Lateral Boundary of Cirrus Cloud from CALIPSO Observations

Yunfei Fu¹, Yilun Chen¹, Rui Li¹, Fang Qin¹, Tao Xian¹, Lu Yu¹, Aoqi Zhang¹, Guosheng Liu² & Xiangdong Zhang³

Due to the thinness and small scale of cirrus clouds, its lateral boundary may be missed by conventional passive remote-sensing techniques and climate models. Here, using satellite observations in June–August from 2006 to 2011, a global dataset for the cirrus cloud lateral boundary (CCLB) was established. The results indicate that the optical properties, such as the lidar backscatter, the depolarization ratio and the optical depth, sharply decrease from cloudy regions to clear-sky regions. There are significant regional differences in optical properties and height and thickness of the CCLB. Based on a quantitative estimation, the strongest longwave warming effects (>0.3 W m⁻²) are found near the Equator and over tropical continents. The global average longwave warming effect of the CCLB is at least 0.07 W m⁻², which is much larger than some of the radiative forcings considered in the Intergovernmental Panel on Climate Change (IPCC) reports. Specifically, the CCLB in traditional “clear-sky” region may be totally missed by current models and IPCC reports, which contributes 28.25% (~0.02 W m⁻²) of the whole CCLB radiative effect, twice greater than contrail effect. It is recommended that the CCLB effect should be taken account in future climate models and the next IPCC reports.

Cirrus clouds regularly cover approximately 20% of the globe, providing significant radiative forcing (RF) on the Earth climate system¹⁻³. It varies in altitude from a maximum cloud top of 17.6 km to a minimum cloud base of 6 km with an equivalent range in temperature from −82 to −7 °C, respectively⁴, and plays an important role in regulating the water vapor concentration in the upper troposphere and lower stratosphere⁵.

Cirrus clouds reflect shortwave solar radiation and absorb outgoing longwave radiation, and act as a thermostat, shielding Earth’s surface from solar radiation⁶⁻⁸. In most cases, the absorbed longwave radiation outweighs the reflected shortwave radiation⁸ and thus cirrus clouds have a net warming effect on the Earth. It is found that cirrus clouds with an optical depth greater than 0.06 have a significant longwave radiation absorption effect (~10 W m⁻²)⁹. Although there is large uncertainty in RF estimations of clouds, cirrus RF is generally calculated as a positive value; that is, cirrus clouds make both tropospheric and surface temperature increase¹⁰⁻¹².

Satellite passive optical sensors, such as the Moderate Resolution Imaging Spectroradiometer (MODIS), can retrieve cirrus clouds during the daytime¹³,¹⁴, but the retrieval algorithm may misclassify up to 40% of thin cirrus clouds with an optical depth less than 0.3 as “clear sky”¹⁵. The CloudSat Cloud Profile Radar (CPR) can observe three-dimensional cloud structures, but still misses many of the thin cirrus clouds¹⁶. However, due to the high sensitivity and resolution of the Cloud-Aerosol Lidar with Orthogonal Polarization (CALIOP) onboard the Cloud–Aerosol Lidar and Infrared Pathfinder Satellite Observation (CALIPSO) satellite, there is a unique opportunity to comprehensively observe the thin cirrus clouds with range of optical depth from 0.01 to 5¹⁶,¹⁷.

The transition zone between cloud and clear sky is a region of dramatic change in terms of cloud optical properties, aerosol particles and water vapor. Several recent studies using ground-based radar and CALIPSO observations have focused on warm cloud and aerosols near the cloud edge, and found that reflectance, backscatter and optical thickness increase with decreasing distance from cloud¹⁸⁻²¹. The width of the transition zone still has large uncertainties due to different observation and calculation methods. Specifically, the width of the transition zone has been found to extend up to 15 km over ocean²² and up to about 6.4 km over land²³, whereas other studies have found it to be less than 1 km for cumulus cloud²⁴.

