Stability of disk-like galaxies—Part I: Stability via reduction

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March 28, 2022

Abstract

We prove the existence and stability of flat steady states of the Vlasov-Poisson system, which in astrophysics are used as models of disk-like galaxies. We follow the variational approach developed by Guo and Rein [5, 6, 7] for this type of problems and extend previous results of Rein [11]. In particular, we employ a reduction procedure which relates the stability problem for the Vlasov-Poisson system to the analogous question for the Euler-Poisson system.

1 Introduction

In astrophysics, galaxies or globular clusters are often modeled as a large ensemble of particles (stars) interacting only by the gravitational field which they create collectively. In such systems collisions among particles are sufficiently rare to be neglected. Hence in a nonrelativistic setting the particles move on trajectories determined by Newton’s equations of motion

\[ \dot{X} = V, \quad \dot{V} = -\nabla_X U(t, X), \]

where \( U(t, X) \) denotes the gravitational potential of the ensemble, \( t \in \mathbb{R} \) is time, and \( X, V \in \mathbb{R}^3 \) denote position and velocity; it is assumed that all particles have the same mass which is normalized to unity. To describe the time evolution of the ensemble, the density function \( F: \mathbb{R} \times \mathbb{R}^3 \times \mathbb{R}^3 \to \mathbb{R}_0^+ \) on phase space is used. It obeys a conservation law known as the Vlasov equation,

\[ \frac{\partial F}{\partial t} + V \cdot \nabla_X F - \nabla_X U \cdot \nabla_V F = 0, \]
which can be understood as an incompressibility condition of the "fluid" in phase space, also known as Liouville’s theorem. The gravitational potential $U$ is induced by the spatial density $R(t,X):=\int_{\mathbb{R}^3} F(t,X,V)\,dV$ via Newton’s law of gravity

$$U(t,X) = -\int_{\mathbb{R}^3} \frac{R(t,Y)}{|X-Y|}\,dY.$$ 

In the present paper we are interested in a situation where extremely flattened objects such flat galaxies are to be modeled. We therefore assume that all particles are concentrated in a plane, say the $(x_1,x_2)$-plane, with velocity vectors tangent to it. If this holds initially and if the only force acting on the particles is their mutual gravitational attraction, then the particles stay in that plane, and we can introduce a new, flat particle density $f : \mathbb{R} \times \mathbb{R}^2 \times \mathbb{R}^2 \to \mathbb{R}_0^+$, which is related to the density on the full phase space through

$$F(t,X,V) = f(t,x,v)\delta(x_3)\delta(v_3).$$

Here $\delta$ denotes the Dirac distribution, and $X = (x,x_3)$, $V = (v,v_3)$ with $x,v \in \mathbb{R}^2$. However, the particles still interact by the three dimensional Newtonian gravitational potential. Therefore, the Vlasov-Poisson system for $f$ reads

$$\frac{\partial f}{\partial t} + v \cdot \nabla_x f - \nabla_x U \cdot \nabla_v f = 0,$$

$$U(t,x) = -\int_{\mathbb{R}^2} \frac{\rho(t,y)}{|x-y|}\,dy,$$

$$\rho(t,x) = \int_{\mathbb{R}^2} f(t,x,v)\,dv,$$

where $x,v \in \mathbb{R}^2$. We refer to this system as the flat Vlasov-Poisson system. From the mathematics point of view it consists of the two dimensional Vlasov equation coupled with the $1/|x|$-type potential typical for three space dimensions. Since the $1/|x|$-singularity is integrated only over $\mathbb{R}^2$ this kind of coupling makes the system more singular and mathematically more difficult to analyze than the regular, three dimensional system.

The aim of the present investigation is to prove the existence of a large class of non-linearly stable steady states of the flat Vlasov-Poisson system. To do so we follow the approach developed by GUO and REIN [5, 6, 7].
in the regular, three dimensional situation. We prove that under suitable assumptions on a prescribed function \( \Phi : [0, \infty) \to [0, \infty] \) the energy-Casimir functional

\[
\mathcal{H}_C(f) = \frac{1}{2} \iint |v|^2 f(x, v) \, dv \, dx - \frac{1}{2} \iint \iint \frac{f(x, v) f(y, w)}{|x - y|} \, dv \, dx \, dw \, dy + \iint \Phi(f(x, v)) \, dv \, dx
\]

has a minimizer \( f_0 \) subject to the constraint

\[
\iint f(x, v) \, dv \, dx = M,
\]

where \( M > 0 \), the total mass of the resulting steady state, is prescribed. The Euler-Lagrange relation for this variational problem implies that

\[
f_0(x, v) = \phi(E).
\]

Here the particle energy \( E \) is defined as

\[
E(x, v) = \frac{1}{2} |v|^2 + U_0(x)
\]

with \( U_0 \) the potential induced by \( f_0 \), and the function \( \phi \) is determined by \( \Phi \) and a Lagrange multiplier. The point now is that for the time-independent potential \( U_0 \) the particle energy \( E \) and hence also \( \phi(E) \) is constant along particle trajectories and hence a solution of the time-independent Vlasov equation. Hence \( f_0 \) is a steady state of the flat Vlasov-Poisson system. The fact that \( f_0 \) minimizes the energy-Casimir functional \( \mathcal{H}_C \) can then be used to derive a non-linear stability property for this steady state.

In [11] this approach has already been used to construct stable steady states of the flat Vlasov-Poisson system. In the present paper we obtain a number of improvements and extensions of this earlier result. Firstly, we use a reduction procedure for proving the existence of a minimizer of \( \mathcal{H}_C \). This approach is mathematically more elegant and adequate, since the reduced functional lives on the set of spatial densities \( \rho \), and the main difficulty in the variational problem lies in the potential energy part which does not really depend on \( f \) but only on the spatial density induced by \( f \). More importantly, the reduced variational problem is of interest in its own right since it provides a stability result for the flat Euler-Poisson system which is the fluid dynamical analogue of the kinetic Vlasov-Poisson system. For the reduction procedure to work the function \( \Phi \) has to satisfy certain
growth conditions. An example of a steady state which violates this growth condition is the so-called Kuzmin disk which is known in the astrophysics literature and was not covered by previous results. The Kuzmin disk will be investigated in a companion paper [3]. Secondly, in [11] the perturbations admissible in the stability result had to be supported on the plane and in addition had to be spherically symmetric. In the present paper we remove the latter, unphysical restriction. It is desirable to remove also the restriction that the perturbations have to live in the plane, but that is much harder and is still under investigation. Lastly, we relax the assumptions on Φ the main one being that Φ be strictly convex so that we cover a larger class of steady states, and we obtain stability estimates in stronger norms than were obtained previously.

