On the nonlocality of the state and wave equation of Treeby and Cox

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Abstract
In this paper it is shown that the state equation of Treeby and Cox [B. E. Treeby and B. T. Cox, J. Acoust. Soc. Am. 127 5, (2010)] is nonlocal, more precisely, a local density variation causes an instant global pressure variation and a local pressure variation can only be caused by an instant global density variation. This is in contrast to all frequency dependent dissipative state equations known to the author. Moreover, it is shown that the Green function $G$ of the wave equation of Treeby and Cox cannot have a finite wave front speed, i.e. there exists no finite $c_F > 0$ such that

$$G(x, t) = 0 \quad \text{for} \quad |x|/c_F > t$$

holds, where $|x|/c_F$ corresponds to the travel time of a wave propagating with speed $c_F$ from point $0$ to point $x$. As a consequence, the density and pressure waves satisfying (i) the state equation of Treeby and Cox, (ii) the equation of motion and (iii) the equation of continuity do not have a finite wave front speed.

1 Introduction

By the authors of [6], the pressure state equation

$$p = c_0^2 \rho - a_0 (-\Delta)^{\gamma-1} \frac{\partial \rho}{\partial t} - b_0 (-\Delta)^{\gamma-1/2} \rho$$

with constants $\gamma \in (0, \frac{1}{2}) \cup (\frac{3}{2}, 3)$, $c_0 > 0$, $a_0(\gamma) > 0$ and $b_0 = -a_0 c_0 \tan(\pi \gamma)$ was postulated for some dissipative media arising in biological and medical
applications. Based on this state equation, they also derived the pressure wave equation

\[ \frac{\partial^2 p}{\partial t^2} + a_0 (-\Delta)^\gamma \frac{\partial p}{\partial t} + b_0 (-\Delta)^{\gamma+1/2} p - c_0^2 \Delta p = 0, \tag{2} \]

which is an extension of the wave equation of Chen and Holm modeled by the authors of [1]. That the latter wave equation does not have a finite wave front speed was shown by the authors of [3]. In this paper, we investigate the following two issues arising from the model of Treeby and Cox for

\[ c_0 > 0, \quad a_0 > 0, \quad b_0 \in \mathbb{R} \quad (\text{all independent of } \gamma) \quad \text{and} \quad \gamma > 0. \tag{3} \]

a) Nonlocality of the state equation

The state equation of standard dissipative pressure waves has the form

\[ p(x, t) = c_0^2 \int_0^t K_1(t-s) \rho(x, s) \, ds \quad (x \in \mathbb{R}^3, t \in \mathbb{R}) \tag{4} \]

for any density variation initiated at time \( t = 0 \) and kernel \( K_1 \) satisfying

\[ K_1(t) = 0 \quad \text{for} \quad t < 0 \quad (a \text{ causality condition}). \tag{5} \]

This state equation is local and consequently if \( \rho \) is a density wave with finite wave front speed, then the pressure wave satisfying the state equation \( \text{[4]} \) has a finite wave front speed, too.

In contrast, we show in this paper that the state equation of Treeby and Cox is nonlocal for \( \gamma > 0 \), i.e.

- a local density variation \( \delta \rho \) causes an instant global pressure variation \( \delta p \)
- a local pressure variation \( \delta p \) can only be caused by an instant global density variation \( \delta \rho \).

