Ulam–Hyers–Mittag-Leffler stability for tripled system of weighted fractional operator with TIME delay

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Abstract

This study is aimed to investigate the sufficient conditions of the existence of unique solutions and the Ulam–Hyers–Mittag-Leffler (UHML) stability for a tripled system of weighted generalized Caputo fractional derivatives investigated by Jarad et al. (Fractals 28:2040011 2020) in the frame of Chebyshev and Bielecki norms with time delay. The acquired results are obtained by using Banach fixed point theorems and the Picard operator (PO) method. Finally, a pertinent example of the results obtained is demonstrated.

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1 Introduction

The topic of fractional differential equations (FDEs) has attracted the interest of researchers from various disciplines thanks to it being considered a useful gizmo in modeling the dynamics of various physical systems and their applications in many fields of applied sciences, engineering and technical sciences, etc. For further details, we refer the readers to [2–5].

There are various definitions of fractional calculus (FC) that developed the (FDEs) in modeling and describe the memory accurately. Among these famous operators are Riemann–Liouville, Riemann, Grunwald–Letnikov, Caputo, Hilfer and Hadamard which are the foremost used. For more details, we refer the readers to [1, 6–17]. There is a prominent and noticeable interest within the investigation of qualitative characteristics of solutions (existence, uniqueness, stability) of (FDEs). For applications and up-to-date work, we refer the readers to [18–26].

On the other hand, the study of coupled systems involving (FDEs) is additionally important as intrinsically systems occur in various problems of applied nature. For a few theoretical works on coupled systems of (FDEs), we refer to a series of papers [27–31].
The topic of stability of systems is one among the foremost important qualitative characteristics of a solution. But as far as we know, this is often the primary work with regard to a tripled system of weighted fractional differential equations with time delay.

Tripled fractional boundary systems may be a generalization of coupled fractional systems as they are governed by three associated differential equations with three conditions [32, 33].

Recently, Matar et al. [34], by means of some fixed point theorems like Banach and Krasnoselskii, studied the existence and uniqueness of solutions of the tripled system

\[ C_D^{\kappa_i} \zeta_i(x) = f_i(x, \zeta(x)), \quad \kappa_i \in (1, 2) \]

with cyclic permutation boundary conditions

\[ \zeta_i(j) |_{(0)} = a_{kj} \zeta_{\sigma(j)} |_{(T)}, \quad i = 1, 2, 3, j = 0, 1, \]

where \( C_D^{\kappa_i} \) denotes the Caputo fractional derivative (CFD) of order \( \kappa_i, i = 1, 2, 3, f_i : [0, T] \times \mathbb{R}^3 \rightarrow \mathbb{R} \) are continuous functions, \( \sigma = (1, 2, 3) \) is a cycle permutation.

Wang and Zhang [35], by means of the Banach fixed point theorem and the Picard operator method, studied existence, uniqueness, and UHML stability results with respect to Chebyshev and Bielecki norms of the following problem:

\[ C_D^{\kappa_i} \zeta(x) = f(x, \zeta(x), \zeta(h(x))), \quad x \in [0, b], \kappa \in (0, 1), \]

\[ \zeta(0) = a_0, \]

where \( C_D^{\kappa} \) is the Caputo FD of order \( \kappa \).

Motivated by the preceding works, in the current paper, we investigate the existence of a unique solution and a UHML stability result for a tripled system of weighted Caputo fractional differential equations (TSWFDEs) with time delay

\[
\begin{cases}
C_D^{\kappa_i} |_{w^{\phi}\kappa_i} \zeta_i(x) = f_i(x, \zeta_1(x), \zeta_2(x), \zeta_3(x), \zeta_1(h(x)), \zeta_2(h(x)), \zeta_3(h(x))), \quad x \in J := (0, b], \\
\zeta_i(0) = a_i \in \mathbb{R}, \quad i = 1, 2, 3, \\
\zeta_i(x) = g_i(x), \quad x \in [-r, 0],
\end{cases}
\] (1.1)

where \( C_D^{\kappa_i} |_{w^{\phi}\kappa_i} \) is the weighted generalized Caputo fractional derivative (WCFD) of order \( \kappa_i \in (0, 1) \), \( w_{\phi} : \mathbb{R}^3 \times \mathbb{R}^3 \rightarrow \mathbb{R} \) is a given continuous function, \( w(x) \neq 0 \) is a weighted function with \( w^{-1}(x) = \frac{1}{w(x)} \), \( \phi : (0, b] \rightarrow \mathbb{R}^+ \) is strictly increasing such that \( \phi \in C([0, b]), \phi' \in C([-r, 0], \mathbb{R}) \) and \( h \in C([-r, b], \mathbb{R}) \) with \( h(x) \leq x, r > 0 \). For simplicity, we denote the sequence of functions \( (\zeta_1(x), \zeta_2(x), \zeta_3(x)) \) by \( \zeta(x) \) and \( (\zeta_1(h(x)), \zeta_2(h(x)), \zeta_3(h(x))) \) by \( \zeta(h(x)) \). In the sequel, the functions such as \( f_1(x, \zeta_1(x), \zeta_2(x), \zeta_3(x), \zeta_1(h(x)), \zeta_2(h(x)), \zeta_3(h(x))) \) will be written as \( f(x, \zeta(x), \zeta(h(x))) \).

By a solution of system (1.1), it is meant that there is a sequence \( \zeta = (\zeta_1, \zeta_2, \zeta_3) \) satisfying system (1.1) on \( (0, b] \).

The major contribution of this paper is to derive equivalent fractional integral equations to the (TSWFDEs) and to establish the existence of a unique solution and Ulam–Hyers–Mittag-Leffler stability results for (TSWFDEs) with respect to Chebyshev and Bielecki.
norms with time delay. The Picard operator method and the Banach fixed point theorem are the important tools used to prove our main result. To the best of our observation, there is no analytical literature on studying the existence of tripled systems of fractional differential equations (TSWFDEs). This paper is the first work to study the existence of a unique solution and an Ulam–Hyers–Mittag-Leffler stability result for (TSWFDEs) with respect to Chebyshev and Bielecki norms with time delay.

This paper is systematized as follows: In Sect. 2, we render the rudimentary definitions and prove some lemmas that are applied throughout this paper, also we present the concepts of some fixed point theorems. In Sect. 3, we prove the existence of unique solutions and (UHML) stability results of system (1.1) under Chebyshev and Bielecki norms. In Sect. 4, we give a pertinent example to illustrate our results. Concluding remarks about our results are given in the last section.

2 Preliminaries

In this part, we give important definitions and auxiliary lemmas that are pertinent to our main results.

Let \( E = C([-r, b], \mathbb{R}) \) and \( \Omega = C([0, b], \mathbb{R}) \), \( (b > 0) \) be the Banach spaces of continuous function \( u : [-r, b] \to \mathbb{R} \) and \( v : [0, b] \to \mathbb{R} \) with the norms

\[
\|u\|_E = \max_{x \in [-r, b]} |u(x)|
\]

and

\[
\|v\|_\Omega = \max_{x \in [0, b]} |v(x)|,
\]

respectively. Clearly, \( E \) and \( \Omega \) are the Banach spaces with the above norms. Let \( E^* := E \times E \times E \) and \( \Omega^* := \Omega \times \Omega \times \Omega \) be the product spaces with the norms

\[
\|(u_1, u_2, u_3)\|_{E^*} = \sum_{i=1}^{3} \|u_i\|_E, \quad (u_1, u_2, u_3) \in E^*
\]

and

\[
\|(v_1, v_2, v_3)\|_{\Omega^*} = \sum_{i=1}^{3} \|v_i\|_\Omega, \quad (v_1, v_2, v_3) \in \Omega^*,
\]

respectively.

