MINKOWSKI BISECTORS, MINKOWSKI CELLS, AND LATTICE COVERINGS

CHUANMING ZONG

Abstract. As a counterpart of Hilbert’s 18th problem, it is natural to raise the question to determine the density of the thinnest covering of \( E^3 \) by identical copies of a given geometric object, such as a unit ball, a regular tetrahedron or a regular octahedron. However, systematic study on this problem and its generalizations was started much later comparing with that on packings and the known knowledge on coverings is very limited. By studying Minkowski bisectors and Minkowski cells, this paper introduces a new way to study the density \( \theta^*(C) \) of the thinnest lattice covering of \( E^n \) by a centrally symmetric convex body \( C \). Some basic results and unexpected phenomena such as Example 1, Theorems 2 and 4, and Corollary 1 about Minkowski bisectors, Minkowski cells and covering densities are discovered. Three basic problems about Minkowski cells and parallelohedra are presented.

1. Minkowski Metrics and Centrally Symmetric Convex Bodies

Let \( E^n \) denote the \( n \)-dimensional Euclidean space with an orthonormal basis \( \{e_1, e_2, \cdots, e_n\} \). For convenience we use small letters to denote real numbers, use small bold letters to denote points (or vectors) and use capital letters to denote sets of points in the space. In particular, let \( \mathbf{o} \) denote the origin of \( E^n \), and let \( B_n \) denote the \( n \)-dimensional unit ball \( \{x : \sum |x_i|^2 \leq 1\} \).

A metric \( \| \cdot \| \) define in \( E^n \) is called a Minkowski metric if it satisfies the following conditions.

1. \( 0 \leq \|x\| < \infty \) holds for all vectors \( x \in E^n \) and the equality holds if and only if \( x = \mathbf{0} \).

2. \( \|\lambda x\| = |\lambda| \cdot \|x\| \) holds for all vectors \( x \in E^n \) and all real numbers \( \lambda \).

3. \( \|x + y\| \leq \|x\| + \|y\| \) holds for all vectors \( x, y \in E^n \).

Let us define \( C = \{x \in E^n : \|x\| \leq 1\} \).

Since \( \|-x\| = \|x\| \), if \( x \in C \), then \( -x \in C \). Therefore \( C \) is centrally symmetric. On the other hand, if both \( x \) and \( y \) belong to \( C \) and if \( \mu \) is a real number satisfying \( 0 < \mu < 1 \), by the third condition of the metric we have

\[
\|\mu x + (1 - \mu)y\| \leq \mu \|x\| + (1 - \mu)\|y\| \leq \mu + (1 - \mu) = 1.
\]

In other words, \( C \) is convex. In addition, the origin \( \mathbf{o} \) is an interior point of \( C \). Otherwise there would be a point \( x \) satisfying \( \|x\| = \infty \). Finally, since

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\[ \|x\| = 0 \text{ holds if and only if } x = o, \]it can be deduced that \( C \) is bounded. As a conclusion, \( C \) is a centrally symmetric convex body centered at the origin \( o \).

On the other hand, each centrally symmetric convex body \( C \) centered at the origin \( o \) can define a Minkowski metric. Let \( \overline{x} \) denote the point in the direction of \( x \) and on the boundary of \( C \), and define

\[
\|x\| = \begin{cases} 
0 & \text{if } x = o, \\
\lambda & \text{where } x = \lambda \overline{x}.
\end{cases}
\]

In other words, \( \|x\| \) is the positive number \( \lambda \) that \( x \) is on the boundary of \( \lambda C \).

It can be easily verified that

\[ 0 < \|x\| < \infty \]

holds for all \( x \neq o \), and

\[ \|\lambda x\| = |\lambda| \cdot \|x\| \]

holds for all vectors \( x \in E^n \) and all real numbers \( \lambda \). Since \( C \) is convex, for any pair of vectors \( x \) and \( y \) it follows that

\[
\frac{x + y}{\|x\| + \|y\|} = \frac{\|x\|}{\|x\| + \|y\|} \overline{x} + \frac{\|y\|}{\|x\| + \|y\|} \overline{y} \in C,
\]

and therefore

\[ \|x + y\| \leq \|x\| + \|y\|. \]

Thus \( \| \cdot \| \) defines a Minkowski metric on \( E^n \). In particular, when \( C \) is the \( n \)-dimensional unit ball, the corresponding Minkowski metric is the Euclidean metric.

As a conclusion of this section, we get the following well-known assertion (see page 7 of [14]).

**Theorem 0.** There is a one-to-one correspondence between Minkowski metrics and centrally symmetric convex bodies in \( E^n \).

