DIMENSION GROUPS FOR INTERVAL MAPS

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Abstract. With each piecewise monotonic map \( \tau \) of the unit interval, a dimension triple is associated. The dimension triple, viewed as a \( \mathbb{Z}[t, t^{-1}] \) module, is finitely generated, and generators are identified. Dimension groups are computed for Markov maps, unimodal maps, multimodal maps, and interval exchange maps. It is shown that the dimension group defined here is isomorphic to \( K_0(A) \), where \( A \) is a \( \mathbb{C}^* \)-algebra (an “AI-algebra”) defined in dynamical terms.

1. Introduction

Given a piecewise monotonic map \( \tau \) of the unit interval into itself, our goal is to associate a dimension group \( DG(\tau) \), providing an invariant for the original map.

In a dynamical context, dimension groups were introduced by Krieger [21]. Motivated by Elliott’s classification of AF-algebras by their dimension groups [12], he gave a purely dynamical definition of the dimension group, via an equivalence relation defined by the action of an “ample” group of homeomorphisms on the space of closed and open subsets of a zero dimensional metric space. For a shift of finite type, he associated an ample group, and in [22], showed that the dimension triple (consisting of an ordered dimension group with a canonical automorphism) completely determines an irreducible aperiodic shift of finite type up to shift equivalence.

Krieger’s definition of a dimension group was extended to the context of a surjective local homeomorphism \( \sigma : X \to X \), where \( X \) is a compact zero dimensional metric space, by Boyle, Fiebig, and Fiebig ([1]), who defined a dimension group called the “images group”, and used this group as a tool in studying commuting local homeomorphisms.

We sketch the construction of the dimension group in [1]. If \( \sigma : X \to X \), the transfer map \( L : C(X, \mathbb{Z}) \to C(X, \mathbb{Z}) \) is defined by

\[
L_\sigma f(x) = \sum_{\sigma y = x} f(y).
\]

Then \( G_\sigma \) is defined to be the set of equivalence classes of functions in \( C(X, \mathbb{Z}) \), where \( f \sim g \) if \( L^n f = L^n g \) for some \( n \geq 0 \). Addition is given by \([f] + [g] = [f + g]\), and the positive cone consists of classes \([f]\) such that \( L^n f \geq 0 \) for some \( n \geq 0 \). This is the same as defining clopen sets \( E, F \) in \( X \) to be equivalent if for some \( n \geq 0 \), \( \sigma^n \) is 1-1 on \( E \) and \( F \), and \( \sigma^n(E) = \sigma^n(F) \), and then building a group out of these equivalence classes by defining \([E] + [F] = [E \cup F]\) when \( E, F \) are disjoint. This latter definition is the one given in [1]; the authors then observe that it is equivalent to the definition above involving the transfer operator. If \( \sigma \)
is surjective, this dimension group is the same as the stationary inductive limit of $L_\sigma : C(X,\mathbb{Z}) \to C(X,\mathbb{Z})$, cf. Lemma 3.8 and equation (3.8) in the current paper.

A related approach was taken by Renault in [27]. If $X_1, X_2, \ldots$ are compact metric spaces, and $T_n : C(X_n) \to C(X_{n+1})$ is a sequence of positive maps, Renault defined the associated dimension group to be the inductive limit of this sequence. If $X_n = X$ for all $n$, and $T = L_\sigma$ for a surjective local homeomorphism $\sigma$, the resulting dimension group is formally similar to that in [1]. However, the use of $C(X)$ instead of $C(X,\mathbb{Z})$ results in different dimension groups.

These definitions of dimension groups aren’t directly applicable to interval maps, since such maps are rarely local homeomorphisms. We therefore associate with each piecewise monotonic map $\tau : [0,1] \to [0,1]$ a local homeomorphism. This is done by disconnecting the unit interval at a countable set of points, yielding a space $X$, and then lifting $\tau$ to a local homeomorphism $\sigma : X \to X$. The properties of $\sigma$ are closely related to those of $\tau$. A similar technique has long been used in studying interval maps, e.g., cf. [18, 14, 29, 32].

If $\tau : I \to I$ is piecewise monotonic, and $\sigma : X \to X$ is the associated local homeomorphism, the space $X$ will be a compact subset of $\mathbb{R}$, but will not necessarily be zero dimensional. However the map $\sigma$ will have the property that each point has a clopen neighborhood on which $\sigma$ is injective, and this allows us to define a dimension group in the same way as in [1]. We then define $DG(\tau)$ to be the dimension group $G_\sigma$ associated with $\sigma$.

The result is a triple $(DG(\tau), DG(\tau)^+, L_\tau)$, where $DG(\tau)$ is a dimension group with positive cone $DG(\tau)^+$, and $L_\tau$ is a positive endomorphism of $DG(\tau)$, which will be an order automorphism if, for example, $\tau$ is surjective. In this case, $DG(\tau)$ can be viewed as a $\mathbb{Z}[t,t^{-1}]$ module.

We now summarize this paper. Sections 2–3 lead up to the definition of the dimension group for a piecewise monotonic map (Definition 3.13). Sections 4–6 develop basic properties of the dimension group of a piecewise monotonic map, for example, characterizing when they are simple, and describing a canonical set of generators for the dimension module (Theorem 6.2), which is quite useful in computing dimension groups. Sections 7–11 compute the dimension group for various families of interval maps, some of which are sketched below. Section 12 gives a dynamical description of a $C^*$-algebra $A_\tau$ such that $K_0(A_\tau)$ is isomorphic to $DG(\tau)$.

**Figure 1.** Examples of piecewise monotonic maps
This paper initiates a program to make use of dimension groups (and more generally, C*-algebras and their K-theory) to find invariants for interval maps. In \[30\], we investigate dimension groups for transitive piecewise monotonic maps. For such maps, we describe the order on the dimension group in concrete terms, and show that for some families of maps, the dimension triple is a complete invariant for conjugacy.

In the paper \[8\], two C*-algebras \(F_{\tau}\) and \(O_{\tau}\) are associated with piecewise monotonic maps, and the properties of these algebras are related to the dynamics. These algebras are analogs of the algebras \(F_A\) and \(O_A\) associated with shifts of finite type by Cuntz and Krieger \[9\], and \(F_{\tau}\) is isomorphic to the algebra \(A_{\tau}\) defined in Section 12 of this paper.

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2. Piecewise monotonic maps and local homeomorphisms

Let \(I = [0, 1]\). A map \(\tau : I \to I\) is piecewise monotonic if there are points \(0 = a_0 < a_1 < \ldots < a_n = 1\) such that \(\tau|_{[a_{i-1}, a_i]}\) is continuous and strictly monotonic for \(1 \leq i \leq n\). We denote by \(\tau_i : [a_{i-1}, a_i] \to I\) the unique continuous extension of \(\tau|_{[a_{i-1}, a_i]}\); note that \(\tau_i\) will be a homeomorphism onto its range. We will refer to the ordered set \(C = \{a_0, a_1, \ldots, a_n\}\) as the partition associated with \(\tau\), or as the endpoints of the intervals of monotonicity. We will say this partition is maximal if the intervals \((a_{i-1}, a_i]\) are the largest open intervals on which \(\tau\) is continuous and strictly monotonic. For each piecewise monotonic function there is a unique maximal partition. We do not assume a partition associated with \(\tau\) is maximal unless that is specifically stated. (We will be primarily interested in maximal partitions, but there will be a few cases where non-maximal partitions are useful.)

Our goal in this section is to modify \(\tau\) slightly so that it becomes a local homeomorphism \(\sigma\) on a larger space \(X\), in such a way that properties of \((I, \tau)\) and \((X, \sigma)\) are closely related. In general, points in the partition \(C\) cause trouble, since \(\tau\) is usually neither locally injective nor an open map at such points, and may be discontinuous. We will disconnect \(I\) at points in \(C\) (and at points in their forward and backward orbit).

We have to be a little careful about the values of \(\tau\) at points \(c\) in \(C\) where \(\tau\) is discontinuous: what are relevant for our purposes are the left and right limits \(\lim_{x \to c^\pm} \tau(x)\), not the actual values \(\tau(c)\). If \(\tau : I \to I\) is piecewise monotonic, we define a (possibly multivalued) function \(\tilde{\tau}\) on \(I\) by setting \(\tilde{\tau}(x)\) to be the set of left and right limits of \(\tau\) at \(x\). At points where \(\tau\) is continuous, \(\tilde{\tau}(x) = \{\tau(x)\}\), and we identify \(\tilde{\tau}(x)\) with \(\tau(x)\). If \(A \subset I\), then \(\tilde{\tau}(A) = \cup_{x \in A} \tilde{\tau}(x)\), and \(\tilde{\tau}^{-1}(A) = \{x \in I \mid \tilde{\tau}(x) \cap A \neq \emptyset\}\). Observe that \(\tilde{\tau}\) is a closed map, i.e., if \(A\) is a closed subset of \(I\), then \(\tilde{\tau}(A)\) is closed, since \(\tilde{\tau}(A) = \cup_{x \in \tau_i(A)}\).

The generalized orbit of \(C\) is the smallest subset \(I_1\) of \(I\) containing \(C\) and closed under \(\tilde{\tau}\) and \(\tilde{\tau}^{-1}\). This is the same as the smallest subset of \(I\) closed under \(\tau_i\) and \(\tau_i^{-1}\) for \(1 \leq i \leq n\). We define \(I_0 = I \setminus I_1\). Next we describe the space resulting from disconnecting \(I\) at points in \(I_1\). (The term “disconnecting” we have borrowed from Spielberg \[31\].)

**Definition 2.1.** Let \(I = [0, 1]\), and let \(I_0, I_1\) be as above. The disconnection of \(I\) at points in \(I_1\) is the totally ordered set \(X\) which consists of a copy of \(I\) with the
usual ordering, but with each point \( x \in I_1 \setminus \{0, 1\} \) replaced by two points \( x^- < x^+ \).

We equip \( X \) with the order topology, and define the \textit{collapse map} \( \pi : X \to I \) by \( \pi(x^\pm) = x \) for \( x \in I_1 \), and \( \pi(x) = x \) for \( x \in I_0 \). We write \( X_1 = \pi^{-1}(I_1) \), and \( X_0 = \pi^{-1}(I_0) = X \setminus X_1 \).

If \( x \in I_1 \), then \( x^- \) is the smallest point in \( \pi^{-1}(x) \), and \( x^+ \) is the largest. For \( x \in I_0 \), it will be convenient to define \( x^- = x^+ = \hat{x} \), where \( \hat{x} \) is the unique preimage under \( \pi \) of \( x \). For any pair \( a, b \in X \), we write \([a, b]_X \) for the order interval \( \{x \in X \mid a \leq x \leq b\} \). More generally, if \( J \) is any interval in \( \mathbb{R} \), then we write \( J_X \) instead of \( J \cap X \).

**Proposition 2.2.** Let \( X \) be the disconnection of \( I \) at points in \( I_1 \), and \( \pi : X \to I \) the collapse map. Then \( X \) is homeomorphic to a compact subset of \( \mathbb{R} \), and

1. \( \pi \) is continuous and order preserving.
2. \( I_0 \) is dense in \( I \), and \( X_0 \) is dense in \( X \).
3. \( \pi|_{X_0} \) is a homeomorphism from \( X_0 \) onto \( I_0 \).
4. \( X \) has no isolated points.
5. If \( a, b \in I_1 \), then \([a^+, b^-]_X \) is clopen in \( X \), and every clopen subset of \( X \) is a finite disjoint union of such order intervals.

**Proof.** Fix a listing of the elements of \( I_1 \), say \( I_1 = \{x_1, x_2, \ldots\} \). Define \( \hat{I} \) to be \( I \) with each point \( x_k \) in \( I_1 \setminus \{0, 1\} \) replaced by a pair of points \( x_k^- < x_k^+ \) and a gap of length \( 2^{-k} \) inserted between these points. Then \( \hat{I} \) is a compact subset of \( \mathbb{R} \), and the order topology on \( \hat{I} \) coincides with the topology inherited from \( \mathbb{R} \). Clearly \( \hat{I} \) is order isomorphic to the set \( X \) in Definition 2.1. (Hereafter we will identify \( X \) with \( \hat{I} \).)

1. The inverse image of each open interval under \( \pi \) is an open order interval in \( X \), so \( \pi \) is continuous. It follows at once from the definitions of \( \pi \), and of the order on \( X \), that \( \pi \) is order preserving.

2. The complement of any finite subset of \( I \) is dense in \( I \). By the Baire category theorem, since \( I_1 \) is countable, then \( I_0 \) is dense in \( I \), and this implies density of \( X_0 \) in \( X \).

3. To prove that \( \pi \) restricted to \( X_0 \) is a homeomorphism, let \( B \) be a closed subset of \( X \). We will show \( \pi(B \cap X_0) = \pi(B) \cap I_0 \). If \( x \in \pi(B) \cap I_0 \), then \( x \) has a preimage in \( B \), and since \( x \in I_0 \), by definition of \( X_0 \), that preimage is also in \( X_0 \). Thus \( \pi(B) \cap I_0 \subset \pi(B \cap X_0) \), and the opposite containment is clear. Hence \( \pi(B \cap X_0) \) is closed in \( I_0 \), so \( \pi|_{X_0} \) is a continuous, bijective, closed map from \( X_0 \) onto \( I_0 \), and thus is a homeomorphism.

4. Since \( I_0 \) is infinite and dense in \( I \), no point of \( I_0 \) is isolated in \( I_0 \), so by 3 no point of \( X_0 \) is isolated in \( X_0 \). By density of \( X_0 \) in \( X \), no point of \( X \) is isolated.

5. Observe that if \( a \in I_1 \setminus \{1\} \), then \( a^+ \) is not a limit from the left, and if \( b \in I_1 \setminus \{0\} \), then \( b^- \) is not a limit from the right. Thus for \( a, b \in I_1 \) with \( a < b \), the set \([a^+, b^-]_X \) is clopen. Now let \( E \) be any clopen subset of \( X \), and let \( x \in E \). Since \( E \) is clopen, for each point \( x \) in \( E \) we can find an open order interval containing \( x \) and contained in \( E \). The union of these intervals forms an open cover of the compact set \( E \), so there is a finite subcover. The union of overlapping open order intervals is again an open order interval, so the intervals in this subcover can be expressed as a finite disjoint union of open order intervals. By construction, not only do these cover \( E \), but they are contained in \( E \), so \( E \) is equal to their disjoint union. Since each of these intervals is open, and each is the complement (in \( E \)) of
the union of the others, each is also closed. Thus $E$ is a disjoint union of a finite collection of clopen order intervals.

We will be done if we show that for each clopen order interval $[c, d]_X$, there exist $a, b \in X_1$ with $c = a^+$ and $d = b^-$. By density of $I_0$ in $I$, each point of $I_0$ is a limit from both the left and right of sequences from $I_0$, so each point of $X_0$ is a limit from both the left and right of sequences from $X_0$. Since $[c, d]_X$ is open, $c$ cannot be a limit from the left, and $d$ cannot be a limit from the right, so neither $c$ nor $d$ is in $X_0$. If $a \in I_1 \setminus \{0\}$ and $c = a^-$, then $c$ would be a limit, which is impossible. Thus $c = a^+$ for some $a \in I_1$, and similarly $d = b^-$.

We now turn to constructing a local homeomorphism $\sigma : X \to X$. Recall that if $a_0 < a_1 < \cdots < a_n$ is the partition associated with a piecewise monotonic map $\tau$, we denote by $I_i$ the endpoints of the intervals of monotonicity, $I_1$ the generalized orbit of $C$, and $X$ the disconnection of $I$ at the points of $I_1$.

**Theorem 2.3.** Let $\tau : I \to I$ be a piecewise monotonic map, $C = \{a_0, a_1, \ldots, a_n\}$ the endpoints of the intervals of monotonicity, $I_1$ the generalized orbit of $C$, and $X$ the disconnection of $I$ at the points of $I_1$.

1. The sets $\hat{J}_i = [a_{i-1}^+, a_i^-]_X$ for $i = 1, \ldots, n$ form a partition of $X$ into clopen sets.
2. There is a unique continuous map $\sigma : X \to X$ such that $\pi \circ \sigma = \tau \circ \pi$ on $X_0$.
3. For $1 \leq i \leq n$, $\sigma$ is a monotone homeomorphism from $\hat{J}_i$ onto the clopen order interval with endpoints $\sigma(a_{i-1}^+)$ and $\sigma(a_i^-)$.
4. For $1 \leq i \leq n$, $\pi \circ \sigma = \tau_i \circ \pi$ on $\hat{J}_i$.

**Proof.** For $1 \leq i \leq n$, let $J_i = [a_{i-1}, a_i]$, and define $\hat{J}_i$ as in (1) above. By Proposition 2.2 the order intervals $\hat{J}_1, \ldots, \hat{J}_n$ are clopen and form a partition of $X$.

Now we define $\sigma$ on $\hat{J}_1, \ldots, \hat{J}_n$. Fix $i$, and recall that $\tau_i$ is strictly monotonic. We will assume that $\tau_i$ is increasing; the decreasing case is similar. Then $\tau_i$ is a homeomorphism from $J_i$ onto $[\tau_i(a_{i-1}), \tau_i(a_i)]$.

Since $\pi(\hat{J}_i) = J_i$, each point in $\hat{J}_i$ has the form $x^+$ or $x^-$ for some $x \in J_i$. If $y \in \hat{J}_i$ and $y = x^\pm$, then we define $\sigma(y) = \sigma(x^\pm) = \tau_i(x)^\pm$. This is well defined, since if $y = x^+ = x^-$, then $x \in I_0$, so $\tau_i(x) \in I_0$, and thus $\tau_i(x)^+ = \tau_i(x)^-$. It follows that $\sigma$ is an order isomorphism from $\hat{J}_i$ onto $[\tau_i(a_{i-1})^+, \tau_i(a_i)^-]_X$. Since the topology on compact subsets of $\mathbb{R}$ coincides with the order topology, $\sigma$ is an increasing homeomorphism from $\hat{J}_i$ onto $\sigma(\hat{J}_i)$, so (3) holds. Since $\tau_i(I_1) \subset I_1$, then by Proposition 2.2 $\sigma(\hat{J}_i) = [\tau_i(a_{i-1})^+, \tau_i(a_i)^-]_X$ is clopen. Since each order interval $\hat{J}_i$ is clopen, then $\sigma$ is continuous on all of $X$. From the definition of $\sigma$, $\pi \circ \sigma = \tau \circ \pi$ on $X_0$, and so by continuity of $\sigma$ and density of $X_0$, (2) follows. Now (1) is immediate.

From the proof above, if $\tau$ is increasing on the interval $J_i = [a_{i-1}, a_i]$, and if $c, d \in J_i \cap I_1$ with $c < d$, then

(2.1) $\sigma([c^+, d^-]_X) = [\tau_i(c)^+, \tau_i(d)^-]_X$, while if $\tau$ decreases on $J_i$ then

(2.2) $\sigma([c^+, d^-]_X) = [\tau_i(d)^+, \tau_i(c)^-]_X$.

**Corollary 2.4.** $\pi|_{X_0}$ is a conjugacy from $(X_0, \sigma)$ to $(I_0, \tau)$.
Proof. By Proposition 2.2, }\pi|_{X_0}\text{ is a homeomorphism onto } I_0, \text{ and by Theorem } 2.3, \pi \text{ intertwines } (X_0, \sigma) \text{ and } (I_0, \tau). \tag*{\Box}

The map }\sigma\text{ in Theorem } 2.3\text{ is a local homeomorphism, i.e., it is an open map, and each point admits an open neighborhood on which } \sigma \text{ is a homeomorphism.

