A Differential Pressure Technique for Void Fraction Measurement in Gas-Liquid Flow

Ammar ZEGHLOUL, Abdelwahid AZZI, Nabil GHENDOUR, and Abdallah S. BERROUK

Abstract—Two-phase Gas-liquid flows have many industrial uses, such as hydrocarbon transportation and energy production. The knowledge and an accurate determination of the gas phase’s proportion rate in the two-phase mixture known as the gas void fraction is necessary for optimal and secure sizing of the installations where this kind of flow takes place. This paper focuses on the possibility of using a cost-effective differential pressure transmitter to measure the void fraction parameter. It is obtained using a mathematical model derived from the energy balance equation and the measured pressure drop from the vertical upward gas-liquid flow. Results on flow void fraction obtained through the use of the conductance probe method, are used to validate those derived from the pressure drop that is evaluated by employing the differential pressure transmitter. The measurement accuracy of the void fraction measured using the pressure drop technique, is found to be principally affected by the flow pattern. Moreover, the slip ratio between the phases was the primary factor influencing the void fraction measurement by the differential pressure technique.

Keywords—Two-phase flow, Void fraction, Flow pattern, Differential pressure, Transmitter.

NOMENCLATURE

| Symbol | Description |
|--------|-------------|
| D      | Diameter of the pipe, m |
| f      | Single-phase friction factor |
| g      | Acceleration of gravity, m/s² |
| h      | Pressure tapping vertical distance, m |
| P      | Pressure at the tapping, Pa |
| Re     | Reynolds numbers |
| S      | Slip ratio |
| Uₘ     | Mixture velocity, m/s |
| U₇      | Gas velocity, m/s |
| U₇G    | Gas superficial velocity, m/s |
| U₇L    | Liquid velocity, m/s |
| U₇L      | Liquid superficial velocity, m/s |
| x      | Mass flow quality |
| εG      | Gas void fraction |
| ΔP     | Pressure drop, Pa |
| ρₗ      | Liquid density, kg/m³ |
| ρ₇      | Gas density, kg/m³ |
| ρₗG     | Two-phase mixture density, kg/m³ |
| G      | Gas |
| L      | liquid |
| m      | mixture |
| TP     | two-phase flow |

In two-phase or three-phase flow hydrodynamics, the void fraction represents one of the most critical parameters. It gives information about the fraction of the gas in the pipe's total surface or volume. Moreover, the void fraction is a crucial parameter in predicting the interfacial section and the mass transfer between different phases [1].

Several invasive or non-invasive techniques have been proposed in the literature to predict the void fraction parameter. Among these techniques, one can cite the estimation of void fraction via the time-averaged two-phase pressure drop measurement. This technique is widely used because of its simplicity, high safety, low-cost, and for being non-intrusive. Additionally, the two-phase pressure acquisition signals can be used in two-phase flow pattern recognition [2][3].

Many works have been done in order to establish a correlation between the void fraction and the measured two-phase pressure drop. However, these correlations were not reliable for all flow patterns. In the earlier work, Wallis [4] correlates the liquid holdup (1-εG) as a function of Lockhart and Martinelli’s parameter, which depends on the two-phase pressure drop. Tang and Heindel [5] proposed a new method to estimate the void fraction from the differential pressure measurement in bubble columns. The proposed method highlighted the pressure drop's influence due to friction on the void fraction measurement. Their experimental data analysis showed that the proposed method gives more accurate void fraction results than the model proposed by Wallis. As Gharat and Joshi [2] stated, the frictional two-phase pressure drop depends mainly on two factors. One of them depends on the shear stress between the liquid and the conduit wall, and the second is the friction between the liquid and the gas phases. On the other hand, the experimental work presented by Shaqout et al. [6] considered the frictional parameter negligible. In their study, the tested flow condition covered the bubbly flow pattern with the range of the void fraction [0.17 to 0.33]. They used Electrical Capacitance Tomography technique, ECT, as another technique to validate the void fraction predicted results. Abbas [7] performed a theoretical and experimental study for the bubbly flow regime, considering the value of the void fraction.
less than 0.1748. They proposed a mathematical model derived from the two-phase pressure drop measurement to estimate the gas proportion. However, the experimental results showed that the proposed model is not suitable when the void fraction increases beyond 17.48%. Jia et al. [8] conducted an experimental study in vertical upward bubbly and slug flows. To obtain the void fraction, two-phase pressure drop measurement data were introduced into a mathematical model that was based on the energy conservation. The latter was compared to the ones obtained from Electrical Resistance Tomography, ERT, device and Wire Mesh Sensor, WMS. The experimental investigations showed that the frictional pressure drop could not be neglected mostly for a gas volume fraction less than 0.2. Kara et al. [9] performed a comparison of the void fraction values derived from the pressure drop experimental data and those by measuring the difference in the level between the two-phase mixture and the one of the static liquid in a bubble column. They found that both measurement techniques matched well with an accuracy of 3%.

