Cellular Interference Alignment

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Abstract

Interference alignment promises that, in Gaussian interference channels, each link can support half of a degree of freedom (DoF) per pair of transmit-receive antennas. However, in general, this result requires to precode the data bearing signals over a signal space of asymptotically large diversity, e.g., over an infinite number of dimensions for time-frequency varying fading channels, or over an infinite number of rationally independent signal levels, in the case of time-frequency invariant channels. In this work we consider a wireless cellular system scenario where the promised optimal DoFs are achieved with linear precoding in one-shot (i.e., over a single time-frequency slot). We focus on the uplink of a symmetric cellular system, where each cell is split into three sectors with orthogonal intra-sector multiple access. In our model, interference is “local”, i.e., it is due to transmitters in neighboring cells only. We consider a message-passing backhaul network architecture, in which nearby sectors can exchange already decoded messages and propose an alignment solution that can achieve the optimal DoFs. To avoid signaling schemes relying on the strength of interference, we further introduce the notion of topologically robust schemes, which are able to guarantee a minimum rate (or DoFs) irrespectively of the strength of the interfering links. Towards this end, we design an alignment scheme which is topologically robust and still achieves the same optimum DoFs.

Index Terms

Interference Alignment, Cellular Systems, Interference Cancellation.

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I. INTRODUCTION

Interference is the dominant limiting factor in the performance of today’s wireless networks. Recent theoretical results \cite{1,2,3} have shown that transmission schemes based on interference alignment \cite{1,4} are able to provide half of the Degrees of Freedom (DoFs) of the interference-free rates\footnote{In our context, degrees of freedom are defined in Section II-D} to each user in the network. While these results promise significant gains compared to conventional interference mitigation techniques, the extent to which such gains can be realized in practice has been so far limited.

Most interference alignment schemes are either restricted to networks with a small number of users (typically three transmit-receive pairs) \cite{4,5,6,7}, or rely infinite channel diversity/resolution (e.g., through symbol extensions) for the more general cases \cite{1,2,4,8}. In fact, it has been shown that without symbol extensions, the DoF gain of any linear interference alignment scheme in a fully-connected network vanishes as the number of users increases \cite{9,10,11}. On the other hand, splitting the network into smaller sub-networks does not seem to be the solution either, as the remaining interference between sub-networks can eliminate the potential gain of interference alignment.

Another class of interference management techniques for wireless systems relies on utilizing the backhaul connections in order to enable cooperation between base stations. For the uplink, it is assumed that all base stations can share their received signal samples over the backhaul of the network and then jointly decode the corresponding user messages. Similarly, for the downlink, it is assumed that all user messages can be shared across the entire network, so that base stations can cooperatively transmit the messages to the corresponding users and manage the interference. This technique, often referred to as "Network MIMO" in the literature \cite{12,13,14,15}, effectively reduces the system to a (network-wide) multiple-antenna multiaccess channel for the uplink, or a multiple-antenna broadcast channel \cite{16,17} for the downlink. In an effort to reduce the significant backhaul load requirements of the above technique, limited base station collaboration has also been considered for the downlink \cite{18,19,20,21,22} where user message information is locally shared within smaller clusters of the network, and for the uplink \cite{23,24,25,26} where local receiver collaboration is enabled by sharing sampled (or quantized) received signals under backhaul connectivity (or capacity) constraints.
Here we propose a framework that can take advantage of the partial connectivity of extended\(^2\) cellular networks and provide insights and guidelines for the design of the next generation advanced inter-cell interference management in wireless systems. Within our framework, we are interested in the design of interference alignment schemes for cellular networks with the following three basic principles in mind.

- **Scalability**: The overall performance of the scheme should materialize irrespectively of the size of the cellular network, i.e., when the number of number of transmit-receive pairs becomes arbitrarily large.

- **Locality**: The transmission scheme should operate under local information exchange, and exploit the distributed nature of the cellular network.

- **Spectral Efficiency**: The scheme should aim for high spectral-efficiency by allowing more (interference-free) parallel transmissions to take place within the same spectrum.

In this paper we focus on the uplink of a sectored cellular system. Hence, receivers are located at the base station sites. Motivated by results embraced in practice (see [30] for an example), we assume that if a sector receiver can decode its own user’s message, it can share it with its neighboring sector receivers. This can be easily done for sectors located in the same base station site (co-located) and it can also be done with today’s technology and moderate infrastructure effort through local backhaul connections to neighboring cells. In particular, we show that this local and one directional data exchange — restricted only to decoded messages — is enough to reduce the uplink of a sectored cellular network to a topology in which the optimal degrees of freedom can be achieved without requiring time-frequency expansion or lattice alignment. Notice that in the proposed architecture we do not require that the sector receivers share received signal samples and/or perform joint decoding of multiple user messages, in contrast with existing works on “distributed antenna systems” and the popular and widely studied “Wyner model” [31], [32] for cellular systems. We emphasize that locally sharing decoded information messages over the backhaul and restricting to single-user decoding can be easily implemented within the current technology.

\(^2\)Following [27]–[29] we refer to an “extended” network as a network with a fixed spatial density of cells and increasing total coverage area, in contrast to a “dense” network where the total coverage area is fixed and the cell density increases.
In general, in coordinated cell processing strategies, there is always the risk that the signaling scheme relies on the strength of interference in order to achieve reliable communication. However, practical systems are not designed to guarantee that strength. On the contrary, current system deployment is geared to making interfering links as weak as possible. Hence, a scheme that relies on “strong interference” links would fail if applied to a system which was designed according to the current design guidelines. In order to address this issue, we introduce the concept of topological robustness, where the goal is to design communication schemes that can maintain a minimum rate (or degrees of freedom) no matter if the interference links are strong or weak. In particular, we show that such schemes exist in our framework and prove their optimality using a compound network formulation.

This paper is organized as follows. First, in Section II we describe the cellular model that we consider in this work and give a formal problem statement. Then, in Section III we state our results for networks with no intra-cell interference and give the corresponding achievability and converse theorems. In Section IV we extend our model to incorporate both out-of-cell and intra-cell interference and in Section V we focus on the design and optimality of topologically robust transmission schemes. Finally, we conclude this paper with Section VI.

II. PROBLEM FORMULATION

A. Cellular Model

Consider a large multiple-input multiple-output (MIMO) cellular network with three sectors per cell. As in current 4G cellular systems [33], orthogonal intra-sector multiple access is used in the uplink, such that, without loss of generality, we can consider a single user per sector, as shown in Fig. 1a. Within each sector, the receiver is interested in decoding the uplink message of the user associated with it and observes all other transmissions as interference. We consider here a symmetric configuration in which all transmitters and receivers in the network are equipped with $M$ antennas each and assume frequency-flat channel gains that remain constant throughout the entire communication.

Because of shadowing effects and distance-dependent pathloss, that are inherent to wireless communications [34], we assume that the interference seen at each receiver is generated locally,
Fig. 1: The cellular network topology and the corresponding interference graph: we consider the uplink of a MIMO cellular network with 120° sector receivers as depicted in Fig. 1a. Each receiver is interested in decoding the message of the mobile terminal associated with it and observes all other transmissions as interference. In our cellular model we assume four dominant sources of interference for each sector shown as orange arrows originating from its closest out-of-cell transmitters. Interference between the sectors of the same cell is depicted with black arrows. Fig. 1b shows the corresponding interference graph by taking into account all interfering links in a given cellular network, in which vertices represent transmit-receive pairs within sectors and edges indicate interfering neighbors. The dashed black edges in the above graph correspond to interference between sectors of the same cell that we are going to ignore until Section IV.

Let $S$ be the sector index set and let $\mathcal{N}(i)$ denote the set of the interfering neighbors of the $i$th sector. The received signals in our model can be written as

$$\mathbf{y}_i = \mathbf{H}_{ii}\mathbf{x}_i + \sum_{j \in \mathcal{N}(i)} \mathbf{H}_{ij}\mathbf{x}_j + \mathbf{z}_i, \quad i \in S$$

(1)

where $\mathbf{H}_{ij}$ is the $M \times M$ matrix of channel gains between the transmitter (user terminal) associated with sector $j$ and the receiver of sector $i$ and $\mathbf{x}_i$ are the corresponding transmitted signals satisfying the average power constraint $\mathbb{E}[||\mathbf{x}_i||^2] \leq P$.

In practice, the aggregate effect of non-neighboring transmitters contributes to the “noise floor” of the system. In [35], necessary and sufficient conditions on the channel gain coefficients of a Gaussian $K$-user interference channels are found such that “treating interference as noise” (TIN) is approximately optimal in the sense that, subject to these conditions, the TIN-achievable region is within an SNR-independent gap of the capacity region.
In this paper, we will consider two interference models based on the choice of the sets $\mathcal{N}(i), i \in \mathcal{S}$. In the first part, we will assume that the sectors located in the same cell do not interfere with each other and focus only on interference generated by nearby out-of-cell transmitters. This assumption can be motivated by taking into account the physical orientation and radiation patterns of the antennas used in sectored cellular systems, where the interference power from users in different sectors of the same cell should be much less than the interference power observed from out-of-cell users located in the sector’s line of sight. Then, in Section IV, we are going to lift this assumption and consider the case where sector receivers observe both out-of-cell and intra-cell interference. This extension takes into account the fact that users near the sector boundary may produce significant interference to the neighboring sector in the same cell, due to possibly non-ideal sectored antenna radiation patterns.

B. Interference Graph

A useful representation of our cellular model can be given by the corresponding interference graph $\mathcal{G}(\mathcal{V}, \mathcal{E})$ shown in Fig. 1b. In this graph, vertices represent transmit-receive pairs within each sector and edges indicate interfering neighboring links: the transmitter associated with a node $u \in \mathcal{V}$ causes interference to all receivers associated with nodes $v \in \mathcal{V}$ if there is an edge $(u, v) \in \mathcal{E}$. Notice that the interference graph is undirected and hence interference between sectors in our model goes in both directions.

More formally, we can define the interference graph $\mathcal{G}(\mathcal{V}, \mathcal{E})$ as follows. First, we are going to define the set $\mathcal{V}$ through a one-to-one mapping between the vertices of the graph and a set of complex numbers that we will refer to as node labels. The real and imaginary parts of these labels can be interpreted as the coordinates of the corresponding nodes embedded on the complex plane in a way that resembles the specific sector layout of our cellular system. A natural choice for this labeling is the set of the Eisenstein integers $\mathbb{Z}(\omega)$ that exhibits the hexagonal lattice structure shown in Fig. 2.

**Definition 1 (Eisenstein integers)** The set of Eisenstein integers, denoted as $\mathbb{Z}(\omega)$, is formed by all complex numbers of the form $z = a + b\omega$, where $a, b \in \mathbb{Z}$ and $\omega = \frac{1}{2}(-1 + i\sqrt{3})$.

Define $\mathcal{B}_r \triangleq \{z \in \mathbb{C}; |\text{Re}(z)| \leq r, |\text{Im}(z)| \leq \frac{\sqrt{3}}{2}r\}$ and let $\phi : \mathcal{V} \to \mathbb{Z}(\omega) \cap \mathcal{B}_r$ be an one-to-one mapping between the elements of $\mathcal{V}$ and the set of bounded Eisenstein integers given by $\mathbb{Z}(\omega) \cap \mathcal{B}_r$. 
For any \( v \in \mathcal{V} \) we say that \( \phi(v) \) is the label of the corresponding vertex in the interference graph. Correspondingly, the set of vertices \( \mathcal{V} \) is given by

\[
\mathcal{V} = \{ \phi^{-1}(z) : z \in \mathbb{Z}(\omega) \cap B_r \}.
\]

We now explicitly describe the set of edges \( \mathcal{E} \) in the interference graph in terms of the function \( \phi \). Consider the set of three segments in \( \mathbb{C} \)

\[
\Delta(z) = \{(z, z + \omega), (z, z + \omega + 1), (z + \omega, z + \omega + 1)\}
\]

and define the set

\[
\mathcal{D} \triangleq \bigcup_{[a, b] \in \mathbb{Z}, \ [a+b] \mod 3 \neq 0} \Delta(a + b\omega)
\]

to be the union of \( \Delta(a + b\omega) \) over all \( a, b \in \mathbb{Z} \) such that \( [a + b] \mod 3 \neq 0 \). Observe that the segments in \( \Delta(z) \) form a triangle with vertices in the Eisenstein integers \( z, z + \omega \) and \( z + \omega + 1 \), as shown in Fig. 2. The function \( f(a + b\omega) \triangleq [a + b] \mod 3 \) partitions the hexagonal lattice \( \mathbb{Z}(\omega) \) into three cosets. In particular, all points \( z \) such that \( f(z) = 0 \) form a sublattice \( \Lambda_0 \) of \( \mathbb{Z}(\omega) \), and the points \( z \) for which \( f(z) = 1 \) and \( f(z) = 2 \) corresponds to its cosets \( \Lambda_0 + 1 \) and \( \Lambda_0 - 1 \). In Fig. 2, the points of \( \Lambda_0, \Lambda_0 + 1 \) and \( \Lambda_0 - 1 \) are shown with squares, circles and diamonds, respectively. Without loss of generality, we assume that for all \( z \in \Lambda_0 \) the segments in \( \Delta(z) \) correspond to links between the three sectors of the same cell. Hence, under the assumption that such sectors do not interfere, we exclude the corresponding \( \{ \Delta(z) : z \in \Lambda_0 \} \) in the definition of \( \mathcal{D} \) in (3). Eventually,
the set of edges $\mathcal{E}$ representing out-of-cell interference is given by

$$\mathcal{E} = \{ (u, v) : u, v \in \mathcal{V} \text{ and } (\phi(u), \phi(v)) \in \mathcal{D} \}.$$  

(4)

**Definition 2 (Interference Graph)** The out-of-cell interference graph $G(\mathcal{V}, \mathcal{E})$ is an undirected graph defined by the set of vertices $\mathcal{V}$ given in (2) and the corresponding set of edges $\mathcal{E}$ given in (4). The graph vertices represent transmit-receive pairs in our cellular model and edges indicate interfering neighbors.

**C. Network Interference Cancellation**

We further consider a message-passing network architecture for our cellular system, in which sector receivers communicate locally in order to exchange decoded messages. Any receiver that has already decoded its own user’s message can use the backhaul of the network and pass it as side information to one or more of its neighbors. In turn, the neighboring sectors can use the received decoded messages in order to reconstruct the corresponding interfering signals and subtract them from their observation. It is important to note that this scheme only requires sharing (decoded) information messages between sector receivers and does not require sharing the baseband signal samples, which is much more demanding for the backbone network.

The above operation effectively cancels interference in one direction: all decoded messages propagate through the backhaul of the network, successively eliminating certain interfering links between neighboring sectors according to a specified decoding order. Fig. 3 illustrates the above network interference cancellation process in our cellular graph model assuming a “left-to-right, top-down” decoding order. Notice that edges are now directed in order to indicate the interference flow over the network. For example, if an undirected edge $(u, v)$ exists in $\mathcal{E}$ and, under this message-passing architecture, node $v$ decodes its message before node $u$ and passes it to node $u$ through the backhaul, then the resulting interference graph will contain the directed link $[u, v]$, indicating that the interference is from node (sector) $u$ node (sector) $v$ only.
Fig. 3: The directed interference graph $G_{\pi^*}(V, E_{\pi^*})$ after network interference cancellation according to the “left-to-right, top-down” decoding order $\pi^*$. The transmitter of a sector associated with node $i$ causes interference only to its neighboring sector receivers $j$ with $j < i$. Orange arrows indicate out-of-cell interference while black dashed arrows correspond to interference from within each cell.

