Differential hierarchy and additional grading of knot polynomials

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ABSTRACT

Colored knot polynomials possess a peculiar $Z$-expansion in certain combinations of differentials, which depends on the representation. The coefficients of this expansion are functions of the three variables $A, q, t$ and can be considered as new distinguished coordinates on the space of knot polynomials, analogous to the coefficients of alternative character expansion. These new variables are decomposed in an especially simple way, when the representation is embedded into a product of the fundamental ones. The fourth grading recently proposed in [1], seems to be just a simple redefinition of these new coordinates, elegant but in no way distinguished. If so, it does not provide any new independent knot invariants, instead it can be considered as one more testimony of the hidden differential hierarchy ($Z$-expansion) structure behind the knot polynomials.

1 Introduction

Knot polynomials [2] are observables (Wilson loop averages) in one of the simplest Yang-Mills models: Chern-Simons theory [3, 4] in the simply connected 3d Euclidean space-time $M_3 = R^3$ or $M_3 = S^3$ (in more complicated spaces these are even more interesting non-polynomial functions). Studying these quantities and the rich set of relations between them is a crucial step towards understanding the general structure of Yang-Mills, gravity and more general string models. Since the theory is topological, the Wilson loop averages

\[ H_R^K \sim \langle \text{Tr}_R \, P \exp \oint_K A \rangle \]  

are relatively simple: they actually do not depend on the geometry of the line $K \subset M_3$, only on its topological (linking) class, i.e. $K$ can be considered as a knot or a link (if it consists of several disconnected lines). It also depends on representation $R$, on the coupling constant $q = \exp \left( \frac{2\pi i}{k+\bar{N}} \right)$ and on the gauge group $G$, for which we take $G = SU(N)$; thus, irreducible representations $R$ will be finite-dimensional and labeled by the Young diagrams. (generalizations to other Lie algebras, compact and non-compact, are rather straightforward). As already mentioned, for the simply connected $M_3$ this $H_R$ turns out to be a polynomial (called HOMFLY or HOMFLY-PT polynomial [2]) of the non-perturbative variables $q$ and $A = q^N$, where $\log A$ is the ’t Hooft coupling constant, which remains finite in the planar limit of Yang-Mills theory.

Not only it is a polynomial, all the coefficients turn out to be integers what implies an additional homological structure behind the scene: the moduli of these integer coefficients count something like (BPS) states of some hidden topological theory [5]. Indeed, $H_R$ can be represented as the Euler polynomial of the Khovanov-Rozansky complex [6, 7], describing the flips between different resolutions of the knot diagram induced by the cut-and-join operators (see [8] for a recent review). The corresponding Poincare polynomial has all the coefficients positive, but depends on one extra parameter (grading) $T$, the original polynomial

\[ H_R^K(A|q) = P_R^K(A|q, T) \big|_{T=-1} \]  

is obtained from this ”superpolynomial” [9] at $T = -1$.

For the HOMFLY polynomial $H_R$, there is now a very effective method to evaluate them through a sum over paths in the representation tree [10]. It is based on

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\[ \text{In this paper we actually consider the reduced knot polynomials, divided by their unknot counterparts, hence the } \sim \text{ sign instead of the equality.} \]
• the quantum-\(\hat{R}\)-matrix representation \([11]\) of knot polynomials in the temporal gauge \(A_0 = 0\) (where the propagator gets ultralocal, \(\delta^{(2)}(\vec{x}) \text{ sign}(t)\)),

• braid representation of the knot diagrams (2d projections of \(K\) (naturally appearing in the temporal gauge) and

• the character decomposition \([12, 13]\) (see also \([14]\) and \([15]\)), which reduces the story to the much simpler \(\hat{R}\)-matrices, acting in the space of intertwining operators.

This method generalizes, conceptually and technically, the well-known approach based on the skein relations in the fundamental representation (where the \(\hat{R}\)-matrix has just two eigenvalues and satisfies the equation \((R - q)(q\hat{R} + 1) = 0\)) and on the cabling approach, reducing evaluation of colored knot polynomials to that of the fundamental ones for the cabled knots (in modern terms it is sufficient to restrict the paths in the representation tree to those passing through the vertex \(R\)). It is technically very effective and allows one to calculate the colored HOMFLY polynomials in rather sophisticated examples. However, it is still not very clear, how this method is generalized to superpolynomials.

Until recently, we actually knew some examples of superpolynomials from two sources: from an artful analysis of particular cases in \([9]\) and subsequent papers \([16, 14, 17]\), and from a systematic evolution method of \([12, 18]\), which, however, needs some simple particular cases as the input. The most spectacular application of evolution method is to the torus knots, where, based on the original analysis of \([14, 12]\) and on a specifically torus approaches of \([19]\), a full solution is suggested in terms of the affine Hecke algebras \([15, 20]\). However, it is unclear to what extent the evolution method is systematically applied in this suggestion, and, most important, the answers for the colored would-be-superpolynomials are not always positive what can imply that they still describe some non-trivial deformation of the Euler polynomial rather than the Poincare one. If so, this implies the existence of new non-trivial deformations (extra gradings), at least for the torus knots.

Fortunately, today we possess another powerful method to systematically evaluate the superpolynomials: that of the Z-expansion \([21]\) (a far-going development of the original proposal in \([9]\)). It is still underdeveloped, but it already allowed to calculate the superpolynomials in all (anti)symmetric representations for series of 2-bridge knots (twist and torus knots in \([22]\) and \([23]\) respectively, where it is nicely consistent with the evolution method, which allows to do even more \([18]\)) and slowly proceed to less trivial representations \([24, 1]\). But, most important, it provides a very different description of knot polynomials and also sheds some new light on the problem of extra gradings. In particular, the recently suggested fourth grading of \([1]\) seems to be one-of-many possible new gradings; this view can help to understand that they all are still of lower value then the original three variables \((A, q, T)\). At the same time, the new superpolynomial examples found in \([1]\) allow us to move further with understanding of the Z-expansion approach. Perhaps, a more adequate name would be "differential hierarchy" referring to Khovanov-DGR "differentials" \([6, 9]\). As to "Z", it refers to significance of cases where the differentials enter in pairs named Z-factors in \([21]\) (though this is literally so only for rectangular Young diagrams). In what follows we use both names on equal footing.

2 The idea of Z-expansion

Modern QFT approach to correlators in general, and to the Wilson loop averages in Chern-Simons theory in particular, is to associate with any knot \(K\) and representation \(R\) an element of an infinite-dimensional vector space

\[
X_R^K = \sum_{I} x_R^K[I] \cdot e[I]
\]

where \(\{x_R^K[I]\}\) is a set of coefficients of expansion in a fixed basis \(e[I]\), which does not depend on the knot and representation. Then, the correlation function can be considered as a pairing of this element and a point in the dual space which is called vacuum:

\[
\text{correlation function} = \langle \text{vac} \mid X_R^K \rangle
\]

In \([12, 13, 25]\) the elements like \((3)\) corresponding to the Wilson loop averages in Chern-Simons theory and called extended or off-shell knot polynomials were introduced in the space of symmetric functions with the bases of characters, the Schur functions and the MacDonald polynomials of (infinitely many) time-variables \(\{p_k\}\). The pairing in that case is equivalent to the reduction of the basis to the topological locus,

\[
p^*_k = \frac{A_k - A^{-k}}{t^k - t^{-k}}, \quad M_R(p^*_k) = M^*_R
\]
essentially the same \{ the differentials reduce to just a power of \(21\) and some evidence was provided that it can be further extended to \(\text{miracle}\) polynomial. This miracle was clearly demonstrated already in \(21\) for the eight knot: starting from the special polynomial, the knot polynomials are actually the coefficients of this expansion for the special polynomial. It is crucial, of course that what matters is not the special superpolynomial itself, but its appropriate \(Z\)-representation, i.e. some additional \(\text{character}\) and \(\text{differential}\) expansions the bases \(\{t\}^{\text{off-shell}}\) (for \(A=1\)), and the off-shell polynomials \(X^k_{R}t\) are different, but the on-shell ones all coincide and do not depend on the choice of the braid representation.

In the present paper we elaborate on the alternative suggestion of \(21\) and \(18\): to expand off-shell knot polynomials \(\text{not}\) in the basis of characters \(M^k_{Q}(A,q,t)\), as in \(14, 12, 15, 13, 10\), but in some very different basis formed by \(d[I] = d^{j_1\ldots j_k}_{j_1\ldots j_k}\) which are reduced to the "multi-differentials" on-shell \(d[I] \rightarrow \prod_{a=1}^{k} D^{i_a}_{j_a} = \prod_{a=1}^{k} \{Aq^{i_a}/p^{j_a}\}, \{x\} \equiv x - x^{-1}\) (6)

These are just (Laurent) polynomials, the word "differentials" refers to their role in the theory of Khovanov homologies. The reason why these quantities are originally important in knot theory is that the specialization of representation theory at particular values of \(N\) is described as vanishing of some of the elementary differentials like \(\{Aq^{N}\}\) and \(\{A/t^{N}\}\), and the knot polynomials are constructed to respect these specialization properties (see \(9, 21\) and \(24\) for a detailed discussion).

Thus, we have two examples of (3):
\[ x^{K}_{R}[I] = g^{K}_{R}[I], \quad e[I] = d[I] \quad I \text{ is a set of integers} \]
\[ x^{K}_{R}[I] = c^{K}_{R}[I], \quad e[I] = M_{I} \quad I \text{ is a \text{Young} diagram} \] (8)

and the knot polynomials in the basis of multi-differentials are labeled by the expansion coefficients \(g^{K}\), which play the same role as \(c^{K}\) in the character expansion. Note that the topological invariance in the differential expansion fixes its normalization to start from unity. In both cases, of the character and the differential expansions the bases \((M^k_{Q} \text{ or } D[I])\) are \textit{universal}, i.e. the same for all knots. Dependent on the knot \(K\) are the expansion coefficients \((e_{RQ} \text{ and } g_{R}[I])\).

The crucial advantage of the differential expansion is its power to control the dependence of the coefficients on the representation \(R\) and on the parameters \(q\) and \(t\). In fact, in both cases it is a kind of double deformation of the archetypical relation for the \textit{special polynomials} \(12\) (i.e. the knot polynomials at \(t = q = 1\)), when all the differentials reduce to just a power of \(\{A\}\):

\(\text{at } t = q = 1 \quad P^{K}_{R} = \left(P^{K}_{R}\right)^{|R|} \Rightarrow \left\{ \sum_{Q=|R|} e^{K}_{RQ} M^{*}_{Q} \right\}^{|R|} = \left(1 + \sum_{I} g^{K}_{R}[I] \{A\}^{2I}\right)^{|R|} \) (9)

However, in the case of the differential expansion there is a \textbf{miracle}: the deformation is almost straightforward. This miracle was clearly demonstrated already in \(21\) for the figure eight knot: starting from the special polynomial \(\sigma^{41} = 1 + \{A\}^{2}\), one can define a \textit{procedure}, providing not only the HOMFLY but also superpolynomials in all symmetric and antisymmetric representation. In \(24\) this procedure was generalized to representation \(21\) and some evidence was provided that it can be further extended to \textit{arbitrary} representations. Moreover, essentially the same procedure simultaneously provides colored knot superpolynomials for the trefoil, starting from the \(Z\)-expansion of its special polynomial \(\sigma^{41} = 1 - A^{2}\{A\}^{2}\). The task of this paper is to extend this claim, that the \textbf{differential expansion opens a clear way to tame the representation dependence of knot polynomials}, to arbitrary knots.

Namely, it looks more and more plausible that when one expands knot polynomials in the basis \(D[I]\), i.e. uses the coefficients in front of them as the new coordinates in the space of knots, the independent coordinates are actually the coefficients of this expansion for the special polynomial. It is crucial, of course that what matters is not the special superpolynomial itself, but its appropriate \(Z\)-representation, i.e. some additional...
structure which actually knows a lot (perhaps, all) about the knot. The difference may seem obscure in the above example of $A_1$, it gets a little better seen for the trefoil, with

$$\sigma^{3_1} = -A^4 + 2A^2 = 1 - A^2 \{A\}^2$$

and becomes quite impressive already for more complicated 2-strand knots: for example,

$$\sigma^{[2,7]} = 4A^6 - 3A^8 = 1 - (3A^2 + 2A^6 + A^{10}) \{A\}^2 + (3A^4 + 2A^8) \{A\}^4 - A^6 \{A\}^6$$

it is the vector

$$\vec{g}^{[2,7]}_{[2]} \Big|_{q=t=1} = \begin{bmatrix} 1, - (3A^2 + 2A^6 + A^{10}), (3A^4 + 2A^8), -A^6 \end{bmatrix}$$

(not just the simple two-term expression at the l.h.s!) which has a potential to uniquely characterize the knot. It is a 7-component vector

$$\vec{g}^{[2,7]}_{[2]} = \vec{g}^{[2,7]}_{[2]} \otimes \vec{g}^{[2,7]}_{[2]} = \begin{bmatrix} 1, -2(3A^2 + 2A^6 + A^{10}), 2(3A^4 + 2A^8) + (3A^2 + A^6 + A^{10})^2, \ldots, A^{12} \end{bmatrix}$$

which can serve as a starting point for the two different and algorithmically defined $(q,t)$-deformations, which will provide the two superpolynomials $P^{[2,7]}$ in representations $R = [2]$ and $R = [11]$. (In fact, things are even more involved: as explained in [21], from the point of view of the $Z$-expansion the vector like (12) still has an internal structure, which is signalled about by non-unity coefficients, and the truly relevant coordinates contain even more components, see examples in Sects. 3-4 below.)

