Hidden symmetry of the three-dimensional Einstein–Maxwell equations

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It is shown how to generate three-dimensional Einstein–Maxwell fields from known ones in the presence of a hypersurface-orthogonal non-null Killing vector field. The continuous symmetry group is isomorphic to the Heisenberg group including the Harrison-type transformation. The symmetry of the Einstein–Maxwell–dilaton system is also studied and it is shown that there is the $SL(2,\mathbb{R})$ transformation between the Maxwell and the dilaton fields. This $SL(2,\mathbb{R})$ transformation is identified with the Geroch transformation of the four-dimensional vacuum Einstein equation in terms of the Kaluza–Klein mechanism.

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I. INTRODUCTION

The subject whether Einstein’s field equations have hidden symmetry or not has been studied for a long time (see Ref. [1] for a comprehensive review). As is well known, when the four-dimensional Einstein–Maxwell field admits a non-null Killing vector field, the system may be described in terms of two complex scalar potentials [2]. The equations of motion for their potentials are derived from the non-linear $\sigma$-model action, which is invariant under the $SU(2,1)$ group acting [3]. The invariant transformations of the $\sigma$-model action transform a solution of the Einstein equation into other solutions [4]. These transformations contain three types of transformation: (i) the electromagnetic duality rotation, (ii) the twisting of the Killing vector field, and (iii) the generation of the electromagnetic field. The transformation (i) is just the Fitzgerald transformation in Maxwell theory, which is still valid if coupled with gravity. A discrete version of this was discovered by Bonnor [5]. The transformation (ii) mixes the norm of the Killing vector with the twist potential, and includes the Ehlers transformation [6] which transforms a given static solution into its twisted version. The transformation (iii) is the so-called Harrison transformation [7]. This transforms given vacuum solution into its charged version.

Let us turn to the three-dimensional gravity, then consider whether above three types of transformation do exist or not. The duality between electric and magnetic fields is mathematically based on the Hodge duality, and consequently fails to exist in three dimensions. In the static and rotationally symmetric case, however, a kind of electromagnetic duality is restored [8]. The Ehlers-type transformation appears in rather wide class of solutions. Assuming stationary and rotational symmetry, the Einstein–Maxwell system [9] or the Einstein–Maxwell–dilaton system [10] reduces to a $\sigma$-model action which is invariant under the twisting. This symmetry however locally results in coordinate transformations, so that one might not regard this as a hidden symmetry. The subject considered here is the generation of the electromagnetic field. We show that the Harrison-type transformation exists in the case of the three-dimensional Einstein–Maxwell system admitting a non-null and non-twisting Killing vector field. In this case, a part of the field equations are derived from a $\sigma$-model action which is invariant under some symmetry group, and then the little group which preserves all the field equations is the Heisenberg group. This group includes Harrison-like transformation which generates space-times with the Maxwell field from a locally flat space-time. We also study the symmetry in the three-dimensional Einstein–Maxwell–dilaton system admitting a non-null and non-twisting Killing vector field. We show that the $SL(2,\mathbb{R})$ symmetry similar to the S(uperfield)-duality [11] exists. For the special value of the dilaton coupling constant, this $SL(2,\mathbb{R})$ group transformation may be identified with the Geroch transformation [12] of the four-dimensional stationary vacuum space-time via the Kaluza–Klein method.

This paper is organized as follows. In Sec. II, we analyze the symmetry of the three-dimensional Einstein–Maxwell equations with a non-null and non-twisting Killing vector field, where we show that the symmetry group is the Heisenberg group. In Sec. III, we turn to the Einstein–Maxwell–dilaton equations with a non-null and non-twisting Killing vector field, and show that the $SL(2,\mathbb{R})$ symmetry exists. In Sec. IV, we consider the Kaluza–Klein dimensional reduction of the four-dimensional stationary vacuum space-time, and identify the the $SL(2,\mathbb{R})$ symmetry of reduced system with the Geroch symmetry [13] of the original system. The Section V contains the conclusion and some relevant considerations.

II. SYMMETRY OF THE THREE-DIMENSIONAL EINSTEIN–MAXWELL EQUATIONS

We consider the three-dimensional Einstein–Maxwell theory in the static case. Let $(M^3, g)$ be a three-dimensional static space-time. The metric can be written...
in the form
\[
g = e^{2\Omega(x,y)}[-dt^2 + e^{2\Psi(x,y)}(dx^2 + dy^2)].
\] (1)

The Ricci tensor becomes
\[
\text{Ric} = -e^{-2(\Psi + \Omega)}(\nabla^2 \Omega + \nabla \Omega \cdot \nabla \Omega)g - (\nabla^2 \Psi + \nabla \Psi \cdot \nabla \Omega)\delta
\]
\[
- (\nabla \Omega \cdot \nabla \Omega) + \nabla \Omega \cdot \nabla \Psi + \nabla \Psi \cdot \nabla \Omega,
\] (2)

where \( \delta = dx^2 + dy^2 \) is the standard metric of the two-dimensional Euclidean space \( E^2 \), and the dot and \( \nabla = (\partial_x, \partial_y) \) denote the inner product and the (vector) differential operator naturally defined on \( E^2 \), respectively.

