A POLYNOMIAL INVARIANT AND DUALITY FOR TRIANGULATIONS

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Abstract. The Tutte polynomial $T_G(X,Y)$ of a graph $G$ is a classical invariant, important in combinatorics and statistical mechanics. An essential feature of the Tutte polynomial is the duality for planar graphs $G$, $T_G(X,Y) = T_{G^*}(Y,X)$ where $G^*$ denotes the dual graph. We examine this property from the perspective of manifold topology, formulating polynomial invariants for higher-dimensional simplicial complexes. Polynomial duality for triangulations of a sphere follows as a consequence of Alexander duality. This result may be formulated in the context of matroid theory, and in fact matroid duality then precisely corresponds to topological duality.

The main goal of this paper is to introduce and begin the study of a more general 4-variable polynomial for triangulations and handle decompositions of orientable manifolds. Polynomial duality in this case is a consequence of Poincaré duality on manifolds. In dimension 2 these invariants specialize to the well-known polynomial invariants of ribbon graphs defined by B. Bollobás and O. Riordan. Examples and specific evaluations of the polynomials are discussed.

1. Introduction

The Tutte polynomial is an invariant of graphs and matroids, important in combinatorics, knot theory, and statistical mechanics [19, 3]. Two properties of the Tutte polynomial of graphs are of particular interest: the contraction-deletion rule, and the duality $T_G(X,Y) = T_{G^*}(Y,X)$ where $G$ is a planar graph and $G^*$ is its dual. The purpose of this paper is to investigate and generalize the Tutte polynomial and its duality in the context of topology of manifolds.

In recent years authors have generalized the Tutte polynomial for graphs embedded in surfaces. This line of research was initiated by the work of B. Bollobás and O. Riordan [4] with their introduction of a polynomial invariant of ribbon graphs. A further contribution was made by the first named author in [13] where a four-variable generalization of the Tutte polynomial for graphs on surfaces was defined, satisfying a rather natural duality relation. In this paper we introduce two versions of the Tutte polynomial for simplicial complexes, and more generally for CW complexes. The first version, $T_K(X,Y)$, is defined for an arbitrary simplicial complex $K$. If $K$ is a

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triangulation of the sphere $S^{2n}$, we establish the direct analogue of the Tutte duality, $T_K(X,Y) = T_{K^*}(Y,X)$ where $K^*$ is the dual cell complex, as a consequence of Alexander duality. Recent results of [2], showing that the evaluation $T_K(0,0)$ gives the number of simplicial spanning trees in $K$, are mentioned in section 6.2.

The polynomial $T_K(X,Y)$ may be interpreted as the Tutte polynomial of a matroid associated to the simplicial chain complex of $K$. We then show that the topological duality discussed above precisely corresponds to the notion of matroid duality.

A more general four-variable polynomial invariant is defined for a simplicial complex $K$ embedded in an orientable $2n$-manifold $M$, using the intersection pairing structure on the middle-dimensional homology group $H_n(M)$. If $K$ is a triangulation of $M$, then as a consequence of the Poincaré duality on $M$ we prove

$$P_{K,M}(X,Y,A,B) = P_{K^*,M}(Y,X,B,A)$$

where $K^*$ is the dual CW complex. The polynomial $P$ is analogously defined for handle decompositions of $M$, and the duality stated above also holds for a handle decomposition and its dual. While the polynomial $T_K$ discussed above may be defined in terms of a simplicial matroid, an interpretation of the invariant $P_{K,M}$ in the context of matroid theory is not currently known (except for the case of graphs on surfaces, see discussion in section 8). If $M$ is oriented and its dimension is divisible by 4, the polynomial $P_{K,M}$ may be further refined using the decomposition into positive-definite and negative-definite subspaces associated to the intersection pairing on $M$.

The polynomial $P$ for graphs on surfaces (corresponding to $n = 1$) was introduced in [13]. Its definition was motivated in part by questions in statistical mechanics, specifically the Potts model on surfaces, and applications to topology (the Jones polynomial for virtual knots, see [13]). Moreover, it has unified many previously defined (and seemingly unrelated) invariants of graphs on surfaces: it has been established in [13], [2], [1] respectively that the Bollobás-Riordan polynomial [4], the Bott polynomial [5] and the Las Vergnas polynomial [14] are in fact all specializations of the polynomial $P$. The purpose of this paper is to investigate the duality and other properties of $P$ for higher-dimensional complexes. We give examples of the polynomial for specific handle decompositions of several manifolds.

The organization of the paper is as follows. After reviewing the background material in section 2, we formulate the polynomial $T$ and prove its duality for triangulations of a sphere in section 3. An interpretation of the polynomial $T$ in terms of simplicial matroids, and the relation between matroid duality and topological duality are presented in section 4. The four-variable polynomial $P$ is defined, and the corresponding duality theorem is proved in section 5. Lemma 5.7 establishes that the polynomial $T$ is a specialization of the more general invariant $P$, where the topological information reflecting the embedding of the complex $K$ into a manifold $M$ is disregarded. Section 6 shows calculations of the polynomial $P$ for specific manifolds. It also gives
examples of evaluations of the polynomials $T, P$ generalizing the classical fact that the number of spanning trees of a graph $G$ is the evaluation of the Tutte polynomial $T_G(0,0)$. Section 7 discusses generalizations of the polynomials $T$ and $P$. The final section 8 mentions several questions motivated by our results.

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2. Background

This section reviews some basic notions in topology and combinatorics that will be used throughout the paper. We begin by discussing the Tutte polynomial for graphs.

2.1. Graphs and the Tutte Polynomial. A graph $G$ is defined by a collection of vertices, $V$, together with a specified collection $E$ of pairs of vertices called edges. A graph is planar if it is embedded into the plane. Given a planar graph $G = (V, E)$, one can construct its dual graph $G^* = (V^*, E^*)$, whose vertices $V^*$ correspond to the connected components of $\mathbb{R}^2 \setminus G$. Two vertices in $V^*$ are connected by an edge in $E^*$ if the regions they represent are adjacent along an edge from $E$.

Given a graph $G = (V, E)$, a spanning subgraph $H \subset G$, $H = (V, E')$, has the same vertex set $V$ as $G$ and $E' \subseteq E$. Consider the following normalization of the Tutte polynomial [19].

Definition 2.2. The Tutte Polynomial of a graph $G$ is defined by:

\[
T_G(X,Y) = \sum_{H \subseteq G} X^{c(H)-c(G)} Y^{n(H)}
\]

where the summation is taken over all spanning subgraphs $H \subset G$ of $H$, $c(H)$ is the number of connected components of $H$, and $n(H)$ is the nullity of $H$ given by the rank of the first homology group $H_1(H)$. (The nullity may also be defined combinatorially as $n(H) = c(H) + |E(H)| - |V(H)|$).

