The Porosity of Additive Noise Sequences

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Abstract

Consider a binary additive noise channel with noiseless feedback. When the noise is a stationary and ergodic process \( Z \), the capacity is \( 1 - H(Z) \) (\( H(\cdot) \) denoting the entropy rate). It is shown analogously that when the noise is a deterministic sequence \( z_\infty \), the capacity under finite-state encoding and decoding is \( 1 - \overline{\rho}(z_\infty) \), where \( \overline{\rho}(\cdot) \) is Lempel and Ziv’s finite-state compressibility. This quantity is termed the porosity \( \sigma(\cdot) \) of an individual noise sequence. A sequence of schemes are presented that universally achieve porosity for any noise sequence. These converse and achievability results may be interpreted both as a channel-coding counterpart to Ziv and Lempel’s work in universal source coding, as well as an extension to the work by Lomnitz and Feder and Shayevitz and Feder on communication across modulo-additive channels. Additionally, a slightly more practical architecture is suggested that draws a connection with finite-state predictability, as introduced by Feder, Gutman, and Merhav.

Index Terms

Lempel-Ziv, universal source coding, universal channel coding, modulo-additive channel, compressibility, predictability

I. INTRODUCTION

The “core” results of information theory, starting with Shannon’s source and channel coding theorems, are concerned with probabilistic systems of a known model: an iid Bernoulli \((1/4)\) source must be compressed, or perhaps bits are to be communicated across an AWGN channel of known SNR. One may seek additional generality by asking that a coding scheme simultaneously function for an entire class of such probabilistic models. In the case of source coding, Ziv and Lempel [1, 2] and Ziv [3] take this question to its logical extreme and ask that a compressor not only achieve the optimal rate for any probabilistic source model, but do so for any individual source sequence. In [2], it is discovered that the traditionally relevant probabilistic measurement — entropy rate — generalizes into a measure for an individual sequence — compressibility. In this paper, an analogous set of questions yield an analogous set of answers in the context of noisy channel coding with feedback. Historically, far more attention has been paid to the issue of universality in source coding than in channel coding. The source of this discrepancy is readily apparent from Figs. 1 and 2. The encoder of Fig. 2 never observes the noise sequence in any way, and so its codebook cannot be dynamically customized to suit the channel. The source encoder of Figure 1 on the other hand has direct access to the source sequence and can therefore adjust to its statistics. As such, the degree of universality that can be requested in the classical channel-coding setup is far more restricted than in source coding. Certainly, this does not preclude discussion of “universality,” but the term must take on a considerably looser meaning, as is discussed in Sec. II.

The playing field is considerably leveled by introducing a noiseless feedback link, as in Fig. 3. In particular, the modulo-additive channel of Fig. 4 allows for a clear and precise analogy to the universal source coding of Lempel and Ziv. To highlight some of the parallels:

- Individual sequences. In the source coding setting, Lempel and Ziv replace the source random process \( X_\infty \) with a deterministic sequence \( x_\infty \). Here, the standard stochastic description of channel noise \( Z_\infty \) is supplanted by a specific individual sequence \( z_\infty \).
- Finite state constraint. Lempel and Ziv ask the question: how well can a source encoder/decoder perform for a specific individual sequence, if the engineer designing the encoder/decoder knows the sequence ahead of time? Clearly, if the encoder and decoder are unconstrained, this problem trivializes: one may design a decoder that, with absolutely no input

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![Fig. 1. The model for universal source coding. An unknown source is provided to an encoder, which must describe it to the decoder.](attachment:image1.png)

![Fig. 2. The model for universal channel coding. A message must be communicated over an unknown channel.](attachment:image2.png)
from the encoder, produces $x_i$ at time $t$. A finite-state requirement — which reflects the constraints of the real world — is therefore introduced for both encoder and decoder. Within this class of schemes, Lempel and Ziv provide a (non-trivial) converse.

Similarly, if one permits arbitrary encoders and decoders for the individual noise sequence channel coding setting, the maximum communication rate of $\log |{\cal X}|$ may be easily attained for any noise sequence $z^\infty$. One merely sets the encoder’s output to the difference between the source sequence and the noise sequence $M^\infty - z^\infty$. The channel cancels out the noise, and the decoder needs merely read the channel output to obtain the message $M^\infty$. To avoid such triviality, a finite-state encoder/decoder constraint analogous to that of Lempel and Ziv is introduced. Within this class of schemes, a non-trivial converse is proven.

- In traditional Shannon theoretic results, converses that apply for a particular source/channel model are accompanied by achievability schemes that function for that particular model. For instance, given a BSC with crossover probability $p$, Shannon’s channel coding converse tells us no reliable sequence of coding schemes can achieve a rate better than $1 - h_b(p)$, and Shannon provides a rate $(1 - h_b(p))$-achieving sequence of codebooks customized for the BSC($p$). One might similarly ask Lempel and Ziv that to accompany their converse for a particular source sequence, they provide an achievability scheme for that particular sequence. The achievability they provide, however, goes several steps further: it functions for any individual source sequence. Note that while this scheme that is suggested is infinite-state, it is also shown that by truncation and repetition, achievability is also possible through a sequence of finite-state source-coding schemes.

Similarly, both the infinite-state scheme of Lomnitz and Feder [4] and the sequence of finite-state achievability schemes $\mathcal{F}^\infty$ presented in Sec. VIII achieve the channel-coding converses for any noise sequence.

- The compressibility $\rho(x^\infty)$ of a sequence, introduced by Lempel and Ziv, is its best possible compression rate. The analogous quantity in the channel-coding case is here referred to as the channel’s porosity $\sigma(z^\infty)$. In the binary additive noise case it is demonstrated to be equal to $1 - \rho(z^\infty)$. Both are analogues of probabilistic quantities — entropy rate in the case of compressibility, and one minus the entropy rate in the case of porosity. Both may also be interpreted as generalizations of their probabilistic analogues, since according to Thm. 4 in [2], $\rho(X^\infty) = H(X)$ with probability 1 if $X^\infty$ is an ergodic source.

To summarize, we show both that the porosity of the noise is the best possible rate achievable within the class of finite-state schemes, and that there exist a sequence of finite-state schemes that simultaneously achieves porosity for all noise sequences.

II. RELATED WORK

Lomnitz and Feder introduce the notion of competitive universality to channel coding in [4]. The reference class used in this comparison consists of iterated fixed-blocklength (IFB) schemes, which ignore the feedback channel and simply employ block coding across the noisy channel. Rate-adaptive schemes, on the other hand, make arbitrary use of feedback and communicate a fixed number of bits over at most $n$ channel uses. It is proven that IFB schemes can do no better than porosity (rate $1 - \tilde{\rho}(z^\infty)$), and a rate-adaptive scheme built upon LZ78 is shown to achieve porosity.

In a sense, the results reported here take these statements of competitive optimality a step further: we ask that the achievability schemes not only outperform any elements of the reference class, but that they are elements of the reference class. This
establishes porosity as a channel capacity of sorts. As IFB codes frequently cannot even achieve porosity for a given noise sequence $z^{\infty}$, let alone for the entire set of noise sequences, this requires that the reference class be widened to the class of all finite-state schemes.

The porosity-achieving rate-adaptive scheme introduced by Lomnitz and Feder does not quite fall into this class, as it consists of infinite states. One might consider consider truncating and repeating it in order to construct a finite state scheme. While this could potentially work, we find it somewhat easier to build from the schemes of Shayevitz and Feder [5], whose performance guarantees mesh well with the asymptotic performance metrics of interest here.

In [5], Shayevitz and Feder establish the initial results that have sparked much of the subsequent work in this problem. An extremely general family of channels is considered, but the results provided are most meaningful when restricting attention to the individual additive noise sequence setting. Of interest are two things: the construction of variable-rate, fixed-blocklength schemes expanded from Horner’s coding method, and the strong performance guarantees that are provided. The schemes are shown to achieve for any noise sequence the empirical capacity, or one minus the first-order empirical entropy. By operating this coding technique over blocks of channel use, one can potentially generalize to arbitrary-order empirical entropies. The achievability schemes $\{F^m\}$ presented in this paper are an extension of this idea.

As with both [4] and [5], Eswaran et al. [6] consider a very broad class of channels with noiseless feedback, but the results provided are most meaningful in the modulo-additive setting with an individual noise sequence. Extending [5], it is demonstrated that even when the feedback is asymptotically zero-rate, the empirical capacity is still universally achievable.

As previously mentioned, even in the absence of a feedback link questions of universal channel coding can be considered. The principal complication in this setting is that the encoder no longer has any information about the specific channel, and so neither the rate nor the transmission methodology can be adapted.

One may nonetheless ask that the decoder adapt to the channel. Csiszar and Korner [7] consider the class of memoryless DMC’s that share a common input alphabet $\mathcal{X}$ — call this class $A(\mathcal{X})$. For a randomly generated codebook, a universal decoder for the entire class $A(\mathcal{X})$ is constructed and its performance compared to that of a decoder customized for whichever specific channel happens to appear (maximum likelihood decoder). The universal decoder is not only shown to match the ML decoder in terms of vanishing error, but it is also found to achieve the same error exponent.

Ziv [8] and Lapidoth and Ziv [9] seek to expand such a result into the territory of channels with memory. Each considers a fairly specific form of memory: finite-state channels with deterministic state transitions [8] and those with probabilistic state transitions [2]. Each also demonstrates achievability through decoding schemes that utilize LZ78-style sequence parsing. Feder and Lapidoth [10] on the other hand consider the more general problem of decoding for a parametric family of channels.

Despite the non-adaptability of the encoder in this feedback-less setting, one may seek to maximize the worst-case rate of communication across the channel. The fundamental limit of performance in this scenario is the compound channel capacity, discussed at length in the review article by Lapidoth and Narayan [11].

A generalization of the above is to take a broadcast approach, wherein channel uncertainty is modeled by having the encoder broadcast across all channels in the class considered. The rate region of this broadcast channel then characterizes the rates the encoder may simultaneously achieve for each potential channel. Observe that if this rate region can be specifically determined, it answers all possible questions of universal decoding. Shamai and Steiner [12] leverage this approach for the case of fading channels.

### III. Structure of Paper

In Sec. IV a precise description is provided of the problem setting, the class of finite-state schemes, and the relevant performance metrics. Sec. V builds slightly on Lempel and Ziv’s definition of compressibility and establishes certain useful properties. Sec. VI states the three theorems that constitute the core results of this work. Sec. VII contains the proof of the converse theorems, and Sec. VIII proves achievability. Sec. IX introduces a significantly more practical (but sub-optimal) set of schemes that establish a connection between porosity and finite-state predictability. Sec. X summarizes this paper’s findings. A few lemmas have somewhat distracting proofs that are relegated to the appendices.

### IV. Problem Setup

A deterministic additive noise feedback channel, as depicted in Fig. 4, is defined by a noise sequence $z^{\infty} \in \mathcal{X}^{\infty}$, where $\mathcal{X}$ is a finite alphabet with a modulo-addition operator. The channel output at any time $i$ is given by the sum of the noise and the input: $y_i = x_i + z_i$. Noisless feedback $u_i = y_{i-1}$ delays the channel output by one time unit before providing it to the encoder. Without loss of generality, we will concern ourselves primarily with the binary-alphabet case, i.e. $\mathcal{X} = \{0, 1\}$, as the extension to general finite $\mathcal{X}$ is straightforward.

#### A. Finite-state Schemes

A finite-state (FS) encoder/decoder scheme for an additive noise channel — depicted in Fig. 5 — consists of several components:

1) An encoder state variable $s_i^{(e)}$ and decoder state variable $s_i^{(d)}$, each taking values in a finite set $S$. 
2) A source pointer \( p_i \) and a finite lookahead constant \( \ell \).
3) An iid common randomness source \( \theta_i \sim \rho_\theta \) taking values in a finite alphabet.
4) An encoding function \( x_i = e(s_i^{(e)}, M_{p_i + \ell}, y_i, \theta_i) \in \mathcal{X} \).
5) A decoding length function \( L_i = d_L(s_i^{(d)}, y_i, \theta_i) \) that also determines the update of the source pointer: \( p_{i+1} = p_i + L_i \).
6) A decoding function \( \hat{M}_{p_i + L_i - 1} = d_M(s_i^{(d)}, y_i, \theta_i) \).
7) State-update functions for both the encoder \( s_{i+1}^{(e)} = f_{(e)}(s_i^{(e)}, M_{p_i + \ell}, y_i, \theta_i) \) and decoder \( s_{i+1}^{(d)} = f_{(d)}(s_i^{(d)}, y_i, \theta_i) \).

