Remarks On Quantum Integration

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Abstract

We give a general integration prescription for finite dimensional braided Hopf algebras, deriving the N-dimensional quantum superplane integral as an example. The transformation properties of the integral on the quantum plane are found. We also discuss integration on quantum group modules that lack a Hopf structure.
1 Introduction

The emergence of Hopf algebras, during the last decade, as a promising framework within which new physical symmetries can be accommodated, has prompted an interest in the theory and techniques of integration on them. Similar remarks hold for braided Hopf algebras which, more recently, have provided a still further extension of the classical concept of a group, marrying quantization with nontrivial statistics.

Integrals on (finite dimensional) Hopf algebras have been studied extensively, see for example [12, 19] and references therein. For the braided case see the treatment in [13, 14] for the basics of the theory - some examples appear in [8, 11]. From the point of view of a physicist who is interested in the basic elements of the theory and in applications, the situation presents certain problems. The results are generally scattered and when they do become available, the disparity of the methods employed in them prohibits the formation of a clear image of the minimum background required to explore the field. When it comes to applications, results are extracted (often ingeniously) from particular properties of individual examples - no general integration prescription seems to be available for the quantum space wanderers. The closest one can come to such a prescription in the literature is perhaps the trace formula of Radford and Larson [11] (and a braided analogue of it in [18]) which, however, occasionally returns trivial (i.e. identically zero) results (there doesn’t seem to exist a description of when exactly it fails either). Our purpose in this paper is thus basically twofold. On the one hand, we aim at providing simple, self-contained proofs of basic results, using only the Hopf algebra axioms we assume the reader to be familiar with, attempting in this way a demonstration of what can be accomplished with a rather minimal set of tools. On the other hand, addressing the problem of the missing integration prescription, we give an explicit formula for the integral on any finite dimensional braided Hopf algebra (FDBHA) and show that it is always nontrivial, commenting along the way on the conditions under which the trace formula fails.

The paper is structured as follows: in section 2 we present the notation we use and collect some basic formulas we need in subsequent proofs. Section 3 starts with background information on integrals on (nonbraided) Hopf algebras. We then give a modified trace formula for the integral and prove its non triviality. We also introduce a “vacuum expectation value” approach to integration, discuss properties of right Fourier transforms and prove a number of useful formulas. Section 4 supplies the braided version of the modified trace formula and the vacuum projectors and discusses, as an example, the integral on the N-dimensional quantum superplane. Also included are some comments on the transformation properties of the integral on the N-dimensional quantum plane. The last section provides an integration prescription (with some modest assumptions) for quantum group modules that lack a braided Hopf structure.

2 Hopf Algebras

The language used in the following is predominantly that of Hopf algebras - we refer the reader to [1, 14, 22] for an introduction to the subject. Concerning the notation, we denote by $\Delta$, $\epsilon$, $S$ the coproduct, counit and antipode respectively and by $\Delta_A$, $\Delta_U$ the right $A$ and left $U$-coactions respectively. Sweedler-like conventions are employed throughout - thus $\Delta a = a_{(1)} \otimes a_{(2)}$, $(\Delta \otimes \text{id}) \circ \Delta(a) = a_{(1)} \otimes a_{(2)} \otimes a_{(3)}$ etc. Also, $\Delta_A(x) = x^{(1)} \otimes x^{(2)}$, $\Delta_U(a) = a^{(1)} \otimes a^{(2)}$ and, for example, $(\text{id} \otimes \Delta) \circ \Delta_A(x) = x^{(1)} \otimes x^{(2)}(1) \otimes x^{(2)}(2) = x^{(1)} \otimes x^{(2)} \otimes x^{(3)}$ and so on. By $A$ we
will generally denote a function type Hopf algebra (its elements will be denoted by \(a, b, \text{ etc.}\) - \(\mathcal{U}\) will stand for its dual Hopf algebra (universal enveloping algebra type) with elements \(x, y\) \text{ etc.} . The duality is via a nondegenerate inner product \(\langle \cdot, \cdot \rangle\) that relates the algebra structure in \(\mathcal{A}\) with the coalgebra structure in \(\mathcal{U}\) and vice-versa. The universal \(R\)-matrix is denoted by \(\mathcal{R} = \mathcal{R}^{(1)} \otimes \mathcal{R}^{(2)}\); \(\mathcal{R}'\) stands for \(\tau(\mathcal{R})\) with \(\tau(a \otimes b) = b \otimes a\). \(\mathcal{R}\) satisfies
\[
\Delta'(x) = \mathcal{R}\Delta(x)\mathcal{R}^{-1} \quad \forall x \in \mathcal{U}
\]
as well as
\[
(\Delta \otimes \text{id})\mathcal{R} = \mathcal{R}^{13}\mathcal{R}^{23}
\]
\[
(\text{id} \otimes \Delta)\mathcal{R} = \mathcal{R}^{13}\mathcal{R}^{12}
\]
(with \(\mathcal{R}^{13} \equiv \mathcal{R}^{(1)} \otimes 1_{\mathcal{U}} \otimes \mathcal{R}^{(2)}\) \text{ etc.})

Given a pair of dual Hopf algebras, one can construct their semidirect product \(\mathcal{A} \rtimes \mathcal{U}\) with \(\mathcal{A}, \mathcal{U}\) trivially embedded in it and cross relations
\[
xa = a_{(1)} \langle x_{(1)}, a_{(2)} \rangle x_{(2)} , \quad ax = x_{(2)} \langle x_{(1)}, S^{-1}(a_{(2)}) \rangle a_{(1)} .
\]
The above commutation relations guarantee that [24]
\[
\mathcal{A} \otimes \mathcal{U} \ni a \otimes x \neq 0 \Rightarrow xa \neq 0
\]
with \(xa \in \mathcal{A} \rtimes \mathcal{U}\). The action \(\triangleright\) of \(\mathcal{U}\) on \(\mathcal{A}\) is given by \(x \triangleright a = a_{(1)} \langle x, a_{(2)} \rangle\). The same symbol will denote the (adjoint) action of \(\mathcal{U}\) on \(\mathcal{U}\): \(x \triangleright y = x_{(1)} y S(x_{(2)}) = y^{(1)} \langle x, y^{(2')} \rangle\). The canonical element in \(\mathcal{U} \otimes \mathcal{A}\) is written like \(C = e_i \otimes f^i\) with \(\{e_i\}, \{f^i\}\) dual (in the sense that \(\langle e_i, f^j \rangle = \delta_i^j\)) linear bases in \(\mathcal{U}, \mathcal{A}\) respectively. It holds
\[
(\Delta \otimes \text{id})C_{12} = C_{13}C_{23}
\]
\[
(\text{id} \otimes \Delta)C_{12} = C_{12}C_{13}
\]
\[
(\epsilon \otimes \text{id})C = 1
\]
\[
(\text{id} \otimes \epsilon)C = 1
\]
\[
(S \otimes \text{id})C = C^{-1}
\]
\[
(\text{id} \otimes S)C = C^{-1},
\]
as well as
\[
\Delta_A(a) \equiv \Delta(a) = C(a \otimes 1)C^{-1}
\]
\[
\Delta_A(x) = C(x \otimes 1)C^{-1}
\]
\[
\triangledown A(a) = C^{-1}(1 \otimes a)C
\]
\[
\triangledown A(x) \equiv \Delta(x) = C^{-1}(1 \otimes x)C.
\]
Either of (4) encodes the information about the inner product \(\langle x, a \rangle\). To make this precise, we introduce \(\mathcal{U}\) and \(\mathcal{A}\)-right vacua, denoted by \(|\Omega_u\rangle\) and \(|\Omega_A\rangle\) respectively, which satisfy [3]
\[
x|\Omega_u\rangle = \epsilon(x)|\Omega_u\rangle
\]
\[
a|\Omega_A\rangle = \epsilon(a)|\Omega_A\rangle.
\]
Left vacua \( \langle \Omega_\mathcal{U}, \Omega_\mathcal{A} \rangle \) are defined analogously. In terms of these, the inner product \( \langle x, a \rangle \) can be given as the “expectation value”

\[
\langle \Omega_\mathcal{A}|xa|\Omega_\mathcal{U} \rangle = \langle \Omega_\mathcal{A}|a(1) (x(1), a(2)) x(2)|\Omega_\mathcal{U} \rangle = \langle x, a \rangle
\]

if we normalize the vacua so that \( \langle \Omega_\mathcal{A}|\Omega_\mathcal{U} \rangle = \langle \Omega_\mathcal{U}|\Omega_\mathcal{A} \rangle = 1 \). Similarly, the adjoint action of \( \mathcal{U} \) on \( \mathcal{A} \) can be written as

\[
xa|\Omega_\mathcal{U} \rangle = x \triangleright a|\Omega_\mathcal{U} \rangle.
\]

3 Integration on Hopf Algebras

3.1 Background

We list here known results about invariant integrals on Hopf algebras that we will use later - more details can be found in [22, 1]. Some of the proofs are also supplied in order to familiarize the reader with the usage of the tools presented in section 2. To prevent potential divergence problems from distracting the formulation of concepts, we deal throughout with finite dimensional Hopf algebras - some of the results though retain their validity in the infinite dimensional case as well.

