A Users’ Guide to Infra-nilmanifolds and Almost–Bieberbach groups

Karel Dekimpe∗
KU Leuven Campus Kulak Kortrijk, E. Sabbelaan 53, 8500 Kortrijk, Belgium
March 31, 2017

Abstract
The aim of this text is to provide a clear description of the theory of Infra-nilmanifolds and their fundamental groups, the almost-Bieberbach groups. For most of the proofs of the results, we refer to the literature. Nevertheless, at certain places we offer a somewhat different and new approach and in these cases we provide full proofs. We have tried to keep the prerequisites as minimal as possible. We also provide completely worked out examples, with explicit computations.

1 Flat manifolds and crystallographic groups
The class of infra-nilmanifolds is a natural generalization of the class of flat manifolds. So before entering the world of infra-nilmanifolds, let us first explore that of the flat manifolds. In this section we will describe things in quite some detail, since a good understanding of this part is indispensable for the rest of the text. The material in this section is standard and can be found in e.g. [10, 87, 92]. We also refer to these references for all the proofs of the results mentioned in this section.

Let $\mathbb{R}^n$ be the $n$-dimensional Euclidean space. By $\text{Isom}(\mathbb{R}^n)$, we will denote the group of isometries of Euclidean $n$-space . Any element $f \in \text{Isom}(\mathbb{R}^n)$ can be written as a composition of an orthogonal map $A : \mathbb{R}^n \to \mathbb{R}^n$ and a translation $t_a : \mathbb{R}^n \to \mathbb{R}^n : r \mapsto a + r$, for some $a \in \mathbb{R}^n$. The orthogonal map $A$ is a linear map and so we can identify $A$ with its matrix representation with respect to the standard orthogonal basis of $\mathbb{R}^n$. After this identification, we can say that $A \in O(n)$, where $O(n)$ is the group of orthogonal $n \times n$ matrices. It follows that any element $f$ of $\text{Isom}(\mathbb{R}^n)$ can be identified with a tuple $(a, A) \in \mathbb{R}^n \times O(n)$. Now, let $f = (a, A)$ and $g = (b, B)$ be two isometries, then

$$(f \circ g)(r) = f(b + Br) = a + Ab + ABr,$$

from which it follows that $f \circ g$ is represented by the tuple $(a + Ab, AB)$. As a consequence, it follows that $\text{Isom}(\mathbb{R}^n)$ is the semidirect product group $\mathbb{R}^n \rtimes O(n)$.

Recall that to construct the semidirect product of two groups $G$ and $H$, one first chooses a group homomorphism $\varphi : H \to \text{Aut}(G)$, then the semidirect product $G \rtimes_\varphi H$, or just $G \rtimes H$ when $\varphi$ is clear from the context, is the group where the underlying set is the Cartesian product $G \times H$ and where the product is given by

$$\forall g_1, g_2 \in G, \forall h_1, h_2 \in H : (g_1, h_1)(g_2, h_2) = (g_1 \varphi(h_1)(g_2), h_1h_2).$$

It is an easy exercise to show that this construction indeed yields a group. When $\varphi : H \to \text{Aut}(G) : h \mapsto 1_G$ is the trivial homomorphism, the result of forming the semidirect product $G \rtimes H$

∗Supported by long term structural funding – Methusalem grant of the Flemish Government.
is the ordinary direct product $G \times H$ of two groups. Of course, when $G$ and $H$ are Lie groups (or topological groups), one requires the usual continuity in this construction. Note that both $G$ and $H$ can be seen as subgroups of $G \times H$ by identifying them with $G \times \{1\}$ and $\{1\} \times H$ respectively. Under this identification, we have that $G$ is a normal subgroup of $G \times H$, while in general $H$ is not normal. The projection $p : G \times H \to H$ is a group homomorphism, with kernel $G$.

In the situation above, any orthogonal map $A$ can be seen as a (continuous) homomorphism of the abelian group $\mathbb{R}^n$ and so there is an inclusion $O(n) \subseteq \text{Aut}(\mathbb{R}^n)$ and it is this inclusion which is used as the homomorphism $\varphi$ to construct the semidirect product $\mathbb{R}^n \ltimes O(n)$. Analogously, we can construct the affine group $\text{Aff}(\mathbb{R}^n) = \mathbb{R}^n \rtimes \text{GL}(\mathbb{R}^n)$. So elements of $\text{Aff}(\mathbb{R}^n)$ are tuples $(a,A) \in \mathbb{R}^n \times \text{GL}(\mathbb{R}^n)$ and the product is given by

$$\forall a,b \in \mathbb{R}^n, \forall A, B \in \text{GL}(\mathbb{R}^n) : (a, A)(b, B) = (a + Ab, AB).$$

It is obvious that $\text{Isom}(\mathbb{R}^n) \subseteq \text{Aff}(\mathbb{R}^n)$. Of course, also elements of the affine group $\text{Aff}(\mathbb{R}^n)$ can be seen as maps of $\mathbb{R}^n$, where just as for the isometry group we have that $(a, A)(r) = a + Ar$ for all $a, r \in \mathbb{R}^n$ and $A \in \text{GL}(\mathbb{R}^n)$. It follows that there is a left action of $\text{Aff}(\mathbb{R}^n)$ on $\mathbb{R}^n$ given by

$$\text{Aff}(\mathbb{R}^n) \times \mathbb{R}^n \to \mathbb{R}^n : ((a, A), r) \mapsto (a, A) \cdot r = a + Ar.$$  

As a consequence, also any subgroup $E$ of $\text{Aff}(\mathbb{R}^n)$ (or of $\text{Isom}(\mathbb{R}^n)$) acts on $\mathbb{R}^n$.

**Remark.** The groups $\text{Aff}(\mathbb{R}^n)$ and $\text{Isom}(\mathbb{R}^n)$ are Lie groups (using the usual smooth manifold structures on the underlying sets $\mathbb{R}^n \times \text{O}(n)$ and $\mathbb{R}^n \times \text{GL}(\mathbb{R}^n)$).

As mentioned above when introducing the semidirect product of two groups, we can view $\mathbb{R}^n$ as a normal subgroup of $\text{Isom}(\mathbb{R}^n)$ and $\text{Aff}(\mathbb{R}^n)$. In both cases, this is exactly the group of translations. When $G \subseteq \text{Aff}(\mathbb{R}^n)$, we will then write $G \cap \mathbb{R}^n$ for the group of translations in $G$, which is then a normal subgroup of $G$. We will use $r : \text{Aff}(\mathbb{R}^n) = \mathbb{R}^n \rtimes \text{GL}(\mathbb{R}^n) \to \text{GL}(\mathbb{R}^n)$ to denote the projection on the second factor. For any $G \subseteq \text{Aff}(\mathbb{R}^n)$, we will call $r(G)$ the linear part of $G$ and $G \cap \mathbb{R}^n$ the translational part. We have that $r(G) \cong G/(G \cap \mathbb{R}^n)$.

A flat manifold will be constructed as an orbit space $E \backslash \mathbb{R}^n$, where $E \subseteq \text{Isom}(\mathbb{R}^n)$ is acting properly discontinuously, freely and cocompactly on $\mathbb{R}^n$. For completeness, let us recall the notions we’ve just mentioned.

**Definition 1.1.** Let $G$ be a group acting (continuously) on a locally compact topological space $X$.

1. We say that $G$ acts properly discontinuously on $X$ if for every compact subset $K \subseteq X$ it holds that
   $$\# \{ g \in G \mid g \cdot K \cap K \neq \emptyset \} < \infty.$$  

2. The action of $G$ on $X$ is cocompact if the orbit space $G \backslash X$ is compact.

3. The action is free if $\forall x \in X : \{ g \in G \mid g \cdot x = x \} = \{1\}$, i.e. the stabilizer of any $x \in X$ is trivial.

We are now ready to introduce the class of crystallographic groups

**Definition 1.2.** An $n$–dimensional crystallographic group, is a cocompact and discrete subgroup of $\text{Isom}(\mathbb{R}^n)$. A Bieberbach group is a torsion free crystallographic group.

**Remark.** A subgroup $\Gamma$ of $\text{Isom}(\mathbb{R}^n)$ is cocompact, if and only if the action of $\Gamma$ on $\text{Isom}(\mathbb{R}^n)$ by left translations is cocompact, i.e. the space of cosets $\Gamma \backslash \text{Isom}(\mathbb{R}^n)$ is compact.

The following proposition gives rise to an alternative description of a crystallographic (Bieberbach) group in terms of the induced action on $\mathbb{R}^n$.

**Proposition 1.3.** Let $\Gamma$ be a subgroup of $\text{Isom}(\mathbb{R}^n)$. Then we have
1. $\Gamma$ is a discrete subgroup of $\text{Isom}(\mathbb{R}^n) \Leftrightarrow$ The action of $\Gamma$ on $\mathbb{R}^n$ is properly discontinuous.

2. $\Gamma$ is cocompact in $\text{Isom}(\mathbb{R}^n) \Leftrightarrow$ The action of $\Gamma$ on $\mathbb{R}^n$ is cocompact.

3. If $\Gamma$ is a discrete subgroup of $\text{Isom}(\mathbb{R}^n)$, then $\Gamma$ is torsion free $\Leftrightarrow$ The action of $\Gamma$ on $\mathbb{R}^n$ is free.

From this proposition it follows that a $n$-dimensional crystallographic group $\Gamma$ is a subgroup of $\text{Isom}(\mathbb{R}^n)$ which acts properly discontinuously and cocompactly on $\mathbb{R}^n$. A $n$-dimensional Bieberbach group is a $n$-dimensional crystallographic group for which the action on $\mathbb{R}^n$ is also free.

In case $\Gamma$ is a $n$-dimensional Bieberbach group, the quotient space $M = \Gamma \backslash \mathbb{R}^n$ is a manifold and as $\Gamma \subseteq \text{Isom}(\mathbb{R}^n)$, the manifold locally inherits the metric structure of Euclidean space $\mathbb{R}^n$. It follows that $M$ is a compact Riemannian manifold with constant curvature 0, i.e. a compact flat manifold. Conversely, any compact flat $n$-dimensional manifold can be obtained as a quotient $\Gamma \backslash \mathbb{R}^n$, where $\Gamma$ is a $n$-dimensional Bieberbach group. Moreover, for Bieberbach groups, the natural projection $p : \mathbb{R}^n \rightarrow \Gamma \backslash \mathbb{R}^n$ is a covering with $\Gamma$ as its group of deck transformations and so the fundamental group of the flat manifold $\Gamma \backslash \mathbb{R}^n$ is exactly $\Gamma$.

Before, we proceed let us present some examples of crystallographic and Bieberbach groups.

1. Let $\Gamma_1 = \{(z, I_n) \in \text{Aff}(\mathbb{R}^n) \mid z \in \mathbb{Z}^n\}$, then $\Gamma_1 \cong \mathbb{Z}^n$ consists of pure translations, is a discrete and cocompact subgroup of $\text{Isom}(\mathbb{R}^n)$ and hence is a Bieberbach group. The corresponding manifold $\Gamma_1 \backslash \mathbb{R}^n$ is the $n$-dimensional torus.

2. Let $\Gamma_2 = \{(z, \pm I_n) \in \text{Aff}(\mathbb{R}^n) \mid z \in \mathbb{Z}^n\}$. Then $\Gamma_2$ contains $\Gamma_1$ as a subgroup of index 2, from which it easily follows that also $\Gamma_2$ is a crystallographic group. However, $\Gamma_2$ is not torsion free, so $\Gamma_2$ is not a Bieberbach group.

3. Let $\Gamma_3$ be the subgroup of $\text{Isom}(\mathbb{R}^2)$, which is generated by

$\alpha = (e_1, I_2), \quad b = (e_2, I_2) \quad \text{and} \quad \alpha = \left(\begin{array}{cc} 0 & 1 \\ 1 & 0 \end{array}\right), \left(\begin{array}{cc} -1 & 0 \\ 0 & 1 \end{array}\right),$

where $e_1 = (1,0)^T$ and $e_2 = (0,1)^T$ (we are writing elements of $\mathbb{R}^n$ as column vectors). Note that $\alpha^2 = b$. The group generated by $a$ and $b$ is isomorphic to $\mathbb{Z}^2$ and is a subgroup of index 2 in $\Gamma_3$. Using this, it is not so difficult to see that $\Gamma_3$ is a crystallographic group. Moreover, $\Gamma_3$ is torsion free and hence a Bieberbach group. We leave it to the reader to check that $\Gamma_3 \backslash \mathbb{R}^2$ is the Klein bottle.

The structure of crystallographic groups is well understood by the Bieberbach theorems ([5, 6, 35]), which we recall here.

**Theorem 1.4 (First Bieberbach Theorem).** Let $\Gamma \subseteq \text{Isom}(\mathbb{R}^n)$ be a $n$-dimensional crystallographic group, then the group of translations $T = \Gamma \cap \mathbb{R}^n$ of $\Gamma$ is a lattice in $\mathbb{R}^n$ and is of finite index in $\Gamma$.

By a lattice of $\mathbb{R}^n$ we mean a cocompact and discrete subgroup of $\mathbb{R}^n$. Lattices of $\mathbb{R}^n$ are isomorphic to $\mathbb{Z}^n$ and each minimal generating set of a lattice of $\mathbb{R}^n$ is in fact a basis of the vector space $\mathbb{R}^n$.

**Definition 1.5.** Let $\Gamma \subseteq \text{Isom}(\mathbb{R}^n)$ be a $n$-dimensional crystallographic group, then its linear part $r(\Gamma)$ is called the holonomy group of $\Gamma$.

The term holonomy is well chosen, because when $\Gamma$ is a Bieberbach group, the holonomy group of $\Gamma$ is really the holonomy group of the flat manifold $M = \Gamma \backslash \mathbb{R}^n$. This fact will not be used further in this text, but the interested reader can consult [10] or [92] for more details.
The first Bieberbach theorem states that a \( n \)-dimensional crystallographic group \( \Gamma \) fits is a short exact sequence
\[
0 \to t(\Gamma) \cong \mathbb{Z}^n \to \Gamma \to r(\Gamma) = F \to 1,
\]
where \( F \) is a finite group. Of course, being isomorphic to \( \mathbb{Z}^n \), the translation group \( t(\Gamma) \) is abelian. It is not so difficult to show that \( t(\Gamma) \) is maximal abelian in \( \Gamma \).

Theorem 1.6 (Second Bieberbach Theorem). Let \( \varphi : \Gamma \to \Gamma' \) be an isomorphism between two crystallographic groups, then \( \Gamma \) and \( \Gamma' \) are of the same dimension, say \( n \), and moreover, there exists an affine map \( \alpha \in \text{Aff}(\mathbb{R}^n) \) such that
\[
\forall \gamma \in \Gamma : \varphi(\gamma) = \alpha \circ \gamma \circ \alpha^{-1}.
\]

Note that \( \alpha \circ \gamma \circ \alpha^{-1} \) is a conjugation inside \( \text{Aff}(\mathbb{R}^n) \). This makes sense because both \( \Gamma \) and \( \Gamma' \) are subsets of \( \text{Isom}(\mathbb{R}^n) \) and so also of \( \text{Aff}(\mathbb{R}^n) \).

Geometrically, this theorem says that a compact flat manifold is, up to an affine equivalence, completely determined by its fundamental group. The last Bieberbach theorem then states that, for a fixed \( n \), there are up to affine equivalence only finitely many \( n \)-dimensional compact flat manifolds.

Theorem 1.7 (Third Bieberbach Theorem). For any positive integer \( n \), there are, up to isomorphism (or up to affine conjugation), only finitely many \( n \)-dimensional crystallographic groups.

In [94], Zassenhaus proved a converse to the first Bieberbach theorem, which results in a complete algebraic characterization of the \( n \)-dimensional crystallographic groups:

Theorem 1.8 (Algebraic characterization of crystallographic groups). Let \( \Gamma \) be a \( n \)-dimensional crystallographic group, then \( \Gamma \) fits in a short exact sequence
\[
0 \to \mathbb{Z}^n \overset{j}{\to} \Gamma \to F \to 1,
\]
where \( F \) is finite and \( i(\mathbb{Z}^n) \) is maximal abelian in \( \Gamma \). Conversely, if \( \Gamma \) is an abstract group fitting in a short exact sequence as above, where \( F \) is finite and \( i(\mathbb{Z}^n) \) is maximal abelian in \( \Gamma \), then there exists an embedding \( j : \Gamma \to \text{Isom}(\mathbb{R}^n) \) such that \( j(\Gamma) \) is a \( n \)-dimensional crystallographic group.

A little bit more can be said: when \( \Gamma \) is a crystallographic group, then \( t(\Gamma) \) is the unique normal abelian subgroup of \( \Gamma \) which is also maximal abelian. Hence, as \( t(\Gamma) \) is completely determined by algebraic properties, \( t(\Gamma) \) is a characteristic subgroup of \( \Gamma \).

By choosing a free generating set of the free abelian group \( t(\Gamma) \cong \mathbb{Z}^n \), the short exact sequence \( 0 \to \mathbb{Z}^n \to \Gamma \to F \to 1 \) (where \( F = r(\Gamma) \)) induces a representation \( \varphi : F \to \text{Aut}(\mathbb{Z}^n) \) by conjugation in \( \Gamma \). This representation is often referred to as the holonomy representation of \( \Gamma \). As \( \text{Aut}(\mathbb{Z}^n) \subseteq \text{GL}(\mathbb{Q}^n) \subseteq \text{GL}(\mathbb{R}^n) \) we can also via \( \varphi \) as a representation into \( \text{GL}(\mathbb{Q}^n) \) (we then talk about the rational holonomy representation) or into \( \text{GL}(\mathbb{R}^n) \) (the real holonomy representation). Note that also \( r : \Gamma \to O(n) \subseteq \text{GL}(\mathbb{R}^n) \) induces a representation \( r : \Gamma/t(\Gamma) = F \to \text{GL}(\mathbb{R}^n) \). One can see that \( \bar{r} \) and \( \varphi \) are conjugate inside \( \text{GL}(\mathbb{R}^n) \).

As a flat manifold \( M \) is, up to affine equivalence, completely determined by its fundamental group, a Bieberbach group \( \Gamma(\Gamma) \), it should not come as a surprise that much of the geometry (or topology) of the manifold \( M \) can be studied on the algebraic level. Very often, the holonomy representation plays a crucial role. We refer the reader to the book [52] to see quite some examples of this. In later sections of this article we will see that this is also the case for infra-nilmanifolds.

2 Nilpotent Groups

When moving from the class of flat manifolds (crystallographic groups) to the class of infra-nilmanifolds (almost crystallographic groups), we will replace the abelian groups \( \mathbb{Z}^n \) and \( \mathbb{R}^n \) by
their nilpotent analogues. It is therefore useful to spend some time describing these nilpotent groups, as in the previous section, this material is standard and we omit all proofs. For discrete nilpotent groups we refer the reader to [45, 56, 57, 84] for more details, while for Lie group aspects the references [79, 81, 80] are a good starting point for more information. The book [84] contains a complete description, with full proofs of everything we will say about rational Mal’cev completions.