The paper proceeds as follows. In the next section we introduce various functionals and the reduced version of the variational problem, and we establish the connection between the original and the reduced variational problem. In the third section we establish the existence of a minimizer to the reduced problem using a concentration-compactness argument; notice that the variational problem—both reduced and original—is non-trivial since the energy-Casimir functional is not convex and is defined on functions supported on \( \mathbb{R}^2 \) or \( \mathbb{R}^4 \) respectively. In Section 4 we derive our stability result, and in the final section we consider the stability result for the Euler-Poisson system which arises from the reduced functional.

2 Energy-Casimir functionals and reduction

For \( \rho = \rho(x) \) measurable we define the induced gravitational potential and potential energy as

\[
U_\rho(x) := -\int \frac{\rho(y)}{|x-y|} \, dy,
\]

\[
E_{\text{pot}}(\rho) := \frac{1}{2} \int U_\rho(x)\rho(x) \, dx = -\frac{1}{2} \iint \frac{\rho(x)\rho(y)}{|x-y|} \, dy \, dx;
\]

in the sequel integrals \( \int \) without a subscript always extend over \( \mathbb{R}^2 \). It will also be useful to introduce the bilinear form which corresponds to the potential energy, i.e., for \( \rho, \sigma : \mathbb{R}^2 \to \mathbb{R} \) measurable,

\[
\langle \rho, \sigma \rangle_{\text{pot}} := \frac{1}{2} \iint \frac{\rho(x)\sigma(y)}{|x-y|} \, dy \, dx,
\]

so that in particular \( E_{\text{pot}}(\rho) = -\langle \rho, \rho \rangle_{\text{pot}} \). For the convenience of the reader we collect the main estimates for potentials, potential energies, and the
above bilinear form, which we will need.

**Lemma 2.1** If \( \rho \in L^{4/3}(\mathbb{R}^2) \), then \( U_\rho \in L^4(\mathbb{R}^2) \), and there exists a constant \( C > 0 \) such that for all \( \rho \in L^{4/3}(\mathbb{R}^2) \) the estimates

\[
||U_\rho||_4 \leq C||\rho||_{4/3}, \quad -E_{\text{pot}}(\rho) \leq C||\rho||^2_{4/3}
\]

hold. The bilinear form \( \langle \cdot, \cdot \rangle_{\text{pot}} \) defines a scalar product on \( L^{4/3}(\mathbb{R}^2) \) with induced norm

\[
||\rho||_{\text{pot}} := \langle \rho, \rho \rangle_{\text{pot}}^{1/2} = (-E_{\text{pot}}(\rho))^{1/2},
\]

in particular,

\[
\langle \rho, \sigma \rangle_{\text{pot}} \leq (E_{\text{pot}}(\rho) E_{\text{pot}}(\sigma))^{1/2} = ||\rho||_{\text{pot}} ||\sigma||_{\text{pot}}.
\]

**Proof.** Since \( 1/|\cdot| \in L^2_w(\mathbb{R}^2) \), the weak \( L^2 \) space, the assertions on \( U_\rho \) follow by the generalized Young’s inequality [9, 4.3]. The estimate for the potential energy is nothing but the Hardy-Littlewood-Sobolev inequality [9, 4.3] and follows by Hölder’s inequality, and so does the fact that \( \langle \cdot, \cdot \rangle_{\text{pot}} \) is defined on \( L^{4/3}(\mathbb{R}^2) \). The positive definiteness of \( \langle \cdot, \cdot \rangle_{\text{pot}} \) can be shown exactly like the positivity of the Coulomb energy in the three dimensional case, cf. [9, 9.8]. \( \square \)

Let \( f = f(x, v) \) be a measurable function on phase space. We define the induced spatial density, gravitational potential, and potential energy as

\[
\rho_f(x) := \int f(x, v) dv, \quad U_f := U_{\rho_f}, \quad E_{\text{pot}}(f) := E_{\text{pot}}(\rho_f).
\]

In addition, we define the kinetic energy

\[
E_{\text{kin}}(f) := \frac{1}{2} \iint |v|^2 f(x, v) dv dx,
\]

the so-called Casimir functional

\[
\mathcal{C}(f) := \iint \Phi(f(x, v)) dv dx
\]

with \( \Phi : [0, \infty[ \to [0, \infty[ \) prescribed, and the energy-Casimir functional

\[
\mathcal{H}_C(f) := \mathcal{C}(f) + E_{\text{kin}}(f) + E_{\text{pot}}(f).
\]

The total energy \( E_{\text{kin}} + E_{\text{pot}} \) as well as the Casimir functional \( \mathcal{C} \) and hence also their sum \( \mathcal{H}_C \) are conserved along sufficiently regular solutions of the flat Vlasov-Poisson system. As regards \( \Phi \), we assume for the moment that

\[
\Phi \in C^1([0, \infty[) \text{ is strictly convex, } \Phi(0) = \Phi'(0) = 0, \quad \lim_{\eta \to \infty} \Phi(\eta)/\eta = \infty.
\]
These assumptions make $\Phi$ non-negative and $\Phi'$ a bijection on $[0, \infty]$. Our aim is to show that the energy-Casimir functional $H_C$ has a minimizer in the constraint set

$$\mathcal{F}_M := \left\{ f \in L^1_+ (\mathbb{R}^4) \mid E_{\text{kin}}(f) + C(f) < \infty, \rho_f \in L^{4/3} (\mathbb{R}^2), \iint f = M \right\},$$

where $M > 0$ is prescribed, and the subscript $+$ indicates that only non-negative functions are considered. Since the troublesome term in the functional is the potential energy which actually depends only on the spatial density induced by $f$ we introduce a reduced variational problem for a functional which is defined in terms of spatial densities $\rho$. For $r \geq 0$ we define

$$\mathcal{G}_r := \left\{ g \in L^1_+ (\mathbb{R}^2) \mid \int \left( \frac{1}{2} |v|^2 g(v) + \Phi(g(v)) \right) dv < \infty, \int g(v) dv = r \right\}$$

and

$$\Psi(r) := \inf_{g \in \mathcal{G}_r} \int \left( \frac{1}{2} |v|^2 g(v) + \Phi(g(v)) \right) dv.$$

The idea behind this construction is to first minimize the energy-Casimir functional over all functions $f(x,v)$ which upon integration in $v$ give the same spatial density $\rho$, and then minimize with respect to the latter in a second (and main) step. This approach was introduced in [12, 17].

