Hydrodynamical Behavior for the Symmetric Simple Partial Exclusion with Open Boundary

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Abstract
We analyze the symmetric simple partial exclusion process, which allows at most $\alpha$ particles per site, and we put it in contact with stochastic reservoirs whose strength is regulated by a parameter $\theta \in \mathbb{R}$. We prove that the hydrodynamic behavior is given by the heat equation and depending on the value of $\theta$, the equation is supplemented with different boundary conditions. Setting $\alpha = 1$ we find the results known in Baldasso et al. (J Stat Phys 167(5):1112–1142, 2017) and Bernardin et al. (Markov Processes Relat. Fields 25:217–274, 2017) for the symmetric simple exclusion process.

Keywords Partial exclusion process \cdot Hydrodynamic limit \cdot Heat equation

Mathematics Subject Classification 60J27 \cdot 60K35 \cdot 82C22

1 Introduction

A common problem in the field of statistical mechanics is to deduce the evolution laws of a thermodynamic quantity of interest in a physical system, by analysing the motion of its molecules. Assuming that each molecule behaves as a continuous-time random walk, it arises a system of stochastic interacting particles [19]. Among the many studied models is the exclusion process, which has been serving as a toy model for the analysis of mass transport. Its dynamics can be informally described as follows. Each site of a discrete space can have at most one particle and after an exponential clock
of rate 1, one of the particles at a position $x$ jumps to a position $y$ according to a transition probability $p(y - x)$. Since particles only swap positions, the number of particles is conserved by the random evolution and therefore it is the quantity of interest. The goal in hydrodynamic limit is then to analyse the space-time evolution of the density of particles. The aforementioned model has been extensively studied in the literature and despite its simplicity it captures many interesting non-trivial behavior. The aforementioned dynamics can be much more general as, for example, allowing more than a particle per site and this is the setting we analyse in this article.

The model we investigate here was first introduced in Sect. B of [18], where it was called partial exclusion process since it is allowed to have at most $\alpha \in \mathbb{N}$ particles per site. We restrict to the choice $p(1) = p(-1) = 1/2$ and the exchange rate from a site $x$ to $x + 1$ (resp. from $x + 1$ to $x$) is given by $\eta(x)(\alpha - \eta(x + 1))$ (resp. $\eta(x + 1)(\alpha - \eta(x))$, where $\eta(x)$ denotes the quantity of particles at site $x$. In last case, for $\alpha = 1$, the model is known as the symmetric simple exclusion process (SSEP). Symmetric because of the choice of $p(1) = p(-1)$ and simple because jumps are restricted to nearest-neighbors. This specific choice of the rates were introduced in [18], see Eq. (2.30) there. This precise model was further studied in other settings, such as in [4, 8] when the system is put in contact with stochastic reservoirs, and in [5, 6, 9], but in all of them from a duality point of view. We note that for the choice of rates given above, the instantaneous current of the system, i.e. the difference between the jump rate from $x$ to $x + 1$ and the jump rate from $x + 1$ to $x$ is equal to $\alpha(\eta(x) - \eta(x + 1))$, i.e. the instantaneous current can be written as the gradient of a local function. Besides the gradient property, this generalization of the exclusion process is the only one for which one can find a self-duality relation.

In Sect. 2.4 of [15] it was introduced a generalization of the previous model, that was named generalized exclusion. In that model it is also allowed $\alpha \in \mathbb{N}$ particles per site, but the jump rate from $x$ to $x + y$ is general and given by $r(\eta(x), \eta(x + y))$ such that $r(0, \eta(x)) = 0$ since if there are no particles at $x$ then no jumps occurs, and also $r(\eta(x), \alpha) = 0$, since if the site $x + y$ has $\alpha$ particles, then the jump is suppressed again. For the choice $r(\eta(x), \eta(x + y)) = 1_{[\eta(x) > 0, \eta(x+y)<\alpha]}$, which means that a jump occurs with rate 1 independently of the number of particles at $x$ and $x + y$, the model is no longer gradient. The hydrodynamic limit in this case was derived in Chap. 7 of [15] when the model is taken evolving on the one-dimensional torus and in [16] when the system is in contact with reservoirs whose strength does not scale with the size of the system.

Our focus in this article is to deduce the space-time evolution of the density of particles when the system is evolving on the discrete set of sites $\{1, \ldots, N - 1\}$, that we call bulk. Moreover, we put the process in contact with two boundary reservoirs (modelled by the sites $x = 0$ and $x = N$) interacting with the bulk at different intensities. More precisely, the boundary rates of injection and absorption of particles scale with the size of the system, i.e. $N$, through a parameter $\theta \in \mathbb{R}$. When $\theta < 0$ the interaction is fast and when $\theta \geq 0$ it is slow. We observe that when $\alpha \neq 1$, this model differs from the usual SSEP because it allows more than one particle per site and this difference, at the level of the microscopic dynamics, results in having a model that is not solvable by a matrix ansatz formulation and, as a consequence, there is not much information about its non-equilibrium stationary state (NESS) apart
the case $\theta = 0$ where information on the stationary correlations has been obtained in [4, 5, 9]. For $\alpha = 1$, the matrix ansatz method developed by [7] allows getting information on its NESS, which in turn enables one to obtain explicitly the stationary correlations of the system for any value of $\theta \in \mathbb{R}$, see, for example, Sect. 2.2 of [12] and references therein. In fact, for $\alpha = 1$ the stationary correlation function is solution to an elliptic equation written in terms of the two-dimensional reflected Laplacian distorted at boundary points and explicit expressions can be obtained for any value of $\theta \in \mathbb{R}$ [11]. For $\alpha \neq 1$ and for $\theta \neq 0$ the situation is much more intricate. This is due to the fact that the stationary correlations are solution to an elliptic equation written in terms of a two-dimensional reflected Laplacian besides the case when points are at distance one, where this operator is replaced by another one in which the rates to go left/up are different from going right/down and also distorted at boundary points. For this reason we could not get an explicit expression for these correlations, and this is currently under investigation.

The hydrodynamic limit in the case of the exclusion process with open boundary and $\alpha = 1$ was analyzed in [1] the slow case, and in [2] the fast case. Here we answer a natural question that usually arises which has to do with the extension of the hydrodynamic limit, when more than one particle is allowed at each site. Towards this, we extend the hydrodynamic limit for $\alpha \neq 1$ in both the slow and fast regimes and we obtain the heat equation with several boundary conditions. Our proof follows the same approach as in [1, 2] i.e. it relies on the entropy method introduced by Guo, Papanicolaou, Varadhan in [14]. Our result shows that the entropy method is robust enough in order to prove the hydrodynamic limit for a family of partial exclusion models, regardless of the label $\alpha$ and so also for non-integrable models with a fast/slow boundary. Now we comment a bit on the strategy of the proof. The idea of the argument is to prove tightness of the sequence of empirical measures associated to the density and then characterize uniquely the limit point. This last characterization is done in two steps. First, we show that the limiting points are supported on measures absolutely continuous with respect to the Lebesgue measure. Second, we show that the density is the unique weak solution of the heat equation with diffusion coefficient $\alpha$ given by

$$
\partial_t \rho_t(u) = \alpha \Delta \rho_t(u),
$$

where $\rho_t(u)$ denotes the density of particles at time $t \geq 0$ and position $u \in [0, 1]$. Depending on the range of the parameter $\theta$, we obtain either Dirichlet boundary conditions (for $\theta < 1$) that fix the value of the profile at the boundary of $[0, 1]$, Robin conditions (for $\theta = 1$) that fix the value of the flux at the boundary of $[0, 1]$ as being proportional to the difference of the densities close to the boundary, or Neumann boundary conditions (for $\theta > 1$), that fixes the aforementioned flux as being null. This is similar to the hydrodynamic behavior obtained in [1, 2] for the case $\alpha = 1$. From our results we also obtain theirs.

The main difference of our proof with respect to previous proofs is that the two replacement lemmas that are necessary in order to obtain the boundary conditions from the exclusion dynamics, are more complicated since the process allows $\alpha$ particles per site. In the case $\alpha = 1$, since $\eta(x) \in \{0, 1\}$, the Glauber dynamics flips the value of the configuration at the boundary so that this transformation turns $\eta(x)$ into $1 - \eta(x)$, and
the bulk dynamics coincides with the exchange dynamics, which replaces $\eta(x)$ with $\eta(x + 1)$ and vice-versa. Nevertheless, when there is more than one particle per site, the Glauber dynamics injects or removes particles at the boundary and this does no longer coincides with the flip dynamics; while the bulk dynamics removes one particle from a site $x$ and takes it to $x + 1$, which means that $\eta(x)$ is converted into $\eta(x) - 1$ and $\eta(x + 1)$ to $\eta(x + 1) + 1$. This brings additional difficulties when analysing the boundary terms. The way to overcome this difficulty, is to make a proper splitting of the state-space of the process, and write carefully the action of the Glauber dynamics in a way that creation and annihilation terms can be combined.

