Using a new zero forcing process to guarantee the Strong Arnold Property

Jephian C.-H. Lin†

January 5, 2018

Abstract
The maximum nullity $M(G)$ and the Colin de Verdière type parameter $\xi(G)$ both consider the largest possible nullity over matrices in $S(G)$, which is the family of real symmetric matrices whose $i,j$-entry, $i \neq j$, is nonzero if $i$ is adjacent to $j$, and zero otherwise; however, $\xi(G)$ restricts to those matrices $A$ in $S(G)$ with the Strong Arnold Property, which means $X \circ O$ is the only symmetric matrix that satisfies $A \circ X = O$, $I \circ X = O$, and $AX = O$. This paper introduces zero forcing parameters $Z_{\text{SAP}}(G)$ and $Z_{\text{vc}}(G)$, and proves that $Z_{\text{SAP}}(G) = 0$ implies every matrix $A \in S(G)$ has the Strong Arnold Property and that the inequality $M(G) - Z_{\text{vc}}(G) \leq \xi(G)$ holds for every graph $G$. Finally, the values of $\xi(G)$ are computed for all graphs up to 7 vertices, establishing $\xi(G) = \lfloor \frac{1}{2} \rfloor Z(G)$ for these graphs.

Keywords: Strong Arnold Property, SAP zero forcing, minimum rank, maximum nullity, Colin de Verdière type parameter, vertex cover.

AMS subject classifications: 05C50, 05C57, 05C83, 15A03, 15A18, 15A29.

1 Introduction

A minimum rank problem for a graph $G$ is to determine what is the smallest possible rank, or equivalently the largest possible nullity, among a family of matrices associated with $G$. One classical way to associate matrices to a graph $G$ is through $S(G)$, which is defined as the set of all real symmetric matrices whose $i,j$-entry, $i \neq j$, is nonzero whenever $i$ and $j$ are adjacent in $G$, and zero otherwise. Note that the diagonal entries can be any real number. Another association is $S_+(G)$, which is the set of positive semidefinite matrices in $S(G)$. Thus, the maximum nullity $M(G)$ and the positive semidefinite maximum null-

†Department of Mathematics, Iowa State University, Ames, IA 50011, USA (chlin@iastate.edu).
The classical minimum rank problem is a branch of the inverse eigenvalue problem, which asks for a given multi-set of real numbers, is there a matrix in $S(G)$ such that its spectrum is composed of these real numbers. If $\lambda$ is an eigenvalue of some matrix $A \in S(G)$, then its multiplicity should be no higher than $M(G)$, for otherwise $A - \lambda I$ has nullity higher than $M(G)$. Similarly, $M_+(G)$ provides an upper bound for the multiplicities of the smallest and the largest eigenvalues. Also, $M_+(G)$ is closely related to faithful orthogonal representations \cite{12}.

Other families of matrices are defined through the Strong Arnold Property. A matrix $A$ is said to have the Strong Arnold Property (or SAP) if the zero matrix is the only symmetric matrix $X$ that satisfies the three conditions $A \circ X = O$, $I \circ X = O$, and $AX = O$. Here $I$ and $O$ are the identity matrix and the zero matrix of the same size as $A$, respectively, and $\circ$ is the Hadamard (entrywise) product of matrices. By adding the SAP to the conditions of the abovementioned families, the Colin de Verdière type parameters are defined as

$$\xi(G) = \max\{\text{null}(A) : A \in S(G), A \text{ has the SAP}\} \quad \text{\cite{5}},$$

$$\nu(G) = \max\{\text{null}(A) : A \in S_+(G), A \text{ has the SAP}\} \quad \text{\cite{8}}.$$ 

These parameters are variations of the original Colin de Verdière parameter $\mu(G)$ \cite{7}, which is defined as the maximum nullity over matrices $A \in S(G)$ such that

- every off-diagonal entry of $A$ is non-positive (called a generalized Laplacian),
- $A$ has exactly one negative eigenvalue including the multiplicity, and
- $A$ has the SAP.

In order to see how the SAP makes a difference between these parameters, we define $M_\mu(G)$ as the maximum nullity of the same family of matrices by ignoring the SAP, i.e. the maximum nullity of matrices $A \in S(G)$ such that $A$ is a generalized Laplacian and has exactly one negative eigenvalue.

The SAP gives $\xi(G)$, $\nu(G)$, and $\mu(G)$ nice properties. For example, they are minor monotone \cite{12}. A graph $H$ is a minor of a graph $G$ if $H$ can be obtained from $G$ by a sequence of deleting edges, deleting vertices, and contracting edges; a graph parameter $\zeta$ is said to be minor monotone if $\zeta(H) \leq \zeta(G)$ whenever $H$ is a minor of $G$. By the graph minor theorem (e.g., see \cite{10}), for a given integer $d$ and a minor monotone parameter $\zeta$, the minimal forbidden minors for $\zeta(G) \leq d$ consist of only finitely many graphs. Here $\zeta$ can be $\xi$, $\nu$ or $\mu$. More specifically,
\( \mu(G) \leq 3 \) if and only if \( G \) is a planar graph \[17\], which is characterized by the forbidden minors \( K_5 \) and \( K_{3,3} \).

However, the SAP also makes the Colin de Verdière type parameters less controllable by the existing tools. For example, zero forcing parameters, which will be defined in Section \ref{section1.2} were used extensively as a bound for the minimum controllable by the existing tools. For example, zero forcing parameters, which were used extensively as a bound for the minimum controllable by the existing tools. For example, zero forcing parameters, which were used extensively as a bound for the minimum controllable by the existing tools. For example, zero forcing parameters, which were used extensively as a bound for the minimum controllable by the existing tools. For example, zero forcing parameters, which were used extensively as a bound for the minimum controllable by the existing tools.

For the classical zero forcing number \( Z(G) \), it is known that \( M(G) \leq Z(G) \) for all graphs \[2\], and \( M(G) = Z(G) \) when \( G \) is a tree or \( |G| \leq 7 \) \[2\]. An analogy for \( \xi(G) \) is the minor monotone floor of the zero forcing number, which is denoted as \( [Z](G) \) and will be defined in Section \ref{section4}. It is known that \( \xi(G) \leq [Z](G) \) for all graphs \[4\]. The similar statement \( \xi(G) = [Z](G) \) is not always true when \( G \) is a tree \[4\], and no results about \( \xi(G) \) and \( [Z](G) \) for small graphs are known.

The main goal of this paper is to establish a connection between zero forcing parameters and the SAP, and derive consequences. This leads to some questions. Does some graph structure guarantee that every \( A \in \mathcal{S}(G) \) has the SAP? Thus, the maximum nullity does not change when the SAP condition is added. Or, is there a strategy to perturb any given matrix such that it guarantees the SAP? Thus, the rank changed by the perturbation gives an upper bound for \( M(G) - \xi(G) \).

In Section \ref{section2} we introduce a new parameter \( Z_{\text{SAP}}(G) \) and its variants \( Z_{\text{SAP}}' \) and \( Z_{\text{SAP}}'' \), and prove in Theorem \ref{thm2.6} that under the condition \( Z_{\text{SAP}}(G) = 0 \), every matrix \( A \in \mathcal{S}(G) \) has the SAP. Thus, \( \xi(G) = M(G) \), \( \nu(G) = M_s(G) \), and \( \mu(G) = M_{ss}(G) \) when \( Z_{\text{SAP}}(G) = 0 \), so finding the value of Colin de Verdière type parameters is equivalent to finding the value of the corresponding parameters. Table \ref{table1} in Section \ref{subsection2.2} indicates that there are actually a considerable proportion of graphs that have this property.

In Section \ref{section3}, another parameter \( Z_{\text{vc}}(G) \) and its variant \( Z_{\text{vc}}'(G) \) are defined, and Theorem \ref{thm3.2} states that \( M(G) - \xi(G) \leq Z_{\text{vc}}(G) \) for every graph \( G \). With the help of \( Z_{\text{SAP}}(G) \), \( Z_{\text{vc}}(G) \), and some existing theorems, Section \ref{section4} provides the result that \( \xi(G) = [Z](G) \) for graphs \( G \) up to 7 vertices.

All parameters introduced in this paper and their relations are illustrated in Figure \ref{figure1}. A brief description of the related theorems are given on the sides. A line between two parameters means the lower one is less than or equal to the upper one.

Throughout the paper, the neighborhood of a vertex \( i \) in a graph \( G \) is denoted as \( N_G(i) \), while the closed neighborhood is denoted as \( N_G[i] \), which equals \( N_G(i) \cup \{i\} \). The induced subgraph on a vertex set \( W \) of \( G \) is denoted as \( G[W] \). If \( A \) is a matrix, \( U \) and \( W \) are subsets of the row and column indices of \( A \) respectively, then \( A[U,W] \) is the submatrix of \( A \) induced on the rows of \( U \) and columns of \( W \); if \( U \) and \( W \) are ordered sets, then permute the rows and columns of this submatrix accordingly.

