Analysis of a chemotaxis system modeling ant foraging

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Abstract

In this paper we analyze a system of PDEs recently introduced in [P. Amorim, Modeling ant foraging: a chemotaxis approach with pheromones and trail formation], in order to describe the dynamics of ant foraging. The system is made of convection-diffusion-reaction equations, and the coupling is driven by chemotaxis mechanisms. We establish the well-posedness for the model, and investigate the regularity issue for a large class of integrable data. Our main focus is on the (physically relevant) two-dimensional case with boundary conditions, where we prove that the solutions remain bounded for all times. The proof involves a series of fine a priori estimates in Lebesgue spaces.

Keywords. Ant foraging, Chemotaxis, Animal movement, Reaction-diffusion equations.

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1 Introduction

One of the most interesting phenomena arising in the collective behavior of ants is the formation of trails. Indeed, while each individual ant has a very limited cognitive ability, the population as a whole is capable of complex, organized collective behavior, such as brood rearing, waste management or fungus gardening. Even more striking is the fact that many of these activities, especially trail formation (which occurs during foraging, migration, or aggression), are essentially leaderless and yet highly organized.

Many tools have evolved in ant societies to allow for this sort of complex, so-called emergent behavior. One of the most important is the use of pheromones

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as a means of communication between individuals. Pheromones are chemical compounds secreted by ants (and many other species of animals) which are used to convey information between individuals and to signal different states, such as presence of food or alarm. Each pheromone triggers a corresponding behavior in individuals: when an ant detects alarm pheromone, it becomes itself alarmed and secretes more pheromone, leading to a chain reaction among the population, whose effect is to elicit an apparently organized defense response.

We are interested here in the trail-following behavior of ants, which is triggered in part by trails of pheromones. When an individual ant, foraging at random, encounters a food source, it typically travels back to the nest leaving on the substrate a trail of pheromone. When other ants encounter the trail, they follow it in the direction of the food, and upon finding the food, they head back to the nest and deposit more pheromone. Thus, as long as food is available, the trail will be reinforced and the food will be removed efficiently. Conversely, when the food is exhausted, the evaporation and diffusion of the pheromone quickly erase the trail, when it is no longer being reinforced.

The dynamics of ant foraging behavior has recently come under increased interest from mathematicians trying to find suitable frameworks in which to analyze this behavior. We refer the reader to the recent works [2, 3, 4, 30], among others. In [2] (see also the independent work [3]), a system of PDEs, see (SPD) below, is introduced in order to describe the dynamics of ant foraging. Roughly speaking, the population splits into two parts: the ants searching for food, and the ants going back to the nest, and the pheromone production is interpreted as a chemotactic mechanism that drives the population to privileged directions. The discussion on the modeling issues in [2] is complemented by a set of convincing numerical simulations that illustrate the ability of the model to reproduce relevant behaviors of ant populations. Here, we aim at analysing the mathematical properties of these equations.

More generally, finding relevant models able to reproduce the formation of the space-time heterogeneous patterns observed in life sciences is becoming a very active field, particularly motivated by the landmark contributions of T. Vicsek et al [32], and F. Cucker and S. Smale [9, 10] about the formation of flocks in large populations of birds or fish. The key feature relies on the transmission by the individuals of the information contained in their close environment, so that the whole population organizes according to remarkable patterns. In this vein, various models have been introduced, which have led to original problems for mathematical analysis and fascinating numerical simulations that reproduce certain features of natural phenomena; we refer the reader to the surveys [24, 33] for an overview on the subject. Here, following [2], we are interested in continuum models, where populations are described by their local concentrations. The interaction between the individuals can be thought of through a certain potential, which is defined self–consistently, thus depending on the variations of the concentrations. This is reminiscent to the theory of chemotaxis, which dates back to C. Patlak [28] and E. Keller–L. Segel [22, 23] to model the behavior of certain bacteria and slime molds, which are attracted to chemical substances that they themselves secrete. In particular, the possible formation in finite time
of singularities in the solutions of the Keller–Segel equations, the concentration into Dirac masses corresponding to the aggregation of the population into a single location, has motivated a huge amount of mathematical works, see for instance \[16, 21, 29\]. By now, the mathematical theory of the Keller–Segel system is well established, and we refer the reader to the surveys \[17, 18, 19\] for further information and references. To describe interaction mechanisms between living organisms by chemotactic principles has been successfully adapted to many different situations, see e. g. \[8, 12, 13, 14, 20, 27, 31\] to mention a few.

To be more specific, in this paper, we study the basic mathematical theory for nonnegative solutions \((t, x) \mapsto (u, w, p, c)(t, x)\) of the following model for ant foraging

\[
\begin{align*}
\partial_t u - \Delta u + \nabla \cdot (u \chi \nabla p) &= -uc + wN, \\
\partial_t w - D_w \Delta w + \nabla \cdot (w \nabla v) &= uc - wN, \\
\partial_t p - D_p \Delta p &= Pw - \delta p, \\
\partial_t c &= -uc.
\end{align*}
\]

In this system of PDEs, the unknowns are

- the density of foraging ants \(u\),
- the density of returning ants \(w\): it describes the ants which have found food and are returning to the nest,
- the concentration of the pheromone \(p\),
- the distribution of the food \(c\).

These nonnegative quantities depend on time \((t \geq 0)\) and space \((x \in \Omega \subset \mathbb{R}^n)\) variables. The data of the problem are

- the site of the nest, embodied into the function \(x \mapsto N(x)\),
- a function \(x \mapsto P(x)\) that describes the pheromone deposition as returning ants approach the nest; typically this function decreases as the distance to the nest decreases,
- a nest-bound vector field \(x \mapsto \nabla v(x)\) representing the speed of the ants when returning to the nest (it might contain information on the topography, obstacles...),
- Diffusion, sensitivity and evaporation coefficients \(D_w, D_p, \chi, \delta\), which are all positive constants.

The system \((\text{SPD})\) will be addressed in the sequel as the **Slow Pheromone Diffusion** model as the pheromone diffusion time scale is comparable to that of the dynamics of the ant foraging. We refer the reader to [2] for details on the biological motivation for system \((\text{SPD})\). In what follows, we will take \(P \equiv 1\) and
\( D_p = D_w = \chi = 1 \) for the sake of simplicity. We will study the system (SPD) on the whole Euclidean spatial domain \( \mathbb{R}^2 \) with a few comments applying to dimension \( n = 3 \).

We will also work with the simplified situation where the pheromone diffusion time scale is small compared to the dispersal of the ants. In addition, we suppose that there exists a very abundant, or renewable, food source \( 0 \leq c := c(x) \), so that we can assume it is a given function of space. These simplifying assumptions lead us to the following reduced system, with unknowns \((t, x) \mapsto (u, w, p)(t, x)\)

\[
\begin{aligned}
\partial_t u - \Delta u + \nabla \cdot (u \nabla p) &= -uc + wN, \\
\partial_t w - \Delta w + \nabla \cdot (w \nabla v) &= uc - wN, \\
- \Delta p &= w - \delta p.
\end{aligned}
\]

It will be referred to as the **Fast Pheromone Diffusion** model. This system will be considered in a domain \( \Omega \subset \mathbb{R}^2 \) having a smooth boundary \( \partial \Omega \). In order to conserve the total mass of ants, we impose the following zero-flux boundary conditions

\[
\nabla u \cdot n \bigg|_{\partial \Omega} = (w \nabla v - \nabla w) \cdot n \bigg|_{\partial \Omega} = \nabla p \cdot n \bigg|_{\partial \Omega} = 0,
\]

where \( n \) stands for the outward unit normal vector to \( \partial \Omega \). While this is not crucial for most of the analysis, we can bear in mind the fact that physically relevant velocity fields satisfy

\[
\nabla v \cdot n \bigg|_{\partial \Omega} \leq 0
\]

since \( \nabla v \) is pointing towards the nest. Assumption (1.2) will play a role when proving uniform propagation of the \( L^\infty \)-norm for solutions, namely, estimate (3.23) and later, for the local existence of classical solutions. Therefore, ants do not escape the domain \( \Omega \). The initial data

\[
\begin{aligned}
 u \bigg|_{t=0} &= u_o, \\
 w \bigg|_{t=0} &= w_o
\end{aligned}
\]

will be assumed, naturally, as nonnegative integrable functions. As a consequence, we have

\[
\int_{\Omega} (u + w)(t, x) \, dx = \int_{\Omega} (u_o + w_o)(x) \, dx.
\]

We shall prove the global well-posedness in dimension \( n = 2 \) for both models (SPD) and (FPD). In fact, weak solutions of such systems are bounded in \((0, T] \times \Omega\) for any \( T > 0 \). This is in contrast with the situation known for the usual Keller–Segel system

\[
\begin{aligned}
\partial_t \rho + \nabla \cdot (\rho \nabla \Phi) - \Delta \rho &= 0, \\
- \Delta \Phi &= \rho.
\end{aligned}
\]
It is indeed well-known that, if the initial mass \( \int \rho(0, x) \, dx \) exceeds a certain threshold (which depends on the domain and the space dimension \( n \geq 2 \)), then the solution of (1.5) blows up: \( \| \rho(t, x) \|_{\infty} \to \infty \) as \( t \to T^* < \infty \), typically exhibiting a concentration to a certain location. Roughly speaking, this effect can be seen as a result of the competing effects between diffusion and the explosive behavior of the ODE \( \dot{y} = y^2 \) (which is obtained neglecting diffusion and looking at the solution \( \rho \) evaluated along the characteristics associated to the field \( \nabla \Phi \)). At first sight, the structure of the systems (\( \text{SPD} \)) and (\( \text{FPD} \)) is quite close to that of the Keller–Segel system (1.5) and one may wonder whether of not such threshold phenomena occur to produce the blow up of the solutions. However, we shall see that the introduction of an additional population (the returning ant population \( w \)), which is itself subjected to a regularizing parabolic equation, prevents the blow up formation.

The paper is organized as follows. In Section 2 we set up the assumptions necessary to the analysis and we state the main results. Section 3 is devoted to the model (\( \text{FPD} \)) and it is divided in four subsections for clarity. The first and second subsections present the core of the analysis where increasing integrability of the solutions is shown by means of \textit{a priori} estimates. The initial step is to prove instantaneous generation of \( L^\gamma \)-integrability. To be more specific, we prove that \( L^1 \) initial data will lead to solutions lying in \( L^\infty(t_*, T; L^\gamma(\Omega)) \) for any \( \gamma \in (1, \infty) \) and any positive times \( 0 < t_* \leq T \leq \infty \). The bounds given for the \( L^\gamma \)-norm of the solution will depend on the \textit{structure of the system}, that is, on the data \( N, c, v \) and more importantly, on the conserved quantity, that is the initial mass of the total ant population \( m_0 = \int u_0 \, dx + \int w_0 \, dx \). Such bounds are independent of the time existence interval, a fact that can be used to justify that the solutions are globally defined. Furthermore, it is possible to use such a result to prove that solutions are actually uniformly bounded for any positive time. The proof of this fact relies on the De Giorgi energy level set method, [11]. The third subsection is concerned with the global existence of classical solutions for the problem. Given smooth initial data, local in time existence of solutions can be justified by using the classical Banach fixed-point theorem on suitable metric spaces. Next, the global \textit{a priori} estimates which are valid for classical solutions allow us to justify that the lifespan of these solutions is actually infinite. We finish Section 3 by presenting a global well-posedness theorem for weak solutions of (\( \text{FPD} \)) with initial data in \( L^1 \cap L^\gamma \) with \( \gamma > 2 \). The proof uses approximation by the classical solutions just found. Finally, in Section 4 we discuss the well-posedness of the system (\( \text{SPD} \)). Our approach uses elementary properties of the heat kernel which is, somehow, a different approach than the one used for the analysis of (\( \text{FPD} \)).

2 Notations, hypotheses and main results

The main results of this paper are concerned with the well-posedness of weak solutions of the system (\( \text{FPD} \)).
Definition 2.1. We say that the triple \((u, w, p)\) is a weak solution of the system (FPD) if it satisfies:

(i) \((u, w) \in L^2(0, T; H^1(\Omega))\) and \((\partial_t u, \partial_t w) \in L^2(0, T; H^1(\Omega)^*)\).

(ii) Equations (FPD) are solved in the sense that, for any test function \(\zeta \in C^\infty([0, \infty) \times \Omega),\) compactly supported in \([0, T] \times \Omega\), we have

\[
\int_0^T \int_\Omega \left( -u \partial_t \zeta + (\nabla u - u \nabla p) \cdot \nabla \zeta \right)(t, x) \, dx \, dt - \int_\Omega u_o(x) \zeta(0, x) \, dx = \int_0^T \int_\Omega (-uc + wN) \zeta(t, x) \, dx \, dt,
\]

\[
\int_0^T \int_\Omega \left( -w \partial_t \zeta + (\nabla w - w \nabla v) \cdot \nabla \zeta \right)(t, x) \, dx \, dt - \int_\Omega w_o(x) \zeta(0, x) \, dx = \int_0^T \int_\Omega (uc - wN) \zeta(t, x) \, dx \, dt,
\]

\[
\int_\Omega \nabla p \cdot \nabla \zeta \, dx = \int_\Omega (w - \delta p) \zeta \, dx.
\]

**Main hypotheses.** The following assumptions will be used throughout this Section:

(i) The initial data \((u_o, w_o)\) is nonnegative with finite mass:

\[
\int_\Omega u_o(x) \, dx + \int_\Omega w_o(x) \, dx = m_o < \infty. \tag{2.1}
\]

(ii) The parameters of the system (FPD) are such that

\[
(N, c, \nabla v, \Delta v) \in L^\infty(\Omega). \tag{H}
\]

The results can be extended under weaker assumptions on \(v\) at the price of more involved technicalities in the estimates. As a convention, let us agree here that when a constant is referred to depend on (H) it means that this constant depends on the \(L^\infty\)-norms of \(N, c, \nabla v\) and \(\Delta v\).

(iii) The domain \(\Omega\) is of class \(C^2\).

In what follows we will use the shorthand notation \(\gamma^\pm\) to denote a number close but strictly bigger/smaller that \(\gamma\). Having all these in mind let us gather the main results regarding (FPD) in one single statement.

