Cyclic Prefix Adaptation with Constant Overall Symbol Time for DFT-spread-OFDM and OFDM

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Abstract—For DFT-spread-OFDM or OFDM, if the delay spread varies in a wide range and the symbol duration is relatively short, adapting the cyclic prefix (CP) duration rather than using a fixed one may significantly improve the spectral efficiency while preventing inter-symbol interference (ISI). In practice, it may be beneficial to have a constant overall DFT-spread-OFDM/OFDM symbol time, which is the sum of the duration of a CP and the duration of a data portion. We propose to adapt the CP duration to the delay spread without changing the overall symbol time for DFT-spread-OFDM or OFDM, and address implementation challenges. In particular, we propose changing the clocking rate of ADC and DAC or using a Farrow filter to reduce the computational complexity of arbitrary-size DFT/IDFT resulting from the adaptation.

I. INTRODUCTION

Cyclic prefix (CP) has been widely used in practice to mitigate inter-symbol interference (ISI), for example, for OFDM in the UMTS long-term evolution (LTE) downlink and in IEEE 802.11a/g/n/ac, and for DFT-spread-OFDM in the LTE uplink. To fully eliminate ISI, the length of the CP should be at least as long as the delay spread. On the other hand, to maintain good spectral efficiency, the CP length cannot be too long.

It has long been noted that the delay spread may vary significantly from user to user, and from cell to cell. That motivated the definition of two CP lengths in LTE: a normal CP of length 4.7 μs and an extended CP of length 16.7 μs [1]. The extended CP is intended to be used in environments of extensive delay spread (e.g., in large cells) or in the Multicast/Broadcast over Single Frequency Network (MBSFN) where the effective delay spread could be large due to the difference in propagation delays from different base stations.

Recent measurement studies show that for millimeter-wave wireless channels at 28GHz and 73GHz, the maximum root-mean-square (RMS) delay spread (defined as the RMS of the power delay profile) could be tens of times greater than the average RMS delay spread and hundreds of times greater than the minimum [2]. For the millimeter wave, the symbol duration tends to be short. Therefore, if we use a fixed CP length to prevent ISI, we have to make the CP long enough to accommodate the maximum RMS delay spread, resulting in very inefficient use of the transmission time. As an example, take the maximum RMS delay spread to be 200.3ns and the average 12.1ns at 73GHz from Table 2 of [2]. Let the subcarrier spacing be 0.5MHz, which implies a data portion of 2μs within an overall symbol time. We set the CP length to be a multiple, say, six times, of the RMS delay spread. This setup would ensure that 99.7% of the delay lines to be covered by the CP if the delay lines follows a Gaussian distribution. To use a common CP length targeting the maximum, the CP would be 6 × 200.3ns and the overhead would be 1.2/(2+1.2) = 37.5%. In contrast, the overhead could be reduced to 3.5% if the CP length is set to 6 times of the actual RMS delay spread.

There has been a large amount of research on optimizing the CP duration for maximizing the spectral efficiency [3][4]. However, to our knowledge, in the existing works the duration of a DFT-spread-OFDM/OFDM symbol, which in this paper includes a CP and a data portion as done in [1, p. 322], changes with the CP duration because the duration of the data portion is fixed, making it hard to compose fixed-duration frame structures while maintaining desired spectral efficiency. One needs to be aware that in the literature the DFT-spread-OFDM symbol may refer to the data portion only.

In practice, it is desirable to have a fixed subframe duration for synchronous communication systems such as LTE. For one thing, it simplifies resource allocation and inter-cell interference management [5] by having a common time unit. For another, it helps with backward compatibility with older systems that allocate network resource to a user in some basic time units, for example, the transmission time interval (TTI) of 2ms in HSPA and of 1 ms in LTE [1].