We start with two dually paired Hopf algebras \( \mathcal{U}, \mathcal{A} \) with (finite) dual bases \( \{e_i\}, \{f^j\} \) respectively. We define a right (invariant) integral in \( \mathcal{A} \) as a map \( \langle \cdot \rangle^R: \mathcal{A} \to k \) with the property

\[
\langle a(1) \rangle^R a(2) = \langle a \rangle^R 1_\mathcal{A}
\]

for all \( a \) in \( \mathcal{A} \). We call \( \langle \cdot \rangle^R \) trivial if all \( \langle f^i \rangle^R \) are zero. Left (invariant) integrals are similarly defined via

\[
a(1) \langle a(2) \rangle^L = 1_\mathcal{A} \langle a \rangle^L.
\]

As we shall soon see, when \( \langle 1_\mathcal{A} \rangle^R \neq 0 \) (or \( \langle 1_\mathcal{A} \rangle^L \neq 0 \)), left and right integrals are proportional and can therefore be normalized so that they coincide. One can now introduce the element \( \delta_\mathcal{U}^R \in \mathcal{U} \) (the right delta function in \( \mathcal{U} \)) which implements the right integral in \( \mathcal{A} \) via

\[
\langle \delta_\mathcal{U}^R, a \rangle = \langle a \rangle^R
\]

(so that \( \epsilon(\delta_\mathcal{U}^R) = \langle 1_\mathcal{A} \rangle^R \)). This allows us to write

\[
\delta_\mathcal{U}^R = \langle f^i \rangle^R e_i
\]

(in the mathematics literature \( \delta_\mathcal{U}^R \) is often called a right integral in \( \mathcal{U} \) - we will not use this terminology here). For arbitrary \( a \) in \( \mathcal{A} \) we have

\[
\langle \delta_\mathcal{U}^R x, a \rangle = \langle \delta_\mathcal{U}^R a(1), x, a(2) \rangle
\]

\[
= \langle a(1) \rangle^R \langle x, a(2) \rangle
\]

\[
= \langle a \rangle^R \langle x, 1_\mathcal{A} \rangle
\]

\[
= \epsilon(x)\langle a \rangle^R
\]

\[
= \langle \delta_\mathcal{U}^R \epsilon(x), a \rangle
\]
therefore
\[ \deltaR x = \deltaL \epsilon(x) \quad \forall x \in U. \quad (14) \]

Taking antipodes in the above equation we find \((\epsilon(x) = \epsilon(S(x)))\)
\[ S(x)S(\deltaR) = \epsilon(S(x))S(\deltaR) \quad (15) \]

which, for invertible \(S\) gives
\[ xS(\deltaR) = \epsilon(x)S(\deltaR) \quad \forall x \in U, \quad (16) \]

in other words, \(S(\deltaR)\) implements a left integral and we can therefore take \(S(\deltaR) = \deltaL\). Since \(\epsilon(S(x)) = \epsilon(x)\), we find that \(\langle 1_A \rangle^R = \langle 1_A \rangle^L \equiv \langle 1_A \rangle\) (\(\langle \cdot \rangle\) denotes a biinvariant integral). Consider now the product \(\deltaR S(\deltaR)\). We have
\[ \deltaR S(\deltaR) = \deltaR \epsilon(S(\deltaR)) = \deltaR \epsilon(\deltaR) = \deltaL(1_A) \]

and also
\[ \deltaR S(\deltaR) = \epsilon(\deltaR)S(\deltaR) = \langle 1_A \rangle S(\deltaR) \]

therefore, in the unimodular case where \(\langle 1_A \rangle \neq 0\) (so that we can normalize \(\langle 1_A \rangle = 1\), it holds
\[ \deltaR = S(\deltaR) \quad (17) \]
\[ x\deltaR = \epsilon(x)\deltaR \quad \forall x \in U \quad (18) \]
\[ \langle a \rangle = \langle S(a) \rangle \quad \forall a \in A. \quad (19) \]

Concerning uniqueness, assume that a second right integral \(\langle \cdot \rangle^{R'}\) exists and let \(\deltaR'\) be the element of \(U\) that implements it. We then get \(\deltaR S(\deltaR') = \langle 1_A \rangle S(\deltaR')\) and \(\deltaR S(\deltaR') = \deltaL(1_A)'\). For \(\langle 1_A \rangle = 1\) we conclude that \(\langle 1_A \rangle' = 1\) implies \(\deltaR = S(\deltaR) = \deltaR'\) while \(\langle 1_A \rangle' = 0\) implies that \(\langle \cdot \rangle'\) is trivial.

Radford and Larson [11] have shown that
\[ \langle a \rangle^{R'} = \left< S^2(e_i), f^a \right> \quad (20) \]

defines a right integral on \(A\) which though, in some cases (as [11] warns), is trivial. It is this shortcoming of (20) that (among other things) motivated our formula for the integral of the next section, which is shown to be nontrivial for any FDHA. One can derive from (20) that \(\langle S^{-2}(e_i), f^a \rangle\), \(\langle S^{-2}(e_i), af^i \rangle\) define left and right (again, in some cases trivial) integrals respectively. For \(\sigma \equiv \langle S^2(e_i), f^i \rangle \neq 0\) and \(\sigma' \equiv \langle S^{-2}(e_i), f^i \rangle\) we conclude
\[ \left< S^{-2}(e_i), f^i a \right> = \left< S^{-2}(e_i), a f^i \right> = \frac{\sigma'}{\sigma} \langle a \rangle^{R'} \quad (21) \]

We summarize the main points: when \(\langle 1_A \rangle = 1\), \(\langle \cdot \rangle\) is biinvariant, unique and [19] holds. [20] defines a (sometimes trivial) right integral and when \(\sigma \neq 0\), [21] holds. Considerably more is known about integrals on Hopf algebras - in the interest of self containment we have only mentioned above what we can prove here.
3.2 A modified trace formula

We want to present now a modified version of the trace formula (20) that overcomes the limitations mentioned above. It is given by

\[
\langle a \rangle^R \delta^R_A = \left\langle e_j S^{-2}(e_i), a f^i \right\rangle f^j
\]  

(22)

(for the remainder of this paper, \(\langle a \rangle^R \delta^R_A\) is defined by the rhs of (22)). Notice that (22) also defines (for some nonzero \(\langle a \rangle^R\) which we can normalize to 1) the right delta function in \(\mathcal{A}\). By pairing both sides of (22) with \(x\) in \(\mathcal{U}\) we conclude

\[
\langle x \rangle^R \langle a \rangle^R = \left\langle x S^{-2}(e_i), a f^i \right\rangle.
\]  

(23)

The proof of invariance is quite analogous to that of (20). What is interesting is the following

**Lemma 1** The integral \(\langle \cdot \rangle^R\) defined by (22) is nontrivial for any FDHA \(\mathcal{A}\).

**Proof:** Set \(\Theta^k_l = \left\langle e_l S^{-2}(e_i), f^k f^i \right\rangle\) and compute

\[
\mathcal{A} \cong \mathcal{U} \ni S^{-2}(e_i) f^i = f^i_{(1)} \left\langle S^{-2}(e_i), S^{-2}(e_i) \right\rangle f^i_{(2)}
\]

\[
= f^i_{(1)} f^i_{(1)} \left\langle S^{-2}(e_i), f^i_{(2)} f^i_{(2)} \right\rangle S^{-2}(e_i)
\]

\[
= S^{-2}(f^i) f^i S^{-2}(e_i) f^i S^{-2}(e_i) S^{-2}(e_i)
\]

\[
= \Theta^i_l S^{-2}(f^i) f^i S^{-2}(e_i) S^{-2}(e_i).
\]  

(24)

We now employ (5) to conclude that not all \(\Theta^i_l\) are zero (since \(S^{-2}(e_i) \otimes f^i \neq 0\) in \(\mathcal{U} \otimes \mathcal{A}\)). Alternatively, one can compute directly the integral (23)

\[
\langle S^{-1}(\delta^R_A) \rangle^R = \left\langle e_i \right\rangle^R \langle S^{-1}(f^i) \rangle^R
\]

\[
= \left\langle e_i e_j, S^{-1}(f^i) S^{-2}(f^j) \right\rangle
\]

\[
= \left\langle e_i, S^{-1}(f^i) S^{-2}(f^i) \right\rangle
\]

\[
= \left\langle e_i, f(f^i) 1_A \right\rangle
\]

\[
= \left\langle 1, a \right\rangle
\]

\[
= 1.
\]  

