Avalanches in the raise and peel model in the presence of a wall

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Abstract
We investigate a non-equilibrium one-dimensional model known as the raise and peel model describing a growing surface which grows locally and has non-local desorption. For specific values of adsorption (ua) and desorption (ud) rates, the model shows interesting features. At ua = ud, the model is described by a conformal field theory (with conformal charge c = 0) and its stationary probability can be mapped onto the ground state of the XXZ quantum chain. Moreover, for the regime ua ≥ ud, the model shows a phase in which the avalanche distribution is scale-invariant. In this work, we study the surface dynamics by looking at avalanche distributions using a finite-sized scaling formalism and explore the effect of adding a wall to the model. The model shows the same universality for the cases with and without a wall for an odd number of tiles removed, but we find a new exponent in the presence of a wall for an even number of tiles released in an avalanche. New insights into the effect of parity on avalanche distributions are discussed and we provide a new conjecture for the probability distribution of avalanches with a wall obtained by using an exact diagonalization of small lattices and Monte Carlo simulations.

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(Some figures may appear in colour only in the online journal)

1. Introduction

The raise and peel model (RPM) is a Markov process first proposed in [1] describing the evolution of a growing surface as a fluctuating interface in one dimension. This model has been found to belong to a new universality class in non-equilibrium phenomena [1–5]. For a particular value of the adsorption (ua) and desorption (ud) rates, the model exhibits the phenomenon of self-organized criticality [6, 7] where probability distributions of desorption events show long tails and are characterized by a varying critical exponent that depends on a single parameter given by the ratio of the adsorption and desorption rates [4, 5].
When adsorption and desorption rates are equal, the model becomes solvable. This goes back to a connection established by Razumov and Stroganov [8–10] which relates the two-dimensional dense $O(n = 1)$ fully packed loop models (enumerating the stationary state probability distributions of RPM) to the ground-state wavefunctions of the XXZ chain [5, 11, 12] which in turn can be related to the stationary states of the RPM. Moreover, at this point, the spectra can be described by a conformal field theory with the central charge $c = 0$ [13, 14]. This offers a nice mathematical structure, which allows us to make conjectures using small lattices for expressions of physical quantities that remain valid for any system size.

In this work, we study the effect that a wall on one side of the system has on the avalanche distribution. We will abbreviate the raise and peel model in the presence of a wall by RPMW. So far, little is known about this model which is obtained from the RPM when the boundary is allowed to fluctuate. In this work, we focus on an even number of sites: $L = 2n$ ($n \in \mathbb{Z}$). Some other interesting results for the model with a wall have been reported, for example, in [15, 16]. In section 2, we describe the stochastic rules for the model with and without a wall and highlight some of the known results for these two cases. In section 3, we discuss the energy spectra of the stochastic Hamiltonian of the XXZ quantum chain which describe the RPM and the RPMW models for $u = 1$. Finally in section 4, we compute critical exponents for avalanche distributions in the RPM and the RPMW and derive new conjectures for probability distributions with a wall.

2. Raise and peel models

The RPM describes a growing and fluctuating interface. It is defined as follows: we consider a one-dimensional lattice with $L + 1$ sites and open boundary conditions. An interface is formed by attaching at each site non-negative integer heights $h_i$ which obey the restricted-solid-on-solid rules

$$h_{i+1} - h_i = \pm 1; \quad i = 0, 1, \ldots, L. \quad (1)$$

The initial configuration is the bare substrate (see figure 1) with all $h_i = 0$; $i = 0, 1, \ldots, L$. Tiles from rarefied gas are dropped onto this surface with a certain probability. For the RPM, a tile from the gas hits the site $i$ with probability $P_i = \frac{1}{i+1}$ for $0 < i < L$. Nothing happens on the two boundary sites $i = 0$ and $i = L$.

For the RPMW, the site $i = 0$ becomes active and the probabilities are changed as follows: the probability of landing on a given site ($P_i$) in the bulk ($0 < i < L$) is given by a uniform distribution $P_i = \frac{1}{L+1}$ that depends on an additional parameter $b$ which is the boundary rate (the bulk rate being equal to 1). With probability $P_0 = \frac{b}{L+1}$, a half-tile hits site 0. The rightmost site ($i = L$) is still never hit by a tile; thus, the probability is $P_L = 0$. 