Definition 2.1 ([1]) Let \( \kappa > 0 \) and \( \varsigma : [0, b] \to \mathbb{R} \) be an integrable function. Then (WCFI) and (WCDF) are given by

\[
_wT^{\kappa, \varsigma}_0(\varsigma) = \frac{w^{-1}(\varsigma)}{\Gamma(\kappa)} \int_0^\kappa w(s)N^{\kappa-1}_{\varsigma'}(\kappa, s)\varsigma(s)\,ds
\]

and

\[
C_wD^{\kappa, \varsigma}_0(\varsigma) = w^{-1}(\varsigma) \left( \frac{1}{\psi'(\varsigma)} \frac{d}{d\varsigma} \right)^n w_T^{n-\kappa, \varsigma}(\varsigma),
\]
respectively, where $\mathcal{N}_\psi^k(x,s) = \psi'(s)(\psi(x) - \psi(s))^{k-1}$, $n = \lceil k \rceil + 1$, and $\psi$ is a strictly increasing function on $[0, b]$.

**Definition 2.2** ([1]) Let $\kappa \in (n-1, n)$, $n \in \mathbb{N}$, and $\zeta \in A^\infty_{\psi}[0, b]$. Then (WCFD) is given by

$$
\mathcal{C}^D_{0+}^\kappa,\psi \zeta(x) = w D_{0+}^\kappa w^{-1} \left[ \zeta(x) - w^{-1}(x) \sum_{i=1}^{n-1} \frac{\zeta^{[i]}(0)}{i!} (\psi(x) - \psi(0))^i \right],
$$

where $n = \lceil \kappa \rceil + 1$ and $\zeta^{[i]}(0) = \left( \frac{1}{\psi(x)} \frac{d}{dx} \right)^i (w(x) \zeta(x))$. Moreover, $\mathcal{C}^D_{0+}^\kappa,\psi$ can be written as

$$
\mathcal{C}^D_{0+}^\kappa,\psi \zeta(x) = w D_{0+}^\kappa w^{-1}(x) \left( \frac{1}{\psi(x)} \frac{d}{dx} \right)^n \zeta(x)
$$

$$
= w^{-1}(x) \Gamma(n - \kappa) \int_0^x w(s) \mathcal{N}_{\psi}^{\kappa-1}(x,s) \zeta^{[n]}(s) ds,
$$

where $n = \lceil \kappa \rceil + 1$ and $\zeta^{[n]}(x) = \left( \frac{1}{\psi(x)} \frac{d}{dx} \right)^n (\zeta(x))$. In particular, if $\kappa = n \in \mathbb{N}$, we have $\mathcal{C}^D_{0+}^\kappa,\psi \zeta(x) = \zeta^{[n]}(x)$.

**Lemma 2.3** ([1]) Let $\kappa, \gamma > 0$. Then

$$
w D_{0+}^\kappa \left[ w^{-1}(x) (\psi(x) - \psi(0))^{\gamma-1} \right] = \frac{\Gamma(\gamma)}{\Gamma(\kappa + \gamma)} \left( \psi(x) - \psi(0) \right)^{\kappa+\gamma-1}
$$

(2.1)

and

$$
\mathcal{C}^D_{0+}^\kappa \left[ w^{-1}(x) (\psi(x) - \psi(0))^{\gamma-1} \right] = \frac{\Gamma(\gamma)}{\Gamma(\kappa - \gamma)} \left( \psi(x) - \psi(0) \right)^{\kappa-\gamma-1}
$$

in case $\mathcal{C}^D_{0+}^\kappa \left[ w^{-1}(x) (\psi(x) - \psi(0))^{\gamma-1} \right] = 0$ for all $\gamma - 1 \in \{0, 1, \ldots, n-1\}$, $n \in \mathbb{N}$.

**Remark 2.4** ([1]) If $w(x) = 1$, then equation (2.1) reduces to the relation obtained in Kilbas et al. [3].

**Lemma 2.5** ([1]) For $\kappa \in (n-1, n)$, $n \in \mathbb{N}$, we have

$$
w D_{0+}^\kappa w D_{0+}^\kappa \zeta(x) = \zeta(x)
$$

and

$$
w D_{0+}^\kappa w \mathcal{C}^D_{0+}^\kappa \zeta(x) = \zeta(x) - w^{-1}(x) \sum_{i=1}^{n-1} \frac{\zeta^{[i]}(0)}{i!} (\psi(x) - \psi(0))^i.
$$

(2.2)

In this paper, due to $\kappa \in (0, 1)$, then

$$
w D_{0+}^\kappa w \mathcal{C}^D_{0+}^\kappa \zeta(x) = \zeta(x) - \frac{1}{w(x)} (w(0) \zeta(0)).
$$

**Lemma 2.6** ([1]) Let $\kappa > 0$. Then $w T_{0+}^\kappa : (C[0,b], \mathbb{R}) \to (C[0,b], \mathbb{R})$ is bounded. Moreover,

$$
w T_{0+}^\kappa \zeta(x) = \lim_{x \to 0^+} w T_{0+}^\kappa \zeta(x) = 0.
$$
Lemma 2.8 ([35]) Let \(X,d,\leq\) be an ordered metric space, and let \(T:X \rightarrow X\) be an increasing Picard operator with \(F_T = \{\xi \in X : T(\xi) = \xi\}\) is the fixed point set of \(T\), and the sequence \((T^n(\xi_0))_{n \in \mathbb{N}}\) converges to \(\xi^*\) for all \(\xi_0 \in X\).

Remark 2.9 A sequence \((\xi_1, \xi_2, \xi_3) \in E^*\) satisfies the inequality

\[
\left| |\mathcal{E}_0^{\xi_0,\rho} \xi_i(\sigma) - f_i(\sigma, \xi_i, \xi_j(h(\sigma)))| \right| \leq \varepsilon_i E_{x_i} \left( \sigma - \sigma(0) \right)^\epsilon, \quad i = 1, 2, \ldots, n, \quad \sigma \in (0, b],
\]

if only if there exists a function \(\eta_i(\sigma) \in \Omega\) such that

1. \( |w(\sigma)\eta_i(\sigma)| \leq \varepsilon_i E_{x_i} \left( \sigma - \sigma(0) \right)^\epsilon, \quad \sigma \in (0, b];
2. \( \mathcal{E}_0^{\xi_0,\rho} \xi_i(\sigma) = f_i(\sigma, \xi_i, \xi_j(h(\sigma))) + \eta_i(\sigma), \quad \sigma \in (0, b].

Definition 2.10 System (1.1) is (UHML) stable with respect to \(E_x((\sigma - \sigma(0))\xi) = \max_{x \in (0, b]} \left| E_{x_i} \left( \sigma - \sigma(0) \right)^\epsilon, \quad i = 1, 2, 3, \text{ if there exists } M > 0 \text{ such that, for each } \varepsilon = \max \{|\epsilon_1, \epsilon_2, \epsilon_3| > 0 \text{ and each sequence } (\xi_1, \xi_2, \xi_3) \in E^* \text{ satisfies inequality (2.3), there exists a solution } (\xi_1, \xi_2, \xi_3) \in E^* \text{ of system (1.1) with}\n
\[
\left\| (\xi_1, \xi_2, \xi_3) - (\xi_1, \xi_2, \xi_3) \right\|_{L^*} \leq M \varepsilon E_{x_i} \left( \sigma - \sigma(0) \right)^\epsilon, \quad \sigma \in (0, b].
\]

Lemma 2.11 Let \(i = 1, 2, 3\) and \(w_i: (0, b] \times \mathbb{R}^3 \times \mathbb{R}^3 \rightarrow \mathbb{R}\) be continuous functions. If the sequence \((\xi_1, \xi_2, \xi_3) \in E^*\) satisfies system (1.1), then, in view of Lemma 2.5, we can easily prove that \((\xi_1, \xi_2, \xi_3)\) satisfies the following integral equations:

\[
\xi_i(\sigma) = \begin{cases} \frac{w(0)}{w(\sigma)} d_i + \int_0^\sigma \mathcal{E}_0^{\xi_0,\rho} f_i(s, \xi(s), \xi(s)(h(s))) (\sigma) ds, & \sigma \in [0, b], \\
\partial_i(\sigma), & \sigma \in [-r, 0], \end{cases}
\]

for all \(i = 1, 2, 3\).

