Post-Keplerian perturbations of the orbital time shift in binary pulsars: an analytical formulation with applications to the galactic center

Lorenzo Iorio

Ministero dell’Istruzione, dell’Università e della Ricerca (M.I.U.R.)-Istruzione, Viale Unità di Italia 68, 70125 Bari, BA, Italy

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Abstract We develop a general approach to analytically calculate the perturbations \( \Delta \delta \tau_p \) of the orbital component of the change \( \delta \tau_p \) of the times of arrival of the pulses emitted by a binary pulsar \( p \) induced by the post-Keplerian accelerations due to the mass quadrupole \( Q_2 \), and the post-Newtonian gravitoelectric (GE) and Lense–Thirring (LT) fields. We apply our results to the so-far still hypothetical scenario involving a pulsar orbiting the supermassive black hole in the galactic center at Sgr A*. We also evaluate the gravitomagnetic and quadrupolar Shapiro-like propagation delays \( \delta \tau_{\text{prop}} \). By assuming the orbit of the existing main sequence star S2 and a time span as long as its orbital period \( P_b \), we obtain \( |\Delta \delta \tau_p^{\text{GE}}| \lesssim 10^3 \) s, \( |\Delta \delta \tau_p^{\text{LT}}| \lesssim 0.6 \) s, \( |\Delta \delta \tau_p^{Q_2}| \lesssim 0.04 \) s. Faster (\( P_b = 5 \) years) and more eccentric (\( e = 0.97 \)) orbits would imply net shifts per revolution as large as \( |\Delta \delta \tau_p^{\text{GE}}| \lesssim 10^4 \) s, \( |\Delta \delta \tau_p^{\text{LT}}| \lesssim 400 \) s, \( |\Delta \delta \tau_p^{Q_2}| \lesssim 10^3 \) s, depending on the other orbital parameters and the initial epoch. For the propagation delays, we have \( |\delta \tau_{\text{prop}}^{\text{LT}}| \lesssim 0.02 \) s, \( |\delta \tau_{\text{prop}}^{Q_2}| \lesssim 1 \) \( \mu \)s. The results for the mass quadrupole and the Lense–Thirring field depend, among other things, on the spatial orientation of the spin axis of the Black Hole. The expected precision in pulsar timing in Sgr A* is of the order of 100 \( \mu \)s, or, perhaps, even 1–10 \( \mu \)s. Our method is, in principle, neither limited just to some particular orbital configuration nor to the dynamical effects considered in the present study.

1 Introduction

In a binary hosting at least one emitting pulsar\(^1\) \( p \), the time of arrivals \( \tau_p \) of the emitted radio pulses changes primarily because of the orbital motion about the common center of mass caused by the gravitational tug of the unseen companion \( c \), which can be, in principle, either a main sequence star or an astrophysical compact object like, e.g., another neutron star which does not emit or whose pulses are, for some reason, not detectable, a white dwarf or, perhaps, even a black hole [50]. Such a periodic variation \( \delta \tau_p (f) \) can be modeled as the ratio of the projection of the barycentric orbit \( r_p \) of the pulsar \( p \) onto the line of sight to the speed of light \( c \) [12,31]. By assuming a coordinate system centered in the binary’s center of mass whose reference \( z \)-axis points toward the observer along the line of sight in such a way that the reference \( x, y \) plane coincides with the plane of the sky, we have

\[
\delta \tau_p (f) = \frac{r_p \sin I \sin \theta}{c} = \frac{a_p (1 - e^2) \sin I \sin \theta}{c (1 + e \cos f)} = \frac{m_p \sin I \sin (\omega + f)}{m_{\text{tot}} c (1 + e \cos f)}.
\]

In obtaining Eq. (1), which is somewhat the analogous of the range in Earth–Moon or Earth-planets studies [12], we used the fact that, to the Keplerian level, the barycentric semimajor axis of the pulsar \( A \) is

\[
a_p \simeq \frac{m_c}{m_{\text{tot}}} a.
\]

In a purely Keplerian scenario, there is no net variation \( \langle \delta \tau_p \rangle \) over a full orbital cycle.

In this paper, we illustrate a relatively simple and straightforward approach to analytically calculate the impact that several post-Keplerian (pK) features of motion, both Newtonian (quadrupole) and post-Newtonian (1pN static and stationary fields), have on such a key observable. As such, we will analytically calculate the corresponding net time delays per revolution \( \langle \Delta \delta \tau_p \rangle \); the instantaneous shifts \( \Delta \delta \tau_p (f) \) will be considered as well in order to cope with systems exhibiting very long orbital periods with respect to the time spans usually adopted for data collection. Our strategy has gen-

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\(^1\)See, e.g., [28,49] and references therein.

\(^a\)e-mail: lorenzo.iorio@libero.it
eral validity since, in principle, it can be extended to a wide range of dynamical effects, irrespectively of their physical origin, which may include, e.g., modified models of gravity as well. Furthermore, it is applicable to systems whose constituents may have arbitrary masses and orientations of their spin axes, and orbital configurations. Thus, more realistic sensitivity analyses, aimed at both reinterpreting already performed studies and designing future targeted ones, could be conducted in view of a closer correspondence with which is actually measured. We will also take into account the Shapiro-like time delays due to the propagation of the electromagnetic waves emitted by the visible pulsar(s) throughout the spacetime deformed by axisymmetric departures from spherical symmetry of the deflecting bodies [11, 14, 15, 29, 30, 32, 50, 55].

Our results, which are not intended to replace dedicated, covariance-based real data analyses, being, instead, possible complementary companions, will be applied to the so far putative scenario involving emitting radiopulsars, not yet detected, orbiting the Supermassive Black Hole (SMBH) in the Galactic Center (GC) at Sgr A* [1, 17, 20, 27, 33, 39, 54]. Moreover, we will perform also quantitative sensitivity analyses on the measurability of frame-dragging and quadrupolar-induced time delays in such a hypothesized system. In principle, our results may be applicable even to anthropogenic binaries like, e.g., those contrived in past concept studies to perform tests of fundamental physics in space [37, 43], or continuously emitting transponders placed on the surface of some moons of larger astronomical bodies.

The paper is organized as follows. Section 2 details the calculational approach. The 1pN Schwarzschild-type gravitoelectric effects are calculated in Sect. 3, while Sect. 4 deals with the 1pN gravimagnetic ones. The impact of the quadrupole mass moment of the SMBH is treated in Sect. 5. Section 6 summarizes our findings.

## 2 Outline of the proposed method

If the motion of a binary is affected by some relatively small post-Keplerian (pK) acceleration $A$, either Newtonian or post-Newtonian (pN) in nature, its impact on the projection of the orbit onto the line of sight can be calculated perturbatively as follows. Casotto [10] analytically worked out the instantaneous changes of the radial, transverse and out-of-plane components, $r_\rho$, $r_\sigma$, $r_\nu$, of the position vector $r$, respectively, for the relative motion of a test particle about its primary: they are

$$\Delta r_\rho (f) = \frac{r (f)}{a} \Delta a (f) - a \cos f \Delta e (f) + a e \sin f \sqrt{1 - e^2} \Delta \mathcal{M} (f), \quad (3)$$

$$\Delta r_\sigma (f) = a \sin f \left[ 1 + \frac{r (f)}{p} \right] \Delta e (f) + r (f) \left[ \cos f \Delta \Omega (f) + \Delta \omega (f) \right]$$

$$+ \frac{a^2}{r (f)} \sqrt{1 - e^2} \Delta \mathcal{M} (f), \quad (4)$$

$$\Delta r_\nu (f) = \frac{1}{p} \left[ \sin \nu \Delta I (f) - \sin I \cos \nu \Delta \Omega (f) \right]. \quad (5)$$

