ON MULTI-SOLITONS FOR COUPLED LOWEST LANDAU LEVEL EQUATIONS

Abstract. We consider a coupled system of nonlinear Lowest Landau Level equations. We first show the existence of multi-solitons with an exponentially localised error term in space, and then we prove a uniqueness result. We also show a long time stability result of the sum of traveling waves having all the same speed, under the condition that they are localised far away enough from each other. Finally, we observe that these multi-solitons provide examples of dynamics for the linear Schrödinger equation with harmonic potential perturbed by a time-dependent potential.

1. Introduction and main results

In this paper, we continue the study of a system of coupled Lowest Landau Level (LLL) equations which was initiated in [26]. Denote by $\mathcal{E}$ the Bargmann-Fock space defined as

$$\mathcal{E} = \{ u(z) = e^{-\frac{|z|^2}{2}} f(z), \ f \text{ entire holomorphic} \} \cap L^2(\mathbb{C})$$

and consider $\Pi$ the orthogonal projection on $\mathcal{E}$. The LLL system then reads

$$\begin{cases}
i \partial_t u = \Pi(|v|^2 u), & (t, z) \in \mathbb{R} \times \mathbb{C}, \\
i \partial_t v = \sigma \Pi(|u|^2 v), \\
u(0, \cdot) = u_0 \in \mathcal{E}, \ v(0, \cdot) = v_0 \in \mathcal{E},
\end{cases}$$

where $\sigma \in \{1, -1\}$ is fixed. Such systems arise in the description of fast rotating Bose-Einstein condensates in interaction: for more details and references on the modeling, see [1, 17, 24], the introduction of [14], and references therein. The system (1.1) is Hamiltonian with the structure

$$\begin{cases}
\dot{u} = -\frac{i}{\sigma} \delta \mathcal{H} \delta u, \\
\dot{v} = \frac{i}{\sigma} \delta \mathcal{H} \delta v,
\end{cases}$$

where the Hamiltonian functional is given by

$$\mathcal{H}(u, v) = \int_{\mathbb{C}} |u|^2 |v|^2 dL,$$

and where $L$ stands for Lebesgue measure on $\mathbb{C}$. For mathematical results on LLL equations we refer to [25, 2, 3, 11, 8].

In the case $\sigma = -1$, we have constructed in [26] traveling-waves (solitons) solutions to (1.1) and the aim of the present work is to show the existence of multi-solitons and study some of their properties. When $\sigma = 1$, such solutions are excluded, because their existence would contradict the conservation laws of the system (see [26, Proposition 1.4]). Therefore, from now on, we assume...
and magnetic translations. It turns out that this latter space coincides with the harmonic Sobolev space. For space rotations equipped with the natural norm the weighted Lebesgue space and we define rotations which induce conservation laws (see [14, Section 2] for more details). These symmetries are phase following equivalence of norms holds true.

Symmetries and conservation laws. The system (1.2) is preserved by several symmetries, which induce conservation laws (see [14] Section 2 for more details). These symmetries are phase rotations

\[ T_{\theta_1, \theta_2} : (u, v)(z) \mapsto (e^{i\theta_1}u(z), e^{i\theta_2}v(z)) \quad \text{for} \ (\theta_1, \theta_2) \in \mathbb{T}^2, \]

space rotations

\[ L_\theta : (u, v)(z) \mapsto (u(e^{i\theta}z), v(e^{i\theta}z)) \quad \text{for} \ \theta \in \mathbb{T}, \]

and magnetic translations

\[ R_\alpha : (u, v)(z) \mapsto (u(z + \alpha)e^{\frac{i}{2}(\alpha - z\alpha)}, v(z + \alpha)e^{\frac{i}{2}(\alpha - z\alpha)}) \quad \text{for} \ \alpha \in \mathbb{C}. \]

The corresponding conservation laws are: the mass

\[ M(u) = \int_{\mathbb{C}} |u(z)|^2 dL(z), \quad M(v) = \int_{\mathbb{C}} |v(z)|^2 dL(z), \]

the angular momentum

\[ P_-(u, v) = \int_{\mathbb{C}} (|z|^2 - 1)\left(|u(z)|^2 - |v(z)|^2\right)dL(z), \]

and the magnetic momentum

\[ Q_-(u, v) = \int_{\mathbb{C}} z\left(|u(z)|^2 - |v(z)|^2\right)dL(z). \]

1.2. Functional spaces. In order to state our results we need to define a few spaces. Namely, for \( s \geq 0 \), we denote by

\[ L^{2,s} = \left\{ u \in \mathcal{S}'(\mathbb{C}), \langle z \rangle^s u \in L^2(\mathbb{C}) \right\}, \quad \langle z \rangle = (1 + |z|^2)^{1/2} \]

the weighted Lebesgue space and we define

\[ L^{2,s}_\mathcal{E} = L^{2,s} \cap \mathcal{E}. \]

It turns out that this latter space coincides with the harmonic Sobolev space. For \( s \geq 0 \) we consider

\[ \mathbb{H}^s(\mathbb{C}) = \left\{ u \in \mathcal{S}'(\mathbb{C}), \ H^{s/2}u \in L^2(\mathbb{C}) \right\} \cap \mathcal{E}, \quad (1.3) \]

equipped with the natural norm \( \|u\|_{\mathbb{H}^s(\mathbb{C})} = \|H^{s/2}u\|_{L^2(\mathbb{C})} \). Then, we have \( \mathbb{H}^s(\mathbb{C}) = L^{2,s}_\mathcal{E} \) and the following equivalence of norms holds true

\[ c\|\langle z \rangle^s u\|_{L^2(\mathbb{C})} \leq \|u\|_{\mathbb{H}^s(\mathbb{C})} \leq C\|\langle z \rangle^s u\|_{L^2(\mathbb{C})}, \quad \forall u \in L^{2,s}_\mathcal{E}, \quad (1.4) \]

see [14] Lemma C.1 for a proof.

Similarly, for \( \kappa \geq 0 \), we denote by

\[ \mathcal{X}^\kappa = \left\{ u \in \mathcal{S}'(\mathbb{C}), \ e^{\kappa|z|}u \in L^2(\mathbb{C}) \right\}, \]
and we set
\[ X^\kappa_E = \{ u \in \mathcal{S}'(\mathbb{C}), \ e^{\kappa|z|}u \in L^2(\mathbb{C}) \} \cap E. \]

1.3. Global existence results for the system \((1.2)\). We first recall the global well-posedness result for \((1.2)\), which is contained in [26, Theorem 1.1].

**Theorem 1.1** (Theorem 1.1, [26]). For every \((u_0, v_0) \in E \times E\), there exists a unique solution \((u, v) \in C^\infty(\mathbb{R}, E \times E)\) to the system \((1.2)\), and this solution depends smoothly on \((u_0, v_0)\). Moreover,

(i) for every \(t \in \mathbb{R}\)
\[ M(u) = \int_{\mathbb{C}} |u(t, z)|^2 dL(z) = M(u_0), \quad M(v) = \int_{\mathbb{C}} |v(t, z)|^2 dL(z) = M(v_0), \]
and
\[ \mathcal{H}(u, v) = \int_{\mathbb{C}} |u(t, z)|^2 |v(t, z)|^2 dL(z) = \mathcal{H}(u_0, v_0); \]

(ii) if \((zu_0, zv_0) \in L^2(\mathbb{C}) \times L^2(\mathbb{C})\), then \((zu(t), zv(t)) \in L^2(\mathbb{C}) \times L^2(\mathbb{C})\) for every \(t \in \mathbb{R}\), and
\[ P_-(u, v) = \int_{\mathbb{C}} (|z|^2 - 1) (|u(t, z)|^2 - |v(t, z)|^2) dL(z) = P_-(u_0, v_0), \]
\[ Q_-(u, v) = \int_{\mathbb{C}} z(|u(t, z)|^2 - |v(t, z)|^2) dL(z) = Q_-(u_0, v_0); \]

(iii) if for some \(s > 0\), \((\langle z \rangle^s u_0, \langle z \rangle^s v_0) \in L^2(\mathbb{C}) \times L^2(\mathbb{C})\), then \((\langle z \rangle^s u(t), \langle z \rangle^s v(t)) \in L^2(\mathbb{C}) \times L^2(\mathbb{C})\) for every \(t \in \mathbb{R}\).

We can also prove polynomial bounds on the possible growth of Sobolev norms for \((1.2)\), we refer to [26, Theorem 1.5] for details.

It turns out that equation \((1.2)\) is also globally well-posed for exponentially localised functions and we are able to obtain a quantitative estimate on the long time behaviour of the solutions as well as a stability result.

**Proposition 1.2.** Let \(\kappa \geq 0\), then the following properties hold true:

(i) assume that \((u_0, v_0) \in X^\kappa_E \times X^\kappa_E\), then the corresponding solution to \((1.2)\) satisfies \((u, v) \in C^\infty(\mathbb{R}, X^\kappa_E \times X^\kappa_E)\). Moreover, for every \(t \in \mathbb{R}\),
\[ \|e^{\kappa|z|}u(t)\|_{L^2(\mathbb{C})} \leq \|e^{\kappa|z|}u_0\|_{L^2(\mathbb{C})}^2 + \|v_0\|_{L^2(\mathbb{C})}^2 |t|, \]
\[ \|e^{\kappa|z|}v(t)\|_{L^2(\mathbb{C})} \leq \|e^{\kappa|z|}v_0\|_{L^2(\mathbb{C})}^2 + \|u_0\|_{L^2(\mathbb{C})}^2 |t|, \]  \( (1.5) \)
where the constant \(c_\kappa > 0\) only depends on \(\kappa > 0\) (notice that \(c_0 = 0\) by the conservation of the \(L^2\)-norm);

(ii) consider two solutions \((u, v) \in C^\infty(\mathbb{R}, X^\kappa_E \times X^\kappa_E)\) and \((\tilde{u}, \tilde{v}) \in C^\infty(\mathbb{R}, X^\kappa_E \times X^\kappa_E)\) to \((1.2)\). Then, for all \(t \in \mathbb{R}\)
\[ \|e^{\kappa|z|}(u(t) - \tilde{u}(t))\|_{L^2(\mathbb{C})}^2 + \|e^{\kappa|z|}(v(t) - \tilde{v}(t))\|_{L^2(\mathbb{C})}^2 \]
\[ \leq \left( \|e^{\kappa|z|}(u_0 - \tilde{u}_0)\|_{L^2(\mathbb{C})}^2 + \|e^{\kappa|z|}(v_0 - \tilde{v}_0)\|_{L^2(\mathbb{C})}^2 \right) e^{c_\kappa(\|u_0\|_{L^2}^2 + \|\tilde{u}_0\|_{L^2}^2 + \|v_0\|_{L^2}^2 + \|\tilde{v}_0\|_{L^2}^2) |t|}, \]  \( (1.6) \)
where the constant \(c_\kappa > 0\) only depends on \(\kappa > 0\).

The estimate \((1.5)\) is sharp, see \((1.11)\) below.
1.4. **Solitons and multi-solitons.** Using the invariances induced by phase rotations and magnetic translations, it is natural to look for particular solutions for equation (1.2) of the form

\[ (u(t, z), v(t, z)) = (e^{-i\lambda t} U(z + \alpha t)e^{\frac{1}{2}(\gamma - \overline{\gamma})t}, e^{-i\mu t} V(z + \alpha t)e^{\frac{1}{2}(\gamma - \overline{\gamma})t}), \]

that we call progressive or traveling waves. Such solutions do exist, and by [26, Theorem 1.6], the progressive waves in \( E \), when \( \alpha \neq 0 \), which have a finite number of zeros are given by the initial conditions

\[
\begin{align*}
U &= K e^{i\alpha} \left( \frac{1}{2} \varphi_0^\gamma + \frac{\sqrt{3}}{2} i e^{i\theta} \varphi_1^\gamma \right) \\
V &= K e^{i\beta} \left( \frac{1}{2} \varphi_0^\beta - \frac{\sqrt{3}}{2} i e^{i\phi} \varphi_1^\beta \right),
\end{align*}
\]

with \( \gamma \in \mathbb{C} \) and

\[ \varphi_0^\gamma(z) = \frac{1}{\sqrt{\pi n!}} e^{-|z|^2/2} e^{-\gamma z}. \]

with \( K \geq 0 \), with \( \theta, a, b \in \mathbb{R} \), where

\[ \lambda = \frac{K^2}{32\pi} (7 + 2\sqrt{3}\Im(\gamma e^{-i\theta})), \quad \mu = \frac{K^2}{32\pi} (-7 + 2\sqrt{3}\Im(\gamma e^{-i\theta})), \]

and with the speed

\[ \alpha = \frac{\sqrt{3}}{32\pi} K^2 e^{-i\theta}. \]

It is interesting to notice that any non trivial traveling wave of the form (1.7) has growing Sobolev norms. Actually, if \( u(t) = e^{-i\lambda R_\alpha t} U \), then

\[ \|\langle z \rangle^s u(t)\|_{L^2(C)} = \|\langle z \rangle^s R_\alpha t U\|_{L^2(C)} = \|\langle z - \alpha t \rangle^s U\|_{L^2(C)} \sim |\alpha|^s |t|^s \|U\|_{L^2(C)}, \]

when \( t \to \pm \infty \). Moreover, the previous growth of norms is the strongest possible by [26, Theorem 1.5]. Similarly, when \( t \to \pm \infty \),

\[ \|e^{\kappa |z|} u(t)\|_{L^2(C)} = \|e^{\kappa |z - \alpha t|} U\|_{L^2(C)} \sim e^{\kappa |\alpha| |t|} \|e^{-\kappa \tau \Re(e^{-i\theta})} U\|_{L^2(C)}, \]

with \( \theta = \arg(\alpha) \) and \( \tau = \text{sign}(t) \). Thus (1.11) shows the sharpness of (1.5).

