COPOLYMER AT SELECTIVE INTERFACES AND PINNING POTENTIALS: WEAK COUPLING LIMITS

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Abstract. We consider a simple random walk of length $N$, denoted by $(S_i)_{i \in \{1, \ldots, N\}}$, and we define $(w_i)_{i \geq 1}$ a sequence of centered i.i.d. random variables. For $K \in \mathbb{N}$ we define $((\gamma_i^K, \ldots, \gamma_i^K))_{i \geq 1}$ an i.i.d sequence of random vectors. We set $\beta \in \mathbb{R}$, $\lambda \geq 0$ and $h \geq 0$, and transform the measure on the set of random walk trajectories with the Hamiltonian $\lambda \sum_{i=1}^{N} (w_i + h) \text{sign}(S_i) + \beta \sum_{j=-K}^{K} \sum_{i=1}^{N} \gamma_i^j 1(S_i=j)$. This transformed path measure describes an hydrophobic(philic) copolymer interacting with a layer of width $2K$ around an interface between oil and water.

In the present article we prove the convergence in the limit of weak coupling (when $\lambda$, $h$ and $\beta$ tend to 0) of this discrete model towards its continuous counterpart. To that aim we further develop a technique of coarse graining introduced by Bolthausen and den Hollander in [6]. Our result shows, in particular, that the randomness of the pinning around the interface vanishes as the coupling becomes weaker.

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1. Introduction and main results

1.1. A discrete model of copolymer with adsorption. We consider a copolymer of $N$ monomers, and an interface separating two solvents (for example oil and water). The interface runs along the $x$-axis. The possible configurations of the polymer are given by the trajectories of a simple random walk $S = (S_i)_{i \geq 1}$ of length $N$ such that $S_0 = 0$ and $(S_i - S_{i-1})_{i \geq 1}$ is an i.i.d. sequence of Bernoulli trials satisfying $P(S_1 = \pm 1) = 1/2$. We let $\Lambda_i = \text{sign}(S_i)$ when $S_i \neq 0$ and $\Lambda_i = \Lambda_{i-1}$ otherwise. In size $N$ we take into account the interactions between the polymer and the medium by associating with each trajectory $S$ the Hamiltonian

$$H_{N,\beta,\lambda,h}^{w,\gamma}(S) = \lambda \sum_{i=1}^{N} (w_i + h) \Lambda_i + \beta \sum_{j=-K}^{K} \sum_{i=1}^{N} \gamma_i^j 1(S_i=j),$$

(1.1)

where $\lambda, h, \beta \in \mathbb{R}$, $w = (w_i)_{i \geq 1}$ is an i.i.d. sequence of bounded and symmetric random variables and $\gamma = ((\gamma_i^K, \ldots, \gamma_i^K))_{i \geq 1}$ is an i.i.d. sequence of random vectors ($w$ and $\gamma$ being independent). We stress that $w$ and $\gamma$ are defined under the probability $\mathbb{P}$ and that the variables $\gamma_1^K, \ldots, \gamma_K^K$ are independent but can have different laws. This Hamiltonian allows to define the polymer measure $P_{N,\beta,\lambda,h}^{w,\gamma}$ as

$$\frac{dP_{N,\beta,\lambda,h}^{w,\gamma}(S)}{d\mathbb{P}} = \frac{\exp(H_{N,\beta,\lambda,h}^{w,\gamma}(S))}{Z_{N,\beta,\lambda,h}}.$$\hspace{1cm}(1.2)

This discrete model has already been investigated in physics (see [14] or [21]) and mathematics (see [13]) in the case $K = 0$ and under the name copolymer with adsorption.
model is very natural, because it interpolates between two classes of models that have received a lot of attention in the literature:

- The pure pinning model, which is obtained by setting $\lambda = 0$. In this case only the interaction with the layer around the origin is activated. This model has been studied in the case $K = 0$, for instance in [3], [2], [15], [17].
- The random copolymer model, which is obtained by fixing $\beta = 0$. In this case only the interaction between the monomers and the two solvents is activated. It has been studied for instance in [6], [4], [5].

In general, these two models undergo a localization-delocalization phase transition, which results from an energy-entropy competition. In fact, in both cases, some trajectories are energetically favored with respect to the others. In the pinning case, it concerns the trajectories that remain close to the interface to touch the sites that carry a positive reward $\beta \gamma_j$ as often as possible. In the copolymer case, for every $i \in \{1, \ldots, N\}$ $w_i + h > 0$ (respectively $w_i + h < 0$) means that the $i$-th monomer is hydrophobic (resp. hydrophilic) and therefore, the energetically favored trajectories cross the interface often to put as many monomers as possible in their preferred solvent. In both cases, these favored trajectories are localized in the neighborhood of the interface. Therefore, they carry much less entropy than the trajectories which wander away far from the interface.

At this stage we introduce the free energy of the system that will be a key tool to define the localized and delocalized regimes. Thus, for $N \in \mathbb{N}$ and every disorder $(w, \gamma)$ we define $\Phi^{w,\gamma}_N$ as

$$\frac{1}{N} \log Z^{w,\gamma}_{N,\beta,\lambda,h} = \Phi^{w,\gamma}_N(\beta, \lambda, h).$$  

We recall that $(w, \gamma)$ are defined under the law $\mathbb{P}$ and we denote by $\Phi_N(\beta, \lambda, h)$ the quantity $\mathbb{E}(\Phi^{w,\gamma}_N(\beta, \lambda, h))$. Henceforth, we assume that $\mathbb{E}(\exp(\beta |\gamma_j|)) < \infty$ for every $\beta \in \mathbb{R}$ and $j \in \{-K, \ldots, K\}$.

**Proposition 1.1.** For every $\beta \in \mathbb{R}$, $\lambda \geq 0$, $h \geq 0$, there exists a non random real number, denoted by $\Phi(\beta, \lambda, h)$, such that $\mathbb{P}$ almost surely in $(w, \gamma)$

$$\lim_{N \to \infty} \Phi^{w,\gamma}_N(\beta, \lambda, h) = \Phi(\beta, \lambda, h).$$

This convergence occurs also in $L^1$, which entails the convergence of $\Phi_N(\beta, \lambda, h)$ to $\Phi(\beta, \lambda, h)$ as $N$ tends to $\infty$. The limit $\Phi(\beta, \lambda, h)$ is called the free energy of the model.

This proposition has been proven in different papers for quantities similar to $Z^{w,\gamma}_{N,\beta,\lambda,h}$ (see [10] or [11] for example). In our case, the difference comes from the fact that the disorder is spread out over a layer of finite width around the interface, but the proof remains essentially the same and is left to the reader. We also notice that $\Phi(\beta, \lambda, h)$ is continuous and separately convex.

1.2. The continuous model. We define in this section the continuous counterpart of the discrete model. In size $t$, the configurations of the polymer are given by the set of trajectories of the Brownian motion $(B_s)_{s \in [0,t]}$. The Hamiltonian associated with every trajectory $B$ is

$$\bar{H}^{R,t}_{\beta,\lambda,h}(B) = \lambda \int_0^t \Lambda(s)(dR_s + hds) + \beta L^0_t,$$  

where $L^0_t$ (or $L_t$ when there is no ambiguity) is the local time spent at 0 by $B$ between time 0 and time $t$. As in the discrete case we set $\lambda, h \geq 0$, $\beta \in \mathbb{R}$ and $\Lambda_s = \text{sign}(B_s)$. We denote by $\bar{\mathbb{P}}$ the law of $R = (R_s)_{s \geq 0}$, which is a standard Brownian motion, independent of $B$ such that $dR_s$ plays the role of $w_i$. 
As in the discrete case, we define the polymer measure of length $t$ by perturbing the law $\tilde{P}$ of the Brownian motion $B$ as follows
\[
\frac{d\tilde{P}^{R,t}_{\beta,\lambda,h}}{dP}(B) = \frac{\exp \left( \tilde{R}^{R,t}_{\beta,\lambda,h}(B) \right)}{\tilde{Z}^{R,t}_{\beta,\lambda,h}}. \tag{1.5}
\]
For every $t > 0$ and every disorder $R$ we introduce the free energy of the system of size $t$, denoted by $\tilde{\Phi}^R_t$, as
\[
\frac{1}{t} \log \tilde{Z}^{t,R}_{\beta,\lambda,h} = \tilde{\Phi}^R_t(\beta, \lambda, h). \tag{1.6}
\]
We also denote by $\tilde{\Phi}_t(\beta, \lambda, h)$ the quantity $\tilde{E}(\tilde{\Phi}^R_t(\beta, \lambda, h))$.

**Proposition 1.2.** For every $\beta \in \mathbb{R}$, $\lambda \geq 0$, $h \geq 0$, there exists a non random real number, denoted by $\Phi(\beta, \lambda, h)$, such that $\tilde{E}$ almost surely in $R$
\[
\lim_{t \to \infty} \tilde{\Phi}^R_t(\beta, \lambda, h) = \Phi(\beta, \lambda, h).
\]
As in the discrete case this convergence occurs also in $L^1$, and therefore $\Phi(\beta, \lambda, h)$, which is the free energy of the system, is the limit of $\Phi_t(\beta, \lambda, h)$ as $t$ tends to $\infty$.

A proof of Proposition 1.2 in the case $\beta = 0$ is available in [10]. This proof is adapted in [18] to cover the case $\beta \neq 0$. We also notice that $\Phi(\beta, \lambda, h)$ is continuous, separately convex and non-decreasing in $\beta$.

### 1.3. Localized and delocalized regimes.

In the discrete and the continuous model, the free energy gives us a tool to decide, for every $(\beta, \lambda, h)$, whether the system is localized or not. Observe that if we set $D_N = \{S : S_i > K \forall i \in \{K + 1, \ldots, N\}\}$ and use $P(D_N) = (1 + o(1))c/\sqrt{N}$ and the law of large numbers we have $\mathbb{P}$-a.s.
\[
\Phi(\beta, \lambda, h) \geq \lim_{N \to \infty} \frac{1}{N} \log E \left[ \exp \left( \lambda \sum_{i=1}^N (w_i + h) + \beta \sum_{i=1}^K \gamma_i \right) 1_{D_N} \right] \geq \lambda h. \tag{1.7}
\]
We will say that the polymer is delocalized when $\Phi(\beta, \lambda, h) = \lambda h$, because the trajectories in $D_N$ essentially determine the free energy, and localized when $\Phi(\beta, \lambda, h) > \lambda h$. The $(\beta, \lambda, h)$-space is divided into a localized phase, denoted by $\mathcal{L}$, and a delocalized phase, denoted by $\mathcal{D}$. It is now well understood (see in particular [11] and [13]) that such a free energy dichotomy does correspond to sharply different path behaviors.

In the continuous case, by considering the subset $\tilde{D}_t = \{B : B_s > 0 \forall s \in [1, t]\}$, a computation similar to (1.7) shows that $\tilde{\Phi}(\beta, \lambda, h) \geq \lambda h$. Therefore we can use the same dichotomy used in the discrete case to characterize $\mathcal{L}$ and $\mathcal{D}$.

**Critical curve.** For $\gamma$, $w$, $R$, $K$ and $\beta$ fixed, both for the discrete and continuous models there exists a critical curve $\lambda \mapsto h_c^D(\lambda) / h_c^C(\lambda)$ in the continuous case, which divides the $(\lambda, h)$-space into $\mathcal{L} = \{ (\lambda, h) : h < h_c^D(\lambda) \}$ and $\mathcal{D} = \{ (\lambda, h) : h \geq h_c^D(\lambda) \}$. In fact, by differentiating with respect to $h$ we obtain for every $N \geq 1$ and $t > 0$ that $\Phi_N(\beta, \lambda, h) - \lambda h$ and $\tilde{\Phi}_t(\beta, \lambda, h) - \lambda h$ are non increasing in $h$. Therefore $\Phi(\beta, \lambda, h) - \lambda h$ and $\tilde{\Phi}(\beta, \lambda, h) - \lambda h$ are also non increasing in $h$ and we can simply define $h_c^C(\lambda) = \inf\{h \geq 0 : \Phi(\beta, \lambda, h) - \lambda h = 0\}$ and $h_c^D(\lambda) = \inf\{h \geq 0 : \tilde{\Phi}(\beta, \lambda, h) - \lambda h = 0\}$.

The scaling property of the Brownian motion entails the equality $\tilde{\Phi}(a\beta, a\alpha, ah) = a^2 \Phi(\alpha, \beta, \lambda, h)$ for every $a \geq 0$. From this it follows that $h_c^{D,\alpha}(\lambda) = \lambda K_\beta^2$ with $K_\beta^2 = \inf\{h \geq 0 : \Phi(\beta, 1, h) - h = 0\}$. Notice that the quantity $K_\beta^2$ can be viewed as a critical curve in the $(\beta, h)$-plane for $\lambda = 1$. 

and is non-decreasing in $\beta$. Moreover, since $(\beta, h) \mapsto \Phi(\beta, 1, h) - h$ is convex, we prove easily that $\beta \mapsto K_\beta^c$ is convex.

**Remark 1.3.** Observe that for some values of $\lambda$ and $\beta$ the critical value $h_\beta^c(\lambda)$ can be infinite. In section 2.4 we give certain conditions under which this happens. We prove also, for the continuous model, that $K_\beta^c < \infty$ and $\tilde{h}_\beta^c(\lambda) < \infty$ for all $\beta \in \mathbb{R}$.

As a consequence, $\beta \mapsto K_\beta^c$ is continuous on $\mathbb{R}$ because it is convex and finite.

### 1.4. Discussion of the model and main results

Before studying more in depth the mathematical properties of the model, we recall that one of the physical situations that can be modelled by such systems is a polymer put in the neighborhood of an interface between two solvents (see [6]). Nevertheless, the models considered up to now do not take into account that such an interface has a finite width, that is to say, a small layer in which the two solvents are more or less mixed together. In this sense, the model developed here gives a more realistic image of an interface. Moreover, this model allows us to consider other physical situations. For instance, a case in which micro-emulsions of a third solvent are spread in a thin layer around the interface.

**Former results about the model.** We can roughly classify the results available for polymer models in two categories. On the one hand the results concerning the path behavior of the polymer. In fact, the separation between the localized and delocalized phases has an interpretation in terms of trajectories of the polymer. We refer to [1], [5], [11], [13], [22] for sharp results about the path behavior of the copolymer in $L$ and we refer to [12] for further results in $D$. On the other hand, the results concerning the free energy ($\Phi$): this problem arises only in $L$ since $\Phi$ is constant in $D$. In this last category, we can mention for instance the strong results about disordered pinning obtained recently in [2], in particular concerning the comparison between quenched and annealed critical curve at weak disorder.

