**LAVIS: A Library for Language-Vision Intelligence**

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**Abstract**

We introduce LAVIS, an open-source deep learning library for LAnguage-VISion research and applications. LAVIS aims to serve as a one-stop comprehensive library that brings recent advancements in the language-vision field accessible for researchers and practitioners, as well as fertilizing future research and development. It features a unified interface to easily access state-of-the-art image-language, video-language models and common datasets. LAVIS supports training, evaluation and benchmarking on a rich variety of tasks, including multimodal classification, retrieval, captioning, visual question answering, dialogue and pre-training. In the meantime, the library is also highly extensible and configurable, facilitating future development and customization. In this technical report, we describe design principles, key components and functionalities of the library, and also present benchmarking results across common language-vision tasks. The library is available at: https://github.com/salesforce/LAVIS.

**1. Introduction**

Multimodal content, in particular language-vision data including texts, images and videos are ubiquitous for real-world applications, such as content recommendation, e-commerce and entertainment. There has been tremendous recent progress in developing powerful language-vision models [6, 12, 13, 18, 22, 31–34, 36, 40, 44, 50, 54, 56–58]. However, training and evaluating these models across tasks and datasets require domain knowledge and are not always welcoming to incoming researchers and practitioners. This is mainly due to inconsistent interfaces across models, datasets and task evaluations, and also the duplicating yet non-trivial efforts to prepare the required experiment setup. To make accessible the emerging language-vision intelligence and capabilities to a wider audience, promote their practical adoptions, and reduce repetitive efforts in future development, we build LAVIS (short for LAnguage-VISion), an open-source library for training, evaluating state-of-the-art language-vision models on a rich family of common tasks and datasets, as well as for off-the-shelf inference on customized language-vision data.

Figure 1 shows the overall design of LAVIS. Important features of LAVIS include (i) **Unified interface and modular design**. Key components in the library are organized using a unified and modular design. This allows effortless off-the-shelf access to individual components, swift development and easy integration of new or external components. The modular design also eases model inferences, such as multimodal feature extraction. (ii) **Comprehensive support of image-text, video-text tasks and datasets**. LAVIS supports a growing list of more than ten common language-vision tasks, across over 20 public datasets. These tasks and datasets provide a comprehensive and unified benchmark for evaluating language-vision models. (iii) **State-of-the-art and reproducible language-vision models**. The li-
library enables access to over 30 pre-trained and task-specific fine-tuned model checkpoints of four foundation models: ALBEF [34], BLIP [33], CLIP [44] and ALPRO [32]. These models achieve competitive performance across multiple tasks evaluated using common metrics. We also provide training, evaluation scripts and configurations to facilitate reproducible language-vision research and adoption.

(iv) **Resourceful and useful toolkit.** In addition to the core library functionalities, we also provide useful resources to further reduce the learning barriers for the language-vision research. This includes automatic dataset downloading tools to help prepare the supported datasets, a GUI dataset browser to help preview downloaded datasets and dataset cards documenting sources, supported tasks, common metrics and leaderboards.

### 2. Related Work

Table 1 summarizes the comparisons between LAVIS’ key features with those of other libraries. Most related libraries include MMF [49], UniLM [1], X-modaler [37] and TorchMultimodal [2].

- **MMF** is a comprehensive multimodal framework encapsulating many language-vision models and datasets. It implements modular interface for training and evaluation. However, it consists of mostly task-specific architectures. Besides showing relatively inferior performance, these models are usually not easy to transfer across tasks. Among the included foundation models [12, 34, 35, 56] in MMF, few fully support finetuning or benchmarking on the extended list of downstream tasks. In contrast, considering that pre-trained foundation models prevail across overwhelmingly many tasks and datasets with more principal and unified architectures, our library focuses on pre-trained models and their task-specific variants instead.

- **UniLM** was initiated for developing large language models, and recently also aggregates multiple standalone repositories of multimodal models. Yet, support for multimodal models in UniLM is limited in its current development status. Moreover, UniLM does not provide unified or modular interfaces to allow easy access or reproduction.

- **X-modaler** supports a limited number of tasks and datasets, which are not as comprehensive as LAVIS. Besides, similar to MMF, models in X-modaler are also mostly in task-specific architectures. The few supported foundation model, *e.g.* [12], achieves inferior results than models in LAVIS.