In other words, there is a growing evidence that $g^K_{[2]}[I]$ contain considerably more information about the knot $K$ than $c^K_{Q}$, therefore, in this parametrization the deformation of (9) can be understood much better. One can even think that it can be fully algorithmic, then the collection of functions $g^K_{[2]}[I](A,q,t)$ with $R = \Box(\ell)$, i.e. associated with the fundamental representation only (perhaps, even of $g^K_{[2]}[I](A=q=t)$, i.e. these variables in the HOMFLY set) could provide the complete information about the knot polynomials.\footnote{This conjecture looks very probable for the HOMFLY polynomials and for the superpolynomials in the (anti)symmetric representations, while its present status for more complicated representations remains obscure.}

This strangely sounding claim (which we illustrate below by numerous examples) can seem to contradict the fact that the colored superpolynomials contain much more information than the fundamental HOMFLY ones. The secret is, of course, that the set $g^K_{[2]}[I]$ contains much more than just $H^K_{\ell}$. The latter is obtained from the former one on-shell, i.e. from (3) when $d[I]$ are not just free parameters, but are substituted from (7); after that a lot of cancelations take place and the expression can drastically simplify. We shall see in Sect. 3.4 that the 2-strand torus fundamental HOMFLY polynomials which are just quadratic polynomials in $A$ (up to the normalization), have huge sets of non-zero $g_{\ell}[I]$ quantities, which are polynomials of high degrees in $A$. As an opposite side of the medal, it is not at all simple to extract $g$-variables even if the HOMFLY polynomials are known: either one should know them in many enough representations, or possess some deep insight into the hidden structure of differential expansions. Anyhow, we propose that this structure does exist, and $g$-variables provide a nice set of coordinates in the space of knots. They can look excessively complicated in particular examples, but instead they adequately reflect the structure of relations between various knot polynomials. In particular, the fourth grading proposed in [1] may be interpreted as a kind of transform of the $g$-variables (and there are many others of this kind, perhaps, less elegant, but equally allowed): if this is true, this extra grading is very different from $A,q,t$.

An intuitive picture is that with each representation $R$ there is associated a couple of operations, which together convert $g_{\alpha}$ variables into $g_{R}$:

$$g_{R}[I_R] = (g_{\alpha}[I])^{o[R]}$$

One of these operations, $I_{R}$, transforms the set $I$, while the other one, $o_{R}$ defines an appropriate convolution of the coefficient functions. Still, this insight is already sufficient to make the study of differential hierarchy of [21] and its comparison with the character expansion, sum over paths and evolution method quite interesting and important.

In what follows we begin with the simplest example of the figure eight knot $4_1$ in symmetric representations, where the functions $g[I]$ are essentially trivial, hence, what remains is basically the operation $I_{R}$. After that, the example of trefoil $3_1$ demonstrates that the operation $o$ can also be rather simple. However, already for the more general twist knots there are problems, and the story requires further study.
3 Basic examples of differential hierarchy: (anti)symmetric representations

3.1 Figure eight \((4_1)\) knot \([21, 24]\)

Despite in the braid representation being at least 3-strand, the figure eight knot, the simplest of the fully symmetric knots, appears to be also the simplest from the point of view of the colored knot polynomials and especially of the differential hierarchy. In particular, the answer for the knot polynomial in the fundamental representation is just trivial:

\[
H^{4_1}_0(A|q) = 1 + \{Aq\}\{A/q\} \implies P^{4_1}_0(A|q,t) = 1 + \{Aq\}\{A/t\} = 1 + \delta_{01}^0
\]

This boxed formula encodes the first basic property of the differential hierarchy: formulas for the HOMFLY polynomials are directly lifted to formulas for the superpolynomials, once they are written in terms of the multi-differentials \((7)\). In this case the only non-vanishing parameter is

\[
\mathcal{K} = 4_1 : \quad g^{4_1\{01\}}_1 = 1
\]

The second crucial feature is reflected in the archetypical formulas \([21]\) for the colored knot polynomials in the symmetric representations:

\[
P^{4_1}_{[r]}(A|q,t) = 1 + \sum_{j=1}^r [r]_{q!} [r-j]_{q!} \prod_{i=0}^{j-1} D_{r+i}^r D_1^i
\]

Quantum numbers here are defined as \([x]_q = \frac{q^x - q^{-x}}{q - q^{-1}} = [x]_{1/q}\). In the antisymmetric representations, the answers

\[
P^{4_1}_{[r]}(A|q,t) = 1 + \sum_{j=1}^r [r]_{q!} [r-j]_{q!} \prod_{i=0}^{j-1} D_{r+i}^r D_1^i
\]

are obtained from \((17)\) by the “mirror” transform \([12, 17]\)

\[
q \leftrightarrow -t^{-1}, \quad \text{i.e.} \quad D_j^i \leftrightarrow D_i^j
\]

and therefore do not seem to contribute anything new; however, the knowledge of the both formulas is important for the study of generic representations. They can be rewritten in a variety of ways, one of the most important converting the \(q\)-binomial coefficients into an extended set of differentials \([21]\). This explicitly explains in what sense these combinatorial factors can be interpreted as describing the set \(I(R)\) in \((6)\). For example, the right way to look at the first term in the sum \((17)\) is to substitute it by the combination

\[
[r]_q \cdot D_1^r = \sum_{i=0}^r D_{1}^{\Delta_i} \quad \text{e.g.} \quad [2]_q \cdot \{Aq^2\} \{A/t\} = \{Aq^3\} \{A/t\} + \{Aq\} \{A/t\}
\]

with unit coefficients. In a similar way one can deal with all the other binomial coefficients. Also popular are changes of notation: to the \(q\)-Pochhammer symbols from the \(q\) factorials and to the other sets of \(A, q, t\)-variables.

There are two immediate lessons from these formulas:

- First, under multiplication of representations the coefficients transform in a simple way. The set of contributing differentials in \((17)\) and \((18)\) is restricted, so that these formulas can be written as

\[
P^{4_1}_{[r]}(A|q,t) = 1 + \sum_{j=1}^r g_{r|i} \prod_{i=0}^{j-1} D_{r+i}^r D_1^i, \quad g_{r|i} = \frac{[r]_{q!} [r-j]_{q!}}{[j]_{q!} [r-j]_{q!}}
\]

and

\[
P^{4_1}_{[r]}(A|q,t) = 1 + \sum_{j=1}^r g_{r|i} \prod_{i=0}^{j-1} D_{r+j}^r D_j^i, \quad g_{r|i} = \frac{[r]_{q!} [r-j]_{q!}}{[j]_{q!} [r-j]_{q!}}
\]
If now one considers the generating functions
\[
\pi_{[r]}^{A} (z) = 1 + \sum_{j=0}^{r} g_{r,j} z^{2j} \quad \text{and} \quad \pi_{[1']}^{A} (z) = 1 + \sum_{j=0}^{r} g_{r,j} z^{2j}
\]
then
\[
\pi_{[r]}^{A} (z) = \left[ \pi_{[r]}^{A} (z) \right]^{r}_{q} \quad \text{and} \quad \pi_{[1']}^{A} (z) = \left[ \pi_{[1']}^{A} (z) \right]^{r}_{t}
\]
where the quantum power or the q-Pochhammer symbol is
\[
[1 + x]^{r}_{q} = 1 + \sum_{j=1}^{r} g_{r,j} x^{j} = \prod_{j=1}^{r} (1 + q^{2j-r} x)
\]
These formulas demonstrate clearly that, for different representations ([r] and [1'] in this case), the both operations \( I_{R} \) and \( \oplus_{R} \) are different. At the same time, the difference is clearly controlled by the structure of the Young diagram in a rather simple and intuitively appealing way.

- Second, modulo trivial combinatorial factors the coefficients of expansion (17) do not depend on the representation: if one defines
  \[
g_{r,j} = \frac{[r]_{q}^{1}}{[j]_{q}^{1} [r-j]_{q}^{1} G_{j}}
\]
then the dependence on \( r \) disappears from \( G \), moreover,
\[
\text{all} \quad G_{j}^{4} = 1
\]
(for other knots they are Laurent polynomials of \( A, q \) and \( t \), with the parameter \( T = -q/t \) easily restorable from the HOMFLY case of \( T = -1 \)).

- Another way to encode these relations is to write a difference equation [21] (its relation to the quantum A-polynomial equations [26, 22] is still obscure, instead this form of equations is nice to establish links with the Baxter equations associated with 5d gauge theories [27]):
\[
P_{[r+1]}^{A} (A) - P_{[r]}^{A} (A) = \{ Aq^{2r+1} \} \{ A/t \} P_{[r]}^{A} (qA)
\]
The shift \( A \rightarrow qA \) at the r.h.s. is actually responsible for a reshuffling of the set of differentials associated with the set of relations
\[
\begin{align*}
( [r+1]_{q} \{ Aq^{r+1} \} - [r]_{q} \{ Aq^{r} \} = [2]_{q} \{ Aq^{2r+1} \}) \cdot \{ A/t \} \cdot \frac{1}{[r]_{q} \{ Aq^{r+1} \} \{ Aq/t \}}, \\
( [r+1]_{q} \{ Aq^{r+2} \} - [r-1]_{q} \{ Aq^{r} \} = [3]_{q} [2]_{q} \{ Aq^{2r+1} \}) \cdot \{ A/t \} \cdot \frac{[r]_{q} \{ Aq^{r+2} \} \{ Aq^{r+1} \} \{ Aq^{2}/t \} \{ Aq/t \}}{[r]_{q} \{ Aq^{r} \} \{ Aq/t \}}, \\
\vdots
\end{align*}
\]

where the twice-underlined differentials differ from the single-underlined ones in the previous line by the shift \( A \rightarrow qA \).

The above examples actually explain what we want from the Z-expansion, i.e. provide a kind of its description, at least conceptual. It labels knots by an (infinite) set of parameters \( G \), which are independent of representation, and the Z-expansion provides a procedure to reconstruct the arbitrary colored superpolynomial from the knowledge of these parameters. Examples below are given to demonstrate that such a procedure can indeed exist. Also they show that the fourth grading of [1] acts as a trivial rescaling in the space of \( G \)-parameters (but since it does not transform the multi-differentials, the resulting knot polynomials can, and in most cases are affected, see examples in Sect. 5).
3.2 Trefoil

Our next example is the trefoil $3_1$, which is also the simplest torus knot. This example will help us to illustrate several important issues.

- While the set of relevant differentials in (anti)symmetric representations can still be labeled as $r|j$ with $j = 1, \ldots, r$ (this is the characteristic feature of all twist knots), already for the trefoil the representation-independent $G_j$ become functions of $A, q, t$:

\[
G^{3_1}_j = (-)^j A^{2j} q^{j(j-1)} = (-A^2 q)^j q^{2j(j-1)}
\]  

(30)

- The second version of this formula demonstrates, how HOMFLY is lifted to the superpolynomial: one should introduce $t \neq q$ in the differentials as in (7), and in the coefficients one should change

\[
A^2 \rightarrow A^2 q/t,
q^2 \rightarrow q^2
\]

i.e. the $q$-variable remains intact. This receipt is going to work for all the twist knots.

- Perhaps, most important, the trefoil example allows us to illustrate the difference between the character and differential expansions: in this example it is still not very striking (it becomes such for more complicated torus knots), but already quite visible.

