Diurnal Variability of Surface Temperature over Lakes: Case Study for Lake Huron

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Abstract: The significance of the diurnal variability of Lake Surface Temperature (LST) has been recognized; yet, its magnitude in terms of spatial and temporal variability is not well known. Attempts have been made to derive such information from satellites at a high spatial resolution; however, most have been made from polar orbiting satellites that sample only twice per day. We have developed an approach to derive such information from geostationary satellites at an hourly time scale and at a spatial resolution of about 5 km. The approach to derive LST uses the Radiative Transfer for TIROS Operational Vertical Sounder (TOVS) (RTTOV) model driven by the Modern-Era Retrospective analysis for Research and Applications (MERRA)-2 information. The methodology has been implemented over Lake Huron for about six years. We present the results of the evaluation against various independent satellite products and demonstrate that there is a strong diurnal variability in the skin temperature over the lake and that the lowest and highest values, as derived twice per day from polar orbiting satellites, may not represent the magnitude of the Diurnal Temperature Range (DTR).

Keywords: lake temperature from satellites; diurnal cycle of lake temperature; diurnal temperature range (DTR) for lakes

1. Introduction

Information on Lake Surface Temperature (LST) is important for many applications, such as estimating the evaporation from lakes. For example, evaporation accounts for 95% of the water budget in Lake Tanganyika, East Africa, (Spigel and Coulter [1]; Verburg and Hecky [2]); evaporative water loss has also been reported for the Great Lakes (Gronewold [3]). It is also important in modulating the geographical variability in evaporative demand in the surrounding areas of lakes (Kiefer et al. [4]). Another interesting application is the ability to detect regions of upwelling over lakes. Steissberg et al. [5] used images from the Advanced Spaceborne Thermal Emission and Reflection Radiometer (ASTER), the Enhanced Thematic Mapper (ETM+), and the Moderate Resolution Imaging Spectroradiometer (MODIS) to observe the spatial variability of upwelling events at Lake Tahoe. An upwelling is a process whereby water from below the surface is transported to the surface, which is important for sustaining biological activity. Information on LST is also used to formulate the lake water balance and for the calibration of satellite-measured LST against in situ measurements (Hook et al. 2007 [6], Thome [7]).

The estimation of the evaporation from lakes is quite challenging. Depending on the methodology used, it requires multiple variables including the net radiation, heat storage, air temperature, water surface “skin” temperature, humidity, wind speed, and stability of the atmosphere. Information on the Lake Surface Temperature (LST) and on the atmosphere above are not readily available. The flux of water vapor from a water surface is largely governed by the magnitude of the vapor pressure gradient between the water
surface and the overlying air. This gradient is determined by the surface temperature of the water, the absolute humidity in the atmosphere (e.g., vapor pressure), and the amount of turbulent mixing of air. Since the surface skin temperature is not readily available, short-cuts have been taken to facilitate such computations from wind speed, temperature, air pressure, and relative humidity. For instance, the aerodynamic method of Chou et al. [8] for oceans uses air temperature for the estimation of the saturation vapor pressure at the water surface. However, the air temperature was found to be lower by 1 to 2 °C than the surface water temperature, and therefore some prefer to use water temperatures at a 1-m depth to estimate the saturation vapor pressure at the water surface. Information on the LST can be instrumental for improving this shortcoming.

Most of the satellites that are used for estimating LST are in polar orbits. Remote sensing of the temperature is based on recording the emitted radiation from the earth surface in the spectral domain of 8–14 µm. In the case of inland water bodies, the most common approach is the split-window technique where the difference between the two adjacent thermal channels (10.5–11.5 µm, 11.5–12.5 µm) is taken as a measure of atmospheric attenuation in order to derive the Surface Temperature (ST) (Becker and Li [9]; Sobrino et al. [10]; Wan and Dozier [11]). Typically, ASTER data are acquired twice every 16 days, which is similar to Landsat, for which data at night are only saved by special request. MODIS data are acquired twice daily, but not at optimal times to observe the Diurnal Temperature Range (DTR). The hourly observation from geostationary satellites can meet the need for estimating the DTR (Sun et al. [12]). This is important since this parameter is used to address various scientific questions such as the impact of global warming on the DTR, as seen in the asymmetric trends of the daily maximum and minimum temperature, as discussed in Easterling et al. [13], Karl and Karoly [14], and Karl et al. [15–18]. Changes in DTR have many possible causes (cloud cover, aerosols, water vapor, or green-house gases). It was shown that lakes’ summer surface water temperatures rose rapidly (global mean of 0.34 °C/decade) between 1985 and 2009 (O’Reilly et al. [19]). There is evidence that global warming does have an impact on lake temperatures (Coats et al. [20]). Several studies have investigated the impacts of climate change on the lake surface water temperature (Livingstone [21]; Magee et al. [22]) and provided evidence that lakes are warming on a global scale (Schneider and Hook [23]). Woolway et al. [24] analyzed observational data from eight European lakes and investigated the changes in the annual minimum surface water temperature; they noted a substantial increase in the minimum lake surface temperature at an average rate of +0.35 °C decade⁻¹.