**Regularity and scaling limit of the free energy.** For both the copolymer and the pinning model the free energy $\Phi$ is complicated inside $L$ and an important question is to figure out if another phase transition can occur inside $L$. The answer is partially given for the case $K = 0$ in [13], where a proof of the infinite differentiability of the free energy inside $L$ is given. This proof is based on a result, that was first given in [22] and [5] for the copolymer without adsorption and asserts that in $L$ the laws of the polymer’s excursions are exponentially tight. From this tightness, certain correlation inequalities are deduced that are sufficient to prove the infinite differentiability of the free energy inside $L$. Therefore, there is no other phase transition, at least of finite order, inside the localized phase.

The scaling limit of the discrete model is also a question that has been closely studied recently. In fact, in the case of the copolymer without adsorption ($\beta = 0$), a continuous model is introduced in [6] and it turns out to be the limit of the discrete model at high temperature, i.e., when the coupling parameters $\lambda$ and $h$ tend to 0. The results in [6] deal with the case of $w$ taking values $\pm 1$ and focus on the free energy, i.e.,

$$\lim_{a \to 0} \frac{1}{a^2} \Phi(0, a\lambda, ah) = \overline{\Phi}(0, \lambda, h). \quad (1.8)$$

This has been generalized in [12] to a large class of random variables $w$ and it is of interest in terms of universality of the Brownian limit as we are going to explain. Effectively, it shows that, when the coupling constants become weak, the Brownian models “attracts” any discrete model, regardless of its charge distribution. The proof is based on a coarse-graining method. In fact, for fixed parameters $(a\lambda, ah)$ the $N$ steps of the polymer are partitioned into blocks.
of finite and constant size \( L(a) \). It turns out that the characteristic size of the excursions for \( a \) small is of order \( 1/a^2 \). Then, by choosing \( L(a) \) of order \( 1/a^2 \), one can, block by block, approximate the free energy per steps of the discrete model by the one of the continuous model. When \( N \) tends to \( \infty \) the number of blocks tends to \( \infty \), but an ergodic property of the blocks allows to convert the approximation per block into the convergence \((1.8)\) involving the discrete and the continuous free energies in infinite size. In \([6]\) it is shown that the convergence occurs for the slope of the critical curve at the origin as well, i.e., \( \lim_{a \to 0} h^0_c(\lambda)/\lambda = K^0_c \).

**Main results.** In this article, we extend the scaling limit of the free energy given in \([6]\) to the model of a copolymer with adsorption introduced above. We aim particularly at understanding how the random pinning is modified at high temperature. Some zones in the interacting layer around the origin carry a large number of high rewards and play a particular role from the localization point of view. Indeed, the chain can target these zones when it goes back to the origin in order to maximize the rewards. Consequently, some zones favor the localization of the polymer more than others (see \([3]\) and \([17]\)). Here the question is whether the passage to a very weak coupling preserves the randomness of these rewards or leads to a complete averaging of the disorder.

We answer this question in Theorems \([1.4]\). In fact, by generalizing the limit \((1.8)\) to the case \( \beta \neq 0 \) we prove the convergence of the discrete model to the continuous model, when the parameters tend to 0 at appropriate speeds. The associated continuous model has a pinning term at the interface, given by the local time at 0 of the Brownian motion \( B \). Therefore, the randomness of the pinning term vanishes in the weak coupling limit.

In what follows, we will use the notation

\[
\Sigma = \sum_{j=-K}^{K} \mathbb{E}(\gamma^i_j).
\]

With the limit \((1.11)\) given in Theorem \([1.4]\) we prove that the partial derivatives of \( (\lambda, \beta) \mapsto h^0_c(\lambda) \) at the origin with respect to any vector \((1, \beta) \) \((\beta \in \mathbb{R})\) are only determined by the quantity \( \beta \Sigma \). This is also an important result in terms of universality of the continuous limit with respect to the disorder \( \gamma \). In fact, it shows that the shape of the critical surface close to the origin only depends on \( \Sigma \).

Before stating Theorem \([1.4]\) we recall that the variables \( (\gamma^i_j)_{j \in \{-K, \ldots, K\}} \) are allowed to have different laws, and we assume without loss of generality that \( \mathbb{E}(w^2_1) = 1 \).

**Theorem 1.4.** Let \( \beta \in \mathbb{R} \), \( \lambda > 0 \), \( h \geq 0 \), and \( \Sigma = \sum_{j=-K}^{K} \mathbb{E}(\gamma^i_j) \). Then

\[
\lim_{a \to 0} \frac{1}{a^2} \Phi(a \beta, a \lambda, a h) = \bar{\Phi}(\beta \Sigma, \lambda, h) \quad (1.10)
\]

and

\[
\lim_{\delta \to 0} \frac{h^\beta_c(\delta)}{\delta} = K^{\beta \Sigma}_c. \quad (1.11)
\]

We can derive from Theorem \([1.4]\) some relevant information concerning two particular cases of the model. In a first part we consider the influence of a deterministic pinning term on the critical curve of a copolymer without adsorption. In a second part we consider the case of an homopolymer with adsorption.

1.5. **Two particular cases.**
Influence of a depinning term on the critical curve. We consider here the copolymer model with a deterministic pinning term, i.e., $K = 0$, $\gamma_i^0 = 1$. Up to now the sensibility of the critical curve $\lambda \mapsto h^0_c(\lambda)$ to the presence of a pinning or depinning term is only very partially understood. Effectively, in the case $(\lambda, h) \in \mathcal{D}$, one can prove that choosing $\beta$ large enough is sufficient to obtain $h < h^0_c(\lambda)$, namely to pass from a delocalized regime to a localized regime. It can be done for instance by restricting the computation of the free energy to the random walk trajectories that come back to the origin every second steps. This leaves open the question whether a small $\beta$ can transform the critical curve.

![Fig. 1:](image)

Fig. 1:

The situation does not get easier when $(\lambda, h) \in \mathcal{L}$. In this case, it is useful to divide $\mathcal{L}$ into the two regions $\mathcal{L}_1$ and $\mathcal{L}_2$ separated by the curve $\lambda \mapsto h(\lambda) = (3/4 \lambda) \log E(\exp(4\lambda w_1/3))$ (see Fig 1). In fact, the localization strategy displayed in [4] to prove that $h(\lambda) \leq h^0(\lambda)$ is not sensitive to the presence of a depinning term. This strategy consists in coming back to the origin only to target rare stretches of negative $w_i$. These rare stretches are of length $l$, and the energetic contribution of each of them is of order $l$ whereas the depinning term contributes an energy $O(1)$. Thus, for $h < h(\lambda)$ (i.e., $(\lambda, h) \in \mathcal{L}_2$), we can not chose $\beta < 0$ such that $h \geq h^{\beta}_c(\lambda)$.

The case $(\lambda, h) \in \mathcal{L}_1$ is harder to investigate and we must recall that the strict inequality $h(\lambda) < h^{0}_c(\beta)$ is not rigorously proven for the moment. However, some numerical evidences in [7] shows that $\mathcal{L}_1$ is not an empty set and contrary to what we just said about $\mathcal{D}$ and $\mathcal{L}_2$, the influence of a depinning term in the region $\mathcal{L}_1$ is not understood at all. This leads to the following open problem: for $(\lambda, h) \in \mathcal{L}_1$, namely when $h(\lambda) \leq h < h^0_c(\lambda)$, can we find a large enough depinning term $\beta < 0$ that leads to a delocalization, i.e., $h \geq h^{\beta}_c(\lambda)$?

From this point of view, Theorem 1.4 is an improvement in the knowledge of the depinning influence in $\mathcal{L}_1$. Indeed, even if Theorem 1.4 does not directly answer this open problem, it connects it to another problem that may be easier to solve. Effectively, if one can prove, for example with an exact computation in the Brownian setting, that the continuous critical curve is sensitive to a depinning term, i.e., $K^\beta < K^0_c$ for certain $\beta < 0$, then Theorem 1.4 will entail that the same $\beta < 0$ satisfies $h^{\lambda}_{c}(\lambda) = K^{\beta}_{c} \lambda (1 + o(1))$. This would prove that $\mathcal{L}$ shrinks under the influence of a depinning term, at least for $\lambda$ small.

The homopolymer with adsorption. By fixing $\lambda = 1$ and $w_i \equiv 0$ for $i \geq 1$, we can model a homopolymer instead of a copolymer. Effectively, in this case the polymer only consists of hydrophobic monomers, and its Hamiltonian is given by

$$h \sum_{i=1}^{N} \Lambda_i + \beta \sum_{j=-K}^{K} \sum_{i=1}^{N} \gamma_i^j 1_{\{S_i=j\}}.$$  (1.12)
This type of model, which we call $h$-model, with a pinning term at the interface in competition with a repulsion effect (given here by $h \sum_{i=1}^{N} \Lambda_i$), has already been investigated in the literature (see [14], or [8]). It has been proven, for instance, that some properties of the $h$-model can be extended to the wetting model by letting the parameter $h$ tend to $\infty$ (see [18]).

The free energy of the $h$-model is denoted by $\Phi(\beta,h)$ and the localization condition is as before: $(\beta,h) \in \mathcal{L}$ when $\Phi(\beta,h) > h$ and $(\beta,h) \in \mathcal{D}$ when $\Phi(\beta,h) = h$. The critical curve of the $h$-model, which separates the $(h,\beta)$-plane into a localized and a delocalized phase, is denoted by $\kappa_c(\beta)$. This curve is increasing, convex and satisfies $\kappa_c(0) = 0$.

At this stage, we must recall that $w$ is assumed to satisfy $\mathbb{E}(w_1^2) = 1$ in Theorem 1.4. Therefore, this theorem can not be applied directly to the $h$-model. However, the proof of Theorem 1.4 that we give in Section 3 can easily be extended to the $h$-model, so that (1.10) can be restated in this case as

$$\lim_{a \to \infty} \frac{1}{a^2} \Phi(a\beta, a^2 h) = \tilde{\Phi}(\beta \Sigma, h),$$

where $\tilde{\Phi}(\beta \Sigma, h)$ denotes the free energy of the continuous limit of the $h$-model. The Hamiltonian of this continuous limit is given by

$$h \int_0^t \Lambda_s ds + \beta \Sigma L_t,$$

which is remarkable because the disorder disappears. Thus, we can compute explicitly some quantities related to $\tilde{\Phi}$. For instance, we state the following proposition for the case $\Sigma = 1$.

**Proposition 1.5.** Let $\beta \in \mathbb{R}$ and $h \geq 0$. Then,

$$\tilde{\Phi}(\beta,h) = h \quad \text{if} \quad h \geq \beta^2 \quad \text{and} \quad \tilde{\Phi}(\beta,h) = \frac{h^2}{2\beta^2} + \frac{\beta^2}{2} \quad \text{if} \quad h < \beta^2.$$

Since $h^2/(2\beta^2) + \beta^2/2 > h$ when $h < \beta^2$, we obtain the continuous critical curve, i.e., $\tilde{\kappa}_c(\beta) = \beta^2$ for $\Sigma = 1$ (see Fig. 2).

![Fig. 2](image)

Thanks to Proposition 1.5 we can give the asymptotic behavior, as $\beta$ tends to 0, of some quantities linked to the discrete model. For instance, for the general $h$-model, i.e. with $\Sigma$ not necessarily equal to 1, we can state the equivalent of (1.11), that is

$$\lim_{\beta \to 0} \frac{\kappa_c(\beta)}{\beta^2} = \Sigma^2.$$

Proving (1.15) requires to restate Theorem 2.3 (introduced below) for the $h$-model. This does not present any further difficulty, that is why we will not give the details here. Notice that the
limit \([1.15]\) is conform to our intuition that a stronger pinning along the interface enlarges the localized area and, consequently, increases the curvature of the critical curve at the origin. It is also confirmed by the bounds on the critical limit found in [18].

Still with Proposition \([1.5]\) we can differentiate \(\Phi(h, \beta)\) with respect to \(\beta\) and we find the asymptotic behavior of the reward average in the weak coupling limit. Indeed, if \(h < 2\beta^2\), then by convexity of \(\Phi_N\) in \(\beta\) we can state that, a.s. in \(\gamma\),

\[
\lim_{a \to 0} \lim_{N \to \infty} \frac{1}{\alpha_N} E_{N, a^2}^{\gamma \beta} \left[ \sum_{j=-K}^{K} \sum_{i=1}^{N} \gamma_j^i 1_{\{S_i = j\}} \right] = \beta - \frac{h^2}{2\beta^2}.
\]

The same derivative with respect to \(h\) gives an approximation, for \(a\) small, of the time proportion spent by the polymer under the interface, i.e.,

\[
\lim_{a \to 0} \lim_{N \to \infty} E_{N, a^2}^{\gamma \beta} \left[ \sum_{j=-K}^{K} \sum_{i=1}^{N} \Delta_i^j \right] = \beta^2 - h^2.
\]

1.6. **Organization of the paper.** In section 2 we will state and prove some technical results that turn out to be useful in the proof of Theorem 1.4. More precisely, in section 2.1 we consider the local time spent by the random walk in a finite layer around the interface after \(N\) steps. We rescale the later by \(\sqrt{N}\) and we prove its convergence, in terms of exponential moments, towards the local time spent at the origin by the Brownian motion between times 0 and 1. In section 2.2 we introduce the Theorem 2.3 from which Theorem 1.4 will be deduced.

Theorem 2.3 is essentially technical and consists in comparing the continuous free energy and the discrete free energy when the coupling is weak. Finally, in Section 2.4 we provide some conditions of finiteness for \(h_c\) and \(\tilde{h}_c\).

Section 3 is essentially dedicated to the proof of Theorems 1.4 and 2.3. Thus, in section 3.1 we explain how Theorem 1.4 is deduced from Theorem 2.3 whereas the rest of Section 3 is dedicated to the proof of Theorem 2.3.

Section 4 is an appendix dedicated to the exact computation of \(\Phi\) asserted in Proposition 1.5.