![Figure 1](image.png)

Figure 1. Three possible cases shown for a lattice with $L = 12$ sites. (A) A tile attaches to the surface in the bulk or a half-tile attaches to site 0. (B) A tile removes a layer. (C) A tile is reflected. The substrate, denoted by the bottom tiles touching the dashed lines, remains fixed at all times.
Depending on the value of the slope at site \( i \), \( s_i = (h_{i+1} - h_{i-1})/2 \), the following processes can occur:

- **Case A**: \( s_i = 0 \) and \( h_i < h_{i-1} \). *Tile lands on a local minimum*
  
  For sites \( i > 0 \), a tile attaches to the substrate at site \( i \) with rate \( u_d \). If a tile is attached to site \( i \), the height on that site changes by 2: \( h_i \to h_i + 2 \).

- **Case B**: \( s_i = 1 \) or \( s_i = -1 \). *Tiles lands on a non-zero slope*
  
  For \( s_i = 1 \); \( i = 1, \ldots, L - 1 \); with rate \( u_d \), the tile is reflected after triggering the desorption of a layer of tiles from the segment \( h_j > h_i = h_{i+k}, j = i + 1, \ldots, i + k - 1 \), thus changing all the heights \( h_j \to h_j - 2 \) for \( j = i + 1, \ldots, i + k - 1 \). If \( s_0 = h_1 = h_0 = 1 \), the half-tile gets absorbed with rate \( b \) and the height on that site changes by 2: \( h_0 \to h_0 + 2 \).

  For \( s_i = -1 \); with rate \( u_d \), the tile is reflected after triggering the desorption of a layer of tiles from the segment \( h_j > h_i = h_{i-k}, j = i - k + 1, \ldots, i - 1 \), thus changing all the heights \( h_j \to h_j - 2 \) for \( j = i - k + 1, \ldots, i - 1 \). If \( s_0 = h_1 = h_0 = -1 \), the half-tile is reflected. Thus, the left boundary is the only site with a local absorption/reflection.

- **Case C**: \( s_i = 0 \) and \( h_i > h_{i-1} \). *Tile lands on a local maximum*
  
  The tile is reflected and nothing happens.

This stochastic process in continuum time can be described by the *master equation* [17, 18]:

\[
\frac{d}{dt} P_\alpha(t) = -\sum_\beta H_{\alpha,\beta} P_\beta(t)
\]

(2)

where \( P_\alpha(t) \) is the (unnormalized) probability of finding the system in one of the states \( |\alpha\rangle \) at time \( t \), and \( H_{\alpha,\beta} \) is the rate for the transition \( |\alpha\rangle \to |\beta\rangle \). Since this is an intensity matrix, there is at least one zero eigenvalue [4] and its corresponding eigenvector \( |0\rangle \) gives the probabilities in the *stationary* state

\[
\forall |0\rangle |H\rangle = 0, \quad \forall |0\rangle = (1, 1, \ldots, 1)
\]

\[ H|0\rangle = 0, \quad |0\rangle = \sum_\alpha P_\alpha|\alpha\rangle, \quad P_\alpha = \lim_{t\to\infty} P_\alpha(t).
\]

(4)

For the special case in which the rates are equal \( u_x = u_d \), the Hamiltonian can be written in terms of the Temperley–Lieb algebra defined in terms of generators \( e_1, e_2, \ldots, e_L \) satisfying the following commutation relations [19]:

\[
e_i^2 = e_i
\]

\[
e_i e_{i+1} e_i = e_i
\]

\[
e_i e_{i-1} e_i = e_i
\]

\[
[e_i, e_j] = 0 \quad \text{for } |i - j| \geq 2,
\]

(5)

while the one-boundary term \( e_0 \) at site \( i = 0 \) satisfies the following constraint [20, 21]:

\[
e_0^2 = e_0, \quad e_1 e_0 e_1 = e_1, \quad e_0 e_i = e_i e_0 \quad \text{if } i > 1.
\]

(6)

The algebra given by the generators \( e_i; i = 0, \ldots, L \) is the one-boundary Temperley–Lieb algebra proposed in [22] as the ‘blob algebra’ which was subsequently studied by many other authors; see, e.g., [23, 20]. The generators \( e_i \) have the following representation in terms of Pauli spin matrices:

\[
e_i = \frac{1}{2} \left\{ \sigma_i^x \sigma_{i+1}^x + \sigma_i^y \sigma_{i+1}^y - \frac{1}{2} \sigma_i^z \sigma_{i+1}^z + \frac{i}{2} + i \frac{\sigma_i^z}{2} (\sigma_i^z - \sigma_{i+1}^z) \right\}
\]