In Eqs. (3)–(5), the instantaneous changes $\Delta a (f)$, $\Delta e (f)$, $\Delta I (f)$, $\Delta \Omega (f)$, $\Delta \omega (f)$ are to be calculated as

$$\Delta I (f) = \int f_0^f \frac{d \kappa}{dr} \frac{dr}{df} df', \quad \kappa = a, e, I, \Omega, \omega, \quad (6)$$

where the time derivatives $d\kappa /dr$ of the Keplerian orbital elements $\kappa$ are to be taken from the right-hand sides of the Gauss equations,

$$\frac{da}{dr} = \frac{2}{n_b \sqrt{1 - e^2}} \left[ e A_\rho \sin f + A_\sigma \left( \frac{p}{r} \right) \right], \quad (7)$$

$$\frac{de}{dr} = \sqrt{1 - e^2} \left\{ A_\rho \sin f + A_\sigma \left[ \cos f + \frac{1}{e} (1 - \frac{r}{a}) \right] \right\}, \quad (8)$$

$$\frac{dI}{dr} = \frac{1}{n_b a \sqrt{1 - e^2}} A_\nu \left( \frac{r}{a} \right) \cos u, \quad (9)$$

$$\frac{d\Omega}{dr} = \frac{1}{n_b a \sin I \sqrt{1 - e^2}} A_\nu \left( \frac{r}{a} \right) \sin u, \quad (10)$$

$$\frac{d\omega}{dr} = - \cos I \frac{d\Omega}{dr}$$

$$+ \sqrt{1 - e^2} \frac{1}{n_b a e} \left[- A_\rho \cos f + A_\sigma \left( 1 + \frac{r}{p} \right) \sin f \right], \quad (11)$$

evaluated onto the Keplerian ellipse

$$r = \frac{p}{1 + e \cos f} \quad (12)$$

and assumed as unperturbed reference trajectory; the same holds also for

$$\frac{dr}{df} = \frac{\sqrt{1 - e^2}}{n_b \left( 1 + e \cos f \right)^2}, \quad (13)$$

entering Eq. (6). The case of the mean anomaly $\mathcal{M}$ is more subtle and requires more care. Indeed, in the most general case encompassing the possibility that the mean motion $n_b$ is time-dependent because of some physical phenomena, it can be written as$^2$ [4, 8, 35]

$$\mathcal{M} (t) = \eta + \int_{t_0}^t n_b \left( t \right) dt'; \quad (14)$$

$^2$ The mean anomaly at epoch is denoted as $\eta$ by Milani et al. [35], $t_0$ by Brumberg [8], and $e$ by Bertotti et al. [4]. It is a “slow” variable in the sense that its time derivative vanishes in the limit $A \to 0$; cf. Eq. (15).
the Gauss equation for the variation of the mean anomaly at epoch is \[^{3}[4,8,35]\]
\[
\frac{\mathrm{d}\eta}{\mathrm{d}t} = -\frac{2}{n_b a} A_\rho \left( \frac{L}{a} \right) - \frac{(1 - e^2)}{n_b a e} \times \left[ -A_\rho \cos f + A_\sigma \left( 1 + \frac{r}{p} \right) \sin f \right].
\]

If \(n_b\) is constant, as in the Keplerian case, Eq. (14) reduces to the usual form,
\[
\mathcal{M}(t) = \eta + n_b (t - t_0).
\]

In general, when a disturbing acceleration is present, the semimajor axis \(a\) does vary according to Eq. (7); thus, also the mean motion \(n_b\) experiences a change\[^{4}\]
\[
n_b \to n_b + \Delta n_b(t),
\]

which can be calculated in terms of the true anomaly \(f\) as
\[
\Delta n_b(f) = \frac{\partial n_b}{\partial \Delta a} \Delta a(f) = -\frac{3}{2a} \int_{f_0}^{f} \frac{\mathrm{d}a}{\mathrm{d}f} \frac{\mathrm{d}f}{\mathrm{d}t} \; \mathrm{d}f',
\]
by means of Eqs. (7) and (13). Depending on the specific perturbation at hand, Eq. (18) does not generally vanish. Thus, the total change experienced by the mean anomaly \(\mathcal{M}\) due to the disturbing acceleration \(A\) can be obtained:
\[
\Delta \mathcal{M}(f) = \Delta \eta(f) + \int_{f_0}^{f} \Delta n_b \left( t' \right) \; \mathrm{d}t',
\]
where
\[
\Delta \eta(f) = \int_{f_0}^{f} \frac{\mathrm{d}\eta}{\mathrm{d}f} \frac{\mathrm{d}f}{\mathrm{d}t} \; \mathrm{d}f',
\]
\[
\int_{f_0}^{f} \Delta n_b \left( t' \right) \; \mathrm{d}t' = -\frac{3}{2} \int_{f_0}^{f} \Delta a \left( f' \right) \; \frac{\mathrm{d}t}{\mathrm{d}f} \; \mathrm{d}f'.
\]

In the literature, the contribution due to Eq. (21) has been often neglected. An alternative way to compute the perturbation of the mean anomaly with respect to Eq. (19) implies the use of the mean longitude \(\lambda\) and the longitude of pericenter \(\varpi\). It turns out that\[^{5}\]\[^{46}\]
\[
\Delta \mathcal{M}(f) = \Delta \epsilon(f) - \Delta \sigma(f) + \int_{f_0}^{f} \Delta n_b \left( t' \right) \; \mathrm{d}t',
\]
where the Gauss equations for the variation of \(\sigma, \epsilon\) are \[^{4,8,35,46}\]
\[
\frac{\mathrm{d}\sigma}{\mathrm{d}t} = 2 \sin^2 \left( \frac{f}{2} \right) \frac{\mathrm{d}\Omega}{\mathrm{d}t} + \sqrt{1 - e^2} \frac{\mathrm{d}a}{\mathrm{d}f} \frac{\mathrm{d}f}{\mathrm{d}t} \left[ -A_\rho \cos f + A_\sigma \left( 1 + \frac{r}{p} \right) \sin f \right].
\]
\[
\frac{\mathrm{d}\epsilon}{\mathrm{d}t} = \frac{e^2}{1 + \sqrt{1 - e^2}} \frac{\mathrm{d}\sigma}{\mathrm{d}t} + 2\sqrt{1 - e^2} \frac{\mathrm{d}\Omega}{\mathrm{d}t} - \frac{2}{n_b a} A_\rho \left( \frac{r}{a} \right).
\]

It must be remarked that, depending on the specific perturbing acceleration \(A\) under consideration, the calculation of Eq. (21) may turn out to be rather uncomfortable.

The instantaneous change experienced by the projection of the binary’s relative motion onto the line of sight can be extracted from Eqs. (3) to (5) by taking the \(z\) component \(\Delta \mathbf{r}_z\) of the vector
\[
\Delta \mathbf{r} = \Delta \mathbf{r}_\rho \hat{\rho} + \Delta \mathbf{r}_\varpi \hat{\varpi} + \Delta \mathbf{r}_\nu \hat{\nu},
\]
expressing the perturbation experienced by the binary’s relative position vector \(\mathbf{r}\). It is
\[
\Delta \mathbf{r}_z(f) \frac{(1 - e^2) \sin f \sin u}{1 + e \cos f} \Delta \mathcal{M}(f)
\]
\[
+ a \sin \left[ \frac{1 + e}{1 + e \cos f} \right] \left( \sin f \cos u - \cos f \sin u \right) \Delta \mathcal{M}(f)
\]
\[
+ a \left( 1 - e^2 \right) \frac{\cos I \sin u}{1 + e \cos f} \Delta \mathcal{M}(f)
\]
\[
+ \frac{a \sin I \left( e \cos \omega + \cos u \right)}{\sqrt{1 - e^2}} \Delta \mathcal{M}(f).
\]

It is possible to express the true anomaly as a function of time through the mean anomaly according to Brouwer and Clemence [7, p. 77]
\[
f(t) = \mathcal{M}(t) + 2 \sum_{s=1}^{s_{\text{max}}} \frac{1}{s} \sin \left( \frac{1}{s} \mathcal{M}(t) \right)
\]
\[
\times \left[ J_{s-1}(se) + \sum_{j=1}^{s_{\text{max}}} \left( 1 - \sqrt{1 - e^2} \right)^j \left( J_{s-j}(se) + J_{s+j}(se) \right) \right] \sin s \mathcal{M}(t),
\]
where \(J_k(se)\) is the Bessel function of the first kind of order \(k\) and \(s_{\text{max}}\). \(J_{s_{\text{max}}}(se)\) are some values of the summation indices \(s, j\) adequate for the desired accuracy level. Having at disposal such analytical time series yielding the time-dependent pattern of Eq. (26) allows one to easily study some key features of it such as, e.g., its extrema along with the corresponding epochs and the values of some unknown parameters which may enter the disturbing acceleration. The net change per orbit \(\langle \Delta \mathbf{r}_z \rangle\) can be obtained by calculating Eq. (26) with

\[^{3}\] It is connected with the Gauss equation for the variation of the time of passage at pericenter \(t_p\) by \( \mathrm{d}n_b/\mathrm{d}t = -n_b \mathrm{d}r_p/\mathrm{d}t \).

\[^{4}\] We neglect the case \(\mu(t)\).

\[^{5}\] The mean longitude at epoch is denoted as \(\epsilon\) by Milani et al. [35], Soffel [46], Brumberg [8] and Bertotti et al. [4]. It is better suited than \(\eta\) at small inclinations [4].
\[ f = f_0 + 2\pi, \text{and using Eq. (6) and Eqs. (19)–(21) integrated from } f_0 \text{ to } f_0 + 2\pi. \]

In order to have the change of the times of arrival of the pulses from the binary’s pulsar p, Eq. (26) and its orbit averaged expression have to be scaled by \( m_\text{p} m_\text{w} \) c\(^{-1}\).