Next, we consider the Maxwell equations. The divergence equation \( d*F = 0 \) implies that there locally exists a dual potential \( Y \) such that
\[
F = *dY,
\] (3)

where \( "*" \) denotes the Hodge operator. As is well known, the source-free Maxwell field is equivalent to the minimally coupled massless scalar field in three dimensions, if the dual potential \( Y \) is identified with the scalar field.

We assume that the dual potential \( Y \) is time-independent: \( \partial_t Y = 0 \). Then, the Bianchi identity for the Maxwell field \( dF = 0 \) becomes an elliptic equation on \( E^2 \)
\[
\nabla^2 Y + \nabla Y \cdot \nabla \Omega = 0.
\] (4)

The Einstein equation \( \text{Ric} = 2dY \otimes dY \) can be written in two-dimensional forms as
\[
\nabla^2 \Omega + \nabla \Omega \cdot \nabla \Omega = 0,
\] (5)

and
\[
(\nabla^2 \Psi + \nabla \Psi \cdot \nabla \Omega)\delta = - (\nabla \Omega \cdot \nabla \Omega) + \nabla \Omega \cdot \nabla \Psi + \nabla \Psi \cdot \nabla \Omega - 2\nabla \Omega \otimes \nabla Y. \]

(6)

The trace part of the tensor equation (3) becomes.
\[
\nabla^2 \Psi = \nabla \Omega \cdot \nabla \Omega - \nabla Y \cdot \nabla Y.
\] (7)

One can easily check that a part of the Einstein–Maxwell equations [Eqs. (4), (5) and (6)] are derived from the variation of the energy integral given by
\[
I = \frac{1}{2} \int dxdy e^{\Omega}[(\nabla \Omega)^2 + \nabla \Omega \cdot \nabla \Psi - (\nabla Y)^2].
\] (8)

This describes a nonlinear \( \sigma \)-model with the base space \( (E^2, \delta) \) and the target space \( (T, G) \), where the target space metric is
\[
G = e^{\Omega}(d\Omega^2 + d\Omega d\Psi - dY^2).
\] (9)

In other words, a solution of the Einstein–Maxwell equations \( \{\Omega, \Psi, Y\} \) must be a harmonic mapping: \( E^2 \rightarrow T \), and the solution space is further constrained by the trace-free part of Eq. (1): \( \nabla Y \cdot \nabla \Omega = 0 \).

On the other hand, a Killing vector \( \xi \) of \( (T, G) \):
\[
L_\xi G = 0 \quad \text{generates a one-parameter group of transformation of the harmonic mapping}, \]

This means that given a solution \( \{\Omega, \Psi, Y\} \) of the Einstein–Maxwell equations, we can obtain another harmonic mapping \( \{\Omega', \Psi', Y'\} \), though the latter should satisfy Eq. (10) to be a solution of the Einstein–Maxwell equations. Let us consider this transformation group that preserves the Einstein–Maxwell equations. It is convenient to introduce variables \( U = e^{\Omega}/2 \) and \( V = \Omega + \Psi \). Then the target space metric is simplified as
\[
G = 2dUdV - 2dYdY. \]

(11)

The Killing vectors are
\[
\xi_1 = U \partial_U - V \partial_V - \frac{1}{2} Y \partial_Y, \quad (12)
\]
\[
\xi_2 = Y \partial_V + \frac{1}{2} \ln(2U) \partial_Y, \quad (13)
\]
\[
\xi_3 = \partial_V, \quad (14)
\]
\[
\xi_4 = \partial_Y. \quad (15)
\]