There are two other related problems that we comment on. The first one is the hydrostatic limit, that can be obtained as a consequence of the hydrodynamic limit in the case $\theta = 0$ by a simple analysis of the stationary correlation function and the discrete stationary profile. In fact, given the result on the hydrodynamic limit, to derive the hydrostatic limit on just needs to show that the stationary measure is associated to a certain profile. The candidate profile is the stationary profile of the hydrodynamic equation. And this is a consequence of showing that the stationary correlations vanish as the systems’ size grows plus the fact that the discrete stationary profile converges to the stationary profile of the limiting hydrodynamic equation. For details on this argument we refer the reader to, for example, the proof of Theorem 2.2 in [1]. Information on the stationary correlations for our model has been obtained in [4, 5, 8] for the case $\theta = 0$. Their results combined with ours, we can obtain the hydrostatic limit for $\theta = 0$. We note however that for $\alpha \neq 1$ and $\theta \neq 0$ explicit formulas for the stationary correlations seem difficult to obtain. We also note that for $\theta > 1$, there is an alternative way to obtain the hydrostatic limit relying on the arguments developed in [20], which consists in analysing the mass of the system in the time scale $N^{1+\theta}$. The second problem that we would like to comment on is the analysis of the non-equilibrium fluctuations, which is well known for the case $\alpha = 1$ and any value of $\theta$, see [12] and references therein. For $\alpha \neq 1$, that result is completely open. It would be interesting to check out whether the fact that for $\alpha \neq 1$ it does not hold $\eta(x)^2 = \eta(x)$ (which destroys many combinatorial properties that hold for the SSEP) brings any additional terms to the equation governing the fluctuations of the system. This is a work in progress to appear in [11]. We also highlight that our replacement lemmas are the building blocks in order to analyse limit theorems for other observables of our model as well as large deviations principles. During the writing of this article, we learned that [17] obtained both the hydrodynamic and the hydrostatic limit for our model and for the inclusion process (see also [10]) evolving on Lipschitz domains in arbitrary dimensions. Those results were obtained by an approach based on duality but also on mild solutions of the heat equation and convergence of random walks to Brownian motions with different boundary conditions. In any case, we decided to write our short proof of the hydrodynamic limit because our approach does not rely on those arguments. Nevertheless, many details in our proof are hidden since we try to highlight the main differences with respect to the proof for $\alpha = 1$. We also believe that our method of proof of the replacement lemmas is new and could fit other models of interest, see, as an example, the results of [13], where it is derived the hydrodynamic limit for a multi-species exclusion process. About the dimension, we present the results in $d = 1$ but we believe that they can be extended to higher
dimensions as, for example, to the set \( \{1, \ldots, N-1\} \times \mathbb{T}_N^{d-1} \), where \( \mathbb{T}_N \) represents the discrete torus. Moreover, one interesting problem is the extension of our results to the long-range interaction setting, for which the hydrodynamic limit brings fractional PDEs with different boundary conditions, and in this case we believe that our results can be extended without too many complications. This is left for a future work.

Here follows an outline of the article. In Sect. 2 we introduce the model and our main result, Theorem 2.1. In Sect. 3 we prove tightness for any range of the parameter \( \theta \) and we characterize the limit points as weak solutions of the corresponding partial differential equations. In Sect. 4 we establish the replacement lemmas.

2 The Model and Statement of Results

2.1 SEP(\( \alpha \))

Fix a parameter \( \alpha \in \mathbb{N} \) and let \( \Lambda_N := \{1, \ldots, N-1\} \). The exclusion process that we consider in this paper has state space given by \( \Omega_N := \{0, \ldots, \alpha\}^{\Lambda_N} \) and the elements of \( \Omega_N \) are configurations denoted by \( \eta \). The number of particles at \( x \) is denoted by \( \eta(x) \). In this process particles wait an exponential random time after which, one of them jumps to a nearest-neighbor site if, and only if, the destination site has at most \( \alpha - 1 \) particles, otherwise the particle waits a new random time. The infinitesimal Markov generator of our process is denoted by \( \mathcal{L}_N \) and it is given on \( f : \Omega_N \to \mathbb{R} \) by

\[
\mathcal{L}_N f(\eta) = \mathcal{L}_\ell f(\eta) + \mathcal{L}_{bulk} f(\eta) + \mathcal{L}_r f(\eta),
\]

where, for all \( \eta \in \Omega_N \),

\[
\mathcal{L}_\ell f(\eta) = \frac{1}{N^\theta} c_{1,0}(\eta) \left\{ f(\eta^{1,0}) - f(\eta) \right\} + \frac{1}{N^\theta} c_{0,1}(\eta) \left\{ f(\eta^{0,1}) - f(\eta) \right\},
\]

\[
\mathcal{L}_{bulk} f(\eta) = \sum_{x=1}^{N-2} \left[ c_{x,x+1}(\eta) \left\{ f(\eta^{x,x+1}) - f(\eta) \right\} 
+ c_{x+1,x}(\eta) \left\{ f(\eta^{x+1,x}) - f(\eta) \right\} \right],
\]

\[
\mathcal{L}_r f(\eta) = \frac{1}{N^\theta} c_{N-1,N}(\eta) \left\{ f(\eta^{N-1,N}) - f(\eta) \right\} 
+ \frac{1}{N^\theta} c_{N,N-1}(\eta) \left\{ f(\eta^{N,N-1}) - f(\eta) \right\}.
\]

Above

\[
\eta^{x,y}(z) = (\eta(x) - 1) \mathbb{I}_{z=x} + (\eta(y) + 1) \mathbb{I}_{z=y} + \eta(z) \mathbb{I}_{z \neq x,y},
\]
where $x, y \in \Lambda_N$. For $x, y \in \Lambda_N$ with $y \neq x$ and $|x - y| \leq 1$, the rates are chosen as

$$c_{x,y}(\eta) := \eta(x)[\alpha - \eta(y)].$$

Now we define

$$\eta^{0,1}(z) = (\eta(1) + 1) \mathbb{1}_{z=1} \mathbb{1}_{\eta(1) \leq \alpha - 1} + \eta(1) \mathbb{1}_{z=1} \mathbb{1}_{\eta(1) = \alpha} + \eta(z) \mathbb{1}_{z \neq 1}.$$

Analogously we define $\eta^{N,N-1}$ by replacing 0 by $N$ and 1 by $N - 1$, respectively. We also define

$$\eta^{1,0}(z) = (\eta(1) - 1) \mathbb{1}_{z=1} \mathbb{1}_{\eta(1) \geq 1} + \eta(1) \mathbb{1}_{z=1} \mathbb{1}_{\eta(1) = 0} + \eta(z) \mathbb{1}_{z \neq 1}.$$

Analogously we define $\eta^{N-1,N}$ by replacing 1 by $N - 1$ and 0 by $N$, respectively. Moreover, for $\epsilon, \gamma, \beta, \delta \in \mathbb{R}^+$ and $\theta \in \mathbb{R}$ we define

$$c_{0,1}(\eta) = \epsilon[\alpha - \eta(1)], \quad c_{1,0}(\eta) = \gamma \eta(1), \quad c_{N-1,N}(\eta) = \beta \eta(N-1) \quad \text{and} \quad c_{N,N-1}(\eta) = \delta[\alpha - \eta(N-1)].$$

The dynamics of $\text{SEP}(\alpha)$ is described in the figure below.

