COMPLETE TRANSLATING SOLITONS TO THE MEAN CURVATURE FLOW 
IN $\mathbb{R}^3$ WITH NONNEGATIVE MEAN CURVATURE

JOEL SPRUCK AND LING XIAO

ABSTRACT. We prove that any complete immersed two-sided mean convex translating soliton $\Sigma \subset \mathbb{R}^3$ for the mean curvature flow is convex. As a corollary it follows that an entire mean convex graphical translating soliton in $\mathbb{R}^3$ is the axisymmetric “bowl soliton”. We also show that if the mean curvature of $\Sigma$ tends to zero at infinity, then $\Sigma$ can be represented as an entire graph and so is the “bowl soliton”. Finally we classify the asymptotic behavior of all locally strictly convex graphical translating solitons defined over strip regions.

1. INTRODUCTION

A complete immersed hypersurface $f : \Sigma^n \to \mathbb{R}^{n+1}$ with trivial normal bundle (two-sided for short) is called a translating soliton for the mean curvature flow, with respect to a unit direction $e_{n+1}$, if its mean curvature is given by $H = \langle N, e_{n+1} \rangle$ where $N$ is a global unit normal field for $\Sigma$. Then $F(x, t) := f(x) + te_{n+1}$ satisfies

$$\Delta^\Sigma F = HN = \langle N, e_{n+1} \rangle > N = (e_{n+1})^\perp = F^\perp_t,$$

thus justifying the terminology. Translating solitons form a special class of eternal solutions for the mean curvature flow that besides having their own intrinsic interest, are models of slow singularity formation. Therefore there has been a great deal of effort in trying to classify them in the case $H > 0$. In this paper, we shall always assume our translating solitons are mean convex which by abuse of language we take to mean $H > 0$. The abundance of glueing constructions for translating solitons with high genus and $H$ changing sign (see [24],[25],[26], [13], [11], [28]) suggests a general classification is unlikely.

For $n = 1$ the unique solution is the grim reaper curve $\Gamma : x_2 = \log \sec x_1, \ |x_1| < \frac{\pi}{2}$, while for $n \geq 2$ we have the one parameter family of convex grim cylinders (see Lemma 5.1 for the $n = 2$ case)

$$(1.1) \quad x_{n+1} = \lambda^2 \log \sec \frac{x_1}{\lambda} + \sum_{k=2}^{n} \alpha_k x_k, \quad \sum_{k=2}^{n} \alpha_k^2 = \lambda^2 - 1, \quad |x_1| < \frac{\pi}{2} \lambda, \quad \lambda \geq 1,$$
which can be obtained from the standard grim cylinders $\Gamma \times \mathbb{R}^{n-1}$ by a rotation and scaling. The family of grim graphical solitons in $\mathbb{R}^3$:

\begin{equation}
     u^\lambda(x_1, x_2) = \lambda^2 \log \sec \frac{x_1}{\lambda} \pm Lx_2, \quad L = \sqrt{\lambda^2 - 1}, \quad \lambda \geq 1
\end{equation}

defined over the strip $S^\lambda := \{(x_1, x_2) : |x_1| < R := \frac{\lambda\pi}{2}\}$ will play a central role in our classification of mean convex graphical translating solitons in $\mathbb{R}^3$.

Similarly if $x_{m+1} = v(x_1, \ldots, x_m)$ is a graphical translating soliton in $\mathbb{R}^{m+1}$, then for $x = (x_1, \ldots, x_n) = (x', x_{m+1}, \ldots, x_n)$,

\begin{equation}
     v^\lambda(x) := \lambda^2 v(x'/\lambda) + \sum_{k=m+1}^{n} \alpha_k x_k, \quad \sum_{k=m+1}^{n} \alpha_k^2 = \lambda^2 - 1, \quad \lambda \geq 1,
\end{equation}

is a graphical translating soliton in $\mathbb{R}^{n+1} = \mathbb{R}^m \times \mathbb{R}^{n-m} \times \mathbb{R}$. Conversely if $x_{n+1} = u(x_1, \ldots, x_n)$ is a convex graphical translating soliton in $\mathbb{R}^{n+1}$, then $D^2 u$ has constant rank $m$, $1 \leq m < n$ by Corollary 1.3 of Bian and Guan [4] which implies $u(x) = v^\lambda(x)$ for an appropriate choice of $x_1, \ldots, x_n$ and $\alpha_{m+1}, \ldots, \alpha_n$. Moreover by the results of Wang [33], $\Sigma = \text{graph}(v)$ is a complete graph in $\mathbb{R}^{m+1}$ defined over a strip in $\mathbb{R}^m$ or is an entire graph over $\mathbb{R}^m$.

There is as well a unique (up to horizontal translation) axisymmetric solution called the “bowl soliton” [1], [3] which has the asymptotic expansion as an entire graph $u(x) = \frac{1}{2(n-1)}|x|^2 - \log |x| + O(1)$.

White [35] tentatively conjectured that all convex translating solutions have the form

$$\{(x, y, z) \in \mathbb{R}^j \times \mathbb{R}^{n-j} \times \mathbb{R} : z = f(|x|)\}$$

for $j \geq 2$; for $j = 1$, $f$ defines the grim reaper curves so is defined on an interval. White remarks that even if this conjecture is false, it may be true for blow up limits of mean convex mean curvature flows. In [33] Wang proved that in dimension $n = 2$, any entire convex graphical translating soliton must be rotationally symmetric, and hence the bowl soliton. He also showed there exist entire locally strictly convex graphical translating solitons for dimensions $n > 2$ that are not rotationally symmetric (thus disproving one conjecture of White [35]) as well as complete locally strictly convex graphical translating solitons defined over strip regions in $\mathbb{R}^n$. Wang also conjectured that for $n = 2$, any entire graphical translating soliton must be locally strictly convex and a similar statement in dimension $n > 2$ under the additional assumption that $H$ tends to zero at infinity.
More recently, Haslhofer [16] proved the uniqueness of the bowl soliton in arbitrary dimension under the assumption that the translating soliton $\Sigma$ is $\alpha$-noncollapsed and uniformly 2-convex. The $\alpha$-noncollapsed condition means that for each $P \in \Sigma$, there are closed balls $B^\pm$ disjoint from $\Sigma - P$ of radius at least $\frac{\alpha}{H(P)}$ with $B^+ \cap B^- = \{P\}$. It figures prominently in the regularity theory for mean convex mean curvature flow [34], [35], [20], [30]. The 2-convex condition (automatic if $n = 2$) means that if $\kappa_n \leq \kappa_{n-1} \leq \ldots \kappa_1$ are the ordered principal curvatures of $\Sigma$, then $\kappa_n + \kappa_{n-1} \geq \beta H$ for some uniform $\beta > 0$. The $\alpha$-noncollapsed condition is a deep and powerful property of weak solutions of the mean convex mean curvature flow [35], [17] which implies that any complete ($\alpha$-noncollapsed) mean convex translating soliton $\Sigma$ is convex with uniformly bounded second fundamental form.

The main result of this paper is a proof of a more general form of the $n = 2$ conjecture of Wang.

**Theorem 1.1.** Let $\Sigma \subset \mathbb{R}^3$ be a complete immersed two-sided translating soliton for the mean curvature flow with nonnegative mean curvature. Then $\Sigma$ is convex.

By Sacksteder’s theorem [28], the condition $H > 0$ and Corollary 2.1 of [33], we may conclude

**Corollary 1.2.** $\Sigma$ is the boundary of a convex region in $\mathbb{R}^3$ whose projection on the plane spanned by $e_1$, $e_2$ is (after rotation of coordinates) either a strip region $\{(x_1, x_2) : |x_1| < R\}$ or $\mathbb{R}^2$. Moreover $\Sigma$ is the graph of a function $u(x_1, x_2)$ which satisfies the equation

\[
(1.4) \quad \text{div} \left( \frac{\nabla u}{\sqrt{1 + |\nabla u|^2}} \right) = \frac{1}{\sqrt{1 + |\nabla u|^2}},
\]

or in nondivergence form,

\[
(1.5) \quad (1 + u_{x_2}^2)u_{x_1x_1} - 2u_{x_1}u_{x_2}u_{x_1x_2} + (1 + u_{x_1}^2)u_{x_2x_2} = 1 + u_{x_1}^2 + u_{x_2}^2.
\]

Combining Theorem [1.1] with Theorem 1.1 in [33] we have

**Corollary 1.3.** Any entire solution in $\mathbb{R}^2$ to the equation

\[
\text{div} \left( \frac{\nabla u}{\sqrt{1 + |\nabla u|^2}} \right) = \frac{1}{\sqrt{1 + |\nabla u|^2}},
\]

must be rotationally symmetric in an appropriate coordinate system and hence is the bowl soliton.
A necessary and sufficient condition for mean convex translating solitons to be graphical over \( \mathbb{R}^2 \) and thus the bowl soliton is given in the next theorem.

**Theorem 1.4.** Let \( \Sigma \subset \mathbb{R}^3 \) be a complete immersed two-sided translating soliton for the mean curvature flow with nonnegative mean curvature and suppose that \( H(P) \to 0 \) as \( P \in \Sigma \) tends to infinity. Then \( \Sigma \) is after translation the axisymmetric bowl soliton.

The existence of the grim family \( u^\lambda \) (see [12]), the convexity Theorem 1.1 and a global curvature bound (see Theorem 2.8 in section 2) are the key tools that allows us to classify locally strictly convex graphical translating solitons defined over strips.

