Primordial perturbations and non-Gaussianities in DBI and general multi-field inflation

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We study cosmological perturbations in general inflation models with multiple scalar fields and arbitrary kinetic terms, with special emphasis on the multi-field extension of Dirac-Born-Infeld (DBI) inflation. We compute the second-order action governing the dynamics of linear perturbations in the most general case. Specializing to DBI, we show that the adiabatic and entropy modes propagate with a common effective sound speed and are thus amplified at sound horizon crossing. In the small sound speed limit, we find that the amplitude of the entropy modes is much higher than that of the adiabatic modes. We also derive, in the general case, the third-order action which is useful for studying primordial non-Gaussianities generated during inflation. In the DBI case, we compute the dominant contributions to non-Gaussianities, which depend on both the adiabatic and entropy modes.

I. INTRODUCTION

While inflation has become a standard paradigm with which to describe the physics of the very early universe, the nature of the field(s) responsible for inflation remains an open question. The last few years have seen an intensive effort devoted to trying to connect string theory and inflation (for recent reviews, see e.g. \textsuperscript{[1,2,3,4,5]}), with the hope that future cosmological observations, in particular of the CMB anisotropies, could detect some specific stringy signatures.

Of particular interest are scenarios based on the motion of a D-brane in a higher-dimensional spacetime. Since the dynamics of a D-brane is described by the Dirac-Born-Infeld (DBI) action, characterized by a non-standard kinetic term, inflation can occur with steep potentials, in contrast with usual slow-roll inflation. In this sense, this scenario, called DBI inflation \textsuperscript{[6,7,8,9]}, belongs to the more general class of $k$-inflation models \textsuperscript{[10,11]} characterized by a Lagrangian of the form $P(X,\phi)$, where $X = -\partial_{\nu} \phi \partial^\nu \phi/2$.

In DBI inflation, the effective four-dimensional scalar field corresponds to the radial position of a brane in a higher dimensional warped conical geometry. For simplicity, the other possible degrees of freedom of the brane, namely the angular coordinates, are usually assumed to be frozen. Relaxing this assumption and allowing the brane to move in the angular directions (see e.g. \textsuperscript{[12-15]}) leads to a multi-field scenario, since each brane coordinate in the extra dimensions gives rise to a scalar field from the effective four-dimensional point of view.

Beyond the multi-field extension of DBI inflation, it is interesting to study, in the spirit of $k$-inflation, very general multi-field Lagrangians of the form

$$P = P\left(X^{IJ},\phi^K\right),$$

with

$$X^{IJ} = -\frac{1}{2} \partial_{\mu} \phi^I \partial^\mu \phi^J,$$

where $I = 1,\ldots,N$ labels the multiple fields. (In the following we will adopt the implicit summation convention on both field and space-time indices.)

A more restrictive class of models consists of Lagrangians that depend on the global kinetic term $X = G_{IJ} X^{IJ}$ where the functions $G_{IJ}(\phi^K)$ are the components of some metric defined in field space \textsuperscript{[16]}. While this simpler class of Lagrangians is enough to describe the homogeneous dynamics of multi-field DBI inflation, it turns out that the full inhomogeneous dynamics cannot be described by such a Lagrangian, as we pointed out in \textsuperscript{[17]} and show below in more detail.

The purpose of the present work is thus two-fold. Our first aim is to derive the equations governing cosmological perturbations in the generalized models of the form given in Eq. (1). Our second aim is to apply this general formalism to the multi-field extension of the DBI scenario.

The structure of this paper is the following. In the next section, we first consider the multi-field DBI action which motivates our subsequent study of the general formalism. In section II we derive, in the general case, the field
equations for the metric and for the scalar fields, after which we specialize to the homogeneous background. Section IV is devoted to the dynamics of the linear perturbations in the general case: we derive the second-order action and analyse the resulting equations of motion for the perturbations. We then focus, in section V, on the specific example of the DBI action: we show that the adiabatic and entropy modes propagate with the same speed of sound $c_s$ and we compute the second-order action for linear perturbations. For two-field DBI inflation we also compute the power spectra of the adiabatic and entropy modes. Finally in section VI we discuss non-Gaussianities. We first derive, in the general case, the third-order action for perturbations. We then limit our analysis to two-field DBI models, for which we compute the main contribution to non-Gaussianity in the limit of small $c_s$. We summarize our main results in the last section.

II. THE MULTIFIELD DBI ACTION

In this section we motivate our reasons for looking at Lagrangians of the general form $P(X^{IJ}, \phi^K)$ by showing, in particular, that multi-field DBI inflation is described by a Lagrangian of this form. We also discuss the properties of the higher order terms in derivatives which appear in the DBI Lagrangian.

Consider a D3-brane with tension $T_3$ evolving in a 10-dimensional geometry described by the metric

$$ds^2 = h^{-1/2}(y^K) g_{\mu\nu} dx^\mu dx^\nu + h^{1/2}(y^K) G_{IJ}(y^K) dy^I dy^J = H_{AB} dY^A dY^B$$

with coordinates $Y^A = \{x^\mu, y^I\}$, where $\mu = 0, \ldots, 3$ and $I = 1, \ldots, 6$ (the label $I$ has been chosen in this way as below it will label the multiple effective scalar fields). The kinetic part of the DBI action,

$$L = -T_3 \sqrt{-\det \gamma_{\mu\nu}}$$

depends on the determinant of the induced metric on the 3-brane,

$$\gamma_{\mu\nu} = H_{AB} \partial_\mu Y^A (b) \partial_\nu Y^B (b)$$

where the brane embedding is defined by the functions $Y^A (b) = (x^\mu, \phi^I (x^\mu))$, with the $x^\mu$ being the spacetime coordinates on the brane. In our case, they coincide with the first four bulk coordinates. On writing $Y^A (b) = (x^\mu, \varphi^I (x^\mu))$, we find

$$\gamma_{\mu\nu} = h^{-1/2} \left( g_{\mu\nu} + h G_{IJ} \partial_\mu \varphi^I \partial_\nu \varphi^J \right),$$

which after substitution into (3) implies

$$L = -T_3 h^{-1} \sqrt{-g} \sqrt{\det(\delta_{\mu\nu} + h G_{IJ} \partial_\mu \varphi^I \partial_\nu \varphi^J)}.$$  

Finally, in order to absorb the brane tension $T_3$, it is convenient to rescale in the following way:

$$f = \frac{h}{T_3}, \quad \phi^I = \sqrt{T_3} \varphi^I.$$  

As a result, in the following, we consider the DBI Lagrangian

$$P = -\frac{1}{f(\phi^I)} \left( \sqrt{D} - 1 \right) - V(\phi^I)$$

where

$$D = \det(\delta_{\mu\nu} + f G_{IJ} \partial_\mu \varphi^I \partial_\nu \varphi^J),$$

and where we have also included potential terms, which arise from the brane’s interactions with bulk fields or other branes. From now on we let $I = 1, \ldots, N$.

One can express the above Lagrangian in (9) explicitly in terms of the $X^{IJ}$ defined in (2), by rewriting $D$, which is the determinant of a $4 \times 4$ matrix, as the determinant of an $N \times N$ matrix:

$$D = \det(\delta^J_I - 2f X^K_I),$$

where

$$X^K_I = G_{IK} X^{IJ}.$$
Throughout this paper field indices will always be raised and lowered with the ‘field metric’ $G_{IJ} = G_{IJ}(\phi^K)$. The equality between the expressions (10) and (11) for the determinant can be proved by using the identity $\det(\mathbf{Id} + \alpha) = \exp[\text{Tr}(\ln(\mathbf{Id} + \alpha))]$ for the matrix $\alpha$ of components $\alpha^\mu_\nu = f G_{IJ} \partial^\mu \phi^I \partial^\nu \phi^J$. Indeed from Eq. (10) we have

$$D = \exp \left[ \text{Tr}(\alpha) - \frac{1}{2} \text{Tr}(\alpha^2) + \frac{1}{3} \text{Tr}(\alpha^3) + \ldots \right], \quad (13)$$

and on noting that

$$\text{Tr}(\alpha^n) = \text{Tr} \left[ (-2f\mathcal{X})^n \right] \quad (14)$$

where $\mathcal{X}$ represents the matrix of components $X^I_J$. One obtains the expression given in Eq. (11).

Another very useful expression for $D$ can be obtained by computing directly the determinant in Eq. (10). As we show in Appendix 1, this yields

$$D = 1 - 2f G_{IJ} X^I_J + 4f^2 X^I_J X^J_I - 8 f^3 X^I_J X^J_K X^K_I + 16 f^4 X^I_J X^J_K X^K_L X^L_I, \quad (15)$$

where the brackets denote antisymmetrisation on the field indices. We note that, in four spacetime dimensions, Eq. (15) is automatically truncated at order $f^4$ even if the number of scalar fields is larger than four (see Appendix 1). To use shorter notations, we will rewrite the above equation as

$$D = 1 - 2f \tilde{X}, \quad (16)$$

with

$$\tilde{X} = X + F(X^{IJ}, \phi^K), \quad (17)$$

$$X = G_{IJ} X^{IJ}, \quad (18)$$

and where $F(X^{IJ}, \phi^K)$ can be read from Eq. (15):

$$F(X^{IJ}, \phi^K) = -2f X^I_J X^J_I + 4f^2 X^I_J X^J_K X^K_I - 8 f^3 X^I_J X^J_K X^K_L X^L_I. \quad (19)$$

For a single field, $I = 1$, it is straightforward to see that $F$ vanishes so that the determinant takes the familiar form $D = 1 + f \partial_\mu \phi \partial^\mu \phi$ (for $G_{11} = 1$). Similarly, for a multi-field homogeneous configuration in which the scalar fields depend only on time and $X^{IJ} = \phi^I \phi^J / 2$, one again finds $F = 0$ because of the antisymmetrisation on field indices in Eq. (19). Thus in this case the determinant $D$ reduces to

$$\tilde{D} = 1 - f G_{IJ} \phi^I \phi^J. \quad (20)$$

(In the following a bar denotes homogeneous background quantities.)

