Discrete aspects of continuous symmetries in the tensorial formulation of Abelian gauge theories

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We show that standard identities and theorems for lattice models with \( U(1) \) symmetry get re-expressed discretely in the tensorial formulation of these models. We explain the geometrical analogy between the continuous lattice equations of motion and the discrete selection rules of the tensors. We construct a gauge-invariant transfer matrix in arbitrary dimensions. We show the equivalence with its gauge-fixed version in a maximal temporal gauge and explain how a discrete Gauss’s law is always enforced. We propose a noise-robust way to implement Gauss’s law in arbitrary dimensions. We reformulate Noether’s theorem for global, local, continuous or discrete Abelian symmetries: for each given symmetry, there is one corresponding tensor redundancy. We discuss semi-classical approximations for classical solutions with periodic boundary conditions in two solvable cases. We show the correspondence of their weak coupling limit with the tensor formulation after Poisson summation. We briefly discuss connections with other approaches and implications for quantum computing.

I. INTRODUCTION

Tensor Field Theory (TFT) is a recently developed approach of models studied in the context of lattice gauge theory [1–26]. The basic idea is to rewrite the partition function of lattice models as a product of tensors where all the indices are contracted. Many lattice models have compact fields. This feature appears naturally when we integrate over compact unitary groups attached to links in gauge models or over the Nambu-Goldstone modes of \( O(N) \) symmetric scalar models in nonlinear sigma models. Functions over compact groups can be expanded in terms of discrete sums of characters for Abelian groups [27] or more generally of group representations [28]. This property was exploited to calculate strong coupling expansions [29] and introduce dual variables [30–32] for the type of lattice models mentioned above.

These group theoretical methods were used in a systematic way to build the tensors [7, 8] of the spin and gauge models reviewed in [31], and to rewrite partition functions and averages of observables in a way that is suitable for exact coarse-graining or sampling of tensor configurations similar to the worm algorithm [33–35]. It is also important to realize that TFT remains useful and accurate in regimes that are completely beyond the range of validity of the strong coupling expansion even when phase transitions are present [36]. In addition, the discreteness of TFT formulations also makes them a natural starting point for building approximate forms of known lattice models suitable for quantum computations or quantum simulation experiments [37, 38].

Symmetry considerations have played a crucial role in uncovering the subconstituents of matter and their interactions. A key result is Noether’s theorem which associates a conserved charge to a global continuous symmetry. Is there a way to re-express Noether’s theorem in a completely discrete TFT formulation? In the following we will show show that the answer is affirmative in the case of a continuous and compact \( U(1) \) symmetry. We will also discuss the effect of approximations and various types of noise, which are unavoidable in practical TFT implementations, on these symmetry properties.

In the conventional formulation of field theory, a global \( U(1) \) symmetry results in a conserved Noether current at the classical level. The use of the continuous symmetry and the classical equations of motion, which result from local continuous variations of the action, are crucial steps of the derivation. At the quantum level, the invariance under a local continuous shift of the field variables generates Schwinger-Dyson equations which are quantum versions of the equations of motion. For local \( U(1) \) symmetries, Ward-Takahashi identities, or more complicated identities if gauge fixing is involved, can be found in quantum field theory textbooks such as Ref. [39]. These remarkable theorems and identities rely on the fact that the field variables are continuous.

In this article we show that the basic features of continuous Abelian symmetries in the conventional formulation of field theory have discrete counterparts in TFT. The article is organized as follows. In Sec. II, we review the tensorial formulation of models with continuous Abelian symmetries in arbitrary Euclidean space-time dimension \( D \). We start with the compact Abelian Higgs models (CAHM) and then consider the pure gauge limit and the \( O(2) \) spin model limit. In Sec. III, we establish a precise correspondence between the classical equations of motion of the lattice action with the selection rules. They have identical grading and geometrical interpretation in terms of inside/outside features. In Ref. [40], it was noted that these selection rules, a discrete divergenceless condition, could be interpreted as a discrete version of Noether’s theorem and would also extend to discrete symmetries. The selection rules for the CAHM are a discrete version of Maxwell’s equations with charges and currents. In particular, Gauss’s law which has complicated aspects in the
conventional Hamiltonian formulation appears in a transparent way in TFT. The questions of gauge-invariance and gauge-fixing are discussed in Sec. IV. We show that local selection rule redundancies observed in Ref. [40] can be reinterpreted in terms of a gauge fixing that removes the integration over the fields leading to the redundant selection rules. In Sec. V, we show that the mechanism can be extended to global symmetries and discrete symmetries. Noether’s theorem for Abelian symmetries can be re-expressed in the tensor reformulation context as: for each symmetry, there is a corresponding tensor redundancy. This applies with a remarkable generality to local, global, continuous or discrete Abelian symmetries.

The transfer matrix of the CAHM is constructed in arbitrary dimensions in Sec. VI. It is made out of electric and magnetic “layers” and is automatically gauge invariant. It defines a Hilbert space over which Gauss’s law is implemented when we apply the transfer matrix on an arbitrary state. We use “Gauss’s law” in a context dependent manner. In the CAHM context, there are charges and currents and Gauss’s law means that the quantum numbers associated to the matter fields are completely fixed by the quantum numbers associated with the gauge fields. This is because there are infinitely many possible Fourier modes for bosonic fields in contrast to fermions that only allow a finite number of possibilities as, for instance, for the Schwinger model [41-46].

However, when we take the pure gauge limit by decoupling the matter fields, we obtain a restriction on the gauge quantum number which is a discrete version of $\nabla \cdot E = 0$. In the pure gauge limit, we discuss the equivalence with a gauge-fixed version and propose a way to implement Gauss’s law with unrestricted variables which can be used in any dimension. In Sec. VII, we take the time-continuum limit in the same way as in [31] and get a similar Hamiltonian formulation.

The correspondence between the continuous classical equations of motion and the discrete selection rules allows us to connect topological solutions that appear with periodic boundary conditions, and not with open boundary conditions, to tensor assemblies that are allowed or forbidden under the same periodic or open boundary conditions. In Sec. VIII, we show that this correspondence can be made precise using Poisson summation for two models that are exactly solvable. The practical consequences of the results for coarse graining, the continuum limit and quantum computations are briefly discussed in the conclusions.

II. ABELIAN LATTICE MODELS

In this section we introduce the compact Abelian Higgs model (CAHM) and situations where it can be reduced to the pure gauge $U(1)$ model or the $O(2)$ spin model. In its original form, the Abelian Higgs model has also a non-compact scalar field which can be decoupled by a strong coupling limit discussed in [37] and will not be considered in the following. The main purpose of this section is to introduce models, notations and symmetries.