1.4.1. **Existence of multi-solitons.** A natural question is the existence of solutions to (1.2) which are a finite sum of such traveling waves. The answer is positive and this is the content of the following result:

**Theorem 1.3.** Let \( n \geq 1 \). For \( 1 \leq j \leq n \), let \( (K_j, \alpha_j, b_j, \theta_j, \gamma_j) \in \mathbb{R}_+^n \times \mathbb{R} \times \mathbb{R} \times \mathbb{R} \times \mathbb{C} \) and consider the parameters \( (\lambda_j, \mu_j, \alpha_j) \in \mathbb{R} \times \mathbb{R} \times \mathbb{C}^* \) given by (1.9) and (1.10). Assume that \( \alpha_j \neq \alpha_\ell \) for \( j \neq \ell \). Denote by

\[ \alpha_\sharp = \min_{j \neq \ell} |\alpha_j - \alpha_\ell|. \]

Then, for all \( \kappa > 0 \), there exists a solution \( (u, v) \in C^{\infty}(\mathbb{R}, X_\kappa^\sharp \times X_\kappa^\sharp) \) to equation (1.2) of the form

\[
\begin{align*}
\begin{cases}
&u(t, z) = \sum_{j=1}^n e^{-i\lambda_j t} U_j(z + \alpha_j t)e^{\frac{1}{2}(\gamma_j - \overline{\gamma}_j)t} + r_1(t, z) \\
&v(t, z) = \sum_{j=1}^n e^{-i\mu_j t} V_j(z + \alpha_j t)e^{\frac{1}{2}(\gamma_j - \overline{\gamma}_j)t} + r_2(t, z),
\end{cases}
\end{align*}
\]

where the \( (U_j, V_j) \) take the form (1.8) and where the error terms satisfy: for all \( c < \frac{1}{4} \)
and all \( m \in \mathbb{N} \), there exists \( C_{m, \kappa} > 0 \) such that for all \( t \geq 0 \)
\[
\| e^{\kappa |z|} (\partial_t^m r_1)(t) \|_{L^2} + \| e^{\kappa |z|} (\partial_t^m r_2)(t) \|_{L^2} \leq C_{m, \kappa} e^{-c_0 \kappa^2 t^2}. \tag{1.13}
\]

Notice that thanks to the Carlen inequality \((1.27)\) below, the bound \((1.13)\) implies the following pointwise estimate: for all \( c < 1/4 \), all \( m \in \mathbb{N} \) and all \( z \in \mathbb{C} \)
\[
\left| (\partial_t^m r_1)(t, z) \right| + \left| (\partial_t^m r_2)(t, z) \right| \leq C_{m, \kappa} e^{-c_0 \kappa^2 t^2} e^{-\kappa |z|}.
\]

The construction of multi-solitons for \((1.2)\) relies on classical arguments, including backwards in time integration and energy estimates. We refer to \([22, 6, 7, 12, 11]\) where these methods were used. The situation here is very favorable since in the space \( E \times E \) in \([12]\), it is that the convergence to the multi-soliton holds in weighted Sobolev spaces (namely in \( H^1 \cap \mathcal{F}(H^1) \)). Another interesting similarity with the results as in \((1.13)\) is obtained in \([12]\) where multi-Gaussian solutions are constructed for the Schrödinger equation with logarithmic nonlinearity (logNLS). Another interesting similarity with the results in \([12]\), is that the convergence to the multi-soliton holds in weighted Sobolev spaces (namely in \( H^1 \cap \mathcal{F}(H^1) \)). In the present case, one can even upgrade to exponential weights, and this is due to the absence of linear part in the equation \((1.2)\) (see Remark \(1.4\) for the case of LLL with a linear part). We refer to \([5]\) and references therein for more results on the dynamics of logNLS.

The result of Theorem \(1.3\) actually holds under the weaker assumption that each traveling wave \((U, V) \in E \times E\) of the sum \((1.12)\) satisfies a Gaussian bound
\[
|U(z)| + |V(z)| \leq C e^{-c_0 |z|^2}, \tag{1.14}
\]
for some \( C, c_0 > 0 \), and the proof of the Theorem \(1.3\) is written using only the assumption \((1.14)\). In this latter case, \((1.13)\) is replaced by
\[
\| e^{\kappa |z|} (\partial_t^m r_1)(t) \|_{L^2} + \| e^{\kappa |z|} (\partial_t^m r_2)(t) \|_{L^2} \leq C_{m, \kappa} e^{-c_m \alpha^2 t^2}, \tag{1.15}
\]
for some \( c_m > 0 \). However, we do not know if there exist other traveling waves (with \( \alpha \neq 0 \)) than the ones exhibited in \((1.8)\) (such traveling waves would then have an infinite number of zeros by \([26, \text{Theorem } 1.6]\)).

In the hypotheses of Theorem \(1.3\) one can also allow for the case where \( \alpha_j = 0 \) for at most only one \( 1 \leq j \leq n \). In this case, \((e^{-i\lambda t} U(z), e^{-i\mu t} V(z))\) is a solution to \((1.2)\) if and only if
\[
\begin{cases}
\lambda U = \Pi(|U|^2 U) \\
\mu V = -\Pi(|V|^2 V).
\end{cases} \tag{1.16}
\]

By Theorem \(A.1\) any solution \((U, V) \in E \times E\) to \((1.16)\) satisfies the bound \((1.14)\) for all \( c_0 \leq 1/2 \). Examples of solutions of \((1.16)\) are for instance:

- \((U, V) = (A_1 \varphi_{n_1}^\gamma, A_2 \varphi_{n_2}^\gamma)\), for any \( A_1, A_2, \gamma \in \mathbb{C} \) and \( n_1, n_2 \in \mathbb{N} \), by \([26, \text{Theorem } 1.6]\) ;
- \((U, V) = (U, U)\) and \( \mu = -\lambda \) where \( U \in E \) is any solution of \( \lambda U = \Pi(|U|^2 U) \). We refer to \([14, \text{Appendix A}]\) for explicit examples.
By reversibility of the equation (1.12), similar multi-solitons can be constructed in the regime \( t \to -\infty \). Actually, if \((u, v)\) is a solution to (1.12), then \((\bar{u}, \bar{v})\) is also a solution where \((\bar{u}, \bar{v})(t) := (v, u)(-t)\). However, the question whether there exists \((r_1, r_2)\) such that (1.13) holds for all \( t \in \mathbb{R} \) is left open.

Since the terms in (1.12) decouple when \( t \to +\infty \), it is easy to observe that the solutions of Theorem 1.3 satisfy

\[
M(u) = M(v) = \sum_{j=1}^{n} K_j^2, \quad \mathcal{H}(u, v) = \frac{11}{64\pi} \sum_{j=1}^{n} K_j^2, \quad P_-(u, v) = \sqrt{3} \sum_{j=1}^{n} \mathfrak{m}(\gamma_j e^{-i\delta_j}) K_j^2, \quad Q_-(u, v) = -\frac{\sqrt{3}}{2} \sum_{j=1}^{n} e^{-i\delta_j} K_j^2.
\]

(1.17)

**Remark 1.4.** We can also construct multi-solitons for the system

\[
\begin{cases}
i\partial_t \bar{u} - \delta H \bar{u} = \Pi(|\bar{v}|^2 \bar{u}), & (t, z) \in \mathbb{R} \times \mathbb{C}, \\
i\partial_t \bar{v} - \delta H \bar{v} = -\Pi(|\bar{u}|^2 \bar{v}), \\
\bar{u}(0, z) = u_0(z), \quad \bar{v}(0, z) = v_0(z),
\end{cases}
\]

(1.18)

where \( \delta \in \mathbb{R} \) is a given dispersion parameter. Actually, the change of unknown \((\bar{u}, \bar{v}) = e^{-i\delta t H}(u, v)\) shows that the system (1.12) is equivalent to (1.18) (see [26, Section 1.7.2] for more details). Recall that \( e^{i\tau H} = e^{2i\tau L_{2\tau}} \) (which can be directly checked by testing on the complete family \((\varphi_n)_{n \geq 0}\)), then Theorem 1.3 enables the construction of the following multi-solitons for (1.18)

\[
\begin{cases}
\bar{u}(t, z) = \sum_{j=1}^{n} e^{-i(\lambda_j + 2\delta)t} L_{-2\delta t} U_j(z + \alpha_j t)e^{\frac{i}{2}(\varpi \alpha_j - z \varpi)} + \tilde{r}_1(t, z) \\
\bar{v}(t, z) = \sum_{j=1}^{n} e^{-i(\mu_j + 2\delta)t} L_{-2\delta t} V_j(z + \alpha_j t)e^{\frac{i}{2}(\varpi \alpha_j - z \varpi)} + \tilde{r}_2(t, z),
\end{cases}
\]

where for all \( s \geq 0 \) and all \( t \geq 0 \)

\[
\|z^s(\partial_t^m \tilde{r}_1(t))\|_{L^2} + \|z^s(\partial_t^m \tilde{r}_2(t))\|_{L^2} \leq C_{s, m} e^{-c_{s, m} t^2}.
\]

(1.19)

We refer to paragraph 4.3 for a proof of (1.19).

1.4.2. *A uniqueness result in \( X^s_\varpi \).* We are able to prove that the multi-soliton constructed in Theorem 1.3 is actually unique in the class \( X^s_\varpi \), provided that \( \kappa > 0 \) is large enough:

**Theorem 1.5.** Let \( n \geq 1 \). For \( 1 \leq j \leq n \), let \((K_j, a_j, b_j, \theta_j, \gamma_j) \in \mathbb{R}_+^n \times \mathbb{R} \times \mathbb{R} \times \mathbb{C} \) and consider the parameters \((\lambda_j, \mu_j, \alpha_j) \in \mathbb{R} \times \mathbb{R} \times \mathbb{C}^* \) given by (1.9) and (1.10). Assume that \( \alpha_j \neq \alpha_\ell \) for \( j \neq \ell \). Set

\[
\delta = \frac{\max_{1 \leq j \leq n} K_j^2}{\min_{1 \leq j \leq n} K_j^2} = \frac{\max_{1 \leq j \leq n} |\alpha_j|}{\min_{1 \leq j \leq n} |\alpha_j|}.
\]

(1.20)

There exists a universal constant \( c_0 > 0 \) such that if \( \kappa > c_0 \delta \) and if \((\bar{u}, \bar{v}) \in C(\mathbb{R}, X^s_\varpi \times X^s_\varpi) \) is a solution to equation (1.12) of the form

\[
\begin{cases}
\bar{u}(t, z) = \sum_{j=1}^{n} e^{-i\lambda_j t} U_j(z + \alpha_j t)e^{\frac{i}{2}(\varpi \alpha_j - z \varpi)} + \tilde{r}_1(t, z) \\
\bar{v}(t, z) = \sum_{j=1}^{n} e^{-i\mu_j t} V_j(z + \alpha_j t)e^{\frac{i}{2}(\varpi \alpha_j - z \varpi)} + \tilde{r}_2(t, z),
\end{cases}
\]

(1.21)
where the \((U_j, V_j)\) take the form (1.8) and where
\[
\left\|e^{\alpha_j |z|} \tilde{r}_1(t)\right\|_{L^2} + \left\|e^{\alpha_j |z|} \tilde{r}_2(t)\right\|_{L^2} \to 0, \quad t \to +\infty,
\]
(1.22)
then \((\tilde{u}, \tilde{v}) \equiv (u, v)\), where \((u, v)\) is given in Theorem 1.3.

In particular, if \(\kappa > c_0 \delta\), the solutions constructed in Theorem 1.3 do not depend on \(\kappa\). The assumption (1.22) is consistent with the result of Theorem 1.3 but this assumption is quite strong. It would be interesting to relax it by asking only decay in \(L^2_{x,s}\) for some \(s \geq 0\), but the situation would more involved in this case. Actually, the assumption (1.22) implies an exponential decay in time of the error term and as a consequence the interaction terms can quite easily be controlled.

Contrarily to the Theorem 1.3 in the previous result, one needs the assumption \(\alpha_j \neq 0\) for all \(1 \leq j \leq n\). However, the result of Theorem 1.5 holds true for any traveling waves satisfying the weaker assumption (1.14), but in this latter case, the threshold is
\[
\tilde{\delta} = \max_{1 \leq j \leq n} \frac{K_j^2}{\min_{1 \leq j \leq n} |\alpha_j|},
\]
(1.23)
where \(K_j = \|U_j\|_{L^2} = \|V_j\|_{L^2}\). The modification (1.23) comes from the fact that one does no more necessarily have the relation (1.10) for a general traveling wave, but only an inequality \(|\alpha_j| \leq \frac{K_j^2}{2\sqrt{2\pi}}\) (see [26, Proposition 1.8]).

