Entanglement without nonlocality

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We consider the characterization of entanglement from the perspective of a Heisenberg formalism. We derive an original two-party generalized separability criteria, and from this describe a novel physical understanding of entanglement. We end that entanglement may be considered as fundamental to the local part and therefore as a separable computational resource from nonlocality. We show how entanglement differs from correlation physically, and explore the implications of this new concept of entanglement for the notion of classicality. We find that this understanding of entanglement extends naturally to multipartite cases.

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INTRODUCTION

Entanglement is a key concept in quantum mechanics, and plays a central role in the field of quantum computation. It acts as a resource that enables us to perform both faster calculations [1] and other impossible communication protocols [2,3]. It is also a concept of considerable importance in the foundations of quantum theory. Entanglement aims, however, notoriously difficult to understand, and the task of qualifying and quantifying it are extremely challenging. In this paper we will present a new physical understanding of the concept of entanglement. We will look at how and why systems become entangled, and what it means in conceptual terms for systems to be either entangled or separable. While the formalism of entanglement will likely be central to our investigation, we will not primarily be concerned with giving new calculational tools for the recognition of separability or the computation of entanglement quantities. Rather, we are trying to understand entanglement as a physical property of systems. This understanding is to be offered in the hope that it will be part of a full picture of this important, yet elusive, concept. In particular, we will find that the picture we gain of entanglement may be of use in understanding multipartite entanglement, and the relation of entangled subsystems to a larger entangled system. At present, these are both very poorly understood.

Entanglement is often considered to be a fundamental nonlocal effect, and indeed as the generator of nonlocality in quantum mechanics (see for example [4]). Such a viewpoint expresses in the standard description of entangled systems, that shared entanglement enables a system to in one another instantaneously, no matter how far apart they are ( whilst, of course, preserving the same local statistics ( an effect known as statistical locality [4]), arising from the well-known no-signalling theorem [5]). This is given as the mechanism behind effects such as teleportation, where quantum information appears to 'jump' between separated qubits. Entanglement also played a key role in the first explicit discussion of nonlocality in quantum mechanics, the famous paper by Einstein, Podolsky and Rosen [7]. The connection between entanglement and nonlocality is, however, a conceptual one, rather than a theorem of quantum mechanics. The exact nature of their relationship has not been established, and this will be considered in detail in this paper. We will find that, contrary to the standard belief, entanglement can best be understood as a purely local effect.

In order to make our investigation of entanglement as general as possible, we are going to use a no-collapse regime. This is of particular relevance in quantum computation, where coherent entangled states are generally used throughout the algorithm [8]. We will also be using a Heisenberg, rather than a Schrodinger, representation in which to frame our results. There has recently been interest in the Heisenberg approach to analyse computation [9,10] and spin chains [11], where entanglement plays a vital role [12,13,14]. A Heisenberg-picture specification of entanglement therefore would also have specific computational use in these analyses. Furthermore, the Heisenberg approach of emphasising operators rather than states accords closely with the approach to many-body systems in solid-state physics. Entanglement is particularly important in these systems as correlations will in a sense the properties of materials [15]. The understanding of entanglement given here will therefore be amenable to use in such projects. We will use a particular type of Heisenberg formalism, that of the Deutsch-Hayden approach. The main reason for using this is its transparency in the localisation of qubits. When we are dealing with questions of locality it is very important that we are able to say that the (non)locality that we have found is real, rather than an artefact of a particular formalism.

In the standard Schrodinger representation a joint system is in general given its fullest description by giving a joint characterisation (a joint density matrix). Individual density matrices in general do not contain the full amount of data. In the Deutsch-Hayden approach, however, each system has its own description, which is necessarily localised when the system is localised. We therefore do not
have extraneous non-local descriptions of joint system s.

We will therefore start in the first section by outlining the formalism that we will use. In the next section we will then discuss the understanding of correlation and pure state entanglement that we have found using this approach. After this, we will begin to generalize this to mixed states, and will derive an entirely new necessary and sufficient separability criterion for two mixed qubits. The physical explication of this will take place in the next section, giving us the physical description of entanglement that we have been looking for, and expanding on the implications that this understanding of entanglement has for, among other areas, quantum information theory. In the final section we will make good our claim that entanglement may be constructed as a purely local element of quantum mechanics.

