Spin and magnetization effects in plasmas

G Brodin, M Marklund, J Zamanian and M Stefan

Department of Physics, Umeå University, SE–901 87 Umeå, Sweden
E-mail: mattias.marklund@physics.umu.se

Received 4 October 2010
Published 18 May 2011
Online at stacks.iop.org/PPCF/53/074013

Abstract
Quantum effects in plasmas are of interest for a diverse set of systems, and have thus as a field been revived and attracted a lot of attention from a wide community over the past decade. In models of quantum plasmas, the effects studied mostly are due to the quantum particle dispersion and tunnelling. Such effects can be of importance in dense systems and on short length scales. There are also a number of effects related to spin and statistics. However, up to recently the magnetization effect in plasmas due to the intrinsic electron spin has been largely ignored. The magnetization dynamics of e.g. solids has many important applications, such as components for memory storage, but has also been discussed in more ‘proper’ plasma environments, such as fusion plasmas. Furthermore, also from a basic science point-of-view the effects of intrinsic spin and gyromagnetic effects are of considerable interest. Here we give a short review of a number of different models for treating magnetization effects in plasmas, with a focus on recent results. In particular, the transition between kinetic models and fluid models is discussed. We also give a number of examples of applications of such theories, as well as an outlook for possible future work.

(Some figures in this article are in colour only in the electronic version)

1. Introduction
The field of quantum plasmas has been rapidly growing over the last decade. In particular, studies regarding the nonlinear properties of systems in which quantum and collective effects play an important role have been in focus (for recent reviews, see, e.g. [1, 2]). The research has been motivated by applications to e.g. quantum wells [3], plasmonics [4], spintronics [5], astrophysics [6] and ultra-cold plasmas [7]. Quantum plasma effects have also been measured in solid density target experiments [8]. Furthermore, there has also been a growing interest in quantum plasmas where magnetization effects are of importance, see, e.g. [9–12]. One reason for this is the promise of novel electronic devices. Furthermore, the utilization of spin may also play a key role in the yet to come implementation of quantum computing [5, 13].
spin effects are included, the intrinsic magnetic moment of the plasma constituents give rise to several new effects, principally due to the magnetic dipole force and the magnetization current. These effects are further complicated by the basic spin precession and also from more complex aspects of the spin dynamics.

The above physical systems can be described in a multitude of ways. Certain types of phenomena require kinetic descriptions, where the standard phase space is extended [14], and the much used Wigner function [15] is generalized to cover the spin dynamics [16]. However, such theories are typically too cumbersome to study complex nonlinear and/or inhomogeneous phenomena, and thus there is also a need to develop simpler models, in particular fully macroscopic fluid models. Here we will give a short overview of both approaches leading to kinetic theories, as well as fluid models. The fluid models can be derived directly from the Schrödinger or Pauli equation, using the ‘heuristic’ approach of Madelung, in which case the decomposition of the wave function of the system into phase and amplitude leads to the definition of macroscopic density, velocity and spin variables [9]. We then go on to describe the more detailed effective field quantum kinetic theory [16], through which the relevant fluid moments may be defined and the concomitant fluid equations derived [17], as well as giving the opportunity to analyse proper kinetic effects in quantum plasma systems. Finally, we give a brief account of possible applications and results of the quantum fluid/kinetic models.

2. The Madelung approach to quantum dynamics

A rather generic approach to quantum fluids is the use of a Madelung decomposition of the system wave function, in which the amplitude is translated into a density and the gradient of the phase determines the velocity variable. Such a decomposition will be reviewed below, and the results obtained will be compared later with the moment hierarchy obtained through a more rigorous quantum kinetics approach.

2.1. The Schrödinger equation

The basic equation of nonrelativistic quantum mechanics is the Schrödinger equation. The dynamics of an electron, represented by its wave function $\psi$, in an external electromagnetic potential $\phi$ is governed by

$$i\hbar \frac{\partial \psi}{\partial t} + \frac{\hbar^2}{2m_e} \nabla^2 \psi + e\phi \psi = 0,$$

where $\hbar$ is Planck’s constant, $m_e$ is the electron mass and $e$ is the magnitude of the electron charge. This complex equation may be written as two real equations, writing $\psi = \sqrt{n} \exp iS/\hbar$, where $n$ is the amplitude and $S$ the phase of the wave function, respectively [18]. Such a decomposition was presented by de Broglie and Bohm in order to understand the dynamics of the electron wave packet in terms of classical variables. Using this decomposition in equation (1), we obtain

$$\frac{dn}{dt} = -n \nabla \cdot \mathbf{v}$$

and

$$m_e \frac{d\mathbf{v}}{dt} = e\nabla \phi + \frac{\hbar^2}{2m_e} \frac{\nabla^2 \sqrt{n}}{\sqrt{n}},$$

where the velocity is defined by $v = \nabla S/m_e$ and $d/dt = \partial_t + \mathbf{v} \cdot \nabla$. The last term of equation (3) is the gradient of the Bohm–de Broglie potential, and is due to the effect of wave
function spreading, giving rise to a dispersive-like term. We also note the striking resemblance of equations (2) and (3) to the classical fluid equations.

2.2. The Pauli equation

The nonrelativistic evolution of spin-1/2 particles, as described by the two-component spinor $\Psi(\alpha)$, is given by the Pauli equation (see, e.g. [18])

$$i\hbar \frac{\partial \psi}{\partial t} + \left[ \frac{\hbar^2}{2m_e} \left( \nabla + \frac{ie}{\hbar} A \right)^2 - \mu_B \mathbf{B} \cdot \mathbf{\sigma} + e\phi \right] \psi = 0,$$

where $A$ is the vector potential, $\mu_B = e\hbar/2m_e$ is the Bohr magneton and $\mathbf{\sigma} = (\sigma_1, \sigma_2, \sigma_3)$ is the Pauli spin vector.

Now, in the same way as in the Schrödinger case, we may decompose the electron wave function $\psi$ into its amplitude and phase. However, as the electron has spin, the wave function is now represented by a 2-spinor instead of a $c$-number. Thus, we may use $\psi = \sqrt{n} \exp(iS/\hbar)\phi$, where $\phi$, normalized such that $\phi^\dagger \phi = 1$, now gives the spin part of the wave function. Multiplying the Pauli equation (4) by $\psi^\dagger$, inserting the above wave function decomposition and taking the gradient of the resulting phase evolution equation, we obtain the conservation equations

$$\frac{dn}{dt} = -n \nabla \cdot \mathbf{v},$$

and

$$\frac{dv_i}{dt} = -\frac{e}{m_e} (E_i + \epsilon_{ijk} v_j B_k + \frac{\hbar^2}{2m_e^2} \frac{\partial}{\partial x_j} (\nabla^2 \sqrt{n})) - \frac{\mu_B}{m_e} \frac{\partial B_j}{\partial x_i} - \frac{\hbar^2}{4m_e^2 n} \frac{\partial}{\partial x_j} (n \Gamma_{ij}),$$

respectively, where $\epsilon_{ijk}$ is the fully antisymmetric (pseudo-)tensor and we have used Einstein’s sum convention so that a sum over indices occurring twice in a term is implied, where $i, j, k, \ldots = 1, 2, 3$. The spin contribution to equation (6) is consistent with the results of [28]. Here the velocity is defined by

$$\mathbf{v} = \frac{1}{m_e} \left( \nabla S - i\hbar \phi^\dagger \nabla \phi \right) + \frac{e\mathbf{A}}{m_ec},$$

the spin density vector is

$$\mathbf{s} = \phi^\dagger \mathbf{\sigma} \phi,$$

which is normalized according to \footnote{An alternative choice for the normalization would be to choose $|\sigma| = \hbar/2$.}

$$|\mathbf{s}| = 1,$$

and we have defined the symmetric gradient spin tensor

$$\Gamma_{ij} = \frac{\partial s_k}{\partial x_i} \frac{\partial s_k}{\partial x_j}.$$
We note that the last equation allows for the introduction of an effective magnetic field
\( B_{\text{eff}} \equiv \frac{(2\mu_B/h)B - \hbar/[(\partial_j(n\partial_j\bar{s}))/2m_e n]}{\partial_j(n\partial_j\bar{s})}. \) However, this will not be pursued further here (for a discussion, see [18]).