Let $G$ be any group, then we define the terms of the upper central series $Z_i(G) \subseteq G$ ($i \geq 0$) and those of the lower central series $\gamma_i(G) \subseteq G$ ($i \geq 1$) inductively as follows:

\[
Z_0(G) = 1, \quad Z_{i+1}(G) \text{ is determined by } Z_{i+1}(G)/Z_i(G) = Z(G/Z_i(G)),
\]

\[
\gamma_1(G) = G, \quad \gamma_{i+1}(G) = [G, \gamma_i(G)].
\]

Note that a group is abelian $\Leftrightarrow Z_1(G) = G$ $\Leftrightarrow \gamma_2(G) = 1$. As a generalization of abelian groups, we can consider groups for which the upper central series eventually stabilizes at $G$ or where the lower central series eventually stabilizes at the trivial group. The following lemma shows that both points of view lead to the same class of groups.

**Lemma 2.1.** Let $G$ be a group, then for any positive integer $c$ we have that

\[
Z_c(G) = G \Leftrightarrow \gamma_{c+1}(G) = 1.
\]

**Definition 2.2.** A group $G$ is nilpotent of class $\leq c$ if and only if $Z_c(G) = G$ (if and only if $\gamma_{c+1}(G) = 1$). We say that $G$ is nilpotent of class $c$ if $c$ is the smallest positive integer for which $Z_c(G) = G$ ($\gamma_{c+1}(G) = 1$).

It follows that the abelian groups are exactly the nilpotent groups of class 1.

**Example 2.1.** Let

\[
H = \left\{ \begin{pmatrix} 1 & y & z \\ 0 & 1 & x \\ 0 & 0 & 1 \end{pmatrix} \mid x, y, z \in \mathbb{Z} \right\}
\]

be the group of upper triangular $3 \times 3$ integral matrices. Then, $H$ is a nilpotent group of class 2. The group $H$ is often referred to as the (integral) Heisenberg group. More generally, for any commutative ring $R$ with 1, the group of upper triangular $n \times n$ matrices with entries in $R$ and 1’s everywhere on the diagonal, say $UT_n(R)$, is a nilpotent group of class $\leq n - 1$. (E.g. see [84, page 8])

It is easy to prove that subgroups and quotient groups of nilpotent groups are also nilpotent (of at most the same class as the original group).

In the setting of crystallographic groups, the abelian groups $\mathbb{Z}^n$ play a crucial role, since any crystallographic group contains such a group as a characteristic subgroup of finite index. The groups $\mathbb{Z}^n$ are exactly the finitely generated and torsion free abelian groups. In the generalized setting of almost–crystallographic groups, the role of those $\mathbb{Z}^n$ will be replaced by the finitely generated and torsion free nilpotent groups.

So, since our aim is to discuss infra-nilmanifolds and almost–crystallographic groups in detail, it is necessary to obtain a good understanding of those finitely generated torsion free nilpotent groups.

**Lemma 2.3.** Let $N$ be a nilpotent group, then

1. If $N$ is finitely generated, then any subgroup of $N$ is finitely generated (since $N$ is a polycyclic group).

2. If $N$ is torsion free, then for any positive integer $i$ also $N/Z_i(N)$ is torsion free.
Note that for a torsion free nilpotent group \( N \), it is not necessarily true that \( N/\gamma_i(N) \) is torsion free. E.g. for any positive integer \( n \) we define
\[
H_n = \left\{ \begin{pmatrix} 1 & y & \frac{z}{n} \\ 0 & 1 & x \\ 0 & 0 & 1 \end{pmatrix} \mid x, y, z \in \mathbb{Z} \right\}.
\]
Then \( H_n \) is a torsion free nilpotent group (where \( H_1 \) is the Heisenberg group \( H \) which we already met in the example above). One can compute that
\[
Z(H_n) = \left\{ \begin{pmatrix} 1 & 0 & \frac{z}{n} \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \mid z \in \mathbb{Z} \right\} \text{ and } \gamma_2(H_n) = \left\{ \begin{pmatrix} 1 & 0 & z \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \mid z \in \mathbb{Z} \right\},
\]
from which it is follows that
\[
H_n/Z(H_n) \cong \mathbb{Z}^2 \text{ is indeed torsion free, while } H_n/\gamma_2(H_n) = \mathbb{Z}^2 \oplus \mathbb{Z} \text{ is not, when } n \neq 1.
\]
It follows from the lemma above that for a given finitely generated torsion free nilpotent group \( N \) of class \( \leq c \), we have that
\[
N = Z_c(N) \supseteq Z_{c-1}(N) \supseteq \cdots \supseteq Z_2(N) \supseteq Z_1(N) \supseteq 1 = Z_0(N)
\]
is a filtration of \( N \) with \( Z_i(N)/Z_{i-1}(N) \cong \mathbb{Z}^{k_i} \) for some integers \( k_i \). By refining this filtration (and numbering in the other direction), we can find a series of normal subgroups \( N_i \) of \( N \):
\[
N = N_1 \supset N_2 \supset N_3 \cdots \supset N_k \supset \cdots \supset N_{k+1} = 1
\]
with \( N_i/N_{i+1} \cong \mathbb{Z} \) and \( N_i/N_{i+1} \subseteq Z(N/N_{i+1}) \) (which is equivalent to \( [N,N_i] \subseteq N_{i+1} \)). Now, given a series of subgroups \( N_i \) of \( N \) satisfying these conditions, we fix an element \( a_i \in N_i \) for all \( i \), in such a way that the natural projection of \( a_i \) in \( N_i/N_{i+1} \) is a generator of the infinite cyclic group \( N_i/N_{i+1} \). It is then obvious to see that any element \( x \in N \) can be uniquely expressed as an element of the form
\[
x = a_1^{z_1}a_2^{z_2} \cdots a_k^{z_k} \text{ for some } z_1, z_2, \ldots, z_k \in \mathbb{Z}.
\]
We will refer to \( a_1, a_2, \ldots, a_k \) as a Mal’cev basis for \( N \).

**Proposition 2.4.** Let \( N \) be a finitely generated torsion free nilpotent group with Mal’cev basis \( a_1, a_2, \ldots, a_k \), then there exist polynomials \( p_i(x_1, x_2, \ldots, x_{i-1}, y_1, y_2, \ldots, y_{i-1}) \) \((2 \leq i \leq k)\) with coefficients in \( \mathbb{Q} \) and polynomials \( q_i(x_1, x_2, \ldots, x_{i-1}, z) \) \((2 \leq i \leq k)\) also with coefficients in \( \mathbb{Q} \) such that for all \( x_1, x_2, \ldots, x_k, y_1, \ldots, y_k, z \in \mathbb{Z} \) we have that
1. \( a_1^{x_1}a_2^{x_2} \cdots a_k^{x_k}a_1^{y_1}a_2^{y_2} \cdots a_k^{y_k} = a_1^{x_1+y_1}a_2^{x_2+y_2+p_1(x_1, x_2, \ldots, x_{i-1}, y_1, y_2, \ldots, y_{i-1})} \cdots a_k^{x_k+y_k+p_k(x_1, \ldots, y_{i-1})} \).
2. \((a_1^{x_1}a_2^{x_2} \cdots a_k^{x_k})^z = a_1^{zx_1}a_2^{zx_2+q_1(x_1, z)} \cdots a_k^{zx_k+q_k(x_1, \ldots, x_{i-1}, z)} \).

Using these polynomials, we can now construct two new groups, \( N^\mathbb{Q} \) and \( N^\mathbb{R} \). These groups consist formally of the elements \( a_1^{n_1}a_2^{n_2} \cdots a_k^{n_k} \) where the \( x_i \in \mathbb{Q} \) (respectively \( \mathbb{R} \)) and where the product rule is given by means of the same polynomials \( p_i \). Both \( N^\mathbb{Q} \) and \( N^\mathbb{R} \) are torsion free nilpotent groups (but of course, they are no longer finitely generated).

The group \( N^\mathbb{Q} \) is a radicable group, this is a group such that any element of \( N^\mathbb{Q} \) has a (unique) \( m \)-th root in \( \mathbb{Q} \) (for all positive integers \( m \)). Moreover, \( N^\mathbb{Q} \) is the radicable closure of \( N \), i.e. it is a radicable group containing \( N \) and any element of \( N^\mathbb{Q} \) has a positive power lying in \( N \). This implies that \( N^\mathbb{Q} \) is the smallest radicable group containing \( N \). This property does determine \( N^\mathbb{Q} \) uniquely up to isomorphism. Often \( N^\mathbb{Q} \) is referred to as the rational Mal’cev completion of \( N \).
Example 2.2. It is easy to see that when $N \cong \mathbb{Z}^k$, then $N^\mathbb{Q} \cong \mathbb{Q}^k$. For the integral Heisenberg group we have that

$$H^\mathbb{Q} = \left\{ \begin{pmatrix} 1 & y & z \\ 0 & 1 & x \\ 0 & 0 & 1 \end{pmatrix} \mid x, y, z \in \mathbb{Q} \right\}$$

In fact, for every $H_n$, we have that $H^\mathbb{Q}_n \cong H_n$.

Proposition 2.5. Let $\varphi : N_1 \to N_2$ be a homomorphism between two finitely generated torsion free nilpotent groups. Then $\varphi$ uniquely extends to a homomorphism $\varphi^\mathbb{Q} : N^\mathbb{Q}_1 \to N^\mathbb{Q}_2$. Moreover, when $\varphi$ is an isomorphism, so is $\varphi^\mathbb{Q}$.

The proof of the proposition is not difficult, since it is easy to see that the homomorphism $\varphi$ is expressed as a polynomial map in terms of coordinates with respect to chosen Mal’cev bases of $N_1$ and $N_2$. Using the same polynomial map, one then defines the homomorphism between $N^\mathbb{Q}_1$ and $N^\mathbb{Q}_2$ (but now allowing also rational coordinates).

In the example 2.2 above we saw that it is possible that $N_1 \not\cong N_2$, but $N^\mathbb{Q}_1 \cong N^\mathbb{Q}_2$. This occurs exactly when the groups $N_1$ and $N_2$ are commensurable.

Definition 2.6. Two groups $N_1$ and $N_2$ are said to be (abstractly) commensurable if there exists finite index subgroups $H_1 \leq N_1$ and $H_2 \leq N_2$ such that $H_1 \cong H_2$.

Proposition 2.7. Let $N_1$ and $N_2$ be two finitely generated torsion free nilpotent groups, then

$$N^\mathbb{Q}_1 \cong N^\mathbb{Q}_2 \iff N_1 \text{ and } N_2 \text{ are commensurable.}$$

The group $N^\mathbb{R}$ is called the real Mal’cev completion of $N$. This is a Lie group. Indeed as a manifold $N^\mathbb{R}$ is diffeomorphic to $\mathbb{R}^k$ and the group operations are polynomial in the coordinates, so these are certainly smooth. The group $N^\mathbb{R}$ is a simply connected nilpotent Lie group which contains $N$ as a discrete cocompact subgroup. Generalizing the abelian case, we formulate the following definition.

Definition 2.8. A lattice of a simply connected Lie group $G$ is a discrete and cocompact subgroup $N$ of $G$.

It is known that, up to a Lie group isomorphism, $N^\mathbb{R}$ is the unique connected and simply connected nilpotent Lie group containing $N$ as a lattice. At this point we want to remark that there exist nilpotent groups with different rational Mal’cev completions, but with the same real Mal’cev completion.

Analogously to the situation for rational Mal’cev completions, we have the following result:

Proposition 2.9. Let $\varphi : N_1 \to N_2$ be a homomorphism between two finitely generated torsion free nilpotent groups. Then $\varphi$ uniquely extends to a continuous homomorphism $\varphi^\mathbb{R} : N^\mathbb{R}_1 \to N^\mathbb{R}_2$. Moreover, when $\varphi$ is an isomorphism, so is $\varphi^\mathbb{R}$.

To study radicable nilpotent groups, like $N^\mathbb{Q}$, or nilpotent Lie groups, like $N^\mathbb{R}$, it is often useful to move over to their associated Lie algebras. The rest of this section is devoted to the description of this connection in our situation. To explain this, it is easy to make use of the following result:

Theorem 2.10. Let $N$ be a finitely generated torsion free nilpotent group. Then there exists an embedding $\varphi : N \to UT_n(\mathbb{Z})$, for some $n$. So any finitely generated torsion free nilpotent group can be realized as a subgroup of some $UT_n(\mathbb{Z})$ and any subgroup of $UT_n(\mathbb{Z})$ is a finitely generated torsion free nilpotent group.

From now onwards, we will assume that

$$N \subseteq UT_n(\mathbb{Z}) \subseteq UT_n(\mathbb{Q}) \subseteq UT_n(\mathbb{R}).$$
Let us now use $NT_n(R)$ to denote the set of $n \times n$ upper triangular matrices with entries in the ring $R$ and with a 0 everywhere on the diagonal. So all elements of $NT_n(R)$ are nilpotent matrices. By considering the usual Lie bracket $[A, B] = AB - BA$ for matrices, one easily sees that $NT_n(Q)$ (resp. $NT_n(R)$) is a Lie algebra over $Q$ (resp. over $R$).

We introduce two maps:

$$\exp : NT_n(R^n) \rightarrow UT_n(R^n) : A \mapsto \sum_{k=0}^{\infty} \frac{1}{k!} A^k$$

and

$$\log : UT_n(R^n) \rightarrow NT_n(R^n) : A \mapsto \sum_{k=1}^{\infty} \frac{(-1)^{k+1}}{k}(A - I_n)^k$$

where $I_n$ is the $n \times n$ identity matrix.

Note that in the definitions above, we have that the matrices $A$ and $A - I_n$ appearing in the expression for exp and log respectively, are nilpotent matrices and so the infinite sums are actually finite sums. The maps exp and log are each others inverse and so are both bijective.

The Campbell–Baker–Hausdorff formula provides a relation between the multiplication in the group $UT_n(R)$ and the Lie bracket in the Lie algebra $NT_n(R)$. This formula says that

$$\forall X, Y \in NT_n(R) : \exp(X) \exp(Y) = \exp(X + Y + \frac{1}{2}[X, Y] + \frac{1}{12}([X, [X, Y]] + [Y, [Y, X]]) + \sum_{k=4}^{\infty} r_k)$$

where each $r_k$ is a rational combination of $k$–fold Lie brackets in $X$ and $Y$. Again the sum is in fact a finite sum, since $k$-fold brackets are 0 when $k$ is big enough.

**Theorem 2.11.** Let $N \subseteq UT_n(\mathbb{Z})$ and take

$$n^Q = Q \log(N) \text{ (the } Q\text{-vector space generated by } \log(N)) \text{ and}$$

$$n^R = R \log(N) \text{ (the } R\text{-vector space generated by } \log(N)).$$

Then

1. $n^Q$ is a rational Lie algebra and $N^Q = \exp(n^Q)$.
2. $n^R$ is a real Lie algebra and $N^R = \exp(n^R)$.

We remark here that the isomorphism type of the Lie algebras $n^Q$ and $n^R$ are independent of the chosen embedding of $N$ into $UT_n(\mathbb{Z})$ (even into some $UT_n(Q)$ and this also for various $n$) and so is really an invariant of the group $N$.

This correspondence behaves nicely on the level of (iso)morphisms:

**Theorem 2.12.** Let $N_1$ and $N_2$ be two finitely generated torsion free nilpotent groups and let $\mathbb{F} = Q$ or $R$. Then, for any group homomorphism $\varphi : N_1^\mathbb{F} \rightarrow N_2^\mathbb{F}$ (continuous in the case $\mathbb{F} = R$) there exists a unique Lie algebra homomorphism $\varphi_* : n_1^\mathbb{F} \rightarrow n_2^\mathbb{F}$ making the following diagram commutative:

\[
\begin{array}{ccc}
N_1^\mathbb{F} & \xrightarrow{\varphi} & N_2^\mathbb{F} \\
\exp \downarrow \quad \downarrow \exp & & \downarrow \exp \\
\log \quad \downarrow \quad \downarrow \log & & \log \\
N_1^\mathbb{F} & \xrightarrow{\varphi_*} & N_2^\mathbb{F}
\end{array}
\]

Conversely, given a Lie algebra homomorphism $\varphi_* : n_1^\mathbb{F} \rightarrow n_2^\mathbb{F}$, there is a unique (continuous) homomorphism $\varphi : N_1^\mathbb{F} \rightarrow N_2^\mathbb{F}$ making the diagram commutative.

Under this correspondence, we have that $\varphi$ is bijective (resp. injective, surjective) if and only if $\varphi_*$ is.
So as a corollary we find that

**Corollary 2.13.** Let $N$ be a finitely generated torsion free nilpotent group, then

$$\text{Aut}(N^Q) = \text{Aut}(n^Q) \text{ and } \text{Aut}(N^R) = \text{Aut}(n^R).$$

Before we continue let us illustrate all of this by means of a rather elaborate example. Let us consider the Heisenberg group $H$ again and let

$$a = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix}, \quad b = \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \text{ and } c = \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}.$$  

Then $a$, $b$, $c$ form a Mal’cev basis of $H$ and one computes that

$$a^x b^y c^z = \begin{pmatrix} 1 & y & z \\ 0 & 1 & x \\ 0 & 0 & 1 \end{pmatrix}.$$  

The group $H$ has a presentation of the form

$$H = \langle a, b, c | [b, a] = c, [c, a] = [c, b] = 1 \rangle,$$

where we define the commutator as $[x, y] = x^{-1}y^{-1}xy$.

It is easy to check that $\forall x_1, x_2, y_1, y_2, z_1, z_2 \in \mathbb{Z}$:

$$a^{x_1}b^{y_1}c^{z_1}a^{x_2}b^{y_2}c^{z_2} = a^{x_1+x_2}b^{y_1+y_2}c^{z_1+z_2+z_2y_1},$$

and $\forall x, y, z, m \in \mathbb{Z}$:

$$(a^x b^y c^z)^m = a^{mx}b^{my}c^{mz} + \frac{m(m-1)}{2} xy,$$

which illustrates Proposition 2.4.

Now we compute the rational Lie algebra associated to $H$ (the case for the real Lie algebra is completely analogous). We have that

$$\log(a^x b^y c^z) = \log \begin{pmatrix} 1 & y & z \\ 0 & 1 & x \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 0 & y & z - \frac{xy}{2} \\ 0 & 0 & x \\ 0 & 0 & 0 \end{pmatrix}.$$  

It follows that

$$h^Q = Q \log(H) = \left\{ \begin{pmatrix} 0 & y & z - \frac{xy}{2} \\ 0 & 0 & x \\ 0 & 0 & 0 \end{pmatrix} | x, y, z \in \mathbb{Q} \right\} = \left\{ \begin{pmatrix} 0 & y & z \\ 0 & 0 & x \\ 0 & 0 & 0 \end{pmatrix} | x, y, z \in \mathbb{Q} \right\} = NT_3(\mathbb{Q}).$$

From this, it follows that $H^Q = \exp(h^Q) = UT_3(\mathbb{Q})$ as claimed already in Example 2.2.