However, for multiple inhomogeneous scalar fields, the terms in $F$, which are higher order in gradients and have not been considered in previous works, do not vanish: we will show later in this paper that they drastically change the behaviour of perturbations. Furthermore, since they vanish in the homogeneous background, we expect them to modify only the terms in the perturbation equations which contain spatial derivatives. From this discussion we therefore see explicitly that the multi-field DBI action does not depend only on $X = G_{IJ} X^{IJ}$ (as has been assumed in recent works on multi-field DBI inflation [18, 19]), but requires a general description of the form $P = P(X^{IJ}, \phi^K)$.

After this digression on the specific form of the multi-field DBI Lagrangian, in the following section we return to the general Lagrangian given in Eq. (1).

### III. FIELD EQUATIONS

We begin this section by deriving the equations of motion for the general action

$$S = \frac{1}{2} \int d^4x \sqrt{-g} \left[ (d)R + 2P(X^{IJ}, \phi^K) \right], \quad (21)$$

where we have set $8\pi G = 1$. The energy-momentum tensor can be obtained by varying $P$ with respect to the metric, and is given by

$$T^{\mu\nu} = Pg^{\mu\nu} + P_{<IJ>\geq} \partial^\mu \phi^I \partial^\nu \phi^J, \quad (22)$$
where we have defined
\[ P_{<IJ>} \equiv \frac{1}{2} \left( \frac{\partial P}{\partial X^{IJ}} + \frac{\partial P}{\partial X^{JI}} \right) = P_{<JI>} . \] (23)

We use this symmetrized derivative of the Lagrangian \( P \) with respect to \( X^{IJ} \) for the following reason: since \( X^{IJ} \) is symmetric in \( I \) and \( J \), the explicit dependence of \( P \) on say \( X^{12} \) and \( X^{21} \) can vary depending on the chosen convention and the above definition avoids any ambiguity. The same notation will apply to the derivative of any arbitrary function which depends on \( X^{IJ} \).

The equations of motion for the scalar fields follow from the variation of the action in Eq. (21) with respect to each scalar field. One finds
\[ \frac{1}{\sqrt{-g}} \partial_{\mu} \left( \sqrt{-g} P_{<IJ>} \partial^{\mu} \phi^J \right) + P_{,I} = 0 , \] (24)

where \( P_{,I} \) denotes a partial derivative with respect to \( \phi^I \).

Now we consider a spatially flat FLRW (Friedmann-Lemaître-Robertson-Walker) geometry with metric
\[ ds^2 = -dt^2 + a(t)^2 dx^2 , \] (25)

where \( t \) is cosmic time. Then the kinetic terms defined in Eq. (2) reduce to
\[ X^{IJ} = \frac{1}{2} \dot{\phi}^I \dot{\phi}^J , \] (26)

where a dot denotes a derivative with respect to \( t \). From Eq. (22), the energy density can be expressed as
\[ \rho = 2P_{<IJ>} X^{IJ} - P \] (27)

while the pressure is simply \( P \), and the Friedmann equations are given by
\[ H^2 = \frac{1}{3} \left( 2P_{<IJ>} X^{IJ} - P \right) , \quad \dot{H} = -X^{IJ} P_{<IJ>} . \] (28)

The equations of motion for the scalar fields Eq. (24) reduce to
\[ a^{-3} \frac{d}{dt} \left( a^3 P_{<IJ>} \dot{\phi}^J \right) = P_{,I} . \] (29)

On calculating the time derivative and taking into account the terms in \( \ddot{\phi}^J \) contained in \( \frac{d}{dt} P_{<IJ>} \), the above equation can be rewritten as
\[ \left( P_{<IJ>} + P_{<IK>,<JK> \dot{\phi}^I \dot{\phi}^K} \right) \ddot{\phi}^J + \left( 3HP_{<IJ>} + P_{<IK>,<K> \dot{\phi}^K} \right) \dot{\phi}^J - P_{,I} = 0 \] (30)

where, in analogy with Eq. (23), we have defined
\[ P_{<IJ>,<KL>} \equiv \frac{1}{2} \left( \frac{\partial P_{<IJ>}}{\partial X^{KL}} + \frac{\partial P_{<IJ>}}{\partial X^{LK}} \right) = P_{<KL>,<IJ>} . \] (31)

Finally we end this section by noting that were the Lagrangian to depend on the \( X^{IJ} \) only through \( X = G_{IJ} X^{IJ} \), then one would define \( \bar{P}(X, \dot{\phi}^K) = P(X^{IJ}, \dot{\phi}^K) \) so that \( P_{<IJ>} = \bar{P}_X G_{IJ} \). In that case all the above expressions would reduce to those of [16].

**IV. LINEAR PERTURBATIONS IN THE GENERAL CASE**

In this section, we derive the second-order action governing the dynamics of the linear perturbations for the general action given in Eq. (21). As in [20], we use the ADM approach, and our calculations are very similar to those of [16], except that we work with the quantities \( X^{IJ} \) rather than \( X \).

Starting from the metric in the ADM form
\[ ds^2 = -N^2 dt^2 + h_{ij}(dx^i + N^i dt)(dx^j + N^j dt) \] (32)
where \( N \) is the lapse and \( N_i \) the shift, the full action becomes

\[
S = \frac{1}{2} \int d^4x \sqrt{-g} \left( \frac{1}{2} R + 2P \right) = \frac{1}{2} \int dt d^3x \sqrt{\tilde{h}} \left[ N (\frac{3}{2} R + \frac{1}{N} (E^2 + E_{ij} E^{ij}) + 2NP \right]
\]

(33)

where \( (3)R \) is the scalar curvature of the spatial metric \( h_{ij} \) with \( h \) its determinant, and the symmetric tensor \( E_{ij} \), defined by

\[
E_{ij} = \frac{1}{2} h_{ij} - D_i N_j
\]

(34)
is proportional to the extrinsic curvature of the spatial slices (\( D_i \) denotes the spatial covariant derivative associated with the spatial metric \( h_{ij} \)).

The function \( P = P(X^{IJ}, \phi^K) \) in Eq. (33) depends on the kinetic quantities \( X^{IJ} \), which can be decomposed as

\[
X^{IJ} = \frac{1}{2N^2} v^I v^J - \frac{1}{2} h^{ij} \partial_i \phi^I \partial_j \phi^J
\]

(35)

with

\[
v^J = \dot{\phi}^J - N^i \partial_i \phi^J
\]

(36).

We now work in the flat gauge so that spatial sections are flat, \( h_{ij} = a^2(t) \delta_{ij} \) and \( (3)R = 0 \). The Hamiltonian and momentum constraints, which follow from the variation of (33) with respect to the lapse and the shift are, respectively,

\[
2(N^2 P - P_{<IJ>,<J>}) + E^2 - E_{ij} E^{ij} = 0 , \quad (37)
\]

\[
D_i \left[ \frac{1}{N} (E_i^j - E\delta_i^j) \right] = \frac{1}{N} P_{<IJ>,<K>} \partial_i \phi^K . \quad (38)
\]

To zeroth order (background), the Hamiltonian constraint simply gives the first Friedmann equation in Eq. (28), while the momentum constraint vanishes identically.

At first order in the scalar perturbations, we write

\[
N = 1 + \delta N, \quad N_i = \partial_i \psi, \quad \phi^J = \tilde{\phi}^J (t) + Q^J (t, x)
\]

(39)

where, from now on and when there is no ambiguity, we promptly drop the bars on all the unperturbed fields. Note that \( \psi \) is related to the standard Bardeen potential \( \Psi \) by

\[
\Psi = -H \psi . \quad (40)
\]

At linear order, the momentum constraint (38) gives

\[
\delta N = \frac{1}{2H} P_{<IJ>,<J>} \dot{\phi}^J Q^J . \quad (41)
\]

The Hamiltonian constraint is more complicated, but a straightforward calculation yields

\[
-2H \left( \frac{\partial^2 \psi}{a^2} \right) = 2A \delta N + B_{IJ} \dot{\phi}^I \dot{Q}^J + C_I Q^I
\]

(42)

with

\[
A = P_{<IJ>,<J>} X^{IJ} - 2X^{IJ} X^{KL} P_{<IJ>,<K>,<L>}, \\
B_{IJ} = P_{<IJ>,<J>} + 2X^{KL} P_{<IJ>,<K>}, \\
C_I = -P_{<I>} + 2P_{<KL>,<I>} X^{KL} .
\]

(43)

