Incompressibility of classical distributions

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Abstract

In blind compression of quantum states, a sender Alice is given a specimen of a quantum state $\rho$ drawn from a known ensemble (but without knowing what $\rho$ is), and she transmits sufficient quantum data to a receiver Bob so that he can decode a near perfect specimen of $\rho$. For many such states drawn iid from the ensemble, the asymptotically achievable rate is the number of qubits required to be transmitted per state. The Holevo information is a lower bound for the achievable rate, and is attained for pure state ensembles, or in the related scenario of entanglement-assisted visible compression of mixed states wherein Alice knows what state is drawn.

In this paper, we prove a general and robust lower bound on the achievable rate for ensembles of classical states, which holds even in the least demanding setting when Alice and Bob share free entanglement and a constant per-copy error is allowed. We apply the bound to a specific ensemble of only two states and prove a near-maximal separation (saturating the dimension bound in leading order) between the best achievable rate and the Holevo information for constant error. This also implies that the ensemble is incompressible – compression does not reduce the communication cost by much. Since the states are classical, the observed incompressibility is not fundamentally quantum mechanical. We lower bound the difference between the achievable rate and the Holevo information in terms of quantitative limitations to clone the specimen or to distinguish the two classical states.

1 Introduction

1.1 Blind quantum data compression and related scenarios

A central goal of information theory is to capture the ultimate rate of transformation of resources. For example, we may want to minimize the communication cost of a task, which is an optimization problem over a potentially unbounded number of possible communication protocols. In some special cases, the best communication cost is given by a simple enough information theoretic quantity that can be computed. For example, this has been achieved in Shannon’s source coding theorem (data compression) and noisy channel coding [1] and some network analogues [2]. Quantum information theory shares the same goal, and similar understanding has been achieved in quantum noisy coding theorem, albeit with regularization issues in many scenarios.

This paper focuses on the problem of quantum data compression, which can be stated as follows. Fix an ensemble $\{p(x), \rho|^C_x\}$ of quantum states $\rho|^C_x$ on a register $C$, and define the associated state

$$\rho^	ext{XC} = \sum_x p(x)|x\rangle\langle x| \otimes \rho|^C_x .$$

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In the aforementioned ensemble, each state $\rho^C_x$ is labeled by a classical index $x$ recorded in the register $X$ and occurring with probability $p(x)$. Suppose a Referee prepares $n$ copies of the above state:

$$\sum_{x_1x_2\cdots x_n} p(x_1)p(x_2)\cdots p(x_n) |x_1\rangle |x_1\rangle_1 \otimes |x_2\rangle_2 \otimes \cdots \otimes |x_n\rangle_n |x_n\rangle_n \otimes \rho^C_{x_1} \otimes \rho^C_{x_2} \otimes \cdots \otimes \rho^C_{x_n},$$

where each $C_i \equiv C$. The Referee transmits $C_1 \cdots C_n$ to Alice. Alice is allowed to send some quantum data to Bob. Bob decodes and his final output registers are $C'_1 \cdots C'_n$. The goal is that the final state of the Referee and Bob should be close to the state in (2), while minimizing the amount of data sent. A rate $r$ is achievable for the compression if there is a family of protocols labeled by $n$ in which Alice sends $nr$ qubits. There are many related but inequivalent scenarios for quantum data compression.

- In the blind scenario (as described above), Alice does not have access to the registers $X_1 \cdots X_n$. She has a specimen of the states $\rho^{x_1} \otimes \cdots \otimes \rho^{x_n}$ in $C_1 \cdots C_n$, but she does not know what they are in general. In contrast, in the visible scenario, the Referee gives a copy of $X_1 \cdots X_n$ to Alice so she knows $x_1 \cdots x_n$ (and in this case it is unnecessary to give her $C_1 \cdots C_n$).

- In the unassisted model, Alice and Bob do not share any correlations. In other scenarios, they may share classical randomness. In the entanglement-assisted scenario, they may share any entangled state of their choice. Note that with entanglement assistance, sending quantum or classical data are equivalent due to teleportation [3] and superdense coding [4]. The rate in qubits is equal to half of the rate in bits.

- One has to specify the measure of proximity between the initial state (2) and the final state held by the Referee and Bob. A more stringent definition of error requires that the final state in $X_1 \cdots X_n C'_1 \cdots C'_n$ be close to the original state in (2), in trace distance or in fidelity. The error in this case is called “global.” A more relaxed definition of error requires that for each $i$, the $i$-th output state in $X_i C'_i$ is close to the initial state in $X_i C_i$. The error in this case is called “local.” For the asymptotic case, the error is typically required to vanish as $n$ increases. Alternatively, one can consider the one-shot scenario when $n = 1$, but this scenario is out of the scope for our paper. We will mention some one-shot results which have asymptotic implications.

- There is no limitation on the states $\rho^C_x$ in the ensemble in the problem. There are several special cases of interest. One well-studied special case is the “pure state case” in which all $\rho^C_x$ are pure. Another case concerns ensembles of states that are commuting, in which case they can be simultaneously diagonalized, and the $\rho^C_x$ correspond to classical distributions.

We can summarize prior results as follows. The unassisted blind scenario for pure state case was formulated in [5], [6], [7]. These pioneering works established the quantum analogue of Shannon’s source coding theorem when the ensemble $\{p(x), |\rho^x\rangle\langle\rho^x|_C\}$ consists only of pure states, with the best achievable rate shown to be $S(\rho_C)$ qubits, where $S(\cdot)$ is the von-Neumann entropy [8] and $\rho_C = \sum_x p(x)|\rho^x\rangle\langle\rho^x|_C$ is the average state of the ensemble. If the states $|\rho^x\rangle_C$ are mutually orthogonal, the problem reduces to Shannon’s source coding problem and Schumacher’s protocol recovers Shannon’s result with rate being $S(\rho_C)$ bits.

For a general ensemble $\{p(x), \rho^C_x\}$, the Holevo information is defined as $S(\sum_x p(x)|\rho^x\rangle\langle\rho^x|_C) - \sum_x p(x)S(\rho^C_x)$, and it is also the quantum mutual information $I(X : C)_p$ between $X$ and $C$ evaluated on $\rho_{X\otimes C}$. It was independently shown by [9] and [10] that the Holevo information is a lower bound for the achievable rate in the unassisted scenarios for both visible and blind compression.

For unassisted compression of pure states, the above lower bound on the rate is already attained by the protocol in the blind setting [5], [6], [7]. Thus the visible scenario, with Alice’s knowledge of the state to be compressed, surprisingly does not improve the rate. Furthermore, shared randomness does not reduce the best achievable rate.

The situation is more complex for the compression of mixed quantum states. The problem was considered as early as in [11] and formulated and studied in detail in a large body of work [12], [13], [14], [15], [16], [17].
The rate depends on whether the protocol is visible or blind, what kind of assistance is available, under local or global error, and whether the ensemble is classical or quantum, to be discussed as follows.

Visible compression of classical ensemble is relatively well understood, given the assistance of shared randomness. The problem is equivalent to the simulation of classical channels (associated to the classical Reverse Shannon theorem). Authors in [20] and [13] independently showed that the Holevo information is the achievable rate in bits under global error criteria. Winter [18] further showed that under the local error criteria, shared randomness is not needed to achieve the Holevo information. It was also shown in [18, Theorem 3] that the Holevo information is a lower bound even for asymptotically non-vanishing global error. This is a notable feature of visible compression: even a constant global error (for example $\frac{1}{3}$) requires a rate at least equal to the Holevo information. Using rejection sampling, the Holevo information was shown to be achievable in the asymptotic setting [21] and one-shot with expected communication [22].

For the visible compression of quantum ensembles without any assistance, Horodecki [12] showed that the qubit rate is given by a quantity defined via extensions of the ensemble. Later, Hayashi [23] gave a simpler characterization of the qubit rate in terms of the entanglement of purification [24]. With entanglement assistance, protocols for the visible compression have several guises. The first guise is remote state preparation of entangled states between Alice and Bob, first formalized in [25] and solved in [26] with qubit rate $\frac{1}{2}I(X : C)_{\rho}$ (subsequently reproduced from a one-shot approach in [27]). The second is via the rejection sampling method and quantum substate theorem [28, 29] which gives a one-shot protocol with asymptotic rate of $\frac{1}{2}I(X : C)_{\rho}$ qubits. The third guise is via the general scenario of the quantum Reverse Shannon theorem [30, 31] which also attains the optimal qubit rate of $\frac{1}{2}I(X : C)_{\rho}$. The first and third methods are entanglement optimal as well. Reference [32], Section 10.8, also addresses visible compression.

Finally, for blind compression of a mixed ensemble, the difference between the rate of quantum communication and the Holevo information was termed “information defect” by Horodecki [9]. Both [9] and [10] provided bounds on the information defect without resolving whether it could be positive. In [13], a classical ensemble was presented with an argument sketching the positivity of its information defect. But the error criteria in their argument was not made precise. Kramer and Savari [14] also showed a similar result with an error criteria based on empirical distribution of the outputs. But this error criteria does not match either the global or local criteria discussed above. In a powerful series of results [15, 16, 17], Koashi and Imoto characterized the optimal rates of quantum and classical communication, the amount of entanglement required, and their tradeoffs in blind compression. This was done by a decomposition of the ensemble of states, now colloquially called the Koashi-Imoto decomposition. Their result requires that the local error goes to zero in the asymptotic setting and leads to a large information defect. An ensemble witnessing this separation consists of two equiprobable commuting states [16], and its blind compression requires classical communication at the rate of the entropy of the average state. This ensemble achieves a near-maximal separation between achievable rate of communication and the Holevo information of the ensemble in the regime of vanishing error. By ‘near-maximal’, we mean that the leading order term in the separation saturates the dimension bound.

We motivate this study by asking if the above rate characterization holds for non-vanishing error; mimicking the feature of visible compression mentioned earlier. This is a first step towards chalking out the “communication versus error” profile for blind compression and understanding its strong converse rate. We observe that the Koashi-Imoto rate characterization is sensitive to the amount of error. We highlight this using an example in Appendix A where we show that blind compression of any ensemble of two commuting states $\{\rho_0^C, \rho_1^C\}$ with local error $\varepsilon$ can be achieved with unassisted rate of $2 \log \log \frac{1}{\varepsilon} + 2 \log \frac{1}{\varepsilon} + 5$ bits ($d$ is the dimension of register $C$ which is a constant independent of $n$). For $\varepsilon \gg \sqrt{d}$, our achievable rate is substantially less than the lower bound of $\log d$ given by the Koashi-Imoto rate characterization for a generic pair of commuting states in the vanishing error regime. The general compression rate, as a function of $\varepsilon$, therefore, remains unresolved.
Is there a coding scheme that can even further reduce the rate exhibited in the aforementioned example for finite $\varepsilon$? For instance, could the rate depend on the error as $O(\log \log \frac{1}{\varepsilon})$, as in [25, 29, 22] using rejection sampling? Much of this paper is devoted to showing the contrary. We provide an example where the rate of $O(\log \frac{1}{\varepsilon})$ is optimal for a suitable finite choice of local error. For this ensemble, we show a large and robust lower bound $(\log d) - 7$ for the rate, while the Holevo information is less than 1. By ‘robust’, we mean that the lower bound is a simple function of the error. Thus compression of this ensemble does not reduce communication rate in a significant manner relative to sending the whole register $C$. Note that since our lower bound holds for local error, it also implies the same lower bound for the global error. Furthermore, our lower bound applies to entanglement-assisted protocols. Since we consider entanglement-assisted protocols, our lower bound also applies to shared randomness assisted protocols, such as in [32, Section 10.8].

