Superforms in six-dimensional superspace

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ABSTRACT: We investigate the complex of differential forms in curved, six-dimensional, $N = (1,0)$ superspace. The superconformal group acts on this complex by super-Weyl transformations. An ambi-twistor-like representation of a second conformal group arises on a pure spinor subspace of the cotangent space. The $p$-forms are defined by super-Weyl-covariant tensor fields on this pure spinor subspace. The on-shell dynamics of such fields is superconformal. We construct the superspace de Rham complex by successively obstructing the closure of forms. We then extend the analysis to composite forms obtained by wedging together forms of lower degree. Finally, we comment on applications to integration in curved superspace and propose a superspace formulation of the abelian limit of the non-abelian tensor hierarchy of $N = (1,0)$ superconformal models.

KEYWORDS: Superspaces, Differential and Algebraic Geometry, Extended Supersymmetry, Supergravity Models

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1 Introduction
The investigation of the structure of superforms is an important step toward understanding the geometry of the underlying superspace. Due to the interplay between the spinors and
tensors in such spaces, this structure is non-trivial even in the flat case. In the flat, four-dimensional, $N = 1$ superspace, this is textbook material (cf. section 4.4 of *Superspace* [1] and the original ref. [2]).

In flat, four-dimensional, $N = 2$ harmonic superspace a systematic analysis was carried out by Biswas and Siegel [3]. In curved superspaces or in flat superspace of dimensions other than four, partial results may be found throughout the literature, with interesting developments in four and five dimensions being reported as recently as last year [4–8]. Systematic studies of the closely related integral invariants in various dimensions are being carried out by Howe and his collaborators (e.g. ref. [9–11]). Many of these results have been extended to three, five, and six dimensions even more recently by Kuzenko and collaborators (see e.g. ref. [12–16]). In ten dimensions, composite forms and their couplings to supergravity in superspace were used early on to construct effective actions for massless string states (e.g. ref. [17–19]). With the advent of covariant superstrings, a systematic analysis for the forms arising in the pure spinor superspace was performed by Berkovits and Howe [20] (see also [10]).

A special place in the hierarchy of superspaces is occupied by six-dimensional, $N = (1, 0)$ Minkowski space as it has the largest isometry group compatible with the existence of eight real supercharges. The auxiliary field problem (that there are strictly more fermionic auxiliary fields required for off-shell closure than bosonic ones [21]) is solved by retaining an $S^2 \cong SU(2)_R/U(1)_R$ part of the $R$-symmetry group in the quotient construction [22, 23]. Closely related to this “harmonic” superspace is the “projective” superspace of [24–26]. The extension of this to curved, six-dimensional superspace was presented in [27] where certain super-Weyl-covariant field representations were defined and an action principle was proposed. In this work, we continue the exploration of this superspace by analyzing the structure of the complex of differential forms. Motivated by its interpretation as the target space for covariant heterotic strings compactified on K3 [36], we introduce formal variables generating an algebra isomorphic to the graded exterior algebra in section 2. This algebra has a subalgebra corresponding to the projection of a bosonic spinor $s \mapsto \lambda \otimes v$ to the product of a pure spinor $\lambda^\alpha$ and iso-twistor variable $v^i$. We show that the differential forms are naturally defined on this subalgebra. In section 3, we exploit the existence of the pure spinor subspace of differential forms to define super-Weyl covariant tensor fields and construct an ambi-twistor-like representation of the six-dimensional conformal group that acts on these tensor fields. The resulting *superconformal* field representations are subsequently used in section 4 to derive the superspace analogue of the de Rham complex. In section 5 we construct composite forms by wedging the various forms from section 4. In doing so, we are able to give a geometrical interpretation to certain multiplets constructed in [27]. Finally, we comment on some applications of the formalism in section 6. One of these is an attempt to reformulate the non-abelian tensor hierarchy [38–40], reviewed

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1 This extension to six dimensions is based on previous work in five dimensions [28–31] and below [32–35].

2 This complex was described recently as the Chevalley-Eilenberg complex of $p$-co-chains of the supersymmetry algebra with values in the space of superfields [8] (see also [7, 37]) where it was shown that the components and constraints have the interpretation of co-boundaries and co-homology, respectively, of the Chevalley-Eilenberg differential with values reduced to constant superfields.
in appendix B, in terms of a Chern-Simons theory on the ambi-twistor-like superspace of section 3. Additionally, since the Bianchi identity for the differential forms were solved in a curved background, this automatically determines the couplings of the abelian part of the tensor hierarchy to supergravity. Appendix A summarizes some results of reference [27] on curved, six-dimensional, $N = (1,0)$ superspace.

A note on notation. After careful consideration, we have decided to present our analysis (mostly) in an index-free notation because we are convinced that the benefits of doing so outweigh the risks. Firstly, this presentation most closely resembles our method of calculation and discovery and is useful in proofs. Secondly, the notation simplifies comparison to the covariant string theories and higher gauge theories to which it is closely related. Thirdly, we will need a representation of the conformal group defined in terms of these variables in order to build a certain differential complex of superfields in terms of which the $p$-form components are defined. Fourth, it is quite possible (and in fact happens in projective/harmonic and pure spinor theories) that some subset of these variables enters into the solution of constraints (such as those we will find) and/or the superspace measure when one attempts to define superinvariants by integration. Finally, the presentation of the resulting complex is more easily compared to the results on higher gauge theory existing in the literature. Conversely, using the more familiar, ordinary superspace notation would significantly complicate substantial parts of the presentation.

2 Closed superforms

In this section we write down the Bianchi identities for $p$-forms in six dimensions. We introduce some notation to simplify the calculations and find that the forms are supported on a certain subspace of the full cotangent space. Some results from reference [27] used in our calculations are summarized in appendix A.

A $p$-form $\omega$ is closed iff

$$d\omega = 0$$

where $d$ is given locally by $d\theta^\alpha_i \partial_{\alpha i} + dx^a \partial_a$. For notational convenience, we will replace the basis forms $d\theta^\alpha_i$ and $dx^a$ by new variables $s^\alpha_i$ and $\psi^a$. To automatically incorporate the super-anti-commutative nature of the wedge product, we take the $\{s^\alpha_i\}$ to be bosonic spinor variables and the $\{\psi^a\}$ to be fermionic vector variables

$$s^\alpha_i s^\beta_j = s^\beta_j s^\alpha_i, \quad s^\alpha_i \psi^a = \psi^a s^\beta_j, \quad \psi^a \psi^b = -\psi^b \psi^a.$$ (2.2)

The super-$p$-form $\omega = \sum_{s=0}^{p} \omega_{(s,p-s)}$ splits up as a sum of superfield components of degree $s|(p-s)^3$

$$\omega_{(s,p-s)} := \omega_{s...s}\psi...\psi := s^{\alpha_1 i_1} s^{\alpha_2 i_2} ... s^{\alpha_{p-s} i_{p-s}} \psi^{a_1} \psi^{a_2} ... \psi^{a_{p-s}} \omega_{\alpha_1 i_1...\alpha_{p-s} i_{p-s}}.$$ (2.3)

\(^3^3\)We are borrowing a compact, index-free notation from the theory of ordinary tensor fields on manifolds in which the subscript indicates the vector field on which the corresponding index is contracted (e.g. $\nabla_X$ for the directional derivative along the vector field $X$).
where the \( p \)-form components \( \omega_{\alpha_1 i_1 \ldots \alpha_p i_p} = \omega_{\alpha_1 i_1 \ldots \alpha_p i_p} (x, \theta) \) are ordinary \( N = (1, 0) \) superfields. The differential \( d \) splits into two differentials \( \partial_\theta \) and \( \partial_\psi \)

\[
d = \partial_\theta + \partial_\psi := s^{\alpha_1} \partial_{\alpha_1} + \psi^a \partial_a := s^{\alpha_1} \frac{\partial}{\partial \theta^{\alpha_1}} + \psi^a \frac{\partial}{\partial x^a},
\]
and the closure condition fans out into a collection of conditions respecting the grading by number of \( s^{\alpha_1} \)-type variables. Thus, the closure condition may be represented compactly as

\[
s! (d\omega)_{s s \ldots \psi \psi \ldots} = s \partial_\theta \omega_{s s \ldots \psi \psi \ldots} + (-1)^s (p + 1 - s) \partial_\psi \omega_{s s \ldots \psi \psi \ldots} = 0 \tag{2.5}
\]

with the \( s \) in front of the first term denoting the total number of \( s s \) in that term and with \( p \) denoting the total degree of the \( p \)-form \( \omega \).

The differentials \( \partial_\theta \) and \( \partial_\psi \) do not commute with supersymmetry transformations. To get supersymmetrically covariant \( p \)-form components, we must replace coordinate derivatives by supercovariant derivatives. In terms of flat supercovariant derivatives \( D_\theta \) and \( D_\psi = \partial_\psi \), the closure condition acquires a flat-space torsion term \( T_{s s}^a = 2 i s^a (\gamma^a)_{s s}^b s_b^i \):

\[
s D_\theta \omega_{s s \ldots \psi \psi \ldots} + (-1)^s (p + 1 - s) \partial_\psi \omega_{s s \ldots \psi \psi \ldots} - i (-1)^s s (s - 1) \omega_{s s \ldots s \gamma (s, s) \psi \psi} = 0, \tag{2.6}
\]

where the notation \( \omega_{\gamma (s, s)} \) is shorthand for the contraction of the null vector \( \gamma^a (s, s) := s^a \gamma^a s_1 \) on the component \( \omega_{a \ldots \gamma} \) (cf. (A.14)). In the curved superspace version of this closure relation, there are additional torsion terms.

\[
s D_\theta \omega_{s s \ldots \psi \psi \ldots} + (-1)^s (p + 1 - s) D_\psi \omega_{s s \ldots \psi \psi \ldots} - i (-1)^s s (s - 1) \omega_{s s \ldots s \gamma (s, s) \psi \psi} \\
+ (-1)^s s (p + 1 - s) T_{s \psi}^{\alpha_i \omega_{a i s} \ldots \psi \psi} - \frac{1}{2} (p + 1 - s) (p - s) T_{s \psi}^{\alpha_i \omega_{a i s} \ldots \psi \psi} = 0. \tag{2.7}
\]

These torsions, and the six-dimensional curved supergeometry in general, are reviewed in appendix A. In section 4 we will be solving this equation for each \( p = 1, \ldots, 6 \).

Superforms with no restrictions on their components yield reducible representations of the super-Poincaré algebra. Irreducible representations result by setting to zero one or more irreducible components. Once this is done, the closure conditions become non-trivial consistency conditions on the other components (e.g. all components of lower dimension are required to vanish). Following common superspace practice, we will refer to the resulting closure conditions as “Bianchi identities”. Thus, to begin solving the Bianchi identities of any particular \( p \)-form, we must locate the component of lowest engineering dimension that does not vanish.

Let \( n \) denote the largest value of \( s \) such that the \( s! (p - s) \)-component of the \( p \)-form \( \omega \) is non-vanishing. Then equation (2.7) simplifies to

\[
(n + 1) D_\theta \omega_{s s \ldots \psi \psi} = i (-1)^{s+1} n (n + 1) \omega_{s s \ldots s \gamma (s, s) \psi \psi}. \tag{2.8}
\]

\(^4\)Whenever we use the letter \( s \) for a number, we mean the number of \( s^{\alpha_1} \)-type variables appearing in the relevant formula. For example, the component \( s! (d\omega)_{s i j k l} \) for a 4-form \( \omega \) has \( s = 3 \) and \( p = 4 \) giving \( 3 \partial_\theta \omega_{s i j k l} - 2 \partial_\psi \omega_{s i j k l} \). We will simplify such formulas by multiplying by symmetry factors to cancel denominators, as we have done here.
If we further take the projection \( s^{\alpha i} \mapsto \lambda^0 v^i \) to the product of an unconstrained bosonic spinor \( \lambda \) of \( SU(4) \) and an unconstrained bosonic spinor \( v \) of \( SU(2) \), then the right-hand side vanishes and we find that

\[
Q^{\omega_{\lambda \ldots \lambda \psi \ldots \psi}}_{\mu, n - p} = 0.
\]  

Here,

\[
Q := D_{\lambda \otimes v} = \lambda^0 v^i D_{\alpha i} =: \lambda^0 D^{+}_\alpha
\]

stands for the projected superspace derivative.

The operator \( Q \) appears repeatedly in the analysis that follows. Its importance derives from the fact that the condition (2.9) holds for the lowest non-vanishing component of any \( p \)-form and, as such, it appears as a defining condition on the superfield from which all other components are derived.\(^5\) We call the projection \( s \mapsto \lambda \otimes v \) the pure spinor projection for reasons discussed in appendix A (cf. eq. (A.16) and the surrounding discussion).

Superfields \( \Phi = \Phi(x, \theta, v) \) satisfying \( D^{+}_\alpha \Phi = 0 \) are known in the projective superspace literature as analytic superfields.\(^6\) When \( \Phi \) is homogeneous of degree \( n \) in the variables \( v, \Phi \) is said to have homogeneity weight \( n \). When we wish to indicate this explicitly, we will do so with a superscript \( \Phi^{+n} \). In these terms, equation (2.9) says that the pure spinor projection \( \omega^{\lambda \ldots \lambda \psi \ldots \psi} \) of the lowest-dimension, non-vanishing component of the \( p \)-form is an analytic superfield with homogeneity weight \( n \). The dimension of this field is \( d = \frac{1}{2} n + p - n = p - \frac{n}{2} \).

It is possible for the aforementioned projection of the \( n \) \((p-n)\)-component to vanish.\(^7\) When this happens, the pure spinor projection of the lowest dimension \((d+\frac{1}{2})\) Bianchi identity is trivially satisfied. Passing to the next Bianchi identity (that with dimension \( d + 1 \)) we find that it is the \((n-1)\) \((p-n+1)\)-component of \( \omega \) that projects to an analytic superfield provided this projection does not also vanish identically. If it does, we pass to the next Bianchi identity. We proceed this way until we find a value \( n' \leq n \) such that the projection of the \( n' \) \((p-n')\)-component does not vanish under pure spinor projection and, therefore, defines an analytic superfield with homogeneity weight \( n' \).\(^8\) In our analysis, we will find that this field is a superconformal primary field, that is, a superfield transforming homogeneously under super-Weyl transformations as we recall in section 3.1 (cf. eq. (3.9)).

