Abstract

Controllable image synthesis with user scribbles has gained huge public interest with the recent advent of text-conditioned latent diffusion models. The user scribbles control the color composition while the text prompt provides control over the overall image semantics. However, we note that prior works in this direction suffer from an intrinsic domain shift problem wherein the generated outputs often lack details and resemble simplistic representations of the target domain. In this paper, we propose a novel guided image synthesis framework, which addresses this problem by modelling the output image as the solution of a constrained optimization problem. We show that while computing an exact solution to the optimization is infeasible, an approximation of the same can be achieved while just requiring a single pass of the reverse diffusion process. Additionally, we show that by simply defining a cross-attention based correspondence between the input text tokens and the user stroke-painting, the user is also able to control the semantics of different painted regions without requiring any additional training or finetuning. Human user study results show that the proposed approach outperforms the previous state-of-the-art by over 85.32% on the overall user satisfaction scores. Project page for our paper is available at https://1jsingh.github.io/gradop.

1. Introduction

Guided image synthesis with user scribbles has gained widespread public attention with the recent advent of large-scale language-image (LLI) models [23, 26, 28, 30, 40].

Figure 1. Overview. We propose a novel stroke based guided image synthesis framework which (Left) resolves the intrinsic domain shift problem in prior works (b), wherein the final images lack details and often resemble simplistic representations of the target domain (c) (generated using only text-conditioning). Iteratively reperforming the guided synthesis with the generated outputs (c) seems to improve realism but it is expensive and the generated outputs might lose faithfulness with the reference (a) with each iteration. (Right) Additionally, the user is also able to specify the semantics of different painted regions without requiring any additional training or finetuning.
novice user can gain significant control over the final image contents by combining text-based conditioning with unsupervised guidance from a reference image (usually a coarse stroke painting). The text prompt controls the overall image semantics, while the provided coarse stroke painting allows the user to define the color composition in the output scene.

Existing methods often aim to achieve this through two means. The first category leverages conditional training using semantic segmentation maps [8, 28, 39]. However, the conditional training itself is quite time-consuming and requires a large scale collection of dense semantic segmentation labels across diverse data modalities. The second category, typically leverages an inversion based approach for mapping the input stroke painting to the target data manifold without requiring any paired annotations. For instance, a popular solution by [22, 35] introduces the painting based generative prior by considering a noisy version of the original image as the start of the reverse diffusion process. However, the use of an inversion based approach causes an intrinsic domain shift problem if the domain gap between the provided stroke painting and the target domain is too high. In particular, we observe that the resulting outputs often lack details and resemble simplistic representations of the target domain. For instance, in Fig. 1, we notice that while the target domain consists of realistic photos of a landscape, the generated outputs resemble simple pictorial arts which are not very realistic. Iteratively reperforming the guided synthesis with the generated outputs [4] seems to improve realism but it is costly, some blurry details still persist (refer Fig. 4), and the generated outputs tend to lose faithfulness to the reference with each successive iteration.

To address this, we propose a diffusion-based guided image synthesis framework which models the output image as the solution of a constrained optimization problem (Sec. 3). Given a reference painting \( y \), the constrained optimization is posed so as to find a solution \( x \) with two constraints: 1) upon painting \( x \) with an autonomous painting function we should recover a painting similar to reference \( y \), and, 2) the output \( x \) should lie in the target data subspace defined by the text prompt (i.e., if the prompt says "photo" then we want the output images to be realistic photos instead of cartoon-like representations of the same concept). Subsequently, we show that while the computation of an exact solution for this optimization is infeasible, a practical approximation of the same can be achieved through simple gradient descent.

Finally, while the proposed optimization allows the user to generate image outputs with high realism and faithfulness (with reference \( y \)), the fine-grain semantics of different painting regions are inferred implicitly by the diffusion model. Such inference is typically dependent on the generative priors learned by the diffusion model, and might not accurately reflect the user’s intent in drawing a particular region. For instance, in Fig. 1, we see that the light blue regions can be inferred as blue-green grass instead of a river. To address this, we show that by simply defining a cross-attention based correspondence between the input text tokens and user stroke-painting, the user can control semantics of different painted regions without requiring semantic-segmentation based conditional training or finetuning.

