Abstract. Examples show that Riemannian manifolds with almost-Euclidean lower bounds on scalar curvature and Perelman entropy need not be close to Euclidean space in any metric space sense. Here we show that if one additionally assumes an almost-Euclidean upper bound on volumes of geodesic balls, then unit balls in such a space are Gromov-Hausdorff close, and in fact bi-Hölder and bi-$W^{1,p}$ homeomorphic, to Euclidean balls. We prove a compactness and limit space structure theorem under the same assumptions.

1. Introduction

The scalar curvature of a Riemannian manifold $(M^n,g)$ governs volumes of geodesic balls of asymptotically small radii. More specifically, for $x \in M$ and $r > 0$,
\[
\text{vol}_g(B_g(x,r)) = \omega_n r^n \left\{ 1 - \frac{R_g(x)}{6(n+2)} r^2 + O(r^4) \right\}.
\] (1.1)
Here $B_g(x,r)$ is a geodesic ball, $\omega_n r^n$ is the volume of a Euclidean ball of radius $r$, and $R_g(x)$ is the scalar curvature of $(M,g)$ at $x$. For a Riemannian manifold with a lower bound $R_g \geq -\delta$ on the scalar curvature, this Taylor expansion gives an upper bound
\[
\text{vol}_g(B_g(x,r)) \leq (1 + \delta)\omega_n r^n
\] (1.2)
for the volumes of balls of sufficiently small radii. However, the error term $O(r^4)$ in (1.1) and hence the threshold of “sufficiently small” in (1.2) depends not only on the scalar curvature, but on the full curvature tensor of the metric $g$. This means that in practice, (1.1) and (1.2) have limited utility in the study of spaces with lower bounds on scalar curvature.

On the other hand, lower bounds on the Ricci curvature lead to volumes control for geodesic balls of all radii. In particular, for small $\delta > 0$, a lower bound $\text{Ric}_g \geq -c_n \delta$ on the Ricci curvature implies that the upper bound (1.2) holds for all scales $r \in (0,1]$ thanks to the Bishop-Gromov inequality. Furthermore, if a unit ball in such a space has an almost-Euclidean “noncollapsing” bound $\text{vol}_g(B_g(x,1)) \geq (1 - \delta)\omega_n$, then $B_g(x,r)$ has almost-Euclidean volume for every scale $r \in (0,1]$, again by Bishop-Gromov. Cheeger and Colding [Col97, CC97] proved the following epsilon regularity theorem in this context, which serves as a starting point for the structure and regularity theory for Riemannian manifolds with Ricci curvature lower bounds and their limit spaces [CC97, CC00a, CC00b, CC96, CN13, CJN21].

**Theorem 1.1** (Cheeger-Colding). Fix $n \geq 2$ and $\epsilon > 0$. There exists $\delta = \delta(n,\epsilon) > 0$ such that if $(M,g)$ is a Riemannian manifold with $\text{Ric}_g \geq -\delta$ and $\text{vol}_g(B_g(x,1)) \geq (1 - \delta)\omega_n$ for a given $x \in M$, then $d_{GH}(B_g(x,1),B_{g_{\text{eucl}}}(0^n,1)) < \epsilon$.

Here $d_{GH}$ is the Gromov-Hausdorff distance; see for instance [Pet98, Chapter 10].

In [LNNb], Lee, Naber and the author sought to formulate and prove an analogous epsilon regularity theorem with lower bounds on scalar curvature in place of Ricci curvature. It turns out...
that the Gromov-Hausdorff control of Theorem 1.1 is false in that context, even when one assumes an almost Euclidean bound \( \nu(g, 2) \geq -\delta \) on the Perelman entropy, which is a stronger type of noncollapsing condition. (We define the Perelman entropy precisely and discuss its relation to the volume noncollapsing condition in section 2.) We construct examples in [LNNb] (see also [LNa] and [LT22]) showing that Riemannian manifolds with almost-Euclidean lower bounds on scalar curvature and Perelman entropy can have metric space structures that are far from Euclidean.

**Theorem 1.2** (Lee-Naber-N.). Fix \( n \geq 4 \). There exists \( C = C(n) \) such that for every \( \delta > 0 \) there exists a complete Riemannian manifold with bounded curvature such that \( R_g \geq -\delta \) and \( \nu(g, 2) \geq -\delta \), but \( d_{GH}(B_g(x, 1), B_{euc}(0^n, 1)) \geq C \).

The simplest example of Theorem 1.2 comes from a family of metrics \( g_i \) on \( \mathbb{R}^n \) that are Euclidean away from a line \( \{ x_1 = \cdots = x_{n-1} = 0 \} \) and become increasingly degenerate along this line; in the pointed Gromov-Hausdorff limit the entire line collapses to a point. In a related example, we paste copies of this family onto a flat torus to construct a sequence of metrics \( g_i \) on the torus whose volumes converge to the volume \( v \) of the initial flat torus but that converge in the Gromov-Hausdorff topology to a single point.

In both of these examples, the “sufficiently small” scale up to which (1.2) holds degenerates to zero along the sequence. For the first, the volumes \( \text{vol}_{g_i}(B_{g_i}(0^n, r)) \) tend to infinity as \( i \to \infty \) for any fixed \( r \); in the global Euclidean chart in which the \( g_i \) are defined, \( g_i \)-geodesic balls look increasingly elongated along the central fiber. In the second, the volumes of \( g_i \)-balls of any radius converge to \( v \) as \( i \to \infty \).

In this note we show that if the upper bound (1.2) holds up to a definite scale, then distance functions cannot degenerate. With this additional assumption, we recover Gromov-Hausdorff a priori regularity analogous to Theorem 1.1, and in fact bi-Hölder and bi-\( W^{1,p} \) estimates, as well as measured Gromov-Hausdorff compactness and several structural properties of limit spaces. We begin with the epsilon regularity theorem:

**Theorem 1.3.** Fix \( n \geq 2 \) and \( \epsilon > 0 \), \( \alpha \in (0, 1) \) and \( p \geq 1 \). There exists \( \delta = \delta(n, \epsilon, \alpha, p) > 0 \) such that the following holds. Let \( (M, g) \) be a complete Riemannian \( n \)-manifold with bounded curvature such that

\[
R_g \geq -\delta, \quad \nu(g, 2) \geq -\delta \tag{1.3}
\]

and

\[
\text{vol}_{g}(B_{g}(x, r)) \leq (1 + \delta) \omega_{n} r^{n} \quad \forall r \in (0, 2]. \tag{1.4}
\]

Then for any \( x \in M \), there is a smooth diffeomorphism \( \psi : B_{g}(x, 1) \to U \subset \mathbb{R}^n \) with \( \psi(x) = 0 \) and \( B_{g_{euc}}(0, 1 - \epsilon) \subset U \subset B_{g_{euc}}(0, 1 + \epsilon) \) satisfying the bi-Hölder estimates

\[
(1 - \epsilon) d_{g}(y, z)^{1/\alpha} \leq |\psi(y) - \psi(z)| \leq (1 + \epsilon) d_{g}(y, z)^{\alpha} \tag{1.5}
\]

for all \( y, z \in B_{g}(x, 1) \) and the \( W^{1,p} \) estimates

\[
\int_{U} |(\psi^{-1})^{*} g - g_{euc}|^{p} \, dy \leq \epsilon, \quad \int_{B_{g}(x, 1)} |\psi^{*} g_{euc} - g|^{p} \, d\text{vol}_{g} \leq \epsilon \tag{1.6}
\]

The assumption (1.3) implies that \( \text{vol}_{g}(B_{g}(x, r)) \geq (1 - \epsilon)\omega_{n} r^{n} \) for all \( x \in M \) and \( r \in (0, 1] \), i.e. balls are non-collapsing up to scale one with an almost-Euclidean volume ratio; see Lemma 2.3. In particular, the assumptions (1.3) and (1.4) together imply that the volume measure is doubling up to scale one. In (1.6), \( \cdot \) \( \cdot \) denotes the tensor norm with respect to \( g \) and \( g_{euc} \) respectively. The estimate (1.6) is equivalent to \( \int_{B_{g}(x, 1)} |d\psi|^{p} \, d\text{vol}_{g} \leq 1 + \epsilon \) and \( \int_{U} |d\psi^{-1}|^{p} \, dy \leq 1 + \epsilon \), i.e. they
are $W^{1,p}$ estimates for the map $\psi$ and its inverse. Theorem 1.3 in particular implies that for any $x \in M$, we have $d_{GH}(B_g(x, 1), B_{d_{weu}}(0^g, 1)) \leq \epsilon$.

