Multi-objective optimization of sandwich composite pressure hull for decreasing weight and drag force and increasing buckling load capacity

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Abstract:

In underwater applications, space vehicles, and aircrafts, the weight becomes an important factor. Additionally, the design of composites structures greatly depends on the number of layers and the fiber orientation angle. Therefore, this work presents the optimization of sandwich composite pressure hull in order to minimize (weight and drag force) and maximize the buckling load capacity using ANSYS Parametric Design Language (APDL). Tsai-Wu and maximum stress failure criteria were incorporated for predicting the first-ply failure. The major and minor radius of the pressure hull, the ring and long beams dimensions, the fiber orientation angle and layer thickness are taken as design variables. The results illustrated that, core thickness ($T_{core}$) has a great effect to resist the shell buckling. While, has a little effect on both Tsai-Wu and maximum stress failure index.

Keywords: Multi-objective optimization; Buckling; drag force; pressure hull; Tsai-Wu.
1. Introduction

The pressure hulls are one of the most main structures of the submarine which provide high load capacity for electronic systems and buoyancy [1]. The optimization and buckling behavior have been attracted some recent attention [1-17]. Additionally, Zhang et al. [18], investigated the egg-shaped pressure hulls to improve the low buckling resistance, the difficult interior arrangement and the poor hydrodynamics of the spherical pressure hull. Vosoughi et al. [19], investigated the optimum stacking sequences of laminated composite plate to maximize the buckling load by achieving the optimum fibers orientations. Significant research work had been presented so far in this field. Among them, Mian et al. [20], presented the design optimization procedure for a composite pressure vessel, considering both maximum stress and Tsai-Wu failure criteria. Pan et al. [21], studied the optimization of composite cylinder due to hydrostatic pressure. The ply orientation and thickness are studied. Furthermore, Fathallah and Helal [22], optimized deep cross elliptical pressure hull taking into consideration both buckling and failure criteria. Imran et al. [23], optimized a composite pressure hull to minimize the buoyancy factor. Lund [24], Optimized a laminated composite structures using failure criteria. Moreover, Fathallah et al. [25], investigated the optimization of elliptical composite pressure hull for minimizing buoyancy factor. In this work, a sandwich composite pressure hull is proposed. The view of the model is shown in Fig. 1. The multi-objective optimization methodology for the pressure hull is presented. The optimization is established for maximizing the buckling load capacity and minimizing the drag force and (weight/displacement) ratio, of the pressure hull.
1.1 Buckling in multilayer-sandwich composite pressure hull

In this work, a scalar multiple $\lambda$ of the design load, the so-called buckling load strength factor, is introduced to identify pre-buckling of the multilayer sandwich submersible pressure hulls and defined as [1]:

$$\lambda = \frac{P_s}{P_{act}}$$  \hspace{1cm} (1)

Where: $P_{act}$ is the actual load and $P_s$ is the structural critical buckling strength. The buckling will occur when $\lambda < 1$ and $(P_s)$ less than $(P_{act})$. The critical value of the pressure $P_{cr}$ that will cause buckling is determined using the following equations [22, 26]:

$$P_{cr} = \frac{R}{n^2 + 0.5 \left( \frac{m \pi R}{L} \right)^2} \begin{bmatrix} C_{11} & C_{12} & C_{13} \\ C_{11} & C_{12} & C_{13} \\ C_{11} & C_{12} & C_{13} \end{bmatrix} \begin{bmatrix} C_{11} \\ C_{12} \\ C_{13} \end{bmatrix}$$ \hspace{1cm} (2)