**Theorem 1.5.** Let \( \Sigma = \text{graph}(u) \) be a complete locally strictly convex translating soliton defined over a strip region \( S^\lambda := \{ (x_1, x_2) : |x_1| < R := \frac{\lambda \pi}{2} \} \). Then (after possibly relabeling the \( e_2 \) direction)

i. For \( \lambda \leq 1 \) there is no locally strictly convex solution in \( S^\lambda \).

ii. \( \lim_{x_2 \to +\infty} u_{x_2}(x_1, x_2) = L := \sqrt{\lambda^2 - 1}, \lambda > 1. \)

iii. \( \lim_{x_2 \to -\infty} u_{x_2}(x_1, x_2) = -L. \)

iv. \( \lim_{A \to \pm \infty} (u(x_1, x_2 + A) - u(0, A)) = u^\lambda(x_1, x_2) \)

\[(1.6) \]

\( \lim_{A \to \pm \infty} u_{x_1}(x_1, A) = \lambda \tan \frac{x_1}{\lambda}. \)

The above limits are uniform in \( |x_1| \leq R - \varepsilon \) for any \( \varepsilon > 0. \)

v. For \( P = (x_1, x_2, u(x_1, x_2)) \in \Sigma, (x_1, x_2) \in S^\lambda, \)

\[(1.7) \]

\( H(P) \leq R - |x_1|, \quad H(P) \geq \theta(\varepsilon) \text{ if } |x_1| \leq R - \varepsilon. \)

vi. \( u(x_1, x_2) = u(-x_1, x_2) \) and \( u_{x_1}(x_1, x_2) > 0 \) for \( x_1 > 0. \)

**Remark 1.6.** It was shown in [33] that locally strictly convex solutions in strips do exist. The existence of a locally strictly convex translating soliton in every \( S^\lambda \) has recently been proven by Bourdin, Langford and Tinaglia in the preprint [6]. Moreover, the existence, uniqueness and a complete classification of all graphical translators has just appeared in the preprint of Hoffman, Ilmanen, Martin and White [18].

The organization of the paper is as follows. In section 2 we show that any immersed two-sided mean convex translating soliton is stable. This allows us to use the method of Choi-Schoen [7] as modified by Colding-Minicozzi [9], [10] to prove a global curvature
bound (Theorem 2.8). This is needed for the proof of Theorem 1.1 in section 3, which is based on a delicate maximum principle argument. In section 4 we give the proof of Theorem 1.4. This result also allows us to start the proof of Theorem 1.5 which is long and detailed and contained in section 5. We wish to thank Theodora Bourni for a careful reading and helpful comments.

2. STABILITY AND CURVATURE ESTIMATES.

We will need the following well-known identities that hold on any translating soliton in $\mathbb{R}^{n+1}$ (see for example [23]).

Lemma 2.1. Let $\Sigma$ be a two-sided immersed translating soliton in $\mathbb{R}^{n+1}$ with second fundamental form $A$. Let $A = (h_{ij})$ be the second fundamental form of $\Sigma$, $u = x_{n+1}|_{\Sigma}$ and $\Delta^f := \Delta^\Sigma + <\nabla, e_{n+1}>$ be the drift Laplacian on $\Sigma$. Then

i. $|\nabla u|^2 = 1 - H^2$, $\Delta^\Sigma u = H^2$

ii. $\Delta^f A + |A|^2 A = 0$,

iii. $\Delta^f H + H|A|^2 = 0$,

iv. $\Delta^f (|A|^2) - 2|\nabla A|^2 + 2|A|^4 = 0$.

It is well known that a translating soliton $\Sigma$ with respect to the direction $e_{n+1}$ in $\mathbb{R}^{n+1}$ is a critical point of the weighted area functional

$$\mathcal{A}(\Sigma) = \int_\Sigma e^{x_{n+1}} dv$$

and is in fact minimal with respect to the weighted Euclidean metric $e^{x_{n+1}} \delta$ on $\mathbb{R}^{n+1}$. The second variation of $\mathcal{A}$ with respect to a compactly supported normal variation $\eta N$ is easily computed to be

$$\mathcal{A}''(0) = \int_\Sigma (|\nabla \eta|^2 - |A|^2 \eta^2) e^{x_{n+1}} dv = \int_\Sigma -\eta L\eta e^{x_{n+1}} dv,$$

where $L\eta = e^{-x_{n+1}} \text{div}^\Sigma (e^{x_{n+1}} \nabla \eta) + |A|^2 \eta$ is the associated stability operator.

Proposition 2.2. i. Let $\Sigma \subset \mathbb{R}^{n+1}$ be a complete immersed two-sided translating soliton with respect to $e_{n+1}$ with $H \geq 0$. Then $\Sigma$ is strictly stable, that is, $\lambda_1(-L)(D) > 0$ on any compact subdomain $D \subset \Sigma$.

ii. The following are equivalent:

a. There exists a positive solution $v$ of $Lv = 0$ for every bounded $D$.  


b. \( \lambda_1(-L)(D) \geq 0 \) for every bounded \( D \).
c. \( \lambda_1(-L)(D) > 0 \) for every bounded \( D \).

Proof. i. We may assume that \( H > 0 \). Then \( w = \log H \) satisfies \( \Delta w + \langle \nabla w, e_{n+1} \rangle + |A|^2 = -|\nabla w|^2 \). Hence

\[
\int_{\Sigma} (\eta^2 |A|^2 - |\nabla \eta|^2) e^{x_{n+1}} dv = - \int_{\Sigma} (\eta^2 |\nabla w|^2 - 2\eta < \nabla \eta, \nabla w > + |\nabla \eta|^2) e^{x_{n+1}} dv
\]

\[
= - \int_{\Sigma} |\eta \nabla w - \nabla \eta|^2 e^{x_{n+1}} dv < 0.
\]

ii. The proof is a straightforward modification of that of Fischer-Colbrie and Schoen [12] and will not be given. \(\square\)

We will need the following corollary for the case at hand \( n = 2 \).

Corollary 2.3. Let \( B_\rho(P) \) be an intrinsic ball in \( \Sigma \) with \( \rho < 2\pi \). Then \( B_\rho(P) \) is disjoint from the conjugate locus of \( P \) and

\[
\int_{\Sigma} f^2 |A|^2 dv \leq e^{2\rho} \int_{\Sigma} |\nabla f|^2 dv
\]

for \( f \in H_0(B_\rho(P)) \).

Proof. Let \( K = K^\Sigma \) denote the Gauss curvature of \( \Sigma \). Since \( K \leq \frac{H^2}{4} \leq \frac{1}{4} \), the first statement follows from standard comparison geometry. Also \( |\nabla x_3|^2 = 1 - H^2 \leq 1 \), so \( |x_3(Q) - x_3(P)| \leq \rho \) for any \( Q \in B_\rho(P) \). Hence \( e^{-\rho} e^{x_3}(P) \leq e^{x_3}(Q) \leq e^{\rho} e^{x_3}(P) \) and the result follows from Proposition 2.2. \(\square\)

We now follow the Colding-Minicozzi method [9, 10] with appropriate modification, to prove intrinsic area bounds and then curvature bounds. For two dimensional graphs, such curvature estimates follow immediately from the work of Leon Simon [31], see also [29].

Proposition 2.4. Let \( \Sigma \subset \mathbb{R}^3 \) be a two-sided immersed translating soliton with \( H \geq 0 \) and let \( B_\rho(P) \) be a topological disk in \( \Sigma \). Then \( B_\rho(P) \) is disjoint from the cut locus of \( P \) for \( e^{2\rho} < 2 \) and

\[
\begin{align*}
&i. \quad \frac{\text{area}(B_\rho(P))}{\rho^2} \leq 2\pi, \\
&ii. \quad \int_{B_\rho^{\rho^2}(P)} |A|^2 dv \leq 2\pi \left\{ (\log \frac{1}{\mu})^{-2} + 2(\log \frac{1}{\mu})^{-1} \right\} \text{ for } \mu \in (0, 1).
\end{align*}
\]
Proof. We first prove $\mathcal{B}_\rho(P)$ is disjoint from the cut locus $C(P)$ of $P$, that is the injectivity radius of $P$ satisfies $r_0 := \text{inj}_p(\Sigma) > \rho$. Suppose for contradiction that $Q \in \partial \mathcal{B}_{r_0}(P)$ is a cut locus of $P$ and $r_0 \leq \rho$. We know by Corollary 1.2 that $Q$ is not in the conjugate locus of $P$ so by Klingenberg’s lemma (see for example Lemma 5.7.12 of [27]) there are two minimizing geodesics from $P$ to $Q$ which fit together smoothly at $Q$ with a possible corner at $P$ and bounding a domain $D \subset \mathcal{B}_{r_0}(P)$. By Gauss-Bonnet,

$$\frac{1}{4} \text{area}(D) \geq \int_D K \, dv = 2\pi - \int_{\partial D} \kappa_g \, d\sigma \geq \pi,$$

hence $\text{area}(\mathcal{B}_{r_0}(P)) > \text{area}(D) \geq 4\pi$. On the other hand by (2.2) with $\rho = r_0$ (proved below), $\text{area}(\mathcal{B}_{r_0}(P)) < 2\pi r_0^2$. Therefore $r_0 > \sqrt{2}$, contradicting $r_0 \leq \rho < \frac{1}{2} \log 2$.

We now prove the stated inequalities. Let $l(s)$ be the length of $\partial \mathcal{B}_s(P)$ and $K(s) = \int_{\mathcal{B}_s(P)} K \, dv$. By Gauss-Bonnet,

$$l'(s) = \int_{\partial \mathcal{B}_s(P)} \kappa_g \, d\sigma = 2\pi - K(s).$$

For $r = d(P, x)$, $f(x) = \eta(r)$, $\eta, -\eta' \geq 0, \eta(\rho) = 0$, we use the stability inequality (2.1) and write

$$|A|^2 = H^2 - 2K \geq -2K,$$

to obtain (for $\rho \leq r_0$)

$$(2.4) \quad -2 \int_{\mathcal{B}_\rho(P)} K f^2 \leq 2 \int_{\mathcal{B}_\rho(P)} |\nabla f|^2.$$

By the coarea formula,

$$(2.5) \quad \int_{\mathcal{B}_\rho(P)} K f^2 = \int_0^\rho \eta^2(s) \int_{\partial \mathcal{B}_s(P)} K \, d\sigma \, ds = \int_0^\rho \eta^2(s) K'(s) \, ds,$$

$$\int_{\mathcal{B}_\rho(P)} |\nabla f|^2 = \int_0^\rho \int_{\partial \mathcal{B}_s(P)} |\nabla f|^2 \, d\sigma \, ds = \int_0^\rho (\eta')^2(s) l(s) \, ds.$$

For $\eta(r) = 1 - \frac{r}{\rho}$, using (2.3)-(2.5) this gives

$$(2.6) \quad -\frac{4}{\rho} \int_0^\rho (2\pi - l'(s))(1 - \frac{s}{\rho}) \, ds \leq 2 \frac{\text{area}(\mathcal{B}_\rho(P))}{\rho^2}.$$

