Muon reconstruction and identification with the Run II D0 detector

V.M. Abazov, B. Abbott, B.S. Acharya, M. Adams, T. Adams, J.P. Agnew, G.D. Alexeev, N. Varelas, M. Alkhazov, A. Alton, M. Arthaud, A. Askew, S. Atkins, K. Augsten, C. Avila, F. Badaud, L. Bagly, B. Baldin, D.V. Bandurin, S. Banerjee, E. Barberis, P. Baringer, J.F. Bartlett, U. Bassler, V. Bazterra, A. Bean, M. Begalli, L. Bellantoni, S.B. Beri, G. Bernardi, R. Bernhard, I. Bertram, M. Besançon, R. Beuselinck, P.C. Bhat, S. Bhatia, V. Bhattagari, G. Blazej, S. Blessing, K. Bloom, A. Boehlein, D. Boline, E.E. Boos, G. Borissov, A. Brandt, O. Brandt, R. Brock, A. Bross, D. Brown, X.B. Bu, M. Buehler, V. Buescher, B. Bunichev, S. Burlin, C.P. Buszello, P. Calafayn, E. Camacho-Pérez, B.C.K. Casey, H. Castilla-Valdez, S. Caughron, S. Chakrabarti, K.M. Chan, A. Chandra, E. Chapon, G. Chen, S. Chevalier-Théry, S.W. Cho, S. Choi, B. Choudhary, D. Claes, C. Clément, J. Clutter, M. Cooke, W.E. Cooper, M. Corcoran, F. Coudere, M.C. Cousinou, A. CROC, D. Cutts, A. Das, G. Davies, S.J. De Jong, E. De La Cruz-Burelo, F. Deliò, R. Demina, D. Denisov, S.P. Denissen, S. Desai, C. Deterre, K. DeVaughan, H.T. Diehl, M. Diesburg, P.F. Ding, A. Dominguez, A. Dubey, L.V. Dudko, A. Duperrin, S. Dutt, M. Eads, D. Edmunds, J. Ellison, V.D. Elvira, Y. Enari, H. Evans, V.S. Evdokimov, L. Feng, T. Felber, F. Fiedler, F. Filthaut, W. Fisher, H.E. Fisk, M. Fortner, H. Fox, S. Fuess, T. Gadfort, A. Garcia-Bellido, J.A. García-González, V. Gavrilov, S. Geng, W. Geng, C.E. Gerber, Y. Gershtein, G. Ginter, H. Golovanov, P.D. Grannis, S. Greder, H. Greenlee, G. Grentier, 17. Ph. Gris, J.F. Grivaz, A. Grohsjean, S. Grünewald, M.W. Grünewald, T. Guillemin, G. Gutierrez, P. Gutierrez, J. Haley, L. Han, K. Harder, A. Harel, J.M. Hapke, J. Hays, T. Head, R. Hebbeker, D. Hedin, H. Hegaz, A.P. Heinson, U. Heintz, C. Hensel, I. Heredia-De La Cruz, K. Herner, G. Hesketh, M.D. Hildreth, R. Hirosky, T. Hoang, J.D. Hobbs, B. Hoeheisen, J. Hogan, M. Holfeld, J.L. Holzbauer, J. Hovey, Z. Hubacek, V. Hynek, I. Iashvili, Y. Ilchenko, R. Illingworth, A.S. Ito, S. Jabeen, M. Jaffe, A. Jayasinghe, M.S. Jeong, R. Jesik, P. Jiang, K. Johns, E. Johnson, M. Johnson, A. Jonckheere, P. Jonsson, J. Joshi, A.W. Jung, A. Juste, E. Kafzis, D. Karmanov, I. Katsoyan, R. Kehe, J. Kermiche, N. Khalatyan, A. Khanov, A. Kharchilava, Y.N. Kharchzeev, I. Kiselevich, J.M. Kohli, A.V. Kozelov, J. Kraus, A. Kumar, A. Kupco, T. Kurca, V.A. Kuzmin, S. Lammers, P. Lebrun, H.S. Lee, C. Lee, S.W. Lee, W.M. Lee, Y. Lee, J. Lellouch, V. Lesene, D. Li, H. Liu, L. Li, Z.Q. Li, J.K. Lim, D. Lincoln, J. Linnemann, V.V. Lipaev, R. Lipton, J. Linnemann, S. Lipton, A. Liu, J. Liu, S. Lobodenko, M. Lokajícek, R. Lopes de Sa, R. Luna-García, K. Luo, A.L. Lyon, A.A. Maciel, R. Madar, R. Magaña-Villalba, S. Malik, V.L. Malyshev, J. Mansour, J. Martínez-Ortega, R. McCarthy, C.L. McGivern, M.M. Meijer, A. Menhitchouk, D. Menezes, P.G. Mercadante, M. Merkin, A. Meyer, J. Meyer, F. Miconi, 10.K. Mondal, M. Mulders, M. Mulhearn, J.C. Murray, M. Narain, R. Nayyar, H.A. Neal, J.P. Negret, P. Neustroev, H.T. Nguyen, T. Nunnemann, E. Nurse, J. Orduna, N. Osman, 12. O. Sata, M. Pal, N. Parashar, V. Parihar, S.K. Park, R. Partridge, N. Parua, A. Patwa, B. Penning, M. Perifol, Y. Peters, K. Petridis, G. Petrollo, P. Pétrot, M.-A. Pleier, V.M. Podstavkov, A.V. Popov, M. Prewitt, D. Price, N. Prokopenko, J. Qian, Q. Quadt, B. Quinn, P.N. Ratoff, I. Razumov, I. Ripp-Baudot, F. Rizatdinova, A. Ross, C. Royon, P. Rubinov, R. Ruchti, G. Sajot, A. Sánchez-Hernández, M.P. Sanders, A.S. Santos, G. Savage, L. Sawyer, T. Scanlon, R.D. Schamberger, G. Schellman, G. Schwaneberger, R. Schwienhorst, J. Sekaric, H. Severini, B.C.K. Casey, H. Schellman, 47. G. Bernardi, 56. J. Sekaric, 52. H. Severini, 44. T. Sekaric, 47. H. Severini, 20. D. Sajot, 40. V. Saini, P. Skubic, 66. L. Satterley, 62. D. Smirnov, 50. G.R. Snow, J. Snow, S. Snyder, S. Södler-Rembold, L. Sonnenschein, K. Soustruznik, J. Stark, D.A. Stoyanova, M. Strauss, R. Ströhmer, L. Suter, P. Svoisky, 56. M. Titov, V.V. Tokmenin, Y.T. Tsai, D. Tsybychev, 53. T. Tuchming, C. Tully, 60. Uvarov, S. Uvarov, S. Uzunyan, R. Van Kooten, W.M. van Leeuwen, N. Varelas, E.W. Varnes, I.A. Vasilyev, A.Y. Verkheev, L.S. Vertogradov, M. Vesterinen, D. Vilanova, P. Vokac, 7. H.D. Wahl, M.H.L.S. Wang, J. Warchol, G. Watts, M. Wayne, J. Weichert, L. Welty-Rieger, M.R.J. Williams, G.W. Wilson, M. Wolbisky, D.R. Wood, T.R. Wyatt, Y. Xie, R. Yamada, S. Yang, T. Yasuda, Y.A. Yatsunenko, W. Ye, Z. Ye, H. Yin, K. Yip, S.W. Yoon.
J.M. Yu, J. Zennamo, T.G. Zhao, B. Zhou, J. Zhu, M. Zielinski, D. Zieminska, and L. Zivkovic
(The D0 Collaboration*)