Where: $L$, $R$, $m$ and $n$ are the length, the radius, the number of buckle half waves in the axial direction and the number of buckle waves in the circumferential direction, respectively. The coefficients $C$, $A$, $B$ and $D$ are defined as follows:
\[ C_{11} = A_{11} \left( \frac{m \pi}{L} \right)^2 + A_{66} \left( \frac{n}{R} \right)^2, \quad C_{22} = A_{22} \left( \frac{n}{R} \right)^2 + A_{66} \left( \frac{m \pi}{L} \right)^2 \]

\[ C_{33} = B_{11} \left( \frac{m \pi}{L} \right)^4 + (4D_{66} + 2D_{12}) \left( \frac{m \pi}{L} \right)^2 \left( \frac{n}{R} \right)^2 + D_{22} \left( \frac{n}{R} \right)^4 \]

\[ + \frac{A_{22}}{R^2} + 2 \frac{B_{22}}{R^2} \left( \frac{n}{R} \right)^2 + 2 \frac{B_{12}}{R^2} \left( \frac{m \pi}{L} \right)^2 \left( \frac{n}{R} \right)^2 C_{12} = C_{21} = \left( A_{12} + A_{66} \right) \left( \frac{m \pi}{L} \right) \left( \frac{n}{R} \right) \]

\[ C_{23} = C_{32} = \left( B_{12} + 2B_{66} \right) \left( \frac{m \pi}{L} \right)^2 \left( \frac{n}{R} \right) + A_{22} \left( \frac{n}{R} \right)^2 + B_{22} \left( \frac{m \pi}{L} \right)^2 \left( \frac{n}{R} \right)^2 \]

\[ C_{31} = C_{31} = A_{31} \left( \frac{m \pi}{L} \right)^3 + B_{11} \left( \frac{n}{R} \right)^3 + (B_{12} + 2B_{66}) \left( \frac{m \pi}{L} \right) \left( \frac{n}{R} \right)^2 \]

Where: \( A_{ij}, B_{ij} \) and \( D_{ij} \) are the stiffness components including extensional stiffness, coupling stiffness and bending stiffness coefficient matrix, respectively. The elements of the stiffness matrices are:

\[ A_{ij} = \sum_{k=1}^{n} (\bar{\Theta}_{ij})_k (Z_k - Z_{k-1}), \quad B_{ij} = \frac{1}{2} \sum_{k=1}^{n} (\bar{\Theta}_{ij})_k (Z_{i,k}^2 - Z_{i,k-1}^2) \]

\[ D_{ij} = \frac{1}{3} \sum_{k=1}^{n} (\bar{\Theta}_{ij})_k (Z_{k}^3 - Z_{k-1}^3) \]

Where: \( n \) is the number of different plies in the stacking sequence and \( Z_{i,k}, Z_{i,k-1} \) are the upper and lower \((Z)\) coordinate of the \( k \)th ply layer as shown in Fig. 2. \( \bar{\Theta}_{ij} \) are the elements of the transformed reduced stiffness matrix\([\bar{\Theta}]\) and are defined as in \([27]\): The optimization can be achieved to obtain the highest buckling strength factor. The number of plies can be varied as well as their orientation. Since the fiber orientation has no influence on the mass function.

\[ a) \quad A \text{ composite laminate subjected to forces and moments.} \quad b) \quad \text{Enlarged view of laminate cross-section} \]

\textbf{Fig. 2} Laminated composite shell and coordinate locations of plies in a laminate.

The successful design requires an efficient and safe use of materials. Therefore, theories are needed to develop and compare the state of the stresses and the strains in the material \([28]\). In
this study both Tsai-Wu and maximum stress failure criteria were incorporated for predicting the first-ply failure. and are defined as in [1]. The von Mises yielding criteria is employed here to assess the capability of the core materials to withstand the yielding failure.