In the following, we will look at three pK dynamical effects: the Newtonian deviation from spherical symmetry of the binary’s bodies due to their quadrupole mass moments, the velocity-dependent 1pN static (gravitoelectric) and stationary (gravitomagnetic) accelerations responsible of the time-honored anomalous Mercury perihelion precession and the Lense–Thirring frame-dragging, respectively.

### 3 The 1pN gravitoelectric effect

Let us start with the static component of the 1pN field, which, in the case of our Solar System, yields the formerly anomalous perihelion precession of Mercury of \( \dot{\sigma}_{\text{q}} = 42.98 \text{ arcsec yr}^{-1} \) [38].

The 1pN gravitoelectric, Schwarzschild-type, acceleration of the relative motion is, in General Relativity [46],

\[
A_{\text{GE}} = \frac{\mu}{\mathcal{c}^2 r^2} \left\{ \left[ (4 + 2\xi) \frac{\mu}{r} - (1 + 3\xi) (\mathbf{v} \cdot \mathbf{v}) + \frac{3}{2} \xi (\mathbf{v} \cdot \mathbf{v})^2 \right] \mathbf{\hat{\rho}} \\
+ (4 - 2\xi) (\mathbf{v} \cdot \mathbf{v}) \mathbf{\hat{v}} \right\}.
\]

By projecting Eq. (28) onto the radial, transverse, out-of-plane unit vectors \( \mathbf{\hat{\rho}}, \mathbf{\hat{\sigma}}, \mathbf{\hat{v}} \), its corresponding components are

\[
A^\rho_{\text{GE}} = \frac{\mu^2}{\mathcal{c}^2 a^3 (1 - e^2)^3} \left[ (4 - 13\xi) e^2 + 4 (3 - \xi) + 8 (1 - 2\xi) e \cos f - (8 - \xi) e^2 \cos 2f \right],
\]

\[
A^\sigma_{\text{GE}} = \frac{2\mu^2}{\mathcal{c}^2 a^3 (1 - e^2)^3} (2 - \xi) e \sin f,
\]

\[
A^\nu_{\text{GE}} = 0.
\]

Here, we use the true anomaly \( f \) since it turns out computationally more convenient.

The resulting net shifts per orbit of the osculating Keplerian orbital elements, obtained by integrating Eq. (6) and Eqs. (19)–(21) from \( f_0 \) to \( f_0 + 2\pi \), are

\[
\begin{align*}
\Delta a_{\text{GE}} &= \Delta e_{\text{GE}} = \Delta f_{\text{GE}} = \Delta \Omega_{\text{GE}} = 0, \quad (32) \\
\Delta \omega_{\text{GE}} &= \Delta \varpi_{\text{GE}} = \frac{6\pi \mu}{\mathcal{c}^2 p}, \\
\Delta M_{\text{GE}} &= \frac{\pi \mu}{4\mathcal{c}^2 a (1 - e^2)^2} \times \left[ 8 (-9 + 2\xi) + 4e^4 (-6 + 7\xi) \right].
\end{align*}
\]

The net time change per revolution of the pulsar p can be calculated with Eq. (26) together with Eqs. (32)–(34), by obtaining

\[
\frac{\mathcal{c}^3}{\pi G m_\text{p} \sin f} \left( \Delta \delta_{\text{p}}, \Delta \varpi_{\text{p}}, \Delta \mu_{\text{p}}, \Delta M_{\text{p}} \right) = \frac{6 \cos u_0}{(1 + e \cos f_0)}
\]

\[
+ \frac{(e \cos \omega + \cos u_0)}{4 (1 - e^2)^{3/2}} \times \left[ 8 (-9 + 2\xi) + 4e^4 (-6 + 7\xi) + e^2 (-84 + 76\xi) \right. \\
+ 3e \left[ 8 (-7 + 3\xi) + e^2 (-24 + 31\xi) \right] \cos f_0 \\
\left. + 3e^2 [4 (-5 + 4\xi) \cos 2f_0 + e \xi \cos 3f_0] \right].
\]

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It should be noted that Eq. (35) is independent of the semimajor axis $a$, depending only on the shape of the orbit through $e$ and its orientation in space through $I$, $\omega$. Furthermore, Eq. (35) does depend on the initial epoch $t_0$ through $f_0$. In the limit $e \to 0$, Eq. (35) does not vanish, reducing to

$$\left\{ \Delta \delta \tau_p^{\text{GE}} \right\} \simeq \frac{4\pi G m_c \sin I (3 + \xi) \cos \mu_0}{c^3} + \mathcal{O}(e). \quad (36)$$

In view of its cumbersomeness, we will not display here the explicit expression of $\Delta \delta \tau_p^{\text{GE}}(f)$ whose validity was successfully checked by numerically integrating the equations of motion for a fictitious binary system, as shown by Fig. 1; see also Sect. 3.1.

We will not deal here with the Shapiro-like propagation delay since it was accurately calculated in the literature; see, e.g., [11,14] and the references therein.

3.1 The pulsar in Sgr A* and the gravitoelectric orbital time delay

An interesting, although still observationally unsupported, scenario involves the possibility that radio pulsars orbit the SMBH at the GC in Sgr A*; in this case, the unseen companion would be the SMBH itself. Thus, in view of its huge mass, the expected time shift per orbit $\left\{ \Delta \delta \tau_p^{\text{GE}} \right\}$ would be quite large.

By considering a hypothetical pulsar with standard mass $m_p = 1.4 \, M_\odot$ and, say, the same orbital parameters of the main sequence star S2 actually orbiting the galactic SMBH [19], Eq. (35) yields

$$\left\{ \Delta \delta \tau_p^{\text{GE}} \right\} = 1.722,6948 \, \text{s}. \quad (37)$$

Figure 1 displays the temporal pattern of $\Delta \delta \tau_p^{\text{GE}}(t)$ for the same hypothetical pulsar calculated both analytically with Eqs. (26)–(27) applied to Eq. (28) and numerically by integrating its equations of motion: their agreement is remarkable. It turns out that

$$\Delta \delta \tau_p^{\text{GE}} \bigg|^{\text{max}} = 2520.3557 \, \text{s}, \quad (38)$$

$$\Delta \delta \tau_p^{\text{GE}} \bigg|^{\text{min}} = -6119.2341 \, \text{s}. \quad (39)$$

Equation (35) allows one to find the maximum and minimum values of the net orbital change per revolution of the putative pulsar in Sgr A* by suitably varying $e$, $I$, $\omega$, $f_0$ within given ranges. By limiting ourselves to $0 \leq e \leq 0.97$ for convergence reasons of the optimization algorithm adopted, we have

$$\left\{ \Delta \delta \tau_p^{\text{GE}} \right\}^{\text{max}} = 1.74521212562 \times 10^7 \left( \epsilon_{\text{max}} = 0.97, \, I_{\text{max}} = 94.98^\circ, \right.$$

$$\omega_{\text{max}} = 184.56^\circ, \, f_0^{\text{max}} = 357.23^\circ \bigg), \quad (40)$$

$$\left\{ \Delta \delta \tau_p^{\text{GE}} \right\}^{\text{min}} = -1.7568613043 \times 10^7 \left( \epsilon_{\text{min}} = 0.97, \, I_{\text{min}} = 89.95^\circ, \right.$$

$$\omega_{\text{min}} = 359.68^\circ, \, f_0^{\text{min}} = 0.28^\circ \bigg). \quad (41)$$

Such huge orbital time delays would be accurately detectable, even by assuming a pessimistic pulsar timing precision of just 100 $\mu\text{s}$ [20,39]; more optimistic views point towards precisions of the order of even 1–10 $\mu\text{s}$ [20,39].
Table 1 Relevant physical and orbital parameters of the S2 star and the SMBH at the GC along with their estimated uncertainties according to Table 3 of [19]; they are referred to the epoch 2000.0. $D_0$ is the distance to Sgr A*. The Schwarzschild radius of the SMBH is $r_g = 2GM/c^2 = 0.088$ au, while the linear size of the semimajor axis of S2 is $a = 1.044$ au = 11.863.6 $r_g$. We quote also the derived values of the SMBH’s angular momentum and quadrupole mass moment calculated as [18,21] $J_0 = \chi S_0 Gc^{-1}$, $Q_0^+ = -S_0^2 c^{-2} M_0^*$ due to the “no-hair” theorems [22,26,40]. The dimensionless parameter $\chi_S \leq 1$ is of the order of about 0.6 for the SMBH in Sgr A* [39]. We display also the value $f_0$ inferred from Eq. (27) for the true anomaly at the epoch $t_0 = 2003.271$ quoted in Table 5 of [19].

| Parameter | Value |
|-----------|-------|
| $M_\star$ | $4.28 \pm 0.10 \, M_\odot$ |
| $D_0$ | $8.32 \pm 0.07 \, \text{kpc}$ |
| $P_0$ | $16.00 \pm 0.02 \, \text{years}$ |
| $a$ | $0.1255 \pm 0.0009 \, \text{arcsec}$ |
| $e$ | $0.8839 \pm 0.0019$ |
| $I$ | $134.18 \pm 0.40^\circ$ |
| $\Omega$ | $226.94 \pm 0.60^\circ$ |
| $\delta$ | $65.51 \pm 0.57^\circ$ |
| $t_p$ | $2002.33 \pm 0.01 \, \text{calendar year}$ |

| Parameter | Value |
|-----------|-------|
| Parameter | Value |
| $f_0$ | $139.72 \pm 0.48^\circ$ |
| $S_\star$ | $x_S 1.61 \times 10^{55} \, \text{kg m}^2 \text{s}^{-1}$ |
| $Q_0^+$ | $-\chi_S^2 3.40 \times 10^{36} \, \text{kg}^2 \text{m}^{-2}$ |
| $Q_{\rho}^+$ | $-\chi_S^2 3.40 \times 10^{36} \, \text{kg}^2 \text{m}^{-2}$ |

4 The 1pN gravitomagnetic Lense–Thirring effect

The stationary component of the 1pN field, due to mass-energy currents, is responsible of several aspects of the so-called spin-orbit coupling, or frame-dragging [16,44,45,48].

