Flux transitions in a superconducting ring

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We consider a superconducting ring embedded in a magnetic field. The magnetic field is initially too high to support a superconducting state, but is ideally slowly decreased and then reversed. During this process, the number of fluxoids trapped by the ring exhibits a complex pattern of transitions, which depends qualitatively on the ratios of the geometric dimensions of the ring to the coherence length. We evaluate the current around the ring and find rough agreement with experiments. However, we also predict a new feature that has not shown up in experiments: in the vicinity of a critical field, giant jumps are expected.

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I. INTRODUCTION

It has been long known that a superconducting loop embedded in a magnetic field exhibits phenomena of fundamental nature, such as persistent currents and flux quantization. The concept of flux quantization has been crucial for the analysis of a wide range of topics of basic and practical importance. The ability to manufacture loops with widths of the order of the coherence length brought renewed interest in this system; experimental and theoretical studies are being performed until present.

The purpose of the present article is the theoretical study of the following situation. A ring of superconducting material is embedded in a homogeneous magnetic field. Initially the field is too high to support a superconducting state, but it is slowly lowered to zero while the temperature is kept constant; the field is then reversed and increased until superconductivity is destroyed. The most prominent feature of these experiments comes from the thermodynamic need for a winding number (number of fluxoids) which is not too far from the applied flux, together with the constraint that this number has to be integer. These coupled requirements usually lead to jumps in the winding number and, accordingly, in quantities such as the current around the ring.

Experiments like this were performed long ago, but modern versions of it are still giving new results. Situations similar to that considered here have been reported in Refs. 15, 16. In the limit of a thin ring, this situation provides a neat example for the study of state selection in phase transitions. Similar experiments for weakly connected rings and for disks have also been widely studied.

In the limit of infinite radius, a ring becomes a slab with parallel plane boundaries. We shall suggest in Sec. II that the most outstanding feature obtained in our results can be related to the condition for the formation of vortices in a slab parallel to the magnetic field. If the coherence length is larger than 0.55 times the width of the slab, then vortices cannot be present in the slab, whereas for smaller coherence lengths they can. This change of regime is accompanied by a change of behavior of the temperature–field dependence along the normal–superconducting (N-S) phase boundary. The second derivative of the transition temperature with respect to the field is discontinuous at the critical value of the coherence length. These results were confirmed experimentally. For more recent studies on slabs, see e.g. Refs. 23, 24, 25, 26.

We consider a ring with perfect axial symmetry and analyze it by means of the Ginzburg–Landau model. Since the magnetic field varies with time, it is natural to use the time-dependent Ginzburg–Landau model (TDGL). This approach has been followed in recent calculations. While TDGL is appropriate for the study of a given experiment, the number of parameters it introduces is rather large, depending on the material, the temperature, and the rate at which the magnetic field is swept. In this article we have chosen to consider the theoretical limit in which the field varies ideally slowly, so that the time independent formalism can be used.

We assume that the ring is very thin compared with the magnetic penetration length. Under these assumptions the free energy is (up to unimportant constants)

$$G = \int_0^{2\pi} d\theta \int_{R_s}^{R} r dr \left[ \mu (|\psi|^2 + \frac{1}{2} |\psi|^4) + |(iR \nabla - br/R \hat{\theta})\psi|^2 \right]$$

(1)

where $r$ and $\theta$ are cylindrical coordinates, $\psi$ is a normalized order parameter, $R_s$ and $R$ are the inner and outer radii of the ring, $\mu = (R/\xi)^2$ is a function of the temperature ($\xi$ is the coherence length) and $b = \pi R^2 H_c/\Phi_0$, where $H_c$ is the magnetic field and $\Phi_0$ the quantum of flux.

II. THE ONSET OF SUPERCONDUCTIVITY

In order to gain some intuition about this problem, we first consider the Little–Parks regime, at the onset of superconductivity. In this regime $|\psi| \ll 1$, so that the Ginzburg–Landau equations are linearized and the case of the ring can be solved exactly. The purpose of the present section is to point out that there exists a
critical point in the N-S boundary. As will be seen in the following sections, it appears that this critical point plays a major role in the “superheating” stability of the superconducting states.