Comparing the effects due to spin from the Pauli dynamics with the Schrödinger theory, we see a significant increase in the complexity of the fluid-like equations due to the presence of spin. The fact that the spin couples linearly to the magnetic field makes the dynamical aspects of such Pauli systems very rich. Moreover, when going over to the collective regime, the back-reaction through Maxwell’s equation can yield interesting new properties of such spin plasmas. In fact, the introduction of an intrinsic magnetization can give rise to linear instability regimes, much like the Jeans instability.

2.3. Collective plasma dynamics

As pointed out in the previous section, the route from single wavefunction dynamics to collective effects introduces a new complexity into the system. At the classical level, the ordinary pressure is such an effect. In the quantum case, a similar term, based on the thermal distribution of spins, will be introduced.

The multistream model of classical plasmas was successfully introduced by Dawson [19]. Here we will focus on the electrostatic interaction between a multistream quantum plasma described within the Schrödinger model, a system first investigated in [21] (where also the stationary regime was probed). Thus, we have the governing equations (2) and (3) but for \( N \) beams of electrons on a stationary ion background, i.e. using this decomposition in equation (1), we obtain

\[
\frac{dn_\alpha}{dt} = -n_\alpha \nabla \cdot v_\alpha \tag{12}
\]

and

\[
\frac{dv_\alpha}{dt} = \frac{e}{m_e} \nabla \phi + \frac{\hbar}{2m_\alpha^2} \nabla \left( \frac{\nabla^2 \sqrt{n_\alpha}}{\sqrt{n_\alpha}} \right), \tag{13}
\]

now coupled through the self-consistent electrostatic potential governed by

\[
\nabla^2 \phi = \frac{e}{\epsilon_0} \sum_{\alpha=1}^{N} (n_\alpha - n_0). \tag{14}
\]

Here \( n_0 \) is the density of the stationary ion background.

In the one-stream case (\( \alpha = 1 \)), we have the equilibrium solution \( v = v_0 \) (a constant drift relative to the stationary ion background) and the constant electron density \( n = n_0 \) (such that \( \phi = 0 \)). Perturbing this system and Fourier decomposing the perturbations, such that \( n = n_0 + \delta n \exp[\text{i}(k \cdot x - \omega t)] \), \( v = v_0 + \delta v \exp[\text{i}(k \cdot x - \omega t)] \) and \( \phi = \delta \phi \exp[\text{i}(k \cdot x - \omega t)] \), we obtain [20, 21]

\[
(\omega - k \cdot v_0)^2 = \omega_p^2 + \frac{\hbar^2 k^4}{4m_e^2}, \tag{15}
\]

where the last term is the Bohm–de Broglie correction to the dispersion relation. Here we have the electron plasma frequency \( \omega_p = (e^2 n_0/\epsilon_0 m_e)^{1/2} \).

Similarly to the one-stream case, we obtain, in the two-stream model, the dispersion relation [21, 22]

\[
1 = \frac{\omega_p^2_{1}}{(\omega - v_{01} \cdot k)^2 - \hbar^2 k^4/4m_e^2} + \frac{\omega_p^2_{2}}{(\omega - v_{02} \cdot k)^2 - \hbar^2 k^4/4m_e^2}, \tag{16}
\]
Figure 1. A figure illustrating regions of importance in parameter space for various quantum plasma effects. The lines are defined by different dimensionless quantum parameters being equal to unity. The effects included in the figure are (i) Fermi pressure effects, described by the parameter 
\[ \frac{T_F}{T_e} \propto \frac{\bar{h}^2 n_0^2}{m k_B T_e} \]; (ii) effects due to the Bohm–de Broglie potential, described by the parameter \( \hbar \omega_{pe} / k_B T_e \); (iii) spin single-fluid Alfvénic effects, described by the parameter \( \bar{h}^2 \omega_{pe}^2 / m c^2 k_B T_e \); (iv) spin single-fluid acoustic effects, described by the parameter \( \mu_B B / m c^2 \). The quantum regime corresponds to lower temperatures, i.e. it exists below each of the three horizontal lines; (v) spin two-fluid nonlinear effects, described by the parameter \( \mu_B B_0 / m c^2 \). The quantum regime corresponds to higher densities, i.e. it exists to the right of each of the three vertical lines. Note that we have extended the range of the plot to some perhaps unphysical regions. This is done as a visual aid only and regions of extremely high density and low temperature are not relevant.

(This figure is in colour only in the electronic version)

for two propagating electron beams (with velocities \( v_{01} \) and \( v_{02} \)) with background densities \( n_{01} \) and \( n_{02} \). The quantum effect has a subtle influence on the stability of the perturbed plasma. For the case \( n_{01} = n_{02} = n_0 / 2 \) and \( v_{01} = -v_{02} = v_0 \), we have the instability condition

\[ \frac{4}{K^2} \left( 1 - \frac{1}{K^2} \right) < H^2 < \frac{4}{K^2}, \]  

(17)

in terms of the normalized wave number \( K = k v_0 / \omega_p \) and the quantum parameter \( H = \hbar \omega_p / m c v_0^2 \) (see figure 1) [21, 22]. We see that when \( H = 0 \), we have unstable perturbations for \( 0 < K < 1 \), but when \( H \neq 0 \) a considerably more complex instability region develops.

A model for treating partial coherence in such systems, based on the Wigner transform technique [15,23–25], can also be developed [22] (see also [26]). Moreover, using equations (5) and (6), a similar framework may be set up for electron streams with spin properties.

2.4. Fluid model

2.4.1. Plasmas based on the Schrödinger model. Suppose that we have \( N \) electron wave functions, and that the total system wave function can be described by the factorization \( \psi(x_1, x_2, \ldots, x_N) = \psi_1(x_1) \psi_2(x_2) \ldots \psi_N(x_N) \). For each wave function \( \psi_\alpha \), we have a corresponding probability \( P_\alpha \). From this, we first define \( \psi_\alpha = n_\alpha \exp(i \Sigma / \hbar) \) and follow the steps leading to equations (2) and (3). We now have \( N \) such equations for the wave
functions \( \{ \psi_a \} \). Defining \( n \equiv \sum_{a=1}^{N} p_a n_a \) (18) and
\[ v = \langle v_a \rangle = \sum_{a=1}^{N} p_a n_a v_a / n, \] (19)
we can define the deviation from the mean flow according to
\[ w_a = v_a - v. \] (20)
Taking the average, as defined by (19), of equations (2) and (3) and using the above variables, we obtain the quantum fluid equation
\[ \frac{dn}{dt} = -n \nabla \cdot v \] (21)
and
\[ \frac{dv}{dt} = \frac{e}{m_e} \nabla \phi - \frac{1}{nm_e} \nabla p + \frac{\hbar^2}{2m_e^2} \nabla \left( \frac{\nabla^2 \sqrt{n}}{\sqrt{n}} \right), \] (22)
where we have assumed that the average produces an isotropic pressure \( p = m_e n (|w_a|^2) \). We note that the above equations still contain an explicit sum over the electron wave functions.