As a consequence, if \( \rho \) denotes a density wave with finite wave front speed, then the pressure wave defined by the state equation of Treeby and Cox does not have a finite wave front speed. Obviously, this behavior violates cause and effect, at least in the framework of classical physics. In addition, this nonlocal behavior is in contrast to all frequency dependent dissipative state equations known to the author (cf. [1, 5, 7, 8]).
b) Infinite speed of the wave front

The state equation not only relates the pressure with the density, but in combination with the equation of motion and equation of continuity, it implies a density wave equation. As a consequence, it determines the causal behavior of the respective density wave, too. We show that the density wave as well as the pressure wave implied by the Treeby and Cox model do not have a finite wave front speed \( c_F \) for \( \gamma > 0 \). More precisely, if \( G \) denotes the Green function of the density wave equation, then for every \( c_F > 0 \)

\[
G(x, t) = 0 \quad \text{for} \quad |x|/c_F > t
\]

(6)
does not hold. Here \(|x|/c_F\) corresponds to the travel time of a wave front traveling with speed \( c_F \) from point 0 to point \( x \). The physical interpretation of Eq. (6) is as follows: Consider a dissipative spherical wave, i.e. \( G \), generated in location 0 at time 0. Then an observer in location \( x \in \mathbb{R}^3 \setminus \{0\} \) feels the wave not before the travel time \(|x|/c_F|\) had passed. If he feels the wave sooner the wave front speed is larger than \( c_F \) and otherwise it is smaller. However, if he feels it for every arbitrary small time period, then \( c_F = \infty \).

Because the wave front speed of a non-dissipative wave is finite, it seems not reasonable that a dissipative wave model has an infinite wave front speed.

Remark 1. If we consider the "reversed" state equation

\[
\rho(x, t) = c_0^{-2} \int_0^t K_2(t-s)p(x, s)\, ds
\]

with \((K_2 \ast_1 K_1)(t) = \delta(t)\), then condition (5) with \( K_1 \) replaced by \( K_2 \) corresponds to the Kramer-Kronig relations which are satisfied for all standard frequency dependent dissipation models known to the author (cf. [4], [5], [7], [3]). As above, it follows that the Kramer-Kronig relations imply a finite wave front speed for the wave \( \rho \) (output of linear system), if the wave \( p \) (input) has a finite wave front speed [3]. However, it does not follow that the pressure wave \( p \) (input) satisfying, in addition, the equation of motion and equation of continuity has a finite wave front speed. This is partly a misapprehension in the literature. For more detail, we refer to [2], [3].

This paper was written with the intention to keep its contents as short and simple as possible such that it is readable for a broad range of physicists and applied mathematicians. It is organized as follows. First, we investigate and discuss the properties of state equations of dissipative media. Second,
we show that the density wave and the pressure wave of the Treeby and Cox model do not have a finite wave front speed. For the convenience of the reader, we put the mathematical part of this paper in a self-contained appendix.

2 Properties of the state equation

In this section we show the nonlocality of the state equation \( \Box \) of Treeby and Cox. For a better understanding, we shortly discuss the non-dissipative and the frequency dissipative case. In what follows, \( \delta(x) \) and \( \delta(t) \) denote the dirac distribution on \( \mathbb{R}^3 \) and \( \mathbb{R} \), respectively.

**Dissipation-free case**

For a non-viscous fluid the state equation can be modeled by

\[
p = c_0^2 \rho,
\]

which is nothing else but Eq. \( \Box \) for \( \gamma = 0 \) with \( a_0 = 0 \) and \( b_0 = 0 \). As a consequence, we have

\[
\delta \rho(x, t) = \delta(x - x_0) \delta(t) \quad \Leftrightarrow \quad \delta p(x, t) = c_0^2 \delta(x - x_0) \delta(t),
\]

i.e. a local density variation \( \delta \rho \) in point \( x_0 \) at time \( t = 0 \) causes a local pressure variation \( \delta p \) in the same point at the same time and vice versa. Due to this local behavior in space and time, \( p \) has a finite wave front speed if and only if \( \rho \) has a finite wave front speed.