This is a classical invariant in graph theory, and in particular its one variable specializations, the chromatic polynomial and the flow polynomial, are of considerable independent interest. While the Tutte polynomial encodes many properties of a graph, the main focus of this paper is on its duality relation, a feature important for applications to topology and statistical mechanics. Specifically, for a connected planar graph $G$ and its dual $G^*$, $T_G(X,Y) = T_{G^*}(Y,X)$, cf [3].
2.3. Triangulations and Duality. Our goal is to define a version of the Tutte polynomial for simplicial complexes (and more generally, for cell complexes) and to establish a duality relation similar to that of planar graphs. For this purpose, we consider triangulations and handle decompositions of smooth manifolds. Planar graphs may be thought of as cellulations of the sphere $S^2$, and when thickened a planar graph provides a handle decomposition of the sphere (vertices give rise to disks, edges to ribbons glued on along the boundaries of disks). Handle decompositions for manifolds of higher dimensions provide a geometric form of duality that generalizes dualization for planar graphs. In the remainder of this section we will summarize the relevant material about triangulations and handle decompositions, a more detailed account may be found in [17], [15].

Definition 2.4. A triangulation of a topological space $X$ is a simplicial complex $K$ homeomorphic to $X$ along with a homeomorphism $h: K \to X$.

In the formulation of the Tutte polynomial for graphs (2.1), the sum is taken over all spanning subgraphs. Framing this in the language of simplicial complexes, the sum is over all subcomplexes of top dimension 1 such that the entire 0-skeleton is included in each subcomplex. We generalize this condition to higher dimensions.

Definition 2.5. Given a simplicial (or CW) complex $K$ of dimension $\geq n$, let $L$ be its $n$-dimensional subcomplex. Call $L$ a spanning $n$-subcomplex of $K$ if their $(n-1)$-skeleta coincide, $L^{(n-1)} = K^{(n-1)}$.

If $K$ is a finite complex (this will be the case throughout the paper), there are $2^{C_n}$ spanning $n$-subcomplexes of $K$, where $C_n$ is the number of $n$-cells of $K$. Suppose $K$ is a triangulation of an $n$-manifold $M$. The dual cell complex $K^*$ of $M$ has an important property that the $k$-cells of $K^*$ are in one-to-one correspondence with the $(n-k)$-cells of $K$. This correspondence has deeper consequences that will help establish the duality statements for the polynomials introduced in this paper. We will next discuss a combinatorial construction of $K^*$, equivalently the dual complex may also be defined using dual handle decompositions, see section 2.6.

Let $M$ be an $n$-manifold and let $K$ be a triangulation of $M$. Given a $k$-cell $\sigma_k$ of $K$, its dual, $D\sigma_k$, is an $(n-k)$-cell formed by taking the union of all simplices of the barycentric subdivision that contain the centroid of $\sigma_k$ as a vertex and that are transverse to $\sigma_k$. Taking the collection of all such $D\sigma_k$ for $k = 0, 1, ..., n$ gives the desired dual cell complex $K^*$.

For example, the dual of an $n$-simplex is the 0-cell corresponding to the centroid. For a 0-simplex, the dual is the union of all simplices in the barycentric subdivision of $M$ that have that 0-cell as a vertex, which gives the $n$-cell that contains the 0-cell as a centroid. Thinking of a planar graph as a cell decomposition of the sphere $S^2$, the dual graph corresponds exactly to the dual complex. For more on triangulations
A polynomial invariant and duality for triangulations consult [17]. The geometric duality on manifolds is best understood in the context of handle decompositions, discussed in the following subsection.

2.6. Handle Decompositions. A handle decomposition of a manifold is analogous to a cell decomposition of a topological space. The goal is to understand the entire space as a union of \( n \)-balls pieced together by prescribed attaching maps. Let \( 0 \leq k \leq n \) and consider the \( n \)-ball, \( D^n \), as the product \( D^k \times D^{n-k} \). It is attached to a manifold along a part of its boundary. More precisely:

**Definition 2.7.** Let \( M \) be an \( n \)-manifold with boundary. Let \( 0 \leq k \leq n \) and let 
\[
    f : (\partial D^k) \times D^{n-k} \to \partial M
\]
be an embedding. Then \( M \cup_f (D^k \times D^{n-k}) \) is called the result of attaching a \( k \)-handle to \( M \). Some standard terminology: \( f \) is the attaching map of the handle, \( f(\partial D^k \times 0) \) is the attaching sphere, \( f(D^k \times 0) \) is the core and \( f(0 \times D^{n-k}) \) is the co-core of the handle.

It is a basic and central fact in Morse theory [15] that any smooth manifold \( M \) admits a handle decomposition. In fact, given a triangulation \( K \) of \( M \), the simplices of \( K \) may be thickened to produce a handle decomposition (see [17, p. 82]). Conversely, a handle decomposition may be retracted to give a cell decomposition of \( M \), see [17, p. 83]. (Each handle is retracted onto its core, using the product structure of the handle.)

Given a handle decomposition of \( M \), each \( k \)-handle \( D^k \times D^{n-k} \) dually may be thought of as an \( (n-k) \)-handle attached along the complementary part of its boundary, \( D^k \times \partial D^{n-k} \). This gives rise to a dual handle decomposition of \( M \). Given a triangulation \( K \) of \( M \), thickening \( K \) gives rise to a handle decomposition \( \mathcal{H} \), dualizing gives a handle decomposition \( \mathcal{H}^* \), then retracting the handles of \( \mathcal{H}^* \) onto their cores gives a complex \( K^* \). This is a construction of the dual complex \( K^* \), alternative to the combinatorial construction discussed above.

3. The Tutte polynomial for complexes and duality for triangulations of a sphere

A natural generalization of the Tutte polynomial to higher dimensions defined below is formulated using homology groups of subcomplexes of a given complex \( K \). All homology groups considered in this paper are taken with real coefficients, \( H_i(\cdot; \mathbb{R}) \). We refer the reader to [11] as a basic reference in homology theory. Denote by \( |H_n(L)| \) the rank (dimension) of the \( n \)th homology group of \( L \). The following definition is formulated for CW complexes, but the reader interested in the more restricted class of simplicial complexes may replace the term “CW” by “simplicial” and all definitions and proofs hold in this context as well.
Definition 3.1. Let $K$ be a CW complex of dimension $\geq n$. Define
\begin{equation}
T_K(X, Y) = \sum_{L \subset K^{(n)}} X^{|H_{n-1}(L)|} Y^{|H_n(L)|}
\end{equation}
where the summation is taken over all spanning $n$-subcomplexes $L$ of $K$ (see definition 2.5).

A more precise notation for the polynomial defined in (3.1) is $T_{K,n}$, including a reference to the dimension $n$. However in the case of main interest in this paper $K$ will be a triangulation of a $2n$-dimensional manifold and $n$ in definition (3.1) will always be half the dimension of the ambient manifold. Therefore the reference to $n$ is omitted from our notation.