(7)

and

\[
e_0 = - \frac{1}{\sqrt{3}} \left( \frac{1}{2} \sigma_i^x + \sigma_i^y - \frac{\sqrt{3}}{2} \right).
\]

(8)
For our purposes, it becomes convenient to view the generators in terms of a tile in the bulk and a half-tile at the boundary.

$$e_0 = \begin{array}{c}
\uparrow \\
0
\end{array} \quad e_i = \begin{array}{c}
\uparrow \\
i
\end{array}$$

Products of generators at different sites, following the algebra relations, reduce to a subset of unique configurations. This is illustrated by the following two examples:

$$e_4 e_6 e_1 e_3 e_5 e_7 = \begin{array}{c}
\Box \\
0 1 2 3 4 5 6 7 8
\end{array}$$

$$e_0 e_1 e_3 e_0 e_2 e_4 e_6 e_1 e_3 e_5 e_7 = \begin{array}{c}
\Box \\
0 1 2 3 4 5 6 7 8
\end{array}$$

In terms of these generators, the stochastic Hamiltonians $H$ for the RPMs can be written as

$$H^{(b)} = b(1 - e_0) + \sum_{i=1}^{L-1} (1 - e_i)$$  \hspace{1cm} (9)$$

where $b$ is the rate at the boundary and $u_d = u_a$ and we consider open boundary conditions only. In the following sections, we will consider the RPM with a rate at the boundary $b = 0$ and the RPM with a rate $b = 1$. In the former case, a half-tile never attaches to the boundary, whereas in the latter, the half-tile may be attached to the boundary if it hits a positive slope. The following two examples illustrate the combinatorial properties for a small lattice with $L = 6$ in the RPM and for $L = 4$ in the RPMW.

$$H^{(0)} = \begin{pmatrix}
-2 & 2 & 2 & 0 & 2 \\
1 & -3 & 0 & 1 & 0 \\
1 & 0 & -3 & 1 & 0 \\
0 & 1 & 1 & -3 & 2 \\
0 & 0 & 0 & 1 & -4
\end{pmatrix} \quad H^{(b)} = \begin{pmatrix}
-3 & 0 & 0 & b & 0 & 0 \\
1 & -2 & 1 & 0 & b & 0 \\
1 & 1 & -2 & 1 & 0 & b \\
1 & 0 & 1 & -2 & -b & 0 \\
0 & 1 & 0 & 1 & -1 - b & 2 \\
0 & 0 & 0 & 0 & 1 & -2 - b
\end{pmatrix}$$

The ground-state eigenvectors of the intensity matrices (equation (9)) have remarkable combinatorial properties [4, 5, 10].

The wavefunctions $|0\rangle^{(b)}_{L}$ normalized to have the smallest entry equal to 1 (or $b$) are given by

$$|0\rangle^{(0)}_{L=6} = (11, 5, 5, 4, 1) \quad |0\rangle^{(b)}_{L=4} = (b^2, 3b(2 + b), 2b(3 + b), 3b, 3(2 + b), 3).$$  \hspace{1cm} (10)$$

Furthermore, the normalization expressions $\langle 0 |^{(b)}(0) |^{(b)}$ for $b = \{0, 1\}$ can be related to expressions describing alternating sign matrices [21]. This leads to known expressions for the normalization sequences for a given $L$ as shown in table 1.
sign matrices \([24–26]\):

AV partitions \([24, 21]\):

\[ N, H \]

and \(J\). The Phys. A: Math. Theor. to the energy spectra of the intensity matrices

The Virasoro characters are given by (here, \(\Delta\) is an integer \((\text{u} \in \mathbb{N})\) labeling descendents and \(v = \frac{\sqrt{3}}{2}\) is the speed of sound in the system \([5]\). The conformal weights \(\Delta\) are given by the following formula \([27]\):

\[ \Delta_s = \frac{s(2s - 1)}{3} = 0, 0, \frac{1}{3}, 1 \cdots \] \(s = 0, \frac{1}{2}, 1, \frac{3}{2} \cdots \).