Notice that the conditions (1.20) and (1.23) are consistent with the symmetries of the problem. In particular, the conditions are invariant by scaling: if \((u, v)\) is a solution to (1.2), then for all \(A > 0\), \((u_A, v_A)\) defined by \((u_A(t, z), v_A(t, z)) = (Au(A^2t, z), Av(A^2t, z))\) is also a solution and under this transformation one has \((K, \alpha) \to (AK, A^2\alpha)\).

The multi-soliton enjoys a rigidity property. Consider a multi-soliton of the form (1.21) where the remainder terms satisfy (1.22) with \(\kappa = 0\). Then either \((\tilde{u}, \tilde{v}) \equiv (u, v)\), where \((u, v)\) is given in Theorem 1.3 or there exist \(C, c > 0\) such that for all \(t \in \mathbb{R}\)
\[
\|\tilde{r}_1(t)\|_{L^2} + \|\tilde{r}_2(t)\|_{L^2} \geq Ce^{-c|t|},
\]
see Lemma 2.2. In other words, there is only one multi-soliton which enjoys a Gaussian decay in time. A similar property holds true for logNLS (1.2).

1.4.3. Nonlinear superposition principle. The next result shows that if one starts from a sum of traveling waves which all have the same speed but which are localised far away enough, then one has a good description of the dynamics of the solution to (1.2) for long times, depending on the relative distance of the traveling waves.

**Theorem 1.6.** Let \((K, \theta) \in \mathbb{R}^*_+ \times \mathbb{R}\) and set \(\alpha = \frac{\sqrt{3}}{32\pi} K^2 e^{-i\theta}\). Let \(n \geq 1\) and for \(1 \leq j \leq n\), let \((a_j, b_j, \gamma_j) \in \mathbb{R} \times \mathbb{R} \times \mathbb{C}\) and consider the parameters \((\lambda_j, \mu_j) \in \mathbb{R} \times \mathbb{R}\) given by (1.9). Assume that \(\gamma_j \neq \gamma_{\ell}\) for \(j \neq \ell\), and denote by
\[
\epsilon = \min_{j \neq \ell} |\gamma_j - \gamma_{\ell}|.
\]
Consider the solution \((u, v) \in C^\infty(\mathbb{R}, \mathcal{E} \times \mathcal{E})\) to equation (1.2) such that
\[
u_0(z) = \sum_{j=1}^n V_j(z), \quad v_0(z) = \sum_{j=1}^n V_j(z),
\]
and\(u_0(z) = \sum_{j=1}^n U_j(z)\).
where the \((U_j, V_j)\) take the form \([1.8]\). Then
\[
\begin{align*}
\begin{cases}
    u(t, z) = \sum_{j=1}^{n} e^{-i\lambda_j t} U_j(z + \alpha t) e^{i(x\alpha - z\gamma)t} + r_1(t, z) \\
    v(t, z) = \sum_{j=1}^{n} e^{-i\mu_j t} V_j(z + \alpha t) e^{i(x\alpha - z\gamma)t} + r_2(t, z),
\end{cases}
\end{align*}
\]
and where the error terms satisfy: there exist absolute constants \(c, C > 0\) such that for all \(t \in \mathbb{R}\)
\[
\|r_1(t)\|_{L^2} + \|r_2(t)\|_{L^2} \leq C K^2 \sqrt{|t|} e^{-\frac{c}{|t|} + cn^2 K^2 |t|}.
\]
(1.24)
In particular for \(|t| \leq \epsilon^{-2}/(10cn^2 K^2)\), then
\[
\|r_1(t)\|_{L^2} + \|r_2(t)\|_{L^2} \leq C e^{-\frac{c}{|t|}}.
\]

The proof of Theorem \([1.3]\) is in the same spirit as the proof of Theorem \([1.3]\): in the present case, smallness is obtained thanks to the large distance between the waves \((\epsilon \ll 1)\) instead of considering large times as in Theorem \([1.3]\). This result can be compared with \([13, \text{Theorem 1.10}]\) where a similar phenomenon occurs for the logNLS equation.

By a slight modification of our analysis, as in Theorem \([1.3]\) one should also be able to obtain bounds for \((\partial_{\nu}^\alpha r_1, \partial_{\nu}^\alpha r_2)\) and/or work in \(X^s_r\) spaces, but we do not write the details here.

1.5. **Unbounded dynamics for 2D linear harmonic oscillator.** The result of Theorem \([1.3]\) allows us to give new examples of unbounded trajectories to the 2D linear harmonic oscillator
\[
\begin{align*}
\begin{cases}
    i \partial_t \psi - H \psi + V(t, x, y) \psi = 0, & (t, x, y) \in \mathbb{R} \times \mathbb{R}^2, \\
    \psi(0, \cdot) = \psi_0 \in L^2(\mathbb{R}^2),
\end{cases}
\end{align*}
\]
(1.25)
Recall the definition \([1.3]\) of the Sobolev space \(H^\sigma(\mathbb{C})\). Our result for the equation \([1.25]\) reads as follows:

**Theorem 1.7.** Let \(n \geq 1\). For \(1 \leq j \leq n\), let \((K_j, \omega_j, b_j, \theta_j, \gamma_j) \in \mathbb{R}_+^n \times \mathbb{R} \times \mathbb{R} \times \mathbb{R} \times \mathbb{C}\) and consider the parameters \((\lambda_j, \mu_j, \alpha_j) \in \mathbb{R} \times \mathbb{R} \times \mathbb{C}^*\) given by \([1.9]\) and \([1.10]\). Assume that \(\alpha_j \neq \alpha_\ell\) for \(j \neq \ell\).

Then there exists a potential \(V \in C^\infty(\mathbb{R} \times \mathbb{R}^2, \mathbb{R})\) such that for all \(\sigma \geq 0\) and all \(k \in \mathbb{N}\)
\[
\lim_{t \to +\infty} \|\partial_t^k V(t)\|_{H^\sigma(\mathbb{C})} = 0,
\]
(1.26)
and there exists a solution \(\psi \in C^\infty(\mathbb{R} \times \mathbb{R}^2, \mathbb{C})\) to the equation \([1.25]\) of the form
\[
\psi(t) = \sum_{j=1}^{n} e^{-i\lambda_j \ln t} e^{-2i\alpha_j \ln t} R_{\alpha_j} \ln t U_j(t) + \eta(t),
\]
where \(\|\eta(t)\|_{H^1(\mathbb{C})} \rightarrow 0\), when \(t \rightarrow +\infty\).

In particular, for all \(1 \leq j \leq n\),
\[
\left\| e^{-i\lambda_j \ln t} e^{-2i\alpha_j \ln t} R_{\alpha_j} \ln t U_j(t) \right\|_{H^1(\mathbb{C})} = \left\| R_{\alpha_j} \ln t U_j \right\|_{H^1(\mathbb{C})} \sim c_j \ln t, \quad t \rightarrow +\infty,
\]
for some \(c_j > 0\). The previous term has Gaussian decay and is concentrated near the point \(x + iy \sim -\alpha_j \ln t\). Therefore, \(\psi\) is a sum of space-localised bubbles and
\[
\|\psi(t)\|_{H^1(\mathbb{C})} \sim \left( \sum_{j=1}^{n} c_j \right) \ln t, \quad t \rightarrow +\infty.
\]

The result of Theorem \([1.7]\) is a direct application of \([11, \text{Proposition 7.1}]\) (see also \([11, \text{Theorem 1.1}]\)), using the solutions constructed in Theorem \([1.3]\).
1.6. Analysis in the Bargmann-Fock space and notations. We end this section by recalling a few results and fixing some notations. The harmonic oscillator $H$ is defined by

$$H = -\frac{\partial_z^2}{\partial z^2} + |z|^2 = -\partial_x^2 - \partial_y^2 + (x^2 + y^2).$$

Denote by $(\varphi_n)_{n \geq 0}$ the family of the special Hermite functions given by

$$\varphi_n(z) = \frac{1}{\sqrt{\pi n!}} z^n e^{-\frac{|z|^2}{2}}.$$

The family $(\varphi_n)_{n \geq 0}$ forms a Hilbertian basis of $E$ (see [28, Proposition 2.1]), and the $\varphi_n$ are the eigenfunctions of $H$, namely

$$H \varphi_n = 2(n + 1) \varphi_n, \quad n \geq 0.$$

For $\gamma \in \mathbb{C}$, we define

$$\varphi_n^\gamma(z) = R_\gamma(\varphi_n)(z) = \frac{1}{\sqrt{\pi n!}} (z - \gamma)^n e^{-\frac{|z|^2}{2} - \frac{|\gamma|^2}{2} + \gamma z}.$$

The kernel of $\Pi$, the orthogonal projection on $E$, is explicitly given by

$$K(z, \xi) = \sum_{n=0}^{+\infty} \varphi_n(z) \overline{\varphi_n}(\xi) = \frac{1}{\pi} e^{\frac{|z|^2}{2}} e^{\frac{|\xi|^2}{2}} e^{-\frac{|z|^2}{2}}, \quad (z, \xi) \in \mathbb{C} \times \mathbb{C},$$

and therefore we get the formula

$$[\Pi u](z) = \frac{1}{\pi} e^{-\frac{|z|^2}{2}} \int_{\mathbb{C}} e^{\frac{|z|^2}{2}} u(w) dL(w),$$

where $L$ stands for Lebesgue measure on $\mathbb{C}$.

We define the enlarged lowest Landau level space as

$$\tilde{E} = \left\{ u(z) = e^{-\frac{|z|^2}{2}} f(z), \; f \text{ entire holomorphic} \right\} \cap \mathscr{S}'(\mathbb{C}) = \left\{ u \in \mathscr{S}'(\mathbb{C}), \partial_z u + \frac{z}{2} u = 0 \right\}.$$

By Carlen [3], for all $u \in \tilde{E}$ the following hypercontractivity estimates hold true

$$\text{if } 1 \leq p \leq q \leq +\infty, \quad \left( \frac{q}{2\pi} \right)^{1/q} \| u \|_{L^q(\mathbb{C})} \leq \left( \frac{p}{2\pi} \right)^{1/p} \| u \|_{L^p(\mathbb{C})}. \quad (1.27)$$

In this paper $c, C > 0$ denote universal constants the value of which may change from line to line.

1.7. Plan of the paper. The rest of the article is organized as follows. In Section 2 we prove the well-posedness result for exponentially localised initial conditions. Section 3 is devoted to technical results, while the next ones contain the proofs of the main theorems.

2. Well-posedness and stability results

2.1. Continuity results for the projector $\Pi$. The next result shows that $\Pi$ is continuous in $\mathcal{X}_E^s$ spaces.

**Lemma 2.1.** Let $s \geq 0$ and $1 \leq p \leq +\infty$, then for all $F \in \mathscr{S}'(\mathbb{C})$,

$$\|(z)^s \Pi(F)\|_{L^p} \leq C \|(z)^s F\|_{L^p}, \quad (2.1)$$

and for all $\kappa \geq 0$

$$\|e^{\kappa |z|} \Pi(F)\|_{L^p} \leq C_\kappa \|e^{\kappa |z|} F\|_{L^p}. \quad (2.2)$$
Proof. The bound \((2.1)\) is proved in \([14]\) Proposition 3.1. Let us show \((2.2)\). For \(F \in \mathcal{S}'(\mathbb{C})\) we have
\[
\Pi(F)(z) = \frac{e^{-|z|^2}}{\pi} \int_\mathbb{C} e^{\frac{|w|^2}{2}} F(w) \, dL(w),
\]
and therefore, using that \(e^{-|z|^2+|w|^2} = e^{-|z-w|^2/2} \) and \(e^{\kappa|z|} \leq e^{\kappa|z-w|} e^{\kappa|w|}\) we get
\[
e^{\kappa|z|} |\Pi(F)(z)| \leq \frac{1}{\pi} \int_\mathbb{C} e^{\kappa|z-w|-|z-w|^2/2} |e^{\kappa|w|} F(w)| \, dL(w) = (\psi * (e^{\kappa|.|} F))(z),
\]
where \(\psi(z) = \frac{1}{\pi} e^{\kappa|z|-|z|^2/2} \in L^1(\mathbb{C})\). Therefore by the Young inequality
\[
\|e^{\kappa|.|} \Pi(F)\|_{L^p(\mathbb{C})} \leq \|\psi\|_{L^1(\mathbb{C})} \|e^{\kappa|.|} F\|_{L^p(\mathbb{C})} \leq C e^{\kappa^2/2} \|e^{\kappa|.|} F\|_{L^p(\mathbb{C})}
\]
which is \((2.2)\). \(\square\)

2.2. Proof of Proposition 1.2. The proof of Proposition 1.2 follows the lines of the proof of \([20]\) Theorem 1.1. We also refer to \([14]\) Section 3 for other well-posedness results for the LLE equation.