In section 3.1, we will also show that \( Q^2 = 0 \) on superfields defined over the pure spinor subspace. These superfields, graded by homogeneity weight and spin, form a complex of spaces with differential \( Q \). Assuming this, we conclude that differential forms restricted to the pure spinor subspace are sourced by superconformal primary superfields in the cohomology of this complex. In the next section, we will study large families of such superfields.

With the lowest non-vanishing component in hand, the remaining components of the superform can be reconstructed by the usual method. To wit, one first solves the lowest non-trivial Bianchi identity for the dimension-\((d+\frac{1}{2})\) component by inverting the constant tor-

\(^{5}\)This helps to explain the observation in reference [41] that for differential forms their “spinor cohomology” of coincides with the pure spinor cohomology.

\(^{6}\)We are glossing over some subtleties here that we address as needed.

\(^{7}\)This happens, for example, for the \( p = 3 \) form \( H \) where \( n = 2 \) (i.e. \( H_{s \varphi} \neq 0 \)) but \( H_{\lambda \psi} \equiv 0 \) (cf. section 4.3).

\(^{8}\)In the \( p = 3 \) example, \( n = 2 \) but \( n' = 1 \) (cf. section 4.3).
sion $2i(s^i \gamma^a s_i)$ in equation (2.8). These components suffice to solve the next Bianchi identity (2.7) for the dimension-$(d + 1)$ component, provided certain additional constraints are imposed on the defining field. This process continues to define the next-higher component and, in principle, additional constraints, until we have reached the top component of dimension $p$. The final two Bianchi identities must now be identically satisfied [8, 37]. In section 4, we will carry out this procedure to find the components of all the differential forms in curved superspace and verify that the final two identities are satisfied identically in the flat limit.

3 Conformal symmetry

Consider a superfield $\Phi^{\beta_1...\beta_s \alpha_1...\alpha_s \gamma_1...\gamma_f}(x, \theta)$ with $c$ symmetric fundamental spinor indices, $s$ symmetric anti-fundamental spinor indices, and $f$ symmetric isospin indices. We introduce the commuting variables $\{\lambda^\alpha, \bar{\lambda}_\alpha, v^i\}$ in the $\{(4, 1), (\bar{4}, 1), (1, 2)\}$ representations of $\text{SU}(4) \times \text{SU}(2)$ and replace the superfield with

$$\Phi^{+f}_{\lambda_1...\bar{\lambda}_c...\gamma_1...\gamma_f} = v^{i_1} ... v^{i_f} \lambda^{\alpha_1} ... \lambda^{\alpha_s} \bar{\lambda}_{\beta_1} ... \bar{\lambda}_{\beta_c} \Phi^{\beta_1...\beta_c}_{\alpha_1...\alpha_s i_1...i_f}. \quad (3.1)$$

Lorentz-irreducibility requires tracelessness on pairs of fundamental and anti-fundamental spinor indices. We impose this by requiring

$$\lambda^\alpha \bar{\lambda}_\alpha = 0. \quad (3.2)$$

Introducing the conjugate momenta $\{\omega^\alpha, \bar{\omega}^\alpha, p_i\}$ allows us to rewrite the action of the Lorentz and isospin generators as

$$m_{ab} = -\frac{1}{2} \lambda_{\gamma a b} \bar{\omega} - \frac{1}{2} \bar{\lambda}_{\gamma a b} \omega \quad \text{and} \quad j_{ij} = v_{(i} p_{j)} \quad (3.3)$$

This representation preserves the constraint (3.2). The other derivations preserving the constraint are

$$p_a = \bar{\lambda} \gamma^a \omega, \quad \bar{p}^a = \lambda \gamma^a \bar{\omega}, \quad \Delta = \frac{1}{2} \lambda^a \omega_{\alpha} - \frac{1}{2} \bar{\lambda}_{\alpha} \bar{\omega}^a, \quad \text{and} \quad q = v^i p_i. \quad (3.4)$$

Together, they generate the conformal algebra $\mathfrak{so}_{6,2}$

$$[m_{ab}, m_{cd}] = -2 \eta_{[a} m_{b]d} + 2 \eta_{d[a} m_{b]a}, \quad [p_a, \bar{p}^b] = 2 g^b_a \Delta - 2 m_a^b, \quad [\Delta, p_a] = -p_a, \quad [\Delta, \bar{p}^a] = -\bar{p}^a, \quad (3.5)$$

and a decoupled $u_2$.

An irreducible (iso-)spin-tensor (3.1) is an irreducible representation of this algebra. The derivation $Q$ acts on such representations. In general, its square is proportional to Lorentz and isospin generators (cf. eq. (A.18)). When acting on the representations (3.1), however, the Lorentz $M \rightarrow m$ and isospin generators $J \rightarrow j$ are represented by (3.3). Simple Fierz rearrangement then implies that the only remaining term is proportional to the constraint (3.2). Therefore,

$$Q^2 = 0 \quad (3.6)$$

when acting on the family of fields of the form (3.1). Thus, these fields form a differential complex graded by spin and isospin.

– 6 –
3.1 Superconformal primary superfields

In this subsection, we use the pure spinor/ambi-twistor-like representation just introduced to construct large families of superconformally covariant field representations by imposing super-Weyl-invariant constraints. The ambi-twistor-like variables are not necessary to define the constraints but they greatly simplify the proof of their super-Weyl covariance. When the resulting representations are on shell, their dynamics are superconformally invariant.

In appendix A we recall the action of super-Weyl transformations (cf. eq. (A.9)–(A.12) preserving the algebra of covariant derivatives defining the six-dimensional, $N = (1,0)$ supergravity theory studied in reference [27]. These transformations are parameterized by a real, unconstrained scalar superfield $\sigma(z)$. In keeping with superspace terminology, we define an irreducible superfield (3.1) to be a Weyl tensor of weight $w$ provided that under such a transformation

$$\delta \Phi = w \sigma \Phi.$$  \hfill (3.7)

On such fields, the differential transforms as

$$\delta Q = \frac{1}{2} \sigma Q + \frac{1}{2} (3s + c - 4f)(Q \sigma),$$  \hfill (3.8)

as follows from (A.9) evaluated on the representation (3.3). Therefore, if $\Phi$ is a Weyl tensor with weight $w$ then $Q \Phi$ will be a Weyl tensor of weight $w + \frac{1}{2}$ provided

$$w = 2f - \frac{3}{2}s - \frac{1}{2}c.$$  \hfill (3.9)

In particular, it is consistent to constrain

$$Q \Phi = 0 \quad \text{provided} \quad w = 2f - \frac{3}{2}s - \frac{1}{2}c.$$  \hfill (3.10)

Important examples are given in the following table:

| $p$ | $\Phi (f, s, c)$ | superfield field strength/potential | $w$ | section |
|-----|-----------------|------------------------------------|-----|---------|
| 1   | $A (1, 1, 0)$   | $A_{a i}$                          | $\frac{1}{2}$ | 4.1     |
| 2   | $W (1, 0, 1)$   | $W^{a i}$                          | $\frac{3}{2}$ | 4.2     |
| 3   | $V (1, 0, 1)$   | $V^{a i}$                          | $\frac{3}{2}$ | 4.3.1   |
| 3   | $C (2, 1, 1)$   | $C_{ab i}$                         | 2    | 4.4.1   |
| 5   | $K (2, 0, 0)$   | $K_{ij}$                           | 4    | 4.5     |
| 6   | $L (3, 1, 0)$   | $L_{ai j k}$                       | $\frac{9}{2}$ | 4.6     |

As we will discuss in detail in section 4, they represent, respectively, the gauge 1-form potential $A := \lambda^a v^i A_{a i}$, its 2-form field strength $W := \lambda^{a i} v_j W^{a i}$, the gauge 2-form potential $V := \lambda_{a i} v_j V^{a i}$, the gauge 3-form potential $C := (\lambda^{ab} \lambda) v^i v^j C_{ab i}$, the so-called linear

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9The parameter $D_{\alpha} \sigma$ is the $S$-supersymmetry parameter. Canceling this term implies that the field $\Phi$ is invariant under $S$-supersymmetry, that is, it is a superconformal primary field.
**multiplet** $K := v^j v^j K_{ij}$ related to the projective Lagrangian density,\(^\text{10}\) and the 6-form field strength $L := 3 \lambda^\alpha v^i v^j v^k L_{\alpha ijk}$.

In addition to this family of representations, there is an infinite family of symmetric, traceless “spin-$\ell$” superfields $J_{c_1 \ldots c_i \ldots i_f} = J_{(c_1 \ldots c_i)}(i_1 \ldots i_f) - \text{traces}$: using $\ell$ (cf. eq. (3.4)), let

$$J^\ell_f := v^{i_1} \ldots v^{i_f} \psi^{c_1} \ldots \psi^{c_\ell} J_{c_1 \ldots c_i \ldots i_f}. \quad (3.11)$$

Then the condition

$$QJ^\ell_f = 0 \Rightarrow w = 2\ell - f, \quad (3.12)$$

defines a Weyl superfield of weight $2\ell - f$. We will see in section 4.4 that for $\ell = 1$ and $f = 2$, this condition defines the weight $w = 3$ field $G_{aij}$ sourcing the 4-form field strength.

Finally, there are seven other families of Weyl superfields that are described naturally in various alternative “polarizations” of the pure spinor variables. To illustrate what we mean by this, we will explicitly work out the only example used in our analysis of differential forms: consider a superfield with $s = 0$ but $c$ and $f$ arbitrary. Performing the canonical transformation from $\{\bar{\lambda}, v\}$ variables to $\{\omega, p\}$ on the superfield $\Phi \mapsto \Phi^\dagger$ only, results in a re-“normal”-ordering under which the conformal weight changes as $w = 2p_i - \frac{1}{2} \bar{\lambda}_\alpha \bar{\omega}^\alpha - \frac{3}{2} \lambda^\alpha \omega_\alpha \mapsto 2[-f - 2] - \frac{1}{2} [0] - \frac{3}{2} [-c - 4]$. In the new polarization, the constraint $Q\Phi^\dagger = 0$ is equivalent to the condition

$$D_{ai} \Phi^{\alpha_\beta_\gamma \ldots \beta_{i-1} ij_1 \ldots j_f} = 0 \Rightarrow w = -2f + \frac{3}{2} c + 2 \quad (3.13)$$

on the contraction of the operator $D_{ai}$ with the spin and isospin indices on $\Phi^{ai \ldots}$. This constraint is compatible with the condition (3.10) when the weights agree, that is, for $c = 2f - 1$ and $w = f + \frac{1}{2}$. As we will derive in section 4.2, the lowest-weight member of this tower is the the gauge 1-form field strength superfield $W$. Note that we are not required to impose this condition on such a weight-(f + $\frac{1}{2}$) field. If we do not, we find that the component $Q\Phi^\dagger$ is another Weyl tensor of weight $f + 1$. We will see in section 4.3.1 that this observation provides the link between the description of the 2-form gauge potential described by the superfield $V$ and that in terms of its 3-form field strength. The latter is built on the Weyl-weight-2, real scalar superfield $\Phi$ related to $V$ by $\Phi = D_{ai} V^{ai}$ (cf. eq. (4.34)).

### 4 The super-differential complex

In this section, we will explicitly go through the steps outlined at the end of section 2 for solving the closure conditions (referred to as Bianchi identities) for $p$-forms with $p = 1, \ldots, 6$ subject to the condition that certain components vanish (e.g. $F_{ss} = 0, H_{sss} = 0$). In the process, we will find that for each $p \leq 5$, there is an additional constraint on the defining superfield necessary for the closure of the dimension-$p$ Bianchi identity. To pass to the

\(^{10}\)The projective Lagrangian density [27] is a homogeneity weight-2, analytic superfield $\hat{K}^{++}(\zeta)$ containing an infinite number of ordinary superfields. Of these, $K_{ij}$ are the first three terms in an expansion in $\zeta := v^2/v^4$ with all other superfields containing only auxiliary components.

\(^{11}\)Equivalently, we can keep $\Phi$ and perform the transformation on $Q \mapsto Q'$. Then $Q'$ will act by contraction of the form $\Phi$ on the vector $D_{\lambda \otimes \nu}$. 

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next $p$-form in the complex, we relax this last condition, thereby obstructing the closure of the $p$-form field strength. In doing so, we find the defining superfield for the $(p+1)$-form. In this sense, the entire complex is derived from the constraint $F_{\alpha i \beta j} = 0$ imposed on the 2-form. The lowest non-vanishing components of the resulting forms have precisely the dimensions found to imply superconformal invariance in section 3.1.

The result for flat forms with $p = 2, \ldots , 5$ is represented schematically in the following table:

| $p$ | $F_{ss} = 0$ | $F_{s\psi} = s^i \gamma_\psi W_i$ | $H_{ss} = 0$ | $H_{s\psi} = s^i \gamma_\psi s_i \Phi$ | $G_{ssss} = 0$ |
|-----|--------------|-------------------------------|----------|----------------|----------------|
| 2   | $F_{s\psi} = D^i \gamma_\psi W_i$ | $H_{s\psi} = s^i \gamma_\psi s_i \Phi$ | $G_{ssss} = 0$ | $K_{ssss} = 0$ | $G_{s\psi s} = 0$ |
| 3   | $H_{s\psi} = s^i \gamma_\psi D_i \Phi$ | $G_{ssss} = 0$ | $K_{ssss} = 0$ | $K_{s\psi s} = 0$ | $G_{s\psi s} = 0$ |
| 4   | $H_{s\psi} = D^i \gamma_\psi D_i \Phi$ | $G_{ssss} = 0$ | $K_{ssss} = 0$ | $K_{s\psi s} = 0$ | $G_{s\psi s} = 0$ |
| 5   | $H_{s\psi} = * D_i \gamma_\psi D_j G_{ij}$ | $K_{ssss} = 0$ | $K_{s\psi s} = 0$ | $K_{s\psi s} = 0$ | $G_{s\psi s} = 0$ |

In order to fit the entries into the table, we have suppressed the 1- and 6-form, are ignoring numerical factors, and we use $*$ in the higher components of the forms of degree $p = 4, 5$ to schematically denote the Hodge dual.

Very roughly, going up a $p$-form chain corresponds to applying the operator $D_i \gamma_\psi \partial / \partial s_i$. Going across corresponds to finding the dimension-$p$ component and replacing the $DD$ operator acting on the defining field with some field that is bilinear in $s$. In fact, this is happening because the Bianchi identity has reducible Lorentz/isospin components while the $DD$ field strength of the $p$ form is irreducible. Imposing that the additional irreducible components vanish closes the $p$-form Bianchi identity $d\omega_p = 0$. Alternatively, we can interpret this additional irreducible part as the lowest non-trivial component of a $(p+1)$-form $\omega_{p+1}$. Then the statement is that the non-vanishing of this new form is the obstruction to the $p$-form Bianchi identity, that is, $d\omega_p = \omega_{p+1}$.

