FREE BOUNDARY REGULARITY FOR A PROBLEM WITH RIGHT HAND SIDE

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Abstract. We consider a one-phase free boundary problem with variable coefficients and non-zero right hand side. We prove that flat free boundaries are $C^{1,\alpha}$ using a different approach than the classical supconvolution method of Caffarelli. We use this result to obtain that Lipschitz free boundaries are $C^{1,\alpha}$.

1. Introduction

Consider the following one-phase free boundary problem with variable coefficients and non-zero right hand side,

\begin{equation}
\begin{aligned}
\sum_{i,j} a_{ij}(x) u_{ij} &= f, & \text{in } \Omega^+(u) := \{ x \in \Omega : u(x) > 0 \}, \\
|\nabla u| &= g, & \text{on } F(u) := \partial \Omega^+(u) \cap \Omega,
\end{aligned}
\end{equation}

with $\Omega$ a bounded domain in $\mathbb{R}^n$, the coefficients $a_{ij} \in C^{0,\beta}(\Omega)$, $f \in C(\Omega) \cap L^\infty(\Omega)$, and $g \in C^{0,\beta}(\Omega)$, $g \geq 0$.

In this paper we are concerned with the regularity of the set $F(u)$, that is the so-called free boundary of $u$. There is an extensive literature on the regularity of the free boundary for this type of problem when $f \equiv 0$. In the case of the Laplace operator, Caffarelli proved in his pioneer work [C1] that Lipschitz free boundaries are $C^{1,\alpha}$, while in [C2] he showed that “flat” free boundaries are Lipschitz. The key step of the method in [C1, C2] consists in finding a family of comparison subsolutions using supconvolutions on balls of variable radii.

Higher regularity of the free boundary follows from the classical work of Kinderlehrer and Nirenberg [KN].

Regularity results in the spirit of [C1, C2] have been subsequently proved for more general operators. In [W1, W2] Wang considered concave fully nonlinear uniformly elliptic operators of the form $F(D^2u)$. The work [C1] was extended by Feldman [F1, F2] to a class on nonconcave fully nonlinear uniformly elliptic operators of the type $F(D^2u, Du)$ and to certain nonisotropic problems. For operators with variable coefficients regularity results are proved in the work of Cerruti, Ferrari, Salsa [CFS], and Ferrari, Salsa [FS1, FS2]. Also, Ferrari and then Argiolas, Ferrari in [Fe1, Fe2] considered a class of fully nonlinear operators of the form $F(D^2u, x)$ with Hölder dependence on $x$.

The results cited above follow the guidelines of [C1, C2]. One purpose of this paper is to provide a different method to obtain that flat free boundaries are $C^{1,\alpha}$. The approach we use is quite flexible since it easily applies to more general nonlinear operators, even degenerate ones, and it also applies to two-phase problems.

In particular, when dealing with operators with variable coefficients we easily obtain that Lipschitz free boundaries are $C^{1,\alpha}$. In fact our flatness result allows
us to use a blow-up argument and reduce the problem to the case of constant coefficients operators. Our strategy is largely inspired by the work of Savin [S].

We now state our main results (for the precise definition of viscosity solutions we refer the reader to Section 2.) We assume that the matrix $A = (a_{ij}(x))$ is positive definite.

**Theorem 1.1** (Flatness implies $C^{1,\alpha}$). Let $u$ be a viscosity solution to (1.1) in $B_1$. Assume that $0 \in F(u)$, $g(0) = 1$ and $a_{ij}(0) = \delta_{ij}$. There exists a universal constant $\varepsilon > 0$ such that, if the graph of $u$ is $\varepsilon$-flat in $B_1$, i.e.

$$
(x_n - \varepsilon) \leq u(x) \leq (x_n + \varepsilon), \quad x \in B_1
$$

and

$$
[a_{ij}]_{C^{0,\beta}(B_1)} \leq \varepsilon, \quad \|f\|_{L^\infty(B_1)} \leq \varepsilon, \quad [g]_{C^{0,\beta}(B_1)} \leq \varepsilon,
$$

then $F(u)$ is $C^{1,\alpha}$ in $B_{1/2}$.

**Theorem 1.2** (Lipschitz implies $C^{1,\alpha}$). Let $u$ be a viscosity solution to (1.1). Assume that $0 \in F(u)$ and $g(0) > 0$. If $F(u)$ is a Lipschitz graph in a neighborhood of 0, then $F(u)$ is $C^{1,\alpha}$ in a (smaller) neighborhood of 0.

In the theorem above, the size of the neighborhood where $F(u)$ is $C^{1,\alpha}$ depends on the radius $\rho$ of the ball $B_{\rho}$ where $F(u)$ is Lipschitz, on the Lipschitz norm of $F(u)$, on $[a_{ij}]_{C^{0,\beta}(B_{\rho})}$, $[g]_{C^{0,\beta}(B_{\rho})}$, and $\|f\|_{L^\infty(B_{\rho})}$.

We remark that the assumptions on the coefficients $a_{ij}(x)$ in Theorem 1.1 can be weakened to a Cordes-Nirenberg type condition:

$$
\|a_{ij} - \delta_{ij}\|_{L^\infty(B_1)} \leq \delta(n).
$$

As already pointed out, our strategy of the proof of Theorem 1.1 is inspired by [S]. The main idea is to show that the graph of $u$ enjoys an “improvement of flatness” property, that is if the graph of $u$ oscillates $\varepsilon$ away from a hyperplane in $B_1$, then in $B_{\rho_0}$ it oscillates $\varepsilon\rho_0/2$ away from possibly a different hyperplane. The key tool in proving this property will be a Harnack type inequality for solutions to a one-phase free boundary problem.

The proof of Theorem 1.2 will follow via a blow-up argument from Theorem 1.1 and the classical theory in [C1].

The problem (1.1), in which a right hand side appears, is not specifically dealt with in any of the previous cited works. Our interest in this problem arises in connection with the question of the regularity of the free surface which occurs in the classical hydrodynamical problem for traveling two-dimensional gravity water-waves with vorticity. There has been considerable interest in this problem in recent years, starting with the systematic study of Constantin and Strauss [CS].