The reduced variational problem is to minimize the reduced functional

$$H^r_C (\rho) := \int \Psi(\rho(x)) dx + E_{\text{pot}} (\rho)$$

over the set

$$\mathcal{F}^r_M := \left\{ \rho \in L^{4/3} \cap L^1_+ (\mathbb{R}^2) \mid \int \Psi(\rho(x)) dx < \infty, \int \rho(x) dx = M \right\}.$$

We need to establish a relation between minimizers of the original functional and minimizers of the reduced one. Here we can essentially follow the corresponding results proven for the three dimensional case in [12]. First of all we explore the relation between $\Phi$ and $\Psi$. For a function $h: \mathbb{R} \to [-\infty, \infty]$ we denote by

$$h^* (\lambda) := \sup_{r \in \mathbb{R}} (\lambda r - h(r))$$

its Legendre transform. In what follows constants denoted by $C$ are always positive, may depend on $\Phi$ and $M$, and may change their value from line to line.
Lemma 2.2 Let $\Phi$ and $\Psi$ be as specified respectively defined above, and extend both functions by $+\infty$ to the interval $]-\infty,0]$. Then the following holds:

(a) For $\lambda \in \mathbb{R}$,

$$\Psi^*(\lambda) = \int \Phi^* \left( \lambda - \frac{1}{2} |v|^2 \right) dv,$$

and in particular $\Phi^*(\lambda) = 0 = \Psi^*(\lambda)$ for all $\lambda < 0$.

(b) $\Psi \in C^1([0,\infty[)$ is strictly convex, and $\Psi(0) = \Psi'(0) = 0$.

(c) Let $k > 0$ and $n = k + 1$.

(i) If $\Phi(f) = C f^{1+1/k}$ for $f \geq 0$, then $\Psi(\rho) = C \rho^{1+1/n}$ for $\rho \geq 0$.

(ii) If $\Phi(f) \geq C f^{1+1/k}$ for $f \geq 0$ large, then $\Psi(\rho) \geq C \rho^{1+1/n}$ for $\rho \geq 0$ large.

(iii) If $\Phi(f) \leq C f^{1+1/k}$ for $f \geq 0$ small, then $\Psi(\rho) \leq C \rho^{1+1/n}$ for $\rho \geq 0$ small.

If the restriction to large or small values of $f$ can be dropped then the corresponding restriction for $\rho$ can be dropped as well.

Proof. By definition

$$\Psi^*(\lambda) = \sup_{r \geq 0} \left[ \lambda r - \inf_{r \in \mathbb{R}_+} \int \left( \frac{1}{2} |v|^2 g(v) + \Phi(g(v)) \right) dv \right]$$

$$= \sup_{r \geq 0} \sup_{g \in G_r} \int \left[ \left( \lambda - \frac{1}{2} |v|^2 \right) g(v) - \Phi(g(v)) \right] dv$$

$$= \sup_{g \in L^1_+(\mathbb{R}^2)} \int \left[ \left( \lambda - \frac{1}{2} |v|^2 \right) g(v) - \Phi(g(v)) \right] dv$$

$$\leq \int \sup_{y \geq 0} \left[ \left( \lambda - \frac{1}{2} |v|^2 \right) y - \Phi(y) \right] dv = \int \Phi^* \left( \lambda - \frac{1}{2} |v|^2 \right) dv.$$

For $\lambda \leq 0$ both sides of this estimate are zero, so consider $\lambda > 0$. If $|v| \geq \sqrt{2\lambda}$ then $\sup_{y \geq 0} \cdots = 0$ and for $|v| < \sqrt{2\lambda}$ the supremum is attained at $y = y_v := (\Phi')^{-1}(\lambda - \frac{1}{2} |v|^2)$. Hence with the definition

$$g_0(v) := \begin{cases} y_v & \text{for } |v| < \sqrt{2\lambda} \\ 0 & \text{for } |v| \geq \sqrt{2\lambda} \end{cases},$$

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we obtain the reversed estimate, and part (a) is established. Part (b) is standard for Legendre transforms, and we refer to [12, Lemma 2.2] for the details. As to (c), if we assume that \( \Phi(f) \geq Cf^{1+1/k} \) for \( f \geq 0 \) large, we find that \( \Phi(f) \geq C f^{1+1/k} - C' \) for \( f \geq 0 \). Hence for \( \lambda \geq 0 \),

\[
\Phi^*(\lambda) = \sup_{f \geq 0} (\lambda f - \Phi(f)) \leq C' + \sup_{f \geq 0} \left( \lambda f - C f^{1+1/k} \right) \leq C + C \lambda^{k+1},
\]

and

\[
\Psi^*(\lambda) = \int_{|v| \leq \sqrt{2\lambda}} \Phi^* \left( \lambda - \frac{1}{2} |v|^2 \right) dv \leq C \int_{|v| \leq \sqrt{2\lambda}} \left[ 1 + \left( \lambda - \frac{1}{2} |v|^2 \right)^{k+1} \right] dv
\]

\[
\leq C \lambda + C \int_{|v| \leq \sqrt{2\lambda}} \left( \lambda - \frac{1}{2} |v|^2 \right)^{k+1} dv \leq C + C \lambda^{k+2} = C + C \lambda^{1+n}.
\]

Using the fact that \( \Psi^{**} = \Phi \) we obtain the estimate

\[
\Psi(\rho) = \sup_{\lambda \geq 0} (\rho \lambda - \Psi^*(\lambda)) \geq -C' + \sup_{\lambda \geq 0} (\rho \lambda - C \lambda^{1+n}) = C \rho^{1+1/n} - C',
\]

which proves (c) (ii). The remaining estimates are shown in a similar way. \( \square \)

The relation between the minimizers of \( \mathcal{H}_C \) and \( \mathcal{H}_C^r \) is as follows.

**Theorem 2.3** (a) For every function \( f \in \mathcal{F}_M \),

\[ \mathcal{H}_C(f) \geq \mathcal{H}_C^r(\rho_f), \]

with equality if \( f \) is a minimizer of \( \mathcal{H}_C \) over \( \mathcal{F}_M \).

