GRADED GEOMETRY AND POISSON REDUCTION

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Abstract. A result of [2] extends the Marsden-Ratiu reduction theorem [4] in Poisson geometry, and is proven by means of graded geometry. In this note we provide the background material about graded geometry necessary for the proof in [2]. Further, we provide an alternative algebraic proof for the above result.

1. Introduction

Many geometric structures on an ordinary manifold may be rephrased as the data of a Poisson-self-commuting function on an associated super symplectic manifold (with a refinement in the grading—a graded symplectic manifold). This is the case, e.g., of Poisson and Courant structures.

The problem of reduction of such structures may be then equivalently rephrased in the associated super version. The most general reduction in symplectic geometry is that of presymplectic submanifolds. In the case at hand, besides generalizing this result to the super case, one has to find conditions for the associated function to descend and to be still self-commuting on the quotient. In the special case of coisotropic submanifolds the first condition implies the second, but in general this is not the case. Some rather general sufficient, but not necessary, conditions may be worked out in a reduction-by-stages framework.

Once these results have been obtained, they can be translated back into the ordinary diffeogeometric language. Namely, one gets a general reduction theory for Poisson manifolds in terms of vector bundles on submanifolds satisfying certain conditions. Once the result is known, it can also be proved directly without reference to supergeometry, see Section 8.

All this generalizes the known reduction procedures in Poisson geometry, in particular the celebrated Marsden–Ratiu reduction [4].

In this note we concentrate on the main results of this approach referring to [2] for more details and complete proofs. The classical proof of Section 8 is new. The case of reduction of Courant algebroids and of generalized complex structures will be treated in [1].

2. Poisson manifolds

Definition 1. $M$ is a Poisson manifold if $C^\infty(M)$ is endowed with a Lie bracket $\{\cdot, \cdot\}$ satisfying

$$\{f, gh\} = \{f, g\}h + g\{f, h\}. \quad (1)$$

Let $M$ be a smooth manifold. The Lie bracket of vector fields on $M$ extends to a bracket—called Schouten bracket—on all multivector fields on $M$. The Schouten bracket, together with the wedge product, endows the set of multivector fields
A := Γ(∧^*TM) with the structure of a Gerstenhaber algebra (also called graded Poisson algebra of degree 1). This means that A is a graded commutative algebra, that A[k] (defined by A[1] = A_{i+1}) is a graded Lie algebra (see [4]), and that the two structures are compatible in the sense that the adjoint action of a homogeneous element X ∈ A is a graded derivation of degree deg(X) − 1:

\[ [X, Y \wedge Z] = [X, Y] \wedge Z + (-1)^{(\text{deg}(X)-1) \cdot \text{deg}(Y)} Y \wedge [X, Z]. \]

The Schouten bracket between a vector field and a function is [X, f] = X(f), and the Schouten bracket of two vector fields is the usual Lie bracket. This determines the Schouten bracket on the whole of Γ(∧^*TM) by virtue of (2).

The Gerstenhaber algebra of multivector fields is relevant for us because it allows us to describe a Poisson manifold \( \mathcal{M} \) as a manifold with a bivector field \( \pi \in \Gamma(\wedge^2T\mathcal{M}) \) satisfying the Schouten-bracket relation \( [\pi, \pi] = 0 \). The connection to Def. 1 is established as follows: the bracket \( \{\cdot, \cdot\} \) is encoded by a bivector field \( \pi \) due to (1), the correspondence being \( \{f, g\} = \pi(df, dg) \). The fact that \( \{\cdot, \cdot\} \) satisfies the Jacobi identity is equivalent to \( [\pi, \pi] = 0 \).

3. Graded manifolds and the problem

Ordinary manifolds are modeled on open subsets of \( \mathbb{R}^n \). We start describing the local model for a graded manifold.

**Definition 2.** Let \( U \subset \mathbb{R}^n \) open subset and \( V = \oplus_{i \neq 0} V_i \) a \( \mathbb{Z} \)-graded vector space.

