Constraining the Delay Time Distribution of Compact Binary Objects from the Stochastic Gravitational-wave Background Searches

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Abstract

The initial separation of massive star binaries sets the timescale over which their compact remnants merge through the emission of gravitational waves. We show that the delay time distribution (DTD) of binary neutron stars or black holes can be inferred from the stochastic gravitational wave background (SGWB). If the DTD of a population is long, most of the mergers take place at low redshifts and the background would be rather quiet compared to a scenario in which the DTD is short leading to few individual detections at low redshift but a rather loud background. We show that different DTDs predict a factor of 5 difference in the magnitude of the gravitational wave background energy density ($\Omega_{\text{GW}}$) and have the dominant effect on $\Omega_{\text{GW}}$ over other factors such as the mass function of the primary BH mass, $p(m_1)$, the maximum considered BH mass ($M_{\text{max}}$), and the effective spin of the black hole ($x_{\text{eff}}$). A nondetection of such a background can rule out the short DTD scenario. We show that SGWB searches can rule out the short DTD scenario for the BBHs within about four years of observing time at advanced LIGO design sensitivity for a local merger rate of 30 Gpc$^{-3}$yr$^{-1}$ assuming $p(m_1) \propto m_1^{-1}$, and $M_{\text{max}} = 50 M_\odot$.

Unified Astronomy Thesaurus concepts: Gravitational wave astronomy (675); Astrophysical black holes (98); Neutron stars (1108); Gravitational waves (679); Gravitational wave sources (677); Gravitational wave detectors (676)

1. Introduction

The detectability of individual compact binary objects (CBOs) through the emission of gravitational waves (GWs) by the advanced LIGO (Collaboration et al. 2015) and Virgo (Abernase et al. 2015) detectors depends on the CBO’s mass, distance, and orientation on the sky. While the redshift reach of LIGO to detected individual sources is $z \approx 0.1$ for binary neutron stars (BNS), and $z \approx 1$ for binary black holes (BBH), the majority of the coalescing binaries would be undetected as their signal-to-noise ratios ($S/N$s) fall below the detection threshold (Abbott et al. 2018). The undetected population of the CBOs contributes to the stochastic gravitational wave background (SGWB) that is detectable through searches for excess correlated power in two or more GW detectors (Allen & Romano 1997; Camp & Cornish 2004; Romano & Cornish 2017). The LIGO Scientific Collaboration currently constrains the dimensionless energy density of gravitational waves to be $\Omega_{\text{GW}} < 6.0 \times 10^{-9}$ with 95% confidence, assuming a flat energy density spectrum in the most sensitive part of the LIGO band (20–86 Hz) (Abbott et al. 2019).

The contribution of each subpopulation of the CBOs to the SGWB depends on the cosmic star formation history and their associated delay time distribution (DTD). In this paper we use the known star formation history to examine the impact of the DTD on the GW background amplitude and frequency spectrum. Assuming that the initial separations ($a$) of compact binaries follow $dn/da \propto a^{-1}$, given that the timescale for merging through gravitational waves scales as $t \propto a^4$, a power-law distribution in coalescence timescales $dn/dt \propto t^{-1}$ would be inferred. This underlies the results from the population synthesis analysis of binary stellar evolution leading to the formation of BNS and BBH systems (Dominik et al. 2012).

However, current observations allow for a range of possible distributions that might contradict the above assumptions (Beniamini et al. 2016; Safarzadeh et al. 2018).

One can characterize the shape of a DTD through two parameters: (i) the minimum delay time ($t_{\text{min}}$) that translates into the smallest possible separation for two compact objects, and (ii) the slope ($\Gamma$) of the probability distribution in time $dn/dt \propto t^\Gamma$. This is the simplest case if we assume the population can be represented by a single DTD, meaning no bimodality is present in the population and also assuming the DTD does not evolve with redshift. It is, however, plausible that the DTD is bimodal, evolves with redshift, or is determined by a different form than a power law, such as a log-normal distribution (Simonetti et al. 2019).

In the context of BNS systems, three frameworks for constraining the DTD have been considered: (i) scaling relations between the host galaxies of BNS merger events (Safarzadeh & Berger 2019), requiring on the order of $O(10^5)$ GW detection in the local universe, (ii) third-generation gravitational wave detectors, such as Einstein Telescope (ET) and Cosmic Explorer (CE) (Safarzadeh et al. 2019b), which was shown to take about one year of data acquisition, and (iii) detailed knowledge of the host galaxies of the BNS merger events (Safarzadeh et al. 2019a), which was shown to require $O(10^2)$ detections. LIGO’s horizon for detecting BNS mergers reaches out to $z \approx 0.1$, which is insufficient to probe the redshift distribution of the BNS mergers and therefore constrain the 2D parameterized model for the DTD (Safarzadeh et al. 2019b).

