Structural Stability Analysis of Proteins Using End-to-End Distance: A 3D-RISM Approach

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Abstract: The stability of a protein is determined from its properties and surrounding solvent. In our previous study, the total energy as a sum of the conformational and solvation free energies was demonstrated to be an appropriate energy function for evaluating the stability of a protein in a protein folding system. We plotted the various energies against the root mean square deviation, required as a reference structure. Herein, we replotted the various energies against the end-to-end distance between the N- and C-termini, which is not a required reference and is experimentally measurable. The solvation free energies for all proteins tend to be low as the end-to-end distance increases, whereas the conformational energies tend to be low as the end-to-end distance decreases. The end-to-end distance is one of interesting measures to study the behavior of proteins.

Keywords: molecular solvation theory; 3D-RISM; solvation-free energy; conformational energy; molecular dynamics; simulation; protein; structural stability; end-to-end distance

1. Introduction

AlphaFold2 [1] and RoseTTAFold [2], which are protein structure software programs using amino acid sequences, have shown a high level of accuracy. In addition, DeepMind and EMBL’s European Bioinformatics Institute have created a database of 21 model-organism proteome structures for free use by the academic community [3]. The development and movement of protein structure prediction have increased the importance of protein-structure-based methods. For example, it is necessary to select reasonable and stable structures from among predicted structure candidates by incorporating the solvent effect. Moreover, it is difficult to investigate structural fluctuations and conformational changes in a protein, which can affect their functions, using prediction software. It is important to investigate the structural stability, including the solvent effect during conformational changes and the protein-folding process. The three-dimensional reference interaction site model (3D-RISM), which is the statistical mechanical theory for molecular liquids, is one of the structure-based methods applied [4,5]. The 3D-RISM theory provides the distribution functions of a solvent around a biomolecule such as a protein using the solute molecule structure as input. We can know the position of water [6–8] or ions [9–11] around the protein from the distribution function. In this way, we can calculate the physical quantity of the surrounding solvent around the protein, and in particular, estimate the stability of the proteins.

In a previous study [12], we discussed the structural stability of proteins performed on Anton’s molecular dynamics (MD) simulation trajectory [13]. For many structural calculations, we summarized that the sum of the conformational energy and solvation free energy using 3D-RISM theory is a reasonable indicator of protein structural stability. In the previous study, we plotted various energies as a function of the root-mean-square-deviation (RMSD) for atomic Cα positions. This is a useful approach for investigating the structural...
stability of a protein [14–18]. However, the reference structure of RMSD, which, in this case, is a native structure, must be known in advance. We also plotted various energies against the radius of gyration in the Supporting Information in Ref. [12]. The radius of gyration is a physical quantity that can be measured experimentally and calculated without the reference structure. Plots against the radius of gyration are used to study the protein stability as well as the RMSD [19–22]. Figure 1 shows the Cα-RMSD against the radius of gyration for the four proteins (see also Ref. [12]). It can be seen that the vertical distribution of all proteins is concentrated at a certain value of the radius of gyration. The value of the radius of gyration settles to approximately the same value when the protein becomes compact. It might be difficult to compare the stabilities between native and compact structures, whereas the radius of gyration is one of appropriate physical quantities for investigating stabilities.

A fluorescent resonance energy transfer (FRET) is a useful technique for studying the conformational distribution and dynamics of biological molecules. FRET, detected at the single-molecule level, provides new opportunities to investigate the detailed kinetics of structural changes [23–25]. A sequential data assimilation method for single-molecule FRET data combined with MD simulations was developed by Matsunaga et al. [26], who also devised a machine learning method to combine the complementary information from single-molecule FRET experiments and an MD simulation to construct a consistent model of conformational dynamics [27–29]. It has become possible to associate information on the distance between fluorescent molecules obtained from FRET with structural information at the atomic level through an MD simulation. Thus, we can observe information regarding the end-to-end distance between the N- and C-termini of a protein through experiments such as FRET.

In the present study, we attempted to analyze the various energies of proteins as a function of the end-to-end distance, which does not require the reference structure and is experimentally measurable. From the analysis, the solvation free energy as a function of the end-to-end distance has a characteristic tendency among four proteins.
2. Computational Details

As in our previous study, we used the following four proteins: superchignolin (a small protein, CLN025), the WW domain variant GTT (a β-sheet protein, mGTT), a triple mutant of the redesigned protein G variant NuG2 (an α+β protein, mNuG2), and the de novo-designed three-helix bundle protein α3D (an α-helical protein, ma3D). The details of Anton’s MD simulations for these proteins can be found in the Supporting Information in [13]. In addition, CLN025, mGTT, mNuG2, and ma3D contain 10, 35, 56, and 73 amino acids, respectively.

