Protein folding simulations with Interacting Growth Walk model

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We demonstrate that the recently proposed interacting growth walk (IGW) model, modified for generating self-avoiding heteropolymers, proves to be a simpler alternative to the other Monte Carlo methods available in the literature for obtaining minimum energy conformations of lattice proteins. In fact, this simple growth algorithm seems to be capable of quickly leading to low energy states for all the three dimensional benchmark HP-sequences investigated.

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Proteins are non-branching heteropolymers obtained from twenty commonly occurring amino acids. Their specific biological functions are intimately related to their 'native' (i.e., unique and thermodynamically stable) conformational structure. One of the most challenging problems in Biophysics is to understand the kinetic mechanism by which the information encoded in an amino acid sequence helps the protein grow or fold quickly into its native conformation [1]. Since the amino acids can be classified broadly into hydrophobic (H) or polar (P) types, the problem may be simplified by treating a protein as a random copolymer made up only two types of amino acids with non-bonded contact interactions between them. If we ignore the intra-molecular structures of the individual amino acids (i.e., treat them as monomer units) then these interactions can be expressed in terms of a few effective parameters. Such a coarse-grained approach to this problem is justified by the observation that the protein-folding mechanisms and rates are determined more by the topology of protein conformations than by the details of interatomic interactions [2]. By assuming further that the individual bonds in the linear chain of monomers are all of equal length and can only be along the directions of a regular lattice, we have the lattice protein models [3], called HP-models, which are amenable to exact enumeration as well as Monte Carlo studies.

In this paper, we consider the problem of finding the native conformational structure that corresponds to a given HP-sequence and contact interactions. For short chains, the native state (or equivalently, the ground state) can easily be found by an exact enumeration of all possible conformations. However, for long chains, specially designed Monte Carlo methods [4] have to be used for generating a large ensemble of conformations before a ground state search is performed. This ignores the phenomenology of chain growth and its conformational relaxation.

The information for building the proteins is transcribed from the DNA to the mRNA, and translated into the corresponding amino acid sequences by a specific biochemical process - namely, as the ribosomes move along the mRNA strand from one codon to the next, different tRNA molecules lock into the appropriate places one after another, resulting in the transfer of the corresponding amino acids to the growing protein molecule. And as the protein grows, it coils into its secondary and tertiary structures as well.

In this paper, we discuss an implementation of this growth scenario for any given HP-sequence using the recently proposed Interacting Growth Walk (IGW) model [5]. We demonstrate that this simple growth algorithm is capable of quickly finding the ground state conformations for all the three dimensional benchmark sequences investigated [6,7].

Given a sequence of H and P monomers, say \( S_N = \{ A_j = H \text{ or } P; j = 0, 1, \ldots, N - 1 \} \), we start growing a lattice protein by placing the first monomer \( A_0 \) at an arbitrarily chosen site, \( r_0 \), of a regular \( d \)-dimensional lattice of coordination number \( z \). The second monomer, \( A_1 \), can be placed in any one of the \( z \) available nearest neighbour (NN) sites of \( r_0 \), chosen at random. Let the walk be non-reversing so that we have a maximum of \( z - 1 \) sites to choose from for making any further step. Let \( \{ r_k^m \mid m = 1, 2, \ldots, z_k \} \) be the 'unoccupied' NN sites available for making the \( k \)th step of the walk.
number of available sites, $z_k$, is zero, then the walk can not grow further because it is geometrically 'trapped'. In this case, we clear the lattice and start a fresh walk from $r_0$ again. If $z_k \neq 0$, the walk proceeds by choosing one of the $z_k$ available sites at random with a probability defined as follows.

Let $n^{m}_{k}$ be the number of non-bonded NN contacts which the $k$th monomer of type $A_k$ would make with the walk if it were placed at site $r_k$. Clearly, $0 \leq n^{m}_{k} < z - 1$. Some of these contacts will be with the H type, and some of them will be the P type monomers. Let these numbers be denoted by $n^m_{A_k H}$ and $n^m_{A_k P}$ respectively. If the energies associated with an HH-contact, an HP-contact and a PP-contact are denoted by $\varepsilon_{HH}$, $\varepsilon_{HP}$ and $\varepsilon_{PP}$ respectively, then the cost of energy involved in placing the $k$th monomer of type $A_k$ at $r_k$ is given by $E^{m}_{A_k} = n^{m}_{A_k H} \varepsilon_{A_k H} + n^{m}_{A_k P} \varepsilon_{A_k P}$. The probability of choosing the site $r_k$ for the $k$th monomer of type $A_k$ may now be defined as, $P^{m}_{A_k} \equiv \exp(-\beta E^{m}_{A_k}) / \sum m \exp(-\beta E^{m}_{A_k})$, where the summation is over all the $z_k$ available sites, $\beta = 1/k_B T$, $k_B$ is the Boltzmann constant and $T$ the temperature.