These give infinitesimal transformations of harmonic mappings. To obtain finite transformations, we exponentiate these infinitesimal generators \( \xi \). Taking into account Eq. (4), we find that the transformation group of the Einstein–Maxwell equations are given by
\[
\{\Omega', \Psi', Y'\} = \{\Omega, \Psi, \epsilon Y\}, \quad (16)
\]
\[
\{\Omega', \Psi', Y'\} = \{\Omega, \Psi + \beta Y + \frac{\beta^2}{4} \Omega, Y + \frac{\beta}{2} \Omega\}, \quad (17)
\]
\[
\{\Omega', \Psi', Y'\} = \{\Omega, \Psi + \gamma, Y + \delta\}, \quad (18)
\]

where \( \epsilon = \pm 1 \), and \( \beta, \gamma \) and \( \delta \) are real numbers. The parameter \( \epsilon \) just exchanges the sign of the Maxwell field. The parameter \( \beta \) gives a non-trivial transformation. In particular, \( \beta \) generates non-vanishing Maxwell field starting with a locally flat space-time. The parameters \( \gamma \) and \( \delta \) result in gauge transformations. The continuous transformations generated by parameters \( \beta, \gamma \) and \( \delta \) form the Heisenberg group (see Appendix A).

The above argument also holds when there is a hypersurface-orthogonal spacelike Killing vector instead of a static Killing vector. Then, the metric can be written as

\[
* \text{More precisely, the transformation generated by a conformal Killing vector (with a constant conformal factor) of } (T, G) \text{ leaves the } \sigma \text{-model action (8) invariant up to a constant factor.}
\]
\[ g = e^{2\Omega(x,r)}[e^{2\Phi(x,r)}(-dt^2 + dr^2) + d\varphi^2], \]

and the transformations (16), (17) and (18) hold without modifications.

As a simple example, we show a transformation of a flat space into Einstein–Maxwell fields. The usual Minkowski metric does not generate a non-trivial solution, however, there is another static form of the flat space-time metric does not generate a non-trivial solution, however, there is another static form of the flat space-time

\[ g = -[\ln(r/r_0)]^2dt^2 + (r_1/r)^2(dr^2 + r^2d\varphi^2), \]

where \( r_0 \) and \( r_1 \) are constants, and the null hypersurface \( \{ r = r_0 \} \) is the Rindler horizon. The equation (17) transforms this metric into

\[ g = -[\ln(r/r_0)]^2dt^2 + (r_1/r)^2[\ln(r/r_0)]^{\beta^2/2}(dr^2 + r^2d\varphi^2), \]

and generates the dual potential

\[ Y = \frac{\beta}{2} \ln \left( \frac{r}{r_0} \right). \]

Then, the Maxwell field becomes

\[ F = -\frac{\beta}{2} dt \wedge d\varphi, \]

which describes the electric field along \( \varphi \)-axis.

III. SYMMETRY OF THE EINSTEIN–MAXWELL–DILATON EQUATIONS

The method given in the previous section can be applied even when the dilaton is included. The action of the Einstein–Maxwell-dilaton system in the Einstein frame is

\[ S = \int \ast [R - 4(\partial \Phi)^2 - e^{-4\alpha \Phi} F^2], \]

where \( \alpha \) is the dilaton coupling constant. From the Maxwell equation \( d \ast e^{-4\alpha \Phi} F = 0 \), there exists a dual potential such that

\[ F = e^{4\alpha \Phi} \ast dY. \]

Then, the remaining field equations are the Bianchi identity for the Maxwell field

\[ * d * dY = 4\alpha g^{-1}(d\Phi, dY), \]

the equation of motion of the dilaton,

\[ * d * d\Phi = -\alpha e^{4\alpha \Phi} g^{-1}(dY, dY), \]

and the Einstein equation

\[ \text{Ric} = 4d\Phi \otimes d\Phi + 2e^{4\alpha \Phi} dY \otimes dY. \]

We again consider the static metric \( \mathbb{1} \), and assume the time-independent field variables: \( \partial t Y = \partial t \Phi = 0 \). Then, the field equations become the scalar equations

\[ \nabla^2 Y + \nabla \Omega \cdot \nabla Y = -4\alpha \nabla \Phi \cdot \nabla Y, \]

\[ \nabla^2 \Phi + \nabla \Omega \cdot \nabla \Phi = \alpha e^{4\alpha \Phi} \nabla Y \cdot \nabla Y, \]

\[ \nabla^2 \Omega + \nabla \Omega \cdot \nabla \Omega = 0, \]

and the tensor equation

\[ (\nabla^2 \Psi + \nabla \Psi \cdot \nabla \Omega) \delta \]

on \( E^2 \). The trace part of the tensor equation (32) is

\[ \nabla^2 \Psi = \nabla \Omega \cdot \nabla \Omega - 2\nabla \Phi \cdot \nabla \Phi - e^{4\alpha \Phi} \nabla Y \cdot \nabla Y. \]