Now, consider

$$\varphi : H^Q \to H^Q : \begin{pmatrix} 1 & y & z \\ 0 & 1 & x \\ 0 & 0 & 1 \end{pmatrix} \mapsto \begin{pmatrix} 1 & x - y & z + x - xy + \frac{y(y-1)}{2} \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{pmatrix}.$$  

One can check that $\varphi \in \text{Aut}(H^Q)$ (in fact $\varphi(H) = H$, so $\varphi$ can also be seen as an automorphism of $H$). Let us now compute the Lie algebra homomorphism $\varphi^* : h^Q \to h^Q$ from Theorem 2.12.
holds that $\forall X \in h^Q$ we have that $\varphi_*(X) = \log(\varphi(\exp(X)))$, so

$$
\varphi_* \left( \begin{array}{ccc}
0 & y & z \\
0 & 0 & x \\
0 & 0 & 0 \\
\end{array} \right) = \log \left( \varphi \left( \begin{array}{ccc}
1 & y & z + \frac{x}{2} \\
0 & 0 & 1 \\
0 & 0 & 1 \\
\end{array} \right) \right) \\
= \log \left( \begin{array}{ccc}
1 & x - y & z + x - \frac{y}{2} + \frac{\mu(y-1)}{2} \\
0 & 0 & 1 \\
0 & 0 & 1 \\
\end{array} \right) \\
= \left( \begin{array}{ccc}
0 & x - y & z + x - \frac{y}{2} \\
0 & 0 & 0 \\
0 & 0 & 0 \\
\end{array} \right).
$$

From the above, it is obvious that $\varphi_*$ is a linear endomorphism of $h^Q$. A small calculation also shows that $\varphi_*$ is in fact a Lie algebra automorphism. Another computation will show that $\varphi_3$ is the identity map on $h^Q$. From this it follows that also $\varphi_3$ is the identity map of $H^Q$.

In the sequel, it will be useful to work with another representation of $H$ (and $H^Q$) as a group of unipotent matrices: one easily computes that the map

$$
\psi = UT_3(Q) \to UT_4(Q) : \left( \begin{array}{ccc}
1 & y & z \\
0 & 1 & x \\
0 & 0 & 1 \\
\end{array} \right) \mapsto \left( \begin{array}{ccc}
1 & \frac{y}{2} - \frac{x}{2} & z - \frac{x}{2} \\
0 & 0 & 1 \\
0 & 0 & 0 \\
\end{array} \right)
$$

is an injective homomorphism of groups.

Let

$$
N = \left\{ \left( \begin{array}{ccc}
1 & \frac{y}{2} - \frac{x}{2} & z - \frac{x}{2} \\
0 & 0 & 1 \\
0 & 0 & 0 \\
\end{array} \right) \mid x, y, z \in \mathbb{Z} \right\}.
$$

Then $H \cong N$ (via $\psi$ above). As

$$
\log \left( \begin{array}{ccc}
1 & \frac{y}{2} - \frac{x}{2} & z - \frac{x}{2} \\
0 & 0 & 1 \\
0 & 0 & 0 \\
\end{array} \right) = \left( \begin{array}{ccc}
0 & \frac{y}{2} - \frac{x}{2} & z - \frac{x}{2} \\
0 & 0 & 1 \\
0 & 0 & 0 \\
\end{array} \right),
$$

we find that

$$
n^Q = \left\{ \left( \begin{array}{ccc}
0 & \frac{y}{2} - \frac{x}{2} & z - \frac{x}{2} \\
0 & 0 & 1 \\
0 & 0 & 0 \\
\end{array} \right) \mid x, y, z \in \mathbb{Q} \right\} = \left\{ \left( \begin{array}{ccc}
0 & \frac{y}{2} - \frac{x}{2} & z \\
0 & 0 & 1 \\
0 & 0 & 0 \\
\end{array} \right) \mid x, y, z \in \mathbb{Q} \right\}.
$$

It follows that

$$
N^Q = \left\{ \exp \left( \begin{array}{ccc}
0 & \frac{y}{2} - \frac{x}{2} & z \\
0 & 0 & 1 \\
0 & 0 & 0 \\
\end{array} \right) \mid x, y, z \in \mathbb{Q} \right\} = \left\{ \left( \begin{array}{ccc}
1 & \frac{y}{2} - \frac{x}{2} & z \\
0 & 0 & 1 \\
0 & 0 & 0 \\
\end{array} \right) \mid x, y, z \in \mathbb{Q} \right\},
$$

so we have that $\psi(UT_3(Q)) = \psi(H^Q) = N^Q$.

Note that

$$
\psi_* : NT_3(Q) \to NT_4(Q) : \left( \begin{array}{ccc}
0 & y & z \\
0 & 0 & x \\
0 & 0 & 0 \\
\end{array} \right) \mapsto \left( \begin{array}{ccc}
0 & \frac{y}{2} & z \\
0 & 0 & 0 \\
0 & 0 & 0 \\
\end{array} \right)
$$

10
is an injective homomorphism of Lie algebras. In fact $\psi_*$ is really the homomorphism making the diagram

$$
\begin{array}{ccc}
H^\mathbb{Q} & \xrightarrow{\psi} & N^\mathbb{Q} \\
\exp & \xrightarrow{\log} & \exp \\
\psi^* & \xrightarrow{} & \psi^* \\
\h^\mathbb{Q} & \xrightarrow{\psi_\ast} & \n^\mathbb{Q}
\end{array}
$$

commutative as in Theorem 2.12. Note that this observation illustrates that the Lie algebra associated to a torsion free nilpotent group is independent of the way this group is represented as a subgroup of some $UT_n(\mathbb{Q})$.

We will now indicate a little bit why this second representation of the Heisenberg group as a group of $4 \times 4$ matrices has some advantage. To see this, we consider

$$\begin{pmatrix}
1 & 1 & 1 & 0 \\
0 & 0 & 1 & 0 \\
0 & 1 & -1 & 0 \\
0 & 0 & 0 & 1
\end{pmatrix}$$

Some computations show that

$$A^3 = I_4 \quad \text{and} \quad A = \begin{pmatrix} 1 & \frac{y}{2} & -\frac{z}{2} & \frac{-y}{2} \\ 0 & 1 & 0 & x \\ 0 & 0 & 1 & y \\ 0 & 0 & 0 & 1 \end{pmatrix},$$

from which we can conclude that conjugation with $A$ induces an automorphism of $N^\mathbb{Q}$ of order 3, let us call this automorphism $\phi_A$. To see what the corresponding automorphism on $n^\mathbb{Q}$ looks like, let us first of all remark that

$$\phi_{A^*}(X) = \log(\phi_A(\exp(X))) = \log(\exp(A X A^{-1})) = \log(\exp(A^T A^{-1})) = A X A^{-1}$$

from which we obtain that also $\phi_{A^*}$ is given by conjugation with $A$. Hence we find:

$$\phi_{A^*} = \begin{pmatrix} 0 & \frac{y}{2} & -\frac{z}{2} & \frac{z}{2} \\ 0 & 0 & 0 & x \\ 0 & 0 & 0 & y \\ 0 & 0 & 0 & 0 \end{pmatrix}, \quad A^{-1} = \begin{pmatrix} 1 & \frac{y}{2} & \frac{z}{2} & \frac{-y}{2} \\ 0 & 1 & 0 & -y \\ 0 & 0 & 1 & x - y \\ 0 & 0 & 0 & 1 \end{pmatrix} \in N^\mathbb{Q},$$

It follows that there is a commutative diagram of the form

$$
\begin{array}{ccc}
H^\mathbb{Q} & \xrightarrow{\psi_\ast} & H^\mathbb{Q} \\
\psi_\ast & \Downarrow & \psi_\ast \\
n^\mathbb{Q} & \xrightarrow{\phi_A} & n^\mathbb{Q}
\end{array}
$$

so this means that under the identification of $H^\mathbb{Q}$ with $N^\mathbb{Q}$ via $\psi$, we have that $\phi$ corresponds to the automorphism $\phi_A$. The advantage of viewing the rational Heisenberg group as being the group $N^\mathbb{Q}$ is that any automorphism of $N^\mathbb{Q}$ can be described by means of a conjugation by a matrix (of a nice form). We will come back to this fact later in section 6.

## 3 Infra-nilmanifolds and almost–crystallographic groups

We are now ready to introduce the main concepts of this text, namely the almost–crystallographic groups and the infra-nilmanifolds. In the setting of the usual crystallographic groups, the basic
Then we can consider the semidirect product $G \rtimes \text{Aut}(G)$, where the group operation is given by

$$\forall g, h \in G, \forall \alpha, \beta \in \text{Aut}(G) : (g, \alpha)(h, \beta) = (g\alpha(h), \alpha\beta).$$

We will refer to this group as the affine group of $G$ and we denote it by $\text{Aff}(G)$. This affine group acts on $G$ in the following way:

$$\forall (g, \alpha) \in \text{Aff}(G), \forall x \in G : (g, \alpha) \cdot x = g\alpha(x).$$

Note that, when $G = R^n$, all of this agrees with what we earlier introduced for $\text{Aff}(R^n)$. When, introducing the crystallographic groups, we regarded $R^n$ as being a Euclidean space and then we obtained the group of isometries $\text{Isom}(R^n) = R^n \rtimes O(n)$ as a subgroup of $\text{Aff}(R^n)$. For general $G$, it is perhaps not so obvious at first what should be the analogue of the Euclidean structure and the corresponding isometry group. To see this, let us focus on the group $\text{Isom}(R^n)$, which is an almost– Bieberbach group. The dimension of an almost–crystallographic group modeled on $G$ is the dimension of $G$. This group $O(n)$ is a maximal compact subgroup of $\text{Aut}(R^n)$ and is in this sense uniquely determined up to inner conjugation inside $\text{Aut}(R^n)$.

Therefore, when moving on to the setting of almost–crystallographic groups, we fill fix a maximal compact subgroup $C \subseteq \text{Aut}(G)$. Again, this $C$ is determined up to conjugation inside $\text{Aut}(G)$. Although we will not need this in the rest of the text, we remark here that the group $G \rtimes C$ can also be interpreted as a group of isometries of $G$ in the following way: We have seen that the group of automorphisms of $G$ is isomorphic to the group of automorphisms of its Lie algebra $g$. So we can consider $C$ as being a maximal compact subgroup of $\text{Aut}(g)$ and then there exists a positive definite inner product on $g$ which is invariant under the action of $G$ (see [88]). The Lie algebra of $G$ can be interpreted as being the tangent space of $G$ at the identity element.

At the end of this section, we give an explicit example of an almost–crystallographic group (which is not torsion free) and of an almost–Bieberbach group. The interested reader can already look at these examples now and then read the rest of this section.

**Definition 3.1.** An almost–crystallographic group (modeled on $G$), is a cocompact and discrete subgroup of $G \rtimes C$, where $G$ and $C$ are as introduced above.

The dimension of an almost–crystallographic group modeled on $G$ is the dimension of $G$.

An almost–Bieberbach group is a torsion free almost–crystallographic group.

**Proposition 3.2.** Let $\Gamma$ be an almost–crystallographic group modeled on $G$. Then

1. $\Gamma$ (as a subgroup of $\text{Aff}(G)$) acts properly discontinuously and cocompactly on $G$.

2. The action of $\Gamma$ on $G$ is free $\iff$ $\Gamma$ is an almost–Bieberbach group.

**Definition 3.3.** An infra–nilmanifold is a quotient space $\Gamma \backslash G$, where $\Gamma$ is an almost–Bieberbach group modeled on $G$. If moreover, $\Gamma$ is completely contained inside $G$ (so none of the elements in $\Gamma$ have a non-trivial $C$-component), then $\Gamma \backslash G$ is called a nilmanifold.

So, the class of infra–nilmanifolds is a generalization of the class of flat manifolds and a nilmanifold is in this sense a generalization of a torus.

All three Bieberbach theorems have been generalized to the class of infra-nilmanifolds. The first one has a straightforward generalization and was proved already in 1960 by L. Auslander ([2]):

**Theorem 3.4 (Generalized First Bieberbach Theorem).** Let $\Gamma \subseteq G \rtimes C$ be an almost–crystallographic group modeled on $G$, then $N = \Gamma \cap G$ is a lattice of $G$ and $\Gamma/N$ is finite.
We will refer to the group \( N = \Gamma \cap G \) as the the group of pure translations of \( \Gamma \).

Consider the natural homomorphism \( p : \text{Aff}(G) = G \times \text{Aut}(G) \to \text{Aut}(G) \). Let \( \Gamma \subseteq G \times G \) be an almost-crystallographic group. Then the first generalized first Bieberbach says that the kernel of the restriction of \( p \) to \( \Gamma \), namely \( G \cap \Gamma \) is a lattice in \( G \) and the image \( p(\Gamma) \) is a finite group. We will call this finite group \( F = p(\Gamma) \) the holonomy group of \( \Gamma \).

A useful fact when working with with almost-crystallographic groups is the fact that the group of pure translations of an almost-crystallographic group \( \Gamma \) is maximal nilpotent in \( \Gamma \). Since I was unable to locate a complete proof of this fact in the literature, I will present a proof here.

For this we will also need the following group theoretical lemma

**Lemma 3.5.** Let \( C_n = \langle t \rangle \) be a cyclic group of finite order \( n \) and let \( E \) be an extension

\[
1 \to \mathbb{Z}^k \to E \to C_n \to 1.
\]

Then the following are equivalent

1. \( E \) is a nilpotent group.
2. \( E \) is an abelian group.
3. The action of \( C_n \) on \( \mathbb{Z}^k \) induced by conjugation in \( E \) is the trivial action.

**Proof.** The implications \((3) \Rightarrow (2) \) and \((2) \Rightarrow (1) \) are obvious, so we just have to prove the implication \((1) \Rightarrow (3) \). The action of the generator \( t \) of \( C_n \) on \( \mathbb{Z}^k \) is given by a \( k \times k \) integral matrix \( A \). We will show by induction on \( k \) that \( A \) has to be a unipotent matrix. The case \( k = 0 \) is trivially true. As \( E \) is nilpotent, \( Z(E) \cap \mathbb{Z}^k \) is non trivial, since in any nilpotent group it holds that the intersection of a non-trivial normal subgroup with the center is non-trivial. Let \( Z = Z(E) \cap \mathbb{Z}^k \). It is not so difficult to see that \( \mathbb{Z}^k / Z \) is torsion free, hence \( \mathbb{Z}^k / Z \cong \mathbb{Z}^l \) with \( l < k \). Also the group \( E / Z \) is nilpotent and fits in an extension \( 1 \to \mathbb{Z}^l \to E / Z \to C_n \to 1 \). By induction, we find that the action on \( \mathbb{Z}^l \) is nilpotent. Now, we have an extension of \( C_n \)-modules \( 0 \to Z \to \mathbb{Z}^k \to \mathbb{Z}^l \to 0 \), where \( C_n \) acts trivially on \( Z \) and unipotently on \( \mathbb{Z}^l \). It follows that \( C_n \) acts unipotently on \( \mathbb{Z}^k \), hence \( A \) is a unipotent matrix. But as \( t \) is of order \( n \), we must have that \( A \) is also of finite order. The only unipotent matrix of finite order is the identity matrix, so \( C_n \) acts trivially on \( \mathbb{Z}^k \). \( \square \)

**Proposition 3.6.** Let \( \Gamma \) be an almost-crystallographic group modeled on \( G \). Then, the group of pure translations \( N = \Gamma \cap G \) is maximal nilpotent in \( \Gamma \).

**Proof.** Let us start with a remark: if \( g \) is a nilpotent Lie algebra and \( \alpha \in \text{Aut}(g) \) is such that \( \alpha \) induces the identity automorphism on \( g/\gamma_2(g) \), then by induction on \( i \) one gets that \( \alpha \) will also induce the identity automorphism on all quotients \( \gamma_i(g)/\gamma_{i+1}(g) \) and hence \( \alpha \) is a unipotent automorphism of \( g \). If moreover \( \alpha \) is of finite order, this will imply that \( \alpha \) is the trivial automorphism of \( g \). From this it also follows that for a given simply connected nilpotent Lie group \( G \) and an automorphism of finite order \( \alpha \in \text{Aut}(G) \) inducing the identity on \( G/\gamma_2(G) \), we have that \( \alpha \) is itself the identity.

Now, consider \( x \in \Gamma \), such that \( \langle N, x \rangle \) is nilpotent. Such an element \( x \) is of the form \( x = (g, \alpha) \in G \times C \), where \( \alpha \) is of finite order \( n \). Now, consider the short exact sequence

\[
1 \to \frac{N}{N \cap \gamma_2(G)} \to \frac{\langle N, x \rangle}{N \cap \gamma_2(G)} \to C_n \cong \frac{\langle N, x \rangle}{N} \to 1.
\]

The group \( \frac{N}{N \cap \gamma_2(G)} \) is torsion free and hence isomorphic to \( \mathbb{Z}^k \) for some \( k \). By the lemma above, we know that the action of \( x \) on this group has to be trivial. But this action is the same as the action which is induced by \( \alpha \) on \( \frac{N}{N \cap \gamma_2(G)} \). As \( \frac{N}{N \cap \gamma_2(G)} \) is a lattice of \( G/\gamma_2(G) \), it follows that \( \alpha \) induces the identity automorphism on \( G/\gamma_2(G) \) and by the remark above, we have that \( \alpha \) is the identity automorphism. Hence \( x = (g, 1) \in N \) and so \( N \) is maximal nilpotent. \( \square \)
Also the second Bieberbach Theorem has a straightforward generalization. This theorem was proved by K.B. Lee and F. Raymond in [71].

Theorem 3.7 (Generalized Second Bieberbach Theorem). Let \( \varphi : \Gamma \to \Gamma' \) be an isomorphism between two almost-crystallographic groups, then \( \Gamma \) and \( \Gamma' \) are modeled on the same Lie group \( G \), and moreover, there exists an affine map \( \alpha \in \text{Aff}(G) \) such that

\[
\forall \gamma \in \Gamma : \varphi(\gamma) = \alpha \circ \gamma \circ \alpha^{-1}.
\]

We remark here that in [71] it was assumed from the beginning that \( \Gamma \) and \( \Gamma' \) were modeled on the same nilpotent Lie group. However assume that \( \Gamma \) is modeled on \( G \) and \( \Gamma' \) is modeled on \( G' \). Then, if \( \varphi : \Gamma \to \Gamma' \) is an isomorphism, \( \varphi \) also induces an isomorphism between \( \Gamma \cap G \) and \( \Gamma' \cap G' \) because these groups are both characterized as being the unique normal and maximal nilpotent subgroup of \( \Gamma \cap G \) resp. \( \Gamma' \cap G' \). As these groups are lattices in \( G \) and \( G' \), this isomorphism extends uniquely to an isomorphism of \( G \) to \( G' \) and hence we can assume that \( G \) equals \( G' \). Note that for this theorem it is not necessary that the same maximal compact subgroup \( C \subseteq \text{Aut}(G) \) is used to define both \( \Gamma \) and \( \Gamma' \).

In a following section, we will even further generalize this theorem for general homomorphisms \( \varphi \). This will lead to a complete understanding of all maps between two given infra-nilmanifolds up to homotopy.

The third Bieberbach Theorem is less trivial to generalize. It is no longer true that for a given dimension \( n \) there are only finitely many \( n \)-dimensional almost-crystallographic groups (or even almost-Bieberbach groups) up to isomorphism. This is not even true when one restricts to considering only almost-Bieberbach groups modeled on a given nilpotent Lie group \( G \). Indeed, if one considers the real Heisenberg group \( H^R \), which is the easiest non-abelian nilpotent Lie group, then this group contains all of the groups \( H_n \) as a lattice (see page 6). These groups \( H_n \) are pairwise non-isomorphic almost-Bieberbach groups modeled on \( H^R \) and hence the corresponding nilmanifolds \( H_n \backslash \mathbb{R}^n \) are pairwise non-homeomorphic.

