BIELLiptIC CURVES OF GENUS 3 IN THE HYPERELLIPTIC MODULI

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Abstract. In this paper we study bielliptic curves of genus 3 defined over an algebraically closed field $k$ and the intersection of the moduli space $M^3_b$ of such curves with the hyperelliptic moduli $H^3$. Such intersection $S$ is an irreducible, 3-dimensional, rational algebraic variety. We determine the equation of this space in terms of the $Gl(2,k)$-invariants of binary octavics as defined in [27] and find a birational parametrization of $S$. We also compute all possible subloci of curves for all possible automorphism group $G$. Moreover, for every rational moduli point $p \in S$, such that $|Aut(p)| > 4$, we give explicitly a rational model of the corresponding curve over its field of moduli in terms of the $Gl(2,k)$-invariants. genus 3 hyperelliptic curves and dihedral invariants

1. Introduction

The moduli space $M_g$ of algebraic curves of genus $g \geq 2$, defined over an algebraically closed field $k$, is an interesting object that has received plenty of attention since the mid XX-century. It is an irreducible quasi-projective variety of dimension $3g-3$. Understanding the stratification of this space has been also a major problem with many papers written on the subject to this day. There are two main difficulties on this problem:

i) an explicit description of $M_g$ is not known (i.e., a coordinate in $M_g$),

ii) a list of automorphism groups for a fixed $g \geq 2$ has not been known.

Naturally one has a better chance to address the above problem if focused on the hyperelliptic sublocus $H_g$ of $M_g$, since it is easier to pick a coordinate on the space $H_g$. After all, the hyperelliptic curves were well understood since the XIX-century and restricting the problem to the hyperelliptic locus seems reasonable. It was well known to classical algebraic geometers of the XIX-century that the isomorphism classes of hyperelliptic curves defined over an algebraically closed field $k$ correspond to the orbits of the $GL_2(k)$ action on the space of binary forms of degree $2g+2$ with coefficients from $k$. This was, among others, one of the main motivations of the invariant theory during the XIX-century. For the generalization to the case of superelliptic curves one can check [21].

The case of genus 2 had been studied extensively by XIX-century mathematicians; see [6,7] even though the concept of the moduli space was not quite refined at the time. About a decade ago Gaudry/Schost in [13] attacked the problem for $g = 2$ from the computational point of view. After all, a coordinate in $M_2$ could be fixed using the Igusa invariants and the list of automorphism groups of genus 2 was known; see [14] among others. At the same time that [13] was being circulated as a preprint, Shaska/Völklein [30] considered the problem from a more
of course, the main case in both those papers was the case when the genus 2 curves had an elliptic involution. The locus $\mathcal{L}_2$ of such curves is a 2-dimensional irreducible variety in $\mathcal{M}_2$ computed in both papers. In the process, a group action was discovered in [30] and its $u, v$ invariants were instrumental in computing equations for the strata of $\mathcal{M}_2$. The map

$$\phi_2(u, v) \rightarrow (i_1, i_2, i_3)$$

provides a birational parametrization of the space $\mathcal{L}_2$, where $i_1, i_2, i_3$ are $GL_2(k)$-invariants in the space of binary sextics. The singular locus of this map correspond to genus 2 curves with larger automorphism group; see [30, Lemma 3]. The paper [30] spurred interest in two directions. First, it naturally brought to the attention of the authors the problem of automorphism groups of curves of genus $g \geq 2$. This corresponds to the ii) part of the problem stated in the beginning. Second, naturally raised the question whether the invariants $u, v$ for $g = 2$ could be generalized to higher genus. In the next two paragraphs we consider each direction in more details.

Determining the list of automorphism groups of algebraic curves of genus $g \geq 2$ is a classical problem. There were hundreds of papers in the subject before 2001, most of them considering specific cases for small genus. However, there was one interesting development at the time that it seems as it did not get the attention it deserved. Breuer computed all signatures of the groups acting on compact Riemann surfaces for genus $g \leq 48$; see [5]. The restriction $g \leq 48$ is merely technical and Breuer’s algorithm works for any genus, providing that some careful analysis is required for sporadic cases. Using results in [5] and the theory of Hurwitz spaces, Magaard, Shpectorov, Shaska, Völklein determined an algorithm of how to determine the list of full automorphism groups of curves for any given genus $g \geq 2$; see [20]. In [20] a complete list of full automorphism groups for curves of genus 3 was determined and the corresponding equations were provided as a way to illustrate the methods described in that paper. There were tens of papers on the case of genus $g = 3$ before [20] appeared. Moreover, by methods in [20] the list of full automorphism groups of curves for any genus $g \geq 2$ can be determined. This settles the second part ii) of the initial problem.

The second direction that was spurred by [30] was the problem of generalizing the map (1) to higher genus. Natural questions to follow would be whether the curves with larger automorphism groups would be in the singular locus of $\phi$. The group action discovered in [30] was generalized in [26] and then in a more formal paper in [16] were such invariants in higher genus were called dihedral invariants.

For a genus $g \geq 2$ now we have a map

$$\phi_g (s_1, \ldots, s_g) \rightarrow (t_1, \ldots, t_{2g-1})$$

where $t_1, \ldots, t_{2g-1}$ are $GL_2(k)$-invariants in the space of binary forms of degree $2g - 1$. In papers [24], [15], and [16] the case of stratification of the hyperelliptic moduli $\mathcal{H}_3$ was treated to illustrate the general theory. Dihedral invariants have been used quite extensively since by many authors. They were generalized for fields of positive characteristic by [2] and are defined again in the projective version in [19], where they are renamed as dihedral arithmetic invariants.

This paper takes another look at the study of genus 3 hyperelliptic curves with extra automorphisms. The general strategy for $g = 3$ was quite obvious a decade ago; one computes the Shioda invariants defined in [31] starting from the Table 1 of [20] and then eliminating the parameters which appear as coefficients of the
curve. Such computations were simplified considerable via the dihedral invariants $s_2$, $s_3$, $s_4$. There was an obvious drawback compared to the genus $g = 2$ case; the $GL_2(k)$-invariants for $g = 3$ were not known. Hence, the obvious strategy was to describe the strata in terms of the $SL_2(k)$-invariants defined by Shioda in [31]. This approach is taken in [18]. It is not clear from [18] if the dihedral invariants were used in these computations or were performed straight from the equations of the curves as in Table 3 in [20]. In any case, Shioda invariants $J_2$, ..., $J_{10}$ are computed in [18] and using syzygies determined in [31, Theorem 5] the authors determine each loci in $H_3$. In [27] it was shown that the syzygies determined by Shioda in [31, Theorem 5] are not correct. It is unclear if the authors in [18] have corrected such syzygies, otherwise all the results of [18] could be incorrect.

The motivation for this paper was the definition of $GL_2(k)$-invariants in [27] where an explicit equation of the hyperelliptic moduli $H_3$ is given in the ambient space $C^6$. Using the absolute invariants $t_1$, ..., $t_6$ as in [27] and the dihedral invariants $s_2$, $s_3$, $s_4$ one can easily compute the locus in $H_3$ for each case of Table 3 of [20]. The drawback of invariants $t_1$, ..., $t_6$ is that they are not defined everywhere. However, this is done by choice so that their degrees are kept small. This makes computations a lot easier. One can get projective equations (i.e., equations in terms of $J_2$, ..., $J_8$) from our equations simply by replacing $t_1$, ..., $t_6$ with their definitions and clearing denominators.

The paper is organized as follows. In section 2 we give a brief description of the invariants of the binary octavics and definitions of absolute invariants. Notice that our definitions of $J_2$, ..., $J_8$ are slightly different from those of Shioda. In section 3 we discuss genus 3 hyperelliptic curves with an elliptic involution and derive an parametric equation for such family of curves. This is rather known material that has been treated in [16, 26].

Section 4 is the main section of the paper where the equation for the locus of curves with an elliptic involution. The main theorem here describes the equation of the irreducible sub variety $S$ in the hyperelliptic moduli $H_3$. We show that for a generic curve $C$ in $S$ the field of definition is at most a degree 2 extension of the field of moduli. This is an improvement from [18] where it is shown that this bound is eight. For example, for the case when the group is $V_4$, we get a model for the parametric curve defined over a quadratic extension of the field of moduli versus a degree 8 extension in [18].

In section 5, we determine the equation of all 1 and 2-dimensional loci for any fixed automorphism group $G$. Parametrization of such loci were also given in [15]. Here we compute them in terms of the absolute invariants $t_1$, ..., $t_6$.

The goal of this paper was to describe the stratification of the space $H_3$ in terms of the absolute invariants $t_1$, ..., $t_6$. The benefit of this approach is that there are fewer equations and even simpler ones. The results in [27] make it possible that we do not have to use the invariants $J_6$, $J_{10}$ and have fewer equations in each case. We get better results compared to [18] in the case of the group $V_4$ and $Z^2_3$ on the minimal equation of the curves over their field of moduli.

In the case of group $Z^2_3$ we prove that the field of moduli is a field of definition and give a model of the curve over its field of definition. Some of these results were not new to us, since they were proved in [16]. However, in this paper we are able to explicitly describe such results in terms of the absolute invariants $t_1$, ..., $t_6$. All our results are implemented in a Maple package which is provided for free on [29].
Notation: Throughout this paper, by a "curve" we mean an irreducible algebraic curve defined over an algebraically closed field $k$. While we use invariants $J_2, \ldots, J_8$ of binary octavics as Shioda [31], the reader must be aware that our definitions are not the same as those in Shioda’s paper, instead we use the definitions as [27]. We also use the dihedral invariants $s_2, s_3, s_4$ which are the same as those used in [15] $u, v, w$, where $s_4 = u$, $s_3 = v$, $s_2 = w$.