The equations (29), (30), (31) and (33) are derived from the variation of the energy integral

\[ I = \frac{1}{2} \int dxdy \]

\[ \times e^\Omega [(\nabla \Omega)^2 + \nabla \Psi \cdot \nabla \Psi - 2(\nabla \Phi)^2 - e^{4\alpha \Phi}(\nabla Y)^2]. \]

This describes the nonlinear \( \sigma \)-model with the target space metric

\[ G = e^\Omega [d\Omega^2 + d\Omega d\Psi - 2d\Phi^2 - e^{4\alpha \Phi} dY^2]. \]

Introducing new variables

\[ U = e^{\Omega/2}, \quad V = \Omega + \Psi, \quad X = \frac{1}{\sqrt{2\alpha}} e^{-2\alpha \Phi}, \]

the target space metric becomes

\[ G = 2dU dV - \left( \frac{U}{\alpha^2} \right) \frac{dX^2 + dY^2}{X^2}. \]

The Killing vectors are

\[ \xi_1 = 2XY \partial X - (X^2 - Y^2) \partial Y, \]

\[ \xi_2 = X \partial X + Y \partial Y, \]

\[ \xi_3 = \partial \gamma, \]

\[ \xi_4 = \partial \delta, \]

where \( \xi_A \) \((A = 1, 2, 3)\) correspond to the Killing vectors of the Poincaré metric. The finite transformations preserving the trace-free part of Eq. (32) consist of

\[ Y' = \epsilon Y, \quad (\epsilon = \pm 1) \]

\[ \Psi' = \Psi + \gamma, \quad (\gamma \in \mathbb{R}) \]

and the \( SL(2, \mathbb{R}) \) transformation

\[ X' = \frac{aX + ib}{cX + id}, \quad (a, b, c, d \in \mathbb{R}, \quad ad - bc = 1) \]

where \( \lambda = -X + iY \). This \( SL(2, \mathbb{R}) \) transformation resembles the S-duality, and turns out to be the symmetry of the action (24) without the assumption of staticity.
Here we show that the origin of the $SL(2,\mathbb{R})$ invariance of the Einstein–Maxwell–dilaton system can be identified with the Geroch symmetry of the vacuum Einstein equation for the special value of the dilaton coupling constant.

Let $(M^4, g)$ be a four-dimensional Ricci flat space-time admitting a space-like Killing vector $\zeta$. The metric can be decomposed into

$$\hat{g} = e^{2\phi} g + e^{-2\phi} (dz + 2^{1/2} A)^2,$$  \hspace{1cm} (45)

where the Killing vector is $\zeta = \partial_z$, and the metric $g$ and the one-form $A$ are regarded as tensor fields on the three-dimensional manifold $M^3$. The three-dimensional effective theory is described by the action

$$S = \int [R - 2\alpha^2 (\partial \Phi)^2 - e^{-4\phi} F^2],$$  \hspace{1cm} (46)

where $F = dA$. The action coincides with Eq. (24) when $\alpha = 2^{1/2}$.

Let us consider the Einstein equation on $M^4$ for a moment. The basic variables are the amplitude

$$X = \frac{1}{2} \hat{g}(\zeta, \zeta) = \frac{1}{2} e^{-2\phi},$$  \hspace{1cm} (47)

and the twist

$$\omega = * (\zeta \wedge d\zeta) = -2^{1/2} e^{-4\phi} * F,$$  \hspace{1cm} (48)

of the Killing vector, where $*$ denotes the Hodge operator on $M^4$. From the Ricci-flatness of $M^4$, the twist is closed:

$$d\omega = 2 * [\zeta \wedge \hat{\text{Ric}}(\zeta)] = 0,$$  \hspace{1cm} (49)

so that there locally exists a twist potential $Y$:

$$dY = 2^{-1/2} \omega.$$  \hspace{1cm} (50)

The complex potential is defined by

$$\lambda = -X + iY.$$  \hspace{1cm} (51)

In terms of this, the Ricci flat condition of $M^4$ can be written in the three-dimensional form as

$$* d * d\lambda = \frac{2g^{-1} (d\lambda, d\lambda)}{(\lambda + \lambda^*)^2},$$  \hspace{1cm} (52)

and

$$\text{Ric} = \frac{2d\lambda \otimes d\lambda^*}{(\lambda + \lambda^*)^2},$$  \hspace{1cm} (53)

where Ric is the Ricci tensor on $(M^3, g)$.

