Research Article

Optimal Selling Strategies under Regime-Switching Market Environment with Finite Expiry

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Received 9 June 2021; Revised 11 August 2021; Accepted 31 August 2021; Published 30 September 2021

Academic Editor: Xiaohua Ding

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This paper addresses an optimal stock liquidation problem over a finite-time horizon; to that end, we model it as an optimal stopping problem in a regime-switching market. The optimal stopping time is written as a solution to a system of Volterra type integral equations. Moreover, it reveals that when the risk-free interest rate is always lower than the return rate of the stock, it is never optimal to sell the stock early; otherwise, one should sell the stock in bear market if the stock price reaches a critical value and hold the stock in bull market until the maturity date. Finally, we present a trinomial tree method for numerical implementation. The numerical results are consistent with the theoretical findings.

1. Introduction

“What is the best time to sell an asset to maximize revenue?” is a fundamental problem in finance. Given a fixed transaction cost, the objective is to choose a stopping time so as to maximize an expected return. This kind of optimal stopping problem was studied by McKean firstly under Black–Scholes model [1]. It is well known that the stochastic variability in the market parameters is not reflected in the Black–Scholes model. At present, the market trend is considered in literature when dealing with the optimal stock liquidation problem. In [2], Wang et al. proposed a Markov regime-switching DCC-GARCH model and estimated the model parameters by a two-stage maximum likelihood method. Hou et al. presented a spatial-temporal neural network frame to forecast the stock price movement [3]. In [4], Zhang provided a suboptimal selling rule in a regime-switching market by a two-point-boundary approach. For regime-switching exponential Gaussian diffusion model, Elo et al. used a similar approach to derive an optimal selling rule by two threshold levels [5]. Guo and Zhang used a smooth-fit technique to analyze the optimal selling boundary under certain parameter conditions for infinite horizonal problem [6]. The finite horizonal optimal selling rule under regime-switching model was firstly studied by Pemy and Zhang using viscosity solution approach [7]. Later, Pemy studied a similar problem in the case where the underlying dynamic is a Markov switching Lévy process [8]. Bian et al. investigated the optimal liquidation problem with regime-switching until the exit time, which is essentially an optimal control problem rather than an optimal stopping problem [9]. Recently, Vaicenavicius put forward an optimal liquidation problem involved with drift uncertainty and regime-switching volatility and solved it by constructing approximating sequences of optimal stopping problem with constant volatility [10].

It is known that Pemy and Zhang only discussed the value function to the related HJB equation, and up to the
author’s knowledge, the optimal selling strategies under regime-switching model are still unknown so far [7]. In filling this gap, this paper is concerned with the optimal selling strategies. That is, we mainly focus on the early exercise boundary with respect to the optimal stopping problem rather than the value function. Indeed, the role of the present paper should be viewed as a supplement to [7]. On the other hand, the impacts of varying parameters on the selling decision were not discussed in [7]. We discuss it rigorously by variational inequality approach. It is important to distinguish this paper from the existing literature on optimal stopping problems with regime-switching volatility. Buffington and Elliott discussed American options in regime-switching market and obtained an approximate valuation of American option [11]. Jacka and Ocejo studied the regularity of the value function for a finite horizontal optimal stopping problem in the presence of regime-switching uncertainty [12]. The abovementioned authors mainly concentrated on the value function and did not investigate the free boundary arising from American option pricing problem. Boyarchenko and Levendorski calculated the early exercise boundaries for American options by using a generalization of Carr’s randomization procedure for regime-switching models [13]. But they did not study the properties of the free boundary and the early exercise premium was unknown. Liu and Privault dealt with optimal prediction of the free boundary and the early exercise premium was switching models [13]. But they did not study the properties of free boundary, integral equation for the free boundary, and sensitivity analysis of the free boundary. In Section 5, we use the trinomial tree method mentioned in [17] to calculate the optimal stopping problem and perform some numerical experiments. Finally, Section 6 concludes.

2. Problem Set-Up

Consider a probability space \((\Omega, \mathcal{F}, P)\). Consider also a standard Brownian motion \(B = \{B_t, t \geq 0\}\). We assume that the continuous time Markov chain \(\alpha = \{\alpha_t, t \geq 0\}\) takes values in \(\mathcal{S} = \{1, 2\}\), i.e. there are only two states: “bull” and “bear,” and the generator of \(\alpha_t\) is of the form

\[
\mathcal{A} = \begin{pmatrix}
-\lambda_1 & \lambda_1 \\
\lambda_2 & -\lambda_2
\end{pmatrix},
\]

where \(\lambda_1\) and \(\lambda_2\) are the positive constants. We denote by \(\mathcal{F} = \{\mathcal{F}_t, t \geq 0\}\) the \(P\)-augmentation of the filtration \(\{\mathcal{F}_{t, t}^{B, \alpha}, t \geq 0\}\) generated by the stochastic process \(B\) and \(\alpha\). Here, \(\{\mathcal{F}_{t, t}^{B, \alpha} = \sigma(B_\tau, \alpha_\tau); 0 \leq \tau \leq t\}\) for \(t \in [0, +\infty)\). Moreover, the stock price satisfies the following Markovian switching stochastic differential equation:

\[
dX_t = X_t(\mu(\alpha_t)dt + \sigma(\alpha_t)dB_t), \quad s > t, \\
X_s = x,
\]

where \(x\) is the initial stock price, \(\mu(\alpha_t) \in \left[\mu_1, \mu_2\right]\) is the rate of return, and \(\sigma(\alpha_t) \in \left[\sigma_1, \sigma_2\right]\) is the volatility.

Let \(\Lambda_{x,T}\) denote the set of all \(\mathcal{F}_t\)-stopping times taking value in \([t, T]\) a.s. Given a transaction cost \(\kappa > 0\), the agent aims to maximize \(E[e^{-r(T-t)}(X_T - a)]\) by choosing a stopping time \(\tau\), where \(r\) is the risk-free interest rate. Therefore, we consider the optimal stopping problem as follows:

\[
V(t, x, i) = \sup_{\tau \in \Lambda_{x,T}} \mathbb{E}\left[e^{-r(T-t)}(X_T^{i \tau} - a)\middle| X_\tau = x, \alpha_\tau = i\right],
\]

where \(X_T^{i \tau} = \{X_t^{i \tau}, s \geq t\}\) is the strong solution to the SDE (2) starting from \(x\) at time \(t\).

Denote \(g(x) = x - a\). By Markov property of \(X\), we can rewrite the optimal stopping problem as follows:

\[
V(t, x, i) = \sup_{\tau \in \Lambda_{x,T}} \mathbb{E}[e^{-rT}g(X_T^\tau)], \quad i \in \mathcal{S},
\]

where \(X^x = X_0^x\) is the strong solution to the SDE (2) starting from \(x\) at time \(0\) and \(\mathbb{E}[\cdot | X_0 = x, a_0 = i] = \mathbb{E}^{i \tau}[\cdot]\). For simplicity, we will always omit the superscripts in \(\mathbb{E}^{i \tau}\).

Besides, we assume that the following assumption holds throughout this paper.