(b) Let \( \rho_0 \in \mathcal{F}_M \) be a minimizer of \( \mathcal{H}_C^r \) with induced potential \( U_0 \). Then there exists a Lagrange multiplier \( E_0 \in \mathbb{R} \) such that the identity

\[
\rho_0 = \begin{cases} (\Psi')^{-1}(E_0 - U_0), & E_0 < E_0 \\ 0, & E_0 \geq E_0 \end{cases}
\]

holds almost everywhere. The function

\[
f_0 := \begin{cases} (\Phi')^{-1}(E_0 - E), & E < E_0 \\ 0, & E \geq E_0 \end{cases} \text{ with } E = E(x,v) := \frac{1}{2} |v|^2 + U_0(x)
\]

is a minimizer of \( \mathcal{H}_C \) in \( \mathcal{F}_M \).
Proof. Since the proof follows the same lines as [12, Thm 2.1] we only indicate the main arguments. The estimate in part (a) follows directly from the definitions. Next one can show that if \( f \in \mathcal{F}_M \) is such that up to sets of measure zero,
\[
\Phi'(f) = E_0 - E > 0 \quad \text{where} \quad f > 0, \quad \text{and} \quad E_0 - E \leq 0 \quad \text{where} \quad f = 0.
\]
with \( E \) defined as in (b) but with \( U_f \) instead of \( U_0 \) and \( E_0 \) a constant, then equality holds in part (a). If \( f \) is a minimizer of \( \mathcal{H}_C \), then the Euler-Lagrange equation implies that \( f \) is of the above form for some Lagrange multiplier \( E_0 \), and equality holds in (a). The relation of \( \rho_0 \) and \( U_0 \) in part (b) is nothing but the Euler-Lagrange equation for the reduced variational problem. If \( f_0 \) is defined as in (b) then \( \rho_0 = \rho_{f_0} \), in particular, \( f_0 \in \mathcal{F}_M \), and (2.1) holds by definition of \( f_0 \). Hence equality holds in (a) for \( f_0 \) so that by part (a) for any other \( f \in \mathcal{F}_M \),
\[
\mathcal{H}_C(f) \geq \mathcal{H}_C(f_0) \geq \mathcal{H}_C(\rho_0) = \mathcal{H}_C(f_0),
\]
which means that \( f_0 \) minimizes \( \mathcal{H}_C \).

Remark. (a) In the next section we show that under suitable assumptions on \( \Psi \) which can be translated into corresponding assumptions on \( \Phi \) the reduced variational problem has a solution \( \rho_0 \). The minimizer \( f_0 \) obtained by the lifting procedure in part (b) of the theorem depends only on the particle energy \( E \). The latter is for the time-independent potential \( U_0 \) constant along characteristics of the Vlasov equation, and hence \( f_0 \) is a steady state of the flat Vlasov-Poisson system.

(b) If \( \mathcal{H}_C^r \) has at least one minimizer in \( \mathcal{F}_M^r \) and if \( f_0 \in \mathcal{F}_M \) is a minimizer of \( \mathcal{H}_C \), then one can show that \( \rho_0 := \rho_{f_0} \in \mathcal{F}_M^r \) is a minimizer of \( \mathcal{H}_C^r \). This map is one-to-one between the sets of minimizers of \( \mathcal{H}_C \) in \( \mathcal{F}_M \) and \( \mathcal{H}_C^r \) in \( \mathcal{F}_M^r \) and is inverse to the mapping \( \rho_0 \mapsto f_0 \) described in part (b) of the theorem.

3 Existence of a solution to the reduced variational problem

In the present section we prove that the reduced energy-Casimir functional \( \mathcal{H}_C^r \) has a minimizer in the constraint set
\[
\mathcal{F}_M^r := \left\{ \rho \in L^1_+(\mathbb{R}^2) \mid \int \Psi(\rho(x)) \, dx < \infty, \int \rho(x) \, dx = M \right\},
\]
where \( M > 0 \) is prescribed and \( \Psi \) satisfies the assumptions \( \Psi \in C^1([0, \infty]) \), \( \Psi(0) = \Psi'(0) = 0 \) and...
(Ψ1) Ψ is strictly convex,

(Ψ2) Ψ(ρ) ≥ Cρ^{1+1/n} for ρ ≥ 0 large,

(Ψ3) Ψ(ρ) ≤ Cρ^{1+1/n'} for ρ ≥ 0 small,

with growth rates n, n' ∈ [0, 2]. The core of the proof is a concentration-compactness argument to show that along a minimizing sequence the matter cannot spread out but has to remain concentrated in a finite region of space. First however we show that the energy-Casimir functional is bounded from below in such a way that minimizing sequences are bounded in a suitable L^p space.

**Lemma 3.1** Under the above assumptions on Ψ and for ρ ∈ FM,

\[
\int \rho^{1+1/n} \, dx \leq C + C \int \Psi(\rho) \, dx,
\]

and

\[
\mathcal{H}_C^r(\rho) \geq \int \Psi(\rho) \, dx - C \left( \int \Psi(\rho) \, dx \right)^{n/2}.
\]

In particular,

\[
h_C^r := \inf_{\mathcal{F}_M^r} \mathcal{H}_C^r > -\infty.
\]

**Proof.** The first estimate follows by assumption (Ψ2) and the fact that \( \int \rho = M \). By Lemma 2.1 and interpolation,

\[
-E_{\text{pot}}(\rho) \leq C \|\rho\|_{L^{3/2}}^2 \leq C \|\rho\|_1^{(3-n)/2} \|\rho\|_{1+1/n}^{(n+1)/2} \leq C + C \left( \int \Psi(\rho) \, dx \right)^{n/2},
\]

and since 0 < n < 2 the proof is complete. 

We note an immediate corollary.

**Corollary 3.2** Any minimizing sequence of \( \mathcal{H}_C^r \) in \( \mathcal{F}_M^r \) is bounded in \( L^{1+1/n}(\mathbb{R}^2) \) and therefore contains a subsequence which converges weakly in that space.

The concentration-compactness argument mentioned above relies on the behavior of \( \mathcal{H}_C^r(\rho) \) if \( \rho \) is scaled or split into several parts. We start with the latter; in the sequel \( B_R \) denotes the open ball of radius \( R > 0 \) about the origin.
Lemma 3.3 Let $\rho \in F^*_M$. Then for $R > 1$,

$$\sup_{a \in \mathbb{R}^2} \int_{a + B_R} \rho(x) \, dx \geq \frac{1}{RM} \left( -2E_{\text{pot}}(\rho) - M^2R^{-1} - C\|\rho\|_{1+1/n}^2R^{-(3-n)/(n+1)} \right).$$

Proof. We split the potential energy as follows:

$$-2E_{\text{pot}} = \int \int_{|x-y| \leq 1/R} \rho(x)\rho(y) \, dx \, dy + \int \int_{1/R < |x-y| < R} \cdots + \int \int_{|x-y| \geq R} \cdots \quad =: I_1 + I_2 + I_3.$$ 

By Hölder’s and Young’s inequalities we obtain estimates

$$I_1 \leq \|\rho\|_{1+1/n} \|\rho\|_{1} \|1_{B_{1/R}}(\cdot)\|_{n+1} \leq \|\rho\|_{1+1/n}^2 \|1_{B_{1/R}}(\cdot)\|_{n+1} \|\rho\|_{1+1/n}^2 \leq C\|\rho\|_{1+1/n} R^{-(3-n)/(n+1)},$$

$$I_2 \leq R \int \int_{|x-y| \leq R} \rho(x)\rho(y) \, dx \, dy = MR \sup_{a \in \mathbb{R}^2} \int_{a + B_R} \rho(x) \, dx,$$

$$I_3 \leq M^2R^{-1}.$$

We insert these estimates into the formula for $-2E_{\text{pot}}$ and rearrange terms to obtain the assertion. \qed

Next we investigate the behavior of the reduced functional under scalings.