In the following, we use a $D$-dimensional (hyper) cubic Euclidean space-time lattice. The space-time sites are denoted $x = (x_1, x_2, \ldots, x_D)$, with $x_D = \tau$, the Euclidean time direction. Lattice units are implicit and the space-time sites are labelled with integers. We use the bold notation $\mathbf{x}$ for the $D-1$ dimensional labels of spatial sites. The links between two nearest neighbor lattice sites $x$ and $x + \mathbf{\mu}$ are labelled by $(x, \mathbf{\mu})$ and the plaquettes delimited by four sites $x$, $x + \mathbf{\mu}$, $x + \mathbf{\mu} + \mathbf{\nu}$ and $x + \mathbf{\nu}$ are labelled by $(x, \mathbf{\mu}, \mathbf{\nu})$. By convention, we start with the lowest index when introducing a circulation at the boundary of the plaquette. The total number of sites is denoted $V$. Periodic boundary conditions (PBC) or open boundary conditions (OBC) will be considered.

Our main object is the CAHM partition function

$$Z_{\text{CAHM}} = \prod_x \int_{-\pi}^{\pi} \frac{d\varphi_x}{2\pi} \prod_{x,\mu} \int_{-\pi}^{\pi} \frac{dA_{x,\mu}}{2\pi} e^{-S_{\text{gauge}} - S_{\text{matter}}},$$

(1)

with

$$S_{\text{gauge}} = \beta_{\text{pl}} \sum_{x,\mu < \nu} (1 - \cos(A_{x,\mu} + A_{x,\mu} - A_{x,\nu} - A_{x,\nu})),

(2)

and

$$S_{\text{matter}} = \beta_I \sum_{x,\mu} (1 - \cos(\varphi_{x,\mu} - \varphi_{x} + A_{x,\mu})).$$

(3)

The CAHM is a gauged version of the $O(2)$ model where the global symmetry under a $\varphi$ shift becomes local

$$\varphi'_x = \varphi_x + \alpha_x$$

(4)

and these local changes in $S_{\text{matter}}$ are compensated by the gauge field changes

$$A'_{x,\mu} = A_{x,\mu} - (\alpha_{x,\mu} - \alpha_x),

(5)

which also leave $S_{\text{gauge}}$ invariant.

The matter fields can be decoupled by simply setting $\beta_I = 0$. As they don’t appear in the action, their integration yields a factor 1 and we are left with the pure gauge (PG) $U(1)$ lattice model with partition function

$$Z_{\text{PG}} = \prod_{x,\mu} \int_{-\pi}^{\pi} \frac{dA_{x,\mu}}{2\pi} e^{-S_{\text{gauge}}},$$

(6)

The decoupling of the gauge fields is less straightforward. Strictly speaking, the $O(2)$ spin model is obtained by removing the gauge fields introduced to make the global symmetry a local one and the partition function of the $O(2)$ model reads

$$Z_{O(2)} = \prod_x \int_{-\pi}^{\pi} \frac{d\varphi_x}{2\pi} e^{-S_{O(2)}},$$

(7)
with
\[ S_{O(2)} = \beta_l \sum_{x,\mu} (1 - \cos(\varphi_{x+\hat{\mu}} - \varphi_x)). \] (8)

It is tempting to consider this model as the weak gauge coupling limit \((\beta_{pl.} \to \infty)\) of the CAHM. However for compact gauge fields, this limit involves subtleties when defined in the context of the infinite volume and continuum limit. In addition, the \(O(2)\) model has charge sectors labelled by integers and it is possible to select a specific charge sector by tuning the gauge boundary conditions. This is discussed in Ref. [38] in 1+1 dimensions.

Most of the results presented in the rest of the paper also hold for finite subgroups of \(U(1)\). If we consider the “clock” restriction to angles \(\varphi_x\) and \(A_{x,\mu}\) taking values \(\frac{2\pi}{q} \ell\) for \(\ell = 0, 1, \ldots, q - 1\), the values of \(\ell\) are added modulo \(q\) and form the additive group \(\mathbb{Z}_q\).

III. TENSOR SELECTION RULES AND LATTICE EQUATIONS OF MOTION

In this section, we reformulate the CAHM in arbitrary dimensions using the tensor formalism developed in Refs. [8, 37]. We point out and explain the geometrical analogy between the tensor selection rules and the lattice equations of motion. We then discuss the pure gauge and spin limits.

A. General case

The basic ingredients of the tensor reformulation are the Fourier expansions for the links
\[ e^{\beta_l \cos(\varphi_{x+\mu} - \varphi_x)} = \sum_{n_{x,\mu} = -\infty}^{+\infty} e^{in_{x,\mu}(\varphi_{x+\mu} - \varphi_x) + A_{x,\mu}} I_{n_{x,\mu}}(\beta_l), \] (9)
and the plaquettes
\[ e^{\beta_{pl.} \cos(A_{x,\mu} + A_{x+\hat{\mu},\nu} - A_{x+\hat{\mu},\mu} - A_{x,\nu})} = \sum_{m_{x,\mu,\nu} = -\infty}^{+\infty} e^{im_{x,\mu,\nu}(A_{x,\mu} + A_{x+\hat{\mu},\nu} - A_{x+\hat{\mu},\mu} - A_{x,\nu})} I_{m_{x,\mu,\nu}}(\beta_{pl.}). \] (10)

Notice that in both cases, the argument of the cosine function and the expression multiplying the Fourier indices are identical and, in particular, their signs are identical. These signs can be interpreted as forming a binary grading. This grading depends on the link or plaquette to which the fields belong.

The classical lattice equations of motions are obtained by setting the derivatives of the action with respect to the fields to zero. In general one obtains a sum of sine with relative signs corresponding to the grading. The tensors to be traced in the reformulation of the partition function, are obtained by integrating over the fields. When the Fourier indices corresponding to a given field are collected they appear with relative signs that correspond to the same grading and can be interpreted geometrically. We now discuss the scalar and gauge derivation/integration separately.