So the big difference with the abelian case is that a fixed nilpotent Lie group \( G \) can have infinitely many non-isomorphic lattices, while all lattices of \( \mathbb{R}^n \) are isomorphic to the same group \( \mathbb{Z}^n \). Algebraically, we can also formulate the third Bieberbach theorem as follows. Fix a positive integer \( n \), then there are only finitely many crystallographic groups containing \( \mathbb{Z}^n \) as its group of pure translations. From this point of view, the third Bieberbach theorem does have a direct generalization.

Theorem 3.8. Let \( N \) be a finitely generated, torsion free nilpotent group. Then there are, up to isomorphism, only finitely many almost-crystallographic groups \( \Gamma \) for which the group of pure translations of \( \Gamma \) is isomorphic to \( N \).

This theorem was first formulated by K.B. Lee in [69] (but see also [24]) using the concept of an essential extension. An essential extension of a finitely generated, torsion free nilpotent group \( N \) is an extension of the form

\[
1 \to N \to E \to F \to 1
\]

in which \( F \) is a finite group and \( N \) is maximal nilpotent in \( E \). So any almost crystallographic group \( \Gamma \) modeled on \( G \) gives rise to such an essential extension: \( 1 \to N = \Gamma \cap G \to \Gamma \to F = \Gamma / (G \cap N) \to 1 \) by the generalized first Bieberbach theorem and Proposition 3.6. Later on, we will see that any group \( E \) which is obtained as such an essential extension of \( N \) is (isomorphic to) an almost-crystallographic group.

As already promised, we end this section with some explicit examples of almost-crystallographic and almost-Bieberbach groups.

Let \( N = H \) be the Heisenberg group, which is a lattice of its Mal’cev completion \( H^R = UT_3(\mathbb{R}) \). Let \( \varphi \in \text{Aut}(H^R) \) be the automorphism of order 3, which we introduced on page 7 (on that page we defined it on \( H^Q \), but the definition also works on \( H^R \) of course). Let \( F = \{1, \varphi, \varphi^2\} \subseteq \text{Aut}(H^R) \),
then $F \cong \mathbb{Z}_3$. As we already saw, we have that $\varphi(N) = N$. It follows that we can form the semidirect product

$$\Gamma_1 = N \rtimes F \subset H^\mathbb{R} \rtimes F \subseteq \text{Aff}(H^\mathbb{R}).$$

It is not difficult to see that $\Gamma_1$ is discrete and cocompact in $H^\mathbb{R} \rtimes F$ and hence $\Gamma_1$ is an almost-crystallographic group. It is not an almost-Bieberbach group since $\Gamma_1$ has torsion (e.g. $\varphi$ is an element of order 3 in $\Gamma_1$).

Take

$$c_1 = \begin{pmatrix} 1 & 0 & \frac{1}{3} \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \in H^\mathbb{R}$$

(This notation comes from the fact that $(c_1)^3 = c$, where $c$ (and $a, b$) were defined on page 9).

Let $\alpha = c_1 \varphi \in H^\mathbb{R} \rtimes F$. Let

$$\Gamma_2 = \langle N, \alpha \rangle$$

One computes that $\alpha^3 = c$ and that $\alpha N \alpha^{-1} = N$. Using this, it is not so difficult to see that $N$ is a normal subgroup of $\Gamma_2$ of index 3 and that $\Gamma_2$ is indeed an almost-crystallographic group. Note that for any element $\gamma$ of $\Gamma_2$ there exists a $\lambda \in N$ such that one of the three following expressions holds:

$$\gamma = \lambda, \quad \gamma = \lambda \alpha \quad \text{or} \quad \gamma = \lambda \alpha^2.$$

Moreover, we claim that this group $\Gamma_2$ is torsion free and hence $\Gamma_2$ is an almost-Bieberbach group and $\Gamma_2 \backslash H^\mathbb{R}$ is an infra-nilmanifold with holonomy group $F \cong \mathbb{Z}_3$. How do we check that $\Gamma_2$ is torsion free? It turns out that this can be done quite easily by using the 4-dimensional matrix representation $\psi$ of $H^\mathbb{R}$ which we defined on page 10 (where one has to replace $\mathbb{Q}$ by $\mathbb{R}$). We can extend this representation $\psi : H^\mathbb{R} \rightarrow \text{GL}(\mathbb{R}^4)$ to a representation (which we also denote by $\psi$)

$$\psi : H^\mathbb{R} \rtimes F \rightarrow \text{GL}(\mathbb{R}^4)$$

by mapping $\alpha$ to $A$ (see page 14). The fact that this is really a representation follows from the fact that $\psi(\varphi(h)) = A\psi(h)A^{-1}$ for all $h \in H^\mathbb{R}$ (which was explained at the end of section 2). Now let us assume that $\Gamma_2$ is not torsion free, then there has to exist a non-trivial element $\gamma$ of $\Gamma_2$ which is of finite order. As $\gamma^3 \in N$ and $N$ is torsion free, we must have that $\gamma^3 = 1$. Moreover, $\gamma$ cannot belong to $N$, so we must have that there exists a $\lambda \in N$ such that $\gamma = \lambda \alpha$ or $\gamma = \lambda \alpha^2$. By replacing $\gamma$ with $\gamma^3$ if necessary, we may assume that $\gamma = \lambda \alpha$. It follows that

$$\psi(\gamma^3) = \psi(\lambda \alpha^3) = \begin{pmatrix} 1 & 0 & \frac{1}{3} - \frac{x}{2} + z \\ 0 & 1 & -1 \\ 0 & 0 & 1 \end{pmatrix}, \quad \text{for some } x, y, z \in \mathbb{Z}.$$
4 Characterizations of almost–crystallographic groups

In this section we want to describe several algebraic characterizations of almost–crystallographic groups. As any almost–crystallographic group \( E \) can be seen as an extension \( 1 \to N \to E \to F \to 1 \) where \( N \) is a nilpotent group, it is useful to recall the basic theory of group extensions with a non-abelian kernel \( N \) (see e.g. [7] Section IV.6).

For the moment, let

\[ 1 \to N \to E \to F \to 1 \]

be any extension of groups, with no restriction on the groups involved. There is a natural homomorphism \( \phi : E \to \text{Aut}(N) \) which is induced by conjugation inside \( E \): we have that \( \phi(e) : N \to N : n \mapsto \phi(e)(n) = ene^{-1} \), where we will consider \( N \) as a subgroup of \( E \). As \( \phi(N) = \text{Inn}(N) \), this induces a homomorphism \( \psi : F \to \text{Out}(N) = \text{Aut}(N)/\text{Inn}(N) \). We will call a homomorphism \( \psi : F \to \text{Out}(N) \) an abstract kernel and we say that the extension \( 1 \to N \to E \to F \to 1 \) is compatible with the abstract kernel \( \psi \) (which we obtained from \( \phi \)).

Now given two groups \( F \) and \( N \) and an abstract kernel \( \psi : F \to \text{Out}(N) \), we want to classify all group extensions \( 1 \to N \to E \to F \to 1 \) which are compatible with \( \psi \). Let us recall that two extensions \( 1 \to N \to E \to F \to 1 \) and \( 1 \to N \to E' \to F \to 1 \) are said to be equivalent if and only if there exists a homomorphism \( \alpha : E \to E' \) (which will be necessarily an isomorphism), such that the following diagram commutes:

\[
\begin{array}{ccc}
1 & \longrightarrow & N & \longrightarrow & E & \longrightarrow & F & \longrightarrow & 1 \\
\downarrow & & \downarrow & & \downarrow & & \downarrow & & \downarrow \\
1 & \longrightarrow & N & \longrightarrow & E' & \longrightarrow & F & \longrightarrow & 1.
\end{array}
\]

Let us denote by \( \text{Ext}_\psi(F,N) \) the set of equivalence classes of extensions of \( N \) by \( F \) compatible with \( \psi \). It might happen that this set is empty. But suppose for the moment that it is not empty and fix such an extension \( 1 \to N \to E \to F \to 1 \). Choose a function \( s : F \to E \), such that \( s(1) = 1 \) and \( s(f) \) is mapped to \( f \) under the projection \( E \to F \). This \( s \) determines a function \( \varphi : F \to \text{Aut}(N) : f \mapsto \varphi(f) \), where \( \varphi(f) : N \to N : n \mapsto s(f)ns(f)^{-1} \). If \( p : \text{Aut}(N) \to \text{Out}(N) \) denotes the natural projection, we then have that \( p \circ \varphi = \psi \). The function \( s \) also determines a second function, a non-abelian 2-cocycle, \( c : F \times F \to N \), which is given by \( c(f,g) = s(f)s(g) \) for all \( f,g \in F \). The function \( \varphi \) and \( c \) satisfy the following two conditions:

1. \( \forall f,g \in F : \varphi(f)(\varphi(g)) = \mu(c(f,g)) \varphi(fg) \) where \( \mu(x) : N \to N : n \mapsto xux^{-1} \) denotes the inner automorphism determined by \( x \).

2. \( \forall f,g,h \in F : c(f,g)c(fg,h) = (\varphi(f)(c(g,h)))c(f,gh) \).

Conversely, given two functions \( c : F \times F \to N \) and \( \varphi : F \to \text{Aut}(N) \) with \( p \circ \varphi = \psi \), satisfying the two conditions above, one constructs the extension \( E_{c,\varphi} \), where the underlying set is \( N \times F \) and the product is given by

\[
\forall m,n \in N, \forall f,g \in F : (n,f)(m,g) = (n(\varphi(f)(m)))c(f,g),fg).
\]

E.g., when there is a homomorphism \( \varphi : F \to \text{Aut}(N) \), lifting \( \psi \), then one can take \( c(f,g) = 1 \) for all \( f,g \in F \) and then \( E_{c,\varphi} \) is just \( N \rtimes_\varphi F \).

The main result on the classification of extensions with a non-abelian kernel says that if \( \text{Ext}_\psi(F,N) \) is non-empty, then this set is in 1-1 correspondence with \( H^2(F,Z(N)) \).

A proof of the following result can be found in [15] Lemma 3.1.2 for the case \( F = \mathbb{R} \), but the proof also works for \( F = \mathbb{Q} \).

**Lemma 4.1.** Let \( N \) be a finitely generated torsion free nilpotent group and let \( F \) be a finite group. Let \( F = \mathbb{Q} \) or \( \mathbb{R} \) and suppose that \( \psi : F \to \text{Out}(N^F) \) is an abstract kernel. Then
1. \( \psi \) lifts to a homomorphism \( \phi : F \rightarrow \text{Aut}(N^F) \) and

2. any extension of \( N^F \) by \( F \) is a split extension (i.e. is equivalent to a semi-direct product \( N^F \rtimes \phi F \)).

We are now going to prove our first algebraic characterization of almost–crystallographic groups. The proof of this theorem is of a constructive nature and has thus importance from this point of view also.

**Theorem 4.2.** Let \( E \) be a finitely generated virtually nilpotent group. Then, the following are equivalent:

1. \( E \) is (isomorphic to) an almost–crystallographic group.

2. \( E \) contains a finitely generated torsion free nilpotent normal subgroup \( N \) such that \( N \) is maximal nilpotent in \( E \) and \( [E : N] < \infty \). (In other words if and only if \( E \) can be seen as an essential extension).

3. \( E \) does not contain a nontrivial finite normal subgroup.

**Proof.** (1. \( \Rightarrow \) 2.) When \( E \cong \Gamma \), then the generalized first Bieberbach Theorem 3.4 and Proposition 3.6 show the existence of the subgroup \( N \) (which corresponds to the group of pure translation \( \Gamma \cap G \) in \( \Gamma \)).

(2. \( \Rightarrow \) 3.) Assume that \( E \) does contain a non-trivial finite normal subgroup \( G \), then \( [G, N] \subseteq N \cap G = 1 \) which implies that \( \forall g \in G \) the group \( \langle N, g \rangle \) is nilpotent, contradicting the maximal nilpotency of \( N \).

(3. \( \Rightarrow \) 1.) Now, assume that \( N \) is a nilpotent normal subgroup of finite index in \( E \). Then \( N \) is torsion free, because the set of torsion elements of \( N \) is a finite normal subgroup of \( \text{Out}(N) \). Then we consider the extension

\[
1 \rightarrow N \rightarrow E \rightarrow F \rightarrow 1
\]

and choose a section \( s : F \rightarrow E \) giving rise to a map \( \varphi : F \rightarrow \text{Aut}(N) \) (which is a lift of the abstract kernel of the extension) and a non-abelian 2-cocycle \( c : F \times F \rightarrow N \) satisfying the two conditions mentioned above. If we denote the extension of \( F \) by \( N \) determined by \( c \) and \( \varphi \) as \( E_{c,\varphi} \) as before, we know that there is a commutative diagram of the form (where \( \alpha \) is an isomorphism):

\[
\begin{array}{cccccc}
1 & \rightarrow & N & \rightarrow & E & \rightarrow & F & \rightarrow & 1 \\
\downarrow & & \downarrow & & \alpha & & \downarrow & & \\
1 & \rightarrow & N & \rightarrow & E_{c,\varphi} & \rightarrow & F & \rightarrow & 1.
\end{array}
\]

Now, since any automorphism \( \varphi(f) \in \text{Aut}(N) \) can be extended uniquely to an automorphism \( \tilde{\varphi}(f) \in \text{Aut}(N^R) \), we obtain a map \( \tilde{\varphi} : F \rightarrow \text{Aut}(N^R) \), such that the composition \( \psi : F \rightarrow \text{Aut}(N^R) \rightarrow \text{Out}(N^R) \) is a homomorphism (so an abstract kernel).

The map \( c : F \times F \rightarrow N \) can also be interpreted as a map \( \tilde{c} : F \times F \rightarrow N^R \) (using the embedding of \( N \) into \( N^R \)). Of course, the pair \( \tilde{c}, \tilde{\varphi} \) still satisfies the two 2-cocycle conditions and we can define the group \( \tilde{E}_{\tilde{c},\tilde{\varphi}} \) which is an extension of \( N^R \) by \( F \). Now, let \( i : N \rightarrow N^R \) denote the embedding, then we have a commutative diagram:

\[
\begin{array}{cccccc}
1 & \rightarrow & N & \rightarrow & E_{c,\varphi} & \rightarrow & F & \rightarrow & 1 \\
\downarrow & & \downarrow & & i \times 1_F & & \downarrow & & \\
1 & \rightarrow & N^R & \rightarrow & \tilde{E}_{\tilde{c},\tilde{\varphi}} & \rightarrow & F & \rightarrow & 1.
\end{array}
\]
By Lemma 4.1, we know that the bottom sequence splits and so there is a commutative diagram in which $\beta$ is an isomorphism and $\varphi' : F \to \text{Aut}(N^R)$ is another lift of the abstract kernel $\psi : F \to \text{Out}(N^R)$, which is a homomorphism of groups:

\[
\begin{array}{c}
1 \rightarrow N^R \rightarrow \tilde{E}_{c,\tilde{\varphi}} \rightarrow F \rightarrow 1 \\
\downarrow \quad \downarrow \beta \quad \downarrow \gamma \quad \downarrow \varphi' \quad \downarrow \gamma \quad \downarrow \varphi' \\
1 \rightarrow N^R \rightarrow N^R \rtimes \varphi' F \rightarrow F \rightarrow 1.
\end{array}
\]

Let $\gamma = 1 \times \varphi' : N^R \rtimes \varphi' F \rightarrow N^R \rtimes \text{Aut}(N^R) : (n, f) \mapsto (n, \varphi'(f))$. This is a homomorphism, inducing a commutative diagram

\[
\begin{array}{c}
1 \rightarrow N^R \rightarrow N^R \rtimes \varphi' F \rightarrow F \rightarrow 1 \\
\downarrow \downarrow \gamma \quad \downarrow \varphi' \quad \downarrow \\
1 \rightarrow N^R \rightarrow N^R \rtimes \text{Aut}(N^R) \rightarrow \text{Aut}(N^R) \rightarrow 1.
\end{array}
\]

Now, let $j : E \to N^R \rtimes \text{Aut}(N^R)$ be the composition $j = \gamma \circ \beta \circ (i \times 1_F) \circ \alpha$:

\[
\begin{array}{c}
E \xrightarrow{\alpha} E_{c,\alpha} \xrightarrow{i \times 1_F} \tilde{E}_{c,\tilde{\varphi}} \xrightarrow{\beta} N^R \rtimes \varphi' F \xrightarrow{\gamma} N^R \rtimes \text{Aut}(N^R) \\
N \xrightarrow{1_N} N \xleftarrow{i} N \xrightarrow{1_{N^R}} N^R \xleftarrow{1_{N^R}} N^R
\end{array}
\]

Note that when we restrict $j$ to $N$, we obtain the embedding $j|_N = i : N \hookrightarrow N^R$ of $N$ into its real Mal’cev completion. This shows $\text{Ker}(j) \cap N = 1$, from which it follows that $\text{Ker}(j)$ is finite. However, as we are assuming that $E$ does not have any non-trivial finite subgroups, this implies that $j$ is injective and hence $E \cong j(E)$. Note that $j(E) \subseteq N^R \rtimes \varphi'(F)$. As $\varphi'(F)$ is finite, we can choose a maximal compact subgroup $C \subseteq \text{Aut}(\mathbb{R}^R)$ containing $\varphi'(F)$ and then we have that $j(E) \subseteq N^R \rtimes C$. Now, $j(E) \cap N^R$ is a group containing $N$ as a subgroup of finite index. As $N$ is a lattice in $N^R$, also $j(E) \cap N^R$ is a lattice of $N^R$. And hence $j(E) \cap N^R$ is a discrete and cocompact subgroup of $N^R \rtimes C$. However, as $j(E)$ contains $j(E) \cap N^R$ as a subgroup of finite index, also $j(E)$ itself is discrete and cocompact in $N^R \rtimes C$, showing that $E \cong j(E)$ is an almost-crystallographic group modeled on $N^R$.

The above characterization of almost-crystallographic groups immediately implies the following description of almost-Bieberbach groups.

**Corollary 4.3.** A group $E$ is isomorphic to an almost–Bieberbach group if and only if $E$ is a finitely generated torsion free virtually nilpotent group.

Also the following result is easy to deduce now:

**Corollary 4.4.** Let $\Gamma$ be an almost–crystallographic group and let $E$ be any normal subgroup of $\Gamma$, then $E$ is also an almost–crystallographic group.

**Proof.** As $\Gamma$ is finitely generated virtually nilpotent, the group $E$ is also finitely generated and virtually nilpotent. Let $G$ be the unique maximal finite normal subgroup of $E$ (which exists in any polycyclic-by-finite group), then $G$ is characteristic in $E$ and hence normal in $\Gamma$. But since $\Gamma$ is almost–crystallographic, this implies that $G = 1$, which in turn implies that $E$ is almost–crystallographic.

\[\square\]
The next result we want to mention is useful for constructing almost–crystallographic groups by induction on the Hirsch length (which equals the dimension).