Definition 2.5. We will call the map }\sigma : X \to X\text{ in Theorem } 2.3\text{ the local homeomorphism associated with } \tau.\n
Example 2.6. Let }\tau : [0, 1] \to [0, 1]\text{ be the full tent map given by } \tau(x) = 1 - |2x - 1|. \text{ Here the set } C \text{ of endpoints of intervals of monotonicity is } \{0, 1/2, 1\}. \text{ This set is invariant under } \tau, \text{ so the generalized orbit } I_1 = \bigcup_{n \geq 0} \tau^{-n}(C), \text{ which is just the set of dyadic rationals. The order intervals } J_1, J_2 \text{ defined in Theorem } 2.3\text{ satisfy } \sigma(J_1) = \sigma(J_2) = X. \text{ For } x \in X, \text{ let } S(x) = s_0s_1s_2\ldots, \text{ where } s_n = i \text{ if } \sigma^nx \in J_i. \text{ Then } S \text{ is a conjugacy from } (X, \sigma) \text{ onto the full (one-sided) 2-shift.}

For a general piecewise monotonic map }\tau : I \to I, \text{ the associated local homeomorphism } \sigma : X \to X\text{ will not be a shift of finite type, nor even a subshift. For example, for a logistic map } \tau(x) = kx(1-x) \text{ with an attractive fixed point, } X \text{ will contain non-trivial connected components.} \n
In the remainder of this section, we will see that properties of a piecewise monotonic map }\tau : I \to I\text{ and the associated local homeomorphism } \sigma \text{ are closely related. \textbf{We illustrate this relationship for transitivity.}}

Definition 2.7. If } X \text{ is any topological space, and } f : X \to X\text{ is a continuous map, then } f \text{ is } \textit{transitive} \text{ if for each pair } U, V \text{ of non-empty open sets, there exists } n \geq 0 \text{ such that } f^n(U) \cap V \neq \emptyset. \text{ We say } f \text{ is } \textit{strongly transitive} \text{ if for every non-empty open set } U, \text{ there exists } n \text{ such that } \bigcup_{k=0}^n f^k(U) = X.\n
Definition 2.8. If }\tau : I \to I\text{ is piecewise monotonic, we view } \tau \text{ as undefined at the points } C \text{ of endpoints of intervals of monotonicity, and say } \tau \text{ is transitive if for each pair } U, V \text{ of non-empty open sets, there exists } n \geq 0 \text{ such that } \tau^n(U) \cap V \neq \emptyset. \text{ We say } \tau \text{ is } \textit{strongly transitive} \text{ if for every non-empty open set } U, \text{ there exists } n \text{ such that } \bigcup_{k=0}^n \hat{\tau}^k(U) = I. \text{ (Recall that } \hat{\tau} \text{ denotes the (possibly multivalued) function whose value at each point } x \text{ is given by the left and right hand limits of } \tau \text{ at } x.)\n
It is well known that for } X \text{ compact metric with no isolated points, and } f : X \to X\text{ continuous, transitivity is equivalent to the existence of a point with a dense orbit. The same equivalence holds if } \tau : I \to I\text{ is piecewise monotonic, and is viewed as undefined on the set } C \text{ of endpoints of intervals of monotonicity. (Apply the standard Baire category argument to show that transitivity implies the existence of a dense orbit, cf. e.g. 2.3 Thm. 5.9)).} \n
If }\tau : I \to I\text{ is piecewise monotonic and continuous, then any dense orbit must eventually stay out of } C. \text{ It follows that the definitions of transitivity in Definitions 2.7 and 2.8 are consistent. In addition, in this case } \tau = \hat{\tau}, \text{ so the definitions of strong transitivity also are consistent.} \n
For general compact metric spaces } X, \text{ transitive maps need not be strongly transitive. For example, the (two-sided) shift on the space of all bi-infinite sequences of two symbols is transitive in the sense of Definition 2.7 but is not strongly transitive, since the complement of a fixed point is open and invariant. However, the next proposition shows that every piecewise monotonic transitive map is strongly transitive. (For continuous piecewise monotonic maps, this follows from 2.6 Thm.}
Proposition 2.9. For a piecewise monotonic map \( \tau : I \to I \), with associated local homeomorphism \( \sigma : X \to X \), the following are equivalent.

1. \( \tau \) is transitive.
2. \( \tau \) is strongly transitive.
3. \( \sigma \) is transitive.
4. \( \sigma \) is strongly transitive.

Proof. Assume \( \tau \) is transitive. View \( \tau \) as undefined on the set of endpoints of intervals of monotonicity. Let \( V \) be an open interval. Choose an open interval \( W \) such that \( W \subset V \). By [4, Prop. 2.6], or [15, Corollary on p. 382], there exists an \( N \) such that \( \bigcup_0^N \tau^k(W) = \bigcup_0^N \sigma^k(W) \). The right side is a finite union of open intervals. Since \( \tau \) is transitive, the left side is dense, and thus \( I \setminus \bigcup_0^N \tau^k(W) \) is finite. On the other hand, for each \( k \), \( \tau^k(W) \subset \tilde{\tau}^k(W) \subset \tilde{\sigma}^k(V) \). Since \( \tilde{\tau} \) is a closed map, it follows that \( \bigcup_0^N \tilde{\tau}^k(W) = I \), so \( \bigcup_0^N \tilde{\sigma}^k(V) = I \). Thus \( \tau \) is strongly transitive.

Strong transitivity of \( \tau \) is equivalent to strong transitivity of \( \tau|_{I_0} \). This in turn is equivalent to strong transitivity of \( \sigma|_{X_0} \), and then to strong transitivity of \( \sigma \) on \( X \). Finally, if \( \sigma \) is transitive on \( X \), it is transitive on \( X_0 \), so \( \tau \) is transitive on \( I_0 \), which in turn implies transitivity of \( \tau \) on \( I \). \( \square \)

3. Dimension groups

In this section we will associate a dimension group \( DG(\tau) \) with each piecewise monotonic map \( \tau \). Our method will be to define a dimension group \( G_{\sigma} \), where \( \sigma \) is the local homeomorphism associated with \( \tau \), and then define \( DG(\tau) = G_{\sigma} \). We start by defining a class of functions that includes the local homeomorphisms associated with piecewise monotonic maps, but also includes any local homeomorphism of a zero dimensional metric space.

Definition 3.1. Let \( X \) be a topological space. A map \( \sigma : X \to X \) is a piecewise homeomorphism if \( \sigma \) is continuous and open, and \( X \) admits a finite partition into clopen sets \( X_1, X_2, \ldots, X_n \) such that \( \sigma \) is a homeomorphism from \( X_i \) onto \( \sigma(X_i) \) for \( i = 1, \ldots, n \).

If \( \tau : I \to I \) is piecewise monotonic, and \( \sigma : X \to X \) is the associated local homeomorphism, then \( \sigma \) is a piecewise homeomorphism, cf. Theorem 2.3. Every local homeomorphism \( \sigma \) on a compact zero dimensional metric space \( X \) is a piecewise homeomorphism. In fact, each open neighborhood of a point in a zero dimensional space contains a clopen neighborhood of that point, so there is a cover of \( X \) by clopen subsets on which \( \sigma \) is injective. Since \( X \) is compact, we can take a finite subcover, and the resulting partition that arises from all intersections of these subsets and their complements is the desired partition. Note that a composition of piecewise homeomorphisms is again a piecewise homeomorphism.

Hofbauer [15] and Keller [19] have studied the dynamics of maps that are piecewise invertible, i.e., that meet the requirements of a piecewise homeomorphism except for the requirement that the map be open.

We begin by defining \( G_{\sigma} \) as an ordered abelian group; later we will show \( G_{\sigma} \) is in fact a dimension group. Recall that an abelian group \( G \) is ordered if there is a
subset $G^+$ such that $G = G^+ - G^+$, $G^+ \cap (-G^+) = \{0\}$ and $G^+ + G^+ \subseteq G^+$. Then for $x, y \in G$ with $y - x \in G^+$, we write $x \leq y$. We write $nx$ for the sum of $n$ copies of $x$. An element $u$ of an ordered abelian group $G$ is an order unit if for each $x$ in $G$ there is a positive integer $n$ such that $-nu \leq x \leq nu$.

The motivating idea for $G_{\sigma}$ is to build a group out of equivalence classes of clopen subsets of $X$. As discussed in the introduction, this idea originated with Krieger [21], and was extended by Boyle-Fiebig-Fiebig [1]. In [1] a dimension group is associated with any surjective local homeomorphism on a zero dimensional compact metric space. Our context is a slight generalization of that in [1], namely, piecewise homeomorphisms on an arbitrary compact metric space.

In what follows, a key role will be played by the transfer map. We will use this map both to define the dimension group for a piecewise homeomorphism, and to provide a key tool in computing this group.

**Definition 3.2.** Let $X, Y$ be compact metric spaces. If $\sigma : Y \to X$ is any map which is finitely-many-to-one, the transfer map $L_{\sigma}$ associated with $\sigma$ is defined by

\[(L_{\sigma} f)(x) = \sum_{\sigma(y) = x} f(y)\]

for each $f : X \to \mathbb{C}$. (We will usually have $Y = X$.) We will write $L$ instead of $L_{\sigma}$ when the map $\sigma$ intended is clear from the context.

We note some simple properties of $L$, which are immediate consequences of the definition. If $f \geq 0$, then $L f \geq 0$. If $f \geq 0$ and $L f = 0$, then $f = 0$. If $\sigma$ is injective on $E$, then

\[(L \chi_{E}) = \chi_{\sigma(E)}\].

If $\sigma : X \to X$ is a piecewise homeomorphism, then every function in $C(X, \mathbb{Z})$ can be written as a sum $\sum n_i \chi_{E_i}$, where $\sigma$ is injective on $E_i$, so $L$ maps $C(X, \mathbb{Z})$ into $C(X, \mathbb{Z})$. Observe that for $\sigma : X \to X$,

\[(L_{\sigma})^n = (L_{\sigma^n}) \quad \text{if} \quad X \text{ is a compact metric space, we will write } 1_X \text{ (or simply } 1) \text{ for the function constantly } 1 \text{ on } X.

**Definition 3.3.** Let $X$ be a compact metric space, and $\sigma : X \to X$ a piecewise homeomorphism. Write $L$ for $L_{\sigma}$. We define an equivalence relation on $C(X, \mathbb{Z})$ by $f \sim g$ if $L^n f = L^n g$ for some $n \geq 0$, and write $G_{\sigma}$ for the set of equivalence classes, and $G_{\sigma}^+ = \{[f] \mid f \geq 0\}$. We define addition on $G_{\sigma}$ by $[f] + [g] = [f + g]$, and we order $G_{\sigma}$ by $[f] \leq [g]$ if $|g - f| \in G_{\sigma}^+$. We call $[1_X]$ the distinguished order unit of $G_{\sigma}$.

It is easily verified that $G_{\sigma}$ is an ordered abelian group. We will show $G_{\sigma}$ is a dimension group, after developing some properties of the ordering on $G_{\sigma}$. When $X$ is a zero dimensional space and $\sigma : X \to X$ is a local homeomorphism, then $G_{\sigma}$ is the same as the “images group” defined by Boyle-Fiebig-Fiebig in [1]. Our definition is different from theirs, but equivalent, as observed in [1 Rmk. 9.4].

**Lemma 3.4.** Let $X$ be a compact metric space and $\sigma : X \to X$ a piecewise homeomorphism. Then for each clopen subset $F$ of $\sigma(X)$, there exists a clopen subset $E$ of $X$ such that $\sigma$ is injective on $E$ and $\sigma(E) = F$. 

Proof. Since $\sigma$ is a piecewise homeomorphism, there exists a partition $G_1, G_2, \ldots, G_n$ of $X$ into clopen sets on which $\sigma$ is injective. If $F \subset \sigma(G_i)$ for some $i$, then the set $E = G_i \cap \sigma^{-1}(F)$ has the desired properties. Otherwise, let $F_1, F_2, \ldots, F_k$ be the partition of $F$ generated by the sets $\{F \cap \sigma(G_i) \mid 1 \leq i \leq n\}$. For each $k$, choose a clopen set $E_k$ such that $\sigma$ is injective on $E_k$ and $\sigma(E_k) = F_k$. Then $\sigma$ is injective on $E = E_1 \cup E_2 \cup \cdots E_k$, and $\sigma(E) = F$. \hfill $\Box$

If $f \in C(X, \mathbb{Z})$, we define the support of $f$ to be the set of $x$ in $X$ where $f$ is nonzero, and denote this set by $\text{supp } f$. Note that by the definition of $L$ we have

$$\text{supp } Lf \subset \sigma(\text{supp } f),$$

with equality if $f \geq 0$. In particular, since $L^n\sigma = L^{n\sigma}$, we have

$$\text{supp } L^n f \subset \sigma^n(X).$$

A result similar to the following can be found in [1] Lemma 2.8.

**Lemma 3.5.** Let $X$ be a compact metric space, and $\sigma : X \to X$ a piecewise homeomorphism. If $f \in C(X, \mathbb{Z})$, and the support of $f$ is contained in $\sigma^n(X)$, then there exists $f_0 \in C(X, \mathbb{Z})$ such that $L^n f_0 = f$. If $f \geq 0$, then $f_0$ can be chosen so that $f_0 \geq 0$.

**Proof.** Let $f \in C(X, \mathbb{Z})$, with $\text{supp } f \subset \sigma^n(X)$. Write $f = \sum_{i=1}^{p} n_i \chi_{E_i}$, with $E_1, \ldots, E_p$ disjoint, and $n_1, \ldots, n_p \in \mathbb{Z}$. We may assume that for each index $i$, $n_i \neq 0$. Then each $E_i$ is contained in the support of $f$, and thus is contained in $\sigma^n(X)$. Applying Lemma 3.4 to $\sigma^n$, for each index $i$ we can find a clopen set $F_i$ such that $\sigma^n$ is injective on $F_i$ and $\sigma^n(F_i) = E_i$. Let $f_0 = \sum_{i=1}^{p} n_i \chi_{F_i}$. Then $L^n f_0 = \sum_{i=1}^{p} n_i \chi_{\sigma^n(F_i)} = \sum_{i=1}^{p} n_i \chi_{E_i} = f$. If $f \geq 0$, we can arrange $n_i > 0$ for all $i$, so $f_0 \geq 0$. \hfill $\Box$

**Lemma 3.6.** Let $X$ be a compact metric space, and $\sigma : X \to X$ a piecewise homeomorphism. In $G_\sigma$, $[f] \leq [g]$ iff $L^n f \leq L^n g$ for some $n \geq 0$.

**Proof.** It suffices to show $[f] \geq [0]$ iff $L^n f \geq 0$ for some $n \geq 0$. If $[f] \geq [0]$, then by definition there is $h \geq 0$ such that $f \sim h$, and therefore $L^n f = L^n h \geq 0$ for some $n \geq 0$. Conversely, fix $n$ and suppose $L^n f \geq 0$. By [3.5] and Lemma 3.6 there exists $h \geq 0$ such that $L^n f = L^n h$. Then $f \sim h$, so $[f] \geq [0]$. \hfill $\Box$

**Definition 3.7.** $L_* : G_\sigma \to G_\sigma$ is defined by $L_* [f] = [Lf]$.

This is an injective homomorphism. If $\sigma$ is surjective, by Lemma 3.4 $L_*$ is surjective, so $L_*$ is surjective, and thus is an automorphism of $G_\sigma$. Note, however, that $L_*$ is usually not unital.

If $\sigma$ is injective on a clopen set $E$, then by

$$L_* [\chi_E] = [\chi_{\sigma(E)}].$$

**Notation.** Let $G_1 \overset{T_1}{\to} G_2 \overset{T_2}{\to} G_3 \cdots$ be a sequence of ordered abelian groups with positive connecting homomorphisms. We review the construction of the inductive limit of this sequence. Let $G_\infty$ be the set of sequences $(g_1, g_2, \ldots)$ such that $g_i \in G_i$ for each $i$, and such that there exists $N$ such that $T_n g_n = g_{n+1}$ for all $n \geq N$. Make $G_\infty$ into a group with coordinate wise addition. Consider two sequences $(g_1), (h_1)$ to be equivalent if they eventually agree, i.e., if there exists $N$ such that $g_i = h_i$ for $i \geq N$. The quotient group $G$ is then an abelian group. Denote equivalence classes by square brackets. Define $G^+$ to be the set of equivalence classes of sequences that
are eventually positive, and order $G$ by $g \leq h$ if $h - g \in G^+$. Then $G$ is the inductive limit in the category of ordered abelian groups. If $G_1, G_2, \ldots$ are identical, and $T_1, T_2, \ldots$ are the same map, we call $G$ the \textit{stationary} inductive limit with connecting maps $T_1 : G_1 \to G_1$.

**Lemma 3.8.** Let $X$ be a compact metric space, and $\sigma : X \to X$ a piecewise homeomorphism. Then $G_\sigma$ is isomorphic as an ordered group to the inductive limit

$$\vdots \rightarrow C(X, Z) \xrightarrow{L} L(C(X, Z)) \xrightarrow{L} L^2 C(X, Z) \xrightarrow{L} \cdots \; .$$

and this isomorphism carries the map $L_*$ to the shift map $[(g_1, g_2, \ldots)] \mapsto [(g_2, g_3, \ldots)]$.

\textit{Proof.} Let $G$ be the inductive limit of this sequence. Every element of $G$ has the form $[(0_0, 0_1, \ldots, 0_{n-1}, L^n g, L^{n+1} g, \ldots)] = [(g, Lg, \ldots)]$, where $0_i$ denotes a zero in the $i$-th position. The map $\pi : G \to G_\sigma$ given by $\pi([(g, Lg, \ldots)]) = [g]$ is an order isomorphism of $G$ onto $G_\sigma$, and carries $L_*$ to the shift map. \qed

If $\sigma : X \to X$ is surjective, then $L : C(X, Z) \to C(X, Z)$ is also surjective (Lemma 3.8). Hence for surjective $\sigma$, the dimension group $G_\sigma$ is isomorphic to the inductive limit of the sequence

$$\vdots \rightarrow C(X, Z) \xrightarrow{L} C(X, Z) \xrightarrow{L} C(X, Z) \xrightarrow{L} \cdots \; .$$

**Lemma 3.9.** Let $X$ be a compact metric space, and $\sigma : X \to X$ a piecewise homeomorphism. For each $n \geq 0$, $L^n C(X, Z)$ (with the order inherited from $C(X, Z)$) is isomorphic as an ordered group to $C(\sigma^n (X), Z)$.

\textit{Proof.} By 3.5, $\text{supp} \, L^n f \subset \sigma^n (X)$, so the map $f \mapsto f|_{\sigma^n (X)}$ is an order isomorphism from $L^n C(X, Z)$ into $C(\sigma^n (X), Z)$. To prove this map is surjective, let $g \in C(\sigma^n (X), Z)$. Extend $g$ to be zero on $X \setminus \sigma^n (X)$, so that $g$ is in $C(X, Z)$ with support in $\sigma^n (X)$. There exists $f \in C(X, Z)$ with $L^n f = g$ by Lemma 3.5 Then $L^n f|_{\sigma^n X} = g$, so $f \mapsto f|_{\sigma^n X}$ is surjective. \qed

**Definition 3.10.** An ordered abelian group $G$ has the \textit{Riesz decomposition property} if whenever $x_1, x_2, y_1, y_2 \in G$ with $x_i \leq y_j$ for $i, j = 1, 2$, then there exists $z \in G$ with $x_i \leq z \leq y_j$ for $i, j = 1, 2$. $G$ is \textit{unperforated} if $ng \geq 0$ for some $n > 0$ implies $g \geq 0$. A \textit{dimension group} is a countable ordered abelian group $G$ which is unperforated and which has the Riesz decomposition property.

A more common definition is that a dimension group is the inductive limit of a sequence of ordered groups $Z^n$ (where $Z^n$ is given the usual coordinate-wise order.) By a result of Effros, Handelman, and Shen [11], this is equivalent to the definition we have given. Two standard references on dimension groups are the books of Goodearl [13] and of Effros [10].

If $G$ is a dimension group with a distinguished order unit $u$, then we refer to the pair $(G, u)$ as a \textit{unital dimension group}. A homomorphism between unital dimension groups $(G_1, u_1), (G_2, u_2)$ is \textit{unital} if it takes $u_1$ to $u_2$.

Below $C(X, Z)$ is viewed as an ordered abelian group with the usual addition and ordering of functions.

**Lemma 3.11.** If $X$ is a compact metric space, then $C(X, Z)$ is a dimension group, with order unit $1_X$. 

Lemma 3.8, \( G \) and the Riesz decomposition property) are preserved by inductive limits, so by Lemma 3.9. Each of the properties defining a dimension group (being unperforated, Definition 4.1. If \( f \) in \( C(X) \) is countable, any two characteristic functions of clopen sets are a distance 2 apart in \( X \). If \( \sigma \) is surjective, \( \sigma \) is equivalent to surjectivity of \( \tau \), and \( \tau \) is eventually surjective then we instead write \( DG_\sigma \) as the dimension group. For any \( f \in C(X) \), \( \sigma(X) \) is countable (cf. Lemma 3.11), and since \( \sigma \) is a dimension group, \( \sigma(X) \) is unperforated, \( \sigma(X) \) is a quotient of \( \sigma^n(X) \), cf. Lemma 3.8. Each of the properties defining a dimension group (being unperforated, and the Riesz decomposition property) are preserved by inductive limits, so by Lemma 3.8 \( G_\sigma \) is a dimension group. For any \( f \in C(X) \) there exists \( k \) such that \(-k1_X \leq f \leq k1_X \), so \([1_X] \) is an order unit. □

Corollary 3.12. If \( X \) is a compact metric space, and \( \sigma : X \to X \) a piecewise homeomorphism, then \( G_\sigma \) is a dimension group, with distinguished order unit \([1_X] \).