\section{1.1 SAP system and its matrix representation}

Let \( G \) be a graph on \( n \) vertices, and \( \overline{m} = |E(\overline{G})| \). In order to see if a matrix \( A \in \mathcal{S}(G) \) has the SAP or not, the matrix \( X \) can be viewed as a symmetric matrix.
with $m$ variables at the positions of non-edges so that $X$ satisfies $A \circ X = I \circ X = O$. Next, $AX = O$ leads to $n^2$ restrictions on the $m$ variables, which forms a linear system. Call this linear system the SAP system of $A$, which can also be written as an $n^2 \times m$ matrix.

**Definition 1.1.** Let $G$ be a graph on $n$ vertices, $m = |E(G)|$, and $A = [a_{i,j}] \in \mathcal{S}(G)$. Given an order of the set of non-edges, the SAP matrix of $A$ with respect a given order of the non-edges is an $n^2 \times m$ matrix $\Psi$ whose rows are indexed by pairs $(i, k)$ and columns are indexed by the non-edges $\{j, h\}$ such that

$$
\Psi_{(i,k),(j,h)} = \begin{cases} 
0 & \text{if } k \notin \{j, h\}, \\
 a_{i,j} & \text{if } k \in \{j, h\} \text{ and } k = h.
\end{cases}
$$

The rows follow the order $(i, k) < (j, h)$ if and only if $k < h$, or $k = h$ and $i < j$; the columns follow the order of the non-edges.

**Remark 1.2.** Let $G$ be a graph, $A \in \mathcal{S}(G)$, and $\Psi$ the SAP matrix of $A$ with respect a given order of the non-edges. The columns of $\Psi$ correspond to the $m$ variables in $X$, and the row for $(i, j)$ represents the equation $(AX)_{i,j} = 0$. Therefore, a matrix has the SAP if and only if the corresponding SAP matrix is full-rank.

The rows of $\Psi$ can be partitioned into $n$ blocks, each having $n$ elements. The $k$-th block are those rows indexed by $(i, k)$ for $1 \leq i \leq n$. Let $v_j$ be the $j$-th column of $A$. For the submatrix of $\Psi$ induced by the rows in the $k$-th block, the $\{j, h\}$ column is $v_j$ if $k \in \{j, h\}$ and $k = h$, and is a zero vector otherwise. Equivalently, on the $\{i, j\}$ column of $\Psi$, the $i$-th block is $v_j$, the $j$-th block is $v_i$, while other blocks are zero vectors.

### Figure 1: Parameters introduced in this paper.

| $|E(G)|$ | $|V(G)|$ |
|--------|--------|
| $Z_{\text{SAP}}(G)$ | $Z_{\text{SAP}}$ |
| $M(G) - Z_{\text{vc}}(G) \leq \xi(G)$ | Theorem 3.2 |
| $Z'_{\text{SAP}}(G) = 0$ implies | $Z'_{\text{SAP}}$ |
| every $A \in \mathcal{S}(G)$ has the SAP | $M'_+(G) - Z_{\text{vc}}^\ell(G) \leq \nu(G)$ | Theorem 3.6 |
| $Z''_{\text{SAP}}(G) = 0$ implies | $Z''_{\text{SAP}}$ |
| every $A \in \mathcal{S}(G)$ has the SAP | $0$ |

With $m$ variables at the positions of non-edges so that $X$ satisfies $A \circ X = I \circ X = O$. Next, $AX = O$ leads to $n^2$ restrictions on the $m$ variables, which forms a linear system. Call this linear system the SAP system of $A$, which can also be written as an $n^2 \times m$ matrix.

**Definition 1.1.** Let $G$ be a graph on $n$ vertices, $m = |E(G)|$, and $A = [a_{i,j}] \in \mathcal{S}(G)$. Given an order of the set of non-edges, the SAP matrix of $A$ with respect a given order of the non-edges is an $n^2 \times m$ matrix $\Psi$ whose rows are indexed by pairs $(i, k)$ and columns are indexed by the non-edges $\{j, h\}$ such that

$$
\Psi_{(i,k),(j,h)} = \begin{cases} 
0 & \text{if } k \notin \{j, h\}, \\
 a_{i,j} & \text{if } k \in \{j, h\} \text{ and } k = h.
\end{cases}
$$

The rows follow the order $(i, k) < (j, h)$ if and only if $k < h$, or $k = h$ and $i < j$; the columns follow the order of the non-edges.

**Remark 1.2.** Let $G$ be a graph, $A \in \mathcal{S}(G)$, and $\Psi$ the SAP matrix of $A$ with respect a given order of the non-edges. The columns of $\Psi$ correspond to the $m$ variables in $X$, and the row for $(i, j)$ represents the equation $(AX)_{i,j} = 0$. Therefore, a matrix has the SAP if and only if the corresponding SAP matrix is full-rank.

The rows of $\Psi$ can be partitioned into $n$ blocks, each having $n$ elements. The $k$-th block are those rows indexed by $(i, k)$ for $1 \leq i \leq n$. Let $v_j$ be the $j$-th column of $A$. For the submatrix of $\Psi$ induced by the rows in the $k$-th block, the $\{j, h\}$ column is $v_j$ if $k \in \{j, h\}$ and $k = h$, and is a zero vector otherwise. Equivalently, on the $\{i, j\}$ column of $\Psi$, the $i$-th block is $v_j$, the $j$-th block is $v_i$, while other blocks are zero vectors.
Example 1.3. Let $G = P_4$ be the path on four vertices, labeled by the linear order. Consider a matrix $A \in S(G)$ and the matrix $X$ with three variables, as shown below.

$$AX = \begin{bmatrix}
1 & 2 & 3 & 4 \\
1 & -1 & 1 & 0 \\
2 & 1 & -1 & 1 \\
3 & 0 & 0 & 1 \\
4 & 0 & 0 & 1 \\
\end{bmatrix}, \quad X = \begin{bmatrix}
x_{(1,3)} & x_{(1,4)} & x_{(2,4)} \\
0 & 0 & 0 \\
0 & 0 & 0 \\
x_{(1,3)} & 0 & 0 \\
x_{(1,4)} & x_{(2,4)} & 0 \\
\end{bmatrix}$$

The SAP matrix of $A$ with respect to the order $(\{1, 3\}, \{1, 4\}, \{2, 4\})$ is a matrix $\Psi$ representing the linear system for $AX = O$ with three variables $x_{(1,3)}, x_{(1,4)}, x_{(2,4)}$. For convenience, write $A = [v_1 \ v_2 \ v_3 \ v_4]$, where $v_j$ is the $j$-th column vector of $A$. Now $AX = O$ means

$$\sum_{j \in N_G(k)} x_{(j,k)}v_j = 0 \text{ for each } k \in V(G).$$

Thus,

$$\Psi = \begin{bmatrix}
1 & v_3 & v_4 & 0 \\
2 & 0 & 0 & v_4 \\
3 & v_1 & 0 & 0 \\
4 & 0 & v_1 & v_2 \\
\end{bmatrix}.$$

### 1.2 Zero forcing parameters

On a graph $G$, the conventional zero forcing game (ZFG) is a color-change game such that each vertex is colored blue or white initially, and then the color change rule (CCR) is applied repeatedly. If starting with an initial blue set $B \subseteq V(G)$ and every vertex turns blue eventually, this set $B$ is called a zero forcing set (ZFS). The zero forcing number is defined as the minimum cardinality of a ZFS.

Different types of zero forcing numbers are discussed in the literature (e.g., see [3, 4, 12]). Most of them serve as upper bounds of different types of maximum nullities. Here we consider three types of the zero forcing numbers $Z, Z_\ell, Z_+$ with the corresponding color change rules:
(CCR-Z) If \( i \) is a blue vertex and \( j \) is the only white neighbor of \( i \), then \( j \) turns blue.

(CCR-\( \ell \)) CCR-Z can be used to perform a force. Or if \( i \) is a white vertex without white neighbors and \( i \) is not isolated, then \( i \) turns blue.

(CCR-\( + \)) Let \( B \) be the set of blue vertices at some stage and \( W \) the vertices of a component of \( G - B \). CCR-Z is applied to \( G[B \cup W] \) with blue vertices \( B \).

When a zero forcing game is mentioned, it is equipped with a color change rule, and we use \( i \rightarrow j \) to denote a corresponding force (i.e. \( i \) forcing \( j \) to become blue). Note that for CCR-\( \ell \), it is possible to have \( i \rightarrow i \).