Our result may also provide insights to rate distortion theory for blind compression of distributions. Rate-distortion theory has been studied in the quantum setting, for example, see [33, 34, 35]. These prior works use a less stringent error measure than our current work, but preserve the purification of the compressed states. Therefore, their lower bounds do not apply to the current setting.

### 1.2 Main result, techniques and consequences

In this work, we show a near-maximal (for the dimension of the states) separation between the achievable rate of classical communication for entanglement-assisted blind mixed state compression and the Holevo information. As mentioned earlier, our separation holds for finite (non-vanishing) local error. We establish this separation in two steps.

In the first step, we consider entanglement-assisted blind mixed state compression of the $n$-copy state in (2), for ensembles of classical states $\rho^n_C$ that are diagonal. We obtain a single-letter lower bound on the asymptotic achievable rate $R$:

$$R \geq \min_{\mathcal{F},C\rightarrow CC'} \left( I(C : C' | X)_{F(\rho)} + I(X : C)_{\rho} - \varepsilon \log |X| - 1 \right),$$

where $\rho$ is defined in (1), the quantum TPCP map $\mathcal{F}$ takes $\rho_{XC}$ to $\rho_{XCC'}$ and satisfies the constraints

1. $\text{Tr}_{C'} \mathcal{F}(\rho_{XC}) = \rho_{XCC'}$,
2. $\text{Tr}_{C'} \mathcal{F}(\rho_{XC}) = \rho_{XC}$,

and the approximation in the first constraint is given by $\varepsilon$. Since the map $\mathcal{F}$ acts as identity on the register $X$, we have shortened the notation $I_X \otimes \mathcal{F}$ to $\mathcal{F}$ for convenience. Note that despite a similarity in form between (3) and Lemma 3.1 in [14], our bound is obtained under the local error condition (unlike the empirical error condition of [14]). The expression $\min_{\mathcal{F},C\rightarrow CC'} \left( I(C : C' | X)_{F(\rho)} \right)$ approximates the difference between $R$ and the Holevo information $I(X : C)_{\rho}$ in (3), with the following noteworthy features:

- If Alice knows $X$ (visible scenario or distinguishable $\rho^n_C$’s), the expression vanishes which matches previous known bounds. Thus this expression represents Alice’s lack of knowledge of the label $X$ of the given state. Our strategy is to prove a large lower bound for the expression.
- We can view $C$ as the register containing the state held by Alice, and $C'$ as the register $C'$ containing the output state held by Bob. The first constraint $\text{Tr}_{C'} \mathcal{F}(\rho_{XC}) = \rho_{XCC'}$ reflects the correctness of the protocol: the state $\text{Tr}_{C'} \mathcal{F}(\rho_{XC})$ between Bob and the Referee (holding $X$) is close to the desired state $\rho_{XCC'}$ (with $C$ replaced by $C'$). The second constraint $\text{Tr}_{C'} \mathcal{F}(\rho_{XC}) = \rho_{XC}$ comes from classicality of the ensemble, which allows Alice to retain a copy of the classical value in register $C$. Being classical, the system $C$ is not disturbed by the measurement that allows Alice to retain the copy of $C$. 


In Section 3, we specialize to equiprobable ensembles of two states, and convert the expression to two simpler lower bounds given in (10). The first lower bound, (10)(c), is the expected distance (over \( x \)) between two joint states shared by Alice and Bob. The first joint state is the output of the protocol, and the second state consists of two independent copies of Alice’s input state, one held by each of Alice and Bob. Thus, the compression rate is lower bounded by the inability to clone the states in the ensemble. The second lower bound, (10)(f), is the gain in distinguishability between the states for \( x = 0 \) and \( x = 1 \), if two copies of the states are available instead of one copy. We note that these two lower bounds involve trace distances on the joint system held by Alice and Bob, and are optimized over arbitrary joint operations by Alice and Bob. These quantities are also easily evaluated.

The lower bounds (10)(c) and (f) are not extensive. To obtain a large lower bound on the expression
\[
\min_{F : C \rightarrow CC'} I(C : C' | X)_{F(\rho)}
\]
limited only by the dimension, we choose an equiprobable ensemble of two states \( \rho^0_C \) and \( \rho^1_C \), where the former represents the uniform distribution and the latter the ‘staircase’ distribution; see Figure 1. We show that if the error is a small constant \( \varepsilon \approx 1/d^4 \), then the only strategy Alice can employ is to send the register \( C \) to Bob. For this, we view \( F \) as a transition matrix for probability distributions and show that it must be close to the identity matrix. We obtain the following.

**Theorem 1.** The following holds for the ensemble of two equiprobable states \( \{\rho^0_C, \rho^1_C\} \), where \( |C| = d \), \( \rho^0_C = I/d \), \( \rho^1_C \) is diagonal, with \((c, c)\)-entry being \((d - c + 1)/\eta\), and \( \eta = d(d + 1)/2 \). The achievable rate for entanglement-assisted blind compression is at least \((\log d) - 7\) bits, while the Holevo information \( I(X : C)_{\rho} \) is at most 1. The lower bound holds for both global and local errors of \( \varepsilon \approx 1/d^4 \), which is independent of the number of instances \( n \). Thus the information defect at non-vanishing local error can be arbitrarily large, and near maximal for the dimension.

![Figure 1: The two distributions in our example. The red line is the uniform distribution and the blue line is the staircase distribution. Here, \( d = |C| \) and \( \eta = d(d+1)/2 \).](image)

Our proof highlights a ‘strong no-cloning principle’ in the classical setting. To clarify, observe that Alice and Bob cannot transform (or clone) \( \rho^0_C \rightarrow \rho^0_C \otimes \rho^0_C' \) without the knowledge of \( x \). This translates to the statement that \( \min_{F : C \rightarrow CC'} I(C : C' | X)_{F(\rho)} \) is bounded away from 0 in (10)(c). Theorem 1 goes further to show that the only way to produce the register \( C' \) creates a lot of correlation between \( C \) and \( C' \). This is akin to the situation in quantum no-cloning; the operation \( |i\rangle_C \rightarrow |i\rangle_C |i\rangle_{C'} \) leads to a large correlation when applied to a state \( \sum_i \alpha_i |i\rangle_C \) in superposition.

### 1.3 Conclusion

In this work, we study the problem of blind compression of quantum data, in the regime of finite error. Our inspiration comes from two sources. First is the visible scenario, where the trade-off between global
error and communication rate is very well understood (providing a strong converse rate) and the trade-off between local error and communication rate is relatively well understood. Second is the Koashi-Imoto characterization, which gives the optimal rate of communication as the error vanishes in the asymptotic limit and hence shows a near maximal separation between the communication rate and the Holevo information in the vanishing error regime. In their converse bound for non-vanishing error, the error dependence of the rate is not explicitly given, and we have observed sensitivity to error in the appendix. Thus the Koashi-Imoto characterization does not immediately apply to the current regime of non-vanishing (global or local) error.  

Our main result resolves this problem, showing a near maximal separation of the rate from the Holevo information in the non-vanishing local error regime. For this, we prove a new lower bound that is based on a variant of the no-cloning theorem for classical distributions. Our technical proof builds on an approximate version of the Birkoff-von Neumann theorem.

An immediate question raised by our work is to understand the error vs communication rate trade-off for the blind compression scenario, for the cases of global and local errors. Furthermore, we ask if a strong converse rate exists for the blind compression scenario when the global error is finite, which is known to hold for the visible case. Finally, we highlight that our lower bound does not entirely rely on the spatial separation between the sender and the receiver, which leads to the question of further applicability of our techniques to other problems.

2  Notations and information theoretic quantities used

2.1  Basic notions in quantum information theory

Throughout the paper, log is taken base 2. For a finite set $C$, a probability distribution is a function $p : C \rightarrow [0, 1]$ satisfying $\sum_{c \in C} p(c) = 1$. In this paper, we only consider finite dimensional Hilbert spaces. Consider such a Hilbert space $\mathcal{H}$ endowed with an inner product $\langle \cdot, \cdot \rangle$. For an operator $X$ acting on $\mathcal{H}$, the Schatten-1 norm of $X$ is defined as $\|X\|_1 := \text{Tr} \sqrt{X^\dagger X}$ and the Schatten-2 norm is defined as $\|X\|_2 := \sqrt{\text{Tr} X X^\dagger}$. A quantum state is represented by a density matrix $\rho$, which is a positive semi-definite operator on $\mathcal{H}$ with trace equal to 1. The quantum state $\rho$ is pure if and only if its density matrix is rank 1, in which case $\rho = |\psi\rangle \langle \psi|$ for some unit vector $|\psi\rangle \in \mathcal{H}$. Throughout the paper, we may use $\psi$ to represent the quantum state and also the density matrix $|\psi\rangle \langle \psi|$. Given a quantum state $\rho$ on $\mathcal{H}$, the support of $\rho$, denoted $\text{supp}(\rho)$, is the subspace of $\mathcal{H}$ spanned by all eigenvectors of $\rho$ with positive eigenvalues.

A quantum register $A$ is associated with some Hilbert space $\mathcal{H}_A$. Define $|A| := \text{dim}(\mathcal{H}_A)$. Let $\mathcal{L}(A)$ represent the set of all linear operators on $\mathcal{H}_A$. We denote the set of quantum states on the Hilbert space $\mathcal{H}_A$ by $\mathcal{D}(A)$. The quantum state $\rho$ with subscript $A$ indicates $\rho_A \in \mathcal{D}(A)$. If two registers $A, B$ are associated with isomorphic Hilbert spaces (that is, of the same dimension), we write $A \equiv B$. Two disjoint registers $A$ and $B$ combined, denoted as $AB$, is associated with the tensor product Hilbert space $\mathcal{H}_A \otimes \mathcal{H}_B$. For two operators $M_1 \in \mathcal{L}(A)$ and $M_2 \in \mathcal{L}(B)$, $M_1 \otimes M_2 \in \mathcal{L}(AB)$ represents the tensor product (Kronecker product) of $M_1$ and $M_2$. The identity operator on $\mathcal{H}_A$ (and its associated register $A$) is denoted as $I_A$.