Theorem 1.3 is closely related to the work of Bing Wang in [Wan20], and in fact the first conclusion (1.5) can be deduced from results there. In [Wan20] and the companion paper [Wan18], Wang introduces and proves localized versions of many of Perelman’s fundamental Ricci flow concepts, included entropy functionals, no-local collapsing theorems, and pseudo-locality theorems. In [Wan20, Section 5], he points out the key ideas, which are already present in [TW15], that “when the volume element is decreasing and the distance is expanding, we shall have a rough distance distortion estimate along the [Ricci] flow, if the initial volume ratio has an upper bound,” and that such an estimate can be refined using an integral estimate for the scalar curvature. The conclusion (1.5) in Theorem 1.3 can be shown by combining Proposition 5.3 and Theorem 5.4 of Wang’s [Wan20] with Lemma 2.1 below. Instead we give a slightly different (though fundamentally similar) proof, which is self contained apart from a few facts pulled from [LNNb]. The conclusion (1.6) does not follow from [Wan20] and rests upon a decomposition theorem proven by Lee, Naber and the author in [LNNb]. The overall proof scheme of Theorem 1.3 is similar to the proof of the main epsilon regularity theorem in [LNNb, Theorem 1.1].

Next, we have a compactness result and structure theorem for limit spaces under the same assumptions of Theorems 1.3.

**Theorem 1.4.** Fix $n \geq 2$, $\epsilon > 0$, $C_0 > 0$, $r_0 > 0$, and $\tau_0 > 0$. There exists $\delta = \delta(n, \epsilon) > 0$ such that the following holds. Let $\{(M_i, g_i, x_i)\}$ be a sequence of complete pointed Riemannian manifolds with bounded curvature satisfying

$$R_{g_i} \geq -C_0, \quad \nu(g_i, \tau_0) \geq -\delta, \quad \text{and} \quad \text{vol}_{g_i}(B_{g_i}(x, r)) \leq (1 + \delta)\omega_n r^n$$

for all $x \in M_i$ and $r \in (0, r_0]$. Then, up to a subsequence, $(M_i, g_i, x_i, d\text{vol}_{g_i})$ converges in the pointed measured Gromov-Hausdorff topology to a pointed metric measure space $(X, d, x_\infty, m)$ satisfying the following properties:

1. $X$ is an $n$-dimensional manifold.
2. For each $x \in X$ and $r \in (0, \rho_0)$, where $\rho_0^2 := \min\{\delta/C_0, \tau_0/2, r_0^2/4\}$ we have

$$(1 - \epsilon)\omega_n r^n \leq m(B_d(y, r)) \leq (1 + \delta)\omega_n r^n.$$  \quad (1.8)

3. The measure $m$ and the $n$-dimensional Hausdorff measure $\mathcal{H}^n$ are mutually absolutely continuous, with $m = f\mathcal{H}^n$ for a function $f$ satisfying $(1 - \epsilon) \leq f \leq (1 + \delta)$.
4. $X$ is $\mathcal{H}^n$-rectifiable and $m$-rectifiable.

Recall that a metric space $X$ is $m$-rectifiable if there is a countable collection of $m$-measurable subsets $\mathcal{F}^k \subset X$ and bi-Lipschitz maps $\psi_k : \mathcal{F}^k \to U_k \subset \mathbb{R}^n$ such that $m(X \setminus \cup_k \mathcal{F}^k) = 0$.

Let us make some comments regarding the theorems above.

1. In view of recent work of Liang Cheng in [Che22], as well as Wang’s work in [Wan18, Wan20], it is likely possible to establish local versions of Theorems 1.3 and 1.4. We will pursue this in upcoming work.
2. In Theorem 1.4, one is led to wonder whether the measure $m$ is equal to the $n$-dimensional Hausdorff measure $\mathcal{H}^n$. We are not sure. If one replaces the volume growth assumption in (1.7) with the stronger assumption $\text{vol}_{g_i}(B_{g_i}(x, r)) \leq (1 + \sigma(r))\omega_n r^n$ for all $x \in M_i$ and $r \in (0, r_0]$ for some modulus of continuity $\sigma$ that is uniform in $i$, then indeed one can show that $m = \mathcal{H}^n$ using a refinement of the decomposition theorem in Lemma 2.5.
3. In [LNNb, Theorem 1.15], we prove a different type of compactness and limit structure theorem for sequences satisfying only the first two conditions of (1.7) in Theorem 1.4. In view of the examples discussed above, the objects that arise as limit spaces are not metric.
spaces. Instead, we show in [LNNb] for any \( p > n \), one can choose \( \delta = \delta(n,p) \) small enough so that such sequences converge in the pointed \( d_p \) sense to a so-called pointed rectifiable Riemannian space that has certain nice structural properties. Without getting too far into details, we mention that it would be interesting to systematically investigate the relationship and compatibility between the limits of Theorem 1.4 and [LNNb, Theorem 1.15].

(4) In [LNNb, Theorem 1.11], we prove that under only assumption (1.3), the metric enjoys \( W^{1,p} \) estimates of a similar form to (1.6) (with the important distinction that in [LNNb] the domain of \( \psi \) and of the second integral in (1.6) is not \( B_g(x, 1) \) but rather a “\( d_p \) ball”).

Theorem 1.3 shows that with the additional assumption (1.4) of control from above on the volumes of balls, these estimates (which give \( L^p \) estimates for the metric coefficients) can be upgraded to control on the distance functions. Although their results are not directly applicable here, we point out that similar themes are present in [AS20, All21], where various conditions are given allowing one can upgrade from \( L^p \) control on metric coefficients to control of the distance functions, and in [APS20] where upper volume control combined with one-sided control of distance functions is shown to imply volume preserving intrinsic flat convergence.

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2. Preliminaries

The Perelman entropy was introduced by Perelman in [Per02] as a monotone quantity for the Ricci flow, and is defined in the following way. For a function \( f \in C^\infty(M) \) and real number \( \tau > 0 \), Perelman’s \( W \)-functional is defined by

\[
W(g, f, \tau) = \frac{1}{(4\pi \tau)^{n/2}} \int_M \left\{ \tau (|\nabla f|^2 + R_g) + f - n \right\} e^{-f} d\text{vol}_g. \tag{2.1}
\]

The Perelman entropy \( \mu(g, \tau) \) is

\[
\mu(g, \tau) = \inf \left\{ W(g, f, \tau) : \frac{1}{(4\pi \tau)^{n/2}} \int_M e^{-f} d\text{vol}_g = 1 \right\}. \tag{2.2}
\]

This quantity can be viewed as the optimal constant in a log-Sobolev inequality on \((M, g)\) at scale \( \tau^{1/2} \); on Euclidean space, Gross’s log-Sobolev inequality [Gro75] is equivalent to the fact that \( \mu(g_{\text{eucl}}, \tau) = 0 \) for every \( \tau > 0 \). An important feature of the Perelman entropy is that it is extremized by Euclidean space: for any complete Riemannian manifold \((M, g)\) with bounded curvature, \( \mu(g, \tau) \leq 0 \) for every \( \tau > 0 \), and equality holds for some \( \tau > 0 \) if and only if \((M, g)\) is isometric to Euclidean space. We will assume that, for a given \( \delta > 0 \), the Perelman entropy is \( \delta \)-close to that of Euclidean space for at all scales below two. This is compactly expressed as \( \nu(g, 2) \geq -\delta \), where Perelman’s \( \nu \)-functional is defined by

\[
\nu(g, \tau) = \inf \{ \mu(g, \tilde{\tau}) : \tilde{\tau} \in (0, \tau) \}.
\]

Recall that \((M, g(t))_{t \in (0, T)}\) is a solution to the Ricci flow if \( \partial_t g_t = -2\text{Ric}_g(t) \). The scalar curvature evolves along the Ricci flow as \( (\partial_t - \Delta g(t))R_g(t) = 2|\text{Ric}_g(t)|^2 \), and in particular as a supersolution to the heat equation, its lower bounds are preserved along the flow. This feature, together with its regularizing properties, make the Ricci flow useful tool for studying spaces with lower bounds on scalar curvature; see [LNNb, Bam16, BG19, BG] for instance. The volume form evolves via \( \partial_t d\text{vol}_g(t) = -R_g(t) d\text{vol}_g(t) \) along the Ricci flow. So, if an initial metric \( g(0) \) satisfies \( R_g(0) \geq -\delta \),
then the same lower bound persists and volumes do not expand too much along the flow: \( d\text{vol}_{g(t)} \leq \exp(\delta(t-s))d\text{vol}_{g(s)} \) for all \( s \leq t \). So, provided \( \delta \leq 1/2 \), a Taylor expansion shows that for all \( 0 \leq s \leq t \leq \min\{1,T\} \),

\[
d\text{vol}_{g(t)} \leq \{1 + 2\delta(t-s)\} d\text{vol}_{g(s)}.
\]

(2.3)

The Perelman entropy interacts naturally Ricci flow as well, by design. The following lemma highlights some of the basic Ricci flow facts that will be useful in our setting.