Assumption 1. The rate of return satisfies \(\mu(1) = \mu_1 < \mu_2 = \mu(2)\).
3. Some Preliminary Results

The following notations will be used throughout this paper. Define the stopping region and continuation region as follows:
\[ \mathcal{D} = \{(t, x, i) \in [0, T] \times (0, +\infty) \times \delta': V(t, x, i) = g(x)\}, \]
\[ \mathcal{C} = \{(t, x, i) \in [0, T] \times (0, +\infty) \times \delta': V(t, x, i) > g(x)\}, \]
\[ \mathcal{D}_i = \{(t, x) \in [0, T] \times (0, +\infty): V(t, x, i) = g(x)\}, \quad i \in \delta, \]
\[ \mathcal{C}_i = \{(t, x) \in [0, T] \times (0, +\infty): V(t, x, i) > g(x)\}, \quad i \in \delta. \]

Lemma 2. For each \( t, x, i \), \( \eta \) has the following notations will be used throughout this paper. Define the stopping region and continuation region as follows:
\[ D \] is Lipschitz continuous in \( \mathbb{R}^+ \times \delta \), the function \( V(t, x, i) \) is 1/2–Hölder continuous uniformly over a neighborhood of \( x \); for each \( (t, i) \in [0, T] \times \delta \), the value function \( V(t, x, i) \) is Lipschitz continuous in \( \mathbb{R}^+ \). Moreover, it has at most linear growth rate, i.e., there exists a constant \( C \) such that \( |V(t, x, i)| \leq C(1 + |x|) \).

Proof. For the proof, we refer to Appendix B.

Next, we show that \( V(\cdot, x, i) \) is 1/2–Hölder continuous and \( V(t, \cdot, i) \) is Lipschitz continuous.

Lemma 2. For each \( (x, i) \in \mathbb{R}^+ \times \delta \), the function \( V(t, x, i) \) is 1/2–Hölder continuous uniformly over a neighborhood of \( x \); for each \( (t, i) \in [0, T] \times \delta \), the value function \( V(t, x, i) \) is Lipschitz continuous in \( \mathbb{R}^+ \). Moreover, it has at most linear growth rate, i.e., there exists a constant \( C \) such that \( |V(t, x, i)| \leq C(1 + |x|) \).

Proof. For the proof, we refer to Appendix B.

It is clear that
\[ \mathbb{E} \left[ \sup_{0 \leq s \leq T} e^{-rs} |X_s - a| \right] \leq \mathbb{E} \left[ \sup_{0 \leq s \leq T} e^{-rs} |X_s| \right] + a + \infty, \]
where the last inequality follows from the moment estimates (see [18] or [12]). By Corollary 2.9 in [19], the above inequality together with the fact that \( V \) and \( g \) are continuous (Lemma 2) implies that
\[ \tau_{\mathcal{D}}(t, x, i) = \inf \{0 \leq s \leq T - t: (t + s, X_{t+s}, a_s) \in \mathcal{D}\} \]
is an optimal stopping time in (4).

The next important lemma gives the property of discounted stock price process. The proof can be found in [6].

Lemma 3. Suppose that \( \eta > \bar{\eta} \) are two roots of
\[ x^2 - (\mu_1 - \lambda_1 + \mu_2 - \lambda_2)x + (\mu_1 - \lambda_1)(\mu_2 - \lambda_2) - \lambda_1\lambda_2 = 0, \]
where \( \lambda_1, \lambda_2 \) are defined in (1). If \( \eta > \tau \), then \( e^{-\eta X_t} \) is a submartingale. If \( \eta \leq \tau \), then \( e^{-\eta X_t} \) is a supermartingale.

Remark 1. Under Assumption 1, a direct computation shows
\[ \eta = \frac{\mu_1 - \lambda_1 + \mu_2 - \lambda_2 + \sqrt{\Gamma}}{2}, \]
where
\[ \Gamma = (\mu_1 - \lambda_1 + \mu_2 - \lambda_2)^2 - 4((\mu_1 - \lambda_1)(\mu_2 - \lambda_2) - \lambda_1\lambda_2). \]

Simple calculation gives that
\[ \left( \mu_2 - \mu_1 + \lambda_2 - \lambda_1 \right)^2 - \Gamma = 4\lambda_2(\mu_2 - \mu_1) > 0, \]
\[ \Gamma - (\mu_1 + \lambda_1 - \mu_2 + \lambda_2)^2 = -4\lambda_1(\mu_1 - \mu_2) > 0, \]
which implies that \( \mu_1 < \eta < \mu_2 \). We will see that the root \( \eta \) affects the shape of the stopping region in the following proposition and the next section. Economically speaking, the decisions to sell the stock are closely related to \( \eta \).

Proposition 1. Let \( \eta \) be defined by (10).

Case 1. If \( \eta > \tau \), then the optimal stopping time \( \tau_{\mathcal{D}} = T - t \), and
\[ V(t, x, i) = \mathbb{E} \left[ e^{-\tau T} g(X_T^x) \right]. \]

Case 2. If \( \eta \leq \tau \), then the function \( x \rightarrow V(t, x, i) - g(x) \) is decreasing. Moreover, \( \mathcal{D} \) is upward connected: if \( (t, x', i) \in \mathcal{D} \), then \( (t, x, i) \in \mathcal{D} \) for \( x > x' \).

Proof. If \( \eta > \tau \), by Lemma 3, it is easy to see that \( e^{-\eta X_t} g(X_t) \) is also a submartingale. By optional sampling theorem, for any \( \tau \in [0, T - t] \),
\[ \mathbb{E} \left[ e^{-\tau_{\mathcal{D}} T} g(X_T^x) \right] \leq \mathbb{E} \left[ e^{-\tau T} g(X_T^x) \right]. \]

Hence, by the definition of \( V \) (see (4)), we conclude that \( \tau = T - t \) is an optimal stopping time of problem (10) and
\[ V(t, x, i) = \mathbb{E} \left[ e^{-T-t} g(X_T^x) \right]. \]

If \( \eta \leq \tau \), for any \( x' < x \), let \( \tau \) be the optimal stopping time for \( V(t, x, i) \), then \( \tau \) is suboptimal for \( V(t, x', i) \). By Lemma 3, \( e^{-\eta X_t} \) is supermartingale. The optional sampling theorem leads to
\[ V(t, x', i) - V(t, x, i) \geq \mathbb{E} \left[ e^{-rt} \left( X_t^i - a \right) \right] - \mathbb{E} \left[ e^{-rt} \left( X_t^x - a \right) \right] \]
\[ = \mathbb{E} \left[ e^{-rt} \left( X_t^i - X_t^x \right) \right] \]
\[ = (x' - x) \mathbb{E} \left[ e^{-rt} \exp(H_t) \right] \]
\[ \geq x' - x, \]

(17)

where \( H_t \) is defined by
\[ H_t = \int_0^t \left( \mu(\alpha) - \frac{1}{2} \sigma^2(\alpha) \right) dt + \int_0^t \sigma(\alpha) dB_s. \]

(18)

This implies the monotonicity of the function \( x \rightarrow V(t, x, i) - g(x) \). If \( (t, x', i) \in \mathcal{D} \), then the above inequality leads to
\[ 0 \leq V(t, x, i) - g(x) \leq V(t, x', i) - g(x') = 0 \text{ for } x > x'. \]

(19)

That is, \((t, x, i) \in \mathcal{D}\).

\[ \square \]

Remark 2. From Proposition 1, we know that if the risk-free interest rate is always lower than the return rate of the stock, then it is never optimal to sell the stock before the maturity date.