For the scalar fields, we first introduce the notation
\[ d_{x,\mu} \equiv \varphi_{x+\mu} - \varphi_x + A_{x,\mu}, \] (11)
which approximates the covariant derivative of \(\varphi\). The equation of motion
\[ \partial S / \partial \varphi_x = \beta_l \sum_{\mu} \left[ -\sin(d_{x,\mu}) + \sin(d_{x-\hat{\mu},\mu}) \right] = 0. \] (12)
On the other hand the integration with respect to \(\varphi_x\) implies
\[ \sum_{\mu} \left[ -n_{x,\mu} + n_{x-\hat{\mu},\mu} \right] = 0. \] (13)

It is clear that the geometrical structure of the two above equations are identical and that the equations can be obtained from each other by the substitution
\[ \beta_l \sin(d_{x,\mu}) \leftrightarrow n_{x,\mu}. \] (14)

The geometrical interpretation is simple: the \(n_{x,\mu}\) come with a plus and correspond to links coming “out” of \(x\) in the positive directions, while the \(n_{x-\hat{\mu},\mu}\) come with a minus and correspond to links coming “in” the site \(x\) from the negative direction. Notice that this feature is completely dictated by the sign convention appearing in the Fourier expansion Eq. (9). More specifically, fields appearing with a minus (plus) sign inside the cosine belong to an out (in) link, respectively.

Notice that Eq. (13) is a discrete version of Noether’s theorem which is a divergenceless condition. This implies [40] a discrete version of Gauss’s theorem which is preserved when truncations are applied. In addition, the equations of motions are satisfied in average, when inserted in the path integral. This is a consequence of the invariance under a local shift for each integral which is used in the derivation of Schwinger-Dyson equations. If such a shift is applied after expansion in Fourier modes in the functional integral, then Eq. (13) follows, making the connection between the two sets of equations.

In a similar manner, we can assign in and out features to the plaquettes attached to a link in a way consistent with the Fourier expansion Eq. (11). For \(\mu < \nu\), \(m_{x,\mu,\nu}\) are in and \(m_{x-\hat{\mu},\mu,\nu}\) out, while for \(\mu > \nu\), \(m_{x,\mu,\nu}\) are out and \(m_{x-\hat{\mu},\mu,\nu}\) in. Using the obvious analogy with the continuum, we define the standard lattice field strength tensor
\[ f_{x,\mu,\nu} \equiv A_{x,\mu} + A_{x+\hat{\mu},\nu} - A_{x+\hat{\mu},\mu} - A_{x,\nu}. \] (15)
As in the continuum they are gauge invariant.
With these notations,
\[
\frac{\partial S}{\partial A_{x,\mu}} = \beta_{pl.} \sum_{\nu > \mu} [\sin(f_{x,\mu,\nu}) - \sin(f_{x,\varphi,\mu,\nu})]
+ \sum_{\nu < \mu} [-\sin(f_{x,\nu,\mu}) + \sin(f_{x,\varphi,\nu,\mu})]
+ \beta_t \sin(d_{x,\mu})
= 0.
\] (16)

On the other hand, the integration over \(A_{x,\mu}\) yields the selection rule
\[
\sum_{\nu > \mu} [m_{x,\mu,\nu} - m_{x,\varphi,\mu,\nu}]
+ \sum_{\nu < \mu} [-m_{x,\nu,\mu} + m_{x,\varphi,\nu,\mu}]
+ n_{x,\mu}
= 0.
\] (17)

We see again geometric similarities between Eq. (16) with continuous variable and Eq. (17) with integer variables. They both have the tensor structure of
\[
\partial_{\mu} F^{\mu\nu} = J^\nu.
\] (18)

They can be mapped into each other using Eq. (14) and in addition the substitution
\[
\beta_{pl.} \sin(f_{x,\mu,\nu}) \leftrightarrow m_{x,\mu,\nu}.
\] (19)

Eq. (17) means that the link indices \(n_{x,\mu}\) can be seen as determined by unrestricted plaquette indices \(m_{x,\mu,\nu}\). We write this dependence as \(n_{x,\mu}([m])\) which is shorthand for Eq. (17). Note that for \(n_{x,\mu}([m])\) Eq. (13) holds [40] and as long as the gauge fields are present, there is no need to enforce Eq. (13).

Each integration provides a tensor with the selection rules discussed above. For convenience we factorize all the \(I_0(\beta)\) factors which dominate the small \(\beta\) regime and define the ratios
\[
t_n(\beta) \equiv \frac{I_n(\beta)}{I_0(\beta)} \approx \begin{cases} 1 - \frac{n^2}{2} + \mathcal{O}(1/\beta^2), & \text{for } \beta \to \infty \\ \frac{1}{2^n m!} + \mathcal{O}(\beta^n), & \text{for } \beta \to 0 \\ \end{cases}.
\] (20)

Their limiting behavior at weak and strong coupling will be used often.

The four tensor legs attached to a given plaquette \((x, \mu, \nu)\) must carry the same index \(m\). For this purpose we introduce the “B-tensor” as in [8]
\[
B^{(x,\mu,\nu)}_{m_1 m_2 m_3 m_4} = \begin{cases} t_{m_1}(\beta_{pl.}), & \text{if all } m_i \text{ are the same} \\ 0, & \text{otherwise} \end{cases}
\] (21)

These are assembled (traced) together with “A-tensors” attached to links with \(2(D - 1)\) legs orthogonal to the link
\[
A^{(x,\mu)}_{m_1 \ldots m_{2(D-1)}} = t_{n_{x,\mu}}(\beta_t) \delta_{n_{x,\mu}, n_{x,\nu}([m])}.
\] (22)

Notice that in contrast to Ref. [8], the weight of the plaquettes is carried by the \(B\)-tensor. The partition function with PBC can now be written as
\[
Z = (e^{-\beta_{pl.} I_0(\beta_{pl.})})^{V D (D-1)/2} (e^{-\beta_t} I_0(\beta_t))^V D 
\times \text{Tr} \prod I_{l.} A^{(l.)}_{m_1 \ldots m_{2(D-1)}} \prod B^{(pl.)}_{m_1 m_2 m_3 m_4},
\] (23)

where the trace means index contraction following the geometric procedure described above. The tensor assembly is illustrated in Fig. 1 for \(D = 2\). Illustrations for \(D = 3\) will be provided in Sec. VI.

FIG. 1. \(A\) and \(B\) tensors assembled in \(D = 2\).

It is clear that for PBC, we have a discrete translation invariance and the tensor assembly is the same everywhere. We can introduce OBC by starting with PBC and setting \(\beta_t\) and \(\beta_{pl.}\) to zero on the links and plaquettes at the boundary. Since
\[
I_n(0) = \delta_{n,0},
\] (24)

this forces the indices at the boundary to be zero with an associated weight 1.

B. The O\((2)\) model

Part of the results of subsection III A extend in a straightforward way to the O\((2)\) model. We just need to set \(A_{x,\mu} = 0\) in Eqs. (11) to (13). It was pointed out [40], that Eq. (13) is a discrete version of Noether’s theorem associated with the global O\((2)\) symmetry. A discrete version of Gauss theorem holds and guarantees a global neutrality for PBC and OBC.