Figure 1 shows the normalized field $b$ at which a ring with $R_i = 0.8R$ becomes superconducting, as a function of the winding number $m$, for $\mu = 92$ and for $\mu = 94$. Only integer values of $m$ are meaningful, and only the value of $m$ with the highest $b$ is physically realized, but these curves are useful for explanatory purposes. We found that for $\mu \lesssim 92$ these onset curves have only one maximum, whereas for $\mu \gtrsim 94$ they have two. At $\mu \approx 93, m \approx 68, b \approx 87$ there is a critical point, where the first and the second derivative of the onset field (or of the free energy) with respect to $m$, both vanish. As a consequence, near this critical point, the free energy depends very weakly on the winding number $m$.

The influence of this critical point is felt quite far from its immediate vicinity. The dashed line in Fig. 1 is a line of constant (negative) free energy for $\mu = 110$. We see in its upper part that for a range of about 8 winding numbers the slope of $b$ with respect to $m$, expressed in “natural” units, is less than a tenth. By the relationship

$$\frac{\partial b}{\partial m} = \frac{-\partial G/\partial m}{\partial G/\partial b},$$

the smallness of $\frac{\partial b}{\partial m}$ suggests that the free energy also has a very weak dependence on the winding number $m$.

In reality, only integer values of $m$ and their linear combinations exist. The typical scenario for flux transitions is as follows. A given field $b$ is present and the order parameter has a certain winding number. Linear combinations with other winding numbers act as energy barriers and the sample is “trapped” at $m$. When $b$ becomes sufficiently small, the energy barrier towards smaller winding numbers is levelled off, and the state decays. If $\frac{\partial G/\partial m}{\partial G/\partial b}$ is large, the order parameter will be “stopped” by the following barrier and become trapped at $m - 1$. However, a small slope means that $m$ has to change by a big amount for a given change in $G$, leading to the possibility of transitions that change $m$ by several units.

The critical point found here can be associated to two phenomena which have been discussed in the literature. The first is the condition for the formation of vortices in a slab, quoted in Sec. I. Using the value $0.2R$ as the thickness of the slab, the onset for the appearance of vortices is located at $\mu \sim b \sim 80$, not far from the critical point in our case. We can therefore expect that for $\mu$ above the critical point (low temperatures) there will be vortices in the ring, whereas for small $\mu$ the winding number will be the same for the inner or for the outer boundary of the ring.

An additional feature noted in Ref. 24 is the crossover from a regime in which at the N-S boundary $b$ is approximately proportional to $\mu^{1/2}$ to a regime where $b$ is approximately proportional to $\mu$. In the case of rings, this crossover applies to the background line of this boundary, which has the Little-Parks oscillations superimposed on it. This is actually a dimensional crossover: at low fields the sample behaves as a thin slab and $b = 5(3\mu)^{1/2}$; at high fields it behaves as half a plane and $b = 0.847\mu$. Again, the crossover occurs at $\mu \sim 100$. For the case of slabs the passage from one regime to the other involves discontinuities of some quantities, but for the case of rings these discontinuities are not relevant, since except for accidental situations the critical point does not occur at a physical (i.e. integer) value of $m$.

Since we believe that the main features of the situation we study are governed by the critical point described in this section, we have evaluated numerically the position of this point as a function of the ratio $R_i/R$. Figure 2 shows the values of $\mu$ and $b$ at which the critical point occurs. Since to a rough approximation these values are inversely proportional to the square of the width of the ring, the normalized values $\mu(1-R_i/R)^2$ and $b(1-R_i/R)^2$ appear in the figure. In the following sections we will always take $R_i = 0.8R$, which is a representative experimental value.

III. MATHEMATICAL METHOD

We return now to the general situation in which the order parameter $\psi$ is not necessarily small. We write $\psi$ as
where Eq. (2a) is a Fourier expansion and Eq. (2b) is an expansion into orthogonal polynomials, with $P_n(R_i) = P_n'(R_i) = 0$ and such that $P_n(r)$ vanishes $n$ times in the range $R_i \leq r \leq R$. We then keep up to four terms in Eq. (2a): two “leading” terms with winding numbers $m_0$ and $m_1$, and two “satellite” terms, with winding numbers $2m_0 - m_1$ and $2m_1 - m_0$. In Eq. (2b), we keep the terms $n = 0, 1, 2$ for the leading terms, and only the term $n = 0$ for the satellite terms. The coefficients $c_{mn}$, which are not declared to vanish, are found by minimizing the free energy.