¹School of Earth and Space Sciences, University of Science and Technology of China (USTC), Hefei, 230026, P.R. China. ²Department of Earth Ocean & Atmospheric Science, Florida State University, Tallahassee, Florida, 32306, USA. ³International Arctic Research Center and Department of Atmospheric Sciences, University of Alaska Fairbanks, 930 Koyukuk Dr, Fairbanks, Alaska, 99775, USA. Yunfei Fu and Yilun Chen contributed equally to this work. Correspondence and requests for materials should be addressed to Y.F. (email: fyf@ustc.edu.cn) or R.L. (email: rli7@ustc.edu.cn)
To the best of our knowledge, a few global observational studies have explored the relationship between the lateral boundary of cirrus clouds and their optical properties and the consequent RF. Using CALIOP measurements, Li et al. (2014) analyzed the lateral boundary layer of cirrus clouds in the east and south of China and estimated that the corresponding longwave RF is about 10 W m⁻². Based on their conservative estimation, the RF induced by this cirrus cloud lateral boundary (CCLB) is at least 0.0047 W m⁻² globally, which is not taken account in any global atmospheric circulations models, because there is no global model considers the lateral boundary of clouds. However, their RF result was calculated based on the assumption that coverage, width and RF of the CCLB are all fixed values. Furthermore, they assembled all the CCLBs into a “big round plate” to obtain the RF of this “plate”, that is, thousands of CCLBs were assembled into one enormous cloud, which may substantially underestimate the RF of the CCLB. Note that, because of the scan method (nadir-looking) of CALIOP, the transition zone is the wide regions around cirrus boundaries, as opposed to the exact 3D boundaries.

Accurate identification of CCLB can have great impacts on improving estimating global energy budgets and in turn global warming, helping climate model improvements that will reduce biases and uncertainties of climate simulation and projection. In this study, CALIOP data from 2006 to 2011 and an event-based method were used to construct a CCLB database and quantitatively address the following questions. (1) To what extent do the identification criteria affect the results? (2) What is the global distribution of the CCLB and its properties? (3) What contribution does the CCLB make to the Earth’s radiative energy budget?

Methods

The standard CALIPSO-CALIOP Level 1B data and Level 2 vertical feature mask (VFM) data (version 3.01) for June–August from 2006 to 2011 were used to identify the CCLB. Level 1B data provide 532 nm attenuated backscatter profiles (β532) and the depolarization ratio (δ532) at a horizontal resolution of 1 km and a vertical resolution of 60 m at altitudes of 8.3–20.2 km. VFM data provide cloud and aerosol classification at the same resolution as Level 1B data at altitudes of 8.3–20.2 km above mean sea level. Only nighttime data were used in this study as there is lower noise and more reliable cloud detection due to weaker background illumination at nighttime. Though many previous studies have simply used β532, backscatter profiles (β532) were calculated from β532 to reduce the error from two-way attenuation.

It is difficult to quickly search for information on individual CCLB cases in original orbital data because of the large quantity of data. Therefore, it is necessary to eliminate useless data and establish a CCLB dataset. The event-based method first groups “cloud” and “clear sky” pixels, and then identifies the boundary points layer-by-layer to form an individual CCLB case. Specifically, the constraints for identifying the boundary points of each layer were improved from Li et al. (2014) and are listed below:

1. “Cloud” and “clear sky” pixels should be wide enough (contiguous at least 45 km) with high reliability to ensure the location of the boundary from cloud to clear sky.
2. Cloud type should be “cirrus” with “confident” quality.
3. To avoid shifts in boundary locations caused by horizontal averaging, horizontal averaging of “cirrus” should be less than 5 km.
4. The cloud phase should be “ice”. Phase quality of more than 90% pixels should be “high confidence”.
5. β532 in the cloud should be significantly stronger than that in clear sky (minimum β532 in the cloud should be greater than the mean β532 in clear sky plus two standard deviations; clear sky here means the pixels identified as “clear sky” and 15 to 45 km away from the boundary point).

Based on the above criteria, the positions of the boundary points were obtained in each layer and then the proper cloud–clear sky interface cases were identified by the boundary points in continuous vertical layers.