A decoding order $\pi$ can be specified by defining a partial order “$\prec_{\pi}$” over the set of vertices $V$ in our interference graph. Then, the message of the user associated with vertex $v \in V$ will be decoded before the one associated with vertex $u \in V$ if $v \prec_{\pi} u$. In principle, we can choose any decoding order that partially orders the set $V$ and hence $\pi$ can be treated as an optimization parameter in our model.

**Definition 3 (Directed Interference Graph $G_{\pi}$)** For a given partial order “$\prec_{\pi}$” on $V$, the directed interference graph is defined as $G_{\pi}(V, E_{\pi})$ where $E_{\pi}$ is a set of ordered pairs $[u, v]$ given by $E_{\pi} = \{[u, v] : (u, v) \in E \text{ and } v \prec_{\pi} u\}$.

Next, we formally specify the “left-to-right, top-down” decoding order $\pi^*$ that has been chosen in Fig. 3. As we will show in the following section, this decoding order is indeed optimum and can lead to the maximum possible DoF per user in large cellular networks.

**Definition 4 (The Decoding Order $\pi^*$)** The “left-to-right, top-down” decoding order $\pi^*$ is defined by the partial ordering $\prec_{\pi^*}$ over $V$ such that for any $u, v \in V$, $v \prec_{\pi^*} u$ if

\[
\begin{cases}
\text{Im} (\phi(v)) > \text{Im} (\phi(u)), \\
\text{Im} (\phi(v)) = \text{Im} (\phi(u)) \text{ and } \text{Re} (\phi(v)) < \text{Re} (\phi(u))
\end{cases}
\]
D. Problem Statement

Our main goal is to design efficient communication schemes for the cellular model previously introduced. As a first-order approximation of a scheme’s efficiency, we will consider here the achievable DoFs, broadly defined as the number of point-to-point interference-free channels that can be created between transmit-receive pairs in the network.

More specifically, we are going to limit ourselves to linear beamforming strategies over multiple antennas assuming constant (frequency-flat) channel gains without allowing symbol extensions. We refer to such schemes as “one-shot”, indicating that precoding is achieved over a single time-frequency slot (symbol-by-symbol). Our goal it to maximize, over all decoding orders $\pi$, the average (per sector) achievable DoFs

$$d_{G,\pi} \triangleq \frac{1}{|\mathcal{V}|} \sum_{v \in \mathcal{V}} d_v,$$

(5)

where $\mathcal{G}(\mathcal{V}, \mathcal{E})$ is the interference graph defined in Section II-B and $d_v$ denotes the DoFs achieved by the transmit-receive pair associated with the node $v \in \mathcal{V}$, where

$$d_v = \lim_{P \to \infty} \frac{R_v(P)}{\log(P)},$$

and $R_v(P)$ is the achievable rate in sector $v \in \mathcal{V}$ under the per-user transmit power constraint $P$.

III. NETWORKS WITH NO INTRA-CELL INTERFERENCE

Here we state our main results for the case where there is no interference between the sectors of the same cell. It is worth pointing out that in this section we do not assume any form of collaboration between sector receivers other than the message passing scheme described in Section II-C. The main results of this section are given by the following achievability and converse theorems. The complete proof of these results is provided in Appendices A and C. For the sake of clarity and in order to build intuition on both the achievability coding scheme and the converse proof technique, we treat in detail the case of two-antenna terminals ($M = 2$) in Sections III-A and III-B

**Theorem 1** For a sectored cellular system $\mathcal{G}(\mathcal{V}, \mathcal{E})$ in which transmitters and receivers are equipped with $M$ antennas each, there exist a one-shot linear beamforming scheme that achieves the average (per sector) DoFs

$$d_{\mathcal{G},\pi^*} = \begin{cases} 
\frac{M}{2}, & M \text{ is even} \\
\frac{M}{2} - \frac{1}{6}, & M \text{ is odd}
\end{cases}$$

(6)

under the network interference cancellation framework with decoding order $\pi^*$. 

\[\square\]
Theorem 2 For a sectored cellular system \( G(V,E) \) in which transmitters and receivers are equipped with \( M \) antennas each and for any network interference cancellation decoding order \( \pi \), the average (per sector) DoFs \( d_{G,\pi} \) that can be achieved by any one-shot linear beamforming scheme are bounded by \( d_{G,\pi}^* + \mathcal{O}\left(1/\sqrt{|V|}\right) \), where \( d_{G,\pi}^* \) is given by Theorem 1.

The above theorems yield a tight DoFs result for large extended cellular networks, for which \( |V| \to \infty \). The term \( \mathcal{O}\left(1/\sqrt{|V|}\right) \) comes from the fact that sectors on the boundary observe less interference, and therefore can achieve higher DoFs. However, the number of sectors on the boundary is small compared to the total number or sectors \( |V| \), and therefore, their effect vanishes as the size of the network increases.

Remark 1 Notice that \( d_{G,\pi}^* \) is not exactly \( M/2 \) for odd values of \( M \). This is because we have insisted on one-shot schemes. By precoding over two time-frequency varying slots it is not difficult to show that \( M/2 \) DoFs per sector are indeed achievable also for odd \( M \).

A. Achievability

For the purpose of illustrating our main ideas, we will consider here the case where sector receivers and mobile terminal transmitters are equipped with \( M = 2 \) antennas and describe the linear beamforming scheme that is able to achieve one DoF per link for the entire network.

Consider the directed interference graph \( G_{\pi^*}(V,E_{\pi^*}) \) shown in Fig. 3 and assume that all user terminals \( v \in V \) are simultaneously transmitting their signals \( x_v \) to their corresponding receivers. Recall that each sector receiver that is able to decode its own message, is also able to pass it as side information to its neighbors, effectively eliminating interference in that direction. Hence, following the “left-to-right, top-down” decoding order \( \pi^* \) introduced in Section II-C, the sector receiver associated with the node \( u \in V \) is able to eliminate interference from all neighboring sectors \( v \prec_{\pi^*} u \) and attempt to decode its own message from the two-dimensional received signal observation \( y_u \) given by

\[
y_u = H_{uu}x_u + \sum_{v:v,u \in E_{\pi^*}} H_{uv}x_v + z_u.
\]

Our goal is to design the transmitted signals \( x_v \) such that all interference observed in \( y_u \) is aligned in one dimension for every sector receiver \( u \) in our cellular system. Let \( u_u \) and \( v_u \) denote the 2-dimensional receive and transmit beamforming vectors associated with node \( u \in V \) and
assume that every user terminal in the network has encoded its message in the corresponding codeword. Although codewords span many slots (in time), we focus here on a single slot and denote the corresponding coded symbol of user \( u \) by \( s_u \). Then, the vector transmitted by user \( u \) is given by \( x_u = v_u s_u \) and each receiver can project its observation \( y_u \) along \( u \) to obtain

\[
\hat{y}_u = u_H H u v_u s_u + \sum_{v: [v, u] \in \mathcal{E}} u_H H u v_v s_v + \hat{z}_u.
\]

We will show next that it is possible to design \( u, v \) across the entire network \( G^\pi(V, \mathcal{E}) \) such that the following interference alignment conditions are satisfied:

\[
\begin{align*}
\mathbf{u}_u^H H u u v_u & \neq 0, \quad \forall u \in V \quad \text{and} \\
\mathbf{u}_u^H H u u v_v & = 0, \quad \forall [v, u] \in \mathcal{E}^\pi.
\end{align*}
\]

Hence, each receiver in the network can decode its own desired symbol \( s_u \) from an interference-free channel observation of the form

\[
\hat{y}_u = \hat{h}_u s_u + \hat{z}_u
\]

where \( \hat{h}_u = u_H H u v_u \) and \( \hat{z}_u = u_H z_u \).

Fig. 4: Out-of-Cell Interference in the neighborhood of a blue node. Sectors are labeled here with letters to avoid confusion with the underlying decoding order (cf. Fig. 3).

In order to describe the alignment precoding scheme, we will partition the nodes in \( G^\pi(V, \mathcal{E}) \) into three sets based on their interference in-degree, defined as the number of incoming interfering links. Notice that in Fig. 3 all the square nodes observe at most three incoming interfering links, while the in-degrees of all diamond and circle nodes are at most two and one respectively. Let \( V_{\text{square}} = \{ v : \phi(v) \in \Lambda_0 \} \), \( V_{\text{circle}} = \{ v : \phi(v) \in \Lambda_0 + 1 \} \) and \( V_{\text{diamond}} = \{ v : \phi(v) \in \Lambda_0 - 1 \} \) denote the sets of square, diamond, and circle nodes respectively, as introduced in Section II-B.
First we are going to propose an interference alignment solution for a small part of the network that we will refer to as the *neighborhood* of a square node, denoted as $S(u), u \in V_{\text{square}}$, and then explain how this solution can be extended and applied in the entire network. Fig. 4 shows the interfering links and transmit-receive pairs that belong to the neighborhood $S(a)$.

In the above neighborhood, the goal is to design the 2-dimensional beamforming vectors $v_a, v_b, v_c$ and $v_d$ such that all interference occupies a single dimension in every receiver. We will hence require that $\text{span}(H_{ea}v_a) = \text{span}(H_{eb}v_b)$ for receiver $e$ and $\text{span}(H_{ab}v_b) = \text{span}(H_{ac}v_c) = \text{span}(H_{ad}v_d)$ for receiver $a$. These interference alignment conditions can be satisfied if we choose:

\begin{align*}
    v_a &:= H_{ea}^{-1}H_{eb}v_b \quad (11) \\
    v_b &:= H_{ab}^{-1}H_{ac}v_c \quad (12) \\
    v_c &:= H_{ac}^{-1}H_{ad}v_d \quad (13)
\end{align*}

where $v := u$ is a shorthand notation for $v \in \text{span}(u)$. Notice that in the above solution the beamforming vectors $v_a, v_b$ and $v_c$ depend on the chosen direction for $v_d$. This is a key observation in order to embed the above beamforming strategy in the entire network.

![Interference Alignment Scheme](image)

**Fig. 5:** Interference Alignment Scheme. The alignment conditions are depicted here with arrows connecting interfering streams that have to be aligned. The direction of the arrows show the corresponding beamforming dependencies (e.g., the arrow labeled with the number 1 requires that $v_a$ is chosen as a function of $v_b$).

All the transmitters associated with square nodes $a \in V_{\text{square}}$ can choose their beamforming vectors $v_a$ such that the first alignment condition (Eq. 11) is satisfied in every neighborhood $S(a)$. This beamforming choice is shown in Fig. 5 with an arrow labeled with the number 1, connecting the two interfering links that have to be aligned. The direction of the arrow indicates that $v_a$ has
been chosen as a function of \(v_b\). In a similar fashion, following the arrows labeled with the number 2, every circle node \(b \in \mathcal{V}_{\text{circle}}\) can beamform to satisfy the second alignment condition (Eq. [12]) by choosing \(v_b\) as a function of \(v_c\). Now, in order to ensure that the third condition (Eq. [13]) is also satisfied in every neighborhood we can choose the beamforming vectors of diamond nodes \(c \in \mathcal{V}_{\text{diamond}}\) according to the arrows labeled with the number 3, as shown in Fig. 5.

Notice that, from each neighborhood’s perspective, \(v_c\) is chosen as a function of an arbitrary vector \(v_d\) that has in turn been chosen to satisfy an alignment condition in a different neighborhood. Following this procedure, all the transmitters are able design their beamforming vectors sequentially, as functions of their neighbors’ choices, starting from the boundary of the network. It is not hard to verify that with the above beamforming strategy, every receiver in the network will observe all interference aligned in one dimension that can subsequently be zero-forced in order to obtain an observation in the form of (10). In that way, under the network interference cancellation framework with decoding order \(\pi^*\), all transmit-receive pairs in \(\mathcal{G}_{\pi^*}(\mathcal{V}, \mathcal{E}_{\pi^*})\) can successively create an one-dimensional interference-free channel for communication and hence achieve \(d_v = 1, \forall v \in \mathcal{V}\).

B. Converse

In the previous section we described a linear beamforming scheme that can be applied in \(\mathcal{G}(\mathcal{V}, \mathcal{E})\) when \(M = 2\), and achieve \(d_v = 1\), for all \(v \in \mathcal{V}\), following the “left-to-right, top-down” decoding order \(\pi^*\). Here, we are going to show that the above DoFs are almost optimal for our cellular network in the sense that for any decoding order \(\pi\), the average (per sector) DoFs \(d_{G,\pi}^*\) achievable by any linear scheme are upper bounded by \(1 + \mathcal{O}(1/\sqrt{|\mathcal{V}|})\).

Let \(\mathbf{V}_v, \mathbf{U}_v \in \mathbb{C}^{2 \times d_v}\) denote the transmit and receive beamforming matrices associated with a node \(v \in \mathcal{V}\). Any linear scheme that achieves the DoFs \(\{d_v, v \in \mathcal{V}\}\) in \(\mathcal{G}_{\pi}(\mathcal{V}, \mathcal{E}_{\pi})\) has to satisfy the interference alignment conditions:

\[
\mathbf{U}_v^H \mathbf{H}_{vu} \mathbf{V}_u = 0, \quad \forall [u,v] \in \mathcal{E}_{\pi}\]  \hspace{1cm} (14)

\[
\text{rank} (\mathbf{U}_v^H \mathbf{H}_{vu} \mathbf{V}_u) = d_v, \quad \forall v \in \mathcal{V}.
\]  \hspace{1cm} (15)

For any receiver associated with a node \(v \in \mathcal{V}\), the first condition corresponds to zero-forcing all interference from transmitters \(\{u \in \mathcal{V} : [v,u] \in \mathcal{E}_{\pi}\}\) and the second one requires that its own desired symbols can be successfully resolved.
From the above we can obtain the following necessary conditions such that any \( \{d_v : v \in V\} \) is achievable in \( G_{\pi}(V, E_{\pi}) \):

\[
d_v \in \{0, 1, 2\}, \quad \forall v \in V
\]

\[
d_v + d_u \leq 2, \quad \forall [u, v] \in E_{\pi},
\]

where (16) follows directly from (15) and (17) follows from (14) assuming that \( \text{rank}(H_{vu} V_u) = \text{rank}(V_u) = d_u, \forall [v, u] \in E_{\pi} \).

In order to obtain an upper bound on the achievable average DoFs, we shall consider the optimization problem

\[
Q_{1}(G_{\pi}) : \maximize_{\{d_v : v \in V\}} \frac{1}{|V|} \sum_{v \in V} d_v
\]

subject to: (16), (17).

In particular, we will derive an upper bound \( \hat{d}_G \) for the optimal value of \( Q_{1}(G_{\pi}) \), such that \( \hat{d}_G \geq \text{opt}(Q_{1}(G_{\pi})) \), \( \forall \pi \) and show that \( \hat{d}_G = 1 + \mathcal{O}(1/\sqrt{|V|}) \).

As a first step, we are going to rewrite the sum in the objective of \( Q_{1}(G_{\pi}) \) as a sum over connected vertex triplets \([u, v, w]\) that we are going to call the triangles \( \mathcal{T} \) of our graph.