The physical meaning of a single winding number in the expansion (2a) is that $|\psi|$ has axial symmetry. If there are two leading winding numbers $m_0$ and $m_1$ and two satellites, as we shall consider as our most general situation, and if the weights of the two leading winding numbers are similar, then the equilibrium order parameter exhibits a ring of $|m_0 - m_1|$ equidistant vortices in the superconducting sample. If there are several winding numbers, but the weight of one of them is much larger than those of the others, then $|\psi|$ does not have axial symmetry, but there are no vortices in the sample. For situations in which there are vortices in the sample that are not equidistant from the $z$-axis, our approximation breaks down.

According to our results, the approximations used seem to be reasonable as long as $\mu$ is not much higher than that of the critical point discussed in Sec. [I]. The usual situation is that the weight of the leading terms is much greater than that of the satellites. In Fig. 2 we compare the radial dependence of an axially symmetric order parameter obtained by the present approximations to that from an exact calculation.

Our procedure is as follows. For fixed temperature (fixed $\mu$), we first evaluate the magnetic field for the onset of superconductivity. At the onset, the Ginzburg–Landau equations are linear, so that the order parameter generically has axial symmetry and the sum (2a) contains only one $m$, which we denote by $m_0$. The field is then gradually lowered and for every field we evaluate the order parameter $R_{m_0}(r)e^{-m_0i\theta}$. We then check the stability of this order parameter against small variations.

Variations explore subspaces with larger dimensions than that of the equilibrium order parameter. When looking for decays from $m_0$, variations also contain the winding numbers $m_0 - \ell$ and $m_0 + \ell$, where $\ell$ is swept over at least the range $1 \leq \ell \leq \mu/5$. It is important to include both $m_0 - \ell$ and $m_0 + \ell$, since due to nonlinearity of the GL model these harmonics are coupled. For each variation we evaluate the Hessian of the variation of the free energy and obtain its eigenvalues. If all the eigenvalues are positive, it means that $R_{m_0}(r)e^{-m_0i\theta}$ is stable, and we proceed to decrease the field by a small step.

If any of the eigenvalues is negative, it means that $R_{m_0}(r)e^{-m_0i\theta}$ is unstable with respect to the variation represented by the corresponding eigenstate. We denote by $m_1 = m_0 \pm \ell$ the value of the winding number that has the highest weight in the variation against which $m_0$ was unstable.

During the decay of $R_{m_0}(r)e^{-m_0i\theta}$, the order parameter changes quickly. Therefore, in order to follow the order parameter or the currents during the decay, we would...
have to use the TDGL model. Using a gauge in which the electrochemical potential vanishes, the equations of this model take the form

$$\frac{\partial \psi}{\partial t} = -D_\psi \delta \psi G, \quad (3a)$$

$$\frac{\partial A}{\partial t} = -D_A \delta A G, \quad (3b)$$

where $A$ is the vector potential, $\delta \psi$ and $\delta A$ denote variations over the complex conjugate of $\psi$ and over $A$, and $D_\psi$ and $D_A$ are positive constants. From here, it follows that $G$ will always decrease during the decay and the order parameter will reach equilibrium when $G$ reaches a minimum. (The applied field is assumed to remain constant during the decay.)

Therefore, in order to obtain the order parameter after the decay, we perform a minimization of the free energy over states of the form (3), where the leading winding numbers are $m_0$ and $m_1$. The initial state from which the minimization flows is a combination of the former state with $m = m_0$ and of the eigenstate that had the negative eigenvalue. The minimization may lead to a state in which only one winding number has a significant weight; in this case we recover the previous situation and we just have to update the value of $m_0$. The other possibility is to be left with a combination of winding numbers (which means that $|\psi|$ is not axially symmetric). It seems plausible to assume that in the generic case the minimization leads to the same minimum, and with the same leading harmonics that would be obtained by TDGL; we intend to investigate the range of validity of this assumption in a future study.