**Standard frequency dependent case**

For the case of standard frequency dependent dissipation, the state equation

\[
p = c_0^2 (K_1 \ast_t \rho)
\]

satisfying the causality condition \( \Box \) implies

\[
\delta \rho(x, t) = \delta(x - x_0) \delta(t) \quad \Rightarrow \quad \delta p(x, t) = c_0^2 K_1(t) \delta(x - x_0),
\]

i.e. a local density variation \( \delta \rho \) in point \( x_0 \) at time \( t = 0 \) causes a local pressure variation \( \delta p \) in the same point for the time points \( t \geq 0 \). We still have a local behavior in space, but also a memory effect modeled by the function \( t \mapsto K_1(t) \). Due to \( K_1 = K_1(t) \) and causality condition \( \Box \), \( p \) has a
finite wave front speed, if \( \rho \) has a finite wave front speed. Mathematically, this means that the statement

\[
\rho(x, t) = 0 \quad \text{for} \quad \frac{|x|}{c_F} > t \quad \Rightarrow \quad (K_1 * t \rho)(x, t) = 0 \quad \text{for} \quad \frac{|x|}{c_F} > t
\]

holds.

**Model case of Treeby and Cox**

The following statement concerning the distribution

\[
A^\gamma(x) := (-\Delta)^\gamma \delta(x) \quad \text{for} \quad \gamma > 0 \quad \text{with} \quad \gamma \not\in \{1, 2, 3, \ldots\} \quad (7)
\]

is shown in the appendix (cf. Example 1):

(A) For every \( n \in \mathbb{N} \) there exists an \( x_n \in \mathbb{R}^3 \) with \( |x_n| \geq n \) such that

\[A^\gamma(x_n) \quad \text{does not vanish}\]

for \( \gamma > 0 \) with \( \gamma \not\in \{1, 2, 3, \ldots\} \). In particular, this means that \((-\Delta)^\gamma\) is not a local operator for \( \gamma > 0 \) with \( \gamma \not\in \mathbb{N} \).

From the state equation (1) for \( \gamma > 0 \), it follows that

\[
\delta p(x, t) = \delta(x) \delta(t) \quad \Rightarrow \quad \delta p(x, t) = \left[ c_0^2 \delta(x) - b_0 A^{\gamma-1/2}(x) \right] \delta(t) - a_0 A^{\gamma-1}(x) \delta'(t).
\]

Because \( \gamma - 1/2 \in \{1, 2, 3, \ldots\} \) excludes \( \gamma - 1 \in \{1, 2, 3, \ldots\} \) and vice versa, property (A) implies (for fixed \( \gamma > 0 \) and \( t > 0 \)) that for every \( n \in \mathbb{N} \) there exists an \( x_n \in \mathbb{R}^3 \) with \( |x_n| \geq n \) such that

\[\delta p(x_n, t) \quad \text{does not vanish.}\]

From this and the fact that the distributions \( \delta(t) \) and \( \delta'(t) \) appear in the pressure variation, we infer that \( \delta p \) is an instant global pressure variation caused by a density variation concentrated in a point in space and time. Hence the state equation is not local and if \( \rho \) has a finite wave front speed, then \( p \) does not have a finite wave front speed.

**3 Density and pressure waves of the Treeby and Cox model**

In this section we show that the density and pressure waves of the Treeby and Cox model do not have a finite wave front speed. For that purpose we start with the derivation of the two governing wave equations.

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\[\text{Notice that } |A(x_n)| \text{ may be small for large } n, \text{ but it does not vanish.}\]
Two wave equations

The state equation of Treeby and Cox (1) can be written as follows
\[ p = c_0^2 K *_{x,t} \rho \] (space-time convolution), \( (8) \)

with \( A^\gamma \) defined as in Eq. (7) and
\[ K(x, t) := \delta(x) \delta(t) - \frac{a_0}{c_0^2} A^{\gamma-1}(x) \delta'(t) - \frac{b_0}{c_0^2} A^{\gamma-1/2}(x) \delta(t) . \] (9)