1 LAFEX, Centro Brasileiro de Pesquisas Físicas, Rio de Janeiro, Brazil
2 Universidade do Estado do Rio de Janeiro, Rio de Janeiro, Brazil
3 Universidade Federal do ABC, Santo André, Brazil
4 University of Science and Technology of China, Hefei, People’s Republic of China
5 Universidad de los Andes, Bogotá, Colombia
6 Charles University, Faculty of Mathematics and Physics, Center for Particle Physics, Prague, Czech Republic
7 Czech Technical University in Prague, Prague, Czech Republic
8 Institute of Physics, Academy of Sciences of the Czech Republic, Prague, Czech Republic
9 University San Francisco de Quito, Quito, Ecuador
10 LPC, Université Blaise Pascal, CNRS/IN2P3, Clermont, France
11 LPSC, Université Joseph Fourier Grenoble 1, CNRS/IN2P3, Institut National Polytechnique de Grenoble, Grenoble, France
12 CPPM, Aix-Marseille Université, CNRS/IN2P3, Marseille, France
13 LAL, Université Paris-Sud, CNRS/IN2P3, Orsay, France
14 LPNHE, Universités Paris VI and VII, CNRS/IN2P3, Paris, France
15 CEA, Irfu, SPP, Saclay, France
16 IPHYS, Université de Strasbourg, CNRS/IN2P3, Strasbourg, France
17 IPNL, Université Lyon 1, CNRS/IN2P3, Villeurbanne, France and Université de Lyon, Lyon, France
18 III. Physikalisches Institut A, RWTH Aachen University, Aachen, Germany
19 Physikalisches Institut, Universität Freiburg, Freiburg, Germany
20 II. Physikalisches Institut, Georg-August-Universität Göttingen, Göttingen, Germany
21 Institut für Physik, Universität Mainz, Mainz, Germany
22 Ludwig-Maximilians-Universität München, München, Germany
23 Panjab University, Chandigarh, India
24 Delhi University, Delhi, India
25 Tata Institute of Fundamental Research, Mumbai, India
26 University College Dublin, Dublin, Ireland
27 Korea Detector Laboratory, Korea University, Seoul, Korea
28 CINVESTAV, Mexico City, Mexico
29 Nikhef, Science Park, Amsterdam, the Netherlands
30 Radboud University Nijmegen, Nijmegen, the Netherlands
31 Joint Institute for Nuclear Research, Dubna, Russia
32 Institute for Theoretical and Experimental Physics, Moscow, Russia
33 Moscow State University, Moscow, Russia
34 Institute for High Energy Physics, Protvino, Russia
35 Petersburg Nuclear Physics Institute, St. Petersburg, Russia
36 Institució Catalana de Recerca i Estudis Avançats (ICREA) and Institut de Física d’Altes Energies (IFAE), Barcelona, Spain
37 Stockholm University, Stockholm and Uppsala University, Uppsala, Sweden
38 Lancaster University, Lancaster LA1 4YB, United Kingdom
39 Imperial College London, London SW7 2AZ, United Kingdom
40 The University of Manchester, Manchester M13 9PL, United Kingdom
41 University of Arizona, Tucson, Arizona 85721, USA
42 University of California Riverside, Riverside, California 92521, USA
43 Florida State University, Tallahassee, Florida 32306, USA
44 Fermi National Accelerator Laboratory, Batavia, Illinois 60510, USA
45 University of Illinois at Chicago, Chicago, Illinois 60607, USA
46 Northern Illinois University, DeKalb, Illinois 60115, USA
47 Northwestern University, Evanston, Illinois 60208, USA
48 Indiana University, Bloomington, Indiana 47405, USA
49 Purdue University Calumet, Hammond, Indiana 46323, USA
50 University of Notre Dame, Notre Dame, Indiana 46556, USA
51 Iowa State University, Ames, Iowa 50011, USA
52 University of Kansas, Lawrence, Kansas 66045, USA
53 Louisiana Tech University, Ruston, Louisiana 71272, USA
54 Northeastern University, Boston, Massachusetts 02115, USA
55 University of Michigan, Ann Arbor, Michigan 48109, USA
56 Michigan State University, East Lansing, Michigan 48824, USA
57 University of Mississippi, University, Mississippi 38677, USA
58 University of Nebraska, Lincoln, Nebraska 68588, USA
59 Rutgers University, Piscataway, New Jersey 08855, USA
We present an overview of the muon reconstruction and identification methods employed by the D0 collaboration to analyze the Run II (2001–2011) $p\bar{p}$ data of the Fermilab Tevatron collider at $\sqrt{s} = 1.96$ TeV. We discuss the performance of these methods, how it is measured using D0 data, and how it is properly modeled by the D0 simulation program. In its pseudorapidity acceptance, $|\eta| < 2$, the muon system identifies high-$p_T$ muons ($p_T \gtrsim 10$ GeV) with efficiencies ranging from 72% to 89%. Muons tracks are reconstructed in the D0 central tracking system with efficiencies ranging from 85% to 92% and with a typical relative momentum resolution of 10% for $p_T = 40$ GeV. Isolation criteria reject multijet background with efficiencies of 87% to 99%.

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I. INTRODUCTION

Muon reconstruction and identification are cornerstones of the D0 Run II physics program at the Fermilab Tevatron $p\bar{p}$ collider. Muons of high transverse momentum ($p_T \gtrsim 10$ GeV) with no extra calorimeter or tracking activity around them are a signature of electroweak boson decays ($W \rightarrow \mu\nu$, $Z/\gamma^* \rightarrow \mu\mu$), allowing the study of electroweak physics, top quark physics ($t \rightarrow Wb$), and Higgs boson physics ($WH$, $ZH$ production, $H \rightarrow WW$ decay). Lower-$p_T$ muons, resulting for example from the semi-leptonic decays of heavy flavor quarks or from $J/\psi \rightarrow \mu\mu$ decay, give access to a rich flavor physics program.

In this article, we present an overview of the muon reconstruction and identification methods employed by the D0 experiment to analyze the Run II (2001–2011) $p\bar{p}$ data of the Fermilab Tevatron collider at $\sqrt{s} = 1.96$ TeV. We discuss the performance of these methods, how it is measured using D0 data, and how it is properly modeled by the D0 simulation program. In its pseudorapidity acceptance, $|\eta| < 2$, the muon system identifies high-$p_T$ muons ($p_T \gtrsim 10$ GeV) with efficiencies ranging from 72% to 89%. Muons tracks are reconstructed in the D0 central tracking system with efficiencies ranging from 85% to 92% and with a typical relative momentum resolution of 10% for $p_T = 40$ GeV. Isolation criteria reject multijet background with efficiencies of 87% to 99%.

II. OVERVIEW OF THE D0 DETECTOR AND ITS MUON SYSTEM

Figure 1 presents a cross sectional view of the Run II D0 detector [5–8]. The detectors surrounding the interaction region include a silicon microstrip detector (SMT) for precision tracking of charged particles and determination of the primary vertex and secondary decay vertices, a scintillating fiber tracker (CFT) for precise track reconstruction, a 2 T solenoidal magnet for momentum determination of charged particles, preshower detectors, and the liquid-argon uranium calorimeters with electromagnetic, fine, and coarse hadronic sections. The muon system, which is described in detail in Ref. [9], resides
outside the calorimeter system and its main components are identified in Fig. 1. The identification of muons relies mainly on the muon system; however, other D0 components, namely the solenoid, CFT, SMT and calorimeter, are used to measure the muon momentum and estimate whether a muon is isolated, i.e., there is no extra calorimeter or tracking activity around the particle.

The D0 coordinate system is right-handed, with the $z$-axis pointing in the direction of the Tevatron proton beam and the $y$-axis pointing upwards. The angles $\phi$ and $\theta$ are the azimuthal and polar angles relative to the $x$- and $z$-axes, respectively. We also use as an angular variable the pseudorapidity defined by $\eta = \ln[\tan(\theta/2)]$.

The Run II muon system design is based on the extensive experience obtained with the Run I (1992–1996) muon spectrometer [10] consisting of two muon systems: the wide angle muon system and the small angle muon system. The wide angle system, covering the pseudorapidity region $|\eta| \lesssim 2.0$, consisted of proportional drift tubes (PDTs) and three large iron toroidal magnets: a central toroid (CF) and two end toroids (EFs). The small angle system, covering $2.0 \lesssim |\eta| \lesssim 3.0$, consisted of a set of drift tube planes and two small iron toroids. For Run II, the small angle system was completely removed and the small angle magnets were replaced by new shielding assemblies. In the forward region ($1.0 \lesssim |\eta| \lesssim 2.0$), the PDT chambers were replaced by a new tracking system. The three main toroids in the muon magnet system, the CF and the two EFs, were not changed, except that the current was reduced by 40% yielding substantial operating cost savings. As the operating point of Run I was close to the magnetic saturation in iron, the reduced current resulted in a 6% lower magnetic field of 1.8 T. This small change did not degrade the overall performance, since the addition of the solenoid for Run II provided precision measurements of charged particle momenta close to the interaction region.