This definition lends itself to a number of generalizations, for example see section 7.1. Section 5 below defines a 4-variable polynomial $P_K$ for a complex $K$ embedded in a $2n$-manifold $M$, giving $T_K$ as a particular specialization. If $K$ is a 1-complex (i.e. a graph), the definition of the polynomial $T_K$ coincides with the classical Tutte polynomial (2.1). The following is a generalization of the duality for the Tutte polynomial of planar graphs.

Theorem 3.2. Let $K$ be a triangulation of $S^{2n}$, then
\begin{equation}
T_{K^{(n)}}(X, Y) = T_{K^*(n)}(Y, X)
\end{equation}
where $K^{(n)}$ is the $n$-skeleton of $K$ and $K^*(n)$ is the $n$-skeleton of the dual complex $K^*$.

The duality relation (3.2) also holds in a more general setting where $K$ is the CW complex (not necessarily a triangulation) associated to a handle decomposition of $S^{2n}$, see section 2.6. The proof of the theorem still holds when $S^{2n}$ is replaced by an orientable $2n$-manifold $M$ such that $H_{n-1}(M) = H_n(M) = 0$. (For manifolds $M$ without this vanishing condition on homology, the more general polynomial $P$ of section 5 provides the right context for the duality statement.)

A generalization of the polynomial $T$, taking into account the cardinality of the torsion subgroups of the homology (with $\mathbb{Z}$ coefficients) of the subcomplexes $L$, has been suggested in [2]. It is shown in [2] that this refinement still satisfies the duality analogous to (3.2), see section 6.2 for further discussion of this invariant.

Proof of theorem 3.2. When $K$ is a triangulation of the sphere, $H_{n-1}(K) = H_{n-1}(S^{2n}) = 0$, therefore definition 3.1 in this context reads
\begin{equation}
T_K(X, Y) = \sum_{L \subset K^{(n)}} X^{|H_{n-1}(L)|} Y^{|H_n(L)|}
\end{equation}
Given a spanning $n$-subcomplex $L \subset K$, let $\overline{L}$ be the spanning $n$-subcomplex of the dual complex $K^*$ containing all of the $n$-simplices of $K^*$ except those dual to the
n-simplices of $K$. An important ingredient of the proof is the observation that $\overline{T}$ is homotopy equivalent to $S^{2n} \setminus L$. More generally:

**Lemma 3.3.** Let $M$ be a closed orientable $2n$-manifold, and let $K$ be a triangulation of $M$. Let $L$ be a spanning $n$-subcomplex of $K$ and let $\overline{T}$ be the corresponding $n$-subcomplex of $K^*$ described above. Then $\overline{T}$ is homotopy equivalent to $M \setminus L$.

**Proof.** Recall from [17] and section 2.6 above that triangulations give rise to handle decompositions. Specifically, construct a handle decomposition $\mathcal{H}$ of $M$ by thickening each $k$-simplex in $K$ to a $k$-handle, $k = 0, 1, \ldots, 2n$. Consider all handles that result from thickening $L \subset K$ and call this collection $\mathcal{H}_L$. Notice that the handles in $\mathcal{H} \setminus \mathcal{H}_L$ are thickenings of the simplices in $K \setminus L$, and these are precisely the simplices of $K$ dual to those in $\overline{T}$. Considering these handles dually, $\mathcal{H} \setminus \mathcal{H}_L$ is a thickening of $L$ (and hence it is homotopy equivalent to $\overline{T}$). To summarize, $M = \mathcal{H}_L \cup (\mathcal{H} \setminus \mathcal{H}_L)$, where $\mathcal{H}_L$ is homotopy equivalent to $L$ (in fact $L$ is a deformation retract of $\mathcal{H}_L$) and $\mathcal{H} \setminus \mathcal{H}_L$ is homotopy equivalent to $\overline{T}$. It follows that $M \setminus L$ is homotopy equivalent to $M \setminus \mathcal{H}_L$ and this in turn is homotopy equivalent to $\overline{T}$, finishing the proof of lemma 3.3. □

For each spanning $n$-subcomplex $L \subset K$, consider the corresponding $\overline{T} \subset K^*$ as above. Observe that

$$|H_{n-1}(L)| = |H_n(\overline{T})|.$$  

Indeed, one has $|H_n(X)| = |H^n(X)|$ for any topological space $X$, and Alexander duality [11] for the sphere states that

$$H^{n-1}(L) \cong H_{2n-n}(S^{2n} \setminus L) = H_n(S^{2n} \setminus L).$$

Since $\overline{T}$ is homotopy equivalent to $S^{2n} \setminus L$ we conclude that $|H_{n-1}(L)| = |H_n(\overline{T})|$. By the symmetry of our construction, this also gives $|H_{n-1}(\overline{T})| = |H_n(L)|$. Since the spanning subcomplexes $L, \overline{T}$ are in 1–1 correspondence, the corresponding terms in the expansion (3.3) of the two sides of (3.2) are equal. This concludes the proof of theorem 3.2. □

4. **Connection to Matroid Theory**

A matroid is a finite set with a notion of independence that generalizes the concept of linear independence in vector spaces. This notion was introduced by H. Whitney [23], detailed expositions may be found in [16], [21], [22]. We begin with some background definitions for matroids and the formulation of the Tutte polynomial in this context.

**Definition 4.1.** A matroid is a finite set $E$ with a specified collection $I$ of subsets of $E$, called the independent sets of $E$, such that:

[Insert definition of matroid, including independence axioms and the Tutte polynomial]

[Provide examples and applications of matroids in various fields, such as graph theory and combinatorial optimization]
(1) $\emptyset \in I$.
(2) If $B \in I$ and $A \subset B$ then $A \in I$.
(3) If $A, B \in I$ and $|A| > |B|$ then there exists $a \in A \setminus B$ such that $a \cup B \in I$.

A maximal independent set in $E$ is called a basis for the matroid.

An important example is given by graph matroids. A finite graph $G$ gives rise to a matroid as follows: take the set of all edges to be the set $E$ and call a collection of edges independent if and only if it does not contain a cycle. Equivalently, the matroid associated to a graph may be defined using the (adjacency) linear map from the vector space spanned by its edges to the one spanned by its vertices. (This is a basic example of a simplicial matroid, and this point of view is examined in more detail further below.)

**Definition 4.2.** If the set $E$ with independent sets $I$ forms a matroid, then a rank function $r$ assigns a non-negative integer to every subset of $E$ such that:

1. $r(A) \leq |A|$ for all $A \subset E$. (Here $|A|$ denotes the cardinality of $A$.)
2. If $A \subset B \subset E$, then $r(A) \leq r(B)$.
3. If $A, B \subset E$ then $r(A \cup B) + r(A \cap B) \leq r(A) + r(B)$.