Proof. Since \( C(X) \) is countable (cf. Lemma 3.11), and since \( G_\sigma \) is a quotient of \( C(X) \), \( G_\sigma \) is countable. With the order inherited from \( C(X) \), \( L^\infty C(X,Z) \) is a dimension group, since it is isomorphic to the dimension group \( C(\sigma^n(X),Z) \), cf. Lemma 3.8. Each of the properties defining a dimension group (being unperforated, and the Riesz decomposition property) are preserved by inductive limits, so by Lemma 3.8 \( G_\sigma \) is a dimension group. For any \( f \in C(X,Z) \) there exists \( k \) such that \(-k1_X \leq f \leq k1_X \), so \([1_X] \) is an order unit. □

Definition 3.13. If \( \tau : I \to I \) is piecewise monotonic, and \( \sigma : X \to X \) is the associated local homeomorphism, then \( DG(\tau) \) is defined to be the dimension group \( G_\sigma \). Here we assume the partition \( C \) associated with \( \tau \) is the maximal one; if not, then we instead write \( DG(\tau,C) \) for this dimension group.

4. Reduction to surjective maps

In this section, we will see that we can often reduce the computation of the dimension group \( DG(\tau) \) to the case where \( \tau \) is surjective.

Definition 4.1. If \( X \) is a metric space and \( \sigma : X \to X \) is continuous, we say \( \sigma \) is eventually surjective if \( \sigma^{n+1}(X) = \sigma^n(X) \) for some \( n \geq 0 \). In this case we refer to \( \sigma^n(X) \) as the eventual range of \( \sigma \). If \( \tau : I \to I \) is piecewise monotonic but not continuous, we say \( \tau \) is eventually surjective if \( \tau|_{I_0} \) is eventually surjective, and \( \tau \) is surjective if \( \hat{\tau} \) is surjective (i.e., if \( \hat{\tau}(I) = I \)).

If \( \tau \) is piecewise monotonic and continuous, it is straightforward to check that the two definitions of eventual surjectivity in Definition 4.1 that are applicable are consistent.

Lemma 4.2. If \( \tau : I \to I \) is piecewise monotonic, and \( \sigma : X \to X \) is the associated local homeomorphism, then \( \sigma \) is essentially surjective iff \( \tau \) is essentially surjective, and \( \sigma \) is surjective iff \( \tau \) is surjective.

Proof. Since \( I_0 \) is dense in \( I \), and \( \hat{\tau} \) is a closed map, surjectivity of \( \tau \) is equivalent to surjectivity of \( \tau|_{I_0} \). By density of \( X_0 \) in \( X \) and continuity of \( \sigma \), surjectivity of \( \sigma \) is equivalent to surjectivity of \( \sigma|_{X_0} \). By the conjugacy of \( (I_0,\tau) \) and \( (X_0,\sigma) \), surjectivity of \( \sigma \) is equivalent to surjectivity of \( \sigma \).

Similarly, \( \sigma^{n+1}(I_0) = \sigma^n(I_0) \) is equivalent to \( \sigma^{n+1}(X_0) = \sigma^n(X_0) \), which in turn is equivalent to \( \sigma^{n+1}X = \sigma^nX \), so eventual surjectivity of \( \sigma \) is equivalent to eventual surjectivity of \( \tau \). □
An alternative definition for eventual surjectivity of discontinuous \( \tau \) might be that \( \hat{\tau}^{n+1}(I) = \hat{\tau}^n(I) \) for some \( n \geq 0 \). This implies \( \tau^{n+1}(I_0) = \tau^n(I_0) \), so \( \tau \) is eventually surjective in the sense of Definition 3.7. The converse is also true, but is a little tedious to prove when \( \tau \) is discontinuous, and won’t be needed in the sequel, so we have chosen to define eventual surjectivity of \( \tau \) as in Definition 4.1 instead.

**Proposition 4.3.** If \( X \) is a compact metric space and \( \sigma : X \to X \) is an eventually surjective piecewise homeomorphism with eventual range \( Y \), then \( G_\sigma \) is isomorphic to the stationary inductive limit

\[
(C(Y, \mathbb{Z}) \xrightarrow{L} C(Y, \mathbb{Z}) \xrightarrow{L} C(Y, \mathbb{Z}) \xrightarrow{L} \cdots).
\]

**Proof.** This follows from Lemmas 3.8 and 3.9. \( \square \)

**Example 4.4.** If \( \tau : [0, 1] \to [0, 1] \) is defined by \( \tau(x) = kx(1 - x) \), and \( 2 \leq k < 4 \), then \( \tau([0, 1]) = \tau([0, 1/2]) = [0, k/4] \supset [0, 1/2] \), so \( \tau^2([0, 1]) = \tau([0, 1]) \). Thus \( \tau \) is eventually surjective, but is not surjective. By Lemma 4.2 the associated piecewise homeomorphism \( \sigma : X \to X \) is also eventually surjective but not surjective. On the other hand, if \( 0 \leq k < 2 \), then the sets \( \tau^n([0, 1]) \) are nested with intersection \( \{0\} \), so \( \sigma \) is not eventually surjective.

The following is [1, Thm. 4.3], adapted to our current context.

**Proposition 4.5.** Let \( X \) be a compact metric space, and \( \sigma : X \to X \) a piecewise homeomorphism. Then \( L_\sigma \) is a homomorphism and an order isomorphism of \( G_\sigma \) onto its image, and is surjective if \( \sigma \) is eventually surjective.

**Proof.** We observed after Definition 3.7 that \( L_\sigma \) is injective. Since \( L \) is a positive operator, it follows that \( L_\sigma \) is positive. If \( L_\sigma[f] \geq 0 \), then \( |L_\sigma f| \geq 0 \), which by definition implies \( L^{n+1} f \geq 0 \) for some \( n \geq 0 \), and thus \( [f] \geq 0 \). Hence \( L_\sigma \) is an order isomorphism onto its image.

Next we show \( L_\sigma \) is surjective if \( \sigma \) is eventually surjective. Suppose that \( \sigma^{n+1}(X) = \sigma^n(X) \), and let \( f \in C(X, \mathbb{Z}) \). Then the support of \( L^n f \) is contained in \( \sigma^n(X) = \sigma^{n+1}(X) \), so there exists \( g \in C(X, \mathbb{Z}) \) such that \( L^{n+1}g = L^n f \). It follows that \( L_\sigma[g] = [f] \).

Finally, suppose \( L_\sigma \) is surjective. Choose \( f \in C(X, \mathbb{Z}) \) such that \( L_\sigma[f] = [1] \). Then for some \( n \geq 0 \), \( L^{n+1} f = L^n f \). Thus \( \sigma^n X = \supp L^n f = \supp L^{n+1} f = \sigma^{n+1} X \), so \( \sigma^n X = \sigma^{n+1} X \). Thus \( \sigma \) is eventually surjective. \( \square \)

**Definition 4.6.** Let \( X \) be a compact metric space, and \( \sigma : X \to X \) a piecewise homeomorphism. \( \left(G_\sigma, G_\sigma^\sharp, (L_\sigma)_*\right) \) is the dimension triple associated with \( \sigma \).

Suppose \( X_1, X_2 \) are compact metric spaces, \( \sigma_i : X_i \to X_i \) for \( i = 1, 2 \) are piecewise homeomorphisms, and \( \psi : X_1 \to X_2 \) is a piecewise homeomorphism that intertwines \( \sigma_1 \) and \( \sigma_2 \), i.e., \( \psi \circ \sigma_1 = \sigma_2 \circ \psi \). Then \( L_\psi L_{\sigma_1} = L_{\psi \circ \sigma_1} = L_{\sigma_2 \circ \psi} = L_{\sigma_2} L_\psi \). It follows that \( L_\psi L_{\sigma_1} = L_{\sigma_1}^* L_\psi \). Thus the map \( (L_\psi)_* : G_{\sigma_1} \to G_{\sigma_2} \) defined by \( (L_\psi)_*[f] = [L_\psi f] \) is well defined, and is a positive homomorphism that intertwines \( (L_{\sigma_1})_* \) and \( (L_{\sigma_2})_* \).

**Proposition 4.7.** Let \( X \) be a compact metric space, and \( \sigma : X \to X \) an eventually surjective piecewise homeomorphism. Let \( Y \) be the eventual range of \( \sigma \), and choose \( N \) so that \( \sigma^N(X) = Y \). Then there is a group and order isomorphism \( \Phi \) from \( G_\sigma \) onto \( G_{\sigma|Y} \), which carries the automorphism \((L_\sigma)_*\) to the automorphism \((L_{\sigma|Y})_*\), and carries the distinguished order unit \( [1_X] \) to the order unit \([L^N 1]_\mid Y \).
Proof. Let $\psi : Y \to X$ be the inclusion map; note that $\psi$ intertwines $\sigma|_Y$ and $\sigma$. By the remarks preceding this proposition, $\Phi_0 = (L_\psi)_*$ is a positive homomorphism from $G_{\sigma|_Y}$ into $G_\sigma$, intertwining $(L_{\sigma|_Y})_*$ and $(L_\sigma)_*$. We will show that $\Phi_0$ is an order isomorphism of $G_{\sigma|_Y}$ onto $G_\sigma$.

Observe that $L_\psi f$ is the function that agrees with $f$ on $Y$, and is zero off $Y$; in particular, $L_\psi$ is 1-1 on $C(Y, \mathbb{Z})$, and $L_\psi f \geq 0$ iff $f \geq 0$.

To prove that $\Phi_0$ is surjective, let $f \in C(X, \mathbb{Z})$. Note that $\text{supp} L_\sigma^N f \subset \sigma^N(X) = Y$. Since $\sigma$ is surjective on $Y$, Lemma 4.9 (applied to $\sigma|_Y$) implies that there exists $g \in C(Y, \mathbb{Z})$ such that $L_\sigma^N g = (L_\sigma^N f)|_Y$. Applying $L_\psi$ to both sides gives $L_\sigma^N L_\psi g = L_\psi (L_\sigma^N f)|_Y = L_\psi^N f$ (since $\text{supp} L_\sigma^N f \subset Y$), so $\Phi_0([g]) = [L_\psi g] = [f]$. Thus $\Phi_0$ is surjective. Furthermore, if $[f] = [L_\psi g] \geq 0$, then there exists $n$ such that $L_\sigma^n L_\psi g \geq 0$. Then $L_\psi L_\sigma^n g \geq 0$, which implies $L_\sigma^n_* g \geq 0$. Thus $[g] \geq 0$, so $\Phi_0$ is an order isomorphism.

Finally, if $f = 1_X$ in the last paragraph, and $g \in C(Y, \mathbb{Z})$ is chosen so that $L_\sigma^n_* g = (L_\sigma^n 1_X)|_Y$, then $\Phi_0([g]) = [1_X]$. Thus $\Phi_0^{-1}[1_X] = (L_{\sigma|_Y})_*^N(\text{supp} L_\sigma^N 1_X)|_Y$. Since $\sigma|_Y$ is surjective, by Proposition 4.4, $(L_{\sigma|_Y})_*$ is an order automorphism of $C(Y, \mathbb{Z})$. Now the map $\Phi = (L_{\sigma|_Y})_0^N \Phi_0^{-1}$ satisfies the conclusion of the proposition.

Remark Suppose that $\tau : I \to I$ is continuous, and piecewise monotonic, and let $C$ be the set of endpoints of the associated maximal partition. If $\tau$ is eventually surjective, with eventual range $J$, then $\tau|_J$ is surjective, and we can reduce calculation of $DG(\tau)$ to finding $DG(\tau|_J, C')$ for a suitable partition $C'$ as follows.

Choose $N$ so that $J = \tau^N(X) = \tau^{N+1}(X)$. Since $\tau$ is continuous, then $J$ is a closed interval. Let $C' = (C \cap J) \cup \tau^N(C)$. (If desired, we may omit from $C'$ any points in $\tau^N(C)$ that are in the generalized orbit of $C \cap J$ under $\tau|_J$.) Associate with $\tau|_J$ the partition whose endpoints are the points in $C'$. Then the generalized orbit of $C'$ under $\tau|_J$ will be $I_1 \cap J$. If $\sigma : X \to X$ is the local homeomorphism associated with $\tau$, then $\sigma$ will be eventually surjective; let $Y$ be its eventual range. Then the local homeomorphism associated with $\tau|_J$ (with the partition $C'$) will be $\sigma|_Y$. Thus by Proposition 4.4, $DG(\tau) \cong DG(\tau|_J, C')$.

Example 4.8. Let $\tau$ be the map on $[0, 2]$ which has the values $\tau(0) = 0$, $\tau(1/2) = 1$, $\tau(1) = 0$, $\tau(k/2) = k < 1$, $\tau(2) = 0$, with $\tau$ linear between these points. The eventual range of $\tau$ is $J = \tau([0, 2]) = [0, 1]$. We take as a partition of $\tau|_J$ the non-maximal partition $C' = \{0, 1/2, k, 1\}$. Then $DG(\tau) \cong DG(\tau|_J, C')$.

Example 4.9. Let $\tau$ be the logistic map in Example 4.4 with $2 < k < 4$. The eventual range of $\tau$ is $J = \tau([0, 1]) = [0, 1]$. We can take as partition for $\tau|_J$ the maximal partition $C' = \{0, 1/2, 1\}$. Thus $DG(\tau) \cong DG(\tau|_J)$.

5. Simplicity of the dimension group

An order ideal in a dimension group $G$ is a subgroup $J$ such that $a, b \in J$ and $a \leq c \leq b$ implies $c \in J$. An ideal $J$ of a dimension group is positively generated if $J = J^+ - J^+$ where $J^+ = J \cap G^+$. A dimension group $G$ is simple if it has no positively generated order ideals other than $\{0\}$ and $G$. We will use the following equivalent condition: $G$ is simple iff every nonzero positive element of $G$ is an order unit. We now examine conditions that guarantee that $G_\sigma$ is simple.
Choose a non-empty open set \( I \) in \( X \). We first show that \( \sigma \) is exact.

\[
\sigma^n(V) = X.
\]

If \( \tau : I \to I \) is piecewise monotonic (but not necessarily continuous everywhere), then \( \tau \) is topologically exact if for every open set \( V \) there exists \( n \geq 0 \) such that \( \tilde{\tau}^n(V) = I \). (Recall that if \( \tau \) is continuous, then \( \tilde{\tau} = \tau \), so these two definitions of exactness are consistent.)

If \( X \) is a compact metric space, and \( \sigma : X \to X \) is topologically exact, then evidently \( \sigma \) is topologically mixing. The converse is not necessarily true, but is true for a broad class of piecewise monotonic maps. For a more thorough discussion of the relationship, see [30, Prop. 4.9].

Two examples of topologically exact maps are \( \beta \)-transformations, and tent maps with slopes \( \pm s \) with \( \sqrt{2} < s \leq 2 \), restricted to a suitable interval \([0,1]\).

**Lemma 5.2.** Let \( \tau : I \to I \) be piecewise monotonic, with associated local homeomorphism \( \sigma : X \to X \). Then \( \tau \) is topologically exact iff \( \sigma \) is topologically exact.

**Proof.** We first show that \( \tau \) is exact iff \( \tau|_{I_0} \) is exact. Assume \( \tau \) is exact, and let \( V \) be an open subset of \( I_0 \). Choose an open subset \( W \) of \( I \) such that \( W \cap I_0 = V \). By exactness of \( \tau \), there exists \( n \) such that \( \hat{\tau}^n(W) = I \). Since \( I_0 \) is forward and backward invariant under \( \hat{\tau} \), then \( \tau^n(W) = \tau^n(W \cap I_0) = I_0 \), which proves that \( \tau|_{I_0} \) is exact.

Conversely, suppose \( \tau|_{I_0} \) is exact, and let \( W \) be a non-empty open subset of \( I \). Choose a non-empty open set \( V \subset W \) such that \( \overline{V} \subset W \). Then \( V \cap I_0 \) is open in \( I_0 \), and is non-empty by density of \( I_0 \). Choose \( n \) so that \( \tau^n(V \cap I_0) = I_0 \). Then \( \hat{\tau}^n(V) \supset \tau^n(V \cap I_0) = I_0 \). Since \( \hat{\tau} \) is a closed map, then \( \hat{\tau}^n(V) \) is a closed subset of \( I \), containing the dense set \( I_0 \), so equals \( I \). Then \( \hat{\tau}^n(W) = I \), which proves that \( \hat{\tau} \) is exact. \( \square \)

Recall that a compact metric space is zero dimensional if there is a base of clopen sets, and this is equivalent to being totally disconnected, cf. [10].

**Theorem 5.3.** Let \( X \) be a compact metric space, and \( \sigma : X \to X \) a piecewise homeomorphism. Then \( G_\sigma \) is simple iff

1. \( \sigma \) is eventually surjective, and
2. for every compact open subset \( V \) of the eventual range \( Y \) of \( \sigma \), there exists \( n \geq 0 \) such that \( \sigma^n(Y) = Y \).

In particular, if \( \sigma \) is eventually surjective and is topologically exact when restricted to its eventual range, then \( G_\sigma \) is simple. The converse is true if \( X \) is totally disconnected.

**Proof.** Suppose that 1 and 2 hold. By Proposition 4.7 if \( Y \) is the eventual range of \( \sigma \), then \( G_\sigma \) is isomorphic to \( G_{\sigma|_Y} \), so we may assume without loss of generality that \( \sigma \) is surjective. Let \( f \in C(X,\mathbb{Z})^+ \), with \( f \neq 0 \), and let \( E \) be a clopen set such that \( \chi_E \leq f \). (Since \( f \geq 0 \) takes on integer values, such an \( E \) exists.) Choose \( n \geq 0 \) such that \( \sigma^n(E) = X \), and choose a positive integer \( k \) such that \( L^n1 \leq k1 \). (Since \( L^n1 \) is bounded, such an integer \( k \) exists.) Then

\[
L^nf \geq L^n\chi_E \geq \chi_{\sigma^n(E)} = 1_X \geq (1/k)L^n1_X.
\]

Thus \( k[f] \geq [1_X] \). Since \([1_X]\) is an order unit, then so is \([f]\), and this proves that \( G_\sigma \) is simple.
Conversely, suppose $G_\sigma$ is simple. We first show that $\sigma$ is eventually surjective. We have $X \supset \sigma(X) \supset \sigma^2(X) \cdots$. Since $G_\sigma$ is simple, then there is some $k \geq 0$ such that $[1_X] \leq k[\chi_\sigma(X)]$. Then for some $n \geq 0$, $L^n1_X \leq kL^n\chi_\sigma(X)$. The support of $L^n1_X$ is $\sigma^n(X)$, and the support of $L^n\chi_\sigma(X)$ is $\sigma^{n+1}(X)$, so $\sigma^n(X) \subset \sigma^{n+1}(X)$. Since the opposite inclusion also holds, we must have equality, so $\sigma$ is eventually surjective.

Now let $Y$ be the eventual range of $\sigma$. If $Y \neq X$, replace $\sigma$ by $\sigma|_Y$, so that we may assume $\sigma$ is surjective. Let $E$ be any non-empty clopen subset of $X$. By simplicity of $G_\sigma$, there exists $k > 0$ such that $k[\chi_E] \geq [1_X]$, and thus there exists $n \geq 0$ such that $kL^n\chi_E \geq L^n1_X$. Comparing supports, we conclude that $\sigma^n(E) = X$, so (2) holds.

Finally, suppose that $X$ is totally disconnected, and that $G_\sigma$ is simple. Then by (1), $\sigma$ is eventually surjective. Let $Y$ be the eventual range of $\sigma$. Let $V$ be any non-empty open subset of $Y$. Then $V$ contains a non-empty clopen subset $W$, and so by (2) there exists $n$ such that $\sigma^n(W) = Y$. Therefore $\sigma^n(V) = Y$, proving that $\sigma$ is topologically exact on $Y$.

\textbf{Corollary 5.4.} If $\tau : I \to I$ is piecewise monotonic and topologically exact, then $DG(\tau)$ is a simple dimension group.

\textbf{Proof.} Let $\sigma : X \to X$ be the associated local homeomorphism, and assume $\tau$ is topologically exact. By Lemma 5.2, $\sigma$ is topologically exact, so by Theorem 5.3, $DG(\tau)$ is simple.

By Theorem 5.3, simplicity of $DG(\tau)$ is most informative when $X$ is totally disconnected. We now explore when this occurs. Recall that the generalized orbit of a subset $A$ of $I$ is the smallest set containing $A$ and closed under $\hat{\tau}$ and $\hat{\tau}^{-1}$.

\textbf{Lemma 5.5.} Let $\tau : I \to I$ be piecewise monotonic, let $C$ be the set of points in the associated partition, and let $\sigma : X \to X$ be the associated local homeomorphism. Then $X$ is totally disconnected iff the generalized orbit $I_1$ of $C$ is dense in $I$.

\textbf{Proof.} Suppose that $I_1$ is dense in $I$. Let $d \in X$, and let $(a,b)_X$ contain $d$. We will assume $\pi(a) < \pi(d) < \pi(b)$; the cases where $\pi(a) = \pi(d)$ or $\pi(d) = \pi(b)$ can be proved in a similar manner. By density of $I_1$, we can choose $x, y \in I_1$ with $\pi(a) < x < \pi(d) < y < \pi(b)$. Then $a < x^+ < d < y^- < b$, and $[x^+, y^-]_X$ is a clopen order interval containing $d$ and contained in $(a,b)_X$. Thus the clopen sets form a base for the topology of $X$, so $X$ is totally disconnected.