Actually, this explicit expression for \( \psi \) is not necessary in order to derive the second-order action, as the terms involving \( \psi \) (coming from the matter and gravitational parts of the action) cancel each other. The scalar field perturbations are related to a useful geometrical quantity, namely the comoving curvature perturbation \( \mathcal{R} \) (see e.g. [21] and [22]). On using the standard definition of \( \mathcal{R} \) which combines the metric perturbations with the perturbations of the momentum density for the Lagrangian \( P = P(X^{IJ}, \phi^K) \), one obtains

\[
\mathcal{R} = \left( \frac{H}{2P_{<IJ>,<J>} X^{IJ}} \right) P_{<KL>,<K>} \dot{\phi}^K Q^L . \quad (44)
\]
After these preliminary steps, one can now expand the action \( S\[2\] \) up to second order in the linear perturbations \( \delta N, \psi \) and \( Q^I \). As mentioned earlier, the terms involving \( \psi \) cancel each other. On reexpressing \( \delta N \) in terms of the \( Q^I \) using the constraint \( [11] \), one obtains, after a long but straightforward calculation,

\[
S\[2\] = \frac{1}{2} \int dt \, d^3x \, a^3 \left[ (P\<_{<IJ>}> + 2P\<_{<MJ>},<IK>\>X^{MK}) \dot{Q}^I \dot{Q}^J - P\<_{<IJ>}> h_{ij} \partial_i Q^I \partial_j Q^J - \mathcal{M}_{KL} Q^K Q^L + 2 \Omega_{KI} Q^K \dot{Q}^I \right]
\]

where the mass matrix is

\[
\mathcal{M}_{KL} = -P_{KL} + 3X^{MN}P\<_{<NK>}>P\<_{<ML>}> + \frac{1}{H^2} P\<_{<NL>}> [2P\<_{<IJ>},<K>\>X^{IJ} - P_K] + \frac{1}{H^2} X^{MN}P\<_{<NK>}>P\<_{<ML>}> [X^{IJ}P\<_{<IJ>}> + 2P\<_{<IJ>},<AB>\>X^{IJ}X^{AB}] - \frac{1}{a^3} \frac{d}{dt} \left( \frac{a^3}{H} P\<_{<AK>}>P\<_{<LJ>}>X^{AJ} \right)
\]  

and the mixing matrix is

\[
\Omega_{KI} = \dot{\phi}^I P\<_{<IJ>,K}> - \frac{2}{H} P\<_{<LK>}>P\<_{<MJ>,<NI>\>}X^{LN}X^{MK}.
\]

We find that the equations of motion for the \( Q^I \) (in Fourier space) are

\[
K_{IJ} \ddot{Q}^J + \frac{k^2}{a^2} P\<_{<IJ>}> Q^J + \left( K_{IJ} + 3HK_{IJ} + \Omega_{JI} - \Omega_{IJ} \right) \dot{Q}^J + \left( \Omega_{KI} + M_{IK} + 3H\Omega_{KI} \right) Q^K = 0.
\]

The propagation velocities can be deduced from the structure of the first two terms in the above equation. On assuming that \( K_{IJ} \) is invertible, the sound speeds correspond to the eigenvalues of the matrix of components \( (K^{-1})^{IJ} P\<_{<IJ>}> \) (recall that these are background quantities).

For a single scalar field, \( P\<_{<IJ>}> \) reduces to \( P_X \), and it is easy to see that the kinetic coefficient in Eq. \([45]\) is simply \( K = P_X + 2XP_{XX} \) which can be identified with \( \rho_X \) according to the relation \([27]\). Hence one recovers the familiar result \([11]\) that the effective speed of sound is given by

\[
c^2 = \frac{P_X}{\rho_X} = \frac{P_X}{P_X + 2XP_{XX}} \quad \text{(single scalar field)}.
\]

For multiple fields and in the particular case where the Lagrangian is a function of \( X = G_{IJ} X^{IJ} \), i.e. \( P = P(X, \phi^K) \), it has been shown in \([16]\) (see also \([18, 19]\)) that the propagation matrix \( (K^{-1})^{IJ} P\<_{<IJ>}> \) becomes anisotropic: the perturbations along the field space trajectory propagate with an effective speed of sound \( c_s \), defined as in the single field case above \([50]\), whereas the perturbations orthogonal to the background trajectory propagate at the speed of light. In the next section, we examine what happens in multi-field DBI inflation for which \( P = P(X^{IJ}, \phi^K) \).

\[\text{V. LINEAR PER TURBATIONS IN DBI INFLATION}\]

We now focus on linear perturbations in the specific case of multi-field DBI inflation for which the Lagrangian was derived in section 2:

\[
P(X^{IJ}, \phi^K) = -\frac{1}{f(\phi^J)} \left( \sqrt{D} - 1 \right) - V(\phi^I),
\]

where \( D \) is given in Eq. \([11]\) or Eq. \([15]\). According to Eq. \([16]\), this Lagrangian can also be seen as a function of \( \tilde{X} \), and it will be convenient later to use \( \tilde{P} \) defined by

\[
\tilde{P}(X^{IJ}, \phi^K) \equiv \tilde{P}(\tilde{X}, \phi^K) = -\frac{1}{f(\phi^J)} \left( \sqrt{1 - 2f(\phi^J)\tilde{X}} - 1 \right) - V(\phi^I).
\]
A. Propagation speed

Before considering the full dynamics of the linear perturbations, it is instructive to concentrate on their propagation speed. According to the general analysis given in the previous section, we simply need to calculate $P_{<IJ>}$ as well as the matrix $K_{IJ}$, defined in Eq. (48).

To do so, it is convenient to use the form of the determinant given in Eq. (11), namely

$$D = \det(M), \quad M^I_J = \delta^I_J - 2f G_{IK} X^K J.$$

(53)

In the homogeneous background, the components of the matrix $M^I_J$ reduce to

$$\bar{M}^I_J = \delta^I_J - 2f X e_I e^J,$$

(54)

when expressed in terms of $X = G_{IJ} X^I J$ and of the unit vector in field space

$$e^I = \frac{\dot{\phi}^I}{\sqrt{2X}}, \quad e_I = G_{IJ} e^J.$$

(55)

We will shortly need the inverse of the background matrix $\bar{M}$, denoted by $\tilde{G}$. Its components are given by

$$\tilde{G}^I_J = \delta^I_J + \frac{2f X}{1 - 2f X} e_I e^J = \perp^I_J + \frac{1}{1 - 2f X} e_I e^J,$$

(56)

where, in the second equality, we have introduced the projector orthogonal to the vector $e^I$,

$$\perp^I_J = \delta^I_J - e_I e^J.$$

(57)

Let us also define

$$c_s = \sqrt{1 - 2f X} = D^{1/2}$$

(58)

which, as we show below, is the propagation speed for all perturbations. Note that this definition coincides with that given in Eq. (50) for a single scalar field (on replacing $P(X, \phi^I)$ by $\tilde{P}(\tilde{X}, \phi^I)$ given in Eq. (52)), and that $\tilde{G}$ given in Eq. (56) can be rewritten as

$$\tilde{G}^I_J = \perp^I_J + \frac{1}{c_s^2} e_I e^J.$$

(59)

Let us now compute $P_{<IJ>}$. The identity $\delta \det(M) = \det(\bar{M}) \bar{M}^{-1} \delta M$ implies, using Eq. (58), that

$$D_{<IJ>} = -2f c_s^2 \tilde{G}_{IJ},$$

(60)

where $\tilde{G}_{IJ} = \tilde{G}^K_I G_{KL}$. It then follows from Eq. (51) that

$$P_{<IJ>} = -\frac{1}{2f c_s} D_{<IJ>} = c_s \tilde{G}_{IJ},$$

(61)

where all quantities are evaluated on the background. For the matrix $K_{IJ}$, one needs the second derivative of $P$ with respect with $X^{IJ}$. On using the second derivative of the determinant $D$, which can be deduced from Appendix 1, it is straightforward to obtain

$$P_{<IK>,<JL>} = f c_s \left( \tilde{G}_{IL} \tilde{G}_{KL} + \tilde{G}_{IJ} \tilde{G}_{KL} - \tilde{G}_{IK} \tilde{G}_{JL} \right).$$

(62)

By noting that $X^{KL} \tilde{G}_{KL} = X/c_s^2$, the above equation together with Eq. (51) leads to

$$K_{IJ} = P_{<IJ>} + 2P_{<IK>,<JL>} X^{KL} \frac{1}{c_s} \tilde{G}_{IJ} = \frac{1}{c_s} P_{<IJ>}.$$

(63)

Hence we obtain the remarkable result that the propagation matrix is proportional to the identity matrix and that all perturbations propagate at the same speed, namely the effective sound speed $c_s$ defined in Eq. (58).

Intuitively one can understand this result as follows. Let us return to the DBI action in terms of the embedding of a brane in a higher dimensional spacetime, as discussed in Section II. The perturbations we have considered above can be seen as fluctuations of the brane position in the higher dimensional background. Since the brane action is the world-sheet volume, its fluctuations propagate at the speed of light from the higher dimensional point of view. From a 4-dimensional point of view, this translates into the speed of sound $c_s$ as a consequence of time-dilation between the bulk time coordinate and the brane proper-time (the Lorentz factor is $1/c_s$).
\[ \delta^{(1)} \dot{X} = \delta^{(1)} X, \quad \delta^{(2)} \ddot{X} = \delta^{(2)} X + f X \perp_{IJ} h^{ij} \partial_i Q^I \partial_j Q^J. \]  \hspace{1cm} (64)

With respect to the second order action of [16], the extra term in Eq. (64) only modifies the spatial gradient term, while the rest of that action is unchanged. Hence, as in [16], we can rewrite the action in terms of covariant derivatives \( D_t \) defined with respect to the the field space metric \( \mathcal{M}_{IJ} \), which appears above, and which differs from \( \mathcal{M}_{IJ} \) defined in Eq. (52) and simply identify the new terms which appear because the DBI Lagrangian depends on \( \dot{X} \) rather than \( X \).