To explain this result, we need some more background on nilpotent groups. Let $N$ be a finitely generated torsion free nilpotent group, then generally $N/\gamma_i(N)$ is not torsion free. But we can introduce the groups

$$\sqrt{\gamma_i(N)} = \{ n \in N \mid 3^k > 0 : n^k \in \gamma_i(N) \}.$$  

Then $\sqrt{\gamma_i(N)} = p^{-1}\tau(N/\gamma_i(N))$, where $\tau(N/\gamma_i(N))$ is the finite group of all torsion elements of $N/\gamma_i(N)$ and $p : N \to N/\gamma_i(N)$ is the natural projection. It follows that $N/\sqrt{\gamma_i(N)}$ is torsion-free and $\gamma_i(N)$ is contained in $\sqrt{\gamma_i(N)}$ as a subgroup of finite index. In fact, $\sqrt{\gamma_i(N)}$ is the smallest normal subgroup $H$ of $N$, containing $\gamma_i(N)$ as a subgroup of finite index and for which $N/H$ is torsion free.

This group can also be described using the rational or real Mal’cev completion of $N$:

**Lemma 4.5.** Let $N$ be a finitely generated torsion free nilpotent group, then for all $i > 0$:

$$\sqrt{\gamma_i(N)} = N \cap \gamma_i(N^R) = N \cap \gamma_i(N^Q).$$

Using this lemma it follows immediately that $[\sqrt{\gamma_i(N)}, \sqrt{\gamma_j(N)}] \subseteq \sqrt{\gamma_{i+j}(N)}$.

**Theorem 4.6.** Let $\Gamma$ be an almost–crystallographic group with translation subgroup $N$. Then for any $i > 1$, the group $\Gamma/\sqrt{\gamma_i(N)}$ is also an almost–crystallographic group.

**Proof.** There is a short exact sequence $1 \to N \to \Gamma \to F \to 1$ where $F$ is a finite group and $N$ is maximal nilpotent in $\Gamma$. This gives rise to a short exact sequence $1 \to N/\sqrt{\gamma_i(N)} \to \Gamma/\sqrt{\gamma_i(N)} \to F \to 1$, so that $\Gamma/\sqrt{\gamma_i(N)}$ contains the finitely generated torsion free nilpotent group $N/\sqrt{\gamma_i(N)}$ as a subgroup of finite index. By Theorem 4.2 it suffices to show that $\Gamma/\sqrt{\gamma_i(N)}$ does not contain a nontrivial finite normal subgroup $G$. Suppose on the contrary that such a $G$ does exist, then $[N/\sqrt{\gamma_i(N)}, G] = 1$. So any element $g \in G$ commutes with $N/\sqrt{\gamma_i(N)}$. Now, let $e \in E$, such that its image in $\Gamma/\sqrt{\gamma_i(N)}$ is a nontrivial element in $G$. Then $e \notin N$ and conjugation with $e$ in $E$ induces the identity automorphism on $N/\sqrt{\gamma_i(N)}$. It follows that it also induces the identity automorphism on $N/\sqrt{\gamma_j(N)}$. From, this it now follows that conjugation with $e$ induces the identity automorphism on each of the quotients $\sqrt{\gamma_i(N)}/\sqrt{\gamma_{i+j}(N)}$. This is enough to conclude that the group $\langle N, e \rangle$ is nilpotent, contradicting the maximal nilpotency of $N$ in $E$.

This theorem shows that if $\Gamma$ is an almost–crystallographic group, with a $c$-step nilpotent translation subgroup $N$, $\Gamma$ fits in a short exact sequence

$$1 \to \sqrt{\gamma_c(N)} \to \Gamma \to \Gamma/\sqrt{\gamma_c(N)} \to 1.$$  

Here $\sqrt{\gamma_c(N)} \cong \mathbb{Z}^k$ (for some $k$) and $\Gamma/\sqrt{\gamma_c(N)}$ is an almost–crystallographic subgroup containing $N/\sqrt{\gamma_c(N)}$ as its translation subgroup. The short exact sequence is almost central, since $N/\sqrt{\gamma_c(N)}$ acts trivially on $\sqrt{\gamma_c(N)}$. This implies that to construct all possible $\Gamma$, we need to construct all possible almost-central extensions of $\mathbb{Z}^k$ by all possible $\Gamma/\sqrt{\gamma_c(N)}$, which leads to a classification procedure by induction on the dimension. This approach was used to obtain the classification in dimensions 3 and 4 in [15].

To end this section, we introduce the so called rational representation of an almost–crystallographic group. In the proof of Theorem 4.2 we constructed for any abstract crystallographic group an embedding $j : E \to N^Q \rtimes \text{Aut}(N^R)$. One can also do this proof by using $N^Q$ in stead of $N^R$. In this way we will obtain an embedding $i : E \to N^Q \rtimes \text{Aut}(N^Q)$, in such a way that the composite map $E \to N^Q \rtimes \text{Aut}(N^Q) \to \text{Aut}(N^Q)$ has a finite image, say $F$. If we start this construction with $N$ being the unique normal and maximal nilpotent subgroup of $E$, then $F = E/N$. If $N'$ is another normal nilpotent group of finite index in $E$, then $N' \subseteq N$, $N'^Q = N^Q$ and $E/N'$ is a group which maps onto $F$ (indeed $(E/N')(N/N') = F)$.
Definition 4.7. Let $\Gamma$ be an almost–crystallographic group. A rational realization of $\Gamma$ is an embedding

$$i : \Gamma \to N^Q \times \text{Aut}(N^Q)$$

where $N$ is a finitely generated torsion free nilpotent group and the composition $\Gamma \to N^Q \times \text{Aut}(N^Q) \to \text{Aut}(N^Q)$ has finite image, say $F$.

We just explained that any almost-crystallographic group has a rational representation. Moreover, if we consider the composition $j : \Gamma \to N^Q \times \text{Aut}(N^Q) \to N^R \times \text{Aut}(N^R)$, then $j(\Gamma)$ is a genuine almost–crystallographic subgroup with translation subgroup $j(\Gamma) \cap N^R = i(\Gamma) \cap N^Q$. It follows that the group $F$ is the holonomy group of $\Gamma$ (see the generalized first Bieberbach theorem).

The induced representation

$$\phi : F \to \text{Aut}(N^Q)$$

is called the rational holonomy representation. This representation depends on the choice of $\varphi$ and its chosen lift $\tilde{\varphi}'$. Other choices will alter $\varphi$ by an inner automorphism of $N^Q$. Note that since $\text{Aut}(N^Q) \cong \text{Aut}(n^Q)$, we can view the rational holonomy representation as a representation into a rational vector space. Analogously, one can define the real holonomy representation (which is often just called the holonomy representation).

It is often useful to consider only the induced representation

$$\varphi_{ab} : F \to \text{Aut}(N^Q/[N^Q,N^Q]) = \text{Aut}(n^Q/[n^Q,n^Q])$$

which will be referred to as the abelianized rational holonomy representation. This abelianized representation is independent of any choices made for $\varphi$ or $\tilde{\varphi}'$.

5 Maps on infra–nilmanifolds

In this section we will describe all possible maps between two infra–nilmanifolds up to homotopy. In order to do this, we need to generalize the second Bieberbach theorem even further.

Let $G_1$ and $G_2$ be two simply connected nilpotent Lie group, then we will use $\text{End}(G_1,G_2)$ to denote the set of continuous homomorphisms from $G_1$ to $G_2$. We now let $\text{aff}(G_1,G_2) = G_2 \times \text{End}(G_1,G_2)$ and any $(d,\delta) \in \text{aff}(G_1,G_2)$ (so $d \in G_2$ and $\delta \in \text{End}(G_1,G_2)$) determines a so called affine map

$$(d,\delta) : G_1 \to G_2 : g \mapsto d \cdot \delta(g).$$

Note that in case $G_1 = \mathbb{R}^k$ and $G_2 = \mathbb{R}^l$, $\text{aff}(\mathbb{R}^k,\mathbb{R}^l)$ is the usual set of affine maps from $\mathbb{R}^k$ to $\mathbb{R}^l$.

When $G_1 = G_2 = G$ we will use $\text{aff}(G)$ to denote $\text{aff}(G,G)$. In this case $\text{aff}(G) = G \times \text{End}(G)$ (where $\text{End}(G) = \text{End}(G,G)$) is a semigroup containing the group $\text{Aff}(G)$. Then, $\text{Aff}(G)$ consists exactly of the invertible elements of $\text{aff}(G)$. It was K.B. Lee who first proved the more general version of the generalized second Bieberbach theorem in [70] in the case $G_1 = G_2$. A slightly adapted proof for the case $G_1 \neq G_2$ can be found e.g. in [68]. (In fact, in this last paper the groups $G_1$ and $G_2$ are assumed to be soluble of type (R), which is even more general than being nilpotent). As I cannot improve their arguments, I refer to those papers for the proof.

Theorem 5.1. Take $i = 1$ or $2$ and Let $G_i$ be a simply connected nilpotent Lie group, $C_i \subseteq \text{Aut}(G_i)$ be a maximal compact subgroup and $\Gamma_i \subseteq G_i \times C_i$ be an almost–crystallographic group. Then, for any homomorphism $\theta : \Gamma_1 \to \Gamma_2$, there exists an affine map $(d,\delta) \in \text{aff}(G_1,G_2)$ such that

$$\forall \gamma \in \Gamma_1 : \theta(\gamma) \circ (d,\delta) = (d,\delta) \circ \gamma.$$
then as $N^2 = N_1^2 = G_1$, there is a unique extension of $\alpha$ to a homomorphism $\tilde{\alpha} : G_1 \to G_2$. For all $n \in N$ we have that

$$(\tilde{\alpha}(n) d, \delta) = (\tilde{\alpha}(n), 1) \circ (d, \delta) = \theta(n, 1) \circ (d, \delta) = (d, \delta) \circ (n, 1) = (d\delta(n), \delta)$$

showing that $\tilde{\alpha}(n) = d\delta(n)d^{-1}$ for all $n \in N$. Since $N$ is a lattice in $G_1$, it follows that $\tilde{\alpha}(g) = d\delta(g)d^{-1}$ for all $g \in G_1$. Hence, $\delta$ is determined, up to an inner automorphism of $G_2$, by $\alpha$, the restriction of $\theta$ to $N$. We have the following:

**Lemma 5.2.** With the notations of Theorem 5.1,

1. $\delta$ is injective $\iff$ $\theta$ is injective $\iff$ $\theta|_H$ is injective, where $H$ is any finite index subgroup of $\Gamma_1$.

2. $\delta$ is surjective if and only if $\theta(\Gamma_1)$ is of finite index in $\Gamma_2$.

**Proof.** Let $H$ be a finite index subgroup of $\Gamma_1$ We first of all show that $\theta$ is injective $\iff$ $\theta|_H$ is injective. Of course, one direction is obvious. Now suppose that $\theta|_H$ is injective. Since $H$ is of finite index in $\Gamma_1$, this implies that the kernel of $\theta$ is finite. But $\Gamma_1$ does not contain any non-trivial finite normal subgroup, so $\theta$ is injective. Now, let $N$ be the subgroup of $\Gamma_1$ with $\theta(N) \subseteq N_2$ as mentioned above and let $\tilde{\alpha} : G_1 \to G_2$ be the unique lift of $\alpha = \theta|_N$. Then $\tilde{\alpha}$ is injective if and only if $\alpha$ is injective. Moreover, as explained above $\tilde{\alpha}(g) = d\delta(g)d^{-1}$ for all $g \in G_1$ from which it follows that $\tilde{\alpha}$ is injective if and only if $\delta$ is injective. We can conclude that $\delta$ is injective if and only if $\alpha$ is injective if and only if $\theta$ is injective.

Analogously, $\delta$ is surjective if and only if $\tilde{\alpha}$ is. Now $\tilde{\alpha}$ is surjective if and only if $\alpha(N)$ is a lattice of $G_2$. As $\alpha(N) = \theta(N) \subseteq N_2$, we have that $\theta(N)$ is a lattice of $G_2$ if and only if $\theta(N)$ is of finite in $N_2$, which is equivalent to being of finite index in $\Gamma_2$. But $\theta(N)$ being of finite index in $\Gamma_2$ is equivalent to $\theta(\Gamma_1)$ being of finite index in $\Gamma_2$, so we proved that $\delta$ is surjective if and only if $[\Gamma_2 : \theta(\Gamma_1)] < \infty$.

**Remark.** When $G_1 = G_2$ and $\theta : \Gamma_1 \to \Gamma_2$ is an isomorphism, then the above lemma implies that $\delta \in \text{Aut}(G)$ and so $(d, \delta) \in \text{Aff}(G)$ and we have that

$$\forall \gamma \in \Gamma_1 : \theta(\gamma) \circ (d, \delta) = (d, \delta) \circ \gamma \text{ or equivalently } \theta(\gamma) = (d, \delta)\gamma(d, \delta)^{-1},$$

which is exactly what Theorem 5.7 says.

Now, we will use this in the study of maps between two infra-nilmanifolds and therefore from now onwards we assume that $\Gamma_1$ and $\Gamma_2$ are almost-Bieberbach groups modeled on $G_1$ and $G_2$ respectively. Let $p_i : \Gamma_1 \to \Gamma_1 \backslash G_i (i = 1, 2)$ denote the natural projections ($G_i$ is the universal covering space of $\Gamma_1 \backslash G_i$).

The generalized second Bieberbach Theorem gives a way of constructing maps between two infra-nilmanifolds

**Lemma 5.3.** For $i = 1, 2$, let $\Gamma_i$ be an almost-Bieberbach group modeled on a simply connected nilpotent Lie group $G_i$ and let $\theta : \Gamma_1 \to \Gamma_2$ be any homomorphism. Consider $(d, \delta) \in \text{Aff}(G_1, G_2)$ with

$$\forall \gamma \in \Gamma_1 : \theta(\gamma) \circ (d, \delta) = (d, \delta) \circ \gamma,$$

then $(d, \delta)$ induces a map

$$(d, \delta) : \Gamma_1 \backslash G_1 \to \Gamma_2 \backslash G_2 : \Gamma_1 \cdot g \mapsto \Gamma_2 \cdot ((d, \delta) \cdot g) = \Gamma_2 \cdot d\delta(g).$$

**Proof.** We have to show that $(d, \delta)$ is well-defined. So take $g \in G_1$ and $\gamma \in \Gamma_1$, then we need to check that $(d, \delta) \cdot g$ and $(d, \delta) \cdot (\gamma \cdot g)$ lie in the same $\Gamma_2$-orbit. But this is obvious since:

$$(d, \delta) \cdot (\gamma \cdot g) = ((d, \delta) \cdot \gamma) \cdot g = (\theta(\gamma) \circ (d, \delta)) \cdot g = \theta(\gamma) \cdot ((d, \delta) \cdot g) \in \Gamma_2 \cdot ((d, \delta) \cdot g).$$
**Definition 5.4.** We will refer to a map $(d, \delta): \Gamma_1 \backslash G_1 \to \Gamma_2 \backslash G_2$ as in the lemma above, as an affine map between the two infra-nilmanifolds.

Consider now any (continuous) map

$$f: \Gamma_1 \backslash G_1 \to \Gamma_2 \backslash G_2$$

and fix a lift $\tilde{f}_0: G_1 \to G_2$ of $f$. So we have a commutative diagram

$$
\begin{array}{ccc}
G_1 & \xrightarrow{\tilde{f}_0} & G_2 \\
p_1 & \downarrow & \downarrow p_2 \\
\Gamma_1 \backslash G_1 & \xrightarrow{f} & \Gamma_2 \backslash G_2
\end{array}
$$

Such a lift $\tilde{f}_0$ always exists and if we compose $\tilde{f}_0$ with $\beta \in \Gamma_2$, then $\tilde{f} = \beta \circ \tilde{f}_0$ will be another lift of $f$. And in fact all lifts $\tilde{f}$ of $f$ can be uniquely written as a composition $\beta \circ \tilde{f}_0$. So there is a 1–1 correspondence between the lifts of $f$ and $\Gamma_2$. On the other hand, for any $\alpha \in \Gamma_1$, we also have that $\tilde{f}_0 \circ \alpha$ is a lift of $f$. Hence, there exists a $\beta \in \Gamma_2$ such that $\tilde{f}_0 \circ \alpha = \beta \circ \tilde{f}_0$.

It follows that the map $f$ induces a homomorphism $f_*: \Gamma_1 \to \Gamma_2$ which is determined by

$$\forall \gamma \in \Gamma_1: \quad \tilde{f}_0 \circ \gamma = f_*(\gamma) \circ \tilde{f}_0.$$ 

The homomorphism $f_*$ depends on the choice of the reference lift $\tilde{f}_0$. Another choice of lift will change $f_*$ by an inner automorphism of $\Gamma_2$.

**Definition 5.5.** We will refer to $f_*: \Gamma_1 \to \Gamma_2$ as the induced homomorphism by $f$ (with respect to the reference lift $\tilde{f}_0$).

**Remark.** Let $(d, \delta)$ be an affine map (associated to $\theta: \Gamma_1 \to \Gamma_2$) as in Lemma 5.3. If one takes $(d, \delta)$ as the reference lift of $(\tilde{d}, \tilde{\delta})$, then the equation $\theta(\gamma) \circ (d, \delta) = (d, \delta) \circ \gamma$ shows that

$$[(d, \delta)]_\theta = \theta.$$

It follows that for any homomorphism $\theta: \Gamma_1 \to \Gamma_2$, we can construct a map $f: \Gamma_1 \backslash G_1 \to \Gamma_2 \backslash G_2$ such that $f_* = \theta$ (where we can take $f$ to be an affine map).

**Remark.** Under the right identifications of $\Gamma_i$ with the fundamental group of $\Gamma_i \backslash G_i$ ($i = 1, 2$) we have that $f_*$ exactly corresponds to the induced map on the fundamental group $f_*: \Pi_1(\Gamma_1 \backslash G_1, x) \to \Pi_1(\Gamma_2 \backslash G_2, f(x))$.

**Theorem 5.6.** For $i = 1, 2$, let $\Gamma_i$ be an almost–Bieberbach group modeled on a simply connected nilpotent Lie group $G_i$ and let $f, g: \Gamma_1 \backslash G_1 \to \Gamma_2 \backslash G_2$ be two maps such that $f_* = g_*: \Gamma_1 \to \Gamma_2$ (where $f_*$ and $g_*$ are the induced homomorphisms w.r.t. some reference lifts $\tilde{f}$ and $\tilde{g}$). Then $f$ and $g$ are homotopic.

