TIME-DEPENDENT COROTATION RESONANCE IN BARRED GALAXIES

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Received 2016 July 4; revised 2016 July 29; accepted 2016 August 2; published 2016 October 17

ABSTRACT

The effective potential neighboring the corotation resonance region in barred galaxies is shown to be strongly time-dependent in any rotating frame, due to the competition of nearby perturbations of similar strengths with differing rotation speeds. Contrary to the generally adopted assumption that in the bar rotating frame the corotation region should possess four stationary equilibrium points (Lagrange points), with high quality N-body simulations, we localize the instantaneous equilibrium points (EPs) and find that they circulate or oscillate broadly in azimuth with respect to the pattern speeds of the inner or outer perturbations. This implies that at the particle level the Jacobi integral is not well conserved around the corotation radius. That is, angular momentum exchanges decouple from energy exchanges, enhancing the chaotic diffusion of stars through the corotation region.

Key words: galaxies: kinematics and dynamics – methods: numerical

1. INTRODUCTION

Most spiral galaxies, including the Milky Way, are barred with the interface between the central bar and its surrounding spiral region corresponding to the corotation region, which is a broad circular annulus showing a progressive transition between the bar and the spiral arms. This region marks the transition between two fundamentally different dynamical regimes: in the bar region energy and angular momentum are exchanged at the maximally possible rate given by the bar rotation rate (Pfenniger & Friedli 1991), whereas in the disk region these quantities become progressively better conserved at larger radii. Angular momentum is increasingly better conserved when the potential is closer to rotational symmetry, while energy is increasingly better conserved as the potential becomes time-invariant in an inertial frame.

Since the 1960s, dynamical studies in disk galaxies have been focused on the spiral density wave theory pioneered by Lin & Shu (1964) and Goldreich & Lynden-Bell (1965), where the spirals are considered to be small perturbations of an axisymmetric background potential and are supposed to rotate with a constant pattern speed. In this particular rotating frame, circular orbit resonances exist; the corotation resonance is the most important one because it marks the region of the galaxy where the star orbital period is close to the spiral perturbation period. The corotation resonance is characterized by a number of stationary Lagrange points in the rotating frame that characterize the dynamics around the corotation region. Of these points, the unstable ones generate chaos, which is the ultimate cause of the irreversible behavior linked with resonances.

Starting in the 1970s (de Vaucouleurs & Freeman 1972; Contopoulos 1973), dynamical studies of bars adopted the same conceptual framework as in the spiral density wave theory. Specifically, the bar has been considered to be a perturbation of the background potential with a well defined corotation resonance. This assumption is implicit in most publications on the topic (e.g., Binney & Tremaine 2008, Section 3.3.2), but remained unchecked to date. However, bars are much stronger nonlinear perturbations than spirals, and their dynamical influence ranges well beyond the corotation region, typically inducing spiral arms that rotate at a different, slower pattern speed than the bar itself (Sellwood & Sparke 1988). In this context, it is therefore not obvious that the conceptual framework adopted for a weak spiral perturbation in the linear approximation remains valid because the bar and outer spiral perturbation are both strong and rotate at different frequencies. This paper’s aim is to show that the location of the equilibrium points (EPs) in self-consistent models are essentially time-dependent, and that the commonly assumed dynamics in the corotation region are not well described by a theoretical model based on stationary Lagrange points.

2. MODELS

To examine the dynamics of the corotation region of a barred galaxy, we use three-dimensional (3D) N-body models based on the most accurate method available to set up the initial conditions for equilibrium multi-component galaxy models (GalIC; Yurin & Springel 2014), and perform high quality, momentum conserving pure stellar dynamical model simulations (gyrfalcON; Dehnen 2000). The details are not essential for this discussion, but will be described elsewhere (Y.-T. Wu et al. 2016, in preparation).

The initial galaxy model is constructed using three axisymmetric Miyamoto–Nagai (hereafter MN) components (Miyamoto & Nagai 1975) corresponding to a bulge, a disk, and a halo with a chosen Q-parameter profile. The parameters of these three components are listed in Table 1.

