Neuronal Adaptation Translates Stimulus Gaps into a Population Code

Chun-Wei Yuan¹, Leila Khouri¹,², Benedikt Grothe¹, Christian Leibold¹*

¹ Department Biologie II, Ludwig-Maximilians-Universität München, Planegg-Martinsried, Germany, ² Department of Neurobiology, The Hebrew University of Jerusalem, Jerusalem, Israel

**Abstract**

Neurons in sensory pathways exhibit a vast multitude of adaptation behaviors, which are assumed to aid the encoding of temporal stimulus features and provide the basis for a population code in higher brain areas. Here we study the transition to a population code for auditory gap stimuli both in neurophysiological recordings and in a computational network model. Independent component analysis (ICA) of experimental data from the inferior colliculus of Mongolian gerbils reveals that the network encodes different gap sizes primarily with its population firing rate within 30 ms after the presentation of the gap, where longer gap size evokes higher network activity. We then developed a computational model to investigate possible mechanisms of how to generate the population code for gaps. Phenomenological (ICA) and functional (discrimination performance) analyses of our simulated networks show that the experimentally observed patterns may result from heterogeneous adaptation, where adaptation provides gap detection at the single neuron level and neuronal heterogeneity ensures discriminable population codes for the whole range of gap sizes in the input. Furthermore, our work suggests that network recurrence additionally enhances the network's ability to provide discriminable population patterns.

**Introduction**

Behaviorally relevant auditory signals such as speech, or the reverberations that convey information about the spatial environment, are characterized by temporal features in the lower millisecond range. The intrinsic time scales of neurons that represent the auditory information in the downstream cortical processing centers are, however, much slower [1,2]. The general view of the auditory pathway is thus that it translates the temporal code of the acoustic wave into the population code of the cortex, and relaxes the required temporal precision of cortical processing to the time scale of tens of milliseconds [3–5]. This translation between time and rate representation is assumed to gradually occur along the multiple processing centers in the auditory brainstem [6,7].

A central stage in the ascending auditory pathway is taken by the inferior colliculus (the auditory midbrain), which collects most afferent projections and transfers them to the thalamo-cortical system [8]. In this sense the inferior colliculus acts as a hub, meaning that most auditory information processed by cortical centers has to be somehow represented in the inferior colliculus. The neurons in the inferior colliculus are characterized by a large diversity of in vivo responses [5,9,10] and cellular parameters, in particular temporal ones such as onset vs. sustained firing [11], membrane time constants and adaptation currents [12]. It is therefore reasonable to assume that the inferior colliculus population represents acoustic information in both spike timing and rate [13,14]. Moreover, one expects the rich assortment of neuronal behaviors observed at the inferior colliculus to play a central role in the computational capacity of the population code.

In this paper, we investigate the transformation from a temporal to a population representation using the simple paradigm of gap stimuli. We re-analyzed in-vivo recordings from anesthetized gerbils to show that such transformation indeed takes place at the level of the inferior colliculus. We then construct a computational model suggesting that the heterogeneity of biophysical properties of the neurons, particularly of their adaptation time constants, can explain the in-vivo phenomenology.

**Materials and Methods**

**Ethics Statement**

All experiments were approved according to the German Tierschutzgesetz (AZ 55.2-1-54-2531-57-05 Regierung von Oberbayern). For more details see original data publication [15].

**Data Analysis**

We re-analyzed previously published single unit recordings from 91 inferior colliculus neurons of young adult Mongolian gerbils with best frequencies from 2 to 12 kHz [15]. Each stimulus was composed of a series of symmetric, broadband (500 Hz to 12 kHz) sound pulses of 128 ms duration interjected with silent intervals (gaps) of a fixed length, as shown in Figure 1A. The pulse-gap interfaces used in the experiment were ramped with 1 ms rise and fall times. These ramps are assumed to be negligible compared to the duration of the sound pulse (128 ms) for further analysis of the
population code, hence these ramps are shown as steps in the schematics of Figure 1A. Between stimuli, the gap lengths range exponentially from 2 to 128 ms (2^1,…,7 ms). Therefore, each stimulus pulse train is characterized by the particular gap length it carries.

Due to the limit on the total length of the stimulus, the number of times the sound pulses are repeated per pulse train varies, as illustrated in Figure 1A. The resultant pulse trains were presented to the anesthetized animal through ear phones, and each neuron was recorded over multiple (10) trials of the same pulse train.

The mean population rate response to each stimulus is shown in Figures 1B–H. The network response to the stimulus typically follows a transmission delay. By inspecting the ramp-up of the population rate response relative to the first pulse in the stimulus, we consistently found this latency to be 12 ms across different gap stimuli. This transmission delay is already applied in Figures 1B–H, where time = 0 denotes the onset of the network’s reaction to the first (control) pulse of the stimulus (gap size = ∞), and the dashed lines represent the gap-to-pulse interfaces. All single-neuron spike times for later analyses are latency-corrected according to this transmission delay.

