On the automatic selection of the tuning parameter appearing in certain families of goodness-of-fit tests∗

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Abstract

The situation, common in the current literature, is that of a whole family of location-scale/scale invariant test statistics, indexed by a parameter $\lambda \in \Lambda$, is available to test the goodness of fit of $F$, the underlying distribution function of a set of independent real-valued random variables, to a location-scale/scale family of distribution functions. The power properties of the tests associated with the different statistics usually depend on the parameter $\lambda$, called the “tuning parameter”, which is the reason that its choice is crucial to obtain a performing test procedure. In this paper, we address the automatic selection of the tuning parameter when $\Lambda$ is finite, as well as the calibration of the associated goodness-of-fit test procedure. Examples of existing and new tuning parameter selectors are discussed, and the methodology presented of combining different test statistics into a single test procedure is applied to well known families of test statistics for normality and exponentiality. A simulation study is carried out to access the power of the different tests under consideration, and to compare them with the fixed tuning parameter procedure, usually recommended in the literature.

Keywords: goodness-of-fit tests; data-based tuning parameter selection; calibration; normality tests; empirical characteristic function; exponentiality tests; empirical Laplace transform.

AMS 2010 subject classifications: 62G10; 62G20
1 Introduction

Given a sample \(X_1, \ldots, X_n\) of independent and identically distributed real-valued random variables from a distribution function \(F\), assume that \(T_{n,\lambda} = T_{n,\lambda}(X_1, \ldots, X_n)\), for \(\lambda \in \Lambda\), is a finite family of statistics for testing the hypothesis

\[
H_0 : F \in \mathcal{F},
\]

against a general alternative hypothesis, where \(\mathcal{F}\) is either a location-scale family,

\[
\mathcal{F} = \{F_0((\cdot - b)/a) : a > 0, b \in \mathbb{R}\}
\]
or a scale family of distribution functions,

\[
\mathcal{F} = \{F_0(\cdot/a) : a > 0\},
\]

with \(F_0\) a known distribution function on \(\mathbb{R}\). If the test statistics \(T_{n,\lambda}\) are location-scale invariant in case (2), that is, \(T_{n,\lambda}(\nu X_1 + \mu, \ldots, \nu X_n + \mu) = T_{n,\lambda}(X_1, \ldots, X_n)\), for each \(\nu > 0\) and \(\mu \in \mathbb{R}\), or scale invariant in case (3), that is, \(T_{n,\lambda}(\nu X_1, \ldots, \nu X_n) = T_{n,\lambda}(X_1, \ldots, X_n)\), for each \(\nu > 0\), the distribution of \(T_{n,\lambda}\) under \(H_0\) does not depend on \(F\). Therefore, if large values of \(T_{n,\lambda}\) are significant, each one of the tests with critical regions \(\{T_{n,\lambda}(X_1, \ldots, X_n) > c_{n,\lambda}(\alpha)\}\), has a level of significance at most equal to \(\alpha\), that is, \(P_F(T_{n,\lambda}(X_1, \ldots, X_n) > c_{n,\lambda}(\alpha)) \leq \alpha\), for all \(F \in \mathcal{F}\), where \(\alpha \in [0,1]\), and \(c_{n,\lambda}(\alpha) = F_{T_{n,\lambda}}^{-1}(1 - \alpha)\) denotes the quantile of order \(1 - \alpha\) of \(T_{n,\lambda}\) under \(H_0\). Of course, if the distribution functions of all \(T_{n,\lambda}\) under \(H_0\), are continuous on \(\mathbb{R}\), the test procedures associated with the previous critical regions have a level of significance exactly equal to \(\alpha\). The power properties of the previous test procedures usually depend on the parameter \(\lambda\) which is the reason that its choice is crucial to obtain a performing test procedure.

The previous situation, where a finite family of test statistics is available for testing the hypothesis \(H_0\), is now common in the current literature as evidenced by the works of Epps and Pulley (1983), Baringhaus and Henze (1991), Henze (1993), Güntler and Henze (2000), Klar (2001), Henze and Meintanis (2002), Meintanis (2004, 2004a), and Meintanis et al. (2014), where goodness-of-fit tests for the normal, exponential, Cauchy, Laplace, or logistic distributions, based on the empirical characteristic function, the probability weighted characteristic function, the integrated empirical distribution function or the Laplace transform, are proposed (for related work, see also Henze and Zirkler, 1990, Fun, 1998, Tenreiro, 2005, 2007). In all these situations the test statistics \(T_{n,\lambda}, \lambda \in \Lambda\), are either location-scale invariant in case (2) or scale invariant in case (3). More precisely, they can be written in the form \(T_{n,\lambda}(X_1, \ldots, X_n) = T_{n,\lambda}(Y_1, \ldots, Y_n)\) with

\[
(Y_1, \ldots, Y_n) = g(X_1, \ldots, X_n),
\]

where \(g\) is a known function given by \(g(X_1, \ldots, X_n) = (X_1 - \hat{b}_n/\hat{a}_n, \ldots, X_n - \hat{b}_n/\hat{a}_n)\), in case (2), and by \(g(X_1, \ldots, X_n) = (\frac{X_1}{\hat{a}_n}, \ldots, \frac{X_n}{\hat{a}_n})\), in case (3), where \(\hat{a}_n = \hat{a}_n(X_1, \ldots, X_n)\) is a location invariant and scale equivariant estimator of the scale parameter \(a\), i.e., \(\hat{a}_n(\nu X_1 + \mu, \ldots, \nu X_n + \mu) = \)
Therefore the Epps-Pulley test statistic is given by
\[ T_n, \lambda = n \int_{\mathbb{R}} |\varphi_n(t) - \varphi(t)|^2 \exp(-\lambda^2 t^2)dt = 2\pi \frac{1}{n} \sum_{i,j=1}^{n} Q(Y_i, Y_j; \lambda), \] (5)
with \( Q(u, v; \lambda) = \phi(2\lambda^2)^{1/2}(u - v) - \phi(1 + 2\lambda^2)^{1/2}(u) - \phi(1 + 2\lambda^2)^{1/2}(v) + \phi(2 + 2\lambda^2)^{1/2}(0) \), for \( u, v \in \mathbb{R} \), \( \lambda \in [0, +\infty[ \), and \( \phi_n(\cdot) = \phi(\cdot/h)/h \), \( h > 0 \). The simplicity of the previous expression shows the attractive feature of the considered weight function (see Henze and Zirkler, 1990, and Fan, 1998, for the relation between the Epps-Pulley test statistic and the Bickel-Rosenblatt test statistic). From a practical point of view, it is well known that the finite sample performance of the Epps-Pulley test is very sensitive to the choice of \( \lambda \). Choosing a small value of \( \lambda \), which means letting the weight function decay slowly, will produce a test sensitive to short tailed or high moment alternatives, whereas large values of \( \lambda \), which means putting most of the mass of the weight function near zero, are adequate for detecting alternative distributions with long tails, symmetric or asymmetric (cf. Tenreiro, 2009). Note that for large values of \( \lambda \) the considered weight function puts most of its mass near the origin, and then, the previous behaviour can be seen as a consequence of the fact that the tail behaviour of a probability distribution is reflected by the behaviour of its characteristic function at the origin (cf. Kawata, 1972, pp. 419–420).