The Run II muon system consists of one layer of muon detectors before the toroidal magnet and two similar layers of detectors after the magnet. This provides the ability to reconstruct and measure the muon track parameters, including the muon momentum. The three layers of the muon system are referred to as A, B, and C, as indicated in Fig. 1. For the purposes of triggering and muon track reconstruction, a system of fast scintillation counters with time resolution of $\sigma(t) \approx 2$ ns is used in Run II. In the central muon system ($|\eta| \lesssim 1.0$) there are 630 scintillation counters in the A-layer (referred to as A$\phi$ counters), with an angular segmentation of 79 mrad in $\phi$, and 372 counters in the C-layer (referred to as outer counters). In the forward region, a total of 4214 scintillation counters (referred to as pixel counters) are used in the A, B, and C layers, providing three independent coordinate and time measurements along muon tracks. They have a segmentation of approximately 0.1 in $\eta$ and approximately 79 mrad in $\phi$.

The muon system tracking detectors consist of PDTs in the central rapidity region ($|\eta| \lesssim 1.0$) and mini drift tubes (MDTs) in the forward region ($1.0 \lesssim |\eta| \lesssim 2.0$). Both PDTs and MDTs are installed in the three layers, A, B, and C (see Fig. 1), which consist of 4, 3, and 3 detection planes, respectively (except the bottom A-layer PDTs which have three planes). The PDTs and MDTs provide high-accuracy coordinate measurements with a resolution of approximately 1 mm in the direction perpendicular to the sensitive wires which are arranged parallel to the toroidal field lines. The PDTs have also Vernier pads [11], but only those of layer A are read out to determine the position of the muon hits along the wires.

Because of energy loss in the calorimeter, a muon produced in the $pp$ interaction region must have a minimum energy of 2 to 2.5 GeV, depending on $|\eta|$, to pass through the calorimeter and reach layer A of the muon system, as shown in Fig. 2. Similarly, the muon energy must be at least 3 to 5 GeV to pass through both the uranium calorimeter and the iron toroid to reach all instrumented layers of the muon system.

III. MUON RECONSTRUCTION

To reconstruct muon trajectories, the same algorithm is used in the forward and central regions. A list of hits from the muon detector is first built. These hits are associated to form muon track segments, which are then used to form tracks in the muon system, called local tracks. The local tracks and the segments not used in the reconstruction of local tracks are generically called local muons. In a last step the local muons are matched to tracks reconstructed in the central tracking system. The details of these different steps are discussed below.

A. Hit finding

For the forward system, the $\phi$ coordinate is determined by the scintillation counters. As each counter covers 79 mrad, the $\phi$ resolution in each layer is approximately $79/\sqrt{12} = 23$ mrad.

For the central system, the $\phi$ coordinate is determined by both the central counters and the PDTs. Similarly to the forward scintillation counters, the measurement of $\phi$ in the central A-layer counters has a resolution of approximately $23$ mrad. In each of the three layers, the wires of the PDTs are ganged together in pairs at one end of each chamber and read out by electronics located at the other end of the chamber. To obtain the $\phi$ coordinate, the PDTs measure the hit position along the wire using the time difference of the signal arrival between each end of the pairs. After correcting for a non-linearity in the response for those hits with a time difference above 75% of the maximum value, position resolutions per wire of 15 cm are obtained. For the A-layer only, the Vernier pads are combined with the time division and scintillator position, which resolve the pad ambiguity and reduce the
FIG. 1: Cross sectional side view of the D0 detector at the beginning of Run II. The abbreviations CF, EF, MDT, and PDT stand for central toroid, end toroids, mini drift tubes, and proportional drift tubes, respectively.

position resolution to about 2 mm, which corresponds to about 7 mrad.

The time of passage of a particle in a layer of the muon system is given by the corresponding scintillator time. Each scintillator time is adjusted based on the path length from the D0 detector center to the scintillating element, so that a particle produced in a $p\bar{p}$ collision and traveling at the speed of light will have an expected time of zero. Given the size of the central counters, a correction is needed to account for the time it takes for the light produced in the scintillator to reach the phototube. It is found to be about 0.05 ns cm$^{-1}$ for all counters, consistent with the speed of light in the scintillating material. Including the correction improves the time resolution from 2.1 ns to 2.0 ns for the A-layer counters, and from 4.5 ns to 3.8 ns for the large C-layer counters on the sides and top. The bottom B- and C-layer counter resolutions are improved from 3.7 ns and 3.5 ns to 3.1 ns and 2.5 ns, respectively.

For both the central and forward muon systems, the drift time of the wire chambers is used to measure the impact position of a muon perpendicular to the wire. The time-to-distance relation is not linear and depends on the muon incidence angle because of the geometry of the drift tubes. In the first iteration, the muon track is assumed to be orthogonal to the drift chambers, then the segment direction is used. Both the left and right ambiguity in the drift time are treated as individual hits. The position resolution of both the MDT and PDT systems is approximately 1 mm, primarily due to the position accuracy of the wire.
B. Segment reconstruction

In a first step, 2D segments in the deviation plane, i.e., the plane orthogonal to the toroidal magnetic field and the wires, are found in each of the A-, B-, and C-layers using the drift times from the MDT and PDT systems. In each layer, all possible pairs of wire hits form the first segments. They are then iteratively merged using a fit to a straight line. The $\chi^2$ of the fit procedure is used to measure the segment quality. Segments in the B- and C-layers are combined if they are consistent with being on a single straight line. In the following, we denote as a BC-segment either a single B- or C-segment, or the combination of a B- and a C-segment. The final 2D segments require at least two wire hits in different planes. If a pair of wire hits in different planes of a given layer is part of a segment composed of three or more planes, then only the segment with the highest hit multiplicity is retained.

After 2D segments are found, scintillator hits are associated with each segment if they agree with the $\eta$ position for the forward system and both the $\eta$ position and $\phi$ position for the central system. At $|\eta|$ near 1.0, a single particle can go through both the PDT and MDT systems and segments made from each system are combined if they are consistent with a single track. The typical segment position resolution perpendicular to the wires is 0.7 mm while the segment angular resolution is around 10 mrad for A-segments and 0.5 mrad for BC-segments.

A single muon can produce multiple segments, for example, due to left-right ambiguities of the drift time. To reduce combinatorics, only the three highest-quality segments arising from a given cluster of hits are kept for the A-layer and only the two highest-quality segments for the BC-layer. The remaining ambiguities are resolved by the local track finding.

C. Local muon track finding

Segments in the A-layer before the toroid and BC-layer after the toroid are paired if they are consistent with the passage of a single particle through the toroid. Non-paired A- and BC-segments are retained in the list of local muons because muons can still be identified if the segments are matched to central tracks using the algorithm described in the next section.

For each compatible pair of segments, a muon track is reconstructed from a fit taking into account the magnetic field strength, energy loss, and multiple Coulomb scattering in the toroids. Figure 4 illustrates the method and shows the different parameters and terms involved in the fitting procedure. The covariance matrix for the random displacement in position and direction of a track due to multiple scattering in a continuous material can be accurately reproduced by just two independent random changes of direction, $\theta_{MS1}$ and $\theta_{MS2}$, if they occur at the location $t\left(\frac{1}{2} + \frac{1}{\sqrt{12}}\right)$ and $t\left(\frac{1}{2} - \frac{1}{\sqrt{12}}\right)$ along the track, where $t$ represents the thickness of the material traversed [12]. Using this property, the five fitted parameters defined in the deviation plane are therefore the two scattering angles, $\theta_{MS1}$ and $\theta_{MS2}$; the track position coordinate at...
layer A along the direction contained in the wire chamber plane and perpendicular to the wires, $z_A$ in the example of Fig. 4; the track angle at layer A, $\theta_A$; and the curvature $q/p_{\text{dev}}$, where $q$ is the muon charge and $p_{\text{dev}}$ is the muon momentum at layer A projected to the deviation plane ($p_{\text{dev}} = \sqrt{p_x^2 + p_y^2}$ in the example of Fig. 4).