The spike times were translated into post-stimulus time histograms ri(t,ℓ),t = 1,…,91 (bin size 10 ms) by averaging over all repetitions of post gap activity snippets, where i denotes the neuron index, t denotes the post-gap time, and ℓ denotes the gap length.

Independent Component Analysis

For our independent component analysis (ICA), we employ the FastICA algorithm [16] on the vectors

\[ \tilde{r}(t,\ell) = [r_1(t,\ell), \ldots, r_N(t,\ell)]^T \]

considering all combinations of t and ℓ as single measurements. As a means of noise-filtering, ICA is applied on a low-dimensional subspace identified by the number Npc of principal components of the full data set of 91 dimension. PSTHs in this low dimensional space are denoted as \( \tilde{R}(t,\ell) \), i.e., every PSTH vector \( \tilde{r}(t,\ell) \) is approximated by a linear superposition of \( N_{pc} \) ICs \( \tilde{a}_n, n = 1, \ldots, N_{pc} \),

\[ \tilde{r}(t,\ell) \approx \tilde{R}(t,\ell) = \sum_{n=1}^{N_{pc}} \rho_n(t,\ell)\tilde{a}_n. \]  

(1)

The ICs are normalized, \( |\tilde{a}_n| = 1 \), and \( \rho_n(t,\ell) \) denote the projections to the subspace spanned by \( \tilde{a}_n \). Note that \( \{\tilde{a}_1, \ldots, \tilde{a}_{N_{pc}}\} \) do not necessarily form an orthogonal basis set and thus the projections are calculated as \( \rho_n = \tilde{w}_n^\top\tilde{R} \), using the dual basis \( \{\tilde{w}_1, \ldots, \tilde{w}_{N_{pc}}\} \) defined by

\[ \tilde{w}_n^\top\tilde{a}_m = \delta_{nm}. \]

An important step is to find the minimum value of \( N_{pc} \) that captures all gap-sensitive components. To determine this value, we begin with \( N_{pc} = 1 \) and examine the resultant independent component. We then increment \( N_{pc} \) by 1 until we reach a final \( N_{pc} \) beyond which no more gap-sensitive ICs can be identified by visual inspection. For most analyses we thereby obtained \( N_{pc} = 3 \), explaining 73% of the data variance. This approach allowed us to extract all gap-sensitive ICs that possess enough signal strength.

Neuron Model

As a neuronal model, we use the integrate-and-fire neuron, where the membrane voltage \( v_M \) integrates exponentially-decaying synaptic currents (see Section Synapse Model). Simulations are performed using the Neural Simulation Technology (NEST) Initiative software package, version 2.0 [17], at a time resolution of 0.1 ms.

The membrane time constant \( \tau_m = 30 \text{ ms} \) and membrane capacitance \( (C = 120 \text{ pF}) \) are taken from the mean experimental values of [18] unless otherwise mentioned. The membrane potential thus follows the dynamics

\[ \frac{d}{dt} v_M = -(v_M - V_r)/\tau_m + I_S(t)/C. \]

where \( I_S(t) \) denotes the synaptic current (see below). The resting
potential (and reset potential) of every neuron is $V_r = -70$ mV, while the spike threshold is set to be $V_{th} = -55$ mV. These values are only used for convenience of illustrations in the Figures. The values are effectively irrelevant for the neuron model used (integrate and fire with current-based synapses), since their difference only acts as a scaling factor for synaptic strengths. After a spike, the membrane voltage $v_M$ is reset to the resting potential and the neuron goes through a refractory time of $t_{ref} = 2$ ms (limiting the maximal firing rate to below 500 Hz), before post-synaptic currents are integrated again.

Adaptation is implemented as an exponentially-decaying hyperpolarizing potential $v_A$ that follows the dynamics

$$\frac{dv_A}{dt} = -v_A/\tau_{adp} - V_{adp} \sum_{i \neq j} \delta(t - t_i).$$

Each spike (at time $t_i$) decrements $v_A$ by $V_{adp} = -15$ mV and $v_A$ decays back to zero with a time constant $\tau_{adp}$ that may be different for each neuron. This adaptation effect is additive; hence, the resulting adaptation potential

$$v_A(t) = -15 mV \sum_{i \neq j} \exp[-(t-t_i)/\tau_{adp}]$$

and the membrane voltage $v_M$ are evaluated separately and summed up afterwards to be compared to the threshold $V_{th}$.

**Network Topography**

For our standard network, we use the following parameters: $N_{inp} = 1000$ inputs are feed-forwardly directed to a network of the same size ($N = 1000$ neurons). Each input fiber projects to a small random fraction of $N \times c_{inp} = 50$ network neurons, where $c_{inp} = 0.05$ is the input connectivity. Also the recurrent network connectivity $c = 0.05$ is sparse: each network neuron is connected to $N \times c = 50$ other network neurons. Thus, the total impact of feed-forward and recurrent connections is balanced.

In some simulations we use different values of $N$, $N_{inp}$, $c$, and $c_{inp}$ as indicated.