A matroid is determined by its rank function. One could alternatively define the independent sets of $E$ as the sets $A \subset E$ with $|A| = r(A)$.

**4.3. Duality on Matroids.** There is a natural notion of duality for matroids. If $M = (E, I)$ is a finite matroid, then the dual matroid $M^*$ is obtained by taking the same underlying set $E$ and the condition that a set, $A$, is a basis in $M^*$ if and only if $E \setminus A$ is a basis in $M$. An important result by Kuratowski gives as a corollary that for a graphic matroid $M$, the dual matroid is graphic if and only if $M$ is the matroid of a planar graph. The rank function of the dual matroid is given by $r^*(A) = |A| - r(E) + r(E \setminus A)$.

The Tutte polynomial of a matroid $M = (E, I)$ with rank function $r$ is defined as follows:

$$T_M(X, Y) = \sum_{A \subset E} X^{r(E)-r(A)} Y^{|A|-r(A)}$$

**Theorem 4.4.** [22] The Tutte polynomial for matroids satisfies the duality

$$T_M(X, Y) = T_{M^*}(Y, X).$$

**4.5. An alternative proof of Theorem 3.2.** We will now give another proof of theorem 3.2 using a combination of algebraic topology and matroid theory. The proof relies on construction of a matroid whose Tutte polynomial coincides with the polynomial defined in (3.1).
Let $K$ be as in the statement of theorem 3.2 and consider the simplicial chain complex for $K$:

$$
\cdots \longrightarrow C_{n+1}(K) \xrightarrow{\partial_{n+1}} C_n(K) \xrightarrow{\partial_n} C_{n-1}(K) \longrightarrow \cdots
$$

Recall that $C_i(K)$ is the free abelian group generated by the $i$-simplices of $K$.

**Definition 4.6.** Given a simplicial complex $K$ of dimension $\geq n$, let $E$ be the set of $n$-simplices of $K$ (also thought of as a specific choice of generators of $C_n(K)$). A collection of elements of $E$ is said to be independent if their images under $\partial_n$ are linearly independent in $C_{n-1}(K)$. The resulting matroid $M(K) = (E, I)$ is called the *simplicial matroid* associated to $K$.

As in definition 3.1, a more precise notation for this matroid is $M(K, n)$, however $n$ should be clear from the context and is omitted from the notation. The rank function $r$ on the matroid $M(K)$ is defined by $r(A) = \text{rank}(\partial_n(A))$ where $\partial_n(A)$ is the subgroup of $C_{n-1}(K)$ generated by the images of the elements of $A$ under $\partial_n$.

This matroid has been studied by a number of authors, see [6, 7]. We will investigate the simplicial matroid in the context of triangulations of a sphere, showing that matroid duality then precisely corresponds to topological duality.

**Lemma 4.7.** (1) Let $K$ be a simplicial complex of dimension $\geq n$. Then the polynomial $T_K$ defined in (3.1) coincides with the Tutte polynomial $T_{M(K)}$ associated to the simplicial matroid $M(K)$.

(2) If $K$ is a triangulation of the sphere $S^{2n}$ then the dual matroid $(M(K))^*$ coincides with the simplicial matroid associated to the dual cell complex $K^*$, that is $(M(K))^* = M(K^*)$.

**Proof of lemma 4.7.** Note that subsets $A \subset E$ correspond to spanning $n$-subcomplexes of $K$ (definition 2.5). Given $A \subset E$, consider the corresponding $n$-subcomplex $L$ (equal to the $(n-1)$-skeleton of $K$ union with the $n$-simplices corresponding to the elements of $A$). We get the following commutative diagram induced by the inclusion $L \subset K$:

$$
\begin{array}{cccccc}
0 & \xrightarrow{\partial_{n+1}^K} & C_n(L) & \xrightarrow{\partial_n^L} & C_{n-1}(L) & \xrightarrow{\partial_n^{K-1}} & C_{n-2}(L) & \longrightarrow & \cdots \\
\downarrow & & \downarrow & & \downarrow & & \downarrow & \cdots \\
C_{n+1}(K) & \xrightarrow{\partial_{n+1}^K} & C_n(K) & \xrightarrow{\partial_n^K} & C_{n-1}(K) & \xrightarrow{\partial_n^{K-1}} & C_{n-2}(K) & \longrightarrow & \cdots \\
\end{array}
$$

where $C_{n+1}(L) = 0$ since $L$ has no $(n+1)$-cells. Thus $H_n(L) \cong \ker \partial_n^L$, and $|H_n(L)| = |\ker \partial_n^L| = |A| - r(A)$.

Note that $|H_{n-1}(L)| - |H_{n-1}(K)| = |\ker \partial_n^L / \text{im} \partial_n^L| - |\ker \partial_n^{K-1} / \text{im} \partial_n^K| = |\text{im} \partial_n^K| - |\text{im} \partial_n^L| = r(E) - r(A)$. Thus the Tutte polynomial $T_{M(K)}$ of the matroid $M(K) = (E, I)$ coincides with the polynomial $T_K$ defined in (3.1).
We will now show that when $K$ is a triangulation of $S^{2n}$, the dual matroid $(M(K))^*$ coincides with the simplicial matroid structure described above applied to $K^*$. Consider the simplicial chain complex for $K^*$:

$$\cdots \longrightarrow C_{n+1}(K^*) \xrightarrow{\partial_{n+1}^*} C_n(K^*) \xrightarrow{\partial_n^*} C_{n-1}(K^*) \longrightarrow \cdots$$

From the construction of the dual cell complex $K^*$ (sections 2.3, 2.6) it is clear that $C_i(K) \cong C_{2n-i}(K^*)$, and moreover $\partial_n^*$ is the adjoint of $\partial_{2n-i+1}$.

By definition $A$ is a basis of $M(K)$ if and only if $E \setminus A$ is a basis for $(M(K))^*$. It follows from the properties of the adjoint map that $\partial^K_n(A)$ is a linear basis for $\text{im} \partial^K_n$ if and only if $\partial_n^*(E^* \setminus A^*)$ is a basis for $\text{im} \partial_n^*$. Thus $(M(K))^* = (E^*, I^*)$ where a set $A^* \subset E^*$ is in $I^*$ iff $\partial_n^*(A^*)$ is linearly independent in $C_{n-1}(K^*)$. Therefore $(M(K))^* = M(K^*)$, concluding the proof of lemma 4.7.

It follows from the lemma that if $K$ is a triangulation of $S^{2n}$ then $T_{(M(K))^*} = T_{M(K^*)}$. This observation together with theorem 4.4 gives an alternative proof of theorem 3.2.