**Lemma 2.1.** Fix \( n \geq 2 \), \( \lambda > 0 \) and \( \epsilon > 0 \). There exists \( \delta = \delta(n,\lambda,\epsilon) \) such that if \((M,g)\) is a complete Riemannian manifold with bounded curvature with \( \nu(g,2) \geq -\delta \), then the smooth Ricci flow \((M,g(t))\) with \( g(0) = g \) exists for \( t \in (0,1] \) and has the scale-invariant curvature estimates

\[
|Rm_{g(t)}| \leq \frac{\lambda}{t} \quad \text{for all} \quad t \in (0,1].
\]

(2.4)

Moreover, for any \( x \in M \) and \( t \in (0,1] \), we may find a diffeomorphism \( \psi : B_{g(t)}(x,16t^{1/2}) \to \Omega \subset \mathbb{R}^n \) such that \( \psi(0) = x \) and

\[
(1 - \epsilon) g_{euc} \leq \psi^* g(t) \leq (1 + \epsilon) g_{euc}
\]

(2.5)

for all \( y \in \Omega \). In particular, for any \( r \in (0,16t^{1/2}) \) we have

\[
(1 - \epsilon) \omega_n r^n \leq \text{vol}_{g(t)}(B_{g(t)}(x,r)) \leq (1 + \epsilon) \omega_n r^n
\]

(2.6)

*Proof.* The uniform existence time and scale invariant curvature estimates (2.4) were proven in [LNNb, Theorem 3.2], and the proof there is essentially from Hein and Naber [HN14]. The proof is a contradiction argument using Shi’s derivative estimates [Shi89] and the rigidity of Euclidean space as a maximizer of the entropy.

Next, Perelman’s no local collapsing theorem implies that balls are noncollapsing below scale \( t^{1/2} \) in the sense that \( \text{vol}_{g(t)}(B_{g(t)}(x,r)) \geq kr^n \) for all \( x \in M \) and \( r \leq t^{1/2} \leq 1 \) for a uniform constant \( k = k(n,\lambda,\delta) \); see [Per02]. Together with the curvature estimates (2.4), this implies that the injectivity radius of \((M,g(t))\) is bounded below by \( i_0 t^{1/2} \) for a number \( i_0 = i_0(n,\delta,\lambda) > 0 \); see [Pet98, Chapter 10, Lemma 53]. A further contradiction argument using the rigidity of Euclidean space for the entropy as in the proof of [LNNb, Theorem 3.2] shows that, that up to decreasing \( \delta \), we may assume that \( i_0 \geq 16 \). In turn, this implies the second part of the lemma, say in normal coordinate charts. Though we won’t directly need it here, it is worth noting that Shi’s derivative estimates actually tell us that \( B_{g(t)}(x,16t^{1/2}) \) is smoothly close to a Euclidean ball. \( \square \)

In view of Lemma 2.1, under the hypotheses of Theorem 1.3 we may assume that the Ricci flow \((M,g(t))\) with \( g(0) = g \) exists for all \( t \in (0,1] \) and \( B_{g(t)}(x,16) \) is smoothly close to a Euclidean ball for any \( x \in M \). To prove Theorem 1.3, then, it suffices prove bi-Hölder and bi-\( W^{1,p} \) estimates for the identity map between \( t = 0 \) and \( t = 1 \). In particular we will need to compare the distance functions along the flow. One direction of this comparison comes essentially for free by combining the scale-invariant curvature estimates (2.4) with the following one-sided distance distortion estimate due to Hamilton. We state it only in the form needed here; see [Ham95, Theorem 17.1] or [CLN06, Lemma 8.33].

**Lemma 2.2 (Hamilton).** Let \((M,g(t))_{t \in [0,1]}\) be a smooth Ricci flow satisfying (2.4). Then for any \( x,y \in M \), and \( 0 \leq s \leq t \leq 1 \) we have

\[
d_{g(t)}(x,y) \geq d_{g(s)}(x,y) - 8\sqrt{(n-1)\lambda t}.
\]

(2.7)

Let us observe that (2.7) implies that for any \( \rho > 0 \) and \( 0 \leq s \leq t \leq 1 \), setting \( C^2 = 64(n-1) \), we have

\[
B_{g(t)}(x,\rho) \subseteq B_{g(s)}(x,\rho + \sqrt{C\lambda t}).
\]

(2.8)
By choosing \( s = 0 \) and \( \lambda \) (hence \( \delta \)) sufficiently small depending on \( \epsilon \), Lemma 2.2 implies
\[
B_{g(t)}(x, \rho) \subset B_{g(0)}(x, (1 + \epsilon)\rho)
\] (2.9)
for any \( \rho \geq t^{1/2}/100 \).

Lemma 2.2 asserts that distances cannot decrease too much along the flow when (2.4) is in force. On the other hand, the evolution of the volume form shows that volumes cannot increase too much along the flow under the lower scalar bound. The interplay between these two estimates implies that under a scalar curvature lower bound, the entropy noncollapsing condition \( \nu(g, 2) \geq -\delta \) implies the volume noncollapsing condition (2.10) at every point.

**Lemma 2.3** (Entropy noncollapsing implies volume noncollapsing). Fix \( n \geq 2 \) and \( \epsilon > 0 \). There exists \( \delta = \delta(n, \epsilon) > 0 \) such that the following holds. Suppose that \((M, g)\) is a complete Riemannian manifold with bounded curvature such that \( R_g \geq -\delta \) and \( \nu(g, 2) \geq -\delta \). Then for every \( r \in (0, 1] \),
\[
\vol_g(B_g(x, r)) \geq (1 - \epsilon)\omega_n r^n.
\] (2.10)
More generally, if \((M, g(t))_{t \in [0, 1]}\) is the Ricci flow with \( g(0) = g \), whose existence is guaranteed by Lemma 2.1, then for every \( t \in [0, 1] \) and \( r \in (0, 1] \),
\[
\vol_{g(t)}(B_{g(t)}(x, r)) \geq (1 - \epsilon)\omega_n r^n.
\] (2.11)

*Proof.* Fix \( t \in [0, 1] \) and \( r \in (0, 1] \). If \( r \leq t^{1/2}, \) then (2.11) is a consequence of (2.6). Next consider the case when \( r \in (t^{1/2}, 1] \). We apply (2.8), taking \( s = t \) and \( t = r^2 \), and \( \rho = r - \sqrt{C\lambda t} \) where \( C \) is the constant in (2.8). Provided \( \lambda \), and hence \( \delta \), is sufficiently small, we find that \( B_{g(r^2)}(x, (1 - \epsilon)r) \subseteq B_{g(t)}(x, r) \). In particular,
\[
\vol_{g(t)}(B_{g(t)}(x, r)) \geq \vol_{g(t)}(B_{g(r^2)}(x, (1 - \epsilon)r)).
\] (2.12)
Then, since \( R \geq -\delta \), by (2.3), we see that
\[
\vol_{g(t)}(B_{g(r^2)}(x, (1 - \epsilon)r)) \geq (1 - \epsilon)\vol_{g(r^2)}(B_{g(r^2)}(x, (1 - \epsilon)r)).
\] (2.13)
We appeal to (2.6) once more to conclude. \( \square \)

Wang shows in [Wan20, Theorem 5.9] that under a lower bound on the Ricci curvature, the local versions of these two conditions are equivalent, and are also equivalent to an almost-Euclidean local isoperimetric constant.

We will use the following elementary lemma that follows from integrating the scale-invariant curvature estimate (2.4) along the Ricci flow; see [LNNb, Lemma 3.8].

**Lemma 2.4.** Fix \( n \geq 2 \) and \( \beta \in (0, 1/4) \). There exists \( \lambda = \lambda(n, \beta) \) small enough such that if \((M, g(t))_{t \in [0, 1]}\) is a Ricci flow satisfying (2.4), then for any \( x \in M \) and \( 0 < s_1 \leq s_2 \leq 1 \), we have
\[
\left(\frac{s_1}{s_2}\right)^\beta g(s_1) \leq g(s_2) \leq \left(\frac{s_1}{s_2}\right)^{-\beta} g(s_1).
\] (2.14)
Consequently, for any \( r > 0 \),
\[
B_{g(s)}(x, rs^{1/2}) \subset B_{g(t)}(x, rt^{1/2}) \quad \text{for all } 0 \leq s \leq t \leq 1.
\]
Moreover, for \( t_0 \in (0, 1), \ r_0 \in (0, 1) \) and \( \epsilon > 0 \) fixed, there is \( \lambda \) small enough such that
\[
B_{g(t_0)}(x, r_0) \subset B_{g(1)}(x, (1 + \epsilon)r_0).
\] (2.15)

Finally, we recall the decomposition theorem from [LNNb, Theorem 5.1] for a Riemannian manifold with almost-Euclidean lower bounds on scalar curvature and Perelman entropy, which decomposes a ball \( B_{g(1)}(x, 8) \) into a countable union of sets \( \{G_k\}_{k \in \mathbb{N}} \) with volumes decaying geometrically
in $k$ and on which the metric tensors $g(0)$ and $g(1)$ are pointwise comparable up to $(1 \pm \epsilon)^k$-multiplicative constants.