**Synapse Model**

Synaptic currents

$$I = w \sum_{i \neq j} \exp[-(t-t_i)/\tau]$$

are evoked by input spikes at times $t_i$, and decay exponentially with time constants $\tau$ of 3 ms for inhibition and 2 ms for excitation as measured in [18].

For the feed-forward input to the network, the excitatory synaptic weight is set to be $w_{inp} = c_{inh} = 600$ pA, roughly half of what is needed to bring a neuron to threshold from resting potential. Within the network, the weight of recurrent excitation $w_{exc}$ is measured in units of $\omega_{exc} = 600$ pA/($N \times p \times c$), where $p$ is the fraction of the excitatory neurons in the network. For inhibition, the weight $w_{inh}$ is given in units of $\omega_{inh} = 600$ pA/($N \times (1 - p) \times c$)

All synaptic transmissions introduce an additional delay of 1 ms, which is a typical value in many modelling studies.

**Linear Classifier**

To test how well the network activity discriminates between different gap sizes in the input we trained a linear classifier. The performance of the classifier on the test set (test accuracy) is used as a criterion for discriminability. As a linear classifier we use the LIBSVM support vector machine implementation provided by the SHOGUN machine learning toolbox [19].

We began by constructing $P$ unique pairs of spike trains snippets. Each snippet pair was then used to build 2 input patterns, one with gap size $A$ and the other with gap size $B$. The resultant input patterns were fed to the network to train the classifier. Each output vector was generated by counting the spikes in the time bin corresponding to the onset of the 2nd snippet, where the bin size was chosen to be 30 ms to match the average time constant of the cell membrane [18]. Once the classifier was trained using the output vectors, we shuffled the order of the original input patterns and laid these shuffled patterns over a new background noise. This “test input” was then streamed into the same network for a new set of output vectors, and the accuracy at which the previously trained classifier identified the gap sizes associated with each output vector was used as the quantity to gauge the network’s capacity to encode gaps. To avoid over-fitting, we keep $P \geq 10$ such that many realizations of each gap size are processed. For each parameter set, the experiment was repeated 100 times to gain statistical significance.

**Results**

**Population Coding of Gaps in Gerbil inferior colliculus**

Temporal features of auditory stimuli on the millisecond scale are preserved in the time course of the firing rates of inferior colliculus neurons [15]. To see whether they are represented as population patterns in the inferior colliculus as well, we performed a population rate analysis (see Materials and Methods section on ICA). The underlying data are illustrated in Figures 2A–C, which show two typical neuronal responses to a pulse train with 64 ms gaps. Each neuron was measured during multiple trials of the same stimulus, and the resultant latency-corrected post-gap spike times were binned and averaged to render a post stimulus time histogram (PSTH) representing this neuron’s response to the stimulus, as illustrated at the bottom in Figures 2A–C. Because gap-encoding necessarily occurs after the presentation of the gap, only those spike counts during the 2nd and latter pulses were considered for further analysis. For each cell, the sets of post-gap PSTH were averaged to improve signal-to-noise ratio. This averaging across pulse-responses is justified because we observed no discernable pattern arising as a function of pulse-repetition in our data (Figure 2D and inset). Hence, for each gap size, we obtained a population spike count raster matrix as shown in Figure 2E.

For each gap size in Figure 2E, we obtained the network-averaged spike count and its variance as a function of time (Figure 2F). These results suggest that (1) the network encodes gap size by the neuronal spike rates immediately following the gap, with large gap sizes eliciting high rate responses and vice versa, and (2) gap size is encoded in the first 30 ms after the gap, and beyond this point, the network has reached a steady balance between external stimulation and intrinsic activity. To extract the underlying patterns from the noisy data, we collected the first 70 ms of each spike count raster matrix in Figure 2E and concatenated them for independent component analysis (ICA).

ICA found 3 population patterns (explained variance: 73%) that correspond to well-known inferior colliculus response types: onset, delayed onset, and sustained (Figure 3A). Our ICA procedures (see...
Materials and Methods) indicated the onset response to be the most predominant component, followed by the sustained and the delayed onset component. Beyond $N_{pc} = 3$, no more discriminant patterns were found. While the sustained component yields no discriminability, the onset and the delayed onset components clearly encode gap sizes early on during the post-gap network response with the same rate-encoding mechanism, and the separation is lost during the latter part of the pulse (Figure 3B). These ICA results are consistent with the firing rate responses of Figure 2F. In fact, the onset and the delayed onset components likely originate from the same population dynamics, and their differentiation stems only from binning. In Figure 3C, we applied the same analytical procedures to our data, this time with 5 ms bin size, to reach 4 independent patterns (62% explained variance), 3 of which display gap-discrimination. Comparing the gap-encoding patterns of Figure 3A to their counterparts in Figure 3C, we observe two delayed onset components indicating a continuous temporal code of the gap sizes. One thus may generalize that gap-discrimination in these gerbil inferior colliculus neurons arises from one predominant mechanism: the time course of activity within 30 ms post-gap. Generally, larger gap sizes are encoded by higher network firing rate. Upon closer inspection of Figure 2F, a plausible neurophysiological explanation is that after a longer gap the cells’ excitability has recovered better than after a shorter gap. Along these lines, the fact that these neurons fire briskly after a