By integration by parts,

$$(2.7) \quad \int_0^\rho (2\pi - l'(s))(1 - \frac{s}{\rho}) \, ds = \pi \rho - \frac{\text{area}(\mathcal{B}_\rho(P))}{\rho}.$$
Finally combining (2.6), (2.7) and simplifying gives inequality i. in (2.2). For part ii. we use the logarithmic cutoff

\[ \eta(s) = \begin{cases} 
    1 & \text{if } s \leq \mu^2 \rho \\
    \frac{\log \frac{s}{\rho}}{\log \mu} - 1 & \text{if } \mu^2 \rho < s < \mu \rho \\
    0 & \text{if } s > \mu \rho 
\end{cases} \]  

in (2.1). Then

\[ \int_{B_{\mu^2 \rho}(P)} |A|^2 \leq \frac{2}{(\log \mu)^2} \int_{\mu^2 \rho}^{\mu \rho} \frac{l(s)}{s^2} ds \]

\[ \leq \frac{2}{(\log \mu)^2} \left\{ \frac{\text{area}(B_{\mu \rho}(P))}{s^2} \left| \frac{\mu}{\mu^2 \rho} \right|^\mu + 2 \int_{\mu^2 \rho}^{\mu \rho} \frac{\text{area}(B_{s}(P))}{s^3} ds \right\} \]

\[ \leq 4\pi \left\{ \frac{1}{(\log \mu)^2} + \frac{2}{\log \mu} \right\} \]

by (2.2) part i. □

For later use we will need two well known lemmas; the first is an extrinsic mean value inequality (for a proof see [10] p. 26-27) and the second one says that curvature bounds implies graphical with intrinsic balls \( B_s \) and extrinsic balls \( B_s \) related (see [10] Lemma 2.4).

Lemma 2.5. Let \( \Sigma \subset \mathbb{R}^3 \) be an embedded surface with \( x_0 \in \Sigma, \ B_s(x_0) \cap \partial \Sigma = \emptyset \). Suppose the mean curvature of \( \Sigma \) satisfies \( |H| \leq C \) and \( f \geq 0 \) is a smooth function on \( \Sigma \) satisfying \( \Delta^\Sigma f \geq -\lambda s^{-2} f \). Then

\[ f(x_0) \leq \frac{e^{(\frac{t}{2}+Cs)}}{\pi s^2} \int_{B_s(x_0) \cap \Sigma} f dv. \]

Lemma 2.6. Let \( \Sigma \subset \mathbb{R}^3 \) be an immersed surface with \( 16s^2 \sup_{\Sigma} |A|^2 \leq 1 \). If \( P \in \Sigma \) and \( \text{dist}^\Sigma(P, \partial \Sigma) \geq 2s \), then

i. \( B_{2s}(P) \) can be written as a graph of a function \( u \) over \( T_P \Sigma \) with \( |\nabla u| \leq 1 \) and \( \sqrt{2s} |\text{Hess} u| \leq 1 \);

ii. The connected component of \( B_s(P) \cap \Sigma \) containing \( P \) is contained in \( B_{2s}(P) \).

Proposition 2.7. (Choi-Schoen type curvature bound) Let \( \Sigma \subset \mathbb{R}^3 \) be a two-sided immersed translating soliton and let \( B_\rho(P) \) be disjoint from the cut locus of \( P \). Then there exists \( \varepsilon, \tau < \sqrt{\frac{C}{2\pi}} < \rho \) such that if for all \( r_0 \leq \tau \), there holds \( \int_{B_{r_0}(P)} |A|^2 \leq \varepsilon \), then for all \( 0 < \sigma \leq r_0, \ y \in B_{r_0-\sigma}(P) \) we have \( |A|^2(y) \leq \sigma^{-2} \).
**Proof.** Define $F(x) = (r_0 - r(x))^2|A|^2(x)$ on $B_{r_0}(P)$ and suppose $F$ assumes its maximum at $x_0$. Note that if $F(x_0) \leq 1$, then $\sigma^2|A|^2(y) \leq (r_0 - r(y))^2|A|^2(y) \leq F(x_0) \leq 1$ and we are done. If not, define $\sigma$ by $4\sigma^2|A|^2(x_0) = 1$. Then by the triangle inequality on $B_{\sigma}(x_0)$,

$$\frac{1}{2} \leq \frac{r_0 - r(x)}{r_0 - r(x_0)} \leq 2,$$

which implies $\sup_{B_{\sigma}(x_0)} |A|^2 = 4|A|^2(x_0) = \sigma^{-2}$. On $\Sigma$ we have the Simons’ type equation $L(|A|^2) - 2|\nabla A|^2 + 2|A|^4 = 0$ which implies $\Delta(|A|^2 + \frac{1}{2}) \geq -2|A|^2(|A|^2 + \frac{1}{2})$. Hence for $f(x) := |A|^2 + \frac{1}{2}$, $\Delta f \geq -2\sigma^{-2}f$ on $B_{\sigma}(x_0)$. Using Lemmas 2.6 and 2.5 with $s = \frac{\sigma}{2}$, $\lambda = \frac{1}{6}$, $C = 1$ and Proposition 2.4 part i., we find

$$\left(\frac{1}{4\sigma^2} + \frac{1}{2}\right) = |A|^2(x_0) + \frac{1}{2} \leq \frac{16}{\pi\sigma^2} e^{\left(\frac{1}{\pi} + \frac{\lambda}{4}\right)}\{\varepsilon + 2\pi r_0^2\}. \tag{2.10}$$

Multiplying (2.10) by $\sigma^2$ we find

$$\frac{1}{4} < \frac{1}{4} + \frac{\sigma^2}{2} \leq \frac{16}{\pi} e^{\left(\frac{1}{\pi} + \frac{\lambda}{4}\right)}\{\varepsilon + 2\pi r_0^2\} < \frac{32e\varepsilon}{\pi}, \tag{2.11}$$

which is impossible for $\varepsilon \leq \frac{\pi}{128e}$. \hfill \Box

We are now in a position to prove the curvature estimate we will need in the next section.

**Theorem 2.8.** Let $\Sigma \subset \mathbb{R}^3$ be a complete immersed two-sided translating soliton with respect to $e_3$ with $H \geq 0$. Then there is a universal constant $C$ such that $|A|^2(P) \leq C$ for $P \in \Sigma$.

**Proof.** For any $P \in \Sigma$, we fix $\rho > 0$ such that $e^{\rho} < 2$ as in Proposition 2.4 so that $B_{\rho}(P)$ is disjoint from the cut locus of $P$. We may assume $B_{\rho}(P)$ is a topological disk since by Proposition 2.2, the universal cover of $B_{\rho}(P)$ endowed with pull-back metric is also a stable translating soliton with nonnegative mean curvature. Thus using Proposition 2.4 part ii. with $\mu = e^{-\frac{6\epsilon}{\pi}}$, the conditions of Proposition 2.7 are satisfied for $\tau = \mu^2\rho$. We can choose $\sigma = \tau$ and obtain $|A|^2(P) \leq \tau^{-2}$. \hfill \Box

3. **Proof of Theorem 1.1**

We restate for the readers convenience our main result.

**Theorem 3.1.** Let $\Sigma \subset \mathbb{R}^3$ be a complete immersed two-sided translating soliton for the mean curvature flow with nonnegative mean curvature. Then $\Sigma$ is convex.
Proof. Without loss of generality, we assume Σ satisfies
\[ H = \langle N, e_3 \rangle > 0. \]
Let
\[ f(x_1, x_2) = \frac{x_1 + x_2}{2} + \left[ \left( \frac{x_1 - x_2}{2} \right)^2 \right]^{1/2}, \]
\[ \phi(r) = \begin{cases} r^4 e^{-1/r^2} & \text{if } r < 0 \\ 0 & \text{if } r \geq 0 \end{cases}, \]
and
\[ g(z) = f(z) \sum_{i=1}^2 \phi \left( \frac{z_i}{f(z)} \right). \]
It’s easy to see that f and g are smooth when \( z_1 \neq z_2 \). Now denote
\[ G(A) = g(\kappa(A)) \text{ and } F(A) = f(\kappa(A)), \]
where A is a 2 × 2 symmetric matrix and \( \kappa(A) \) are the eigenvalues of A. Now let \( A = (h_{ij}) \) be the second fundamental form of Σ. If we order the principle curvatures \( \kappa_1 \geq \kappa_2 \) of Σ, then \( \frac{G}{F} = \phi(\frac{\kappa_2}{\kappa_1}) \geq 0 \) is smooth when \( \kappa_1 > 0 > \kappa_2 \). Since \( G/F \leq 1 \), \( G/F \) achieves its maximum either at an interior point or “at infinity”.

Lemma 3.2. On \( \Sigma \cap \{ \kappa_1 > 0 > \kappa_2 \} \),
\[ \Delta^\Sigma \left( \frac{G}{F} \right) + 2 \left( \frac{\nabla G}{F}, \nabla \left( \frac{G}{F} \right) \right) + \left( \frac{\nabla G}{F}, e_3 \right) \]
\[ = - \frac{G^{ij} h_{ij} |A|^2}{F} + \frac{GF^{ij} h_{ij} |A|^2}{F^2} + \left( \frac{G_{pq,rs}}{F} - \frac{GF_{pq,rs}}{F^2} \right) h_{pqk} h_{rsk}, \]
where \( G^{ij} = \frac{\partial G}{\partial a_{ij}}, F^{ij} = \frac{\partial F}{\partial a_{ij}}, G_{pq,rs} = \frac{\partial^2 G}{\partial a_{pq} \partial a_{rs}}, F_{pq,rs} = \frac{\partial^2 F}{\partial a_{pq} \partial a_{rs}}. \)

Proof. Let \( \tau_1, \tau_2 \) be a local orthonormal frame on Σ. Then using Lemma 2.1
\[ \nabla_k \left( \frac{G}{F} \right) = \left( \frac{G}{F} \right)^{pq} h_{pqk} = \left( \frac{F G_{pq} - GF_{pq}}{F^2} \right) h_{pqk} \]
\[ \Delta^\Sigma \left( \frac{G}{F} \right) = \left( \frac{G}{F} \right)^{pq} \Delta h_{pq} + \left( \frac{G}{F} \right)_{pq,rs} h_{pqk} h_{rsk} \]
\[ = - |A|^2 \left( \frac{FG^{ij} h_{ij} - GF^{ij} h_{ij}}{F^2} \right) - \langle \nabla \left( \frac{G}{F} \right), e_3 \rangle + \left( \frac{G}{F} \right)_{pq,rs} h_{pqk} h_{rsk}. \]
But

\[(3.6) \quad (G_F^{pq,rs} h_{pqk} h_{rsk} = \left( \frac{G_F^{pq,rs}}{F} - \frac{GF^{pq,rs}}{F^2} \right) h_{pqk} h_{rsk} - 2 < \nabla \left( \frac{G}{F} \right), \nabla F >),\]

and together (3.5), (3.6) give (3.4).

