Inverse problems in spin models
Vitor Sessak

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Titre:

Problèmes inverses dans les modèles de spin

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Résumé

Un bon nombre d’expériences récentes en biologie mesurent des systèmes composés de plusieurs composants en interactions, comme par exemple les réseaux de neurones. Normalement, on a expérimentalement accès qu’au comportement collectif du système, même s’il s’intéresse souvent à la caractérisation des interactions entre ses différentes composants. Cette thèse a pour but d’extraire des informations sur les interactions microscopiques du système à partir de son comportement collectif dans deux cas distincts. Premièrement, on étudie un système décrit par un modèle d’Ising plus général. On trouve des formules explicites pour les couplages en fonction des corrélations et magnétisations. Ensuite, on s’intéresse à un système décrit par un modèle de Hopfield. Dans ce cas, on obtient non seulement une formule explicite pour inférer les patterns, mais aussi un résultat qui permet d’estimer le nombre de mesures nécessaires pour avoir une inférence précise.
Abstract

Several recent experiments in biology study systems composed of several interacting elements, for example neuron networks. Normally, measurements describe only the collective behavior of the system, even if in most cases we would like to characterize how its different parts interact. The goal of this thesis is to extract information about the microscopic interactions as a function of their collective behavior for two different cases. First, we will study a system described by a generalized Ising model. We find explicit formulas for the couplings as a function of the correlations and magnetizations. In the following, we will study a system described by a Hopfield model. In this case, we find not only explicit formula for inferring the patterns, but also an analytical result that allows one to estimate how much data is necessary for a good inference.
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Résumé détaillé

Récemment, un grand nombre d’expériences en biologie qui génèrent une quantité très importante de données ont vu le jour. Dans une partie considérable de ces expériences, dont on peut citer les réseaux de neurones, l’analyse de données consiste grosso modo d’identifier les corrélations entre les différentes parties du système. Malheureusement, les corrélations en soi n’ont qu’une valeur scientifique limitée : la plupart des propriétés intéressantes du système sont décrites plutôt par l’interaction entre ses différentes parties. Le but de ce travail est de créer des outils pour permettre de déterminer les interactions entre les différentes parties d’un système en fonction de ses corrélations.

Dans ce résumé en langue française, on va commencer par une introduction où on exposera des résultats classiques sur le principal système qui a motivé ce travail : les réseaux des neurones. Ensuite, on va parler brièvement de la modélisation qu’on a choisi pour ce travail et des résultats connus sur des systèmes similaires.

Dans une deuxième partie, on présentera un développement en petites corrélations du problème d’Ising inverse. Finalement, dans une dernière partie on traitera le problème d’Hopfield inverse, ie., trouver les patterns du modèle à partir des champs et corrélations locales.

Introduction

Une des questions scientifiques plus importantes du 21ème siècle est la compréhension du cerveau. Aujourd’hui, il est bien connu que la complexité du cerveau est un produit de l’organisation des ses cellules (les neurones) en des réseaux complexes. Un neurone typique est composé de trois parties : un corps cellulaire, qui contient le noyau de la cellule, des dendrites, responsables pour la réception des signaux des autres cellules et un axone, qui envoie des signaux à des autres neurones (voir image). Les connexions entre neurones sont appelées synapses et ont lieu typiquement entre un axone et un dendrite.
RÉSUMÉ DÉTAILLÉ

Figure 0.1: Schéma d’un neurone [Alberts 02]. Le diamètre du corps cellulaire est typiquement de $10 \mu m$, pendant que la taille des dendrites et des axones varie considérablement avec la fonction du neurone.

Comme toutes les cellules, les neurones possèdent une différence de potentiel entre son cytoplasme et le milieu inter-cellulaire. Cette différence de potentiel est contrôlée par des mécanismes de pompes d’ions, qui peuvent augmenter ou diminuer ce potentiel. Quand la différence de potentiel d’un neurone atteint un certain seuil, un mécanisme de feedback active les pompes, faisant le potentiel croître rapidement jusqu’à environ $100 \text{ mV}$ (en dépendant du type de neurone), après quoi il atteint la saturation et décroît, en revenant au potentiel de repos de la cellule. On appelle ce processus un spike.

À chaque fois qu’un neurone émet un spike, son axone libère des neurotransmisseurs dans les cellules à lesquelles il est connecté, en changent leur différence de potentiel. Comme les synapses peuvent être excitatrices ou inhibitrices, les modèles normallement définissent un poids pour les synapses, avec la convention que un poids positive correspond à une synapse qui augmentent le potentiel des neurones auquel elle est connecté (et donc favorise les spikes) et un poids négatif au cas où la synapse décroît ce potentiel.

Une nouvelle venue de recherche très prometteuse dans le domaine des neurosciences a été le développement des techniques d’enregistrement multi-neurones. Dans ces expériences, une matrice de micro-électrodes (contant jusqu’à 250 électrodes) est mise en contact avec le tissu cérébral et le potentiel à chaque électrode est mesuré pendant quelques heures. Un procédé sophistiqué d’analyse de données permet alors d’identifier la activité individuelle de chaque neurone en contact avec les électrodes. La sortie typique de un enregistrement multi-neurones est montrée dans la figure suivante.
Figure 0.2: Résultat typique d’une expérience d’enregistrement multi-électrodes [Peyrache 09]. Chaque ligne correspond à un seul neurone, pendant que les barres verticales correspondent à des spikes.

En principe, on pourrait trouver les synapses à partir des enregistrements multi-électrodes, mais extraire cette information n’est pas trivial. Naïvement, on aurait envie de dire que si l’activité de deux neurones sont corrélées ils sont connectés par une synapse, mais considérons trois neurones dont l’activité est corréle : on voit aisément que toutes les deux configurations montrées dans l’image suivante peut rendre compte de ces corrélations.

Figure 0.3: Deux configurations possibles pour trois neurones corrélés.

Pour pouvoir donner une contribution à ce problème, il est nécessaire d’abord de choisir un modèle pour les réseaux de neurones. Le modèle d’intéresse pour cette thèse est la machine de Boltzmann [McCulloch 43]. Dans ce modèle, on modélise l’état d’un neurone par une variable binaire : $\sigma = +1$ si il est en train d’émettre un spike, $\sigma = -1$ sinon. Le réseau de N neurones est alors décrit par un vecteur \{\sigma_1, \ldots, \sigma_N\}. Pour simplifier, on ignore totalement la dynamique du système et le modèle décrit seulement la probabilité $P(\{\sigma_1, \ldots, \sigma_N\})$ de trouver le système dans un état \{\sigma_1, \ldots, \sigma_N\}, qui est donnée par le poids de Boltzmann d’un modèle d’Ising généralisé :

$$P(\{\sigma_1, ..., \sigma_N\}) = \frac{1}{Z} e^{-\beta H(\sigma_1, ..., \sigma_N)}, \quad (1)$$
avec
\[ Z = \sum_{\{\sigma\}} e^{-\beta H(\{\sigma_1, \ldots, \sigma_N\})}, \]
(2)

où \( Z \) est la fonction de partition du modèle, \( \beta \) est un paramètre du modèle, qui dans le contexte de spins correspond à la température inverse et on introduit la notation
\[ \sum_{\{\sigma\}} \equiv \sum_{\sigma_1=\pm 1} \sum_{\sigma_2=\pm 1} \cdots \sum_{\sigma_N=\pm 1}. \]
(3)

Le Hamiltonien doit prendre en compte les synapses entre les neurones et qu’il doit recevoir une certaine quantité minimum des signaux pour émettre un spike. L’expression la plus utilisée est
\[ H(\{\sigma_1, \ldots, \sigma_N\}) = -\frac{1}{2N} \sum_{i,j} J_{ij} \sigma_i \sigma_j - \sum_i h_i \sigma_i, \]
(4)

où \( J_{ij} \) correspond au poids des synapses et \( h_i \) est un terme qui modélise le seuil de spike comme un champs qui attire le neurone vers son état de repos. Ce modèle est intéressant pour ce travail pour deux raisons : d’abord, il permet de mettre en œuvre directement les outils développés dans le contexte de la mécanique statistique et des systèmes désordonnés. En outre, ce modèle est émergé naturellement quand on cherche un modèle qui peut rendre compte d’un ensemble de moyennes \( \langle \sigma_i \rangle \) et de corrélations \( \langle \sigma_i \sigma_j \rangle \). C’est important à noter que dans ce modèle les couplages sont symétriques, ie, \( J_{ij} = J_{ji} \), ce qui n’est pas forcément vrai dans des systèmes biologiques.

Le modèle d’Ising généralisé contient comme cas particulier des différents modèles classiques de la littérature. On peut citer le modèle d’Ising ordinaire, le modèle de Sherrington-Kirkpatrick et, d’un intérêt particulier pour cette thèse, le modèle de Hopfield. Dans ce modèle, le Hamiltonien est donné par
\[ H = -\frac{1}{2N} \sum_{\alpha=1}^p \left( \sum_i \xi^\alpha_i \sigma_i \right)^2, \]
(5)

où \( \xi^\alpha_i \) sont des valeurs réels et en développant le carré on voit bien qu’il correspond au modèle d’Ising généralisé par
\[ J_{ij} = \sum_{\mu=1}^p \xi^\mu_i \xi^\mu_j. \]
(6)

L’idée derrière le modèle d’Hopfield est de rendre compte d’un système qui garde un nombre \( p \) de mémoires et peut les retrouver à partir d’un état initial similaire à la mémoire recherchée. Effectivement, dans l’équation (5) on voit bien que si les mémoires \( \xi^p \) sont à peu près orthogonaux les unes avec les autres, l’état \( \sigma_i = \xi^\alpha_i \) correspond à un minimum local de l’énergie. Un résultat classique (voir [Amit 85a]) est que dans certaines conditions, ces états sont aussi des minimums locales de
l’énergie libre, ce qui permet effectivement de dire que le système peut retrouver ces mémoires.

Déterminer le comportement d’un système décrit par un modèle d’Ising généralisé est normalement très difficile et il n’existe pas de solution générale pour ce problème. On peut, par contre, trouver des solutions approchées dans un certain limite de validité. Un cas particulier que nous intéresser est le développement en petites couplages introduit par Thouless, Anderson and Palmer (dites équations TAP) [Thouless 77]. Le résultat qu’ils ont obtenu dit que pour un système avec un Hamiltonien donné par

\[ H = - \sum_{i<j} J_{ij}\sigma_i\sigma_j \] (7)

l’énergie libre est donnée par

\[
\log Z = - \sum_i \frac{1 + m_i}{2} \log \left( \frac{1 + m_i}{2} \right) - \sum_i \frac{1 - m_i}{2} \log \left( \frac{1 - m_i}{2} \right) \\
+ \sum_{i<j} J_{ij}m_im_j + \frac{1}{2} \sum_{i<j} J_{ij}^2(1 - m_i^2)(1 - m_j^2) + O(J^3),
\] (8)

où \( m_i = \langle \sigma_i \rangle \) est la magnétisation locale du système, qui selon les équations TAP obéissent

\[
\tanh^{-1} m_i = \sum_{j(\#i)} J_{ij}m_j - m_i \sum_{j(\#i)} J_{ij}^2(1 - m_j^2).
\] (9)

Malheureusement, dans le cadre des expériences avec les neurones, on n’a pas besoin d’avoir une méthode pour trouver le comportement d’un système en fonction des paramètres, mais faire le contraire : trouver les paramètres qui rendent compte au mieux des résultats observés. On parle alors de “problèmes inverses”.