THE DEUTSCH-HAYDEN HEISENBERG APPROACH

The Deutsch-Hayden formalism was presented in [17] and expanded in [16]. It is based on the development of stabilizer theory by Gottesman [17,18] and is closely related to it. In this approach we start with a standard universal Heisenberg state, by convention usually denoted as \( |j\rangle \), and time-evolving operators. The evolution of a given system, \( a \), is represented by tracking its descriptors, given by

\[
q_a(t) = U^T q_a(0) U
\]

These are chosen as they form a basis in the Hilbert-Schmidt space of operators for the system, so can be used to reconstruct the time-evolved form of any operator (and hence make physical predictions). In the terms of stabilizer theory, they are the individual elements of the stabilizer group. By convention, we choose

\[
q_a(0) = 1^n 1^n a
\]

for an \( n \)-qubit array. The descriptors for a joint system are the simple combinations of descriptors for individual systems, e.g. \( q_{12} = q_1 q_2 \). The most natural way to move between this formalism and the Schrödinger representation is through the density matrix. In terms of the descriptors, for two qubits this is the simple form

\[
\rho_{12} = \sum_{ij} x_{ij} q_i q_j^* \quad x_{ij} = 0
\]

If we look at equation (1) we can see can see that, after a time \( t \), in general the descriptor for any given qubit will span the space of all qubits in the system. However, it is often possible to reduce the dimensionality of the descriptor for all practical purposes. Such reduced descriptors are formed by ignoring all components not on the specified spaces. For example, the reduced descriptor of \( q_{13} \) on space \( N \) is written

\[
q_{13} = q_3 2 H_N
\]

As a concrete example, take the descriptor component \( q_{12} = 1_1 \), which spans \( H_{12} \). The reduced descriptor on \( H_1 \) only is \( q_{12} = 1 \). In order for us to be able to substitute a reduced descriptor for a full one, we need to make sure that the reduced version gives us the same result as the full one. In our above example we can see that this is not the case: taking a look at the average values of the operators, we see that

\[
h q_{13} | 1 \rangle h q_{12} | 1 \rangle
\]

In fact, it is only in very specific circumstances that the reduced descriptors may be used [16]. In order to reduce a descriptor to the space of a given system, that system must be pure. If our example, qubit 1 is not in a pure state as we cannot reduce its descriptor to the space \( H_1 \) whilst preserving its predictions. It is possible, however, that taken together with qubit 3 it is in a pure state, that qubit 3 purifies qubit 1 (but we would need to see the remaining descriptors for all three systems in order to work that out. If this were the case, then we would be able to write the x-component of the reduced descriptor for qubit 1 as

\[
q_{13} = z_x
\]

We may, however, want to write a descriptor on the space of a system that is not pure. This is done by representing it by a convex sum of descriptors that are pure on that space [16]. For example, if we have two qubits which are both mixed, and we denote by \( q_{ij} \) all the possible descriptors on \( H_{12} \) of a qubit that is pure on \( H_1 \), then we can write

\[
\sum_{ij} x_{ij} q_{ij} = h w_i q_{ij}^* h_i
\]

In other words, we can use \( h w_i q_{ij}^* h_i \) as the reduced descriptor on \( H_1 \).

CORRELATION AND THE REDUCED DESCRIPTORS

Using this formalism, we have two conditions for pure state separability. The first comes from considering the average values of operators in separable states. If \( A \) and \( B \) are operators then

\[
h A B i = h A h B i \quad h q_{12} = h q_{1} h q_{2} i \quad (2)
\]

The second is the use of the reduced descriptors:

\[
h q_{12} = h q_{1} h q_{2} i
\]

(3)
These are not, however, entirely separate conditions (nor would we expect them to be) as 4 is derived from 3.

The ability to use the reduced descriptors in separable states points to one element of an understanding entanglement for pure states. Consider q1 H_12 where h_{q1} = h_{q1}. The neglected element g_{ij} represents the evolution of the first system on the space of the second. That is, it is a record of the past interaction of the first system with the second. If the systems are not entangled then this past interaction becomes irrelevant for the description of the first system (it is as if they had never interacted. So, if systems are entangled then we cannot ignore one if we are looking at the past evolution of another; it is irreducibly part of the history of that system.

This is, however, the most general form of entanglement. For this, we need to look at entanglement between system s in mixed states. We have, of course, a different criterion for separability in this situation:

\[
X_{12} = W_{11} W_{12} \quad 1
\]

Equation 2 now becomes the criteria for system s to be uncorrelated rather than separable. However, the relation of 3 to correlation is more complicated, and will now investigate it.