2. Preparation

2.1. **Technical Lemma.**

**Lemma 2.1.** For every \(K \in \mathbb{N}\) and every \((f_K, f_{-K+1}, \ldots, f_{-K})\) in \(\mathbb{R}^{2K+1}\) the following convergence occurs:

\[
\lim_{N \to \infty} E \left[ \exp \left( \frac{1}{\sqrt{N}} \sum_{j=-K}^{K} \sum_{i=1}^{N} f_j^i 1_{\{S_i = j\}} \right) \right] = E \left[ \exp \left( \left( \sum_{j=-K}^{K} f_j \right) L^0_1 \right) \right],
\]

where \(L^0_1\) is the local time in 0 of a Brownian motion \((B_s)_{s \geq 0}\) between 0 and 1.

**Proof.** First, we prove the following intermediate result. For every \(K \in \mathbb{N}\)

\[
\lim_{N \to \infty} \frac{1}{\sqrt{N}} \sum_{j=-K}^{K} f_j \sum_{i=1}^{N} 1_{\{S_i = j\}} \overset{\text{Law}}{=} \left( \sum_{j=-K}^{K} f_j \right) L^0_1.
\]

For simplicity, we only prove that \(\frac{1}{\sqrt{N}}(\sum_{i=1}^{N} 1_{\{S_i = 0\}}, \sum_{i=1}^{N} 1_{\{S_i = 1\}})\) converges in law to \((L^0_1, L^0_1)\) as \(N \uparrow \infty\). The proof for \(2K + 1\) levels is exactly the same. For this convergence in law, we use a result of [19], saying that we can build, on the same probability space \((W, \mathcal{A}, P)\), a simple random walk \((S_i)_{i \geq 0}\) and a Brownian motion \((B_s)_{s \geq 0}\) such that \(P\) almost surely

\[
\lim_{n \to \infty} \sup_{j \in (0,1)} \frac{1}{\sqrt{n}} |U^j_n - L^j_1| = 0
\]

(2.3)
with \( U_{n}^{j} = \sum_{i=1}^{n} 1_{\{S_{i}=j\}} \) and \( L_{n}^{x} \) the local time in \( x \) of \( B \) between 0 and \( n \). The equation (2.3) implies that \( \frac{1}{\sqrt{n}} \left( U_{n}^{0} - L_{n}^{x} \right) \) and \( \frac{1}{\sqrt{n}} \left( U_{n}^{1} - L_{n}^{x} \right) \) tend a.s. to 0 as \( n \uparrow \infty \). Therefore, the proof of (2.2) will be completed if we show that \( \frac{1}{\sqrt{n}} \left( L_{n}^{0}, L_{n}^{1} \right) \) converges in law to \( (L_{0}^{0}, L_{1}^{1}) \). By the scaling property of Brownian motion, we obtain that, for every \( n \geq 1 \), \( \frac{1}{\sqrt{n}} \left( L_{n}^{0}, L_{n}^{1} \right) \) has the same law as \( (L_{0}^{0}, L_{1}^{1})^{1/\sqrt{n}} \). Thus, since \( L_{n}^{x} \) is a.s. continuous in \( x = 0 \), we obtain immediately the a.s. convergence of \( (L_{n}^{0}, L_{n}^{1})^{1/\sqrt{n}} \) towards \( (L_{0}^{0}, L_{1}^{1}) \). This a.s. convergence implies the convergence in law and (2.2) is proven.

Since the function \( \exp(x) \) is continuous, (2.2) gives us the convergence in law of \( W_{N} = \exp \left( \frac{1}{\sqrt{N}} \sum_{j=-K}^{K} f_{j} \sum_{i=1}^{N} 1_{\{S_{i}=j\}} \right) \) to \( \left( \sum_{j=-K}^{K} f_{j} L_{0}^{j} \right) \) as \( N \uparrow \infty \). The uniform integrability of the sequence \( (W_{N})_{N \geq 1} \) will therefore be sufficient to complete the proof of Lemma 2.1.

We will obtain this uniform integrability if we can prove that \( \sup_{N \geq 1} E(W_{N}^{2}) < \infty \). By the Hölder inequality, it is sufficient to prove that for every \( b > 0 \) and every \( j \in \mathbb{Z} \) we have the inequality

\[
\sup_{N \geq 1} E \left( \exp \left( \frac{b}{\sqrt{N}} \sum_{i=1}^{N} 1_{\{S_{i}=j\}} \right) \right) < \infty. \tag{2.4}
\]

We let \( k_{N} = \sum_{i=1}^{N} 1_{\{S_{i}=0\}} \) and \( \tau_{j} = \inf \{ n \geq 1 : S_{n} = j \} \). Thus by the Markov property we can write

\[
E \left( \exp \left( \frac{b}{\sqrt{N}} \sum_{i=1}^{N} 1_{\{S_{i}=j\}} \right) \right) \leq E \left( \exp \left( \frac{b}{\sqrt{N}} 1_{\{\tau_{j} \leq N\}} \sum_{i=1}^{\tau_{j}} 1_{\{S_{i}=j\}} \right) \right) \leq E \left( e^{b(1+k_{N})} \right), \tag{2.5}
\]

and it just remains to prove that for every \( b > 0 \) the sequence \( (E(\exp(bk_{N}/\sqrt{N}))\}_{N \geq 0} \) is bounded from above independently of \( N \). To that aim, we notice that \( k_{N} \leq k_{2N} \leq N \) and write the obvious inequality

\[
E(\exp(bk_{2N}/\sqrt{N})) \leq \sum_{k=0}^{\lfloor \sqrt{N}/2 \rfloor} e^{2b(k+1)} P(k_{2N} \in [k\sqrt{2N}, (k+1)\sqrt{2N}]). \tag{2.6}
\]

With the help of (2.4) we can compute an upper bound of \( P(k_{2N} \in [k\sqrt{2N}, (k+1)\sqrt{2N}]) \).

Indeed, for every \( k \leq \lfloor \sqrt{N}/2 \rfloor \) we obtain

\[
P(k_{2N} \in [k\sqrt{2N}, (k+1)\sqrt{2N}]) \leq \sum_{j=[k\sqrt{2N}]}^{\max(\lfloor (k+1)\sqrt{2N} \rfloor, N)} P(S_{2N} = 0) \frac{(1-\frac{j}{2N})...(1-\frac{j+1}{2N})}{(1-\frac{k}{2N})...(1-\frac{k+1}{2N})}. \tag{2.7}
\]

The function \( x \mapsto \log(1-x) + x \) is decreasing on \([0,1]\) and consequently, for every \( j \in \{\lfloor k\sqrt{2N} \rfloor, \ldots, \max(\lfloor (k+1)\sqrt{2N} \rfloor, N)\} \), we have \( \log(1-j/N) - \log(1-j/2N) \leq -j/2N \). Therefore,

\[
\frac{(1-\frac{j}{2N})...(1-\frac{j+1}{2N})}{(1-\frac{k}{2N})...(1-\frac{k+1}{2N})} \leq \exp \left( \sum_{i=1}^{j} -\frac{j}{2N} \right) = \exp \left( -\frac{j(j-1)}{4N} \right) \leq \exp \left( -\frac{(k-1)^{2}}{2} \right).
\]

Moreover \( \lfloor (k+1)\sqrt{2N} \rfloor - \lfloor k\sqrt{2N} \rfloor \leq \sqrt{2N} + 1 \) and there exists a constant \( c > 0 \) such that \( P(S_{2N} = 0) \leq c/\sqrt{2N} \) for every \( N \geq 1 \). That is why, the equation (2.7) becomes

\[
P(k_{2N} \in [k\sqrt{2N}, (k+1)\sqrt{2N}]) \leq 2c \exp \left( -(k-1)^{2}/2 \right).
\]

This results allows us to rewrite (2.6) as

\[
E(\exp(bk_{2N}/\sqrt{N})) \leq \sum_{k=0}^{\infty} 2c e^{b(k+1)} e^{-\frac{(k-1)^{2}}{4}}.
\]

and the r.h.s. of this inequality is the sum of a convergent series. Therefore, the sequence \( (W_{N})_{N \geq 0} \) is uniformly integrable and the proof of Lemma 2.1 is completed. \( \Box \)
2.2. Excess free energies. We define the quantities \( \Psi_N(\beta, \lambda, h) = \Phi_N(\beta, \lambda, h) - \lambda h \) and \( \tilde{\Psi}_N(\beta, \lambda, h) = \tilde{\Phi}_N(\beta, \lambda, h) - \lambda h \). They converge respectively to \( \Psi(\beta, \lambda, h) = \Phi(\beta, \lambda, h) - \lambda h \) and \( \tilde{\Psi}(\beta, \lambda, h) = \tilde{\Phi}(\beta, \lambda, h) - \lambda h \), which are called excess free energies of the polymer. Therefore, to decide whether the polymer is localized or not, it suffices to compare \( \Psi \) or \( \tilde{\Psi} \) with 0. Moreover, since \( \sum_{i=1}^{N} (w_i + h) = hN + o(N) \) when \( N \uparrow \infty \), \( \mathbb{P}\)-a.s., we can subtract this quantity from the Hamiltonian (1.1) and associate \( \Psi_N \) with

\[
H_{N, \beta, \lambda, h}^{w_1} = -2\lambda \sum_{i=1}^{N} (w_i + h) \Delta_i + \beta \sum_{j=-K}^{K} \sum_{i=1}^{N} \gamma_i^j 1_{\{S_i = j\}},
\]

with \( \Delta_i = 1 \) if \( \Lambda_i = -1 \) and \( \Delta_i = 0 \) otherwise. Similarly, \( \tilde{\Psi}_N(\beta, \lambda, h) \) is associated with

\[
\tilde{H}_{t, \beta} = -2\lambda \int_{0}^{t} 1_{\{B_s < 0\}} (dR_s + hds) + \beta L_t^0,
\]

and \( \Psi \) and \( \tilde{\Psi} \) are continuous, separately convex and non-increasing in \( h \). Moreover \( \tilde{\Psi} \) is non-decreasing in \( \beta \).

2.3. Technical Theorem.

Remark 2.2. Stating Theorem 2.3 requires a slight modification of the Hamiltonian. In fact, let \( (\beta_1, \beta_2) \in \mathbb{R}^2 \) and define

\[
I_1 = \{ j \in \{-K, \ldots, K\} : \mathbb{E}(\gamma_1^j) > 0 \} \quad \text{and} \quad I_2 = \{ j \in \{-K, \ldots, K\} : \mathbb{E}(\gamma_1^j) < 0 \}.
\]

Then, if \( \mathbb{E}(\gamma_1^j) \neq 0 \) for every \( j \in \{-K, \ldots, K\} \), we define

\[
H_{N, \beta_1, \beta_2, \lambda, h}^{w_1} = \beta_1 \sum_{j \in I_1} \sum_{i=1}^{N} \gamma_i^j 1_{\{S_i = j\}} + \beta_2 \sum_{j \in I_2} \sum_{i=1}^{N} \gamma_i^j 1_{\{S_i = j\}} + \lambda \sum_{i=1}^{N} (w_i + h) \Delta_i.
\]

The associated free energy \( \Psi(\beta_1, \beta_2, \lambda, h) \) is defined as in Proposition 2.1 and satisfies \( \Psi(\beta, \lambda, h) = \Psi(\beta, \beta, \lambda, h) \). Thus, in what follows, we will use the notation \( \Psi(\beta_1, \beta_2, \lambda, h) \) if \( \beta_1 \neq \beta_2 \), otherwise we will use \( \Psi(\beta, \lambda, h) \). We let \( \Sigma = \Sigma_1 + \Sigma_2 \), with \( \Sigma_1 = \sum_{j \in I_1} \mathbb{E}(\gamma_1^j) \) and \( \Sigma_2 = \sum_{j \in I_2} \mathbb{E}(\gamma_1^j) \).

Theorem 2.3. Suppose \( \mathbb{E}(\gamma_1^j) \neq 0 \) for every \( j \in \{-K, \ldots, K\} \). If \( \beta_1 \neq 0 \), \( \beta_2 \neq 0 \), and \( (\mu_1, \mu_2) \in \mathbb{R}^2 \) satisfy

\[
\mu_1 > \beta_1 \Sigma_1 + \beta_2 \Sigma_2 > \mu_2,
\]

and \( \rho > 0 \), \( h > 0 \), \( h' \geq 0 \), \( \lambda > 0 \) satisfy \( (1 + \rho)h' < h \), then there exists \( a_0 > 0 \) such that for every \( a < a_0 \)

\[
\frac{1}{a^2} \Psi(a\beta_1, a\beta_2, a\lambda, ah) \leq (1 + \rho) \tilde{\Psi}(\mu_1, \lambda, h')
\]

\[
\tilde{\Psi}(\mu_2, \lambda, h) \leq \frac{1 + \rho}{a^2} \Psi(a\beta_1, a\beta_2, a\lambda, ah').
\]

2.4. Conditions of finiteness for \( h_c \) and \( \tilde{h}_c \).

One particular discrete model. We give here some more details about one particular case, namely \( K = 0 \) and \( \gamma_1^0 = 1 \). We let \( \zeta(\lambda) = \log(\mathbb{E}(\exp(\lambda w_1))) \). The Jensen’s inequality allows us to write

\[
\Psi(\beta, \lambda, h) \leq \lim_{N \to \infty} \frac{1}{N} \log \mathbb{E} \left[ \exp \left( \sum_{i=1}^{N} (\zeta(-2\lambda) - 2\lambda h) \Delta_i + \beta \sum_{i=1}^{N} 1_{\{S_i = 0\}} \right) \right].
\]
The limit in the right-hand side of (2.10) is computed in [17] and is equal to 0 for \( h \) large enough, as long as \( \beta < \log 2 \). This means that \( h_c^\beta(\lambda) < \infty \) for \( \beta < \log 2 \). In the same spirit we can let \( h \) tend to \( \infty \) and write the lower bound
\[
\Psi(\beta, \lambda, h) \geq \lim_{N \to \infty} \frac{1}{N} \log E \left[ \exp \left( \beta \sum_{i=1}^{N} I_{\{s_i=0\}} I_{\{s_i \geq 0 \text{ for all } i \in \{1, \ldots, N\}} \right) \right].
\] (2.11)
The r.h.s. of (2.11) is strictly positive for \( \beta > \log 2 \), and therefore \( h_c^\beta(\lambda) = \infty \) when \( \beta > \log 2 \).

The continuous case. In the continuous case we can assert the following general result.

**Proposition 2.4.** For every \( \beta \in \mathbb{R} \) we have \( K_c^\beta < \infty \). As a consequence, for every \( \beta \in \mathbb{R} \) and \( \lambda > 0 \) we have \( h_c^\beta(\lambda) < \infty \).