Some atypical CCLB cases may be eliminated by our strict criteria. Possible regional differences in atypical CCLB cases will lead to an inaccurate global RF estimation. Therefore, it is necessary to examine the geographical distribution of the CCLB using different criteria. The above criteria, as the strictest criteria, are defined as criteria A. Criteria B excludes constraint (5); criteria C excludes constraint (5) and only requires phase quality better than or equal to “medium confidence” for constraint (4); criteria D, as the most relaxed criteria, only includes constraint (1) and (2) to guarantee the boundary is from “cirrus cloud” to “clear sky”. Figure 1 shows the geographical distribution of CCLB data points identified by the four criteria groups based on a 5° × 5° latitude × longitude grid. The sample sizes show a ratio of approximately 1:2:2:2.5 among the four groups with nearly the same distribution pattern. Overall, the distribution of CCLB cases is similar to the distribution of cirrus clouds, as revealed by Sassen et al. More CCLB cases are located in the tropical belt than the mid-latitudes as a result of anvils produced by deep convection in the intertropical convergence zone. Typhoons over the western North Pacific enhance the troposphere-to-stratosphere water vapor transport, and will also form injection cirrus. Few CCLB cases appear in northern Africa, southern Indian Ocean and eastern South Pacific, as well as regions with weak precipitation and convection over the Northern Hemisphere summer. As a result, Criteria A was used in this study because of the strict requirements and the small effect on CCLB geographical distribution pattern. Although different criteria for identifying CCLB would lead to different CCLB properties and sample sizes, we believe that the current stage of using criteria A is the most appropriate, because lenient criteria may misidentify the CCLB and produce large uncertainty.

The SBDART (Santa Barbara DISORT Atmospheric Radiative Transfer) model was used to calculate the RF caused by the CCLB. Cloud-top height, cloud-bottom height and optical depth of the CCLB were calculated on a 5° × 5° latitude × longitude grid, and then used as inputs to simulate the RF. As the differences between the CCLB and “clear sky” (RF, calculated by radiation fluxes of the CCLB minus clear-sky radiation fluxes) rather than the radiation fluxes themselves were our main interest, the uncertainties, such as atmospheric profile, should not significantly bias our conclusions.
occurred between 9 and 12 km altitude with a width of 150 km. On the right of the cloud layer, no cloud or aerosols were detected by CALIOP. It can be seen from Fig. 2a that a cloud layer (see Methods) that occurred on 15 August 2007 over the East Pacific. It is apparent from Fig. 2a that a cloud layer is shown in Fig. 2c.

The optical depth (Fig. 3d) ranged from 0.25 to 0.5 with a mean of 0.35 in cloud, which may be partly missed by MODIS and CloudSat CPR.3,16. The optical depth decreases from 0.08 (−45 to −20 km) to 0.02 (−15 to −6 km) in approximately 12 km between the cloudy and clear-sky regions. In addition, perpendicular $\beta_{532}$ (Fig. 3b) shows a clear log-linear decreasing trend in the transition zone, and a similar trend to $\beta_{532}$ in the cloudy region. However, perpendicular $\beta_{532}$ in the clear-sky region is irregular, ranging from $10^{-4}$ to $10^{-6}$ km$^{-1}$ sr$^{-1}$, and a similar magnitude of noise. Therefore, $\beta_{532}$ rather than perpendicular $\beta_{532}$ was used to calculate the CCLB width. Before calculation, the cloud–clear sky interface case was roughly divided into three key regions according to distance to the boundary point: suspected cloudy region (−45 to −15 km), suspected transition zone (−5 to 0 km) and suspected clear sky (15 to 45 km). These typical distances were derived from the statistical analysis (Fig. 4a). On completion of this region segmentation, log($\beta_{532}$) for each distance in the three regions was calculated, followed by linear fitting of log($\beta_{532}$) and distance in the three regions. The intersections of the fitted line in the suspected transition zone with the fitted lines in the cloudy and clear-sky regions determined the CCLB width. The CCLB was then defined as the region between the two intersections, which is illustrated in Fig. 3a. $\delta_{532}$ shows a significant change at the CCLB (from ~0.2 to ~0.05).

The optical depth (Fig. 3d) ranged from 0.25 to 0.5 with a mean of 0.35 in cloud, which may be partly missed by MODIS and CloudSat CPR.3,16. The optical depth decreases from 0.08 (−20 km) to 0.02 (−3 km). In view of the small optical depth and scale.

Data availability. The datasets generated during and/or analysed during the current study are available from the corresponding author on reasonable request.

Results

Case study analysis. Figure 2 shows a prominent cloud–clear sky interface case identified using criteria A (see Methods) that occurred on 15 August 2007 over the East Pacific. It is apparent from Fig. 2a that a cloud layer occurred between 9 and 12 km altitude with a width of 150 km. On the right of the cloud layer, no cloud or aerosols were detected by CALIOP. It can be seen from Fig. 2b that the 532 nm backscatter ($\beta_{532}$) in cloud is greater than that in clear sky, confirming the existence of the cloud. The cloud–clear sky interface identified by criteria A is shown in Fig. 2c.

