Experimental work on Data Clustering using Enhanced Random K-Mode Algorithm

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Abstract— Clustering the uncertainty data is not an easy task but an essential task in data mining. The traditional algorithms like K-Means clustering, UK Means clustering, density based clustering etc, to cluster uncertain data are limited to using geometric distance based similarity measures and cannot capture the difference between uncertain data with their distributions. Such methods cannot handle uncertain objects that are geometrically indistinguishable, such as products with the same mean but very different variances in customer ratings. Because of its complexity, the clustering takes high execution time resulting in high computational cost. In this we propose a Enhance Random K-Mode algorithm which is also called as ERK-Mode to cluster the uncertainty data. The K-mode concept classifies the dataset and separates as certain and uncertain data from the whole dataset. Again enhanced random K-Mode is used to cluster the uncertainty data. The Weather data values are taken in to the account for experiments [3]. The experiment shows that the proposed algorithm is very efficient with fast execution time and low complexity.

Keywords: Uncertainty Clustering, Weather dataset, Random K-Mode, Probability Density Function

I. INTRODUCTION

In the real world, data mining applications are affected by data’s uncertainty. All clustering algorithms aim of dividing the collection all data objects into subsets or similar clusters. A cluster is a collection of objects which are “similar” between them and are “dissimilar” to the objects belonging to other clusters and a clustering algorithm aims to find a natural structure or relationship in an unlabeled data set. Due to uncertainty into account during the computations, designing of data mining technique has become critical [4][5]. For measuring the applications like weather station monitors, weather conditions, hardware techniques in the real time, the uncertainty is measured through elements like temperature, precipitation amount, humidity etc [1].

The Uncertain data can be clustered by probability density function equation:

$$PDF(z_{l,1}, z_{l,2} \ldots z_{l,m}) = \int_1^m f(z_{l,m})dx$$

For example, the mode of an object's probability density function can be used as typical point. However, it gives outstanding clustering results than traditional methods.

K-mode algorithm uses values as the highest number of occurrence as a cluster head. K-means supports only for numerical but K-mode supports both Numerical and categorical dataset. Major contributions in the real time application for this paper: Weather dataset has been taken with parameters like temperature, humidity and are analyzed.

The previous studies on clustering uncertain data are largely various extensions of the traditional clustering algorithms considered for certain data [2]. Here the object in certain dataset is considered as a single point and distribution concerning the object itself is not considered in traditional clustering algorithms.

New algorithm Enhanced Random K-mode has been proposed to cluster the uncertain data efficiently.

II. PROBLEM STATEMENT

Clustering the certain data is a normal process but clustering the uncertainty data is not an easy task. Clustering on uncertain data, one of the essential tasks in mining uncertain data, posts significant challenges on both modeling similarity between uncertain objects and developing efficient computational methods. The previous methods extend traditional partitioning clustering methods.

The randomized k-mode algorithm is used to improve the accuracy of the clusters. In k-mode clustering, number of cluster depends on dataset value which results in time consumption.

III. PROPOSED WORK

Here we consider weather dataset values consist of different parameters like temperature, humidity etc. The dataset is given as input to the K-mode process where
the dataset can be classified into two clusters as certain and uncertain data.

Uncertainty data’s are given as input for the Enhance random K-mode algorithm to cluster these data into different categories to find out uncertain values for each parameter to evaluate its efficiency. Then, we compare the output of the two algorithms to find the best one to predict uncertain values in climatic or weather conditions.

Algorithm Steps

Phase I:

a) Select K initial modes, one for each of the cluster.

b) Allocate data object to the cluster whose mode is nearest to it according to parameters like temperature, humidity etc.

c) Compute new modes of all clusters.

d) Repeat step 2 to 3 until no data object has changed cluster membership.

First, choose the cluster head by probability density function and then select the object nearby the cluster head. Now allot the object to cluster which is near to the object. Similarly compute for remaining modes of all the clusters. Repeat the above steps until the data object doesn’t change the cluster membership.

Phase II:

Pseudo code:

Input: Uncertain dataset from phase I

Output: uncertain clusters

1. Associate each data point to the most similar mode.

2. For each mode m for each non mode data o pick random value m and o and compute the total cost of the randomness.

3. Select the random value with the lowest cost.

4. Repeat steps 2 to 3 until the clusters are not changed.

In the second phase, uncertain data is taken as input from phase I and random k-mode algorithm is applied to get efficient clusters without lot of computations.

IV. DATASET DESCRIPTION

Weather dataset is taken and various readings for the past 4 years are taken from 2012 to 2015 consisting of temperature and humidity values. The dataset includes reading time, temperature, and speed of fan and some humidity details. The fundamental data includes the data relating to humid and temperature values taken at 100 samples per second.

Uncertain data are grouped into different clusters using phase I followed by Phase II of above algorithm. Month wise data is also taken and analyzed.

5.1 Temperature and Humidity values

The following example shows the different temperature and humidity values taken in the corresponding year.

```plaintext
2012 1 13.007 1 25.9 1 20.7 1 21 1 2013 1 11.03 1 21.96 1 17.87 1 17 1 2013 1 14.01 1 27.9 1 18.9 1 18 1 2014 1 17.87 1 17 1 20
```
n  - maximum humidity (%)  
u  - No of Uncertainty  
L  - separator

In the above example, the values represent the various temperature and humidity values which are taken in the corresponding years. Each reading is separated by a separator [6].

5.2 Dataset Setup

The dataset is collected from metrological department for the year 2010 to 2015 to predict the weather values in the year 2016 regarding climate changes due to uncertain temperature and humidity values.

We use dot net framework to implement the system. The dataset is collected month wise day wise for the past years.

V. RESULTS

Table 6.1 Weather Data Taken from different file

| Year | Min humidity | Max humidity | Mode Humidity | Uncertain Value |
|------|--------------|--------------|---------------|----------------|
| 2012 | 13.006       | 25.997       | 20.786        | 21             |
| 2013 | 11.003       | 21.967       | 17.876        | 18             |
| 2014 | 14.001       | 27.998       | 18.997        | 18             |
| 2015 | 13.889       | 16.893       | 14.988        | 19             |

Figure 6.1 Humidity values at different time

In the above graph, x-axis represents Year Wise Prediction values. By analyzing the graph we can conclude that the uncertain values depends mode values and the number of uncertain data decreases when the mode value decreases.

Table 6.2 weather Data temperature for year 2015

| Month | Temperature |
|-------|-------------|
| January | 49          |
| February | 50           |

Figure 6.2 Data taken from same Data set file

In the above figure, the x-axis represents months for year 2015. By the above graph we can analyze that the temperature for the year 2016 can be predicted.

VI. CONCLUSION

The traditional algorithms were focused for neither categorical nor numerical data, but our proposed method is suitable for all kinds of data. The above experiments are proved our enhanced k-Mode algorithm effectively with Gas Sensor’s numerical values. The K-Mode algorithm and Probability density calculations only used and so the complexity is also reduced. Moreover the computational cost is very low [7][8]. The accuracy in producing the resulting clusters is good.

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