4. Main Results

In this section, we shall investigate the shape of the stopping region of the primal problem (4). We start with some basic properties of the free boundary.

\[ \mathbb{E} \left[ e^{-rt} g(X_t^i) \right] = g(x) + \mathbb{E} \left[ \int_0^t e^{-rv} \cdot (-rg + \mathcal{L} g)(t + v, X_t^i, \alpha) dv \right]. \]

(25)

Theorem 1. Consider the problem (4) with \( \mu_1 < \eta \leq r \).

Case 1: if \( \mu_1 < \eta \leq \mu_2 \), then there exists a continuous function \( b_1(t) > 0 \) defined by
\[ b_1(t) = \inf \left\{ x : V(t, x, 1) = g(x) \right\}, \]

(20)

such that
\[ \mathcal{D}_1 = \{ (t, x) : x \geq b_1(t) \}, \]

(21)

and \( \mathcal{D}_2 = \emptyset \). Moreover, \( b_1(t) \) is nonincreasing and \( b_1(T) = ra/(r - \mu_1) \).

Case 2: if \( \mu_1 < \eta \leq \mu_2 \), then for every \( i \in \mathcal{S} \), there exists a continuous function \( b_i(t) > 0 \) defined by
\[ b_i(t) = \inf \left\{ x : V(t, x, i) = g(x) \right\}, \]

(22)

such that
\[ \mathcal{D}_i = \{ (t, x) : x \geq b_i(t) \}. \]

(23)

Moreover, \( b_i(t) \) is nonincreasing and \( b_i(T) = ra/(r - \mu_i) \) for \( i \in \mathcal{S} \).

Proof. Firstly, we assert that
\[ \{ (t, x) : -rg(x) + (\mathcal{L} g)(t, x, i) > 0 \} \subset \mathcal{C}_i, \quad i \in \mathcal{S}. \]

(24)

By Dynkin’s formula, we obtain that

\[ \mathcal{D}_i \subset \{ (t, x) : -rg(x) + (\mathcal{L} g)(t, x, i) \leq 0 \}, \quad i \in \mathcal{S}. \]

(28)

Under the assumption that \( \mu_1 < r \leq \mu_2 \), this leads to \( \mathcal{D}_1 \subset \{ (t, x) : x \geq ra/(r - \mu_1) \} \) and \( \mathcal{D}_2 = \emptyset \). Now, we shall follow the steps in [19] to show that the value function \( V(t, x, i) \) satisfies
\[ V_t(t, x, i) + (\mathcal{A} V)(t, x, i) - r V(t, x, i) = 0 \text{ in } \mathcal{C}_i. \]

(29)

Define a killed process
\[ \bar{X}_t \equiv \begin{cases} X_t, & \text{if } t < T, \\ \Delta, & \text{if } t \geq T, \end{cases} \]

where \( T \) is a random variable exponentially distributed with parameter \( r > 0 \) and independent of \( X, \Delta \) is a...
fictitious point, and all functions are assumed to take value zero at $\Delta$. By a direct computation, we have

$$
E[g(\bar{X}_t)] = E[g(X_t)1_{t<T}] + E[g(X_t)1_{t>T} | T > t] + E[g(X_t)1_{t<T} | T \leq t] \quad (31)
$$

where the second equality follows from law of total expectation and the last equality follows from the fact that $X_t$ is independent of $T$. Now, we can rewrite the value function as

$$
V(t, x, i) = E[g(\bar{X}_{\tau_{x}})]. \quad (32)
$$

We choose $(t, x, i) \in C$ and a neighborhood $U \subset C$ of $(t, x, i)$. Define $\sigma = \inf\{s \in [0, T - t] : (t + s, X^s_t, \alpha_s) \notin U\}$. It is clear $\sigma \leq \tau_{x}$. This leads to

$$
\E[V(t, x, i)] = E\left[ g(\bar{X}_{\sigma}) \cdot 1_{\sigma < \tau_{x}} \mid \mathcal{F}_t \right] = E\left[ g(\bar{X}_{t+w}) \mid \mathcal{F}_t \right] = E\left[ g\left( \bar{X}_{\tau_{x}} \right) \right] = V(t, x, i). \quad (33)
$$

Here, $\theta$ is the shift operator. This implies the characteristic operator of $(t, X_t, \alpha_t)$ is identically zero:

$$
\lim_{U \rightarrow (t, x, i)} \frac{\E[V(\sigma, X_{\sigma}, \alpha_{\sigma})] - V(t, x, i)}{\E[\sigma]} = 0. \quad (34)
$$

By the fact that the characteristic operator coincides with the infinitesimal generator of $(t, X_t, \alpha_t)$, we derive that (29) holds.

We claim that $\mathcal{D}_1 \neq \emptyset$. Otherwise, by (29) and letting $t \rightarrow T^-$, we obtain that

$$
\lim_{t \rightarrow T^-} V_t(t, x, 1) = rV(t, x, 1) - \frac{1}{2} \sigma^2 V_{xx}(t, x, 1) - \mu_1 xV_x(T, x, 1) - \lambda_1 (V(T, x, 2) - V(T, x, 1)) = (r - \mu_1)x - r\alpha > 0, \quad (35)
$$

for $x > r\alpha (r - \mu_1)$, where the second equality follows from the fact that $V(T, x, 1) = g(x)$. As $V_t(t, x, 1) \leq 0$ (Lemma 1), this leads to a contradiction. By Proposition 1 and $\mathcal{D}_1 \neq \emptyset$, we obtain that $b_1(t)$ defined by (20) is well defined and (21) holds.

We shall deduce that $b_1(t)$ is nonincreasing. Otherwise, there exist $t_1 < t_2 < T$ such that $b_1(t_1) > b_1(t_2)$. By the definition of $b_1(t)$, we derive that

$$
V(t_2, b_1(t_1)) > g(b_1(t_1)) = V(t_1, b_1(t_1)), \quad (36)
$$

This contradicts with the fact that $V(t, x, i)$ is nonincreasing (Lemma 1).

Next, we prove the continuity of $b_1(t)$. Otherwise, suppose that there exist some $t_0 \in [0, T)$ such that

$$
0 \leq \lim_{t \rightarrow t_0^-} b_1(t) < \lim_{t \rightarrow t_0^+} b_1(t) = \lim_{t \rightarrow t_0^+} b_1(t). \quad (37)
$$

Then, the domain $\mathcal{M} = (0, t_0) \times (x_2, x_1) \times \{1\} \subset C_1$. For any $\epsilon > 0$, by a similar argument as (33), we have

$$
\E[V(t, x, i)] = \E\left[ g(\bar{X}_{\tau_x}) \mid \mathcal{F}_t \right] = \E[g(\bar{X}_{\tau_x})] \leq \sup_{\tau \in \lambda_{X}} \E[g(\bar{X}_{\tau})] = V(t, x, i), \quad (38)
$$

where the inequality follows from the fact that $\tau_{x} (t + \epsilon, x, i) \leq T - (t + \epsilon)$. By Dynkin’s formula and (30), we have

$$
\E[V(t + \epsilon, \bar{X}_{\epsilon}, \alpha_{\epsilon})] - V(t, x, i) = \E[e^{-\epsilon \nu}V(t + \epsilon, x, i)] - V(t, x, i)
$$

$$
= \E\left[ \int_{0}^{\epsilon} e^{-\nu v}(V_t + \nu \lambda V - rV)(t + \nu, x, \alpha_{\epsilon})dv \right] \leq 0, \quad (39)
$$

where the last inequality follows from (38). Dividing the above inequality by $\epsilon$, letting $\epsilon \rightarrow 0$, and using the mean value theorem, we derive
\[(V_t + \mathcal{A}V - rV)(t, x, i) \leq 0. \quad (40)\]