![Fig. 6: The set of triangles \([u, v, w]\) \( \in \mathcal{T} \) for \( G(V, E) \). All the circle nodes belong to \( V_{\text{in}} \) and participate in exactly two triangles \( (n_v = 2) \). The set \( V_{\text{ex}} \) contains the colored nodes on the boundary for which \( n_v < 2 \).](image-url)
In order to formally describe the set of triangles $\mathcal{T}$ in $\mathcal{G}(\mathcal{V}, \mathcal{E})$, we consider the set of ordered Eisenstein integer triplets

$$\mathcal{P} = \{[z, z + \omega, z + \omega + 1] : z \in \mathbb{Z}(\omega) \setminus \Lambda_0\}.$$ 

Recall from Section II-B that when $z \in \mathbb{Z}(\omega) \setminus \Lambda_0$, the points $z$, $z + \omega$ and $z + \omega + 1$ form the line segments $\Delta(z) \subseteq \mathcal{D}$ and the corresponding graph vertices $\phi^{-1}(z)$, $\phi^{-1}(z + \omega)$ and $\phi^{-1}(z + \omega + 1)$ form a connected triangle in $\mathcal{G}(\mathcal{V}, \mathcal{E})$. We can hence define the set of vertex triangles as

$$\mathcal{T} = \{[u, v, w] : [\phi(u), \phi(v), \phi(w)] \in \mathcal{P}, u, v, w \in \mathcal{V}\}. \quad (18)$$

The above definition is illustrated in Fig. 6 in which shaded triangles connect the corresponding vertex triplets $[u, v, w] \in \mathcal{T}$. Notice that apart from some vertices on the external boundary of the graph, all other nodes participate in exactly two triangles in $\mathcal{T}$. This observation will be particularly useful in rewriting the sum in the objective function of $Q_1(\mathcal{G}_\pi)$ as a sum over $\mathcal{T}$ instead of $\mathcal{V}$.

Let

$$n_v \triangleq \sum_{[i,j,k] \in \mathcal{T}} \mathbb{1}\{v \in \{i,j,k\}\} \quad (19)$$

de note the number of triangles $[i, j, k] \in \mathcal{T}$ that include a given vertex $v \in \mathcal{V}$. As we have seen, $n_v$ can only take values in $\{0, 1, 2\}$ for any $v \in \mathcal{V}$. More specifically $n_v = 2$ for all internal vertices in $\mathcal{G}(\mathcal{V}, \mathcal{E})$, while $n_v < 2$ only for some external vertices that lie on the outside boundary of our graph.

We define the set of internal and external vertices as follows.

$$\mathcal{V}_{\text{in}} = \{v \in \mathcal{V} : n_v = 2\}, \text{ and}$$

$$\mathcal{V}_{\text{ex}} = \{v \in \mathcal{V} : n_v < 2\}. \quad (20)$$

In Fig. 6 we show the above distinction by coloring all graph vertices $v$ that belong to the set $\mathcal{V}_{\text{ex}} \subseteq \mathcal{V}$.

**Lemma 1 (Triangle sums)** Consider the interference graph $\mathcal{G}(\mathcal{V}, \mathcal{E})$ and let $\{ x_v : v \in \mathcal{V}) \}$ be a set of values associated with $\mathcal{V}$. The sum of $x_v$ over all vertices $v \in \mathcal{V}$ can be written as

$$\sum_{v \in \mathcal{V}} x_v = \sum_{[i,j,k] \in \mathcal{T}} \left(\frac{x_i + x_j + x_k}{2}\right) + \sum_{u \in \mathcal{V}_{\text{ex}}} \left(1 - \frac{n_u}{2}\right)x_u. \quad (22)$$
Proof: From the definition of \( n_v \) in (19), we have that
\[
\sum_{[i,j,k] \in T} (x_i + x_j + x_k) = \sum_{v \in V} n_v x_v.
\]
Splitting the sum in terms of \( V_{in} \) and \( V_{ex} \) we get
\[
\sum_{v \in V} n_v x_v = \sum_{v \in V_{in}} n_v x_v + \sum_{v \in V_{ex}} n_v x_v = 2 \sum_{v \in V} x_v + \sum_{v \in V_{in}} (n_v - 2) x_v + \sum_{u \in V_{ex}} (n_u - 2) x_u = 2 \sum_{v \in V} x_v + \sum_{v \in V_{ex}} (n_v - 2) x_v,
\]
where the last step follows from the fact that \( n_v = 2 \) for all \( v \in V_{in} \). Rearranging the terms and dividing by 2 gives the desired result.

In view of the above lemma, we can rewrite the average DoFs in the objective of \( Q_1(G_{\pi}) \) as
\[
\frac{1}{|V|} \sum_{v \in V} d_v = \frac{1}{2|V|} \sum_{[i,j,k] \in T} (d_i + d_j + d_k) + \frac{D_{ex}}{|V|},
\]
where
\[
D_{ex} = \sum_{v \in V_{ex}} \left(1 - \frac{n_v}{2}\right) d_v.
\]
Notice that from (16) and (17), the maximum sum \( d_i + d_j + d_k \) that any triangle \([i,j,k] \in T\) can achieve in our setting is 3 and hence we can bound the sum in (23) as
\[
\sum_{[i,j,k] \in T} (d_i + d_j + d_k) \leq 3|T|.
\]
Similarly, since \( d_v \leq 2 \) and \( n_v \geq 0 \) for all \( v \in V \), we have that
\[
D_{ex} \leq 2|V_{ex}|.
\]
Using the above inequalities we can upper bound the average achievable DoFs in the cellular network as
\[
\frac{1}{|V|} \sum_{v \in V} d_v \leq \frac{3|T|}{2|V|} + \frac{2|V_{ex}|}{|V|}.
\]

Lemma 2 By construction, the interference graph \( G(V,E) \) satisfies
\[
|T| \leq \frac{2}{3} |V|, \quad \text{and} \quad |V_{ex}| = O\left(\sqrt{|V|}\right).
\]
Proof: See Appendix B.

Using the result of the above lemma, we can obtain
\[
\text{opt}(Q_1(G_\pi)) \leq 1 + O\left(\frac{1}{\sqrt{|V|}}\right),
\]
and hence conclude that when $M = 2$, the average DoFs achievable in the sectored cellular system are bounded by $1 + O\left(\frac{1}{\sqrt{|V|}}\right)$ for any decoding order $\pi$.

IV. NETWORKS WITH INTRA-CELL INTERFERENCE

In this section we extend our cellular model to incorporate both out-of-cell and intra-cell interference. Namely we will assume here that a sector receiver observes interference not only from its out-of-cell neighbors but also from the other transmitters located within the same cell. These intra-cell interfering links are shown as black arrows in Fig. 1a and correspond to the dashed edges in the interference graph shown in Fig. 1b.

The interference graph, denoted here as $\hat{G}(V, \hat{E})$, is the same as the graph defined in Section II-B with the only difference that the set $\hat{E}$ now includes both out-of-cell and intra-cell interference edges. Similarly we can define the directed interference graph $\hat{G}_\pi(V, \hat{E}_\pi)$ for any network interference cancellation decoding order $\pi$.

We will see next that these additional interfering links in $\hat{E}$ do not affect the achievable degrees of freedom in our cellular system as long as we allow the sectors of each cell to jointly process their received signals\footnote{It is interesting to notice that joint sector processing at the same cell base station site is implemented in current technology.}.

Again, we state here our main achievability result and focus on the case where $M = 2$ in Section IV-A, while the full proof is postponed to Appendix D.

**Theorem 3** For a sectored cellular system $\hat{G}(V, \hat{E})$ in which transmitters and receivers are equipped with $M$ antennas each, there exists a one-shot linear beamforming scheme that achieves the average (per sector) DoFs
\[
d_{\hat{G}, \pi^*} = \begin{cases} 
\frac{M}{2}, & M \text{ is even} \\
\frac{M}{2} - \frac{1}{6}, & M \text{ is odd}
\end{cases}
\]
under the network interference cancellation framework with decoding order $\pi^*$, and with joint processing within the sectors of each cell.
A. Achievability

Consider the beamforming scheme described in Section III-A for $M = 2$ and focus on the cell $\{a, b, c\}$ shown in Fig. 7. Without loss of generality, we will describe here how to jointly process the received observations in $y_a$, $y_b$ and $y_c$ such that all intra-cell interference can be eliminated and show that under the network interference cancellation framework and the beamforming choices of Section III-A every sector receiver in the network is able to decode its own desired message.

![Fig. 7: Intra-Cell Interference Elimination. The sectors of each cell can jointly process their received signals and successively decode their desired messages.]

According to the “left-to-right, top-down” decoding order $\pi^*$, at the time when sector $a$ attempts to decode, all the interfering links from transmitters located “above and to the left” of $a$ have already been eliminated. As we can also see in Fig. 7 sector $a$ will observe intra-cell interference from sectors $b$ and $c$, and out-of-cell interference from sector $d$. Hence, the received signal available to sector $a$ is given by

$$y_a = H_{aa}v_a s_a + \sum_{u \in \{b,c,d\}} H_{au}v_u s_u + z_a.$$  \hspace{1cm} (29)

At the same time, the receivers $b$ and $c$ will be observing interference from all their neighboring sectors that have not decoded their messages yet. Notice however that with the specific beamforming choices described in Section III-A all interference that comes from sectors whose messages will be decoded after sectors $b$ and $c$ according to $\pi^*$, occupy a single dimension in each receiver and can hence be zero-forced. It is only the transmitter associated with sector $d$ that is going to cause interference after the projection. Therefore, the corresponding observations from sectors $b$ and $c$
that are available when receiver $a$ attempts to decode are given by

\[ u_b^H y_b = u_b^H H_{bb} v_b s_b + \sum_{u \in \{a,c\}} u_b^H H_{bu} v_u s_u + u_b^H z_b, \quad (30) \]

\[ u_c^H y_c = u_c^H H_{cc} v_c s_c + \sum_{u \in \{a,b,d\}} u_c^H H_{cu} v_u s_u + u_c^H z_c. \quad (31) \]

We will see next that the cell with sectors $\{a, b, c\}$ can jointly process the above observations such that all the corresponding sector receivers will be able to decode their desired messages in the order $s_a, s_b, s_c$ specified by $\pi^*$. Indeed, if we let $s = [s_a, s_b, s_c, s_d]^T$, the observations (29), (30) and (31) can be written in vector form as

\[ \tilde{y} = \tilde{H} s + \tilde{z} \quad (32) \]

where

\[ \tilde{y} = [y_a, u_b^H y_b, u_c^H y_c]^T, \]

\[ \tilde{z} = [z_a, u_b^H z_b, u_c^H z_c]^T \]

and

\[ \tilde{H} = \begin{bmatrix}
H_{aa} v_a & H_{ab} v_b & H_{ac} v_c & H_{ad} v_d \\
H_{ba} v_a & H_{bb} v_b & H_{bc} v_c & 0 \\
H_{ca} v_a & H_{cb} v_b & H_{cc} v_c & u_c^H H_{cd} v_d
\end{bmatrix}. \]

Now, assuming that the channel matrices in our cellular network are chosen independently at random from a non-degenerate continuous complex distribution (e.g., they have independent elements drawn from a complex normal distribution), we can show that $\tilde{H} \in \mathbb{C}^{4 \times 4}$ is full rank with probability one. One can check that the beamforming vectors $u_i$ and $v_j$ do not depend on the above channel realizations, and therefore the elements of $\tilde{H}$ can be seen as independent random variables for which $\mathbb{P}[\det(\tilde{H}) \neq 0] = 1$. Hence, the given cell can always decode the corresponding messages from $\tilde{y}$ in the required order, as soon as the observations (29), (30) and (31) become available to sectors $a$, $b$ and $c$. 
In order to state the decoding process more explicitly, consider \( Q = [q_1, q_2, q_3, q_4] \) to be the unitary matrix obtained by the \( QL \)-decomposition of \( \tilde{H} \) such that

\[
Q^\dagger \tilde{H} = \begin{bmatrix}
\ell_{11} & 0 & 0 & 0 \\
\ell_{21} & \ell_{22} & 0 & 0 \\
\ell_{31} & \ell_{32} & \ell_{33} & 0 \\
\ell_{41} & \ell_{42} & \ell_{43} & \ell_{44}
\end{bmatrix}.
\]

The sector receivers \( a, b \) and \( c \) can first project \( \tilde{y} \) along \( q_1, q_2 \) and \( q_3 \) in order to obtain their corresponding observations in the form

\[
y'_a = \ell_{11}s_a + z'_1 \\
y'_b = \ell_{21}s_a + \ell_{22}s_b + z'_2 \\
y'_c = \ell_{31}s_a + \ell_{32}s_b + \ell_{33}s_c + z'_3,
\]

and then successively decode their desired messages \( s_a, s_b \) and \( s_c \) according to the specified order.

In general, the above observations can be generated for every cell in the network just before their first sector receiver attempts to decode. Therefore, following the “left-to-right, top-down” decoding order \( \pi^* \), all the sectors in \( \hat{G}_{\pi^*}(V, \hat{E}_{\pi^*}) \) can decode their desired messages using the above procedure and hence the average (per sector) degrees of freedom \( d_{\hat{G}_{\pi^*}} = 1 \) are achievable.

\[\textbf{V. Topological Robustness}\]

In this section, we introduce the concept of topological robustness for interference networks. Broadly speaking, an achievable scheme is said to be robust with respect to a network topology if its performance does not depend on the existence (or strength) of interference. This is a very important property to take into account if we want to apply a communication scheme in practice. Cellular systems are in principle designed such that most interfering links are weak and hence any scheme that solely depends on the existence (or strength) of interference will fail whenever the corresponding links are missing (or weak).

Consider for example the achievable scheme described in Section \[\text{IV-A}\] and assume that for a given channel realization all interference observed at receiver \( a \) is zero. In this network instance, depicted in Fig. 8, the equivalent channel matrix in the joint receiver observation for the cell
Fig. 8: The achievable scheme of Section IV-A is not topologically robust. Sector $b$ will not be able to decode its own desired message if Sector $a$ does not observe interference from its neighbors.

\[
\{a, b, c\}, \text{ given by }
\begin{bmatrix}
H_{aa} v_a & 0_{2 \times 1} & 0_{2 \times 1} & 0_{2 \times 1} \\
0 & u_b^H H_{bb} v_b & u_b^H H_{bc} v_c & 0 \\
0 & u_c^H H_{cb} v_b & u_c^H H_{cc} v_c & u_c^H H_{cd} v_d \\
\end{bmatrix}
\]
is rank-deficient and hence the desired transmitted messages cannot be resolved from (32). Even though sector $a$ can always decode its own message, its observation cannot help sectors $b$ and $c$ eliminate the remaining interference, and therefore sector $b$ cannot decode its message.

It is not surprising that the above scheme fails in this case; the receiver has been designed to rely on a specific interference topology (cf. Fig. 7) in order obtain the required linearly-independent observations. Whenever the corresponding links are missing, the decoding process fails and therefore the scheme proposed in Section IV-A cannot be considered topologically robust.