For example, starting with $F_{ss} = 0$ and working our way up to the Bianchi identity $(dF)_{ss\psi} = 0$, we find that $F_{s\psi} \propto D^i \gamma_\psi W_i$ for the top component of the 2-form. However, in that same identity, there remains uncanceled the Lorentz-irreducible term $D_{ai} W^{ai}$ which the Bianchi identity sets to zero. Alternatively, we may decide to deform the closure
condition by introducing a source $H_{ss\psi}$ at this level. Then the new identity is $dF = H$. Consistency requires $dH = 0$, which we then proceed to solve. But this is just the Bianchi identity for the 3-form as it appears in the second column of the table.

Below the dividing line in the table are the conditions the defining superfields satisfy. The top line represents the relation $Q\Phi = 0$ on the pure spinor cone. The line below it denotes additional conditions required for the closure of the Bianchi identity for that particular $p$-form. The interpretation of the $(p+1)$-form as an obstruction to the $p$-form Bianchi identity is reflected in the fact that the left-hand side of each condition on the bottom line is in the same irreducible Lorentz and isospin representation as the defining field to the right of it.\textsuperscript{12} In the following subsections, we will make all of these statements explicit.

We should mention that we are not claiming that the set of $p$-form representations we obtain is complete;\textsuperscript{13} in lower dimensions, it is possible to have so-called “variant representations” [1, 3, 42]. However, the tower we obtain is uniquely determined by working our way up from the constraint $F_{ss} = 0$. Furthermore, each form has a superconformal primary field as its lowest non-vanishing component. Taken together, it may be that the resulting complex is unique. Proving this or finding counter-examples (variant representations) should be possible by first classifying all superconformal constraints of scaling weight $w \leq p$ along the lines of section 3.1 and then inspecting them for proper Lorentz and iso-spin structure.\textsuperscript{14}

The complex described in this section was recently interpreted as the Chevalley-Eilenberg complex of $p$-co-chains of the supersymmetry algebra with values in the space of superfields [8], with a differential $\omega \mapsto d_{CE} \omega$ that is defined by the left-hand-side of equation (2.7) or, for simplicity, its flat-space analogue (2.6).\textsuperscript{15} Let us denote the lowest-dimension non-vanishing component of $\omega$ by $\phi$ (e.g. for the 2-form $\omega = F$ of section 4.2, $\phi = W$ enters in eq. (4.10) as the spinor fieldstrength.) The form of $\phi$ is determined by the Bianchi identities. Similarly, the higher Bianchi identities define the remaining components of $\omega$ in terms of superspace derivatives on $\phi$ projected to combinations of $\gamma$-matrices (and in curved space, covariantized with torsions) that may or may not be Lorentz-irreducible. The projection to the complementary representations define constraints on $\phi$.

This picture was made precise in reference [8] (see also [37]) in the following sense: when the coefficients in the complex are taken to be constant superfields, we obtain an algebraic complex with a reduced differential $d_{CE0}$ which is essentially the contraction $\psi \mapsto \gamma(s, s)$ (a.k.a. interior product with the vector defined by $s$ and the Clifford map). Then the set of constraints on $\phi$ is in bijection with the cohomology of this reduced differential $d_{CE0}$

\textsuperscript{12}For example, for $p = 2$ the spinor field strength has no scalar component $D_{\alpha}W^{\dot{\alpha}}$: this term appears in the Bianchi identity at the same level as $F_{\alpha \dot{\alpha}}$ but cannot be canceled by it since there is no Lorentz-invariant way to absorb a scalar into a 2-form. This component must therefore be set to vanish if we want the Bianchi identity for the 2-form to be satisfied. This scalar superfield is of the same form as the defining field $\Phi$ in the 3-form to the right of it in the table.

\textsuperscript{13}We thank Gabriele Tartaglino-Mazzucchelli for raising this question.

\textsuperscript{14}For example, $H_{ss\psi}$ has scaling weight $\frac{3}{2}$. There is a representation of this dimension which we call $V^{\alpha \dot{\alpha}}$ but it cannot be used to construct this particular component $H_{ss\psi}$ since, for example, $s^{\alpha_{1}} s^{\beta} s^{\dot{\alpha}_{1}} \varepsilon_{\alpha_{2}\beta} s_{\dot{\alpha}_{2}} V^{\alpha_{2}} \equiv 0$. Instead, it enters into $H_{ss\psi}$ as $D_{\alpha}V^{\alpha \dot{\alpha}}$, as explained in section 4.3.1.

\textsuperscript{15}The analysis of [8, 37] was carried out for the flat five-dimensional case but the results generalize to other dimensions.
and the set of equations defining the components of $\omega$ in terms of $\phi$ is bijective to the co-boundaries of the reduced Chevalley-Eilenberg complex. An immediate corollary of this theorem is the well-known statement that there are no new constraints imposed by the last two Bianchi identities because the reduced cohomology is empty there (since co-boundaries must have at least two $s$ variables). We will generally not use the results just described (except to avoid a particularly tedious and unilluminating calculation in section 4.4) as the analysis presented here predates that of [8, 37].

4.1 The closed 1-form

The components of a generic 1-form are $(A_s, A_\psi)$. The first condition for a closed 1-form is the component of (2.7) with the most $s$:

$$2(dA)_{ss} = 2D_s A_s - 2i A_\gamma(s,s) = 0. \tag{4.1}$$

The pure spinor projection of this equation is simply (2.9)

$$QA = 0 \tag{4.2}$$

where $A = \lambda^\alpha v^i A_{\alpha i}$ defines a Weyl tensor superfield provided $w = \frac{1}{2} \tag{3.10}$. This condition, which is equivalent to $D_{(\alpha(i A_{\beta j})} = 0$, was solved in flat space in references [43] and [44] based on the four-dimensional, $N = 2$ solution of Mezin\c{c}escu [45] as $A_{\alpha i} = D_{\alpha i} U + D^j_{\alpha} U_{ij}$. Substituting this back into the pure spinor constraint $QA = 0$, we find that the isotriplet prepotential $U_{ij}$ is required to satisfy $D^k \gamma_{abc} D_k U_{ij} = 0$. Due to the flat-space identity $D^m \gamma_{abc} D_m D^i_{ijkl} \equiv 0$, this implies that it can be written in terms of the unconstrained Mezin\c{c}escu prepotential $u_{ij}$ as $U_{ij} = D^i_{ijkl} u^{kl}$.

Returning to curved space, the vector component the super-1-form is determined by the dimension-1 Bianchi identity to be

$$A_\psi = -i \frac{1}{8} D^k \tilde{\gamma}_\psi A_k. \tag{4.3}$$

Substituting the curved-space analogue of the solution above

$$A_{\alpha i} = D_{\alpha i} U + D^j_{\alpha} U_{ij} \quad \text{with} \quad D^k \gamma_{abc} D_k U_{ij} + 256i N_{abc} U_{ij} = 0, \tag{4.4}$$

this becomes $A_\psi = D_\psi U - i \frac{1}{8} D_{(i \tilde{\gamma}_\psi D_j)} U^{ij}$. The $U$ part drops out of the dimension-$\frac{3}{2}$ Bianchi identity

$$D_s A_\psi - D_\psi A_s - T_{s\psi} A_{\alpha i} = 0 \tag{4.5}$$

which constrains the prepotential $U_{ij}$ by $s_i \gamma_\psi W^i U = 0$ for

$$W^i U := \frac{1}{8} D^k \gamma_{ijk} U_{jk} - \frac{i}{6} (\tilde{\gamma}_\alpha)^\alpha_{\beta \gamma} D_\alpha D_\beta U^{ij} + \text{torsion terms.} \tag{4.6}$$

Note that this is the form of the field strength superfield for a gauge 1-form with prepotential $U_{ij}$. In the next section, we will relax the condition forcing it to vanish, thereby generating the closed 2-form field strength as an obstruction to the closure of the 1-form being worked out here.
Setting the field strength superfield \( W_U = 0 \) is gauge equivalent to setting \( U_{ij} = 0 \).
Doing this, we find that the closed 1-form is given by \( (A_s, A_\psi) = (D_s U, D_\psi U) \). The dimension-2 Bianchi identity
\[
2D_\psi A_\psi - \frac{1}{2} \cdot 2T_{\psi\psi}^{\alpha i} A_\alpha i = 0 \tag{4.7}
\]
is satisfied identically. We conclude that, as expected, the unique closed, Weyl-covariant 1-form is the exact 1-form with weight-0 (iso-)scalar potential \( U \).

4.2 The closed 2-form

The closed 1-form \( A \) of the previous section satisfied two constraints. The first of these was the pure spinor constraint \( QA = 0 \) (4.2). The second was the dimension-3 Bianchi identity (4.5) constraining the prepotential \( U \) to vanish. We can deform this particular Bianchi identity by introducing the superfield 2-form field strength \( F_s^{\psi} \) as an obstruction to the closure of the 1-form field \( A \). In this interpretation, continuing to impose the pure spinor condition (4.2) corresponds to keeping \( F_{ss} = 0 \). In fact, the two conditions are equivalent: generally, \( F_{\alpha i\beta j} = F_{\beta j\alpha i} = F_{(\alpha|\beta|j)} + F_{[\alpha|\beta|j]} \) but the second term is equivalent to \( \epsilon_{ij}(\gamma^a)_{\alpha\beta} F_a \) which can be absorbed by a field redefinition into the vector component \( A_a \). The remaining term \( F_{(\alpha|\beta|j)} = \mathcal{D}_{(\alpha|\beta|j)} \) is precisely the combination \( QA \).

In this section, we will solve the Bianchi identities for the closed 2-form \( F \) subject to
\[
F_{ss} = 0. \tag{4.8}
\]
We emphasize that this is the only input from section 4.1 that we will use. The lowest-level Bianchi identity relates the components \( F_{ss} \) and \( F_{s\psi} \) as
\[
3D_s F_{ss} + 3 \cdot 2iF_{s\gamma(s,s)} = 0. \tag{4.9}
\]
By the Fierz identity (A.15), the condition \( F_{ss} = 0 \Rightarrow F_{s\gamma(s,s)} = 0 \) is compatible with the solution
\[
F_{s\psi} = 2i(s^i\gamma_\psi W_i), \tag{4.10}
\]
for some positive chirality, fermionic superfield \( W^{\alpha i} \). The dimension-2 identity reads
\[
2D_s F_{s\psi} + D_\psi F_{ss} - 2iF_{\gamma(s,s)\psi} = 0. \tag{4.11}
\]
The pure spinor projection of this implies
\[
QW = 0 \tag{4.12}
\]
in the sense of section 3.1. To see this, note that under pure spinor projection, \( (s^i\gamma_\psi W_i) \mapsto c_\alpha W^{\alpha i} \) where we define \( c_\alpha := (\lambda^i\gamma_\psi)^\alpha_i \). Although this contravariant spinor is fermionic, it satisfies \( \lambda^\alpha c_\alpha \equiv 0 \) analogously to (3.2) so that the analysis of that section remains valid in this special parameterization. The pure spinor condition (4.12) defines a Weyl tensor superfield provided its weight is \( w = \frac{3}{2} \). By condition (3.2) or, rather, its fermionic version, it is equivalent to
\[
\mathcal{D}_{(i\gamma_{ab}W_j)} = 0. \tag{4.13}
\]
As a practical matter, this condition says that at the level of component field strengths, there is no triplet of 2-forms.

The pure spinor projection isolates the isospin triplet part of the dimension-2 Bianchi identity (4.11). The remaining isospin singlet part contains a superfield 2-form term and a scalar term. Canceling the 2-form part results in the definition of the top component of the closed 2-form

\[ F_{\psi\psi} = -\frac{1}{4} D_k \bar{\gamma}_{\psi\psi} W^k, \]  

leaving only \((s^i\gamma_{\psi}s_i)(D_{\beta j}W^{\beta j}) = 0\) uncanceled. Therefore, in addition to the constraint (4.13), we are required to impose the vanishing of the scalar term

\[ D_{\alpha i} W^{\alpha i} = 0. \]  

Note that this condition is Weyl invariant by (3.13) since \(w = \frac{3}{2}\). Furthermore, it is required for consistency of that part of the dimension-2 Bianchi identity that drops out of the pure spinor projection. By contrast, the constraint (4.12) is defined by the projection to the pure spinor subspace. In the next subsection (cf. section 4.3), we will interpret the lowest 3-form component as an obstruction to this additional condition (4.15).

The constraints (4.13) and (4.15) define the abelian 2-form field strength representation \(W\) [46]. Its derivative can be expanded as

\[ D_{\alpha i} W^{\beta j} = \delta^i_j F_{\alpha}^{\beta} + \delta_{\alpha \beta} X^{ij} \]  

for some iso-triplet superfield \(X_{ij} = X_{(ij)}\) whose lowest components are auxiliary fields. The dimension-\(\frac{5}{2}\) Bianchi identity

\[ D_s F_{\psi\psi} - 2D_{\psi} F_{\psi\psi} - 2T_{\psi\psi}^{\alpha \beta} F_{\alpha \psi\psi} = 0 \]  

serves to relate the field equations to \(X\) and imply no additional conditions on \(W\). Likewise, the dimension-3 identity

\[ D_{\psi} F_{\psi\psi} - T_{\psi\psi}^{\alpha \beta} F_{\alpha \psi\psi} = 0 \]  

implies no new constraints. Consequently, this \((5 + 3)(4 + 4)\)-component representation is off-shell.

