Stationary Heston model: calibration and pricing of exotics using product recursive quantization

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(Received 9 July 2020; accepted 13 December 2021; published online 18 February 2022)

Product Recursive Quantization is used to price exotic options in the Stationary Heston model, a model that generates more realistic volatility surfaces than the original Heston model

1. Introduction

Originally introduced by Heston in Heston (1993), the Heston model is a stochastic volatility model used in quantitative finance to model the joint dynamics of a stock, denoted \( (S_t^x)_{t \geq 0} \), and its volatility, denoted \( (v_t^x)_{t \geq 0} \) where \( v_0^x = x > 0 \) stands for the initial volatility at time \( t = 0 \). Historically, the initial condition of the volatility \( x \) is considered as deterministic and is calibrated to market data like the other parameters of the model. This model received an important attention among practitioners for two reasons: first, it is a stochastic volatility model, hence it introduces smile in the implied volatility surface as observed in the market, which is not the case of models with constant volatility, and second, in its original form, we have access to a semi closed-form formula for the characteristic function which allows us to price European options (Call & Put) almost instantaneously using the Fast Fourier approach (Carr & Madan in Carr and Madan (1999)). Yet, a complaint often heard about the Heston model is that it fails to fit the implied volatility surface for short maturities because the model cannot produce a steep-enough smile for those maturities (see Gatheral (2011)).

In Pagès and Panloup (2009) devoted to the computation by Langevin Monte Carlo simulation of stationary regime of ergodic diffusion, the authors introduce as an example what they called the Stationary Heston model: noting that the volatility process is ergodic with the Gamma distribution as unique invariant distribution \( \nu = \gamma(\alpha, \beta) \), where \( \alpha \) and \( \beta \) depend on the structure parameters of the volatility process, they assume the volatility evolves under this stationary regime rather than starting at time 0 from a deterministic value. The couple asset-volatility in this Stationary Heston model will be denoted \( (S_t^{\nu}, v_t^{\nu})_{t \geq 0} \). Considering this avatar of Heston model is justified (on simulated data) by more realistic implied volatility surfaces produced for short maturities by the pricing of vanilla options. The resulting pricing method of

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paths, et al. noun equation driven by a ‘rough’ Liouville process with Rough Heston model where the volatility satisfies a Volterra reduce the slope of the skew for short-term expiring options: the model have been suggested and extensively analyzed to repro-

duce the slope of the skew for short-term expiring options: the Rough Heston model where the volatility satisfies a Volterra equation driven by a ‘rough’ Liouville process with H-Hölder paths, $H \simeq 0.1$ (see Jaissin and Rosenbaum (2016), Guennoun et al. (2018), Gatheral et al. (2018), Gatheral and Radoicic (2019), and Callegaro et al. (2021) for details on the model and numerical solutions).

In the beginning of the paper, we briefly recall the well-known methodology used for the pricing of European option in the regular Heston model. Based on that, we express the price $I_0$ of a European option on the asset $S_t^{(1)}$ as

$$ I_0 = E \left[ e^{-rT} \phi(S_T^{(1)}) \right] = E \left[ f(v_0^0) \right] $$

where $f(x)$ denotes the price of the European option in the regular Heston model with same parameters but starting from $v_0 = x \in (0, +\infty)$. The last expectation can be computed efficiently using quadrature formulas either based on optimal quantization of the Gamma distribution or on Laguerre polynomials.

Once we are able to price European options, we can think of calibrating our model to market data. Indeed the parameters of the model are calibrated using the implied volatility surface observed in the market. However, the calibration of the Heston model is highly depending on the initial guess we choose in the minimization problem. This is due to an over-parametrization of the model (see Gauthier and Rivaille (2009)). Hence, when we consider the Heston model in its stationary regime, there is one parameter less to calibrate as the initial value of the volatility is no longer deterministic.

In the second part of paper, we deal with the pricing of Exotic options such as Bermudan and Barrier options. We propose a method based on hybrid product recursive quantization. The ‘hybrid’ term comes from the fact that we use two different types of schemes for the discretization of the volatility and the asset (Milstein and Euler–Maruyama). Recursive quantization was first introduced by Pagès and Sagna (2015). It is a Markovian quantization (see Pagès et al. (2004)) drastically improved by the introduction of fast deterministic optimization procedure of the quantization grids and the transition weights. This optimization allows them to drastically reduce the time complexity by an order of magnitude and build such trees in a few seconds. Originally devised for Euler–Maruyama scheme of one-dimensional Brownian diffusion, it has been extended to one-dimensional higher-order schemes by McWalter et al. (2018) and to medium dimensions using product quantization (see Callegaro et al. (2017), Rudd et al. (2017), Callegaro et al. (2018), Fiorin et al. (2018) and Pagès and Sagna (2021)). Then, once the quantization tree is built, we proceed by a backward induction using the Backward Dynamic Programming Principle for the price of Bermudan options and using the methodology detailed in Sagna (2010) and Pagès (2018) based on the conditional law of the Brownian Bridge for the price of Barrier options.

The paper is organized as follows. First, in Section 1, we recall the definition of the Heston model and the interesting features of the volatility diffusion which bring us to define the Stationary Heston model. In Section 2, we give a fast solution for the pricing of European options in the Stationary Heston model when there exists methods for the Heston model. Finally, once we are able to price European options, we can define the optimization problem of calibration on implied volatility surface. We perform the calibration of both models and compare their induced smile for short maturities options. In Section 3, we propose a numerical method based on hybrid product recursive quantization for the pricing of exotic financial products: Bermudan and Barrier options.

2. The Heston model

The Heston model is a two-dimensional diffusion process $(S_t^{(1)}, v_t^{(1)})_{t \geq 0}$ with $S_t^{(1)}$ is the price of the risky asset at time $t$, and $v_t^{(1)}$ the volatility at time $t$, depending on $x > 0$ the initial value of the volatility. This two-dimensional process $(S_t^{(1)}, v_t^{(1)})_{t \geq 0}$ is the solution to the following Stochastic Differential Equation:

$$
\begin{align*}
\frac{dS_t^{(1)}}{S_t^{(1)}} &= (r - q) \, dt + \sqrt{v_t^{(1)}} \, dW_t, \\
\frac{dv_t^{(1)}}{\sqrt{v_t^{(1)}}} &= \kappa (\theta - v_t^{(1)}) \, dt + \xi \sqrt{v_t^{(1)}} \, d\tilde{W}_t,
\end{align*}
$$

where

- $S_0^{(1)} = x_0 > 0$ is the initial value of the price of the risky asset and $v_0^{(1)} = x > 0$ is the deterministic initial condition of the volatility,
- $(W, \tilde{W})$ is a two-dimensional correlated Brownian motion, with correlation $\rho \in [-1, 1]$ (correlation between the asset and the volatility),
- $r \in \mathbb{R}$ denotes the interest rate, and $q \geq 0$ is the dividend rate,
- $\theta > 0$ the long run average price variance,
- $\kappa > 0$ the rate at which $v_t^{(1)}$ reverts to $\theta$,
- $\xi > 0$ is the volatility of the volatility.

This model is widely used by practitioners for various reasons. One is that it leads to semi-closed forms for vanilla options. The other reason is that it represents well the
observed mid and long-term market behavior of the implied volatility surface observed on the market. However, it fails producing or even fitting to the smile observed for short-term maturities.

**Remark 2.1 (The volatility) One can notice that the volatility process is autonomous hence we are facing a one-dimensional problem. Moreover, the volatility process is following a Cox–Ingersoll–Ross (CIR) diffusion also known as the square root diffusion. The existence and uniqueness of a strong solution to this stochastic differential equation have been first shown in Ikeda and Watanabe (1981), if \( x \geq 0 \). Moreover, it has been shown, see, e.g. Lamberton and Lapeyre (2011), that, if the Feller condition

\[
\xi^2 \leq 2\kappa \theta
\]

is in force, then for every \( x > 0 \), then there exists a unique solution \((v^\nu_t)_{t \geq 0}\) to the volatility equation which satisfies

\[
\forall t \geq 0, \quad \mathbb{P}(\tau^\nu_0 = +\infty) = 1,
\]

where \( \tau^\nu_0 \) is the first hitting time defined by

\[
\tau^\nu_0 = \inf\{t \geq 0 \mid v^\nu_t = 0\} \quad \text{where} \quad \inf \emptyset = +\infty.
\]

Moreover, the CIR diffusion admits, as a Markov process, a unique stationary regime, characterized by its invariant distribution, the Gamma distribution

\[
v = \gamma(\alpha, \beta)
\]

where

\[
\alpha = \theta \beta \quad \text{and} \quad \beta = 2\kappa / \xi^2.
\]

Based on the above remarks, the idea is to precisely consider the volatility process under its stationary regime, i.e. replacing the deterministic initial condition from the Heston model by a \( \nu \)-distributed random variable independent of \((W, \tilde{W})\). We will refer to this model as the Stationary Heston model. Doing so, we inject more randomness for short maturities (\( t \) small) into the volatility but also to reduce the number of free parameters to stabilize and robustify the calibration of the Heston model which is commonly known to be overparametrized (see, e.g. Gauthier and Rivaille (2009)).

This model was first introduced by Pagès and Panloup (2009) (see also Ikeda and Watanabe (1981), p. 221). More recently, Jacquier and Shi (2017) studied its small-time and large-time behaviors of the implied volatility. The dynamic of the asset price \((S^{(v)}_T)_{t \geq 0}\) and its stochastic volatility \((v^\nu_t)_{t \geq 0}\) in the Stationary Heston model are given by

\[
\begin{align*}
\frac{dS^{(v)}_t}{S^{(v)}_t} &= (r - q) \, dt + \sqrt{v^\nu_t} \, dW_t, \\
v^\nu_t &= \kappa (\theta - v^\nu_t) \, dt + \xi \sqrt{v^\nu_t} \, d\tilde{W}_t,
\end{align*}
\]

where \( v^\nu_0 \sim \nu(\alpha, \beta) \) with \( \beta = 2\kappa / \xi^2, \ \alpha = \theta \beta \). Other parameters \( S^{(v)}_0, r \) and \( q \) are the same as those in (2) and the parameters \( \rho, \theta, \kappa, \theta, \xi \) can be described as in the Heston model.

![Figure 1. Implied volatility surface of the EURO STOXX 50 as of the 26th of September 2019 (S_0 = 3541, r = -0.0032 and q = 0.00225). The expiries T are given in days and the strikes K in percentage of the spot.](image)

### 3. Pricing of European options and calibration

In this section, we first calibrate both Stationary Heston and Heston models and then compare their short-term behaviors of their resulting implied volatility surfaces. For that purpose, we relied on a dataset of options price on the EURO STOXX 50 observed the 26th of September 2019 (see figure1). This is why, as a preliminary step we briefly recall the well-known methodology for the evaluation of European Call and Put in the Heston model. Based on that, we outline how to price these options in the Stationary Heston model. Then, we describe the methodology employed for the calibration of both models: the Stationary Heston model (8) and the Heston model (2), both under the Feller condition (3), and then we discuss the obtained parameters and compare their short-term behaviors.