### 2. The Minkowski Bisectors

Let \( \| \cdot \|_C \) denote a Minkowski metric determined by a centrally symmetric convex body \( C \) and let \( \|x, y\|_C = \|y - x\|_C \) denote the Minkowski distance between two points \( x \) and \( y \) with respect to the metric. For two distinct points \( p \) and \( q \) in \( E^n \) we define

\[
H(p, q) = \{ y \in E^n : \langle y, q - p \rangle = 0 \}
\]

and

\[
L(p, q, x) = \{ x + \lambda(q - p) : \lambda \in \mathbb{R} \},
\]

where \( x \in H(p, q) \). In other words, \( H(p, q) \) is a hyperplane containing the origin and perpendicular to the vector \( q - p \), and \( L(p, q, x) \) is the straight line determined by the point \( x \) and the vector \( q - p \). Then, for every \( x \in H(p, q) \), we define

\[
S(C, p, q, x) = \{ y \in L(p, q, x) : \|p, y\|_C = \|q, y\|_C \}.
\]
Now let us introduce a basic result about \( S(C, p, q, x) \) which is essential for the definition of the Minkowski bisectors.

**Lemma 1 (Horváth [10]).** For every \( x \in H(p, q) \), the set \( S(C, p, q, x) \) is either a single point or a closed segment.

**Proof.** Since \( C \) is a centrally symmetric convex body, both \( f(y) = \|p, y\|_C \) and \( g(y) = \|q, y\|_C \) are continuous functions of \( y \). On the other hand, when \( \lambda \) is sufficiently large, we have
\[
f(x + \lambda(q - p)) > g(x + \lambda(q - p))
\]
and
\[
f(x - \lambda(q - p)) < g(x - \lambda(q - p)).
\]
Thus it follows that \( S(C, p, q, x) \) is nonempty. In addition, it can be easily deduced that \( S(C, p, q, x) \) is always a compact set.

Now we show that if both \( u \) and \( v \) belong to \( S(C, p, q, x) \) (see Figure 1) then the whole segment \([u, v]\) belongs to \( S(C, p, q, x) \).

![Fig. 1. Structure of the bisectors](image)

Assume that
\[
\|p - u\|_C = \|q - u\|_C = \alpha,
\|p - v\|_C = \|q - v\|_C = \beta
\]
and \( \alpha < \beta \). It is easy to see that both \( u + p - q \) and \( v + p - q \) belong to \( L(p, q, x) \), \( u \) is between \( v \) and \( u + p - q \) and therefore
\[
u - p = \mu(v - p) + (1 - \mu)(u + p - q - p)
\]
holds for some \( \mu \) with \( 0 < \mu < 1 \). Thus we get
\[
\alpha = \|p - u\|_C \geq \mu\|p - v\|_C + (1 - \mu)\|p - u\|_C \\
\geq \mu\beta + (1 - \mu)\alpha = \alpha + \mu(\beta - \alpha) > \alpha.
\]
By this contradiction we can conclude that \( \alpha = \beta \). Then it follows by convexity (since all \( u + p - q \), \( v + p - q \), \( u \) and \( v \) belong to the boundary of \( p + \alpha C \)) that the whole segment \([u + p - q, v]\) belongs to the boundary of \( p + \alpha C \), the whole segment \([u, v + q - p]\) belongs to the boundary of \( q + \alpha C \), and therefore \([u, v]\) belongs to \( S(C, p, q, x) \). \( \square \)

**Definition 1.** Let \( p \) and \( q \) be fixed distinct points. For \( x \in H(p, q) \) let \( \overline{x} \) denote the middle point of \( S(C, p, q, x) \). Then we define
\[
B(C, p, q) = \{ \overline{x} : x \in H(p, q) \}
\]
and call it a Minkowski bisector of \( p q \) with respect to \( \| \cdot \|_C \).

**Remark 1.** In the literature like [5], [13], [16], [18], [20], [21] and [28], the bisector was defined by

\[
B'(C, p, q) = \{ S(C, p, q, x) : x \in H(p, q) \}.
\]

Clearly we have

\[
B(C, p, q) \subseteq B'(C, p, q).
\]

As one will see from Section 3 that, for the purpose to study packing and covering, \( B(C, p, q) \) is more natural than \( B'(C, p, q) \).

Let \( f(x) \) be a map from \( H(p, q) \) to \( B(C, p, q) \) defined by \( f(x) = e \). Clearly it is a one-to-one map. However it is less obvious if it is continuous in general. We note that in some references such as [16] and [21] our “continuous” is referred as “homeomorphic to a hyperplane”. In fact, as one can see from the following lemma and example, the situation is quite complicated.

**Lemma 2.** In \( E^2 \), for any given metric \( \| \cdot \|_C \) and given distinct points \( p \) and \( q \), the map \( f(x) = e \) from \( H(p, q) \) to \( B(C, p, q) \) is continuous.

**Proof.** Without loss of generality, we assume that \( p = o \) and \( q = e_2 \). Then the set \( H(p, q) \) is the \( x \)-axis. Let \( R_1 \) denote the set of points \( x \in H(p, q) \) such that \( S(C, p, q, x) \) is a single point and write \( R_2 = H(p, q) \setminus R_1 \).