Figure 2. Population rate response to gap sizes. (A)–(C) Exemplary gerbil inferior colliculus neurons and their responses to repeated trials of the same stimulus. The stimulus is comprised of three 128 ms broadband pulses that are separated by two 64 ms silent intervals (gaps). The resultant trial-averaged post-stimulus time histograms (PSTHs) are generated with a 10 ms bin size. The first two neurons show fast onset responses, while (C) shows delayed onset behavior. (D) The mean network PSTH during the first (solid line), second (long dashed) and third (point dashed) post-gap pulse of the 2 ms gap stimulus. One sees no clear pattern as a function of pulse-repetition. Inset: the same mean PSTHs for the 32 ms gap stimulus. (E) Grey level plot of cell-wise normalized post-gap PSTHs for all 91 cells and all gap sizes obtained from averaging over all pulses in the train following a gap. The cells are ordered according to their PSTH peaks for the 128 ms gap stimulus. (F) Mean network spike count over the 13 bins for each gap size. Dark to bright means short to long gap sizes. The dashed line is the mean network response during the first pulse, i.e. the control response. Inset: the mean network spike count variance over all gap sizes during the post-gap time series. The dips in the last bin reflect the fact that it only contains 8 ms of stimulation for a 10 ms bin size.

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long gap before dropping to a lower, steady-state rate also points to the possibility of adaptation in the network.

Simulation Paradigm

To gain a mechanistic understanding of how such a population code may be generated, we devised a simple computational network model (see Materials and Methods and Figure 4A), which was inspired by our previous work [20]. The network consists of $N$ integrate-and-fire neurons with simple adaptation behavior. These neurons receive input from $N_{\text{in}}$ input fibers with low connectivity $c_{\text{in}}$. The input spikes are supposed to mimic the activity evoked by the noise pulses. Focusing on high-frequency channels of the auditory pathway (recorded IC neurons had best frequencies above 2 kHz) in which phase-locking is absent, we assume that there is no inherent temporal structure in the input spike trains and model them as Poisson processes. Each input pattern is comprised of a silent interval of a certain length, surrounded by two snippets of such neuronal population spike trains. All snippets are of identical duration (130 ms) and all fibers fire at an identical mean rate (Poisson density) of 10 Hz, unless otherwise stated. In addition, ongoing spontaneous background spikes (noise) are imposed along each nerve fiber according to a second independent Poisson process. For simplicity, patterns are presented with a 900 ms spacing in-between to avoid serial correlations.

In the following, this paradigm will be used to evaluate the influence of cellular and network parameters on discrimination performance.

Single Neuron Gap Discrimination

We began our simulation study with an example that illustrates how adaptation supports gap discrimination tasks at the single neuron level ($N = 1$). We constructed two noise-free stimuli on a single input fibre with one stimulus containing a 64 ms gap while the other contained an 128 ms gap size. This time, for simplicity, the input snippets for both patterns consisted of periodic input spikes of 500 Hz, where the second snippet was limited to only 30 ms in length for illustration (Figure 5). The choice of 500 Hz input rate here reflects the average input spike rate received per neuron in our network study to be presented later, where $N_{\text{inp}} = 1000$, $c_{\text{inp}} = 0.05$ and the spike rate per input fiber is 10 Hz. We first tested the two stimuli separately on a non-adapting neuron and observed its membrane potential over time. While the membrane potential at the onset of the second snippet changed slightly between the two cases, the difference was insignificant such
that the two stimuli elicit identical spike counts during the second
snippets, failing to encode the different gap sizes in terms of the
neuron’s spike count.

Conversely, performing the same test on an adapting neuron
with $t_{adp} \approx 150$ ms resulted in different spike counts between the
two stimuli (Figure 5, bottom). In the 64 ms case, the membrane
was still much depressed upon the presentation of the second
snippet such that only one spike was induced, whereas 128 ms
after the first snippet, the membrane had recovered sufficiently
such that the second snippet produced two spikes. Gap discrim-
ination was hence achieved by distinct recovery from adaptation.

The greater sub-threshold depression from the shorter gap also
means a longer integration time before the neuron reacts with an
action potential. This adaptation-based single-neuron model can
already help explain the network firing rate behavior observed in
Figure 2F. In Figure 2F, the short gaps leave the network
substantially hyperpolarized such that its initial firing rate response
is in fact below the steady state value. On the other hand, the
longer gaps evoke more rapid responses from the cells due to their
further recovery.

To explore the relevant parameter space of the single neuron
example and to quantify how much adaptation aids in gap
discrimination, we next applied our binary classification paradigm
to the single neuron case. We first restricted the input spike trains
to periodic, 500 Hz snippets, and we presented each stimulus 10
times along a single fiber against 5 Hz background noise. The
classification results for three different gap pairs are shown in
Figure 6A as a function of the adaptation time constant $t_{adp}$,
which was used as a free neuronal parameter. Not too surprisingly,
the classification performance strongly depended on the gap sizes
as well as on the adaptation time constant $t_{adp}$. For each gap pair
we observed islands of $t_{adp}$ in which the accuracy was well above
chance. These accuracy peaks represented regions where the
neuron produced different spike counts for the two gap sizes,
whereas in the regions outside these peaks the spike counts were
the same.