Conversely, suppose that $I_1$ is not dense in $I$. Let $(a,b)$ be an open interval in $I$ containing no point of $I_1$. Then every point in $(a,b)$ is in $I_0 = I \setminus I_1$, so every point in the open set $\pi^{-1}(a,b)$ is in $X_0$. Since each clopen subset of $X$ contains points of $X_1$ (cf. Proposition 2.2), then $\pi^{-1}(a,b)$ is a non-empty open subset of $X$ containing no non-empty clopen subset. Thus $X$ is not totally disconnected.

Below “interval” will always denote an interval that is not a single point.

\textbf{Definition 5.6.} Let $\tau : I \to I$ be piecewise monotonic, and $J$ an open interval. Then $J$ is a hominterval if $\tau^n$ is a homeomorphism on $J$ for all $n$.

Note that if $J$ is a hominterval for $\tau$, then for each $p \geq 0$, $J$ will be a hominterval for $\tau^p$. For additional background on homintervals, see the books of Collet-Eckmann [5] §II.5 or de Melo-van Strien [25, Lemma II.3.1]. The following result characterizes the existence of homintervals for polynomials.
Let \( \tau : I \to I \) be piecewise monotonic and continuous. An attracting periodic orbit is a periodic orbit such that the set of points whose orbits converge to that periodic orbit has non-empty interior.

**Proposition 5.7.** If \( \tau : I \to I \) is a polynomial of degree \( \geq 2 \), then \( \tau \) has a hominterval iff \( \tau \) has an attracting periodic orbit.

**Proof.** If \( f \) has a hominterval, by Lemma II.3.1 and Thm. A, p.267], there exists an attracting periodic orbit. Conversely, let \( x_0 \) be an attracting periodic point of \( f \), say \( f^n(x_0) = x_0 \). Let \( h = f^{2p} \); then \( h \) has \( x_0 \) an attractive fixed point. Note \( h'(x_0) = (f^n)'(x_0)^2 \geq 0 \). If \( h'(x_0) > 0 \), since \( x_0 \) is attractive, there must be an open interval \( V \) with endpoint \( x_0 \) such that \( 0 < h' < 1 \) on \( V \). By the mean value theorem, \( h(V) \subset V \), and \( h \) is 1-1 on \( V \). Thus \( V \) is a hominterval for \( h \), and therefore also for \( f \).

If \( h'(x_0) = 0 \), choose \( \delta > 0 \) such that \( 0 < |h'(x)| < 1 \) for \( 0 < |x - x_0| < \delta \). Let \( W = (x_0 - \delta, x_0 + \delta) \cap I \). By the mean value theorem, \( h \) maps \( W \setminus \{x_0\} \) into itself. If \( V \) is a component of \( W \setminus \{x_0\} \), then \( V \) is a hominterval for \( h \), and thus for \( f \).

**Proposition 5.8.** Let \( \tau : I \to I \) be piecewise monotonic, and let \( \sigma : X \to X \) be the associated local homeomorphism. The following are equivalent.

1. \( I \) contains no hominterval.
2. \( I_1 \) is dense in \( I \).
3. \( X \) is totally disconnected.

In particular, these hold if \( \tau \) is transitive.

**Proof.** If \( I \) contains no hominterval, then for any open interval \( J \), there exists \( n \) such that \( \tau^n(J) \) meets \( C \). Thus \( I_1 \) is dense in \( I \).

\( I_1 \iff I_1 \leftarrow I_2 \) Lemma 5.6

\( I_2 \Rightarrow I_1 \) Suppose that there exists a hominterval \( J \); we will show \( I_1 \) is not dense in \( I \). We first show that either (1) there exists \( p \geq 1 \) and a hominterval whose images under \( \tau^p \) are disjoint, or (2) there exists \( p \geq 1 \) and an interval fixed pointwise by \( \tau^p \).

Suppose the images of \( J \) under \( \tau \) are not disjoint, so that \( \tau^n(J) \cap \tau^{n+p}(J) \neq \emptyset \) for some \( n \geq 0 \) and \( p \geq 1 \). Then for \( k \geq 0 \), \( \tau^{n+kp}(J) \cap \tau^{n+(k+1)p}(J) \neq \emptyset \), so \( V = \bigcup_{k=0}^{\infty} \tau^{n+kp}(J) \) is an interval invariant under \( \tau^p \). Since \( J \) is a \( \tau^p \)-hominterval, therefore \( \tau^p \) is continuous and monotonic on each of the overlapping open intervals \( \tau^{n+kp}(J) \) for \( k = 0, 1, \ldots \), so \( \tau^p \) is a homeomorphism from \( V \) into \( V \). Replacing \( \tau^p \) by \( \tau^{2p} \) if necessary, we may assume that \( \tau^p \) is increasing on \( V \).

If some point \( x \) in \( V \) is not fixed by \( \tau^p \), then the \( \tau^p \)-orbit of \( x \) is a monotonic sequence converging to some point of \( \overline{V} \). Let \( K \) be the open interval with endpoints \( x \) and \( \tau^p(x) \). Then \( K \) is an \( \tau^p \)-hominterval whose images under \( \tau^p \) are disjoint. Thus we’ve shown either (1) or (2) must hold. We will show in both cases that \( I_1 \) is not dense in \( I \).

Let \( p \geq 1 \) and \( h = \tau^p \), and suppose that \( J \) is a hominterval whose images under \( h \) are disjoint. We will prove that \( h^N(J) \cap I_1 \) is finite for some \( N \geq 0 \), showing that \( I_1 \) is not dense in \( I \). Let \( D = \bigcup_{k=0}^{\infty} \tau^k(C) \). Observe that \( \bigcup_{k=0}^{\infty} \tau^k(D) = \bigcup_{n=1}^{\infty} \tau^n(C) \) is invariant under \( \tau \), and that the generalized orbit of \( C \) under \( \tau \) is the same as the generalized orbit of \( D \) under \( h \), i.e.,

\[
\tau^m \tau^n C \neq \emptyset \text{ for some } m, n \geq 0 = \{ x \mid h^j x \cap h^k D \neq \emptyset \text{ for some } j, k \geq 0 \}.
\]
In the rest of this proof, “orbit” means the orbit under the map $h$ unless otherwise specified.

Since the orbit of $J$ consists of disjoint intervals, by replacing $J$ by $h^k(J)$ for suitable $k \geq 0$, we can arrange that the orbit of $J$ is disjoint from the finite set $C \cup h(C)$. (Since $\hat{r}$ may be multivalued at points in $C$, it simplifies the discussion to avoid such points where possible.)

Let $D_1$ consist of those points in $D$ whose orbits miss $C$ and meet the orbit of $J$. If $d \in D_1$, let $n_d$ be the least integer such that $\text{orbit}(d) \cap \tau^{n_d}(J) \neq \emptyset$, and let $N = \max_{d \in D_1} n_d$, and $J_N = \tau^N(J)$. (If $D_1 = \emptyset$, define $J_N = J$.) The orbit of each point $d$ in $D_1$ meets $J_{n_d}$, and therefore meets $J_N$. Furthermore, $\text{orbit}(d)$ meets $J_N$ in a unique point $y_d$, since having $\tau^k d \in J_N$ and $\tau^{k+q} d \in J_N$ would imply $\tau^q J_N \cap J_N \neq \emptyset$, contrary to the assumption that the orbit of $J$ consists of disjoint intervals.

Let $P = J_N \cap I_1$: we will prove $P$ is finite. If $x \in P$, by (5.2) the orbit of $x$ meets the orbit of some $d_0 \in D$. Then there is a sequence $d_0, d_1, \ldots, d_k$ such that $d_{i+1} = h(d_i)$ for $0 \leq i \leq k-1$, and $d_k \in \text{orbit}(x)$. By construction of $J$, the orbit of $J$ misses $C$, so the orbit of $x$ misses $C$: thus $d_k \notin C$. Let $j$ be the least index such that $d_j, d_{j+1}, \ldots, d_k$ miss $C$, and set $d = d_j$. Then $d \in D_1$, and the orbit of $d$ meets the orbit of $x$. Let $y_d$ be the unique point where the orbit of $d$ meets $J_N$. Distinct points in $J_N$ have disjoint orbits, so $y_d = x$. Thus for each $x \in P$, there exists a point $d \in D_1$ whose orbit meets $J_N$ exactly in the single point $x$. Since $D_1$ is finite, then $P$ is finite, which finishes the proof that $I_1$ is not dense in $I$.

Suppose instead that there exists an interval $V$ fixed pointwise by $h = \tau^p$ for some $p \geq 1$. Replacing $V$ by a component of $V \setminus (C \cup \hat{r}C)$ if necessary, we can assume that $V$ is disjoint from $C \cup \hat{r}C$. Let $D_2$ be the set of points in $D$ whose orbits land in $V$ and miss $C$. Each orbit of a point in $D_2$ is finite; let $A$ be the union of such orbits. Then no point in $C$ has an orbit that meets $V \setminus A$, so any component of $V \setminus A$ is disjoint from $I_1$. Thus $I_1$ is not dense in $I$.

Finally, suppose $\tau$ is transitive. Then $\tau$ is strongly transitive by Proposition 4.4. If $V$ is any non-empty open subset of $I$, and $c \in C$, by strong transitivity there exists $n \geq 0$ such that $c \in \hat{r}^n(V)$. Then $V$ meets $\hat{r}^{-n}(c)$, so $V \cap I_1 \neq \emptyset$. Thus $I_1$ is dense in $I$.

Example 5.9. Let $1 < s \leq 2$ and let $\tau$ be the tent map with slopes $\pm s$. The length of each interval not containing the critical point $1/2$ is expanded by $\tau$ by a factor $s$, so for every open interval $J$, there exists $n$ such that $1/2$ is in $\tau^n(J)$. Thus $I_1$ is dense in $I$, so if $\sigma : X \to X$ is the local homeomorphism associated with $\tau$, then $X$ is totally disconnected.

We have the following partial converse for Corollary 5.4.

Corollary 5.10. If $\tau : I \to I$ is piecewise monotonic, is surjective, has no homintervals, and $\text{DG}(\tau)$ is simple, then $\tau$ is topologically exact.

Proof. Let $\sigma : X \to X$ be the associated local homeomorphism. Then $X$ is totally disconnected (Proposition 5.8), and by hypothesis, the dimension group $G_\sigma = \text{DG}(\tau)$ is simple. Since $\tau$ is surjective, then $\sigma$ is surjective, cf. Lemma 4.2. By Theorem 5.3, $\sigma$ is topologically exact on its eventual range, namely, $X$, and then by Lemma 5.2, $\tau$ is topologically exact. □
6. Module structure of the dimension group

In this section we will generally work with eventually surjective piecewise monotonic maps $\tau : I \to I$, cf. Definition 4.1. For such maps, if $\sigma : X \to X$ is the associated local homeomorphism, then by Proposition 4.5, $(L_\sigma)_* \tau$ is an order automorphism of $DG(\tau) = G_\sigma$. We use this to give $DG(\tau)$ the structure of a module. We will show that this module is finitely generated, and will identify generators.

**Definition 6.1.** Let $\tau : I \to I$ be piecewise monotonic and eventually surjective. Then we view $DG(\tau)$ as a $\mathbb{Z}[t,t^{-1}]$-module by defining

$$DG(\tau) \ni (\sum_{i=-n}^{m} z_i t^i) [f] = \left( \sum_{i=-n}^{m} z_i (L_\tau)^i \right) [f]$$

for $z_{-n}, \ldots, z_m \in \mathbb{Z}$ and $[f] \in DG(\tau)$. Thus $DG(\tau)$ is both a dimension group and a $\mathbb{Z}[t,t^{-1}]$ module, and we call it the dimension module for $\tau$.

Let $0 = a_0 < a_1 < \ldots < a_n = 1$ be the partition associated with $\tau$. Recall that $\tau_i$ denotes the unique extension of $\tau|_{(a_{i-1}, a_i]}$ to a homeomorphism from $[a_{i-1}, a_i]$ onto its image.

If $a, b \in I_1$ with $a < b$, then we write $I(a, b)$ for the order interval $[a^+, b^-]_X$. If $a > b$, then we define $I(a, b) = I(b, a)$, and we set $I(a, a) = 0$. Recall that each such set $I(a, b)$ is clopen, and that every clopen subset of $X$ is a finite disjoint union of such sets, cf. Proposition 2.2. We generally will not distinguish between an order interval $E$ in $X$, its characteristic function $\chi_E \in C(X, \mathbb{Z})$, and the equivalence class $[\chi_E] \in DG(\tau)$; it should be clear from the context which is intended. In particular, if $a, b \in I_1$, we consider $I(a, b)$ as a member of $DG(\tau)$.

We also observe that if $a, b$ are in $[a_{i-1}, a_i] \cap I_1$, then by equations (2.1) and (2.2),

$$\sigma(I(a, b)) = I(\tau_i(a), \tau_i(b)).$$

If $D$ is a finite subset of $\mathbb{R}$, we will say distinct points $x, y \in D$ are adjacent in $D$ if there is no element of $D$ between them.

**Theorem 6.2.** Let $\tau : I \to I$ be piecewise monotonic and eventually surjective, with associated partition $C = \{a_0, a_1, \ldots, a_n\}$. Let $M$ be any member of the set $\tilde{C} = \{\tau_1(a_0), \tau_1(a_1), \tau_2(a_1), \tau_2(a_2), \ldots, \tau_n(a_{n-1}), \tau_n(a_n)\}$. Let

$$J_1 = \{ I(c, d) \mid c, d \text{ are adjacent points in } \{a_0, a_1, \ldots, a_n, M\} \},$$

and let $J_2$ be the set of intervals corresponding to jumps at partition points, i.e.,

$$J_2 = \{ I(\tau_i(a_i), \tau_{i+1}(a_i)) \mid 1 \leq i \leq n - 1 \}.$$ 

Then $DG(\tau)$ is generated as a module by $J_1 \cup J_2$.

**Proof.** Let $H$ be the submodule of $DG(\tau)$ generated by $J_1 \cup J_2$. By Proposition 2.2, $DG(\tau)$ is generated by the intervals $I(c, d)$ for $c, d \in I_1$, so it suffices to show each such interval is in $H$. Define $c \sim d$ if $I(c, d) \in H$. Then we need to show $c \sim d$ for all $c, d \in I_1$. This relation is clearly reflexive and symmetric. To show it is transitive, suppose $c \sim d$ and $d \sim e$. If $c \leq d \leq e$, then $I(c, d)$ and $I(d, e)$ are in $H$, and are
disjoint intervals, so the sum \( I(c, e) \) of their corresponding characteristic functions is also in \( H \), and thus \( c \sim e \). If \( c \leq e \leq d \), then \( I(c, e) = I(c, d) - I(e, d) \in H \), so again \( c \sim e \). The case \( e \leq c \leq d \) is similar.

By the definition of \( \mathcal{J}_1 \), each pair of adjacent points in \( \{ a_0, a_1, \ldots, a_n, M \} \) is equivalent. By transitivity, all points in \( \{ a_0, a_1, \ldots, a_n, M \} \) are equivalent. Suppose \( c, d \in [a_{i-1}, a_i] \cap I_1 \). We will show

\[
(6.5) \quad c \sim d \implies \tau_i(c) \sim \tau_i(d).
\]

Recall from Theorem 6.2 that \( \sigma \) is a homeomorphism on \( [a_{i-1}^+, a_i^-] \), so by (6.3) we have \( L_s(I(c, d)) = \sigma(I(c, d)) \). From (6.2), \( I(\tau_i(c), \tau_i(d)) = L_s(I(c, d)) \). Thus \( I(\tau_i(c), \tau_i(d)) \in H \) if \( I(c, d) \in H \), which gives (6.5).

In particular, \( \tau_i(a_{i-1}) \sim \tau_i(a_i) \) for \( 1 \leq i \leq n \). By the definition of \( \mathcal{J}_2 \), we have \( \tau_i(a_1) \sim \tau_i(a_1) \) for \( 1 \leq i \leq n - 1 \). Then by transitivity we conclude that \( \tau_i(a_0), \tau_i(a_1), \ldots, \tau_i(a_{n-1}), \tau_i(a_n) \) are equivalent. By definition, \( M \) is one of these numbers, so we conclude that each of these is also equivalent to each of \( a_0, a_1, \ldots, a_n \).

Let \( P \) be the set of all points in \( I_1 \) equivalent to \( a_0 \). So far we have shown that \( P \) contains \( a_0, a_1, \ldots, a_n \), and \( \tau_i(a_0), \tau_i(a_1), \ldots, \tau_i(a_{n-1}), \tau_i(a_n) \). Let \( x \in P \). Then for some index \( i \), \( x \) is in \( [a_{i-1}, a_i] \). Since \( x \in P \), then \( x \sim a_0 \), and since \( a_0 \sim a_{i-1} \), then \( x \sim a_{i-1} \). By (6.3), \( \tau_i(x) \sim \tau_i(a_{i-1}) \sim a_0 \), so \( \tau_i(x) \in P \). Thus \( P \) is closed under application of each \( \tau_i \).

Now suppose that \( x \in P \) and \( y \in [a_{i-1}, a_i] \) with \( \tau_i(y) = x \). Since \( \tau_i(a_i) \in P \), then \( \tau_i(y) \sim \tau_i(a_i) \). By (6.3), \( y \sim a_i \), so \( y \in P \). Therefore \( P \) contains \( \{a_0, a_1, \ldots, a_n\} \) and is closed under application of each \( \tau_i \) and \( \tau_i^{-1} \), so must coincide with \( I_1 \).

Corollary 6.3. If \( \tau : I \to I \) is a continuous, surjective piecewise monotonic map with associated partition \( \{a_0, a_1, \ldots, a_n\} \), then \( DG(\tau) \) is generated as a module by \( I(a_0, a_1), I(a_1, a_2), \ldots, I(a_{n-1}, a_n) \).

Proof. Since \( \tau \) is continuous, then all intervals in \( \mathcal{J}_2 \) in Theorem 6.2 are empty, so can be omitted. Since \( \tau \) is continuous and monotonic on each interval \( [a_i, a_{i+1}] \), its maximum must occur at one of \( a_0, \ldots, a_n \). On the other hand, since \( \tau \) is surjective, its maximum value must be \( a_n \). Thus \( a_n = \tau(a_j) \) for some \( j \), so \( M \) as defined in Theorem 6.2 is equal to \( a_n \). Now the result follows from Theorem 6.2.

Example 6.4. Let \( 1 \leq s \leq 2 \), and let \( \tau : [0, 1] \to [0, 1] \) be the map \( \tau(x) = sx \) for \( 0 \leq x \leq 1/2 \) and \( \tau(x) = s - sx \) for \( x > 1/2 \). By Theorem 6.2 for the maximal partition \( \{0, 1/2, 1\} \), taking \( M = \tau(0) = 0 \), \( DG(\tau) \) is generated as a \( \mathbb{Z}[t, t^{-1}] \) module by \( I(0, 1/2) \) and \( I(1/2, 1) \). Furthermore, we have \( L_s(I(0, 1/2)) = I(0, s/2) = L_s(I(1/2, 1)) \), so in fact this module is singly generated, with generator \( I(0, s/2) \).

Example 6.5. Let \( \tau \) be the map \( \tau(x) = 2x \) for \( 0 \leq x \leq 1/3 \) and \( \tau(x) = (4/3 - x) \) for \( 1/3 < x \leq 1 \). Then \( DG(\tau) \) is generated by the intervals \( I(0, 1/3), I(1/3, 1) \), and \( I(2/3, 1) \). The last interval is included because of the jump discontinuity at \( 1/3 \); note that \( \tau_1(1/3) = 2/3 \) while \( \tau_2(1/3) = 1 \).
7. Cyclic dimension modules

We will see later that the dimension modules of surjective unimodal maps are cyclic (i.e., singly generated). In the current section, we find conditions that guarantee that cyclic dimension modules are free. These conditions involve requirements that certain orbits of critical points are infinite and disjoint.

Let \( \tau : I \to I \) be piecewise monotonic, with associated local homeomorphism \( \sigma : X \to X \). We will identify functions in \( C(X,\mathbb{Z}) \) with functions in \( L^1(\mathbb{R}) \) in the following manner. If \( g \in C(X,\mathbb{Z}) \), there is a unique \( f \in L^1(\mathbb{R}) \) such that \( (f \circ \pi)(x) = g(x) \) for \( x \in X_1 \), with \( f(x) = 0 \) for \( x \notin I \). We will always choose \( f \) to be continuous except at a finite set of points in \( I_1 \). (This is possible by Proposition 2.2.6.) For example, for \( a, b \in I_1 \), the function in \( L^1(\mathbb{R}) \) corresponding to the characteristic function of the order interval \([a^+,b^-]_X \) is the characteristic function of \([a,b]_X \). Any two such choices for \( f \) will agree except on a finite set.