For typical scale lengths larger than the Fermi wavelength \( \lambda_F \), we may approximate the last term by the Bohm–de Broglie potential \[ \langle \nabla^2 \sqrt{n} \rangle \approx \nabla^2 \sqrt{n}. \] (23)

Using a classical or quantum model for the pressure term, we finally have a quantum fluid system of equations. For a self-consistent potential \( \phi \) we furthermore have
\[ \nabla^2 \phi = \frac{e}{\epsilon_0} (n - n_i). \] (24)

### 2.4.2. Spin plasmas.

The collective dynamics of electrons with spin and some of the spin modifications of the classical dispersion relation was presented in [9]. Here we will follow [9] and [27] for the derivation of the governing equations. Suppose that we have \( N \) wave functions for the electrons with magnetic moment \( \mu_e = -\mu_B \), and that, as in the case of the Schrödinger description, the total system wave function can be described by the factorization \( \psi = \psi_1 \psi_2 \ldots \psi_N \). Then the density is defined as in equation (18) and the average fluid velocity defined by (19).

However, we now have one further fluid variable, the spin vector, and accordingly we let \( S = \langle s_a \rangle \). From this we can define the microscopic spin density \( S_a = s_a - S \), such that \( \langle S_a \rangle = 0 \).

Taking the ensemble average of equation (5) we obtain the continuity equation (21), while the ensemble average applied to equation (6) yields
\[ \frac{dv_i}{dt} = -\frac{e}{m_e} (E_i + \epsilon_{ijk} v_j B_k) - \frac{1}{nm_e} \frac{\partial p}{\partial x_i} + \frac{\hbar^2}{2m_e^2} \frac{\partial}{\partial x_i} \left( \frac{\nabla^2 \sqrt{n}}{\sqrt{n}} \right) + \frac{1}{nm_e} F^\text{spin}_i \] (25)
and the average of equation (11) gives
\[ \frac{dS_i}{dt} = \frac{2\mu_B}{\hbar} \epsilon_{ijk} B_j S_k - \frac{1}{nm_e} \frac{\partial \Sigma_{ij}}{\partial x_j} + \frac{1}{nm_e} \Omega_{ij}^\text{spin}. \] (26)
Here the force density due to the electron spin is
\[ F_{\text{spin}}^i = -\mu_B n S_j \frac{\partial B_j}{\partial x_i} \frac{\hbar}{4m_e} \frac{\partial}{\partial x_j} \left[ n \left( \Gamma_{ij} + \tilde{\Gamma}_{ij} \right) \right] \]
\[ - \frac{\hbar}{4m_e} \frac{\partial}{\partial x_j} \left[ n \frac{\partial S_k}{\partial x_j} \right] \frac{\partial}{\partial x_i} \left[ n \frac{\partial S_k}{\partial x_i} \right] + n \frac{\partial S_k}{\partial x_j} \frac{\partial}{\partial x_i} \left[ n \frac{\partial S_k}{\partial x_i} \right] , \]  
(27)
consistent with the results in [28], while the asymmetric thermal spin coupling is
\[ \Sigma_{ij} = n m_e \langle S_{ai} w_{aj} \rangle \]  
(28)
and the nonlinear spin-fluid correction is
\[ \Omega_{ij}^\text{spin} = \frac{\hbar}{2} \epsilon_{ijk} S_j \left[ \frac{\partial}{\partial x_k} \left( n \frac{\partial S_k}{\partial x_i} \right) \right] + \frac{\hbar}{2} \epsilon_{ijk} S_j \left[ \frac{\partial}{\partial x_i} \left( n \frac{\partial S_k}{\partial x_k} \right) \right] \]
\[ + n \frac{\hbar}{2} \epsilon_{ijk} \left[ S_{ai} \frac{\partial}{\partial x_i} \left( n \frac{\partial S_k}{\partial x_a} \right) \right] + n \frac{\hbar}{2} \epsilon_{ijk} \left[ S_{ak} \frac{\partial}{\partial x_k} \left( n \frac{\partial S_i}{\partial x_a} \right) \right] \right] \right] , \]  
(29)
where \( \Gamma_{ij} = (\partial_i S_a) (\partial_j S_a) \) is the nonlinear spin correction to the classical momentum equation, \( \tilde{\Gamma}_{ij} = ((\partial_i S_{a/0}) (\partial_j S_{a/0})) \) is a pressure like spin term (which may be decomposed into a trace-free part and trace). We note that, apart from the additional spin density evolution equation (26), the momentum conservation equation (25) is considerably more complicated compared with the Schrödinger case represented by (22). Moreover, equations (25) and (26) still contain the explicit sum over the \( N \) states, and have to be approximated using insights from quantum kinetic theory or some effective theory.

The coupling between the quantum plasma species is mediated by the electromagnetic field. By definition, we let \( H = B / \mu_0 - M \) where \( M = -2 n \mu_B S / \hbar \) is the magnetization due to the spin sources. Ampère's law \( \nabla \times H = j + \epsilon_0 \partial_t E \) takes the form
\[ \nabla \times B = \mu_0 (j + \nabla \times M) + \frac{1}{c^2} \frac{\partial E}{\partial t} , \]  
(30)
where \( j \) is the free current contribution. The system is closed by Faraday's law
\[ \nabla \times E = -\frac{\partial B}{\partial t} . \]  
(31)
It should be noted that electrons produce a pure magnetic moment contributing to a magnetization in their rest frame. Thus in the case where the electrons are moving in the laboratory frame, the spin of the electrons contributes also to a polarization \( P \) and polarization currents \( \partial P / \partial t \) that should be added to the right-hand side of equation (30). However, this is a weakly relativistic effect, which also requires the spin–orbit coupling to be added to the Pauli–Hamiltonian for a consistent treatment. In the rest of this paper we will limit ourselves to the nonrelativistic treatment corresponding to equation (4), in which case polarization currents due to the spin must be left out in Ampère’s law.

2.5. The magnetohydrodynamic limit

The concept of a magnetoplasma was first introduced in the pioneering work [29] by Alfvén, who showed the existence of waves in magnetized plasmas. Since then, magnetohydrodynamics (MHD) has found applications in a vast range of fields, from solar physics and astrophysical dynamos, to fusion plasmas and dusty laboratory plasmas.

Magnetic fields, an essential component in the MHD description of plasmas, also couples directly to the spin of the electron. Thus, the presence of spin alters the single electron dynamics, introducing a correction to the Lorentz force term. Indeed, from the experimental
perspective, a certain interest has been directed towards the relation of spin properties to the classical theory of motion (see, e.g. [30–42]). In particular, the effects of strong fields on single particles with spin has attracted experimental interest in the laser community [32–36, 38]. However, the main objective of these studies was single particle dynamics, relevant for dilute laboratory systems, whereas our focus will be on collective effects.