At each time step, the encoding function determines the input \( x_i \) to the channel, the decoding function estimates the first \( L_i \) source symbols that have yet to be estimated (based on the output \( y_i \) of the channel), and state variables and the source pointer location are updated in anticipation of the next transmission.

Observe, first, that this class of schemes is sufficiently general to include the following as special cases:

1) The class of “iterated fixed-length” block schemes, as defined by Lomnitz and Feder \cite{Lomnitz}. These are simply block codes that ignore the feedback. The common randomness at encoder and decoder allows for randomly generated block codes as well.

2) Schemes that transmit a variable number of source symbols over a fixed number of channel uses, before resetting their state variables and repeating the operation (defined more precisely in Sec. VIII-A as “Repeated Finite-Extent” schemes).

3) Schemes that transmit a variable (or fixed) number of source symbols over a variable (but bounded) number of channel uses (also known as “rate-adaptive” schemes \cite{Lomnitz}).

Secondly, notice that without certain restrictions in the definition of class FS, the problem can become trivial:

1) Suppose that the encoder is permitted to be infinite-state. The system designer may then allow the encoder state \( s_i^{(e)} \) to be the current time index \( i \). This then allows the encoding function to be a function of \( i \), which in turn permits the encoding function to be customized for a particular noise sequence \( z^\infty \): \( c(i, M_{p_i}) = M_{p_i} - z_i \). Sending this through the channel, \( z_i \) is canceled out. The decoder merely needs to read the channel output to obtain the message at the maximum possible rate, \( \log |\mathcal{X}| \).

2) Suppose that the decoder is permitted to be infinite-state. One may reverse the above construction by having the encoder blindly send the message bits through the channel \( c(M_{p_i}) = M_{p_i} \) and asking the decoder to cancel out the noise. Specifically, letting \( s_i^{(d)} = i \), the decoding function can be a function of the time \( i \). This allows for a clever system designer to choose \( d_M(i, y_i) = y_i - z_i \), which guarantees that \( \hat{M}_{p_i} = M_{p_i} \) and that \( L_i = 1 \) for any \( i \).

3) Finally, suppose that the finite-lookahead requirement is nonexistent — that is, the encoding function can look at the entire untransmitted message stream \( x_i = e(s_i^{(e)}, M_{p_i}^{\infty}, y_i, \theta_i) \). As we will illustrate, this is identical to allowing the encoder an infinite number of states. If \( M^\infty \) is a Bernoulli(1/2) sequence, then with probability one there exists a one-to-one map between \( M_i^{\infty} \) and \( i \). The encoder may therefore send \( e(M_{p_i}^{\infty}) = M_{p_i} + z_{p_i} \) as the channel input at time \( i \). The decoder, as before, simply reads the channel output, achieving the maximum rate \( \log |\mathcal{X}| \).

B. Performance metrics

Channel coding typically concerns itself with the tradeoff between rate of communication and the frequency of errors. In the individual sequence setting of interest to us, we define the instantaneous rate and bit-error rate of an FS scheme at time \( n \) as

\[
R_n = \frac{1}{n} \sum_{i=1}^{n} L_i,
\]

and

\[
\epsilon_n = \frac{1}{nR_n} \sum_{i=1}^{nR_n} 1_{\hat{M}_i \neq M_i}.
\]
We consider two interpretations of these quantities.

**Best-Case.** An FS scheme best-case p-achieves rate/error \((R, \epsilon)\) for a noise sequence \(z^\infty\) if with at least probability \(p\) there exists a sequence of points \(\{n_i\} \in \mathbb{Z}^+\) such that \(\lim_{n \to \infty} R_{n_i} \geq R\) and \(\lim_{n \to \infty} \epsilon_{n_i} \leq \epsilon\). In other words, a performance monitor that observes the system at the “right” times will see it achieve \((R, \epsilon)\) with probability at least \(p\). If \(p = 1\), we say that the scheme simply best-case achieves \((R, \epsilon)\).

**Worst-Case.** An FS scheme worst-case p-achieves rate/error \((R, \epsilon)\) if with at least probability \(p\) both \(\lim \inf_{n \to \infty} R_n \geq R\) and \(\lim \sup_{n \to \infty} \epsilon_n \leq \epsilon\). In other words, a performance monitor observing the system at any set of sample times will see it achieve \((R, \epsilon)\) with probability at least \(p\). If \(p = 1\) the scheme is said to worst-case achieve \((R, \epsilon)\).

Observe that the randomness in these definitions has two possible sources: the source sequence \(X^\infty\) and the new limit supremum compression ratio achievable for a sequence (Theorem 3 in [2]). The sliding-window \(k\)th order empirical entropy is similarly written as \(H^k_{sw}(x^n) = H_{\hat{p}^k}(X^k)\). The sliding-window \(k\)th order empirical entropy is similarly written as \(H^k_{sw}(x^n) = H_{\hat{p}^k}(X^k)\). The following lemma, proved in Appendix A, demonstrates that both best-case and worst-case compressibilities may be computed using either block-by-block or sliding-window empirical entropies.

**Lemma 1:** Let \(x^\infty\) be a finite-alphabet sequence. Then

\[ \rho(x^\infty) = \lim_{k \to \infty} \lim_{n \to \infty} \frac{1}{k} \hat{H}^k(x^n) \]

and

\[ \overline{\rho}(x^\infty) = \lim_{k \to \infty} \lim \sup_{n \to \infty} \frac{1}{k} \hat{H}^k(x^n). \]

The **porosity** of a noise sequence \(z^\infty \in \mathcal{Z}^\infty\) is defined in best-case

\[ \sigma(z^\infty) = \log_2 |\mathcal{Z}| - \rho(z^\infty) \]

and worst-case

\[ \sigma(z^\infty) = \log_2 |\mathcal{Z}| - \overline{\rho}(z^\infty) \]

varieties as well. Observe the sign changes: while a “good” compressibility is small, a “good” porosity is large. The remainder of this paper clarifies the operational significance of these quantities.
VI. Statement of Results

The results of this paper may be summarized as follows:

1) A converse that upper-bounds the best-case achievable rate by an FS scheme.
2) A converse that upper-bounds the worst-case achievable rate by an FS scheme.
3) A sequence of universal FS schemes \( \{\overline{F}_m^m\}_{m=1}^\infty \), that simultaneously achieve the best-case and worst-case converse bounds for any noise sequence \( z^\infty \).

Formally, each of these three statements corresponds to a theorem:

**Theorem 2:** Suppose an FS scheme best-case \( p \)-achieves \( (R, \varepsilon) \). If \( p > 0 \), then

\[
R \leq h_b(\varepsilon) + \sigma(z^\infty).
\]

**Theorem 3:** Suppose an FS scheme worst-case \( p \)-achieves \( (R, \varepsilon) \). If \( p > 0 \), then

\[
R \leq h_b(\varepsilon) + \sigma(z^\infty).
\]

**Theorem 4:** There exists a sequence of schemes \( \overline{F}_m^m \), which for an iid Bernoulli\((1/2)\) source \( M^\infty \) and every noise sequence \( z^\infty \) best-case achieves

\[
\sigma(z^\infty) - \delta_m(z^\infty), \quad \epsilon_m/(\sigma(z^\infty) - \delta_m(z^\infty)),
\]

and worst-case achieves

\[
\sigma(z^\infty) - \delta_m(z^\infty), \quad \epsilon_m/(\sigma(z^\infty) - \delta_m(z^\infty)),
\]

with probability one, where \( \epsilon_m, \delta_m \), and \( \sigma_m \) all go to zero.

Theorems 2 and 3 are proven in Section VII. In Section VIII, we introduce the schemes \( \{\overline{F}_m^m\}_{m=1}^\infty \) and prove Theorem 4.

VII. Proof of Converse

A. Definitions and Lemmas

In order to prove the converse theorems, a series of definitions and lemmas is first required.

**Lemma 5:** (Selection Lemma) Suppose \( X^\infty \) is iid Bernoulli\((1/2)\) and \( L \) is a random positive integer with arbitrary conditional distribution \( p_{L|X^\infty} \) with respect to \( X^\infty \). Then \( H(X^L) \leq E[L] \).

**Proof:**

\[
H(X^L) = \sum_{x^l} p(X^L = x^l) \log \frac{1}{p(X^L = x^l)}
\geq \sum_{x^l} p(X^L = x^l) \log \frac{1}{p(x^l)}
\geq \sum_{x^l} p(X^L = x^l) l
= E[L]
\]

where step (a) follows because if \( X^L = x^l \) then \( X^L \) must necessarily equal \( x^l \). Step (b) follows from the iid Bernoulli \((1/2)\) distribution of \( X^\infty \).  

**Definition 1:** Let \( \{L_i\}_{i=1}^\infty \) be a bounded sequence of nonnegative integers, and let \( M^\infty \) and \( z^\infty \) as usual denote binary sequences. The \( k \)-partition of \( (M^\infty, z^\infty) \) according to \( \{L_i\} \) is the sequence of blocks

\[
(M_{L_i}, z^k)_i = M_{\sum_{j=1}^{i-1} L_j + 1}^{\sum_{j=1}^{i} L_j}, z^{k(i-1)+1}.
\]

In this context, \( \{L_i\} \) are referred to as the partition lengths.

**Definition 2:** Let \( x^\infty \) be a sequence of symbols drawn from a finite alphabet \( \mathcal{X} \). If there exists a series of sample points \( \{n_k\}_{k=1}^\infty \) such that the sequence \( \hat{p}^1(x|z^n) \) converges to a distribution \( \hat{p}(x) \), \( \hat{p}(x) \) is said to be a limiting distribution for \( x^\infty \). Observe that for any finite-alphabet sequence \( x^\infty \) at least one limiting distribution exists: \( \hat{p}^1(x|z^n) \) is an infinite sequence in a compact set, so at least one convergent subsequence must exist.

**Definition 3:** Let \( z^\infty \) be a finite-alphabet sequence. The set \( \mathcal{M}_k(z^\infty) \) consists of all binary sequences \( M^\infty \) such that there exist partition lengths \( \{L_i\} \), a resulting \( k \)-partition \( \{M_{L_i}, z^k\}_i \), and a limiting distribution \( \hat{p}(L, M^L, z^k) \) for the sequence \( \{L_i, (M_{L_i}, z^k)_i\} \) such that

\[
E[L]\hat{p} > H_{\hat{p}}(M^L|z^k) + 1.
\]

We may interpret the set in the following manner. Suppose first that a “genie” partitions the source sequence \( M^\infty \) into an arbitrary series of variable-length blocks \( \{(M_{L_i})\}_i \). Each block \( (M_{L_i})_i \), of length \( L_i \), is then source-coded with side
information \((z^k)\), at average rate less than \(H_p(M^L|z^k) + 1\). The set \(M_k(z^\infty)\) consists of all source sequences that, in a sense, allow such a genie/side-information-source-coding setup to compress strictly better than one bit per source symbol. One would expect that the occurrence of such a set is a rare event when the source is drawn iid Bernoulli\((1/2)\). This is formalized with the following lemma.

**Lemma 6:** Let \(z^\infty\) be a fixed finite-alphabet sequence, and let \(M^\infty\) be drawn from an iid Bernoulli\((1/2)\) process. Then the probability that \(M^\infty \in M_k(z^\infty)\) is zero for all \(k\).

**Proof:** See Appendix \[3\]

We may easily expand this lemma to allow for common randomness.

**Corollary 7:** Let \(z^\infty\) be a fixed binary sequence, let \(M^\infty\) be drawn from an iid Bernoulli\((1/2)\) process, and let \(\theta^\infty\) be a finite-alphabet sequence of arbitrary distribution that is independent of \(M^\infty\). Then the probability that \(M^\infty \in M_k((z_i, \theta_i)_{i=1}^{\infty})\) is zero for any \(k\).

**Proof:** First observe that Lemma \[3\] does not require that \(z^\infty\) be a binary sequence — only that it be of a finite alphabet. As such, for a given sequence \(\theta^\infty\) we may define the surrogate \(z\)-sequence \(z^\infty = (z_i, \theta_i)_{i=1}^{\infty}\).

Applying Lemma 6 for this surrogate sequence, we have that for any fixed \(z^\infty\) and \(\theta^\infty\), the probability of drawing an element of \(M_k((z_i, \theta_i)_{i=1}^{\infty})\) from a Bernoulli\((1/2)\) process is zero. Since \(\theta^\infty\) is independent from \(M^\infty\), the corollary follows. ■

### B. Converse Lemma

Although the converse results are presented as two distinct theorems, at their heart is the same argument. We present this core result in the following lemma.