The present experimental study consists in investigating the derivation of the void fraction using differential pressure measurement. Moreover, the effect of the flow pattern on the void fraction measurement accuracy is discussed.

II. THEORETICAL BACKGROUND

The mathematical correlation relying the void fraction and differential pressure measurement is based on Bernoulli’s energy conservation principle. According to the diagram in Figure 1. One can write;

\[ P_1 = P_2 + \rho_{TP} g h + \Delta P_{friction} \]  

(1)

where \( P_1 \) and \( P_2 \) are the measured pressures at two selected positions along the pipe, \( \rho_{TP} \) is the two-phase density, \( g \) is the gravitational acceleration, \( h \) is the distance between the two measurement points and \( \Delta P_{friction} \) the frictional pressure drop.

\[ \Delta P_{read} = P_2 + \rho_L g h - P_1 \]  

(2)

Eq. 1 and Eq. 2 lead to;

\[ \Delta P_{read} + \Delta P_{friction} = g h (\rho_L - \rho_{TP}) \]  

(3)

The two-phase density \( \rho_{TP} \) is expressed as follow:

\[ \rho_{TP} = \varepsilon_G \rho_G + (1-\varepsilon_G) \rho_L \approx (1-\varepsilon_G) \rho_L \]  

(4)

where \( \varepsilon_G \) is the void fraction.

Replace Eq. 4 into Eq. 3 and solving for void fraction \( \varepsilon_G \) reads:

\[ \varepsilon_G = \frac{(\Delta P_{read} + \Delta P_{friction})}{(\rho_L - \rho_G) g h} \]  

(5)

According to [7], the pressure drop due to friction is:

\[ \Delta P_{friction} = \frac{2 \rho_L h}{D} U_m^2 \]  

(6)

Where \( U_m \) represents the mixture velocity, \( D \) is the internal pipe diameter, \( f \) the single-phase friction factor, also known as the Fanning friction factor, which depends on flow conditions and the pipe wall roughness. In our experiment, the pipe material is Perspex, which can be considered a smooth surface.

The friction factor, \( f \), can be obtained experimentally by employing the following expression [7];

\[ f = \frac{\Delta P_L}{2 \rho_L h U_L^2} \]  

(7)

Where \( \Delta P_L \) is the measured liquid pressure drop, and \( U_L \) is the liquid velocity.

A different form of Fanning friction factor can be found in the literature, which depends on Reynolds numbers, \( Re \). In the present work, the Reynolds numbers test conditions were ranged from 3500 to 30600. The corresponding Fanning friction factor \( f \) is expressed as;

\[ f = 0.079 Re^{-0.25} \]  

(8)

III. EXPERIMENTAL FACILITY

The test facility performed to carried out measurements of the pressure drop and the void fraction simultaneously is presented in Figure 2. This test facility has been used earlier by Zeghloul et al. [10][11]. The test section, which is transparent for visual observation of the flow regime is positioned vertically. Its length is about 6m with an inner diameter of 34mm. A centrifugal pump (9), which can reach a maximal mass flow rate of 40 m³/s, draws tap water from the tank (10) to the mixing section through calibrated water rotameters (4). A pressure regulator (2) was used to adjust the air supplied from a compressor (1) to the operating pressure before it passes through the air rotameters (5). Both air and water flow-meters have a maximum uncertainty of 2%. The two-phases are blended in the mixer (8) to create the air-water mixture. Further information on the mixer geometry is given in Zeghloul et al. [12], [13]. After the mixer, the gas and liquid phases flow through the test section then continues up to the separator (10). The liquid flowed down to the separator's bottom due to gravity, and the gas (air) flows into the ambient.