2. Related Work

**GAN-based methods** have been extensively explored for performing guided image synthesis from coarse user scribbles. [1–3, 14, 27, 37, 42] use GAN-inversion for projecting user scribbles on to manifold of real images. While good for performing small scale inferences these methods fail to generate highly photorealistic outputs when the given stroke image is too far from the real image manifold. Conditional GANs [7, 13, 18, 21, 24, 36, 43] learn to directly generate realistic outputs based on user-editable semantic segmentation maps. In another work, Singh et al. [34] propose an image synthesis framework which leverages autonomous painting agents [19, 32, 33, 44] for inferring photorealistic outputs from rudimentary user scribbles. Despite its efficacy, this requires the creation of a new dataset and conditional training for each target domain, which is expensive.

**Guided image synthesis with LLI models** [6, 23, 26, 28, 30, 40, 41] has gained widespread attention [9, 12, 15, 17, 20, 29, 31] due to their ability to perform high quality image generation from diverse target modalities. Of particular interest are works wherein the guidance is provided using a coarse stroke painting and the model learns to generate outputs conditioned on both text and painting. Current works in this direction typically 1) use semantic segmentation based conditional training [8, 28, 39] which is expensive, or, 2) adopt an inversion-based approach for mapping the input stroke painting to the target data manifold without requiring paired annotations. For instance, Meng et al. [22] propose guided image synthesis framework, wherein the generative prior is introduced by simply considering a noisy version of the original sketch input as the start of the reverse diffusion process. Choi et al. [5] propose an iterative conditioning strategy wherein the intermediate diffusion outputs are successively refined to move towards the reference image. While effective, the use of an inversion-like approach causes an implicit domain shift problem, wherein the output images though faithful to the provided reference show blurry or less textured details. Iteratively reperforming guided synthesis with generated outputs [4] seems to improve realism but it is costly. In contrast, we show that it is possible to perform highly photorealistic image synthesis while just requiring a single reverse diffusion pass.

**Cross-attention control.** Recently, Hertz et al. [10] propose a prompt-to-prompt image editing approach with text-conditioned diffusion models. By constraining the cross-attention features of all non-targeted text tokens to remain...
3. Our Method

Let \( f : \mathcal{D}_{\text{real}} \rightarrow \mathcal{D}_{\text{paint}} \) be a function mapping a real input image \( x \) to its painted image \( f(x) \). Then given a colored stroke image \( y \) and input prompt \( \tau_{\text{text}} \), we formulate the computation of guided image synthesis output \( x^* \) as the solution to the following constrained optimization problem,

\[
\begin{align*}
   x^* &= \arg\min_x \mathcal{L}(f(x), y) \\
   \text{subject to } x &\in \mathcal{S}_{\tau_{\text{text}}} 
\end{align*}
\]

where \( \mathcal{L}(f(x), y) \) represents a distance measure between the painted output \( f(x) \) of image \( x \) and the target painting \( y \), while \( \mathcal{S}_{\tau_{\text{text}}} \) represents the subspace of output images conditioned only on the text input.

In other words, by additionally conditioning on a stroke image \( y \), we wish to find a solution \( x^* \) such that 1) the distance between the painted image of \( x \) and reference painting \( y \) is minimized, while at the same time ensuring 2) the final solution lies in the subspace of images conditioned only on the text prompt \( \tau_{\text{text}} \). For instance, if the text says "a realistic photo of a tree" then the use of stroke-based guidance should still produce a "realistic photo", wherein the composition of the tree regions is controlled by the painting \( y \).

### 3.1. GradOP: Obtaining an Approximate Solution

The optimization problem in Eq. 1 can be reformulated as an unconstrained optimization problem as,

\[
x^* = \arg\min_x \mathcal{L}(f(x), y) + \gamma d(x, \mathcal{S}_{\tau_{\text{text}}}),
\]

where \( d(x, \mathcal{S}_{\tau_{\text{text}}}) \) represents a distance measure between \( x \) and subspace \( \mathcal{S}_{\tau_{\text{text}}} \), and \( \gamma \) is a hyperparameter.