1.2 Drag Estimation and power requirements

The proper hydro-dynamic design is necessary to achieve the effective performance of the submarine. An improper shape can cause excessive noise, drag and instability. Drag is the hydro-dynamic force exerted on the hull body in a direction opposite to its velocity. The propulsive power requirement is proportional to the drag and times the velocity divided by the propulsive efficiency. The drag is consist of two components, the form drag (function of the shape and frontal area) and friction drag (function of the speed and wetted surface area) [29]. For drag estimation, the following formula has been used [30]:

\[
D = \frac{1}{2} \rho V^2 C_v S
\]  

(5)

Where:
- \(D\) denote the submarine drag in Newton (N),
- \(\rho\) denote the density of the fluid in kg/m\(^3\),
- \(V\) denote the velocity in m/s,
- \(S\) denote the wetted surface area of the vehicle in m\(^2\) and
- \(C_v\) denote the coefficient of viscous resistance for the smooth hull. There are three methods used to compute the coefficient of viscous resistance \((C_v)\) namely; Virginia Tech, MIT and G&J method [31]. According to G&J method, the coefficient of the viscous resistance, \(C_v\), can be calculated as [32]:

\[
C_v = C_F \left[ 1 + 0.5 \left( \frac{d}{L} \right) + 3 \left( \frac{d}{L} \right)^3 \right]
\]  

(6)

In MIT method, \(C_v\) defined as:

\[
C_v = C_F \left[ 1 + 1.5 \left( \frac{d}{L} \right)^3 + 7 \left( \frac{d}{L} \right)^3 + 0.002(C_F - 0.6) \right]
\]  

(7)

Where: \(d\) denote the maximum body diameter in meters, \(L\) denote the total length in meters, \(C_F\) denote the bare hull skin friction drag coefficient and defined as a function of Reynolds number \((Re)\) as [33]:
\[ C_p = \frac{0.075}{(\log_{10} R_n - 2)^2} \]  \hspace{1cm} (8)

Where: \( C_p \) denote the prismatic coefficient and can be defined as:

\[ C_p = \frac{V_d}{\pi \left(\frac{d}{2}\right)^2 L} \]  \hspace{1cm} (9)

Where: \( V_d \) denote the displacement volume of the submarine in m³, \( R_n \) denote the Reynolds number and can be defined as:

\[ R_n = \frac{\rho V L}{\mu} \]  \hspace{1cm} (10)

Where: \( \rho \) is the density of the fluid in kg/m³, \( V \) is the velocity in m/s, \( L \) is the overall length of the submarine pressure hull in meters and \( \mu \) is the dynamic viscosity of the fluid in kg/(m.s). In this study, \((V_d, S)\) will be calculated using volume and surface measurement function in ANSYS.

2. Submarines pressure hulls materials and simulation

The model constructed from Boron/Epoxy B(4)/5505 composites with the lay-up composed of sixteen plies \((n = 16)\) having equal thicknesses \((t_i)\) and fiber orientation angle \((\alpha_i)\) and one core layer with thickness \((T_{core})\). Low density PVC foam is used for the core layer. The material properties and strength parameters of B(4)/5505 Boron/Epoxy and PVC foam are given in Table 1 [25, 34, 35]. Fig.3 illustrates the relationship between the collapse depth and buoyancy factor for a visual comparison of different structural materials. [36]. The sandwich structure is modeled using Shell 281 element. The Beam 189 element is used for ring and long beams [37, 38].

| Material     | Material and strength properties |
|--------------|----------------------------------|
| B(4)/5505 Boron/Epoxy | \( E_{11} = 204 \text{GPa}, E_{22} = 18.5 \text{GPa}, E_{33} = 18.5 \text{GPa}, G_{12} = 5.59 \text{GPa}, G_{13} = 5.59 \text{GPa}, v_{12} = 0.23, X_t = 1260 \text{MPa}, X_c = 2500 \text{MPa}, Y_t = 61 \text{MPa}, Y_c = 5.4 \text{MPa}, S = 67 \text{MPa}, \rho = 2000 \text{kg/m}^3 \) |
| H200         | \( E = 250 \text{MPa}, G = 73 \text{MPa}, v = 0.3, X_t = 7.1 \text{MPa}, X_c = 5.4 \text{MPa}, Y_t = 7.1 \text{MPa}, Y_c = 5.4 \text{MPa}, S = 3.5 \text{MPa}, \rho = 200 \text{kg/m}^3 \) |
The boundary conditions applied here as in [1, 41]. The pressure hull is loaded by external pressure ($P = \rho gh$). Where $\rho$ denotes the density of the sea water, $g$ is the acceleration due to the gravity and $h$, represents the operating depth. Two failure criteria, Tsai-Wu and maximum stress are used to evaluate the failure of the pressure hull [25]. Fig. 4 shows the final layer stacking for the global model.

