Construction of Concrete Surface Crack Recognition Model Based on Digital Image Processing Technology

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Abstract. In this paper, the bridge crack detection method based on digital images is studied. In-depth analysis and evaluation are performed on the image processing algorithms such as image graying, resolution of checkerboard corner pixel rate, filtering denoising, and edge detection, etc. The calculation and software system for bridge crack width based on videos (or images) is implemented, and 15 bridge crack images are used to verify its crack detection accuracy. The results suggest that the proposed crack identification method in this paper can be used for the crack detection of reinforced concrete bridges and class B prestressed concrete bridges properly. When the crack width is greater than 0.3 mm, the calculated crack width value based on images is very close to the measured value.

Keywords: Concrete Bridge, Crack Detection, Digital Image, Computer Identification, Image Processing

1. Introduction

In the daily inspection, regular inspection of the concrete bridge and the crack detection at the bottom of the beam, the lifting engineer is usually used to send the bridge engineer to the bottom of the bridge beam, use the crack observer to read the crack width, and manually record the crack position, width, length, and other information [1-2]. The method is inefficient, time-consuming, difficult to grasp the most extensive position of cracks and is not suitable for the needs of the rapid development of modern bridges [3-4]. In recent years, some scholars have developed research on methods for identifying and detecting cracks in concrete members based on image analysis and processing technology. The segmentation algorithms are compared, and the crack width values in the image are obtained. The research focus is on image processing algorithms, and the lack of detection and verification of actual crack images. Some scholars have researched concrete crack detection methods for ordinary and oblique images. However, in the process of correcting and calibrating images it can easily distort the actual crack. The above techniques all use image processing functions such as MATLAB to implement crack image processing [5-6]. Bridge cracks are extracted by threshold segmentation. If there are pores, honeycombs, peeling, etc. on the concrete surface, the separated image still has local noise, which affects the crack identification Identify.
This paper proposes the concept of bridge crack detection based on digital images. A checkerboard calibration board is pasted on the bridge surface. The bridge video is captured with a camera, and the bridge crack image is extracted in the video frame. The program is compiled with Visual C++ 6.0 language to image grayscale. Based on systematic analysis and comparison of image processing algorithms such as filtering, filtering denoising, and edge detection, a processing algorithm suitable for bridge crack images is determined. On this basis, this paper studies the checkerboard corner method to solve the pixel rate of the image (The actual length of the image), use an improved smoothing filter to remove noise from the image, use edge detection algorithms to identify the contour of the crack, and then fit the crack edge line to calculate the perimeter, area, and width of the crack. In addition, based on oblique photography The key to bridge crack detection in video images is how to solve the pixel rate in the crack image. The author will discuss it in another article.

2. Bridge crack image processing techniques

2.1. Image Graying
This paper uses equation (1) to convert the RGB image into a grayscale image:

\[ x = 0.30 \times R + 0.59 \times G + 0.11 \times B \]  

(1)

Where x is the pixel rate value of the grayscale image; R, G, and B are the red, green, and blue component values of the pixel rate in the true-color image, respectively.

2.2. Gray Conversion
The grayscale conversion of crack images can improve the quality of the image and enhance the grayscale of the image. The commonly used grayscale conversion methods are linear conversion and histogram conversion. This paper uses Equation (2) for linear conversion. The effect of image conversion is shown in Figure 1.

\[
g(x) = \begin{cases} 
0, & x = T_{\text{min}} \\
\frac{(x - T_{\text{min}}) \times 255}{(T_{\text{max}} - T_{\text{min}})}, & T_{\text{min}} < x < T_{\text{max}} \\
255, & x = T_{\text{max}}
\end{cases}
\]  

(2)

Where \( g(x) \) is the converted grayscale pixel rate value; and \( T_{\text{min}} \) and \( T_{\text{max}} \) are the minimum and maximum grayscale values in the image, respectively.

Figure 2 shows that the linear transformation better preserves the bridge crack details, further opening up the difference in gray values between the crack and the background, which is conducive to subsequent image processing and crack identification. Histogram conversion makes the gray
distribution of the entire image more uniform. However, the gray value and crack width of the crack area in the image is deepened, which may cause a more significant error between the calculated crack width value and the actual value. Hence, linear grayscale conversion can better handle the bridge crack image.

2.3. Resolution of Image Pixel Rate

To meet the requirements of bridge crack identification, the checkerboard corner method is used to calculate the pixel rate of the image. The image plane coordinate values of the checkerboard corner points (except the edge points) are calculated, and the pixel rate of the bridge crack image is calculated. The calculation equation is as follows: (3) shown:

$$\eta = \frac{D_1}{D_2}$$

(3)

Where \( \eta \) is the pixel rate (mm / pixel rate) of the image; \( D_1 \) is the actual distance (mm) between the two corner points in the checkerboard; \( D_2 \) is the pixel rate distance (pixel rates) between the two corner points in the checkerboard.