It is also interesting to keep the gauge fields and take the \(\beta_{pl.} \to \infty\) limit where the weights of the \(B\)-tensors
are 1. The relation \( n_{x,\mu}(\{m\}) \) of Eq. (17) remain valid and guarantees that the discrete divergenceless condition Eq. (13) is obeyed for arbitrary plaquette configurations \( \{m\} \). For \( D = 2 \), this corresponds to the dual construction [32], however, the gauge procedure described here extends to any dimension without requiring the use of the dimension-dependent Levy-Civita tensor.

C. Pure gauge limit

We now consider the pure gauge limit by setting \( \beta_l = 0 \). Eq. (24) imposes the constraint \( n_{x,\mu} = 0 \) and Eq. (17) reduces to a discrete version of \( \partial_\mu F^{\mu\nu} = 0 \). We can make this statement more precise by introducing suggestive notations. We define the electric integers

\[
e_{x,j} \equiv m_{x,j,D},
\]

with \( j = 1, \ldots, D - 1 \), the integers associated with time plaquette and which can be interpreted as electric fields. Eq. (17) for \( \mu = D \) reads

\[
\sum_{j=1}^{D-1} (e_{x,j} - e_{x-j,j}) = 0.
\]

This is a discrete form of Gauss’s law in the pure gauge limit \( \nabla \cdot \mathbf{E} = 0 \).

For \( D \geq 3 \), we can introduce magnetic fields in a dimension dependent way. For \( D = 3 \), we define

\[
b_x \equiv m_{x,1,2}.
\]

Eq. (17) for \( \mu = 1 \) and 2 are

\[
e_{x,1} - e_{x-\tau,1} = -(b_x - b_{x-2}),
\]

\[
e_{x,2} - e_{x-\tau,2} = (b_x - b_{x-1}).
\]

These are a discrete version of the \( D = 3 \) Euclidean Maxwell’s equations

\[
\partial_1 B = \partial_2 E_2
\]

\[
\partial_2 B = -\partial_1 E_1,
\]

with \( B = F^{12} \). However, there is no discrete equation corresponding to Maxwell equation for the dual field strength tensor

\[
\partial_\mu \epsilon^{\mu\nu\sigma} F_{\nu\sigma} = 0.
\]

Example of legal configurations violating the discrete version of Eq. (30), also written \( \dot{B} = -\nabla \times \mathbf{E} \), can be constructed.

For \( D = 4 \), we can introduce

\[
b_{x,j} \equiv \epsilon_{jkl} m_{x,k,l},
\]

and obtain a discrete version of

\[
\partial_r \mathbf{E} = -\nabla \times \mathbf{B},
\]

with the Euclidean magnetic field

\[
F^{jk} = +\epsilon^{jkl} B^l.
\]

Note that Eq. (32) implies

\[
\partial_r (\nabla \cdot \mathbf{E}) = 0,
\]

even if we don’t impose Gauss’s law. Again there is no discrete version of the homogeneous equations for the dual field strength \( \dot{B} = -\nabla \times \mathbf{E} \) and \( \nabla \cdot \mathbf{B} = 0 \). Note that the sign in Eq. (32) is different in Euclidean and Minkowskian spaces. It can be traced to the minus sign in the Minkowskian Klein-Gordon equation.

D. Restrictions to \( Z_q \)

Some of the results of this section hold in an obvious way for the \( Z_q \) restrictions. The infinite sums in the Fourier expansions are replaced by finite sums with \( q \) values. The modified Bessel functions are replaced by their discrete counterparts:

\[
I_n(\beta) \rightarrow I_n^{(q)}(\beta) = (1/q) \sum_{\ell=0}^{q-1} e^{\beta \cos(\pi \ell/q)} e^{i n \pi \ell/q},
\]

which in the large \( q \) limit turns into the usual integral formula. In the Ising case \( (q = 2) \), we have

\[
I_0(\beta) \rightarrow \cosh(\beta), \text{ and } I_1(\beta) \rightarrow \sinh(\beta).
\]

The selection rules Eqs. (13) and (17) remain valid modulo \( q \). The infinitesimal variations of the action can be replaced discrete variations by an amount \( \frac{2\pi}{q} \), but the sine functions should be replaced by finite differences of cosine functions.

IV. LOCAL GAUGE INVARIANCE, SELECTION RULE REDUNDANCY AND GAUGE FIXING

Sec. III A makes clear that selection rule Eq. (13) due to the \( \varphi \) integration is redundant and a consequence of Eq. (17). This forces a local neutrality. If we insert \( e^{i\varphi x} \) in the partition function Eq. (13) is modified and clashes with the original form of Eq. (13) which follows from Eq. (17), forcing the functional integral to be zero.

Similarly, it was shown [40] that in the pure gauge limit the set of equations (17) with \( n_{x,\mu} = 0 \) are not independent. If we pick a site, we can construct a in-out partition for the legs attached to links coming out of this site, the sum of “in” indices is the same as the sum of the “out” indices, and if we assemble them on the boundary of a \( D \)-dimensional cube, as illustrated in Fig. 2 for \( D = 3 \), one of the divergenceless condition follow from the other \( 2D - 1 \) conditions.
FIG. 2. Illustration that one divergenceless condition is redundant for $D = 3$. Imagine the tensor assembled on the surface of a cube, remove the $A$-tensor on the top: the sum of the in indices equals the sum of the out indices at the missing tensor because it holds at the 17 other vertices.

To be completely specific, we remind the details of this in-out partition [40]. For a given pair of directions $\mu$ and $\nu$, there are 8 types of legs for the $A$-tensors on links connected the site $x$ that we label $[(x, \mu), \pm \nu]$; $[(x - \hat{\mu}, \mu), \pm \nu]$, $[(x, \nu), \pm \hat{\mu}]$, and $[(x - \hat{\nu}, \nu), \pm \hat{\mu}]$. The pair of indices appearing first refers to the links where the $A$-tensor is attached and the second index to the direction of the leg which can be positive or negative. The $[(x, \mu), \nu]$ with $\mu < \nu$ are given an out assignment. There are three operations that swap in and out: changing $(x, \mu)$ into $(x - \hat{\mu}, \mu)$, changing $\hat{\mu}$ into $\hat{\mu}$ and interchanging $\mu$ and $\nu$.