Travailler avec des problèmes inverses entraîne deux complications supplémentaires : d’abord, même pour les cas où on peut résoudre le problème directe, trouver les paramètres qui décrivent les données est normalement un problème difficile. En outre, donner une signification mathématique à la expression “mieux décrit le système” est aussi un point délicat. Une cas possible est que plusieurs différents choix de paramètres peuvent décrire exactement les mesures. La situation contraire, où il n’existe pas d’ensemble de paramètres qui rendent compte des données (à cause des erreurs expérimentaux), est tout aussi possible.

Pour rendre compte de ce problème, il est utile de postuler que les paramètres qui décrivent le problème suivent eux aussi une loi statistique. On peut alors appliquer le théorème de Bayes qui dit que la probabilité que les paramètres valent \( \{\lambda_i\} \) en fonction des mesures \( \{X_i\} \) est donnée par

\[
P(\{\lambda_i\}|\{X_i\}) = \frac{P(\{X_i\}|\{\lambda_i\})P_0(\{\lambda_i\})}{P(\{X_i\})},
\] (10)

où \( P_0(\{\lambda_i\}) \) est la probabilité a priori des paramètres et \( P(\{X_i\}) \) est la probabilité marginale de \( \{X_i\} \), qui peut aussi être interprétée comme une normalisation de la
probabilité \( P(\{\lambda_i\}|\{X_i\}) : \)

\[
P(\{X_i\}) = \sum_{\{\lambda_i\}} P(\{X_i\}|\{\lambda_i\}) P_0(\{\lambda_i\}). \tag{11}
\]

Ce théorème permet de donner une définition précise du “meilleur” ensemble de paramètres pour décrire le système comme ceux qui maximisent \( P(\{\lambda_i\}|\{X_i\}) \). À part cela, s’il existe plus d’un ensemble de paramètres qui rendent compte des données, un choix judicieux de \( P_0(\{\lambda_i\}) \) permet de “choisir” parmi ces solutions et de rendre le problème bien défini.

**Le problème d’Ising inverse**

On considère le modèle d’Ising généralisé avec un Hamiltonien donné par

\[
H(\{\sigma_i\}) = -\sum_{i<j} J_{ij} \sigma_i \sigma_j - \sum_i h_i \sigma_i, \tag{12}
\]

qui définit alors une probabilité sur les états suivant la loi de Boltzmann

\[
P(\{\sigma_i\}) = \frac{1}{Z} e^{-H(\{\sigma_i\})}, \tag{13}
\]

où \( Z \) est la fonction de partition, donnée par

\[
Z = \sum_{\{\sigma_i\}} e^{-H(\{\sigma_i\})}. \tag{14}
\]

Normalement, quand on étudie un tel système on cherche à déterminer les magnétisations locales \( m_i = \langle \sigma_i \rangle \) et les corrélations à deux sites \( c_{ij} = \langle \sigma_i \sigma_j \rangle - m_i m_j \) en fonction des couplages \( \{ J_{ij} \} \) et des champs \( \{ h_i \} \). Par contre, on parle de problème d’Ising inverse quand on cherche à déterminer \( J_{ij} \) et \( h_i \) en fonction des corrélations et magnétisations.

Notre point de départ pour résoudre ce problème est l’entropie de Shannon du problème\(^2\)

\[
S(\{J_{ij}\}, \{\lambda_i\}; \{m_i\}, \{c_{ij}\}) = \log Z(\{J_{ij}\}, \{h_i\}) - \sum_{i<j} J_{ij} (c_{ij} + m_i m_j) - \sum_i h_i m_i, \]

\[
= \log \sum_{\{\sigma_i\}} \exp \left\{ \sum_{i<j} J_{ij} [\sigma_i \sigma_j - c_{ij} - m_i m_j] + \sum_i h_i (\sigma_i - m_i) \right\}, \tag{15}
\]

où on a introduit des nouveaux champs externes \( \lambda_i \) qui sont liés avec le vrai champs \( h_i \) par \( \lambda_i = h_i + \sum_j J_{ij} m_j \). On voit aisément calculant \( \partial S/\partial J_{ij} \) et \( \partial S/\partial h_i \) qui

\(^2\)Pour plus de détails, voir Chapitre 3 et 4 de la version en anglais.
l’ensemble des \( J_{ij}^* \) et \( \lambda_i^* \) qui reproduisent les magnétisations \( m_i \) et corrélations \( c_{ij} \) est celui qui minimise \( S \). On va aussi s’intéresser à la valeur de \( S \) au minimum

\[
S(\{m_i\}, \{c_{ij}\}) = \min \min S(\{J_{ij}\}, \{\lambda_i\}; \{m_i\}, \{c_{ij}\}),
\]

car à partir de cette expression il est possible d’extraire les valeurs de \( J_{ij}^* \) et \( \lambda_i^* \) utilisant

\[
\frac{\partial S(\{m_i\}, \{\beta c_{ij}\})}{\partial c_{ij}} = -\beta J_{ij}^*(\beta),
\]

et

\[
\frac{\partial S(\{m_i\}, \{\beta c_{ij}\})}{\partial m_i} = -\lambda_i^*(\beta).
\]

Comme le problème d’Ising inverse est très difficile à résoudre en toute généralité, on va chercher une expansion pour des valeurs petites des corrélations. On les multiplie alors toutes pour un paramètre \( \beta \) qui on introduit, de façon à qu’un expansion en série autour de \( \beta = 0 \) corresponde à une série en petites corrélations. L’équation (15) s’écrit alors

\[
S(\{m_i\}, \{\lambda_i\}; \{m_i\}, \{\beta c_{ij}\}) = \log \sum_{\{\sigma_i\}} e^{U(\{\sigma_i\})}.
\]

On cherche maintenant à trouver une expansion de \( S \) au minimum (voir Eq. (16)) pour \( \beta \) petit :

\[
S(\{m_i\}, \{\beta c_{ij}\}) = S^0 + \beta S^1 + \beta^2 S^2 + \ldots,
\]

d’où on pourra extraire aussi des séries pour \( J_{ij}^* \) et \( \lambda_i^* \) utilisant l’éqs. (17) et (18).

La détermination du premier terme de l’expansion de \( S \) est trivial, car quand \( \beta = 0 \) on a des spins décorrélés (qui correspond à des spins indépendants) :

\[
S^0 = -\sum_i \left[ \frac{1 + m_i}{2} \ln \frac{1 + m_i}{2} + \frac{1 - m_i}{2} \ln \frac{1 - m_i}{2} \right].
\]

Pour trouver les termes non-triviaux de l’entropie, on procède de la manière suivante : d’abord, on définit un potentiel \( U \) sur les configurations de spins par (noter le nouveau terme à la fin)

\[
U(\{\sigma_i\}) = \sum_{i<j} J_{ij}^*(\beta) [(\sigma_i - m_i)(\sigma_j - m_j) - \beta c_{ij}] + \sum_i \lambda_i^*(\beta)(\sigma_i - m_i)
\]

\[
+ \sum_{i<j} c_{ij} \int_0^\beta d\beta' J_{ij}^*(\beta'),
\]

et une nouvelle entropie (à comparer avec éq. (15))

\[
\tilde{S}(\{m_i\}, \{c_{ij}\}, \beta) = \log \sum_{\{\sigma_i\}} e^{U(\{\sigma_i\})}.
\]

RÉSUMÉ DÉTAILLÉ
Notez que la valeur de $U$ dépend de la valeur des couplages $J_{ij}^*(\beta')$ à tous les valeurs de $\beta' < \beta$ et pas seulement pour la valeur de $\beta$ pour laquelle on veut calculer $U$. $S$ et $\tilde{S}$ se relient par

$$S(\{m_i\}, \{c_{ij}\}, \beta) = \tilde{S}(\{m_i\}, \{c_{ij}\}, \beta) - \sum_{i<j} c_{ij} \int_0^\beta d\beta' J_{ij}^*(\beta') .$$  \hspace{1cm} (24)

L’expression de $\tilde{S}$ a été choisie de sorte qu’elle soit indépendante de $\beta$, comme un petit calcul permet de le vérifier

$$\frac{d\tilde{S}}{d\beta} = \frac{\partial \tilde{S}}{\partial \beta} = -\sum_{i<j} c_{ij} J_{ij}^*(\beta) + \sum_{i<j} c_{ij} J_{ij}^*(\beta) = 0 .$$  \hspace{1cm} (25)

Notez que cela est valable pour toute valeur de $\beta$, d’où $\tilde{S}$ est constante et égal à sa valeur en $\beta = 0$, $S^0$, donnée par l’éq. (21).

On utilise alors le fait que $\tilde{S}$ est indépendant de $\beta$ pour écrire des équations d’auto-consistence pour les dérivés de $S$. Par exemple, pour déterminer $S^1$, on écrit

$$S^1 = \left[ \frac{\partial S}{\partial \beta} \right]_0 = \left[ \frac{\partial \tilde{S}}{\partial \beta} \right]_0 - \sum_{i<j} c_{ij} J_{ij}^*(0) ,$$  \hspace{1cm} (26)

où on a utilisé que $J_{ij}^*(0) = 0$ qui découle du fait que à température nulle les spins sont découpés.