The same rationale applies to BBH mergers; however, in this case it is possible that the underlying DTD depends on the mass scale of the binaries and/or their effective spin distribution. Vitale et al. (2019) showed that the delay time distribution and...
star formation rate can be measured with three months of observations of binary black hole mergers with third-generation detectors. Evolution of the DTD with mass or spin can be incorporated into the framework of their analysis, which relies on hierarchical Bayesian inference. For BNS systems, one typically assumes to have a fixed component mass of $1.4 \, M_\odot$, an assumption that should be revisited in light of the most recent LIGO detection of a massive BNS system, GW190425, with a total mass of $\approx 3.4 \, M_\odot$. (Abbott et al. 2020).

In this article we demonstrate how advanced LIGO (adLIGO) will be able to constrain the DTD through SGWB searches. In Section 2 we compute the merger rate of the BNS and BBH systems given different assumptions regarding the DTD. In Section 3 we measure the corresponding expected SGWB level from each system. In Section 4 we present our results for adLIGO at design sensitivity as our detector network. In Section 5 we discuss the role and prospects for future GW detectors, and in Section 6 we summarize our work.

2. Merger Rate of the BNS and BBH Systems with Different DTDs

The merger rate as a function of redshift is a convolution of the DTD with the cosmic star formation rate density:

$$R(z) = \int_{z=10}^{z} \lambda \frac{dP_m}{dt}(t - t_b - t_{\text{min}}) \psi(z_b) \frac{dt}{dz}(z_b) dz_b,$$

where $dt/dz = -[(1 + z)E(z)H_0]^{-1}$, and $E(z)=\sqrt{\Omega_{m,0}(1 + z)^3 + \Omega_{k,0}(1 + z)^2 + \Omega_{\Lambda}(z)}$. We use $H_0 = 67 \, \text{km} \, \text{s}^{-1} \, \text{Mpc}^{-1}$ for the Hubble constant, and $\Omega_{m,0} = 1 - \Omega_\Lambda = 0.31$ (Ade et al. 2016). Here, $\lambda$ is the BNS or BBH production efficiency per mass in stars (assumed not to evolve with redshift) used as a free parameter to normalize the merger rate in the local universe; $t_b$ is the cosmic time corresponding to redshift $z_b$; $dP_m/dt$ is the DTD, parameterized to follow a power-law distribution $(x \lambda^\Gamma)$ with a minimum delay time, $t_{\text{min}}$ that refers to the time since the birth of the progenitor stars (the sum of the nuclear lifetime of the lowest mass component of the binary system and the minimal gravitational delay that is induced by the existence of a minimal separation between the two newly born compact objects). We also impose a maximum delay time of 10 Gyr for our fiducial case, comparable to the age of the universe. We choose to integrate from $z_b = 10$, since mergers beyond this redshift are extremely unlikely, even for the fastest DTD models (see Figure 1). We adopt the cosmic star formation rate density from Madau & Dickinson (2014):

$$\psi(z) = 0.015 \frac{(1 + z)^{2.7}}{1 + [(1 + z)/2.9]^{10}} \, M_\odot \, \text{yr}^{-1} \, \text{Mpc}^{-3}.$$

In this work we ignore the impact of metallicity with uncertainties that may affect the final merger rate of the BBHs, and BNSs. We refer the reader to other works that have explored the impact of such uncertainties (e.g., Neijssel et al. 2019; Safarzadeh & Farr 2019). While in the approach presented in this work an overall sense of DTD could be constrained, in reality DTD of BBHs would depend on their mass as more massive BBHs are born preferentially at lower metallicities. However, DTD uncertainties likely dominate over that of star formation history (SFH) and metallicity evolution; for example, by fixing the SFH parameterization and adopting different relations for the stellar mass–metallicity relation,

Neijssel et al. (2019) arrives at about less than 1 dex difference in the predicted merger rate of the BBHs (see their Table 1). Although relying on extreme uncertainties for SFH at high redshift can inflate the uncertainty budget for the merger rate of the BBHs, reasonable SFH parameterizations only differ by about 10%–20% in the overall shape and magnitude. We only caution the reader of other contributions to the merger rate uncertainties and defer a more comprehensive work to a future study.