As was already mentioned, the trefoil is a torus knot $[2, 3] = [3, 2]$, thus, the character expansion is given by a straightforward $t$-deformation $[12]$ (we remind that our superpolynomials are reduced) of the Rosso-Jones formula $[28]$. In the fundamental representation one has

\[
P^{[2, 3]}_a = A^3 \left( t^{-3} \left( \frac{Aq}{q} \right) - q^3 \left( \frac{A/t}{tq} \right) \right)
\]

(32)

At the same time, the $Z$-expansion of the same quantity looks quite different:

\[
P^{3_1}_a = 1 - \frac{A^2 q}{t} \{ Aq \} \{ A/t \} = 1 - \frac{A^2 q}{t} D_{01}^{10} \quad \text{(31)} \quad H^{3_1}_a = 1 - A^2 \{ Aq \} \{ A/q \}
\]

(33)

Note that the same quantity in an unstructured form looks quite different from the both formulas:

\[
P_{\text{trefoil}}^{[2, 3]} = \frac{q^2}{t^2} A^4 + A^2 (q^2 + t^{-2}) \quad (\text{and} \quad H_{\text{trefoil}}^{[2, 3]} = -A^4 + A^2 (q^2 + q^{-2}))
\]

(34)

Of course all the three formulas coincide,

\[
P^{3_1} = P^{[2, 3]} = P_{\text{trefoil}}
\]

(35)

but their meaning is not the same, they belong to very different classes with very different structures and implications. For example, $P^{[2, 3]}$ is perfectly suited for introducing the off-shell knot polynomials in the character basis $[13]$. Instead, $P^{3_1}$ is most suited for continuation to other representations: as we explained, the purpose of the $Z$-expansion is to provide a counterpart of the factorization property (9), which can be lifted to $t \neq q \neq 1$. In this particular case this is, indeed, straightforward:

\[
\begin{array}{ccc}
\text{rep } R & [1] = \varnothing & [2] & [3] \\
\hline
\text{t = q = 1} & 1 - A^2 \{ A \} & 1 - A^2 (A^2)^2 & 1 - 3A^2 (A^2)^2 + 3A^4 (A^4)^2 - A^6 (A^6)^6 \\
\text{t = q} & 1 - A^2 \{ Aq \} \{ A/q \} & 1 - [2] q^2 A^2 \{ Aq^2 \} \{ A/q \} + q^2 A^4 \{ Aq^3 \} \{ A \} \{ A/q \} & 1 - [3] q^2 A^2 \{ Aq^3 \} \{ Aq \} + [3] q^2 A^4 \{ Aq^3 \} \{ Aq \} \{ A/q \} - q^2 A^6 \{ Aq^3 \} \{ Aq^3 \} \{ Aq \} \{ A \} \{ A/q \} \\
\text{t \neq q} & 1 - \frac{A^2 q}{t} \{ Aq/t \} & 1 - [2] q (A^2 t^2) \{ Aq^2 \} \{ A/t \} + q^2 (A^2 t^2)^2 \{ Aq^3 \} \{ Aq^2 \} \{ A/t \} \{ A/t \} & 1 - [3] q (A^2 t^2) \{ Aq^3 \} \{ Aq^3 \} \{ Aq/t \} \{ A/t \} + [3] q^2 (A^2 t^2)^2 \{ Aq^3 \} \{ Aq^3 \} \{ Aq/t \} \{ A/t \} \{ A/t \} - q^2 (A^2 t^2)^3 \{ Aq^3 \} \{ Aq^3 \} \{ Aq^2 \} \{ Aq/t \} \{ A/t \} \{ A/t \}
\end{array}
\]
This table illustrates the change of both the differentials and the $G$-coefficients along the rows and columns. For an alternative representation with an extended set of differentials substituting the quantum binomial coefficients see [21, 18].

For the generic (anti)symmetric representation one has literally the same formulas as for the figure eight knot $4_1$:

\[
P_{[r]}^{31} = 1 + \sum_{j=1}^{r} G_j^{31} \frac{[r]_q!}{[j]_q![r-j]_q!} \prod_{i=0}^{j-1} D_0^{r+j} D_1^j, \\
P_{[r]}^{\bar{3}1} = 1 + \sum_{j=1}^{r} G_j^{\bar{3}1} \frac{[r]_q!}{[j]_q![r-j]_q!} \prod_{i=0}^{j-1} D_0^{r+j} D_1^j
\]

only this time, instead of (27), one has (30):

\[
G_j^{31} = (-)^j A^{2j} q^{j(2j-1)\ell(j-1)} = \left(-\frac{A^2 q}{\ell}\right)^j q^{2j(j-1)}, \\
G_j^{\bar{3}1} = (-)^j A^{2j} q^{-j(2j-3)\ell^{-j(2j-1)}} = \left(-\frac{A^2 q}{\ell}\right)^j \ell^{-2j(j-1)}.
\]

Finally, relations (24) between the generating functions remains intact:

\[
\pi_{[r]}^{31}(z) = \left[\pi_{[r]}^{31}(z)\right]^r_q \quad \text{and} \quad \bar{\pi}_{[r]}^{31}(z) = \left[\bar{\pi}_{[r]}^{31}(z)\right]_{t_q}^r
\]

but the generating functions themselves need to be slightly modified: they involve a new ingredient, a dilatation operator $\delta_q : A \rightarrow qA$, so that

\[
\pi_{[r]}^{31}(z) = 1 + \sum_{j=0}^{r} G_j^{31}(A^2 \delta_q) \frac{[r]_q!}{[j]_q![r-j]_q!} z^{2j} \quad \text{and} \quad \bar{\pi}_{[r]}^{31}(z) = 1 + \sum_{j=0}^{r} \bar{G}_j^{31}(A^2 \delta_{-1/t_q}) \frac{[r]_q!}{[j]_q![r-j]_q!} z^{2j}
\]

In this form they remain valid for all the twist knots.

- While in the case of the figure eight knot $4_1$ with all the coordinates $G = 1$, the superpolynomials, at least in all (anti)symmetric representations $R$, were described by the $R$-dependent reshuffling of the set of differentials $D[R]$, i.e. by what we called the operation $I_R$, already for the trefoil this is not enough: one should complement the same, already known, $I_R$ by the operation $\circ_R$ acting on the coefficients. At least, for the (anti)symmetric representations it is reduced to the sequence of box-gluing operations, $\circ_R \rightarrow \circ_{R'}$, moreover, in this case it is enough to consider $\circ_r = \circ_{[r]} \rightarrow [r+1]$ and $\bar{\circ}_r = \circ_{[r]} \rightarrow [1]$, acting on monomials of $A^2$. From above formulas it is clear that

\[
A^2 \circ_r q^{r(r-1)} A^{2r} = q^{r(r+1)} A^{2r} \quad \Rightarrow \quad A^2 \circ_r A^{2r} = q^{2r} A^{2r+2} \quad A^2 \bar{\circ}_r A^{2r} = t^{-2r} A^{2r+2}
\]

- The difference equation (28) for the trefoil remains almost the same:

\[
P_{[r+1]}^{31}(A) - P_{[r]}^{31}(A) = \{Aq^{2r+1}\} \{A/t\} G_{[r]}^{31}(A) P_{[r]}^{31}(qA)
\]

The only difference is the factor $G_{[r]}^{31}(A) = A^2$ at the r.h.s. (while for the figure eight knot $G_{[r]}^{31}(A) = 1$). One would naturally expect a convolution operation $\circ$ attached to it, but this equation means that in this particular case it is fully taken into account by the same shift $A \rightarrow qA$, which adequately describes the operation $I_{[r]}$ on the set of the relevant differentials.

### 3.3 Twist knots [22, 18]

The general construction which is applicable to all twist knots directly generalizes the approach described in Sect. 3.1 and 3.2. The main idea is to decompose the polynomials in (anti)symmetric representations in the
same set of DGR-like differentials as in (17), (18), and (36). For any twist knot \( \mathcal{K} \) in all (anti)symmetric representations one has

\[
P_{[r]}^{\mathcal{K}} = 1 + \sum_{j=1}^{r} G_j^{\mathcal{K}} \frac{[r]!}{[j]! [r-j]!} \prod_{i=0}^{j-1} D_0^{r+j} D_1^i, \\
P_{[r']}^{\mathcal{K}} = 1 + \sum_{j=1}^{r} G_j^{\mathcal{K}} \frac{[r']!}{[j]! [r-j]!} \prod_{i=0}^{j-1} D_0^{r+j} D_1^i,
\]

where the infinite set \( G_j^{\mathcal{K}} \) depend on the knot but not on the representation.

Since the twist knots are enumerated with one parameter \( k \in \mathbb{Z} \setminus 0 \), in the remaining part of this subsection we refer to the corresponding \( G^{\mathcal{K}} \) as \( G^{(k)} \).

At the level of special polynomials all the coefficients \( G_j^{(k)} \) are trivial and according to the rule (38) are just simple powers of \( G_1^{(k)} \)

\[
G_j^{(k)} |_{q=1} = \left( G_1^{(k)} |_{q=1} \right)^j
\]

To raise this expansion to the level of HOMFLY polynomials one has to provide a natural \( q \)-deformation of the multiplication of coefficients \( G^{(k)} \) in such a way that

\[
G_j^{(k)} = \left( G_1^{(k)} \right)^{\circ_j}
\]

As opposed to the trefoil (40),(41), for the generic twist knots we do not demand the operation \( \circ \) to be binary. Instead, we only claim that it is universal for all the twist knots and is \( j \)-linear. We define and discuss this operation in Sect. 3.3.1 and 3.3.2.

The last transition from the HOMFLY to the superpolynomials in terms of decomposition (42) is quite simple: one makes the change of variables (31) in the expansion coefficients \( G_j^{(k)} \)

\[
A^2 \rightarrow A^2 q/t, \quad q^2 \rightarrow q^2,
\]

and restore \( t \) in the differentials \( D_0^{r+j} \cdot D_{1} \) (correspondingly in \( D_0^{r+j} \cdot D_{1} \) for the antisymmetric representations).

All nontrivial part of this procedure is included in the initial knowledge of a proper set of differentials for the twist knots in symmetric and antisymmetric representations. We discuss the generalization of this method beyond the symmetric/antisymmetric representations and the twist knots further in the paper.

### 3.3.1 Operation \( \circ_1 \) for twist knots, bilinear case

We suggested in (44) that all the expansion coefficients \( G_j^{\mathcal{K}} \) of a given twist knot \( \mathcal{K} \) are reconstructed from \( G_1^{\mathcal{K}} \) with some proper operation \( \circ \). To illustrate this statement we start with the simplest example of \( G_2^{(k>0)} \), while the general construction is presented further in Sect. 3.3.2.

In case of \( G_2^{\mathcal{K}} \), the operation \( \circ \) is simply bilinear, to avoid a confusion with multilinear operation we refer to it as \( \circ_1 \)

\[
G_2^{\mathcal{K}} = G_1^{\mathcal{K}} \circ_1 G_1^{\mathcal{K}}.
\]

The first two coefficients \( G \) are

\[
G_1^{(k)} = A \frac{1 - A^{2k}}{\{A\}}, \\
G_2^{(k)} = q A^2 \left( \frac{\{1\}}{\{A\}\{Aq\}} - \frac{\{2\}q}{\{A\}\{Aq^2\}} + \frac{\{4\}q^4 A^{4k}}{\{Aq\}\{Aq^2\}} \right),
\]

For the operation \( \circ_1 \) one has

\[
\begin{array}{ll}
\text{for } m \leq n & A^{2m} \circ_1 A^{2n} = q^{4m-2} A^{2m+2n} \\
\text{for } m > n & A^{2m} \circ_1 A^{2n} = q^{4n} A^{2m+2n}
\end{array}
\]
In the both cases, the degree of \( q \) depends on the *smaller* of the two powers. It is often convenient to look at the multiplication table:

\[
\begin{array}{cccccccc}
  & A^2 & A^4 & A^6 & A^8 & A^{10} & A^{12} & \ldots \\
A^2 & q^2 & q^2 & q^2 & q^2 & q^2 & q^2 & \ldots \\
A^4 & q^4 & q^6 & q^6 & q^6 & q^6 & q^6 & \ldots \\
A^6 & q^4 & q^8 & q^{10} & q^{10} & q^{10} & q^{10} & \ldots \\
A^8 & q^4 & q^8 & q^{12} & q^{14} & q^{14} & q^{14} & \ldots \\
A^{10} & q^4 & q^8 & q^{12} & q^{16} & q^{18} & q^{18} & \ldots \\
A^{12} & q^4 & q^8 & q^{12} & q^{16} & q^{20} & q^{22} & q^{24} \\
\ldots & q^4 & q^8 & q^{12} & q^{16} & q^{20} & q^{24} & \ldots \\
\end{array}
\]

(49)

### 3.3.2 Operation \( \circ \) for twist knots, multilinear case

In this section we define the multilinear operation proposed in (44). This operation acts on the graded space of polynomials in \( A \) and preserves the corresponding grading, at the locus \( q = 1 \) it turns into the simple multiplication of polynomials in \( A \). However, the operation defined here is by no means commutative or even associative.

In order to define the multilinear operation on polynomials in \( A \), it is enough to describe its action on powers of \( A \). Let us have the product of \( n \) monomials of \( A \), which we denote by \( \{k_1, k_2, \ldots, k_n\} \). Since our operation preserves the grading the result is proportional to \( A^{\sum_{i=1}^n k_i} \),

\[
\circ \left( A^{k_1}, A^{k_2}, A^{k_3}, \ldots, A^{k_n} \right) = C_k A^{\sum_{i=1}^n k_i},
\]

(50)

The corresponding coefficient of proportionality \( C_k = c_k^4 c_k^4 \) consists of two parts: \( c_k \) is the average power of \( q \) which depends on the set of powers, but not on the permutation, and the so called ”fine structure” \( c_k^f \) which depends only on the permutation with repetitions, but not on the exact values of powers \( k \).