A useful system for these purposes is a 3-qubit Greenberger-Horne-Zeilinger (GHZ) state. In Schrödinger notation this is written (unnormalized) as |00i + j111i. This state has the property that it is overall pure and entangled, but if any one qubit is traced out then the remaining pair is in a separable mixed state. We can (not, of course, uniquely) construct a GHZ state from a single pair and a ground state system by the operation CNOT (1;3) (|00i + j111i)j1. In terms of descriptors this gives us

\[
q_1 = ( z \quad x \quad x; \quad y \quad x \quad x; \quad 1 \quad 1 )
\]

\[
q_2 = (1 \quad 1; \quad x \quad 1; \quad x \quad z)
\]

\[
q_3 = (1 \quad 1; \quad x \quad 1; \quad y \quad 1; \quad x \quad z)
\]

We can see immediately that each pair is mixed, as the reduced descriptors do not give the same average values as the full descriptors. For example, if we take system 1 and 3, thus neglecting H_2, we are left with

\[
[1]_{1} = ( z \quad x; \quad y \quad x; \quad 1 )
\]

\[
[3]_{1} = (1 \quad x; \quad y \quad x; \quad 1)
\]

which gives us h_{q1} q1_1 6 h_{q2} q3_1. We also see that each pair is correlated, through its q4, q5 component (ie for each pair h_{q5} q4_1 6 h_{q5} q5_1). The obvious thing to assume at this point is that the relationship between correlation and the use of reduced descriptors holds, in that if system s and b are correlated then it is not possible to neglect the components of eg q4 on H_1. The GHZ descriptors, however, tell us that this is an incorrect assumption. Take system s 2 and 3. We see that they are correlated, and yet we have h_{q2} q3_1 6 h_{q2} q2_1, thus breaking the link between correlation and use of the reduced descriptors. Note that the product h_{q2} h_{q2} q3_1 is not straightforwardly a tensor product as it is in the pure-state case, as here we have a non-trivial vector product on H_3. To make this product with the reduced descriptors, the original descriptors are taken and the components to be neglected are then replaced by 1. The product is then between two objects on H_{123}.

What is going on here can be seen from the combined descriptors: it is the components on H_1 which give the average values of the combinations different from the combined averages. That is, system s 2 and 3 are correlated by their (separate) past interactions with system 1. What the reduced descriptors are telling us here is not the correlation between the system s but the system's past interactions. Consider again how we constructed this particular set of GHZ descriptors. The first two system s started o in a single state, unentangled and uncorrelated with the third system which was in the zero state. System 1 then interacted with the second system and then with system 3 (at no time did system s 2 and 3 interact with each other. It is this lack of past interaction that is being picked up by the fact that the reduced descriptors are sufficient to fully describe the physically measurable properties of the systems.

The next obvious assumption to make is that as the use of the reduced descriptors is not telling us about correlation in the mixed case, perhaps it will tell us about entanglement? This would then be identical to the pure case, and we could use our understanding of entanglement as needing to take past interactions with other system s into account when looking at present measurable properties. Unfortunately this is easily shown not to be the case. If we take the reduced descriptors for the pairs (12) and (13) then they do not give the same average values as the full descriptors.

If we look at pairs (12) and (23) however, we find that the reduced descriptors do not preserve the average values of the full descriptors, and it is interesting to look at which values differ. Let us look at the reduced descriptors in full. Writing the reduced descriptors all on H_{123} we have for the pair (12):

\[
H_{12} = ( z \quad 1; \quad x; \quad y \quad 1; \quad x \quad 1; \quad 1 )
\]

\[
H_{13} = (1 \quad x; \quad 1; \quad y; \quad 1; \quad z)
\]

And for pair (13):

\[
H_{12} = ( z \quad x; \quad 1; \quad 1; \quad 1; \quad 1; \quad 1)
\]

\[
H_{13} = (1 \quad 1; \quad 1; \quad 1; \quad 1; \quad 1; \quad z)
\]

If we compare these with the full descriptors then we see that for each pair all of the descriptors give the same e
average values except the components $q_1 q_2$ and $q_1 q_2$. For these products the reduced descriptors give 0 rather than 1. What is interesting is that, as we saw above, these are the components which show the correlations between the system $s$. With the reduced descriptors, all the average values are the same except for those for the components which show the correlation. This lets us see that the correlation has arisen in the case of these two pairs from the interaction of each member of the pair with the other, rather than with a third party. If you take away this history of this mutual interaction (by using the reduced descriptors) then you lose the correlation.

Thus we have retained a partial connection between the reduced descriptors and correlation. If the reduced descriptors retain the correlation then we know that it has been brought about by past interaction with a third party. However, if the correlation is not there, then we can see that it has been produced directly from past interaction between the two system $s$ alone.