The lack of long-term in-situ data at a high temporal frequency is the main obstacle in identifying long-term trends. In this context, data from remote sensing as a substitute to in-situ data could play a key role in limnologic studies. The purpose of our study is to demonstrate that it is now possible to assess the temporal and spatial variability of LST in a systematic way, which is an important contribution for advancing research related to lakes. In Section 2, we will describe data used in this study; Section 3 will provide results and a summary, and discussion will be provided in Section 4.

2. Data Used in Current Study

In the current study, LST as available from: (a) https://largelakes.jpl.nasa.gov/, accessed on 18 December 2020; (b) as estimated from the Geostationary Operational Environmental Satellite East (GOES-E) at the University of Maryland (UMD); and (c) as derived from MODIS (Wan, [25]) will be compared at the Lake Huron JPL site (JPL500: 44.757° N, 82.34° W).

2.1. LST As Provided by JPL

Several estimates of LST are provided from satellite observations at https://largelakes.jpl.nasa.gov/ (accessed on 18 December 2020) for 169 of the world’s largest lakes. Specifically, the following satellite systems have been used: MODIS/Terra, MODIS/Aqua, AASTR, and the Advanced Very High Resolution Radiometer (AVHRR) PathFinder data
The methodology used to obtain the surface temperatures is given in Schneider and Hook [23]. For Lake Huron, the observations are taken at a site centered at JPL500 (44.757° N, 82.34° W). The data selection criteria used for the above data are: cloud free cases of good quality and an instrument viewing angle between −50°~+50°. The data used in the comparison with the JPL products are from 2004 to 2008 only.

2.2. MODIS Daily Products

We also used the MOD11C1 (Terra) version 6 LST as described in Wan [25]. This product provides daytime and nighttime Land Surface Temperature and Emissivity values in a 0.05 degree latitude/longitude Climate Modeling Grid (CMG) (5600 m at the equator). A CMG granule follows a geographic grid, having 7200 columns and 3600 rows, which represent the entire globe. Each MOD11C1 product consists of the following information for daytime and nighttime: LST, quality control assessments, observation times, view zenith angles, number of clear-sky observations, and emissivity from bands 20, 22, 23, 29, 31, and 32 (bands 31 and 32 are daytime only), along with the percentage of land in the grid. As such, it can be used for estimating a proxy DTR. A detailed description of the product and downloading links can be found at: https://lpdaac.usgs.gov/products/mod11c1v006/ (accessed on 18 December 2020).

2.3. UMD GOES-E LST

The Geostationary Operational Environment Satellite (GOES) systems (East and West) provide continuous, timely, and high-quality observations over much of the Western Hemisphere. Since the GOES data archive extends well over three decades, its applications for long-term climate change studies are being used extensively. The UMD GOES-E LST product is based on a single channel retrieval methodology (Pinker et al. [26]) using the Radiative Transfer for TOVS (RTTOV) model v11.2 adjusted for the GEO-characteristics with atmospheric profiles data from the Modern-Era Retrospective analysis for Research and Applications (MERRA) - 2 reanalysis four times a day (00, 06, 12, 18 h) (Gelaro et al. [27]) and the CAMEL emissivity information (Borbas et al. [28]). The GOES product provides hourly LST from 2004 to 2009 at a 0.05°×0.05° spatial resolution. This is important for many applications; for instance, most satellites estimate DTR from polar orbiting satellites that do not observe at optimal times in order to estimate DTR. Moreover, an evaluation against the “true” DTR as estimated from GOES observations will provide an opportunity to estimate bias in products based on the polar orbiters.

2.4. Spatial and Temporal Matching

To accomplish spatial matching, we use the “nearest point” concept with respect to the JPL500 location. If the number of GOES-E nearest points is more than 2, the mean value of these points is calculated and weighted with their latitude and longitude. The time difference between the JPL LST and those from the GOES-E nearest points must be under ±15 min.

3. Results

In Figure 1, we compare the JPL products with the GOES-E UMD estimates. It shows the matched instantaneous cases for a period of five years (2004–2008). In general, there seems to be a good agreement between the various products, with few outliers for MODIS Terra and Aqua (red and blue dots). The possible reason for the outliers may be related to cloud detection issues for the illustrated cases.