The exponentiality tests introduced in Henze and Meintanis (2002), is another example where a whole family of test statistics is available to the user. In this case the test statistics are based on a weighted \( L_2 \)-distance between the empirical Laplace transform of the scaled data \( Y_j = X_j/\hat{\lambda} \), \( j = 1, \ldots, n \), defined by \( \psi_n(t) = \frac{1}{n} \sum_{j=1}^{n} \exp(-tY_j) \), \( t \geq 0 \), and the Laplace transform of the unit exponential distribution \( \psi(t) = 1/(1 + t) \), \( t \geq 0 \), with weight function \( t \mapsto (1 + t^2) \exp(-\lambda t) \), for \( \lambda > 0 \). Thus, the Henze-Meintanis test statistic is given by
\[ T_{n, \lambda} = n \int_{0}^{\infty} \left( \psi_n(t) - \psi(t) \right)^2 (1 + t)^2 \exp(-\lambda t)dt \]
\[ = \frac{1}{n} \sum_{j,k=1}^{n} \frac{1 + (Y_j + Y_k + \lambda + 1)^2}{(Y_j + Y_k + \lambda)^3} - 2 \sum_{j=1}^{n} \frac{1 + Y_j + \lambda}{(Y_j + \lambda)^2} + \frac{n}{\lambda}, \] (6)
for \( \lambda \in [0, +\infty[ \). As the Epps-Pulley test for normality, the Henze-Meintanis test for exponentiality is very sensitive to the choice of \( \lambda \). As remarked by Baringhaus and Henze (1991, p. 552) (see
also Henze and Meintanis, 2002, p. 148), from Tauberian theorems on Laplace transform (cf. Feller, 1971, Chapter XIII.5), it is known that the tail behaviour of a probability distribution concentrated on $[0, \infty[$ is reflected by the behaviour of its Laplace transform at zero and vice versa. Therefore, choosing a small value of $\lambda$, which means letting the weight function decay slowly, gives high power against alternative distributions having a point mass or infinite density at zero, and a large value of $\lambda$ means putting most of the mass of the weight function near zero, which should give high power against alternatives that greatly differ in tail behaviour with respect to the exponential distribution.

As illustrated by the previous examples, the parameter $\lambda$ acts as a tuning parameter, through which the user can increase the power of the test toward some particular direction along the alternative distribution set. However, as the formulation of a specific alternative hypothesis is, in general, impossible in a real situation, the usual practice is to evaluate the test power performance for $\lambda$ varying in a finite set $\Lambda$, and then suggesting a selection of $\lambda$ that produces a test with a reasonable power against a wide range of alternative distributions. However, this strategy of taking a fixed tuning parameter does not prevent the user from obtaining a test that achieves a very low power against some of the considered alternative distributions (cf. Henze and Meintanis, 2002).

Some efforts have been made in order to combine, based on the available data, test procedures associated to different values of the tuning parameter $\lambda$ into a single test procedure that could show a good power performance against a wide range of alternative distributions. This was the case of the multiple test approach, considered in Klar (2001), Fromont and Laurent (2006) and Tenreiro (2011, 2017), which can be viewed as an improvement of the classical Bonferroni multiple test procedure. The proposed test leads to the rejection of the null hypothesis if one of the statistics $T_{n,\lambda}$, for $\lambda \in \Lambda$, is larger than its $(1-u)$ quantile under the null hypothesis, the level $u$ being calibrated so that the resulting multiple test has a level of significance at most equal to $\alpha$. Thus, the associated critical region is given by

$$\left\{ \max_{\lambda \in \Lambda} \left( T_{n,\lambda} - c_{n,\lambda}(u) \right) > 0 \right\},$$

for some $u \in [0, 1[$. This testing procedure is closely related to the single-step $\min P$ multiple testing procedure based on minima of unadjusted $p$-values (cf. Dudoit and van der Lann, 2008, pp. 117–121). Unlike classical Bonferroni multiple, that can be obtained by taking $u = \alpha/|\Lambda|$, where $|\Lambda|$ denotes the cardinality of $\Lambda$, the previous rejection region takes into account the dependence structure among the test statistics $T_{n,\lambda}$ for $\lambda \in \Lambda$. As the previous critical region can be written as $\{ T_{n,\lambda_u} > c_{n,\lambda_u}(u) \}$, where

$$\lambda_u = \lambda_u(X_1, \ldots, X_n) = \arg \max_{\lambda \in \Lambda} \left( T_{n,\lambda}(X_1, \ldots, X_n) - c_{n,\lambda}(u) \right),$$

the previous multiple test procedure can be seen as a test based on a data-dependent procedure for selecting the tuning parameter $\lambda$: for a given sample of size $n$, one selects the value $\lambda$ in $\Lambda$ for which the test statistic $T_{n,\lambda}$ shows stronger evidence, at level $u$, against the null hypothesis.
More recently, Allison and Santana (2015) proposed an alternative data-dependent method, based on the bootstrap, for choosing the tuning parameter. They considered the test with critical region \( \{ T_{n,\lambda^*} > c_{n,\lambda^*}(\alpha) \} \), where \( \lambda^* = \lambda^*(X_1, \ldots, X_n) \) is obtained by maximizing the bootstrap power, that is,

\[
\lambda^* = \lambda^*(X_1, \ldots, X_n) = \arg \max_{\lambda \in \Lambda} \frac{1}{B} \sum_{k=1}^{B} I(T_{n,\lambda}(Y^*_k, \ldots, Y^*_n) > c_{n,\lambda}(\alpha)),
\]

where \((Y^*_k, \ldots, Y^*_n)\) is a bootstrap random sample of size \(n\) drawn with replacement from the empirical distribution function of the transformed sample \((Y_1, \ldots, Y_n)\) defined by (4), \(B \in \mathbb{N}\) is the considered number of bootstrap samples, and \(I(A)\) denotes the indicator function of the set \(A\). Unfortunately, the proposed method presents two important drawbacks. Firstly, the suggested bootstrap procedure, as based on a bootstrap random sample drawn from the empirical distribution function of the transformed sample (4), and not from the empirical distribution function of the original sample, does not always produce a good approximation for the power associated with the distribution of the observations. Secondly, by using the quantiles of order \(1 - \alpha\) of each one of the test statistics \(T_{n,\lambda}\) to define the critical region, the proposed test is not correctly calibrated and may reach a level of significance much bigger than \(\alpha\) (see Section 4, Figure 1). In order to overcome these problems, we consider in this paper the test with critical region \(\{ T_{n,\hat{\lambda}_u} > c_{n,\hat{\lambda}_u}(u) \}\), for \(u \in ]0, 1]\), where the modified tuning parameter selector \(\hat{\lambda}_u\), is defined by

\[
\hat{\lambda}_u(X_1, \ldots, X_n) = \arg \max_{\lambda \in \Lambda} \frac{1}{B} \sum_{k=1}^{B} I(T_{n,\lambda}(X^*_k, \ldots, X^*_n) > c_{n,\lambda}(u)), \tag{9}
\]

with \(X^*_k = X^{U_{(k-1)n+j}}, k = 1, \ldots, B\) and \(j = 1, \ldots, n\), where \(U_l\), for \(l = 1, \ldots, nB\), are independent copies of the discrete uniform distribution on \(\{1, \ldots, n\}\), and \(u\) is calibrated so that the test has a level of significance at most equal to \(\alpha\). Although not assumed or discussed in this paper, if, for \(B\) and \(n\) large enough, the mean in (9) gives a good approximation for the probability \(P_F(T_{n,\lambda}(X_1, \ldots, X_n) > c_{n,\lambda}(u))\), we might expect that \(\hat{\lambda}_u\) mimics the behaviour of the ideal tuning parameter

\[
\lambda_u(F) = \arg \max_{\lambda \in \Lambda} P_F(T_{n,\lambda}(X_1, \ldots, X_n) > c_{n,\lambda}(u)), \tag{10}
\]

this being the main motivation for the previous definition of \(\hat{\lambda}_u\). As \(\hat{\lambda}_u\) depends on \(U = (U_l, l = 1, \ldots, nB) \in \{1, \ldots, n\}^{nB}\), any statement on this tuning parameter selector should always be interpreted conditionally on \(U\). However, by the law of large numbers, different choices of \(U\), essentially lead to tuning parameter selectors with similar behaviours.

The paper is organised as follows. Sections 2 and 3 deal with the calibration and the consistency of the tests with critical region \(\{ T_{n,\lambda_u} > c_{n,\lambda_u}(u) \}\), where \(\hat{\lambda}_u = \hat{\lambda}_u(X_1, \ldots, X_n)\) is a general family of measurable functions, indexed by \(u \in ]0, 1]\), taking values in \(\Lambda\), which are either location-scale invariant in case (2) or scale invariant in case (3). The cases of the tuning parameter
selectors $\tilde{\lambda}_u$ and $\tilde{\lambda}_u$, defined by (8) and (9), respectively, are analysed in detail. In Sections 4 and 5 we will restrict our attention to the cases where $T_{n,\lambda}$ is either the test statistic for normality of Epps and Pulley (1983), or the test statistic for exponentiality of Henze and Meintanis (2002). We conclude that the proposed calibration procedure is effective, and, as a result of a simulation study, we deduce that the tests based on $\tilde{\lambda}_u$ and $\tilde{\lambda}_u$ are serious competitors for the tests based on a fixed tuning parameter usually recommended in the literature, and perhaps should be employed in practice, in the absence of any information about the type of deviation from the null model. All the proofs and some auxiliary results are deferred to Section 8. The simulations and plots in this article were carried out using the R software (R Core Team, 2014).