The $\text{SEP}(\alpha)$ describes an irreducible continuous-time Markov chain with a finite state-space and so it admits a unique invariant measure. In equilibrium, i.e. when $\frac{\epsilon}{\epsilon + \gamma} = \frac{\delta}{\delta + \beta}$, the invariant measure is reversible and explicitly known. For a function $\varphi : [0, 1] \rightarrow [0, 1]$, let $\nu_{\varphi}^N$ be the product measure whose marginals are given by the Binomial($\alpha$, $\varphi(\frac{x}{N})$) distribution, i.e.

$$\nu_{\varphi}^N(\eta) = \prod_{x \in \Lambda_N} \binom{\alpha}{\eta(x)} [\varphi(\frac{x}{N})]^{\eta(x)} [1 - \varphi(\frac{x}{N})]^{\alpha - \eta(x)}.$$
Proposition 2.1 ([4]) Let $\alpha \in \mathbb{N}$ and $\varrho \in (0, 1)$. If $\frac{\varepsilon}{\varepsilon + \gamma} = \frac{\delta}{\delta + \beta} = \varrho$, then the homogeneous product measure $v_\varrho^N(\cdot)$ given in (5) with $\varrho(\cdot) \equiv \varrho$ is reversible.

Hereafter we fix $T > 0$ and a finite time horizon $[0, T]$. We denote by $\mathcal{D}([0, T], \Omega_N)$ as the space of càdàg trajectories endowed with the Skorohod topology and $\mathcal{M}$ as the space of non-negative Radon measures on $[0, 1]$ with total mass bounded by $\alpha$ and equipped with the weak topology. For $\eta \in \Omega_N$, we define the empirical measure $\pi^N(\eta, du)$ by

$$
\pi^N(\eta, du) := \frac{1}{N - 1} \sum_{x \in \Lambda_N} \eta(x) \delta_{\frac{x}{N}} (du) \in \mathcal{M},
$$

where $\delta_b$ is a Dirac measure in $b \in [0, 1]$. For every $G : [0, 1] \to \mathbb{R}$, we denote the integral of $G$ with respect to $\pi^N$ by $\langle \pi^N, G \rangle$ and we observe that

$$
\langle \pi^N, G \rangle := \frac{1}{N - 1} \sum_{x \in \Lambda_N} \eta(x) G \left( \frac{x}{N} \right).
$$

We also define $\pi^N_t(\eta, du) := \pi^N(\eta_t N^2, du)$.

Definition 2.1 Let $g : [0, 1] \to [0, \alpha]$ be a measurable function. We say that a sequence of probability measures $(\mu_N)_{N \geq 1}$ on $\Omega_N$ is associated to the profile $g$ if for every continuous function $G$ and $\delta > 0$, it holds

$$
\lim_{N \to +\infty} \max_{x \in \Lambda_N} \left| E_{\mu_N} \left[ \eta(x) \right] - \frac{1}{N - 1} \sum_{x \in \Lambda_N} \eta(x) G \left( \frac{x}{N} \right) \right| = 0.
$$

Remark 2.1 We observe that as examples of measures that satisfy the previous identity is the set of measures for which the following conditions are true:

1. there exists a measurable profile $\gamma : [0, 1] \to [0, \alpha]$ such that for $\gamma^N(x) := E_{\mu_N} \left[ \eta(x) \right]$ it holds

$$
\lim_{N \to +\infty} \max_{x \in \Lambda_N} \left| \gamma^N(x) - \gamma \left( \frac{x}{N} \right) \right| = 0. \tag{6}
$$

2. $\lim_{N \to +\infty} \max_{x \neq y \in \Lambda_N} \left| E_{\mu_N} \left[ \eta(x) \eta(y) \right] - \gamma^N(x) \gamma^N(y) \right| = 0. \tag{7}$

The proof of this observation can be seen, for example, in the proof of Theorem 2.2 of [1]. If for a given measurable Lipschitz profile $\varrho : [0, 1] \to [0, 1]$ we consider the Binomial product measure given in (5), then the two previous conditions are trivially satisfied with $\mu_N := v_\varrho^N(\cdot)$ and with the profile $\gamma(\cdot) = \alpha \varrho(\cdot)$. 

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Now, for every $N \geq 1$, let $\mathbb{P}_{\mu_N}$ be the probability measure on $\mathcal{D}([0, T], \Omega_N)$ induced by the Markov process $(\eta_t)_{t \geq 0}$ and by the initial measure $\mu_N$ and the expectation with respect to $\mathbb{P}_{\mu_N}$ is denoted by $\mathbb{E}_{\mu_N}$. We denote by $\mathcal{D}([0, T], M)$ the space of càdlàg trajectories endowed with the Skorohod topology and $(Q_N)_{n \geq 1}$ as the sequence of probability measures on $\mathcal{D}([0, T], M)$ induced by the Markov process $(\pi_t^N)_{0 \leq t \leq T}$ and by the initial measure $\mu_N$.

### 2.2 Hydrodynamic Equations

In order to properly introduce our notions of solutions, which are in the weak sense, we first need to define the set of test functions. For $m, n \in \mathbb{N}_0$, let $C^{m,n}([0, T] \times [0, 1])$ be the set of continuous functions defined on $[0, T] \times [0, 1]$ that are $m$ times differentiable on the first variable and $n$ times differentiable on the second variable, and with continuous derivatives. We also denote $C_c^{m,n}([0, T] \times [0, 1])$ as the set of functions $G \in C^{m,n}([0, T] \times [0, 1])$ such that for each time $s$, $G_s$ has a compact support included in $(0, 1)$ and we denote by $C_c^m(0, 1)$ (resp. $C_c^\infty(0, 1)$) the set of all $m$ continuously differentiable (resp. smooth) real-valued functions defined on $(0, 1)$ with compact support. The supremum norm is denoted by $\| \cdot \|_\infty$. Now we define the Sobolev space $\mathcal{H}^1$ on $[0, 1]$. For that purpose, we define the semi inner-product $\langle \cdot, \cdot \rangle_1$ on the set $C^\infty(0, 1)$ by $\langle G, H \rangle_1 = \langle \partial_u G, \partial_y H \rangle$ for $G, H \in C^\infty(0, 1)$ and the corresponding semi-norm is denoted by $\| \cdot \|_1$. Above $\langle \cdot, \cdot \rangle$ corresponds to the inner product in $L^2((0, 1))$ and should not be mistaken with $\langle \pi^N, G \rangle$. The corresponding norm is denoted by $\| \cdot \|_{L^2}$.

**Definition 2.2** The Sobolev space $\mathcal{H}^1$ on $[0, 1]$ is the Hilbert space defined as the completion of $C^\infty(0, 1)$ for the norm

$$
\| \cdot \|_{\mathcal{H}^1}^2 := \| \cdot \|_{L^2}^2 + \| \cdot \|_1^2
$$

and we note that its elements coincide a.e. with continuous functions. The space $L^2(0, T; \mathcal{H}^1)$ is the set of measurable functions $f : [0, T] \rightarrow \mathcal{H}^1$ such that $\int_0^T \| f_s \|_{\mathcal{H}^1}^2 ds < \infty$.

Let $g : [0, 1] \rightarrow [0, \alpha]$ be a measurable function which will be the initial condition in all our equations. We use the notation

$$
\rho_- := \frac{\alpha}{\epsilon + \gamma} \quad \text{and} \quad \rho_+ := \frac{\delta}{\delta + \beta}
$$

to identify, respectively, the left and right density of the boundary reservoirs.

**Definition 2.3** We say that $\rho : [0, T] \times [0, 1] \rightarrow [0, \alpha]$ is a weak solution of the heat equation with Dirichlet boundary conditions

$$
\begin{cases}
\partial_t \rho_t(u) = \alpha \Delta \rho_t(u), \quad (t, u) \in [0, T] \times (0, 1), \\
\rho_t(0) = \rho_-, \quad \rho_t(1) = \rho_+, \quad t \in (0, T),
\end{cases}
$$

(8)
if $\rho \in L^2(0, T; H^1)$, $\rho_t(0) = \rho_-$ and $\rho_t(1) = \rho_+$ for a.e. $t \in (0, T)$, and for all $t \in [0, T]$ and any $G \in C^{1,2}([0, T] \times [0, 1])$ it holds

$$\langle \rho_t, G_t \rangle - \langle g, G_0 \rangle - \int_0^t \langle \rho_s, \left( \alpha \Delta + \partial_s \right) G_s \rangle ds = 0.$$ 

**Definition 2.4** Let $\kappa \geq 0$. We say that $\rho : [0, T] \times [0, 1] \rightarrow [0, \alpha]$ is a weak solution of the heat equation with Robin boundary conditions

$$\begin{cases}
\partial_t \rho_t(u) = \alpha \Delta \rho_t(u), & (t, u) \in [0, T] \times (0, 1), \\
\partial_u \rho_t(0) = \kappa \frac{\epsilon + \gamma}{\alpha} \left( \rho_t(0) - \rho_- \right), & \partial_u \rho_t(1) = \kappa \frac{\delta + \beta}{\alpha} \left( \rho_+ - \rho_t(1) \right), & t \in (0, T],
\end{cases}$$

(9)

if $\rho \in L^2(0, T; H^1)$ and for all $t \in [0, T]$ and any $G \in C^{1,2}([0, T] \times [0, 1])$ it holds

$$\begin{align*}
\langle \rho_t, G_t \rangle - \langle g, G_0 \rangle - \int_0^t \langle \rho_s, \left( \alpha \Delta + \partial_s \right) G_s \rangle ds + \alpha \\
&\quad\quad - \kappa \int_0^t \left[ G_s(0)(\epsilon + \gamma) \left( \rho_s(0) - \rho_- \right) + G_s(1)(\delta + \beta) \left( \rho_+ - \rho_s(1) \right) \right] ds = 0.
\end{align*}$$

Taking $\kappa = 0$ in Definition 10, we get the heat equation with Neumann boundary conditions.