**Lemma 8:** Suppose an \(s\)-state \(\ell\)-lookahead FS scheme achieves \((R, \epsilon)\) on points \(\{n_i\}\) for a specific source sequence \(M^\infty\), a specific channel noise sequence \(z^\infty\), and a specific encoder/decoder common information sequence \(\theta^\infty\). If for some \(k \in \mathbb{Z}^+\), \(M^\infty\) is not a member of \(M_k((z_i, \theta_i)_{i=1}^{\infty})\), and if \(H_k(z^\infty) + H_k(\theta^\infty) - H_k((z_i, \theta_i)_{i=1}^{\infty}) \to n \to \infty 0\), then

\[
R \leq 2 \log s + \ell + \frac{2}{k} + h_k(\epsilon) + 1 - \limsup_{i \to \infty} \frac{1}{k} \hat{H}_k(z_i^\infty).
\]

The general idea in proving this lemma is to turn any given FS scheme into a source encoding/decoding scheme. Consider an FS decoder that achieves \((R, \epsilon)\) on some points \(\{n_i\}\), and ignore the minor complication of common randomness \(\theta^\infty\). Given only the channel output \(y^\infty\), the decoder produces an estimate of the source sequence \(M^\infty\). Knowing the source sequence and the channel output, the decoder is technically capable of “simulating” the encoder and thereby obtaining both the channel input sequence \(x^\infty\) and the noise sequence \(z^\infty\). One may therefore interpret the channel output \(y^\infty\) as an encoding of the joint source sequence \((M^\infty, z^\infty)\). The following proof utilizes a rigorous argument inspired by this intuition.

**Proof:** Let \(e^\infty\) denote the error indication sequence \(e_i = 1_{M_i \neq \hat{M}_i}\). First, consider the \(k\)-partition of \((M^\infty, z^\infty, \theta^\infty, e^\infty)\) according to the given FS scheme:

\[
(M^{L_i}, e^{L_i}, z^k, \theta^k)_{i=1}^{\infty} = (M^{p_{i(k+1)}-1}_{p_{i(k+1)}}, e^{p_{i(k+1)}-1}_{p_{i(k+1)}}, z^{i_{(k+1)}}_{i_{(k+1)}}, \theta^k_{i_{(k+1)}})_{i=1}^{\infty}.
\]

In other words, let \((M^{L_i}, e^{L_i}, z^k, \theta^k)\) enumerate \(k\)-blocks of channel noise and common information, along with the source bits that are estimated during each such block and the error indicators for these source bits. Let \(L_i = p_{i(k+1)} - p_{(i+1)-k+1}\) denote the partition lengths.

Now define the sequence of points \(\{n_i^*\} \subset \{n_i\}\) so that

\[
\lim_{i \to \infty} \frac{1}{k} \hat{H}_k(z_{n_i^*}) = \limsup_{i \to \infty} \frac{1}{k} \hat{H}_k(z_{n_i^*}),
\]

and let \(p(M^L, e^L, z^k, \theta^k)\) be a limiting distribution of \((M^L, z^k, \theta^k)_i\) on these points \(\{n_i^*\}\). Recall from Def. \[2\] that such a limiting distribution always exists.

Suppose random variables \((M^L, e^L, z^k, \theta^k)\) are distributed according to \(p(M^L, z^k, \theta^k)\). We first use the FS scheme given in the lemma statement to construct a lossless source encoder/decoder for \((M^L, z^k)\), with \(\theta^k\) as side information. By later requiring that the rate of this encoding exceed \(H_p(M^L, z^k|\theta^k)\), the lemma may be proven.

**E1** Let \(j \in \mathbb{Z}^+\). We construct a codeword for the source block \((M^{L_j}, z^k)\) given side information block \((\theta^k)_{j}\) as follows:

1. To reduce clutter, we remove some of the unnecessary indices. Denote the source bits used by the FS encoder during this \(j\)th block as \(M^L = M^{p_{j(k+1)}-1}_{p_{j(k+1)}+1} + 1\). Similarly, let the source bits estimated by the FS decoder be referred to as \(\hat{M}^L = \hat{M}^{p_{j(k+1)}-1}_{p_{j(k+1)}+1}\) and the error indicators as \(e^L = e^{p_{j(k+1)}-1}_{p_{j(k+1)}+1}\). Additionally, let \(s^{(e)} = s^{(e)}_{j-1} + 1\) and \(s^{(d)} = s^{(d)}_{j-1} + 1\) indicate the initial encoder and decoder states, and let \(x^k = x^k_{j-1} + 1\) and \(y^k = y^k_{j-1} + 1\) denote the channel inputs and outputs during the block.

2. Apply a binary Huffman code to \(e^L\) to create the compressed representation \(g(e^L) \in \{0, 1\}^*\). The Huffman code is designed according to the limiting empirical distribution \(p(e^L)\).
3) Add the codeword \((s^{(e)}; g^{(e)}; M_{L_{+1}}^{+\ell}, y^k, g(\epsilon^L))\) to the codebook.

4) Observe that \((s^{(e)}; s^{(a)}; M_{L_{+1}}^{+\ell}, g(\epsilon^L))\) decodes uniquely into \((M_L, \theta^k))_j\) given side information block \((\theta^k))_j:\n
- Simulate the channel decoding operation with initial state \(s^{(a)}\), common information \(\theta^k\), and channel output \(y^k\). This yields \(\hat{M}_L\). Correcting for errors with the correctional information embedded in \(g(\epsilon^L)\), we have \(M_L\).
- Simulate the channel encoding operation using initial state \(s^e\), feedback \(y^k\), common information \(\theta^b\), source \(M_L\) from the previous step, and \(M_{L_{+1}}^{+\ell}\) from the codeword. This yields the channel input \(z^k\), which produces \(z^k\) when modulo-2 added to \(y^k\).

Refer to this decoding operation on a codeword \(c\) as \(C^{-1}(c, \theta^k)\).

E2 Build the codebook by repeating step E1 for every block \((M_L, z^k, \theta^k), j \in \mathbb{Z}^+\). Note that each codeword is of length \(2 \log s + \ell + k + \text{length}(g(\epsilon^L))\) and losslessly decodes into its source block. Call this codebook \(\tilde{C}\).

E3 Define the codebook encoding function \(F\) of a source sample \((M_L, z^k|\theta^k)\) as mapping to the shortest codeword in the set \(\{c \in \tilde{C} : C^{-1}(c, \theta^k) = (M_L, z^k)\}\).

We now establish the expected length of this code when applied to the probabilistic source \((M_L, z^k|\theta^k)\). As mentioned in step E2, a given codeword is of length \(2 \log s + \ell + k + \text{length}(g(\epsilon^L))\), where \(\epsilon^L\) is the error sequence. According to the assumptions of the lemma, the bit error rate on points \(\{n_i^*\}\) is upper-bounded by \(\epsilon\). From this and from \(p(\epsilon^L)\) being a limiting distribution on \(\{n_i^*\}\), the expected frequency of 1 in \(\epsilon^L\) may be upper-bounded by \(\epsilon\). Therefore, the expected length of \(g(\epsilon^L)\) is upper-bounded by \(kh_b(\epsilon) + 1\), and

\[
\mathbb{E} \left[ \text{length}(F(M_L, z^k|\theta^k)) \right] \leq 2 \log s + \ell + k(1 + h_b(\epsilon)) + 1.
\]

Since \(F\) is a lossless variable-length encoder for sources drawn from \(p(M_L, z^k|\theta^k)\), the expected codeword length must exceed the conditional entropy according to \(p\):

\[
2 \log s + \ell + k(1 + h_b(\epsilon)) + 1 \geq H_p(M_L, z^k|\theta^k) \geq H_p(z^k|\theta^k) + H_p(M_L|z^k, \theta^k)
\]

\[
\geq H_p(z^k) + H_p(M_L|z^k, \theta^k)
\]

\[
\geq H_p(z^k) + \mathbb{E}[L]_p - 1
\]

\[
\geq \limsup_{i \to \infty} \hat{H}^k(z^{n_i}) + Rk - 1
\]

where (a) holds because of the final assumption in the theorem statement, (b) follows from Corollary [7] and (c) is due to both \([2]\) and the lemma’s assumption about rate \(R\) being achieved on points \(\{n_i^*\}\). Rearranging terms proves the lemma.

C. Proof of Converse

Armed with Lemma [8] it is a relatively straightforward matter to prove Theorems [2] and [3].

Proof of Theorem [2] We first note that because \(\theta^\infty\) is drawn iid and \(z^\infty\) is fixed, \(\hat{H}^k(z^n) + \hat{H}^k(\theta^n) - \hat{H}^k((z_i, \theta_i)_{i=1}^\infty) \to 0\) with probability one for every \(k\). Furthermore, by Corollary [7] \(M^\infty \notin \mathcal{M}_k((z_i, \theta_i)_{i=1}^\infty)\) with probability one for every \(k\). Therefore, if \((R, \epsilon)\) is best-case-achieved with positive probability, it must then be achieved for some specific \((M^\infty, \theta^\infty)\) such that \(M^\infty \notin \mathcal{M}_k((z_i, \theta_i)_{i=1}^\infty)\) and \(\hat{H}^k(z^n) + \hat{H}^k(\theta^n) - \hat{H}^k((z_i, \theta_i)_{i=1}^\infty) \to 0\) for every \(k\). Let \(\{n_i\}\) be the subsequence on which this is achieved.

Applying Lemma [8]

\[
R \leq \frac{2 \log s + \ell + \sqrt{k}}{k} + h_b(\epsilon) + 1 - \frac{1}{k} \limsup_{i \to \infty} \hat{H}^k(z^{n_i}),
\]

for any \(k\).

Taking the limit supremum as \(k \to \infty\),

\[
R \leq h_b(\epsilon) + 1 - \liminf_{k \to \infty} \frac{1}{k} \limsup_{i \to \infty} \hat{H}^k(z^{n_i})
\]

\[
\leq h_b(\epsilon) + 1 - \liminf_{k \to \infty} \frac{1}{k} \liminf_{i \to \infty} \hat{H}^k(z^{n_i})
\]

\[
\leq h_b(\epsilon) + 1 - \liminf_{k \to \infty} \frac{1}{k} \liminf_{n \to \infty} \hat{H}^k(z^n)
\]

\[
= h_b(\epsilon) + 1 - p(z^\infty).
\]
M_1, \ldots, M_{p_i}, M_{p_i+1}, \ldots, M_{p_i+\ell}, M_{p_i+\ell+1}, \ldots

Fig. 6. A finite-state active feedback scheme for a modulo-additive channel.

Proof of Theorem 9: If \((R, \epsilon)\) is worst-case-achieved with positive probability \(p\), then it must be worst-case achieved for some \((M^\infty, \theta^\infty)\) such that \(M^\infty \not\in M_k((z_i, \theta_i)_{i=1}^\infty)\) (because by Corollary 7 this occurs with probability one) and \(\hat{H}^k(z^n) + \hat{H}^k(\theta^n) - \hat{H}^k((z_i, \theta_i)_{i=1}^n) \to 0\) (because this occurs with probability one when \(\theta^\infty\) is chosen iid).

We may therefore apply Lemma 8 with \(\{n_i\} = \mathbb{Z}^+\). For any \(k\), we have that

\[ R \leq \frac{2\log s + \ell + \sqrt{k}}{k} + h_b(\epsilon) + 1 - \frac{1}{k} \limsup_{n \to \infty} \hat{H}^k(z^n). \]

Since this holds for arbitrary \(k\), we may take the limit infimum of the expression with \(k \to \infty\):

\[
R \leq \liminf_{k \to \infty} \left( \frac{2\log s + \ell + \sqrt{k}}{k} + h_b(\epsilon) + 1 - \frac{1}{k} \limsup_{n \to \infty} \hat{H}^k(z^n) \right)
\]
\[
= h_b(\epsilon) + 1 - \limsup_{k \to \infty} \frac{1}{k} \limsup_{n \to \infty} \hat{H}^k(z^n)
\]
\[
= h_b(\epsilon) + 1 - \overline{p}(z^\infty).
\]

VIII. PROOF OF ACHIEVABILITY

In this section, a sequence of FS schemes is constructed and guaranteed to achieve both the best-case and worst-case bounds for any channel noise sequence \(z^\infty\). This “universal achievability” is analogous to the universal source coding achievability scheme introduced by Ziv and Lempel [2].

A. Some Classes of Schemes

To begin, several additional classes of schemes are introduced, and their relationships with each other and with class FS are clarified. This will prove useful in constructing the universal achievability schemes.