(25)

which shows nontriviality in both \(\mathcal{U}\) and \(\mathcal{A}\) (of course, \(\left\langle e_i \right\rangle^R \langle S^{-1}(f^i) \rangle^R = 1\) is a stronger statement). \(\square\)

Defining \(\Theta = \Theta^{(1)} \otimes \Theta^{(2)} = \Theta^i_l f^k \otimes e_l\) we get

\[
\langle a \rangle^R \delta^R_A = \left\langle \Theta^{(1)}(a) \right\rangle \langle \Theta^{(2)} \rangle
\]

\[
\langle x \rangle^R \delta^R_u = \left\langle x, \Theta^{(1)} \right\rangle \langle \Theta^{(2)} \rangle.
\]  

(26)

Related to the above proof is

**Lemma 2** For \(\mathcal{A}\) a FDHA, it holds (\(a\) in \(\mathcal{A}\))

\[
\langle af^i \rangle^R = 0 \ \forall i \Rightarrow a = 0
\]  

(27)
Proof: Assuming \( \langle af^i \rangle^R = 0 \) for all \( i \) we get

\[
0 = \langle S^{-1}(e_i) \rangle^R \langle af^i(1) \rangle^R S(f^i(2)) = \langle S^{-1}(e_i) \rangle^R \langle a(1) f^i(1) \rangle^R a(2) f^i(2) S(f^i(3))
\]

\[
= \langle S^{-1}(e_i) \rangle^R \langle a(1) f^i(1) \rangle^R a(2) \]

\[
= \langle S^{-1}(e_i) \rangle^R \langle f^i \rangle^R a
\]

\[
= a
\]

where, in the last line, use was made of (25).

There exist formulas similar to (23) for other combinations of invariance properties

\[
\langle x \rangle^L \langle a \rangle^L \sim \langle e_i x, S^{-2}(f^i) a \rangle
\]

\[
\langle x \rangle^L \langle a \rangle^R \sim \langle x S^2(e_i), f^i a \rangle
\]

\[
\langle x \rangle^R \langle a \rangle^L \sim \langle e_i x, a S^2(f^i) \rangle.
\]

(28)

We could have used any of these formulas as our basic definition of the integral. When we deal with braided Hopf algebras we use in fact the analogue of the second of (28) as our starting point. The coefficient of proportionality in the above formulas depends on which function's integral we normalize to 1. The relation with the trace formula (20) is illuminated by the following

Lemma 3 For \( A, U \) dually paired FDHAs, it holds (\( a \) in \( A, x \) in \( U \))

\[
\langle x \rangle^R \langle a \rangle^R = \sigma \langle x e_i, S^2(f^i) a \rangle.
\]

(29)

Proof:

\[
\langle x \rangle^R \langle a \rangle^R = \langle e_i x, S^2(f^i) \rangle \langle e_k, S^2(f^k) a \rangle
\]

\[
= \langle e_i x(1), S^2(f^i) \rangle \langle e_k(2), S^2(f^k) a \rangle
\]

\[
= \langle e_i, S^2(f^i(1)) \rangle \langle x(1), S^2(f^i(2)) \rangle \langle x(2) e_k, S^2(f^k) a \rangle
\]

\[
= \langle e_i, S^2(f^i(1)) \rangle \langle x(1) e_k(2) S^{-1}(e_k(1)), S^2(f^i(2)) \rangle \langle x(2) e_k(3), S^2(f^k) a \rangle
\]

\[
= \langle e_i, S^2(f^i(1)) \rangle \langle S^{-1}(e_k(1)), S^2(f^i(3)) \rangle \langle x e_k(2), S^2(f^j) S^2(f^k) a \rangle
\]

\[
= \langle e_i e_j e_i, S^2(f^i) \rangle \langle e_k(1), S(f^i) \rangle \langle x e_k(2), S^2(f^j) S^2(f^k) a \rangle
\]

\[
= \langle e_i e_j e_i S(e_k(1)), S^2(f^i) \rangle \langle x e_k(2), S^2(f^j) S^2(f^k) a \rangle
\]

\[
= \langle e_i e_j S(e_k(1)), S^2(f^i) \rangle \langle x e_k(2), S^2(f^j) S^2(f^k) a \rangle
\]

\[
= \langle e_i, S^2(f^i) \rangle \langle x e_j, S^2(f^j) a \rangle.
\]

As a corollary, we infer that, when \( \sigma = 0 \), \( \langle \cdot \rangle^R \) is trivial in \( U \) or \( A \) (or both); when \( \sigma \neq 0 \), it is nontrivial in both \( U \) and \( A \).
3.3 Vacuum Projectors

We give here a formulation of invariant integration in which the integral of a function is regarded as its “vacuum expectation value”. First, notice that right invariance can also be expressed as (in U, a in A)

$$\langle x \triangleright a \rangle = \epsilon(x) \langle a \rangle.$$  \hspace{1cm} (30)

Recall now the U and A-vacua introduced in section 3. We could define, in terms of these, our “vacuum” integral via an equation like (a ∈ A)

$$\langle a \rangle_v \sim \langle \Omega_U | a | \Omega_U \rangle ;$$  \hspace{1cm} (31)

invariance in the form (30) is automatically satisfied. However, as we shall soon see, it is more natural, in this case, to work instead with quantities like

$$| \Omega_A \rangle \langle \Omega_U | a | \Omega_U \rangle, | \Omega_A \rangle \langle \Omega_U | \Omega_U \rangle$$

etc., i.e. with operators rather than states. The reason is that the former can be realized in A×U and hence their properties can be derived while those of the latter have to be introduced “by hand”. We aim therefore at a definition like

$$\langle a \rangle_v \sim | \Omega_A \rangle \langle \Omega_U | a | \Omega_U \rangle \langle \Omega_A |.$$  \hspace{1cm} (32)

We expect the rhs of (32) to be proportional to δA (at least, under certain conditions), consistent with its property to return counit when multiplied by functions either from the left or from the right. What we need next is to find quantities in A×U that represent the operators

$$| \Omega_A \rangle \langle \Omega_U |, | \Omega_A \rangle \langle \Omega_U | \Omega_U \rangle$$

etc., i.e. with operators rather than states. We recall at this point a result of [2]: the vacuum projectors E, ¯E defined by

$$E = S^{-1}(f^i)e_i, \quad \bar{E} = S^2(e_i)f^i$$  \hspace{1cm} (33)

satisfy

$$Ea = S^{-1}(f^i)e_j a$$
$$= S^{-1}(f^i)a_{(1)} \langle e_{i(1)}, a_{(2)} \rangle e_{i(2)}$$
$$= S^{-1}(f^j)S^{-1}(f^i)a_{(1)} \langle e_i, a_{(2)} \rangle e_j$$
$$= S^{-1}(f^j)S^{-1}(a_{(2)})a_{(1)}e_j$$
$$= \epsilon(a)E$$  \hspace{1cm} (34)

for all a in A, as well as

$$xE = xS^{-1}(f^i)e_i$$
$$= S^{-1}(f^j)S^{-1}(f^i) \langle x_{(1)}, S^{-1}(f^i) \rangle x_{(2)}e_i$$
$$= S^{-1}(f^j) \langle x_{(1)}, S^{-1}(f^i) \rangle x_{(2)}e_i e_j$$
$$= S^{-1}(f^j)x_{(2)}S^{-1}(x_{(1)})e_j$$
$$= \epsilon(x)E$$  \hspace{1cm} (35)

for all x in U, while we can similarly show that

$$\bar{E}x = \epsilon(x)\bar{E} \quad \forall x \in U$$  \hspace{1cm} (36)
$$a\bar{E} = \epsilon(a)\bar{E} \quad \forall a \in A.$$  \hspace{1cm} (37)
Furthermore, \( E^2 = E \) and \( \bar{E}^2 = \bar{E} \) which allows us to write \( E = |\Omega_\delta\rangle\langle\Omega_\delta|, \bar{E} = |\Omega_\Delta\rangle\langle\Omega_\Delta| \). With an eye on (32), we now compute
\[
\bar{E}aE = S^2(e_i)f^i aE \\
= f^i(a_1) \left< S^2(e_i), f^i(a_2) \right> E \\
= f^n \left< e_n, f^i(a_1) \right> \left< S^2(e_i), f^i(a_2) \right> E \\
= f^n \left< e_n S^2(e_i), f^i a \right> E \\
= \langle a \rangle^R \delta_A E. \tag{38}
\]
This simplifies further when \( \delta_A^L = \delta_A^R \equiv \delta_A \) - we then get
\[
EaE = \langle a \rangle \delta_A. \tag{39}
\]