### 4.3 The closed 3-form

The defining superfield \(W\) of the abelian 2-form satisfies, in addition to the pure spinor condition (4.12), the dimension-2 constraint (4.15) as follows from the \(0 = (dF)_{\psi\psi} \propto (s^i\gamma_{\psi}s_i)(D_{\beta j}W^{\beta j})\) Bianchi identity. In keeping with our general philosophy, we source this equation with

\[ H_{\psi\psi} = 2i(s^i\gamma_{\psi}s_i)\Phi \]  

for some Weyl tensor superfield \(\Phi\) of weight \(w = 2\) [43, 44]. This is consistent with the dimension-2 Bianchi identity

\[ 4D_s H_{sss} - 4 \cdot 3i H_{ss\gamma(s,s)} = 0. \]
provided we also impose $H_{sss} = 0$. Note that $H_{ss\psi}$ vanishes under the pure spinor projection. This is consistent with the projection of the dimension-$\frac{5}{2}$ Bianchi identity

$$3D_s H_{ss\psi} - D_\psi H_{ss\psi} + 3 \cdot 2i H_{\gamma(s,s)\psi} = 0,$$

from which we easily obtain

$$H_{s\psi\psi} = -(s^i \gamma_{\psi\psi} D_i \Phi).$$

Therefore, in the notation of section 2, $n = 2$ and $n' = 1$. Plugging this into the dimension-3 identity

$$2D_s H_{s\psi\psi} + 2D_\psi H_{ss\psi} - 2i H_{\gamma(s,s)\psi\psi} + 4T_{s\psi}^{\alpha i} H_{\alpha is\psi} = 0$$

and taking the pure spinor projection, we find the condition

$$\frac{1}{8} (\lambda \gamma_{\psi\psi} \lambda) \left( D^+ \tilde{\gamma}^a D^+ + 16iC^{a++} \right) \Phi = 0.$$  

Here, we have defined the combination

$$D^2_{aij} := \frac{1}{2} D(i \tilde{\gamma}_a D_j)$$

which will show up repeatedly. Thus, the dimension-3 identity implies the curved 3-form field strength constraint [27]

$$D^2_{aij} \Phi + 8iC_{aij} \Phi = 0$$

with the remaining combination defining the 3-form field strength component

$$H_{\psi\psi\psi} = \frac{i}{8} \left( D^k \tilde{\gamma}_{\psi\psi\psi} D_k + 128iN_{\psi\psi\psi} \right) \Phi.$$  

Acting on the constraint (4.26) with $D_s$ results in the Dirac equation

$$iD^{\alpha\beta} D_{\beta}^\alpha \Phi - iC^{\alpha\beta ij} D_{\beta j} \Phi - 2iN^{\alpha\beta} D_{\beta}^\alpha \Phi - 12iC^{\alpha i} \Phi = 0$$

so this multiplet is on-shell. The calligraphic torsion components entering here and below are the dimension-$\frac{5}{2}$ components of the supergravity torsions (A.7). They are included here only for completeness and are not critical to the understanding of the 3-form. Similarly, we find the covariantized Klein-Gordon equation that results from contracting with another spinor derivative:

$$0 = D^a D_a \Phi + 8C_{ij} C_{ij}^a \Phi + \frac{i}{6} N^{abc} D^k \tilde{\gamma}_{abc} D_k \Phi - \frac{3i}{2} D_{ai} C^{ai} \Phi$$

$$- 3iC^{ai} D_{ai} \Phi + \frac{5i}{2} N^{ai} D_{ai} \Phi.$$  

The higher Bianchi identities

$$D_s H_{\psi\psi\psi} - 3D_\psi H_{s\psi\psi} - 3T_{s\psi}^{\alpha i} H_{\alpha is\psi} - 3T_{\psi}^{\alpha i} H_{\alpha is\psi} = 0$$

An alternative interpretation of this formula in curved space is as a mechanism for defining geometrical objects in the Weyl multiplet in terms of those in the tensor multiplet [47] (see also section 2.3 of [27]).
\[ 4D_\psi H_{\psi\psi\psi} - \frac{1}{2} \cdot 4 \cdot 3T^a_{\psi\psi\psi} H^{a}_{\alpha i} = 0 \]  
\( (4.30) \)

do not imply any new conditions on \( \Phi \) beyond those following from the constraint \((4.26)\).

Instead of presenting calculations resulting in equations implied by \((4.28)\) and \((4.29)\), we will merely verify that the flat limits are identically satisfied. For the dimension-\( \frac{7}{2} \) identity:

\[ D_s H_{\psi\psi\psi} = \frac{1}{2} (s^i \gamma^a \tilde{\gamma}_{\psi\psi\psi} D_i) \partial_a \Phi = \frac{1}{2} (s^i \gamma^a \tilde{\gamma}_{\psi\psi\psi} D_i - s^i \tilde{\gamma}_{\psi\psi\psi} \gamma^a D_i) \partial_a \Phi \]
\[ = -3 \partial_\psi (s^i \gamma_{\psi\psi} D_i \Phi) = 3 \partial_\psi H_{s\psi\psi} \]  
\( (4.31) \)

where we have used the Dirac equation on the spinor of \( \Phi \). Similarly,

\[ \partial_\psi H_{\psi\psi\psi} = \frac{i}{64} \epsilon_{\psi\psi\psi}^{ab} (D^i \tilde{\gamma}_{abc} D_i) \partial_i \Phi \]
\[ = \frac{i}{64} \epsilon_{\psi\psi\psi}^{ab} D^i (\tilde{\gamma}_{ab} - 2 \eta_{[a} \tilde{\gamma}_{b]} D_i) D_i \partial_i \Phi \]
\[ = \frac{i}{32} \epsilon_{\psi\psi\psi}^{ab} D^i \tilde{\gamma}_{ab} D_i \partial_i \Phi = \frac{1}{4} \epsilon_{\psi\psi\psi}^{ab} \partial_a \partial_b \Phi = 0, \]  
\( (4.32) \)

by using the Dirac equation in the third equality.

### 4.3.1 Alternative formulation

The recovery of the 3-form superfield as an obstruction to one of the two defining conditions of the vector multiplet \((4.15)\), suggests an alternative description of this form in terms of a dimension-\( \frac{7}{2} \) spinor superfield \( V^a \) [48]. As we are obstructing only the scalar constraint, this field would still be required to satisfy the defining condition analogous to \((4.12)\) or \((4.13)\):

\[ QV = 0 \iff D_{(i} \tilde{\gamma}_{ab} V_{j)} = 0. \]  
\( (4.33) \)

It can be shown by brute force calculation that this condition is equivalent to the constraint \((4.26)\) with

\[ \Phi = D_{\alpha i} V^{\alpha i}. \]  
\( (4.34) \)

This description neatly incorporates the gauge invariance of the 3-form field strength since \( \Phi \) is invariant under \( \delta V^{\alpha i} = \Lambda^{\alpha i} \) where \( \Lambda \) satisfies both constraints \((4.13)\) and \((4.15)\) defining the vector multiplet. The condition on \( V \) implies that

\[ D_{\alpha i} V^{\beta j} = \frac{1}{8} \delta^i_\beta \delta^j_\alpha \Phi + \frac{1}{4} \delta^i_\beta B^{\alpha \beta} + \delta^i_\beta Y^j \]  
\( (4.35) \)

for a scalar \( \Phi \), 2-form potential \( B \), and an auxiliary triplet \( Y \). Under the gauge transformation, the 2-form gauge field transforms into the field strength of a 1-form \( \lambda \) as \( \delta B = d\lambda \).

### 4.4 The closed 4-form

The closure constraint \((4.24)\) on the 3-form can be obstructed with a 4-form, the lowest non-trivial component of which is given by

\[ G_{s\psi\psi} = (s^i \gamma_{\psi\psi} s^j) G^a_{ij}. \]  
\( (4.36) \)
This is consistent with the dimension-$\frac{7}{2}$ Bianchi identity

$$3\mathcal{D}_s G_{s\psi \psi} + 3 \cdot 2i G_{s\gamma(s,s)\psi\psi} = 0 \quad (4.37)$$

under the pure spinor projection, provided

$$\langle \gamma_{abc}\rangle_{(a\beta} \mathcal{D}_{\gamma(k)G_{ij})} = 0 \quad \Leftrightarrow \quad \Pi^\gamma_{\alpha a} \mathcal{D}_{\gamma(k)G_{eij})} = 0 \quad (4.38)$$

where $\Pi$ is the projector onto the $\gamma$-traceless subspace of the spinor-vector representation (A.8). To see this, note that the pure spinor projection of (4.36) is proportional to $(c\tilde{\gamma}^a c)G_{a^+}$. The condition that this be annihilated by $Q$ then becomes equivalent to the Weyl-invariant constraint (3.12) for $\ell = 1$ ($\Rightarrow w = 3$). The remaining part of the Bianchi identity (4.37) is, then, easily solved for the dimension-$\frac{7}{2}$ component

$$G_{s\psi \psi} = -\frac{i}{12} \epsilon_{s\psi \psi}^{abc} (s^i \gamma_{ab} \mathcal{D}^j) G_{cij}. \quad (4.39)$$

The dimension-4 Bianchi identity is

$$2\mathcal{D}_s G_{s\psi \psi} + 3 \mathcal{D}_s G_{s\psi \psi} - 2i G_{s\gamma(s,s)\psi\psi} + 2 \cdot 3 T_{s\psi}^{\alpha i} G_{\alpha is\psi\psi} = 0. \quad (4.40)$$

The pure spinor projection gives three conditions:

$$\mathcal{D}^2_{(a k(i} G_{b)j)}^a = 24i C_{a k(i} G_{b)j}^a + 8i \mathcal{D}_a G_{ij} = 0, \quad (4.41)$$

$$\mathcal{D}^2_{(a k(i} G_{b)j)}^k = -4i \mathcal{D}_{(a} G_{b)ij} + \ldots - \text{trace} = 0, \quad (4.42)$$

$$\mathcal{D}^2_{[a k(i} G_{b)j]}^k - 4i \mathcal{D}_{[a} G_{b]ij} - \frac{1}{8} D^k \tilde{\gamma}_{abc} \mathcal{D}_k G_{ij} + \ldots = 0, \quad (4.43)$$

where the ellipses stand for unilluminating torsion corrections. The second and third condition follow from the constraint (4.38) by contraction with $(D^k \tilde{\gamma}_b)^a$. Indeed, the combination $\mathcal{D}^2_{a k(i} G_{b)j})^k - 4i \mathcal{D}_a G_{b ij} = -\frac{3}{4} D^k \tilde{\gamma}_a D_{(a} G_{b)ij}$. Since $\Pi$ is $\gamma$-traceless, we get no condition upon contraction with $\eta^{ab}$. Therefore, the only condition not already implied by the lower Bianchi identities is the condition (4.41) on the trace. It is this condition that we will source to get the 5-form (cf. section 4.5).

The remaining terms in (4.40) determine the dimension-4 component

$$G_{\psi \psi \psi} = -\frac{1}{24} \epsilon_{\psi \psi \psi} \psi^{a b} (\mathcal{D}^2_{a} G_{ij} - 40iC_{a} G_{ij}) G_{b}^{ij}. \quad (4.44)$$

In this calculation, there are no irreducible components beyond this 4-form that need to be canceled so we do not generate any additional constraints on $G_{a} G_{ij}$ at this level.

The remaining identities are the dimension-$\frac{9}{2}$ identity

$$\mathcal{D}_s G_{\psi \psi \psi} - 4 \mathcal{D}_s G_{s\psi \psi} - 4T_{s\psi}^{\alpha i} G_{\alpha i} G_{\psi \psi} - \frac{1}{2} \cdot 4 \cdot 3 T_{s\psi}^{\alpha i} G_{\alpha is\psi\psi} = 0 \quad (4.45)$$

and the dimension-5 identity

$$5 \mathcal{D}_s G_{\psi \psi \psi} - \frac{1}{2} \cdot 5 \cdot 4 T_{s\psi}^{\alpha i} G_{\alpha i} G_{\psi \psi} = 0. \quad (4.46)$$
They should be satisfied identically in the flat limit. This calculation, however, turns out to be particularly tedious. Instead of checking it explicitly, we cite the corollary in [8, 37] stating that this identity is required to hold due to the vanishing cohomology of a certain algebraic complex. In the flat limit, \((*G)^{ab} = \frac{1}{12}D^2_{[a}G_{b]}^{ij}\) and thus it must be that \(\partial^b(*G)^{ab} = 0\): the closure of the top component implies that the dual 2-form \(*G\) is divergenceless up to torsion terms.

4.4.1 Alternative formulation

In section 4.3.1 we explored the alternative “potential” formulation of the gauge 2-form. There, the condition defining the representation was expressed as \(QV = 0\) (4.33) instead of the condition (4.26) in terms of its field strength \(\Phi\). Similarly, one expects to be able to obstruct the closure condition in this potential-type formulation by taking

\[ QV = C. \tag{4.47} \]

Since \(V = \tilde{\lambda}_a v_i V^{\alpha i}\) is a field with \((f, s, c) = (1, 0, 1)\) and \(Q\) is an operator of type \((1, 1, 0)\), \(C\) is of type \((2, 1, 1)\), that is, \(C := (\lambda^{ab} \tilde{\lambda})^i v^j C_{abij}^{\gammaij}\). Consistency then implies

\[ QC = 0 \Rightarrow w = 2 \tag{4.49} \]

where the weight, again, follows from the general formula (3.10).

Recall that the vector multiplet field strength \(W\) obeys two conditions (4.12) and (4.15). Relaxing (4.15) introduces the potential \(V\) for the 3-form field strength which still obeys (4.33). We are now relaxing this second condition by introducing the potential \(C\) for the 4-form field strength \(G = dC\). The constraints on \(G\) imply that \(C_{ss\bar{\psi}} = s^i \gamma^a_{\bar{\psi}} s^j C_{abij}^{\gammaij}\) is the lowest non-vanishing component of this potential. The pure spinor projection of this component with \(C_{abij} := \frac{1}{8}D(\tilde{\gamma}^a_{ab} V^i j)\) gives back equation (4.47).