Figure 1 shows the expected merger rate of BBHs across redshift for nine different DTD models all normalized to 30 Gpc$^{-3}$yr$^{-1}$ at $z = 0$, which is a conservative estimate based on the inferred local merger rate from LIGO’s second observing run (Abbott et al. 2018). These values of $\Gamma$ were chosen to represent small deviations from the expected value of $\Gamma = -1$ based on binary population synthesis (Dominik et al. 2012). In both cases, those DTDs favoring long delay, i.e., those with shallower slopes ($\Gamma = -1/2$) and longer minimum delay times ($t_{\text{min}} = 1 \, \text{Gyr}$) merge a smaller fraction of all binaries by $z = 0$ compared to the DTD model that favors short delay times.

3. The Stochastic Background

The stochastic background is defined as the energy density of gravitational waves $\rho_{GW}$ per logarithmic frequency interval:

$$\Omega(f) = \frac{1}{\rho_c} \frac{d \rho_{GW}}{d \ln f}$$

where $\rho_c$ is the critical density of the universe given by $\rho_c = 3H_0^2/8\pi G$. Here $H_0$ is the Hubble constant, and $G$ is the
Newton constant. The spectrum of the SGWB is given by:

\[
\frac{d \rho_{GW}}{d \ln f} = \int_{z=0}^{z_{\text{nf}}} \frac{R}{1 + z} \frac{dt}{dz} \left( f_r \frac{dE_{GW}}{df_r} \right)_{f_r = f(1+z)} dz
\]

(Phinney 2001), where \(f_r\) and \(f_r' = f(1+z)\) are the observed and rest-frame GW frequencies, respectively.

The GW spectrum from a coalescing BNS or BBH is given by

\[
\frac{dE_{GW}}{df_r} = \frac{(\pi G)^{2/3} M_{\text{chirp}}^{2/3}}{3} \left\{ \begin{array}{ll}
\frac{f_r^{-1/3} \mathcal{F}_{\text{PN}}}{\omega_{m1} f_r^{2/3} \mathcal{F}_{\text{PN}}} & f_r < f_1, \\
\omega_{m1} f_r^{2/3} \mathcal{F}_{\text{PN}} & f_1 \leq f_r < f_2, \\
\omega_{m2} f_r^{2/3} \mathcal{F}_{\text{PN}} & f_2 \leq f_r < f_3,
\end{array} \right.
\]

where \(E_{GW}\) is the energy emitted in GWs, \(M_{\text{chirp}} \equiv (m_1 m_2)^{3/5}/(m_1 + m_2)^{1/5}\) is the chirp mass, and \(f_i\) (\(i = 1, 2, 3\)) and \(\sigma\) are frequencies that characterize the inspiral-merging ringdown waveforms, \(\omega_{m(i)}\) are normalization constants chosen to make the waveform continuous, and \(\mathcal{F}(\mathcal{G})_{\text{PN}}\) are the post-Newtonian correction factors (Ajith et al. 2008).

We model the ensemble distribution of primary black hole masses as a power law

\[
p(m_1|\alpha, M_{\text{min}}, M_{\text{max}}) = \begin{cases} m_1^{-\alpha} & (M_{\text{min}} \leq m_1 \leq M_{\text{max}}) \\ 0 & \text{(else)} \end{cases}
\]

and assume a flat distribution

\[
p(m_2|m_1, M_{\text{min}}) = \begin{cases} \frac{1}{m_2 - m_1} & (M_{\text{min}} \leq m_2 \leq m_1) \\ 0 & \text{(else)} \end{cases}
\]

of secondary masses. We set \(M_{\text{min}} = 5 \, M_\odot\) as the lower observed BH mass in low-mass X-ray binaries (Farr et al. 2011). We set our fiducial values of \(\alpha = 1\), and \(M_{\text{max}} = 50 \, M_\odot\); however, we will explore the effect of varying these two parameters later in the paper. The upper limit on the BH mass is due to the assumption that pair-instability supernovae set an upper limit for the mass of the BHs born from stellar progenitors (Woosley 2017). The population analysis using BBH observations from LIGO/Virgo’s first and second observing runs measured the spectral index of the primary BH power law to be \(\alpha = 2.3^{+3.1}_{-1.4}\) at 90% confidence assuming a minimum black hole mass of 5 \(M_\odot\) and a maximum total mass of 100 \(M_\odot\) (Abbott et al. 2018). For the BNS systems we assume a uniform distribution between 1.3–1.5 \(M_\odot\) for each of the NSs to be consistent with the range of observed masses of galactic double neutron star systems (Kiziltan et al. 2013; Özel & Freire 2016; Farrow et al. 2019), although we note that this choice is in tension with the masses of GW190425 (Abbott et al. 2020).