The local model for a graded manifold consists of the pair:

- \( U \) (the “body”)
- \( C^\infty(U) \otimes S^\bullet(\mathcal{V}^*) \) (the graded commutative algebra of “functions”)

Notice that here \( S^\bullet(\mathcal{V}^*) \) denotes the graded symmetric algebra over \( \mathcal{V}^* \), so its homogeneous elements anticommute if they both have odd degree.

**Definition 3.** A graded manifold consists of a pair as follows:

- a topological space \( \mathcal{M} \) (the “body”)
- a sheaf \( \mathcal{O}_\mathcal{M} \) over \( \mathcal{M} \) of graded commutative algebras, locally isomorphic to the above local model (the sheaf of “functions”).

We use the notation \( C(\mathcal{M}) \) for \( \mathcal{O}_\mathcal{M}(\mathcal{M}) \), the space of “functions on \( \mathcal{M} \).”

A graded vector bundle \( E = \oplus_{i \neq 0} E_i \to \mathcal{M} \) can be viewed as a graded manifold with body \( \mathcal{M} \) and functions \( \Gamma(S^\bullet E^*) \). Recall that \( E[1] \) is defined by \( (E[1])_i = E_{i+1} \).

**Example 4.** \( T^*[\mathcal{M}] \) is a graded manifold with body \( \mathcal{M} \) and functions

\( \Gamma(S^\bullet(\mathcal{T}[\mathcal{M}])) = \Gamma(\wedge^*TM) = \{\text{multivector fields on } \mathcal{M}\}. \)

Explicitly, we can choose coordinates \( x_j \) on \( \mathcal{M} \), giving rise coordinates \( p_j \) on the fibers of \( T^*\mathcal{M} \); assigning degree 1 to them we obtain coordinates \( \xi_j \) of fibers of \( T^*[\mathcal{M}] \). In these coordinates, a vector field \( a_i(x) \partial_{x_i} \) corresponds to the degree 1 function \( a_i(x)\xi_i \) on \( T^*[\mathcal{M}] \).

Exactly as usual cotangent bundles, \( T^*[\mathcal{M}] \) has a symplectic form \( \omega = dx_j \wedge d\xi_j \), which gives rise a Poisson bracket of degree −1 on \( C(T^*[\mathcal{M}]) \) determined by \( \{\xi_j, x_k\} = \delta_{jk}, \quad \{\xi_j, \xi_k\} = 0, \quad \{x_j, x_k\} = 0 \) and the Leibniz rule. But this is just the Schouten bracket on multivector fields! Hence we see that the degree 1 graded
Poisson algebra structure on the functions on \( T^*|1| M \) coincides with the one defined in Section 2. Summarizing, we obtain the following bijective correspondences (this is Prop. 4.1 of [5]):

**Proposition 5.** Poisson bracket \( \{\cdot, \cdot\} \) on \( M \leftrightarrow \) bivector field \( \pi \in \Gamma(\wedge^2 TM) \) satisfying \( [\pi, \pi] = 0 \leftrightarrow \) degree 2 function \( S \) on \( T^*|1| M \) satisfying \( \{S, S\} = 0 \).

Hence a Poisson structure on a manifold \( M \) can equivalently be regarded as a very simple kind of structure – indeed, just a function – on \( T^*|1| M \).

In the rest of this note we want to consider the following reduction problem:

Let \( M \) be a Poisson manifold. Specify geometric data on \( M \) out of which one can construct canonically a new Poisson manifold.

In virtue of Prop. 5 the problem becomes: specify geometric data on the pair \((T^*|1| M, S)\) which allow us to construct canonically a new degree 1 symplectic manifold – see Remark 6 it will be again of the from \( T^*|1| X \) for some manifold \( X \) – and a self-commuting degree 2 function on it.