2 The calibration procedure

In this section we will denote by $T_{n,\lambda}$, for $\lambda \in \Lambda$, a finite family of test statistics for testing the hypothesis (1), whose large values are considered significant. We will also assume that such test statistics are either location-scale invariant in case (2) or scale invariant in case (3). This assumption enables us to consider that the quantiles of order $1 - u$ of $T_{n,\lambda}$ under $H_0$, denoted, as before, by $c_{n,\lambda}(u) = F_{T_{n,\lambda}}^{-1}(1-u)$, are known quantities as they can be approximated by performing Monte Carlo experiments under the null hypothesis.

Given a general invariant tuning parameter selector $\check{\lambda}_u = \check{\lambda}_u(X_1, \ldots, X_n)$, that is, a family of measurable functions indexed by $u \in [0, 1]$, taking values in $\Lambda$, which are either location-scale invariant in case (2) or scale invariant in case (3), we have

$$\{T_{n,\check{\lambda}_u} > c_{n,\check{\lambda}_u}(u)\} \subset \left\{ \max_{\lambda \in \Lambda} (T_{n,\lambda} - c_{n,\lambda}(u)) > 0 \right\} = \bigcup_{\lambda \in \Lambda} \{T_{n,\lambda} > c_{n,\lambda}(u)\}, \quad (11)$$

from which we conclude that it is always possible to choose $u \in [0, 1]$ such that the test with critical region $\{T_{n,\check{\lambda}_u} > c_{n,\check{\lambda}_u}(u)\}$, has a level of significance at most equal to the nominal level $\alpha$:

**Theorem 1.** Given an invariant tuning parameter selector $\check{\lambda}_u$, and $\alpha \in [0, 1]$, then for all $0 < u \leq \alpha/|\Lambda|$, we have

$$P_F(T_{n,\check{\lambda}_u} > c_{n,\check{\lambda}_u}(u)) \leq \alpha, \quad \text{for all } F \in \mathcal{F},$$

where the probability $P_F(T_{n,\check{\lambda}_u} > c_{n,\check{\lambda}_u}(u))$, we denote by $\psi_\lambda(u)$, is independent of $F$, for $F \in \mathcal{F}$.

Note that the previous assumptions are fulfilled by the tuning parameter selector $\check{\lambda}_u$ given by (8), and, conditionally on $U = (U_l, l = 1, \ldots, nB)$, by $\check{\lambda}_u$ defined by (9).

2.1 A first calibration stage

Although important, as it assures that the Type I error of the test with critical region $\{T_{n,\check{\lambda}_u} > c_{n,\check{\lambda}_u}(u)\}$, may be put under a preassigned level of significance $\alpha$ through an appropriate choice of $u$, Theorem 1 does not provide a criterium for such a choice. Taking into account that the
test should have a level of significance not only less than or equal to \( \alpha \) but also as close to \( \alpha \) as possible, the practical selection of \( u \) will be performed by considering a regular grid \( G_p = \{ u_k, k \in I_p \} \) on the interval \([0, 1]\), where \( u_1 = p \), \( u_{k+1} = u_k + p \), for some \( 0 < p \leq \alpha/|\Lambda| \), and \( I_p = \{ k \in \mathbb{N} : kp < 1 \} \), and taking \( u = u_{n,\alpha,p}^\lambda \), where \( u_{n,\alpha,p}^\lambda \) is the largest value of \( G_p \) satisfying

\[
\psi_\lambda(u) := P_{F_0}(T_{n,\hat{\lambda}} > c_{n,\hat{\lambda}}(u)) \leq \alpha, \quad \text{that is},
\]

\[
u_{n,\alpha,p}^\lambda = \max\{ u \in G_p : \psi_\lambda(u) \leq \alpha \}.
\]  

(12)

We present in the next theorem a set of sufficient conditions on \( \psi_\lambda \) assuring that the test with critical region \( \{ T_{n,\hat{\lambda}} > c_{n,\hat{\lambda}}(u) \} \), for \( u = u_{n,\alpha,p}^\lambda \), has a level of significance as close to \( \alpha \) as possible, when \( p \) tends to zero.

**Theorem 2.** Given an invariant tuning parameter selector \( \hat{\lambda}_u \), let \( \alpha \in ]0,1[ \), and \( \nu_{n,\alpha,p}^\lambda \) given by (12). If \( \psi_\lambda \) is increasing on \([0,1]\), with \( \lim_{\alpha \uparrow 1} \psi_\lambda(u) = 1 \), we have \( \lim_{p \uparrow 0} \nu_{n,\alpha,p}^\lambda = \nu_{n,\alpha}^\lambda \), where

\[
u_{n,\alpha}^\lambda = \sup\{ u \in ]0,1[ : \psi_\lambda(u) \leq \alpha \},
\]

(13)

is such that \( \alpha/|\Lambda| \leq \nu_{n,\alpha}^\lambda < 1 \). Moreover, if \( \psi_\lambda \) is continuous on \([0,1]\[, we have

\[
\lim_{p \uparrow 0} \sup_{F \in \mathcal{F}} P_F(T_{n,\hat{\lambda}_u} > c_{n,\hat{\lambda}_u}(u_{p})) = \sup_{F \in \mathcal{F}} P_F(T_{n,\hat{\lambda}} > c_{n,\hat{\lambda}}(u)) = \alpha,
\]

where \( u_p \) and \( u \) stand for \( \nu_{n,\alpha,p}^\lambda \) and \( \nu_{n,\alpha}^\lambda \), respectively.

The previous general result allows us to present a set of sufficient conditions on the null distribution of the statistics \( T_{n,\lambda} \), weaker that those considered in Tenreiro (2011, Theorem 1), assuring that the test associated with the critical region \( \{ T_{n,\hat{\lambda}_u} > c_{n,\hat{\lambda}_u}(u) \} \), with \( \hat{\lambda}_u \) given by (8) and \( u = u_{n,\alpha,p}^\lambda \) given by (12), has a level of significance not only inferior, but also as close to \( \alpha \) as possible, when \( p \) tends to zero.

**Theorem 3.** If the distribution function of \( T_{n,\lambda} \) under \( H_0 \) is continuous, for all \( \lambda \in \Lambda \), then, for \( \alpha \in ]0,1[ \) we have

\[
\lim_{p \uparrow 0} \sup_{F \in \mathcal{F}} P_F(T_{n,\hat{\lambda}_u} > c_{n,\hat{\lambda}_u}(u_{p})) = \sup_{F \in \mathcal{F}} P_F(T_{n,\hat{\lambda}} > c_{n,\hat{\lambda}}(u)) = \alpha,
\]

where \( u_p \) and \( u \) stand for \( \nu_{n,\alpha,p}^\lambda \) and \( \nu_{n,\alpha}^\lambda \) given by (12) and (13), respectively, with \( \alpha/|\Lambda| \leq \nu_{n,\alpha}^\lambda < \alpha \).