Since we identify functions that agree except at a finite number of points, then by a “discontinuity” for a function in \( C(X,\mathbb{Z}) \), viewed as a function on \( \mathbb{R} \), we will mean a point where left and right limits exist but are different. We denote the set of discontinuities of \( g \) by \( \mathcal{D}(g) \). Note that \( \mathcal{D}(1_X) = \{0,1\} \).

Next we will develop some basic facts about \( \mathcal{D}(g) \). For the definition of \( I(a,b) \), see the beginning of the previous section.

Let \( \tau : I \to I \) be piecewise monotonic, with associated partition \( C \), and let \( C_0 = C \setminus \{0,1\} \). For \( g \in C(X,\mathbb{Z}) \), let \( x_0 < x_1 < \cdots < x_q \) be the points in \( C_0 \), together with the points where \( g \) is discontinuous. Then for some \( n_1, \ldots, n_q \) in \( \mathbb{Z} \), we can write

\[
(7.1) \quad g = \sum_{i=1}^q n_i I(x_{i-1},x_i),
\]

and

\[
(7.2) \quad Lg = \sum_i n_i \sigma(I(x_{i-1},x_i)) = \sum_i n_i [(\tau_1 I(x_{i-1}),\tau_1(x_i))].
\]

It follows that

\[
(7.3) \quad \mathcal{D}(Lg) \subset \bar{\tau}(\mathcal{D}(g)) \cup \bar{\tau} C_0,
\]

so for all \( n \geq 0 \),

\[
(7.4) \quad \mathcal{D}(L^n g) \subset \bar{\tau}^n \mathcal{D}(g) \cup \bigcup_{k=1}^n \bar{\tau}^k C_0.
\]

Note in Lemma 7.1 we interpret \( \tau e \notin \bar{\tau} C_0 \), where \( C_0 = C \setminus \{0,1\} \), to mean in particular that \( e \notin C_0 \), so that \( \tau \) is single-valued at \( e \).

Lemma 7.1. Let \( \tau : I \to I \) be piecewise monotonic, with associated partition \( C \), and let \( C_0 = C \setminus \{0,1\} \). Let \( e \in I_1 \) satisfy \( \tau e \notin \bar{\tau} C_0 \). If \( g \in C(X,\mathbb{Z}) \) is discontinuous at \( e \), and \( g \) is continuous at all points in \( \tau^{-1}(\tau e) \) except \( e \), then \( Lg \) is discontinuous at \( \tau e \).

Proof. Since we are viewing functions in \( C(X,\mathbb{Z}) \) as members of \( L^1(\mathbb{R}) \), if \( a, b \in I_1 \), we will write \( \tau([a,b]) \) for characteristic function of the closed interval \( \bar{\tau}([a,b]) \). With the notation in \( a \), since \( \mathcal{D}(g) \subset \{x_0, \ldots, x_q\} \), there is some index \( j \) such that \( e = x_j \). First consider the case \( 0 < j < q \). Since \( g \) is discontinuous at \( e \), then \( n_j \neq n_{j+1} \). Since \( e \notin C_0 \), then \( \tau \) is monotonic and continuous on \( (x_{j-1},x_{j+1}) \).
Therefore $\tau([x_{j-1}, x_j])$ and $\tau([x_j, x_{j+1}])$ are closed intervals with just the endpoint $x_{\tau} = \tau e$ in common. Since $n_j \neq n_{j+1}$, then $n_j \tau([x_{j-1}, x_j]) + n_{j+1} \tau([x_j, x_{j+1}])$ is discontinuous at $x_{\tau} = \tau e$. On the other hand, for all $i \neq j$, either $x_i \in C_0$ or else $x_i$ is a point of discontinuity of $g$. If $x_i \in C_0$, then $\tau e \notin \hat{\tau} C_0$ implies that $\tau e \notin \hat{\tau} x_i$. If $x_i \notin D(g)$, by hypothesis $x_i \notin \tau^{-1} \tau e$, so again $\tau e \notin \hat{\tau} x_i$. Thus none of the endpoints of the intervals $\tau([x_{i-1}, x_i])$ for $i \notin \{j, j + 1\}$ is equal to $\tau e$, so by (7.2), $Lg$ is discontinuous at $\tau e$.

Now consider the remaining case where $j \in \{0, q\}$. We treat the case $j = q$; the other case is similar. Since $g$ is discontinuous at $e = x_j$, then $n_j \neq 0$, so $\tau x_j \tau([x_{j-1}, x_j])$ is discontinuous at $x_{\tau} = \tau e$. As in the previous paragraph, none of the endpoints of the intervals $\tau([x_{i-1}, x_i])$ for $i \neq j$ is equal to $\tau e$, so by (7.2), $Lg$ is discontinuous at $\tau e$.

**Lemma 7.2.** Let $\tau : I \to I$ be piecewise monotonic, with associated partition $C$, and let $C_0 = C \setminus \{0, 1\}$. Let $g \in C(X, \mathbb{Z})$, and $e \in D(g) \setminus C_0$. If for all $n \geq 0$,

1. $\tau^n e \notin \hat{\tau}^k C_0$ for $k \leq n$, and
2. $\tau^n e \notin \hat{\tau}^n(D(g) \setminus \{e\})$,

then for all $n \geq 0$, $L^n g$ is discontinuous at $\tau^n e$.

**Proof.** By (7.1),

$$
\tag{7.5} D(L^n g) \subset \hat{\tau}^n(D(g) \setminus \{e\}) \cup \{\tau^n e\} \cup \bigcup_{k=1}^n \hat{\tau}^k C_0.
$$

We will prove

$$
\tag{7.6} \tau^n e \in D(L^n g)
$$

for all $n$, by induction on $n$. Suppose (7.6) holds for a particular $n \geq 0$. We will apply Lemma (7.1) with $\tau^n e$ in place of $e$. By (1), $\tau(\tau^n e) \notin \hat{\tau} C_0$. Suppose $x \in \tau^{-1} \tau(\tau^n e) \cap D(L^n g)$, so that $\tau \tau x \tau^n e$ for $x \in \tau^{-1} \tau(\tau^n e) \cap D(L^n g)$. We will show that $x$ is not in the first or third set on the right side of (7.6), so must be in the second. By (2), $\tau x = \tau^{n+1} e \notin \hat{\tau}^{n+1}(D(g) \setminus \{e\})$, so $x \notin \hat{\tau}^{n}(D(g) \setminus \{e\})$. Similarly, if $x \in \hat{\tau}^k C_0$ with $k \leq n$, then $\tau^{n+1} e = \tau x \in \hat{\tau}^{k+1} C_0$, which contradicts (1). Thus (7.5) implies $x = \tau^n e$, so we’ve shown $x = \tau^n e$, so we’ve shown

$$
\tag{7.7} \tau^{-1} \tau(\tau^n e) \cap D(L^n g) = \{\tau^n e\}.
$$

By Lemma (7.1), $\tau^{n+1} e \in D(L^{n+1} g)$, so by induction, $\tau^n e \in D(L^n g)$ for all $n \geq 0$. $\square$

Recall that a $\mathbb{Z}[t, t^{-1}]$ module $G$ is cyclic if there is an element $e \in G$ such that $G = \mathbb{Z}[t, t^{-1}] e$.

**Proposition 7.3.** Let $\tau : I \to I$ be piecewise monotonic, with associated partition $C$. Assume that $DG(\tau)$ is cyclic, and that there exists $a \in \{0, 1\}$ with an infinite orbit, such that

$$
\tag{7.8} \hat{\tau}(C \setminus \{a\}) \subset C.
$$

Then $DG(\tau) \cong \mathbb{Z}[t, t^{-1}]$ as abelian groups, with the action of $L$, given by multiplication by $t$.

**Proof.** Let $b \in C$ be adjacent to $a$ (i.e., there are no points in $C$ between $a$ and $b$). Since the orbit of $a$ is infinite, $\tau^n a \neq \tau^k a$ for $k \neq n$, and $\tau^n a \notin C$ for $n \geq 1$. 

By (7.8) and Lemma 7.2 (with \( e = a \) and \( g = I(a, b) \)), for each \( n \geq 0 \), \( L^n I(a, b) \) is discontinuous at \( \tau^n a \). On the other hand, by (7.8), for \( k < n \),

\[
(7.9) \quad D(L^k I(a, b)) \subset \{ \tau^k a \} \cup \tau^k b \cup \bigcup_{j=1}^{k} \tau^j C_0,
\]

where \( C_0 = C \setminus \{ 0, 1 \} \). It follows that \( L^k I(a, b) \) is continuous at \( \tau^n a \) for \( k < n \). Therefore, for any polynomial \( p \in \mathbb{Z}[t] \) of degree \( n \), \( p(L)I(a, b) \) is discontinuous at \( \tau^n a \), and in particular is not identically zero.

By hypothesis, \( DG(\tau) \) is cyclic, so there exists \( g \in C(X, Z) \) such that \([g] \) is a generator for \( DG(\tau) \). Suppose that \( q(L_\tau)[g] = 0 \) for some \( q \in \mathbb{Z}[t, t^{-1}] \). Choose \( q' \in \mathbb{Z}[t, t^{-1}] \) so that \( q'(L_\tau)[g] = I(a, b) \). Then \( q(L_\tau)q'(L_\tau)I(a, b) = 0 \). It follows that there is a non-zero polynomial \( q'' \in \mathbb{Z}[t] \) such that \( q''(L)I(a, b) = 0 \), contrary to the result established in the first paragraph. We conclude that \( p \rightarrow p(L_\tau)[g] \) is an isomorphism from \( \mathbb{Z}[t, t^{-1}] \) onto \( DG(\tau) \).

We will apply Proposition 7.2 to find dimension groups of unimodal maps later in this paper, cf. Theorem 9.1, and we will show for multimodal maps that a similar requirement of infinite disjoint orbits for critical points leads to the dimension module being free, cf. Proposition 10.6.

8. Markov maps

**Definition 8.1.** A piecewise monotonic map \( \tau \) is Markov if there is a partition \( 0 = b_0 < b_1 < \ldots < b_n = 1 \), with each \( b_i \) being in \( I_1 \), such that for each \( i \), \( \tau \) is monotonic on \((b_i, b_{i+1})\), \( \tau(b_i, b_{i+1}) \) is a union of intervals of the form \([b_j, b_{j+1}]\), and for some \( k \geq 0 \), \( \tau^k(C) \subset \{ b_0, b_1, \ldots, b_n \} \). We call such a partition a **Markov partition** for \( \tau \), and will refer to \((b_0, b_1), (b_1, b_2), \ldots, (b_{n-1}, b_n)\) as the **partition intervals** for \( \tau \).

For a Markov map, we have both the original partition associated with \( \tau \), and the Markov partition. Since we don’t require that \( \tau \) be continuous on each interval \((b_{i-1}, b_i)\), a Markov partition for \( \tau \) may not even qualify as a “partition associated with \( \tau \)” in the sense defined at the start of this paper.

If \( C \) is the set of endpoints in the partition associated with \( \tau \), then \( \tau \) will be Markov iff the forward orbit of \( C \) under \( \tau \) is finite. In that case, the points of the forward orbit of \( C \) will be the endpoints of a Markov partition. When \( \tau \) is continuous, \( \tau \) will be Markov iff each point in \( C \) is eventually periodic.

If \( \tau : I \rightarrow I \) is piecewise monotonic, and \( \sigma : X \rightarrow X \) is the associated local homeomorphism, a **Markov partition for** \( \sigma \) is a partition of \( X \) into clopen order intervals \( E_1, \ldots, E_k \) such that \( \sigma \) is monotonic on each \( E_i \), and maps \( E_i \) onto a union of some of \( E_1, \ldots, E_k \). If \( 0 = b_0 < b_1 < \ldots < b_n = 1 \) is a Markov partition for \( \tau \), then defining \( E_i = I(b_{i-1}, b_i) \) gives a Markov partition for \( \sigma \). The associated zero-one incidence matrix \( A \) is given by \( A_{ij} = 1 \) iff \( \sigma(E_i) \supset E_j \), or equivalently, if \( \tau(b_{i-1}, b_i) \supset (b_{j-1}, b_j) \).

Note that if \( E_1, \ldots, E_n \) is a Markov partition for \( \sigma \), then \( \{ \sigma^k(X) \} \) will be a nested decreasing sequence of sets, with each being a union of some of \( E_1, \ldots, E_n \). Thus \( \sigma \) will be eventually surjective (Definition 4.1), and similarly so will \( \tau \) (Lemma 7.2).
Definition 8.2. If $A$ is an $n \times n$ zero-one matrix, $G_A$ denotes the stationary inductive limit $\mathbb{Z}_n \to \mathbb{Z}^n$ in the category of ordered abelian groups. Here $A$ acts by right multiplication, and $G_A$ will be a dimension group. The action of $A$ induces an automorphism of $G_A$ denoted $A_*$, so we view $G_A$ as a $\mathbb{Z}[t, t^{-1}]$ module, and refer to $(G_A, G_A^+, A_*)$ as the dimension triple associated with $A$.

Notation. Let $G$ be an ordered abelian group, $T : G \to G$ a positive homomorphism, and $G_1, G_2, \ldots$ a sequence of subgroups of $G$ such that $T(G_i) \subset G_{i+1}$. If $g \in G_n$, we will write $(g, n)$ for the sequence $(0, 0, \ldots, 0, g, Tg, T^2g, \ldots)$, where $n-1$ zeros precede $g$. We write $[g, n]$ (or simply $[g, n]$) for the equivalence class of this sequence in the inductive limit. (See the notation introduced after Definition 8.1. Every element of the inductive limit is of the form $[g, n]$, and $[g_1, n_1] = [g_2, n_2]$ with $n_2 \geq n_1$ iff $T^{n_2-n_1+k}g_1 = T^kg_2$ for some $k \geq 0$, or equivalently, iff $T^k g_1 = T^{n_2-k}g_2$. In particular, we represent elements of $G_A$ as pairs $[v, k]$, where $v \in \mathbb{Z}^n$ and $k \in \mathbb{N}$, and the automorphism $A_*$ of $G_A$ is given by $A_*([v, k]) = [vA, k]$. Similarly, there is a canonical automorphism associated with any stationary inductive limit. For an exposition of inductive limits for dimension groups, see [25].

Lemma 8.3. Let $C_1, C_2, \ldots$ be subgroups of $C(X, \mathbb{Z})$ such that $LC_n \subset C_{n+1}$ for all $n$, and let $G$ be the inductive limit of the sequence $C_n \to C_{n+1}$. If

(1) for each $f \in C(X, \mathbb{Z})$ there exists $n \geq 0$ such that $L^nf \in C_n$,

(2) for every $k \geq 0$ and $f \in C_k$, there exists $g \in C(X, \mathbb{Z})$ such that $L^k g = [f]$, then the map $\Phi : G \to DG(\tau)$ defined by $\Phi([f, n]) = L_n^{-n}[f]$ is an order isomorphism from the dimension group $G$ onto the dimension group $DG(\tau)$. If $C_1 = C_2 = C_3 \cdots$, then this isomorphism carries the canonical automorphism of this stationary inductive limit to $L_*$. 

Proof. Recall that $L_*$ is injective, but need not be surjective. However, by [23], $L_*^{-n}$ makes sense on $C_n$. Suppose that $f_1 \in C_{n_1}$ and $f_2 \in C_{n_2}$, and that $[f_1, n_1] = [f_2, n_2]$. Then $L^{n_2-n_1+k}f_1 = L^{n_2+k}f_2 \in C_{n_1+n_2+k}$ for some $k \geq 0$, so taking equivalence classes and applying $L_*^{-n_1-n_2-k}$ gives $L_*^{-n_1}[f_1] = L_*^{-n_2}[f_2]$. Thus $\Phi$ is well defined.

If $f_1 \in C_{n_1}$, $f_2 \in C_{n_2}$ and $\Phi([f_1, n_1]) = \Phi([f_2, n_2])$, then reversing the previous argument gives $L_*^{-n_2}[f_1] = L_*^{-n_1}[f_2]$, so for some $n \geq 0$, $L_*^{n_1+n_2}f_1 = L_*^{n_2+n_1}f_2 \in C_{n_1+n_2+n_2}$. Thus $[f_1, n_1] = [f_2, n_2]$, proving that $\Phi$ is 1-1.

For any $f \in C(X, \mathbb{Z})$, choose $n$ so that $L_*^n f \in C_n$. Then $\Phi[L_*^n f, n] = L_*^{-n}[L_*^n f] = [f]$, so $\Phi$ is surjective. The remaining assertions are readily verified. \qed

Proposition 8.4. Let $\tau : I \to I$ be piecewise monotonic and Markov, with associated local homeomorphism $\sigma : X \to X$. Let $E_1, E_2, \ldots, E_q$ be the associated Markov partition for $\sigma$, with incidence matrix $A$, and define $\psi : \mathbb{Z}^q \to C(X, \mathbb{Z})$ by $\psi(z_1, z_2, \ldots, z_q) = \sum_i z_i E_i$. Then the map $\Phi : G_A \to DG(\tau)$ defined by $\Phi([v, n]) = L_*^{-n}[\psi(v)]$ is an isomorphism from the dimension triple $(G_A, G_A^+, A_*)$ onto the dimension triple $(DG(\tau), DG(\tau)^+, L_*)$.

Proof. Let $M$ be the range of $\psi$. Then $\psi$ is an order isomorphism from $\mathbb{Z}^q$ onto $M$, and $M$ is invariant under $L$ (by the Markov property of the partition). Observe that $L(\psi(v)) = \psi(vA)$ for all $v \in \mathbb{Z}^q$.\hfill (8.1)
so \( \psi \) is an isomorphism from \((G_A, G_A^+, A_x)\) onto the inductive limit of the stationary sequence \( L : M \to M \).

We next show that for any \( f \in C(X, \mathbb{Z}) \) there exists \( n \geq 0 \) such that \( L^n f \in M \).

It suffices to prove this for \( f = I(a, b) \) with \( a, b \in I_1 \). Note that \( LI(a, b) \) is a sum of intervals \( I(c, d) \) with \( c, d \) either being images of \( a, b \) or being points in \( \tau C \). By definition of \( I_1 \), for each point \( x \in I_1 \) there exists \( n \) such that \( \tau^n(x) \) is in the forward orbit of \( C \). It follows that for \( k \) large enough, \( L^k f \) is a sum of intervals of the form \( I(x, y) \) with endpoints \( x, y \) in the forward orbit of \( C \), and thus, by the definition of a Markov partition (Definition 8.1), for \( k \) large enough these endpoints will be in \( \{b_0, \ldots, b_q\} \). Thus \( L^n f \in M \) for \( n \) large enough. Since \( \tau \) is Markov, \( \tau \) and \( \sigma \) are eventually surjective, so \( L_\tau \) is surjective (Proposition 8.3). Now the conclusion follows from Lemma 8.2 with each of \( C_1, C_2, \ldots \) equal to \( M \).

Every zero-one square matrix (without zero rows) is the incidence matrix of a Markov map. To illustrate, the matrix

\[
A = \begin{pmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \end{pmatrix}
\]

is the incidence matrix for the Markov map pictured in Figure 1 on page 2, with respect to the Markov partition \( B = \{0, 1/3, 2/3, 1\} \). In this example, the maximal partition associated with \( \tau \) is \( C = \{0, 1/3, 1/2, 2/3, 1\} \).

Let \( A \) be an \( n \times n \) zero-one matrix (with no zero rows), and let \((X_A, \sigma_A)\) be the associated one-sided shift of finite type. (In other words, \( X_A \) consists of sequences \( x_0 x_1 x_2 \ldots \) with entries in \( \{1, 2, \ldots, n\} \) such that \( A_{x_i x_{i+1}} = 1 \) for all \( i \), and \( \sigma \) is the left shift.) Then, for an appropriate metric, \( X_A \) is a zero dimensional metric space, and \( \sigma_A \) is a local homeomorphism. The dimension group \( G_{\sigma_A} \) (cf. Definition 3.3) is isomorphic to \( G_A \). (For \( A \) irreducible, this is \[\text{Thm. 4.5} \); the proof in \[\text{Thm. 4.5} \]; the proof in \[\text{Thm. 4.5} \] works in general. Alternatively, the proof of Proposition 8.4 can be adapted to prove this.) This suggests that \((X, \sigma)\) might be conjugate to the one-sided shift \((X_A, \sigma_A)\), and we now show that this happens precisely if \( \tau \) has no homtervals (Definition 5.6).

Given a Markov partition \( E_1, \ldots, E_n \) for \( \sigma : X \to X \), with incidence matrix \( A \), the itinerary map \( S : X \to X_A \) is given by \( S(x) = s_0 s_1 s_2 \ldots \), where \( s^k(x) \in E_{s_k} \). We say \( \text{itineraries separate points of} \ X \) if the itinerary map is 1-1. The following proposition shows that this property is independent of the choice of Markov partition.

**Proposition 8.5.** Assume \( \tau : I \to I \) is piecewise monotonic and Markov, with incidence matrix \( A \). These are equivalent.

