Numerical Simulation and Performance Prediction of Centrifugal Pump’s Full Flow Field Based on OpenFOAM

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Abstract: The open-source software OpenFOAM 5.0 was used as a platform to perform steady-state and transient numerical simulation for full flow field of a pipeline centrifugal pump (specific speed $n_s = 65$) in a wide operating capacity range of $0.3Q_d \sim 1.4Q_d$. The standard k-$\varepsilon$ and k-$\omega$ SST (Shear-Stress Transport) turbulence models were selected in the flow governing equations. The simpleFoam and pimpleDyMFoam solvers were used for the steady-state and transient calculations, respectively. ParaView, the postprocessor in OpenFOAM, was used to display the calculated flow velocity, pressure and streamline distributions, and to analyze the relationship between the vortex and the hydraulic loss in the pump. The external performance parameters of the pump such as head, input power and efficiency were also calculated based on the simulated flow fields. The predicted pump performances by OpenFOAM and Ansys-Fluent are compared with the test results under the same calculation model, grids and boundary conditions. The comparison indicates that OpenFOAM had high accuracy in the prediction of pump performance in the current case.

Keywords: OpenFOAM; centrifugal pump; numerical simulation; performance prediction

1. Introduction

Centrifugal pumps are widely applied in the processing industry, agricultural, civil and various other fields [1]. With the development of computational technology, the computational fluid dynamics (CFD) technique becomes very powerful and spans a wide range of industrial and non-industrial areas [2]. Commercial CFD software is convenient to use but the programming is usually unknown, so it is hard for users to modify or add models and algorithms according to their own ideas on certain issues. OpenFOAM, an object-oriented CFD open-source software, not only provides a wide range of standard solvers but also allows users to edit them in terms of the source code [3]. Due to the expandability and openness of source codes, recently some researches have been carried out on the flow field of pump machines by means of OpenFOAM. Petit et al. [4,5] and Nilsson [6], respectively, performed steady-state (frozen rotor method) and transient (sliding grid method) simulations on the flow field of centrifugal pumps and hydro turbines, and compared the results with the actual measurement. Xie [7] used 2D and 3D steady-state and transient methods to simulate the flow fields of a low specific speed centrifugal pump. Zhang [8] performed numerical calculations of turbulent flow for a high head turbine with k-$\omega$ SST (shear-stress transport) turbulence model and obtained the distribution of cavitating vapor in the turbine. Nuernberg and Tao [9] simulated the 3D tidal turbine array using a moving mesh with a rotor-stator interface to account for the effects of rotating tidal turbine blades and the flow field characteristics in tidal turbine arrays. Liu et al. [10] conducted a steady-state numerical simulation of the flow field in a centrifugal pump with specific speed $n_s$.
= 117.8 under three operating conditions (0.8Q_d, 1.0Q_d and 1.2Q_d) and found that the pump under the off-design operating conditions was well predicted by OpenFOAM 1.5-dev. However, due to the limitations of the solvers and post-processing functions of the previous OpenFOAM versions, the numerical results of the above-mentioned studies were far from satisfactory on the prediction accuracy of pump performance. Also, the researches based on OpenFOAM lacked in a full flow field of centrifugal pumps in a wide range of flow rates.

With the upgrade of the open source software OpenFOAM, the potential for computing pumps’ flow field and performance has significantly improved. In this work, therefore, a common pipeline centrifugal pump was selected by using OpenFOAM 5.0 to study the steady-state and transient full flow fields in a wide range (0.3Q_d~1.4Q_d) of operating conditions and to analyze the relationship between flow field and hydraulic loss in the pump with the updated post-processors. By comparing the measured results, the accuracy of OpenFOAM 5.0 software in predicting the performance of the centrifugal pump was analyzed.