Currently, checkerboard corner detection can be divided into two types: straight line detection and corner detection. The straight line detection method first performs edge detection on the image, finds the straight line in the image, and finds the pixel rates of the checkerboard corner point by the intersection of the two straight lines. The coordinate corner detection method is based on the image gray detection method, which considers the gray value changes of pixel rates in the pixel rate area.

2.4. Image Filtering Denoising

Image filtering must effectively filter out noise in bridge crack images on the one hand, and effectively protect crack information on the other hand, and minimize blurring of crack edges during filtering to facilitate subsequent crack edge detection. This article uses actual bridge crack images as For the test object, several commonly used image filtering methods were systematically analyzed, and the average pixel rate deviation was used to evaluate the filtering effect of each algorithm.

1) Image Filtering Algorithm

Commonly used image filtering algorithms include smoothing filtering, median filtering, and mean filtering. In this paper, multiple bridge crack image filtering is used to improve the smoothing filtering, and a filtering method combining median and mean is studied.

The improved smoothing filter increases the gray value of a pixel point in a grayscale image to 4 times, the gray value of 4-pixel rates in adjacent top, bottom, left, and right to 2 times and the adjacent 4-pixel rates in the diagonal The gray value of the point is unchanged, then the gray values of 9-pixel rates are added and divided by 16 as the new gray value of the pixel rate.

The median and mean are filtered together, assuming that the gray value distribution of the pixel rates in the bridge crack image follows the normal distribution of \( F \sim N (\mu, \sigma^2) \). If the gray value of the image point is in \([\mu - 2\sigma, \mu + 2\sigma]\), Mean filtering is used; if the gray value of the image point is outside \([\mu - 2\sigma, \mu + 2\sigma]\), median filtering is used. The parameter \( \mu, \sigma \) can be calculated using the gray value of the pixel rate:

$$\mu = \frac{1}{N} \sum_{i=1}^{N} x_i$$

(4)

$$\sigma = \sqrt{\frac{1}{N} \sum_{i=1}^{N} (x_i - \mu)^2}$$

(5)

Where \( N \) is the total number of pixel rates in the bridge crack image; is the gray value of a pixel rate.
2) Filtering Effect Evaluation

To evaluate the effect of various filtering algorithms on bridge crack images, the average pixel rate deviation evaluation method is adopted. Firstly, a noise with an average pixel rate deviation of 14.4957 is added to the original bridge crack grayscale image. Subsequently, different methods are used for filtering, and the filtering effects are shown in Figure 2.

![Grayscale diagram of bridge cracks](image1.png)
![Additional noise map](image2.png)
![Improved smoothing filtering](image3.png)
![5×5 median filtering](image4.png)
![Mean filtering](image5.png)
![Filtering combining median and mean](image6.png)

**Figure 2.** Filtering effects of different algorithms

The filtered crack image is compared with the original grayscale image (that is, the grayscale image before noise is added). The smaller the average deviation of the grayscale value of the pixel rate, the better the filtering effect. The evaluation equation is as follows:

\[
D(x_i) = |P(x_i) - M(x_i)|
\]  

(6)

\[
A = \frac{1}{n} \sum_{i=1}^{n} D(x_i) / N
\]

(7)

Where \(P(x_i)\) is the gray value of a pixel rate in the original gray map of the bridge crack; \(M(x_i)\) is the gray value of the corresponding pixel rate in the filtered image; \(D(x_i)\) is the Gray value difference; \(A\) is the average pixel rate deviation of the entire image.

After calculation, the average pixel rate deviation corresponding to various filtering methods is obtained, as shown in Table 1.
Table 1. Mean pixel rate deviation corresponding to various filtering methods

| Filtering method | Additional noise | Improved smoothing filtering | Median smoothing filtering | Mean filtering | Median and mean |
|------------------|------------------|------------------------------|---------------------------|---------------|-----------------|
| Mean pixel rate deviation | 14.4957 | 6.72764 | 7.17565 | 7.34539 | 14.1566 |
| Filtering rate /% | - | 53.59 | 50.50 | 49.33 | 2.34 |

Figure 2 and Table 1 show that the filtering denoising of bridge crack images is very necessary. The improved smoothing filtering algorithm has the most apparent filtering effect on the grayscale images of bridge cracks. The median filtering can effectively protect the edges of the image, the mean filtering makes the bridge cracks blurred, and the filtering method combining the median and the mean has a poor filtering effect and is not suitable for the filtering of bridge crack images.

