\]
which contradicts (6). Therefore \(\tilde{u}(x, t) \geq \tilde{v}(x, t)\) for all \((x, t) \in S \times (0, T')\), so that we get
\(u(x, t) \geq v(x, t)\) for all \((x, t) \in \overline{S} \times [0, T)\), since \(T' < T\) is arbitrary. \(\square\)

When \(p \geq 2\), we obtain a strong comparison principle.

**Theorem 1.14 (Strong comparison principle)** Let \(T > 0 T \text{ may be } \infty\) and \(p \geq 2\), and let \(f\) be locally Lipschitz continuous on \(R\). Suppose that real-valued functions \(u(x, \cdot), v(x, \cdot) \in C[0, T)\) are differentiable in \((0, T)\) for each \(x \in \overline{S}\) and satisfy

\[
\begin{cases}
  u_t(x, t) - \Delta_{p,0} u(x, t) - f(u(x, t)) \\
  \geq v_t(x, t) - \Delta_{p,0} v(x, t) - f(v(x, t)), & (x, t) \in S \times (0, T), \\
  B[u] \geq B[v] & \text{on } \partial S \times [0, T), \\
  u(x, 0) \geq v(x, 0), & x \in \overline{S}.
\end{cases}
\]
(12)

If \(u(x^*, 0) > v(x^*, 0)\) for some \(x^* \in S\), then \(u(x, t) > v(x, t)\) for all \((x, t) \in S \cup \Gamma \times (0, T)\).

**Proof** First, note that \(u \geq v\) on \(\overline{S} \times [0, T')\) by the previous theorem. Let \(T' > 0\) be arbitrarily given with \(T' < T\). Since \(f\) is locally Lipschitz continuous on \(R\), there exists \(L > 0\) such that

\[
|f(a) - f(b)| \leq L|a - b|, \quad a, b \in [-m, m],
\]
(13)
where \(m = \max_{x \in \overline{S}} \max_{0 \leq t \leq T'}(|u(x, t)|, |v(x, t)|)\). Let \(\tau : \overline{S} \times [0, T'] \to \mathbb{R}\) be the function defined by

\[
\tau(x, t) := u(x, t) - v(x, t), \quad (x, t) \in \overline{S} \times [0, T'].
\]

Then \(\tau(x, t) \geq 0\) for all \((x, t) \in \overline{S} \times [0, T']\). From inequality (12) we have

\[
\tau_t(x^*, t) - \Delta_{p,0} u(x^*, t) - \Delta_{p,0} v(x^*, t) - [f(u(x^*, t)) - f(v(x^*, t))] \geq 0
\]
(14)
for all $0 < t \leq T'$. Then by the mean value theorem, for each $y \in \mathcal{S}$ and $0 \leq t \leq T'$, it follows that

\[
(u(y, t) - u(x^*, t))^2 |v(y, t) - v(x^*, t)| = (p - 1) |\zeta(x^*, y, t)|^p |\tau(y, t) - \tau(x, t)|,
\]

(15)

where $|\zeta(x^*, y, t)| \leq 2 \max_{x \in \mathcal{S}} \max_{0 \leq t \leq T'} |u(x, t)|, |v(x, t)|$. By (13) and (15) inequality (14) becomes

\[
\tau_t(x^*, t) \geq -d_w x^*(p - 1)[2M]^{p/2} \tau(x^*, t) - L |\tau(x^*, t)|
\]

\[
= -(d_w x^*(p - 1)[2M]^{p/2} + L) \tau(x^*, t).
\]

This implies

\[
\tau(x^*, t) \geq \tau(x^*, 0) e^{-(d_w x^*(p - 1)[2M]^{p/2} + L)t} > 0, \quad t \in (0, T'],
\]

(16)

since $\tau(x^*, 0) > 0$. Now suppose there exists $(x_0, t_0) \in \mathcal{S} \cup \Gamma \times (0, T']$ such that

\[
\tau(x_0, t_0) = \min_{x \in \mathcal{S} \cup \Gamma, 0 \leq t \leq T'} \tau(x, t) = 0.
\]

Case 1: $x_0 \in \mathcal{S}$.