The Eqs. (52) and (53) are equivalent to Eqs. (28), (27) and (25) when $\alpha = 2^{1/2}$, and these are derived from the variation of the effective action:

$$S = \int [R - 2\alpha^{-1} (d\lambda, d\lambda^*)].$$  \hspace{1cm} (54)

The effective action (54) is invariant under the so-called Geroch transformation

$$\lambda' = \frac{a\lambda + ib}{c\lambda + id}, \hspace{1cm} (a, b, c, d \in \mathbb{R}, \hspace{0.5cm} ad - bc = 1),$$  \hspace{1cm} (55)

which has the same form as Eq. (44). Thus, the $SL(2, \mathbb{R})$ invariance of the Einstein–Maxwell–dilaton system can be identified with the Geroch transformation of the vacuum metric when $\alpha = 2^{1/2}$.

V. CONCLUSION

We have discussed the hidden symmetry possessed by the three-dimensional gravity. It has been shown that the symmetry group of the Einstein–Maxwell equations with a non-null and non-twisting Killing vector field is the Heisenberg group, and this group includes the Harrison-type transformation. In the case of the Einstein–Maxwell–dilaton system admitting a non-null and non-twisting Killing vector field, the symmetry group is $SL(2, \mathbb{R})$. For the special value of the dilaton coupling constant ($\alpha = 2^{1/2}$), this symmetry may be identified with the Geroch symmetry of the four-dimensional vacuum space-time admitting a spacelike Killing vector field via the Kaluza–Klein mechanism.

The resulting transformations require only a single non-twisting Killing vector field. We can therefore apply these transformations to a wide class of the static vacuum solutions without rotational symmetry. For instance, we can obtain non-trivial solutions through the Harrison-type transformation to static multiparticle solutions [3]. Moreover, applying the S-duality-like transformation, we can have a class of static multiparticle solutions with the non-trivial Maxwell and dilaton fields.

Our results rely on the $\sigma$-model structure of the system, however, the non-vanishing cosmological term brakes the $\sigma$-model structure; namely, the method presented here is no longer valid in the presence of the cosmological constant. In particular, the solution generating method could not be applied to three-dimensional black holes, which require the negative cosmological term [4].

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APPENDIX A: GROUP STRUCTURE OF FINITE TRANSFORMATION OF EINSTEIN–MAXWELL EQUATIONS

Let $\Gamma$ be the connected component including the unit element of the symmetry group of Einstein–Maxwell equations. [Namely, $\Gamma$ is the set of finite transformations except the Maxwell field inversion (16).] Each element of $\Gamma$ is uniquely represented as

$$ f_{\beta\delta\gamma} := \exp(\beta \xi_2 + \delta \xi_4 - \gamma \xi_3), \quad \beta, \delta, \gamma \in \mathbb{R}. \quad (A1) $$

Using the Campbell–Hausdorff formula, one can obtain the product formula

$$ f_{\beta\delta\gamma} \circ f_{\beta'\delta'\gamma'} = f_{\beta + \beta', \delta + \delta', \gamma + \gamma' + (\beta\delta' - \beta'\delta)/2}, \quad (A2) $$

and the identity:

$$ f_{\beta\delta\gamma} = e^{-\gamma \xi_3} e^{\delta \xi_4/2} e^{\beta \xi_2} e^{\delta \xi_4/2} = e^{\delta \xi_4/2} e^{\beta \xi_2} e^{\delta \xi_4/2} e^{-\gamma \xi_3}. \quad (A3) $$

Consider a map $\phi : \Gamma \to GL(3, \mathbb{R})$ such that

$$ \phi(f_{\beta\delta\gamma}) = \begin{pmatrix} 1 & \beta & \gamma + \beta \delta/2 \\ 0 & 1 & \delta \\ 0 & 0 & 1 \end{pmatrix}. \quad (A4) $$

From Eq. (A2), it can easily be checked that $\phi$ is one-to-one group homeomorphism. Since the image of $\phi$ is upper triangular matrices whose diagonal elements are unity, $\Gamma$ is the Heisenberg group so called. From the identity (A3) and the transformation laws (17) and (18), one can calculate the group action

$$ f_{\beta\delta\gamma}(\{\Omega, \Psi, Y\}) $$

$$ = \left\{ \Omega, \Psi + \beta Y + \frac{\beta^2}{4} \Omega - \gamma + \frac{\beta \delta}{2} Y + \frac{\beta \delta}{2} \Omega + \delta \right\}. \quad (A5) $$

Using Eq. (A5) again, one obtains

$$ f_{\beta\delta\gamma}(f_{\beta'\delta'\gamma'}(\{\Omega, \Psi, Y\})) $$

$$ = (f_{\beta'\delta'\gamma'} \circ f_{\beta\delta\gamma})(\{\Omega, \Psi, Y\}). \quad (A6) $$

Therefore, $\Gamma$ is the right transformation group on the solution space $\{\Omega, \Psi, Y\}$.

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