The proof of this proposition involves the discrete case mentioned above and the Theorem 2.3.

3. Proof of theorems and propositions

3.1. Proof of Proposition 2.4
In this section we assume that Theorem 2.3 is satisfied. Since \( \beta \to K_c^\beta \) is non decreasing in \( \beta \), the proof of Proposition 2.4 will be completed if we can show that \( K_c^\beta < \infty \) for all \( \beta > 0 \). Therefore, we let \( \beta > 0 \) and for any \( h \geq 0 \), we let
\[
\Psi(\beta, \lambda, h) = \lim_{N \to \infty} \frac{1}{N} \log E \left[ \exp \left( -2h \sum_{i=1}^{N} \Delta_i + \beta \sum_{i=1}^{N} I_{\{s_i=0\}} \right) \right].
\] (3.1)
It is proven in [17] that \( \Psi(\beta, h) > 0 \) when \( h < \kappa_c(\beta) \) and \( \Psi(\beta, h) = 0 \) when \( h \geq \kappa_c(\beta) \). The critical value is also computed in [17], i.e.,
\[
\kappa_c(\beta) = - \left( 1/4 \right) \log \left( 1 - 4 \left( 1 - \exp(-\beta) \right)^2 \right).
\] (3.2)

We recall the particular discrete case introduced in section 1.3, namely \( K = 0 \) and \( \gamma_1^0 = 1 \). We assume also that \( w_1 \) is a Bernouilli trial taking the values 1 and \(-1\) with probability 1/2. We let \( \beta > 0 \), \( h > 0 \) and we can apply the second inequality of Theorem 2.3 to this particular discrete model with the parameters \( \rho = 1/2 \), \( \mu_2 = \beta \), \( \beta_1 = \beta_2 = 2\beta \) and \( h' = h/2 \). Since \( \Sigma_1 = 1 \) and \( \Sigma_2 = 0 \) in this case we obtain for a small enough
\[
\tilde{\Psi}(\beta, 1, h) \leq \frac{1 + \frac{1}{2}}{a^2} \Psi(2\alpha, a, ah/2).
\] (3.3)

Moreover, the equation (2.10) gives \( \Psi(2\alpha, a, ah/2) \leq \Psi(2\alpha, -\zeta(-2a)/2 + a^2h/2) \). The equation (3.2) gives \( \kappa_c(2\alpha) = 4a^2\beta^2 + o(a^2) \) whereas \( -\zeta(-2a)/2 + a^2h/2 = a^2(h - 2)/2 + o(a^2) \). Therefore, by choosing \( h \) large enough and \( a \) small enough we have that the r.h.s. of (3.3) is equal to 0. This shows that \( K_c^\beta < \infty \) for all \( \beta > 0 \) and the proof of Proposition 2.4 is completed.

3.2. Proof of Theorem 1.4

Part 1: proof of the convergence (1.10). In this section, we prove that the convergence (1.10) is a consequence of Theorem 2.3. This proof is divided into 3 steps. In the first step, we show that (1.10) is satisfied when \( \lambda > 0 \), \( h > 0 \), \( \beta \neq 0 \) and every pinning reward \( \gamma_1^i \) has a non zero average. In the second step, we prove that the result can be extended to the case in which some \( \gamma_1^i \) have a zero average and consequently to the case \( \beta = 0 \). Finally, in the last step, we will consider the case \( h = 0 \). We recall that proving (1.10) with \( \Phi \) and \( \tilde{\Phi} \) or \( \Psi \) and \( \tilde{\Psi} \) is completely equivalent.
Step 1. First, we consider the case \( \lambda > 0, h > 0, \beta \neq 0 \) and \( \mathbb{E}(\gamma^j_1) \neq 0 \) for every \( j \in \{-K, \ldots, K\} \). We can apply the first inequality of Theorem 2.3 with the parameters \( \rho = 1/n, h' = h/(1 + 1/n)^2 \), \( \beta_1 = \beta_2 = \beta \) and \( \mu_1(v) = \beta \Sigma_1 + \beta \Sigma_2 + 1/v \) \( (n \text{ and } v \in \mathbb{N} - \{0\}) \). It gives, for every integers \( n \) and \( v \) strictly positive, that

\[
\limsup_{a \to 0} \frac{1}{a^2} \Psi(a \beta, a \lambda, ah) \leq (1 + \frac{1}{n}) \bar{\Psi}(\mu_1(v), \lambda, \frac{h}{1 + 1/n}).
\]

(3.4)

At this stage, we let successively \( n \) and \( v \) tend to \( \infty \), and, by continuity of \( \bar{\Psi} \) in \( h \) and \( \beta \) we obtain \( \limsup_{a \to 0} 1/a^2 \Psi(a \beta, a \lambda, ah) \leq \bar{\Psi}(\beta \Sigma, \lambda, h) \). The lower bound is proven with the second inequality of Theorem 2.3. Indeed, if we choose \( \mu_2(v) = \beta \Sigma_1 + \beta \Sigma_2 - 1/v \) and keep the other notations, we obtain

\[
\bar{\Psi}(\mu_2(v), \lambda, h(1 + \frac{1}{n})^2) \leq (1 + \frac{1}{n}) \liminf_{a \to 0} \frac{1}{a^2} \Psi(a \beta, a \lambda, ah).
\]

(3.5)

We let \( n \uparrow \infty \), and after, we let \( v \uparrow \infty \). In that way, we can conclude that \( \lim_{a \to 0} 1/a^2 \Psi(a \beta, a \lambda, ah) = \bar{\Psi}(\beta \Sigma, \lambda, h) \) which implies (1.10).

Step 2. We prove the convergence (1.10) when \( \lambda > 0, h > 0, \beta \neq 0 \) and there exists \( j \in \{-K, \ldots, K\} \) such that \( \mathbb{E}(\gamma^j_1) = 0 \). For that, we choose \( \mu > 0 \) and small enough, such that, \( \mathbb{E}(\gamma^j_1 + \mu) \neq 0 \) for every \( j \in \{-K, \ldots, K\} \). With these new variables we can use the result of Step 1 with \( \Sigma_\mu = \Sigma + (2K + 1)\mu \). Since the free energy \( \Psi_\mu \) associated with the variables \( \gamma^j_i + \mu \) is larger than \( \Psi \), we obtain

\[
\limsup_{a \to 0} \frac{1}{a^2} \Psi(a \beta, a \lambda, ah) \leq \lim_{a \to 0} \frac{1}{a^2} \Psi_\mu(a \beta, a \lambda, ah) = \bar{\Psi}(\beta(\Sigma + (2K + 1)\mu), \lambda, h).
\]

As \( \bar{\Psi} \) is continuous in \( \beta \), we let \( \mu \downarrow 0 \) and write \( \limsup_{a \to 0} 1/a^2 \Psi(a \beta, a \lambda, ah) \leq \bar{\Psi}(\beta \Sigma, \lambda, h) \). Thus, it suffices to do the same computation with \(-\mu < 0\), and we obtain the other inequality, i.e.,

\[
\liminf_{a \to 0} \frac{1}{a^2} \Psi(a \beta, a \lambda, ah) \geq \lim_{\mu \to 0} \bar{\Psi}(\beta(\Sigma - (2K + 1)\mu), \lambda, h) = \bar{\Psi}(\beta \Sigma, \lambda, h).
\]

Therefore, we can say that \( \lim_{a \to 0} \frac{1}{a^2} \Psi(a \beta, a \lambda, ah) = \bar{\Psi}(\beta \Sigma, \lambda, h) \).

As a consequence, (1.10) is satisfied when the variables \( \gamma^j_i \) are all equal to 0. Therefore, it is also satisfied when \( \beta = 0 \).

Step 3. It remains to prove (1.10) when \( h = 0 \). Since \( \Psi \) and \( \bar{\Psi} \) are non increasing in \( h \), (1.10) with \( \lambda > 0, h > 0 \) and \( \beta \in \mathbb{R} \) (proven in Step 2) implies

\[
\liminf_{a \to 0} \frac{1}{a^2} \Psi(a \beta, a \lambda, 0) \geq \liminf_{a \to 0} \frac{1}{a^2} \Psi(a \beta, a \lambda, ah) = \bar{\Psi}(\beta \Sigma, \lambda, h).
\]

We let \( h \downarrow 0 \) and by continuity of \( \bar{\Psi} \) in \( h \) we obtain

\[
\liminf_{a \to 0} \frac{1}{a^2} \Phi(a \beta, a \lambda, 0) = \liminf_{a \to 0} \frac{1}{a^2} \Psi(a \beta, a \lambda, 0) \geq \bar{\Psi}(\beta \Sigma, \lambda, 0) = \bar{\Phi}(\beta \Sigma, \lambda, 0).
\]

To prove the opposite inequality, we just notice that \( \Phi \) is non decreasing in \( h \). Effectively

\[
\frac{\partial \Phi_{N}}{\partial h} \big|_{(\beta, \lambda, 0)} = \mathbb{E} \left[ E_{N, \beta, \lambda, h} (\frac{\Lambda}{N} \sum_{i=1}^{N} \Lambda_i) \right],
\]

(3.6)

and by symmetry of the laws of the random walk and of the variables \( \{w_i\}_{i=1,2,\ldots} \), we can transform \( w_i \) in \(-w_i \), and \( (\Lambda_1, \ldots, \Lambda_N) \) in \((-\Lambda_1, \ldots, -\Lambda_N) \), without changing (3.6). It gives

\[
\frac{\partial \Phi_{N}}{\partial h} \big|_{(\beta, \lambda, 0)} = -\frac{\partial \Phi_{N}}{\partial h} \big|_{(\beta, \lambda, 0)}.
\]

Therefore, this derivative is equal to 0 and since \( \Phi_N \) is convex in \( h \), \( \Phi_N \) is non-decreasing in \( h \). Then, the convergence of \( \Phi_N \) to \( \Phi \) implies that \( \Phi \) is also non-decreasing in \( h \). The step 2
Part 2: proof of the convergence \((1.11)\). In this section, we assume that Theorem 2.3 is satisfied. We consider \(\beta \neq 0\). We prove the convergence \((1.11)\) by applying Theorem 2.3 with particular parameters. However we have to take into account the fact that there may exist \(j \in \{-K, \ldots, K\}\) such that \(E(\gamma_i^j) = 0\). Therefore, as we did in Step 2 of the proof of \((1.10)\) we consider \(\mu > 0\) small enough, such that, \(E(\gamma_i^j + \mu) \neq 0\) and \(E(\gamma_i^j - \mu) \neq 0\) for every \(j \in \{-K, \ldots, K\}\). Then, we use the result of Theorem 2.3 with the variables \(\gamma_i^j + \mu\) for \(i \geq 1\) and \(j \in \{-K, \ldots, K\}\). We denote by \(\Psi_\mu\) the associated excess free energy and we let \(\Sigma_\mu = \Sigma + (2K+1)\mu\). Then we denote \(\rho = 1/n, \mu_1 = \beta\Sigma_\mu + 1/n, h = (1+2/n)K_c^\mu, h' = K_c^\mu, \beta_1 = \beta_2 = \beta,\) and \(\lambda = 1\). For a small enough, the first inequality of Theorem 2.3 gives

\[
\frac{1}{\alpha^2} \Psi_\mu(\alpha\beta, a, a(1 + \frac{2}{n})K_c^\beta\Sigma_\mu + \frac{1}{n}) \leq (1 + \frac{1}{n})\Psi(\beta\Sigma_\mu + \frac{1}{n}, 1, K_c^\beta\Sigma_\mu + \frac{1}{n}).
\]

(3.7)

By definition of \(K_c^\mu\), the right hand side of \((3.7)\) is equal to zero. Moreover \(\Psi \leq \Psi_\mu\) for \(\mu > 0\). Therefore, we have the inequality \(\limsup_{a \to \infty} h_c^\alpha(a)/a \leq (1 + 2/n)K_c^\beta\Sigma_\mu + 1/n\). Then, we let \(n \uparrow \infty\) and \(\mu \downarrow 0\) and since \(x \to K_c^\mu\) is continuous in \(\beta\Sigma\), the former inequality becomes \(\limsup_{a \to \infty} h_c^\alpha(a)/a \leq K_c^\beta\Sigma\). It remains to prove the opposite inequality. To that aim, we apply the second inequality of Theorem 2.3 with the variables \(\gamma_i^j - \mu\) for \(i \geq 1\) and \(j \in \{-K, \ldots, K\}\) and with the parameters \(\rho = 1/n, \mu_2 = \beta\Sigma_\mu - 1/n, h = K_c^{\mu_2} - 1/n, h' = (K_c^{\mu_2} - 2/n)/(1 + 1/n), \beta_1 = \beta_2 = \beta,\) and \(\lambda = 1\). For a small enough we obtain

\[
\Phi(\beta\Sigma_\mu - \frac{1}{n}, 1, K_c^\beta\Sigma_\mu - \frac{1}{n}) \leq \frac{1 + 1/\alpha^2 n}{1.5}\Psi_\mu(\alpha\beta, a, a(1 + 1/n K_c^\beta\Sigma_\mu - \frac{1}{n})).
\]

(3.8)

Therefore, since the l.h.s. of \((3.8)\) is strictly positive and since \(\psi \geq \psi_\mu\) for all \(\mu > 0\), we can write the inequality \(\liminf_{a \to \infty} h_c^\alpha(a)/a \geq (K_c^\beta\Sigma_\mu - 1/n - 2/n)/(1 + 1/n)\). Finally, by continuity of \(x \to K_c^\mu\) around \(\beta\Sigma\), we let \(n \uparrow \infty\) and \(\mu \downarrow 0\) and it completes the proof of \((1.11)\).

As in the step 2 of the proof of \((1.10)\), the case \(\gamma_i^j = 0\) for all \(i \geq 1\) and all \(j \in \{-K, \ldots, K\}\) gives us directly \((1.11)\) in the case \(\beta = 0\).

3.3. Proof of Theorem 2.3.

Remark 3.1. We will only consider in this proof the case \(\beta_1 > 0\) and \(\beta_2 > 0\). Indeed, if for instance \(\beta_1 < 0\), we transform all the variables \((\gamma_i^j)_{i \geq 1, j \in I_1}\) into \((-\gamma_i^j)_{i \geq 1, j \in I_1}\) and we take \(-\beta_1\) instead of \(\beta_1\).

First, we define a relation (previously introduced in \([5]\)), which is very useful to carry out the proof.