Since $\tau(x_0, t_0) \leq \tau(x, t)$ for all $(x, t) \in \mathcal{S} \times [0, T']$, we have

\[
\tau_t(x_0, t_0) \leq 0
\]

and

\[
\Delta_{pw} u(x_0, t_0) - \Delta_{pw} v(x_0, t_0) \geq 0.
\]

Hence from inequality (12) we obtain

\[
0 \leq \tau_t(x_0, t_0) - \Delta_{pw} u(x_0, t_0) + \Delta_{pw} v(x_0, t_0) \leq 0.
\]

Therefore we have

\[
\Delta_{pw} u(x_0, t_0) - \Delta_{pw} v(x_0, t_0) = 0,
\]

which implies that $\tau(y, t_0) = 0$ for all $y \in \mathcal{S}$ with $y \sim x_0$. Now, for any $x \in \mathcal{S}$, there exists a path

\[
x_0 \sim x_1 \sim \cdots \sim x_m \sim x,
\]

since $\mathcal{S}$ is connected. By applying the same argument as before inductively we see that $\tau(x, t_0) = 0$ for every $x \in \mathcal{S}$, which is a contradiction to (16).
Case 2: \( x_0 \in \Gamma \).

By the boundary condition in (12) we have

\[
\mu(x) \left[ \frac{\partial u}{\partial n}(x_0, t_0) - \frac{\partial v}{\partial n}(x_0, t_0) \right] 
\geq \sigma(x) \left[ |u(x_0, t_0)|^{p-2} u(x_0, t_0) - |v(x, t)|^{p-2} v(x_0, t_0) \right] = 0,
\]

from which it follows that

\[
u(x_0, t_0) - u(x_1, t_0) \geq v(x_0, t_0) - v(x_1, t_0)
\]

for some \( x_1 \in S \) with \( x_0 \sim x_1 \). This means that \( \tau(x_1, t_0) = 0 \), which contradicts to Case 1. Hence we finally obtain that \( u(x, t) > v(x, t) \) for all \( (x, t) \in S \times (0, T) \), since \( T' < T \) is arbitrary.

\[\Box\]

Note that by the comparison principle, if \( f(0) = 0 \), then solutions \( u \) to equation (2) are nonnegative. On the other hand, it is natural that \( f \) is assumed to be positive on \((0, +\infty)\) when we deal with the blow-up theory. Hence we always assume that \( f \) is a locally Lipschitz continuous function on \( \mathbb{R} \), which is positive in \((0, +\infty)\) and \( f(0) = 0 \). Moreover, we assume that the initial data \( u_0 \) is nontrivial and nonnegative.

## 2 Blow-up: the concavity method

In this section, we discuss the blow-up phenomena of the solutions to equation (2), which is the main part of this paper.

**Definition 2.1** (Blow-up) We say that a solution \( u \) to equation (2) blows up at finite time \( T > 0 \) if there exists \( x \in S \) such that \( |u(x, t)| \to +\infty \) as \( t \nearrow T^- \) or, equivalently, \( \sum_{x \in S} |u(x, t)| \to +\infty \) as \( t \nearrow T^- \).

To state and prove our result, we introduce the following condition:

\[
(C_p) \quad \alpha F(u) \leq uf(u) + \beta u^p + \gamma, \quad u > 0,
\]

for some \( \alpha > 2, \beta \geq 0, \) and \( \gamma > 0 \) with \( 0 \leq \beta \leq \frac{(\alpha-2)\lambda_{p,0}}{p} \).

**Remark 2.2** We have the fact that \( \lambda_{p,0} = 0 \) if and only if \( \sigma \equiv 0 \) (see [12]). Therefore we can easily obtain that the condition on \( \alpha \) in \((C_p)\) depends on the boundary condition and \( p > 1 \) as follows:

(i) If \( \sigma \equiv 0 \), then \( \alpha > 2 \) for all \( p > 1 \).