One first notes that smaller gap pairs manifested lower and
narrower $t_{adp}$ peaks. Hence the task of correctly classifying the 4–
8 ms gap pair was not only highly selective in $t_{adp}$ values, but the
performance was also very susceptible to noise (Figure 6A). On the
other hand, the accuracy curve for the 64–128 ms gap pair
exhibited robust performance for a wide range of $t_{adp}$ values
(Figure 6A). In fact, the broadest peak existed beyond the 200 ms
scope in Figure 6A, where the neuron fired once to encode 128 ms
gaps and stayed silent for 64 ms gaps.

Furthermore, while the test performance peaks tended to be
situated around the order of the gap sizes involved, their widths

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**Figure 4. Gap discrimination paradigm.** (A) Schematic of the input stream to the network. Sensory-evoked spikes (black ticks) from Poisson
processes (3 shown) and spontaneous background spikes (gray) are fed into a network. Each box marks a 130 ms snippet, and the gap size is defined
as the silent interval (with noise) between the two snippets. Two input patterns, with identical snippets ($P = 1$) and differing only in the gap sizes (gap
A and gap B), are shown in a single input stream, with a 900 ms spacing between them. (B) Schematic of the network’s output is read out at the onset
of the second snippet with a bin size of 30 ms (the first black box, latency-corrected). The output patterns are translated into population vectors of
spike counts and then used to train a linear classifier (filled circle) to distinguish the gap A vectors from the gap B vectors. Later on, when we perform
ICA on simulated networks, the bin size is switched to 10 ms to collect 13 bins from the second snippet.

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**Figure 5. Single neuron gap encoding.** Two different input stimuli
are shown at the top, with the gray pattern delivering a 64 ms gap and
the black pattern delivering a 128 ms gap. The snippets are constructed
using identical, 500 Hz periodic spikes along a single noiseless fiber. The
membrane potential (clipped at $-55$ mV) in response to each stimulus
is displayed in the middle panel, for a non-adapting neuron. The
difference in membrane potential between 64 ms (gray) and 128 ms
(black) after the first snippet is not significant enough to result in
different spike counts during the second snippet. On the other hand,
for an adapting neuron with $t_{adp} = 150$ ms, the hyperpolarization and
recovery result in a large difference in membrane potential at the two
time points such that the neuron produces a different spike count
during the second snippet.

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networks. We constructed the heterogeneous network by random-gaps pairs of 4–8 ms, 6–12 ms and 8–16 ms with non-connected paradigm.

neity and connectivity parameters influence the classification. This spike rate may be increased by multiple factors, such as input generally improves with an increased number of output spikes. spike counts of a single neuron differ for different gap sizes by spike count, the number and size of parameter islands in which range of possible gaps lengths. (2) If gap lengths are to be encoded whose islands of high discrimination accuracy cover the whole network. Thus, in an environment where the afferent fibers carry a poor. The results from Figure 6 therefore suggest that adaptation is a quintessential, and perhaps necessary element in gap discrimination tasks.

Lastly, for comparison, we applied our binary classification paradigm to a non-adapting neuron with variable membrane time constant t_m. Using the same 500 Hz periodic input snippets, Figure 6D shows that, without adaptation, the neuron performs poorly. The results from Figure 6 therefore suggest that adaptation is a quintessential, and perhaps necessary element in gap discrimination tasks.

From these single neuron simulations, we draw two major conclusions: (1) In order to encode arbitrary gap lengths, we require several neurons with different adaptation time constants, whose islands of high discrimination accuracy cover the whole range of possible gaps lengths. (2) If gap lengths are to be encoded by spike count, the number and size of parameter islands in which spike counts of a single neuron differ for different gap sizes generally improves with an increased number of output spikes. This spike rate may be increased by multiple factors, such as input rate, input connectivity, and recurrent connectivity.

Gap Discrimination in a Network

As a next step we studied a network of adapting neurons (see Materials and Methods) and investigated how its t_adp heterogeneity and connectivity parameters influence the classification paradigm.

We first compared heterogeneity to homogeneity in classifying gap pairs of 4–8 ms, 6–12 ms and 8–16 ms with non-connected networks. We constructed the heterogeneous network by random-

and distribution were partly sensitive to the makeup of the input snippets. As a validation, we performed the same experiment, this time using two different instantiations of 500 Hz Poissonian snippets to construct our input patterns (Figures 6B–C). We found that, although the islands of high accuracy were at different values of t_adp, the distribution of these islands were very similar as with periodic input spikes.