Pour des ordres plus élevés, on doit procéder ordre par ordre. Pour trouver $S^k$ en ayant déjà calculé $S^p$ pour tout $p < k$, on démarre avec l’équation $\left[ \frac{\partial^k \tilde{S}}{\partial \beta^k} \right]_0 = 0$, égalité conséquence de l’éq. (25). Après un calcul explicite de la dérivée, on se retrouvera avec une équation du type

$$\left[ \frac{\partial^k \tilde{S}}{\partial \beta^k} \right]_0 = -S^k + Q_k = 0 ,$$  \hspace{1cm} (27)

où $Q_k$ est une expression qui dépend des magnétisations, corrélations et des dérivés à l’ordre $p < k - 2$ en zéro des couplages $J_{ij}$ et des champs $\lambda_i^*$. En utilisant les éqs. (17) et (18), on peut trouver ces dérivés des couplages et des champs en fonction des valeurs déjà connus de $S^p$ pour $p < k$ et avoir une expression explicite pour $Q_k$ et donc pour $S^k$. Le résultat final pour $S$ est donc

$$S = -\sum_{i,j} \left[ \frac{1+m_i}{2} \ln \frac{1+m_i}{2} + \frac{1-m_i}{2} \ln \frac{1-m_i}{2} \right] + \frac{2}{3} \beta^3 \sum_{i<j} K_{ij}^3 m_i m_j L_i L_j$$
$$+ \frac{\beta^4}{6} \sum_{i<j} K_{ij}^4 \left[ 1 - 3m_i^2 - 3m_j^2 - 3m_i^2 m_j^2 \right] L_i L_j$$
$$- \frac{\beta^2}{2} \sum_{i<j} K_{ij}^2 L_i L_j$$
$$+ \beta^3 \sum_{i<j<k} K_{ij} K_{jk} L_i L_j L_k$$
$$- \frac{\beta^4}{8} \sum_{i,j,k,l} K_{ij} K_{jk} K_{kl} L_i L_j L_k L_l$$
$$+ O(\beta^5) .$$  \hspace{1cm} (28)
Les couplages sont données par
\[ J_{ij}^o (\{c_{kl}\}, \{m_i\}, \beta) = \beta K_{ij} - 2\beta^2 m_i m_j K_{ij}^2 - \beta^2 \sum_k K_{jk} K_{ki} L_k + \frac{1}{3} \beta^3 K_{ij}^3 [1 + 3m_i^2 + 3m_j^2 + 9m_i^2 m_j^2] + \beta^3 \sum_{k \neq i, j} K_{ij} (K_{jk}^2 L_j + K_{ki}^2 L_i) L_k + \beta^3 \sum_{k \neq i, j} K_{jk} K_{kl} K_{li} L_i L_l + O(\beta^4), \]

(29)

et le champs \( h \) par
\[ h_i^o (\{c_{ij}\}, \{m_i\}, \beta) = \frac{1}{2} \ln \left( \frac{1 + m_i}{1 - m_i} \right) - \sum_j J_{ij}^o m_j + \beta^2 \sum_{j \neq i} K_{ij}^2 m_i L_j - \frac{2}{3} \beta^4 (1 + 3m_i^2) \sum_{j \neq i} K_{ij}^3 m_j L_j - 2\beta^4 m_j \sum_{j < k} K_{ij} K_{jk} K_{kl} L_j L_k + 2\beta^4 m_i \sum_{j < k} K_{ij}^4 L_j [1 + m_i^2 + 3m_j^2 + 3m_i^2 m_j^2] + \beta^4 m_i \sum_{j \neq i} \sum_{j \neq i} K_{ij}^2 K_{ji}^2 L_i L_j + O(\beta^5). \]

(30)

Dans ces expressions on a utilisé les notations
\[ L_i = \langle (\sigma_i - m_i)^2 \rangle_0 = 1 - m_i^2, \]

(31)
qui est la déviation standard d’un spin indépendant \( m_i \) et
\[ K_{ij} = \delta_{ij} \frac{\langle (\sigma_i - m_i) (\sigma_j - m_j) \rangle_0}{\langle (\sigma_i - m_i)^2 \rangle_0 \langle (\sigma_j - m_j)^2 \rangle_0} = \delta_{ij} \frac{c_{ij}}{L_i L_j}, \]

(32)

où \( \delta_{ij} \) est le symbole de Kronecker.

Malheureusement, on a vérifié que la qualité d’inférence obtenue par cette formule se dégrade très rapidement quand on sort de son limite de validité \( c_{ij} \ll 1 \). Pour améliorer son stabilité, on a remarqué que les trois derniers termes de l’éq. (28) peuvent s’écrire de la forme d’une série alterné
\[ -\frac{\beta^2}{4} \text{Tr}(M^2) + \frac{\beta^3}{6} \text{Tr}(M^3) - \frac{\beta^4}{8} \text{Tr}(M^4), \]

(33)

où \( M \) est la matrice définie par \( M_{ij} = K_{ij} \sqrt{L_i L_j} \). Comme \( K_{ii} = 0 \), on a que \( \text{Tr} M = 0 \), donc les trois derniers termes s’écrivent
\[ S^{\text{loop}} = \frac{1}{2} \text{Tr} \left( \beta M - \frac{\beta^2}{2} M^2 + \frac{\beta^3}{3} M^3 - \frac{\beta^4}{4} M^4 \right) = \text{Tr} [\log(1 + \beta M)] + O(\beta^5) = \log [\det(1 + \beta M)] + O(\beta^5) \]

(34)
Cette expression peut aussi être retrouvée comme une conséquence de l’éq. (9), ce qui montre qu’elle correspond à une approximation du type “champs moyen” de l’entropie. En outre, si on remplace les trois derniers termes de l’éq. (28) par cette expression, on voit une nette amélioration de la stabilité de l’inférence. Cela s’explique car très probablement les termes d’ordre supérieure à $O(\beta^5)$ du développement de $\log[\det(1 + \beta M)]$ sont contenus dans l’expansion de $S$, et les développer en série correspond à une série alternée, divergente pour des valeurs modérément grands de $c_{ij}$.

Comme l’expression de champs moyen a pu améliorer considérablement la stabilité de l’expansion, on a cherché à intégrer une autre approximation possible du problème : l’approximation de pairs indépendants, dans laquelle on examine chaque pair de sites $i$ et $j$ comme un système composé de juste deux spins. Utilisant cette expression et l’approximation de champs moyen décrite dans le paragraphe précédent, on obtient

\[
S^{2\text{spin} + \text{loop}} = \sum_i S^{1\text{spin}}_i + \sum_{i<j} \left[ S^{2\text{spin}}_{ij} - S^{1\text{spin}}_i - S^{1\text{spin}}_j \right] + S^{\text{loop}} - \frac{1}{2} \sum_{i<j} \log(1 - K^2_{ij} L_i L_j).
\]

où

\[
S^{2\text{spin}}_{ij} = S^{1\text{spin}}_i + S^{1\text{spin}}_j + \frac{1}{4} \log \left[ 1 + \frac{c_{ij}}{(1 - m_i)(1 - m_j)} \right] \left[ c_{ij} + (1 - m_i)(1 - m_j) \right] + \frac{1}{4} \log \left[ 1 - \frac{c_{ij}}{(1 - m_i)(1 + m_j)} \right] \left[ c_{ij} - (1 - m_i)(1 + m_j) \right] + \frac{1}{4} \log \left[ 1 - \frac{c_{ij}}{(1 + m_i)(1 - m_j)} \right] \left[ c_{ij} - (1 + m_i)(1 - m_j) \right] + \frac{1}{4} \log \left[ 1 + \frac{c_{ij}}{(1 + m_i)(1 + m_j)} \right] \left[ c_{ij} + (1 + m_i)(1 + m_j) \right],
\]

et

\[
S^{1\text{spin}}_i = - \left[ \frac{1 + m_i}{2} \ln \frac{1 + m_i}{2} + \frac{1 - m_i}{2} \ln \frac{1 - m_i}{2} \right].
\]

Cette expression est équivalente à l’éq. (28) (ils ne diffèrent que en termes d’ordre $O(\beta^5)$ ou plus), mais elle est beaucoup plus stable numériquement. La formule pour $J_{ij}^*$ qui se déduit de cette expression est

\[
J_{ij}^*(2\text{spin}+\text{loop}) = J_{ij}^*\text{loop} + J_{ij}^*\text{2-spin} - \frac{K_{ij}}{1 - K^2_{ij} L_i L_j},
\]
où

\[ J_{ij}^{(2\text{-spin})} = \frac{1}{4} \ln \left[ 1 + K_{ij}(1 + m_i)(1 + m_j) \right] \\
+ \frac{1}{4} \ln \left[ 1 + K_{ij}(1 - m_i)(1 - m_j) \right] \\
- \frac{1}{4} \ln \left[ 1 - K_{ij}(1 - m_i)(1 + m_j) \right] \\
- \frac{1}{4} \ln \left[ 1 - K_{ij}(1 + m_i)(1 - m_j) \right] \] (39)

et

\[ J_{ij}^{\text{loop}} = \frac{1}{\sqrt{(1 - m_i^2)(1 - m_j^2)}} \left[ M(M + 1)^{-1} \right]_{ij}. \] (40)

**Inférence d’un modèle de Hopfield**

Dans la partie précédente, on s’est intéressé à un modèle d’Ising généralisé sans préciser la forme des couplages. Maintenant, on s’intéresse au cas particulier d’un modèle de Hopfield. Il y a plusieurs avantages d’utiliser ce modèle : d’abord, il existe d’expériences de enregistrement multi-neurones où on ne cherche pas à trouver des couplages entre les neurones mais d’en extraire des patterns. Deuxièmement, on s’attend que diminuer le nombre de degrés de liberté du problème rend la procédure d’inférence plus stable. Finalement, le modèle de Hopfield peut être résolu analytiquement, d’où on espère avoir un meilleur contrôle des erreurs d’inférence.

Notez qu’en principe on pourrait procéder par d’abord inférer la matrice \( \{J_{ij}\} \) des couplages pour ensuite la diagonaliser pour trouver un ensemble de patterns. Le problème de cette approche est qu’elle n’est pas optimale d’un point de vue Bayesian : les patterns trouvés ne seront pas forcément ceux qui maximisent la probabilité a posteriori. Cela est particulièrement problématique quand la supposition de que le système qu’on étudie est décrit par un modèle de Hopfield est juste une approximation.

Dans cette partie on va avoir deux buts : premièrement, on va chercher une formule permettant d’inférer les patterns en fonction des données. Ensuite, on va s’intéresser à estimer le nombre de fois qu’on doit mesurer le système pour avoir une bonne inférence.

Premièrement, on remarque que trouver les patterns qui mieux rendent compte d’une séquence de données est un problème mal posé, car il y a plusieurs ensembles de patterns qui peuvent décrire le même système. Supposons pour exemple le cas de deux patterns (\( p = 2 \)) :

\[ H = N \left( \frac{1}{N} \sum_i \xi_1^i \sigma_i \right)^2 + N \left( \frac{1}{N} \sum_i \xi_2^i \sigma_i \right)^2. \] (41)

Si l’on définit un nouveau ensemble de patterns donné par \( \tilde{\xi}_i^1 = \xi_1^i \cos \theta + \xi_2^i \sin \theta \)
et \( \tilde{\xi}_i^2 = -\xi_i^1 \sin \theta + \xi_i^2 \cos \theta \), le nouveau Hamiltonien est

\[
\tilde{H} = N \left[ \frac{1}{N} \sum_i (\xi_i^1 \cos \theta + \xi_i^2 \sin \theta) \sigma_i \right]^2 + N \left[ \frac{1}{N} \sum_i (-\xi_i^1 \sin \theta + \xi_i^2 \cos \theta) \sigma_i \right]^2,
\]

\( (42) \)

\[
= H. \quad (43)
\]

En général, si on a \( p \) patterns, faire une rotation des patterns en \( p \) dimensions ne change pas le Hamiltonien du système. On dit que le système possède une invariance de gauge. Alors, pour rendre le problème d’inférence bien posé on doit soit lever cette dégénérescence en additionnant des contraintes pour lever les \( p(p-1)/2 \) degrés de liberté, soit additionner un prior \( P_0 \) dans notre probabilité Bayesienne. Pour des raisons techniques, on va se concentrer sur la première solution.

