Ambient Air Quality Measurement with Low-Cost Optical and Electrochemical Sensors: An Evaluation of Continuous Year-Long Operation

Jiří Bílek, Ondřej Bílek, Petr Maršolek and Pavel Buček *

Institute of Environmental Technology, Energy and Environmental Technology Centre, VSB-Technical University of Ostrava, 17. Listopadu 2172/15, 708 00 Ostrava, Czech Republic; jiri.bilek@vsb.cz (J.B.); ondrej.bilek@vsb.cz (O.B.); petr.marsolek@vsb.cz (P.M.)
* Correspondence: pavel.bucek@vsb.cz

Abstract: Sensor technology is attractive to the public due to its availability and ease of use. However, its usage raises numerous questions. The general trustworthiness of sensor data is widely discussed, especially with regard to accuracy, precision, and long-term signal stability. The VSB-Technical University of Ostrava has operated an air quality sensor network for more than two years, and its large sets of valid results can help in understanding the limitations of sensory measurement. Monitoring is focused on the concentrations of dust particles, NO$_2$, and ozone to verify the impact of newly planted greenery on the reduction in air pollution. The sensor network currently covers an open field on the outskirts of Ostrava, between Liberty Ironworks and the nearby ISKO1650 monitoring station, where some of the worst air pollution levels in the Czech Republic are regularly measured. In the future, trees should be allowed to grow over the sensors, enabling assessment of the green barrier effect on air pollution. As expected, the service life of the sensors varies from 1 to 3 years; therefore, checks are necessary both prior to the measurement and regularly during operation, verifying output stability and overall performance. Results of the PMx sensory measurements correlated well with the reference method. Concentration values measured by NO$_2$ sensors correlated poorly with the reference method, although timeline plots of concentration changes were in accordance. We suggest that a comparison of timelines should be used for air quality evaluations, rather than particular values. The results showed that the sensor measurements are not yet suitable to replace the reference methods, and dense sensor networks proved useful and robust tools for indicative air quality measurements (AQM).

Keywords: sensor; electrochemical sensors; air quality; PM10 particulate matter; inhalable particles; air pollution

1. Introduction

The development of low-cost electrochemical and optical sensors has been very dynamic in recent years. Their use is becoming easier, and possible applications are constantly growing, including in the field of air quality measurements. The rise in sensor technology has changed the approach to monitoring a wide range of air pollutants, allowing for fast online measurements in dense networks [1,2]. Due to their reducing price, air quality measurement technology has become more widely available. Despite the widespread use of sensors, there is a lack of information on measurement validity [3], and due to rapid evolution, there is a lack of information on long-term behavior. The first step discussed is sensor validation, i.e., the correct setting [4], because of direct calibration, as understood for reference methods, is usually not possible. Although comparisons under identical or rather similar conditions are feasible [5–7], validation routines should ideally comprise parallel measurements according to the standards for equivalence tests [8] or simultaneous closed
chamber measurements of both sensors and calibrated reference instruments. Sensors usually require very low air flow—some are even capable of passive measurements—although reference devices require an air flow of 20–40 L per minute. In the case of a particle monitor equipped with a PM$_{10}$ sampling head, the required air flow could even be up to 300 L per minute. For the 24-h test, stable and homogeneous conditions were required in a volume greater than 7 m$^3$. In closed chambers, a homogeneous atmosphere is expected, but larger rooms are favorable because the mutual influence of the respective devices decreases with size. Thus, a 100 m$^3$ room suits such an experiment better than an 8 m$^3$ box. The values presented reflect the unsuitability of a defined dust chamber and the calibration method for optical particle counting using electronic controls of the distribution function.

Another serious problem is the lack of real applications that use long-term sensory measurements (e.g., one year or more). Such a long period of operation is necessary for checking the useful lifetime of the sensors and proves the stability of the preset calibration. It is obvious that depletion of the active elements or the change in lighting characteristics reduce the sensors’ sensitivity; however, little is known about the conditions that lead to decreased sensitivity and the effects on the measurements, hence affecting data interpretation. The authors’ team at the Institute of Environmental Technology has been operating a sensor network for continuous air quality measurements for 18 months, and even longer in some locations. The particulate matter and NOx concentration values provided by the sensors in 5-min intervals are stored in a database that currently contains more than three million data rows collected over the measurement period, enabling statistical data analysis. Interpretation of the results can reveal answers to questions raised and evaluate the operating characteristics of sensors.