**Theorem 2.2.** Let \(\delta > 0\) be fixed. Let \((u_o, w_o)\) be a pair of nonnegative functions in \(L^1 \cap L^2(\Omega)\). Then, there exists a unique nonnegative weak solution to (FPD). In the case \(\delta = 0\) uniqueness continues holding up to a constant in the pheromone \(p\) distribution. Furthermore, the following estimates are satisfied by the solutions for any \(0 < t \leq T < \infty\):
(i) $L^\gamma$-integrability

\[ \|w(t)\|_\gamma + \|u(t)\|_\gamma \leq C(m_0, \gamma)\left(1 + \frac{1}{t^{(1/\gamma)''}}\right), \text{ for any } \gamma \in [1, \infty), \]

(ii) $L^\infty$-bound

\[ \|w(t)\|_\infty + \|u(t)\|_\infty \leq C(m_0)\left(1 + \frac{1}{t^{1/\gamma}}\right). \]

The constants in (i) and (ii) depend on $\mathbf{H}$ but do not depend on $T$.

(iii) If, in addition, the initial data are in $L^\gamma(\Omega)$ for $\gamma \in (1, \infty]$, then the previous estimates are improved to

\[ \|w(t)\|_{\gamma'} + \|u(t)\|_\gamma \leq C'(m_0, \gamma), \]

where the constant $C'$ depends on $\mathbf{H}$ and on $\|w_0\|_{\gamma'}, \|u_0\|_\gamma$ but not on $T$.

**Remark 2.3.** Once the $L^\infty$ estimate has been established, it can be used to investigate further regularity of the solution. In particular, it implies that $\nabla u$ and $\nabla p$ are bounded on $[t_*, T] \times \Omega'$, for any $0 < t_* < T$ and any domain $\Omega'$ strictly included in $\Omega$; see [25, Th. VII.6.1]. Assuming that $N, c, v$ are $C^\infty$, we can boil down a bootstrap argument to show that the solution $(u, w)$ is actually of class $C^\infty$ in any such subdomain $[t_*, T] \times \Omega'$, see for instance [15, Prop. A.1 & Th. A. 1].

### 3 Analysis of the model (FPD)

In this section we provide a series of *a priori* estimates to build up enough regularity to prove the existence of classical solutions of (FPD).

**Definition 3.1.** A classical solution $(u, w, p)$ of the system (FPD) is defined as a triple $(u, w, p)$ satisfying the following:

(i) The triple $(u, w, p) \in C\left([0, T]; L^2(\Omega)\right)$ and each of the terms in the system (FPD) (i.e. $\partial_t u$, $\Delta u$, $\nabla \cdot (u \nabla p)$, and so forth) are well defined functions in $L^2((0, T) \times \Omega)$.

(ii) The equations (FPD) are satisfied almost everywhere,

(iii) The initial data $(u, w)|_{t=0} = (u_0, w_0)$ and the boundary condition (1.1) are satisfied almost everywhere.

#### 3.1 From $L^1$ to $L^\gamma$ regularity.

In this section we prove instantaneous generation of $L^\gamma$ integrability, with $\gamma > 1$, for nonnegative classical solutions of (FPD) associated to initial data lying in
A crucial fact used in the argument is mass conservation, that is, classical solutions \((u(t), w(t))\) satisfy \((1.4)\) that we rewrite as
\[
\int_{\Omega} u(t, x) \, dx + \int_{\Omega} w(t, x) \, dx = \int_{\Omega} u_0(x) \, dx + \int_{\Omega} w_0(x) \, dx = m_0 \quad \text{for any} \ t > 0.
\]

**Proposition 3.2.** Let \((u, w)\) be a classical nonnegative solution of the system \((FPD)\) with boundary conditions \((1.1)\). Then, for any \(\gamma \in [1, \infty)\) we have the estimate
\[
\|w(t)\|_\gamma + \|u(t)\|_\gamma \leq C(m_0, \gamma) \left(1 + \frac{1}{\gamma(1/\gamma')}\right), \quad t > 0,
\]
where the constant \(C(m_0, \gamma)\) depends additionally on \((H)\), but, is independent of time. Furthermore, for any \(\gamma \in [1, \infty)\) this estimate can be upgraded, provided we add the dependence of the integrability of the initial data to the constant, to
\[
\int_{\Omega} w^{\gamma^+}(t) \, dx + \int_{\Omega} u^{\gamma^+}(t) \, dx \leq C(m_0, \|u_0\|_\gamma, \|w_0\|_\gamma), \quad t > 0.
\]

The constant depends on \((H)\) (but is independent of time).

**Proof.** We start by multiplying equation \((FPD)\) by \(u^{\gamma - 1}\), with \(\gamma > 1\), and integrating with respect to the space variable. We obtain
\[
\frac{1}{\gamma} \frac{d}{dt} \int_{\Omega} u^{\gamma} \, dx - \frac{\gamma - 1}{\gamma} \int_{\Omega} \nabla p \cdot \nabla (u^{\gamma}) \, dx + (\gamma - 1) \int_{\Omega} u^{\gamma - 2} |\nabla u|^2 \, dx
= - \int_{\Omega} u^{\gamma} c \, dx + \int_{\Omega} Nu^{\gamma - 1} \, dx.
\]

Now multiply the third (pheromone) equation by \(u^{\gamma}\) and integrate by parts to conclude that
\[
\int_{\Omega} \nabla p \cdot \nabla (u^{\gamma}) \, dx \leq \int_{\Omega} w u^{\gamma} \, dx.
\]

Next using
\[
\int_{\Omega} u^{\gamma - 2} |\nabla u|^2 \, dx = \frac{4}{\gamma^2} \int_{\Omega} |\nabla u^{\gamma/2}|^2 \, dx,
\]
and the Young inequality with conjugate exponents \(p = \gamma, \ p' = \frac{\gamma}{\gamma - 1},\) and \(p = \gamma + 1, \ p' = \frac{\gamma + 1}{\gamma},\) respectively, we find
\[
\frac{d}{dt} \int_{\Omega} u^{\gamma} \, dx + \frac{\gamma - 1}{\gamma} \int_{\Omega} |\nabla u^{\gamma/2}|^2 \, dx
\leq \gamma \int_{\Omega} Nu^{\gamma - 1} \, dx + (\gamma - 1) \int_{\Omega} w u^{\gamma} \, dx
\leq \|N\|_{\infty} \int_{\Omega} w^{\gamma} \, dx + \|N\|_{\infty} \int_{\Omega} u^{\gamma} \, dx
+ \frac{1}{\varepsilon} \int_{\Omega} w^{\gamma + 1} \, dx + \gamma \varepsilon^1/\gamma \int_{\Omega} u^{\gamma + 1} \, dx.
\]
We have also used weighted Young’s inequality
\[ ab = \frac{a}{\varepsilon^{1/\beta}} \times \varepsilon^{1/\beta} b \leq \frac{1}{\varepsilon\beta} a^\beta + \varepsilon^{\beta'/\beta} b^{\beta'/\beta}, \]
with free parameter \( \varepsilon > 0 \), in the last inequality. A similar procedure on the second equation in \( \text{FPD} \) gives, for any \( \alpha > 1 \),
\[
\frac{d}{dt} \int_{\Omega} w^\alpha \, dx + \frac{\alpha - 1}{\alpha} \int_{\Omega} |\nabla w^{\alpha/2}|^2 \, dx \\
\leq \alpha \int_{\Omega} cuw^{\alpha-1} \, dx + \alpha(\alpha - 1) \int_{\Omega} w^{\alpha-1} \nabla w \cdot \nabla v \, dx.
\]
The first integral of the right hand side is directly estimated by
\[
\|c\|_\infty \left( \int_{\Omega} u^\alpha \, dx + \alpha \int_{\Omega} w^\alpha \, dx \right),
\]
as a consequence of Hölder and Young inequalities. There are two ways to estimate the last integral, depending on the assumptions on \( v \):

- We recognize \( \alpha w^{\alpha-1} \nabla w = w^{\alpha/2} \times 2 \nabla w^{\alpha/2} \) and we simply use the Cauchy-Schwarz inequality to obtain
\[
\left| \alpha(\alpha - 1) \int_{\Omega} w^{\alpha-1} \nabla w \cdot \nabla v \, dx \right| \\
\leq \|\nabla v\|_\infty \left( \frac{4(\alpha - 1)}{\alpha} \int_{\Omega} |\nabla w^{\alpha/2}|^2 \, dx \right)^{1/2} \left( \alpha(\alpha - 1) \int_{\Omega} w^\alpha \, dx \right)^{1/2}
\]
which leads to
\[
\frac{d}{dt} \int_{\Omega} w^\alpha \, dx + \frac{\alpha - 1}{\alpha} \int_{\Omega} |\nabla w^{\alpha/2}|^2 \, dx \\
\leq \|c\|_\infty \int_{\Omega} u^\alpha \, dx + \alpha \left( \|c\|_\infty + \frac{\alpha}{2} \|\nabla v\|_\infty^2 \right) \int_{\Omega} w^\alpha \, dx. \tag{3.2}
\]

- When \( (1.2) \) holds, we can integrate by parts so that
\[
\alpha(\alpha - 1) \int_{\Omega} w^{\alpha-1} \nabla w \cdot \nabla v \, dx = (\alpha - 1) \int_{\Omega} \nabla w^\alpha \cdot \nabla v \leq (\alpha - 1) \int_{\Omega} w^\alpha \Delta v \, dx
\]
which yields
\[
\frac{d}{dt} \int_{\Omega} w^\alpha \, dx + \frac{4(\alpha - 1)}{\alpha} \int_{\Omega} |\nabla w^{\alpha/2}|^2 \, dx \\
\leq \|c\|_\infty \int_{\Omega} u^\alpha \, dx + \alpha \left( \|c\|_\infty + \|\Delta v\|_\infty \right) \int_{\Omega} w^\alpha \, dx. \tag{3.3}
\]
Estimate \((3.2)\) is better in terms of required regularity for \(v\), however, \((3.3)\) will play a role when \(\alpha \to \infty\). The latter will be used to show uniform propagation of the \(L^\infty\)-norm later on.

Now, we use the fact that the space dimension is \(n = 2\) and we appeal to the following Gagliardo–Nirenberg–Sobolev inequality (see e. g. [5, eq. (85) p. 195]), which holds for any \(\alpha \geq 1\),

\[
\int \Omega \xi^{\alpha+1} \, dx \leq C(\Omega, \alpha) \|\xi\|_1 \|\xi^{\alpha/2}\|_{H^1}^2,
\]

\[
\leq C(\Omega, \alpha) \int \Omega \xi \, dx \left( \int \Omega \xi^\alpha \, dx + \int \Omega |\nabla (\xi^{\alpha/2})|^2 \, dx \right). \tag{3.4}
\]

Combined with \(\int u(t, x) \, dx + \int w(t, x) \, dx = m_o\), it allows us to absorb the higher exponent of \(u\) in the right side of \((3.1)\) by choosing \(\varepsilon > 0\) sufficiently small. We can thus find positive constants \(C(m_o)\) and \(C'(m_o)\), depending on \(H\), and on the exponents \(\alpha\) and \(\gamma\), such that

\[
\frac{d}{dt} \int \Omega u^\gamma \, dx + C'(m_o) \int \Omega u^{\gamma+1} \, dx \leq C(m_o) \left( \int \Omega u^\gamma \, dx + \int \Omega u^{\gamma+1} \, dx \right), \tag{3.5}
\]

\[
\frac{d}{dt} \int \Omega w^\alpha \, dx + C'(m_o) \int \Omega w^{\alpha+1} \, dx \leq C(m_o) \left( \int \Omega u^\gamma \, dx + \int \Omega w^\gamma \, dx \right).
\]

In order to control the right hand side of inequalities \((3.5)\) exponents in the left hand side have to be bigger than exponents in the right; therefore, we are forced to choose \(\gamma < \alpha < \gamma + 1\). We shall use Lebesgue’s interpolation inequalities

\[
\|w\|_\gamma \leq \|w\|_1^{1-\theta_1} \|w\|_\alpha^{\theta_1}, \quad \theta_1 = \frac{(\gamma-1)(\alpha+1)}{\gamma \alpha} \in (0, 1),
\]

\[
\|w\|_{\gamma+1} \leq \|w\|_1^{1-\theta_2} \|w\|_{\alpha+1}^{\theta_2}, \quad \theta_2 = \frac{\gamma(\alpha+1)}{\alpha(\gamma+1)} \in (0, 1).
\]

\[
\|u\|_\alpha \leq \|u\|_1^{1-\theta_3} \|u\|_{\gamma+1}^{\theta_3}, \quad \theta_3 = \frac{\gamma(1) \alpha^{-1}}{\gamma \alpha} \in (0, 1).
\]

Let us introduce

\[
U(t) := \int \Omega u^\gamma(t) \, dx, \quad W(t) := \int \Omega w^\alpha(t) \, dx.
\]

>From \((3.5)\) we are thus led to

\[
\frac{d}{dt} U + C'(m_o) \|u\|_{\gamma+1}^{\gamma+1} \leq C(m_o) \left( U + \|w\|_{\alpha+1}^{(\alpha+1)\theta_1} + \|w\|_{\alpha+1}^{(\alpha+1)\theta_2} \right),
\]

\[
\frac{d}{dt} W + C'(m_o) \|w\|_{\alpha+1}^{\alpha+1} \leq C(m_o) \left( W + \|u\|_{\gamma+1}^{(\gamma+1)\theta_3} \right).
\]
For any $\varepsilon > 0$, $\beta \geq 1$, we can find $C(\varepsilon, \beta) > 0$ such that $s \leq \varepsilon s^\beta + C(\varepsilon, \beta)$ for any $s \geq 0$. Thus, adding up these inequalities and setting $Z := U + W$, it follows that there exists constants $C_1(m_0)$ and $C_2(m_0)$ such that

$$\frac{d}{dt} Z + C_1(m_0) \left( \| u \|_{\gamma + 1}^{\gamma + 1} + \| w \|_{\alpha + 1}^{\alpha + 1} \right) \leq C_2(m_0) (Z + 1). \quad (3.6)$$

Using Lebesgue's interpolation again

$$\| u \|_\gamma \leq \| u \|_{1}^{1-\theta_4} \| u \|_{\gamma+1}^{\theta_4}, \quad \theta_4 = \frac{\gamma^2 - 1}{\gamma^2},$$

$$\| w \|_\alpha \leq \| w \|_{1}^{1-\theta_5} \| u \|_{\alpha+1}^{\theta_5}, \quad \theta_5 = \frac{\alpha^2 - 1}{\alpha^2},$$

we readily infer

$$\| u \|_{\gamma + 1}^{\gamma + 1} + \| w \|_{\alpha + 1}^{\alpha + 1} \geq C(m_0) \left( \| u \|_\gamma^{(\gamma+1)/\theta_4} + \| w \|_{\alpha}^{(\alpha+1)/\theta_5} \right)$$

$$\geq C(m_0) \left( U^\frac{\gamma}{\gamma+1} + W^\frac{\alpha}{\alpha+1} \right) \geq C(m_0) Z^\frac{\gamma}{\gamma+1} - C(m_0),$$

by using the fact that $s \mapsto \frac{s}{s-1}$ is non increasing. Using $s \leq \varepsilon s^\beta + C(\varepsilon, \beta)$ again, and coming back to (3.6), we arrive at

$$\frac{d}{dt} Z + C_1'(m_0) Z^\frac{\gamma}{\gamma+1} \leq C_2'(m_0),$$

with constants $C_1'(m_0)$ and $C_2'(m_0)$ depending on the initial mass $m_0$, $\| u \|_{\gamma+1}$ and $\| w \|_{\alpha+1}$. Therefore, the comparison principle in Corollary A.2 yields

$$Z(t) \leq C(m_0) \left( 1 + \frac{1}{t^{\alpha-1}} \right).$$

In other words, for any $1 < \gamma < \alpha < \gamma + 1 < \infty$, we have

$$\| w(t) \|_\alpha \leq C(m_0) \left( 1 + \frac{1}{t^{\alpha}} \right),$$

$$\| u(t) \|_\gamma \leq C(m_0) \left( 1 + \frac{1}{t^{\gamma}} \right) = C(m_0) \left( 1 + \frac{1}{t^{\gamma}} \right).$$

In the last equality we have used the fact that $\gamma < \alpha$ can be taken as close as desired. Furthermore, by invoking Lemma A.1 the estimate on $t \mapsto Z(t)$ can be upgraded to $\sup_{t \geq 0} Z(t) \leq C$ provided we add the dependence on the norms $\| w_0 \|_\alpha$ and $\| u_0 \|_\gamma$ in the constant. This completes the proof of Proposition 3.2.
3.2 From $L^\gamma$ to $L^\infty$ regularity.