This redundancy can be rephrased in a more enlightening way in the discrete electric/magnetic language developed in Sec. III C: if Gauss’s law is satisfied for a $A$-tensor attached to the $((x, \tau), D)$ time link which is assembled with the divergenceless $A$-tensors attached to the $(2D - 1)$ spatial links $((x, \tau + 1), j)$ and $((x - j, \tau + 1), j)$ with $j = 1, \ldots, D - 1$, then the $A$-tensors attached to the time link $(x, \tau + 1), D)$ is forced to obey Gauss’s law because of its connection to the other tensors.

We can now see that gauge fixing is equivalent to removing these redundant conditions. For the CAHM, we can go to the unitary gauge where the $\varphi$ can be removed everywhere and the redundant Eq. (13) obtained from the $\varphi$ integration disappears independently of boundary conditions. For the pure gauge case, we can try to use the temporal gauge to set $A_{\tau, D}$ to zero. For OBC, this can be accomplished for all time links and as Gauss’s law is satisfied by the trivial $\epsilon = 0$ configuration at the time slices at the boundaries it is also satisfied on every time slice. For PBC, one link remains to be integrated for each closed time link (Polyakov loop) attached to any given spatial site. Putting these unintegrated time links at the same time, we get a time layer where after integrating over the leftover time links, Gauss’s law is satisfied. Again, Gauss’s law is then propagated to the entire lattice for the reason explained above.

V. A REFORMULATION OF NOETHER’S THEOREM

The discussion of Sec. IV clarifies that redundant selection rules are in one-to-one correspondence with irrelevant integrations. In other words, we can skip the integrations that produce redundant selection rules and replace these integrated fields by arbitrary values. This is exactly what gauge-fixing does. With our normalization of each integration over the circle to one, this does not cost extra factors.

The argument can be extended to global symmetries. In the case of the O(2) model, it follows from the discussion of Ref. [40] that in-out assignments for the $2D$ legs of the divergenceless tensor attached to sites imply that one of the divergenceless conditions is a consequence of all the other ones. This requires the whole tensor network to be isolated. For PBC, there are no boundaries. For OBC, the boundaries carry 0 indices which are neutral (neither in or out). It is clear that the global O(2) symmetry allows us to fix one of the $\varphi$ fields to an arbitrary value.

In view of this discussion, we suggest that Noether’s theorem can be expressed in the tensor formulation context as: for each symmetry, there is a corresponding tensor redundancy. This applies to global, local, continuous and discrete Abelian symmetries.

VI. TRANSFER MATRIX

In Eq. (23), the partition function is written as the trace of a product of tensors attached to links and plaquettes. We can organize this trace by assembling “time layers” corresponding to “magnetic” time slices and “electric” slices half-way between the magnetic time slices. This construction singles out a time direction as for the Hamiltonian treatment. The case $D = 2$ is discussed in Ref. [37] and the pure gauge $D = 3$ case in Ref. [22]. For $D = 3$, this construction can be visualized as a “lasagna”. We first discuss the general CAHM case and then the two limits.

A. General case

For the CAHM, the magnetic time slices contain $B$-tensors on space-space plaquettes and the $A$-tensors attached to their space links. These $A$-tensors have $2(D - 2)$
legs in spatial directions and 2 legs in opposite time directions which we can visualize as the “past” and the “future”. These legs in the time direction are connected to space-time plaquettes. This is illustrated in Fig. 3 for \( D = 3 \). Seen “from above”, in other words without the time legs, this looks like the full \( D = 2 \) assembly shown in Fig. 1.

FIG. 3. Magnetic layer of the transfer matrix for \( D = 3 \) on a time slice. The \( B \)-tensors are represented by circles.

In between the magnetic time slices we have electric layers with \( B \)-tensors on space-time plaquettes labelled by \( e(x, \tau, j) \) with a fixed \( \tau \), and the \( A \)-tensors attached to their time links. These \( A \)-tensors have \( 2(D-1) \) legs all in spatial directions. This is illustrated in Fig. 4 for \( D = 3 \). Seen “from above”, in other words without the time legs of the \( B \)-tensors, this looks like the full \( D = 2 \) assembly for the O(2) model.

We want to represent these two types of layers as matrices. It is convenient to think of these two types of layers as matrices connecting electric states

\[
|\{\mathbf{e}\}\rangle = \otimes_{x,j} |e_{x,j}\rangle.
\]

(37)

This is a natural choice because the \( B \)-tensors on the space-time plaquettes have two legs in the time direction. In this basis, the electric layer can be expressed as a diagonal matrix \( T_E \) with matrix elements

\[
\langle \{\mathbf{e}'\}| T_E |\{\mathbf{e}\}\rangle = \delta_{\{\mathbf{e}\},\{\mathbf{e}'\}} T_E(\{\mathbf{e}\}),
\]

(38)

where \( T_E(\{\mathbf{e}\}) \) can be written with some implicit notations as a traced product of \( A \) tensors on time links with \( B \) tensors on space-time plaquettes

\[
T_E(\{\mathbf{e}\}) = \text{Tr} \prod_{\text{time } l} A^{(l)}_{m_1,\ldots,m_{2(D-1)}} \prod_{\text{sp.-time pl.}} B^{(pl)}(\mathbf{e}).
\]

(39)

Similarly, we can define a magnetic matrix \( \mathcal{T}_M \) with matrix elements \( \langle \{\mathbf{e}\}| \mathcal{T}_M |\{\mathbf{e}'\}\rangle \) with the indices \( \mathbf{e} \) and \( \mathbf{e}' \) carried by the time legs of the \( A \)-tensors.

\[
\langle \{\mathbf{e}'\}| \mathcal{T}_M |\{\mathbf{e}\}\rangle = \text{Tr} \prod_{\text{sp. } l} A^{(l)}_{m_1,\ldots,m_{2(D-1)}}(\mathbf{e},\mathbf{e}') \prod_{\text{sp.-sp. pl.}} B^{(pl)}.
\]

(40)

All the traces are over the spatial legs of the tensors, while the time legs are left open and carry the the indices \( \mathbf{e} \) and \( \mathbf{e}' \). Figs. 3 and 4 should help visualizing these matrix elements: the horizontal lines correspond to traced indices while the vertical indices carry the \( \{\mathbf{e}\} \) indices.