For any operator $M_{AB} \in \mathcal{L}(AB)$, the partial trace on $A$ is defined as:

$$\text{Tr}_A (M_{AB}) := \sum_i \langle i | \otimes I_B | M_{AB} \rangle (| i \rangle \otimes I_B),$$

where $\{|i\rangle \}$ is an orthonormal basis for the Hilbert space $\mathcal{H}_A$. For a quantum state $\rho_{AB} \in \mathcal{D}(AB)$, we use the shorthand

$$\rho_B := \text{Tr}_A (\rho_{AB})$$

and the quantum state $\rho_B \in \mathcal{D}(B)$ is referred to as the marginal quantum state of $\rho_{AB}$. Unless otherwise stated, a missing register from the subscript of a quantum state represents a partial trace over that register.
A quantum state $\rho_{AB}$ is classical-quantum with $A$ being the classical register, if it is of the form $\rho_{AB} = \sum_a p_A(a) |a\rangle \langle a| \otimes \rho_B^a$, where $\{|a\rangle\}$ forms an orthonormal basis, $\{p_A(a)\}$ is a probability distribution and $\rho_B^a \in \mathcal{D}(B)$. The value $a$ stored in register $A$ identifies a corresponding quantum state $\rho_B^a$ on register $B$. This convention allows a clear distinction between having a specimen of the state $\rho_B^a$ (having system $B$) and knowing what it is (having system $A$). If all $\rho_B^a$ are diagonal in the same basis, $\rho_{AB}$ is called classical-classical or simply classical.

A quantum channel $\mathcal{E} : \mathcal{L}(A) \rightarrow \mathcal{L}(B)$ is a completely positive and trace preserving (CPTP) linear map. (We sometimes just call it a “map” in this paper.) In particular, it takes quantum states in $\mathcal{D}(A)$ to the quantum states in $\mathcal{D}(B)$. A quantum measurement (or instrument) $\mathcal{N} : \mathcal{L}(A) \rightarrow \mathcal{L}(A'C)$ is characterized by a collection of operators $\{N_c : \mathcal{H}_A \rightarrow \mathcal{H}_{A'}\}$ that satisfy $\sum_c N_c^\dagger N_c = I_A$ and is given by

$$\mathcal{N}(\rho_A) = \sum c |c\rangle \langle c| \otimes N_c \rho_A N_c^\dagger.$$ 

A unitary operator $U_A : \mathcal{H}_A \rightarrow \mathcal{H}_A$ is such that $U_A^\dagger U_A = U_A U_A^\dagger = I_A$.

### 2.2 List of quantum information theoretic quantities

We consider the following information theoretic quantities. All logarithms are base 2 and only normalized quantum states are considered in the definitions below. Let $\varepsilon \in (0, 1)$.

1. **Trace distance:** For $\rho_A, \sigma_A \in \mathcal{D}(A)$,
   $$\Delta(\rho_A, \sigma_A) := \frac{1}{2} \|\rho_A - \sigma_A\|_1.$$ 

2. **Fidelity:** For $\rho_A, \sigma_A \in \mathcal{D}(A)$,
   $$F(\rho_A, \sigma_A) := \|\sqrt{\rho_A} \sqrt{\sigma_A}\|_1.$$ 

3. **$\varepsilon$-ball:** For $\rho_A \in \mathcal{D}(A)$,
   $$B_\varepsilon(\rho_A) := \{\rho'_A \in \mathcal{D}(A) | \Delta(\rho_A, \rho'_A) \leq \varepsilon\}.$$ 

4. **Von Neumann entropy:** For $\rho_A \in \mathcal{D}(A)$,
   $$S(\rho_A) := -\text{Tr}(\rho_A \log \rho_A).$$ 

5. **Conditional entropy:** For $\rho_{AB} \in \mathcal{D}(AB)$,
   $$S(AB)_\rho := S(AB)_\rho - S(B)_\rho.$$ 

6. **Relative entropy:** For $\rho_A, \sigma_A \in \mathcal{D}(A)$ such that $\text{supp}(\rho_A) \subset \text{supp}(\sigma_A)$,
   $$\mathcal{D}(\rho_A \| \sigma_A) := \text{Tr}(\rho_A \log \rho_A) - \text{Tr}(\rho_A \log \sigma_A).$$ 

7. **Mutual information:** For $\rho_{AB} \in \mathcal{D}(AB)$,
   $$I(A : B)_\rho := S(AB)_\rho + S(B)_\rho - S(A)_\rho = \mathcal{D}(\rho_{AB} \| \rho_A \otimes \rho_B).$$ 

8. **Conditional mutual information:** For $\rho_{ABC} \in \mathcal{D}(ABC)$,
   $$I(A : B| C)_\rho := I(A : BC)_\rho - I(A : C)_\rho.$$
2.3 Basic facts used in our proofs

Fact 1 (Triangle inequality for trace distance, [37], Chapter 9). For quantum states \( \rho, \sigma, \tau \in \mathcal{D}(A) \),
\[
\Delta(\rho, \sigma) \leq \Delta(\rho, \tau) + \Delta(\tau, \sigma).
\]

Fact 2 (Data-processing inequality, [38] [39]). For the quantum states \( \rho, \sigma \in \mathcal{D}(A), \theta \in \mathcal{D}(AC) \) and the quantum channel \( \mathcal{E} : \mathcal{L}(A) \to \mathcal{L}(B) \), it holds that
\[
\Delta(\rho, \sigma) \geq \Delta(\mathcal{E}(\rho), \mathcal{E}(\sigma)),
\]
\[
\mathcal{D}(\rho\|\sigma) \geq \mathcal{D}(\mathcal{E}(\rho)\|\mathcal{E}(\sigma)),
\]
\[
\mathcal{I}(A : C)_{\theta} \geq \mathcal{I}(B : C)_{\mathcal{E}(\theta)}.
\]

Fact 3 (Pinsker’s inequality, [40]). For the quantum states \( \rho, \sigma \in \mathcal{D}(A) \),
\[
\Delta(\rho, \sigma)^2 \leq \frac{1}{2} \mathcal{D}(\rho\|\sigma).
\]

Fact 4 (Dimension bound). For the quantum state \( \rho_{XAB} \), with classical register \( X \), it holds that
\[
\mathcal{I}(A : X|B)_{\rho} \leq \log |X|.
\]

Fact 5 (Alicki-Fannes-Winter inequality, [41] [42]). For quantum-classical states \( \rho_{AB} \) and \( \sigma_{AB} \) satisfying \( \rho_B = \sigma_B \),
\[
|\mathcal{S}(A|B)_{\rho} - \mathcal{S}(A|B)_{\sigma}| \leq \Delta(\rho_{AB}, \sigma_{AB}) \cdot \log |A| + 1,
\]
\[
|\mathcal{I}(A : B)_{\rho} - \mathcal{I}(A : B)_{\sigma}| \leq \Delta(\rho_{AB}, \sigma_{AB}) \cdot \log |B| + 1.
\]

Fact 6 (Fano’s inequality, [43]). For any classical state \( \rho_{AA'} = \sum_{a,a'} p_{AA'}(a,a')|a,a'\rangle\langle a,a'|, \) with \( p_{AA'} \) a probability distribution, it holds that
\[
\mathcal{S}(A|A')_{\rho} \leq 1 + \Pr[A \neq A'] \log |A|.
\]

Note that we have stated weaker versions of Alicki-Fannes-Winter inequality and Fano’s inequality that simplify the expressions in our results.

3 Lower bound on entanglement-assisted blind distribution compression

For our lower bound on the compression rate, we focus on ensembles of classical states (these can be simultaneously diagonalized). We will henceforth refer to them as distributions. We begin with a formal definition of our task.

Definition 1 (Entanglement-assisted blind distribution compression). Consider an ensemble \( \{p(x), \rho_C^x\} \) where all \( \rho_C^x \)'s are diagonal. Let \( \rho_{XC} \) be as obtained through (7). Let \( \varepsilon \in (0,1) \) be an error parameter and \( n \in \mathbb{N} \). Let the initial joint state between the Referee and Alice be \( \rho_{X_1C_1} \otimes \rho_{X_2C_2} \otimes \ldots \otimes \rho_{X_nC_n} \), with the Referee holding registers \( X_1, X_2, \ldots, X_n \) (each \( X_i \equiv X \)) and Alice holding registers \( C_1, C_2, \ldots, C_n \) (each \( C_i \equiv C \)). Alice and Bob share entanglement \( |\theta\rangle_{E_AE_B} \), where \( E_A \) is with Alice and \( E_B \) is with Bob. An \( (n,R,\varepsilon) \)-entanglement-assisted blind distribution compression protocol is as follows. Alice applies an encoding map \( \mathcal{E} : C_1C_2\ldots C_nE_A \to C_1C_2\ldots C_nT \), where \( T \) is a classical register of size \( 2^{nR} \). She communicates \( T \) to Bob (so the number of bits communicated in the protocol is \( nR = \log |T| \)). After
receiving $T$, Bob applies a decoding map $D : TE_B \to C'_1 C'_2 \ldots C'_n$. Here, each $C'_i \equiv C$. It is required that
\begin{equation}
\Delta \left( \text{Tr}_{C_1 \cdots C_n} \circ D \circ \mathcal{E} \left( \rho X_1 C_1 \otimes \ldots \otimes \rho X_n C_n \otimes \theta_{E_A E_B} \right), \rho X_1 C'_1 \otimes \ldots \otimes \rho X_n C'_n \right) \leq \varepsilon. \tag{4}\end{equation}
The above definition involves a global error for the compression. Our lower bounds apply also to the more relaxed setting of the local error model:
\begin{equation}
\forall i \Delta \left( \text{Tr}_{C'_1 \ldots C'_{i-1} C_i C_{i+1} \ldots C'_n} \circ D \circ \mathcal{E} \left( \rho X_1 C_1 \otimes \ldots \otimes \rho X_n C_n \otimes \theta_{E_A E_B} \right), \rho X_i C'_i \right) \leq \varepsilon. \tag{5}\end{equation}

Note that the definition uses classical communication, which is equivalent to quantum communication up to a factor of 2 when entanglement is free.

Since the ensemble is classical, Alice can always retain the information in the registers $C_1, C_2, \ldots, C_n$, so, without loss of generality, we assume the following equality throughout the discussion.

\begin{equation}
\text{Tr}_T \left( \mathcal{E} \left( \rho X_1 C_1 \otimes \rho X_2 C_2 \otimes \ldots \otimes \rho X_n C_n \otimes \theta_{E_A} \right) \right) = \rho X_1 C_1 \otimes \rho X_2 C_2 \otimes \ldots \otimes \rho X_n C_n. \tag{6}\end{equation}

The following theorem shows a lower bound on the rate of communication $R$ required for the task.