Lemma 2.12 Let \(k_i \in (0, 1), i = 1, 2, 3,\) and \(\mu = \max_{\sigma \in (0, b]} |w(\sigma)|\). If a sequence \((\xi_1, \xi_2, \xi_3) \in E^*\) satisfies inequality (2.3), then \((\xi_1, \xi_2, \xi_3)\) satisfies the following integral inequality:

\[
\left| \mathcal{E}_0^{\xi_0,\rho} \xi_i(\sigma) - \frac{w(0)}{w(\sigma)} d_i + \frac{w^{-1}(\sigma)}{\Gamma(k_i)} \int_0^\sigma w(s) N_{\rho}^{\xi_0^{-1}}(\sigma, s) f_i(s, \xi(s), \xi(s)(h(s))) ds \right| \leq \varepsilon_i E_{x_i} \left( \sigma - \sigma(0) \right)^\epsilon.
\]

Proof Let \((\xi_1, \xi_2, \xi_3) \in E^*\) satisfy inequality (2.3). Then, in the light of Remark 2.9 and Lemma 2.11, we have

\[
\mathcal{E}_0^{\xi_0,\rho} \xi_i(\sigma) = \frac{w(0)}{w(\sigma)} d_i + \frac{w^{-1}(\sigma)}{\Gamma(k_i)} \int_0^\sigma w(s) N_{\rho}^{\xi_0^{-1}}(\sigma, s) f_i(s, \xi(s), \xi(s)(h(s))) ds
\]
Thus, we have

\[ \left| \bar{\zeta}(x) - \frac{w(0)}{w(x)} G_i(x) - \frac{w^{-1}(x)}{G_i(x)} \int_0^x w(s)N_{\psi}^{\kappa-1}(x, s) \eta_i(s) \right| \leq \varepsilon_i \frac{w^{-1}(x)}{G_i(x)} \int_0^x \left| N_{\psi}^{\kappa-1}(x, s) \right| |\eta_i(s)| ds \]

\[ \leq \varepsilon_i \frac{1}{G_i(x)} \int_0^x \left| N_{\psi}^{\kappa-1}(x, s) \right| E_i(x) (\varphi(s) - \varphi(0))^{\kappa_i} ds \]

\[ \leq \varepsilon_i \sum_{n=1}^{\infty} \frac{1}{(n+1)\kappa_i + 1} \int_0^x \left| N_{\psi}^{\kappa-1}(x, s) \right| (\varphi(s) - \varphi(0))^{\kappa_i} ds \]

\[ \leq \varepsilon_i \sum_{n=1}^{\infty} \frac{1}{(n+1)\kappa_i + 1} \frac{1}{\mu} F_i (\varphi(x) - \varphi(0))^{\kappa_i} \]

Let us consider the continuous operator \( G : E^* \to E^* \) defined by

\[ G_i(x) = \left( G_1(x), G_2(x), G_3(x) \right) \]

where

\[ G_1(x) = \begin{cases} \frac{w(0)}{w(x)} a_1 + w(x) \int_{-\kappa_i}^0 f_1(x, \zeta(s), \zeta(h(s))) ds, & \kappa_i \in (0, b], \\ \vartheta_1(x), & \kappa_i \in [-r, 0], \end{cases} \]

\[ G_2(x) = \begin{cases} \frac{w(0)}{w(x)} a_2 + w(x) \int_{-\kappa_i}^0 f_2(x, \zeta(s), \zeta(h(s))) ds, & \kappa_i \in (0, b], \\ \vartheta_2(x), & \kappa_i \in [-r, 0], \end{cases} \]

and

\[ G_3(x) = \begin{cases} \frac{w(0)}{w(x)} a_3 + w(x) \int_{-\kappa_i}^0 f_3(x, \zeta(s), \zeta(h(s))) ds, & \kappa_i \in (0, b], \\ \vartheta_3(x), & \kappa_i \in [-r, 0]. \end{cases} \]

### 3 Main results

In this section, we prove the existence of a unique solution and a (UHML) stability result for system (1.1) with respect to Chebyshev and Bielecki norms with time delay. For our analysis, the following hypotheses should be satisfied.

(H1) \( w_i \in C([0, b] \times \mathbb{R}^3 \times \mathbb{R}, \mathbb{R}) \), \( h \in C([0, b] \times [-r, b]) \), \( b(x) \leq x, r > 0, i = 1, 2, 3 \).

(H1) \( w_i : [0, b] \times \mathbb{R}^3 \times \mathbb{R}^3 \to \mathbb{R} \) are continuous functions and there exists \( L_i > 0 \) such that

\[ |w(x)f_i(x, \zeta, z) - w(x)f_i(x, v, y)| \leq L_i \sum_{k=1}^3 |z_k - v_k| + |z_k - x_k| \]

for all \( x \in (0, b], \zeta, v, z, y \in \mathbb{R}^3 \).
Theorem 3.1 Assume that (H1) and (H2) are satisfied. If

\[ \gamma = \sum_{i=1}^{3} \frac{2L_i (\varphi(b) - \varphi(0))^{\kappa_i}}{\Gamma(k_i + 1)} < 1, \]

then system (1.1) has a unique solution \( \zeta = (\zeta_1, \zeta_2, \zeta_3) \in \Xi := E \cap \Omega \times E \cap \Omega \times E \cap \Omega. \)

Proof Define a closed ball set as \( P_\zeta = \{ (\zeta_1, \zeta_2, \zeta_3) \in E^3 : \| (\zeta_1, \zeta_2, \zeta_3) \| E \leq \zeta \} \) with \( \zeta \geq \frac{\Lambda}{1 - \gamma}, \)

where

\[ \Lambda := \sum_{i=1}^{3} \left[ \frac{|w(0)|}{\mu} a_i + \frac{2L_i \hat{f}_i(\varphi(b) - \varphi(0))^{\kappa_i}}{\Gamma(k_i + 1)} \right] \]

and \( \hat{f}_i = \sup_{s \in [0,b]} |w_f(s,0,0)|, \mu = \max_{s \in [0,b]} |w(s)|. \) In order to examine the existence of a unique solution by means of the Banach fixed point theorem, we only prove that the operator \( G(\zeta) \) defined by (2.5) has a fixed point in \( \Xi. \) For this purpose, we split the proof into the following steps.

Step (1): \( G(\zeta) \) is continuous.

From the continuity of functions \( w_f(s,\zeta(s),h(s)) \), we deduce that the operator \( G(\zeta_1, \zeta_2, \zeta_3) \) is continuous too.