#### 3.1. European options pricing

The price of the European option with payoff \( \varphi \) on the asset \( S_T^{(v)} \), under the Stationary Heston model, exercisable at time \( T \) is given by

\[
I_0 = \mathbb{E}\left[ e^{-rT} \varphi(S_T^{(v)}) \right].
\]

After preconditioning by \( v^\nu_0 \), we have

\[
I_0 = \mathbb{E} \left[ \mathbb{E}\left[ e^{-rT} \varphi(S_T^{(v)}) \right| \sigma(v^\nu_0) \right] = \mathbb{E} \left[ f(v^\nu_0) \right]
\]

where \( f(v) \) is the price of the European option in the Heston model with deterministic initial conditions for the set of parameters \( \lambda(v) = (\xi, r, q, \theta, \kappa, \xi, \rho, \nu) \).

**Example 3.1 (Call)** If \( \varphi \) is the payoff of a Call option, then \( f \) is simply the price given by Fourier transform in the Heston...
model of the European Call Option. The price at time 0, for a spot price \( s_0 \), of an European Call \( C(\lambda(v), K, T) \) with expiry \( T \) and strike \( K \) under the Heston model with parameters \( \lambda(v) = (s_0, r, \rho, \theta, \xi, \rho, v) \) is

\[
C(\lambda(v), K, T) = \mathbb{E}\left[ e^{-rT}(S_T^{(v)} - K)_+ \right]
= e^{-rT} \mathbb{E}\left[ S_T \mathbb{1}_{S_T \geq K} \right] - K \mathbb{E}\left[ \mathbb{1}_{S_T \geq K} \right]
= s_0 e^{-rT} P_1(\lambda(v), K, T) - K e^{-rT} P_2(\lambda(v), K, T)
\]

with \( P_1(\lambda(v), K, T) \) and \( P_2(\lambda(v), K, T) \) given by

\[
P_1(\lambda(v), K, T) = \frac{1}{2} + \frac{1}{\pi} \int_0^{+\infty} \operatorname{Re}\left( \frac{e^{-i(\log K)} \psi(\lambda(v), u - i, T)}{s_0 e^{-(r-q)T}} \right) du
\]

\[
P_2(\lambda(v), K, T) = \frac{1}{2} + \frac{1}{\pi} \int_0^{+\infty} \operatorname{Re}\left( \frac{e^{-i(\log K)} \psi(\lambda(v), u, T)}{iu} \right) du
\]

where \( i \) is the imaginary unit s.t. \( i^2 = -1 \), \( \psi(\lambda(v), u, T) \) is the characteristic function of the logarithm of the stock price process at time \( T \). Several representations of the characteristic function exist, we choose to use the one proposed by Schoutens et al. (2004), Albrecher et al. (2007), and Gatheral (2011), which is numerically more stable. It reads

\[
\psi(\lambda(v), u, T) = \operatorname{Re}\left( e^{iu \log(S_T^{(v)})} S_T^{(v)} \right)
= e^{iu \log(S_T^{(v)})} e^{iu \xi^2} (1 + (\kappa - \rho \xi u - d)T - 2 \log((1 - g e^{\xi^2})/(1 - g)))
\]

\[
\times e^{\xi^2(1 - \rho \xi u - d)/(1 - g e^{\xi^2})}
\]

with

\[
d = \sqrt{(\rho \xi u - \kappa)^2 - \xi^2(-u \xi - u^2)}
\]

\[
g = (\kappa - \rho \xi u - d)/(\kappa - \rho \xi u + d).
\]

Hence, in (10), \( f(v) \) can be replaced by \( C(\lambda(v), K, T) \), which yields

\[
I_0 = \mathbb{E}\left[ e^{-rT}(S_T^{(v)} - K)_+ \right] = \mathbb{E}\left[ C(\lambda(v_0), K, T) \right].
\]

Now, we come to the pricing of European options in the Stationary Heston model, using the expression of the density of \( v_0 \sim \gamma(\alpha, \beta) \), (10) reads

\[
I_0 = \mathbb{E}\left[ f(v_0) \right] = \int_0^{+\infty} f(v) \frac{\gamma^a}{\Gamma(\alpha)} v^{\alpha-1} e^{-\beta v} dv.
\]

Now, several approaches exist to approximate this integral on the positive real line.

- **Quantization based quadrature formulas.** One could use a quantization-based cubature formula with an optimal quantizer of \( v_0^N \) with the methodology detailed in Appendix 2. Given that optimal quantizer of size \( N, v_0^N \), we approximate \( I_0 \) by \( \hat{I}_0^N \)

\[
\hat{I}_0^N = \mathbb{E}\left[ f(v_0^N) \right] = \sum_{i=1}^{N} f(v_0^N) \mathbb{P}(v_0^N = v_0^N). \]

**Remarks 3.2** In one dimension, the minimization problem, that consists in building an optimal quantizer, commutes with affine transformations. Hence applying an affine transformation \( T \) to an optimal quantizer at level \( N \) of a distribution \( \mu \) makes it an optimal quantizer of \( \mu \circ T^{-1} \). Thus if we consider an optimal quantization \( \hat{X}^{N} \) of a standard normal distribution \( N(0, 1) \), then \( \mu + \sigma \hat{X}^{N} \) is an optimal quantizer of \( N(\mu, \sigma^2) \) and the associated probabilities of each Voronoi centroid stay the same.

In our case, noticing that if we consider a Gamma random variable \( X \sim \gamma(\alpha, 1) \), then the rescaling of \( X \) by \( 1/\beta \) yields \( X/\beta \sim \gamma(\alpha, \beta) \). Hence, for building the optimal quantizer \( v_0^N \) of \( v_0 \), we can build an optimal quantizer of \( X \sim \gamma(\alpha, 1) \) and then rescale it by \( 1/\beta \), yielding \( \hat{v}_0^N = \hat{X}^{N/\beta} \). Our numerical tests showed that it is numerically more stable to use this approach.

In order to build the optimal quantizer, we use Lloyd’s method detailed in Appendix 2 to \( X \sim \gamma(\alpha, 1) \) with the cumulative distribution function \( F_X (x) = P(X \leq x) \) and the partial first moment \( K_\alpha (x) = E[X \mathbb{1}_{X \leq x}] \) given by

\[
F_X (x) = \frac{\Gamma(\alpha, x)}{\Gamma(\alpha)}, \quad K_\alpha (x) = \alpha F_X (x) - \frac{x^\alpha e^{-x}}{\Gamma(\alpha)},
\]

\[
x > 0
\]

\[
F_X (x) = K_\alpha (x) = 0, \quad \text{otherwise},
\]

where \( \Gamma(\alpha, x) = \int_0^x t^{\alpha-1} e^{-t} dt \) is the lower incomplete gamma function. The distribution (weights) of the optimal quantizer \( v_0^N \) is given by (A11)

\[
P (v_0^N = v_0^N) = P(\hat{X}^{N} = x_N^N)
= F_X (x_{N+1/2}^N) - F_X (x_{N-1/2}^N)
\]

where, for every \( i \in \{2, \ldots, N\} \), \( x_{N+1/2}^N = \frac{x_N^N + x_{N+1}^N}{2} \) and \( x_{N-1/2}^N = 0 \) and \( x_N^N = +\infty \).

- **Quadrature formula from Laguerre polynomials.** One could also use an algorithm based on fixed point quadratures for the numerical integration. Indeed, noticing that the density we are integrating against is a gamma density which is exactly the Laguerre weighting function (up to a rescaling). Then, \( I_0 \) rewrites

\[
I_0 = \int_0^{+\infty} f(v) \frac{\gamma^a}{\Gamma(\alpha)} v^{\alpha-1} e^{-\beta v} dv.
\]
\[
\omega(v) = \mu^v e^{-\beta v}
\]
where \(\omega(v)\) is the Laguerre weighting function. Then, for a fixed integer \(n \geq 1\) (†), \(I_0\) is approximated by
\[
P_0 = \frac{\beta^\alpha}{\Gamma(\alpha)} \sum_{i=1}^{n} \omega_i f(v_i)
\]
where the \(v_i\)'s are the associated Laguerre nodes and the \(\omega_i\)'s their weights (†).

### 3.2. Calibration

Now that we are able to compute the price of European options, we define the problem of minimization we wish to optimize to calibrate our model parameters. Let \(\mathcal{P}_{m}\) be the set of parameters of the Stationary Heston model that needs to be calibrated, defined by
\[
\mathcal{P}_m = \{ \phi = (\theta, \kappa, \xi, \rho) \in \mathbb{R}_+ \times \mathbb{R}_+ \times \mathbb{R}_+ \times [-1,1] \}
\]
and let \(\mathcal{P}_n\) be the set of parameters of the Heston model that needs to be calibrated, defined by
\[
\mathcal{P}_n = \{ \phi = (x, \theta, \kappa, \xi, \rho) \in \mathbb{R}_+ \times \mathbb{R}_+ \times \mathbb{R}_+ \times \mathbb{R}_+ \times [-1,1] \}
\]
The others parameters are directly inferred from the market: we get \(S_0 = 3541\), \(r = -0.0032\) and \(q = 0.00225\). Note that we did not directly included the Feller condition (3) in the set of parameters \(\mathcal{P}_m\) and \(\mathcal{P}_n\) since this constraint will be introduced in the loss function of the calibration problem as a penalization (see further on). Indeed, preliminary calibration attempt tests performed without constraints yielded parameters really far from fulfilling the Feller condition, which was inconsistent with the aim of pricing path-dependent or American style derivatives by any method.

In our case, we calibrate to option prices having all the same maturity. The problem can be formulated as follows: we search for the set of parameters \(\phi^\ast\) that minimizes the relative error between the implied volatility observed on the market and the implied volatility produced by the model for the given set of parameters, such that \(\mathcal{P} = \mathcal{P}_m\) for the Stationary Heston model and \(\mathcal{P} = \mathcal{P}_n\) for the Heston model. There is no need to calibrate the parameters \(S_0\), \(r\) and \(q\) since they are directly observable in the market.

Being interested in the short-term behaviors of the models, it is natural to calibrate both models based on option prices at a small expiry. Once the optimization procedures have been performed, we compare their performances for small expiries.

† In practice, we choose \(n = 20\). This number of points allows us to reach a high precision while keeping the computation time under control.
† During our numerical tests, we used the numerical integration routine \(gsl\_integration\_fixed\_laguerre\) developed in the C++ gsl library. See https://www.gnu.org/software/gsl/doc/html/integration.html for more details on the implementation.

### Table 1. Parameters obtained for both models after calibration with penalization (\(\lambda = 0.01\)) for options with maturity 50 days (\(S_0 = 3541\), \(r = -0.0032\) and \(q = 0.00225\)).

| Model              | \(\phi^\ast\) | \(\rho\) | \(v_0\) | \(\theta\) | \(\kappa\) | \(\xi\) |
|--------------------|----------------|--------|---------|-----------|-----------|---------|
| Heston             | -0.83          | 0.0045 | 0.17023 | 2.19      | 1.04      |         |
| Stationary Heston  | -0.99          | 0.02691| 19.28   | 1.15      |           |         |

For that, we calibrate using only the data on the volatility surface in figure 1 with expiry 50 days (\(T = 50/365\)) and then we compare both models to the market implied volatility at expiry 22 days which is the smallest available in the data set.

**Remark 3.3** The calibration is performed in C++ on a laptop with a 2.4-GHz 8-Core Intel Core i9 CPU using the randomized version of the simplex algorithm of Nelder and Mead (1965) proposed in the C++ library GSL. This algorithm is a derivative-free optimization method. It uses only the value of the function at each evaluation point. The computation time for calibrating the Heston model is around 20 s and a bit more than a minute for the Stationary model. However, these computation times need to be considered carefully because the calibration time highly depends on the initial condition we choose for the minimizer and on the implementation of the Call price in the Heston model.