The Virasoro characters are given by (here, \(q\) is the modular parameter)

\[ \chi_s(q) = q^{\Delta_s} (1 - q^{2s+1}) \prod_{n=0}^{\infty} (1 - q^n)^{-1}. \]

In Table 1, the excited energy states \(E_n\) for different conformal weights (labeled by \(s\)) are compared to the numerical estimations obtained by diagonalizing the intensity matrices \(H^{(0)}\) and \(H^{(1)}\) (equation (9)) and extrapolating the results for \(L \to \infty\).

Comparing both sides of Table 2, we see that the energy levels of the RPM model coincide with the ones predicted by a conformal field theory with \(\Delta_{s=0}\), while the RPMW model has different energy levels that can be explained by a conformal field theory with two conformal weights \(\Delta_{s=0}\) and \(\Delta_{s=1/2}\). Thus, there is an additional boundary operator in the model with a wall.

Next, we will turn to the time evolution of certain observables in the RPMW model. The expectation value of an observable \(X\) can be described using stochastic dynamics as

\[ \langle X \rangle(t) = \langle 0|X e^{-Ht} |\Psi(0)\rangle \]
Figure 2. The time evolution of the average number of clusters $K(t)$ for RPM and RPMW. The lines represent the expected decay functions given by $K(t, L) \propto e^{-E_1 t/L}$ with $E_1 = \frac{2v\pi}{L}$ (RPM) and $E_1 = \frac{v\pi}{L}$ (RPMW).

Table 2. Left: excited energy states $E_n \times L$ (in units of $v\pi$) for different values of $s$ (equation (13)). Right: numerical approximations for $H^{(0)} \times L$ using up to $L = 18$ sites and for $H^{(1)} \times L$ using up to $L = 16$ sites.

| $s$     | 0   | 1   | 2   | 3   | 4   | 5   |
|---------|-----|-----|-----|-----|-----|-----|
| $s = 0$ | 0   | 0   | 2   | 3   | 4   | 4   | 5   |
| $s = \frac{1}{2}$ | 0   | 0   | 1   | 2   | 3   | 3   | 4   |
| $s = 0$ (for $s = \frac{1}{2}$) | 0   | 0   | 1   | 2   | 2   | 3   | 3   |

| $n$     | 0   | 1   | 2   | 3   | 4   | 5   |
|---------|-----|-----|-----|-----|-----|-----|
| RPM     | 0   | 0.0000 | 2.0009 | 3.0035 | 4.0247 | 4.0257 | 5.037 |
| RPMW    | 1   | 0.0000 | 1.0015 | 2.0087 | 1.9954 | 3.0030 | 3.0158 |

where the initial state $|\Psi(0)\rangle$ can be expanded in a complete eigenbasis characterizing the system $|\Psi(0)\rangle = \sum_n c_n |\psi_n\rangle$, and $H$ is the stochastic matrix describing the system. Since $H$ is an intensity matrix, the lowest eigenvalue is zero; hence, the lowest non-zero eigenvalue $E_1$ is expected to dominate the time evolution for large times. Let us consider the effect of adding a wall on temporal profiles of quantities describing the system. We are going to use Family–Vicsek [30] scaling in order to check if the system is in a scale-invariant phase (analogous to the RPM) and calculate the dynamical critical exponent $z$.

If we consider a time-dependent average quantity $x(t, L)$ with $x(L)$ being its average in the stationary state, we can define a function $X(t, L) = \frac{x(t, L)}{x(L)} - 1$ that scales for large $t$ and $L$ as

$$X(t,L) = \frac{x(t,L)}{x(L)} - 1 \sim X\left(\frac{t}{L^z}\right)$$

(17)

where $z$ is the dynamical critical exponent.

We will apply this to a new quantity, the average number of clusters which we call $K(L)$ and which is defined as follows: a contact point is defined as a site $i$ where $h_i = 0$ and a cluster is defined to be the domain between two contact points. Hence, the average number of clusters can be written as $K(L) = \langle \sum_i \delta_{h_i,0} \rangle$. This quantity is plotted in figure 2 as a function of time in the form given by equation (17). Thus, $X(t, L)$ becomes $K(t, L)$ here.
The data collapse shows that the average number of clusters $K(t, L)$ has a critical exponent given by $z = 1$ for both RPM and RPMW. The long-time decay is described well by the exponential given by $E_1 = \frac{2\pi v}{L}$ for RPM and by $E_1 = \frac{\pi v}{L}$ for RPMW as expected from equation (16) for large times. This confirms that the time evolution of this stochastic system is described well by a conformal field theory expression in the presence of a wall.