4. Results

The results for the two extreme cases of DTDs for both the BBH and BNS systems are shown in Figure 2. The green shaded region shows the predicted range of \(\Omega_{\text{GW}}\) for a population of BNS composed of two NSs each with a mass uniformly distributed between 1.3 and 1.5 \(M_\odot\). The rate of the BNS mergers from LIGO is \(\mathcal{A} \approx 980^{+1490}_{-370} \text{Gpc}^{-3}\text{yr}^{-1}\) (Abbott et al. 2020). In order to get the full possible range we assign the highest rate to the short DTD model, and the lowest rate to the long DTD model. We do the same for the BBHs where we consider a merger rate between 20 to 110 \(\text{Gpc}^{-3}\text{yr}^{-1}\) (Abbott et al. 2020). For the BBH systems we considered two models in which (i) the primary BH mass follows \(p(m_1) \propto m_1^{-1}\) bounded between 5 and 50 \(M_\odot\), and the secondary uniformly distributed between 5 and \(m_1\) (this scenario is shown with the black shaded region); and (ii) one in which the two BHs each have a mass of 15 \(M_\odot\), which is shown with the red shaded region. The average chirp mass of the two BBH population models is the same. The solid orange line is the power-law integrated (PI) curve for adLIGO detection of the SGWB with SNR = 3 after one year of observing time. The dashed orange line shows the 2\(\sigma\) PI curve from LIGO’s O1 and O2 runs (Abbott et al. 2019). The cutoff frequency is lower for the full population since the ISCO frequency of BHs is inversely proportional to their mass, and we have contributions from more massive BHs in the full population model.

Figure 2. Predicted SGWB incorporating the uncertainty due to both the local merger rate and the underlying DTD of the population of BBH and BNS mergers. The green shaded region shows the predicted range of \(\Omega_{\text{GW}}\) for a population of BNS composed of two NSs each with a mass uniformly distributed between 1.3 and 1.5 \(M_\odot\). The black shaded region shows the 2\(\sigma\) PI curve from LIGO’s O1 and O2 runs. Any background intersecting the PI curve will be considered two models in which (i) the primary BH mass follows \(p(m_1) \propto m_1^{-1}\) bounded between 5 and 50 \(M_\odot\), and the secondary uniformly distributed between 5 and \(m_1\) (this scenario is shown with the black shaded region); and (ii) one in which the two BHs each have a mass of 15 \(M_\odot\), which is shown with the red shaded region. The average chirp mass of the two BBH population models is the same. The solid orange line is the power-law integrated (PI) curve for adLIGO detection of the SGWB with SNR = 3 after one year of observing time. The dashed orange line shows the 2\(\sigma\) PI curve from LIGO’s O1 and O2 runs (Abbott et al. 2019). The cutoff frequency is lower for the full population since the ISCO frequency of BHs is inversely proportional to their mass, and we have contributions from more massive BHs in the full population model.
from the BBHs if the DTD follows a fast-merging model. A lack of detection can rule out short DTDs for BBHs at a fixed value of $\gamma = 1$, and large $M_{\text{max}} = 60\,M_\odot$ would need an integration time of less than half a year to be detected assuming an optimistic local merger rate of 110 Gpc$^{-3}$ yr$^{-1}$, and therefore a nondetection of a background can rule out that part of the parameter space as the constraint on the local merger rate improves.

We also study the impact of spin on the overall contribution to $\Omega_{\text{GW}}$. For this purpose we construct $\frac{d\Omega_{\text{GW}}}{d\alpha}$ for nonprecessing, spinning BBHs following Ajith et al. (2011). Figure 6 shows this effect, comparing a nonspinning population to one in which all the BBHs have $\chi = 0.85$, which is the maximum spin considered in the construction of the waveform models in Ajith et al. (2011). Here we have assumed population (ii) of equal mass BBH mergers at a local merger rate of 30 Gpc$^{-3}$ yr$^{-1}$. The overall impact is subdominant compared to the other parameters we considered in this work. The only noticeable difference is the increase of the cutoff frequency, which arises from the fact that the ISCO radius of a spinning BH is smaller compared to a nonspinning BH, and therefore its associated frequency is higher.