### 3.4 Fourier Transforms

We work again with a general (i.e. not necessarily unimodular) FDHA. We define a right Fourier transform \( \hat{\gamma}^R : \mathcal{A} \to \mathcal{U} \) in terms of a right integral as follows
\[
\hat{a}^R \equiv \left< a S^{-1}(f^i) \right>^R e_i, \tag{40}
\]
so that \((b \text{ in } \mathcal{A})\)
\[
\left< \hat{a}^R, b \right> = \left< a S^{-1}(b) \right>^R. \tag{41}
\]
We show now that the right Fourier transform is invertible
\[
\left< e_j \hat{a}^R \right>^R f^j = \left< a S^{-1}(f^i) \right>^R (e_j e_i)^R f^j \\
= \left< a S^{-1}(f^i) \right>^R (e_i)^R f^i(a_1) \\
= \left< a(1) S^{-1}(f^i) \right>^R (e_i)^R f^i(a_2) S^{-1}(f^i) f^i(1) \\
= \langle a(1) S^{-1}(f^i) \rangle^R (e_i)^R a(2) \\
= \langle a(1) S^{-1}(\delta^R_A) \rangle^R a(2) \\
= \langle S^{-1}(\delta^R_A)^R \rangle^R a \\
= a. \tag{42}
\]
In the language of the previous section, when \( \sigma' \neq 0 \), the Fourier transform allows the switching between \( |\Omega_\delta\rangle \) and \( |\Omega_\Delta\rangle \). Indeed, we find
\[
aE = a S^{-1}(f^i) e_i \\
= e_i(a_2) \left< S^{-1}(a_2 S^{-1}(f^i)) \right> a(1) S^{-1}(f^i) \\
= e_i(a_2) \left< S^{-1}(e_i), f^i(a_2) \right> a(1) S^{-1}(f^i) \\
= e_j \left< S^{-2}(e_i) f^j(1) a(2) \right> a(1) S^{-1}(f^j) S^{-1}(f^i) \\
= e_j \left< S^{-2}(e_i) S^{-2}(e_k) f^j(1) S(a_2) \right> a(1) S^{-1}(f^j) S^{-1}(f^i) f^k \\
= e_j \left< S^{-2}(e_k) (f^j(1) S(a_2)) a(1) S^{-1}(f^j) S^{-1}(f^i) f^k \right> \\
= e_j \left< a(2) S^{-1}(f^j(1)) a(1) S^{-1}(f^j) S^{-3}(e_k) f^k \right> \\
= e_j \left< a S^{-1}(f^j) \right> \langle e_k f^k \rangle \hat{a} \delta_A, \tag{43}
\]
which, in terms of the action on right vacua, corresponds to
\[ a|\Omega_U\rangle = \hat{a}|\Omega_A\rangle. \] (44)

One can easily check that (\(a \in \mathcal{A}\), \(x \in \mathcal{U}\))
\[ x \triangleright a_R = x\hat{a}_R. \] (45)

Another familiar, in the unimodular case, property that survives when \(\langle 1_A \rangle = 0\), is
\[ f \star_R g_R = \hat{f}_R\hat{g}_R, \] (46)

where the right convolution \(\star_R\) of \(f, g\) in \(\mathcal{A}\) is given by
\[ f \star_R g = g_R(1)(fS^{-1}(g(2)))_R \]
(47)

(46), together with the invertibility of \(\hat{\cdot}_R\), guarantee the associativity of \(\star_R\). On the other hand, the following property that is easily seen to hold in the unimodular case,
\[ \hat{a} = S(a) \] (48)
does not hold, in general, for \(\hat{\cdot}_R\) when \(\langle 1_A \rangle = 0\).

### 3.5 Further properties

We give now the proof of a number of interesting formulas, valid for unimodular FDHAs. First, notice that
\[ S^{-2}(a) = e_i\langle S^2(a)S^{-1}(f^i) \rangle \]
\[ = e_i\langle aS^{-3}(f^i) \rangle \]
\[ = S^{-2}(e_i)\langle aS^{-1}(f^i) \rangle \]
\[ = S^{-2}(\hat{a}) \] (49)

where, in the second line, we used (14). Two useful lemmas follow

**Lemma 4** For \(\mathcal{A}\) a FDHA and \(\sigma' \neq 0\), it holds
\[ S^{-2}(a) = \langle a^{(1)}, S^{-2}(a^{(2)}(2)) \rangle a^{(2)}(1) \] (50)

for all \(a \in \mathcal{A}\).

**Proof:** We have (the notation is introduced in section 2)
\[ a^{(1)} \otimes a^{(2)}(1) \otimes a^{(2)}(2) = (\text{id} \otimes \Delta)(S(e_i)e_j \otimes f^i a f^j) = S(e_k)S(e_i)e_j e_l \otimes f^i a^{(1)}(1) f^j \otimes f^k a^{(2)}(2) f^l \]
which gives

\[
\langle a^{(1)}, S^{-2}(a^{(2)}_{(2)}) \rangle a^{(2)}_{(1)} = \langle S(e_k)S(e_i)e_j e_i, S^{-2}(f^k)S^{-2}(a_{(2)})S^{-2}(f^j) \rangle f^ia_{(1)}f^j
\]
\[
= \langle S(e_k)S(e_i)e_j \rangle \langle S^{-2}(f^k)S^{-2}(a_{(2)}) \rangle f^ia_{(1)}f^j
\]
\[
= \langle S(e_i)e_j \rangle \langle S^{-2}(f^i_{(2)})S^{-2}(a_{(2)}) \rangle f^i_{(1)}a_{(1)}f^j
\]
\[
= \langle S(e_i)e_j \rangle \langle f^i a f^j \rangle
\]
\[
= \langle S(e_i)e_j \rangle \langle S^{-1}(a)S^{-1}(f^i) \rangle f^j
\]
\[
= \langle S(S^{-1}(a))e_j \rangle f^j
\]
\[
= \langle e_j S^2(S^{-1}(a)) \rangle S(f^j)
\]
\[
= \langle e_j S^3(a) \rangle S(f^j)
\]
\[
= S^{-2}(a) ,
\]
(51)

where, in the last line, we used the formula for the inverse Fourier transform, eqn [12].

\[\square\]

**Lemma 5** For \(A\) a FDHA, it holds

\[a^{(2)} S^{-1}(a^{(1)}) b = b a^{(2)} S^{-1}(a^{(1)})\]

(52)

for all \(a, b\) in \(A\).

**Proof:** We have

\[a^{(2)} S^{-1}(a^{(1)}) b = a^{(2)} b_{(1)} \left( S^{-1}(a^{(1)}_{(2)}), b_{(2)} \right) S^{-1}(a^{(1)}_{(1)}) \]
\[= b_{(1)} \left( a^{(2)} b_{(1)} \left( S^{-1}(a^{(1)}_{(2)}), b_{(2)} \right) a^{(2)(2)} \left( S^{-1}(a^{(1)}_{(2)}), b_{(3)} \right) \right) S^{-1}(a^{(1)}_{(1)}) \]
\[= b_{(1)} \left( a^{(2)} b_{(1)} \left( S^{-1}(a^{(1)}_{(2)}), b_{(2)} \right) a^{(2)(2)} S^{-1}(a^{(1)}_{(1)}) \right) \]
\[= b_{(1)} \left( a^{(1)}_{(3)} S^{-1}(a^{(1)}_{(2)}), b_{(2)} \right) a^{(2)} S^{-1}(a^{(1)}_{(1)}) \]
\[= b a^{(2)} S^{-1}(a^{(1)}) ,\]
(53)

where, in the first and second line, we used the first and second of (4) respectively.

At this point, we have enough machinery at our disposal to prove the following

**Proposition 1** For \(A\) a FDHA and \(a' \neq 0\), it holds

\[\langle ba \rangle = \langle S^{-2}(a)b \rangle\]

(54)

for all \(a, b\) in \(A\).

**Proof:** We have

\[E b a E = \tilde{E} b a^{(2)} \epsilon(S^{-1}(a^{(1)})) E \]
\[= \tilde{E} b a^{(2)} S^{-1}(a^{(1)}) E \]
\[= \tilde{E} a^{(2)} S^{-1}(a^{(1)}) b E \]
\[= \tilde{E} S^{-1}(a^{(1)}_{(1)}) \left( S^{-1}(a^{(1)}_{(2)}), S^{-1}(a^{(2)}_{(2)}) \right) a^{(2)}_{(1)} b E \]
\[= \tilde{E} \left( S^{-1}(a^{(1)}), S^{-1}(a^{(2)}_{(2)}) \right) a^{(2)}_{(1)} b E \]
\[= \tilde{E} S^{-2}(a) b E \]
where in the third line we used (52) and in the last one, (51). The proposition follows now from (39).