Two conductance probes have been installed in the vertical test section to provide the gas volume fraction, \( \varepsilon_G \). The first conductance probe, CP1, was placed at 4760 mm (140D) downstream of the mixer, and the second probe, CP2, at a distance of 790 mm after the first probe. These two positions were chosen carefully to ensure enough distance to allow the flow to be fully developed Saidj et al. [14].
To increase the measurement accuracy, two selected differential pressure transmitters have been used to measure the difference in pressure between the two tappings. The latter has the exact locations as the two conductance probes CP1 et CP2. The two transmitters were provided from FOXBORO company with 0.2% accuracy corresponding to their full scale with ranges of [0-7.2] kPa and [0-36] kPa, respectively. Using an appropriate pressure calibrator (Fluke 725) with an error of 0.02%, the two transmitters were further re-calibrated.

Before starting the pressure measurements, it is necessary to ensure that the pressure sampling lines have a constant fluid density, i.e., the pressure lines contain only liquid without any air bubbles inside. Therefore, a purging arrangement has been used to evacuate air bubbles from the pressure sampling lines, as shown in Figure 3.

A data acquisition card (6092E) and the corresponding LabVIEW software from National Instruments Company, was used to acquire all the necessary data from the different experiments. 200 Hz was the sampling frequency of the data acquisition for a duration of 60 seconds for each test, i.e., total data samples of 12000 for each run.

The test experimental conditions of the gas and liquid superficial velocities varied from 0 to 3.5 ms\(^{-1}\) and from 0.1 to 0.92 ms\(^{-1}\), respectively, which cover a wide flow pattern range from bubbly to churn flows. The two-phase flow configuration was first visually observed through the Plexiglas pipes near the pressure tapings. At these locations, the flow regime is considered to be entirely developed. These flow observations were confirmed by analyzing the signature shape of the Probability Density Function (PDF) and the temporal variation of the acquired gas volume fraction signals (Bouyahiaoui et al. [16], Costigan and Whalley[17]).

From Figure 4, A total number of 121 experimental test conditions were plotted over the flow pattern map of Shoham [18]. From this figure, one can note that the slug flow test conditions have taken a large area in Shoham’s map. Furthermore, the transition line between the bubbly and the slug flow shows a good prediction of the experimental test conditions. However, the slug/churn line transition poorly predicts the experimental data. This overprediction may be due to the difference in the experimental conditions used in predicting the slug/churn line transition.

IV. EXPERIMENTAL RESULTS

A. Flow Pattern Map

The test experimental conditions of the gas and liquid superficial velocities varied from 0 to 3.5 ms\(^{-1}\) and from 0.1 to 0.92 ms\(^{-1}\), respectively, which cover a wide flow pattern range from bubbly to churn flows. The two-phase flow configuration was first visually observed through the Plexiglas pipes near the pressure tapings. At these locations, the flow regime is considered to be entirely developed. These flow observations were confirmed by analyzing the signature shape of the Probability Density Function (PDF) and the temporal variation of the acquired gas volume fraction signals (Bouyahiaoui et al. [16], Costigan and Whalley[17]).

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B. Void Fraction Temporal Variation

Figure 5 illustrates example plots of the void fraction temporal variation obtained from the two conductance probes (CP1 and CP2). Three different velocities combination of liquid and gas has been chosen to exhibit the various flow patterns studied in this work. It can be observed from the void fraction temporal variation that the two conductance probe signals are very close to each other, which confirms that the flow pattern is thoroughly
developed [14]. Figure 5 (a) shows the typical void fraction signal of bubbly flow. The latter is often characterized by stable fluctuations with some small peaks that indicate both agglomerated and dispersed bubbles. The mean void fraction of the corresponding bubbly flow is about 0.19. Figure 5 (b) depicts the slug flow void fraction temporal variation that was represented by an alternative value of the void fraction. The void fraction values of the threshold corresponding to the passage of Taylor bubbles, and the low void fraction values representing the liquid plug, which contain tiny bubbles. The mean void fraction value of the corresponding slug flow is found to be 0.45. Figure 5 (c) represents a typical void fraction temporal variation of the churn flow. This flow pattern signals and appearance show a chaotic behavior with a mean void fraction of 0.81.