Inserting this state equation into the linearized Euler and continuity equations, i.e.
\[ \rho_0 \frac{\partial v}{\partial t} = -\nabla p - f_0 \quad \text{and} \quad \frac{\partial \rho}{\partial t} + \rho_0 \nabla \cdot v = 0 \]
yields the wave equations
\[ K *_{x,t} \Delta \rho - \frac{1}{c_0^2} \frac{\partial^2 \rho}{\partial t^2} = -\frac{1}{c_0^2} f , \] (10)

and
\[ K *_{x,t} \Delta p - \frac{1}{c_0^2} \frac{\partial^2 p}{\partial t^2} = -K *_{x,t} f , \] (11)

with \( f := \nabla \cdot f_0 \). Conversely, the state equation (8) can be inferred from these wave equations. If \( K^\dagger \) is such that \((K^\dagger *_{x,t} K)(x, t) = \delta(x) \delta(t)\), then Eq. (11) reads as follows
\[ \Delta p - \frac{1}{c_0^2} K^\dagger *_{x,t} \frac{\partial^2 p}{\partial t^2} = -f , \]
i.e. it is not the same wave equation as in Eq. (10). In particular, we see that the modeling of the correct source terms of dissipative waves are crucial.

The Green function of Eq. (10) is defined by
\[ \frac{\partial^2 G}{\partial t^2} + a_0 \frac{\partial}{\partial t} (-\Delta)^\gamma G + b_0 (-\Delta)^{\gamma+1/2} G - c_0^2 \Delta G = \delta(x) \delta(t) \] (12)

from which we infer
\[ \rho = \frac{1}{c_0^2} f *_{x,t} G \quad \text{and} \quad p = f *_{x,t} K *_{x,t} G . \]

We see that \( \rho \) has a finite wave front speed if and only if \( G \) has a finite wave front speed.
Derivation of the Green function of Eq. (10)

Fourier transform of Eq. (12) with respect to $x$ yields the Helmholtz equation

$$\frac{\partial^2 \hat{G}}{\partial t^2} + a_0 k^\gamma \frac{\partial \hat{G}}{\partial t} + (c_0^2 k^2 + b_0 k^{\gamma+1/2}) \hat{G} = \frac{\delta(t)}{(2\pi)^{3/2}}. \quad (13)$$

Here $k := |k|$ denotes the wave number corresponding to the wave vector $k \in \mathbb{R}^3$. Inserting the ansatz

$$\hat{G}(k, t) = [A_1 e^{-\lambda_1 t} + A_2 e^{-\lambda_2 t}] H(t) \quad (H \text{ Heaviside function}) \quad (14)$$

into the Helmholtz equation leads to the equations

$$A_1 + A_2 = 0, \quad (\lambda_1 A_1 + \lambda_2 A_2) = -\frac{1}{(2\pi)^{3/2}} \quad (15)$$

and

$$\lambda_1^2 - a_0 k^\gamma \lambda_1 + (c_0^2 k^2 + b_0 k^{\gamma+1/2}) = 0. \quad (16)$$

Hence

$$\hat{G}(k, t) = i2 A_1(k) e^{-\mu(k)t} \sin(\vartheta(k)t) \quad \text{for } t > 0,$$

where $\lambda_j = \mu + i (-1)^{j-1} \vartheta$ with

$$\mu = \frac{1}{2} a_0 k^\gamma \quad \text{and} \quad \vartheta = c_0 k \sqrt{1 - \frac{a_0^2}{4 c_0^2} k^2 - \frac{b_0}{c_0^2} k^{\gamma-3/2}} \quad (17)$$

for $j = 1, 2$. Solving Eqs. (15) with respect to $A_1$ and $A_2$ yields

$$A_1 = \frac{i}{(2\pi)^{3/2} 2 \vartheta} \quad \text{and} \quad A_2 = -A_1 \quad (18)$$

and thus we end up with

$$\hat{G}(k, t) = \frac{e^{-\mu(k)t}}{(2\pi)^{3/2}} \frac{\sin(\vartheta(k)t)}{\vartheta(k)} H(t). \quad (19)$$

We note that this identity holds for $\vartheta(k) \in \mathbb{R}$ as well as for $\vartheta(k) \in i\mathbb{R}$.