The physical situation is the following: a traveling wave of an incompressible, inviscid, heavy fluid moves with constant speed over an horizontal surface. Since the fluid is incompressible, the flow can be described by a stream function $u$ which solves the following free boundary problem (in 2D)

$$
\Delta u = -\gamma(u), \quad \text{in } \Omega := \{(x, y) \in \mathbb{R}^2 : 0 < u(x, y) < B\}
$$

$$
u = B, \quad \text{on } y = 0
$$

$$
|\nabla u|^2 + 2gy = Q, \quad \text{on } S := \{u = 0\},
$$

with $B, g$ fixed constants, $\gamma$ a given vorticity function and $Q$ a parameter. Of special interest are those free boundaries which are given by the graph of a function $y =
ψ(x). In the regions where ψ is monotone decreasing (resp. increasing) the free boundary is Lipschitz with respect to the direction $e_1 + e_2$ (resp. $e_2 - e_1$) and moreover $Q - 2g\psi > 0$. As a consequence of Theorem 1.2 we obtain that the free boundary is smooth in these regions.

The free boundary is not expected to be smooth at the so-called stagnation points where $Q = 2g\psi$. At such points, the profile of an irrotational wave ($\gamma \equiv 0$) has a corner with included angle of 120°. This was conjectured by Stokes and it was proved by Amick, Fraenkel, and Toland [AFT], and by Plotnikov [P]. The case $\gamma \neq 0$ was investigated by Varvaruca in [V] and recently by Varvaruca and Weiss [VW].

The paper is organized as follows. In Section 2 we introduce notation and definitions and we prove a regularity result for viscosity solutions to a Neumann problem which we will use in the proof of Theorem 1.1. Next, in Section 3, we present the statement of our Harnack inequality and we exhibit its proof. In Section 4, we state and prove the “improvement of flatness” lemma. Finally, in Section 5, we provide the proof of Theorem 1.1 and Theorem 1.2. We conclude the paper with an Appendix in which we prove the standard Lipschitz continuity and non-degeneracy of solutions to a one-phase free boundary problem.

2. Preliminaries

In this section we provide notation and definitions used throughout the paper. We also present an auxiliary result which will be used in the proof of our main Theorem 1.1.

**Notation.** For any continuous function $u : \Omega \subset \mathbb{R}^n \rightarrow \mathbb{R}$ we denote

$$\Omega^+(u) := \{x \in \Omega : u(x) > 0\}, \quad F(u) := \partial \Omega^+(u) \cap \Omega.$$ 

We refer to the set $F(u)$ as to the free boundary of $u$, while $\Omega^+(u)$ is its positive phase (or side).

We now state the definition of viscosity solution to the problem under consideration, that is

$$\begin{aligned}
\sum_{i,j} a_{ij}(x) u_{ij} &= f, \quad \text{in } \Omega^+(u) \\
|\nabla u| &= g, \quad \text{on } F(u).
\end{aligned} \tag{2.1}$$

Here $\Omega$ is a bounded domain in $\mathbb{R}^n$, $a_{ij} \in C^{0,\beta}(\Omega)$, $f \in C(\Omega) \cap L^\infty(\Omega)$, $g \in C^{0,\beta}(\Omega)$, and $g \geq 0$.

First we need the following standard notion.

**Definition 2.1.** Given $u, \varphi \in C(\Omega)$, we say that $\varphi$ touches $u$ by below (resp. above) at $x_0 \in \Omega$ if $u(x_0) = \varphi(x_0)$, and

$$u(x) \geq \varphi(x) \quad \text{(resp. } u(x) \leq \varphi(x)\text{)}$$

in a neighborhood $O$ of $x_0$. If this inequality is strict in $O \setminus \{x_0\}$, we say that $\varphi$ touches $u$ strictly by below (resp. above).

**Definition 2.2.** Let $u$ be a nonnegative continuous function in $\Omega$. We say that $u$ is a viscosity solution to (2.1) in $\Omega$, if and only if the following conditions are satisfied:
(i) \( \sum_{i,j} a_{ij}(x) u_{ij} = f \) in \( \Omega^+(u) \) in the viscosity sense, i.e. if \( \varphi \in C^2(\Omega^+(u)) \) touches \( u \) by below (resp. above) at \( x_0 \in \Omega^+(u) \) then
\[
\sum_{i,j} a_{ij}(x_0) \varphi_{ij}(x_0) \leq f(x_0) \quad \text{ (resp. } \sum_{i,j} a_{ij}(x_0) \varphi_{ij}(x_0) \geq f(x_0) \text{).}
\]

(ii) If \( \varphi \in C^2(\Omega) \) and \( \varphi^+ \) touches \( u \) by below (resp. above) at \( x_0 \in F(u) \) and \( |\nabla \varphi|(x_0) \neq 0 \) then
\[
|\nabla \varphi|(x_0) \leq g(x_0) \quad \text{ (resp. } |\nabla \varphi|(x_0) \geq g(x_0) \text{).}
\]

Viscosity solutions are introduced so to be able to use comparison techniques. To this aim, we will need the following notion of comparison subsolution/supersolution.

**Definition 2.3.** Let \( v \in C^2(\Omega) \). We say that \( v \) is a strict (comparison) subsolution (resp. supersolution) to (2.2) in \( \Omega \), if and only if the following conditions are satisfied:

(i) \( \sum_{i,j} a_{ij}(x) v_{ij} > f(x) \) (resp. \( < f(x) \)) in \( \Omega^+(v) \);

(ii) If \( x_0 \in F(v) \), then
\[
|\nabla v|(x_0) > g(x_0) \quad \text{ (resp. } 0 < |\nabla v|(x_0) < g(x_0) \text{).}
\]

Notice that, by the implicit function theorem, if \( v \) is a strict subsolution/supersolution then \( F(v) \) is a \( C^2 \) hypersurface.

The following lemma is an immediate consequence of the definitions above.

**Lemma 2.4.** Let \( u, v \) be respectively a solution and a strict subsolution to (2.1) in \( \Omega \). If \( u \geq v^+ \) in \( \Omega \) then \( u > v^+ \) in \( \Omega^+(v) \cup F(v) \).

**Notation.** Here and after \( B_{\rho}(x_0) \subset \mathbb{R}^n \) denotes a ball of radius \( \rho \) centered at \( x_0 \), and \( B_{\rho} = B_{\rho}(0) \). A positive constant depending only on the dimension \( n \) is called a universal constant. We often use \( c, c_i \) to denote small universal constants, and \( C, C_i \) to denote large universal constants.