Pour pouvoir développer un méthode d’inférence, il est nécessaire de traiter séparément le cas où le système est dans une phase ferromagnétique et le cas d’une phase paramagnétique. Dans le premier cas, on va supposer que les données qu’on dispose pour faire l’inférence sont des mesures des configurations du système. On suppose de plus que ces mesures sont une réalisation de la loi de Boltzmann. Comme les minimum de l’énergie libre correspondent à des configurations magnétisées selon un des patterns [Amit 85a], on suppose qu’on a mesuré \( l_1 \) configurations magnétisées selon le premier pattern, \( l_2 \) selon le deuxième et ainsi de suite. Dans ce cas, si on estime à partir des mesures la corrélation entre deux sites, on a

\[
C_{ij} = \frac{1}{L} \sum_i \sigma_i^l \sigma_j^l = \sum_{k=1}^p \frac{1}{L} \sum_{l \in l_k} \sigma_i^l \sigma_j^l \approx \frac{1}{L} \sum_{k=1}^p l_k m_i^k m_j^k + O(1/N), \quad (44)
\]

où

\[
m^k = \frac{1}{N} \sum_i \xi^k_i \tanh(m_k \xi^k_i), \quad (45)
\]

et

\[
m_i^k = \tanh(m^k \xi_i^k), \quad (46)
\]

d’où on peut aisément inférer les patterns en diagonalisant la matrice \( C_{ij} \). Notez que cette procédure choisi implicitement un gauge tel que

\[
\sum_i \tanh(m^k \xi_i^k) \tanh(m^{k'} \xi_i^{k'}) = 0, \quad \text{avec} \ k \neq k'. \quad (47)
\]
Le cas paramagnétique est plus intéressant, mais plus complexe. D’abord, comme on cherche un système dans une phase où il n’est pas magnétisé selon aucun pattern, on suppose qu’il existe un champs externe suffisamment fort pour que les magnétisations \( m_i \) soient dominées par le champs externe locale \( h_i \). Aussi, pour faciliter les calculs qui suivent, on remplace le Hamiltonien habituel du modèle d’Hopfield (éq. (5)) par
\[
H = -\frac{1}{N} \sum_{\mu=1}^{p} \sum_{i<j} \xi^\mu_i \xi^\mu_j (\sigma_i - \tanh h_i)(\sigma_j - \tanh h_j) - \sum_i h_i \sigma_i. \tag{48}
\]
Ce Hamiltonien permet de retrouver l’éq. (5) par une translation du champs externe :
\[
h_i \rightarrow h_i - \sum_{\mu \neq i} \sum_{j} \xi^\mu_i \xi^\mu_j \tanh h_j. \tag{49}
\]
Utilisant le théorème de Bayes (eq. (10)), on a alors
\[
P(\{\xi^\mu_i\}|\{\sigma^l_i\}) = \frac{P_0(\{\xi^\mu_i\})}{Z(\{\xi^\mu_i\})} \times \prod_{l=1}^{L} \exp \left[ \frac{\beta}{N} \sum_{\mu=1}^{p} \sum_{i<j} \xi^\mu_i \xi^\mu_j (\sigma_i^l - \tanh h_i)(\sigma_j^l - \tanh h_j) + \beta \sum_i h_i \sigma_i^l \right]. \tag{50}
\]
On voit que cette probabilité ne dépend que des valeurs mesurées des corrélations et magnétisations
\[
m_i = \frac{1}{L} \sum_l \sigma_i^l, \quad c_{ij} = \frac{1}{L} \sum_l \sigma_i^l \sigma_j^l - m_i m_j, \tag{51}
\]
donnant
\[
P(\{\xi^\mu_i\}|\{\sigma^l_i\}) = \frac{P_0(\{\xi^\mu_i\})}{Z(\{\xi^\mu_i\})} \exp \left[ \frac{\beta \lambda}{N} \sum_{\mu=1}^{p} \sum_{i<j} \xi^\mu_i \xi^\mu_j c_{ij} + \frac{\beta \lambda}{N} \sum_{\mu=1}^{p} \sum_i \xi^\mu_i \xi^\mu_j (m_i - \tanh h_i)(m_j - \tanh h_j) + \beta \sum_i h_i m_i \right]. \tag{52}
\]
Pour optimiser cette quantité par rapport aux patterns \( \xi^\mu_i \), il est nécessaire d’écrire explicitement un développement de log \( Z \) pour \( N \) grand, ce qui est fait dans l’Appendice D. La minimisation en soit étant assez technique, elle peut être consultée au chapitre 6. Le résultat final, à l’ordre dominante en \( N \), est
\[
h_i^0 = \tanh^{-1} m_i. \tag{53}
\]
et
\[
\xi_i^{\mu,0} = \sqrt{1 - \frac{1}{\lambda^\mu}} \frac{\nu_i^{\mu}}{\sqrt{1 - \tanh^2 h_i^0}}, \tag{54}
\]
RÉSUMÉ DÉTAILLÉ

où $\lambda_\mu$ et $v^\mu$ sont, respectivement, le $\mu$-ème plus grande valeur propre de la matrice $M$ et sont vecteur propre associé, où $M$ est donnée par

$$M_{ij} = \frac{c_{ij}}{\sqrt{1 - \tanh^2 h_i^0} \sqrt{1 - \tanh^2 h_j^0}}.$$  

(55)

C’est intéressant de noter que cette expression implique que

$$J_{ij} = \sum_\alpha \frac{\lambda_\alpha - 1}{\lambda_\alpha} \frac{v^\alpha_i v^\alpha_j}{\sqrt{(1 - m_i^2)(1 - m_j^2)}} \left[ M^{-1}(M - 1) \right]_{ij},$$  

(56)

qui est exactement l’expression déjà trouvée dans l’éq. (40) pour le modèle d’Ising généralisé.

Dans le but de trouver une expression inédite pour l’inférence, on a aussi déterminé les corrections sous-dominantes correspondant à l’éq. (54). Les détails se trouvent dans le chapitre 6. Malheureusement, l’expression trouvée est très sensible à des erreurs aléatoires sur les magnétisations et corrélations mesurées, donc peu utile pour des données réelles.

Un autre problème intéressant est de savoir combien de mesures on doit faire d’un système d’Hopfield pour qu’il soit possible d’inférer précisément les valeurs de ses patterns. Pour donner une réponse à ce problème, on a calculé l’entropie de Shannon de la procédure d’inférence, car il est raisonnable de penser que quand $S/N \ll 1$, on peut trouver les patterns avec un erreur faible. On rappelle que l’entropie de Shannon d’une distribution de probabilité $P$ défini sur un ensemble $\Omega$ est

$$S = -\sum_{\omega \in \Omega} P(\omega) \log P(\omega).$$  

(57)

Dans le cas de notre inférence, la probabilité est donné par le théorème de Bayes (eq. (10)) et on suppose que nos patterns ne peuvent valoir que $\pm \sqrt{\beta}$, où $\beta$ est une constante fixe, qu’on associe à une température inverse. On traite d’abord le cas d’un seul pattern. On a alors

$$S[\{\sigma_i^l\}] = -\frac{1}{N[\{\sigma_i^l\}]Z(\beta)^L} \sum_{\{\xi\}} \exp \left( \frac{\beta}{N} \sum_{l=0}^{L} \sum_{i<i,j} \xi_i \xi_j \sigma_i^l \sigma_j^l \right) \times$$

$$\times \left[ -\log (N[\{\sigma_i^l\}]Z(\beta)^L) + \left( \frac{\beta}{N} \sum_{l=0}^{L} \sum_{i<i,j} \xi_i \xi_j \sigma_i^l \sigma_j^l \right) \right].$$  

(58)

où

$$N[\{\sigma_i^l\}] = Z(\beta)^{-L} \sum_{\{\xi\}} \exp \left( \frac{\beta}{N} \sum_{l=0}^{L} \sum_{i<i,j} \xi_i \xi_j \sigma_i^l \sigma_j^l \right).$$  

(59)

Notez que $S$ dépend explicitement des mesures $\{\sigma_i\}$. Par contre, il est naturel d’espérer que pour un système assez grand et pour un nombre pas trop petit de
mesures, l’entropie va dépendre plus des caractéristiques du système que des détail
des mesures effectuées. On s’intéresse alors à calculer \( \langle S \rangle \), où la moyenne est effectué
par rapport à la probabilité de Boltzmann de mesurer les configurations \( \{\sigma_i\} \), en
supposant que le système que les a généré est décrit par un modèle de Hopfield.

Le comportement de \( \langle S \rangle \) est très différent pour les deux phases du système.
S’il est dans une phase ferromagnétique, l’entropie décroît exponentiellement avec le
nombre de mesures \( L \). On peut trouver les détails du calcul et l’expression analytique
de l’entropie dans le chapitre 7. Les résultats sont représentés dans le graphique suivant :

![Figure 0.4: Entropie par spin en fonction du nombre de mesures \( L \) pour \( \beta = 1.1 \). Notez
le comportement asymptotique \( \langle S \rangle \approx C e^{-\gamma L} \) où \( \gamma = \log \cosh(\beta m) \).](image)

Ce résultat montre que le nombre de mesures nécessaires pour inférer le pattern
du système est une grandeur intensive du système, ie, il reste finit quand la taille du
système tend vers l’infini.

Quand le système est dans la phase paramagnétique, cette situation se modifie.
En fait, il faut un nombre de mesures \( L = \alpha N \) proportionnel à la taille du système
pour pouvoir inférer le pattern. Comme on peut voir dans le chapitre 7, les calculs
sont aussi plus complexes, et on est obligé d’utiliser des méthodes des systèmes
désordonnées (notamment la méthode des répliques) pour trouver une expression
analytique pour l’entropie moyenne. Un graphique illustrant les résultats obtenus se
trouve dans la Fig. 0.5.
Figure 0.5: Entropie par spin comme fonction de $\alpha$ pour $\beta = 0.5$. La ligne solide correspond à la solution analytique trouvé dans le chapitre 7 et les points correspondent à des résultats numériques.

Finalement, pour le cas de plusieurs patterns dans la phase paramagnétique, on retrouve que l’entropie de l’inférence de chaque pattern décroit comme l’entropie du système où on n’a qu’un seul pattern (Fig. 0.5).
Part I

Introduction
Chapter 1

Biological motivation and related models

In the last years, we have seen a remarkable growth in the number of experiments in biology that generate an overwhelming quantity of data. In several cases, like in neuron assemblies, proteins and gene networks, most of the data analysis focuses on identifying correlations between different parts of the system. Unfortunately, identifying the correlations on their own is only of limited scientific value: most of the underlying properties of the system can only be understood by describing the interaction between their different parts. This work finds its place in developing statistical mechanics tools to derive these interactions from measured correlations.

In this introductory chapter, we present two biological problems that inspired this thesis. First, in section 1.1 we give a brief introduction to neurons and how they exchange information in a network. We discuss some experiments where the individual activity of up to a hundred interacting neurons is measured. For this example, the neurons are the interacting parts and they interact via synapses, whose details are very hard to extract experimentally.