To investigate the structural stability of the proteins, we introduce the total energy $E_{\text{tot}}$, which is the sum of the conformational energy $E_{\text{conf}}$ and the solvation free energy (SFE) $E_{\text{sol}}$:

$$E_{\text{tot}} = E_{\text{conf}} + E_{\text{sol}}.$$  (1)

We used GROMACS [30] for calculating the conformational energy with a CHARMM22* force field [31–33]. The SFE of the proteins is calculated using the 3D-RISM theory based on the reference-modified density functional theory [34]. The number densities of water and the optimal hard sphere diameters used for the thermodynamic states at 298, 325, 350, and 373 K are shown in Table 1 (See Ref. [35]). We conducted an SFE calculation using the 3D-RISM theory with the original code written for a GPU [36]. An SFE calculation of a mNuG2 protein takes within 10 s on NVIDIA V100 GPU (2563 grids, water solvent).

The structures were applied every 20 ns (every 1000 samples) for CLN025 and every 200 ns (every 1000 samples) for the others when extracted from Anton’s trajectory during the calculations. The total numbers of sampling structures are 5348, 5686, 5780, and 3534 for CLN025, mGTT, mNuG2, and ma3D, respectively. For the Cα-RMSD calculations, the reference structures were taken from the supporting information provided by Honda et al. [37], i.e., 2F21.pdb, 1MIO.pdb, and 2A3D.pdb for CLN025, mGTT, mNuG2, and ma3D, respectively. These structures correspond to the native structures. The end-to-end distance is defined as the distance between the Cα atoms of the N- and C-termini.

Table 1. Experimental number density of water [38] and optimal diameters of the hard sphere diameter for SFE calculations with the reference-modified density functional theory at several temperatures along 1 atm [35].

| Temperature [K] | Number Density [Å⁻³] | Diameter [Å] |
|----------------|----------------------|--------------|
| 298            | 0.033329             | 2.87500      |
| 325            | 0.032994             | 2.87125      |
| 350            | 0.032526             | 2.87000      |
| 375            | 0.031924             | 2.87250      |

3. Results and Discussion

First, we show the lowest-total-energy and shortest end-to-end distance structures of the four proteins in Figure 2. In Table 2, Cα-RMSD, the radius of gyration, the end-to-end distance, and the total energy of the two structures for each protein are listed. For the four proteins, the lowest-total-energy structures correspond to the native structures. The lowest-total energy and the shortest end-to-end distance structures are compact because the values of the radius of gyration for two structures are small and similar to each other for four proteins as listed in Table 2.

For CLN025 (Figure 2a,b) and mGTT (Figure 2c,d), the shortest end-to-end distance structures are similar to the native structures because Cα-RMSD for the shortest end-to-end distance is small and similar to that for the lowest-total-energy distance. The native structures tend to have short end-to-end distances. Note that even though the lowest total energy and shortest end-to-end distance structures are similar, the total energy values are different, as listed in Table 2.
Figure 2. Backbone structures with the lowest total energy and the shortest end-to-end distance for (a,b) CLN025, (c,d) mGTT, (e,f) mNuG2, and (g,h) ma3D. Circles indicate the terminal portions of the protein. Chimera [39] was used to generate the figures.
Table 2. Cα-RMSD, the end-to-end distance, the radius of gyration (Rg), and the total energy of the lowest-total-energy ($E_{tot}$) and the shortest end-to-end distance (distance) structures for each protein in Figure 2.

| Protein | Minimum | Cα-RMSD [Å] | End-to-End Distance [Å] | Rg [Å] | $E_{tot}$ [kcal/mol] |
|---------|---------|--------------|--------------------------|--------|---------------------|
| CLN025  | $E_{tot}$ | 0.7          | 5.0                      | 6.2    | $-177.0$            |
|         | distance | 1.0          | 4.0                      | 6.3    | $-136.1$            |
| mGTT    | $E_{tot}$ | 1.6          | 5.0                      | 10.1   | $-675.0$            |
|         | distance | 1.8          | 3.6                      | 10.2   | $-596.0$            |
| mNuG2   | $E_{tot}$ | 1.9          | 27.4                     | 10.7   | $-563.4$            |
|         | distance | 8.2          | 3.9                      | 11.2   | $-493.9$            |
| ma3D    | $E_{tot}$ | 3.6          | 43.1                     | 13.2   | $-1501.7$           |
|         | distance | 14.3         | 4.2                      | 12.9   | $-1287.9$           |

By contrast, for mNuG2 ((e,f)) and ma3D ((g,h)), there is a large difference between the native and shortest end-to-end distance structures, as shown in Figure 2. The Cα-RMSDs for the shortest end-to-end distances were large. The lowest-total-energy structures of these proteins tend to have slightly larger end-to-end distances. Because of the different structures, a large difference in the total energy between the lowest total energy and shortest end-to-end distance structures was also observed.