The 1pN gravitomagnetic, Lense–Thirring-type acceleration affecting the relative orbital motion of a generic binary made of two rotating bodies A, B is [2,46]

$$A_{\rho}^{LT} = \frac{2Gn_0}{c^2} \left[ 3 \frac{(S \cdot \hat{\rho})}{\hat{\rho} \times \hat{\rho} + \hat{v} \times S} \right].$$

In general, it is

$$\hat{S}_A \neq \hat{S}_B,$$

i.e. the angular momenta of the two bodies are usually not aligned. Furthermore, they are neither aligned with the orbital angular momentum $L$, whose unit vector is given by $\hat{v}$. Finally, also the magnitudes $S_A$, $S_B$ are, in general, different.

The radial, transverse and out-of-plane components of the gravitomagnetic acceleration, obtained by projecting Eq. (42) onto the unit vectors $\hat{\rho}$, $\hat{\sigma}$, $\hat{v}$, turn out to be

$$A^{LT}_\rho = \frac{2Gn_0}{c^2} \left( 1 + e \cos f \right)^4 \frac{S \cdot \hat{v}}{c^2 (1 - e^2)^{7/2}},$$

$$A_{\sigma}^{LT} = \frac{2eGn_0}{c^2} \left( 1 + e \cos f \right)^3 \frac{S \cdot \hat{v}}{c^2 (1 - e^2)^{7/2}},$$

$$A_{v}^{LT} = \frac{2Gn_0}{c^2} \left( 1 + e \cos f \right)^3 S \cdot \hat{v}\left\{ \left[ e \cos \omega (2 + 3e \cos f) \cos u \right] \hat{v} - \frac{1}{2} \left[ e \sin \omega + 4 \sin u + 3e \sin (\omega + 2f) \right] \hat{m} \right\}.$$

By using Eqs. (44)–(46) in Eq. (6) and Eqs. (19)–(21) and integrating them from $f_0$ to $f_0 + 2\pi$, it is possible to straightforwardly calculate the 1pN gravitomagnetic net orbital changes for a generic binary arbitrarily oriented in space: they are

$$\left\{ \Delta a^{LT} \right\} = \left\{ \Delta e^{LT} \right\} = \left\{ \Delta M^{LT} \right\} = 0,$$

$$\left\{ \Delta I^{LT} \right\} = \frac{4\pi G S \cdot \hat{I}}{c^2 n_0 a^3 (1 - e^2)^{3/2}},$$

$$\left\{ \Delta \Omega^{LT} \right\} = \frac{4\pi G \csc I \hat{S} \cdot \hat{m}}{c^2 n_0 a^3 (1 - e^2)^{3/2}},$$

$$\left\{ \Delta \omega^{LT} \right\} = -\frac{4\pi G S \cdot (2\hat{v} + \cot I \hat{m})}{c^2 n_0 a^3 (1 - e^2)^{3/2}}.$$

It is interesting to remark that, in the case of Eq. (42), both Eqs. (15) and (21) yield vanishing contributions to $\left\{ \Delta M^{LT} \right\}$. For previous calculations based on different approaches and formalisms, see, e.g., [2,13,25], and the references therein.

Equation (26), calculated with Eqs. (47)–(50), allows one to obtain the net orbit-type time change per revolution of the pulsar $p$ as

$$\left\{ \Delta \delta_\rho^{LT} \right\} = \frac{4\pi G m_e}{\cos \omega u_0 - \left( \hat{n} \cos I + 2\hat{v} \sin I \right) \cos u_0}.$$

Note that, contrary to Eq. (35), Eq. (51) does depend on the semimajor axis as $a^{-1/2}$. As Eq. (35), also Eq. (51) depends on $f_0$. The instantaneous orbital time shift $\Delta \delta_\rho^{LT} (f)$ turns out to be too unwieldly to be explicitly displayed here. Its validity was successfully checked by numerically integrating the equations of motion for a fictitious binary system, as shown by Fig. 2; see also Sect. 4.1.

The gravitomagnetic propagation time delay is treated in Sect. 4.2.
Let us, now, consider the so-far hypothetical scenario of an emitting radio pulsar orbiting the SMBH in Sgr A\(^*\). By assuming \([3,36]\)

\[
I_{\text{NS}} \simeq 10^{38} \text{ kg m}^2
\]

for the moment of inertia of a neutron star (NS), the spin of PSR J0737-3039A is

\[
S^A = 2.8 \times 10^{40} \text{ kg m}^2 \text{s}^{-1}. \tag{53}
\]

The angular momentum of a NS of mass \(m_{\text{NS}}\) can also be expressed in terms of the dimensionless parameter \(\chi_s > 0\) as \([34]\)

\[
S_{\text{NS}} = \chi_s \frac{m_{\text{NS}}^2 G}{c}. \tag{54}
\]

Thus, Eq. (53) implies

\[
\chi_s^A = 0.01755 \tag{55}
\]

for PSR J0737-3039A. Since for the galactic SMBH it is \([21]\)

\[
S_\bullet = \chi_s \frac{M_\bullet^2 G}{c} \simeq 9.68 \times 10^{54} \text{ kg m}^2 \text{s}^{-1} \tag{56}
\]

with\(^6\) \([39]\)

\[
\chi_s \simeq 0.6, \tag{57}
\]

we have

\[
\frac{S^\bullet}{S^A} \simeq 6 \times 10^{-9}. \tag{58}
\]

Thus, in this case, the dominant contribution to Eq. (42) is due to the pulsar’s companion \(c\). As far as the orientation of the SMBH’s spin is concerned, we model it as

\[
\hat{S} = \sin \iota_\bullet \cos \epsilon_\bullet \hat{e}_x + \sin \iota_\bullet \sin \epsilon_\bullet \hat{e}_y + \cos \iota_\bullet \hat{e}_z. \tag{59}
\]

The angles \(\iota_\bullet, \epsilon_\bullet\) are still poorly constrained \([5,6,53]\), so that we prefer to treat them as free parameters by considering their full ranges of variation

\[
0 \leq \iota_\bullet \leq 180^\circ, \tag{60}
\]

\[
0 \leq \epsilon_\bullet \leq 360^\circ. \tag{61}
\]

Also in this case, we assume for our putative pulsar the same orbital parameters of, say, the S2 star.

By using our analytical expression for \(\Delta \delta r_{\text{LT}}^\bullet (t)\), calculated with \(S^0 \to 0\) in view of Eq. (58), one gets

\[
\Delta \delta r_{\text{LT}}^\bullet \bigg|_{\text{max}} = 0.6054 \text{ s} \ (\iota_\bullet = 20.9^\circ, \epsilon_\bullet = 317.9^\circ), \tag{62}
\]

\[
\Delta \delta r_{\text{LT}}^\bullet \bigg|_{\text{min}} = -0.6053 \text{ s} \ (\iota_\bullet = 159.1^\circ, \epsilon_\bullet = 137.9^\circ), \tag{63}
\]

within the assumed ranges of variation for the angles \(\iota_\bullet, \epsilon_\bullet\) provided by Eqs. (60)–(61). To this aim, see Fig. 2 which shows both the analytical time series, calculated with Eqs. (26)–(27) applied to Eq. (42) for \(\iota_\bullet = 20.9^\circ, \epsilon_\bullet = 317.9^\circ\) and the numerically integrated one for the same values of the