In this section we prove further gain of boundedness for \([\text{FPD}]\), showing that classical solutions are in fact bounded for any positive time. We adopt De Giorgi’s energy method [11], which has been successfully adapted to investigate the regularity of PDEs systems see e.g. [6][7][15]. Let us start the discussion and we shall state the theorem at the end of this section.

Consider a classical non negative solution $w$ of the equation
\[
\partial_t w - \Delta w + \nabla \cdot (w \nabla v) = f, \quad \text{in } [0,T] \times \Omega,
\]
with $v$ and $f$ given functions. For the boundary condition we assume that $(\nabla w - w \nabla v) \cdot n = 0$. Define the level sets
\[
w_\lambda = (w - \lambda) \mathbb{1}_{\{w > \lambda\}}, \quad \lambda \geq 0.
\]
Multiply (3.7) by $w_\lambda$. Owing to the boundary conditions, we obtain
\[
dt \int_\Omega w_\lambda^2 \, dx + 2 \int_\Omega |\nabla w_\lambda|^2 \, dx \leq 2 \int_\Omega w \nabla v \cdot \nabla w_\lambda \, dx + 2 \int_\Omega f + w_\lambda \, dx.
\]
Young’s inequality leads to
\[
dt \int_\Omega w_\lambda^2 \, dx + \int_\Omega |\nabla w_\lambda|^2 \, dx \leq \int_\Omega |w \nabla v|^2 \mathbb{1}_{\{w > \lambda\}} \, dx + 2 \int_\Omega f + w_\lambda \, dx.
\]
We split the reasoning into two steps. We start by proving the $L^\infty$ bound on a given time interval $[t_*, T]$. Secondly, we shall extend the estimate to infinitely large time intervals. Thus, let us consider $0 < t_* < T < \infty$. Let $M > 0$ and define the following sequence of levels and times
\[
\lambda_k = (1 - 1/2^k)M, \quad t_k = (1 - 1/2^{k+1})t_*, \quad k = 0, 1, 2, ...
\]
Define the following energy functional for the level sets
\[
W_k := \sup_{t \in [t_k, T]} \int_\Omega w_k^2 \, dx + \int_{t_k}^T \int_\Omega |\nabla w_k|^2 \, dx \, dt,
\]
where we adopted the notation $w_k := w_{\lambda_k}$. With $\lambda = \lambda_k$, let us integrate inequality (3.8) over the time interval $[s, t]$; we obtain
\[
\int_\Omega w_k^2(t, x) \, dx + \int_s^t \int_\Omega |\nabla w_k|^2 \, dx \, dt' \leq \int_\Omega w_k^2(s, x) \, dx
\]
\[
+ \int_s^t \int_\Omega |w \nabla v|^2 \mathbb{1}_{\{w > \lambda_k\}} \, dx \, dt' + 2 \int_s^t \int_\Omega f + w_k \, dx \, dt'.
\]
We use this relation with $t_{k-1} \leq s \leq t_k \leq t \leq T$. It implies

$$W_k \leq \int_\Omega w_k^2(s, x) \, dx$$

$$+ \int_{t_{k-1}}^T \int_\Omega |w \nabla v|^2 \, 1_{\{w > \lambda_k\}} \, dx \, dt' + 2 \int_{t_{k-1}}^T \int_\Omega f_+ \, w_k \, dx \, dt'.$$

We take the mean over $s \in [t_{k-1}, t_k]$, bearing in mind that $t_k - t_{k-1} = t_* / 2^{k+1}$. It yields

$$W_k \leq \frac{2^{k+1}}{t_*} \int_{t_{k-1}}^T \int_\Omega w_k^2 \, dx \, ds$$

$$+ \int_{t_{k-1}}^T \int_\Omega |w \nabla v|^2 \, 1_{\{w > \lambda_k\}} \, dx \, dt' + 2 \int_{t_{k-1}}^T \int_\Omega f_+ \, w_k \, dx \, dt'. \quad (3.10)$$

We are going to make use of the Gagliardo-Nirenberg interpolation inequality, see [5, eq. (85), p. 195],

$$\|w\|_p \leq C(\Omega, p, \alpha)\|w\|_{H_1}^{(1-\alpha)p}, \quad 1 = \left(\frac{1}{2} - \frac{1}{n}\right)\alpha + \frac{1}{2} p, \quad (3.11)$$

which holds for any $\alpha \in [0, 1]$ and $1 \leq p, q \leq \infty$ (note that we perform the estimates without restricting the space dimension for the moment). Thus, choosing $\alpha p = 2$ it follows that

$$\|w\|_p \leq C(\Omega, n)\|w\|_{H_1}^{2} \|w\|_{2}^{p-2}, \quad p = 2 \frac{n+2}{n}. \quad (3.12)$$

Note that if $w_k > 0$ then $w_{k-1} \geq 2^{-k} M$, and, as a consequence,

$$1_{\{w > \lambda_k\}} \leq \left(\frac{2^k}{M} w_{k-1}\right)^a, \quad \forall \ a \geq 0. \quad (3.13)$$

Having this in mind one can play with the homogeneity of the right hand terms in the level set energy inequality (3.10). Indeed, with $a = 4/n$, the first of them can be evaluated as follows

$$\frac{2^{k+1}}{t_*} \int_{t_{k-1}}^T \int_\Omega w_k^2 \, 1_{\{w > \lambda_k\}} \, dx \, ds \leq \frac{2^{k+1}}{t_*} \int_{t_{k-1}}^T \int_\Omega w_{k-1}^2 \left(\frac{2^k}{M} w_{k-1}\right)^\frac{4}{n} \, dx \, ds$$

$$\leq 2 \frac{2^{k+1}}{M \pi t_*} \int_{t_{k-1}}^T \int_\Omega w_{k-1}^2 \, dx \, ds$$

$$\leq 2C(\Omega, n) \frac{2^{k+1}}{M \pi t_*} \int_{t_{k-1}}^T \left(\|w_{k-1}\|_2^2 + \|\nabla w_{k-1}\|_2^2\right) \|w_{k-1}\|_{2}^{\frac{n+2}{n}-2} \, ds$$

$$\leq 2C(\Omega, n)(1 + T) \frac{2^{k+1}}{M \pi t_*} W_{k-1}^{\frac{n+2}{n}}. \quad (3.14)$$
by virtue of (3.12) and the definition of \(W_{k-1}\). The last two terms in the right hand side of (3.10) can be treated by using a similar procedure, together with the application of Hölder’s inequality. On the one hand, bearing in mind that the \(t_k\)’s are all larger than \(t_*/2\), we get using (3.13) with \(a = p\)

\[
\int_{t_{k-1}}^{T} \int_{\Omega} |w\nabla v|^2 \mathbf{1}_{\{w > \lambda_k\}} \, dx \, dt \leq \int_{t_{k-1}}^{T} \|w\nabla v\|_{2q'}^2 \left( \int_{\Omega} \mathbf{1}_{\{w > \lambda_k\}} \, dx \right)^{\frac{a}{q'}} \, dt
\]

\[
\leq \frac{2^\frac{a}{q'}}{M^\frac{a}{q'}} \sup_{t \geq \frac{t_*}{2}} \|w\nabla v\|_{2q'}^2 \int_{t_{k-1}}^{T} \|w_{k-1}\|_{\frac{a}{q'}} \|w_{k-1}\|_2^{(1-a)\frac{a}{q'}} \, dt.
\]

We have used (3.11) in the last inequality. We choose the parameters so that \(\frac{q}{a} \alpha = 2\) for some \(0 < \alpha < 1\), which can be achieved as long as \(1 < q < \frac{n}{n-2}\) (more precisely, going back to (3.11), note that \(\alpha = \frac{q}{1+2q/n}\) and \(p = 2(1+2q/n)\)). It follows that

\[
\int_{t_{k-1}}^{T} \int_{\Omega} |w\nabla v|^2 \mathbf{1}_{\{w > \lambda_k\}} \, dx \, dt \leq (1 + T) C(\Omega, p, \alpha)^\frac{2}{q'} \frac{2^\frac{a}{q'}}{M^\frac{a}{q'}} \left( \sup_{t \geq \frac{t_*}{2}} \|w\nabla v\|_{2q'}^2 \right) W^{\frac{a}{q'}}_{k-1}.
\]

On the other hand, since \(w_k \leq w \mathbf{1}_{\{w > \lambda_k\}}\), we have

\[
\int_{t_{k-1}}^{T} \int_{\Omega} f_+ w_k \, dx \, dt \leq \left( \sup_{t \geq \frac{t_*}{2}} \|f_+\|_{q'} \right) \int_{t_{k-1}}^{T} \left( \int_{\Omega} \mathbf{1}_{\{w > \lambda_k\}} \, dx \right)^{\frac{a}{q'}} \, dt
\]

\[
\leq \frac{2^\frac{a}{q'}}{M^\frac{a}{q'}} \left( \sup_{t \geq \frac{t_*}{2}} \|f_+\|_{q'} \right) \int_{t_{k-1}}^{T} \left( \int_{\Omega} w_{k-1}^p \, dx \right)^{\frac{a}{q'}} \, dt
\]

\[
\leq (1 + T) C(\Omega, p, \alpha)^\frac{2}{q'} \frac{2^\frac{a}{q'}}{M^\frac{a}{q'}} \left( \sup_{t \geq \frac{t_*}{2}} \|f_+\|_{2q'} \|w\|_{2q'} \right) W^{\frac{a}{q'}}_{k-1},
\]

still using the same relation between \(p, q\) and \(\alpha\). We go back to (3.10), with (3.14), (3.15) and (3.16), we arrive at

\[
W_k \leq (1 + T) \left[ 2C(\Omega, n) \frac{2^{\alpha+n}}{M^\frac{a}{q'}} W^{\frac{a}{q'}}_{k-1} w^{\frac{n}{n-2}} + 2C(\Omega, p, \alpha)^\frac{2}{q'} \frac{2^\frac{a}{q'}}{M^\frac{a}{q'}} \left( \|\nabla v\|_{\infty}^2 \|w\|_{2q'}^2 + \|f_+\|_{2q'} \|w\|_{2q'} \right) W^{\frac{a}{q'}}_{k-1} \right].
\]

For the final step, we specialize to the case of space dimension \(n = 2\). As a matter of fact, we observe that \(1 < q < \frac{n}{n-2} = \infty\). We can then appeal to the
estimates in Proposition 3.2 which imply (particularizing to \( f_+ = u c \))

\[
\sup_{t \geq t^*} \left( \|\nabla v\|_{L^\infty}^2 \|w\|_{L^2}^2 + \|f_+\|_{L^2} \|w\|_{L^2} \right) \leq C(m_o) \left( 1 + \frac{1}{t^*_*} \right).
\]  

(3.18)

Therefore, (3.17) becomes

\[
W_k \leq C(1 + T) \left( \frac{2^{3k}}{M^2 t_*} W_{k-1}^2 + \left( 1 + \frac{1}{t^*_*(1+q)^*} \right) \frac{2^{(2+1)k}}{M} W_{k-1}^{2+1} \right).
\]  

(3.19)

We can take advantage of the fact that the powers \( \frac{n+2}{n} = 2 \) and \( \frac{2+1}{q} \) are strictly larger than 1 to conclude. Indeed, a direct calculation shows that \( W_0 a^k \) is a super solution of the first order difference equation (3.19) with choices of \( a \in (0, 1) \) small, and then \( M \) large (see e. g. [15, Lemma 3.3 & 3.4] for similar arguments) such that

\[
\max \left\{ 2^3 a, \frac{2^{(2+1)/q}}{a^{1/2}} \right\} < 1,
\]

\[
\max \left\{ \frac{C W_0}{a^2 M^2 t_*}, \frac{C W_0^{2+1}}{a^{2+1} M^{2+1}} \left( 1 + \frac{1}{t^*_*(1+q)^*} \right) \right\} \leq \frac{1}{2(1+T)}.
\]

By a comparison principle, we check that \( W_0 a^k \geq W_k \) holds under these circumstances. We conclude that

\[
\lim_{k \to \infty} W_k = 0.
\]

Let us suppose \( 0 < t_* < 1 \). Then, observe that such a choice of \( M \) explicitly takes the form

\[
M = \max \left\{ \sqrt{\frac{2C(1+T)W_0}{a^2 t_*}}, \sqrt{\frac{(2C(1+T))^{1/2} W_0^{1/2}}{a}} \frac{2}{t^*_*(1/2)^*} \right\},
\]  

(3.20)

where the constant \( C \) depends on \( m_o \), \( (H) \), and of the exponent \( q \). We clearly have

\[
W_k \geq \frac{1}{T-t_*} \int_t^T \int_\Omega w^2(t,x) 1_{\{w(t,x) \geq M(1-1/2)\}} \, dx \, dt.
\]

Letting \( k \) run to 0, by virtue of Fatou’s lemma we deduce that

\[
\frac{1}{T-t_*} \int_t^T \int_\Omega w^2(t,x) 1_{\{w(t,x) \geq M\}} \, dx \, dt = 0,
\]

which eventually implies

\[
0 \leq w(t,x) \leq M \quad \text{a. e. } (t_*, T) \times \Omega.
\]  

(3.21)

This proves most of the following result.
Proposition 3.3. Let \((u, w)\) be a classical nonnegative solution of \((\text{FPD})\) with boundary conditions \((1.1)\). Then, the following \(L^\infty\)-estimate holds
\[
\|u(t)\|_\infty + \|w(t)\|_\infty \leq C(m_o) \left( 1 + \frac{1}{t^1} \right), \quad t \in (0, T],
\] (3.22)
where the constant \(C\) depends additionally on \((H)\), but, it is independent of \(T > 0\). Furthermore, when \((1.2)\) holds, estimate \((3.22)\) can be upgraded by adding the dependence on the \(L^\infty\)-norms of the initial data in the constant,
\[
\max \{\|w(t)\|_\infty, \|u(t)\|_\infty\} \leq C(m_o, \|w_o\|_\infty, \|u_o\|_\infty), \quad t \geq 0,
\] (3.23)
where the constant is still independent of the time \(T > 0\).