4.5 The closed 5-form

The obstruction to closure of the 4-form is the left-hand side of (4.41). Our procedure, then, implies that the lowest component of the closed 5-form is given in terms of a superfield \(K_{ij}\) by

\[ K_{ss\bar{\psi}\bar{\psi}} = s^i \gamma^a_{\bar{\psi}} s^j K_{ij}^{\gammaij}. \tag{4.50} \]

This is consistent with the dimension-\frac{9}{2} Bianchi identity

\[ 3D_s K_{ss\bar{\psi}\bar{\psi}} - 3D_{\bar{\psi}} K_{ss\bar{\psi}\bar{\psi}} + 3 \cdot 2i K_{s\bar{\psi} s(s, s) \bar{\psi}\bar{\psi}} = 0 \tag{4.51} \]

in the pure spinor projection provided

\[ QK = 0 \Leftrightarrow D_{\gamma(i} K_{ij)} = 0. \tag{4.52} \]

\[ \text{For purposes of illustration we mention that, in terms of the field strength } \Phi, \text{ the flat-space version of equation (4.47) implies} \]

\[ D^2_{a} \Phi = D^2_{a} C_{ij}^{\beta} + 4i \partial^\beta C_{abij}. \tag{4.48} \]
This condition is Weyl invariant when \( w = 4 \) (3.9) in agreement with the engineering dimension of \( K_{\psi\psi\psi} \). This analyticity constraint implies that

\[
D_a^2 K_j^k + 24i C_a^i K_j^k + 4i D_a K_{ij} = 0 \quad (4.53)
\]

and

\[
D^k \gamma_{abc} D_k K_{ij} - 128i N_{abc} K_{ij} = 0. \quad (4.54)
\]

The remaining part of the Bianchi identity defines the dimension-\( \frac{9}{2} \) component of \( K \) to be

\[
K_{\psi\psi\psi\psi} = -\frac{i}{12} \epsilon_{\psi\psi\psi\psi a} (s^i \gamma_{ab} D^i) K_{ij}. \quad (4.55)
\]

The dimension-5 Bianchi identity

\[
2D_a K_{\psi\psi\psi\psi} + 4D_{\psi} K_{\psi\psi\psi\psi} - 2i K_{(s,s)\psi\psi\psi} - 8(T_{s\psi} i \gamma_{\psi\psi} s^j) K_{ij} = 0 \quad (4.56)
\]

is identically satisfied in the pure spinor limit due to the constraint (4.54) and cancelation of the \( D_{\psi} \) terms. The remaining part determines the top component of \( K \) to be

\[
K_{\psi\psi\psi\psi\psi} = \frac{1}{24} \epsilon_{\psi\psi\psi\psi \psi a} (D_a^2 - 48i C_{aij}) K_{ij}. \quad (4.57)
\]

The dimension-\( \frac{11}{2} \) identity is

\[
D_s K_{\psi\psi\psi\psi\psi} - 5D_{\psi} K_{\psi\psi\psi\psi\psi} - 5T_{s\psi} \alpha^i K_{\alpha i \psi\psi\psi\psi} - \frac{1}{2} \cdot 6 \cdot 5 T_{\psi} \alpha^i K_{\alpha i \psi\psi\psi\psi} = 0. \quad (4.58)
\]

It serves only to define the \( \theta^3 \)-terms in \( K \) in terms of space-time derivatives acting on the lower components and is otherwise unilluminating.

The dimension-6 identity is

\[
6D_{\psi} K_{\psi\psi\psi\psi\psi\psi} = -\frac{1}{2} \cdot 6 \cdot 5 T_{\psi} \alpha^i K_{\alpha i \psi\psi\psi\psi\psi} = 0. \quad (4.59)
\]

It tells us that, in the flat limit, the bosonic projection of the top component of the 5-form \( K \) is closed in the bosonic sense. We may check this explicitly by using the flat covariant derivative identity \( \partial^a D_a^{ij} = \frac{1}{12} D_{ijk} D^k \). It implies that the dual form \( *K_a \) is divergenceless

\[
\partial^a (*K)_a = 0 \quad (4.60)
\]

due to the analyticity constraint (4.52) on \( K \).

Another way to understand this result is by comparison with the 1-form of section 4.1. In the flat limit, the constraint (4.54) agrees with the defining condition (4.4) of a (gauge) 1-form prepotential. This implies that there is a 1-form at the \( \theta^2 \)-level of \( K \). Since \( K \) is a field strength, and due to the dimension of this component, this vector must be a field strength. That this component is divergenceless where that of the vector multiplet was not is a consequence of the stronger constraint (4.52) (from which (4.54) follows).
4.6 The closed 6-form

The top component of the 5-form $K$ defined in (4.57) solves the dimension-5 Bianchi identity with no additional requirements on the superfield $K_{ij}$ beyond the defining pure spinor condition (4.52). As there is no obstruction to the closure of the 5-form, our procedure does not generate a non-vanishing 6-form at this level. (The Chevalley-Eilenberg complex with constant coefficients is exact at this level.)

One possibility is to proceed with the proposal by Drummond and Howe [49] which corresponds to sourcing equation (4.53). (This also suggests the alternative co-dimension 0-form with based on sourcing (4.54).) An action constructed from such an obstruction is of “superaction” type [50]. Alternatively, we may force the violation of the 5-form Bianchi identity by obstructing the defining relation and attempting to interpret the result as a closed 6-form. (This alternative is also suggested by the composite 6-form of section 5.2.3.) This corresponds to the Ansatz

$$L_{\alpha \beta \gamma \delta \epsilon \zeta} = (s^i \gamma_{\psi \psi \psi} s^j) L_{ijkl}$$

in terms of the weight $w = \frac{9}{2}$ superfield $L_{ijkl}$.\footnote{Note that this field is of the form of the gauge parameter superfield for supergravity (cf. ref. [43]). Similar observations were made concerning the appearance of superconformal gauge parameter multiplets in the de Rham cohomology in five dimensions in [7, 8] and even in F-theory superspace in [51].}

Upon pure spinor projection, this gives\footnote{Note the similarity of this expression with the pure spinor 0-mode normalization $\langle \lambda \gamma \psi \psi \lambda \rangle = 1$ [52].}

$$L_{\alpha \beta \gamma \delta \epsilon \zeta} \mapsto \lambda^\alpha (\lambda \gamma \psi \psi \lambda) \psi \psi \psi \psi L_{ijkl}.$$  

The projection of the lowest-dimension Bianchi identity (dimension 5)

$$4D_s L_{\alpha \beta \gamma \delta \epsilon \zeta} - 4 \cdot 3i L_{\alpha \beta \gamma \delta \epsilon \zeta} = 0,$$

as usual, requires $QL = 0$ which is again a condition of type (3.10). Explicitly,

$$QL = 0 \Leftrightarrow D_{(\alpha(i} L_{\beta)jkl)} = 0 \Rightarrow w = \frac{9}{2}. \quad (4.64)$$

The remaining terms can be solved to find the dimension-5 component of the six form

$$L_{\alpha \beta \gamma \delta \epsilon \zeta} = \frac{i}{48} \epsilon_{\psi \psi \psi \psi}^{ab} (s^i \gamma_{ab})^\alpha s^j \beta \gamma (3 D^b_{\epsilon \alpha} L_{ijkl} - D^b_{\delta} L_{ijkl}).$$

The dimension-$\frac{11}{2}$ Bianchi identity is

$$3D_s L_{\alpha \beta \gamma \delta \epsilon \zeta} - 4D_\psi L_{\alpha \beta \gamma \delta \epsilon \zeta} + 3 \cdot 2i L_{\alpha \beta \gamma \delta \epsilon \zeta} - 3 \cdot 4T_{\alpha} L_{\alpha \beta \gamma \delta \epsilon \zeta} = 0. \quad (4.66)$$

The constraints following from the pure spinor projection at this, and at any other level in the Bianchi identities, can be obtained by hitting (4.64) with derivatives.\footnote{This is because (4.64) does not project out any irreducible component of $Q$ acting on $L$. Note that this is in contrast to (4.38) which projects out the $\gamma$-trace of $D_{(k} G_{n)}$.} We solve this Bianchi identity for the next component to find

$$L_{\alpha \beta \gamma \delta \epsilon \zeta} = \frac{1}{192} \epsilon_{\psi \psi \psi \psi}^{ab} s^a \alpha \beta \gamma (3 D^2_{\alpha} L_{ijkl} + 164i C_{\alpha}^{jk}) L_{ijkl}$$

$$- \frac{1}{192} \epsilon_{\psi \psi \psi \psi}^{ab} (s^i \gamma_{ab})^\alpha (D^b_{\epsilon \alpha} + 44i C^b_{\delta}) L_{ijkl}. \quad (4.67)$$
The dimension-6 Bianchi

\[ 2D_s L_{\psi\psi\psi\psi\psi\psi} + 5D_\psi L_{s\psi\psi\psi\psi\psi} - 2i L_{\psi (s_s) \psi\psi\psi\psi\psi} + 2 \cdot 5T_{\psi i} L_{\alpha i\psi\psi\psi\psi\psi} - \frac{1}{2} \cdot 5 \cdot 4T_{\psi i} L_{\alpha i\psi\psi\psi\psi\psi} = 0, \]  

(4.68)
can be solved for the top component of the 6-form to give

\[ L_{\psi\psi\psi\psi\psi\psi} = \epsilon_{\psi\psi\psi\psi\psi\psi} \left[ \frac{i}{192} \left( D^{3\alpha i j k} - 12 i C^{\alpha i j k} \right) L_{\alpha i j k} - \frac{1}{9} C^{i j} (D^k \tilde{z}^a L_{i j k}) \right], \]  

(4.69)

where \( D^{3\alpha i j k} := \frac{1}{3!} \epsilon^{\alpha \beta \gamma \delta} \{ D_\beta i \{ [D_\gamma j, D_\delta k] \} \} \). The dimension-\( \frac{13}{2} \) Bianchi

\[ D_s L_{\psi\psi\psi\psi\psi\psi} - 6D_\psi L_{s\psi\psi\psi\psi\psi} - 6T_{\psi i} L_{\alpha i\psi\psi\psi\psi\psi} - \frac{1}{2} \cdot 6 \cdot 5T_{\psi i} L_{\alpha i\psi\psi\psi\psi\psi} = 0. \]  

(4.70)
does not define any new components and serves only to define the \( \theta^3 \)-terms in \( L \) in terms of derivatives acting on its lower components. Similarly, the dimension-7 Bianchi

\[ 7D_\psi L_{\psi\psi\psi\psi\psi\psi\psi} - \frac{1}{2} \cdot 7 \cdot 6T_{\psi i} L_{\alpha i\psi\psi\psi\psi\psi\psi} = 0 \]  

(4.71)
provides the bosonic closure condition (up to torsion) for the six form.

We can solve the condition (4.64) analogously to what was done in section 4.1 by taking

\[ L_{\alpha i j k} = D_{\alpha (i} L_{j k)} + D^k_{\alpha} L_{ij k} \]  

(4.72)
and plugging it back in. Note that the first term is \( Q \)-exact and is therefore not constrained by (4.64). However, precisely analogously to the case of the constrained prepotential \( U_{ij} \) of the gauge field (4.4), the field \( L_{ij k} \) must satisfy the condition

\[ D^m \tilde{z}_{abc} D_m L_{ij k} - 384 i N_{abc} L_{ij k} = 0 \]  

(4.73)
for the constraint (4.64) to hold. In flat space, then, the analogue of Mezin\u2019cescu\u2019s unconstrained prepotential \( u^{ij} \) for the 6-form would be an unconstrained, dimension-2 scalar field \( \ell \) such that \( L_{ij k} = D^4_{ij k} \ell \).

5 Composite forms

In the previous section, we constructed the de Rham complex of differential forms by sequentially obstructing the closure condition with a form of degree 1 higher. In this section, we investigate the alternative method of building higher-degree forms by wedging forms of lower degree. Analogously to how solving the seemingly trivial closure conditions \( d\omega = 0 \) resulted in the elucidation of the superspace representations of superconformally covariant \( p \)-form fields and their coupling to gravity, here we will similarly gain insight into the structure of interactions in superconformal \( N = (1, 0) \) models and their Lagrangians. In the process, we will derive relations between certain types of composite forms that we compare in section 6.2 to explicit formul\ae appearing in the non-abelian tensor hierarchy.
We will refer to the forms obtained by wedging lower-degree forms as composite forms to distinguish them from the forms above. To minimize additional notation, we will use the same letters in bold font to denote the composite forms. Consider the composite \( p \)-form \( \omega_p = \omega_q \wedge \omega_{p-q} \). For simplicity of exposition, we mostly focus on the product of only two forms. Then

\[
\omega_{s_1 \ldots s_r \ldots s_{p-r}} = \sum_{r,s,t=0} \mathcal{C}_{rs} \omega_{s_1 \ldots s_r \psi_1 \ldots \psi_{q-r}} \omega_{s_1 \ldots s_t \psi_1 \psi_{p-q-t}}
\]  

for some rational coefficients \( \mathcal{C}_{rs} \). These are computed by first counting inequivalent permutations of indices and then normalizing the result to 1. For example, the \( \omega_{ss\psi\psi} \) component of \( G = F \wedge F \) is gotten by writing down the terms \( F_{ss}F_{\psi\psi} \) and \( F_{s\psi}F_{s\psi} \) and realizing that there are two inequivalent configurations of the indices on the second term, namely \( F_{\alpha a}F_{\beta b} \) and \( F_{\beta a}F_{\alpha b} \) whereas on the first \( F_{\alpha \beta} = F_{\beta \alpha} \) and similarly for \( F_{ab} \). Therefore these 3 terms are weighted as \( \frac{1}{3} F_{ss}F_{\psi\psi} \) and \( \frac{2}{3} F_{s\psi}F_{s\psi} \). They get a relative sign from the odd permutation \( ss\psi\psi \to s\psi s\psi \). Finally, \( F_{ss} = 0 \) so \( G_{ss\psi\psi} = -\frac{2}{3} F_{s\psi}F_{s\psi} \).

### 5.1 The composite \( p \)-form with \( p = 2 \) and \( 3 \)

In the abelian limit \( F := A \wedge A = 0 \) so that a single 1-form does not generate a composite 2-form. Given a collection of such forms and a bilinear, skew-symmetric map \( f \), however, one can construct \( F_{ss} := f(A_s, A_s) \) and its higher components. If, in addition, \( f \) maps back into the collection of forms, we can use this composite 2-form as a deformation of the collection of abelian field strengths \( dA \). If one further requires that these maps satisfy the Jacobi identity \( f(f(A_s, A_s), A_s) = 0 \) then this component can be absorbed into a connection \( \nabla = D + f(A, \cdot) \) and we recover the usual formulation of the non-abelian gauge field strength.

The condition \( F_{ss} = 0 \) is equivalent to \( \nabla_s^2 = i \nabla_{\gamma(s,s)} \), defining the vector connection in terms of the spinor connection. With this, the first Bianchi identity becomes equivalent to the associativity of the spinor connection: \( 0 = \nabla_s(\nabla_s \nabla_s) - (\nabla_s \nabla_s) \nabla_s = i[\nabla_s, \nabla_{\gamma(s,s)}] = iF_{s\gamma(s,s)} \). The rest of the analysis proceeds as in section 4.2.