\(^6\) Let us recall that, for a Kerr BH, it must be \(\chi_s \leq 1\).
SMBH’s spin axis angles: they are in good agreement. The maximum and the minimum values of the propagation delays for the same orbital configuration of the pulsar are displayed in Eqs. (67)–(68). Let us, now, remove any limitation on the orbital configuration of the pulsar. By restricting ourselves to \(0 < e < 0.97\) for convergence reasons of the optimization algorithm adopted, we have

\[
\begin{align*}
\left\{ \Delta \delta \tau_p \right\}_{\text{max}}^\text{LT} &= 411.1823 \, \text{s} \\
(P_b^\text{max}) &= 5 \, \text{years}, \quad (e)^\text{max} = 0.97, \quad (l)^\text{max} = 90^\circ, \\
\omega_{\text{max}} &= 180^\circ, \quad \Omega_{\text{max}} = 167.21^\circ, \quad f_{0}^\text{max} = 180^\circ, \\
\iota_\bullet^\text{max} = 90^\circ, \quad \epsilon_\bullet^\text{max} = 257.21^\circ, \\
\left\{ \Delta \delta \tau_p \right\}_{\text{min}}^\text{LT} &= -293.1933 \, \text{s} \\
(P_b^\text{min}) &= 5 \, \text{years}, \quad (e)^\text{min} = 0.97, \quad (l)^\text{min} = 46.03^\circ, \\
\omega_{\text{min}} &= 26.31^\circ, \quad \Omega_{\text{min}} = 14.35^\circ, \quad \text{deg}, \quad f_{0}^\text{min} = 179.43^\circ, \\
\iota_\bullet^\text{min} = 159.76^\circ, \quad \epsilon_\bullet^\text{min} = 36.41^\circ.
\end{align*}
\]  

where we considered 5 years \(\leq P_b \leq 16\) years; the ranges of variation assumed for the other parameters \(l, \omega, \Omega, f_0, \iota_\bullet, \epsilon_\bullet\) are the standard full ones. The values of Eqs. (62)–(63) and Eqs. (64)–(65) should be compared with the expected pulsar timing precision of about 100 \(\mu\)s, or, perhaps, even 1–10 \(\mu\)s [20,39].

4.2 The Lense–Thirring propagation time shift

The gravitomagnetic propagation delay for a binary with relative separation \(r\) and angular momentum \(S\) of the primary is [32,50]

\[
\delta \tau^\text{LT}_\text{prop} = -\frac{2GS \cdot (\hat{e}_r \times r)}{c^4 (r - \hat{e}_r)} = \frac{2GS (1 + e \cos f) \left[ \cos \left( \hat{S}_x \sin \Omega - \hat{S}_y \cos \Omega \right) + \cos l \sin u \left( \hat{S}_x \cos \Omega + \hat{S}_y \sin \Omega \right) \right]}{c^4 p (1 - \sin l \sin u)}.
\] (66)

According to Figure 2 of [50], their unit vector \(K_0\) agrees with our \(\hat{e}_r\), since it is directed towards the Earth. About the spin axis of the primary, identified with a BH by [50], our \(\iota_\bullet\) coincides with their \(\lambda_\bullet\). Instead, their angle \(\eta_\bullet\) is reckoned from our unit vector \(\hat{l}\), i.e. it is as if [50] set \(\Omega = 0\). On the contrary, our angle \(\epsilon_\bullet\) is counted from the reference \(x\) direction in the plane of the sky, whose unit vector \(\hat{e}_\epsilon\), in general, does not coincide with \(\hat{l}\). Furthermore, [50] use the symbol \(i\) for the orbital inclination angle, i.e., our \(l\). It is important to notice that, contrary to the orbital time delay of Eq. (51), Eq. (66) is a short-term effect in the sense that there is no net shift over one orbital revolution. It is also worth noticing that Eq. (66) is of order \(O \left( c^{-4} \right)\), while Eq. (51) is of order \(O \left( c^{-3} \right)\).

As far as the putative scenario of the pulsar in the GC is concerned, the emitting neutron star is considered as the source of the electromagnetic beam delayed by the angular momentum of the SMBH. Thus, by calculating Eq. (66) for a S2-type orbit and with \(S = S^\bullet\), it is possible to obtain

\[
\begin{align*}
\delta \tau^\text{LT}_\text{prop}\big|_{\text{max}} &= 0.0195 \, \text{s} \left( l_\bullet = 90^\circ, \quad \epsilon_\bullet = 80.1^\circ, \quad f = 360^\circ \right), \\
\delta \tau^\text{LT}_\text{prop}\big|_{\text{min}} &= -0.0213 \, \text{s} \left( l_\bullet = 90^\circ, \quad \epsilon_\bullet = 235.5^\circ, \quad f = 18.5^\circ \right).
\end{align*}
\] (67, 68)

Such values are one order of magnitude smaller than Eqs. (62)–(63) for the orbital time delay calculated with the same orbital configuration of the pulsar. It turns out that values similar to those of Eqs. (67)–(68) are obtained by discarding the S2 orbital configuration for the pulsar:

\[
\begin{align*}
\delta \tau^\text{LT}_\text{prop}\big|_{\text{max}} &= 0.0105 \, \text{s} \left( P_b^\text{max} = 10.5 \, \text{years}, \quad e_{\text{max}} = 0.97, \quad (l_{\text{max}}) = 54.98^\circ, \\
\omega_{\text{max}} &= 70.09^\circ, \quad \Omega_{\text{max}} = 70.33^\circ, \quad f_{0}^{\text{max}} = 69.94^\circ, \\
i_{\text{max}}^{\bullet} &= 55.11^\circ, \quad \epsilon_{\text{max}}^{\bullet} = 72.19^\circ), \\
\delta \tau^\text{LT}_\text{prop}\big|_{\text{min}} &= -0.0375 \, \text{s} \left( P_b^\text{min} = 5 \, \text{years}, \quad e_{\text{min}} = 0.97, \quad (l_{\text{min}}) = 0^\circ, \\
\omega_{\text{min}} &= 325.24^\circ, \quad \Omega_{\text{min}} = 80.08^\circ, \quad f_{0}^{\text{min}} = 0^\circ, \\
i_{\text{min}}^{\bullet} &= 90.01^\circ, \quad \epsilon_{\text{min}}^{\bullet} = 135.3^\circ).
\end{align*}
\] (69, 70)

5 The quadrupole-induced effect

If both the bodies of an arbitrary binary system are axisymmetric about their spin axes \(S^{A/B}\), a further non-central relative acceleration arises; it is [2]

\[
\frac{2r^4}{3\mu} A_{J_2} = J_2^{A/B} \left\{ \left[ 5 \left( S^A \cdot \hat{\rho} \right)^2 - 1 \right] \hat{\rho} - 2 \left( \hat{S}^A \cdot \hat{\rho} \right) \hat{S}^A \right\} + A \Rightarrow B,
\] (71)

in which the first even zonal parameter \(J_2^{A/B}\) is dimensionless. In the notation of [2], their \(J_2^{A/B}\) parameter is not dimension-
less as ours, being dimensionally an area because it corresponds to our $J_{2}^{A/B} R_{A/B}^2$. Furthermore, [2] introduce an associated dimensional quadrupolar parameter $\Delta I^{A/B}$, having the dimensions of a moment of inertia, which is connected to our $J_{2}^{A/B}$ by

$$J_{2}^{A/B} = \frac{\Delta I^{A/B}}{M_{A/B} R_{A/B}^2}. \quad (72)$$

Thus, $\Delta I^{A/B}$ corresponds to the dimensional quadrupolar parameter $Q_{2}^{A/B}$ customarily adopted when astrophysical compact objects like neutron stars and black holes are considered [34,51], up to a minus sign, i.e.

$$J_{2}^{A/B} = - \frac{Q_{2}^{A/B}}{M_{A/B} R_{A/B}^2}. \quad (73)$$

Thus, Eq. (71) can be written as

$$\frac{2r^4}{3G} A_{Q2} = Q_{2}^{A} \left[ 1 - 5 \left( \hat{S}^{A} \cdot \hat{\rho} \right)^2 \right] \hat{\rho} + 2 \left( \hat{S}^{A} \cdot \hat{\rho} \right) \hat{S}^{A} \right] + A \equiv B. \quad (74)$$

Projecting Eq. (71) onto the radial, transverse and out-of-plane unit vectors $\hat{\rho}$, $\hat{\sigma}$, $\hat{\nu}$ provides us with

$$\frac{2a^4 \left( 1 - e^2 \right)^4}{3\mu \left( 1 + e \cos f \right)^3} \Delta \rho^{J_2} = J_{2}^{A} R_{A}^2 \left[ 3 \left[ \cos u \left( \hat{S}^{A} \cdot \hat{i} \right) + \sin u \left( \hat{S}^{A} \cdot \hat{m} \right) \right]^2 - 1 \right] + A \equiv B, \quad (75)$$

$$- \frac{a^4 \left( 1 - e^2 \right)^4}{3\mu \left( 1 + e \cos f \right)^3} \Delta \sigma^{J_2} = J_{2}^{A} R_{A}^2 \left[ \cos u \left( \hat{S}^{A} \cdot \hat{i} \right) + \sin u \left( \hat{S}^{A} \cdot \hat{m} \right) \right] \times \left[ \cos u \left( \hat{S}^{A} \cdot \hat{m} \right) - \sin u \left( \hat{S}^{A} \cdot \hat{i} \right) \right] + A \equiv B, \quad (76)$$

$$- \frac{a^4 \left( 1 - e^2 \right)^4}{3\mu \left( 1 + e \cos f \right)^3} \Delta \nu^{J_2} = J_{2}^{A} R_{A}^2 \left[ \cos u \left( \hat{S}^{A} \cdot \hat{i} \right) + \sin u \left( \hat{S}^{A} \cdot \hat{m} \right) \right] \left( \hat{S}^{A} \cdot \hat{\nu} \right) + A \equiv B. \quad (77)$$