Computation of the first and second order variations of \( \dot{X} \) gives (see Appendix 2)

\[ S^{(2)} = \frac{1}{2} \int dt d^3x a^3 \left[ \frac{1}{c_s} (\dot{G}_{IJ} D_t Q^I D_t Q^J - c_s^2 \dot{G}_{IJ} h^{ij} \partial_i Q^I \partial_j Q^J) - \mathcal{M}_{IJ} Q^I Q^J + 2 \frac{f X}{c_s^2} \dot{t} Q^I D_t Q^J \right], \]  \hspace{1cm} (65)

where we have substituted \( \tilde{P}_{\dot{X}} = 1/c_s \) and \( \tilde{P}_{\tilde{X}J} = f_j X/c_s^3 \) into the expression of [16], and introduced the time covariant derivative \( D_t Q^I \equiv \dot{Q}^I + \Gamma^I_{JK} \dot{Q}^J K \) where \( \Gamma^I_{JK} \) is the Christoffel symbol constructed from \( \dot{G}_{IJ} \) (and \( \mathcal{R}_{IKLJ} \) will denote the corresponding Riemann tensor). Finally the mass matrix which appears above, and which differs from \( \mathcal{M}_{IJ} \) in Eq. (60), is

\[ \mathcal{M}_{IJ} = -D_I D_J \dot{P} - \tilde{P}_{\dot{X}} \mathcal{R}_{IKLJ} \dot{t} K \dot{t} L + \frac{X \tilde{P}_{\dot{X}}}{H} (\dot{P}_{\tilde{X}J} \dot{t} e^J + \tilde{P}_{\tilde{X}I} \dot{t} e^I) + \frac{X \tilde{P}_{\dot{X}}^2}{2H^2} (1 - \frac{1}{c^2}) \dot{t} \dot{t} \]

\[ = D_I D_J V - \frac{(1 - c_s^2)}{2c_s} D_I D_J f f^2 - \frac{(1 - c_s^2)}{2c_s} (1 + 3c_s) D_I f D_J f \left( \frac{4c_s^3}{f^3} \right) + 2H \mathcal{R}_{IKLJ} e^K e^L + \frac{(1 - c_s^2)}{2c_s^2 H f} \]

\[ + \frac{\dot{H}}{2H^2 c_s^2} (1 - c_s^2) \dot{t} \dot{t} \dot{t} \dot{t} - \frac{1}{a^2} D_t \left[ \frac{a^3}{2H c_s^2} (1 + c_s^2) \dot{t} \dot{t} \dot{t} \dot{t} \right] \]  \hspace{1cm} (66)

where in the second equality we have substituted the explicit DBI Lagrangian, and used \( \dot{H} = -X/c_s \) as well as \( c_s^2 = 1 - 2f X \).

C. Two-field DBI

We can gain a better intuition for the system of perturbations described by the action (66) by restricting our attention to a two-field system, \( I = 1, 2 \). Then one can unambiguously decompose perturbations into (instantaneous) adiabatic and entropic modes by projecting respectively, parallel and perpendicular to the background trajectory in field space. In other words, we introduce the basis \( \{ e^I_{\sigma}, e^I_s \} \) where \( e^I_{\sigma} = e^I \), and \( e^I_s \) is the entropy unit vector orthogonal to \( e^I_{\sigma} \):

\[ e^I_{\sigma} \equiv e^I, \quad G_{IJ} e^I_s e^J_s = 1, \quad G_{IJ} e^I_{\sigma} e^J_{\sigma} = 0. \]  \hspace{1cm} (67)

We also define

\[ \dot{\sigma} \equiv \sqrt{2X}. \]  \hspace{1cm} (68)

One can reformulate the background equations of motion Eq. (60) for DBI in terms of these quantities. The adiabatic component is

\[ \ddot{\sigma} = c_s^2 \left( c_s \ddot{P}_{\dot{X} \dot{\sigma}} - c_s \dot{\sigma}^2 \ddot{P}_{\tilde{X} \dot{\sigma}} - 3H \dot{\sigma} \right), \]  \hspace{1cm} (69)

whereas the entropy component gives the time variation of \( e^I_s \):

\[ D_t e^I_s = \frac{c_s \ddot{P}_{\dot{X} \sigma}}{\dot{\sigma}} e^I_s. \]  \hspace{1cm} (70)
In the above equations, $\tilde{P}$ is given in [52] and partial derivatives with respect to $\sigma$ or $s$ denote the projection of the field space gradients along $e^I_\sigma$ or $e^I_s$ respectively. For example, $\tilde{P}_\sigma = e^I_\sigma \tilde{P}_I$ and $\tilde{P}_{ss} = e^I_s e^J_s \partial_I \partial_J \tilde{P}$.

On introducing the decomposition

$$Q^I = Q_\sigma e^I_\sigma + Q_s e^I_s,$$

the equations of motion for $Q_\sigma$ and $Q_s$ follow from Eqs. (65) and (66) (see 16). For the adiabatic part one finds

$$\dot{Q}_\sigma + \left( 3H - \frac{\dot{\sigma}}{c_s} \right) Q_\sigma + \left( \frac{c_s^2 k^2}{a^2} + \mu^2_\sigma \right) Q_\sigma = (\Xi Q_s)' - \left( \frac{(H \dot{c_s^2})}{H c_s^2} - \frac{c_s \dot{P}_\sigma}{\dot{\sigma}} \right) \Xi Q_s,$$

where the coupling $\Xi$ between the adiabatic and entropy components is

$$\Xi \equiv \frac{c_s}{\sigma} \left[ (1 + c_s^2) \tilde{P}_s - c_s^2 \tilde{P}_{s,xx} \dot{\sigma}^2 \right] = -c_s \sqrt{\frac{f}{1 - c_s^2}} \left[ \frac{(1 - c_s^2)^2}{f^2} f_s + (1 + c_s^2)V_s \right]$$

while the effective mass of the adiabatic modes can be written in the form

$$\mu^2_\sigma \equiv - \frac{(\dot{\sigma}/H)'}{\dot{\sigma}/H} - \left( 3H - \frac{\dot{\sigma}}{c_s} \right) \left( \frac{\dot{\sigma}/H}{\dot{\sigma}/H} \right)'$$

The equation of motion for the entropy part can be expressed as

$$\dot{Q}_s + \left( 3H - \frac{\dot{\sigma}}{c_s} \right) Q_s + \left( \frac{k^2}{a^2} + \mu^2 + \frac{\bar{\xi}^2}{c_s^2} \right) Q_s = - \frac{\dot{\sigma}}{H} \Xi \frac{k^2}{a^2} \Psi,$$

where the right hand side depends on the Bardeen potential $\Psi$, introduced in Eq. (40), and which depends on $Q_\sigma$ and $Q_s$ through Eqs. (42) and (41). The effective mass appearing above is given by

$$\mu^2_s \equiv -c_s \tilde{P}_{ss} + \frac{1}{2} \sigma^2 R_G - \frac{\dot{P}_s^2}{a^2} + 2 c_s^2 \tilde{P}_{s,xx} \dot{P}_s$$

$$= c_s V_{ss} - \frac{f}{1 - c_s^2} V_s^2 - \frac{(1 - c_s)^2}{4(1 + c_s) f^2} \frac{(2 + c_s)(1 - c_s)}{(1 + c_s)f} f_s V_s - \frac{(1 - c_s)^2}{2f^2} f_{ss} + \frac{1}{2} \sigma^2 R_G.$$

($R_G$ is the scalar Riemann curvature in field space.) Note that in this form, Eq. (75) is useful on large scales when the right hand side can be neglected — in this case one sees immediately that the entropy perturbation $Q_s$ evolves independently of the adiabatic mode.

In order to study the quantum fluctuations of the system, it is convenient, after going to conformal time $\tau = \int dt/a(t)$, to work in terms of canonically normalized fields given by

$$v_\sigma = \frac{a}{c_s^{3/2}} Q_\sigma, \quad v_s = \frac{a}{\sqrt{c_s}} Q_s.$$

Remarkably, in terms of these new variables, the second order action (65) reduces to the very simple form

$$S_{(2)} = \frac{1}{2} \int d\tau d^3 x \left\{ v_\sigma' + v_s' - 2 \Xi v'_s v_s - c_s^2 \left[ (\partial v_\sigma)^2 + (\partial v_s)^2 \right] + \frac{z''}{z} e^2_\sigma + \left( \frac{\alpha''}{\alpha} - a^2 \mu^2_s \right) v_s^2 + 2 \frac{z'}{z} \Xi v'_s v_s \right\}$$

where a prime denotes a derivative with respect to conformal time. The coupling between $v_\sigma$ and $v_s$ depends on

$$\xi = \frac{a}{c_s} \Xi$$

and we have introduced the two background-dependent functions

$$z = \frac{a H}{c_s^{3/2}}, \quad \alpha = \frac{a}{\sqrt{c_s}}.$$

(80)
This result is similar to that of [16], except for the spatial gradient terms which have the same coefficient $c_s^2$ for both the adiabatic and isocurvature perturbations. The equations of motion for $v_\sigma$ and $v_s$ are

$$v''_\sigma - \xi v'_s + \left( c_s^2 k^2 - \frac{z''}{z} \right) v_\sigma - \frac{(z \xi')'}{z} v_s = 0 ,$$  
(81)

$$v''_s + \xi v'_\sigma + \left( c_s^2 k^2 - \frac{\alpha''}{\alpha} + a^2 \mu_s^2 \right) v_s - \frac{z'}{z} \xi v_\sigma = 0 .$$  
(82)

In the following we will assume that the time evolution of $H$, $\dot{\sigma}$ and $c_s$ is very slow with respect to that of the scale factor, so that $z''/z \approx \alpha''/\alpha \approx 2/\tau^2$. Since $\tau$ varies from $-\infty$ to 0, the wavelength of a given mode is first inside the sound horizon (when $|kc_s \tau| \gg 1$) and then crosses out the sound horizon. As in standard inflation, the initial conditions for the perturbations are determined by choosing the familiar Minkowski-like vacuum on very small scales. Below, we consider in turn the quantization on sub-horizon scales and then the classical evolution on large scales.