Proof. Proceeding as we did in \((3.8)\), we can establish the following inequality for \(w\):
\[
\frac{d}{dt} \int_\Omega w^2 \, dx + \int_\Omega |\nabla w|^2 \, dx \leq \int_\Omega |w\nabla v|^2 \, dx + 2 \int_\Omega f_+ w \, dx.
\] (3.24)
We integrate over \([s, t]\) and we get, with \(f_+ = uc\),
\[
\int_\Omega w^2(t, x) \, dx + \int_s^t \int_\Omega |\nabla w(\sigma, x)|^2 \, d\sigma \, dx \leq \int_\Omega w^2(s, x) \, dx + \|\nabla v\|_\infty \int_s^t \int_\Omega w^2(\sigma, x) \, d\sigma \, dx
\]
\[
+ \|c\|_\infty \int_s^t \int_\Omega (u^2 + w^2)(\sigma, x) \, d\sigma \, dx.
\]
We use this relation with \(s = t_*/2 \leq t \leq T\), which allows us to obtain the following estimate (recall the definition of \(W_0\) in \((3.9)\))
\[
W_0 \leq \|w(t_*/2)\|_2^2
\]
\[
+ \left( \|\nabla v\|_\infty + \|c\|_\infty \right) \left( T - \frac{t_*}{2} \right) \left( \sup_{t \in [t_*/2, T]} \|w(t)\|_2^2 + \sup_{t \in [t_*/2, T]} \|u(t)\|_2^2 \right).
\] (3.25)
By Proposition \((3.2)\) \(W_0\) is thus dominated by \(C(m_o)(1 + T)(1 + 1/t_*^1)\).

Now, we set \(T = 1\), say. Going back to \((3.20)\) and \((3.21)\), we conclude that
\[
\|w(t)\|_\infty \leq M \leq C(m_o) \frac{1}{t_*^1},
\] (3.26)
holds for short times, say \(0 < t_* \leq t \leq T = 1\). It is clear that the same reasoning can be applied for any \(T\), and it would provide a bound depending on \(T\). In order to justify that the \(L^\infty\) estimate can be made uniform with respect to \(T\), we thus proceed differently, by extending the estimate obtained on \([t_*, 1]\). Indeed, for any \(t_1 > 0\), the shifted function \((t, x) \mapsto w_{t_1}(t, x) = w(t + t_1, x)\) is still a solution of equation \((3.7)\), with data \(w_{t_1}(0, x) = w(t_1, x)\) and the appropriate right hand
side \( f \). In particular mass conservation implies
\[
\int_{\Omega} (u(t_1, x) + w(t_1, x)) \, dx = m_0,
\]
so that the constant \( C(m_o) \) does not change. Therefore, we pick \( 0 < t_1 < T \)
and we can repeat the same arguments for \( w_t \), which leads to the same \( L^\infty \)
estimate (3.26) as for \( w \) on the time interval \( [t_*, T] \), that is to say (3.26) holds
for \( t \in [t_1 + t_*, t_1 + T] \). We have thus extended (3.26) over \( [t_*, t_1 + T] \), see
Figure 1 and we can repeat this procedure. This completes the proof of (3.22)
for \( w \).

\[
\|w(t)\|_\infty \leq C(m_o)/t_1^{1+}
\]

Figure 1: Extension of the local result.

Next, using elliptic regularity for the pheromone equation, see [1], and Sobolev’s embedding (still with space dimension \( n = 2 \)), it follows that
\[
\|\nabla p(t)\|_\infty \leq C\|p(t)\|_{W^{2,2^+}} \leq C(\Omega) \|w(t)\|_{2^+} \leq C(m_o) \left( 1 + \frac{1}{t(1/2)^+} \right).
\]
Equipped with this estimate we repeat for \( u \) the arguments used for estimating \( w \), just changing \( c \) to \( N \) and replacing the uniform estimate on \( \nabla v \) by this time-dependent estimate for \( \nabla p \). This finishes the proof of estimate (3.22). As a matter of fact, note that (3.26) applies in particular to \( t = t_* \):
\[
\|w(t_*)\|_\infty \leq C(m_o)/t_1^{1+}
\]
holds for any \( 0 < t_* \leq 1 \).

For proving the uniform bound (3.23) let us set
\[
A := \max \left\{ \sup_{s \geq 0} \|u(s)\|_{2^+}, \sup_{s \geq 0} \|w(s)\|_{2^+} \right\} < \infty. \tag{3.27}
\]
We slightly modify the previous analysis. In particular, we change the definition
of the \( t_k \)’s by setting \( t_k = t_*(1 - 1/2^k) \), so that it now starts from \( t_0 = 0 \). Going
back to (3.24), we get \( W_0 \leq \|w_0\|_{2^q}^2 + CT \), with \( C \) depending on (1) and the
constant \( A \) in (3.27). Furthermore, the additional information in (3.27) allows
us to control uniformly with respect to time the \( L^{2q'} \) norms (bearing in mind
that making \( q \) large means \( q' \) close to 1) so that (3.18) becomes
\[
\sup_{t \geq 0} \left( \|\nabla v\|_{\infty}^2 \|w\|_{2^q}^2 + \|f\|_{2q'} \|w\|_{2q'} \right) \leq C.
\]
Accordingly, inequality (3.19) is changed into
\[
W_k \leq C_0 \frac{2^{3k}}{M^{2^k}} W_{k-1}^2 + C_1 \frac{2^{2(q+1)k}M^{2^{q+1}k}}{M^{2^{q+1}k} W_{k-1}^{2(q+1)}}.
\]

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where \( C_0 \) and \( C_1 \) depend on \([1]\), but also on \( T \) and \( A \), while they do not depend on \( k \) and \( t_* \). Reproducing the same argumentation as above permits us to establish that
\[
\|w(t)\|_\infty \leq C(m_o, A) \left( 1 + \frac{1}{\sqrt{t}} \right),
\]
holds for \( 0 < t \leq 1 \). Furthermore, elliptic regularity \([1]\) yields
\[
\|\nabla p(t)\|_\infty \leq C(\Omega) \|w(t)\|_2 \leq A
\]
and, as a consequence, we get a similar estimate for \( u \):
\[
\|u(t)\|_\infty \leq C(m_o, A) \left( 1 + \frac{1}{\sqrt{t}} \right)
\]
holds for \( 0 < t \leq 1 \), too. Let us set
\[
U(t) := \int_\Omega u^\gamma(t, x) \, dx, \quad W(t) := \int_\Omega w^\gamma(t, x) \, dx.
\]
Since \([1.2]\) holds, we can make use of inequalities \([3.1] \) and \([3.3] \) (with \( \alpha = \gamma \)), and we get
\[
\frac{dU}{dt} \leq \|N\|_\infty W + \gamma (\|N\|_\infty + \|w(t)\|_\infty) U
\]
\[
\leq \|N\|_\infty W + \gamma B \left( 1 + \frac{1}{\sqrt{t}} \right) U,
\]
\[
\frac{dW}{dt} \leq \|c\|_\infty U + \gamma (\|c\|_\infty + \|\Delta v\|_\infty) W,
\]
for \( t \in (0, 1) \), with \( B > 0 \) independent of \( \gamma > 0 \). Adding the two inequalities in \([3.3] \), we deduce that \( Z := U + W \) satisfies
\[
\frac{dZ}{dt} \leq C \gamma \left( 1 + \frac{1}{\sqrt{t}} \right) Z,
\]
for \( t \in (0, 1) \), and a certain constant \( C > 0 \) which does not depend on \( \gamma \). It leads to
\[
Z(t) \leq Z_0 \exp \left( C \gamma \int_0^t \left( 1 + \frac{1}{\sqrt{s}} \right) \, ds \right) \leq Z_0 e^{3C\gamma},
\]
which eventually implies the estimate
\[
\max\{\|u(t)\|_\gamma, \|w(t)\|_\gamma\} \leq \max\{\|u_o\|_\gamma, \|w_o\|_\gamma\} e^{3C}
\]
which thus holds a.e. \( t \in (0, 1) \). Sending \( \gamma \to \infty \) proves estimate \([3.23] \) for short times.

Going back to the second part of the statement in Proposition \([3.2] \), we realize that \([3.27] \) is ensured when the initial data belong to \( L^1 \cap L^\infty(\Omega) \). This observation ends the proof of the \( L^\infty \) estimate for \( 0 \leq t \leq 1 \). Combined to \([3.22] \), it provides a uniform estimate on the solution for any \( t \geq 0 \). \( \square \)
3.3 Construction of classical solutions

We have now the tools to prove the global well-posedness of the system (FPD). Firstly, we establish the existence–uniqueness of solutions locally in time, and, secondly, we extend the result, as a consequence of the obtained estimates. We start by working with smooth and bounded initial data, say \((u_o, w_o) \in C^\infty_c(\Omega)\).

**Theorem 3.4** (Classical solutions). Let \(u_o, w_o \in C^\infty_c(\Omega)\) be nonnegative initial data. Then, for every \(T > 0\) the system (FPD) with boundary conditions (1.1) admits a unique nonnegative classical solution \((u, w, p) \in Y\) which satisfies the estimates of Propositions 3.2 and 3.3.

**Proof.** As explained above the proof splits into two steps. **Step 1: Local existence.** Let us introduce the convex set

\[ Y = \{ \xi \in C([0, T]; L^2(\Omega)) \cap L^2(0, T; H^1(\Omega)), 0 \leq \xi(t, x) \leq 2\|w_o\|_\infty \}. \]

This space is endowed with the norm

\[ \|u\|_Y = \sup_{0 \leq t \leq T} \|u(t, \cdot)\|_{L^2}. \]

Let \(\varphi \in Y\) be such that \(\varphi(0) = w_o\). To such \(\varphi\) we associate the solution \(p(\varphi)\) of the pheromone equation

\[ -\Delta p = \varphi - \delta p, \quad (3.32) \]

and, then, we associate the solution \(u(\varphi) = u(\varphi, p(\varphi))\) of the equation

\[ \partial_t u - \Delta u + \nabla \cdot (u \nabla p(\varphi)) = -uc + \varphi N, \quad u(0) = u_o. \quad (3.33) \]

Finally, let \(w(\varphi) = w(\varphi, u(\varphi))\) be the solution of

\[ \partial_t w - \Delta w + \nabla \cdot (w \nabla v) = uc - w N, \quad w(0) = w_o. \quad (3.34) \]

Equations are complemented with the zero-flux boundary conditions (1.1). Note that (3.32), (3.33) and (3.34) are linear equations and existence of solutions is provided by the standard theory, see e. g. [5, Theorem X.9]. In particular both \(u(\varphi)\) and \(w(\varphi)\) belong to \(C([0, T]; L^2(\Omega)) \cap L^2(0, T; H^1(\Omega))\). We aim at finding \(T\) small enough, so that solutions of (FPD) can be obtained as fixed points of the mapping

\[ \Phi : \varphi \mapsto w(\varphi). \]

We shall prove that \(\Phi\) is a contraction in \(Y\), for a sufficiently small time \(T > 0\) depending only on \([H]\) and the initial data \((u_o, w_o)\). This is a consequence of the maximum principle for the linear equation

\[ \partial_t \psi - \Delta \psi + \nabla \cdot (B \psi) + b \psi = f, \]

complemented with the boundary condition

\[ \nabla \psi \cdot n - \psi B \cdot n = 0. \]
We assume (related to (1.2))

\[ b \geq 0, \quad f \geq 0, \quad B \cdot n \leq 0. \]

Then, the solution \( \psi \) associated to \( \psi(0, x) = \psi_0(x) \geq 0 \) is non negative. This result can be obtained by considering the identity

\[
\frac{d}{dt} \int_{\Omega} G(\psi) \, dx + \int_{\Omega} G''(\psi) |\nabla \psi|^2 \, dx = \int_{\Omega} \psi G''(\psi) B : \nabla \psi \, dx - \int_{\Omega} b\psi G'(\psi) \, dx + \int_{\Omega} f G'(\psi) \, dx.
\]

We work with the convex function \( G(z) = \frac{|z|^2}{2}, \) \( [z] = \min(z, 0) \leq 0 \). It follows that \( G'(z) = [z] \leq 0, \) and \( zG'(z) \geq 0, \) \( zG''(z) = G'(z) \) so that \( |\psi G''(\psi)\nabla \psi| = \sqrt{2G(\psi)} \times \sqrt{|G''(\psi)|\nabla \psi|} \). Then Cauchy-Schwarz and Young inequality yield

\[
\frac{d}{dt} \int_{\Omega} G(\psi) \, dx \leq \|B\|^2_\infty \int_{\Omega} G(\psi) \, dx.
\]

We conclude as a consequence of the Grönwall lemma that \( \psi(t, x) \geq 0 \). Let us set

\[
\gamma(t) = e^{t(\|\nabla B\|_\infty + \|b\|_\infty)}(t\|f\|_\infty + \|\psi_0\|_\infty).
\]

Observe that \( \lim_{t \to 0} \gamma(t) = \|\psi_0\|_\infty \). Applying the previous maximum principle to \( \tilde{\psi}(t, x) := \gamma(t) - \psi(t, x) \), we conclude that \( \psi(t, x) \leq \gamma(t) \). Indeed, note that \( \tilde{\psi}(t, x) \) satisfies the non homogeneous Robin’s condition \( (\nabla \tilde{\psi} - B\tilde{\psi}) \cdot n = -\gamma B \cdot n \) with a non negative source \( -\gamma B \cdot n \geq 0 \) so that the computation now involves the boundary term \( \int_{\partial \Omega} B \cdot n \gamma \psi G'(\gamma - \psi) \, d\sigma \) which contributes negatively owing to the orientation of \( B \) towards the interior of \( \Omega \).