For the cloud–clear sky interface case in Fig. 2, $\beta_{532}$ and perpendicular $\beta_{532}$ were averaged layer-by-layer, and the depolarization ratio ($\delta_{532}$) was the ratio of perpendicular $\beta_{532}$ to parallel $\beta_{532}$, and the optical depth was calculated by integrating the volume extinction coefficient over the depth of the cloud layer. The results obtained from the preliminary calculation of optical properties are presented in Fig. 3. Interestingly, the distance to the boundary point is a dominant influence on $\beta_{532}$. Figure 3a shows that there is a slight log-linear decrease from −45 to −6 km distance in the cloudy region, whereas $\beta_{532}$ remains steady from 5 to 45 km distance in the clear-sky region. $\beta_{532}$ drops sharply from $4 \times 10^{-5}$ to $4 \times 10^{-6}$ km$^{-1}$ sr$^{-1}$ in approximately 12 km between the cloudy and clear-sky regions. In addition, perpendicular $\beta_{532}$ (Fig. 3b) shows a clear log-linear decreasing trend in the transition zone, and a similar trend to $\beta_{532}$ in the cloudy region. However, perpendicular $\beta_{532}$ in the clear-sky region is irregular, ranging from $10^{-4}$ to $10^{-6}$ km$^{-1}$ sr$^{-1}$, and a similar magnitude of noise. Therefore, $\beta_{532}$ rather than perpendicular $\beta_{532}$ was used to calculate the CCLB width. Before calculation, the cloud–clear sky interface was roughly divided into three key regions according to distance to the boundary point: suspected cloud (−45 to −15 km), suspected transition zone (−5 to 0 km) and suspected clear sky (15 to 45 km). These typical distances were derived from the statistical analysis (Fig. 4a). On completion of this region segmentation, log($\beta_{532}$) for each distance in the three regions was calculated, followed by linear fitting of log($\beta_{532}$) and distance in the three regions. The intersections of the fitted line in the suspected transition zone with the fitted lines in the cloudy and clear-sky regions determined the CCLB width. The CCLB was then defined as the region between the two intersections, which is illustrated in Fig. 3a. $\delta_{532}$ shows a significant change at the CCLB (from −0.2 to −0.05). The optical depth (Fig. 3d) ranged from 0.25 to 0.5 with a mean of 0.35 in cloud, which may be partly missed by MODIS and CloudSat CPR.3,16.

Statistical analysis. Note that the linear fitting algorithm used to identify the boundaries of cloudy, clear, and transition zones in Fig. 3 was also used in the statistical analysis. To analyze the global statistical characteristics of the CCLB optical properties and RF, $\beta_{532}$ and $\delta_{532}$ were averaged case-by-case, and the 75th, 50th and 25th percentiles of average $\beta_{532}$ and $\delta_{532}$ were derived from almost 10$^5$ effective cloud–clear sky interface cases. The percentile method can enhance the robustness compared with the average method. As shown in Fig. 3a, a much smoother distribution is found from cloud to clear sky than for the cloud–clear sky interface case study above. A transition zone is found with a sharp decrease in $\beta_{532}$, which reveals that the lateral boundary is not unique to the case study but is common in almost all cirrus clouds. The 25th to 75th percentile of $\delta_{532}$ ranges from 0.14 to 0.32 in the cloudy region as a result of multiple particle shapes in cirrus clouds, whereas nearly spherical particles appear more in clear sky with $\delta_{532}$ less than 0.05.