2. Numerical Method and Model

2.1. Governing Equations

The governing equations of the fluid flow in this work included the continuity equation and the momentum equation. For turbulent flow, the k-ε model is used widely for internal flows, which provides an efficient method of calculating engineering flows [11]. Also, Liu et al. [10] found that the standard k-ε turbulence model had higher accuracy in computation of centrifugal pump performance after comparing with RNG (ReNormalization Group) k-ε and k-ω SST models. However, Shojaeefard et al. [12] found that the near-wall flow could be evaluated with high precision using the k-ω SST model, and the results had better accuracy than those of the k-ε model in a centrifugal pump simulation. Therefore, both the standard k-ε model and the k-ω SST model were chosen for the simulation in this study. All the governing equations can be expressed in a general differential formulation:

$$\frac{\partial}{\partial t} (\rho \phi) + \frac{\partial}{\partial x_j} (\rho u_j \phi) = \frac{\partial}{\partial x_j} \left( \Gamma \frac{\partial \phi}{\partial x_j} \right) + S$$  

where \( \rho \) is the density of the fluid, \( u_i \) is the i-directional component of the velocity vector, \( \phi \) is the arbitrary scalar, \( \Gamma \) is the diffusion coefficient, and \( S \) is the source term. The items in Equation (1) from left to right are transient items, convection items, diffusion items and source items. For different equations, \( \phi \), \( \Gamma \) and \( S \) have different forms. Table 1 shows the detailed forms of the parameters \( \phi \), \( \Gamma \) and \( S \) for different equations, in which the turbulence model is the standard k-ε model.

| Equation                             | \( \phi \) | \( \Gamma \) | \( S \)               |
|--------------------------------------|------------|-------------|-----------------------|
| Continuity equation                  | 1          | 0           | 0                     |
| Momentum equation                    | \( u_i \)  | \( \mu \)   | \( \frac{\partial \rho \mu}{\partial x_i} + S_i \) |
| Turbulent kinetic energy equation    | \( k \)    | \( \mu + \frac{\nu}{\sigma_k} \) | \( G_k + S_k - \rho \varepsilon \) |
| Turbulence eddy dissipation equation | \( \varepsilon \) | \( \mu + \frac{\nu}{\sigma_\varepsilon} \) | \( C_{1 \varepsilon} G_k - C_{2 \varepsilon} \rho \varepsilon^2 + S_\varepsilon \) |

In these equations, \( \mu \) is dynamic viscosity. The turbulent viscosity \( \mu_t \) is computed by combining \( k \) and \( \varepsilon \) as follows:

$$\mu_t = \rho C_{\mu} \frac{k^2}{\varepsilon}$$  

\( C_{\mu}, C_{1 \varepsilon}, C_{2 \varepsilon}, \sigma_k \) and \( \sigma_\varepsilon \) are model constants. \( G_k \) represents the generation of turbulence kinetic energy due to the mean velocity gradients. \( S_k \) and \( S_\varepsilon \) are source terms. \( S_i \) is a generalized source term of the momentum conservation equation.
2.2. Computational Domain and Meshing

A common pipeline centrifugal pump of type IS125-100 was chosen for the research as shown in Figure 1. The design parameters for the centrifugal pump were: capacity ($Q_d = 54$ L/s), rotational speed ($n = 2900$ r/min), specific speed ($n_s = 65$), impeller inlet diameter ($D_0 = 125$ mm), impeller outlet diameter ($D_2 = 216$ mm), impeller outlet width ($b_2 = 26.5$ mm), impeller blade outlet angle ($\beta_2 = 28^\circ$), number of impeller blades ($Z = 6$), discharge diameter ($D = 100$ mm). The computational domain was composed of an inlet pipe, impeller and volute. A 3D model was created by Pro-E software and imported into the ICEM software to generate the computational grid, which was converted into a format that OpenFOAM recognized. Since the domain of a centrifugal pump with such specific speed is complex, the grid is generally generated in an unstructured type for applications.

![Geometry of type IS125-100.](image)

Figure 1. Geometry of type IS125-100.

To choose a proper computational grid for simulation, the grid independency was examined. Figure 2 shows the relation between element number and calculated pump head with the standard k-$\varepsilon$ turbulence model by Fluent and OpenFOAM. When the number of grids exceeded 1,000,000, the effect of the grids increase on the head was negligible, so the total number of elements in the simulation was 1,024,853 as shown in Figure 3.

![Curves of grids independency.](image)

Figure 2. Curves of grids independency.
2.3. Solvers and Boundary Conditions

The solver is the key tool for solving the discretization forms of the flow governing equations. The solvers, simpleFoam and pimpleDyM Foam, were used for the steady-state and transient simulations in this work, respectively. It was assumed that the pressure at the inlet of the pipeline pump was high enough and no cavitation occurred in the pump.