\textbf{Theorem 2.} Let $\rho_{XC}$ be as given in Definition \[1] and $\varepsilon \in (0, 1)$. For any $(n, R, \varepsilon)$-entanglement-assisted blind distribution compression, it holds that
\begin{equation}
R \geq \min_{F : C \rightarrow CC'} \left( I(C : C' | X)_\tau \right) + I(X : C)_\rho - \varepsilon \log |X| - 1,
\end{equation}
where $\tau_{XCC'} := F(\rho_{XC})$ and the map $F$ must satisfy $\Delta(\tau_{XCC'}, \rho_{XC'}) \leq \varepsilon$ and $\tau_{XC} = \rho_{XC}$.

\textbf{Proof.} For brevity, set $X^n = X_1 X_2 \ldots X_n$, $C^n = C_1 C_2 \ldots C_n$ and $C'^n = C'_1 C'_2 \ldots C'_n$. Let $\sigma_{X^n C^n T E_B}$ be the state after Alice’s encoding, and $\tau_{X^n C^n C'^n}$ be the final quantum state at the end of the protocol. Observe that
\begin{equation}
nR = \log |T| \geq I(X^n C^n : T E_B)_{\sigma} \stackrel{(a)}{=} I(X^n C^n : T E_B)_{\sigma} \geq I(X^n C^n : C'^n)_\tau. \tag{7}\end{equation}
The equality $(a)$ in (7) follows from the fact that $I(X^n C^n : E_B)_{\sigma} = 0$. We apply the data processing inequality to obtain $(b)$. Note also from this step onwards, entanglement no longer plays a role in the proof. Now, consider
\begin{align}
I(X^n C^n : C'^n)_\tau &= \sum_{i=1}^{n} I(X_i C_i : C'^n | X_1 \ldots X_{i-1} C_1 \ldots C_{i-1})_\tau \\
&\geq \sum_{i=1}^{n} \left( I(X_i C_i : C'^n X_1 \ldots X_{i-1} C_1 \ldots C_{i-1})_\tau - I(X_i C_i : X_1 \ldots X_{i-1} C_1 \ldots C_{i-1})_\tau \right) \\
&\stackrel{(c)}{=} \sum_{i=1}^{n} I(X_i C_i : C'^n X_1 \ldots X_{i-1} C_1 \ldots C_{i-1})_\tau \\
&\geq \sum_{i=1}^{n} I(X_i C_i : C'_i)_\tau. \tag{8}\end{align}

In (8), the equality $(c)$ holds since (6) ensures that
\begin{equation}
\tau X_i C_i X_1 \ldots X_{i-1} C_1 \ldots C_{i-1} = \rho X_i C_i X_1 \ldots X_{i-1} C_1 \ldots C_{i-1} = \rho X_i C_i \otimes \rho X_1 \ldots X_{i-1} C_1 \ldots C_{i-1},
\end{equation}
and the last step follows from the data processing inequality. From (4), we have $\Delta \left( \tau_{X_i C'_i}, \rho_{X_i C'_i} \right) \leq \varepsilon$. Thus, using the Alicki-Fannes-Winter inequality (Fact[5]), we obtain
\begin{equation}
I(X_i C_i : C'_i)_\tau = I(C_i : C'_i | X_i)_\tau + I(X_i : C'_i)_\tau \geq I(C_i : C'_i | X_i)_\tau + I(X_i : C_i)_\rho - \varepsilon \log |X| - 1. \tag{9}\end{equation}
Combining (7)-(9), we obtain
\[ nR \geq n \min_i \left( I(C_i : C'_i | X_i)_{\mathcal{I}} + I(X_i : C_i)_{\rho} - \varepsilon \log |X| - 1 \right). \]

We can now convert the above asymptotic inequality to a single-letter bound. For an \( i \) that achieves the minimum, define \( \mathcal{F}_i \) to be the map that acts on register \( C_i \) as follows. It first creates the state \( \rho_{X_1C_1} \otimes \cdots \otimes \rho_{X_{i-1}C_{i-1}} \otimes \rho_{X_{i+1}C_{i+1}} \otimes \cdots \otimes \rho_{X_nC_n} \otimes \theta_{E_AE_B} \). Then it applies \( \mathcal{D} \circ \mathcal{E} \) and traces out registers \( X_1, \ldots, X_{i-1}, X_{i+1}, \ldots, X_n, C_1, \ldots, C_{i-1}, C_{i+1}, \ldots, C_n, C'_1, \ldots, C'_i, \ldots, C'_n \). From (4), we conclude that
\[ \Delta \left( \text{Tr}_{C_i \mathcal{F}_i} \rho_{X_{CC'}}, \rho_{X_{CC'}} \right) \leq \varepsilon. \]

Moreover, \( \text{Tr}_{CC'} \mathcal{F}(\rho_{XC}) = \rho_{XC} \), as the maps \( \mathcal{E} \) and \( \mathcal{D} \) do not change the state in registers \( X, C \). Since \( C \equiv C, C'_i \equiv C' \) and \( \rho_{XC} = \rho_{XC} \), the proof concludes.

Theorem 2 shows that the communication cost for entanglement-assisted blind mixed distribution compression can exceed the Holevo information of the distribution \( I(X : C)_{\rho} \). We now show that this additional cost of \( R - I(X : C)_{\rho} \) can be quantitatively bounded by some measure of indistinguishability of the states in the ensemble, and also by some measure of the inability to clone the states. To proceed with this, consider a simple example of compressing two equiprobable distributions, with \( \rho_{XC} = \frac{1}{2} (|0\rangle\langle 0|_X \otimes \rho_0^0 + |1\rangle\langle 1|_X \otimes \rho_1^1) \). For a map \( \mathcal{F} \) satisfying \( \Delta \left( \text{Tr}_C \left( \mathcal{F}(\rho_{XC}) \right) , \rho_{XC} \right) \leq \varepsilon \) and \( \text{Tr}_{CC'} \mathcal{F} \left( \rho_{XC} \right) = \rho_{XC} \), let \( \tau_{XXC'} = \mathcal{F}(\rho_{XC}) \). We will prove the following:

\[
\sqrt{I(C : C' | X)_{\mathcal{F}(\rho_{XC})}} \overset{(a)}{=} \frac{1}{\sqrt{2}} \left( D(\tau_0^0 || \tau_0^0 \otimes \tau_0^0) + D(\tau_1^1 || \tau_1^1 \otimes \tau_1^1) \right) \\
\geq \overset{(b)}{\sqrt{\Delta(\tau_0^0, \tau_0^0 \otimes \tau_0^0) + \Delta(\tau_1^1, \tau_1^1 \otimes \tau_1^1)}} \\
\overset{(c)}{\geq} \frac{1}{\sqrt{2}} \left( \Delta(\tau_0^0 \otimes \tau_0^0, \tau_0^0 \otimes \tau_1^1) + \Delta(\tau_1^1 \otimes \tau_1^1, \tau_0^0 \otimes \tau_0^0) \right) \\
\overset{(d)}{\geq} \frac{1}{2} \left( \Delta(\tau_0^0 \otimes \tau_0^0, \tau_0^0 \otimes \tau_1^1) - \Delta(\tau_0^0 \otimes \tau_0^0, \tau_1^1 \otimes \tau_1^1) \right) \\
\overset{(e)}{\geq} \frac{1}{\sqrt{2}} \left( \Delta(\rho_0^0 \otimes \rho_0^0, \rho_0^0 \otimes \rho_1^1) - \Delta(\rho_0^0 \otimes \rho_0^0, \rho_1^1 \otimes \rho_1^1) \right) - 2\varepsilon \\
\overset{(f)}{\geq} \frac{1}{\sqrt{2}} \left( \Delta(\rho_0^0 \otimes \rho_0^0, \rho_0^0 \otimes \rho_1^1) - \Delta(\rho_0^0 \otimes \rho_0^0, \rho_1^1 \otimes \rho_1^1) \right) - 2\varepsilon. \tag{10}
\]

Here, (a) uses the expansion
\[ I(C : C' | X)_{\mathcal{F}(\rho_{XC})} = I(C : C' | X)_{\tau} = \sum_x p(x) D(\tau_0^x || \tau_0^x \otimes \tau_0^x) \]

and (b) uses Pinsker’s inequality (Fact 3), (c) follows from the inequality \( a^2 + b^2 \geq \frac{(a+b)^2}{2} \), (d) uses the triangle inequality for trace distance, (e) uses the identity \( \tau_0^x = \tau_0^x \), and the inequality \( \Delta(\tau_{XXC'}, \rho_{XXC'}) = \frac{1}{2} \Delta(\tau_0^{0,C}, \rho_0^{0,C}) + \frac{1}{2} \Delta(\tau_1^{1,C}, \rho_1^{1,C}) \leq \varepsilon \) and (f) uses the data-processing inequality (Fact 2) to conclude that \( \Delta(\tau_0^{0,C}, \rho_0^{0,C}) = \Delta \left( \mathcal{F} \left( \rho_0^{0,C} \right) , \mathcal{F} \left( \rho_0^{1,C} \right) \right) \leq \Delta(\rho_0^{0,C}, \rho_1^{1,C}) \).

Furthermore, the above chain of inequalities quantitatively relate the gap between the communication cost and the Holevo information to other quantitative properties of the ensemble. Recall that \( \tau_0^x = \rho_0^x \), so the RHS of the inequality (c) lower-bounds the gap by a “classical no-cloning bound”, which is the average distance between two copies of \( \rho_0^x \) and the actual Alice-Bob joint-output. Furthermore, the RHS of the inequality (f) says that the gap is lower-bounded by the increase in distinguishability of \( \rho_0^x \) and \( \rho_1^x \) if a second copy is available, which is a measure of the indistinguishability between \( \rho_0^{0,1} \).
This gap can be strictly positive for some ensemble. For example, consider:
\[
\rho_C^0 = \left(\begin{array}{cc}
\frac{1}{2} & 0 \\
0 & \frac{1}{2}
\end{array}\right), \quad \rho_C^1 = \left(\begin{array}{cc}
\frac{1}{3} & 0 \\
0 & \frac{2}{3}
\end{array}\right),
\]
We evaluate
\[
\Delta(\rho_C^0, \rho_C^1) = \frac{1}{2} \left(\left|\frac{1}{2} - 1\right| + \left|\frac{1}{2} - 2\right|\right) = \frac{1}{6}
\]
and
\[
\Delta(\rho_C^0 \otimes \rho_C^0, \rho_C^1 \otimes \rho_C^1) = \frac{1}{2} \left(\left|\frac{1}{4} - 1\right| + 2\left|\frac{1}{4} - 2\right| + \left|\frac{1}{4} - 4\right|\right) = \frac{7}{36}.
\]
We conclude that \(\Delta(\rho_C^0 \otimes \rho_C^0, \rho_C^1 \otimes \rho_C^1) - \Delta(\rho_C^0, \rho_C^1) = \frac{1}{36}\). Thus,
\[
I(C : C' | X)_{F(\rho)} \geq \frac{(1 - 72\varepsilon)^2}{2 \cdot 6^4}.
\]
This example demonstrates a constant lower bound on the information defect. In the next section, we develop a large lower bound that is nearly maximal given the dimension of \(C\).