The fit parameters define the propagation of the muon track from the A-layer to the BC-layer by sequential small displacements, accounting for the deviation due to the magnetic field, energy loss, and the deviation induced by the multiple scattering if crossing one of the multiple scattering planes. The fit is performed by a least squares method, where the $\chi^2$ is constructed from four terms comparing the positions and angles of the track at the A- and BC-layers to the segments’ parameters, and two terms comparing the two scattering angles to their expected null value.

Once the fit has converged, the 3D track parameters are determined from the $\phi$ coordinate of the segments. To obtain the momentum ($p$) at the $pp$ hard scattering vertex, an estimate of the energy loss in the calorimeter, depending on the particle momentum and rapidity, is added to the value determined at the A-layer. The resolution of the momentum determined solely by the muon system depends on $\eta$ and on whether the track has both B- and C-layer hits. This resolution can be measured by computing the difference between the local muon momentum and the matched central track momentum. The results found for different types of local tracks and regions are given in Table I. Primarily due to multiple scattering in the iron toroid, these resolutions are significantly worse than those obtained by the central tracking system, which is about $\frac{\sigma(p)}{p} = 0.021 \oplus 0.0025 \cdot p_T/$GeV at $\eta = 0$ (see Sec. V F).

For a high-$p_T$ muon within the acceptance of the muon system, the efficiency of the local track reconstruction is around 85%, which includes the small fraction ($<5\%$) of non-converged fits. As noted previously, several segments are kept for a given group of hits. The $\chi^2$ of the local track fit as well as the number of hits in the segments are used to choose which pair of segments is the best solution.

**D. Matching with central tracking**

To improve the resolution of the muon momentum, local tracks are matched to the precisely measured tracks of the central tracking system. The matching is performed by propagating the tracks through the calorimeter, taking into account the inhomogeneous magnetic field, energy loss, and multiple scattering.

We consider a relativistic particle of charge $q$, mass $m$ with initial position and momentum ($\vec{x}^\text{in}, \vec{p}^\text{in}$). After traveling an infinitesimal distance $ds$ in a material, its position and momentum become ($\vec{x}^\text{out}, \vec{p}^\text{out}$), which can be written:

\begin{align*}
\vec{x}^\text{out} &= \vec{x}^\text{in} + \frac{\vec{p}^\text{in}}{|\vec{p}^\text{in}|} ds, \\
\vec{p}^\text{out} &= \vec{p}^\text{in} \left(1 - \frac{dE_{\text{loss}}}{|\vec{p}^\text{in}|}\right) + \vec{\Omega}^B \times \vec{p}^\text{in} + \delta\vec{\Omega}^{MS} \times \vec{p}^\text{in}.
\end{align*}

In these equations, $dE_{\text{loss}}$ represents the random energy loss in the calorimeter. Once integrated over the calorimeter thickness, the mean value of energy loss is around 3 GeV and its RMS is about 0.4 GeV. The term:

\begin{equation}
\vec{\Omega}^B = -0.3 \frac{q}{|\vec{p}^\text{in}|} \vec{B} ds,
\end{equation}

accounts for the curvature due to the magnetic field (where the unit for the coefficient 0.3 is GeV·T$^{-1}$.m$^{-1}$), and the term:

\begin{equation}
\delta\vec{\Omega}^{MS} = \frac{\delta\vec{\beta}}{|\vec{v}|} \left(\cos \alpha \vec{z} + \sin \alpha \vec{v}\right),
\end{equation}

represents the effects of the multiple scattering, where $\delta\vec{\beta}$ denotes the infinitesimal deviation from the momentum direction, $\vec{z}$ is an arbitrary direction different from the momentum direction, $\vec{v}$ is defined as $\vec{v} = \vec{z} \times \frac{\vec{p}^\text{in}}{|\vec{p}^\text{in}|}$, and $\alpha$ is a random angle defining the direction of the deviation. In a similar manner, it is possible to write the propagation of the track parameter error matrix [13].

This set of equations allows the propagation (with their respective error matrices) of either the local tracks inward to the center of the D0 detector or the central tracks outward to the muon system. For local tracks, the inward propagation has precedence over the outward propagation. For non-paired A-segments, non-paired BC-segments, and local tracks without a converged local fit,
only the outward propagation is sensible since there is no accurate measurement of the local muon momentum. In all cases, the quality of the matching between a local muon of parameters $P_m$ and error matrix $V_m$ and a central track $P_c$ with error matrix $V_c$ is evaluated by a $\chi^2$ test:

$$\chi^2 = (P_m - P_c)^T \cdot (V_m + V_c)^{-1} \cdot (P_m - P_c).$$  \hspace{1cm} (5)

The minimum $\chi^2$ is used to choose which central track is matched to each of the local muons.

E. Momentum measurement

Since the local muon momentum resolution is inferior to the resolution from the central tracking system, the momentum of a muon matched to a central track is taken to be the momentum measured in the central tracker. Non-paired A- and BC-layer segments matched to central tracks also define muon objects, the momenta of which is taken from the matched tracks.

For muon candidates matched to central track without SMT hit, the additional constraint that the track arises from the beam axis located at $(x_b, y_b)$ is used. This constraint yields a correction for the track curvature $\kappa$, which is given to first order by

$$\kappa \rightarrow \kappa + (x_b \sin \phi_0 - y_b \cos \phi_0 - d_0) \frac{V_{cd}}{V_{dd}},$$  \hspace{1cm} (6)

where $d_0$ is the distance of closest approach to the central axis $(x, y) = (0, 0)$, $\phi_0$ is the track azimuthal angle at the point of closest approach, and $V_{cd}$ and $V_{dd}$ are elements of the covariance matrix resulting from the central track reconstruction fit. $V_{cd}$ is the covariance between $\kappa$ and $d_0$, while $V_{dd}$ is the squared uncertainty on $d_0$. The correction is propagated to the track transverse momentum which is proportional to $\frac{1}{\kappa}$. Central tracks without hits in the SMT have a relative resolution on transverse momentum $\frac{\sigma(p_T)}{p_T}$ of typically 25% for $p_T = 45$ GeV. The correction improves the relative resolution to 15%–18%, compared to the typical resolution of 10% for tracks with SMT hits.

IV. MUON IDENTIFICATION

A muon candidate is primarily defined by (i) the presence of a local muon in the muon system. Additionally, for most physics analyses, the local muon has to to be (ii) matched to a track in the central tracker. For high-$p_T$ physics, (iii) the absence of significant activity around the muon trajectory, both in the calorimeter and in the central tracker may also be demanded. For each of these three criteria, different identification quality categories are defined, which are briefly presented in the following sections. The efficiencies for the different categories and the experimental techniques used to measure them in data and simulated events are summarized in Sec. V.

Despite the relatively high amount of energy lost by a muon in the calorimeter, the energy deposit of muons in an individual cell is close to the threshold level of the calorimeter noise-suppression algorithm [14], and is therefore not well measured. Thus, the calorimeter information is not exploited to identify high-$p_T$ muons but is used for muon identification in heavy flavor analyses.

A. Identification criteria in the muon system

For the identification of local muons, three categories, loose, medium, and tight, are defined as follows.

- A local muon is loose if (a) it has at least one scintillator hit and at least two wire hits in the A layer of the muon system, or (b) at least one scintillator hit and at least two wire hits in the BC layers.
- In the general case, a local muon is medium if it meets both conditions (a) and (b), except that for $|\eta| < 1.6$, the BC scintillator requirement is dropped. For the particular case of the bottom part of the detector where the support structure

| Region | Muon type | Parametrization for $\frac{\sigma(p_T)}{p_T}$ ($p$ and $p_T$ in GeV) |
|--------|-----------|---------------------------------------------------------------------|
| $|\eta| < 0.88$ | ABC | $\frac{p}{p_T} [0.21 \pm 0.011(p_T - 2)]$ |
| $|\eta| < 0.88$ | AB or AC | $\frac{p}{p_T} [0.21 \pm 0.016(p_T - 1.3)]$ |
| $0.88 < |\eta| < 1.1$ | ABC | $\frac{p}{p_T} [0.28 \pm 0.006(p - 2)]$ |
| $0.88 < |\eta| < 1.1$ | AB or AC | $\frac{p}{p_T} [0.30 \pm 0.009(p - 2)]$ |
| $1.1 < |\eta| < 1.7$ | ABC | $\frac{p}{p_T} [0.215 \pm 0.007(p - 3)]$ |
| $1.1 < |\eta| < 1.7$ | AB or AC | $\frac{p}{p_T} [0.28 \pm 0.029(p - 3)]$ |
| $1.7 < |\eta| < 2.0$ | ABC | $\frac{p}{p_T} [0.24 \pm 0.005(p - 2.5)]$ |

TABLE I: Parametrization for the local muon track momentum resolution for different categories of muons.