Our main Theorem 1.1 will follow from the regularity properties of solutions to the classical Neumann problem for the Laplace operator. Precisely, we consider the following boundary value problem:

\[
\begin{aligned}
\Delta \hat{u} &= 0 \quad \text{in } B_{\rho} \cap \{ x_n > 0 \}, \\
\hat{u}_n &= 0 \quad \text{on } B_{\rho} \cap \{ x_n = 0 \}.
\end{aligned}
\]  
(2.2)

We use the notion of viscosity solution to (2.2). For completeness (and for lack of references), we recall standard notions and we prove regularity of viscosity solutions.

**Definition 2.5.** Let \( \hat{u} \) be a continuous function on \( B_{\rho} \cap \{ x_n \geq 0 \} \). We say that \( \hat{u} \) is a viscosity solution to (2.2) if given \( P(x) \) a quadratic polynomial touching \( \hat{u} \) by below (resp. above) at \( \bar{x} \in B_{\rho} \cap \{ x_n \geq 0 \} \), then

(i) if \( \bar{x} \in B_{\rho} \cap \{ x_n > 0 \} \) then \( \Delta P \leq 0 \), (resp. \( \Delta P \geq 0 \)) i.e \( \hat{u} \) is harmonic in the viscosity sense;

(ii) if \( \bar{x} \in B_{\rho} \cap \{ x_n = 0 \} \) then \( P_n(\bar{x}) \leq 0 \) (resp. \( P_n(\bar{x}) \geq 0 \)).
Remark. Notice that, in the definition above we can choose polynomials \( P \) that touch \( \tilde{u} \) strictly by below/above (replace \( P \) by \( P_\eta(x) = P(x) - \eta(x_n - \bar{x}_n)^2 \) and then let \( \eta \) go to 0).

Also, it suffices to verify that (ii) holds for polynomials \( \tilde{P} \) with \( \Delta \tilde{P} > 0 \). Indeed, let \( P \) touch \( \tilde{u} \) by below at \( \bar{x} \). Then,

\[
\tilde{P} = P - \eta(x_n - \bar{x}_n) + C(\eta)(x_n - \bar{x}_n)^2
\]
touches \( \tilde{u} \) by below at \( \bar{x} \) (for a sufficiently small constant \( \eta > 0 \) and a large constant \( C > 0 \) depending on \( \eta \)) and satisfies

\[
\Delta \tilde{P} > 0, \quad \tilde{P}_n(\bar{x}) = P_n(\bar{x}) - \eta.
\]
If (ii) holds for strictly subharmonic polynomials, we get \( \tilde{P}_n(\bar{x}) \leq \eta \) which by letting \( \eta \) go to 0 implies \( P_n(\bar{x}) \leq 0 \).

Lemma 2.6. Let \( \tilde{u} \) be a viscosity solution to (2.2). Then \( \tilde{u} \) is a classical solution to (2.2). In particular, \( \tilde{u} \in C^\infty(B_\rho \cap \{x_n \geq 0\}) \).

Proof. Let

\[
u^*(x) = \begin{cases} 
\tilde{u}(x) & \text{if } x \in B_\rho \cap \{x_n \geq 0\}, \\
\tilde{u}(x',-x_n) & \text{if } x \in B_\rho \cap \{x_n < 0\},
\end{cases}
\]

where \( x' = (x_1,\ldots,x_{n-1}) \).

We claim that \( u^* \) is harmonic (in the viscosity sense), and hence smooth, in \( B_\rho \).

Indeed, let \( P \) be a polynomial touching \( u^* \) at \( \bar{x} \in B_\rho \) strictly by below. We need to show that \( \Delta P \leq 0 \). Clearly, we only need to consider the case when \( \bar{x} \in \{x_n = 0\} \).

Consider the polynomial

\[
S(x) = \frac{P(x) + P(x',-x_n)}{2}.
\]

Then

\[
\Delta S = \Delta P, \quad S_n(x',0) = 0.
\]

Also, \( S \) still touches \( u^* \) strictly by below at \( \bar{x} \). Now, consider the family of polynomials

\[
S_\varepsilon = S + \varepsilon x_n, \varepsilon > 0.
\]

For \( \varepsilon \) small \( S_\varepsilon \) will touch \( u^* \) by below at some point \( x_\varepsilon \).

If \( x_\varepsilon \) belongs to \( \{x_n = 0\} \), since \( S_\varepsilon \) touches \( \tilde{u} \) by below at \( x_\varepsilon \) and \( \tilde{u}_n(x',0) = 0 \) in the viscosity sense, we obtain that

\[
(S_\varepsilon)_n(x'_\varepsilon,0) \leq 0
\]
i.e.

\[
S_n(x'_\varepsilon,0) + \varepsilon \leq 0
\]
contradicting (2.3).

Thus \( x_\varepsilon \in B_\rho \setminus \{x_n = 0\} \) and hence \( \Delta S = \Delta P \leq 0 \).

In conclusion, \( u^* \) is harmonic in \( B_\rho \) and our statement immediately follows. \( \square \)
3. A Harnack Inequality

In this section we will prove a Harnack type inequality for a solution \( u \) to our problem

\[
\begin{aligned}
\sum_{i,j} a_{ij}(x)u_{ij} &= f, & & \text{in } \Omega^+(u) := \{ x \in \Omega : u(x) > 0 \}, \\
|\nabla u| &= g, & & \text{on } F(u) := \partial \Omega^+(u) \cap \Omega,
\end{aligned}
\]

(3.1)

under the assumption \((0 < \varepsilon < 1)\)

\[
\|f\|_{L^\infty(\Omega)} \leq \varepsilon^2, \quad \|g(x) - 1\|_{L^\infty(\Omega)} \leq \varepsilon^2, \quad \|a_{ij} - \delta_{ij}\|_{L^\infty(\Omega)} \leq \varepsilon.
\]

(3.2)

This theorem roughly says that if the graph of \( u \) oscillates \( \varepsilon r \) away from \( x_n^+ \) in \( B_r \), then it oscillates \( (1 - c)\varepsilon r \) in \( B_{r/20} \). A corollary of this theorem will be a key tool in the proof of Theorem 1.1.