We propose Adaptive CP to adapt the CP duration to the delay spread without changing the overall DFT-spread-OFDM or OFDM symbol time, as illustrated in Fig. 1, where $T_c$ is the CP duration and $T_d$ is the data portion duration. With Adaptive CP, a constant subframe duration is easily achieved and essentially there is no constraint on the granularity of the CP duration. It was considered infeasible in [5] to adapt the CP duration with fine granularity to the delay spread while meeting the constraint of a fixed subframe duration under the implicit assumption that $T_d$ is fixed. To see it, suppose that the subframe duration is equal to 500 μs and $T_d = 66.7\mu$s as in LTE. Let $n$ be the integer number of symbols that fill up a subframe. Then $T_c$ must satisfy $n(66.7 + T_c) = 500$, which gives only two solutions 4.7 μs and 16.7 μs that have relatively low overhead among all possible solutions. In our present work, we remove the constraint that $T_d$ is fixed, and as a result we are able to achieve fine granularity in adapting the CP.
duration to the delay spread. However, removing the constraint also leads to challenges in system design and implementation, which we will address in this paper.

besides the CP, the zero tail is also proposed for delay spread adaptation as in zero-tail DFT-spread-OFDM [5]. However, the tails are not exactly zeros and are data dependent, and as a result exact cyclic convolution is not achieved, which may lead to significant bit error rate (BER) performance degradation at high SNR. To illustrate, we look at the performance of adaptive CP and zero-tail DFT-spread-OFDM. Due to the lack of a publicly available channel for mmWave at the moment, we use the extended pedestrian A (EPA) channel model of LTE [6] for the simulation study. The delay spread is 410ns. The overall symbol duration \( T = 2.083 \text{ } \mu\text{s} \), \( T_c = 1.1 \times 410 \text{ } \text{ns} \), \( M = 1024 \), \( N = 2048 \) and \( N = 1632 \), where \( M, N \) and \( N \) are defined in Sections II and III. The standard MMSE equalizer is used. For zero-tail DFT-spread-OFDM, the zero tail is equal to the delay spread. For Adaptive CP, the CP duration is equal to the delay spread. We see that the two schemes have similar performance until about 15dB when Adaptive CP begins to outperform zero-tail DFT-spread-OFDM. The divergence in performance is attributed to the fact that our approach completely removes ISI while zero-tail DFT-spread-OFDM does not and that the difference becomes significant at high SNR.

channel, which may be hard to do in practice. Recently, the idea of unique word is extended to DFT-spread-OFDM [8].

The remainder of the paper is organized as follows. Section II presents the adaptation scheme without regard to computational complexity. Section III proposes solutions to reduce the computational complexity. Lastly, Section IV concludes the paper.

II. ADAPTING THE CP DURATION

A. Single user support

The system architecture is shown in Fig. 3. QAM symbols are fed to the system in blocks of length \( M \). Consider an arbitrary block \( \mathbf{u} = (u_0, u_1, \ldots, u_{M-1})^T \), where \( T \) stands for transpose. Let the output of the \( M \)-point DFT module be \( \mathbf{U} = \text{DFT}(\mathbf{u}) = (U_0, U_1, \ldots, U_{M-1})^T \), where \( U_k = \sum_{n=0}^{M-1} u_ne^{-j2\pi nk/M} \), where \( k = 0, 1, \ldots, M-1 \). Let \( \mathbf{P} \) be an \( N \times N \) permutation matrix used in subcarrier mapping. Let \( \mathbf{0}_1 \times (N-M) \) be a \( 1 \times (N - M) \) vector with all entries being 0. The subcarrier mapping results in an \( N \)-vector \( \mathbf{D} = \mathbf{P}(\mathbf{U}^T, \mathbf{0}_1 \times (N-M))^T \), which is fed to the \( N \)-point DFT module, resulting in \( \mathbf{d} = \text{IDFT}(\mathbf{D}) = (d_0, d_1, \ldots, d_{N-1})^T \), where \( d_k = \sum_{n=0}^{N-1} D_ne^{j2\pi nk/N} \), where \( k = 0, 1, \ldots, N-1 \). Let the channel impulse response (CIR) be \( K + 1 \) samples long. The addition of a CP of \( K \) samples results in the signal \( \mathbf{x} = (d_{N-K}, d_{N-K+1}, \ldots, d_{N-1}, d_0, d_1, \ldots, d_{N-1})^T \) of length \( (N + K) \), which is then passed to the DAC module, carrier modulated, and transmitted across the continuous-time channel which induces a discrete-time CIR \( \mathbf{h} \). The received signal \( \mathbf{y} = \mathbf{h} \otimes \mathbf{d} + \mathbf{z} \), where \( \otimes \) stands for circular convolution and \( \mathbf{z} \) for noise. \( \mathbf{Y} = \text{DFT}(\mathbf{y}) \) and \( \mathbf{W} \) is equal to elements 1 through \( M \) of \( \mathbf{P}^{-1}\mathbf{Y} \), where \( \mathbf{P}^{-1} \) is the inverse permutation. The equalization output is \( \hat{\mathbf{U}} \), and the \( M \)-point IDFT output is \( \hat{\mathbf{u}} \).