(ii) If \( \sigma \not\equiv 0 \), then \( \alpha > 2 \) for all \( 1 < p \leq 2 \).

(iii) If \( \sigma \not\equiv 0 \), then \( \alpha \geq p \) for all \( p > 2 \).

We now state the main theorem of this paper:
**Theorem 2.3** For $p > 1$ and the function $f$ with hypothesis $(C_p)$, if the initial data $u_0$ satisfies

\[
\frac{1}{2p} \sum_{x,y \in S} |u_0(x) - u_0(y)|^p \omega(x,y) - \frac{1}{p} \sum_{z \in \Gamma} \sigma(z) |u_0(z)|^p + \sum_{x \in S} [F(u_0(x)) - \gamma] > 0,
\]

then the solutions $u$ to equation (2) blow up at finite time $T^*$ in the sense that

\[
\lim_{t \to T^*} \sum_{x \in S} u^2(x, t) = +\infty,
\]

where $\gamma$ is the constant in condition $(C_p)$.

**Proof** First, let us define functionals by

\[
A(t) := \sum_{x \in S} u^2(x, t), \quad t \geq 0,
\]

and

\[
B(t) := -\frac{1}{2p} \sum_{x,y \in S} |u(x, t) - u(y, t)|^p \omega(x,y) - \frac{1}{p} \sum_{z \in \Gamma} \sigma(z) |u(z, t)|^p + \sum_{x \in S} |F(u(x, t)) - \gamma|, \quad t \geq 0.
\]

Then we have from equation (2) and Lemma 1.7 that

\[
A'(t) = 2 \sum_{x \in S} u(x, t) \left[ \Delta_{p,\omega} u(x, t) + f(u(x, t)) \right]
\]

\[
= 2 \sum_{x \in S} u(x, t) \Delta_{p,\omega} u(x, t) + 2 \sum_{z \in \Gamma} u(z, t) \frac{\partial u}{\partial p}(z, t) + 2 \sum_{x \in S} u(x, t) f(u(x, t))
\]

\[
= -2 \sum_{x,y \in S} |u(x, t) - u(y, t)|^p \omega(x,y) - 2 \sum_{z \in \Gamma} \sigma(z) |u(z, t)|^p
\]

\[
+ 2 \sum_{x \in S} u(x, t) f(u(x, t)).
\]

Applying condition $(C_p)$ and Lemma 1.8, we can see that (18) implies

\[
A'(t) \geq 2 \sum_{x \in S} \left[ \alpha F(u(x, t)) - \beta u^p(x, t) - \gamma \right] - \sum_{x,y \in S} |u(x, t) - u(y, t)|^p \omega(x,y)
\]

\[
- 2 \sum_{z \in \Gamma} \sigma(z) |u(z, t)|^p
\]

\[
\geq 2\alpha B(t) - 2\beta \sum_{x \in S} u^p(x, t) + \left( \frac{\alpha}{p} - 1 \right) \sum_{x,y \in S} |u(x, t) - u(y, t)|^p \omega(x,y)
\]
\[ + 2 \left( \frac{\alpha}{p} - 1 \right) \sum_{z \in S} \frac{\sigma(z)}{\mu(z)} |u(z, t)|^p \]
\[ \geq 2\alpha B(t) + 2 \left[ \frac{(\alpha - p)\lambda_{p,0}}{p} - \beta \right] \sum_{x \in S} u^p(x, t) \]
\[ \geq 2\alpha B(t). \] (19)

Here it is easy to see that if \( \lambda_{p,0} = 0 \) or \( \alpha = p \), then \( \beta = 0 \). Therefore, even though \( \lambda_{p,0} = 0 \) or \( \alpha = p \), (19) is true.