A comparison was also made between the GOES-E UMD product and the AVHRR PathFinder estimates (Figure 2). The PathFinder record is of interest since it spans climatic time scales. Few outliers in the PathFinder data are evident, yet the patterns of annual and interannual variations from both data sources follow each other closely with a correlation coefficient of 0.98. Overall, the AVHRR PathFinder results systematically
overestimate the GOES-E values. The mean difference between them is about 1.34 °C (Table 1). This comparison will allow one to assess possible biases in the long-term AVHRR PathFinder data.

![Figure 1](image_url)

**Figure 1.** Instantaneous LST as derived from the JPL archive for MODIS/Terra, MODIS/Aqua, AATSR, and from GOES-E UMD (matched in both time (±15 min) and location (0.05° × 0.05° box)) at JPL500 (44.757° N, 82.34° W). Red dot: MODIS/Aqua; Blue dot: MODIS/Terra; Green plus: AATSR; Black square: UMD GOES-E LST. Period covered is 2004–2008.

![Figure 2](image_url)

**Figure 2.** Instantaneous LST as derived from the JPL archive for PathFinder and from GOES-E UMD. Red dot: PathFinder data; Blue dot: GOES-E UMD. Period covered is 2004–2008.

| GOES-E       | r    | Bias | Std  | RMSE | N  |
|--------------|------|------|------|------|----|
| PathFinder   | 0.98 | 1.34 | 1.26 | 1.83 | 318|
| MODIS-Terra  | 0.99 | 0.42 | 1.17 | 1.24 | 268|
| MODIS-Aqua   | 0.99 | 0.29 | 0.98 | 1.02 | 270|
| AATSR        | 0.99 | 0.38 | 1.06 | 1.12 | 102|

In Table 1, the statistics for Figure 3 comparing the differences between GOES-E and all the other JPL products are given. As evidenced, a better agreement is found between MODIS/Terra, MODIS/Aqua, AATSR, and GOES-E as compared to the AVHRR PathFinder. The mean difference is less than 0.5 °C, and the Std and RMSE are less than 1.5 °C. The AVHRR PathFinder overestimates GOES-E, the Std (1.26 °C) and RMSE (1.83 °C) being relatively larger than for the other cases.

In Figure 4, we illustrate the spatial and temporal variability of the “climatological” mean LST at different UTC times from GOES-E during the period of 2004–2009. Specifically, the averages for UTC00, UTC06, UTC12, and UTC18 (images for other hours are omitted) are shown. The LST temperature varies with time and space. In Figure 5, we show the frequency distribution of LST for cases illustrated in Figure 4. As evidenced, between
UTC00 to UTC18 the median values can change between 9.5 and 11.2 °C, while the maxima range between 15.6 and 24.9 °C and the minima range between −0.5 and 3.60 °C. The temperature changes over time and space have implications for the estimates of the lake’s water budget.
Figure 5. Frequency distribution of hourly LSTs as derived from GOES-E for cases illustrated in Figure 4: (a) UTC00; (b) UTC06; (c) UTC12; and (d) UTC18.

In Figure 6, we show an example of two types of observations for Lake Huron, as derived from MOD11C1 during daytime and nighttime in July. Figure 6a,b represents the mean values over the period of 2004–2009, while Figure 6c,d represents a specific day (05/28/2008). In both cases, the spatial distribution characteristics are similar to those from GOES-E with a noted north-to-south temperature gradient, yet the day/night differences shown for the two satellite systems differ substantially.

In Figure 7, we show the Mean Minimum/Maximum and DTR spatial variability as seen from GOES-E and Mean Night/Day and DTR from MOD11 LST averaged for 2004–2009. Figure 8 shows the LST and DTR frequency distributions for the cases illustrated in Figure 7. As evidenced, the GOES-E LST product shows the detailed spatial variability of both LST and DTR. While the minimum/maximum LST from the GOES observations is between 4–6 °C and 8–10 °C, it is between 6–8 °C for the MODIS cases. For most of the GOES observations, the DTR is between 1 to 5 °C, while for most of the lake the range for the MODIS DTR is 0–1 °C.

