Determination of the laminate strains using discrete damage mechanics

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Abstract. In this paper discrete damage mechanics (DDM) is used to predict inter-laminar transverse and shear damage initiation and evolution in terms of the fracture toughness of the laminate. The finite element method (FEM) is one of the most widely and most popular numerical methods for analyzing composite structures, therefore ANSYS commercial software is used for analysis of layered plate composite structure reinforced with long unidirectional fibers with Carbon/Epoxy material. Because ANSYS does not have a built-in capability for calculating crack density, we have to use plugin. A methodology for determination of the fracture toughness is based on fitting DDM model and these data are obtained from literature. Also, prediction of modulus vs. applied strain is contrasted with ply discount results and the effect of in situ correction of strength is highlighted. Evaluation of matrix cracking detected in lamina has been solved using return mapping algorithm.

1 Introduction

The term damage is commonly used in different ways in the field of composites to describe lack of adhesion, debonding of the fiber from its matrix, delamination, or breakage of the fiber, etc. Fracture and failure are one of the challenging issues in solid mechanics. Under high levels of mechanical loads, fracture can occur in different materials ranging from metals, ceramics to polymers and composites. Depending on the microstructure of the materials, fracture can originate from voids, microcracks, movement of dislocations, de-bonding and even structural effects such as buckling. The problem becomes more complex in the case of composite materials [1,2]. In general, composite materials are composed by stacking different layers of materials. Each layer consists of two different constituents.

There are several methodologies to model the failure of composite materials which have been used in the scientific literature, as failure criteria (usually stress based) or continuum damage mechanics (CDM) models [3].

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Alternatives to CDM include: micromechanics of damage, crack opening displacement methods, computational micromechanics, and synergistic methods. While CDM homogenizes the damage and treats it phenomenologically, the alternative methods attempt to represent the actual geometry and characteristics of damage. Accurate physical representation of the fracture phenomena is the most salient feature of alternative models.

In laminated composites, matrix cracks grow parallel to the fiber orientation due to the inability of the crack front to break the fibers [4]. These cracks reduce the stiffness of the cracked lamina, which then sheds its share of the load onto the remaining laminas [5]. Since the actual geometry of the cracks is modelled, the formulation is called discrete damage mechanics (DDM). These models are able to predict accurately the strain at which the first crack appears, how crack density evolves as a function of applied strain, and how stress are redistributed in the laminate due to degradation of the mechanical properties of a cracked lamina.

2 Theory background

Models for flexural stiffness reduction due to transverse matrix cracks confront more difficulties than the models for in-plane stiffness reduction. Also, as unsymmetrical laminates present extension-bending coupling, modelling such laminates demands specific formulations. Therefore, just a limited number of works can be found on flexure deformations compared with those on in-plane deformations.

Most practical laminates are symmetric and the most efficient use of them is by designing the structure to be loaded predominantly with membrane loads. Therefore, the solution presented here is for a symmetric laminate under membrane loads. In this case,

\[ \frac{\partial w^{(i)}}{\partial x_1} = \frac{\partial w^{(i)}}{\partial x_2} = 0, \quad \sigma_z^i = 0 \]

where: \( u(x,y,z) \), \( v(x,y,z) \), \( w(x,y,z) \) are displacements of a point in lamina \( i \) as a function of the coordinates \( x_1, x_2 \). The basic steps of the DDM model for transverse tension and in-plane shear damage are listed below.

2.1 Discrete damage model

To study damage localization, the DDM is selected. DDM model is a semi-analytical linear-elastic fracture mechanics (LEFM) model [6]. The model is able to predict the crack density \( \lambda = 1/2l \) where \( 2l \) is the distance between each pair of cracks (Fig.1). The crack density is only state variable needed to represent the state of damage in the cracked lamina.

2.2 Solution algorithm

The solution algorithm is based on three main steps: 1) strain steps, 2) laminate-iterations, and 3) lamina-iterations. The state variables for the laminate are stored in the array of crack densities for all laminas \( i \) and the membrane strain \( \varepsilon \). At each strain load step, the strain on the laminate is increased and the laminas are checked for damage. The basic methodology of the DDM modelling for transverse tension and in-plane shear damage is:
- In each lamina \( i \), the state variable is the crack density \( \lambda_i \). The set of crack densities for the laminate is denoted by \( \lambda = \lambda_i, i = 1, ..., N \), where \( N \) is the number of laminas in the laminate.
- The independent variable is the midsurface strain \( \varepsilon = \{ \varepsilon_1, \varepsilon_2, \gamma_{12} \}^T \).
- The damage activation function is
\[ g = (1 - r) \sqrt{\frac{G_{Ic}(\lambda_1 \varepsilon)}{G_{Ic}}} + r \frac{G_{IIc}(\lambda_1 \varepsilon)}{G_{IIc}} + 1 \leq 0, \quad r = \frac{G_{IIc}}{G_{Ic}}, \]  \hspace{1cm} (2)

where \( g \leq 0 \) represents the undamaging domain.