We examine the relationships between the radius of gyration and end-to-end distance and between Cα-RMSD and end-to-end distance in the four proteins in Figures 3 and 4, respectively. For CLN025, the radius of gyration and end-to-end distance appeared to have a positive correlation as shown in Figure 3. The reason is the simple structure, which is a turn one for CLN025. For mGTT, mNuG2, and ma3D, the structures with small values of the radius of gyration were spread in the end-to-end distance direction. In the folding trajectories, many compact structures were generated. For the proteins with complicated structures, the end-to-end distance distinguishes the compact structures.

Figure 3. The radius of gyration of (a) CLN025, (b) mGTT, (c) mNuG2, and (d) ma3D as functions of the end-to-end distance.
In Figure 4, the distributions for the end-to-end distance are different for all proteins, whereas those for the radius of gyration are similar to each other, as shown in Figure 1. Because the native structures are energetically stable and occur frequently during simulations, the point-concentrated areas correspond to the native structures, which have low RMSDs. For CLN025, shown in Figure 4a, the point-concentrated area corresponds to the shortest end-to-end distance and the lowest Cα-RMSD. The Cα-RMSD and end-to-end distance appeared to have a positive correlation. However, for mGTT, shown in Figure 4b, the lowest Cα-RMSD structures were spread in the end-to-end distance direction from 5 to 20 Å. This indicates that the structures in the area are close to stable, but the N- or C-termini fluctuate. For mNuG2, shown in Figure 4c, the point-concentrated area was narrow and corresponded to a slightly large end-to-end distance (approximately 27 Å). For ma3D, shown in Figure 4d, the point-concentrated area is spread along the end-to-end distance from 30 to 45 Å. As shown above, the behaviors of the end-to-end distance within the vicinity of the most stable structure are different for the four proteins. The relationship between Cα-RMSD and end-to-end distance depends on the protein. For mGTT, mNuG2, and ma3D, structures with a similar end-to-end distance include not only the native structure but also other structures. It is difficult to use the end-to-end distance for identifying the native structure without the reference. However, the conformational energy and the solvation free energy as functions of the end-to-end distance have characteristics as explained below.

Figure 5 shows the total energy of each protein as a function of the end-to-end distance. The patterns of the point distribution for the end-to-end distance were different for the four proteins, whereas those for the Cα-RMSD are similar, as shown in Figure 2 of Ref. [12]. The ranges of the total energy of CLN025, mGTT, mNuG2, and ma3D, shown in Figure 5a–d, respectively, are approximately 100, 180, 250, and 350 kcal/mol. The range of total energy expands as the protein size increases. The end-to-end distances for the point-concentrated areas corresponding to the native structures are 5 Å, 5 Å, 27 Å, and 30–45 Å for CLN025, mGTT, mNuG2, and ma3D in Figure 5a–d, respectively. The broad distribution along the total energy within the regions are observed. For mGTT, shown in Figure 5d, the structures where the end-to-end distance is between 7 Å and 20 Å correspond to the native-like structure in which the N- or C-termini fluctuate. A broad distribution along the total energy of the regions was also observed.
Figure 5. Total energy ($E_{tot}$) of (a) CLN025, (b) mGTT, (c) mNuG2, and (d) ma3D as a function of the end-to-end distance. A red point represents the average value for each width 1 Å.

The red point represents the average value of the total energy for each end-to-end distance. The average values for the regions of the native structures were lower than those of the other regions. The regions correspond to where the end-to-end distances are 5 Å, 5–20 Å, 27 Å, and 30–45 Å for CLN025, mGTT, mNuG2, and ma3D, respectively. There were no significant changes in the average total energy within the region of the native structure. For CLN025 and mGTT, shown in Figure 5a,b, respectively, the average value increases as the end-to-end distance increases because the shortest end-to-end distance structures correspond to the lowest-energy structures. In addition, NuG2 and ma3D, shown in Figure 5c,d, respectively, have different tendencies because the shortest end-to-end distance structures do not correspond to the lowest-energy structures.

Figure 6 shows the conformational energy of each protein as a function of the end-to-end distance. Conformational energy ranges of CLN025, mGTT, mNuG2, and ma3D, shown in Figure 6a–d, respectively, were approximately 250, 600, 750, and 1100 kcal/mol. Compared to the total energy, the range of the conformational energy is wider because it competes with the SFE. The conformational energy and the SFE are inversely correlated, as shown in Figure 4d in Ref. [12]. The point-concentrated areas are similar to those for the total energy. The red point represents the average value of the conformational energy for each end-to-end distance.