Step (2): \( G(\zeta) \in P_\zeta \)

Case (1). For each \( \zeta = (\zeta_1, \zeta_2, \zeta_3) \in P_\zeta \) and for \( \varphi \in [-r,0], \) we have

\[ \| G_i(\zeta_1, \zeta_2, \zeta_3) \| E_i = \| \vartheta_i \| E, \quad i = 1, 2, 3. \]

Hence

\[ \| G(\zeta_1, \zeta_2, \zeta_3) \| E \leq \| \vartheta_1 \| E + \| \vartheta_2 \| E + \| \vartheta_3 \| E \]

\[ \leq \| (\vartheta_1, \vartheta_2, \vartheta_3) \| E \leq \zeta. \]

Case (2). For each \( \zeta = (\zeta_1, \zeta_2, \zeta_3) \in P_\zeta \) and for \( \varphi \in [0,b], \) we have

\[ |G_i(\zeta_1, \zeta_2, \zeta_3)| \]

\[ \leq \| w(0) \| \frac{|w(s)|}{|w(\varphi)|} a_i + \frac{w^{-1}(\varphi)}{\Gamma(k)} \int_{0}^{\varphi} N_{\psi}^{\kappa-1}(\varphi,s) \]

\[ \times \left\{ |w(s)f_1(s,\zeta(s),h(s))| + |w(s)f_2(s,0,0)| \right\} ds \]

\[ \leq \| w(0) \| \frac{L_i}{\mu \Gamma(k)} \int_{0}^{\varphi} N_{\psi}^{\kappa-1}(\varphi,s) \left[ |\zeta_1(s)| + |\zeta_2(s)| + |\zeta_3(s)| \right] \]

\[ + |\zeta_1(h(s))| + |\zeta_2(h(s))| + |\zeta_3(h(s))| + |w(s)f_3(s,0,0)| \] ds

\[ \leq \frac{\| w(0) \|}{\mu} a_i + \frac{2L_i \hat{f}_i}{\mu \Gamma(k)} \left\{ \| \zeta_1 \| E + \| \zeta_2 \| E + \| \zeta_3 \| E \right\} + \hat{f}_i \int_{0}^{\varphi} N_{\psi}^{\kappa-1}(\varphi,s) ds \]

\[ \leq \frac{\| w(0) \|}{\mu} a_i + \frac{2L_i \hat{f}_i}{\mu \Gamma(k)} \left\{ \| \zeta_1 \| E + \| \zeta_2 \| E + \| \zeta_3 \| E \right\} \frac{(\varphi(s) - \varphi(0))^{\kappa_i}}{\Gamma(k_i + 1)} \]

\[ \leq \frac{\| w(0) \|}{\mu} a_i + \frac{2L_i \hat{f}_i}{\mu \Gamma(k)} \left( \zeta + \hat{f}_i \right) \frac{(\varphi(s) - \varphi(0))^{\kappa_i}}{\Gamma(k_i + 1)} \]
\[
\frac{|w(0)|}{\mu} - d_i + \frac{2L_i}{\mu} \frac{(\varphi(b) - \varphi(0))^{\kappa}}{\Gamma(\kappa_i + 1)} + \frac{2L_i}{\mu} \frac{(\varphi(b) - \varphi(0))^{\kappa}}{\Gamma(\kappa_i + 1)} \zeta,
\]
which implies
\[
\| \mathcal{G}(s_1, s_2, s_3) \|_E^E
= \| \mathcal{G}_1(s_1, s_2, s_3) \|_E + \| \mathcal{G}_2(s_1, s_2, s_3) \|_E + \| \mathcal{G}_3(s_1, s_2, s_3) \|_E
\leq \sum_{i=1}^{3} \left[ \frac{|w(0)|}{\mu} - d_i + \frac{2L_i}{\mu} \frac{(\varphi(b) - \varphi(0))^{\kappa}}{\Gamma(\kappa_i + 1)} \zeta \right],
\]
\[
< \Lambda + \zeta \gamma \leq \zeta.
\]

This proves that \( \mathcal{G}(\zeta) \in \mathbb{P}_\zeta \).

**Step (3):** \( \mathcal{G}(\zeta) \) is a contraction in \( \mathbb{P}_\zeta \).

In this step, we will show that the operator \( \mathcal{G}(\zeta) \) is a contraction mapping on \( \mathbb{P}_\zeta \) with respect to the norm \( \| (s_1, s_2, s_3) \|_E = \| s_1 \|_E + \| s_2 \|_E + \| s_3 \|_E \).

Case (1): For \( (s_1, s_2, s_3), (v_1, v_2, v_3) \in \mathbb{P}_\zeta \) and \( \zeta \in [-r, 0] \), we have
\[
\| \mathcal{G}_i(s_1, s_2, s_3) - \mathcal{G}_i(v_1, v_2, v_3) \|_E = 0, \quad i = 1, 2, 3.
\]

It follows that
\[
\| \mathcal{G}(s_1, s_2, s_3) - \mathcal{G}(v_1, v_2, v_3) \|_E = \sum_{i=1}^{3} \| \mathcal{G}_i(s_1, s_2, s_3) - \mathcal{G}_i(v_1, v_2, v_3) \|_E
= 0 \leq \gamma \| (s_1, s_2, s_3) - (v_1, v_2, v_3) \|_E.
\]

Case (2): For \( (s_1, s_2, s_3), (v_1, v_2, v_3) \in \mathbb{P}_\zeta, \zeta \in (0, b] \) and by (H2), we obtain
\[
\| \mathcal{G}_i(s_1, s_2, s_3) - \mathcal{G}_i(v_1, v_2, v_3) \|_E
\leq \frac{w^{-1}(\zeta)}{\Gamma(\kappa_i)} \int_0^\infty w(s) \mathcal{N}^{-1}_v(\zeta, s) \left| \left| f_i(s, \zeta(s), \zeta(h(s))) - f_i(s, v(s), v(h(s))) \right| \right| ds
\leq \frac{w^{-1}(\zeta)}{\Gamma(\kappa_i)} \int_0^\infty \mathcal{N}^{-1}_v(\zeta, s) \left| \left| f_i(s, \zeta(s), \zeta(h(s))) - f_i(s, v(s), v(h(s))) \right| \right| ds
\leq \frac{L_i}{\mu \Gamma(\kappa_i)} \int_0^\infty \mathcal{N}^{-1}_v(\zeta, s) \left| \left| s_1(s) - v_1(s) \right| + \left| s_2(s) - v_2(s) \right| + \left| s_3(s) - v_3(s) \right| \right| ds
+ \left| s_1(h(s)) - v_1(h(s)) \right| + \left| s_2(h(s)) - v_2(h(s)) \right| + \left| s_3(h(s)) - v_3(h(s)) \right| \| ds
\leq \frac{2L_i}{\mu} \frac{\psi(b) - \psi(0))^{\kappa}}{\Gamma(\kappa_i + 1)} \left[ \| s_1 - v_1 \|_E + \| s_2 - v_2 \|_E + \| s_3 - v_3 \|_E \right]
= \frac{2L_i}{\mu} \frac{\psi(b) - \psi(0))^{\kappa}}{\Gamma(\kappa_i + 1)} \| (s_1, s_2, s_3) - (v_1, v_2, v_3) \|_E.
\]

It follows that
\[
\| \mathcal{G}(s_1, s_2, s_3) - \mathcal{G}(v_1, v_2, v_3) \|_E
= \sum_{i=1}^{3} \| \mathcal{G}_i(s_1, s_2, s_3) - \mathcal{G}_i(v_1, v_2, v_3) \|_E
\]
Now, by Lemma 2.11, for all \( x \in [-r, b] \), we get
\[
\|G(\xi_1, \xi_2, \ldots, \xi_n) - G(v_1, v_2, \ldots, v_n)\|_{E^*} \leq \Upsilon \| (\xi_1, \xi_2, \xi_3) - (v_1, v_2, v_3) \|_{E^*}.
\]
Thus, the operator \( G(\xi_1, \xi_2, \xi_3) \) is a contraction mapping on \( \Xi \) with respect to the norm
\[
\| (\xi_1, \xi_2, \xi_3) \|_{E^*} = \| \xi_1 \|_E + \| \xi_2 \|_E + \| \xi_3 \|_E.
\]
So, by the above steps and the Banach fixed point theorem, we deduce that system (1.1) has a unique solution in \( \Xi \).