We will now include the ion species, which are assumed to be described by the classical equations and have charge \( Ze \). We can then derive a set of one-fluid equations [27]. The ion equations read

\[
\frac{dn_I}{dt} = -n_I \nabla \cdot v_I \tag{32}
\]

and

\[
m_I n_I \frac{dv_I}{dt} = Ze n_I (E_i + \epsilon_{ijk} v_I j B_k) - \frac{\partial p_I}{\partial x_i} \tag{33}
\]

Next we define the total mass density \( \rho \equiv (m_e n + m_I n_I) \), the centre-of-mass fluid flow velocity \( V \equiv (m_e n v_e + m_I n_I v_I)/\rho \) and the current density \( j = -en_e v_e + Zen_I v_I \). Using these definitions, we immediately obtain

\[
\frac{d\rho}{dt} = -\rho \nabla \cdot V, \tag{34}
\]

from equations (21) and (32). Assuming quasi-neutrality, i.e. \( n \approx Z n_I \), the momentum conservation equations (25) and (33) give

\[
\rho \frac{dV}{dt} = \epsilon_{ijk} j j B_k - \frac{\partial \Pi_{ij}}{\partial x_j} - \frac{\partial p}{\partial x_i} + \frac{Z \hbar^2 \rho}{2m_e m_I} \frac{\partial}{\partial x_i} \left( \nabla^2 \sqrt{\rho} \right) + F_{\text{spin}}, \tag{35}
\]

where \( \Pi \) is the trace-free pressure tensor in the centre-of-mass frame and \( P \) is the scalar pressure in the centre-of-mass frame. We also note that due to quasi-neutrality, we have \( n_e \approx Z \rho / m_I \) and \( v = V - m_I j / Ze \rho \), and we can thus express the quantum terms in terms of the total mass density \( \rho \), the centre-of-mass fluid velocity \( V \), and the current \( j \). With this, the spin transport equation (26) reads

\[
\rho \frac{dS_i}{dt} = \frac{m_e}{Ze} j j \frac{\partial S_i}{\partial x_j} + \frac{2\mu_0 \rho}{\hbar} \epsilon_{ijk} B_j S_k - \frac{m_I}{Z} \frac{\partial \Sigma_{ij}}{\partial x_j} + \frac{m_I}{Z} \Omega_{\text{spin}}. \tag{36}
\]

In the momentum equation (35), neglecting the pressure and the Bohm–de Broglie potential for the sake of clarity, we have the force density \( j \times B + F_{\text{spin}} \). In general, for a magnetized medium with magnetization density \( M \), Ampère’s law gives the free current in a finite volume \( V \) according to

\[
\mathcal{J} = \left( \frac{1}{\mu_0} \nabla \times B - \nabla \times M \right), \tag{37}
\]

where we have neglected the displacement current. The surface current is an important part of the total current when we are interested in the forces on a finite volume, as was demonstrated in [27] and will be shown below.

It worth noting that the expression for the force density, occurring in the momentum conservation equation, can to lowest order in the spin be derived on general macroscopic grounds. Formally, the total force density on a volume element \( V \) is defined as \( \mathbf{F} = \lim_{v \to 0} (\sum_a f_a / V) \), where \( f_a \) are the different forces acting on the volume element, and might include surface forces as well. For magnetized matter, the total force on an element of volume \( V \) is then

\[
f_{\text{tot}} = \int_V \mathcal{J} \, dV + \oint_{\partial V} (M \times \mathbf{n}) \times \mathbf{B} \, dS, \tag{38}
\]
where (neglecting the displacement current) \( j_{\text{tot}} = j + \nabla \times M \). Inserting the expression for the total current into the volume integral and using the divergence theorem on the surface integral, we obtain the force density

\[
F_{\text{tot}} = j \times B + M_k \nabla B_k, \tag{39}
\]

identical to the lowest order description from the Pauli equation (see equation (35)). Inserting the free current expression (37), due to Ampère’s law, we can write the total force density according to

\[
F_i = - \partial_i \left( \frac{B^2}{2\mu_0} - M \cdot B \right) + \partial_k (H_i B_k). \tag{40}
\]

The first gradient term in equation (40) can be interpreted as the force due to a potential (the energy of the magnetic field and the magnetization vector in that field), while the second divergence term is the anisotropic magnetic pressure effect. Noting that the spatial part of the stress tensor takes the form [28]

\[
T_{ik} = -\partial_i \left( \frac{B^2}{2\mu_0} - M \cdot B \right) \delta_{ik}, \tag{41}
\]

we see that the total force density on the magnetized fluid element can be written \( F_i = -\partial_i T_{ik} \), as expected. Thus, the Pauli theory results in the same type of conservation laws as the macroscopic theory. The momentum conservation equation (35) then reads

\[
\rho \left( \frac{\partial}{\partial t} + \mathbf{V} \cdot \nabla \right) \mathbf{V} = -\nabla \left( \frac{B^2}{2\mu_0} - M \cdot B \right) + B_k \partial_k H - \nabla p, \tag{42}
\]

where for the sake of clarity we have assumed an isotropic pressure, dropped the displacement current term in accordance with the nonrelativistic assumption, and neglected the Bohm potential (these terms can of course simply be added to (42)). This concludes the discussion of the spin-MHD plasma case. Next, we will look at some applications of the derived equations. However, it should be noted that in many cases the spins are close to thermodynamic equilibrium, and we can thus write the paramagnetic electron response in terms of the magnetization [27]

\[
M = \frac{\mu_B \rho}{m_I} \tanh \left( \frac{\mu_B B}{k_B T} \right) \hat{B}, \tag{43}
\]

instead of using the full spin dynamics. Here \( B \) denotes the magnitude of the magnetic field and \( \hat{B} \) is a unit vector in the direction of the magnetic field, \( k_B \) is Boltzmann’s constant and \( T \) is the electron temperature.

### 3. Spin quantum kinetics

Quantum mechanics in terms of quasi-distribution functions is perhaps the formulation with the closest resemblance to classical statistical mechanics. The formulation started with Wigner’s paper [15] together with Weyl’s correspondence principle [43]. In terms of this formulation the state of the system is no longer described by a density matrix but instead a phase-space distribution function. Similarly operators are translated into phase-space functions. Calculating the expectation value of an operator is then a matter of calculating a phase-space integral over a corresponding function weighted by the distribution function. The method has been applied to a wide range of problems. For example in optics [44, 45], collision theory [46, 47], nonlinear theory [48] and transport problems in solid state physics, see, e.g. [49, 50] and references therein.
There are many different ways to define a quasi-distribution function in quantum mechanics. The most well-known examples are probably the Glauber–Sudarshan \(P\)-distribution [51, 52], the \(q\)-distribution [53] and the related Husimi distribution [54]. The many different definitions come from the fact that the position and momentum operators do not commute, so the transformation between an operator and a phase-space function is not unique. See, e.g. [55] for a review of the different phase-space distribution functions. The Wigner distribution corresponds to ordering the position and momentum operators symmetrically.

When considering a particle in a magnetic field gauge invariance has to be assured. This can be done by adding a phase factor to the definition of the Wigner function [56]. The phase factor will then compensate for the change in phase that occurs in the density matrix when performing a gauge transformation. When dealing with the gauge invariant Wigner–Stratonovich distribution the Weyl correspondence is modified [57]. The natural variables to use are the position and \textit{kinetic} momentum.

The formulation of quantum mechanics in terms of phase-space distributions has also been generalized for spin particles [58–61]. Also in this case the definition is not unique and one can find analogues to the different definitions in the phase-space case [58].

\subsection{3.1. Scalar quasi-distribution theory for a spin plasma}

The distribution function which we will work with here is the combination of a Wigner distribution function [15] for the phase-space variables and a \(q\)-function for the spin degree of freedom [60]. This combination of distribution functions was used in [16] and it turns out to yield an intuitive description of spin-\(1/2\) particles in an extended phase space.