Since \( 0 \leq \varphi(t, x) \leq 2 \| w_o \|_\infty \) holds on \( [0, T] \times \Omega \), we have that \( p \) and \( \Delta p \) are bounded in \( L^\infty([0, T] \times \Omega) \), and \( \nabla p \) as well. This allows us to use the above maximum principle with the solution of (3.32), and then also to the solution of (3.34), to justify that \( 0 \leq w(t, x) \leq 2 \| w_o \|_\infty \) holds a.e. \( (t, x) \in [0, T] \times \Omega \), provided \( T \) is small enough. We thus have \( \Phi(\bar{y}) \subset \bar{y} \).

Let us show that \( \Phi \) is a contraction in \( \bar{y} \), possibly at the price of making \( T > 0 \) smaller. Let \( \varphi_1, \varphi_2 \in \bar{y} \) and let \((u_i, w_i, \nu_i), \) with \( i = 1, 2, \) be the corresponding solutions of respectively, (3.32), (3.33), and (3.34). Define \( \bar{w} := w_1 - w_2 = \Phi(\varphi_1) - \Phi(\varphi_2) \) so forth. We compute

\[
\frac{1}{2} \frac{d}{dt} \int_{\Omega} |\bar{w}|^2 \, dx + \int_{\Omega} |\nabla \bar{w}|^2 \, dx + \int_{\Omega} N |\bar{w}|^2 \, dx
\]

\[
= \int_{\Omega} c\bar{w} \, dx + \int_{\Omega} \bar{w} \nabla v \cdot \nabla \bar{w} \, dx
\]

\[
\leq \frac{1}{2} (\|\nabla v\|_\infty^2 + \|c\|_{\infty}^2) \int_{\Omega} |\bar{w}|^2 \, dx + \frac{1}{2} \int_{\Omega} |\nabla \bar{w}|^2 \, dx + \frac{1}{2} \int_{\Omega} |\bar{u}|^2 \, dx.
\]

Grönwall’s lemma thus yields

\[
\int_{\Omega} |\bar{w}|^2 \, dx \leq e^{K_1 t} \int_{0}^{t} \int_{\Omega} |\bar{u}|^2 \, dx \, ds \tag{3.35}
\]

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with \(K_1 = \|\nabla v\|^2_\infty + \|c\|^2_\infty\). We proceed similarly with (3.33) and we get

\[
\frac{1}{2} \frac{d}{dt} \int_\Omega |\bar{u}|^2 \, dx + \int_\Omega |\nabla \bar{u}|^2 \, dx + \int_\Omega c|\bar{u}|^2 \, dx \\
= \int \nabla \bar{u} \cdot \nabla \phi \, dx + \int_\Omega \bar{u} \nabla p_1 \cdot \nabla u + \int \bar{u} \nabla p_2 \cdot \nabla u \, dx \\
\leq \frac{1}{2} \|N\|^2_\infty \int_\Omega |\bar{u}|^2 \, dx + \frac{1}{2} \int_\Omega |\bar{\varphi}|^2 \, dx + \frac{1}{2} \|w_1\|_\infty \int_\Omega |\bar{u}|^2 \, dx \\
+ \frac{1}{2} \int_\Omega |\nabla \bar{u}|^2 \, dx + \frac{1}{2} \|u_2\|^2_\infty \int_\Omega |\nabla \bar{p}|^2 \, dx,
\]

where we have used the equation \(\delta_1 - \Delta p_1 = w_1\). Since \(0 \leq \varphi_1(t, x) \leq 2\|w_0\|_\infty\) holds on \([0, T] \times \Omega\), we deduce that \(p_2\) and \(\Delta p_2\) are bounded in \(L^\infty((0, T) \times \Omega)\), and thus, the maximum principle applies for (3.33) and we can assume that \(\|u_2\|_\infty \leq 2\|u_0\|_\infty\) holds on \([0, T]\). Furthermore, we have \(\|\nabla \bar{p}\|^2_2 \leq C\|\bar{\varphi}\|^2_2\), with \(C\) depending on \(\delta \geq 0\). It follows that

\[
\frac{d}{dt} \int_\Omega |\bar{u}|^2 \, dx \leq (\|N\|^2_\infty + 2\|w_0\|_\infty) \int_\Omega |\bar{u}|^2 \, dx + (1 + 4C\|u_0\|^2_\infty) \int_\Omega |\bar{\varphi}|^2 \, dx
\]

holds on \([0, T]\). Hence, we get

\[
\int_\Omega |\bar{u}|^2 \, dx \leq (1 + 4C\|u_0\|^2_\infty)e^{K_2 t} \int_0^t \int_\Omega |\bar{\varphi}|^2 \, dx \, ds,
\]

with \(K_2 = \|N\|^2_\infty + 2\|w_0\|_\infty\). Finally (going back to (3.33)), we find \(K, M > 0\), depending on \((H)\) and the \(L^\infty\) norms of the data \((u_0, w_0)\), such that

\[
\int_\Omega |\tilde{w}(t, x)|^2 \, dx \leq Me^{Kt} t^2 \sup_{0 \leq s \leq t} \int_\Omega |\tilde{\varphi}(s, x)|^2 \, dx,
\]

holds on \([0, T]\). This justifies that \(\Phi\) is a contraction on \(\mathcal{Y}\), for a small enough time interval. The fixed point defines a solution of (FPD).

**Step 2: Global solutions.** We remind the reader that we are working with data \((u_0, w_0) \in C_c^\infty(\Omega)\). The obtained solution is bounded on \((0, T) \times \Omega\). Therefore, the classical theory of parabolic equations tells us that \(\nabla u\) and \(\nabla p\) are bounded on \([t_*, T] \times \Omega'\), for any \(0 < t_* < T\) and \(\Omega'\) strictly included in \(\Omega\); see for instance [25] Th. VII.6.1]. We can then perform a bootstrap argument to show that the solution is \(C^\infty([t_*, T] \times \Omega')\), if the coefficients \(N, c, v\) are assumed to be \(C^\infty\). Moreover, by virtue of \((u_0, w_0) \in C_c^\infty(\Omega)\), the data satisfy compatibility conditions with the boundary conditions, so that we have actually constructed classical solutions, see [26] Th. 4.3] or [25] Th. V.7.4. In particular, the a priori estimates discussed above apply. Proposition 3.3 provides a uniform \(L^\infty\) estimate on the solution, which depends only on \((H)\) and \(\|u_0\|_\infty, \|w_0\|_\infty\). Therefore, we can reproduce the fixed point argument and extend the solution over \([0, \infty)\).
Multiplying the second equation in (3.36) by \( \text{Cauchy-Schwarz} \), we are led to Proposition 3.5.

**Proposition 3.5.** Nonnegative classical solutions of (3.30) are stable in \( S := \{ (u, w) \in L^\infty(0, T; L^1 \cap L^2(\Omega)) \} \), \( T > 0 \).

**Proof.** Let \( \varpi = u_1 - u_2 \) and similarly for the other differences. The system for the differences reads

\[
\begin{aligned}
\partial_t \varpi - \Delta \varpi + \nabla \cdot (\varpi \nabla p_1) + \nabla \cdot (u_2 \nabla \varpi) &= -c \varpi + N \varpi, \\
\partial_t \varpi - \Delta \varpi + \nabla \cdot (\varpi \nabla \varpi) &= c \varpi - N \varpi, \quad (3.36)
\end{aligned}
\]

- \( \Delta \varpi = \varpi - \varpi \).

Multiplying the second equation in (3.36) by \( \varpi \), integrating by parts and using Cauchy-Schwarz, we are led to

\[
\frac{1}{2} \frac{d}{dt} \| \varpi \|_2^2 + \| \nabla \varpi \|_2^2 \leq \| \varpi \|_2 \left( \| \nabla v \|_\infty \| \nabla \varpi \|_2 + \| \varpi \|_\infty \right) ,
\]

which yields

\[
\frac{d}{dt} \| \varpi \|_2^2 + \| \nabla \varpi \|_2^2 \leq C \left( \| \varpi \|_2^2 + \| \varpi \|_2^2 \right) .
\]

(3.37)

for \( C = \| \nabla v \|_\infty^2 + \| \varpi \|_\infty^2 \). Next, using the equation for \( u \) we get

\[
\frac{d}{dt} \| \varpi \|_2^2 + \| \nabla \varpi \|_2^2 \leq 2 \left( \| \varpi \nabla p_1 \|_2^2 + \| u_2 \nabla \varpi \|_2^2 \right) + \| \varpi \|_2^2 + \| \nabla N \|_2^2 ,
\]

The right side terms above are easily controlled using (3.27), (3.28), (3.29), (3.30)

\[
\begin{aligned}
\| \varpi(t) \nabla p_1(t) \|_2^2 &\leq \| \nabla p_1(t) \|_\infty^2 \| \varpi(t) \|_2^2 \leq C \| \varpi(t) \|_2^2 , \\
\| u_2(t) \nabla \varpi(t) \|_2^2 &\leq \| u_2(t) \|_\infty^2 \| \nabla \varpi(t) \|_2^2 \leq \left( \| u_2(t) \|_1^{1/q} \| u_2(t) \|_\infty^{1+1/q} \right) \| \varpi(t) \|_2^2 ,
\end{aligned}
\]

\[
\leq C \left( \frac{1}{1+1/q} \right) \| \varpi(t) \|_2^2 , \quad q \in [1, \infty) .
\]

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The constant $C$ now depends on $m_o$ and on the $L^2$-norm of the data. Taking $q$ arbitrarily large, we obtain

$$\frac{d}{dt} \|\pi\|_2^2 + \frac{1}{2} \|
abla \pi\|_2^2 \leq C \left( 1 + \frac{1}{t^{(1/2)+}} \right) \left( \|\pi\|_2^2 + \|\pi\|_2^2 \right). \tag{3.38}$$

Now define $Z(t) := \|\pi\|_2^2 + \|\pi\|_2^2$. Thus, adding up estimates (3.37) and (3.38), it follows that

$$\frac{dZ(t)}{dt} \leq C \left( 1 + \frac{1}{t^{(1/2)+}} \right) Z(t).$$

Integration of this ODE leads to the result. \hfill \Box

### 3.4 Global well-posedness of weak solutions

We are going to prove the global existence of weak solutions, in the sense of Definition 2.1.

**Theorem 3.6** (Global well-posedness). Let arbitrary $T > 0$, $\delta > 0$ be fixed and assume nonnegative initial data $(u_o, w_o) \in L^1 \cap L^2 + (\Omega)$. Then, there exists a unique nonnegative weak solution for the system (FPD). Such solution satisfies the estimates of Propositions 3.2 and 3.3.

In the case $\delta = 0$ uniqueness continues holding up to a constant in the pheromone $p$ distribution.

**Proof.** Take a sequence of non negative initial data $(u_o^k, w_o^k) \in C^\infty_c(\Omega)$ such that

$$(u_o^k, w_o^k) \to (u_o, w_o) \quad \text{strongly in } L^1 \cap L^2^+(\Omega).$$

Using Theorem 3.4 on global well-posedness of classical solutions, we have a sequence $(u^k, w^k, p^k) \in C(0,T;L^2(\Omega))$ of solutions to the system (FPD). It is not difficult to check that, in fact, such a sequence is uniformly bounded in $L^2(0,T;H^1(\Omega))$ with time derivatives uniformly bounded in $L^2(0,T;H^1(\Omega)^*)$.

Let $Z_{kl}(t) = \|u^k(t) - u^l(t)\|_2^2 + \|w^k(t) - w^l(t)\|_2^2$, $k,l \geq 1$, be the Cauchy differences. Note that Proposition 3.2 implies that $(u^k, w^k) \in L^\infty(0,T;L^2^+(\Omega))$ uniformly with respect to $k \geq 1$, hence, the stability result of Proposition 3.3 implies that

$$Z_{kl}(t) \leq Z_{kl}(0)e^{Ct},$$

with constant $C$ independent of the indices $k, l$. In this way we conclude that both $u^k$ and $w^k$ are Cauchy in $L^\infty(0,T;L^2(\Omega))$. Thus, the following convergence properties hold:

$$(u^k, w^k) \to (u, w) \quad \text{strongly in } L^\infty(0,T;L^2(\Omega)),$$

$$(u^k, w^k) \to (u, w) \quad \text{weakly in } L^2(0,T;H^1(\Omega))$$

$$(\partial_t u^k, \partial_t w^k) \to (\partial_t u, \partial_t w) \quad \text{weakly in } L^2(0,T;H^1(\Omega)^*).$$

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With standard estimates for the elliptic problems, we deduce that $\nabla p^k$ is bounded in $L^\infty(0,T;L^2(\Omega))$, and $\nabla p_k$ converges to $\nabla p$ strongly in $L^1((0,T)\times\Omega)$. As a consequence, $0 \leq (u, w) \in L^\infty(0,T;L^2(\Omega))$ is a weak solution of (FPD). Note that the initial condition $(u(0), w(0)) = (u_0, w_0)$ is satisfied by continuity at $t = 0$ which follows from the estimate on the time derivatives.

Finally, using approximation by classical solutions again one proves that the stability result of Proposition 3.5 is valid for weak solutions as well. Uniqueness follows from here. \hfill \square

**Remark 3.7.** It is likely that the $L^{2^+}$ integrability of the data is not optimal for the theory of existence of solutions. However, it simplifies the analysis in two directions. On the one hand, it makes the definition, and the stability, of the product $u\nabla p$ meaningful. On the other hand, the underlying estimate is also useful in the proof of Proposition 3.5 which implies the uniqueness of weak solutions.