On the other hand, we have from equation (2) and Lemma 1.7 that
\[
B'(t) = -\frac{1}{2} \sum_{x,y \in S} |u(y, t) - u(x, t)|^{p-2} [u(y, t) - u(x, t)][u_t(y, t) - u_t(x, t)] \omega(x, y) 
- \sum_{z \in S} \frac{\sigma(z)}{\mu(z)} |u(z, t)|^{p-2} u(z, t) u_t(z, t) + \sum_{x \in S} f(u(x, t)) u_t(x, t) 
= \sum_{x \in S} u_t(x, t) \left[ \Delta_{p,0} u(x, t) + f(u(x, t)) \right] 
= \sum_{x \in S} u_t^2(x, t) \geq 0. \] (20)

Now we will show that
\[
\frac{d}{dt} [A^{-\frac{\alpha}{2}}(t)B(t)] = -\frac{\alpha}{2} A^{-\frac{\alpha}{2} - 1} A'(t)B(t) + A^{-\frac{\alpha}{2}} B'(t) \geq 0 \] (21)
for all \( t > 0 \). Using the Schwarz inequality, from (19) and (20) we obtain that
\[
\frac{\alpha}{2} A'(t)B(t) \leq \frac{1}{4} \left[ A'(t) \right]^2 \leq \sum_{x \in S} u^2(x, t) \sum_{x \in S} u_t^2(x, t) 
= A(t)B'(t) \]
for all \( t > 0 \). Therefore inequality (21) is true, which implies that
\[
\frac{1}{2\alpha} A^{-\frac{\alpha}{2}}(t)A'(t) \geq A^{-\frac{\alpha}{2}}(t)B(t) \geq A^{-\frac{\alpha}{2}}(0)B(0) > 0. \] (22)

Solving the differential inequality (22), we obtain
\[
A(t) \geq \left[ \frac{1}{-(\alpha - 2)\alpha A^{-\frac{\alpha}{2}}(0)B(0)t + A^{-\frac{\alpha}{2}}(0)} \right]^{\frac{2}{\alpha - 2}}. 
\]
Hence \( A(t) \) blows up in finite time \( T \) with \( 0 < T \leq \frac{A(0)}{(\alpha - 2)\alpha B(0)}. \) \qed
Remark 2.4 The blow-up time can be estimated roughly as

\[ 0 < T \leq \frac{\frac{1}{(\alpha-2)\alpha} \sum_{x \in S} u_0^2(x)}{-\sum_{x \in S} |u_0(x)-u_0(y)|^{p(x,y)} - \sum_{x \in S} \frac{|u_0(x)|^p}{p} + \sum_{x \in \Gamma} \sigma(x) \mu(x) u_0^p(x) + \sum_{x \in S} \left[ F(u_0(x)) - \gamma \right]} \]

Remark 2.5 Chung and Choi [11] obtained the blow-up results for equation (2) under the Dirichlet boundary condition in the continuous setting, where \( p \geq 2 \) by using condition \((C_p)\). In fact, their condition had the assumption \( \alpha > p \), which is one of the main differences to us.

3 Discussion on condition \((C_p)\) with the initial data conditions

In this section, we compare conditions \((A_p)\), \((B_p)\), and \((C_p)\) and discuss the role of \( B(0) > 0 \).

First, we consider the Neumann boundary condition \( \sigma \equiv 0 \). Summing up over \( S \) to equation (2), we have

\[ \sum_{x \in S} u_t(x, t) = \sum_{x \in S} \Delta_{p_0} u(x, t) - \sum_{z \in S} \Delta_{p_0} u(z, t) + \sum_{x \in S} f(u(x, t)) \]

\[ = \sum_{x \in S} f(u(x, t)). \]

From this equality we can obtain that the time behavior of \( \sum_{x \in S} u(x, t) \) is determined by \( \sum_{x \in S} f(u(x, t)) \). Therefore by the definition of the blow-up we can expect that the blow-up condition for the solution \( u \) depends only on \( f \), not on \( p \). On the other hand, for all \( p > 1 \), condition \((C_p)\) is represented by

\[ (2 + \epsilon)F(u) \leq uf(u) + \gamma \]

for some \( \epsilon > 0 \) and \( \gamma > 0 \), which also does not depend on \( p \).