### 2.2 A second calibration stage

Under the assumptions of Theorem 3 on the null distribution of the statistics \( T_{n,\lambda} \), it can be proved that \( \lim_{\alpha \uparrow 1} \psi_\lambda(u) = 1 \), for any invariant tuning parameter selector \( \hat{\lambda}_u \) (see Section 8, Proposition 1). However, the same set of assumptions does not necessarily assure that \( \psi_\lambda \) is increasing and continuous on \([0,1]\]. Therefore, under the assumptions of Theorem 3 the test with critical region
\{T_{n,\hat{\lambda}} > c_{n,\hat{\lambda}}(u)\}, \text{ with } u = u_{n,\alpha,p}^{\hat{\lambda}} \text{ given by (12), has a level of significance no bigger than } \alpha, \text{ but we cannot affirm that its level of significance becomes as close to } \alpha \text{ as possible, when } p \text{ tends to zero. Next, we will see that this goal can be achieved if a second calibration stage is performed.}

For a fixed \(u \in ]0, 1[\), consider the family of critical regions \(\{T_{n,\lambda} > c_{n,\hat{\lambda}}(v)\}\), indexed by \(v \in ]0, 1[\). Although it is natural to take for \(u\) the value \(u_{n,\alpha,p}^{\hat{\lambda}}\) obtained in the first calibration stage, this is not assumed in what follows. Define

\[
v_{n,\alpha,q}^{\hat{\lambda}} = \max\{v \in G_q : \psi_{\lambda}^{\hat{\lambda}}(v) \leq \alpha\},
\]

where \(\psi_{\lambda}^{\hat{\lambda}}\) is given by \(\psi_{\lambda}^{\hat{\lambda}}(v) := P_{F_0}(T_{n,\hat{\lambda}} > c_{n,\hat{\lambda}}(v))\), \(G_q = \{v_k, k \in I_q\}\), is a regular grid on the interval \(]0, 1[\), with \(v_1 = q, v_{k+1} = v_k + q\), for some \(0 < q < u\), and \(I_q = \{k \in \mathbb{N} : kq < 1\}\).

**Theorem 4.** Given an invariant tuning parameter selector \(\hat{\lambda}_u\), where \(u\) is assumed to be fixed in \(]0, 1[\), if the distribution function of \(T_{n,\lambda}\) under \(H_0\) is continuous and strictly increasing (on the set \(\{t \in \mathbb{R} : 0 < F_{T_{n,\lambda}}(t) < 1\}\)), for all \(\lambda \in \Lambda\), then, for \(\alpha \in ]0, 1[\), we have \(\lim_{q \downarrow 0} v_{n,\alpha,q}^{\hat{\lambda}_u} = v_{n,\alpha,\hat{\lambda}_u}\), where

\[
v_{n,\alpha,q}^{\hat{\lambda}_u} = \sup\{v \in ]0, 1[ : \psi_{\lambda}^{\hat{\lambda}_u}(v) \leq \alpha\},
\]

is such that \(\max(u, \alpha/|\Lambda|) \leq v_{n,\alpha}^{\hat{\lambda}_u} < 1\), whenever \(\psi_{\lambda}^{\hat{\lambda}_u}(u) \leq \alpha\), and \(\alpha/|\Lambda| \leq v_{n,\alpha}^{\hat{\lambda}_u} \leq u\), whenever \(\psi_{\lambda}^{\hat{\lambda}_u}(u) > \alpha\). Moreover, we have

\[
\lim_{q \downarrow 0} \sup_{F \in F} P_F(T_{n,\hat{\lambda}_u} > c_{n,\hat{\lambda}_u}(v_{n,q})) = \sup_{F \in F} P_F(T_{n,\hat{\lambda}_u} > c_{n,\hat{\lambda}_u}(v_u)) = \alpha,
\]

where \(v_{n,q}\) and \(v_u\) stand for \(v_{n,\alpha,q}^{\hat{\lambda}_u}\) and \(v_{n,\alpha,\hat{\lambda}_u}\), respectively.

This general result gives us a set of sufficient conditions on the null distribution of the statistics \(T_{n,\lambda}\), assuming that, conditionally on \(U = (U_l, l = 1, \ldots, nB)\), the test with critical region \(\{T_{n,\lambda} > c_{n,\hat{\lambda}_u}(v_u)\}\), with \(u = u_{n,\alpha,p}^{\hat{\lambda}}\) and \(v_u = v_{n,\alpha,q}^{\hat{\lambda}_u}\) given by (12) and (14), respectively, has a level of significance not only less than or equal but also as close to \(\alpha\) as possible, when \(q\) tends to zero.

### 3 Consistency against fixed alternatives

Under some general assumptions, the test procedures considered in the previous section detect an alternative \(F \notin \mathcal{F}\), if such an alternative is detected by all the test statistics \(T_{n,\lambda}\), for \(\lambda \in \Lambda\). Next we will restrict our attention to the tests that use a single calibration stage. However, similar results can be derived for the test procedures considered in subsection 2.2, where a second calibration stage is used.

**Theorem 5.** Under the conditions of Theorem 2, let \(F \notin \mathcal{F}\), and assume that \(T_{n,\lambda} \xrightarrow{p} +\infty\), under \(F\), for all \(\lambda \in \Lambda\). If \(T_{n,\lambda} \xrightarrow{d} T_{\infty,\lambda}\), under \(H_0\), with \(F_{T_{\infty,\lambda}}\) strictly increasing (on the set \(\{t \in \mathbb{R} : 0 < F_{T_{\infty,\lambda}}(t) < 1\}\)), for all \(\lambda \in \Lambda\), then

\[
P_F(T_{n,\lambda} > c_{n,\hat{\lambda}}(u)) \longrightarrow 1, \text{ as } n \rightarrow \infty,
\]
where \( u \) stands for \( u_{n,\alpha}^{\lambda} \) given by (13).

In the particular case of the tuning parameter selector \( \tilde{\lambda}_u \) given by (8), it is interesting to note that the previous consistency result may be obtained under weaker assumptions. In fact, the test with critical region \( \{ T_{n,\tilde{\lambda}_u} > c_{n,\tilde{\lambda}_u}(u) \} \), with \( u = u_{n,\alpha}^{\lambda} \), detects any alternative \( F \notin \mathcal{F} \) that is detected by at least one of the tests based on \( T_{n,\lambda} \), for \( \lambda \in \Lambda \). This attractive property of the tuning parameter selector \( \tilde{\lambda}_u \) is stated in the following result.

**Theorem 6.** Under the conditions of Theorem 3, let \( F \notin \mathcal{F} \), and assume there exists \( \lambda \in \Lambda \) such that \( T_{n,\lambda} \overset{P}{\to} +\infty \), under \( F \). If \( T_{n,\lambda} \overset{d}{\to} T_{\infty,\lambda} \), under \( H_0 \), where \( F_{T_{\infty,\lambda}} \) is strictly increasing (on the set \( \{ t \in \mathbb{R} : 0 < F_{T_{\infty,\lambda}}(t) < 1 \} \)), then

\[
P_F(T_{n,\tilde{\lambda}_u} > c_{n,\tilde{\lambda}_u}(u)) \to 1, \text{ as } n \to \infty,
\]

where \( u \) stands for \( u_{n,\alpha}^{\lambda} \) given by (13).

### 4 Combining the EP and HM test statistics

In this and the following section we will restrict our attention to the families of test statistics of Epps and Pulley (1983) and of Henze and Meintanis (2002), given by (5) and (6), respectively (henceforth denoted by EP and HM). In the former case, the parametric family \( \mathcal{F} \) is given by (2), with \( F_0 \) the distribution function of the standard Gaussian distribution, whereas in the latter it is given by (3), with \( F_0 \) the distribution function of the unit exponential distribution. We start by showing that both test statistic families satisfy the assumptions of Theorems 3 and 4 stated in the previous section.

**Theorem 7.** The null distribution functions of the EP test statistics (for \( n \geq 3 \)), and of the HM test statistics (for \( n \geq 2 \)), are continuous and strictly increasing (on the set \( \{ t \in \mathbb{R} : 0 < F_{T_{n,\lambda}}(t) < 1 \} \)), for all \( \lambda \in [0, +\infty[ \).