In a second part, we discuss some recent works on the analysis of families of homologous proteins, i.e., proteins that share an evolutionary ancestry and function. The variation of the amino acids inside these families are highly correlated which is deeply related to the biological function of the proteins. In general terms, we can say thus that individual amino acid variations play the role of interacting parts with very complicated interactions, as we will see in section 1.2.

1.1 Neuron networks

One of the most important scientific questions of the 21st century is the understanding of the brain. It is widely accepted that its complexity is due to the organization of neurons in complex networks. If we consider, for example, the human brain, we can count about $10^{11}$ neurons connected by about $10^{14}$ connections. Even much simpler organisms like the *Drosophila melanogaster* fruit fly counts about 100,000 neurons.

A typical neuron can be schematized as a cell composed of three parts: the cell body, dendrites and one axon (see Fig. 1.1). A dendrite is composed of several...
branches in a tree-like structure and is responsible for receiving electric signals from other neurons. The axon is a longer, ramified single filament, responsible for sending electrical signals to other neurons. A connexion between two neurons in most cases happens between an axon and a dendrite\(^1\). We call such connections *synapses*.

![Figure 1.1: Schema of a neuron [Alberts 02]. The diameter of the cell body is typically of the order of 10 \(\mu m\), while the length of dendrites and axons varies considerably with the neuron’s function.](image)

Like most cells, neurons have an electrical potential difference between their cytoplasm and the extracellular medium. This potential difference is regulated by the exchange of ions (such as \(Na^+\) and \(K^+\)) through the cell membrane, which can be done in two ways: passively, by proteins called *ion channels* that selectively allow the passage of a certain ion from the most concentrated medium to the least and, conversely, actively by proteins called *ion pumps* that consume energy to increase the ion concentration difference.

A typical neuron has a voltage difference of about \(-70\ mV\) when it is not receiving any signal from other neurons. We call this voltage the *resting potential* of the neuron. If the voltage of a neuron reaches a threshold (typically about \(-50\ mV\)), a feedback mechanism makes ion channels of the membrane to open, making the voltage increase rapidly up to \(100\ mV\) (depending on the neuron type), after which it reaches saturation and decreases quickly, recovering the resting potential after a few \(\text{ms}\) (see Fig. 1.2). We call this process *firing* or *spiking*. One important characteristic of the spikes is that once the voltage reaches the threshold, its shape and its intensity do not depend on the details of how the threshold was attained.

\(^1\)As common in biology, such simplified description of a neuron and synapses has exceptions. Some axons transmit signals while some dendrites receive them. We also find axon-axon and dendrite-dendrite synapses [Churchland 89].
When a neuron fires, its axon releases neurotransmitters at every synapse. Those neurotransmitters make ions channels in the dendrites open, changing the membrane potential of the neighboring neurons. Different neurotransmitters cause the opening of different ion channels, allowing for both excitatory synapses, which increase the neuron potential, and inhibitory synapses which decrease it. Since synapses can be excitatory or inhibitory to different degrees, most models define a synaptic weight with the convention that excitatory synapses have a positive synaptic weight and inhibitory synapses have a negative one, as we will see in section 1.1.2. Another important feature of synapses is that they are directional: if a neuron A can excite a neuron B, the converse is not necessarily true: neuron B might inhibit neuron A, or simply not be connected to it at all.

1.1.1 Multi-neuron recording experiments

While much progress has been done in describing individual neurons, understanding their complex interaction in a network is still an unsolved problem. One of the most promising advances in this area was the development of techniques for recording simultaneously the electrical activity of several cells individually [Meister 94].

In these experiments, a microarray counting as many as 250 electrodes is placed in contact with the brain tissue. The potential of each electrode is recorded for up to a few hours. Each one of the electrodes might be affected by the activity of more than one neuron and, conversely, a single neuron might affect more than one electrode. Thus, a computational-intensive calculation is needed to factorize the signal as the sum of the influence of several different neurons. This procedure is known as Spike Sorting [Peyrache 09] and its results are spike trains, i.e., time sequences of the state of each cell: firing or at rest. An example of a set of spike trains can be seen in Fig. 1.3.
Figure 1.3: Typical measurement of spike trains [Peyrache 09]. Each line corresponds to a single neuron. Black vertical bars correspond to spikes.

In principle, one should be able to pinpoint the synapses and the synaptic weights from the spike trains. However, extracting this information is a considerable challenge. First of all, it is not possible with current technology to measure every neuron of a network. Thus, experiments measure just a small fraction of the system even if the network is small. That means that all that we can expect to find are effective interactions that depend on all links between the cells that are not measured. Secondly, one cannot naively state that if the activity of two neurons is correlated then they are connected by a synapse. Consider, for example, neurons 7, 22 and 27 of Fig. 1.3, indicated by the red arrows. We can clearly see that there is a tendency for all three of firing at the same time, but distinguishing between the two possible connections shown in Fig. 1.4 is not trivial.

Figure 1.4: Two different possible configurations for three positively correlated neurons.

1.1.2 Models for neuron networks

Before talking about what have already been done to solve this problem and our contribution to it, we present some models for neural networks. We will proceed by first introducing a model that describes rather faithfully real biological networks, the leaky Integrate-and-Fire model. Afterwards, we introduce the Ising model, which is much more tractable analytically. Finally, we will look at the Ising model from a different point of view by studying one particular case of it: the Hopfield model.
Leaky integrate-and-fire model

The leaky integrate-and-fire model, first proposed by Lapicque in 1907 [Lapicque 07, Abbott 99, Gerstner 02, Burkitt 06], is a straightforward modelization of the firing process presented in section 1.1. It supposes that neurons behave like capacitors with a small leakage term to account for the fact that the membrane is not a perfect insulator. Posing $V(t)$ as the function representing the difference of potential between the inside and the outside of the membrane:

$$C \frac{dV}{dt} = - \frac{V(t)}{R} + I(t), \quad (1.1)$$

where $C$ is the capacitance of the neuron, $R$ is the resistance of the cell membrane and $I(t)$ is the total current due to the synapses of neighboring neurons. If we introduce the characteristic time of leakage $\tau = RC$, we can rewrite this equation as

$$\tau \frac{dV}{dt} = -V(t) + RI(t). \quad (1.2)$$

Spikes are modelized solely by their “firing time” $t_f$. This firing time is defined as the moment where the neuron’s potential reaches a firing threshold value $V_{tr}$. Implicitly, it is given by the equation

$$V(t_f) = V_{tr}. \quad (1.3)$$

Every time a neuron spikes, its potential is reset to zero and its synapses produce a signal in the form of some function $f(t)$. We can thus describe the signal $S(t)$ that this neuron send to its neighbors as a function only of the set of firing times $\{t_f^r\}_{r=1,...,N_{\text{spikes}}}$

$$S(t) = \sum_{r=1}^{N_{\text{spikes}}} f(t - t_f^r). \quad (1.4)$$

The choice of the function $f(t)$ can be based on biological measures, mimicking the behavior shown in Fig. 1.2 or can be a simple Dirac-delta function to make calculations easier.

Finally, we can introduce the synaptic weights to model a neuron network with the following equations:

$$\tau_i \frac{dV_i}{dt} = -V_i(t) + \sum_j J_{ij} S_j(t), \quad (1.5)$$

$$V_i(t_{i,r}^{t_f}) = 1, \quad (1.6)$$

$$S_i(t) = \sum_{r=1}^{N_i \text{spikes}} f(t - t_{i,r}^{t_f}), \quad (1.7)$$

where $V_i$ is the potential of the neuron $i$ rescaled so that $V_{tr} = 1$, $t_{i,r}^{t_f}$ is the time of the $r$-th spike of the neuron $i$ and $J_{ij}$ is the matrix of the synaptic weights. Note
that it is usually assumed as an approximation that the function \( f(t) \) is identical for all neurons.

This model is very popular due to its balance between biological accuracy and relative simplicity. It is also very well-suited for computer simulations by the direct integration of its differential equations. On the other hand, while some numerical work has been done on the inference of synaptic weights from spike trains using this model [Cocco 09], it is not very practical for analytical results.

### Generalized Ising model / Boltzmann Machine

The Boltzmann Machine [McCulloch 43] is a model of neuron networks that mimics less well real biological systems than the leaky Integrate-and-Fire model. It is however considerably simpler, being even exactly solvable for some special networks. In this model, the state of a neuron is fully described by a spin variable \( \sigma = \pm 1 \) with the convention of \( \sigma = +1 \) if the neuron is firing and \( \sigma = -1 \) if it is not\(^2\). The dynamics of the system is ignored\(^3\) and we describe only the probability \( P(\{\sigma_1, \ldots, \sigma_N\}) \) of finding the network of \( N \) neurons in a state \( \{\sigma_1, \ldots, \sigma_N\} \), which is given by the Boltzmann weight of a generalized Ising model

\[
P(\{\sigma_1, \ldots, \sigma_N\}) = \frac{1}{Z} e^{-\beta H(\{\sigma_1, \ldots, \sigma_N\})}, \tag{1.8}
\]

with

\[
Z = \sum_{\{\sigma\}} e^{-\beta H(\{\sigma_1, \ldots, \sigma_N\})}, \tag{1.9}
\]

where \( Z \) is the partition function of the model, \( \beta \) is a parameter of the model, that in the context of spins represents the inverse temperature and we introduced the notation

\[
\sum_{\{\sigma\}} = \sum_{\sigma_1=\pm 1} \sum_{\sigma_2=\pm 1} \cdots \sum_{\sigma_N=\pm 1}. \tag{1.10}
\]

The Hamiltonian should take into account the connection between neurons and the fact that some minimum input is needed for the neuron to reach the threshold and fire. The widely used expression is

\[
H(\{\sigma_1, \ldots, \sigma_N\}) = -\frac{1}{2N} \sum_{i,j} J_{ij} \sigma_i \sigma_j - \sum_i h_i \sigma_i, \tag{1.11}
\]

where \( J_{ij} \) corresponds to the synaptic weight and \( h_i \) is a term that models the threshold as a “field” favoring the neuron to be in the rest position.

Two features of this model are particularly pertinent for what follows. First, it is directly defined in the language of statistical physics and allows the use of its framework with no additional complications. Secondly, if one measures the averages \( \langle \sigma_i \rangle \) and the correlations \( \langle \sigma_i \sigma_j \rangle \) of a spike train, the Boltzmann machine arises naturally as a model consistent with these measurements, as we will discuss in more detail.
in section 3.1. On the other hand, a significant shortcoming of this model is that synapses are symmetric, i.e., \( J_{ij} = J_{ji} \), which is not necessarily true in biological systems.

It is important to note that the Hamiltonian shown in Eq. (1.11) can give rise to a rich diversity of behaviors depending on the choice of \( J_{ij} \): ferromagnetism, frustration, glassy systems, etc, as we will see in chapter 2.