In Figure 9a, we show the annual variability of the average true minimum and maximum LST over the lake as documented from GOES-E. In Figure 9b, the annual variability of the average nighttime and daytime values, as observed from MOD11C1, are presented. These are frequently used to represent the DTR. As seen, the observations from polar orbiting satellites do not represent the true DTR well. Both GOES-E and MOD11C1 capture the annual heating progress of the lake, with a maximum temperature reached in August (thermal inertia of water). However, the seasonality of the changes between the maximum and minimum or day and night LST differs. MOD11C1 observations show the same changes between day and night LST from January to December, while the changes between the maximum and minimum LST from GOES-E vary with the season.
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Figure 6. Upper: LST retrievals for July from MOD11C1 (Terra) observations averaged during 2004–2009 for: (a) Nighttime; (b) Daytime. Lower: same as above for a particular day (28 May 2008); (c) nighttime; (d) daytime.

Figure 7. Left Column: (a) mean values of Min LST; (b) mean value of Max LST; (c) mean value of DTR as derived from GOES-E UMD; Right Column: same as the left column using information from MOD11C1 (Terra); (d) mean value of nighttime; (e) mean value of daytime; (f) mean value of proxy DTR. All values are averaged for 2004–2009.
Figure 8. LST frequency distributions for the cases illustrated in Figure 7. Left Column: (a) mean values of Min LST; (b) mean value of Max LST; (c) mean value of DTR as derived from GOES-E UMD; Right Column: same as the left column using information from MOD11C1 (Terra); (d) mean value for nighttime; (e) mean value for daytime; (f) mean value for proxy DTR. All values are averaged for 2004–2009.
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Figure 9. (a) Annual change of the average maximum/minimum LST (DTR) over Lake Huron from GOES-E during 2004–2009; (b) annual change of the average Day/Night LST over Lake Huron from MOD11C1 (Terra) during 2004–2009.

4. Discussion

Surface temperature plays a significant role in the water budget of lakes and the functioning of lake ecosystems. It affects the thermal stratification, the solubility of dissolved oxygen, the metabolism and respiration of the lake’s fauna and flora, and the toxicity of pollutants (Stefan et al. [29]). Thermal infrared data from historical and recently launched satellites provide an opportunity to derive long-term information about the Earth surface temperature at unprecedented spatial and temporal resolutions. Such information has not been readily available in the past, but it is needed in order to address key scientific issues related to climate change, to the energy budget at the surface, and to the development of new applications. Geostationary satellites have contributed substantially to the improvement in available temporal variability. The continuation of newly developed systems such as GOES-16 and 17 (Laszlo et al. [30]) and HIMAWARI-8/9 (Bessho et al. [31]) is enhancing the prospects for the usefulness of such records. Of particular interest is the impact of global warming on DTR due to differences in atmospheric heating during daytime and nighttime. The determination of heat transfer into the subsurface also requires information on the diurnal cycle of the surface temperature.
In this paper, we focus on the diurnal cycle of the temperature over Lake Huron as derived from GOES-E LST at an hourly time scale and at a spatial resolution of about 5 km for a period of six years. We compare our results against JPL and MOD11C1 products. We found a diurnal variability of 1–5 °C in the skin temperature over the lake as observed from GOES-E and that such a variability, when derived from the polar orbiting satellite, was much smaller, in the range of 0–1 °C. The magnitude of this variability (DTR), when observed from GOES-E, changes with time and space. The proxy observations of DTR from MOD11C1 seem to have a constant value over the seasons.

Since information on the spatial and temporal variability of LST is of interest, initial attempts tried to model it empirically from air temperature at various time scales (Leathers et al. [32]; Shuter et al. [33]; McCombie [34]); (Livingstone and Lotter [35]; Livingstone et al. [36]). Sun et al. [37] applied a coupled atmosphere-lake model, which consisted of the NOAA Weather Research and Forecasting (WRF) model and the Princeton Ocean Model (POM), in order to understand the LST variability over lakes. It attempted to estimate mean daily lake surface water temperatures using only the air temperature, theoretical clear-sky solar radiation, and lake size. To verify the approach, measurements were made at a selection of lakes in southwest Greenland during the summers of 1998–2000. Picolroaz [38] simulated the lake surface temperature by means of a hybrid physically based/statistical model, also only using air temperature. When applied to Lake Superior and Lake Erie, the model showed performances that were comparable with those obtained when using process-based models. Sharma et al. [39] developed models that predicted annual maximum near-surface lake water temperatures for lakes across Canada using four statistical approaches. They found that climatic variables and the date of sampling were the most important factors for predicting the water temperature, while the lake morphology did not play a substantial role in the predictions across any of the spatial scales.

All of the diverse studies mentioned above demonstrate the extensive efforts made to obtain information on LST at various spatial and temporal resolution scales. Our study addresses the issue of such variability when it is detectable from space at unprecedented spatial and temporal scales and evaluates the credibility of the information. It is hoped that the derived information will result in useful applications in lake investigations.

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