1. \( \tau \) has no homtervals.
2. Itineraries separate points of \( X \).
3. \((X, \sigma)\) is conjugate to the one-sided shift of finite type \((X_A, \sigma_A)\).

In particular, these equivalent conditions hold if \( \tau \) is transitive.

**Proof.** Let \( B = \{b_0, b_1, \ldots, b_q\} \) be the given Markov partition for \( \tau \), and let \( C \) be the partition associated with \( \tau \).

1. \( \Rightarrow \) Assume that there are no homtervals. We will show that the itinerary map \( S : X \to X_A \) is 1-1. Suppose (to reach a contradiction) that there exists points \( x < y \) in \( X \) with the same itinerary.
We first consider the case where \( x = a^- \) and \( y = a^+ \) for \( a \in I_1 \). By definition of \( I_1 \), the orbit of \( a \) eventually lands on some point in the forward orbit of \( C \), and by the definition of a Markov partition, the forward orbit of \( C \) is eventually contained in \( B \). Thus there exists \( n \) such that \( \tau^n a \subset B \), so \( \pi(a^n(a^\pm)) \subset B \). Suppose that \( \sigma^k(a^-) \) and \( \sigma^k(a^+) \) belong to the same Markov partition interval for \( 0 \leq k \leq n-1 \). Then \( \sigma \) is monotonic on the Markov partition interval containing \( \sigma^{n-1}(a^-) \) and \( \sigma^{n-1}(a^+) \), so \( \sigma^n(a^-) \neq \sigma^n(a^+) \). If \( \sigma^n(a^-) = b^\pm \) for \( b \in B \), then \( \sigma^n(a^+) = b^\mp \), so the itineraries of \( a^\pm \) are different, contrary to our assumption.

Now assume \((x,y)_X \) is not empty, and that \( x,y \) have the same itinerary. By density of \( X_0 \) in \( X \), we may assume \( x \) and \( y \) are in \( X_0 \). Then \( x' = \pi(x) \) and \( y' = \pi(y) \) are distinct points in \( I_0 \) with the same itinerary with respect to the given Markov partition of \( I \). Let \( J = (x',y') \), and for \( n \geq 0 \) define \( J_n \) to be the open interval whose endpoints are \( \tau^n(x') \) and \( \tau^n(y') \). Since \( x \) and \( y \) have the same itinerary, \( \tau \) is monotonic on \( J_n \) for all \( n \). Since there are no homtervals, there is some \( n \) such that \( J_n \) contains a point \( c \in C \). Then \( \tau^k(c) \subset J_{n+k} \) for all \( k \geq 0 \). However, the orbit of \( c \) eventually lands in \( B \), so \( J_q \) contains a point of \( B \) for some \( q \). But then \( \tau^q(x') \) and \( \tau^q(y') \) would have different itineraries, a contradiction. Thus \( S \) is 1-1.

\[ \Rightarrow \] Assume itineraries separate points, so that \( S \) is 1-1. To show that \( S \) is surjective, let \( s = s_0 s_1 \cdots \in X_A \). For each \( n \geq 0 \), let \( I_{s_0 s_1 \cdots s_n} \) be the set of points in \( X \) with the initial itinerary \( s_0 s_1 \cdots s_n \). Then the points with itinerary \( s \) are those that are in \( \cap_{n=0}^\infty I_{s_0 s_1 \cdots s_n} \). The sets \( I_{s_0 s_1 \cdots s_n} \) for \( n = 0,1,\ldots \) are nested and compact, so surjectivity of the map \( S \) will follow if we show each such set is nonempty.

Observe that \( I_{s_0 s_1 \cdots s_n} = I_{s_0} \cap \sigma^{-1}(I_{s_1 \cdots s_n}) \). We use induction on the length of the partial itinerary. Suppose that these partial itinerary sets are nonempty for partial itineraries of length \( m \). If \( s_0 s_1 \ldots s_m \) is an allowed transition with respect to the incidence matrix \( A \), by definition of \( A \), \( \sigma(I_{s_0}) \supset I_{s_1} \), so \( \sigma(I_{s_0}) \supset I_{s_1 \cdots s_m} \). Thus \( \sigma(I_{s_0}) \cap \sigma^{-1}(I_{s_1 \cdots s_m}) \) is not empty, which completes the proof that \( S \) is surjective, so that \((X,\sigma)\) is conjugate to \((X_A,\sigma_A)\).

\[ \Rightarrow \] If \((X,\sigma)\) is conjugate to a shift of finite type, then \( X \) is totally disconnected. By Proposition 5.8 \( \tau \) has no homtervals.

Finally, if \( \tau \) is transitive, then \( \tau \) has no homtervals (Proposition 5.8). \(\square\)

**Example 8.6.** Let \( \tau_0(x) = kx(1-x) \), with \( c \) the unique critical point, and choose \( k \approx 3.68 \) so that \( p = \tau^3(c) \) is fixed. Let \( \tau \) denote \( \tau_0|J \), where \( J = [\tau^2(c),\tau(c)] \), rescaled so that the domain of the restricted map is \([0,1]\). (See the restricted logistic map in Figure 1 on page 2.) The map \( \tau \) is Markov, with Markov partition \( \{0,c,p,1\} \). The incidence matrix is

\[
A = \begin{pmatrix}
0 & 0 & 1 \\
0 & 0 & 1 \\
1 & 1 & 0
\end{pmatrix}.
\]

Since \( \tau \) is a polynomial, it will have homtervals iff it has an attracting periodic orbit (Proposition 5.7). For a quadratic, the orbit of the critical point will be attracted to any attracting periodic orbit (\( \square \) p. 158)). For our particular polynomial \( \tau_0 \), since the orbit of the critical point \( c \) lands on a repelling fixed point \( p \), we conclude that there are no homtervals. If \( \sigma : X \to X \) is the associated local homeomorphism, by Proposition 5.8 \( (X,\sigma) \cong (X_A,\sigma_A) \).
If \( \tau : I \to I \) is piecewise monotonic and Markov, the directed graph associated with \( \tau \) has vertices consisting of the Markov partition intervals, with an edge from \( E \) to \( F \) if \( \tau(E) \supset F \). This is the same as the directed graph associated with the incidence matrix for \( \tau \). By “directed graph” we will always mean a graph in which there are no multiple edges between pairs of vertices. A loop in a directed graph is a path that begins and ends at the same vertex. If \( \tau : I \to I \) is piecewise linear and Markov, we will see we can determine whether there are homtervals by looking at the directed graph associated with \( \tau \).

**Definition 8.7.** Let \( v_1, \ldots, v_n \) be vertices of a directed graph. If \( v_1 v_2 \ldots v_n v_1 \) is a loop, then an exit for this loop is an edge from some \( v_i \) to a vertex other than \( v_{i+1 \mod n} \). A directed graph satisfies Condition L if every loop has an exit.

Condition L appears in the study of C*-algebras associated with (possibly infinite) directed graphs, cf. [23]. An equivalent condition for finite graphs (“Condition \( \Gamma \)”) was assumed in [6]. If a (finite) directed graph is irreducible, Condition L is equivalent to the associated incidence matrix not being a permutation matrix.

In Proposition 8.8 by a piecewise linear Markov map we mean a piecewise monotonic map, which is Markov, and which on each interval of the Markov partition is piecewise linear. We allow the slopes of the pieces to vary from interval to interval, but not within an interval of the partition. We don’t require the map to be continuous on each partition interval, since we want to allow examples like the Markov map in Figure 1 on page 2.

**Proposition 8.8.** Let \( \tau : I \to I \) be piecewise linear and Markov, with incidence matrix \( A \). These are equivalent.

1. \( \tau \) has no homtervals.
2. Itineraries separate points of \( X \).
3. \( (X, \sigma) \) is conjugate to the one-sided shift of finite type \( (X_A, \sigma_A) \).
4. In the directed graph associated with \( \tau \), every loop has an exit.

**Proof.** By Proposition 8.8 it suffices to prove that 3 and 4 are equivalent. Suppose \( v_1 v_2 \ldots v_n v_1 \) is a loop without an exit in the directed graph associated with \( \tau \). By definition, each \( v_i \) is an open interval in the associated Markov partition for \( \tau \). Since \( \tau \) is monotonic and piecewise linear on each \( v_i \), and \( \tau(v_i) = v_{i+1 \mod 1} \) for each \( i \), then \( \tau \) must be a homomorphism of \( v_i \) onto \( v_{i+1 \mod n} \) for each \( i \). Thus \( v_i \) is a hominterval.

Conversely, assume that every loop has an exit. By conjugating \( \tau \) by a suitable continuous piecewise linear map if necessary, we may assume that each interval in the Markov partition has the same length. If \( E \) is an interval in the Markov partition, since the slope of \( \tau \) within \( E \) is constant, it must be an integer, equal to the number of partition intervals covered by \( \tau(E) \). Let \( V \) be a hominterval contained in a partition interval \( E_0 \). We claim that there exists \( n \geq 1 \) such that the length \( \tau^n(V) \) is at least double that of \( V \). If the slope of \( \tau|_{E_0} \) is \( \pm 1 \), since all partition intervals have the same length, then \( E_1 = \tau(E_0) \) will also be a partition member. If \( E_0, \ldots, E_j \) have been defined, and the slope of \( \tau \) on \( E_j \) is \( \pm 1 \), define \( E_{j+1} = \tau(E_j) \). Note that if \( E_i = E_j \) for \( i < j \), then \( E_i, \ldots, E_j \) would be a loop without an exit, which is not allowed, so the sets \( E_1, E_2, \ldots, E_j \) are distinct. Choose \( n \) maximal such that \( E_0, E_1 = \tau(E_1), \ldots, E_n = \tau(E_{n-1}) \) are all partition members. Then \( \tau|_{E_n} \) has slope \( \geq 2 \), so the (Lebesgue) measure of \( \tau^n(V) \) is at least double the length of \( V \).
Furthermore, since $V$ is a hominterval, $\tau$ is 1-1 on $\tau^k(V)$ for all $k$, so the measure of
$\tau^k(V)$ never decreases as $k$ increases.

Now let $V$ be an arbitrary hominterval. Then we can write $V$ as a disjoint union
of homintervals $V_1, \ldots, V_k$, each contained in a partition interval, together with a
finite set of points. Then there exists $n$ such that for all $i$, $\tau^n(V_i)$ has measure at
least double the length of $V_i$. Then the measure of $\tau^n(V)$ is at least double the
length of $V$. This process can be repeated indefinitely, which is impossible since
$\tau^n(V) \subset [0,1]$ for all $n$. We conclude that $\tau$ has no homintervals. □

This provides an easy way to tell if Markov piecewise linear maps are transitive or
topologically exact. Recall that a zero-one matrix is irreducible if in the associated
directed graph, there is a path from any vertex to any other vertex, and is irreducible
and aperiodic if it is irreducible and the greatest common divisor of the lengths of
paths between any two vertices is 1. This is equivalent to $A$ being primitive, i.e., to
some power of $A$ having strictly positive entries. It is well known that the one-sided
shift $\sigma_A$ is transitive iff $A$ is irreducible, (e.g., [20 Thm. 1.4.1]), and is topologically
mixing iff $A$ is primitive. It is readily verified that $\sigma_A$ will be topologically exact
iff it is topologically mixing.

Corollary 8.9. Assume $\tau: I \to I$ is piecewise linear and Markov, with incidence
matrix $A$. Then $\tau$ is topologically exact iff $A$ is primitive, and is transitive iff $A$
is irreducible and is not a permutation matrix. If $A$ is irreducible, and is not a
permutation matrix, and $\sigma: X \to X$ is the local homeomorphism associated with $\tau$,
then $(X,\sigma)$ is conjugate to the one-sided shift $(X_A,\sigma_A)$.

Proof. Assume $\tau$ is transitive. By Proposition 8.8, $(X,\sigma)$ is conjugate to the one-
sided shift $(X_A,\sigma_A)$. Transitivity of $\tau$ implies transitivity of $\sigma$ (Proposition 2.9).
Thus $\sigma_A$ is transitive, so $A$ is irreducible. If $A$ were a permutation matrix, then $A^p$
would be the identity for some $p$, so $\tau^p$ restricted to each interval of the Markov part-
tition would be a monotonic bijection of that interval onto itself. This contradicts
transitivity of $\tau$, so $A$ cannot be a permutation matrix.

Conversely, if $A$ is irreducible and not a permutation matrix, then $\sigma_A$ is transi-
tive, and every loop has an exit, which implies that $\tau$ has no homintervals (Proposi-
tion 8.8). Having no homintervals implies that $(X,\sigma)$ is conjugate to $(X_A,\sigma_A)$ (Proposi-
tion 8.8). Thus $\sigma$ and $\tau$ are transitive.

If $\tau$ is topologically exact, then it is also transitive, so again $(X,\sigma)$ is conjugate
to $(X_A,\sigma_A)$. Then $\sigma$ and $\sigma_A$ are topologically exact, so $A$ is primitive. Conversely,
if $A$ is primitive, one easily verifies that in the associated graph every loop has an
exit, so $(X,\sigma)$ will be conjugate to $(X_A,\sigma_A)$. Primitivity of $A$ implies that $\sigma_A$
is topologically exact, and thus that $\sigma$ and $\tau$ are topologically exact. □

Example 8.10. Let $\tau$ be the Markov map in Figure 1 on page 2 and let $\sigma: X \to X$
be the associated local homeomorphism. Then $\tau$ is Markov, so the dimension
triples $(DG(\tau), DG(\tau)^+, L_\tau)$ and $(G^+_A, G^-_A, A_\tau)$ are isomorphic (Proposition 8.4).
The associated incidence matrix $A$ is primitive, so $(X,\sigma)$ is conjugate to $(X_A,\sigma_A)$
and $\tau$ is topologically exact (Corollary 8.9).

9. Unimodal maps

If $\tau: I \to I$ is continuous, with just two intervals of monotonicity, without loss
of generality, we may assume $\tau$ increases and then decreases. (If not, conjugate by
the map \( \phi(x) = 1 - x \). We will say a continuous map \( \tau : I \to I \) is unimodal if there exists \( c \) in \((0, 1)\) such that \( \tau \) is increasing on \([0, c]\) and decreasing on \([c, 1]\). We are mainly interested in the case when \( \tau \) is eventually surjective. In that case, for the purpose of computing the dimension group, we may as well assume that \( \tau \) is surjective, cf. Proposition 7.3.

**Example 9.2.** Let \( k \geq (9.1) \) where by Proposition 7.3. A the forward orbit of \( c \) injectivity the unique critical point maps to 1, one endpoint of \( I \) the automorphism /suppress L. **Example 9.3.** Let \( G \) a matrix \( c \geq k \)(10) Figure 1 on page 2.) Note that \( G \) topologically exact (Corollary 8.9), as also is easy to verify directly. We compute \( G \) surjective, cf. Proposition 4.7.

For use in the next example, we recall one way to compute the dimension group \( G_A \) (Definition 8.2), due to Handelman; see [24] for an exposition. If \( A \) is \( n \times n \), view \( A \) as acting on \( \mathbb{Q}^n \), and let \( V_A \subset \mathbb{Q}^n \) be the eventual range of \( A \), i.e. \( V_A = \cap_{k=1}^{\infty} \mathbb{Q}^n A^k \). Let \( G \) be the set of vectors \( v \in V_A \) such that \( vA^k \in \mathbb{Z}^n \) for some \( k \geq 0 \), and \( G^\perp \) those vectors such that \( vA^k \in (\mathbb{Z}^n)^\perp \) for some \( k \geq 0 \). Then \( (G_A, G^\perp_A) \cong (G, G^\perp, A) \).

**Theorem 9.1.** Let \( \tau : I \to I \) be unimodal and surjective. Then the dimension module \( DG(\tau) \) is cyclic, with generator \( I(0, 1) \). If the critical point \( c \) is eventually periodic, then \( \tau \) is Markov. In that case, if the incidence matrix is \( A \), then \( (DG(\tau), DG(\tau)^+, L_\tau) \cong (G_A, G^+_A, A_\tau) \). If \( c \) is not eventually periodic, then \( DG(\tau) \cong \mathbb{Z}[t, t^{-1}] \) (as abelian groups), with the action of \( L_\tau \) given by multiplication by \( t \).

**Proof.** Suppose \( \tau(1) = 0 \). By Corollary 7.3 the module \( DG(\tau) \) is generated by \( I(0, c) \) and \( I(c, 1) \), where \( c \) is the unique critical point. Since \( L_\tau I(\tau(c), 1) = I(0, 1) \), then \( I(0, c) = I(0, 1) - (L_\tau)^{-1} I(0, 1) \), so \( DG(\tau) \) is generated by \( I(0, 1) \), and thus is cyclic. The same conclusion applies if \( \tau(0) = 0 \), by a similar argument.

If \( c \) is eventually periodic, then \( \tau \) is Markov with respect to the partition given by the forward orbit of \( c \), together with the endpoint 0. Then \( (DG(\tau), DG(\tau)^+, L_\tau) \cong (G_A, G^+_A, A_\tau) \) follows from Proposition 7.3. If \( c \) is not eventually periodic, by surjectivity the unique critical point maps to 1, one endpoint of \( I \) must map to zero, and the other endpoint will have an infinite orbit. Thus \( DG(\tau) \cong \mathbb{Z}[t, t^{-1}] \) by Proposition 7.3.

Given \( s > 1 \), we define the restricted tent map \( T_s \) by

\[
T_s(x) = \begin{cases} 1 + s(x - c) & \text{if } x \leq c \\ 1 - s(x - c) & \text{if } x > c, \end{cases}
\]

where \( c = 1 - 1/s \). (This is the usual symmetric tent map on \([0, 1]\) with slopes \( \pm s \), restricted to the interval \([\tau^2(1/2), \tau(1/2)]\), which is the interval of most interest for the dynamics. Then the map has been rescaled so that its domain is \([0, 1]\). See Figure 1 on page 2.) Note that \( \tau(c) = 1 \) and \( \tau(1) = 0 \).

For use in the next example, we recall one way to compute the dimension group \( G_A \) (Definition 8.2), due to Handelman; see [24] for an exposition. If \( A \) is \( n \times n \), view \( A \) as acting on \( \mathbb{Q}^n \), and let \( V_A \subset \mathbb{Q}^n \) be the eventual range of \( A \), i.e. \( V_A = \cap_{k=1}^{\infty} \mathbb{Q}^n A^k \). Let \( G \) be the set of vectors \( v \in V_A \) such that \( vA^k \in \mathbb{Z}^n \) for some \( k \geq 0 \), and \( G^\perp \) those vectors such that \( vA^k \in (\mathbb{Z}^n)^\perp \) for some \( k \geq 0 \). Then \( (G_A, G^+_A, A_\tau) \cong (G, G^\perp, A) \).

**Example 9.2.** Let \( \tau = T_2 \) be the full tent map. Then \( \tau \) is Markov, with incidence matrix \( A = \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} \), so \( DG(\tau) \cong G_A \). Since the incidence matrix is primitive, \( \tau \) is topologically exact (Corollary 8.3), as also is easy to verify directly. We compute \( G_A \). The eventual range of \( A \) in \( \mathbb{Q}^2 \) consists of multiples of \((1, 1)\), and multiplication by \( A \) on the eventual range multiplies this vector by 2. Thus \( G_A \) is isomorphic to the space of vectors \( q(1, 1) \) for \( q \) in \( \mathbb{Q} \) such that \( q(1, 1) A^k = 2^k q(1, 1) \in \mathbb{Z}^2 \) for some \( k \geq 0 \). It follows that \( DG(\tau) \) is isomorphic to the group of dyadic rationals, with the automorphism \( L_\tau \) given by multiplication by 2.

**Example 9.3.** Let \( \tau \) be the restricted tent map \( T_{\sqrt{2}} \), let \( c \) be the critical point, and let \( p \) be the fixed point. Then \( \tau \) is Markov, with Markov partition \( \{0, c, p, 1\} \).
and $\tau^2$ is conjugate to the tent map on each of the invariant intervals $[0,p]$ and $[p,1]$. Thus $\tau$ is transitive (as can also be seen by applying Corollary 8.9). By Example 9.2, $\text{DG}(\tau)$ will be the direct sum of two copies of the dyadic rationals, with the generators of the summands being $I(0,p)$ and $I(p,1)$. The associated automorphism $L_*$ will exchange the two summands, taking $(a,b) \in \mathbb{Z}[1/2] \oplus \mathbb{Z}[1/2]$ to $(b,2a)$.

**Example 9.4.** Let $s = 3/2$. Then the critical point of the restricted tent map $T_s$ is not eventually periodic. (Indeed, if $c$ is the critical point and $n \geq 3$, then $\tau^n(c) = a_n/2^{n-2}$, where $a_n$ is odd.) By Theorem 9.1, $\text{DG}(T_s) \cong \mathbb{Z}[t,t^{-1}]$ as abelian groups, with the action of $L_*$ given by multiplication by $t$.