### 1. Quantization

For simplicity, we assume that the coupling $\xi$ is very small when the scales of interest cross out the sound horizon, in which case one can quantize the two degrees of freedom independently and solve analytically the system (otherwise, one can resort to numerical integration by starting deep enough inside the sound horizon as in [23, 24]). The amplification of the vacuum fluctuations at horizon crossing is possible only for very light degrees of freedom. Consequently, if $\mu_s^2$ is larger than $H^2$, this amplification is suppressed and there is no production of entropy modes. Interestingly we see from Eq. (76) that the term coming from the second derivative of the potential along the entropy direction is multiplied by the sound speed $c_s$ so that one recovers the usual single-field result [11] that the power spectrum for $\mathcal{R}$ at sound horizon crossing is given by

$$\mathcal{P}_{\mathcal{R}} = \frac{k^3}{2\pi^2} \left| v_{\sigma k} \right|^2 \simeq \frac{H^4 a^2}{4\pi^2 c_s^3} ,$$  
(88)

and thus tend to destabilize the entropic direction. Below we assume that $|\mu_s^2|^3/H^2 \ll 1$.

Following the standard procedure (see e.g. [21] or [22]) one selects the positive frequency solutions of Eqs. (81) and (82), which correspond to the usual vacuum on very small scales:

$$v_{\sigma k} \simeq v_{s k} \simeq \frac{1}{\sqrt{2kc_s}} e^{-ikc_s \tau} \left( 1 - \frac{i}{kc_s \tau} \right) .$$  
(83)

As a consequence, the power spectra for $v_\sigma$ and $v_s$ after sound horizon crossing have the same amplitude

$$\mathcal{P}_{v_\sigma} = \mathcal{P}_{v_s} \simeq \frac{k^3}{2\pi^2} |v_{\sigma k}|^2 \simeq \frac{H^2 a^2}{4\pi^2 c_s^3} .$$  
(84)

However, in terms of the initial fields $Q_\sigma$ and $Q_s$, one finds, using (77),

$$\mathcal{P}_{Q_{\sigma k}} \simeq \frac{H^2}{4\pi^2} , \quad \mathcal{P}_{Q_{s k}} \simeq \frac{H^2}{4\pi^2 c_s^3} ,$$  
(85)

(the subscript * indicates that the corresponding quantity is evaluated at sound horizon crossing $kc_s = aH$) which shows that, for small $c_s$, the entropic modes are amplified with respect to the adiabatic modes:

$$Q_{ss} \simeq \frac{Q_{\sigma s}}{c_s} .$$  
(86)

In order to confront the predictions of inflationary models to cosmological observations, it is useful to rewrite the scalar field perturbations in terms of geometrical quantities, such as the comoving curvature perturbation. The latter is related to the adiabatic perturbation by the expression (13), which yields

$$\mathcal{R} = \frac{H}{\dot{\sigma}} Q_\sigma ,$$  
(87)

so that one recovers the usual single-field result [11] that the power spectrum for $\mathcal{R}$ at sound horizon crossing is given by

$$\mathcal{P}_{\mathcal{R}_c} = \frac{k^3}{2\pi^2} \left| v_{\sigma k} \right|^2 \simeq \frac{H^4}{4\pi^2 \dot{\sigma}^2} = \frac{H^2}{8\pi^2 c_s} ,$$  
(88)
where \( \epsilon \equiv -\dot{H}/H^2 \).

It is then convenient to define an entropy perturbation, which we denote \( S \), such that its power spectrum at sound horizon crossing is the same as that of the curvature perturbation:

\[
S = c_s H Q_\sigma.
\]  

We thus have

\[
\mathcal{P}_R = \mathcal{P}_S = \mathcal{P}_S.
\]  

We stress that our convention for the definition of \( S \) is purely for convenience.

In contrast with the scalar perturbations, the tensor modes are, as usual, amplified at Hubble radius crossing. The amplitude of their power spectrum, given by

\[
P_T = \left( \frac{2H^2}{\pi^2} \right)_{k=aH},
\]  

is much smaller than the curvature amplitude in the small \( c_s \) limit.

2. Evolution on large scales

In order to determine the observational consequences of single-field inflation models, it is usually sufficient to evaluate the amplitude of the comoving curvature perturbation just after horizon crossing. The reason is that the comoving curvature perturbation is conserved on large scales for adiabatic perturbations, as is also the case for the curvature perturbation on uniform energy density hypersurfaces \( \zeta \), which coincides with \( -\mathcal{R} \) on large scales. This property is simply a consequence of the conservation of the energy-momentum tensor \( \tilde{T} \) (this is also true for non-linear perturbations \( \mathcal{T} \)).

In contrast with the single-field case, the curvature perturbation generally evolves in time, even on large scales, in a multi-field scenario \( \mathcal{T} \) (see also \( \mathcal{T} \) for a recent analysis with non-standard kinetic terms). This can be interpreted as due to a transfer between the adiabatic and entropic modes, governed by the relation

\[
\dot{\mathcal{R}} = \Xi c_s S + \frac{H c_s^2 k^2}{H a^2} \Psi.
\]  

Note that, whereas this relation might be useful during inflation, it is not always relevant, for example at the end of inflation and during reheating where \( \dot{\mathcal{R}} \) may temporarily vanish. The importance of the transfer depends on the specific model under consideration and can be computed analytically only in some simple cases.

On large scales the curvature-entropy evolution can be approximated by two equations of the form

\[
\dot{\mathcal{R}} \approx \alpha H S, \quad \dot{S} \approx \beta H S,
\]  

where in the latter, we have neglected the second-order time derivative in Eq. \( \mathcal{T} \). In our case, the coefficients \( \alpha \) and \( \beta \) are given by

\[
\alpha = \frac{\Xi}{c_s H}, \quad \beta \approx \frac{s}{2} - \frac{\eta}{2} - \frac{1}{3H^2} \left( \mu_s^2 + \Xi^2 \right),
\]  

where we have introduced the slow-varying parameters

\[
\eta = \frac{\dot{\epsilon}}{H \epsilon}, \quad s = \frac{\dot{c}_s}{H \epsilon},
\]  

and kept only the leading order terms in the expression for \( \beta \).

The system of equations \( \mathcal{T} \) can be formally integrated (see \( \mathcal{T} \)) to yield

\[
\begin{pmatrix}
\mathcal{R} \\
\mathcal{S}
\end{pmatrix} =
\begin{pmatrix}
1 & T_{RS} \\
0 & T_{SS}
\end{pmatrix}
\begin{pmatrix}
\mathcal{R}(t) \\
\mathcal{S}(t)
\end{pmatrix},
\]  

with

\[
T_{SS}(t, t') = \exp \left( \int_{t'}^t \beta(t')H(t')dt' \right), \quad T_{RS}(t, t') = \int_{t'}^t \alpha(t')T_{SS}(t, t')H(t')dt'.
\]
Hence the (time-dependent) power spectra for the curvature perturbation, the entropy perturbation and the correlation between the two can be formally expressed as

\[ P_R = (1 + T_{RS}^2)P_*, \quad P_S = T_{SS}^2P_*, \quad C_{RS} \equiv \langle RS \rangle = T_{RS}T_{SS}P_*, \] (98)

(recall that \( R \) and \( S \) are implicitly assumed to be uncorrelated at sound horizon crossing).

An interesting question, which depends on the details of reheating and thus goes beyond the scope of the present work, is whether the entropy perturbation during inflation can be transferred to some entropy perturbations after inflation, i.e. in the radiation phase. If this is the case, then the primordial entropy fluctuations could be directly observable, with the interesting possibility that there could be a correlation between the adiabatic and entropy modes \[31\].

In any case, one can introduce the correlation angle \( \Theta \), defined by

\[ \sin \Theta \equiv \frac{C_{RS}}{\sqrt{P_R} \sqrt{P_S}} \] (99)

which can also be seen as a transfer angle, since

\[ \sin \Theta = \frac{T_{RS}}{\sqrt{1 + T_{RS}^2}}. \] (100)

If \( \Theta = 0 \) there is no transfer \( (T_{RS} = 0) \), whereas if \( |\Theta| = \pi/2 \) \( (T_{RS} \gg 1) \) the final curvature perturbation is mostly of entropic origin. The relationship between the curvature power spectrum at sound horizon crossing and its final value is thus

\[ P_{R_\ast} = P_R \cos^2 \Theta. \] (101)

This implies, on using the tensor amplitude Eq. \[31\], that the tensor to scalar ratio is given by

\[ r \equiv \frac{P_T}{P_R} = 16 \epsilon c_s \cos^2 \Theta. \] (102)

Interestingly this expression combines the result of \( k \)-inflation \[11\], where the ratio is suppressed by the sound speed \( c_s \), and that of standard multi-field inflation \[30\].

From the expression of the curvature power spectrum, one can compute the scalar spectral index in the slow-varying approximation. We obtain

\[ n_R \equiv \frac{d \ln P_R}{d \ln k} = n_{R_\ast} + H_{\ast}^{-1} \sin(2\Theta) \frac{\partial T_{RS}}{\partial t_{\ast}} = n_{R_\ast} - \alpha_\ast \sin(2\Theta) - 2\beta_\ast \sin^2 \Theta \] (103)

with

\[ n_{R_\ast} - 1 = -2\epsilon_\ast - \eta_\ast - s_\ast, \] (104)

and where we have used

\[ H_{\ast}^{-1} \frac{\partial T_{SS}}{\partial t_{\ast}} = -T_{SS} \beta_\ast, \quad H_{\ast}^{-1} \frac{\partial T_{RS}}{\partial t_{\ast}} = -\alpha_\ast - T_{RS} \beta_\ast. \] (105)

The observable spectral index, given in Eq. \[103\], not only depends on the values of the various parameters at sound horizon crossing, but also on the transfer angle \( \Theta \).