- A concurrent yet in-progress* library TorchMultimodal [2] promotes modular development of language-vision models. Our library supports a wider range of tasks and datasets than TorchMultimodal while being more comprehensive and resourceful.

Other open-source implementations of individual models exist [12,18,31,36,40,44], yet do not provide centralized access. In summary, in contrast to previous efforts, our library stands out by providing easier access to stronger models on comprehensively many tasks and datasets. With this effort, we hope to significantly reduce the cost and effort to leverage and benchmark existing multimodal models, as well as to develop new models.

### 3. Supported Tasks, Datasets and Models

Table 3 summarizes the supported tasks, datasets and models in LAVIS. In particular, we prioritize tasks that are standard, widely adopted for evaluation, and with publicly available datasets. For image-text tasks, the library implements image-text retrieval, image captioning, visual question answering (VQA), visual dialogue, visual entailment (VE), natural language visual reasoning (NLVR²) and image classification. For video-text tasks, LAVIS currently support video-text retrieval and video question answering (VideoQA). There are in total over 20 public datasets supported, including MSCOCO [39], Flickr30k [43], VQAv2 [19], OK-VQA [41], A-OK-VQA [48], Visual Genome [26], ImageNet [15], NoCaps [3], Conceptual Captions [11, 47], SBU-caption [42], LAION [45], NLVR² [51], SNLI-VE [9], VisDial [14], AVSD [4], MSRVTT [55], MSVD [53], DiDeMo [5] and their task-specific variants.

LAVIS currently supports 4 foundation models, *i.e.* ALBEF [34], BLIP [33], CLIP [44] and ALPRO [32].

- **ALBEF** is an image-text model. It employs a ViT [17] as the image encoder, early BERT [16] layers as the text encoder, and re-purposes late BERT layers as the multimodal encoder by adding cross-attentions. It proposes the novel image-text contrastive (ITC) loss to align unimodal features before fusing them using the multimodal encoder. It is also one of the first few models requiring no region information while demonstrating strong multimodal understanding capability.

- **BLIP** primarily tackles image-text tasks, while also showing strong zero-shot transfer capabilities to video-text tasks. It employs a ViT as the image encoder and a BERT as the text encoder. To facilitate multimodal understanding and generation, BLIP proposes mixture of encoder-decoder (MED), which re-purposes BERT into multimodal encoder and decoder with careful weight sharing. Moreover, BLIP proposes dataset bootstrapping to improve the quality of texts in the pre-training corpus by removing noisy ones and generating

*by the publication date of this report.
Table 1. Comparison of features in LA VIS and other existing language-vision libraries or codebase. Note that language-vision models in UniLM and TorchMultimodal (alpha release) are under development, therefore, the table only includes their supported features by the publication time of this technical report.

| feature | LA VIS (Ours) | MMF | UniLM | X-modaler | TorchMultimodal |
|---------|---------------|-----|-------|-----------|-----------------|
| Unified Model and Dataset Interface | ✓ | | | | |
| Modular Library Design | ✓ | ✓ | ✓ | ✓ | ✓ |
| Pre-trained Model Checkpoints | ✓ | | | | |
| Task-specific Finetuned Model Checkpoints | ✓ | | | | |
| Modalities | | | | | |
| Image-Text | ✓ | ✓ | ✓ | ✓ | ✓ |
| Video-Text | ✓ | ✓ | | | |
| Tasks | | | | | |
| End2end Pre-training | ✓ | ✓ | | | |
| Multimodal Retrieval | ✓ | ✓ | ✓ | ✓ | ✓ |
| Captioning | ✓ | ✓ | ✓ | ✓ | ✓ |
| Visual Question Answering | ✓ | ✓ | ✓ | ✓ | ✓ |
| Multimodal Classification | ✓ | ✓ | ✓ | ✓ | ✓ |
| Visual Dialogue | ✓ | ✓ | ✓ | ✓ | ✓ |
| Multimodal Feature Extraction | ✓ | ✓ | ✓ | ✓ | ✓ |
| Toolkit | | | | | |
| Benchmarks | ✓ | ✓ | ✓ | ✓ | ✓ |
| Dataset Auto-downloading | ✓ | ✓ | ✓ | ✓ | ✓ |
| Dataset Browser | ✓ | ✓ | ✓ | ✓ | ✓ |
| GUI Demo | ✓ | ✓ | ✓ | ✓ | ✓ |
| Dataset Cards | ✓ | ✓ | ✓ | ✓ | ✓ |