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3For wave attenuation, it is required that $\mu$ is positive and thus the constant $a_0$ has to be positive. Indeed, this is part of our general assumption in Eq. (3).
Wave front speed of $G$

In the Appendix (cf. Examples 2 and 3 and Remark 4), it is shown that the support of the Green function $G$ as well as $p := c_0^2 K *_{x,t} G$ cannot be bounded, i.e. for every $n \in \mathbb{N}$ there exists an $x_n \in \mathbb{R}^3$ such that

$$G(x_n, t) \text{ does not vanish for } |x_n| \geq n,$$  \hfill (20)

where $t > 0$ and $\gamma > 0$ are fixed. Does this mean that the wave front speed of $G$ is not finite? Assume that $c_F$ is finite. Then the travel time of the wave front traveling from point $0$ to point $x$ is given by

$$T(|x|) = \frac{|x|}{c_F},$$

and we expect

$$G(x, t) = 0 \quad \text{ for } \quad T(|x|) > t.$$  

But, due to property (20) this does not hold for $x_n$ with $n > c_F t$. This contradiction shows that $c_F < \infty$ does not hold, i.e. there exists no finite wave front speed $c_F$ of $G$, $\rho$ and $p$.

4 Conclusions

In this paper we showed that the state equation of Treeby and Cox establishes a nonlocal relationship $p = F(\rho)$ between the density $\rho$ and the pressure $p$. As a consequence, it follows if the density wave $\rho$ has a finite wave front speed, then the respective pressure wave $p = F(\rho)$ does not have a finite wave front speed. This is in contrast to the state equations for the frequency dependent dissipation models, which satisfy the Kramer-Kronig relation. Moreover, we showed that any density wave satisfying

- the state equation of Treeby and Cox,
- the equation of motion and
- the equation of continuity

cannot have a finite wave front speed. Similarly, it follows that the respective pressure wave does not have a finite wave front speed.

In summary, we have shown that the state equation of the Treeby and Cox violate causality and that the respective density and pressure waves violate causality in the sense that they do not have a finite wave front speed. Thus it
is not an appropriate substitution for those frequency dependent dissipation models that obey causality.

The model might be corrected by modeling a kernel $K$ similarly to Eq. (9) which satisfies at least the following modification of Eq. (5):

$$K(x, t) = 0 \quad \text{for} \quad t < \frac{|x|}{c_0}.$$ 

However, an analysis of the respective wave equation for the density is far more complicated than that one presented in this paper. Such an analysis of an appropriate model is beyond the scope of this paper.

## 5 Appendix: Applications of the Paley-Wiener Theorem

In this section we focus on the pure mathematical part of this paper that permits to conclude crucial physical statements. In essence, we employ the first (and simplest) part of the Paley-Wiener Theorem which is well-known from signal and image processing. In what follows, $\hat{f}$ denotes the Fourier transform of $f$ with respect to the space variable $x$. The Paley-Wiener Theorem reads as follows:

**Theorem 1** (Paley, Wiener). Let $n \in \mathbb{N}$, $|z| := \sqrt{\sum_{j=1}^{n} |z_j|^2}$ for $z \in \mathbb{C}^n$ and $R > 0$. The support of a distribution $f$ is contained in the closed ball $B_R(0)$ if and only if

$$(PW1) \quad \hat{f} = \hat{f}(k) \ (k \in \mathbb{R}^n) \text{ can be extended to a holomorphic function } g = g(z) \ (z \in \mathbb{C}^n) \text{ satisfying } \hat{f}(z) = g(z) \text{ and}$$

$$(PW2) \text{ there exist constants } C > 0 \text{ and } N > 0 \text{ such that}$$

$$|g(z)| \leq C(1 + |z|)^N e^{R|\text{Im}(z)|} \quad \text{for} \quad z \in \mathbb{C}^3.$$ 