4 Near maximal separation between information cost and the communication cost

In this section, we prove Theorem[1]. The proof will proceed in the following steps.

- We will simplify the form of the map \(F\) by observing that the input and the output are classical. This will also lead to a simpler lower bound than given in Theorem[2] in terms of stochastic maps.
- We will show the utility of the simpler lower bound first in the case of zero error. We will show that the stochastic map under consideration is actually doubly stochastic, since one of the two distributions in the ensemble is uniform. Then we apply the Birkoff-von Neumann theorem to show that the only relevant doubly stochastic map is the identity map, which implies our lower bound.
- Finally, we will consider the case of non-zero error. We will show that the stochastic map under consideration is close to a doubly stochastic map. Then we will analyze the action of this doubly stochastic map on the distributions in the ensemble. Since the doubly stochastic map keeps the distributions approximately unchanged, we bound its distance from the identity map. This will lead to the desired lower bound for the communication cost.

4.1 Stochastic maps and the distribution

Recall the state \(\rho_{XC}\), the map \(F\) and the state \(\tau_{XCC'}\) in Theorem[2]. We start with the observation that, despite the fact that the map \(F\) involves entanglement, the state \(\tau_{XCC'} = F(\rho_{XC})\) can be considered to be completely classical, without loss of generality. To see this, consider the constraints
\[
\Delta(\text{Tr}_C (F(\rho_{XC})), \rho_{XC'}) \leq \varepsilon
\]
and \(\text{Tr}_{C'}F(\rho_{XC}) = \rho_{XC}\) as in Theorem[2]. Let \(F'\) be the map resulting from measuring the register \(C'\) after applying \(F\) to \(\rho_{XC}\). Then it still holds that
\[
\Delta(\text{Tr}_C (F'(\rho_{XC})), \rho_{XC'}) \leq \Delta(\text{Tr}_C (F(\rho_{XC})), \rho_{XC'}) \leq \varepsilon
\]
and \( \text{Tr}_{C'\tau} \mathcal{F}'(\rho_{XC}) = \rho_{XC} \), so the constraints are still satisfied, and moreover

\[
I(C : C' | X)_{\mathcal{F}'(\rho)} \leq I(C : C' | X)_{\mathcal{F}(\rho)}
\]

by the data processing inequality. Therefore in Theorem 2, it suffices to restrict to maps \( \mathcal{F} \) with completely classical \( \tau_{XCC'} \), which has the form

\[
\tau_{XCC'} = \sum_{x,c,c'} p_{XXC'}(x,c,c')|x,c,c'\rangle\langle x,c,c'|.
\]

(Note that \( p_{XXC'}(x,c,c') \) satisfies the Markov chain condition \( p_{XX'|C=c}(x',c') = p_X|C=c(x) p_{C'|C=c}(c') \), as the map \( \mathcal{F} \) produces \( C' \) from \( C \). Define a matrix \( M \) with

\[
M_{c,c'} = p_{C'|C=c}(c').
\]

Clearly, \( M \) is a stochastic matrix: \( \forall c \sum_{c'} M_{c,c'} = 1 \). Therefore each distribution on \( C \) is mapped to a distribution on \( C' \). The rest of the paper revolves about understanding this stochastic matrix \( M \). First, we view \( M \) as a ‘channel’ between Alice and Bob that inputs \( C \) and outputs \( C' \), and appeal to Fano’s inequality (Fact 6) to bound the information between \( C \) and \( C' \) in terms of the probability of \( C \) being equal to \( C' \).

This concludes the proof.

The ensemble. Using Claim 1, our strategy to obtain a large gap between the communication cost for compression and the Holevo information is to construct ensembles for which \( \sum_c p_C(c) M_{c,c} \approx 1 \), which implies \( I(C : C' | X)_{\tau} \approx S(C | X)_{\rho} \). We now define our ensemble using the following notations. Let \( d = |C|, c \in \{1,2,\ldots,d\}, x \in \{0,1\} \), and \( p_X(0) = p_X(1) = \frac{1}{2} \). We choose the states \( \rho_C^{0} \) and \( \rho_C^{1} \) to correspond to the uniform and ‘staircase’ distributions (see Figure 1 and also Theorem 1), defined as follows.

\[
p_{C|X=0}(c) = \frac{1}{d} =: u_c, \quad p_{C|X=1}(c) = \frac{d-c+1}{\eta} =: v_c, \quad \eta = \frac{d(d+1)}{2}.
\]

We use \( u \) to denote the row vector with the \( c \)-th entry being \( u_c \), and similarly for \( v \).
4.2 Lower bound in the zero error case

To illustrate the principles in the general case, we first consider the zero-error case where \( \varepsilon = 0 \). In this case, we have \( \tau_{X|C'} = \rho_{X|C'} \). From the definition of the stochastic matrix \( M \) in Equation 12 and the choice of distributions \( p_C|X=0, p_C|X=1 \) given above, we arrive at the following set of equations.

\[
u M = u, vM = v, \tag{15}\]

so both \( u, v \) are fixed points of the transition matrix \( M \). We have the following theorem.

**Theorem 3.** Using aforementioned definitions, (15) implies that \( M_{c,c'} = 1 \) iff \( c' = c \) (i.e., \( M = I \)).

**Proof.** Using the conditions \( uM = u \) and \( u_c = \frac{1}{|C|} \) for all \( c \), (15) implies that

\[\forall c' \sum_c M_{c,c'} = 1.\]

Thus the matrix \( M \) is doubly stochastic. From the Birkhoff-von Neumann theorem \([44, 45, 46]\), there exist permutation matrices \( \Pi_1, \Pi_2, \ldots \Pi_k \) and a probability distribution \((q_1, \ldots q_k)\) such that

\[M = \sum_i q_i \Pi_i. \tag{16}\]

Next, we show that \( M = I \). Without loss of generality, \( \Pi_1 = I \), \( 0 \leq q_1 \leq 1 \). Suppose, by contradiction, \( q_1 < 1 \), so there exists \( i \geq 2 \) with \( q_i > 0 \) and \( \Pi_i \neq I \). Using \( vM = v \) and applying (16),

\[\sum_i q_i (v \Pi_i) = v.\]

Since \( v \Pi_1 = v \), we obtain

\[\frac{1}{1 - q_1} \sum_{i=2}^k q_i (v \Pi_i) = v. \tag{17}\]

We will argue that this is a contradiction for the vector \( v \). A permutation \( \Pi_i \) is said to act “non-trivially” on an index \( j \in [d] \) if \( j \) is not invariant under \( \Pi_i \). Let \( j_0 \in [d] \) be the smallest index such that at least one of the permutations in the set \( \{\Pi_i\}_{i=2}^k \) act non-trivially on \( j_0 \). Since \( \Pi_i \neq I \) for \( i = 2, 3, \ldots, k \), such an index \( j_0 \) must exist. This implies the following:

1. \( (v \Pi_i)_j = v_j \) for all \( j < j_0 \), that is, all the permutations act trivially on indices smaller than \( j_0 \).
2. \( (v \Pi_i)_{j_0} \leq v_{j_0} \), as any permutation \( \Pi_i \) swaps the element \( v_{j_0} \) with a potentially smaller element \( v_j \).
3. There is a permutation \( \Pi_{i_0} \) such that \( (v \Pi_{i_0})_{j_0} < v_{j_0} \), by the definition of \( j_0 \).

But items 2, 3 jointly contradict what is implied by the \( j_0 \)-th entry of the vector equality in (17):

\[\frac{1}{1 - q_1} \sum_{i=2}^k q_i (v \Pi_i)_{j_0} = v_{j_0}. \]

Hence we must have \( q_1 = 1 \) and \( M = I \). This completes the proof.

We conclude this subsection with a lower bound on the rate in the zero error case. When \( \varepsilon = 0 \), Theorem 3 implies that \( \sum_c p_C(c)M_{c,c} = 1 \). Substituting this into Claim 1

\[I(C : C'|X) \geq S(C|X) - \varepsilon \log(|C|).\]

Substituting this into Theorem 2,

\[R \geq I(X : C) - \varepsilon (\log(|C|) + 1) - 1 \approx I(X : C) + \alpha \log(|C|)\]

for some constant \( \alpha \). In the next subsection, we proceed to the case of small error \( \varepsilon \). We will generalize the intuition from the zero-error case in which \( v \) is a vertex of the polytope formed by the convex hull of \( \{v \Pi_i\}_{i=1}^k \).
4.3 Lower bound for the case of non-zero error

In this case, Theorem 2 ensures that \( \Delta (\tau_{XC}, \rho_{XC}) \leq \varepsilon \). Using the distribution \( p_{XCC'} \) from Equation 11, this translates to

\[
\sum_x p_X(x) \sum_{c'} \left| p_{C|X=x}(c') - p_{C'|X=x}(c') \right| \leq 2\varepsilon.
\]

For the rest of this paper, we continue to use the symbols \( M, u, v \) defined earlier (see Equations 12 and 14). Translating the above in terms of \( M, u, v \), and using the fact \( p_X(0) = p_X(1) = \frac{1}{2} \),

\[
\frac{1}{2} (\|u - uM\|_1 + \|v - vM\|_1) \leq 2\varepsilon.
\]

In particular,

\[
\|u - uM\|_1 \leq 4\varepsilon \quad \text{and} \quad \|v - vM\|_1 \leq 4\varepsilon.
\]

We are ready to obtain our lower bound in spirits similar to the zero-error case. First, we will use the condition concerning \( u \) in (18) to approximate \( M \) by a doubly stochastic matrix \( N \) (Lemma 1 part (a)). Then we approximate \( vM \) by \( vN \) (Lemma 1 part (b)). With this approximation, and with the condition on \( v \) in (18), we lower bound the identity component of \( N \) which in turns lower bound \( N_{c,c} \) and then \( M_{c,c} \) and the last bound gives us the desired lower bound on the communication cost for the compression.

Lemma 1. Let \( d \geq 2 \) and \( M \) as defined before. There exists a doubly stochastic matrix \( N \) such that

(a) \( \forall_{c,c'} |N_{c,c'} - M_{c,c'}| \leq 12d\varepsilon \),

(b) \( \|vN - vM\|_1 \leq 12d\varepsilon \).