We next compute the last term in (3.4). We use the notation $g^p = \partial g^p / \partial \kappa_p$, $g^{pq} = \partial^2 g^{pq} / \partial \kappa_p \partial \kappa_q$ and similarly for $f$. As is now well-known (see for example [2])

\[(3.7) \quad G^{pq,rs} h_{pqk} h_{rsk} = g^{pq} h_{ppk} h_{qqk} + 2 g^2 - 2 g^1 \kappa^2 - 2 \kappa^1 h_{12k},\]

where

\[(3.8) \quad g^{pq} = f^{pq} \sum_{i=1}^2 \left[ \phi \left( \frac{z_i}{f} \right) - \frac{z_i}{f} \phi \left( \frac{z_i}{f} \right) \right] + \frac{1}{f} \sum_{i=1}^2 \phi \left( \frac{z_i}{f} \right) \left( \delta^p_i - \frac{z_i}{f} f^p \right) \left( \delta^q_i - \frac{z_i}{f} f^q \right).\]

It follows that

\[(3.9) \quad FG^{pq,rs} - GF^{pq,rs} \]

\[= (fg^{pq} - gf^{pq}) + 2 \left\{ f \frac{g^2 - g^1}{\kappa_2 - \kappa_1} - g \frac{f^2 - f^1}{\kappa_2 - \kappa_1} \right\} \]

\[= I + II.\]

We proceed to calculate the terms $I$ and $II$.

\[(3.10) \quad I = f^{pq} \left[ g - \sum_{i=1}^2 z_i \phi \left( \frac{z_i}{f} \right) \right] + \sum_{i=1}^2 \phi \left( \frac{z_i}{f} \right) \left( \delta^p_i - \frac{z_i}{f} f^p \right) \left( \delta^q_i - \frac{z_i}{f} f^q \right) - gf^{pq} \]

\[= -f^{pq} \sum_{i=1}^2 z_i \phi \left( \frac{z_i}{f} \right) + \sum_{i=1}^2 \phi \left( \frac{z_i}{f} \right) \left( \delta^p_i - \frac{z_i}{f} f^p \right) \left( \delta^q_i - \frac{z_i}{f} f^q \right),\]

\[(3.11) \quad g^2 - g^1 = \dot{\phi} \left( \frac{z_2}{f} \right) + f^2 \sum_{i=1}^2 \left[ \phi \left( \frac{z_i}{f} \right) - \frac{z_i}{f} \phi \left( \frac{z_i}{f} \right) \right] \]

\[- \dot{\phi} \left( \frac{z_1}{f} \right) - f^1 \sum_{i=1}^2 \left[ \phi \left( \frac{z_i}{f} \right) - \frac{z_i}{f} \phi \left( \frac{z_i}{f} \right) \right].\]
and

\[
\frac{\kappa_2 - \kappa_1}{2} II = f(g^2 - g^1) - g(f^2 - f^1)
\]

\[
= f \left[ \dot{f} \left( \frac{z_2}{f} \right) - \dot{f} \left( \frac{z_1}{f} \right) \right] + f^2 \left[ g - \sum_{i=1}^{2} z_i \dot{f} \left( \frac{z_i}{f} \right) \right] - f^1 \left[ g - \sum_{i=1}^{2} z_i \dot{f} \left( \frac{z_i}{f} \right) \right] - g \left( f^2 - f^1 \right)
\]

(3.12)

\[
= f \left[ \dot{f} \left( \frac{z_2}{f} \right) - \dot{f} \left( \frac{z_1}{f} \right) \right] + \sum_{i=1}^{2} z_i \dot{f} \left( \frac{z_i}{f} \right) (f^1 - f^2).
\]

Assume \(\kappa_1 > 0 > \kappa_2\); then

(3.13)

\[
\Delta^\Sigma \left( \frac{G}{F} \right) + 2 \left\langle \nabla F, \nabla \left( \frac{G}{F} \right) \right\rangle + \left\langle \nabla \left( \frac{G}{F} \right), e_3 \right\rangle = \left( \frac{G^{pq,rs}}{F^2} - \frac{GF^{pq,rs}}{F^2} \right) h_{pqk} h_{rsk}
\]

\[
= \frac{1}{\kappa_1^2} \dot{\phi} \left( \frac{\kappa_2}{\kappa_1} \right) \left( \delta_2^p - \frac{\kappa_2}{\kappa_1} f^p \right) \left( \delta_2^q - \frac{\kappa_2}{\kappa_1} f^q \right) h_{pqk} h_{rsk} + \frac{2}{\kappa_1^2} \dot{\phi} \left( \frac{\kappa_2}{\kappa_1} \right) \left( \frac{\kappa_1 + \kappa_2}{\kappa_2 - \kappa_1} \right) h_{12k}^2 \geq 0.
\]

Here we used \(f^{pq} = 0\), \(\dot{\phi} \left( \frac{\kappa_2}{\kappa_1} \right) = 0\), and \(f^2 = 0\) when \(\kappa_1 > 0 > \kappa_2\). It follows that if \(G/F\) achieves its maximum at an interior point, then by the strong maximum principle we have \(G/F \equiv \text{constant}\). If \(\kappa_2/\kappa_1 \neq 0\), then \(\varphi := \log \frac{|A|^2}{|H|^2}\) is constant and so

(3.14)

\[
0 = \nabla \varphi = \frac{\nabla |A|^2}{|A|^2} - 2 \frac{\nabla H}{H}
\]

\[
0 = \Delta^\Sigma \varphi + \left\langle \nabla \varphi, e_3 \right\rangle
\]

\[
= 2 \frac{|\nabla |A|^2|^2}{|A|^2} - \frac{|\nabla |A|^2|^2}{|A|^4} + 2 \frac{|\nabla H|^2}{H^2}
\]

\[
= 2 \frac{|A|^2 (|\nabla |A|^2|^2 - |\nabla |A|^2)^2}{|A|^2}.
\]

Hence \(|\nabla |A|^2|^2 = |\nabla |A|^2|^2\) and so \(h_{12k} = 0\), \(k = 1, 2\). By the Codazzi equations, \(h_{112} = h_{221} = 0\). Since \(h_{22} = r_0 h_{11}\), we deduce \(\nabla A = 0\). Thus \(M\) is a complete surface with constant mean curvature. Since \(M\) satisfies \(H = \langle N, e_3 \rangle\), we conclude that \(M\) is a plane, a contradiction. Therefore in this case we must have \(G/F \equiv 0\), and thus \(\kappa_2 \geq 0\).

If \(G/F\) achieves its maximum at infinity, by Theorem 2.8 we may apply the Omori-Yau maximum principle and conclude that there exists a sequence \(P_n\) tending to infinity with
\( r_n := \frac{\kappa_2}{\kappa_1}(P_n) \to r_0 \), where \(-1 \leq r_0 < 0\). Introduce a local orthonormal frame \( \tau_1, \tau_2 \) in a neighborhood of \( P_n \) which diagonalizes \((h_{ij}(P_n))\). Then we have at \( P_n \):

\[
\left(1 + \frac{1}{n}\right) \geq \frac{\dot{\phi}(r_n)}{\kappa_1} \left[ \frac{r_n h_{11k}}{\kappa_1} - \frac{h_{22k}}{\kappa_1} \right]^2 + \frac{2}{\kappa_1^2} \phi(r_n) \frac{1 + r_n}{r_n - 1} h_{12k}^2 - 2 \left\langle \nabla F, \nabla \left( \frac{G}{F} \right) \right\rangle
\]

\[= \dot{\phi}(r_n) \left[ \frac{r_n h_{11k}}{\kappa_1} - \frac{h_{22k}}{\kappa_1} \right]^2 + \frac{2}{\kappa_1^2} \phi(r_n) \frac{1 + r_n}{r_n - 1} h_{12k}^2 - 2 \phi(r_n) \left\langle \frac{h_{11k}}{h_{11}}, \frac{h_{22k}}{h_{11}} - r_n \frac{h_{11k}}{h_{11}} \right\rangle\]

and

\[
C_{n,k} := \frac{h_{22k}}{h_{11}} - r_n \frac{h_{11k}}{h_{11}} \to 0 \text{ as } n \to \infty.
\]

Note that

\[
\tilde{C}_{n,k} := \frac{\nabla_k H}{\kappa_1} = -\kappa_1 \langle \tau_k, e_3 \rangle
\]

\[
= \frac{h_{22k}}{h_{11}} - r_n \frac{h_{11k}}{h_{11}} + (1 + r_n) \frac{h_{11k}}{h_{11}} = C_{n,k} + (1 + r_n) \frac{h_{11k}}{h_{11}}.
\]

From (3.16) we have,

\[
\frac{h_{22k}}{\kappa_1} = -|r_n| \frac{h_{11k}}{\kappa_1} + C_{n,k}, \ k = 1, 2
\]

and

\[
\frac{h_{11k} h_{22k}}{\kappa_1^2} = -|r_n| \left( \frac{h_{11k}}{\kappa_1} \right)^2 + C_{n,k} \frac{h_{11k}}{\kappa_1}.
\]

Claim: \((1 + r_n) \left| \frac{h_{11k}}{h_{11}} \right| \to 0, \ k = 1, 2.\)