For a \(2 \times 2\) density matrix \(\rho(x, y, t)\) describing a spin-\(1/2\) particle the corresponding extended phase-space distribution function is defined by

\[
 f(x, p, s, t) = \frac{1}{4\pi} \text{Tr} \left[ (1 + s \cdot \sigma) W(x, p, t) \right],
\]

where \(\text{Tr}\) denotes that the trace is to be calculated for the resulting \(2 \times 2\) matrix and where \(\sigma\) is a vector with the Pauli matrices as components, \(s\) is a vector on the unit sphere. The Wigner distribution matrix function is given by

\[
 W(x, p, t) = \int \frac{d^3y}{(2\pi\hbar)^3} e^{-i\hbar q \left[ \frac{1}{2} \sigma \cdot A(x+y,t) \right]} \rho \left( x + \frac{y}{2}, x - \frac{y}{2}, t \right),
\]

where \(q\) is the charge of the particle and \(A\) is the vector potential. The integral over the vector potential is there to ensure gauge invariance. The momentum variable \(p\) is the gauge invariant kinetic momentum related to the canonical momentum \(p_c\) by \(p = p_c - qA(x, t)\). This distribution function is defined on an extended phase-space \((x, p, s)\) and can in principle be used to calculate the expectation value of any observable defined by an operator \(\hat{O} = O(\hat{x}, \hat{p}, \sigma)\). The way to do this is to use the modified Weyl correspondence [57] together with a transformation for the spin variable to obtain a phase-space function, and subsequently take the average of this function weighted by the distribution function. For an operator depending on \(\hat{x}, \hat{p}\) the corresponding phase-space function is obtained by

\[
 O(x, p) = \int d^3y e^{-i\hbar q \left[ \frac{1}{2} \sigma \cdot A(x+y,t) \right]} \rho \left( x + \frac{y}{2}, x - \frac{y}{2} \right) \bigg| O \bigg| x - \frac{y}{2} \bigg). 
\]

Alternatively, the function \(O(x, p)\) can be found by first putting the position and kinetic momentum operators of the operator \(\hat{O}\) in symmetric order using the commutation relation and then make the substitution \(\hat{x} \rightarrow x\) and \(\hat{p} \rightarrow p\). For example the pressure tensor which just contains the kinetic momentum operator is obtained by \(\hat{P}_{ij} = \hat{p}_i \hat{p}_j \rightarrow p_ip_j\). Note that for
the gauge dependent Wigner distribution this correspondence is not so simple anymore, since we are then dealing with the position and canonical momentum operators which have to be ordered symmetrically using the commutation relation. So for the pressure tensor above, for example, we have to put the combination

\[ \hat{P}_{ij} = \left[ \hat{p}c_i - qA_i(\hat{x}) \right]\left[ \hat{p}c_j - qA_j(\hat{x}) \right] \]

in symmetric ordering and then make the substitution \( \hat{x}_i \rightarrow x_i \) and \( \hat{p}_i \rightarrow p_i \). This is a difficult task for a general operator since the form of the vector potential is not necessarily known.

The spin space function corresponding to an operator \( \hat{O} \) depending on \( \sigma \) is obtained by transformation

\[ \hat{O}(s) = \frac{1}{4\pi} \text{Tr}[ (1 + s \cdot \sigma) \hat{O} ] \]  

(47)

If the operator in question depends on both the position and momentum operators and the spin, both of these transformations have to be made, see [16]. Since \( \sigma^2 = 1 \) the only possible spin operator we may have is the identity operator 1 and \( \sigma \). Transformation (47) above yields

\[ \hat{O} = \sigma \rightarrow \hat{O}(s) = 3s. \]  

(48)

The momentum variable in the Wigner function above is the canonical momentum. In the presence of a magnetic field it is often more convenient to work with the gauge invariant kinetic momentum.

3.2. Evolution and the long scale-length limit

The Hamiltonian for a spin-1/2 particle in a magnetic field is given by

\[ \hat{H} = \frac{\left[ \hat{p} \cdot A(\hat{x}, t) \right]^2}{2m} + qV + \mu_B \sigma \cdot B(\hat{x}, t), \]  

(49)

where \( V \) and \( A \) are the electromagnetic potentials, \( B = \nabla \times A \) is the magnetic induction and \( \mu_B \) is the magnetic moment of the particle. Specifically, for an electron, the magnetic moment is given by \( \mu_B = q\hbar/(4m) \) where \( g \approx 2.001 \) is a correction factor deduced from quantum electrodynamics [62]. Note that we have used \( q = -|e| \) so that the magnetic moment is negative. The evolution equation for the density operator is given by the von Neumann equation

\[ i\hbar \partial_t \rho = [\rho, \hat{H}]. \]  

(50)

Taking transform (44) of this equation, it is possible to derive an evolution equation for the extended phase-space Wigner function \( f(x, p, s, t) \), see [16], and it is given by

\[ \frac{\partial f}{\partial t} + (v + \Delta \vec{v}) \cdot \nabla_x f + \frac{q}{m} \left[ \vec{E} + (v + \vec{v}) \times \vec{B} \right] \cdot \nabla_v f \]

\[ + \frac{\mu_B}{m} \nabla_s \left[ (s + \nabla_s) \cdot \vec{B} \right] \cdot \nabla_v f + \frac{2\mu_B}{\hbar} (s \times \vec{B}) \cdot \nabla_s f = 0, \]

(51)

where \( v = p/m \) is the velocity and we have defined the operators

\[ \vec{E} = E(x) \int_{-1/2}^{1/2} ds \cos \left( \frac{\hbar s}{m} \nabla_x \cdot \nabla_v \right) \]  

(52)

\[ \vec{B} = B(x) \int_{-1/2}^{1/2} ds \cos \left( \frac{\hbar s}{m} \nabla_x \cdot \nabla_v \right) \]  

(53)

\[ \Delta \vec{v} = \frac{q\hbar}{m^2} B(x) \int_{-1/2}^{1/2} dss \sin \left( \frac{\hbar s}{m} \nabla_x \cdot \nabla_v \right) \cdot \nabla_v. \]  

(54)
Here the arrows on the differential operators indicate in which direction they will act. Note the similarity of the equation above with the classical Vlasov equation. In order to compare it further we may consider the semiclassical limit which is applicable when the typical length scale is much shorter than the de Broglie wave length $\hbar/(mv)$, where $v$ is the typical velocity of the system. We may then expand the sine and cosine operators above. Keeping terms up to order $\hbar^2$ the resulting equation is

$$\frac{\partial f}{\partial t} + v \cdot \nabla_x f + \frac{q}{m} [E + v \times B] + \frac{\mu_B}{m} \nabla_s [(s + \nabla_s) \cdot B] \cdot \nabla_v f + \frac{2\mu_B}{\hbar} (s \times B) \cdot \nabla_s f = 0.$$  

(55)

The first term proportional to the spin $s$ is the dipole force of a magnetic moment in an inhomogeneous magnetic field and the last term accounts for the spin precession. Both of these can be understood from a classical analogue; however, there is also a quantum dipole term given by $(\mu_B/m) \nabla_s (B \cdot \nabla_s) \cdot \nabla_v f$. This term accounts for the fact that the spin is not a classical dipole and we can, for example, not have a distribution function proportional to $\delta(s - \hat{z})$, where $\hat{z}$ is a unit vector in the $z$-direction. The corresponding distribution function in the quantum mechanical case is proportional to $1 + \cos \theta_s$ where $\theta_s$ is the angle between the spin direction and the $z$-axis. The macroscopic magnetization of the classical and quantum cases are still the same which is ensured by the factor 3 in transformation (48). This factor occurs in the quantum case

$$M_q(x) = 3\mu_B \int d\Omega f(x, v, s),$$  

(56)

but is absent in the corresponding classical equation

$$M_{cl}(x) = \mu_B \int d\Omega s f_{cl}(x, v, s),$$  

(57)

where $f_{cl}$ is the classical distribution function and we in both cases have $d\Omega = d^3v \, d^2s$.