A cursory glance at the above formulation should make it evident that the computation of an exact solution is infeasible without first generating a large enough sample size for the \( \mathcal{S}_{\tau_{\text{text}}} \) subspace, which will be quite time consuming.

To address this, we propose to obtain an approximate solution by estimating \( d(x, \mathcal{S}_{\tau_{\text{text}}}) \) through the distance of \( x \) from a single random sample \( x_{\tau_{\text{text}}} \in \mathcal{S}_{\tau_{\text{text}}} \). Thus, we can approximate the optimization problem as follows,

\[
x^* = \arg\min_x \mathcal{L}(f(x), y) + \gamma d(x, x_{\tau_{\text{text}}}).
\]

Assuming a latent diffusion model with decoder \( \mathcal{D} \), we can rewrite the above above optimization in latent space as,

\[
z^* = \arg\min_z \mathcal{L}(f(D(z)), y) + \gamma \| z - z_{\tau_{\text{text}}} \|_2^2.
\]

where the image output \( x^* \) can be computed as \( x^* = \mathcal{D}(z^*) \).

In order to solve the above optimization problem, we first use the diffusion model to sample \( x_{\tau_{\text{text}}} \in \mathcal{S}_{\tau_{\text{text}}} \). Initializing \( z = \mathcal{E}(x_{\tau_{\text{text}}}) \), where \( \mathcal{E} \) represents the encoder, we solve the above optimization using gradient descent (assuming \( f \) and \( \mathcal{L} \) are differentiable). Finally, we note that the solution \( x^* = \mathcal{D}(z^*) \) to the above approximation of the optimization problem might be non-photorealistic, as Eq. 5 has no explicit constraint for enforcing \( x \in \mathcal{S}_{\tau_{\text{text}}} \) (Eq. 2). We therefore use the diffusion-based-inversion approach from [35] in order to map it to the target image subspace \( \mathcal{S}_{\tau_{\text{text}}} \).
Algorithm 1 GradOP: Solution Approximation

Input: Stroke Painting $y$, text prompt $\tau_{text}$

Require: Differentiable painting function $f$, differentiable distance measure $L$, hyperparameter $\gamma, t_0$.

1: Sample $x_{\tau_{text}} \in S_{\tau_{text}}$;
2: Initialize $z = z_{\tau_{text}} = \mathcal{E}(x_{\tau_{text}})$;
3: for $0 \leq i \leq M$ do
4: \hspace{1em} $L_{\text{total}} = L(f(D(z)), y) + \gamma \|z - z_{\tau_{text}}\|_2$;
5: \hspace{1em} $z = z - \lambda \nabla_z L_{\text{total}}$;
6: end for
7: $z_0 = \text{ForwardDiff}(z = z, 0 \rightarrow t_0)$;
8: $z = \text{ReverseDiff}(z_0, t_0 \rightarrow 0)$;
9: return $x_{\text{out}} = D(z)$.

In other words, unlike prior works [5,22] which directly perform an inversion-like operation on the reference painting $y$ (high domain gap with the target subspace e.g. real images), GradOP first uses the unconstrained optimization from Eq. 5 to compute a point $x^*$ which is close to target subspace in the latent space $z$, while still being faithful to the reference $y$. Since $x^*$ is closer to target domain than $y$, the inversion operation leads to more realistic outputs (refer to Fig. 4). Please refer Alg. 1 for the detailed implementation.

3.2. GradOP+ : Improving Sampling Efficiency

While the guided synthesis solution in Alg. 1 leads to high output realism, for each output it requires the sampling of a text-only conditioned image $x_{\tau_{text}} \in S_{\tau_{text}}$. To address this, we propose a modified guided image synthesis approach which allows for equally high quality outputs while requiring just a single reverse diffusion pass for each output. Our key insight is that a lot of information in $z^*$ is discarded during the forward diffusion from $z^* \rightarrow z_{t_0}$. Thus, instead of performing the optimization to first compute $z^*$, we would like to directly optimize the intermediate latent states $z_t$ by injecting the optimization gradients within the reverse diffusion process itself (refer Fig. 3).