- The return–mapping algorithm (RMA) [7] calculates the increment (decrement) of crack density \( \lambda \) as

\[ \Delta \lambda_k = -g_k \frac{\partial g_k}{\partial \lambda} \]  \hspace{1cm} (3)

Fig. 1. Representative volume element used by DDM [7].

A RMA achieves this by integrating until \( g = 0 \) and updating the crack density with iterative increments calculated as \( \Delta \lambda = -g \frac{\partial g}{\partial \lambda} \).

- The damage threshold is represented by the energy release rate (ERR) \( G_{Ic}, G_{IIc} \). For a given value of strain, the calculated values of ERR are monotonically decreasing functions \( \lambda \).

- Crack density grows until saturation, defined as \( \lambda_{lim} = 1/t_k \), where \( t_k \) is the thickness of lamina \( k \).

3 Problem description

Consider a [0/90/0/90/0] laminate made of IM7/8552 Unidirectional Graphite/Epoxy Prepreg with properties given in Table 1 subjected to a membrane strain \( \varepsilon_x \neq 0, \varepsilon_y = \gamma_{xy} = 0 \). The dimensions of the model are \( a \) and \( b \) along the \( x \) and \( y \) directions, respectively. We have calculate and visualize the crack density in lamina \( k = 2 \) for an uniform applied strain \( \varepsilon_x = 0.48 \% \). Then it is necessary calculate the average laminate stress \( \sigma_x = N_x/h \), where \( N_x \) and \( h \) are the stress resultant and the total laminate thickness, respectively.
3.1 The DMM plugin

First, since ANSYS does not have a built-in capability for calculating crack density, we have to use a plugin. In this case, it necessary to implement material subroutine for a state of plane stress for DDM. The DDM plugin is available in [1, USERMATLib.DLL].

| Elastic and strength properties | Symbol | Value |
|---------------------------------|--------|-------|
| Longitudinal modulus           | $E_1$  | 161   |
| Transverse modulus             | $E_2$  | 14.39 |
| In-plane shear modulus         | $G_{12}$ | 5.2   |
| In-plane Poisson’s ratio       | $\nu_{12}$ | 0.467 |
| Intralaminar Poisson’s ratio   | $G_{23}$ | 0.41  |
| Lamina thickness               | $t_k$ [mm] | 0.15  |
| Critical value of ERR in mode I| $G_{Ic}$ [kJ/m²] | 0.17  |
| Critical value of ERR in mode II| $G_{IIc}$ [kJ/m²] | 0.23  |
| Longitudinal coefficient of thermal expansion | $CTE_1$ [1E − 6/°C] | 0.9   |
| Transverse coefficient of thermal expansion | $CTE_2$ [1E − 6/°C] | 28.8  |
| Change in temperature from the temperature at which $G_{Ic}, G_{IIc}$, were measured to the operating temperature | $\Delta T$ [°C] | 0     |
| Lamina orientation with respect to the laminate c.s. | $\theta_k$ | 0     |

We note that the plugin requires an input of 3+9N material properties $G_{Ic}$, $G_{IIc}$, $\Delta T$, $E_1$, $E_2$, $G_{12}$, $\gamma_{12}$, $\gamma_{23}$, $\alpha_1$, $\alpha_2$, $\theta_k$, $t_k$, where $N$ is the number of laminas in the symmetric part of the laminate, i.e., in one half of the LSS. The properties are ordered as follows, starting with the first lamina, $k = 1$ (bottom surface), and continuing until the lamina $N$ (middle surface).

In this study we use ANSYS 14.0, Microsoft Visual studio 2008 and Fortran Intel 11.1 operating under a Windows system.

Next, the plugin calculates 3N state variables, starting with the first lamina, $k = 1$ (bottom surface), and continuing until the lamina $N$ (middle surface):
- $\lambda_k$ – Crack density in lamina $k$,
- $D_2$ – Transverse damage, lamina $k$,
- $D_6$ – Shear damage, lamina $k$.

3.2 Parametric modelling in APDL

Second, the model is set parametrically, as follows. The input parameters are:
- the applied strain at the end of the time step,
- the initial crack density,
- the shell dimensions,
- the ply thickness,
- the number of laminas,
- the number of properties, which for DDM is calculated in terms of the number of laminas.

Next, APDL commands are used to specify the element type, the laminate stacking sequence (LSS) [0/90\%/0/90\%/0], the elastic properties with MP command and the material strengths with TB command (Table 1).

The APDL code to set up the model parametrically is shown next.