Median $\beta_{532}$, cloud height and ambient temperature were used as inputs to derive the optical depth, the ice-water path and effective particle radius using the algorithms developed by Heymsfield et al.3,16. As shown in Fig. 4c, optical depth decreases from 0.08 (−20 km) to 0.02 (−3 km). In view of the small optical depth and scale.
of the CCLB, the associated RF may be missed by Clouds and the Earth’s Radiant Energy System (CERES)\cite{33}. Based on the optical properties mentioned above, the RF from cloud to clear sky was retrieved. Note that only nighttime data were used to identify the CCLB in this study. Consequently, longwave radiation is the key RF used for calculations using the Santa Barbara DISORT Atmospheric Radiative Transfer (SBDART) model. The RF results are shown in Fig. 4d and e. The outgoing RF at the top of the atmosphere in the cloudy region is $-15$ to $-10$ W m$^{-2}$, and the value sharply increases to 0 W m$^{-2}$ through the transition zone. A possible explanation is that this negative outgoing RF (warming) is a result of absorption by cirrus clouds. According to some previous studies, cirrus clouds generally have a heating effect on the top of the atmosphere\cite{34,35}. The trapped radiation then heats the cloud and atmosphere, and only a slight increase in longwave RF (Fig. 4e) is received on the Earth’s surface.

The probability distribution functions (PDFs) for parameters of the CCLB are shown in Fig. 5. The cloud height was calculated by averaging cloud-top height and cloud-bottom height, and cloud thickness was the height difference between the cloud top and cloud bottom. It can be seen from Fig. 5 that more than 50% of cirrus clouds are between 10 and 13 km height. Less than 15% of cirrus clouds are above 14 km, and located at the upper troposphere. Cloud thickness shows an exponential distribution and thin cirrus clouds (cloud thickness less than 0.5 km) dominate by more than 50%. The proportion of CCLB width peaks at 5 to 8 km with more than 7% km$^{-1}$, and then gradually declines to 2% km$^{-1}$ at 20 km. It is possible that the wide variation in the CCLB width results from highly variable environmental conditions. Recently, Li et al. (2014) found a statistically significant correlation between the CCLB width and ambient temperature\cite{22}. However, due to the spatial and temporal mismatch between reanalysis data and satellite observations, there is no general agreement on how these parameters affect the CCLB width. The optical depth in Fig. 5d was calculated by integrating the optical depth over the CCLB, and treating it as a constant to obtain the average optical depth for each CCLB case. For example, the optical depth in the case study (Fig. 2c) is about 0.15. As the CCLB is extremely thin and the optical depth is very small, such an assumption should not bias the findings in this study. More than half of the transition zones have an optical depth less than 0.05. A ground-based study by Kienast-Sjogren et al. (2016) at the Swiss high alpine site Jungfraujoch found that subvisible cirrus ($\tau < 0.03$), thin cirrus ($0.03 < \tau < 0.3$) and opaque cirrus ($\tau > 0.3$) account for 43%,
46% and 11% of cirrus clouds, respectively, which is similar to the magnitude of our findings. Since the light is almost fully extinguished within the thick clouds, their lidars could not specify the optical depth of the thickest cirrus clouds (τ > 3), which is almost the detection limit of CALIOP (τ ≈ 5). In addition, they concentrated on the whole cirrus clouds so that their τ is actually a little greater than our results.

As is shown in Fig. 3a, large part of CCLB occurs within cloudy region detected by CALIOP, and so it seems that this part has been considered in CALIOP-based studies. However, the properties of the CCLB are significantly different from the conventional “cloud” or “clear” pixels (see Figs 3a and Fig. 4). Therefore, it would be better to single out the CCLB as a separate part rather than only roughly divide pixels into “cloud” and “clear”. Then accurately calculating the location of the CCLB and identifying which part of CCLB is inside the conventional “cloud” region would be helpful for the future scene classification. Figure 3e shows the location of left intersection in cloudy region (about −6 km in Fig. 3a). On the cloud side of the cloud–clear sky interface, intersection of CCLB to actual “cloud” is located at about −5 km. ~30% CCLBs are totally located at conventional “cloud” and ~5% CCLBs are totally located at conventional “clear” (Fig. 5f).

