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Rayleigh-Taylor instability under an inclined plane

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We revisit the canonical Rayleigh-Taylor instability and investigate the case of a thin film of fluid upon the underside of an inclined plane. The presence of a natural flow along the plane competes with the conventional droplet forming instability. In particular, experiments reveal that no drops form for inclinations greater than a critical value. These features are rationalized in the context of the absolute/convective analysis conducted in this article. © 2015 AIP Publishing LLC. [http://dx.doi.org/10.1063/1.4927857]

I. INTRODUCTION

The Rayleigh-Taylor instability (RTI) describes the destabilization of the interface separating stratified fluids under the action of an applied acceleration directed from the heavier fluid towards the lighter fluid. In particular, this instability occurs under the action of gravity when a fluid is momentarily sustained above a fluid of lesser density.1,2 Other examples are found in a variety of situations ranging from the simple case of water sitting on oil in a kitchen glassware to supernova explosions.3 This interfacial instability has been thoroughly studied and has served as a foundation for tackling fundamental issues such as the break up of free-surface flows4 (drop formation) and pattern generation.5 Applicative components of this instability also arise due to its natural tendency to enhance the mixing of liquid species.2 Additionally, the RTI is a prime concern when coating surfaces, be it with paint or a lubricant, as the instability may lead to coating irregularities or to the detachment of droplets for thick coatings. As such, many studies have concentrated on means of controlling or suppressing the growth of pendant drops. This can be achieved, for example, by surface tension gradients arising from a temperature difference across the thin film6 or from the evaporation of the solvent in a multicomponent liquid.7 The Rayleigh-Taylor instability can also be controlled by high-frequency vibrations of the substrate8 or by the application of an electric field.9 In the following, we revisit the iconic problem of a thin liquid film spread upon the underside of a flat surface and investigate the effect of the substrate orientation on the instability.

In the canonical RTI of a thin viscous fluid layer coated on the underside of a horizontal surface, the interface perturbations are found to grow exponentially in time and generate drops arranged in various patterns.5 The instability development is set by the competition of surface tension effects and gravitational effects such that the distance between droplets is found to be \( \lambda = 2\pi\sqrt{2}\ell_c \) where \( \ell_c = \sqrt{\gamma/\rho g} \) is the capillary length of the problem and \( \gamma, \rho, \) and \( g \) denote the thin layer surface tension, its density, and the acceleration of gravity, respectively. This natural length scale is well recovered with linear arguments since \( \lambda \) is the wavelength of the most unstable mode predicted by linear stability analysis.

Herein, we extend the study to cases where the surface is tilted and set at an angle \( \alpha \leq \pi/2 \) from the vertical (see Fig. 1, \( \alpha = \pi/2 \) corresponds to the horizontal case). In particular, we focus on how the main features of the instability are affected by the base flow along the substrate. For values of \( \alpha \approx \pi/2 \), we observe that the interface deforms and eventually forms droplets according to the
FIG. 1. (a) A thin film of initial thickness $h_i$ flows on the underside of a transparent inclined plane. The angle $\alpha$ denotes the inclination of the substrate with respect to the gravity $g$. (b) A typical experimental observation for $h_i = 0.52 \ell_c$ and $\alpha = 81^\circ$. (c) No drops are formed for $h_i = 0.55 \ell_c$ and $\alpha = 60.5^\circ$. (d) For large enough values of $\alpha$, droplets form according to the Rayleigh-Taylor instability. The black arrows indicate the overall direction of the flow.

RTI (Figs. 1(b) and 1(d)). For values of $\alpha \leq \pi/2$, deformations of the surface are the greatest in the downstream direction where the fluid accumulates; this is also the area where the first droplets form. Soon after, more droplets form and drip from the upward area as well. However, building upon the known characteristics of flows on vertical walls—be it from the application of varnish on furniture in daily experience or else when referring to the literature on plates extracted from liquid baths—one may anticipate that the inclination of the substrate is likely to affect the instability to a point where it could disappear below a critical angle $\alpha_c$. This angle $\alpha_c$ has been observed experimentally (see Fig. 1(c)) as explained in the results of Sec. IV. We will see that traditional temporal linear stability arguments, which are sufficient in the horizontal case, fail to predict the value of $\alpha_c$. The experiments are instead rationalized by addressing the absolute or convective nature of the aforementioned linear stability results as detailed hereafter. Note that the Kapitza instability is here neglected owing to the low Reynolds numbers characterizing the experiment. Hence, we solely focus our analysis on the RTI.