**Theorem 3.2** Assume that (H1) and (H2) are satisfied. If
\[
\Upsilon = \sum_{i=1}^{3} \frac{2L_i (\varphi(b) - \varphi(0))^{r_i}}{\mu \Gamma(k_i + 1)} < 1,
\]
and \( M = \frac{\lambda}{p_x} > 0 \), where \( \lambda = 1 - \sum_{i=1}^{3} \frac{2L_i (\varphi(b) - \varphi(0))^{r_i}}{\mu \Gamma(k_i + 1)} \not= 0 \), then
\[
C_w \mathcal{D}^{q_i}_{0^+} \zeta(x) = f_i\left(x, \zeta(x), \zeta(h(x))\right), \quad x \in (0, b], \quad i = 1, 2, 3,
\]
is UHML stable.

**Proof** Let \( \tilde{\zeta} = (\tilde{\xi}_1, \tilde{\xi}_2, \tilde{\xi}_3) \in \Xi \) be a sequence satisfying inequality (2.3) and \( \zeta = (\xi_1, \xi_2, \xi_3) \in \Xi \) be a unique solution to the following (TSWFDEs)
\[
C_w \mathcal{D}^{q_i}_{0^+} \zeta(x) = f_i\left(x, \zeta(x), \zeta(h(x))\right), \quad x \in (0, b],
\]
\[
\zeta(x) = \tilde{\zeta}(x), \quad x \in [-r, 0].
\]
Now, by Lemma 2.11, for \( i = 1, 2, 3 \), we have
\[
\zeta(x) = \begin{cases} 
\frac{w(0)}{w(x)} d_i + \frac{w^{-1}(x)}{\mu \Gamma(k_i)} \int_0^x w(s) \mathcal{N}^{r_i-1}_\psi(x,s)f_i(s, \zeta(s), \zeta(h(s))) \, ds, & x \in (0, b], \\
\tilde{\zeta}(x), & x \in [-r, 0].
\end{cases}
\]
First, for all \( x \in [-r, 0] \), we have \( |\tilde{\zeta}(x) - \zeta(x)| = 0 \). Next, from (H2) and Lemma 2.12, for each \( x \in (0, b] \), we have
\[
\begin{align*}
|\tilde{\zeta}(x) - \zeta(x)| &
\leq \left| \frac{w(0)}{w(x)} d_i - \frac{w^{-1}(x)}{\mu \Gamma(k_i)} \int_0^x w(s) \mathcal{N}^{r_i-1}_\psi(x,s)f_i(s, \zeta(s), \zeta(h(s))) \, ds \right| \\
&\quad + \left| \frac{w^{-1}(x)}{\mu \Gamma(k_i)} \int_0^x w(s) \mathcal{N}^{r_i-1}_\psi(x,s)f_i(s, \tilde{\zeta}(s), \tilde{\zeta}(h(s))) \, ds \right|
\end{align*}
\]
We prove that 

\[ \set{\varOmega_1} \hat{y}_1, + \] we consider the operator 

\[ \ast \int_{\varOmega_1} \|U\| = \int_{\varOmega_1} \|U\| \left[ \left| \tilde{\varphi}_1(s) - \varphi_1(s) \right| + \left| \tilde{\varphi}_2(s) - \varphi_2(s) \right| + \left| \tilde{\varphi}_3(s) - \varphi_3(s) \right| \right] ds. \] (3.3)

Set \( \varOmega_* : = C([-r, b], \mathbb{R}^+) \) and \( \varOmega_*^* = \varOmega_* \times \varOmega_* \times \varOmega_* \). Now, for each sequence \( \gamma = (y_1, y_2, y_3) \in \varOmega_*^* \), we consider the operator \( \mathcal{U} : \varOmega_*^* \to \varOmega_* \), defined by

\[ \mathcal{U}(y_1, y_2, y_3) = \left( \mathcal{U}_1(y_1, y_2, y_3)(x), \mathcal{U}_2(y_1, y_2, y_3)(x), \mathcal{U}_3(y_1, y_2, \ldots, y_6)(x) \right), \]

where \( \mathcal{U}_i(y_1, y_2, y_3)(x), i = 1, 2, 3 \), given as

\[
\mathcal{U}_i(y_1, y_2, y_3)(x) = \begin{cases} 
\frac{E_i(x)}{\mu} \mathcal{E}_1(y_1(x) - y_1(0)) + \frac{E_i(x)}{\mu} \mathcal{E}_1(y_1(x)) y_1(s) ds \\
+ \frac{E_i(x)}{\mu} \mathcal{E}_1(y_2(x)) y_2(s) ds + \frac{E_i(x)}{\mu} \mathcal{E}_1(y_3(x)) y_3(s) ds \\
+ \frac{E_i(x)}{\mu} \mathcal{E}_1(y_1(x)) y_1(h(s)) ds + \frac{E_i(x)}{\mu} \mathcal{E}_1(y_2(x)) y_2(h(s)) ds \\
+ \frac{E_i(x)}{\mu} \mathcal{E}_1(y_3(x)) y_3(h(s)) ds & x \in (0, b], \\
0, & x \in [-r, 0].
\end{cases}
\]

We prove that \( \mathcal{U}(y_1, y_2, y_3) \) is a Picard operator. For \( i = 1, 2, 3 \), \( x \in (0, b] \) and \( (y_1, y_2, y_3), (\tilde{y}_1, \tilde{y}_2, \tilde{y}_3) \in \varOmega_*^* \), we have

\[
\left\| \mathcal{U}_i(y_1, y_2, y_3) - \mathcal{U}_i(\tilde{y}_1, \tilde{y}_2, \tilde{y}_3) \right\|_E \leq \frac{2E_i(x)}{\mu \Gamma(k_i)} \left[ \|y_1 - \tilde{y}_1\|_E + \|y_2 - \tilde{y}_2\|_E + \|y_3 - \tilde{y}_3\|_E \right].
\]
\[
\frac{2L_i(\psi(b) - \psi(0))^\kappa}{\mu \Gamma(\kappa_i + 1)} \| (y_1, y_2, y_3) - (\hat{y}_1, \hat{y}_2, \hat{y}_3) \|_{E^*},
\]
which implies
\[
\left\| u(y_1, y_2, y_3) - u(\hat{y}_1, \hat{y}_2, \hat{y}_3) \right\|_{E^*} = \sum_{i=1}^{3} \left\| u(y_1, y_2, y_3) - u(\hat{y}_1, \hat{y}_2, \hat{y}_3) \right\|_{E^*} \leq 3 \frac{2L_i(\psi(b) - \psi(0))^\kappa}{\mu \Gamma(\kappa_i + 1)} \| (y_1, y_2, y_3) - (\hat{y}_1, \hat{y}_2, \hat{y}_3) \|_{E^*} \leq \Upsilon \| (y_1, y_2, y_3) - (\hat{y}_1, \hat{y}_2, \hat{y}_3) \|_{E^*}.
\]

Since \( \Upsilon < 1 \), we conclude that the operator \( u \) is a contraction mapping on \( \Xi \) with respect to the norm
\[
\left\| (\xi_1, \xi_2, \xi_3) \right\|_{E^*} = \sum_{i=1}^{3} \| \xi_i \|_{E}.
\]

According to the Banach fixed point theorem, we deduce that \( u(y_1, y_2, y_3) \) is a Picard operator and \( \Gamma u = (\gamma_1, \gamma_2, \gamma_3) \). Now, for all \( \alpha \in (0, b] \), we have
\[
\gamma_1^\alpha(\alpha) = u_1(\gamma_1^\alpha, \gamma_2^\alpha, \gamma_3^\alpha)(\alpha),
\]
\[
\gamma_2^\alpha(\alpha) = u_2(\gamma_1^\alpha, \gamma_2^\alpha, \gamma_3^\alpha)(\alpha),
\]
and
\[
\gamma_3^\alpha(\alpha) = u_3(\gamma_1^\alpha, \gamma_2^\alpha, \gamma_3^\alpha)(\alpha).
\]