- **Proof of the global existence in \(\mathcal{X}_\mathbb{C}\).** By \((2.2)\) and \((1.27)\) we obtain
\[
\|e^{\kappa|.|} \Pi(\alpha \beta \gamma)\|_{L^2} \leq C \|e^{\kappa|.|} \alpha\|_{L^2} \|\beta\|_{L^\infty} \|\gamma\|_{L^\infty}
\leq C \|e^{\kappa|.|} \alpha\|_{L^2} \|\beta\|_{L^2} \|\gamma\|_{L^2}.
\]
The estimate \((2.3)\) allows for the construction of a local in time solution with a fixed point argument, and the globalisation is obtained using that the time of existence only depends on the \(L^2\) norm of the solution.

- **Proof of (1.5).** Let \((u_0, v_0) \in \mathcal{X}_\mathbb{C} \times \mathcal{X}_\mathbb{C}\) and consider \((u, v) \in C^\infty(\mathbb{R}, \mathcal{X}_\mathbb{C} \times \mathcal{X}_\mathbb{C})\) the corresponding solution to equation \((1.2)\). We compute
\[
\frac{d}{dt} \int_\mathbb{C} e^{2\kappa|.|} |u|^2 \, dL = 2\text{Re} \int_\mathbb{C} e^{2\kappa|.| \pi} \partial_t u \, dL
\leq 2\text{Im} \int_\mathbb{C} e^{2\kappa|.| \pi} \Pi(|v|^2 u) \, dL
\leq 2 \|e^{\kappa|.|} u\|_{L^2} \|e^{\kappa|.|} \Pi(|v|^2 u)\|_{L^2}.
\]
Next, by \((2.2)\) we get
\[
\frac{d}{dt} \int_\mathbb{C} e^{2\kappa|.|} |u|^2 \, dL \leq C \|e^{\kappa|.|} u\|_{L^2} \|e^{\kappa|.|} |v|^2 u\|_{L^2}
\leq C \|e^{\kappa|.|} u\|_{L^2}^2 \|v\|_{L^\infty}^2
\leq C \|e^{\kappa|.|} u\|_{L^2}^2 \|v\|_{L^2}^2
\leq C \|e^{\kappa|.|} u\|_{L^2}^2 \|v_0\|_{L^2}^2,
\]
where we used the Carlen inequality \((1.27)\) and the conservation of the \(L^2\)-norm. We conclude by integration.

- **Proof of (1.6).** The proof of this inequality is in the same spirit as the previous one. We have
\[
i \partial_t (u - \bar{u}) = \Pi(|v|^2 u - |\bar{v}|^2 \bar{u}) = \Pi((u - \bar{u})|v|^2 + (v - \bar{v})\bar{u} \bar{v} + \bar{v}(\bar{v} - \bar{u})u \bar{v}).
\]
Then, with the same arguments as in (2.4), we get
\[
\frac{d}{dt} \int_{\mathbb{C}} e^{2|z|} |u - \tilde{u}|^2 dL \leq 0
\]
\[
\leq C_n \|e^{\kappa|z|}(u - \tilde{u})\|_{L^2}(\|e^{\kappa|z|}(u - \tilde{u})\|_{L^2} + \|e^{\kappa|z|}(v - \tilde{v})\|_{L^2})(\|u\|_{L^\infty}^2 + \|\tilde{u}\|_{L^\infty}^2 + \|v\|_{L^\infty}^2 + \|\tilde{v}\|_{L^\infty}^2)
\]
\[
\leq C_n \|e^{\kappa|z|}(u - \tilde{u})\|_{L^2}(\|e^{\kappa|z|}(u - \tilde{u})\|_{L^2} + \|e^{\kappa|z|}(v - \tilde{v})\|_{L^2})(\|u_0\|_{L^2}^2 + \|\tilde{u}_0\|_{L^2}^2 + \|v_0\|_{L^2}^2 + \|\tilde{v}_0\|_{L^2}^2).
\]
Therefore, setting \( \theta = \|e^{\kappa|z|}(u - \tilde{u})\|_{L^2}^2 + \|e^{\kappa|z|}(v - \tilde{v})\|_{L^2}^2 \), we get the bound \( \theta'(t) \leq C_n \theta(t) \) and we deduce (1.6) by integration.

2.3. A rigidity result. A direct consequence of (1.6) (with \( \kappa = 0 \)) is the following rigidity result for the system (1.2) in \( L^2(\mathbb{C}) \):

**Lemma 2.2.** Let \((u, v) \in C^\infty(\mathbb{R}, \mathcal{E} \times \mathcal{E}) \) and \((\tilde{u}, \tilde{v}) \in C^\infty(\mathbb{R}, \mathcal{E} \times \mathcal{E}) \) be solutions to (1.2). Then there exists a universal constant \( c > 0 \) such that for all \( t \in \mathbb{R} \)

\[
\|u(t) - \tilde{u}(t)\|_{L^2(\mathbb{C})}^2 + \|v(t) - \tilde{v}(t)\|_{L^2(\mathbb{C})}^2 \geq \left( \|u_0 - \tilde{u}_0\|_{L^2(\mathbb{C})}^2 + \|v_0 - \tilde{v}_0\|_{L^2(\mathbb{C})}^2 \right) e^{-c(\|u_0\|_{L^2}^2 + \|\tilde{u}_0\|_{L^2}^2 + \|v_0\|_{L^2}^2 + \|\tilde{v}_0\|_{L^2}^2)t}.
\]

In other words, either \((u, v) = (\tilde{u}, \tilde{v})\) or there exist \( c, C > 0 \) such that

\[
\|u(t) - \tilde{u}(t)\|_{L^2(\mathbb{C})} + \|v(t) - \tilde{v}(t)\|_{L^2(\mathbb{C})} \geq C e^{-c|t|}.
\]

Notice that a similar property holds true for the Schrödinger equation with logarithmic nonlinearity, see [12 Lemma 6.2].

3. Preliminary results

3.1. Interactions of traveling waves. The next result shows that the interactions between the traveling waves have a Gaussian decay with respect to their relative distance.

**Lemma 3.1.** Assume that \( U_1, U_2 \in \mathcal{E} \) satisfy for all \( z \in \mathbb{C} \)

\[
|U_1(z)| \leq C_0 e^{-c_0|z|^2}, \quad |U_2(z)| \leq C_0 e^{-c_0|z|^2},
\]
for some \( c_0, C_0 > 0 \). Then

(i) there exists \( C > 0 \) such that for all \( \alpha_1, \alpha_2 \in \mathbb{C} \)

\[
\| (R_{\alpha_1}U_1)(R_{\alpha_2}U_2) \|_{L^\infty} \leq C e^{-\frac{\alpha_1^2}{4} + \alpha_2^2}.
\]

(ii) for all \( s \geq 0 \) and all \( c_1 < c_0 \), there exists \( C > 0 \) such that for all \( \alpha_1, \alpha_2 \in \mathbb{C} \)

\[
\| (z)^s (R_{\alpha_1}U_1)(R_{\alpha_2}U_2) \|_{L^2} \leq C \min (|\alpha_1|^s, |\alpha_2|^s) e^{-\frac{\alpha_1^2 + \alpha_2^2}{4}}.
\]

(iii) for all \( \kappa > 0 \) and all \( c_1 < c_0 \) there exists \( C > 0 \) such that for all \( \alpha_1, \alpha_2 \in \mathbb{C} \)

\[
\|e^{\kappa|z|}(R_{\alpha_1}U_1)(R_{\alpha_2}U_2)\|_{L^2} \leq C \min (e^{\kappa|\alpha_1|}, e^{\kappa|\alpha_2|}) e^{-\frac{\alpha_1^2 + \alpha_2^2}{4}}.
\]

(iv) there exists \( C > 0 \) such that for all \( L > 0 \) and \( \alpha_1 \in \mathbb{C} \)

\[
\|e^{-L|z|}R_{\alpha_1}U_1\|_{L^\infty} \leq C e^{-\alpha_2/2} + C e^{-\alpha_1^2/4}.
\]

**Proof.** (i) First, we observe that we have the relation

\[
|z + \alpha_1|^2 + |z + \alpha_2|^2 = 2|z + \frac{\alpha_1 + \alpha_2}{2}|^2 + \frac{1}{2}|\alpha_1 - \alpha_2|^2.
\]

Therefore by (3.4)

\[
| (R_{\alpha_1}U_1)(R_{\alpha_2}U_2)(z) | \leq C e^{-c_0|z + \alpha_1|^2 - c_0|z + \alpha_2|^2} = C e^{-c_0\frac{|\alpha_1 - \alpha_2|^2}{2}} e^{-2c_0|z + \frac{\alpha_1 + \alpha_2}{2}|^2},
\]

(3.5)
hence the estimate \( (3.2) \).

(ii) Assume for instance \( |\alpha_2| \leq |\alpha_1| \). In order to prove \( (3.3) \) we write
\[
\| \langle z \rangle^s (R_{\alpha_1} U_1) (R_{\alpha_2} U_2) \|_{L^2} = \| \langle z - \alpha_2 \rangle^s (R_{\alpha_1 - \alpha_2} U_1) U_2 \|_{L^2} \\
\leq C \langle \alpha_2 \rangle^s \| (R_{\alpha_1 - \alpha_2} U_1) U_2 \|_{L^2} + C \| (R_{\alpha_1 - \alpha_2} U_1) \langle z \rangle^s U_2 \|_{L^2}.
\]
Observe that \( \langle z \rangle^s |U_2(z)| \leq C_0 e^{-c_1|z|^2} \) for all \( c_1 < c_0 \) and therefore by \( (3.5) \) we obtain
\[
\| \langle z \rangle^s (R_{\alpha_1} U_1) (R_{\alpha_2} U_2) \|_{L^2} \leq C \langle \alpha_2 \rangle^s e^{-\frac{c_2}{2} |\alpha_1 - \alpha_2|^2},
\]
which was to prove.

(iii) Similarly, for all \( c_1 < c_0 \), we have
\[
\| e^{\kappa |z|} (R_{\alpha_1} U_1) (R_{\alpha_2} U_2) \|_{L^2} = \| e^{\kappa |z - \alpha_2|} (R_{\alpha_1 - \alpha_2} U_1) U_2 \|_{L^2} \\
\leq e^{\kappa |\alpha_2|} \| (R_{\alpha_1 - \alpha_2} U_1) (e^{\kappa |z|} U_2) \|_{L^2} \\
\leq C e^{\kappa |\alpha_2|} e^{-\frac{\kappa}{2} |\alpha_1 - \alpha_2|^2},
\]
therefore the result.

(iv) By hypothesis \( (3.1) \)
\[
|e^{-L|z|} R_{\alpha_1} U_1| \leq C e^{-L|z - c_0| |z + \alpha_1|^2}, \tag{3.6}
\]
Then observe that
\[
L|z| + c_0 |z + \alpha_1|^2 \geq \left\{ \begin{array}{ll} L |\alpha_1| / 2 & \text{if } |z| \geq |\alpha_1| / 2 \\ c_0 |\alpha_1|^2 / 4 & \text{if } |z| \leq |\alpha_1| / 2, \end{array} \right.
\]
which implies the result by \( (3.6) \). \( \square \)

3.2. Stability of traveling waves under time derivation. The next lemma shows that the Gaussian decay of the traveling waves is stable under time derivation.