2.3.1. The SimpleFoam Solver

The simpleFoam is a steady-state incompressible flow solver in OpenFOAM, based on the SIMPLE (Semi-Implicit Method for Pressure Linked Equations) algorithm for pressure-velocity coupling [13]. In this algorithm, for a given pressure field (initial value or the result of the last iteration calculation), the discrete form of the flow governing equation is solved to obtain the velocity field for the next iteration. Under-relaxation factors \( \alpha_u \) and \( \alpha_p \) \((\alpha_u + \alpha_p = 1)\) were used to maintain iteration stability for velocity and pressure correction [14]. Also, the optimum convergence results with the combination of under-relaxation factors were found to be \( \alpha_u = (0.7 \sim 0.8) \) and \( \alpha_p = (0.3 \sim 0.2) \) [15]. Finally, the under-relaxation factors of velocity \( v \), pressure \( p \), turbulence kinetic energy \( k \) and turbulence dissipation rate \( \varepsilon \) or specific dissipation rate \( \omega \) were 0.7, 0.3, 0.3, 0.3, respectively.

The “frozen rotor method” [16] was used in the simulations based on the multiple reference frame (MRF). The MRF approach implies that there is no relative mesh motion of the rotating and stationary parts. The solution of the steady-state, turbulent and incompressible flow of the impeller is governed by the Reynolds-averaged Navier-Stokes equations (RANS) in the rotating reference frame [4].

Arbitrary mesh interface (AMI) [17] was adopted to transfer the flux between the rotational impeller and stationary domain grids by a set of weighting factors both for steady-state and transient cases. The boundary conditions for the steady state computation were: (1) The type of velocity \( v \), turbulent kinetic energy \( k \) and turbulent eddy dissipation \( \varepsilon \) or \( \omega \) at the inlet were “fixedValue”. The value of \( v \) was given by the pump operation capacity, the initial values of \( k, \varepsilon \) and \( \omega \) were calculated and the pressure type at the inlet was “zeroGradient”; (2) The pressure type at the outlet was “fixedValue”; (3) The no-slip solid wall condition was adopted in wall surfaces, and the standard wall function method was used to determine the flow around the solid wall. The turbulent parameters of wall functions, \( \mu_s, k, \varepsilon \) and \( \omega \) were specified through the “nutkWallFunction”, “kqRWallFunction”, •
“epsilonWallFunction” and “omegaWallFunction” in terms of OpenFOAM code, respectively. Yplus ($y+$) is the dimensionless distance from the wall and is used to check the location of the first node. When standard wall functions are used, the value of $y+$ in the range 30–500 satisfies the log-law [18]. In the present study, thus, the values of $y+$ were set with the locations of the first nodes in the range of 30–300; (4) The type of the impeller wall was “movingWallVelocity”; (5) The impeller domain was defined by the “MRFProperties” file according to the “frozen rotor method”. For the discretizations, the second-order Gauss linear upwind convection schemes were adopted for a higher accuracy. For the gradient terms, the Gauss linear scheme was selected, and the residual criterion was set to $10^{-3}$.

2.3.2. The PimpleDyMFoam Solver

The pimpleDyMFoam solver, based on the PIMPLE (merged PISO (Pressure Implicit with Splitting of Operators)-SIMPLE) algorithm [19], is a reasonable time step transient for incompressible turbulent flow with dynamic meshes. The basic method in the PIMPLE algorithm is to use the PISO algorithm to step the time, and at each step the pressure field of a non-final iteration step and velocity field are solved. The solution of the time-dependent, turbulent and incompressible flow system of the pump is governed by the unsteady Reynolds-averaged Navier-Stokes equations (URANS) that can be in the formulations written for a moving control volume [20].

All boundary conditions for the transient case were consistent with those for the steady-state case except condition (5). The computational domain of the impeller was defined by the “dynamicMeshDict” file according to the “sliding mesh method” [21,22]. The first order implicit Euler scheme was adopted for the time discretization. The time step was set to be $5 \times 10^{-5}$ s equivalent to the time for the impeller to rotate 1 degree, and the maximum Courant number was set to 5. The residual criterion was set to $10^{-6}$ and the maximum iterative loop was 100 in each time step.