We fix \(i = 1\) and let \(t \rightarrow t_0^+\). As \(V(t_0 + \delta, x, 1) = g(x)\) for \(\delta > 0\) and \(x \in (x_2, x_1)\), by (40), we have
\[
rV(t_0^+, x, 1) - (\mathcal{A}V)(t_0^+, x, 1) \geq V_t(t_0^+, x, 1) = 0,
\]
for \(x \in (x_2, x_1)\). \(\square\)

That means
\[
V(t_0, x, 2) = \frac{1}{\lambda_1} (rV(t_0, x, 1) - (V_t + \mathcal{A}V)(t_0, x, 1) + \lambda_1 V(t_0, x, 1)) \geq \frac{1}{\lambda_1} (r - \mu_1 + \lambda_1) x - (\lambda_1 + r)a), \quad \text{for} \ x \in (x_2, x_1),
\]
where the last inequality follows from \(V(t_0, x, 1) = g(x)\) for \(x \in (x_2, x_1)\) and \(V_t \leq 0\) (Lemma 1). By (41) and (43), as \(r > \mu_1\), we derive that
\[
V_x(t_0, x, 2) = \frac{r - \mu_1 + \lambda_1}{\lambda_1} > 1, \quad \text{for} \ x \in (x_2, x_1), \quad (44)
\]
which is in contradiction with Proposition 1. Hence, \(b_1(\cdot)\) is continuous.

Finally, we prove \(b_1(T) = ra/(r - \mu_1)\). As \(b_1(t)\) is nonincreasing and \(\mathcal{D}_1 \subset \{(t, x): x \geq ra/(r - \mu_1)\}\), we have \(b_1(t)\) is well defined and \(b_1(T) = \lim_{t \rightarrow T^-} b_1(t) \geq ra/(r - \mu_1) = x^*\). Suppose that \(b_1(T) > x^*\). For any \(\bar{x} \in (x^*, b_1(T))\), since \(V(T, x, i) = g(x)\), letting \(t \rightarrow T^-\) in (29), we have
\[
V(t, x, 1) + (\mathcal{A}V)(t, x, 1) - rV(t, x, 1) = 0 \quad \text{in} \ \mathcal{C}_1 = \{(t, x): x < b_1(t)\},
\]
\[
V(t, x, 2) + (\mathcal{A}V)(t, x, 2) - rV(t, x, 2) = 0 \quad \text{in} \ (0, T) \times (0, +\infty),
\]
\[
V(t, b_1(t), 1) = g(b_1(t)), \quad t \in [0, T),
\]
\[
V_x(t, b_1(t), 1) = 1, \quad t \in [0, T),
\]
\[
V(T, x, i) = g(x), \quad x \in (0, +\infty), i \in \mathcal{D}.
\]

In particular, the partial derivatives \(V_{xxx}, V_x, \) and \(V_t\) exist and are continuous in \(\mathcal{C}\).

Case 2: if \(\mu_1 < \eta \leq \mu_2 < r\), then the value function \(V\) defined in (4) is the unique solution to the following free boundary problem:

\[
V(t, x, i) = \frac{1}{\lambda_1} ((r - \mu_1 + \lambda_1)x - (\lambda_1 + r)a), \quad r < x < x_1.
\]

On the other hand, for any \((t, x, 1) \in \mathcal{N}_1\), by (29), letting \(t \rightarrow t_0^+\), we derive
\[
V(t_0, x, 2) = \frac{1}{\lambda_1} ((r - \mu_1 + \lambda_1)x - (\lambda_1 + r)a), \quad x \in (x_2, x_1),
\]
which contradicts with \(V_t \leq 0\) (Lemma 1).

Case 2: we notice that \(\mathcal{D}_1 \subset \{(t, x): x \geq ra/(r - \mu_1)\}\).
Now, the proof is similar to Case 1. \(\square\)

In the following theorem, we rewrite the optimal stopping problem (4) as a free boundary problem.

**Theorem 2.** Assume that \(\eta \leq r\).

Case 1: if \(\mu_1 < \eta \leq \mu_2\), then the value function \(V\) is the unique solution to the following problem:

\[
V(t, x, 1) + (\mathcal{A}V)(t, x, 1) - rV(t, x, 1) = 0 \quad \text{in} \ \mathcal{C}_1 = \{(t, x): x < b_1(t)\},
\]
\[
V(t, x, 2) + (\mathcal{A}V)(t, x, 2) - rV(t, x, 2) = 0 \quad \text{in} \ (0, T) \times (0, +\infty),
\]
\[
V(t, b_1(t), 1) = g(b_1(t)), \quad t \in [0, T),
\]
\[
V_x(t, b_1(t), 1) = 1, \quad t \in [0, T),
\]
\[
V(T, x, i) = g(x), \quad x \in (0, +\infty), i \in \mathcal{D}.
\]

Case 2: if \(\mu_1 < \eta \leq \mu_2 < r\), then the value function \(V\) defined in (4) is the unique solution to the following free boundary problem:

\[
V(t, x, i) = \frac{1}{\lambda_1} ((r - \mu_1 + \lambda_1)x - (\lambda_1 + r)a), \quad r < x < x_1.
\]
In particular, the partial derivatives $V_{xx}$, $V_{x}$, and $V$, exist and are continuous in $\mathcal{C}$.

**Proof.** We only prove Case 2. Case 1 can be proved similarly. (47) follows directly from (29). (48) follows from the continuity of $V$ (Lemma 2). (50) follows from (4) directly.

We shall prove the smooth pasting condition (49). We set $x = b_{i}(t)$. As $(t, x - \epsilon) \in \mathcal{C}$, we derive that

$$\frac{V(t, x, i) - V(t, x - \epsilon, i)}{\epsilon} \leq \frac{x - a - (x - \epsilon - a)}{\epsilon} = 1,$$

where the inequality follows from (48). Let $\epsilon \to 0,

$$V_{-}^c(t, x, i) \leq 1,$$

where $V_{-}^c$ is the left derivative of $V$ in $x$. For any $\epsilon > 0$, let $\tau_{\epsilon}$ be the optimal stopping time for $V(t, x - \epsilon, i)$ and $T_{i}$ be the first transition time of $a$ with $a(0) = i$. Denote

$$\tau_{\epsilon} := \inf\{s \in [0, T_{i}] : X_{s}^{x, \epsilon} \geq b_{i}(t + s)\}.$$

By (9) and Theorem 1, if $T_{i} > T - t$, then $\tau_{\epsilon} = \tau_{i}$; otherwise, we have

$$\tau'_{\epsilon}(t, x, i) = \inf\{s \in [0, T - t] : X_{s}^{x, \epsilon} \geq b_{i}(t + s)\} = \tau_{\epsilon} \wedge \inf\{s \in [T_{i}, T - t] : X_{s}^{x, \epsilon} \geq b_{i}(t + s)\}.$$

(54)

By the solution of SDE (2), we have

$$\tau_{\epsilon} = \inf\{s \in [0, T_{i}]: \int_{0}^{s} \left(\mu\left(\alpha_{x}\right) - \frac{1}{2}\sigma^{2}\left(\alpha_{x}\right)\right) dv + \int_{0}^{s} \sigma(\alpha_{x}) dB_{v} \geq \log \left(\frac{b_{i}(t + s)}{x - \epsilon}\right)\}.$$

Lipschitz continuity of (47) follows directly from (29). (48) follows from the continuity of $V$ (Lemma 2). (50) follows from (4) directly.