**Generalized Separability Criteria for Descriptors**

We turn our attention now to the subject of mixed state entanglement. In terms of the descriptors, the standard mixed-state separability criterion is $h_{q_1 q_2} = \sum_i w_i h_{q_1 i} h_{q_2 i}$. As it stands, this is rather like [2]: it is not obvious either where it comes from in the Deutsch-Hayden approach, or what it means physically in that picture. We would therefore like to nd a mixed-state analogue of [4]. Let us now look at the descriptor written on only a limited number of spaces. Now, any individual descriptor may be given on any Hilbert space by a weighted sum of basis descriptors for that space $\sum_i$. Therefore the ability to write a given descriptor without reference to the Hilbert space of another system tells us nothing about whether the two systems are entangled or not. But what if we consider the ability to write the overall descriptors for the combined system that we are looking at as a simple combination of such descriptors for the individual systems that do not have support on the Hilbert space of the other system?

In formal terms what we have is this. We can always represent the individual $q_1$ and $q_2$ as

$$h_{q_1 i} = \sum_i w_i h_{q_1 i} h_{q_2 i}$$

$$h_{q_2 j} = \sum_i w_i h_{q_1 i} h_{q_2 i}$$

where $U_i$ acts only on $H_{13}$ and $U_j$ only on $H_{23}$. However, in general when we want the descriptors for the overall system (writing on $H_{132}$ for convenience),

$$h_{q_1 q_2 i} = h_{q_1 i} h_{q_2 i}$$

We have the following relationship:

$$X_{i j} = \sum_i w_i h_{q_1 i} h_{q_2 i}$$

and hence the condition

$$h_{q_1 q_2 i} = \sum_i w_i h_{q_1 i} h_{q_2 i}$$

is a necessary and sufficient separability condition. We shall now prove that this is indeed the case.

Let us look at the left-hand side of (5). Part of the proposition here is that the weights for the different components in the sum, $h_{q_1 i}$ and $h_{q_2 i}$, are the products of the weights $i$ and $j$ in (4) and (5). That is, we have

$$X_{i j} = \sum_i w_i h_{q_1 i} h_{q_2 i}$$

$$= \sum_i w_i \sum_j h_{q_1 i} h_{q_2 j}$$

$$= \sum_i w_i (h_{q_1 i} h_{q_2 i} + h_{q_1 i} h_{q_2 j})$$

At this point we note that $Tr(U_j^2) Tr(U_j^2)$ is a constant for all components in the sum. For present purposes we can therefore ignore it as part of the normalization of the descriptor. We can therefore write the left-hand side of (5) as

$$X_{i j} = \sum_i w_i \sum_j h_{q_1 i} h_{q_2 j}$$

$$= \sum_i w_i \sum_j h_{q_1 i} h_{q_2 j}$$

$$= \sum_i w_i (h_{q_1 i} h_{q_2 i} + h_{q_1 i} h_{q_2 j})$$

$$= \sum_i w_i (h_{q_1 i} h_{q_2 i} + h_{q_1 i} h_{q_2 j})$$

We will now introduce some notation to make this rather unwieldy expression a little more tractable. Let us denote

$$a_i b_j U_{13} U_{13} U_{13} U_{13}$$

$$= \sum_i w_i \sum_j h_{q_1 i} h_{q_2 j}$$

This gives us

$$X_{i j} = \sum_i w_i \sum_j h_{q_1 i} h_{q_2 j}$$

$$= \sum_i w_i (h_{q_1 i} h_{q_2 i} + h_{q_1 i} h_{q_2 j})$$

In order to look at the behaviour of this double sum, let us now $x$ the index, and see what happens when only
the \( j \) index is varied. For each value of \( i \) the variable sum is then
\[
X \quad \text{Tr} m_j n_j U_{23}^\dagger \text{Tr} (\Phi h \Phi) \text{Tr} (\Phi h \Phi) \quad \text{Tr} m_j n_j U_{23}^\dagger
\]

We now note that in general
\[
\text{Tr} (\Phi h \Phi) = \text{Tr} (\Phi h \Phi) \quad \text{Tr} (\Phi h \Phi) \quad \text{Tr} (\Phi h \Phi)
\]

We will now show that when this is the case, the expression (\ref{eq:19}) sum to zero. In order to show this we will show that for each \( j = p \), such that (\ref{eq:10}) holds, there is a \( j = q \) such that
\[
\text{Tr} m_p n_p U_{23}^\dagger \text{Tr} (\Phi h \Phi) \text{Tr} (\Phi h \Phi) \quad \text{Tr} m_q n_q U_{23}^\dagger \text{Tr} (\Phi h \Phi) \text{Tr} (\Phi h \Phi)
\]

To start, we rewrite
\[
\text{Tr} m_j n_j U_{23}^\dagger \quad \text{Tr} (\Phi h \Phi) \quad \text{Tr} m_j n_j U_{23}^\dagger \quad \text{Tr} m_j n_j \}
\]