In particular, at any timestep $t$ during the reverse diffusion, we wish to introduce optimization gradients in order to solve the following optimization problem,

$$z_t^* = \argmin_z L(f(D(z)), y) + \gamma \|z - z_t\|_2. \tag{6}$$

However, the introduction of gradients will cause $z_t^*$ to not conform with the expected latent distribution at timestep $t$. We therefore pass it through the forward diffusion process in order to map it back to the expected latent variable distribution. Please refer Alg. 2 for the detailed implementation.

3.3. Controlling Semantics of Painted Regions

Finally, while the above approximate guided image synthesis algorithm allows for generation of image outputs with high faithfulness and realism, the semantics of different painted regions are inferred in an implicit manner. Such inference is typically based on the cross-attention priors (learned by the diffusion model) between the provided text tokens and the input painting throughout the reverse diffusion process. For instance, in the first example from Fig. 5, we note that for different outputs, the blue region can be inferred as a river, waterfall, or a valley. Also note that some painting regions might be entirely omitted (e.g. the brown strokes for the hut), if the model does not understand that the corresponding strokes indicate a distinct semantic entity e.g. a hut, small castle etc. Moreover, as shown in Fig. 5 such discrepancies persist even if the corresponding text tokens (e.g. a hut) are added to the textual prompt.

Our key motivation is that when generated faithfully, the average attention maps across different cross-attention layers show high overlap with the target object segmentation during the initial to intermediate parts of the reverse diffusion.

Algorithm 2 GradOP+: Improving Sampling Efficiency

Input: Stroke Painting $y$, text prompt $\tau_{text}$

Require: Differentiable painting function $f$, distance measure $L$, hyperparameter $\gamma, t_0, t_{\text{start}}, t_{\text{end}}$.

1: Sample $z_T \sim \mathcal{N}(0, I)$;
2: for $t = T - 1, T - 2 \ldots 0$ do
3: \hspace{1em} $z_{t} = \text{ReverseDiff}(z_{t+1}, t + 1 \rightarrow t)$;
4: \hspace{1em} if $t_{\text{start}} \leq t \leq t_{\text{end}}$ then
5: \hspace{2em} Initialize $z = z_T$;
6: \hspace{2em} for $0 \leq i \leq M$ do
7: \hspace{3em} $L_{\text{total}} = L(f(D(z)), y) + \gamma \|z - z_t\|_2$;
8: \hspace{3em} $z = z - \lambda \nabla_z L_{\text{total}}$;
9: \hspace{2em} end for
10: \hspace{1em} $z_t = \text{ForwardDiff}(z_T = z, 0 \rightarrow t)$
11: \hspace{1em} end if
12: end for
13: return $x_{\text{out}} = D(z_0)$.
Evaluation criteria  

User Study Results

| Method     | Evaluation criteria | User Study Results |
|------------|---------------------|--------------------|
| SDEdit [22] | 88.93 223.8 | 94.09 % 91.98% |
| Loopback [4] | 104.6 132.9 | 54.28 % 85.32% |
| ILVR [5] | 108.2 161.7 | 75.54 % 93.47% |
| Ours | 94.40 134.2 | N/A N/A |

Table 1. Quantitative Evaluations. (Left) Method comparison w.r.t faithfulness $F$ to the reference painting and realism $R$ to the target domain. (Right) User-study results, showing % of inputs for which human subjects prefer our approach over prior works.

In particular, given the binary masks corresponding to different painting regions $\{B_1, \ldots B_N\}$ and the corresponding semantic labels $\{u_1, \ldots u_N\}$, we first modify the input text tokens as follows,

$$\tau_{\text{modified}} = \tau + \{\text{CLIP}(u_i) \mid i \in [1, N]\},$$

where $\tau$ is the set of CLIP [25] tokens for input text prompt.

At any timestep $t \in [0, T]$ during the reverse diffusion process, we then enforce semantic control by modifying the cross-attention map $A_t^i$ corresponding to label $u_i$ as follows,

$$\tilde{A}_t^i = w_i \left[ (1 - \kappa_t) A_t^i + \kappa_t \frac{B_i}{\|B_i\|_F} \right]$$

where $\| \cdot \|_F$ represents the Frobenius norm, $\kappa_t = t/T \in [0, 1]$ helps regulate the overlap between the cross-attention output $A_t^i$ and the desired painting region $B_i$ during the reverse diffusion process, and, weights $w_i$, $i \in [1, N]$ help the user to control the relative importance of expressing different semantic concepts in the final image.