**Theorem 3.1** (Harnack inequality). There exists a universal constant \( \bar{\varepsilon} \), such that if \( u \) solves (3.1), (3.2) and it satisfies at some point \( x_0 \in \Omega^+(u) \cup F(u) \),

\[
(x_n + a_0)^+ \leq u(x) \leq (x_n + b_0)^+ \quad \text{in } B_r(x_0) \subset \Omega,
\]

with

\[
b_0 - a_0 \leq \varepsilon r, \quad \varepsilon \leq \bar{\varepsilon}
\]

then

\[
(x_n + a_1)^+ \leq u(x) \leq (x_n + b_1)^+ \quad \text{in } B_{r/20}(x_0),
\]

with

\[
a_0 \leq a_1 \leq b_1 \leq b_0, \quad b_1 - a_1 \leq (1 - c)\varepsilon r,
\]

and \( 0 < c < 1 \) universal.

From this statement we immediately get the desired corollary to be used in the proof of our main result. Precisely, if \( u \) satisfies (3.3) with \( r = 1 \), then we can apply Harnack inequality repeatedly and obtain

\[
(x_n + a_m)^+ \leq u(x) \leq (x_n + b_m)^+ \quad \text{in } B_{20^{-m}}(x_0),
\]

with

\[
b_m - a_m \leq (1 - c)^m \varepsilon
\]

for all \( m \)'s such that

\[
(1 - c)^m 20^m \varepsilon \leq \bar{\varepsilon}.
\]

This implies that for all such \( m \)'s, the oscillation of the function

\[
\tilde{u}_\varepsilon(x) = \frac{u(x) - x_n}{\varepsilon}
\]

in \((\Omega^+(u) \cup F(u)) \cap B_r(x_0), r = 20^{-m}\) is less than \((1 - c)^m = 20^{-\gamma m} = r^\gamma\). Thus, the following corollary holds.

**Corollary 3.2.** Let \( u \) be a solution to (3.1), (3.2) satisfying (3.3) for \( r = 1 \). Then in \( B_1(x_0) \) \( \tilde{u}_\varepsilon \) has a Hölder modulus of continuity at \( x_0 \), outside the ball of radius \( \varepsilon / \bar{\varepsilon} \), i.e for all \( x \in (\Omega^+(u) \cup F(u)) \cap B_1(x_0) \), with \( |x - x_0| \geq \varepsilon / \bar{\varepsilon} \)

\[
|\tilde{u}_\varepsilon(x) - \tilde{u}_\varepsilon(x_0)| \leq C|x - x_0|^\gamma.
\]

The proof of the Harnack inequality relies on the following lemma.
Lemma 3.3. There exists a universal constant $\bar{\varepsilon} > 0$ such that if $u$ is a solution to (3.1)-(3.2) in $B_1$ with $0 < \varepsilon \leq \bar{\varepsilon}$ and $u$ satisfies

\[ p(x)^+ \leq u(x) \leq (p(x) + \varepsilon)^+ \quad x \in B_1, \quad p(x) = x_n + \sigma, \quad |\sigma| < 1/10 \]

then if at $\bar{x} = \frac{1}{5}e_n$

\[ u(\bar{x}) \geq (p(\bar{x}) + \varepsilon)^+ \]

then

\[ u \geq (p + c\varepsilon)^+ \quad \text{in} \quad B_{1/2}, \]

for some $0 < c < 1$. Analogously, if

\[ u(\bar{x}) \leq (p(\bar{x}) + \varepsilon)^+ \]

then

\[ u \leq (p + (1 - c)\varepsilon)^+ \quad \text{in} \quad B_{1/2}. \]

Proof. We prove the first statement. Clearly, from (3.4)

\[ u \geq p \quad \text{in} \quad B_1. \]

Let

\[ w = c(|x - \bar{x}|^{-\gamma} - (3/4)^{-\gamma}) \]

be defined in the closure of the annulus

\[ A := B_{3/4}(\bar{x}) \setminus B_{1/20}(\bar{x}). \]

The constant $c$ is such that $w$ satisfies the boundary conditions

\[
\begin{cases}
    w = 0 & \text{on } \partial B_{3/4}(\bar{x}), \\
    w = 1 & \text{on } \partial B_{1/20}(\bar{x}).
\end{cases}
\]

Also, since $||a_{ij} - \delta_{ij}||_{L^\infty(B_1)} \leq \varepsilon$ the matrix $A = a_{ij}$ is uniformly elliptic and we can choose the constant $\gamma$ universal so that

\[ \sum_{ij} a_{ij}(x)w_{ij} \geq \delta > 0 \quad \text{in} \quad A, \]

with $\delta$ universal. Extend $w$ to be equal to 1 on $B_{1/20}(\bar{x})$.

Notice that since $|\sigma| < 1/10$ using (3.7) we get

\[ B_{1/10}(\bar{x}) \subset B_1^+(u). \]

Also,

\[ B_{1/2} \subset B_{3/4}(\bar{x}) \subset B_1. \]

Since in view of (3.7)-(3.8), $u - p \geq 0$ and solves a uniformly elliptic equation in $B_{1/10}(\bar{x})$ with right-hand side $f$, we can apply Harnack inequality to obtain

\[ u(x) - p(x) \geq c(u(\bar{x}) - p(\bar{x})) - C\|f\|_{L^\infty} \quad \text{in} \quad B_{1/10}(\bar{x}). \]

From (3.5) and the first inequality in (3.2) we conclude that (for $\varepsilon$ small enough)

\[ u - p \geq c\varepsilon - C\varepsilon^2 \geq c_0\varepsilon \quad \text{in} \quad B_{1/20}(\bar{x}). \]

Now set

\[ v(x) = p(x) + c_0\varepsilon(w(x) - 1), \quad x \in B_{3/4}(\bar{x}), \]
and for $t \geq 0$,
\[ u_t(x) = v(x) + t, \quad x \in \overline{B}_{3/4}(\bar{x}). \]

Notice that,
\[ \sum_{ij} a_{ij}(x)(v_t)_{ij} \geq c_0 \delta \varepsilon > \varepsilon^2 \quad \text{in } A. \]

According to (3.7) and the definition of $v_t$ we have,
\[ v_0(x) = v(x) \leq p(x) \leq u(x), \quad x \in \overline{B}_{3/4}(\bar{x}). \]

Let $\tilde{t}$ be the largest $t \geq 0$ such that
\[ v_t(x) \leq u(x) \quad \text{in } \overline{B}_{3/4}(\bar{x}). \]

We want to show that $\tilde{t} \geq c_0 \varepsilon$. Then, using the definition (3.11) of $v(x)$ we get
\[ u(x) \geq v(x) + \tilde{t} \geq p(x) + c_0 \varepsilon w(x) \]
and hence, since on $\overline{B}_{1/2} \subset B_{3/4}(\bar{x})$ one has $w(x) \geq c_2$ for some universal constant $c_2$, we obtain that
\[ u(x) - p(x) \geq c \varepsilon \quad \text{on } \overline{B}_{1/2} \]
as desired.