Now we consider how to determine the CP duration \( T_c \) (in seconds) and the data portion duration \( T_d \) (in seconds). The overall symbol time \( T \) is chosen such that it is long enough to have a reasonably high efficiency \( T_d/T \) while not being too long in order to satisfy other requirements such as limiting carrier-frequency offset and having an almost constant channel during \( T \). The procedure of adapting \( T_c \) to the delay spread is as follows. A statistic about the delay spread, for example the RMS delay spread \( \tau \), is measured at the receiver, and fed back to the transmitter. Then, \( T_c \) could be set as a multiple of \( \tau \). Note that the discrete-time signal \( \mathbf{x} \) enters the DAC module one sample per \( T_s \), where \( T_s \) is the period of the clocking signal of the DAC. Therefore, \( T_c = KT_s \), yielding

\[
K = T_c/T_s, \tag{1}
\]

where we ignore the ceiling operation to simplify the notation. To maintain the same subframe duration, we keep the overall symbol duration \( T = T_c + T_d \) constant. Thus, \( T - T_c = NT_s \), or

\[
N = (T - T_c)/T_s. \tag{2}
\]
To achieve orthogonality among subcarriers, the subcarrier spacing $\Delta f = 1/(T - T_c)$. The bandwidth $B$ (in Hertz) of the DAC converted signal is

$$B = N\Delta f = N/(T - T_c) = 1/T_s.$$  

It follows from (3) and (2) that in order to keep $B$ the same, $T_s$ must remain the same and $N$ must be proportional to $T - T_c$.

To enable Adaptive CP for OFDM, we simply remove the $M$-point DFT and IDFT and set $M = N$ in Fig. 3.

**B. Multiuser support**

In order to effectively support multiple users, the CP duration cannot be solely determined by the delay spread of individual users. Otherwise, multiple users on disjoint subcarriers with different CP durations may interfere with one another during simultaneous transmissions. This is shown in Fig. 4(a), where we consider the receiving of two simultaneous transmissions at user 2: one intended for user 1 and the other for user 2. Because the duration of CP1 is shorter than that of CP2, the superposed signal falling within user 2’s DFT window is no longer circular, making the convolution non-circular.

A similar problem exists with many other approaches such as [5][7]. In fact, as long as the CPs, zero-tails, or UWs are of different lengths, mutual interference may occur between users. As an example, Fig. 4(b) shows that for zero-tail OFDM [7] the fact that the two data segments $e_{11}$ and $e_{12}$ are almost always different breaks the cyclicity of the received signal in user 2’s DFT window. Note that the CIRs shown in the figure are the ones seen by user 2.

One approach to addressing the issue with Adaptive CP is to take the maximum of RMS delay spreads of only the users scheduled for simultaneous transmissions and configure these users with a common CP duration corresponding to the maximum. With this, significant gains could be achieved because the maximum of the delay spreads of a small number of users could be dramatically lower than that of all users in a cell.

A second approach is to configure a common CP duration for users of similar delay spreads and schedule only users of the same CP duration for simultaneous transmissions. A third approach is to use a filter to select only the desired frequencies for each intended receiver before doing DFT at the receiver.

The idea of filtering on subcarriers or groups of subcarriers has been proposed for Filtered OFDM, Filter Bank Multicarrier [9] and resource block filtered OFDM [10].