### 5. Future GW Detectors

We separate the contribution of the BBHs at each redshift slice to the overall SGWB and show the result in the left panel of Figure 7. While the majority of the contribution originates from the BBHs at low redshifts, third-generation GW detectors, such as Einstein Telescope (Punturo et al. 2010) and Cosmic Explorer (Dwyer et al. 2015; Abbott et al. 2017), would be able to detect the contributing background from both the BBH and BNS populations at redshifts $z > 6$. Because the BBH population is expected to be completely resolved across cosmic history by 3G detectors (Vitale et al. 2019), the properties of these sources can be extracted from individual detections, but this presents a computational challenge since conducting full source characterization using Bayesian inference for so many high-$S/N$ events is costly (Vitale & Evans 2017). The search for the SGWB from these sources, however, offers a computationally inexpensive alternative, as it relies on searching for excess correlated power in the detectors without modeling the individual sources using waveforms. Additionally for BNS mergers, the SGWB will serve as a probe of the

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**Figure 3.** $S/N$ for the detection of the SGWB from BBH mergers as a function of integration time assuming a local BBH merger rate of 30 Gpc$^{-3}$ yr$^{-1}$ and the fiducial power-law BH mass model (i). The two curves show two extreme DTD models for the BBH mergers. Within four years of observing time with adLIGO, one should be able to detect the SGWB with $S/N > 3$ from BBHs for a short DTD. Lack of detection can be used to rule out the existence of such DTDs for BBHs at a fixed local BBH merger rate of 30 Gpc$^{-3}$ yr$^{-1}$.

The $S/N$ of SGWB detection can be computed following Allen & Romano (1997):

$$SNR \approx \frac{3H_0^2}{10\pi^2} \sqrt{T} \left[ \int_{f_1}^{f_2} df \frac{\gamma^2(f)}{f^6} P_1(f) P_2(f) \right]^{1/2}.$$  

Here $\gamma(f)$ is the overlap reduction function, which accounts for the separation and relative orientation of the detectors, a closed form of which is given in Flanagan (1993). $P_1(f)$ and $P_2(f)$ are the noise power spectral densities of the detectors, and $T$ is the integration time. The results for the BBH mergers, assuming a local merger rate of 30 Gpc$^{-3}$ yr$^{-1}$, are shown in Figure 3. The curves represent two extreme DTD models for the BBH mergers. Within four years of continuous observing time with adLIGO at design sensitivity, one should be able to detect the SGWB with $S/N > 3$ from the BBHs if the DTD follows a fast-merging model. A lack of detection can rule out short DTDs for the BBHs. In this calculation we assumed that the BBHs follow case (i). The BBHs dominate over BNSs according to the results shown in the Figure 2 assuming $R_{\text{BBH}}^0 = 30$ Gpc$^{-3}$ yr$^{-1}$ and $R_{\text{BNS}}^0 = 760$ Gpc$^{-3}$ yr$^{-1}$ in the local universe (Abbott et al. 2020).

So far our results have been based on assuming $p(m) \propto m^{-1}$ and $M_{\text{max}} = 50\,M_\odot$. However, these two assumptions on their own can impact the SGWB on top of the DTD assumptions (Talbot & Thrane 2018; Jenkins et al. 2019). Here we relax both of these assumptions. In the left panel of Figure 4 we explore the impact of changing the maximum BH mass at a fixed value of $\alpha = 1$. We see that a higher allowed maximum mass for the primary BH leads to a higher value of $\Omega_{\text{GW}}$ while also shifting the cutoff frequency to lower values as more massive BHs have lower frequencies associated with their last stable circular orbit (ISCO). In the right panel we vary the exponent $\alpha$, while keeping the value of $M_{\text{max}} = 50\,M_\odot$. In this case we only observe a rescaling of the curves with more positive slopes leading to a higher background level as expected. The shaded regions in all cases correspond to the different extreme DTD and local merger rate assumptions.

Therefore the total uncertainty budget, assuming the local rate is constrained, comes from the DTD, the slope of the primary BH mass function, and the maximum allowed BH mass. However, we can conclude that the uncertainty in the DTD dominates over the uncertainty in $\alpha$ and $M_{\text{max}}$ within the range explored in our work.