Figure 3. Optical properties of the cloud–clear sky interface sample shown in Fig. 1. (a) β_532, (b) perpendicular β_532, (c) δ_532, and (d) τ. Distance zero indicates the boundary point.
Li et al. (2014) found no significant differences in CCLB features among the three specific areas (eastern China, the East China Sea, and the South China Sea) of cirrus clouds in China. However, regional variation would have been much more convincing if the global distributions had been explored. Figure 6 shows the average geographical distributions and latitudinal distribution of cloud height, cloud thickness, width and optical depth.
of the CCLB. Note that, to enhance the robustness of statistical results, only grids with at least 20 samples were used in the calculation. The highest CCLB height occurs in the tropics and subtropics, implying that a high CCLB appears to associate with a higher cloud top height. There are significant regional differences in cloud thickness, width and optical depth. For example, the CCLB cloud thickness is 0.5 to 0.6 km in the tropics and subtropics, but less than 0.45 km in the mid-latitudes in the Southern Hemisphere. This pattern is similar to that in Sassen et al.\textsuperscript{27}, who found that cirrus cloud thickness is greatest in the tropics and decreases toward the poles\textsuperscript{27}. Note that the thickness in our study is thinner than other reports, such as Sassen et al.\textsuperscript{27}, because we only focus on the thickness.
at the lateral boundary rather than the whole cirrus cloud. Optical depths greater than 0.1 occur over East Asia, the Americas and central southern Pacific, which may be due to anvils produced directly by deep convection or southern storm tracks. These results indicate that regional variations in CCLB parameters do exist on a global scale, which leads to regional differences in RF.

Based on the CCLB properties calculated in Fig. 6, the outgoing RF at the top of the atmosphere and the surface downward RF were retrieved grid by grid. However, the calculation suffers from a lack of coverage of the CCLB. Li et al. (2014) assumed that the CCLB width is 6 km, and the global cirrus coverage is 25%. This assumption reduces the computational complexity, but tends to overlook regional differences. To quantify the contribution of the CCLB in the regional radiative energy budget, the RF in each grid was computed using the following equation:

\[
RF = RF_c \times \frac{W \times Num_c}{Num_c \times R^4}
\]
high latitudes, the global RF could be larger than 0.07 W m\(^{-2}\), but for each CCLB); the larger global RF would be estimated than the above result (0.07 W m\(^{-2}\) to the increase of RF. Therefore, if the less strict criteria (such as Criteria B or C) was used to identify the CCLB, the CCLB width, \(W\) is the mean CCLB width, \(Num_c\) is the number of CCLB cases (Fig. 1a), \(Num_v\) is the total number of vertical feature mask (VFM) profiles and \(R\) is the resolution of the VFM profile at altitudes of 8.3–20.2 km. Figure 7 shows the geographical distribution of upward RF at the top of the atmosphere and downward RF at Earth’s surface. It is almost certain that the existence of the CCLB reduces the outgoing radiation and increases the radiation absorbed by Earth’s surface. The warming effect is greater than 0.3 W m\(^{-2}\) near the Equator and over tropical continents. According to the IPCC\(^{36}\), RF is estimated as 0.01 (0.005 to 0.03) W m\(^{-2}\) for persistent (linear) contrails, with a medium confidence attached to this estimate. The RF of the CCLB is much larger than this recognized RF, but it is not considered fully in present climate models. We further calculated the global RF by averaging the whole grids in Fig. 7a, and found that the associated global RF is 0.07 W m\(^{-2}\). Furthermore, as CALIPSO cannot make observations at high latitudes the global RF could be larger than 0.07 W m\(^{-2}\). It is worth noting that the increase of \(Num_c\) will lead to the increase of RF. Therefore, if the less strict criteria (such as Criteria B or C) was used to identify the CCLB, the larger global RF would be estimated than the above result (0.07 W m\(^{-2}\)). As mentioned above, the less strict criteria may produce greater uncertainty for CCLB property estimation, even CCLB identification per se. We believe that with the development of instruments and algorithms, the estimated RF of CCLB will be more accurate than the current result.

As suggested by Lee et al.\(^{15}\), the longwave warming effect of tropical cirrus clouds is ~2.7 W m\(^{-2}\) at the top of the atmosphere, and ~0.6 W m\(^{-2}\) at the surface. Comparing with the RF of natural cirrus clouds, our results (greater than 0.3 W m\(^{-2}\) near the Equator, and 0.07 W m\(^{-2}\) for global at the top of the atmosphere) seem smaller an order of magnitude. However, it should be noted that conventional research may not – or not fully – consider the CCLB. Therefore, the RF caused by CCLB actually increases the uncertainty of cirrus RF, and needs to be accurately quantified.