For uniqueness, let $f(t, x, i)$ be a solution to the free boundary problem (47). We define $M_{\alpha} := e^{-r\tau_{\epsilon}} f(s + t, X_{s}, \alpha_{s})$ and set $\tau_{\beta} := \inf\{s \in [0, T - t] : X_{s}^{x, \epsilon} \geq b_{\alpha}(s + t)\}$. By Itô’s lemma,

$$M_{\beta, \tau_{\beta}} = f(t, x, i) + \int_{0}^{\tau_{\beta}} e^{-r\tau} (f_{s} + \alpha_{s} f - rf) \cdot (s + t, X_{s}, \alpha_{s}) ds + M_{\beta, \tau_{\beta}},$$

where $\{N_{\alpha, \tau_{\alpha}, s \geq 0}\}$ is a martingale. Hence, by (47), $\{M_{\alpha, \tau_{\alpha}, s \geq 0}\}$ is a martingale. We know from the optional sampling theorem that

$$f(t, x, i) = M_{\alpha, \tau_{\alpha}} = E[M_{\alpha, \tau_{\alpha}}] = E[e^{-r\tau_{\alpha}} f(\tau_{\beta} + t, X_{\tau_{\beta}}, \alpha_{\tau_{\beta}})] = E[e^{-r\tau_{\beta}} g(X_{\tau_{\beta}})] = V(t, x, i),$$

where the second equality follows from that $\{M_{\alpha, \tau_{\alpha}, s \geq 0}\}$ is a bounded martingale and dominated convergent theorem, the fourth equality follows from (48) and definition of $\tau_{\beta},$
and the last equality follows from that $\tau_{e^2\nu}$ is an optimal stopping time of $V(t, x, i)$. This implies the uniqueness.

By Lemma 2 and regularity of parabolic equation (see [20]), it is obvious that $V_t, V_x, V_{xx}$ exist and are continuous in $\mathcal{E}$.

In the following, we decompose the value function into two components and derive a Volterra type integral equation. Firstly, we introduce the following notations:

$$J_i(t, x) := \mathbb{E}\left[e^{-(r+\lambda)t}g(X^{(i)}_{T-t})\right],$$

$$K_i(t, x, u, b_i(u + t)) := \mathbb{E}\left[e^{-(r+\lambda)u}\Phi_i\left(X^{(i)}_u\mathbf{1}_{[X^{(i)}_u > b_i(u + t)]}\right) - \lambda V(t + u, X^{(i)}_u, j)\mathbf{1}_{[X^{(i)}_u < b_i(u + t)]}\right],$$

where

$$\Phi_i(x) = (r + \lambda_i - \mu_i)x + (r + \lambda_i)a.$$  

$$X^{(i)}_t$$ satisfies

$$dX^{(i)}_t = X^{(i)}_t(\mu_i dt + \sigma_i dB_t),$$

with initial condition $X^{(i)}_0 = x$.

Theorem 3. Assume that $\eta \leq r$.

Case 1: if $\mu_1 \leq \eta \leq r \leq \mu_2$, then the value function defined in (4) is given by

$$V_i(t, x) = \sup_{0 \leq \tau \leq T-t} \mathbb{E}\left[e^{-(r+\lambda)\tau}g(X^{(i)}_{T-t}) + \lambda \int_0^{T-t} e^{-(r+\lambda)u}V(t + u, X^{(i)}_u, j)\right],$$

where $V(t, x, i)$ is defined in (4) and $X^{(i)}_t$ satisfies (63). Fixing $i$ in Case 2 of Theorem 2, by a similar Markovian argument, we conclude that $V_i(t, x)$ is a solution to the free boundary problem (47)–(50). The uniqueness implies that $V_i(t, x) = V(t, x, i)$ for $(t, x, i) \in [0, T] \times (0, +\infty) \times \mathcal{E}$.

By the regularity of $V$ in Case 2 of Theorem 2, we can use the local time-space formula given in [19] to obtain that

$$e^{-(r+\lambda)s}V_i(s + t, X^{(i)}_s) = V_i(t, x) + \int_0^t e^{-(r+\lambda)s}V_{it} + \frac{1}{2}\sigma_i^2 X_{ix}^2 V_{ixx}$$

$$+ \mu_i x V_{ix} - (r + \lambda_i)v_i(t + u, X^{(i)}_u, 1_{[X^{(i)}_u > b_i(u + t)]})du$$

$$+ \int_0^t \sigma_i X^{(i)}_{ix}(t + u, X^{(i)}_u)1_{[X^{(i)}_u < b_i(u + t)]}dB_u$$

$$+ \frac{1}{2} \int_0^t (V_{ix}(t + u, X^{(i)}_u) + V_{ix}(t + u - X^{(i)}_u))$$

$$\cdot \mathbf{1}_{[X^{(i)}_u = b_i(u + t)]}d\mu(X^{(i)}_u).$$

Furthermore, the free boundary $b_i(t)$ satisfies the following nonlinear Volterra integral equation:

$$g(b_i(t)) = J_i(t, b_i(t)) - \int_0^{T-t} K_i(t, b_i(t), u, b_i(u + t))du.$$
where \( \ell_u^b (X^{(i)}) \) is the local time of \( X^{(i)} \) at the curve \( b_i \) given by
\[
\ell_u^b (X^{(i)}) = \lim_{\epsilon \to 0} \frac{1}{2\epsilon} \int_0^u \mathbb{1}_{[b_i(t) - \epsilon < X^{(i)}(t) < b_i(t) + \epsilon]} \, dt < X^{(i)}(t) >_y,
\]
and \( d\ell_u^b (X^{(i)}) \) refers to integration with respect to the continuous increasing function \( u \to \ell_u^b (X^{(i)}) \).

We notice that \( V_i(t,x) = g(x) \) for \( x > b_i(t) \) and \( V_i \) satisfies (47) for \( x < b_i(t) \). Hence,

\[
(V_i + \frac{1}{2} \sigma_i^2 x^2 V_{1xx} + \mu_i x V_{ix})(t + u, X^{(i)}(t)) = \begin{cases} 
\Phi_i(X^{(i)}(t)), & \text{if } X^{(i)}(t) > b_i(u + t), \\
\lambda_i V(u, X^{(i)}(t)), & \text{if } X^{(i)}(t) < b_i(u + t).
\end{cases}
\]

Here, \( j \neq i \). Setting \( s = T - t \) together with (49) and (50), taking expectation in (69), and using the notation (60) and (61), we derive that

\[
\begin{align*}
V_i(t,x) &= \mathbb{E}\left[ e^{-(r+\lambda)T-t} g(X_{T-t}) \right] - \mathbb{E}\left[ \int_0^{T-t} e^{-(r+\lambda)s} \left[ \Phi_i(X^{(i)}_u) \mathbb{1}_{\{X^{(i)}_u > b_i(u+t)\}} \right] \right] \\
&\quad - \lambda_i V(t + u, X^{(i)}_u, j) \mathbb{1}_{\{X^{(i)}_u < b_i(u+t)\}} du \\
&= J_i(t,x) - \int_0^{T-t} K_i(t, x, u, b_i(u + t)) du \\
&= V(t, x, i).
\end{align*}
\]

Finally, by condition (48), we derive that

\[
J_i(t, b_i(t)) - \int_0^{T-t} K_i(t, b_i(t), u, b_i(u + t)) du = g(b_i(t)), \quad i \in \mathcal{S}.
\]

The next result compares the optimal selling strategies in different states.