The known formulas for \( G_j^{(k)} \) in the case of polynomials for the twist knots in (anti)symmetric representations uniquely determine the first coefficient \( C_k \) as a function of \( k \). Whereas for the second coefficient we could state only that the sum of \( c_k^f \) over all permutations of \( k \) with repetitions gives us a \( q \)-deformed multinomial coefficient. As a possible realization of such a structure, one could take

\[
c_k^f = q^2 \#(inversions) - \max \#(inversions),
\]

(51)

where \( \#(inversions) \) counts inversions in the permutation with repetitions \( \{k_1, k_2, \ldots, k_n\} \).

The average power of \( q \) is far more interesting. As it was stated, it depends only on the values of \( \{k_1, \ldots, k_n\} \) but not on the permutation, which can be naturally depicted as the Young diagram \( D \) with \( \sum_{i=1}^n k_i \) boxes. Let \( \{k_{i_1}, k_{i_2}, k_{i_3}, \ldots, k_{i_n}\} \) be a partially ordered set: \( k_{i_1} \geq k_{i_2} \geq k_{i_3} \geq \cdots \geq k_{i_n} \), where \( k_{i_r} \) is the length of the \( r \)-th row in the Young Diagram \( D \). The above partially ordered set can be parameterized with \( \{k_{j_1}, k_{j_2}, k_{j_3}, \ldots, k_{j_l}\} \), strictly ordered set \( k_{j_1} > k_{j_2} > k_{j_3} > \cdots > k_{j_l} \) with multiplicities \( \{m_1, m_2, \ldots, m_l\} \), \( n = \sum_{j=1}^l m_j \). Next, we denote the corresponding Young diagram of the multiplicities \( m_i \) with \( n \) boxes as \( d \).
Our claim is that

\[
\begin{align*}
  c^a_k &= q^{2\nu(D) - n(n-1)/2 - \nu(d^T)}, & \text{when } \forall i, k_i > 0, \\
  c^b_k &= q^{2\nu(D) - n(n-1)/2 + \nu(d^T)}, & \text{when } \forall i, k_i < 0,
\end{align*}
\]

(52a)

(52b)

where \(\nu(D) = \sum (i - 1)D_i\). It is worth noting that in (52b) all \(D_i\) understood as negative, to clarify this notation we present below example 4.

The operation \(\circ\) has several rather interesting properties. As a consequence of (52) it does not depend on a particular value of maximal power of \(A\) (minimal in the case of negative twist knots) when it has a unit multiplicity in the set \(\{k_1, \ldots, k_n\}\). This can also be noted from Table (49). Also, the dependence on \(k\) separates into three independent parts: the number of inversions, the set of powers, and the multiplicities of powers.

Finally, we present several different examples to illustrate the definition of \(\circ\).

1. We start from the basic example of \(\circ (A^2, A^2, A^2)\), here \(k_1 = k_2 = k_3 = 2\) and the corresponding diagram is

\[
D = [2, 2, 2] = [2^3] = \begin{array}{c}
\text{ } \\
\text{ } \\
\text{ } \\
\text{ } \\
\text{ } \\
\end{array}
\]

In this case one has only one value of powers \(k_i\) with multiplicity 3, thus, the diagram of multiplicities \(d\) consists of one row with length 3:

\[
d = [3] = \begin{array}{c}
\text{ } \\
\text{ } \\
\text{ } \\
\end{array}, \quad d^T = [1^3] = \begin{array}{c}
\text{ } \\
\text{ } \\
\end{array}
\]

Now, using (52a) one gets

\[
\circ (A^2, A^2, A^2) = c^a_{\{2,2,2\}} A^6 = q^6 A^6
\]

(53)

The above example does not illustrate (51), since there is no nontrivial permutation in the set \(\{2, 2, 2\}\) and the number of inversions is always 0, which means that \(c^f_{\{2,2,2\}} = 1\) and plays no role.

2. We continue with less trivial example consisting of different powers of \(A\), namely we describe all permutations of \(\circ (A^2, A^2, A^6)\):

\[
D = [6, 2, 2] = [6^1, 2^2] = \begin{array}{c}
\text{ } \\
\text{ } \\
\text{ } \\
\text{ } \\
\text{ } \\
\text{ } \\
\end{array}, \quad d = d^T = [2, 1] = \begin{array}{c}
\text{ } \\
\text{ } \\
\end{array}
\]

Again, using (52a), one gets \(c^a_{\{2,2,6\}} = c^a_{\{6,2,2\}} = c^a_{\{6,2,2\}} = q^6\). Next, we should take into account (51)

\[
c^f_{\{2,2,6\}} = q^{-2}, \quad c^f_{\{2,6,2\}} = 1, \quad c^f_{\{6,2,2\}} = q^2.
\]

Finally, this leads us to

\[
\begin{align*}
\circ (A^2, A^2, A^6) &= q^6 A^{10} \\
\circ (A^2, A^6, A^2) &= q^8 A^{10} \\
\circ (A^6, A^2, A^2) &= q^{10} A^{10}
\end{align*}
\]

(54)

3. The next example includes a nontrivial multinomial coefficient when taking the sum over all permutations.

To this end, we describe all permutations of \(\circ (A^2, A^2, A^4, A^6)\) which include three types of powers. Here,

\[
D = [6, 4, 2, 2] = [6^1, 4^1, 2^2] = \begin{array}{c}
\text{ } \\
\text{ } \\
\text{ } \\
\text{ } \\
\text{ } \\
\text{ } \\
\end{array}, \quad d = [2, 1, 1] = \begin{array}{c}
\text{ } \\
\text{ } \\
\end{array}, \quad d^T = [3, 1] = \begin{array}{c}
\text{ } \\
\text{ } \\
\end{array}
\]

\[c^a_3 = q^{21}\]
Instead, the Z -factor  is defined as a reminder with respect to the differential expansion. In the latter case, for all 2-strand knots one has an elementary two-term formula for the HOMFLY polynomial in the fundamental representation. Namely, we construct a formula of the form:

\[ Pictorially, in the spirit of schemes in [9], this means that we represent a "snake" with two ends by a sum of rhombi, with a single point added: remarkably, under a proper (topological invariant) normalization this added point is exactly 1: this actually seems to be true for all knots, not only torus: the differential expansion always begins from 1. The rhombus in this case is exactly the first Z-factor \(D_0^0\). Next, we consider \(g_{i,j} = 1\) as a reminder with respect to \(D_0^0D_1^0\), subtract it from HOMFLY polynomial and divide the remaining part by

\[
\begin{align*}
\circ \left( A^2, A^2, A^4, A^6 \right) &= q^{16} A^{14} \\
\circ \left( A^2, A^2, A^6, A^4 \right) &= q^{18} A^{14} \\
\circ \left( A^2, A^4, A^2, A^6 \right) &= q^{18} A^{14} \\
\circ \left( A^2, A^4, A^6, A^2 \right) &= q^{20} A^{14} \\
\circ \left( A^2, A^6, A^2, A^4 \right) &= q^{20} A^{14} \\
\circ \left( A^4, A^2, A^2, A^6 \right) &= q^{22} A^{14} \\
\circ \left( A^4, A^2, A^6, A^2 \right) &= q^{22} A^{14} \\
\circ \left( A^4, A^6, A^2, A^2 \right) &= q^{24} A^{14} \\
\circ \left( A^6, A^2, A^4, A^2 \right) &= q^{24} A^{14} \\
\circ \left( A^6, A^4, A^2, A^2 \right) &= q^{26} A^{14} \\
\end{align*}
\]

(55)
Figure 1: The first step of decomposition of the HOMFLY polynomial for the torus knot $T_{2,5}^{[2,5]}$. 

The next steps are less pictorial, however in each step one takes the proper reminder and continues with the quotient. For the HOMFLY polynomial of torus knot $T_{2,5}^{[2,5]}$ in the fundamental representation, thus, one has

$$H_{[2,5]} = 1 - D_0 D_1^0 \left( \frac{A^2}{q} [2]_q + A^6 q^2 - D_0^2 D_1^1 A^4 \right),$$

or

$$g_{[2,5]} = 1, \quad g_{[2,5]} = - \frac{A^2}{q} [2]_q - A^6 q^2, \quad g_{[2,5]} = A^4,$$

further in this section we assume that everywhere $g_{[2,5]} = 1$.

The reason to present a simple polynomial in a quite sophisticated form is because of the relation of this decomposition with higher (anti)symmetric representations and because it leads directly to reconstructing the superpolynomials.

Decomposition (61) exists for all 2-strand knots in the symmetric representations and can be straightforwardly generalized to the antisymmetric representations,

$$P_{[2,2k+1]}^{[2,2k+1]} = 1 + \sum_{j=1}^{kr} g_{[2,2k+1]} j \prod_{i=0}^{j-1} D_{r+1}^i D_{j-1}^1,$$

$$P_{[2k+1]}^{[2k+1]} = 1 + \sum_{j=1}^{kr} g_{[2k+1]} j \prod_{i=0}^{j-1} D_{r+j}^0 D_{j-1}^1,$$

We provide a few first examples of the 2-strand torus knots in the tables below. Note that in all presented examples the dependence of $g_i$ on $i$ is again included in the q-binomial coefficient. In the case of fundamental representation, the general formula has the following form

$$g_{[2,2k+1]}^{[2,2k+1]} = (-1)^i \sum_{k=0}^{k-1} q^{k-2j+i} \binom{k-i}{j} \binom{i+j-1}{i} \frac{A^2 q^2}{q} \right)^{j+2i}$$

However, the dependence on the representation does not separate so nicely as in the case of the twist knots. As in that case, it is totally included in the combinatorial coefficients, which leads us to the point that decomposition (64) is not the finest structure of the knot invariant. The corresponding coefficients $g_{[2k+1]}^{[2,2k+1]}$ are still not the desired coordinates in the space of knot polynomials, but instead a sum of some proper finer coordinates. The discussion and further generalizations are presented in Sect.3.6.

In the tables below we list a few first $g_i$ for the first few 2-strand torus knots. For the sake of brevity, we use the notation $a^2 = -A^2 q/t$. With this variable (first used in [9]) all the coefficients become positive.

| $T_{2,3}$ | $\square$ | $\square\square$ | $\square\square\square$ |
|---|---|---|---|
| $g_1$ | $a^2$ | $a^2 [2]_q$ | $a^2 [3]_q$ |
| $g_2$ | $a^4 q^2$ | $a^4 q^2 [2]_q$ | $a^4 q^2 [3]_q$ |
| $g_3$ | $a^6 q^6$ | $\square\square\square\square$ | $\square\square\square\square\square$ |
In the 3-strand case the $Z$-expansion can be obtained by a remarkable new trick, which appears intimately related to the new grading of $[1]$. 

3.5 3-strand torus knot $[3, 4]$
Thus, we consider the difference
\[ p^{[3,k]} - p^{[2,2k-1]} = p^{(k)}, \quad k \neq 0 \mod 3 \]  
(66)
and obtain its Z-expansion. It turns out that while for the two-strand knots in the symmetric representation parameters \( g^{[2,2k+1]} \) are actually functions of only two variables, that is, of \( q \) and of the product \( \delta^2 = -A^2 q/t \), in the deviation \( p^{(k)} \), the corresponding coefficients have one extra power of \( q/t \). Thus, a natural rescaling (related with the fourth grading from [1])
\[ A \rightarrow A\sigma, \quad t \rightarrow t\sigma^2 \]  
(67)
does not affect the coefficients \( g \) for \( p^{[2,2k+1]} \) and for the twist knots in (anti)symmetric representations, but does affect those for \( p^{(k)} \).