Let us now look at \( U_N \), which we will denote as taking us from the \( q \)-descriptor to the \( p \)-descriptor:
\[
m_p n_p U_{23}^\dagger m_q n_q U_N
\]

We will look at the subset of possible \( U_N \) such that \( U_N = I \). This has the immediate effect that \( m_p = m_q \) and hence that
\[
\text{Tr} m_q (t) = \text{Tr} m_p (t)
\]

and that
\[
\text{Tr} (\Phi h \Phi) = \text{Tr} (\Phi h \Phi)
\]

We now make use of the fact that a unitary transformation does not change the trace of a vector. As the transformation of \( U_N \) is connected to \( H_3 \) then it does not change the trace on that space. In other words, \( \text{Tr} m_q = \text{Tr} m_p \). If we now evolve both \( n_q \) and \( n_p \) under the same \( U_{23} \) transformation to get \( n_p (t) \) and \( n_q (t) \) then their traces will remain identical. That is,
\[
\text{Tr} n_q (t) = \text{Tr} n_p (t)
\]

Let us therefore look at the part of the expression (\ref{eq:19}) that varies between \( p \) and \( q \):
\[
\text{Tr} (\Phi h \Phi) = \text{Tr} m_j n_j
\]

Now let us consider the case when \( j = p \). If \( p \) is such that (\ref{eq:14}) is zero then that part of the overall sum is zero and we do not need to consider it. If \( p \) is such that (\ref{eq:14}) is nonzero, then let us denote \( B_i = B_i ; n_p = N_p ; \). Then
\[
\text{Tr} n_{23}^\dagger = \text{Tr} m_j n_j U_{23}^\dagger \quad \text{Tr} m_j n_j U_{23}^\dagger
\]

Remembering that \( i \) is xed, we denote the vector \( N_p \) as the rotation by of \( N_p \) about \( B_i \). This gives us \( B_i N_p = B_i N_p \). In other words, for any given \( j = p \) we can always nd \( j = q \) such that \( \text{Tr} n_{23}^\dagger = \text{Tr} n_{23}^\dagger \). Putting this together with the results (\ref{eq:11}), (\ref{eq:12}) and (\ref{eq:13}) we see that, as promised, (\ref{eq:19}) is correct. We can now conclude that for every component of the sum (\ref{eq:19}) which satisfies (\ref{eq:10}) there is another component which cancels it. In other words, the elements of the sum where (\ref{eq:10}) is satisfied sum to zero and are therefore neglected.

Let us now turn to the case in which (\ref{eq:10}) is not satisfied, in other words where
\[
\text{Tr} (\Phi h \Phi) \quad \text{Tr} (\Phi h \Phi) \quad \text{Tr} (\Phi h \Phi)
\]

In this situation (\ref{eq:19}) becomes
\[
\text{Tr} m_j n_j U_{23}^\dagger \quad \text{Tr} m_j n_j U_{23}^\dagger
\]

We can neglect the unvarying element \( \text{Tr} (\Phi h \Phi) \):
\[
\text{X} \quad \text{Tr} m_j n_j U_{23}^\dagger \quad \text{Tr} (\Phi h \Phi) \quad \text{Tr} (\Phi h \Phi)
\]

where the normalisation is explicitly neglected in the last step. We note that each component in the sum is non-negative, so the total cannot be zero.

Now in order to combine this expression properly with the expression for varying \( y \) we need to look closely at (\ref{eq:13}). This is not just a condition on the \( j \)-components of the sum, but on both the \( i \) and \( j \). As a consequence, we are summing not over individual \( i \) and \( j \) indices, but over a third index which we will call \( k \) which denotes the pairs of \( i \) and \( j \) which enable (\ref{eq:13}) to be set to \( 0 \). We therefore replace both the \( i \) and \( j \) indices with \( k \). We therefore have (\ref{eq:10}) as
\[
\text{X} \quad \text{X} \quad \text{X}
\]