The mass production of sensors has decreased in price, meaning they can be purchased and used by the general public, and often those without deeper knowledge of air quality monitoring, statistics, or sensor technology in the form of simple plug-and-play devices. Nevertheless, even in these cases, the sensors produce results that may be publicly presented or campaigned without responsibility for the results.

The aim of this paper is not to present a statistic evaluation of the complete dataset. Rather, the focus is on the characterization of sensory measurements and comparisons of the units used among each other. The hypothesis subject to verify is whether optical PM$_x$ and electrochemical NO$_2$ sensors can be used continuously for a period of 12 months, and to what extent the original (pre-set by manufacturer) calibration functions are useful throughout the measurement period as well as to help establish levels of confidence towards sensory air quality measurements and the produced data.

2. Experimental Section

2.1. Sensor Network and Measurement Location

The sensor units in protective boxes were fitted to poles approximately 4 m above the ground level, and the distance of units from each other was roughly 10 m. The 11-unit cluster subject to evaluation occupied an area of approximately 70 m $\times$ 70 m (Figure 1c) at one end of the urban Radvanice district in the south-eastern corner of the city of Ostrava, near smelter and ironworks facilities. The Radvanice district and surroundings have steadily recorded some of the worst air quality data in the Czech Republic from the beginning of regular air quality monitoring; recently, experiments focused on improving air quality have been conducted within the CLAIRO project.

The cluster presents one part of a large, 60-unit sensor network that continuously measures the area (up to 31 July 2021, more than 18 months) to evaluate the state and changes in air quality before and after application of the experimental measures. All sensor units contained a manufacturer-calibrated Alphasense OPC-N3 dust sensor and a Cairns O$_3$/NO$_2$ sensor. In the initial phase of the measurements, and periodically throughout, the sensors were checked by reference measurements conducted on-site with a mobile air quality monitoring station. Based on the size of the area and location of the cluster,
a homogeneous distribution of pollutants and, thus, similar behavior for all the sensors were expected.

Identification codes were assigned to sensor units that consisted of the letters S or Stc and numbers (S or Stc labelled with the same number mark the same sensor unit, depending on the automatic format of data exported from the database). Sensor locations, layout, and identification are given in Figure 1c.

![Figure 1](image1.png)

**Figure 1.** Sensor network location: (a) monitored area within the city of Ostrava; (b) overview of the city quarters and the deployed sensor network; and (c) detail of the evaluated cluster of sensor units, their identification, and visualization of measured values.

### 2.2. Particulate Matter Sensor—Alphasense OPC-N3

The Alphasense OPC-N3 sensors used (Alphasense, Ltd., Braintree, UK) were optical particle counters, certified according to ISO 9001:2015, which measure PM$_1$, PM$_{2.5}$, and PM$_{10}$ using a pre-programed internal distribution function, changes of which are rather cumbersome [9]. Technical specifications [10] are presented in Table 1, and sensor appearance is presented in Figure 2a.

![Figure 2](image2.png)

**Figure 2.** External view of the (a) Alphasense OPC-N3 sensor, approximate dimensions of 75 × 64 × 60 mm and (b) the Cairsens© sensor, approximate dimensions of 65 mm length and 33 mm diameter, inserted view of the bottom part with air intake.

The output of the Alphasense OPC-N3 sensor is values in µg/m$^3$ which are logged in a Raspberry Pi control unit memory device and are regularly transferred as packages into the database.

Alphasense particulate matter sensors were calibrated against the FIDAS 200 optical particle counter (PALAS GMBH, Karlsruhe, Germany) as an equivalent method [8]. As
required by the standard, simultaneous measurements must last at least 24 h, and 5-min average values are used for comparison.