A finite-state active feedback (FSAF) scheme is a variation of the class FS that allows for active feedback (Fig. 5). It consists of the following:

1) An encoder state variable \(s_i^{(e)}\), a decoder state variable \(s_i^{(d)}\), and a feedback state variable \(s_i^{(f)}\), all taking values in a finite set.
2) A source pointer \(p_i\) and a finite lookahead constant \(\ell\).
3) An iid common randomness source \(\theta_i \sim p_\theta\).
4) A finite-state feedback channel whose output at time \(i\) is distributed according to \(U_i \sim p_{u_i|y_i,s}(u_i|y_i, s_i^{(f)})\).
5) An encoding function \(x_i = e(s_i^{(e)}, M_{p_i}^{p_i+\ell}, \theta_i, u_i)\).
6) A decoding length function \(L_i = d_L(s_i^{(d)}, y_i, \theta_i, u_i)\) that also determines the update of the source pointer: \(p_{i+1} = p_i + L_i\).
7) A decoding function \(\tilde{M}_{p_i}^{p_i+L_i-1} = d_M(s_i^{(d)}, y_i, \theta_i, u_i)\).
8) State-update functions for the encoder \(s_{i+1}^{(e)} = f_\sigma(s_i^{(e)}, M_{p_i}^{p_i+\ell}, \theta_i, u_i)\), decoder \(s_{i+1}^{(d)} = f_\sigma(s_i^{(d)}, y_i, \theta_i, u_i)\), and feedback channel \(s_{i+1}^{(f)} = f_\sigma(s_i^{(f)}, y_i, \theta_i)\).

Lemma 9: The class of schemes FSAF is equivalent to class FS.

Proof: By setting \(U_i = y_i\), we find that FS is a special case of FSAF. To show the other direction, first assume we are given an FSAF scheme. By the arguments that follow, we will construct an FS scheme that simulates it. Quantities relating to the constructed FS scheme will be notated with a “hat,” e.g. \(\hat{\theta}, \hat{s}_i^{(e)}\), etc.

First, let \(\hat{U}\) be a random vector with components indexed by \(y \in X\) and \(s \in S^{(f)}\), and let the \((y,s)\)th component be distributed according to \(U_{y,s} \sim p_{U|y,s}\), where \(p_{U|y,s}\) is the given FSAF scheme’s feedback channel transition matrix. Furthermore, let the components be independently distributed. Then we define the FS scheme’s common randomness as \(\hat{\theta}_i = (\hat{\theta}_i, U_i)\) distributed.
Since this constructed FS scheme is identical to the given FSAF scheme, FSAF is a special case of FS.

The equivalent FS scheme is assigned encoder and decoder state variables $\hat{s}_i^{(e)} = (s_i^{(e)}, s_i^{(f)})$ and $\hat{s}_i^{(d)} = (s_i^{(d)}, s_i^{(f)})$, where $s_i^{(e)}$, $s_i^{(d)}$, and $s_i^{(f)}$ are the state variables for the FSAF scheme. The encoder/decoder update functions are given by

$$\hat{f}_0(\hat{s}_i^{(e)}, M_{p_i}, y_i, \theta_i) = \left( f_0(s_i^{(e)}, M_{p_i}, y_i, (U_{y_i}, s_i^{(d)})), f_1(s_i^{(d)}, y_i, \theta_i) \right),$$

and

$$\hat{f}_0(\hat{s}_i^{(d)}, y_i, \theta_i) = \left( f_0(s_i^{(e)}, y_i, \theta_i, (U_{y_i}, s_i^{(d)})), f_1(s_i^{(d)}, y_i, \theta_i) \right).$$

Observe how the randomness of the FSAF scheme’s active feedback channel is simulated by means of the common randomness $\hat{\theta}_i = (\theta_i, U_i)$.

In this manner the FSAF encoder/decoder/feedback state machines are simulated by the FS encoder/decoder state machines. The FSAF encoding and decoding functions may be implemented in a similar manner:

$$\hat{e}(\hat{s}_i^{(e)}, M_{p_i}, y_i, \hat{\theta}_i) = e(s_i^{(e)}, M_{p_i}, y_i, (U_{y_i}, s_i^{(d)})), $$

and

$$\hat{d}_M(\hat{s}_i^{(d)}, y_i, \hat{\theta}_i) = d_M(s_i^{(d)}, y_i, \theta_i, (U_{y_i}, s_i^{(d)})).$$

Since this constructed FS scheme is identical to the given FSAF scheme, FSAF is a special case of FS.

A finite-extent (FEEx) scheme $\mathcal{F}$ for a channel with alphabet $\mathcal{X}$ — as depicted in Fig. 7 consists of:

1) A extent $n$.
2) A feedback channel with transition probabilities given by $U_i \sim p_u(u_i|u^{i-1}, y^i)$ and taking values in $\mathcal{X}$, for $i \in \{1, \ldots, n\}$.
3) A common randomness variable $\theta$ drawn from a finite alphabet, independent of the source, and provided to both encoder and decoder.
4) Encoding functions $x_1 = e_1(M^\infty, \theta), x_2 = e_2(M^\infty, \theta, u_1), \ldots, x_n = e_n(M^\infty, \theta, u^{n-1})$.
5) A decoding length function $L = d_L(y^n, \theta, u^{n-1})$, upper bounded by $n \log |\mathcal{X}|$.
6) A decoding function $\hat{M}^L = d_M(y^n, \theta, u^{n-1})$.

A repetition scheme is constructed from an $n$-extent FE scheme $\mathcal{F}$ for a channel with alphabet $\mathcal{X}$ — as depicted in Fig. 7. Let $\mathcal{F}(M^\infty, z^n)$ describe the application of scheme $\mathcal{F}$ to source $M^\infty$ and noise block $z^n$. Then the repetition scheme $\mathcal{F}$ consists of repeated independent uses of $\mathcal{F}$, i.e.

$$\mathcal{F}(M^\infty, z^n) = \left\{ \mathcal{F}((M^n_1, 0^n_1), z^n_1), \mathcal{F}((M^n_{L_1+1}, 0^n_{L_1+1}), z^n_{L_1+1}), \ldots \right\}.$$

In each block, $\mathcal{F}$ is applied to a “virtual source” consisting of the first $n$ bits of the source that have yet to be transmitted and a string of 0s.

**Proposition 10:** The class of repetition schemes is a subclass of FSAF schemes (and therefore of FS schemes). This follows directly from two properties of repetition schemes:

- The block-based structure allows for implementation with finite-state machines.
- A repetition scheme constructed from an $n$-extent FE scheme has finite lookahead constant $n$. 

Fig. 7. A finite-extent scheme.
B. Universal Scheme Construction

At the core of the achievability scheme is a lemma, introduced and proven by Shayevitz and Feder [5]:

Lemma 11: (Shayevitz and Feder, 2009) Let \( \mathcal{X} \) be a finite alphabet with an addition operation. Then there exists a sequence of \( n \)-extent FE schemes \( \mathcal{F}_n(\mathcal{X}) \) with the following worst-case performance guarantees over all additive noise sequences \( z^\infty \in \mathcal{X}^\infty \) and source sequences \( M^\infty \in \{0, 1\}^\infty \)

\[
\sup_{z^n \in \mathcal{X}^n, M^\infty \in \{0, 1\}^\infty} P \left( \hat{M}^L \neq M^L \right) \leq \epsilon(n) \tag{3}
\]

and

\[
\inf_{z^n \in \mathcal{X}^n, M^\infty \in \{0, 1\}^\infty} P \left( \frac{L}{n} > 1 - \hat{H}^1(z^n) - \epsilon(n) \right) > 1 - \epsilon(n), \tag{4}
\]

where \( \epsilon(n) \to 0 \).

Note that the only randomness in the above probabilistic statements is due to the randomness in the feedback channel.

Observe that Lemma 11 concerns itself with only the first-order empirical entropy \( \hat{H}^1(z^n) \). By specializing to binary sequences, this may be replaced by higher-order empirical entropies.

Corollary 12: For binary additive noise channels with feedback, there exists a sequence of finite extent schemes \( \mathcal{F}^m \) with extents \( N(m) \to \infty \) and the following performance guarantees:

\[
\sup_{z^{N(m)} \in \mathcal{X}^{N(m)}, M^\infty \in \{0, 1\}^\infty} P \left( \hat{M}^L \neq M^L \right) \leq \epsilon_m \tag{5}
\]

and

\[
\inf_{z^{N(m)} \in \mathcal{X}^{N(m)}, M^\infty \in \{0, 1\}^\infty} P \left( \frac{L}{N(m)} > 1 - \frac{1}{m} \hat{H}^m(z^{N(m)}) - \epsilon_m \right) > 1 - \epsilon_m, \tag{6}
\]

where \( \epsilon_m \to 0 \).

Proof: For a given \( m \), consider the \( m \)-tuple supersymbol channel characterized by inputs \( X_i = x_{(i-1)m+1}^m \), noise \( Z_i = z_{(i-1)m+1}^m \), and outputs \( Y_i = x_{(i-1)m+1}^m + z_{(i-1)m+1}^m \). Applying Lemma 11 to channels of this alphabet yields a sequence of schemes \( \mathcal{F}_n(\{0, 1\}^m) \) with

\[
\epsilon_{n,m} \to_0 0. \tag{7}
\]

Observe that \( \mathcal{F}_n(\{0, 1\}^m) \) may be seen as a finite-extent scheme both for the supersymbol alphabet \( \{0, 1\}^m \) additive noise channel as well as for the (fundamental) binary alphabet \( \{0, 1\} \) additive noise channel.

By (7) we may choose \( N(m) \) so that \( \epsilon_{N(m),m} \to_0 0 \). Denoting \( \mathcal{F}^m = \mathcal{F}_n(\{0, 1\}^m) \), this proves the lemma.

The sequence of finite-extent schemes \( \{\mathcal{F}^m\}_{m=1}^{\infty} \) form the basis of the universal achievability construction.

Definition 4: The universal achievability scheme of order \( m \) is the repetition scheme \( \bar{\mathcal{F}}^m \) formed from the \( N(m) \)-extent scheme \( \mathcal{F}^m \).

We end with an important lemma regarding repetition schemes.

Lemma 13: Let \( \mathcal{F} \) be an \( N \)-extent FE scheme and let \( \bar{\mathcal{F}} \) be the corresponding repetition scheme. Define \( E_i \) be the error indicator for the \( i \)th block and define \( T_i = 1_{L_i \geq \alpha_i} \), so as to indicate if in the \( i \)th block the number of bits transmitted exceeds a fixed threshold \( \alpha_i \). Then the Markov relations

\[
E_i - M_{(i)}^N - E^{i-1} \tag{8}
\]

and

\[
T_i - M_{(i)}^N - T^{i-1} \tag{9}
\]

both hold, where \( M_{(i)}^N = \sum_{j=1}^{i-1} L_j + N \sum_{j=1}^{i} L_j + 1 \) denotes the \( N \) source samples used in the \( i \)th block by the repetition scheme.

Proof: See Appendix C.

C. Proving Achievability (Theorem 4)

Two additional lemmas, regarding the limiting behavior of random binary sequences, are required in order to prove that \( \bar{\mathcal{F}}^m \) achieves the performance promised in Theorem 4.

Lemma 14: Suppose \( \{X_i\} \) is a sequence of iid Bernoulli(\( p \)) random variables, and suppose \( \{\alpha_i\} \) is a bounded sequence of real numbers. Then with probability one,

\[
\lim_{n \to \infty} \sup_{i=1}^{n} \frac{1}{n} \sum_{i=1}^{n} X_i \alpha_i = p \lim_{n \to \infty} \sup_{i=1}^{n} \frac{1}{n} \sum_{i=1}^{n} \alpha_i
\]
and
\[ \liminf_{n \to \infty} \frac{1}{n} \sum_{i=1}^{n} X_i \alpha_i = p \liminf_{n \to \infty} \frac{1}{n} \sum_{i=1}^{n} \alpha_i. \]

**Proof:** Let \( Y_i = \alpha_i X_i \). Since \( \alpha_i \) is bounded, there exists constant \( A \) such that \( |\alpha_i| < A \). We then have that \( E \{ Y_i^2 \} \leq A^2 \) is bounded and \( \sum_{i=1}^{\infty} \frac{1}{n} \text{var} Y_i \leq A^2 \sum_{i=1}^{\infty} \frac{1}{n} < \infty \). These two statements qualify the use of Kolmogorov’s strong law, which states that \( \frac{1}{n} \sum_{i=1}^{n} Y_i - \frac{1}{n} \sum_{i=1}^{\infty} \alpha_i p \to 0 \) with probability one. This proves the lemma.