**Lemma 2.5 (Decomposition theorem).** For each $\epsilon > 0$ there exists $\delta = \delta(n, \epsilon) > 0$, such that the following holds. Let $(M, g(t))_{t \in [0,1]}$ be a complete Ricci flow with bounded curvature with $g = g(0)$ satisfying (1.3). Fix $x_0 \in M$. The ball $B_{g(1)}(x_0, 8)$ can be decomposed into good sets $\mathcal{G}^k$ and a bad set $\mathcal{A}$ in the following way:

$$B_{g(1)}(x_0, 8) = \bigcup_{k=1}^{\infty} \mathcal{G}^k \cup \mathcal{A}$$

where

1. $\text{vol}_{g(0)}(\mathcal{A}) = 0$.
2. For all $x \in \mathcal{G}^k$ and for all $s, t \in (0, 1]$, the metrics satisfy

$$(1 - \epsilon)g(s) \leq g(t) \leq (1 + \epsilon)g(s)$$

3. For each $k \geq 2$, we have $\text{vol}_{g(0)}(\mathcal{G}^k) \leq (1 + \epsilon)^{k-1}k^{-1}$.
4. For each $k \in \mathbb{N}$, let $\mathcal{A}^k = B_{g(1)}(x_0, 8) \setminus \bigcup_{\ell=1}^{k} \mathcal{G}^\ell$ be the complement of the first $k$ good sets.

There is a countable collection $\mathcal{C}^k$ and a mapping $y \mapsto t_y$ for $y \in \mathcal{C}^k$ such that

$$\mathcal{A}^k \subseteq \bigcup_{y \in \mathcal{C}^k} B_{g(t_y)}(y, 12t_y^{1/2}) \quad \text{with} \quad \sum_{y \in \mathcal{C}^k} t_y^{n/2} \leq \epsilon^k.$$  

### 3. Epsilon Regularity

In this section, we prove Theorem 1.3. To begin, we show that if $(M, g)$ satisfies the assumptions of Theorem 1.3 and $(M, g(t))_{t \in [0,1]}$ is the Ricci flow with $g(0) = g$ (whose existence is guaranteed by Lemma 2.1), then

$$B_{g(0)}(x, 1 - \epsilon) \subset B_{g(1)}(x, 1)$$

provided $\delta$ is chosen sufficiently small. Once this is shown, we can apply this and the opposite containment (2.9) and iterate at all points and scales to show (1.5). Moreover, the containment (3.1) will allow us to decompose the ball $B_{g(0)}(x, 1)$ according to Lemma 2.5 to prove the $W^{1,p}$ estimates (1.6). While all of the results in section 2 hold under only the lower bounds on scalar curvature and entropy, the proofs in this section necessarily make use of the upper bounds (1.4) on the volumes of balls: examples in [LNNb, LNNa] show the containment (3.1) is false in the absence of assumption (1.4), even with $1 - \epsilon$ replaced by a tiny radius $\epsilon > 0$.

The containment (3.1) follows from the distance distortion estimates shown in [Wan20], which in turn call on results from [TW15]. Here we give a slightly different proof, which combines two ingredients: lower density estimates and volume control. The lower density estimate, Proposition 3.1 below, says that if (3.1) fails to hold, i.e. $B_{g(0)}(x, 1 - \epsilon)$ is not entirely contained in $B_{g(1)}(x, 1)$, then there is a $g(0)$ ball of definite size that lies inside the slightly bigger ball $B_{g(0)}(x, 1 - \epsilon/2)$ and outside the slightly smaller ball $B_{g(1)}(x, 1 - \epsilon/2)$.

**Proposition 3.1.** Fix $n \geq 2$ and $\epsilon > 0$. There exist $\delta = \delta(n, \epsilon) > 0$ such that the following holds. Let $(M, g)$ satisfy the hypotheses of Theorem 1.3. Then for any $x \in M$ and $y \in B_{g(0)}(x, 1 - \epsilon) \setminus B_{g(1)}(x, 1)$, we have

$$B_{g(0)}(y, \epsilon/20) \subset B_{g(0)}(x, 1 - \epsilon/2) \setminus B_{g(1)}(x, 1 - \epsilon/2).$$
So, if (3.1) fails for some \( x \), then a \( g(0) \) ball of definite radius—thus of definite \( g(0) \) volume by Lemma 2.3—is contained in a \( g(0) \) ball of radius \( \rho_0 = 1 - \epsilon/2 \) and the complement of a \( g(1) \) ball of the same radius and center. This possibility is ruled out by the volume control of Proposition 3.2, which says that the set difference between a \( g(0) \) ball and a \( g(1) \) ball with the same radius and center must have very small volume for sufficiently small \( \delta \). This fact strongly uses the almost-Euclidean volume assumption (1.4), as well as a lemma from [LNNb] letting us compare \( g(0) \) and \( g(1) \) volumes of a fixed set.

**Proposition 3.2.** Fix \( n \geq 2 \) and \( \eta > 0 \). There exists \( \delta = \delta(n, \eta) \) such that if \((M, g)\) satisfies the hypotheses of Theorem 1.3, then for any \( x \in M \) and \( \rho_0 \in [1/5, 1] \),

\[
\text{vol}_{g(0)}(B_{g(0)}(x, \rho_0) \setminus B_{g(1)}(x, \rho_0)) \leq \eta.
\]  

(3.2)

We prove Propositions 3.1 and 3.2 in sections 3.1 and 3.2 respectively, and complete the proof of Theorem 1.3 in section 3.3.

### 3.1. Lower density estimate.**

To prove Proposition 3.1, we first prove the rough containment \( B_{g(0)}(x, 1) \subset B_{g(1)}(x, 5) \). Here, we crucially use the control (1.4) on volumes of balls, although in this step it is not essential that the content is almost-Euclidean. The proof uses a known Ricci flow argument (see for instance [CW12, BZ17]) estimating the number of \( g(t) \)-balls needed to cover \( g(0) \)-geodesics, using the volume bounds (1.4) and noncollapsing of Lemma 2.3.

**Lemma 3.3.** Fix \( n \geq 2 \). There exist \( \delta = \delta(n) > 0 \) such that the following holds. Let \((M, g)\) satisfy the hypotheses of Theorem 1.3 and let \((M, g(t))_{t \in (0, 1]}\) be the Ricci flow with \( g(0) = g \). For each \( t \in (0, 1] \) and \( x, y \in M \) with \( d_{g(0)}(x, y) \geq t^{1/2} \),

\[
d_{g(t)}(x, y) \leq 4d_{g(0)}(x, y)
\]

(3.3)

and

\[
B_{g(0)}(x, t^{1/2}) \subseteq B_{g(t)}(x, 5t^{1/2}).
\]

(3.4)

**Proof.** Fix \( t \in (0, 1] \) and fix \( x, y \in M \) satisfying \( d_{g(0)}(x, y) \geq t^{1/2} \), and set \( d_0 = d_{g(0)}(x, y) \).

**Case 1:** \( d_0 \leq 1/2 \). Let \( \gamma \) be a minimizing geodesic from \( x \) to \( y \) with respect to the metric \( g(0) \). Consider a maximal subset \( \{y_i\}_{i=1}^N \) of \( \text{Im}(\gamma) \) such that the balls \( B_{g(t)}(y_i, d_0) \) are pairwise disjoint. In this way, the collection \( \{B_{g(t)}(y_i, 2d_0)\}_{i=1}^N \) is a covering of \( \text{Im}(\gamma) \) and thus

\[
d_{g(t)}(x, y) \leq L_{g(t)}(\gamma) \leq 4d_0 N.
\]

(3.5)

Here \( L_{g(t)}(\gamma) \) denotes the length of \( \gamma \) with respect to the metric \( g(t) \). We will show that \( N = 1 \) provided \( \delta \) is chosen sufficiently small. Indeed, let \( \epsilon = \epsilon(n) > 0 \) be a fixed small number to be specified below. Taking \( \delta \), small enough depending on \( \epsilon \) and \( n \), we find from (2.9) that for each \( i \in \{1, \ldots, N\} \),

\[
B_{g(t)}(y_i, d_0) \subseteq B_{g(0)}(y_i, (1 + \epsilon)d_0).
\]

(3.6)

In particular, since the balls on the left-hand side of (3.6) are pairwise disjoint,

\[
\sum_{i=1}^N \text{vol}_{g(t)}(B_{g(t)}(y_i, d_0)) \leq \text{vol}_{g(t)}(B_{g(0)}(x, (1 + \epsilon)d_0)).
\]

(3.7)