**III. REDUCING COMPUTATIONAL COMPLEXITY**

We now present ways to reduce the complexity of the design in Section II. The main complexity in Fig. 3 comes from DFT and IDFT, which have complexity about $N^2$ multiplications. The complexity is prohibitive for large $N$. However, if $N$ is a power of 2, we can use the efficient implementation radix-2 FFT, which has much lower complexity of about $(N/2)\log_2 N$ multiplications. On the other hand, if $N$ is not a power of 2, we need to explore other solutions. Mixed-radix IFFT/FFT (by factorizing $N$ into the powers of small prime numbers) has been considered in practice. However, the factorization changes with $N$, leading to changes in the hardware, which is undesirable in practice. We propose two solutions next.

**A. Changing the clocking rate for ADC and DAC**

We choose $\tilde{N}$ to be a power of 2 and append zeros to $\mathbf{D}$ to get a length-$\tilde{N}$ vector

$$\tilde{\mathbf{D}} = (\mathbf{D}^T, 0_{1\times(\tilde{N} - N)})^T$$  

and then apply $\tilde{N}$-point radix-2 IFFT, as shown in Fig. 5(a). Next, the IFFT output is clocked into the DAC at a rate $F_s = \tilde{N}F_s/N$ and denote the DAC output as $\tilde{d}(t)$. Let the DAC output for the case of direct IDFT computation be $d(t)$. We claim that:

**Theorem 3:** With the above zero-padding and clocking rate changing, $\tilde{d}(t) = d(t)$.

**Proof:** The IDFT output in Fig. 3 is

$$d(n) = \sum_{k=0}^{N-1} D_k e^{j2\pi kn/N} = \sum_{k=0}^{N-1} D_k e^{j2\pi n t_k/(T_s)}, 0 \leq n \leq N-1. $$  

Since $d(n)$ is fed into the DAC at rate $F_s = 1/T_s$, by the Sampling Theorem the DAC output

$$d(t) = \sum_{k=0}^{N-1} D_k e^{j2\pi n t_k/T_s}, 0 \leq t \leq T - T_c. $$

This relationship is also explained in texts such as [11].
Similarly, by the Sampling Theorem, we have
\[ \tilde{d}(n) = \sum_{k=0}^{N-1} D_k e^{2\pi i k n / N} = \sum_{k=0}^{N-1} D_k e^{\frac{2\pi i k n}{NT_s}}, \quad 0 \leq n \leq N-1 \]  
(7)

Since \( \tilde{F}_s = \tilde{N} F_s / N \), we have
\[ \tilde{N} \tilde{T}_s = NT_s. \]
(9)

Comparing (6) with (8), we have that \( d(t) = \tilde{d}(t) \).

Let the CP length in samples be \( K \), then \( T_c / (T - T_c) = \tilde{K} / \tilde{N} \), which together with (9) yields
\[ \tilde{K} = T_c / \tilde{T}_s. \]
(10)

The total bandwidth \( \tilde{B} \) is
\[ \tilde{B} = N / (T - T_c) = N / (\tilde{N} \tilde{T}_s). \]
(11)

To account for the limited granularity of the clocking rate provided by a frequency synthesizer, we can work backwards from a set of \( L \) available clocking rates \( \tilde{T}_{s(1)}^\prime, \tilde{T}_{s(2)}^\prime, \ldots, \tilde{T}_{s(L)}^\prime \) to determine \( T_c \) by (9) and \( N \tilde{T}_s = T - T_c \), \( \tilde{K} \) by (10), and \( \tilde{B} \) and \( N \) by (11).