II. THE FLOW UNDER AN INCLINED PLANE

We consider the flow of a thin fluid film of initial thickness $h_i$ placed underneath an inclined plane (Fig. 1). The film of density $\rho$, viscosity $\mu$, and surface tension $\gamma$ is subject to the acceleration of gravity $g$. Of particular importance herein is the angle $\alpha > 0$ between the substrate and the vertical. The thickness $h_i$ is supposed smaller than the typical length scale over which the coating spreads, i.e., the problem is assumed invariant in the flow direction. Additionally, mass conservation indicates that the flow velocity $u = (u, v)$ is essentially one dimensional ($v \sim u \times h/L \ll u$). Assuming low Reynolds number, one may write the lubrication equations for this flow yielding

$$u(x, y) = \frac{\rho g}{\mu} \left( -\sin \alpha \frac{\partial h}{\partial x} - \frac{\gamma}{\rho g} \frac{\partial \kappa}{\partial x} - \cos \alpha \right) y(y - 2h),$$

where $\kappa \approx \frac{\partial^2 h}{\partial x^2}$ is the interface curvature. Integrating Eq. (1) leads to finding the flow rate $Q \propto h^3$, which combined to mass conservation yields

$$\frac{\partial h}{\partial t} = -\frac{\partial}{\partial x} \left( \frac{\rho g h^3}{3\mu} \left( \sin \alpha \frac{\partial h}{\partial x} + \ell_c^2 \frac{\partial \kappa}{\partial x} \right) \right) - \frac{\rho g h^2}{\mu} \frac{\partial h}{\partial x} \cos \alpha.$$  

The trivial solution $h = h_i$ satisfies Eq. (2) and is valid for any value of $h_i < L$. In that case, the Poiseuille-like flow in the $x$-direction is such that the free surface velocity writes

$$u_i = \cos \alpha \frac{\rho g}{\mu} h_i^2.$$
We now turn to examining the stability of the uniform solution to linear perturbations. Assuming a normal decomposition $h(x,t) = h_i + \epsilon h_d(x,t)$ with $\epsilon \ll 1$ and $h_d(x,t) \propto e^{i(kx - \omega t)}$ (see Fig. 2), one obtains the following dispersion relation for $\omega$ from Eq. (2):

$$\omega(k) = \frac{\rho gh_i^3}{3\mu} \left( i \left( k^2 \sin \alpha - \ell_c^2 k^4 \right) + \left( \frac{\rho gh_i^2}{\mu} \cos \alpha \right) k \right).$$

The real part of $\omega$ represents the advection of the wave and is found to be equal to $u_i$, the velocity at the interface of a uniform film. The imaginary part of $\omega$, denoted $\sigma$, is the temporal growth rate of the instability, whose sign sets the stability of the perturbation. The flow is either stable, marginally stable, or unstable for $\sigma < 0$, $\sigma = 0$, and $\sigma > 0$, respectively.

As one may observe in Fig. 3, the flow is always found to be linearly temporally unstable for strictly positive values of $\alpha$ and the most unstable modes are

$$k_{\text{max}} = \frac{1}{\ell_c \sqrt{2}} \sqrt{\sin \alpha}. \quad (5)$$

They correspond to a wavelength $\lambda_{\text{max}} = 2\pi \sqrt{2} \ell_c / \sqrt{\sin \alpha}$ and comments may be made regarding this expression. First, when substituting $\alpha = \pi/2$ in Eq. (5), one recovers the wavelength of the RTI of a thin film underneath a horizontal plate, $\lambda_{\alpha=\pi/2} = 2\pi \sqrt{2} \ell_c$, which sets the distance between neighboring droplets (on the order of 2 cm in our experiments). More generally, Eq. (5) represents the classical...
RTI most unstable mode with an effective gravity $g \sin \alpha$. Second, the sensitivity of $\lambda_{\text{max}}$ with respect to $\alpha$ is limited when $\alpha \approx \pi/2$ (see the $\sqrt{\sin \alpha}$ in Eq. (5) and the proximity of the higher most two curves in Fig. 3(a)). Finally, a crude interpretation of Eqs. (4) and (5) would lead to the conclusion that only perfectly vertical walls prevent drops from forming. In Fig. 3(a), the dotted-dashed curve corresponding to $\alpha = 0$ is the only one fully enclosed in the stable region. In other words, the value of the earlier defined critical angle would be $\alpha_c = 0$. This is in contradiction with our experimental observation presented in Fig. 1(c) where $\alpha \approx \pi/3$ and no drops form. This paradox will be solved by the absolute/convective analysis in Sec. III, but a first insight into the mechanism at stake may be gained when evaluating the typical time scales of the problem.