It is known [2–4] that \( M(G) \leq Z(G) \), \( M_{\ell}(G) \leq Z_{\ell}(G) \), and \( Z_{\ell}(G) \leq Z(G) \). Denote \( S_{\ell}(G) \) as those matrices in \( S(G) \) whose \( i,i \)-entry is zero if and only if vertex \( i \) is an isolated vertex. Then every matrix \( A \in S_{\ell}(G) \) has nullity at most \( Z_{\ell}(G) \).

All these results rely on Proposition 1.4.

Proposition 1.4. [2, 3, 13] Let \( G \) be a graph on \( n \) vertices. Suppose at some stage \( B \) is the set of blue vertices.

• If \( i \rightarrow j \) under CCR-Z, then for any matrix \( A \in S(G) \) with column vectors \( \{v_s\}_{s=1}^n \), \( \sum_{s \in B} x_s v_s = 0 \) implies \( x_j = 0 \).

• If \( i \rightarrow j \) under CCR-\( \ell \), then for any matrix \( A \in S_\ell(G) \) with column vectors \( \{v_s\}_{s=1}^n \), \( \sum_{s \in B} x_s v_s = 0 \) implies \( x_j = 0 \).

• If \( i \rightarrow j \) under CCR-\( + \), then for any matrix \( A \in S_{\ell}(G) \) with column vectors \( \{v_s\}_{s=1}^n \), \( \sum_{s \in B} x_s v_s = 0 \) implies \( x_j = 0 \).

2 SAP zero forcing parameters

In this section, we introduce a new parameter \( Z_{\text{SAP}}(G) \) and prove that if \( Z_{\text{SAP}}(G) = 0 \) then every matrix \( A \in S(G) \) has the SAP, which implies \( M(G) = \xi(G) \). We also introduce similar parameters and results for other variants.

First we give two examples illustrating what we called in Definition 2.4 the forcing triple and the odd cycle rule.

Example 2.1. Consider the graph \( P_4 \). Let \( A \) be the matrix as in Example 1.3 and \( v_j \) its \( j \)-th column. In Example 1.3, we know the SAP matrix of \( A \) can be written as

\[
\begin{bmatrix}
  x_{(1,3)} & x_{(1,4)} & x_{(2,4)} \\
  v_3 & v_4 & 0 \\
  0 & 0 & v_4 \\
  v_1 & 0 & 0 \\
  0 & v_1 & v_2 \\
\end{bmatrix}
\]
Since \( \mathbf{v}_4 \) is the only nonzero vector on the second block-row, \( x_{\{2,4\}} \) must be 0 in this linear system. Similarly, \( \mathbf{v}_1 \) is the only nonzero vector on the third block-row, so \( x_{\{1,3\}} = 0 \). Provided that \( x_{\{1,3\}} = x_{\{2,4\}} = 0 \), the structure on the first block-row forces \( x_{\{1,4\}} = 0 \). Since this argument holds for every matrix in \( S(G) \), every matrix in \( S(G) \) has the SAP.

**Example 2.2.** Let \( G = K_{1,3} \). Consider the matrices \( A \) and \( X \) as

\[
A = \begin{bmatrix}
d_1 & a_1 & a_2 & a_3 \\
da_1 & d_2 & 0 & 0 \\
da_2 & 0 & d_3 & 0 \\
da_3 & 0 & 0 & d_4
\end{bmatrix} \quad \text{and} \quad X = \begin{bmatrix}
0 & 0 & 0 & 0 \\
0 & x_{\{2,3\}} & x_{\{2,4\}} & 0 \\
0 & x_{\{2,3\}} & 0 & x_{\{3,4\}} \\
0 & x_{\{2,4\}} & x_{\{3,4\}} & 0
\end{bmatrix}.
\]

Let \( \mathbf{v}_j \) be the \( j \)-th column of \( A \). Then the SAP matrix of \( A \) with respect to the order \( (\{2,3\}, \{3,4\}, \{2,3\}) \) can be written as

\[
\Psi = \begin{bmatrix}
\begin{array}{c}
x_{\{2,3\}} \\
x_{\{3,4\}} \\
x_{\{2,4\}} \end{array} \\
\mathbf{v}_3 \\
\mathbf{v}_2 \\
\mathbf{v}_4 \\
\mathbf{v}_2
\end{bmatrix}.
\]

Recall that the row with index \( (i,j) \) is the \( i \)-th row in the \( j \)-th block. Thus the submatrix induced by rows \( \{(1,2),(1,3),(1,4)\} \) is

\[
\begin{bmatrix}
a_2 & 0 & a_3 \\
a_1 & a_3 & 0 \\
0 & a_2 & a_1
\end{bmatrix},
\]

whose determinant is always nonzero if \( a_1, a_2, a_3 \neq 0 \). This means the SAP matrix of \( A \) is always full-rank, regardless the choice of \( A \in S(G) \). Hence every matrix \( A \in S(G) \) has the SAP. This reason behind this is because a 3-cycle appears in \( \overline{G} \).

As shown in Example 2.1 and Example 2.2, some graph structures guarantee that every matrix described by the graph has the SAP. This assurance is given by forcing \( x_e = 0 \) step by step or by the occurrence of some odd cycle inside \( \overline{G} \). Utilizing these ideas, we design the SAP zero forcing game, where the information \( x_e = 0 \) is stored by coloring the non-edge \( e \) blue.

Different from the conventional zero forcing game, the SAP zero forcing game is coloring “non-edges” to be blue or white, instead of coloring vertices; also, a set of initial blue non-edges is called a zero forcing set if every non-edge turns blue eventually by repeated applications of the given color change rules.

Let \( G \) be a graph and \( i \in V(G) \). Recall that \( N_G(i) \) is the neighborhood of \( i \) in \( G \). For \( B_E \) a set of edges (2-sets), the notation \( N_{B_E}(i) \) denotes the vertices \( j \) with \( \{i,j\} \in B_E \).

The definition of \( Z_{SAP}(G) \) uses the concept of local games, which we now define.
Definition 2.3. Let $G$ be a graph with some non-edges $B_E$ colored blue, and $k \in V(G)$. The local game $\phi_Z(G, B_E, k)$ is the conventional zero forcing game on $G$ equipped with CCR-$Z$ and the initial blue set $\phi_k(G, B_E) := N_G[k] \cup N_{B_E}(k)$. When $Z$ is replaced by another zero forcing rules, such as $Z_{\ell}$ or $Z_+$, the setting remains the same but a different rule applies.

Definition 2.4. For a graph $G$, the SAP zero forcing number $Z_{\text{SAP}}(G)$ is the minimum number of blue non-edges such that every non-edge will become blue by repeated applications of the color change rule for $Z_{\text{SAP}}$ (CCR-$Z_{\text{SAP}}$):

- Suppose at some stage, $B_E$ is the set of blue non-edges and $\{j, k\}$ is a white non-edge. If $i \to j$ in $\phi_Z(G, B_E, k)$ for some vertex $i$, then the non-edge $\{j, k\}$ is changed to blue. This is denoted as $(k : i \to j)$.
- Let $G_W$ be the graph whose edges are the white non-edges. If for some vertex $i$, $G_W[N_G(i)]$ contains a component that is an odd cycle $C$, then all non-edges on $C$ turn blue. This is denoted as $(i \to C)$.

The three vertices $i, j, k$ in the first rule is called a forcing triple; the second rule is called the odd cycle rule.

The odd cycle rule follows a similar idea from the odd cycle zero forcing number [18].

Lemma 2.5. For any nonzero real numbers $a_1, a_2, \ldots, a_n$ with $n$ odd, a matrix of the form

$$
\begin{bmatrix}
a_2 & 0 & \cdots & 0 & a_n \\
0 & a_1 & 0 & \cdots & 0 \\
\vdots & \ddots & \ddots & \ddots & \ddots \\
0 & \cdots & 0 & a_n & 0 \\
0 & \cdots & 0 & a_{n-1} & a_1
\end{bmatrix}
$$

is nonsingular.

Proof. Let $A$ be a matrix of the described form. When $n$ is odd,

$$
\det(A) = 2\prod_{i=1}^{n} a_i,
$$

which is nonzero provided that $a_i$'s are all nonzero. Hence $A$ is nonsingular. □

Theorem 2.6. Suppose $G$ is a graph with $Z_{\text{SAP}}(G) = 0$. Then every matrix in $S(G)$ has the SAP. Therefore, $M(G) = \xi(G)$, $M_s(G) = \nu(G)$, and $M_\mu(G) = \mu(G)$.