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*The transverse beam position is determined by averaging the primary vertex position over multiple beam crossings. The beam is up to two millimeters away from $(0, 0)$ in the detector coordinate system.*
for the calorimeter is located (\(\frac{T}{p} < \phi < \frac{T}{p}\) and |\(\eta| < 1.6\)), a local muon is medium if it fulfills either condition (a) or (b) above. In the particular case of a low-\(p_T\) muon, a local muon is medium if it fulfills condition (a) above and, additionally, its probability to reach the BC-layers is less than 70% (due to energy loss in the toroid).

- A local muon is tight if it belongs to the category of medium muons that meet both conditions (a) and (b), except that for |\(\eta| < 1.6\), the BC scintillator hit times in each layer, if available, be consistent within 10 ns with those of a particle moving at the speed of light from the primary vertex. It has a typical efficiency of about 98.5% for high-\(p_T\) muons.

B. Identification criteria in the central tracker

For the identification of muon tracks in the central tracking system, four quality categories are defined: loose, medium, medium SMT, and tight, as follows.

- A muon track containing SMT hits is defined as loose if |\(dca| < 0.04\) cm, where \(dca\) is the track distance of closest approach to the beam axis. This requirement is changed to |\(dca| < 0.2\) cm for tracks without SMT hits. The loose quality is a good choice for analyses that do not need the most accurate muon momentum measurement.

- A muon track is tight if it fulfills the loose requirements and if \(\chi^2/N_{DOF} < 4\), where \(\chi^2\) is the result of the fit used for reconstruction of the track in the central tracking system and \(N_{DOF}\) is the number of degrees of freedom. This \(\chi^2\) requirement introduces notable efficiency losses because of wrongly assigned hits arising from tracks from other \(pp\) interactions in the same bunch crossing at luminosityb higher than typically 150 \(\times 10^{30}\) cm\(^{-2}\)s\(^{-1}\). To overcome this issue, the medium quality has been defined using looser \(\chi^2\) requirements.

- A muon track is defined as medium if it is of loose quality and if, in addition, \(\chi^2/N_{DOF} < 9.5\). Furthermore, at least two hits in the CFT are required to further discriminate against accidental combinations of hits in the SMT at high instantaneous luminosity.

- A muon track is medium SMT if it fulfills the medium requirements and, in addition, has hits in the SMT. This results in a lower rate from fake and misreconstructed tracks, and also better momentum resolution compared to the other categories (see Sec. V C).

C. Identification of isolated muons

We select isolated muons arising from the primary vertex by rejecting secondary muons from semi-leptonic decays of b or c quarks, which are surrounded by additional particles due to quark fragmentation and other heavy hadron decay products. Three basic discriminating variables are formed as follows.

- \(\Delta R(\mu,\text{jet}) = \sqrt{\Delta \eta^2(\mu,\text{jet}) + \Delta \phi^2(\mu,\text{jet})}\), is the closest distance in \((\eta, \phi)\) space of the muon to any jet with \(p_T > 15\) GeV, where the jets are reconstructed from energy deposits in the calorimeter using an iterative midpoint cone algorithm [15] with a cone radius \(R = 0.5\).

- \(T^{\text{trk}} = \sum_{\text{tracks}} p_T^{\text{track}}\) is the scalar sum of transverse momenta of all tracks inside a \(\Delta R(\mu, \text{track}) < 0.5\) cone around the muon track with the exception of the muon track itself. To reject the contributions of tracks arising from other \(pp\) interactions in the same bunch crossing, the requirement \(\Delta z_0(\mu, \text{track}) < 2\) cm is demanded for each track in the sum, where \(z_0\) is the coordinate of the track at the point of closest approach to the beam axisc.

- \(T^{\text{cal}} = \sum_{\text{clusters}} E_T^{\text{cluster}}\), is the scalar sum of transverse energies of all calorimeter clusters inside a hollow cone around the muon defined by \(0.1 < \Delta R(\mu, \text{cluster}) < 0.4\). Only the energy deposits in the electromagnetic calorimeter and the first fine sampling layers of the hadron calorimeter are considered to reduce the impact of noise and other \(pp\) interactions in the same bunch crossing.

We also employ as isolation variable \(T^{\text{trk}}/p_T^\mu\) and \(T^{\text{cal}}/p_T^\mu\), which offer higher efficiencies for high-\(p_T\) muons and more stringent rejection against secondary leptons from b- and c-quark decays at low \(p_T\). Because of the \(\Delta z_0(\mu, \text{track}) < 2\) cm requirement which rejects tracks from other \(pp\) interactions in the same bunch crossing efficiently, the quantities \(T^{\text{trk}}\) and \(T^{\text{trk}}/p_T^\mu\) are more robust at high instantaneous luminosity conditions, compared to \(T^{\text{cal}}\) and \(T^{\text{cal}}/p_T^\mu\).

Based on these five variables, several isolation criteria are defined as shown in Table II.

\(^b\) Over the course of Run II, the distribution of luminosity ranges from 1 to \(400 \times 10^{30}\) cm\(^{-2}\)s\(^{-1}\). Its average value is around \(140 \times 10^{30}\) cm\(^{-2}\)s\(^{-1}\) with a RMS of \(70 \times 10^{30}\) cm\(^{-2}\)s\(^{-1}\).

\(^c\) The beam interaction region is distributed along the z-axis following approximately a Gaussian function of width \(\simeq 25\)–30 cm.
The performance of the muon reconstruction can be quantitatively assessed in terms of identification efficiency, fake rate, and momentum resolution. The methods to measure these performances for high-$p_T$ muons and the results are discussed below. More details can also be found in Refs. [16, 17].

### B. Efficiency of muon system reconstruction

The tag-and-probe selection for the measurement of the efficiency of the D0 muon system to identify and re-
construct muons is summarized as follows. The tag object is required to be a local medium muon matched to a central track of tight quality with \( p_T > 30 \) GeV and isolated with \( \Delta R < 2.5 \) GeV. It must have fired a single muon trigger and the absolute value of the A or B layer scintillator time has to be less than 7 ns. The probe is required to be a central track of quality tight with \( p_T > 20 \) GeV and isolated with \( \Delta R < 2.5 \) GeV, matched within \( \Delta R < 0.5 \) to the local muon track. The tag and the probe tracks have to be of opposite electric charge, and have to fulfill \( |\Delta z_0| < 2 \) cm and \( \Delta R > 2 \). Cosmic rays are suppressed by demanding \( \pi - |\phi_{tag} - \phi_{probe}| + |\pi - \theta_{tag} - \theta_{probe}| > 0.05 \).

The measured efficiencies for loose, medium, and tight muons are shown in Fig. 6 as functions of \( \eta_{detector} \) and \( \phi \), where \( \eta_{detector} \) is the angular coordinate (with respect to the center of the D0 detector) of the position where the muon trajectory traverses the A-layer of the muon system. Note that because of the spread in \( z \) of the primary vertex distribution, \( \eta_{detector} \) can be different from the actual pseudorapidity of the muon. In the figure, the bin-to-bin rapid variations of the measured efficiencies are due to the small non-instrumented part of the detector between the wire chambers, and, to a lesser extent, between the scintillators. Because of the support structure of the calorimeter, the bottom part of the muon system is less instrumented which is reflected in lower efficiency for \( 2 < \eta < 3 \) and \( |\eta_{detector}| < 1.6 \). The average reconstruction efficiencies are 88.9%, 80.8%, and 72.0% for the loose, medium, and tight operating points, respectively. If the cosmic veto is not required, these efficiencies increase to 90.9%, 82.5%, and 73.1%, respectively. The statistical uncertainty on these efficiencies is of the order of 0.1% and thus negligible. We consider various sources of systematic uncertainty that may bias the measurement of these efficiencies. The dominant source of relative systematic uncertainty is possible background contamination (0.8%–1.1%), with smaller contributions from \( p_T^2 \) dependence (0.3%), from the tag-and-probe technique (0.2%), and from pattern recognition (0%–0.4%). The relative uncertainties amount in total to 0.9%–1.2%.