2. Bielliptic genus 3 curves

Let $k$ be an algebraically closed field of characteristic zero and $X$ an irreducible, smooth, projective curve of genus $g \geq 3$ defined over $k$. As usual, we denote by $M_g$ the coarse moduli space of smooth curves of genus $g \geq 2$ and by $H_g$ the hyperelliptic locus in $M_g$. The isomorphism class of $C$, i.e. the corresponding point in $M_g$, is denoted by $[C]$. A curve $C$ is called bielliptic if it admits a degree 2 morphism $\pi : C \to E$ onto an elliptic curve. Let

$$M^b_g = \{ [C] \in M_g : C \text{ bielliptic} \}$$

be the locus of bielliptic curves in $M_g$. $M^b_g$ is an irreducible $(2g-2)$-dimensional sub variety of $M_g$. For $g = 3$, $M^b_3$ is the unique component of maximal dimension of the singular locus $\text{Sing}(M_3)$; see [8, 9] for details. It is known that

i) $M^b_3$ is rational

ii) $M^b_3 \cap H_3$ is an irreducible, codimension 1, rational subvariety of $M^b_3$, see [3, Theorem 1.1] for details. In this paper we aim to find an algebraic equation for the space $S := M^b_3 \cap H_3$. An algebraic equation for $M^b_3$ using invariants of ternary quartics and a theorem of Kovalevskaja is intended in [11].

Let $\alpha$ be the element in $\text{Aut}(C)$ which interchanges the sheets of $\pi : C \to E$ such that $E \cong C/\langle \alpha \rangle$. We call $\alpha$ the elliptic involution of $C$ corresponding to $\pi$. Hence, the space $S = M^b_3 \cap H_3$ is exactly the space of genus 3 hyperelliptic curves with elliptic involutions. Such space has been studied before from the point of view of automorphism groups, as described in details in the introduction.

For a fixed group $G$ acting on a genus $g$ algebraic curves $X_g$ we have a covering $X_g \to X_g/G$. All possible ramification structures of such covering for any genus $g$ hyperelliptic curves were determined in [22]. Indeed, this is also done for all superelliptic curves; see [4] for details. In the case of hyperelliptic curves of genus 3, each group occurs only with one signature; see [20]. Hence, there is no confusion if we denote by $S(G)$ the locus in $H_3$ of all curves with automorphism group isomorphic to $G$ (i.e., $G \hookrightarrow \text{Aut}(X_g)$). The loci $S(G)$ is not a priori irreducible. In general, irreducibility is checked by the braid action on Nielsen tuples. The locus $S(G)$ is a Hurwitz space of covers with monodromy group $G$ and fixed ramification structure. However, under our assumptions ($g = 3$ and hyperelliptic) this is always the case as shown in [24] and we will avoid that discussion here.

3. Genus 3 hyperelliptic fields with elliptic involutions

Let $K$ be a genus 3 hyperelliptic field. Then $K$ has exactly one genus 0 subfield of degree 2, call it $k(X)$. It is the fixed field of the hyperelliptic involution $\omega_0$ in $\text{Aut}(K)$. Thus, $\omega_0$ is central in $\text{Aut}(K)$, where $\text{Aut}(K)$ denotes the group $\text{Aut}(K/k)$. It induces a subgroup of $\text{Aut}(k(X))$ which is naturally isomorphic
to $\text{Aut}(K) := \text{Aut}(K)/\langle \omega_0 \rangle$. The latter is called the reduced automorphism group of $K$.

If $\omega_1$ is a non-hyperelliptic involution in $G$ then $\omega_2 := \omega_0 \omega_1$ is another one. So the non-hyperelliptic involutions come naturally in (unordered) pairs $\omega_1, \omega_2$. These pairs correspond bijectively to the Klein 4-groups in $G$. Indeed, each Klein 4-group in $G$ contains $\omega_0$.

**Definition 1.** We will consider pairs $(K, \varepsilon)$ with $K$ a genus 3 hyperelliptic field and $\varepsilon$ an non-hyperelliptic involution in $G$. Two such pairs $(K, \varepsilon)$ and $(K', \varepsilon')$ are called isomorphic if there is a $k$-isomorphism $\alpha : K \rightarrow K'$ with $\varepsilon' = \alpha \varepsilon \alpha^{-1}$.

Let $\varepsilon$ be an non-hyperelliptic involution in $G$. We can choose the generator $X$ of $\text{Fix}(\omega_0)$ such that $\varepsilon(X) = -X$. Then $K = k(X, Y)$ where $X, Y$ satisfy equation

$$Y^2 = (X^2 - \alpha_1^2)(X^2 - \alpha_2^2)(X^2 - \alpha_3^2)(X^2 - \alpha_4^2)$$

for some $\alpha_i \in k, i = 1, \ldots, 4$. Denote by

$$s_1 = - (\alpha_1^2 + \alpha_2^2 + \alpha_3^2 + \alpha_4^2)$$

$$s_2 = (\alpha_1 \alpha_2)^2 + (\alpha_1 \alpha_3)^2 + (\alpha_1 \alpha_4)^2 + (\alpha_2 \alpha_3)^2 + (\alpha_2 \alpha_4)^2 + (\alpha_3 \alpha_4)^2$$

$$s_3 = - (\alpha_1 \alpha_2 \alpha_3)^2 - (\alpha_1 \alpha_2 \alpha_4)^2 - (\alpha_1 \alpha_3 \alpha_4)^2 - (\alpha_2 \alpha_3 \alpha_4)^2$$

$$s_4 = - (\alpha_1 \alpha_2 \alpha_3 \alpha_4)^2$$

Then, we have

$$Y^2 = X^8 + s_1 X^6 + s_2 X^4 + s_3 X^2 + s_4$$

with $s_1, s_2, s_3, s_4 \in k, s_4 \neq 0$. Further $E_1 = k(X^2, Y)$ and $C = k(X^2, YX)$ are the two subfields corresponding to $\varepsilon$ of genus 1 and 2 respectively.

Preserving the condition $\varepsilon(X) = -X$ we can further modify $X$ such that $s_4 = 1$. Then, we have the following:

**Lemma 1.** Every genus 3 hyperelliptic curve $X$, defined over a field $k$, which has an non-hyperelliptic involution has equation

$$Y^2 = X^8 + a X^6 + b X^4 + c X^2 + 1$$

for some $a, b, c \in k^3$, where the polynomial on the right has non-zero discriminant.

Indeed, the non-hyperelliptic involution above is an elliptic involution and $X$ is bielliptic. There is another non-hyperelliptic involution of $X$, as noted above, namely $\omega_2 := \omega_0 \omega_1$ which fixes a genus 2 field. See [23] for the equation of this genus 2 subfield and the arithmetic of such curves. Hence, we have the following result; see [9] or [23] for details.

**Proposition 1.** $[C] \in S$ if and only if $C$ is a double covering of a genus 2 curve.

The above conditions determine $X$ up to coordinate change by the group $\langle \tau_1, \tau_2 \rangle$ where

$$\tau_1 : X \rightarrow \zeta_8 X, \quad \text{and} \quad \tau_2 : X \rightarrow \frac{1}{X},$$

and $\zeta_8$ is a primitive 8-th root of unity in $k$. Hence,

$$\tau_1 : (a, b, c) \rightarrow (\zeta_8^a, \zeta_8^b, \zeta_8^c),$$

and

$$\tau_2 : (a, b, c) \rightarrow (c, b, a).$$
Then, $|\tau_1| = 4$ and $|\tau_2| = 2$. The group generated by $\tau_1$ and $\tau_2$ is the dihedral group of order 8. Invariants of this action are

$$s_2 = ac,$$

$$s_3 = (a^2 + c^2)b,$$

$$s_4 = a^4 + c^4,$$

since

$$\tau_1(a^4 + c^4) = (\zeta_8^6 a)^4 + (\zeta_8^2 c)^4 = a^4 + c^4$$

$$\tau_1((a^2 + c^2)b) = (\zeta_8^4 a^2 + \zeta_8^4 c^2) \cdot (\zeta_8^4 b) = (a^2 + c^2)b$$

$$\tau_1(ac) = \zeta_8^6 a \cdot \zeta_8^2 c = ac$$

Since they are symmetric in $a$ and $c$, then they are obviously invariant under $\tau_2$. Notice that $s_2, s_3, s_4$ are homogenous polynomials of degree 2, 3, and 4 respectively. The subscript $i$ represents the degree of the polynomial $s_i$.