**Particular case: Hopfield model**

Until now, we have presented models for neurons in completely arbitrary neuron networks. In this section we will describe a model that uses the same modelization for neurons we presented in the last section but restricts the synaptic weights \( J_{ij} \) to a particular form:

\[
J_{ij} = \sum_{\mu=1}^{p} \xi_{i}^{\mu} \xi_{j}^{\mu},
\]

(1.12)

where \( \xi_{i}^{\mu} \) are real values that we will discuss in the following. This particular case of the generalized Ising model is called the Hopfield model and was proposed to describe a system that stores a given number \( p \) of memories and is capable to retrieve them when given a suitable input. The form shown in Eq. (1.12) was chosen so that the Hamiltonian we saw in Eq. (1.11) can be rewritten as

\[
H = -\frac{1}{2N} \sum_{\alpha=1}^{p} \left( \sum_{i} \xi_{i}^{\alpha} \sigma_{i} \right)^{2}
\]

(1.13)

which has the property that \( \sigma_{i} = \text{sign}(\xi_{i}^{\alpha}) \) is a local energy minimum for every \( \alpha \) if \( p \ll N \) and the patterns are more or less orthogonal.

The interpretation of this model as a model for associative memory comes from the fact that, under certain conditions, if our system has an initial configuration similar to one of the vectors \( \xi^{\mu} \) it will evolve to the configuration \( \sigma_{i} = \text{sign}(\xi_{i}^{\alpha}) \). In this context, we normally call the \( p \) vectors \( \{\xi_{1}^{\alpha}, ..., \xi_{p}^{\alpha}\} \) memories (or patterns). More rigorously, we will see in section 2.4 that in the limit \( N \gg 1 \), the system can retrieve up to \( \alpha_{c} \approx 0.138 \) memories.

The Hopfield model can also be seen as an approximation of the general Boltzmann Machine for a finite-rank \( J \) matrix. Indeed, let’s write the eigenvector decomposition of the matrix \( J \),

\[
J_{ij} = \sum_{\alpha=1}^{N} \lambda_{\alpha} v_{\alpha,i} v_{\alpha,j},
\]

(1.14)

with \( \{\lambda_{\alpha}\} \) and \( \{v_{\alpha,i}\} \) being respectively the eigenvalues and eigenvectors of the matrix \( J \). If we truncate this summation up to the first \( p \) highest eigenvalues and pose \( \xi_{i}^{\alpha} = \sqrt{\lambda_{\alpha}} v_{\alpha,i} \), we find exactly the same equation as Eq. (1.13). On the other hand, the limit of \( p = N \) does not make this approximation exact, since Eq. (1.13) cannot account for negative eigenvalues of the matrix \( J_{ij} \).

This model got a renewed interest when experimentalists started looking for patterns in spike train recording data. A recent experiment with rats made by Peyrache et al. [Peyrache 09] compared the spike activity of neurons in two different
moments: when the rat was looking for food in a maze and when it was sleeping. The main statistical tool used by the authors was the Principal Component Analysis (PCA), i.e., finding the eigenvalues and eigenvectors of the correlation matrix of the measured neuron activity. They showed that the eigenvectors that were the most strongly correlated with neuron activity when the rat was choosing a direction in the maze were revisited during his next sleep. The authors interpreted this finding as the well-known process of memory consolidation during sleep. In part III, we will show that the author’s proceeding of extracting patterns from neural data using the PCA is closely related to fitting spike trains with a Hopfield model.

1.2 Homologous proteins

We say that two different proteins are homologous if they have both a common evolutionary origin [Reeck 87] and a similar sequence, which normally also imply a similar function. The comparison of the proteins of a homologous group gives some valuable insight of which features are really essential for their biological function.

![Figure 1.5: A set of 41 sequences containing SH2 domain. Each line correspond to a different protein and each letter correspond to an amino acid, with conserved ones in bold. These sequences were matched using a multiple sequence alignment software [Edgar 04].](image)

The first step while comparing two or more homologous proteins is to align their sequences in a way that maximizes the number of identical bases (see Fig. 1.5). This procedure is known as Multiple Sequence Alignment (MSA) [Lockless 99]. Since during evolution there could have been insertion or deletion of bases, the optimal alignment will involve adding empty spaces to the alignment in an optimal way, what makes the MSA problem NP-complete, i.e., solving it needs a number of operations that grows exponentially with the number of sequences.

It is natural to suppose that the most important parts of a protein should vary significantly less than the least important ones, since most mutations in important parts yield non-functional proteins. Consequently, the most straightforward analysis one can do with aligned sequences is to evaluate how the distribution of amino acids in a given position deviates from a random uniform distribution [Capra 07].

While considering each position separately was proved to be useful for identifying functional groups, a much richer behavior was found by considering pairwise correlation between sites. First of all it has been shown that by taking into account both conservation and correlation one can describe more accurately which sites of proteins are essential for its function than by just considering conservation alone [Lichtarge 96].
Secondly, a remarkable experiment by Russ et al. [Russ 05] created artificial proteins by randomly picking amino acids with a probability distribution that reproduced the averages and the pairwise correlations of a group of homologous natural proteins. He showed that these new proteins fold to a native tertiary structure similar to that of the natural proteins of the group. Conversely, he showed that random proteins that were generated \textit{without} taking into account correlations do not fold into a well-defined three-dimensional structure, an essential step for a protein to be functional.

Moreover, an interesting paper by Halabi et al. [Halabi 09] showed that the correlation matrix has a particular structure: the amino acids can be separated in disjoint groups (or \textit{sectors}) that are only correlated to other amino acids inside the same sector. Each sector has a distinct functional role and has evolved practically independently from the others.

Finally, studying the two-basis correlations was shown to be a very good way to infer which pairs of amino acids are spatially close in the three-dimensional structure of the protein [Burger 10]. Yet, some non-trivial work is needed to know if two basis are correlated because they are spatially close one to another or because they are spatially close to a third base, a problem very similar to the one presented in section 1.1.1 for neurons. To solve such a problem, a paper published in 2009 [Weigt 09] proposed a very simplified model to describe a family of proteins composed by $N$ amino acids: it supposes that the proteins that constitute the family are randomly chosen among all possible proteins with length $N$ and that the probability of a given protein is given by:

$$P(A_1, \ldots, A_N) = \frac{1}{Z} \exp \left[ \sum_{i<j} J_{ij}(A_i, A_j) + \sum_i h_i(A_i) \right], \quad (1.15)$$

where $A_i \in \{1, \ldots, 22\}$ describe the $i$-th amino acid of the protein and $J_{ij}(A_i, A_j)$ and $h_i(A_i)$ are real-valued functions. This modelization is very similar to the Ising model we saw above and reduces the problem of finding which basis are actually close in the three-dimensional structure of the protein to the problem of finding which functions $J_{ij}$ and $h_i$ of the Hamiltonian best describe a set of measured two-site correlations.

To sum up, in the same way we saw in section 1.1 for neurons, we are dealing with a large number of correlated data where the pairwise correlation plays a special role. While for neurons we wanted to infer a synaptic network, in this case we would be interested in extracting an expression for the \textit{effective fitness} of the proteins of the group, i.e., a quantity that would say how well a protein performs its biological role as a function of its amino acids sequence.
Chapter 2

Some classical results on Ising-like models

As we have seen in chapter 1, Ising-like models are modelizations of neural networks which are particularly suitable for analytical calculations. In this chapter, we present some classical results for some of these models, such as the Sherrington-Kirkpatrick and the Hopfield model. Since normally most of the behavior of the system can be deduced from the partition function \( Z \), it is normally said that a model is “solved” when one evaluates this quantity explicitly. We start by reminding some results for the Ising model as it was originally defined. In the sequence, we will present for both the Hopfield and the Sherrington-Kirkpatrick models the procedure for evaluating \( Z \) in general lines, since it will be useful later in chapter 6. Indeed, as we will do similar calculations, the comparison with these classical results will be enlightening.

2.1 The Ising model

The original Ising Model was proposed by Wilhelm Lenz and first studied by Lenz’s PhD student Ernst Ising as a simple model for ferromagnetism and phase transitions. This model supposes that the atoms of a magnet are arranged in a lattice and the spin of each atom \( i \) is described by a binary variable \( \sigma_i = \pm 1 \). In addition, it assume that each atom interacts only with its closest neighbors, so we can write the energy of the system as

\[
H = -J \sum_{\langle i,j \rangle} \sigma_i \sigma_j + h \sum_i \sigma_i ,
\]

where \( J \) is the energy of the interaction between neighbors, favoring spins to be aligned and \( h \) corresponds to an external magnetic field. The notation \( \sum_{\langle i,j \rangle} \) means summing over all the pairs \( i, j \) where \( i \) and \( j \) are closest neighbors.

We suppose that the probability of the different states of the system is given by the Boltzmann distribution

\[
P(\{\sigma_1, ..., \sigma_N\}) = \frac{1}{Z} e^{-\beta H(\{\sigma_1, ..., \sigma_N\})},
\]
with
\[ Z = \sum_{\{\sigma\}} e^{-\beta H(\{\sigma_1, ..., \sigma_N\})}, \]  
(2.3)
where \( \beta = \frac{1}{k_B T} \), \( k_B \) is the Boltzmann constant and \( T \) is the temperature. In the following, unless explicitly stated, we will absorb the constant \( \beta \) in the Hamiltonian to make notations lighter, but we might still use the terms “high temperature” and “low temperature” to refer to the magnitude of \( J \) and \( h \) in temperature units. The *thermal average* of a quantity \( f(\{\sigma_1, ..., \sigma_N\}) \) is given by
\[ \langle f(\{\sigma_1, ..., \sigma_N\}) \rangle = \frac{1}{Z} \sum_{\{\sigma\}} f(\{\sigma_1, ..., \sigma_N\}) e^{-H(\{\sigma_1, ..., \sigma_N\})}. \]
(2.4)

The concept of “closest neighbors” depends both on the form of the lattice and its dimension. The one-dimensional case, where spins are arranged on a line, was solved right after the model was proposed and shown to present no phase transitions. With a brief calculation [Le Bellac 02], one can also find the two-site correlation in the \( h = 0 \) case,
\[ \langle \sigma_i \sigma_j \rangle = (\tanh J)^{|i-j|}. \]
(2.5)

In two dimensions, the Ising model was solved after a mathematical *tour de force* [Onsager 44] and shown to have a second-order phase transition that separates a ferromagnetic phase (where magnetizations – given by \( m = \langle \sigma_i \rangle \) – are non zero) from a paramagnetic phase of zero magnetization.