**Lemma 3.2.** Let \( c_0 \leq 1/2 \). Assume that \( U \in \mathcal{E} \) satisfies a Gaussian bound \( |U(z)| \leq C_0 e^{-c_0 |z|^2} \) and assume that \( T \in C(\mathbb{R}; \mathcal{E}) \) takes the form
\[
T(t, z) = e^{-it\lambda} (R_{\alpha t} U)(z), \quad \forall (t, z) \in \mathbb{R} \times \mathbb{C}.
\]
Then there exists \( \widetilde{U} \in \mathcal{E} \) such that for all \( c_1 < \frac{c_0}{1 + 2c_0} \), there exists \( C_1 > 0 \)
\[
|\widetilde{U}(z)| \leq C_1 e^{-c_1 |z|^2}
\]
and
\[
(\partial_t T)(t, z) = e^{-it\lambda} (R_{\alpha t} \widetilde{U})(z), \quad \forall (t, z) \in \mathbb{R} \times \mathbb{C}.
\]

**Proof.** We set \( U(z) = f(z) e^{-\frac{|z|^2}{2}} \), thus
\[
T(t, z) = e^{-i\lambda t} U(z + \alpha t) e^{\frac{1}{2} \langle \overline{\alpha} \alpha - z \overline{z} \rangle t} = e^{-i\lambda t} f(z + \alpha t) e^{-\frac{|z|^2}{2} - \frac{|\alpha|^2}{2} - \frac{|\alpha z|^2}{2}}.
\]
A direct computation gives
\[
(\partial_t T)(t, z) = e^{-i\lambda t} \widetilde{U}(z + \alpha t) e^{\frac{1}{2} \langle \overline{\alpha} \alpha - z \overline{z} \rangle t} \text{ where}
\]
\[
\widetilde{U}(z) = \left( -i \lambda f(z) + \alpha \partial_z f(z) - \overline{\alpha} z f(z) \right) e^{-\frac{|z|^2}{2}}.
\]
Let \( c_1 < \frac{c_0}{1 + 2c_0} \). It remains to check that \( \widetilde{U} \) satisfies a Gaussian bound with constant \( c_1 \). Since \( c_1 < c_0 \), it is clear that \( |z \widetilde{U}(z)| \leq C_0 e^{-c_1 |z|^2} \), and let us prove that \( |\partial_z f(z)| e^{-\frac{|z|^2}{2}} \leq C_0 e^{-c_1 |z|^2} \).
Observe that
\[
(\partial_z f)(z) e^{-\frac{|z|^2}{2}} = (\partial_z - \frac{z}{2}) U(z) + z \overline{U}(z),
\]
hence it is enough to show that $|\left(\partial_z - \frac{\pi}{2}\right) U(z)| e^{-\frac{|z|^2}{2}} \leq C e^{-c_1 |z|^2}$. Writing

$$U(z) = \Pi(U)(z) = \frac{e^{-\frac{|z|^2}{2}}}{\pi} \int_{\mathbb{C}} e^{wz - \frac{|w|^2}{2}} U(w) \, dL(w),$$

we obtain

$$\left(\partial_z - \frac{\pi}{2}\right) U(z) = \frac{e^{-\frac{|z|^2}{2}}}{\pi} \int_{\mathbb{C}} (w - \pi) e^{wz - \frac{|w|^2}{2}} U(w) \, dL(w).$$

This in turn implies

$$\left|\left(\partial_z - \frac{\pi}{2}\right) U(z)\right| \leq C \|e^{c_0 |z|^2} U\|_{L^\infty} \int_{\mathbb{C}} |z - w| e^{-\frac{|z-w|^2}{2}} e^{-c_0 |w|^2} \, dL(w). \quad (3.7)$$

Now let us show that there exists $\epsilon > 0$ such that for all $w, z \in \mathbb{C}$

$$\frac{1}{2} |z - w|^2 + c_0 |w|^2 \geq \epsilon |z - w|^2 + c_1 |z|^2. \quad (3.8)$$

We can assume that $w, z \in \mathbb{R}$ and by homogeneity we can reduce to the case $w = 1$. Define the polynomial

$$P(z) = \frac{1}{2} (z - 1)^2 + c_0 - \epsilon (z - 1)^2 - c_1 z^2 = \left(\frac{1}{2} - c_1 - \epsilon\right) z^2 - (1 - 2\epsilon) z + \left(\frac{1}{2} + c_0 - \epsilon\right).$$

The discriminant of $P$ is $\Delta = 2(c_1 - c_0)(1 - 2\epsilon) + 4c_0 c_1$ which is negative for $\epsilon > 0$ small enough, since $c_1 < \frac{c_0}{1 + 2c_0}$. As a consequence, $P \geq 0$ for $\epsilon > 0$ small enough, which implies (3.8). From (3.7) and (3.8) we deduce that

$$\left|\left(\partial_z - \frac{\pi}{2}\right) U(z)\right| \leq C \|e^{c_0 |z|^2} U\|_{L^\infty} e^{-c_1 |z|^2} \int_{\mathbb{C}} |z - w| e^{-\epsilon |z-w|^2} \, dL(w) \leq C e^{-c_1 |z|^2},$$

which concludes the proof. \hfill \Box

4. PROOF OF THEOREM 1.3

We recall the system

$$\begin{cases}
 i\partial_t u = \Pi(|u|^2 u), & (t, z) \in \mathbb{R} \times \mathbb{C}, \\
 i\partial_t v = -\Pi(|u|^2 v), \\
 u(0, \cdot) = u_0 \in \mathcal{E}, \ v(0, \cdot) = v_0 \in \mathcal{E}.
\end{cases} \quad (4.1)$$

Assume that for each $1 \leq j \leq n$, $(U_j, V_j) \in \mathcal{E} \times \mathcal{E}$ is a traveling wave solution to (4.1) in the sense (1.7), and that there exist $c_0, C > 0$ such that

$$|U_j(z)| + |V_j(z)| \leq C e^{-c_0 |z|^2}. \quad (4.2)$$

One can have $\alpha_j = 0$ for at most one $1 \leq j \leq n$, and in this case, (4.2) is automatically satisfied for any $c_0 < 1/2$, by Theorem A.1. We denote by $K_j = \|U_j\|_{L^2} = \|V_j\|_{L^2}$ (notice that one always has $\|U_j\|_{L^2} = \|V_j\|_{L^2}$ for a traveling wave, see [20, Proposition 1.8]), and we set

$$X_j(t, z) = e^{-i\lambda_j t} U_j(z + \alpha_j t) e^{\frac{i}{2} (\overline{\alpha_j} - \overline{\alpha_j} t) z}, \quad Y_j(t, z) = e^{-i\mu_j t} V_j(z + \alpha_j t) e^{\frac{i}{2} (\overline{\alpha_j} - \overline{\alpha_j} t) z}, \quad (4.3)$$

for $j = 1, \ldots, n$. Then

$$\begin{cases}
 i\partial_t X_j = \Pi(|X_j|^2 X_j), \\
 i\partial_t Y_j = -\Pi(|X_j|^2 Y_j), \\
 X_j(0, \cdot) = X_0, \ Y_j(0, \cdot) = Y_0.
\end{cases} \quad (4.4)$$

One can derive from (4.2) that

$$\|X_j\|_{L^\infty} \leq C e^{-c_0 |\alpha_j|^2 t}, \quad (4.5)$$

for $j = 1, \ldots, n$.
and
\[ u = \sum_{j=1}^{n} X_j + r_1 := X + r_1, \quad v = \sum_{j=1}^{n} Y_j + r_2 := Y + r_2, \] (4.4)
a solution of (4.1).

For \( M > 0 \), let \((u^M, v^M) \in C^\infty(\mathbb{R}, \mathcal{E} \times \mathcal{E})\) be the solution to (4.1) such that \((r_1^M(M), r_2^M(M)) = (0,0)\). By Proposition 1.2 we also have \((u^M, v^M) \in C^\infty(\mathbb{R}, \mathcal{X}_E^\kappa \times \mathcal{X}_E^\kappa)\) for all \( \kappa \geq 0 \), and hence \((r_1^M, r_2^M) \in C^\infty(\mathbb{R}, \mathcal{X}_E^\kappa \times \mathcal{X}_E^\kappa)\).

4.1. The nonlinear analysis. The next result shows that the remainder term has an explicit Gaussian decay, with uniform constants with respect to \( M > 0 \).

**Lemma 4.1.** Let \( \kappa \geq 0 \) and \( c_1 < \frac{\kappa}{2} \). There exists a constant \( C > 0 \) such that for all \( M > 0 \) and all \( 0 < t \leq M \)
\[ \| e^{\kappa|z|} r_1^M(t) \|_{L^2} + \| e^{\kappa|z|} r_2^M(t) \|_{L^2} \leq C e^{-c_1 \alpha_2^2 t^2}. \]

**Proof.** Fix \( M > 0 \). In the sequel, we write \( r_1 = r_1^M \), \( r_2 = r_2^M \) and we denote by
\[ \eta(t) := \| e^{\kappa|z|} r_1(t) \|^2_{L^2} + \| e^{\kappa|z|} r_2(t) \|^2_{L^2}. \]
We stress that all the constants \( C, c_0, c_1, c_2 > 0 \) below will be independent of \( M > 0 \).

**Step 1** : A first \( L^2 \)-bound. To begin with, let us prove that
\[ \| r_1^M(t) \|_{L^2} \leq 2 \sum_{j=1}^{n} K_j \quad \| r_2^M(t) \|_{L^2} \leq 2 \sum_{j=1}^{n} K_j. \] (4.5)
By the conservation of the \( L^2 \) norm for \((u^M, v^M)\) and the triangle inequality, for all \( t \in \mathbb{R} \)
\[ \| r_1^M(t) \|_{L^2} \leq \| u^M(t) \|_{L^2} + \sum_{j=1}^{n} \| X_j(t) \|_{L^2} \]
\[ \leq \| u^M(M) \|_{L^2} + \sum_{j=1}^{n} \| X_j(t) \|_{L^2} \]
\[ \leq \sum_{j=1}^{n} (\| X_j(M) \|_{L^2} + \| X_j(t) \|_{L^2}) \]
\[ \leq 2 \sum_{j=1}^{n} K_j, \]
uniformly with respect to \( t \in \mathbb{R} \) and \( M > 0 \).

**Step 2** : A differential inequality. In this paragraph we show that, for all \( c_1 < \frac{\kappa}{2} \), there exists a constant \( C > 0 \) independent of \( M > 0 \) such that for all \( 0 < t \leq M \)
\[ \left| \frac{d}{dt} \eta(t) \right| \leq C \eta(t) + C e^{-2c_1 \alpha_2^2 t^2}. \] (4.6)
By (4.4), the relation \( i \partial_t u = \Pi(|u|^2 u) \) reads
\[ i \partial_t r_1 = \Pi(|Y + r_2|^2 (X + r_1)) - i \partial_t X := \sum_{j=0}^{3} q_j, \] (4.7)
where
\[
q_0 := \Pi(|Y|^2X) - i\partial_t X
\]
\[
q_1 := \Pi(|Y|^2r_1) + \Pi(\overline{Y}Xr_2) + \Pi(YX\overline{r_2})
\]
\[
q_2 := \Pi(Xr_2^2) + \Pi(\overline{Y}r_1r_2) + \Pi(Yr_1\overline{r_2})
\]
\[
q_3 := \Pi(|r_2|^2r_1).
\]

Next we compute
\[
\left| \frac{d}{dt} \int_{\mathbb{C}} e^{2\kappa|z|^2} |r_1|^2 dL \right| = \left| 2\Re \int_{\mathbb{C}} e^{2\kappa|z|^2} \overline{r_1}\partial_t r_1 dL \right|
\]
\[
= \left| 2\Im \int_{\mathbb{C}} e^{2\kappa|z|^2} \overline{\partial_t r_1} \sum_{j=0}^3 q_j dL \right|
\]
\[
\leq C\|e^{\kappa|z|^2}r_1\|_{L^2} \sum_{j=0}^3 \|e^{\kappa|z|}q_j\|_{L^2},
\] (4.9)

and we now have to estimate each term \(\|e^{\kappa|z|}q_j\|_{L^2}\).

- **Control of \(\|e^{\kappa|z|}q_0\|_{L^2}\).** For all \(1 \leq j \leq n\), \(i\partial_t X_j = \Pi(|Y_j|^2X_j)\), thus
\[
q_0 = \sum_{1 \leq j,k,\ell \leq n} \Pi(Y_j\overline{Y}_k X_\ell).
\]

Assume for instance that \(j \neq k\), so that \(\alpha_j \neq \alpha_k\). Then by (2.2)
\[
\|e^{\kappa|z|}\Pi(Y_j\overline{Y}_k X_\ell)\|_{L^2} \leq C\|e^{\kappa|z|}Y_jY_kX_\ell\|_{L^2}
\]
\[
= C\|e^{\kappa|z|}(R_{\alpha_{j\ell}}V_j)(R_{\alpha_{k\ell}}V_k)(R_{\alpha_{j\ell}}U_\ell)\|_{L^2}
\]
\[
= C\|e^{\kappa|z|-(\alpha_{j\ell}+\alpha_{k\ell})}|(R_{\alpha_{j\ell}}V_j)(R_{\alpha_{k\ell}}V_k)U_\ell|\|_{L^2}
\]
\[
\leq C\|e^{\alpha_{j\ell}t}|(R_{\alpha_{j\ell}}V_j)(R_{\alpha_{k\ell}}V_k)\|_{L^\infty}\|e^{\kappa|z|}U_\ell\|_{L^2}.
\]

Next by (3.2), for all \(c_1 < \frac{Q}{2}\) we have
\[
\|e^{\kappa|z|}\Pi(Y_j\overline{Y}_k X_\ell)\|_{L^2} \leq C\|e^{\kappa|z|}U_\ell\|_{L^2}^2
\]
\[
\leq C\|e^{-c_1|\alpha_j|\alpha_k|^2t}\|_{L^2}^2.
\]

The other terms are treated similarly. As a consequence, for all \(c_1 < \frac{Q}{2}\)
\[
\|e^{\kappa|z|}q_0\|_{L^2} \leq C\|e^{-c_1|\alpha_j|\alpha_k|^2t}\|_{L^2}^2.
\] (4.10)

- **Control of \(\|e^{\kappa|z|}q_1\|_{L^2}\).** From (2.2) we have
\[
\|e^{\kappa|z|}q_1\|_{L^2} \leq C\|e^{\kappa|z|}|Y|^2r_1\|_{L^2} + C\|e^{\kappa|z|}\overline{Y}Xr_2\|_{L^2}
\]
\[
\leq C\|Y\|_{L^\infty}\|e^{\kappa|z|}r_1\|_{L^2} + C\|X\|_{L^\infty}\|Y\|_{L^\infty}\|e^{\kappa|z|}r_2\|_{L^2}
\]
\[
\leq C\left(\|e^{\kappa|z|}r_1\|_{L^2} + \|e^{\kappa|z|}r_2\|_{L^2}\right)
\]
\[
\leq C\eta^{1/2}.
\]