**Proof.** In fact this theorem is a special case of a more general result for $K(\Pi, 1)$–spaces (see [91]).

There is also a constructive proof of this result. Let $\tilde{f}$ and $\tilde{g}$ be the reference lifts for $f$ and $g$ respectively, then, since $g_* = f_*:

$$\forall \gamma \in \Gamma: \quad f_*(\gamma) \circ \tilde{f} = \tilde{f} \circ \gamma \quad \text{and} \quad f_*(\gamma) \circ \tilde{g} = \tilde{g} \circ \gamma.$$

Consider the homotopy

$$H: G_1 \times I \to G_2: (x, t) \mapsto \tilde{f}(x) \left( (\tilde{f}(x))^{-1} \tilde{g}(x) \right)^t,$$

with $H(x, 0) = \tilde{f}(x)$ and $H(x, 1) = \tilde{g}(x)$.
where for all $y \in G_2$, we let $y' = \exp(t \log(y))$. Then $\tilde{H}(x,0) = \tilde{f}(x)$ and $\tilde{H}(x,1) = \tilde{g}(x)$, so $\tilde{H}$ is a homotopy between $f$ and $g$. We claim that $\tilde{H}$ induces a homotopy

$$H : \Gamma_1 \backslash G_1 \to \Gamma_2 \backslash G_2 : (\Gamma_1 \cdot x, t) \mapsto \Gamma_2 \cdot \tilde{H}(x,t)$$

between $f$ and $g$. It is obvious that $H(\Gamma_1 \cdot x,0) = \Gamma_2 \cdot \tilde{f}(x) = f(\Gamma_1 \cdot x)$ and $H(\Gamma_1 \cdot x,1) = g(\Gamma_1 \cdot x)$, so the only thing left to show is that $H$ is well defined. To do this, fix a $\gamma_1 \in \Gamma_1$ and let $f_* (\gamma_1) = (a,a) \in \Gamma_2 \subseteq \text{Aff}(G_2)$. Then $\forall x \in \Gamma_1$:

$$\tilde{H}(\gamma_1 \cdot x,t) = \tilde{f}(\gamma_1 \cdot x) \left( (\tilde{f}(\gamma_1 \cdot x))^{-1} \tilde{g}(\gamma_1 \cdot x) \right)^t$$

$$= \left( f_* (\gamma_1)(\tilde{f}(x)) \right) \left( (f_* (\gamma_1)(\tilde{f}(x)))^{-1} (f_* (\gamma_1)(\tilde{g}(x))) \right)^t$$

$$= \left( a \alpha (\tilde{f}(x)) \right) \left( (a \alpha (\tilde{f}(x)))^{-1} (a \alpha (\tilde{g}(x))) \right)^t$$

$$= \left( a \alpha (\tilde{f}(x)) \right) \left( \alpha (\tilde{f}(x))^{-1} \tilde{g}(x)) \right)^t$$

$$= f_* (\gamma_1) \cdot \tilde{H}(x,t) \in \Gamma_2 \cdot \tilde{H}(x,t)$$

from which it follows that $H$ is a well defined homotopy between $f$ and $g$. \hfill \Box

Combining all of the above, we now find that any map between to infra-nilmanifolds is homotopic to an affine map.

**Corollary 5.7.** For $i = 1,2$, let $\Gamma_i$ be an almost–Bieberbach group modeled on a simply connected nilpotent Lie group $G_i$ and let $f : \Gamma_1 \backslash G_1 \to \Gamma_2 \backslash G_2$ be any map. Then there exists an affine map $(d, \delta) : \Gamma_1 \backslash G_1 \to \Gamma_2 \backslash G_2$ which is homotopic to $f$.

**Proof.** Let $f_* : \Gamma_1 \to \Gamma_2$ be the homomorphism induced by $f$ and let $(d, \delta) \in \text{aff}(G_1, G_2)$ be the affine map with

$$\forall \gamma \in \Gamma_1 : \ f_*(\gamma) \circ (d, \delta) = (d, \delta) \circ \gamma$$

as in the generalized second Bieberbach Theorem [5.3]. Then we know that $(d, \delta)$ determines an affine map $(d, \delta)_* : \Gamma_1 \backslash G_1 \to \Gamma_2 \backslash G_2$ with $(d, \delta)_* = f_*$. It follows that $f$ and $(d, \delta)$ are homotopic. \hfill \Box

**Remark.** In the literature, there has been quite some confusion concerning maps between two infra-nilmanifolds (or selfmaps of a given infra-nilmanifold). This confusion seems to boil down to the fact that some authors believed that any such map was homotopic to one induced by a homomorphism $\delta : G_1 \to G_2$ (so by an affine map $(1, \delta)$, with trivial translational part $d = 1$), which is incorrect. We refer the reader to [18] and [17] for more information on this.

### 6 Computing with almost–crystallographic groups

When working with infra-nilmanifolds it is often needed to be able to make explicit computations involving almost–Bieberbach groups.

In this section, we want to explain how this can be done at least in case the Lie group on which the almost–Bieberbach group is modeled is of low nilpotency class.

First of all I would like to mention here the GAP package aclib [23, 36]. This package contains a library of almost–crystallographic groups of dimension at most 4 (including all almost–Bieberbach groups) together with some algorithms to compute with them. These almost–crystallographic groups are available in two formats. First of all, there is a faithful matrix representation for each of them. Secondly, all of these groups are polycyclic and they are also stored via a polycyclic...
presentation. As a consequence, all methods of the polygraphic package [31] are also available for these groups. We refer the reader to the manual of these two packages for more information.

The rest of this section will be devoted to the construction of an embedding of the affine group \( \text{Aff}(G) \) of a 2-step nilpotent Lie group \( G \) into the usual affine group \( \text{Aff}(\mathbb{R}^n) \), where \( n \) is the dimension of \( G \). Having also in mind the generalized second Bieberbach theorem, such an embedding is very useful to work with explicit examples of infra-nilmanifolds \( \Gamma \backslash G \) modeled on a 2-step nilpotent Lie group \( G \) and for constructing, understanding . . . selfmaps of the manifold \( \Gamma \backslash G \). This embedding was first constructed in [14], where the proof was quite technical. Here we present a new approach to the same embedding.

So for the rest of this section we fix a 2-step nilpotent Lie group \( G \). Let \( g \) denote the Lie algebra of \( G \), then \([g, g, g] = 0\) and so \( g \) fits in a short exact sequence

\[
0 \to [g, g] \to g \to g/[g, g] \to 0
\]

where both \([g, g]\) and \( g/[g, g]\) are abelian Lie algebras. Choose a basis \( v_1, v_2, \ldots, v_k, w_1, w_2, \ldots, w_l \) for \( g \), where \( v_1, v_2, \ldots, v_k \) form a basis of \([g, g]\), so \( k + l = n \) is the dimension of \( G \). In principle one can choose any basis of \( g \), but the embedding looks nicer, when using this choice. With such a choice of basis, the matrix representation of \( \text{ad}_X : g \to g : Y \to \text{ad}_X(Y) = [X, Y] \) is of the form:

\[
\text{ad}_X = \begin{pmatrix} 0 & M \\ 0 & 0 \end{pmatrix}
\]

where the 0’s denote blocks of zeroes and \( M \) is a \( k \times l \) matrix with possibly non-zero entries.

Let

\[
H = \left\{ \begin{pmatrix} A & a \\ 0 & 1 \end{pmatrix} \mid A \in \text{GL}(\mathbb{R}^n), a \in \mathbb{R}^n \right\},
\]

then it is easy to see that

\[
\psi : \text{Aff}(\mathbb{R}^n) \to H : (a, A) \mapsto \begin{pmatrix} A & a \\ 0 & 1 \end{pmatrix}
\]

is an isomorphism of (Lie) groups. We will in fact construct an embedding \( \varphi : \text{Aff}(G) \to H \).

The first step is to define \( \varphi \) on \( \text{Aut}(G) \). For this we just take the map \( \varphi \) which sends an automorphism \( \alpha \) to its differential \( \alpha_* \) and we add an extra row and column:

\[
\varphi_1 : \text{Aut}(G) \to H : \alpha \mapsto \begin{pmatrix} \alpha_* & 0 \\ 0 & 1 \end{pmatrix}
\]

where \( \alpha_* \) should be interpreted as the matrix representation of \( \alpha_* \) with respect to the chosen basis. It is obvious that \( \varphi_1 \) is an injective homomorphism.

For the translational part, we will first define an embedding of the Lie algebra \( g \) into \( \text{NT}_{n+1}(\mathbb{R}) \). Consider the following map:

\[
\varphi_{2*} : g \to \text{NT}_{n+1}(\mathbb{R}) : X \to \begin{pmatrix} \frac{1}{2}\text{ad}_X & X \\ 0 & 0 \end{pmatrix}
\]

In this definition, \( \text{ad}_X \) is actually the matrix representation of \( \text{ad}_X \) and \( X \) is the column vector of the coordinates of \( X \) with respect to the chosen basis. A short computation shows that \( \varphi_{2*} \) is a
Lie algebra homomorphism (which is obviously injective). Indeed, consider any \( X, Y \in \mathfrak{g} \), then

\[
[\varphi_2(X), \varphi_2(Y)] = \left[ \left( \frac{1}{2} \text{ad}_X \begin{pmatrix} 0 & X \\ 0 & 0 \end{pmatrix}, \frac{1}{2} \text{ad}_Y \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix} \right) \right] \\
= \left( \frac{1}{2} (\text{ad}_X \text{ad}_Y - \text{ad}_Y \text{ad}_X) \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix} \right) \\
= \left( \frac{1}{2} \text{ad}_{[X,Y]} + \frac{1}{2} [X,Y] - \frac{1}{2} [Y,X] \right) \\
= \left( \frac{1}{2} \text{ad}_{[X,Y]} + 0 \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix} \right) \quad \text{(since } \text{ad}_{[X,Y]} = 0) \\
= \varphi_2([X,Y])
\]

We let \( \varphi_2 : G \to UT_{n+1}(\mathbb{R}) \subseteq H \) be the (injective) Lie group homomorphism, whose corresponding differential is \( \varphi_{2\ast} \), so

\[
\varphi_2 : G \to H : g \mapsto \exp(\varphi_{2\ast}(\log(g))).
\]

**Theorem 6.1.** The map

\[
\varphi : \text{Aff}(G) = G \rtimes \text{Aut}(G) \to H : (g, \alpha) \mapsto \varphi_2(g)\varphi_1(\alpha)
\]

is an injective homomorphism of Lie groups.

**Proof.** In order to show that \( \varphi \) is a homomorphism, we consider any two elements \((x, \alpha), (b, \beta) \in G \rtimes \text{Aut}(G)\) and have to show that

\[
\varphi(a\alpha(b), \alpha\beta) = \varphi(a, \alpha)\varphi(b, \beta).
\]

Knowing already that \( \varphi_1 \) and \( \varphi_2 \) are homomorphisms, this is equivalent to showing that

\[
\varphi_1(\alpha)\varphi_2(b)\varphi_1(\alpha)^{-1} = \varphi_2(\alpha(b)).
\]

We have (with \( B = \log(b) \))

\[
\varphi_1(\alpha)\varphi_2(b)\varphi_1(\alpha)^{-1} = \begin{pmatrix} \alpha & 0 \\ 0 & 1 \end{pmatrix} \exp \left( \frac{1}{2} \text{ad}_B \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix} \right) \begin{pmatrix} \alpha & 0 \\ 0 & 1 \end{pmatrix}^{-1} \\
= \exp \left( \begin{pmatrix} \alpha & 0 \\ 0 & 1 \end{pmatrix} \left( \frac{1}{2} \text{ad}_B \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix} \right) \begin{pmatrix} \alpha & 0 \\ 0 & 1 \end{pmatrix}^{-1} \right) \\
= \exp \left( \frac{1}{2} \alpha \text{ad}_B \alpha^{-1} \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix} \right) \\
= \varphi_2(\alpha(b))
\]

where we used that \( \alpha \text{ad}_B \alpha^{-1} = \text{ad}_{\alpha(B)} \) and \( \alpha(B) = \log(\alpha(b)) \).

In order to see that \( \varphi \) is injective, it is enough to check that the intersection of the image of \( \varphi_1 \) and \( \varphi_2 \) contains only the identity element. To see this, it is enough to check that the first \( n \) entries of the last column of \( \varphi_2(g) \) are all equal to 0 if and only if \( g = 1 \), while for any \( \alpha \in \text{Aut}(G) \), we have that the first \( n \) entries of the last column of \( \varphi_1(\alpha) \) are always equal to 0.

**Remark.** This theorem is a special case of the more general result that for any nilpotent Lie group \( G \), it holds that \( \text{Aff}(G) \) is a linear group. Also, in the discrete case and in the more general case of polycyclic groups \( \Gamma \), it can be shown that \( \Gamma \rtimes \text{Aut}(\Gamma) \) is linear (see [3, 4, 76, 90] for results in this direction). The advantage of the above theorem is that it provides a very explicit representation \( \varphi \) of \( \text{Aff}(G) \) as a subgroup of \( \text{Aff}(\mathbb{R}^n) \), where \( n = \text{dim}(G) \). Moreover, it is easy to see that \( \varphi(G) \) acts simply transitively on \( G \). It follows that if \( \Gamma \subseteq \text{Aff}(G) \) is a subgroup acting properly discontinuously (resp. cocompactly) on \( G \) then \( \varphi(\Gamma) \) acts properly discontinuously (resp. cocompactly) on \( \mathbb{R}^n \).
At this point we want to remark that the 4-dimensional representation that was introduced on page \[11\] is in fact the representation \( \varphi \) of theorem \[6.1\]. We then further used this representation on page \[15\] to show that a certain almost-crystallographic group is torsion-free. This was in fact the technique which was used to classify all almost-Bieberbach groups in dimensions \( \leq 4 \) in \([15]\).

Of course having a matrix representation of \( \text{Aff}(G) \) for a 2-step nilpotent group is extremely useful to study maps on infra-nilmanifolds \( \Gamma \backslash G \), since by the generalized second Bieberbach Theorem, many maps are constructed by taking an element \((d, \delta) \in \text{Aff}(G)\) such that \((d, \delta)\Gamma(d, \delta)^{-1} \subseteq \Gamma\). The obtained matrix representation provides a very effective way to make these computations involved in this construction possible.

7 Expanding maps and Anosov diffeomorphisms on infra-nilmanifolds

As a first illustration of the use of infra-nilmanifolds, we will see in this section that they play a crucial role in the study of expanding maps and Anosov diffeomorphisms.

We first discuss the case of expanding maps.

**Definition 7.1.** Let \( M \) be a closed smooth Riemannian manifold. A \( C^1 \)-map \( f : M \to M \) is said to be an expanding map if there exist real constants \( C > 0 \) and \( \lambda > 1 \) such that

\[
\forall v \in TM : \forall n \in \mathbb{N} : \|Df^n(v)\| \geq C\lambda^n\|v\|.
\]

It can be shown that whether or not a map \( f \) is expanding does not depend on the choice of the Riemannian structure on \( M \).

There is a standard way of constructing expanding maps on infra-nilmanifolds.

**Definition 7.2.** Let \( M = \Gamma \backslash G \) be an infra-nilmanifold. An affine map \((d, \delta)\) of \( \Gamma \backslash G \) is said to be an expanding infra-nilmanifold endomorphism of \( \Gamma \backslash G \) if and only if for every eigenvalue \( \lambda \) of \( \delta \), it holds that \(|\lambda| > 1\).

The adjective “expanding” for these kind of affine maps is well chosen ([85]):

**Theorem 7.3.** An expanding infra-nilmanifold endomorphism of an infra-nilmanifold \( M \) is indeed an expanding map of that infra-nilmanifold.

Moreover, as a corollary to his famous theorem on groups of polynomial growth, M. Gromov showed that these kind of expanding maps are essentially (i.e. up to topological conjugacy) the only ones ([11], but see also [18]):

**Theorem 7.4.** Let \( f : M \to M \) be an expanding map on a closed smooth Riemannian manifold \( M \), then \( f \) is topologically conjugate to an expanding infra-nilmanifold endomorphism. I.e. there exists an infra-nilmanifold \( \Gamma \backslash G \), an expanding infra-nilmanifold endomorphism \((d, \delta)\) on \( \Gamma \backslash G \) and a homeomorphism \( h : M \to \Gamma \backslash G \), such that the following diagram commutes:

\[
\begin{array}{ccc}
M & \xrightarrow{f} & M \\
\downarrow{h} & & \downarrow{h} \\
\Gamma \backslash G & \xrightarrow{(d, \delta)} & \Gamma \backslash G
\end{array}
\]

This theorem shows that in order to understand the homeomorphism type of those manifolds which admit an expanding map it is enough to study the class of infra-nilmanifolds. We do however remark that F.T. Farrell and L.E. Jones constructed examples of expanding maps on exotic tori.
Definition 7.7. Let $M$ be a closed smooth Riemannian manifold. A $C^1$-diffeomorphism $f : M \to M$ is said to be an Anosov diffeomorphism if and only if there exists a $Df$-invariant continuous splitting of the tangent bundle $TM = E^u \oplus E^s$ and real constants $C > 0$ and $1 > \lambda > 0$ such that

$$\forall v \in E^u : \forall n \in \mathbb{N} : \|Df^n(v)\| \geq C\lambda^{-n}\|v\| \quad \text{and} \quad \forall v \in E^s : \forall n \in \mathbb{N} : \|Df^n(v)\| \leq \frac{1}{C}\lambda^n\|v\|.$$  

$E^u$ is called the unstable (or expanding) part and $E^s$ the stable (or contracting) part. Like in the case of expanding maps, the condition of being an Anosov diffeomorphism does not depend on the chosen Riemannian metric.

Also for Anosov diffeomorphisms there is an algebraic way of constructing them:

Definition 7.7. Let $M = \Gamma\backslash G$ be an infra-nilmanifold. An affine diffeomorphism $(d, \delta)$ of $\Gamma\backslash G$ is said to be a hyperbolic infra-nilmanifold automorphism of $\Gamma\backslash G$ if and only if for every eigenvalue $\lambda$ of $\delta$, it holds that $|\lambda| \neq 1$.

Remark. The fact that we require $(d, \delta)$ to be a diffeomorphism is equivalent to requiring that $\delta$ is invertible and $(d, \delta)\Gamma(d, \delta)^{-1} = \Gamma$. In case $(d, \delta)$ is a hyperbolic infra-nilmanifold automorphism of $\Gamma\backslash G$, then for some of the eigenvalues $\lambda$ of $\delta$ we will have that $|\lambda| > 1$, while for others we will have that $|\lambda| < 1$.

The following result shows that these hyperbolic infra-nilmanifold automorphisms give us really a way of constructing Anosov diffeomorphisms ([33] and [56]):
Theorem 7.8. A hyperbolic infra-nilmanifold automorphism of an infra-nilmanifold \( M \) is an Anosov diffeomorphism of that infra-nilmanifold.

The most famous example of such a hyperbolic infra-nilmanifold endomorphism is most probably Arnold’s cat map, which is the map induced on the 2-dimensional torus \( T^2 = \mathbb{Z}^2/\mathbb{R}^2 \) by the linear map \( \delta : \mathbb{R}^2 \to \mathbb{R}^2 \), where \( \delta \) is given by the matrix \[
\begin{pmatrix}
2 & 1 \\
1 & 1
\end{pmatrix}.
\]

There is a long standing conjecture ([34]) that in fact the hyperbolic infra-nilmanifold endomorphisms are essentially the only examples of Anosov diffeomorphisms:

Conjecture. Let \( f : M \to M \) be an Anosov diffeomorphism on a closed manifold \( M \), then \( f \) is topologically conjugate to a hyperbolic infra-nilmanifold automorphism.

Having this conjecture in mind it is natural to ask which infra-nilmanifolds \( M \) admit an Anosov diffeomorphism. It has been shown that, for infra-nilmanifolds, admitting an Anosov diffeomorphism is indeed equivalent to admitting a hyperbolic infra-nilmanifold automorphism ([18]).

The following lemma is quite easy to prove:

Lemma 7.9. An \( n \)-dimensional torus admits an Anosov diffeomorphism if and only if \( n \geq 2 \).