3. Bridge crack calculation

After processing the bridge crack image, information such as the pixel rate width, pixel rate perimeter, and pixel rate area of the crack can be calculated. The crack pixel rate perimeter can be obtained by counting the distance between adjacent edge points of the crack in the image, and the crack pixel rate area can be calculated by statistical. Obtain the pixel rates contained in the edge line of the middle crack, and then obtain the actual perimeter and area of the crack through the pixel rate. The crack width is an essential indicator for bridge detection and evaluation and cannot be directly obtained by counting the statistical pixel rates. This article focuses on the study of the crack width. Calculation (maximum crack width).

Under normal circumstances, the crack direction in the bridge crack image is an irregular curve. The processed bridge crack image is a pixel rate matrix of discrete points in m rows and n columns. The pixel rate width of the crack can be calculated by using the matrix and the relevant characteristics of the crack.

In the crack image pixel rate matrix, the pixel rate coordinates of any point can be expressed in the form (i, Z (i, k)), i = 1,2, ..., m; k = 1,2, ..., n. The pixel rate coordinates of the top edge detection point (i.e., the crack edge point) in column k are (i, Z (i, k)), and the pixel rate coordinates of the bottom edge detection point are (j, Z (j, k)). The following equation can be obtained.

Crack vertical pixel rate width \( P(k) \):

\[
P(k) = Z(i,k) - Z(j,k)
\]  \hspace{1cm} (8)

\[
M(k) = \frac{z(i,k) + z(j,k)}{2}, \text{crack inclination } \theta(k) \text{ can be obtained as follows}
\]

\[
\theta(k) = \arctan\left(\frac{M(k+1) - M(k-1)}{2}\right)
\]  \hspace{1cm} (9)

Pixel rate width \( W(k) \) of the crack:

\[
W(k) = P(k) \times \cos(\theta(k))
\]  \hspace{1cm} (10)

The maximum value is taken as the pixel rate width value of the bridge crack.

3) Calculation of Actual Crack Width

After the bridge crack pixel rate width \( \text{Max}(w(k)) \) is determined, the image pixel rate \( \eta \) obtained is calculated to obtain the actual bridge crack width \( W \) as follows:

\[
W = \eta \times \text{Max}(w(k))
\]  \hspace{1cm} (11)
4. Instance verification
Based on the above orthopedic video calculation method of concrete bridge cracks, using Visual C ++ 6.0 language programming, using a more reasonable crack image processing algorithm, to achieve bridge crack monitoring based on image technology. This paper takes actual bridge cracks as the test object, 15 bridge images taken by digital cameras were verified, and the crack width measured with a crack observer was compared with the experimental values.

The results suggest that the calculated crack width value is slightly larger than the measured value, and the error value is within 0.05mm. When the crack width is above 0.3mm, the calculated crack width value is very close to the measured width value, and the error is 6 Within the range of 0.2%; when the crack width is between 0.2 ~ 0.3mm, the error is within 10%. When the width of the crack is below 0.2mm, the relative error is greater than 30%, the main reason is that the actual measured crack value is read manually to judge the crack. The widest position depends on the experience and feeling of the inspector, it is difficult to determine the widest position of the crack, and the accuracy of the crack observer is 0.1mm, and the crack value calculated by the image is the maximum value of all cracks. It is stipulated in the Prestressed Concrete Bridges and Culverts Design Code (JTGD62-2004) that the full cross-section of the prestressed bridge under the short-term load effect combination and part of the prestressed class A (limited tensile stress) bridge under the long-term load combination Tensile stress is not allowed at the tensile edge, that is, vertical cracks are not allowed, and the maximum crack width allowed for reinforced concrete bridges and partially prestressed Class B (exceeding limit tensile stress) bridges under normal use conditions (class I or II ring The lower non-steel wire or steel strand prestress) is 0.2mm. The "Code for Conservation of Highway Bridge Conservation" (JTG111-2004) stipulates that vertical cracks in the beam body and longitudinal cracks in the beam body are not allowed for fully prestressed or partially prestressed Class A bridges. The maximum allowable width is 0.2mm, and the maximum permissible width of vertical cracks for reinforced concrete or partially prestressed Class B bridges is 0.25mm, and repair or reinforcement should be performed beyond this value. In summary, the crack identification method proposed in this paper is mainly used for reinforcing steel Crack detection of concrete bridges and Class B prestressed concrete bridges.

5. Conclusion
In this paper, the crack detection technology of concrete bridges based on videos is systematically studied to obtain the following conclusions: 1) The Visual C ++6.0 language is used to develop a program in this paper to compare the relevant algorithms of image processing techniques systematically and obtain the algorithm for bridge crack image processing. Based on instances, it is proved that the proposed bridge crack detection method can be applied to actual detection properly. 2) The pixel rate of bridge crack images is solved by the checkerboard corner calibration method, and the combined algorithm of Harris and SV can identify and calculate the image plane coordinates of corner points accurately to provide technical support for subsequent accurate fracture calculations.

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