Let us be more precise. We want to find the set of parameter \(\phi^\ast\) that minimizes the relative error between the volatilities observed in the market and the ones generated by the model while enforcing the Feller condition. To take this constraint into account, it appears that the most convenient compromise was to introduce it as a penalization in the loss function to be minimized, hence leading to the following problem:

\[
\min_{\phi \in \mathcal{P}} \sum_K \left( \frac{\sigma_{N_{\text{Market}}}(K,T) - \sigma_{N_{\text{Model}}}(\phi, K, T)}{\sigma_{N_{\text{Market}}}(K,T)} \right)^2 + \lambda \max(\xi^2 - 2\kappa\theta, 0)
\]

where \(T\) is the expiry of the chosen options chosen a priori, \(K\) are their strikes and \(\lambda > 0\) is the penalization factor to be adjusted during the procedure. \(\sigma_{N_{\text{Market}}}(K,T)\) is the Market-to-Market implied volatility taken from the observed implied volatility surface and the implied volatility \(\sigma_{N_{\text{Model}}}(\phi, K, T)\) is the Black–Scholes volatility \(\sigma\) that matches the European Call price in this model to the price given by Heston or Stationary Heston model with the set of parameters \(\phi\).

The resulting parameters after calibration are summarized in table 1. The Feller condition is still not fulfilled for both models but it is not far from being satisfied. We choose \(\lambda = 0.01\) which seems to be right the compromise to avoid underfitting the model because of the constraint.

Figure 2 displays the resulting implied volatility curves at 50 days and 22 days for both calibrated models and observed in the market with calibration at 50 days.

Now, we extrapolate the implied volatility of both models for very short term maturities in figure 3. The Stationary Heston model produces the desired smile, however, the Heston model fails to produce prices sensibly different than 0 for strikes higher than 105 with this set of parameters, this is why there is no values in implied volatility curves.
Figure 2. Implied volatilities for 22 (left) and 50 (right) day expiry options after calibration at 50 days with penalization.

Figure 3. Implied volatilities for 7 (left) and 14 (right) day expiry options after calibration at 50 days with penalization.

Figure 4. Term structure of the volatility as a function of $T$ and $K$ of both models (left: Heston and right: Stationary Heston) after calibration at 50 days with penalization.

Figure 5. $(K, T) \rightarrow \log \frac{\sigma^{\text{Market}}(K,T) - \sigma^{\phi}(K,T)}{\sigma^{\text{Market}}(K,T)}$ for both models after calibration at 50 days with penalization. The expiries $T$ are given in days and the strikes $K$ are in percentage of the spot. (left: Heston and right: Stationary Heston).
From figure 3, we can see that the Heston model fails at producing the desired smile for very small maturities whereas the Stationary model meets no difficulty to generate it. Figure 4 reproduces the term structure of the implied volatility as a function of $T$ in both models.

Figure 5 represents the relative error between the implied volatility given by the market and the one given by the calibrated models at 50 days using a penalization. The Heston model completely fails to preserve the term structure while being calibrated at 50 days. In comparison, the Stationary Heston behaves much better and the relative error does not explode for long-term expiries, meaning that the long run average price variance is well caught.

4. Toward the pricing of exotic options

In this section, we evaluate first Bermudan options and then Barrier options under the Stationary Heston model. For both products, the pricing relies on a Backward Dynamic Programming Principle. The numerical solution we propose is based on a two-dimensional product recursive quantization scheme. We extend the methodology previously developed by Callegaro et al. (2017), Fiorin et al. (2018), and Callegaro et al. (2018), where they considered an Euler–Maruyama scheme for both components. In this paper, we consider a two-dimensional product recursive quantization scheme. We extend the methodology previously developed by Bally and Pagès (2003), Bally and Pagès (2005), and Pagès (2018) and the algorithm by Sagna (2010) and Pagès (2018) for Barrier Options based on the conditional law of the Brownian motion.

4.1. Discretization scheme of a stochastic volatility model

We first present the time discretization schemes we use for the asset-volatility couple $(S_t^{(v)}, v_t)$, $t \in [0,T]$. For the volatility, we choose a Milstein on a boosted version of the process to preserve the positivity of the volatility and we select an Euler–Maruyama scheme for the log of the asset.

4.1.1. The boosted volatility. Based on the discussion in Appendix 1, we will work with the following boosted volatility process: $Y_t = e^{\bar{\sigma}} v_t$, $t \in [0, T]$ for some $\kappa > 0$, whose diffusion is given by

$$dY_t = e^{\bar{\sigma}} \kappa \theta \, dt + \xi e^{\xi t/2} \sqrt{Y_t} \, dB_t.$$  

(25)

The Milstein discretization scheme of $Y_t$ is given by

$$\bar{Y}_{n+1} = M_{\tilde{b}, \tilde{\sigma}}(k, \bar{Y}_n, Z_{k+1})$$  

(26)

with $(Z_k)_{k \geq 1}$ is an i.i.d. sequence of standard normal random variables, $k = \frac{n}{N}$ and $\tilde{b}$ and $\tilde{\sigma}$ are given by

$$\tilde{b}(t,x) = e^{\xi t} \kappa \theta, \quad \tilde{\sigma}(t,x) = \xi \sqrt{x} e^{\xi t/2}$$

and $M_{\tilde{b}, \tilde{\sigma}}(t,x,z)$ defined by

$$M_{\tilde{b}, \tilde{\sigma}}(t,x,z) = x - \frac{\tilde{\sigma}(t,x)}{2\tilde{\sigma}'(t,x)} + h \left( \tilde{b}(t,x) - \frac{\tilde{\sigma}(t,x)\tilde{\sigma}'(t,x)}{2} \right) + \frac{(\tilde{\sigma}(t,x)\tilde{\sigma}'(t,x))}{2} \left( z + \frac{1}{\sqrt{h\tilde{\sigma}'(t,x)}} \right)^2.$$  

(28)

We made this choice of scheme because, under the Feller condition, the positivity of $M_{\tilde{b}, \tilde{\sigma}}$ is ensured, since

$$M_{\tilde{b}, \tilde{\sigma}}(t,x,z) = h e^{\xi t} \left( \kappa \theta - \xi^2 \frac{4}{4} \right) + h \xi^2 e^{\xi t} \left( z + 2\sqrt{x} \sqrt{h e^{\xi t/2}} \right)^2$$  

(29)

and

$$\xi^2 \leq 2\kappa \theta \leq 4\kappa \theta.$$  

Other schemes could have been used, see Alfonsi (2005) for an extensive review of the existing schemes for the discretization of the CIR model, but in our case we needed one allowing us to use the fast recursive quantization, i.e., where we can express explicitly and easily the cumulative distribution function and the first partial moment of the scheme, which is the case of the Milstein scheme (we give more details in Section 4.2).

Hence, as our time-discretized scheme is well defined because its positivity is ensured if the Feller condition is satisfied, we can start to think of the time discretization of our process $(S_t^{(v)})_{t \in [0,T]}$.

4.1.2. The log-asset. For the asset, the standard approach is to consider the process which is the logarithm of the asset $X_t = \log(S_t)$. Applying Itô’s formula, the dynamics of $X_t$ is given by

$$dX_t = \left( r - q - \frac{v_t}{2} \right) dt + \sqrt{v_t} dW_t.$$  

(30)

Now, using a standard Euler–Maruyama scheme for the discretization of $X_t$, we have

$$\left\{ \begin{array}{c} \bar{X}_{n+1} = \mathcal{E}_{b, \sigma}(k, \bar{X}_n, \bar{Y}_n, Z_{k+1}^1) \\ \bar{Y}_{n+1} = M_{\tilde{b}, \tilde{\sigma}}(k, \bar{Y}_n, Z_{k+1}^2) \end{array} \right.$$  

(31)

where $(Z_{k}^1, Z_{k}^2)_{k \geq 1}$ is an i.i.d. sequence of bivariate normal random variables with $Z_{k}^1 \sim N(0,1)$, $Z_{k}^2 \sim N(0,1)$, Corr$(Z_{k}^1, Z_{k}^2) = \rho$ and

$$\mathcal{E}_{b, \sigma}(t,x,y,z) = x + b(t,x,y)h + \sigma(t,x,y)\sqrt{h} z$$  

(32)

with

$$b(t,x,y) = r - q - \frac{e^{-\xi t} y}{2} \quad \text{and} \quad \sigma(t,x,y) = e^{-\xi t/2} \sqrt{y}.$$  

(33)
4.2. Hybrid product recursive quantization

In this part, we describe the methodology used for the construction of the product recursive quantization tree of the coupled log asset-boosted volatility in the Heston model.

In figure 6, as an example, we synthesise the main idea behind the recursive quantization of a diffusion $v_t$ which has been time-discretized with $F_0(t,x,z)$. We start at time $t_0 = 0$ with a quantizer $\hat{v}_0$ taking values in the grid $\Gamma_0 = \{v_0^0, \ldots, v_0^{10}\}$ of size 10, where each point is represented by a black bullet (*) with probability $p_0^i = p(\hat{v}_0 = v_0^i)$ is represented by a bar. In the Stationary Heston model, $\hat{v}_0$ is an optimal quantization of the Gamma distribution given by (6) and (7). Then, starting from this grid, we simulate the process from time $t_0$ to time $t_1 = 5$ days with our chosen time-discretization scheme $F_0(t,x,z)$, yielding $\hat{v}_1 = F_0(t_0,\hat{v}_0, Z_1)$, where $Z_1$ is a standardized Gaussian random variable. Each trajectory starts from point $v_0^i$ with probability $p_0^i$. And finally we project the obtained distribution at time $t_1$ onto a grid $\Gamma_1 = \{v_1^0, \ldots, v_1^{10}\}$ of cardinality 10, represented by black triangles () such that $\hat{v}_1$ is an optimal quantizer of the discretized and simulated process starting from quantizer $\hat{v}_0$ at time $t_0 = 0$.

Remark 4.1 In practice, for low dimensions, we do not simulate trajectories. We use the information on the law of $\hat{v}_1$ conditionally of starting from $\hat{v}_0$. The knowledge of the distribution allows us to use deterministic algorithms during the construction of the optimal quantizer of $\hat{v}_1$ that are a lot faster than algorithms based on simulation.

In our case, we consider the following stochastic volatility system:

$$
\begin{align*}
    dX_t &= b(t, X_t, Y_t) \, dt + \sigma(t, X_t, Y_t) \, dW_t \\
    dY_t &= \tilde{b}(t, Y_t) \, dt + \tilde{\sigma}(t, Y_t) \, d\tilde{W}_t,
\end{align*}
$$

where $W_t$ and $\tilde{W}_t$ are two correlated Brownian motions with correlation $\rho \in [-1, 1]$, $b$ and $\sigma$ are defined in (33) and $\tilde{b}$ and $\tilde{\sigma}$ are defined in (27). Our aim is to build a quantization tree of the couple $(X_t, Y_t)$ at given dates $t_k$, $k = 0, \ldots, n$ based on a recursive product quantization scheme. The product recursive quantization of such diffusion system has already been studied by Callegaro et al. (2017) and Rudd et al. (2017) in the case where both processes are discretized using an Euler–Maruyama scheme.