In the fundamental representation one has for the difference \( p^{(k)} \) a rather simple formula
\[ p^{[3,k]} - p^{[2,2k-1]} = D_0^1 D_1^0 \left( \frac{(-1)^{k+1} 2^k M_i}{(-t/q)^{1-j}} \sum_{j=1}^{k-1} \frac{|k-3j|qt}{(-t/q)^{1-j}} \right), \quad k \neq 0 \mod 3, \]  
(68)
which in the simplest case of \( k = 4 \) just gives
\[ p^{[3,4]} - p^{[2,7]} = \frac{q}{t} \left( \frac{A^2 q}{t} \right)^4 D_0^1 D_1^0. \]  
(69)

Now, going to higher symmetric representations, one should decompose the corresponding difference \( p^{(k)} \) with respect to the same basis of multi-differentials that we used for the twist and 2-strand torus knots. This decomposition appears to be in a very intimate relation with the factorization property of the special polynomials. At the level of special polynomials \( (q = t = 1) \), one has for an arbitrary knot \( K \) and representation \( R \):
\[ \mathcal{H}_R^K = (\mathcal{H}_R^K)^{|R|}, \quad \mathcal{H}_R^K \equiv P_R^K, \]  
(70)
where \( \pi_k = p^{(k)}|_{q=t=1} \). The suggestion of [29, 30] was to extend (70) to generic \( t \neq 1 \) in the case of symmetric representations and to generic \( q \neq 1 \) in the case of antisymmetric representations \(^3\), i.e.
\[ P_K^r(A, q = 1, t) = (P_K^r(A, q = 1, t))^r. \]  
(71)

Assume there exists a decomposition with respect to the same pairs of differentials as for the 2-strand torus and twist knots in symmetric representations
\[ P_K^r = 1 + \sum_{j=1}^r G_K^r |j| \prod_{i=0}^{j-1} D_0^{r+i} D_1^i. \]  
(72)
Here one should note that the sequence of pairs of differentials used to decompose polynomials in the symmetric representations turns into a simple geometric progression at \( q = 1 \); indeed,
\[ \left( \prod_{i=0}^{j-1} D_0^{r+i} D_1^i \right)_{q=1} = \left\{ \left\{ A \right\} \left\{ \frac{A}{t} \right\} \right\}^j, \]  
(73)
thus, \( P_K^r(A, q = 1, t) \) can be considered as on-shell value of the generating function of the expansion coefficients \( G_K^r |j| \) at \( q = 1 \)
\[ f_K^r(\delta) = f_K^r(\delta) = \sum_j \delta^j G_K^r |j| (A, q = 1, t), \quad \text{on shell:} \quad \delta_0 = \left\{ \left\{ A \right\} \left\{ \frac{A}{t} \right\} \right\}, \quad P_K^r(A, q = 1, t) = f_K^r(\delta_0). \]  
(74)

Now, if one takes into account (69), at the locus \( q = 1 \) one has
\[ f^{[3,4]}(\delta) = \left( f^{[2,7]}(\delta) + \frac{A^8}{3^9} \delta \right)^r = \sum_{i=0}^r \binom{r}{i} f^{[2,7]}(\delta)^i \left( \frac{A^8}{t^9} \delta \right)^{r-i}. \]  
(75)

\(^3\)Further in this section we restrict ourselves to the symmetric representations, the antisymmetric case is absolutely straightforward.
The answer for the superpolynomials presents a \( q \)-deformation of (75). The basic idea is to describe separately the \( q \)-deformation of differentials and the \( q \)-deformation of coefficients \( G^{K}_{[r],j} \). As for the differentials, it seems naturally to make the following substitution depending on the representation \([r]\):

\[
\delta^j \rightarrow \prod_{i=0}^{j-1} D_{0}^{r+j} D_{1}^{i}.
\]

(76)

To describe the \( q \)-deformation of the multiplication rule for \( G \), one can consider \( P^{[3,4]}_{[2]} \) as a perturbation over \( P^{[2,7]}_{[2]} \), then one has for the difference \( G^{[3,4]}_{[2]} - G^{[2,7]}_{[2]} \) Table 1.

| \( j \) | \( G^{[3,4]}_{[2],j} \) | \( G^{[2,7]}_{[2],j} \) |
|---|---|---|
| 1 | \( -2a^8 t^{j} \) | \( -a^3 t^{[2]q} \) |
| 2 | \( 6a^{10} t^{9} + 4a^{14} t^{13} + a^{16} t^{14} + 2a^{18} t^{15} \) | \( a^{10} t^{9} [2]q_{[3]} + a^{14} t^{13} [2]q_{[1]} + a^{16} t^{14} q^{12} + a^{18} t^{15} q^{13} [2]q \) |
| 3 | \( -6a^{12} t^{11} - 4a^{16} t^{15} \) | \( -a^{12} t^{11} [2]q_{[3]} - a^{16} t^{15} q^{13} [2]q \) |
| 4 | \( 2a^{14} t^{13} \) | \( a^{14} t^{13} q^{13} [2]q \) |

Table 1: \( q \)-deformation of \( G^{[3,4]}_{[2],j} - G^{[2,7]}_{[2],j} \)

3.6 Summary: \( Z \)-expansion in the case of (anti)symmetric representations

In this section we provide a summary of knowledge about the \( Z \)-expansion of knot polynomials in the case of symmetric and antisymmetric representations. Our main claim concerns the basis of multi-differentials. Namely,

- For all knots \( K \) the knot polynomials should be decomposed into \( D_{0}^{r+j} D_{1}^{i} \) for the symmetric representations and into \( D_{r+j}^{0} D_{j}^{1} \) for the antisymmetric ones

\[
P^{K}_{[r]} = 1 + \sum_{j=1}^{s_{K_1}} g^{K}_{[r],j} \prod_{i=0}^{j-1} D_{0}^{r+j} D_{1}^{i},
\]

\[
P^{K}_{[r]} = 1 + \sum_{j=1}^{s_{K_1}} g^{K}_{[r],j} \prod_{i=0}^{j-1} D_{r+j}^{0} D_{j}^{1},
\]

(77)

where \( s_{K} = 1 \) for the twist knots, \( s_{K} = k \) for the 2-strand torus knots \( T^{[2,2k+1]} \) etc. This claim is checked for the twist knots, 2-strand torus knots and \( T^{3,4} \) torus knot. Although it was not checked directly for other knots there is a lot of evidence which supports this claim to be generic.

- In the case of 2-strand torus and twist knots, the expansion coefficients \( g^{K}_{[r],j} \) and \( g^{K}_{[r_1],j} \) can be lifted from the HOMFLY to superpolynomials in a straightforward way. To this end, one has to make the substitution in the expansion coefficients \( g^{K} \):

\[
A^{2} \rightarrow \frac{A^{2} q}{t}, \quad q \rightarrow q, \quad \text{in case of symmetric representations},
\]

\[
A^{2} \rightarrow \frac{A^{2} q}{t}, \quad q \rightarrow t, \quad \text{in case of antisymmetric representations}.
\]

(78)

Then, to generate the entire superpolynomial, one suffices to substitute these coefficients \( g^{K} \) into (77). The result is not obtained from the HOMFLY polynomial by a simple change of variables, since the differentials are \( t \)-deformed not in accordance with (78).

- For the twist knots the dependence of coefficients \( g^{(k)} \) on the representation can be completely separated from the dependence on the knot, that is,

\[
g^{(k)}_{[r],j} = \tilde{G}^{(k)}_{j} \frac{[r]_{q}!}{[j]_{q}! [r-j]_{q}!},
\]

\[
\tilde{g}^{(k)}_{[r_1],j} = \tilde{G}^{(k)}_{j} \frac{[r]_{t}!}{[j]_{t}! [r-j]_{t}!}.
\]

(79)
In (79) all dependence on the representation is included in the binomial coefficient. Thus, the coordinates \(G_j^{(k)} (\bar{G}_j^{(k)})\) parameterize the superpolynomials of a particular twist knot in all (anti)symmetric representations.

- Indeed, all \(G_j^{(k)}\) for the twist knots can be reconstructed from \(G_1^{(k)}\) with a proper multilinear operation \(\circ\):

\[
G_j^{(k)} = (G_1^{(k)})^{\circ j}
\]  

(80)

described in Sect. 3.3.2. This operation provides a natural \(q\)-deformation (in the case of \(\bar{G}\) this is the \(t\)-deformation) of the multiplication of polynomials in \(A\). The reduction of the above operation to simple multiplication at the locus \(q = t = 1\) is due to the factorization property of special polynomials.

Finally, we discuss the reason why the dependence on the (anti)symmetric representation \([r]\) ([1\(r\)]) is not separated from the coefficients \(g^K\) for all knots \(K\) as simply as for the twist knots. The point is that the decomposition (77) is not the finest possible structure of the knot polynomials in the (anti)symmetric representations. Each pair of differentials, \(D_0^{r+j} D_1^j\) (correspondingly \(D_0^j D_1^{r+j}\)) which we used in the decomposition (77) is actually a sum of pairs of the finest level differentials (see (20)). The twist knots belong to a particular case when all the expansion coefficients at the finest level are related in the proper way to produce \(D_0^{r+j} D_1^j\). This particular property guarantees the separation of variables in the sum and thus lifts it to \(g_j^{(k)}\).

We suggest that, with respect to this finer basis of pairs of differentials, all knot polynomials decomposes in the most natural way, which means that the coefficients of decomposition does not depend on the representation. However, this phenomenon cannot be clearly seen at the level of (anti)symmetric representations. The particular properties of the set of differentials which we used to decompose the polynomials here do not allow us to reconstruct the finest decomposition. The solution to this problem lays beyond the (anti)symmetric representations.

The next step towards the proper finest basis of differentials is discussed in the next section. The elements of that basis in an arbitrary representation \(R\) are naturally associated with all subsets of the boxes of Young diagram \(R\). When \(R\) has a single row or column, the sum over all subsets of the Young diagram \(R\) reduces simply to the sum over number of elements in the subset. This is the reason, why (77) is a sum over one index only.

4 Generic representations

4.1 Generalities

Much less is yet known about the differential hierarchy for generic representations, i.e. for the Young diagrams with more than one row or column. The only published result so far is the recent [24] and no independent checks have been made since then of the conjectures, which were formulated there. Still some additional evidence in [18] and [1] seems to confirm that approach, which we briefly formulate here.

- The terms of the differential expansion are naturally graded, by the power of \(\{A\}\) in the corresponding expansion of the special polynomial:

\[
P^K_R(A|q = t = 1) = \left(\sigma^K_\circ(A)\right)^{|R|}
\]  

(81)

where

\[
\sigma^K_\circ(A) = 1 + \sum_k s_k(A)\{A\}^{2k}
\]  

(82)

and \(s_k(1) \neq 0\). Consider the expansion

\[
P^K_R(A|q, t) = \sum_{k=0}^{\infty} p^{(k)}_R(A|q, t)
\]  

(83)

where \(p^{(k)}(A|q, t)\) vanishes as \(\hbar^{2k}\) when \(q = e^{const\cdot\hbar}, t = e^{\hbar}, A = e^{N\hbar}\).
• For all knots and representations [18]

\[ p_R^{(0)} = 1 \]  

(84)

This is the proper normalization, associated with the topological framing, i.e. normalized in such a way that the knot polynomials do not depend on the concrete braid realization. Note that this normalization is different from the group theory one, when the universal $R$-matrix is used in the calculations of, say, the HOMFLY polynomials (which corresponds to the vertical framing).

• Ideally, the term $p^{(k)}(A|q, t)$ is a $k$-linear combination of the $Z$-factors $Z_{a|b}^{k|l} = \{Aq^a/t^b\}\{Aq/t^d\}$:

\[ p^{(k)}(A|q, t) = \sum_{|I|=k} g[I] \cdot Z^{\otimes k}[I] \]  

(85)

with the coefficients $g[I]$ which can depend on $K$, $R$ and $A, q, t$, but do not need to vanish in the limit of $h = 0$.

• These coefficients $g[I]$ also exhibit some kind of representation independence and regularly depend on the knot $K$ in any "natural" series of knots, related by any kind of evolution.

• For the figure eight knot $4_1$ all the non-vanishing coefficients $g[I]$ are $q$-binomials.

• In practice this is indeed so for rectangular diagrams, at best. In general something like the "$\epsilon^2$-terms" of [24] (with $\epsilon = q - 1/q$) can be needed, which do not look as "regular" as the terms with $Z$ and can even contain odd number of differentials. Presumably the $\epsilon^2$-terms appear only for $k \geq 2$ and do not affect the $Z$-linear terms.

• When $A = t^N$ or $A = q^{-N}$, the knot polynomial is reduced to the one in a smaller representation $R_{red}$, respectively with one row or one column excluded. This reduction respects the gradation: terms of $p_R^{(k)}$ with a given $k$ reduce into $p_{R_{red}}^{(k)}$ with the same $k$:

\[ p_R^{(k)} = p_{R_{red}}^{(k)} \bigg|_{A=t^N \text{ or } q^{-N}} \]  

(86)

• As a non-trivial generalization of this reduction property, the knot polynomials satisfy difference relations as functions of representations, see Sect. 4.4 below, which also respect the gradation. Sometime (e.g. in the case of (anti)symmetric representations [21]) they are immediately promoted to recurrent equations enough to fix the polynomials completely (with proper initial conditions), though in general this is not yet achieved. It is also unclear what exactly these simple and nicely looking relations have to do with the sophisticated (but practically convenient) recursions a la [26, 22], often referred to as quantum A-polynomials.

• Extra gradings, like the one proposed in [1] can modify the differentials and $Z$-factors in a variety of ways, but they do not seem to affect the coefficients $g[I]$, which we suggest to consider as the true coordinates in the space of knots. In this sense, it can happen that the new gradations do not provide new knot invariants as compared to the set \{g[I]\}. They can, however, be helpful to find the differential expansion per se, what, as we already saw, is not quite a trivial task even for the (anti)symmetric representations.

In the rest of this section we illustrate to some extent some of the items in this list. The issue of the "fourth grading" from [1] will be addressed in a separate section 5.