From now on we consider the boundary condition \( \sigma \neq 0 \). Let us recall the following conditions:

for \( 1 < p \leq 2 \),

\( (A_p) \quad (2 + \epsilon)F(u) \leq uf(u), \)

\( (B_p) \quad (2 + \epsilon)F(u) \leq uf(u) + \gamma, \)

\( (C_p) \quad (2 + \epsilon)F(u) \leq uf(u) + \beta u^p + \gamma, \)

where

\[ \epsilon > 0, \quad 0 \leq \beta \leq \frac{(2 + \epsilon - p)\lambda_{p,0}}{p}, \quad \text{and} \quad \gamma > 0, \]

and for \( p > 2 \),

\( (A_p) \quad (p + \epsilon)F(u) \leq uf(u), \)

\( (B_p) \quad (p + \epsilon)F(u) \leq uf(u) + \gamma, \)
\[(C_p)\quad (p + \epsilon)F(u) \leq uf(u) + \beta u^p + \gamma,\]

where
\[
\epsilon \geq 0, \quad 0 \leq \beta \leq \frac{\epsilon \lambda_{p,0}}{p}, \quad \text{and} \quad \gamma > 0
\]

for every \(u \geq 0\). Here \(F(u) := \int_0^u f(s) \, ds\).

It is easy to see that \((A_p)\) implies \((B_p)\) and in turn \((B_p)\) implies \((C_p)\). In fact, the first eigenvalue \(\lambda_{p,0}\), which depends on the domain, is not contained in conditions \((A_p)\) and \((B_p)\). However, condition \((C_p)\) depends on the domain due to the term \(\beta u^p\). From this point of view, condition \((C_p)\) can be understood as a refinement of \((B_p)\), corresponding to the domain. On the contrary, if a function \(f\) satisfies \((C_p)\) for every domain, then the first eigenvalue \(\lambda_{p,0}\) can be arbitrarily small so that condition \((C_p)\) gets arbitrarily closer to \((B_p)\).

**Remark 3.1** In fact, there have been efforts to obtain the condition \(\epsilon = 0\) in the continuous analogue. For example, Junning studied the blow-up solutions to equation \((2)\) in the continuous setting under the Dirichlet boundary condition with the assumption \(\epsilon = 0\) in \((A_p)\) and the initial data \(u_0\) satisfying
\[
-\frac{1}{p} \int_\Omega |\nabla u_0(x)|^p \, dx + \int_\Omega F(u_0(x)) \, dx \geq \frac{4(p-1)}{T(p-2)^2} \int_\Omega u_0^2(x) \, dx,
\]
where \(p > 2\) and \(\Omega \subset \mathbb{R}^N\) (see [7]). From this point of view, for \(p > 2\), our condition \(\epsilon \geq 0\) with \(B(0) > 0\) improves the conventional results.

Now we consider the cases \(p > 2\) and \(1 < p \leq 2\) to investigate conditions \((A_p)\), \((B_p)\), and \((C_p)\).

**Case 1: \(p > 2\).**

Assuming that \(\epsilon > 0\), we obtain that condition \((C_p)\) is equivalent to
\[
\frac{d}{du} \left( \frac{F(u)}{u^{p+\epsilon}} - \frac{\gamma}{p+\epsilon} \cdot \frac{1}{u^{p+\epsilon}} - \frac{\beta}{\epsilon} \cdot \frac{1}{u^\epsilon} \right) \geq 0, \quad u > 0. \quad (23)
\]

In a similar way, assuming that \(\epsilon = 0\), we have
\[
\frac{d}{du} \left( \frac{F(u)}{u^p} - \frac{\gamma}{p} \cdot \frac{1}{u^p} \right) \geq 0, \quad u > 0. \quad (24)
\]

Hence \((23)\) and \((24)\) imply that for all \(u > 0\) and \(p > 2\),
\[
(A_p) \quad \text{holds if and only if} \quad F(u) = u^{p+\epsilon} h_1(u),
\]
\[
(B_p) \quad \text{holds if and only if} \quad F(u) = u^{p+\epsilon} h_2(u) + b,
\]
\[
(C_p) \quad \text{holds if and only if} \quad F(u) = u^{p+\epsilon} h_3(u) + au^p + b,
\]

for some constants \(\epsilon > 0\), \(a \geq 0\), and \(b > 0\) with \(0 \leq a \leq \frac{\lambda_{p,0}}{p}\), where \(h_1\), \(h_2\), and \(h_3\) are nondecreasing function on \((0, +\infty)\).