Figure 6. Two-gap classification with a single neuron. (A) Binary classification performance of an adapting neuron for varying adaptation time constant and gap pairs of 4–8 ms (solid black), 16–32 ms (solid gray) and 64–128 ms (broken black). The input patterns are made of 130-and-30 ms snippets, as in Figure 3, containing identical 500 Hz periodic signal spikes. Each input pattern is repeated 10 times against 5 Hz background noise along a single input fiber. (B)–(C) The same experiment as in the top panel, this time with a particular instantiation of 500 Hz Poisson spike train for the input snippets, showing how changing spike timing can alter the peaks. (D) Same experiment as in the top panel, this time varying the membrane time constant t_m of a non-adapting neuron, as further evidence of the advantage of adaptation in gap detection tasks.

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ly choosing each neuron’s t_adp value from a uniform distribution between 0 and 20 ms, and we compare this network’s performance to that of a set of homogeneous networks with different constant values of t_adp. The results are shown in Figure 7A. As expected, the optimum value of t_adp for performing classification in a homogeneous network changed as the gap sizes changed. Also, as far as the linear classifier is concerned, the heterogeneous network provided just as much gap encoding as an optimum homogeneous network. That was because the classifier only required a few units out of the entire population to encode the gaps with high fidelity to correctly perform classification, and in the case of N=1000 network neurons, a uniform distribution between 0 and 20 ms already supplied a sufficient number of good neurons to equal the performance of a good homogeneous network. Thus, in an environment where the afferent fibers carry a wide variety of gap sizes and spike statistics, it is a viable strategy to achieve good gap discrimination by providing a wide distribution of adapting neurons, such that gap encoding can always be found somewhere within the population response.

We next looked into the advantage of network recurrence by conducting the same experiment, this time with excitatory network recurrence (ε = 0.05, p = 0.8, W_{exc} = 1 ε_{exc} and W_{inh} = 0 ε_{inh}). The results, in Figure 7B, indicated that excitatory recurrence enhances a network’s ability to create separable patterns to differentiate gaps. One may qualitatively interpret this observation as follows. When input patterns of different gap sizes are presented to a non-connected network, the good neurons will exhibit differential firing while the non-discriminant neurons will produce identical firing counts. Once the neurons are connected, the non-discriminant neurons will receive non-identical numbers of action potentials from the good neurons in response to different gap sizes, creating further separation in the spiking responses of these non-optimum neurons. How a good neuron can proliferate separability...
to a non-discriminant neuron is illustrated in Figure 8. In our network simulation such proliferation of separation may propagate for a short time before gap information is destroyed by later input spikes, noise and intrinsic network activity.

The aforementioned classification enhancement is not limited to purely excitatory recurrence: The same improvement can also be seen in Figure 7C, where mixed (excitatory/inhibitory) networks were used ($\epsilon = 0.05$, $p = 0.8$, $2\sigma_{\text{exc}}$ and $0.5\sigma_{\text{inh}}$). The results from Figures 7B–C hence again suggest that the key parameter governing a population's classification capacity is its firing rate. To prove this, we conducted the same binary classification experiment as above, but this time the input fibers delivered 8–16 ms, 12–24 ms and 16–32 ms gap pairs, while the neurons had a uniform distribution of adaptation time constants $\tau_{\text{adp}}$ from 0 to 120 ms. We then looked at the network's classification performance as a function of its onset (first 30 ms) firing rate (Figure 7D).

Firing rate was changed by either increasing the input rate or recurrent synaptic weights (see caption for details).

The results illustrate that first, network performance scales monotonically with firing rate from the input fibers. This was not surprising, since we expected from the single neuron study (Figure 5) that a higher spike rate along the input fibers triggers higher network spike counts, hence providing more locations along the spike count dimension where separations can be found.

Second, as seen in Figure 7D, the effect of proliferation of separability from a network's recurrence reached a maximum value at roughly the same firing rate for all three gap pairs tested. We interpret this maximum as a point where the strong intrinsic activity starts to generate stereotyped firing patterns that are no longer related to the input features and, as a result, the activity traces induced by the gaps start to become weaker.

The effect of recurrence and the effect of input rate are relatively independent, as is illustrated in Figure 7E, where we raised input rate to the recurrent network in the 8–16 ms task. The incremental effect of increasing input spike rate simply shifts the starting point of the curve to a higher network spike rate and higher performance point, while increasing recurrent weight exhibits the same general behavior, always bringing the performance to a maximum point before deteriorating.

To check how robust our findings were with respect to heterogeneities in the neuron populations we repeated the analysis of Figure 7D for a network with neurons that had capacitance and time constants distributed according to experimental measurements [18] (Figure 7F). Test accuracy shows that such cellular heterogeneity further improves separability of the network patterns for high firing rates, but not for low firing rates.

Simulated Independent Components

From our previous sections we concluded that heterogeneity in adaptation is a key property of a network to encode gaps in population patterns. We therefore set out to see whether the experimental recordings analyzed by ICA (Figure 3A) were consistent with such heterogeneity. To this end, we fed input
patterns of gap sizes 2, 4, 8, 16, 32, 64 and 128 ms to the network, as in the gerbil experiments [15].