**Theorem 4.** Suppose Assumption 1 holds, \( \sigma_1 < \sigma_2 \), and \( r > \mu_2 \). Let \( X^{(i)}_i \) be defined as (63). Then,

\[
b_i(t) \leq b_i(t) \leq b_i(t), \quad 0 < t < T, \tag{74}
\]

where \( b_i(t) \) (\( i \in \mathcal{S} \)) is the free boundary of the following optimal stopping problem

\[
V_{2i} + \frac{1}{2} \sigma_i^2 x^2 V_{2xx} + \mu_i x V_{2x} - r V_{2x} = V_{2i} + \frac{1}{2} \sigma_i^2 x^2 V_{2xx} + \mu_i x V_{2x} - r V_{2x} + \frac{1}{2} x^2 (\sigma_i^2 - \sigma_2^2) V_{2xx} + (\mu_i - \mu_2) x V_{2x}
\]

\[
\leq 0.
\]
Furthermore, \( V_1(T, x) = V_2(T, x) \) and \( V_1 = V_2 \) on the boundary of \( \mathcal{N} \). Hence, the comparison principle of variational inequality implies that \( V_2 \geq V_1 \) in \( \mathcal{N} \), which is a contradiction with definition of \( \mathcal{N} \). This leads to \( V_2 \geq V_1 \) for \((t, x) \in (0, T) \times (0, +\infty)\). That means \( \mathcal{G}_1 \subset \mathcal{G}_2 \), i.e., \( b_1(t) \leq b_2(t) \).

By Markovian argument, \( V^0 \) satisfies

\[
\min \left\{ -V^0_{\mu} - \frac{1}{2} \sigma^2 x^2 V^0_{xx} - \mu x V^0_x + r V^0 - g(x) \right\} = 0, \\
V^0_i(T, x) = g(x).
\]

(78)

The above inequality implies that

\[
-V^0_{2t} - \frac{1}{2} \sigma^2 x^2 V^0_{xx} - \mu x V^0_x + r V^0 = -\lambda_1 (V_1 - V_2) \\
\geq -\lambda_2 (V_1 - V_2) \geq 0,
\]

(79)

and by (40),

\[
-V^0_{2t} - \frac{1}{2} \sigma^2 x^2 V^0_{xx} - \mu x V^0_x + r V_1 \geq \lambda_1 (V_2 - V_1) \geq 0.
\]

(80)

Applying comparison principle of variational inequality, we deduce that \( V^0_{2t} \leq V_1 \) and \( V^0_x \leq V^0_{2t} \), i.e., \( b^2_1(t) \leq b_1(t) \) and \( b_2(t) \leq b^2_2(t) \).

In the end of this section, we perform some sensitivity analyses of the optimal selling strategy.

**Theorem 5.** Assume that \( r \geq \eta \). The free boundary \( b_1(t) \) of problem (4) is increasing with respect to \( \mu_i, \sigma_i \) for each \( i \in \mathcal{S} \), and \( a \) and decreasing with respect to \( r \).

**Proof.** Assume that \( (\bar{V}_1, \bar{V}_2) \) is the solution to variational inequality

\[
\min \{(rV - V_1 - \sigma V)(t, x, i), V(t, x, i) - g(x) \} = 0,
\]

(81)

for any \((t, x, i) \in (0, T) \times (0, +\infty) \times \mathcal{S} \), where \( \bar{a}_i \) is \( \bar{a}_i \), \( (\bar{V}_1, \bar{V}_2) \) is the solution to variational inequality (81), where \( \sigma_i = \bar{\sigma}_i \), \( \bar{\sigma}_i \) is the stopping region with respect to \( a_i \), \( \bar{\sigma}_i \) is the stopping region with respect to \( a_i \), then \( \mathcal{G}_1 \subset \mathcal{G}_2 \), i.e., \( b_1(t) \leq b_2(t) \). Hence, \( b_1(t) \), \( b_2(t) \) is increasing with respect to \( a \).

In the following, assume that \( (\bar{V}_1, \bar{V}_2) \) is the solution to variational inequality (81), where \( \mu_1 = \bar{\mu}_i, (\bar{V}_1, \bar{V}_2) \) is the solution to variational inequality (81), where \( \mu_1 = \bar{\mu}_i \), \( \bar{\mu}_i \), \( \bar{\mu}_i \) for each \( i \in \mathcal{S} \). By Lemma 1, it follows that

\[
\bar{V}_i + \frac{1}{2} \sigma^2 x^2 \bar{V}_{ixx} + \mu x \bar{V}_{ix} - r \bar{V}_i + \lambda_i (\bar{V}_j - \bar{V}_i) = (\bar{\mu}_i - \bar{\mu}_j)x \bar{V}_{ix} \leq 0,
\]

(85)

if \( \bar{V}_i(t, x) > g(x) \), and

\[
\bar{V}_i + \frac{1}{2} \sigma^2 x^2 \bar{V}_{ixx} + \mu x \bar{V}_{ix} - r \bar{V}_i + \lambda_i (\bar{V}_j - \bar{V}_i) \leq (\bar{\mu}_i - \bar{\mu}_j)x \bar{V}_{ix} \leq 0,
\]

(86)

if \( \bar{V}_i(t, x) = g(x) \). Employing comparison principle of variational system (see [16]), we conclude that \( \bar{V}_i \geq \bar{V}_j \), i.e., \( \bar{b}_1(t) \leq \bar{b}_2(t) \), for \( i \in \mathcal{S} \). Hence, \( (b_1(t), b_2(t)) \) is increasing with respect to \( \sigma_i \) for each \( i \in \mathcal{S} \).

Next, assume that \( (\bar{V}_1, \bar{V}_2) \) is the solution to variational inequality (81), where \( a \) is \( a_1 \), \( (\bar{V}_1, \bar{V}_2) \) is the solution to variational inequality (81), where \( a \) is \( a_2 \), and \( a_1 < a_2 \). Then, we have

\[
\bar{V}_i(t, x) = \sup \int_{0 \leq t \leq T} E[e^{-\tau} (X_\tau - a_2)] \\
\geq a_1 - a_2 + \sup \int_{0 \leq t \leq T} E[e^{-\tau} (X_\tau - a_1)]
\]

(84)

\[
= a_1 - a_2 + \bar{V}_i(t, x).
\]

This implies that if \( \bar{V}_i(t, x) > x - a_1 \), then \( \bar{V}_i(t, x) \geq \bar{V}_j(t, x) + a_1 > x - a_2 \). If we denote \( \mathcal{G}_1 \), to be the stopping region with respect to \( a_1 \), \( \mathcal{G}_2 \), the stopping region with respect to \( a_2 \), then \( \mathcal{G}_1 \subset \mathcal{G}_2 \), i.e., \( \bar{b}_1(t) \geq \bar{b}_2(t) \). Hence, \( (b_1(t), b_2(t)) \) is increasing with respect to \( a \).