For \( i = 1, 2, 3 \), we get
\[
\gamma_i^\alpha(\alpha) = u_i(\gamma_1^\alpha, \gamma_2^\alpha, \gamma_3^\alpha)(\alpha) = \frac{\epsilon_i}{\mu} E_{\alpha_i}(\psi(\alpha) - \psi(0))^\kappa_i + \frac{L_i w^{-1}(\alpha)}{\Gamma(\kappa_i)} \int_0^{\alpha} N_\psi^{-1}(\alpha, s)[\gamma_1^\alpha(s) + \gamma_2^\alpha(h(s))] ds + \frac{L_i w^{-1}(\alpha)}{\Gamma(\kappa_i)} \int_0^{\alpha} N_\psi^{-1}(\alpha, s)[\gamma_2^\alpha(s) + \gamma_3^\alpha(h(s))] ds + \frac{L_i w^{-1}(\alpha)}{\Gamma(\kappa_i)} \int_0^{\alpha} N_\psi^{-1}(\alpha, s)[\gamma_3^\alpha(s) + \gamma_3^\alpha(h(s))] ds.
\]

Next, we prove that the solution \( (\gamma_1^\alpha, \gamma_2^\alpha, \gamma_3^\alpha) \) is increasing. Let \( \sigma = \max\{\sigma_1, \sigma_2, \sigma_3\} \), where \( \sigma_i = \min_{\alpha \in (0, b]} [\gamma_i^\alpha(s) + \gamma_i^\alpha(h(s))] \in \mathbb{R}^+ \), \( i = 1, 2, 3 \), then for all \( 0 \leq \alpha_1 < \alpha_2 \leq b \), we have
\[
\gamma_i^\alpha(\alpha_2) - \gamma_i^\alpha(\alpha_1) = \frac{\epsilon_i}{\mu} \left[ E_{\alpha_1}(\psi(\alpha_2) - \psi(0))^\kappa_i - E_{\alpha_1}(\psi(\alpha_1) - \psi(0))^\kappa_i \right]
\]
we obtain

\[ y_t^i \leq y_t^i + \varepsilon \]

In particular, if \( y_i = |\tilde{z}_i(x) - z_i(x)| \), (i = 1, 2, 3), from (3.3), \( y_i \leq \mathcal{U}(y_t^1, y_t^2, y_t^3) \) by Lemma 2.8, we obtain \( y_i \leq y_t^i \), where \( \mathcal{U} \) is an increasing Picard operator. As a result, we get

\[ |\tilde{z}_i(x) - z_i(x)| \leq \frac{E_i}{\mu} \mathcal{U}(\varphi(x) - \varphi(0))^\varepsilon \]

+ \( \frac{2L_i}{\mu \Gamma(k_i)} \int_0^\infty N_{\psi}^{\alpha-1}(s, y_t^i(s)) ds \)

+ \( \frac{2L_i}{\mu \Gamma(k_i)} \int_0^\infty N_{\psi}^{\alpha-1}(s, y_t^i(s)) ds \)

+ \( \frac{2L_i}{\mu \Gamma(k_i)} \int_0^\infty N_{\psi}^{\alpha-1}(s, y_t^i(s)) ds \).

Therefore \( y_t^i \) is increasing for all \( i = 1, 2, 3 \), and consequently \( (y_t^1, y_t^2, y_t^3) \) is increasing too.

Due to \( h(x) \leq \infty \), we get \( y_t^i(b(x)) \leq y_t^i(x) \) and hence

\[ y_t^i(x) = \mathcal{U}(y_t^1, y_t^2, \ldots, y_t^n)(x) \]

\[ \leq \frac{E_i}{\mu} E_i (\varphi(x) - \varphi(0))^\varepsilon \]

+ \( \frac{2L_i}{\mu \Gamma(k_i)} \int_0^\infty N_{\psi}^{\alpha-1}(s, y_t^i(s)) ds \)

+ \( \frac{2L_i}{\mu \Gamma(k_i)} \int_0^\infty N_{\psi}^{\alpha-1}(s, y_t^i(s)) ds \)

+ \( \frac{2L_i}{\mu \Gamma(k_i)} \int_0^\infty N_{\psi}^{\alpha-1}(s, y_t^i(s)) ds \).

In particular, if \( y_i = |\tilde{z}_i(x) - z_i(x)| \), (i = 1, 2, 3), from (3.3), \( y_i \leq \mathcal{U}(y_t^1, y_t^2, y_t^3) \) by Lemma 2.8, we obtain \( y_i \leq y_t^i \), where \( \mathcal{U} \) is an increasing Picard operator. As a result, we get

\[ |\tilde{z}_i(x) - z_i(x)| \leq \frac{E_i}{\mu} \mathcal{U}(\varphi(x) - \varphi(0))^\varepsilon \]

+ \( \frac{2L_i}{\mu \Gamma(k_i)} \int_0^\infty N_{\psi}^{\alpha-1}(s, y_t^i(s)) |\tilde{z}_1(x) - z_1(x)| ds \)

+ \( \frac{2L_i}{\mu \Gamma(k_i)} \int_0^\infty N_{\psi}^{\alpha-1}(s, y_t^i(s)) |\tilde{z}_2(x) - z_2(x)| ds \)

+ \( \frac{2L_i}{\mu \Gamma(k_i)} \int_0^\infty N_{\psi}^{\alpha-1}(s, y_t^i(s)) |\tilde{z}_3(x) - z_3(x)| ds \).
It follows that
\[
\| \tilde{\zeta}_1 - \zeta_i \|_E \leq \varepsilon_i E_{\kappa_i} (\varphi(x) - \varphi(0))^{\kappa_i} \times
\frac{2L_i(\varphi(b) - \varphi(0))^{\kappa_i}}{\mu \Gamma(\kappa_i + 1)} \left[ \| \tilde{\zeta}_1 - \zeta_1 \|_E + \| \tilde{\zeta}_2 - \zeta_2 \|_E + \| \tilde{\zeta}_3 - \zeta_3 \|_E \right]
\]
\[
= \frac{\varepsilon_i E_{\kappa_i}}{\mu} (\varphi(x) - \varphi(0))^{\kappa_i} + \frac{2L_i(\varphi(b) - \varphi(0))^{\kappa_i}}{\mu \Gamma(\kappa_i + 1)} \| (\tilde{\zeta}_1, \tilde{\zeta}_2, \tilde{\zeta}_3) - (\zeta_1, \zeta_2, \zeta_3) \|_{E^*}.
\]
Thus
\[
\| (\tilde{\zeta}_1, \tilde{\zeta}_2, \tilde{\zeta}_3) - (\zeta_1, \zeta_2, \zeta_3) \|_{E^*} \leq \frac{3}{\mu} \varepsilon_i E_{\kappa_i} (\varphi(x) - \varphi(0))^{\kappa_i} + \frac{2L_i(\varphi(b) - \varphi(0))^{\kappa_i}}{\mu \Gamma(\kappa_i + 1)} \| (\tilde{\zeta}_1, \tilde{\zeta}_2, \tilde{\zeta}_3) - (\zeta_1, \zeta_2, \zeta_3) \|_{E^*}.
\]
As a result, we get
\[
\| (\tilde{\zeta}_1, \tilde{\zeta}_2, \tilde{\zeta}_3) - (\zeta_1, \zeta_2, \zeta_3) \|_{E^*} \leq \frac{3}{\mu} \varepsilon_i E_{\kappa_i} (\varphi(x) - \varphi(0))^{\kappa_i}.
\]
Hence, equation (3.2) is UHML stable.