A common way in ordinary symplectic geometry to construct new symplectic manifolds is to take a submanifold \( N \) which is presymplectic (i.e. \( \ker(\iota^* \omega) = TN^\omega \cap TN \) has constant rank; the special case where \( TN^\omega \subset TN \) is called coisotropic) and to consider the quotient \( N/\ker(\iota^* \omega) \), which is automatically symplectic if smooth.

This suggests to consider presymplectic submanifolds \( \mathcal{C} \) of \( T^*|1| M \) so that the function \( S \) descends to the quotient of \( \mathcal{C} \) by its characteristic distribution and is self-commuting there. In the next sections we will carry this out, and in Thm 13 we will give an answer to the above reduction problem.

**Remark 6.** A degree \( n \) graded symplectic manifold is a \( \mathbb{Z}_{\geq 0} \)-graded manifold endowed with a non-degenerate, closed 2-form whose corresponding Poisson bracket has degree \( -n \). The degrees of coordinates on the graded manifold lie between 0 and \( n \) (Lemma 2.4 of [5]). A choice of degree \( n+1 \) self-commuting function determines a geometric structure by the so-called derived bracket construction.

For \( n = 1 \) this geometric structure is the one of a Poisson manifold (Prop. 5). All degree 1 symplectic manifolds are of the form \( T^*|1| X \) for some \( X \) (Prop. 3.1 of [5]).

For \( n = 2 \) the geometric structure is a so-called Courant algebroid [5]. Some of the constructions for the case \( n = 2 \) carried out in this note for \( n = 1 \) are considered in [1].

4. Graded submanifolds

Degree 1 graded manifolds \( \mathcal{M} \) are always of the form \( W[1] \) where \( W \rightarrow M \) is a vector bundle.

We define graded submanifolds of \( \mathcal{M} \) in terms of coordinate functions on \( \mathcal{M} \). To this aim recall that functions \( x_i \) of degree zero \( (i \leq \dim(M)) \) and \( \xi_j \) of degree one \( (j \leq \text{rk}(W)) \) defined over an open subset \( U \subset M \) are called coordinates if the \( x_i \) are usual coordinates on \( U \) and there is an isomorphism of graded commutative algebras from \( \mathcal{O}_M(U) \) to the local model \( C^\infty(U) \otimes S^*(V^*) \) so that under this isomorphism
the $\xi_j$ correspond a basis of $V^*$. Here $V$ is a vector space concentrated in degree $-1$ with $\dim(V) = \text{rk}(W)$.

**Definition 7.** A graded submanifold $C$ of $M$ is given by a homogeneous graded ideal $I \subset C(M) := O_M(M)$ satisfying the following “smoothness” property. In a neighborhood $U$ of any point $x \in M$ satisfying $I_0(x) = 0$ there exist coordinates $x_i$ and $\xi_j$ so that $I(U)$ is generated by $x_{\dim(C)+1}, \ldots, x_{\dim(M)}$ and $\xi_{\dim(C)+1}, \ldots, \xi_{\dim(W)}$. Further, we require that the vanishing set of $I_0$ be closed in $M$. The integers $\dim_i(C)$ are called the dimensions of $C$ in degree $i$ ($i = 0, 1$).

In concrete terms, we have $I_0 = Z(C)$ for some closed submanifold of $M$ and $I_1 = \Gamma(E)$ for some vector subbundle $E \to C$ of $M^* \to M$. Here and in the sequel we use the notation $\tilde{\Gamma}(\bullet)$ to denote sections of a vector bundle which restrict to sections of the subbundle $\bullet$, so $\tilde{\Gamma}(E) = \{X \in \Gamma(M^*) : X|_C \subset E\}$.

Since $C(M)/I$ is canonically isomorphic to $C(E^*[1])$ we write $C = E^*[1]$. Here $E^o \subset W|_C$ denotes the annihilator of $E$.