Proof. Let $A = [a_{i,j}] \in S(G)$ with $v_j$ as the $j$-th column vector. Pick an order for the set of non-edges, and let $\Psi$ be the SAP matrix for $A$ with respect to the given order. Suppose $x$ is a vector such that $\Psi x = 0$. Then $x = (x_e)_{e \in E(G)}$ such that the entries of $x$ are indexed by the non-edges of $G$ in the given order. We relate the SAP zero forcing game to the zero-nonzero pattern of $x$. 


Claim 1: Suppose at some stage, \( B_E \) is the set of blue non-edges, and \((k : i \rightarrow j)\) is a forcing triple. Then \( x_e = 0 \) for all \( e \in B_E \) implies \( x_{(j,k)} = 0 \).

To establish the claim, recall that the condition \( \Psi \mathbf{x} = \mathbf{0} \) on those rows in the \( k \)-th block means
\[
\sum_{s \in N_G(k)} x_{(s,k)} \mathbf{v}_s = \mathbf{0}.
\]
Suppose \( x_e = 0 \) for all \( e \in B_E \). Then this equality reduces to
\[
\sum_{s \in N_G(k) \cup NB_E(k)} x_{(s,k)} \mathbf{v}_s = \mathbf{0}.
\]

Since by Definition 2.3, the set \( \phi_k(G, B_E) = N_G[k] \cup NB_E(k) \) is exactly the set of initial blue vertices in \( \phi_Z(G, B_E, k) \), the force \( i \rightarrow j \) in \( \phi_Z(G, B_E, k) \) implies \( x_{(j,k)} = 0 \) by Proposition 1.

Claim 2: Suppose at some stage, \( B_E \) is the set of blue non-edges, and \((i \rightarrow C)\) is applied by the odd cycle rule. Then \( x_e = 0 \) for all \( e \in B_E \) implies \( x_e = 0 \) for every \( e \in E(C) \).

To establish the claim, let \( \overline{G}_W \) be the graph whose edges are the white non-edges at this stage. Since \((i \rightarrow C)\) is applied by the odd cycle rule, \( C \) is a component in \( \overline{G}_W[N_G(i)] \) and \(|V(C)| = d\) is an odd number. Following the cyclic order, write the vertices in \( V(C) \) as \( \{k_s\}_{s=1}^d \), and \( e_s = \{k_s, k_{s+1}\} \), with the index taken modulo \( d \).

Denote \( U = \{(i, k_s)\}_{s=1}^d, W_1 = \{e_s\}_{s=1}^d, \) and \( W_2 \) as those white non-edges not in \( W_1 \). For each \( (i, k_s) \in U, \Psi_{(i,k_s), e_{s-1}} = a_{i,k_s} \), and \( \Psi_{(i,k_s), e_s} = a_{i,k_s} \); for every white non-edge \( e = \{j, h\} \) other than \( e_{s-1} \) and \( e_s \), either \( k_s \not\in \{j, h\} \) or \( k_s = h \) but \( j \) is not adjacent to \( i \), so \( \Psi_{(i,k_s), e} = 0 \) by Definition 1.1. This means \( \Psi[U, W_2] = O \) and \( \Psi[U, W_1] \) is of the form described in Lemma 2.5. Consequently, \( x_e = 0 \) for all \( e \in B_E \) implies \( x_e = 0 \) for every non-edge \( e \in E(C) \).

By the claims, \( Z_{\text{SAP}}(G) = 0 \) means all of the \( x_e \) will be forced to zero, so \( \mathbf{x} = 0 \) is the only vector in the right kernel of \( \Psi \). This means \( \Psi \) is full-rank.

Since the argument works for every matrix \( A \in \mathcal{S}(G) \), \( Z_{\text{SAP}}(G) = 0 \) implies every matrix \( A \in \mathcal{S}(G) \) has the SAP. Consequently, \( M(G) = \xi(G), M_\nu(G) = \nu(G), \) and \( M_\mu(G) = \mu(G) \). \( \square \)

Remark 2.7. With and without the restriction of having the SAP, the inertia sets that can be achieved by matrices in \( \mathcal{S}(G) \) are considered in the literature (e.g., see [1][6]). With the help of Theorem 2.6, if \( Z_{\text{SAP}}(G) = 0 \), then these two inertia sets are the same.

Corollary 2.8. If \( G \) has no isolated vertices and \( \overline{G} \) is a forest, then \( Z_{\text{SAP}}(G) = 0 \) and every matrix in \( \mathcal{S}(G) \) has the SAP.

Proof. Suppose at some stage \( \overline{G}_W \) is the graph whose edges are the white non-edges. Since \( \overline{G} \) is a forest, \( \overline{G}_W \) always has a leaf \( k \), unless \( \overline{G}_W \) contains no edge. Let \( j \) be the only neighbor of \( k \) in \( \overline{G}_W \), and let \( i \) be one of the neighbor of \( j \) in \( G \). Since \( G \) has no isolated vertices, \( i \) always exists. Thus, in the local game \( \phi_Z(G, E(G) \setminus E(\overline{G}_W), k) \), every vertex is blue except \( j \), so \( i \rightarrow j \). Therefore,
(k : i → j) applies and {j,k} turns blue. Continuing this process, all non-edge becomes blue, so \( Z_{SAP}(G) = 0 \).

Note that the condition that \( G \) has no isolated vertices is crucial for Corollary 2.8. For example, \( Z_{SAP}(K_{1,n}) > 0 \). In fact, \( Z_{SAP}(G) = 0 \) does not happen only when \( G \) is a forest. Example 2.9 gives a graph \( G \) such that \( Z_{SAP}(G) = 0 \). We will see in Table 1 that there are a considerable number of graphs having the property \( Z_{SAP}(G) = 0 \).

**Example 2.9.** Let \( G \) be the graph shown in Figure 2. Following the steps listed in Figure 2, every non-edge turns blue, so \( Z_{SAP}(G) = 0 \). Observe that at the beginning, the graph \( G_W \) of white non-edges is the same as \( G \), and the odd cycle rule can be used to perform \((2 \rightarrow C)\). This will accelerate the process but not change the result. By Theorem 2.6, every matrix \( A \in S(G) \) has the SAP, so \( \xi(G) = M(G) \). Since the number of vertices is no more than 7, \( M(G) = Z(G) = 2 \) and thus \( \xi(G) = 2 \).

**Corollary 2.10.** Let \( G \) be any graph with diameter 2 and \( \Delta(G) \leq 3 \). Then \( Z_{SAP}(G) = 0 \). In particular, when \( G \) is the Petersen graph, \( Z_{SAP}(G) = 0 \), so \( \xi(G) = M(G) = 5 \).

**Proof.** For every white non-edge \{j,k\}, there is at least one common neighbor \( i \) of \( j \) and \( k \), since the diameter is 2. By the assumption, \( \deg_G(i) \leq 3 \). Since \( i \) has at least two neighbors, \( \deg_G(i) \geq 2 \). If \( \deg_G(i) = 2 \), then \((k : i \rightarrow j)\). Suppose \( \deg_G(i) = 3 \). On the set \( N_G(i) \), the white non-edges can form \( P_2 \), \( P_3 \), or \( C_3 \). In the case of \( P_2 \) and \( P_3 \), one of \( j \) and \( k \) must be the endpoint of the path, say \( k \), so \((k : i \rightarrow j)\). If it is \( C_3 \), then apply the odd cycle rule \((i \rightarrow C)\). Since this argument works for every white non-edge, every non-edge can be colored blue. Hence \( Z_{SAP}(G) = 0 \).

Let \( G \) be the Petersen graph. Then \( G \) is a 3-regular graph with diameter 2. Thus, \( Z_{SAP}(G) = 0 \), and \( \xi(G) = M(G) \) by Theorem 2.6. It is known that \( M(G) = 5 \).
In [5], it is asked if \( \xi(G) \leq \xi(G - v) + 1 \) for every graphs \( G \) and every vertex \( v \) of \( G \). Theorem 2.6 answers this question in positive for a large number of graph-vertex pairs.

**Corollary 2.11.** Let \( G \) be a graph and \( v \in V(G) \). Suppose \( Z_{SAP}(G - v) = 0 \). Then \( \xi(G) \leq \xi(G - v) + 1 \).