5. A Polynomial invariant for Triangulations of an Orientable Manifold

Let $M$ be a closed oriented $2n$-dimensional manifold. Let $K$ be a simplicial (or CW) complex embedded in $M$, for example a triangulation of $M$, and let $L$ be a spanning $n$-subcomplex of $K$ (see definition 2.5) with $i : L \longrightarrow M$ being the embedding. Recall that throughout this paper all homology groups are taken with coefficients in $\mathbb{R}$. Define:

(5.1) \[ k(S) = \text{rank } (\ker (i_* : H_n(L) \rightarrow H_n(M))) \]

Let $\cdot$ denote the intersection pairing [11] on $M$:

$$ \cdot : H_n(M) \times H_n(M) \rightarrow \mathbb{R}. $$

Consider the following vector spaces defined using the intersection pairing:

(5.2) \[ V = V(L) = \text{image } (i_* : H_n(L) \rightarrow H_n(M)), \]

(5.3) \[ V^\perp = V^\perp(L) = \{ u \in H_n(M) | \forall v \in V(L), u \cdot v = 0 \} \]

Consider two invariants of the embedding $L \longrightarrow M$:

(5.4) \[ s(L) := \text{rank } (V/(V \cap V^\perp)) \text { and } s^\perp(L) := \text{rank } (V^\perp/(V \cap V^\perp)). \]

This construction is motivated by the work in [13] corresponding to the case $n=1$. In the case $n=1$ ($M$ is a surface and $L$ is a graph in $M$) there is a geometric interpretation of the invariants $s$, $s^\perp$: $s$ equals twice the genus of the surface obtained as the regular neighborhood of the graph $L$ in $M$, and similarly $s^\perp$ is the regular neighborhood of the dual graph, see [13].
Another invariant of the embedding $S \rightarrow M$ is
\[(5.5) \quad l(H) := \text{rank} (V \cap V^\perp),\]
Note that the intersection pairing is trivial on $V \cap V^\perp$. One immediately gets a useful identity relating these invariants for any $L \subset M$:
\[(5.6) \quad k(H) + l(H) + s(H) = \text{rank} (H_n(L)).\]

**Definition 5.1.** Let $M$ be a closed oriented $2n$-manifold. Given a simplicial complex $K \subset M$, consider the polynomial
\[(5.7) \quad P_{K,M}(X,Y,A,B) = \sum_{L \subset K^{(n)}} X^{|H_{n-1}(L)|-|H_{n-1}(K)|} Y^{k(L)} A^{s(L)} B^{s^\perp(L)}\]
where the sum is taken over all spanning $n$-subcomplexes of $K$.

For a detailed discussion of the properties of this polynomial for graphs on surfaces we refer the reader to [13]. We are ready to state the main result of the paper, establishing the duality of the polynomial invariant $P$, generalizing theorem 3.2.

**Theorem 5.2.** Given a triangulation $K$ of the manifold $M$, let $K^*$ denote the dual cell complex. Then
\[P_{K,M}(X,Y,A,B) = P_{K^*,M}(Y,X,B,A).\]

**Proof.** The proof consists of two parts, first we establish the duality between the $X$ and $Y$ variables using classical duality theorems from algebraic topology. Then we will establish the duality between the $A$ and $B$ variables using elements of symplectic linear algebra. As in the proof of theorem 3.2 for each spanning $n$-subcomplex $L$ of $K$ consider the corresponding “dual” spanning $n$-subcomplex $\overline{L}$ of $K^*$.

Note that for a triangulation $K$ of $M$, $H_{n-1}(K) = H_{n-1}(M)$, therefore the exponent of $Y$ in each summand in (5.7) equals $|H_{n-1}(L)| - |H_{n-1}(M)|$.

**Lemma 5.3.** $|H_{n-1}(L)| - |H_{n-1}(M)| = k(L)$

**Proof.** Consider the homological long exact sequence for the pair $(L, M)$:
\[\cdots \rightarrow H_{n+1}(L) \rightarrow H_{n+1}(M) \rightarrow H_{n+1}(M, L) \rightarrow H_n(L) \rightarrow H_n(M) \rightarrow \cdots\]
Since $L$ does not contain any $(n+1)$-cells, $H_{n+1}(L) = 0$. Recall the following classic theorems from algebraic topology [11]:

Poincaré-Lefschetz duality: $H_i(M, M \setminus L) \cong H^{n-i}(L)$. In particular, taking $K = M$, one has

Poincaré duality: $H_k(M) \cong H^{n-k}(M)$. 
Recall from lemma 3.3 that \( L \) is homotopy equivalent to \( M \setminus \mathcal{T} \). Then \( H_{n+1}(M, L) \cong H^{n-1}(\mathcal{T}) \), and \( H_{n+1}(M) \cong H^{n-1}(M) \). Also recall that \(|H^{n-1}(M)| = |H_{n-1}(M)|\).

Coupling these relations with the long exact sequence above gives us that:

\[
|H_{n-1}(\mathcal{T})| = |H^{n-1}(\mathcal{T})| = |H_{n+1}(M, L)| = \text{rank } (\ker (i_* : H_n(L) \to H_n(M))) + |H_{n+1}(M)| = k(L) + |H^{n-1}(M)| = k(L) + |H_{n-1}(M)|,
\]

concluding the proof of lemma 5.3.

The following lemma implies that \( s(L) = s^\perp(\mathcal{T}) \), establishing the duality between the \( A \) and \( B \) variables in the polynomial \( P \):

**Lemma 5.4.** \( V(\mathcal{T}) \cong V^\perp(L) \).

**Proof.** Decompose \( M \) as the union of two submanifolds \( \mathcal{H} \) and \( \mathcal{H}^* \) that are the handle thickenings of \( L \) and \( \mathcal{T} \) respectively. Denote \( \partial := \partial \mathcal{H} = \partial \mathcal{H}^* \). Suppose \( x \in V(\mathcal{T}) \). Since the intersection of any \( n \)-cycle in \( \mathcal{H}^* \) with any \( n \)-cycle in \( \mathcal{H} \) is zero, and since \( \mathcal{H} \) is a thickening of \( L \), it is clear that \( x \cdot w = 0 \) for any \( w \in V(L) \). Thus \( x \in V^\perp(L) \) and so \( V(\mathcal{T}) \subset V^\perp(L) \).

Now we will show that \( V^\perp(L) \subset V(\mathcal{T}) \). Consider the following part of the Mayer-Vietoris sequence:

\[
\cdots \to H_n(\mathcal{H}) \oplus H_n(\mathcal{H}^*) \xrightarrow{\alpha} H_n(M) \xrightarrow{\partial} H_{n-1}(\partial) \to \cdots
\]

(5.8)

Let \( x \in H_n(M) \), we claim that \( x \notin \text{Im}(\alpha) \) implies \( x \notin V^\perp(L) \). We will establish this by finding an element, \( w \in V(L) \) such that \( x \cdot w \neq 0 \). Since \( x \notin \text{Im}(\alpha) \) we know by exactness of the above sequence that \( x \notin \ker(\partial) \) so \( \partial(x) = y \in H_{n-1}(\partial) \) is nonzero. By Poincaré duality there exists a \( z \in H_n(\partial) \) such that \( y \cdot z \neq 0 \). For a moment, we will consider a simpler case (Claim 5.3) and then we shall generalize this to the actual problem at hand (Claim 5.3).