Proof. Rewriting the condition \( \|u - uM\|_1 \leq 4\varepsilon \) from (18) using \( u_c = \frac{1}{d} \) for all \( c \),

\[
\sum_{c'} \left| \sum_c M_{c,c'} - 1 \right| \leq 4d\varepsilon.
\]

Thus, the matrix \( M \) is a stochastic matrix, but “approximately” a doubly stochastic matrix. In particular, define \( \alpha_{c'} = \sum_c M_{c,c'} - 1 \) which measures how far \( M \) deviates from being doubly stochastic. Using (20),

\[
\forall_{c'} |\alpha_{c'}| \leq 4d\varepsilon.
\]

We can now follow the idea from [47] to find a doubly stochastic matrix \( N \) that approximates \( M \). Define

\[
N_{c,c'} = \frac{1}{1 + 4d\varepsilon} \left( M_{c,c'} + \frac{4d\varepsilon - \alpha_{c'}}{d} \right).
\]

First, note that the entries of \( N_{c,c'} \) are non-negative, as \( M_{c,c'} \geq 0 \) and \( 4d\varepsilon \geq \alpha_{c'} \) for all \( c' \) (according to (21)). Second, \( N \) is stochastic:

\[
\sum_{c'} N_{c,c'} = \frac{1}{1 + 4d\varepsilon} \left( \sum_c M_{c,c'} + \sum_{c'} \frac{4d\varepsilon - \alpha_{c'}}{d} \right) = \frac{1}{1 + 4d\varepsilon} (1 + 4d\varepsilon) = 1,
\]

where we have used the stochastic property of \( M \) to substitute \( \sum_{c'} M_{c,c'} = 1 \), and also \( \sum_{c'} \alpha_{c'} = \sum_{c,c'} M_{c,c'} - d = 0 \). Next we show that \( N \) is doubly stochastic.

\[
\sum_c N_{c,c'} = \frac{1}{1 + 4d\varepsilon} \left( \sum_c M_{c,c'} + \sum_c \frac{4d\varepsilon - \alpha_{c'}}{d} \right) = \frac{1}{1 + 4d\varepsilon} (1 + \alpha_{c'} + 4d\varepsilon - \alpha_{c'}) = 1.
\]
Now, we bound the entry-wise difference between $M$ and $N$. Consider

\[
N_{c,c'} - M_{c,c'} = \frac{1}{1 + 4d\varepsilon} \left( M_{c,c'} + \frac{4d\varepsilon - \alpha_{c'}}{d} \right) - M_{c,c'}
\]

(22)

Thus,

\[
|N_{c,c'} - M_{c,c'}| \leq \frac{1}{1 + 4d\varepsilon} \left( \left| \frac{4d\varepsilon - \alpha_{c'}}{d} \right| + 4d\varepsilon |M_{c,c'}| \right)
\]

\[
\overset{(a)}{\leq} 8\varepsilon + 4d\varepsilon \leq 12d\varepsilon,
\]

where (a) uses $|M_{c,c'}| \leq 1$ and $|4d\varepsilon - \alpha_{c'}| \leq 8d\varepsilon$, in turns followed from (21). This proved claim (a).

For claim (b), define a matrix $W$ as $W_{c,c'} = \frac{4d\varepsilon - \alpha_{c'}}{d(1+4d\varepsilon)}$. Equation (22) states that

\[
N - M = W - \frac{4d\varepsilon}{1 + 4d\varepsilon} M.
\]

Thus,

\[
\|vN - vM\|_1 = \left\| vW - \frac{4d\varepsilon}{1 + 4d\varepsilon} vM \right\|_1
\]

\[
\leq \|vW\|_1 + \frac{4d\varepsilon}{1 + 4d\varepsilon} \|vM\|_1
\]

\[
\overset{(a)}{=} \|vW\|_1 + \frac{4d\varepsilon}{1 + 4d\varepsilon}
\]

\[
= \frac{1}{1 + 4d\varepsilon} \left( \sum_{c'} \left| \frac{4d\varepsilon - \alpha_{c'}}{d} \left( \sum_{c} v_c \right) \right| \right) + \frac{4d\varepsilon}{1 + 4d\varepsilon}
\]

\[
\leq \sum_{c'} \left| \frac{4d\varepsilon - \alpha_{c'}}{d} \right| + 4d\varepsilon
\]

\[
\overset{(b)}{\leq} 8d\varepsilon + 4d\varepsilon \leq 12d\varepsilon
\]

In the above, step (a) uses the fact that $vM$ is a probability distribution so $\|vM\|_1 = 1$ and step (b) uses (20) to substitute $\sum_{c'} |\alpha_{c'}| \leq 4d\varepsilon$. This completes the proof.

Now, we are ready to prove our main result, using the condition $\|v - vM\|_1 \leq 4\varepsilon$ from (18).

**Theorem 4.** Let $d \geq 2$ and $M$ as defined before. It holds that

\[
\forall_c M_{c,c} \geq 1 - 24d^4 \varepsilon.
\]

**Proof.** Let $N$ be the doubly stochastic matrix as promised in Lemma[1] We start with

\[
\|v - vN\|_1 \leq \|v - vM\|_1 + \|vM - vN\|_1
\]

\[
\overset{(a)}{\leq} 4\varepsilon + 12d\varepsilon \leq 16d\varepsilon.
\]

Here, (a) uses (18) and Lemma[1]
Now, we apply the Birkhoff-von Neumann theorem to write $N = \sum_{i=1}^{k} q_i \Pi_i$, where $\Pi_1 = I$ and $\Pi_2, \cdots, \Pi_k$ are permutation matrices not equal to the identity. If $q_1 = 1$ then we are done so assume $q_1 < 1$, and there exists $i \geq 2$ with $q_i > 0$. We lower bound $\|v - vN\|_1$ as follows.

$$\|v - vN\|_1 = \left\| v - \sum_{i=1}^{k} q_i (v \Pi_i) \right\|_1 = \left\| v - q_1 v - \sum_{i=2}^{k} q_i (v \Pi_i) \right\|_1$$

$$= \left\| (1 - q_1) v - \sum_{i=2}^{k} q_i (v \Pi_i) \right\|_1 = (1 - q_1) \left\| v - \sum_{i=2}^{k} \frac{q_i}{1 - q_1} (v \Pi_i) \right\|_1. \quad (24)$$

The last expression in (24) is lower bounded by the minimum $\ell_1$ distance between the vector $v$ and the convex hull of the vectors $\{v \Pi_i\}_{i=2}^{k}$. As shown in Claim 2 below, this distance is lower bounded by

$$\left\| v - \sum_{i=2}^{k} \frac{q_i}{1 - q_1} (v \Pi_i) \right\|_1 \geq \frac{1}{v_1} \left( \sum_{j} v_j^2 - \max_{i>1} \left( \sum_{j} v_j (v \Pi_i)_j \right) \right).$$

From Claim 3

$$\max_{i>1} \left( \sum_{j} v_j (v \Pi_i)_j \right) \leq \sum_{i} v_i^2 - \frac{1}{\eta^2}.$$ 

This implies

$$\left\| v - \sum_{i=2}^{k} \frac{q_i}{1 - q_1} (v \Pi_i) \right\|_1 \geq \frac{1}{v_1 \eta^2}.$$ 

From (24), we conclude

$$\|v - vN\|_1 \geq (1 - q_1) \frac{1}{v_1 \eta^2},$$

and combining this with (23), we find

$$(1 - q_1) \frac{1}{v_1 \eta^2} \leq 16d \varepsilon \Rightarrow 1 - q_1 \leq 16d \varepsilon v_1 \eta^2 \leq 16d^4 \varepsilon. \quad (25)$$

Since $N_{c,c} \geq q_1$, we finally conclude from Lemma 1 and (25) that

$$M_{c,c} \geq N_{c,c} - 12d \varepsilon \geq q_1 - 12d \varepsilon \geq 1 - 24d^4 \varepsilon.$$ 

Here we used $d \geq 2$ to substitute $16d^4 \varepsilon + 12d \varepsilon \leq 24d^4 \varepsilon$. This completes the proof.

The following claims were used in the proof.

**Claim 2.** Let $v, w_1, \ldots, w_s$ be vectors in $\mathbb{R}^n$ with non-negative entries. Suppose $v_1$ is the largest entry of $v$, and $v_1 > 0$. It holds that

$$\min_{r_1, \ldots, r_s \in [0,1]: \sum_i r_i = 1} \left\| v - \sum_i r_i w_i \right\|_1 \geq \frac{1}{v_1} \left( \sum_j v_j^2 - \max_i \left( \sum_j v_j (w_i)_j \right) \right).$$
Proof. We use the fact that \( \|u\|_1 = \max_{m_1, \ldots, m_n \in [-1,1]} \sum_j u_j m_j \) to write

\[
\min_{r_1, \ldots, r_s \in [0,1]: \sum_i r_i = 1} \|v - \sum_i r_i w_i\|_1
\]

\[
= \min_{r_1, \ldots, r_s \in [0,1]: \sum_i r_i = 1} \max_{m_1, \ldots, m_n \in [-1,1]} \left( \sum_j m_j \left( v_j - \sum_i r_i (w_i)_j \right) \right)
\]

\[
= \min_{r_1, \ldots, r_s \in [0,1]: \sum_i r_i = 1} \max_{m_1, \ldots, m_n \in [-1,1]} \left( \sum_j m_j v_j - \sum_i r_i m_j (w_i)_j \right)
\]

\[
\overset{(a)}{=} \max_{m_1, \ldots, m_n \in [-1,1]} \min_{r_1, \ldots, r_s \in [0,1]: \sum_i r_i = 1} \left( \sum_j m_j v_j - \sum_i r_i m_j (w_i)_j \right)
\]

\[
\overset{(b)}{=} \max_{m_1, \ldots, m_n \in [-1,1]} \left( \sum_j m_j v_j - \max_i \left( \sum_j m_j (w_i)_j \right) \right)
\]

\[
\overset{(c)}{\geq} \frac{1}{v_1} \left( \sum_j v_j^2 - \max_i \left( \sum_j (w_i)_j \right) \right)
\]

Here (a) uses the minimax theorem [48], (b) chooses the optimal \( \{r_1, \ldots, r_s\} \) to maximize

\[
\sum_{i,j} r_i m_j (w_i)_j = \sum_i r_i \left( \sum_j m_j (w_i)_j \right)
\]

and (c) chooses \( m_i = \frac{v_i}{v_1} \in [0,1] \). This completes the proof. \( \Box \)

Claim 3. Let \( \{v_1, v_2, \ldots, v_n\} \) be a vector and define \( \gamma := \min_{i \neq j} |v_i - v_j| \). It holds that

\[
\max_{\Pi \neq I} \left( \sum_j v_j (v_{\Pi})_j \right) = \sum_j v_j^2 - \gamma^2,
\]

where the maximization is over all permutations \( \Pi \) not equal to identity. In particular, for the vector \( v \) in our ensemble (see Equation 14 with \( n \) replaced by \( d \)), we have \( \gamma = \frac{1}{\eta} \) and

\[
\max_{\Pi \neq I} \left( \sum_j v_j (v_{\Pi})_j \right) = \sum_j v_j^2 - \frac{1}{\eta^2}.
\]