**Remark 2.2** We observe that the uniqueness of the weak solutions as given above can be seen, for example, in [1, 2] and we refer the interested reader to those articles for a proof.

We observe that the solution of the hydrodynamic equation $\rho_t(u)$ takes values in $[0, \alpha]$ and should not be confused with the function $\varrho(\cdot)$, defined in (5), that takes values in $[0, 1]$.

### 2.3 Hydrodynamic Limit

Now we state our main result.

**Theorem 2.1** Let $g : [0, 1] \rightarrow [0, \alpha]$ be a measurable function and let $(\mu_N)_{N \geq 1}$ be a sequence of probability measures associated to $g$. For any $t \in [0, T]$ and any $G \in C^0([0, 1])$, it holds

$$\lim_{N \to \infty} \mathbb{P}_{\mu_N} \left( \eta : \left| \frac{1}{N-1} \sum_{x \in \Lambda_N} G \left( \frac{x}{N} \right) \eta_{tN^2}(x) - \langle G, \rho_t \rangle \right| > \delta \right) = 0.$$
where $\rho_t(\cdot)$ is the unique weak solution of:

(a) (8), if $\theta < 1$;

(b) (9) with $\kappa = 1$ if $\theta = 1$, and with $\kappa = 0$ if $\theta > 1$.

### 3 Proof of Theorem 2.1

The strategy of the proof follows from the entropy method introduced in [14] and it consists in two ingredients. First, we show in Sect. 3.1 that the sequence $(Q_N)_{n \geq 1}$ is tight with respect to the Skorohod topology in $D([0, T], M)$. From this we know that there exists a limit point $Q^*$ that we want to characterize uniquely, so that convergence of the whole sequence follows. Second, in Sect. 3.2, we characterize the limit points. Since $\eta_t(x)$ is bounded, the limit point $Q^*$ is supported on trajectories of measures that are absolutely continuous with respect to Lebesgue, i.e. $\pi_t(du) = \rho_t(u)du$. Then we show that the density satisfies the integral formulation of the corresponding equations by using Dynkin’s formula and the Replacement Lemmas of Sect. 4. Then, for the proof of uniqueness of weak solutions, one needs to show that $\rho \in L^2(0, T; H^1)$. We note that with the replacement lemma given in Lemma 4.3 in hands, the proof of that result is very similar to the one in [1] and for that reason we leave the details to the reader, but we emphasize that having more particles per site does not bring any additional difficulties to show that result. Finally, the convergence result follows by the uniqueness of the weak solution of the hydrodynamic equation. We observe however that in the Dirichlet case we also have to prove that $\rho_t(0) = \rho_-$ and $\rho_t(1) = \rho_+$ for a.e. $t \in (0, T]$ and this follows easily from the combination of Lemmas 4.2 and 4.3, for details we refer the reader to Section 5.3 of [2].

#### 3.1 Tightness

This section is devoted to the proof of tightness of the sequence $(Q_N)_{N \geq 1}$. From Proposition 4.1.6 of [15], it is enough to show that, for every $\epsilon > 0$ and any function $G \in C^0_c([0, 1])$,

$$\lim_{\delta \to 0^+} \lim_{N \to \infty} \sup_{\tau \in \mathcal{T}_T, t \leq \delta} \mathbb{P}_{\mu_N} \left[ \eta_t \in D([0, T], \Omega_N) : \langle \pi_N^{t+\tau}, G \rangle - \langle \pi_N^t, G \rangle > \epsilon \right] = 0, \quad (10)$$

where $\mathcal{T}_T$ represents the set of stopping times bounded by $T$. By an $L^1$ approximation procedure, it is enough to show the last result for $G \in C^2_c([0, 1])$. From Dynkin’s formula, see, e.g., Appendix 1 of [15], for every $t \geq 0$ and $G$ sufficiently smooth,

$$\mathcal{M}_t^N(G) = \langle \pi_t^N, G \rangle - \langle \pi_0^N, G \rangle - \int_0^t N^2 \mathcal{L}_N \langle \pi_s^N, G \rangle ds \quad (11)$$

is a martingale. We observe that (10) is a direct consequence of the next result combined with Markov’s inequality.
Proposition 3.1 For $G \in C_c^2([0, 1])$, it holds
\[
\begin{align*}
\lim_{\delta \to 0^+} \lim_{N \to \infty} \sup_{\tau \in \mathcal{F}_T, t \leq \delta} \mathbb{E}_{\mu_N} \left[ \left| \int_{\tau}^{\tau+t} N^2 \mathcal{L}_N(\pi_s^N, G) ds \right| \right] &= 0.
\lim_{\delta \to 0^+} \lim_{N \to \infty} \sup_{\tau \in \mathcal{F}_T, t \leq \delta} \mathbb{E}_{\mu_N} \left[ \left( \mathcal{M}_N^N(\tau_t) - \mathcal{M}_N^N(\tau_{t+t}) \right)^2 \right] = 0.
\end{align*}
\]

Proof The proof of the first limit follows from proving that $N^2|\mathcal{L}_N(\pi_s, G)| \leq C$. A simple computation shows that
\[
N^2 \mathcal{L}_N(\pi_s^N, G) = \alpha \frac{1}{N-1} \sum_{x=1}^{N-1} \eta_s(x) \Delta_N \left( \frac{x}{N} \right)
+ \frac{\epsilon + \gamma}{(N-1)N^2} N^2 \left[ \rho_- - \eta_{sN^2}(1) \right] G \left( \frac{1}{N} \right)
+ \alpha \frac{N^2}{N-1} \eta_s(1) \left( G \left( \frac{1}{N} \right) - G(0) \right)
+ \frac{\delta + \beta}{(N-1)N^2} N^2 \left[ \rho_+ - \eta_{sN^2}(N-1) \right] G \left( \frac{N-1}{N} \right)
+ \alpha \frac{N^2}{N-1} \eta_s(N-1) \left( G \left( \frac{N-1}{N} \right) - G(1) \right).
\]

From last identity together with the fact that $G \in C_c^2([0, 1])$ and $|\eta_s(x)| \leq \alpha$ for all $x \in \Lambda_N$ and $s \in [0, T]$, the result easily follows. To prove the second limit we note that
\[
\mathbb{E}_{\mu_N} \left[ \left( \mathcal{M}_N^N(\tau_t) - \mathcal{M}_N^N(\tau_{t+t}) \right)^2 \right]
= \mathbb{E}_{\mu_N} \left[ \int_{\tau}^{\tau+t} N^2 \left( \mathcal{L}_N(\pi_s^N) \right)^2 - 2 \langle \pi_s^N, G \rangle \mathcal{L}_N(\pi_s^N, G) \right] ds.
\]

Above we used the fact that
\[
\mathcal{N}_t^N(\pi_s) = \left[ \mathcal{M}_t^N(\pi_s) \right]^2 - \int_0^t \left[ N^2 \mathcal{L}_N(\pi_s^N, G)^2 - \langle \pi_s^N, G \rangle N^2 \mathcal{L}_N(\pi_s^N, G) \right] ds
\]