3. Results and Analysis

3.1. Pump Flow Field Distribution

The calculated results of flow fields can be displayed by ParaView (OpenFOAM’s postprocessor) or converted to other post-processing data formats. Figure 4 shows the flow velocity vectors in the pump by steady-state calculation under three operating conditions ($0.3Q_d$, $1.0Q_d$ and $1.4Q_d$). It can be seen from the figure that due to the rotation of the impeller, the flow velocity in the impeller gradually increases along the radius, and the flow velocity at the impeller outlet reaches a maximum value. After entering the volute, the flow velocity decreases. Since the volute passage near the outlet is designed as a bend, the flow velocity outside the volute is higher than that inside near the outlet due to centrifugal force. Apparently, the velocity vectors in the volute appear too small or too large under the condition of $0.3Q_d$ or $1.4Q_d$, indicating that the size of the volute is not suitable for these operating conditions.

Figures 5 and 6 respectively show the distributions of the streamlines in the centrifugal pump projected on the central $xy$ and $xz$ planes (corresponding to Figure 3) by the steady-state calculation under three operating conditions. On the $xy$ plane, under $0.3Q_d$ operating condition, the fluid passes the volute diffuser region in a lower velocity (Figure 5a). When the flow rate is $1.0Q_d$, the main flow tends to follow the curvature of the volute outer wall (Figure 5b). Under the $1.4Q_d$ operating condition, a recirculation region is obviously observed on the inner wall near the volute exit due to a higher centrifugal force (Figure 5c). It is noted that flow velocity departing from the outlet of the impeller is more uniform (magnitude is about 20 m/s) under $1.0Q_d$ than at $0.3Q_d$ and $1.4Q_d$ operating conditions.
Figures 5 and 6 respectively show the distributions of the streamlines in the centrifugal pump projected on the central xy and zx planes (corresponding to Figure 3) by the steady-state calculation under three operating conditions. On the xy plane, under 0.3Qd operating condition, the fluid passes the volute diffuser region in a lower velocity (Figure 5a). When the flow rate is 1.0Qd, the main flow tends to follow the curvature of the volute outer wall (Figure 5b). Under the 1.4Qd operating condition, a recirculation region is obviously observed on the inner wall near the volute exit due to a higher centrifugal force (Figure 5c). It is noted that flow velocity departing from the outlet of the impeller is more uniform (magnitude is about 20 m/s) under 1.0Qd than at 0.3Qd and 1.4Qd operating conditions.

On the zx plane, there are some vortices (see arrows in Figure 6) with different sizes in the inlet, impeller and volute under three operating conditions. Under the 0.3Qd operating condition (Figure 6a), the inlet velocity is insufficient to overcome adverse pressure gradient and the separation flow phenomenon occurs at the duct, generating a couple of strong swirling vortexes in the separation point. In Figure 6, some vortexes are clearly observed in the volute cross sections, which belong to the secondary flow vortex which usually occurs in a bent pipe. In contrast, the vortexes under 1.0Qd are...
less comparable to those under off-design conditions. These phenomena explain the reason that the hydraulic loss under off-design conditions is significant compared to that under the design condition.

Figure 5. Distribution of streamlines in the pump on the xy plane (steady-state, OpenFOAM k-ε).

Figure 7 shows the static pressure distribution per density of the fluid in the centrifugal pump by the steady-state calculations under the three operating conditions. It can be seen from the figure that the lowest static pressure zone is located around the leading edges of the impeller blades, while the highest pressure value appears at a certain position in the volute passage. From the point of view of fluid mechanics, hydraulic loss mainly includes friction loss and diffusion loss along the flow passage. Under the 0.3Q_d flow condition (Figure 7a), lower velocity in a larger size of volute leads to serious diffusion loss. Due to the increase of flow velocity under the high flow condition of 1.4Q_d (Figure 7c), the frictional loss increases and the static pressure also reduces at the outlet of the volute.

Figure 6. Distribution of streamlines in the pump on the zx plane (steady-state, OpenFOAM k-ε).

Figure 7. Static pressure distribution in the pump (steady-state, OpenFOAM k-ε).
3.2. Pump Characteristics Prediction

Based on the numerical results of flow field in the pump, the external characteristic parameters such as head $H$, input power $N$ and efficiency $\eta$ can be calculated by Equations (3)–(5):

$$H = \frac{P_{out} - P_{in}}{\rho g} + h$$  \hspace{1cm} (3)

$$N = M \omega$$  \hspace{1cm} (4)

$$\eta = \frac{\rho g Q H}{N}$$  \hspace{1cm} (5)

where, $P_{out}$, $P_{in}$ is the average total pressure of the pump at outlet and inlet, respectively; $h$ is the distance in gravity direction from the pump outlet to the inlet; $M$ is the torque acting on the inner flow surface of the impeller; $\omega = 2\pi n / 60$.