**Claim 5.5.** Suppose \( x_1 \in H_n(\mathcal{H}, \partial \mathcal{H}) \), \( y = \partial(x_1) \in H_{n-1}(\partial) \) and \( z \in H_n(\partial) \) with \( z \cdot y \neq 0 \). Then there exists \( w \in V(L) \) which pairs nontrivially with \( x_1 : w \cdot x_1 \neq 0 \).

**Proof.** Let \( \bar{x}_1 \in H^n(\mathcal{H}) \), \( \bar{y} \in H^n(\partial) \) and \( \bar{z} \in H^{n-1}(\partial) \) be the Poincaré dual cohomology classes of \( x_1 \), \( y \) and \( z \) respectively. The intersection pairing is the Poincaré dual of the cup product in cohomology \([11]\), therefore \( \bar{y} \cup \bar{z} \neq 0 \).
Our goal is to push the cocycle $\bar{z}$ into $\mathcal{H}$, so that it intersects nontrivially with $x$. Consider the following commutative diagram in cohomology \cite{8}:

$$
\begin{array}{ccccccc}
H^n(\mathcal{H}) \otimes H^{n-1}(\partial) & \xrightarrow{i^* \otimes \text{Id}} & H^n(\partial) \otimes H^{n-1}(\partial) & \xrightarrow{\cup} & H^{2n-1}(\partial) \\
\downarrow \text{Id} \otimes \delta & & & & & \delta & \cong \\
H^n(\mathcal{H}) \otimes H^n(\mathcal{H}, \partial) & \xrightarrow{\cup} & H^{2n}(\mathcal{H}, \partial) \\
\end{array}
$$

On the level of representatives we have:

$$
\begin{array}{ccccccc}
\bar{x}_1 \otimes \bar{z} & \xrightarrow{i^* \otimes \text{Id}} & \bar{y} \otimes \bar{z} & \xrightarrow{\cup} & \bar{y} \cup \bar{z} \\
\downarrow \text{Id} \otimes \delta & & & & & \delta & \cong \\
\bar{x}_1 \otimes \delta(\bar{z}) & \xrightarrow{\cup} & \bar{x}_1 \cup \delta(\bar{z}) \\
\end{array}
$$

And since the map on the right is an isomorphism and $\bar{y} \cup \bar{z} \neq 0$, we have that $\bar{x}_1 \cup \delta(\bar{z}) \neq 0$. Finally, Poincaré duality gives an isomorphism $H^n(\mathcal{H}, \partial) \cong H_n(\mathcal{H})$. The image of $\delta(\bar{z})$ under this isomorphism, call it $w$, must pair nontrivially with $x_1$.

Our situation is slightly different. We have a manifold $M$ decomposed as the union of $\mathcal{H}$ and $\mathcal{H}^*$ along their common boundary. We claim that any cycle $\gamma$ representing a homology class in $H_n(M)$ can be decomposed as the sum of two relative cycles $\gamma_1 + \gamma_2$ in $(\mathcal{H}, \partial)$ and $(\mathcal{H}^*, \partial)$ respectively whose boundaries cancel each other.

If we are able to do this, given $x \in H_n(M)$ satisfying $x \notin \text{Im}(\alpha)$, we can decompose $x$ into $x_1 + x_2$ and find a homology class in $H_n(\mathcal{H})$ that intersects either $x_1$ or $x_2$ nontrivially using the method described in Claim\cite{5.5}.

**Claim 5.6.** Every cycle $\gamma \in C_n(M)$ is of the form $\gamma = \gamma_1 + \gamma_2$ where $\gamma_1, \gamma_2$ are relative cycles in $(\mathcal{H}, \partial), (\mathcal{H}^*, \partial)$ respectively and $\partial \gamma_1 = - \partial \gamma_2$.

**Proof.** Consider the following commutative diagram giving rise to the Mayer Vietoris sequence \cite{5.8}:

$$
\begin{array}{ccccccc}
0 & \xrightarrow{\phi} & C_n(\mathcal{H}) \oplus C_n(\mathcal{H}^*) & \xrightarrow{\psi} & C_n(M) & \xrightarrow{\partial} & 0 \\
\downarrow \partial & & & & & \downarrow \partial & & \\
0 & \xrightarrow{\phi} & C_{n-1}(\mathcal{H}) \oplus C_{n-1}(\mathcal{H}^*) & \xrightarrow{\psi} & C_{n-1}(M) & \xrightarrow{\partial} & 0 \\
\end{array}
$$

Let $\gamma$ be a cycle in $C_n(M)$. By the exactness of the top row, there exists $(\gamma_1, \gamma_2) \in C_n(\mathcal{H}) \oplus C_n(\mathcal{H}^*)$ such that $\psi(\gamma_1, \gamma_2) = \gamma_1 + \gamma_2 = \gamma$. By definition, $\partial(\gamma) = 0$ since $\gamma$ is a cycle.

Moving to the bottom row, we get that $\psi(\partial \gamma_1, \partial \gamma_2) = \partial \gamma_1 + \partial \gamma_2 = \partial \gamma = 0$. Finally we show that $\gamma_1$ and $\gamma_2$ are relative cycles with respect to the pairs $(\mathcal{H}, \partial)$ and $(\mathcal{H}^*, \partial)$. 
Since $\psi(\partial \gamma_1, \partial \gamma_2) = 0$, exactness of the bottom row gives us that there exists some $\gamma_0 \in C_{n-1}(\partial)$ such that $\phi(\gamma_0) = (\partial \gamma_1, \partial \gamma_2)$.

Now we return to the proof of lemma 5.4 specifically to the proof of the claim that $x \notin \text{Im}(\alpha)$ implies that $x \notin V^+(L)$. Suppose $x \notin \text{Im}(\alpha)$. Let $\gamma$ be a cycle representing $x$, then in the notation of claim 5.6 consider the relative homology class $x_1$ represented by the relative cycle $\gamma_1$; $x_1 = [\gamma_1] \in H_n(\mathcal{H}, \partial)$. Since $x \notin \text{Im}(\alpha)$, $x_1$ and $y = \partial x = \partial x_1$ satisfy the assumptions of claim 5.5. Therefore there exists $w \in V(L)$ with $w \cdot x_1 = w \cdot x \neq 0$, so $x \notin V^+(L)$.