If not, we can choose a subsequence, still denoted by \( \{P_n\} \), so that for \( n \geq N_0 \)

\[
(1 + r_n) \left| \frac{h_{11k}}{\kappa_1} \right| (P_n) \geq \varepsilon_0, \ (1 + r_n) \left| \frac{h_{22k}}{\kappa_1} \right| (P_n) \geq \varepsilon_0.
\]
Then from (3.15) we have

\[
\frac{1}{n} \geq \dot{\phi} \sum C_{n,k}^2 - 2\dot{\phi} \sum C_{n,k} \frac{h_{11}^{11}}{\kappa_1} - \frac{2\dot{\phi}}{1 + |r_n|} (1 + r_n) \left( \frac{h_{11}^{11}}{\kappa_1^2} + \frac{h_{22}^{21}}{\kappa_1^2} \right)
\]

\[
= \dot{\phi} \sum C_{n,k}^2 - 2\dot{\phi} \left( C_{n,1} \left( - \frac{1}{|r_n|} \frac{h_{22}^{21}}{\kappa_1} + \frac{C_{n,1}}{|r_n|} \right) + \frac{h_{11}^{11}}{\kappa_1} + \frac{C_{n,2}}{|r_n|} \left( \frac{h_{12}^{11}}{\kappa_1} + \frac{C_{n,1}}{|r_n|} \right) \right)
\]

\[
= \dot{\phi} \sum C_{n,k}^2 - 2\dot{\phi} \frac{C_{n,1}}{|r_n|}
\]

\[
- 2\dot{\phi} \left\{ \left( \frac{1 + r_n}{1 + |r_n|} \frac{h_{12}^{11}}{\kappa_1^2} + C_{n,2} \frac{h_{11}^{11}}{\kappa_1} \right) + \left( \frac{1 + r_n}{1 + |r_n|} \frac{h_{22}^{21}}{\kappa_1^2} - C_{n,1} \frac{h_{22}^{21}}{|r_n|} \right) \right\}
\]

\[
\geq - \frac{2\dot{\phi}}{1 + |r_n|} \left( \frac{h_{11}^{11}}{\kappa_1} \right) \left( (1 + r_n) \frac{h_{11}^{11}}{\kappa_1} - C_{n,2} (1 + |r_n|) \right)
\]

\[
+ \frac{h_{22}^{21}}{\kappa_1} \left( (1 + r_n) \frac{h_{22}^{21}}{\kappa_1} - C_{n,1} \frac{h_{22}^{21}}{|r_n|} (1 + |r_n|) \right)
\]

\[
\geq -2 \frac{\dot{\phi}}{1 + |r_n|} \frac{\varepsilon_0}{2} \left( \frac{h_{11}^{11}}{\kappa_1} + \frac{h_{22}^{21}}{\kappa_1} \right),
\]

which leads to a contradiction for \( n \geq N_0 \) by (3.20). Thus the claim is proven and so \( \tilde{C}_{n,k} \to 0 \). Therefore \( N(P_n) \) converges to \( e_3 \) and so \( H(P_n) \to 1 \).

Now let \( \Sigma_n = \Sigma - P_n \) be the surface obtained from \( \Sigma \) by translation of \( P_n \) to the origin. Since \( \Sigma \) has bounded principle curvatures, so do the \( \Sigma_n \). Choosing a subsequence which we still denote by \( \Sigma_n \), the \( \Sigma_n \) converge smoothly to \( \Sigma_\infty \). Thus \( \Sigma_\infty \) is a translating soliton which satisfies \( H = \langle N, e_3 \rangle \), and \( H(0) = 1 \). Moreover, we have

\[
\inf_{x \in \Sigma_\infty} \frac{\kappa_2}{\kappa_1} = \frac{\kappa_2}{\kappa_1}(0).
\]

As before we conclude that \( G/F = \text{constant} \), and \( \Sigma_\infty \) has constant mean curvature one, which is impossible. Therefore \( \Sigma \) is convex. \( \square \)

4. PROOF OF THEOREM 1.4

In this section we give the proof of

**Theorem 4.1.** Let \( \Sigma \subset \mathbb{R}^3 \) be a complete immersed two-sided translating soliton for the mean curvature flow with positive mean curvature and suppose that \( H(P) \to 0 \) as \( P \in \Sigma \) tends to infinity. Then \( \Sigma \) is after translation the axisymmetric bowl soliton.
Proof. By Corollaries 1.2, 1.3 we may suppose for contradiction that \( \Sigma = \text{graph}(u) \) projects onto the strip \( |x_1| < R \). Consider for any \( A \), the convex curve \( \gamma^A(x_1) = (x_1, A, u(x_1, A) : -R \leq x_1 \leq R) \). Since \( u(x_1, A) \to +\infty \) as \( x_1 \to \pm R \), there is a smallest value \( x_1 = x_1(A) \) so that \( u_{x_1}(x_1(A), A) = 0 \). Since \( \Sigma \) is not a grim cylinder we may assume by a suitable change of coordinates that \( u_{x_2}(x_1(0), 0) \geq \delta > 0 \). We normalize \( u(x_1(0), 0) = 0 \); then by convexity of \( u \),

\[
\begin{align*}
  u(x_1(A), A) &\geq u(x_1(0), 0) + Au_{x_2}(x_1(0), 0) \geq A\delta, \\
  0 = u(x_1(0), 0) &\geq u(x_1(A), A) - Au_{x_2}(x_1(A), A) \geq A(\delta - u_{x_2}(x_1(A), A)),
\end{align*}
\]

which implies \( u_{x_2}(x_1(A), A) \geq \delta \). By the assumption that \( H(P) \to 0 \) as \( P \in \Sigma \) tends to infinity, we have that \( |Du(x_1(A), A)| = |u_{x_2}(x_1(A), A)| = u_{x_2}(x_1(A), A) \to \infty \) as \( A \to \infty \). Therefore

\[
(4.2) \quad u(x_1, x_2) \geq u(x_1(A), A) + (x_2 - A)u_{x_2}(x_1(A), A) \geq A\delta + (x_2 - A)u_{x_2}(x_1(A), A),
\]

and so choosing \( x_2 = B, A = \frac{B}{2} \),

\[
(4.3) \quad \lim_{B \to \infty} \frac{u(x_1, B)}{B} \geq \frac{\delta}{2} + \frac{1}{2} \lim_{B \to \infty} u_{x_2}(x_1(B), B) = +\infty.
\]

Hence \( u \) grows superlinearly as \( x_2 \to \infty \).

We now compare \( \Sigma \) with a tilted cylinder of radius \( R \). Consider the parametrized family of graphs

\[
x_3 = v^t(x_1, x_2) := -\sqrt{1 + t^2} \sqrt{R^2 - x_1^2 + t(x_2 - A)}, \quad |x_1| \leq R, x_2 \geq A
\]

of constant mean curvature \( H = \frac{1}{R} \) with respect to upward normal direction. Since \( v^t(x_1, x_2) \leq t(x_2 - A) \), for any choice of \( t \geq 0 \), \( u > v^t \) for \( x_2 \) sufficiently large by (4.3). Also, \( u > v^t \) for \( |x_1| = R \) and for \( x_2 = A \). For \( t \leq \delta, u > v^t \) in \( x_2 \geq A, |x_1| \leq R \) by (4.2). Note that \( \lim_{t \to \infty} v^t(x_1, 3A) \geq \lim_{t \to \infty} (2tA - \sqrt{1 + t^2} R) = +\infty \) for \( A > R \). We can therefore increase \( t \) until there is a first contact of \( \Sigma = \text{graph}(u) \) and \( \text{graph}(v^t) \), which must occur over an interior point of the half-strip \( \{(x_1, x_2), |x_1| < R, x_2 > A\} \). This gives a \( P := (x_1, x_2, u(x_1, x_2)) \in \Sigma, x_2 > A \) with \( H(P) \geq \frac{1}{R} \). Since \( A \) is arbitrary we have a contradiction. \( \square \)
5. ASYMPTOTIC BEHAVIOR OF COMPLETE LOCALLY STRICTLY CONVEX TRANSLATING SOLITONS

In this section we study the asymptotic behavior of complete locally strictly convex translating solitons.

**Lemma 5.1.** Let \( \Sigma = \text{graph}(u) \) be a complete mean convex translating soliton in \( \mathbb{R}^3 \) and suppose that the smallest principle curvature \( \kappa_2 \) vanishes at a point of \( \Sigma \). Then \( \kappa_2 \equiv 0 \) everywhere and after translation, \( \Sigma \) is grim cylinder of the form \( \Sigma = \text{graph}(u^\lambda) \) defined in a strip \( \{ (x_1, x_2) : |x_1| < R \} \) where

\[
 u^\lambda(x_1, x_2) := \lambda^2 \log \sec \left( \frac{x_1}{\lambda} \right) \pm \sqrt{\lambda^2 - 1} \, x_2, \quad R = \frac{\pi}{2} \lambda, \ \lambda \geq 1.
\]

In particular if \( \Sigma \) contains a line, then \( \Sigma \) is a grim cylinder of the above form.

**Proof.** If we choose an orthonormal frame \( \tau_1, \tau_2 \) so that \( \kappa_2(P) = h_{22}(P) \), then \( \kappa_2 \equiv 0 < \kappa_1 \) on \( \Sigma \) by Lemma 2.1 part ii. and the maximum principle. Thus the Gauss curvature \( K^\Sigma \equiv 0 \) and so \( \Sigma \) has a representation (see for example [15]) \( \Sigma = \text{graph}(z) \) where \( z(x_1, x_2) = \eta(x_1) + \alpha x_2 \) for a constant \( \alpha \) and a scalar function \( \eta \) defined in a simply connected region containing the projection of \( P \) on the \( x_1, x_2 \) plane. Therefore

\[
(1 + \alpha^2)\eta'' = 1 + \alpha^2 + \eta^2.
\]

Set \( \tilde{\eta}(x_1) = \lambda^{-2} \eta(\lambda x_1) \), where \( \lambda^2 = 1 + \alpha^2 \). Then

\[
\tilde{\eta}'' = 1 + \tilde{\eta}^2
\]

and so (up to translation of coordinates and an additive constant)

\[
\tilde{\eta}(x_1) = \log \sec x_1,
\]

which proves the lemma. \( \square \)

We have the following Harnack inequality for the mean curvature \( H \) on \( \Sigma \) (compare Hamilton [14], Corollary 1.2).