We now proceed to evaluate and compare the characteristic times of the instability and of the flow. Let us define $\tau_{\text{max}}$ to be the inverse of the growth rate of the most unstable mode, i.e., $\tau_{\text{max}} = \sigma(k_{\text{max}})^{-1}$. Using Eqs. (4) and (5), we find that

$$\tau_{\text{max}} \propto \frac{1}{\sin^2 \alpha}. \quad (6)$$

Similarly, $\tau_f$ is defined as the time of advection over the wavelength $\lambda_{\text{max}}$, i.e., $\tau_f = \lambda_{\text{max}}/u_f$ yielding

$$\tau_f \propto \frac{1}{\cos \alpha \sqrt{\sin \alpha}}. \quad (7)$$

As shown in Fig. 3(b), $\tau_f$ and $\tau_{\text{max}}$ are, respectively, increasing and decreasing with $\alpha$. In particular, they intersect for a given angle denoted $\alpha^*$.* The practical implications are as such: for small angles $\alpha < \alpha^*$, we anticipate that the instability will be dominated by the flow since the time required for the instability to form ($\tau_{\text{max}}$) is much larger than the typical time needed for the same instability to flow down $\tau_f$. Conversely, at large angles, the instability develops much faster than the fluid flows, i.e., we anticipate that drops will form as if there were no flow (in the limit of very large angles $\alpha \approx \pi/2$). The distinction between these two regimes may be made rigorously in the context of a spatio-temporal analysis as detailed in the following.

### III. ABSOLUTE AND CONVECTIVE INSTABILITIES

In this section, we make use of the absolute/convective instability concepts to analyze the RTI on the underside of an inclined surface. The distinction between absolute and convective instability has been pioneered in plasma instabilities, and then more recently applied to fluid-dynamical instabilities in parallel and weakly spatially developing open flows. The nature of a given flow depends on the large-time asymptotic behavior of the linear impulse response; the flow is convectively unstable if the amplified disturbances move away from the source, conversely, the flow is absolutely unstable when amplified perturbations invade the entire flow. In contrast to the temporal stability problem where the axial wavenumber $k$ is real and one seeks a complex frequency $\omega$, the absolute/convective nature of the instability is determined by applying the Briggs-Bers zero-group velocity criterion to the dispersion relation for fully complex $(k, \omega)$ pairs. In order to determine the transition from convective to absolute instability, it is sufficient to detect the occurrence of saddle points in the characteristics of spatio-temporal instability waves, i.e., a complex value of the wavenumber $k_0$ such that

$$\frac{\partial \omega_r}{\partial k_r} = \frac{\partial \omega_i}{\partial k_r} = 0. \quad (8)$$

The discrimination between absolutely and convectively unstable flows was shown to play a crucial role in accounting for the occurrence of synchronized self-sustained oscillations in a variety of spatially developing shear flows, such as single phase wakes, hot jets, and counter-flow mixing layers. But it also explains, for instance, the transition from dripping to jetting in two-phase immiscible microfluidic co-axial injectors, as well as different regimes occurring in the pearl forming instability of a film flowing down a fiber.