Proof. We recall that \( \Pi \) can be decomposed as a product of disjoint cycles \( C_1, C_2, \ldots C_s \). If \( \Pi \) leaves an index unchanged, we will view the action of \( \Pi \) on this index as a ‘trivial cycle’ of size 1. Let \( L_k \) be the set of indices on which the cycle \( C_k \) acts. Since the cycles are disjoint,

\[
\sum_j v_j (v_{\Pi})_j = \sum_{k=1}^{s} \sum_{j \in L_k} v_j (v_{C_k})_j.
\]

Consider the expression \( \sum_{j \in L_k} v_j (v_{C_k})_j \). Let \( |L_k| \) be the number of elements in \( L_k \). Relabel the elements in \( L_k \) with integers \( \{0, 1, \ldots, |L_k| - 1\} \) in a manner that \( C_k(m) = m + s \mod |L_k| \), for some integer \( s \).
Then
\[
\sum_{j \in L_k} v_j (vC_k)_j = \sum_{m=0}^{|L_k|-1} v_m v_{m+s} \mod |L_k|
\]
\[
= \frac{1}{2} \sum_{m=0}^{|L_k|-1} \left( v_m^2 + v_{m+s}^2 \mod |L_k| - (v_m - v_{m+s} \mod |L_k|)^2 \right)
\]
\[
= \sum_{m=0}^{|L_k|-1} v_m^2 - \frac{1}{2} \sum_{m=0}^{|L_k|-1} (v_m - v_{m+s} \mod |L_k|)^2
\]
\[
\leq \sum_{m=0}^{|L_k|-1} v_m^2 - \gamma^2 \cdot \lfloor |L_k|/2 \rfloor = \sum_{j \in L_k} v_j^2 - \gamma^2 \cdot \lfloor |L_k|/2 \rfloor.
\]

Here (a) follows by noticing that \((v_m - v_{m+s} \mod |L_k|)^2 \geq \gamma^2\). Combining with (26), we find that
\[
\sum_{j} v_j (v\Pi)_j \leq \sum_{k=1}^{s} \left( \sum_{j \in L_k} v_j^2 - \gamma^2 \cdot \lfloor |L_k|/2 \rfloor \right) = \sum_{j} v_j^2 - \gamma^2 \cdot \left( \sum_{k=1}^{s} \lfloor |L_k|/2 \rfloor \right).
\]

Since \(\Pi\) is not the identity permutation, there is a \(C_k\) of length at least 2. Thus, \(\sum_{k=1}^{s} \lfloor |L_k|/2 \rfloor \geq 1\) and
\[
\max_{\Pi} \left( \sum_{j} v_j (v\Pi)_j \right) \leq \sum_{j} v_j^2 - \gamma^2.
\]

To show that the right hand side is achieved, choose \(\Pi\) to be any permutation that swaps a pair of consecutive indices and leaves every other index unchanged. This completes the proof. \(\square\)

### 4.4 Final lower bound

Theorem 4 says that \(M_{c,c} \geq 1 - 24d^4 \varepsilon\) for all \(c\). If we choose \(\varepsilon = \frac{1}{24d^4 \log d}\), we conclude that for all \(c\)
\[
M_{c,c} \geq 1 - \frac{1}{\log d}.
\]

Thus, the lower bound in Claim 1 takes the form
\[
I(C : C' | X) \geq S(C | X)_{\rho} - 2 - \left( 1 - \sum_{c} p_C(c) M_{c,c} + \varepsilon \right) \log (d) \geq S(C | X)_{\rho} - 4.
\]
The conditional entropy can be evaluated to be

\[
S(C|X)_\rho = \frac{1}{2} \left( S(C)_{\rho_0} + S(C)_{\rho_1} \right)
\]

\[
= \frac{1}{2} \log d + \frac{1}{2} \left( \sum_c v_c \log \frac{1}{v_c} \right)
\]

\[
= \frac{1}{2} \log d + \frac{1}{2} \left( \sum_c v_c \log \frac{\eta}{d - c + 1} \right)
\]

\[
= \frac{1}{2} \log d + \frac{1}{2} \left( \log \eta - \sum_c v_c \log (d - c + 1) \right)
\]

\[
\geq \frac{1}{2} \log d + \frac{1}{2} \left( \log \eta - \sum_c \frac{\eta (d - c + 1)^2}{\eta} \right)
\]

\[
= \frac{1}{2} \log d + \frac{1}{2} \left( \log \frac{d(d+1)}{2} - \log \left( \frac{d(d+1)(2d+1)}{3d(d+1)} \right) \right)
\]

\[
= \frac{1}{2} \log d + \frac{1}{2} \left( \log \frac{3d(d+1)}{4d+2} \right) \geq (\log d) - 1.
\]

Here (a) follows from concavity of \( \log \) and (b) follows by substituting the value of \( \eta \). This leads to the lower bound

\[
I(C : C'|X)_\tau \geq (\log d) - 5.
\]

Thus, from Theorem 2 we have a state \( \rho_{XC} \) such that the asymptotic rate of communication for local error \( \varepsilon = \frac{1}{24d^4 \log d} \) is at least \( (\log d) - 7 \) while the Holevo information is at most 1. Note that \( d \) is independent of the number of copies \( n \), and \( \varepsilon \) is independent of \( n \) and only depends on \( d \).

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A Koashi-Imoto characterization at non-vanishing error

Koashi and Imoto [15, 16, 17] provide a characterization of the optimal rates of quantum communication, classical communication, and entanglement for \((n, R, \varepsilon)\)-blind compression of general quantum states (defined similarly to the task of blind distribution compression) in the limit where \(n \to \infty\) and the local error \(\varepsilon \to 0\). These results apply to both the unassisted and the entanglement-assisted scenarios.

The Koashi-Imoto characterization of \((n, R, \varepsilon)\)-blind compression is achieved by the following structure theorem for any ensemble \(\{p_i, \rho_i\}\). There exists a decomposition of the Hilbert space \(\mathcal{H} = \bigoplus_{\ell=1}^{L} \mathcal{H}^{(\ell)}_J \otimes \mathcal{H}^{(\ell)}_K\), in a manner that \(\rho_i = \bigoplus_{\ell=1}^{L} q_{i,\ell} \rho^{(i,\ell)}_J \otimes \rho^{(i,\ell)}_K\). Here, \(\rho^{(i,\ell)}_J\) and \(\rho^{(i,\ell)}_K\) are normalized density matrices acting on \(\mathcal{H}^{(\ell)}_J\) and \(\mathcal{H}^{(\ell)}_K\) respectively, and \(q_{i,\ell} \geq 0\), \(\sum_{\ell=1}^{L} q_{i,\ell} = 1\). Furthermore, for each \(\ell\), \(\{\rho^{(i,\ell)}_J, \rho^{(i,2,\ell)}, \ldots\}\) cannot be expressed in a simultaneously block-diagonal form. The register \(K\) is viewed as redundant, as it has no dependence on \(i\). Without loss of generality, one can restrict the attention to ensembles which have no redundant register \(K\), as the register \(K\) can be removed by Alice and later be generated by Bob without communication between them. The average state \(\rho = \sum_i p_i \rho_i\) can also be written as \(\rho = \bigoplus_{\ell=1}^{L} \rho^{(\ell)}_J \rho^{(\ell)}_J\) where \(\rho^{(\ell)}_J = \sum_i p_i q_{i,\ell} \rho^{(i,\ell)}_J\) and \(\rho^{(\ell)}_J = \frac{1}{p^{(\ell)}_J} \left( \sum_i p_i q_{i,\ell} \rho^{(i,\ell)}_J \right)\). Furthermore, the authors proved that any channel \(\mathcal{E}\) satisfying \(\mathcal{E}(\rho_i) = \rho_i\) acts as the identity map on \(J\).

The characterization in the case of zero error \(\varepsilon = 0\) is now immediate. Let \(\mathcal{P}\) be the combined encoding and decoding map in the protocol. Since the protocol makes no error, \(\mathcal{P}(\rho_i) = \rho_i\) for all \(i\) and hence \(\mathcal{P}\) acts as the identity map on the \(J\) register, leading to \(\log(|J|L)\) as the optimal rate in this case.

To address the regime \(n \to \infty, \varepsilon \to 0\), Koashi and Imoto [16] define \(I_C = -\sum \ell \rho^{(\ell)}_J \log \rho^{(\ell)}_J\) and \(I_Q = \sum \ell \rho^{(\ell)}_J S\left(\rho^{(\ell)}_J\right)\). The ensemble can be compressed at the rates of \(I_C\) bits and \(I_Q\) qubits combined, whereas \(I_C + I_Q = S(\rho)\). To prove optimality of this rate, they introduce two error functions

\[
f(\mathcal{P}) = 1 - \sum_i p_i F(\rho_i, \mathcal{P}(\rho_i))
\]

and

\[
g(\mathcal{P}) = H(\lambda) + \lambda \log(d - 1),
\]

where \(\lambda = 1 - \sum a r(a) \text{Tr}(|a\rangle\langle a| \mathcal{P}(|a\rangle\langle a|))\) and \(|a\rangle, r(a)\) are the eigenvectors and eigenvalues of the average state of the ensemble, \(\rho = \sum_i p_i \rho_i\). The parameter \(f(\mathcal{P})\) captures the error \(\varepsilon\) (up to the difference that we are working in trace distance, whereas they work in fidelity). The parameter \(g(\mathcal{P})\) appears in their lower bound \(R \geq S(\rho) - g(\mathcal{P})\) on the communication cost. They give a continuity argument that if \(f(\mathcal{P}) \to 0\), then \(g(\mathcal{P}) \to 0\).

For non-vanishing error, the dependence of \(\lambda\) on \(f(\mathcal{P})\) and in turn, the dependence of \(g(\mathcal{P})\) on \(f(\mathcal{P})\) (via \(\lambda\)) is important. While \(\lambda \to 0\) as \(f(\mathcal{P}) \to 0\), it is unclear how quickly \(\lambda\) vanishes as \(f(\mathcal{P}) \to 0\). Consequently, \(g(\mathcal{P})\) need not vanish quickly enough to provide a strong lower bound. In our context, we construct a protocol in Theorem 5 exhibiting this sensitivity. We show an example where \(g(\mathcal{P})\) becomes
close to \( \log d \), even if \( f(\mathcal{P}) \approx \frac{1}{\sqrt{d}} \). Thus we know from the example that for two distributions, the lower bound proved by Koashi and Imoto only works for error substantially smaller than \( \frac{1}{d} \).

Another reason to expect that the Koashi-Imoto characterization is sensitive to errors, is as follows. Consider an equiprobable ensemble of two states \( \rho \) and \( \sigma \). When the error \( \epsilon \) (defined in (5)) is finite, we have the conditions \( \Delta(\mathcal{P}(\rho), \rho) \leq 2\epsilon, \Delta(\mathcal{P}(\sigma), \sigma) \leq 2\epsilon \). Does this guarantee that \( \rho \) and \( \sigma \) are respectively close to states \( \tilde{\rho} \) and \( \tilde{\sigma} \) that are fixed points of \( \mathcal{P} \)? If this were the case, we could apply the Koashi-Imoto decomposition to \( \tilde{\rho}, \tilde{\sigma} \) to obtain a large lower bound for the rate for finite \( \epsilon \). Unfortunately this is not true, as witnessed by the channel \( \mathcal{E}(\tau) = (1 - \epsilon)\tau + \frac{2\epsilon^2}{d}I \). This channel satisfies \( \Delta(\mathcal{E}(\tau), \tau) \leq \epsilon \) for all \( \tau \), but its only fixed point is \( \frac{1}{d} \).