A semiclassical version of equation (55) (where the quantum dipole term is missing) has been applied to find a new type of resonance due to radiative corrections to the electron $g$-factor [63]. A related kinetic equation has also been applied in the context of thermonuclear fusion [14]. In this model, however, both the dipole and the quantum dipole terms are missing. This equation can formally be retained from our result above by neglecting all terms of order $\hbar$ or higher.

3.3. Thermal equilibrium

The scalar spin distribution also has some other important differences compared with the distribution for a classical dipole. An important example is the thermal equilibrium distribution. In the classical case it is given by

$$f_{cl}^T(v, s) = n_0 f_M(v) \frac{1}{4\pi} \frac{\mu_B B_0}{k_B T} \left[ \sinh \left( \frac{\mu_B B_0}{k_B T} s \right) \right]^{-1} \exp \left[ -\frac{\mu_B B_0 \cdot s}{k_B T} \right],$$  

(58)

where $n_0$ is the equilibrium density, $f_M$ is the usual Maxwellian–Boltzmann distribution, $k_B$ is Boltzmann’s constant, $T$ is the temperature and $B_0$ is the external magnetic field. This distribution gives rise to a magnetization

$$M_{cl}^T = n_0 \mu_B \eta \left( \frac{\mu_B B_0}{k_B T} \right),$$  

(59)
where $\eta$ is the Langevin function. In the quantum mechanical case the corresponding distribution function becomes (assuming that the chemical potential is sufficiently large so that Landau quantization can be neglected, see [16])

$$f^T_q(v, s) = n_0 f_M(v) \frac{1}{4\pi} \left[ 1 + \tanh \left( \frac{\mu B_0}{k_B T} \right) \cos \theta_s \right],$$

(60)

where $\theta_s$ is the angle between the spin vector and the z-axis. The zeroth order magnetization in this case is given by

$$M^T_q = 3\mu_B \int d\Omega_s f_q = n_0 \mu_B \tanh \left( \frac{\mu B_0}{k_B T} \right),$$

(61)

as expected. The dynamics of the magnetization can be treated by the use of a fluid moment hierarchy as we discuss in the following section.

4. Spin-fluid moments

Many problems do not require the full machinery of the kinetic approach and calculations can be significantly simplified if executed in a macroscopic fluid model instead (see, e.g. [64] and references therein). In particular, when dealing with nonlinear problems the kinetic approach soon becomes very cumbersome and the need for a simplified theory cannot be understated.

In this section such a theory will be presented, derived from the kinetic theory by taking moments of the quantum kinetic equation [16] in a way analogous to what is done in classical plasma theory (see, e.g. [64]). The theory presented here was derived in [17]. As in the classical approach all intrinsically kinetic features such as Landau damping will be lost, and one is faced with a closure problem, since the fluid hierarchy is an infinite series of equations that needs to be truncated at some point.

Quantum fluid moments derived from the Wigner formalism have been applied before, see, e.g. [65, 66], and also in the case of gauge invariant Wigner–Stratonovich formalism [67]. In the spin-1/2 case the moments have also been calculated [69] starting from a matrix form of the quantum kinetic equation [68]. In [68, 69] effects due to the collisions are retained, but we will neglect these here. However, their fluid hierarchy is only discussed shortly and also it is derived to order $\hbar$ and hence, for example the effect of the dipole term on the dynamics was not retained.

4.1. One-fluid model

Since we are working with a quasi-distribution function in a phase space extended to also include the microscopic spin variable, the classical approach must be slightly modified. Firstly we also need to integrate over the microscopic spin variable, and furthermore a new macroscopic spin variable is defined, leading to a new hierarchy of spin-dependent macroscopic objects [17]. Thus we define the moments as

$$n = \int d\Omega f,$$

(62)

$$u = \frac{1}{n} \int d\Omega v f,$$

(63)

$$P_{ij} = m \int d\Omega (v_i - u_i)(v_j - u_j) f,$$

(64)

$$Q_{ijk} = m \int d\Omega (v_i - u_i)(v_j - u_j)(v_k - u_k) f,$$

(65)
\[ S = \frac{3}{n} \int d\Omega s f, \quad (66) \]
\[ \Sigma_{ij} = m \int d\Omega (3s_i - S_i)(v_j - u_j) f, \quad (67) \]
\[ \Lambda_{ijk} = m \int d\Omega (3s_i - S_i)(v_j - u_j)(v_k - u_k) f. \quad (68) \]

Here the first four moments are, respectively, the density, the fluid velocity, the pressure density and the energy flux density. Equation (66) above defines the spin density \( S = S(x, t) \) which yields the average spin density at position \( x \) and time \( t \). The factor 3 in this definition occurs due to the correspondence (48). The sixth moment \( (67) \) is a mixed moment of the velocity and the spin which will act as some kind of spin pressure. Finally, we have a mixed spin-velocity–velocity moment which could perhaps be termed the spin pressure correlation. Similarly we could go on to define even higher order moments. Note that there is no need to include higher order moments in the spin variable since we have that \( \int d\Omega \hat{s}_i \hat{s}_j \propto \delta_{ij} \).

Using the evolution equation for the extended phase-space distribution function (55) we may now calculate the evolution equation of the different moments:

\[ \frac{d\Sigma_{ij}}{dt} = - \frac{\Sigma_{ik}}{\partial x_k} \frac{\partial U_j}{\partial x_k} - \frac{\Sigma_{ik}}{\partial x_k} \frac{\partial U_j}{\partial x_k} - \frac{\partial S_i}{\partial x_k} + \frac{m}{\partial S_i} \frac{\partial \Sigma_{ij}}{\partial x_k} + \frac{2\mu}{\hbar} \frac{\partial B_j}{\partial x_k} + \frac{\partial \Sigma_{ij}}{\partial x_k}, \quad (71) \]

As can be seen in equation (72), the spin-velocity moment \( \Sigma_{ij} \) acts as a pressure term in the evolution equation for the spin density. By including this moment, it is possible to capture some kinetic effects in a fluid theory. Some problems which might be difficult or tedious to solve in a kinetic theory may be reachable within a fluid theory. However, the exact role of the spin-velocity moment is a subject of further research.

4.2. Two-fluid model

It is shown in the previous section treating the kinetic equation that the distribution function can be divided in two parts, one for each spin direction along the magnetic field. Each fluid is seen to obey the same hierarchy as above [17], and we will just have two sets of these equations, one for each species. Of course we will have separate macroscopic quantities \( n_\alpha \),...
\( v_\alpha, S_\alpha \) and \( \Sigma_\alpha \) for each species. Here the subscript \( \alpha \) indicates which species the quantities refer to. This approach adds a bit of complexity but can capture some kinetic effects due to the different dynamics of the two spin states, and is therefore worth pursuing in problems where such physics is expected to play a role \[78\].