The lower bound on scalar curvature and (2.3) ensure that \( d\text{vol}_{g(t)} \leq (1 + \epsilon)d\text{vol}_{g(0)} \) for all \( t \in (0, 1] \), provided we choose \( \delta > 0 \) small enough in terms of \( \epsilon \). Therefore, keeping in mind that \( d_0 \leq 1/2 \) so
(1 + \epsilon) d_0 < 1$, we can apply the volume growth assumption (1.4) to bound right-hand side of (3.7) above:

\[
\text{vol}_{g(t)} \left( B_{g(0)}(x, (1 + \epsilon)d_0) \right) \leq (1 + \epsilon) \text{vol}_{g(0)} \left( B_{g(0)}(x, (1 + \epsilon)d_0) \right) \leq \omega_n (1 + \epsilon)^{n+1} d_0^n. \tag{3.8}
\]

On the other hand, up to further decreasing $\delta$ depending on $n$ and $\epsilon$, Lemma 2.3 tells us the balls $B_{g(t)}(y_i, d_0)$ on the left-hand side of (3.7) each have $g(t)$-volume at least $(1 - \epsilon)\omega_n d_0^n$. Using this and (3.8) to bound the left- and right-hand sides of (3.7) respectively, we have

\[
N(1 - \epsilon)\omega_n d_0^n \leq \omega_n (1 + \epsilon)^{n+1} d_0^n.
\]

Dividing through by $\omega_n d_0^n$ and taking $\epsilon > 0$ small enough depending on $n$, we determine that $N < 2$. So, recalling (3.5) and the definition of $d_0$, we conclude that (3.3) holds in this case.

**Case 2: $d_0 \geq 1/2$.** Let $\gamma : [0, d_0] \to M$ be a minimizing geodesic from $x$ to $y$ with respect to the metric $g(0)$ parameterized by arclength. Let $\rho = \frac{d_0}{[2d_0]}$. Note that $\rho \in [1/4, 1/2]$, so in particular $4\rho \geq t^{1/2}$ for any $t \in (0, 1)$. For $i = 0, \ldots, \lfloor 2d_0 \rfloor$, set $x_i = \gamma(i\rho)$. By applying Case 1 to the $g(0)$-geodesic segments from $x_{i-1}$ to $x_i$, we find that

\[
d = \sum_{i=1}^{\lfloor 2d_0 \rfloor} d_{g(0)}(x_{i-1}, x_i) \geq \frac{1}{4} \sum_{i=1}^{\lfloor 2d_0 \rfloor} d_{g(t)}(x_{i-1}, x_i) \geq \frac{1}{4} d_{g(t)}(x, y). \tag{3.9}
\]

This completes the proof of (3.3).

To see how the containment of balls (3.4) follows, fix any $y \in B_{g(0)}(x, t^{1/2})$. Again letting

\[
d_0 = d_{g(0)}(x, y) \quad \text{(so that now $d_0 < t^{1/2}$)},
\]

we apply (3.3) at the time slice $d_0^2$ to see that $y \in B_{g(d_0)}(x, 4(1 + \epsilon)d_0)$. Next, by Lemma 2.4, we have

\[
B_{g(d_0)}(x, 4(1 + \epsilon)d_0) \subseteq B_{g(t)}(x, 4(1 + \epsilon)^2 t^{1/2})
\]

since $d_0^2 \leq t$. Choosing $\epsilon > 0$ small enough so that $4(1 + \epsilon)^2 \leq 5$ completes the proof. \hfill \Box

Now we use Lemma 3.3 to prove the lower density estimate.

**Proof of Proposition 3.1.** Suppose that we may find some $y$ as in the statement of the proposition, i.e. such that $d_{g(0)}(y, x) \leq 1 - \epsilon$ and $d_{g(1)}(y, x) > 1$. We claim that

\[
B_{g(0)}(y, \epsilon/20) \subset B_{g(0)}(x, 1 - \epsilon/2) \tag{3.11}
\]

and

\[
B_{g(0)}(y, \epsilon/20) \subset M \setminus B_{g(1)}(x, 1 - \epsilon/2). \tag{3.12}
\]

The first containment (3.11) is immediate from the triangle inequality: for $z \in B_{g(0)}(y, \epsilon/20),$

\[
d_{g(0)}(z, y) \leq d_{g(0)}(z, y) + d_{g(0)}(y, x) \leq \epsilon/20 + (1 - \epsilon) \leq 1 - \epsilon/2.
\]

Toward showing (3.12), we claim that for $\delta = \delta(n, \epsilon)$ sufficiently small, we have

\[
B_{g(0)}(x, \epsilon/20) \subseteq B_{g(1)}(x, \epsilon/2) \tag{3.13}
\]

for each $x \in M$. Indeed, let $t_0 = \epsilon^2/400$. Applying Lemma 3.3 at scale $t_0$ tells us that $B_{g(0)}(x, \epsilon/20) \subset B_{g(t_0)}(x, \epsilon/4)$. Next, by Lemma 2.4, we can choose $\lambda$ and thus $\delta$ sufficiently small depending on $t_0$ (thus $\epsilon$) and $n$ to find that $B_{g(t_0)}(x, \epsilon/4) \subset B_{g(1)}(x, \epsilon/2)$ for every $x \in M$. This yields (3.13).

So, thanks to (3.13), to show (3.12) it suffices to show that $B_{g(1)}(y, \epsilon/2) \subset M \setminus B_{g(1)}(x, 1 - \epsilon/2)$. Again, this just follows from the triangle inequality: for $z \in B_{g(1)}(y, \epsilon/2),$ we have

\[
d_{g(1)}(z, x) \geq d_{g(1)}(x, y) - d_{g(1)}(y, z) \geq 1 - d_{g(1)}(z, y) \geq 1 - \epsilon/2.
\]

This completes the proof. \hfill \Box
3.2. Volume control. Using only the first iteration of the decomposition theorem, Lemma 2.5, i.e. just splitting $B_{g(1)}(x, 8)$ into the first “good set” $G_1$ and its complement of small volume, we have the following volume control lemma.

**Lemma 3.4.** Fix $n \geq 2$ and $\eta > 0$. There exists $\delta = \delta(n, \eta)$ such that, for any $\Omega \subset M$ with $\text{diam}_{g(1)}(\Omega) \leq 8$,

$$|\text{vol}_{g(0)}(\Omega) - \text{vol}_{g(1)}(\Omega)| \leq \eta.$$  

This lemma is one of the tools in the proof of Proposition 3.2.

**Proof of Proposition 3.2.** Let $V_0 = \text{vol}_{g(0)}(B_{g(0)}(x, \rho_0) \setminus B_{g(1)}(x, \rho_0))$, so we aim to show that $V_0 \leq \eta$. To this end, we first slightly enlarge the $g(0)$ ball appearing on the left-hand side of (3.2): thanks to the containment (2.9) and the assumption $\rho_0 \geq 1/5$, we can take $\delta = \delta(n, \eta)$ sufficiently small so that $B_{g(1)}(x, \rho_0) \subset B_{g(0)}(x, (1 + \delta)\rho_0)$. So, letting $V_0$ denote the left-hand side of (3.2), we have

$$V_0 \leq \text{vol}_{g(0)}(B_{g(0)}(x, (1 + \eta)\rho_0) \setminus B_{g(1)}(x, \rho_0)) = \text{vol}_{g(0)}(B_{g(0)}(x, (1 + \eta)\rho_0)) - \text{vol}_{g(0)}(B_{g(1)}(x, \rho_0)).$$

We bound the first term on the right-hand side using the assumption (1.4) of an almost-Euclidean upper bound for volumes of $g(0)$ balls:

$$\text{vol}_{g(0)}(B_{g(0)}(x, (1 + \eta)\rho_0)) \leq (1 + \delta)(1 + \eta)^n \omega_n \rho_0^n.$$

To bound the second term below, we apply Proposition 3.4, allowing us to compare $g(0)$ and $g(1)$ volumes, followed by the volume noncollapsing of Lemma 2.3:

$$\text{vol}_{g(0)}(B_{g(1)}(x, \rho_0)) \geq (1 - \eta)\text{vol}_{g(1)}(B_{g(1)}(x, \rho_0)) \geq (1 - 2\eta)\omega_n \rho_0^n.$$

Putting these facts together we see that

$$V_0 \leq \omega_n \rho_0^n ((1 + \delta)(1 + \eta)^n - (1 - 2\eta)),$$

$$\leq \omega_n \rho_0^n C_n \eta = C_n \eta.$$

Here we have assumed without loss of generality that $\delta \leq \eta$ and have used that $\rho_0 \leq 1$. Repeating this argument with $\eta' = \eta/C_n$ proves the proposition. \hfill $\square$

3.3. Conclusion. Now we prove Theorem 1.3.

**Proof of Theorem 1.3.** Let $(M, g(t))_{t \in [0, 1]}$ be the Ricci flow with $g(0) = g$, whose existence is guaranteed by Lemma 2.1. Fix $x \in M$.