Definition 3.2. let \(f_{t,\varepsilon}(a, h, \beta_1, \beta_2)\) and \(g_{t,\varepsilon}(a, h, \beta_1, \beta_2)\) be real-valued functions. The relation \(f << g\) occurs if for every \(\beta_3 > \beta_1, \beta_2 > \beta_4, \rho > 0,\) and \(h > h' \geq 0\) satisfying \((1 + \rho)h' < h\), there exists \(\delta_0\) such that for \(0 < \delta < \delta_0\) there exists \(\varepsilon_0(\delta)\) such that for \(0 < \varepsilon < \varepsilon_0\) there exists \(a_0(\varepsilon, \delta)\) satisfying

\[
\limsup_{t \to \infty} f_{t,\varepsilon}(a, h, \beta_1, \beta_2) - (1 + \rho)g_{t,\varepsilon}(a, h, \beta_3, \beta_4) \leq 0
\]

for \(0 < a < a_0\) \((3.9)\)
In this proof we consider some functions of the form
\[ F_{t,\epsilon,\delta}(a, h, \beta_1, \beta_2) = E \left[ \frac{1}{t} \log E \left( \exp(aH_{t,\epsilon,\delta}(a, h, \beta_1, \beta_2)) \right) \right], \]
and we denote
- \( F^1_{t,\epsilon,\delta}(a, h, \beta_1, \beta_2) = \frac{1}{a} \Psi_{t/a^2}(a\beta_1, a\beta_2, a, ah) \)
- \( F^7_{t,\epsilon,\delta}(a, h, \beta_1, \beta_2) = \tilde{\Psi}_t(\beta_1 \Sigma_1 + \beta_2 \Sigma_2, 1, h). \)

The proof of (2.9) will consist in showing that \( F^1 \ll F^7 \) and \( F^7 \ll F^1 \) (denoted by \( F^1 \sim F^7 \)). To that aim, we will create the intermediate functions \( F_2, \ldots, F_6 \) associated with slight modifications of the Hamiltonian to transform, step by step, the discrete Hamiltonian into the continuous one. As the relation \( \sim \) is transitive, we will prove at every step that \( F^i \sim F^{i+1} \), to conclude finally that \( F^1 \sim F^7 \).

### 3.4. Scheme of the proof.
To show that \( F^i \ll F^{i+1} \) we let \( H^i = H^I + H^{II} \) and, by the Hölder inequality, we can bound \( F^i \) from above as follows
\[ F^i_{t,\epsilon,\delta}(a, h, \beta) \leq \frac{1}{(1+\rho)} E \left[ \log E \left( \exp(a(1+\rho)H^I) \right) \right] + \frac{1}{(1+\rho-1)^2} E \left[ \log E \left( \exp(a(1+\rho-1)H^{II}) \right) \right]. \]
Thus, if we choose \( H^I = H^{I+1} \)
\[ t(1+\rho)^a, \epsilon(1+\rho)^2, \delta(1+\rho)^2(a(1+\rho), h', \beta_3, \beta_4), \]
we obtain
\[ F^i_{t,\epsilon,\delta}(a, h, \beta_1, \beta_2) \leq (1+\rho)^2 \frac{1}{(1+\rho)^2} E \left[ \log E \left( \exp(a(1+\rho)H^I) \right) \right]. \]
Then, it suffices to prove that \( \limsup_{t \to \infty} 1/t \log E E \left( \exp(a(1+\rho)H^I) \right) \leq 0 \) for \( a, \epsilon \) and \( \delta \) small enough.

We can assume without problem that \( \epsilon/a^2, \delta/\epsilon \) and \( t/\delta \) are all integers. In this way we avoid the brackets in the formulas.

### 3.5. Step 1.
The first Hamiltonian that we consider in this proof is given by
\[ H^{(1)}_{t,\epsilon,\delta}(a, h, \beta_1, \beta_2) = -2 \sum_{i=1}^{t/a^2} \Delta_i(w_i + ah) + \beta_1 \sum_{j \in I_1} \gamma_j^2 1_{\{S_i=j\}} + \beta_2 \sum_{j \in I_2} \gamma_j^2 1_{\{S_i=j\}}, \]
with \( \Delta_i = 1 \) if \( \Lambda_i = -1 \) and \( \Delta_i = 0 \) if \( \Lambda_i = 1 \).

We define some notation to build the intermediate Hamiltonians (see Fig. 3).
- \( \sigma_0 = 0, \quad i_0 = 0 \) and \( i_{k+1} = \inf \{ n : \sigma_k \epsilon/a^2 + \delta/\epsilon \geq S_n \} \)
- \( m = \inf \{ k \geq 1 : i_k > t/a^2 \} \)
- \( i_k = i_k^w \) for \( k < m \) and \( i_m = t/a^2 \)
- \( \sigma_{k+1} = \inf \{ n \geq 0 : i_{k+1} \in [(n-1)\epsilon/a^2, n\epsilon/a^2] \} \)
- \( \sigma_k = (\sigma_{k-1} - \delta/a^2, \sigma_k \epsilon/a^2) \cap [0, t/a^2], \quad s_{k+1} = \text{sign} i_{k+1} - 1. \)

Fig. 3:
We define the first transformation of the Hamiltonian

\[
H_{t,a}^{(2)}(a,h,\beta_1,\beta_2) = -2\sum_{k=1}^{m} s_k \left[ \sum_{i \in \mathcal{I}_k} w_i + ah |T_k| \right] + \sum_{j=1}^{t/a^2} \beta_1 \sum_{i \in I_1} \gamma_i^j \mathbf{1}_{\{s_i=j\}} + \beta_2 \sum_{j=1}^{t/a^2} \gamma_i^j \mathbf{1}_{\{s_i=j\}}
\]

and we want to show that \( F_1 << F_2 \). To that aim, we denote

\[
H^{II} = -2\sum_{i=1}^{t/a^2} \Delta_i (w_i + ah) + 2\sum_{k=1}^{m} s_k \left( \sum_{i \in \mathcal{I}_k} w_i + a(1 + \rho)h |T_k| \right) + (\beta_1 - \beta_3) \sum_{j=1}^{t/a^2} \gamma_i^j \mathbf{1}_{\{s_i=j\}} + (\beta_2 - \beta_4) \sum_{j=1}^{t/a^2} \gamma_i^j \mathbf{1}_{\{s_i=j\}},
\]  

(3.10)

and it remains to prove that \( \limsup_{t \to \infty} \frac{1}{t} \log E(\exp(a(1 + \rho^{-1})H^{II})) \leq 0 \). We integrate over the disorder \( \gamma \) and the third and forth terms of the right hand side of (3.10) give some contributions of the form

\[
\exp(\sum_{j \in I_2} \sum_{i=1}^{t/a^2} \log E \left[ \exp((\beta_2 - \beta_2 + \rho) a(1 + \rho^{-1}) \gamma_i^j) \right] \mathbf{1}_{\{s_i=j\}}) \quad \text{for} \quad p = 1 \quad \text{and} \quad p = 2.
\]

Since \( E(\exp(\lambda |\gamma_i^j|)) < \infty \) for every \( j \in \{-K, \ldots, K\} \) and \( \lambda > 0 \), we can write a first order Taylor expansion of \( \log E(\exp(Aa \gamma_i^j)) \) when \( a \downarrow 0 \). It gives

\[
\log E \left( \exp(Aa \gamma_i^j) \right) = AaE(\gamma_i^j) + o(a).
\]

(3.11)

We assume in this proof that \( E(\gamma_i^j) \neq 0 \) for every \( j \in \{-K, \ldots, K\} \) (see the assumptions of Theorem 2.3) and therefore \( \{-K, \ldots, K\} = I_1 \cup I_2 \). For every \( i \in I_1 \), \( E(\gamma_i^j) > 0 \), and \( \beta_1 - \beta_3 < 0 \). Thus, by (3.11), we obtain, for a small enough, that

\[
\sum_{j \in I_2} \sum_{i=1}^{t/a^2} \log E \left( (\beta_1 - \beta_3) a(1 + \rho^{-1}) \gamma_i^j \right) \mathbf{1}_{\{s_i=j\}} \leq 0.
\]

(3.12)

The sum over \( I_2 \) satisfies the same inequality for a small enough because \( \beta_2 - \beta_4 > 0 \) and \( E(\gamma_i^j) < 0 \) when \( j \in I_2 \). Therefore, we can remove the third and forth terms of \( H^{II} \) in (3.10) and by rewriting \( \sum_{i=1}^{t/a^2} \) as \( \sum_{k=1}^{m} \sum_{i \in \mathcal{I}_k} \), we can rewrite \( H^{II} \) as

\[
H^{II} = -2\sum_{k=1}^{m} \sum_{i \in \mathcal{I}_k} w_i (\Delta_i - s_k) - 2a(1 + \rho)h \sum_{k=1}^{m} \sum_{i \in \mathcal{I}_k} (\Delta_i - s_k) - 2a(h - (1 + \rho)h') \sum_{k=1}^{m} \sum_{i \in \mathcal{I}_k} \Delta_i
\]

Thus, we integrate over the disorder \( w \) which is independent of the random walk. But, since \( E(w_i) = 0 \) and \( E(\exp(\lambda |w_i|)) < \infty \) for every \( \lambda > 0 \), a second order expansion gives that for every \( c \in \mathbb{R} \) there exists \( A > 0 \) such that for a small enough

\[
\log E \left( \exp(c a w_i (\Delta_i - s_k)) \right) \leq Aa^2 |\Delta_i - s_k|.
\]

(3.13)

Finally, we have to prove, for \( A > 0 \) and \( B > 0 \) and for \( \delta, \varepsilon, \) a small in the sense of Definition 3.2, that

\[
\limsup_{t \to \infty} \frac{1}{t} \log E \left[ \exp \left( Aa^2 \sum_{k=1}^{m} \sum_{i \in \mathcal{I}_k} \left| s_k - \Delta_i \right| - Ba^2 \sum_{i=1}^{t/a^2} \Delta_i \right) \right] \leq 0.
\]

(3.14)

This is explicitly proven in [6] (page 1355), and completes the Step 1 because the proof of \( F_2 << F_1 \) is very similar and consists essentially in showing (3.14).
3.6. **Step 2.** In this step we aim at transforming the disorder \( w \) into a sequence \( (\hat{w}_i)_{i \geq 1} \) of independent random variables of law \( \mathcal{N}_{0,1} \). To that aim, we use a coupling method developed in \([20]\) to define on the same probability space and for every \( j \in \mathbb{N} \setminus \{0\} \) the variables \( (w_i)_{i \in [(j-1)\varepsilon/a^2+1, j\varepsilon/a^2]} \) and some independent variables of law \( \mathcal{N}_{0,1} \), denoted by \( (\hat{w}_i)_{i \in [(j-1)\varepsilon/a^2+1, j\varepsilon/a^2]} \), such that for every \( p > 2 \) and \( x > 0 \)

\[
\mathbb{P}\left( \left| \sum_{i=(j-1)\varepsilon/a^2+1}^{j\varepsilon/a^2} w_i - \hat{w}_i \right| \geq x \right) \leq \frac{(Ap)^p \varepsilon}{x^p} \mathbb{E}(w_i^p),
\]

(3.15)

These constructions are made independently on all blocks \( \{(j-1)\varepsilon/a^2+1, \ldots, j\varepsilon/a^2\} \). Thus, we can form the third Hamiltonian as follow

\[
H_{t,\varepsilon,\delta}^{(3)}(a,h,\beta_1,\beta_2) = -2 \sum_{k=1}^{m} s_k \left[ \sum_{i \in T_k} \hat{w}_i + ah |T_k| \right] + \sum_{j=1}^{t/\varepsilon^2} \beta_1 \sum_{i \in T_1} \gamma_i^j 1_{\{S_i=j\}} + \beta_2 \sum_{j \in T_2} \gamma_i^j 1_{\{S_i=j\}}.
\]

To prove that \( F^2 \ll F^3 \), we need the Hamiltonian \( H^I \). It takes the value

\[
H^I = H_{t,\varepsilon,\delta}^{(2)}(a,h,\beta_1,\beta_2) - H_{t(1+\rho)^2,\varepsilon(1+\rho)^2,\delta(1+\rho)^2}^{(3)}(a(1+\rho), h', \beta_3, \beta_4).
\]

(3.16)

As in Step 1 (see (3.12)) we delete the two pinning terms in \( H^I \) and it is sufficient to consider

\[
H^I = -2 \sum_{k=1}^{m} s_k \sum_{i \in T_k} (w_i - \hat{w}_i) + 2a \sum_{k=1}^{m} s_k (h - (1+\rho)h') |T_k|
\]

\[
\leq 2 \sum_{k=1}^{m} s_k \left( \sum_{j=\sigma_{k-1}+1}^{\sigma_k} \left[ \sum_{i=j\varepsilon/a^2+1}^{(j+1)\varepsilon/a^2} w_i - \hat{w}_i \right] - (h - (1+\rho)h') \varepsilon \right).
\]

We want to prove that \( \limsup_{t \to \infty} 1/t \log \mathbb{E} \left( \exp \left( (a(1+\rho^{-1})H^I) \right) \right) \leq 0 \). By independence of \( (w, \hat{w}) \) on each blocks \( \{(j-1)\varepsilon/a^2+1, \ldots, j\varepsilon/a^2\} \), it suffices to show that for every \( C > 0 \) and \( B > 0 \)

\[
\mathbb{E} \left[ \exp \left( Ca \sum_{i=1}^{\varepsilon/a^2} w_i - \hat{w}_i \right) - B \varepsilon \right] \leq 1 \text{ for } \varepsilon, \text{ and a small enough.}
\]

(3.17)

We prove this point as follows,

\[
\mathbb{E} \left[ \exp \left( Ca \sum_{i=1}^{\varepsilon/a^2} w_i - \hat{w}_i \right) \right] \leq \sum_{k=N}^{+\infty} e^{Ca(k+1)\sqrt{\varepsilon}} \mathbb{P} \left( \left| \sum_{i=1}^{\varepsilon/a^2} w_i - \hat{w}_i \right| \geq k \frac{\varepsilon}{\sqrt{\varepsilon}} \right) + e^{CN\varepsilon \sqrt{\varepsilon}}.
\]

(3.18)

By using (3.15) and the fact that \( \mathbb{E}(w_i^k) \leq R^k \), we obtain that for every \( j \) and \( k \geq 1 \)

\[
\mathbb{P} \left( \left| \sum_{i=(j-1)\varepsilon/a^2+1}^{j\varepsilon/a^2} w_i - \hat{w}_i \right| \geq k \frac{\varepsilon}{\sqrt{\varepsilon}} \right) \leq \frac{(AR\sqrt{\varepsilon})^k}{\varepsilon^{k-1} a^{2k}}.
\]