Table 2. Supported tasks, datasets and models in LA VIS.

| Supported Tasks | Supported Models | Supported Datasets |
|-----------------|------------------|--------------------|
| Image-text Pre-training | ALBEF, BLIP | COCO, Visual Genome, SBU Caption, Conceptual Captions (3M, 12M), LAION |
| Image-text Retrieval | ALBEF, BLIP, CLIP | COCO, Flickr30k |
| Visual Question Answering | ALBEF, BLIP | VQAv2, OKVQA, A-OKVQA |
| Image Captioning | BLIP | COCO Caption, NoCaps |
| Image Classification | CLIP | ImageNet |
| Natural Language Visual Reasoning (NLVR²) | ALBEF, BLIP | NLVR² |
| Visual Entailment | ALBEF | SNLI-VE |
| Visual Dialogue | BLIP | VisDial |
| Video-text Retrieval | ALPRO, BLIP | MSRVTT, DiDeMo |
| Video Question Answering | ALPRO, BLIP | MSRVTT-QA, MSVD-QA |
| Video Dialogue | BLIP | AVSD |

new diverse ones. In addition to the improved understanding capability compared to ALBEF, BLIP highlights its strong text generation ability, producing accurate and descriptive image captions. When adapted to video-text tasks, it operates on sampled frames while concatenating their features to represent the video.

- CLIP is a family of powerful image-text models. Different from ALBEF and BLIP, CLIP models adopt two unimodal encoders to obtain image and text representations. CLIP maximizes the similarity between positive image-text pairs, and was trained on 400M image-text pairs, rendering strong and robust unimodal representations. CLIP variants employ different visual backbones, including ResNet-50 [21], ViT-B/16, ViT-B/32, ViT-L/14, ViT-L/14-336. We integrate a third-party implementation of CLIP [23] into LA VIS while including the official pre-trained weights.

- ALPRO is a video-text model, tackling video-text re-
trieval and video question answering tasks. It uses TimeSformer [8] to extract video features, and BERT to extract text features. Similar to ALBEF, ALPRO uses contrastive loss to align unimodal features, yet it opts to use self-attention to model multimodal interaction. This architecture choice enables an additional visual-grounded pre-training task, i.e. prompt entity modeling (PEM) to align fine-grained video-text information. ALPRO is strong in extracting regional video features and remains competitive for video understanding tasks across various datasets.

4. Library Design

This section delineates the design of LAVIS as shown in Figure 1. Our key design principle is to provide a simple and unified library to easily (i) train and evaluate the model; (ii) access supported models and datasets; (iii) extend with new models, tasks and datasets.

4.1. Description on each library component

Key components in LAVIS include:

- **Runners** – *lavis.runners* module manages the overall training and evaluation lifecycle. It is also responsible for creating required components lazily as per demand, such as optimizers, learning rate schedulers and dataloaders. Currently, *RunnerBase* implements epoch-based training and *RunnerIters* implements iteration-based training.

- **Tasks** – *lavis.tasks* module implements concrete training and evaluation logic per task. This includes pre-training and finetuning tasks as listed in Table 3. The rationale to have an abstraction of task is to accommodate task-specific training, inference and evaluation. For example, evaluating a retrieval model is different from a classification model.

- **Datasets** – *lavis.datasets* module helps create datasets. Specifically, *datasets.builders* module loads dataset configurations, downloads annotations and builds the dataset;
  - *lavis.datasets.datasets* module defines the supported datasets, each is a PyTorch dataset instance.
  - We also provide automatic dataset downloading tools in *datasets/download_scripts* to help prepare common public datasets.

- **Models** – *lavis.models* module holds definitions for the supported models and shared model layers.

- **Processors** – *lavis.processors* module handles preprocessing of multimodal input. A processor transforms input images, videos and texts into the desired form that models can consume.