Suppose $\tilde{t} < c_0 \varepsilon$. Then at some $\hat{x} \in \overline{B}_{3/4}(\bar{x})$ we have
\[ v_t(\hat{x}) = u(\hat{x}). \]

We show that such touching point can only occur on $\overline{B}_{1/20}(\bar{x})$. Indeed, since $w \equiv 0$ on $\partial B_{3/4}(\bar{x})$ from the definition of $v_t$ we get
\[ v_t(x) = p(x) - c_0 \varepsilon + \tilde{t} \quad \text{on } \partial B_{3/4}(\bar{x}). \]

Using that $\tilde{t} < c_0 \varepsilon$ together with the fact that $u \geq p$ we then obtain
\[ v_t < u \quad \text{on } \partial B_{3/4}(\bar{x}). \]

We now show that $\hat{x}$ cannot belong to the annulus $A$. As already observed,
\[ \sum_{ij} a_{ij}(x)(v_t)_{ij} \geq \varepsilon^2, \quad \text{in } A \]
and also
\[ (3.12) \quad |\nabla v_t| \geq |v_n| = 1 + c_0 \varepsilon w_n, \quad \text{in } A. \]

We claim that
\[ w_n(x) \geq c_1 \quad \text{on } \{v_t \leq 0\} \cap A, \]
for a universal constant $c_1$.

Indeed, since $w$ is radially symmetric,
\[ w_n(x) = |\nabla w(x)| \nu_x \cdot e_n, \quad x \in A \]
where $\nu_x$ is the unit direction of $x - \bar{x}$. Clearly from the formula for $w$ we get that $|\nabla w| > c$ on $A$. Also, $\nu_x \cdot e_n$ is bounded below in the region $\{v_t \leq 0\} \cap A$, since for $\varepsilon$ small enough
\[ \{v_t \leq 0\} \cap A \subset \{p \leq c_0 \varepsilon\} = \{x_n \leq -\sigma + c_0 \varepsilon\} \subset \{x_n < 3/20\}, \]
and $\bar{x} = 1/5 e_n$.

Hence, from (3.12) we deduce that
\[ |\nabla v_t| \geq 1 + c_2 \varepsilon, \quad \text{on } \{v_t \leq 0\} \cap A. \]
In particular, for $\varepsilon$ small enough and in view of the second inequality in (3.2),

$$|\nabla v_{\tilde{t}}|(x) > 1 + \varepsilon^2 \geq g(x) \quad \text{for } x \in A \cap F(v_{\tilde{t}}).$$

Thus, $v_{\tilde{t}}$ is a strict subsolution to (3.1) in $A$ and according to Lemma 2.4 since $u$ solves (3.1) in $B_1$, $\tilde{x}$ cannot belong to $A$. Therefore, $\tilde{x} \in B_{1/20}(\bar{x})$ and

$$u(\tilde{x}) = v_{\tilde{t}}(\tilde{x}) \leq p(\tilde{x}) + \bar{\ell} < p(\tilde{x}) + c_0 \varepsilon,$$

which implies

$$u(\tilde{x}) - p(\tilde{x}) < c_0 \varepsilon$$

contradicting (3.10).

The proof of the second statement follows from a similar argument. □

We are now ready to give the proof of the Harnack inequality.

**Proof of Theorem 3.1.** Assume without loss of generality,

$$x_0 = 0, \quad r = 1.$$

According to (3.3),

$$p(x)^+ \leq u(x) \leq (p(x) + \varepsilon)^+ \quad \text{in } B_1,$$

with $p(x) = x_n + a_0$. If $|a_0| < 1/10$ then we can apply the previous Lemma 3.3 and the desired statement immediately follows.

Suppose not. If $a_0 < -1/10$, then (for $\varepsilon$ small) 0 belongs to the zero phase of $(p(x) + \varepsilon)^+$ which implies that 0 also belongs to the zero phase of $u$, a contradiction.

If $a_0 > 1/10$ then $B_{1/10} \subset B_1^+(u)$, and the conclusion follows by the classical Harnack inequality in $B_{1/10}$ as long as $\varepsilon$ is small enough. □

### 4. Improvement of Flatness

In this section we present the main “improvement of flatness” lemma, from which the proof of Theorem 1.1 will easily follow via an iterative argument.

**Lemma 4.1** (Improvement of flatness). Let $u$ be a solution to (3.1)-(3.2) in $B_1$ satisfying

$$(x_n - \varepsilon)^+ \leq u(x) \leq (x_n + \varepsilon)^+ \quad \text{for } x \in B_1,$$

with $0 \in F(u)$.

If $0 < r \leq r_0$ for $r_0$ a universal constant and $0 < \varepsilon \leq \varepsilon_0$ for some $\varepsilon_0$ depending on $r$, then

$$(x \cdot \nu - \frac{\varepsilon}{2})^+ \leq u(x) \leq (x \cdot \nu + \frac{\varepsilon}{2})^+ \quad \text{for } x \in B_r,$$

with $|\nu| = 1$, and $|\nu - e_n| \leq C \varepsilon^2$ for a universal constant $C$.

**Proof.** We divide the proof of this Lemma into 3 steps. We use the following notation:

$$\Omega_{r_0}(u) := (B_1^+(u) \cup F(u)) \cap B_{r_0}.$$

**Step 1 – Compactness.** Fix $r \leq r_0$ with $r_0$ universal (the precise $r_0$ will be given in Step 3). Assume by contradiction that we can find a sequence $\varepsilon_k \to 0$ and
a sequence \( u_k \) of solutions to (3.1) in \( B_1 \) with coefficients \( a_{ij}^k \), right hand side \( f_k \) and free boundary condition \( g_k \) satisfying (3.2), such that \( u_k \) satisfies (4.1), i.e.

\[
(x_n - \varepsilon_k)^+ \leq u_k(x) \leq (x_n + \varepsilon_k)^+ 
\]

for \( x \in B_1, \ 0 \in F(u_k) \),

but it does not satisfy the conclusion (4.2) of the lemma.