## 4 Analysis of the model (SPD)

In this section we perform the analysis for the system (SPD) that includes regularity estimates and global well-posedness in the case where the problem is set on the entire space $\Omega = \mathbb{R}^2$. A short comment for the case $\Omega = \mathbb{R}^n$ with $n \geq 3$ is included in the Remark 4.6. Details are given only in the arguments for obtaining *a priori* estimates since the ideas to make such estimates rigorous were previously presented (and are quite classical). We remind the reader that the main hypotheses imposed on the parameters are gathered in (H). Eq. (SPD) involves an evolution equation for the food concentration $c$; therefore, in addition we will assume

$$c_0 \in L^\infty(\mathbb{R}^n), \quad P \in L^\infty(\mathbb{R}^n). \quad (H+)$$

Of course, we continue assuming that the total population of ants is integrable: $u_o$ and $w_o$ belong to $L^1(\mathbb{R}^2)$, and we still denote

$$\int_{\mathbb{R}^2} (u_o + w_o)(x) \, dx = m_o.$$

### 4.1 Estimates for solutions of the heat equation

The strategy for proving estimates for the system (SPD) is based on a sharp control of the gradient of the pheromone $\nabla p$ in terms of the ant population $w$: recall that for the system (FPD) such an estimate was a direct consequence of the regularity analysis for elliptic equations, *à la* Agmon-Douglis-Nirenberg [1]. We substitute this argument with a direct analysis of the Duhamel formula for
the heat equation. To be more specific, let $\varphi$ be a solution of the problem

$$\partial_t \varphi - \Delta \varphi = f \quad \text{in } (0, \infty) \times \mathbb{R}^n,$$

$$\varphi \big|_{t=0} = \varphi_0 \quad \text{on } \mathbb{R}^n.$$  \hspace{1cm} (4.1)

Then, $\varphi$ is given by the explicit formula

$$\varphi(t,x) = \int_{\mathbb{R}^n} K(t, x-y) \varphi_0(y) \, dy + \int_0^t \int_{\mathbb{R}^n} K(t-s, x-y) f(s, y) \, dy \, ds$$  \hspace{1cm} (4.2)

where

$$K(t, x) = \frac{1}{(4\pi t)^{n/2}} e^{-\frac{|x|^2}{4t}},$$

as long as it makes sense. Throughout this section the technical lemmas will be presented as general results valid for any space dimension $n \geq 2$.

**Lemma 4.1.** Fix $q \in (n, \infty]$ and $\theta \in (0, 2]$ such that

$$\frac{\theta q}{2} > 1, \quad \frac{\theta q}{2 - \theta} > n.$$  

Additionally, assume that for some $T > 0$

$$\nabla \varphi_0 \in L^q(\mathbb{R}^n), \quad f \in L^\infty(0, T; L^1 \cap L^{\theta q/2}(\mathbb{R}^n)).$$

Let $\varphi$ be a solution of the heat equation (4.1). Then, for any $t \in (0, T]$ we have

$$\|\nabla \varphi(t, \cdot)\|_q \leq \|\nabla \varphi_0\|_q + C_n \left(1 + \frac{1}{t^{(n-q')/2q'}}\right) \left(1 + \sup_{0 \leq s \leq t} \|f(s, \cdot)\|_1\right) \sup_{0 \leq s \leq t} \|f(s, \cdot)\|_{\theta q/2}^{\frac{\theta q (n-1)-n}{n-1}}.$$  \hspace{1cm} (4.3)

The constant $C_n$ depends on the dimension $n$, $q$ and $\theta$. Furthermore, the supremum in time can be estimated for any $T \geq 1$ as

$$\sup_{0 \leq t \leq T} \|\nabla \varphi(t, \cdot)\|_q \leq 2 \|\nabla \varphi_0\|_q$$

$$+ C_n \left(1 + \sup_{0 \leq s \leq t} \|f(s, \cdot)\|_1\right) \sup_{0 \leq s \leq T} \|f(s, \cdot)\|_{\theta q/2}^{\frac{\theta q (n-1)-n}{n-1}}.$$  \hspace{1cm} (4.4)

The constant $C_n$ depends on the dimension $n$, $q$ and $\theta$.

**Proof.** Using the explicit solution of the heat equation (4.2), we obtain

$$\nabla \varphi(t,x) = \int_{\mathbb{R}^n} \nabla_x K(t, x-y) \varphi_0(y) \, dy$$

$$+ \int_0^t \int_{\mathbb{R}^n} \nabla_x K(t-s, x-y) f(s, y) \, dy \, ds =: I_1(t,x) + I_2(t,x).$$
Estimate of the term $I_1$ simply follows from integration by parts and Young's inequality for convolutions

\[ \|I_1(t, \cdot)\|_q = \left\| \int_{\mathbb{R}^n} \nabla_x K(t, x - y) \varphi_o(y) \, dy \right\|_q \]

\[ = \left\| \int_{\mathbb{R}^n} K(t, x - y) \nabla \varphi_o(y) \, dy \right\|_q \leq \|K(t, \cdot)\|_1 \|\nabla \varphi_o\|_q = \|\nabla \varphi_o\|_q. \]  

(4.5)

Let us focus on the term $I_2$. Fix $0 < \varepsilon \leq t$ and consider the decomposition

\[ I_2(t, x) = \int_0^{t-\varepsilon} \int_{\mathbb{R}^n} \cdots \, dy \, ds + \int_{t-\varepsilon}^t \int_{\mathbb{R}^n} \cdots \, dy \, ds =: I_2^1(t, x) + I_2^2(t, x). \]

In what follows, we will repeatedly make use of Young's inequalities for convolution [5 Th. IV.30]

\[ \|f * g\|_q \leq \|f\|_p \|g\|_r, \quad 1/p + 1/r = 1 + 1/q. \]  

(4.6)

For $I_2^1(t, x)$, it yields

\[ \|I_2^1(t, \cdot)\|_q \]

\[ = \left\| - \frac{1}{2(4\pi)^{n/2}} \int_0^{t-\varepsilon} \frac{1}{(t-s)^{(n+1)/2}} \int_{\mathbb{R}^n} e^{-\frac{|x-y|^2}{4(t-s)}} (x-y) f(s, y) \, dy \, ds \right\|_q \]

\[ \leq \frac{1}{2(4\pi)^{n/2}} \int_0^{t-\varepsilon} \frac{1}{(t-s)^{(n+1)/2}} \left( \int_{\mathbb{R}^n} \left| \frac{x}{\sqrt{t-s}} e^{-\frac{x^2}{4(t-s)}} \right|^q dx \right)^{1/q} \|f(s, \cdot)\|_1 ds \]

\[ \leq \left| e^{-|x|^2} \right|_q \frac{2q'}{n - q'} \sup_{0 < s \leq t} \|f(s, \cdot)\|_1. \]  

(4.7)

Note that the case $q = \infty$ is valid. Next, we get (using (4.6) with $p = q\theta/2$ and $r = \sigma$)

\[ \|I_2^2(t, \cdot)\|_q \]

\[ = \left\| - \frac{1}{2(4\pi)^{n/2}} \int_{t-\varepsilon}^t \frac{1}{(t-s)^{(n+1)/2}} \int_{\mathbb{R}^n} e^{-\frac{|x-y|^2}{4(t-s)}} (x-y) f(s, y) \, dy \, ds \right\|_q \]

\[ \leq \frac{1}{2(4\pi)^{n/2}} \int_{t-\varepsilon}^t \frac{1}{(t-s)^{(n+1)/2}} \left( \int_{\mathbb{R}^n} \left| \frac{x}{\sqrt{t-s}} e^{-\frac{x^2}{4(t-s)}} \right|^\sigma dx \right)^{1/\sigma} \|f(s, \cdot)\|_{q\theta/2} ds \]

\[ \leq \left| e^{-|x|^2} \right|_\sigma \frac{2\sigma'}{\sigma' - n} \sup_{t-\varepsilon \leq s \leq t} \|f(s, \cdot)\|_{q\theta/2} \varepsilon^{(\sigma' - n)/2\sigma'}. \]  

(4.8)
where \( \sigma' = \frac{q \theta}{n - q'} > n \). (Note that the case \( \theta = 2 \), that is \( \sigma' = \infty \), is a valid choice.) Thus, gathering (4.5), (4.7) and (4.8) we are led to

\[
\| \nabla \varphi(t, \cdot) \|_q = \| I_1(t, \cdot) + I_2(t, \cdot) \|_q \\
\leq \| \nabla \varphi_0 \|_q + C_n \left( \sup_{0 \leq s \leq t} \frac{\| f(s, \cdot) \|_1}{\varepsilon(n - q')/2q'} + \frac{\| f(s, \cdot) \|_{\theta/2}}{\varepsilon(n - q')/2q'} \right),
\]

with \( C_n \) depending on \( n, q, \theta \). We shall choose \( \varepsilon \in (0, \frac{1}{T}] \) defined by

\[
\varepsilon = \min \left\{ 1, \frac{1}{T} \right\} \left( 1 + \sup_{\frac{1}{T} \leq s \leq t} \| f(s, \cdot) \|_{\theta/2} \right)^{-\frac{\sigma'(n - q')}{2n}}
\]
to equalize the homogeneity. Consequently, we obtain the estimate

\[
\| \nabla \varphi(t, \cdot) \|_q \leq \| \nabla \varphi_0 \|_q + C_n \left( \sup_{0 \leq s \leq t} \frac{\| f(s, \cdot) \|_1}{\varepsilon(n - q')/2q'} + \frac{\| f(s, \cdot) \|_{\theta/2}}{\varepsilon(n - q')/2q'} \right),
\]

where the constant \( C > 0 \) depends only on the dimension \( n \), on the exponent \( q \) and \( \theta \). Estimate (4.9) follows by noticing that

\[
\frac{\sigma'(n - q')}{n(n - q')} = 2 - \frac{1}{n} \quad \frac{\theta q(n - 1) - n}{(2 - \theta)q/(q - 1)} = \frac{\theta q(n - 1) - n}{\theta q - 2}.
\]

Now, for estimate (4.10) fix \( T \geq 1 \) and gather (4.5), (4.7) and (4.8) to obtain

\[
\sup_{\varepsilon \leq t \leq T} \| \nabla \varphi(t, \cdot) \|_q = \sup_{\varepsilon \leq t \leq T} \| I_1(t, \cdot) + I_2(t, \cdot) \|_q \\
\leq \| \nabla \varphi_0 \|_q + C_n \left( \sup_{0 \leq s \leq T} \frac{\| f(s, \cdot) \|_1}{\varepsilon(n - q')/2q'} + \frac{\| f(s, \cdot) \|_{\theta/2}}{\varepsilon(n - q')/2q'} \right),
\]

with \( C_n \) depending on \( n, q, \theta \). Note that \( \varepsilon \in (0, T] \). Similarly, when \( t \in [0, \varepsilon] \) it follows that

\[
\sup_{0 \leq t \leq \varepsilon} \| \nabla \varphi(t, \cdot) \|_q = \sup_{0 \leq t \leq \varepsilon} \| I_1(t, \cdot) + I_2(t, \cdot) \|_q \\
\leq \| \nabla \varphi_0 \|_q + C_n \varepsilon^{\sigma'(n - q')/2n} \sup_{0 \leq s \leq T} \| f(s, \cdot) \|_{\theta/2}.
\]

Estimates (4.9) and (4.10) lead to

\[
\sup_{0 \leq s \leq T} \| \nabla \varphi(s, \cdot) \|_q \\
\leq 2\| \nabla \varphi_0 \|_q + C_n \left( \sup_{0 \leq s \leq T} \frac{\| f(s, \cdot) \|_1}{\varepsilon(n - q')/2q'} + \frac{\| f(s, \cdot) \|_{\theta/2}}{\varepsilon(n - q')/2q'} \right),
\]

(4.11)
Again, we shall choose \( \varepsilon \in (0,1] \subset (0,T] \) defined by

\[
\varepsilon = \left( 1 + \sup_{0 \leq s \leq T} \| f(s, \cdot) \|_{q\theta/2} \right)^{-\frac{q}{q'-q}}
\]

to equalize the homogeneity. Consequently, we obtain the estimate

\[
\sup_{0 \leq s \leq T} \| \nabla \phi(s, \cdot) \|_q \leq 2 \| \nabla \phi_0 \|_q + C \left( 1 + \sup_{0 \leq s \leq T} \| f(s, \cdot) \|_1 \right) \sup_{0 \leq s \leq T} \| f(s, \cdot) \|_{q\theta/2}^\frac{q'(q-q')}{2n}\]

where the constant \( C > 0 \) depends only on the dimension \( n \), on the exponent \( q \) and \( \theta \). This proves (4.4).

**Remark 4.2.** The same result applies to the damped equation

\[ \partial_t \varphi - \Delta \varphi = f - \delta \varphi \text{ in } (0, \infty) \times \mathbb{R}^n, \]

\[ \varphi \bigg|_{t=0} = \varphi_0 \text{ on } \mathbb{R}^n. \]  

(4.12)

Indeed, it suffices to apply Lemma 4.1 to \( e^{-\delta t} \varphi(t,x) \).

**Lemma 4.3.** Fix

\[ \varphi_0 \in L^\infty(\mathbb{R}^n), \quad \nabla v \in L^\infty((0,T) \times \mathbb{R}^n), \]

\[ f \in L^\infty((0,T); L^1(\mathbb{R}^n)) \cap L^\infty((0,T) \times \mathbb{R}^n). \]

Let \( \varphi \) be a nonnegative solution of the problem

\[ \partial_t \varphi - \Delta \varphi + \nabla \cdot (\varphi \nabla v) = f \text{ in } \mathbb{R}^n \times (0, \infty) \]

\[ \varphi = \varphi_0 \text{ on } \mathbb{R}^n \times \{ t = 0 \}. \]  

(4.13)

Then, we have for any \( T \geq 1 \)

\[
\sup_{0 \leq t \leq T} \| \varphi(t) \|_\infty \leq 2 \| \varphi_0 \|_\infty + C_n^1 \left( \sup_{0 \leq s \leq T} \| f_+(s) \|_1 + \sup_{0 \leq s \leq T} \| \varphi(s) \|_1 \right) \| \nabla v \|_\infty + C_n^2 \sup_{0 \leq s \leq T} \| f_+(s) \|_\infty^{\frac{n+1}{\infty}}.
\]

The constant \( C_n^1 \) is proportional to \( \ln(T+1) \) in dimension \( n = 2 \) and independent of time for \( n \geq 3 \).