(3.19)

We consider (3.18) with \( N = 5 \), and we use (3.19) to obtain

\[
\mathbb{E} \left[ \exp \left( Ca \sum_{i=1}^{\varepsilon/a^2} w_i - \hat{w}_i \right) \right] \leq e^{5C\sqrt{\varepsilon} + \varepsilon} \frac{e^{C\varepsilon \sqrt{\varepsilon}}}{a^2} \sum_{k=5}^{+\infty} \left( e^{C\varepsilon \sqrt{\varepsilon}} AR\sqrt{\varepsilon} \right)^k.
\]

Therefore, for \( \varepsilon > 0 \) fixed, there exists \( K(\varepsilon, a) > 0 \) which tends to zero when \( a \) tends to zero, and satisfies

\[
\mathbb{E} \left[ \exp \left( Ca \sum_{i=1}^{\varepsilon/a^2} w_i - \hat{w}_i \right) \right] \leq (1 + K(\varepsilon, a)) e^{5C\varepsilon \sqrt{\varepsilon}}.
\]

This implies (3.17), and completes the Step 2 because the proof of \( F^3 \ll F^2 \) is exactly the same.
3.7. Step 3. In this step, we make a link between the discrete and the continuous models. For that, we take into account the number of returns to the origin of the random walk, and the local time of the Brownian motion. We define, independently of the random walk, an i.i.d. sequence \( (\hat{t}_k^j)_{k \geq 0} \) of local times spent in 0 by a Brownian motion between 0 and 1. The law of this sequence is denoted by \( \chi \). Then, we build the new Hamiltonian

\[
H^{(4)}_{t, \varepsilon, \delta}(a, h, \beta_1, \beta_2) = -2 \sum_{k=1}^{m} s_k \left( \sum_{i \in I_k} \hat{w}_{i} + ah|T_k| \right) + \frac{\beta_1 \Sigma_1 + \beta_2 \Sigma_2}{a} \sqrt{\delta} \sum_{k=1}^{m} \hat{t}_k^j.
\]

(3.20)

As usual, to prove that \( F_3 \ll F_1 \), we consider \( H^{II} \), in which we can already remove the term \(-2a(h - (1 + \rho)h') \sum_{k=1}^{m} |T_k| \) because it is negative. Therefore we can bound \( H^{II} \) from above as follows

\[
H^{II} \leq \beta_1 \sum_{k=1}^{m} \sum_{j \in I_1} \sum_{i = i_{k-1} + 1}^{i_k} \gamma_i^j 1_{\{S_i = j\}} - \frac{\beta_3 \Sigma_1 \sqrt{\delta}}{a} \sum_{k=1}^{m} \hat{t}_k^j
\]

\[
+ \beta_2 \sum_{k=1}^{m} \sum_{j \in I_2} \sum_{i = i_{k-1} + 1}^{i_k} \gamma_i^j 1_{\{S_i = j\}} - \frac{\beta_4 \Sigma_2 \sqrt{\delta}}{a} \sum_{k=1}^{m} \hat{t}_k^j.
\]

To prove that \( \limsup_{t \to \infty} \frac{1}{t} \log E_{P \otimes \chi} (\exp(a(1 + \rho^{-1})H^{II})) \leq 0 \), we first apply the Hölder inequality (with the coefficients \( p = q = 2 \)), and then we integrate over the disorder \( \gamma \). Therefore, it remains to prove for \( x = 1 \) and 2 that

\[
\limsup_{t \to \infty} \frac{1}{t} \log E_{P \otimes \chi} \left[ \exp \left( \sum_{k=1}^{m} \sum_{j \in I_1} \sum_{i = i_{k-1} + 1}^{i_k} \log E \left( \exp \left( 2a \beta_x (1 + \rho^{-1}) \gamma_i^j \right) 1_{\{S_i = j\}} - 2 \beta_x + 2 \sqrt{\delta} \Sigma_x (1 + \rho^{-1}) t_i^j \right) \right) \right] \leq 0.
\]

(3.21)

For simplicity, in what follows we will use \( E \) instead of \( E_{P \otimes \chi} \). We begin with the proof of (3.21) in the case \( x = 1 \). To that aim, we recall (3.11), that gives

\[
\log E \left( \exp \left( 2a \beta_x (1 + \rho^{-1}) \gamma_i^j \right) \right) = 2 \mathbb{E} (\gamma_i^j) a \beta_x (1 + \rho^{-1}) + o(a).
\]

(3.22)

Therefore, we can choose \( \beta'' \) such that \( \beta_1 < \beta'' < \beta_3 \) and \( a \) small enough to obtain for every \( j \in I_1 \) the inequality \( \log E(\exp(2a \beta_1 (1 + \rho^{-1}) \gamma_i^j)) \leq 2a \beta'' (1 + \rho^{-1}) \mathbb{E}(\gamma_i^j) \). Finally, since \( \mathbb{E}(\gamma_i^j) > 0 \) for every \( j \), we can replace \( (i_k)_{k \in \{1, \ldots, m\}} \) by \( (i_k^l)_{k \in \{1, \ldots, m\}} \) (see the notation at the beginning of Step 1), and it remains to prove that for \( B > A > 0 \)

\[
\limsup_{t \to \infty} \frac{1}{t} \log E \left[ \exp \left( \sum_{k=1}^{m} \left( A \sum_{j \in I_1} \mathbb{E}(\gamma_i^j) \sum_{i = i_{k-1} + 1}^{i_k} 1_{\{S_i = j\}} - B \sqrt{\delta} \Sigma_1 t_i^j \right) \right) \right] \leq 0.
\]

(3.23)

For simplicity, we will use the notation \( \mathbb{E}(\gamma_i^j) = f(j) \), and consequently \( \Sigma_1 = \sum_{j \in I_1} f(j) \). For every \( N \), we build a new filtration, i.e., \( F_N = \sigma(A_{X_{N}} \cup \sigma(l_0^N, \ldots, l_N^N)) \) with \( A_k = \sigma(X_1, \ldots, X_k) \) and the random variable

\[
M_N = \frac{\mathbb{E} \left( \sum_{k=1}^{N} A \sum_{j \in I_1} f(j) 1_{\{u \in \{i_{k}^N - 1 + 1, i_k^N\} : S_u = j\}} - B \sqrt{\delta} \Sigma_1 \sum_{k=1}^{N} l_k^j \right)}{\mu^N E(\exp(A \sum_{j \in I_1} f(j) 1_{\{i \in \{0, \frac{\delta}{2a} \} : S_i = j\}} - B \sqrt{\delta} \Sigma_1 l_i^j))^N}
\]

where \( \mu \) is a constant > 1. We will precise the value of \( \mu \) later, to make sure that \( M_N \) is a positive super-martingale with respect to \( (F_N)_{N \geq 0} \). To that aim, for every \( j \in \{-K, \ldots, K\} \) we introduce \( P_{N}^j = 1_{\{u \in \{i_{N}^N - 1 + 1, i_k^N\} : S_u = j\}} \), and we define the new filtration \( (G_N)_{N \geq 1} \)
by \( G_{N-1} = \sigma(F_{N-1} \cup \sigma(X_{i_{N-1}^v}^v, i_{N-1}^v + (\delta + \epsilon)/a^2, l_{1}^N)) \). Then, we consider the quantity \( E(M_N|F_{N-1}) \) and by independence of the random walk excursions out of the origin we obtain

\[
E(M_N|F_{N-1}) = M_{N-1} \frac{\mu^{-1} E(\exp(AaJ \sum_{j \in I_1} f(j) P_N^j - B\sqrt{\delta} \Sigma_1 l_1^N)|F_{N-1})}{E(\exp(AaJ \sum_{j \in I_1} f(j) 2\{i \in \{0, \frac{\delta + 1}{a^2}\} : S_i = j\} - B\sqrt{\delta} \Sigma_1 l_1^N))}. \tag{3.24}
\]

We define \( t_N = \inf\{i > i_{N-1}^v + (\delta + \epsilon)/a^2 : S_i = 0\} \) and notice that \( t_N \geq i_{N}^v \) (see Fig. 4 for an example in which \( t_N > i_{N}^v \)).

Fig. 4:

\[
\delta/a^2 + \epsilon/a^2
\]

Therefore, we can write \( P_N^j \leq B_{1,N}^j + B_{2,N}^j \) with

\[
B_{1,N}^j = \{v \in \{i_{N-1}^v + 1, \ldots, i_{N-1}^v + \frac{\delta + \epsilon}{a^2}\} : S_v = j\} \quad \text{and} \quad B_{2,N}^j = \{v \in \{i_{N-1}^v + \frac{\delta + \epsilon}{a^2} + 1, \ldots, t_N\} \} : S_v = j\}. \tag{3.25}
\]

We denote by \( C \) the quantity \( E(\exp(AaJ \sum_{j \in I_1} f(j) P_N^j - B\sqrt{\delta} \Sigma_1 l_1^N)|F_{N-1}) \). Thus, since \( B_{1,N}^j \) is measurable with respect to \( G_{N-1} \) and since \( F_{N-1} \subset G_{N-1} \) we can write

\[
C \leq E\left[ \exp \left( AaJ \sum_{j \in I_1} f(j) B_{1,N}^j - B\sqrt{\delta} \Sigma_1 l_1^N \right) \right] \leq E\left[ \exp \left( AaJ \sum_{j \in I_1} f(j) B_{2,N}^j \right) \right] \quad \text{and} \quad E\left[ \exp \left( AaJ \sum_{j \in I_1} f(j) B_{2,N}^j \right) \right] \leq E\left[ \exp \left( AaJ \sum_{j \in I_1} f(j) B_{1,N}^j \right) \right].
\]

We recall that \( A_k = \sigma(X_1, \ldots, X_k) \) and we let \( Y = E(\exp(AaJ \sum_{j \in I_1} f(j) B_{2,N}^j)|G_{N-1}) \). The fact that the local times \( (l_1^N, \ldots, l_N^N) \) are independent of the random walk allows us to write the equality \( Y = E(\exp(AaJ \sum_{j \in I_1} f(j) B_{2,N}^j)|A_{i_{N-1}^v + (\delta + \epsilon)/a^2}) \). The strong Markov property can be applied here. In fact, if \((V_n)_{n \geq 0} \) is a simple random walk with \( V_0 = S_{i_{N-1}^v + (\delta + \epsilon)/a^2} \), and if \( s = \inf\{n > 1 : V_n = 0\} \), we can write

\[
Y = E_V\left[ \exp \left( AaJ \sum_{j \in I_1} f(j) \{i \in \{1, \ldots, s\} : V_i = j\} \right) \right].
\]

Thus, if we denote \( f = \max_{j \in I_1} \{f_j\} \), we can bound \( Y \) from above as

\[
Y \leq E_V\left[ \exp \left( Aaf^\sharp \{i \in \{1, \ldots, s\} : V_i \in \{-K, \ldots, K\}\} \right) \right]. \tag{3.26}
\]

We want to find an upper bound of \( Y \) independent of the starting point \( S_{i_{N-1}^v + (\delta + \epsilon)/a^2} \). The r.h.s. of \( \tag{3.26} \) is even with respect to the starting point, therefore we can consider that \( V \) is a reflected random walk. That is why it suffices to bound from above the quantities \( W(x,a) = E_x(\exp(Aaf^\sharp \{i \in \{1, \ldots, s\} : |V_i| \in \{0, \ldots, K\}\}) \) with \( x \in \mathbb{N} \). Moreover, the Markov property implies that \( W(x,a) = W(K,a) \) for every \( x \geq K \), and \( W(x,a) < W(K,a) \).
if \( x < K \) because the random walk starting in \( K \) touches necessarily in \( x \) before reaching 0. Therefore, we can write an upper bound of \( C \), i.e.,
\[
C \leq E \left[ \exp \left( Aa \sum_{j \in I_1} f(j) \left( B_{1,N}^j - B\sqrt{\delta} \Sigma_1 l_1^N \right) \right) \right] W(K, a),
\]
and since the excursion of a random walk are independent we can assert that \( B^j_{1,N} \) is independent of \( F_{N-1} \). Hence,
\[
E \left[ \exp \left( Aa \sum_{j \in I_1} f(j) \left( B_{1,N}^j - B\sqrt{\delta} \Sigma_1 l_1^N \right) \right) \right] = E \left[ \exp \left( Aa \sum_{j \in I_1} f(j) \mathbb{1} \left\{ i \in \left\{ 0, \frac{\delta + \epsilon}{a^2} \right\} : S_i = j \right\} - B\sqrt{\delta} \Sigma_1 l_1^N \right) \right],
\]
and (3.24) becomes \( E(M_N | F_{N-1}) \leq M_{N-1} W(K, a)/\mu \). But \( W(K, a) \) tends to 1 as \( a \downarrow 0 \) and becomes smaller than \( \mu \) for some small enough. That is why for a small enough \( (M_N)_{N \geq 0} \) is a supermartingale. Since the stopping time \( m_{t/a^2} \) is bounded from above by \( t/a^2 \), we can apply a stopping time theorem and say that \( E(M_m) \leq E(M_1) \leq 1 \). Then, to complete the proof of (3.23), it suffices to show that, for \( \delta, \epsilon, a \) small enough the quantity \( V_{\delta, \epsilon, a} \), defined in (3.27), is smaller than 1.
\[
V_{\delta, \epsilon, a} = \mu E \left[ \exp \left( Aa \sum_{j \in I_1} f(j) \mathbb{1} \left\{ i \in \left\{ 0, \frac{\delta + \epsilon}{a^2} \right\} : S_i = j \right\} - B\sqrt{\delta} \Sigma_1 l_1^N \right) \right].
\]
We recall that the random walk and the local time \( l_1^N \) are independent. Therefore,
\[
V_{\delta, \epsilon, a} = \mu E \left[ \exp \left( Aa \sum_{j \in I_1} f(j) \mathbb{1} \left\{ i \in \left\{ 0, \frac{\delta + \epsilon}{a^2} \right\} : S_i = j \right\} \right) \right] E \left[ \exp \left( - B\sqrt{\delta} \Sigma_1 l_1^N \right) \right].
\]
By Lemma 2.1 we know that
\[
\lim_{a \to 0} V_{\delta, \epsilon, a} = \mu E \left[ \exp(\sqrt{\delta} + \epsilon \Sigma_1 l_1^N) \right] E \left[ \exp(- B\sqrt{\delta} \Sigma_1 l_1^N) \right].
\]
3.8. Step 4. We notice that the quantities \( m, \sigma_1, \sigma_2, \ldots, \sigma_m, s_1, s_2, \ldots, s_m \) can also be defined for a Brownian motion on the interval \([0, t]\). In fact, we denote \( \sigma_0 = 0, z_0 = 0 \), and recursively \( z_{k+1} = \inf\{s > \sigma_k + \delta : B_s = 0\} \) while \( \sigma_{k+1} \) is the unique integer satisfying \( z_{k+1} \in (\sigma_{k+1} - 1), \sigma_{k+1}] \) and \( s_{k+1} = 1 \) if the excursion ending in \( z_{k+1} \) is in the lower half-plan, \( s_{k+1} = 0 \) otherwise. Finally, we let \( m_t = \inf\{k \geq 1 : z_k > t\} \) and \( z_m = t \). At this stage, we want to transform the random walk that gives the possible trajectories of the polymer into a Brownian motion. For that (as in [6]), we denote by \( \tilde{Q} \) the measure of \((m_{t/a^2}, \sigma_1, \sigma_2, \ldots, \sigma_m, s_1, s_2, \ldots, s_m)\) associated with the random walk on \([0, t/a^2]\) and by \( \tilde{Q} \) the measure of \((m_t, \sigma_1, \sigma_2, \ldots, \sigma_m, s_1, s_2, \ldots, s_m)\) associated with the Brownian motion on \([0, t]\).