### B. Fractional sampling rate conversion

In this approach, we keep the clocking rate of the DAC (and ADC) at \( F_s \), as shown in Fig. 5(b). To ensure that \( d(t) \) is of duration \( T - T_c \), we convert \( \tilde{d}(n) \), which corresponds to oversampling \( d(t) \) at sampling frequency \( \tilde{F}_s = F_s \tilde{N} / N \), into a shorter sequence \( d(n) \) at a reduced sampling rate \( \tilde{F}_s \). Polyphase filter decomposition [13] can be used, as shown in Fig. 6, where \( \tilde{h}_i \)'s are the polyphase filters, \( i = 1, 2, \ldots, p \). The complexity is reduced if \( N / \tilde{N} \) can be written as a ratio of two small integers \( p \) and \( q \) that are relatively prime, i.e., \( N / \tilde{N} = p / q \). For example, for \( N = 1536 \) and \( \tilde{N} = 2048 \), we have \( p = 3 \) and \( q = 4 \). However, such simplification is not always available, especially if we want to have fine granularity in the CP duration adaptation. Additionally, when \( N \) changes, the hardware structure for polyphase decomposition will change as well, which increases hardware complexity. This is clear because the original lowpass filter to be decomposed, which has a passband \([-1/(2 \max(p, q)), 1/(2 \max(p, q))]\) in relative frequency, changes with \( p \) and \( q \), and the number of polyphase filters (which is equal to \( p \)) changes with \( p \).

Alternatively, Farrow filter approximation [14, pp. 185-196] can be used to do arbitrary sampling rate conversion without changing the hardware structure. It works as follows. First, choose a constant integer \( p \) and solve for \( q = p N / \tilde{N} \). Note that here \( q \) may not be an integer any more. Then use lower order polynomials to approximate successive fragments of the original lowpass filter. Lastly `decimate` the output of the polyphase filters in strides of \( q \), corresponding to a step size of \( q / (p \tilde{F}_s) \) in seconds. A special treatment can significantly simplify the design. The original lowpass filter is symmetric in the frequency domain, but the spectrum of the output of the IFFT module is asymmetric with a support of \([0, N / \tilde{N}]\) in relative frequency, resulting in a zero-interpolated signal with asymmetric spectrum with a support \([i/p, N / (p \tilde{N}) + i/p], i = 0, \pm 1, \ldots\), as illustrated in the top plot of Fig. 7. To resolve this mismatch, we shift the spectrum of the IFFT output by multiplying \( d(n) \) with a phase \( \exp(-j \pi n N / \tilde{N}) \). This phase shift makes the spectrum of the interpolated signal symmetric.
in the frequency domain as shown in the middle plot of Fig. 7. An inverse phase shift \( \exp(j\pi n N/N) \) is applied to the output of the Farrow filter. The polynomial approximation can result in very good performance, as illustrated in Fig. 8 for the first 100 data points of the IDFT/IFFT output. The relative MSE is -44.4dB, well below the effect of noise in a typical operating environment.

Fig. 6. Polyphase decomposition for factor \( p/q \) sampling rate conversion.

The Farrow approximation offers attractive complexity reduction. Assume that the original lowpass filter has a length \( L \), and the polynomials are of order \( \alpha \). Then, each polyphase filter has a length \( [L/p] \). Using Horner’s rule [14, p. 196], the evaluation of a polynomial requires \( \alpha \) multiplications. There are 2 multiplications for phase shifts for each sample. The total complexity is about \( (\alpha + 1) [L/p] + 2 + \frac{\alpha}{p} \log_2 N \) multiplications per input sample, as opposed to \( N \) in the direct IDFT/DFT approach. For the example in Fig. 8, \( L = 231, p = 9, \alpha = 4 \). We have 146 multiplications per sample for the Farrow approximation method, as opposed to 1543 multiplications in the direct IDFT computation method.

Fig. 7. Amplitude of frequency response as a function of relative frequency for \( N = 1543 \) and \( N = 2048 \) and an interpolation factor \( p = 9 \). Top: interpolated signal; middle: shifted interpolated signal (blue line) and low pass filter (red line); bottom: filtered shifted interpolated signal.

Note: The Farrow approximation based approach described here offers a way to efficiently calculate arbitrary-size DFT or IDFT, and it can find many applications in practice.

IV. CONCLUSION

We propose to adapt the CP duration to the delay spread without changing the overall symbol duration for DFT-spread-OFDM and OFDM to improve the spectral efficiency, and address the challenges in practical implementations. In particular, we propose changing the ADC/DAC clocking rate or computing arbitrary-size IDFT/DFT using Farrow approximation.

Fig. 8. The real part of the IDFT output by direct computation (red circles with dashed line) and by Farrow approximation (blue crosses with dotted line) with order-4 polynomials.

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