By repeating partial argument of Lemma 1, it can be deduced that \( R_1 \) is closed and if \( (x, 0) \in R_2 \), then \( (x, 0) \in R_2 \) whenever \( |x| \geq |x_1| \). In addition, if \( x_0 = \max \{ x : (x, 0) \in R_1 \} \), \( x_0 = (x_0, 0) \) and \( f(x_0) = (x_0, y_0) \), then \( f(x) \) (for \( (x, 0) \in R_2 \) and \( x > 0 \)) is the middle point of \( [g_1, g_2] \), where \( g_1 = (x, \frac{y_0}{x_0} x) \) and \( g_2 = (x, 1 + \frac{y_0}{x_0} x) \), as shown in Figure 2. In other words \( f(x) \) is an half straight line for \( x \geq x_0 \). Similarly, one can deal with the case that \( (x, 0) \in R_2 \) and \( x \leq -x_0 \).

![Fig. 2. Structure of the Minkowski bisectors](image)

Then the continuity of \( f(x) \) follows easily, by considering two cases \( x \in R_1 \) and \( x \in R_2 \). \( \square \)

**Example 1.** In \( E^3 \) let us define

\[
C = \text{conv}\{v, S, -v\},
\]

where \( S = \{(x, y, 0) : x^2 + y^2 \leq 1\} \) and \( v = (1, 0, 1) \). It is easy to see that \( C \) is a centrally symmetric convex body and its surface has only two vertical segments, they are \( [e_1, v] \) and \( [-e_1, -v] \). Take \( p = (0, 0, 0) \) and \( q = (0, 0, 1) \) and let \( \mathbb{H} \)
denote the set of all planes which containing both \( p \) and \( q \). By considering the intersections with planes \( H \in \mathbb{H} \), one can deduce that the Minkowski bisector \( B(C, p, q) \) with respect to \( \| \cdot \|_C \) consists of two parts \( L \) and \( M \), where \( L \) is a straight line \( \{(x, 0, \frac{1}{2}(x + 1)) : x \in \mathbb{R} \} \) and \( M \) is a set between two planes \( M_1 = \{(x, y, z) : z = 0\} \) and \( M_2 = \{(x, y, z) : z = 1\} \), as shown in Figure 3. Therefore it is easy to see that the map \( f(x) = x \) is not continuous at the points \( (x, 0, 0) \) whenever \(|x| > 1\). By adding more edges similar to \([e_1, v]\), one can make the situation much more complicated.

Let \( C \) denote the set of all \( n \)-dimensional centrally symmetric convex bodies centered at the origin \( o \) and let \( \delta(\cdot, \cdot) \) denote the Hausdorff metric defined on \( C \). In other words,

\[
\delta(C_1, C_2) = \min\{\gamma : C_1 \subseteq C_2 + \gamma B_n; C_2 \subseteq C_1 + \gamma B_n\}.
\]

Let \( p \) and \( q \) be two fixed distinct points, let \( C_0 \) be a centrally symmetric convex body, and let \( C_1, C_2, \cdots \) be a sequence of centrally symmetric convex bodies. It is natural to ask, would \( B(C_i, p, q) \) converges to \( B(C_0, p, q) \) if

\[
\lim_{i \to \infty} \delta(C_i, C_0) = 0?
\]

Unfortunately, as one will see from the next example, the answer to this question is negative, even in the plane.

**Example 2.** In the plane we define

\[
C_0 = \{(x, y) : -1 \leq x \leq 1; -1 \leq y \leq 1\}
\]

and

\[
C_i = \text{conv} \{\pm(1, 1), \pm(1, 0), \pm(1 - \frac{1}{i}, -1)\}
\]

for \( i = 1, 2, \cdots \). Then we have

\[
\lim_{i \to \infty} \delta(C_i, C_0) = 0.
\]

Let \( p = (0, 0) \) and \( q = (0, 2) \), we have

\[
B(C_0, p, q) = \{(x, 1) : x \in \mathbb{R}\}.
\]
However, as shown by Figure 4, the Minkowski bisector $B(C_i, p, q)$ consists of points $(x, y)$ satisfying

$$y = \begin{cases} 
\frac{1}{2}x + 1, & \text{if } |x| \geq 2, \\
\frac{1}{i+1}(x + 2), & \text{if } -2 \leq x \leq \frac{1}{2} - 1, \\
1, & \text{if } |x| \leq 1 - \frac{1}{i}, \\
\frac{1}{i+1}x + \frac{2}{i+1}, & \text{if } 1 - \frac{1}{i} \leq x \leq 2.
\end{cases}$$

Therefore the sequence $B(C_i, p, q)$ does not converge to $B(C_0, p, q)$.

If $B(C, p, q)$ is a continuous surface, then it divides the whole space nicely into two half spaces. Unfortunately, as it was shown by Example 1, the Minkowski bisectors are not always continuous. Nevertheless, for many important metrics, the continuity can be guaranteed by the next lemma.

**Lemma 3.** If $C$ is a regular centrally symmetric convex body or a centrally symmetric polytope, for any pair of distinct points $p$ and $q$, the map $f(x) = x$ from $H(p, q)$ to $B(C, p, q)$ is continuous.