**Lemma 15:** Let \( \{ \alpha_i \} \) be a bounded real-valued sequence, and let \( \{ X_i \} \) be a random binary process. If \( P ( X_i = 1 | X^{i-1} = x^{i-1} ) \leq p \) for any \( x^{i-1} \in \{0, 1\}^{i-1} \), then with probability one
\[ \limsup_{n \to \infty} \frac{1}{n} \sum_{i=1}^{n} \alpha_i X_i \leq p \alpha \tag{8} \]
\[ \liminf_{n \to \infty} \frac{1}{n} \sum_{i=1}^{n} \alpha_i X_i \geq \alpha p \tag{9} \]
where \( \alpha = \limsup_{n \to \infty} \sum_{i=1}^{n} \alpha_i \) and \( \alpha = \liminf_{n \to \infty} \sum_{i=1}^{n} \alpha_i \). Similarly, if \( P ( X_i = 1 | X^{i-1} = x^{i-1} ) \geq p \) for any \( x^{i-1} \in \{0, 1\}^{i-1} \),
\[ \limsup_{n \to \infty} \frac{1}{n} \sum_{i=1}^{n} \alpha_i X_i \geq p \alpha \tag{10} \]
\[ \liminf_{n \to \infty} \frac{1}{n} \sum_{i=1}^{n} \alpha_i X_i \leq p \alpha \tag{11} \]

**Proof:** Let \( \{ Y_i \} \) be a Bernoulli-\( p \) iid process. We will construct correlated binary processes \( \{ \tilde{X}_i, \tilde{Y}_i \} \) whose marginal distributions are identical to those of \( \{ X_i \} \) and \( \{ Y_i \} \), and use these to prove the lemma.

- Let \( \{ U_i \} \) be a sequence of independent uniform \([0, 1]\) random variables.
- For each \( i \) let
  \[ \tilde{X}_i = \begin{cases} 1 & \text{if } U_i < P ( X_i = 1 | X^{i-1} = \tilde{X}^{i-1} ) \\ 0 & \text{otherwise} \end{cases} \]
  and
  \[ \tilde{Y}_i = \begin{cases} 1 & \text{if } U_i \leq p \\ 0 & \text{otherwise} \end{cases} \]
- By Lemma\(^4\) \( \limsup_{n \to \infty} \frac{1}{n} \sum_{i=1}^{n} \alpha_i \tilde{Y}_i = p \alpha \) and \( \liminf_{n \to \infty} \frac{1}{n} \sum_{i=1}^{n} \alpha_i \tilde{Y}_i = p \alpha \).
- Consider the case where \( P ( X_i = 1 | X^{i-1} = x^{i-1} ) \leq p \). Then since \( \tilde{X}_i \leq \tilde{Y}_i \) we have that
  \[ \limsup_{n \to \infty} \frac{1}{n} \sum_{i=1}^{n} \alpha_i \tilde{X}_i \leq p \alpha \]
  and
  \[ \liminf_{n \to \infty} \frac{1}{n} \sum_{i=1}^{n} \alpha_i \tilde{X}_i = p \alpha \]
  with probability one. Since \( \{ X_i \} \) has the same marginal distribution as \( \{ \tilde{X}_i \} \), this proves (8) and (9).
- Similarly, in the case where \( P ( X_i = 1 | X^{i-1} = x^{i-1} ) \geq p \), the relation \( \tilde{X}_i \geq \tilde{Y}_i \) always holds and we have (10) and (11).

**Proof of Theorem 2** Suppose \( \tilde{\Phi}^m \) is applied to a source \( M^\infty \) and noise sequence \( z^\infty \). Let \( \{ L_i \} \) be the number of source bits decoded in each block. Consider the \( i \)th block — i.e., \( \mathcal{F} \left( (M_{\sum_{j=1}^{i-1} L_i + N(m)}^{i N(m)} \big| z_{i-1}^{N(m)}), \tilde{z}_{(i-1) N(m)+1}^{i N(m)} \right) \). Let \( M_{(i)} \) indicate the source bits used by the encoder, let \( \hat{M}_{(i)} \) indicate the estimate produced, \( R_{(i)} = \frac{i N(m)}{N(m)} \) indicate the rate of the block, and let \( \hat{z}_{(i)} \) denote the noise of the block. Finally, let \( u_{(i)} = u_{(i-1) N(m)+1} \) denote the feedback during the block.

**Rate Guarantees**
Recalling that \( \epsilon_m \) denotes the rate-error guarantee in Corollary \([12]\) define the “rate indicator” \( T_i \) as the indication of whether the rate in the \( i \)th block exceeds the threshold \( 1 - \frac{1}{m} \hat{H}^m((z_{(i)}^N)) - \epsilon_m \), i.e.

\[
T_i = \mathbb{I}_{R_i \geq 1 - \frac{1}{m} \hat{H}^m((z_{(i)}^N)) - \epsilon_m}.
\]

One may demonstrate that for any \( i \) and any \( t^{i-1} \in \{0, 1\}^{i-1} \), \( P (T_i | T^{i-1} = t^{i-1}) \geq 1 - \epsilon_m \):

\[
P (T_i = 1 | T^{i-1} = t^{i-1}) = \sum_{m(N) \in \{0,1\}^{N(m)}} \left[ P (T_i = 1 | T^{i-1} = t^{i-1}, M_{(i)}^{N(m)} = m^{N(m)}) \cdot \right.
\]

\[
\left. \sum_{m(N) \in \{0,1\}^{N(m)}} \left[ P (T_i = 1 | M_{(i)}^{N(m)} = m^{N(m)}) \cdot P (M_{(i)}^{N(m)} = m^{N(m)} | T^{i-1} = t^{i-1}) \right] \right]
\]

where step (a) follows from the Markov relation (Lemma \([13]\)) and step (b) follows from the definition of \( \epsilon_m \).

One may demonstrate that for any \( i \) and any \( t^{i-1} \in \{0, 1\}^{i-1} \), \( P (T_i | T^{i-1} = t^{i-1}) \geq 1 - \epsilon_m \):

\[
P (T_i = 1 | T^{i-1} = t^{i-1}) = \sum_{m(N) \in \{0,1\}^{N(m)}} \left[ P (T_i = 1 | T^{i-1} = t^{i-1}, M_{(i)}^{N(m)} = m^{N(m)}) \cdot \right.
\]

\[
\left. \sum_{m(N) \in \{0,1\}^{N(m)}} \left[ P (T_i = 1 | M_{(i)}^{N(m)} = m^{N(m)}) \cdot P (M_{(i)}^{N(m)} = m^{N(m)} | T^{i-1} = t^{i-1}) \right] \right]
\]

where step (a) follows from the Markov relation (Lemma \([13]\)) and step (b) follows from the definition of \( \epsilon_m \).

Applying Lemma \([15]\) to \( \{T_i\} \), \( \text{(10)} \) bounds the limit supremum rate of the scheme.

\[
\limsup_{k \to \infty} \frac{1}{k} \sum_{i=1}^{k} R_i \geq \limsup_{k \to \infty} \frac{1}{k} \sum_{i=1}^{k} R_i T_i \geq \limsup_{k \to \infty} \frac{1}{k} \sum_{i=1}^{k} T_i \left( 1 - \hat{H}^m(z_{(i)}^N) - \epsilon_m \right)
\]

\[
\geq (1 - \epsilon_m) \limsup_{k \to \infty} \frac{1}{k} \sum_{i=1}^{k} \left( 1 - \hat{H}^m(z_{(i)}^N) - \epsilon_m \right) \text{ w.p.1}
\]

\[
\geq (1 - \epsilon_m) \limsup_{k \to \infty} \left( 1 - \hat{H}^m(z_{(i)}^N) - \epsilon_m \right) \text{ w.p.1}
\]

\[
\geq (1 - \epsilon_m) \left( 1 - \delta_{m}(z^{\infty}) - \rho(z^{\infty}) \right) \text{ w.p.1,}
\]

where step (a) is due to \( T_i \leq 1 \), step (b) follows from the definition of \( T_i \), step (c) is an application of \( \text{(10)} \) from Lemma \([15]\).

A similar line of logic can demonstrate the limit infimum rate bound:

\[
\liminf_{k \to \infty} \frac{1}{k} \sum_{i=1}^{k} R_i \geq \liminf_{k \to \infty} \frac{1}{k} \sum_{i=1}^{k} R_i T_i \geq \liminf_{k \to \infty} \frac{1}{k} \sum_{i=1}^{k} T_i \left( 1 - \hat{H}^m(z_{(i)}^N) - \epsilon_m \right)
\]

\[
\geq (1 - \epsilon_m) \liminf_{k \to \infty} \frac{1}{k} \sum_{i=1}^{k} \left( 1 - \hat{H}^m(z_{(i)}^N) - \epsilon_m \right) \text{ w.p.1}
\]

\[
\geq (1 - \epsilon_m) \liminf_{k \to \infty} \left( 1 - \hat{H}^m(z_{(i)}^N) - \epsilon_m \right) \text{ w.p.1}
\]

\[
\geq (1 - \epsilon_m) \left( 1 - \overline{\delta}_{m}(z^{\infty}) - \overline{\rho}(z^{\infty}) \right) \text{ w.p.1,}
\]

where in the final step we define

\[
\overline{\delta}_{m}(z^{\infty}) = \epsilon_m + \liminf_{k \to \infty} \hat{H}^m(z_{(i)}^{k,N}) - \rho(z^{\infty}).
\]

As in the infimum case, since \( \limsup_{k \to \infty} \hat{H}^m(z_{(i)}^{k,N}) = \limsup_{k \to \infty} \hat{H}^m(z^{k}) \) and by Lemma \([11]\) \( \overline{\rho}(z^{\infty}) = \lim_{m \to \infty} \limsup_{k \to \infty} \frac{1}{m} \hat{H}^m(z^{k}) \), we have that \( \delta_{m}(z^{\infty}) \) vanishes as \( m \to \infty \).
Error Guarantees Let $E_i$ indicate the presence of an error in the $i$th block, i.e. $E_i = \mathbb{1}_{\hat{M}_{(i)} = M_{(i)}}$. The limit-supremum bit-error rate may be written in terms of $\{E_i\}$ and $\{L_i\}$ as:

$$
\limsup_{n \to \infty} \frac{1}{n} \sum_{i=1}^{n} E_i L_i = \limsup_{n \to \infty} \frac{1}{n} \sum_{i=1}^{n} E_i L_i
\leq \limsup_{n \to \infty} \frac{1}{n} \sum_{i=1}^{n} E_i \\
\leq \liminf_{n \to \infty} \frac{1}{n} \sum_{i=1}^{n} E_i N(m)
\leq \frac{N(m) \limsup_{n \to \infty} \frac{1}{n} \sum_{i=1}^{n} E_i}{N(m) \left(1 - \mathbb{P}(z^\infty) - \delta_m(z^\infty)\right)} \text{ w.p.1,}
$$

where (a) holds because $L_i \leq N(m)$ for an $N(m)$-horizon repetition scheme, (b) follows with probability one from (15).

As was done with $\{T_i\}$, one may demonstrate that for any $i$ and $e^{i-1} \in \{0,1\}^{i-1}$, the bound $P \left( E_i = 1 | E^{i-1} = e^{i-1} \right) \leq \epsilon_m$ holds:

$$
P \left( E_i = 1 | E^{i-1} = e^{i-1} \right) = \sum_{m^{N(m)} \in \{0,1\}^{N(m)}} \left[ P \left( E_i = 1 | E^{i-1} = e^{i-1}, M_{(i)}^{N(m)} = m^{N(m)} \right) \right].
\leq \sum_{m^{N(m)} \in \{0,1\}^{N(m)}} \left[ P \left( E_i = 1 | M_{(i)}^{N(m)} = m^{N(m)} \right) P \left( M_{(i)}^{N(m)} = m^{N(m)} | E^{i-1} = e^{i-1} \right) \right] (a)
\leq \epsilon_m.
$$

where step (a) follows from the Markov relation (Lemma 13) and step (b) is due to the error bound in Corollary 12. This allows for the application of Lemma 15 to $\{E_i\}$ with constant weights $\alpha_i = 1$, establishing that

$$
\limsup_{n \to \infty} \frac{1}{n} \sum_{i=1}^{n} E_i \leq \epsilon_m.
$$

This in turn may be inserted into (16), proving

$$
\limsup_{n \to \infty} \frac{1}{n} \sum_{i=1}^{n} E_i L_i \leq \frac{\epsilon_m}{1 - \mathbb{P}(z^\infty) - \delta_m(z^\infty)} \text{ w.p.1.}
$$

Therefore scheme $\widehat{m}$ worst-case (and best-case) achieves bit-error rate $\epsilon_m$.