The model develops two long-lived nested bars surrounded by an outer spiral region. The basic rule we have followed for producing long-lived double bar systems is to start the simulations with initial equilibrium axisymmetric models having a double-peaked rotation curve with equal maxima using two of the three MN components, and fixing the respective bar sizes, with the smaller component having a colder kinematics (Q ~ 1) than the medium component (Q ~ 1.5), as in Du et al. (2015). The bulk of each bar shows a well defined pattern speed, while the spiral region is described by a distinct non-uniform pattern speed that decreases with increasing radius. The third MN component is
spherical (i.e., a Plummer model) with a large core, and is used mainly to keep the rotation curve high in the outer spiral region. With \( N = 2 \times 10^7 \), the particle noise is sufficiently low to unambiguously find the instantaneous rotation speed of each bar and the instantaneous locations of the EPs, which are defined by the locations where the acceleration vanishes in the respective rotating frames. Each of these patterns interact with the other adjacent patterns through gravitational torques, and the regions where these torques compete most effectively are the respective corotation rings of the inner and the outer bars.

3. COROTATION DYNAMICS

3.1. Evolution of Two Bar Models

Several figures encompassing several bar–spiral relative phases of a rotating double-barred system allow us to illustrate simultaneously the inner small and outer large bar corotation evolutions. The motivation for choosing a double-barred system was to check whether the findings of this paper are different at the interface between the two nested bars or at the interface between the outer bar and its surrounding spiral arms.

In selected snapshots, Figure 1 shows the projected density of the rotating double-barred system, including about 0.3 Gyr from the whole 8 Gyr simulation, of the inner and outer bars. The color map indicates the projected surface density in log-scale. As can be seen from the left panels, where the bars are displayed at 4 kpc radius scale, the outer and inner bars are aligned at \( t = 3.107 \) Gyr and rotate counter-clockwise. Because the inner bar rotates faster than the outer bar, the angle between them changes with time. At \( t = 3.116 \) Gyr the angle is about 45\(^\circ\), and at \( t = 3.126 \) Gyr the angle is 90\(^\circ\). Alignment occurs again at \( t = 3.146 \) Gyr.

The structure revealed in the right panels at the 20 kpc radius scale clearly shows the outer bar and its outer spiral arm pattern (mainly shown in yellow and red); they are aligned at \( t = 2.975 \) Gyr. Due to their different rotation speeds they become perpendicular to each other at \( t = 3.179 \) Gyr and are again aligned at \( t = 3.295 \) Gyr.

3.2. Pattern Speeds

To investigate quantitatively the dynamics in the vicinity of the corotation region of a given bar, we need the bar pattern rotation frequency \( \Omega_b \) around the rotation axis \( z \). We expect that each bar and spiral may be mutually perturbed, so the pattern speed of each structure may oscillate in time.

There are several methods to determine a pattern speed from a set of particles of mass \( m_i \) and Cartesian coordinates \( x_i, y_i \), whose center of mass is at the origin, the polar moment of inertia tensor in the \((x-y)\)-plane reads

\[
I = \begin{pmatrix} I_{xx} & I_{xy} \\ I_{xy} & I_{yy} \end{pmatrix} = \begin{pmatrix} \sum_i m_i x_i^2 & \sum_i m_i x_i y_i \\ \sum_i m_i x_i y_i & \sum_i m_i y_i^2 \end{pmatrix}.
\]

The selected particles of a given bar belong to a ring included in the bulk of the bar region. The precise size of the ring is not important as long as it includes the bulk of the measured bar. Here, the inner bar ring is taken between 0.1 and 0.4 kpc in radius, and the outer bar ring is between 2.5 and 4.5 kpc. This allows one to calculate the azimuthal angle \( \phi_b \) of the bar major axis from the eigenvectors direction of the tensor \( I \), yielding, after some algebra,

\[
\phi_b(t_k) = \frac{1}{2} \arctan (2I_{xy}, I_{xx} - I_{yy}).
\]

The pattern speed of the bar can be measured by estimating the time-derivative of this angle, which is determined by an average centered finite difference over two time-intervals of \( \pm 2 \) Myr before and after the evaluated time to filter out the highest frequencies.