One can notice that building the quantization tree $(\hat{Y}_k)_{k \in \{0, \ldots, n\}}$ approximating $(Y_k)_{k \in \{0, \ldots, T\}}$ is a one-dimensional problem as the diffusion of $Y_t$ is autonomous. Hence, based on our choice of discretization scheme, we will apply the fast recursive quantization (detailed above in figure 6) that was introduced in Pagès and Sagna (2015) for one-dimensional diffusion discretized by an Euler–Maruyama discretization scheme and then extended to higher order schemes, still in one dimension, by McWalter et al. (2018). The minor difference with existing literature is that, in our problem, the initial condition $v_0$ is not deterministic.

Then, using the quantization tree of $(\hat{Y}_k)_{k \in \{0, \ldots, n\}}$ we will be able to build the tree $(\hat{X}_k)_{k \in \{0, \ldots, n\}}$ following ideas developed in Callegaro et al. (2017), Rudd et al. (2017), Fiorin et al. (2018), and Callegaro et al. (2018). Indeed, once the quantization tree of the volatility is built, we are in a one-dimensional setting and we are able to use fast deterministic algorithms.

An estimate of the $L^2$-error induced by the above ‘hybrid’ product recursive quantization approximation scheme has been established in Montes (2020), Chapter 5. Classical results on quantization-based schemes on the $L^2$-error, showed in Fiorin et al. (2018) and Pagès and Sagna (2021), do not apply here. These estimates rely on Lipschitz continuity propagation of the semi-group induced by the scheme which is not satisfied here (due to the presence of a square root in the diffusion term of the volatility in the CIR model (26)). The upper bound obtained in Montes (2020) should be considered with caution because it does not go to 0 when the number of time-steps goes to infinity. However, in practice, the number of time-steps is fixed and we study the behavior as a function of $N_{1,j}$ and $N_{2,j}$.

Figure 6. Example of recursive quantization of the volatility process in the Heston model for one time-step.
4.2.1. Quantizing the volatility (a one-dimensional case).

Let \((Y_t)_{t \in [0,T]}\) be a stochastic process in \(\mathbb{R}\) and solution to the stochastic differential equation
\[
dY_t = \tilde{b}(t, Y_t) dt + \tilde{\sigma}(t, Y_t) dW_t
\]
where \(Y_0\) has the same law than the stationary measure \(\nu\), \(L(Y_0) = \nu\). In order to approximate our diffusion process, we choose a Milstein scheme for the time discretization, as defined in (28) and we build recursively the Markovian quantization tree \((\hat{Y}_k)_{k \in [0,T]}\) where \(\hat{Y}_{k+1}\) is the Voronoi quantization of \(\hat{Y}_{k+1}\) defined by
\[
\hat{Y}_{k+1} = \mathcal{M}_{\hat{b},\hat{\sigma}}(t_k, \hat{Y}_k, Z_{k+1}^2), \quad \hat{Y}_{k+1} = \text{Proj}_{\hat{Y}_{k+1}} (\hat{Y}_{k+1})
\]
and the projection operator \(\text{Proj}_{\hat{Y}_{k+1}} (\cdot)\) is defined in (A3), \(\Gamma_{N_{k+1}} = \{y_{k+1}^1, \ldots, y_{N_{k+1}}^k\}\) is the grid of the optimal quantizer of \(\hat{Y}_{k+1}\) and \(Z_{k+1}^2 \sim \mathcal{N}(0,1)\). In order to alleviate the notations, we will denote \(\hat{Y}_k\) and \(\hat{Y}_k\) in place of \(\hat{Y}_{k+1}\).

The first step consists in building \(\hat{Y}_0\), an optimal quantizer of size \(N_{0,0}\) of \(Y_0\). Noticing that \(Y_0 = Y_0^0\), we use the optimal quantizer we built for the pricing of European options. Then, we build recursively \((\hat{Y}_{k})_{k=0,\ldots,n}\), where the \(N_{k,}\)-tuple are defined by \(y_{k+1}^i = (y_{k+1}^1, \ldots, y_{N_{k,}+1}^i)\), by solving iteratively the minimization problem defined in Appendix 2 in (A7), with the help of Lloyd’s method I. Replacing \(X\) by \(\hat{Y}_{k+1}\) in (A7) yields
\[
y_{k+1}^i = \left[ E\left[ \mathcal{M}_{\hat{b},\hat{\sigma}}(t_k, \hat{Y}_k, Z_{k+1}^2) 1_{\mathcal{M}_{\hat{b},\hat{\sigma}}(t_k, \hat{Y}_k, Z_{k+1}^2) \in \mathcal{C}(\gamma_{N_{k+1}}^{(i)})} \right] \right]
\]
and
\[
y_{k+1}^i = \sum_{j=1}^{N_{k,}} \left[ E\left[ \mathcal{M}_{\hat{b},\hat{\sigma}}(t_k, \hat{Y}_k, Z_{k+1}^2) 1_{\mathcal{M}_{\hat{b},\hat{\sigma}}(t_k, \hat{Y}_k, Z_{k+1}^2) \in \mathcal{C}(\gamma_{N_{k+1}}^{(j)})} \right] p_{k+1}^j \right]
\]
where \(C_1(\gamma_{N_{k+1}}^{(i)}) = (y_{k+1}^{i+1}, y_{k+1}^{i+1/2})\) is defined in (A2), \(F_k^j\) and \(K_j^k\) are the cumulative distribution function and the first partial moment function of \(U_k^j \sim \mu_k^j + \kappa_j^k(Z_{k+1}^1 + \lambda_j^k)^2\) respectively with
\[
k_j^k = \frac{\lambda_j^k}{\sqrt{\lambda_j^k}}, \quad \lambda_j^k = \frac{1}{\sqrt{\lambda_j^k}}, \quad \text{and}
\]
\[
\mu_j^k = y_j^k - \frac{\lambda_j^k}{2\lambda_j^k}(Y_k^j)^2 + h \left( \frac{\lambda_j^k}{\sqrt{\lambda_j^k}} - \frac{\lambda_j^k}{2\lambda_j^k} \right).
\]
The functions \(F_k^j\) and \(K_j^k\) can explicitly be determined in terms of the density and the cumulative distribution function of the normal distribution.

**Lemma 4.2** Let \(\mu = \mu + \kappa(Z + \lambda)^2\), with \(\mu, \kappa, \lambda \in \mathbb{R}, \lambda \geq 0, \kappa > 0, Z \sim \mathcal{N}(0,1)\) then the cumulative distribution function \(F_k^j\) and the first partial moment \(K_{\mu}^k\) of \(U\) are given by
\[
F_k^j = \left( F_k^j(x_j^i) - F_k^j(x_j^i) \right) \mathbb{1}_{x_j^i \in \mu}
\]
\[
K_{\mu}^k = \left( F_k^j(x_j^i) \mu + \kappa \right) + k \sqrt{2\pi} \left( x - \sqrt{x \mu} \right) \mathbb{1}_{x \in \mu}
\]
where \(x = \sqrt{x \mu} - \lambda, x_j = -\sqrt{x \mu} \lambda, \text{and } F_k^j\) is the cumulative distribution function of \(Z\).

Finally, we can apply the Lloyd algorithm defined in Appendix A10 with \(F_k^j\) and \(K_{\mu}^k\) defined by
\[
F_k^j = \sum_{i=1}^{N_{k,}} p_k^j \mathbb{1}_{x_j^i \in \mu}
\]
\[
F_k^j = \sum_{i=1}^{N_{k,}} p_k^j \mathbb{1}_{x_j^i \in \mu}
\]
In order to be able to build recursively the tree quantization \((\hat{Y}_{k})_{k=0,\ldots,n}\), we need to have access to the weights \(p_k^j = P(\hat{Y}_{k+1} = y_{k+1}^j)\), which can be themselves computed recursively, as well as the conditional probabilities \(p_k^j = P(\hat{Y}_{k+1} = y_{k+1}^j | \hat{Y}_k = y_k^j)\).

**Lemma 4.3** The conditional probabilities \(p_k^j\) are given by
\[
p_k^j = F_k^j(y_{k+1}^j) - F_k^j(y_{k+1}^j).
\]
And the probabilities \(p_k^j+1\) are given by
\[
p_k^j+1 = \sum_{i=1}^{N_{k,}} p_k^j p_{k+1}^j.
\]

**Proof** The
\[
p_k^j = P(\hat{Y}_{k+1} = y_{k+1}^j | \hat{Y}_k = y_k^j)\]
\[
= P\left( \mathcal{M}_{\hat{b},\hat{\sigma}}(t_k, \hat{Y}_k, Z_{k+1}^2) \in \mathcal{C}(\gamma_{N_{k+1}}^{(j)}) | \hat{Y}_k = y_k^j \right)
\]
\[
= P\left( \mathcal{M}_{\hat{b},\hat{\sigma}}(t_k, \hat{Y}_k, Z_{k+1}^2) \in \mathcal{C}(\gamma_{N_{k+1}}^{(j)}) \right)
\]
\[
= F_k^j(y_{k+1}^j) - F_k^j(y_{k+1}^j).
\]
and

\[ p_{j+1}^k = \mathbb{P} \left( Y_{k+1} = y_{j+1}^k \right) = \sum_{i=1}^{N_{\text{d}}} \mathbb{P} \left( Y_{k+1} = y_{j+1}^k \mid \tilde{X}_k = y_e^k \right) \times \mathbb{P} \left( \tilde{X}_k = y_e^k \right) = \sum_{i=1}^{N_{\text{d}}} p_i^k p_j^i. \]

As an illustration, we display in figure 7 the rescaled grids obtained after recursive quantization of the boosted-volatility, where \( \tilde{X}_k = e^{-x_k^e} \tilde{X}_k \) and \( (\tilde{X}_k)_{k=1, \ldots, n} \) are the quantizers built using the fast recursive quantization approach.

### 4.2.2. Quantizing the asset (a one-dimensional case again)

Now, using the fact that \( Y_{i,t} \) has already been quantized and the Euler–Maruyama scheme of \( (X_i)_t \) as defined (32), we define the Markov quantized scheme

\[
\tilde{X}_{i,t+1} = \mathcal{E}_{\sigma, \rho} (t_k, \tilde{X}_{i,t}, \tilde{X}_{i,t}, Z_{i,t+1}) \quad \text{and} \quad \tilde{X}_{i,t+1} = \text{Proj}_{i,t+1} (\tilde{X}_{i,t+1})
\]

(44)

where the projection operator \( \text{Proj}_{i,t+1} (\cdot) \) is defined in (A3), \( \Gamma_{N_{\text{d}}}^k \) is the optimal \( N_{\text{d}} \)-quantizer of \( \tilde{X}_{i,t+1} \) and \( Z_{i,t+1} \sim \mathcal{N}(0,1) \). Again, to simplify the notations, \( \tilde{X}_k \) and \( \tilde{X}_k \) are denoted in what follows by \( \tilde{X}_k \) and \( \tilde{X}_k \).