! NEXT VALUES GO IN TBDATA
GIC = .170
GIIc = 0.23
deltaT = 0.0
E1 = 161e+03
E2 = 14.39e+03
G12= 5.2 e+03
nu12 =0.467
nu23 =0.410
CTE1= 0.9
CTE2 =28.8

! Angle, with TBDATA for each layer
! Thickness, with TBDATA for each layer

! USERMAT DECLARATION SECTION
TB,USER,1,1,Nprops,     ! DECLARES USAGE OF USERMAT 1, MAT 1,
TBTEMP,0                ! ref
TB,USER,1,1,Nprops,     ! DECLARES USAGE OF USERMAT 1, MAT 1,
TBTEMP,0                ! reference temperature
TBDATA,,GIC,GIIc,deltaT,E1,E2,G12    ! 6 values per TBDATA line
TBDATA,,nu12,nu23,CTE1,CTE2,0,tk
TBDATA,,E1,E2,G12,nu12,nu23,CTE1
TBDATA,,CTE2,90,8*tk,E1,E2,G12
TBDATA,,nu12,nu23,CTE1,CTE2,0,tk/2
TB,STAT,1,,3*NL ! NUMBER OF STATE VARIABLES

Since the strain field inside the shell is uniform in both direction (x, y), therefore we use only PLANE182 element to model a unit domain with dimensions $a = 100 \times b = 100$ mm.

! MESH
ET,1,182,,,3           ! PLANE182, plane elements with plane stress
R,1,2*NL*tk           ! Real const. #1, thickness of whole laminate
N,1                   ! Define node 1, coordinates=0,0,0
N,2,ShellDimensionX,0 ! Define node 2,
N,3,ShellDimensionX,ShellDimensionY
N,4,0,ShellDimensionY
Then, set up a uniform deformation $\varepsilon_x$ using displacement boundary conditions.

! Define one-dimensional stress in 1-axes direction
D,1,all ! Define b.c. on node 1, fixed
D,2,UY,0.00 ! Symmetry
D,4,UX,0.00 ! Symmetry
D,2,UX,appliedStrain*ShellDimensionX/100!applied displacement
D,3,UX,appliedStrain*ShellDimensionX/100!applied displacement

The complete APDL code to set up the model parametrically is published in [1] and is printed in Appendix.

4 Numerical results

The postprocessor (/POST1) can be used to produce a contour plot of state variables, as shown in Fig.2 and Fig.4. The contour plot in Fig. 2 is not very interesting because the value of crack is uniform over the $x$-$y$ domain. The $\text{TIME} = 0.24$ was selected purposely to coincide with the initiation of damage at $\varepsilon_x = 0.48\%$. ANSYS implementation of DDM is shown to be independent of mesh density, element type and size and number of nodes.

/POST1 ! POST-PROCESSOR MODULE
/GRA,FULL ! NEEDED FOR PLOTTING SVARS
RSYS,SOLU ! RSYS: ACTIVATE RESULTS IN LAYER COORD.
SYSTEM
SET,,,,,0.24 ! SET,,,,,TIME : SELECT TIME
PLESOL,SVAR,4 ! PLESOL: CONTOUR PLOT STATE VAR NUMBER
FINISH ! EXIT POST-PROCESSOR MODULE

The time postprocessor (/POST26) can be used to produce a time plot of state variables as shown in Fig.3 and Fig.5.

/POST26 ! Start time-history post-process
PLVAR,3 ! REVERSE BACKGROUND COLOR
ANSOL,2,3,EPEL,X,EpsXNod3 ! Var #2, Node 3, Elastic Strain, X-dir, label
ANSOL,3,3,S,X,NxNod3 ! Var #3, Node 3, Stress, X-dir, label
ANSOL,4,3,S,X,SxNod3 ! Var #3, Node 3, Stress, X-dir, label
/AXLAB,X,STRAIN
/AXLAB,Y,STRESS
XVAR,2 ! plot #2 as abscissa
PLVAR,3 ! plot #3 as ordinate
! list time(default), strain=2, reactions=3
PRVAR,2,3
FINISH ! Exit post-process module
Fig. 2. Uniform crack density $\lambda = 0.245864$ crack/mm, in layer 2 ($SVAR = 4$), for applied strain $\varepsilon_x = 0.48\%$.

Fig. 3. Average laminate stress $\sigma_x = N_x/h$ applied strain $\varepsilon_x$
Fig. 4. Linear crack density $\lambda = 0.140073$ crack/mm, in layer 2 ($SVAR = 4$), for applied strain $\varepsilon_x = 0.48\%$ on the lower surface and $\varepsilon_x = 0.24\%$ on the right surface.