A straightforward consequence of Eqs. (75)–(77) is the calculation of the net quadrupole-induced shifts per revolution of the Keplerian orbital elements by means of Eq. (6) and Eqs. (19)–(21), which turn out to be

$$\left( \Delta e^{J_2} \right) = \left( \Delta f^{J_2} \right) = 0, \quad (78)$$

$$- \frac{p^2}{3\pi} \left( \Delta I^{J_2} \right) = J_{2}^{A} R_{A}^2 \left( \hat{S}^{A} \cdot \hat{i} \right) \left( \hat{S}^{A} \cdot \hat{\nu} \right) + A \equiv B, \quad (79)$$

$$- \frac{p^2}{3\pi} \left( \Delta \Omega^{J_2} \right) = J_{2}^{A} R_{A}^2 \left( \hat{S}^{A} \cdot \hat{m} \right) \left( \hat{S}^{A} \cdot \hat{\nu} \right) \csc I + A \equiv B, \quad (80)$$

Also Eq. (82), as Eq. (34) for the Schwarzschild-like 1pN acceleration, is a novel result which amends the incorrect formulas widely disseminated in the literature [9,25,41,47,52]; indeed, it turns out that, in the case of Eq. (71), Eq. (21) does not vanish when integrated over a full orbital revolution. Furthermore, contrary to almost all of the other derivations existing in the literature, Eq. (82) is quite general since it holds for a two-body system with generic quadrupole mass moments arbitrarily oriented in space, and characterized by a general orbital configuration. The same remark holds also for Eqs. (78)–(81); cf. the corresponding (correct) results by [25] in the case of a test particle orbiting an oblate primary.

According to Eq. (26) and Eqs. (78)–(82), the net orbit-like time change of the pulsar $p$ after one orbital revolution is

$$\frac{2m_{tot} \left( 1 - e^2 \right) \left( 1 + e \cos f_0 \right)}{3\pi m_c} \left( \Delta \delta \tau_p^{J_2} \right) = J_{2}^{p} R_{p}^2 \left[ 2 - 3 \left( \hat{S}^{p} \cdot \hat{i} \right)^2 - 3 \left( \hat{S}^{p} \cdot \hat{m} \right)^2 \right] \sin I \cos u_0 + 2J_{2}^{p} R_{p}^2 \cos I \left[ \left( \hat{S}^{p} \cdot \hat{m} \right) \cos u_0 - \left( \hat{S}^{p} \cdot \hat{i} \right) \sin u_0 \right]$$

$$- \frac{J_{2}^{p} R_{p}^2 \left( 1 + e \cos f_0 \right)^4}{\left( 1 - e^2 \right)^{5/2}} \sin I \left( e \cos \omega + \cos u_0 \right)$$

$$\cdot \left[ -2 + 3 \left( \hat{S}^{p} \cdot \hat{i} \right)^2 + \left( \hat{S}^{p} \cdot \hat{m} \right)^2 \right]$$

$$+ 3 \left[ \left( \hat{S}^{p} \cdot \hat{i} \right)^2 - \left( \hat{S}^{p} \cdot \hat{m} \right)^2 \right] \cos 2u_0$$

$$+ 6 \left( \hat{S}^{p} \cdot \hat{i} \right) \left( \hat{S}^{p} \cdot \hat{m} \right) \sin 2u_0 \right] + p \equiv c. \quad (83)$$

It turns out that Eq. (83) does not vanish in the limit $e \to 0$. If, on the one hand, Eq. (83) depends of $f_0$ as Eq. (35) and Eq.
5.1 The pulsar in Sgr A* and the quadrupole-induced orbital time delay

A rotating NS acquires a non-zero quadrupole moment given by [34]

\[
Q_2^\text{NS} = q \frac{m_{\text{NS}} G^2}{c^4};
\]  

(84)

the absolute values of the dimensionless parameter \( q < 0 \) ranges from 0.074 to 3.507 for a variety of Equations of State (EOSs) and \( m_{\text{NS}} = 1.4 \, M_\odot \); cf. Table 4 of [34]. It is interesting to note that [34] find the relation

\[
q \simeq -\alpha_\bullet \chi_s^2,
\]  

(85)

where the parameter \( \alpha \) of the fit performed by [34] depends on both the mass of the neutron star and the EOS used. According to Table 7 of [34], it is

\[
\alpha_{\text{max}} = 7.4 \quad (m_{\text{NS}} = 1.4 \, M_\odot, \text{ EOS L}),
\]  

(86)

\[
\alpha_{\text{min}} = 2.0 \quad (m_{\text{NS}} = 1.4 \, M_\odot, \text{ EOS G})
\]  

(87)

for some of the EOSs adopted by [34]. In the case of PSR J0737-3039A, Eq. (84) yields

\[
Q_2^A = q_\bullet 1.04 \times 10^{37} \text{ kg m}^2.
\]  

(88)

According to Eq. (55) and Eq. (85), we have

\[
q_\bullet = -\alpha_\bullet \times 3.1 \times 10^{-4}.
\]  

(89)

As a consequence of the “no-hair” or uniqueness theorems [22,26,40], the quadrupole moment of a BH is uniquely determined by its mass and spin according to [18,21]

\[
Q_2^* = -\frac{S^2}{c^2 M_\bullet};
\]  

(90)

in the case of the SMBH in Sgr A*, we have (\( \chi_s = 0.6 \))

\[
Q_2^* = -1.2 \times 10^{56} \text{ kg m}^2.
\]  

(91)

Equations (88) and (91) imply that, in the GC,

\[
Q_2^{p,\bullet} = q_\bullet 3.8 \times 10^{43} \text{ kg m}^2,
\]  

(92)

\[
Q_2^p = -1.2 \times 10^{56} \text{ kg m}^2,
\]  

(93)

so that the quadrupole of a hypothetical emitting neutron star p orbiting the SMBH in Sgr A* can be completely neglected with respect to the quadrupole of the latter one in any practical calculation.

According to our analytical expression for \( \Delta \delta t_p^{Q_2^p} (t) \) applied to a pulsar moving along a S2-type orbit, in view of the ranges of variation assumed in Eqs. (60)–(61) for \( i_\bullet, \, \varepsilon_\bullet \), we have

\[
\left. \Delta \delta t_p^{Q_2^p} \right|^{\text{max}} = 0.0215 \text{ s} \quad (i_\bullet = 146.7^\circ, \, \varepsilon_\bullet = 148.8^\circ),
\]  

(94)

\[
\left. \Delta \delta t_p^{Q_2^p} \right|^{\text{min}} = -0.0393 \text{ s} \quad (i_\bullet = 30.5^\circ, \, \varepsilon_\bullet = 331.6^\circ).
\]  

(95)
Figure 3 displays the outcome of a numerical integration of the equations of motion of the pulsar considered for \(i_\bullet = 146.7^\circ\), \(e_\bullet = 148.8^\circ\), and the corresponding analytical time series calculated by means of Eqs. (26)–(27) applied to Eq. (71); they agree quite well. The maximum and minimum values of the propagation delay for the same orbital configuration of the pulsar are in Eqs. (126)–(127). By removing the restrictions on the orbit of the pulsar and assuming the same ranges of variation for \(P_b\), \(e\), \(I\), \(\Omega\), \(\omega\), \(f_0\), \(i_\bullet\), \(e_\bullet\) as in Sect. 4.1, apart from 0 \(\leq e \leq 0.96\) for convergence issues of the optimization algorithm adopted, it is possible to obtain

\[
\{\Delta \tau_{\text{prop}}^2\}^\text{max} = 1392.3665 \text{ s} \quad (P_b^{\text{max}} = 5 \text{ years}, \ e_{\text{max}} = 0.96, \ I_{\text{max}} = 90^\circ, \ \omega_{\text{max}} = 180^\circ, \ \Omega_{\text{max}} = 17.89^\circ, \ f_0^{\text{max}} = 0^\circ, \ \delta \tau_{\text{prop}}^2_{\text{max}} = 90^\circ, \ e_{\text{max}} = 17.89^\circ),
\]

(96)

The bounds of Eqs. (94)–(95) and Eqs. (96)–(97) can be compared with the minimum and maximum values of the gravitomagnetic orbital shift of Eqs. (63)–(62) for an S2-type orbit, which are about one order of magnitude larger than Eqs. (94)–(95), and Eqs. (64)–(65), which, instead, are smaller than Eqs. (96)–(97). Furthermore, the values of Eqs. (94)–(95) and Eqs. (96)–(97) seem to be potentially measurable in view of the expected pulsar timing precision of about 100 \(\mu\)s, or, perhaps, even 1–10 \(\mu\)s [20,39].