The previous Theorem states that if a function or distribution $f$ is such that $g : z \mapsto \hat{f}(z)$ is not holomorphic, then $\hat{f}$ cannot have a bounded support in the closed ball $B_R(0)$ for any $R > 0$. $g$ is not holomorphic means that at least one of the following properties are not satisfied:

$$(H1) \text{ the function } z_j \mapsto g(z_1, \ldots, z_j, \ldots, z_n) \text{ is holomorphic for every } j \in \{1, 2, \ldots, n\} \text{ and}$$
(H2) $g$ is locally bounded, i.e. for each point $w \in \mathbb{C}^n$ there exist constants $M > 0$ and $\epsilon > 0$ such that $|g(z)| \leq M$ for all $z \in B_{\epsilon}(w)$.

In what follows, these facts are used to show the nonlocality of the state equation of Treeby and Cox and the infinite speed of the solutions of the density and pressure wave equation of Treeby and Cox.

Remark 2. For models of wave dissipation, the second condition of the Paley-Wiener Theorem is usually satisfied for vectors of real numbers, because $\hat{f}: \mathbb{R} \rightarrow \mathbb{R}$ decreases exponentially. However, the significance of this condition is due to its validity for all vectors of complex numbers. Frequently, $f$ is not contained in a closed ball of finite radius due to the fact that $\hat{f}$ is holomorphic, but there exists a sequence of complex vectors $z_n \in \mathbb{C}^3$ for $n \in \mathbb{N}$ such that $(|g(z_n)|)_{n \in \mathbb{N}}$ does not decrease exponentially for $n \rightarrow \infty$, but increases much faster than $(e^{C|z_n|})_{n \in \mathbb{N}}$, where $C > 0$ is a constant. For example, it may increase like $(e^{C|z_n|^2})_{n \in \mathbb{N}}$.

Nonlocality of $(-\Delta)^{d/2}$ for $d > 0$ with $d \notin \{2, 4, 6, \ldots\}$

In our first example, we exploit the fact that $k \in \mathbb{R}^3 \mapsto |k|^d$ is not infinitely differentiable at zero, if $d > 0$ with $d \notin \{2, 4, 6, \ldots\}$ and show property (A) stated in Section 2.

For example, consider the function $f(k) := |k|^3$ for which we have

$$\frac{\partial^2 f}{\partial k_1^2}(k) = \frac{3k_1^2}{|k|} + 3|k|.$$ 

Due to the rule of de l’Hospital, we see that this function is everywhere continuous, however, the second term has an edge at $k = 0$ and thus it is not differentiable with respect to $k_1$ at zero. Moreover, for $d = 2m$ with $m \in \mathbb{N}$, we have $|k|^d = (k_1^2 + k_2^2 + k_3^2)^m$ and thus $k \in \mathbb{R}^3 \mapsto |k|^{2m}$ is infinitely differentiable.

Example 1. Property (PW1) is not satisfied for

$$f := (-\Delta)^{d/2}\delta(x) \quad \text{if} \quad d > 0 \quad \text{with} \quad d \notin \{2, 4, 6, \ldots\}.$$ (21)

Indeed, Fourier transform of $f$ yields

$$\hat{f}(k) = [-(i|k|)^2]^{d/2}(2\pi)^{-3/2} = (2\pi)^{-3/2}|k|^d,$$

where $k_1 \in \mathbb{R} \mapsto |k_1|^d$ is not infinitely differentiable (for $d > 0$ and $d \notin \{2, 4, 6, \ldots\}$) and thus $z_1 \in \mathbb{C} \mapsto |z_1|^d$ is not holomorphic. Because (H1) does
not hold, it follows that \( z \in \mathbb{C}^3 \mapsto |z|^d \) is not holomorphic and consequently \( \hat{f} \) is not holomorphic, too. This shows that property (PW1) of the Paley-Wiener Theorem is not satisfied for \( f \) defined as in Eq. (21) and hence the support of \( f \) cannot lie in an open ball of finite radius. In other words, for every \( n \in \mathbb{N} \) there exists an \( x_n \in \mathbb{R}^3 \) with \( |x_n| \geq n \) such that

\[
f(x_n) \text{ does not vanish.} \tag{22}
\]