In practice, interference will never be exactly zero as in the previous example. However, any communication scheme that critically depends on sufficiently strong interfering links (e.g., such that the corresponding messages can be decoded and interference can be canceled) will suffer from significant noise enhancement in the decoding process whenever the corresponding channel gains are below a certain threshold. In this case the corresponding receiver will not be able to decode within the operating SNR range of the network and the weaker interference links will become the bottleneck in its performance.
Under this framework, one could consider all possible channel realizations and design a family of transmission schemes, each one specifically optimized for the corresponding interference topology. Even though this is a tractable approach for small networks, it becomes more challenging as the size of the network increases. Here, we take a unified approach and propose a topologically robust transmission scheme for large cellular systems that is able to maintain the same performance for all network configurations, no matter if the interference links are strong or weak.

A. The Compound Cellular Network

In order to formally capture the concept of topological robustness in our cellular model, we will consider here a compound scenario in which any subset of the interfering links could be potentially missing from the network. More precisely, we focus on the sectored cellular system $\hat{G}(V, \hat{E})$ defined in Section IV and we assume that every directed edge $[v, u] \in \hat{E}$ is associated with a binary channel-state parameter $\alpha_{uv} \in \{0, 1\}$ that determines whether the corresponding link will exist in the network or not.

The compound channel matrices are generated in the form of $\alpha_{uv} \cdot H_{uv}, \forall [v, u] \in \hat{E}$, as a function of the channel-state configuration $A \equiv \{\alpha_{uv} \in \{0, 1\} : [v, u] \in \hat{E}\},$ and the compound cellular network is defined over all possible choices of $A \in \{0, 1\}^{2|\hat{E}|}$. We assume that the channel-state configuration $A$ is known to all receivers but is a priori unavailable to the transmitters in the above compound network, in the sense that the interference alignment precoding scheme (although a function of the channel matrices $H_{uv}$ and of the interference graph $\hat{G}(V, \hat{E})$) must be designed irrespectively of $A$.

A topologically robust transmission scheme is required to maintain the same performance for all channel-state parameters $A \in \{0, 1\}^{2|\hat{E}|}$. Let $\hat{G}(V, \hat{E}|A)$ be the interference graph generated in the above compound network when the channel-state is $A$ and let $d_{\hat{G}}(A)$ denote the average (per sector) degrees of freedom achievable in $\hat{G}(V, \hat{E}|A)$.

\footnote{It is important to note that in the original set-up, the channel state information is available at the transmitters, and therefore obviously the channel is not compound. However, this rather artificial compound model allows us to design a \textit{unified} achievable scheme, which works, independent of the strength of interference links.}
**Definition 5** A communication scheme designed for a sectored cellular system \( \hat{G}(\mathcal{V}, \hat{\mathcal{E}}) \) is said to be topologically robust with robustness level \( d > 0 \), if it can achieve \( d_{\hat{G}}(\mathcal{A}) \geq d \), for all channel-state configurations \( \mathcal{A} \in \{0, 1\}^{2|\hat{\mathcal{E}|}. \)

As we have seen before, the achievable scheme described in Section [IV-A][4] is not topologically robust according to the above definition: even though it can achieve \( d_{\hat{G}}(\mathcal{A}) = 1 \), when \( \alpha_{uv} = 1, \forall (u,v) \in \hat{\mathcal{E}} \), there exists a configuration \( \mathcal{A}' \), shown in Fig. [8][5] in which the decoding process fails.

Under this framework, we are interested in the design of communication schemes that maximize the compound degrees of freedom,

\[
d_C \triangleq \min_{\mathcal{A} \in \{0,1\}^{2|\hat{\mathcal{E}|}} d_{\hat{G}}(\mathcal{A}).
\]

(37)

Notice that a topologically robust scheme with robustness level \( d \) achieves (by definition) the compound DoFs \( d_C = d \). The following theorems show the existence of topologically robust schemes that achieve the optimum compound DoFs performance, which coincides with the optimum DoFs performance in the non-compound setting with intra-cell interference given in Section [IV-A][4].

**Theorem 4** For a compound sectored cellular system \( \{ \hat{G}(\mathcal{V}, \hat{\mathcal{E}}|\mathcal{A} : \mathcal{A} \in \{0,1\}^{2|\hat{\mathcal{E}|} \} \}, \) in which transmitters and receivers are equipped with \( M \) antennas each, there exists a one-shot linear beamforming scheme that achieves the average (per sector) compound DoFs

\[
d^*_C = \begin{cases} 
\frac{M}{2}, & \text{if } M \text{ is even} \\
\frac{M}{2} - \frac{1}{6}, & \text{if } M \text{ is odd}
\end{cases}
\]

(38)

under the network interference cancellation framework, assuming local receiver cooperation within each cell.

**Theorem 5** The compound DoFs \( d_C \) of a sectored cellular system \( \{ \hat{G}(\mathcal{V}, \hat{\mathcal{E}}|\mathcal{A} : \mathcal{A} \in \{0,1\}^{2|\hat{\mathcal{E}|} \} \} \) achievable by any one-shot linear beamforming scheme under the network interference cancellation framework are bounded by \( d^*_C + O(1/\sqrt{|\mathcal{V}|}) \), where \( d^*_C \) is given by Theorem 4.

As before, we discuss in detail the case \( M = 2 \) and sketch the proof of Theorem 4 in the general case in Appendix E. Theorem 5 is proved in Appendix F.
B. Topologically Robust Achievability

In this section, we focus on the case where $M = 2$ and describe a topologically robust transmission scheme for $\hat{G}(V, \hat{E})$ that is able to achieve $d_C = 1$. We will consider a scheme very similar to the one described in Section IV-A. We will use the same beamforming strategy, but consider a new decoding order that is able to guarantee topological robustness.

In the terminology to follow, we distinguish between primary and secondary sectors in our network according to their relative position within each cell. We say that a sector $v \in V$ is primary if $v \in V_{\text{circle}}$ (i.e., it is located in the upper-left corner of a cell) and secondary otherwise.

We consider here a new decoding order under the network interference cancellation framework in which cells decode their messages in diagonal groups, starting from the upper-left corner of the network. Within each group, the cells first decode their primary messages (i.e., the ones associated with primary sectors) following a top-down decoding order and then proceed to their secondary messages which are decoded in the opposite direction. This process leads to the “curly-S” decoding order shown in Fig. 9 and will be denoted here as $\pi_s$.

An important property of the above decoding order is that it maintains, under network interference cancellation, the same out-of-cell interfering link directions as the “left-to-right, top-down”
decoding order $\pi^*$. We have that
\[
E_{\pi_s} \triangleq \{ [u, v] : (u, v) \in E \text{ and } v \prec_{\pi_s} u \} = E_{\pi^*}
\]
and hence the beamforming scheme designed for $E_{\pi^*}$ (Section III-A) can be directly applied in this case and satisfy the out-of-cell alignment conditions
\[
u_i^H H_{uv} v_j = 0, \quad \forall [v, u] \in E_{\pi_s}.
\] (39)

Recall the example shown in Fig. 8 and assume that receiver $a$ has already decoded its own message. With the previous decoding order, $\pi^*$, the receivers $b$ and $c$ were unable to jointly decode their messages due to the existing interference from sector $d$. With the new decoding order however, this is no longer an issue. According to $\pi_s$, the receiver in sector $d$ will be decoded before sectors $b$ and $c$, and hence its message will be available to the corresponding receivers for interference cancellation.

![Fig. 10: Robust decoding for sectors b and c.](image)

The network instance described above is depicted in Fig. 10. Under the network interference cancellation framework with decoding order $\pi_s$, the receiver observations at the time when sectors $b$ and $c$ attempt to decode are given by
\[
y_b = H_{bb} v_b s_b + H_{bc} v_c s_c + \sum_{v : [v, b] \in E_{\pi_s}} \Pi_{bb} v_s s_v + z_b,
\]
\[ y_c = H_{cc}v_c s_c + H_{cb}v_b s_b + \sum_{v'[v,c] \in \mathcal{E}_a} H_{cv}v_v s_v + z_c, \]

where \( H_{uv} = \alpha_{uv} \cdot \mathbf{H}_{uv} \) are the compound channel matrices with state parameters \( \alpha_{uv} \in \{0, 1\} \).

Notice that the secondary sectors \( b \) and \( c \), no longer need the primary observation from sector \( a \) in order to decode their messages. From (39) we have that

\[
\mathbf{u}_b^H \sum_{v'[v,b] \in \mathcal{E}_a} H_{bv}v_v s_v = 0 \quad \text{and} \quad \mathbf{u}_c^H \sum_{v'[v,c] \in \mathcal{E}_a} H_{cv}v_v s_v = 0,
\]

for all compound channel states and hence the corresponding observations can be written in vector form as

\[
\begin{bmatrix}
\mathbf{u}_b^H v_b \\
\mathbf{u}_c^H v_c
\end{bmatrix} = \begin{bmatrix}
\mathbf{u}_b^H \mathbf{H}_{bb} v_b & \mathbf{u}_b^H \mathbf{H}_{bc} v_c \\
\mathbf{u}_c^H \mathbf{H}_{cb} v_b & \mathbf{u}_c^H \mathbf{H}_{cc} v_c
\end{bmatrix}
\begin{bmatrix}
s_b \\
s_c
\end{bmatrix} + \tilde{z}.
\]

The equivalent channel matrix \( \tilde{\mathbf{H}}(\alpha_{bc}, \alpha_{cb}) \in \mathbb{C}^{2 \times 2} \) given in the above observation depends on the compound channel-state parameters \( \alpha_{bc}, \alpha_{cb} \in \{0, 1\} \), which determine whether sectors \( b \) and \( c \) interfere with each other or not. We can see that the resulting channel matrices,

\[
\tilde{\mathbf{H}}(0, 0) = \begin{bmatrix}
\mathbf{u}_b^H \mathbf{H}_{bb} v_b & 0 \\
0 & \mathbf{u}_c^H \mathbf{H}_{cc} v_c
\end{bmatrix}, \quad \tilde{\mathbf{H}}(1, 0) = \begin{bmatrix}
\mathbf{u}_b^H \mathbf{H}_{bb} v_b & \mathbf{u}_b^H \mathbf{H}_{bc} v_c \\
0 & \mathbf{u}_c^H \mathbf{H}_{cc} v_c
\end{bmatrix},
\]

\[
\tilde{\mathbf{H}}(0, 1) = \begin{bmatrix}
\mathbf{u}_b^H \mathbf{H}_{bb} v_b & 0 \\
\mathbf{u}_c^H \mathbf{H}_{cb} v_b & \mathbf{u}_c^H \mathbf{H}_{cc} v_c
\end{bmatrix}, \quad \tilde{\mathbf{H}}(1, 1) = \begin{bmatrix}
\mathbf{u}_b^H \mathbf{H}_{bb} v_b & \mathbf{u}_b^H \mathbf{H}_{bc} v_c \\
\mathbf{u}_c^H \mathbf{H}_{cb} v_b & \mathbf{u}_c^H \mathbf{H}_{cc} v_c
\end{bmatrix},
\]

are all full-rank, and hence the receivers in sectors \( b \) and \( c \) are always able to decode their messages, irrespective of the compound channel-state parameters.

Similarly, we can show that all transmitted messages in \( \mathcal{G}(\mathcal{V}, \mathcal{E} | \mathcal{A}) \) associated with secondary sectors, can be successfully decoded according to \( \pi_s \), for all compound channel-state configurations \( \mathcal{A} \in \{0, 1\}^{2|\mathcal{E}|} \). It remains to argue that primary sectors are also able to decode their messages in the above compound network and hence show that the average (per sector) degrees of freedom \( d^*_c = 1 \) are achievable.

Consider the cell \( \{a, b, c\} \) shown in Fig. 11 just before its primary sector receiver \( a \) attempts to decode. According to \( \pi_s \), the available receiver observations in this cell are given by
\[ y_a = H_{aa}v_a s_a + \sum_{v \in \{b,c,d\}} \overline{H}_{av} v_v s_v + z_a, \]
\[ u_b^H y_b = u_b^H H_{bb} v_b s_b + \sum_{v \in \{a,c\}} u_b^H \overline{H}_{bv} v_v s_v + u_b^H z_b, \]
\[ u_c^H y_c = u_c^H H_{cc} v_c s_c + \sum_{v \in \{a,b,d\}} u_c^H \overline{H}_{cv} v_v s_v + u_c^H z_c, \]

where all interference coming from sectors \( v \prec a \) has already been eliminated. The above observations can be written in vector form (cf. Eq. 32) as,
\[ \tilde{y} = \tilde{H}(\alpha) \tilde{s} + \tilde{z}, \]

where \( \tilde{H}(\alpha) \) depends on the channel-state parameters \( \alpha \coloneqq [\alpha_{ab}, \alpha_{ac}, \alpha_{ad}, \alpha_{ba}, \alpha_{bc}, \alpha_{ca}, \alpha_{cb}, \alpha_{cd}] \in \{0,1\}^8 \) and is given by
\[
\tilde{H}(\alpha) = \begin{bmatrix}
H_{aa}v_a & H_{ab}v_b & H_{ac}v_c & H_{ad}v_d \\
u_b^H \overline{H}_{ba} v_a & u_b^H H_{bb} v_b & u_b^H \overline{H}_{bc} v_c & 0 \\
u_c^H \overline{H}_{ca} v_a & u_c^H \overline{H}_{cb} v_b & u_c^H H_{cc} v_c & u_c^H \overline{H}_{cd} v_d 
\end{bmatrix}.
\]

Notice that \( \tilde{H}(\alpha) \) has the same structure as the matrix \( \tilde{H} \) we considered in Section III-A and as we have already seen in the example of Fig. 8, there exist channel-state configurations (e.g, \( \alpha = [0,0,0,0,1,0,1,1] \)), for which \( \tilde{H}(\alpha) \) becomes rank-deficient. However, this is not necessarily
problem here, since we are only interested in decoding the primary sector’s message $s_a$. In this case, we just have to guarantee that the following condition,

$$[1, 0, 0, 0] \in \text{rowspan}(\tilde{H}(\tau)),$$

holds for every channel-state configuration $\tau$. Of course, when $\tau$ is the all-ones vector, the matrix $\tilde{H}(\tau) \in \mathbb{C}^{4 \times 4}$ is full-rank and the above condition is automatically satisfied.

In order to show that the primary sector’s message can be always be decoded and that (42) holds for all $\tau \in \{0, 1\}^8$, we will consider here the following cases:

1) $\alpha_{cd} = 0$, for all $[\alpha_{ab}, \alpha_{ac}, \alpha_{ad}, \alpha_{ba}, \alpha_{bc}, \alpha_{ca}, \alpha_{cb}] \in \{0, 1\}^7$.

2) $\alpha_{ad} = 1$, for all $[\alpha_{ab}, \alpha_{ac}, \alpha_{ad}, \alpha_{ba}, \alpha_{bc}, \alpha_{ca}, \alpha_{cb}, \alpha_{cd}] \in \{0, 1\}^7$.

3) $[\alpha_{cd}, \alpha_{ad}] = [1, 0]$, for all $[\alpha_{ab}, \alpha_{ac}, \alpha_{ad}, \alpha_{ba}, \alpha_{bc}, \alpha_{ca}, \alpha_{cb}, \alpha_{cd}]$ with $\alpha_{ab} \cdot \alpha_{ac} = 0$.