As proven in [6] (page 1362) \( Q \) and \( \tilde{Q} \) are absolutely continuous and their Radon-Nikodym derivative satisfies that there exists a constant \( K_{a, \epsilon, \delta} > 0 \) such that for every \( \delta > 0 \)

\[
\lim_{a \to 0} \limsup\frac{K_{a, \epsilon, \delta}}{a} = 0 \quad \text{and} \quad (1 - K')^m \leq \frac{dQ}{d\tilde{Q}} \leq (1 + K')^m. \tag{3.29}
\]

We recall that \( \chi \) is the law of the local times \((l_1^1, l_1^2, \ldots, l_1^m)\), which are independent of the random walk and consequently of \( Q \). Moreover, \( \mathbb{T}_k = (\sigma_k - \sigma_k - 1) \epsilon / a^2 \). Hence, the equation (4.20) gives that \( a \cdot H_{t, \epsilon, \delta}^{(4)}(a, h, \beta) \) depends only on \((m_{t/a^2}, \sigma_1, \sigma_2, \ldots, \sigma_m, s_1, s_2, \ldots, s_m)\) and \((l_1^1, l_1^2, \ldots, l_1^m)\). That is why, we can write

\[
F_{t, \epsilon, \delta}^{(4)}(a, h, \beta_1, \beta_2) = E \left[ \frac{1}{t} \log E_{\chi \otimes \tilde{Q}} \left[ \exp (a H_{t, \epsilon, \delta}^{(4)}(a, h, \beta)) \right] \right].
\]

At this stage, we define \( F_5 \) by replacing the random walk by a Brownian motion, namely by integrating over \( \chi \otimes \tilde{Q} \) instead of \( \chi \otimes Q \). We define

\[
H_{t, \epsilon, \delta}^{(5)}(a, h, \beta_1, \beta_2) = H_{t, \epsilon, \delta}^{(4)}(a, h, \beta_1, \beta_2) + \frac{1}{a} \log (dQ/d\tilde{Q}),
\]

and therefore,

\[
F_{t, \epsilon, \delta}^{(5)}(a, h, \beta_1, \beta_2) = E \left[ \frac{1}{t} \log E_{\chi \otimes \tilde{Q}} \left[ e^{a H_{t, \epsilon, \delta}^{(4)}(a, h, \beta_1, \beta_2)} \right] \right] = E \left[ \frac{1}{t} \log E_{\chi \otimes \tilde{Q}} \left[ e^{a H_{t, \epsilon, \delta}^{(5)}(a, h, \beta_1, \beta_2)} \right] \right].
\]

Now, we aim at proving that \( F^4 \ll F^5 \). To that aim, we calculate \( H^{11} \), i.e.,

\[
H^{11} = H_{t, \epsilon, \delta}^{(4)}(a, h, \beta_1, \beta_2) - H_{t, \epsilon, \delta}^{(5)}(a, h, \beta_1, \beta_2)
\]

\[
= -\frac{2}{a} (h - (1 + \rho) h') \sum_{k=1}^m s_k (\sigma_k - \sigma_{k-1}) \epsilon
\]

\[
+ \left( (\beta_1 - \beta_4) \Sigma_1 + (\beta_2 - \beta_4) \Sigma_2 \right) \frac{\sqrt{a}}{a} \sum_{k=1}^m l_k^1 - \frac{1}{a(1+\rho)} \log \frac{d\tilde{Q}}{dQ}.
\]

We do not give the details of the end of this step because it is done in [6] (page 1361 – 1362). To prove that \( F_5 \ll F_4 \), we consider the density \( dQ/d\tilde{Q} \) in \( H^{11} \), and (3.29) can also be applied. It completes the Step 4.

3.9. Step 5. From now on, we integrate over \( \chi \otimes \tilde{Q} \) in \( F^5 \) and consequently the term \( \log (dQ/d\tilde{Q}) \) does not appear in \( H^{(5)} \) any more. In this step, transform the local times \((l_1^1, \ldots, l_k^k, \ldots)\) into the local times of the Brownian motion that determines \( \tilde{Q} \). We recall that \( L_t \) is the local time spent at \( 0 \) by \((B_s)_{s \geq 0}\) between the times \( 0 \) and \( t \).
But before, we define \((R_s)_{s \geq 0}\) a Brownian motion, independent of \(B\), and we emphasize the fact that, for every \(k \in \{1, \ldots, m\}\),
\[
a \sum_{i \in I_k} \hat{w}_i^D \overset{D}{=} R_{\sigma_k \varepsilon} - R_{\sigma_{k-1} \varepsilon} \quad \text{and} \quad a^2 |I_k| = (\sigma_k - \sigma_{k-1}) \varepsilon. \tag{3.30}
\]
Then, we can rewrite the fifth Hamiltonian as
\[
H^{(5)}_{t, \varepsilon, \delta}(a, h, \beta_1, \beta_2) = -\frac{2}{a} \sum_{k=1}^{m} s_k (R_{\sigma_k \varepsilon} - R_{\sigma_{k-1} \varepsilon} + h(\sigma_k - \sigma_{k-1}) \varepsilon) - \frac{\beta_1 \Sigma_1 + \beta_2 \Sigma_2}{2} \sqrt{\delta t_k^1}. \tag{3.31}
\]
We define the sixth Hamiltonian as,
\[
H^{(6)}_{t, \varepsilon, \delta}(a, h, \beta_1, \beta_2) = -\frac{2}{a} \sum_{k=1}^{m} s_k (R_{\sigma_k \varepsilon} - R_{\sigma_{k-1} \varepsilon} + h(\sigma_k - \sigma_{k-1}) \varepsilon) + \frac{\beta_1 \Sigma_1 + \beta_2 \Sigma_2}{a} L_t.
\]
At this stage, we notice that \(F^5\) and \(F^6\) do not depend on \(a\) anymore. Hence, to simplify the following steps, we transform a bit the general scheme of the proof. In fact, from now on, we will denote, for \(i = 5, 6\) or 7,
\[
F^i_{t, \varepsilon, \delta}(h, \beta_1, \beta_2) = \mathbb{E} \left[ \frac{1}{t} \log E \left[ \exp\left(\mathcal{H}^i_{t, \varepsilon, \delta}(h, \beta_1, \beta_2)\right)\right] \right] \tag{3.32}
\]
with \(\mathcal{H}^i_{t, \varepsilon, \delta}(h, \beta_1, \beta_2) = a H^i_{t, \varepsilon, \delta}(h, \beta_1, \beta_2)\). Therefore, to prove that \(F^i \ll \ll F^j\) we use
\[
H^{I1} = \mathcal{H}^i_{t, \varepsilon, \delta}(h, \beta_1, \beta_2) - \frac{1}{1+\rho} \mathcal{H}^j_{t, \varepsilon, \delta}(h, \beta_1, \beta_2) = (1+\rho) \mathcal{H}^j_{t, \varepsilon, \delta}(h, \beta_1, \beta_2).
\]
and we show that \(\limsup_{t \to \infty} 1/t \log \mathbb{E} E(\exp((1+\rho^{-1})I^{I1})) \leq 0\).

We want to prove that \(F^5 \ll F^6\) but, by the scaling property of Brownian motion, it is not difficult to show that for \(i = 5\) or 6
\[
\mathcal{H}^i_{t, \varepsilon, \delta}(h, \beta_1, \beta_2) = (1+\rho) \mathcal{H}^j_{t, \varepsilon, \delta}(h, \beta_1, \beta_2).
\]
Therefore, by \((3.33)\), we can write \(H^{I1} = \mathcal{H}^i_{t, \varepsilon, \delta}(h, \beta_1, \beta_2) - \mathcal{H}^j_{t, \varepsilon, \delta}(1+\rho) h, \beta_3, \beta_4\). Thus, since \((1+\rho) h < h\) and \(-\sum_{k=1}^{m} s_k(\sigma_k - \sigma_{k-1}) \varepsilon < 0\), we obtain
\[
H^{I1} \leq \beta_1 \Sigma_1 \sqrt{\delta} \sum_{k=1}^{m} t_k^1 - \beta_3 \Sigma_1 \sum_{k=1}^{m} L_{z_k^1} - L_{z_{k-1}^1}
\]
\[
+ \beta_3 \Sigma_1 \sum_{k=1}^{m} L_{z_{k+1}} - L_{z_k^1},
\]
with \(z_j^v = z_j\) for every \(j < m\) and \(z_m^v = \inf\{t > \sigma_{m-1} \varepsilon + \delta : B_t = 0\}\). Finally, by the Hölder inequality, it suffices to prove, for \(B > A\), that
\[
\limsup_{t \to \infty} \frac{1}{t} \log E \left[ \exp \left( A \sum_{k=1}^{m} \sqrt{\delta t_k^1} - B \sum_{k=1}^{m} L_{z_k^1} - L_{z_{k-1}^1} \right) \right] \leq 0, \tag{3.35}
\]
and
\[
\limsup_{t \to \infty} \frac{1}{t} \log E \left[ \exp \left( A \sum_{k=1}^{m} L_{z_k^1} - L_{z_{k-1}^1} - B \sum_{k=1}^{m} \sqrt{\delta t_k^1} \right) \right] \leq 0, \tag{3.36}
\]
and
\[
\limsup_{t \to \infty} \frac{1}{t} \log E(\exp(B(L_{t+\delta} - L_t))) = 0. \tag{3.37}
\]
We denote by \(C_t\) the first time of return to the origin after time \(t\). Proving \((3.37)\) is immediate because \(C_t\) is a stopping time with respect to the natural filtration of \(B\), we can therefore apply the strong Markov property to obtain, for every \(u \in [t, t + \delta]\), the equality \(E(\exp(B(L_{t+\delta} - L_u)))|C_t = u) = E(\exp(B(L_{t+\delta} - u)))\). Thus, we can write
\[
E(\exp(B(L_{t+\delta} - L_t))) = \int_{t}^{t+\delta} E(\exp(B(L_{t+\delta} - u))) dC_t(u) \leq E(\exp(BL_{\delta})). \tag{3.38}
\]
This implies (3.37), and it remains to prove (3.35), and (3.36). We define a new filtration, \(F_N = \sigma(\sigma((B_k)_{k \leq z_k^N}) \cup \sigma(t_1^1, \ldots, t_1^N))\). We notice that \((z_k^N)_{N \geq 0}\) is a sequence of increasing stopping times, and consequently, \(F_N\) is an increasing filtration. We denote by \(M_N\) the quantity

\[
M_N = \frac{\exp \left( A \sum_{k=1}^N \sqrt{\delta t_k^1} - B \sum_{k=1}^N L_{z_k^N} - L_{z_{k-1}^N} \right)}{E \left[ \exp (-BL_\delta + A\sqrt{\delta t_1^1}) \right]^N},
\]

which is a super-martingale with respect to \(F_N\). Effectively, \(L\) and \((t_k^i)_{k \geq 1}\) are independent, \((L_s - L_{z_k^N})_{s \geq z_k^N}\) is independent of \(F_N\) (because \(B_{z_k^N} = 0\) and \(L_{z_{k+1}^N} - L_{z_k^N} \geq L_{z_k^N} + \delta - L_{z_k^N}\). Thus, since \(E \left( -B(L_{z_k^N} + L_{z_{k+1}^N}) \right) = E \left( -B(L_\delta) \right)\), we obtain \(E(M_{N+1}|F_N) \leq M_N\). Moreover, \(m_t\) is a stopping time with respect to \(F_N\) and is bounded from above by \(t/\delta\). Therefore, to prove (3.35), it suffices to show (as in Step 3) that for \(B > A\) and \(\delta\) small enough, \(V = E[\exp(A\sqrt{\delta t_1^1} - BL_\delta)] \leq 1\). Moreover, \(L_\delta\) and \(\sqrt{\delta t_1^1}\) have the same law and are independent. That is why we can write \(V = E[\exp(A\sqrt{\delta t_1^1})]E[\exp(-B(L_\delta))]\), which is strictly smaller than 1 for \(\delta\) small enough (as proven in Step 3).

We prove (3.36) in a very similar way. Effectively, since \(L_{z_{k+1}^N} - L_{z_k^N} \leq L_{z_k^N} + \delta + \varepsilon - L_{z_k^N}\), we prove that the inequality (3.35) is still satisfied when \(A\) and \(-B\) are exchanged. Therefore, the proof of \(F^5 \ll F^6\) is completed. To end this step, we notice that (3.36) and (3.35) imply directly that \(F^6 \ll F^5\). Thus, the proof of Step 5 is completed.