**Proof.** First let us deal with the regular case. By regular we mean that its surface does not contain any segment. Then, for any point $x \in H(p, q)$, $S(C, p, q, x)$ is a single point. If the map is not continuous at point $x_0$, then one can deduce that $S(C, p, q, x_0)$ is not a single point. The regular case follows.

Now we consider the polytope case. Let $P$ be an $n$-dimensional centrally symmetric convex polytope, let $P'$ denote its projection on $H(p, q)$, and let $\partial(P')$ denote the relative boundary of $P'$. Clearly $P'$ is a $(n-1)$-dimensional centrally symmetric polytope and $\partial(P')$ is a polytope complex of dimension less than or equal to $n-2$.

Let $v$ be a point in $\partial(P')$, let $v^*$ denote the point $v + \mu(q - p) \in P$ with maximal $\mu$, let $v'$ denote the corresponding point with minimal $\mu$, and write

$$h(v) = \frac{\|v^* - v\|}{\|q - p\|}.$$ 

Since $P$ is a polytope, by convexity, it is easy to see that both $g_1(v) = v^*$ and $g_2(v) = v'$ are continuous maps for $v \in \partial(P')$, and $h(v)$ is a continuous function for $v \in \partial(P')$. 

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Fig. 4. Non-convergence of the Minkowski bisectors
Let $Q(p, q, v)$ denote the two-dimensional hyperplane determined by $p$, $q$ and $v$. By studying the intersections with $Q(p, q, v)$, it can be shown that $S(P, p, q, \alpha v)$ is a single point if and only if $\alpha \leq 1/h(v)$ (when $h(v) = 0$, $\alpha$ can be any number). For $\alpha v \in H(p, q)$, let $f_1(\alpha v)$ denote the point $\alpha v + \mu(q - p)$ in $S(P, p, q, \alpha v)$ with the maximal $\mu$ and let $f_2(\alpha v)$ denote the corresponding point in $S(P, p, q, \alpha v)$ with the minimal $\mu$. When $\alpha > 1/h(v)$, illustrated by Figure 5, it can be shown by similar triangles that

$$f_1(\alpha v) = \alpha v^*,$$

$$f_2(\alpha v) = \alpha v^* - (\alpha h(v) - 1)(q - p)$$

and

$$f(\alpha v) = \alpha v^* - \frac{1}{2}(\alpha h(v) - 1)(q - p).$$

(1)

Let $H_1(p, q)$ denote the set of the points $x \in H(p, q)$ such that $S(P, p, q, x)$ is not a single point. It can be shown that $H_1(p, q)$ is an open set and therefore $H(p, q) \setminus H_1(p, q)$ is a closed set. By (1) it follows that $f(x)$ is continuous in $\overline{H_1(p, q)}$. On the other hand $f(x)$ is continuous in $H(p, q) \setminus H_1(p, q)$. Therefore $f(x)$ is a continuous map from $H(p, q)$ to $B(P, p, q)$. The lemma is proved. □

By the previous proof, it is easy to see that the Minkowski bisector $B(P, p, q)$ is consists of planar pieces if the metric is defined by a polytope $P$. Let $\varphi(P, p, q)$ denote the minimal number $k$ such that the Minkowski bisector of $p$ and $q$ with respect to $\| \cdot \|_P$ can be divided into $k$ planar pieces. We have the following results.

**Theorem 1.** If $P$ is a centrally symmetric polygon with $m$ vertices. Then, we have

$$\varphi(P, p, q) \leq m - 1.$$  

**Proof.** For convenience, without loss of generality, we take $p = (0, 0)$ and $q = (0, 1)$. Let $\lambda$ change from 0 to infinity, it is easy to see that the boundaries of $\lambda P + p$ and $\lambda P + q$ intersect each other whenever $\lambda \geq \alpha$ for some $\alpha$.

For some $\beta > 0$, assume that the boundaries of $\beta P + p$ and $\beta P + q$ meet at a vertex $v_1$ of $\beta P + p$ or $\beta P + q$ (see Figure 6), $v_1 v_2$ is an edge of $\beta P + p$, $v_1 v_3$ is an edge of $\beta P + q$. Let $M_2$ denote the line which is parallel to $v_1 v_2$ and pass through $2v_2$, let $M_3$ denote the line which is parallel to $v_1 v_3$ and pass through $2v_3$. From $v_2$ to $v_3$, there should be at least one line parallel to the boundary of $\beta P + p$ and $\beta P + q$ which passes through $v_2$. Therefore, $\varphi(P, p, q) \leq m - 1$.

Fig. 5. From a bisector to a Minkowski bisector

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2(v₃ − q) + q, let m be the intersection of M₂ and M₃, let L denote the line passes v₁ and m, let L₂ denote the line determined by p and v₂, and let L₃ denote the line determined by q and v₃. Then L₂ intersects L at a point u₂ and L₃ intersects L at a point u₃. Let u denote the uᵢ which is closer to v₁. By elementary geometry it is easy to see that the whole segment [u, v₁] belongs to B(P, p, q). In addition, for some γ > 0, the boundaries of γP + p and γP + q meet at u and u is a vertex of either γP + p or γP + q. By repeating this process and dealing with two cases with respect to if ∂(C) contains a segment which is parallel to pq or not, it can be shown that

\[ \varphi(P, p, q) \leq m - 1. \]

The theorem is proved. □

**Remark 2.** It is easy to see that

\[ B(\lambda C, p, q) = B(C, p, q) \]

holds for all positive number λ. Thus, for a fixed polytope P, the number \( \varphi(P, p, q) \) is determined by the direction of pq. In fact, it follows by the proof of Theorem 1 that,

\[ \varphi(P, p, q) = m - 1 \]

holds for all p and q, except for a finite number of directions pq.