At 'infinite' temperature ($\beta = 0$), the walk is insensitive to the type of monomers being added and so is identical to the Kinetic Growth Walk (KGW) which in turn is in the same universality class as self-avoiding walk [5]. However, at zero temperature ($\beta = \infty$), the walk will grow into a compact or an extended conformation depending on whether the local site-energies, $E$, are negative or positive respectively. How compact a minimum energy conformation is going to be depends strongly on the fraction, $\chi$, of H type monomers in the walk - in the limit $\chi \rightarrow 1$, it is the most compact one, whereas in the other limit $\chi \rightarrow 0$, it is identical to the KGW which is noncompact. In order to mimic the tendency of the H type monomers to minimize contact with the aqueous medium by forming clusters, it is customary to choose the contact energies, $\varepsilon \equiv (\varepsilon_{HH}, \varepsilon_{HP}, \varepsilon_{PP}) = (-1, 0, 0)$, in lattice protein models.

In this case, at $T = 0$, an H type monomer will be placed at a site with maximum HH-contacts whereas a P type monomer is insensitive to the type of NN contacts. We have schematically illustrated this in Fig. 1. It is clear that the total energy associated with a conformation is equal to the total number of HH-contacts in the walk. However, such a straightforward adaptation of the IGW algorithm, hereafter referred to as the HP-IGW algorithm, does not automatically lead to ground state conformations corresponding to a given HP-sequence. Hence, we have further modified the HP-IGW algorithm so that it can be used in the multi-pass mode.

The given HP-sequence, $S_N$, may be partitioned into $M$ subsequences, $S_{N_1}, S_{N_2}, ..., S_{N_M}$, without changing the order in which the letters appear in the original sequence. Clearly, $S_N \equiv S_{N_1} \cup S_{N_2} \cup ... \cup S_{N_M}$ with $N = N_1 + N_2 + ... + N_M$. We concentrate on the zero temperature case.

![FIG. 1. Schematic illustration of HP-chain growth on a square lattice at $T = 0$.](image-url)

In 'pass' 1, we use the HP-IGW algorithm to generate a large number of chains consisting of $N_1$ monomers in the order, as well as of the type, specified by the first subsequence, $S_{N_1}$. Out of all the conformations generated, we store only those with minimum energy, say $-E_1$. Let $N_2$ denote the ensemble as well as the number of all these minimum energy conformations. This part of the algorithm is not truly kinetic because it does not simulate the relaxation kinetics in the conformation space. Nevertheless, together with the chain growth algorithm, it quickly leads to the ground state conformations.

In 'pass' 2, we take a chain, say $C^1_j \in N_1$, and use the HP-IGW algorithm to let it grow further by a chain segment consisting of $N_2$ monomers whose order and type are specified by the next subsequence, $S_{N_2}$. Thus we obtain a chain consisting of $N_1 + N_2$ monomers whose type and order are specified by the subsequence, $S_{N_1} \cup S_{N_2}$. We use the same chain segment $C^1_j$ again and again for generating a specified number of $(N_1 + N_2)$-monomer chain segments. We repeat this for all the chain segments, $\{C^1_j \in S_{N_1} \mid j = 1, 2, ..., N_1\}$. It is clear that all these chain conformations will have energy less than or equal to $-E_1$. Let $N_3$ denote the ensemble as well as the number of $(N_1 + N_2)$-monomer conformations with minimum energy $-E_2$, and so on. Thus, at the end of 'pass' $M$,
we have an ensemble of $N$-monomer chain conformations with minimum energy, $-\mathcal{E}(<-\mathcal{E}_{m-1} < \ldots < -\mathcal{E}_3 < -\mathcal{E}_1)$. It may be noted that the order and type of the monomers in the chains generated are as specified by the original sequence, $\mathcal{S}_N$. We have schematically illustrated this algorithm in Fig. 4. We generate a large number of chain conformations at every stage, not for the purpose of statistics, but to make sure that we obtain as many distinct conformations as possible. This improves the chances of obtaining minimum energy states. Moreover, the optimal lengths of the subsequences (i.e., the optimal values of $N_1, N_2, N_3$ etc.) for which we may get the 'global' minimum are strongly dependent on the particular sequence under consideration. 