**5. Coisotropic submanifolds**

In the previous section we saw that submanifolds of $M := T^*[1]M$ are of the form $E^*[1]$ for some vector subbundle $E \to C$ of $MC \to M$. Denote by $I$ the ideal defining $C$ and by $\mathcal{N}(I)$ the Poisson normalizer of $I$, i.e. the set of functions $\phi \in C(M)$ satisfying $\{\phi, I\} \subset I$. One computes

\begin{equation}
\mathcal{N}(I)_0 = \{f \in C^\infty(M) : df|_C \subset E^o\} =: C_{E^o}^\infty(M),
\end{equation}

\begin{equation}
\mathcal{N}(I)_1 = \{X \in \tilde{\Gamma}(TC) : [X, \tilde{\Gamma}(E)] \subset \tilde{\Gamma}(E)\}.
\end{equation}

**Definition 8.** The submanifold $C$ is coisotropic if $\{I, I\} \subset I$ (i.e. $I \subset \mathcal{N}(I)$).

By degree reasons $\{I_0, I_0\}$ always vanishes. If $X \in I_1 = \tilde{\Gamma}(E)$ and $f \in I_0 = Z(C)$ we have $\{f, X\} = -X(f)$. So $\{I_0, I_1\} \subset I_0$ equivalent to $E \subset TC$. If $X, Y \in I_1$ then $\{X, Y\} = [X, Y]$, so $\{I_1, I_1\} \subset I_1$ is equivalent to the involutivity of the distribution $E$ on $C$.

In this case, since by construction $I$ is a Poisson ideal in the Poisson algebra $\mathcal{N}(I)$, the Poisson bracket descends making $\mathcal{N}(I)/I$ into a graded Poisson algebra. In degree 0 by eq. (3) it consists of the $E$-invariant functions on $C$, so let us assume that the quotient $\overline{C}$ of $C$ by the foliation integrating $E$ be a smooth manifold (so that $C \to \overline{C}$ is a submersion). In degree 1 by eq. (4) $\mathcal{N}(I)/I$ consists of vector fields on $C$ which are projectable w.r.t. the projection $C \to \overline{C}$, modulo vector fields lying in the kernel of the projection. In other words $(\mathcal{N}(I)/I)_1$ is isomorphic to the space of vector fields on $\overline{C}$. We conclude that $\mathcal{N}(I)/I$ is the graded Poisson algebra on a graded symplectic manifold iff $\overline{C}$ is smooth, and in that case it is the Poisson algebra of functions on $T^*[1]\overline{C}$.

Further, the function $\mathcal{S}$ induces a function $\mathcal{S}$ on $T^*[1]\overline{C}$ iff $\mathcal{S} \in \mathcal{N}(I)$. In that case, by the way we defined the bracket on $\mathcal{N}(I)/I$, it is clear that $\mathcal{S}$ commutes with itself. Hence we obtain a reduced Poisson structure on $\overline{C}$. We spell out what it means for $\mathcal{S}$ to lie in $\mathcal{N}(I)$. Since for any function $f$ on $M$ we have $\{\mathcal{S}, f\} = [\pi, f] = \sharp df$, $\{\mathcal{S}, I_0\} \subset I_0$ is equivalent to $\sharp N^* C \subset E$. Here $\sharp : T^* M \to TM$ denotes contraction with the bivector $\pi$ and $N^* C := \{\xi \in T^* M|_C : \langle \xi, TC \rangle = 0\}$. Notice that in particular $C$ is a coisotropic submanifold of $M$. Further, for any vector field $X$ on $M$, $\{\mathcal{S}, X\} = [\pi, X] = -\mathcal{L}_X \pi$, so $\{\mathcal{S}, I_1\} \subset I_2$ is equivalent
to \((L_X \pi)|_C \in \Gamma(E \wedge TM|_C)\) for any \(X \in \check{\Gamma}(E)\), which using eq. (13) below is equivalent to \(C_{E_2}^\infty(M)\) being closed under the Poisson bracket of \(M\).