**Proof.** Since \( Z_{SAP}(G - v) = 0 \), \( \xi(G - v) = M(G - v) \) by Theorem 2.6. Therefore,

\[
\xi(G) \leq M(G) \leq M(G - v) + 1 = \xi(G - v) + 1,
\]

where the inequality \( M(G) \leq M(G - v) + 1 \) is given in [11]. \( \square \)

**Example 2.12.** Let \( G \) be one of the tetrahedron \( K_4 \), cube \( Q_3 \), octahedron \( G_8 \), dodecahedron \( G_{12} \), or icosahedron \( G_{20} \). Then, \( Z_{SAP}(G) = 0 \). This is trivial for tetrahedron, since it is a complete graph. The complement of an octahedron is three disjoint edges, which is a forest, so \( Z_{SAP}(G) = 0 \). For the other three graphs, pick one vertex \( i \) and look at its neighborhood \( N_G(i) \). The induced subgraph of \( \overline{G} \) on \( N_G(i) \) is either a 3-cycle or a 5-cycle. Thus the odd cycle rule could apply, and every non-edge in \( N_G(i) \) is colored blue. After doing this to every vertex, by picking one vertex and look at its local game, all white non-edge incident to this vertex will be colored blue. Therefore, \( \xi(G) = M(G) \).

It is known [15] that \( M(K_4) = 3 \) and \( M(Q_3) = 4 \). Since the octahedron graph is strongly regular, in [2] it shows \( 4 \leq M(G_8) \); together with the fact \( Z(G_8) \leq 4 \), we know \( M(G_8) = 4 \). For \( G_{12} \) and \( G_{20} \), the zero forcing numbers can be computed through the computer program and both equal to 6, but the maximum nullity is not yet known.

**Definition 2.13.** Let \( G \) be a graph with some non-edges \( B_E \) colored blue. The color change rule for \( Z_{SAP}^+ \) (CCR-\( Z_{SAP}^+ \)) is the following:

- Let \( \{j, k\} \) be a non-edge. If \( i \to j \) in \( \phi_{Z_{SAP}^+}(G, B_E, k) \) for some vertex \( i \), then the non-edge \( \{j, k\} \) is changed to blue. This is denoted as \( (k : i \to j) \).

- The odd cycle rule can be used to perform a force.

Similarly, the color change rule of \( Z_{SAP}^\ell \) (CCR-\( Z_{SAP}^\ell \)) is defined through the local game \( \phi_{Z_{SAP}^\ell}(G, B_E, i) \). As usual, \( Z_{SAP}^\ell(G) \) (respectively, \( Z_{SAP}^\ell \)) is the minimum number of blue non-edges such that every non-edge will become blue by repeated applications of CCR-\( Z_{SAP}^+ \) (respectively, CCR-\( Z_{SAP}^\ell \)).

**Observation 2.14.** For any graph \( G \), \( Z_{SAP}^+(G) \leq Z_{SAP}^\ell(G) \leq Z_{SAP}(G) \).

By a proof analogous to that of Theorem 2.6, we can establish Theorem 2.15. Observe that \( Z_{SAP}^+(G) = 0 \) implies \( Z_{SAP}(G) = 0 \).

**Theorem 2.15.** Let \( G \) be a graph. If \( Z_{SAP}^+(G) = 0 \), then every matrix in \( S_I(G) \) has the SAP. If \( Z_{SAP}(G) = 0 \), then every matrix in \( S_I(G) \) has the SAP. Therefore, if \( Z_{SAP}^+(G) = 0 \), then \( M_\nu(G) = \nu(G) \).
Corollary 2.16. Suppose $G$ is a graph with $Z^+_{SAP}(G) = 0$. Then $\xi(G) \geq M_*(G)$.

Example 2.17. Let $G = K_{n_1,n_2,...,n_p}$ be a complete multi-partite graph with $n_1 \geq n_2 \geq \cdots \geq n_p$ and $p \geq 2$. Denote $n = \sum_{i=1}^{p} n_i$. Then $Z^+_{SAP}(G) = Z^+_{SAP}(G) = 0$, so $\nu(G) = M_*(G) = n - n_1$ \cite{12}. On the other hand, if $n_1 \geq 4$, then $Z^+_{SAP}(G) > 0$, since none of the non-edges in this part can be colored.

Example 2.18. If $T$ is a tree, then $Z^+_{SAP}(T) = 0$. However, not every tree $T$ has $Z^+_{SAP}(T) = 0$. For example, let $G$ be the graph obtained from $K_{1,4}$ by attaching four leaves to the four existing leaves. In this graph, only the non-edges incident to the center vertex can be colored by CCR-$Z^+_{SAP}$, so $Z^+_{SAP}(G) > 0$.

2.1 Graph join

Since the SAP zero forcing process uses a propagation on non-edges, it is interesting to consider $Z_{SAP}(G)$ if $\mathcal{G}$ has two or more components; that is, $G$ is a join of two or more graphs.

Proposition 2.19. Let $G$ and $H$ be two graphs. Then

$$Z_{SAP}(G \vee H) = Z_{SAP}(G \vee K_1) + Z_{SAP}(H \vee K_1).$$

Proof. Let $v$ be the vertex corresponding to the $K_1$ in $G \vee K_1$. Denote $E_1 = E(G)$ and $E_2 = E(H)$. Consider the mapping $\pi : V(G \vee H) \to V(G \vee K_1)$ such that $\pi(i) = i$ if $i \in V(G)$ and $\pi(i) = v$ if $i \in V(H)$. Fix a vertex $u \in V(H)$, consider the mapping $\pi^{-1} : V(G \vee K_1) \to V(G \vee H)$ such that $\pi^{-1}(i) = i$ if $i \in V(G)$ and $\pi^{-1}(v) = u$.

Suppose at some stage $B_E$ is the set of blue non-edges in $G \vee H$, and $B_E \cap E_1$ and $B_E \cap E_2$ are the sets of blue non-edges in $G \vee K_1$ and $H \vee K_1$ respectively. Let $e = \{j,k\} \in E_1$. If $(k : i \to j)$ happens in $G \vee H$, then $(k : \pi(i) \to j)$ can be applied in $G \vee K_1$; if $(k : i \to j)$ happens in $G \vee K_1$, then $(k : \pi^{-1}(i) \to j)$ can be applied in $G \vee H$. Also, if $e$ is in some cycle $C$ and $(i \to C)$ happens in either $G \vee H$ or $G \vee K_1$, then by the definition of the odd cycle rule $C$ must totally fall in $V(G)$. If $(i \to C)$ in $G \vee H$, then $(\pi(i) \to C)$ in $G \vee K_1$; if $(i \to C)$ in $G \vee K_1$, then $(\pi^{-1}(i) \to C)$ in $G \vee H$. Similarly, all these correspondences work when $e \in E_2$.

Therefore, we can conclude that $B_E$ is a ZFS-$Z_{SAP}$ in $G \vee H$ if and only if $B_E \cap E_1$ and $B_E \cap E_2$ are ZFS-$Z_{SAP}$ in $G \vee K_1$ and $H \vee K_1$ respectively. □

Example 2.20. The value of $Z_{SAP}(G \vee K_1)$ and the value of $Z_{SAP}(G)$ can vary a lot. For example, when $G = K_n$, we will show that $Z_{SAP}(K_n) = \binom{n}{2}$ and $Z_{SAP}(K_n \vee K_1) = Z_{SAP}(K_{1,n}) = \binom{n-1}{2} - 1$ when $n \geq 3$.

Since there are no edges in $K_n$, no vertex can make a force in any local game. This means $Z_{SAP}(K_n) = \binom{n}{2}$.

For $K_{1,n}$, color some edges $B_E$ of $K_{1,n}$ blue so that the set of white non-edges forms a 3-cycle with $n-3$ leaves attaching to a vertex of the 3-cycle. Then
\(B_E\) is a ZFS-\(Z_{SAP}\) for \(K_{1,n}\), since the \(n-3\) leaves can be colored by forcing triples, and then the 3-cycle can be colored by the odd cycle rule. Therefore, \(Z_{SAP}(K_{1,n}) \leq \binom{n-1}{2} - 1\).

Conversely, suppose \(B_E\) is a ZFS-\(Z_{SAP}\) of \(K_{1,n}\) with \(|B_E| = \binom{n-1}{2} - 2\). Let \(\overline{G}_W\) be the graph whose edges are the white non-edges. Then \(|E(\overline{G}_W)| = n + 1\). Obtain a subgraph \(H\) of \(\overline{G}_W\) by deleting leaves and isolated vertices repeatedly until there is no leaf left. Thus \(H\) has minimum degree at least two. Since deleting a leaf removes an edge and a vertex, \(|V(H)| - 1 \leq |E(H)|\). This means \(H\) must contain a component that is not a cycle (so in particular not an odd cycle). Since this component has minimum degree at least two, none of its edge can be colored, a contradiction. Hence \(Z_{SAP}(K_{1,n}) = \binom{n-1}{2} - 1\).

**Proposition 2.22.** For any graph \(G\), \(Z_{SAP}(G \lor K_1) \leq Z_{SAP}(G)\). If \(G\) contains no isolated vertices, then \(Z_{SAP}(G \lor K_1) = Z_{SAP}(G)\).