3. Structural design optimization

Fig. 5 shows the flow chart of the multi-objective optimization procedure. The optimization design is described as:
Objective function: \( F(X) \): Minimize (weight/displacement ratio (B.F) and drag force \( (D_{Fr}) \)) and maximize (buckling capacity \( (\lambda) \)).

Design constraints:

\[
FS(i) \geq 1, \quad i = 1, 2, 3, \ldots, n
\]  
(11)

Where: \( FS \) represents the factor of safety and must be greater than one to avert the first-ply failure of the angle-ply laminated for each \( i^{th} \) layer and equals to the inverse of the failure index for both Tsai-Wu and maximum stress failure criteria and \( n \) is the number of layers.

\[
\frac{\sigma}{\sigma_y} - 1 \leq 0
\]  
(12)

Where: \( \sigma \) and \( \sigma_y \) are the actual stress and yielding strength in the core layer, respectively.

\[
H \leq H_{max}
\]  
(13)

Where: \( H \), and \( H_{max} \) represent the operating depth and the maximum operating depth, respectively.

Design variables:

The composite pressure hull diameters are taken as:

\[
D_i^L \leq D_i \leq D_i^U, \quad i = \text{min}, \text{max}
\]  
(14)

Where: \( D_i \), \( D_i^L \) and \( D_i^U \) are the \( i^{th} \) submersible pressure hull diameters and its upper and lower limits, respectively.
Fig. 5 Flow chart layout of multi-objective optimization procedures

For core thickness:

\[ T^L \leq T_{\text{core}} \leq T^U \]  \hspace{1cm} (15)

Where: \( T_{\text{core}}, T^L \) and \( T^U \) represent the core thickness of pressure hull, and its lower and upper
limits, respectively. For ply thicknesses:

\[ t^L_i \leq t_i \leq t^U_i, \quad i = 1, 2, 3, \ldots, n \]  

(16)

Where: \( t_i \), \( t^L \), \( t^U \) represent the \( i^{th} \) thickness for the lower and upper bounds of the individual ply thicknesses, respectively.

\[ \alpha^L_i \leq \alpha_i \leq \alpha^U_i, \quad i = 1, 2, 3, \ldots, n \]  

(17)

Where: \( \alpha_i \), \( \alpha^L \), \( \alpha^U \) represent the \( i^{th} \) orientation angle of each layer and their lower and upper limits, respectively.

4. Results and discussions

The results of Multi-objective optimization are summarized in Table 1. The drag force is equals to \( 2.19925 \times 10^{12} \) N, buckling strength factor \((\lambda)\) equals 118, at \((B.F)\) equals 0.47. The maximum magnitude of deflection value \((\delta_{\text{max}})\) equal to 2.18 mm. Fig. 6 illustrates the displacement distribution in \( X \), \( Y \) and \( Z \) directions for the model. The maximum displacement occurs at the centroids regions of the composite pressure hull and occurs in vertical direction with value equals to 2.14 mm. The optimum configuration of the sandwich composite pressure hull can overcome all structural failures until operating depth \((H)\) equals to 255 m.