- **Common tools and utilities** – *lavis.commons* module contains shared classes and methods used by multiple other modules. For example, *configs* module contains classes to store and manipulate configuration files used by LAVIS. In particular, we use a hierarchical configuration design, to allow highly customizable training and evaluation. The *registry* module serves as a centralized place to manage modules that share the same functionalities. It allows building datasets, models, tasks, and learning rate schedulers during runtime, by specifying their names in the configuration; *optims* contains definitions of learning rate schedulers; *utils* contains miscellaneous utilities, mostly IO-related helper functions.

4.2. Example library usage

The design of the library enables easy access to existing models and future development. In this section, we include a few examples to demonstrate some common use cases.

Unified interface for loading datasets and models

LAVIS provides unified interface *load_dataset* and *load_model* to access supported datasets and models. This is helpful for off-the-shelf use of datasets and model inference etc. In the first example, we show how to load a dataset using the library.

```python
from lavis.datasets.builders import load_dataset
# load a specific dataset
coco_dataset = load_dataset("coco_caption")
# dataset is organized by split names.
print(coco_dataset.keys())
# dict_keys(['train', 'val', 'test'])
# total number of samples in the training split.
print(len(coco_dataset["train"]))
# 566747
# peek a random sample
print(coco_dataset["train"][0])
# {
#   'image': <PIL.Image.Image image mode=RGB size=640x480>,
#   'text_input': 'A woman wearing a net on her head cutting a cake. ',
#   'image_id': 0
# }
```

Models and their related preprocessors can also be loaded via a unified interface, which facilitates effortless analysis and inference on custom data. In the following, we show an example that uses a BLIP captioning model to generate image captions.
from lavis.models import
  load_model_and_preprocess
# load model and preprocessors
model, vis_procs, _ = load_model_and_preprocess(
  name="blip_caption", model_type="base_coco")
# preprocess a raw input image
image = vis_procs["eval"](raw_image).unsqueeze(0)
# generate caption
caption = model.generate({"image": image})
"a man riding a motorcycle down a dirt road"

Unified interface for multimodal feature extraction

LA VIS supports a unified interface to extract multimodal features. The features are useful especially for offline applications where end-to-end fine-tuning is not affordable. By changing name and model_type, users can choose to use different model architecture and pre-trained weights.

# load feature extraction models and processors
model, vis_procs, txt_procs = load_model_and_preprocess(
  name="blip_feature_extractor", model_type="base")
# a random instance from coco dataset
raw_image = coco_dataset["test"][0]["image"]
# process the input
image = vis_procs["eval"](raw_image).unsqueeze(0)
text_input = txt_procs["eval"](text)
sample = {"image": image,
  "text_input": [text_input]}
# extract multimodal features
features = model.extract_features(sample)

5. Benchmarks and Library Toolkit

In this section, we benchmark model performance across tasks and datasets in LA VIS. Then we take our web demo interface to show a few case studies on multimodal content understanding. We also present a GUI dataset browser that helps to preview supported datasets.

5.1. Main results

The purpose of the benchmark is two-fold. First, since most models in LA VIS are integrated from prior works, we use the benchmark to validate that our re-implementation faithfully replicates official models. Second, the benchmark also serves as a reference for further development and extension. In Table 3-6, we organize benchmark results by models and compare our replication results with those reported officially. Experiments are conducted on NVIDIA A100 GPUs.

| Tasks     | Datasets | Impl. | Results |
|-----------|----------|-------|---------|
| Retrieval |          |       | R1     | R5     | R10    |
| TR        | COCO*    | 🔄 77.6  | 94.3   | 97.2   |
| IR        | COCO     | 🔄 60.7  | 84.3   | 90.5   |
| TR        | Flickr30k| 🔄 95.9  | 99.8   | 100.0  |
| IR        | Flickr30k| 🔄 85.6  | 97.5   | 98.9   |

Table 3. Comparison between official and replicated task performance using ALBEF. TR denotes text retrieval; IR denotes image retrieval. The impl. column indicates results are from official implementation ( Crate ) or replication in LA VIS ( Crate ). (*) We use COCO Karpathy split [25] in all the experiments.