Figure 8 shows the steady-state and transient calculated results of the head $H$ over time $t$. From the $H$ transient curve, it can be seen that after about $2T$ time ($T = 0.0207$ s, impeller rotational period), the $H$ transient value has a stable harmonic variation with $t$. The time-average value of transient $H$ is approximately equal to the steady-state value of $H$ (i.e., the pump is in a stable operating stage). Within the period $T$, the $H$ transient value has six pulses corresponding to the number of impeller blades. The pulsation amplitude increases significantly with operating capacity.

![Figure 8. Variation of calculated value $H$ with time $t$ (OpenFOAM k-ε).](image-url)
3.3. CFD Model Validation

In this study, flow field simulation was also performed with the standard k-\(\varepsilon\) turbulence model by Ansys Fluent in the same geometry model, computational grids and boundary conditions. In order to validate the computational method and results, the performance tests of the type IS125-100 centrifugal pump were performed at Guangyi Pump Co. Ltd. in China [23].

Figure 9 shows the comparisons between the predicted performance results and the test data. The predicted values were calculated by Equations (3)–(5) with steady-state OpenFOAM and Fluent computation, respectively. It is noted that the measured values of shaft power and efficiency are related to the volumetric and mechanical loss of the pump. These two kinds of losses could not be considered in CFD software, so the predicted results of power and efficiency were only consumed by flow and the hydraulic efficiency, respectively.

![Figure 9. Comparisons between predicted and tested performances.](image)

Compared to the results by Fluent as seen in Figure 9a, the head curves by OpenFOAM are closer to the test values. The error analysis was conducted, and the results are shown in Table 2. The mean relative error of the head curve computed with k-\(\varepsilon\) model by Fluent is 4.9% relative to the test values, while the corresponding values with k-\(\varepsilon\) and k-\(\omega\) SST models by OpenFOAM are 1.2% and 2.3%, respectively. In terms of head maximum relative error, the value with the k-\(\varepsilon\) model by Fluent reaches 7.5%, but the values with k-\(\varepsilon\) and k-\(\omega\) SST by OpenFOAM are 4.7% and 6.5%. This indicates that OpenFOAM is able to obtain more acceptable results than Fluent under the flow conditions of 0.3Q_d~1.4Q_d in the current case. Meanwhile, in Figure 9b,c, the measured values of the shaft power and
efficiency lie between the predicted results by Fluent and OpenFOAM. If volumetric and mechanical losses are considered, the predicted values by Fluent will deviate further from the measured results, and the predicted results by OpenFOAM will be close to the measured results.

|                      | Fluent k-ε | OpenFOAM k-ε | OpenFOAM k-ω SST (shear-stress transport) |
|----------------------|------------|--------------|------------------------------------------|
| Mean relative error  | 4.9%       | 1.2%         | 2.3%                                     |
| Maximum relative error| 7.5%       | 4.7%         | 6.5%                                     |

4. Conclusions

With the steady state and transient simulations of the full flow field of the centrifugal pump in a wide range of operating conditions by OpenFOAM, the following conclusions are summarized:

1. When the pump runs stably, the transient value of the head changes with time in a stable harmonic way, and the time-average value of the head is approximately equal to the steady state value. In one impeller rotation period, the number of head pulses corresponds to that of the impeller blades. The pulsation amplitude increases significantly with capacity.
2. The flow simulation by OpenFOAM could well capture the vortexes in the pump. There are more vortexes under off-design conditions than those under design operating conditions. The flow velocity departing from the outlet of the impeller is more uniform under design operating conditions than those under off-design conditions. Diffusion loss and friction loss are the main hydraulic losses under lower and higher flow conditions, respectively.
3. The predicted results by OpenFOAM with the standard k-ε and the k-ω SST turbulence models agree well with the measured results of the pump characteristics in the current case.
4. The present study assumed that the inlet pressure was high enough to ensure no cavitation. In fact, cavitation always occurs and seriously affects pump performance. Thus, the effect of cavitation will be considered by OpenFOAM in further pump performance simulations.

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