It is interesting to compare (54) with the formula one can derive in the presence of a universal \( R \)-matrix \( R \) in \( U \). The result in this case is contained in

Proposition 2 Let \( A \) be a dual quasitriangular Hopf algebra and \( \langle \cdot \rangle \) a biinvariant integral on it. It holds

\[
\langle ba \rangle = \langle S^2(a \triangleright s)b \rangle. \tag{55}
\]

for all \( a, b \) in \( A \), where

\[
s = cu^{-2}, \quad u = S(R^{(2)})R^{(1)}, \quad c = uS(u) \tag{56}
\]

(\( s, u, c \) in \( U \sim A^* \)) and \( a \triangleleft s \equiv \langle s(1), a \rangle s(2) \).

Proof: The commutation relations in \( A \) can be written in the form

\[
ba = \langle R, a(1) \otimes b(1) \rangle a(2)b(2) \langle R^{-1}, a(3) \otimes b(3) \rangle \tag{57}
\]

(this is the dual version of (1)). It can also be shown that the element \( u \) defined above implements the square of the antipode in \( U \) according to

\[
S^2(x) = u_xu^{-1} \tag{58}
\]

for all \( x \) in \( U \). - its inverse is given by \( u^{-1} = R^{(2)}S^2(R^{(1)}) \). We can then write

\[
\langle ba \rangle = \langle R, a(1) \otimes b(1) \rangle \langle a(2)b(2) \rangle \langle R^{-1}, a(3) \otimes b(3) \rangle \\
= \langle R, a(1) \otimes b(1)S(b(2))S(a(2)) \rangle \langle a(3)b(3) \rangle \langle R^{-1}, a(5) \otimes b(5)S^{-1}(b(4))S^{-1}(a(4)) \rangle \\
= \langle R, a(1) \otimes S(a(2)) \rangle \langle a(3)b \rangle \langle R^{-1}, a(5) \otimes S^{-1}(a(4)) \rangle \\
= \langle S(u), a(1) \rangle \langle a(2)b \rangle \langle u^{-1}, a(3) \rangle. \tag{59}
\]

However,

\[
S(u)xu^{-1} = S(u)u^{-1}uxu^{-1} \\
= sS^2(x).
\]

Then, for arbitrary \( x \) in \( U \), we have

\[
\langle S(u), a(1) \rangle \langle x, a(2) \rangle \langle u^{-1}, a(3) \rangle = \langle S(u)xu^{-1}, a \rangle \\
= \langle sS^2(x), a \rangle \\
= \langle x, S^2(a \triangleleft s) \rangle
\]

therefore

\[
\langle S(u), a(1) \rangle a(2) \langle u^{-1}, a(3) \rangle = S^2(a \triangleleft s); \tag{60}
\]

substituting in (59) we get (54).

Comparison with (54) and use of (27) leads to the relation \( S^4(a) = a \triangleleft s^{-1} \) which in the dual implies \( S^4(x) = s^{-1}x \) and therefore (by taking \( x = 1_U \))

\[
S^4(x) = x \tag{61}
\]
for all \( x \) in \( U \) (a different proof of this has been given in [20]). Equations (54) and (61) have been proven above only in the finite dimensional case (the latter assuming quasitriangularity as well). On the other hand, (55) and the following versions of it which are proved similarly, hold for all quasitriangular Hopf algebras with biinvariant integral

\[
\langle ba \rangle = \langle aS^2(s^{-1} \triangleright b) \rangle = \langle S^{-2}(s \triangleright a)b \rangle = \langle (u^{-1} \triangleright b)(a \triangleleft u) \rangle.
\] (62)

We close this section with the remark that \( \langle ba \rangle = \langle S^2(a)b \rangle \) has been shown to hold for unimodular, finite dimensional ribbon Hopf algebras (see [19]). Using (61) in (54) we conclude that it actually holds for (the wider class of) quasitriangular FDHAs.

4 Integration On Braided Hopf Algebras

We transcribe here the main results of section 3 to the case of FDBHAs, using the \( N \)-dimensional quantum superplane as a concrete example.

4.1 Preliminaries

4.1.1 The quantum superplane

Let us review briefly the basics of the construction of the quantum superplane [25, 27]. As is typical in the study of quantum spaces, one deals with the associative, noncommutative algebra \( X \) generated by \( 1_X \) and the coordinate functions \( \xi_i, i = 1, \ldots, N \) on the quantum superplane satisfying the commutation relations

\[
\xi_2 \xi_1 = -q \hat{R}_{12} \xi_2 \xi_1
\] (we work with the “\( q^{-1} \)” version [11] - we remind the reader that \( \hat{R}_{12}(q^{-1}) = \hat{R}_{21}^{-1}(q) \)). The derivatives \( \sigma_i, i = 1, \ldots, N \), dual to the above coordinates, generate (together with \( 1_D \)) the algebra \( D \) with commutation relations

\[
\sigma_1 \sigma_2 = -q \sigma_1 \sigma_2 \hat{R}_{12}.
\] (64)

The coordinate-derivative duality is encoded in the cross relations

\[
\sigma_i \xi_j = \delta_{ij} - q \hat{R}^{-1}_{mi} \xi_m \sigma_i.
\] (65)

We denote the combined coordinate - derivative algebra by \( \mathcal{P} \). In analogy with the treatment of the quantum plane in [3], one can enlarge \( \mathcal{P} \) by the introduction of displacements \( \eta_i, \tau_i, i = 1, \ldots, N \) for the coordinates and derivatives respectively, satisfying

\[
\eta_2 \eta_1 = -q \hat{R}_{12} \eta_2 \eta_1, \quad \tau_1 \tau_2 = -q \tau_1 \tau_2 \hat{R}_{12}, \quad \tau_i \eta_j = \delta_{ij} - q \hat{R}^{-1}_{mj} \eta_m \tau_i,
\] (66)

\[
\xi_2 \eta_1 = -q \hat{R}^{-1}_{12} \eta_2 \xi_1, \quad \sigma_i \eta_j = -q^{-1} \hat{R}_{kj} \eta_i \sigma_k,
\] (67)

\[
\xi_i \tau_j = -q^{-1} D_{ia} \hat{R}_{ia} \tau_k D_{bj}^{-1} \tau_i \xi_k, \quad \sigma_1 \tau_2 = -q \sigma_1 \tau_2 \hat{R}_{12}^{-1}.
\] (68)
As seen from above, the $\eta$’s are taken to be just a second copy of the $\xi$’s but are endowed with nontrivial statistics with both the $\xi$’s and the $\sigma$’s - analogous remarks hold for the $\tau$’s. The remarkable property of (68) is that the displaced coordinates $\xi_i + \eta_i$ and derivatives $\sigma_i + \tau_i$ still satisfy (63) and (64) respectively while the entire enlarged algebra is covariant under the $GL_q(N)$-coaction

\begin{align*}
\xi_i &\mapsto \xi_i' = \xi_j \otimes S(A_{ij}) \quad (69) \\
\eta_i &\mapsto \eta_i' = \eta_j \otimes S(A_{ij}) \quad (70) \\
\sigma_i &\mapsto \sigma_i' = \sigma_j \otimes S^2(A_{ji}) \quad (71) \\
\tau_i &\mapsto \tau_i' = \tau_j \otimes S^2(A_{ji}). \quad (72)
\end{align*}

We will often drop the tensor product sign in the following.

### 4.1.2 Braiding

Suppose $\mathcal{U}$ is a quasitriangular Hopf algebra (with universal $R$-matrix $\mathcal{R}$) that acts from the left on two algebras $V, W$. One can, in this case, form the braided tensor product $W \otimes V$ in which $V, W$ are trivially embedded as subalgebras but have nontrivial statistics, given by ($v$ in $V$, $w$ in $W$)

\[(1 \otimes v)(w \otimes 1) \equiv \Psi(v \otimes w) = \tau \circ (\mathcal{R}^{(1)} \triangleright v \otimes \mathcal{R}^{(2)} \triangleright w) = w^{(1)} \otimes v^{(2)} \langle \mathcal{R}, v^{(2')} \otimes w^{(2')} \rangle. \quad (73)\]

We have expressed above the action of $\mathcal{U}$ on $V, W$ in terms of the dual coaction of $\mathcal{A} \sim \mathcal{U}^*$. The first line of (73) also defines the braided transposition $\Psi : V \otimes W \to W \otimes V$ for which it holds in general $\Psi^2 \neq \text{id}$ (due to $\mathcal{R}' \mathcal{R} \neq 1$). For a detailed discussion of the properties of $\Psi$ see e.g. [17].