4. Avalanches

Throughout this section, we always consider the boundary parameter $b = 1$. The RPM exhibits events where layers are evaporated from the substrate when a tile from the gas hits the interface. The number of tiles removed ($v$) defines the size of an avalanche. While this number is always an odd number in RPM, in RPMW, there is a possibility of an even number of tiles removed whenever an avalanche touches the boundary (the half-tile is counted as one tile). This is illustrated in figure 3.

It is known that the RPM with and without a wall exhibits self-organized criticality [6, 7] in the regime for $u \geq 1$ [4]. Desorption processes being non-local result in avalanches lacking a characteristic length scale. We denote by $S(v, L)$ the probability distribution function which gives the probability that an avalanche of size $v$ occurs for a system of size $L$. This probability distribution $S(v, L)$ therefore appears as a power law which can be described in the finite-sized scaling (FSS) form [31, 3]

$$S(v, L) = v^{-\tau}F\left(\frac{v}{L^\alpha}\right)$$

characterized by two exponents $\tau$ and $D$.

We would like to calculate these exponents for avalanches in which an odd, resp. even, number of tiles is removed. In order to obtain these exponents, the method of moments is used [4, 31]. Using the scaling form (equation (18)), we have

$$\langle v^m \rangle_L = \int S(v, L) v^m dv = \int v^{-\tau} F\left(\frac{v}{L^\alpha}\right) v^m dv$$

$$= \int w^{-\tau} L^{-D\tau} F(w) w^m L^D dw$$

$$= L^{D(1+\tau-m)} \int w^{m-\tau} F(w) dw = L^{\sigma(m)} \Gamma_m$$

where $\Gamma_m$ is the gamma function.

Figure 3. Examples of even and odd avalanches in RPMW. Avalanches occurring in the RPM release only an odd number of tiles.
where we have used \( w = v/L^D \) to obtain the scaling dependence on \( L \). We can obtain an estimate for the exponent \( \sigma(m) \) by looking at the ratio:

\[
(\langle m^m \rangle_L / \langle m^m \rangle_{L'}) = (L/L')^{-\sigma(m)}
\]

and in this manner, the exponent \( \sigma(m) \) can be estimated as [1]

\[
\sigma(m) = \left\{ \frac{\ln(\langle m^m \rangle_L / \langle m^m \rangle_{L'})}{\ln(L/L')} \right\} = \begin{cases} 0 & \text{for } m < \tau - 1 \\ D(1 + m - \tau) & \text{for } m > \tau - 1. \end{cases}
\] (23)

A linear fit to equation (23) for \( m > \tau - 1 \) gives an estimate for the values of \( D \) and \( \tau \). To obtain an idea of the spread of these values, we ran several Monte Carlo simulations to find the variation of the distribution resulting from different seeds. The results are shown in table 3.

Results in this table show that the critical exponents for an odd number of tiles removed remain unchanged by adding a wall. However, we found that for an even number of tiles, the power-law exponent \( \tau \) decreases by about 1.

We also found an interesting effect on the FSS function when the wall is added. Figure 4 shows the scaling function for RPM and RPMW for \( u = 1 \) and \( 1/u = 0.005 \). In the first case, we use \( \tau = 3.0 \) and \( \tau = 2.0 \) for an odd number of tiles and an even number of tiles, respectively, while \( D \) is kept fixed at \( D = 1 \). The bottom part shows a similar plot where we use \( \tau = 2.0 \) and \( \tau = 1.0 \). The data collapse for large lattices shown in these plots confirms the FSS form (equation (4)). In these plots, we have rescaled \( v \rightarrow (v + 1)/2 \) for \( v \) odd and \( v \rightarrow v/2 \) for \( v \) even to compare the scaling function with the one given in [5].