Lemma 3.4 (a) For every $M > 0$, $h^*_M < 0$.

(a) For every $0 < M \leq \overline{M}$ the estimate $h^*_M \geq (\overline{M}/M)^{3/2}h^*_M$ holds.

Proof. For $\rho \in F^*_M$ and $a, b > 0$ we define $\bar{\rho}(x) := a\rho(bx)$. Then

$$\int \bar{\rho} \, dx = ab^{-2} \int \rho \, dx,$$

$$E_{\text{pot}}(\bar{\rho}) = a^2b^{-3}E_{\text{pot}}(\rho),$$

$$\int \Psi(\bar{\rho}) \, dx = b^{-2} \int \Psi(a\rho) \, dx.$$

To prove part (a) we fix a bounded and compactly supported function $\rho \in F^*_M$ and choose $a = b^2$ so that $\bar{\rho} \in F^*_M$ as well. By $(\Psi3)$ and since $2/n' > 1$,

$$\mathcal{H}_C^*(\bar{\rho}) = b^{-2} \int \Psi(b^2\rho) \, dx + bE_{\text{pot}}(\rho) \leq Cb^{2/n'} + bE_{\text{pot}}(\rho) < 0.$$
for \( b \) sufficiently small, and part (a) is established. As to part (b), we take \( a = 1 \) and \( b = (M/M)^{1/2} \geq 1 \). For this choice of parameters the mapping \( \mathcal{F}_M \ni \rho \mapsto \bar{\rho} \in \mathcal{F}_M^* \) is one-to-one and onto, and the estimate

\[
H_C^r(\bar{\rho}) = b^{-2} \int \Psi(\rho) \, dx + b^{-3} E_{\text{pot}}(\rho) \\
\geq b^{-3} \left( \int \Psi(\rho) \, dx + E_{\text{pot}}(\rho) \right) = \left( \frac{M}{M_0} \right)^{3/2} H_C^r(\rho)
\]

proves the assertion of part (b).

\[\blacksquare\]

**Corollary 3.5** Let \( (\rho_i) \subset \mathcal{F}_M^* \) be a minimizing sequence of \( H_C^r \). Then there exist \( \delta_0 > 0, R_0 > 0, \) and a sequence of shift vectors \( (a_i) \subset \mathbb{R}^2 \) such that for \( i \) sufficiently large,

\[
\int_{a_i + B_{R_0}} \rho_i(x) \, dx \geq \delta_0.
\]

**Proof.** By Corollary 3.2 (\( ||\rho_i||_{1+1/n} \)) is bounded. By Lemma 3.4 (a),

\[
E_{\text{pot}}(\rho_i) \leq H_C^r(\rho_i) \leq \frac{1}{2} h_M^r < 0
\]

for \( i \) sufficiently large, and the assertion follows by Lemma 3.3. \[\blacksquare\]

This corollary only shows that along a minimizing sequence not all matter can spread uniformly. In the proof of the existence theorem below we shall actually see that the matter remains within a ball of finite radius up to spatial shifts and an arbitrarily small remainder. In such a situation we have the following compactness result:

**Lemma 3.6** Let \( (\rho_i) \subset \mathcal{F}_M^* \) be such that

\[
\rho_i \rightharpoonup \rho_0 \text{ weakly in } L^{1+1/n}(\mathbb{R}^2)
\]

and such that the following concentration property holds:

\[
\forall \epsilon > 0 \exists R > 0 : \limsup_{i \to \infty} \int_{|x| > R} \rho_i(x) \, dx < \epsilon.
\]

Then

\[
E_{\text{pot}}(\rho_i - \rho_0) \to 0 \text{ and } E_{\text{pot}}(\rho_i) \to E_{\text{pot}}(\rho_0), \ i \to \infty.
\]

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Proof. By weak convergence $\rho_0 \geq 0 \text{ a.e., and } \int \rho_0 \leq M$. We define $\sigma_i := \rho_i - \rho_0$ so that $\sigma_i \to 0$ weakly in $L^{1+1/n}(\mathbb{R}^2)$, the concentration property holds for $|\sigma_i|$ as well, and $\int |\sigma_i| \leq 2M$. We need to prove that

$$I_i := \iint \frac{\sigma_i(x)\sigma_i(y)}{|x-y|} \, dx \, dy \to 0,$$

which is the first assertion. Since

$$E_{\text{pot}}(\rho_i) - E_{\text{pot}}(\rho_0) = E_{\text{pot}}(\rho_i - \rho_0) + \int U_{\rho_0}(\rho_i - \rho_0),$$

the fact that $U_{\rho_0} \in L^4(\mathbb{R}^2)$ together with the weak convergence of $\rho_i$ implies the second assertion. For $\delta > 0$ and $R > 0$ we split the domain of integration into three subsets defined by

- $|x-y| < \delta$,
- $|x-y| \geq \delta \wedge (|x| \geq R \vee |y| \geq R)$,
- $|x-y| \geq \delta \wedge |x| < R \wedge |y| < R$,

and we denote the corresponding contributions to $I_i$ by $I_{i,1}, I_{i,2}, I_{i,3}$. Young’s inequality implies that

$$|I_{i,1}| \leq C||\sigma_i||_{1+1/n}^2 ||1_{B_R}||_1 ||1||_{(n+1)/2} \leq C \left( \int_0^{\delta} r^{(1-n)/2} \, dr \right)^{2/(n+1)}$$

which can be made as small as we wish, uniformly in $i$ and $R > 0$, by making $\delta > 0$ small. For $\delta > 0$ now fixed,

$$|I_{i,2}| \leq 4M \frac{\delta}{\delta} \int_{|x| > R} |\sigma_i(x)| \, dx$$

which becomes small for $i \to \infty$ by the concentration assumption, if we choose $R > 0$ accordingly. Finally by Hölder’s inequality,

$$|I_{i,3}| = \left| \int \sigma_i(x)h_i(x) \, dx \right| \leq ||\sigma_i||_{1+1/n} ||h_i||_{1+n} \leq C ||h_i||_{1+n},$$

where in a pointwise sense,

$$h_i(x) := 1_{B_R}(x) \int_{|x-y| \geq \delta} 1_{B_R}(y) \frac{1}{|x-y|} \sigma_i(y) \, dy \to 0$$

due to the weak convergence of $\sigma_i$ and the fact that the test function against which $\sigma_i$ is integrated here is in $L^{1+n}$. Since $|h_i| \leq \frac{2M}{\delta} 1_{B_R}$ uniformly in $i$, 

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Lebesgue's dominated convergence theorem implies that \( h_i \to 0 \) in \( L^{1+n} \), and the proof is complete. □

We have now assembled all the tools we need to prove the existence of a minimizer of the reduced functional.