3.3. Instantaneous EPs

Given the structures associated with the inner bar, outer bar, and outer spiral, we now focus on the properties of the instantaneous EPs. The EPs in the frame rotating at the known frequency \( \Omega_b \) are found by finding the extrema of the effective potential

\[
\Phi_{\text{eff}} = \Phi - \frac{1}{2} \Omega_b^2 R^2,
\]

where \( R^2 = x^2 + y^2 \) and \( \Phi \) is the gravitational potential. This can be achieved by finding the zero acceleration points including the centrifugal force component,

\[
0 = a_R + \Omega_b^2 R = \frac{a_xx + a_yy}{R} + \Omega_b^2 R,
\]

\[
0 = a_\phi = \frac{a_yx - a_xx}{R},
\]

\[
0 = a_z,
\]

where \( a = -\nabla \Phi \) and \( a_\phi \) are the respective gravitational acceleration components in Cartesian or polar coordinates. To find the respective EPs in the inner bar and the outer bar rotating frame, the pattern speed of each bar is used for \( \Omega_b \).

The EPs can be visually inspected by the intersections of the black curves and the white curves in Figure 1. These curves show the locations satisfying the zero acceleration conditions: Equations (4) and (5), respectively. Specifically, the black curves in Figure 1 represent the corotation ovals where the radial acceleration vanishes, and the white curves show the zero-torque locations.

To determine the EPs, we adopt the following procedure. For each bar the particles located within the \( |z| < \frac{1}{2} \) half of the disk scale height are binned in a \( x-y \) grid (pixel size of \( \Delta x = 0.03 \) and 0.09 kpc for the inner and outer bar grids), and the summed

\footnote{The single argument arctan formula given by Binney & Merrifield (1998, Section 10.3.2) in the mathematically similar context of the vertex deviation delivers angles over only a quadrant due to the factor 1/2, preventing it from tracking continuously on the same principal axis.}
Figure 1. Evolution of the inner bar (left panel (a)–(e)) and the outer bar projected density (right panel (f)–(j)) at selected times. The black and white curves show the zero radial and tangential accelerations, respectively (satisfying Equations (4) and (5)). The green points show the equilibrium point locations. The black square and black triangle show the location of the equilibrium points with the smallest and the largest radius, respectively. The + and − indicate the torque sign.
squares of the right-hand sides of Equations (4) and (5) multiplied by $R$.\(^5\)

$$W = (a_x x + a_y y + \Omega_0^2 R^2)^2 + (a_x y - a_y x)^2$$

are averaged in the grid cells. The disk scale height is 0.45 kpc here, as listed in Table 1. For each snapshot, the 36 gridded pixels that are not close to the origin and contain the smallest values of $W$ are selected as a sample of points that are spatially close to the true EPs. These pixels are represented by the green points in Figure 1. At any given time, a different number of pixels may be found near any EPs, but over time the evolution of the cloud of points provides an approximate estimate of the EP positions. The number 36 is retained based on the fact that in average 9 points for 4 EPs sample well the nearest pixels of the sought points.

From the left panels of Figure 1, it is evident that the EPs near the inner bar are mainly affected by the outer bar and lie close to the semimajor and semiminor axis of the outer bar. However, because the outer bar rotates with respect to the inner bar, the EPs are not stationary in the inner bar rotating frame.

On a larger spatial scale, corresponding to the right panels of Figure 1, the EPs between the outer bar and the spiral arms are shown. It is apparent that the spiral structure causes a torque that competes with the bar torque, resulting in the bending of the white lines, especially just outside the corotation region represented by the black curves. When the outer bar and its outer spiral structure are in phase, as shown in panel (f), the white curves are bent beyond $R > 10$ kpc, where the torque is dominated by the outer spiral structure. Here, the EPs are located along the semimajor and semiminor axis of the outer bar. Subsequently, since the rotation frequencies of the outer bar and its surrounding spiral arms differ, the two structures become out of phase, as shown in panel (g). During this stage, the white curves are bent near the corotation region and the EPs, as indicated by the green points, are no longer near the semimajor or semiminor axis of the outer bar. When the two structures are out of phase by about 90°, as shown in panel (h), the white curves are bent and overlay the corotation region. Therefore, the EPs are located at arbitrary angles near the corotation region. We note that at this stage, the direction of the torque, as indicated by the + and − signs, differs between the inside and outside the corotation region. For example, along the $y = 0$ axis, the torque is negative inside the corotation region, but positive outside the corotation region. Later, the two structures are in phase again, as shown in panel (j), and the EPs are located near the semimajor and semiminor axis of the outer bar, which is similar in appearance to panel (f), with the directions of the torque unchanged inside and outside the corotation region.