Figure 4: Temporal variation of the void fraction, (a), bubbly flow [$U_{ls}=0.80\text{ m.s}^{-1}$, $U_{gs}=0.10\text{ m.s}^{-1}$], (b), slug flow [$U_{ls}=0.40\text{ m.s}^{-1}$, $U_{gs}=0.43\text{ m.s}^{-1}$], (c), churn flow [$U_{ls}=0.21\text{ m.s}^{-1}$, $U_{gs}=3.01\text{ m.s}^{-1}$].

C. Single and Two-Phase Flow Pressure Drop

The measured two-phase gas-liquid pressure drop, $\Delta P_{\text{read}}$, from the differential pressure transmitter was fed into the equation (2) to obtain the total pressure difference ($P_1 - P_2$). Figure 6 represents the gas-liquid total pressure drop variation depending on the gas superficial velocity by keeping the liquid superficial velocity constant. From this figure, one can see for a particular gas superficial velocity that the gas-liquid total pressure drop increases with the liquid superficial velocity's augmentation. Furthermore, and by keeping the liquid superficial velocity constant, the two-phase total pressure drop decreases with the increase of the gas superficial velocity.

Figure 5: Temporal variation of the void fraction, (a), bubbly flow [$U_{ls}=0.80\text{ m.s}^{-1}$, $U_{gs}=0.10\text{ m.s}^{-1}$], (b), slug flow [$U_{ls}=0.40\text{ m.s}^{-1}$, $U_{gs}=0.43\text{ m.s}^{-1}$], (c), churn flow [$U_{ls}=0.21\text{ m.s}^{-1}$, $U_{gs}=3.01\text{ m.s}^{-1}$].

This finding can be clarified by the expansion of the gas in the gas-liquid flow due to gas superficial velocity increasing, which required less energy for the gas-liquid mixture to flow inside the pipe [14][19]. Besides the effect of the gas and liquid velocities, the way that the gas-liquid total pressure drop evolves in each flow pattern is not the same; the latter is very important for the bubbly flow and less when passing to the slug flow. The gas-liquid total pressure drop is nearly constant for the churn flow.

Figure 6: Total gas-liquid differential pressure vs. gas superficial velocity.

Figure 7 represents the calculated two-phase frictional pressure drop for different velocity combinations of the gas and the liquid. The corresponding data of the frictional pressure drop was derived from equation (3). From this figure and by maintaining a liquid superficial velocity constant, one can remark that the two-phase frictional pressure drop increases with the increase of the gas superficial velocity. The same behavior of the frictional pressure drop was noticed for a constant gas and variable liquid velocity. Besides the gas and liquid velocities’ impact, the flow pattern was also found to affect the frictional two-phase pressure drop. The latter can be noticed from the different slopes of the frictional pressure drop, which characterizing each liquid superficial velocity. The sharpest slope was found in the churn flow. This may be caused by the turbulent effect of this kind of chaotic flow pattern, which enhances friction between phases and between the gas-liquid mixture and the pipe inside wall.

Figure 7: Gas-liquid frictional pressure drop vs. gas superficial velocity.

The measured single-phase (liquid) pressure drop was injected into equation (7) to find the experimental friction factor, $f$. 
The actual friction factor data and those calculated from Fanning correlation (Eq. (8)) and the experimental data of Abbas [7] are represented in Figure 8. From this figure, one can notice a good fit of the actual data to the experimental data of Abbas and fanning correlation for the conditions of liquid superficial velocity, Uls, over 0.4 ms⁻¹. For Uls, less than 0.4 ms⁻¹, we found some difference between the represented data with a relatively good approach between the actual data and the Fanning correlation. This may be due to the accuracy of the differential pressure device when it is used in the low gas and liquid velocity conditions.

**Fig. 8**: Friction factor variation with water superficial velocity.

It can be inferred from Figure 9 that, for ε₉ < 0.30, the void fraction predicted from differential pressure measurement agrees well with the measured one. For ε₉ > 0.30, the deviation from the diagonal line increases with the void fraction. The deviation can reach 30% as the flow pattern approaches the slug/churn transition, which corresponding to the void fraction of about 0.7.