Since the above transformations are automorphisms of the projective line $\mathbb{P}^1(k)$ then the $SL_2(k)$ invariants must be expressed in terms of $s_4, s_3, \text{ and } s_2$. In these parameters, the discriminant of the octavic polynomial on the right hand side of Eq. (4) equals

$$\Delta = \frac{256}{(s_4 + s_2^2)^2} \Delta^2,$$

where

$$\Delta = 132s_2^4s_4 - 18s_4^2s_2s_3 - 72s_4^2s_3^2 - s_4s_2^2s_3^2 + 80s_2s_3^2s_4 - 576s_3s_2^2s_4 - 256s_4^2 + 768s_4s_2^3 - 1024s_4s_2 - 256s_2^2s_3^2 - 576s_3^4s_2 + 768s_2^5 + 24s_2^6 - 16s_3^4 - 1024s_2^4 + 128s_3^2s_4 + 192s_4^2s_2 + 114s_4^2s_2 + 4s_4^2s_2^3 - 144s_4^2s_3 + 16s_4s_2^5 - 72s_2^5s_3 - 2s_2^4s_3^2 + 160s_2s_3^2s_4 + 4s_3^3s_4 + 8s_3^3s_2^2 + 27s_4^3 + 16s_2^7$$

The map

$$(a, b, c) \mapsto (s_2, s_3, s_4)$$

is a branched Galois covering with group $D_4$ of the set

$$\{(s_2, s_3, s_4) \in k^3 : \Delta(s_2, s_3, s_4) \neq 0\}$$

by the corresponding open subset of $a, b, c$-space. In any case, it is true that if $a, b, c$ and $a', b', c'$ have the same $s_2, s_3, s_4$-invariants then they are conjugate under $\langle \tau_1, \tau_2 \rangle$.

The case when $s_3 = 0$ must be treated separately. We have two sub cases $a^2 + c^2 = 0$ or $b = 0$. Then we define new invariants as follows:

$$p(X_3) = \begin{cases} w = b^2 & \text{if } a = c = 0, \\ (s_2, w, s_4) & \text{if } a^2 + c^2 = 0 \text{ and } b \neq 0, \\ (s_2, s_3, s_4) & \text{otherwise.} \end{cases}$$

The invariants $s_2, s_3, s_4, \ldots$ are valid for any genus $g \geq 2$ and are called by many authors dihedral invariants. They were discovered by the second author in his PhD thesis and appeared for the first time in the literature in Shaska/Völklein [30]. Then, they appeared for genus $g = 3$ in [15] [24] and were generalized for every genus in [16]. They were generalized a ditto to all cyclic curves by Antoniadis/Kontogorgis [2]. In [19] a projective version of these dihedral invariants are called dihedral arithmetic invariants.
Lemma 2. For \((a, b, c) \in k^3\) with \(\Delta \neq 0\), equation \((4)\) defines a genus 3 hyperelliptic field \(K_{a,b,c} = k(X, Y)\). Its reduced automorphism group contains the elliptic involution \(\varepsilon_{a,b,c} : X \mapsto -X\). Two such pairs \((K_{a,b,c}, \varepsilon_{a,b,c})\) and \((K_{a',b',c'}, \varepsilon_{a',b',c''})\) are isomorphic if and only if

\[
(s_2, s_3, s_4) = (s'_2, s'_3, s'_4)
\]

where \(s_2, s_3, s_4\) and \(s'_2, s'_3, s'_4\) are dihedral invariants associated with \(a, b, c\) and \(a', b', c'\), respectively.

Proof. An isomorphism \(\alpha\) between these two pairs yields \(K = k(X, Y) = k(X', Y')\) with \(k(X) = k(X')\) such that \(X, Y\) satisfy \((4)\) and \(X', Y'\) satisfy the corresponding equation with \(a, b, c\) replaced by \(a', b', c'\). Further, \(\varepsilon_{a,b,c}(X') = -X'\). Thus \(X'\) is conjugate to \(X\) under \(\langle \tau_1, \tau_2 \rangle\) by the above remarks. This proves the condition is necessary. It is clearly sufficient.

\(\square\)

Remark 1. If \((2s_4 + s_2^2) = 0\), then this implies that \(a = c = 0\). In this case the equation of the curve becomes

\[
Y^2 = X^8 + bX^4 + 1,
\]

which corresponds to the curves with automorphism group \(Z_2 \times D_8\), (cf. Eq. \((27)\))

We have the following theorem

**Theorem 1.** Let \((s_2, s_3, s_4) \in k^3\) \(\setminus \{\Delta = 0\}\). Then the following hold:

i) The ordered triples \((s_2, s_3, s_4)\) bijectively parameterize the isomorphism classes of pairs \((K, \varepsilon)\) where \(K\) is a genus 3 hyperelliptic field and \(\varepsilon\) an elliptic involution of \(Aut(K)\). The j-invariant of the elliptic subfield of \(K\) associated with \(\varepsilon\) is given by

\[
j = \frac{64}{M} \left(\frac{-4s_3^2 - 48s_4 - 24s_2^2 + 3s_1^2 + 6s_4s_2}{(2a_4 + s_2^2)}\right)^3,
\]

where

\[
M = 66s_4s_2^4 - 204s_4^2 - 512s_4^2 - 204s_4s_2^2 - 128s_4^2 + 1024s_3^3s_4 + 512s_3^3s_2^2 + 228s_3^2s_2^2
+ 768s_2s_2^2 + 216s_2^2 + s_2 + 3s_3^2 + 4s_3^2s_2^2 + 4s_3s_2^2 - s_2^4 + 768s_4s_2^2 + 160s_3^2s_2^2
+ 192s_2^2 - 2s_3^2s_2^2 + 320s_3^2s_3s_2 - 72s_3^2s_3^2 - 72s_3s_2^2s_3^2 - 1152s_3^2s_3^2 + 32s_3^2s_4
- 115s_3s_3 - 288s_3s_3 + 16s_3^2s_3^2 - 18s_3s_3
\]

ii) There is another involution \(\omega_0 = \varepsilon \in Aut(K)\) which fixes a genus 2 curve \(X_2\) with equation

\[
Y^2 = X(X^4 + aX^3 + bX^2 + cX + 1).
\]

The isomorphism class of \(X_2\) is determined uniquely by the triple \((s_2, s_4, s_4)\) as in Eq. \((9)\).

iii) The triples \((s_2, s_3, s_4)\) parametrize the isomorphism classes of genus 3 hyperelliptic fields with \(V_4 \hookrightarrow Aut (K)\).

Proof. i) The automorphism \(\varepsilon \in Aut(K)\) fixes a degree 2 elliptic subfield \(E\) which has equation

\[
Y^2 = x^4 + ax^3 + bx^2 + cx + 1
\]
and \( j \)-invariant given in terms of \( a, b, \) and \( c \). Using substitutions in Eq. (13) we get \( j(E) \) as in Eq. (8).

ii) The quotient \( X/\langle \omega_0 \rangle \) has genus 2. This follows straight from the Riemann-Hurwitz formula. The equation of this genus 2 curve is as claimed; see [28]. The isomorphism class of this genus 2 curve is determined by the absolute invariants \((i_1, i_2, i_3)\). In terms of the \( s_2, s_3, s_4 \) they have the following expressions

\[
(9)
\]

\[
i_1 = \frac{9(2s_1 + s_3^3)}{D^2} (s_3^6 - 80s_3^2 - 72s_2^2 - 2s_3^3s_1 - 24s_1s_2 - 12s_3^3s_2 + 2s_3^3 - 160s_1 + 4s_3s_1)
\]

\[
i_2 = \frac{27(2s_1 + s_3^3)^2}{D^3} (2s_3^3s_1 - 1116s_1s_2 + s_3^3 - 2240s_3^2 + 162s_2s_3 + 864s_2^2 + 216s_2^2
\]

\[
+ 114s_2^2s_1 + 3s_1 - 558s_3^2s_2 - 4480s_1 + 624s_3^3 - 18s_3^2s_2 - 36s_1s_2s_3 + 124s_3s_1)
\]

\[
i_3 = \frac{243 (2s_1 + s_3^3)^3}{1024 D^5} (s_3^7 - 128s_2^4 - 2048s_2^2 + 768s_3s_1 - 2048s_3s_1 + 192s_3^5 - 512s_3^4
\]

\[
+ 216s_3^3 + 3s_1 - 72s_2s_3s_2 - 320s_1s_2s_3 - 72s_1s_3s_2 - 1152s_1s_3s_2 - 2s_2s_1s_3^2
\]

\[
- 1152s_1s_2^2 + 1024s_1s_2^2 + 160s_3^2s_3^3 + 512s_3^2s_3^3 - 18s_3^2s_2 - 288s_3^2s_2 + 768s_3s_1^2
\]

\[
+ 4s_3^6s_1 + 4s_3^3s_1 + 228s_3^4s_1 + 66s_3^4s_1 + 16s_3^2s_3^3 + 32s_3^2s_1 - s_3^2s_1^2)
\]

where \( D = -20s_1 - 10s_2 + 2s_3^2 + 4s_3s_1 - 3s_3^2 \).

iii) This is a straight consequence of the first two parts. The cases when \(|\operatorname{Aut}(K)| > 4\) are treated in Thm. [11] \( \square \)

4. The Locus \( \mathcal{S} \) of Genus 3 Hyperelliptic Curves with Elliptic Involution

In this section, first we briefly define the invariants of binary octavics. We will use interchangeably the terms genus 3 hyperelliptic curve and genus 3 hyperelliptic field. There is a one to one equivalence between the isomorphic classes of genus 3 hyperelliptic curves and projective classes of equivalence of binary octavics. Thus, we have to describe some basic properties of binary octavics. The following material can be found on works of classical algebraic geometers; see Alagna [11], van Gall [32], et al or for a modern version one can check [10].