Note that we are still in an one-dimensional case, hence we can apply the same methodology as developed in Appendix 2 and build recursively the quantization \( (\tilde{X}_k)_{k=0, \ldots, n} \) as detailed above, where the \( N_{\text{d}} \)-tuple are defined by \( x_{i,t+1} = (x_{i,1}^e, \ldots, x_{i,n}^e) \). Replacing \( X \) by \( \tilde{X} \) in (A7) yields

\[
\begin{align*}
\tilde{x}_{i,t+1}^k &= \mathbb{E} \left[ \mathcal{E}_{\sigma, \rho} (t_k, \tilde{X}_{i,t}, \tilde{X}_{i,t}, Z_{i,t+1}) \right] \\
&= \sum_{i=1}^{N_{\text{d}}} \sum_{j=1}^{N_{\text{d}}} \mathbb{P} \left( \mathcal{E}_{\sigma, \rho} (t_k, \tilde{X}_{i,t}, \tilde{X}_{i,t}, Z_{i,t+1}) \in C_i (\Gamma_{N_{\text{d}}}^k) \right) p_i^k p_j^i \\
&= \sum_{i=1}^{N_{\text{d}}} \sum_{j=1}^{N_{\text{d}}} \mathbb{E} \left[ \mathcal{E}_{\sigma, \rho} (t_k, \tilde{X}_{i,t}, \tilde{X}_{i,t}, Z_{i,t+1}) \right] p_i^k p_j^i
\end{align*}
\]

(45)

where \( p_i^k = \mathbb{P} (\tilde{X}_k = x_{i}^e, \tilde{Y}_k = y_{i}^e) \) and \( F_{i,t+1}^k \) are the cumulative distribution function and the first partial moment of the normal distribution \( \mu_{i,t+1}^k + \sigma_{i,t+1}^k \) and they are defined by

\[
F_{i,t+1}^k (x) = F_{\sigma_{i,t+1}^k} \left( \frac{x - \mu_{i,t+1}^k}{\sigma_{i,t+1}^k} \right)
\]

(46)

with

\[
\begin{align*}
\mu_{i,t+1}^k &= x_{i,t+1}^k + b(t_k, x_{i,t+1}^k, y_{i,t+1}^k) h \quad \text{and} \quad \sigma_{i,t+1}^k = \sigma (t_k, x_{i,t+1}^k, y_{i,t+1}^k) \sqrt{h}
\end{align*}
\]

(47)

and \( F_{i} \) and \( K_{i} \) are the cumulative distribution function and the first partial moment of the standard normal distribution.

Finally, we apply the Lloyd method defined in Appendix (A10) with \( F_{i} \) and \( K_{i} \) defined by

\[
\begin{align*}
F_{i} (x) &= \sum_{i=1}^{N_{\text{d}}} \sum_{j=1}^{N_{\text{d}}} p_{i,j}^k F_{i,j} (x) \\
K_{i} (x) &= \sum_{i=1}^{N_{\text{d}}} \sum_{j=1}^{N_{\text{d}}} p_{i,j}^k K_{i,j} (x).
\end{align*}
\]

(48)

The sensitive part concerns the computation of the joint probabilities \( p_{i,j}^k \). Indeed, they are needed at each step to be able to design recursively the quantization tree.

**Lemma 4.4** The joint probabilities \( p_{i,j}^k \) are given by the following forward induction:

\[
p_{i,j}^k = \sum_{i=1}^{N_{\text{d}}} \sum_{j=1}^{N_{\text{d}}} p_{i,j}^k (\tilde{X}_{i,t+1} = x_{i,t+1}^k, \tilde{Y}_{i,t+1} = y_{i,t+1}^k) \\
\tilde{X}_{i,t+1} = x_{i,t+1}^k, \tilde{Y}_{i,t+1} = y_{i,t+1}^k
\]

(49)

where the joint conditional probabilities \( \mathbb{P} (\tilde{X}_{i,t+1} = x_{i,t+1}^k, \tilde{Y}_{i,t+1} = y_{i,t+1}^k \mid \tilde{X}_k = x_{i}^e, \tilde{Y}_k = y_{i}^e) \) are given by the formulas below, depending on the correlation

- if \( \text{Corr}(Z_{i,t+1}^k, Z_{i,t+1}^k) = \rho = 0 \)

\[
\begin{align*}
\mathbb{P} (\tilde{X}_{i,t+1} = x_{i,t+1}^k, \tilde{Y}_{i,t+1} = y_{i,t+1}^k \mid \tilde{X}_k = x_{i}^e, \tilde{Y}_k = y_{i}^e) &= p_{i,j}^k \left[ \mathcal{N} (x_{i,t+1,j+1}^k) - \mathcal{N} (x_{i,t+1,j+1}^k) \right],
\end{align*}
\]

(50)

where \( p_{i,j}^k \) is defined in (42) and

\[
\begin{align*}
x_{i,t+1,j} &= \frac{x_{i,t+1,j} - \mu_{i,t+1,j}}{\sigma_{i,t+1,j}}, \\
\frac{x_{i,t+1,j}}{\sigma_{i,t+1,j}} &= \frac{x_{i,t+1,j} - \mu_{i,t+1,j}}{\sigma_{i,t+1,j}}.
\end{align*}
\]

(51)

with \( \mu_{i,t+1,j} \) and \( \sigma_{i,t+1,j} \) defined in (47).

- if \( \text{Corr}(Z_{i,t+1}^k, Z_{i,t+1}^k) = \rho \neq 0 \)

\[
\begin{align*}
\mathbb{P} (\tilde{X}_{i,t+1} = x_{i,t+1}^k, \tilde{Y}_{i,t+1} = y_{i,t+1}^k \mid \tilde{X}_k = x_{i}^e, \tilde{Y}_k = y_{i}^e) &= \mathbb{P} \left( Z_{i,t+1} = y_{i,t+1}^k \mid \tilde{X}_k = x_{i}^e, \tilde{Y}_k = y_{i}^e \right)
\end{align*}
\]

(52)
we have time step of 5 days with grids of size $N = 10$. The recursive quantization methodology is applied to $Y_k$ and then we display the rescaled volatility $\tilde{v}_k = e^{-x(t)\tilde{v}_k}$.

$$
Z_k^{i+1} \in \left(\sqrt{y_{i,2i,\ldots,-1}^{k+1}} - \lambda_k^{k+1}, \sqrt{y_{i,2i,\ldots,-1}^{k+1}} - \lambda_k^{k+1}\right)
$$

$$
+ \mathbb{P} \left( Z_k^{i+1} \in \left(\sqrt{y_{i,2i,\ldots,1}^{k+1}} - \lambda_k^{k+1}, \sqrt{y_{i,2i,\ldots,1}^{k+1}} - \lambda_k^{k+1}\right) \right)
$$

$$
Z_k^{i+1} \in \left[ -\sqrt{y_{i,2i,\ldots,-1}^{k+1}} - \lambda_k^{k+1}, -\sqrt{y_{i,2i,\ldots,-1}^{k+1}} - \lambda_k^{k+1}\right)
$$

(52)

where

$$
y_{i,2i,\ldots,-1}^{k+1} = 0 \vee \sqrt{y_{j,2j,\ldots,-1}^{k+1} - \mu_k^{k+1}}
$$

(53)

$$
y_{i,2i,\ldots,1}^{k+1} = 0 \vee \sqrt{y_{j,2j,\ldots,1}^{k+1} - \mu_k^{k+1}}
$$

(54)

with $\mu_k^{k+1}, \kappa_k^{k+1}$ and $\lambda_k^{k+1}$ defined in (39).

**Remark 4.5** The probability in the right-hand side of (52) can be computed using the cumulante distribution function of a correlated bivariate normal distribution†. Indeed, let

$$
P_{\rho}(x_1, x_2) = \mathbb{P}(X_1 \leq x_1, X_2 \leq x_2)
$$

the cumulante distribution function of the correlated centered Gaussian vector $(X_1, X_2)$ with unit variance and correlation $\rho$, we have

$$
\mathbb{P} \left( X_1 \in [a, b], X_2 \in [c, d] \right)
$$

\[\text{Proof}\]

$$
p_{\rho}(x_{i,j+1}) = \mathbb{P} \left( \tilde{X}_{k+1} = x_{i,j+1}^{k+1}, \tilde{Y}_{k+1} = y_{i,j+1}^{k+1} \right)
$$

$$
= F_{\rho}(b, d) - F_{\rho}(b, c) - F_{\rho}(a, d) + F_{\rho}(a, c)
$$

with $a, c \geq -\infty$ and $b, d \leq +\infty$.

- If $\text{Corr}(Z_{k+1}^{i,j}, Z_{k+1}^{i,j}) = \rho = 0$

$$
\mathbb{P} \left( \tilde{X}_{k+1} = x_{i,j+1}^{k+1}, \tilde{Y}_{k+1} = y_{i,j+1}^{k+1} \right) = \mathbb{P} \left( \tilde{X}_{k+1} = x_{i,j+1}^{k+1} \parallel \tilde{X}_k = x_{i,j}^{k}, \tilde{Y}_k = y_{i,j}^{k} \right)
$$

$$
= p_{\rho}^{k+1} \mathbb{P} \left( \tilde{X}_{k+1} = x_{i,j+1}^{k+1} \parallel \tilde{X}_k = x_{i,j}^{k}, \tilde{Y}_k = y_{i,j}^{k} \right)
$$

(54)
Remark 4.6 Another possibility for the quantization of the Stationary Heston model could be to use optimal quantizers for the volatility and the log-asset.

Indeed, these probability weights would not be as straightforward to compute as the methodology we adopt in this paper, namely using time-discretization schemes for both components. Our approach allows us to express the conditional probability of the couple as the probability that a correlated bivariate Gaussian vector lies in a rectangle domain and this can be easily be computed numerically.

4.3. Backward algorithm for Bermudan and Barrier options

4.3.1. Bermudan options. A Bermudan option is a financial derivative product that gives the right to its owner to buy or sell (or to enter to, in the case of a swap) an underlying product with a given payoff $\psi_t(\cdot, \cdot)$ at predefined exercise dates $\{t_0, \ldots, t_n\}$. Its price, at time $t_0 = 0$, is given by

$$\sup_{\tau \in \{t_0, \ldots, t_n\}} E\left[ e^{-\tau r_t} \psi_t(x_t, y_t) \mid \mathcal{F}_0 \right]$$

where $x_t$ and $y_t$ are solutions to the system defined in (34).

In this part, we follow the numerical solution first introduced by Bally and Pagès (2003) and Bally et al. (2005). They proposed to solve discrete-time optimal stopping problems using a quantization tree of the risk factors $X_t$ and $Y_t$.

Let $\mathcal{F}_t^{X, Y} = (\mathcal{F}_k)_{0 \leq k \leq n}$ the natural filtration of $X$ and $Y$. Hence, we can define recursively the sequence of random variable $\mathcal{F}$-integrable $(V_k)_{0 \leq k \leq n}$

$$V_n = e^{-r \eta^d} \psi_n(x_n, y_n),$$
$$V_k = \max \left( e^{-r \eta^d} \psi_k(x_k, y_k), E[V_{k+1} \mid \mathcal{F}_k] \right),$$

where $0 \leq k \leq n - 1$, called Backward Dynamic Programming Principle. Then

$$V_0 = \sup \left\{ E[ e^{-r \tau} \psi_t(X_t, Y_t) \mid \mathcal{F}_0 ] \mid \tau \in \Theta_{0,s} \right\}$$

with $\Theta_{0,s}$ the set of all stopping times taking values in $\{t_0, \ldots, t_n\}$. The sequence $(V_k)_{0 \leq k \leq n}$ is also known as the Snell envelope of the obstacle process $(e^{-r \eta^d} \psi_t(X_t, Y_t))_{0 \leq k \leq n}$. In the end, $E[V_0]$ is the quantity we are interested in. Indeed, $E[V_0]$ is the price of the Bermudan option whose payoff is $\psi_k$ and is exercisable at dates $\{t_1, \ldots, t_n\}$.