Next, we use the Bielecki norm \( \| \cdot \|_B \). Let \( B_i = E = C([-r, b], \mathbb{R}) \) be the Banach spaces of continuous functions \( \zeta_i : [-r, b] \to \mathbb{R} \) with the norms

\[
\| \zeta_i \|_{B_i} = \max_{x \in [0,b]} e^{-|x|} \varphi(x) \left| \zeta_i(x) \right|, \quad \delta > 0, i = 1, 2, 3,
\]

where

\[
B_i = \{ \zeta_i : (0, b] \to \mathbb{R}; e^{-|x|} \varphi(x) \left| \zeta_i(x) \right| \in C([-r, b], \mathbb{R}) \}.
\]

Define the product space \( B = B_1 \times B_2 \times B_3 \). Clearly, \( B \) is a Banach space with the following Bielecki norm:

\[
\| (\zeta_1, \zeta_2, \zeta_3) \|_B = \sum_{i=1}^{B} \| \zeta_i \|_{B_i}, \quad (\zeta_1, \zeta_2, \zeta_3) \in B.
\]

**Theorem 3.3** Assume that (H1) and (H2) are satisfied. If

\[
\Upsilon_1 = \sum_{i=1}^{3} \frac{2L_i e^{\delta [\varphi(b) - \varphi(0)]'}}{\mu} \left( \varphi(b) - \varphi(0) \right)^{\kappa_i} \Gamma(\kappa_i + 1) < 1,
\]

then system (1.1) has a unique solution \( (\zeta_1, \zeta_2, \zeta_3) \in E \times \Omega \times E \times \Omega \times E \times \Omega \).
Proof. In order to prove the uniqueness of solution, by means of the Banach fixed point theorem, we only prove that the operator $G(\xi_1, \xi_2, \xi_3)$ defined by (2.5) has a fixed point in $\mathfrak{I}$ with respect to Bielecki's norm. For this purpose, we divided the proof into the following steps.

Step (1): $G(\xi_1, \xi_2, \xi_3)$ is continuous.

The continuity of a function $f_i$ implies that the operator $G(\xi_1, \xi_2, \xi_3)$ is continuous too.

Step (2): Define $P_{\xi^*}^*$ is a bounded, closed, and convex set as $P_{\xi^*}^* = \{(\xi_1, \xi_2, \xi_3) \in B : \|G(\xi_1, \xi_2, \xi_3)\|_B \leq \xi^*\}$ with

$$\xi^* \geq \frac{\Lambda_1}{1 - \Gamma_1}$$

where $\Lambda_1 := \sum_{i=1}^{3} \left[ \frac{|w(0)|}{\mu} a_i + \frac{2L_i e^{\xi|\mu(b-\mu\xi)|}}{\mu} \frac{f_i (\rho(\xi) - \phi(0))^{\xi_i}}{\Gamma(\xi_i + 1)} \right]$, where $\rho_i = \sup_{x \in [0, b]} |w_i(s, 0, 0)|$ and $\mu = \max_{x \in [0, b]} |w(x)|$.

Case (1). For each $(\xi_1, \xi_2, \xi_3) \in P_{\xi^*}^*$, $i = 1, 2, 3$, and for $x \in [-r, 0]$, we have

$$\|G(\xi_1, \xi_2, \xi_3)\|_B = \|\theta_i\|_{B_i}.$$ 

Hence

$$\|G(\xi_1, \xi_2, \xi_3)\|_B \leq \|\theta_1\|_{B_1} + \|\theta_2\|_{B_2} + \|\theta_3\|_{B_3} \leq \|\theta_1, \theta_2, \theta_3\|_B \leq \xi^*.$$ 

Case (2). For each $(\xi_1, \xi_2, \xi_3) \in P_{\xi^*}^*$, $i = 1, 2, 3$, and for $x \in [0, b]$, we have

$$\left|G_i(\xi_1, \xi_2, \xi_3)\right| \leq \left|\frac{w(0)}{w(\xi)}\right| a_i + \frac{w^{-1}(\xi)}{\Gamma(\xi_i)} \int_0^\infty w(s) N_{\nu_i}^{-1}(\xi, s) \left|f_i(s, \xi(s), \xi(b(s))) - f_i(s, 0, 0) + f_i(s, 0, 0)\right| ds$$

$$\leq \left|\frac{w(0)}{w(\xi)}\right| a_i + \frac{w^{-1}(\xi)}{\Gamma(\xi_i)} \int_0^\infty N_{\nu_i}^{-1}(\xi, s) e^{\xi|\mu(b-\mu\xi)|} ds$$

$$\leq \left|\frac{w(0)}{\mu}\right| a_i + \frac{2L_i}{\mu \Gamma(\xi_i)} \left\{ \|\xi_1\|_{B_1} + \|\xi_2\|_{B_2} + \|\xi_3\|_{B_3} \right\} + \frac{\rho_i}{\Gamma(\xi_i + 1)}$$

$$\leq \left|\frac{w(0)}{\mu}\right| a_i + \frac{2L_i e^{\xi|\mu(b-\mu\xi)|}}{\mu \Gamma(\xi_i)} \left\{ \|\xi_1, \xi_2, \xi_3\|_B + \frac{\rho_i}{\Gamma(\xi_i + 1)} \right\} \left(\phi(b) - \phi(0)\right)^{\xi_i}$$

$$\leq \left|\frac{w(0)}{\mu}\right| a_i + \frac{2L_i e^{\xi|\mu(b-\mu\xi)|}}{\mu} \left\{ \|\xi_1, \xi_2, \xi_3\|_B + \frac{\rho_i}{\Gamma(\xi_i + 1)} \right\} \left(\phi(b) - \phi(0)\right)^{\xi_i}$$

$$\leq \left|\frac{w(0)}{\mu}\right| a_i + \frac{2L_i e^{\xi|\mu(b-\mu\xi)|}}{\mu} \left\{ \|\xi_1, \xi_2, \xi_3\|_B + \frac{\rho_i}{\Gamma(\xi_i + 1)} \right\} \left(\phi(b) - \phi(0)\right)^{\xi_i}$$

$$+ \frac{2L_i e^{\xi|\mu(b-\mu\xi)|}}{\mu} \left(\phi(b) - \phi(0)\right)^{\xi_i} \zeta^*,$$
which implies
\[
\| G(\xi_1, \xi_2, \xi_3) \|_B = \sum_{i=1}^{3} \| G_i(\xi_1, \xi_2, \xi_3) \|_{B_i} \\
\leq \sum_{i=1}^{3} \left[ \frac{|w(0)|}{\mu} a_i + \frac{2L_i e^{\delta(|\psi(b) - \psi(0)|)}}{\mu} \int_{0}^{1} \frac{(\psi(b) - \psi(0))^{\nu_i}}{\Gamma(\nu_i + 1)} \right] \\
+ \sum_{i=1}^{3} \frac{2L_i e^{\delta(|\psi(b) - \psi(0)|)}}{\mu} \frac{(\psi(b) - \psi(0))^{\nu_i}}{\Gamma(\nu_i + 1)} \xi^* \\
< \Lambda_1 + \xi^* \gamma_1 \leq \xi^*.
\]

This proves that \( G(\xi_1, \xi_2, \xi_3) \in \mathbb{F}_1 \).

**Step (3):** \( G(\xi_1, \xi_2, \xi_3) \) is a contraction.

In this step, we need only to prove that the operator \( G(\xi_1, \xi_2, \xi_3) \) is a contraction mapping on \( \Xi \) with respect to the Bielecki norm \( B \).