In summary, given that the contributions to the torque around corotation from the inner and outer non-axisymmetric structures are similar, the instantaneous EPs move in any rotating frame. Thus, except for the potential minimum at the origin, there are no stationary points in any rotating frame. In other words, no true stationary Lagrange points exist.

\(^5\) The $a_z = 0$ condition holds anyway within $|z| < \Delta z$, where $\Delta z$ is about half the disk scale height, because the disks are never significantly warped. The multiplication by $R$ of the horizontal acceleration is used to avoid numerical overflow near the origin.

### 3.4. Time Evolution of EPs

In this subsection, we describe quantitatively the temporal variation of the EP parameters. For the corotation region of the inner and outer bar, their radii as well as their azimuths oscillate substantially. Specifically, Figures 2 and 3 show the radius and the reduced azimuthal angle (described in Section 3.4.2) of the EPs as functions of time. In both figures, the dashed and dotted vertical lines mark the times when two bars are aligned and perpendicular to each other, respectively.

#### 3.4.1. EP Radii

From Figure 2, it is clear that the radii of the EPs of the inner corotation region (hereafter OCR) and the outer corotation region (hereafter OCR) oscillate substantially (∼±5 − 10%) according to the azimuth difference between the inner and outer bar. Most of time, the EPs can be classified into two groups according to their radii. Namely, for the EPs of the OCR, the group with a larger radius is located near the bar major axis, whereas the group characterized by a smaller radius is located near the bar minor axis. In Figures 1(f)–(j), the black square and black triangle mark the location of the EPs with the smallest and the largest radius, respectively. However, for the EPs of the ICR, the group with larger radius is located along the semiminor axis of the outer bar, and the group with smaller radius is located along the semimajor axis of the outer bar. Again, the black square and black triangle in Figures 1(a)–(e) show the location of the EPs with the smallest and the largest radius, respectively.

The maximum and the minimum radii of the EPs of the ICR are in phase, with the relative angle of the two bars indicated by the dotted and dashed lines in Figure 2, while the maximum and the minimum radii of the EPs of the OCR are sometimes shifted by more than 30°. This is due to the interaction of the spiral structure external to the outer bar.

At different times, the EPs of the OCR no longer exhibit a bimodal distribution in the radial range, such as at $t = 2.80$ Gyr. This corresponds to events involving the phase difference between the outer bar and spiral structure, and will be described in more detail below.

#### 3.4.2. EP Azimuths

To facilitate the presentation of the time evolution of the EPs azimuths $\phi$, which are monotonously growing functions of time, in Figure 3 we plot the reduced azimuth $\phi_{\text{re}}$,

$$\phi_{\text{re}} = \phi - \Omega(t - t_0),$$

where $\Omega = 25$ km s\(^{-1}\) kpc\(^{-1}\) is a constant frequency that is similar to the outer bar frequency over the analyzed time interval, and $t_0$ is the time of the starting point. The reduced azimuth plot allows one to perceive more easily the relative changes of angular velocity. When the EPs rotate faster/slower, the curve slope increases/decreases. For example, the EPs of the ICR (red dots) rotate faster than $\Omega$ at $t = 2.05$ Gyr and rotate slower at $t = 2.07$ Gyr.