In anticipation of the following analysis, we rewrite Eq. (4) in a convenient dimensionless form

$$\tilde{\omega} = i(\tilde{k}^2 - \tilde{k}^4) + \tilde{u} \tilde{k}, \quad (9)$$
where the wavenumber and angular frequency have been non-dimensionalised with the characteristic space and time scales as

$$\tilde{k} = k \frac{\ell_c}{\sqrt{\sin \alpha}} \quad \text{and} \quad \tilde{\omega} = \omega - \frac{3\ell_c^2 \mu}{\rho g h_i^3 \sin^2 \alpha}. \quad (10)$$

The non-dimensional interface velocity reads

$$\tilde{u} = \frac{3}{\sqrt{\sin \alpha \tan \alpha}} \frac{\ell_c}{h_i}. \quad (11)$$

Hereafter, both the wavenumber $\tilde{k}$ and the wavefunction $\tilde{\omega}$ are complex numbers. Denoting $\tilde{k} = \tilde{k}_r + i\tilde{k}_i$ and injecting this form in Eq. (9) yields

$$\tilde{\omega}_r = \tilde{k}_r \left( -4\tilde{k}_i^3 + \tilde{k}_i \left( 4\tilde{k}_r^2 - 2 \right) + \tilde{u} \right), \quad (12)$$

$$\tilde{\omega}_i = -\tilde{k}_i^4 + \tilde{k}_i^2 \left( 6\tilde{k}_r^2 - 1 \right) + \tilde{k}_i \tilde{u} - \tilde{k}_r^2 + \tilde{k}_r^2. \quad (13)$$

The complex group velocity writes $\tilde{v}_g = \frac{d\tilde{\omega}}{d\tilde{k}}$ and we denote $\tilde{\omega}_0$ and $\tilde{k}_0$ the absolute frequency and wavenumber, respectively. They are defined by the zero-group-velocity condition $\tilde{v}_g(\tilde{k}_0) = 0$, such that $\tilde{\omega}_0 = \tilde{\omega}(\tilde{k}_0)$. Differentiating (13) with respect to $\tilde{k}_r$ and $\tilde{k}_i$ and canceling both equations, one obtains

$$\tilde{u} = -32\tilde{k}_{0,i}^3 - 4\tilde{k}_{0,i}, \quad (14)$$

$$\tilde{\omega}_{0,i} = 1/4 - 2\tilde{k}_{0,i}^2 - 24\tilde{k}_{0,i}^4. \quad (15)$$

Note that the values of $\tilde{k}_{0,i}$ and $\tilde{\omega}_{0,i}$ are directly set by the value of the parameter $\tilde{u}$, itself function of the physical parameters $h_i/\ell_c$ and $\alpha$ (see Eq. (11)). In turn, the value of $\tilde{\omega}_{0,i}$ relative to zero sets the nature of the flow. When $\tilde{\omega}_{0,i} < 0$, the flow is convectively unstable and conversely, it is absolutely unstable when $\tilde{\omega}_{0,i} > 0$. In both cases, the flow is linearly unstable, as found earlier in Sec. II. However, those two cases lead to completely different scenarios, which is the main focus of the rest of the article. We now search for the roots of Eq. (15), which combined with Eq. (14), yields to the exact expression of the critical value of $\tilde{u} = \tilde{u}^*$ leading to a transition between the convective and absolute regimes, namely,

$$\tilde{u}^* = \frac{1}{\sqrt{27}} \sqrt{34 + 14\sqrt{7}} \approx 1.62208. \quad (16)$$

With a dispersion relation taking the form found in Eq. (9), the leading $\tilde{v}_f^+$ and receding $\tilde{v}_f^-$ front velocities of the wedge of the impulse response can be directly determined as the sum of the inherent advection $\tilde{u}$ and $\pm \tilde{u}^*$,

$$\tilde{v}_f^\pm = \tilde{u} \pm \tilde{u}^* = \tilde{u} \pm \frac{\Delta \tilde{u}_f}{2}, \quad (17)$$