5. **Numerical Examples**

In this section, we present some numerical results obtained from trinomial tree method, which was put forward in [17] for pricing American option. Firstly, we briefly explain how to use the trinomial tree method to solve our problem.
Let $\Delta t = T/n$ be the time step-size. We take the jump ratios of the lattice as
\[ u = e^{\sigma \sqrt{\Delta t}}, \]
\[ d = e^{-\sigma \sqrt{\Delta t}}, \]
where $\bar{\sigma} = \max_{i \in S} \{\sigma_i\} + (\sqrt{1.5} - 1)\bar{\sigma}$,
\[ \sigma = \max_{i \in S} \{\sigma_i\} + (\sqrt{1.5} - 1)\bar{\sigma}, \]
where $\bar{\sigma}$ is the arithmetic mean or geometric mean of $\sigma_i$, $i \in S$.

For regime $i$, let $\pi_{iu}^i$, $\pi_{im}^i$, and $\pi_{id}^i$ be the risk neutral probabilities corresponding to the stock price increases, remaining the same, and decreases, respectively. By moment matching technique, the values of the probabilities are given by

\[ \pi_{iu}^i = e^{\mu \Delta t} - e^{\sigma \sqrt{\Delta t}} - (1 - (\sigma^2/\sigma_i^2))(1 - e^{-\sigma \sqrt{\Delta t}}), \]
\[ \pi_{im}^i = \frac{e^{\mu \Delta t} - e^{\sigma \sqrt{\Delta t}} - (1 - (\sigma^2/\sigma_i^2))(1 - e^{-\sigma \sqrt{\Delta t}})}{e^{\sigma \sqrt{\Delta t}} - e^{-\sigma \sqrt{\Delta t}}}, \]
\[ \pi_{id}^i = \frac{e^{\sigma \sqrt{\Delta t}} - e^{\mu \Delta t} - (1 - (\sigma^2/\sigma_i^2))(e^{\sigma \sqrt{\Delta t}} - 1)}{e^{\sigma \sqrt{\Delta t}} - e^{-\sigma \sqrt{\Delta t}}}. \]

Let $x_{j+1} = ux_j$ and $x_{j-1} = dx_j$, and $V^k(x_j, i)$ be the trinomial approximation of the primal value function for regime $i$ at asset price $x_j$ and time $t_k = k\Delta t$. Then, the trinomial formula of the primal value function is given by, for $k = 0, 1, \ldots, n - 1$,

---

**Figure 1:** Sample path of Markov chain and stock price with (A.) $\alpha_0 = 1, S_0 = 0.5$, and early exercise boundary when $r > \mu_2$ and (B.) $\alpha_0 = 2, S_0 = 1$, and early exercise boundary when $\eta \leq r \leq \mu_2$. 

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\[ \pi_{iu}^i = 1 - \frac{\sigma^2_i}{\bar{\sigma}}, \]
\[ \pi_{im}^i = \frac{e^{\mu \Delta t} - e^{\sigma \sqrt{\Delta t}} - (1 - (\sigma^2/\sigma_i^2))(1 - e^{-\sigma \sqrt{\Delta t}})}{e^{\sigma \sqrt{\Delta t}} - e^{-\sigma \sqrt{\Delta t}}}, \]
\[ \pi_{id}^i = \frac{e^{\sigma \sqrt{\Delta t}} - e^{\mu \Delta t} - (1 - (\sigma^2/\sigma_i^2))(e^{\sigma \sqrt{\Delta t}} - 1)}{e^{\sigma \sqrt{\Delta t}} - e^{-\sigma \sqrt{\Delta t}}}. \]
with $V^n(x_j,i) = g(x_j)$ for $j = 0, \pm 1, \ldots, \pm n$, in which $p_{il}$ is the transition probability from state $i$ to state $l$ for the time interval with length $\Delta t$. It is given by

$$p_{il} = e^{-r\Delta t} \sum_{j=1}^{\infty} p_{il}^j V^{k+1}(x_{j+1},l) + n_i^V V^{k+1}(x_j,l) + n_i^m V^{k+1}(x_{j-1},l), g(x_j),$$

with $V^n(x_j,i) = g(x_j)$ for $j = 0, \pm 1, \ldots, \pm n$, in which $p_{il}$ is the transition probability from state $i$ to state $l$ for the time interval with length $\Delta t$. It is given by

$$p_{il} = e^{-r\Delta t} \sum_{j=1}^{\infty} p_{il}^j V^{k+1}(x_{j+1},l) + n_i^V V^{k+1}(x_j,l) + n_i^m V^{k+1}(x_{j-1},l), g(x_j),$$

(92)

with $V^n(x_j,i) = g(x_j)$ for $j = 0, \pm 1, \ldots, \pm n$, in which $p_{il}$ is the transition probability from state $i$ to state $l$ for the time interval with length $\Delta t$. It is given by

$$p_{il} = e^{-r\Delta t} \sum_{j=1}^{\infty} p_{il}^j V^{k+1}(x_{j+1},l) + n_i^V V^{k+1}(x_j,l) + n_i^m V^{k+1}(x_{j-1},l), g(x_j),$$

(93)

where $I$ is the identity matrix and $A$ is the generator matrix of the Markov chain process given by (1).

**Example 1.** In this example, the numerical experiments shed light on the optimal selling strategy of problem (4) with fixed parameters for two different cases. The generator of Markov chain $\alpha_t$ is taken as

$$A = \begin{pmatrix} -0.4 & 0.4 \\ 0.5 & -0.5 \end{pmatrix}.$$  

(94)

The returns of the stock are $\mu_1 = 0.04$ and $\mu_2 = 0.05$ and the volatilities $\sigma_1 = 0.25$ and $\sigma_2 = 0.45$. The maturity date is
assumed to be $T = 1$. The transaction cost is assumed to be $a = 0.4$. The interest rate is taken as $r = 0.08$ for Figure 1(a) so that $r > \mu_2$ and $r = 0.045$ for Figure 1(b) so that $\mu_1 < \eta < r < \mu_2$. The number of time steps for both methods is $N = 10000$. In Figure 1, we simulate the sample path of the stock price and plot the early exercise boundary of problem (4). Intuitively, from Figure 1(a), we see that if the risk-free interest rate is always higher than the return rate of stock, the stockholder will have motivation to sell the stock when the stock price hits the free boundary at time $t_0$. Hence, in this case, there exists a unique free boundary for each state. Moreover, the larger return rate and volatility mean that the value function is larger, and the early exercise boundary will be higher. Intuitively, from Figure 1(b), it is clear that if the risk-free interest rate is between the return rate of bear market and return rate of the bull market, then the stockholder will sell the stock early in bear market and hold the stock until the maturity date in bull market. Hence, in this case, there exists a unique free boundary when the investor is in bear market, and the free boundary does not exist when the investor is in bull market.

Example 2. In this example, we assess the impact of varying model parameters on the early exercise boundary.

Figure 2 displays the sensitivity with respect to transaction fee. We vary the transaction fee between 1 and 4 and compute the early exercise boundary. We observe that the early exercise boundary is higher for a higher transaction fee.

Figure 4: The impact of varying return rate of stock on the early exercise boundary for (A.) regime 1 and (B.) regime 2.

Figure 5: The impact of varying volatility on the early exercise boundary for (A.) regime 1 and (B.) regime 2.
The higher transaction fee means that the stockholder will sell the stock if stock price is higher. That is, the critical price will be higher.

In Figure 3, we show the sensitivity of the early exercise boundary with respect to interest rate. In our case, the interest rate takes values from 0.055 to 0.07. The figure shows that with a higher interest rate, the early exercise boundary is lower. Intuitively, the higher interest rate motivates the stockholder to sell the stock although the stock price is lower.