4) $[\alpha_{cd}, \alpha_{ad}] = [1, 0]$, for all $[\alpha_{ab}, \alpha_{ac}, \alpha_{ad}, \alpha_{ba}, \alpha_{bc}, \alpha_{ca}, \alpha_{cb}, \alpha_{cd}]$ with $\alpha_{ab} \cdot \alpha_{ac} = 1$.

Notice that these four cases (illustrated in Fig. 13) cover all possible compound channel-state configurations for the interfering links between the sectors $a, b, c,$ and $d$. Before proceeding to examine these cases separately, we give a lemma that will be repeatedly used.

---

**Fig. 12:** Compound channel-state configurations for sectors $a, b, c$ and $d$. Case 1 captures all parameter configurations $\tau$, in which there is no interference between sectors $c$ and $d$, and Case 2 corresponds to configurations with $\alpha_{ad} = 1$. In Cases 3 and 4, we assume that $[\alpha_{cd}, \alpha_{ad}] = [1, 0]$ and distinguish between configurations in which sector $a$ observes at most one, or two interfering signals.
Lemma 3 Let $\mathbf{H}$ be an $n \times n$ matrix whose elements are chosen independently at random from a continuous probability distribution. For any binary matrix $\mathbf{A} \in \{0, 1\}^{n \times n}$ with diagonal elements $a_{ii} = 1$, $i = 1, ..., n$, the rank of the Hadamard (pointwise) product $(\mathbf{A} \circ \mathbf{H})$ is equal to $n$ with probability one.

Proof: Let $\mathbf{G} = (\mathbf{A} \circ \mathbf{H})$ and define the multivariate polynomial $Q(h_{1,1}, h_{1,2}, ..., h_{n,n})$ as being equal to $\det(\mathbf{G})$. Using the Leibnitz formula for the determinant we have that

$$Q(h_{1,1}, h_{1,2}, ..., h_{n,n}) = \sum_{\sigma \in S_n} \text{sgn}(\sigma) \prod_{i=1}^{n} G_{i,\sigma(i)}$$

(43)

$$= \sum_{\sigma \in S_n} \text{sgn}(\sigma) \prod_{i=1}^{n} a_{i,\sigma(i)} \prod_{i=1}^{n} h_{i,\sigma(i)}$$

(44)

$$= \prod_{i=1}^{n} h_{i,i} + \sum_{\sigma \in S_n \setminus \{\sigma^*\}} \text{sgn}(\sigma) \prod_{i=1}^{n} a_{i,\sigma(i)} \prod_{i=1}^{n} h_{i,\sigma(i)}$$

(45)

and hence $Q(h_{1,1}, h_{1,2}, ..., h_{n,n}) \neq 0$, for all $\mathbf{A}$ with $a_{i,i} = 1$. Further, assuming that $h_{i,j}$ are chosen independently at random from a continuous distribution we have that

$$\mathbb{P}[Q(h_{1,1}, h_{1,2}, ..., h_{n,n}) \neq 0] = 1,$$

and therefore the matrix $\mathbf{G} = (\mathbf{A} \circ \mathbf{H})$ is full-rank with probability one.

Case 1: When $\alpha_{cd} = 0$, the receiver $a$ can first zero-force the interference from sector $d$ and obtain

$$\mathbf{u}_a^H \mathbf{y}_a = \mathbf{u}_a^H \mathbf{H}_{aa} \mathbf{v}_a s_a + \sum_{v \in \{b,c\}} \mathbf{u}_a^H \mathbf{H}_{ab} \mathbf{v}_b s_v + \mathbf{u}_a^H \mathbf{z}_a.$$  

Then it can use the projected observations from sectors $b$ and $c$, which are given in this case by

$$\mathbf{u}_b^H \mathbf{y}_b = \mathbf{u}_b^H \mathbf{H}_{bb} \mathbf{v}_b s_b + \sum_{v \in \{a\}} \mathbf{u}_b^H \mathbf{H}_{bc} \mathbf{v}_c s_v + \mathbf{u}_b^H \mathbf{z}_b,$$

$$\mathbf{u}_c^H \mathbf{y}_c = \mathbf{u}_c^H \mathbf{H}_{cc} \mathbf{v}_c s_c + \sum_{v \in \{a,b\}} \mathbf{u}_c^H \mathbf{H}_{ca} \mathbf{v}_a s_v + \mathbf{u}_c^H \mathbf{z}_c,$$

in order to create a three-dimensional vector observation of the form

$$\begin{bmatrix} \mathbf{u}_b^H \mathbf{y}_b \\ \mathbf{u}_b^H \mathbf{y}_b \\ \mathbf{u}_c^H \mathbf{y}_c \end{bmatrix} = \begin{bmatrix} \mathbf{u}_a^H \mathbf{H}_{aa} \mathbf{v}_a & \mathbf{u}_a^H \mathbf{H}_{ab} \mathbf{v}_b & \mathbf{u}_a^H \mathbf{H}_{ac} \mathbf{v}_c \\ \mathbf{u}_b^H \mathbf{H}_{ba} \mathbf{v}_a & \mathbf{u}_b^H \mathbf{H}_{bb} \mathbf{v}_b & \mathbf{u}_b^H \mathbf{H}_{bc} \mathbf{v}_c \\ \mathbf{u}_c^H \mathbf{H}_{ca} \mathbf{v}_a & \mathbf{u}_c^H \mathbf{H}_{cb} \mathbf{v}_b & \mathbf{u}_c^H \mathbf{H}_{cc} \mathbf{v}_c \end{bmatrix} \begin{bmatrix} s_a \\ s_b \\ s_c \end{bmatrix} + \mathbf{z},$$

$$\triangleq \mathbf{H}(\alpha_{ab}, \alpha_{ac}, \alpha_{ba}, \alpha_{bc}, \alpha_{ca}, \alpha_{cc})$$
Notice that \( \tilde{H}(\alpha_{ab}, \alpha_{ac}, \alpha_{ba}, \alpha_{bc}, \alpha_{ca}, \alpha_{cb}) \) can be written as the pointwise product 
\[
(A \circ \tilde{H}) = \begin{bmatrix}
1 & \alpha_{ab} & \alpha_{ac} \\
\alpha_{ba} & 1 & \alpha_{bc} \\
\alpha_{ca} & \alpha_{cb} & 1
\end{bmatrix} \circ \begin{bmatrix}
u_a^H H_{aa} v_a & u_a^H H_{ab} v_b & u_a^H H_{ac} v_c \\
u_b^H H_{ba} v_a & u_b^H H_{bb} v_b & u_b^H H_{bc} v_c \\
u_c^H H_{ca} v_a & u_c^H H_{cb} v_b & u_c^H H_{cc} v_c
\end{bmatrix},
\]
where \( H \) and \( A \) satisfy the conditions of Lemma 3, and hence it is full-rank for all channel-state parameters \( [\alpha_{ab}, \alpha_{ac}, \alpha_{ba}, \alpha_{bc}, \alpha_{ca}, \alpha_{cb}] \). We can therefore argue that receiver \( a \) is always able in this case to decode its desired message from the above joint observation.

**Case 2:** When \( \alpha_{ad} = 1 \), the equivalent channel matrix \( \tilde{H}(\bar{\alpha}) \) is going to be full-rank for every choice of \( [\alpha_{ab}, \alpha_{ac}, \alpha_{ba}, \alpha_{bc}, \alpha_{ca}, \alpha_{cb}, \alpha_{cd}] \in \{0, 1\}^7 \) and hence \( s_a \) can be decoded directly from (41). In order to show this we will first write the matrix \( \tilde{H}(\bar{\alpha}) \) in its product form \( (A \circ \tilde{H}) \), where
\[
A = \begin{bmatrix}
1 & \alpha_{ab} & \alpha_{ac} & 1 \\
1 & \alpha_{ab} & \alpha_{ac} & 1 \\
\alpha_{ba} & 1 & \alpha_{bc} & 0 \\
\alpha_{ca} & \alpha_{cb} & 1 & \alpha_{cd}
\end{bmatrix},
\]
and consider a permutation matrix \( P_\sigma \) that reorders the rows of \( A \) according to \( \sigma(1) = 4, \sigma(2) = 1, \sigma(3) = 2, \sigma(4) = 3 \). We have that
\[
\text{rank}(A \circ \tilde{H}) = \text{rank}(P_\sigma (A \circ \tilde{H}))
\]
\[
= \text{rank}(P_\sigma A \circ P_\sigma \tilde{H})
\]
and since \( [P_\sigma A]_{ii} = 1, \forall i \), we can use Lemma 3 to show that the above matrix is indeed full-rank for any choice of channel-state parameters \( [\alpha_{ab}, \alpha_{ac}, \alpha_{ba}, \alpha_{bc}, \alpha_{ca}, \alpha_{cb}, \alpha_{cd}] \in \{0, 1\}^7 \).

**Case 3:** When \( \alpha_{ad} = 0 \) and \( [\alpha_{ab}, \alpha_{ac}] = [0, 0] \), receiver \( a \) observes no interference and can directly decode its own message. Now, when \( [\alpha_{ab}, \alpha_{ac}] \in \{[0, 1], [1, 0]\} \), the receiver \( a \) has only one interfering link which can always be zero-forced from its two-dimensional observation \( y_a \). Without loss of generality, assume that \( \alpha_{ac} = 1 \) and choose \( u_a \in \mathbb{C}^2 \) such that \( u_a^H H_{ac} v_c = 0 \). Then,
\[
u_a^H y_a = u_a^H H_{aa} v_a s_a + u_a^H z_a,
\]
and since \( u_a^H H_{aa} v_a \neq 0 \) with probability one, the message \( s_a \) can be decoded in this case as well.
Case 4: In this case, the equivalent channel matrix $\tilde{H}(\tau)$ can be written as $(A \circ \tilde{H})$, with

$$A = \begin{bmatrix}
1 & 1 & 1 & 0 \\
1 & 1 & 1 & 0 \\
\alpha_{ba} & 1 & \alpha_{bc} & 0 \\
\alpha_{ca} & \alpha_{cb} & 1 & 1
\end{bmatrix},$$

and, as in Case 2, we can use Lemma 3 to show that it is full-rank, by swapping the second and third rows of $A$. Hence, $s_a$ can be decoded from (41) for all $[\alpha_{ba}, \alpha_{bc}, \alpha_{ca}, \alpha_{cb}] \in \{0, 1\}^4$.

VI. Conclusions

In this work we have shown that the promised DoFs gain of interference alignment can be achieved in cellular networks with straightforward one-shot alignment precoding, without requiring symbol extensions over very large number of time-frequency dimensions, or infinite resolution of “rationally independent” signal levels. In particular, we have shown schemes that achieve $\frac{1}{2}$ DoFs per antenna in the uplink of a cellular system with three sectors per cell and one active user per sector, where both the user transmitter and the sector receiver have $M$ antennas. Our result applies immediately to the case of $M$ even, while it requires extension over two time/frequency varying slots for $M$ odd. Furthermore, for the case where there is (possibly) interference between sectors of the same cell, we have considered a scheme that exploits joint processing (in fact, successive decoding is sufficient) of the three sectors in the same cell and achieves the same optimal DoFs. Finally, for this scenario we have defined the notion of “topological robustness” of a scheme, as the ability to achieve fixed average DoFs irrespectively of the presence/absence of the interfering links. We have shown that topologically robust one-shot linear schemes exist, which achieve the same optimal DoFs of the original network where all links are present.

The key technology enabler to achieve these results is to allow base stations to share their own locally decoded messages with their neighboring base station receivers. This framework is very different from joint processing of all the cell sites as advocated in the so-called “Wyner model”, which requires all received signals to be jointly processed at a single central processor. As a matter of fact, both joint processing of same-cell sectors and message passing of already (individually) decoded messages to neighboring cells can be implemented in current cellular technology. Therefore, we believe that the results of this paper are not only a step forward in the understanding of the true potential of interference alignment in wireless networks, but also
provide practical and valuable system design guidelines towards a much more efficient interference management in large wireless networks.

APPENDIX A
PROOF OF THEOREM 1

Consider the directed interference graph $G_{\pi^*}(V, E_{\pi^*})$ and let $V_v, U_v \in \mathbb{C}^{M \times d_v}$ denote the transmit and receive beamforming matrices associated with each node $v \in V$.

We will show here that it is possible to choose $d_v, V_v$ and $U_v$ for every $v \in V$ such that the following conditions are satisfied.

\[ U_v^H H_{uv} V_v = 0, \quad \forall [v, u] \in E_{\pi^*} \tag{46} \]

\[ \text{rank}(U_v^H H_{uv} V_v) = d_v, \quad \forall v \in V, \quad \text{and} \tag{47} \]

\[ \frac{1}{|V|} \sum_{v \in V} d_v \geq \begin{cases} \frac{M}{2}, & M \text{ is even} \\ \frac{M}{2} - \frac{1}{6}, & M \text{ is odd}. \end{cases} \tag{48} \]

Recall the definitions of $f(\cdot)$ and $\phi(\cdot)$ that are given in Section II-B and consider the sets

\[ V_k = \{v \in V : f(\phi(v)) = k\}, \quad k = 0, 1, 2. \tag{49} \]

Notice that $V_k$ satisfy

\[ V = \bigcup_{k=0}^{2} V_k \quad \text{and} \quad V_i \cap V_j = \emptyset, \quad i \neq j \]

and hence form a partition of $V$.

An important observation is that, according to $E_{\pi^*}$, every receiver associated with a node $u \in V_1$ has at most one interfering transmitter. More specifically, for every $u \in V_1$ there exist $[v, u] \in E_{\pi^*}$ if and only if there exist $v \in V_2$ with $\phi(v) = \phi(u) - 1 - \omega$.

Similarly, the receivers associated with the nodes $u \in V_2$ have at most two interfering transmitters and hence we can argue that for every $u \in V_2$ there exist $[v, u] \in E_{\pi^*}$ if and only if there exist $v_0 \in V_0$ with $\phi(v_0) = \phi(u) + 1$ or $v_1 \in V_1$ with $\phi(v_1) = \phi(u) - \omega$.

Finally, every receiver associated with a node $u \in V_0$ observes at most three interferers and we have that for every $u \in V_0$ there exist $[v, u] \in E_{\pi^*}$ if and only if there exist $v_1 \in V_1$ with $\phi(v_1) = \phi(u) + 1$ or $v_2 \in V_2$ with $\phi(v_2) = \phi(u) - \omega$ or $v'_1 \in V_1$ with $\phi(v'_1) = \phi(u) - 1 - \omega$. 
For any full rank matrix \( A \in \mathbb{C}^{m \times n} \) with \( m > n \), we let \( P_A^\perp \in \mathbb{C}^{m \times (m-n)} \) be a basis for the nullspace of \( A^H \), such that \( (P_A^\perp)^H A = 0 \).

A. \( M \) is even

Let \( d_v = \frac{M}{2} \), for all \( v \in \mathcal{V} \) and consider the following beamforming choices.

(a) For all \( v_0 \in \mathcal{V}_0 \) such that there exist \( v_1 \in \mathcal{V}_1 \) and \( u \in \mathcal{V}_2 \) with \( \phi(v_1) = \phi(v_0) - 1 - \omega \) and \( \phi(u) = \phi(v_0) - 1 \), set

\[
V_{v_0} = H_{uv_0}^{-1} H_{uv_1} V_{v_1} / ||H_{uv_0}^{-1} H_{uv_1} V_{v_1}||.
\]

Otherwise choose \( V_{v_0} \in \mathbb{C}^{M \times d_v} \) at random.