where $\Delta \tilde{u}_f = \tilde{v}_f^+ - \tilde{v}_f^- = 2\tilde{u}^*$ is the width of the perturbed region. This concept is best illustrated when following the time evolution of a wavepacket generated with a localized initial perturbation. In Fig. 4, we report the time evolution of two packets generated by a Dirac impulse in $x = 0$ at $t = 0$ and observed in the laboratory frame. First, a global view of the flow as a function of time is presented in the two panels in Figs. 4(a) and 4(b). They correspond to $\tilde{\omega}_{0,i} < 0$ and $\tilde{\omega}_{0,i} > 0$, respectively. Second, the time evolution at the impulse location, $h(0,t)$, is presented in Fig. 4(c). When $\tilde{\omega}_{0,i} < 0$, the perturbation increases with time but is carried away faster than it spreads across the flow and the upstream front velocity $\tilde{v}_f^-$ of the perturbed wedge is positive. As a consequence, the perturbation at the source point ($x = 0$) decreases with time such that $h(0,t)$ is quickly indistinguishable from the vertical axis, and the instability is convective. Conversely, if $\tilde{\omega}_{0,i} > 0$, the perturbation grows exponentially in the laboratory frame despite the presence of the flow. The upstream front velocity $\tilde{v}_f^-$ of the perturbed wedge is negative, so the wavepacket counter-propagates to invade the all space, and the instability is absolute (Figure 4(b)). These examples emphasize that the absolute/convective transition is found when $\tilde{v}_f^- = 0$, i.e., $\tilde{u} = \tilde{u}^*$.  

FIG. 4. Spatio-temporal evolution of two wavepackets generated by a Dirac perturbation in $x = 0$ at $t = 0^+$ for $h_i/\ell_c \simeq 0.67$ and (a) $\alpha = \pi / 4$ and (b) $\alpha = \pi / 2.2$. Both cases are unstable, but (a) is convectively unstable, the perturbation decreases with time in $x = 0$, and conversely, (b) is absolutely unstable as the perturbation grows exponentially in the laboratory frame. Dashed lines correspond to the fronts of the perturbed wedges. (c) shows the time evolution of the relative amplitude of the perturbation at the origin in both cases.

Recalling from Eqs. (11) and (16) that $\tilde{u}$ is a decreasing function of $\alpha$ and that $\tilde{u}^*$ is constant, one may derive the critical value of the inclination $\alpha^*$ yielding the absolute/convective transition

$$\sqrt{\sin \alpha^* \tan \alpha^*} = \frac{3\ell_c}{\tilde{u}^* h_i}.$$  \hspace{1cm} (18)

We now proceed to examining the critical angle in Eq. (18). This implicit expression is solely a function of the ratio $h_i/\ell_c$, such that surface tension and gravity effects influence the problem through the capillary length $\ell_c$. On the other hand, the fluid viscosity $\mu$ does not enter in Eq. (18). This could have been anticipated as $\mu$ intervenes linearly both in the typical flow rate and in the typical droplet formation time, such that it does not affect their relative values. A practical consequence of Eq. (18) is the state diagram shown in Fig. 5 where the plot of $\alpha^*$ as a function of $h_i/\ell_c$ may be found. For a given value of $h_i/\ell_c$, the flow is absolutely unstable for angles $\alpha > \alpha^*$ and convectively unstable for $\alpha < \alpha^*$. Note that for $\alpha = \pi / 2$, all thin films with non-zero thickness are absolutely unstable since such an angle forbids any flow parallel to the substrate to compete with the instability.

In summary, the flow under an inclined plane is always linearly temporally unstable (unless $\alpha = 0$). However, two cases are possible. Depending on the respective values of $\alpha$ and $h_i/\ell_c$, the flow is either convectively or absolutely unstable. In the first case, perturbations are found to decrease in

FIG. 5. State diagram of the flow under an inclined plane in the parameter space $(h_i/\ell_c, \alpha)$. Plotted in black are the values of the critical angle $\alpha^*$ delimiting the absolute and convective domains. The two stars indicate the physical parameters used in Fig. 4.
the laboratory frame, despite the unstable nature of the flow, as they are carried away by advection. In the second, the instability is strong enough to overcome the flow. We now examine experimentally the consequences of such scenarios.

IV. EXPERIMENTS

The experiments were conducted on a test stand which consists of a base plate, two columns, and two mounting plates where the clamp assemblies that hold the experimental surface in place are free to rotate (Fig. 1(a)). The working fluid used in the experiments is Castor Oil (Hänseler AG) of viscosity 865 ± 5 cP (measured with a Bohlin C-VOR rheometer). The value of the capillary length \( \ell_c = 1.91 \text{ mm} \) was measured using axisymmetric drop shape analysis\(^\text{21} \) on a pendant drop experiment. Plexiglas was chosen to serve as support surfaces for the experiments. A grid was included in the setup to enhance the distortions of the interface. The grid was aligned parallel with the surface and placed far below the flow so as not to induce any perturbations.