3.10. Step 6. Let \(\mu_1 = \beta_1 \Sigma_1 + \beta_2 \Sigma_2\) and \(\mu_3 = \beta_3 \Sigma_1 + \beta_4 \Sigma_2\). This step is the last one, therefore, the following Hamiltonian is the one of the continuous model, i.e.,

\[
\Pi_{t,\varepsilon,\delta}(h, \beta_1, \beta_2) = -2 \int_0^t \mathbb{1}_{\{B_s < 0\}}(dR_s + hds) + \mu_1 L_t.
\]

For simplicity, we define \((\phi_s)_{s \in [0, t]}\) by \(\phi_s = s_k\) for every \(s \in (\sigma_{k-1}, \sigma_k]\). In that way, \(\sum_{k=1}^m s_k(R_{\sigma_k} - R_{\sigma_{k-1}}) + h(\sigma_k - \sigma_{k-1}) = \int_0^t \phi_s(dR_s + hds)\). Moreover, the scaling property of Brownian motion gives, for \(i = 6 \text{ or } 7\),

\[
\Pi_{t,\varepsilon,\delta}^{(i)}((1 + \rho)h, \beta_1, \beta_2) \overset{D}{=} \Pi_{t,\varepsilon,\delta}^{(i)}((1 + \rho)h, \beta_1, \beta_2),
\]

Hence, to show that \(F^6 \ll F^7\), we consider (as in Step 5) the difference

\[
H^{11} = \Pi_{t,\varepsilon,\delta}(h, \beta_1, \beta_2) - \Pi_{t,\varepsilon,\delta}^{(i)}((1 + \rho)h, \beta_3, \beta_4),
\]

which is equal to \(\Pi_{t,\varepsilon,\delta}(h, \beta_1, \beta_2) - \Pi_{t,\varepsilon,\delta}^{(i)}((1 + \rho)h, \beta_3, \beta_4)\). Thus, we can bound \(H^{11}\) from above as follows

\[
H^{11} = -2 \int_0^t (\phi_s - 1_{\{B_s < 0\}}) dR_s - 2 \int_0^t (h \phi_s - (1 + \rho) h' 1_{\{B_s < 0\}}) ds + (\mu_1 - \mu_3) L_t
\]

\[
H^{11} \leq -2 \int_0^t (\phi_s - 1_{\{B_s < 0\}}) dR_s - 2h \int_0^t (\phi_s - 1_{\{B_s < 0\}}) ds + (\mu_1 - \mu_3) L_t.
\]

We want to prove that \(\lim_{t \to \infty} \frac{1}{t} \log \mathbb{E} \left[ \exp ((1 + \rho^{-1})H^{11}) \right] \leq 0\) and after the integration over \(\mathbb{E}\), it remains to prove that for \(A > 0\) and \(B > 0\) and for \(\delta, \varepsilon\) small

\[
\lim_{t \to \infty} \frac{1}{t} \log \mathbb{E} \left[ \exp \left( A \int_0^t |\phi_s - 1_{\{B_s < 0\}}| ds - BL_\delta \right) \right] \leq 0. \tag{3.40}
\]

As in Step 3 (see Fig. 4), we notice that between \(z_{k-1}\) and \(z_k\), if we find an excursion of length larger than \(\delta + \varepsilon\), it is necessarily the one which ends at \(z_k\) and gives the value of \(s_k\).
It means that, apart eventually from the very beginning of such an excursion (between \(z_{k-1}\) and \(\sigma_{k-1}\)), \(s_k\) and \(\phi_s\) have the same value along the excursion. Finally, we obtain

\[
\int_0^t \mathbf{1}_{\{B_s < 0\}} - \phi_s|ds \leq P_{0,t,\delta,\varepsilon} + m\varepsilon, \tag{3.41}
\]

where \(P_{u,v,\delta,\varepsilon}\) is the sum between \(u\) and \(v\) of the excursion lengths which are smaller than \(\delta + \varepsilon\). The term \(m\varepsilon\) allows us to take into account the formerly mentioned situation between \(z_{k-1}\) and \(\sigma_{k-1}\).

Thus, with (3.41) and the Hölder inequality, we can show that the inequality (3.40) occurs if, for \(\delta, \varepsilon\) small, we have

\[
\limsup_{t \to \infty} \frac{1}{t} \log \mathbb{E}[\exp(A\varepsilon m - BL_t)] \leq 0 \quad \text{and} \quad \limsup_{t \to \infty} \frac{1}{t} \log \mathbb{E}[\exp(AP_{0,t,\delta,\varepsilon} - BL_t)]\leq 0. \tag{3.42}
\]

We begin with the proof of the first inequality of (3.42). To that aim, we recall that, for every \(k < m\), we have \(z_k > z_{k-1} + \delta\). Therefore, we can write

\[
Ac \varepsilon m - BL_t \leq A \varepsilon m - B \sum_{k=1}^m (L_{z_{k-1}} + \delta - L_{z_{k-1}}) + B(L_{t+\delta} - L_t).
\]

From the equation (3.37) and the Hölder inequality we deduce that the term \(B(L_{t+\delta} - L_t)\) does not change the result. For this reason we just have to consider the quantity \(1/t \log \mathbb{E}[\exp(\sum_{k=1}^m A\varepsilon - B(L_{z_{k-1}} + \delta - L_{z_{k-1}}))]\) when \(t \to \infty\). As in (3.39), we define the martingale

\[
M_N = \frac{1}{(\varepsilon, \delta)^N} \exp \left( \sum_{k=1}^N A\varepsilon - B(L_{z_{k-1}} + \delta - L_{z_{k-1}}) \right) \tag{3.43}
\]

Since \(m\) is a stopping time bounded from above by \(t/\delta\), it is sufficient to show that \(V_{\varepsilon, \delta} < 1\) for \(\delta, \varepsilon\) small enough. It is the case because \(E[\exp(-BL_0)] < 1\) for every \(B > 0\). Therefore, we take \(\varepsilon\) small enough and it completes the proof.

It remains to prove the second part of (3.42). Notice that \(P_{0,t,\delta,\varepsilon} = \sum_{k=1}^m P_{z_{k-1}, z_k, \delta, \varepsilon}\) and that for every \(k \leq m\) \(P_{z_{k-1}, z_k, \delta, \varepsilon} \leq 2(\delta + \varepsilon)\) (still because there can not be more than one excursion larger than \(\delta + \varepsilon\) between \(z_{k-1}\) and \(z_k\)). Therefore, we obtain the following upper bound

\[
AP_{0,t,\delta,\varepsilon} - BL_t \leq 2A(\delta + \varepsilon)m - B \sum_{k=1}^m (L_{z_{k-1}} + \delta - L_{z_{k-1}}) + B(L_{t+\delta} - L_t).
\]

As in (3.37) the term \(B(L_{t+\delta} - L_t)\) is removed, and it remains to consider \(1/t \log \mathbb{E}[\sum_{k=1}^m A(\varepsilon + \delta) - B(L_{z_{k-1}} + \delta - L_{z_{k-1}})]\) when \(t \to \infty\). To that aim, we build again the martingale

\[
M_N = \frac{1}{(D_{t,\delta})^N} \exp \left( \sum_{k=1}^N A(\varepsilon + \delta) - B(L_{z_{k-1}} + \delta - L_{z_{k-1}}) \right) \tag{3.44}
\]

with \(D_{t,\delta} = E[\exp(A(\delta + \varepsilon) - BL_0)]\). The term \(m\) is a bounded stopping time, therefore, it suffices to show, for \(\delta, \varepsilon\) small enough, that \(D_{t,\delta} < 1\). To that aim, we choose \(\varepsilon \leq \delta\), and it remains to consider the quantity \(E[\exp(2A\delta - BL_0)]\). Moreover, \(L_0 = D \sqrt{\delta} L_1\), and if we denote \(f(x) = E[\exp(xL_1)]\), we can use a first order development of \(f\) in 0. It gives \(f(-B\sqrt{\delta}) = 1 - f'(0)B\sqrt{\delta} + \xi_1(\delta)\sqrt{\delta}\) with \(f'(0) > 0\) and \(\lim_{x \to 0} \xi_1(x) = 0\). We also know that, \(\exp(2A\delta) = 1 + 2A\delta + \xi_2(\delta)\delta\) with \(\lim_{x \to 0} \xi_2(x) = 0\). Hence, for \(\varepsilon \leq \delta\) and \(\delta\) small enough, we obtain \(E[\exp(2A\delta - BL_0)] = \exp(2A\delta) f(-B\sqrt{\delta}) < 1\). The proof of \(F_6 << F_5\) is exactly the same and the Step 6 is completed.

4. Appendix

4.1. proof of Proposition 1.5

Proof. The computation of \(\bar{\Phi}\) is based on the fact that \(\bar{\Phi} = \bar{\Phi}(\beta, h)\) is equal to the quantity \(h + \lim_{t \to \infty} 1/t \log \mathbb{E} \left( \exp \left( -2h\Gamma^-(\beta)(t) + \beta L(t)_0 \right) \right)\), where \(\Gamma(t) = \int_0^t 1_{\{B_s < 0\}} ds\). When \(\beta \leq 0\) we
can conclude immediately that $\tilde{\Phi}(\beta, h) = h$. Therefore, in what follows we consider $\beta > 0$. Moreover, the joint law of $(\Gamma^-(t), L_t)$ is available in [16] and takes the value

$$dP_{\{\Gamma^-(t), L_t\}}(\tau, b) = 1_{\{0 < \tau < t\}} 1_{\{b > 0\}} \frac{b t \exp\left(-\frac{b^2}{8t}(t-\tau)\right)}{4\pi \tau^{3/2}(t-\tau)^{3/2}} \, db \, d\tau. \quad (4.1)$$

From now on, we will denote $R_t = E(\exp(-2\log^{\Gamma^-(t)} + \beta L_t))$, and with (4.1) and the new variables $s = \tau/t$ and $v = b/\sqrt{t}$, we obtain

$$R_t = \int_0^\infty v \exp\left(\frac{b v \sqrt{t}}{4\pi}\right) \int_0^1 \exp(-2h\frac{s\sqrt{t}}{s^2(1-s)^{3/2}}) \, ds \, dv. \quad (4.2)$$

In this computation we delete the constant terms because they do not change the limit. We can write $f_1$ of (4.2) as the sum of $A_1(t) = \int_0^{1/2} \exp\left(h(\sqrt{1-t^2} - \frac{b^2}{8t})\right) dvdu$. As

$$\lim sup_{t \to \infty} \int_0^\infty v \exp(\beta v \sqrt{t}) A_1(t) \, dv = 0 \quad (4.3)$$

It gives immediately the inequalities $A_1(t) \leq A_2(t) + 2A_3(t)$. Therefore, instead of studying the convergence of $1/t \log R(t)$, it suffices to consider $1/t \log S(t)$ with $S(t) = \int_0^\infty v \exp(\beta v \sqrt{t}) A_1(t) \, dv$. We apply the Fubini Tonelli theorem which gives

$$S(t) = \int_0^1 v \exp\left(h(\sqrt{1-t^2} - \frac{b^2}{8t})\right) dvdu \exp(-ht). \quad (4.4)$$

Thus, for every $u \in [0, 1/4]$, we change the variables of the second integral of (4.4). To that aim, we denote $r = v^2/u$. After that, we transform the variable $u$ into $x = 4u$, and we obtain

$$S(t) = \frac{1}{4} \int_0^1 \exp\left(h(\sqrt{1-x} - \frac{b^2r^2}{2x})\right) drdx \exp(-ht). \quad (4.5)$$

The constant factor 1/4 can be deleted and thus, by considering (4.3), for every $\varepsilon > 0$, we can write the following lower bound,

$$\liminf_{t \to \infty} \frac{1}{t} \log S(t) + h \geq \liminf_{t \to \infty} \frac{1}{t} \left[\log \int_0^e \exp\left(h(\sqrt{1-x} - \frac{b^2r^2}{2x})\right) dr\right] + \log \int_0^\infty e^{-x} dx \geq h \sqrt{1 - \varepsilon}. \quad (4.6)$$

Thus, we let $\varepsilon$ tend to 0 and we obtain

$$\liminf_{t \to \infty} \frac{1}{t} \log S(t) + h \geq h. \quad (4.6)$$

But we can also bound $\liminf_{t \to \infty} \frac{1}{t} \log S(t) + h$ as follows. The laplace method allows us to find the asymptotic behavior of $Y(x) = \int_0^\infty \exp\left(\beta \sqrt{xt}/2 - r/8\right) dr$ when $x$ tends to $\infty$. Since $\beta > 0$, it gives $Y(x) \sim_{x \to \infty} c\sqrt{x} \exp\left(\beta^2 xt/2\right)$ with $c > 0$ that depends on $\beta$, and we obtain

$$\liminf_{t \to \infty} \frac{1}{t} \log S(t) + h \geq \liminf_{t \to \infty} \frac{1}{t} \log \int_0^1 \exp(\beta \sqrt{1-x} - \frac{b^2x^2}{2x}) dx. \quad (4.7)$$

With the formerly mentioned laplace method, we can find the asymptotic behavior of the integral of the r.h.s. of (4.7). As $t$ tends to $\infty$, it behaves as $d \exp\left(t\left(\frac{h^2}{2\beta^2} + \frac{b^2}{2}\right)\right)$ with $d > 0$. Therefore, we obtain

$$\liminf_{t \to \infty} \frac{1}{t} \log S(t) + h \geq \frac{h^2}{2\beta^2} + \frac{b^2}{2}. \quad (4.8)$$

Finally, (4.6) and (4.8) give

$$\liminf_{t \to \infty} \frac{1}{t} \log S(t) + h \geq \max\left\{\frac{h^2}{2\beta^2} + \frac{b^2}{2}, h\right\}. \quad (4.9)$$

Now, we want to show that the r.h.s. of (4.9) is also an upper bound of the quantity $\limsup_{t \to \infty} 1/t \log S(t) + h$. To that aim, we use the fact that $\limsup_{t \to \infty} 1/t \log S(t) + h$
is equal to the maximum of \( \limsup_{t \to \infty} t \log \int_{\frac{1}{2}}^{1} \) and \( \limsup_{t \to \infty} 1/t \log \int_{\frac{1}{2}}^{1} \). The same kind of estimates allows us to perform the computation. Hence, we have
\[
\lim_{t \to \infty} \frac{1}{t} \log S(t) + h = \max \left( \frac{h^2}{2\beta^2} + \frac{\beta^2}{2}, h \right).
\]
Finally, \( \Phi(\beta, h) = h + \lim_{t \to \infty} 1/t \log S(t) \), and therefore,
\[
\Phi(h, \beta) = h \text{ if } h > \beta^2 \quad \text{and} \quad \Phi(h, \beta) = \frac{h^2}{2\beta^2} + \frac{\beta^2}{2} \text{ if } h \leq \beta^2.
\]

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