Another case that shows a phase transition is the *infinite dimension* limit of the model, where the lattice is a complete graph, i.e., each spin is neighbor of every other one. In this case the Hamiltonian is given by
\[ H = -\frac{J}{N} \sum_{i < j} \sigma_i \sigma_j - h \sum_i \sigma_i, \]
(2.6)
where we did a rescaling of \( J \to J/N \) to keep the Hamiltonian extensive. It is a classical calculation to show that in this case the magnetization is given by the implicit equation
\[ m = \tanh(Jm + h), \]
(2.7)
which presents a ferromagnetic/paramagnetic phase transition on \( J = 1 \). We can also obtain the connected correlation of the model:
\[ \langle \sigma_i \sigma_j \rangle - \langle \sigma_i \rangle \langle \sigma_j \rangle = \frac{1}{N} \frac{J(1-m^2)^2}{1 - J(1-m^2)}. \]
(2.8)

Besides the different choices of lattice, there are several possible generalizations of the model expressed by small changes in the Hamiltonian (2.1). For example, one can add interactions between three sites with a term \( J \sum_{i,j,k} \sigma_i \sigma_j \sigma_k \). Of particular interest for this work is the generalization of the lattice by defining arbitrary two-site interactions and making the external field site-dependant:
\[ H = -\sum_{i<j} J_{ij} \sigma_i \sigma_j - \sum_i h_i \sigma_i, \]
(2.9)
as we have already seen in section 1.1.2. In this case, Ising models are also a privileged ground for the modeling of disordered systems for two main reasons: first, they are specially convenient for obtaining exact results and, secondly, the Ising model and all its generalizations are particularly suitable for computer simulations using Monte-Carlo methods [Krauth 06], with systems of up to a thousand spins being tractable.

We will now look at some particular cases.

2.2 Sherrington-Kirkpatrick model

The Sherrington-Kirkpatrick model (or SK model) is a simplified model of disordered systems [Sherrington 75]. In this model, the Hamiltonian is given by

\[ H = -\sum_{i<j} \left( J_{ij} + \frac{J_0}{N} \right) \sigma_i \sigma_j, \]  

(2.10)

where \( J_0 \) corresponds to a ferromagnetic component of the system. Each \( J_{ij} \) is chosen randomly with a Gaussian distribution

\[ P(J_{ij}) = \frac{1}{\sqrt{2\pi J^2}} e^{-\frac{J_{ij}^2}{2J^2}}, \]  

(2.11)

where \( J \) represents the typical magnitude of couplings. To work with intensive quantities, we pose \( J = \tilde{J}/\sqrt{N}, \tilde{J} \) being \( O(1) \). We will denote the average of a value \( f \) according to the distribution of \( J_{ij} \) by \( \overline{f} \), not to confound with the thermal average \( \langle f \rangle \).

In the following we will look into the technical details of the solution of this model for two reasons. First, there are some interesting concepts that emerge and secondly, we will do a similar calculation in part III.

2.2.1 Replica solution of the SK model

As we discussed in the beginning of the chapter, to solve this model we need to evaluate the free-energy \( F = -\log Z \), a quantity that depends on the particular sampling of \( J_{ij} \). Since the free-energy is extensive, we expect it to be self-averaging, i. e., to converge to its average value in respect to \( J_{ij} \) when one increases the size of the system. We would like thus to evaluate \( \log Z \) to find the typical behavior of the system. Since evaluating \( Z^n \) is much easier than evaluating \( \log Z \), we will first evaluate \( Z^n \) for every integer \( n \) and consider that

\[ \log Z = \lim_{n \to 0} \frac{Z^n}{n}. \]  

(2.12)

This procedure, known as the replica trick [Edwards 75], is useful for correctly solving several statistical mechanics problems but is not mathematically rigorous: the limit depends on the behavior of \( Z^n \) for \( n \ll 1 \) which is not unambiguously defined as an analytic continuation of the integer values of \( Z^n \).
Initially, we have

$$Z^n = \sum_{\{\sigma\}} \exp \left[ \sum_{\alpha=1}^n \sum_{i<j} \left( J_{ij} + \frac{J_0}{N} \right) \sigma_i^\alpha \sigma_j^\alpha \right],$$

(2.13)

which is just the partition function of \(n\) identical, non-interacting copies of the system. Evaluating its average, we obtain

$$\bar{Z}^n = \sum_{\{\sigma\}} \exp \left[ \sum_{\alpha=1}^n \sum_{i<j} \frac{J_0}{N} \sigma_i^\alpha \sigma_j^\alpha \right. + \left. \frac{1}{2} \sum_{\alpha=1}^n \sum_{i<j} \left( J_0 \sigma_i^\alpha \sigma_j^\alpha + J \sum_{\alpha=1}^n \sigma_i^\alpha \sigma_j^\alpha \right) \right],$$

(2.14)

where in the last passage we neglected a term subdominant in \(N\).

Using an integral transform, Eq. (2.14) can be written as

$$\bar{Z}^n \approx e^{N^2 J^2 n/4} \int \prod_{1 \leq \alpha < \gamma \leq n} \frac{d q_{\alpha \gamma}}{\sqrt{2 \pi N^{-1}}} \prod_{\alpha=1}^n \frac{d m_\alpha}{\sqrt{2 \pi N^{-1}}} \sum_{\{\sigma\}} e^U,$$

(2.15)

where \(U\) is given by

$$U = -\frac{N}{2} \sum_{1 \leq \alpha < \gamma \leq n} q_{\alpha \gamma}^2 - \frac{N}{2} \sum_{\alpha=1}^n m_\alpha^2 + \sqrt{J_0} \sum_{\alpha=1}^n m_\alpha \sum_{i} \sigma_i^\alpha + \bar{J} \sum_{1 \leq \alpha < \gamma \leq n} q_{\alpha \gamma} \sigma_i^\alpha \sigma_i^\gamma.$$

(2.16)

Note that with this writing the sites are decoupled. Consequently we have

$$\sum_{\{\sigma\}} e^U = \left\{ \sum_{\{\sigma\}} \exp \left[ -\frac{1}{2} \sum_{1 \leq \alpha < \gamma \leq n} q_{\alpha \gamma}^2 - \frac{1}{2} \sum_{\alpha=1}^n m_\alpha^2 + \sqrt{J_0} \sum_{\alpha=1}^n m_\alpha \sum_{i} \sigma_i^\alpha + \bar{J} \sum_{1 \leq \alpha < \gamma \leq n} q_{\alpha \gamma} \sigma_i^\alpha \sigma_i^\gamma \right] \right\}^N.$$

(2.17)

Finally we could in principle evaluate the integrals in Eq. (2.15) using the saddle-point approximation. Yet, finding the set of \(q_{\alpha \gamma}\) and \(m_\alpha\) that constitute the saddle point for an arbitrary \(n\) is non trivial.

To find the maximum of Eq. (2.17), one classically assumes that all the different copies of the system have identical statistical properties. This is known as the \textit{replica symmetric} ansatz. Mathematically, it corresponds to setting \(q_{\alpha \gamma} = q\) and

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2.2. SHERRINGTON-KIRKPATRICK MODEL
\( m_\alpha = m \). This hypothesis can be shown to yield a good approximation of the free-energy and to correctly find the phase diagram of the model (Fig. 2.1), but for very low temperatures it yields a negative entropy and hence this supposition is clearly unjustified in this regime.

The parameters \( m \) and \( q \) have straightforward physical meanings in the replica-symmetric case: \( m = \langle \sigma_i \rangle \), which means that if \( m \neq 0 \), the system has a preferred magnetization that does not vanish after averaging with respect to the disorder. We say the system is in a ferromagnetic phase. The other parameter \( q \) can be written as \( q = \frac{1}{N} \sum_i \langle \sigma_i \rangle^2 \). When \( m = 0 \) and \( q \neq 0 \), the system has a non-zero magnetization for a giving sampling of \( J_{ij} \), but this magnetization vanishes when averaging with respect to \( J_{ij} \). In this case, we say our system is in a spin glass phase, where the system is frozen in one of the several (random) local minima of the energy. Finally, the case \( q = m = 0 \) correspond to the paramagnetic phase.

The correct saddle-point of equation (2.17) was found in the late 70’s by G. Parisi by defining the value of the matrix \( q_{\alpha\gamma} \) at the saddle-point through an iterative procedure. Note that in the general case, \( q_{\alpha\gamma} \) is the overlap between the replicas \( \alpha \) and \( \gamma \):

\[
q_{\alpha\beta} = \frac{1}{N} \sum_i \sigma_i^\alpha \sigma_j^\beta .
\]  

(2.18)

His solution have a very interesting property: if we consider any three replicas \( \alpha, \gamma \) and \( \rho \) and their overlaps \( q_{\alpha\gamma}, q_{\gamma\rho} \) and \( q_{\alpha\rho} \) we will have two identical overlaps and one that is strictly larger than the other two. We can represent the replicas as the leaves of a three where the length of the path from one leaf to another is the overlap between the replicas (see Fig. 2.2). This distance defines an ultrametric structure for the replicas. More precisely, we say that a metric space is ultrametric if for any three points \( x, y, z \) we have \( d(x, z) \leq \max\{d(x, y), d(y, z)\} \) [Rammal 86].

Figure 2.1: Phase diagram of the Sherrington-Kirkpatrick model [Sherrington 75].

2.2. SHERRINGTON-KIRKPATRICK MODEL
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The details of the Parisi solution can be found on [Parisi 80].

![Figure 2.2: Topology of the distance between the different replicas for the Parisi solution.](image)

2.3 TAP Equations

We will now present another way of solving the SK model that remain correct in the low-temperature regime: the TAP equations. This solution is of particular interest to this work since it shares some common points with our procedure for solving the inverse Ising model presented in part II. In this section, we will derive these results following the work of Georges and Yedidia [Georges 91], since this formulation will be particularly useful for what follows.

The TAP equations are a mean-field approximation for the SK model derived by Thouless, Anderson and Palmer [Thouless 77]. Its starting point is the same Hamiltonian as Eq. (2.10) with \( J_0 = 0 \):

\[
H = -\sum_{i<j} J_{ij} \sigma_i \sigma_j .
\]

(2.19)

To be able to make a small-coupling expansion, we introduce an inverse temperature \( \beta \) in our Hamiltonian. We add also a Lagrange multiplier \( \lambda(\beta) \) fixing \( \langle \sigma_i \rangle = m_i \)

\[
H = -\beta \sum_{i<j} J_{ij} \sigma_i \sigma_j - \sum_i \lambda_i(\beta) (\sigma_i - m_i) ,
\]

(2.20)

and the corresponding partition function is

\[
Z = \sum_{\{\sigma\}} \exp \left[ \beta \sum_{i<j} J_{ij} \sigma_i \sigma_j + \sum_i \lambda_i(\beta) (\sigma_i - m_i) \right] .
\]

(2.21)

For \( \beta = 0 \), the Hamiltonian is trivial since it describes decoupled spins. In this case,

\[
\tanh \lambda_i(0) = m_i
\]

(2.22)

and

\[
\log Z|_{\beta=0} = \sum_i \log \left[ 2 \cosh(\lambda_i(0)) \right] - \lambda_i(0) m_i
\]

\[
= -\sum_i \frac{1+m_i}{2} \log \frac{1+m_i}{2} - \sum_i \frac{1-m_i}{2} \log \frac{1-m_i}{2} .
\]