The EP's azimuths of the ICR (red points) are split into four distinct groups, for example $\phi_{\text{re}} = 10^\circ, 100^\circ, 190^\circ, 280^\circ$ at $t = 1.90$ Gyr, which is similar to Lagrange points, except that they oscillate. Their regular periodic oscillation is in phase with the relative angle of the two bars: they rotate faster/slower when the bars are aligned/ perpendicular. The typical oscillation
Figure 2. Time evolution of the equilibrium point radii over 3 Gyr after the formation of the double-barred system. At any time, the positions of the true equilibrium points are sampled by 36 dots with the lowest $W$ values (Equation (7)). The red and black dots are for the inner and outer corotation region, respectively. The dashed and dotted lines mark the times when two bars are aligned and perpendicular to each other, respectively.
Figure 3. Time evolution of the equilibrium point azimuths. The dots and lines have the same meaning as in Figure 2. The dots more than 360° are repeated dots between 0° and 360°.
Figure 4. Time evolution of the effective potential $\Phi_{\text{eff}}$ at the equilibrium points. The dots and lines have the same meaning as in Figure 2.
amplitude amounts to ±10° within a period equal to π/(Ω0 − Ω0), where Ωi and Ωo are the inner and outer bar pattern speeds, respectively. Departures from such a description are seen in the last frame (f), during short episodes where two of these groups sharply merge, showing that further complications can occur.

The EP azimuths of the OCR (black points) are also split into four distinct groups with oscillation amplitudes of ∼ ±10° within a period π/(Ωi − Ωo). However, about every 0.3–0.4 Gyr, they are distributed over all angles (∼ ±90°) due to ∼90° phase difference between the outer bar and the spiral structure, such as at t = 2.83, 3.18 Gyr. Figure 1(h) shows a typical snapshot of this behavior. In addition, when the bars are aligned or perpendicular to each other, the EPs of the OCR rotate at an approximately constant speed because the slope of \( \phi_{re} \) is almost constant.

Overall, the average slope of the EPs of the ICR is slightly larger than the EPs of the OCR. Thus, the EPs of the ICR rotate with the speed of the outer bar, as well as the EPs of the OCR, except that occasionally the EPs of the OCR sharply decrease their speed during the episodes when they are distributed over all angles, as described in the previous paragraph. During these episodes, the corotation resonance loses its strength as discussed in the next subsection.

### 3.4.3. The Effective Potential

As a consequence of the temporal radial and azimuthal variations described above, there is a corresponding time-dependence of the effective potential \( \Phi_{eff} = \Phi - \frac{1}{2} \Omega^2 R^2 \) at the EPs. Specifically, Figure 4 shows the time-dependence of the effective potential at the EPs. As in Figure 3, the dashed and dotted lines represent the times when the bars are aligned and perpendicular to each other, respectively. The red dots denote the EPs of the OCR, while the black dots denote the EPs of the ICR. For both kinds of dots, the lower values correspond to the local \( \Phi_{eff} \) saddle points, and the higher values correspond to the local \( \Phi_{eff} \) maxima.

For the EPs of the ICR and OCR, the amplitude of the oscillations amounts to \( \sim 0.5\% \) over almost the whole shown time interval, with a period \( \pi/(\Omega_i - \Omega_o) \) as defined in Section 3.4.2. The \( \Phi_{eff} \) of the EPs of ICR are in phase with the relative phase of two bars, while over time the \( \Phi_{eff} \) phase of the EPs of the OCR may lag by up to 40°, which results from the bar–spiral interactions.

For the EPs of the OCR, the variations between the saddle points and the maxima of \( \Phi_{eff} \) at any time \( t \) (i.e., \( \Delta \Phi_{eff}(t) = \Phi_{max}(t) - \Phi_{saddle}(t) \)), oscillate between 0 and \( \sim 2\% \). At some times, \( \Delta \Phi_{eff} \) becomes very small, such as at \( t = 2.83 \) or 3.18 Gyr. Over timescale of order \( \sim 100 \) Myr, the OCR becomes less effective. This feature repeats with a period of 300–400 Myr. Such variations modulate the strength of the corotation resonance, and its influence on the outer disk dynamics.