| Tasks     | Datasets | Impl. | Results |
|-----------|----------|-------|---------|
| Retrieval |          |       | R1     | R5     | R10    |
| TR        | COCO     | 🔄 82.4 | 95.4   | 97.9   |
| IR        | COCO     | 🔄 82.0 | 95.8   | 98.1   |
| TR        | Flickr30k| 🔄 65.1 | 86.3   | 91.8   |
| IR        | Flickr30k| 🔄 64.5 | 86.0   | 91.7   |
| TR        | Flickr30k| 🔄 97.2 | 99.9   | 100.0  |
| IR        | Flickr30k| 🔄 96.9 | 99.9   | 100.0  |

Table 4. Comparison between official and replicated performance using BLIP. TR denotes text retrieval; IR denotes image retrieval. Results are produced by BLIPCapFilt-L model. NoCaps results are reported on the entire validation set. Retrieval and captioning results are reported on the test sets; B@4 denotes BLEU-4.
Table 5. Comparison between official and replicated task performance using ALPRO. TR denotes video-to-text retrieval; VR denotes text-to-video retrieval.

| Tasks   | Datasets | Impl. | Results |
|---------|----------|-------|---------|
| Retrieval |          |       | R1  | R5  | R10 |
| TR      | MSRVTT  |       | 32.0 | 60.7 | 70.8 |
|         |         |       | 33.2 | 60.5 | 71.7 |
| VR      | MSRVTT  |       | 33.9 | 60.7 | 73.2 |
|         |         |       | 33.8 | 61.4 | 72.7 |
| TR      | DiDeMo  |       | 37.9 | 67.1 | 77.9 |
|         |         |       | 38.8 | 66.4 | 76.8 |
| VR      | DiDeMo  |       | 35.9 | 67.5 | 78.8 |
|         |         |       | 36.6 | 67.5 | 77.9 |

Tasks Datasets Impl. Results

Table 6. Comparison between official and replicated performance using CLIP-ViT-L/336. Note the relative difference is possibly due to the versioning of the model weights.

| Tasks   | Datasets | Impl. | Results |
|---------|----------|-------|---------|
| Retrieval |          |       | R1  | R5  | R10 |
| TR      | COCO    |       | 58.4 | 81.5 | 88.1 |
|         |         |       | 57.2 | 80.5 | 87.8 |
| IR      | COCO    |       | 37.8 | 62.4 | 72.2 |
|         |         |       | 36.5 | 60.8 | 71.0 |
| TR      | Flickr30k|     | 88.0 | 98.7 | 99.4 |
|         |         |       | 86.5 | 98.0 | 99.1 |
| IR      | Flickr30k|     | 68.7 | 90.6 | 95.2 |
|         |         |       | 67.0 | 88.9 | 93.3 |

models in LAVIS based on the official repositories and report finetuning results using their official pre-trained weights (Table 3-5). For CLIP models, we integrate a third-party implementation [23] and report CLIP-ViT-L/336 zero-shot inference results using the official weights [44] (Table 6). As can be seen in the tables, our library consistently produce similar results as reported officially.

5.2. Additional task results with LAVIS

In Table 7, we present results by adapting models in LAVIS to new tasks and datasets, on which the models were not previously reported on. In this way, we show that our library helps to easily adapt to new tasks and datasets, while achieving competitive performance.

Table 7. Experiment results on KVQA compared with best existing methods. Due to the submission number limits, only BLIP AOKVQA result on the test split is reported.

| Tasks   | Datasets | Models         | Results |
|---------|----------|----------------|---------|
| KVQA    | test     | KAT (Single) [20] | 53.1 |
|         |          | KAT (Ensemble) [20] | 54.4 |
|         |          | ALBEF           | 54.7 |
|         |          | BLIP            | 55.4 |
| AOKVQA  | val      | GPV-2 [24]     | 48.6 |
|         | test     | ALBEF           | 45.4 |
|         |          | BLIP (VQA2)    | 53.4 |
|         |          | BLIP            | 56.2 |

Knowledge-based VQA (KVQA). The task of KVQA aims to measure the commonsense knowledge learnt by language-vision models, where models are asked to answer questions involving external knowledge. To this end, state-of-the-art models [20, 24] resort to external knowledge base [52] and/or large language models [10]. In our experiments, we show that language-vision pre-trained models finetuned on VQAv2 [19] show strong transfer results to KVQA datasets. With additional finetuning on KVQA datasets, further improvements are observed on both OKVQA and AOK-VQA datasets. As a result, our best model BLIP surpasses previous state-of-the-art by a clear margin.