There are only minor changes in the identification efficiency of the muon system over the course of Run II. A small fraction of this effect is due to a slight dependence on instantaneous luminosity, while most of it is driven by the number of operating PDTs. The efficiency of single hit reconstruction and assignment to tracks is dominated by alignment effects. Variations over the course of Run II are small.

C. Efficiency of muon central track reconstruction

The tag-and-probe selection for the measurement of the efficiency of the D0 central tracker to reconstruct muon tracks is summarized as follows. The tag object is required to be a local loose muon matched to a central track of tight quality with \( p_T > 30 \) GeV and \( |dca| < 0.2 \) mm, and isolated with \( \Delta R < 3.5 \) GeV and \( \Delta \eta < 2.5 \) GeV. The probe is a local muon track of loose quality, with \( p_T > 15 \) GeV as measured in the muon system, and isolated with \( \Delta \eta < 2.5 \) GeV. The tag and the probe must fulfill \( \Delta R > 2 \), and their respective scintillator hit times at either the A- or B-layer have to match within a 6 ns window. For these events, the trigger requirement consists of a dimuon trigger with no explicit central track condition.

The measured efficiencies are shown in Fig. 7, as a function of \( \eta_{CFT} \), \( z_0 \) and luminosity, where \( \eta_{CFT} \) is the angular coordinate of the outermost intercept between the muon trajectory and the CFT detector volume. The average efficiencies are 91.6%, 90.5%, 84.6%, and 86.2%, for the loose, medium, mediumSMT, and tight operating points, respectively. Various sources of relative systematic uncertainty that may bias our efficiency measurement are considered: modeling of the primary...
vertex position along the beamline (0.7%–0.8%), possible background contamination (0.5%), the tag-and-probe technique (0.3%), and the jet multiplicity in the final state (0.1%–1.4%). The relative statistical uncertainty is of the order of 0.1% and thus negligible with respect to the total systematic uncertainty. The relative uncertainties amount in total to 1.1%–1.6%.

There were changes, some of them substantial, in the reconstruction efficiency of muon tracks in the central tracker over the course of Run II. The most significant changes, resulting in an increase of the track reconstruction efficiency of the order of 1% despite detector aging effects, occurred in 2006 after 1 fb\(^{-1}\) of data had been collected, when an additional Layer 0 was installed in the SMT [7]. A similar increase occurred in 2009 after 6 fb\(^{-1}\) of data had been collected, when a large fraction of the non-responsive modules of the SMT were recovered. The pronounced dependence of the track reconstruction efficiency on instantaneous luminosity resulted in an increasingly adverse effect in the second half of Run II. As the detector aged, the reconstruction efficiency decreased in the central region of the CFT and, to a smaller degree, in the inner layers of the SMT towards the end of Run II. The former effect is attributed to reduced scintillation light yield resulting from radiation damage, which has the largest impact on reconstruction efficiency at central pseudorapidity due to the smaller effective path length of the muons through individual fibers at those pseudorapidities. The reduction in reconstruction efficiency in the inner layers of the SMT is attributed to radiation damage to the silicon sensors. As a result, their operating high voltage had to be increased in order to fully deplete the sensor. However, this voltage is limited to 150 V for the inner SMT barrel layers (except Layer 0), thus resulting in a reduced active sensitive region for some of the inner sensors towards the end of data taking. The innermost Layer 0 remained fully depleted throughout Run II.

D. Efficiency of isolation requirements

The tag-and-probe selection for the measurement of the isolation efficiency is summarized as follows. Both the tag and probe objects are required to be local muons of loose quality, with \(p_T > 8\) GeV, matched to central tracks of loose quality, with \(p_T > 15\) GeV and \(|dca| < 0.4\) (2) mm if matched (not matched) to hits in the SMT. In addition, the tag muon has to be isolated according to \(\mathcal{I}\) \(< 2.5\) GeV and \(\mathcal{I}_{\text{cal}} < 10\) GeV, and a dimuon trigger with no explicit isolation requirement has to have fired. The tag and the probe tracks have to be of opposite charge and must fulfill \(|\Delta z_0| < 2\) cm, \(\Delta R > 2\), \(\pi - |\phi_{\text{tag}} - \phi_{\text{probe}}| + |\pi - \theta_{\text{tag}} - \theta_{\text{probe}}| > 0.05\), and 70 GeV \(< m_{\mu\mu} < 120\) GeV.

A sample of measured efficiencies for the operating points defined in Table II is shown in Fig. 8 as functions of \(\eta_{\text{CFT}}, p_T\), and luminosity. All these efficiencies are measured with respect to the jetIso criterion \((\Delta R(\mu,\text{jet}) < 0.5)\) to factorize out the dependence on event topology. The jetIso criterion has an efficiency of 95.8% for the particular topology of inclusive \(Z/\gamma^* \rightarrow \mu^+\mu^-\) selection.

The average efficiencies relative to the jetIso criterion are reported in Table III. They are in the range 87.3% to 98.6%. For each criteria, the relative statistical uncertainty is of the order of 0.1% and thus negligible. We consider various sources of relative systematic uncertainty that may bias our measurement of the isolation efficiency: potential tag-and-probe biases (0.3%), possible background contamination (0.2%), correlation to the identification of muons in the muon system (0.1%) and to the reconstruction of tracks in the central tracker (0.1%), as well as the mismodeling of the luminosity spectrum (0.1%–0.8%). The total relative uncertainty amounts to 0.4% for the efficiency of the jetIso criterion. For the efficiencies of the other operating points with respect to the jetIso criterion, the total

**FIG. 7**: [color online] Efficiencies of the identification criteria (loose, medium, mediumSMT, and tight) in the tracking system as functions of (a) \(\eta_{\text{CFT}}\), (b) \(z_0\), and (c) instantaneous luminosity (L).
isolation (one of the reasons why working points using mostly track the tracks considered in the isolation calculation. This is from the requirement ∆p tracking system are less affected by the presence of other pronounced dependence on instantaneous luminosity. were defined. The tight criteria measured with respect to the jetIso criterion. TABLE III: Average efficiencies for the different isolation criteria measured with respect to the jetIso criterion.

| Operating point | Efficiency (%) relative to ∆R(μ, jet) < 0.5 |
|-----------------|---------------------------------------------|
| scaledLoose     | 98.4                                        |
| scaledMedium    | 97.3                                        |
| scaledTight     | 93.6                                        |
| tight           | 87.3                                        |
| trkTight        | 94.1                                        |
| trkScaledLoose  | 98.6                                        |
| trkScaledTight  | 97.3                                        |

relative uncertainties are 0.4%-0.8%.

There have been variations in the isolation efficiency of muon candidates during Run II, up to several percent for some working points. They are due to the dependence of the isolation efficiency on the detector occupancy, which depends on instantaneous luminosity. This effect is mostly driven by the calorimeter isolation, for which it is not possible to control the effect of pile-up from other pp interactions in the same bunch crossing. The jetIso efficiency is almost independent (< 1% variation) of luminosity. The isolation conditions based on the tracking system are less affected by the presence of other pp interactions in the same bunch crossing as they benefit from the requirement Δz0(μ, track) < 2 cm imposed on the tracks considered in the isolation calculation. This is one of the reasons why working points using mostly track isolation (trkTight, trkScaledLoose, and trkScaledTight) were defined. The tight working point shows the most pronounced dependence on instantaneous luminosity.