The ring of invariants of binary octavics was also studied by Shioda [31]. However, the syzygies among such \( SL_2(k) \)-invariants described in the Shioda’s paper seem to be incorrect. In [27] such \( SL_2(k) \)-invariants \( J_2, \ldots, J_8 \) are redefined and the algebraic relations among them determined. Furthermore, \( GL_2(k) \)-invariants \( t_1, \ldots, t_6 \) are defined and relation among them determined. Throughout this paper we will make use of these \( GL_2(k) \)-invariants and therefore follow definitions from [27].

Let \( f(X,Y) \) be the binary octavic

\[
f(X,Y) = \sum_{i=0}^{8} a_i X^i Y^{8-i}.
\]
defined over an algebraically closed field \( k \). We define the following covariants:

\[
g = (f, f)^4, \quad k = (f, f)^6, \quad h = (k, k)^2, \\
m = (f, k)^4, \quad n = (f, h)^4, \quad p = (g, k)^4, \quad q = (g, h)^4,
\]

where the operator \( (\cdot, \cdot)^n \) denotes the \( n \)-th transvection of two binary forms; see [27] among many other references.

Then, the following

\[
J_2 = 2^2 \cdot 5 \cdot 7 \cdot (f, f)^8, \quad J_3 = \frac{1}{3} \cdot 2^4 \cdot 5^2 \cdot 7^3 \cdot (f, g)^8, \\
J_4 = 2^9 \cdot 3 \cdot 7^4 \cdot (k, k)^4, \quad J_5 = 2^9 \cdot 5 \cdot 7^5 \cdot (m, k)^4, \\
J_6 = 2^{14} \cdot 3^2 \cdot 7^6 \cdot (k, h)^4, \quad J_7 = 2^{14} \cdot 3^5 \cdot 7^7 \cdot (m, h)^4, \\
J_8 = 2^{17} \cdot 3^5 \cdot 7^9 \cdot (p, h)^4, \quad J_9 = 2^{19} \cdot 3^2 \cdot 5 \cdot 7^9 \cdot (n, h)^4, \\
J_{10} = 2^{22} \cdot 3^2 \cdot 5^2 \cdot 7^{11} (q, h)^4
\]

are \( SL_2(k) \)-invariants; see [27] for details. The following is a classical fact of invariant theory of binary forms.

**Lemma 3.** Two binary forms \( f(X, Y) \) and \( f'(X, Y) \) are projectively equivalent via a matrix \( M \in GL_2(k) \) if and only if

\[
J_i(f) = \lambda^i J_i(f'), \quad \text{where} \quad \lambda = (\det(M))^4
\]

The following technical result is helpful for the rest of the paper; see [27, Lemma 4].

**Lemma 4.** If \( J_2 = \cdots = J_7 = 0 \), then the binary octavic has a double root.

Next, we define \( GL(2, k) \)-invariants as follows

\[
t_1 := \frac{J_3^2}{J_2^3}, \quad t_2 := \frac{J_4}{J_2^2}, \quad t_3 := \frac{J_5}{J_2 \cdot J_3}, \quad t_4 := \frac{J_6}{J_2 \cdot J_4}, \quad t_5 := \frac{J_7}{J_2 \cdot J_5}, \quad t_6 := \frac{J_8}{J_2^2}
\]

There is an algebraic relation

\[
T(t_1, \ldots, t_6) = 0
\]

that such invariants satisfy, computed in [27]. The field of invariants \( S_8 \) of binary octavics is \( S_8 = k(t_1, \ldots, t_6) \), where \( t_1, \ldots, t_6 \) satisfies the equation \( T(t_1, \ldots, t_6) = 0 \). Hence, we have an explicit description of the hyperelliptic moduli \( \mathcal{H}_3 \); see [27] for details.

Throughout this paper we will use the following important result

**Lemma 5** (Shaska [27]). Two genus 3 hyperelliptic curves \( C \) and \( C' \), defined over an algebraically closed field \( k \) of characteristic zero, with \( J_2, J_3, J_4, J_5 \) nonzero are isomorphic over \( k \) if and only if

\[
t_i(C) = t_i(C'), \quad \text{for} \quad i = 1, \ldots, 6.
\]

In the cases of curves when \( t_1, \ldots, t_6 \) are not defined we will define new invariants as suggested in [27]. From [27, Lemma 4] we know that \( J_2, \ldots, J_7 \) can’t all be 0, otherwise the binary form would have a multiple root.

To describe the moduli points in cases when absolute invariants are not defined is not difficult. In this case, one has to treat each case separately when any of the invariants \( J_2, \ldots, J_5 \) are zero. Indeed, we can define invariants depending of which of the invariants is nonzero.
If $J_2 \neq 0$, then we define

$$i_1 = \frac{J_2^2}{J_3^2}, \; i_2 = \frac{J_4}{J_2^2}, \; i_3 = \frac{J_2^2}{J_4^2}, \; i_4 = \frac{J_6}{J_2^2}, \; i_5 = \frac{J_2^2}{J_5^2}, \; i_6 = \frac{J_8}{J_2^2}$$

If $J_2 = 0$ then we pick the smallest degree invariant among $J_3, \ldots, J_7$ which is not zero. Let $J_2 = 0$ and $J_3 \neq 0$. Define

$$h_1 = \frac{J_3^2}{J_3}, \; h_2 = \frac{J_3^2}{J_3}, \; h_3 = \frac{J_6}{J_3}, \; h_4 = \frac{J_3^2}{J_4}, \; h_5 = \frac{J_3^2}{J_5}$$

Let $J_2 = J_3 = 0$ and $J_4 \neq 0$. Then we have

$$j_1 = \frac{J_3^2}{J_4}, \; j_2 = \frac{J_6}{J_4}, \; j_3 = \frac{J_4^2}{J_4}, \; j_4 = \frac{J_8}{J_4}$$

Let $J_2 = J_3 = J_4 = 0$ and $J_5 \neq 0$. Then

$$k_1 = \frac{J_6}{J_5}, \; k_2 = \frac{J_8}{J_5}, \; k_3 = \frac{J_3^5}{J_5^5}$$

Let us assume that $J_2 = J_3 = J_4 = J_5 = 0$. In this case, we define the absolute invariants

$$\tau_1 := \frac{J_6^5}{J_6}, \; \tau_2 = \frac{J_8^3}{J_6^3}$$

There is only one curve in the case when $J_2 = \cdots = J_6 = 0$, namely $Y^2 = X^7 - 1$. In our discussion in section 5 we will see cases when $J_3 = J_5 = J_7 = 0$. In this case we will use invariants defined in Eq. (13).

Since a tuple $(t_1, \ldots, t_6)$ uniquely determines the isomorphism class of a curve then we will study the locus of the curves with a fixed automorphism group $G$ in terms of such invariants $(t_1, \ldots, t_6)$. The only interesting cases are groups $G$ which have non-hyperelliptic involutions; see [15] or [4].

To make it easier to state some of the results in the following sections we define the absolute invariants of $\mathcal{X}$ as follows

$$p(\mathcal{X}) = \begin{cases} 
(t_1, \ldots, t_6) & \text{if } J_2, \ldots, J_5 \text{ are nonzero} \\
(i_1, \ldots, i_6) & \text{if } J_2 \neq 0 \wedge (J_3 = 0 \vee J_4 = 0 \vee J_5 = 0) \\
(h_1, \ldots, h_5) & \text{if } J_2 = 0 \wedge J_3 \neq 0 \\
(j_1, j_2, j_3, j_4) & \text{if } J_2 = J_3 = 0 \wedge J_4 \neq 0 \\
(k_1, k_2, k_3) & \text{if } J_2 = J_3 = J_4 = 0 \wedge J_5 \neq 0 \\
(\tau_1, \tau_2) & \text{if } J_2 = J_3 = J_4 = J_5 = 0 
\end{cases}$$

For each case of the above we determine the equation of the moduli space $\mathcal{H}_3$. For the first case this equation is Eq. (12). The rest of the cases are described briefly below. The $p(\mathcal{X})$ determines uniquely the isomorphism class of $\mathcal{X}$.

Computational benefits of these invariants are that they are of small degree and therefore nicer especially when we deal with families of curves and have to compute symbolically. In each case for $p(\mathcal{X})$ we can compute the equation of the moduli in terms of the corresponding invariants analogous to the $T(t_1, \ldots, t_6) = 0$ as in Eq. (12).
4.1. Computing the locus $\mathcal{S}$. Let $\mathcal{S}$ denote the locus of genus 3 hyperelliptic curves with elliptic involutions. It follows from the theory of Hurwitz spaces that this is an irreducible 3-dimensional subvariety of $H_3$; see [15, 24]. In [15] it is shown that $k(\mathcal{S}) = k(s_2, s_3, s_4)$. In this paper, we will give an explicit computational proof of this result and provide a birational parametrization of the locus $\mathcal{S}$. We will outline all the computations and display only those results which are reasonable to display in this paper.

Every genus 3 hyperelliptic curve which has an elliptic involution is isomorphic to a curve with equation as in Eq. (4). The obvious strategy would be to compute the invariants $t_1, \ldots, t_6$ in terms of $a, b, c$ and then eliminate $a, b, c$ from these equations. This is rather difficult computationally. Since dihedral invariants $s_2, s_3, s_4$ are invariant under coordinate changes in $\mathbb{P}^1(k)$ then we can express $t_1, \ldots, t_6$ in terms of such invariants as stated in Theorem 1. In the next few paragraphs we describe these computations.