Fig. 5. Average laminate stress $\sigma_x = N_x/h$ $\varepsilon_x = 0.48\%$ on the lower surface and $\varepsilon_x = 0.24\%$ on the right surface.

5 Conclusion

Methodology is proposed to determine the material parameters for DDA in ANSYS and the procedure is explained. The damage parameters of DDA can be calculated from measured laminate stiffness degradation but they are not directly measurable parameters, as it is, for
example, the crack density. DDA can predict reduction of stiffness, and uses damage parameters to do, but also crack density as a function of load or applied strain is predicted.

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Appendix – complete the APDL input file

/TITLE, Laminate [0/90s/0/90s/0] made from IM7/8552 Unidirectional Graphite/Epoxy Prepreg, USERMATLib.DLL
/PREP7 ! Start pre-processor module

! PARAMETERS
appliedStrain = 2. ! percent
L0 = 0.02 ! initial the crack density
ShellDimensionX = 100. ! model dimensions
ShellDimensionY = 100. ! mm
tk = 0.15 ! ply thickness
NL = 3 ! number layers half laminate
Nprops = 3+9*NL ! # material properties

! NEXT VALUES GO IN TBDATA
GIc = .170
GIIc = 0.23
deltaT = 0.
E1 = 161e+03
E2 = 14.39e+03
G12= 5.2e+03
nu12 = 0.467
nu23 = 0.410
CTE1 = -0.9
CTE2 = 28.8

! Angle with TBDATA for each layer
! Thickness with TBDATA for each layer

! USERMAT DECLARATION SECTION
TB,USER,1,1,Nprops, ! DECLARES USAGE OF USERMAT 1, MAT 1,
TBTEMP,0 ! reference temperature
TBDATA,,GIc,GIIc,deltaT,E1,E2,G12 ! 6 values per TBDATA line
TBDATA,,nu12,nu23,CTE1,CTE2,0,tk
TBDATA,,E1,E2,G12,nu12,nu23,CTE1
TBDATA,,CTE2,90,8*tk,E1,E2,G12
TBDATA,,nu12,nu23,CTE1,CTE2,0,tk/2
TB,STAT,1,1,3*NL ! NUMBER OF STATE VARIABLES
! INITIALIZE THE STATE VARIABLES
TBDATA,,L0,L0,L0,L0,L0,L0
TBDATA,,L0,L0,L0

! MESH
ET,1,182,,3  ! PLANE182, plane elements with plane stress
R,1,2*NL*tk  ! Real const. #1, thickness of whole laminate
N,1          ! Define node 1, coordinates=0,0,0
N,2,ShellDimensionX,0  ! Define node 2,
N,3,ShellDimensionX,ShellDimensionY
N,4,0,ShellDimensionY
E,1,2,3,4     ! Generate element 1 by node 1 to 4
FINISH        ! Exit pre-processor module
/SOLU         ! Start Solution module
ANTYPE,STATIC
OUTRES,ALL,1  ! Store results for each substep
OUTRES,SVAR,1 ! Store results of state variables

! Define one-dimensional stress in 1-axes direction
D,1,all       ! Define b.c. on node 1, fixed
D,2,UY,0.00   ! Symmetry
D,4,UX,0.00   ! Symmetry
D,2,UX,appliedStrain*ShellDimensionX/100  ! applied displacement
D,3,UX,appliedStrain*ShellDimensionX/100  ! applied displacement

!AUTOS, ON     ! Automatic substeps (min supstep=1/desired)
NSUBST,100,200,100  ! substeps: desired, max.#, min.#
SOLVE         ! Solve load step
FINISH        ! Exit solution module

/POST1         ! POST-PROCESSOR MODULE
/GRA,FULL      ! NEEDED FOR PLOTTING SVARS
RSYS,SOLU      ! RSYS: ACTIVATE RESULTS IN LAYER COORD. SYSTEM
SET,,,,,24     ! SET,,,,,TIME : SELECT TIME
PLESOL,SVAR,4  ! PLESOL: CONTOUR PLOT STATE VAR NUMBER
FINISH         ! EXIT POST-PROCESSOR MODULE

/POST26        ! Start time-history post-process
PLVAR,3        ! REVERSE BACKGROUND COLOR
ANSOL,2,3,EPEL,X,EpsXNod3  ! Var #2, Node 3, Elastic Strain, X-dir, label
ANSOL,3,3,S,X,NxNod3        ! Var #3, Node 3, Stress, X-dir, label
ANSOL,4,3,S,X,SxNod3        ! Var #3, Node 3, Stress, X-dir, label
/AXLAB,X,STRAIN
/AXLAB,Y,STRESS
XVAR,2          ! plot #2 as abscissa
PLVAR,3 ! plot #3 as ordinate
! list time(default), strain=2, reactions=3
PRVAR,2,3
FINISH ! Exit post-process module