We used a network containing a uniform distribution of \( \tau_{adp} \) values from 0 ms to 1000 ms, so as to cover all gap sizes, and the recurrent weights for both networks were tuned such that their average onset firing rates match the average onset firing rate of the 91 gerbil neurons measured (~30 Hz). We then followed the same ICA steps as done for the experimental data by constructing the network’s response during each second snippet (10 ms bins) and looked for the most prominent independent components.

The results for the heterogeneous recurrent network are shown in Figure 9B. For comparison, we performed the same study on a recurrent homogeneous network (Figure 9C), a non-connected heterogeneous network (Figure 9D) and a recurrent non-adapting network (Figure 9E). All networks were tuned to the same firing rate (~30 Hz). We found that the two heterogeneous networks manifested qualitatively the same onset, delayed onset, and sustained components as observed from the gerbil inferior colliculus neurons. Functionally, in this multi-gap classification task, the heterogeneous recurrent network (Figure 9B) performed slightly better than the non-connected heterogeneous network (Figure 9D; 67.4% vs. 64.2% test accuracies), followed by the homogeneous adapting network (Figure 9C; 61.8%). Lastly, the non-adapting network (Figure 9E) displayed distinctly inferior accuracy (38.6%) than its adapting counterparts.

Figure 9D shows that the three dominant ICs can be observed without the effect of intrinsic connectivity. This implies that the onset, delayed onset, and sustained patterns arise from individual neurons. Recalling our single neuron study, we imagine that the various input patterns are processed by all neurons along the \( \tau_{adp} \) axis, eliciting onset response from some, delayed onset response from some others, and sustained responses from yet some other neurons. When one homogenizes the adapting network, the diversity along the \( \tau_{adp} \) axis is lost, and hence so is the variety of response types. This is shown in Figure 9C, where a homogeneous network of \( \tau_{adp} = 50 \) ms only renders delayed onset and sustained patterns. Lastly, the non-adapting network essentially contains only sustained components, which provide scant gap-encoding capacity, as evidenced by its poor classification performance (cf. Figure 9A for \( \tau_{adp} = 0 \)).

In summary, our results thus indicate that (1) gap encoding in the gerbil inferior colliculus is consistent with heterogeneity in adaptation, and that (2) this encoding is best achieved at moderate recurrent drive from the network.

Invariance of the Gap Code

We finally asked, whether the observed population activity patterns not only encode gaps within the tight constraints of our paradigm, but also show some degree of invariance against changes of the parameter regime. First, we analyzed the gerbil data obtained for the same gap sizes but with varying durations of the preceding noise pulses and compared their projections onto the onset and delayed onset ICs (from 128 ms pulses) to projections of the original 128 ms pulses. For short gap sizes (dark dots), the independent components capturing onset and delayed onset responses were relatively invariant with respect to pulse length (Figure 10A). Deviations from invariance occurred for longer gap sizes (brighter dots) and were relatively gradual and systematic such that a downstream station could easily achieve invariant decoding by a linear transformation. This finding was not necessarily unexpected, since gap length discrimination was shown to depend on pulse length in human psychophysics as well [21].

Next, we did the same analysis for our simulated network with heterogeneous adaptation and excitatory and inhibitory recurrent couplings. Also there, onset and delayed onset components showed gradual and systematic deviations (Figure 10B). Particularly the behavior of the delayed onset component (IC2) matches that of the physiological data well. To test invariance from a functional perspective, we then used the linear classifier and trained it with pulse lengths of 32, 64 and 128 ms, before testing it with a whole range of pulse lengths between 16 and 256 ms (Figure 10C). The test accuracy was almost invariant for pulse lengths of 32 ms and larger, verifying that invariance can be functionally extracted from IR patterns, at least for some of the pulse lengths. As a last test we also varied the firing rate by first training the classifier with input rates of 10, 15 and 20 Hz and found that the classifier works well (Figure 10D) in a relatively broad range of input rates (10 to 25 Hz).

From these tests, we conclude that heterogeneous adaptation allows a linear classifier to extract gap durations with some degree of invariance to pulse lengths and background rate and thus likely provides a robust code for gap size that only changes gradually with variations of the stimulus paradigm.
Discussion

We investigated gap encoding in the inferior colliculus, through both analysis of experimental data from gerbils and simulation of neural networks. Our independent component analysis revealed that, when presented with stimuli containing multiple gap sizes, neurons responded with three prominent population patterns: onset, delayed onset, and sustained. Only the onset and delayed onset components showed gap-encoding capacity. In our computational effort to understand gap processing in inferior colliculus, we employed a simple input/network/read-out paradigm that emulated some of the basic features of the auditory midbrain. Then, starting from a single adapting neuron, we showed that experimentally-observed population patterns could arise from heterogeneous adaptation in a network. Moreover, network recurrence could serve to further enhance the network’s ability to provide discriminable population patterns.