Let $X_3$ be a genus 3 hyperelliptic curve with equation as in Eq. (4). Notice that from the definitions of the dihedral invariants in Eq. (5) we have

\begin{equation}
(14) \quad b = \frac{s_3}{a^2 + c^2}, \quad b^2 = \frac{s_5^2}{s_4 + 2s_2^2}, \quad a^8 + c^8 = s_4^2 - 2s_2^4, \quad (a^2 + c^2)^2 = s_4 + 2s_2^2
\end{equation}

We denote by $\lambda := a^2 + c^2$. Then, $\lambda^2 = s_4 + 2s_2^2$ and $\lambda a^2 = (a^2 + c^2) a^2 = a^4 + s_2^2$.

By changing the coordinate by

$$X \rightarrow (a^2 + c^2) \sqrt{\lambda} X$$

we get the curve

$$Y^2 = \lambda^8 a^4 X^8 + \lambda^6 a^4 X^6 + \lambda^4 ba^2 X^4 + \lambda^2 ca X^2 + 1$$

Notice that the coefficient of $X^4$ is

$$\lambda^4 ba^2 = (a^2 + c^2)^2 \cdot \lambda^2 a^2 = b(a^2 + c^2) \cdot a^2(a^2 + c^2) \cdot \lambda^2 = s_3 \cdot (a^4 + s_2) \cdot \lambda^2$$

Then, we have the curve with equation

\begin{equation}
(15) \quad Y^2 = A X^8 + \frac{A}{s_4 + 2s_2^2} X^6 + \frac{sg_2(A + s_2^2)}{(s_4 + 2s_2^2)^3} X^4 + \frac{s_2}{(s_4 + 2s_2^2)^3} X^2 + \frac{1}{(s_4 + 2s_2^2)^4}
\end{equation}

where $A = a^4$. Notice that by substituting $c = \frac{-a}{\sqrt{\lambda}}$ in the definition of $s_4$ we get that $A + s_2^2 = s_4$, which says that $A$ satisfies the equation

\begin{equation}
(16) \quad A^2 - s_4 A + s_2^4 = 0
\end{equation}

We will see how this equation will be useful when discussing the field of definition of the curve $X_3$.

From the Eq. (1) we compute the invariants $J_2, \ldots, J_8$. By performing the above substitutions we get the following expressions.
\( J_2 = 2(140 s_4 + 280 s_2^2 + 5 s_2 s_4 + 10 s_2^3 + s_4^2) \)

\[ J_3 = 2(6 s_3^3 + 525 s_4 + 2100 s_2 s_4 + 2100 s_4^2 - 55 s_2 s_3 s_4 - 110 s_2^3 s_3 + 1960 s_4 s_3 + 3920 s_3 s_2^2) \]

\[ J_4 = 2^6 \left( s_4^4 + 126 s_3 s_4^2 + 504 s_3 s_4^2 + 504 s_3 s_2^4 + 38416 s_4^2 + 153664 s_2 s_4^2 + 153664 s_2^4 \right) \]
\[ - 784 s_2^3 s_4 - 784 s_2^3 s_2 + 4 s_2^3 s_2 + 16 s_4 s_2 + 16 s_2^2 + 392 s_4 s_3 - 784 s_2 s_3^2 + 31 s_2 s_4 s_3 \]
\[ - 196 s_2 s_4^2 + 62 s_2^3 s_3^2 \}

\[ J_5 = 2^7 \left( 76832 s_3 s_4^2 + 207328 s_3 s_2^4 + 123480 s_4^2 s_2^2 + 246960 s_4 s_2^4 + 1148 s_4^3 s_3^2 + 287 s_4^2 s_3^2 \right) \]
\[ - 1568 s_4 s_3 s_2^4 + 41552 s_4 s_4^3 s_2 - 26 s_2 s_4^3 s_3^2 - 1680 s_2^2 s_4^3 s_2 - 208 s_2 s_3 s_4^3 - 140 s_2 s_3 s_4^3 - 840 s_3 s_4^3 s_2^2 \]
\[ + 20580 s_4^3 s_3^2 - 2 s_2 s_4 s_3^2 + 307328 s_3 s_4^3 s_2 + 10388 s_2 s_4^3 s_2 + 41552 s_2^3 s_3 s_4^2 \]
\[ - 52 s_3 s_4 s_2^4 + 164640 s_4^2 s_2 s_3^2 - 784 s_4 s_3 s_2^4 + 208 s_4 s_4^2 s_3^2 + 1148 s_4^2 s_2^2 s_3^2 + 13 s_2^2 s_4 s_3^2 \]

\[ J_6 = 2^9 \left( 2 s_2^4 s_3 - 196 s_2^3 s_4 + 392 s_2^2 s_3^2 + s_3^4 \right) \left( s_3 + 38 s_3 s_4^2 - 1512 s_3 s_4^2 + 1512 s_3 s_2^4 \right) \]
\[ - 10192 s_4 s_5 s_4 - 10192 s_5 + 77 s_4 s_5 s_3^2 - 154 s_2 s_3^2 s_2^2 + 4 s_2 s_3 s_2^2 + 16 s_4 s_2^4 + 16 s_2^6 \]
\[ + 38416 s_4^2 s_2^4 + 153664 s_4 s_2^4 + 153664 s_2^2 s_4 s_2^4 - 784 s_2 s_3^2 s_2^2 - 254 s_2 s_3^2 s_2^2 \]

\[ J_7 = 2^{10} \left( 1120 s_2^4 s_4^3 - 120472576 s_3 s_2^6 - 34300 s_2 s_4^4 + 3360 s_2 s_4^2 \right) \]
\[ + 4400 s_2^5 s_3 + 39200 s_2^5 s_3^3 - 931 s_3 s_4^3 - 3724 s_3 s_4^3 \]
\[ - 90 s_3^2 s_2^6 - 252 s_3 s_2^5 s_4 + 161986 s_3 s_4^3 + 8344 s_2 s_3 s_4^3 + 234096 s_4 s_3 s_4^3 + 1295168 s_2 s_3 s_4^3 \]
\[ + 129077760 s_3 s_4^3 - 1097600 s_5^3 s_4 - 15059072 s_3 s_4^3 \]
\[ + 9680320 s_2 s_4^2 s_4 + 29196160 s_2 s_4^2 s_3 + 29196160 s_2 s_4^2 s_3 + 2240 s_3 s_4^3 + 4033680 s_4^4 \]
\[ + 2 s_3 s_4^2 + 90534432 s_2 s_4^2 s_4 - 18708864 s_3 s_4^2 s_4 - 270480 s_3 s_4^2 s_4 - 45 s_4 s_5 s_2^4 \]
\[ + 6258 s_2 s_4^2 s_2^4 + 912 s_2 s_3 s_4^2 s_2^4 + 971376 s_2^2 s_2 s_4^2 s_2^4 - 9800 s_2 s_3 s_4^2 s_2^4 + 345 s_2 s_3 s_4^2 s_2^4 \]
\[ + 456 s_2 s_3 s_4^2 s_2^4 - 39200 s_2 s_3 s_4^2 s_2^4 + 46538880 s_2^3 s_4 + 1380 s_2^3 s_4^3 \]
\[ - 3724 s_3 s_4^3 s_2^4 + 921984 s_3 s_4^3 s_2^4 + 1043 s_3 s_4^3 s_2^4 + 21897120 s_3 s_4^3 s_2^4 + 76 s_3 s_4^3 s_2^4 \]
\[ + 43794240 s_2 s_3 s_4^4 + 1380 s_2^3 s_3 s_4^3 + 3649520 s_2 s_3 s_4^3 + 1942752 s_2^3 s_3 s_4^3 + 980 s_3 s_4^3 s_2^4 \]
\[ + 32269440 s_4^3 s_2^4 - 99960 s_4^3 s_2^4 - 548800 s_2^3 s_4^3 + 12516 s_2^3 s_4^3 s_2^4 - 823200 s_2^3 s_4^3 s_2^4 \]

We do not display \( J_8 \) but it is easy to compute as the previous ones. The reader who want to obtain the above expressions can use computational packages. For example, "algsubs" would work in Maple and similar commands in other packages.

Hence, we can write now \( t_1, \ldots, t_6 \) in terms of the dihedral invariants \( s_2, s_3, s_4 \). 