Set,

\[
\tilde{u}_k(x) = \frac{u_k(x) - x_n}{\varepsilon_k}, \ x \in \Omega_1(u_k).
\]

Then (4.3) gives,

\[
-1 \leq \tilde{u}_k(x) \leq 1 \quad \text{for} \ x \in \Omega_1(u_k).
\]

From Corollary 3.2, it follows that the function \( \tilde{u}_k \) satisfies

\[
|\tilde{u}_k(x) - \tilde{u}_k(y)| \leq C|x - y|, \quad \text{for} \ C \ \text{universal and}
\]

\[
|x - y| \geq \varepsilon_k/\bar{\varepsilon}, \ x, y \in \Omega_{1/2}(u_k).
\]

From (4.3) it clearly follows that \( F(u_k) \) converges to \( B_1 \cap \{x_n = 0\} \) in the Hausdorff distance. This fact and (4.5) together with Ascoli-Arzela give that as \( \varepsilon_k \to 0 \) the graphs of the \( \tilde{u}_k \) over \( \Omega_{1/2}(u_k) \) converge (up to a subsequence) in the Hausdorff distance to the graph of a Hölder continuous function \( \tilde{u} \) over \( B_{1/2} \cap \{x_n \geq 0\} \).

**Step 2 – Limiting Solution.** We now show that \( \tilde{u} \) solves

\[
\begin{cases}
\Delta \tilde{u} = 0 & \text{in} \ B_{1/2} \cap \{x_n > 0\}, \\
\tilde{u}_n = 0 & \text{on} \ B_{1/2} \cap \{x_n = 0\},
\end{cases}
\]

in the sense of Definition 2.5

Let \( P(x) \) be a quadratic polynomial touching \( \tilde{u} \) at \( \bar{x} \in B_{1/2} \cap \{x_n \geq 0\} \) strictly by below. We need to show that

(i) if \( \bar{x} \in B_{1/2} \cap \{x_n > 0\} \) then \( \Delta P \leq 0 \); 

(ii) if \( \bar{x} \in B_{1/2} \cap \{x_n = 0\} \) then \( P_n(\bar{x}) \leq 0 \).

Since \( \tilde{u}_k \to \tilde{u} \) in the sense specified above, there exist points \( x_k \in \Omega_{1/2}(u_k) \), \( x_k \to \bar{x} \), and constants \( c_k \to 0 \) such that

\[
P(x_k) + c_k = \tilde{u}_k(x_k)
\]

and

\[
\tilde{u}_k \geq P + c_k \quad \text{in a neighborhood of} \ x_k.
\]

From the definition of \( \tilde{u}_k \), (4.7) and (4.8) read as

\[
u_k(x_k) = Q(x_k)
\]

and

\[
u_k(x) \geq Q(x) \quad \text{in a neighborhood of} \ x_k
\]

where

\[
Q(x) = \varepsilon_k(P(x) + c_k) + x_n.
\]

We now distinguish the two cases.
Thus, in view of the last inequality in (3.2), we can assume that $\Delta P > x$.
Passing to the limit as $k \to \infty$ we get,
\[ \Delta P = \sum_{i,j} (\delta_{ij} - a_{ij}^k(x_k))P_{ij} + \sum_{i,j} a_{ij}^k(x_k)P_{ij} \leq C \varepsilon_k. \]
Passing to the limit as $k \to +\infty$ we obtain that $\Delta P \leq 0$ as desired.

(ii) If $\bar{x} \in B_{1/2} \cap \{x_n = 0\}$, as observed in the Remark following Definition 2.5, we can assume that $\Delta P > 0$. We claim that for $k$ large enough, $x_k \in F(\underline{u})$. Otherwise $x_{k_n} \in B_1^+(\underline{u}_{k_n})$ for a subsequence $k_n \to \infty$ and as in the case (i),
\[ \Delta P \leq C \varepsilon_{k_n}. \]
Letting $k_n \to \infty$ we contradicts the fact that $P$ is strictly subharmonic. Thus $x_k \in F(\underline{u}_k)$ for $k$ large. Now notice that
\[ \nabla Q = \varepsilon_k \nabla P + e_n \]
thus, for $k$ large, $|\nabla Q| > 0$. Since $Q^+$ touches $\underline{u}_k$ by below,
\[ |\nabla Q| (x_k) \leq g_k(x_k) \leq 1 + \varepsilon_k^2, \]
which gives,
\[ |\nabla Q|^2 (x_k) = \varepsilon_k^2 |\nabla P|^2 (x_k) + 1 + 2 \varepsilon_k P_n(x_k) \leq 1 + 3 \varepsilon_k^2, \]
and thus (after division by $\varepsilon_k$)
\[ \varepsilon_k |\nabla P|^2 (x_k) - 3 \varepsilon_k + 2 P_n(x_k) \leq 0. \]
 Passing to the limit as $k \to +\infty$ we obtain
\[ P_n (\bar{x}) \leq 0 \]
as desired.

**Step 3 – Improvement of flatness.** From the previous step, $\tilde{u}$ solves (1.6) and from (1.4),
\[ -1 \leq \tilde{u} \leq 1 \text{ in } B_{1/2} \cap \{x_n \geq 0\}. \]
From Lemma 2.9 and the bound above we obtain that, for the given $r$,\[ |\tilde{u}(x) - \tilde{u}(0) - \nabla \tilde{u}(0) \cdot x| \leq C_0 r^2 \text{ in } B_r \cap \{x_n \geq 0\}, \]
fors a universal constant $C_0$. In particular, since $0 \in F(\tilde{u})$ and also $\tilde{u}_n(0) = 0$, we obtain
\[ x' \cdot \tilde{v} - C_0 r^2 \leq \tilde{u}(x) \leq x' \cdot \tilde{v} + C_0 r^2 \text{ in } B_r \cap \{x_n \geq 0\}, \]
with $\tilde{v}_i = \tilde{u}_i(0), i = 1, \ldots, n-1, |\tilde{v}| \leq \tilde{C}, \tilde{C}$ universal constant. Therefore, for $k$ large enough we get,
\[ x' \cdot \tilde{v} - C_1 r^2 \leq \tilde{u}_k(x) \leq x' \cdot \tilde{v} + C_1 r^2 \text{ in } \Omega_r(\underline{u}_k). \]
From the definition of $\tilde{u}_k$ the inequality above reads
\[ \varepsilon_k x' \cdot \tilde{v} + x_n - \varepsilon_k C_1 r^2 \leq u_k \leq \varepsilon_k x' \cdot \tilde{v} + x_n + \varepsilon_k C_1 r^2 \text{ in } \Omega_r(\underline{u}_k). \]
Call \[ \nu = \frac{\langle \varepsilon_k \nu, 1 \rangle}{\sqrt{\varepsilon_k^2 + 1}}. \]