Taking into account Theorems 3 and 4, the previous result enables us to conclude that, either for the EP test statistic family (\( n \geq 3 \)), or for the HM test statistic family (\( n \geq 2 \), the test with critical region \( \{ T_{n,\tilde{\lambda}_u} > c_{n,\tilde{\lambda}_u}(u) \} \), with \( \tilde{\lambda}_u \) given by (8) and \( u = u_{n,\alpha}^{\lambda} \) given by (13), has an exact \( \alpha \) level of significance. The same is true for the test with critical region \( \{ T_{n,\lambda_{up}} > c_{n,\lambda_{up}}(v_{up}) \} \), with \( \lambda_u, u_p = u_{n,\alpha,p}^{\lambda}, \) and \( v_{up} = v_{n,\alpha,p}^{\lambda} \), given by (9), (12), and (14), respectively. Moreover, from the results presented in Section 3, and those of Baringhaus and Henze (1988, Theorems 3 and 4), and Henze and Meintanis (2002, Theorems 2.3 and 2.7), we deduce that the previous tests are consistent against each nondegenerated non-normal distribution with finite variance, when \( T_{n,\lambda}, \lambda \in \Lambda \), is the EP test statistic family, and they are consistent against each nonnegative non-exponential distribution not degenerated at zero, when \( T_{n,\lambda}, \lambda \in \Lambda \), is the HM test statistic family.
Figure 1: Estimates of $\hat{\psi}(u)$ and $\check{\psi}(u)$, for $u \in [0, 0.2]$ and $n = 50$, for the EP and HM test statistic families with $\Lambda = \{0.1, 0.25, 0.5, 0.75, 1, 1.5, 2, 2.5, 3.5, 5\}$. These plots describe the level of significance of the test procedures based on the tuning parameter selectors $\check{\lambda}_u$ and $\hat{\lambda}_u$, as a function of $u$.

In order to implement the previous test procedures in practice, where the values $u_{n,\alpha}$ and $v_{n,\alpha}$, are replaced by the approximations $u_{n,\alpha,p}$ and $v_{n,\alpha,q}$, respectively, the values $\check{\psi}(u)$, $\hat{\psi}(u)$ and $\check{\lambda}_{up}(v)$, with $u_p = u_{n,\alpha,p}$, need to be approximated by Monte Carlo experiments under the null hypothesis, for $u$ and $v$ varying on the regular grid $G_p = \{w_k, k \in \mathbb{I}_p\}$, on the interval $[0, 1]$, where $w_1 = p$ and $w_{k+1} = w_k + p$, for some $0 < p \leq \alpha/|\Lambda|$. For that, we use 100,000 simulations under the null hypothesis of the involved test statistics $T_{n,\lambda}$, $\lambda \in \Lambda$, and the R function `quantile(·, type=7)` for estimating the $1 - u$ quantiles $c_{n,\lambda}(u)$, for $u$ varying on $G_p$ with $p = 0.0001$. Further 100,000 simulations are used for estimating the probabilities $\check{\psi}(u)$, $\hat{\psi}(u)$ and $\check{\lambda}_{up}(v)$, for $u$ and $v$ varying on $G_p$. In the evaluation of $\check{\lambda}_u$, $B = 100$ bootstrap samples are used.

We always take $\Lambda = \{0.1, 0.25, 0.5, 0.75, 1, 1.5, 2, 2.5, 3.5, 5\}$, a set of tuning parameters that includes the range of values for $\lambda$ considered by Epps and Pulley (1983) and Henze and Meintanis (2002). Although the choice of the set $\Lambda$, of relevant values for the tuning parameter $\lambda$, may be based on some preliminary information, the previous set $\Lambda$ is meant for the most common situation in practice where no relevant information about the alternative hypothesis is available. For $n = 50$ we show in Figure 1 the graphics of the functions $\check{\psi}(u)$ and $\hat{\psi}(u)$, for $u \in [0, 0.2]$, that describe the estimated levels of significance of the test procedures based on the tuning parameter selectors $\check{\lambda}_u$ and $\hat{\lambda}_u$, respectively, as a function of $u$. As observed in Section 1, from these graphics we clearly see that choosing $u = \alpha$ for $\check{\lambda}_u$, as suggested by Allison and Santana (2015), leads to a badly calibrated test procedure with a level of significance bigger than $\alpha$. Similar graphics have been observed for other sample sizes. The suggested continuity of $\psi_{\lambda}(u)$ explains the similar
results observed in practice for the test with critical region \( \{ T_n, \tilde{\lambda}_u > c_{n,\tilde{\lambda}_u}(v_p) \} \), that includes two calibration stages, and the test with critical region \( \{ T_n, \hat{\lambda}_u > c_{n,\hat{\lambda}_u}(v_p) \} \), that includes a single calibration stage. For this reason, and because it is less time-consuming than the test with two calibration stages, only the test with a single calibration stage is henceforth considered.

For \( \alpha = 0.01, 0.05 \), and sample sizes \( n = 20, 50, 100 \), we present in Table 1 estimates of the levels \( u_{n,\alpha,p}^\lambda \) and \( u_{n,\alpha,p}^{\tilde{\lambda}} \), for the preassigned level of significance \( \alpha \), based on regular grids of size 0.0001 on the interval \([0,1]\), and estimates of the nominal levels of significance (EL) for the tests based on the EP and HM families of test statistics. The estimation of the nominal levels was based on 100,000 simulations under the null hypotheses. With some few exceptions, the preassigned level \( \alpha \) is inside its approximate 95% confidence interval, revealing the effectiveness of the calibration procedures.

### 5 Finite sample power analysis

In order to study the performance of the tests based on the data-based tuning parameter selectors \( \tilde{\lambda}_u \) and \( \hat{\lambda}_u \), a simulation study is conducted for each one of the Epps-Pulley and Henze-Meintanis families of test statistics. Other than to assess their empirical power, the simulation study is also meant to compare the previous tests with the fixed tuning parameter procedures, usually recommended in the literature. For the Epps-Pulley test of normality, we take \( \lambda = \lambda_{EP} := 1/\sqrt{2} \), which is one of the two values for \( \lambda \) recommended in the pioneering work of Epps and Pulley (1983), and also considered in other studies like those of Baringhaus et al. (1989) and Arcones and Wang (2006) (see also Tenreiro, 2009). For the Henze-Meintanis test of exponentiality, we take

| \( n \) | \( \hat{\lambda}_u \) | \( \tilde{\lambda}_u \) | \( \hat{\lambda}_u \) | \( \tilde{\lambda}_u \) |
|---|---|---|---|---|
| 20 | 0.0032 | 0.0092 | 0.0049 | 0.0096 | 0.0040 | 0.0101 | 0.0042 | 0.0101 |
| 50 | 0.0029 | 0.0098 | 0.0037 | 0.0095 | 0.0037 | 0.0099 | 0.0038 | 0.0099 |
| 100 | 0.0029 | 0.0099 | 0.0039 | 0.0102 | 0.0038 | 0.0096 | 0.0039 | 0.0095 |
| 20 | 0.0183 | 0.0487 | 0.0325 | 0.0484 | 0.0220 | 0.0487 | 0.0225 | 0.0501 |
| 50 | 0.0172 | 0.0497 | 0.0264 | 0.0494 | 0.0217 | 0.0497 | 0.0223 | 0.0499 |
| 100 | 0.0173 | 0.0502 | 0.0277 | 0.0509 | 0.0218 | 0.0499 | 0.0224 | 0.0499 |

Table 1: Estimates of \( u_{n,\alpha,p}^\lambda \) and \( u_{n,\alpha,p}^{\tilde{\lambda}} \), for a preassigned level \( \alpha \), based on regular grids of size 0.0001 on the interval \([0,1]\), and estimates of the nominal levels of significance (EL) for the tests based on the EP and HM families of test statistics. For the estimation of the nominal levels, the number of replications for each case is 100,000.
\[ \alpha = 0.01 \]

\[ \alpha = 0.05 \]

\[ n = 20 \]
\[ n = 50 \]
\[ n = 100 \]

# 1 Uniform distribution
\[ \lambda_{EP} \]
\[ \lambda_{\alpha} \]
\[ \lambda_n \]

# 2 Logistic distribution
\[ \lambda_{EP} \]
\[ \lambda_{\alpha} \]
\[ \lambda_n \]

# 3 LN(0.5) distribution
\[ \lambda_{EP} \]
\[ \lambda_{\alpha} \]
\[ \lambda_n \]

# 4 Normal mixture 0.8N(0, 1) + 0.2N(3, 1)
\[ \lambda_{EP} \]
\[ \lambda_{\alpha} \]
\[ \lambda_n \]

# 5 Tukey(5) distribution
\[ \lambda_{EP} \]
\[ \lambda_{\alpha} \]
\[ \lambda_n \]

Table 2: Empirical power results for the normality tests based on the Epps-Pulley test statistic family. The power estimates are based on 10,000 samples from the considered alternatives.

\[ \lambda = \lambda_{HM} := 1 \], which is one of the two values for \( \lambda \) recommended in Henze and Meintanis (2002).