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(18) 
\[ t_1 = \frac{1}{2} \cdot \frac{(3920s_2s_3^2 + 2100s_2^2 + 2100s_3^2s_4 + 525s_1^4 + 7840s_3s_4 + 24s_2^3 - 110s_3s_4s_2 - 55s_3s_2^2) (2s_4 + s_2^2)^2}{(560s_4 + 280s_2^2 + 10s_2s_4 + 5s_2^2 + 4s_1^2)^2} \]

\[ t_2 = \frac{64}{(560s_4 + 280s_2^2 + 10s_2s_4 + 5s_2^2 + 4s_1^2)^3} (38416s_2^4 + s_2^6 + 4s_1^2s_2^2 + 4s_2s_4 - 392s_3s_4 + 15364s_2^2s_4 - 392s_3s_2^2 + 4s_3^4 - 98s_2^2 + 504s_3s_2s_4 - 1568s_2^2s_4 - 784s_2^2s_4^2 + 504s_3s_4^2 + 126s_3s_2^2 + 62s_3s_2s_4 + 15364s_4^2 + 313s_2^2s_4) \]

\[ t_3 = -\frac{32}{(560s_4 + 280s_2^2 + 10s_2s_4 + 5s_2^2 + 4s_1^2)} \frac{M}{N} \]

\[ M = -123480s_2s_3^2 - 61740s_3s_4 - 307328s_3s_4^2 - 76832s_3s_4^2 - 5194s_3s_4^2 + 13s_3s_4^2 + 3136s_3s_4 + 1568s_3s_2^2 \]
\[-1148s_3^2s_4^2 + 280s_3^2s_4^2 + 420s_3^2s_4^2 + 210s_3^2s_4^2 + 13s_3^2s_4^2 - 287s_3^2s_4^2 - 10290s_4^2 - 8s_4^2 - 82320s_4^2 + 3s_4^2 \]
\[-307328s_3^2s_4^2 - 20776s_3^2s_4^2 + 52s_3^2s_4^2 - 20776s_3^2s_4^2 + 52s_3^2s_4^2 + 26s_3^2s_4^2 - 148s_3^2s_4^2 \]
\[ N = 3920s_2^2s_4^2 + 2100s_2^2s_4 + 525s_2^2s_4 + 7840s_3s_4 + 24s_3^2 - 110s_3s_4s_2 - 55s_3s_2^2 \]

\[ t_4 = -\frac{A}{B} \frac{(8s_2^3 + 2s_2s_4 - 392s_4 - 196s_2^2 + 2s_1^2))}{(560s_4 + 280s_2^2 + 10s_2s_4 + 5s_2^2 + 4s_1^2)} \]

\[ A = -38416s_2^4 - s_2^6 - 4s_1^2s_2^2 - 4s_2s_4 - 5096s_2s_4 + 15364s_2s_4 + 5096s_2s_4 - 4s_2^3 + 1274s_2^2 + 1512s_3s_2^3 \]
\[+ 1568s_2^3s_4 + 784s_2^3s_4 + 1512s_3s_4^2 + 378s_3s_4^2 + 154s_3s_2s_4 - 15364s_2s_4 + 77s_3^2s_4^2 \]
\[ B = 38416s_2^4 + s_2^6 + 4s_1^2s_2^2 + 4s_2s_4 - 392s_3s_4 + 15364s_2s_4 + 392s_3s_2^2 + 4s_3^4 - 98s_2^2 + 504s_3s_2s_4 \]
\[-1568s_2^3s_4 - 784s_2^3s_4 + 504s_3s_4^2 + 126s_3s_2^2 + 62s_3s_2s_4 + 15364s_4^2 + 313s_2^2s_4 \]

We are not displaying \( t_5 \) and \( t_6 \).

Hence, we have a map given by the above equations

\[ k^3 \setminus \{ \Delta = 0 \} \to S = M_3^b \cap H_3 \]
\[ (s_2, s_3, s_4) \to (t_1, t_2, t_3, t_4, t_5, t_6) \]

which as it will be shown in the next theorem is birational.

**Theorem 2.** \( k(S) = k(s_2, s_3, s_4) \).

**Proof.** Since \( k(S) \) is a subfield of \( k(s_2, s_3, s_4) \) which contains all \( k(t_i) \) for \( i = 1, \ldots, 6 \) then \( k((s_2, s_3, s_4) : k(S)) \) must divide each of degrees if \( t_i \). The degrees of \( t_i \) as rational functions in \( s_2, s_3, s_4 \) are respectively 12, 6, 7, 9, 10, 12. Hence, \( k((s_2, s_3, s_4) : k(S)) = 1 \). This completes the proof.

This was also proved in [14] for any genus \( g \geq 2 \). Here we provide a direct computational proof and explicitly determine the formulas for \( s_2, s_3, s_4 \) as rational functions in terms of \( t_1, \ldots, t_6 \). We have the following theorem.

**Theorem 3.** The space \( S := M_3^b \cap H_3 \) is an irreducible, codimension 1, rational subvariety of \( M_3^b \). Its defining equations are

\[ F_i(J_2, \ldots, J_8) = 0, \quad i = 1 \ldots 5 \]

as displayed in [29]. The map

\[ k^3 \setminus \{ \Delta = 0 \} \to S := M_3^b \cap H_3 \]
\[ (s_2, s_3, s_4) \to (t_1, \ldots, t_6) \]

given by Eq. (18) (in homogeneous coordinates by the formulas (17)) is birational and surjective.
Proof. From Theorem 1, ii) we have that \( \mathcal{M}_3^0 \cap \mathcal{H}_3 \) is birationally isomorphic to the coarse moduli space of smooth curves of genus 2 together with a nontrivial divisor class of order 2. Since this space is an irreducible, 3-dimensional, rational variety then the first part of the theorem is proved.

It remains to show the map in the Theorem is birational. We need to show that the degree of the field extension \( k(\mathfrak{s}_2, \mathfrak{s}_3, \mathfrak{s}_4)/k(\mathcal{S}) \) is 1. For this we use the functions \( t_1, t_2, t_3, t_4, t_5, t_6 \) in \( k(\mathcal{H}_3) \). The fact that \( [k(\mathfrak{s}_2, \mathfrak{s}_3, \mathfrak{s}_4) : k(\mathcal{S})] = 1 \) comes straight from the computation of the locus \( \mathcal{S} \) where we get rational expressions for the \( \mathfrak{s}_2, \mathfrak{s}_3, \mathfrak{s}_4 \) or from Theorem 2. This completes the proof. \( \square \)

4.2. Field of moduli vs field of definition. It is a classical problem in the arithmetic of the algebraic curves to try to find an equation of the curve in terms of the moduli point corresponding to this curve. In other words, this means that given the moduli point \( p(\mathcal{X}) \), could we determine an equation for \( \mathcal{X} \) in terms of the coordinates of \( p(\mathcal{X}) \). If an equation of the curve can be found in terms of coordinates of the moduli point we say that the field of moduli is the same with the minimal field of definition. In 2003 the first author conjectured that this would be the case for all hyperelliptic curves with extra involutions \([23, 25] \). It is true for \( g = 2 \) and as we will see next it is true for all genus 3 hyperelliptic curves in \( p \in \mathcal{M}_3^0 \cap \mathcal{H}_3 \) such that \( |\text{Aut}(p)| > 2 \). There have been claims on whether the above conjecture is true or false and some confusion from work of Huggins \([17] \) and Fuertes \([12] \) which seem to come from different definitions of the field of moduli.

Summarizing we have the results of section 4.1 and Eq. (15) and (16) we have the following:

**Proposition 2.** Let \( [\mathcal{X}] \in \mathcal{M}_3^0 \cap \mathcal{H}_3 \). Then the following hold true:

i) \( \mathcal{X} \) is isomorphic to a curve with equation

\[
Y^2 = A X^6 + \frac{A}{\mathfrak{s}_4 + 2\mathfrak{s}_2^2} X^6 + \frac{\mathfrak{s}_3(\mathfrak{s}_4 + \mathfrak{s}_3^2)}{(\mathfrak{s}_4 + 2\mathfrak{s}_2^2)^3} X^4 + \frac{\mathfrak{s}_2}{(\mathfrak{s}_4 + 2\mathfrak{s}_2^2)^3} X^2 + \frac{1}{(\mathfrak{s}_4 + 2\mathfrak{s}_2^2)^2},
\]

where \( A \) satisfies

\[
(21) \quad A^2 - \mathfrak{s}_4 A + \mathfrak{s}_2^4 = 0,
\]

for some \( (\mathfrak{s}_2, \mathfrak{s}_3, \mathfrak{s}_4) \in k^3 \setminus \{\Delta_{\mathfrak{s}_2, \mathfrak{s}_3, \mathfrak{s}_4} = 0\} \) and \( \Delta_{\mathfrak{s}_2, \mathfrak{s}_3, \mathfrak{s}_4} \) as in Eq. (6).

ii) Let \( F \) denote the field of moduli of \( \mathcal{X} \) and \( F' \) its minimal field of definition. Then, \( F' \subset F(\mathcal{A}) \) and \( [F' : F] \leq 2 \). An equation of \( \mathcal{X} \) over \( F(\mathcal{A}) \) is given by Eq. (21).

iii) If the discriminant \( d = \mathfrak{s}_3^2 - 4\mathfrak{s}_2^3 \) of the quadratic in Eq. (21) is a complete square in \( k(\mathfrak{s}_2, \mathfrak{s}_3, \mathfrak{s}_4) \) then the corresponding curve is defined over its field of moduli.

Proof. Part i) was proved in section 4.1. The field of moduli of a curve \( \mathcal{X} \) is \( F = k(t_1, \ldots, t_6) \). Hence, form Theorem 2, \( F = k(\mathfrak{s}_2, \mathfrak{s}_3, \mathfrak{s}_4) \). Since \( \mathcal{X} \) is defined via Eq. (21) over \( F \left(\sqrt{\frac{\mathfrak{s}_3^2 - 4\mathfrak{s}_2^3}{}}\right) \), then \( F' \subset F(\mathcal{A}) \) and \( [F' : F] \leq 2 \). Prat iii) is clearly true. \( \square \)

The above result improves on the bound of the degree of \( [F' : F] \leq 8 \) as shown in \([18] \). It is expected that the field of moduli is a field of definition for all curves \( \mathcal{X} \in \mathcal{M}_3^0 \cap \mathcal{H}_3 \). A generalization of methods for \( g = 2 \) should provide and algorithm also for \( g = 3 \).
5. **Singular locus of \( \mathcal{S} \), classification of strata of the hyperelliptic moduli**

In this section we give a classification of the strata of the hyperelliptic moduli \( 3 \). The stratum of the hyperelliptic moduli has been known to the classical algebraic geometers. Indeed, it is the only case that was considered fully known even though explicit descriptions were not available even for small genus (i.e., \( g = 2 \)). On the turn of the new century a couple of papers appeared for the case of genus \( g = 2 \); see [13] and [30].