**Case 2: \(1 < p \leq 2\).**
We obtain that \((C_p)\) is equivalent to
\[
\frac{d}{du} \left( F(u) \left( \frac{1}{u^{2+\epsilon}} - \frac{1}{2+\epsilon} \cdot \frac{\beta}{2+\epsilon - p} \cdot \frac{1}{u^{2+\epsilon - p}} \right) \right) \geq 0, \quad u > 0,
\]
which implies that for all \(u > 0\) and \(1 < p \leq 2,\)
\[
\begin{align*}
(A_p) & \quad \text{holds if and only if } F(u) = u^{2+\epsilon} h_1(u), \\
(B_p) & \quad \text{holds if and only if } F(u) = u^{2+\epsilon} h_2(u) + b, \\
(C_p) & \quad \text{holds if and only if } F(u) = u^{2+\epsilon} h_3(u) + au^p + b,
\end{align*}
\]
for some constants \(\epsilon > 0, a \geq 0,\) and \(b > 0\) with \(0 \leq a \leq \frac{\lambda_{p,0}}{p}\), where \(h_1, h_2,\) and \(h_3\) are nondecreasing function on \((0, +\infty)\).

In case 1 and case 2, the constants \(\epsilon, a,\) and \(b\) may be different in each case. Also, the nondecreasing function \(h_1\) is nonnegative on \((0, +\infty),\) but \(h_2\) and \(h_3\) may be not nonnegative in general.

**Theorem 3.2** For \(p > 1,\) let \(f\) be a real-valued function satisfying condition \((C_p).\) Suppose that \(f(u) \geq \lambda u^{p-1}, u > 0,\) for some \(\lambda > \lambda_{p,0}.\) Then the following statements are true.

(i) There exists \(m > 0\) such that \(h_3(u) > 0\) for \(u \geq m.\)

(ii) There exists \(\zeta > 0\) such that \(f(u) \geq \zeta u^{\max\{p-1,1\} + \epsilon}, u \geq m.\)

(iii) Conditions \((B_p)\) and \((C_p)\) are equivalent when \(p \geq 2.
\)

**Proof** (i): First, it follows from the fact \(F(u) \geq \frac{\lambda}{p} u^p > \frac{\lambda_{p,0}}{p} u^p\) that
\[
u^{\max\{p,2\} + \epsilon} h_3(u) = F(u) - au^p - b \geq \frac{\lambda - \lambda_{p,0}}{p} u^p - b,
\]
which goes to \(+\infty\) as \(u \to +\infty.\) Therefore we can find \(m > 0\) such that \(h_3(m) > 0.\)

(ii): (i) implies that
\[
f(u) \geq u^{\max\{p,2\} + \epsilon} h_3(u), \quad u \geq m.
\]
Putting it into condition \((C_p),\) we obtain
\[
\alpha u^{\max\{p,2\} + \epsilon} h_3(m) \leq uf(u) + \beta u^p + \gamma.
\]
Hence we obtain that
\[
\alpha u^{\max\{p-1,1\} + \epsilon} h_3(m) \leq uf(u) + \beta u^{p-1} + \frac{\gamma}{u} \leq \left(1 + \frac{\beta}{\lambda_{p,0}}\right)f(u) + \gamma, \quad u \geq m > 0,
\]
which gives
\[
f(u) \geq \zeta u^{1+\epsilon}, \quad u \geq m > 0,
\]
for some \(\zeta > 0.\)
(iii): Now consider the case $p \geq 2$. Then it is trivial that $(B_p)$ and $(C_p)$ are equivalent when $\epsilon = 0$. Therefore we may assume that $\epsilon > 0$. Since $0 \leq \beta \leq \frac{\epsilon \lambda_0}{p}$ and $f(u) \geq \lambda u > \lambda_{p,0}u$, $u > 0$, it follows from $(C_p)$ that