Comparing the \( \Delta \Phi_{eff}(t) \) at any given time (0 to \( \sim 2\% \)) and the amplitude variation over a period \( \pi/(\Omega_i - \Omega_o) \) (\( \sim 5\% \)), the time variations of \( \Phi_{eff} \) over a period that is comparable with the bar rotation times, are more important than \( \Delta \Phi_{eff}(t) \) over the corotation region at any specific time. This demonstrates that, unlike true Lagrange points, these EPs are essentially time-dependent.

What is not shown in Figures 2–4 is that for the EPs of the ICR, the saddle points of \( \Phi_{eff} \) are located at slightly smaller radii than the maxima of \( \Phi_{eff} \) (by about 0.1 kpc). This is contrary to the EPs’ radii of the OCR (or the classical Lagrange points in bars), where the saddle points are located at larger radii than the maxima of \( \Phi_{eff} \) (by about 0.6 kpc).

### 4. CONCLUSIONS

The results of this paper are a logical corollary of the Sellwood & Sparke (1988) work. In their work the pattern speeds of the bar and spiral arms were studied and found to differ, which implies that the respective patterns torque each other and cannot be strictly rigid. Thus, around the corotation regions, time-independence is impossible in any rotating frame.

We have analyzed the dynamical consequences of both the bar–bar and bar–spiral pattern interactions quantitatively in N-body simulations of a typical galaxy disk model, including two nested bars and spiral arms. We found that the common assumptions that a rigid bar and the existence of stationary EPs in a particular rotating frame are invalidated by the high degree of time-dependence in these systems.

The dynamics in the two corotation regions are shown to be essentially time-dependent because the instantaneous EPs oscillate with a period comparable to the orbital period over distances (1–2 kpc) larger than the width of the corotation regions. Further, over similar periods, the effective potential values at these EPs are modulated by a larger amount than the differences between their maxima and minima at any given time. This demonstrates the strong time-dependence of the potential and the non-existence of true Lagrange points.

In usual bar models, where the bar is supposed to be rigid and rotating with a constant speed \( \Omega_b \), the Hamiltonian \( H = \mathcal{E} - \Omega_b L_C \) is time-independent (\( \mathcal{E} = v^2/2 + \Phi \) is the particle energy and \( L_C \) is the particle angular momentum), so \( H \) is an integral of motion, the so-called Jacobi integral. In our simulation, \( \Phi \) is time-dependent in any rotating frame, so \( H \) is time-dependent. While \( E \) and \( L_C \) still vary, they are no longer constrained to conserve \( H \). Therefore, chaotic motion must be much more widespread than in the time-independent case, and the effect of such a kind of corotation resonance is much more diffusive than estimated in analytic theories that assume time-independent dynamics. This provides a dynamical understanding of the results in Brunetti et al. (2011), where in a barred galaxy model the radial migration of stars measured by a radial diffusion rate was found to be the largest around the bar corotation radius, and not in the spiral region. We conclude that the Sellwood & Binney (2002) migration scenario attributed to transient spirals must be supplemented by an eventually larger contribution to stellar migration when a bar is present, because the bar–spiral corotation region is strongly time-dependent.

We have seen that the EPs oscillate in azimuth back and forth up to 40°, which means that the tips of the bars are twisted to similar extent (see Figure 1(g)). In other words, bars are actually rather flexible structures, especially near their ends. Near their ends, the assumptions of rigidity and constant pattern speed may be improper. At any particular time, a bar may present a differently twisted pattern, and therefore we expect that estimations of the Milky Way bar pattern speed made with star samples located near its corotation radius (at 4–6 kpc from the Galactic Center) might give a different pattern speed than estimations derived from star samples that
are located well within the bulk of the bar. In the future, to assure the Milky Way basic parameters, such as the bar pattern speed or the bar orientation, we will need to take into account the particular twisting stage of the Milky Way bar.

The authors are grateful to W. Dehnen for the gyfalcON code and D. Yurin & V. Springel for the GaLiC code. The authors are also thankful for the support of the Theoretical Institute for Advanced Research in Astrophysics (TIARA) based in Academia Sinica Institute of Astronomy and Astrophysics (ASIAA) and Sam Tseng for assistance on the TIARA computational facilities and resources. The authors would like to acknowledge the support of the Geneva Observatory and its computational facilities, as well as Yves Revaz for his assistance.

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