This model can be compared to other models exhibiting self-organized criticality. There are different universality classes given by values of critical exponents observed in the respective models. The dynamics of the RPM is similar to the Manna model [32, 33], where the sites of a one-dimensional lattice are associated with integer values representing, e.g., particles or sand grains. If the particle occupation number is below a certain threshold, the respective site is considered to be inactive, whereas lattice sites with an occupation number larger than the threshold are active. The model evolves in time by the rules that all active sites redistribute their particles among randomly chosen nearest neighbors. However, comparing the critical exponents of the Manna model and the RPM, it is clear that the RPM and the RPMW are in a different universality class from the Manna model. In fact, the models discussed in this paper belong to a new universality class of non-equilibrium models as shown in [1–5]. Evidence for this fact provided in this paper includes the dynamical critical exponent \( z = 1 \) found at the Razumov–Stroganov point (the dynamical exponent for the Manna model being \( z = 1.393(37) \) [33]) and the exponents \( D \) and \( \tau \) calculated for the probability distribution function \( S(v, L) \) (see table 3).

### Table 3. Estimates for the critical exponents in \( S(v, L) \sim v^{-D} F(v/L^D) \) for even and odd avalanches using lattices \( L = 4096 \) and \( L' = 8192 \) for boundary parameter \( b = 1 \).

| Exponent | Model | \( v \) | 1.0 | 0.45 | 0.005 |
|----------|-------|-------|-----|------|-------|
| \( D \)  | RPM [4] | Odd | 1.004 | 1.026 | 1.006 |
|          | RPM [this work] | Odd | 0.992 ± 0.058 | 1.015 ± 0.006 | 1.006 ± 0.0001 |
|          | RPMW [this work] | Odd | 0.994 ± 0.025 | 1.008 ± 0.002 | 1.006 ± 0.0001 |
|          | RPMW [this work] | Even | 0.980 ± 0.117 | 1.013 ± 0.008 | 1.006 ± 0.0001 |
| \( \tau \) | RPM [4] | Odd | 3.000 | 2.25 | 2.00 |
|          | RPM [this work] | Odd | 2.977 ± 0.079 | 2.224 ± 0.016 | 2.011 ± 0.001 |
|          | RPMW [this work] | Odd | 3.003 ± 0.071 | 2.237 ± 0.012 | 2.011 ± 0.001 |
|          | RPMW [this work] | Even | 1.932 ± 0.222 | 1.280 ± 0.074 | 1.020 ± 0.011 |
Figure 4. The scaling function $F(v/L)$ versus $v/L$ for different rates, $1/u = 1.0$ (top) and $1/u = 0.005$ (bottom). $b = 1$ for the RPMW. The left column shows the behavior for an odd number of tiles removed and the right column shows the behavior for an even number of tiles removed. The exponents used to show the data collapse are taken from table 3.

5. Conjectures for probabilities

In the RPM, three different processes may occur: absorption, desorption and reflection. Simple conjectures for the probabilities of these events have been established previously [1, 15]. In this section, we add some new conjectures for the RPMW. We will assume $u = 1$ and $b = 1$ for the RPMW throughout this paper.

The probability to lose (or gain) $v$ tiles can be written by considering the rate of change between different states of the model:

$$P(v, L) = \sum_{\eta \neq \eta'} \delta(v(\eta') - v(\eta))w_{\eta' \rightarrow \eta}P_{\eta'}/(\langle 0 | 0 \rangle \times L).$$

(24)

Here, $w_{\eta' \rightarrow \eta}$ is the transition rate from state $|v(\eta')\rangle$ to state $|v(\eta)\rangle$. $P_{\eta'}$ denotes the frequency of the state $|v(\eta')\rangle$ occurring relative to other states, i.e. the coefficient in the right eigenvector given by equation (10), while the denominator corresponds to the sum of all possible transitions. With hindsight, the denominator can be written as $\langle 0 | 0 \rangle \times L$ since there are known expressions for the normalization $\langle 0 | 0 \rangle$ per unit length, at least for $u = 1$ (see table 1).

For certain cases, the expression above can be reduced to a nice ratio of algebraic expressions depending on the size of the system. Probabilities for the RPM were first reported in [1]. In this work, we focus on the RPMW. Table 4 shows the factorized numbers for the numerator and denominator for the RPMW for different cases obtained by diagonalizing the intensity matrices and obtaining the corresponding eigenvectors for values of $L$ up to $L = 10$. This sequence can be used to conjecture expressions for the probabilities for the different
cases for arbitrary $L$. In this table, we denote the case of absorption by $v = -1$, the case of reflection by $v = 0$ and the case of desorption of $v$ tiles by $v > 0$.