Since, for \( k \) large,
\[ 1 \leq \sqrt{\varepsilon_k^2 + 1} \leq 1 + \frac{\varepsilon_k^2}{2}, \]
we deduce from (4.9) that
\[ x \cdot \nu - \frac{\varepsilon_k r}{2} - C_1 r^2 \varepsilon_k \leq u_k \leq x \cdot \nu + \frac{\varepsilon_k r}{2} - C_1 r^2 \varepsilon_k \quad \text{in} \quad \Omega_r(u_k). \]

In particular, if \( r_0 \) is such that \( C_1 r_0 \leq 1/4 \) and also \( k \) is large enough so that \( \varepsilon_k \leq 1/2 \) we obtain
\[ x \cdot \nu - \frac{\varepsilon_k r}{2} \leq u_k \leq x \cdot \nu + \frac{\varepsilon_k r}{2} \quad \text{in} \quad \Omega_r(u_k), \]
which together with (4.3) implies that
\[ (x \cdot \nu - \frac{\varepsilon_k r}{2})^+ \leq u_k \leq (x \cdot \nu + \frac{\varepsilon_k r}{2})^+ \quad \text{in} \quad B_r. \]

Thus the \( u_k \) satisfy the conclusion of the lemma, and we reached a contradiction. \( \Box \)

5. The proofs of Theorem 1.1 and Theorem 1.2

In this section we finally present the proof of our main theorems.

**Proof of Theorem 1.1** Let \( u \) be a viscosity solution to (1.1) in \( B_1 \), with \( 0 \in F(u), g(0) = 1 \) and \( a_{ij}(0) = \delta_{ij} \). Consider the sequence of rescalings
\[ u_k(x) := \frac{u(\rho_k x)}{\rho_k}, \quad x \in B_1, \]
with \( \rho_k = \bar{r}^k \), \( k = 0, 1, \ldots \), for a fixed \( \bar{r} \) such that
\[ \bar{r}^\beta \leq 1/4, \quad \bar{r} \leq r_0, \]
with \( r_0 \) the universal constant in Lemma 4.1.

Each \( u_k \) solves (1.1) in \( B_1 \) with coefficients \( a_{ij}^k(x) = a_{ij}(\rho_k x) \), right hand side \( f_k(x) := \rho_k f(\rho_k x) \), and free boundary condition \( g_k(x) := g(\rho_k x) \). For the chosen \( \bar{r} \), by taking \( \varepsilon = \varepsilon_0(\bar{r})^2 \) the assumption (4.2) holds for \( \varepsilon = \varepsilon_k := 2^{-k-1}(\varepsilon_0(\bar{r})) \). Indeed, in \( B_1 \), in view of (1.3),
\[ |f_k(x)| \leq \|f\|_{L^\infty} \rho_k \leq \bar{r}^k \leq \varepsilon_k^2, \]
\[ |g_k(x) - 1| = |g(\rho_k x) - g(0)| \leq |g|_{0, \beta} \rho_k^\beta \leq \bar{r}^{k\beta} \leq \varepsilon_k^2, \]
and
\[ |a_{ij}^k(x) - \delta_{ij}| = |a_{ij}(\rho_k x) - a_{ij}(0)| \leq |a_{ij}|_{0, \beta} \rho_k^\beta \leq \bar{r}^{k\beta} \leq \varepsilon_k. \]

The hypothesis (1.2) guarantees that for \( k = 0 \) also the flatness assumption (4.1) in Lemma 4.1 is satisfied by \( u_0 \). Then, it easily follows by induction on \( k \) and Lemma 4.1 that each \( u_k \) is \( \varepsilon_k \)-flat in \( B_1 \) in the sense of (4.1). Now, a standard iteration argument gives the desired statement. \( \Box \)

**Proof of Theorem 1.2** Let \( u \) be a viscosity solution to (1.1), with \( 0 \in F(u) \) and \( g(0) > 1 \). Without loss of generality, assume \( g(0) = 1 \). Also, for simplicity we take \( a_{ij}(0) = \delta_{ij} \).
Consider the blow-up sequence
\[ u_k := u_{\delta_k}(x) = \frac{u(\delta_k x)}{\delta_k}, \]
with \( \delta_k \to 0 \) as \( k \to \infty \). As in the previous theorem, each \( u_k \) solves (1.1) with coefficients \( a_k(x) = a_{ij}(\delta_k x) \), right hand side \( f_k(x) := \delta_k f(\delta_k x) \), and free boundary condition \( g_k(x) := g(\delta_k x) \). For \( k \) large, the assumption (1.3) is satisfied for the universal constant \( \bar{\varepsilon} \). In fact, in \( B_1 \)
\[
|f_k(x)| = \delta_k |f(\delta_k x)| \leq \delta_k \|f\|_{L^\infty} \leq \bar{\varepsilon}
\]
\[
|g_k(x) - 1| = |g_k(x) - g(0)| \leq |g_k|_{0,\beta} = \delta_k^2 |g|_{0,\beta} \leq \bar{\varepsilon},
\]
and
\[
|a_{ij}(x) - \delta_{ij}| = |a_{ij}(\delta_k x) - a_{ij}(0)| \leq |a_{ij}(\delta_k x)|_{0,\beta} = \delta_k^2 |a_{ij}|_{0,\beta} \leq \bar{\varepsilon}.
\]
Thus, using non-degeneracy and uniform Lipschitz continuity of the \( u_k \)'s (see Appendix for a proof of these properties), standard arguments (see for example [AC]) give that (up to extracting a subsequence):