| Table 2. Results of the optimal design of the sandwich composite deep pressure hull. |
|-----------------------------------------------|
| \( \text{FSTWSR}_1 \) | \( \text{FSTWSR}_2 \) | \( \text{FSTWSR}_3 \) | \( \text{FSTWSR}_4 \) | \( \text{FSTWSR}_5 \) | \( \text{FSTWSR}_6 \) | \( \text{FSTWSR}_7 \) | \( \text{FSTWSR}_8 \) |
| 1.59 | 1.63 | 1.60 | 1.64 | 1.61 | 1.65 | 1.62 | 1.65 |
| \( \text{FSTWSR}_{10} \) | \( \text{FSTWSR}_{11} \) | \( \text{FSTWSR}_{12} \) | \( \text{FSTWSR}_{13} \) | \( \text{FSTWSR}_{14} \) | \( \text{FSTWSR}_{15} \) | \( \text{FSTWSR}_{16} \) | \( \text{FSTWSR}_{17} \) |
| 1.73 | 1.72 | 1.70 | 1.69 | 1.67 | 1.66 | 1.65 | 1.64 |
| \( \text{FSMAXF}_1 \) | \( \text{FSMAXF}_2 \) | \( \text{FSMAXF}_3 \) | \( \text{FSMAXF}_4 \) | \( \text{FSMAXF}_5 \) | \( \text{FSMAXF}_6 \) | \( \text{FSMAXF}_7 \) | \( \text{FSMAXF}_8 \) |
| 1.76 | 1.78 | 1.77 | 1.79 | 1.78 | 1.80 | 1.78 | 1.81 |
| \( \text{FSMAXF}_{10} \) | \( \text{FSMAXF}_{11} \) | \( \text{FSMAXF}_{12} \) | \( \text{FSMAXF}_{13} \) | \( \text{FSMAXF}_{14} \) | \( \text{FSMAXF}_{15} \) | \( \text{FSMAXF}_{16} \) | \( \text{FSMAXF}_{17} \) |
| 1.88 | 1.86 | 1.84 | 1.82 | 1.80 | 1.79 | 1.77 | 1.75 |

Maximum deflection \((\delta_{\text{max}})\)

| \( \text{LAY9}_{\text{SMAX}} \) | \( \text{LAY9}_{\text{SMIN}} \) | \( \text{LAY9}_{\text{SYMAX}} \) | \( \text{LAY9}_{\text{SYMIN}} \) | \( D_{\text{max}} \) | \( D_{\text{min}} \) | \( t_1 \) |
|-----------------------------------------------|
| 158772(Pa) | -28654(Pa) | 219556.6(Pa) | -69869(Pa) | 2.0838(m) | 1.8842(m) | 1.59(mm) |

Buckling strength factor \((\lambda)\)

| \( L_{\text{pre}}(m) \) | \( T_{\text{cor}}(m) \) | \( \alpha \) | \( \text{Operating depth (H(m))} \) | \( \text{LAY9}_{\text{yvon}} \) | \( \text{Drag Force (N)} \) | \( \text{B.F} \) |
|-----------------------------------------------|
| 118 | 2.80 | 0.091 | 55° | 255.00 | 1636834.95 | 2.19925\times10^{12} | 0.47 |
Fig. 6 Displacement distribution (Ux, Uy, Uz and U_{magnitude}) in composite pressure hull.
Also, Table 2 illustrated that, material failure incorporating both Tsai-Wu and maximum stress failure criteria were considered together for predicting the first-ply failure. The minimum factor of safety ($F_{\text{TWSR}}$ and $F_{\text{MAXF}}$) are occurring in the lower face at ply-1 due to maximum tensile stresses and equal 1.59 and 1.76, respectively. At upper face, the minimum values of $F_{\text{TWSR}}$ and $F_{\text{MAXF}}$ are occurring at ply-17 due to maximum compressive stresses with value equal to 1.64 and 1.75, respectively. The optimized orientation fiber $\alpha$ equals to (55°) with $T_{\text{core}}$ of about 91
mm. Fig. 7 (a, b, c and d) shows the Tsai-Wu and maximum stress failure distribution at critical Plies (Ply-1 and pl-17). The maximum Tsai-Wu and maximum stress failure at ply-1 will be initiates first at the middle of the left and right sides of the composite pressure hull. For ply-17, the failure will be initiates first at the upper and lower regions of the composite pressure hull. Fig. 7 -e shows the von Mises stress distribution for core layer (Ply-9) and illustrated clearly that, the maximum von Mises stresses occurs at the regions between long and ring beams.