\section{VI. NON-GAUSSIANITIES}

In the simplest models of inflation, primordial perturbations are characterized by a very small amount of non-Gaussianity \[20\]. However, other models, such as single-field DBI inflation, are expected to produce significant non-Gaussianity \[32\]. If ever detected, primordial non-Gaussianity would be a powerful discriminator between various early universe models. In order to study non-Gaussianities, one must analyse the perturbations beyond linear order. During inflation, primordial non-Gaussianities can arise from the quantum fluctuations at horizon crossing or, in the case of multi-field inflation, from the classical non-linear evolution on large scales (see e.g. \[33\] \[34\]).

In this section, we concentrate on the primordial non-Gaussianity originating from the three-point function of the scalar field fluctuations, which is the main contribution in single-field DBI inflation. Its calculation requires the third-order action in perturbations. Below, we first consider the general case — that is models of the form \[1\] — and then specialise to DBI.
A. Third-order action: general case

We follow the standard approach which has been presented in \cite{24,32,31,33}, considering successively the third-order action from the Einstein-Hilbert term and then from the matter part. A similar calculation of the third-order action can be found in \cite{35}, but only for the multi-field Lagrangians of the form $P(X,\phi^K)$, where $X = \delta_{ij}X^{ij}$.

The third-order action coming from the gravitational part is the same as in the single field case and is given by the expression

$$S^{(G)}_{(3)} = \frac{1}{2} \int dt \, d^3x \, a^3 \left\{ -\frac{\delta N}{a^3} \left[ (\partial_i \partial_j \psi) \partial^i \partial^j \psi - (\partial^2 \psi)^2 \right] + 4 \frac{H}{a^3} \partial^2 \psi (\delta N)^2 + 6H^2 (\delta N)^3 \right\},$$

(106)

where the relation between $\delta N$ and the field perturbations given in Eq. (111) can be rewritten as

$$\delta N \equiv N_A Q^A$$

(107)

with the (field-space) vector

$$N_A = \frac{1}{2H} P_{\langle AB \rangle} \dot{\phi}^B.$$  

(108)

By expanding systematically the matter part of the action up to third order, we finally find (intermediate steps can be found in Appendix 3)

$$S^{(M)}_{(3)} = \int dt \, d^3x \, a^3 \left\{ (g_1)_{ABC} Q^A Q^B Q^C + (g_2)_{ABC} Q^A Q^B \dot{Q}^C + (g_3)_{ABC} Q^A \dot{Q}^B \dot{Q}^C 
+ (g_4)_{ABC} \dot{Q}^A \dot{Q}^B \dot{Q}^C + (g_5)_{ABC} \partial_i \partial_j Q^B \partial^i \partial^j Q^C + (g_6)_{ABC} \partial_i \partial_j \dot{Q}^B \partial^i \partial^j \dot{Q}^C \right\}$$

(109)

with

$$(g_1)_{ABC} = \frac{1}{6} P_{ABC} + \frac{1}{2} P_{BCA} N_A - P_{<ij> X^{ij} N_A N_B N_C} + P_{<ij>,B X^{ij} N_A N_C} - 4P_{<ij>,<KL>X^{ij}X^{KL}N_A N_B N_C} - X^{ij} P_{<ij>,BC N_A} + 2P_{<ij>,<KL>C X^{ij}X^{KL}N_A N_B} - \frac{4}{3} P_{<ij>,<KL>,<MN>X^{ij}X^{KL}X^{MN}N_A N_B N_C}$$

(110)

$$(g_2)_{ABC} = 2H N_A N_B N_C + \frac{1}{2} P_{<KC>,ABC} \dot{\phi}^K + N_A \delta^K \left[ 5N_B X^{ij} P_{<ij>,<KC>} - P_{<KC>,B} + 2N_B X^{ij} X^{KL} P_{<ij>,<KL>,<KC>} - 2X^{ij} P_{<ij>,<KC>,B} \right]$$

(111)

$$(g_3)_{ABC} = -\frac{1}{2} N_A P_{<BC>} + \frac{1}{2} P_{<BC>,A} - N_A \left[ 3X^{IK} P_{<IB>,<KC>} + X^{KL} P_{<BC>,<KL>} \right] - 2N_A P_{<ij>,<KB>,<MC>} X^{ij} X^{KM} + P_{<IB>,<KC>,A} X^{IK}$$

(112)

$$(g_4)_{ABC} = \frac{1}{2} \delta^M P_{<BC>,<MA>} + \frac{1}{3} X^{IK} \dot{\phi}^M P_{<IA>,<KB>,<MC>}$$

(113)

$$(g_5)_{AB} = 2H N_A N_B + 2N_A X^{KL} \dot{\phi}^I P_{<IB>,<KL>} - \dot{\phi}^I P_{<IB>,A}$$

(114)

$$(g_6)_{AB} = -P_{<AB>} - 2X^{IK} P_{<IB>,<KA>}$$

(115)

$$(g_7)_{ABC} = N_A X^{KL} P_{<BC>,<KL>} - \frac{1}{2} P_{<BC>,A} - \frac{1}{2} P_{<BC>} N_A$$

(116)

$$(g_8)_{ABC} = -\frac{1}{2} \dot{\phi}^K P_{<BC>,<KA>}.$$  

(117)
In order to get a flavour for the new effects which could arise in multi-field inflation with non-standard kinetic terms, it is instructive to compare the above terms with their counterparts in standard multi-field inflation, such as studied in [30]. Substituting the standard matter Lagrangian

\[ P = G_{IJ} X^{IJ} - V(\phi), \quad G_{IJ} = \delta_{IJ}, \]  

the above coefficients reduce to

\[
(g_1)_{ABC} = - \frac{1}{6} V_{,ABC} - \frac{1}{2} V_{,BC} \mathcal{N}_A - X \mathcal{N}_A \mathcal{N}_B \mathcal{N}_C, \\
(g_2)_{ABC} = 2H \mathcal{N}_A \mathcal{N}_B \mathcal{N}_C, \quad (g_3)_{ABC} = - \frac{1}{2} \mathcal{N}_A G_{BC}, \quad (g_4)_{ABC} = 0, \\
(g_6)_{AB} = 2H \mathcal{N}_A \mathcal{N}_B, \quad (g_8)_{AB} = - G_{AB}, \quad (g_9)_{ABC} = - \frac{1}{2} G_{BC} \mathcal{N}_A, \quad (g_d)_{ABC} = 0. \quad (119)
\]

As we will see in the next subsection, the main contribution for DBI inflation will come precisely from the vertices associated with the coefficients \( g_4 \) and \( g_d \), which do not exist for standard kinetic terms.

### B. Non-Gaussianities in DBI inflation

Single-field DBI inflation is an inflationary model which naturally produces a (relatively) high level of non-Gaussianity in the small \( c_s \) limit, as shown in [3, 33]. It is thus important to investigate how the amplitude and shape of primordial non-Gaussianities are modified in the multi-field case [40, 41].

Here, we will focus on the dominant contributions to the non-Gaussianities for \( c_s \ll 1 \), and therefore ignore the contributions coming from the gravitational part of the action, which are known to be sub-dominant. As in the single-field case, the dominant contributions come from the terms involving derivatives of \( P \) with respect to the \( X^{IJ} \), because they are enhanced by negative powers of \( c_s \) with respect to the other terms. Moreover, terms containing \( \mathcal{N}_A \) are suppressed in the slow-varying approximation. Indeed, if one compares for example the first term of \( g_c \) with \( g_d \), one finds schematically

\[
\frac{g_c}{H g_d} \sim \frac{\dot{\sigma}^2}{H^2 c_s},
\]  

which is proportional to \( \epsilon = -\dot{H}/H^2 \) and thus small. Finally, the dominant contributions come from the following terms in \( S_{(3)} \):

\[
(g_4)_{IJK} \dot{Q}^I \dot{Q}^J \dot{Q}^K + (g_d)_{IJK} \dot{Q}^I h^{ik} \partial_j Q^J \partial_k Q^K. \quad (121)
\]

On substituting the multi-field DBI Lagrangian into the expressions given in Eqs. (113) and (117), the coefficients \( g_4 \) and \( g_d \) can be calculated explicitly (one needs the third derivative of \( P \) with respect to the \( X^{IJ} \), which can be deduced from Appendix I).

In the two-field case, decomposing the fields in terms of their adiabatic and entropic components according to (71), as well as using (122), one finally finds that the relevant terms of the third-order action are given by

\[
S_{(3)}^{(\text{main})} = \int dt d^3 x \left\{ \frac{a^3}{2c_s^2 \sigma} \left[ (\dot{Q}_\sigma)^3 + c_s^2 \dot{Q}_\sigma (\ddot{Q}_\sigma)^2 \right] - \frac{a}{2c_s^2 \sigma} \left[ \dot{Q}_\sigma (\nabla Q_\sigma)^2 - c_s^2 \dot{Q}_\sigma (\nabla Q_\sigma)^2 + 2c_s^2 \dot{Q}_\sigma \nabla Q_\sigma \nabla Q_\sigma \right] \right\}, \quad (122)
\]

where we have used the fact that \( f \simeq 1/\dot{\sigma}^2 \) in the limit \( c_s \ll 1 \). All the terms which appear in Eq. (122) are of the same order of magnitude, since \( Q_\sigma \simeq Q_\sigma/c_s \) as we have seen earlier. Note that using \( X \) instead of \( \dot{X} \) in the DBI action (that is, neglecting the higher order terms appearing in \( F \)) would lead to a different third-order action.