We summarize:

**Proposition 9.** A coisotropic submanifold \(C\) of \(T^*[1]M\) corresponds to a submanifold \(C\) of \(M\) endowed with an integrable distribution \(E\). The coisotropic quotient of \(C\) is smooth iff \(C \cong C/E\) is smooth, and in that case the coisotropic quotient is canonically symplectomorphic to \(T^*[1]C\). The function \(S\) on \(M\) descends to a degree 2 self-commuting function on \(T^*[1]C\) (which therefore corresponds to a Poisson structure on \(C\)) iff \(\sharp N^*C \subset E\) and \(C_{E_2}^\infty(M)\) is closed under the Poisson bracket.

The Poisson-reduction result obtained from the above proposition is quite trivial. In order to obtain more interesting results we have to allow \(C\) to be not just a coisotropic submanifold, but actually a presymplectic submanifold of \(T^*[1]M\).

6. Presymplectic submanifolds

We consider again a submanifold \(C = E_2^*[1]\) of \(M := T^*[1]M\), and denote by \(I\) its vanishing ideal. To define presymplectic submanifolds we need the following

**Definition 10.** Let \(A_{ij}\) be a matrix with entries in \(C(C) := C(M)/I\). \(A\) has constant rank along \(C\) iff, switching rows and adding \(C(C)\)-multiples of a row to another row, the matrix \(A\) can be brought to the form \((\ast 0)\) where the degree zero part of the rows of \(\ast\) are linearly independent at every point of the body of \(C\).

**Definition 11.** A submanifold \(C\) is presymplectic iff \(I\) is generated by homogeneous functions \(\phi_i\) for which the matrix \(\{\phi_i, \phi_j\} \bmod I\) has constant rank along \(C\).

Translating in terms of classical geometry we obtain

**Lemma 12.** \(C\) is a graded presymplectic submanifold iff \(TC \cap E\) is a constant rank, involutive distribution on \(C\).

The quotient of \(C\) by its characteristic distribution, defined as \(N(I)/N(I) \cap I\), is smooth iff the quotient \(C := C/(TC \cap E)\) is smooth. In this case it is isomorphic to \(T^*[1]C\) as a graded symplectic manifold.

Now we address the issue of when the function \(S\) induces a function \(\tilde{S}\) on the quotient \(\tilde{C} := T^*[1]C\). \(S\) descends iff its image under the map \(C(M) \to C(M)/I\) lies in \(N(I)/N(I) \cap I\), i.e. \(S\) lies in \(N(I) + I\).

When \(S\) descends, \(\tilde{S}\) might not commute with itself. The reason is that the Poisson bracket on \(N(I)/N(I) \cap I\) is computed lifting to elements of \(N(I)\) (and not to arbitrary elements of \(N(I) + I\)).

It is clear that if \(S\) lies in \(N(I)\) then the induced function on \(\tilde{C}\) still commutes with itself. It turns out that it suffices to require that

\[\{S, I_0\} \subset I_1\]

(or equivalently \(\sharp TC^0 \subset E\)); this conditions leads to the statement of Prop. 5.17 of [2] and Prop. 4.1 of [3], which is a mild improvement of that of [4]. We do not state it here because in Thm. [13] we will state a yet better result.
7. Reduction in stages and the theorem

To derive a condition weaker than \( 5 \) we perform reduction in stage \( s \), as follows. We imbed the presymplectic submanifold \( \mathcal{C} \) in a larger coisotropic submanifold \( \mathcal{A} \) of \( \mathcal{M} \). We assume that the quotient \( \bar{\mathcal{C}} \) of \( \mathcal{C} \) by its characteristic distribution \( T \mathcal{C} \cap T \mathcal{C}^\omega \) is smooth. Locally the quotient can be realized in two stages: first take the image \( \bar{\mathcal{C}} \) of \( \mathcal{C} \) under the projection \( \mathcal{A} \to \bar{\mathcal{A}} := \mathcal{A} / T \mathcal{A}^\omega \); assuming that \( T \mathcal{C} \cap T \mathcal{A}^\omega \) has constant rank, \( \bar{\mathcal{C}} \) is a presymplectic submanifold. Then take the presymplectic quotient of \( \bar{\mathcal{C}} \). It will be (locally) symplectomorphic to \( \mathcal{C} \). Now assume that