Proof. That \( n \) must be at least 2 is obvious, since the tangent bundle has to split in an expanding part \( E^u \) and a contracting part \( E^s \). To show that each \( n \)-dimensional torus, with \( n \geq 2 \), admits an Anosov diffeomorphism, it is enough to show that there exists a matrix \( \delta_n \in \text{GL}(\mathbb{Z}^n) \) with no eigenvalue of modulus 1. For \( n = 2 \), we can take \( \delta_2 \) to be the matrix of Arnold’s cat map given above. For \( n = 3 \) we can e.g. take \[
\delta_3 = \begin{pmatrix}
0 & 0 & 1 \\
1 & 0 & 0 \\
0 & 1 & 1
\end{pmatrix}.
\]
For higher values of \( n \), we can choose a block diagonal matrix with blocks \( \delta_2 \) and/or \( \delta_3 \) on the diagonal.

There has been a lot of research on the existence question of Anosov diffeomorphisms for nilmanifolds, especially in low dimensional cases or for nilmanifolds modeled on very special types of nilpotent Lie groups (See e.g. [9, 12, 16, 22, 27, 30, 32, 33, 51, 72, 73, 75, 74, 82]). The situation is much more difficult than in the case of expanding maps. As an illustration of how complicated the situation can be let us remark here that for \( G = H^R \times H^\mathbb{R} \), the direct product of the Heisenberg Lie group with itself, there are lattices \( N_1, N_2 \subseteq G \) such that the nilmanifold \( N_1/G \) admits an Anosov diffeomorphism, while \( N_2/G \) does not admit an Anosov diffeomorphism (see [9, 75]). So, in the case of Anosov diffeomorphisms there is no hope to find a result in the sense of Theorem 7.5.

As it is already quite complicated to study Anosov diffeomorphisms on nilmanifolds, not that much research has been done in the case of infra-nilmanifolds. Nevertheless there is a complete answer in the flat case, due to H. Porteous ([83]).

Theorem 7.10. Let \( \Gamma \subseteq \text{Isom}(\mathbb{R}^n) \) be a Bieberbach group with rational holonomy representation \( \varphi : F \to \text{GL}(\mathbb{Q}^n) \) (see page [7]) and let \( M = \Gamma \backslash \mathbb{R}^n \) be the corresponding flat manifold. Then we have:

\( M \) admits an Anosov diffeomorphism \( \Leftrightarrow \)

Each \( \mathbb{Q} \)-irreducible component of \( \varphi \) which appears with multiplicity one is reducible over \( \mathbb{R} \).

When we want to generalize the above theorem to the case of infra-nilmanifolds, we need to restrict ourselves to certain classes of them e.g. by considering only infra-nilmanifolds modeled on well understood nilpotent Lie groups \( G \). A successful generalization was obtained in case \( G \) is a free nilpotent group.
Definition 7.11. A Lie group $G$ is said to be a free nilpotent Lie group of class $c$ on $r$ generators in case its Lie algebra $\mathfrak{g}$ is a free nilpotent Lie algebra of class $c$ on $r$ generators. We denote the free nilpotent Lie group of class $c$ on $r$ generators by $G_{c,r}$.

We have a complete understanding of which nilmanifolds modeled on a free nilpotent Lie group $G_{c,r}$ do admit an Anosov diffeomorphism. It turns out that this only depends on the values of $c$ and $r$ and not on the specific lattice which was chosen to construct the nilmanifold ([12, 16, 27]).

Theorem 7.12. Let $N$ be a lattice in the free $c$-step nilpotent Lie group $G_{c,r}$ on $r$ generators. Then, the nilmanifold $N \backslash G_{c,r}$ admits an Anosov diffeomorphism if and only if $r > c$.

When $c = 1$, then $G_{1,r} = \mathbb{R}^r$ and the above theorem says that a torus $N \backslash \mathbb{R}^r$ (with $N \cong \mathbb{Z}^r$ a lattice in $\mathbb{R}^r$) admits an Anosov diffeomorphism if and only if $r > 1$. This is exactly the content of Lemma 7.9.

The Heisenberg group $H^\mathbb{R}$ is equal to $G_{2,2}$. The theorem above says that no nilmanifold (and hence also no infra-nilmanifold) modeled on the Heisenberg group admits an Anosov diffeomorphism. Actually, no infra-nilmanifold, which is not a flat manifold, in dimension $\leq 5$ admits an Anosov diffeomorphism (see e.g. [75]).

Based on [26] and [28], we were very recently able to prove in [21] a full generalization of Porteous’ result to the case of infra-nilmanifolds modeled on a free nilpotent Lie group.

Theorem 7.13. Let $\Gamma \subseteq G_{c,r} \rtimes F$ be an almost–Bieberbach group modeled on the free $c$-step nilpotent Lie group with $r$ generators and let $\varphi : F \to GL(\mathbb{Q}^r)$ be the associated abelianized rational holonomy representation (see page 24), then

The infra-nilmanifold $\Gamma \backslash G_{c,r}$ admits an Anosov diffeomorphism.

Every $\mathbb{Q}$–irreducible component of $\varphi$ that occurs with multiplicity $m$, splits in strictly more than $\frac{r}{m}$ components when viewed as a representation over $\mathbb{R}$.

Let us see what this condition says in case $c = 1$. In that case, we are dealing with flat manifolds and the abelianized rational holonomy representation is just the rational holonomy representation. The above theorem says that a $\mathbb{Q}$-irreducible component that appears with multiplicity $m = 1$ has to split in more than 1 component over $\mathbb{R}$ (so is reducible over $\mathbb{R}$), while a component that appears with multiplicity $m > 1$ has to split in more than $1/m < 1$ components, which means it does not need to split (so there are no conditions on these components). This is exactly the same result as what H. Porteous proved.

Apart from the above, no real general results on the existence of Anosov diffeomorphism on infra-nilmanifolds has been obtained and still a lot of research can be done in this direction.

In general one has the feeling that admitting an Anosov diffeomorphism is a much stronger condition than admitting an expanding map. However, recently J. Deré constructed an example of a nilmanifold admitting an Anosov diffeomorphims, but no expanding map ([29]).

8 Nielsen fixed point theory on infra–nilmanifolds

A second domain in which infra-nilmanifolds have been studied quite a lot is that of topological fixed point theory, in particular Nielsen fixed point theory.

In this section, we consider a compact manifold $X$ (more general spaces are allowed in Nielsen theory, but in our case it suffices to consider only compact manifolds).

Let $f : X \to X$ be a selfmap and let $\text{Fix}(f) = \{x \in X \mid f(x) = x\}$ denote the fixed point set of $f$. The goal of Nielsen fixed point theory is to study the minimal number of fixed points of all maps $f'$ which are homotopic to $f$.

A first indication on the number of fixed points is the Lefschetz number of $f$, denoted by $L(f)$, which is defined as the alternating sum of the traces of the linear maps induced by $f$ on the
homology spaces $H_*(X, \mathbb{Q})$ (which are finite dimensional rational vectorspaces):

$$L(f) = \sum_{i=0}^{\dim X} (-1)^i \text{Trace}(f_*: H_i(X, \mathbb{Q}) \to H_i(X, \mathbb{Q})).$$

The famous Lefschetz fixed point theorem states that in case $L(f) \neq 0$, then $f$ has at least one fixed point. Moreover, since $L(f') = L(f)$ for all maps $f'$ which are homotopic to $f$, the non-vanishing of $L(f)$ ensures that any map $f'$ homotopic to $f$ has at least one fixed point. Unfortunately, the Lefschetz number does not give any information on the exact number of fixed points. In fact, it is even possible that $L(f) = 0$, while any map homotopic to $f$ does have at least one fixed point.

There is a second number, called the Nielsen number of $f$, denoted by $N(f)$, also homotopy invariant and which contains more information than $L(f)$. Unfortunately, $N(f)$ is in general more difficult to compute than $L(f)$.

To define the Nielsen number of $f$, we divide Fix($f$) into fixed point classes. We say that two elements $x, y \in \text{Fix}(f)$ are Nielsen equivalent if there exists a path $\alpha : [0, 1] \to X$ with $\alpha(0) = x$, $\alpha(1) = y$ and such that $\alpha$ and $f \circ \alpha$ are path homotopic:

![Diagram](image)

It is easy to see that being Nielsen equivalent is an equivalence relation on the set Fix($f$). The equivalence classes are called the fixed point classes of $f$. To each fixed point class $F$, one associates an integer $I(f, F)$, the fixed point index of $F$. This is done in an axiomatic way (see [8, 55]) and is not so easily explained in a few words. To give some idea about the index, we can mention that when $X$ is a differentiable manifold, $f : X \to X$ is a differentiable function and $F = \{x_0\}$ is a fixed point class consisting of one isolated fixed point, then

$$I(f, F) = \text{sgn det}(1 - df_{x_0})$$

where $df_{x_0} : T_{x_0}X \to T_{x_0}X$ is the differential of $f$ at $x_0$, $1$ denotes the identity map of $T_{x_0}X$ and $\text{sgn}(r) = -1, 0$ or $1$ when $r < 0$, $r = 0$ and $r > 0$ respectively.

A fixed point class is said to be essential when the index $I(f, F) \neq 0$. The idea is that essential fixed point classes cannot vanish under a homotopy, while unessential ones might disappear (become empty). The Nielsen number of $f$ is defined as

$$N(f) = \text{the number of essential fixed point classes of } f = \#\{F \mid I(f, F) \neq 0\}.$$ 

It is obvious that $N(f) \leq \#\text{Fix}(f)$. Moreover, it can be shown that $N(f)$ is a homotopy invariant, from which it follows that $N(f) \leq \#\text{Fix}(f')$ for all maps $f'$ which are homotopic to $f$, so we have

$$N(f) \leq \min\{\#\text{Fix}(f') \mid f' \sim f\}.$$

So $N(f)$ is a lower bound for the number of fixed points of any map homotopic to $f$. It turns out that in many cases this lower bound is sharp, since there is the following theorem due to Wecken ([9]):

**Theorem 8.1.** Let $f : X \to X$ be a map on a closed manifold of dimension $\geq 3$. Then there exists a map $f'$ homotopic to $f$ such that $N(f) = \#\text{Fix}(f')$.

But although the circle, the torus and the Klein bottle, the only infra-nilmanifolds in dimensions $< 3$, are not included in the above theorem of Wecken, one can still show (since it is easy to determine all maps of these manifolds up to homotopy), that the result of Wecken’s theorem is still valid for these manifolds. So in case we are working with infra-nilmanifolds, the Nielsen number $N(f)$ is always a sharp lower bound for the number of fixed points of maps homotopic to $f$.

For maps on nilmanifolds, D. Anosov proved that the computation of $N(f)$ is as easy as the computation of the Lefschetz number ([1]):

30
Assume that we view a compact subgroup of \( C \) constructed as a quotient \( \Gamma \). Let \( \delta : G \to G \) be the unique extension of \( f \) to a homomorphism \( \delta : G \to G \) and let \( \delta : g \to g \) be the differential of \( \delta \), then

\[
L(f) = \det(1 - \delta) \text{ and } N(f) = |\det(1 - \delta)|.
\]

**Theorem 8.2.** Let \( G \) be a simply connected nilpotent Lie group and let \( N \) be a lattice of \( G \). Assume that \( f : N \setminus G \to N \setminus G \) is a map inducing a homomorphism \( f_* : N \to N \). Let \( \delta : G \to G \) be the unique extension of \( f_* \) to a homomorphism \( \delta : G \to G \) and let \( \delta : g \to g \) be the differential of \( \delta \), then

\[
L(f) = \det(1 - \delta) \text{ and } N(f) = |\det(1 - \delta)|.
\]

**Remark.** Note that \( \delta \) is a homomorphism such that \( f \) is homotopic to \((1, \delta)\) (see section 5). The reader who is familiar with Nomizu’s work ([78]) can see where the formula for the Lefschetz number comes from.

So for nilmanifolds, we always have that \( N(f) = |L(f)| \) and hence in this case the Lefschetz number does contain all the information we want.

**Definition 8.3.** Let \( f : X \to X \) be a selfmap of a closed manifold. We say that \( f \) satisfies the Anosov relation when \( N(f) = |L(f)| \).

We say that a manifold \( X \) satisfies the Anosov relation, in case the Anosov relations holds for any selfmap \( f \) of \( X \).

We have just seen that any nilmanifold satisfies the Anosov relation. This is no longer true for infra-nilmanifolds as we shall see below.

For maps on infra-nilmanifolds, it suffices to consider affine maps, since any map is homotopic to an affine map. By using the fact that any infra-nilmanifold is finitely covered by a nilmanifold S.W. Kim, J.B. Lee and K.B. Lee were able to prove a nice averaging formula to compute both the Lefschetz and the Nielsen number of a selfmap of an infra-nilmanifold (see [60] and [67]).

**Theorem 8.4.** Let \( G \) be a simply connected nilpotent Lie group. Assume that \( \Gamma \subseteq G \times C \) (with \( C \) a compact subgroup of \( \text{Aut}(G) \)) is an almost-Bieberbach group with holonomy group \( F \) (where we view \( F \subseteq C \subseteq \text{Aut}(G) \) as the subgroup of rotational parts of the elements of \( \Gamma \)). Assume that \( f = (d, \delta) \) is an affine selfmap of the infra-nilmanifold \( \Gamma \setminus G \), then

\[
L(f) = \frac{1}{|F|} \sum_{\alpha \in F} \det(1 - \alpha \delta) \quad \text{and} \quad N(f) = \frac{1}{|F|} \sum_{\alpha \in F} |\det(1 - \alpha \delta)|
\]

From this formula it is clear that the Anosov relation holds if and only if the terms \( \det(1 - \alpha \delta) \) are either all non-negative or all non-positive. We formulate this as a corollary:

**Corollary 8.5.** Let \( f = (d, \delta) \) be as in Theorem 8.4, then

\[
N(f) = |L(f)| \iff \forall \alpha, \beta \in F : \det(1 - \alpha \delta) \det(1 - \beta \delta) \geq 0
\]

Let us illustrate the averaging formula on the Klein bottle. Recall that the Klein bottle was constructed as a quotient \( \Gamma \setminus \mathbb{R}^2 \) where \( \Gamma \) is generated by

\[
a = \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}, \quad b = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix} \quad \text{and} \quad \alpha = \begin{pmatrix} -1 & 0 & 0 \\ 0 & 1 & \frac{1}{2} \\ 0 & 0 & 1 \end{pmatrix}
\]

where we represent elements \((a, A)\) of \( \text{Aff}(\mathbb{R}^2) \) as a \( 3 \times 3 \) matrix \( \begin{pmatrix} A & a \\ 0 & 1 \end{pmatrix} \) as in section 6.

Consider the affine map \((d, \delta) = \begin{pmatrix} 2 & 0 & -\frac{1}{2} \\ 0 & 3 & 0 \\ 0 & 0 & 1 \end{pmatrix}\) (also seen as a \( 3 \times 3 \)-matrix). We easily compute that

\[
(d, \delta)a(d, \delta)^{-1} = a^2, \quad (d, \delta)b(d, \delta)^{-1} = b^3 \quad \text{and} \quad (d, \delta)\alpha(d, \delta)^{-1} = a^{-1}b\alpha.
\]
This implies that \((d, \delta)\Gamma(d, \delta)^{-1} \subseteq \Gamma\) and so \((d, \delta)\) induces a map \(f = (d, \delta)\) on the Klein bottle \(\Gamma \setminus \mathbb{R}^2\). To compute \(L(f)\) and \(N(f)\) note that \(\delta^* = \delta\) and that

\[
F = \left\{ \alpha_1 = \alpha_1^*, I_2, \alpha_2 = \alpha_2^* = \left( \begin{array}{cc} -1 & 0 \\ 0 & 1 \end{array} \right) \right\}
\]

and use this in the following computation involving the averaging formulas of Theorem 8.4

\[
L(f) = \frac{1}{2} \left[ \det \left( I_2 - \left( \begin{array}{cc} 2 & 0 \\ 0 & 3 \end{array} \right) \right) + \det \left( I_2 - \alpha_2 \left( \begin{array}{cc} 2 & 0 \\ 0 & 3 \end{array} \right) \right) \right] = \frac{1}{2} \left[ \det \left( I_2 - \left( \begin{array}{cc} 2 & 0 \\ 0 & 3 \end{array} \right) \right) + \det \left( I_2 - \left( \begin{array}{cc} -2 & 0 \\ 0 & 3 \end{array} \right) \right) \right] = \frac{1}{2} \left[ \det \left( \begin{array}{cc} -1 & 0 \\ 0 & -2 \end{array} \right) + \det \left( \begin{array}{cc} 3 & 0 \\ 0 & -2 \end{array} \right) \right] = \frac{1}{2} [2 + (-6)] = -2
\]

\[
N(f) = \frac{1}{2} |2| + | -6 | = 4.
\]

One clearly sees that this \(f\) does not satisfy the Anosov relation.

Let us conclude this section by discussing some situations for which the Anosov relation does hold. We can do this by looking for conditions on the map or on the manifold.

Let us first use the averaging formula to give a a new and short proof for the Anosov relation in case of homotopically periodic maps on infra-nilmanifolds. A map \(f : X \rightarrow X\) is said to be homotopically periodic if there exists a positive integer \(k\) such that \(f^k\) is homotopic to the identity. The following theorem was first proved by S. Kwasik and K.B. Lee in 1988 ([61]).

**Theorem 8.6.** Let \(f : X \rightarrow X\) be a homotopically periodic map on an infra-nilmanifold \(X\), then \(N(f) = L(f)\).

**Proof.** Let \(X = \Gamma \setminus G\) where \(\Gamma\) is an almost-Bieberbach group modeled on a nilpotent Lie group \(G\). We can assume that \(f\) is homotopic to an affine map \((d, \delta)\), where \((d, \delta) \in \text{Aff}(G)\). The map \((d, \delta)\) satisfies

\[
\forall \gamma \in \Gamma : f_*(\gamma)(d, \delta) = (d, \delta)\gamma.
\]

Let \(k\) be the positive integer for which \(f^k\) is homotopic to the identity, from which it follows that \(\delta^k = 1_G\). It follows that \(\delta\) is invertible, and so \(\forall \gamma = (a, \alpha) \in \Gamma : f_*(\gamma) = (d, \delta)\gamma(d, \delta)^{-1}\). From this, it follows that \(F = \delta F \delta^{-1}\). Now, let \(\alpha \in F\), then \(\exists \alpha' \in F:\)

\[
(\alpha\delta^k|F|) = (a'\delta^k|F|) = a'^{|F|} = 1.
\]

So, any \(\alpha\delta^k\) is a matrix of finite order, having only roots of unity \(\lambda\) as eigenvalues. Hence

\[
\det(I_n - \alpha\delta^k) = \prod_{i=1}^{n} (1 - \lambda_i)\quad \text{with} \quad |\lambda_i| = 1.
\]

We claim that this determinant is always \(\geq 0\). Indeed, we have the following possibilities for \(\lambda_i:\)

- \(\lambda_i = 1\), this gives a contribution \(1 - 1 = 0\) to the product (so when \(\alpha \delta^k\) has 1 as an eigenvalue, the determinant \(\det(I_n - \alpha\delta^k) = 0\)).
- \(\lambda_i = -1\), this gives a contribution \(1 - (-1) = 2 > 0\) to the product.
- \(\lambda_i \in \mathbb{C} \setminus \mathbb{R}\), then also its complex conjugate \(\overline{\lambda_i}\) is an eigenvalue of \(\alpha\delta^k\). The contribution of the pair \(\{\lambda_i, \overline{\lambda_i}\}\) to the product is \((1 - \lambda_i)(1 - \overline{\lambda_i}) = 2 - 2\text{Re}(\lambda_i) > 0\).