5.1. **Singular loci in terms of dihedral invariants.** Next, we will characterize each one of these loci in terms of the \( s \)-invariants. The proof of the following theorem can be found in [15], where such relations were determined by studying the group action on the invariants \( s_2, s_3, s_4 \). Here we give a more computational proof.

5.2. **2-dimensional strata.** There are two 2-dimensional loci in \( H_3 \) which correspond to the case when the reduced automorphism group of the curve is isomorphic to \( V_4 \). Indeed, the following is true for any genus \( g \geq 2 \); see [16, Theorem 3].

Let \( X_g \) be a genus \( g \) hyperelliptic curve with an extra involution, \( \text{Aut}(X_g) \) its reduced automorphism group, and \((s_4, \ldots, s_g)\) its corresponding dihedral invariants as defined in [16].

If \( V_4 \hookrightarrow \text{Aut}(X_g) \) then \( 2^{g-1} s_1^2 = s_{g+1}^g \). Moreover, if \( g \) is odd then \( V_4 \hookrightarrow \text{Aut}(X_g) \) implies that

\[
(2^r s_1 - s_g^{r+1})(2^r s_1 + s_g^{r+1}) = 0
\]

where \( r = \left[ \frac{g+1}{2} \right] \). The first factor corresponds to the case when involutions of \( V_4 \hookrightarrow \text{Aut}(X_g) \) lift to involutions in \( \text{Aut}(X_g) \), the second factor corresponds to the case when two of the involutions of \( V_4 \hookrightarrow \text{Aut}(X_g) \) lift to elements of order 4 in \( \text{Aut}(X_g) \).

In the case of genus \( g = 3 \), we have \( s_1 = s_4 \) and \( s_g = \frac{s_3}{2} \) and the relation becomes \( s_4 - 2s_2^2 = 0 \). This gives exactly the cases when the full automorphism group is \( \mathbb{Z}_3^2 \).

We will verify such fact directly below.

5.2.1. **The automorphism group is isomorphic to \( G \cong \mathbb{Z}_3^2 \).** The equation of the curve from Table 3 of [20] is

\[
y^2 = (x^4 + ax^2 + 1)(x^4 + bx^2 + 1)
\]

Let new parameters \( u \) and \( v \) be as follows

\[
u := a + b, \quad \text{and} \quad v = ab.
\]

Then we have

\[
y^2 = x^8 + ux^6 + (v + 2)x^4 + ux^2 + 1
\]

The dihedral invariants are

\[
s_4 = 2u^4, \quad s_3 = 2u^2(v + 2), \quad s_2 = u^2
\]

Then directly we can verify \( u^2 = s_2 \), \( v = \frac{s_3 - 2s_2}{2s_2} \) and

\[
(24) \quad s_4 - 2s_2^2 = 0.
\]
By transforming the coordinate \( X \) as \( X \to \sqrt{u}X \) on the curve in Eq. (23) we get
\[
Y^2 = u^4X^8 + u^4X^6 + (v + 2)(u^2)X^4 + u^2X^2 + 1
\]
or
\[
(25) \quad Y^2 = s_2^2X^8 + s_2^4X^6 + \frac{s_3}{2}X^4 + s_2X^2 + 1
\]
We compute the invariants \( t_1, \ldots, t_6 \) in terms of \( s_3, s_2 \). Eliminating \( s_3 \) and \( s_2 \) from the system of equations gives the locus \( S(\mathbb{Z}_3) \) and rational expressions of \( s_3, s_2 \) in terms of \( t_1, \ldots, t_6 \). The computations are long and the results involve very large expressions. Instead, we provide a quicker proof for the reader which is easier to check.

From the expressions of \( t_1, \ldots, t_6 \) in terms of \( s_3, s_2 \) we eliminate \( s_3 \). In other words, \( s_3 \) is easily written as a rational function in terms of \( s_2, t_1, \ldots, t_6 \). Any software package such as Maple or Mathematica will be able to do this. We are left with 5 equations of degree 20, 18, 16, 23, and 21. Since the function field \( k(S(\mathbb{Z}_3)) \) is a subfield of \( k(s_2) \), then the degree of this extension \( [k(s_2), k(S(\mathbb{Z}_3))] \) is a common divisor of 20, 18, 16, 23, and 21. Therefore, \( [k(s_2), k(S(\mathbb{Z}_3))] = 1 \) and \( k(S(\mathbb{Z}_3)) = k(s_2) \).

**Lemma 6.** Every genus 3 hyperelliptic curve with full automorphism group isomorphic to \( \mathbb{Z}_3 \) has equation
\[
(26) \quad Y^2 = s_2^2X^8 + s_2^4X^6 + \frac{s_3}{2}X^4 + s_2X^2 + 1
\]
for \( s_3, s_2 \neq 0, 4 \). Moreover, \( k(S(\mathbb{Z}_3)) = k(s_4, s_3) \) and therefore the field of moduli is a field of definition.

The result of the Lemma above can be obtained directly by the \( V_t \)-locus, by enforcing the equation \( 2s_4 - s_2^2 = 0 \). The expressions for \( s_3, s_2 \) and the equations of \( S(\mathbb{Z}_3) \) in terms of \( t_1, \ldots, t_6 \) are displayed in [29].

5.2.2. The automorphism group is isomorphic to \( G \cong \mathbb{Z}_4 \): This is the only case that is not a sublocus of the space \( S \). The equation of the curve from Table 3 of [20] is
\[
y^2 = x(x^2 - 1)(x^4 + ax^2 + b)
\]
In this case we have \( J_3 = J_5 = J_7 = 0 \). The defining equations of this space are two polynomials in \( J_2, J_4, J_6, J_8 \). We make them part of the "genus3" package in [29]. It is worth noting that both \( a \) and \( b \) can be expressed as rational functions in \( t_1, \ldots, t_6 \). Hence, in this case the field of moduli is a field of definition.

5.3. 1-dimensional strata.

5.3.1. The automorphism group is isomorphic to \( \mathbb{Z}_2 \times D_5 \): Given a curve \( C \) in the \( \mathbb{Z}_2 \times D_5 \) locus, from Table 1, it has equation:
\[
(27) \quad Y^2 = X^8 + aX^4 + 1,
\]
where \( a \neq \pm 2 \). We calculate the invariants, \( t_1, t_2, \ldots, t_6 \) and denote \( t := a^2 \). Then we have
\[
t_1 = 2 \left( \frac{3t + 980}{140 + t} \right)^2, \quad t_2 = 16 \left( \frac{t - 196}{140 + t} \right)^2, \quad t_3 = 8 \left( \frac{t - 196}{140 + t} \right) \left( \frac{3t + 980}{140 + t} \right),
\]
\[
t_4 = 4 \left( \frac{196 + t}{140 + t} \right), \quad t_5 = 4 \left( \frac{t - 196}{140 + t} \right), \quad t_6 = 128 \left( \frac{9t + 980}{140 + t} \right) \left( \frac{t - 196}{140 + t} \right)^3
\]
These invariants are not defined for \( t = -140 \) and \( t = -\frac{280}{3} \). We can rewrite the above equations as
\[
t = -28 \frac{5t_4 + 28}{t_4 - 4}
\]
and the equations of this submoduli space are given by
\[
t_1 = -\frac{175}{288}t_4^2 + \frac{125}{3456}t_4^3 + \frac{686}{27}, \quad t_2 = t_4^2, \quad t_3 = -6 - \frac{t_4^2}{(5t_4 - 56)}, \quad t_5 = t_4, \quad t_6 = \frac{49}{3}t_4^3 + \frac{5}{12}t_4^4
\]
Notice that we can get the equations in terms of \( J_2, \ldots, J_8 \) very easily by substituting \( t_1, \ldots, t_6 \). Such equations would be valid in even in the cases when some of \( J_i \) are zero.

The equation of the curve can be written in terms of \( t \) as follows. Let \( X \to a^tX \). Then the equation of the curve becomes
\[
Y^2 = tX^8 + tX^4 + 1
\]
Hence, for this family of curves the field of moduli is a field of definition.

**Lemma 7.** Every genus 3 hyperelliptic curve with full automorphism group isomorphic to \( \mathbb{Z}_2 \times D_8 \) has equation
\[
Y^2 = tX^8 + tX^4 + 1
\]
for some \( t \neq 0, 4, -\frac{280}{3} \). If \( t \neq -140, -\frac{280}{3} \) then
\[
t = -28 \frac{5t_4 + 28}{t_4 - 4}
\]
in terms of the absolute invariants and therefore the field of moduli is a field of definition.