4. Experiments

Implementation Details. We use publicly available text-conditioned latent diffusion models [28, 38] for implementing the proposed approach in Sec. 3. The constrained optimization is performed using gradient descent with the Adam [16] optimizer and number of gradient steps $N_{\text{grad}} \in [20, 60]$ (please refer Sec. 5.2 for detailed analysis). While several formulations of the distance measure $\mathcal{L}$ and painting function $f$ are possible (refer supp. material for details), we find that simply approximating the function $\mathcal{L}$ using mean squared distance and $f$ as a convolution operation with a gaussian kernel seems to give the fastest inference time performance with our method. For consistency reasons, we use the non-differentiable painting function from SDEdit [22] while reporting quantitative results (refer Sec. 4.1).

4.1. Stroke Guided Image Synthesis

Evaluation metrics. Given an input stroke painting, we compare the performance of our approach with prior works in guided image synthesis when no paired data is available. The performance of the final outputs is measured in terms of both faithfulness of the generated image with the target stroke painting as well as the realism of the final output distribution. In particular, given an input painting $y$ and output real image prediction $x$, we define faithfulness $F(x, y)$ as,

$$F(x, y) = \mathcal{L}_x(f(x), y)$$

where $f(.)$ is the painting function. Thus an output image $x$ is said to have high faithfulness with the given painting $y$ if upon painting the final output $x$ we get a painting $\tilde{y} = f(x)$ which is similar to the original target painting $y$.

Similarly, given a set of output data samples $S(y, \tau_{\text{text}})$ conditioned on both painting $y$ and text $\tau_{\text{text}}$, and, $S(\tau_{\text{text}})$ conditioned only on the text, the realism $R$ is defined as,

$$R(S(y, \tau_{\text{text}})) = \text{FID}(S(y, \tau_{\text{text}}), S(\tau_{\text{text}}))$$

where $\text{FID}$ represents the Fisher inception distance [11].

Baselines. We compare our approach with prior works on guided image synthesis from stroke paintings with no paired data. In particular we show comparisons with, 1) SDEdit [22] wherein the generative prior is introduced by first passing the painting $y$ through the forward diffusion pass $y \rightarrow y_{t_0}$ [15, 35], and then performing reverse diffusion $y_{t_0} \rightarrow y_0$ to get the output image $x = y_0$. 2) SDEdit + Loopback [4] which reuses the last diffusion output to iteratively increase the realism of the final output. 3) ILVR2 [5]: which uses an iterative refinement approach for conditioning the output $x$ of the diffusion model with a guidance image $y$. Unless otherwise specified, we use the GradOP+ algorithm (refer Alg. 2) when reporting evaluation results.

Qualitative Results. Results are shown in Fig. 4. We observe that both proposed approximate optimization methods (i.e. GradOP in row-1,2 and GradOP+ in row-3,4) lead to output images which are both highly photorealistic as well as faithful with reference painting. In contrast, while SDEdit [22] shows high faithfulness to the input painting, the final outputs lack details and resemble more of a pictorial art rather than realistic photos. Iteratively reperforming the guided synthesis with the generated outputs (SDEdit + Loopback [4]) helps improve the realism of output images, however, we find that this has two main disadvantages. First, the iterative loop increases the effective time required for generating each data sample (e.g. four reverse

\[\text{loopbacks per step} \times \text{number of steps} \times \text{runtime of one step}\]

\[\text{loopbacks per step} \times \text{number of steps} \times \text{runtime of one step}\]
we also quantitatively evaluate the final outputs on the painting in terms of the overall color composition. Finally, ILVR [5] leads to more realistic outputs, however, the final outputs are not fully faithful to the reference painting in terms of the overall color composition.