Let us now combine this with the expression that we had for \( i = j \). As we replace \( i \) with \( k \) we get
\[
\text{X} \quad \text{X} \quad \text{X}
\]
\[
\begin{align*}
\text{Tr}(\mathbf{\psi}_i \mathbf{\psi}_j) \text{Tr}(\mathbf{\psi}_k \mathbf{\psi}_l) &= \text{Tr}(\mathbf{a}_k \mathbf{b}_k \mathbf{U}_{13}^i \mathbf{U}_{13}^j) \\
\text{Tr}(\mathbf{\psi}_i \mathbf{\psi}_j) \text{Tr}(\mathbf{\psi}_k) &= \text{Tr}(\mathbf{a}_k \mathbf{U}_{13}^j) \\
\text{Tr}(\mathbf{\psi}_i \mathbf{\psi}_j) \text{Tr}(\mathbf{\psi}_k) &= \text{Tr}(\mathbf{b}_k \mathbf{U}_{13}^i \mathbf{U}_{13}^j) \\
\text{Tr}(\mathbf{\psi}_i \mathbf{\psi}_j) \text{Tr}(\mathbf{\psi}_k) &= \text{Tr}(\mathbf{b}_k \mathbf{U}_{13}^i \mathbf{U}_{13}^j)
\end{align*}
\]

which is the known separation criteria for mixed states. We have therefore shown that if we can write

\[
\text{h}_{12} = \text{Tr}(\mathbf{\psi}_i \mathbf{\psi}_j) \text{Tr}(\mathbf{\psi}_k \mathbf{\psi}_l)
\]

(7)

where

\[
\begin{align*}
\text{h}_{1} &= \text{Tr}(\mathbf{\psi}_i \mathbf{\psi}_j) \mathbf{U}_{13}^i \\
\text{h}_{2} &= \text{Tr}(\mathbf{\psi}_i \mathbf{\psi}_j) \mathbf{U}_{13}^j
\end{align*}
\]

then the systems 1 and 2 are separable, and if their descriptors cannot be written in this way then they are entangled. In terms of the reduced descriptors, this separability condition becomes

\[
\text{h}_{12} = \text{Tr}(\mathbf{\psi}_i \mathbf{\psi}_j) \mathbf{U}_{13}^i \mathbf{U}_{13}^j
\]

(7)

where

\[
\begin{align*}
\text{h}_{1} &= \text{Tr}(\mathbf{\psi}_i \mathbf{\psi}_j) \mathbf{U}_{13}^i \\
\text{h}_{2} &= \text{Tr}(\mathbf{\psi}_i \mathbf{\psi}_j) \mathbf{U}_{13}^j
\end{align*}
\]

PHYSICAL ENTANGLEMENT

This separability criterion that we have derived gives us a notion of mixed state entanglement that is an extension of that which we had for pure states. Again, reduced descriptors play an key role, but there is an important difference here. Instead of reducing the space of the descriptors to that of one qubit, we reduce them to that of two. That is because we are really dealing with three qubits: the two which are in a mixed state, and the third which purifies them. We will see that this third qubit is not merely a mathematical convenience, but plays an important physical role in entanglement and correlation. Despite this, the essential point remains the same: if the two qubits are separable, then the description of one qubit does not depend on the description of the other qubit. Put another way, all the physical properties of one qubit can be described without reference to the physical properties of the other at the time at which they previously interacted.

What this means is that if we have two qubits, 1 and 2, which are entangled, then qubit 1 contains data about qubit 2, and vice-versa. This information is what was received during their mutual past interaction. That is, shared entanglement enables one qubit to carry information about another.

It is important to compare this characterization of entanglement with correlation. Consider two mixed qubits (and a third which purifies the system), which are separable but correlated. We can represent their descriptors as in (9) and (10), and they satisfy (11). We can therefore write the correlation condition as

\[
\text{h}_{12} = \text{Tr}(\mathbf{\psi}_i \mathbf{\psi}_j) \mathbf{U}_{13}^i \mathbf{U}_{13}^j
\]

(7)

where

\[
\begin{align*}
\text{h}_{1} &= \text{Tr}(\mathbf{\psi}_i \mathbf{\psi}_j) \mathbf{U}_{13}^i \\
\text{h}_{2} &= \text{Tr}(\mathbf{\psi}_i \mathbf{\psi}_j) \mathbf{U}_{13}^j
\end{align*}
\]

We can see that the only place the inequality can come from is the combination of descriptors on \( H_3 \). This gives us the principal difference between correlation and entanglement: correlation may always be represented as occurring through a third party, entanglement may never be. This is because we can always represent the correlation between two qubits as arising because they each, separately, have interacted with, and therefore contain a description of, a third qubit. Entanglement, however, cannot be represented in this way. In other words, if two qubits are entangled then they each carry information about the other, but if two qubits are correlated then they carry information not about each other, but about a third qubit.

This is, in fact, a considerable advantage of our new conception of entanglement. Standardly, entanglement and correlation are difficult to separate conceptually, and the same condition (SEIBERG does double work for both pure-state entanglement and mixed-state correlation. It is difficult to say exactly in what the difference between them consists, except to describe one as quantum and the other as classical, which is somewhat circular.