In higher dimensions the situation is much more complicated. We have the following upper bound for \( \varphi(P, p, q) \).

**Theorem 2.** Let \( n \geq 3 \) be an integer and let P be an n-dimensional centrally symmetric polytope with m facets. Then

\[ \varphi(P, p, q) \leq \frac{1}{2}m^2 + \frac{1}{27}m^3 \]

holds for any pair of distinct points p and q.

**Proof.** Let F denote a facet of P, let n(F) denote its outer unit normal, and let \( \mathcal{F} \) denote the set of the m facets of P. Then we define

\[ \mathcal{F}_- = \{ F \in \mathcal{F} : \langle n(F), q - p \rangle < 0 \}, \]
\[ \mathcal{F}_0 = \{ F \in \mathcal{F} : \langle n(F), q - p \rangle = 0 \} \]
and
\[ \mathcal{F}_+ = \{ F \in \mathcal{F} : \langle n(F), q - p \rangle > 0 \}. \]

It is easy to see, let \( |X| \) denote the number of the elements of \( X \), that these three sets are pairwise disjoint and satisfying
\[ |\mathcal{F}_-| = |\mathcal{F}_+| \leq \frac{1}{2} m \] (2)

and
\[ |\mathcal{F}_-| + |\mathcal{F}_0| + |\mathcal{F}_+| = m. \] (3)

Assume that \( B(P, p, q) \) can be divided into \( \varphi(P, p, q) \) planar pieces \( G_1, G_2, \ldots, G_{\varphi(P, p, q)} \) and write
\[ G = \{ G_i : i = 1, 2, \ldots, \varphi(P, p, q) \}. \]

For each \( i \) let \( w_i \) be a relative interior point of \( G_i \) such that there are a relative interior point \( u_i \) of a facet which belongs to either \( \mathcal{F}_- \) or \( \mathcal{F}_0 \), a relative interior point \( v_i \) of a facet which belongs to either \( \mathcal{F}_0 \) or \( \mathcal{F}_+ \), and a positive number \( \lambda_i \) satisfying
\[ w_i = \lambda_i u_i + q = \lambda_i v_i + p. \] (4)

If \( u_i \in F \in \mathcal{F}_0 \), by looking at Figure 5, it can be deduced that \( v_i \in F \).

Then \( G \) can be divided into two disjoint subsets

\[ \mathcal{G}_1 = \left\{ G_i : u_i \in \bigcup_{F \in \mathcal{F}_-} F \right\} \]

and

\[ \mathcal{G}_2 = \left\{ G_i : u_i \in \bigcup_{F \in \mathcal{F}_0} F \right\}. \]

Clearly we have
\[ \varphi(P, p, q) = |\mathcal{G}_1| + |\mathcal{G}_2|. \] (5)

Now we proceed to estimate \( |\mathcal{G}_1| \) and \( |\mathcal{G}_2| \), respectively.

If \( u_i \) and \( u_j \) belong to one facet \( F^* \) in \( \mathcal{F}_- \) and \( v_i \) and \( v_j \) belong to one facet \( F^* \) in \( \mathcal{F}_+ \), then one can deduce that \( w_i \) and \( w_j \) should belong to the same planar piece. In other words, the whole segment \( [w_i, w_j] \) belongs to \( B(P, p, q) \). To see this, when \( 0 \leq \theta \leq 1 \), writing \( \lambda = \theta \lambda_i + (1 - \theta) \lambda_j \) and \( \theta' = \theta \lambda_i / \lambda \), we have
\[ \theta w_i + (1 - \theta) w_j = \theta (\lambda_i u_i + q) + (1 - \theta)(\lambda_j u_j + q) \]
\[ = \theta \lambda_i u_i + (1 - \theta) \lambda_j u_j + q \]
\[ = \lambda (\theta' u_i + (1 - \theta') u_j) + q \]

and
\[ \theta w_i + (1 - \theta) w_j = \theta (\lambda_i v_i + p) + (1 - \theta)(\lambda_j v_j + p) \]
\[ = \theta \lambda_i v_i + (1 - \theta) \lambda_j v_j + p \]
\[ = \lambda (\theta' v_i + (1 - \theta') v_j) + p, \]

where \( \theta' u_i + (1 - \theta') u_j \in F^* \) and \( \theta' v_i + (1 - \theta') v_j \in F' \).
Therefore $|\mathcal{G}_1|$ is bounded from above by the number of distinct pairs of facets $\{F^*, F'\}$ such that $F^* \in \mathcal{F}_-$ and $F' \in \mathcal{F}_+$. Then by (2) we get

$$|\mathcal{G}_1| \leq |\mathcal{F}_-| \cdot |\mathcal{F}_+| \leq \frac{1}{4}m^2. \quad (6)$$