A typical experiment is divided in two steps: preparation and testing. First, a fluid film is prepared on the solid surface: the surface is made horizontal and a mass \( m \) of oil is deposited in the center of the surface so that it will spread over time. Its area \( A \) increases with time, \( A \propto t^{1/4} \), while its interface remains approximately flat apart from the boundaries.\(^\text{22,23} \) Second, at a given time \( t = t_i \), the surface is gently rotated into the testing position where the fluid is beneath the surface, which makes an angle \( \alpha \) with the vertical axis \( e_z \) (Fig. 1(a)). At the beginning of the testing, the thickness of the film writes \( h_i = \frac{\pi}{\rho} \frac{1}{4 \sqrt{2} \ell_c} \). Initial film height uncertainties were, on average, ±5%. The dynamics of the film is recorded from \( t = t_i \) onward. The angle of inclination was evaluated with image analysis and was evaluated within ±0.7°.

In a typical experiment, the downstream contact line advances in the direction of the flow (Fig. 1(d)). In the meantime, the film drains downstream and, in some cases, droplets were found to form and drip (Fig. 1(b)). However, for greater inclinations, no droplets were observed to form (Fig. 1(c)). Describing the full dynamics requires complex non-linear and time evolving tools\(^\text{12} \) and is beyond the scope of this article. Instead, we propose to simply count the number of droplets formed during an experiment, keeping track of their dripping time and location. In particular, we focus on the central part of the film and denote \( N \) the number of droplets dripping from this area. The region of interest, of area \( A_i \), is defined by scaling the perimeter inwards of a length \( 2\pi \sqrt{2} \ell_c \) to avoid further complications at the contact line (see supplementary information for more details\(^\text{25} \)). To summarize, any experiment is fully characterized by the triplet

\[
(h_i/\ell_c, \alpha, \bar{N})_{\text{exp}},
\]

where \( \bar{N} = N/A_i \) denotes the density of droplets in the center part of the flow. Those data points are reported in Fig. 6 and are discussed in Sec. V.

As a side remark, note that, in the limit of very long spreading times, the ratio \( h_i/\ell_c \) directly relates to the contact angle of the fluid on the substrate. In fact, the thickness at equilibrium of a partially wetting puddle sitting on an horizontal surface may be expressed as \( h_p = 2\ell_c \sin \theta_c/2. \) By assuming the initial film thickness being the one of the puddle, \( h_p, \) the results may be represented as a function of \( \theta_c \) instead of \( h_i/\ell_c. \)

V. DISCUSSION

As inferred from Fig. 6(a), the experiments divide into two categories: experiments that do not lead to any drop \( \bar{N} = 0, \) and experiments during which several drops are formed \( \bar{N} > 0. \) As anticipated, the largest drop-density experiments are those with the smallest inclination of the substrate \( (\alpha \approx \pi/2). \) In those cases, the flow is weak and does not affect the RTI. Increasing the inclinations (decreasing \( \alpha \) when keeping other parameters fixed) yields a decrease in the number of drops. Interestingly, experiments reveal the existence of a critical angle \( \alpha_c^{\text{exp}} \) under which no droplets are found. As seen from Fig. 6, this angle is a decreasing function of \( h_i/\ell_c. \) Those observations are now rationalized using the previous theoretical results. The absolute/convective transition angle \( \alpha'(h_i/\ell_c) \) from Eq. (18) is
superimposed to the experimental results in Figs. 6(a) and 6(b) in the form of a curved transparent surface and solid black line, respectively. This theoretical prediction acts as a demarcation line between the two experimental regimes ($\bar{N} > 0$ and $\bar{N} = 0$) over the range of experimental parameters explored. The overall agreement between theory and experiment is good. We merely found a few incursions of $\bar{N} = 0$ cases in the absolutely stable domain, attributed to the migration of quasi-static pendant drops out of the domain of interest.