Following what was defined in (59), to compute $E[V_0]$, we will need to use the previously defined quantizer of $X_k$ and $Y_k$: $\tilde{X}_k$ and $\tilde{Y}_k$. Hence, for a given global budget $N = N_0 + N_2, \ldots, + N_0, N_2, \ldots$, the total number of nodes of the tree by the couple $(\tilde{X}_k, \tilde{Y}_k)_{0 \leq k \leq n}$, we can approximate the Backward Dynamic Programming Principle (59) by the following sequence involving the couple $(\tilde{X}_k, \tilde{Y}_k)_{0 \leq k \leq n}$

$$\tilde{V}_n = e^{-r \eta^d} \psi_n(\tilde{X}_n, \tilde{Y}_n),$$
$$\tilde{V}_k = \max \left( e^{-r \eta^d} \psi_k(\tilde{X}_k, \tilde{Y}_k), E[\tilde{V}_{k+1} \mid (\tilde{X}_k, \tilde{Y}_k)] \right),$$

$k = 0, \ldots, n - 1$.
Remark 4.7 A direct consequence of choosing recursive Markovian Quantization to spatially discretize the price process is that the sequence \((\tilde{X}_k, \tilde{Y}_k)_{0 \leq k \leq n}\) is Markovian. Hence \((\tilde{V}_k)_{0 \leq k \leq n}\) defined in (60) obeying a Backward Dynamic Programming Principle is the Snell envelope of \((e^{-rT} \psi_t(X, \tilde{Y}))_{0 \leq k \leq n}\). This is the main difference with the first approach of Bally and Pagès (2003) and Bally et al. (2005), where in the case they only had a pseudo-Snell envelope of \((e^{-rT} \psi_t(X, \tilde{Y}))_{0 \leq k \leq n}\).

Using the discrete feature of the quantizers, (60) can be rewritten as

\[
\tilde{v}_n(x_i^m, y_j^m) = e^{-rT} \psi_t(x_i^m, y_j^m), \quad i_1 = 1, \ldots, N_{1,n}, \quad i_2 = 1, \ldots, N_{2,n},
\]

\[
\tilde{v}_k(x_i^m, y_j^m) = \max \left( \left\{ e^{-rT} \psi_t(x_i^m, y_j^m) : \sum_{j=1}^{N_{k+1}} \pi_k^{i, j} \prod_{j=1}^{k} \tilde{v}_{k+1}(x_i^{j+1}, y_j^{j+1}), \quad k = 0, \ldots, n - 1 \right\} \right)
\]

where \(\pi_k^{i, j} \in \mathbb{P}(\tilde{X}_{k+1} = x_i^{k+1}, \tilde{Y}_{k+1} = y_j^{k+2} | \tilde{X}_k = x_i^k, \tilde{Y}_k = y_j^k)\) is the conditional probability weight given in (52).

Finally, the approximation of the price of the Bermudan option is given by

\[
E \left[ \tilde{V}_0(x_0, \tilde{Y}_0) \right] = \sum_{i=1}^{N_{1,0}} p_i \tilde{v}_0(x_0, y_i^0) \tag{62}
\]

with \(p_i = \mathbb{P}(\tilde{X}_0 = x_i^0)\) given by (19).

4.3.2. Barrier options. A Barrier option is a path-dependent financial product whose payoff at maturity date \(T\) depends on the value of the process \(X_T\) at time \(T\) and its maximum or minimum over the period \([0, T]\). More precisely, we are interested by options with the following types of payoff:

\[
h = f(X_T) \mathbb{1}_{[\text{sup}_{0 \leq t \leq T} X_t \in I]} \quad \text{or} \quad h = f(X_T) \mathbb{1}_{[\text{inf}_{0 \leq t \leq T} X_t \in I]} \tag{63}
\]

where \(f\) is an unbounded interval of \(R\), usually of the form \((\infty, L]\) or \([L, +\infty)\) (\(L\) is the barrier) and \(f\) can be any vanilla payoff function (Call, Put, Spread, Butterfly, ...).

In this part, we follow the methodology initiated in Sagna (2010) in the case of functional quantization. This work is based on the Brownian bridge method applied to the Euler–Maruyama scheme as described, e.g., in Pagès (2018). We generalize it to stochastic volatility models and product Markovian recursive quantization. \(X_t\) being discretized by an Euler–Maruyama scheme, yielding \(\tilde{X}_k\) with \(k = 0, \ldots, n\), we can determine the law of \(\max_{0 \leq t \leq T} \tilde{X}_t\) and \(\min_{0 \leq t \leq T} \tilde{X}_t\) given the values \(\tilde{X}_k = x_k, \tilde{Y}_k = y_k, k = 0, \ldots, n\).

where \(x_k = x_k, y_k = y_k, k = 0, \ldots, n\).

and

\[
L \left( \min_{0 \leq t \leq T} \tilde{X}_t = x_k, \tilde{Y}_t = y_k, k = 0, \ldots, n \right) = L \left( \max_{k=0, \ldots, n} (G^{k}_{(0,y),u_1})^{-1}(U_k) \right) \quad \text{and} \quad L \left( \max_{0 \leq t \leq T} \tilde{X}_t = x_k, \tilde{Y}_t = y_k, k = 0, \ldots, n \right)
\]

\[
L \left( \min_{0 \leq t \leq T} \tilde{X}_t = x_k, \tilde{Y}_t = y_k, k = 0, \ldots, n \right) = L \left( \max_{k=0, \ldots, n} (F^{k}_{(0,y),u_1})^{-1}(U_k) \right) \quad \text{and} \quad L \left( \max_{0 \leq t \leq T} \tilde{X}_t = x_k, \tilde{Y}_t = y_k, k = 0, \ldots, n \right)
\]

with \(U_k|_{k=0, \ldots, n} - \text{i.i.d. uniformly distributed random variables over the unit interval and } (G^{k}_{(0,y),u_1} - 1) \text{ and } (F^{k}_{(0,y),u_1} - 1) \text{ are the inverse of the conditional distribution functions } G^{k}_{(0,y),u_1} \text{ and } F^{k}_{(0,y),u_1} \text{ defined by}

\[
G^{k}_{(0,y),u_1}(u) = \left( 1 - e^{-2n \frac{u - u_{\min}}{u_{\max} - u_{\min}}} \right) \mathbb{1}_{[u_{\min}, u_{\max}]} \tag{66}
\]

and

\[
F^{k}_{(0,y),u_1}(u) = 1 - \left( 1 - e^{-2n \frac{u - u_{\min}}{u_{\max} - u_{\min}}} \right) \mathbb{1}_{[u_{\min}, u_{\max}]} \tag{67}
\]

Now, using the resulting representation formula for \(E[f(\tilde{X}_T, \max_{0 \leq t \leq T} \tilde{X}_t)]\) (see, e.g., Sagna (2010) and Pagès (2018)), we have a new representation formula for the price of up-and-out options \(\tilde{P}_{UO}\) and down-and-out options \(\tilde{P}_{DO}\)

\[
\tilde{P}_{UO} = e^{-rT} E \left[ f(\tilde{X}_T) \mathbb{1}_{[\text{sup}_{0 \leq t \leq T} \tilde{X}_t \leq L]} \right] = e^{-rT} E \left[ f(\tilde{X}_T) \prod_{k=0}^{n-1} G^{k}_{(0,y),u_1}(L) \right] \tag{68}
\]

and

\[
\tilde{P}_{DO} = e^{-rT} E \left[ f(\tilde{X}_T) \mathbb{1}_{[\text{inf}_{0 \leq t \leq T} \tilde{X}_t \leq L]} \right] = e^{-rT} E \left[ f(\tilde{X}_T) \prod_{k=0}^{n-1} (1 - F^{k}_{(0,y),u_1}(L)) \right] \tag{69}
\]

where \(L\) is the barrier.

Finally, replace \(\tilde{X}_k\) and \(\tilde{Y}_k\) by \(\tilde{X}_k\) and \(\tilde{Y}_k\) and apply the recursive algorithm to approximate \(\tilde{P}_{UO}\) or \(\tilde{P}_{DO}\) by \(E[\tilde{V}_0]\) or equivalently \(E[\tilde{V}_0(x_0, \tilde{Y}_0)]\).

\[
\tilde{V}_n = e^{-rT} f(\tilde{X}_n), \quad \tilde{V}_k = E \left[ g_k(\tilde{X}_k, \tilde{Y}_k, \tilde{X}_{k+1}) \tilde{V}_{k+1} | (\tilde{X}_k, \tilde{Y}_k) \right], \quad 0 \leq k \leq n - 1 \tag{70}
\]

that can be rewritten as

\[
\tilde{v}_n(x_i^m, y_j^m) = e^{-rT} f(x_i^m), \quad i = 1, \ldots, N_{1,n} \quad j = 1, \ldots, N_{2,n}
\]

\[
\tilde{v}_k(x_i^m, y_j^m) = \sum_{j=1}^{N_{k+1}} \pi_k^{i, j} \prod_{j=1}^{k} \tilde{v}_{k+1}(x_i^{j+1}, y_j^{j+1}) \prod_{j=1}^{k} \tilde{v}_{k+1}(x_i^{j+1}, y_j^{j+1}) \tag{71}
\]

with \(\pi_k^{i, j} = \mathbb{P}(\tilde{X}_{k+1} = x_i^{k+1}, \tilde{Y}_{k+1} = y_j^{k+2} | \tilde{X}_k = x_i^k, \tilde{Y}_k = y_j^k)\) the conditional probabilities given in (52) and
In this part, we deal with numerical experiments in the \(N_t\) of time steps) and quantization grids of constant size: for \(n\) quantization and the benchmark, as a function of the strike \(K\) and \((N_1, N_2)\) where we set \(n = 180\). Relative error in percent between brackets.

### Table 2. Comparison between European options prices, with maturity \(T = 0.5\) (6 months), given by quantization and the benchmark, as a function of the strike \(K\) and of the number \(n\) of time-steps where we set \((N_1, N_2) = (50, 10)\). Relative error in percent between brackets.

| \(K\) | Benchmark | \((N_1, N_2)\) |
|-------|-----------|-----------------|
| Call  | 80        | 20.17           |
|       | 85        | 15.56           |
|       | 90        | 11.24           |
|       | 95        | 7.383           |
| Put   | 100       | 4.196           |
|       | 105       | 7.171           |
|       | 110       | 10.86           |
|       | 115       | 15.38           |
|       | 120       | 20.30           |
| Time  | 1.7 s + 5 ms | 16.5 s + 30 ms |

\(g_k(x, y, z)\) is either equal to \(G_{k,0,2}(L)\) or \(1 - F_{k,0,2}(L)\) depending on the option type. Finally, the approximation of the price of the barrier option is given by

\[
E[\tilde{V}_0] = E[\hat{\tilde{V}}_0(x_0, \hat{\tilde{V}}_0)] = \sum_{i=1}^{N_{1,0}} p_i \tilde{V}_0(x_0, y_i^0) \tag{72}\]

with \(p_i = \mathbb{P}(\tilde{V}_0 = y_i^0)\) given by (19).

### 4.4. Numerical illustrations

In this part, we deal with numerical experiments in the Stationary Heston model. Throughout this section, we implement the recursive quantization algorithm with size \(n\) (the number of time steps) and quantization grids of constant size: for all \(k = 0, \ldots, n\), we take \(N_{1,k} = N_1\) and \(N_{2,k} = N_2\) where \(n\) is the number of time steps. First, we use the European option framework to numerically evaluate the errors of recursive quantization as a function of quantization grids sizes. Then, we evaluate Bermudan options and Barrier options.