**Table 1.** Technical specifications of the Alphasense OPC-N3 sensor.

| Sensed Matter         | PM$_x$  |
|-----------------------|---------|
| Measured particle size| 0.35–40 µm |
| Number of size classes| 24       |
| Limit of detection    | <1 µg/m$^3$ |
| Measurement range     | 0–2000 µg/m$^3$ |
| Sensitivity           | <1 µg/m$^3$ |

**2.3. Ozone and Nitrous Oxide Combined Sensor Cairsens O$_3$/NO$_2$**

The Cairsens (Envea, Poissy, France) combined sensor uses a 3-electrode electrochemical system (working, auxiliary, and reference electrodes) (Envea, France; appearance of the sensor shown in Figure 2b). Gases of interest diffuse through a selective membrane towards the working electrode, and the signal produced is then directly proportional to the gas concentration (Table 2). The sensor is equipped with a filter that reduces the influence of humidity. As part of the Cairsens sensor family, sensors can be used for individual measurements (data are stored in internal memory) or connected to clusters with their respective control units.

**Table 2.** Technical specifications of the Cairsens© NO$_2$/O$_3$ sensor [11].

| Sensed Matter         | NO$_2$/O$_3$ |
|-----------------------|--------------|
| Limit of detection    | 20 ppb (vol) |
| Measurement range     | 0–250 ppb    |
| Sensitivity           | 1 ppb$^3$    |
| Uncertainty           | <30%         |
| Interferences         | Chlorine gas |

The producer calibrates the sensors, and the default output is produced in ppb (by volume), which needs further conversion to µg/m$^3$ for air quality monitoring. For reference measurements, the AC32e chemiluminescence-based NO/NO$_2$/NO$_X$ analyzer (Envea, Poissy, France) was used. Continuous parallel measurements were performed for 1 week, and 10-min average values were taken for statistical analysis.

**2.4. Statistics**

All statistical calculations were conducted with the StatPlus software (AnalystSoft, Inc., Walnut, CA, USA). The presented correlation coefficients were calculated as the Pearson correlation coefficient between two independent groups of variables (5-min averages for PM10 and 10-min averages for NO$_2$) of both measurement methods along the same time period.

Validation factors were determined from long-term averages as a coefficient applied to sensor results to match with reference measurement results over the same time period. Scatter plots were used for the visualization of the variable pairs. Reference method results were considered independent values, and sensory results as dependent variables for the comparisons. The scatter plots contain regression equations between independent and dependent variable sets and prediction lines based on them.

**3. Results and Discussion**

In the case of a 100% data yield, each of the sensors produced 8760 data points, corresponding to hourly averages and 105,120 5-min average values. The average yield of data throughout the monitored period was 97% for both PMx and NO$_2$ sensors. For statistical analysis purposes [12] and measurement stability verification, data from 11 sensor units
were used in the form of hourly averages calculated from 5-min average values stored in the database.

3.1. Suspended Particles PM$_{10}$

Table 3 presents the mean, median, and maximum values of all the sensors. The distribution of PM$_{10}$ values is characteristic for ambient air, presenting a lower median than the arithmetic average and a skewness of 1.99. PM$_{10}$ concentrations up to 40 µg/m$^3$ are most common in ambient air, as shown in Figure 3; the values presented as outliers in the box plot are not, in fact, outlying extremes, but valid values of episodes of high concentrations that can occur infrequently. However, it must be emphasized that the measurements did not take place in a closed or controlled environment. Only sensor S8 produced values lower than the overall average throughout the measurement. Although the recorded concentration values and their changes were less dynamic and the variance was lower, the statistical analysis did not reveal outlying values produced by that sensor, or any significant effect on the overall average value.

Table 3. Hourly average values of particulate matter recorded over the 1-year monitoring period.

| Sensor No. | Mean  | Median | Maximum |
|------------|-------|--------|---------|
| S4         | 28.09 | 22.45  | 233.09  |
| S6         | 27.72 | 21.54  | 210.69  |
| S7         | 31.84 | 25.09  | 236.38  |
| S8         | 23.87 | 19.98  | 165.32  |
| S10        | 27.84 | 20.46  | 234.66  |
| S12        | 30.04 | 21.12  | 282.82  |
| S15        | 33.84 | 26.11  | 222.28  |
| S17        | 27.87 | 20.49  | 223.86  |
| S19        | 30.57 | 25.11  | 214.19  |
| S23        | 27.72 | 20.49  | 223.86  |
| S25        | 32.76 | 26.72  | 212.88  |

Overall average value (all recorded values of all sensors): 29.29 ± 2.85.