(12)
is a martingale (see, e.g., Appendix 1 of [15]). A simple computation shows that, for $\eta \in \Omega_N$, it holds
\[
N^2 \mathcal{L}_N(\pi^N, G)^2 - 2 \langle \pi^N, G \rangle \mathcal{L}_N(\pi^N, G)
= \frac{N^2}{(N-1)^3} \sum_{x=1}^{N-2} \left\{ \eta(x)[\alpha - \eta(x + 1)] + \eta(x + 1)[\alpha - \eta(x)] \right\} \times \left[ G \left( \frac{x+1}{N} \right) - G \left( \frac{x}{N} \right) \right]^2 + \frac{N^2}{N^2(N-1)^2}
\]
\[
\times \left[ (\gamma \eta(1) + \epsilon(\alpha - \eta(1))) G^2 \left( \frac{1}{N} \right) + (\beta \eta(N - 1) + \delta(\alpha - \eta(N - 1))) G^2 \left( \frac{N-1}{N} \right) \right].
\]

Since \( G \in C^2_+([0, 1]) \), last display vanishes as \( N \to +\infty \), from where the proof ends. \( \Box \)

### 3.2 Characterization of Limit Points

In this subsection we explain how to get the integral notions of weak solutions from the microscopic system. Our starting point is Dynkin’s formula which tells us that for \( G \) regular enough

\[
\mathcal{M}_t^N (G) := \langle \pi_t^N, G_t \rangle - \langle \pi_0^N, G_0 \rangle - \int_0^t \langle \pi_s^N, \partial_s G_s \rangle + \alpha \langle \pi_s^N, \Delta_N G_s \rangle ds
\]

\[
- \int_0^t \left\{ \frac{\epsilon + \gamma}{(N - 1)N^\theta} N^2 \left[ \rho_+ - \eta sN^2(1) \right] G_s \left( \frac{1}{N} \right)

+ \alpha \frac{N}{N - 1} sN^2(1) \nabla_N^+ G_s(0) \right\} ds
\]

\[
+ \int_0^t \left\{ \frac{\delta + \beta}{(N - 1)N^\theta} N^2 \left[ \rho_+ - \eta sN^2(N - 1) \right] G_s \left( \frac{N-1}{N} \right) \right\} ds
\]

is a martingale. Above we used the usual notations for the discrete laplacian and derivative, i.e.

\[
\Delta_N G (x \in \Lambda_N) := N^2 \left[ G \left( \frac{x-1}{N} \right) - 2G (x \in \Lambda_N) + G \left( \frac{x+1}{N} \right) \right] \quad \text{and}
\]

\[
\nabla_N^+ G (x \in \Lambda_N) := N \left[ G \left( \frac{x+1}{N} \right) - G (x \in \Lambda_N) \right].
\]

From the computations of the previous proof we know that the martingale \( \mathcal{M}_t^N (G) \) vanishes in \( L^2(\mathbb{P}_{\mu_N}) \) as \( N \to +\infty \). It remains to analyse the other terms. From here on we take into account the value of \( \theta \). We present the argument for \( \theta \geq 1 \), since for \( \theta < 1 \) the test function \( G \in C^{1,2}_c([0, T] \times [0, 1]) \) and the argument is much simpler. We note that in the proof of tightness we took, for simplicity, a time independent test function. However, now we need to consider time dependent test functions, nevertheless all the arguments used to prove tightness carry out analogously. Now, for \( \theta \geq 1 \) we assume that \( G \in C^{1,2}_c([0, T] \times [0, 1]) \). We start with \( \theta > 1 \) and we see that

\[
\mathcal{M}_t^N (G) = \langle \pi_t^N, G_t \rangle - \langle \pi_0^N, G_0 \rangle - \int_0^t \langle \pi_s^N, (\partial_s G_s + \alpha \Delta_N G_s) \rangle ds
\]

\[
- \int_0^t \left\{ \alpha \eta sN^2(1) \nabla_N^+ G_s(0) - \alpha \eta sN^2(N - 1) \nabla_N^+ G_s \left( \frac{N-1}{N} \right) \right\} ds + O(N^{1-\theta})
\]
is a martingale. Since $G$ is of class $C^2([0, 1])$, from Lemma 4.3, last identity is equivalent to

$$M^N_t(G) = \langle \pi_t^N, G_t \rangle - \langle \pi_0^N, G_0 \rangle - \int_0^t \langle \pi_s^N, (\partial_s G_s + \alpha \Delta N G_s) \rangle ds$$

$$+ O(N^{1-\theta}) + o(1),$$

plus terms whose $L^1(\mathbb{P}_{\mu^N})$-norm vanishes as $N \to +\infty$ and then $\epsilon \to 0$. Now fix $\theta = 1$. Again from Lemma 4.3 we get that

$$M^N_t(G) = \langle \pi_t^N, G_t \rangle - \langle \pi_0^N, G_0 \rangle - \int_0^t \langle \pi_s^N, (\partial_s G_s + \alpha \Delta N G_s) \rangle ds$$

$$- \int_0^t \{ (\epsilon + \gamma) \left[ \rho_+ - \eta^\epsilon_{sN^2}(1) \right] G_s \left( \frac{1}{N} \right) + \alpha \eta^\epsilon_{sN^2}(1) \nabla^+_N G_s (0) \} ds$$

$$+ \int_0^t \{ \alpha \eta^\epsilon_{sN^2}(N - 1) \nabla^+_N G_s \left( \frac{N-1}{N} \right) \} ds + o(1).$$

Now we can conclude the argument in all cases. To recognize the limiting equations it is enough to observe the following facts. First, note that for any $x \in \Lambda_N$ it holds $\eta^\epsilon_t(x) = \langle \pi_t^N, \xi^{x/N}_\epsilon \rangle$, where for $v \in [0, 1]$, $\xi^{x/N}_\epsilon(u) = \epsilon^{-1} 1_{[v, v+\epsilon]}(u)$. From tightness, we know the convergence of a subsequence $\pi_t^{N_k}(\eta, du)$ to $\pi_t(du)$, given by $\pi_t(du) = \rho_t(u) du$. Moreover, since $\rho_t(u) \in [0, \alpha]$ for all $t \in [0, T]$ and $u \in [0, 1]$, from Lebesgue’s differentiation theorem we can conclude that

$$\lim_{\epsilon \to 0} \left| \rho_t(u) - \frac{1}{\epsilon} \int_u^{u+\epsilon} \rho_s(v) dv \right| = 0,$$

for almost every $u \in [0, 1]$. But to recognize the boundary conditions we need the last result to be true for the boundary points $u = 0$ and $u = 1$. This is easy and it is analogous to the proof of Lemma 6.2 in [3]. We leave the details to the reader.

### 4 Replacement Lemmas

In this section we collect several results that were used along the proofs. From here on we assume that $\varrho(\cdot)$ is a profile bounded away from zero and one, i.e. there exist $0 < a < b < 1$ such that, for all $x \in \Lambda_N$, it holds

$$0 < a \leq \varrho \left( \frac{x}{N} \right) \leq b < 1.$$
We claim that under the previous conditions, for any probability measure $\mu_N$, the entropy of $\mu_N$ with respect to the Binomial product measure of parameters $(\alpha, \varrho(N))$, i.e. the measure $\nu^N_{\varrho(\cdot)}$ given in (5), satisfies

$$H(\mu_N | \nu^N_{\varrho(\cdot)}) \lesssim N.$$ 

To prove the claim, observe that by the definition of the entropy, since $\mu_N$ is a probability measure, we have

$$H(\mu_N | \nu^N_{\varrho(\cdot)}) = \sum_{\eta \in \Omega_N} \mu_N(\eta) \log \left( \frac{\mu_N(\eta)}{\nu^N_{\varrho(\cdot)}(\eta)} \right) \nu^N_{\varrho(\cdot)}(\eta) \leq \max_{\eta \in \Omega_N} \left\{ \log \left[ \nu^N_{\varrho(\cdot)}(\eta) \right]^{-1} \right\}.$$ 

For $\eta \in \Omega_N$, recalling the expression of $\nu^N_{\varrho(\cdot)}$ given in (5), we have

$$\log \left[ \nu^N_{\varrho(\cdot)}(\eta) \right]^{-1} = \sum_{x=1}^{N-1} \log \left[ \frac{\eta(x)! [\alpha - \eta(x)]!}{\alpha!} \right] + \eta(x) \log \left[ \varrho \left( \frac{x}{N} \right)^{-1} \right] + [\alpha - \eta(x)] \log \left[ 1 - \varrho \left( \frac{x}{N} \right) \right]^{-1} \leq (N-1) \left\{ \log [\alpha!] + \alpha \log a^{-1} + \alpha \log [1-b]^{-1} \right\}.$$ 

### 4.1 Estimating Dirichlet Forms

In this section we want to compare the Dirichlet form of our model with a quadratic form, given in terms of the carré du champ operator. To properly do that we take as reference measure $\nu^N_{\varrho(\cdot)}$ given in (5) and we consider a Lipschitz continuous profile $\varrho(\cdot)$ which is bounded away from zero and one and locally constant at the boundary satisfying $\varrho(0) = \frac{\epsilon}{\epsilon + \gamma}$ and $\varrho(1) = \frac{\delta}{\delta + \beta}$.