(b) For all \( v_1 \in \mathcal{V}_1 \) such that there exists \( v_2 \in \mathcal{V}_2 \) and \( u \in \mathcal{V}_0 \) with \( \phi(v_2) = \phi(v_1) + 1 \) and \( \phi(u) = \phi(v_1) - 1 + \omega \), set

\[
V_{v_1} = H_{uv_1}^{-1} H_{uv_2} V_{v_2} / ||H_{uv_1}^{-1} H_{uv_2} V_{v_2}||.
\]

Otherwise choose \( V_{v_1} \in \mathbb{C}^{M \times d_v} \) at random.

(c) For all \( v_2 \in \mathcal{V}_2 \) such that there exists \( v_1 \in \mathcal{V}_1 \) and \( u \in \mathcal{V}_0 \) with \( \phi(v_1) = \phi(v_2) + 1 + \omega \) and \( \phi(u) = \phi(v_2) + \omega \), set

\[
V_{v_2} = H_{uv_2}^{-1} H_{uv_1} V_{v_1} / ||H_{uv_2}^{-1} H_{uv_1} V_{v_1}||.
\]

Otherwise choose \( V_{v_2} \in \mathbb{C}^{M \times d_v} \) at random.

(d) For all \( u \in \mathcal{V} \) such that there exists an edge \([v, u] \in \mathcal{E}_{\pi^*}\) for some \( v \in \mathcal{V} \), set

\[
U_u = P_{H_u}^\perp V_u.
\]

Otherwise choose \( U_u \in \mathbb{C}^{M \times d_v} \) at random.

Notice that the conditions (47) and (48) are automatically satisfied (with probability one) since \( d_v = \frac{M}{2}, \forall v \in \mathcal{V} \) and \( H_{uv} \) are chosen at random from a continuous distribution. We are going to show next that the conditions (46) are also satisfied for all \([v, u] \in \mathcal{E}_{\pi^*}\). Consider the sets:

\[
\mathcal{E}^{(k)}_{\pi^*} = \{ [v, u] \in \mathcal{E}_{\pi^*} : u \in V_k \}.
\]

As we have seen, every receiver associated with \( u \in \mathcal{V}_1 \) observers at most one interfering transmitter and hence \( U_u^H H_{uv} \cdot V_{v} = (P_{H_u}^\perp V_u)^H H_{uv} \cdot V_{v} = 0 \) for all \([v, u] \in \mathcal{E}^{(1)}_{\pi^*}\). For every receiver \( u \in \mathcal{V}_2 \) there exist at most two interfering transmitters given by \( v_0 \in \mathcal{V}_0, v_1 \in \mathcal{V}_1 \) with \( \phi(v_0) = \phi(u) + 1 \) and
Fig. 13: The beamforming choices (a), (b) and (c). In this example, all the nodes with dashed outline have chosen their beamforming vectors at random.

\[ \phi(v_1) = \phi(u) - \omega. \] Notice that in this case \( \phi(v_1) = \phi(v_0) - 1 - \omega \) and according to (a), \( H_{uv_0} V_{v_0} = H_{uv_1} V_{v_1} / \| H_{uv_1} V_{v_1} \| \in \text{span}(H_{uv_1} V_{v_1}) \). Hence we can also argue that \( U_u^H H_{uv} V_v = 0 \) for all \([v, u] \in \mathcal{E}_{\pi}^{(2)}\). Now consider the set \( \mathcal{E}_{\pi}^{(2)} \). In a similar fashion, we can see that according to the beamforming choices (b) and (c), all interference observed by receivers \( u \in V_0 \) aligns in \( M/2 \) dimensions. That is for every \( u \in V_0 \) that observes interference from the transmitters \( v_1 \in V_1, v_2 \in V_2 \) and \( v'_1 \in V_1 \) with \( \phi(v_1) = \phi(u) + 1 \), \( \phi(v_2) = \phi(u) - \omega \) and \( \phi(v'_1) = \phi(u) - 1 - \omega \) we have that \( \text{span}(H_{uv_1} V_{v_1}) = \text{span}(H_{uv_1} V_{v'_1}) = \text{span}(H_{uv_1} V_{v_2}) \) and hence \( U_u^H H_{uv} V_v = 0 \) for all \([v, u] \in \mathcal{E}_{\pi}^{(3)}\) as well. Since by definition \( \mathcal{E}_{\pi}^{(1)} \cup \mathcal{E}_{\pi}^{(2)} \cup \mathcal{E}_{\pi}^{(3)} = \mathcal{E}_{\pi} \) we conclude that the conditions (46) are satisfied for all \([v, u] \in \mathcal{E}_{\pi}\).

B. \( M \) is odd

Let \( \tilde{d}_v = \frac{M-1}{2}, \forall v \in V \) and consider the beamforming matrices \( \tilde{U}_v \in \mathbb{C}^{M \times \frac{M+1}{2}} \) and \( \tilde{V}_v \in \mathbb{C}^{M \times \frac{M-1}{2}} \) given by (a), (b), (c) and (d). Following the same arguments as before we can see that if we use the above beamforming subspaces for transmission, every receiver \( u \in V \) will observe
interference aligned in $\frac{M-1}{2}$ dimensions and hence we could directly achieve $\frac{1}{|V|} \sum_{v \in V} \tilde{d}_v = \frac{M-1}{2}$.

Notice however that in this case, any receiver that zero-forces $\frac{M-1}{2}$ out of $M$ dimensions can in principle support one extra dimension for transmission since $M - \frac{M-1}{2} = \tilde{d}_v + 1$. Furthermore, any receiver that uses only $\tilde{d}_v = \frac{M-1}{2}$ dimensions for desired symbols can zero-force the remaining $\frac{M+1}{2}$ dimensions and can hence tolerate one additional interfering stream from its neighbors.

Let $V_s \subseteq V$ be a set of nodes such that the following two conditions are satisfied:

\begin{align}
(u, v) \notin E, \forall u, v \in V_s \quad (50) \\
|\{ v \in V_s : [v, u] \in E_{\pi^*} \}| \leq 1, \forall u \notin V_s. \quad (51)
\end{align}

The first condition requires that $V_s$ is an independent set in $G(V, E)$ and the second one states that for every $u \notin V_s$ there is at most one $v \in V_s$ such that $[v, u] \in E_{\pi^*}$. Consider the following beamforming choices given in terms of $\tilde{V}_v$ and $\tilde{V}_v$:

- For all $v \in V_s$ set $V_v = [\tilde{V}_v, v][[\tilde{V}_v, v]]$, for some $v_v \notin \text{span}(\tilde{V}_v)$ and let $U_v^H = \tilde{U}_v^H$.
- For all $u \notin V_s$ set $V_u = \tilde{V}_u$. If there exists $v \in V_s$ such that $[v, u] \in E_{\pi^*}$ set and $U_u^H = P_{\tilde{U}_u^H v_v} \tilde{U}_u^H$. Otherwise set $U_u^H = \tilde{U}_u^H$.

We have that $d_v = \tilde{d}_v + 1$ for all $v \in V_s$ and $d_v = \tilde{d}_v$ for all $v \notin V_s$. We are going to show next that with the above beamforming choices the interference alignment conditions (46) and (47) are satisfied and hence the average (per sector) degrees of freedom

$$
\frac{1}{|V|} \sum_{v \in V} d_v = \frac{M - 1}{2} + \frac{|V_s|}{|V|}
$$

are achievable. Then we are going to show that it is always possible to find a set $V_s \subseteq V$ that satisfies the properties (50) and (51) with $|V_s| \geq \frac{|V|}{3}$ and hence show that $\frac{1}{|V|} \sum_{v \in V} d_v \geq \frac{M}{2} - \frac{1}{6}$ as required by (48).

First notice that the conditions (47) are automatically satisfied (with probability one) since all the channel matrices $H_{uv}$ have been chosen at random from a continuous distribution. In order to show that the zero-forcing conditions (46) are also satisfied, consider the sets

$$
\begin{align*}
V_s^{(0)} &\triangleq \{ u \in V \setminus V_s : |\{ v \in V_s : [v, u] \in E_{\pi^*} \}| = 0 \}, \\
V_s^{(1)} &\triangleq \{ u \in V \setminus V_s : |\{ v \in V_s : [v, u] \in E_{\pi^*} \}| = 1 \}.
\end{align*}
$$
Notice that according to (51), the sets $V_s$, $V_s^{(0)}$, and $V_s^{(1)}$ form a partition of $V$. According to (50), every receiver associated with $u \in V_s$ will only observe interference from transmitters $v \notin V_s$ and since $U_u = \tilde{U}_u$ for all $u \in V_s$ and $V_v = \tilde{V}_v$ for all $v \notin V_s$, we have that $U_u^H H_{uv} V_v = \tilde{U}_u^H H_{uv} \tilde{V}_v = 0, \forall \{u, v\} \in \mathcal{E}_r : u \in V_s$. Similarly, $U_u^H H_{uv} V_v = \tilde{U}_u^H H_{uv} \tilde{V}_v = 0, \forall \{u, v\} \in \mathcal{E}_r : u \in V_s^{(0)}$. Now, consider the receivers associated with the nodes $u \in V_s^{(1)}$ and let $v_0 \in \{v \in V_s : [v, u] \in \mathcal{E}_r\}$. By construction, we have that $\text{span}(H_{uv} V_v) \subseteq \text{span}(H_{uv_0} V_{v_0}) = \text{span}(H_{uv_0} \tilde{V}_{v_0}) \cup \text{span}(H_{uv_0} V_{v_0})$ for all $v \in V$ such that $[v, u] \in \mathcal{E}_r$, and since $U_u^H H_{uv_0} V_{v_0} = [\tilde{U}_u^H H_{uv_0} \tilde{V}_{v_0}, \tilde{U}_u^H H_{uv_0} V_{v_0}] = \left[\begin{array}{cc}
p_{\tilde{U}_u H_{uv} V_{v_0}} & \tilde{U}_u^H H_{uv_0} \tilde{V}_{v_0} \p_{\tilde{U}_u H_{uv} V_{v_0}} & \tilde{U}_u^H H_{uv_0} V_{v_0} \end{array}\right] = 0$, we get $U_u^H H_{uv} V_v = 0, \forall \{u, v\} \in \mathcal{E}_r : u \in V_s^{(1)}$. Putting everything together, since the sets $V_s$, $V_s^{(0)}$, and $V_s^{(1)}$ form a partition of $V$, we can argue that $U_u^H H_{uv} V_v = 0$ for all $[u, v] \in \mathcal{E}_r$ and hence show that the conditions (46) are satisfied.

For the last part of the proof consider the sets $V_k$ given in (49) and recall that they form a partition of $V$. First notice that since $|\mathcal{V}| = |\mathcal{V}_0| + |\mathcal{V}_1| + |\mathcal{V}_2|$, there must exist some $k^* \in \{0, 1, 2\}$ such that $|\mathcal{V}_k^*| \geq \frac{|\mathcal{V}|}{3}$. By symmetry, we have that $|\mathcal{V}_1| = |\mathcal{V}_2|$ since $f(z) = 1 \leftrightarrow f(-z) = 2, \forall z \in \mathbb{Z}(\omega)$, and hence we can assume without loss of generality that $k^*$ is either 0 or 2.

Furthermore the set $V_{k^*}$ will satisfy (50) since for every $(u, v) \in \mathcal{E}$ we can write $\phi(u) = \phi(v) + \delta$, for some $\delta \in \{-1, \pm\omega, \pm(\omega + 1)\}$ and hence $f(\phi(u)) \neq f(\phi(v)), \forall (u, v) \in \mathcal{E}$.

Finally, recall that 1) for every $u \in V_1$ there exist $[v, u] \in \mathcal{E}_r$, if and only if there exist $v \in V_2$ with $\phi(v) = \phi(u) - 1 - \omega$, 2) for every $u \in V_2$ there exist $[v, u] \in \mathcal{E}_r$, if and only if there exist $v_0 \in V_0$ with $\phi(v_0) = \phi(u) + 1$ or $v_1 \in V_1$ with $\phi(v_1) = \phi(u) - \omega$ and 3) for every $u \in V_0$ there exist $[v, u] \in \mathcal{E}_r$, if and only if there exist $v_1 \in V_1$ with $\phi(v_1) = \phi(u) + 1$ or $v_2 \in V_2$ with $\phi(v_2) = \phi(u) - \omega$ or $v'_1 \in V_1$ with $\phi(v'_1) = \phi(u) - 1 - \omega$. Therefore, $\{|v \in V_{k^*} : [v, u] \in \mathcal{E}_r|\} \leq 1, \forall u \in V$ and hence the set $V_{k^*}$, $k^* \in \{0, 2\}$ will also satisfy (51).

In order to complete the proof we set $V_s = V_{k^*}$ and obtain $\frac{1}{|V|} \sum_{v \in V} d_v = \frac{M - 1}{2} + \frac{|V_{k^*}|}{|V|} \geq \frac{M}{2} - \frac{1}{6}$ as required.
APPENDIX B

PROOF OF LEMMA

Recall that the set of vertices $\mathcal{V}$ of the graph $\mathcal{G}(\mathcal{V}, \mathcal{E})$ is defined in terms of a parameter $r \geq 1$ as

$$\mathcal{V} = \{ \phi^{-1}(z) : z \in \mathbb{Z}(\omega) \cap B_r \} ,$$

where

$$B_r \triangleq \left\{ z \in \mathbb{C} : |\text{Re}(z)| \leq r, |\text{Im}(z)| \leq \frac{\sqrt{3}r}{2} \right\} .$$

Since the size of the graph depends on the choice of $r$, we will consider here the sequence of graphs $\mathcal{G}^{(r)}(\mathcal{V}^{(r)}, \mathcal{E}^{(r)})$, indexed by $r \in \mathbb{Z}^+$ and provide the corresponding results in terms of the above parameter.

A. The cardinality of $\mathcal{V}^{(r)}$

By definition $|\mathcal{V}^{(r)}| = |\mathbb{Z}(\omega) \cap B_r|$. Hence, our goal is to count the number of Eisenstein integers that belong to the set $\mathbb{Z}(\omega) \cap B_r$. We define the sets

$$L(k) = \left\{ z \in \mathbb{Z}(\omega) \cap B_r : |\text{Im}(z)| = \frac{\sqrt{3}k}{2} \right\} ,$$

for all $k \in \{-r, ..., 0, ..., r\}$. Notice that the sets $L(k)$ contain all the Eisenstein integers that lie on the same horizontal line on the complex plane and hence $\bigcup_k L(k)$ forms a partition of the set $\mathbb{Z}(\omega) \cap B_r$. Therefore,

$$|\mathbb{Z}(\omega) \cap B_r| = \sum_{k=-r}^{r} |L(k)| .$$

A key observation coming from the triangular structure of $\mathbb{Z}(\omega)$ is that

$$|L(k)| = \begin{cases} |L(0)|, & k \text{ is even} \\ |L(1)|, & k \text{ is odd.} \end{cases}$$

Hence, we can write

$$|\mathbb{Z}(\omega) \cap B_r| = K^{[r]}_{\text{even}}|L(0)| + K^{[r]}_{\text{odd}}|L(1)| .$$

where $K^{[r]}_{\text{even}}, K^{[r]}_{\text{odd}}$ denote the cardinalities of even and odd integers in $\{-r, ..., 0, ..., r\}$. 