5. Applications of fluid and kinetic models

The various quantum models developed cover several physical effects. Effects of the Fermi pressure and particle dispersion have been described in some detail in \[1, 2\] both within fluid theories and within a kinetic approach. The fluid approach uses the so-called Bohm–de Broglie potential to get an effective quantum force in the momentum equation, and the equation of state is chosen such as to get the Fermi pressure. Several modifications of classical behaviour due to such models have been described in the literature, see the references in \[1\] for an up-to-date list. Many papers using kinetic approaches cover the effects of particle dispersion and Fermi pressure, but using a Wigner function derived without the magnetic dipole coupling of the Pauli–Hamiltonian. In this way all effects due to the magnetic dipole force and spin magnetization are left out. In contrast to these works, here we will focus on physical effects directly associated with the spin coupling in the Pauli–Hamiltonian, which gives rise to the magnetic dipole force, the spin precession and the spin magnetization in the above presented models. Most of the recent results along these lines have been derived from models similar to those presented here.

5.1. Results from spin-fluid theories

The most basic question to ask concerning the electron spin properties in a plasma is ‘when are they important?’ For spin effects due to the Fermi pressure this is straightforward to answer. The Fermi pressure becomes important when the Fermi temperature approaches the thermodynamic temperature, which gives a simple condition on the temperature and density of a plasma. For the effects due to the direct spin coupling in the Pauli–Hamiltonian the answer is less straightforward, as it depends on the full parameter regime (involving also the magnetic field strength) but also on the specific geometry of the fields. During certain geometric configurations, the spin effects can be important in regimes of modest density and modest temperature, which traditionally have been thought to be completely classical \[70\]. A specific example of this kind can be found in the MHD regime. In \[70\] fluid equations of type \( (25)–(26) \) were adopted to the MHD regime, in order to study the physics of nonlinear spin-modified Alfvén waves. Within linear theory, the Alfvén waves were almost unaffected by the spin terms, provided the Zeeman energy associated with the unperturbed magnetic field \( B_0 \) was much smaller than the thermal energy, i.e. \( \mu_B B_0 \ll k_B T \). This condition holds for most plasmas except those close to pulsars and/or magnetars. However, nonlinearly the situation is different. Reference \[70\] used a two-fluid spin model based on \( (25)–(26) \), where spin-up and spin-down populations were formally treated as different species, as a mean to capture certain kinetic effects within a more simple fluid theory. From this theory a nonlinear Schrödinger equation

\[
i \partial_t B_1 + \frac{v'_g}{2} \partial^2_\zeta B_1 + \frac{Q |B_1|^2}{B_0^2} B_1 = 0
\]  

(74)

for Alfvén waves propagating parallel to the magnetic field was derived, where \( B_1 \) is the slowly varying magnetic field amplitude, \( v'_g = d v_g / d k \) is the group dispersion, \( \zeta = z - v_g t \) is the comoving coordinate and \( v_g \) is the group velocity. These quantities are determined from
the Alfvén wave dispersion relation, which reads \( \omega^2 = k^2 c_A^2 (1 \pm k c_A / \omega_c) \), when weakly dispersive effects due to the Hall current are included [71]. Here \( c_A \) is the Alfvén velocity and \( \omega_c \) is the ion-cyclotron frequency. The upper (lower) sign corresponds to right (left) hand circular polarization. The nonlinear coefficient is \( Q = Q_c [1 - (2 \mu_B B_0 / m c_A)^2] \), where the classical coefficient is \( Q_c = k c_A^3 / 4 (c_A^2 - c_s^2) \simeq -k c_A^3 / 4 c_s^2 \), where \( c_s \) is the ion-sound speed. Although linearly the modification of the Alfvén waves can be neglected (for modest temperature and densities), the nonlinear coefficient \( Q \) could be significantly affected by the spin terms. Illustration of the parameters needed to make the different quantum plasma effects significant is shown in figure 1. In particular, we note that the two-fluid nonlinear spin effects are important for high plasma densities and/or a weak (external) magnetic field. For comparison, both the Fermi pressure and the Bohm–de Broglie potential need a low temperature or a very high density to be significant. A somewhat surprising result is that here nonlinear spin effects tend to be more important for a lower magnetic field, whereas the opposite is true for linear spin effects.

As a second example of spin-fluid effects we will consider the ponderomotive force of an electromagnetic wave propagating along an external magnetic field. Classically, the density fluctuations induced by the ponderomotive force of an electromagnetic (EM) wave lead to an electrostatic wake field [72], as used in advanced particle accelerator schemes [73]. In other regimes, the back-reaction on the EM wave due to the density fluctuations leads to phenomena such as soliton formation, self-focusing or wave collapse [74, 75]. When spin effects based on equations (25)–(26) are included, the spin contribution to the ponderomotive force, resulting from the combined effect of the magnetic dipole force and spin precession, leads to a separation of spin-up and -down populations. The expression for the ponderomotive force density for electromagnetic waves propagating along the unperturbed magnetic field \( B_0 = B_0 \hat{z} \) can be divided into its classical part

\[
F_{\alpha z} = -\frac{e^2}{2m^2 \omega (\omega \pm \omega_c)} \left[ \frac{\partial}{\partial z} \pm \frac{k \omega_c}{\omega (\omega \pm \omega_c)} \frac{\partial}{\partial t} \right] |E|^2 \tag{75}
\]

where \(+(-)\) correspond to right (left) hand circular polarization, and the spin part ([78])

\[
F_{\alpha z} = \pm \frac{2 \mu^2}{m \hbar} \frac{S_{\alpha h}}{(\omega \pm \omega_g)} \left[ \frac{\partial}{\partial z} - \frac{k}{(\omega \pm \omega_g)} \frac{\partial}{\partial t} \right] |B|^2 \tag{76}
\]

Here \( E \) and \( B \) are the electric and magnetic field amplitude, respectively, \( \omega_c = e B_0 / m \) is the cyclotron frequency, \( \omega_g = 2 \mu_B B_0 / \hbar = g \omega_c / 2 \). The index \( \alpha = (u, d) \) refers to the up and down populations, respectively. In particular, the up- and down-spin vector components are \( S_{hu} = 1 \) and \( S_{hd} = -1 \). Thus it is clear that the spin part of the ponderomotive force induces a separation of the up and down populations. This effect survives also in the absence of an external magnetic field, and it turns out that the magnitude of the relative up- and down-density perturbations can be larger than the classical density perturbations in an unmagnetized plasma, provided

\[
1 < \frac{\hbar \omega \omega_g^2 L^2}{m c^2 \varepsilon} \tag{77}
\]

where \( L \) is the pulse length of the high-frequency pulse. The first factor of the right-hand side of (77) is smaller than unity for frequencies below the Compton frequency, but the second factor can be large for long pulse lengths, and hence large spin polarization can be induced by a sufficiently long EM-pulse in an unmagnetized plasma for optical frequencies and higher.
Once the plasma is spin polarized, the spin terms in the evolution equations can be important for the dynamics. For further studies of results from spin-fluid theories, see, e.g. [76, 77].