Table 5 shows the probabilities for avalanches with even or odd numbers of tiles removed for a given $L$ for both RPM and RPMW. Expressions for $P(v, L)$ for RPM were first written by de Gier et al [1], and recently Alcaraz et al [15] provided the probability of absorption ($P_a$) for RPMW. In this work, we show that by splitting the desorption probability ($P_d$) into its even and odd components, we obtain a nice expression for the desorption case when an odd number of tiles is removed. However, for the even case, a simple factorization for the reflection and desorption probability is not apparent. The coefficients remain non-integer numbers within the precision of our fits. Only the sum $P_a + P_d + P_i$ has an expression with integer coefficients. The error bars on the fits leading to non-integer coefficients are as follows:

\[
P_d(\text{even}) = \frac{(1.805 \pm 0.002)L + (-4.77 \pm 0.04)}{4(2L + 1)(2L + 3)}
\]

\[
P_r = \frac{(5.99995 \pm 0.000004)L^2 + (17.201 \pm 0.003)L + (12.66 \pm 0.04)}{4(2L + 1)(2L + 3)}.
\]

We also tried to obtain fits assuming higher order polynomials for the denominators (e.g. quartic polynomials), but the errors were even bigger. The culprit probably is the probability of desorption for an even number of tiles removed, as can be seen from the following argument.

This probability is the only one vanishing algebraically as $P_d(v \text{ even}) \sim L^{-1}$ in the large-$L$ limit, whereas all other probabilities given in the table become finite expressions as $L \to \infty$. This is consistent with the scaling exponent for avalanche distributions with an even number
of tiles removed differing by 1 from the exponent for avalanches with an odd number of tiles removed. The reason for avalanches with an even number of tiles removed vanishing in the large-$L$ limit has to do with the fact that these avalanches always touch the boundary. Hence, they become more rare as the size of the system increases.

There is an alternative approach that allows us to quantify the accuracy of the numerical results. The mean size of an avalanche $\langle v \rangle$ in the stationary state can be obtained from the following mean-field expression taken from [4]:

$$\langle v \rangle_L = \frac{P_a(L)}{P_d(L)} \quad (25)$$

This is a quotient of parabolas, and in the large limit ($L \gg 1$),

$$\frac{P_a(L)}{P_d(L)} = \frac{aL^2 + bL + c}{aL^2 + bL + c} = \frac{aL^2 + bL + c}{aL^2(1 + \frac{b}{aL} + \frac{c}{aL^2})}$$

$$\approx \left(\frac{a}{a} + \frac{b}{aL} + \mathcal{O}(L^{-2})\right) \left(1 - \frac{b}{aL} + \mathcal{O}(L^{-2})\right)$$

$$\approx \left(\frac{a}{a} + \frac{1}{aL} \left(\frac{b}{a} - \frac{ab}{a}\right)\right)$$

$$= \frac{a}{a} \left(1 + \frac{1}{L} \left(\frac{b}{a} - \frac{b}{a}\right)\right). \quad (26)$$

We assume that $\alpha \neq 0$ and $a \neq 0$ and dropped terms of the order of $\mathcal{O}(L^{-2})$. In the following, we consider $v$ to be odd only. From table 5, we see that for RPM, we have in that case

$$\frac{P_a(L)}{P_d(L)} = \frac{3}{2} \left(1 - \frac{1}{L} \left(\frac{6}{3} - \frac{0}{2}\right)\right)$$

$$\Rightarrow \langle v \rangle_L = \frac{3}{2} \left(1 - \frac{2}{L}\right) \quad (27)$$

while for RPMW, we have

$$\frac{P_a(L)}{P_d(L)} = \frac{6}{4} \left(1 + \frac{1}{L} \left(\frac{8}{6} - \frac{6.8}{4}\right)\right)$$

$$\Rightarrow \langle v \rangle_L = \frac{3}{2} \left(1 - \frac{0.366}{L}\right). \quad (28)$$

The average avalanche size $\langle v \rangle(L)$ obtained from Monte Carlo simulations of the RPM and the RPMW agrees quite well with these predictions as can be seen in figure 5. This is remarkable since this describes a non-equilibrium system.