4.1 Effect of fiber orientation on design variables and design constraints

Fig. 8-(a and b) shows the effect of (α) on maximum deflection value (δ_{MAX}) and buckling strength factor (λ). It can be seen that, (δ_{MAX}) equals to 4.63 mm and occurs when α equals to 0°. As (α) increases the maximum deflection value decreases and reaches to the minimum value when α equals to 90° with value equals to 2.04 mm. Fig. 8-b shows the variations of buckling strength factor with fiber orientation α. It illustrates that, the minimum buckling strength factor value is equal to 16.5 and occurs when α equals to 0°. After that, as (α) increases (λ) increases and reaches to maximum value when α equals to 60° with value equals to 157.2. With increasing α, (λ) decreases again and reaches to 45 at α equals to 90°.

![Graph](image-url)  
**Fig. 8** The effect of fiber orientation (α) on the buckling strength factor and maximum deflection value (δ_{MAX}).
Fig. 9 presents the effect of ($\alpha$) on Tsai-Wu and maximum stress failure index for both upper and lower faces of the sandwich composite pressure hull. The maximum failure indices for Tsai-Wu and maximum stress failures occur when $\alpha$ equals to 10° at lower face with values equal to 1.7 and 1.29, respectively and the maximum occurs at (Ply-1) due to the high tensile stresses. With increasing $\alpha$, the maximum failure indices for Tsai-Wu and maximum stress decrease and reach to the minimum values when $\alpha$ equals to 55°. After that, the maximum failure indices increase until $\alpha$ equals to 70° with values equal to 0.76 and 0.69 for Tsai-Wu and maximum stress failures, respectively. The maximum failure indices for the lower face decrease until $\alpha$ equals to 90° and reach to the minimum with values equal to 0.55 and 0.52 for Tsai-Wu and maximum stress failures, respectively. For the upper face, the minimum values of Tsai-Wu and maximum stress failure are equal to 0.52 and 0.5, respectively.
4.2 Effect of core thickness ($T_{core}$) on design variables and design constraints

Fig. 10 illustrates the effect of core thickness ($T_{core}$) on buckling strength factor and maximum deflection value ($\delta_{MAX}$). The figure shows that, as $T_{core}$ increases the buckling strength factor increases and $\delta_{MAX}$ decreases. The results emphasize that, $T_{core}$ has great effect on buckling strength factor. Fig. 11 presents the effect of $T_{core}$ on maximum Tsai-Wu and maximum stress.
failure indices. It reveals that, increasing $T_{core}$, decreasing the failure index and the core thickness has moderate effect on both Tsai-Wu and maximum stress failure index.

![Fig. 12](Lpmb on Tsai-Wu and maximum stress failure index)

5. Conclusions

In this study the finite element simulation and optimization were presented for increasing the buckling load capacity, minimizing the drag force and the weight/displacement ratio using ANSYS (APDL). The following observations were made:

- The pattern of optimum points is presented which is used in fabricating and designing the composite pressure hull under hydrostatic pressures.
- At lower face sheet the failure will be initiate first at (ply-1), for upper face sheet the failure will be initiate at the upper most layer (ply-17).
- The core thickness is important to resist the shell buckling.
• The fiber orientation angle ($\alpha$) has a great effect on buckling strength factor, maximum deflection value, Tsai-Wu and maximum stress failure index of the sandwich composite pressure hull.

• The results suggest that, in the design of composite pressure hull, both buckling and material failure should be considered.

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