**Lemma 4.1** For any density $f$, if $\varrho(\cdot)$ satisfies the conditions of the previous paragraph, then there exist constants $C, K > 0$ and $N_0 \in \mathbb{N}$, such that for $a \in \{\ell, r\}$, it holds

$$\langle \mathcal{L}_a \sqrt{f}, \sqrt{f} \rangle_{\nu^N_{\varrho(\cdot)}} = -\frac{1}{2} D^a_{\nu^N_{\varrho(\cdot)}}(\sqrt{f}), \forall N \geq N_0$$

and

$$\langle \mathcal{L}_{\text{bulk}} \sqrt{f}, \sqrt{f} \rangle_{\nu^N_{\varrho(\cdot)}} \leq -K D^{\text{bulk}}_{\nu^N_{\varrho(\cdot)}}(\sqrt{f}) + \frac{C}{N^2}, \forall N \geq 1,$$

where

$$D^\ell_{\nu^N_{\varrho(\cdot)}}(\sqrt{f}) := \frac{1}{N^2} \int_{\Omega_N} \left[ c_{1,0}(\eta) \left( \sqrt{f}(\eta^{1,0}) - \sqrt{f}(\eta) \right)^2 \right]$$

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\[ + c_{0,1}(\eta) \left\{ \sqrt{f'(\eta)} - \sqrt{f(\eta)} \right\}^2 d\nu^N_{\psi(\cdot)}, \]

\[ D^\text{bulk}_{\nu^N_{\psi(\cdot)}}(\sqrt{f}) := \sum_{x=1}^{N-2} D^{x,x+1}_{\nu^N_{\psi(\cdot)}}(\sqrt{f}) + D^{x+1,x}_{\nu^N_{\psi(\cdot)}}(\sqrt{f}) \]

\[ = \sum_{x=1}^{N-2} \left[ \int_{\Omega} c_{x,x+1}(\eta) \left( \sqrt{f'(\eta)} - \sqrt{f(\eta)} \right)^2 d\nu^N_{\psi(\cdot)} \right. \]

\[ + \int_{\Omega} c_{x+1,x}(\eta) \left( \sqrt{f'(\eta)} - \sqrt{f(\eta)} \right)^2 d\nu^N_{\psi(\cdot)} \],

and the definition of \( D^r_{\nu^N_{\psi(\cdot)}}(\sqrt{f}) \) is analogous to the one of \( D^\ell_{\nu^N_{\psi(\cdot)}}(\sqrt{f}) \) by replacing 0 and 1 by \( N \) and \( N - 1 \), respectively.

**Proof** We present the proof in details for the left boundary (for the right one it is analogous) and the bulk generators. For the left boundary generator we have

\[ \langle \mathcal{L}_\ell \sqrt{f}, \sqrt{f} \rangle_{\nu^N_{\psi(\cdot)}} = -\frac{1}{2} D^\ell_{\nu^N_{\psi(\cdot)}}(\sqrt{f}) \]

\[ + \frac{1}{2N^\theta} \int_{\Omega} \left[ c_{1,0}(\eta) \left\{ f(\eta^{1,0}) - f(\eta) \right\} \right. \]

\[ + c_{0,1}(\eta) \left\{ f(\eta^{0,1}) - f(\eta) \right\} \left. \right] d\nu^N_{\psi(\cdot)}. \]  

(13)

From a change of variables and the fact that

\[ v^N_{\psi(\cdot)}(\eta^{1,0}) = \frac{\eta(1)}{\alpha - \eta^{1,0}(1)} \frac{1 - \varphi(\frac{1}{N})}{\varphi(\frac{1}{N})} v^N_{\psi(\cdot)}(\eta) \] \] and

\[ v^N_{\psi(\cdot)}(\eta^{0,1}) = \frac{\alpha - \eta(1)}{\eta^{0,1}(1)} \frac{\varphi(\frac{1}{N})}{1 - \varphi(\frac{1}{N})} v^N_{\psi(\cdot)}(\eta), \]

we conclude that (13) is equal to

\[ \gamma + \epsilon \int_{\Omega} \left( \frac{\eta(1)}{\varphi(\frac{1}{N})} - \frac{\alpha - \eta(1)}{1 - \varphi(\frac{1}{N})} \right) f(\eta) \left[ \frac{\epsilon}{\epsilon + \gamma} - \varphi\left(\frac{1}{N}\right) \right] d\nu^N_{\psi(\cdot)}. \]

Observe that since \( \varphi(0) = \frac{\epsilon}{\epsilon + \gamma} \) and the profile is locally constant, last display vanishes for \( N \) sufficiently big. Finally we treat the bulk generator. Observe that by summing and subtracting proper terms, we get
\[ \langle \mathcal{L}_{\text{bulk}} \sqrt{f}, \sqrt{f} \rangle_{v_N^{(\eta)}} = -\frac{1}{4} \sum_{x=1}^{N-2} \left[ D_{v_N^{(\eta)}}^{x,x+1} (\sqrt{f}) + D_{v_N^{(\eta)}}^{x+1,x} (\sqrt{f}) \right] \\
+ \frac{1}{4} \sum_{x=1}^{N-2} \int_{\Omega_N} \left\{ c_{x,x+1}(\eta) \left[ f(\eta^{x,x+1}) - f(\eta) \right] \right\} d\nu_N^{(\eta)} \\
+ \frac{1}{4} \sum_{x=1}^{N-2} \int_{\Omega_N} \left\{ \sqrt{f}(\eta^{x,x+1}) - \sqrt{f}(\eta) \right\} \sqrt{f}(\eta) d\nu_N^{(\eta)} \\
+ \frac{1}{2} \sum_{x=1}^{N-2} \int_{\Omega_N} \left\{ \sqrt{f}(\eta^{x+1,x}) - \sqrt{f}(\eta) \right\} \sqrt{f}(\eta) d\nu_N^{(\eta)}. \tag{14} \]

Now we treat the terms (15) and (16). We first make a change of variables, i.e. \( \xi = \eta^{x,x+1} \) and \( \xi = \eta^{x+1,x} \) in (15) and (16), respectively. Then, we sum and subtract appropriate terms, use the fact that

\[ c_{x+1,x}(\eta^{x+1,x})v_N^{(\eta)}(\eta^{x+1,x}) = \frac{1}{a_x} c_{x,x+1}(\eta)v_N^{(\eta)}(\eta), \]
\[ c_{x,x+1}(\eta^{x+1,x})v_N^{(\eta)}(\eta^{x+1,x}) = a_x c_{x+1,x}(\eta)v_N^{(\eta)}(\eta), \tag{17} \]

where

\[ a_x := \frac{\varrho(x/N)(1 - \varrho(x+1/N))}{\varrho(x+1/N)(1 - \varrho(x/N))}. \tag{18} \]

From this we obtain that (15) + (16) is equal to

\[ -\sum_{x=1}^{N-2} \frac{1}{4a_x} D_{v_N^{(\eta)}}^{x,x+1} (\sqrt{f}) - \sum_{x=1}^{N-2} \frac{a_x}{4} D_{v_N^{(\eta)}}^{x+1,x} (\sqrt{f}) \\
+ \sum_{x=1}^{N-2} \frac{1}{4a_x} \int_{\Omega_N} c_{x,x+1}(\eta) \left[ f(\eta) - f(\eta^{x,x+1}) \right] d\nu_N^{(\eta)} \\
+ \sum_{x=1}^{N-2} \frac{a_x}{4} \int_{\Omega_N} c_{x+1,x}(\eta) \left[ f(\eta) - f(\eta^{x+1,x}) \right] d\nu_N^{(\eta)}. \]
From the previous results we obtain

\[
\langle L_{\text{bulk}}, \sqrt{f}, \sqrt{f} \rangle_{\nu N} = -\frac{1}{4} \left[ \sum_{x=1}^{N-2} \left( 1 + \frac{1}{a_x} \right) D_{\nu N}^{x,x+1} (\sqrt{f}) + \sum_{x=1}^{N-2} \left( 1 + a_x \right) D_{\nu N}^{x+1,x} (\sqrt{f}) \right] \\
+ \sum_{x=1}^{N-2} \frac{1}{4} \int_{\Omega_N} c_{x+1,x} (\eta) \left[ f(\eta^{x+1,x}) - f(\eta) \right] (1 - a_x) d\nu N_{\cdot} \\
+ \sum_{x=1}^{N-2} \frac{1}{4} \int_{\Omega_N} c_{x,x+1} (\eta) \left[ f(\eta^{x,x+1}) - f(\eta) \right] (1 - \frac{1}{a_x}) d\nu N_{\cdot}.
\]