**Proof.** Fix \( T \geq \varepsilon > 0 \) and consider \( t \in [\varepsilon, T] \). We shall use the Duhamel formula for the heat equation (4.12) with the source term

\[ \tilde{f} = f - \nabla \cdot (\varphi \nabla v). \]  

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We split the corresponding expression as $\varphi = \sum_{j=1}^{3} I_j$: let us concur here that $I_1$ is the term corresponding to the initial data, $I_2$ is the term corresponding to the source $f$, and $I_3$ corresponds to the convection term $-\nabla \cdot (\varphi \nabla v)$. For $I_1$, we immediately obtain

$$0 \leq I_1(t, x) = \int_{\mathbb{R}^n} K(t, x - y) \varphi_o(y) \, dy \leq \|\varphi_o\|_{\infty}.$$  \hspace{1cm} (4.15)

For $I_2$, we split the time integral as follows

$$I_2(t, x) = \int_0^t \int_{\mathbb{R}^n} K(t-s, x-y) f(s, y) \, dy \, ds = \int_0^{t-\varepsilon} \int_{\mathbb{R}^n} \cdots \, dy \, ds + \int_{t-\varepsilon}^t \int_{\mathbb{R}^n} \cdots \, dy \, ds \equiv I_2^1 + I_2^2.$$

A direct computation shows that

$$|I_2^1| \leq C_n \left( \frac{\ln(t/\varepsilon)}{\varepsilon} \right) \quad \text{if } n = 2$$

$$\times \sup_{0 \leq s \leq t-\varepsilon} \|f_+(s)\|_1 =: C_n \Phi(\varepsilon, t) \sup_{0 \leq s \leq t-\varepsilon} \|f(s)\|_1,$$

while

$$|I_2^2| \leq \int_{t-\varepsilon}^t \left( \int_{\mathbb{R}^n} K(t-s, x-y) \, dy \right) ds \sup_{t-\varepsilon \leq s \leq t} \|f_+(s)\|_{\infty}$$

$$\leq \int_{t-\varepsilon}^t 1 \, ds \sup_{t-\varepsilon \leq s \leq t} \|f(s)\|_{\infty} = \varepsilon \sup_{t-\varepsilon \leq s \leq t} \|f_+(s)\|_{\infty}.$$

As a consequence, we get

$$I_2(t, x) \leq C_n \left( \Phi(\varepsilon, t) \sup_{0 \leq s \leq T} \|f_+(s)\|_1 + \varepsilon \sup_{t-\varepsilon \leq s \leq T} \|f_+(s)\|_{\infty} \right). \hspace{1cm} (4.16)$$

Additionally, integration by parts implies that

$$I_3(t, x) = -\int_0^t \int_{\mathbb{R}^n} K(t-s, x-y) \nabla_y \cdot (\varphi(s, y) \nabla v(s, y)) \, dy \, ds$$

$$= \int_0^t \int_{\mathbb{R}^n} \nabla_y K(t-s, x-y) \cdot \nabla v(s, y) \varphi(s, y) \, dy \, ds$$

$$= \int_0^{t-\varepsilon} \int_{\mathbb{R}^n} \cdots \, dy \, ds + \int_{t-\varepsilon}^t \int_{\mathbb{R}^n} \cdots \, dy \, ds =: I_3^1 + I_3^2.$$
Similar arguments lead to
\[
|I_3^1(t, x)| = \left| \frac{1}{2(4\pi)^{n/2}} \int_0^{t-\varepsilon} \frac{1}{(t-s)^{(n+1)/2}} \int_{\mathbb{R}^n} e^{-\frac{|x-y|^2}{4(t-s)}} \frac{(x-y)}{\sqrt{(t-s)}} \cdot \nabla \varphi \ dy \ ds \right|
\leq \frac{e^{-1/2} \|\nabla \varphi\|_\infty}{\sqrt{2(4\pi)^{n/2}(n-1)}} \sup_{0 \leq s \leq T} \|\varphi(s)\|_1 \varepsilon^{(n-1)/2},
\]
(4.17)

and
\[
|I_3^2(t, x)| \leq \left| \frac{1}{2(4\pi)^{n/2}} \int_0^{t} \frac{1}{(t-s)^{(n+1)/2}} \int_{\mathbb{R}^n} e^{-\frac{|x-y|^2}{4(t-s)}} \frac{(x-y)}{\sqrt{(t-s)}} \cdot \nabla \varphi \ dy \ ds \right|
\leq \frac{2 \|e^{-|x|^2} x\|_1 \|\nabla \varphi\|_\infty}{\pi^{n/2}} \sqrt{\varepsilon} \sup_{t-\varepsilon \leq s \leq T} \|\varphi(s)\|_\infty.
\]
(4.18)

Gathering estimates (4.17) and (4.18) it follows that
\[
I_3(t, x) \leq C_n \|\nabla \varphi\|_\infty \left( \sup_{0 \leq s \leq T} \|\varphi(s)\|_1 + \varepsilon \sup_{t-\varepsilon \leq s \leq T} \|\varphi(s)\|_\infty \right).
\]
(4.19)

Thus, combining (4.15), (4.16) and (4.19) we obtain
\[
\sup_{\varepsilon \leq t \leq T} \|\varphi(t)\|_\infty = \sup_{\varepsilon \leq t \leq T} \|I_1(t) + I_2(t) + I_3(t)\|_\infty \\
\leq \|\varphi_0\|_\infty + C_n \left( \Phi(\varepsilon, T) \sup_{0 \leq s \leq T} \|f_+(s)\|_1 + \varepsilon \sup_{0 \leq s \leq T} \|f_+(s)\|_\infty \right) \frac{\sup_{0 \leq s \leq T} \|\varphi(s)\|_1}{\varepsilon^{(n-1)/2}} + \sqrt{\varepsilon} \sup_{0 \leq s \leq T} \|\varphi(s)\|_\infty.
\]
(4.20)

Now assume \( t \in [0, \varepsilon] \). A simpler, yet analog, procedure shows that
\[
\sup_{0 \leq t \leq \varepsilon} \|\varphi(t)\|_\infty = \sup_{0 \leq t \leq \varepsilon} \|I_1(t) + I_2(t) + I_3(t)\|_\infty \\
\leq \|\varphi_0\|_\infty + \varepsilon \sup_{0 \leq s \leq T} \|f_+(s)\|_\infty + \|\nabla \varphi\|_\infty \sqrt{\varepsilon} \sup_{0 \leq s \leq T} \|\varphi(s)\|_\infty.
\]
(4.21)

Noticing that
\[
\sup_{0 \leq t \leq T} \|\varphi(t)\|_\infty \leq \sup_{0 \leq t \leq \varepsilon} \|\varphi(t)\|_\infty + \sup_{\varepsilon \leq t \leq T} \|\varphi(t)\|_\infty.
\]
we can add inequalities (4.20) and (4.21) to obtain

\[
\sup_{0 \leq t \leq T} \| \varphi(t) \|_{\infty} \leq 2 \| \varphi_0 \|_{\infty} + C_n \left( \Phi(\varepsilon, T) \sup_{0 \leq s \leq T} \| f_+(s) \|_1 + \varepsilon \sup_{0 \leq s \leq T} \| f_+(s) \|_{\infty} \right) \\
+ C_n \| \nabla v \|_{\infty} \left( \frac{\sup_{0 \leq s \leq T} \| \varphi(s) \|_1}{\varepsilon (n-1)/2} + \sqrt{\varepsilon} \sup_{0 \leq s \leq T} \| \varphi(s) \|_{\infty} \right).
\]

(4.22)

Let us choose in all dimensions

\[
\varepsilon = \min \left\{ 1, \delta^2, T \right\} \left( 1 + \sup_{0 \leq s \leq T} \| f_+(s) \|_{\infty} \right)^{-\frac{1}{n+1}}
\]

with \(1/\delta := 2C_n \| \nabla v \|_{\infty}\), to discover that

\[
\sup_{0 \leq t \leq T} \| \varphi(t) \|_{\infty} \leq 2 \| \varphi_0 \|_{\infty}
\]

\[
+ C_1^n \left( \sup_{0 \leq s \leq T} \| f_+(s) \|_1 + \sup_{0 \leq s \leq T} \| \varphi(s) \|_1 \right) \| \nabla v \|_{\infty}^n + C_2^n \sup_{0 \leq s \leq T} \| f_+(s) \|_{\infty}^{n-1}.
\]

The constant \(C_1^n\) inherits the dependence of \(T\) from \(\Phi(\varepsilon, T)\). Thus, for any \(T \geq 1\), we get

\[
C_1^n = \begin{cases} 
\hat{C}_1^n (\ln(T+1)) & \text{if } n = 2, \\
\text{Independent of } T & \text{if } n \geq 3.
\end{cases}
\]

This proves the lemma. \(\square\)

### 4.2 Analysis of the system (SPD) in dimension \(n = 2\)

#### 4.2.1 From \(L^1\) to \(L^\gamma\) integrability

**Proposition 4.4.** Fix a time \(T > 0\) and let \((u, w)\) be a classical nonnegative solution of the SPD system (SPD) in the interval \([0, T]\). Then, for any \(\gamma > 1\) there exists an explicitly computable exponent \(\beta := \beta(\gamma)\) such that

\[
\| u(t) \|_\gamma + \| w(t) \|_\gamma \leq C(m_0, \gamma) \left( 1 + \frac{1}{T} \right), \quad t \in (0, T],
\]

with constant \(C\) depending additionally on \(\| h_0 \|_{-1}^\gamma\) and \(\| \nabla p_0 \|_{L^{2(\gamma+1)}}\) but independent of \(T\). If additionally \((u_0, w_0) \in L^\gamma \times L^\gamma\) for some \(\gamma > \sqrt{2}\), it follows that

\[
\sup_{0 \leq t \leq T} \left( \| u(t) \|_\gamma + \| w(t) \|_\gamma \right) \leq C(m_0, \gamma, \| u_0 \|_\gamma, \| w_0 \|_\gamma),
\]

where, as before, the constant \(C\) depends additionally on \(\| h_0 \|_{-1}^\gamma\) and \(\| \nabla p_0 \|_{L^{2(\gamma+1)}}\) but it is independent of \(T\).
Proof. For the population $u$, we obtain the following estimate

$$\frac{d}{dt} \int_{\mathbb{R}^n} u^\gamma \, dx + 4 \frac{\gamma - 1}{\gamma} \int_{\mathbb{R}^n} |\nabla u^{\gamma/2}|^2 \, dx$$

$$\leq (\gamma - 1) \int_{\mathbb{R}^n} \nabla p \cdot \nabla (u^\gamma) \, dx + \gamma \int_{\mathbb{R}^n} Nw u^{\gamma - 1} \, dx.$$  

With Cauchy-Schwarz and Young inequalities, we get

$$(\gamma - 1) \int_{\mathbb{R}^n} \nabla p \cdot \nabla (u^\gamma) \, dx = 2(\gamma - 1) \int_{\mathbb{R}^n} |\nabla p| u^\gamma \, dx + \frac{\gamma - 1}{\gamma} \int_{\mathbb{R}^n} |\nabla (u^{\gamma/2})|^2 \, dx,$$

so that

$$\frac{d}{dt} \int_{\mathbb{R}^n} u^\gamma \, dx + 3 \frac{\gamma - 1}{\gamma} \int_{\mathbb{R}^n} |\nabla u^{\gamma/2}|^2 \, dx$$

$$\leq \gamma \int_{\mathbb{R}^n} Nw u^{\gamma - 1} \, dx + \gamma(\gamma - 1) \int_{\mathbb{R}^n} |\nabla p|^2 u^\gamma \, dx.$$  

We make use of the Hölder inequality with conjugate exponents $\gamma$ and $\gamma' = \gamma/(\gamma - 1)$ in the first integral of the right hand side and with the pair $\gamma + 1$, $(\gamma + 1)/\gamma$ in the second. Combined with the convexity inequality $ab \leq a^{\theta/p} + b^{q/p'}$, we find, for any $\varepsilon > 0$,

$$\frac{d}{dt} \int_{\mathbb{R}^n} u^\gamma \, dx + 3 \frac{\gamma - 1}{\gamma} \int_{\mathbb{R}^n} |\nabla u^{\gamma/2}|^2 \, dx$$

$$\leq \gamma \|N\|_\infty \int_{\mathbb{R}^n} u^\gamma \, dx + \gamma \|N\|_\infty \int_{\mathbb{R}^n} u^\gamma \, dx +$$

$$\frac{\gamma}{\varepsilon + 1} \int_{\mathbb{R}^n} |\nabla p|^{2(\gamma + 1)} \, dx + \frac{\gamma^2}{\varepsilon + 1} \int_{\mathbb{R}^n} u^{\gamma + 1} \, dx.$$  

In order to control $\nabla p$ we use estimate (4.3) in Lemma 4.1 with $n = 2$, $q = 2(\gamma + 1)$, $\theta = \frac{2}{\gamma + 1}$, and $f = P w$, to conclude that

$$\int_{\mathbb{R}^n} |\nabla p(t, x)|^{2(\gamma + 1)} \, dx$$

$$\leq \|\nabla p_0\|^{2(\gamma + 1)}_{2(\gamma + 1)} + C(m_o) \left(1 + \frac{1}{t^\gamma}\right) \sup_{\frac{1}{2} \leq s \leq t} \left(\int_{\mathbb{R}^n} |w(s, x)|^\gamma \, dx\right)^{\frac{\gamma}{\gamma'}}$$

holds for any $\gamma > \sqrt{2}$. The constant $C(m_o)$ depends on (H) and (H+). This
leads to
\[
\frac{d}{dt} \int_{\mathbb{R}^n} u^\gamma(t, x) \, dx + 3 \frac{\gamma - 1}{\gamma} \int_{\mathbb{R}^n} |\nabla u^{\gamma/2}(t, x)|^2 \, dx \\
\leq \gamma \|N\|_\infty \int_{\mathbb{R}^n} w^\gamma(t, x) \, dx + \\
\gamma \|N\|_\infty \int_{\mathbb{R}^n} u^\gamma(t, x) \, dx + \frac{C(m_0) \gamma}{\varepsilon^{\gamma+1}} \left(1 + \frac{1}{t^\gamma}\right) \sup_{\frac{s}{2} \leq s \leq t} \left(\int_{\mathbb{R}^n} w^\gamma(s, x) \, dx\right)^{\frac{2}{\gamma}} \\
+ \gamma^2 \varepsilon^{\frac{\gamma+1}{2}} \int_{\mathbb{R}^n} u^{\gamma+1}(t, x) \, dx + \frac{\gamma}{\varepsilon^{\gamma+1}} \|\nabla p_0\|_{2(\gamma+1)}^{2(\gamma+1)}.
\]