**Fig. 9**: Experimental gas-liquid pressure drop vs. void fraction.

**Figure 10**: Comparison between Measured and predicted void fraction.

To quantify the deviation between the calculated void fraction from the gas-liquid pressure drop measurement and the measured void fraction from the conductance probes, two statistical parameters have been used. The first parameter is the root mean square deviation, RMS, and the second one is the mean relative absolute error, ABE, expressed in equations (9) to (11).

\[
\text{RMS} = \sqrt{\frac{1}{n} \sum_{i=0}^{n} \left( \frac{\varepsilon_{g,\text{calculated}} - \varepsilon_{g,\text{measured}}}{\varepsilon_{g,\text{measured}}} \right)^2} \quad (9)
\]

\[
x_i = \left| \frac{\varepsilon_{g,\text{calculated}} - \varepsilon_{g,\text{measured}}}{\varepsilon_{g,\text{measured}}} \right| \quad (10)
\]

\[
\text{ABE} = \frac{1}{n} \sum_{i=0}^{n} x_i \quad (11)
\]

where \( \varepsilon_{g,\text{calculated}} \) is the predicted void fraction from the two-phase pressure measurement and \( \varepsilon_{g,\text{measured}} \) is the measured void fraction from the conductance probes.

Table I, summarizes the two statistical parameters RMS and ABE obtained from the 121 experimental tests. From this table, one can see that the most accurate predicted data of the void fraction are those of the bubbly flow with an RMS and ABE of 3.63% and 2.57%, respectively. As expected from figure 8, The RMS and ABE increase considerably when passing from the bubbly to the slug flow with an RMS and ABE of 10.75% and 8.55%, respectively, which are three times less accurate compared to the bubbly flow. For the churn flow, the results show the most deviated results with an RMS and ABE of 12.01% and 9.39%, respectively.

**Figure 10**: Comparison between Measured and predicted void fraction.

**D. Calculated vs. Experimental Void Fraction**

Figure 10 exhibit the comparison between the calculated void fraction from the differential pressure transmitter (predicted void fraction) and the measured data using conductance probes.

**Figure 9**: Experimental gas-liquid pressure drop vs. void fraction.
The analysis of the two statistical parameter results showed that the bubbly flow pattern exhibits the most accurate results with RMS and ABE of 3.63% and 2.57%, respectively. For the slug and the churn flow, εg<0.3, the deviation between the theoretical and the experimental void fraction increases significantly. The results also showed that the frictional pressure drop between gas and liquid phases significantly affected the void fraction prediction accuracy. The latter cannot be neglected when the slip ratio between phases is beyond unity.

### E. Slip Ratio and Flow Pattern Effects

Figure 11 illustrates the impact of the flow pattern on the relative difference between the calculated and the experimental void fraction. Equally, in order to exhibit the slippage between the phases, the slip ratio has been added in the second axes. The latter can be calculated using the following expression.

\[
S = \frac{U_G}{U_L} = \frac{U_{GS}(1-\epsilon_G)}{U_{LS} \epsilon_G}
\]

(12)

From this figure, the impact of the flow pattern is evident. For the bubbly flow (εg < 0.30), the slip ratio between phases is around the unity indicating that the flow can be considered as homogeneous. The slip ratio increases beyond the unity when passing from bubbly to slug and considerably increases when reaching churn flow. A similar behavior of the slip ratio has been noticed for the relative difference error. The relation between these two parameters can be explained by the slip ratio's effect between the phases, which increases the frictional pressure drop between gas and liquid phases, i.e., the total frictional pressure drop [7]. The latter was not taken in the void fraction prediction, which in turn increases the error between the predicted and the measured void fraction.

### V. CONCLUSION

A differential pressure in a vertical ascending single and two-phase flow has been measured. From the obtained pressure drop results, the void fraction was predicted from a model derived from energy conservation. The calculated void fraction data were compared to those measured experimentally from the conductance probe sensor. To evaluate the accuracy of the predicted void fraction from the energy conservation model, the statistical parameters RMS and ABE have been used.

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