As before the nominal levels \( \alpha = 0.01, 0.05 \) and the sample sizes \( n = 20, 50, 100 \) are considered. All the power estimates are based on 10,000 samples from the considered alternatives.

Although the following conclusions are based on a simulation study carried out for large sets of alternative distributions usually considered in power studies for testing normality (see Epps and Pulley, 1983, Romão et al., 2010, Yap and Sim, 2011), and exponentiality (see Henze, 1993, Henze and Meintanis, 2002, 2005), we limit ourselves to present in Tables 2 and 3 the empirical power results for some of the considered alternatives. In these tables: LN(\( \theta \)) denotes the lognormal distribution with density \( \frac{1}{\theta x} \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{1}{2} \frac{(\log x)^2}{\theta^2}\right) I(x \geq 0) \); W(\( \theta \)) denotes the Weibull distribution with density \( \theta x^{\theta-1} \exp(-x^\theta) I(x \geq 0) \); LF(\( \theta \)) denotes the linear increasing failure rate distribution with density \( (1 + \theta x) \exp(-x - \theta x^2/2) I(x \geq 0) \); and PW(\( \theta \)) denotes the power distribution with density \( \frac{1}{\theta x^{\theta-1}} I(0 \leq x \leq 1) \), where \( x \in \mathbb{R} \).

For all the considered alternatives, the tests based on the data-dependent tuning parameter selectors performed similarly. Being clearly less time-consuming than the bootstrap-based method for choosing \( \lambda \), our preference goes to \( \tilde{\lambda}_n \). For the generality of the considered alternatives, these data-dependent tuning parameter selectors compare well with the fixed tuning parameters \( \lambda_{EP} \) or \( \lambda_{HM} \), none of them being the best over the considered set of alternative distributions. This is
Table 3: Empirical power results for the exponentiality tests based on the Henze-Meintanis test statistic family. The power estimates are based on 10,000 samples from the considered alternatives.

|                   | $n = 20\alpha = 0.01$ | $n = 50\alpha = 0.01$ | $n = 100\alpha = 0.01$ | $n = 20\alpha = 0.05$ | $n = 50\alpha = 0.05$ | $n = 100\alpha = 0.05$ |
|-------------------|------------------------|------------------------|------------------------|------------------------|------------------------|------------------------|
|                   | $\lambda_{HM}$         | $\lambda_{Hu}$         | $\tilde{\lambda}_{Hu}$ | $\lambda_{HM}$         | $\lambda_{Hu}$         | $\tilde{\lambda}_{Hu}$ |
| #1 Standard uniform distribution | 0.22 0.73 0.99 0.53 0.92 1.00 | 0.13 0.76 1.00 0.46 0.96 1.00 | 0.13 0.76 1.00 0.46 0.96 1.00 | 0.12 0.32 0.63 0.25 0.51 0.80 | 0.16 0.36 0.65 0.31 0.56 0.82 | 0.16 0.35 0.64 0.31 0.55 0.82 |
| #2 W(0.8) distribution | 0.49 0.87 0.99 0.62 0.93 1.00 | 0.53 0.89 0.99 0.65 0.94 1.00 | 0.52 0.89 0.99 0.65 0.94 1.00 | 0.07 0.31 0.72 0.27 0.62 0.91 | 0.03 0.23 0.68 0.17 0.55 0.91 | 0.03 0.23 0.68 0.17 0.55 0.91 |
| #3 LN(1.5) distribution | 0.07 0.15 0.30 0.17 0.30 0.50 | 0.25 0.54 0.84 0.44 0.73 0.94 | 0.25 0.54 0.85 0.44 0.73 0.94 | 0.07 0.15 0.30 0.17 0.30 0.50 | 0.25 0.54 0.84 0.44 0.73 0.94 | 0.25 0.54 0.85 0.44 0.73 0.94 |

illustrated by the alternative distributions # 1, # 2 and # 3 shown in Tables 2 and 3.

For the alternative distributions # 4 in both tables, the tests based on the fixed tuning parameters $\lambda_{EP}$ or $\lambda_{HM}$ are slightly more powerful than those based on the data-dependent tuning parameter selectors. For the normality test this is a consequence of small and large values of $\lambda$, as $\lambda = 0.1$ or $\lambda = 5$, included in the set $\Lambda$. In fact, for the considered normal mixture alternative the power of the Epps-Pulley tests seems to behave like an inverted U-shaped function of $\lambda$. In the case of the exponential test, the power of the Henze-Meintanis tests for the considered alternative, is very low for small values of $\lambda$. Therefore, the inclusion of the value $\lambda = 0.1$ in the set $\Lambda$, may explain the inferior power attained for this alternative by the tests based on the data-dependent tuning parameter selectors. This is a price to pay for having tests with a reasonable power against a wide range of alternative distributions.

The power results reported for alternatives # 5 in Tables 2 and 3, illustrate the already mentioned weak point of the strategy of taking a fixed tuning parameter in the absence of any prior information on the underlying alternative distribution. The usually recommended tuning parameters $\lambda_{EP}$ or $\lambda_{HM}$ lead to tests that achieve a very low power against these alternatives, for which a smaller tuning parameter value would be a better choice. As values as small as $\lambda = 0.1$ or $\lambda = 0.25$, have been included in the set $\Lambda$, the tests based on the considered data-dependent
tuning parameter selectors perform much better than the recommended fixed tuning parameters for these alternatives.

6 A practical example

In this section we illustrate the use of the tests with critical regions \( \{ T_{n,\hat{\lambda}_u} > c_{n,\hat{\lambda}_u}(u) \} \), with \( u = u_{n,\alpha,p}^{\hat{\lambda}} \) given by (12), for each one of the data-based tuning parameter selectors \( \hat{\lambda}_u = \bar{\lambda}_u \) and \( \hat{\lambda}_u = \tilde{\lambda}_u \), defined by (8) and (9), respectively. To this end, we take the data considered in Allison and Santana (2015, Table 9, p. 3287), which concerns the survival times of 43 patients diagnosed with a certain type of Leukaemia. With the intention of testing the appropriateness of the exponential distribution as the underlying distribution from which the Leukaemia data set was obtained, we consider the family of test statistics \( T_{n,\lambda} \) given by (6), with \( \lambda \in \Lambda \), where we take for \( \Lambda \) the same set of tuning parameter values used in the previous sections. As before, in the implementation of \( \tilde{\lambda}_u \) we use \( B = 100 \) bootstrap samples. Approximations of the previous tests \( p \)-values for this data set, are reported in Table 4.

At level \( \alpha = 0.05 \) the null hypothesis of exponentiality is not rejected by any of the considered test procedures. These results are compatible with that obtained by the test based on the fixed tuning parameter \( \lambda = \lambda_{HM} = 1 \), which is one of the values for \( \lambda \) recommended in Henze and Meintanis (2002). The associated \( p \)-value is also reported in Table 4.

| \( \hat{\lambda}_u \) selector | \( \hat{\lambda}_u \) value | \( T_{n,\hat{\lambda}_u} \) value | \( p \)-value |
|-------------------------------|------------------|------------------|----------------|
| \( \bar{\lambda}_u \)        | 5                | 0.00257          | 0.161          |
| \( \tilde{\lambda}_u \)      | 5                | 0.00257          | 0.170          |
| \( \lambda_{HM} \)           | 1                | 0.37985          | 0.112          |

Table 4: Summary of the results for the Leukaemia data set (\( n = 43 \)). The values shown for \( \hat{\lambda}_u \) with \( u = u_{n,\alpha,p}^{\hat{\lambda}} \) are those obtained when \( \alpha \) is equal to the reported \( p \)-value.