### 4.1.3 The quantum superplane as a braided Hopf algebra

The concept of braided tensor products provides a natural framework for an elegant description of the quantum superplane as a braided Hopf algebra. We give here, for completeness, an outline of this approach - more details can be found in [17]. Essential to this description is the use of diagrams which encode neatly the braiding information. The maps $\Psi$ and $\Psi^{-1}$ are represented by the diagrams $\otimes$ and $\otimes$ respectively. For the algebra $\mathcal{X}$, the map $\xi_i \mapsto \xi_i \otimes 1 + 1 \otimes \xi_i \equiv \eta_i + \xi_i$ is regarded as a braided coproduct $\Delta : \mathcal{X} \to \mathcal{X} \otimes \mathcal{X}$ (extended (braided) multiplicatively on the whole $\mathcal{X}$). Diagramatically this appears as

\[
\text{\begin{align*}
\xi &\rightarrow \xi_i \otimes 1 + 1 \otimes \xi_i \\
\eta &\rightarrow \eta_i + \xi_i
\end{align*}}
\]

where the first two vertices denote the product and coproduct in $\mathcal{X}$ and the third diagram expresses the braided multiplicativity of $\Delta$ ($\xi, \eta$ etc. denote generic elements of $\mathcal{X}$). One also has a matching counit and antipode with $\epsilon, S, S^2, S^{-1}, S^{-2}$ denoted respectively by
and satisfying braided versions of the familiar Hopf algebra identities, e.g.

\[
\begin{align*}
\Delta(\sigma_i) &= \sigma_i \otimes 1 + 1 \otimes \sigma_i \\
\tau &\equiv \sigma_i \\
\end{align*}
\]

(74)

A particularly important requirement on the braiding, which \(\Psi\) of (73) satisfies, is that one should be able to move crossings past all vertices and boxes, e.g.

\[
\begin{align*}
\sigma &\equiv \sigma_i \\
\end{align*}
\]

(75)

should hold. Exactly analogous treatment is possible for \(\mathcal{D}\), the algebra of derivatives. The braided coproduct is given by \(\Delta(\sigma_i) = \sigma_i \otimes 1 + 1 \otimes \sigma_i \equiv \tau_i + \sigma_i\) and the corresponding diagrams are an exact copy of those for \(\mathcal{X}\) (we will use in them the letters \(\sigma, \tau\) etc. to denote generic elements of \(\mathcal{D}\)). One can now combine \(\mathcal{X}\) and \(\mathcal{D}\) to form a braided semidirect product \(\mathcal{X} \bowtie \mathcal{D}\). We need for this a braided action of \(\mathcal{D}\) on \(\mathcal{X}\) which is given by the second of the following diagrams

\[
\langle \sigma, \xi \rangle \sim \sigma \xi \\
\]

(76)

while the first one simply depicts the pairing between a derivative and a function (defined as the counit of the derivative of the function). When viewed upside - down, the first diagram stands for the canonical element \(\phi^i \otimes \epsilon_i \in \mathcal{X} \otimes \mathcal{D}\) (notice the reversal of order in the tensor product) with \(\langle \epsilon_i, \phi^j \rangle = \delta^j_i\). Both the inner product and the canonical element are assumed invariant under \(\Delta_A:\)

\[
\begin{align*}
\langle p^{(1)}, x^{(1)} \rangle p^{(2)} x^{(2)} &= \langle p, x \rangle 1_A \\
\phi^i \otimes \epsilon_i^{(1)} \otimes \phi^j \otimes \epsilon_j^{(2)} &= \phi^i \otimes \epsilon_i \otimes 1_A.
\end{align*}
\]

(77) (78)

The product - coproduct duality between \(\mathcal{X}\) and \(\mathcal{D}\) is taken to be

\[
\sigma \xi \eta \equiv \sigma \xi \eta \\
\]

(79)

Notice that this differs from the standard convention in the unbraided case. As a result, to get the unbraided version of any diagrammatic equation that appears in the following, one should translate the diagrams, ignoring the braiding information, into the language of section 2 and then set \(\Delta \to \Delta', S \to S^{-1}\). Again, viewing the diagrams upside - down reveals additional
We close this review with a technical remark. If one computes the $\xi - \xi$ braiding given by (73) (with $V = W = \mathcal{X}$), using the coaction (69), one fails to reproduce the $\xi - \eta$ commutation relations of (67) - the result is off by a $q$ factor (similarly for the rest of (67), (68)). To remedy this, one can enlarge $\mathcal{A}$ by a grouplike central element $g$ (the dilaton, see [16]), the inner product of which with $\mathcal{R}$ is given by

$$
\langle \mathcal{R}, g^a \otimes g^b \rangle = (-q)^{-ab}, \quad \langle \mathcal{R}, g^a \otimes A_{ij} \rangle = \langle \mathcal{R}, A_{ij} \otimes g^a \rangle = \delta_{ij}.
$$

We will call the enlarged algebra $\tilde{\mathcal{A}}$. Setting $A \to gA$ in the rhs of (69)-(72) gives an $\tilde{\mathcal{A}}$-coaction on the quantum superplane which reproduces, via (73), the commutation relations (67), (68).

### 4.2 The invariant integral

#### 4.2.1 First definition and problems

The integral we are looking for is a linear map $\langle \cdot \rangle : \mathcal{X} \to \mathbb{C}$ which is translationally invariant in the following sense [25]

$$
\langle \sigma_i f(\xi) \rangle = 0, \quad i = 1, \ldots, N \quad \forall f \in \mathcal{X}.
$$

An equivalent formulation of invariance is [3]

$$
\langle f(\xi + \eta) \rangle = 1_{\mathcal{X}} \langle f(\xi) \rangle \quad \forall f \in \mathcal{X}
$$

or, in braided Hopf algebra language,

$$
f_{(1)} \langle f_{(2)} \rangle = 1_{\mathcal{X}} \langle f \rangle \quad \forall f \in \mathcal{X}.
$$

Representing the integral with a rhombus, we want it to satisfy

$$
\langle \xi \eta \rangle = \langle \eta \xi \rangle
$$

(85)
a requirement which, as one can easily see, cannot, in general, be satisfied. Indeed, we only need consider the classical fermionic line with coordinate $\xi$ and displacement $\eta$ satisfying $\xi^2 = \eta^2 = 0$, $\xi \eta = -\eta \xi$. Taking $\xi$, $\eta$ to stand for themselves in the diagram above, we find that the lhs is $\eta \langle \xi \rangle$ (since $\langle \xi \rangle$, being a number, braids trivially), while the rhs is $\eta \langle -\xi \rangle = -\eta \langle \xi \rangle$, implying $\langle \xi \rangle = 0$ which contradicts the known Berezin result. We conclude that $\langle f(\xi) \rangle$, assumed invariant (and nontrivial), cannot both be a number and satisfy the property expressed in the diagram above.

4.2.2 An improved definition

Our treatment, in section 3.2, of the integral on FDHAs points to a simple solution to the above problem. We recall that there, the quantity that naturally emerged, in our algebraic formulation in terms of the modified trace formula, was the numerical integral $\langle \cdot \rangle$ times a delta function (as in the lhs of (22)). Motivated by this, we define a new integral $\langle \langle \cdot \rangle \rangle^L : \mathcal{X} \to k\delta^k_X$ (with $k$, in our case, the complex numbers) as follows

$$\langle \langle \xi \rangle \rangle^L = \langle \xi \rangle^L \delta^k_X. \quad (86)$$

The output braid of the integration rhombus in our diagrams will stand accordingly for a numerical multiple of $\delta^k_X$. The rhombus’ inner workings are exposed in the diagram below

To get the product $\langle \sigma \rangle^R \langle \xi \rangle^L$ one should pair the output braid with $\sigma$. Whether (87), in its present or a suitably modified form, applies to the infinite dimensional case (and under what conditions), is a direction for future work (one can easily see that, in certain such cases, the rhs of (87) diverges).

Lemma 6  The integral $\langle \langle \cdot \rangle \rangle^L$ defined by (87) is nontrivial for every FDBHA.

Proof: Using $(S^{-1} \otimes \text{id}) \circ \Psi^{-1}(\phi^i \otimes \epsilon_i)$ as input to the braided version of $\Theta$ (shown below), we find

from which nontriviality follows. \qed
4.2.3 Braided vacuum projectors

We denote in the following by $\mathcal{E}$, $\mathcal{E}$ the braided analogues of $E$, $\bar{E}$. They are given by

$$\mathcal{E} = \begin{array}{c} \includegraphics[width=0.1\textwidth]{braided_E.pdf} \end{array}, \quad \mathcal{E} = \begin{array}{c} \includegraphics[width=0.1\textwidth]{braided_bar_E.pdf} \end{array}$$

(88)

The proof of the (analogue of) (34) is as follows

As before, $\mathcal{E}aE$ is a multiple of $\delta^R_XE$ - when $\delta^R_X = \delta^L_X \equiv \delta_X$, it becomes a multiple of $\delta_X$. Notice that, with $\delta^R_X$ defined via $\langle \tau, \delta^R_X \rangle = \langle \tau \rangle^R$, one gets $\xi \delta^R_X = \epsilon(\xi) \delta^R_X$ - the difference in the order of multiplication, compared to (14), is due to the second of (79).