**Lemma 5.2.** For any two points \( P_1, P_2 \in \Sigma \),

\[
 H(P_2) \geq e^{-d^2(P_1, P_2)} H(P_1).
\]

**Proof.** Since \( H = \langle N, e_3 \rangle, \nabla_k H = -\kappa_k < \tau_k, e_3 \rangle \) so that

\[
 |\nabla H|^2 \leq |A|^2 = H^2 - 2K \leq H^2.
\]

Therefore, \( |\nabla \log H| \leq 1 \) and (5.4) follows. \( \square \)
Lemma 5.3. Let \( \Sigma = \text{graph}(u) \) be a complete mean convex translating soliton in \( \mathbb{R}^3 \) defined in the strip \( \{(x_1, x_2) : |x_1| < R\} \). Then
\[
H(x_1, x_2) := H((x_1, x_2, u(x_1, x_2))) \leq R - |x_1|.
\]

Proof. We use that \( \sum u_i^2 \leq |A|^2 \leq H^2 = \frac{1}{W^2} \) where \( W^2 = 1 + |\nabla u|^2 \). Then \( |DW| \leq W^2 \) or \( |DH| = |D(\frac{1}{W})| \leq 1 \). By the convexity of \( u \) and the fact that \( u(x_1, x_2) \to \infty \) as \( R - |x_1| \to 0, x_2 \) fixed, we see that \( H(x_1, x_2) \to 0 \) as \( R - |x_1| \to 0, x_2 \) fixed. Hence \( H(x_1, x_2) \leq \min (R - x_1, x_1 + R) = R - |x_1| \). \( \square \)

Lemma 5.4. Let \( \Sigma = \text{graph}(u) \) be a convex translating soliton in \( \mathbb{R}^3 \) defined in the strip \( \{(x_1, x_2) : |x_1| < R\} \). Then
\[
\frac{d}{dx_i} \arctan u_{x_i} \leq 1, \quad i = 1, 2,
\]
\[
\frac{d}{dx_2} \sqrt{1 + (u_{x_1})^2} \leq |u_{x_1}| \sqrt{1 + (u_{x_2})^2}.
\]

Proof. Since \( u \) is a convex graphical solution to the translating soliton equation,
\[
(1 + u_{x_2}^2)u_{x_1x_1} + (1 + u_{x_1}^2)u_{x_2x_2} = 2u_{x_1}u_{x_2}u_{x_1x_2} + (1 + u_{x_1}^2 + u_{x_2}^2)
\]
\[
\leq 2|u_{x_1}| |u_{x_2}| \sqrt{u_{x_1x_1}u_{x_2x_2} + (1 + u_{x_1}^2 + u_{x_2}^2)}
\]
\[
\leq (1 + u_{x_1}^2)u_{x_2x_2} + \frac{u_{x_1}^2 u_{x_2}^2}{(1 + u_{x_1}^2)} u_{x_1x_1} + (1 + u_{x_1}^2 + u_{x_2}^2).
\]
This implies
\[
u_{x_1x_1} \leq 1 + u_{x_1}^2 \text{ and by symmetry } u_{x_2x_2} \leq 1 + u_{x_2}^2,
\]
\[
|u_{x_1x_2}| \leq \sqrt{u_{x_1x_1}u_{x_2x_2}} \leq \sqrt{1 + u_{x_1}^2} \sqrt{1 + u_{x_2}^2},
\]
and (5.5) follows. \( \square \)

Lemma 5.5. Let \( \Sigma = \text{graph}(u) \) be a complete mean convex translating soliton in \( \mathbb{R}^3 \) defined over \( \mathbb{R}^2 \). Then \( H(P) \to 0 \) for \( P \in \Sigma \) tending to infinity.

Proof. We slightly modify the argument of Haslhofer [16]. Fix \( P_0 \in \Sigma \) and suppose there is a sequence \( P_n \in \Sigma \) tending to infinity with \( \liminf_{n \to \infty} H(P_n) > 0 \). Passing to a subsequence, we may assume \( \frac{P_n - P_0}{|P_n - P_0|} \) converges to a unit direction \( \omega \). Let \( \Sigma_n = \Sigma - P_n \) be the surface obtained from \( \Sigma \) by translation of \( P_n \) to the origin. Since \( \Sigma \) has bounded principle curvatures, so do the \( \Sigma_n \). Choosing a subsequence which we still denote by \( \Sigma_n \), the \( \Sigma_n \) converge smoothly to \( \Sigma_\infty \), a convex complete translating soliton. Moreover, \( \Sigma_\infty \)
is not a vertical plane since \( H(0) > 0 \), so must be a graph. Since the region \( K \) above \( \Sigma \) is convex and \( \frac{P_n - P_0}{|P_n - P_0|} \to \omega \), the limit \( \Sigma_\infty \) contains a line (see Lemma 3.1 of [5] for more details). Therefore by Lemma 5.1, \( \Sigma_\infty \) is a grim cylinder and thus is a graph over a strip, a contradiction. \( \square \)

**Lemma 5.6.** Let \( \Sigma = \text{graph}(u) \) be a complete locally strictly convex translating soliton defined over a strip region \( S^\Lambda := \{(x_1, x_2) : |x_1| < R := \frac{\lambda_2}{2} \} \). Then there exist sequences \( P_n = (x_1^n, x_2^n, u(x_1^n, x_2^n)), \bar{P}_n = (\bar{x}_1^n, \bar{x}_2^n, u(\bar{x}_1^n, \bar{x}_2^n)) \in \Sigma \) with \( x_2^n \to \infty, \bar{x}_2^n \to -\infty \) and \( H(P_n), H(\bar{P}_n) \geq \theta > 0 \).

**Proof.** By Theorem 1.4 there is a sequence of points \( P_n = (x_1^n, x_2^n, u(x_1^n, x_2^n)) \in \Sigma \) where (after relabeling axes if necessary) \( \liminf_{n \to \infty} H(P_n) \geq \theta > 0 \) and \( x_2^n \to +\infty \). Note that by Lemma 5.3, \( |x_1^n| \leq R - \theta \). We claim there is also a sequence \( \bar{P}_n = (\bar{x}_1^n, \bar{x}_2^n, u(\bar{x}_1^n, \bar{x}_2^n)) \in \Sigma \) with \( \bar{x}_2^n \to -\infty \) and \( H(\bar{P}_n) \geq \theta > 0 \). If not, then for \( x_2 \to -\infty, H(x_1, x_2) := H(x_1, x_2, u(x_1, x_2)) \to 0 \). For any \( B \leq 0 \) let \( x_1(B) \) be the unique value so that \( u_{x_1}(x_1(B), B) = 0 \). Since \( \Sigma \) is not a grim cylinder, we may assume by a translation of coordinates that \( u_{x_2}(x_1(0), 0) = \delta > 0 \). We normalize \( u(x(0), 0) = 0 \); then

\[
0 = u(x_1(0), 0) \geq u(x_1(B), B) - Bu_{x_2}(x_1(0), 0) = B\delta ,
\]

and

\[
0 = u(x_1(0), 0) \geq u(x_1(B), B) - Bu_{x_2}(x_1(0), 0) = B(\delta - u_{x_2}(x_1(B), B)) .
\]

Hence \( u_{x_2}(x_1(B), B) \leq \delta \). Since \( H(x_1, x_2) \to 0 \) as \( x_2 \to -\infty \), we conclude

\[
(5.8) \quad u_{x_2}(x_1(B), B) \to -\infty \text{ as } B \to -\infty .
\]

Therefore

\[
(5.9) \quad u(x_1, x_2) \geq u(x_1(B), B) + (x_2 - B)u_{x_2}(x_1(B), B) \geq B\delta + (x_2 - B)u_{x_2}(x_1(B), B)
\]

Now choose \( x_2 = \Lambda < 0 \) and \( B = \frac{\Lambda}{2} \). Then

\[
u(x_1, \Lambda) \geq \frac{\delta \Lambda}{2} + \frac{\Lambda}{2}u_{x_2}(x_1(\frac{\Lambda}{2}), \frac{\Lambda}{2}) ,
\]

hence

\[
(5.10) \quad \lim_{\Lambda \to -\infty} \frac{u(x_1, \Lambda)}{\Lambda} \leq \frac{\delta}{2} + \frac{1}{2}u_{x_2}(x_1(\frac{\Lambda}{2}), \frac{\Lambda}{2}) \to -\infty
\]

by (5.8). Thus \( u(x_1, \Lambda) \to \infty \) superlinearly as \( \Lambda \to -\infty \). We now compare \( \Sigma \) with a tilted cylinder of radius \( R \). Consider \( x_3 = v^t(x_1, x_2) := -\sqrt{1 + t^2} \sqrt{R^2 - x_1^2} + t(x_2 - B) \) in the half-strip \( S^B := \{(x_1, x_2) : |x_1| \leq R, x_2 \leq B < 0 \} \). Since \( v^t \leq t(x_2 - B) \), for any choice
of \( t \leq 0, u > v^t \) for \( x_2 \) sufficiently small (i.e. \( x_2 \) large negative) by (5.10). Also \( u > v^t \) for \( |x_1| = R \) and \( x_2 = B < 0 \), as soon as \( u(x_1, B) > 0 \). For \( t \geq -\delta \), \( u > v^t \) in \( S^B \) and since
\[
\lim_{t \to -\infty} v^t(x_1, 3B) \geq \lim_{t \to -\infty} (2Bt - \sqrt{1 + t^2} R) \to \infty ,
\]
we can decrease \( t \) until there is a first contact point \( P \in S^B \) of graph \( (v^t) \) and \( \Sigma \). At \( P \in \Sigma \), \( H(P) \geq \frac{1}{W} \), a contradiction.

□

Lemma 5.7. Let \( \Sigma = \text{graph}(u) \) be a complete locally strictly convex translating soliton defined over a strip \( S_R := \{(x_1, x_2) : |x_1| < R\} \) with \( \max_{|x_1| \leq R-\delta} W(x_1, 0) \leq C_0 \). If \( W := \sqrt{1 + |\nabla u|^2} \) satisfies \( \sup_{x_2 \geq 0} W(0, x_2) \leq C_1 \), then
\[
W(x_1, x_2) \leq 2 \left( \frac{R - \delta}{\delta} \right) \max(C_0, C_1) \text{ in the half-strip } S^+_{R-\frac{3}{2}\delta} := S_{R-\frac{3}{2}\delta} \cap \{x_2 \geq 0\} .
\]

Proof. We give the proof for the right half of \( S^+_{R-\frac{3}{2}\delta} \) (where \( 0 \leq x_1 \leq R - \frac{3}{2}\delta \)); the proof for the left half of \( S_{R-\frac{3}{2}\delta} \) is analogous.