The second advantage, which seems at first sight to contradict the first, is that we can see that entanglement and correlation arise from exactly the same mechanism. Being able to describe both in the same framework is a great improvement on having to think of them as entirely separate. In the understanding of entanglement, that we are advancing here, correlation arises because of entanglement. For two (mixed) systems to be correlated, they both must have interacted with a third system (this purifies the overall system). Systems 1 and 2 are then both, separately, entangled with system 3. Suppose we now ignore system 3, or we do not have access to it. The
A consequence of this, we can also use our conception of entanglement to help understand the notion of classicality. One part of a definition of the classical domain is that there is no access to entanglement, only correlation. We can see now in greater detail what this entails. Firstly, it is not simply the case that there is no entanglement at all (then there would be no correlation). Rather, we can say that system systems which may be described classically are those whose descriptions rely only on reference to them selves and to their own past evolution, or to system systems which are no longer accessible. There is no irreducible part of the definition of one system that includes another system with which it is still interacting. Systems in situations which can be described classically can be described essentially as separate (this description relies only on their own past evolution (or on that of system systems which are now inaccessible). System systems which are entangled cannot be described in this separate way. An archetypal example of a classical situation is when a system has undergone decoherence. In this situation, system system 3 is the environment to which system systems 1 and 2 have been entangled. If we look just at system systems 1 and 2 then they behave separately from each other (they would not behave separately from system 3, but we have no access to it). They may be correlated, but not entangled.

So far, for reasons of tractability, we have been considering two-party entanglement. However, one bonus of our approach is that even in the bipartite case we also have elements of multipartite entanglement. This makes it a lot easier in this approach to consider the extension of an understanding of entanglement to the multipartite case. Let us start by considering the standard 3-qubit system that we have been using. The entanglement of three qubits may either be simply bipartite entanglement, or it may take the form of true tripartite entanglement [13]. There may also be a combination of the two. True tripartite entanglement comes in two distinct forms, typified by the GHZ and W states. We saw the descriptors for the GHZ state at the beginning of this paper, and will now look at the (unnormalised) form for the W state:

\[
q_1 = (z \times x; y \times x; x \times 1) \\
q_2 = (x \times z; 1 \times y; 1 \times x) \\
q_3 = (1 \times 1; 1 \times y; 1 \times z)
\]

On our understanding of entanglement, we would expect true tripartite entanglement to come about when a qubit contains information not only about itself but also about two other qubits (contrast with the bipartite case where it contains data about one other qubit). We would not expect all qubits to dem onstrate this property as this would preclude the question of whether there is bipartite entanglement at all. This is indeed what we see in both the GHZ and W states. In the GHZ case, qubit 1 contains information about both qubits 2 and 3, and in the W state case both qubits 1 and 2 contain complete information (rem embering of course that the numbering of the qubits here is arbitrary; both states have been constructed using a non-unique circuit). We would expect this to be the case for larger numbers of qubits and greater orders of entanglement. A true n-partite entanglement would arise from at least one qubit containing information about all the other n-1 qubits.

**Locality**

We have seen how entangled systems contain information about each other, and seen the implications of this for various aspects of quantum information theory. The problem now is, where does this leave us with the question of the locality or otherwise of entanglement?

Entanglement is usually considered to be a non-local effect because of the apparently instantaneous (or at least faster-than-light) way in which a change in one system comm unicates itself to another with which it is entangled. For example, in a Bell-type experiment we separate a single pair of photons and send them to different detectors. A choice of basis at one detector will project the electron heading towards the other detector on time scales shorter than that of a classical signal passing between them. Such a non-local effect is essentially necessary for the individual outcomes to be correlated at the different detectors. This, combined with the Bell results for the impossibility of a local hidden-variables theory [20, 21], appears to give the non-local nature of entanglement the status of a fact about the world. How, then, can we claim that a different form ofism will change this?

The answer to this rests on two important points. The first is that we need to take a closer look at what it really means for the outcome es of measurement on system systems to be correlated in a stronger-than-classical way. Taking the Bell-type scenario of the previous paragraph, if we look simply at the results of the two detectors then we are told nothing (the no-signalling theorem [6], requires the statistics to be unchanged when settings on the other are changed. What we must do is compare the individual measurement outcomes at the two detectors (which requires the results to be communicated to the same place (perhaps another researcher). It is only then, in a purely local operation, that the outcomes are found to be correlated [22]. We can think of this as a consequence of the lack of collapse during the detecting
processes: a particular choice of outcome at that time is not needed, and so we do not require a superluminal signal to pass between the system s.