**Proof.** Every ZFS-\(Z_{SAP}\) for \(G\) is a ZFS-\(Z_{SAP}\) for \(G \lor K_1\), so \(Z_{SAP}(G \lor K_1) \leq Z_{SAP}(G)\).

Now consider the case that \(G\) has no isolated vertices. Suppose at some stage \(B_E\) is the set of blue non-edges for both \(G \lor K_1\) and \(G\). We claim that if a non-edge \((j,k) \in E(G)\) is colored in \(G \lor K_1\), then it can also be colored in \(G\).

Label the vertex in \(V(K_1)\) as \(v\). If \((k : i \rightarrow j)\) in \(G \lor K_1\) with \(i \neq v\), then it is also a forcing triple in \(G\). Suppose \((k : v \rightarrow j)\) happens in \(G \lor K_1\). Then it must be the case when \(j\) is the only white vertex in \(\phi_2(G \lor K_1, B_E, k)\), since \(v\) is a vertex that is adjacent to every vertex and it cannot make a force unless every vertex except \(j\) is already blue. Since \(j\) is not an isolated vertex, it has a neighbor \(i' \neq j\) in \(V(G)\). Now \((k : i' \rightarrow j)\) can make \((j,k)\) blue. Therefore, \(Z_{SAP}(G \lor K_1) = Z_{SAP}(G)\).

**Proposition 2.22.** Let \(G\) be a graph. Then \(Z_{SAP}(G \lor K_1) = 0\) if and only if one of following holds:

- \(G\) has no isolated vertices and \(Z_{SAP}(G) = 0\).
- \(G = K_1\) or \(G\) is a disjoint union of a connected graph \(H\) and an isolated vertex such that \(Z_{SAP}(H) = 0\).
- \(G = \overline{K_n}\).

**Proof.** Let \(v\) be the vertex in \(V(K_1) \subseteq V(G \lor K_1)\). In the case that \(G\) has no isolated vertices, \(Z_{SAP}(G \lor K_1) = 0\) if and only if \(Z_{SAP}(G) = 0\) by Proposition 2.21. If \(G = K_1\), then \(Z_{SAP}(K_2) = 0\). If \(G = \overline{K_n}\), then \(Z_{SAP}(K_{1,3}) = 0\). Finally, suppose \(G\) is a disjoint union of a connected graph \(H\) and an isolated vertex \(w\) such that \(Z_{SAP}(H) = 0\). Then every forcing triple in \(H\) can work in \(G \lor K_1\) to make all non-edges in \(H\) blue. After that, \((k : v \rightarrow w)\) takes action in \(G \lor K_1\) for every \(k \in V(H)\). Thus, every non-edge in \(G \lor K_1\) is blue.

For the converse statement, suppose \(Z_{SAP}(G \lor K_1) = 0\) and no initial blue non-edge is given for \(G \lor K_1\). Suppose \(G\) has \(p\) components with vertex sets
Call a non-edge with two endpoints in different components in $G$ as a crossing non-edge. We claim that if $p \geq 3$, then no crossing non-edge can turn blue in $G \vee K_1$ by any forcing triples. Let $\{j, k\}$ be a crossing non-edge. Without loss of generality, let $k \in V_1$ and $j \in V_2$. Suppose at some stage $B_E$ is the set of blue non-edges and none of the crossing non-edges is blue. In the local game $\phi_Z(G \vee K_1, B_E, k)$, all blue vertices are contained in $V_1 \cup \{v\}$, since all the crossing non-edges are white. If $(k : i \to j)$ happens in $G \vee K_1$, it must be the case that $i = v$, since $v$ is the only blue neighbor of $j$ in $\phi_Z(G \vee K_1, B_E, k)$. Pick a vertex $u \in V_3$. Since both $j$ and $u$ are white neighbors of $v$ in $\phi_Z(G \vee K_1, B_E, k)$, it is impossible that $(k : i \to j)$ is a forcing triple. In conclusion, if $Z_{\text{SAP}}(G \vee K_1) = 0$ and $G$ contains at least three components, the odd cycle rule must be applied to the crossing non-edges. Therefore, $G$ must be $K_3$ in this case.

If $G$ has only one component, then $G$ contains no isolated vertices, unless $G = K_1$. Otherwise assume $G$ has an isolated vertex and has exactly two components. Then $G$ must be a disjoint union of a connected graph $H$ and an isolated vertex $w$. Now we build a sequences of forces for $H$ according to the forces in $G \vee K_1$. Suppose $(k : i \to j)$ happens in $G \vee K_1$ with $j, k \in V(H)$. If $i \in V(H)$, then $(k : i \to j)$ also works in $H$. If $i \notin V(H)$, then it must be $(k : v \to j)$. But $v$ is adjacent to every vertex, so in $\phi_Z(G, B_E, k)$ every vertex except $j$ must be blue. Since $H$ is connected, there must be a vertex $i'$ that is adjacent to $j$. Thus, $(k : i' \to j)$ can make $\{j, k\}$ blue. Therefore, if $Z_{\text{SAP}}(G \vee K_1) = 0$, then $Z_{\text{SAP}}(H) = 0$. \hfill \Box

2.2 Computational results for small graphs

Table 1 shows the proportions of graphs that have certain parameters equal to 0, over all connected graphs with a fixed number of vertices. Graphs are not labeled and isomorphic graphs are considered as the same. The computation is done by Sage and the code can be found in [19].

| $n$ | $Z_{\text{SAP}} = 0$ | $Z_{\text{SAP}}^e = 0$ | $Z_{\text{SAP}}^z = 0$ |
|-----|---------------------|---------------------|---------------------|
| 1   | 1.0                 | 1.0                 | 1.0                 |
| 2   | 1.0                 | 1.0                 | 1.0                 |
| 3   | 1.0                 | 1.0                 | 1.0                 |
| 4   | 1.0                 | 1.0                 | 1.0                 |
| 5   | 0.86                | 0.95                | 0.95                |
| 6   | 0.79                | 0.92                | 0.92                |
| 7   | 0.74                | 0.89                | 0.89                |
| 8   | 0.73                | 0.88                | 0.88                |
| 9   | 0.76                | 0.89                | 0.89                |
| 10  | 0.79                | 0.90                | 0.91                |

Table 1: The proportion of graphs satisfies $\zeta(G) = 0$ over all connected graphs on $n$ vertices.
In Section 4 we apply these results to help compute the value of $\xi(G)$ when $|G| \leq 7$.

3 A vertex cover version of the SAP zero forcing game

As Example 2.20 points out, for a connected graph $G$ on $n$ vertices, the value of $Z_{SAP}(G)$ can be much higher than $n$. This section considers a vertex cover version of the SAP zero forcing game. That is, if $B$ is a set of vertices, then consider the complementary closure $\overline{c}(B)$ as all those non-edges that are incident to any vertex in $B$. Now instead of picking some non-edges as blue at the beginning, we pick a set of vertices $B$, and color the set $\overline{c}(B)$ blue initially.

Following this idea, a new parameter $Z_{vc}(G)$ is defined with $0 \leq Z_{vc}(G) \leq n$, and Theorem 3.2 shows that $M(G) - Z_{vc}(G) \leq \xi(G)$.

**Definition 3.1.** For a graph $G$, the parameter $Z_{vc}(G)$ is the minimum number of vertices $B$ such that by coloring $\overline{c}(B)$ blue, every non-edge will become blue by repeated applications of CCR-$Z_{SAP}$ with the restriction

- $(k : i \rightarrow j)$ cannot perform a force if $i \in B$ and $\{i, k\} \in E(G)$.

A set $B \subseteq V(G)$ with this property is called a $Z_{vc}$ zero forcing set.

**Theorem 3.2.** Let $G$ be a graph. Then

$$M(G) - Z_{vc}(G) \leq \xi(G).$$

**Proof.** For given $G$ and $A = [a_{i,j}] \in S(G)$, let $d = Z_{vc}(G)$ and $\overline{m} = |E(G)|$.

Pick an order for the set of non-edges, and let $\Psi$ be the SAP matrix for $A$ with respect to the given order. Let $B$ be a ZFS-$Z_{vc}$ with $|B| = d$. We will show that we can perturb the diagonal entries of $A$ corresponding to $B$ such that the new matrix has the SAP.