For an \( n \)-dimensional hypersurface \( \Sigma = \text{graph}(u) \),
\[
\Delta^f H := \Delta^\Sigma H + \langle \nabla^\Sigma H, e_{n+1} \rangle = a^{ij} H_{x_i x_j} ,
\]
where \( a^{ij} := \delta_{ij} - \frac{u_i u_j}{W^2} \). Since \( H = 1/W \), we obtain from Lemma 2.1 part iii.,
\[
(5.11) \quad \mathcal{L} W := (a^{ij} \partial_i \partial_j - \frac{2}{W} a^{ij} W_i \partial_j)W = \frac{|A|^2}{W^3} \geq \frac{1}{2W}
\]
for \( n = 2 \). For \( N > 1 \) fixed and large, set \( \eta = \eta^N := (1 - \frac{x_1}{R-\delta} - \frac{x_2}{N})_+ \) in the domain \( D = \{0 < x_1 < R - \delta, x_2 > 0\} \). Since \( \eta \) is linear in \( D \cap \{\eta > 0\} \) and
\[
\mathcal{L}(\eta W) = \eta \mathcal{L} W + W a^{ij} \eta_{ij} \geq \frac{\eta}{2W} ,
\]
\( \eta W \) cannot have an interior maximum in \( D \cap \{\eta > 0\} \). Thus \( \eta W \) achieves its maximum when \( x_1 = 0 \) or \( x_2 = 0 \). Restricting to \( D' := \{0 \leq x_1 \leq R - \frac{3\delta}{2}, x_2 \geq 0\} \) and letting \( N \to \infty \) gives
\[
\frac{\delta}{2(R - \delta)} W \leq \eta W \leq \max(C_0, C_1) \text{ in } D' .
\]
This completes the proof. □

We now analyze the asymptotic behavior of complete locally strictly convex translating solitons \( \Sigma = \text{graph}(u) \) in \( \mathbb{R}^3 \) that are defined over the strip region \( S^\lambda \).
Theorem 5.8. Let $\Sigma = \text{graph}(u)$ be a complete locally strictly convex translating soliton defined over a strip region $S^\lambda := \{(x_1, x_2) : |x_1| < R := \lambda \frac{\pi}{2}, \lambda \geq 1\}$. Then (after possibly relabeling the $e_2$ direction)

i. For $\lambda \leq 1$ there is no locally strictly convex solution in $S^\lambda$.

ii. $\lim_{x_2 \to +\infty} u_{x_2}(x_1, x_2) = L := \sqrt{\lambda^2 - 1}$, $\lambda > 1$.

iii. $\lim_{x_2 \to -\infty} u_{x_2}(x_1, x_2) = -L$.

iv. \begin{align*}
\lim_{A \to \pm\infty} (u(x_1, x_2 + A) - u(0, A)) &= u^\lambda(x_1, x_2) \\
\lim_{A \to \pm\infty} u_{x_1}(x_1, A) &= \lambda \tan \frac{x_1}{\lambda}.
\end{align*} 

(5.12)

The above limits hold uniformly on $S^\varepsilon = \{(x_1, x_2) \in S^\lambda : |x_1| \leq R - \varepsilon\}$.

v. For $P = (x_1, x_2, u(x_1, x_2)) \in \Sigma$, $(x_1, x_2) \in S^\varepsilon$,

\begin{equation}
H(P) \geq \theta(\varepsilon).
\end{equation} 

(5.13)

Proof. By Lemma 5.6 there is a sequence of points $P_n \in \Sigma$ where (after relabeling axes if necessary) $\liminf_{n \to \infty} H(P_n) \geq \theta > 0$ and $x_2^n \to +\infty$. Note that by Lemma 5.3, $|x_1^n| \leq R - \theta$. Arguing as in Lemma 5.5, $\Sigma_n := \Sigma - P_n$ converge smoothly to $\Sigma_\infty$, a complete convex translating soliton defined over a strip $S'^\lambda - (x_1^\infty, 0)$ passing through the origin. Note that to begin with we can only assert that $\lambda' \leq \lambda$. By Lemma 5.1, $\lambda' > 1$ and $u(y_1 + x_1^n, y_2 + x_2^n) - u(x_1^n, x_2^n)$ converges locally smoothly to

\begin{equation}
(\lambda')^2 \log \sec \left( \frac{y_1 + x_1^\infty}{\lambda'} \right) + \sqrt{(\lambda')^2 - 1} y_2 - (\lambda')^2 \log \sec \frac{x_1^\infty}{\lambda'}
\end{equation}

as $n \to \infty$ for $|y_1 + x_1^\infty| < R' := \frac{\pi}{2} \lambda'$. In particular,

\begin{align*}
\ lim_{n \to \infty} u_{x_1}(y_1 + x_1^n, y_2 + x_2^n) &= \lambda' \tan \frac{y_1 + x_1^\infty}{\lambda'} , \\
\lim_{n \to \infty} u_{x_2}(y_1 + x_1^n, y_2 + x_2^n) &= L' := \sqrt{(\lambda')^2 - 1}.
\end{align*} 

(5.14)

Using Lemma 5.4 we see that

\begin{equation}
|\arctan u_{x_1}(y_1 + o(1) + x_1^\infty, y_2 + x_2^n) - \arctan u_{x_1}(y_1 + x_1^n, y_2 + x_2^n)|
\end{equation}

\begin{equation}
\leq |x_1^n - x_1^\infty + o(1)| \to 0 \text{ as } n \to \infty, \text{ hence by (5.14) i.}
\end{equation} 

\begin{equation}
\lim_{n \to \infty} u_{x_1}(y_1 + o(1) + x_1^\infty, y_2 + x_2^n) = \lambda' \tan \frac{y_1 + x_1^\infty}{\lambda'}.
\end{equation}
Similarly using Lemma 5.4 and (5.15),
\[
|\arctan u_{x_2}(y_1 + x_1^\infty, y_2 + x_2^n) - \arctan u_{x_2}(y_1 + x_1^n, y_2 + x_2^n)| \\
\leq \frac{\sqrt{1 + u_{x_2}^2} (y_1 + o(1) + x_1^\infty, y_2 + x_2^n) |x_1^n - x_1^\infty|}{\sqrt{1 + u_{x_2}^2} y_1 + o(1) + x_1^\infty, y_2 + x_2^n)} \to 0 \text{ as } n \to \infty,
\]
(5.16)

(so that by (5.14) ii.,) \( \lim_{n \to \infty} u_{x_2}(y_1 + x_1^n, y_2 + x_2^n) = L' := \sqrt{(\lambda')^2 - 1} \).

Setting \( y_1 = x_1 - x_1^\infty, y_2 = x_2 \), it follows that
\[
i. \lim_{n \to \infty} (u(x_1, x_2 + x_2^n) - u(x_1^\infty, x_2^n)) = u'(x_1, x_2) = (\lambda')^2 \log \sec \frac{x_1^\infty}{\lambda'}
\]
(5.17)

\[
ii. \lim_{n \to \infty} u_{x_1}(x_1, x_2 + x_2^n) = \lambda' \tan \frac{x_1}{\lambda'}
\]
\[
iii. \lim_{n \to \infty} u_{x_2}(x_1, x_2 + x_2^n) = L'
\]

for \( |x_1| < \lambda' \).

From (5.17) iii. we conclude that \( \limsup_{x_2 \to \infty} u_{x_2}(x_1, x_2) \leq L' \). But \( u_{x_2}(x_1, x_2) \leq u_{x_2}(x_1, x_2 + x_2^n) \) for \( n \) large so
\[
\lim_{x_2 \to \infty} u_{x_2}(x_1, x_2) = L' \leq L, |x_1| < \lambda'.
\]

In exactly the same way, we may prove
\[
\lim_{x_2 \to -\infty} u_{x_2}(x_1, x_2) = L'' \leq L, |x_1| < \lambda''.
\]

Note that by (5.18), (5.19) for \( x_2 = A, x_1 = x_1(A) \) (recall \( u_{x_1}(x_1(A), A) = 0 \),
\( H((x_1(A), A, u(x_1(A), A)) \geq \frac{1}{\sqrt{1 + L^2}} \). Hence we may choose \( x_2^n \to \infty \) arbitrary and \( x_1^n = x_1(x_2^n) \). From (5.14) i. with \( y_1 = y_2 = 0 \), we conclude \( x_1^\infty = 0 \). Since the choice of \( x_2^n \to \infty \) is arbitrary, it follows from (5.17) ii. (with \( x_1 = x_2 = 0 \)) that
\[
\lim_{x_2 \to \infty} u_{x_1}(0, x_2) = 0,
\]
and therefore (by (5.18))
\[
\lim_{x_2 \to \infty} W(0, x_2) = \lambda',
\]
where \( W := \sqrt{1 + |Du|^2} \).

We can now prove that there is no drop of width in the strip of convergence, i.e \( \lambda' = \lambda \)
(and similarly for \( \lambda'' = \lambda \)). Suppose for contradiction that \( R' = R - 2\delta < R \) and set
\( C_0 := \sup_{|x_1| < R - \delta} W(x_1, 0) \). By (5.21), \( C_1 := \sup_{x_2 \geq 0} W(0, x_2) < \infty \). Applying Lemma 5.7 we conclude \( W(x_1, x_2) \leq 2 \frac{R - \delta}{\delta} \max (C_0, C_1) \) in the half-strip \( \{(x_1, x_2) : |x_1| \leq \)}
$R - \frac{3}{2} \delta, x_2 \geq 0 \}$, contradicting the completeness of $\Sigma_\infty$. This completes the proof of parts i.ii., iii. and part iv. follows immediately from (5.17) i., ii. since $x_1^n = x_1(x_2^n)$, $x_1^n = 0$ and $x_2^n$ is arbitrary.