It is interesting to see that the leading term in this expansion is universal, whereas the correction term depends on the details of the model (i.e. whether there is a wall or not). This is similar behavior as in FSS of the concentration of particles in certain reaction–diffusion systems [34–36] and surface exponent corrections to quantum chains using different types of boundary conditions [37–39].

The simple functional form for the probabilities shown in table 5 suggests that we can guess a general quadratic expression in $L$ for the probabilities $P(v, L)$ by fixing the denominator as

$$P_{RPM}(v, L) = \frac{a(v)L^2 + b(v)L + c(v)}{4(2L+1)(L-1)} \quad (29)$$
Figure 5. Average avalanche size $\langle v \rangle(L)$. Predictions from the ratio of $P_v(L)/P_d(L)$ given by equations (27) and (28), respectively (lines) compared to Monte Carlo data for RPM (○) and RPMW (□). The inset figure shows the correction terms calculated from equations (27) and (28).

Figure 6. Behavior of the quadratic term $a(v)$, linear term $b(v)$ and constant term $c(v)$ obtained from fits to equations (29) and (30).

\[ P_{\text{RPMW}}(v, L) = \frac{a(v)L^2 + b(v)L + c(v)}{4(2L + 3)(2L + 1)} \]  

and fitting for the parameters \{a(v), b(v), c(v)\} in the forms (29) and (30). The behavior of these parameters as a function of $v$ is shown in figure 6. As expected, the quadratic term shows power-law behavior $\propto v^{-3.0}$. The linear and constant terms however do show different behavior, but we were not able to reduce it to an analytical form. Consistency of the fits demands that (see table 5)

\[ \sum_{v>0} P_{\text{RPM}}(v, L) = \frac{2L^2 - 8}{4(2L + 1)(L - 1)} \]  

\[ \sum_{v>0} P_{\text{RPMW}}(v, L) = \frac{4L^2 + 5L + 9}{4(2L + 3)(2L + 1)} \]
Table 6. Sums over $v$ for the parameters $a(v)$, $b(v)$ and $c(v)$ resulting from the fits.

|       | $\sum_v a(v)$ | $\sum_v b(v)$ | $\sum_v c(v)$ |
|-------|----------------|----------------|----------------|
| RPM   | 1.9999         | -0.00375       | -13.8002       |
| RPMW  | 3.9999         | 4.96604        | 30.4445        |

The sums over the parameters $\sum_v \{a(v), b(v), c(v)\}$ are shown in table 6 for RPM and RPMW. We see that the quadratic $a(v)$ and linear $b(v)$ terms capture the behavior in $v$ quite well, whereas as shown in figure 6, the constant term $c(v)$ is dominated by the fluctuations.

6. Conclusion

We studied the non-equilibrium statistical model known as the raise and peel model (RPM). We have confirmed that this model retains several features as predicted from conformal invariance when the boundary conditions are changed. We allowed one boundary to fluctuate and demonstrated that the temporal profile of a stochastic quantity follows its expected behavior from stochastic dynamics where the long-time behavior is dominated by the lowest non-zero eigenvalue. We studied the surface dynamics by looking at avalanche distributions exhibiting power-law distributions. Using the finite-sized scaling formalism, we confirmed the universality exponent $\tau = 3$ for the RPM with different boundary conditions and identified an even/odd effect with a new exponent $\tau = 2$ for avalanches with an even number of tiles removed. We also found new conjectures for the probability of desorption and reflection with a wall added to the system and checked that they agree with Monte Carlo data.

In the context of surface critical phenomena, it is interesting to ask how the presence of the wall in the RPMW changes its phase diagram. For the case without a wall, the full phase diagram is given in [5]. It depends only on the parameter $u$ and consists of a massive phase for $0 \leq u < 1$ and a scale-invariant phase for $1 < u < \infty$. At $u = 1$, the model is massless and conformal-invariant. This work shows that in the presence of a wall, the integrable point remains at $u = 1$ where the model is still given by a conformal field theory with $c = 0$; the conformal field theory has an additional boundary operator compared to the conformal field theory for the RPM. Furthermore, there is a phase exhibiting self-organized criticality for $u \leq 1$; in comparison with the RPM, there are new critical exponents in the SOC phase which occur for an even number of tiles removed in an avalanche as explained above. The detailed exploration of the full phase diagram for the RPMW is left for a future publication.

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