**Example 9.5.** Let $\tau(x) = kx(1-x)$, with $k$ as in Example 8.6, restricted to the interval described there. Then $\tau$ is Markov, with incidence matrix is

$$A = \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 1 \\ 1 & 1 & 0 \end{pmatrix}.$$

As shown in Example 8.6, the associated local homeomorphism $(X,\sigma)$ is conjugate to $(X_A,\sigma_A)$. The map $T_{\sqrt{2}}$ is Markov, with the same incidence matrix. Since $A$ is irreducible and not a permutation matrix, $T_{\sqrt{2}}$ also is conjugate to $(X_A,\sigma_A)$ (Corollary 8.9). Thus $\tau$ is conjugate to $T_{\sqrt{2}}$, so $\text{DG}(\tau)$ is as described in Example 9.3. Alternatively, $\text{DG}(\tau)$ can be computed by applying Proposition 8.4.

10. Multimodal maps

By a multimodal map we mean a continuous piecewise monotonic map. In this section we will show that the dimension modules for multimodal maps are free modules, under the assumption that the critical points have orbits that are infinite and disjoint.

**Definition 10.1.** Let $\tau : I \to I$. If a set $B \subset I$ has the property that for $b_1, b_2 \in B$, and $n, m \geq 0$,

$$(10.1) \quad \tau^m b_1 = \tau^n b_2 \implies b_1 = b_2 \text{ and } m = n,$$

we say $B$ satisfies the infinite disjoint orbit condition (IDOC).

Note that if $B$ satisfies the IDOC, then $\tau$ is 1-1 on $\text{orbit}(B)$. The IDOC condition has been used in studies of interval exchange maps, cf., e.g., [18].

Recall from Section 7 that we view functions in $C(X,\mathbb{Z})$ as functions in $L^1(\mathbb{R})$, continuous except on a finite set, and that $\mathcal{D}(g) \subset I_1$ denotes the set of points where $g \in L^1(\mathbb{R})$ has an essential (jump) discontinuity.

**Lemma 10.2.** Let $\tau : I \to I$ be piecewise monotonic and continuous, with associated partition $C$, and associated local homeomorphism $\sigma : X \to X$. Let $B = \tau C \setminus \{0,1\}$. Assume

1. The orbits of points in $B$ are infinite and disjoint.
2. $\tau(\{0,1\}) \subset B$.

Then the only solution in $C(X,\mathbb{Z})$ of $Lg = g$ is $g = 0$. 

Proof: We start by establishing some basic facts about $B$ that will also be used in the proof of Lemma 10.3. By the definition of $B$,

\[
(10.2) \quad \tau C \subset B \cup \{0, 1\},
\]

and since $\tau(\{0, 1\}) \subset B$,

\[
(10.3) \quad \tau^2 C \subset \tau B \cup B.
\]

Combining (10.2) and (10.3) gives

\[
(10.4) \quad \text{orbit}(C) \setminus C \subset \text{orbit}(B).
\]

By (10.3) and the IDOC,

\[
(10.5) \quad \tau^2(\text{orbit}(B)) \cap \tau^2 C \subset \left( \bigcup_{i=2}^{\infty} \tau^i B \right) \cap (\tau B \cup B) = \emptyset.
\]

Hence

\[
(10.6) \quad \text{orbit}(B) \cap C = \tau(\text{orbit}(B)) \cap \tau C = \emptyset,
\]

since if (10.6) failed, the result of applying $\tau^2$ or $\tau$ to each equality would contradict (10.5).

By the definition of $I_1$, for each $a \in I_1$ there exists $m \geq 0$ such that $\tau^m a \in \text{orbit}(C)$. By (10.3), $\tau^2 C \subset \text{orbit}(B)$, and thus $\tau^{m+2} a \in \text{orbit}(B)$. Hence

\[
(10.7) \quad a \in I_1 \implies \tau^m a \in \text{orbit}(B) \text{ for some } n \geq 0.
\]

Now assume $g \in C(X, \mathbb{Z})$ and $Lg = g$. Choose $n \geq 0$ such that

\[
(10.8) \quad \tau^n D(g) \subset \text{orbit}(B).
\]

By (10.2), (10.3), and (10.6), using $Lg = g$,

\[
(10.9) \quad D(g) = D(I^n g) \subset \tau^n D(g) \cup \bigcup_{k=1}^{n} \tau^k C \subset \text{orbit}(B) \cup \{0, 1\}.
\]

Suppose that $D(g) \not\subset \{0, 1\}$, and let $N \geq 0$ be the largest integer such that $D(g)$ contains a point of $\tau^N B$. (By the IDOC for $B$, the sets $\{\tau^n B \mid n \geq 0\}$ are disjoint, and $D(g)$ is finite, so such an integer $N$ exists.) Choose $e \in D(g) \cap \tau^N B$. We now will verify that the hypotheses of Lemma 7.1 hold here. Since $e \in \text{orbit}(B)$, then $\tau e \not\in \tau C$ by (10.6). Let $x \in D(g) \cap \tau^{-1} \tau e$. Then $\tau x = \tau e \not\in \tau C$, so $x \notin C$. Thus $x \in D(g) \setminus C$ and (10.9) imply that $x$ is in $\text{orbit}(B)$. By the IDOC, $\tau$ is 1-1 on $\text{orbit}(B)$, so $\tau x = \tau e$ implies $x = e$. Now Lemma 7.1 implies that $\tau e \in D(Lg)$. Then $D(g) = D(Lg)$ contains $\tau e \in \tau^{N+1} B$, which contradicts the maximality of $N$.

We conclude that $D(g) \subset \{0, 1\}$, and therefore $g \in GI(0, 1)$. If $LI(0, 1) = I(0, 1)$, since $LI(0, 1)(t)$ is the cardinality of $\sigma^{-1}(t)$, then $\sigma$ would be bijective. It would follow that $\tau$ was bijective, and thus would be a homeomorphism, so $\tau(\{0, 1\}) \subset \{0, 1\}$, contrary to (2). Thus $g = 0$.

\[\Box\]

**Lemma 10.3.** Let $\tau : I \to I$ be piecewise monotonic and continuous, with associated partition $C$, and associated local homeomorphism $\sigma : X \to X$. Let $B = \tau C \setminus \{0, 1\}$. Assume

1. the orbits of points in $B$ are infinite and disjoint, and
2. $\tau(\{0, 1\}) \subset B$.

If $f \in C(X, \mathbb{Z})$ and $D(f - Lf) \subset C$, then $D(f) \subset C$ and $L f \in GI(0, 1)$.
Proof. Assume \( D(f - Lf) \subset C \). We first prove

\[
D(f) \subset \text{orbit}(C). \tag{10.10}
\]

Suppose that \( e_0 \in D(f) \setminus \text{orbit}(C) \). Observe that \( e_0 \) can't be periodic, since by (10.7), the orbit of \( e_0 \) lands in the orbit of \( B \), and by the IDOC, no point of \( B \) can be periodic. Therefore the sets \( \{\tau^{-k}e_0 \mid k \geq 0\} \) are disjoint, so there exists a maximal integer \( N \) such that \( \tau^{-N}e_0 \cap D(f) \neq \emptyset \). Choose \( e \in \tau^{-N}e_0 \cap D(f) \), and observe that

\[
e \in D(f) \setminus \text{orbit}(C) \text{ and } \tau^{-1}e \cap D(f) = \emptyset. \tag{10.11}
\]

Then \( e \notin \tau D(f) \), and since \( e \notin \text{orbit}(C) \), in particular \( e \notin \tau C \). By (10.12),

\[
D(Lf) \subset \tau D(f) \cup \tau C, \tag{10.12}
\]

so \( e \notin D(Lf) \). Since \( f \) is discontinuous at \( e \) and \( Lf \) is continuous at \( e \), then \( e \) is in \( D(f - Lf) \), which is contained in \( C \) by hypothesis, contradicting \( e \notin \text{orbit}(C) \). This proves (10.10).

We now prove

\[
\tau(D(f) \setminus C) \subset D(f) \setminus C. \tag{10.13}
\]

Let \( e \) be an arbitrary member of \( D(f) \setminus C \). By (10.10) and (10.4),

\[
e \in D(f) \setminus C \subset \text{orbit}(C) \setminus C \subset \text{orbit}(B). \tag{10.14}
\]

By the same argument as in the proof of Lemma 10.2 the hypotheses of Lemma 10.4 are satisfied here, so \( \tau e \in D(Lf) \). By (10.6), \( \tau e \in \text{orbit}(B) \) implies that \( \tau e \notin C \). By hypothesis, \( D(f - Lf) \subset C \), so \( \tau e \notin D(f - Lf) \), i.e., \( f - Lf \) is continuous at \( \tau e \). Since \( \tau e \in D(Lf) \), then \( Lf \) is discontinuous at \( \tau e \), so \( f = (f - Lf) + Lf \) is discontinuous at \( \tau e \). Hence \( \tau e \in D(f) \setminus C \), which finishes the proof of (10.13).

Since \( D(f) \setminus C \subset \text{orbit}(B) \), by the IDOC any point in \( D(f) \setminus C \) has an infinite orbit, and this orbit stays in \( D(f) \setminus C \) by (10.13). Since \( D(f) \) is finite, it follows that \( D(f) \setminus C \) is empty, so we’ve proven

\[
D(f) \subset C. \tag{10.15}
\]

By hypothesis \( D(f - Lf) \subset C \), so \( D(Lf) \subset C \). On the other hand, by (10.2),

\[
D(Lf) \subset \tau D(f) \cup \tau C \subset \tau C. \tag{10.16}
\]

By (10.6), \( B \cap C = \emptyset \), so by (10.2),

\[
D(Lf) \subset \tau C \cap C \subset (B \cup \{0, 1\}) \cap C = \{0, 1\}. \tag{10.17}
\]

If follows that \( Lf \subset \mathbb{Z}l(0, 1) \), which completes the proof of the lemma. \( \square \)

Lemma 10.4. Let \( E_1, \ldots, E_n \) be elements in a \( \mathbb{Z}[t] \) module. If

1. \( E_1, \ldots, E_n \) are independent in \( M \) viewed as a \( \mathbb{Z} \) module,
2. \( (1 - t)M \cap \sum_i \mathbb{Z}E_i = \{0\} \), and
3. \( \ker(1 - t) = \{0\} \),

then \( E_1, E_2, \ldots, E_n \) are independent in \( M \) viewed as a \( \mathbb{Z}[t] \) module.

Proof. We first prove the implication (for \( p_1, p_2, \ldots, p_n \in \mathbb{Z}[t] \))

\[
\sum_i p_i(t)E_i = 0 \implies p_1(1) = p_2(1) = \cdots = p_n(1) = 0. \tag{10.17}
\]
If
\[
(10.18) \quad 0 = \sum_i p_i(t)E_i = \sum_i (p_i(t) - p_i(1))E_i + \sum_i p_i(1)E_i,
\]

since each \( p_i(t) - p_i(1) \) is divisible by \((1 - t)\), then
\[
(10.19) \quad \sum_i p_i(1)E_i = -\sum_i (p_i(t) - p_i(1))E_i \in (1 - t)M,
\]
which by (1) and (2) gives the implication (10.17).

Now let \( p_1, p_2, \ldots, p_n \) be arbitrary polynomials in \( \mathbb{Z}[t] \), and assume that \( \sum_i p_i(t)E_i = 0 \), and that not all \( p_i \) are the zero polynomial. Let \( k \) be the largest power such that \((1 - t)^k \) divides each \( p_i(t) - p_i(1) \) for \( 1 \leq i \leq n \). Write \( p_i(t) - p_i(1) = (1 - t)^k q_i(t) \), where \( q_1, \ldots, q_n \in \mathbb{Z}[t] \). Note, for use below, that by the maximality of \( k \), there is an index \( j \) such that \((1 - t)\) does not divide \( q_j(t) \), and thus \( q_j(1) \neq 0 \).

Now by (3),
\[
(10.20) \quad 0 = (1 - t)^k \sum_i q_i(t)E_i
\]
implies that \( \sum_i q_i(t)E_i = 0 \), so by (10.17), \( q_1(1) = q_2(1) = \ldots = q_n(1) = 0 \). This contradicts \( q_j(1) \neq 0 \). Thus we conclude that \( p_1 = p_2 = \ldots = p_n = 0 \), and hence that \( E_1, \ldots, E_n \) are independent in the \( \mathbb{Z}[t] \) module \( M \).

**Lemma 10.5.** Let \( \tau : I \to I \) be continuous, surjective, and piecewise monotonic, with associated partition \( C = \{a_0, a_1, \ldots, a_q\} \), and associated local homeomorphism \( \sigma : X \to X \). Assume that the orbits of \( a_1, a_2, \ldots, a_{q-1} \) are infinite and disjoint, and that \( \tau(\{0, 1\}) \cap \{0, 1\} = \emptyset \). Then \( I(a_0, a_1), I(a_1, a_2), \ldots, I(a_{q-2}, a_{q-1}) \) are independent in \( DG(I) \).

**Proof.** Let \( B = \tau C \setminus \{0, 1\} \). By surjectivity,
\[
(10.21) \quad \{0, 1\} \subset \tau\{\{a_1, \ldots, a_{q-1}\}\},
\]
and it follows that \( B \) satisfies the hypotheses of Lemma 10.2 and 10.3. Let \( E_i = I(a_{i-1}, a_i) \) for \( 1 \leq i \leq q - 1 \).

We now verify the hypotheses of Lemma 10.4 with \( n = q - 1 \) and \( M = C(X, Z) \), viewed as a \( \mathbb{Z}[t] \) module via the action of \( L = \mathbb{L}_\sigma \).

Since \( E_1, \ldots, E_{q-1} \) are disjoint, if \( \sum z_iE_i = 0 \), where \( z_1, \ldots, z_{q-1} \in \mathbb{Z} \), then \( z_1 = \cdots = z_{q-1} = 0 \), so \( E_1, \ldots, E_{q-1} \) are independent in \( M \) viewed as a \( \mathbb{Z} \) module.

Next we show \( (id - L)C(X, Z) \cap \sum z_iE_i = \{0\} \). Suppose that \( g \in \sum_{i=1}^{q-1} z_iE_i \), with \( g \neq 0 \), and that \( g = (id - L)f \) for some \( f \in C(X, Z) \). Then \( D(f - Lf) = D(g) \subset C \), so by Lemma 10.2 \( D(f) \subset C \), and \( Lf = zI(0, 1) \) for some \( z \in \mathbb{Z} \). Let \( f = \sum_{i=1}^q z_iI(a_{i-1}, a_i) \), where \( z_1, \ldots, z_q \in \mathbb{Z} \). Then
\[
(10.22) \quad zI(0, 1) = Lf = \sum_{i=1}^q z_iI(\tau a_{i-1}, \tau a_i).
\]

By (10.21) and the IDOC for \( \{a_1, \ldots, a_{q-1}\} \), the points \( \{\tau a_j \mid 0 \leq j \leq q\} \) are all distinct. If \( x \) is the first index in (10.22) for which \( z_x \) is nonzero, and \( y \) is the last such index, then the right side of (10.22) will be discontinuous at \( \tau a_{x-1} \) and \( \tau a_y \), so \( \{\tau a_{x-1}, \tau a_y\} \subset \{0, 1\} \), and \( z_x = z_y = z \neq 0 \). Since \( g \in \sum_{i=1}^{q-1} zE_i \) is continuous
at 1,
\[(10.23)\]
g = f - Lf = \sum_{i=x}^{y} z_i I(a_{i-1}, a_i) - zI(0, 1)
implies that \(a_y = 1\). Since \(\{\tau a_x-1, \tau a_y\} \subset \{0, 1\}\), this contradicts our assumption that \(\tau(\{0, 1\}) \cap \{0, 1\} = \emptyset\), so we have shown that \(g\) cannot be in \((\text{id} - L)C(X, Z)\).

Finally, by Lemma 10.2 \(\ker(\text{id} - L) = \{0\}\), so we have verified all the assumptions of Lemma 10.4. We conclude that \(E_1, \ldots, E_{q-1}\) are independent in the \(Z[t]\) module \(C(X, Z)\). It follows that their equivalence classes are also independent in the \(Z[t, t^{-1}]\) module \(DG(\tau)\). \(\square\)

**Proposition 10.6.** Let \(\tau : I \to I\) be multimodal and surjective, with associated partition \(C = \{a_0, a_1, a_2, \ldots, a_q\}\). If the orbits of \(a_1, \ldots, a_{q-1}\) are disjoint and infinite, and \(\tau(\{0, 1\}) \cap \{0, 1\} = \emptyset\), then \(DG(\tau) \cong (Z[t, t^{-1}])^{q-1}\) as (unordered) \(Z[t, t^{-1}]\) modules, with basis \(I(a_0, a_1), I(a_1, a_2), \ldots, I(a_{q-2}, a_{q-1})\).

**Proof.** By Corollary 6.3 \(I(a_0, a_1), I(a_1, a_2), \ldots, I(a_{q-1}, a_q)\) generate \(DG(\tau)\). We will show \(I(a_{q-1}, a_q)\) is in the submodule generated by the first \(q - 1\) of these elements. It will follow that \(I(a_0, a_1), I(a_1, a_2), \ldots, I(a_{q-2}, a_{q-1})\) generate \(DG(\tau)\), and are independent by Lemma 10.4, and thus these elements form a basis.

Since \(\tau\) is surjective, we can choose indices \(x, y\) such that \(\tau(a_x) = 0\) and \(\tau(a_y) = 1\). For simplicity of notation, we suppose that \(x < y\). Since \(\tau(\{0, 1\}) \cap \{0, 1\} = \emptyset\), then \(0 < x < y < q\). Next observe that for \(a, b \in I_1\), \(I(0, a) \pm I(a, b) = I(0, b)\), with the \(\pm\) sign depending on whether \(a < b\) or \(a > b\). Let \(b_i = \tau(a_{x+i})\) for \(0 \leq i \leq y-x\).

In particular, \(b_0 = \tau(a_x) = 0\) and \(b_{y-x} = \tau(a_y) = 1\). Then for appropriate choices of the \(\pm\) signs in the equation below,

\[
\begin{align*}
L\left(I(a_x, a_{x+1}) \pm I(a_{x+1}, a_{x+2}) \pm \cdots \pm I(a_{y-1}, a_y)\right) \\
= I(b_0, b_1) \pm I(b_1, b_2) \pm \cdots \pm I(b_{y-x-1}, b_{y-x}) \\
= I(b_0, b_{y-x}) = I(0, 1).
\end{align*}
\]

It follows that \(I(0, 1)\) is in the \(Z[t, t^{-1}]\) submodule of \(DG(\tau)\) generated by \(I(a_0, a_1), I(a_1, a_2), \ldots, I(a_{q-2}, a_{q-1})\). Since
\[(10.24)\]
\[I(a_{q-1}, a_q) = I(0, 1) - I(a_0, a_1) - I(a_1, a_2) - \cdots - I(a_{q-2}, a_{q-1}),\]
it follows that \(I(a_0, a_1), I(a_1, a_2), \ldots, I(a_{q-2}, a_{q-1})\) generate \(DG(\tau)\). This completes the proof that the prescribed set of \(q-1\) elements form a basis for the module \(DG(\tau)\), and thus that \(DG(\tau) \cong (Z[t, t^{-1}])^{q-1}\). \(\square\)

11. **Interval exchange maps**

**Definition 11.1.** A piecewise monotonic map \(\tau : [0, 1) \to [0, 1)\) is an interval exchange map if \(\tau\) is linear with slope 1 on each interval of monotonicity, is bijective, and is right continuous at all points. (See Figure 1 on page 2 for an example.) We will usually identify \(\tau\) with its extension to a map from \([0, 1]\) into \([0, 1]\), defined to be left continuous at 1.

If \(\{a_0, a_1, \ldots, a_n\}\) is the associated partition for an interval exchange map, then for each \(i\), the lengths of \([a_{i-1}, a_i]\) and \(\tau([a_{i-1}, a_i])\) will be the same, and the images of the intervals \(\{\tau(a_{i-1}, a_i) \mid 1 \leq i \leq n\}\) will form a partition of \([0, 1]\), which is the reason for the name “interval exchange map"
Definition 11.2. A map \( \tau : I \to I \) is **essentially injective** if there are no disjoint intervals \( J, J' \) with \( \tau(J) = \tau(J') \).

This is equivalent to \( \tau \) being injective on the complement of the set of endpoints of intervals of monotonicity.

Lemma 11.3. A piecewise monotonic map \( \tau : I \to I \) is essentially injective iff the associated local homeomorphism \( \sigma : X \to X \) is injective.

Proof. If \( J, J' \) are disjoint intervals in \( I \) such that \( \tau(J) = \tau(J') \), then \( \tau(J \cap I_0) = \tau(J' \cap I_0) \). Since \( \sigma \) restricted to \( X_0 \) is conjugate to \( \tau \) restricted to \( I_0 \), then \( \sigma \) is not \( 1 \)-\( 1 \).