Quantitative Results. In addition to qualitative results we also quantitatively evaluate the final outputs on the faithfulness $F(x, y)$ and targeted-realism $R(.)$ metrics defined earlier. Additionally, similar to [22] we also perform a human user study wherein the realism and the overall satisfaction score (faithfulness + realism) are evaluated by human subjects (please refer supp. material for details). Results are shown in Tab. 1. We find that as expected, while SDEdit [22] leads to the best faithfulness with the target painting, it exhibits very poor performance in terms of the
realism score. SDEdit with loopback [4] improves the realism score but the resulting images start loosing faithfulness with the given reference. In contrast, our approach leads to the best tradeoff between faithfulness to the target image and realism with respect to the target domain. These findings are also reflected in the user-study results wherein our method is preferred by > 85.32% of human subjects in terms of the overall satisfaction scores.

4.2. Controlling Semantics of Painted Regions

Results are shown in Fig. 5. We observe that in absence of semantic attention control, the model tries to infer the semantics of different painting regions in an implicit manner. For instance, the orange strokes in the sky region can be inferred as the sun, moon, or even as a yellow tree. Similarly, the brown strokes in the lower-left region (intended to draw a hut or small castle) are often inferred as muddy or rocky parts of the terrain. Moreover, such disparity continues even after modifying the input prompt to describe the intended semantic labels. For instance, in row-1 from Fig. 5, while changing the text prompt to include the text “hut” leads to the emergence of “hut” like structures, the inference is often done in a manner that is not intended by the user.

In contrast, by ensuring a high overlap between the intended painting regions and the cross-attention maps for the corresponding semantic labels (refer Sec. 3.3), we are able to generate outputs which follow the intended semantic guide in a much more accurate manner. For instance, the user is able to explicitly specify that the brown regions on the ground describes a hut (row 1) or castle (row 2-4). Similarly, the semantics of different regions can be controlled, e.g., the blue region is specified as a river or waterfall, the orange strokes in the sky is specified as moon or sun etc.

5. Analysis

5.1. Variation in Target Domain

In this section, we analyse the generalizability of the our approach across different target domains (e.g., children drawings, disney scenes) and compare the output performance with prior works. Results are shown in Fig. 6-a. We observe that our approach is able to adapt the final image outputs reliably across a range of target domains while still maintaining a high level of faithfulness with the target image. In contrast, SDEdit [22] generates outputs which lack details and thereby look very similar across a range of target domains. SDEdit + Loopback [4] addresses this problem to some extent, but it requires multiple reverse diffusion passes and the generated outputs tend to lose their faithfulness to the provided reference with each iteration.

5.2. Variation with Number of Gradient Steps

In this section, we analyse the variation in output performance as we change the number of gradient descent steps $N_{\text{grad}}$ used to solve the unconstrained optimization problem in Sec. 3. Results are shown in Fig. 6-b. As expected, we find that for $N_{\text{grad}} = 0$, the generated outputs are sampled randomly from the subspace of outputs ($S_{\text{text}}$) condi-
5.3. Out-of-Distribution Generalization

As shown in Sec. 4, 5, we find that the proposed approach allows for a high level of semantic control (both color composition and fine-grain semantics) over the output image attributes, while still maintaining the realism with respect to the target domain. Thus a natural question arises: Can we use the proposed approach to generate realistic photos with out-of-distribution text prompts?

As shown in Fig. 7, we observe that both success and failure cases exist for out-of-distribution prompts. For instance, while the model was able to generate “realistic photos of cats with six legs” (note that for the same inputs prior works either generate faithful but cartoon-like outputs, or, simply generate regular cats), it shows poor performance while generating “a photo of a rat chasing a lion”.

6. Conclusions

In this paper, we present a novel framework for performing guided image synthesis with user scribbles, without the need for paired annotation data. We point that prior works in this direction [4, 5, 22], typically adopt an inversion-like approach which leads to outputs which lack details and are often simplistic representations of the target domain. To address this, we propose a novel formulation which models the guided synthesis output as the solution of a constrained optimization problem. While obtaining an exact solution to this optimization is infeasible, we propose two methods GradOP and GradOP+ which try to obtain an approximate solution to the constrained optimization in a sample-efficient manner. Additionally, we show that by defining a cross-attention based correspondence between the input text tokens and user painting, it is possible to control semantics of different painted regions without the need for semantic segmentation based conditional training.
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