(4.23)

We also have the following estimate for \(w\)
\[
\frac{d}{dt} \int_{\mathbb{R}^n} w^\alpha(t, x) \, dx + 4 \frac{\alpha - 1}{\alpha} \int_{\mathbb{R}^n} |\nabla w^{\alpha/2}(t, x)|^2 \, dx \\
\leq \|c\|_\infty \int_{\mathbb{R}^n} u^\alpha(t, x) \, dx + \alpha \left(\|c\|_\infty + \|\Delta v\|_\infty\right) \int_{\mathbb{R}^n} w^\alpha(t, x) \, dx.
\]

(4.24)

In order to control the right side with the left side we are forced to select \(\gamma < \alpha < \gamma + 1\). We shall also use Gagliardo-Nirenberg-Sobolev’s inequality: in the whole space \(\mathbb{R}^2\), inequality (3.4) reduces to \(\int \xi^{\alpha+1} \, dx \leq C \int \xi \, dx \int |\nabla (\xi^{\alpha/2})| \, dx\). Thus, adding inequalities (4.23) and (4.24) we obtain, after similar computations to those of the FPD system, the following estimate which holds for any \(t \in (0, T]\)
\[
\frac{d}{dt} Z(t) + C(m_0) Z\gamma'(t) \leq C \left(1 + \|\nabla p_0\|_{2(\gamma+1)}^{2(\gamma+1)}\right) + C(m_0) \left(1 + \frac{1}{t^\gamma}\right) \sup_{\frac{s}{2} \leq s \leq t} \|w\|_{\gamma'}^{\gamma'} \\
\leq C \left(1 + \|\nabla p_0\|_{2(\gamma+1)}^{2(\gamma+1)}\right) + C(m_0) \left(1 + \frac{1}{t^\gamma}\right) \sup_{\frac{s}{2} \leq s \leq t} \|w\|_{\alpha'}^{\alpha'} \\
\leq C \left(1 + \|\nabla p_0\|_{2(\gamma+1)}^{2(\gamma+1)}\right) + C(m_0) \left(1 + \frac{1}{t^\gamma}\right) \sup_{\frac{s}{2} \leq s \leq t} Z^{\frac{\gamma}{\gamma'}}(t).
\]

(4.25)

where
\[
Z(t) := \int_{\mathbb{R}^n} u^\gamma(t, x) \, dx + \int_{\mathbb{R}^n} w^\alpha(t, x) \, dx.
\]

Now apply the comparison Lemma [A.2] to obtain for any \(\gamma > \sqrt{2}\)
\[
Z(t) \leq C(m_0, \gamma) \left(1 + \frac{1}{t^{\frac{\gamma}{\alpha+\gamma}}}\right), \quad 0 < t \leq T.
\]

The constant \(C\) depends additionally on \(\mathbf{H}^{-}(\mathbf{H}+)\) and \(\|\nabla p_0\|_{L^{2(\gamma+1)}}\) but it is independent of \(T > 0\). The case \(\gamma \in (1, \sqrt{2})\) follows by Lebesgue’s interpolation between estimate (4.25) and the mass conservation.
Finally, uniform propagation of the $L^\gamma$ and $L^{\gamma^+}$ norms of $u$ and $w$ follows using previous computations with the estimate (4.4) instead of estimate (4.3) which give us the bound

$$\frac{d}{dt} Z(t) + C(m_o) Z^\alpha'(t) \leq C \left( 1 + \|\nabla p_o\|^{2(\gamma + 1)}_{2(\gamma + 1)} \right) + C(m_o) \sup_{0 \leq s \leq T} Z^{\gamma \alpha'}(s),$$

valid for any $t \in [0, T]$ with $T \geq 1$ and $\sqrt{2} < \gamma < \alpha < \gamma + 1$. The comparison Lemma A.1 gives

$$\sup_{0 \leq s \leq T} Z(s) \leq \max \left\{ Z(0), \left( C \left( 1 + \|\nabla p_o\|^{2(\gamma + 1)}_{2(\gamma + 1)} \right) + C(m_o) \sup_{0 \leq s \leq T} Z^{\gamma \alpha'}(s) \right)^{\frac{1}{\alpha'}} \right\},$$

which implies, since $\frac{\gamma}{\alpha} < 1$, that $\sup_{0 \leq s \leq T} Z(s)$ is finite and uniform in $T$. \qed

4.2.2 From $L^\gamma$ to $L^\infty$ integrability

**Proposition 4.5.** Let $T > 0$. Consider initial data $(u_o, w_o, \nabla p_o) \in L^3 \times L^3 \times L^8$ and, let $(u, w)$ be a classical nonnegative solution of the system (SPD) in the interval $[0, T]$. Then, the following $L^\infty$-estimate holds

$$\|u(t)\|_\infty + \|w(t)\|_\infty \leq C(m_o) \left( 1 + \frac{1}{\sqrt{t}} \right), \quad t \in (0, T], \quad (4.26)$$

where the constant $C$ depends on $[H]$, $[H^+]$ and the initial data, but, it is independent of $T > 0$. In particular, for any $\gamma \in [1, \infty]$ it follows that

$$\|u(t)\|_\gamma + \|w(t)\|_\gamma \leq C(m_o) \left( 1 + \frac{1}{t^{\frac{1}{\gamma}}} \right), \quad t \in (0, T]. \quad (4.27)$$

Furthermore, estimate (4.26) can be upgraded by adding the dependence on the $L^\infty$-norms of the initial data in the constant,

$$\sup_{0 \leq s \leq T} \|w(s)\|_\infty + \sup_{0 \leq s \leq T} \|u(t)\|_\infty \leq C(m_o, \|w_0\|_\infty, \|u_0\|_\infty), \quad (4.28)$$

The constant depend on $[H]$, $[H^+]$ and $\|\nabla p_o\|_\infty$, but, it is independent of the time.

**Proof.** The proof of estimate (4.26) is a direct consequence of De Giorgi level set technique presented in the proof of Proposition 3.3 and Proposition 4.4. The integrability of the initial data assures that the delicate nonlinear term $u \nabla p$ will remain uniformly bounded as required in these arguments. Interestingly, the uniform bound (4.28) is not straightforward to prove. The main reason is the lack of knowledge about the regularity of $\Delta p$, which was a consequence of elliptic regularity for the FPD system. This is where we make
Indeed, let us apply Lemma 4.3 to the population $u$, that is, $ϕ = u$, $f = wN$, and recalling that conservation of mass implies

$$\sup_{0 \leq s \leq T} \|w(s)\|_1 + \sup_{0 \leq s \leq T} \|u(s)\|_1 \leq 2m_o.$$  

Thus, we get

$$\sup_{0 \leq s \leq T} \|u(s)\|_\infty \leq 2\|u_0\|_\infty + C_1^1 \sup_{0 \leq s \leq T} \|\nabla p(s)\|_\infty + C_2^2 \sup_{0 \leq s \leq T} \|u(s)\|_\infty.$$  

(4.29)

Now, apply Lemma 4.1 with $q = \infty$ and $\theta = 2$, to the pheromone equation to obtain

$$\sup_{0 \leq s \leq T} \|\nabla p(s)\|_\infty \leq 2\|\nabla p_0\|_\infty + C_3 \sup_{0 \leq s \leq T} \|w(s)\|_\infty^{\frac{n-1}{n}}.$$  

(4.30)

Noticing that $c \leq c_0$, we may apply Lemma 4.3 to the population $w$ as well to conclude that

$$\sup_{0 \leq s \leq T} \|w(s)\|_\infty \leq 2\|w_0\|_\infty + C_2^1 \|\nabla v\|_\infty + C_5 \sup_{0 \leq s \leq T} \|u(s)\|_\infty^{\frac{n-1}{n+1}}.$$  

(4.31)

In addition to the mass, the constants depend on the $L^\infty$-norms of the parameters and grow logarithmically in time. Plugging successively (4.31) in (4.30) and the result in (4.29) the estimate for the population $u$ reduces to

$$\sup_{0 \leq t \leq T} \|u(t)\|_\infty \leq C_o + C_1 \sup_{0 \leq s \leq T} \|u(s)\|_\infty^{\frac{(n-1)^2}{n+1}} + C_2 \sup_{0 \leq s \leq T} \|u(s)\|_\infty^{\frac{(n-1)^2}{(n+1)^2}}.$$  

(4.32)

where $C_o$ depends on the initial data and $\|\nabla v\|_\infty$. Since $\frac{1}{2} = \frac{(n-1)^2}{n+1} < 1$ the result follows for short $T > 0$ with constants growing at most $\ln(T)$. For large $T > 0$ the result follows after simple interpolation with estimate (4.26). 

**Remark 4.6.** The maximal exponent in the right side of (4.32) $\frac{(n-1)^2}{n+1} \geq 1$ for $n \geq 3$. This suggest, for these dimensions, a finite in time Dirac concentration of mass similar to that of the Keller-Segel model in two or more dimensions. Similarly, such concentration could be avoided by smallness conditions on the initial data and model parameters.

### A A useful comparison lemma

**Lemma A.1** (ODE comparison). Assume $Y$ and $X$ are absolutely continuous functions in $[0, T]$ and such that

$$Y'(t) + a Y^\alpha(t) \geq b + \delta + c \left(1 + \frac{1}{t^\gamma}\right) \sup_{\tau \leq s \leq t} Y^\alpha(s)$$

$$X'(t) + a X^\alpha(t) \leq b + c \left(1 + \frac{1}{t^\gamma}\right) \sup_{\tau \leq s \leq t} X^\alpha(s),$$

(A.1)
with \( b \geq 0, c \geq 0, a > 0, \delta > 0, \alpha > \alpha_0 \geq 0, \gamma \geq 0 \) and \( t \geq \tau \geq 0 \). If \( Y(0) > X(0) \) then \( Y \geq X \) in \([0,T]\). In particular, if \( \gamma = 0 \)

\[
\sup_{t \in [0,T]} X(t) \leq \max\{X(0), C\}, \tag{A.2}
\]

where the constant \( C > 0 \) depends on all parameters but \( \tau, \delta \) and \( T \).

**Proof.** Define

\[ t_\alpha := \sup \{ t : Y(s) \geq X(s), s \in [0,t] \} . \]

Note that \( t_\alpha > 0 \) since \( Y(0) > X(0) \). Let us argue by contradiction assuming that there exists \( t_1 \in (0,T] \) such that \( X(t_1) > Y(t_1) \). Since \( X \) and \( Y \) are continuous \( t_\alpha \in (0,T) \) and \( X(t_\alpha) = Y(t_\alpha) \). Also, there exists interval \( I = (t_\alpha, t_\alpha + \varepsilon) \) such that \( X(t) > Y(t) \) for any \( t \in I \). Thus, the fundamental theorem of calculus implies

\[
\int_{t_\alpha}^{t} X'(s) \, ds = X(t) - X(t_\alpha) > Y(t) - Y(t_\alpha) = \int_{t_\alpha}^{t} Y'(s) \, ds, \quad t \in I .
\]

Therefore, there exists \( t_* \in I \) sufficiently close to \( t_\alpha \) such that: (1) \( X \) and \( Y \) are differentiable at \( t_* \) with \( X'(t_*) > Y'(t_*) \), and (2) \( c(1 + \frac{1}{t_*}) \left( \sup_{\tau \leq s \leq t_*} Y^{\alpha}(s) - \sup_{\tau \leq s \leq t_*} X^{\alpha}(s) \right) \geq -\delta \). Thus, using (A.1)

\[
0 > Y'(t_*) - X'(t_*) \geq a \left( X^{\alpha}(t_*) - Y^{\alpha}(t_*) \right) + \delta + c \left( 1 + \frac{1}{t_*^2} \right) \left( \sup_{\tau \leq s \leq t_*} Y^{\alpha}(s) - \sup_{\tau \leq s \leq t_*} X^{\alpha}(s) \right) \geq 0 .
\]

This contradicts the existence of \( t_1 \). Finally, the estimate (A.2) follows by taking \( Y := Y_\delta \) as the constant function in \([0,T]\) given by \( \max\{X(0) + \delta, C_\delta\} \) where

\[
C_\delta = \frac{2}{a} \left( b + \delta + \frac{1}{\varepsilon(\alpha/\alpha_0)} \right), \quad \varepsilon^{\alpha/\alpha_0} = \frac{a}{4c} .
\]

Then, \( X(t) \leq Y_\delta \) for any \( \delta > 0 \). The result follows by sending \( \delta \to 0 \). \( \square \)

**Corollary A.2.** Assume \( X \) be an absolutely continuous function in \([0,T]\) such that

\[
X' + aX^{\alpha} \leq b + c \left( 1 + \frac{1}{t} \right) \sup_{\frac{1}{2} \leq s \leq t} X^{\alpha}(s) ,
\]

with \( b \geq 0, c \geq 0, a > 0, \alpha > \alpha_0 \geq 0 \) and \( \gamma \geq 0 \). Then,

\[
X(t) \leq C \left( 1 + \frac{1}{t^\beta} \right), \quad \beta = \max \left\{ \frac{1}{\alpha}, \frac{\alpha}{\alpha - \alpha_0} \right\} .
\]

The constant \( C > 0 \) depends on all parameters but it is independent of \( T \).
Proof. First note that the function

\[ Y(t) = C \left( 1 + \frac{1}{t^\beta} \right) \]

satisfies \( Y'(t) + a Y^{\alpha}(t) \geq b + \delta + (1 + \frac{1}{t^\gamma}) \sup_{\frac{s}{2} \leq s \leq t} Y^{\alpha}(s) \) for \( C \) sufficiently large depending on all parameters. Second, since \( X \) is bounded on \([0, T]\), there exists sufficiently small \( t_o > 0 \) such that \( Y(s) > \sup_{t \in [0, T]} X(t) \) for \( s \in (0, t_o) \). Applying Lemma \([\Delta]\) in the interval \([s, T]\) it follows that \( Y \geq X \) in \([s, T]\). The result follows since \( s \) can be taken arbitrarily small.

\[ \square \]

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