Exact analytical solutions of the fractional biological population model, fractional EW and modified EW equations

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1. Introduction

Due to the applications in nonlinear optics, biology, population dynamics, biomathematics, and other areas, fractional order differential equations have been considered more often. Differential equations of non-integer order construct more accurate models for the phenomena they describe. Hence, to find analytical and numerical solutions of these equations, some effective methods have been introduced and applied so far. Even so, a general method could not be proposed so scientists are still trying to develop new approaches. Finding exact analytical solutions of non-integer order differential equations play an essential role in describing the behavior of the considered model. This study implements the trial solution algorithm with the aid of complete discrimination system to establish exact solutions of non-integer order differential equations.

To this purpose, we first consider time fractional biological population model [1-4]. The equation describes population dynamics and gives ideas about complex interactions. Then, space-time fractional equal width (EW) equation [5] which describes complex physical phenomena in many fields has been considered. Finally, space-time fractional modified equal width equation [6] that describes the wave propagation with dispersion processes for one-dimensional nonlinear form was considered. Exact analytical solutions of the considered equations have been obtained successfully. All of these solutions have been confirmed by substituting them into their corresponding equation via Mathematica package program.

2. Conformable fractional derivative and trial solution algorithm

Fractional derivative reveals more suitable models for real world problems than integer order derivative. For this reason, many researchers have paid attention to develop new definitions of fractional derivative such as Caputo-Fabrizio [7] and Riemann-Liouville [8]. Also, a new definition, conformable derivative is proposed to overcome some setbacks of the existing derivatives, see Khalil et al. [9]. Conformable fractional derivative for a function \( f \) of order \( \alpha \) is defined as

\[
T_{\alpha}(f)(t) = \lim_{\tau \to 0} \frac{f(t + \tau t^{\alpha}) - f(t)}{\tau},
\]

(1)
where \( f : [0, \infty) \to R \) for all \( t > 0 \) and \( \alpha \in (0, 1) \) [9].

Some properties of the conformable fractional derivative are summarized as [9, 10]:

\[
T_\alpha (cf + kg) = cT_\alpha (f) + kT_\alpha (g), \quad \text{for all } c, k \in R.
\]

\[
T_\alpha (t^\alpha) = \beta t^{\alpha-1}, \quad \text{for all } \beta \in R.
\]

\[
T_\alpha (f \circ g) = T_\alpha (f) (g(t)), \quad \text{for all } \alpha \in (0, 1).
\]

Also, fractional versions of the Laplace transform, Taylor power series expansions and integration by parts are given by Abdeljawad, see [10].

Some authors [11-16] have studied fractional differential equations by different methods. Besides these, to investigate analytical solutions of PDEs, Liu proposed an approach called trial equation method which aims to reduce the examined equation to the solvable differential equations. Also Liu proposed complete discrimination system (CDS) to find exact solutions of PDEs, see [17-19]. The method is studied by some authors [20-23] to investigate analytical solutions of integer and non-integer order partial differential equations.

Solution steps of the trial solution algorithm can be outlined as follows [17-19]:

**Step 1.** We can consider a PDE of \( u \). Using a wave transformation, it can be reduced to an ODE.

**Step 2.** Trial equation can be chosen as

\[
U' = \sum_{i=1}^{n} a_i U^i
\]

or

\[
(U')^2 = \sum_{i=1}^{n} a_i U^i,
\]

according to the structure of the reduced equation. Using the balance procedure, the value of \( n \) can be determined.

**Step 3.** Rewriting these equations into integral form

\[
\pm (\xi - \xi_0) = \int \frac{dU}{\sum_{i=1}^{n} a_i U^i}
\]

or

\[
\pm (\xi - \xi_0) = \int \frac{dU}{\sqrt{\sum_{i=1}^{n} a_i U^i}}
\]

and using the CDS for polynomial yield the exact solution of the considered PDE.

We will apply this procedure for the fractional models.

3. Governing models

3.1. The time fractional biological population model

Consider the time fractional biological population model:

\[
\frac{\partial^\alpha u}{\partial t^\alpha} = \frac{\partial^2 u}{\partial x^2} (u^2) + \frac{\partial^2 v}{\partial y^2} (u^2) + h(u^2 - r),
\]

where \( t > 0, 0 < \alpha \leq 1, x, y \in R \), and \( h, r \) are constants. \( u \) is the population density and \( h(u^2 - r) \) denotes the population supply as a result of births and deaths. [1-4].