Our arguments are made precise in the following protocol for the blind compression of any pair of commuting states \( \rho, \sigma \), with rate significantly less than \( \log(d) \) for non vanishing local error.

**Theorem 5.** Let \( n \) be a positive integer and \( \delta \in (0, \frac{1}{2}), \gamma \in (0, 1) \). Consider the local error model. Given two commuting states \( \rho, \sigma \), there exists an \((n, R, \delta + \gamma)\) blind distribution compression protocol \( \mathcal{P} \) with \( R = 2 \log \log(\frac{n}{\delta}) + 2 \log \frac{1}{\delta} + 3 \).

**Proof.** Without loss of generality, \( \rho, \sigma \) are both diagonal in the computational basis, so, they can be written as 
\[
\rho = \sum_a p(a) |a\rangle \langle a|, \quad \sigma = \sum_a q(a) |a\rangle \langle a| \begin{array}{c}
\text{where} \quad p(a), q(a) \geq 0, \quad \sum_a p(a) = \sum_a q(a) = 1. \\
\end{array}
\]

Let \( u = \left\lceil \frac{\log d}{\log(1 - \delta)} \right\rceil \), so that \( (1 - \delta)^u \leq \frac{1}{n} \). For \( i, j \in \{1, 2, \cdots, u\} \), define the sets
\[
T_{i,j} := \{ a : p(a) \in ((1 - \delta)^i, (1 - \delta)^{i-1}], q(a) \in ((1 - \delta)^j, (1 - \delta)^{j-1}] \},
\]
\[
T_{i,u+1} := \{ a : p(a) \in ((1 - \delta)^i, (1 - \delta)^{i-1}], q(a) \leq (1 - \delta)^u \},
\]
\[
T_{u+1,j} := \{ a : p(a) \leq (1 - \delta)^u, q(a) \in ((1 - \delta)^j, (1 - \delta)^{j-1}] \}
\]
\[
T_{u+1,u+1} := \{ a : p(a) \leq (1 - \delta)^u, q(a) \leq (1 - \delta)^u \}.
\]

The protocol \( \mathcal{P} \) is as follows.

- Alice receives a sample \( a \). She finds the unique \((i, j)\) such that \( a \in T_{i,j} \) and communicates \((i, j)\) to Bob.

- Receiving \((i, j)\), Bob outputs an \( a' \) drawn uniformly from \( T_{i,j} \).

If the input given to Alice is drawn from \( \rho \) (\( \sigma \)), let the output produced by Bob be drawn from \( \rho' \) (\( \sigma' \)). The analysis of the protocol is as follows.

- **Communication cost:** Since there are at most \((u + 1)^2 \) \((i, j)\)'s, it suffices for Alice to communicate \( 2 \log(u + 1) \leq 2((\log u) + 1) \leq 2 \log \frac{d}{\gamma} + 2 \log \frac{1}{\log(1 - \delta)} + 3 \leq 2 \log \frac{d}{\gamma} + 2 \log \frac{1}{\delta} + 3 \) bits to Bob. Note that we have used the inequality \( \frac{1}{-\log(1 - \delta)} \leq \frac{1}{\delta} \) derived from the Taylor series expansion of \( \log(1 - \delta) \).

- **Error analysis:** Let \( p(T_{i,j}) := \sum_{a \in T_{i,j}} p(a) \) and \( q(T_{i,j}) := \sum_{a \in T_{i,j}} q(a) \). We can rewrite \( \rho \) and \( \sigma \) as
\[
\rho = \sum_{i,j=1}^{u+1} \sum_{a \in T_{i,j}} p(T_{i,j}) \frac{p(a)}{p(T_{i,j})} |a\rangle \langle a|, \quad \sigma = \sum_{i,j=1}^{u+1} \sum_{a \in T_{i,j}} q(T_{i,j}) \frac{q(a)}{q(T_{i,j})} |a\rangle \langle a|.
\]

Observe from the protocol that
\[
\rho' = \sum_{i,j=1}^{u+1} \sum_{a \in T_{i,j}} \frac{1}{|T_{i,j}|} |a\rangle \langle a|, \quad \sigma' = \sum_{i,j=1}^{u+1} \sum_{a \in T_{i,j}} \frac{1}{|T_{i,j}|} q(T_{i,j}) \frac{q(a)}{|T_{i,j}|} |a\rangle \langle a|.
\]
So,
\[
\Delta(\rho, \rho') = \Delta \left( \sum_{i,j=1}^{u+1} p(T_{i,j}) \sum_{a \in T_{i,j}} \frac{p(a)}{p(T_{i,j})} |a\rangle\langle a|, \sum_{i,j=1}^{u+1} p(T_{i,j}) \sum_{a \in T_{i,j}} \frac{1}{|T_{i,j}|} |a\rangle\langle a| \right)
\]
\[= \sum_{i,j=1}^{u+1} p(T_{i,j}) \Delta \left( \sum_{a \in T_{i,j}} \frac{p(a)}{p(T_{i,j})} |a\rangle\langle a|, \sum_{a \in T_{i,j}} \frac{1}{|T_{i,j}|} |a\rangle\langle a| \right) \]  
(27)

By definition of the set \(T_{i,j}\) with \(i \leq u\), it holds that \(1 - \delta \leq \frac{p(a_1)}{p(a_2)} \leq \frac{1}{1 - \delta} \) for all \(a_1, a_2 \in T_{i,j}\). Thus, for all \(a \in T_{i,j}\) with \(i \leq u\),
\[
(1 - \delta) \frac{1}{|T_{i,j}|} \leq \frac{p(a)}{p(T_{i,j})} \leq \frac{1}{1 - \delta} \frac{1}{|T_{i,j}|} \implies \frac{p(a)}{p(T_{i,j})} - \frac{1}{|T_{i,j}|} \leq \frac{\delta}{1 - \delta} \frac{1}{|T_{i,j}|}.
\]

So,
\[
\Delta \left( \sum_{a \in T_{i,j}} \frac{p(a)}{p(T_{i,j})} |a\rangle\langle a|, \sum_{a \in T_{i,j}} \frac{1}{|T_{i,j}|} |a\rangle\langle a| \right) \leq \frac{1}{2} \sum_{a \in T_{i,j}} \delta \frac{1}{1 - \delta} \frac{1}{|T_{i,j}|} \leq \frac{\delta}{2(1 - \delta)}.
\]  
(28)

Furthermore,
\[
\sum_{j=1}^{u+1} p(T_{u+1,j}) = \sum_{a: p(a) \leq (1 - \delta)^u} p(a) \leq (1 - \delta)^u \cdot d \leq \gamma.
\]  
(29)

Applying (28), (29), and \(\delta \leq \frac{1}{2}\) to (27),
\[
\Delta(\rho, \rho') \leq \sum_{i=1}^{u} \sum_{j=1}^{u+1} p(T_{i,j}) \frac{\delta}{2(1 - \delta)} + \sum_{j=1}^{u+1} p(T_{u+1,j}) \leq \frac{\delta}{2(1 - \delta)} + \gamma \leq \delta + \gamma.
\]

A similar argument shows that \(\Delta(\sigma, \sigma') \leq \delta + \gamma\). This completes the error analysis.

The correctness of the protocol concludes by running the above protocol independently for each copy to obtain an \((n, R, \delta + \gamma)\) protocol.

Theorem 5 immediately implies that \(g(P)\) is close to \(S(\rho)\) for constant \(\delta, \gamma\), else the lower bound \(R \geq S(\rho) - g(P)\) would contradict the statement of the theorem. We can see this explicitly by evaluating the functions \(f(P)\) and \(g(P)\). Let us continue using the notation in Theorem 5. Since \(\Delta(\rho, \mathcal{P}(\rho)) \leq \delta + \gamma\), the Fuchs-van de graaf inequality implies that \(\mathcal{F}(\rho, \mathcal{P}(\rho)) \geq 1 - 2\delta - 2\gamma\). Similarly, \(\mathcal{F}(\sigma, \mathcal{P}(\sigma)) \geq 1 - 2\delta - 2\gamma\). Hence \(f(P) \leq 2\delta + 2\gamma\). Now, for the given ensemble, \(r(a) = \frac{1}{2} p(a) + \frac{1}{2} q(a)\). Then,
\[
1 - \lambda = \sum_a r(a) \text{Tr}(|a\rangle\langle a| : \mathcal{P}(|a\rangle\langle a|))
\]
\[= \sum_{i,j=1}^{u+1} \sum_{a \in T_{i,j}} r(a) \text{Tr} \left( |a\rangle\langle a| : \left( \sum_{a' \in T_{i,j}} \frac{|a'\rangle\langle a'|}{|T_{i,j}|} \right) \right)
\]
\[= \sum_{i,j=1}^{u+1} \sum_{a \in T_{i,j}} r(a) \cdot \frac{1}{|T_{i,j}|} \leq \max_{a'} r(a') \cdot \sum_{i,j=1}^{u+1} \sum_{a \in T_{i,j}} \frac{1}{|T_{i,j}|}
\]
\[= \max_{a'} r(a') \cdot (u + 1)^2 \leq \frac{4 \log^2 \frac{d}{\delta}}{\delta^2} \cdot \max_{a'} r(a').
\]

Suppose \(p\) and \(q\) are the uniform and the staircase distributions (Figure 1). That is, \(p(a) = \frac{1}{d}\) for all \(a\) and \(q(a) = \frac{2(d-a+1)}{d(d+1)} = \frac{2}{d} - \frac{2a}{d(d+1)}\) (note that these distributions have no redundant part). Then \(\max_a r(a) \leq \frac{4 \log^2 \frac{d}{\delta}}{\delta^2} \cdot \max_a r(a')\).
\frac{3}{2d}, which leads to $1 - \lambda \leq \frac{6 \log^2 \frac{d}{\delta}}{d\delta^2}$. This gives us $g(P) \geq \lambda \log(d-1) \geq \log(d-1) - \frac{6 \log^3 \frac{d}{\delta}}{d\delta^2}$. If $\delta = \gamma = \frac{\log^2 d}{\sqrt{d}}$, then $g(P) \geq \log(d-1) - \frac{20}{\log(d)}$ and $f(P) \leq \frac{4 \log^2 d}{\sqrt{d}}$. So, $g(P)$ is close to $\log d$, even when $f(P) \approx \frac{1}{\sqrt{d}}$. 

\[ \text{25} \]