For CLN025 and mGTT, shown in Figure 6a,b, respectively, the broad energy distributions near the stable states, where the end-to-end distances are 4–6 Å are also observed and are lower than those where the end-to-end distance is more than 7 Å. The average values rapidly decreased as the end-to-end distances decreased from 7 Å to 5 Å. The native structures with an end-to-end distance of 4–6 Å for both proteins had the lowest conformational energy. These results indicate that the conformational energy determines the stable structure of CLN025 and mGTT. For these proteins, the longer the end-to-end distance is, the higher the average conformational energy.
In Figure 6c,d, the broad energy distributions corresponding to the stable structures where the end-to-end distances are 24–25 Å for mNuG2 and 32–42 Å for ma3D shift to higher positions, unlike those for the total energy. Similarly, the average values near the native structure are higher. The lowest conformational energy structures correspond to the shortest end-to-end structures. This means that the most stable structure is not determined by the conformational energy in mNuG2 and ma3D. In particular, for ma3D, there is no significant difference between the average values of the conformational energy when the end-to-end distance is less than 50 Å. For proteins, the longer the end-to-end distance is, the higher the average conformational energy. The conformational energy and end-to-end distance have a slight positive correlation.

Next, we show the SFE as a function of the end-to-end distance in Figure 7. The distribution of the SFE is close to an upside-down reversal of that of the conformational energy owing to mutual competition. However, a perfect upside-down symmetry is not shown because the SFE reflects hydrogen bond formations at the surface of the protein, whereas the conformational energy reflects the complex hydrogen bond formation within the protein. The SFE decreases as the end-to-end distance increases, not only for CLN025 and mGTT, as shown in Figure 7a,b, respectively, where the end-to-end distances of the stable states are small, but also for mNuG2 and ma3D, shown in Figure 7c,d, where the end-to-end distances of the stable structures are large. Although the native structures of the four proteins have different end-to-end distances, the SFE as a function of the end-to-end distances has a similar tendency.
Finally, we show the temperature dependence of the average value of the SFE with different end-to-end distances in Figure 8. The triangles, crosses, and squares correspond to the average values of the SFE for end-to-end distances of 10, 20, 30, and 40 Å, respectively. Note that the conformational energy of a protein does not depend on temperature because the structures are extracted in the same simulations. The actual distribution of protein structures will be different when MD simulations are conducted at different temperatures. We ignored this point herein.

Figure 8. Solvation free energy ($E_{\text{sol}}$) of (a) CLN025, (b) mGTT, (c) mNuG2, and (d) ma3D as a function of temperature. Circles, triangles, crosses, and squares correspond to the end-to-end distance 10, 20, 30, and 40 Å.
For a liquid phase of water at 1 atm, the SFE for structures with the same end-to-end distance is lower as the temperature is further decreased, as shown in Figure 8. The values of the slope for CLN025, mGTT, mNuG2, and mα3D, shown in Figure 8, are approximately 0.4, 1.1, 1.7, and 2.1, respectively. Because the slope values for different end-to-end distance structures are similar, they do not depend on the end-to-end distances. The slope values depend on the protein size and increase as the protein becomes larger. The slope value at 10 Å is lower than that at 20 Å in mα3D, shown in Figure 8d, because there are fewer sample points at below 10 Å, and the error at this value is large.

4. Conclusions

We investigated the energetics of proteins by plotting various energies against the end-to-end distance between the N- and C-termini, which does not require the reference structure and is experimentally measurable. We discussed how the end-to-end distance information of proteins can be incorporated into the stability of the proteins. The distributions of the total energy as a function of the end-to-end distance are different for the four proteins because native structures do not correspond to the shortest end-to-end distances. However, based on a number of calculations for all proteins, the characteristic behaviors of the distributions of the conformational energy and SFE were observed as the end-to-end distance increased. The solvation free energy tends to be low as the end-to-end distance increases, and the conformational energy tends to be high as the end-to-end distances decrease. The end-to-end distance is one of interesting measures for studying the behavior of proteins.

Here, we discuss the physical aspects of proteins as biopolymers. Proteins can be regarded as water-rich macromolecules. It is considered that the softness of polymers, in general, can be explained through entropic elasticity [40–42]. Polymer gels containing a large amount of water solvent are significantly softer than rubber without water and show a negative energy elasticity [43–45]. The microscopic origin of negative energy elasticity is the solvent–polymer interaction with the deformation of a polymer. When the polymer chain is mechanically stretched, the number of water molecules interacting with the chain increases, decreasing the total energy of the solvent–polymer interaction. The result in which the SFE decreases with an increase in the end-to-end distance might be related to the origin of the negative elastic energy of a polymer gel.

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Abbreviations

3D-RISM  Three-dimensional reference interaction site model
MD        Molecular dynamics
RMSD      Root-mean-square deviation
FRET      Fluorescence resonance energy transfer

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