Since the goal is to prove $V^+(L) \subset V(\overline{\mathcal{L}})$, we may assume $x \in \text{Im}(\alpha)$ and that $x \in V^+(L)$. Since $\text{Im}(\alpha)$ is spanned by $V(L)$, $V(\overline{\mathcal{L}})$, we may further assume $x \in V(L)$, so $x \in V(L) \cap V^+(L)$. Now $x \in V(L)$ means that there is some $x_1 \in H_n(\mathcal{H})$ such that $i_*(x_1) = x$. Consider the following part of the long exact sequence:

$$\cdots \to H_n(\partial) \xrightarrow{j_*} H_n(\mathcal{H}) \xrightarrow{k} H_n(\mathcal{H}, \partial) \to \cdots$$

We claim that $x_1 \in \text{Im}(j_*)$. Suppose to the contrary that $x_1 \notin \text{Im}(j_*)$. By exactness this means that $k(x_1) \neq 0$. Recall that the following intersection pairing is nonsingular 14:

$$H_n(\mathcal{H}) \times H_n(\mathcal{H}, \partial) \to H_{2n}(\mathcal{H}, \partial)$$

So $u \cdot k(x_1) \neq 0$ for some $u \in H_n(\mathcal{H})$. Then $u \cdot x = u \cdot x_1 = u \cdot k(x_1) \neq 0$, contradicting $x \in V^+(L)$. So $x_1 = j_*(\bar{x})$ for some $\bar{x} \in H_n(\partial)$. Recall the Mayer-Vietoris sequence 5.8:

$$\cdots \to H_n(\partial) \xrightarrow{j_*} H_n(\mathcal{H}) \xrightarrow{i_*} H_n(M) \xrightarrow{i_*} H_n(\mathcal{H}) \xrightarrow{j_*} H_n(\partial) \to \cdots$$

where $\alpha = i_* + i'_*$. Since $x_1 = j_*(\bar{x})$ and the sequence above is exact, the image $j'_*(\bar{x}) = x_2$ satisfies $i'_*(x_2) = x$. Thus $x \in V(\overline{\mathcal{L}})$, concluding the proof of lemma 5.4.

We have shown $V(\overline{\mathcal{L}}) \subset V^+(L)$ and $V^+(L) \subset V(\overline{\mathcal{L}})$, completing the proof of theorem 5.2.

The proof of theorem 5.2 above yields the following statement relating the polynomials $T$ and $P$:
Lemma 5.7. Let $K$ be a complex embedded in a manifold $M$. The polynomial $T_K$ defined in (3.1) is a specialization of $P_{K,M}$:

$$T_K(X,Y) = Y^{r/2} P_{K,M}(X,Y,Y^{1/2},Y^{-1/2}),$$

where $r = \text{rank } (H_n(M))$.

Analyzing the Mayer-Vietoris sequence for the decomposition $M = H \cup H^*$ establishes the following relation between the invariants $s,s^\perp$ and $l$ of a subcomplex $L \subset M$:

$$s(L) + s^\perp(L) + 2l(L) = \text{rank } (H_n(M)).$$

Given this relation and (5.6), the proof of lemma 5.7 follows from the fact that the corresponding summands in the expansions (3.1), (5.7) are equal.

6. Examples and evaluations

6.1. Examples. In this section we compute the polynomial $P$ for certain handle decompositions of $\mathbb{C}P^2$ and $S^2 \times S^2$. We refer the reader to [13] for examples of evaluations of $P$ in the case $n = 1$ (for graphs on surfaces).

Consider $\mathbb{C}P^2$ with the “standard” handle decomposition $\mathcal{H}$, with a single 4-handle $H^i$ for each index $i = 0, 2, 4$:

$$\mathbb{C}P^2 = H^0 \cup H^2 \cup H^4.$$ 

As remarked in section 5, the polynomial $P_{K,M}$ can be defined not just for a triangulation $K$ of a manifold $M$ but also in a more general context of a handle decomposition of $M$. (The role of the dual cell complex $K^*$ is played by the dual handle decomposition.) For the given handle decomposition of $\mathbb{C}P^2$, the sum (5.7) consists of two terms corresponding to $S = H^0$ and $S = H^0 \cup H^2$. Since the self-intersection number of the generating class of $H_2(\mathbb{C}P^2)$ is non-trivial, the first term is $B$, and the second term is $A$. Therefore for this handle decomposition of $\mathbb{C}P^2$ the polynomial is given by

$$P_{\mathcal{H},\mathbb{C}P^2} = A + B.$$ 

Observe that the polynomial is the same for a manifold $M$ and for $M$ with the opposite orientation, in this case $\mathbb{C}P^2$, however see the following section for a refinement that distinguishes them.

Now consider $S^2 \times S^2$ with the handle decomposition $\mathcal{H}$ consisting of a single 0-handle, two 2-handles, and a single 4-handle. The intersection pairing on $H_2(S^2 \times S^2)$ is of the form $\langle 1, 1 \rangle$. There are four summands in the expression (5.7), the term corresponding to $H^0$ (and no 2-handles) is $B^2$, the term corresponding to $H^0 \cup (a$ single 2-handle$)$ is 1, the term corresponding to $H^0 \cup (both$ 2-handles$)$ is $A^2$, so the polynomial is $P_{\mathcal{H},S^2 \times S^2} = A^2 + 2 + B^2$. (In both of these examples the handle decompositions are self-dual and the polynomials are actually symmetric in $A,B$, giving a stronger version of duality than the general case in theorem 5.2.)
6.2. Counting simplicial spanning trees: results of [2]. The value $T_G(0, 0)$ of the classical Tutte polynomial equals the number of spanning trees in a graph $G$, cf. [3]. A generalization of this fact for the polynomial $T_K$ defined in (3.1), due to [2], states that $T_K(0, 0)$ is the number of simplicial spanning trees of the complex $K$ in the sense of [12].

A weighted count of spanning trees has been of substantial interest, in particular due to its appearance in the matrix-tree theorem, cf. [9]. Here the weight of an $n$-dimensional spanning tree is the square of the order of its $(n - 1)$-st homology group (which is finite according to the definition of a higher dimensional spanning tree [12], [9]). Another result of [2] is a refinement of the polynomial $T_K(X,Y)$ where the terms in (3.3) are taken with coefficients $|\text{Tor}(H_{n-1}(L;\mathbb{Z}))|^2$. It is shown in [2] that this modified polynomial also satisfies the duality relation analogous to (3.2), and moreover its evaluation at $(0, 0)$ gives the weighted number of spanning subcomplexes, so it can be calculated by the simplicial matrix-tree theorem.

6.3. Other evaluations. The polynomial $P_{K,M}(X,Y,A,B)$ reflects both the combinatorial properties of a complex $K$ and the topological information concerning the embedding of $K$ into $M$. Recall that the value $T_G(1, 1)$ of the classical Tutte polynomial equals the number of all spanning subgraphs of $G$. In the following lemma we point out a generalization of this fact which holds for the polynomial $P$ for graphs on surfaces (corresponding to $n = 1$ in definition 5.7). Given a graph $G$ embedded in a surface $S$, taking a regular neighborhood of $G$ in $S$ gives it a structure of a ribbon graph (see [4, 13] for a detailed account of ribbon graphs). Similarly any subgraph of $G$ then also may be viewed as a ribbon graph.