\[
\mathcal{S} \text{ descends to } \bar{\mathcal{C}} \\
\mathcal{S} \text{ descends to a function } \bar{\mathcal{S}} \text{ on } \bar{\mathcal{A}} \\
\bar{\mathcal{S}} \text{ satisfies condition } 3, \text{ i.e. } \{\bar{\mathcal{S}}, (\mathcal{I}_{\bar{\mathcal{C}}})_0\} \subset (\mathcal{I}_{\bar{\mathcal{C}}})_1.
\]

Then the reasoning of the previous section implies that the function \( \mathcal{S} \) on \( \mathcal{C} \) commutes with itself. Since we are ultimately interested in a quotient of \( \mathcal{C} \), it is clear that condition \( 7 \) can be weakened.

The geometric procedure described above is carried out in algebraic terms in \([2]\). Writing \( \mathcal{A} = D^\circ [1] \) for a subbundle \( D \to \mathcal{A} \) of \( T \mathcal{M} \), we obtain

**Theorem 13.** Let \( \mathcal{C} \) be a submanifold of the Poisson manifold \( \mathcal{M} \) and \( E \subset T \mathcal{M} \) a subbundle such that \( F := T \mathcal{C} \cap E \) is a constant rank, involutive distribution on \( \mathcal{C} \).

Let \( D|\mathcal{C} \) be a subbundle of \( T \mathcal{M}|\mathcal{C} \) with \( F \subset D|\mathcal{C} \subset E \) and

\[
\sharp E^\circ \subset TC + D|\mathcal{C}.
\]

Let \( \mathcal{A} \) be a submanifold containing \( \mathcal{C} \) such that \( TA|\mathcal{C} = TC + D|\mathcal{C} \), and assume that \( D|\mathcal{C} \) can be extended to an integrable distribution \( D \) on \( \mathcal{A} \) such that

\[
\langle L_{X_i}, \Pi \rangle|\mathcal{C} \subset E \wedge T \mathcal{M}|\mathcal{C}
\]

where \( \{X_i\} \) is an extension from \( \mathcal{A} \) to \( \mathcal{M} \) of a (local) frame of sections of \( D \).

Then \( \underline{\mathcal{C}} := \mathcal{C}/F \) inherits a Poisson manifold structure.

8. An algebraic proof

Without the graded geometric interpretation it would have been hard to derive Thm. 13. Once the statement is known, however, it is easy to give an alternative algebraic proof. We will do so in this section.

The following algebraic statement (compare also to Prop. A.1 in \([3]\)) reduces to an obvious one when \( B = D \), for in that case \( B \cap \mathcal{I} \) a Poisson ideal in the Poisson subalgebra \( B \).

**Proposition 14.** Let \( \mathcal{P} \) be a Poisson algebra, \( \mathcal{B} \subset \mathcal{D} \) multiplicative subalgebras of \( \mathcal{P} \) and \( \mathcal{I} \) a multiplicative ideal of \( \mathcal{P} \). Assume that

\[
\{\mathcal{B}, \mathcal{B}\} \subset \mathcal{D} \cap (\mathcal{I} + \mathcal{B})
\]

and

\[
\{\mathcal{B}, \mathcal{I} \cap \mathcal{D}\} \subset \mathcal{I}.
\]
Then there is an induced Poisson algebra structure on $B_{I \cap B}$, whose bracket is determined by the commutative diagram

\[
\begin{array}{ccc}
B \times B & \xrightarrow{\{ \cdot, \cdot \}} & D \cap (I + B) \\
\downarrow & & \downarrow \\
B_{I \cap B} \times B_{I \cap B} & \xrightarrow{\{ \cdot, \cdot \}} & B_{I \cap B}.
\end{array}
\]