**Remark 3.** What do we mean by Eq. (22), if \( f \) is a distribution? It means that for arbitrary small \( \epsilon > 0 \), the restriction of the distribution \( f \) to the set \( B_\epsilon(x_n) \) is not the zero function (=zero distribution), where \( B_\epsilon(x_n) \) denotes the open ball with center \( x_n \) and radius \( \epsilon \). In other words, the integral of \( f \) over \( B_\epsilon(x_n) \) does not vanish for arbitrary small \( \epsilon > 0 \).

**Unbounded support of \( G \)**

Let \( f \) be a distribution with a Fourier transform of the form

\[
\hat{f}(k) = g(\theta(k)) h(k), \tag{23}
\]

where \( g, h : \mathbb{R} \to \mathbb{R} \) are well-defined and nice functions. From the product and chain rule of differentiation, it follows that \( \hat{f} \) is not \( n \)-times differentiable at zero if

a) \( \theta(k) \) is not \( n \)-times differentiable at \( k = 0 \) and

b) \( h(0) \neq 0 \) and \( g'(\theta(0)) \neq 0 \).

For example,

\[
\frac{\partial^2 \hat{f}}{\partial k^2_1}(0) = \frac{\partial^2 \theta}{\partial k^2_1}(0) g'(\theta(0)) h(0) + \cdots ,
\]

i.e. \( \hat{f} \) is not two times differentiable at zero if \( \theta \) is not two times differentiable at zero, \( h(0) \neq 0 \) and \( g'(\theta(0)) \neq 0 \).

**Example 2.** Let \( T > 0 \), \( \gamma > 0 \) with \( \gamma \notin \{2, 4, 6, \ldots \} \) and the function \( f \) be such that its Fourier transform is as in Eq. (23) with

\[
g(s) = e^{-s^T}, \quad \theta(k) = |k|^\gamma \quad \text{and} \quad h(0) \neq 0.
\]

Because \( g'(0) \neq 0 \) and \( \theta \) is not \( n \)-times differentiable for \( n \geq \gamma \) with \( n \in \mathbb{N} \), it follows that \( \hat{f} \) is not \( n \)-times differentiable. Hence, \( \hat{f} \) is not holomorphic on \( \mathbb{C}^3 \) and thus, due to the Paley-Wiener Theorem, the distribution \( f \) does not have a bounded support. In other words, for every \( n \in \mathbb{N} \) there exists an \( x_n \in \mathbb{R}^3 \) with \( |x_n| \geq n \) such that

\[
f(x_n) \text{ does not vanish.}
\]
The Green function of the density wave equation of Treeby and Cox (cf. Eqs. \ref{eq:25} and \ref{eq:27}) has the same form as in Example 2, where
\[ h(k) = \sin(\vartheta(|k|)t) \frac{H(t)}{(2\pi)^{3/2}} \]
with
\[ \vartheta = c_0 \sqrt{|k|^2 - \frac{a_0^2}{4c_0^2} |k|^{2\gamma} + \frac{b_0}{c_0^2} |k|^{\gamma+1/2}}. \]
Because \( h(0) \neq 0 \) holds for \( t > 0 \), Example 2 implies that for every \( n \in \mathbb{N} \) there exists an \( x_n \in \mathbb{R}^3 \) with \( |x_n| \geq n \) such that \( G(x_n, t) \) does not vanish, for fixed \( t > 0 \) and \( \gamma > 0 \) with \( \gamma \notin \{2, 4, 6, \ldots\} \). The remaining cases \( \gamma \in \{2, 4, 6, \ldots\} \) follow from the next example. For this example, we require the second part of the Paley-Wiener Theorem.