**4.4.1. Impact of \(N_1\), \(N_2\) and \(n\).** In this paragraph, we want to evaluate the impact that has the tree parameters \(N_1, N_2\) and \(n\) on the accuracy of the prices computed by product recursive quantization. For that purpose, we consider pricing of European options in the Stationary Heston model with parameters given in table 1 (obtained after the penalized calibration procedure). We set \(S_0 = 100\) to get prices of an order we are used to. The benchmark prices of 10 European options with various strikes \(K\): 5 calls and 5 puts, all in-the-money, with maturity \(T = 0.5\) (6 months) are computed using the quadrature formula based on Laguerre polynomials as explained in Section 2. At this point, let us emphasize that we are aware that neither quantization nor Monte Carlo should be used in practice to compute premia of European options in a Heston model.

In place of using the backward algorithm (60) (without the max function) for computing the expectation at the expiry date, we use the weights \(p_{i,(k)}^\theta\) defined in (49) and computed by a forward induction, to use the quantization-based cubature formula

\[
E\left[\psi_\theta(x_n, \hat{\tilde{V}}_n)\right] = \sum_{i_1=1}^{N_1} \sum_{i_2=1}^{N_2} \psi_\theta(x_{i_1}^n, y_{i_2}^n) p_{i_1,i_2}^\theta. \tag{73}\]

The results are reported in tables 2 and 3. The relative error induced by the quantization-based approximation is given.
between brackets. The computation time is split into the time taken to construct the tree and the pricing time (equation (73)). First, we compare in table 2 the prices for a fixed number of time-steps: \( n = 180 \) and we make vary the parameters \( N_1 \) and \( N_2 \). Then in table 3 we fix \((N_1, N_2) = (50, 10)\) and make \( n \) vary.

We notice from table 3 that the error is mostly explained by the number of the time-steps \( n \). By comparison, a Monte-Carlo pricer with \( M = 300,000 \) paths reaches the same order of precision than our quantization tree with \((N_1, N_2) = (100, 10)\) and \( n = 180 \) in 3.3 s. Once the quantification tree is built, the price calculation is extremely fast and if we compare it with the Monte Carlo estimator we have a ratio of 3.3/0.173 \(\simeq 19\) in calculation speed. Note also that it is much more efficient to store the quantization tree than to store all the paths of a Monte Carlo estimator.

### 4.4.2. Bermudan options

For Bermudan options, we do not use the parameters we calibrated in Section 3.2 because the interest rate and the dividend rate are very close to 0. Hence the prices of Bermudan options with those parameters are equal to European ones. In place we use the parameter set No. 5 defined in Fang and Oosterlee (2011) which is a set of parameters commonly used in the financial literature for the pricing of Bermudan options that we recall in table 4.

Moreover, for the Bermudan Put we will use its European price as a control variate. This has to be compared to including the payoff function into the regression basis at each time-steps in regression-projection methods ‘à la Longstaff-Schwarz’. The Backward Dynamic Programming Principle becomes

\[
\begin{align*}
\tilde{V}_n &= 0, \\
\tilde{V}_k &= \max \left( e^{-r\tau_k} \psi_k(X_k, Y_k) - C_{EU}^{n-k}(e^{X_k}), \right. \\
&\quad \left. \mathbb{E}[\tilde{V}_{k+1} \mid \mathcal{F}_k] \right), \quad 0 \leq k \leq n-1,
\end{align*}
\]  

(74)

where \( C_{EU}^{t}(x) \) is the European price for maturity \( t \) with initial stock price \( x \) in the Stationary Heston model (see Bally et al. (2005) for more details). Finally, the price of the Bermudan option \( V_0 \) is equal to

\[
V_0 = \tilde{V}_0 + C_{EU}^{T}(S_0)
\]

In table 5, we display the prices obtained using product hybrid recursive quantization of Bermudan Call/Put with \( n \) equally spaced exercise dates, strike \( K = 100 \) and maturity \( T = 0.25 \). The prices of the European Call and Put are 3.6729 and 2.6779 respectively. QC\(\text{Call} \) and QC\(\text{Put} \) are the prices given by quantization without control variate and QC\(\text{PutCV} \) are the prices obtained using the control variate as detailed in equation (74).

As \( r > 0 \), the Bermudan Call price is equal to the European one, namely 3.6729. Hence, we display the prices only for the sake of studying the convergence of the methodology. We notice in table 5 that QC\(\text{Call} \) converges to the European price but, as prescribed by theoretical error bounds, the more timesteps \( n \) we add in the quantization tree, the larger the grids need to be. For the Put, the methodology without control variate converges as well but control variate dramatically reduces the size of the grid needed to converge.

We are aware that the theoretical assumptions to obtain error bounds for quantization based space discretization

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**Table 4.** Test set No.5 from Fang and Oosterlee (2011).

| \( \rho \) | \( \theta \) | \( \kappa \) | \( \xi \) | \( S_0 \) | \( r \) | \( q \) |
|---|---|---|---|---|---|---|
| -0.64 | 0.0348 | 1.15 | 0.39 | 100 | 0.04 | 0 |

---

**Table 5.** Pricing of Bermudan options with maturity \( T = 0.25 \) and strike \( K = 100 \) in the Stationary Heston model with product hybrid recursive quantization.

| \( n \) | \( N_1 \) | \( N_2 \) | QC\(\text{Call} \) | QC\(\text{Put} \) | QC\(\text{PutCV} \) | QC\(\text{Call} \) | QC\(\text{Put} \) | QC\(\text{PutCV} \) | QC\(\text{Call} \) | QC\(\text{Put} \) | QC\(\text{PutCV} \) |
|---|---|---|---|---|---|---|---|---|---|---|---|
| 20 | 10 | 5 | 3.8048 | 2.9741 | 2.7335 | 3.6829 | 2.9529 | 2.7329 | 3.6750 | 3.0341 | 2.7266 |
| 40 | 10 | 5 | 3.7693 | 2.8613 | 2.7371 | 3.8152 | 2.9447 | 2.7383 | 3.7944 | 2.9649 | 2.7382 |
| 60 | 20 | 20 | 3.6997 | 2.7732 | 2.7377 | 3.7338 | 2.8156 | 2.7401 | 3.6811 | 2.8236 | 2.7402 |
| 100 | 20 | 20 | 3.6908 | 2.7635 | 2.7374 | 3.6447 | 2.7553 | 2.7384 | 3.6417 | 2.7767 | 2.7387 |
| 200 | 20 | 20 | 3.6782 | 2.7602 | 2.7375 | 3.6470 | 2.7488 | 2.7382 | 3.6484 | 2.7704 | 2.7384 |

---

**Figure 8.** Relative difference of Bermudan prices between the Heston model and the Stationary Heston model.
schemes of the Milstein scheme (see Pagès and Sagna (2021)) are not satisfied by the volatility process due to the presence of a square root. However, considering larger grids allow overcome this problem in practice. Indeed we provide error bound for our model in a supplementary material available in arXiv which guided our choice for the ratio grid size of the volatility over grid size of the asset for a given time discretion time step (see also Montes (2020)).

4.4.3. Heston vs stationary Heston. In figure 8, we compare the prices of Bermudan Call/Put with maturity $T = 0.25$ in the Heston model and the Stationary Heston model where both prices are given by product hybrid recursive quantization with $N_1 = 50$, $N_2 = 20$ and $n = 40$. Our aim is just to highlight the prices both models differ significantly, especially for short maturities. In order to compare the prices, we compute the relative difference between the 2 prices, namely $(P_{3H} - P_{2H})/P_{2H}$ where $P_{2H}$ is the price in the Heston model and $P_{3H}$ is the price in the Stationary Heston model. We used the same values given in table 4 for the parameters in common and set $v_0 = \theta$ in the case of the Heston model. This means that we took as a starting value for the volatility of the Heston its long-term mean. This confirms that, as expected, both models yield different prices. To be more precise, prices in the Stationary Heston model are higher on the tails and lower close to moneyness.

4.4.4. Barrier options. Finally, we apply our recursive quantization algorithm for a path-dependent European option pricing. The parameters of the Stationary Heston model are given in table 1 and $S_0 = 100$. The path-dependent option is an up-and-out Barrier option with strike $K = 100$, maturity $T = 0.5$ (6 months), barrier $L = 115$ and $N_2 = 10$. In figure 9, we display the prices obtained for a fixed value $N_2 = 10$ and different values of $N_1$ and $n$. Again, we can notice the impact of $n$ on the approximated price.

Acknowledgments

The authors wish to thank Guillaume Aubert for fruitful discussion on the Heston model and Jean-Michel Fayolle for his advice on the calibration of the models. The PhD thesis of Thibaut Montes is funded by a CIFRE grant from The Independent Calculation Agent (The ICA) and French ANRT. The first and third authors benefited for the support of the ‘Chaire Risques financiers’ funded by the Société Générale, under the aegis of the Fondation du Risque.

Disclosure statement

No potential conflict of interest was reported by the author(s).

Funding

This work was supported by Association Nationale de la Recherche (ANR) [2016/1360] ‘Chaire Risques Financiers’ funded by Société Générale, under the aegis of ‘Fondation du Risque’ [N/A].

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Appendices

Appendix I. Discretization scheme of the volatility preserving the positivity

We recall the dynamics of the volatility
\[ dV_t = \kappa(\theta - V_t) \, dt + \xi \sqrt{V_t} \, d\tilde{W}_t \]
with \( \kappa > 0 \), \( \theta > 0 \) and \( \xi > 0 \). In this section, we discuss the choice of the discretization scheme under the Feller condition, which ensures the positivity of the process.

A.1. Euler–Maruyama scheme

Let \((Z_k)_{k \geq 1}\) an i.i.d. sequence of standard normal distribution. Discretizing the volatility using an Euler–Maruyama scheme
\[ \bar{V}_{k+1} = \bar{V}_k + \kappa(\theta - \bar{V}_k)h + \xi \sqrt{\bar{V}_k} \sqrt{h} \tilde{Z}_{k+1} \]
with \( t_k = kh \), \( h = T/n \), may look natural. However, such a scheme clearly does not preserve positivity of the process even if the Feller condition is fulfilled since
\[ P(\bar{V}_{k+1} < 0) = P\left( Z_1 < \frac{V_0 - \kappa(\theta - V_0)h}{\xi \sqrt{V_0} \sqrt{h}} \right) > 0. \]
This suggests to introduce the Milstein scheme which is quite tractable in one dimension in absence of Lévy areas.