If \( r \) is even then \( K_{\text{even}}[r] = r + 1 \) and \( K_{\text{even}}[r] = r \), whereas if \( r \) is odd then \( K_{\text{even}}[r] = r \) and \( K_{\text{even}}[r] = r + 1 \). Since \(|L(0)| = 2r + 1\) and \(|L(1)| = 2r\) for all \( r \geq 1 \) we have that

\[
|V(r)| = |\mathbb{Z}(\omega) \cap B_r| = \begin{cases} 
4r^2 + 3r + 1, & \text{if } r \text{ is even} \\
4r^2 + 3r, & \text{if } r \text{ is odd.}
\end{cases}
\] (54)

**B. The cardinality of \( T(r) \)**

We will associate here each ordered vertex triplet \([u, v, w] \in T(r)\) with its leading vertex \( u \in V(r) \) in an one-to-one fashion and define the set

\[
A^{(r)} = \{ \phi^{-1}(u) \in \mathbb{Z}(\omega) \cap B_r : [u, v, w] \in T^{(r)} \}.
\]

In order to determine the cardinality of \( T(r) \), it suffices to count the number of Eisenstein integers that belong to the set \( A^{(r)} \), since \(|T^{(r)}| = |A^{(r)}|\) by definition. Consider the sets

\[
S(k) = A^{(r)} \cap L(k)
\]

for all \( k \in \{-r, \ldots, 0, \ldots, r-1\} \). The set \( S(k) \) contains all the Eisenstein integers that are associated with a leading vertex of a triangle and lie on the same horizontal line \( L(k) \). As before, \( \bigcup_k S(k) \) forms a partition of \( A^{(r)} \) and hence

\[
|A^{(r)}| = \sum_{k=-r}^{r-1} |S(k)|.
\]

Intuitively \(|S(k)|\) counts the number of triangles that are formed between the lines \( L(k) \) and \( L(k+1) \) and hence the total number of triangles can be obtained by adding all \(|S(k)|\) up to \( k = r - 1 \).

It is not hard to verify that

\[
|S(k)| = \begin{cases} 
|S(0)|, & \text{if } k \text{ is even} \\
|S(1)|, & \text{if } k \text{ is odd.}
\end{cases}
\]

for all \( r \geq 2 \) and hence

\[
|A^{(r)}| = K_{\text{even}}^{[r]}|S(0)| + K_{\text{odd}}^{[r]}|S(1)|
\]

where \( K_{\text{even}}^{[r]}, K_{\text{odd}}^{[r]} \) denote the cardinalities of even and odd integers in \( \{-r, \ldots, 0, \ldots, r-1\} \). We have that \( K_{\text{even}}^{[r]} = K_{\text{odd}}^{[r]} = r \) and hence

\[
|A^{(r)}| = r (|S(0)| + |S(1)|).
\]
It follows from the definitions of $T(r)$, $A(r)$ and $S(0)$ that

$$z \in S(0) \iff \begin{cases} z \in L(0), f(z) \neq 0 \text{ and } \\ z + \omega, z + \omega + 1 \in L(1). \end{cases}$$

We can argue hence that the set $S(0)$ hence contains the integers $a \in \{-r + 1, \ldots, r - 1\}$ for which $f(a) = [a] \text{mod} 3 \neq 0$.

Similarly,

$$z \in S(1) \iff \begin{cases} z \in L(1), f(z) \neq 0 \text{ and } \\ z + \omega, z + \omega + 1 \in L(2). \end{cases}$$

And hence the set $S(1)$ contains the Eisenstein integers $z = a + \omega$, for all $a \in \{-r + 1, r\}$ that satisfy $f(z) = [a + 1] \text{mod} 3 \neq 0$.

It follows that

$$|S(0)| = 2 \left( r - 1 - \left\lfloor \frac{r - 1}{3} \right\rfloor \right), \text{ and}$$

$$|S(1)| = 2r - 1 - \left\lfloor \frac{r + 1}{3} \right\rfloor - \left\lfloor \frac{r - 2}{3} \right\rfloor.$$

We can hence conclude that

$$|T(r)| = r \left( 4r - \left\lfloor \frac{r - 2}{3} \right\rfloor - 2 \left\lfloor \frac{r - 1}{3} \right\rfloor - \left\lfloor \frac{r + 1}{3} \right\rfloor - 3 \right). \quad (55)$$

C. The cardinality of $V_{ex}^{(r)}$

We will upper bound $|V_{ex}^{(r)}|$ as follows. From Lemma 1 we have that

$$\sum_{u \in V_{ex}^{(r)}} \left( 1 - \frac{n_u}{2} \right) x_u = \sum_{v \in V^{(r)}} x_v - \sum_{[i,j,k] \in T^{(r)}} \left( \frac{x_i + x_j + x_k}{2} \right),$$

for any $\{x_v : v \in V^{(r)}\}$. Setting $x_v = 1$, $\forall v \in V^{(r)}$, we obtain

$$|V_{ex}^{(r)}| - \sum_{u \in V_{ex}} \frac{n_u}{2} = |V^{(r)}| - \frac{3}{2} |T^{(r)}|.$$ 

Since $n_v \leq 1$ for all $v \in V_{ex}^{(r)}$ we have that

$$\sum_{u \in V_{ex}} \frac{n_u}{2} \leq \frac{1}{2} |V_{ex}^{(r)}|,$$
and hence

$$|\mathcal{V}_r^{(r)}| \leq 2|\mathcal{V}^{(r)}| - 3|\mathcal{T}^{(r)}|. \quad (56)$$

We can lower bound $|\mathcal{T}^{(r)}|$ from (55) as

$$|\mathcal{T}^{(r)}| \geq r \left(4r - \frac{r - 2}{3} - \frac{2r - 2}{3} - \frac{r + 1}{3} - 3\right)$$

$$= r \left(4r - \frac{4r - 3}{3} - 3\right)$$

$$= \frac{8}{3}r^2 - 2r. \quad (57)$$

From (54), (56) and (57), we have that

$$|\mathcal{V}_r^{(r)}| \leq 2 \left(4r^2 + 3r + 1\right) - 3 \left(\frac{8r^2}{3} - 2r\right)$$

$$= 8r^2 + 6r + 2 - 8r^2 + 6r$$

$$= 12r + 2. \quad (58)$$

D. Proof of $|\mathcal{T}^{(r)}| = \frac{2}{3}|\mathcal{V}^{(r)}|$

First we will upper bound $|\mathcal{T}^{(r)}|$ using the inequality

$$\left\lfloor \frac{x}{3} \right\rfloor \geq \frac{x - 2}{3}, \forall x \in \mathbb{R}. $$

Applying the above inequality in (55) we obtain

$$|\mathcal{T}^{(r)}| \leq r \left(4r - \frac{4r - 11}{3} - 3\right) = \frac{8r^2 + 2r}{3}. $$

From (54) we can see that

$$2|\mathcal{V}^{(r)}| \geq 8r^2 + 2r,$$

and hence it follows that $|\mathcal{T}^{(r)}| \leq \frac{2|\mathcal{V}^{(r)}|}{3}$, which completes the proof.

E. Proof of $|\mathcal{V}_r^{(r)}| = \mathcal{O}\left(\sqrt{|\mathcal{V}^{(r)}|}\right)$

From (54) it follows that $\sqrt{|\mathcal{V}^{(r)}|} \geq 2r$ for all $r \geq 1$. From (58) we have that

$$|\mathcal{V}_r^{(r)}| \leq 12r + 2 \leq 7\sqrt{|\mathcal{V}^{(r)}|}, \forall r \geq 1,$$

and hence $|\mathcal{V}_r^{(r)}| = \mathcal{O}\left(\sqrt{|\mathcal{V}^{(r)}|}\right)$. 
APPENDIX C

PROOF OF THEOREM 2

Consider the directed interference graph $G_{\pi}(\mathcal{V}, \mathcal{E}_\pi)$ and assume that there exist full rank matrices $U_v, V_v \in \mathbb{C}^{M \times d_v}, v \in \mathcal{V}$ such that

$$U_v^H H_{vu} V_u = 0, \forall [u, v] \in \mathcal{E}_\pi$$

$$\text{rank} (U_v^H H_{vu} V_v) = d_v, \forall v \in \mathcal{V},$$

where $H_{uv} \in \mathbb{C}^{M \times M}$ have been chosen at random from a continuous distribution. Then, $\{d_v : v \in \mathcal{V}\}$ must satisfy

$$d_v \in \{0, 1, \ldots, M\}, \forall v \in \mathcal{V}$$

$$d_v + d_u \leq M, \forall (u, v) \in \mathcal{E}.$$  \hfil (61)

The first condition follows trivially from the fact that $\text{rank} (U_v^H H_{vu} V_v) \leq M$. The second condition follows from (59): The columns of the matrices $H_{vu} V_u$ and $U_v$ span two orthogonal subspaces of $\mathbb{C}^M$. Since $\text{rank} (H_{vu} V_u) = d_u$ and $\text{rank} (U_v) = d_v$, the columns of the composite matrix $[H_{vu} V_u, U_v]$ span a $(d_u + d_v)$-dimensional subspace of $\mathbb{C}^M$ and hence $d_u + d_v \leq M$, for all $[u, v] \in \mathcal{E}_\pi$. Now, for any $(u, v) \in \mathcal{E}$ and any $\pi$, either $[u, v]$ or $[v, u]$ must be in $\mathcal{E}_\pi$. Since, $d_u + d_v \leq M$ is symmetric in $(d_u, d_v)$, we can write the above inequalities for all $(u, v) \in \mathcal{E}$.

The above conditions are necessary for all $\{d_v : v \in \mathcal{V}\}$ that can be achieved in $G_{\pi}(\mathcal{V}, \mathcal{E}_\pi)$ for any decoding order $\pi$ and any linear beamforming scheme that does not use symbol extensions. We will use these conditions here to upper bound the average (per sector) achievable degrees of freedom in our framework.

From Lemma 1 we can write

$$\frac{1}{|\mathcal{V}|} \sum_{v \in \mathcal{V}} d_v = \frac{1}{2|\mathcal{V}|} \sum_{[i,j,k] \in \mathcal{T}} s(d_i, d_j, d_k) + \frac{D_{\text{ex}}}{|\mathcal{V}|},$$

where

$$s(d_i, d_j, d_k) \triangleq d_i + d_j + d_k$$

and

$$D_{\text{ex}} = \sum_{v \in \mathcal{V}_{\text{ex}}} \left(1 - \frac{n_v}{2}\right) d_v.$$
Since \( d_v \leq M \) and \( n_v \geq 0 \) for all \( v \in \mathcal{V} \), we have that
\[
D_{\text{ex}} \leq M|\mathcal{V}_{\text{ex}}|,
\]
and hence
\[
\frac{1}{|\mathcal{V}|} \sum_{v \in \mathcal{V}} d_v \leq \frac{1}{2|\mathcal{V}|} \sum_{[i,j,k] \in \mathcal{T}} s_{(d_i,d_j,d_k)} + \frac{2|\mathcal{V}_{\text{ex}}|}{|\mathcal{V}|},
\]
for all \( \{d_v : v \in \mathcal{V}\} \) that satisfy (61) and (62). Letting
\[
s^* \triangleq \max_{(d_i,d_j,d_k) \in \mathcal{T}_D} s_{(d_i,d_j,d_k)}
\]
where
\[
\mathcal{T}_D = \left\{(d_i,d_j,d_k) : \begin{array}{l}
\{d_i,d_j,d_k \in \{0,1,\ldots,M\} \\
 d_i + d_j \leq M \\
 d_j + d_k \leq M \\
 d_k + d_i \leq M
\end{array}\right\},
\]
we can conclude that any degrees of freedom \( \{d_v : v \in \mathcal{V}\} \) that are achievable in \( \mathcal{G}_\pi(\mathcal{V},\mathcal{E}_\pi) \) for any \( \pi \) must satisfy
\[
\frac{1}{|\mathcal{V}|} \sum_{v \in \mathcal{V}} d_v \leq \frac{1}{2|\mathcal{V}|} |\mathcal{T}| s^* + \frac{M|\mathcal{V}_{\text{ex}}|}{|\mathcal{V}|}.
\]

**Lemma 4** We have that
\[
s^* = \begin{cases} 
\frac{3M}{2}, & \text{if } M \text{ is even} \\
\frac{3M-1}{2}, & \text{if } M \text{ is odd}
\end{cases}
\]

**Proof:** By definition, every \( (d_i,d_j,d_k) \in \mathcal{T}_D \) must satisfy \( d_i + d_j \leq M \), \( d_j + d_k \leq M \), \( d_k + d_i \leq M \). Adding these inequalities together we obtain
\[
s_{(d_i,d_j,d_k)} \leq \frac{3M}{2}, \forall (d_i,d_j,d_k) \in \mathcal{T}_D.
\]

When \( M \) is even, the tuple \( \left( \frac{M}{2}, \frac{M}{2}, \frac{M}{2} \right) \in \mathcal{T}_D \) achieves \( s_{\left( \frac{M}{2}, \frac{M}{2}, \frac{M}{2} \right)} = 3M/2 \) and from (69) we can conclude that \( s^* = s_{\left( \frac{M}{2}, \frac{M}{2}, \frac{M}{2} \right)} = 3M/2. \)
When $M$ is odd, consider $\left(\frac{M-1}{2}, \frac{M-1}{2}, \frac{M+1}{2}\right) \in \mathcal{T}_D$ with $s\left(\frac{M-1}{2}, \frac{M-1}{2}, \frac{M+1}{2}\right) = (3M-1)/2$. Assume that $s^* > (3M-1)/2$. Since $s(d_i, d_j, d_k)$ is integer, there must exist a tuple $(d_i, d_j, d_k) \in \mathcal{T}_D$ with $s(d_i, d_j, d_k) \geq \frac{3M-1}{2} + 1 = \frac{3M+1}{2}$. This is a contradiction due to (69) and hence $s^* = s\left(\frac{M-1}{2}, \frac{M-1}{2}, \frac{M+1}{2}\right) = (3M-1)/2$.

Combining the results of Lemma 2 and 3 with the bound in (67) we arrive at

$$\frac{1}{|V|} \sum_{v \in V} d_v \leq \begin{cases} \frac{M}{2} + \mathcal{O}\left(1/\sqrt{|V|}\right), & M \text{ is even} \\ \frac{M}{2} - \frac{1}{6} + \mathcal{O}\left(1/\sqrt{|V|}\right), & M \text{ is odd}, \end{cases} \tag{70}$$

which completes the proof of Theorem 2.