$$\epsilon_1 F(u) + (p + \epsilon_2)F(u) \leq uf(u) + \frac{\epsilon \lambda_0}{p} u^p + \gamma,$$

where $\epsilon_1 = \frac{\epsilon \lambda_0}{\lambda} > 0$ and $\epsilon_2 = \epsilon - \epsilon_1 > 0$. This implies that for every $u > 0$,

$$uf(u) + \gamma \geq (p + \epsilon_2)F(u) + \epsilon_1 \int_0^u \left[f(s) - \lambda s^{p-1}\right] ds$$

$$\geq (p + \epsilon_2)F(u),$$

which implies $(B_p)$. □

In general, only condition $(C_p)$ may not guarantee the blow-up solutions for every initial data $u_0$. Therefore, from now on, we are going to discuss when we can find initial data $u_0$ that satisfies $B(0) > 0$.

**Lemma 3.3** Let $p > 1$. If there exists $v_0 > 0$ such that $F(v_0) > \frac{\omega_0}{p} v_0^p + \gamma_1$, where $\gamma_1 \geq \gamma$, then there exists the initial data $u_0$ such that $B(0) > 0$. Here $\omega_0 := \max_{x \in S} d_w x$.

**Proof** First of all, there exist $a, b > 0$ with $0 < a < b$ such that $F(v) > \frac{\omega_0}{p} v^p + \gamma_1$, $v \in (a, b)$, since $F$ is continuous on $[0, +\infty)$. Now, we consider the function $u_0(x)$ satisfying

$$\begin{cases}
  a < u_0(x) < b, & x \in S, \\
  0 < u_0(x) < b, & x \in \Gamma, \\
  u_0(x) = 0, & x \in \partial S \setminus \Gamma,
\end{cases}$$

which satisfies the boundary condition $B[u_0] = 0$. Then we obtain that

$$B(0) = \frac{1}{p} \sum_{x \in S} \sum_{y \in S} \left|u_0(y) - u_0(x)\right|^{p-2} \left[uf(u) - u_0(x)\right]u_0(x)w(x,y)$$

$$+ \sum_{x \in S} F(u_0(x)) - \gamma'$$

$$\geq - \frac{1}{p} \sum_{x \in S} \sum_{y \in S} u_0^p(x)w(x,y) + \sum_{x \in S} [F(u_0(x)) - \gamma]$$

$$= - \frac{1}{p} \sum_{x \in S} u_0^p(x)d_w x + \sum_{x \in S} [F(u_0(x)) - \gamma]$$

$$\geq \sum_{x \in S} \left[F(u_0(x)) - \frac{\omega_0}{p} u_0^p(x)\right] - \gamma |S|$$

$$\geq \gamma_1 |S| - \gamma |S| \geq 0,$$

where $|S|$ denotes the number of vertices in $S$. □
Corollary 3.4  The following statements are true.

(i) If there exists \((a, b)\) such that 
\[
F(v) > \frac{\omega_0}{p} v^p + \gamma_1, \quad \gamma_1 \geq \gamma
\]
for every \(v \in (a, b)\), then for every \(u_0\) satisfying the boundary condition \(B[u_0] = 0\) such that
\[
\begin{cases}
  a < u_0(x) < b, & x \in S, \\
  0 < u_0(x) < b, & x \in \Gamma, \\
  u_0(x) = 0, & x \in \partial S \setminus \Gamma,
\end{cases}
\]
we see that \(B(0) > 0\).

(ii) If \(F(v) > \omega_0 \max\{2 + \epsilon_1, p\} + \gamma_1, \quad \epsilon_1 > 0, \quad \gamma_1 \geq \gamma\), for every \(v \in (0, +\infty)\) on \(S \cup \Gamma\), then the solutions blow up for every initial data \(u_0 > 0\) on \(S \cup \Gamma\). Here \(\omega_0 := \max_{x \in S} d_x \omega x\).

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