For $F \in \mathcal{F}_0$ we write

$$\mathcal{G}(F) = \{ G_i : u_i \in F \}.$$

Let $\mathcal{F}'_+$ denote the set of the facets $F'$ of $P$ such that $\langle n(F'), q - p \rangle > 0$ and $F \cap F'$ is a $(n-2)$-dimensional polytope and let $\mathcal{F}'_-$ denote the set of the facets $F^*$ of $P$ such that $\langle n(F^*), q - p \rangle < 0$ and $F \cap F^*$ is a $(n-2)$-dimensional polytope. For $u_i, v_i$ and $w_i$ defined by (4), let $u_i^+ = v_i^+$ and $u_i^- = v_i^-$. If both $u_i^+$ and $u_i^-$ belong to int$(F \cap F')$ for a facet $F' \in \mathcal{F}'_+$ and both $v_i^-$ and $v_i^+$ belong to int$(F \cap F^*)$ for a facet $F^* \in \mathcal{F}'_-$, by an argument similar to the previous case it can be deduced that both $w_i$ and $w_j$ belong to a planar piece of $B(F, p, q)$. Therefore $|\mathcal{G}(F)|$ is bounded from above by the number of distinct pairs of facets $\{F', F^*\}$ such that $F' \in \mathcal{F}'_+$ and $F^* \in \mathcal{F}'_-$. Consequently, we get

$$|\mathcal{G}(F)| \leq |\mathcal{F}'_-| \cdot |\mathcal{F}'_+| \leq |\mathcal{F}_-| \cdot |\mathcal{F}_+|$$

and, by (3),

$$|\mathcal{G}_2| \leq |\mathcal{F}_0| \cdot |\mathcal{F}_-| \cdot |\mathcal{F}_+| \leq \frac{1}{57}m^3. \quad (7)$$

As a conclusion of (5), (6) and (7) we get

$$\varphi(P, p, q) \leq \frac{1}{4}m^2 + \frac{1}{27}m^3.$$

The theorem is proved. \hfill \Box

**Remark 3.** Although we cannot give a proof, the upper bound in Theorem 2 seems much too large. It is easy to see that the direction $pq$ such that $\mathcal{F}_0 \neq \emptyset$ is a zero measure set on $\partial(B_n)$. Therefore we have

$$\varphi(P, p, q) \leq \frac{1}{4}m^2,$$

unless the direction $pq$ belongs to a zero measure set of $\partial(B_n)$.

### 3. Minkowski Cells, Lattice Packings and Lattice Coverings

Let $C$ be an $n$-dimensional centrally symmetric convex body, and let $p$ and $q$ be two distinct points in $\mathbb{R}^n$. We recall that $H(p, q)$ is the hyperplane $\{ x : \langle x, q - p \rangle = 0 \}$ and $x$ is the point $x + \lambda (q - p)$ in $B(C, p, q)$. For convenience, we define

$$D(C, p, q) = \{ x + \lambda (q - p) : x \in H(p, q), \ \lambda \leq 0 \}.$$

In principle, the structure of $D(C, p, q)$ can be very complicated. Nevertheless, we have the following general result.

**Lemma 4.** The set $D(C, p, q)$ is a star set with $p$ as its origin.

**Proof.** For convenience, we take $p = 0$. Then we proceed to show that, if $u \in D(C, p, q)$, then $\alpha u \in D(C, p, q)$ holds for all $\alpha$ with $0 \leq \alpha \leq 1$. 

Let \( Q(p, q, u) \) denote the two-dimensional plane determined by \( p, q \) and \( u \). We consider the intersection of \( D(C, p, q) \) with \( Q(p, q, u) \). Clearly, \( u \in D(C, p, q) \) implies

\[
\|p, u\|_C \leq \|q, u\|_C.
\]

(8)

Fig. 7. A section of \( D(C, p, q) \) is star shape

On the contrary, if \( v = \alpha u \notin D(C, p, q) \) holds for some \( \alpha < 1 \), we proceed to deduce a contradiction. Assume that

\[
v = y + \lambda (q - p)
\]

with suitable \( y \in H(p, q) \) and \( \lambda \in \mathbb{R} \). Then the point \( y \) corresponding to \( y \) on the Minkowski bisector is below \( v \), as shown in Figure 7. By Lemma 2, there is a suitable \( w \) between \( p \) and \( v \) such that \( w \in B(C, p, q) \). Therefore,

\[
w \in \partial(\lambda C + p) \cap \partial(\lambda C + q)
\]

holds for some suitable \( \lambda \). Then we have

\[w + q - p \in \partial(\lambda C + q).\]

If the whole segment \([w, w + q - p]\) belongs to \( \partial(\lambda C + q) \), then one can deduce that the whole segment \([w, u]\) belongs to \( D(C, p, q) \) and thus \( v \in D(C, p, q) \), which contradicts the assumption. If

\[ [w, w + q - p] \notin \partial(\lambda C + q), \]

then by convexity it can be deduced that

\[
\|q, u\|_C < \frac{\|q, u\|}{\|q, w'\|} \cdot \lambda = \frac{\|p, u\|}{\|p, w\|} \cdot \lambda = \|p, u\|_C,
\]

which contradicts (8).