**APPENDIX D**

**PROOF OF THEOREM 3**

Consider the set $V$ as defined as in Section II-B and let

$$\mathcal{D}_{\text{in}} \triangleq \bigcup_{a,b \in \mathbb{Z}: [a+b] \mod 3 = 0} \Delta(a + b\omega), \tag{71}$$

and

$$\mathcal{D}_{\text{out}} \triangleq \bigcup_{a,b \in \mathbb{Z}: [a+b] \mod 3 \neq 0} \Delta(a + b\omega) \tag{72}$$

where

$$\Delta(z) = \{(z, z + \omega), (z, z + \omega + 1), (z + \omega, z + \omega + 1)\}.$$

The set of out-of-cell edges can be defined as

$$\mathcal{E}^{\text{out}} = \{(u, v) : u, v \in V \text{ and } (\phi(u), \phi(v)) \in \mathcal{D}_{\text{out}}\}, \tag{73}$$

and the set of intra-cell edges as

$$\mathcal{E}^{\text{in}} = \{(u, v) : u, v \in V \text{ and } (\phi(u), \phi(v)) \in \mathcal{D}_{\text{in}}\}. \tag{74}$$

The interference graph in this case is given by $\hat{G}(V, \hat{\mathcal{E}})$, where $\hat{\mathcal{E}} = \mathcal{E}^{\text{out}} \cup \mathcal{E}^{\text{in}}$. We further define the sets

$$C(z) = \{z, z + 1, z - \omega, z - \omega - 1\} \cap \mathcal{B}_r.$$
for all \( z \in \mathbb{Z}(\omega) \) such that \( f(z) = 1 \). Notice that if \( |C(z)| = 4 \), the set \( C(z) \) corresponds to the labels of four vertices \( a, b, c, d \in \mathcal{V} \) with

\[
\begin{align*}
\phi(a) &= z, \\
\phi(b) &= z + 1, \\
\phi(c) &= z - \omega, \\
\phi(d) &= z - \omega - 1.
\end{align*}
\]

Moreover, the vertices \( \{a, b, c\} \) are connected in \( \mathcal{G}(\mathcal{V}, \mathcal{E}) \) only with edges in \( \mathcal{E}^{in} \) and hence correspond to sectors of the same cell (cf. Fig. 7).

First we are going to show that with the beamforming choices given in Appendix A, the above cell \( \{a, b, c\} \) can jointly decode its corresponding messages according to the decoding order \( \pi^* \).

Notice that at the time when receiver \( a \) wants to decode, all the sectors that correspond to vertices \( v \in \mathcal{V} : v \prec_{\pi^*} a \) have already decoded their messages and no longer cause interference to their neighbors. Hence, the received signal for a sector associated with \( u \in \mathcal{V} \) can be written as

\[
y_u = H_{uu} V_u s_u + \sum_{(u,v) \in \mathcal{E} : a \prec_{\pi^*} v} H_{uv} V_v s_v + z_u. \tag{75}
\]

The interfering transmitters for receiver \( a \) are given by \( \{v : (a, v) \in \mathcal{E}, a \prec_{\pi^*} v\} = \{b, c, d\} \). In order to identify the interfering transmitters for receivers \( b \) and \( c \) notice that for any \( u \in \{b, c\} \) the set \( \{v : (u, v) \in \mathcal{E}, a \prec_{\pi^*} v\} \) can be written as

\[
\{v : (u, v) \in \mathcal{E}^{in}\} \bigcup \{v : (u, v) \in \mathcal{E}^{out}, a \prec_{\pi^*} v\}.
\]

For receiver \( b \) the set \( \{v : (b, v) \in \mathcal{E}^{out}, a \prec_{\pi^*} v\} = \{v : [v, b] \in \mathcal{E}^{out}_{\pi^*}\} \) and for receiver \( c \) we have that \( \{v : (c, v) \in \mathcal{E}^{out}, a \prec_{\pi^*} v\} = \{d\} \cup \{v : [v, c] \in \mathcal{E}^{out}_{\pi^*}\} \). Putting everything together, the interfering transmitters for receivers \( b \) and \( c \) are given by

\[
\{v : (b, v) \in \mathcal{E}, a \prec_{\pi^*} v\} = \{a, c\} \cup \{v : [v, b] \in \mathcal{E}^{out}_{\pi^*}\},
\]

and

\[
\{v : (c, v) \in \mathcal{E}, a \prec_{\pi^*} v\} = \{a, c, d\} \cup \{v : [v, c] \in \mathcal{E}^{out}_{\pi^*}\}.
\]

A key observation is that according to (46) and the achievability scheme of Appendix A, all the interference from the transmitters in \( \{v : [v, b] \in \mathcal{E}^{out}_{\pi^*}\} \) and \( \{v : [v, c] \in \mathcal{E}^{out}_{\pi^*}\} \) can be zero-forced
at receivers $b$ and $c$ by projecting along $U_b^H$ and $U_c^H$ respectively. The corresponding observations are given by

$$
U_b^H y_b = U_b^H H_{bb} V_b s_b + \sum_{v \in \{a,c\}} U_b^H H_{bv} V_v s_v + z_b, \quad (76)
$$

$$
U_c^H y_c = U_c^H H_{cc} V_c s_c + \sum_{v \in \{a,c,d\}} U_c^H H_{cv} V_v s_v + z_c. \quad (77)
$$

We are going to show next that it is possible for the cell $\{a, b, c\}$ to jointly decode the desired messages $s_a, s_b$ and $s_c$ from the received signals $y_a, U_b^H y_b$ and $U_c^H y_c$. Let

$$
\tilde{s} = \begin{bmatrix} s_a \\ s_b \\ s_c \\ s_d \end{bmatrix}, \quad \tilde{y} = \begin{bmatrix} y_a \\ U_b^H y_b \\ U_c^H y_c \end{bmatrix}, \quad \tilde{z} = \begin{bmatrix} z_a \\ U_b^H z_b \\ U_c^H z_c \end{bmatrix},
$$

and

$$
\tilde{H} = \begin{bmatrix}
H_{aa} V_a & H_{ab} V_b & H_{ac} V_c & H_{ad} V_d \\
U_b^H H_{sa} V_a & U_b^H H_{bb} V_b & U_b^H H_{bc} V_c & 0_{d_a \times d_d} \\
U_c^H H_{sa} V_a & u_c^H H_{sa} V_b & U_c^H H_{cc} V_c & U_c^H H_{sd} V_d
\end{bmatrix},
$$

such that the available observations in the cell $\{a, b, c\}$ can be written in vector form as

$$
\tilde{y} = \tilde{H} \tilde{s} + \tilde{z}. \quad (78)
$$

**Lemma 5** If the channel gains $H_{uv} \in \mathbb{C}^{M \times M}$, $(u, v) \in \hat{E}$ are chosen independently at random from a Gaussian distribution, the matrix $\tilde{H}$ has full column rank with probability one.

**Proof:** The matrix $\tilde{H}$ has $M + d_b + d_c$ rows and $d_a + d_b + d_c + d_d$ columns. Since $d_a + d_d \leq M$ for all $M$ (odd or even), we have to show that $Pr[\text{rank}(\tilde{H}) = d_a + d_b + d_c + d_d] = 1$. Recall that the beamforming matrices $V_v, U_u$ do not depend on the channel realizations $H_{ij}$ used in the definition of the above matrix. Hence, assuming that all channel gains are chosen independently at random from a Gaussian distribution, we can argue that the non-zero entries in $\tilde{H}$ (given by the projections $U^H U^H H_{ij} V_v$) are also independent. Let $F = P \tilde{H}$ be the matrix obtained by rearranging the rows of $\tilde{H}$ such that all zero entries are in the upper-right corner and consider $\tilde{F}$ to be the square sub-matrix defined by the $d_a + d_b + d_c + d_d$ rows of $F$. We can see that the diagonal
elements of $\tilde{F}$ are going to be non-zero, and hence, we can show by Lemma 3 that the rank of $\tilde{F}$ is full with probability one. Therefore, $\tilde{H}$ will always have $d_a + d_b + d_c + d_d$ linearly independent rows and $Pr[\text{rank}(\tilde{H}) = d_a + d_b + d_c + d_d] = 1$.

In view of the above lemma, the vector observation in (78) can be used to decode the symbols in $\tilde{s}$ and hence the cell $\{a, b, c\}$ is able to recover the desired messages $s_a$, $s_b$ and $s_c$.

Applying the above procedure successively, according to the decoding order $\pi^*$, we can argue that all the cells $\{a, b, c\} \subseteq \mathcal{V}$ whose labels correspond to a set $C(z)$ with $|C(z)| = 4$, can decode their desired messages using the beamforming choices of Appendix A.

In order to conclude the proof it remains to consider all the degenerate cases for cells that lie on the boundary of $\hat{G}(\mathcal{V}, \hat{E})$ and correspond to $C(z)$ with $|C(z)| \leq 3$. When $C(z) = 1$, there is only out-of-cell interference and hence the scheme works as described in Appendix A. This is also the case when $|C(z)| = 2$ and $\phi(d) = z - 1 - \omega \in C(z)$. If $|C(z)| = 2$ and $\phi(d) = z - 1 - \omega \notin C(z)$ the two sectors $u, v$ of the given cell can zero-force all out-of-cell interference and use their vector observation

$$
\begin{bmatrix}
U^H_y y_u \\
U^H_y y_v
\end{bmatrix} =
\begin{bmatrix}
U^H_v H_{uv} V_v & U^H_v H_{vu} V_u \\
U^H_u H_{uv} V_v & U^H_u H_{uu} V_u
\end{bmatrix}
\begin{bmatrix}
s_u \\
s_v
\end{bmatrix} + \tilde{z}
$$

to jointly decode the desired messages $s_u$ and $s_v$. In a similar fashion, all the cells $\{a, b, c\}$ that correspond to a set $C(z)$ with $|C(z)| = 3$ and $\phi(d) = z - 1 - \omega \notin C(z)$ can decode their messages using the projected observations $U^H_y y_a$, $U^H_y y_b$ and $U^H_y y_c$. Finally, the only possible cell configuration with $|C(z)| = 3$ and $\phi(d) = z - 1 - \omega \in C(z)$, is $\{a, c\}$ with $\phi(a) = z$ and $\phi(c) = z - \omega$. The corresponding vector observation is given by

$$
\begin{bmatrix}
y_a \\
U^H_c y_c
\end{bmatrix} =
\begin{bmatrix}
H_{aa} V_a & H_{ac} V_c & H_{ad} V_d \\
U^H_c H_{ca} V_a & U^H_c H_{cc} V_c & U^H_c H_{cd} V_d
\end{bmatrix}
\begin{bmatrix}
s_a \\
s_c \\
s_d
\end{bmatrix} + \tilde{z}.
$$

Notice that the above channel matrix has $M + d_c$ rows and $d_a + d_c + d_d$ columns. According to the beamforming choices of Appendix A we have that $d_a + d_d \leq M$ for all $M$ and hence we can argue as before that the above matrix has full column rank with probability one. Therefore, the receivers $a$ and $c$ can jointly decode their desired messages in this case as well.
The proof can be obtained as a straightforward generalization of the proof described in Section V-B using the beamforming design of Theorem 3 given in Appendix D. Applying Lemma 3, we can show that primary and secondary sectors are always able to decode their messages from the available observations

\[
\begin{bmatrix}
    y_a \\
    U_b^H y_b \\
    U_c^H y_c
\end{bmatrix} =
\begin{bmatrix}
    H_{aa} V_a & H_{ab} V_b & H_{ac} V_c & H_{ad} V_d \\
    U_b^H H_{ba} V_a & U_b^H H_{bb} V_b & U_b^H H_{bc} V_c & 0_{d_b \times d_d} \\
    U_c^H H_{ca} V_a & U_c^H H_{cb} V_b & U_c^H H_{cc} V_c & U_c^H H_{cd} V_d
\end{bmatrix}
\begin{bmatrix}
    s_a \\
    s_b \\
    s_c \\
    s_d
\end{bmatrix} + \tilde{z},
\]

(79)

and

\[
\begin{bmatrix}
    U_b^H y_b \\
    U_c^H y_c
\end{bmatrix} =
\begin{bmatrix}
    U_b^H H_{bb} V_b & U_b^H H_{bc} V_c \\
    U_c^H H_{cb} V_b & U_c^H H_{cc} V_c
\end{bmatrix}
\begin{bmatrix}
    s_b \\
    s_c
\end{bmatrix} + \tilde{z},
\]

(80)

for all channel-state configurations given in Section V-B. We omit the details here for brevity.

Here, we are going to follow an approach similar to the one in Section III-B and show that for any decoding order \(\pi\), any linear scheme for the system \(\{\hat{G}(V, \hat{E} | A) : A \in \{0, 1\}^{2|\hat{E}|}\}\) achieves compound DoFs \(d_C\) upper bounded by \(d_C^* + O\left(1/\sqrt{|V|}\right)\), as stated in Theorem 5.

First we will upper bound \(d_C\) by conditioning on a specific channel-state configuration \(A^*\) shown in Fig. 14. We have that

\[
d_C = \min_{A \in \{0, 1\}^{2|\hat{E}|}} d_{\hat{G}}(A) \leq d_{\hat{G}}(A^*),
\]

(81)

where \(A^*\) is given by setting \(\alpha_{ij} = 1\) for all edges \([i, j] \in \hat{E}\) that belong to the triangles,

\[\hat{T} = \{[u, v, w] : [\phi(u), \phi(v), \phi(w)] \in \hat{P}, u, v, w \in V\},\]

with \(\hat{P} = \{[z, z + \omega, z + \omega + 1] : z \in \Lambda_0 - 1\}\), and \(\alpha_{ij} = 0\) otherwise.

Notice, that the set \(\hat{T}\) has been chosen such that for all \([u, v, w] \in \hat{T}\), the sectors associated with the nodes \(u, v, w\) belong to different cells and hence cannot be jointly decoded. Arguing as in
Fig. 14: The set of triangles \([u, v, w] \in \hat{T}\) for \(\hat{G}(V, \hat{E}|A^*)\). All the circle nodes belong to \(\hat{V}_{in}\) and participate in one triangle \((n_v = 1)\). The set \(\hat{V}_{ex}\) contains the colored nodes on the boundary for which \(n_v = 0\).

Lemma 4 in Appendix C, we can show that for any decoding order, the total degrees of freedom achievable in each triangle cannot be more than

\[
s^* = \begin{cases} 
  \frac{3M}{2}, & M \text{ is even} \\
  \frac{3M-1}{2}, & M \text{ is odd.}
\end{cases}
\] (82)

Further, observe that apart from some vertices on the external boundary of the graph \((v \in \hat{V}_{ex})\), all other nodes \((v \in \hat{V}_{in})\) participate in exactly one triangle in \(\hat{T}\), and therefore we have that \(\sum_{v \in V} d_v = \sum_{[i,j,k] \in \hat{T}} (d_u + d_v + d_w) + \sum_{v \in \hat{V}_{ex}} d_v\). The average (per sector) degrees of freedom achievable in \(\hat{G}(V, \hat{E}|A^*)\) can be bounded as

\[
d_{\hat{G}}(A^*) = \frac{1}{|\hat{V}|} \sum_{v \in V} d_v
\]

(83)

\[
= \frac{1}{|\hat{V}|} \sum_{[i,j,k] \in \hat{T}} (d_u + d_v + d_w) + \frac{1}{|\hat{V}|} \sum_{v \in \hat{V}_{ex}} d_v
\]

(84)

\[
\leq \frac{|\hat{T}|}{|\hat{V}|} s^* + \frac{|\hat{V}_{ex}|}{|\hat{V}|}
\]

(85)

To conclude the proof we can argue as, in Lemma 2, that \(|\hat{T}| \leq \frac{1}{3} |V|\) and \(|V_{ex}| = \mathcal{O}\left(\sqrt{|V|}\right)\), and show that \(d_C = \frac{1}{3} s^* + \mathcal{O}\left(1/\sqrt{|V|}\right)\).
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