A composite 3-form is easily constructed as \( H = A \wedge F \).\(^{21}\) The properly normalized components

\[
\begin{align*}
H_{sss} &= A_s F_{ss} = 0 \\
H_{ss\psi} &= \frac{2}{3} A_s F_{s\psi} + \frac{1}{3} A_\psi F_{ss} = \frac{2}{3} A_s F_{s\psi} \\
H_{s\psi\psi} &= \frac{1}{3} A_s F_{s\psi} - \frac{2}{3} A_\psi F_{s\psi} \\
H_{\psi\psi\psi} &= \frac{1}{3} A_\psi F_{s\psi} 
\end{align*}
\]

satisfy the Bianchi identities provided \( A \) and \( F \) satisfy theirs. That is, \( H \) is closed provided both \( A \) and \( F \) are. When \( dF = 0 \) but \( dA \neq 0 \), a short calculation

\[
2(dH)_{ss\psi\psi} = 2D_s H_{ss\psi\psi} + 2\partial_\psi H_{ss\psi} - 2iH_{\gamma(s,s)\psi\psi}
\]

\(^{21}\)In the non-abelian case, this can be extended to the full Chern-Simons 3-form. For simplicity of exposition, we work in the abelian limit but allow \( A \) and \( F \) to be independent fields.
\[
\begin{align*}
&= \frac{2}{3} D_s A_s F_{\psi \psi} - \frac{2}{3} A_s D_s F_{\psi \psi} - \frac{4}{3} D_s A_{\psi} F_{s \psi} - \frac{4}{3} A_{\psi} D_s F_{s \psi} \\
&\quad + \frac{4}{3} \partial_{\psi} A_s F_{s \psi} + \frac{4}{3} A_s \partial_{\psi} F_{s \psi} - \frac{2i}{3} A_{\gamma(s,s)} F_{\psi \psi} + \frac{4i}{3} A_{\psi} F_{\gamma(s,s)\psi} \\
&= -\frac{2}{3} A_{\psi} (D_s F_{s \psi} - 2 \partial_{\psi} F_{s \psi}) - \frac{4}{3} (D_s A_{\psi} - \partial_{\psi} A_{s}) F_{s \psi} \\
&\quad - \frac{2}{3} A_{\psi} (D_s F_{s \psi} - 2i F_{\gamma(s,s)\psi}) \\
&= -\frac{4}{3} (dA)_{s \psi} F_{s \psi} 
\end{align*}
\]

shows that \((d\mathbf{H})_{s \psi \psi} = \mathbf{G}_{s \psi \psi}\) where \(\mathbf{G} = dA \wedge F\).

On the pure spinor subspace, this form is represented simply by the abelian Chern-Simons super-3-form field \(\mathbf{C} = AW\). This is a composite analogue of the alternative description of the exact 4-form obstruction (4.47). We will use this form in section 6.2 to obstruct the defining condition (4.33) of the gauge 2-form potential \(V\) as

\[QV = \alpha \text{tr}(AW)\]  

for some parameter \(\alpha\). This equation was proposed in flat space in the form \(D_{(i} \tilde{\gamma}_{ab} V_{j)} = \alpha A_{(i} \tilde{\gamma}_{ab} W_{j)}\) in reference [48]. There, it was explained that this deformation is consistent since both sides obey the constraint \(D_{(i} (\gamma_{\alpha j)} - \text{traces}) = 0\) where \(\sigma\) stands for the \(DV\) and \(AW\) combinations on the left-hand side and the right-hand side, respectively. In the pure spinor notation, this observation reduces to the fact that \(Q^2 = 0\) on \(V\) and that \(Q(AW) = (QA)W + AQW = 0\) by the defining equations (4.2) and (4.12).

5.2 The composite \(p\)-form with \(p = 4, 5,\) and \(6\)

Let \(Z^{\alpha i}\) denote a positive chirality Weyl tensor of weight \(\frac{3}{2}\) and define its weight-2 field strength

\[\Phi(Z) := D_{\alpha i} Z^{\alpha i}.\]  

Recall that when \(Z\) satisfies the condition \(QZ = 0\) (4.33), its associated field strength \(\Phi\) satisfies the condition (4.26). Additionally, restricting \(\Phi = 0\), implies that \(Z\) describes the vector multiplet of section 4.2.

For any two such spinor superfields \(\tilde{Z}\) and \(Z\), define the bilinear

\[\mathbf{G}_{aij}(\tilde{Z}, Z) := \tilde{Z}_{(i} \gamma_{Z_{j)}}.\]  

When \(\tilde{Z}, Z\) satisfy the condition (4.33), as we will henceforth assume, this bilinear satisfies (4.38) and defines a composite version of the 4-form of section 4.4. To see this, let \(B_{ab}(Z) := D_{i} \tilde{\gamma}_{ab} Z^{i}\) denote the 2-form superfield associated to \(Z\) in analogy to the definition of the fundamental 2-form (4.35). The composite 4-form has as its lowest non-trivial component \(\mathbf{G}_{s \psi \psi} = -\frac{2}{3} B_{s \psi} B_{s \psi}\). In the pure spinor projection this component becomes proportional to \((\gamma_{s \psi})^\lambda \gamma^\psi \gamma^\lambda \gamma^\psi\).

In section 4.4 we found that the top component of the 4-form is given by (4.44). Consider the composite version in the flat limit

\[\ast_{G}^{\alpha i} := D_{[aij} G_{\alpha]}^{ij},\]  

\[\text(5.3)\]
the bosonic part of which evaluates to

$$G|_{\text{bose}} = -\frac{3}{16} \left[ \Phi \ast B + \Phi \ast \tilde{B} + 6B \wedge B \right].$$

(5.8)

In general, this form is not closed. Indeed, straightforward \(D\)-algebra gives

$$\partial^b (\ast G)_{ab} = \frac{1}{8} D_{aij}^2 \left( K_{ij} + \tilde{K}_{ij} \right)$$

(5.9)

where we have defined the bilinear \(K_{ij} := iD_{\alpha}(\tilde{\Phi} Z_{ij}^\alpha) + i\tilde{\Phi} D_{\alpha}(iZ_{ij}^\alpha)\) and the \(\tilde{K}\) that follows from switching \(\tilde{Z} \leftrightarrow Z\). This combination, or its curved version

$$K_{ij} = iD_{\alpha}(\tilde{\Phi} Z_{ij}^\alpha) + i\tilde{\Phi} D_{\alpha}(iZ_{ij}^\alpha),$$

(5.10)

is a composite analogue of the defining field of the 5-form multiplet of section 4.5. It is analytic (i.e. it satisfies equation (4.52)) because \(\tilde{\Phi}\) satisfies (4.26) [27]. Since \(K(\tilde{Z}, Z) \neq K(Z, \tilde{Z})\) is not symmetric as a function of \(\tilde{Z}\) and \(Z\), the divergenceless vector superfield

$$D_{\gamma a} K_{ij} = \frac{3}{2} \tilde{\Phi} \partial_\gamma \Phi - \frac{3}{2} \partial^b \left( \Phi B_{ab} \right) - \frac{3}{4} \bar{H}^{(-)}_{abc} B^{bc} + \text{fermions}$$

(5.11)

gives rise to two conserved currents when there are at least two tensor fields present. This will be important when we relate our complex to the non-abelian tensor hierarchy in section 6.2.

The composite 4-form superfield (5.6) can be used to obstruct the defining constraint on the fundamental (i.e. not composite) 3-form field strength superfield \(\Phi\):

$$\mathcal{D}_{(i\tilde{\gamma}_a D_j)} \Phi + 16iC_{aij} \Phi = \alpha G_{aij}.$$  (5.12)

where \(\alpha\) is a coupling constant. We now turn to the analysis of this deformation in the case where \(\tilde{Z}\) and \(Z\) are some combination of vector and tensor multiplets.

5.2.1 The composite 4-form

Specializing \(\tilde{Z} = Z = W\) to a single vector multiplet, \(G_{aij}\) becomes the usual supercurrent [43, 53].

In this special case, the composite 4-form (5.8) reduces to \(G \sim F \wedge F\). It is closed (the 4-form Bianchi identities are not obstructed) since \(\Phi \equiv 0\) and, therefore also, \(K \equiv 0\). The construction is off-shell as there are no tensors present to put it on-shell.

If we couple this form to a fundamental tensor, we recover the fact that the obstructed closure condition (5.12) is the superspace analogue of the Green-Schwarz anomaly equation [48]

$$dH = \alpha F \wedge F.$$  (5.13)

\(\text{In six dimensions, this current is analytic only on-shell as } \mathcal{D}_{(i\tilde{\gamma}_a D_j)} G_{aij}\text{ is proportional to the derivative of the vector multiplet auxiliary field } X_{ij}.\)
5.2.2 The composite 5-form

In this section, we take $\tilde{Z} = V$ and $Z = W$ to describe a tensor multiplet and a vector multiplet, respectively. The composite $G_{aij}$ still describes a 4-form (5.8) but now in terms of a gauge 2-form $B \to B$ and a field strength 2-form $B \to F$. The associated composite field strength $K$ is sourced by the analytic vector-tensor multiplet Lagrangian $-iK_{ij} = \Phi X_{ij} + D_i(\Phi W_j)$ (5.10).

This linear multiplet has an interpretation as a composite version of the super-5-form: consider the lowest component of the composite form $K = F \wedge H$,

$$K_{ss\psi\psi} = K_{ij} = \frac{1}{10}F_{ss}H_{\psi\psi} - \frac{6}{10}F_{s\psi}H_{ss\psi} + \frac{3}{10}F_{\psi\psi}H_{ss\psi}$$

(5.14)

In the pure spinor projection, this reduces to

$$K_{\lambda\lambda\psi\psi} = \frac{2i}{5}\lambda\gamma_{\psi\psi}\Lambda v^i v^j K_{ij} + Q\text{-exact},$$

(5.15)

that is, the pure spinor projection of the lowest component of the super-5-form is proportional to $K_{ij}$ up to a $Q$-exact term.\footnote{This is not surprising since $QK_{\lambda\lambda\psi\psi} \propto QF_{\lambda\psi}H_{\psi\psi} + F_{\lambda\psi}QH_{\lambda\psi} = 0$ by Bianchi identities and the combination $K_{ij}$ was originally constructed in reference \cite{27} to satisfy specifically this condition.}

The top component of the 5-form $K_{\psi\psi\psi\psi\psi}$ is given in terms of $K_{ij}$ in equation (4.57). Here, we will explicitly compute its flat-space dual $*K_a = \frac{1}{3}sD_{aij}K^{ij}$. The bosonic part evaluates to

$$K_a \bigg|_{\text{bose}} = -\frac{1}{8}D^b(\Phi F_{ab}) - \frac{1}{16}H_{abc}^{-1}F_{bc}$$

(5.16)

where we used the off-shell version of the Maxwell equation

$$D_{aij}X^{ij} = 6i\partial^b F_{ab}.$$  

(5.17)

For the fermionic part, we need the equation

$$D_{\alpha i}F_{\beta j} = 2i\partial_{\alpha\beta}W_i^\gamma + \frac{2}{3}\delta_{\alpha}^\gamma D_{\beta j}X_{ij} - \frac{1}{3}\delta_{\beta}^\gamma D_{\alpha i}X_{ij}$$

(5.18)

and its consequence

$$D_{aij}W^{\gamma j} = 6i\partial_aW_i^{\gamma} - (\bar{\gamma}_a)^{\gamma^j}D_{\delta j}X_{ij}.$$  

(5.19)

With this,

$$K_a \bigg|_{\text{fermi}} = \frac{1}{8}D_k\Phi \partial_a W^k + \frac{1}{8}D_k\Phi \bar{\gamma}_a \gamma_\delta \partial^\delta W^k$$

(5.20)

where we have used the fact that the tensor multiplet is on shell (4.28). It is also due to this condition that $K$ is divergenceless: algebraically,

$$\partial^a K_a = -\frac{1}{16}\partial^a H_{abc}^{-1}F_{bc} - \frac{1}{8}D_k\Phi W^k + \frac{1}{8}D_k\Phi \bar{\gamma}_a \gamma_\delta \partial^\delta W^k$$

and these terms are all proportional to the equations of motion (4.28), (4.29), (4.32) of the tensor multiplet.
5.2.3 The composite 6-form

Finally, we consider the case where both $\tilde{Z}$ and $Z$ describe tensor multiplets $\tilde{V}$ and $V$. The composite 5-form density resulting from this double-tensor can be understood along the lines of the vector-tensor construction of the previous section by replacing $F \rightarrow \tilde{B}$. In particular, $K = \tilde{B} \wedge H$ and the current (5.16), (5.20) gets modified to the form

$$D_{aij}^2 K^{ij} \sim \tilde{\Phi} \partial_a \Phi + \partial^b (\Phi \tilde{B}_{ab}) + H^{(-)}_{abc} \tilde{B}^{bc}$$

$$+ D^\Phi \tilde{\gamma}_a D_k \tilde{\Phi} + D_k \Phi \tilde{\gamma}_a V^k + D_k \Phi \tilde{\gamma}_a \gamma_b \partial^b V^k. \quad (5.21)$$

Note that this composite is not gauge invariant. It also does not generate a gauge invariant 6-form since the current is conserved. Conservation uses the equations of motion of both multiplets and the fact that $H \wedge \tilde{H} \equiv 0$ for any two anti-self-dual forms $H$ and $\tilde{H}$. In the case $\tilde{\Phi} = \Phi$, the first term on each line vanishes. We will return to this form in section 6.2.

The fact that we do not generate a closed 6-form with this bilinear is the composite analogue of the observation in section 4.6 that there is no obstruction to the closure of the 5-form $K_{ij}$ once it satisfies the defining relation $QK = 0$ (4.52). Similarly to the analysis of that section, we can nevertheless define such a composite provided we go beyond bilinears and construct the analogue of $F \wedge F \wedge F$:

$$L_{ss \psi \psi} = \frac{3 \cdot 3}{15} F_{ss} F_{\psi \psi} F_{s \psi} - \frac{3!}{15} F_{s \psi} F_{s \psi} F_{s \psi} = -\frac{2}{5} F_{s \psi} F_{s \psi} F_{s \psi}. \quad (5.22)$$

(Other possibilities include $B \wedge F \wedge F$ and $A \wedge F \wedge H$.) In the pure spinor projection, this becomes

$$L_{ss \psi \psi} \rightarrow \frac{16i}{5} e^{\alpha} v^j v^j v^k (W^3)_{\alpha j k} \quad (5.23)$$

giving the composite analogue $L_{\alpha \beta \gamma}$ of the closed 6-form field strength of section 4.6. Note that the Weyl weight of this composite is $w = 3 \cdot \frac{3}{2} = \frac{9}{2}$ in agreement with the condition (4.64).