5.2. Results from spin-kinetic theories

The full kinetic theory (51) is accurate, but cumbersome for many purposes. As seen from equation (51), the effects separate quite naturally into particle dispersive effects (which are insignificant for spatial scale lengths much longer than the characteristic de Broglie wavelength), and effects due to the electron spin. The particle dispersive effects have been studied in some detail in e.g. [1, 2]. Focusing on the spin effects rather than particle effects, we can therefore consider the long scale-length equation (55). An interesting effect of spin-kinetic theory is the appearance of new wave–particle resonances. Linearized theory in a magnetized plasma can be solved in much the same way as in a classical plasma (see, e.g. [63] for technical details). However, due to the fact that the spin-precession frequency \( \omega_g \) and the Larmor gyration occurs \( \omega_c \) are slightly different (i.e. \( \omega_g = (g/2)\omega_c \approx 1.001\omega_c \)) new resonances appear. In particular, the denominators of the perturbed distribution function in kinetic theory are replaced as

\[
\frac{1}{(\omega - k_z v_z - n\omega_c)} \rightarrow \frac{1}{(\omega - k_z v_z - n\omega_c - m\omega_g)}
\]

(78)

when spin-kinetic effects are included, where the integer \( n \) covers \( \pm \infty \) and \( m = \pm 1 \). Thus for a fixed parallel phase velocity, resonant wave–particle interaction can occur at a much lower temperature when spin effects are taken into account, since \( |\omega_c - \omega_g| \ll |\omega_c| \). This aspect has been discussed in some detail in [16]. Furthermore, for perpendicular propagation to the external magnetic field, new Bernstein-like modes appear with frequencies close to the resonant value \( \omega = \Delta \omega_c = |\omega_e - \omega_g| \). Specifically, the dispersion relation for perpendicular propagation reads

\[
\omega^2 = k^2 c^2 + \omega_p^2 \int \left\{ J_0^2 \left( k_\perp v_\perp / \omega_c \right) + \frac{k^2 \hbar^2 \Delta \omega_c \sin^2 \theta_s}{4m_e (\omega - \Delta \omega_c) k_B T} \left[ J_1^2 \left( k_\perp v_\perp / \omega_c \right) \right] \right\} f_0 \, d\Omega,
\]

(79)

where \( J_0 \) and \( J_1 \) are zero and first order Bessel functions, respectively. Here we have assumed the classical terms involving higher order Bessel functions are negligible, which is accurate for \( \omega \ll |\omega_c| \). The numerical solutions of (79) reveal that the wave frequency only deviates slightly from the resonance \( \Delta \omega_c \) for most parameters [63]. It should be noted that a Madelung approach (cf equations (25)–(26)) cannot capture the physics of the resonances at \( \omega \approx \Delta \omega_c \). However, the moment theory (69)–(73) correctly recovers the dispersion relation in the low temperature limit [17]. Due to the higher order moments, however, it should be noted that this theory is computationally somewhat more demanding than equations (25)–(26), at least if the higher order spin effects are omitted in that theory. Other work on spin-kinetic theory includes [80], where the general linear theory based on (55) was studied in a magnetized plasma [14], where a simpler version of (55) (a semiclassical correspondence without the magnetic dipole force term) was studied with regard to fusion applications, and [79] where a semiclassical version of (55) was adopted to consider spin induced damping of electron plasma oscillations.

6. Summary and discussion

A rapid development of spin models for plasmas has taken place during the last few years, using different types of methods. The most accurate is the kinetic approach, based on the combined Wigner and \( q \)-transforms of the density matrix. This theory captures not only the
spin effects but also the particle dispersive effects. However, for scale lengths longer than the characteristic de Broglie wavelengths only the spin effects remain, as described by (55). While the kinetic approach is accurate, and contains much interesting physics, as for example the resonances displayed in equation (78), there is a simultaneous need for models that are simple enough to be applied also for more complicated problems, involving inhomogeneities and nonlinearities. Various fluid approaches have been adopted for this purpose. Those based on the Madelung approach capture most of the spin physics in the physically intuitive effects of a magnetic dipole force and spin precession, together with a spin magnetization current. Such approaches has been used in several recent works, see, e.g. [76–78]. However, higher order quantum terms also appear in this context, which either must be modelled or omitted in order to form a closed set for the fluid variables. Another approach to obtain fluid theories is by computing moments of the kinetic theory. The basic terms (i.e. spin precession and the magnetic dipole force) are the same as in the Madelung approach, but now a spin-velocity correlation tensor appears in the evolution equation for the spin. This corresponds to the tensor in equation (28) in the Madelung approach, but here things are complicated by the presence of other terms such as given by (29). Thus an advantage with the moment approach is that it is straightforward to model the spin-velocity tensor by computing the corresponding moment. As always when taking moments, the coupling to a higher moment appears, but truncating the moment expansion in the next step (i.e. dropping higher order moments in the evolution equation for the spin-velocity tensor) seems to capture most basic spin physics, and leave out only thermal effects [17]. However, even when one is interested in the low temperature limit, certain effects of a nonzero temperature should be kept to address the behaviour in the more common plasma regimes. This has to do with the fact that the Zeeman energy is typically much smaller than the thermal energy (i.e. $\mu_B B_0 \ll k_B T$), such that in thermodynamic equilibrium the two spin states are almost equally populated. As a consequence, even if the temperature is small in all other respects (i.e. all characteristic velocities of a system are larger than the thermal (or Fermi) velocity), there is a large spread in the spin distribution. As a means to capture some of the physics associated with this large spread, two-fluid theories of electrons have been developed where up and down states with respect to the (unperturbed) magnetic field are described as different species, as described briefly in section 3.1. To some extent the fluid theories including the spin-velocity tensor seem able to account for some of the effects of the spread in the spin distribution, but it is too early to make a definitive evaluation of the various models strengths and weaknesses. Thus the final conclusion is that more research on the physics of electron spin in plasmas is needed.

References

[1] Shukla P K and Eliasson B 2010 Phys.—Usp. 53 51
[2] Manfredi G 2005 Fields Inst. Commun. 46 263
[3] Manfredi G and Hervieux P-A 2007 Appl. Phys. Lett. 91 061108
[4] Atwater H A 2007 Sci. Am. 296 56
[5] Wolf S A et al 2001 Science 294 1488
[6] Kouveliotou C et al 1998 Nature 393 235
[7] Palmer D M, Barthelmy S and Gehrels N 2005 Nature 434 1107
[8] Harding A K and Lai D 2006 Rep. Prog. Phys. 69 2631
[9] Robinson M P et al 2000 Phys. Rev. Lett. 85 4466
[10] Glenzer S H et al 2007 Phys. Rev. Lett. 98 065002
[11] Marklund M and Brodin G 2007 Phys. Rev. Lett. 98 025001
[12] Shukla P K 2009 Nature Phys. 5 92
[13] Asenjo F A 2009 Phys. Lett. A 373 4460
[14] Mushtaq A and Vladimirov S V 2010 Phys. Plasmas 17 102510
[70] Brodin G, Marklund M and Manfredi G 2008 Phys. Rev. Lett. 100 175001
[71] Brodin G and Stenflo L 1990 Contrib. Plasma Phys. 30 413
[72] Gorbunov L M and Kirsanov V I 1987 Zh. Eksp. Teor. Fiz. 93 509
   Gorbunov L M and Kirsanov V I 1987 Sov. J. Plasma Phys. 93 290
[73] Bingham R 2007 Nature 445 721
[74] Berge L 1998 Phys. Rep. 303 259
[75] Shukla P K, Rao N N, Yu M Y and Tsintsadze N L 1986 Phys. Rep. 138 1
[76] Brodin G and Marklund M 2007 Phys. Rev. E 76 055403
[77] Brodin G and Marklund M 2007 Phys. Plasmas 14 112107
[78] Brodin G, Missa A P and Marklund M 2010 Phys. Rev. Lett. 105 105004
[79] Moya P S and Asenjo F A 2010 arXiv:1005.2573 [physics-plasm-ph]
[80] Lundin J and Brodin G 2010 Phys. Rev. E 82 056407