7 Conclusions

As any goodness-of-fit test, the tests considered in this paper have a preference for some finite-dimensional space of alternatives, and cannot pay equal attention to an infinite number of orthogonal alternatives (see Janssen, 2000). However, the considered tests based on the data-dependent tuning parameter selectors \( \hat{\lambda}_u \) and \( \bar{\lambda}_u \) have shown to be serious competitors for the recommended tests based on a fixed tuning parameter, and perhaps should be used — especially \( \bar{\lambda}_u \) because is less time-consuming than \( \hat{\lambda}_u \) —, in the absence of any information regarding the type of deviation from the null model.
8 Proofs

Proof of Theorem 1: The first part of Theorem 1 follows from (11) as it implies that

\[ P_F(T_{n,\hat{\lambda}} > c_{n,\hat{\lambda}}(u)) \leq |\Lambda|u, \]  

(16)

for all \( u \in [0,1] \), where \(|\Lambda|\) denotes the cardinality of \( \Lambda \). In order to prove that the probability \( P_F(T_{n,\hat{\lambda}} > c_{n,\hat{\lambda}}(u)) \) is independent of \( F \), for \( F \in \mathcal{F} \), it is enough to use the invariance properties of \( T_{n,\lambda} \) and \( \hat{\lambda} \).

Proof of Theorem 2: Let \( I_{n,\alpha}^\lambda = \{ u \in [0,1]; \psi_\lambda(u) \leq \alpha \} \). As we are assuming that \( \psi_\lambda \) is increasing, we have \( I_{n,\alpha} = [0, u_{n,\alpha}] \) or \( \hat{I}_{n,\alpha} = [0, u_{n,\alpha}^\lambda] \), where \( u_{n,\alpha}^\lambda = \sup I_{n,\alpha}^\lambda \). Taking into account (16), we get \( \psi_\lambda(\alpha/|\Lambda|) \leq \alpha \), and therefore \( \alpha/|\Lambda| \geq u_{n,\alpha}^\lambda \). On the other hand, as \( \lim_{u \uparrow 1} \psi_\lambda(u) = 1 \), we necessarily have \( u_{n,\alpha}^\lambda < 1 \). Using this fact, take \( p > 0 \) small enough such that \( G_p \cap]0, u_{n,\alpha}[ \neq \emptyset \) and \( G_p \cap]0, u_{n,\alpha}^\lambda[ \neq \emptyset \), where \( G_q \) is the considered regular grid on the interval \([0,1]\). By the definition of \( u_{n,\alpha}^\lambda \), we have \( \psi_\lambda(u_{n,\alpha}^\lambda) \leq \alpha \), that is, \( u_{n,\alpha}^\lambda \in I_{n,\alpha}^\lambda \), thus \( u_{n,\alpha}^\lambda \leq u_{n,\alpha} \). On the other hand, as \( \psi_\lambda(u_{n,\alpha}^\lambda + p) > \alpha \) we have \( u_{n,\alpha}^\lambda + p \notin I_{n,\alpha}^\lambda \), and \( u_{n,\alpha}^\lambda + p \geq u_{n,\alpha}^\lambda \). We have proved that \( u_{n,\alpha}^\lambda \leq u_{n,\alpha} \), \( u_{n,\alpha}^\lambda \leq u_{n,\alpha}^\lambda + p \), for \( p > 0 \) small enough, from which we deduce that \( \lim_{p \downarrow 0} u_{n,\alpha}^\lambda = u_{n,\alpha} \). Taking into account the continuity of \( \psi_\lambda \), we finish the proof by showing that \( \psi_\lambda(u_{n,\alpha}^\lambda) = \alpha \). Let us consider \( m \in I_{n,\alpha}^\lambda \) such that \( u_{n,\alpha} \uparrow u_{n,\alpha}^\lambda \). Therefore we get \( \psi_\lambda(u_{n,\alpha}^\lambda) = \psi_\lambda(\lim_{m \uparrow} u_{n,\alpha}) = \lim_{m \uparrow} \psi_\lambda(u_{n,\alpha}) \leq \alpha \). Using the fact that \( u_{n,\alpha} < 1 \), let us consider a sequence \( u_{n,\alpha} \), \( m \in ]0,1[ \) such that \( u_{n,\alpha} \downarrow u_{n,\alpha}^\lambda \). As \( u_{n,\alpha} \) is the supremum of \( I_{n,\alpha}^\lambda \), we have \( \psi_\lambda(u_{n,\alpha}) > \alpha \) for all \( m \in \mathbb{N} \), and therefore \( \psi_\lambda(u_{n,\alpha}) = \psi_\lambda(\lim_{m \uparrow} u_{n,\alpha}) = \lim_{m \uparrow} \psi_\lambda(u_{n,\alpha}) \geq \alpha \).

Proof of Theorem 3: For \( u \in ]0,1[ \) we have

\[
\left\{ \min_{\lambda \in \Lambda} p_{n,\lambda} < u \right\} \subset \{ T_{n,\hat{\lambda}} > c_{n,\hat{\lambda}}(u) \} \subset \left\{ \min_{\lambda \in \Lambda} p_{n,\lambda} \leq u \right\},
\]

(17)

where \( p_{n,\lambda} \) denotes the \( p \)-value \( p_{n,\lambda} = \inf \{ \alpha \in ]0,1[; T_{n,\lambda} > c_{n,\lambda}(\alpha) \} \), with \( \inf \emptyset = 1 \) (see Lehmann and Romano, 2005, Subsection 3.3). As \( F_{T_{n,\lambda}} \) is continuous for all \( \lambda \in \Lambda \), \( p_{n,\lambda} \) is, under \( H_0 \), uniformly distributed on the interval \([0,1]\), and the distribution function of \( \min_{\lambda \in \Lambda} p_{n,\lambda} \) under \( H_0 \), we denote by \( F_m \), is continuous on \( \mathbb{R} \). Finally from (17) we get \( \psi_\lambda(u) = F_m(u) \geq u \), for \( u \in ]0,1[ \), and the stated result follows from Theorem 2, where \( u_{n,\alpha}^\lambda = \sup \{ u \in ]0,1[; F_m(u) \leq \alpha \} \leq \alpha \).

Before given de proof of Theorem 4, we state two auxiliary results on the function \( \psi_\lambda(u) := P_{F_0}(T_{n,\hat{\lambda}} > c_{n,\hat{\lambda}}(u)) \), defined for \( u \in ]0,1[ \). Firstly, note that from inequality (16), we have \( \lim_{u \uparrow 1} \psi_\lambda(u) = 0 \), for any invariant tuning parameter selector \( \hat{\lambda} \). The limit of \( \psi_\lambda(u) \) when \( u \uparrow 1 \), is given in the following proposition, where \( F_{T_{n,\lambda}} \) denotes the null distribution function of \( T_{n,\lambda} \).

Proposition 1. If \( F_{T_{n,\lambda}} \) is continuous, for all \( \lambda \in \Lambda \), then \( \lim_{u \uparrow 1} \psi_\lambda(u) = 1 \).

In the following proposition we analyse the case where \( \hat{\lambda}_u = \hat{\lambda} \), for all \( u \in ]0,1[ \), with \( \hat{\lambda} = \hat{\lambda}(X_1, \ldots, X_n) \) a measurable function that takes values in \( \Lambda \), which is either location-scale invariant in case (2) or scale invariant in case (3).
Proposition 2. If \( F_{T_{n,\lambda}} \) is continuous and strictly increasing (on the set \( \{ t \in \mathbb{R} : 0 < F_{T_{n,\lambda}}(t) < 1 \} \)), for all \( \lambda \in \Lambda \), and \( \hat{\lambda}_u = \lambda_u \), for all \( u \in [0,1] \), then the function \( \psi_\lambda \) is continuous and increasing on \( [0,1] \).

Proof of Theorem 4: For \( u \) fixed in \( [0,1] \) define the invariant tuning parameter selector \( \hat{\lambda}_u \) by \( \hat{\lambda}_u = \lambda_u \), for all \( v \in [0,1] \). Using Propositions 1 and 2, the stated result follow from Theorem 2, where \( u^\lambda_{n,\alpha,p} = u^\lambda_{n,\alpha,q} \) and \( u^\lambda_{n,\alpha} = u^\lambda_{n,\alpha} \).