Let us now compute the contribution of these vertices to the relevant three-point functions, by following the procedure outlined in detail in [25]. Working at leading order in the slow varying regime, we use the adiabatic and entropic propagators defined by, respectively,

\[
\langle Q_\sigma(0) Q_\sigma(\tau) \rangle = \frac{H^2}{2k^3} (1 - i k c_s \tau) e^{i k c_s \tau}, \quad \langle Q_\sigma(0) Q_\sigma(\tau) \rangle = \frac{H^2}{2k^3} (1 - i k c_s \tau) e^{i k c_s \tau}, \quad (123)
\]

which correspond to the Fourier transforms of the Green functions, solutions of Eqs. (81) and (82) with \( \xi = 0 \) and \( z''/z = \alpha^3/\alpha = 2/\tau^2 \). The calculation of the three-point functions involve time integrations and we assume that, as
As we will see below, the three-point function of the curvatu re perturbation depends on the symmetrized (with respect 
where the ‘perm.’ indicate two other terms with the same stru cture as the last term but permutations of indices 1, 2
from the vertex proportional to $\dot{\sigma}$
Summing these contributions, we find
\begin{equation}
\langle Q_\sigma(k_1)Q_\sigma(k_2)Q_\sigma(k_3) \rangle = -2(2\pi)^3\delta\left(\sum_i k_i\right) \frac{H^4}{4\sqrt{2c_\epsilon c_\sigma}^2} \frac{1}{\prod_i k_i^3} \left[ -2k_1^2 k_2^2 k_3^2 
- k_1^2 (k_2 \cdot k_3)(2k_2 k_3 - k_1 K + 2K^2) 
+ k_3^2 (k_1 \cdot k_2)(2k_1 k_3 - k_2 K + 2K^2) \right].
\end{equation}
As we will see below, the three-point function of the curvature perturbation depends on the symmetrized (with respect to permutations of the three wave vectors $k_i$) version of this three-point function, and this has exactly the same shape as (127). Nevertheless, its amplitude is enhanced with respect to the purely adiabatic one by a factor of $1/c_\epsilon^2$. 

Let us now relate the correlation function of the scalar fields to the three-point function of the curvature perturbation \( \mathcal{R} \) which is the observable quantity. In order to do so, we use Eqs. (87), (89) and (90) to write

\[
\mathcal{R} \approx A_\sigma Q_{\sigma *} + A_s Q_{s *}
\]  

(132)

with

\[
A_\sigma = \left( \frac{H}{\dot\sigma} \right)_s, \quad A_s = T_{RS} \left( \frac{c_s H}{\dot\sigma} \right)_s.
\]

(133)

Let us compute the three-point function for three wave vectors of comparable magnitude (so that the coefficients \( A_\sigma \) and \( A_s \), which depend on the time at which the relevant scales cross the sound horizon, have approximately the same value). The two three-point functions of the fields we have calculated give the following contribution

\[
\langle \mathcal{R}(k_1)\mathcal{R}(k_2)\mathcal{R}(k_3) \rangle^{(3)} = (A_\sigma)^3 \langle Q_\sigma(k_1)Q_\sigma(k_2)Q_\sigma(k_3) \rangle + A_\sigma A_s \langle Q_\sigma(k_1)Q_s(k_2)Q_s(k_3) \rangle + \text{perm.}
\]

\[
= (A_\sigma)^3 \langle Q_\sigma(k_1)Q_\sigma(k_2)Q_s(k_3) \rangle \left( 1 + T_{RS}^2 \right)
\]

(134)

where the adiabatic three-point function is given in Eq. (127). Note that the enhancement of the mixed correlation \( \langle Q_\sigma Q_s Q_s \rangle \) by a factor of \( 1/c_s^2 \) is compensated by the ratio between \( A_s \) and \( A_\sigma \) so that the purely adiabatic and mixed contributions in (133) are exactly of the same order.

The superscript (3) in the above equation indicates that we take into account only the contribution from the three-point function of the scalar fields. One could also include the contribution from the four-point function of the scalar fields, which can be expressed in terms of the power spectra using Wick’s theorem, and also from other higher-order terms. This has been done for instance in [33, 34]. In the single-field DBI case, the corresponding contribution \( f_{NL}^{(4)} \) is negligible compared to \( f_{NL}^{(3)} \). Because of the transfer between adiabatic and entropic modes, this should be reconsidered in specific multi-field models. Here we simply disregard these contributions though it should be borne in mind that they are present in principle.

Instead of the three-point function, it is now customary to use the non-Gaussianity parameter \( f_{NL} \) defined by

\[
\langle \mathcal{R}(k_1)\mathcal{R}(k_2)\mathcal{R}(k_3) \rangle = - (2\pi)^7 \delta^3(\sum_i k_i) \left( \frac{3}{10} f_{NL} P_R \right)^2 \prod_i k_i^3.
\]

(135)

From the relation between \( P_R \) and \( P_{R*} \) given in Eq. (101), we then obtain, for the equilateral configuration,

\[
f_{NL}^{(3)} = - \frac{35}{108 c_s^2} \frac{1}{1 + T_{RS}^2} = - \frac{35}{108 c_s^2} \cos^2 \Theta.
\]

(136)

One can easily understand this result. The curvature power spectrum is amplified by a factor of \( (1 + T_{RS}^2) \) due to the feeding of curvature by entropy modes. Similarly the three-point correlation function for \( \mathcal{R} \) resulting from the three-point correlation functions of the adiabatic and entropy modes is enhanced by the same factor \( (1 + T_{RS}^2) \). However, since \( f_{NL} \) is roughly the ratio of the three-point function with respect to the square of the power spectrum, one sees that \( f_{NL} \) is now reduced by the factor \( (1 + T_{RS}^2) \). This may be important in confronting DBI models to observations [42, 43].

We end by revisiting the consistency condition relating the non-Gaussianity of the curvature perturbation, the tensor to scalar ratio \( r \), and the tensor spectral index \( n_T = -2\epsilon \), given in [45] for single-field DBI. In our case, substituting \( f_{NL}^{(3)} \simeq - \frac{1}{3} \frac{1}{c_s^2} \cos^2 \Theta \) in (102), gives

\[
r + 8n_T = - r \left( \sqrt{-3 f_{NL}^{(3)} \cos^{-3} \Theta} - 1 \right),
\]

(137)

As we can see from (136) and (137), violation of the standard inflation consistency relation (corresponding to a vanishing right-hand side in (137)) would be stronger in multi-field DBI than in single-field DBI, and thus easier to detect. In the multi-field case the consistency condition is only an inequality, unless the entropy modes survive after inflation in which case \( \Theta \) is potentially observable.
VII. CONCLUSIONS

In this paper we have studied cosmological perturbations in multi-field inflation models for which the Lagrangian depends \textit{a priori} on all the $N(N+1)/2$ kinetic terms that can be constructed by contracting the spacetime gradients of the $N$ scalar fields. Our analysis can be seen as the multi-field extension of $k$-inflation, and it also generalizes very recent papers which considered more restrictive Lagrangians of the form $P = P(X, \phi^K)$. In our very general framework, we have computed the second-order action which governs the dynamics of the linear perturbations, and were thus able to identify the propagation matrix whose eigenvalues correspond to the generalized propagation speeds.

We have argued that such a general framework is necessary in order to study multi-field DBI inflation. In that model, we showed that all modes propagate with the same speed of sound $c_s$, and hence (if light) they are all amplified simultaneously at sound horizon crossing. However, because their respective canonically normalized functions differ, the result is that the entropy modes are \textit{enhanced} with respect to the adiabatic modes: $Q_s \sim Q_a/c_s$. If there is a subsequent transfer from the entropy modes into the curvature perturbation — a generic feature as soon as the trajectory in field space is non trivial — the final amplitude of the curvature perturbation is significantly affected by the entropy modes.

We have also derived, in the general case, the third-order action from which one can compute the predictions for primordial non-Gaussianities. We have identified the vertices which appear in this action and expressed their coefficients in terms of the initial Lagrangian and its derivatives. In the DBI case, we have computed the dominant contributions to the non-Gaussianities of the curvature perturbation in the small $c_s$ limit. If there is an entropy-curvature transfer, we have shown that the contribution from the entropy modes will increase the amplitude of the three-point function with respect to the single field DBI prediction, but the shape of the non-Gaussianities remains exactly the same. Since the entropy modes enhance the curvature two-point and three-point functions by the same amount, it implies that the $f_{NL}$ parameter, which is related to the three-point function divided by the square of the two-point function, is smaller than in the single field case. The impact of the entropy modes can be expressed simply in terms of the entropy-curvature transfer coefficient, which is model-dependent. In the future, it would be interesting to study specific scenarios of DBI inflation and to estimate quantitatively this transfer coefficient.

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Appendix 1: the DBI Lagrangian and its derivatives

Calculation of the DBI determinant

The expression for $D$ in Eq. (15) can be obtained from its definition in Eq. (10) on substituting into

$$\det(A) = -\frac{1}{4!} \epsilon_{\alpha_1 \alpha_2 \alpha_3 \alpha_4} \epsilon^{\beta_1 \beta_2 \beta_3 \beta_4} A_{\beta_1}^{\alpha_1} A_{\beta_2}^{\alpha_2} A_{\beta_3}^{\alpha_3} A_{\beta_4}^{\alpha_4}$$

(138)

the matrix of components

$$A_{\beta}^{\alpha} = \delta_{\beta}^{\alpha} + f B_{I}^{\alpha} B_{\beta}^{I}, \quad B_{I}^{\alpha} \equiv G_{IJ} \partial^J \phi^I, \quad B_{I}^{\beta} \equiv \partial^I \phi^I.$$  

(139)

On using the identity

$$\epsilon_{\alpha_1 \alpha_2 \alpha_3 \alpha_4} \epsilon^{\alpha_1 \alpha_2 \beta_1 \beta_2 \beta_3 \beta_4} = -(4-j)! j! f \delta_{\alpha_{j+1}}^{[\beta_{j+1}} \ldots \delta_{\alpha_4]}^{\beta_4]}$$

(140)

and the contractions $B_{I}^{\alpha} B_{\alpha}^{I} = -2G_{IK} X_{K}^{I}$, one finally gets the expression

$$D = 1 - 2f G_{IJ} X_{I}^{J} + 4f^2 X_{I}^{[I} X_{J}^{J]} - 8f^3 X_{I}^{[I} X_{J}^{J} X_{K}^{K]} + 16f^4 X_{I}^{[I} X_{J}^{J} X_{K}^{K} X_{L}^{L]}.$$

(141)

If there are three scalar fields, the last term disappears because of the antisymmetrization over the field indices. For two scalar fields, the last two terms disappear; and for one scalar field, only the first two terms remain. For more than
four scalar fields, the truncation at order $f^4$ is natural if one considers $\mathcal{D}$ as the determinant of a $4 \times 4$ matrix, but it is less obvious if one starts from the expression for $\mathcal{D}$ as the determinant of a $N \times N$ matrix, Eq. (11). However, this can be understood by noting that the term proportional to $f^n$ is a sum of products involving $n$ terms of the form $X_I^J = -B^I_{\mu}B^\mu_J/2$. If $n > 4$, among the $n$ terms of the form $B^I_{\mu}$, at least two have the same index $\mu$ because the spacetime index $\mu$ can only take four different values. Since, by definition of the determinant, all the field indices $I$ are antisymmetrized, one thus finds that the term of order $f^n$ necessarily vanishes.