The explicit computation of $\mathcal{E}$ is simplified by the following identity

$$\Psi^{-1}(\phi^i \otimes \epsilon_i) = S(u^{-1}) \triangleright \epsilon_i \otimes \phi^i.$$  

(89)

which is easily proved using the invariance of the canonical element.

Inspection of our definition reveals the braided version of the trace formula (20) for the numerical integral $\langle \xi \rangle^R_{\mathcal{E}}$ - it is given by

$$\langle \xi \rangle^R_{\mathcal{E}} = \begin{array}{c} \includegraphics[width=0.1\textwidth]{braided_trace.pdf} \end{array}$$

(90)

The proof of invariance is as follows
To find out under what conditions it becomes trivial, we have to derive the braided version of (29). Omitting the somewhat lengthy diagrammatic proof, which parallels that of Lemma 3, we state

**Lemma 7** For $\mathcal{X}$, $\mathcal{D}$ dually paired FDBHAs, it holds

\[
\xi \sigma \xi \sigma (91)
\]

In analogy with the unbraided case, when $\sigma \equiv \langle 1, \mathcal{X} \rangle_{\mathcal{F}} = 0$, $\langle \cdot \rangle_{\mathcal{F}}$ is trivial; when $\sigma \neq 0$, $\langle \cdot \rangle_{\mathcal{F}}$ provides a nontrivial integral in $\mathcal{X}$. For the existence of integrals on FDBHAs and properties of them, see also [13, 14]. An analogous definition for the numerical braided integral (and a different proof of its invariance) can be found in [18].

### 4.2.4 Braided Fourier transforms

Transcribing (40), we define the Fourier transform $\hat{f}$ of the element $\xi$ of a FDBHA $\mathcal{X}$ by the equation

\[
\hat{\xi} \equiv \langle \xi S(\phi^i) \rangle \epsilon_i (92)
\]

or, in pictures,

\[
\xi \overset{\sigma}{=} \xi (93)
\]
(this differs from earlier definitions \[14\] by the use of the nonbosonic integral \(\langle \cdot \rangle\)). The output braid on the right stands for what one usually calls the Fourier transform of \(\xi\) (an element of \(\mathcal{D}\), the dual of \(\mathcal{X}\)) while the one on the left stands for the delta function in \(\mathcal{X}\) that is produced by the integration and which ensures the correct braiding behavior of \(\hat{\cdot}\). There is also a notion of braided convolution of functions, defined by

\[
\begin{align*}
\xi \otimes \eta &= \xi \otimes \eta \\
\xi \otimes \eta &= \xi \otimes \eta 
\end{align*}
\]

(94)

Again, the output braid on the left only carries a delta function in \(\mathcal{X}\). The following basic properties can be shown to hold

\[
\begin{align*}
\xi \otimes \eta &= \xi \otimes \eta \\
\xi \otimes \eta &= \xi \otimes \eta 
\end{align*}
\]

(98)

4.3 Integration on the quantum superplane

We apply now the general formalism developed above to the problem of integration on the quantum superplane. Our starting point will be the vacuum projector construction of section 4.2.3 - notice that although \(\langle 1, A \rangle = 0\) in this case, the integral is nevertheless biinvariant so we expect (95) to hold. For the canonical element we find

\[
\phi^i \otimes \epsilon_i = e_q^{-1}(\xi_i \otimes \sigma_i) 
\]

(95)

where

\[
e_q(x) = \sum_{k=0}^{\infty} \frac{1}{[k]_q!} x^k, \quad [k]_q = \frac{1 - q^{2k}}{1 - q^2}, \quad [k]_q! = [1]_q[2]_q \cdots [k]_q, \quad [0]_q \equiv 1
\]

(96)

(compare with the vacuum projectors for the quantum plane in \[3\]). The commutation relations (63), (64) imply \(\xi_i^2 = \sigma_i^2 = 0\) for \(i = 1, \ldots, N\) which gives \((\xi_i \otimes \sigma_i)^{N+1} = 0\). Using the braiding relations (67), the second of which can also be written as

\[
\Psi(\sigma_i \otimes \xi_j) = -q^{-1} \hat{R}_{kj,l} \xi_l \otimes \sigma_k
\]

(97)

we can expand \((\xi_i \otimes \sigma_i)^k\) in (95) to find

\[
\phi^i \otimes \epsilon_i = \sum_{k=0}^{N} \frac{q^{-k(k-1)}}{[k]_q!} \xi_i \cdots \xi_i \otimes \sigma_i \cdots \sigma_i
\]

(98)

With the antipode being given by

\[
S(\xi_i \cdots \xi_{ik}) = (-1)^k q^{k(k-1)} \xi_{i1} \cdots \xi_{ik}
\]

(99)
and using (89) we find
\[ E = \sum_{k=0}^{N} (-1)^k \xi_{i_1} \ldots \xi_{i_k} \sigma_{i_k} \ldots \sigma_{i_1} \] (100)

\[ \bar{E} = \sum_{k=0}^{N} (-1)^k q^k \sum_{j=1}^{N} \sum_{j_k} \sigma_{i_k} \ldots \sigma_{i_1} \xi_{j_1} \ldots \xi_{j_k} \] (101)

It will be convenient in the following to express \( \bar{E} \) in the alternative form
\[ \bar{E} = \sum_{k=0}^{N} (-1)^k q^k \left( [N-q] - \xi \cdot \sigma \right) (\bar{E}) \] (102)

where \( \xi \cdot \sigma \equiv \xi_i \sigma_i \) (this form makes the invariance under \( \Delta_A \) evident - a similar expression exists for \( E \)). Using the commutation relation \( \xi \cdot \sigma \xi_j = \xi_j (1+q^2 \xi \cdot \sigma) \) and the fact that \( \xi \cdot \sigma E = 0 \), we can now compute the integral of an arbitrary monomial \( \xi_{i_1} \ldots \xi_{i_r} \) (\( r < N \))
\[ \bar{E} \xi_{i_1} \ldots \xi_{i_r} E = \sum_{k=0}^{A} (-1)^k q^k \left[ \left( \frac{[N-q]}{[k]} \right) [A]_q ! \right] \xi_{i_1} \ldots \xi_{i_r} E \] (103)

where \( A \equiv N - r \). For the sum in parentheses, one can set
\[ S(z) = \sum_{k=0}^{A} \left( \frac{(-1)^k q^{k(2A+1)} [A]_q !}{[k]_q ! [A-k]_q !} \right) z^k \] (104)

Introducing a Jackson derivative \( \partial_z \), satisfying \( \partial_z z = 1 + q^2 \partial_z \), we find from (104)
\[ \partial_z S(z) = \frac{1}{q^2 - 1} S(z) - \frac{q^{-2A}}{q^2 - 1} S(q^2 z) \] (105)

On the other hand, it holds
\[ \partial_z S(z) = \frac{S(q^2 z) - S(z)}{q^2 - 1} ; \]

comparison with (105) shows that
\[ \frac{S(q^2 z)}{S(z)} = \frac{1 - q^2 z}{1 - q^{-2(A-1)} z} \]

from which we find
\[ S(z) = (1 - z)(1 - q^{-2} z) \ldots (1 - q^{-2(A-1)} z) , \] (106)

implying that \( S(1) = 0 \) and therefore that
\[ \langle \xi_{i_1} \ldots \xi_{i_r} \rangle = 0 \quad 0 \leq r < N . \] (107)

For \( r = N \), the integrand is (a multiple of) a delta function and its numerical integral is evidently (a multiple of) 1. We conclude that the quantum Berezin integral in \( N \) dimensions is essentially undeformed. As expected, \( \langle \cdot \rangle_N \) is trivial in this case, as the reader can easily verify.
4.4 Remarks on the integral on the quantum plane

We make here a few remarks about the transformation properties of the invariant integral on the quantum plane [25]. We denote by \(x_i, i = 1, \ldots, N\) the coordinate functions on it and by \(\partial_i, i = 1, \ldots, N\) the dual derivatives, satisfying

\[
x_1x_2 = q^{-1}\hat{R}_{12}x_1x_2, \quad \partial_2\partial_1 = q^{-1}\hat{R}_{12}\partial_2\partial_1, \quad \partial_i x_j = \delta_{ij} + q\hat{R}_{jl}ik x_k \partial_l. \tag{108}
\]