Case (1): For \((\xi_1, \xi_2, \xi_3), (v_1, v_2, v_3) \in B \) and \( \epsilon \in [-r, 0], \) \( i = 1, 2, 3, \) we have
\[
\| G_i(\xi_1, \xi_2, \xi_3) - G_i(v_1, v_2, v_3) \|_{B_i} = 0.
\]

It follows that
\[
\| G(\xi_1, \xi_2, \xi_3) - G(v_1, v_2, v_3) \|_B \\
= \sum_{i=1}^{n} \| G_i(\xi_1, \xi_2, \xi_3) - G_i(v_1, v_2, v_3) \|_{B_i} \\
< \gamma_1 \| (\xi_1, \xi_2, \xi_3) - (v_1, v_2, v_3) \|_B.
\]

Case (2): For \((\xi_1, \xi_2, \xi_3), (v_1, v_2, v_3) \in B, \) \( \epsilon \in (0, b] \) and by (H2), we obtain
\[
\| G_i(\xi_1, \xi_2, \xi_3) - G_i(v_1, v_2, v_3) \|_{B_i} \\
\leq \frac{w^{-1}(\epsilon)}{\Gamma(\nu_i)} \int_{0}^{\infty} \| w(s)N_{\epsilon}^{\nu_i-1}(\epsilon, s) \| \| f_i(s, \xi(s), v\psi(h(s))) - f_i(s, v, v\psi(h(s))) \| ds \\
\leq \frac{w^{-1}(\epsilon)}{\Gamma(\nu_i)} \int_{0}^{\infty} N_{\epsilon}^{\nu_i-1}(\epsilon, s) \| w(s) \| \| f_i(s, \xi(s), v\psi(h(s))) - f_i(s, v, v\psi(h(s))) \| ds \\
\leq \frac{L_i}{\mu} \int_{0}^{\infty} N_{\epsilon}^{\nu_i-1}(\epsilon, s) e^{\delta(\psi(\epsilon) - \psi(0))} \\
\times e^{-\delta(\psi(\epsilon) - \psi(0))} \left[ |\xi_1(s) - v_1(s)| + |\xi_2(s) - v_2(s)| + |\xi_3(s) - v_3(s)| \\
+ |\xi_1(h(s)) - v_1(h(s))| + |\xi_2(h(s)) - v_2(h(s))| + |\xi_3(h(s)) - v_3(h(s))| \right] ds \\
\leq \frac{2L_i e^{\delta(\psi(b) - \psi(0)) \mu}}{\Gamma(\nu_i + 1)} \left[ \| \xi_1 - v_1 \|_{B_i} + \| \xi_2 - v_2 \|_{B_i} + \| \xi_3 - v_3 \|_{B_i} \right] \\
= \frac{2L_i e^{\delta(\psi(b) - \psi(0)) \mu}}{\Gamma(\nu_i + 1)} \| (\xi_1, \xi_2, \xi_3) - (v_1, v_2, v_3) \|_B.
\]
It follows that
\[
\|G(\xi_1, \xi_2, \ldots, \xi_n) - G(\nu_1, \nu_2, \ldots, \nu_n)\|_B
= \sum_{i=1}^{3} \|G_i(\xi_1, \xi_2, \ldots, \xi_n) - G_i(\nu_1, \nu_2, \ldots, \nu_n)\|_{B_i}
\leq \sum_{i=1}^{3} \frac{2L_i e^{\beta(b)-\beta(0)}}{\mu} \left(\frac{\beta(b) - \beta(0)}{\Gamma(k_i + 1)}\right) \|G_i(\xi_1, \xi_2, \xi_3) - (\xi_1, \xi_2, \xi_3)\|_B
\leq \Upsilon_i \|G_i(\xi_1, \xi_2, \xi_3) - (\xi_1, \xi_2, \xi_3)\|_B.
\]

Thus, the operator $G(\xi_1, \xi_2, \xi_3)$ is a contraction mapping on $\Xi$ with respect to Bielecki’s norm. So, by the above steps and the Banach fixed point theorem, we deduce that system (1.1) has a unique solution in $\Xi$.

The proof of UHML stability is just like in Theorem 3.1, so we omit it here. □

4 An example

Example 4.1 - Consider the following WFDE:

\[
\begin{align*}
\frac{C^\alpha D^\beta_0 \psi}{\mu} \xi(\varepsilon) &= f(\varepsilon, \xi(\varepsilon), \xi(\beta(\varepsilon))), \quad \varepsilon \in (0, 1] \\
\xi(0) &= \alpha_i, \\
\xi(\varepsilon) &= \psi(\varepsilon), \quad \varepsilon \in [-1, 0].
\end{align*}
\]

Set $\kappa_i = \frac{1}{3}, f_i(\varepsilon, \xi(\varepsilon), \xi(\beta(\varepsilon))) = \sum_{i=1}^{n} [\psi_i(\varepsilon) - \psi_i(0) + \frac{\beta_i}{10} \cos(2\xi_i(\varepsilon + 1)) + \frac{\beta_i^2}{10\xi_i^2(\varepsilon + 1)}], w_i(\varepsilon) = e^{\kappa_i}, i = 1, 2, 3, \beta_i(\varepsilon) = (\varepsilon - 1).$ Thus, for all $\xi_i, \xi_i^* \in \mathbb{R}^+$ and $\varepsilon \in (0, 1]$, we have

\[
|w_i(\varepsilon)f_i(\varepsilon, \xi(\varepsilon), \xi(\beta(\varepsilon)))| - f_i(\varepsilon, \xi^*(\varepsilon), \xi^*(\beta(\varepsilon)))| \leq \frac{1}{10} |\xi(\varepsilon) - \xi^*(\varepsilon)| + \frac{1}{10} |\xi(\beta(\varepsilon)) - \xi^*(\beta(\varepsilon))|.
\]

Here $L_i = \frac{1}{10}$ for all $i = 1, 2, 3$. We select $\psi(\varepsilon) = e^{\kappa_i}$. Then we get $\mu = \max_{\varepsilon \in (0, 1]} |\psi(\varepsilon)| = e$, and hence $\Upsilon = \sum_{i=1}^{3} \frac{2L_i e^{\beta(b)-\beta(0)}}{\Gamma(k_i + 1)} \approx 0.5$. Thus all conditions in Theorem 3.1 are satisfied, and hence system (4.1) has a unique solution. Finally, we see that the inequality

\[
|\frac{C^\alpha D^\beta_0 \psi}{\mu} \xi(\varepsilon) - f_i(\varepsilon, \xi, \beta(\varepsilon))| \leq \varepsilon \varepsilon E_\varepsilon(\psi(\varepsilon) - \psi(0))^{\kappa_i}
\]

is satisfied. Then equation (3.2) is UHML stable with

\[
\|G(\xi_1, \xi_2, \xi_3) - G(\xi_1, \xi_2, \xi_3)\|_B \leq M \varepsilon E_\varepsilon(\psi(\varepsilon) - \psi(0))^\kappa,
\]

where $M \simeq 2.2 > 0$.

5 Conclusion

We have obtained the existence of unique solutions and Ulam–Hyers–Mittag-Leffler stability results for the solution of a tripled system of weighted generalized Caputo fractional derivatives investigated by Jarad et al. [1] with respect to Chebyshev and Bielecki norms.
and time delay based on the reduction of fractional differential equations to integral equations. We employed the Picard operator method and fixed point theorems to obtain our results. To the best of our observation, there is no analytical literature on studying the existence of tripled systems of fractional differential equations. This paper is the first work to study existence of a unique solution and an Ulam–Hyers–Mittag-Leffler stability result for (TSWFDEs) with respect to Chebyshev and Bielecki norms with time delay. We trust the reported results here will have a positive impact on the event of further applications in engineering and applied sciences.

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