Proof. The above diagram is well-defined because of (11) and $\{B, I \cap B\} \subset I$ (which holds by (12)). The induced bilinear operation on $B_{I \cap B}$ satisfies the Leibniz rule (1) because the Poisson bracket on $P$ does. To check the Jacobi identity consider $f, g, h \in B_{I \cap B}$ and lifts $\tilde{f}, \tilde{g}, \tilde{h}$ to elements of $B$. Since $\{g, h\}$ and $\{\tilde{g}, \tilde{h}\}$ are lifts of the same element, using again (11) we see that their difference $\Delta$ lies in $I \cap D \cap (I + B) = I \cap D$. Hence

\[
\{f, \{g, h\}\} = \{\tilde{f}, \{\tilde{g}, \tilde{h}\}\} \mod I = \{\tilde{f}, \{\tilde{g}, \tilde{h}\}\} + \{\tilde{f}, \Delta\} \mod I
\]

where $\{\tilde{f}, \Delta\}$ lies in $I$ by (12). Taking the cyclic sum over $f, g, h$ we see that the Jacobi identity on $B_{I \cap B}$ follows from the one on $P$. \qed

Lemma 15. Theorem 13 follows from Prop. 14 setting $P = \mathcal{C}^\infty(M)$, $D = \mathcal{C}^\infty(M)_{D|\mathcal{C}}$, $B = \mathcal{C}^\infty_{E}(M) \cap \mathcal{C}^\infty_{D}(M)$ and $I = \{f \in \mathcal{C}^\infty(M) : f|_{\mathcal{C}} = 0\}$. Here we use the notation introduced for $\mathcal{C}^\infty_{E}(M)$ at the beginning of Section 5.

Proof. Condition (12) is satisfied because of requirement (9). Now we check condition (11) in two steps.

First, using (9) (i.e. $2E \supset T\mathcal{A}|_{\mathcal{C}}$), requirement (10) is equivalent to $\{B, B\} \subset D$. To see this apply to $f, g \in B$ and $X \in \tilde{\Gamma}(D)$ the identity

\[
X\{f, g\} = (\mathcal{L}_{X} \Pi)(df, dg) + \Pi(d(Xf), dg) + \Pi(df, d(Xg)).
\]

Second, we have $\{B, B\} \subset I + B$. Indeed the bracket of two elements of $B$ annihilates $D|_{\mathcal{C}}$ by the above, so its restriction to $C$ annihilates $D|_{\mathcal{C}} \cap TC = F$. So it suffices to show: any function $h$ in $\mathcal{C}^\infty_{F}(\mathcal{C})$ can be extended to a function in $B$. Using fact that locally $C/F$ embeds naturally into $A/D$ we can extend $h$ to a function in $\mathcal{C}^\infty_{F}(A)$. Choosing a complement of $E \cap TA|_{\mathcal{C}} = D|_{\mathcal{C}}$ in $E$, we can extend to an element of $B$.

Hence the assumptions of Prop. 14 are satisfied, and therefore $\frac{B}{B + I}$ is a Poisson algebra. It is clear that $\frac{B}{B + I} \subset \mathcal{C}^\infty_{F}(\mathcal{C})$. Equality holds because, as shown above, any function in $\mathcal{C}^\infty_{F}(\mathcal{C})$ can be extended to a function in $B$. \qed

Acknowledgments: M.Z. thanks the organizers of the conference “Special metrics and supersymmetry” in Bilbao (2008) for the invitation and for local support, and C.R.M. Barcelona for partial financial support. A.S.C. is grateful to C.R.M. Barcelona for hospitality. This work has been partially supported by SNF Grant 20-113439, by the European Union through the FP6 Marie Curie RTN ENIGMA (contract number MRTN-CT-2004-5652), and by the European Science Foundation through the MISGAM program.
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