![Figure 3](image-url)

Figure 3. Distribution of PM$_{10}$ values recorded throughout the year-long measurements: (a) box plot for individual sensors in the cluster and (b) histogram of hourly averages (overall averaged values of all sensors).

The correlation matrix in Table 4 lists all the relationships among the sensors in the group (55 values of correlation coefficients). The distribution of concentrations presented in Figure 3 confirms the very good correlation of all sensors in the cluster. Due to the large
number of results produced and the various conditions, the reliability of the sensors was tested for several concentration levels.

Table 4. Correlation matrix of all PM$_{10}$ data recorded by all sensors.

|       | R   | S4  | S6  | S7  | S8  | S10 | S12 | S15 | S17 | S19 | S23 | S25 |
|-------|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|
| S4    | 1.00|     |     |     |     |     |     |     |     |     |     |     |
| S6    | 0.69| 1.00|     |     |     |     |     |     |     |     |     |     |
| S7    | 0.71| 0.91| 1.00|     |     |     |     |     |     |     |     |     |
| S8    | 0.64| 0.85| 0.86| 1.00|     |     |     |     |     |     |     |     |
| S10   | 0.63| 0.75| 0.82| 0.68| 1.00|     |     |     |     |     |     |     |
| S12   | 0.62| 0.75| 0.81| 0.66| 0.94| 1.00|     |     |     |     |     |     |
| S15   | 0.78| 0.73| 0.75| 0.67| 0.64| 0.65| 1.00|     |     |     |     |     |
| S17   | 0.61| 0.70| 0.76| 0.59| 0.86| 0.89| 0.61| 1.00|     |     |     |     |
| S19   | 0.67| 0.88| 0.87| 0.85| 0.69| 0.70| 0.72| 0.72| 1.00|     |     |     |
| S23   | 0.83| 0.73| 0.75| 0.72| 0.62| 0.62| 0.75| 0.61| 0.74| 1.00|     |     |
| S25   | 0.70| 0.74| 0.77| 0.69| 0.64| 0.65| 0.61| 0.60| 0.72| 0.82| 1.00|     |

3.1.1. Low Concentration Level

A range of 1 to 10 µg/m$^3$ is considered a low concentration level of PM$_{10}$. The background level of PM$_{10}$ concentration in the Czech Republic generally exceeds 10 µg/m$^3$ [13]. Reaching such a level of PM$_{10}$ concentration is possible only in short periods of humid atmospheric conditions with precipitation, when the wet deposition of particles occurs. From the total number of 8580 hourly average values, only 856 values were below 10 µg/m$^3$.

Although the manufacturer states a lower limit of detection, measurements near the detection limit were impaired due to the lower sensitivity and higher imprecision. As suggested by the correlation matrix in Table 5, the robustness of sensor measurements at low concentration levels is significantly lower, even in clustered parallel measurements, when compared to overall averages. The correlation matrix contains over 50% of very poor values. The sensors have proven unreliable for the monitoring of low concentrations of PM$_{10}$. Nevertheless, low concentration levels of particles in ambient air do not impose health risks, nor contribute to air pollution; therefore, the effects on the overall results of air quality monitoring are minimized.

Table 5. Overview of correlation matrices among PM$_{10}$ sensors.

|       | R Absolute Value | Strength of Correlation | Overall | Low Concentrations (<10 µg/m$^3$) | Legislation Limit (10–100 µg/m$^3$) | High Concentrations (>100 µg/m$^3$) |
|-------|-----------------|-------------------------|---------|----------------------------------|-----------------------------------|-----------------------------------|
|       | 0.90–1.00       | Very high               | 2       | 14                               | 1                                 | 1                                 |
|       | 0.70–0.90       | High                    | 32      | 7                                | 41                                | 19                                |
|       | 0.50–0.70       | Moderate                | 21      | 7                                | -                                 | 12                                |
|       | 0.30–0.50       | Low                     | -       | 16                               | -                                 | 23                                |
|       | 0.00–0.30       | Little, if any          | -       | 25                               | -                                 | -                                 |
|       | Number of values in the group | | 8580 | 856                             | 7422                              | 302                               |
|       | Maximum R       |                          | 0.94    | 0.85                             | 0.97                              | 0.99                              |
|       | Minimum R       |                          | 0.59    | 0.03                             | 0.75                              | 0.3                               |