It follows that for \(\alpha \in F\), \(\det(I_n - \alpha\delta^k) \geq 0\), from which we can deduce that \(L(f) = N(f)\). \(\square\)

Analogously, one can prove the following result on expanding maps which was first obtained in [20].
Theorem 8.7. Let $f$ be an expanding map on an infra-nilmanifold $X$, then

$$N(f) = L(f) \iff X \text{ is orientable.}$$

In case $X$ is not orientable then $N(f) \neq |L(f)|$.

Remark. An infra-nilmanifold $X = \Gamma \backslash G$ is orientable if and only if $\forall \alpha \in F : \det(\alpha) = 1$.

The previous two results were about the Anosov relation for specific types of maps. Now we list some results concerning specific manifolds. The first theorem was proved in [20]:

Theorem 8.8. Let $\Gamma \backslash G$ be an infra-nilmanifold with an odd order holonomy group $F$, then $N(f) = |L(f)|$ for any selfmap $f$ of $\Gamma \backslash G$.

Note that any infra-nilmanifold with an odd order holonomy group is orientable, so this is compatible with the previous result.

As a final illustration, we want to mention a result on infra-nilmanifolds with a holonomy group of even order. In any dimension $n \geq 2$ there exist flat manifolds with a holonomy group isomorphic to $\mathbb{Z}_2^{n-1}$ and there are no flat manifolds with a holonomy group isomorphic to $\mathbb{Z}_2^k$ with $k \geq n$. The number of such manifolds grows exponentially with the dimension $n$ ([77]). In dimension 2, there is the non-orientable Klein bottle, in dimension 3, there is one orientable flat manifold with holonomy group $\mathbb{Z}_2^3$ and two non-orientable ones. The orientable one is known as the Hantsche-Wendt manifold. Therefore, one refers to a $n$-dimensional flat manifold with holonomy group $\mathbb{Z}_2^{n-1}$ as a generalized Hantsche-Wendt manifold. For these manifolds, we have proven in [19] the following theorem:

Theorem 8.9. Let $X$ be a generalized Hantsche-Wendt manifold, then

- $N(f) = |L(f)|$ for all selfmaps $f$ of $X$ in case $X$ is orientable.
- In case $X$ is non-orientable, there exists a selfmap $f$ of $X$ such that $N(f) \neq |L(f)|$ (e.g. one can take $f$ to be an expanding map).

Of course, many more results about Nielsen fixed point theory for infra-nilmanifolds have been proved and the above theorems are mainly meant to illustrate what kind of results can be obtained.

Besides fixed point theory, one has also studied (and is still studying) periodic points and coincidences.

Definition 8.10. Let $f : X \to X$ and $g : X \to Y$ be a maps.

A periodic point of $f$ is a point $x \in X$ such that $f^n(x) = x$ for some positive integer $n$.

A pair of points $(x, y)$ with $x, y \in X$ is called a coincidence pair of $g$ if $g(x) = g(y)$.

In literature one can find quite some results on Nielsen periodic point theory ([17, 16, 48, 49, 52, 51, 53, 54, 41, 61]) and Nielsen coincidence theory ([25, 37, 38, 39, 43, 44, 40, 50, 58, 57, 93] for maps on/between infra-nilmanifolds.

References

[1] Anosov, D. The Nielsen numbers of maps of nil-manifolds. Uspekhi. Mat. Nauk, 1985, 40 (2), pp. 133–134. English transl.: Russian Math. Surveys, 40 (no. 4), 1985, pp. 149–150.

[2] Auslander, L. Bieberbach’s Theorem on Space Groups and Discrete Uniform Subgroups of Lie Groups. Ann. of Math. (2), 1960, 71 (3), pp. 579–590.

[3] Auslander, L. and Baumslag, G. Automorphism groups of finitely generated nilpotent groups. Bull. Amer. Math. Soc., 1967, 73 716–717.

[4] Baumslag, G. Automorphism groups of nilpotent groups. Amer. J. Math., 1969, 91 1003–1011.
[5] Bieberbach, L. Über die Bewegungsgruppen der Euklidischen Räume I. Math. Ann., 1911, 70 3, pp. 297–336.

[6] Bieberbach, L. Über die Bewegungsgruppen der Euklidischen Räume II. Math. Ann., 1912, 72 3, pp. 400–412.

[7] Brown, K. S. Cohomology of groups., volume 87 of Grad. Texts in Math. Springer-Verlag New York Inc., 1982.

[8] Brown, R. F. The Lefschetz fixed point theorem. Scott, Foresman and Company, 1971.

[9] Cassidy, C., Kennedy, N., and Scevenels, D. Hyperbolic automorphisms for groups in T(4,2). Contemporary Math. A. M. S., 2000, 262, pp. 171–175.

[10] Charlap, L. S. Bieberbach Groups and Flat Manifolds. Universitext. Springer-Verlag New York Inc., 1986.

[11] Cornulier, Y. Gradings on Lie algebras, systolic growth, and cohopfian properties of nilpotent groups. Preprint, 2014, [arXiv:1403.5295].

[12] Dani, S. Nilmanifolds with Anosov Automorphisms. J. London Math. Soc. (2), 1978, 18, pp. 553–559.

[13] Dani, S. G. and Mainkar, M. G. Anosov automorphisms on compact nilmanifolds associated with graphs. Trans. Amer. Math. Soc., 2005, 357 6, 2235–2251.

[14] Dekimpe, K. The construction of affine structures on virtually nilpotent groups. Manuscripta Math., 1995, 87 pp. 71–88.

[15] Dekimpe, K. Almost-Bieberbach Groups: Affine and Polynomial Structures, volume 1639 of Lect. Notes in Math. Springer–Verlag, 1996.

[16] Dekimpe, K. Hyperbolic automorphisms and Anosov diffeomorphisms on nilmanifolds. Trans. Amer. Math. Soc., 2001, 353 7, pp. 2859–2877.

[17] Dekimpe, K. What is ... an infra-nilmanifold endomorphism? Notices Amer. Math. Soc., 2011, 58 5, 688–689.

[18] Dekimpe, K. What an infra-nilmanifold endomorphism really should be .... Topol. Methods Nonlinear Anal., 2012, 40 1, 111–136.

[19] Dekimpe, K., De Rock, B., and Malfait, W. The Anosov theorem for flat generalized Hantsche-Wendt manifolds. J. Geom. Phys., 2004, 52, pp. 174–185.

[20] Dekimpe, K., De Rock, B., and Malfait, W. The Anosov relation for Nielsen numbers of maps of infra-nilmanifolds. Monatschete für Mathematik, 2007, 150, pp. 1–10.

[21] Dekimpe, K. and Deré, J. Existence of Anosov diffeomorphisms on infra-nilmanifolds modeled on free nilpotent Lie groups. Topological Methods in Nonlinear Analysis, 2016, 46 1, 165–190.

[22] Dekimpe, K. and Deschamps, S. Anosov diffeomorphisms on a class of 2-step nilmanifolds. Glasgow. Math. J., 2003, 45 pp. 2269–280.

[23] Dekimpe, K. and Eick, B. Aclib - Almost Crystallographic Groups (Version 1.2) - A GAP package. [http://www.gap-system.org/Packages/aclib.html](http://www.gap-system.org/Packages/aclib.html), 2012.

[24] Dekimpe, K., Igodt, P., and Malfait, W. There are only finitely many infra-nilmanifolds under each nilmanifold: a new proof. Indagationes Math., 1994, 5 (3), pp. 259–266.
Dekimpe, K. and Penninckx, P. Coincidence theory for infra-nilmanifolds. Topology Appl., 2010, 157 10-11, 1815–1832.

Dekimpe, K. and Verheyen, K. Anosov diffeomorphisms on infra-nilmanifolds modeled on a free 2-step nilpotent Lie group. Groups, Geometry and Dynamics, 2009, 3 4, pp. 555–578.

Dekimpe, K. and Verheyen, K. Anosov diffeomorphisms on nilmanifolds modeled on a free nilpotent Lie group. Dynamical Systems – an international journal, 2009, 24 1, pp. 117–121.

Dekimpe, K. and Verheyen, K. Constructing infra-nilmanifolds admitting an Anosov diffeomorphism. Adv. Math., 2011, 228 6, 3300–3319.

Deré, J. Gradsings on Lie algebras with applications to infra-nilmanifolds. 2014, arXiv:1410.3713.

Dixmier, J. and Lister, W. Derivations of nilpotent Lie algebras. Proc. Am. Math. Soc., 1957, 8 155–158.

Eick, B. and Nickel, W. Polycyclic (Version 2.11) - A GAP package. (http://www.gap-system.org/Packages/polycyclic.html), 2013.

Epstein, D. and Shub, M. Expanding endomorphisms of flat manifolds. Topology, 1968, 7, pp. 139–141.

Farrell, F. T. and Jones, L. E. Examples of expanding endomorphisms on exotic tori. Invent. Math., 1978, 45 2, 175–179.

Franks, J. Anosov diffeomorphisms. Global Analysis: Proceedings of the Symposia in Pure Mathematics, 1970, 14, pp. 61–93.

Fröbenius, G. Über die unzerlegbaren diskreten Bewegungsgruppen. Sitzungsber. Akad. Wiss. Berlin, 1911, 29, pp. 654–665.

The GAP Group. GAP – Groups, Algorithms, and Programming, Version 4.8.2, 2016.

Gonçalves, D. L. Coincidence Reidemeister classes on nilmanifolds and nilpotent fibrations. Topology Appl., 1998, 83 3, 169–186.

Gonçalves, D. L. and Wong, P. N.-S. Nilmanifolds are Jiang-type spaces for coincidences. Forum Math., 2001, 13 1, 133–141.

Gonçalves, D. L. and Wong, P. N.-S. Homogeneous spaces in coincidence theory II. Forum Math., 2005, 17 2, 297–313.

Gorbatevich, V. V. On algebraic Anosov diffeomorphisms on nilmanifolds. Sibirsk. Mat. Zh., 2004, 45 5, 995–1021.

Gromov, M. Groups of polynomial growth and expanding maps. Institut des Hautes Études Scientifiques, 1981, 53, pp. 53–73.

Ha, K. Y., Kim, H. J., and Lee, J. B. Eventually periodic points of infra-nil endomorphisms. Fixed Point Theory Appl., 2010, pages Art. ID 721736, 15.

Ha, K. Y., Lee, J. B., and Penninckx, P. Anosov theorem for coincidences on special solv-manifolds of type (R). Proc. Amer. Math. Soc., 2011, 139 6, 2239–2248.

Ha, K. Y., Lee, J. B., and Penninckx, P. Formulas for the Reidemeister, Lefschetz and Nielsen coincidence number of maps between infra-nilmanifolds. Fixed Point Theory Appl., 2012, pages 2012:39, 23.
[45] Hall, P. *Nilpotent Groups*. Queen Mary College Maths. Notes, London, 1969.

[46] Heath, P. and Keppelmann, E. *Fibre techniques in Nielsen periodic point theory on nil and solvmanifolds I*. Topology and its Applications, 1997, 76 pp. 217–247.

[47] Heath, P. R. *A survey of Nielsen periodic point theory (fixed n)*. Nielsen theory and Reidemeister torsion (Warsaw, 1996), 1999, 49 159–188.

[48] Heath, P. R. and Keppelmann, E. C. *Fibre techniques in Nielsen periodic point theory on nil and solvmanifolds. II*. Topology Appl., 2000, 106 2, 149–167.

[49] Heath, P. R. and Keppelmann, E. C. *Model solvmanifolds for Lefschetz and Nielsen theories*. Quaest. Math., 2002, 25 4, pp. 483–501.

[50] Jezierski, J. *The Nielsen number product formula for coincidences*. Fund. Math., 1990, 134 3, 183–212.

[51] Jezierski, J. *Wecken’s theorem for periodic points in dimension at least 3*. Topology Appl., 2006, 153 11, 1825–1837.

[52] Jezierski, J., Kędra, J., and Marzantowicz. *Homotopy minimal periods for NR-solvmanifold maps*. 2004. To appear in Topology and Applications.

[53] Jezierski, J. and Marzantowicz, W. *Homotopy minimal periods for nilmanifold maps*. Mathematica Zeitschrift, 2002, 239 2, pp.381–414.

[54] Jezierski, J. and Marzantowicz, W. *Homotopy Methods in Topological Fixed and Periodic Point Theory*, volume 3 of *Topological Fixed Point Theory and Its Applications*. Springer, 2006.

[55] Jiang, B. *Estimation of the Nielsen numbers*. Chinese Math. – Acta, 1964, 5 330–339.

[56] Kargapolov, M. and Merzljakov, J. *Fundamentals of the Theory of Groups*, volume 62 of *Grad. Texts in Math*. Springer–Verlag, 1979.

[57] Khukhro, E. I. *Nilpotent groups and their automorphisms*, volume 8 of *de Gruyter Expositions in Mathematics*. Walter de Gruyter & Co., Berlin, 1993.

[58] Kim, S. W. and Lee, J. B. *Anosov theorem for coincidences on nilmanifolds*. Fund. Math., 2005, 185 3, 247–259.

[59] Kim, S. W. and Lee, J. B. *Averaging formula for Nielsen coincidence numbers*. Nagoya Math. J., 2007, 186 69–93.

[60] Kim, S. W., Lee, J. B., and Lee, K. B. *Averaging formula for Nielsen numbers*. Nagoya Math. J., 2005, 178, pp. 37–53.

[61] Kwasik, S. and Lee, K. B. *The Nielsen numbers of homotopically periodic maps of infranilmanifolds*. J. London Math. Soc. (2), 1988, 38, pp. 544–554.

[62] Lauret, J. *Examples of Anosov diffeomorphisms*. J. Algebra, 2003, 262 1, 201–209.

[63] Lauret, J. *Rational forms of nilpotent Lie algebras and Anosov diffeomorphisms*. Monatsh. Math., 2008, 155 1, 15–30.

[64] Lauret, J. and Will, C. E. *On Anosov automorphisms of nilmanifolds*. J. Pure Appl. Algebra, 2008, 212 7, 1747–1755.

[65] Lauret, J. and Will, C. E. *Nilmanifolds of dimension ≤ 8 admitting Anosov diffeomorphisms*. Trans. Amer. Math. Soc., 2009, 361 5, 2377–2395.
[66] Lee, H. and Lee, K. B. Expanding maps on 2-step infra-nilmanifolds. Topology Appl., 2002, 117 (1), pp. 45–58.

[67] Lee, J. B. and Lee, K. B. Lefschetz numbers for continuous maps and periods for expanding maps on infra-nilmanifolds. J. Geom. Phys., 2006, 56 10, pp. 2011–2023.

[68] Lee, J. B. and Lee, K. B. Averaging formula for Nielsen numbers of maps on infra-solvable manifolds of type (R). Nagoya Math. J., 2009, 196 117–134.

[69] Lee, K. B. There are only finitely many infra-nilmanifolds under each nilmanifold. Quart. J. Math. Oxford Ser. (2), 1988, 39, pp. 61–66.

[70] Lee, K. B. Maps on infra-nilmanifolds. Pacific J. Math., 1995, 168, 1, pp. 157–166.

[71] Lee, K. B. and Raymond, F. Rigidity of almost crystallographic groups. Contemp. Math., 1985, 44, pp. 73–78.

[72] Mainkar, M. G. Anosov automorphisms on certain classes of nilmanifolds. Glasg. Math. J., 2006, 48 1, 161–170.

[73] Mainkar, M. G. Anosov Lie algebras and algebraic units in number fields. Monatsh. Math., 2012, 165 1, 79–90.

[74] Mainkar, M. G. and Will, C. E. Examples of Anosov Lie algebras. Discrete Contin. Dyn. Syst., 2007, 18 1, 39–52.

[75] Malfait, W. Anosov diffeomorphisms on nilmanifolds of dimension at most six. Geometriae Dedicata, 2000, 79 (3), 291–298.

[76] Merzljakov, J. I. Integer representation of the holomorphs of polycyclic groups. Algebra i Logika, 1970, 9 539–558.

[77] Miatello, R. and Rossetti, J. Isospectral Hantzsche-Wendt manifolds. J. Reine Angew. Math., 1999, 515 pp. 1–23.

[78] Nomizu, K. On the cohomology of compact homogeneous spaces of nilpotent Lie groups. Ann. of Math., 1954, 59, pp. 531–538.

[79] Onishchik, A. and Vinberg, E. Lie Groups and Lie Algebras I, volume 20 of Encyclopedia of Mathematics. Springer Verlag, Berlin Heidelberg New York, 1993.

[80] Onishchik, A. and Vinberg, E. Lie Groups and Lie Algebras III, volume 41 of Encyclopedia of Mathematics. Springer Verlag, Berlin Heidelberg New York, 1994.

[81] Onishchik, A. and Vinberg, E. Lie Groups and Lie Algebras II, volume 21 of Encyclopedia of Mathematics. Springer Verlag, Berlin Heidelberg New York, 2000.

[82] Payne, T. L. Anosov automorphisms of nilpotent Lie algebras. J. Mod. Dyn., 2009, 3 1, 121–158.

[83] Porteous, H. L. Anosov diffeomorphisms of flat manifolds. Topology, 1972, 11, pp. 307–315.

[84] Segal, D. Polycyclic Groups. Cambridge University Press, 1983.

[85] Shub, M. Endomorphisms of compact differentiable manifolds. Amer. J. Math., 1969, 91, pp. 175–199.

[86] Smale, S. Differentiable dynamical systems. Bull. Amer. Math. Soc., 1967, 73, pp. 747–817.

[87] Szczepański, A. Geometry of crystallographic groups, volume 4 of Algebra and Discrete Mathematics. World Scientific Publishing Co. Pte. Ltd., Hackensack, NJ, 2012.

37
[88] Vinberg, E. B. *Linear Representations of Groups*. Basler Lehrbücher. Birkhäuser Verlag, Basel, 1989.

[89] Wecken, F. *Fixpunktklassen. III. Mindestzahlen von Fixpunkten*. Math. Ann., 1942, 118 pp. 544–577.

[90] Wehrfritz, B. A. F. *On the holomorphs of soluble groups of finite rank*. J. Pure Appl. Algebra, 1974, 4 55–69.

[91] Whitehead, G. *Elements of Homotopy Theory*, volume 61 of *Graduate Texts in Math*. Springer-Verlag, 1978.

[92] Wolf, J. A. *Spaces of constant curvature*. Publish or Perish, Inc. Berkeley, 1977.

[93] Wong, P. *Coincidence theory for spaces which fiber over a nilmanifold*. Fixed Point Theory Appl., 2004, 2, 89–95.

[94] Zassenhaus, H. *Über einen Algorithmus zur Bestimmung der Raumgruppen*. Commentarii Mathematici Helvetici, 1948, 21, pp. 117–141.