IX. Predictability and a Simpler Sub-Optimal Scheme

The finite-state predictability was introduced by Feder et al. in [13] as an analog of compressibility in the context of universal prediction, just as porosity is an analog in the context of modulo-additive channels. We explore the relationship between porosity and predictability, but we do so with fairly pragmatic motivations.

A. Practicality of $\{\widehat{m}\}$

While the achievability schemes $\{\widehat{m}\}$ manage to asymptotically achieve porosity for any sequence, they are not particularly simple to implement. The complexity of $\widehat{m}$ is hidden within the Shayevitz-Feder empirical-capacity-achieving scheme at its core (Corollary 12). At each time instant, the Shayevitz-Feder decoder is required to compute the posterior of the message given all the channel outputs in the block so far. This computation is linear in the alphabet size, but because $\widehat{m}$ applies Shayevitz-Feder to binary $m$-tuples (Corollary 12), it is exponential in $m$.

Although it grows in complexity quite rapidly, this Horstein-based approach of Shayevitz and Feder is actually quite efficient for small alphabets, e.g. binary. The only reason it is applied to $m$-tuples in our construction is to account for memory and correlation within the noise sequence. Alternatively stated, we seek to achieve the $m$th-order empirical capacity for arbitrarily large $m$. The simpler repetition schemes suggested in this section take a layered approach, wherein memory and correlation is first “removed” from the noise sequence, after which the binary-alphabet Shayevitz-Feder scheme is used to communicate with the decoder.
B. Construction of layered scheme

In defining the more practical repetition schemes \( \mathcal{G}_n \), we first describe the finite-extent schemes \( \{ \mathcal{G}_n \} \) at their heart. As shown in Fig. 8 in its inner layer \( \mathcal{G}_n \) consists of a predictor that forms an estimate \( \hat{z}_i \) for the noise \( z_i \) at each time \( i \in \{1, \ldots, n\} \). By subtracting this prediction from the encoder’s output, a “surrogate” channel is created with “effective” noise \( \hat{z}_i = (z_i - \hat{z}_i)_{i=1}^n \). In other words, the noise \( z^n \) is replaced by a sequence of error indications for the predictor (Fig. 9). The first-order finite-extent scheme \( \mathcal{F}_n(\{0,1\}) \) (defined in Lemma 11), which we will refer to simply as \( \mathcal{F}_n \), is then applied to this surrogate channel. Roughly speaking, the prediction step exploits the memory and correlation in \( z^n \) in order to reduce its first-order empirical entropy, which then serves to boost the performance of \( \mathcal{F}_n \).

To aid in formally constructing \( \{ \mathcal{G}_n \} \), define the following:

- \( \{e_i^F\} \) refers to the encoding functions for \( \mathcal{F}_n \).
- \( d_i^{L} \) and \( d_i^{M} \) refer to the decoding-length and decoding-message functions of \( \mathcal{F}_n \).
- \( \{p_i(u_i|u_i^{-1}, y_i)\} \) is the set of feedback conditional distributions for \( \mathcal{F}_n \), and \( \theta_F \) is the common randomness.
- \( \hat{z}_i = f(z^{i-1}) \) is the estimation function implemented by the prediction scheme (which has yet to be described).

The prediction-based FE scheme \( \mathcal{G}_n \) can then be defined in terms of the six components listed in the definition of FE schemes:

1) The extent is \( n \).
2) The feedback channel is a simple delay-one noiseless feedback: \( u_i = y_{i-1} \).
3) The common randomness is given by \( \theta_i = (\theta_F, U^{(1)}, U^{(2)}, \ldots, U^{(n)}) \). \( U^{(i)} \) is a \( \mathcal{A}^{2^{2i-1}} \)-valued vector indexed by \((y^i, u_i^{-1})\). The \((y^i, u_i^{-1})\)-th component \( U_{y^i,u_i^{-1}}^{(i)} \) is distributed according to \( p_i(\cdot|y^i, u_i^{-1}) \). Note that \( U^{(i)} \) is introduced only to simulate the feedback channel of scheme \( \mathcal{F}_n \) at both encoder and decoder. This is similar to the technique used in the proof of Lemma 9.
4) To define the \( i \)-th encoding function, first let \( u_i^F = U_{y^i,u_i^{-1},F}^{(i)} \) be the simulated feedback channel. Note that both encoder and decoder may compute \( u_i^F \) at the end of the \( i \)-th time step. The encoding functions are then given by

\[
e_i(M^\infty, \theta, u_i^{-1}) = e_i^F(M^\infty, \theta, u_i^{-1}; F) - f(y_i^{-1} - x_i^{-1}).
\]

5) The decoding length function is unchanged: \( L = d_i^{F}(y^n, \theta, u^{n-1}; F) \).
6) The decoding function is also unchanged: \( \hat{M}^L = d_i^{M}(y^n, \theta, u^{n-1}; F) \).

Fig. 8. Block diagram for the scheme \( \mathcal{G}_n \).

Fig. 9. An alternative block diagram for scheme \( \mathcal{G}_n \), where the prediction loop is represented as a surrogate noise sequence \( \hat{z}^\infty \).
The prediction scheme at the heart of \( G_n \) is the incremental parsing (IP) algorithm introduced by Feder et al. [13]. This is an elegant and simple algorithm that is based on the same parsing procedure as Lempel and Ziv’s compression scheme. Rather than describe its operation in detail, we point the reader towards the exposition in Sec. V of [13].

C. Analysis of performance

The schemes \( \{ G_n \} \) have been constructed to simplify the encoding and decoding process. Here, this notion is quantified.

As a layered scheme, \( G_n \) consists of two machines running in parallel: the IP predictor of Feder et al. [13] and the actual communication scheme \( F_n \) of Shayevitz and Feder [5]. The operations-per-time-step required by \( F_n \) do not scale appreciably with \( n \), so the bottleneck is the prediction operation. Observe that the complexity bottleneck for \( F^m \) also arises from accounting for the noise sequence’s memory and correlation. As previously mentioned, accounting for memory with \( G_n \) requires an exponential number of operations-per-time-step. The IP predictor, on the other hand, requires only a linear number of operations in order to produce an estimate. Specifically, at each time step the Lempel-Ziv parsing tree must be extended.

The rates achieved by schemes \( G_n \), however do not quite reach porosity. To illustrate this, we start by repeating the definition of predictability as given in [13].

**Definition 5:** The finite-state predictability of a sequence \( x^\infty \) is the minimum limit-supremum fraction of errors that a finite-state predictor can attain when operating on \( x^\infty \). Just as with compressibility, one may define a limit infimum version of this quantity. We term the former the worst-case predictability \( \pi \) and the latter the best-case predictability \( \rho \).

In Theorem 4 of [13] it is shown that the IP predictor achieves the worst-case predictability \( \pi(x^\infty) \) of any sequence \( x^\infty \). Though it is not stated in the theorem, the proof that is given also demonstrates that the IP predictor achieves the best-case predictability \( \rho(x^\infty) \). Therefore the limit supremum (or infimum) first-order empirical entropy of the surrogate noise sequence \( h_b(\pi(x^\infty)) \) (or \( h_b(\rho(x^\infty)) \)). By applying the FS schemes \( F^m \) to this noise sequence, the performance approaches rate \( 1 - h_b(\pi(x^\infty)) \) (or \( 1 - h_b(\rho(x^\infty)) \)) with vanishing error.

In Sec. VI of [13], the worst-case predictability \( \pi(x^\infty) \) is bounded in terms of the compressibility:

\[
\frac{1}{2} \| x^\infty \| \leq \pi(x^\infty) \leq \frac{1}{2} \| x^\infty \| .
\]

An identical set of bounds exist between the best-case predictability and best-case compressibility. When a noise sequence satisfies the lower bound with equality, one may observe that the asymptotic performance of \( \{ G_n \} \) matches that of \( \{ F^m \} \). However, this is usually not the case, and one must settle for the guarantee of worst-case rate \( 1 - h_b(\pi(z^\infty)) / 2 \) and best-case rate \( 1 - h_b(\rho(z^\infty) / 2) \). Each falls strictly below worst- and best-case porosity unless the noise sequence is either completely redundant or incompressible.

X. Summary

In this work, the best-case/worst-case porosity \( \pi(\cdot)/\rho(\cdot) \) of a binary noise sequence is defined as one minus the best-case/worst-case compressibility \( 1 - \rho(\cdot)/1 - \pi(\cdot) \). Porosity may be seen as an individual sequence property, analogous to compressibility or predictability, that identifies the ease of communication through a modulo-additive noise sequence. Two results regarding porosity are at the core of this work. First, porosity is identified as the maximum achievable rate within the class of finite-state communication schemes. Second, it is shown that porosity may be universally achieved within this class. Together, these results parallel those of Lempel and Ziv in the source coding context [2]. Furthering this analogy, the achievability schemes given here complement those of Lomnitz and Feder [4] in similar manner as the infinite-state and finite-state schemes of [2].

In addition to the above, a more practical universal communication architecture is introduced, built upon prediction. Rather than communicate using blocks of channel uses — which contributes to an exponentially growing complexity — a layered approach is taken. A prediction algorithm first “removes” the memory from the noise, and then a simple first-order communication scheme is employed. While the resulting algorithm is suboptimal, it reduces complexity considerably, and also draws an operational connection between predictability and porosity.

**APPENDIX A**

**PROOF OF LEMMA 1**

We show that the distinction between block-by-block and sliding-window empirical entropy computations vanishes in the limit of large blocks and long blocklengths. First, a few definitions that simplify notation:

**Definition 6:** A \( k \)-block code \( C \) maps \( k \)-tuples from an alphabet \( \mathcal{X}^k \) into binary strings of arbitrary but finite length.

**Definition 7:** The \( (\theta, k) \)-extension code for a \( k \)-block code \( C \) is a \( \overline{k} \)-block code \( \overline{C}_\theta \) whose encoding of a block \( X^k \) is given by

\[
\overline{C}_\theta(X^k) = \left( X^\theta, C(X^{\theta+k}), \ldots, C(X^{[k-1+\theta]}), X^{[k+1]} \right).
\]
The $\tilde{k}$-extension code is a $\tilde{k}$-block code whose encoding is given by

$$\tilde{C}(X^k) = \arg\min_{\tilde{C}_\theta(X^k) : \theta \in \{0, \ldots, k-1\}} \ell \left( \tilde{C}_\theta(X^k) \right),$$

where $\ell(\cdot)$ returns the length of a binary string.

In both the $\tilde{k}$-extension and the $(\theta, \tilde{k})$-extension, the initial segment of $X^\theta$ is referred to as the uncoded prefix, while the punctuating segment $X^k_{\lfloor \frac{m}{k} \rfloor k + \theta + 1}$ is the uncoded suffix. The encoded segments in the middle are called the encoded subblocks.

We start by demonstrating that the block-by-block empirical entropy limits exist.

**Lemma 16:** Let $x^\infty$ be a finite-alphabet sequence. Then the limits

$$\lim_{k \to \infty} \limsup_{n \to \infty} \frac{1}{k} \hat{H}(x^n)$$

and

$$\lim_{k \to \infty} \liminf_{n \to \infty} \frac{1}{k} \hat{H}(x^n)$$

both exist.

**Proof:** Let $\tilde{k} > k$, and let $C_{n,k}$ denote the $k$-block Huffman code for the block-by-block empirical distribution $\hat{p}(X^k)[x^n]$.

Observe that by optimality of the Huffman code,

$$\hat{H}(x^n) \leq \mathbf{E} \left[ \ell(C_{n,k}(X^k)) \right]_{\hat{p}(X^k)[x^n]} = \mathbf{E} \left[ \ell(C_{n,k}(x_{kN}^k)) \right] \leq \hat{H}(x^n) + 1$$

where $N$ is distributed uniformly over the set $\{0, \ldots, \lfloor \frac{n}{k} \rfloor - 1\}$. Let $C_{n,\tilde{k},\theta}$ and $C_{n,k}$ be the $(\theta, \tilde{k})$- and $\tilde{k}$-extensions of $C_{n,k}$.

By expressing the expected length of $\tilde{C}_{n,\tilde{k}}$ in terms of the expected length of $C_{n,k}$, we can show that both limits in the lemma statement exist.