### 4.2 $Z$-linear terms: self-consistent anzatz for the knot $4_1$ in arbitrary representation

At the moment the self-consistent conjecture is known for the $Z$-linear terms in arbitrary colored HOMFLY polynomials for the figure eight knot. For the one-hook diagrams $R$ it was already formulated in [24], now we extend it to arbitrary $R$. It serves as a starting point for all further extensions: to terms of higher order in $Z$ and to other knots. Self-consistency means that the $Z$-linear terms are nicely reduced among themselves when $A = t^N$ and $A = q^{-N}$. In accordance with our list of conjectures in Sect. 4.1, the $Z$-linear terms are free of the
The shift $s$ of the $Z$-formula depends a little more tricky on its position in $R$. Both parts are illustrated for $R = [10, 10, 10, 8, 7, 4, 4]$ in Figure 2. Let $(i, j)$ be an element of the Figure 2, it corresponds to the linear term $\propto Z^{(s)}_{ij} = Z_{i+s|j-s}$. The index $i$ counts the number of boxes to the right of the particular box, whereas the index $j$ counts the number of boxes down in accordance with the following rule

$$i = 2 \#(\text{boxes to the right}) + 1, \quad j = 2 \#(\text{boxes down}) + 1. \quad (88)$$

The shift $s$ is constructed in a more tricky way. Let us split the Young diagram $Y$ into nested hooks $\Gamma_i$. The first raw along with the first column form the first hook and so on, $Y = \bigcup_i \Gamma_i$. Fix a particular $n$-th hook, say, with the column length $r_n$ and the row length $s_n$, create the subdiagram $Y_n = \bigcup_{i \geq n} \Gamma_i$ and complete it to the full $r_n \times s_n$-rectangular $B_n$. Then the shift $s$ for any element of $\Gamma_n$ is the difference of the numbers of boxes in $B_n/Y_n$ down and to the right of this element respectively.

### 4.3 Example of rectangular diagram: representation [22]

This is an illustrative example: it shows very clearly what kind of criteria can be used to find the proper version of the $Z$-expansion.

Namely, one and the same HOMFLY polynomial for the trefoil (provided, for example, by the Rosso-Jones formula) can be expanded in a variety of ways, of which we present three, together with their counterparts for the figure eight knot (for its HOMFLY polynomial see [31] and [1]):

- **version 1**

$$H^{3}_{[22]} = 1 - A^2\left(Z_{1|1} + Z_{1|3} + Z_{3|1} + Z_{3|3}\right) + A^4Z_{2|2}D_0^{(0)}\left(q^4D_0^2 + q^{-4}D_0^{-2} + D_0^4 + D_0^{-4} + A^{-1}(q^2)^2\right) + A^4Z_{2|2}Z_{3|3}\left((q^2 + 1/q^2) - (q + 1/q)^2A^2Z_{1|1} + A^4Z_{1|1}Z_{2|2}\right). \quad (90)$$
\[ H_{[22]}^{41} = 1 + \left( Z_{1|1} + Z_{1|3} + Z_{3|1} + Z_{3|3} \right) + Z_{2|2}D_0^6 \left( D_0^2 + D_0^{-2} + D_0^4 + D_0^{-4} \right) + \]
\[ + Z_{2|2}Z_{3|3} \left( 2 + (q + 1/q)^2 Z_{1|1} + Z_{1|1}Z_{2|2} \right), \quad (91) \]

In this case \( H_{[22]}^{41} \) looks relatively nice, but \( H_{[22]}^{33} \) contains an \( \epsilon^2 \) term \( \{q^2\}^2 A^3 D_0^6 Z_{2|2} \). The \( Z \)-linear terms are in accordance with the conjecture of Sect. 4.1.

• version 2

\[ H_{[22]}^{33} = 1 - [2]_q (q^5 + q^{-5}) A^2 Z_{2|2} + [3]_q (q^4 + q^{-4}) A^4 Z_{1|1} Z_{2|2} - [2]_q^2 A^6 Z_{1|1} Z_{2|2}Z_{3|3} + A^8 Z_{1|1} Z_{2|2}Z_{3|3} = \]
\[ = 1 - [2]_q [2]_q^2 A^2 Z_{2|2} + [3]_q [2]_q^4 A^4 Z_{1|1} Z_{2|2} - [2]_q^2 A^6 Z_{1|1} Z_{2|2}Z_{3|3} + A^8 Z_{1|1} Z_{2|2}Z_{3|3} \quad (92) \]

\[ H_{[22]}^{44} = 1 + [2]_q^2 (q^4 - q^2 - 1 - q^{-2} + q^{-4}) Z_{2|2} + [3]_q [2]_q^2 Z_{1|1} Z_{2|2} + [2]_q^2 A^4 Z_{1|1} Z_{2|2}Z_{3|3} + Z_{1|1} Z_{2|2}Z_{3|3} \quad (93) \]

These two expansions look quite nice from the point of view of selection of the \( Z \)-factors, in particular, no \( \epsilon^2 \)-terms are present. However, the coefficients are much worse, especially in the case of \( H_{[22]}^{44} \). As manifestation of this, the \( Z \)-linear term underlined in (93) is different from the one conjectured in Sect. 4.1.

• version 3

\[ H_{[22]}^{33} = 1 - [2]_q^2 A^2 Z_{2|2} + [3]_q A^4 Z_{2|2}(q^2 Z_{3|1} + q^{-2} Z_{1|3}) - [2]_q^2 A^6 Z_{1|1} Z_{2|2}Z_{3|3} + A^8 Z_{1|1} Z_{2|2}Z_{3|3} \quad (94) \]

\[ H_{[22]}^{41} = 1 + [2]_q^2 Z_{2|2} + [3]_q Z_{2|2}(Z_{3|1} + Z_{1|3}) + [2]_q^2 Z_{1|1} Z_{2|2}Z_{3|3} + Z_{1|1} Z_{2|2}Z_{3|3} \quad (95) \]

This is what we think is the right \( Z \)-expansion: no \( \epsilon^2 \)-terms are present (as it should be for [22], which is a rectangular diagram), \( Z \)-linear terms are in accordance with Sect. 4.1 and other coefficients are also nice. Moreover, as expected, in the case of \( 4_1 \) the coefficients can be actually done unities: through the identities like \( (Z_{1|1} + Z_{1|3} + Z_{3|1} + Z_{3|3}) = [2]_q^2 Z_{2|2} \) one can express (95) as a sum over all subsets of the Young diagram \([2, 2]\) of \( Z \)-factors. It can be done in a few ways, one of the possible realizations of this kind is

\[ H_{[22]}^{41} = 1 + \left( Z_{1|1} + Z_{1|3} + Z_{3|1} + Z_{3|3} \right) + \]
\[ + \left( Z_{0|2}Z_{1|3} + Z_{3|1}Z_{3|1} + Z_{3|3}Z_{1|3} + Z_{2|0}Z_{3|1} + Z_{1|1}Z_{3|3} + Z_{3|1}Z_{3|3} \right) + \]
\[ + \left( Z_{1|1}Z_{1|3}Z_{1|3} + Z_{1|1}Z_{3|3}Z_{1|3} + Z_{1|1}Z_{3|3}Z_{1|3} + Z_{1|1}Z_{1|3}Z_{3|3} \right) + \]
\[ + Z_{1|1}Z_{2|2}Z_{3|3} \quad (96) \]

4.4 Recursion relations: emerging evidence

One of the first basic results about the \( Z \)-expansion, found already in [21], is the set of simple recurrent relations, like

\[ P_{[r+1]}^4(A) - P_{[r]}^4(A) = \{ Aq^{2r+1} \} \{ A/t \} \cdot P_{[r]}^4(qA), \]
\[ P_{[r+1]}^4(A) - P_{[r]}^4(A) = \{ Aq \} \{ A/t^{2r+1} \} \cdot P_{[r]}^4(1/t) \quad (97) \]

These equations are much simpler than the conventional quantum \( A \)-polynomials, but instead they do not allow any simple reduction to \( A = t^N \) and \( A = q^{-N} \), including that to the Jones polynomials (for \( N = 2 \)).

Generalization to more sophisticated representations require deeper investigation. Still, something non-trivial is already known for the rectangular Young diagrams, namely, for arbitrary \( r_1, r_2 \) and \( k \)

\[ P_{[r_1]}^k - P_{[r_2]}^k \sim \{ Aq^{r_1+r_2} \} \{ A/t^k \} = Z_{r_1+r_2|k} \quad (98) \]

However, the coefficient in front of this \( Z \)-factor is not yet properly identified and expressed through the superpolynomials in some other representations and with somehow shifted arguments. On the other hand, this kind of proportionality seems to hold not only for the figure eight knot \( 4_1 \), but also for the trefoil \( 3_1 \) and probably for other knots.
4.5 A comment on negative coefficients in torus superpolynomials

Since the trefoil is a torus knot, all the HOMFLY polynomials are given by the Rosso-Jones formula. The superpolynomials can be obtained in different ways. For example, one can use the fact that trefoil is simultaneously a twist knot, and thus belongs to the common series with 41 (for which non-trivial HOMFLY polynomials are obtained in [31]) and they can be t-deformed all together, a la [18].

Another possibility is to use the superpolynomials suggested in [15]. However, there is a well-known problem related with such obtained superpolynomials in higher representations: they are generally no longer positive polynomials in the variables \((a, t, T)\). At the same time, ref.[1] contains several explicit examples of the improved (positive) trefoil superpolynomials for the Young diagrams with several rows and columns. The superpolynomials calculated following [15] have negative coefficients when colored not by rectangular Young diagrams \([r^*]\). In the case of rectangular diagrams, the superpolynomials from [15] coincide with [1]. The only presented example in [1] beyond the rectangular diagram is a trefoil knot in representation \([2, 1]\). Comparing this superpolynomial with that constructed in [15], we find that they are in a rather interesting relation. That is, once one rewrites them in the \((a, t, T)\)-variables, one should take all powers of \(t\) which enters monomials with negative coefficient. Further we refer to this set of powers as \(\pi_1\). Next, we apply the following simple operation to all the monomials with powers of \(t\) from \(\pi_1\): we substitute coefficient \((-1)\) by \(T\), and divide monomials with positive coefficient by \(T^2\). To illustrate this rule, we present the coefficient tables (see Tab. 2 and Tab. 3) of the two mentioned polynomials. In Tab. 2 and Tab. 3 we omitted inessential common factors in order to compare these two polynomials.

| Table 2: Superpolynomial for the trefoil 31 in representation [2, 1] constructed in ref. [15]. |
|---------------------------------------------------------------|
| \(t^{-10}\) | \(t^{-8}\) | \(t^{-6}\) | \(t^{-4}\) | \(t^{-2}\) | \(t^0\) | \(t^2\) | \(t^4\) | \(t^6\) | \(t^8\) | \(t^{10}\) |
| \(a^6\) | 0 | 0 | 0 | 0 | 0 | 0 | \(T^{15}\) | 0 | 0 | 0 |
| \(a^4\) | 0 | 0 | \(T^8\) | \(T^{10}\) | \(T^{10}\) | \(-T^{10} + T^{12}\) | \(T^{12}\) | \(T^{14}\) | \(T^{14}\) | 0 |
| \(a^2\) | \(T^3\) | 0 | \(2T^5\) | \(-T^5 + T^7\) | \(3T^7\) | \(-T^7 + T^9\) | \(3T^9\) | \(-T^9 + T^{11}\) | \(2T^{11}\) | 0 | \(T^{13}\) |
| \(a^0\) | 1 | 0 | \(2T^2\) | \(-T^2\) | \(2T^4\) | \(-T^4 + T^6\) | \(2T^6\) | \(-T^6\) | \(2T^8\) | 0 | \(T^{10}\) |

| Table 3: Superpolynomial for the trefoil 31 in representation [2, 1] presented in ref. [1]. |
|---------------------------------------------------------------|
| \(t^{-10}\) | \(t^{-8}\) | \(t^{-6}\) | \(t^{-4}\) | \(t^{-2}\) | \(t^0\) | \(t^2\) | \(t^4\) | \(t^6\) | \(t^8\) | \(t^{10}\) |
| \(a^6\) | 0 | 0 | 0 | 0 | 0 | 0 | \(T^{13}\) | 0 | 0 | 0 |
| \(a^4\) | 0 | 0 | \(T^8\) | \(T^8\) | \(T^{10}\) | \(T^{11} + T^{10}\) | \(T^{12}\) | \(T^{12}\) | \(T^{14}\) | 0 |
| \(a^2\) | \(T^3\) | 0 | \(2T^5\) | \(T^6 + T^5\) | \(3T^7\) | \(T^8 + T^7\) | \(3T^9\) | \(T^{10} + T^9\) | \(2T^{11}\) | 0 | \(T^{13}\) |
| \(a^0\) | 1 | 0 | \(2T^2\) | \(T^3\) | \(2T^4\) | \(T^5 + T^4\) | \(2T^6\) | \(T^7\) | \(2T^8\) | 0 | \(T^{10}\) |

5 Z-expansion vs additional gradings

5.1 Introducing additional gradings

As we already explained in the text, reconstructing the Z-expansion from first few knot polynomials is ambiguous. Hence, having a knot superpolynomial at hands, this is still a highly non-trivial problem to determine its proper Z-expansion. This problem can be, however, simplified by introducing new gradings which differs between different differentials. Actually, in order to reconstruct the Z-expansion of any colored superpolynomial, one needs to introduce infinitely many new gradings, however, for smaller representations one needs only a few ones.