(i) \( u_k \to u_0 \) in \( C^{0,\alpha}_{loc}(\mathbb{R}^n) \), for all \( 0 < \alpha < 1 \);
(ii) \( \partial\{u_k > 0\} \to \partial\{u_0 > 0\} \) locally in the Hausdorff distance;

for a globally defined function \( u_0 : \mathbb{R}^n \to \mathbb{R} \). The blow-up limit \( u_0 \) is a global solution to the free boundary problem
\[
\begin{align*}
\Delta u_0 &= 0, \quad \text{in } \{u_0 > 0\}, \\
|\nabla u_0| &= 1, \quad \text{on } F(u_0),
\end{align*}
\]
and since \( F(u) \) is a Lipschitz graph in a neighborhood of 0 we also have from (i)-(ii) that \( F(u_0) \) is Lipschitz continuous. Thus, it follows from [C1] that \( u_0 \) is a so-called one-plane solution, i.e. (up to rotations) \( u_0 = x_n^+ \). Combining the facts above, one concludes that for all \( k \) large enough, \( u_k \) is \( \bar{\varepsilon} \)-flat say in \( B_1 \) i.e.
\[
(x_n - \bar{\varepsilon})^+ \leq u_k(x) \leq (x_n + \bar{\varepsilon})^+, \quad x \in B_1.
\]
Thus \( u_k \) satisfies the assumptions of Theorem 1.1 and our conclusion follows. \( \square \)

6. APPENDIX

We sketch here the proof of a standard result that is Lipschitz continuity and non-degeneracy of a solution \( u \) to
\[
\begin{align*}
\sum_{i,j} a_{ij}(x) u_{ij} &= f, \quad \text{in } \Omega^+(u) := \{x \in \Omega : u(x) > 0\}, \\
|\nabla u| &= g, \quad \text{on } F(u) := \partial\Omega^+(u) \cap \Omega,
\end{align*}
\]
under the assumption \( 0 < \varepsilon < 1 \)
\[
\|f\|_{L^\infty(\Omega)} \leq \varepsilon^2, \quad \|g(x) - 1\|_{L^\infty(\Omega)} \leq \varepsilon^2, \quad \|a_{ij} - \delta_{ij}\|_{L^\infty(\Omega)} \leq \varepsilon.
\]

**Lemma 6.1.** Let \( u \) be a solution to (6.1)-(6.2) with \( \varepsilon \leq \bar{\varepsilon} \) a universal constant. If \( F(u) \cap B_1 \neq \emptyset \) and \( F(u) \) is a Lipschitz graph in \( B_2 \), then \( u \) is Lipschitz and non-degenerate in \( B_1^+(u) \) i.e.
\[
c_0 d(z) \leq u(z) \leq C_0 d(z) \quad \text{for all } z \in B_1^+(u),
\]
with \( d(z) = \text{dist}(z, F(u)) \) and \( c_0, C_0 \) universal constants.
Proof. Assume without loss of generality that $0 \in B_1^+(u)$ and call $d := d(0)$.

Consider the rescaled function

$$\tilde{u}(x) = \frac{u(dx)}{d}, \quad x \in B_1.$$ 

Clearly $\tilde{u}$ still satisfies (1.1) in $B_1$ with coefficients $\tilde{a}_{ij}(x) = a_{ij}(dx)$, right hand side $\tilde{f}(x) = df(dx)$ and free boundary condition $\tilde{g}(x) = g(dx)$. Since $d \leq 1$, the assumption (3.2) holds. We wish to show that

$$c_0 \leq \tilde{u}(0) \leq C_0.$$ 

Assume by contradiction that $\tilde{u}(0) > C_0$, with $C_0$ to be made precise later.

To construct a subsolution, we use the same function as in Lemma 3.3. Precisely,

let

$$G(x) = C(|x|^{-\gamma} - 1)$$

be defined on the closure of the annulus $B_1 \setminus B_{1/2}$. In view of the uniform ellipticity of the coefficients, we can choose $\gamma$ large universal so that (for $\varepsilon$ small)

$$\sum_{ij} \tilde{a}_{ij} G_{ij} > \varepsilon^2 \quad \text{on} \quad B_1 \setminus B_{1/2}$$

and we can choose $C$ so that

$$G = 1 \quad \text{on} \quad \partial B_{1/2}.$$ 

By Harnack inequality (see (3.9)), using the contradiction hypothesis we get (for $\varepsilon$ small)

$$\tilde{u} \geq c\tilde{u}(0) \quad \text{on} \quad B_1 \setminus B_{1/2}.$$ 

Thus, by the maximum principle

$$\tilde{u}(x) \geq v(x) = c\tilde{u}(0)G(x) \quad \text{on} \quad B_1 \setminus B_1/2.$$ 

Hence at the point $z$ where $d(0)$ is achieved we have

$$|\nabla v|(z) \leq g(z) \leq 1 + \varepsilon^2 \leq 2$$

which contradicts $\tilde{u}(0) > C_0$ if $C_0$ is large enough.

To prove the lower bound, let

$$\tilde{G}(x) = \eta(1 - G(x))$$

with $\eta$ (depending on $\gamma$) such that

$$|\nabla \tilde{G}| < 1 - \varepsilon^2 \quad \text{on} \quad \partial B_{1/2}.$$ 

Assume without loss of generality that $F(u)$ is a Lipschitz graph in the $x_n$ direction with Lipschitz constant equal to 1. We translate the graph of $\tilde{G}$ by $-4e_n$. Notice that it is above the graph of $\tilde{v}$ since $\tilde{u} \equiv 0$ in $B_1(-4e_n)$. We slide the graph of $\tilde{G}$ in the $e_n$ direction till we touch the graph of $\tilde{u}$. Since $\tilde{G}$ is a strict supersolution to our free boundary problem, the touching point $\tilde{z}$ can occur only on the $\eta$ level set with $\tilde{d} := d(\tilde{z}, F(u)) \leq 1$. From the first part, $\tilde{u}$ is Lipschitz continuous and hence $\tilde{u}(\tilde{z}) = \eta \leq C\tilde{d}$. Thus

$$C^{-1}\eta \leq \tilde{d} \leq 1$$

that is $\tilde{d}$ is comparable to 1. Since $F(u)$ is Lipschitz we can connect 0 and $\tilde{z}$ with a chain of intersecting balls included in the positive side of $\tilde{u}$ with radii comparable
to 1. The number of balls is bounded by a universal constant. Then we can apply Harnack inequality and obtain (for $\varepsilon$ small)

$$\tilde{u}(0) \geq c\tilde{u}(\tilde{z}) = c_0,$$

as desired. $\square$

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