6 Applications

In the previous sections we studied the structure of differential forms in six-dimensional, $N = (1, 0)$ superspace. In this section, we present a selection of applications of these results. Topics we have refrained from discussing include applications to covariant superstring compactifications [36, 54, 55] and related superspace gauge theories (e.g. ref. [56]), the new ambi-twistor strings of [57], the construction of superconformal theories with a second, nonlinearly realized supersymmetry [40], superspaces with boundaries [58], and the comparison to interesting recent lower-dimensional results (e.g. ref. [4, 59, 60]). Instead, we restrict our attention to the two applications that most overlap with the results already derived. These are intended only to motivate the use of superforms and do not represent complete analyses.
6.1 Ectoplasm

This work has its origin in failed attempts to construct the density projection formula [61–63] for curved, six-dimensional, \( N = (1, 0) \) projective superspace action [27]

\[
S = \frac{1}{2\pi} \oint_C (v_i dv^i) \int_M d^6x \int d^8\theta E \Theta^{(-4)} \mathcal{L}^{++}
\]

(\( \mathcal{L}^{++} \) is a weight-4 analytic superfield). Generally, the Bianchi identities are solved in curved superspace for a \( p \)-form with \( p \) equal to the dimension of the bosonic space-time. By an extension of Noether’s argument defining conserved charges from conserved currents, the components of this form can be shown to define a curved supersymmetric invariant extending the flat-space component action [67]. This invariant is, then, a natural candidate for the component action in curved superspace.\(^{24}\) Six-dimensional, \( N = (1, 0) \) superspace has the peculiar property of disallowing the straightforward construction of a natural 6-form. The naïve generalization of two known approaches immediately fails for trivial reasons. One of these extends the observation that it is sometimes possible to construct the top form by wedging two middle-dimensional forms [68]. Applied to six dimensions, we expect to obtain the top form corresponding to the projective measure defined in [27] from the wedge of the 3-form with itself. This fails, however, since the 3-form is self-dual so that the associated 6-form vanishes identically in the flat limit. In curved superspace, it fails to produce the \( D^4 \) part of the analytic measure. An attempt to construct a 6-form from other composites (e.g. three 2-forms) does not generate a forth-order operator acting on a scalar Lagrangian and, therefore, also does not represent the curved analytic measure.

A second attempt to guess the 6-form directly may be made by using Berkovits’ Ansatz for the structure of the lowest component of the top form [69]. The proposed component is of the form \( L_{\alpha \beta \gamma abc} \sim (\gamma_{abc})(\alpha \beta f_{\gamma}) \) with \( D_{(\alpha f_{\beta})} = 0 \). However, this component is pure gauge when interpreted as a Weyl tensor superfield as described in section 4.1. In flat superspace, the Berkovits conjecture can be modified in the Biswas-Siegel approach to \( p \)-forms in harmonic superspace [3] by constructing a 7-form with one leg in the harmonic sphere \( \mathbb{C}P^1: \mathcal{L}_{\alpha \beta \gamma \gamma \alpha \beta \gamma abc} \sim (\gamma_{abc})(\alpha \beta D_{\gamma}) \mathcal{L}^{++} \). The superfield \( \mathcal{L}^{++} \) is required to be analytic \( D_{(\alpha} \mathcal{L}^{++} \) and the top component \( \ast K \propto D^{-4} \mathcal{L}^{++} \) reproduces the flat limit of the projective measure of [27]. Somewhat surprisingly, however, the curved superspace Bianchi identities cannot be satisfied for this choice of 6-form: the non-trivial isospin structure of \( \mathcal{L}^{++} \) forces the dimension-1 torsions to vanish. (For example, already the first Bianchi identity implies \( 0 = D^+_{(\alpha D_{\beta)} \mathcal{L}^{++} \propto (\gamma_{abc})_{\alpha \beta} N_{abc} \mathcal{L}^{++} \).)

While it is beyond the scope of this work to investigate the question of integration in projective/harmonic superspace in any depth, the application of our results on differential forms already suggests some preliminary insights. For example, the analysis of section 4.5 suggests that the action for a linear multiplet in curved superspace reduces to the component result

\[
\int_N d^5x e n^a \left\{ (D_{\alpha i}^2 - 48i C_{\alpha ij}) K^{ij} + \frac{4i}{5} \psi^b \gamma_{a b} D_{j} K^{ij} + \frac{6}{5} \psi^b \gamma_{a b} \psi^c K^{ij} \right\}
\]

\(^{24}\)For more recent investigations into the general theory of integration on supermanifolds, we refer the reader to [64–66].
with the integral taken over some 5-dimensional bosonic subspace $N$ of $M$ with normal vector $n$. The full analysis of the four-dimensional analogue of this was carried out in reference \[6\].

In section 4.6, we found that the correct Ansatz for the 6-form was $L_{\alpha s s \psi \psi} = s^i \gamma_{\psi \psi} s^j s^k L_{\alpha ijk}$. Together with the other components derived in that section, we can write down a supersymmetric invariant that, schematically, is given by

$$\int d^6 x e \left\{ \mathcal{D}^5 L + \Psi \mathcal{D}^2 L + \Psi \Psi \mathcal{D} L + \Psi \Psi \Psi L \right\}.$$ (6.3)

If one further solves the constraint (4.64) on the dimension-$\frac{9}{2}$ component as in (4.72), one obtains a formula for covariantizing the component $D_{ijkl}^4 L_{ijkl}$. The method used in \[31, 70\] to obtain the analogous density projection formula starts with precisely such a term and successively constructs the higher components in the gravitino expansion in a Noether-type procedure based on the invariance under projective SL(2; C) transformations of the projective superspace action (6.1). Therefore, if the component result from ectoplasm can be checked to be SL(2; C)-invariant, it should correspond to the density projection formula for the projective superspace action.

### 6.2 Abelian tensor hierarchy

The non-abelian tensor hierarchy \[38–40\] is an attempt to construct a non-abelian gauge theory of forms of degree $p > 1$ by obstructing the closure of the standard Yang-Mills field strength.\footnote{See also \[71, 72\] for details on the tensor hierarchy algebra and applications and \[73\] for extensions to four dimensions.} As we review in appendix B, one introduces a collection of $p$-form potentials $(B^I, C_r, D_\alpha, E_\mu)$ for $p = 2, 3, 4, 5$, respectively, extending the standard Yang-Mills potential $A^r$. A collection of linear maps $(b^I_r, g^{rI}, k_r^s)$ is introduced to obstruct the closure of the $p$-form field strength with a $(p+1)$-form potential. Consistency of this deformation in the non-abelian case requires the extension of the Yang-Mills structure constants $f^{rs}_t$ by a collection of constants denoted by $(d^{Irs}_r, b_{Irs}, c_{aIJ}, c^s_{ar})$. Finally, superpartners are introduced and the whole model is shown to be superconformally invariant.

The first step in this program is the obstruction of the Bianchi identity of a $p$-form field strength with a $(p + 1)$-form field strength. This is precisely the procedure carried out in section 4 to derive the complex of differential forms. Thus, the linearized part of the non-abelian tensor hierarchy is just the construction of this complex. Consider, for example, the case of the vector multiplet field strength $W$. Shifting $W \to W + h(V)$ obstructs the Bianchi identity (4.15) by the term (4.34). As explained in section 4.3.1, this is the superfield defining the 3-form field strength of section 4.3. It satisfies the condition (4.26) which can, in turn, be obstructed by $g(G)$ using the 4-form field of section 4.4.

This interpretation of the differential complex refers only to the linearized part of the hierarchy. We see from equation (5.12), however, that certain non-linear parts are captured by introducing the composite deformations from section 5 alongside the fundamental ones. Indeed, if, after constructing the non-abelian tensor hierarchy, one takes the abelian limit $f \to 0$, one is apparently left with a non-linear theory.\footnote{There is a subtlety concerning the non-triviality of this limit that we address in footnote 30.} It seems to be the case, then, that
the non-linear but abelian part of the hierarchy is precisely the entire differential complex augmented with composite obstructions. In this sense, one may think of the non-abelian tensor hierarchy as a non-abelian deformation of this complex or “non-abelian ectoplasm” in the terminology of section 6.1. Such structures should be closely related to the gravitational tensor hierarchies of references [74, 75] appearing in gauged supergravity. For recent applications to self-dual non-gravitational theories and their actions, see also [76–79]. Although demonstration of the complete equivalence of the two sides and the non-abelian extension of them is beyond the scope of this paper, some non-trivial comparisons can be made with the results already worked out. The obstructed closure condition (5.13) is central to the construction of the non-abelian tensor hierarchy in which it appears in the form

\[ d\mathcal{H} = d(F,F) + g(\mathcal{G}). \]  

(6.4)

Here,

- \( d \) is the symmetric bi-linear form (extended to act by wedge product on forms) on the space of vector multiplets valued in the space of tensor multiplets,
- \( F = F + h(B) \) is a deformation of the non-abelian 2-form field strength \( F = dA \) by a gauge 2-form \( B \),
- \( H = H + g(C) \), is a deformation of the 3-form field strength \( H = dB \) by a gauge 3-form \( C \), and
- \( G = G + k(D) \), is a deformation of the 4-form field strength \( G = dC \) by a gauge 4-form \( D \) although this term does not enter into the hierarchy at this level since \( g \circ k = 0 \).

As we have seen in section 4.4 and 5.2.1, this condition results from sourcing the defining equation of the tensor superfield strength (5.12). Therefore, provided we shift the pure spinor superfields \( W \rightarrow W = W + h(V) \), we can capture the \( b, c, c' = 0 \) sector of the hierarchy in curved superspace with the constraint

\[ (D_i \tilde{\gamma}_a D_j + 16iC_{aij}) \Phi = d(W_i \tilde{\gamma}_a W_j) + g(G_{aij}) \]  

(6.5)

defining the deformed 3-form \( \mathcal{H} \).

It was shown in reference [77] that the \( p \)-form field strengths with \( p \geq 4 \) are all composite. Therefore, at least when formulated in terms of field strengths, it is possible that this constraint already encodes the entire abelian hierarchy. In fact, the composite “current” (5.6) has a natural extension by the associative \( * \)-product of appendix B to \( G_{aij} \sim b(W,V) + k \circ c(V,V) \). Associated to this field is a composite linear superfield \( K_{ij} \) (5.10). An important set of constraints (cf. eq. (3.7) of ref. [38]) in the non-abelian tensor hierarchy is given in superspace by setting

\[ b(K_{ij}) = 0. \]  

(6.6)

In the context of section 5.2, this equation implies that the 4-form Bianchi identities are satisfied when the composite obstruction is mapped to the space of 4-forms by \( b \). Equations (5.16) and (5.20) then imply the deformed closure condition (cf. eq. (3.39) and (3.43).
of reference [77])

\[ dG = b(F, H) + k(K), \]  

(6.7)

where \( K \) stands for the terms given in equation (5.21). These terms make up the composite 5-form of the tensor hierarchy (cf. eq. (3.43) and (3.49) of reference [77]) in the \( c' \to 0 \) limit.\(^{27}\) Thus, we have found that this level of the hierarchy is compactly described by equation (6.5).

By (a deformation of) the discussion in section 4.3.1, the condition (5.13) is equivalent to

\[ QV = d(A, W), \]  

(6.8)

provided we describe the tensor \( \Phi \) in terms of its potential \( V \).\(^{48}\) Using our shifted fields, we can attempt to write the analogous expression for (6.5) in pure spinor superspace. The naïve guess is \( QV = d(A, W) + g(C) \) for the 3-form potential \( C \) described in section 4.4.1. However, according to [77], the associated field strength \( G \sim dC \) is composite. In fact, it is precisely the composite appearing because the Bianchi identities of dimension \( \geq 3 \) do not close. Therefore, it may even be that an equation of the form

\[ DA + A \star A = 0 \text{ with } D = Q + \partial \text{ and } A \in \Omega^\bullet \otimes K^\bullet, \]  

(6.9)

by itself already describes the entire hierarchy in the abelian limit.\(^{28}\) Work is currently underway to investigate this idea and extend it to the full non-abelian hierarchy. For recent closely-related work on such a construction for the bosonic part of the non-abelian tensor hierarchy, see [80, 81] and references therein.

7 Conclusion

In this work we have augmented the curved six-dimensional, \( N = (1, 0) \) superspace [27] (reviewed in appendix A) with a supercommutative ring of variables (2.2) and exploited its structure to reformulate the superspace analogue of the de Rham complex of differential forms.\(^{29}\) The augmented complex has a “pure spinor” subcomplex (cf. section 3) that is preserved by a second conformal algebra. This construction, roughly speaking, can be interpreted as extending the six-dimensional projective superspace to a super-CR manifold the Lagrangian distribution of which is generated by (3.5). On this subspace the curved superspace spinor derivative reduces to a differential (3.6). Tensor superfields on this subspace that are in the cohomology of this differential define large classes of superconformal primary superfields. They are classified by their Dynkin labels, in terms of which one trivially computes their scaling weights.

\(^{27}\)As we have restricted ourselves to quadratic bilinears in section 5.2, we will not generate the \( c' \) contributions of the full tensor hierarchy here.

\(^{28}\)It may be of interest to recall here that the complex of \( p \)-forms was determined uniquely by applying the obstruction procedure to the condition \( F_{ss} = 0 \). At the beginning of section 4.2, it was explained that this condition is equivalent to the formula \( QA = 0 \).

\(^{29}\)The flat superspace version of this was recognized in [8] as (a “free resolution” of) the Chevalley-Eilenberg complex of the super-translation algebra with values in superfields.
Certain such superconformal primary superfields are the defining superfields from which de Rham forms are constructed in section 4. Roughly, each of these is the lowest-weight member of its respective family. Some forms have alternative representations which also fit naturally into the classification. Composite forms are gotten by multiplying the fundamental forms together. On the pure spinor subcomplex this induces the structure of a differential graded superalgebra. Peculiarities of the superfield structure of certain forms are elucidated by this observation (cf. e.g. section 5.2.2 for the geometrical origin of the projective Lagrangian for systems of tensor and vector multiplets in projective superspace [27]).

Finally, we singled out two particular examples for applications of our results, the full investigations of which are beyond the scope of this work. The first of these is an initial attempt at finding the density projection formula for the projective superspace integral which was the original motivation to consider the differential forms investigated in this work. The second application is to the theory of superconformal models in six dimensions with (at least) $N = (1,0)$ supersymmetry. Specifically, we make a superficial attempt marry the DG algebra structure of the pure spinor subcomplex to the algebraic structure of the non-abelian tensor hierarchy [38–40] (reviewed in appendix B).