The above algebra is covariant under the transformation \(x \to \Delta_A(x) = xA, \partial \to \Delta_A(\partial) = \partial S(A^T)\) with \(A\) a GL\(_q\)(\(N\)) matrix (we omit the tensor product symbol). We assume an integral \(\langle \langle \cdot \rangle \rangle\) exists, defined on a suitable class of functions, satisfying translational invariance (in the spirit of (82)) and braiding correctly, \(i.e.\) according to (85). In the classical case of integration on the \(N\) - dimensional plane, one finds the transformation property

\[
\int f(xA) dx = \frac{1}{\text{det}(A)} \int f(x) dx \tag{109}
\]

where \(A\) is a GL\(_N\) matrix. We now show that a similar property holds in the quantum case. We remark first that (85) implies

\[
\Delta_A(\langle \langle f(x) \rangle \rangle) = \langle \langle f(xA) \rangle \rangle = \langle \langle f^{(1)}(x) \rangle \rangle f^{(2')}\langle A \rangle \tag{110}
\]

where \(f(xA) \equiv f^{(1)}(x)f^{(2')}\langle A \rangle\). Consider now the dual action of the generators \(Y_{ij} \equiv L^+_imS(L^-mj)\) of \(U_q(gl(N))\) on the integrand

\[
\langle \langle Y_{ij} \triangleright f \rangle \rangle = \langle \langle f^{(1)} \rangle \rangle \langle Y_{ij}, f^{(2')} \rangle. \tag{111}
\]

The above action can be represented in terms of differential operators on the plane as follows [4, 5]

\[
Y_{ij} \sim q^{-2}\delta_{ij} + q^{-1}\lambda \partial_i x_j \tag{112}
\]

which gives, making use of the invariance of the integral

\[
\langle \langle Y_{ij} \triangleright f \rangle \rangle = \langle \langle (q^{-2}\delta_{ij} + q^{-1}\lambda \partial_i x_j)f \rangle \rangle = q^{-2}\delta_{ij} \langle \langle f \rangle \rangle. \tag{113}
\]

Repeating the calculation for products of \(Y\)’s acting on \(f\), we find

\[
\langle \langle f^{(1)} \rangle \rangle \otimes f^{(2')} = \langle \langle f \rangle \rangle \otimes z \tag{114}
\]

with \(\Delta(z) = z \otimes z\) and \(\langle Y_{ij}, z \rangle = q^{-2}\delta_{ij}, \langle 1l, z \rangle = 1\). The above information completely determines \(z\). Since \(\langle Y_{ij}, \text{det}_q(A) \rangle = q^2, \epsilon(\text{det}_q(A)) = 1\) and \(\text{det}_q(A)\) is grouplike, we conclude

\[
\langle \langle f(xA) \rangle \rangle = \langle \langle f(x) \rangle \rangle (\text{det}_q(A))^{-1}. \tag{115}
\]

As in the case of the quantum superplane, to obtain the correct \(q\) factors for the braiding (so that, for example, \(x \to x\otimes 1 + 1\otimes x\) is a homomorphism of the first of (108)) one has to introduce a grouplike, central dilatation \(g\) (extending this way \(A\) to \(\tilde{A}\)) with

\[
\langle \mathcal{R}, g^a \otimes g^b \rangle = q^{ab}, \quad \langle \mathcal{R}, g^a \otimes A_{ij} \rangle = \langle \mathcal{R}, A_{ij} \otimes g^a \rangle = \delta_{ij}. \tag{116}
\]
and use the $\tilde{A}$ coaction $x \rightarrow x A g$, $\partial \rightarrow \partial S(A^T) g^{-1}$ in \cite{13}. We obtain in this way the braiding relations

\[
\Psi(\langle f(x) \rangle \otimes x_i) = q^{-(N+1)} x_i \otimes \langle f(x) \rangle \\
\Psi(\langle f(x) \rangle \otimes \partial_i) = q^{N+1} \partial_i \otimes \langle f(x) \rangle \\
\Psi(\langle f(x) \rangle \otimes \langle g(x) \rangle) = q^{N(N+1)} \langle g(x) \rangle \otimes \langle f(x) \rangle.
\] (116)

We point out that a translationally invariant integral on the quantum plane cannot be also invariant under the coacting quantum group - an assumption to the contrary is made in \cite{10}.

\section{Integration on Quantum Group Modules}

We present here an approach to integration on quantum spaces that are covariant under a quantum group transformation, which does not rely on the braided Hopf algebra structure we have assumed so far. The only necessary ingredients are

- a coaction $\Delta_A : \mathcal{X} \rightarrow \mathcal{X} \otimes A$, where $A$, $\mathcal{X}$ are the algebras of functions on the quantum group and the quantum space respectively
- a map $\eta : \mathcal{X} \rightarrow C$ that respects the algebra structure of $\mathcal{X}$
- a (left) invariant integral on $A$.

Given the above data, an invariant (under $\Delta_A$) integral on $\mathcal{X}$ can be defined by

\[
\langle \alpha \rangle = \eta(\alpha^{(1)}) \langle \alpha^{(2)} \rangle
\] (117)

(we denote by $\langle \cdot \rangle$ the integral on both $\mathcal{X}$ and $A$). Notice that our notion of invariance in this section is different from the one employed so far in this paper. Indeed, in the absence of a (possibly braided) Hopf structure, no concept of translation exists (as codified by the coproduct) and therefore \cite{10} cannot serve as our starting point. We illustrate the above procedure taking for $\mathcal{X}$ the quantum Euclidean space (for detailed treatments of this case see \cite{8, 21}). An example of a function algebra the integral on which eludes all methods presented so far in this paper appears in \cite{3}).

\subsection{Integration on the quantum Euclidean space}

In the following we use the notation and conventions of \cite{3}. The algebra of functions on the $N$-dimensional quantum Euclidean space is generated by the coordinates $x_i$, $i = 1, \ldots, N$ satisfying

\[
x_1 x_2 P^{(-)}_{12} = 0,
\] (118)

where $P^{(-)}$ is the antisymmetric projector in the spectral decomposition of the $SO_q(N)$ $\hat{R}$ matrix. The center of the algebra is generated by 1 and the squared length $L^2 = x^T C x$ where $C$ is the quantum metric. For $A$ an $SO_q(N)$ matrix, it holds

\[
S^2(A) = D A D^{-1}, \quad D = C C^T, \quad A = C^T S(A^T)(C^{-1})^T.
\] (119)

The algebra of the $x$’s admits the coaction $\Delta_A : x \mapsto x A$ while the map $\eta : x_i \mapsto u_i \equiv u_1 \delta_{i1} + u_N \delta_{iN}$, with $u_1$, $u_N$ numbers, respects \cite{118}. $L^2$ is $\Delta_A$-invariant.
The integral \( \mathcal{I}_{i_1 \ldots i_m} \equiv \langle x_{i_1} \ldots x_{i_m} \rangle \) is given by
\[
\mathcal{I}_{i_1 \ldots i_m} = \eta(x_{j_1} \ldots x_{j_m}) \langle A_{j_1i_1} \ldots A_{j_mi_m} \rangle.
\] (120)

Notice that the function \( x_{j_1} \ldots x_{j_m} \langle A_{j_1i_1} \ldots A_{j_mi_m} \rangle \) is \( \Delta_A \)-invariant. Assuming that all \( \Delta_A \)-invariant functions are functions of the invariant length, we conclude
\[
x_{j_1} \ldots x_{j_m} \langle A_{j_1i_1} \ldots A_{j_mi_m} \rangle = \begin{cases} 
    f_{i_1 \ldots i_m}(L^m) & \text{m even} \\
    0 & \text{m odd}
\end{cases}
\] (121)
and therefore
\[
\mathcal{I}_{i_1 \ldots i_m} = \begin{cases} 
    \eta(f_{i_1 \ldots i_m}(L^2)) & \text{m even} \\
    0 & \text{m odd}
\end{cases}.
\] (122)

We treat, as an example, the case \( m = 2 \). Setting
\[
F_{ni,mj} \equiv \langle S(A_{im})A_{nj} \rangle
\] (123)
and invoking invariance in the form \( S(a(1)) \langle a(2) \rangle = 1 \langle a \rangle \), we get
\[
A_{rb}F_{bi,aj} = A_{rb}S(A_{bm})S^2(A_{ni})F_{ma,nj}
\Rightarrow A_1F_{12}D_1 = F_{12}D_1A_1.
\] (124)

Since only multiples of the identity matrix commute with \( A \), we conclude
\[
F_{12} = M_2D_1^{-1}.
\] (125)

However,
\[
A_{ki}F_{bi,aj} = A_{ki}S(A_{in})A_{rj}F_{bm,ar}
\Rightarrow A_2F_{12} = F_{12}A_2
\Rightarrow M_2 = \rho I_2,
\] (126)
with \( \rho \) a number. With the normalization \( \langle 1_A \rangle = 1 \), we find \( \rho = (\text{Tr } D^{-1})^{-1} \) and therefore
\[
F_{bi,aj} = \frac{1}{\text{Tr } D^{-1}}D^{-1}_{ba}\delta_{ij}.
\] (127)

Using now the third of (119) in (120) and substituting the above result, we find, with the help of (119),
\[
\mathcal{I}_{i_1i_2} = \frac{\eta(L^2)}{\text{Tr } D^{-1}}C_{i_1i_2}.
\] (128)

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