As a conclusion, \( \alpha u \in D(C, p, q) \) holds for all \( 0 \leq \alpha \leq 1 \). Lemma 4 is proved.

□

Remark 4. For the \( C \), \( p \) and \( q \) defined in Example 1, the region \( D(C, p, q) \) is not closed. However, when \( B(C, p, q) \) is continuous, the region \( D(C, p, q) \) is closed.
Definition 2. Let $C$ be a centrally symmetric convex body, let $\Lambda$ be a lattice and define 

$$M(C, \Lambda) = \bigcap_{v \in \Lambda \setminus \{o\}} D(C, o, v).$$

We call $M(C, \Lambda)$ a Minkowski cell of $\Lambda$ with respect to the metric $\| \cdot \|_C$.

Remark 5. For fixed $C$, $p$ and $q$, it can be verified that both 

$$B(\lambda C, p, q) = B(C, p, q)$$

and 

$$D(\lambda C, p, q) = D(C, p, q)$$

hold for all positive numbers $\lambda$. If $\Lambda$ is a lattice and $\tau$ is a non-singular linear transformation from $E^n$ to $E^n$. Then we have 

$$B(\tau(C), \tau(p), \tau(q)) = \tau(B(C, p, q)),$$

$$D(\tau(C), \tau(p), \tau(q)) = \tau(D(C, p, q))$$

and 

$$M(\tau(C), \tau(\Lambda)) = \tau(M(C, \Lambda)).$$

By Lemma 4 it follows that the Minkowski cells are centrally symmetric star sets centered at the origin. In the Euclidean case, $C = B_n$, all Minkowski bisectors are hyperplanes, and all Minkowski cells are parallellohedra.

Lemma 5. Let $C$ be an $n$-dimensional centrally symmetric convex body, let $\Lambda$ be an $n$-dimensional lattice, and let $\gamma$ denote the smallest positive number such that $\gamma C + \Lambda$ is a covering of $E^n$. Then 

$$M(C, \Lambda) \subseteq \gamma C.$$ 

Proof. If, on the contrary, there is a point $x \in M(C, \Lambda)$ such that $\|o, x\|_C > \gamma$. Since $\gamma C + \Lambda = E^n$, there is a lattice point $v \in \Lambda$ such that $\|v, x\|_C \leq \gamma$. Thus, we have 

$$x \notin D(C, o, v)$$

and hence 

$$x \notin M(C, \Lambda).$$

The lemma is proved.

Theorem 3. Let $C$ be a two-dimensional centrally symmetric convex domain and let $\Lambda$ be a two-dimensional lattice. Then the region $M(C, \Lambda)$ is a centrally symmetric star domain and $M(C, \Lambda) + \Lambda$ is a tiling.

Proof. First, by Definition 2, Lemma 4 and Remark 4, it follows that $M(C, \Lambda)$ is a centrally symmetric star domain. In other words, it is a centrally symmetric compact star set.

Now, we claim that 

$$(\text{int}(M(C, \Lambda)) + v_i) \cap (\text{int}(M(C, \Lambda)) + v_j) = \emptyset$$

holds for all distinct lattice points $v_i$ and $v_j$.

If, on the contrary, without loss of generality there are a point $x$, a positive number $\epsilon$ and a lattice point $v$ such that 

$$\epsilon C + x \subseteq \text{int}(M(C, \Lambda)) \cap (\text{int}(M(C, \Lambda)) + v).$$

(9)
Then, we observe the Minkowski bisector $B(C, o, v)$. If $x \in B(C, o, v)$, then we have

$$x + \epsilon v \not\in D(C, o, v)$$

and

$$x + \epsilon v \not\in M(C, \Lambda),$$

which contradicts to (9), where $\nabla$ is the boundary point of $C$ in the direction of $v$ as defined in Section 1. If $x \not\in B(C, o, v)$, since $B(C, o, v)$ divides $\mathbb{E}^2$ into two separated parts which contains $\text{int}(M(C, \Lambda))$ and $\text{int}(M(C, \Lambda)) + v$, respectively. Therefore, $\epsilon C + x$ can't belong to both $\text{int}(M(C, \Lambda))$ and $\text{int}(M(C, \Lambda)) + v$ simultaneously when $\epsilon$ is sufficiently small, which contradicts to (9) as well.