5.2 The quadrupole-induced propagation time shift

The propagation delay \(\delta \tau_{\text{prop}}^2\) due to the quadrupole mass moment is rather complicated to be analytically calculated; see, e.g., [29,30,32,55]. No explicit expressions analogous to the simple one of Eq. (66) for frame-dragging exist in the literature. Here, we will obtain an analytical formula for \(\delta \tau_{\text{prop}}^2\), which will be applied to the double pulsar and the pulsar–Sgr A* systems. The approach by [55] will be adopted by adapting it to the present scenario. In the following, the subscripts \(d\), \(s\), \(o\) will denote the deflector, the source, and the observer, respectively. In the case of, say, the double pulsar, \(d\) is the pulsar B, while \(s\) is the currently visible pulsar A; in the pulsar–Sgr A* scenario, \(d\) is the SMBH and \(s\) is the hypothetical pulsar \(p\) orbiting it. See Fig. 4 for the following vectors connecting \(d\), \(s\), \(o\). The origin \(O\) is at the binary’s center of mass, so that

\[
\begin{align*}
\dot{r}_{\text{emi}}^s & = r_{\text{emi}}^s(t_{\text{emi}}) \\
\dot{r}_{\text{emi}}^d & = r_{\text{emi}}^d(t_{\text{emi}}) \\
\dot{r}_{\text{rec}}^o & = r_{\text{rec}}^o(t_{\text{rec}}) \\
\dot{r}_{\text{rec}}^d & = r_{\text{rec}}^d(t_{\text{rec}}) \\
\dot{r}_{\text{rec}}^s & = r_{\text{rec}}^s(t_{\text{rec}}) \\
\dot{r}_{\text{rec}}^o & = D \dot{e}_z,
\end{align*}
\]

(98) (99) (100) (101) (102) (103) (104) (105) (106)
where $D$ is the distance of the binary at $t_{\text{emi}}$ from us at $t_{\text{rec}}$, which is usually much larger than the size $r_{\text{emi}}$ of the binary’s orbit. Thus, the following simplifications can be safely made:

$$s = r_{\text{rec}}^o - r_{\text{emi}}^o = D \hat{e}_z - \frac{m_d}{m_{\text{tot}}} r_{\text{emi}} \simeq D \hat{e}_z,$$  
(107)

$$\hat{s} \simeq \hat{e}_z,$$  
(108)

$$r_{\text{rec}}^d = r_{\text{rec}}^o - r_{\text{emi}}^d = D \hat{e}_z + \frac{m_s}{m_{\text{tot}}} r_{\text{emi}} \simeq D \hat{e}_z.$$  
(109)

To order $\mathcal{O}(c^{-2})$, the impact parameter vector can be calculated as [55]

$$\ell^d \simeq \hat{s} \times (r_{\text{emi}} \times \hat{s}) = r_{\text{emi}} - \hat{s} (r_{\text{emi}} \cdot \hat{s}).$$  
(110)

In view of Eq. (108), it turns out that $\ell^d$, evaluated onto the unperturbed Keplerian ellipse, lies in the plane of the sky, being made of the $x$, $y$ components of $\hat{p}$ scaled by Eq. (12).

The coefficients of Eqs. (A.18)–(A.20) of [55]

$$\mathcal{E}_d = \frac{\hat{s} \cdot r_{\text{emi}}}{r_{\text{emi}}^3} - \frac{\hat{s} \cdot r_{\text{rec}}^d}{r_{\text{rec}}^d 3},$$  
(111)

$$\mathcal{F}_d = \ell^d \left( \frac{1}{r_{\text{emi}}^3} - \frac{1}{r_{\text{rec}}^d 3} \right),$$  
(112)

$$\mathcal{V}_d = -\frac{1}{c d^2} \left( \frac{\hat{s} \cdot r_{\text{emi}}}{r_{\text{emi}}} - \frac{\hat{s} \cdot r_{\text{rec}}^d}{r_{\text{rec}}^d} \right),$$  
(113)

required to calculate $\delta t_{\text{prop}}^{J_2}$, can be approximated to

$$\mathcal{E}_d \simeq \frac{\hat{s} \cdot r_{\text{emi}}}{r_{\text{emi}}^3},$$  
(114)

$$\mathcal{F}_d \simeq \frac{\ell^d}{r_{\text{emi}}},$$  
(115)

$$\mathcal{V}_d \simeq -\frac{1}{c d^2} \left( \frac{\hat{s} \cdot r_{\text{emi}}}{r_{\text{emi}}} - 1 \right).$$  
(116)

The rotation matrix which takes the deflector’s symmetry axis from $\hat{e}_z$ to a generic position in space characterized by the usual polar angles $i$, $\varepsilon$, is

$$[R]_{ij} = \begin{pmatrix} \cos \varepsilon \cos i - \sin \varepsilon \cos \varepsilon \sin i \\ \sin \varepsilon \cos i & \cos \varepsilon \sin i \\ -\sin i & 0 & \cos i \end{pmatrix}$$  
(117)

It is made of an anticlockwise rotation by an amount $i$ around $\hat{e}_y$, followed by an anticlockwise rotation by an amount $\varepsilon$ around $\hat{e}_z$. The symmetric trace-free quadrupole moment of the deflector [55]

$$M^d = \frac{1}{3} m_d R_{d3}^{J_2} R_{d3} \mathbf{D}[1, 1, -2] \mathbf{R}_T,$$  
(118)

where $\mathbf{D}[\ast, \ast, \ast]$ denotes the diagonal matrix along with the associated entries, becomes

$$[M^d]_{ij} = m_d R_{d3}^{J_2} R_{d3} \times \left( \begin{array}{ccc} 1 - \cos^2 \varepsilon \sin^2 \varepsilon \sin 2i & -\frac{1}{2} \sin^2 \varepsilon \cos 2\varepsilon \\
-\frac{1}{2} \sin^2 \varepsilon \sin 2\varepsilon & \frac{1}{2} \cos^2 \varepsilon + \cos^2 \varepsilon \sin^2 \varepsilon & -\frac{1}{2} \cos \varepsilon \sin 2i \sin 2\varepsilon \\
-\frac{1}{2} \cos \varepsilon \sin 2i \sin 2\varepsilon & -\frac{1}{2} \cos \varepsilon \sin 2i \sin 2\varepsilon & \frac{1}{2} \cos^2 \varepsilon \end{array} \right).$$  
(119)

Equation (119) agrees with Eqs. (48)–(53) of [30] for $i \to \pi/2 - \delta$, $\varepsilon \to \alpha$, where $\delta$, $\alpha$ are the declination and right ascension, respectively. Equation (119) is needed to work out the coefficients of Eqs. (A.21)–(A.23) of [55]

$$\beta_d = \left[ M^d \right]_{ij} \hat{s}_i \hat{s}_j - \left[ M^d \right]_{ij} \hat{e}_d^i \hat{e}_d^j,$$  
(120)

$$\gamma_d = 2 \left[ M^d \right]_{ij} \hat{s}_i \hat{e}_d^j,$$  
(121)

$$\theta_d = \left[ M^d \right]_{ij} \hat{s}_i \hat{s}_j + 2 \left[ M^d \right]_{ij} \hat{e}_d^i \hat{e}_d^j,$$  
(122)

which are the building blocks of the calculation of $\delta t_{\text{prop}}^{J_2}$ along with Eqs. (114)–(116).