**Example 3.** Let \( f \) be as in Example 2 with \( \gamma \in \{2, 4, 6, \ldots\} \) and
\[ h(i^{2/\gamma} k_1, 0, 0) \geq D > 0 \quad \text{for} \quad k_1 \to \infty \quad (24) \]
hold for some constant \( D > 0 \). Then \( f \) does not have a bounded support. We assume that \( f \) has bounded support and show a contradiction. For \( d := \gamma/2 \) we have
\[ |k|^\gamma = (k_1^2 + k_2^2 + k_3^2)^d \]
and consequently \( z \in \mathbb{C}^3 \mapsto |k|^\gamma \) is holomorphic. Moreover, for \( z = (i^{1/d} k_1, 0, 0) \) with \( k_1 > 1 \), we have
\[ |z|^\gamma = (i^{1/d} k_1)^{2d} = -k_1^\gamma \leq -k_1^{1/2} < 0 \]
and
\[ 0 < \text{Im}(i^{2/\gamma} k_1) \leq k_1 \quad \text{for} \quad k_1 > 0. \]
Hence, for this choice of \( z \), condition (PW2) of the Paley-Wiener Theorem with property (24) implies that there exist constants \( C > 0 \) and \( N > 0 \) such that
\[ D \exp(T k_1^2) \leq C (1 + k_1)^N \exp(R k_1) \quad \text{for} \quad |k_1| \to \infty. \]
But this inequality cannot hold for positive constants \( D, T, C, N \) and \( R \). This contradiction shows that the support of \( f \) cannot lie in an open ball of finite radius \( R \).

\[ ^4 \text{The crucial point is that the left hand side is not decreasing but increasing for an appropriate sequence of complex numbers.} \]
Let $\gamma \in \{2, 4, 6, \ldots\}$ and $k = (i^{2/\gamma} k_1, 0, 0)$ for $k_1 > 1$. For the Green function $G$ of the density wave equation of Treeby and Cox, we have

\[
    h := \frac{\sin(\vartheta t)}{\vartheta} \quad \text{and} \quad \vartheta(i^{2/\gamma} k) \approx i \frac{a_0}{2} k_1^\gamma \quad \text{for large } k_1 > 1
\]

and thus, due to $\sin(i x) = i \sinh(x)$,

\[
    h(i^{2/\gamma} k) \approx \frac{2 \sinh(a_0^2 t k_1^\gamma)}{a_0 k_1^\gamma} \quad \text{for large } k_1 > 0.
\]

But this means that property (24) holds and therefore the support of $G$ cannot lie in an open ball of finite radius due to Example 3.

**Remark 4.** The above examples show that the Green function of the density wave of Treeby and Cox does not have a finite wave front speed, but what does this mean for the respective pressure wave $p_G := c_0^2 (K_1 *_{x,t} G)$?

Let $\gamma > 0$ with $\gamma \notin \{2, 4, 6, \ldots\}$. Then it is easy to see that

\[
    \hat{p}_G(k, t) = c_0^2 \hat{G}(k, t) - a_0 |k|^{2(\gamma-1)} \frac{\partial \hat{G}}{\partial t}(k, t) - b_0 |k|^{2\gamma-1} \hat{G}(k, t)
\]

is not infinitely differentiable, because $\hat{G}(k, t)$ is not infinitely differentiable. If $\gamma \in \{2, 4, 6, \ldots\}$, then property (PW2) of the Paley-Wiener Theorem does not hold, because

\[
    |\hat{p}_G(i^{2/\gamma} k_1, 0, 0, t)| \quad \text{grows like} \quad \exp(C k_1^2) \quad \text{for } k_1 \to \infty,
\]

where $C > 0$ is a constant. As in Examples 2 and 3, it follows that for every $t > 0$ the support of $p_G(\cdot, t)$ cannot lie in an open ball of finite radius.

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