Video Dialogue. The task of video-grounded dialogues requires models to generate a natural response given a dialogue context and a grounding video [4]. Existing models have exploited new architectural designs [30], additional learning tasks [27, 28], and pretraining [29, 38] to improve the model abilities to understand multimodal context and generate natural language. In our experiments, we show that our library can be easily integrated with any vision-language models (such as VGD-GPT [29]) to adapt to this dialogue task. The results in Table 7 show that our model implementation with LAVIS can lead to impressive performance, comparable to current state-of-the-art approaches.

5.3. Library resources and toolkit

In addition to the components aforementioned, LAVIS also provides useful toolkit and resources to further ease development. This includes pre-trained and finetuned model checkpoints, automatic dataset downloading tools, a web demo and a dataset browser.

Pre-trained and finetuned model checkpoints. We include pre-trained and finetuned model checkpoints in the library. This promotes easy replication of our experiment.

*Source repos: ALBEF, BLIP, ALPRO and OpenClip.*
results and to repurpose pre-trained models for other applications. Model checkpoints are downloaded automatically upon loading models.

**Web demo.** As shown in Figure 2, we develop a GUI-based web demo, which aims to provide a user-friendly interface to explore various multimodal capabilities. Currently the demo supports the following functionalities: (i) *image captioning*: produces a caption in natural language to describe an input image; (ii) *visual question answering*: answer natural language questions regarding the input image; (iii) *multimodal search*: search images in a gallery given a text query; (iv) *text visualization*: given an input image and a text caption, produces GradCam [46] for each text token on the image; (v) zero-shot multimodal classification: classify an input images into a set of input labels in text. (vi) Thanks to the modular design of LA VIS, one can easily extend the demo with new functionalities, such as *text-to-image generation*, as shown in the Figure 2.

![Automatic dataset downloading and browsing.](image)

Preparing language-vision datasets for pre-training and fine-tuning incurs much duplicating effort. To this end, LA VIS provides tools to automatically download and organize the public datasets, so that users can get access to the common datasets easier and quicker. In addition, we also develop a GUI dataset browser, as shown in Figure 3, that helps users to rapidly gain intuitions about the data they use.

**6. Conclusion and Future Work**

We present LA VIS, an open-source deep learning library for language-vision research and applications. The library is designed to provide researchers and practitioners with easier and comprehensive access to state-of-the-art multimodal capabilities, The library also features a unified inter-
face and extensible design to promote future development. Besides, the library also features extensive access to pre-trained weights and useful resources to reduce duplicating replication efforts. With these features, we expect LA VIS to serve as a one-stop library in multimodal AI for a wide and growing audience.

We continue to actively develop and improve LA VIS. In future releases, our priorities are to include more language-vision models, tasks and datasets to the library. We also plan to add more parallelism support for scalable training and inference. While we will maintain LA VIS in the long term, we welcome and invite contributions from the open-source community to join this evolving effort.

Broader Impact and Responsible Use

LA VIS can provide useful capabilities for many real-world multimodal applications. It features easy, unified and centralized access to powerful language-vision models, facilitating effective multimodal analysis and reproducible research and development. We encourage researchers, data scientists, and ML practitioners to adopt LA VIS in real-world applications for positive social impacts, e.g. efficient and environment-friendly large-scale multimodal analysis.

However, LA VIS may also be misused. We encourage users to read detailed discussion and guidelines for building responsible AI, e.g. [7]. In particular, LA VIS should not be used to develop multimodal models that may expose unethical capabilities.

It is also important to note that that models in LA VIS provide no guarantees on their multimodal abilities; incorrect or biased predictions may be observed. In particular, the datasets and pretrained models utilized in LA VIS contain socioeconomic biases which may result in misclassification and other unwanted behaviors such as offensive or inappropriate speech. We strongly recommend that users review the pre-trained models and overall system in LA VIS before practical adoption. We plan to improve the library by investigating and mitigating these potential biases and inappropriate behaviors in the future.

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