3.1.2. Legislative Concentration Level Limit

The European Union states the concentration limit of PM$_{10}$ in ambient air to be 50 µg/m$^3$ averaged over a 24-h measurement period, with a maximum of 35 episodes allowed to exceed the limit value [14]. The most common concentration of suspended particles in the Ostrava region ranged between 10 and 100 µg/m$^3$. Therefore, measurement reliability is required to be very high at this concentration level. There were 7422 hourly concentration values collected in the database in total. As shown in the correlation matrices (Table 5), correlation significantly increased in this range, showing that individual sen-
sors behaved similarly and produced similar results that can be considered reproducible and reliable.

3.1.3. Very High Concentration Level

Episodes of extreme concentrations of suspended particles in the air exceeding the double value of the stated limit at 100 µg/m³ regularly occur in the region. In the event of extremely unfavorable meteorological conditions, the PM$_{10}$ concentration can even reach up to an hourly average of 500 µg/m³ [13]. Sensors are not intended to be replacements of reference methods; therefore, regulation of the pollution sources based on their measurement is not possible. However, they should be capable of measurements at this concentration level. Table 6 lists the recorded episodes of PM$_{10}$ concentration levels exceeding 100 µg/m³ over the measurement period; the sensors did not indicate any false positive or false negative air quality situations. Although the correlation strength decreased in comparison to the midrange, the produced results are usable in general.

Table 6. Monthly overview of high concentration cases (PM$_{10}$ concentration exceeding an hourly average of 100 µg/m³).

| Month            | Number of Episodes |
|------------------|--------------------|
| October 2019     | 90                 |
| November 2019    | 107                |
| December 2019    | 18                 |
| January 2020     | 22                 |
| February 2020    | 8                  |
| March 2020       | 46                 |
| April 2020       | 9                  |
| May 2020         | 2                  |

3.1.4. Comparison with Reference Measurements

Both sensory and reference measurement data were transferred into a database, which is accessible online on the website www.airsens.eu (accessed on 10 May 2021). Raw measurement data were subject to correction that accounts for missing values (packets of data are mostly lost due to power shortages or problems with data transfer). Unpaired data were excluded to even pairs of data points in both groups. From the corrected 10-day average data, the validation factor was calculated as a coefficient for the sensor data to match the reference data (Table 7).

Table 7. Data used to determine the validation factor (sensor unit no. S25).

| PM$_{10}$ (µg/m³) | Alphasense S-25 | Reference FIDAS 200 | Validation Factor | Correlation Coefficient R |
|-------------------|-----------------|---------------------|-------------------|---------------------------|
| 24-h average      | 23.61           | 23.67               |                   |                           |
| 72-h average      | 25.33           | 23.46               |                   |                           |
| 240-h average     | 23.94           | 23.93               | 1.014             | 0.78                      |

Long-term data are presented in Figure 4, which shows a comparison of reference measurements (FIDAS 200) and a sensor unit.

Sensor data after correction were multiplied by the validation coefficient, and the linear regression between datasets was calculated (Figure 5). The correlation between the groups was strong, even though neither dataset was corrected for measurement conditions (relative humidity, temperature, etc.) that can lead to the over- or underestimation of sensor-measured values in comparison to the reference instrument [15,16].

All the PM$_{10}$ sensor units have been operating continuously for at least 18 months, including two winter seasons with no significant deterioration of measurement quality recorded so far.
Figure 4. Example of parallel 10-day measurements of PM$_{10}$ values measured by a sensor and a reference instrument (FIDAS 200); moving average values were offset by 40 µg/m$^3$.

Figure 5. Linear regression plot of reference measurement results (FIDAS 200). Measured and predicted sensory values according to regression equation are presented in the plot.

3.2. Nitrous Oxide NO$_2$

3.2.1. Sensory Measurements

Cairsens sensors provide the output of NO$_2$ concentration in ppb units; therefore, conversion to µg/m$^3$ is necessary before further operation. Statistical calculations were carried out with converted values using a factor of 1.882 (25 °C, 101.325 kPa). An overview of the measured concentrations is presented in Table 8.