**Derivatives**

In order to compute the derivatives of the DBI Lagrangian with respect to $X_I^J$, one can use the explicit expression for $\mathcal{D}$ given above in Eq. (141). An alternative derivation, which is simpler, is to start from the identity

$$
\mathcal{D} = \exp[\text{Tr} \ln \mathcal{M}] = \exp[\text{Tr} \ln(\mathcal{M} + \delta \mathcal{M})] = \exp\{\text{Tr}[\ln(\mathcal{M}) + \ln(\text{Id} + \mathcal{M}^{-1} \delta \mathcal{M})]\},
$$

where the components of $\mathcal{M}$, given in [53], are decomposed into

$$
\mathcal{M}_I^J = \delta_I^J - 2f \mathcal{G}_{IK} \hat{X}^{KJ}, \quad \delta \mathcal{M}_I^J = -2f \mathcal{G}_{IK} \delta X^{KJ}.
$$

Moreover the components of the matrix $(\mathcal{M})^{-1}$ are the $\hat{G}_{I}^{J}$ given in Eq. (59).

Using (142), the expansion of $\mathcal{D}^{1/2}$ in terms of the matrix $U = \mathcal{M}^{-1} \delta \mathcal{M}$ yields

$$
\mathcal{D}^{1/2} = \bar{\mathcal{D}}^{1/2} \exp\left[\frac{1}{2} \text{Tr}(U) - \frac{1}{4} \text{Tr}(U^2) + \frac{1}{6} \text{Tr}(U^3) + \ldots\right]
$$

$$
= \bar{\mathcal{D}}^{1/2} \left[1 + \frac{1}{2} \text{Tr}(U) - \frac{1}{4} \text{Tr}(U^2) + \frac{1}{8} \text{Tr}(U^2)^2 + \frac{1}{6} \text{Tr}(U^3) - \frac{1}{8} \text{Tr}(U)\text{Tr}(U^2) + \frac{1}{48} (\text{Tr}U)^3 + \ldots\right].
$$

Substituting in the above expression the components

$$
U_I^J = -2f \mathcal{G}_{IK} \delta X^{KJ}
$$

of the matrix $U$, one gets

$$
\mathcal{D}^{1/2} = \bar{\mathcal{D}}^{1/2} \left[1 - f \hat{G}_{IJ} \delta X^{IJ} - \frac{f^2}{2} \left(2 \hat{G}_{IL} \hat{G}_{JK} - \hat{G}_{IJ} \hat{G}_{KL}\right) \delta X^{IJ} \delta X^{KL}
$$

$$
+ f^3 \left(\hat{G}_{IJ} \hat{G}_{KM} \hat{G}_{LN} - \frac{4}{3} \hat{G}_{IN} \hat{G}_{JK} \hat{G}_{LM} - \frac{1}{6} \hat{G}_{IJ} \hat{G}_{KL} \hat{G}_{MN}\right) \delta X^{IJ} \delta X^{KL} \delta X^{MN}\right].
$$

By interpreting this relation as a Taylor expansion with respect to the variables $X_I^J$, one can obtain the derivatives of $\mathcal{D}^{1/2}$ and thus of the DBI Lagrangian with respect to the $X_I^J$, up to third order, as required for the computation of the non-Gaussianities.

**Appendix 2: variations of $\hat{X}$ up to second order**

The computation of the first and second order variations of $\hat{X}$ follows from

$$
\delta^{(1)} \hat{X} = \delta^{(1)} X + \mathcal{F}_{<IJ>} \delta^{(1)} X^{IJ} + \mathcal{F}_{K} Q^{K}
$$

where

$$
\delta^{(1)} X^{IJ} = \dot{\phi}^{(I} \dot{Q}^{J)} - \dot{\phi}^{I} \dot{\phi}^{J} \delta N,
$$

and also from

$$
\delta^{(2)} \hat{X} = \delta^{(2)} X + \mathcal{F}_{<IJ>} \delta^{(2)} X^{IJ} + \frac{1}{2} \mathcal{F}_{<IJ>,<KL>} \delta^{(1)} X^{IJ} \delta^{(1)} X^{KL} + \frac{1}{2} \mathcal{F}_{K} Q^{K} Q^{L} + \mathcal{F}_{<IJ>,<K} \delta^{(1)} X^{IJ} Q^{K}
$$

where

$$
\delta^{(2)} X^{IJ} = \frac{1}{2} \dot{Q}^{I} \dot{Q}^{J} + \frac{3}{2} \dot{\phi}^{I} \dot{\phi}^{J} \delta N^2 + \phi^{(I} \delta^{(2)} \phi^{J)} - \frac{1}{2} h^{ij} \partial_i Q^I \partial_j Q^J - 2 \dot{\phi}^{(I} \dot{Q}^{J)} \delta N.
$$
From the explicit expression for $\mathcal{F}$ in Eq. (19), we immediately see that its antisymmetric structure implies that $\mathcal{F}_{JK} = \mathcal{F}_{KL} = 0$. We also find

$$\mathcal{F}_{IJ} = -2f X_{IJ},$$
(151)

$$\mathcal{F}_{<IJ>,KL>} = 2f c_k^2 \left( \tilde{G}_{I(K} \tilde{G}_{L),J} - \tilde{G}_{IJ} \tilde{G}_{KL} \right),$$
(152)

$$\mathcal{F}_{<IJ>,K} = -2f X \left( G_{IJ,K} + G_{IJ}e^L e^M G_{LM,K} - e_I e^L G_{JL,K} - e_J e^L G_{IL,K} \right) - 2f_{JK} X_{IJ},$$
(153)

where the first two identities can be deduced from Eqs. (61) and (62). This readily gives

$$\delta^{(1)} X = \delta^{(1)} X, \quad \delta^{(2)} X = \delta^{(2)} X + f X_{IJ} h^{IJ} \partial_i Q^I \partial_j Q^J.$$  
(154)

Appendix 3: third-order action

The following relations are useful for determining the third-order action:

$$X^{IJ} = \frac{1}{2} \delta^{(1)} \dot{X}^J + \delta^{(1)} X^{IJ} + \delta^{(2)} X^{IJ} + \delta^{(3)} X^{IJ}$$
(155)

where we have used Eq. (108) to rewrite (148) and (150) in the form

$$\delta^{(1)} X^{IJ} = -2N_A X^{IJ} Q^A + \phi^{(1)} \dot{Q}^I$$
(156)

$$\delta^{(2)} X^{IJ} = -2N_A \dot{\phi}^{(1)} \dot{Q}^I Q^A + 3N_A N_B X^{IJ} Q^A Q^B + \frac{1}{2} \dot{Q}^I \dot{Q}^J - \dot{\phi}^{(1)} \delta_i Q^J \left( Q^i - \frac{1}{2} h^{ij} \partial_i Q^I \partial_j Q^J \right).$$
(157)

We also have

$$P_{<IJ>} \delta^{(3)} X^{IJ} = -4P_{<IJ>} X^{IJ} N_A N_B N_C Q^A Q^B Q^C + 6H N_A N_B N_C Q^A Q^B Q^C$$

$$-P_{<BC>} N_A Q^A Q^B Q^C + 4H N_B N_A Q^A \partial_i Q^B \delta^i N^i$$

$$-P_{<AB>} Q^A \partial_j Q^B \partial_i Q^j \delta^i N^i$$
(158)

as well as

$$\delta^{(2)} P = P_{<IJ>} \delta^{(2)} X^{IJ} + \frac{1}{2} P_{<IJ>,<KL>} \delta^{(1)} X^{KL} + \frac{1}{2} P_{<IJ>,K} Q^K \delta^{(1)} X^{IJ} + \frac{1}{2} P_{<KL} Q^K Q^L$$
(159)

and

$$\delta^{(3)} P = P_{<IJ>} \delta^{(3)} X^{IJ} + \left[ P_{<IJ>,<KL>} \delta^{(2)} X^{IJ} \delta^{(1)} X^{KL} + P_{<IJ>,K} Q^K \delta^{(2)} X^{IJ} \right]$$

$$+ \frac{1}{6} \left[ P_{<IJ>,<KL>,<MN>} \delta^{(1)} X^{IJ} \delta^{(1)} X^{KL} \delta^{(1)} X^{MN} + P_{<JK} Q^J Q^J Q^K \right]$$

$$+ \frac{1}{2} \left[ P_{<IJ>,<KL>,M} Q^M \delta^{(1)} X^{IJ} \delta^{(1)} X^{KL} + P_{<MN>,IJ} Q^J Q^J \delta^{(1)} X^{MN} \right].$$
(160)

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