- **Control of \(\|e^{\kappa|z|}q_2\|_{L^2}\).** The estimation of this contribution is in the same spirit as the previous one. Firstly,
\[
\|e^{\kappa|z|}q_2\|_{L^2} \leq C\left(\|Y\|_{L^\infty}\|r_1\|_{L^\infty} + \|X\|_{L^\infty}\|r_2\|_{L^\infty}\right)\|e^{\kappa|z|}r_2\|_{L^2}.
\] (4.11)
Then by the Carlen estimate (1.28) and by (4.7),
\[ \|r_1\|_{L^\infty} \leq C\|r_1\|_{L^2} \leq C, \]
and \( \|r_2\|_{L^2} \leq C \) as well. Thus from (4.11) we deduce
\[ \|e^{\kappa |z|}q_2\|_{L^2} \leq C\eta^{1/2}. \]

- Control of \( \|e^{\kappa |z|}q_3\|_{L^2} \). Similarly,
\[ \|e^{\kappa |z|}q_3\|_{L^2} \leq C\|r_2\|_{L^\infty}^2 \|e^{\kappa |z|}r_1\|_{L^2} \leq C\eta^{1/2}. \]

Putting all the previous estimates together, from (4.9) we obtain
\[ \left| \frac{d}{dt}\|e^{\kappa |z|}r_1(t)\|_{L^2}^2 \right| \leq C\eta^{1/2}(t)(\eta^{1/2}(t) + Ce^{-c_1\alpha_2^2t^2}) \leq C\eta(t) + Ce^{-2c_1\alpha_2^2t^2}. \]

The estimate for \( \left| \frac{d}{dt}\|e^{\kappa |z|}r_2(t)\|_{L^2}^2 \right| \) is similar, hence we get (4.6).

Step 3 : Backward Grönwall. Now, by integrating (4.6) on \([t, M]\) we get that for all \( 0 < t < M \)
\[ \eta(t) \leq C \int_t^{+\infty} e^{-2c_1\alpha_2^2\sigma^2} d\sigma + C \int_t^M \eta(\sigma)d\sigma \leq Ce^{-2c_1\alpha_2^2t^2} + C \int_t^M \eta(\sigma)d\sigma. \]
By the backward Grönwall inequality (Lemma 3.1) this implies that for all \( 0 < t < M \)
\[ \eta(t) \leq Ce^{-2c_1\alpha_2^2t^2} + C \int_t^M e^{-2c_1\alpha_2^2\sigma^2} \exp\left( \int_t^\sigma Cd\tau \right)d\sigma \leq Ce^{-2c_1\alpha_2^2t^2} + C \int_t^M e^{-2c_1\alpha_2^2\sigma^2 + C\sigma} d\sigma \leq Ce^{-2c_2\alpha_2^2t^2}, \]
for any \( c_2 < c_1 \), and where the previous constant \( C > 0 \) does not depend on \( M > 0 \), which was the claim. \( \square \)

We now prove that for all \( T > 0 \), the sequence \((r_1^M, r_2^M)_{M \geq 0}\) is a Cauchy sequence in the space \( \mathcal{C}([0, T]; \mathcal{X}_E^\kappa \times \mathcal{X}_E^\kappa) \).

**Lemma 4.2.** Let \( \kappa \geq 0 \). For all \( c_1 < \frac{c_0}{2} \), there exists a constant \( C > 0 \) such that for all \( 0 < N < M \) and all \( 0 < t \leq N \)
\[ \|e^{\kappa |z|}(r_1^M - r_1^N)(t)\|_{L^2} + \|e^{\kappa |z|}(r_2^M - r_2^N)(t)\|_{L^2} \leq Ce^{-c_1\alpha_2^2N^2}. \]

**Proof.** By (4.1),
\[ i\partial_t(r_1^M - r_1^N) = \sum_{j=1}^3 (q_j^M - q_j^N), \]
and we observe that the term \( q_0 \) does not depend on \( N \) or \( M \), thus \( q_0^M = q_0^N \). We compute
\[ \left| \frac{d}{dt} \int_C e^{2\kappa |z|}|r_1^M - r_1^N|^2 dL \right| = \left| 2\Re \int_C e^{2\kappa |z|}(r_1^M - r_1^N)\partial_t(r_1^M - r_1^N)dL \right| \leq C\|e^{\kappa |z|}(r_1^M - r_1^N)\|_{L^2}^2 \sum_{j=1}^3 \|e^{\kappa |z|}(q_j^M - q_j^N)\|_{L^2}^2. \]

Denote by
\[ \theta(t) = \|e^{\kappa |z|}(r_1^M - r_1^N)(t)\|_{L^2}^2 + \|e^{\kappa |z|}(r_2^M - r_2^N)(t)\|_{L^2}^2, \]
then we can prove that $\theta$ satisfies the inequality

$$\left| \frac{d}{dt} \theta(t) \right| \leq C \theta(t), \quad (4.12)$$

where $C > 0$ does not depend on $N, M > 0$. To do this, we can proceed as in the proof of Lemma 4.1: the estimates are the same, simply using

$$\|r_1^M\|_{L^\infty} + \|r_1^N\|_{L^\infty} + \|r_2^M\|_{L^\infty} + \|r_2^N\|_{L^\infty} \leq C.$$ 

Next by Lemma 4.1, we have, for any $c_1 < \frac{C}{2}$

$$\theta(N) = \|e^{\alpha|z|}r_1^M(N)\|_{L^2}^2 + \|e^{\alpha|z|}r_2^M(N)\|_{L^2}^2 \leq Ce^{-\alpha z^2 N^2}.$$ 

By integration of (4.12) on $[t, N]$ we deduce that for all $0 \leq t \leq N$

$$\theta(t) \leq \theta(N) + C \int_t^N \theta(\sigma)d\sigma \leq Ce^{-\alpha z^2 N^2} + C \int_t^N \theta(\sigma)d\sigma.$$ 

Therefore, by Lemma 7.1 for all $0 \leq t \leq N$

$$\theta(t) \leq Ce^{-\alpha z^2 N^2} + Ce^{-\alpha z^2 N^2} \int_t^N e^{C\sigma}d\sigma \leq Ce^{-\alpha z^2 N^2},$$

for any $c_2 < c_1$, which was the claim. \hfill \Box

4.2. Conclusion of the proof of Theorem 1.3. For $\kappa > 0$, we denote by

$$X^\kappa = \{ u \in \mathcal{S}'(\mathbb{C}), \ e^{\alpha |z|}u \in L^2(\mathbb{C}) \}.$$ 

By Lemma 4.2, for all $T > 0$, the sequence $r_1^M, r_2^M)_{M \geq 0}$ is a Cauchy sequence in the space $C([0, T]; X^\kappa \times X^\kappa)$, hence it converges in $C([0, T]; X^\kappa \times X^\kappa)$. By Lemma 4.1 its limit satisfies the bound

$$\|e^{\alpha|z|}r_1(t)\|_{L^2} + \|e^{\alpha|z|}r_2(t)\|_{L^2} \leq Ce^{-\alpha z^2 t^2},$$

for any $c_1 < \frac{C}{2}$ and for all $t \geq 0$.

Now let us prove that for all $t \in [0, T]$ we have $(r_1(t), r_2(t)) \in \mathcal{E} \times \mathcal{E}$, so that we will deduce that $(r_1, r_2) \in C([0, T]; X^\kappa \times X^\kappa)$. Fix $t \in [0, T]$. In the next lines, we do not mention the dependence on $t$. For $j = 1, 2$, write $r_j^M(z) = f_j^M(z)e^{-\alpha |z|^2/2}$, where $f_j^M$ is entire. By the Carlen inequality (4.24), for all $z \in \mathbb{C}$ and $M \geq 1$

$$|f_j^M(z)e^{-\alpha |z|^2/2}| \leq \|r_j^M\|_{L^\infty} \leq C\|r_j^M\|_{L^2} \leq C.$$ 

Therefore, for all $K > 0$ and $M \geq 1$, we get

$$|f_j^M(z)| \leq C_K, \quad |z| \leq K.$$ 

By the Montel theorem, there exists an entire function $f_j$ such that, when $M \to +\infty$, up to a subsequence $f_j^M \to f_j$, uniformly on any compact of $\mathbb{C}$, and by uniqueness of the limit we have $r_j(z) = f_j^M(z)e^{-\alpha |z|^2/2} \in \mathcal{E}$.

To complete the proof of Theorem 1.3 it remains to show that (1.13) holds for all $k \in \mathbb{N}$. We proceed by induction on $k \geq 0$. The case $k = 0$ has just been proven. Let $k \geq 0$ such that

$$\|e^{\alpha|z|}(\partial_t^j r_1)(t)\|_{L^2} + \|e^{\alpha|z|}(\partial_t^j r_2)(t)\|_{L^2} \leq Ce^{-\alpha z^2 t^2}, \quad (4.13)$$

holds true for all $0 \leq j \leq k$, and where the constant $c_1 < 1/4$ can be chosen arbitrarily close to $1/4$. Then by (4.7),

$$i\partial_t^{k+1}r_1 = \sum_{j=0}^{3} \partial_t^j q_j.$$
Using the Leibniz rule, we observe that $\partial_t^k q_j$ is a trilinear term in $(\partial_t^j r_k)_{0 \leq j \leq k}$, $(\partial_t^j X_k)_{0 \leq j \leq k}$, and $(\partial_t^j Y_\ell)_{0 \leq j \leq k}$. We write
\[\|e^{\kappa|z|}(\partial_t^{k+1} r_1)(t)\|_{L^2} \leq \|e^{\kappa|z|}(\partial_t^k q_0)(t)\|_{L^2} + \sum_{j=1}^3 \|e^{\kappa|z|}(\partial_t^k q_j)(t)\|_{L^2}.\]
To bound the first term, we can use Lemma 3.2 repeatedly with $c_0 < 1/2$ arbitrarily close to 1/2, hence for all $c_1 < 1/2$ we get $\|e^{\kappa|z|}(\partial_t^k q_0)(t)\|_{L^2} \leq C e^{-c_1\alpha t^2}$. To bound the other terms, we use (1.13) and Lemma 3.2 which implies $\|e^{\kappa|z|}(\partial_t^{k+1} r_1)(t)\|_{L^2} \leq C e^{-c_1\alpha t^2}$. With the same arguments we obtain $\|e^{\kappa|z|}(\partial_t^k r_2)(t)\|_{L^2} \leq C e^{-c_1\alpha t^2}$.

By the same manner, when one of the traveling waves satisfies the bound (1.2) for some $c_0 < 1/2$, one can establish (1.15). In this latter case, the constant $\tilde{c}_k > 0$ giving the rate of the Gaussian decay may depend on $k \in \mathbb{N}$.

The relations (1.17) are obtained by plugging the expressions (1.12) in the conservation laws and using Lemma 3.1 together with the values given in [26, equation (1.15)].

4.3. Proof of the bound (1.19). By the change of unknown $(\tilde{u}, \tilde{v}) = e^{-i\delta t H}(u, v)$, we have $(\tilde{r}_1, \tilde{r}_2) = e^{-i\delta t H}(r_1, r_2)$. For $s \geq 0$,
\[\|\langle z \rangle^s (\partial_t^k \tilde{r}_1)\|_{L^2} = \|\langle z \rangle^s \partial_t^k (e^{-i\delta t H} r_1)\|_{L^2},\]
and by the Leibniz rule, we are reduced to bound terms of the form $\|\langle z \rangle^s H^j e^{-i\delta t H} (\partial_t^j r_1)\|_{L^2}$ for $0 \leq j, \ell \leq k$. By (1.14),
\[\|\langle z \rangle^s H^j (\partial_t^j r_1)\|_{L^2} \leq C \|H^j e^{-i\delta t H} (\partial_t^j r_1)\|_{H^s} \leq C \|\partial_t^j r_1\|_{H^{s+2j}} \leq C \|\langle z \rangle^{s+2j} \partial_t^j r_1\|_{L^2} \leq C e^{-\tilde{c}_k t^2},\]
where in the last line we used (1.15).

5. Proof of Theorem 1.5

Consider $(\tilde{u}, \tilde{v}) = (X + \tilde{r}_1, Y + \tilde{r}_2) \in \mathcal{C}(\mathbb{R}, X^s \times X^s)$ a multi-soliton as given in Theorem 1.5. We stress that for all $j \neq \ell$, we have $\alpha_j \neq \alpha_\ell$ and that for all $1 \leq j \leq n$, $\alpha_j \neq 0$.

Similarly to (4.3), we assume that
\[X(t, z) = \sum_{j=1}^n e^{-i\lambda_j t} U_j(z + \alpha_j t) e^{\frac{1}{2}(\overline{\alpha_j} z - z \overline{\alpha_j})t},\]
\[Y(t, z) = \sum_{j=1}^n e^{-i\mu_j t} V_j(z + \alpha_j t) e^{\frac{1}{2}(\overline{\alpha_j} z - z \overline{\alpha_j})t},\]
and we set $K_j := \|U_j\|_{L^2} = \|V_j\|_{L^2}$.