5.3.2. The automorphism group is isomorphic to \( D_{12} \): The equations of the curve is:
\[
Y^2 = X(X^6 + aX^3 + 1)
\]
We perform the following coordinate change \( X \to a^tX \) and the equation of the curve becomes
\[
Y^2 = X(tX^6 + tX^3 + 1),
\]
where \( t = a^2 \). Then, we have
\[
t_1 = 9 \frac{(4t + 245)^2}{(-35 + 2t)^4}, \quad t_2 = \frac{(8t + 49)^2}{(-35 + 2t)^2}, \quad t_3 = \frac{1}{3} \frac{(8t + 49)^2}{(-35 + 2t)(4t + 245)}, \quad t_4 = \frac{8t + 49}{-35 + 2t}, \quad t_5 = \frac{8t + 49}{-35 + 2t}, \quad t_6 = \frac{3(12t + 245)(8t + 49)^3}{(-35 + 2t)^4}
\]
We can eliminate \( t \)
\[
t = \frac{7}{2} \frac{5t_4 + 7}{t_4 - 4},
\]
and the equations for the submoduli space become
\[
t_1 = \frac{686}{27} + \frac{125}{54}t_4^3 - \frac{175}{18}t_4^2, \quad t_2 = t_4^2, \quad t_3 = \frac{t_2^2}{5t_4 - 14}, \quad t_5 = t_4, \quad t_6 = \frac{65}{9}t_4^4 - \frac{98}{9}t_4^3
\]
Lemma 8. Every genus 3 hyperelliptic curve with full automorphism group isomorphic to $D_{12}$ has equation
\begin{equation}
Y^2 = X(tX^6 + tX^3 + 1)
\end{equation}
for $t \neq 0, 4$. If $t \neq -\frac{45}{2}, -\frac{245}{4}$ then
\[ t = \frac{7}{2} \frac{5t_4 + 7}{t_4 - 4}, \]
in terms of the absolute invariants and therefore the field of moduli is a field of definition.

5.3.3. The automorphism group is isomorphic to $\mathbb{Z}_2 \times \mathbb{Z}_4$: The equations of the curve is:
\[ y^2 = (x^4 - 1)(x^2 + ax^2 + 1) \]
By a transformation $X \to a^2X$ the equation of the curve becomes
\[ Y^2 = (tx^4 - 1)(tx^4 + tx^2 + 1) \]
Since this curve has an element of order 4 and therefore a factor of $X^4 - 1$ then $J_3 = J_5 = J_7 = 0$. In this case the absolute invariants $t_1, \ldots, t_6$ are not defined. Hence we use the invariants $i_1, \ldots, i_5$ as in Eq. (13).

\begin{align*}
\frac{i_2}{25} &= \frac{64}{25}\left(\frac{t^2 + 9604 - 49t}{(28 + t)^2}\right), \\
\frac{i_4}{125} &= \frac{512}{125}\left(\frac{(t - 98)\left((t^2 - 637t + 9604)\right)}{(28 + t)^3}\right), \\
\frac{i_6}{125} &= \frac{512}{125}\left(\frac{11t^4 - 12397t^3 + 1296540t^2 + 368947264 - 43294832t}{(28 + t)^4}\right)
\end{align*}

Hence, we get
\begin{align*}
t &= 28 \frac{15625i_2i_4 - 152500i_4 + 24375i_2^2 + 1215200i_4 - 2809856}{-15625i_2i_4 + 2500i_4 + 245625i_2^2 - 725600i_4 + 401408}
\end{align*}

and
\begin{align*}
-81462500i_4 + 927746400i_4 - 963780608 - 256055625i_2^2 - 1953125i_4^2 &
\begin{cases}
+36093750i_2i_4 + 15187500i_3^2 & = 0 \\
-22689450000i_6 - 4593393436800i_2 + 4628074479616 + 52734375i_6^2 + 8912109375i_2^4 & +1371093750i_2^2i_6 + 5788125000i_2i_6 + 1572126780000i_2^2 - 215275375000i_2^3 & = 0
\end{cases}
\end{align*}

5.4. 0-dimensional strata. We first briefly go over the 0-dimensional cases.

5.4.1. Case : $G \cong \mathbb{Z}_2 \times S_4$: The equation of the curve is $y^2 = x^8 + 14x^4 + 1$ and its absolute invariants are

\[ (t_1, t_2, t_3, t_4, t_5, t_6) = \left(\frac{15435}{8}, \frac{784}{25}, \frac{56}{5}, \frac{-28}{5}, \frac{28}{5}, \frac{7760032}{125}\right) \]

The next two cases correspond to curves with $J_3 = J_5 = J_7 = 0$. In both cases we use invariants $i_2, i_4, i_6$ as in Eq. (13).
5.4.2. Case: $G \cong U_6$: The equations of the curve is given by $y^2 = x(x^6 - 1)$ and its absolute invariants are $i_1 = i_3 = i_5 = 0$ and 

$$i_2 = \frac{49}{25}, \quad i_4 = \frac{-343}{125}, \quad i_6 = \frac{7203}{125}$$

5.4.3. Case: $G \cong V_8$: The equations of the curve is $y^2 = x^8 - 1$ and its absolute invariants are $i_1 = i_3 = i_5 = 0$ and 

$$i_2 = \frac{784}{25}, \quad i_4 = \frac{-21952}{125}, \quad i_6 = \frac{-307328}{125}$$

The following theorem determines relations among $s_2, s_3, s_4$ for each group $G$ such that $V_4 \rightarrow G$.

**Theorem 4.** Let $X$ be a curve in $\mathcal{S} = \mathcal{M}_b^3 \cap \mathcal{H}_3$. Then, one of the following occurs:

i) $\text{Aut}(X) \cong \mathbb{Z}_2^2$ if and only if $s_4 - 2s_2^2 = 0$

ii) $\text{Aut}(X) \cong \mathbb{Z}_2 \times D_8$ if and only if $s_2 = s_4 = 0$

iii) $\text{Aut}(X) \cong \mathbb{Z}_2 \times \mathbb{Z}_4$ if and only if $s_4 + 2s_2^2 = 0$ and $s_3 = 0$.

iv) $\text{Aut}(X) \cong D_{12}$ if and only if

$$s_3 = \frac{1}{75} (9s_2 - 224)(s_2 - 196)$$

$$s_4 = -\frac{9}{125} s_2^3 + \frac{1962}{125} s_2^2 - \frac{84048}{1125} s_2 + \frac{9834496}{1125}$$

*(32)*

**Proof.** Part i) and ii) are immediate consequences of the previous discussion. For part iii), we start with the curve $X$ with equation

$$Y^2 = (X^4 - 1)(X^4 + aX^2 + 1).$$

Transforming $X \rightarrow \epsilon_{16} X$ we have

$$Y^2 = X^8 - \epsilon_{16}^6 aX^6 + \epsilon_{16}^2 aX^2 + 1,$$

where $\epsilon_{16}$ is the 16-th root of unity. The dihedral invariants are

$$s_2 = a^2, \quad s_3 = 0, \quad s_4 - 2a^4$$

By eliminating $a^2$ we have that

$$s_4 + 2s_2^2 = 0, \quad \text{and} \quad s_3 = 0$$

Conversely, if the above equations hold then $a^2 + c^2 = 0$. Take a curve with equation as in Eq. (4) and compute $i_2, i_4, i_6$. These invariants satisfy Eqs. (30). Hence, the curve is in the $(\mathbb{Z}_2 \times \mathbb{Z}_4)$–locus.

For case iv), let $X$ be a curve with equation $Y^2 = X(X^6 + aX^3 + 1)$, where $a \neq 0, \pm 2$. By a transformation $X \rightarrow \frac{X + 1}{\lambda + 1}$, $X$ has equation

$$Y^2 = X^8 + (5 - 9\lambda)X^6 + 3(\lambda + 1)X^4 + (5\lambda - 9)X^2 + \lambda$$

where $\lambda = \frac{a - 2}{a + 2}, \lambda \neq 0, \pm 1$. Then, by another transformation $X \rightarrow \sqrt[3]{a}X$, we get the following curve

$$Y^2 = X^8 + \frac{(5 - 9\lambda)}{\lambda^4} X^6 + \frac{3(\lambda + 1)}{\lambda^4} X^4 + \frac{(5\lambda - 9)}{\lambda^2} X^2 + 1$$
Computing the dihedral invariants:

\[ s_2 = \frac{1}{\lambda} (5 - 9\lambda)(5\lambda - 9) \]
\[ s_3 = \frac{3}{\lambda} (\lambda + 1) \left[ (5 - 9\lambda)^2 + \frac{1}{\lambda} (5\lambda - 9)^2 \right] \]
\[ s_4 = \frac{1}{\lambda} (5 - 9\lambda)^4 + \frac{1}{\lambda^3} (5\lambda - 9)^4 \]

Eliminating \( \lambda \), we get

\[ \lambda = \frac{45}{106 - s_2} \]
\[ s_3 = \frac{1}{75} (9s_2^2 - 224)(s_2 - 196) \]
\[ s_4 = \frac{9}{125} s_2^3 + \frac{1962}{125} s_2^2 - \frac{840448}{1125} s_2 + \frac{9834496}{1125} \quad (33) \]

Conversely, let us assume that the equations in (33) hold. From the expressions of \( t_1, \ldots, t_6 \) in Eqs. (18) and equations in (33) we eliminate \( s_2, s_3, s_4 \) to get the equations of the \( D_{12} \)-locus in Eq. (29). The proof is complete. \( \square \)

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