Throughout this work, we have relied rather heavily on the notational and calculational simplifications afforded us by the use of auxiliary variables. Stripping off the original supercommutative variables reduces the results to ordinary superspace formulæ. Passing first to the pure spinor subspace and then stripping off only the pure spinor variables, one recovers the analogous results in projective superspace. In this sense, the use of the auxiliary variables is purely a convenience. Nevertheless, we have found the additional structure of such augmented superspaces to be very useful in the theoretical and computational analyses of problems in curved superspace. We hope that our presentation was effective in conveying these, what we perceive to be, significant advantages.

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A Curved six-dimensional superspace

In this appendix, we collect the results on six-dimensional, \(N = (1, 0)\) supergravity used in our analysis of superforms in curved space-time. A detailed understanding of this material is not absolutely necessary to follow the discussion in the main text and serves mainly to fix some notation and introduce the supergravity torsion fields. For additional details, see references [27] and [82].

We denote the local coordinates on curved, six-dimensional, \(N = (1, 0)\) superspace by \((z^M) = (\theta^{\mu i}, x^m)\). The covariant derivative \((D_A) = (D_{\alpha i}, D_a)\) expands out to

\[
D_A = E_A + \Omega_A + \Phi_A
\]

where

\[
E_A = E_A^M \partial_M, \quad \Omega_A = \frac{1}{2} \Omega^M_{\alpha \beta} M_{\alpha \beta}, \quad \Phi_A = \Phi_{\alpha i}^J J_{ij}
\]

are the coframe, spin connection, and SU(2) connection, respectively. The generators of the superalgebra \(\text{spin}(5,1) \oplus \text{sp}(1) \subset \text{osp}(6,2|1)\) are defined by their action on the spinors as

\[
[M_{ab}, D_\gamma^k] = -\frac{1}{2} (\gamma_{ab})^\delta \delta_{\delta k}^\gamma \quad \text{and} \quad [J_{ij}, D_\gamma^k] = -\varepsilon_{k(i} D_{\gamma j)}.
\]

The graded commutation relations of the covariant derivatives define torsions, curvatures, and field strengths

\[
[D_A, D_B] = T_{AB} C_{CD} + \frac{1}{2} R_{AB}^{\text{cd}} M_{\text{cd}} + F_{AB}^{ij} J_{ij}.
\]

We will work with the supergeometry defined by the relations

\[
\{D_{\alpha i}, D_{\beta j}\} = 2i \varepsilon_{ij} (\gamma^a)_{\alpha \beta} D_a + 2i C_{\alpha ij} (\gamma^{abc})_{\alpha \beta} M_{bc} + 4i \varepsilon_{ij} N^{abc} (\gamma_a)_{\alpha \beta} M_{bc}
\]

\[
- 6i \varepsilon_{ij} C_{\alpha kl} (\gamma^a)_{\alpha \beta} J_{kl} - \frac{8i}{3} N^{abc} (\gamma_{abc})_{\alpha \beta} J_{ij}
\]

\[
[D_\gamma^k, D_a] = C_{k}^{\beta \delta} (\gamma_{ab})^\gamma D_{\delta l} + N_{abc} (\gamma^{bc})^\gamma D_{\delta k} + \frac{1}{2} R_{\gamma ka}^{\text{bc}} M_{bc}
\]

\[
+ \left( (\gamma_a)_{\gamma \delta} C_{k}^{\delta ij} - 6\delta_k^i C_{a \gamma}^j + 5\delta_k^i (\gamma_a)_{\gamma \delta} \left[ C^{\delta j} - \frac{1}{3} N^{\delta j} \right] \right) J_{ij}.
\]

The curvature term of dimension-\(\frac{3}{2}\) is an unilluminating function of the dimension-\(\frac{3}{2}\) torsion so we do not reproduce it here. The dimension-\(\frac{3}{2}\) torsion components \(C\) and \(N\) appear in the higher components of the p-forms. Their definitions are as the irreducible components

\[
D_\gamma^k C_{a ij} = C_{a \gamma k}^i j + (\gamma_a)_{\gamma \delta} C_{k}^{\delta ij} + \varepsilon_{k(i} C_{a \gamma j)} + \varepsilon_{k(i} (\gamma_a)_{\gamma \delta} C_{j)}^\delta
\]

\[
D_\gamma^k N_{\alpha \beta} = N_{\gamma k}^\alpha \beta + \tilde{N}_{\gamma k}^\alpha \beta
\]

\[
D_\gamma^k N^{\alpha \beta} = \tilde{N}_{\gamma k}^\alpha \beta + \delta^\alpha_\gamma N_k^{\beta}.
\]
These components are constrained by the supergravity Bianchi identities to be \[ \begin{align*}
C_{\alpha \gamma k ij} &= 0 \\
C_{ijkl} &= \frac{1}{6} (\gamma^b \delta^k \delta^j D_{b(k} C_{b ij)}) \\
N_{\gamma k \alpha \beta} &= 0 \\
N_{\gamma k \alpha \beta} &= -\frac{3}{4} (\gamma^a)_{\gamma (a \alpha} C_{b \beta) k} \\
C_{\alpha \beta ij} &= \frac{2}{3} \Pi^\gamma_{\alpha \gamma} D^i C_{a ij} \\
C_{\gamma k} &= \frac{1}{9} D_{a i} C^\delta \gamma l k \\
N_{\alpha i} &= 2 \delta^\delta_\gamma \gamma_{\alpha}^\beta \\
N_{\alpha \beta} &= -\frac{2}{5} D_{\beta} \gamma_{\beta \alpha} ,
\end{align*} \] (A.7)
where
\[ \Pi^{b \beta}_{a \alpha} = \delta^b_a \delta^\beta_\alpha + \frac{1}{6} (\gamma^a)_{\gamma b} \gamma^b_\alpha \] (A.8)
is the projector onto the $\gamma$-traceless subspace of the spinor-vector representation: $\Pi^{b \beta}_{a \alpha} (\gamma_b)_{\beta \gamma} = 0$ and $(\gamma^a)_{\gamma \alpha} \Pi^{b \beta}_{a \alpha} = 0$.

Super-Weyl transformations preserving this geometry are generated by a real, unconstrained, scalar superfield $\sigma(z)$. The transformations that preserve the covariant derivative algebra act as
\[ \delta D_{\alpha i} = \frac{1}{2} \sigma D_{\alpha i} - 2 (D_{\beta i} \sigma) M_{\alpha \beta} + 4 (D_{a j} \sigma) J_{ij} \] (A.9)
\[ \delta D_a = \sigma D_a - \frac{i}{2} (D^k \sigma) \tilde{\gamma}_a D_k - (D^b \sigma) M_{ab} - \frac{i}{8} (D^l \tilde{\gamma}_a D_l \sigma) J_{ij} \] (A.10)
on the covariant derivatives and as
\[ \delta C_{\alpha i j} = \sigma C_{\alpha i j} + \frac{i}{8} (D_{(i} \tilde{\gamma}_c D_{j)}) \sigma \] (A.11)
\[ \delta N_{abc} = \sigma N_{abc} - \frac{i}{32} (D^k \tilde{\gamma}_{abc} D_k \sigma) \] (A.12)
on the dimension-1 torsions.

In section 2 we introduce a commuting spinor $s^{\alpha i}$ that plays the role of $d \theta^{\alpha i}$ in the algebra of exterior superforms. The product of two of such basis elements decomposes into two parts
\[ s^{\alpha i} s^{\beta j} = -\frac{1}{8} \varepsilon^{ij} (\gamma^a)_{\alpha \beta} \gamma^a (s, s) + \frac{1}{48} (\gamma^{abc})_{\alpha \beta} \omega^{ij}_{abc} (s, s) \] (A.13)
where we have defined the vector and self-dual 3-form components
\[ \gamma^a (s, s) := s^k \gamma^a s_k \quad \text{and} \quad \omega^{ij}_{abc} (s, s) := s^i (\gamma^{abc} s^j) . \] (A.14)
The vector $\gamma^a (s, s)$ is null as follows from the general identity
\[ (s^l \gamma^a s_l)(s^j \gamma_\alpha s_j) = 0 \] (A.15)
which holds for any chiral spinor $\xi$ (because $(\gamma^a)_{\alpha \beta} (\gamma_a)_{\gamma \delta} = 2 \varepsilon_{\alpha \beta \gamma \delta}$ whereas the isospin indices range only over 2 values). It is also orthogonal to the triplet of 3-forms $\gamma^a (s, s) \omega^{ij}_{abc} (s, s) = 0$ Many Fierz identities can be derived from these basic relations by polarizing on $s$ (i.e. replacing $s \rightarrow s + t + u$, expanding, and collecting like powers).
Projecting $s \mapsto \lambda \otimes v$ to the product of a commuting chiral spinor $\lambda^\alpha$ and isotwistor $v^i$ kills the vector part and isolates the self-dual 3-form part of the bilinear. A chiral spinor with the property

$$\lambda^\alpha \lambda^\beta = \frac{1}{3!} \Gamma^{abc} \gamma_{abc} \lambda$$

(A.16)

is called pure (see e.g. reference [83]) so we will refer to this projection as the pure spinor projection.

The constant, commuting spinor $s$ combines with the covariant derivative to define the odd derivation $D_s = s^\alpha D_\alpha$ which squares to

$$D_s^2 = iD_{\gamma(s,s)} + 2iN_{\gamma(s,s)ab} M_{ab} - 3iC_{\gamma(s,s)}^{ij} J_{ij} + i\omega_{ij}^{abc}(s,s) \left( C_{cij} M_{ab} - \frac{4}{3} N_{abc} J_{ij} \right).$$

(A.17)

In section 2, we define the projected derivation $Q = D_{\lambda \otimes v}$. Its square reduces to

$$Q^2 = i(\lambda \gamma^{abc}) v^i v^j \left( C_{cij} M_{ab} - \frac{4}{3} N_{abc} J_{ij} \right).$$

(A.18)

In section 3, we introduce a complex of spaces on which this square vanishes, thereby promoting $Q$ to a differential.

B The non-abelian tensor hierarchy

In section 6.2, we describe an application of the results on the structure of fundamental and composite $p$-forms to the (abelian part of the) non-abelian tensor hierarchy [38–40]. In this appendix, we review very briefly the underlying cohomological structure of this hierarchy and propose a reformulation of it in terms of a generalized field strength satisfying a Maurer-Cartan equation.

The non-abelian tensor hierarchy is built on a collection of $p$-form gauge fields $(A^r, B^I, C_r, D_\alpha, E_\mu)$ where $p = 1, 2, 3, 4, 5$, respectively. The representation indices take values in a collection of vector spaces that fit into a chain complex

$$K_\bullet = \ldots \longrightarrow K_3 \xrightarrow{\partial} K_2 \xrightarrow{\partial} K_1 \xrightarrow{\partial} K_0 \longrightarrow 0.$$  

(B.1)

Here the representation space of a gauge $p$-form is denoted by $K_{p-1}$. The first few terms of the differential are denoted by $(\partial_1, \partial_2, \partial_3) = (h, g, k)$.

Introduce the de Rham complex

$$\Omega^\bullet = 0 \longrightarrow \Omega^0 \xrightarrow{d} \Omega^1 \xrightarrow{d} \Omega^2 \xrightarrow{d} \Omega^3 \longrightarrow \ldots$$

(B.2)

and consider the double complex $\Omega^\bullet \otimes K_\bullet$ with differential $D = d + \partial$. Let $A$ denote an element of total degree 1 so that $A$ represents the collection $(A^r, B^I, C_r, D_\alpha, E_\mu)$ of bi-degrees $(1, 0), (2, -1), (3, -2), (4, -3), (5, -4)$, respectively. Then

$$F := DA$$

(B.3)
is a form of total degree 2 representing $(F^r, H^I, G_r, K_\alpha, L_\mu) = (dA^r + h^I_r B^I, dB^I + g^{I r} C_r, dC_r + k^\alpha_r D_\alpha, dD_\alpha + \nu^\alpha_\mu E_\mu, dE_\mu)$. Then

$$DF = 0 \iff \begin{align*}
    dF^r &= h^I_r H^I \\
    dH^I &= g^{I r} G_r \\
    dG_r &= k^\alpha_r K_\alpha \\
    dK_\alpha &= \nu^\alpha_\mu L_\mu \\
    dL_\mu &= 0.
\end{align*} \quad (B.4)$$

Analogously to the algebra structure given to the de Rham complex by the wedge product, it turns out that $K_\bullet$ can be given an algebra structure by defining a collection of maps

$$* : K_p \times K_q \to K_{p+q+1}. \quad (B.5)$$

When we wish to distinguish them, we will denote the non-vanishing restrictions of the product by $(d^I_{rs}, b_{Irs}, c_{\alpha IJ}, c^s_{\alpha r})$ [38]. Together with the tensors defining the differential on $K_\bullet$, these define an action

$$\triangleright : K_0 \times K_\bullet \to K_\bullet \quad (B.6)$$

of $K_\bullet$ on itself shown in reference [84] to make the $*$-product associative $(a * b) * c = a * (b * c)$ and the action $\triangleright_X$ a derivation $\triangleright_X (a * b) = (\triangleright_X a) * b + a * (\triangleright_X b)$ of the resulting algebra $\forall a, b, c \in K_\bullet$. Here, we will extend this product to the double complex by wedge, that is, we interpret $*$ on the double complex to mean $*$ on $K_\bullet$ together with $\wedge$ on $\Omega^\bullet$.

We are now in a position to use the $*$-product to deform the closure condition (B.4) on $F$. To do this, one should first extend the differential on the double complex to a connection $\nabla = D + \triangleright_A$. With this, one can define the non-abelian field strength $F := \nabla^2$. Finally, one writes $\nabla F + F * F = 0$.

The non-abelian tensor hierarchy appears to have a non-linear abelian limit obtained by setting $f \to 0$ after deforming the complex with the $*$-product.\(^{30}\) For simplicity, we will work in this limit. Then the deformed version of the closure condition (B.4) may be postulated to be the Maurer-Cartan equation

$$DF + F * F = 0. \quad (B.7)$$

This equation expands out to

\begin{align*}
    dF^r &= h^I_r H^I \quad (B.8a) \\
    dH^I &= g^{I r} G_r + d^I_{rs} F^r \wedge F^s \quad (B.8b)
\end{align*}
\[ dG_r = k^\alpha_r K_\alpha + b_{Irs} F^s \wedge H^I \]  
(8c)

\[ dK_\alpha = \nu^\alpha_{\mu} L_\mu + c_{\alpha IJ} H^I \wedge H^J + c_{\alpha rs} F^r \wedge G^s \]  
(8d)

\[ dL_\mu = 0. \]  
(8e)

In section 6.2 we connect this construction to the sourced and composite \( p \)-form complices of sections 4 and 5. For recent work in this direction, see [80, 81].

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