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The resolution parameters \( A \) and \( B \) can be measured by comparing samples of \( Z \to \mu^+\mu^- \) and \( J/\psi \to \mu^+\mu^- \) data to Monte Carlo (MC) events generated by the ALPGEN [18] and PYTHIA generators [19], respectively. We use these two resonances, which correspond to two different scales of momentum, to disentangle the roles of \( A \) and \( B \) in the resolution. For both data and MC, the selections of the samples demand two isolated, acollinear, oppositely charged muons, either with \( p_T > 3 \) GeV to obtain the \( J/\psi \to \mu^+\mu^- \) dominated sample, or with \( p_T > 20 \) GeV to obtain the \( Z/\gamma^* \to \mu^+\mu^- \) dominated sample. The opposite sign requirement of the data \( J/\psi \to \mu^+\mu^- \) selection is reversed to obtain a same-sign \( \mu^+\mu^- \) control sample that models the background under the \( J/\psi \to \mu^+\mu^- \) invariant mass peak.

In the MC samples, we apply a random smearing of the generated true muon momentum inspired by the form of the resolution Eq. (7). The random smearing is applied according to:

\[
\frac{q}{p_T} \to (1 + S) \frac{q}{p_T} + G \frac{R^2_{\text{CFT}}}{L^2_{\text{arm}}} \left( A \oplus B \sqrt{\cosh \eta} \right) p_T,
\]

where \( q \) is the particle charge, the \( S \) parameter represents the potential difference in momentum scale between data and MC, and \( G \) is a random number following a Gaussian distribution of mean zero and width one. We compare the resulting smeared dimuon invariant mass spectra to their data counterparts and determine the \( A \) and \( B \) parameters by a \( \chi^2 \) minimization procedure. The scale parameter \( S \) is determined iteratively by shifting the distributions so that the positions of the invariant mass peaks of the MC and data distributions agree.

We determine the resolution parameters for three different types of muon tracks: (i) tracks with SMT hits and in the full CFT acceptance (\( |\eta_{\text{CFT}}| < 1.6 \)), (ii) tracks with SMT hits and located outside the full CFT acceptance (\( |\eta_{\text{CFT}}| > 1.6 \)), and (iii) tracks without SMT hits.

The \( S \) parameter is typically around 0.5%. The typical resolution parameters are given in Table IV [16]. In these figures, the uncertainties are assessed by increasing the muon \( p_T \) requirement in the \( Z \) or \( J/\psi \) selections, varying the muon and track qualities, and varying the mass range used to compute the \( \chi^2 \). The statistical uncertainties are obtained from pseudoexperiments in which the number of events in each bin of the invariant mass distributions is varied according to its expected statistical uncertainty. The relative momentum resolutions as a function of \( p_T \) for the different types of tracks are shown in Fig. 9. The typical resolution is 10%–16% for tracks of \( p_T = 40 \) GeV.

![FIG. 9: Relative muon momentum resolution for different types of tracks. The bands correspond to the ±1 standard deviation uncertainties on the measurements.](image)

### VI. MUON BACKGROUND

We identify three sources of background for physics with muons: (i) muons from cosmic rays, (ii) in-flight decays of pions or kaons into muons, and (iii) hadrons passing through the calorimeter (punch-through). For high-\( p_T \) physics, (iv) real muons from the semi-leptonic decays of heavy-flavor hadrons constitute an additional source of background. For high-\( p_T \) analyses, types (i–iv) are merged under the generic name of multijet muon background, as they all occur in events where hadrons or jets yield a reconstructed muon. This multijet background is completely dominated by the heavy flavor component.

The contamination due to each source of background depends on the particular selected final state topology and on the identification criteria. The numbers and examples given below are therefore only indicative.

#### A. Cosmic rays

The muon identification criteria described in Secs. IV A and IV B are optimized to reject the background composed of cosmic muons. In particular the timing veto and the cuts on dca result in a negligible contamination for most data analyses. An example of the determination of the cosmic-ray contamination is described in Ref. [13] where template histograms of the dca distributions are employed to fit to the data the contributions of cosmic rays and \( p\bar{p} \to W \to \mu\nu \) events. In this analysis, the template histogram for the \( W \to \mu\nu \) signal is obtained from a selection of \( Z \to \mu\mu \) events, while the cosmic muon template is obtained from a sample with two back-to-back
reconstructed muons. The contamination is estimated to be below the 0.1% level.

B. Multijet background

The multijet background is mainly reduced by the isolation criteria described in Sec. IV C. The multijet background can be assessed in two different ways. Either by determining (i) the rate at which a jet yields a reconstructed isolated muon, or (ii) the rate at which a multijet event with an identified muon yields an isolated muon. Once this rate is known, it can be applied in a multijet control sample to determine the contamination in the signal sample.

For case (i), the method consists of defining an unbiased background-enriched sample of multijet events and measuring the rate in that sample. This method is employed in Ref. [20] where it is found in dijet events that the probability for a jet of $p_T > 15$ GeV (100 GeV) to produce an isolated muon of $p_T > 15$ GeV is approximately $4 \times 10^{-4}$ ($2 \times 10^{-3}$).

For case (ii), the method defines four different disjoint samples of events as illustrated by Fig. 10. In the first step, one selection criterion $X$ of the signal sample is reversed to produce a multijet-enhanced sample (region $C + D$ in Fig. 10). As an example, $X$ can be a high missing transverse energy ($E_T$) requirement that selects $W \rightarrow \mu\nu$ decays, where the $E_T$ is obtained from the vector sum of the transverse components of the reconstructed muon momenta and energy deposits in the calorimeter, corrected for the differences in detector response of the reconstructed electrons and jets. The rate $f$ at which a muon is isolated in that sample is then measured, $f = C/(C + D)$. The rate $f/(1 - f)$ can then be applied to a multijet control sample similar to the signal sample but in which the isolation criterion is reversed (region $B$ in Fig. 10). Because there can be leakage of signal into the non-isolated sample, it may be necessary to solve a set of linear equations to determine the composition of the different samples, so that the method is sometimes referred to as the "matrix method." Once $f$ is properly measured, the equations read:

$$A = S + EW + MJ$$  \hspace{1cm} (9)

$$B = \frac{1 - \epsilon}{\epsilon} \times (S + EW) + \frac{1 - f}{f} \times MJ,$$  \hspace{1cm} (10)

where $S$, $EW$, and $MJ$ are the signal, electroweak background, and multijet background components in sample $A$, respectively, and $\epsilon$ is the isolation efficiency for both the signal and the electroweak background. Because the method involves defining four independent samples of events according to $(X$, not $X) \times$ (isolated, not isolated) it is also known under the name of "ABCD method".

This method is applied for example in Ref. [21], where the selection of the $tt \rightarrow \mu\nu+\text{jets}$ signal events demands $E_T > 25$ GeV. The isolation rate for muons in multijet events is determined with the same selection but demanding small missing transverse energy, $E_T < 10$ GeV; it is found to be 17%–22%.

C. In-flight decays and punch-throughs

Analyses based on final states with muons from heavy flavor decays within jets may require an accurate estimate of the in-flight decay and calorimeter punch-through contamination. To measure the rate for kaons or pions to be reconstructed and identified as muons, a common method consists of identifying known resonances using the invariant mass of the decay products, and determining the rate at which one of the decay products is reconstructed as a muon. For example Ref. [22] uses the $D^0 \rightarrow K\pi$ resonance and determines the rate for the kaon to be reconstructed as a muon. For a track requirement of two SMT hits and two CFT hits, the fraction of tracks of $p_T > 5$ GeV originating from kaons that are reconstructed and identified as tight muons with a converged local fit in the muon system is found to be $(1.9 \pm 0.5) \times 10^{-3}$.

VII. CORRECTION TO FULL DETECTOR SIMULATION

Physics analyses at D0 widely employ the simulation of the full detector response for standard model and beyond the standard model processes. Most of these processes are simulated with the PYTHIA or ALPGEN generators, with PYTHIA providing showering and hadronization in the latter case, followed by a detailed GEANT3-based [23] simulation of the D0 detector. To model the effects of multiple $p\bar{p}$ interactions, the MC samples are overlaid with events from random $p\bar{p}$ collisions with the same luminosity distribution as data. These events are then reconstructed with the same software as used for the data. Small differences are found between the data and the MC, both for the identification efficiency of muons and for their momentum resolution. Corrections to the full D0 simulation need to be applied to bring the simulation of the detector into better agreement with the data. These corrections are discussed below. More details can be found in Refs. [16, 17].