In this section, we consider the simplest case of just one additional grading which was introduced in [1] and demonstrate how it emerges within the differential hierarchy. In fact, there is another argument for introducing additional gradings: as we already mentioned at the beginning of Sect. 3.5, it seems to be badly needed after I.Cherednik’s observation [15] that the colored torus superpolynomials can fail to be positive beyond rectangular representations \([r^*]\). A way out (if the problem exists at all, see a comment in Sect. 4.5 on how this problem
is solved in [1]) is supposed to be that, what is obtained by this procedure is, in fact, the Euler characteristics
of a $t$-deformed complex, while there should be the corresponding Poincare polynomial of this complex, which
thus depends on an additional variable $T$. Totally this gives us a polynomial of 4 variables $(A, q, t, T)$.

We feel that the suggestion of an additional grading in [1] is intimately related to the story of the differential
hierarchy, but we are not sure that the structures implicitly referred to in [1] are exactly the same as ours.

Below we denote the additional grading variable through $\sigma$ (we explain its connection with variables of [1]
later in this section). We claim that

- In terms of variables $(A, q, t, \sigma)$ the fourth grading can be completely algorithmically reconstructed from
  the $Z$-expansion. The building blocks of $Z$-expansion are pairs of the DGR-like differentials $D[I]$. Each
  pair consists of one differential of the so-called type $X$ which scales as $A \to A/\sigma$ and the other differential
  of the so-called type $Y$ which scales as $A \to A\sigma$. At the same time, all expansion coefficients $G_{\sigma}^{K}\[r,j]$
  remain fixed. This conjecture is valid for all examples of quadruply-graded homology presented in [1]. We provide
  an explicit decomposition for each of that examples throughout Sect. 5.2, 5.3, 5.4, and 5.5.

- The specific properties of the $Z$-expansion of superpolynomials of the 2-strand torus and twist knots in
  symmetric and antisymmetric representations make introduction of the fourth grading $\sigma$ even more trivial.
  The key feature of this decomposition in the above case is that the expansion coefficients $G_{[r]}^{K}[r,j]$ or
  $G_{[r]}^{K}[1s,j]$ are indeed polynomials only in two instead of three variables, namely

$$G_{[r]}^{K}[r,j] = G_{[r]}^{K}[r,j] \left( \frac{A^2}{t}, q \right),$$

$$G_{[r]}^{K}[1s,j] = G_{[1s]}^{K}[1s,j] \left( \frac{A^2}{t}, t \right),$$

for knot $K$ being a 2-strand torus or twist knot. Next, we note that introduction of $\sigma$ in differentials
suggested in the previous item is made just with a simple change of variables inside this differentials

$$A \to A/\sigma, \quad t \to t/\sigma^2 \quad \text{for symmetric representations},$$

$$A \to A\sigma, \quad q \to q\sigma^2 \quad \text{for antisymmetric representations},$$

which leaves respectively (99a) and (99b) invariant. This makes the quadruply-graded homology homo-

geneous for all 2-strand torus and twist knots in the case of symmetric and antisymmetric representation.

This result is due to specific properties of differentials used for decomposing the knot polynomials in
the case of symmetric representations along with degeneracy of the expansion coefficients. The explicit
changes of variables are presented in Sect. 5.2 and 5.3.

- The recursive relations discussed in Sect. 4.4 can also be transferred naturally from the superpolynomials
to the quadruply-graded homology. The introduction of the fourth grading into these relations is the same
as in the differentials of knot polynomials. We briefly illustrate this claim in Sect. 5.6.

In fact, particular comments of this kind were already made in appropriate places of the previous sections,
now it is time to make them a little more systematic. In the rest of this section we explain what we mean in a
little more detail.

### 5.2 Figure eight knot, representations [1] and [2]

Both presented examples in sec.4.2 of [1] are indeed polynomials in three variables. If one takes the superpoly-
nomial in the MacDonald variables $A, q, t$, then using the substitution

$$A = \alpha \sqrt{-t/\kappa c}, \quad q = -\kappa t, \quad t = \kappa t_r$$

one gets the quadruply graded answer in the variables $(\alpha, \kappa, t_c, t_r)$.

Or, after substitution

$$\alpha = t_r^{-2} A \sqrt{t/q}, \quad \kappa = t_r^{-1} t, \quad t_c = -t_r q/t$$

Throughout this section we denote four variables $(a, q, t_c, t_r)$ used in [1] as $(\alpha, \kappa, t_c, t_r)$ to avoid a confusion with $a$ and $q$ used here.
one gets
\[ P_{[1]}^{41}(\alpha, \kappa, t_c, t_r) = P_{[1]}^{41}(A, q, t) = 1 + \{Aq\} \{A/t\} \]
(103)
i.e. \( t_r \) drops out of the answer. It was already noted in [1] that, in this case, the answer depends only on the product \( t_tC \), thus, the number of independent variables is three, not four. But in general eliminating the fourth variable is more sophisticated, provided by the change of variables (102).

In particular, after this substitution the fourth variable \( t_r \) also drops out of
\[ P_{[2]}^{41}(\alpha, \kappa, t_c, t_r) = P_{[2]}^{41}(A, q, t) = 1 + (q + q^{-1}) \{Aq^2\} \{A/t\} + \{Aq^3\} \{Aq^2\} \{Aq/t\} \{A/t\} \]
(104)

In this case, this can also be seen from the very beginning, because the answer is homogeneous: all the terms have the same value
\[ 2\#(\alpha) + \#(\kappa) - \#(t_c) - \#(t_r) = \text{const} = 0 \]
(105)

### 5.3 Trefoil in representations [1], [2] and [11]

First, we note that all answers for the (anti)symmetric representations presented in sec. 4.1 of [1] are homogeneous and, thus, the fourth grading can be completely eliminated from them. For representations [1] and [2] one has
\[ 2\#(\alpha) + \#(\kappa) - \#(t_c) - \#(t_r) = \text{const}, \]
(106a)
with exactly the same invariant (105) as for the figure eight knot (the nonzero value of \( \text{const} \) corresponds to an inessential common factor). At the same time, for representation [11] one has another invariant, which looks completely different
\[ 4\#(\alpha) + \#(\kappa) - 5\#(t_c) + \#(t_r) = \text{const}. \]
(106b)

It is worth noting that (106b) is not applicable to the trefoil in representation [1], the reason is a rather specific choice of grading \( (\alpha, \kappa, t_c, t_r) \) which heavily depends on the number of rows in the Young diagram. Additionally, the choice of grading \( (\alpha, \kappa, t_c, t_r) \) makes mirror symmetry transformation formulas dependent on the diagram (see Sect. 3.3 of [1] for details). We prefer to use the set of variables which makes description of the mirror symmetry universal for all diagrams:
\[ \alpha = A\sqrt{\frac{t}{q}}, \quad \kappa = t\sigma^{-1/l(R)}, \quad t_c = -\frac{q}{t}\sigma^{1/l(R)}, \quad t_r = \sigma^{-1/l(R)}, \]
(107)
where \( l(R) \) is the number of rows in corresponding Young diagram \( R \).

The dependence on the diagram in (107) compensates the corresponding dependence of the mirror symmetry rules for the variables \( (\alpha, \kappa, t_c, t_r) \). In terms of the variables \( (A, q, t, \sigma) \), the mirror transformation is the simple exchange
\[ A \leftrightarrow A, \quad q \leftrightarrow -\frac{1}{t}, \quad \sigma \leftrightarrow \frac{1}{\sigma} \]
(108)
for all knots and representations.

Return to the regular triple-graded homology (superpolynomials) is thus achieved at \( \sigma = 1 \). At the same time, \( A, q, t \) are just the MacDonald variables. The fourth grading \( \sigma \) here is exactly the grading \( Q \) in [1] (formulas of Sect. 1.5 and the next to last one in Sect. 2.4).

Now, if one rewrites the \( Z \)-expansion of the quadruply-graded constructions in terms of variables (107), one can note that the fourth \( \sigma \)-grading can be reconstructed fully algorithmically from the proper expansion of the superpolynomials, that is,
\[ \left( \frac{q}{t} \right)^{P_{[1]}^{31}} = 1 - \left( A\frac{q^2}{t} \right) \left( \frac{A\sigma}{q} \right) \left( \frac{Aq}{\sigma} \right) \]
(109)
\[ \left( \frac{q}{t} \right)^2 P_{[2]}^{31} = 1 - \left( A\frac{q^2}{t} \right) \left( \left\{ Aq^3 \right\} \left\{ A\sigma \right\} \left\{ Aq \right\} \left\{ A\sigma \right\} \right) + \left( A\frac{q^2}{t} \right)^2 \left\{ Aq^3 \right\} \left\{ Aq^2 \right\} \left\{ Aq \right\} \left\{ A\sigma \right\} \left\{ A\sigma \right\} \]
(110)
\[(q/t)^2 P_{[1]}^{3_1} = 1 - \left(\frac{A^2 q}{t}\right) \left\{ \left\{ \frac{A \sigma}{t^3} \right\} \left\{ \frac{A q}{\sigma} \right\} + \left\{ \frac{A \sigma}{t^2} \right\} \left\{ \frac{A q}{\sigma} \right\} \right\} \right\} + \left(\frac{A^2 q}{t}\right)^2 t^{-2} \left\{ \frac{A \sigma}{t^3} \right\} \left\{ \frac{A \sigma}{t^2} \right\} \left\{ \frac{A q}{\sigma} \right\} \left\{ \frac{A q}{t \sigma} \right\} \right\} \right\} \tag{111}

The Z-expansion building blocks are pairs made of two different types of differentials. To make the description more pictorial one can associate one differential with the \(x\)-coordinate of a particular box of the Young diagram and the other one with the \(y\)-coordinate (however, this does not imply the exact separation, see Sect. 3.6 for a detailed description). To restore \(\sigma\), one should scale \(A\) in the first type of differentials as \(A \to A/\sigma\), whereas in the second sort of differentials one substitutes \(A \to A \sigma\). The same rule also holds for the figure eight knot presented examples, for the trefoil in representation [22], and for knot \(T^{3,4}\) in representations [1], [2], thus for all examples presented in [1]. We conjecture this to be a generic rule for reconstruction of the quadruply graded homology.

Finally, we should make a note on the specifics of the symmetric and antisymmetric representations. In terms of the variables \((A, q, t, \sigma)\) (107), formulas (106) turn into

\[
\#(A) + 2\#(t) + \#(\sigma) = \text{const},
\]

\[
\#(A) - 2\#(q) - \#(\sigma) = \text{const}.
\]

In other words, if one takes the superpolynomial of knot \(3_1\) in the (anti)symmetric representation \(P_{[r]}^{3_1}\) (correspondingly \(P_{[r]}^{3_1}\)) then the quadruply-graded homology can be reconstructed via the simple change of variables

\[
P_{[r]}^{3_1} = P_{[r]}^{3_1} (A/\sigma, q, t/\sigma^2),
\]

\[
P_{[r]}^{3_1} = P_{[r]}^{3_1} (A \sigma, q \sigma^2, t).
\]

We conjecture that the same should hold for all the 2-strand torus and twist knots in all symmetric and antisymmetric representations.