**Theorem 3.7** Let \( (\rho_i) \subset \mathcal{F}_M \) be a minimizing sequence of \( \mathcal{H}_C^r \). Then there exists a sequence of shift vectors \( (a_i) \subset \mathbb{R}^2 \) and a subsequence, again denoted by \( (\rho_i) \), such that for every \( \varepsilon > 0 \) there exist \( R > 0 \) with

\[
\int_{a_i + BR} \rho_i(x) \, dx \geq M - \varepsilon, \quad i \in \mathbb{N},
\]

\[
T_{a_i} \rho_i := \rho_i(\cdot + a_i) \to \rho_0 \text{ weakly in } L^{1+1/n}(\mathbb{R}^2), \quad i \to \infty,
\]

\[
\int_{BR} \rho_0(x) \, dx \geq M - \varepsilon.
\]

Finally,

\[
E_{\text{pot}}(T_{a_i} \rho_i - \rho_0) \to 0,
\]

and \( \rho_0 \in \mathcal{F}_M \) is a minimizer of \( \mathcal{H}_C^r \).

**Proof.** We split \( \rho \in \mathcal{F}_M \) as follows:

\[
\rho = 1_{BR_1} \rho + 1_{BR_2 \setminus BR_1} \rho + 1_{\mathbb{R}^2 \setminus BR_2} \rho =: \rho_1 + \rho_2 + \rho_3.
\]

The parameters \( R_1 < R_2 \) of the split are yet to be determined. Recalling the definition of the bilinear form \( \langle \cdot, \cdot \rangle_{\text{pot}} \),

\[
\mathcal{H}_C^r(\rho) = \mathcal{H}_C^r(\rho_1) + \mathcal{H}_C^r(\rho_2) + \mathcal{H}_C^r(\rho_3) - 2 \langle \rho_1 + \rho_3, \rho_2 \rangle_{\text{pot}} - 2 \langle \rho_1, \rho_3 \rangle_{\text{pot}}.
\]

If we choose \( R_2 > 2R_1 \), then

\[
\langle \rho_1, \rho_3 \rangle_{\text{pot}} \leq \frac{C}{R_2}.
\]

By Lemma 2.1 and interpolation,

\[
\langle \rho_1 + \rho_3, \rho_2 \rangle_{\text{pot}} \leq \| \rho_1 + \rho_3 \|_{\text{pot}} \| \rho_2 \|_{\text{pot}}
\]

\[
\leq C \| \rho_1 + \rho_3 \|_{4/3} \| \rho_2 \|_{\text{pot}} \leq C \| \rho \|^{(n+1)/4}_{1+1/n} \| \rho_2 \|_{\text{pot}}.
\]

If we define

\[
M_l := \int \rho_l(x) \, dx, \quad l = 1, 2, 3,
\]

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then Lemma 3.4 (b) and the estimates above imply that

\[ h^r_M - \mathcal{H}^r_C(\rho) \leq \left( 1 - \left( \frac{M_1}{M} \right)^{3/2} - \left( \frac{M_2}{M} \right)^{3/2} - \left( \frac{M_3}{M} \right)^{3/2} \right) h^r_M \]

\[ + C \left( R^{-1}_2 + ||\rho||^{(n+1)/4}_{L^{1+1/n}} ||\rho_2||_{\text{pot}} \right) \]

\[ \leq \frac{C}{M^2} (M_1 M_2 + M_2 M_3 + M_1 M_3) h^r_M \]

\[ + C \left( R^{-1}_2 + ||\rho||^{(n+1)/4}_{L^{1+1/n}} ||\rho_2||_{\text{pot}} \right) \]

\[ \leq C h^r_M M_1 M_3 + C \left( R^{-1}_2 + ||\rho||^{(n+1)/4}_{L^{1+1/n}} ||\rho_2||_{\text{pot}} \right). \]

Here we used that for some constant \( C > 0 \) the following inequality holds:

\[ x^{3/2} + y^{3/2} + z^{3/2} \leq 1 - C(x y + x z + y z) \text{ for } x, y, z \geq 0 \text{ with } x + y + z = 1. \]

Now we consider a minimizing sequence \((\rho_i) \subset \mathcal{F}^r_M\) of \( \mathcal{H}^r_C \) and choose shift vectors \((a_i) \subset \mathbb{R}^2\), \( \delta_0 > 0 \), and \( R_0 > 0 \) according to Cor. 3.3. Since all our functionals are invariant under spatial translations the sequence \( T_{a_i} \rho_i = \rho_i(\cdot + a_i) \) is again minimizing and hence bounded in \( L^{1+1/n}(\mathbb{R}^2) \) so that up to a subsequence we can assume that it converges weakly to some \( \rho_0 \in L^{1+1/n}(\mathbb{R}^2) \).

We choose \( R_1 > R_0 \) so that by Cor. 3.3 \( M_{i,1} \geq \delta_0 \) for \( i \) large, and

\[ -C h^r_M \delta_0 M_{i,3} \leq C R^{-1}_2 + C ||\rho_0,2||_{\text{pot}} + C ||\rho_{i,2} - \rho_0,2||_{\text{pot}} + \mathcal{H}^r_C(T_{a_i} \rho_i) - h^r_M. \]

Given any \( \varepsilon > 0 \) we increase \( R_1 > R_0 \) such that the second term on the right hand side is smaller than \( \varepsilon \). Next we choose \( R_2 > 2R_1 \) such that the first term is small. Now that \( R_1 \) and \( R_2 \) are fixed, the third term converges to zero by Lemma 3.6 and since \( T_{a_i} \rho_i \) is minimizing the remainder follows suit. Therefore for \( i \) sufficiently large,

\[ \int_{B_{R_2}} T_{a_i} \rho_i \, dx = M - M_{i,3} \geq M - (-C h^r_M \delta_0)^{-1} \varepsilon. \]

The strong convergence of the potential energies now follows by Lemma 3.6. By weak convergence \( \rho_0 \geq 0 \) a.e., and for any \( \varepsilon > 0 \) there exists \( R > 0 \) such that

\[ M \geq \int_{B_R} \rho_0 \, dx \geq M - \varepsilon, \]

in particular \( \rho_0 \in L^1(\mathbb{R}^2) \) with \( \int \rho_0 = M \). The functional \( \rho \mapsto \int \Psi(\rho) \, dx \) is convex, so by Mazur’s lemma [2, 2.13] and Fatou’s lemma

\[ \int \Psi(\rho_0) \, dx \leq \limsup_{i \to \infty} \int \Psi(T_{a_i} \rho_i) \, dx. \]
Hence \( \rho_0 \in \mathcal{F}_M \) with
\[
\mathcal{H}_C^r(\rho_0) \leq \limsup_{i \to \infty} \mathcal{H}_C^r(\rho_i) = h_M^r,
\]
and the proof is complete.