Next, we claim that for every point $x \in \mathbb{E}^2$ there is a lattice point $v$ such that

$$x \in M(C, \Lambda) + v.$$  

(10)

Without loss of generality, since $\Lambda$ is periodic, we assume that $x \in \gamma C$. Clearly, we have

$$\gamma C \subseteq D(C, o, q)$$

whenever $\|o, q\|_C > 2\gamma$. Therefore, there are at most $|2\gamma C \cap \Lambda|$ Minkowski bisectors which can effect $M(C, \Lambda)$. Consequently, we assume further that

$$x \in \text{int}(\gamma C) \setminus \bigcup_{v_i, v_j \in 2\gamma C \cap \Lambda} B(C, v_i, v_j).$$

If, for any positive $\epsilon$ there is a point $x'$ such that $x' \in \epsilon C + x$ and

$$\|o, x'\|_C < \|v, x'\|_C$$

holds for all $v \in 2\gamma C \cap (\Lambda \setminus \{o\})$. Then, since $M(C, \Lambda)$ is compact, we have $x \in M(C, \Lambda)$. If, there are a positive number $\epsilon'$ and a subset $W$ of $2\gamma C \cap \Lambda$ with $|W| \geq 2$ such that

$$\|x', w_i\|_C = \min\{\|x', v\|_C : v \in 2\gamma C \cap \Lambda\}$$

holds for all $x' \in \epsilon C + x$ and $w_i \in W$. Then, $W \subset \partial(\lambda C) + x$ holds for some suitable positive number $\lambda$. By Figure 8 it can be shown that, if $w_i$ and $w_j$ are two distinct points in $W$, then the whole segment $[w_i, w_j]$ belongs to $\partial(\lambda C) + x$ and thus all the points of $W$ are colinear.

![Fig. 8. The structure of the equidistance set](image-url)
Assume that $w_1, w_2, \ldots, w_k$ are the points of $W$ that successively on a line $H$, as shown in Figure 9. Since $W \subset \Lambda$, we have

$$w_{i+1} - w_i = w_2 - w_1.$$ 

Let $\Lambda'$ denote the affine lattice generated by $W$ in $H$. In other words,

$$\Lambda' = \{w_1 + z(w_2 - w_1) : z \in \mathbb{Z}\}.$$ 

Then, $M(C, \Lambda') + \Lambda'$ is a tiling of $E^2$. Therefore, as illustrated by Figure 9, there is a $w_i \in W$ such that

$$x \in M(C, \Lambda') + w_i$$

and consequently

$$x \in M(C, \Lambda) + w_i.$$

Fig. 9. Every point belongs to a Minkowski cell

As a conclusion, $M(C, \Lambda) + \Lambda$ is a tiling of $E^2$. Theorem 3 is proved. $\square$

**Theorem 4.** Let $C$ be an $n$-dimensional centrally symmetric convex body, let $\Lambda$ be an $n$-dimensional lattice, and let $\gamma$ denote the smallest positive number such that $\gamma C + \Lambda$ is a covering of $E^n$. If $\partial(C)$ has no segment in the directions of $\{v : v \in 2\gamma C \cap (\Lambda \setminus \{0\})\}$, then the region $M(C, \Lambda)$ is a centrally symmetric star body and $M(C, \Lambda) + \Lambda$ is a tiling.

This result can be proved just like the Euclidean case. Let $\delta^*(C)$ denote the density of the densest lattice packing of $C$ and let $\theta^*(C)$ denote the density of the thinnest lattice covering of $E^n$ by $C$. Theorem 4 has the following corollary.

**Corollary 1.** Let $P$ be an $n$-dimensional centrally symmetric polytope and let $\mathcal{M}$ denote the set of all Minkowski cells $M(P, \Lambda)$ contained in $P$. Then, we have

$$\theta^*(P) = \inf_{M \in \mathcal{M}} \frac{\text{vol}(P)}{\text{vol}(M)}.$$

**Remark 6.** When $C = B_3$, there are only five types of Minkowski cells (parallelorhedra). Therefore, one can determine the values of $\delta^*(B_3)$ and $\theta^*(B_3)$ by studying a unit ball inscribed in parallelorhedra or parallelorhedra inscribed in a unit ball. For other particular nontrivial centrally symmetric convex bodies, for
example the octahedron, to enumerate their Minkowski cells seems challenging and interesting.

It was proved by D.G. Ewald, D.G. Larman and C.A. Rogers [9] that the line segment directions on the surface of an $n$-dimensional convex body is a very small subset of $\partial(B_n)$. Therefore, Theorem 4 and Corollary 1 seem can be improved further. We end this article by three open problems as following.

**Problem 1.** Let $P$ be an $n$-dimensional centrally symmetric polytope. Enumerate the different types (geometric or combinatorial) of the Minkowski cells $M(P, \Lambda)$ for all lattices $\Lambda$.

**Problem 2.** Let $C$ be an $n$-dimensional centrally symmetric convex body such that all its Minkowski bisectors are continuous. Is $M(C, \Lambda) + \Lambda$ always a tiling of $\mathbb{E}^n$ for all lattice $\Lambda$?

**Problem 3.** Whenever $C + \Lambda$ is a lattice covering of $\mathbb{E}^n$, $n \geq 3$, is there always a parallelohedron $P$ satisfying both $P \subseteq C$ and $P + \Lambda$ is a tiling of $\mathbb{E}^n$?

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