By using the identity \((x - y) = (\sqrt{x} - \sqrt{y})(\sqrt{x} + \sqrt{y})\) for \(x, y \geq 0\), Young’s inequality and the inequality \((x + y)^2 \leq 2(x^2 + y^2)\), we get that

\[
\langle L_{\text{bulk}}, \sqrt{f}, \sqrt{f} \rangle_{\nu N} \leq -\frac{1}{4} \left[ \sum_{x=1}^{N-2} \left( \frac{1}{2} + \frac{1}{a_x} \right) D_{\nu N}^{x,x+1} (\sqrt{f}, \nu N) \right] \\
+ \sum_{x=1}^{N-2} \left( \frac{1}{2} + a_x \right) D_{\nu N}^{x+1,x} (\sqrt{f}) \\
+ \sum_{x=1}^{N-2} \frac{1}{4} \int_{\Omega_N} c_{x+1,x} (\eta) \left[ f(\eta^{x+1,x}) + f(\eta) \right] (1 - a_x)^2 d\nu N_{\cdot} \\
+ \sum_{x=1}^{N-2} \frac{1}{4} \int_{\Omega_N} c_{x,x+1} (\eta) \left[ f(\eta) + f(\eta^{x,x+1}) \right] (1 - \frac{1}{a_x})^2 d\nu N_{\cdot}.
\]

The proof now ends by using the fact that \(f\) is a density, the fact that \(\nu N_{\cdot}\) is Lipschitz continuous and bounded away from zero and one; and the definition of \(a_x\) given in (18). \(\square\)

### 4.2 Replacement Lemmas: at the Boundary and at the Bulk

We start with the replacement lemma needed at the boundary for the Dirichlet case \((\theta < 1)\) and then we prove the replacement lemma at the bulk needed in all cases \((\theta \in \mathbb{R})\).

**Lemma 4.2** If \(\theta < 1\), for any \(t \in [0, T]\) and for \(x = 1\) it holds

\[
\lim_{N \to +\infty} \mathbb{E}_{\mu_N} \left[ \int_0^t \left( \nu N_{\cdot} - \eta s N^2(x) \right) ds \right] = 0. \tag{19}
\]

The same result is true for \(x = N - 1\) and with \(\nu \) instead of \(\nu_{\cdot}\).

**Proof** Let \(\nu N_{\nu(\cdot)}\) be the product measure defined in (5) and we assume that the profile satisfies the conditions exposed in the beginning of Sect. 4.1. From entropy’s and
Jensen’s inequalities, we bound the expectation appearing in the statement of the lemma by

\[ \frac{H(\mu_N|\nu_N)}{BN} + \frac{1}{BN} \log \left( \mathbb{E}_{\nu_N} \left[ e^{\int_0^t BN \left( \eta_{N2}(1) - \varrho \right) ds} \right] \right), \]

(20)

for \( B > 0 \). From the computations in the beginning of this section we know that \( H(\mu_N|\nu_N) \lesssim N \). Moreover, from the inequality \( e^{|x|} \leq e^x + e^{-x} \), the fact that

\[ \limsup_{N \to \infty} \frac{1}{N} \log(a_N + b_N) = \max \left\{ \limsup_{N \to \infty} \frac{1}{N} \log(a_N), \limsup_{N \to \infty} \frac{1}{N} \log(b_N) \right\}, \]

(21)

and from Feynman–Kac’s formula, (20) is bounded from above by a constant times

\[ \frac{1}{B} + \frac{1}{BN} \int_0^t \sup_{f \text{ density}} \left\{ BN \langle \eta(1) - \varrho, f \rangle_{\nu_N^1} + N^2 \langle \mathcal{L}_N \sqrt{f}, \sqrt{f} \rangle_{\nu_N^1} \right\} ds. \]

(22)

Our goal now consists in estimating the term \( \langle \eta(1) - \varrho, f \rangle_{\nu_N^1} \). We split the state space into disjoint hyper-planes with a fixed number of particles at the site 1, i.e. \( \Omega_N = \bigcup_{i=0}^{\alpha} \Omega_i \), where

\[ \Omega_i = \{ \eta \in \Omega_N \mid \eta(1) = i \}. \]

Fix \( i \in \{0, \ldots, \alpha\} \). Observe that from a change of variables \( \xi = \eta^{0.1} \) and \( \tilde{\xi} = \eta^{1.0} \), we get

\[ \int_{\Omega_i} \gamma \eta(1) f(\eta) d\nu_N^1 = 1_{[1 \leq i \leq \alpha]} \int_{\Omega_i} \gamma [\alpha - \eta(1)] f(\eta^{0.1}) \frac{\varrho(\frac{1}{N})}{1 - \varrho(\frac{1}{N})} d\nu_N^1, \]

(23)

\[ \int_{\Omega_i} \epsilon [\alpha - \eta(1)] f(\eta) d\nu_N^1 = 1_{[0 \leq i \leq \alpha - 1]} \int_{\Omega_i} \epsilon \eta(1) f(\eta^{1.0}) \frac{1 - \varrho(\frac{1}{N})}{\varrho(\frac{1}{N})} d\nu_N^1. \]

(24)

Using the identity

\[ \eta(1) - \varrho = \frac{-1}{\epsilon + \gamma} \left( -\gamma \eta(1) + \epsilon [\alpha - \eta(1)] \right), \]

instead of estimating \( \langle \eta(1) - \varrho, f \rangle_{\nu_N^1} \), we estimate \( (\epsilon + \gamma) \langle \eta(1) - \varrho, f \rangle_{\nu_N^1} \), which is enough for our purposes. Note that we can write
\[
\langle -\gamma \eta(1) + \epsilon[\alpha - \eta(1)], f \rangle_{\nu^N_{\psi(\cdot)}} = \frac{1}{2} \sum_{i=0}^{\alpha} \int_{\Omega_i} \epsilon[\alpha - \eta(1)] f(\eta) d\nu^N_{\rho(\cdot)} \\
- \frac{1}{2} \sum_{i=0}^{\alpha} \int_{\Omega_i} \gamma \eta(1) f(\eta) d\nu^N_{\psi(\cdot)} \\
+ \frac{1}{2} \sum_{i=0}^{\alpha} \int_{\Omega_i} \epsilon[\alpha - \eta(1)] f(\eta) d\nu^N_{\rho(\cdot)} \\
- \frac{1}{2} \sum_{i=1}^{\alpha} \int_{\Omega_i} \gamma \eta(1) f(\eta) d\nu^N_{\psi(\cdot)}.
\]

From (23) and (24), we get
\[
\langle -\gamma \eta(1) + \epsilon[\alpha - \eta(1)], f \rangle_{\nu^N_{\psi(\cdot)}} \\
= \frac{1}{2} \sum_{i=0}^{\alpha} \int_{\Omega_i} \epsilon[\alpha - \eta(1)][f(\eta) - f(\eta^{0.1})] d\nu^N_{\psi(\cdot)} \\
- \frac{1}{2} \sum_{i=0}^{\alpha} \int_{\Omega_i} \gamma \eta(1)[f(\eta) - f(\eta^{1.0})] d\nu^N_{\psi(\cdot)} \\
+ \frac{1}{2} \sum_{i=0}^{\alpha} \int_{\Omega_i} \left\{ \frac{\epsilon(1 - \psi(\frac{1}{N}))}{\psi(\frac{1}{N})} - \gamma \right\} \eta(1) f(\eta^{1.0}) d\nu^N_{\psi(\cdot)} \\
- \frac{1}{2} \sum_{i=0}^{\alpha} \int_{\Omega_i} \left\{ \frac{\gamma \psi(\frac{1}{N})}{1 - \psi(\frac{1}{N})} - \epsilon \right\} [\alpha - \eta(1)] f(\eta^{0.1}) d\nu^N_{\psi(\cdot)}.
\]