**Remark.** (a) Thm. 3.7 provides a minimizer \( \rho_0 \) of the reduced energy-Casimir functional \( \mathcal{H}_C^r \) under the assumptions (Ψ1)–(Ψ3). By Thm. 2.3 this minimizer can be lifted to a minimizer \( f_0 \) of the original energy-Casimir functional \( \mathcal{H}_C \). By Lemma 2.2 the function \( \Psi \) satisfies the necessary assumptions if \( \Phi \) which appears in the original Casimir functional satisfies the following ones: \( \Phi \in C^1([0, \infty]), \Phi(0) = \Phi'(0) = 0 \) and

- (Φ1) \( \Phi \) is strictly convex,
- (Φ2) \( \Phi(f) \geq C f^{1+1/k} \) for \( f \geq 0 \) large,
- (Φ3) \( \Phi(f) \leq C f^{1+1/k'} \) for \( f \geq 0 \) small,

with growth rates \( k,k' \in ]0,1[ \).

(b) As will be seen in the next section the mere fact that \( f_0 \) minimizes \( \mathcal{H}_C \) is not sufficient for stability. However, let \( (f_i) \subset \mathcal{F}_M \) be a minimizing sequence of \( \mathcal{H}_C \). By Thm. 2.3 (a) the sequence of induced spatial densities \( \rho_i = \rho_{f_i} \) is minimizing for \( \mathcal{H}_C^r \). Choose a subsequence of \( (\rho_i) \) (and \( (f_i) \)) and shift vectors such that the assertions of Thm. 3.7 hold, and denote the shifted subsequence again by \( (f_i) \). We claim that this sequence converges weakly to \( f_0 \). Clearly, \( (f_i) \) is bounded in \( L^{1+1/k}(\mathbb{R}^4) \) with bounded kinetic energy, and \( E_{\text{pot}}(f_i) = E_{\text{pot}}(\rho_i) \to E_{\text{pot}}(\rho_0) \). Any subsequence of \( (f_i) \) must therefore have a weakly convergent subsequence with weak limit \( f_0 \) which is a minimizer of \( \mathcal{H}_C \) and induces the same spatial density \( \rho_0 \) and potential \( U_0 \). But then by Thm. 2.3 \( f_0 = f_0 \) so that indeed \( f_i \to f_0 \) weakly in \( L^{1+1/k}(\mathbb{R}^4) \).

(c) For \( k \geq 1 \) one can still obtain stability results, cf. 3 for the Kuzmin disk which corresponds to \( \Phi(f) = f^{3/2} \), i.e., \( k = k' = 2 \). However, the reduction approach cannot work, because as we shall see in the last section this approach implies stability for the Euler-Poisson system where stability is probably lost at \( n = 2 \), i.e., \( k = 1 \).

### 4 Stability of minimizers

Now that the existence of a minimizer is proven, we can explore its dynamical stability properties. So let \( \rho_0 \) be as obtained in Thm. 3.7 and \( f_0 \) as induced
by Thm. 2.3 A simple expansion shows that

$$\mathcal{H}_C(f) - \mathcal{H}_C(f_0) = d(f, f_0) + E_{\text{pot}}(f - f_0),$$

(4.2)

where for $f \in \mathcal{F}_M$ and with the Lagrange multiplier $E_0$ from Thm. 2.3 (b),

$$d(f, f_0) := \int \int [\Phi(f) - \Phi(f_0) + E(f - f_0)] dv dx$$

$$= \int \int [\Phi(f) - \Phi(f_0) + (E - E_0)(f - f_0)] dv dx$$

$$\geq \int \int [\Phi'(f_0) + (E - E_0)](f - f_0) dv dx \geq 0$$

with $d(f, f_0) = 0$ iff $f = f_0$. For the positivity of $d$ we use the strict convexity of $\Phi$ and the form of $f_0$ according to Thm. 2.3 (b); by that theorem the term in brackets vanishes on the support of $f_0$. We recall that $-E_{\text{pot}}(f) = \langle \rho_f, \rho_f \rangle_{\text{pot}} = ||\rho_f||^2_{\text{pot}}$ defines a norm on $\rho_f$, cf. Lemma 2.1. Note that the right hand side in Eqn. (4.2) is $d(f, f_0) - ||\rho_f - \rho_0||^2_{\text{pot}}$. We obtain the following stability result; $C^2_c(\mathbb{R}^4)$ denotes the space of compactly supported $C^2$ functions on $\mathbb{R}^4$.

Theorem 4.1 Let $f_0$ be a minimizer of $\mathcal{H}_C$ on $\mathcal{F}_M$ obtained from a minimizer $\rho_0$ of $\mathcal{H}_r$ and assume that the minimizer is unique. Then for any $\varepsilon > 0$ there exists $\delta > 0$ such that for any classical solution $[0, T] \ni t \mapsto f(t)$ of the flat Vlasov-Poisson system with $f(0) \in C^2_c(\mathbb{R}^4) \cap \mathcal{F}_M$ and $||f(0)||_{1+1/k} = ||f_0||_{1+1/k}$ the estimate

$$d(f(0), f_0) + ||\rho_f(0) - \rho_0||^2_{\text{pot}} < \delta$$

implies that for each $t \in [0, T]$ there exists a shift vector $a \in \mathbb{R}^2$ such that

$$||f(t) - T_a f_0||_{1+1/k} + d(f(t), T_a f_0) + ||\rho_f(t) - T_a \rho_0||^2_{\text{pot}} < \varepsilon.$$

Proof. Assume that the assertion were false. Then there exists $\varepsilon > 0, t_j > 0, f_j(0) \in C^2_c(\mathbb{R}^4) \cap \mathcal{F}_M$ with $||f_j(0)||_{1+1/k} = ||f_0||_{1+1/k}$ such that for every $j \in \mathbb{N}$,

$$d(f_j(0), f_0) - E_{\text{pot}}(f_j(0) - f_0) < \frac{1}{j}$$

(4.3)

but for any shift vector $a \in \mathbb{R}^2$,

$$||f_j(t_j) - T_a f_0||_{1+1/k} + d(f_j(t_j), T_a f_0) - E_{\text{pot}}(f_j(t_j) - T_a f_0) \geq \varepsilon.$$  