The observing time at design sensitivity would depend on all these assumptions. The left panel of Figure 5 shows the integration time needed to detect the SGWB assuming a short DTD, as a function of $\gamma$ and $M_{\text{max}}$, for the advanced LIGO detectors operating at design sensitivity. The right panel shows the same but assuming a slow DTD. There are regions of the parameter space, such as a short DTD, large positive slope ($\gamma = 1$), and large $M_{\text{max}} = 60\,M_\odot$ which would need an integration time of less than half a year to be detected assuming an optimistic local merger rate of 110 Gpc$^{-3}$ yr$^{-1}$.
significant fraction of the population that remains individually undetectable even with 3G detectors (Safarzadeh et al. 2019b).

We also show the PI curves for Cosmic Explorer and Einstein Telescope using the ET-D design configuration in Figure 7. We consider a network of two Cosmic Explorer instruments with the same overlap reduction function as the Hanford–Livingston detector pair. For the Einstein Telescope, we use the overlap reduction function for two V-shaped detector pairs separated by 120° following Regimbau et al. (2012). We note that the SGWB cannot be detected using a single 3G interferometer, as instrumental power cannot be separated from astrophysical power without cross-correlating between detectors with different noise sources. This presents a challenge for detecting the SGWB with ET alone, even though it consists of three nested interferometers, they will share common instrumental and environmental noise sources.

While the overall background level is detectable by standard cross-correlation techniques (Allen & Romano 1997), such techniques would not be able to single out the contribution from each of the CBO populations (BBHs versus BNS) separately. However, new approaches (Smith & Thrane 2018; Vivanco et al. 2019; Smith et al. 2020) have recently been proposed to search for the SGWB from BBHs and BNSs separately. These new searches use the fact that the astrophysical background is non-Gaussian–since individual compact binary systems do not merge simultaneously–and represent the background as a sum of individual subthreshold detections modeled by waveforms. Because BBH and BNS systems lie in disparate parts of the mass parameter space, searches can be conducted for each background from each type of source separately. The merger rate for each type of compact binary system inferred using these search methods can be converted into a stochastic background energy density, so the individual DTDs for BBH and BNS can be constrained using the framework described in this work. These non-Gaussian searches will serve as a hybrid, allowing both the individual detections and the subthreshold population to be probed simultaneously when implemented for 3G detector sensitivity (Smith et al. 2020).

If we are interested in probing the subthreshold population alone, after removing the individually detected sources, one can measure the background. Figure 8 shows the level of $\Omega_{\text{GW}}$ as a function of detection horizon for the population of BBHs that we have considered in this work. As the detection horizon increases, the expected contribution to the background naturally drops. This is more pronounced for a long DTD as the contribution to the background is already limited to sources at $z < 3$ and therefore increasing the detection horizon beyond that leaves little room for the SGWB contribution from the BNS or BBH systems. We note that constraints on the DTD can be used to inform the design of 3G detectors, since for longer delay times, there will be no astrophysical compact binary mergers at high redshifts.

We also show the horizon redshift for advanced LIGO design sensitivity, Cosmic Explorer, and Einstein Telescope in Figure 8. The horizon distance is defined as the maximum distance at which a source would be detectable with an $S/N$ above some threshold, $\rho > \rho_{\text{min}}$, where the optimal $S/N$ for a compact binary source with waveform $h(f)$ observed by a detector with power spectral density $P(f)$ is

$$\rho^2 = 4 \int_0^\infty \frac{h(f)^2P(f)}{P(f)} \, df.$$  \hfill (9)

The waveform $h(f)$ includes the contribution from the detector antenna patterns, which account for the sensitivity of the detector to the two gravitational wave polarizations due to its geometry. We follow Schutz (2011) and average the antenna patterns for the three interferometer configurations over the sky using the bilby software (Ashton et al. 2019). We compute...
the waveform for the BBH population (ii) specified above for a source with an inclination angle of 28°6, which is the most likely inclination angle for observed sources after accounting for selection biases (Schutz 2011). Because the waveform is proportional to the inverse of the luminosity distance \(d_L\) to the source, the horizon distance can be calculated as

\[
d_r = \frac{d_0}{\rho},
\]

where \(d_0\) is some reference distance used to calculate \(\rho^2\). This can then be converted into a redshift assuming the cosmological parameters specified in Section 2. We choose \(\rho_{\text{min}} = 8\) and consider only a single detector of each sensitivity, with ET consisting of three individual interferometers. For the source described above, we obtain \(z_{\text{max}} = 0.28, 2.73,\) and \(5.77\), for advanced LIGO, ET, and CE, respectively. We note that heavier sources with different orientations can be observed out to much higher redshifts for all three detectors, but use these values for representation.