Figure 4 illustrates the sensitivity with respect to the return rate of stock. For \((\mu_1, \mu_2) = (0.01, 0.02), (0.02, 0.03), (0.03, 0.04), (0.04, 0.05)\), we compute the early exercise boundary. This figure shows that the free boundary is higher with a higher return rate. Intuitively, this result can be explained by the fact that the higher return rate makes the investor unwilling to sell the stock for a low stock price. Therefore, the critical price to sell stock is higher.

We analyze the sensitivity of the early exercise boundary with respect to the volatility in Figure 5. For \((\sigma_1, \sigma_2) = (0.10, 0.15), (0.15, 0.20), (0.20, 0.25), (0.25, 0.30)\), we compute the early exercise boundary. We observe that the higher the volatility, the higher is the early exercise boundary. Intuitively, if the volatility is higher, the stock price fluctuates more heavily and the investor will be more willing to hold the stock until the stock price goes up.

6. Conclusions

In this paper, we discuss the optimal selling rule under regime-switching models. To explore the optimal stopping rule, we analyze the optimal stopping problem and convert the problem into a free boundary problem. The properties of the free boundary and the involved Volterra type integral equations are established. Finally, we calculate the free boundary by trinomial tree method. Once the free boundary can be calculated, the optimal stopping rule is determined. We make a conclusion that, when the return of the stock is always higher than the interest rate, the agent should hold the stock until the maturity date; otherwise, he/she should sell the stock in the bear market when the stock price reaches a critical level and hold the stock until the maturity date in the bull market, which is consistent with intuition. Since the Volterra equations in this paper are interacting, this makes it difficult to solve the free boundary in each state independently. Therefore, the method of solving the Volterra equation without regime-switching cannot be extended to solve our problem directly. We will discuss this kind of problem in the future.

Appendix

A. Proof of Lemma 1

Proof. For any \(s_1 < s_2, \epsilon > 0\), let \(\tau_s \in [0, T - s]\) be the \(\epsilon\)-optimal stopping time for \(V(s_1, x, i)\). It is clear that \(0 \leq \tau_s \leq T - s_1\) is suboptimal for \(V(s_1, x, i)\). This implies that

\[
V(s_1, x, i) \geq \mathbb{E}\left[e^{-r\tau_s}g\left(X_{\tau_s}\right)\right] \geq V(t_2, x, i) - \epsilon. \tag{A.1}
\]

Now, the monotonicity of \(V\) in \(t\) follows by letting \(\epsilon \longrightarrow 0\).

For the monotonicity of \(V\) in \(x\), we solve the SDE (2) to obtain that

\[
X_t = x \exp(H_t), \tag{A.2}
\]

where \(H_t\) is defined by (18). Now, by (4),

\[
V(t, x, i) = \sup_{t \leq \tau \leq t} \mathbb{E}\left[e^{-r\tau}\left(x \exp(H_{\tau}) - a\right)\right], \quad i = 1, 2. \tag{A.3}
\]

It is obvious that \(V\) is increasing in \(x\).

At last, we prove the convexity of \(V(t, \cdot, i)\). For any \(x_1, x_2 > 0, \lambda \in [0, 1]\), we set \(x^* = \lambda x_1 + (1 - \lambda)x_2\). (4) leads to

\[
V(t, x^*, i) = \sup_{t \leq \tau \leq t} \mathbb{E}\left[e^{-r\tau}(X_{\tau}^* - a)\right] = \sup_{t \leq \tau \leq t} \mathbb{E}\left[e^{-r\tau}(\lambda(X_{\tau}^* - a) + (1 - \lambda)(X_{\tau}^* - a))\right] \leq \lambda \sup_{t \leq \tau \leq t} \mathbb{E}\left[e^{-r\tau}(X_{\tau_1} - a)\right] + (1 - \lambda) \sup_{t \leq \tau \leq t} \mathbb{E}\left[e^{-r\tau}(X_{\tau_2} - a)\right] \leq \lambda V(t, x_1, i) + (1 - \lambda)V(t, x_2, i). \tag{A.4}
\]

Hence, \(V(t, \cdot, i)\) is a convex function.

B. Proof of Lemma 2

Proof. For the proof of Lipschitz continuity of \(V(t, \cdot, i)\), we refer to [7]. It suffices to prove that \(V(\cdot, x, i)\) is \(1/2\)-Hölder continuous. The following argument is based on a similar method developed by [12]. Integrating the SDE (2) from 0 to \(t\), we have

\[
X_t = x + \int_0^t \mu(a_s)X_s \, ds + \int_0^t \sigma(a_s)X_s \, dB_s. \tag{B.1}
\]

For any \(0 \leq t_1 < t_2 \leq T\), we assume that \(\tau_1\) is the \(\epsilon\)-optimal stopping time for \(V(t_1, x, i)\). Then, \(0 \leq \tau_1 \leq T - t_1\), by setting \(\tau_2 = \tau_1 \wedge (T - t_2)\). Then, it is clear that

\[
0 \leq \tau_1 - \tau_2 = (\tau_1 \wedge (T - t_2) - \tau_1) = -\tau_1 \wedge (T - t_2 - \tau_1) \leq (0 \wedge (T - t_2 - \tau_1)) = (0 \wedge (T - t_2 - t_1)) = t_2 - t_1. \tag{B.2}
\]
Hence, we derive that

\[ 0 \leq V(t_1, x, i) - V(t_2, x, i) \leq E\left[ e^{-r(t_2-t_1)} \right] \frac{\partial}{\partial x} \left[ e^{-r(t_2-t_1)} \frac{1}{\sigma_0^2} X_{t_2} \right] \leq E\left[ e^{-r(t_2-t_1)} \right] \frac{\partial}{\partial x} \left[ e^{-r(t_2-t_1)} \frac{1}{\sigma_0^2} X_{t_2} \right] + \epsilon \]

where the second inequality follows from the fact that \( t_1 \) is \( e \)-optimal for \( V(t_1, x, i) \) and \( t_2 \) is suboptimal for \( V(t_2, x, i) \), the last inequality follows from (B.2). By mean value theorem and (B.2), it is obvious that

\[ E\left[ e^{-r(t_2-t_1)} \right] \leq C|t_2 - t_1|. \]

Applying (B.1) and (B.2) and Burkholder–Davis–Gundy inequality, we derive that

\[
E\left[ \left| X_{t_2} - X_{t_1} \right|^2 \right] \leq E\left[ \int_{t_1}^{t_2} \frac{\partial}{\partial x} \left( e^{-r(t_2-t_1)} \frac{1}{\sigma_0^2} \right) X_{t_2} dt \right] + E\left[ \int_{t_1}^{t_2} \frac{\partial}{\partial x} \left( e^{-r(t_2-t_1)} \frac{1}{\sigma_0^2} \right) X_{t_2} dt \right] + \epsilon
\]

Now, since \( E[\sup_{0 \leq t \leq T}|X_t|] \leq C^n(x, i, T) \) by moment estimates (see [18] or [12]), combining with (B.3)–(B.5), we conclude that \( V \) is 1/2–Hölder continuous in \( t \).

\[ \square \]

**Data Availability**

No data were used in this paper.

**Conflicts of Interest**

The authors declare that they have no conflicts of interest.

**Acknowledgments**

This work was supported by the Innovative Team Program of the Neijiang Normal University (Grant No. 2019TD02) and the Scientific Research Start-Up Program for Talents of Guizhou University of Finance and Economics (Grant No. 2019Y070).

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