We can now define the transfer matrix \( \mathcal{T} \) as

\[
\mathcal{T} \equiv (e^{-\beta_{pl} I_0(\beta_{pl})})^{(V/N \tau)} D^{(D-1)/2} (e^{-\beta_l I_0(\beta_l)})^{(V/N \tau)} D^{-1/2} \mathcal{T}_E^{-1/2} \mathcal{T}_M \mathcal{T}_E^{-1/2},
\]

(41)

with \( N_r \) the number of sites in the temporal direction. With this definition, we can reexpress the partition function as

\[
Z = \text{Tr} \mathcal{T}^{N_r},
\]

(42)

B. O(2) limit

For the O(2) model, the transfer matrix can be constructed by taking all the O(2) tensors on a time slice.
and tracing over the spatial indices. This is discussed in detail in Ref. [35] in the case $D = 2$ and the extension to arbitrary dimension is straightforward. In the CAHM reformulation the implicit $O(2)$ tensors attached at each site are divergenceless. By implicit, we mean that a link index $n_{x,a}$ carries a weight $t_{n_{x,a}}(\beta_l)$ as in the $O(2)$ model (see Eq. (22)).

From the perspective of quantum simulations, the gauge parametrization insures that the divergenceless condition is automatically satisfied and insensitive to noise. However the Hilbert space becomes larger for $D \geq 4$ (see below).

C. Pure gauge limit: a robust way to implement Gauss’s law

The restricted electric Hilbert space of the pure gauge compact $U(1)$ model in $D$ dimensions is equivalent to the set of legal tensor configurations of a $D-1$ dimensional $O(2)$ model. The integer quantum numbers of the space-time plaquettes $e_{x,j}$ are like the link variables $n_{x,j}$ for $O(2)$. Both sets are divergenceless. For the pure gauge model, the divergenceless condition is Gauss’s law (without charge density).

In Sec. VI B we presented the $O(2)$ model as a weak gauge coupling limit of the compact Abelian Higgs model. As seen in Eq. (17), integration over the gauge fields provides an automatic divergenceless condition for the link quantum numbers. This is a discrete version of $\partial_\mu \partial_\nu F^{\mu \nu} = \partial_\mu J^\mu = 0$. The argument does not involve the dimension-dependent Levy-Civita tensor.

We can insure that Gauss’s law is automatically satisfied by introducing a new set of quantum numbers $c_{x,j,k}$, associated with the plaquettes of a $D-1$ CAHM, and unrelated to the existing gauge quantum numbers. For an arbitrary configuration $\{c_{x,j,k}\}$, we impose

$$e_{x,j} = \sum_{k>j} \left( -c_{x,j,k} + c_{x-k,j,k} \right) + \sum_{k<j} \left( c_{x,k,j} - c_{x-k,k,j} \right),$$

and Gauss’s law is automatically satisfied. This is a discrete version of

$$E^k = \partial_j C^{jk},$$

For an arbitrary antisymmetric tensor $C^{jk}$ with indices $j, k$ running from 1 to $D-1$. It is possible to introduce dimension-dependent “magnetic” notations such as $G = \epsilon^{kl} C^{kl}$ for $D = 3$ and $G^1 = \epsilon^{jkl} C^{jkl}$ for $D = 4$.

For a $D = 3$ pure gauge theory we can visualize the electric Hilbert space as a $D = 2$ O(2) model being on a plane between two time slices, as at the bottom of Fig. 4. We can further imagine the auxiliary variables located in the middle of the plaquettes of this “horizontal” plane, which means in the center of the $D = 3$ cubes of the original lattice. This is equivalent to the dual formulation discussed in Ref. [22].

For $D = 4$, this reparametrization is a discrete equivalent of setting

$$E = \nabla \times G.$$  \hspace{1cm} (45)

This guarantees Gauss’s law, but $\nabla \times E$ is in general non-zero so we don’t use this trick for conventional electrostatics because one of the homogeneous Maxwell’s equation ($B = -\nabla \times E$) implies that the magnetic field changes with time.

This method is very efficient for $D = 3$, because it reduces the dimensionality of the Hilbert space. There is one index per site $(c_{x,1,2})$ rather than 2 $(e_{x,1} \ldots e_{x,2})$. For $D = 4$, there are 3 indices per sites in both case, because $c_{x,j,k}$ is only defined up to a gradient. However, the robustness against noise is an important advantage.

VII. HAMILTONIAN LIMIT

For lattice models at Euclidean time, the transition from the Lagrangian to the Hamiltonian formalism is a standard procedure [30, 31]. The central idea is to deform the isotropic formulation by increasing the $\beta$ variables associated with time directions and to decrease those associated with space directions. In the tensor language, examples involving the transfer matrix in 1+1 dimension can be found in Refs. [35, 37, 38].

The crucial features of $T_E$ is that it only involves time links and plaquettes having one direction in time. We introduce separate $\beta_r$ couplings for $T_E$ and use redefinitions in terms of the time lattice spacing $a_r$:

$$\beta_{r,pl.} = \frac{1}{a_r g_{pl.}^2}, \quad \beta_{r,l.} = \frac{1}{a_r g_{l.}^2}. \hspace{1cm} (46)$$

Given the weak coupling ($\beta$) behavior of $t_{n,\beta}(\beta)$ given in Eq. (20), at first order in $a_r$, we get “rotor” energies $(1/2)g_{pl.}^2 m_r^2$ for the plaquettes and $(1/2)g_{l.}^2 n_r^2$ for the links.

On the other hand, $T_M$ only involves space links and space-space plaquettes and we redefine

$$\beta_{s,pl.} = a_r J_{pl.}, \quad \beta_{s,l.} = a_r h_{l.}. \hspace{1cm} (47)$$

Given the strong coupling ($\beta$) behavior of $t_{n,\beta}(\beta)$ from Eq. (20), at first order in $a_r$, the contribution to $T_M$ involve a single link or plaquette with quantum number $\pm 1$ all the other ones having a quantum number 0 and a weight $1$. This leaves us with only few options: raise or lower $e_{x,j}$ over a link $(x, j)$ or raise over two links and lower over the two other links of a plaquette.