Denote $W = E(G) - \overline{c}(B)$ as the initial white non-edges. Since $B$ is a ZFS-$Z_{vc}$, every non-edge in $W$ is forced to blue at some stage. Say at stage $t$, $W_t$ is the set of white non-edges that are forced blue. The set $W_t$ can be one non-edge, or the edges of an odd cycle; thus, $\{W_t\}_t$ forms a partition of $W$, where $s$ is the number of stages it takes to color all non-edges blue. Define $U_t$ as follows:

If $W_t$ is a non-edge colored by the forcing triple $(k : i \rightarrow j)$, then $U_t = \{(i, k)\}$; if $W_t$ is a cycle colored by an odd cycle rule $(i \rightarrow C)$, then $U_t = \{(i, v)\}_{v \in V(C)}$.

Let $U = \bigcup_{t=1}^{s} U_t$.

We first show that $\Psi[U, W]$ is nonsingular. The proof of Theorem 2.6 shows that if $W_{t_0}$ is given by the odd cycle rule for some step $t_0$, then $\Psi[U_{t_0}, W_{t_0}]$ is nonsingular and $\Psi[U_{t_0}, \bigcup_{t=t_0+1}^{s} W_t] = O$. We will see that the same property is also true when $W_{t_0}$ a single non-edge. Suppose at stage $t_0$, the set of blue non-edges is $B_E$ and $(k : i \rightarrow j)$ applies. Thus, $U_{t_0} = \{(i, k)\}$ and $W_{t_0} = \{(j, k)\}$.

By Definition 1.1

$$\Psi[U_{t_0}, W_{t_0}] = [\Psi_{(i,k),(j,k)}] = [a_{i,j}],$$

15
which is nonsingular, since \( \{i,j\} \) is an edge. For any white non-edge \( e \) that is not incident to \( k \), \( \Psi_{(i,k),e} = 0 \). If \( e = \{j',k\} \) is a white non-edge for some \( j' \neq j \), then \( j' \) is not a neighbor of \( i \), for otherwise \( i \) has two white neighbors in \( \phi_Z(G, B_{Z}, k) \); therefore, \( \Psi_{(i,k),e} = a_{i,j'} = 0 \). By column/row permutations according to \( \{W_i\}_{j=1}^{d} \) and \( \{U_z\}_{i=1}^{d} \) respectively, the \( \Psi[U, W] \) becomes a lower triangular block matrix, with every diagonal block nonsingular. Hence \( \Psi[U, W] \) is nonsingular.

Now give the non-edges in \( \overline{c}(B) \) an order. Following the order, for each non-edge \( \{i,j\} \) in \( \overline{c}(B) \), put either \( (i,j) \) or \( (j,i) \) into another ordered set \( U_{B} \). Since \( \Psi_{(i,j),\{i,j\}} = a_{i,j} \), the diagonal entries of \( \Psi[U_{B}, \overline{c}(B)] \) are controlled by \( a_{i,j} \) for some \( i \in B \).

Consider the matrix
\[
\Psi[U \cup U_{B}, W \cup \overline{c}(B)] = \begin{bmatrix} \Psi[U, W] & \Psi[U, \overline{c}(B)] \\ \Psi[U_{B}, W] & \Psi[U_{B}, \overline{c}(B)] \end{bmatrix}.
\]
We claim that those entry \( a_{i,j} \) with \( i \in B \) only appear on the diagonal of \( \Psi[U_{B}, \overline{c}(B)] \). For each \( i \in B \), the only possible occurrence of \( a_{i,i} \) is in the case \( \Psi(i,k),i,k) = a_{i,i} \) for some vertex \( k \) and non-edge \( \{i,k\} \in E(G) \). Suppose \( i \in B \) and \( \{i,k\} \in E(\overline{c}(B)) \). Then \( \{i,k\} \notin \overline{c}(B) \). Therefore, \( \Psi[U, W] \) and \( \Psi[U_{B}W] \) does not have this type of \( a_{i,i} \) with \( i \in B \) involved. Now it is enough to show \( \{i,k\} \notin U \). Recall that \( U = \cup_{i=1}^{d} U_i \). At stage \( t \), if a forcing triple is applied, then \( \{i,k\} \notin U_t \) since \( \{k:i \rightarrow j\} \) is forbidden for any \( j \) by the definition; if the odd cycle rule is applied, then \( \{i,k\} \notin U_t \) since \( \{i,k\} \in E(\overline{c}(B)) \). Therefore, \( \Psi[U, \overline{c}(B)] \) contains no such \( a_{i,i} \) with \( i \in B \), either.

Let \( D_{B} \) be the diagonal matrix indexed by \( V(G) \) with the \( i,i \)-entry 1 if \( i \in B \) and 0 otherwise. Consider the matrix \( A + xD_{B} \). By the discussion above, the SAP matrix of \( A + xD_{B} \) is
\[
\Psi[U \cup U_{B}, W \cup \overline{c}(B)] = \begin{bmatrix} \Psi[U, W] & \Psi[U, \overline{c}(B)] \\ \Psi[U_{B}, W] & \Psi[U_{B}, \overline{c}(B)] + xI \end{bmatrix}.
\]
Since \( \Psi[U, W] \) is nonsingular, \( \Psi[U \cup U_{B}, W \cup \overline{c}(B)] \) is nonsingular when \( x \) is large enough. This means, by changing \( d = |B| \) diagonal entries of \( A \), the corresponding SAP matrix becomes full-rank. Therefore,
\[
M(G) - Z_{\text{vc}}(G) \preceq \text{null}(A + xD_{B}) \preceq \xi(G).
\]
\( \Box \)

**Remark 3.3.** Theorem [3.2] actually proves that if \( B \) is a ZFS-\( Z_{\text{vc}} \), then every matrix \( A \in \mathcal{S}(G) \) attains the SAP by perturbing those diagonal entries corresponding to \( B \).

In classical graph theory, a vertex cover of a graph \( G \) is a set of vertices \( S \) such that every edge in \( G \) is incident to some vertex in \( S \); that is, \( G - S \) contains no edges. The **vertex cover number** \( \beta(G) \) is defined as the minimum cardinality of a vertex cover in the graph \( G \). Corollary [3.4] below shows the relation between \( M(G) \), \( \xi(G) \), and \( \beta(G) \).
Corollary 3.4. Let $G$ be a graph. Then

$$M(G) - \beta(G) \leq \xi(G).$$

Proof. Let $S$ be a vertex cover of $G$. Then $S$ is a ZFS-$Z_{vc}$, since every non-edge is blue initially. Therefore, $Z_{vc}(G) \leq \beta(G)$ and the desired inequality comes from Theorem 3.2. \qed

Example 3.5. Let $G = K_3 \vee K_4$. Then from data in [9], $M(G) = Z(G) = 5$. Since $G$ is a subgraph of $K_3 \vee P_4$, by minor monotonicity $\xi(G) \leq \xi(K_3 \vee P_4) \leq Z(K_3 \vee P_4) \leq 4$. On the other hand, by picking one of the vertex in $V(K_4)$, it forms a ZFS-$Z_{vc}$, since the initial white non-edges form a 3-cycle and the odd cycle rule applies. Thus $Z_{vc}(G) = 1$ and $\xi(G) \geq M(G) - Z_{vc}(G) = 4$. Therefore, $\xi(G) = 4$.

Notice that $G$ contains a $K_4$ minor but not a $K_5$ minor, so we can only say $\xi(G) \geq \xi(K_4) = 3$ by considering $K_p$ minors.

Similarly, we can define $Z_{\ell vc}(G)$ by changing CCR-$Z_{SAP}$ to CCR-$Z_{\ell SAP}$. Then we have Theorem 3.6.

Theorem 3.6. Let $G$ be a graph. Then

$$M_\ell(G) - Z_{\ell vc}(G) \leq \nu(G).$$

Remark 3.7. The proof of Theorem 3.2 relies on the fact $\Psi[U,W]$ is a lower triangular block matrix. This is not always true for $Z_\ell$. As a vertex can force two or more white vertices under CCR-$Z$, the sets $\{U_t\}_{t=1}^n$ might not be mutually disjoint and it is possible that $|U| < |W|$. Therefore, the same proof does not work for $Z_\ell$.

4 Values of $\xi(G)$ for small graphs

Analogous to $M(G) \leq Z(G)$, it is shown in [4] that $\xi(G) \leq [Z](G)$, where $[Z](G)$ is defined through a (conventional) zero forcing game with CCR-$Z$:

- CCR-$Z$ can be used to perform a force. Or if $i$ is blue, $i$ has no white neighbors, and $i$ was not used to make a force yet, then $i$ can pick one white vertex $j$ and force it blue.