To prove part v. we will use Lemma 5.2 with

$$P_2 = (x_1, x_2, u(x_1, x_2)), P_1 = (x_1(x_2), x_2, u(x_1(x_2), x_2)), \quad H(P_1) \geq \frac{1}{\sqrt{1 + L^2}}.$$ 

Normalize $u$ by $|\nabla u(x_1(0), 0)| = 0$. We observe that

$$d^2(P_2, P_1) \leq L(x_2) := \int_{-R+\epsilon}^{R-\epsilon} \sqrt{1 + u_2^2(t, x_2)} \, dt$$

and by (5.12), $L(x_2) \leq M(\epsilon)$ for $|x_2| \geq A(\epsilon)$ sufficiently large. Therefore using Lemma 5.4 $|L'(x_2)| \leq \sqrt{1 + L^2} L(x_2)$ and so

$$d^2(P_2, P_1) \leq L(x_2) \leq e^{\sqrt{1+L^2}A(\epsilon)} M(\epsilon) \leq e^{\sqrt{1+L^2}A(\epsilon)} M(\epsilon) =: \bar{M}(\epsilon)$$

for $|x_2| \leq A(\epsilon)$. Therefore $H(P_1) \geq \theta(\epsilon) := \frac{e^{-\bar{M}(\epsilon)}}{\sqrt{1+L^2}}$, completing the proof. $\square$

An immediate application of Theorem 5.8 is the following symmetry result.

**Theorem 5.9.** Let $\Sigma = \text{graph}(u)$ be a complete locally strictly convex translating soliton defined over a strip region $S^\lambda$. Then $u(x_1, x_2) = u(-x_1, x_2)$ and $u_{x_1}(x_1, x_2) > 0$ for $x_1 > 0$.

**Proof.** We employ the method of moving planes; see for example [3]. Set $S_t = \{(x_1, x_2) \in S^\lambda : t < x_1 < R\}$ for $t \in (0, R)$. We want to show that the function

$$u_t(x_1, x_2) := u(x_1, x_2) - u(2t - x_1, x_2) > 0 \text{ in } S_t \text{ for all } t \in (0, R).$$

Once (5.23) is proven, the conclusion of Theorem 5.9 follows easily. Indeed letting $t \rightarrow 0$ in (5.23) implies by continuity

$$u(x_1, x_2) \geq u(-x_1, x_2) \text{ for } 0 \leq x_1 \leq R.$$ 

Since we may replace $x_1$ by $-x_1$ in (5.24), we have equality and thus we have symmetry in $x_1$. From (5.23) we may also conclude that $u_{x_1} \geq 0$ for $0 < x_1 < R$. Since $u_{x_1}$ satisfies an elliptic equation without zeroth order term, we have from the maximum principle either $u_{x_1} > 0$ or $u_{x_1} \equiv 0$. Since the latter possibility is impossible, Theorem 5.9 follows.

Set $u^t = u(2t - x_1, x_2)$. Since $u$ and $u^t$ both satisfy the same elliptic equation (1.4) in $S_t$, ...
the difference $v^t = u^t - u^t$ satisfies a linear elliptic equation

\begin{equation}
\sum_{i,j=1}^{2} A_{ij} v^t_{ij} + \sum_{i=1}^{2} B^k v^t_k = 0 \text{ in } S_t,
\end{equation}

and so $v^t$ cannot have an interior minimum in $S_t$. Also $v^t = 0$ for $x_1 = t$, $\lim_{x_1 \to R} v^t = +\infty$, and by Theorem 5.8 part iv.,

\begin{equation}
\lim_{x_2 \to \pm\infty} v^t = \lambda^2 \log \left\{ \frac{\sec^2 \frac{\lambda}{x_1}}{\sec \left( \frac{2t - x_1}{\lambda} \right)} \right\} \geq 0.
\end{equation}

Therefore $v_t \geq 0$ and so by the maximum principle (5.23) holds completing the proof. □

\begin{thebibliography}{9}
\bibitem{1} Steven J. Altschuler and Lang F. Wu, \textit{Translating surfaces of the non-parametric mean curvature flow with prescribed contact angle}, Calc. Var. Partial Differential Equations 2 (1994), 101–111.
\bibitem{2} Ben Andrews, \textit{Contraction of convex hypersurfaces in Euclidean space}, Calc. Var. PDE 2 (1994), 151-171.
\bibitem{3} Henri Berestycki, Luis A. Caffarelli and Louis Nirenberg, \textit{Inequalities for second-order elliptic equations with applications to unbounded domains I}, Duke Math. J. 81 (1996), 467–494.
\bibitem{4} Baojun Bian and Pengfei Guan, \textit{A microscopic convexity principle for nonlinear partial differential equations}, Invent. Math. 177 (2009), 30–335.
\bibitem{5} Theodora Bourni and Mat Langford, \textit{Type-II singularities of two-convex immersed mean curvature flow}, Geometric Flows 2 (2016), 1–17.
\bibitem{6} Theodora Bourni, Mat Langford and Giuseppe Tinaglia, On the existence of translating solitons of mean curvature flow in slabs, preprint ArXiv .
\bibitem{7} Hyeong I. Choi and Richard Schoen, \textit{The space of minimal embeddings of a surface into a three-dimensional manifold of positive Ricci curvature}, Invent. Math. 81 (1985) 387–394.
\bibitem{8} Julie Clutterbuck, Oliver C. Schnürer and Felix Schulze, \textit{Stability of translating solutions to the mean curvature flow}, Calc. Var. Partial Differential Equations 29 (2007), 281–293.
\bibitem{9} Tobias H. Colding and William P. Minicozzi II, \textit{Estimates for parametric elliptic integrands}, International Math. Research Notices, 6 (2002), 291-297.
\bibitem{10} Tobias H. Colding and William P. Minicozzi II, \textit{A course in minimal surfaces} Graduate studies in Mathematics v. 121, American Mathematical Society, Providence, R. I.
\bibitem{11} Juan Dávila, Manuel Del Pino and Xuan Hien Nguyen, \textit{Finite topology self translating surfaces for the mean curvature flow in }$\mathbb{R}^3$, Preprint, arXiv:1501.03867
\bibitem{12} Doris Fischer-Colbrie and Richard Schoen, \textit{The structure of complete stable minimal surfaces in 3-manifolds of nonnegative scalar curvature}, Comm. Pure Appl. Math. 33 (1980), 199–211.
\bibitem{13} Hoeskuldur P. Halldorsson, \textit{Helicoidal surfaces rotating/inscribing under the mean curvature flow}, Geom Dedica 162 (2013), 45–65.5
\bibitem{14} Richard Hamilton, \textit{Harnack estimate for the mean curvature flow}. J. Diff. Geom. 41 (1995), 215–226.
\bibitem{15} Philip Hartman and Louis Nirenberg, \textit{On spherical image maps whose jacobians do not change sign} Amer. J. Math 81 (1959), 901–920.
\bibitem{16} Robert Haslhofer, \textit{Uniqueness of the bowl soliton}, Geom. Topol. 19 (2015), 2393–2406.
\end{thebibliography}
[17] Robert Haslhofer and Bruce Kleiner, Mean curvature flow of mean convex hypersurfaces, CPAM 70 (2017), 511–546.
[18] David Hoffman, Tom Ilmanen, Francisco Martin and Brian White, Graphical translators for the mean curvature flow, preprint ArXiv.
[19] Gerhard Huisken, Asymptotic behavior for singularities of the mean curvature flow, J. Diff. Geom. 31 (1990), 285–299.
[20] Gerhard Huisken and Carlo Sinestrari, Convexity estimates for mean curvature flow and singularities of mean convex surfaces, Acta Math. 183 (1999), 45-70.
[21] Gerhard Huisken and Carlo Sinestrari, Convex ancient solutions of the mean curvature flow, J. Diff. Geom., 101 (2015), 267?287.
[22] Haozhao Li and Bing Wang, The extension problem of the mean curvature flow (I). Preprint (2016), arXiv:1608.02832.
[23] Francisco Martin, Andreas Savas-Halilaj and Knut Smoczyk, On the topology of translating solitons of the mean curvature flow, Calc. Var. Partial Differential Equations 54 (2015), 2853–2882.
[24] Xuan Hien Nguyen, Translating tridents Comm. PDE 34 (2009), 257–280.
[25] Xuan Hien Nguyen, Complete embedded self-translating surfaces under mean curvature flow, J. Geom. Anal. 23 (2013), 1379–1426.
[26] Xuan Hien Nguyen, Doubly periodic self-translating surfaces for the mean curvature flow, Geom. Dedicata 174 (2015), 177–185.
[27] Peter Petersen, Riemannian Geometry, Third Edition Springer, 2016.
[28] Richard Sacksteder, On hypersurfaces with no negative sectional curvatures, Amer. J. Math. 82, (1960), 609–630.
[29] Leili Shahriyari, Translating graphs by mean curvature flow, Geom. Dedicata 175, (2015), 57–64.
[30] Weimin Sheng and Xu-Jia Wang, Singularity profile in the mean curvature flow, Methods Appl. Anal. 16 (2009), 139–155.
[31] Leon Simon, Equations of mean curvature type in 2 independent variables. Pacific J. Math. 69 (1977), 245-268.
[32] Graham Smith, On complete embedded translating solitons of the mean curvature flow that are of finite genus. Preprint, [arXiv:1501.04149]
[33] Xu-Jia Wang, Convex solutions to the mean curvature flow. Ann. of Math.173 (2011), 1185–1239.
[34] Brian White, The size of the singular set in mean curvature flow of mean-convex sets, J. Amer. Math. Soc. 13 (2000), 665–695.
[35] Brian White, The nature of singularities in mean curvature flow of mean-convex sets, J. Amer. Math. Soc., 16 (2003), 123–138.
[36] Brian White, Curvature estimates and compactness theorems in 3-manifolds for surfaces that are stationary for parametric elliptic functionals, Invent. Math. 88 (1987), 243–256.

DEPARTMENT OF MATHEMATICS, JOHNS HOPKINS UNIVERSITY, BALTIMORE, MD 21218
E-mail address: js@math.jhu.edu

DEPARTMENT OF MATHEMATICS, UNIVERSITY OF CONNECTICUT, STORRS, CONNECTICUT 06269
E-mail address: ling.2.xiao@uconn.edu