We define the Hamiltonian $H$ as the order $a_r$ correction to the identity in the transfer matrix:

$$T = 1 - a_r h_l + O(a_r^2) .$$

(48)
After introducing the operators [47] $\hat{e}_{x,j}$ and $\hat{U}_{x,j}$ such that
\begin{align}
\hat{e}_{x,j} |e_{x,j}\rangle &= e_{x,j} |e_{x,j}\rangle \\
\hat{U}_{x,j} |e_{x,j}\rangle &= |e_{x,j} + 1\rangle \\
\hat{U}_{x,j}^\dagger |e_{x,j}\rangle &= |e_{x,j} - 1\rangle,
\end{align}
(49)
the discussion of the first order behavior of $T_F$ and $T_M$ allows us to write
\begin{align*}
\mathcal{H} &= \frac{1}{2} g_{pl}^2 \sum_{x,j} (\hat{e}_{x,j})^2 \\
&\quad + \frac{1}{2} g_{pl}^2 (\sum_{x,j} (\hat{e}_{x,j} - \hat{e}_{x-j,j}))^2 \\
&\quad - h, \sum_{x,j} (\hat{U}_{x,j} + h.c.) \\
&\quad - J_{pl} \sum_{x,j<k} (\hat{U}_{x,j} \hat{U}_{x+j,k} \hat{U}_{x+k,j} \hat{U}_{x,k} + h.c.).
\end{align*}
(50)
We have used
\begin{equation}
\sum_{j=1}^{D-1} (e_{x,j} - e_{x-j,j}) = n_x D, 
\end{equation}
(51)
to eliminate $n_x D$. Up to straightforward rescalings of the couplings, the first three terms are the same as in 1+1 dimensions [37, 38], while the fourth one requires at least one more spatial dimension and is as in the pure gauge case [31]. The considerations [40] regarding the modification of the algebra due to truncation and the relationship with the quantum link approach [48–51] remain valid.

VIII. TOPOLOGICAL SOLUTIONS AND SEMI-CLASSICAL APPROXIMATIONS

In Sec. III, we found a direct similarity between the continuous lattice equations of motion and the discrete tensor selection rules. In this section we discuss the effect of periodic boundary conditions on both sets of equations. We will limit ourselves to the solvable cases: the $D = 1$ O(2) spin model and the $D = 2$ pure gauge $U(1)$ model.

For the $D = 1$ O(2) spin model with PBC and $N_\tau$ sites, the equations of motion (12) with $A_{x,\mu} = 0$ are equivalent to the statement that $\sin(\varphi_{x+1} - \varphi_x)$ takes the same value on every link. These equations have many solutions and we will focus our attention on the ones that can be interpreted as continuous topological solutions in the continuum limit for PBC. If we impose that $\varphi_{x+1} - \varphi_x$ is a small constant, we can obtain a solution that meets this requirement. Given any choice for the constant, we can then “integrate” the equations: starting with some $\varphi_0$, we obtain $\varphi_1$, and so on until, due to PBC, we get an independent value for $\varphi_n$ which should be consistent with the initial value modulo an integer multiple of $2\pi$.

This approximately corresponds to a smooth mapping of the circle into itself provided that the successive changes can be made arbitrarily small. This can be accomplished by requiring that for all links
\begin{equation}
\varphi_{x+1} - \varphi_x = \frac{2\pi}{N_\tau} \ell, 
\end{equation}
(52)
for a given integer $\ell$. By taking, $N_\tau$ large with fixed $\ell$ we obtain a solution which can be interpreted as a topological solution with winding number $\ell$. In the limit $\ell \ll N_\tau$, these solutions have classical action
\begin{equation}
S_\ell \approx \beta \left(\frac{2\pi}{N_\tau}\ell\right)^2 N_\tau. 
\end{equation}
(53)

We can calculate the quadratic fluctuations with respect to this solution. We can first use the global O(2) symmetry to set $\varphi_0 = 0$. Other values of $\varphi_0$ are taken into account by performing the integration over $\varphi_0$ which with our normalization of the measure yields a factor 1. By construction, the linear fluctuations vanish because the first derivatives are zero and all we need to calculate are the quadratic fluctuations
\begin{equation}
\Delta = \prod_{x=1}^{N_\tau-1} \int_{-\pi}^{\pi} \frac{d\varphi_x}{2\pi} e^{-S_\ell^{quad}}, 
\end{equation}
(54)
with
\begin{equation}
S_\ell^{quad} = \frac{\beta}{2} \cos(\frac{2\pi}{N_\tau}\ell) (\varphi_1^2 + (\varphi_2 - \varphi_1)^2 + \cdots + \varphi_{N_\tau-1}^2) 
\end{equation}
(55)
Following the standard quadratic path integral procedure, we find
\begin{equation}
\Delta = (N_\tau-1/2) \left(\frac{2\pi}{N_\tau}\ell\right)^{-(N_\tau-1)/2}. 
\end{equation}
(56)

We can now attempt to re-sum the topological contributions. This is delicate because we have assumed $\ell \ll N_\tau$, however if $\beta$ is large enough, the terms with large $\ell$ are exponentially suppressed. In the same spirit, we will ignore the $\ell$ dependence of $\Delta$ and use the Poisson summation formula
\begin{equation}
\sum_{\ell=-\infty}^{\infty} e^{-\frac{\beta}{2} \ell^2} = \sqrt{\frac{2\pi}{B}} \sum_{n=-\infty}^{\infty} e^{-\frac{(2\pi n)^2}{2B}} 
\end{equation}
(57)
with $B = \beta(2\pi)^2/N_\tau$. Putting everything together, we get a semi-classical approximation of the partition function in the large $\beta$ limit
\begin{equation}
Z \approx (2\pi\beta)^{-N_\tau/2} \sum_{n=-\infty}^{\infty} (e^{-\frac{\pi^2 n^2}{N_\tau}})^{N_\tau}. 
\end{equation}
(58)

We now consider the solutions of the discrete Eq. (13). The solution is that $n_{x,1}$ should be constant. With PBC, this implies the exact expression:
\begin{equation}
Z = \sum_{n=-\infty}^{\infty} (e^{-\beta I_n(\beta)})^{N_\tau}. 
\end{equation}
(59)
which can be compared to the semi-classical expression Eq. (58). Using the large $\beta$ approximations

$$e^{-\beta I_0(\beta)} \simeq \frac{1}{\sqrt{2\pi\beta}} (1 + O(1/\beta)), \quad (60)$$

and Eq. (20) in the same limit, we see the approximate correspondence between the two expressions.

A similar construction can be carried for the $D = 2$ pure gauge $U(1)$ model with PBC. We consider a rectangular $N_s \times N_r$ lattice. The equation of motion requires that $\sin(f_{x,1,2})$ is constant. Following the analogy with the O(2) case, we start with

$$f_{x,1,2} \equiv A_{x,1} + A_{x+1,2} - A_{x,2} - A_{x+2,1} = \delta, \quad (61)$$

with $\delta$ a constant to be determined with PBC. As seen in Sec. IV, we can gauge fix the temporal links with a given spatial coordinate $x_1$ to the identity with the exception of one time layer. For definiteness, we take this layer of nontrivial time links to be between $\tau = N_r - 1$ and $N_r$ which is identified with 0 due to PBC. The space links with a given spatial coordinate, which can be visualized as a vertical ladder can be treated as the indices of a $D = 1$ O(2) model changing by $-\delta$ at each step until we get to the “last” rung and temporal links are present. The constancy of the “last” plaquette requires that

$$A_{(x+1, N_r-1),2} - A_{(x, N_r-1),2} = N_r \delta. \quad (62)$$

Iterating in the spatial direction, we obtain PBC in the spatial direction provided that

$$\delta = \frac{2\pi}{N_s N_r} \ell. \quad (63)$$

The action for this topological solution is

$$S^{U(1)}_\ell \simeq \frac{\beta}{2} \left( \frac{2\pi}{N_s N_r} \ell \right)^2 N_s N_r. \quad (64)$$

Note that we could have obtained another periodic solution by setting all the time links to 1 and imposing PBC in time for $N_s$ independent $D = 1$ O(2) models, however, the action for these configurations is larger by a factor $N_r^2$.