Similarly to the PM$_{10}$ sensors, the group contained one sensor that provided lower values (S7) than the rest of the group; however, the statistical analysis did not prove the values to be outlying, so the results were considered valid and used further. Table 9 presents the correlation matrix among the sensors; in Figure 6, the distribution of the measured values is shown.
Table 8. Average hourly values of NO\textsubscript{2} concentration recorded over the 1-year monitoring period.

| Sensor No. | Mean | Median | Maximum |
|------------|------|--------|---------|
| S4         | 22.8 | 15.3   | 264.0   |
| S6         | 22.5 | 14.6   | 211.9   |
| S7         | 21.6 | 15.0   | 269.2   |
| S8         | 25.2 | 16.3   | 270.8   |
| S10        | 25.5 | 18.8   | 190.1   |
| S12        | 24.5 | 17.9   | 202.6   |
| S15        | 23.1 | 16.5   | 199.4   |
| S17        | 23.6 | 15.4   | 253.3   |
| S19        | 24.3 | 16.0   | 233.2   |
| S23        | 23.2 | 13.7   | 217.3   |
| S25        | 22.3 | 15.7   | 173.1   |

Table 9. Correlation matrix of sensor-measured NO\textsubscript{2} concentrations.

|   | S4 | S6 | S7 | S8 | S10 | S12 | S15 | S17 | S19 | S23 | S25 |
|---|----|----|----|----|-----|-----|-----|-----|-----|-----|-----|
| R |    |    |    |    |     |     |     |     |     |     |     |
| S4| 1.00|    |    |    |     |     |     |     |     |     |     |
| S6| 0.46| 1.00|    |    |     |     |     |     |     |     |     |
| S7| 0.51| 0.77| 1.00|    |     |     |     |     |     |     |     |
| S8| 0.46| 0.91| 0.78| 0.76| 1.00|     |     |     |     |     |     |
| S10| 0.44| 0.74| 0.91| 0.77| 1.00| 0.99| 1.00|     |     |     |     |
| S12| 0.46| 0.73| 0.89| 0.78| 0.99| 0.44| 0.48| 1.00|     |     |     |
| S15| 0.79| 0.43| 0.50| 0.51| 0.44| 0.48| 1.00| 0.62| 0.80| 0.86| 0.86| 0.47| 1.00|
| S17| 0.55| 0.62| 0.80| 0.63| 0.86| 0.86| 0.47| 1.00| 0.67| 0.69| 0.69| 0.45| 0.71| 1.00|
| S19| 0.55| 0.62| 0.80| 0.63| 0.86| 0.86| 0.47| 1.00| 0.67| 0.69| 0.69| 0.45| 0.71| 1.00|
| S23| 0.69| 0.30| 0.37| 0.35| 0.33| 0.35| 0.35| 0.65| 0.44| 0.44| 0.41| 0.41| 0.41| 1.00|
| S25| 0.58| 0.35| 0.43| 0.40| 0.39| 0.39| 0.39| 0.73| 0.38| 0.38| 0.31| 0.31| 0.87| 1.00|

Figure 6. Distribution of NO\textsubscript{2} values throughout the year-long measurement: (a) box plot for individual sensors and (b) histogram of hourly averages (overall averaged values of all sensors).

The correlations among some of the sensors are strong (35% of the coefficient values in the matrix are higher than 0.7), with most being low to moderate. Considering that there is no source of NO\textsubscript{2} in the surroundings of the cluster location, such as congested roads or large combustion sources, the measured NO\textsubscript{2} concentration was more stable than the PM\textsubscript{10} concentration. The shift in concentration towards lower values (below 10 µg/m\textsuperscript{3}) is characteristic of NO\textsubscript{2}.
3.2.2. Comparison with Reference Measurements

Sensory and reference measurement datasets underwent identical procedures (exclusion of unpaired values, calculation of validation coefficient using 10-day average, and linear regression), revealing that the linear correlation among the sensory data and reference instruments was very poor (Table 10, Figure 7), even though average values were similar and long-term timelines showed very similar trends (Figure 8).