(4.4)
Since $H_C$ is preserved along solutions we have from (4.2) and (4.3) that

$$H_C(f_j(t_j)) = H_C(f_j(0)) \to H_C(f_0),$$

i.e., $(f_j(t_j))$ is a minimizing sequence. By Thm. 3.7 and the remark at the end of the previous section there is a sequence of shift vectors $(a_j) \subset \mathbb{R}^2$ such that up to a subsequence,

$$\lim_{j \to \infty} E_{\text{pot}}(T_{a_j}f_j(t_j) - f_0) \to 0.$$

By (4.2) this implies that $d(T_{a_j}f_j(t_j), f_0) \to 0$. For the convergence of $\|\cdot\|_{1+1/k}$ we use the fact that $\|f_j(t)\|_{1+1/k} = \|f_j(0)\|_{1+1/k} = \|f_0\|_{1+1/k}$ for any $t > 0$. By the remark, $T_{a_j}f_j(t_j) \to f_0$ weakly in $L^{1+1/k}(\mathbb{R}^4)$, and hence $T_{a_j}f_j(t_j) \to f_0$ strongly in $L^{1+1/k}(\mathbb{R}^4)$. But these convergence results for $T_{a_j}f_j(t_j)$ contradict (4.4). $\square$

Remark. (a) The uniqueness assumption on $f_0$ in the above theorem is made mostly in order to avoid technical complications. It suffices if $f_0$ is isolated with respect to the topology of our stability estimate. If there should be a continuum of minimizers then the set of minimizers itself is stable; we refer to [6, Thm. 4] for such a formulation of the result in the three dimensional case. We are not aware of a case where there is a continuum of minimizers with fixed mass $M$. For a closely related variational problem it has been shown that the above stability estimate remains valid even then [16].

(b) As opposed to the three dimensional case [10, 14, 15] there is no global existence and uniqueness result to the initial value problem for the flat Vlasov-Poisson system yet. Hence our stability result is conditional in the sense that it holds as long as a suitable solution exists. A local existence and uniqueness result for smooth solutions with initial data in $C^2(\mathbb{R}^4)$ as well as a global existence result for weak solutions to the flat system was established in [2]. We could also carry out our stability analysis in the framework of these global weak solutions, but this would only bury the main ideas under technicalities.

(c) By interpolation between $L^1$ and $L^{1+1/k}$ we obtain a stability estimate for $\|f(t) - T_a f_0\|_p$ with $p \in [1, 1 + 1/k]$. If we assume that the initial perturbations have supports of uniformly bounded measure we can include the case $p = 1$, if we assume a uniform bound on the $L^\infty$ norm of the initial perturbations we can by interpolation include all $p \in [1 + 1/k, \infty]$; notice that both the measure of the support and the $L^\infty$ norm are invariant under classical solutions of the Vlasov-Poisson system.
The need for the shifts in the stability estimate arises from the Galilei invariance of the Vlasov-Poisson system. If $f_0$ is a steady state then for any fixed $V \in \mathbb{R}^2$ the function $f_0(x-tV,v-V)$ is a time dependent solution; $f_0$ is simply put into a uniformly moving coordinate system. But while the distance of this perturbation to the steady state grows linearly in $t$, it is arbitrarily close to the steady state at $t=0$ for $V$ small.

5 Connection to the Euler-Poisson system

A self-gravitating matter distribution can be described on the microscopic, kinetic level represented by the Vlasov-Poisson system or on the macroscopic, fluid level represented by the Euler-Poisson system. The reduction technique connects the stability problems for these two viewpoints. In the three dimensional situation this connection was observed in [13]. In the flat case the corresponding Euler-Poisson system reads

$$\frac{\partial \rho}{\partial t} + \text{div}(\rho u) = 0,$$

$$\rho \frac{\partial u}{\partial t} + (u \cdot \nabla x)u = -\nabla x p - \rho \nabla x U,$$

$$U(t,x) = -\int \frac{\rho(t,y)}{|x-y|} \, dy,$$

with the equation of state

$$p(\rho) = \rho \Psi'(\rho) - \Psi(\rho).$$

Here $p$ denotes the pressure of the fluid and $u$ denotes its velocity field; the meaning of $\rho$ and $U$ is as before. If $\rho_0$ is a minimizer of the reduced energy-Casimir functional $\mathcal{H}_C^r$, then using the Euler-Lagrange identity in Thm. [13] (b) it is easy to check that $\rho_0$ and the zero velocity field $u_0 \equiv 0$ solve the flat Euler-Poisson system. Clearly, the state $(\rho_0,u_0)$ minimizes the energy

$$\mathcal{H}(\rho,u) = \frac{1}{2} \int |u|^2 \rho \, dx + \int \Psi(\rho) \, dx + E_{\text{pot}}(\rho),$$

among the states with $\int \rho = M$. Formally, the energy is conserved along solutions of the Euler-Poisson system. An expansion about $(\rho_0,u_0)$ gives

$$\mathcal{H}(\rho,u) - \mathcal{H}(\rho_0,u_0) = \frac{1}{2} \int |u|^2 \rho \, dx + d(\rho,\rho_0) + E_{\text{pot}}(\rho - \rho_0),$$
where
\[
d(\rho, \rho_0) := \int [\Psi(\rho) - \Psi(\rho_0) + (U_0 - E_0)(\rho - \rho_0)] dx \geq 0.
\]

Now the stability proof proceeds in the same way as in the Vlasov case. We can for every \(\varepsilon > 0\) find a \(\delta > 0\) such that for every solution \(t \mapsto (\rho(t), u(t))\) of the flat Euler-Poisson system with \(\rho(0) \in \mathcal{F}_M^t\), which preserves energy and mass, the initial estimate
\[
\frac{1}{2} \int |u(0)|^2 \rho(0) dx + d(\rho(0), \rho_0) + ||\rho(0) - \rho_0||_{pot}^2 < \delta
\]
implies that as long as the solution exists and up to shifts in space,
\[
||\rho(t) - \rho_0||_{1+1/n} + \frac{1}{2} \int |u(t)|^2 \rho(t) dx + d(\rho(t), \rho_0) + ||\rho(t) - \rho_0||_{pot}^2 < \varepsilon.
\]

Neither in the flat case nor in the three dimensional one is there an existence theory for global solutions of the Euler-Poisson system, which preserve all the necessary quantities, so the result is conditional in this sense.

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