Step 1: Exponential decay of the error. In this paragraph only, we write $r_1 = \tilde{r}_1$ and $r_2 = \tilde{r}_2$. Assume that, when $t \to 0$,
\[\|e^{\kappa|z|} r_1(t)\|_{L^2} + \|e^{\kappa|z|} r_2(t)\|_{L^2} \to 0.\]
Let us show that for all $t \geq 0$
\[\|r_1\|_{L^2(C)}^2 + \|r_2\|_{L^2(C)}^2 \leq C_\alpha e^{-\kappa \alpha_{\min} t}.\]
Starting from the relation

\[ i\partial_t r_1 = \sum_{j=0}^{3} q_j, \]

similarly to (4.9) we compute

\[
\left| \frac{d}{dt} \int_C |r_1|^2 dL \right| = \left| 2\text{Im} \int_C r_1^3 \left( \sum_{j=0}^{3} q_j \right) dL \right|
\leq 2\|r_1\|_{L^2} \sum_{j=0}^{2} \|q_j\|_{L^2},
\]

and we observe that the contribution of \( q_3 \) cancels in the previous line. We now control each term \( \|q_j\|_{L^2} \), for \( 0 \leq j \leq 2 \).

- Control of \( \|q_0\|_{L^2} \). We have already controlled this term, namely by (4.10) (with \( \kappa = 0 \))

\[ \|q_0\|_{L^2} \leq Ce^{-c_1^2t^2}. \]

- Control of \( \|q_1\|_{L^2} \). We directly obtain

\[
\|q_1\|_{L^2} \leq C\|r_1 Y \|_{L^2} + C\|r_2 XY\|_{L^2}
\leq C(\|e^{\kappa|z|}r_1\|_{L^2} + \|e^{\kappa|z|}r_2\|_{L^2})\|e^{-\kappa|z|}Y\|_{L^\infty}(\|Y\|_{L^\infty} + \|X\|_{L^\infty})
\leq C(\|e^{\kappa|z|}r_1\|_{L^2} + \|e^{\kappa|z|}r_2\|_{L^2})\|e^{-\kappa|z|}Y\|_{L^\infty}. \tag{5.3}
\]

We now use the expression of \( Y \) and (3.4), and we rely on the crucial fact that \( \alpha_j \neq 0 \) for all \( 1 \leq j \leq n \) : denote by \( \alpha_{\min} = \min_{1 \leq j \leq n} |\alpha_j| \), then there exists a universal constant \( c_1 > 0 \) such that

\[ \|e^{-\kappa|z|}Y\|_{L^\infty} \leq C(e^{-c_1\alpha_{\min}t^2/2} + e^{-c_1\alpha_{\min}^2t^2/4}) \leq C e^{-c_1\alpha_{\min}t^2/2}. \]

Therefore, from (5.3) and (5.1), we deduce

\[ \|q_1\|_{L^2} \leq C e^{-c_1\alpha_{\min}t^2/2}(\|e^{\kappa|z|}r_1\|_{L^2} + \|e^{\kappa|z|}r_2\|_{L^2}) \leq C e^{-c_1\alpha_{\min}t^2/2}. \]

- Control of \( \|q_2\|_{L^2} \). Similarly we get

\[
\|q_2\|_{L^2} \leq C(\|e^{\kappa|z|}r_1\|_{L^2} + \|e^{\kappa|z|}r_2\|_{L^2})(\|e^{-\kappa|z|}X\|_{L^\infty} + \|e^{-\kappa|z|}Y\|_{L^\infty})(\|r_1\|_{L^\infty} + \|r_2\|_{L^\infty})
\leq C(\|e^{\kappa|z|}r_1\|_{L^2} + \|e^{\kappa|z|}r_2\|_{L^2})(\|e^{-\kappa|z|}X\|_{L^\infty} + \|e^{-\kappa|z|}Y\|_{L^\infty}) \leq C e^{-c_1\alpha_{\min}t^2/2}.
\]

Putting the previous estimates together we get

\[
\left| \frac{d}{dt} \left( \|r_1\|_{L^2(\mathbb{C})}^2 + \|r_2\|_{L^2(\mathbb{C})}^2 \right) \right| \leq C(\|r_1\|_{L^2(\mathbb{C})}^2 + \|r_2\|_{L^2(\mathbb{C})}^2)^{1/2} e^{-c_1\alpha_{\min}t^2/2}
\]

and by integration on \([t, +\infty)\), using (5.1), we deduce (5.2).

Step 2: An explicit \( L^\infty \) bound. Consider two multi-solutions

\[ (u, v) = (X + r_1, Y + r_2), \quad (\bar{u}, \bar{v}) = (X + \bar{r}_1, Y + \bar{r}_2), \]
where the remainder terms satisfy \((5.1)\). Then by \((4.7)\), the errors satisfy the equations
\[
i \partial_t r_1 = \sum_{j=0}^3 q_j, \quad i \partial_t \tilde{r}_1 = \sum_{j=0}^3 \tilde{q}_j.
\]

Denote by \(\rho_j = r_j - \tilde{r}_j\) and set
\[
\theta(t) = \|\rho_1(t)\|_{L^2(\mathbb{C})}^2 + \|\rho_2(t)\|_{L^2(\mathbb{C})}^2.
\]
Observe that, thanks to \((5.2)\), we already have the bound
\[
\theta(t) \leq C e^{-\kappa \alpha_{\min} t}.
\]
Denote by
\[
G(t) = \|X(t)\|_{L^\infty}^2 + \|Y(t)\|_{L^\infty}^2 + \|r_1(t)\|_{L^2}^2 + \|r_2(t)\|_{L^2}^2 + \|\tilde{r}_1(t)\|_{L^2}^2 + \|\tilde{r}_2(t)\|_{L^2}^2,
\]
and set \(K_{\max} = \max_{1 \leq j \leq n} K_j\). We now show that there exists a universal constant \(c_0 > 0\) and \(t_0 > 0\)
such that for all \(t \geq t_0\),
\[
G(t) \leq c_0 K_{\max}^2.
\]  \((5.5)\)

Since \(\alpha_j \neq \alpha_{\ell}\), one has \(\|X(t)\|_{L^\infty} \rightarrow \max_{1 \leq j \leq n} \|U_j\|_{L^\infty}\) when \(t \rightarrow +\infty\). Besides, by \((1.27)\), \(\|U_j\|_{L^\infty} \leq C \|U_j\|_{L^2} = CK_j\). Therefore, for \(t\) large enough, \(\|X(t)\|_{L^\infty} \leq 2CK_{\max}\). We proceed similarly for \(Y\)
and we can use \((1.27)\) to conclude that \((5.5)\) holds true.

Step 3: A differential inequality. Let us show that there exists an universal constant \(C_0 > 0\)
such that for all \(t \geq t_0\)
\[
\left| \frac{d}{dt} \theta(t) \right| \leq C_0 K_{\max}^2 \theta(t).
\]
As in \((4.9)\) we compute
\[
\left| \frac{d}{dt} \|\rho_1\|_{L^2}^2 \right| \leq C \|\rho_1\|_{L^2}^2 \sum_{j=1}^3 \|q_j - \tilde{q}_j\|_{L^2},
\]
where we observe that \(q_0 = \tilde{q}_0\). Using the expressions \((4.8)\) we bound the previous terms. In the sequel, we assume that \(t \geq t_0\).

- Control of \(\|q_1 - \tilde{q}_1\|_{L^2}\). Using \((5.5)\) we directly obtain
  \[
  \|q_1 - \tilde{q}_1\|_{L^2} \leq C \|\rho_1 Y^2\|_{L^2} + C \|\rho_2 XY\|_{L^2} \\
  \leq C (\|\rho_1\|_{L^2} + \|\rho_2\|_{L^2}) (\|X\|_{L^\infty}^2 + \|Y\|_{L^\infty}^2) \\
  \leq C (\|\rho_1\|_{L^2} + \|\rho_2\|_{L^2}) K_{\max}^2.
  \]

- Control of \(\|q_2 - \tilde{q}_2\|_{L^2}\). Similarly we get
  \[
  \|q_2 - \tilde{q}_2\|_{L^2} \leq C (\|\rho_1\|_{L^2} + \|\rho_2\|_{L^2}) (\|X\|_{L^\infty} + \|Y\|_{L^\infty}) (\|r_1\|_{L^\infty} + \|r_2\|_{L^\infty} + \|\tilde{r}_1\|_{L^\infty} + \|\tilde{r}_2\|_{L^\infty}) \\
  \leq C (\|\rho_1\|_{L^2} + \|\rho_2\|_{L^2}) K_{\max}^2.
  \]

- Control of \(\|q_3 - \tilde{q}_3\|_{L^2}\). By the same manner, we have
  \[
  \|q_3 - \tilde{q}_3\|_{L^2} \leq C (\|\rho_1\|_{L^2} + \|\rho_2\|_{L^2}) (\|r_1\|_{L^\infty} + \|r_2\|_{L^\infty} + \|\tilde{r}_1\|_{L^\infty} + \|\tilde{r}_2\|_{L^\infty})^2 \\
  \leq C (\|\rho_1\|_{L^2} + \|\rho_2\|_{L^2}) K_{\max}^2.
  \]
Therefore, by \(5.7\) and the previous estimates
\[
\left| \frac{d}{dt} \| \rho_1 \|_{L^2}^2 \right| \leq C(\| \rho_1 \|_{L^2}^2 + \| \rho_2 \|_{L^2}^2) K_{\max}^2.
\]
The same bound holds for \(\left| \frac{d}{dt} \| \rho_2 \|_{L^2}^2 \right|\), and we deduce \eqref{5.6}.

**Step 4 : Backward Grönnwall.** Let \(t_0 \leq t \leq M\). We integrate \eqref{5.6} on \([t, M]\)
\[
\theta(t) \leq \theta(M) + C_0 K_{\max}^2 \int_t^M \theta(s) ds.
\]
We are able to apply Lemma \(B.1\) and get for all \(0 \leq t \leq M\)
\[
\begin{align*}
\theta(t) & \leq \theta(M) + C_0 K_{\max}^2 \int_t^M \exp \left( C_0 K_{\max}^2 \int_t^\sigma d\tau \right) d\sigma \\
& \leq \theta(M) + C_0 K_{\max}^2 \theta(M) \int_t^M e^{C_0 K_{\max}^2 \sigma} d\sigma \\
& \leq \theta(M) \left( 1 + e^{C_0 K_{\max}^2 M} \right).
\end{align*}
\]
Next, by \(5.4\)
\[
\theta(t) \leq C e^{-\kappa \alpha_{\min} M} \left( 1 + e^{C_0 K_{\max}^2 M} \right),
\]
which tends to 0 when \(M \to +\infty\), provided that \(\kappa > C_0 K_{\max}/\alpha_{\min}\) is chosen large enough. As a conclusion \(\theta(t) = 0\) for all \(t \geq t_0\) which in turn implies that \(\theta \equiv 0\) on \(\mathbb{R}\), since equation \(\eqref{4.4}\) is globally well-posed on \(\mathbb{R}\). In the case where the traveling waves take the form \(\eqref{1.8}\), one has \(|\alpha| = \frac{\sqrt{K}}{32\pi} K^2\), and \(\eqref{1.20}\) follows.

6. **Proof of Theorem 1.6**

The proof of this result is in the same spirit as the proof of Theorem 1.3 but here the error estimate will be done starting from \(t = 0\) instead of considering times \(t \gg 1\).

Assume that \((U_0, V_0) \in \mathcal{E} \times \mathcal{E}\) is a traveling wave solution to \(\eqref{4.1}\) in the sense \(\eqref{1.7}\), and that there exist \(c_0, C > 0\) such that
\[
|U_0(z)| + |V_0(z)| \leq C e^{-c_0|z|^2}.
\]
We moreover assume that ||\(U_0\)||_{L^2} = ||V_0||_{L^2} = 1, and we denote by \(\alpha_0 \in \mathbb{C}\) the speed of this traveling wave and consider \((\lambda_0, \mu_0)\) the phase parameters. Next, for \(a_j, b_j, \gamma_j \in \mathbb{C}, K \geq 0,\) and \(\theta \in \mathbb{R}\), we define
\[
U_j = Ke^{i\alpha_j} R_{\gamma_j} L_\theta U_0, \quad V_j = Ke^{i\beta_j} R_{\gamma_j} L_\theta V_0.
\]
By \[26\] Proposition 1.8 (iv)], each couple \((U_j, V_j)\) defines a traveling wave
\[
X_j(t, z) = e^{-i\lambda_j t} U_j(z + \alpha t) e^{\frac{i}{2}(\alpha - z\bar{\alpha}) t},
\]
\[
Y_j(t, z) = e^{-i\mu_j t} V_j(z + \alpha t) e^{\frac{i}{2}(\alpha - z\bar{\alpha}) t},
\]
with speed \(\alpha = \alpha_0 K^2 e^{-i\theta}\) and where \((\lambda_j, \mu_j) = K^2 (\lambda_0 + 2\Im(\bar{\alpha_0} \gamma_j e^{i\theta}), \mu_0 + 2\Im(\bar{\alpha_0} \gamma_j e^{i\theta})).\) We consider the solution \((u, v)\) to \(\eqref{1.2}\)
\[
u = \sum_{j=1}^n X_j + r_1 := X + r_1, \quad v = \sum_{j=1}^n Y_j + r_2 := Y + r_2,
\]
such that \((r_1(0), r_2(0)) = (0, 0)\). We now have to estimate the error term \((r_1, r_2)\) and by reversibility of the equation it is enough to consider the case \(t \geq 0\).
We write the expansion (4.7)–(4.8), and similarly to (4.9) we obtain
\[
\frac{d}{dt}\int_{\mathbb{C}} |r_1|^2 dL \leq C\|r_1\|_{L^2}^2 \sum_{j=0}^2 \|q_j\|_{L^2}.
\]

We now estimate each term \(\|q_j\|_{L^2}\). Denote by \(\eta(t) := \|r_1(t)\|_{L^2(\mathbb{C})} + \|r_2(t)\|_{L^2(\mathbb{C})}\).