### 5.4 Trefoil in representation [22]

For representation [22], after two minor misprints corrected, the answer of [1] decomposes nicely in terms of multi-differentials. Namely, rewrite the proposed polynomials in terms of the variables \((A, q, t, \sigma)\) (107) for the number of rows \(R = 2\)

\[
\alpha = A \sqrt{\frac{t}{q}}, \quad \kappa = \frac{t}{\sqrt{q}}, \quad t_e = -\frac{q \sqrt{\sigma}}{t}, \quad t_r = \frac{1}{\sqrt{\sigma}}, \quad \text{(in these terms } \gamma = t_e t_r = -q/t = T)\). \tag{114}

Then one has

\[
\left(\frac{q}{t}\right)^4 P_{[22]}^{3_1 \text{ GGS}} = 1 - A^2 \left\{ \frac{A q^2}{\sigma} \right\} \left\{ \frac{A \sigma}{t^2} \right\} \times
\]

\[
\times \left( - \left(\frac{q}{t}\right)^8 A^6 \left\{ \frac{A q^3}{\sigma} \right\} \left\{ \frac{A \sigma}{t^3} \right\} \left\{ \frac{A q}{\sigma} \right\} \left\{ \frac{A q^2}{t^2} \right\} \right\} \left\{ \frac{A \sigma}{t^2} \right\} +
\]

\[
+ A^4 \left( q^6 - q^4 + \frac{q^6}{t^4} + \frac{q^6}{t^6} + \frac{q^4}{t^4} \right) \left\{ \frac{A q^3}{\sigma} \right\} \left\{ \frac{A \sigma}{t^3} \right\} \left\{ \frac{A q}{\sigma} \right\} \left\{ \frac{A q^2}{t^2} \right\} -
\]

\[
- \left(\frac{q}{t}\right)^3 \frac{A^2 (q t^2 + t - 1)}{\sigma} \left\{ \frac{A q^3}{\sigma} \right\} \left\{ \frac{A \sigma}{t^3} \right\} + \frac{(q + q^{-1})}{q^2 t} \left\{ \frac{A q^2}{t} \right\} \right\} \left\{ \frac{A \sigma}{t} \right\} \right\} \left\{ \frac{A q}{t^2} \right\} +
\]

\[
+ \left\{ \frac{A q^2}{\sigma} \right\} \left\{ \frac{A \sigma}{t^2} \right\} + \left\{ \frac{A q^2}{t} \right\} \left\{ \frac{A \sigma}{q t^2} \right\} \right\} \left\{ \frac{A q}{t} \right\} (q + q^{-1})(t + t^{-1}) \tag{115}
\]

### 5.5 Three-strand torus knot \(T^{3,4}\)

The only example of a three-strand torus knot in [1] is \(T^{3,4}\). Applying the change of variables (107) to results presented in sec.4.3 of [1] one can note that (112a) is no longer true. Instead, the quadruply-graded construction separates into several homogeneous pieces. In the simplest example of the fundamental representation there are two pieces

\[
\left(\frac{q}{t}\right)^3 P_{[1]}^{3,4} (A, q, t, \sigma) = Pr_0 \left( P_{[4]}^{3,4} \right) + \frac{q}{t} \cdot Pr_1 \left( P_{[4]}^{3,4} \right) \tag{116}
\]
where \( \text{Pr}_k \) denotes the projector onto the degree \( k \) homogeneous part and \( \{ P^{[2,7]}_n \} \) can be taken from Sect. 3.4, we need it only as a function of the three variables without any references to its \( Z \)-expansion

\[
\begin{align*}
\text{Pr}_0 \left( P^{[3,4]}_n \right) &= P^{[2,7]}_n = P^{[2,7]}_n \left( A/\sigma, q, t/\sigma^2 \right), \\
\text{Pr}_1 \left( P^{[3,4]}_n \right) &= \frac{t}{q} \left( P^{[3,4]}_n - P^{[2,7]}_n \right) = \left( A^2 \frac{q}{t} \right)^4 \left\{ \frac{Aq}{\sigma} \right\} \left\{ \frac{Aq}{t} \right\}, \\
\text{Pr}_2 \left( P^{[3,4]}_n \right) &= \frac{q}{t} \left( P^{[3,4]}_n - P^{[2,7]}_n \right) = \left( A^2 \frac{q}{t} \right)^8 q^{12} \left\{ \frac{Aq}{\sigma} \right\} \left\{ \frac{Aq}{t} \right\} \left\{ \frac{Aq}{\sigma} \right\} \left\{ \frac{Aq}{t} \right\}.
\end{align*}
\]

The homogeneity is understood here w.r.t. the scaling (100a) which allows one to reduce any homogeneous piece to a functions of less number of variables, i.e. to remove the fourth grading \( \sigma \). On contrary, in the sum of a few pieces of different homogeneities this scaling would produce factors of \( \sigma \) of different degrees. In particular, in this concrete case the function \( \{ P^{[3,4]}_n \} \) to be no longer homogeneous is the presence of an additional factor of \( q/t \) in the \( Z \)-decomposition of this superpolynomial. Unlike the combination \( A^2 q/t \) the factor \( q/t \) is not invariant under change (113a). This reveals the origin of the fourth grading \( \sigma \) as a different rescaling of two types of differentials which enter the \( Z \)-decomposition in pairs. Again, we conjecture that transition to the quadruply-graded construction does not affect the expansion coefficients \( g_{R,j} \) for all knots \( K \) and representations \( R \).

The decomposition (116) is still not very impressive, due to the extreme simplicity of superpolynomial of the torus knot \( T^{3,4} \) in the fundamental representation, however, we started from this trivial example to demonstrate the generic concept. The approach becomes more spectacular when being applied to the quadruply-graded \( \{ P^{[3,4]}_n \} \). Here one has

\[
\left( \frac{q}{t} \right)^6 \left( P^{[3,4]}_n \right) = \text{Pr}_0 \left( P^{[3,4]}_n \right) + \frac{q}{t} \text{Pr}_1 \left( P^{[3,4]}_n \right) + \left( \frac{q}{t} \right)^2 \text{Pr}_2 \left( P^{[3,4]}_n \right),
\]

where

\[
\begin{align*}
\text{Pr}_0 \left( P^{[3,4]}_n \right) &= \text{Pr}_0 \left( P^{[3,4]}_n \right) (A/\sigma, q, t/\sigma) = P^{[2,7]}_n (A/\sigma, q, t/\sigma^2), \\
\text{Pr}_1 \left( P^{[3,4]}_n \right) &= \text{Pr}_1 \left( P^{[3,4]}_n \right) (A/\sigma, q, t/\sigma), \\
\text{Pr}_2 \left( P^{[3,4]}_n \right) &= \text{Pr}_2 \left( P^{[3,4]}_n \right) (A/\sigma, q, t/\sigma) = \left( A^2 \frac{q}{t} \right)^8 q^{12} \left\{ \frac{Aq}{\sigma} \right\} \left\{ \frac{Aq}{t} \right\} \left\{ \frac{Aq}{\sigma} \right\} \left\{ \frac{Aq}{t} \right\}.
\end{align*}
\]

Equation (119a) looks like a straightforward generalization of (117a). As for the highest homogeneity degree, if one compares (119c) with (117b) it is natural to treat the expansion coefficient in the second symmetric representation as a square of the corresponding coefficient in the fundamental representation with respect to some graded operation \( \circ ' \) similar to that in Sect. 3.3.1:

\[
a^8 \circ ' a^8 = q^{12} a^{16}
\]

The most interesting part of (119) is the omitted left part of equation (119b). Using \( a \) as a natural variable in the expansion coefficients, one can rewrite

\[
\begin{align*}
\text{Pr}_1 \left( P^{[3,4]}_n \right) &= \left[ 2 \right] q \left\{ \frac{Aq^2}{\sigma} \right\} \left\{ \frac{Aq}{t} \right\} \\
&\times \left( a^8 - \left\{ \frac{Aq^3}{\sigma} \right\} \left\{ \frac{Aq}{t} \right\} \right) \left( a^{1\cdot 8} q^{19} + a^{1\cdot 4} q^{10} [2]_q + a^{1\cdot 0} q [3]_q \right) - \left\{ \frac{Aq^4}{\sigma} \right\} \left\{ \frac{Aq^2}{t} \right\} \\
&\times \left( a^{1\cdot 6} q^{15} [2]_q + a^{1\cdot 2} q^{4} [3]_q \right) - \left\{ \frac{Aq^5}{\sigma} \right\} \left\{ \frac{Aq^3}{t} \right\} a^{1\cdot 4} q^9 \right),
\end{align*}
\]

or, in terms of the coefficients \( g \), one has

\[
g = \left[ 2 \right] q \begin{pmatrix}
0 \\
-a^8 \\
a^{1\cdot 8} q^{19} + a^{1\cdot 4} q^{10} [2]_q + a^{1\cdot 0} q [3]_q \\
-a^{1\cdot 6} q^{15} [2]_q - a^{1\cdot 2} q^{4} [3]_q \\
a^2 q^9
\end{pmatrix}.
\]

Again, we note that in all three parts of (119) the fourth grading do not affect the coefficients \( g \) of decomposition in the basis of multi-differentials.
5.6 Recursive relations

An algorithmic way of introducing the additional grading allows one to deform immediately various relations to the quadruply-graded case. For instance, according to the described rules, the equations from Sect. 4.4 are immediately generalized to the case of quadruply-graded polynomials. For example, for the trefoil

\[
\left(\frac{q}{t}\right)^2 P_{[22]} - P_{[11]} = \left\{\frac{Aq^3}{\sigma}\right\} \left\{\frac{A\sigma}{t^2}\right\} \left\{A^{14} q^{15} t^{-16} - A^{12} q^{15} \sigma^2 t^{-14} - A^{12} q^9 \sigma^2 t^{-14} + A^{10} q^{13} \sigma t^{-6} - A^{10} q^{13} \sigma^4 t^{-4} + A^{10} q^{11} t^{-10} + A^{10} q^{11} t^{-8} + A^{10} q^{11} \sigma^4 t^{-6} + A^{10} q^9 t^{-12} + A^{10} q^9 t^{-10} + A^{10} q^9 t^{-8} + A^{10} q^7 \sigma^4 t^{-14} + A^{10} q^5 \sigma^4 t^{-14} + A^{10} q^5 \sigma^4 t^{-12} - A^8 q^{11} \sigma^6 - A^8 q^9 \sigma^2 t^{-6} - A^8 q^9 \sigma^2 t^{-8} + A^6 q^3 \sigma^2 t^{-8} - A^6 q^3 \sigma^2 t^{-6} - A^6 q^3 \sigma^2 t^{-6} - A^6 q^3 \sigma^2 t^{-6} \right\}
\]

and the deformation of the differentials at the r.h.s. is as expected.

6 Conclusion

Of crucial importance in the study of every particular model of quantum field/string theory is understanding of what is appropriate basis for its correlation functions. In Chern-Simons theory at least two such bases are solidly identified: that of the chord diagrams, relevant for the theory of Vassiliev invariants [32], and for genus expansion of [33], and that of the SU(∞) characters (the Schur and MacDonald functions), naturally appearing [12, 34, 35] in the braid realization of knots and allowing one to introduce the off-shell (extended) knot polynomials a la [7].

In this paper we claim that the basis, provided by the Z-expansion of [21] can be of no less importance, and for some purposes even better than the character expansion. There is a whole number of motivations for this study.

- The story starts from the factorization property (9) of special polynomials (i.e. at \(q = t = 1\)) and the first purpose is to lift it to the HOMFLY and superpolynomials as straightforwardly as only possible. An important sign that this is a well motivated task, was a partial (in only one variable), but literal extension, at least, for particular representations, in [29].

- The second crucial observation is that the special polynomials, functions of \(A\) only are in fact naturally expanded in powers of \(A\) itself and of \(\{A\}^2 = (A - 1/A)^2\). This sounds strange, and of course this bi-expansion is not defined entirely at the level of special polynomials. Instead, it keeps some non-trivial information about structure of the generic colored superpolynomial. If there was \(t \neq 1\), then one could put \(A = t^N\) and consider an expansion in powers of \(\hbar = \log t\), where \(\{A\}\) would be of the order \(\hbar\). The \(\{A\}\)-expansion is a remnant of that expansion, and the powers of \(A\) are introduced so that no new powers of \(\hbar\) are added. This hidden structure information about the knot polynomial is dramatically extended at the next step of our reasoning.

- This next observation is just that each \(\{A\}\) is the \(q = t = 1\) limit of some DGR-differential \(D^j = \{Aq^j/t^j\}\). Thus, the \(\{A\}\)-expansion with \(A\)-dependent coefficients of the special polynomial comes from the corresponding expansion of the entire superpolynomial. In the simplest, (anti)symmetric representations this expansion has a peculiar form

\[
P_{[\tau]} = 1 + Z_{1[1]} \left( g_1 + Z_{2[1]} \left( g_2 + Z_{3[1]} \left( g_3 + \ldots \right) \right) \right)
\]

with \(Z_{n[1]} = \{Aq^n\}\{A/t\}\), hence, the two names: Z-expansion and differential hierarchy. In general this expansion actually describes an arbitrary colored superpolynomial in terms of the coefficients \(g_{R}[I]\) of its expansion in multi-differentials.

- The crucial property of this expansion is that the set of coefficients \(g_{R}[I](A,q,t)\) is much simpler than it seems. It looks like the knowledge of just \(g_{\circ}(A,q = t)\) for \(R = \emptyset\) and for the HOMFLY polynomials \(q = t\) may be finally sufficient to find all \(g_{R}[I]\), as certain powers of \(g_{\circ}\) w.r.t. some \(R\)-dependent non-associative multiplications and comultiplications, and with an algorithmically defined \(t\)-deformation. Moreover, it looks like the other gradings, including the one suggested in [1], can also be algorithmically introduced, once the Z-expansion is known.
In this paper we gave only some very limited evidence in support of these observations. The differential hierarchy is rather tedious to work out even in the simplest examples. Moreover, it is not always reduced to the $Z$-factors: as it is known since the [21] example of [24], some \$\epsilon^2\$-terms, even with odd numbers of differentials, can occur, which still need to be appropriately understood and tamed. Still, we believe that the existing evidence is already convincing enough to justify the need to study the differential hierarchy along with other generic approaches to knot polynomials.

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