A.2. Milstein scheme and boosted Milstein scheme

The Milstein scheme of the stochastic volatility is given by
\[ \bar{V}_{k+1} = \mathcal{M}_{b,\sigma}(t_k, \bar{V}_{k+1}, Z_{k+1}) \]
where (see (28))
\[ \mathcal{M}_{b,\sigma}(t, x, z) = x - \frac{\sigma(x)}{2\sigma_0'(x)} + h \left( b(t, x) + \frac{(\sigma'(x))}{2} \right)^2 \]
\[ + \frac{(\sigma'(x))^2}{2} \left( z + \frac{1}{\sqrt{\sigma_0'(x)}} \right)^2 \]
with \( b(t, x) = \kappa(\theta - x) \), \( \sigma(x) = \xi \sqrt{x} \) and \( \sigma'(x) = \frac{\xi}{\sqrt{x}} \). Consequently, under the Feller condition, the positivity of \( \mathcal{M}_{b,\sigma}(t, x, z) \) is ensured if
\[ x \geq \frac{\sigma(x)}{2\sigma_0'(x)} \geq 0, \quad b(t, x) \geq \frac{(\sigma'(x))}{2} \geq 0. \]
In our case, if the first condition holds as an equality since \( \frac{\sigma(x)}{2\sigma_0'(x)} = \frac{\xi^{1/2}}{2\sqrt{\kappa}} \) is the second one fails. But
\[ \frac{(\sigma'(x))^2}{2} = \frac{\xi^{1/2}}{2} = \frac{\xi^{1/2}}{4} \]
can be bigger than \( b(t, x) \). To solve this problem, we consider the following k-boosted volatility process:
\[ Y_t = e^{t_0} V_t, \quad t \in [0, T], \]
which satisfies the stochastic differential equation
\[ dY_t = k \theta dt + \xi e^{t_0/2} \sqrt{T} d\tilde{W}_t. \]

**Remark A.1** Note that the process \((Y_t)_{t \in [0, T]}\) will have a higher variance but, having in mind a quantized scheme, this has no real impact (by contrast with a Monte Carlo simulation).
Now, if we look at the Milstein discretization scheme of $Y_t$,
\[ \tilde{Y}_{t+h} = M_{t,h} (\tilde{Y}_t, \tilde{Z}_t, Z_{t+1}) \]
using the notation defined in (28) where drift and volatility term are now time-dependent and given by
\[ \tilde{b}(t,x) = e^{t} x \theta, \quad \tilde{\sigma}(t,x) = \frac{\xi e^{t/2}}{2 \sqrt{x}.} \]
Under the Feller condition, the positivity of the above scheme is ensured, since
\[ \tilde{\sigma}(t,x) = x \quad \text{and} \quad \frac{\tilde{\sigma}(t,x)}{2 \tilde{\sigma}(t,x)} = \frac{\xi^{2} e^{t/2}}{4} \leq \tilde{b}(t,x) = e^{t} x \theta. \]
The last inequality is satisfied thanks to the condition $\frac{\xi^{2}}{2 \theta^{2}} \leq 1$ ensuring the positivity of the scheme.

**Appendix 2. Quadratic optimal quantization: generic approach**

Let $X$ be an $\mathbb{R}$-valued random variable with distribution $P_X$ defined on a probability space $(\Omega, \mathcal{A}, P)$ such that $X \in L^2(\mathbb{R}, \Omega, \mathcal{A}, P)$. Let $\Gamma_X = [x_1, ..., x_N] \subset \mathbb{R}$ be a subset of size $N$ indexed in an increasing order, called an $N$-quantizer. Any such $N$-quantizer is in a bijective correspondence with the $N$-tuple $x = (x_1^N, ..., x_N^N)$ lying in the simplex of $\mathbb{R}^N$. This leads us to sometimes replace $\Gamma_X$ by $x$.

The Voronoi partition $(C_i(\Gamma_X))_{i=1,...,N}$ induced by $\Gamma_X$ in such a one-dimensional setting is defined by
\[ C_i(\Gamma_X) = \{ x_{i-1/2}^N, x_{i+1/2}^N \}, \quad i \in \{1, ..., N-1\}, \]
\[ C_N(\Gamma_X) = \{ x_{N-1/2}^N, x_{N+1/2}^N \} \quad (\text{A2}) \]
where $\forall i \in \{2, ..., N\}, x_{i-1}^N = \frac{x_{i-1/2}^N + x_{i+1}^N}{2}$ and $x_{1/2}^N = -\infty$ and $x_{N+1/2}^N = +\infty$. Elements of the cell are closer to $x_i$ than to any other $x_j$ (up the endpoints).

The Voronoi quantization of $X$ induced by $\Gamma_X$, denoted $X^{\Gamma_X}$ or $\hat{X}^N$ when ambiguity, is defined as the nearest neighbor projection of $X$ onto $\Gamma_X$ based onto above Voronoi cells, namely
\[ \hat{X}^N = \text{Proj}_{\Gamma_X}(X) = \sum_{i=1}^{N} x_i^N \mathbb{1}_{X \in C_i(\Gamma_X)}. \quad (\text{A3}) \]

The probability distribution of $\hat{X}^N$ (also known as weights) is given by
\[ P(\hat{X}^N = x_i^N) = P_x(\Gamma_X) = P \left( X \in \{ x_{i-1/2}^N, x_{i+1/2}^N \} \right). \]

To measure the adequacy of a grid to the distribution of $X$, one introduces the quadratic distortion function at level $N$ given by
\[ Q_{2,N} : x = (x_1, ..., x_N) \mapsto \frac{1}{2} \mathbb{E} \left[ \min_{i \in \{1, ..., N\}} |X - x_i^N|^2 \right] \]
\[ = \frac{1}{2} \mathbb{E} \left[ \text{dist}(X, \Gamma_X)^2 \right] = \frac{1}{2} \|X - \hat{X}^N\|^2. \]

Of course, the above result can be extended to the $L^p$ case. We briefly recall some classical theoretical results, see Graf and Luschgy (2000) and Pagès (2018) for further details. The first one treats of the existence of optimal quantizers.

**Theorem 1** (Existence of optimal $N$-quantizers) Let $X \in L^2(\mathbb{P})$ and $N \in \mathbb{N}^*$. (a) The quadratic distortion function $Q_{2,N}$ at level $N$ attains a minimum at an $N$-tuple $x^* = (x_1^N, ..., x_N^N)$ and $\Gamma_N = \{x_i^N, i \in \{1, ..., N\}\}$ is a quadratic optimal quantizer at level $N$.
(b) If the support of the distribution $P_X$ of $X$ has at least $N$ elements, then $x^* = (x_i^N, ..., x_N^N)$ has pairwise distinct components, $P_x(C_i(\Gamma_N)) > 0, i \in \{1, ..., N\}$. Furthermore, the sequence $N \rightarrow \text{inf}_{\Gamma_N \subset \mathbb{R}^N} Q_{2,N}(x)$ converges to 0 and is decreasing as long as it is positive.

The uniqueness of an optimal $N$-quantizer (defined as an $N$-tuple with increasing components) due to Trushkin (1982) was shown in dimension one under log-concavity assumptions on the density of the distribution $P_X$ of $X$.

In what follows, we will drop the * subscript when speaking of optimal quantizers, $x^*$ and $\Gamma_N$ will be replaced by $x$ and $\Gamma_N$.

The next result elucidates the asymptotic behavior of the distortion. We saw in Theorem 1 that the infimum of the quadratic distortion converges to 0 as $N$ goes to infinity. The next theorem, known as Zador’s Theorem, establishes the sharp rate of convergence of the quantization error (stated here in the quadratic case).

**Theorem 2** (Zador’s Theorem)
(a) Sharp rate (Zador 1982, Graf and Luschgy 2000). Let $X \in L^2(\mathbb{P})$ for some $\theta > 0$. Let $P_x(\delta x) = \varphi(\xi) \cdot \lambda(dx) + v(dx)$, where $\nu$ is singular with respect to the Lebesgue measure $\lambda$ on $\mathbb{R}$.
\[ \lim_{N \rightarrow +\infty} \inf_{\Gamma_N \subset \mathbb{R}^N} \|X - \hat{X}^N\|_2 = \frac{1}{\sqrt{32}} \left( \int_{\mathbb{R}} \varphi^2 \lambda(dx) \right)^{3/2}. \quad (\text{A4}) \]

(b) Non asymptotic upper-bound (Graf and Luschgy 2000, Pagès 2018). Let $\theta > 0$. There exists a real constant $C_{1,\theta} \in (0, +\infty)$ such that, for every $R$-valued random variable $X$,
\[ \forall N \geq 1, \quad \min_{\Gamma_N \subset \mathbb{R}^N} \|X - \hat{X}^N\|_2 \leq C_{1,\theta} \sigma_0 \lambda(X) N^{-1} \quad (\text{A5}) \]
where, for $r \in (0, +\infty)$, $\sigma_r(X) = \min_{a \in \mathbb{R}} \|X - a\|_r < +\infty$ is the $L^r$-pseudo-standard deviation.

To compute optimal quantizers, we first differentiate $Q_{2,N}$, whose gradient is given by
\[ \nabla Q_{2,N}(x) = \left( \mathbb{E} \left[ \varphi(x^N - x) \mathbb{1}_{x \in (x_{i-1}^N, x_{i+1}^N)} \right] \right)_{i=1,...,N}. \quad (\text{A6}) \]

Then any critical point of $Q_{2,N}$, in particular its minima, satisfies
\[ \nabla Q_{2,N}(x) = 0 \]
\[ \iff x_i^N = \frac{K_x(x_{i-1}^N) - K_x(x_{i+1}^N)}{F_x(x_{i-1}^N) - F_x(x_{i+1}^N)}, \quad i = 1, ..., N \]
\[ \iff x_i^N = \frac{K_x(x_{i-1}^N) - K_x(x_{i-1}^N)}{F_x(x_{i-1}^N) - F_x(x_{i+1}^N)}, \quad i = 1, ..., N \quad (\text{A7}) \]
where $K_x(\cdot)$ and $F_x(\cdot)$ are the first partial moment and the cumulative distribution respectively, function of $X$, i.e.
\[ K_x(x) = \mathbb{E} \left[ X \mathbb{1}_{X \leq x} \right] \quad \text{and} \quad F_x(x) = \mathbb{P}(X \leq x). \quad (\text{A8}) \]

Note equation (A7) can be rewritten as the following so-called stationarity equation:
\[ \mathbb{E} \left[ \frac{X - \hat{X}^N}{\hat{X}^N} \right] = \hat{X}^N. \quad (\text{A9}) \]
quantizers: the Lloyd’s method I. This fixed point method was first devised in 1957 by S.P. Lloyd and published later (Lloyd 1982). Starting from a sorted $N$-tuple $\{x_i\}$ and with the knowledge of the first partial moment $K_x$ and the cumulative distribution function $F_x$ of $X$, the algorithm, which is essentially a deterministic fixed point method, is defined as follows:

$$x_i^{N,[n+1]} = \frac{K_x(x_i^{N,[n]} + 1/2) - K_x(x_i^{N,[n]} - 1/2)}{F_x(x_i^{N,[n]} + 1/2) - F_x(x_i^{N,[n]} - 1/2)}, \quad i = 1, \ldots, N. \quad (A10)$$

In Kieffer (1982), it has been shown that $(x_i^{(n)})_{n>1}$ converges exponentially fast toward $x$, the optimal quantizer, when the density $\varphi$ of $X$ is log-concave and not log-piecewise affine.

The convergence rate of this fixed point method can be improved, e.g. by using Anderson acceleration (see Anderson (1965) for the original paper and Walker and Ni (2011) for details on the procedure).

Other algorithms exist, such as stabbed gradient descent, the Newton–Raphson zero search procedure or its Levenberg–Marquardt variant which are deterministic procedures provided the density, the first partial moment and the cumulative distribution function of $X$ are known. Additionally, we can cite stochastic procedures such as the CLVQ procedure (for Competitive Learning Vector Quantization) which is a zero search stochastic gradient and the randomized version of the Lloyd’s method I. For more details, the reader can refer to Pagès and Yu (2016) and Pagès (2018).

Once the algorithm (A10) has been converging, we have at hand the quadratic optimal quantizer $\hat{X}^N$ of $X$ and its associated probabilities given by

$$P(\hat{X}^N = x_i^n) = F_x(x_i^{N,[n]} + 1/2) - F_x(x_i^{N,[n]} - 1/2), \quad i = 1, \ldots, n. \quad (A11)$$