Since the profile \(\psi(\cdot)\) is locally constant equal to \(\frac{\epsilon}{\epsilon + \gamma}\) at 0, then, the last line vanishes for \(N\) sufficiently big. It remains to analyse the first line of last display. To that end, using the identity \((x - y) = (\sqrt{x} - \sqrt{y})(\sqrt{x} + \sqrt{y})\) for \(x, y \geq 0\), and Young’s inequality, we get for \(A > 0\):
\[
\langle -\gamma \eta(1) + \epsilon[\alpha - \eta(1)], f \rangle_{\nu^N_{\psi(\cdot)}} \\
\leq \frac{N^\theta}{4A} D^\epsilon_{\psi(\cdot)} \langle \sqrt{f} \rangle + \frac{A}{2} \int_{\Omega_N} \gamma \eta(1)[f(\eta) + f(\eta^{1.0})] \\
+ \epsilon[\alpha - \eta(1)][f(\eta) + f(\eta^{0.1})] d\nu^N_{\psi(\cdot)}.
\]

To conclude the proof it is enough to invoke Lemma 4.1, choose \(A = \frac{N^\theta B}{4K N}\) and use the fact that \(f\) is a density. Then, (22) vanishes by taking the limit in \(N \to +\infty\) and then \(B \to +\infty\). \(\square\)
Lemma 4.3 For any $\theta \in \mathbb{R}$, for any $t \in [0, T]$ and $z = 1$ it holds

$$
\lim_{\epsilon \to 0} \lim_{N \to +\infty} \mathbb{E}_{\mu_N} \left[ \left| \int_0^t \eta_{\epsilon N^2}(z) - \eta_{\lfloor \epsilon N \rfloor \epsilon_N^2}(z) ds \right| \right] = 0,
$$

where, for $L \in \mathbb{N}$, $\eta^L(z) := \frac{1}{L} \sum_{y=z+1}^{z+L} \eta(y)$.

The proof is analogous for $z = N - 1$ but taking instead the average to the left, i.e. $\eta^L(z) := \frac{1}{L} \sum_{y=z-L}^{z-1} \eta(y)$.

Proof Fix $L \in \mathbb{N}$. Repeating the first steps of the previous proof, the expectation in the statement of the lemma is bounded from above, for any constant $B > 0$, by

$$
\frac{1}{B} + t \sup_{f \text{ density}} \left\{ \langle \eta(z) - \eta^L(z), f \rangle_{\nu_N} + \frac{N}{B} \langle \mathcal{L}_N \sqrt{f}, \sqrt{f} \rangle_{\nu_N} \right\}.
$$

Observe that

$$
\eta(z) - \eta^L(z) = \frac{1}{L} \sum_{y=z+1}^{z+L} [\eta(z) - \eta(y)] = \frac{1}{L} \sum_{y=z+1}^{z+L} \sum_{x=z}^{y-1} [\eta(x) - \eta(x+1)].
$$

Since $\alpha[\eta(x) - \eta(x+1)] = c_{x,x+1}(\eta) - c_{x+1,x}(\eta)$, we will analyze $\langle c_{x,x+1}(\eta) - c_{x+1,x}(\eta), f \rangle_{\nu_N}$. By writing the last integral as twice its half and decomposing $\Omega_N = \bigcup_{i,j=0}^\alpha \Omega_{i,j}$, where

$$
\Omega_{i,j} := \{ \eta \in \Omega_N \mid \eta(x) = i, \eta(x+1) = j \},
$$

we get that

$$
\int (c_{x,x+1}(\eta) - c_{x+1,x}(\eta)) f(\eta) d\nu_N^{\eta(x)} = \frac{1}{2} \int (c_{x,x+1}(\eta) - c_{x+1,x}(\eta)) f(\eta) d\nu_N^{\eta(x)}
$$

$$
+ \frac{1}{2} \sum_{i=1}^\alpha \sum_{j=0}^{\alpha-1} \int_{\Omega_{i,j}} c_{x,x+1}(\eta) f(\eta) d\nu_N^{\eta(x)}
$$

$$
- \frac{1}{2} \sum_{i=0}^{\alpha-1} \sum_{j=1}^\alpha \int_{\Omega_{i,j}} c_{x+1,x}(\eta) f(\eta) d\nu_N^{\eta(x)}.
$$

Recall (17) and (18). Changing variables $\xi = \eta^{x,x+1}$ and $\xi = \eta^{x+1,x}$ in (27) and then making a change of variables in the summations, we can rewrite the last display as
Now we invoke Lemma 4.1 and we make the choice above

\[
\frac{1}{2} \int (c_{x,x+1}(\eta) - c_{x+1,x}(\eta)) f(\eta) d\nu_{\nu(\cdot)}^N \\
+ \frac{1}{2} \sum_{i=0}^{a-1} \sum_{j=1}^{a} \int_{\Omega_{i,j}} c_{x+1,x}(\eta) a_x f(\eta^{x+1,x}) d\nu_{\nu(\cdot)}^N \\
- \frac{1}{2} \sum_{i=1}^{a} \sum_{j=0}^{a-1} \int_{\Omega_{i,j}} c_{x,x+1}(\eta) \frac{1}{a_x} f(\eta^{x,x+1}) d\nu_{\nu(\cdot)}^N.
\]

By summing and subtracting appropriate terms we can rewrite the previous expression as

\[
\frac{1}{2} \int c_{x,x+1}(\eta)[f(\eta) - f(\eta^{x,x+1})] d\nu_{\nu(\cdot)}^N - \frac{1}{2} \int c_{x+1,x}(\eta)[f(\eta) - f(\eta^{x+1,x})] d\nu_{\nu(\cdot)}^N \\
+ \frac{1}{2} \int c_{x+1,x}(\eta)(a_x - 1) f(\eta^{x+1,x}) d\nu_{\nu(\cdot)}^N - \frac{1}{2} \int c_{x,x+1}(\eta) \left( \frac{1}{a_x} - 1 \right) f(\eta^{x,x+1}) d\nu_{\nu(\cdot)}^N.
\]

From the identity \((x - y) = (\sqrt{x} - \sqrt{y})(\sqrt{x} + \sqrt{y})\) for \(x, y \geq 0\), and Young’s inequality we bound the last display from above by

\[
\frac{1}{4A} D^{x,x+1}_{\nu(\cdot)}(\sqrt{\bar{f}}) + \frac{1}{4A} D^{x+1,x}_{\nu(\cdot)}(\sqrt{\bar{f}}) \\
+ \frac{A}{4} \int c_{x,x+1}(\eta)[\sqrt{\bar{f}}(\eta) + \sqrt{\bar{f}(\eta^{x,x+1})}]^2 d\nu_{\nu(\cdot)}^N \\
+ \frac{A}{4} \int c_{x+1,x}(\eta)[\sqrt{\bar{f}}(\eta) + \sqrt{\bar{f}(\eta^{x+1,x})}]^2 d\nu_{\nu(\cdot)}^N \\
+ \frac{1}{2} \int c_{x+1,x}(\eta)(a_x - 1) f(\eta^{x+1,x}) d\nu_{\nu(\cdot)}^N \\
- \frac{1}{2} \int c_{x,x+1}(\eta) \left( \frac{1}{a_x} - 1 \right) f(\eta^{x,x+1}) d\nu_{\nu(\cdot)}^N.
\]

From these computations, we see that

\[
\langle \eta(z) - \eta^L(z), f \rangle_{\nu_{\nu(\cdot)}^N} \\
\lesssim \frac{1}{L} \sum_{y=z+1}^{z+L} \sum_{x=z}^{y-1} \left[ \frac{1}{4A} \left( D^{x,x+1}_{\nu(\cdot)}(\sqrt{\bar{f}}) + D^{x+1,x}_{\nu(\cdot)}(\sqrt{\bar{f}}) \right) + A + \left| \varphi\left(\frac{x}{N}\right) - \varphi\left(\frac{x+1}{N}\right) \right| \right].
\]

Now we invoke Lemma 4.1 and we make the choice above \(A = \frac{B}{4NK} \). Taking \(L = \lfloor \epsilon N \rfloor \), since the profile is Lipschitz continuous we have that

\[
\frac{1}{L} \sum_{y=z+1}^{z+L} \sum_{x=z}^{z+L-1} |\varphi\left(\frac{x}{N}\right) - \varphi\left(\frac{x+1}{N}\right) | \lesssim \epsilon.
\]
To conclude the proof it is enough to take the limit as $N \to +\infty$, $\epsilon \to 0$ and then $B \to +\infty$. □

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