**Step 1:** First, we show (3.1), that is, we claim that

$$B_{g(0)}(x, 1 - \epsilon) \subset B_{g(1)}(x, 1),$$

for $\delta$ sufficiently small depending on $n$ and $\epsilon$. Let $\eta > 0$ be a fixed number depending on $n$ and $\epsilon$ to be specified below. Choose $\delta = \delta(n, \epsilon, \eta)$ small enough according to Propositions 3.1 and 3.2 and Lemma 3.3. Set $\rho_0 = 1 - \epsilon/2$. If $\rho_0 < 1/5$, the claim follows from Lemma 3.3, so we assume that $\rho_0 \geq 1/5$. Suppose there is some point $y \in B_{g(0)}(x, 1 - \epsilon)$ with $y \notin B_{g(1)}(x, 1)$. The lower density estimate of Proposition 3.1 then implies that

$$B_{g(0)}(y, \epsilon/20) \subset B_{g(0)}(x, \rho_0) \setminus B_{g(1)}(x, \rho_0),$$

and thus Proposition 3.2 implies that

$$\text{vol}_{g(0)}(B_{g(0)}(y, \epsilon/20)) \leq 100\eta$$  \hfill (3.14)

by containment. On the other hand, by Lemma 2.3, the right-hand side of this expression is bounded below by $\omega_n \epsilon^n/21^n$ for $\delta = \delta(n, \epsilon) > 0$ small enough. Choosing $\eta \leq \omega_n \epsilon^n/21^n$, we see that
such a point \( y \) cannot exist and thus the claim holds. Since all hypotheses are preserved under rescaling the metric \( g \mapsto t^{-1} g \) for \( t \in (0,1] \), we note that this claim shows that
\[
B_{g(0)}(x, (1-\epsilon)t^{1/2}) \subseteq B_{g(t)}(x, t^{1/2})
\]
for all \( t \in (0,1] \) and \( x \in M \); up to further decreasing \( \delta \) we may assume this holds for all \( t \in (0,2] \).

**Step 2:** Together step 1 and (2.9) tell us that, up to further decreasing \( \delta > 0 \), we have
\[
B_{g(t)}(x, (1-\epsilon)t^{1/2}) \subseteq B_{g(0)}(x, t^{1/2}) \subseteq B_{g(t)}(x, (1+\epsilon)t^{1/2})
\]  
(3.15)
for all \( x \in M \) and \( t \in (0,2] \). By Lemma 2.1, we have a smooth diffeomorphism \( \psi : B_{g(1)}(x,16) \to \Omega \subseteq \mathbb{R}^n \), with inverse \( \phi = \psi^{-1} \) such that \( \psi(x) = 0 \) and
\[
(1-\epsilon)g_{euc} \leq \phi^*g(1) \leq (1+\epsilon)g_{euc}
\]  
(3.16)
for all \( x \in \Omega \), as long as \( \lambda \) (and hence \( \delta \)) has been chosen to be sufficiently small depending on \( \epsilon \) and \( n \). Set \( U = \psi(B_{g(0)}(x,1)) \). By (3.15) with \( t = 1 \) and (3.16), we have
\[
B(0,1-\epsilon) \subseteq U \subseteq B(0,1+\epsilon).
\]  
(3.17)

Let us establish the bi-Hölder estimates (1.5), which is standard from (3.15). Thanks to (3.16), it suffices to show that the identity map is a bi-Hölder between \( g \) and \( g(1) \) satisfying
\[
(1-\epsilon)d_g(y,z)^{1/\alpha} \leq d_g(1)(y,z) \leq (1+\epsilon)d_g(y,z)^{1/\alpha}
\]  
(3.18)
for all \( y,z \in B_g(x,1) \). To this end, fix any such \( y,z \) and let \( d = d_g(y,z) \leq 2 \). By (3.15) at scale \( t = d^2 \), we have
\[
(1-\epsilon)d \leq d_g(1)(x,y) \leq (1+\epsilon)d.
\]  
(3.19)
Let \( 2\beta = 1 - \alpha \). Up to further decreasing \( \lambda \) (and thus \( \delta \)) to comply with Lemma 2.4, we see that (2.14) yields
\[
(1-\epsilon)d^{2\beta} d_g(1)(x,y) \leq d_g(1)(x,y) \leq (1+\epsilon)d^{-2\beta} d_g(1)(x,y).
\]  
(3.20)
Combining these two estimates (3.19) and (3.20) establishes (3.18). We have thus shown (1.5).

Finally, we can repeat the proof of theorem 1.11 in [LNNb, Section 6] identically, with the key improvement that the decomposition of Lemma 2.5 now holds on \( B_g(0,1) \) thanks to step 1, to conclude the \( W^{1,p} \) estimates (1.6).

\[
\square
\]

4. Limit spaces

In this section we establish Theorem 1.4. We first prove the compactness and properties (1) and (2) of Theorem 1.4 in section 4.1, then introduce two additional lemmas in section 4.2 before proving properties (3) and (4) in section 4.3.

4.1. Compactness, topological structure, and measure of balls. We start by proving that sequences of pointed Riemannian manifolds as in the statement of Theorem 1.4 have pointed measured Gromov-Hausdorff limits, that the limit space \( X \) is a topological manifold, and that the measure of balls up to scale one in the limit space are almost equal to the volume of Euclidean balls of the same radius.

**Proof of Theorem 1.4.** Take \( \delta = \delta(n,\epsilon) > 0 \) as in Theorem 1.3. Up to replacing each \( g_i \) by the rescaled metric \( \rho_0^{-2} g_i \) where \( \rho_0^2 = \min\{\delta/C_0, \tau_0/2, r_0^2/4\} \), we may assume that \( C_0 = \delta, \tau_0 = 2 \), and \( r_0 = 2 \) in (1.7). In this way, each \( (M_i, g_i, x_i) \) satisfies the hypotheses of Theorem 1.3. At various points in the proof, we will pass to subsequences, which we will not relabel.
Step 0. We first show that the sequence \( \{(M_i, g_i, x_i, d\nu_{g_i})\} \) has a convergent subsequence in the pointed measured Gromov-Hausdorff topology. At a fixed \( y \in M_i \), we let \( \text{Cov}_R(y) \) denote the minimum number of balls of radius \( r \) needed to cover \( B_{g_i}(y, R) \). As a direct consequence of Theorem 1.3, we find that \( \text{Cov}_1(r) \) is bounded above by a function \( N_1(r) = N_1(r, n, \epsilon, \delta) \). Furthermore, we have assumed that \( \text{vol}_{g_i}(B_{g_i}(y, r)) \) is bounded above by a function \( V(r) = V(r, n, \epsilon, \delta) \) for each \( r \leq 1 \). As this holds at every point, a simple induction argument then establishes that \( \text{Cov}_R(y) \) is bounded above by a function \( N_R(r) = N_R(r, n, \epsilon, \delta) \) for \( R \geq 1 \) as well, and consequently, \( \text{vol}_{g_i}B_{g_i}(y, R) \) is bounded above by a function \( V(R) = V(R, n, \epsilon, \delta) \) for all \( R \geq 1 \) as well. Hence, the sequence \( \{(M_i, g_i, x_i, d\nu_{g_i})\} \) is precompact in the pointed measured Gromov-Hausdorff sense and a subsequence converges to a proper pointed metric measure space \( (X, d, x_\infty, m) \); see for instance [HKST15, Theorem 11.4.7].

Step 1. Next we establish the manifold structure of \( X \) by constructing an atlas of charts, proving part (1) of the theorem. We follow Petersen’s presentation of Cheeger’s fundamental theorem of convergence theory, [Pet98, Chapter 10, Theorem 72]. For each fixed \( i \), Theorem 1.3 establishes the existence of an atlas of charts \( \phi_{i\ell} : B_{g_{guc}}(0, 1) \rightarrow U_{i\ell} \subset M_i \), where each \( \phi_{i\ell} \) is a bi-Hölder homeomorphism with uniform bounds on the bi-Hölder norms. Without loss of generality, we may assume that the index set \( \{\ell\} \) is the same for all \( i \), and that we have indexed the charts in such a way that \( x_i \in U_{i1} \), and that \( B(p, R) \) is covered by the first \( N_R(1) \) charts. For each \( \ell \), the uniform bi-Hölder estimates ensure that, up to a subsequence, \( \{\phi_{i\ell}\} \) converges to a bi-Hölder map \( \phi_\ell : B_{g_{guc}}(0, 1) \rightarrow U_\ell \subset X \). In particular, \( \phi_\ell \) is a homeomorphism. Up to selecting a diagonal subsequence, this convergence occurs for all \( \ell \in \mathbb{N} \). Finally, it is easy to check from the Gromov-Hausdorff convergence that every \( x \in X \) is contained in \( U_\ell \) for some \( \ell \). Therefore, the collection of maps \( \{\phi_\ell\} \) provides an atlas of topological charts for \( X \).