In any numerical procedure, arbitrary decisions have to be taken concerning parameters such as cutoffs and convergence factors. Usually these parameters are fixed empirically in order to optimize convergence properties. In our case, one has to choose the initial weights given empirically in order to optimize convergence properties. Usually these parameters are fixed empirically in order to optimize convergence properties. For $\mu = 0.475$ and close to $b = \pm 4.35$, the ring is in the normal state. This reentrant behavior is due to the Little–Parks oscillations. For a ring with $R_i = 0.8R$, reentrant superconductivity is possible in the range $0.02 \leq \mu \leq 12.4$. For $\mu < 0.02$, only the Meissner state ($m = 0$) exists; in the range $0.02 \leq \mu \leq 12.4$ there are “windows” for which superconductivity is interrupted when passing from one $m$ to the next. For low values of $\mu$ these windows are wide, but, as $\mu$ increases, the background slope of the N-S boundary in the $b - \mu$ plane increases and these windows become narrower. For $\mu > 12.4$ the N-S boundary is monotonic.

### IV. RESULTS

For each field, after the order parameter is known, the free energy is evaluated using Eq. (1), the normalized current density is evaluated as $\text{Re}[\bar{\psi}(iR \nabla - br/R\partial r)\psi]$ and then the current (per unit height) is obtained by integration over $r$ of the tangential component.

#### A. Near $T_c$

Figure 4 shows the current around the ring, as a function of the field, for low values of $\mu$. As expected, there are discontinuities in the current, nearly periodically spaced. These discontinuities correspond to the passage between consecutive winding numbers.

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#### B. Short coherence length

Figures 5 and 6 show our results in the range $20 \leq \mu \leq 120$. For $\mu > 120$, our approximation of Eq. (2a) by four uniformly spaced harmonics breaks down. This was expected since, if the distance between the boundaries is considerably larger than the coherence length, then there is room for more than one ring of vortices.

Obviously, if the magnetic field is reversed, the current
in the sample for the equilibrium (absolute minimum) configuration is reversed too. For small values of $\mu$ hysteresis is a minor effect, and indeed we note in Fig. 5 that the current for $\mu = 0.475$ is nearly an odd function of the field. On the other hand, for the values considered in Fig. 6, hysteresis is dominant and the equilibrium values have practically no importance. At first glance the curves in Fig. 6 look like even functions and we observe that qualitatively different regions appear in nearly symmetric pairs. In the following, we shall review these regions, by decreasing values of $|b|$. Following the line of reasoning of Sec. II, we may argue that the approximate evenness is due to the invariance of $|\langle \partial G/\partial m \rangle_b|$ when both $b$ and $m$ change sign.

1. Near the onset

Figures 7 and 8 show our results for high values of $b$, with $\mu = 110, 120$ or 130. [Near the onset of superconductivity, the approximation of the expansion (2a) by a limited number of terms remains valid beyond $\mu = 120.$] The region at the right consists of steps where a single value of $m$ is left in (2a) and, as $b$ is lowered, $m$ decreases by 1 between consecutive steps. There are five such steps for $\mu = 120$ and 130, and four steps for $\mu = 110$. The current always drops when the state decays to a lower $m$.

2. Breaking of axial symmetry

This is roughly the region $87 \lesssim b \lesssim 94$ for $\mu = 110$, $81 + 7 \lesssim b \lesssim 94 + 7$ for $\mu = 120$ and includes most of
the line for \( \mu = 130 \) in Fig. 7. If we denote by \((m_0)\) a state with a single harmonic \(m = m_0\) and by \((m_0, m_1)\) a state with two leading winding numbers \(m_0\) and \(m_1\), this region extends from \((84, 70)\) to \((77, 65)\) for \(\mu = 110\), from \((91, 74)\) to \((78, 66)\) for \(\mu = 120\) and from \((98, 79)\) to an uncalculated state for \(\mu = 130\).

We may divide this region into a subregion of “incipient symmetry breaking” and a subregion of “developed symmetry breaking”. The subregion of incipient symmetry breaking consists of the sequence of double steps \((m_0^{(1)}) \rightarrow (m_0^{(2)}), (m_1^{(1)}) \rightarrow (m_1^{(2)}) \rightarrow \ldots\). Here \(m_0^{(i+1)} = m_0^{(i)} - 1 > m_1^{(i)}\), so that the transitions \((m_0^{(i)}, m_1^{(i)}) \rightarrow (m_0^{(i+1)}, m_1^{(i+1)})\) are continuous; on the other hand, the transitions \((m_0^{(i)}), m_1^{(i)}) \rightarrow (m_0^{(i)}, m_1^{(i)}\) are continuous bifurcations. In the subregion of developed symmetry breaking, all the states are combinations with two leading winding numbers. For \(\mu = 130\) there is only one step with incipient symmetry breaking and for \(\mu = 120\) there are two steps; for \(\mu = 110\), incipient symmetry breaking extends over the entire region. Some segments are very short, and cannot be seen in the graph.