Finally, the quadrupole-induced propagation delay due to the deflector $d$ can be obtained by evaluating [55]

$$\delta t_{\text{prop}}^{J_2} = \frac{G}{c^3} (\beta_d \mathcal{E}_d + \gamma_d \mathcal{F}_d + \theta_d \mathcal{V}_d)$$  
(123)

onto the unperturbed Keplerian ellipse by means of Eqs. (114)–(116) and Eqs. (120)–(122). The resulting explicit expression is

$$\delta t_{\text{prop}}^{J_2} = \frac{G m_d R_{d3}^{J_2} (1 + \cos f)^2}{4c^3 p^2} T (I, \Omega, u, i, \varepsilon),$$  
(124)

with

$$T = \frac{2 (2 + \sin I \sin u) \sin^2 i}{(1 + \sin I \sin u)^2} \times \left[ \cos 2\Omega + \cos I \sin 2\Omega \sin 2u \\
- (1 + \cos^2 I) \cos 2\Omega \sin^2 u \right] \cos 2\varepsilon \\
- \left[ \cos I \sin 2u + \sin 2\Omega - 2 \cos I \sin^2 \Omega \sin 2u \\
- \sin 2\Omega (1 + \cos^2 I) \sin^2 u \right] \\
- 4 \sin 2i \left[ (\cos \Omega \cos u - \cos I \sin \Omega \sin u) \cos \varepsilon \\
+ (\cos u \sin \Omega + \cos I \cos \Omega \sin u) \sin \varepsilon \right] \\
+ \sin I \sin u (-1 - 3 \cos 2i).$$  
(125)

It is interesting to note that Eq. (124) does not vanish for circular orbits. Furthermore, from Eq. (124) it turns out that there is no net quadrupolar propagation delay per cycle.
If the pulsar–SMBH in the GC is considered, the quadrupole Shapiro-type time delay is much smaller than the orbital time shift. Indeed, by using Eqs. (124)–(125) for a S2-type orbital configuration, it turns out that

\[
\delta r^Q_p \bigg|_{\text{max}} = 0.6 \mu s \left( i_* = 90^\circ, \ v_* = 281.8^\circ, \ f = 339.8^\circ \right) ,
\]

(126)

\[
\delta r^Q_p \bigg|_{\text{min}} = -1.1 \mu s \left( i_* = 35.8^\circ, \ v_* = 182.5^\circ, \ f = 349.0^\circ \right) .
\]

(127)

The bounds of Eqs. (126)–(127) should be compared with those of Eqs. (94)–(95), which are about four orders of magnitude larger. Values as little as those of Eqs. (126)–(127) should be hard to be detectable in view of the expected pulsar timing precision, even in the optimistic case of 1–10 \( \mu s \) [20,39]. If the orbital configuration of S2 is abandoned, letting \( I, \Omega, \omega, f, i_*, v_* \) freely vary within their full natural ranges, we get values which can reach the 100 \( \mu s \) level for 0 \( \leq e \leq 0.97 \), 5 years \( \leq P_b \leq 16 \) years.

6 Summary and conclusions

In order to perform sensitivity studies, designing suitable tests and reinterpreting existing data analyses in a way closer to the actual experimental practice in pulsar timing, we devised a method to analytically calculate the shifts \( \Delta \delta \tau^A_p \) experienced by the orbital component of the time changes \( \delta \tau_p \) of a binary pulsar \( p \) due to some perturbing post-Keplerian accelerations \( A \): Schwarzschild, Lense–Thirring and mass quadrupole. We applied it to the still hypothetical scenario encompassing an emitting neutron star which orbits the supermassive black hole in Sgr A*; its timing precision could reach 100 \( \mu s \), or, perhaps, even 1–10 \( \mu s \) [20,39]. The main results of the present study are resumed in Table 2. By assuming a S2-like orbital configuration and a time span as long as its orbital period, the magnitude of the post-Newtonian Schwarzschild-type gravitoelectric signature can reach \( \left| \Delta \delta \tau^A_p \right| \lesssim 10^3 \) s. The post-Newtonian Lense–Thirring gravitomagnetic and quadrupolar effects are much smaller, amounting to at most \( \Delta \delta \tau^L_{p,T} \lesssim 0.6 \) s, \( \Delta \delta \tau^Q_{p,T} \lesssim 0.04 \) s, depending on the orientation of the black hole’s spin axis. Faster, \( (P_b = 5 \) years), and more eccentric, \( (e = 0.97) \), orbits would imply net shifts per revolution \( \left| \Delta \delta \tau^A_p \right| \lesssim 10 \) Ms, \( \left| \Delta \delta \tau^L_{p,T} \right| \lesssim 400 \) s, \( \left| \Delta \delta \tau^Q_{p,T} \right| \lesssim 10^3 \) s or so, depending on the other orbital parameters and the initial epoch.

Among other things, we also explicitly calculated an analytical formula for the Shapiro-like time delay \( \delta \tau^L_{p,T} \) due to the propagation of electromagnetic waves in the field of a spinning oblate body, which we applied to the aforementioned binary system. As far as the Lense–Thirring and the quadrupolar effects are concerned, the Shapiro-like time shifts \( \delta \tau^L_{p,T} \) are, in general, much smaller than the orbital ones \( \Delta \delta \tau_p \) which, contrary to \( \delta \tau_p \), are cumulative. In the case of the pulsar–Sgr A* scenario, we find, for a S2-type orbit, that the Lense–Thirring propagation delay is as little as \( \delta \tau^L_{p,T} \lesssim 0.02 \) s, while the quadrupolar one is of the order of \( \delta \tau^Q_{p,T} \lesssim 1 \) \( \mu s \), both depending on the spin orientation of the black hole. Removing the limitation to the S2 orbital configuration yields essentially similar values for \( \delta \tau^L_{p,T} \), \( \delta \tau^Q_{p,T} \), even for highly eccentric and faster orbits.

Finally, we remark that our approach is general enough to be extended to arbitrary orbital geometries and symmetry axis orientations of the binary’s bodies, and to whatsoever disturbing accelerations. As such, it can be applied to other binary systems as probes for, say, modified models of gravity. In principle, also man-made binaries could be considered.

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A. Notations and definitions

Here, some basic notations and definitions used in the text are presented [4,8,35,46]

$G$: Newtonian constant of gravitation
$c$: speed of light in vacuum
$\hat{\varepsilon}_z$, $\hat{\varepsilon}_y$: unit vectors spanning the plane of the sky.
$M_A$: mass of the body A
$M_B$: mass of the body B
$m_p$: mass of the pulsar p
$m_c$: mass of the unseen companion c
$m_{tot} \equiv M_A + M_B$: total mass of the binary
$\mu \equiv Gm_{tot}$: gravitational parameter of the binary
$\xi \equiv M_A M_B m_{tot}^{-2}$: dimensionless mass parameter of the binary
$S$: magnitude of the angular momentum of any of the binary’s components
$S^{A/B} \equiv \left(1 + \frac{3}{4} \frac{m_{BA}}{M_{AB}}\right) S^{A/B}$: magnitude of the scaled angular momentum of any of the binary’s component
$\hat{S}$: unit vector of the spin axis of any of the binary’s components
$i$, $\varepsilon$: spherical angles determining the spatial orientation of $\hat{S}$; $i = 90^\circ$ implies that the latter lies in the plane of the sky
$\chi_S$: dimensionless angular momentum parameter of a Kerr black hole
$R$: equatorial radius of any of the binary’s components
$Q_2$: dimensionless quadrupole mass moment of any of the binary’s components
$Q^{A/B} \equiv \left(1 + \frac{M_B}{M_A}\right) Q^{A/B}$: scaled dimensional quadrupole mass moment of any of the binary’s components
$r$: relative position vector of the binary’s orbit
$v$: relative velocity vector of the binary’s orbit
$a$: semimajor axis of the binary’s orbital orbit
$n_b \equiv \sqrt{\mu a^{-3}}$: Keplerian mean motion
$P_b \equiv 2\pi n_b^{-1}$: Keplerian orbital period
$a_A \equiv M_B M_{tot}^{-1} a$: semimajor axis of the barycentric orbit of the binary’s visible component A
$e$: eccentricity
$p \equiv a(1 - e^2)$: semilatus rectum

$I$: inclination of the orbital plane
$\Omega$: longitude of the ascending node
$\omega$: argument of pericenter
$\sigma \equiv \Omega + \omega$: longitude of pericenter
$t_p$: time of periastron passage
$t_0$: reference epoch
$\mathcal{M} \equiv n_b \left(t - t_p\right)$: mean anomaly
$\eta \equiv n_b \left(t_0 - t_p\right)$: mean anomaly at epoch
$\lambda \equiv \sigma + \mathcal{M}$: mean longitude
$\epsilon$: mean longitude at epoch
$f$: true anomaly
$u \equiv \omega + f$: argument of latitude
$\hat{l} \equiv [\cos \Omega, \sin \Omega, 0]$: unit vector directed along the line of the nodes toward the ascending node
$\hat{m} \equiv [-\cos I \sin \Omega, \cos I \cos \Omega, \sin I]$: unit vector directed transversely to the line of the nodes in the orbital plane
$r$: magnitude of the binary’s relative position vector
$\hat{\rho} \equiv r^{-1} \hat{l} \cos u + \hat{m} \sin u$: radial unit vector
$\hat{v} \equiv [\sin I \sin \Omega, -\sin I \cos \Omega, \cos I]$: unit vector of the orbital angular momentum
$\hat{\sigma} \equiv \hat{v} \times \hat{\rho}$: transverse unit vector
$A$: disturbing acceleration
$A_\rho = A \cdot \hat{\rho}$: radial component of $A$
$A_\sigma = A \cdot \hat{\sigma}$: transverse component of $A$
$A_n = A \cdot \hat{n}$: normal component of $A$
$\delta t_p$: periodic variation of the time of arrivals of the pulses from the pulsar p due to its barycentric orbital motion

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