Psychophysical experiments in gerbils [22] and rats [23] show gap detection thresholds as short as a few milliseconds. This finding imposes a strong constraint on the shortest adaptation time-scales in the model. Gap discrimination tasks in rodents are rather rare. In [23], it was shown that rats can learn to distinguish a 15 ms from a 60 ms gap, which could be easily explained by the differences in the independent components from our gerbil recordings. In [24] gap discrimination in rats was measured for two reference gap sizes (15 and 40 ms). For both gap sizes the relative gap discrimination error was about 40%. These results are also in rough qualitative agreement with the clearly observable differences in the (gerbil) independent components for gap sizes of 8, 16, 32, and 64 ms (Fig. 1E).

The inferior colliculus is a very heterogeneous brain structure, morphologically and physiologically [25], in terms of its inputs [7], but, most prominently, in terms of its responses. Some neurons’ responses are very specifically related to the ethology of the animal such as breath-selective [26] or wingbeat-specific [27] neurons. Some are more general responses that are simple combinations of elementary receptive fields such as duration tuned neurons [28], target-distance-specific responses in echolocating bats [29], or combinations of temporally segregated frequencies [30,31].

In light of this variety of receptive fields, it may not come as a surprise that there are only few general theories on inferior colliculus function. One of these theories [4], suggests two general types of inferior colliculus responses. One type of receptive fields contains stimuli that are essential for the survival of animals and the outputs are directly conveyed to the motor system (for example neurons that are selective to wing-beat patterns of prey). These receptive fields have to be very specific and detailed. The other type of receptive fields are rather general and unspecific (e.g. combination-specific neurons) and can be seen as multi-purpose primitives that are useful to further cortical processing. For both response types the downstream stations (motor and cortical) operate on a slower time scale than that of the auditory input and...
thus the inferior colliculus has to encode information in rate (or population pattern).

The translation from time to rate can occur by means of adaptation (as in our model) but can also result from intricate combinations of inhibition and excitation via delay lines [32], a degree of freedom we have neglected in this paper. While we have focused most of our attention on the heterogeneity in adaptation time constants, there are several other conceivable mechanisms that would generate an analogous effect. One such mechanism is the initial amplitude of the adapting hyperpolarization, $V_{\text{adp}}$, since, at the single neuron level, the slope of the recovery in membrane potential (Figure 3) linearly scales with $V_{\text{adp}}$. Thus, in principle the heterogeneity in adaptation slopes could also be achieved by a heterogeneity in adaptation strengths $V_{\text{adp}}$. Also different levels of delayed feed-forward inhibition can generate a heterogeneity in re-depolarization time courses, which would have the same effect as the heterogeneity in adaptation time constants. For the present study, we chose to only explore $\tau_{\text{adp}}$ in an effort to coarse-grain our investigation of heterogeneous adaptation. In the bigger picture, we expect each neuron’s membrane behavior to be a function of all neuronal parameters as well as the external inputs: heterogeneity may arise along all pertinent parameter dimensions to optimize the network’s performance. This idea, of course, also pertains to other nuclei that have been suggested to contribute to gap encoding, such as the paratoalvalary nucleus [33], for example, via heterogeneity of its postinhibitory rebound spikes.

Our model can be generalized to also describe population coding of amplitude-modulated (AM) signals. Neurons in the inferior colliculus discharge phase-locked to AM stimuli [34,35]. Intrinsic neuronal properties inducing adaptation effects have been shown to strongly influence single unit phase-locking in a model [36]. Our results predict that, beyond single unit responses, population patterns are also highly informative about AM frequency due to the heterogeneous cellular adaptation time constants.

Adaptation is ubiquitous along sensory pathways [37–41] and there are several specific accounts of its functional role related to the processing of temporal stimulus features [42–44]. Also the benefits of heterogeneity have already been studied [45]. This paper proposes a further mechanism, both at the single neuron level and at the network level, of how adaptation provides improved discriminability of temporal gaps and selective processing of amplitude modulations in an auditory stimulus. Beyond the auditory system, our model can be generalized to other modalities. For example, in the visual domain, spatial motion can be interpreted as the movement of brightness patches, which translates to amplitude modulations of brightness at one retinal location.

Author Contributions
Conceived and designed the experiments: CWY LK BG CL. Performed the experiments: CWY LK. Analyzed the data: CWY LK. Contributed reagents/materials/analysis tools: BG. Wrote the paper: CWY LK CL.

Figure 10. Invariance of the gap code. (A) Projections $p_{z1}$ on the first two independent components of the gerbil recordings (128 ms pulse length): projections of activity from reduced pulse lengths (32 and 64 ms as indicated) vs. original (128 ms pulse length). Dark dots indicate short gap lengths, bright dots indicate long gaps. Dashed lines indicate identity. (B) Same as A for simulations of the network from Figure 9B. (C) Test accuracy of a linear classifier for gap discrimination trained on the simulated network from B for multiple pulse lengths (32, 64, and 128 ms). Gap pairs were 128 ms vs. 64 ms (solid line), 64 ms vs. 32 ms (dashed line), and 8 ms vs. 4 ms (dotted lines). (D) Test accuracy of a linear classifier for gap discrimination trained on the simulated network from B for multiple input rates (10, 15, 20 Hz). Gap pairs as in C.

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