The subregion of developed symmetry breaking can be subdivided further: in its high-field part the transitions \((m_0^{(i)}, m_1^{(i)}) \rightarrow (m_0^{(i+1)}, m_1^{(i+1)})\) have either \(m_0^{(i+1)} = m_0^{(i)}\) or \(m_1^{(i+1)} = m_1^{(i)}\); for lower fields there may be “cascades”. By a cascade we mean that, after a state decays, the new state is already unstable with respect to a third state, and decays at the same field at which it appeared. By means of cascades, \(m_0\) and \(m_1\) can both change simultaneously.

For axially symmetric states, the slope of the current in Fig. 7 is negative. On the other hand, for combinations with two leading winding numbers, the current is a markedly convex function, and can reach large positive slopes. For decays that follow after these large positive slopes, the current usually rises.

### 3. Critical region

This is the region with large discontinuities near \(|b| \sim 70\). For \(\mu = 120\) and \(\mu = 110\) the region of asymmetry ends with a long cascade, the last stage of which is a discontinuous decay into a symmetric state. For \(\mu \leq 100\) the region of asymmetry is absent. For \(\mu = 100\) the critical region begins with a decay in which \(m\)overshoots and then goes up. For \(b < 0\), the critical region in which \(m\) jumps by several units appears without previous signs.

It may be surprising that although the samples are sufficiently wide to have vortices on them, the order parameter is axially symmetric in this region. An intuitive explanation might be that the field is not sufficiently large and therefore a ring of vortices is not thermodynamically favorable.

Table I is a record of the states through which the critical region passes.

One notices that for \(b > 0\) the number of fluxoids that go through the ring during the critical region is largest for \(\mu\) near its critical value. The largest signal in the current-field graph, as well as the number of fluxoids that go through for \(b < 0\), appear to be at higher values of \(\mu\).

### 4. Subcritical region

This is the broadest region in Figs. 5 and 6. As the field decreases through the critical region, jumps in the winding number decrease from giant to moderate, until we finally reach a region in which the winding number changes by just one in each decay. For \(\mu \leq 60\) the two previous regions are absent and there is no distinction between this and the first region.

For \(20 \leq \mu \leq 60\) and \(b > 0\), the average range \(\Delta b\) between consecutive jumps in this region is \(1.30\); for \(b < 0\), \(\Delta b = 1.17\). This difference can be understood, since for \(b > 0\) a delay in the decays is produced by “supercooling” and in the negative region it is necessary to catch up with this delay. For \(80 \leq \mu \leq 120\), \(\Delta b = 1.24\) for positive fields and \(\Delta b = 1.23\) for \(b < 0\), indicating that the presence of the critical region helps to release most of this delay. Note that \(\Delta b\) is not close to unity due to our choice of the outer radius as the unit of length. Had we chosen the average radius \(0.9R\) as the unit of length (as in Ref. 11), we would have had to divide the values of \(b\) by \(1/0.9^2 \approx 1.235\).

### 5. Low fields

This is a short region centered at slightly negative fields. In this region the “satellite” harmonic \(2m_1 - m_0\) is not necessarily small. In this region the results we obtain are sensitive to the minimization strategy, and the results in Figs. 5 and 6 are less reliable here than in the other regions.
FIG. 9: Comparison between our results and those measured in Ref. 14. The experimental data are represented by the dense set of dots and the theory by the line above. The experimental value of \( b \) was obtained by multiplying the applied field by \( \pi R^2 / \Phi_0 \). Also, since in our calculations the field was swept downwards and in the experiment upwards, the sign of the experimental field was switched. The experimental value of the normalized current was obtained by multiplying the field induced by the supercurrent at the center of the ring by \( 2\pi\kappa^2 (R_0 + R)R^2 / \Phi_0 \mu t \). We took \( \kappa \sim 0.5 \) and estimated the field induced at the center of the ring as 2.5 times its average value on the active square of the Hall cross. The calculated curve is for \( \mu = 30 \).

V. COMPARISON WITH EXPERIMENTS

To our knowledge, the experiments closest to the situation discussed in this article are Ref. 11 and Refs. 13, 14. Reference 11 deals with only three fluxoids, and from the present point of view may be considered featureless. (See however Ref. 32.) The results of Ref. 13 are similar to those of Ref. 11, but in this case the susceptibility goes to zero at the onset of superconductivity, as in our results. Ref. 14 also confirms our result that, if the width of the ring is appreciably smaller than the coherence length, all the transitions involve the passage of just one fluxoid.