Table 10. Data used to determine the validation factor (NO$_2$, sensor unit no. S25).

| NO$_2$ (µg/m$^3$) | Cairsens | Reference AC32e | Validation Factor | Correlation Coefficient R |
|------------------|----------|-----------------|-------------------|---------------------------|
| 24-h average     | 24.46    | 24.44           | -                 | -                         |
| 72-h average     | 23.38    | 22.78           | -                 | -                         |
| 240-h average    | 24.63    | 24.62           | 0.97              | 0.28                      |

Figure 7. Regression plot of reference (AC32) vs. sensor (S25) datasets.

The outputs of the NO$_2$ sensors were not corrected for any influences or interferences. Highly improved correlations between reference and sensory measurements are reported in studies after the introduction of correction functions (mainly correcting for influences of temperature and relative humidity, or duration of the operation period), using non-linear regression methods or artificial neural networks [17–19]. Although correlation based on linear regression methods is poor, all the studies cited mention the consistency of concentration trends in averaged periods over several minutes to hours. Similarly, differences between calibrations in controlled laboratory conditions and field measurements of ambient air are commonly described [19–24]. Measurements of the combined Cairns sensors were based on reactions of oxidizing gases, i.e., the sum of present NO$_2$, ozone, and interferences. In combined sensors, the electric signal from the sensing layer is always mathematically processed to produce NO$_2$ and ozone concentrations as the output. The computation can take place in the electronics of the dual-channel sensor assembly, or a single-channel output presents an input for the computation cascade in the data processing step.
Figure 8. Comparison of reference (AC32) and sensor (S25) data for NO2 over the 7-day measurement; moving average values are offset by 40 µg/m³.

3.3. Sensor Data-Based Network

Attempts to obtain additional and more detailed air quality data than may be supplied by the official air quality monitoring stations have been made ever since the start of AQM. Due to the price of the sensors, networks covering various areas can be easily established.

In our case, sensors were used as a source of complementary high-density data, based on the deployment of the sensor network. The data stored in the database could be visualized on a map, and the evolution and partial prediction of air pollution is possible. Figure 9 shows a model which is already in use with the data stored in the database that adds a colored layer over the map of the locations monitored by sensors, showing the current situation. In such cases, trends and changes in concentration values, as well as spatial and temporal resolution, are preferred over measurement precision and accuracy.

Figure 9. Visualized situation of the air quality based on NO2 sensor data: (a) low average concentrations in the area and (b) elevated concentrations of NO2.
4. Conclusions

The purpose of the study was to verify whether it is possible to continuously use optical PMx and electrochemical NO\textsubscript{2} sensors for 12 months, and to what extent the original calibration/setup is useful for the whole measurement period. Annual measurements proved that the sensor system arranged in a network is quite robust and stable. Although there were variations in the individual sensors for both PM\textsubscript{10} and NO\textsubscript{2}, there were no significant differences in the cluster.

In the case of PM\textsubscript{10}, some of the sensors revealed slower responses to changes in concentration (S4, S8, S25), although one of the sensors responded significantly faster (S17). Finally, all the sensor-produced data had very similar basic statistical characteristics, such as the mean, median, and maximum measured values. Thus, in the long term, they provide identical air quality data. The correlations show very good agreement among the individual sensors in the range of normal and high PM\textsubscript{10} concentrations. High agreement only decreases for low concentration levels, which scarcely occur and are not problematic from an air pollution and health risk point of view. Based on our results, Alphasense OPC-N3 sensors can also be utilized as single indicators in addition to their use in a network.

The characteristics of the NO\textsubscript{2} sensory measurements were poor using linear regression methods. Poor statistical parameters and correlations can be improved with the use of correction functions and/or more advanced data analysis methods. Dispersion of the measured values (dynamics) varied among the sensors, but basic parameters (maxima and average values) of individual sensors datasets were similar, as well as their trends and changes during the monitoring period. It can be summarized that differences among sensors can be compensated for with multiple units deployed in the cluster for parallel measurements.

For both types of sensors, it can be concluded that they are currently not suitable as a substitute for reference techniques, especially if one sensor is intended to replace one device.

However, the sensors are very suitable for monitoring trends and concentration changes in monitored pollutants when deployed in clusters and networks that provide high spatial and temporal resolution. The long-term usability was also proved by annual measurements. Although none of the sensor devices needed replacing, the quality of each individual device is important for both data quality and unit usability.

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