![FIG. 10: Illustration of the “matrix/ABCD” method, where the criterion $X$, for example a requirement of high $E_T$, and the muon isolation define four independent samples. See text for details](image-url)
A. Efficiency correction

The tag-and-probe method described in Sec. V can be used to measure muon-related efficiencies of the full detector simulation using a PYTHIA $Z \rightarrow \mu^+ \mu^-$ MC sample. The same selection criteria are demanded as for the $Z \rightarrow \mu^+ \mu^-$ data sample, except the trigger requirement. The luminosity spectra of the MC samples are reweighted to the same spectrum as for the measurements of efficiencies in data.

Differences are found in the measured $Z \rightarrow \mu^+ \mu^-$ MC efficiencies compared to the measured data efficiencies as can be seen in Fig. 11. The relative differences are smaller than 10%, and for most of the phase space they are below the 5% level. However, for an optimal agreement between data and simulated events the analysis chain used by most D0 physics analyses includes weight factors to correct for these differences. The weight factors are obtained as the ratio of efficiencies measured in data to those measured in MC.

For the muon identification, the corrections are computed for each of the six operating points defined in Sec. IV A. The corrections are parametrized in the ($\eta_{\text{detector}}, \phi$) plane to reflect the geometry of the detector. The dependence of the correction on luminosity is found to be negligible. On average the correction factors are 1.004, 0.988, and 0.970 for the loose, medium, and tight operating points, respectively. The relative systematic uncertainties on these numbers are the same as the relative uncertainties for the data efficiencies given in Sec. V B. They amount to 0.9%–1.2%.

For each of the four track reconstruction categories defined in Sec. IV B, two efficiency corrections are derived to bring MC into optimal agreement with data. The first correction accounts for the geometry of the tracking system and is parametrized as a function of ($\eta_{\text{CFT}}, z_0$). The second correction accounts for the dependence of the track reconstruction efficiency on instantaneous luminosity ($L$) for different regions in $\eta_{\text{CFT}}$, and is parametrized in ($L, |\eta_{\text{CFT}}|$). The average overall correction factors are 0.988, 1.020, 1.002, and 1.005 for the loose, medium, mediumSMT, and tight operating points, respectively.

The systematic uncertainties on these numbers are given by the uncertainties for the measurements reported in Sec. V C. They amount to 1.1%–1.6%.

For each of the isolation operating points defined in Table II, two efficiency corrections are applied. All operating points demand $\Delta R(\mu, \text{jet}) > 0.5$, and the first correction is computed as a function of ($L, |\eta_{\text{CFT}}|$) for this requirement only. The second correction is computed relative to the $\Delta R(\mu, \text{jet}) > 0.5$ requirement, as a function of ($L, |\eta_{\text{CFT}}|, \Delta R(\mu, \text{jet})$). This second correction is not applied for the jetIso operating point, which is based solely on the $\Delta R(\mu, \text{jet}) > 0.5$ requirement. The average correction for the $\Delta R(\mu, \text{jet}) > 0.5$ is 1.011. The overall average correction factors are 1.000–1.021 for the other operating points relative to the $\Delta R(\mu, \text{jet}) > 0.5$ requirement, with a relative systematic uncertainty of 0.4%–0.8%, dominated by the systematic uncertainties of the measurements in data as discussed in Sec. V D. Once combined, the relative systematic uncertainty of both corrections is 0.8%–0.9%.

B. Momentum oversmearing

The momentum resolution in data is typically worse by about 30% compared to the simulation for a muon with a transverse momentum of 40 GeV. This discrepancy reveals some mismodeling arising from the simulation of hit efficiencies, the simulation of hit resolution, the magnetic field mapping, and the alignment of detector elements. Although the simulation was constantly improved during Run II, an ad-hoc smearing of the muon curvature, called oversmearing, was developed in order to make the resolution in MC match that in data.

The oversmearing follows Eq. (8) in Sec. V F but instead of being applied to the true generated momentum, it is applied on the reconstructed momentum, i.e., after the full detector simulation and reconstruction:

$$\frac{q}{p_T} \rightarrow (1 + S) \frac{q}{p_T} + G \frac{R_{\text{CFT}}^2}{L_{\text{arm}}} \left( A \oplus B \sqrt{cosh(\eta)} \right).$$

Here $A$, $B$, and $S$ are the oversmearing parameters to be determined, and $G$ is a random number that follows a Gaussian distribution of mean zero and width one. As in Eq. (7), $L_{\text{arm}}$ is the radius corresponding to the outermost CFT hit of the track and $R_{\text{CFT}}$ is the CFT radius. To determine $A$, $B$, and $S$, we use the same methods, the same samples of $J/\psi \rightarrow \mu^+ \mu^-$ and $Z/\gamma^* \rightarrow \mu^+ \mu^-$ events, and the same track types as in Sec. V F. Typically, the $A$ parameter is determined to be around 1.7–3 $\times 10^{-3}$ GeV$^{-1}$, the $B$ parameter around $1.4 \times 10^{-2}$, and the $S$ parameter around $0.3 \times 10^{-2}$. The total uncertainty on the oversmearing parameters range from 5% to 25% for $A$ and $B$, and 50% for $S$ for tracks of type (i) and (ii). Due to the limited statistics available to determine the parameters for type (iii), the uncertainty on the oversmearing reaches 100% for this category.

Analyses requiring a good modeling of the high-$p_T$ muon momentum resolution tail use an alternate oversmearing method. It is similar to that described in Eq. (11), but we introduce a parameter $A'$ representing a resolution term for the tail of the distribution and a parameter $C$ representing the fraction of tracks belonging to that tail. For a fraction $1 - C$ of randomly chosen tracks, we use the same smearing formula as in Eq. (11) while for the rest we use the same relation as (11) but we replace $A$ by $A'$. This method allows reproduction of a double Gaussian structure in the momentum resolution function. As for the single Gaussian case, the parameters are determined by a $\chi^2$ minimization procedure. The parameters $A$ and $B$ are found to be quite similar to the single Gaussian case. The parameter $C$ is determined to be around 3%–8% depending on the track type. The parameter $A'$ is determined to be around 5–10 $\times 10^{-3}$ GeV$^{-1}$.
for types (i) and (ii), and around $20 - 30 \times 10^{-3}$ GeV$^{-1}$ for type (iii). The determination of the double Gaussian parameters suffers from higher systematic and statistical uncertainties than for the single Gaussian case. The uncertainties on $C$ and $A'$ are at the level of 30\%-50\% for type (i) while they are up to 200\% for both types (ii) and (iii).

The necessity of the oversmearing and its effects are illustrated in Fig 12, where the invariant mass spectrum of $Z/\gamma^{*} \rightarrow \mu^{+}\mu^{-}$ dimuon events is compared to the MC before and after applying the oversmearing procedures.

VIII. CONCLUSION

We have described the techniques and algorithms employed by the D0 collaboration during Run II of the Fermilab Tevatron collider to reconstruct muons from the muon system hits, and to match these muon system objects to tracks from the D0 central tracker. We have presented the muon identification criteria employed at D0, the reconstruction and identification performances, and the experimental techniques used to measure these performances. In the angular region $|\eta| < 2$, the muon system is able to identify high-$p_T$ muons with efficiencies ranging from 72\% to 90\%, depending on the quality requirements. Central tracks matched to these muons are reconstructed with efficiencies ranging from 85\% to 92\%, depending on the quality requirements, and a relative momentum resolution of typically 10\% for $p_T = 40$ GeV. Isolation criteria reject multijet background for high-$p_T$ physics with efficiencies of 87\% to 99\% depending on the criteria. Combined together these criteria have typical efficiencies of 50\% to 80\%.

The main backgrounds to the muon reconstruction have been briefly discussed. We find that the background from cosmic rays is negligible, while jets from multijet events yield reconstructed isolated muons with a typical probability of $4 \times 10^{-4}$.

We have presented the method employed to optimize agreement between simulated MC and data events. An oversmearing method corrects for the approximately 30\%
difference in momentum resolution observed between the data and the default simulation. Efficiency correction factors ranging from 0.93 to 1.02 are needed to properly simulate the efficiencies related to muon identification.

Thanks to the performance of the detector, the analysis chain, and the methods used to obtain a proper simulation of the muon reconstruction, the D0 experiment was able to fully exploit the Tevatron Run II data and obtain a large number of physics results relying on muon signatures.

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