Allowing $M$ to be uniformly distributed over the set $\{0, \ldots, \lfloor \frac{n}{k} \rfloor - 1\}$, we have that

$$\hat{H}(x^n) \overset{(a)}{\leq} \mathbf{E} \left[ \ell \left( \tilde{C}_{n,\tilde{k}}(x_{kM}^{kM+\tilde{k}}) \right) \right]$$

$$\overset{(b)}{=} \mathbf{E} \left[ \min_{\theta \in \{0, \ldots, k-1\}} \ell \left( \tilde{C}_{n,\tilde{k},\theta}(x_{kM+\tilde{k}}^{kM+1}) \right) \right]$$

$$\overset{(c)}{=} \mathbf{E} \left[ \ell \left( \tilde{C}_{n,\tilde{k},-M\tilde{k} \mod k}(x_{kM+\tilde{k}}^{kM+1}) \right) \right]$$

$$\overset{(d)}{=} \mathbf{E} \left[ 2k + \sum_{m=0}^{\lfloor \frac{n}{k} \rfloor - 1} \ell \left( C_{n,k}(x_{kM+\tilde{k}}^{kM+1}) \right) \mathbf{1}_{kM+\tilde{k} \geq kM+1} \mathbf{1}_{kM+1 \leq kM+\tilde{k}} \right]$$

$$= 2k + \sum_{m=0}^{\lfloor \frac{n}{k} \rfloor - 1} \mathbf{P} \left( km + 1 \geq \tilde{k}M + 1, km + k \leq \tilde{k}M + \tilde{k} \right) \ell \left( C_{n,k}(x_{kM+1}^{kM+1}) \right)$$

$$\overset{(e)}{=} 2k + \sum_{m=0}^{\lfloor \frac{n}{k} \rfloor - 1} \frac{\tilde{k}}{k} \ell \left( C_{n,k}(x_{kM+1}^{kM+1}) \right)$$

$$\overset{(f)}{=} 2k + \frac{n}{k} \mathbf{E} \left[ \ell(C_{n,k}(x_{kN+1}^{kN+k})) \right]$$

$$\overset{(g)}{=} 2k + \frac{n}{k} \mathbf{E} \left( \hat{H}(x^n) + 1 \right)$$

Step (a) follows by Shannon’s source coding converse. (b) is from the definition of $\tilde{C}_{n,\tilde{k}}$. (c): Observe that by setting $\theta = -M\tilde{k} \mod k$, every encoded subblock within $\tilde{C}_{n,\tilde{k},\theta}$ is aligned so that it will be of the form $C_{n,k}(x_{kM+1}^{kM+k})$ for some integer $m$. Step (d) involves first upper-bounding the length of the unencoded prefix and suffix components of $\tilde{C}_{n,\tilde{k}}(x_{kM+1}^{kM+1})$ at $k$ bits each, and then summing the lengths of each of the encoded subblocks. Note that an encoded subblock $C_{n,k}(x_{kM+1}^{kM+1})$ only appears in $\tilde{C}_{n,\tilde{k},-M\tilde{k} \mod k}(x_{kM+1}^{kM+1})$ if $x_{kM+1}^{kM+k}$ is fully contained within the $\tilde{k}$-block being encoded $x_{kM+1}^{kM+\tilde{k}}$. The indicator functions ensure that only these encoded subblocks contribute to the length summation. (e) follows from recognizing that $M$ takes $\lfloor n/k \rfloor$ values uniformly, and that at most $\tilde{k}/k$ of these positions satisfy the conditions $mk + 1 \geq M\tilde{k} + 1$ and $mk + k \leq M\tilde{k} + \tilde{k}$. (f) replaces the summation with an expectation, where the random variable $N$ is uniformly distributed over the set $\{0, \ldots, \lfloor \frac{n}{k} \rfloor - 1\}$. (g) invokes (f).
Dividing both sides of this resulting inequality by \( \tilde{k} \) and taking the limit supremum with respect to \( n \), we have that
\[
\limsup_{n \to \infty} \frac{1}{k} \hat{H}^k(x^n) \leq \frac{2k}{k} + \frac{1}{k} + \limsup_{n \to \infty} \frac{1}{k} \hat{H}^k(x^n).
\]

Taking the limit supremum of both sides of this expression with \( \tilde{k} \), we have that
\[
\limsup_{\tilde{k} \to \infty} \limsup_{n \to \infty} \frac{1}{k} \hat{H}^k(x^n) \leq \limsup_{n \to \infty} \frac{1}{k} \hat{H}^k(x^n).
\]

Finally, taking the limit infimum with respect to \( k \),
\[
\limsup_{\tilde{k} \to \infty} \limsup_{n \to \infty} \frac{1}{k} \hat{H}^k(x^n) \leq \liminf_{n \to \infty} \limsup_{k \to \infty} \frac{1}{k} \hat{H}^k(x^n).
\]

This proves that \( \lim_{k \to \infty} \limsup_{n \to \infty} \frac{1}{k} \hat{H}^k(x^n) \) exists.

Repeating this last set of arguments with the limit infimum with respect to \( n \) proves that \( \lim_{k \to \infty} \liminf_{n \to \infty} \frac{1}{k} \hat{H}^k(x^n) \) exists.

Next, we prove that the sliding-window compressibility can be no greater than the block-by-block compressibility.

**Lemma 17:** Let \( x^\infty \) be a finite-alphabet sequence. Then the following two statements hold:
\[
\bar{\rho}(x^\infty) \leq \lim_{k \to \infty} \liminf_{n \to \infty} \frac{1}{k} \hat{H}^k(x^n)
\]

and
\[
\bar{\rho}(x^\infty) \leq \lim_{k \to \infty} \limsup_{n \to \infty} \frac{1}{k} \hat{H}^k(x^n).
\]

**Proof:** As the form of this proof is very similar to that of Lemma 16 exposition will be limited.

Let \( \tilde{k} > k \), let \( C_{n,k} \) denote the \( k \)-block Huffman code for the block-by-block empirical distribution \( \bar{\rho}(X^n) \), and let \( \tilde{C}_{n,\tilde{k},\theta} \) and \( \tilde{C}_{n,\tilde{k}} \) be the \((\theta, \tilde{k})\)- and \( \tilde{k} \)-extensions of \( C_{n,k} \).

Allowing \( M \) to be uniformly distributed over the set \( \{0, \ldots, n - \tilde{k}\} \), we have that
\[
\tilde{H}_{sw}^\tilde{k} \leq E \left[ \ell \left( \tilde{C}_{n,\tilde{k},\tilde{k}}(x_{M+\tilde{k}}) \right) \right]
\]

\[
= E \left[ \min_{\theta \in \{0, \ldots, k-1\}} \ell \left( \tilde{C}_{n,\tilde{k},\theta}(x_{M+\tilde{k}}) \right) \right]
\]

\[
\leq E \left[ \ell \left( \tilde{C}_{n,\tilde{k},-M \mod k}(x_{M+\tilde{k}}) \right) \right]
\]

\[
\leq E \left[ 2k + \sum_{m=0}^{[\tilde{k}]-1} \ell \left( C_{n,k}(x_{km+1}) \right) \mathbf{1}_{km+1 \geq M+1} \mathbf{1}_{km+k \leq M+\tilde{k}} \right]
\]

\[
= 2k + \sum_{m=0}^{[\tilde{k}]-1} P \left( km+1 \geq M+1, km+k \leq M+\tilde{k} \right) \ell \left( C_{n,k}(x_{km+1}) \right)
\]

\[
\leq 2k + \sum_{m=0}^{[\tilde{k}]-1} \frac{k}{n-k-1} \ell \left( C_{n,k}(x_{km+1}) \right)
\]

\[
\leq 2k + \frac{n}{k} \frac{\tilde{k}}{n-k-1} \left( \bar{H}^k(x^n) + 1 \right)
\]

Dividing both sides by \( \tilde{k} \) and taking the limit supremum in \( n \), we have that
\[
\limsup_{n \to \infty} \frac{1}{k} \tilde{H}_{sw}^\tilde{k} \leq \frac{2k}{k} + \frac{1}{k} \left( \bar{H}^k(x^n) + 1 \right).
\]

Now taking the limit supremum in \( \tilde{k} \) followed by the limit supremum in \( k \), we have that
\[
\limsup_{\tilde{k} \to \infty} \limsup_{n \to \infty} \frac{1}{k} \tilde{H}_{sw}^\tilde{k} \leq \limsup_{k \to \infty} \limsup_{n \to \infty} \frac{1}{k} \hat{H}^k.
\]
We can identically show (by replacing all limits supremum with limits infimum) that
\[
\liminf_{k \to \infty} \liminf_{n \to \infty} \frac{1}{k} \tilde{H}_w^k \leq \liminf_{k \to \infty} \liminf_{n \to \infty} \frac{1}{k} \hat{H}^k.
\] (21)

Equations (20) and (21) prove the lemma.

We now prove the opposite direction: that the sliding window compressibility can be no smaller than the block-by-block compressibility.

**Lemma 18:** Let \( x^\infty \) be a finite-alphabet sequence. Then
\[
\mu(x^\infty) \geq \lim_{k \to \infty} \liminf_{n \to \infty} \frac{1}{k} \hat{H}^k(x^n)
\]
and
\[
\overline{\mu}(x^\infty) \geq \lim_{k \to \infty} \limsup_{n \to \infty} \frac{1}{k} \hat{H}^k(x^n).
\]

**Proof:** Let \( \tilde{k} > k \) be two blocklengths, and let \( C_{n,k} \) be the optimal \( k \)-block Huffman code for the \( k \)th-order sliding window distribution \( \hat{p}_w^k(X^k)[x^n] \). Then there must exist a phase \( \theta^* \in \{0, \ldots, k-1\} \) such that
\[
E \left[ \ell \left( C_{n,k}(X_{km+1}^{(N+1)k+\theta^*}) \right) \right] \leq \tilde{H}_w^k(x^n) + 1
\] (22)
where \( N \) is distributed uniformly across the set \( \{0, \ldots, \left[ \frac{n-\theta^*}{k} \right] - 1 \} \). This follows from the within-one-bit optimality of \( C_{n,k} \) over the sliding-window distribution, and because the sliding-window distribution may be expressed as a (nonnegative) linear combination of the block-by-block distributions \( \hat{p}_w^k(X^k)[x^n] \) computed according to each phase \( \theta \).

Define \( C_{n,k,\theta} \) and \( C_{n,k} \) as the \((\theta,k)\)- and \( k \)-extensions of \( C_{n,k} \).

A familiar sequence of inequalities may then be applied. Allowing \( M \) to be uniformly distributed over the set \( \{0, \ldots, \left[ n/\tilde{k} \right] - 1 \} \), we have:
\[
\hat{H}^k(x^n) \overset{(a)}{\leq} E \left[ \ell \left( C_{n,k}(x_{km+1}^{(M+1)k+\theta^*}) \right) \right] = E \left[ \min_{\theta \in \{0,\ldots,k-1\}} \ell \left( C_{n,k,\theta}(x_{km+1}^{(M+1)k+\theta^*}) \right) \right] \overset{(b)}{\leq} E \left[ \ell \left( C_{n,\tilde{k},(\theta^* - M) \mod k}(x_{km+1}^{(M+1)k+\theta^*}) \right) \right] \overset{(c)}{\leq} 2k + \sum_{m=0}^{\left[ \frac{n-\theta^*}{k} \right]-1} \ell \left( C_{n,k}(x_{km+1}^{k(m+1)k+\theta^*}) \right) 1_{M\tilde{k}+1 \leq km+\theta^*+1} \overset{(d)}{\leq} 2k + \sum_{m=0}^{\left[ \frac{n-\theta^*}{k} \right]-1} \frac{\tilde{k}}{n-\theta^*-k} \ell \left( C_{n,k}(x_{km+1}^{k(m+1)k+\theta^*}) \right) \overset{(e)}{\leq} 2k + \frac{n-\theta^*}{k} \frac{\tilde{k}}{n-\theta^*-k} E \left[ \ell \left( C_{n,k}(x_{km+1}^{k(N+1)k+\theta^*}) \right) \right] \overset{(f)}{\leq} 2k + \frac{n-\theta^*}{k} \frac{\tilde{k}}{n-\theta^*-k} \left( \tilde{H}_w^k(x^n) + 1 \right)
\]