The quadratic fluctuations can be calculated as in the O(2) case but with extra complications due to the special time layer. Keeping track of all the $2\pi$ factors and using Poisson summation for the winding numbers, we obtain the semi-classical approximation

$$Z^{U(1)} \simeq (2\pi \beta)^{-N_s N_r/2} \sum_{n=-\infty}^{\infty} (e^{-n^2 \pi})^{N_s N_r}, \quad (65)$$

which agrees with the exact expression at leading order.

As a test of the semi-classical picture we can calculate the topological susceptibility. For this purpose we first calculate

$$Z(\beta, \theta) = \prod_{x,\mu} \int_{-\pi}^{\pi} \frac{dA_{x,\mu}}{2\pi} e^{-S_{g(x,y)} - i\theta Q}, \quad (66)$$

with the topological charge $Q$ defined as

$$Q = \frac{1}{2\pi} \sum_x \sin(A_{x,1} + A_{x+1,2} - A_{x,2} - A_{x+2,1}). \quad (67)$$

The topological susceptibility is defined as

$$\chi = -\frac{d^2}{d\theta^2} \ln(Z)|_{\theta=0}. \quad (68)$$

It can be calculated using the exact resummation [52]

$$Z(\beta, \theta) = \sum_{n=-\infty}^{\infty} \left[ e^{-\beta I_n} \sqrt{\beta^2 - \left(\frac{\theta}{2\pi}\right)^2} \right] \times \left( \frac{\beta - \theta}{\beta + \theta} \right)^{n/2} N_s N_r. \quad (69)$$

If $\chi$ is dominated by configurations corresponding to winding number $\pm 1$ where $|Q| \simeq 1$ in the continuum limit, we have the large-$\beta$ estimate

$$\chi \simeq (0)^2 + 1 + (1)^2 \exp\left( -\frac{\beta (2\pi)^2 (1)^2}{2 N_s N_r} \right) + (-1)^2 \exp\left( -\frac{\beta (2\pi)^2}{2 N_s N_r} (-1)^2 \right). \quad (70)$$

Fig. 5 shows that this estimate is reasonably good when $\beta$ is large enough.

![Logarithm of the topological susceptibility using the exact formula for $N_s = N_r = 8$ expanded up to order 5 (dots) and the semi-classical approximation Eq. (70) (continuous line).](image-url)

FIG. 5. Logarithm of the topological susceptibility using the exact formula for $N_s = N_r = 8$ expanded up to order 5 (dots) and the semi-classical approximation Eq. (70) (continuous line).

As a remark, it is a common misconception to identify the Fourier mode indices $n$ in Eq. (59) as “topological sectors”. They are rather labelling “rotor energy levels” $n^2/2$. The fact that Poisson summation interchanges these energy levels with the correctly identified topological sectors was observed in Ref. [53] in a version of the O(2) model where the fluctuations are limited. Note also that it is possible to construct models where the approximations Eqs. (58) and (65) are exact. The questions of topological configurations and duality are discussed for Abelian gauge models of this type in various dimensions in Refs. [54, 55].
IX. CONCLUSIONS

In summary, we have shown that some standard theorems and identities associated with the $U(1)$ symmetry that can be derived in the conventional formulation of field theory have a discrete counterpart in TFT. This includes the equations of motion, Noether’s theorem, Maxwell’s equations with charges and currents, Gauss’ law, gauge-fixing and effects of boundary conditions.

We have constructed gauge-invariant transfer matrices by reorganizing the partition function obtained integrating over all the fields without gauge fixing. We also explained how an equivalent partition function is obtained by a gauge-fixing which removes intermediate projections into the sector of the Hilbert space which satisfies Gauss’s law. These projections are only useful in the case of a noisy evolution. We proposed a reparametrization of the the sub Hilbert space satisfying Gauss’s law in arbitrary dimension which generalizes dual construction in $D = 3$.

Practical implementations of TFT require finite truncations. They provide numerically accurate approximations at finite volume [26, 35, 37, 38]. The results derived here depend only on the selection rules which completely capture the symmetry and not on the numerical values of the Bessel functions appearing in Fourier expansions. This confirms the observation that truncations preserve the symmetries [40]. The class of universality is encoded in the selection rules of the tensors and is expected that in the continuum limit, results should not depend on microscopic details. Similar expectations are found in the quantum link approach [48–51]. One advantage of TFT is that it connects smoothly the Lagrangian and Hamiltonian approaches in a way that allows testing using standard importance sampling methods. This allows comparisons with Hamiltonian based quantum simulations proposals for Abelian gauge models [56–61].

The discrete nature of TFT formulations makes it a generic tool to setup quantum computing protocols. It provides an alternative to field discretization [62–64]. Motivations for quantum computing include doing ab-initio real-time calculations relevant to fragmentation processes and parton distribution functions [65]. In order to work on these ambitious and high-impact projects, we need to move up the steps of a “ladder” of models [31, 66] that has been proven effective to deal with the static properties of hadrons. The first steps are the spin and gauge Ising models. Practical implementations are discussed in Refs. [67–69]. The next steps are their counterparts with a continuous and compact Abelian $U(1)$ symmetry [22, 51, 70, 71]. In this context, the Euclidean transfer matrix could also be used to prepare initial states following the suggestion of Ref. [72].

Models with Wilson [13–15, 19, 21, 23] and staggered [26] fermions have also been reformulated using TFT. The Schwinger model is of great interest in this context. This model and its $Z_q$ approximations have been studied directly with the Hamiltonian formalism [41–46], providing useful comparisons for future TFT calculations.

As a last remark, the compactness of the field variables in the models considered here provide a convenient and elegant computational framework. Could compactness be a physical feature of the fluctuations at very short distance? It would interesting to put experimental limits on this possibility.

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