Under the transformation

\[
u(x, y, t) = U(\xi), \quad \xi = kx + iky - \frac{c^\alpha}{\alpha},
\]

where \( c, k \) are constants and \( i^2 = -1 \), Eq.(6) turns into the following ODE:

\[
cU' + hU^2 - hr = 0.
\]

Balancing \( U' \) and \( U^2 \) yields \( n = 2 \). Then trial equation is:

\[
U' = a_0 + a_1 U + a_2 U^2.
\]

Substituting Eq.(9) into Eq.(8) and letting all the coefficients of obtained polynomial to zero yields an algebraic equation system:

\[
- hr + ca_0 = 0
\]

\[
ca_1 = 0
\]

\[
h + ca_2 = 0.
\]

From the system above, coefficients are determined as:

\[
a_0 = \frac{hr}{c}, \quad a_1 = 0, \quad a_2 = - \frac{h}{c}.
\]

Substituting these coefficients into Eq.(4) and integrating the equation gives the following exact traveling wave solutions of the Eq.(6):

\[
u(x, y, t) = \sqrt{r} \tanh \left[ \frac{h}{c} \sqrt{r} \left( kx + iky - \frac{c^\alpha}{\alpha} \right) \right],
\]

\[
u(x, y, t) = \sqrt{r} \coth \left[ \frac{h}{c} \sqrt{r} \left( kx + iky - \frac{c^\alpha}{\alpha} \right) \right],
\]

which are dark and singular soliton solutions for \( r > 0 \). The solutions (11) and (12) signify singular periodic solutions

\[
u(x, y, t) = - \sqrt{r} \tan \left[ \frac{h}{c} \sqrt{r} \left( kx + iky - \frac{c^\alpha}{\alpha} \right) \right],
\]

\[
u(x, y, t) = \sqrt{r} \cot \left[ \frac{h}{c} \sqrt{r} \left( kx + iky - \frac{c^\alpha}{\alpha} \right) \right],
\]

as long as \( r < 0 \).

Figures 1-2 represent the graphs of the solution Eq.(11) for some arbitrary constants.
(a) Solution Eq. (11) for $\alpha = 0.05$

(b) Solution Eq. (11) for $\alpha = 0.5$

(c) Solution Eq. (11) for $\alpha = 1$

Figure 1. Solution Eq. (11) for $h = 0.01, r = 50, c = k = 1, t = 10$ and indicated $\alpha$ values.

(a) Solution Eq. (11) for $\alpha = 0.2$

(b) Solution Eq. (11) for $\alpha = 0.5$

(c) Solution Eq. (11) for $\alpha = 1$

Figure 2. Solution Eq. (11) for $h = 0.01, r = 50, c = k = 1, y = 5$ and indicated $\alpha$ values.
3.2. The space-time fractional equal width (EW) equation

Consider the space-time fractional EW equation [5]
\[ D^\alpha_t u + \epsilon D^\alpha_x u^2 - \delta D^\beta_{xx} u = 0, \]
where \( t > 0, 0 < \alpha \leq 1, \) and \( \epsilon, \delta \) are real parameters.

Under the transformation
\[ u(x, t) = U(\xi), \quad \xi = k \frac{x^\alpha}{\alpha} - c \frac{t^\alpha}{\alpha}, \]
Eq.(15) converts into the ODE:
\[ -cU' + \epsilon k (U^2)' + \delta c k^2 U'' = 0. \]

Integrating Eq.(17) and letting the constant of integration zero yields
\[ -cU + \epsilon k U^2 + \delta c k^2 U'' = 0. \]

Balancing \( U'' \) and \( U^2 \) results with \( n = 3. \) Then, trial equation is:
\[ (U')^3 = a_0 + a_1 U + a_2 U^3 + a_3 U^3. \]

With the same procedure, corresponding system of algebraic equation
\[ ck^2 \delta a_1 = 0 \\
-2c + c k^2 \delta a_2 = 0 \\
2k \epsilon + 3ck^2 \delta a_3 = 0 \]
is obtained. So, the coefficients are determined as
\[ a_0 = a_1 = 0, \quad a_2 = \frac{1}{\delta k^2}, \quad a_3 = -\frac{2 \epsilon}{3ck \delta}. \]

Using the coefficients into Eq.(5) gives
\[ \pm (\xi - \xi_0) = \int \frac{dU}{\sqrt{a_0 + \frac{1}{\delta k^2} U^2 - \frac{2 \epsilon}{3ck \delta} U^3}}. \]

Integrating (21) aid of the CDS, exact solutions of fractional EW equations have been emerged as traveling wave solutions along with \( \delta > 0 \)
\[ u(x, t) = \frac{3c}{2k \epsilon} \text{sech}^2 \left[ \frac{1}{2k \sqrt{\delta}} \left( k x^\alpha - c t^\alpha \right) \right], \]  
\[ u(x, t) = \frac{3c}{2k \epsilon} \text{csch}^2 \left[ \frac{1}{2k \sqrt{\delta}} \left( k x^\alpha - c t^\alpha \right) \right] \]