**Lemma 6.4.** Let $G$ be a graph embedded in an orientable surface $S$. Then $P_{G,S}(1, 1, 0, 1)$ is the number of (spanning) planar ribbon subgraphs of $G$.

The proof is immediate:

$$P_{G,S}(1, 1, 0, 1) = \sum_{H \subset G} 1^{c(H) - c(G)} 1^{k(H)} 0^{s(H)} 1^{s(H)} = |\{H \subset S : s(H) = 0\}|$$

The statement now follows from the fact [13] that for graphs on surfaces $s(H)$ is twice the genus of the regular neighborhood of the graph $H$ in $S$. □

7. Generalizations of the polynomial invariants $T$ and $P$.

7.1. Polynomials $T^j$ for triangulations of the sphere $S^N$. In this subsection we note that definition 3.1 of the polynomial $T$ may be extended to spheres of any (not necessarily even) dimension, giving rise to a collection of polynomials $T^j$:
Definition 7.2. Let $K$ be a simplicial complex of dimension $n$ and let $1 \leq j \leq n$. Consider the polynomial invariant

$$T^j_K(X,Y) = \sum_{L \subset K^{(j)}} X^{|H_{j-1}(L)|-|H_{j-1}(K)|} Y^{|H_j(L)|}$$

where $K^{(j)}$ is the $j$-skeleton of $K$ and the summation is taken over all “spanning” $j$-subcomplexes $L$ of $K$ such that $L^{(j-1)} = K^{(j-1)}$.

Clearly the original polynomial $T$ in definition 3.1 (for $N = 2n$) equals $T^n$ in the definition above. The analogue of theorem 3.2 for the polynomials $T^j$ is stated as follows:

Lemma 7.3. Given a triangulation $K$ of $S^N$, let $K^*$ denote the dual cell complex. Then

$$T^j_K(X,Y) = T^{N-j}_{K^*}(Y,X)$$

for $1 \leq j \leq N$.

The proof comes down to the Alexander duality for subspaces of $S^N$, following along the lines of the proof of theorem 3.2.

7.4. The polynomial $\overline{P}$ for triangulations of an oriented $4n$-dimensional manifold. When the dimension of an oriented manifold $M$ is divisible by 4, the definition of the polynomial $P$ may be refined further. Following the notation used in equations (5.4), observe that the intersection pairing is a symmetric non-degenerate bilinear form on the vector spaces $V/(V \cap V^\perp), V^\perp/(V \cap V^\perp)$. Denote by $s_+(L)$ the dimension of a maximal subspace of $V/(V \cap V^\perp)$ on which the intersection pairing is positive definite, and similarly by $s_-(L)$ the dimension where it is negative definite. $s_+(L), s_-(L)$ are defined analogously. Note that

$$s(L) = s_+(L) + s_-(L), \quad s^+(L) = s_+(L) + s^-(L).$$

Given a triangulation $K$ of $M^{2n}$, where $n$ is even, consider

\begin{equation}
\overline{P}_{K,M}(X,Y, A_+, A_-, B_+, B_-) = \sum_{L \subset K^{(n)}} X^{|H_{n-1}(L)|-|H_{n-1}(M)|} Y^{|k(L)|} A_+^{s_+(L)} A_-^{s_-(L)} B_+^{s_+(L)} B_-^{s_-(L)}
\end{equation}

This is a refinement of the polynomial (5.7) in the sense that

$$P_{K,M}(X,Y, A, B) = \overline{P}_{K,M}(X,Y, A, A, B, B).$$

Note that while reversing the orientation of the manifold $M$ did not change the polynomial $P$, the polynomial $\overline{P}$ changes as follows:

$$\overline{P}_{K,M}(X,Y, A_+, A_-, B_+, B_-) = \overline{P}_{K,M}(X,Y, A_-, A_+, B_-, B_+).$$
where $\overline{M}$ denotes $M$ with the opposite orientation. The duality theorem 5.2 takes the form
\[ \overline{P}_{K,M}(X,Y,A_+,A_-,B_+,B_-) = \overline{P}_{K^*,M}(Y,X,B_+,B_-,A_+,A_-). \]

8. Remarks and Questions

We conclude by listing several questions motivated by our results.

1. An example of an evaluation of the polynomial $P$ is given in section 6.3: $P_{G,S}(1,1,0,1)$ is the number of planar ribbon subgraphs of a graph $G$ embedded in a surface $S$. The results of [2], discussed in section 6.2, show that the evaluation of $T_K(0,0)$ is the number of simplicial spanning trees of a complex $K$. It is likely that there are other evaluations of these polynomials which reflect both the combinatorics of the triangulation and the topology of the ambient manifold $M$. For example, an interesting question is whether a higher-dimensional generalization of lemma 6.4 holds: Given a complex $K \subset M^{2n}$, is $P_{K,M}(1,1,0,1)$ equal to the number of those subcomplexes of $K$ whose neighborhoods in $M$ embed in a homology $2n$-dimensional sphere?

2. Establishing the asymptotics of the number of different triangulations on $N$ vertices of $S^n$, as $N \to \infty$, is an interesting and difficult open problem for $n \geq 3$. The polynomials $T^j$ introduced in this paper may be useful in the analysis of this problem.

3. The chromatic polynomial (which may be thought of as a one-variable specialization of the Tutte polynomial) of planar graphs is known to satisfy a sequence of linear local relations when it is evaluated at the Beraha numbers, and moreover is satisfies a remarkable quadratic golden identity at the golden ratio [20, 10]. It is a natural generalization of this problem to ask whether there are evaluations of the polynomials introduced in this paper which satisfy additional local relations. The planar identities satisfied by the Tutte polynomial are known to fit in the framework of quantum topology (see [10]), and the lack of interesting topological quantum field theories in higher dimensions indicates that possible local relations in higher dimensions would have to be of a different nature.

4. A generalization of the Tutte and of the Bollobás-Riordan polynomials, motivated by ideas in quantum gravity, in the context of tensor graphs has been introduced in [18]. It would be interesting to find out if there is a relation between the invariants defined in this paper and those in [18].

5. Recall that the polynomial $T_K$ defined in (3.1) may be formulated in the context of matroid theory (section 1). Such a formulation of the more general polynomial $P_{K,M}$ defined in (5.7) is not immediate. A different relation between the polynomial $P$ (in the context of graphs on surfaces) and matroids is presented in [1]. It seems reasonable that this approach, in terms of matroid perspectives, may generalize to higher dimensions as well.
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