Reference 13 reports on two rings. In both cases the estimated mean radius is 2.16 \( \mu \)m and the coherence length, 180 nm. For their wide ring, \( R - R_0 = 630 \text{nm} \). Using graph 4, these values result in \( \mu = (R / \xi)^2 \sim 3\mu_{\text{crit}} \), far beyond the region we have studied. One observation can nevertheless be adventurous: the critical value of the field is \( b_{\text{crit}} \sim 56 \), which for this geometry corresponds to about 60G. The “catastrophic behavior” in their Fig. 5 begins not far from there.

Their narrow ring has a width \( R - R_0 = 316 \text{nm} \), which now implies \( \mu = (R / \xi)^2 \sim 0.9\mu_{\text{crit}} \). Translated to our case, this corresponds to \( \mu \sim 80 \). Inspection of their Fig. 2 and our Fig. 3 suggests that \( \mu = 60 \) would give a better comparison. The difference between \( \mu = 80 \) and \( \mu = 60 \) could be due to a 15% error in any of the reported lengths, and is an expected experimental uncertainty. There are some similar features between our results and the experimental curve: there is a central region sandwiched between two outer regions, like the low-field and the subcritical regions of the previous section. The size of the discontinuities grows towards lower fields at an apparently correct pace. The average period \( \Delta b \) for positive fields is longer than that for negative fields, and the ratio 1.30 : 1.17 seems to be of the right order. For \( \mu = 60 \) and \( b \sim 0 \) we predict a current of the order of \( 0.6e\Phi_0 \mu t / (2\pi\kappa R)^2 \), where \( t \) is the thickness of the ring. Assuming \( t \approx 90 \text{nm} \) and \( \kappa \sim 0.5 \), this current amounts to \( 2 \times 10^6 \text{esu/} \text{sec} \). A current like this would induce a magnetic field of \( \sim 2 \text{G} \) at the center of the ring; this is the correct order of magnitude.

Figure 9 compares our results with a measurement in Ref. 14. The micrograph at a corner shows an aluminum ring grown on a Hall cross which permits to measure the average magnetic field produced by the supercurrent. The dots are the experimental results. As can be seen from the micrograph, the width is close to 0.2\( R \), enabling a direct comparison with our results. The thickness is \( t \approx 0.12 \mu \text{m} \). The outer radius, as measured by optical means, is \( R = 1.1 \pm 0.1 \mu \text{m} \). We picked \( R = 1.22 \mu \text{m} \), in order to have the correct average periodicity. The temperature was 0.6 \pm 0.1K, which implies a coherence length between 0.190 \mu \text{m} \) and 0.217 \mu \text{m} \) and hence \( \mu = 34 \pm 3 \). The line in Fig. 9 was evaluated for \( \mu = 30 \). The difference in height between the measured and the calculated results is not very significant, since several factors have been just estimated; however, the range of the central part is much wider than predicted. Again, the average period \( \Delta b \) for positive fields is longer than that for negative fields; this time the effect is more pronounced than in Ref. 13.

Since both experiments show a central part with two-fluxoid jumps which is considerably wider than in our results, we list some deviations from our idealizations that might give rise to this discrepancy.

- We have neglected the induced field. The magnetic penetration depth \( \lambda = \kappa R \mu t^{-1/2} \sim 0.5 \times 2300 \mu \text{m} \times 60^{-1/2} \approx 150 \mu \text{m} \) is only marginally larger than the thickness of the ring, so that our assumption is not clearly justified. The influence of the induced field on “superheating” for the case of thick disks has been considered in Ref. 67 and does not hint at a qualitatively different behavior.

- An experimental ring never has perfect axial symmetry. This imperfection has been treated in previous studies and has a profound influence near the onset of superconductivity, but is not expected to be important deep inside the superconducting region. Large imperfections have been found to inhibit the size of the transitions in the present problem, variation of the width with the height might also be important.

- Decays most probably occur before the ideal metastability limit is reached, mainly due to electromagnetic noise. When taking measurements,
noise can be filtered out by a lock-in amplifier, but in order to avoid premature decays only shielding could help.

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