Step 2. We now show the bound \((1.8)\) for the \( m \) measure of balls to establish part (2) of the theorem. The initial rescaling makes \( r_0 = 1 \), and up to further rescaling, it suffices to take \( r = 1 \) in \((1.8)\). Any ball \( B_\infty := B_g(x, 1) \subset X \) is the Gromov-Hausdorff limit of balls \( B_i := B_{g_i}(x_i, 1) \subset (M_i, g_i) \), and as in the previous step comes equipped with a bi-Hölder map \( \phi : B_{g_{guc}}(0, 1) \rightarrow B_\infty \) arising as the limit of the maps \( \phi_i : B_{g_{guc}}(0, 1) \rightarrow B_i \) of Theorem 1.3. We denote by \( \psi_i \) and \( \psi \) the inverses of \( \phi_i \) and \( \phi \) respectively. We claim that

\[
m(B_\infty) = \lim_{i \to \infty} \text{vol}_{g_i}(B_i). \tag{4.1}
\]

Then \((1.8)\) follows immediately from \((4.1)\), because assumption \((1.7)\) and Lemma 2.3 ensure that \((1 - \epsilon)\omega_n \leq \text{vol}_{g_i}(B_i) \leq (1 + \delta)\omega_n \). To prove \((4.1)\), note that (up to a subsequence) the map \( F_i = \phi \circ \psi_i : B_i \rightarrow B_\infty \) is a \( 1/i \) Gromov-Hausdorff approximation. So, for a fixed function \( f \in C_c(B_\infty) \), we have \( \lim_{i \to \infty} \int_{M_i} f \circ F_i \text{dvol}_{g_i} \rightarrow \int_X f \text{d}m \) from the weak convergence of measures. Take a sequence of functions \( f_j \in C_c(B_\infty) \) converging in \( L^1(X; m) \) to the characteristic function of \( B_\infty \). We have

\[
\lim_{j \to \infty} \lim_{i \to \infty} \int_{M_i} f_j \circ F_i \text{dvol}_{g_i} = \lim_{j \to \infty} \int_X f_j \text{d}m = m(B_\infty). \tag{4.2}
\]

Now, we claim that the integrals on the left-hand side are uniformly bounded with respect to \( i \) and \( j \), so we may exchange the limits. We can assume that \( f_j \leq \chi_{B_\infty} \), so, letting \( \nu_i := (\psi_i)_*\mu_i \) for \( d\mu_i = \text{dvol}_{g_i} \), be a sequence of measures defined on \( B_{g_{guc}}(0, 1) \), it suffices to show that \( \nu_i(B_{g_{guc}}(0, 1)) \) is uniformly bounded in \( i \). This fact then follows directly from Lemma 2.1 and the volume control of Lemma 3.4. So, we may exchange order of the limits with respect to \( i \) and \( j \) in \((4.2)\). Next, applying the dominated convergence theorem and recalling the definition of \( F_i \), we find that

\[
\lim_{i \to \infty} \lim_{j \to \infty} \int_{M_i} f_j \circ F_i \text{dvol}_{g_i} = \lim_{i \to \infty} \text{vol}_{g_i}(F^{-1}_i(B_\infty)) = \lim_{i \to \infty} \text{vol}_{g_i}(B_i). \tag{4.3}
\]
Together (4.2) and (4.3) imply (4.1). We have thus proven the pointed measured Gromov-Hausdorff compactness part of Theorem 1.4 and the properties (1) and (2) of the limiting pointed metric measure spaces.

4.2. Intermediate lemmas. Toward proving the remaining two properties (3) and (4) of limit spaces in Theorem 1.4, we first prove two intermediate lemmas. The first lemma will directly lead to property (3):

**Lemma 4.1.** Fix $\epsilon > 0$, $\epsilon' > 0$ and $r_0 > 0$. Let $(X,d)$ be a locally compact separable metric space, and let $m$ be a Radon measure on $X$ satisfying

$$(1 - \epsilon)\omega_n r^n \leq m(B_d(x,r)) \leq (1 + \epsilon')\omega_n r^n$$

for every $B_d(x,r) \subset B_d(x_0,r_0)$. Then $m$ and $\mathcal{H}^n$ are mutually absolutely continuous in $B_d(x_0,r_0)$, and $m = f\mathcal{H}^n$ with $1 - \epsilon \leq f \leq 1 + \epsilon'$.

**Proof.** We show that for any $m$-measurable set $\Omega \subseteq B_d(x_0,r_0)$, we have

$$(1 - \epsilon)\mathcal{H}^n(\Omega) \leq m(\Omega) \leq (1 + \epsilon')\mathcal{H}^n(\Omega).$$

First we prove the upper bound in (4.5). Since $m$ is a Radon measure, it suffices to assume that $\Omega$ is compact, and hence $\Omega \subseteq B_d(x_0,r_0 - \delta_0)$ for some $\delta_0 > 0$. Fix $\delta < \delta_0$. From the definition of Hausdorff measure, we may find a covering $\{\Omega_{\ell}\}_{\ell=1}^{\infty}$ of $\Omega$ with $r_\ell := \text{diam}(\Omega_{\ell})/2 \leq \delta$ and such that

$$\mathcal{H}^n(\Omega) \geq \omega_n \sum_{\ell=1}^{\infty} r_\ell^n - \delta.$$  

For each $\ell$, the set $\Omega_{\ell}$ is contained in $B_d(x_\ell,r_\ell)$ for some $x_\ell \in B(x_0,r_0)$, and thus $\{B_d(x_\ell,r_\ell)\}$ is a covering of $\Omega$ as well. From the second inequality in (4.4), we thus have

$$\omega_n \sum_{\ell=1}^{\infty} r_\ell^n - \delta \geq \frac{1}{1 + \epsilon'} \sum_{\ell=1}^{\infty} m(B_d(x_\ell,r_\ell)) - \delta \geq \frac{1}{1 + \epsilon'} m(\Omega) - \delta.$$  

Taking $\delta \to 0$ proves the upper bound in (4.5).

Now we show the lower bound in (4.5). As $m$ is a Radon measure, it suffices to consider $\Omega$ open. Fix $\delta > 0$ and let $B = \{B_d(x,r) : B_d(x,r) \subset \Omega, r \leq 2\delta\}$, which is a covering of $\Omega$. We have assumed $X$ is locally compact and separable and $m$ is doubling in $B_d(x_0,r_0)$ by (4.4). So, by [Sim83, Remark 4.5(1)], $B_d(x_0,r_0)$ has the symmetric Vitali property with respect to $m$, in other words we may find a countable pairwise disjoint subcollection $B' = \{B_d(x_\ell,r_\ell)\} \subset B$ covering $\Omega$ up to an $m$-negligible set. Therefore, applying the first inequality in (4.4), we have

$$m(\Omega) = \sum_{\ell=1}^{\infty} m(B_d(x_\ell,r_\ell)) \geq (1 - \epsilon)\omega_n \sum_{\ell=1}^{\infty} r_\ell^n \geq (1 - \epsilon)\mathcal{H}^n(\Omega).$$

Taking $\delta \to 0$ concludes the proof of the lower bound in (4.5) and thus of the lemma. \(\square\)

In the next lemma, we let $(M,g(t))_{t \in [0,1]}$ be the Ricci flow starting from $g$, whose existence is guaranteed by Lemma 2.1. Thanks to (the proof of) Theorem 1.3, we know in particular that $B_g(x,2) \subset B_{g(1)}(x,8)$ for any $x \in M$ and so the decomposition of Lemma 2.5 applies to $B_g(x,2)$. We use the notation $\mathcal{G}^k$ and $\mathcal{A}^k$ for the $k$th good and bad sets in Lemma 2.5, and can always assume they are intersected with $B_g(x,1)$.