Step (a) follows from Shannon’s converse and the definition of the \( \tilde{k} \)-block empirical entropy \( \hat{H}^k(x^n) \). (b) sets \( \theta = (\theta^* - M) \mod k \) so that every encoded subblock within \( C_{n,\tilde{k},\theta} \) is of the form \( C_{n,k}(x_{km+1}^{k(m+1)k+\theta^*}) \) for some integer \( m \). (c) upper-bounds the length of an encoding first by bounding the suffix and prefix at \( k \) bits each, and then by summing the encoding lengths for each contributing encoded subblock. Observe that an encoded subblock \( C_{n,k}(x_{km+1}^{k(m+1)k+\theta^*}) \) only appears in \( C_{n,\tilde{k},(\theta^* - M) \mod k}(x_{km+1}^{(M+1)k+\theta^*}) \) if \( x_{km+1}^{k(m+1)k+\theta^*} \) is fully contained within the \( \tilde{k} \)-block being encoded \( x_{km+1}^{(M+1)k+\theta^*} \). (d) follows from recognizing that \( M \) takes \( \{(n-\theta^*)/k\} \) values uniformly, and that at most \( \tilde{k}/k \) of these positions satisfy the conditions \( M\tilde{k} + 1 \leq km + \theta^* + 1 \) and \( M\tilde{k} + \tilde{k} \geq mk + \theta^* + k \). (e) introduces \( N \) as a random variable distributed uniformly over \( \{0, \ldots, \left[ n/\tilde{k} \right] - 1 \} \), and the sum is replaced by an expectation. Finally, (f) is a direct application of (22).
Dividing both sides by \( \bar{k} \) and taking the limit infimum in \( n \), we have that
\[
\liminf_{n \to \infty} \frac{1}{k} \hat{H}^k(x^n) \leq \frac{2k}{\bar{k}} + \frac{1}{k} \left( \hat{H}^k_{sw}(x^n) + 1 \right).
\]

Taking the limit infimum in \( \bar{k} \), followed by the limit infimum in \( k \), we have
\[
\liminf_{\bar{k} \to \infty} \liminf_{n \to \infty} \frac{1}{k} \hat{H}^k(x^n) \leq \liminf_{\bar{k} \to \infty} \liminf_{n \to \infty} \frac{1}{k} \hat{H}^k_{sw}(x^n).
\]

By repeating these two steps with limits supremum instead of limits infimum, we find that
\[
\limsup_{\bar{k} \to \infty} \limsup_{n \to \infty} \frac{1}{k} \hat{H}^k(x^n) \leq \limsup_{\bar{k} \to \infty} \limsup_{n \to \infty} \frac{1}{k} \hat{H}^k_{sw}(x^n).
\]

Lemma 1 now follows from lemmas 16, 17 and 18.

**Appendix B**

**Proof of Lemma 6**

Proof: We begin by defining a function \( n_M(M^\infty) \) that specifies the truncated source \( M^{n_M(M^\infty)} \).

1. If \( M^\infty \notin \mathcal{M}_k(z^\infty) \) then select only the first bit \( n_M(M^\infty) = 1 \).
2. Suppose \( M^\infty \in \mathcal{M}_k(z^\infty) \). Then let \( \{L_i\}, \{n_i\}, \) and \( \hat{p}(M^L|z^k) \) be specified so that (I) is satisfied. Let \( C_{M^\infty} \) be the optimal conditional Huffman code for \( \hat{p}(M^L|z^k) \), and let \( B_{M^\infty} \) be the number of bits required to describe \( C_{M^\infty} \) to a decoder.

We then choose \( i(M^\infty) \in \mathbb{Z}^+ \) sufficiently large so that the following three conditions are satisfied:

\[ C1 \quad \left| \mathbb{E}[L]\hat{p} - \mathbb{E}[L]\hat{p}_{n_i(M^\infty)} \right| < \delta, \] where \( \hat{p}_{n_i} \) is the empirical distribution of \( (M^L, z^k)^{n_i} \). This can be satisfied because \( \hat{p} \) is a limiting empirical distribution on the points \( \{n_i\} \).

\[ C2 \quad \mathbb{E}[[\ell(C(M^L|z^k))]|_{\hat{p}_{n_i(M^\infty)}}] \leq H \hat{p}(M^L|z^k) + 1. \] This is possible since we know that \( \mathbb{E}[[\ell(C(M^L|z^k))]|_{\hat{p}}] \leq H \hat{p}(M^L|z^k) + 1 \), and that \( \hat{p}_{n_i} \to \hat{p} \).

\[ C3 \quad \frac{H \hat{p}(M^L|z^k)}{n_i(M^\infty)} < \delta. \] This is possible simply because \( B_{M^\infty} \) is finite.

Armed with \( i(M^\infty) \) we may define the following:

- \( n(M^\infty) = n_i(M^\infty) \) is the relevant index in the partition sequence \( \{(M^L, z^k)_i\} \).
- \( n_M(M^\infty) = \sum_{j=1}^{n_i(M^\infty)} L_j \) is the relevant index in the source sequence \( M^\infty \).
- \( n_k(M^\infty) = kn_i(M^\infty) \) is the relevant index in the noise sequence \( z^\infty \).

We now describe a variable-length source coding scheme for this constructed source \( M_1^{n_M(M^\infty)} \) with encoder-side-information \( M_1^{n_M(M^\infty)+1} \):

1. If \( M^\infty \notin \mathcal{M}_k \), directly encode \( M_1^{n_M(M^\infty)} \). Recall that since \( n_M((M_k)^C) = 1 \), this is just the first bit \( M_1 \).
2. If \( M^\infty \in \mathcal{M}_k \): First, specify \( C_{M^\infty} \) with the first \( B_{M^\infty} \) bits in the encoding. Then, apply \( C_{M^\infty} \) to each of the \( n(M^\infty) \) blocks in the \( k \)-partition \( (M^L, z^k)^{n(M^\infty)} \).

Call this encoding function \( F(M_1^{n_M(M^\infty)}) \). By Shannon’s source coding converse, the expected length of this encoding must exceed the entropy of the source \( M_1^{n_M(M^\infty)} \). We demonstrate that for this to hold \( \mathcal{M}_k \) must be of measure zero.
0 \leq E \left[ \ell(F(M_{1}^{n,M(M^{\infty})})) \right] - H(M_{1}^{n,M(M^{\infty})})
\implies (a) E \left[ \ell(F(M_{1}^{n,M(M^{\infty})})) \right] - E (n_{M}(M^{\infty}))
\implies (b) P (M^{\infty} \notin M_{k}) + P (M^{\infty} \in M_{k}) E \left[ B_{M^{\infty}} + n(M^{\infty})E \left[ \ell(C_{M^{\infty}}(M^{L}|z^{k})) \right]_{\tilde{P}_{n}(M^{\infty})} \mid M^{\infty} \in M_{k} \right] - P (M^{\infty} \notin M_{k}) - P (M^{\infty} \notin M_{k}) E (n_{M}(M^{\infty}) \mid M^{\infty} \in M_{k}) = P (M^{\infty} \in M_{k}) E \left[ B_{M^{\infty}} + n(M^{\infty})E \left[ \ell(C_{M^{\infty}}(M^{L}|z^{k})) \right]_{\tilde{P}_{n}(M^{\infty})} - n_{M}(M^{\infty}) \mid M^{\infty} \in M_{k} \right]
\implies (c) P (M^{\infty} \in M_{k}) E \left[ n(M^{\infty}) \left( \delta + E \left[ \ell(C_{M^{\infty}}(M^{L}|z^{k})) \right]_{\tilde{P}_{n}(M^{\infty})} \right) - n_{M}(M^{\infty}) \mid M^{\infty} \in M_{k} \right]
\implies (d) P (M^{\infty} \in M_{k}) E \left[ n(M^{\infty}) \left( \delta + E \left[ \ell(C_{M^{\infty}}(M^{L}|z^{k})) \right]_{\tilde{P}_{n}(M^{\infty})} \right) - n(M^{\infty})E[L]_{\tilde{P}_{n}(M^{\infty})} \mid M^{\infty} \in M_{k} \right]
\implies (e) P (M^{\infty} \in M_{k}) E \left[ n(M^{\infty}) \left( \delta + H_{p}(M^{L}|z^{k}) + 1 \right) - n(M^{\infty})E[L]_{\tilde{P}_{n}(M^{\infty})} \mid M^{\infty} \in M_{k} \right]
\implies (f) P (M^{\infty} \in M_{k}) E \left[ n(M^{\infty}) \left( 2\delta + H_{p}(M^{L}|z^{k}) + 1 \right) - n(M^{\infty})E[L]_{\tilde{P}_{n}(M^{\infty})} \mid M^{\infty} \in M_{k} \right]
\implies (g) P (M^{\infty} \in M_{k}) E \left[ n(M^{\infty}) \left( H_{p}(M^{L}|z^{k}) + 1 - E[L]_{\tilde{P}_{n}} \right) \mid M^{\infty} \in M_{k} \right]

Step (a) holds by Lemma [5]. Step (b) follows from an expansion of both expectations. (c) is due to condition C3. The definition of $n_{M}(M^{\infty})$ yields (d). Condition C2 implies (e). (f) follows from condition C1. Because $\delta$ can be arbitrarily small, (g) holds. Finally, by the definition of $M_{k}$ in [4], this last inequality can only be satisfied if $P (M^{\infty} \in M)$ is zero. 

APPENDIX C

PROOF OF LEMMA [13]

First, some notational conveniences are defined. Suppose the given repetition scheme $\overline{\mathcal{T}}$ is applied to an iid Bernoulli$(1/2)$ source $M^{\infty}$ and fixed noise sequence $z^{\infty}$. Let $\{L_{i}\}$ be the number of source bits decoded in each block. Consider the $i$th block — i.e. $\mathcal{F} \left( M_{j}^{\sum_{j=i+1}^{i+L_{i}} L_{i}+N} \mid z_{i}^{N} \right)$. Let $M_{i}^{N} = M_{j}^{\sum_{j=i+1}^{i+L_{i}} L_{i}+N}$ indicate the source bits used by the encoder, and let $M_{i}^{L_{i}} = M_{j}^{\sum_{j=i+1}^{i+L_{i}} L_{i}+1}$ indicate the estimate produced, let $R_{i} = \frac{L_{i}}{N}$ indicate the rate of the block, and let $z_{i}^{N} = z_{i}^{N}$ denote the noise of the block. Finally, let $u_{i}^{N} = u_{i}^{N}$ denote the feedback during the block.

Observe that the $j$th block in a repetition scheme can only affect a future block in one way: by adjusting $L_{j}$ and thereby changing $M_{i}^{N}$ for $i > j$. As such, for all $i > j$, the Markov chain $u_{i}^{N} - M_{i}^{N} - (u_{j}^{N}, M_{j}^{N})$ holds. The joint distribution of $(u_{i}^{N}, u_{j}^{N}, M_{i}^{N}, M_{j}^{N})$ may then be written as

$$p \left( u_{i}^{N}, u_{j}^{N}, M_{i}^{N}, M_{j}^{N} \right) = p(u_{i}^{N}, M_{i}^{N}) p(M_{i}^{N} | u_{i}^{N}, M_{j}^{N}) p(u_{j}^{N} | M_{i}^{N}).$$

Since $E_{i}$ and $E_{j}$ are deterministic functions of $(u_{i}^{N}, M_{i}^{N})$ and $(u_{j}^{N}, M_{j}^{N})$ respectively, we may easily introduce them into the joint distribution:

$$p \left( u_{i}^{N}, u_{j}^{N}, M_{i}^{N}, M_{j}^{N}, E_{i}, E_{j} \right) = p(u_{i}^{N}, M_{i}^{N}) p(e_{i} | u_{i}^{N}, M_{j}^{N}) \cdot p(M_{i}^{N} | u_{i}^{N}, M_{j}^{N}) \cdot p(u_{j}^{N} | M_{i}^{N}) \cdot p(e_{j} | u_{j}^{N}, M_{i}^{N}).$$

This may be rephrased as

$$p \left( u_{i}^{N}, u_{j}^{N}, M_{i}^{N}, M_{j}^{N}, E_{i}, E_{j} \right) = p(u_{i}^{N}, M_{i}^{N}, E_{i}) p(u_{j}^{N}, M_{j}^{N}, E_{j}, E_{i} | M_{i}^{N}) p(u_{i}^{N}, E_{i} | M_{i}^{N}).$$

Summing over $(u_{i}^{N}, u_{j}^{N}, M_{i}^{N})$ this yields

$$p \left( E_{i}, E_{j} | M_{i}^{N} \right) = p \left( E_{j} | M_{i}^{N} \right) p \left( E_{i} | M_{i}^{N} \right) = p \left( E_{j} | M_{i}^{N} \right) p \left( E_{i} | M_{i}^{N} \right),$$

which proves the Markov relation $E_{i} - M_{i}^{N} - E_{i+1}$. The above arguments may be repeated verbatim to show that $T_{i} - M_{i}^{N} - T_{i+1}$.
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