Figure 5f shows the roughly one third of CCLBs lie entirely within cloud, and most CCLBs are halfway inside clouds. Is it possible that most CCLBs have been considered as cloud effects and less significant? We believe that some CCLB effects were indeed calculated in previous study, but please note that these CCLBs were treated as “clouds” rather than “transition zone” themselves. As was described, “cloud” and “transition zone” are different in optical properties so that misclassifying “transition zone” as “cloud” may introduce additional errors. To show the RF of CCLBs more accurately, a formula was designed to calculate the proportion of the inevitable missed CCLB, as well as the proportion of CCLBs in clear sky:

\[
P_m = 1 - \frac{\sum P_i}{Num}
\]

where \(P_m\) is the missed proportion of CCLBs (the part in clear sky); \(P_i\) is the in-cloud proportion (x-axis in Fig. 5f, but for each CCLB); \(Num\) is the amount of all CCLBs. After the investigation of the each CCLB, \(P_m\) is 28.25%, that is, at least 28.25% × 0.07 ≈ 0.02 W/m\(^2\) CCLB radiative effect has not been considered in any climate models and IPCC reports, which is still greater than contrail effect.

**Discussion**

The purpose of this study was to identify the CCLB and then estimate its optical properties and associated global RF using nighttime CALIPSO observations in June–August from 2006 to 2011. A global CCLB dataset was established to increase the search speed for information on individual CCLB cases, and to analyze the CCLB parameters.

The CCLB width can be identified by linear fitting of log(\(\beta_{355}\)) for the three key regions of cirrus clouds. It is hard for CERES to detect the small width (~10 km) of the CCLB, so the RF caused by the CCLB may be missed by current radiance observations. In addition, the optical depth of the CCLB is also so small that it may be partly missed by passive optical sensors such as MODIS or active microwave sensors such as CloudSat CPR. This study set out to gain a better understanding of the CCLB.

CCLB cases are mainly distributed in the intertropical convergence zone and tropical continents, which are high-frequency areas of high cloud\(^{46}\). The CCLB identification criteria affect the number of CCLB data points, but only slightly influence the geographical distribution pattern of the CCLB. The optical properties, such as 532 nm
backscatter, the depolarization ratio and optical depth, all sharply decrease from the cloudy region to the clear-sky region in the CCLB. Globally, there are significant regional differences in the optical properties, and height and thickness of the CCLB.

The average longwave RF of the CCLB at the top of the atmosphere is $-10$ to $-5 \text{ W} \cdot \text{m}^{-2}$. In other words, the CCLB warms the Earth. This effect may have been missed by previous estimations of the radiative energy budget using passive remote sensing observations and climate models due to the thinness and small scale of the CCLB. Further research evaluated the regional differences in RF considering coverage of the CCLB, and found that the strongest warming effect occurred near the Equator and over tropical continents. Based on a quantitative estimation, the global RF of the CCLB is at least $0.07 \text{ W} \cdot \text{m}^{-2}$, which is much larger than some forcings considered in the IPCC reports, such as persistent contrails from aviation (0.01 W m$^{-2}$). Because the strict criteria were used in the current estimation, some cirrus-clear boundaries were not designed as CCLBs, which likely underestimated the global RF of the CCLB.

Specifically, CALIOP is nearly the most accurate sensor for cloud observation. We are confident that no model or IPCC reports consider the cloud transition zone in CALIOP-detect clear sky. Therefore, CCLBs in traditional “clear-sky” region may be totally missed, which contribute 28.25% ($=-0.02 \text{ W} \cdot \text{m}^{-2}$) of the whole CCLB radiative effect, twice greater than contrail effect ($=-0.01 \text{ W} \cdot \text{m}^{-2}$).

This study first established a global CCLB dataset, and then quantitatively investigated the global distribution of CCLB properties and the associated RF. Notwithstanding some uncertainties and limitations related to observations and modeling, for example, only nighttime data could hardly show the diurnal cycle and the relationship with deep convection, the main strength of this study is the quantitative estimation of the RF using regional statistics rather than assumed values. It would be interesting to assess the boundary radiative effects of other types of cloud. Also, it is recommended that the RF of the CCLB should be considered in future climate models, and “cloud boundary” should be identified as an independent subcategory in the future scene classification.

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Author Contributions
Y.F. designed and organized the studies. Y.F. and Y.C. performed the analysis and wrote the manuscript. R.L. and Y.F. modified the last version of the manuscript. F.Q., T.X., A.Z., L.Y., G.L., and X.Z. provided comments and contributed to the text.

Additional Information
Competing Interests: The authors declare that they have no competing interests.

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