We have tested this multi-pass algorithm for all the ten bench mark sequences of Yue et al [6] and for two of Toma & Toma [7]. These sequences were designed by minimizing the energy of a particular target conformation on a cubic lattice with the energy parameters given by $\vec{\epsilon} = (-1,0,0)$. We spent a maximum of thirty minutes CPU time on a DEC Alpha Workstation for each of these bench mark sequences. We could obtain the ground state conformations for some of these sequences in just two passes - namely, the first halves of the chains in the first pass, and the second halves in the second pass - while for others, in three passes. We find that generating the first segment of the chain from an arbitrary point in the sequence, rather than always from the beginning, ultimately leads to better ground states: (i) we occupy the site $r_0$ with the monomer of the type specified by the $n(1 \leq n \leq N_1)$th letter in the subsequence $\mathcal{S}_{N_1}$; (ii) the next monomer will then correspond either to the $(n-1)$th or to the $(n+1)$th letter in the sequence with probability 1/2, and so on. In other words, the chain will grow either to the left or to the right at random with equal probability. However, the successfully grown chain will finally have monomers in the same order as well as of the type specified by the subsequence, $\mathcal{S}_{N_1}$. The chain segments in subsequent passes will be grown always in the order in which they should grow. We handled these passes separately and manually, rather than as integrated modules in a single program. In Table I we have presented our results along with the ones reported in the literature.

**TABLE I.** Ground state energies obtained for the 3d bench mark sequences. All the sequences of Yue et al. [6] are of length $N = 48$. The sequences 10 and 11 of Toma and Toma [7] are of lengths, $N = 46$ and $N = 47$ respectively. The two energy values presented in the middle column are those of Yue et al and Bastolla et al [6]

| Ref.          | Seq. | $-E_{\text{min}}(\text{reported})$ | $-E_{\text{min}}(\text{ours})$ |
|--------------|------|-----------------------------------|----------------------------------|
| Yue et al [6]| 1    | 31, 32                            | 31                               |
|              | 2    | 32, 34                            | 32                               |
|              | 3    | 31, 34                            | 32                               |
|              | 4    | 30, 33                            | 30                               |
|              | 5    | 30, 32                            | 30                               |
|              | 6    | 30, 32                            | 30                               |
|              | 7    | 31, 32                            | 31                               |
|              | 8    | 31, 31                            | 30                               |
|              | 9    | 31, 34                            | 31                               |
|              | 10   | 33, 33                            | 31                               |
| Toma & Toma [7]| 10   | 34                                | 33                               |
|              | 11   | 42                                | 41                               |

In Fig.3, we have shown the distributions of NN contacts corresponding to the three passes used for Sequence 3 of Yue et al. Configurations of the first segment of length, $N_1 = 19$, with maximum number of contacts ($n_{\text{max}} = 9$) were used in the second pass for growing the second segment of length, $N_2 = 17$, whose minimum energy configurations ($n_{\text{max}} = 22$)

![Fig. 2. Schematic illustration of the multi-pass algorithm described in the text. $N_1, N_2$ and $N_3$ are the ensembles of conformations with minimum energies, $-\mathcal{E}_1$, $-\mathcal{E}_2$ and $-\mathcal{E}_3$ at the end of passes 1, 2 and 3 respectively.](image1)

![Fig. 3. The distributions of NN contacts obtained in the three passes used for the Sequence 3 of Yue et al](image2)
were in turn used for growing the last segment of length, $N_3 = 12$, in the third pass. The distributions, not normalized in any way with respect to each other, schematically illustrate how the number of contacts in a typical configuration can be increased in a progressive manner.

Thus, we have a simple but powerful growth algorithm which can be used for obtaining the ground state conformations of lattice proteins. A finite temperature version of this algorithm can be implemented in two ways. Since the temperature used in the chain growth process, say $T_G$, could be different from the temperature $T$ at which the fully grown conformations are sampled, we may use the growth module HP-IGW either at $T_G = 0$ or at $T_G \neq 0$. In the latter case, we may set $T_G = T$ so as to have just one temperature for the entire process. Having generated a chain conformation of energy $E$, we may store it with a probability proportional to the Botzmann factor, $\exp(-\beta E)$. This algorithm is similar to the simple enrichment scheme of Wall and Erpenbeck [8] for KGW at $T_G = T \to \infty$. It is also likely that this finite temperature version is more efficient for a ground state search than the zero temperature version discussed in this paper. A detailed study of this algorithm and its variants will be reported elsewhere.

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