Although this last point is important, it shows us only that we need not have nonlocality when we have entanglement; it does not show that we do not in fact have it. We can easily imagine a scenario in which there is no collapse but still nonlocal signalling between system s. We now turn to our second important point, which comes directly from our analysis of descriptors. This is that entangled system s carry information about one another, and that the information that one system carries is data about the state of the other system s at a previous time, that is, when they last interacted. Information is not carried about the current state of the other system s, and we can see clearly from the evolution of the descriptors that an operation on one system alone changes nothing about the other. What it will change, however, is the state of the joint system when the individual system s are being used as a basis to contact. The mutual information contained in the system s will then determine how they combine, and it is here that entanglement correlations are displayed. This is a purely local description; at no point does information come via nonlocally.

Before we continue, it is interesting to note a lemma to these main points. We have seen that it is when we build a joint state out of individual descriptors that we see the correlations of entanglement. We saw also that this situation can take the form of information about detector outcomes being transmitted to a mutually local one. The transmission is entirely classical; for example, it could take the form of one researcher talking on the phone to another. We therefore see that, with our understanding of entanglement, we also have a picture of quantum information being transmitted through classical channels. The data that entangled system s contain about each other is capable of transmission through what is usually thought of as a classical channel.

This is, in fact, something that should be expected, given our previous discussion of classicality on this view. This is yet another example of the lack of a sharp distinction between quantum and classical, and the rather messy, for most current practical purposes, de nition of the classical realm. It is an interesting insight into what is meant by a bit however, while it may not take part in entangling operations, they may nevertheless carry information that was gained that way. This operation of a bit is crucial to the locality of entanglement.

Let us now look at how this local view of entanglement works in practice. We will take a qubit pair in the entangled state $\lvert 01 \rangle + \lvert 11 \rangle$ and send them to di erent detectors. The detectors start in the $\lvert 0 \rangle$ state and perform perfect measurements on qubits 1 and 2 in the computational basis, and then transmit this information through a classical channel to the researcher. We start with the entangled qubits:

$$q_1 = (z \ x \ y \ x \ 1)$$  
$$q_2 = (1 \ x \ y \ z)$$

As we have seen, each carries information about the other (signi ed here by the $x$ components). Now we separate them, and perform perfect measurements (CNOT operations) on them, with the results in qubits 3 and 4 respectively:

$$q_3 = (1 \ 1 \ 1 \ x \ 1 \ 1 \ y \ x \ z)$$  
$$q_4 = (1 \ 1 \ 1 \ x \ 1 \ 1 \ y \ z)$$

We now send the results of the measurements down a classical channel. This is represented by using only the q x components of the descriptors:

$$q_3^R = (x \ 1 \ 1 \ x)$$  
$$q_4^R = (x \ 1 \ 1 \ 1)$$

We can see from these the information about qubit 1 travelling down this classical channel. It is how these dependencies (one straight from qubit 1, and one that has come via qubit 2) combine that shows the correlations due to entanglement in the measurement results. This process, and the transmission of information about the past states of the entangled qubits, is entirely local.

CONCLUSION

In this paper we have seen how the descriptor formalism gives us a view of entanglement where two system s that are entangled carry information about each other. We have seen how this differs signi cantly from correlation, in which situation the system s would each carry information about another, third, system. We have also seen how this means that correlation arises from entanglement, and the implication for a notion of classicality. We have explored how this gives insight into the relation between subsystems and entangled larger system s, and the information about different system s that is carried. We have expanded this understanding to the multipartite case. Finally, we have seen how this understanding of entanglement is entirely local.

This is a much more comprehensible picture of entanglement than has hitherto been given. It is a coherent conceptual picture of what is usually thought of as a "mystery" of quantum mechanics. The use of a Heisenberg picture aided our understanding because it did not contain the arti cial nonlocality of the Schr" odeinger formalism, and so we were able to gain a conception of entanglement from a Heisenberg separability criterion that we would not be able to derive from any of the standard criteria. The discovery that it is possible to do without nonlocality in characterizing entanglement is in important...
for our understanding both of entanglement and also of the nature of what is usually described as nonlocality in quantum mechanics.

This novel understanding of entanglement has implications for a very wide range of areas, of which we will mention just a few. In the foundations of quantum mechanics it can help with understanding the quantum/classical divide, and with exploring important entanglement-based situations (such as the Bell inequality set-ups). In quantum computation, it gives us a much broader understanding of a vital resource, and suggests that we may be able to use the idea of a 'now' of dependencies to show which qubits are in use during any given part of an algorithm or protocol. We have also shown that the resources of entanglement and nonlocality are different, and situations where they are used separately may point us towards new information transmission protocols. As this understanding has also given us a greater conception of what is meant by a classical computation, it points towards a greater understanding of the fundamental nature of quantum computation and how far it may go beyond what is possible classically.

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