- Control of \(\|q_0\|_{L^2}\). For all \(1 \leq j \leq n\), \(i\partial_t X_j = \Pi(|Y_j|^2 X_j)\), thus
  \[
  q_j = \sum_{\substack{1 \leq k \leq n \leq \rho \ (j,k,\ell) \neq (j,j,j)}} \Pi(Y_j \overline{Y}_k X_\ell).
  \]

Assume for instance that \(j \neq k\), so that \(\gamma_j \neq \gamma_k\). Then by (2.2)
\[
\|\Pi(Y_j \overline{Y}_k X_\ell)\|_{L^2} \leq C\|Y_j Y_k X_\ell\|_{L^2}
= CK^3\|(R_{\alpha,\gamma_j+\gamma_k} V_0)(R_{\alpha\gamma_k}^\perp V_0)\|_{L^2}
= CK^3\|(R_{\gamma_j-\gamma_k}^\perp V_0)(R_{\gamma_k}^\perp V_0)\|_{L^2}
\leq CK^3\|(R_{\gamma_j-\gamma_k}^\perp V_0)(R_{\gamma_k}^\perp V_0)\|_{L^\infty}\|U_0\|_{L^2}.
\]

Next by (5.2)
\[
\|\Pi(Y_j \overline{Y}_k X_\ell)\|_{L^2} \leq CK^3 e^{-\frac{59}{2} |\gamma_j-\gamma_k|^2} \|U_0\|_{L^2} = CK^3 e^{-\frac{59}{2} |\gamma_j-\gamma_k|^2}.
\]

The other terms are treated similarly, as a consequence
\[
\|q_0\|_{L^2} \leq CK^3 e^{-\frac{59}{2} \epsilon^2}.
\]

- The controls of \(\|q_j\|_{L^2}\) for \(1 \leq j \leq 2\) are obtained as in the proof of Theorem 1.3 and we get
  \[
  \|q_j\|_{L^2} \leq Cn^2 K^2 \eta^{1/2}.
  \]

Putting the previous estimates together we can write
\[
\frac{d}{dt}\eta(t) \leq C\eta(t)^{1/2}(n^2 K^2 \eta(t)^{1/2} + K^3 e^{-\frac{59}{2} \epsilon^2}) \leq Cn^2 K^2 \eta(t) + CK^4 e^{-c_0 \epsilon^2},
\]
and by integration
\[
\eta(t) \leq Cn^2 K^2 \int_0^t \eta(s)ds + CK^4 t e^{-c_0 \epsilon^2}.
\]

Finally, the Grönwall estimate implies
\[
\eta(t) = \|r_1(t)\|_{L^2(\mathbb{C})}^2 + \|r_2(t)\|_{L^2(\mathbb{C})}^2 \leq CK^4 t e^{-c_0 \epsilon^2 + Cn^2 K^2 t}.
\]

In particular, when \(c_0 = 1/2\) we obtain (1.24).

7. Proof of Theorem 1.7

We will adopt the formalism of [11] Section 7 so that the result of Theorem 1.7 will be a direct application of [11] Proposition 7.1.

As in [11] we denote by \(T\) the CR trilinear operator which was first defined in [10] and further studied in [15] [16]. This operator \(T\) is defined by
\[
(u_1, u_2, u_3) \mapsto T(u_1, u_2, u_3)(w) := \int_{\mathbb{R}^2} \int_{\mathbb{R}} u_1(x + w) u_2(x + \lambda x^+ + w) u_3(\lambda x^+ + w) d\lambda dx,
\]
where for $x = (x_1, x_2) \in \mathbb{R}^2$ we have set $x^\perp = (-x_2, x_1)$. By [15, Lemma 8.2], when it is restricted to the Bargmann-Fock space $\mathcal{E}$, the operator $\mathcal{T}$ can be simply expressed using $\Pi$ : for all $u_1, u_2, u_3 \in \mathcal{E}$,

$$\mathcal{T}(u_1, u_2, u_3) = \pi^2 \Pi(u_1 \overline{u_2} u_3).$$

Next, following [11], we define

$$\mathcal{T}[F]u := \mathcal{T}(F, F, u),$$

so that $\mathcal{T}[F]u = \pi^2 \Pi(|F|^2 u)$ when $F, u \in \mathcal{E}$. Consider the solution $(u, v)$ given by Theorem 1.3, define $\tilde{u}(s, z) := u(e^{s/2}, z)$ and $F(s, z) := \frac{e^{s/2}}{\pi} v(e^{s}, z)$. Then

$$i\partial_s \tilde{u} = \pi^2 \Pi(|F|^2 \tilde{u}) = \mathcal{T}[F] \tilde{u},$$

for all $s \in \mathbb{R}$. Recall the definition (1.3) of the Sobolev space $H^s(\mathbb{C})$. Using the explicit representation (1.12), we observe that for all $\sigma \geq 0$ and $k \geq 0$ we have the bounds

$$\|\partial^k_s F(s)\|_{H^\sigma(\mathbb{C})} + \|\partial^k_s \tilde{u}(s)\|_{H^\sigma(\mathbb{C})} \leq C e^{cs}, \quad \forall s \geq 0.$$

Moreover, when $s \to +\infty$

$$\|\tilde{u}(s)\|_{H^1(\mathbb{C})} \sim C e^s.$$

Therefore, [11, Proposition 7.1] can be applied: we set

$$V(t) := \frac{1}{\ln t} |e^{-itH} F(\ln \ln t)|^2,$$

which satisfies (1.26). Next by [11, Proposition 7.1], there exists $r_0 \in C(\mathbb{R}; H^1(\mathbb{C}))$ which satisfies

$$\|r_0(t)\|_{H^1(\mathbb{C})} \to 0, \quad t \to +\infty,$$

and such that

$$\psi(t) := e^{-itH} \tilde{u}(\ln \ln t) + r_0(t) = e^{-itH} u(\ln t) + r_0(t)$$

is solution to the equation (1.25). Let us give a better description of $\psi$. By (1.12) we have

$$\tilde{u}(\ln \ln t) = u(\ln t) = \sum_{j=1}^n e^{-i\lambda_j \ln t} R_{\alpha_j} \ln t U_j + r_1(\ln t),$$

thus

$$\psi(t) = e^{-itH} \sum_{j=1}^n e^{-i\lambda_j \ln t} R_{\alpha_j} \ln t U_j + (e^{-itH} r_1(\ln t) + r_0(t))$$

$$= \sum_{j=1}^n e^{-i\lambda_j \ln t} e^{-2it} L_{-2t} R_{\alpha_j} \ln t U_j + \eta(t),$$

where $\eta(t) := e^{-itH} r_1(\ln t) + r_0(t)$ satisfies

$$\|\eta(t)\|_{H^1(\mathbb{C})} \to 0, \quad t \to +\infty.$$

This completes the proof of Theorem 1.7.
Appendix A. On the decay of stationary solutions

In this section, we show that any stationary solution \((u(t), v(t)) = (e^{-i\lambda t}U, e^{-i\mu t}V)\) to (1.1) with \((U, V) \in \mathcal{E} \times \mathcal{E}\) has a Gaussian decay. Let \(\lambda, \mu \in \mathbb{R}, \sigma \in \{-1, 1\}\) and consider the system

\[
\begin{align*}
\lambda U &= \Pi(|V|^2 U) \\
\mu V &= \sigma \Pi(|U|^2 V).
\end{align*}
\]

Then we have a natural extension of [14, Theorem 5.3]:

**Theorem A.1.** Let \((U, V) \in \mathcal{E}\) be a solution of (A.1). Then, for any \(\eta > \eta_0\),

\[
\eta > \eta_0 = \left( \frac{1}{2} + \frac{1}{2 \log 3} \right)^{-1} \sim 1.226 \ldots,
\]

the following estimates hold true,

\[
|U(z)| \leq C_\eta e^{\eta |z|^2 - \frac{1}{2} |z|^2}, \quad |V(z)| \leq C_\eta e^{\eta |z|^2 - \frac{1}{2} |z|^2}, \quad \forall z \in \mathbb{C}.
\]

(A.2)

It is classical that a bound of the form (A.2) gives an estimate of the number of zeros of the corresponding function. More precisely, as proven in [14, Corollary 5.5], if one denotes by \(N(R) = \# \{ z \in \mathbb{C} \text{ such that } U(z) = 0 \text{ and } |z| < R \}\), then for any \(\eta > \eta_0\),

\[
\frac{N(R)}{R^\eta} \rightarrow 0 \quad \text{as} \quad R \rightarrow +\infty,
\]

and similarly for \(V\).

**Proof.** The argument follows the main lines of [14, Theorem 5.3] where a similar result is established for the solutions \(U_0 \in \mathcal{E}\) of the equation

\[
\lambda U = \Pi(|U_0|^2 U_0).
\]

There are very few changes in the proof, and we just give the main steps of the argument.

We write the expansion \(U = \sum_{n=0}^{+\infty} c_n \varphi_n\) and \(V = \sum_{n=0}^{+\infty} d_n \varphi_n\).

**Step 1 (Step 1 in [14, paragraph 5.3.]):** For \(0 < \kappa < 1\), we set \(M_n = \sup_{|w| > \kappa^n} (|U(w)| + |V(w)|)\) and we prove

\[
M_n \leq C_\eta e^{-(1-\kappa)^2} + C_\eta M_{n-1}^3.
\]

for some constant \(C_\eta > 0\). By an induction argument we show that there exists \(\sigma > 0\) such that

\[
|U(z)| + |V(z)| \leq C e^{-\sigma |z|^2}.
\]

(A.3)

**Step 2 (Step 2 in [14, paragraph 5.3.]):** The estimate (A.3) implies that there exists \(0 < r < 1\) such that

\[
|c_k| + |d_k| \leq Cr^k.
\]

(A.4)
Step 3 (Steps 1 and 2 in [14, paragraph 5.2.]): In the coordinates \((c_n), (d_n)\), the system (A.1) reads
\[
\begin{align*}
\lambda c_k &= \frac{1}{2\pi} \sum_{\ell, m, n \geq 0, k + \ell = m + n} \frac{(k + \ell)!}{2^{k + \ell} \sqrt{k! \ell! m! n!}} d_{\ell} d_{m} c_{n}, \quad k \geq 0 \\
\mu d_k &= \frac{\sigma}{2\pi} \sum_{\ell, m, n \geq 0, k + \ell = m + n} \frac{(k + \ell)!}{2^{k + \ell} \sqrt{k! \ell! m! n!}} c_{\ell} c_{m} d_{n}, \quad k \geq 0.
\end{align*}
\]

With a bootstrap argument, starting from (A.4), we show that for any \(\gamma < \gamma_0 = \frac{\log 2}{2 \log 3}\) we have
\[|c_k| + |d_k| \leq C k^{-\gamma k}. \tag{A.5}\]

Step 4 (Step 3 in [14, paragraph 5.3.]): The estimate (A.5) implies that for all \(\gamma < \gamma_0\)
\[|U(z)| + |V(z)| \leq C e^{C|z|^{\frac{\delta}{2} - \frac{1}{2} |z|^2}}, \]
with \(\delta = \left(\frac{1}{2} + \gamma\right)^{-1}\). \(\square\)

Appendix B. Technical results

We reproduce a backward Grönwall estimate taken from [11, Lemma B.1].

**Lemma B.1.** Let \(t_0 > 0\) and \(M > 0\). Assume that \(\beta > 0\) and \(\alpha > 0\) are functions defined on \((t_0, M)\), and that \(F\) satisfies for all \(t \in (t_0, M)\)
\[F(t) \leq \alpha(t) + \int_{t}^{M} \beta(\sigma) F(\sigma) d\sigma.\]
Then for all \(t \in (t_0, M)\)
\[F(t) \leq \alpha(t) + \int_{t}^{M} \alpha(\sigma) \beta(\sigma) \exp \left( \int_{t}^{\sigma} \beta(\tau) d\tau \right) d\sigma.\]

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