6. Summary and Discussion

The distribution of the time lag between the birth and merger of compact binary objects due to the emission of gravitational waves (the delay time distribution, or DTD) can be characterized by a simple power law with two parameters, namely the minimum delay time and the slope of the power law. We examined two extreme cases of short and long DTDs, where in the fast version the time difference between the birth and merger is typically short compared to the age of the universe, and in the slow version it is comparable or longer. By normalizing to the observed rate of BBH or BNS mergers in the local universe, each of the DTD models results in a vastly different population of undetected sources at high redshifts. These undetected populations will show themselves in the correlated searches for the stochastic background signal between different detectors.
We studied the impact of the delay time distribution on the stochastic gravitational wave background (SGWB), and showed that the background level can change by a factor of \(\approx 5\) in the case of the BBHs assuming the two opposite ends of the DTDs. The difference of the background level is similar for the BNS systems. We note that the cutoff frequency for the BNSs and BBHs are different. The cutoff frequency is sensitive to the mass function we considered for the BBHs. The presence of more massive BHs in a population shifts the cutoff frequency to lower values as the ISCO frequency of a BH scales inversely with its mass. In our fiducial model assuming a local BBH merger rate of \(30 \text{Gpc}^{-3}\text{yr}^{-1}\), the level of the SGWB in the case of the short DTD is loud enough that it would be detectable after about four years of observing time with advanced LIGO at design sensitivity, and therefore a null detection can in principle rule out such DTD models.

We further explore the role of the primary BH mass function and the maximum allowed mass for the BHs on the contribution to the SGWB and show that, within the ranges of the parameters we studied in our work, the uncertainties associated with these parameters is subdominant compared to the DTD variations.

We further show that the next generation of GW detectors such as Einstein Telescope and Cosmic Explorer would be able to peer into the SGWB for sources above reionization redshifts \(z > 6\); however, novel SGWB search techniques should be implemented to distinguish between the contributions from the two populations.

Figure 7. Top panel: the predicted SGWB for BBHs in different redshift slices. Each shaded area indicates the estimated contribution to \(\Omega_{GW}\) of the BBHs in a specific redshift range. We also show the PI curves for the adLIGO, ET, and CE detectors for an S/N of 3 within one year of observing time. Bottom panel: the same but for the BNSs. Third-generation gravitational wave detectors, such as ET and CE, would be able to detect the contributing background from both the BBH and BNS populations at redshifts \(z > 6\); however, novel SGWB search techniques should be implemented to distinguish between the contributions from the two populations.

Figure 8. Predicted SGWB for BBHs at \(f = 25\) Hz as a function of detection horizon. As the detection horizon increases, the SGWB decreases. The effect is more drastic for long DTD (red line) than short DTD (blue line) because in the long DTD case the contribution to the SGWB is already limited to redshifts \(z < 3\), and therefore increasing the detection horizon to such redshifts leaves no room for additional contributions to the background. The vertical lines indicate the horizon distance for adLIGO, ET, and CE for the case of a population of BBHs with \(m_1 = m_2 = 15\ M_\odot\).
SGWB search results from the O1 and O2 LIGO observing runs. In their formulation, the evolution of merger rate density with redshift is constrained through the detection of the SGWB using a phenomenological model assuming that the stochastic background is due entirely to a population of compact binaries that is describable by a single mass distribution. In our work we assign the evolution of the merger rate with redshift to the underlying DTD of a given population. Moreover, our method allows for isolating the contributions from BBH and BNS mergers and determining the DTD for each type of compact binary independently, which is not captured by the framework presented in the Callister et al. (2020) analysis. In addition, we show how 3G detectors can further constrain the shape of the DTDs.

A preference for short DTD through the SGWB searches would indicate that BBHs all form from a fast-merging channel irrespective of the metallicity at which their progenitor is born. This would go against the currently accepted paradigm of BBH assembly. On the other hand, a long DTD would indicate the local BBH merger events have originated from low metallicities at high redshifts and therefore provide us clues with respect to the conditions of BBH formation at such metallicities.

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