The idea of Lemma 4.2 below is that, when restricted to the set $\mathcal{G}^k$ in Lemma 2.5, the identity map from $(B_g(x,1),g(0))$ to $B_g(x,1),g(1))$ is $(1 + \epsilon)^k$ bi-Lipschitz. In turn, this implies that the map $\psi$ in Theorem 1.3 is a $(1 + 2\epsilon)^k$ bi-Lipschitz map when restricted to the set $\mathcal{F}_k = \cup_{\ell=1}^{k} \mathcal{G}^\ell$.
by Lemma 2.1. In fact, in order to pass these Lipschitz maps to the limit toward proving the rectifiability of limit spaces, we need to extend this bi-Lipschitz property to some of the points outside of $G^k$. To this end, and using the notation of Lemma 2.5, let

$$r_k(x) = \begin{cases} 0 & \text{if } x \in F_k \\ \max\{l_y^{1/2} : y \in C^k \text{ and } x \in B_{g(t_\alpha)}(y, 12l_y^{1/2})\} & \text{else.} \end{cases}$$

(4.9)

**Lemma 4.2.** Fix $n \geq 2$ and $\epsilon > 0$. There exists $\delta = \delta(n, \epsilon) > 0$ such that the following holds. Fix $(M, g)$ satisfying the assumptions of Theorem 1.3 and $x_0 \in M$. Fix $k \in \mathbb{N}$ and let $r_k$ be as defined in (4.9). For any pair of points $x_1, x_2 \in B_g(x_0, 1)$ such that $d_{g(0)}(x_1, x_2) \geq \epsilon \max\{r_k(x_1), r_k(x_2)\}$, we have

$$(1 - \epsilon)^k d_{g(0)}(x_1, x_2) \leq d_{g(1)}(x_1, x_2) \leq (1 + \epsilon)^k d_{g(0)}(x_1, x_2).$$

(4.10)

**Proof.** Choose $\delta = \delta(n, \epsilon) > 0$ small enough to apply Theorem 1.3 (for any choice of $\alpha, p$) and Lemma 2.5. Let $d = d_{g(0)}(x_1, x_2)$. We prove the case when $k = 1$; the case $k \geq 1$ then follows by induction as in the proof of Lemma 2.5 (see [LNNb, Theorem 5.1]). First, we apply the distance distortion estimates (3.15) at scale $d^2$ with $\epsilon/2$ in place of $\epsilon$ (by further decreasing $\delta$) to see that

$$(1 - \epsilon/2)d \leq d_{g(\bar{d})}(x_1, x_2) \leq (1 + \epsilon/2)d.$$  

(4.11)

Now, if $r_k(x_1) = r_k(x_2) = 0$, let $\bar{y} = x_1$. Otherwise, suppose without loss of generality that $\bar{r} := r_k(x_1) \geq r_k(x_2)$ and let $\bar{y} \in C^k$ be such that $r_k(x_1) = l_{\bar{y}}^{1/2}$. We claim that in either case,

$$x_1, x_2 \in B_{g(\bar{d})}(\bar{y}, 15d).$$

(4.12)

Once (4.12) is shown, then [LNNb, Proposition 5.6(2)] ensures that

$$(1 - \epsilon/2)d_{g(\bar{d})}(x_1, x_2) \leq d_{g(1)}(x_1, x_2) \leq (1 + \epsilon/2)d_{g(\bar{d})}(x_1, x_2);$$

(4.13)

this estimate essentially comes from the way the decomposition is defined and parabolic estimates for the Ricci flow, and for the case $k > 1$ the multiplicative factors $1 \pm \epsilon/2$ become $(1 \pm \epsilon/2)^k$. Once this is shown, together (4.11) and (4.13) establish (4.10).

So, it remains to show the containment (4.12). In the case when $\bar{y} = x_1$ this is immediate for $x_1$ and follows from (4.13) for $x_2$ (with $1 + \epsilon/2$ in place of 15). We focus on the second case where $x_1 \in B_{g(\bar{d})}(\bar{y}, 12\bar{r})$. In this case, we see as a direct consequence of (2.8) and Lemma 2.4 that $x_1 \in B_{g(\bar{d})}(\bar{y}, (1 + 2\epsilon)12d)$. So, the containment (4.12) holds for $x_1$ in this case. For $x_2$, we have from (4.11) that

$$d_{g(\bar{d})}(x_2, \bar{y}) \leq d_{g(\bar{d})}(x_1, \bar{y}) + d_{g(\bar{d})}(x_1, x_2) \leq (1 + 2\epsilon)12d + (1 + \epsilon/2)d \leq 15d.$$

This completes the proof. \qed

**Remark 4.3.** Note also that if we let $\psi$ be the map from Theorem 1.3, then Lemma 4.2 and Lemma 2.1 together imply that

$$(1 - \epsilon)^{k+1}d_g(x_1, x_2) \leq |\psi(x_1) - \psi(x_2)| \leq (1 + \epsilon)^{k+1}d_g(x_1, x_2)$$

(4.14)

for any pair of points as in Lemma 4.2.

**4.3. Mutual absolute continuity and rectifiability.** We now complete the proof of Theorem 1.4 by showing properties (3) and (4) for limit spaces.

**Proof of Theorem 1.4, continued.** We continue with the same notation used in the first part of the proof of Theorem 1.4 above. The limit pointed metric measure space $(X, m, x_\infty, d)$ is proper (e.g. by [HKST15, Theorem 11.4.7]), thus in particular locally compact and separable. Moreover, by [HKST15, Corollary 3.3.47], the limit measure $m$ is a Radon measure. So, thanks to (1.8), we are in
a position to apply Lemma 4.1 with $\epsilon' = \delta$ to any unit ball $B_\infty$ in $(X, d, x_\infty, m)$. Lemma 4.1 shows that $m$ and $\mathcal{H}^n$ are mutually absolutely continuous (in every ball unit $B_\infty$ and thus globally), with $m = f \mathcal{H}^n$ satisfying $(1 - \epsilon) \leq f \leq (1 + \delta)$. This proves (3).

Next, we show that $X$ is $m$-rectifiable and $\mathcal{H}^n$-rectifiable. As rectifiability is a local property, it suffices to show that $B_\infty$ is $m$- and $\mathcal{H}^n$-rectifiable. For $i$ fixed, let $B_i = \bigcup_{k=1}^\infty G_i^k \cup \mathcal{A}_i$ be the decomposition given by Lemma 2.5 applied to $B_i \subset B_{g_i(1)}(x, 8) \subset M_i$, and let $\mathcal{F}^k := \bigcup_{i=1}^k G_i^k$. By Lemma 2.5, for fixed $k$, we have

$$B_i \setminus \mathcal{F}^k_i \subset \bigcup_{a=1}^{\infty} B_{g_i}(y_{a,i}, 15t_{a,i}^{1/2}), \quad \sum_{a=1}^{\infty} t_{a,i}^{n/2} \leq \epsilon^k.$$ (4.15)

Note that on the right-hand side of the inclusion, we have replaced balls with respect to $g_i(t_{a,i}^{1/2})$ in Lemma 2.5(4) by balls of slightly larger radii with respect to $g_i = g_i(0)$ using (2.9). For each fixed $k$, after passing to a diagonal subsequence, we have $y_{i,a} \to y_a \in B_\infty$ and $t_{a,i} \to t_a \in [0, \epsilon^{2k/n}]$ for each $a \in \mathbb{N}$. (Here the convergence of points is meant with respect to the metric on $X$ (i.e., $\Pi_i$ in which the Hausdorff convergence of the spaces occurs.) Define the set $\mathcal{C}^k = \{y_a \in B_\infty : t_a > 0\}$, and define

$$\mathcal{F}^k = B_\infty \setminus \bigcup_{y_a \in \mathcal{C}^k} B_2(x_a, t_{a,i}^{1/2}).$$ (4.16)

Since $\mathcal{F}^k$ is a Borel set, it is $m$-measurable and $\mathcal{H}^n$-measurable. Observe that $\sum_{a \in \mathcal{C}^k} t_{a,i}^{n/2} \leq \epsilon^k$, and thus applying (1.8), we find that

$$m(B_\infty \setminus \mathcal{F}^k) \leq (1 + \delta)\omega_n \epsilon^k.$$

Thanks to property (3) of the theorem, we also get $\mathcal{H}^n(B_\infty \setminus \mathcal{F}^k) \leq (1 + \delta)^n \omega_n \epsilon^k$. So, in particular

$$\mathcal{H}^n(X \setminus \bigcup_k \mathcal{F}^k) = m(X \setminus \bigcup_k \mathcal{F}^k) = 0.$$ (4.17)

We claim that $\psi|_{\mathcal{F}^k}$ is a $(1 + \epsilon)^k$ bi-Lipschitz map onto its image. In view of (4.17) and the measurability of the $\mathcal{F}^k$, this will show that $B_\infty$ is $m$-rectifiable and $\mathcal{H}^n$-rectifiable, thereby completing the proof. To this end, for any $x, y \in \mathcal{F}^k$, we may find sequences $x_i, y_i \in M_i$ such that $x_i \to x$ and $y_i \to y$ and with $d_i := d_{g_i}(x_i, y_i) \to d := d(x, y)$. From the definition of $\mathcal{F}^k$, we see that for $i$ sufficiently large, either $x_i \in \mathcal{F}^k_i$, or else $x_i \in B_{g_i}(y_{a,i}, t_{a,i}^{1/2})$ with $t_{a,i} \to 0$ as $i \to \infty$. The same holds for $y_i$. In either case, $d_{g_i}(x_i, y_i) \geq \epsilon \min\{r_k(x_i), r_k(y_i)\}$ for $i$ sufficiently large, where $r_k$ is defined in (4.9) above. The claim then follows from Lemma 4.2, Remark 4.3, and the Arzelà-Ascoli theorem. This completes the proof. \hfill \Box

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