The existence of such a critical angle had been anticipated in the time scale analysis in Sec. II using temporal arguments. However, the spatio-temporal analysis presented in Sec. III constitutes a rigorous derivation of its exact expression. Note that expressions derived in Sec. III are consistent with the physical mechanism depicted in Sec. II. Representing Eq. (17) with dimensional terms, the existence of a critical angle results from the competition of the advection velocity $u_i = \cos \alpha \rho g \mu h_i^2$, which increases with an increasing inclination (decreasing values of $\alpha$), and the wedge spreading of the unstable region,

$$\Delta v_f \approx \frac{3.24 \rho g h_i^3 \sin^{3/2} \alpha}{3 \ell_c \mu},$$

(20)

which decreases with an increasing inclination (decreasing values of $\alpha$). A critical angle is unavoidable as an increasing inclination of the plane therefore simultaneously increases the advection and decreases the growth rate. Note that Eq. (20) may be recovered from the analysis of Ref. 26 when using the gravity component normal to the plate. In their study, Limat et al. found the wedge speed using Van Saarloos front propagation velocity theory, which is an analogue of the absolute/convective instability concept. This approach, sometimes called marginal stability criterion, consists of directly identifying the edge velocities by the following three conditions: $\frac{\partial \omega}{\partial k_i} = 0$, $v^\pm_f = \frac{\omega_i}{k_i}$, $v^+_f = \frac{\partial \omega_i}{\partial k_i}$ using the notations of Sec. III. These two methods are completely equivalent and give identical results of the absolute/convective threshold with the only difference being in the steps to solve the problem: the method following the theory by Huerre and Monkewitz, which was used in this paper, uses the zero of the imaginary part of the absolute frequency ($\omega_{0,i} = 0$) to determine the threshold while the method proposed by Van Saarloos uses a cancellation the front propagation velocity ($v^-_f = 0$). For a dispersion relation of the form of Eq. (9), where the advection is uniform and the real part of the frequency is non-dispersive, one can deduce the absolute/convective threshold from the front velocity determined in the absence of advection. In effect, the relevance of these linear edge velocities extends far beyond the intrinsic limitations expected from a linear analysis. The nonlinear front separating the base state from the invading unstable nonlinearly saturated state can be shown in many cases to inherit the linear edge velocity (see Powers et al. for an application to interfacial instabilities). This linear criterion for the nonlinear front propagation is also one of the cornerstones of modern nonlinear global mode theories (see Ref. 30 for a review).

We turn back to discussing our experimental observations in the view of the derived model. On the one hand, the agreement between experiments and theory shown in Fig. 6 was expected as the physical mechanism behind a convective instability is precisely that the flow outruns the instability,
which cannot grow locally, and therefore drop formation is prevented. Note that these experiments lie in the validity range of our lubrication model based on low Reynolds number $Re = \rho u h / \mu$. The latter, prescribing the relative magnitude of inertial effects and viscous stresses may be evaluated using the flow field parallel to the substrate $Re = (h / \ell_c)^3$ with $\ell_c = (\mu^2 / \rho g)^{1/3}$, or else considering the RTI when dominant. In such a case, the maximum growth rate of the instability is used in evaluating the inertial term, yielding $Re = h^3 / \ell_c^2 \ell_c^3$. In our experiments $\ell_c \approx 4.4 \text{ mm}, \ell_c \approx 1.91 \text{ mm},$ and $0.7 < h (\text{ mm}) < 2$ yielding $0.01 < Re < 0.1$, so that our model applies and reveals the physical mechanism at play. The geometry of the substrate, that is its inclination, stabilizes the flow. This type of geometrically induced stabilization is consistent with recent work on the dynamics of thin films on the underside of a cylinder where the curvature of the substrate, that is the local change in its slope, is shown to suppress the RTI if the film is thin enough.

On the other hand, we note the favorable agreement of theory with the experiments despite the significant differences between the experimentally obtained flow and the model depicted in Fig. 2. In particular, the model is one dimensional and our analysis is restricted to describing the linear behavior of the system, omitting the contact line propagation. In reality, dripping is inherently non-linear and the experiment is essentially three dimensional so that a fully predictive model (for example accounting for the number of drops formed) would certainly need to go beyond this linear approximation. Yet, as it often turns out in fluid mechanics, the linear predictions prove to be an acceptable representation of the problem far beyond their validity range, thereby helping in the rationalization of the observed physical reality.

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35 See supplementary material at http://dx.doi.org/10.1063/1.4927857 for details on the method used to determine the number of droplets dripping in our experiments.