Proof of Theorem 5: Let \( F \notin \mathcal{F} \), such that \( T_{n,\lambda} \xrightarrow{p} +\infty \) under \( F \), for all \( \lambda \in \Lambda \). As \( \alpha/|\Lambda| \leq u^\lambda_{n,\alpha} = u \), for each \( \lambda \in \lambda \) we have \( P_F(T_{n,\lambda} > c_{n,\lambda}(u)) \geq P_F(T_{n,\lambda} > c_{n,\lambda}(\alpha/|\Lambda|)) \), since \( c_{n,\lambda}(u) \leq c_{n,\lambda}(\alpha/|\Lambda|) \). Moreover, from the continuity of \( F_{T_{n,\lambda}}^{-1} \), and the convergence \( F_{T_{n,\lambda}}^{-1}(t) \rightarrow F_{T_{n,\lambda}}^{-1}(t) \), for all \( 0 < t < 1 \) (see Shorack and Wellner, 1986, pp. 3–10), we get \( c_{n,\lambda}(\alpha/|\Lambda|) = F_{T_{n,\lambda}}^{-1}(1 - \alpha/|\Lambda|) \rightarrow F_{T_{n,\lambda}}^{-1}(1 - \alpha/|\Lambda|) \), which implies that \( \sup_{n \in \mathbb{N}} c_{n,\lambda}(\alpha/|\Lambda|) < +\infty \). Therefore, we conclude that \( P_F(T_{n,\lambda} > c_{n,\lambda}(u)) \rightarrow 1 \), as \( n \rightarrow \infty \), for all \( \lambda \in \Lambda \). Finally, the stated result follows from the equality \( P_F(T_{n,\hat{\lambda}_u} > c_{n,\hat{\lambda}_u}(u)) = \sum_{\lambda \in \Lambda} P_F(T_{n,\lambda} > c_{n,\lambda}(u), \hat{\lambda}_u = \lambda) \).

Proof of Theorem 6: Let \( F \notin \mathcal{F} \), and take \( \lambda \in \Lambda \) such that \( T_{n,\lambda} \xrightarrow{p} +\infty \) under \( F \). Proceeding as in the proof of Theorem 5, for \( u = u^\lambda_{n,\alpha} \) we conclude that \( P_F(T_{n,\lambda} > c_{n,\lambda}(u)) \rightarrow 1 \), as \( n \rightarrow \infty \), and the stated result follows from the fact that \( P_F(T_{n,\hat{\lambda}_u} > c_{n,\hat{\lambda}_u}(u)) \geq P_F(T_{n,\lambda} > c_{n,\lambda}(u)) \).

Proof of Theorem 7: The Epps and Pulley test statistics given by (5) are nonconstant whenever \( n \geq 3 \), and well defined on \( D_n \), where \( D_n = \{ x \in \mathbb{R}^n : x_1 = \cdots = x_n \} \). Therefore, they are nonconstant and well defined with probability one, whenever \( n \geq 3 \), and \( F \) is such that \( \mu_F^n(D_n) = 1 \). This condition is fulfilled whenever \( F \) is absolutely continuous on \( \mathbb{R} \), which occurs under the null hypothesis of normality. Regarding the Henze and Meintanis test statistics given by (6), they are nonconstant whenever \( n \geq 2 \), and well defined on the set \( D_n = \{ x \in \mathbb{R}^n : x_1, \ldots, x_n > 0 \} \). Therefore, they are nonconstant and well defined with probability one, whenever \( n \geq 2 \), and \( F \) is such that \( \mu_F^n(D_n) = 1 \), where \( \mu_F \) denotes the probability distribution of \( F \) and \( \mu_F^n \) is the product measure. This condition is satisfied whenever \( F \) is such that \( F(0) = 0 \), which is true under the null hypothesis of exponentiality.

We start by proving that \( F_{T_{n,\lambda}} \) is strictly increasing on the set \( \{ t \in \mathbb{R} : 0 < F_{T_{n,\lambda}}(t) < 1 \} \). For that, let us take \( s, t \in \mathbb{R} \) with \( s < t \) and \( 0 < F_{T_{n,\lambda}}(s) \leq F_{T_{n,\lambda}}(t) < 1 \). As \( \mu_{F_0}^n \left( \{ x \in D_n : T_{n,\lambda}(x) \leq s \} \right) > 0 \) and \( \mu_{F_0}^n \left( \{ x \in D_n : T_{n,\lambda}(x) > t \} \right) > 0 \), the sets \( \{ x \in D_n : T_{n,\lambda}(x) \leq s \} \) and \( \{ x \in D_n : T_{n,\lambda}(x) > t \} \) are nonempty, which implies, from the continuity of \( T_{n,\lambda} \) and the fact that \( D_n \) is open and connected, that the set \( \{ x \in D_n : s < T_{n,\lambda}(x) < t \} = T_{n,\lambda}^{-1}(s,t) \) is a nonempty open subset of \( D_n \). Taking into account that \( \mu_{F_0}^n \) is either the standard Gaussian or the unit exponential probability distributions on \( \mathbb{R} \), we conclude that \( \mu_{F_0}^n \left( T_{n,\lambda}^{-1}(s,t) \right) > 0 \), which finally implies that \( F_{T_{n,\lambda}}(s) < F_{T_{n,\lambda}}(t) \).

Next we will prove that \( F_{T_{n,\lambda}} \) is continuous on \( \mathbb{R} \). For that, we start by showing that is enough to prove that

\[
\mu_{F_0} \left( (T_{n,\lambda}^{x_2,\ldots,x_n})^{-1}(y) \right) = 0, \quad \text{for all } (x_2, \ldots, x_n) \in D_{n-1} \text{ and } y \in \mathbb{R}, \quad (18)
\]
where $T_{n,\lambda}^{x_2,\ldots,x_n}$ is the section of $T_{n,\lambda}$ determined by $(x_2, \ldots, x_n)$, defined, for $z \in \mathbb{R}$, by $T_{n,\lambda}^{x_2,\ldots,x_n}(z) = T_{n,\lambda}(z, x_2, \ldots, x_n)$. In fact, from Fubini’s theorem and the fact that $\mu_{F_0}^{n-1}(D_{n-1}) = 0$, we have

$$\mu_{F_0}^{n}(T_{n,\lambda}^{-1}(y)) = \mu_{F_0}^{n-1} \otimes F_0(T_{n,\lambda}^{-1}(y)) = \int_{D_{n-1}} \mu_{F_0}((T_{n,\lambda}^{-1}(y))^{x_2,\ldots,x_n})d \mu_{F_0}^{n-1}(x_2, \ldots, x_n) = \int_{D_{n-1}} \mu_{F_0}((T_{n,\lambda}^{x_2,\ldots,x_n})^{-1}(y))d \mu_{F_0}^{n-1}(x_2, \ldots, x_n),$$

where $(T_{n,\lambda}^{-1}(y))^{x_2,\ldots,x_n} = \{z \in \mathbb{R} : (z, x_2, \ldots, x_n) \in T_{n,\lambda}^{-1}(y)\} = (T_{n,\lambda}^{x_2,\ldots,x_n})^{-1}(y)$ is the section of $T_{n,\lambda}^{-1}(y)$ determined by $(x_2, \ldots, x_n)$. Therefore, under (18) we get $\mu_{F_0}^{n}(T_{n,\lambda}^{-1}(y)) = 0$, for all $y \in \mathbb{R}$, which enables us to conclude that $F_{T_{n,\lambda}}$ is continuous on $\mathbb{R}$.

Finally, in order to establish (18) it is enough to take into account that $T_{n,\lambda}^{x_2,\ldots,x_n}$ is a nonconstant analytic function on $\mathbb{R}$, for each $(x_2, \ldots, x_n) \in D_{n-1}$. In fact, for those functions the set $(T_{n,\lambda}^{x_2,\ldots,x_n})^{-1}(y)$, for $y \in \mathbb{R}$, is either empty or consists entirely of isolated points (cf. Carathéodory, 1983, p. 138), which implies that $\mu_{F_0}((T_{n,\lambda}^{x_2,\ldots,x_n})^{-1}(y)) = 0$, as $F_{F_0}$ is an absolutely continuous probability distribution on $\mathbb{R}$. ■

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