By using Sage and with the help of Theorem 2.6 and Theorem 3.2 we will see that $[Z]$ agrees with $\xi(G)$ for graphs up to 7 vertices. This result also relies on some other lower bounds. The Hadwiger number $\eta(G)$ is defined as the largest $p$ such that $G$ has a $K_p$ minor. Since $\xi(G)$ is minor monotone, it is known [4] that when $\eta(G) = p$

$$\xi(G) \geq \xi(K_p) = p - 1 = \eta(G) - 1.$$
Lemma 4.1. Let $G$ be a connected graph with at most 7 vertices. Then at least one of the following is true:

- $Z_{SAP}(G) = 0$, which implies $\xi(G) = M(G)$.
- $G$ is a tree, which implies $\xi(G) = 2$ if $G$ is not a path, and $\xi(G) = 1$ otherwise.
- $[Z](G) = M(G) - Z_{vc}(G)$, which implies $\xi(G) = [Z](G)$.
- $[Z](G) = \eta(G) - 1$, which implies $\xi(G) = [Z](G)$.
- $[Z](G) = 3$ and $G$ contains a $T_3$-family minor, which implies $\xi(G) = 3$.

Proof. By running a Sage program [19], one of the five cases will happen. If $Z_{SAP}(G) = 0$, then $\xi(G) = M(G)$ by Theorem 2.6. If $G$ is a tree, then $\xi(G) \leq 2$, and the equality holds only when $G$ is not a path [5]. Both $M(G) - Z_{vc}(G)$ and $\eta(G) - 1$ are lower bounds of $\xi(G)$ by Theorem 3.2 and [4]. When one of the lower bounds meets with the upper bound $[Z](G)$, $\xi(G) = [Z](G)$. Finally, if $G$ has a $T_3$-family minor, then $\xi(G) \geq 3$ [14]. In this case, $\xi(G) = 3$ when $[Z](G) = 3$.

While $\xi(T) \leq 2$ for all tree $T$, the value of $[Z](T)$ can be more than two. Example A.11. of [4] gives a tree $T$ with $[Z](T) = 3$; the graph $T$ is shown in Figure 3. However, $\xi(G) = [Z](G)$ is still true when $G$ is a tree and $|G| \leq 7$.

![Figure 3: An example of tree $T$ with $[Z](T) > 3.$](image)

Lemma 4.2. Let $G$ be a tree with at most 7 vertices. Then $\xi(G) = [Z](G)$.

Proof. When $G$ is a tree, it is known [5] that $\xi(G) = 2$ when $G$ is not a path, and $\xi(G) = 1$ if $G$ is a path. When $G$ is a path, then $\xi(G) = 1 = [Z](G)$. Assume $G$ is not a path. It is enough to show $[Z](G) \leq 2$. In this case, $G$ must have a vertex $v$ of degree at least 3. Call this type of vertex a high-degree vertex. If $G$ has only one high degree vertex, then $[Z](G) \leq 2$ since any two leaves form a ZFS-[Z]. Since $|G| \leq 7$, there are at most two high-degree vertices. Pick two leaves such that the unique path between them contains only one high-degree vertex, then these two leaves form a ZFS-[Z].
Theorem 4.3. Let \( G \) be a graph with at most 7 vertices. Then \( \xi(G) = |Z(G)| \).

Proof. Let \( G \) be a graph with at most 7 vertices. Then \( M(G) = Z(G) \) [9]. If \( Z_{\text{SAP}}(G) = 0 \), then \( \xi(G) = M(G) = Z(G) \). Since \( \xi(G) \leq |Z|(G) \leq Z(G) \), \( \xi(G) = |Z|(G) \). If \( G \) is a tree, then \( |Z|(G) = \xi(G) \) by Lemma 4.2. Then by Lemma 4.1, \( \xi(G) = |Z|(G) \) for all connected graph \( G \) up to 7 vertices. It is known that \( \xi(G_1 \cup G_2) = \max \{ \xi(G_1), \xi(G_2) \} \) [5] and \( |Z|(G_1 \cup G_2) = \max \{ |Z|(G_1), |Z|(G_2) \} \) [4], so \( \xi(G) = |Z|(G) \) for any graph up to 7 vertices. \( \square \)

![Graph G](image)

Figure 4: A graph \( G \) on 8 vertices with \( \xi(G) = 2 \) but \( |Z|(G) = 3 \).

Example 4.4. Let \( G \) be the graph shown in Figure 4. It is known [16] that \( M(G) = 2 \). Since \( G \) is not a disjoint union of paths, \( \xi(G) = 2 \). Also, it can be computed that \( Z(G) = |Z|(G) = 3 \).

5 Acknowledgments

The author thanks Leslie Hogben and Steve Butler for their suggestions.

References

[1] M. Arav, F. J. Hall, Z. Li, and H. van der Holst. The inertia set of a signed graph. Linear Algebra Appl., 439:1506–1529, 2013.

[2] AIM Minimum Rank – Special Graphs Work Group (F. Barioli, W. Barrett, S. Butler, S. M. Cioabă, D. Cvetković, S. M. Fallat, C. Godsil, W. Haemers, L. Hogben, R. Mikkelson, S. Narayan, O. Pryporova, I. Sciriha, W. So, D. Stevanović, H. van der Holst, K. Vander Meulen, and A. Wangsness). Zero forcing sets and the minimum rank of graphs. Linear Algebra Appl., 428:1628–1648, 2008.
[3] F. Barioli, W. Barrett, S. M. Fallat, H. T. Hall, L. Hogben, B. Shader, P. van den Driessche, and H. van der Holst. Zero forcing parameters and minimum rank problems. *Linear Algebra Appl.*, 433:401–411, 2010.

[4] F. Barioli, W. Barrett, S. M. Fallat, H. T. Hall, L. Hogben, B. Shader, P. van den Driessche, and H. van der Holst. Parameters related to tree-width, zero forcing, and maximum nullity of a graph. *J. Graph Theory*, 72:146–177, 2013.

[5] F. Barioli, S. M. Fallat, and L. Hogben. A variant on the graph parameters of Colin de Verdière: Implications to the minimum rank of graphs. *Electron. J. Linear Algebra*, 13:387–404, 2005.

[6] W. Barrett, H. T. Hall, and R. Loewy. The inverse inertia problem for graphs: Cut vertices, trees, and a counterexample. *Linear Algebra Appl.*, 431:1147–1191, 2009.

[7] Y. Colin de Verdière. On a new graph invariant and a criterion for planarity. In *Graph Structure Theory*, pp. 137–147, American Mathematical Society, Providence, RI, 1993.

[8] Y. Colin de Verdière. Multiplicities of eigenvalues and tree-width graphs. *J. Combin. Theory Ser. B*, 74:121–146, 1998.

[9] L. DeLoss, J. Grout, L. Hogben, T. McKay, J. Smith, and G. Tims. Techniques for determining the minimum rank of a small graph. *Linear Algebra Appl.*, 432:2995–3001, 2010.

[10] R. Diestel. *Graph Theory*. Springer-Verlag, Heidelberg, 4th edition, 2010. Electronic edition, 2012.

[11] C. J. Edholm, L. Hogben, M. Huynh, J. LaGrange, and D. D. Row. Vertex and edge spread of zero forcing number, maximum nullity, and minimum rank of a graph. *Linear Algebra Appl.*, 436:4352–4372, 2012.

[12] S. M. Fallat and L. Hogben. Minimum rank, maximum nullity, and zero forcing number of graphs. In *Handbook of Linear Algebra*, 2nd edition, L. Hogben editor, CRC Press, Boca Raton, 2013.

[13] L. Hogben. Minimum rank problems. *Linear Algebra Appl.*, 432:1961–1974, 2010.

[14] L. Hogben and H. van der Holst. Forbidden minors for the class of graphs $G$ with $\xi(G) \leq 2$. *Linear Algebra Appl.*, 423:42–52, 2007.

[15] L.-H. Huang, G. J. Chang, and H.-G. Yeh. On minimum rank and zero forcing sets of a graph. *Linear Algebra Appl.*, 432:2961–2973, 2010.

[16] C. R. Johnson, R. Loewy, and P. A. Smith. The graphs for which the maximum multiplicity of an eigenvalue is two. *Linear Multilinear Algebra*, 57:713–736, 2009.
[17] A. Kotlov, L. Lovász, and S. Vempala. The Colin de Verdière number and sphere representations of a graph. *Combinatorica*, 17:483–521, 1997.

[18] J. C.-H. Lin. Odd cycle zero forcing parameters and the minimum rank of graph blowups. To appear in *Electron. J. Linear Algebra*.

[19] J. C.-H. Lin. *Sage* code for $Z_{\text{SAP}}$ related parameters. Published on the Iowa State *Sage* server at [https://sage.math.iastate.edu/home/pub/54/](https://sage.math.iastate.edu/home/pub/54/). Sage worksheet available at [https://github.com/jephianlin/publish/raw/master/VariationsOfZsap.sws](https://github.com/jephianlin/publish/raw/master/VariationsOfZsap.sws)