Solutions (22) and (23) mean periodic function solutions along with \( \delta < 0 \)
\[ u(x, t) = \frac{3c}{2k \epsilon} \sec^2 \left[ \frac{1}{2k \sqrt{-\delta}} \left( k x^\alpha - c t^\alpha \right) \right], \]  
\[ u(x, t) = \frac{3c}{2k \epsilon} \csc^2 \left[ \frac{1}{2k \sqrt{-\delta}} \left( k x^\alpha - c t^\alpha \right) \right] \]

Figure 3 shows the graphs of the solution Eq.(22) for some values of the arbitrary constants.
3.3. The space-time fractional modified EW equation

Now we consider the space-time fractional modified EW equation [6]

\[ D_0^\alpha u + c D_0^\alpha u^3 - \delta D_{10}^\alpha u = 0, \]  

(26)

where \( t > 0 \) and \( 0 < \alpha \leq 1 \).

Using the transformation (16), Eq.(26) reduces into the ODE:

\[ -cU'' + \epsilon k(U^3)' + \delta ck^2 U'' = 0. \]  

(27)

Integrating Eq.(27) and letting the constant of integration to zero gives:

\[ -cU + \epsilon kU^3 + \delta ck^2 U'' = 0. \]  

(28)

Balancing the terms \( U'' \) and \( U^3 \) gives \( n = 4 \). Trial equation can be chosen as

\[ (U')^2 = a_0 + a_1 U + a_2 U^2 + a_3 U^3 + a_4 U^4. \]  

(29)

If one uses the same procedure above, corresponding system

\[
\begin{align*}
ck^2\delta a_1 &= 0 \\
-2c + 2ck^2\delta a_2 &= 0 \\
3ck^2\delta a_3 &= 0 \\
2k\epsilon + 4ck^2\delta a_4 &= 0
\end{align*}
\]

is obtained. So, the coefficients are determined as

\[
\begin{align*}
a_0 &= a_0, \quad a_1 = 0, \quad a_2 = \frac{1}{\delta k^2}, \quad a_3 = 0, \quad a_4 = -\frac{\epsilon}{2ck\delta}.
\end{align*}
\]  

(30)

Using the coefficients into Eq.(5) and applying solution procedure of the trial solution algorithm, exact solutions to the modified EW equation are determined as bright and dark traveling wave solutions for when \( \delta > 0 \)

\[
\begin{align*}
u(x, t) &= \sqrt{-\frac{2c}{\delta k}} \operatorname{sech} \left[ \frac{1}{k\sqrt{\delta}} \left( k^\frac{x^\alpha}{\alpha} - c \frac{t^\alpha}{\alpha} \right) \right], \\
u(x, t) &= \sqrt{-\frac{2c}{\epsilon k}} \operatorname{csch} \left[ \frac{1}{k\sqrt{\delta}} \left( k^\frac{x^\alpha}{\alpha} - c \frac{t^\alpha}{\alpha} \right) \right]
\end{align*}
\]  

(31)

(32)

Solutions (31) and (32) purport singular periodic function solutions provided that \( \delta < 0 \)

\[
\begin{align*}
u(x, t) &= \sqrt{\frac{2c}{\delta k}} \sec \left[ \frac{1}{k\sqrt{-\delta}} \left( k^\frac{x^\alpha}{\alpha} - c \frac{t^\alpha}{\alpha} \right) \right], \\
u(x, t) &= \sqrt{-\frac{2c}{\epsilon k}} \csc \left[ \frac{1}{k\sqrt{-\delta}} \left( k^\frac{x^\alpha}{\alpha} - c \frac{t^\alpha}{\alpha} \right) \right]
\end{align*}
\]  

(33)

(34)

Figures 4-5 represent graphs of the solutions (31) and (33).

**Figure 4.** Solution Eq.(31) for \( c = k = \delta = 1, \epsilon = -2 \) and indicated \( \alpha \) values.
4. Conclusion

The trial solution algorithm with aid of CDS was implemented to find exact traveling wave solutions of the fractional biological population model, the fractional EW and the fractional modified EW equations in sense of conformable derivative. Using this algorithm, significant dark, bright and also singular periodic traveling wave solutions of these equations were obtained. All solutions were checked by Mathematica and some of them were plotted by Maple. Finding exact analytical solutions of the models may play a quite important role for explaining the physical phenomenon they characterize.

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