Conversely, suppose \( \sigma \) is not \( 1 \)-\( 1 \). Note that for \( z \in X \), \((L_1)(z)\) is the number of pre-images of \( z \). Let \( z \in X \) have at least two distinct pre-images. Since \( L_1 \) is integer valued and continuous, then \((L_1)(x) \geq 2 \) for all \( x \) in an open neighborhood \( V \) of \( z \). Thus each member of \( V \) has at least two pre-images. It follows that each member of an open set in \( X_0 \) has two pre-images, so the same is true for \( \tau \) on an open set in \( I_0 \). It follows that \( \tau \) is not essentially injective.

Definition 11.4. A piecewise monotonic map \( \tau : I \to I \) is **essentially bijective** if \( \tau \) is surjective and essentially injective, cf. Definitions 11.1 and 11.2.

A piecewise monotonic map \( \tau : I \to I \) will be essentially bijective iff the associated local homeomorphism \( \sigma : X \to X \) is bijective, cf. Lemma 11.3 and the remarks after Definition 11.1. Note that an interval exchange map \( \tau : I \to I \) is bijective on \([0, 1] \), but might only be essentially bijective on \([0, 1] \).

For our purposes, the fact that an interval exchange map is linear on each interval of monotonicity will not play a role, which motivates the following definition.

Definition 11.5. A piecewise monotonic map \( \tau : [0, 1) \to [0, 1) \) is a **generalized interval exchange map** if \( \tau \) is increasing on each interval of monotonicity, is bijective, and is right continuous at all points. We will usually identify \( \tau \) with its extension to a map from \([0, 1] \) into \([0, 1] \), defined to be left continuous at 1. (That map will be essentially bijective.)

We are now going to find the dimension group for (generalized) interval exchange maps that have certain orbits infinite and disjoint. (See also Theorem 9.11 and Proposition 10.6 for continuous maps with the IDOC property.)

Lemma 11.6. Let \( \tau : I \to I \) be piecewise monotonic, with associated partition \( C = \{a_0, a_1, \ldots, a_n\} \), and associated local homeomorphism \( \sigma : X \to X \). Let \( E_i = I(a_{i-1}, a_i) \) for \( 1 \leq i \leq n - 1 \). If \( L = L_\sigma \) is injective, and orbit(\( \tau C \) \( \cap C \subset \{0, 1\} \), then \( E_1, \ldots, E_{n-1} \) are independent in \( DG(\tau) \).

Proof. Suppose first, to reach a contradiction, that \( E_1, \ldots, E_{n-1} \) are not independent in the \( \mathbb{Z}[t] \) module \( C(X, \mathbb{Z}) \), and choose \( p_1, \ldots, p_{n-1} \) in \( \mathbb{Z}[t] \), not all zero, satisfying \( \sum_{i=1}^{n-1} p_i(L) E_i = 0 \), with the sum of the degrees of the non-zero polynomials among \( p_1, \ldots, p_{n-1} \) as small as possible. For \( 1 \leq i \leq n - 1 \), define \( q_i(t) \in \mathbb{Z}[t] \) by \( t q_i(t) = p_i(t) - p_i(0) \), and define

\[
g_1 = \sum_{i=1}^{n-1} p_i(0) E_i, \quad g_2 = \sum_{i=1}^{n-1} q_i(L) E_i. \tag{11.1}
\]
Then $g_1 + Lg_2 = \sum p_i(L)E_i = 0$. Note by (1.4),
\[(11.2)\]
$$D(Lg_2) \subset \tilde{\tau}(D(g_2)) \cup \tau C.$$  
Since $\cup_i D(E_i) \subset C$, then $D(g_2) \subset \text{orbit}(C)$, so $D(Lg_2) \subset \text{orbit}(\tilde{\tau}C)$. Since $D(g_1) \subset C \setminus \{1\}$ and $g_1 = -Lg_2$, by the assumption that $\text{orbit}(\tilde{\tau}C) \cap C \subset \{0, 1\}$,
\[(11.3)\]
$$D(g_1) = D(Lg_2) \subset \text{orbit}(\tilde{\tau}C) \cap (C \setminus \{1\}) \subset \{0\}.$$  
Thus $D(g_1) = D(Lg_2) = \{0\}$, hence $g_1 = 0$, and $Lg_2 = L\sum q_i(L)E_i = 0$. By assumption, $L$ is injective, so $\sum q_i(L)E_i = 0$, which contradicts the minimality of the sum of the degrees of the non-zero polynomials among $p_1, \ldots, p_{n-1}$. We conclude that $p_1, \ldots, p_{n-1}$ are all the zero polynomial. Thus $E_1, \ldots, E_{n-1}$ are independent in the $\mathbb{Z}[t]$ module $C(X, \mathbb{Z})$. It follows that their equivalence classes are independent in the $\mathbb{Z}[t, t^{-1}]$ module $DG(\tilde{\tau})$.

We will write $\tau(a^-)$ for $\lim_{t \to a^-} \tau(t)$, and define $\tau(a^+)$ similarly.

**Proposition 11.7.** Assume $\tau : I \to I$ is piecewise monotonic and essentially bijective, with associated partition $C = \{a_0, a_1, \ldots, a_n\}$. If $\text{orbit}(\tilde{\tau}C) \cap C \subset \{0, 1\}$, then the (unordered) module $DG(\tau)$ is isomorphic to $\mathbb{Z}[t, t^{-1}]^{n-1} \oplus \mathbb{Z}$, where the action of $\mathbb{Z}[t, t^{-1}]$ on the first summand is the usual one, and $t$ acts trivially on the second summand.

**Proof.** Since $\tau$ is essentially bijective, the associated local homeomorphism $\sigma : X \to X$ is bijective. Then for $g \in C(X, \mathbb{Z})$, $L_\sigma g = g \circ \sigma^{-1}$, so $L_\sigma$ is bijective.

Let $E_i = I(a_{i-1}, a_i)$ for $1 \leq i \leq n$. By Lemma 11.4, $E_1, \ldots, E_{n-1}$ are independent in $DG(\tau)$. Let $\tilde{\tau}C = \{b_0, b_1, \ldots, b_n\}$, in increasing order. Then each interval $I(b_{j-1}, b_j)$ is equal to $LE_k$ for some $k$. The left and right limits of $\tau$ at partition points are in $\tilde{\tau}C$, so each jump $I(\tau(a_i^-), \tau(a_i^+))$ at partition points is of the form $I(b_j, b_k)$ for some $j < k$, and therefore is a sum of intervals of the form $LE$ for $E \in \{E_1, \ldots, E_n\}$. Furthermore, by surjectivity, $0 \in \tilde{\tau}C$, so by Theorem 6.2, $\{E_1, \ldots, E_n\}$ is a set of generators for $DG(\tau)$. Since $E_1 + E_2 + \ldots + E_n = I(0, 1)$, then the intervals $I(0, 1)$, $E_1$, $E_2$, $\ldots$, $E_{n-1}$ also generate.

Since $\sigma$ is bijective, then $L_\sigma I(0, 1) = I(0, 1)$, so for every $p \in \mathbb{Z}[t, t^{-1}]$, $p(L_\sigma)I(0, 1) = p(1)I(0, 1)$. Thus $\mathbb{Z}[t, t^{-1}]I(0, 1) = \mathbb{Z}I(0, 1)$, so every element of $DG(\tau)$ can be written in the form $\sum_{i=1}^{n-1} p_i(L_\sigma)E_i + zI(0, 1)$, with each $p_i \in \mathbb{Z}[t, t^{-1}]$, and $z \in \mathbb{Z}$. By the independence of $\{E_i \mid 1 \leq i \leq n - 1\}$, no nonzero element $\sum_{i=1}^{n-1} p_i(L_\sigma)E_i$ is fixed by $L_\sigma$, so this representation is unique.

When we have referred to the orbit of a point with respect to a piecewise monotonic map with some discontinuities, we have previously used the orbit with respect to the multivalued map $\tilde{\tau}$. In the next proposition, we need to refer to the orbit with respect to $\tau$ itself, and we will call this the $\tau$-orbit to avoid confusion with our earlier usage. Recall that if a set $B$ has the property that its points have orbits that are infinite and disjoint, we refer to this property as the IDOC for $B$.

**Corollary 11.8.** Let $\tau : I \to I$ be a generalized interval exchange map, with associated partition $C = \{a_0, a_1, \ldots, a_n\}$. If the $\tau$-orbits of $a_1, a_2, \ldots, a_{n-1}$ are infinite and disjoint, then $DG(\tau) = C(X, \mathbb{Z})$ is isomorphic as an (unordered) $\mathbb{Z}[t, t^{-1}]$ module to $\mathbb{Z}[t, t^{-1}]^{n-1} \oplus \mathbb{Z}$ (where the action of $L_\sigma$ on the first summand is coordinatewise multiplication by $t$, and on the second summand is trivial).
Proof. Let \( C_0 = C \setminus \{0, 1\} = \{a_1, a_2, \ldots, a_{n-1}\} \). We’ll prove
\[
(11.4) \quad x \in C \implies \text{orbit}(\hat{x}) \cap C_0 = \emptyset.
\]
First consider the case \( x = 0 \). If \( \tau = 0 = 0 \), then \( 11.4 \) is clear. If \( \tau \neq 0 \), by surjectivity, we can choose \( a \in C_0 \) with \( \tau a = 0 \). Then \( \text{orbit}(\hat{0}) = \text{orbit}(\tau^2 a) \), and \( \text{orbit}(\tau^2 a) \) misses \( C_0 \) by the IDOC.

Now suppose \( x \in C_0 \). Then the orbit of \( \tau x \) misses \( C_0 \) by the IDOC. Furthermore, if \( x \in C_0 \cup \{1\} \), there exists \( y \in C_n \cup \{0\} \) such that \( \tau y = \tau(x^-) \). Then \( \text{orbit}(\tau(x^-)) = \text{orbit}(\tau y) \) misses \( C_0 \) by the previous part of this proof. Thus we’ve shown \( \text{orbit}(\hat{x}) \cap C_0 = \emptyset \).

As observed in the proof of Proposition 11.7, if \( \sigma : X \to X \) is the local homeomorphism associated with \( \tau \), then essential bijectivity of \( \tau \) implies that \( \mathbb{L} = \mathbb{L}_\sigma \) is bijective, and so \( DG(\tau) = C(X, \mathbb{Z}) \). The rest of the corollary follows from Proposition 11.7.

Note that in Corollary 11.8, the order on \( DG(\tau) = C(X, \mathbb{Z}) \) is just the usual pointwise order on \( C(X, \mathbb{Z}) \).

12. \( \mathbb{C}^* \)-algebras

Let \( \tau : I \to I \) be a piecewise monotonic map, with associated partition \( C = \{a_0, a_1, \ldots, a_n\} \). We now give a dynamical construction of a \( \mathbb{C}^* \)-algebra \( A_\tau \) such that \( K_0(A_\tau) \cong DG(\tau) \). The construction will also display \( DG(\tau) \) explicitly as an inductive limit of groups of the form \( \mathbb{Z}^{n_k} \), with the connecting maps easily computable from the map \( \tau \). Define \( C_0 = \{0, 1\} \), and for \( n \geq 1 \), define \( C_n = (\bigcup_{k=1}^{2n} \hat{\tau}^k C) \cap \hat{\tau}^n(I) \). Observe that the sequence \( \{C_n\} \) has the following properties.

\[
\begin{align*}
(12.1) \quad \hat{\tau}(C) & \subset C_1, \\
(12.2) \quad \hat{\tau}(C_n) & \subset C_{n+1}, \\
(12.3) \quad C_n & \subset \hat{\tau}^n I, \\
(12.4) \quad C_k \cap \hat{\tau}^n I & \subset C_n \text{ for } k \leq n, \\
(12.5) \quad \text{If } a \in I_1, \text{ then there exists } n \geq 0 \text{ such that } \hat{\tau}^n(a) \subset C_n.
\end{align*}
\]

Any sequence \( \{C_n\} \) of finite subsets of \( I_1 \) satisfying these five properties would work equally well in what follows. (Note that \( 12.5 \) could fail if we replaced the upper limit \( 2n \) by \( n \) in the union defining \( C_n \).) We say \( x, y \in C_n \) are adjacent in \( C_n \) if there is no point in \( C_n \) strictly between \( x \) and \( y \). For \( n \geq 0 \), let \( \mathcal{P}_n \) be the set of closed intervals contained in \( \hat{\tau}^n(I) \) whose endpoints are adjacent points in \( C_n \). For each \( Y \in \mathcal{P}_n \), choose a point \( x \) in the interior of \( Y \) and define \( k(Y) \) to be the cardinality of \( \tau^{-n}(x) \). (By the definition of \( \mathcal{P}_n \), \( k(Y) \) does not depend on the choice of \( x \).) For \( n \geq 0 \), define
\[
A_n = \bigoplus_{Y \in \mathcal{P}_n} C(Y, M_{k(Y)}).
\]

Recall that for each \( i \), \( \tau_i \) denotes the continuous extension of \( \tau|_{[a_{i-1}, a_i]} \) to a homeomorphism on \([a_{i-1}, a_i]\). Fix \( n \geq 0 \). If \( Z \in \mathcal{P}_{n+1} \), for each index \( i \), \( \tau_i(I) \) either contains \( Z \) or is disjoint from the interior of \( Z \). In the former case, there is exactly one \( Y \in \mathcal{P}_n \) such that such that \( \tau_i(Y) \supset Z \), or equivalently, \( \tau_i^{-1}(Z) \subset Y \).
For $n \geq 0$, let $X^n$ be the disjoint union of $\{Y \in \mathcal{P}_n\}$. We view $A_n$ as a subalgebra of $C(X^n, \oplus_{Y \in \mathcal{P}_n} M_k(Y))$. Define $\phi_n : A_n \to A_{n+1}$ by

$$\phi_n(f) = \oplus_{Z \in \mathcal{P}_{n+1}} \text{diag}(f \circ \tau^{-1}_{i_1}, \ldots, f \circ \tau^{-1}_{i_p}),$$

where for each $Z \in \mathcal{P}_{n+1}$ the indices $i_1, \ldots, i_p$ are the indices $i$ such that $\tau_i(I)$ contains $Z$.

Let $A_{\tau}$ be the inductive limit of the sequence $\phi_n : A_n \to A_{n+1}$. Recall that an interval algebra is one isomorphic to $C([0, 1], F)$, where $F$ is a finite dimensional C*-algebra, and an AI-algebra is an inductive limit of a sequence of interval algebras. Thus each $A_n$ is an interval algebra, and $A_{\tau}$ is an AI-algebra.

**Example 12.1.** We illustrate this construction with the full tent map, cf. Example 9.2. Here $C_n = \{0, 1\}$ for all $n$, $\tau^{-1}_1(x) = x/2$ and $\tau^{-1}_2(x) = 1 - x/2$. Hence for all $n$, $A_n = C([0, 1], M_2^n)$, and $\phi_n : A_n \to A_{n+1}$ is given by $\phi_n(f) = \text{diag}(f \circ \tau^{-1}_1, f \circ \tau^{-1}_2)$.

(This example also appears in [3] and [7].)

**Example 12.2.** Let $\tau$ be the restricted tent map $\tau = T_{\sqrt{2}}$. In this case the critical point $c$ is eventually fixed, with $\tau^4c = \tau^3c$. Let $c = c_0, c_1, c_2, c_3, \ldots$ be the orbit of $c$, and let $p$ be the fixed point of $\tau$. Note that $0 = c_2 < c_0 = c < c_3 = p < c_1 = 1$. Then we can represent the imbeddings by the following diagram of intervals.

![Figure 2. Inductive limit construction](image)

The disjoint union of the intervals on each level of this diagram are the sets $X^0, X^1, X^2, \ldots$ described previously, with the connecting lines indicating the maps of intervals by $\tau$. From this diagram, the algebras $A_0, A_1, \ldots$ and the maps $\phi_n : A_n \to A_{n+1}$ can also be read off. For example,

$$A_3 = C([c_2, c_3], M_2) \oplus C([c_3, c_1], M_4).$$
Here the dimensions of the matrix algebras for a given interval are the number of paths from the bottom to that interval. Since $K_0(C([0, 1], M_n)) = \mathbb{Z}$, $K_0(A_n)$ is found by replacing each interval by a copy of $\mathbb{Z}$. The connecting lines indicate the connecting maps for the inductive limit of dimension groups, giving $DG(\tau)$. In this particular example, the map $\tau$ is Markov, so the width of the diagram stabilizes. For general $\tau$ the diagram can become steadily wider, as can be seen from the examples discussed in the previous section.

The diagram in Figure 2, with intervals shrunk to points, also can be thought of as a Bratteli diagram, cf. [2]. The AF-algebra associated with that diagram would have the same $K_0$ group as $A_\tau$. However, $A_\tau$ is not necessarily an AF-algebra.

**Proposition 12.3.** If $\tau : I \to I$ is piecewise monotonic, $K_0(A_\tau)$ and $DG(\tau)$ are isomorphic dimension groups.

**Proof.** Recall that for each $n$, we view elements of $A_n$ as maps from $X^n$ into a suitable matrix algebra. We view elements of the matrix algebra $M_q(A_n)$ as functions from $X^n$ into $\oplus_{y \in P_n} M_q(M_k(Y))$. For each projection $p$ in a matrix algebra over $A_n$, define $\dim(p)$ to be the function $y \mapsto \dim(p(y))$. Then $\dim(p) \in C(X^n, \mathbb{Z})$, and since $X_n$ is a disjoint union of closed intervals, $\dim$ extends uniquely to an isomorphism of $K_0(A_n)$ onto $C(X^n, \mathbb{Z})$.

Let $\pi_n : \sigma^n(X) \to X^n$ be the collapse map (that collapses $x^{\pm}$ to the single point $x$ except for the pre-images of points in $C_n$.) For each $n \geq 0$, let $\hat{C}(X^n, \mathbb{Z})$ denote the subgroup of $C(X, \mathbb{Z})$ generated by characteristic functions of intervals $I(a, b)$ with $a, b \in C_n$. Then $f \mapsto f \circ \pi_n$ is an order isomorphism from $C(X^n, \mathbb{Z})$ onto $\hat{C}(X^n, \mathbb{Z})$. Observe that

$$\hat{C}(X^n, \mathbb{Z}) = \{ f \in C(X, \mathbb{Z}) \mid D(f) \subset C_n \},$$

where $D(f)$ is the set of discontinuities of $f$ viewed as a function on $\mathbb{R}$, cf. Section 7. If $f \in \hat{C}_n(X, \mathbb{Z})$, then $\supp f \subset \sigma^n(X)$, and $\supp Lf \subset \sigma^{n+1}(X)$. By (7.4) and (12.4),

$$D(Lf) \subset (\hat{\tau}(D(f)) \cup \hat{\tau}C) \cap \hat{\tau}^{n+1}I \subset (\hat{\tau}(C_n) \cup \hat{\tau}C) \cap \hat{\tau}^{n+1}I \subset C_{n+1}.$$ 

Thus $L$ maps $\hat{C}_n(X, \mathbb{Z})$ into $\hat{C}_{n+1}(X, \mathbb{Z})$.

Consider the following commutative diagram.

$$\begin{array}{ccc}
K_0(A_n) & \xrightarrow{\dim} & C(X^n, \mathbb{Z}) \\
\downarrow \phi_n & & \downarrow \quad \quad \quad \quad \\
K_0(A_{n+1}) & \xrightarrow{\dim} & C(X^{n+1}, \mathbb{Z})
\end{array}$$

(12.9)

(The commutativity of this diagram can be verified by checking it on generators of $K_0(A_n)$, which are of the form $[1_Y e_{11}]$ for $Y \in P_n$.) Since the horizontal maps are isomorphisms, by continuity of $K_0$ with respective to inductive limits, $K_0(A_\tau)$ is isomorphic to the inductive limit of the sequence $L : \hat{C}_n(X, \mathbb{Z}) \to \hat{C}_{n+1}(X, \mathbb{Z})$. We will be done if we show this inductive limit is isomorphic to $DG(\tau)$. 

For that purpose, we apply Lemma 8.3. By (7.4), for $f \in C(X, Z)$,

$$D(L_n f) \subset \tau^n D(f) \cup \left( \bigcup_{k=1}^{n} \tau^k f \cap \tau^n f \right) \subset \tau^n D(f) \cup C_n. \tag{12.10}$$

By (12.2) and (12.5), for each $f \in C(X, Z)$ there exists $n \geq 0$ such that $\tau^n D(f) \subset C_n$, so (12.10) implies that $L_n f \in \hat{C}_n(X, Z)$. If $f \in \hat{C}_k(X, Z)$, then $\text{supp } f \subset \sigma^k(X)$, so $f \in L^\infty C(X, Z)$ (Lemma 8.4). By Lemma 8.3, $DG(\tau)$ is isomorphic to the inductive limit of the sequence $L : C_n(X, Z) \rightarrow C_{n+1}(X, Z)$, so $K_0(A)$ is isomorphic to $DG(\tau)$. □

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