(2.23)
For a general $\beta$, we do a Taylor expansion around $\beta = 0$

$$\lambda_i(\beta) = \lambda_i(0) + \left. \frac{\partial \lambda_i(\beta)}{\partial \beta} \right|_{\beta=0} \beta + \left. \frac{\partial^2 \lambda_i(\beta)}{\partial \beta^2} \right|_{\beta=0} \frac{\beta^2}{2} + ... \tag{2.24}$$

and

$$F(\beta) = \log Z = F(0) + \left. \frac{\partial F(\beta)}{\partial \beta} \right|_{\beta=0} \beta + \left. \frac{\partial^2 F(\beta)}{\partial \beta^2} \right|_{\beta=0} \frac{\beta^2}{2} + ... \tag{2.25}$$

Each one of the derivatives of this series can be written as thermal averages of decoupled spins. For example

$$\left. \frac{\partial F(\beta)}{\partial \beta} \right|_{\beta=0} = \frac{1}{Z} \sum_{\{\sigma\}} \left[ \sum_{i<j} J_{ij} \sigma_i \sigma_j + \sum_i \left. \frac{\partial \lambda_i(\beta)}{\partial \beta} \right|_{\beta=0} (\sigma_i - m_i) \right] \times \exp \left[ \sum_i \lambda_i(0)(\sigma_i - m_i) \right]$$

$$= \sum_{i<j} J_{ij} m_i m_j , \tag{2.26}$$

and

$$\left. \frac{\partial \lambda_i(\beta)}{\partial \beta} \right|_{\beta=0} = - \left. \frac{\partial^2 F(\beta)}{\partial \beta \partial m_i} \right|_{\beta=0} = - \sum_{j(\neq i)} J_{ij} m_j . \tag{2.27}$$

Continuing this expansion with respect to $\beta$ up to the next order, we get

$$F(\beta = 1) = - \sum_i \frac{1 + m_i}{2} \log \left( \frac{1 + m_i}{2} \right) - \sum_i \frac{1 - m_i}{2} \log \left( \frac{1 - m_i}{2} \right)$$

$$+ \sum_{i<j} J_{ij} m_i m_j + \frac{1}{2} \sum_{i<j} J_{ij}^2 (1 - m_i^2)(1 - m_j^2) \tag{2.28}$$

and

$$\lambda_i(\beta = 1) = \tanh^{-1} m_i - \sum_{j(\neq i)} J_{ij} m_j + m_i \sum_{j(\neq i)} J_{ij}^2 (1 - m_j^2) . \tag{2.29}$$

Finally, to get back to our original Hamiltonian (2.19), we set $\lambda_i = 0$, obtaining:

$$\log Z = - \sum_i \frac{1 + m_i}{2} \log \left( \frac{1 + m_i}{2} \right) - \sum_i \frac{1 - m_i}{2} \log \left( \frac{1 - m_i}{2} \right)$$

$$+ \sum_{i<j} J_{ij} m_i m_j + \frac{1}{2} \sum_{i<j} J_{ij}^2 (1 - m_i^2)(1 - m_j^2) \tag{2.30}$$

2.3. TAP EQUATIONS
and
\begin{equation}
\tanh^{-1} m_i = \sum_{j \neq i} J_{ij} m_j - m_i \sum_{j \neq i} J_{ij}^2 (1 - m_j^2), \tag{2.31}
\end{equation}
which are the original TAP equations. Note that the next terms of this expansion are on higher powers of \( J_{ij} \), that are defined in the SK model to be \( O(N^{-1/2}) \) and thus negligible in the \( N \to \infty \) limit. Remark also that solving the \( N \) coupled equations (2.31) is a hard problem in general, but feasible in the limit \( J \gg 1 \) or close to the spin-glass phase transition [Thouless 77].

### 2.4 Hopfield model

In this section, we will discuss in more detail the Hopfield model that we have already presented in section 1.1.2, based on the work of Amit et al. [Amit 85a]. We will consider a more general Hamiltonian than the one presented previously, with the addition of local external fields:

\begin{equation}
H = -\frac{1}{2N} \sum_{\mu=1}^{p} \sum_{ij} \xi^\mu_i \xi^\mu_j \sigma_i \sigma_j - \sum_i h_i \sigma_i. \tag{2.32}
\end{equation}

The corresponding partition function is

\begin{equation}
Z = \int \prod_{\mu=1}^{p} \frac{dm_\mu}{\sqrt{2\pi \beta^{-1} N^{-1}}} \sum_{\{\sigma\}} \exp \left[ -\frac{\beta N}{2} \sum_{\mu=1}^{p} m_\mu^2 + \beta \sum_{\mu=1}^{p} m_\mu \sum_i \xi^\mu_i \sigma_i + \beta \sum_i h_i \sigma_i \right] \tag{2.33}
\end{equation}

\begin{equation}
= \int \prod_{\mu=1}^{p} \frac{dm_\mu}{\sqrt{2\pi \beta^{-1} N^{-1}}} \exp \left\{ -\frac{\beta N}{2} \sum_{\mu=1}^{p} m_\mu^2 + \sum_i \log \left[ 2 \cosh \left( \beta \sum_{\mu=1}^{p} m_\mu \xi^\mu_i + \beta h_i \right) \right] \right\}. \tag{2.34}
\end{equation}

If the number of patterns \( p \) remains finite when \( N \to \infty \), we can solve this integral using the saddle-point approximation

\begin{equation}
\log Z = -\frac{\beta N}{2} \sum_{\mu=1}^{p} m_\mu^2 + \sum_i \log \left[ 2 \cosh \left( \beta \sum_{\mu=1}^{p} m_\mu \xi^\mu_i + \beta h_i \right) \right], \tag{2.35}
\end{equation}

where

\begin{equation}
m_\mu = \frac{1}{N} \sum_i \xi^\mu_i \tanh \left( \beta \sum_{\nu} m_\nu \xi^\nu_i + \beta h_i \right). \tag{2.36}
\end{equation}
The solutions of the equation (2.36) depend on the details of the patterns and on the external fields. For instance, let’s consider the case where $h_i = 0$ and $\xi^\mu$ taken randomly according to a Bernoulli distribution $P(\xi^\mu_i = 1) = P(\xi^\mu_i = -1) = 1/2$. In this case, we can show that if $\beta < 1$, the only solution to the saddle-point equations is $m_\mu = 0$, which corresponds to a paramagnetic phase, while for $\beta > 1$, non-trivial solutions of Eq. (2.36) do exist. The solutions that are global minima of the free-energy are the states where the magnetization over one pattern $m_\mu$ is non-zero while the others are zero, which correspond exactly to the thermodynamic states where one retrieves the $\mu$-th pattern.

Dealing with the case of $p = \alpha N$, for $\alpha$ finite is considerably harder. It can be however treated through a calculation similar to that we will see in part III using the replica trick [Amit 92]. In this case, the system has a ferromagnetic phase, where it retrieves one of the patterns, a paramagnetic phase and a spin glass phase. In the solution of Amit et al., as in the Sherrington-Kirkpatrick model, one needs to make a replica-symmetric hypothesis to solve the saddle-point equations of the problem. In the case of the Hopfield model, for all but the very lowest temperatures the replica-symmetric solution yields the correct expression of the free energy. The phase diagram of the model is depicted in Fig. 2.3.

![Phase diagram of the Hopfield model](image)

**Figure 2.3:** Phase diagram of the Hopfield model [Amit 87] of $p = \alpha N$ patterns. The temperature $T_g$ corresponds to a transition from a paramagnetic phase to a spin-glass phase. For $T < T_M$ the patterns are a local minima of the free-energy and for $T < T_c$ these minima are global. The temperature $T_R$ is the one below which the replica-symmetric solution is false (see inset).

## 2.5 Graphical models

The Ising problem is a particular case of a class of problems known in the statistics community as undirected graphical models [Wainwright 08], which are statistical...
models where the probability distribution can be factorized over the \textit{cliques} of a certain graph $G$.

A clique of a graph $G$ is a subgraph $C \subset G$ that is fully connected (see Fig 2.4). We pose $\mathcal{C}$ as the set of maximal cliques of a graph $G$, i.e., cliques that are not contained in any other clique. We say a probability distribution over $N$ variables $x_1, \ldots, x_N$ is a graphical model if it can be factorized as

$$P(x_1, ..., x_N) = \frac{1}{Z} \prod_{C \in \mathcal{C}} p_C(\{x_k\}_{k \text{ vertex of } C}),$$

where the underlying graph $G$ has $N$ vertices and $Z$ is a normalizing constant of the probability.

![Figure 2.4: In this graph the maximal cliques are the two dark-blue colored subgraphs, each one of the 11 light blue colored triangles and all the edges that are not part of any of them [Eppstein 07].](image)

In the case of the Ising model described in the beginning of this chapter, the underlying graph is the lattice and the maximal cliques are the edges that connect two neighbors. The probability of a configuration on the most general graphical model on a lattice is then

$$P(x_1, ..., x_N) = \frac{1}{Z} \exp \left[ \sum_{<i,j>} \log(p_{ij}(x_i, x_j)) \right].$$

If we assume that our variables $x_i$ can take binary values $\pm 1$, the function $p_{ij}(x_i, x_j)$ is a function of $\{0,1\} \times \{0,1\} \rightarrow \mathbb{R}$, i.e., it can only take four different values: $p_{ij}(+1, +1)$, $p_{ij}(+1, -1)$, $p_{ij}(-1, +1)$ and $p_{ij}(-1, -1)$. There are an infinity of ways to express such a function with simple operations. We will choose the one that resembles the most with the Hamiltonian of a generalized Ising model:

$$\log(p_{ij}(x_i, x_j)) = J_{ij} x_i x_j + \tilde{h}_{ij} x_i + \tilde{h}_{ji} x_j + \kappa_{ij}.$$  

Indeed, we can easily solve the linear system to find the four unknown values ($J_{ij}$, $\tilde{h}_{ij}$, $\tilde{h}_{ji}$ and $\kappa_{ij}$) as a function of the four different values of $p_{ij}(x_i, x_j)$.
Absorbing all the constants \( \kappa_{ij} \) in the normalization \( Z \) and posing \( h_i = \sum_j \tilde{h}_{ij} \), our probability is

\[
P(x_1, \ldots, x_N) = \frac{1}{Z} \exp \left[ \sum_{<i,j>} J_{ij} x_i x_j + \sum_i h_i x_i \right],
\]

which correspond to the probability of a Ising-like model with couplings between closest neighbors and where both the local fields and the coupling between the neighbors are site-dependent\(^1\).

### 2.5.1 Message-passing algorithms

The expectation propagation is an interesting approximation for the general problem of evaluating averages according to a graphical model. The starting point of this method is the fact that when the underlying graph is a tree, we can evaluate these averages exactly. Suppose that we want to evaluate

\[
P(x_s) = \sum_{\{x_1, \ldots, x_{s-1}, x_{s+1}, \ldots, x_N\}} P(x_1, \ldots, x_N).
\]

We choose to represent our tree with \( s \) as its root. In this case, we can write

\[
P(x_s) = \sum_{\{x_1, \ldots, x_{s-1}, x_{s+1}, \ldots, x_N\}} \frac{1}{Z} \prod_{(r,s) \in E(G)} p_{r,s}(x_r, x_s),
\]

where \( E(G) \) is the set of edges of the graph \( G \). We can decompose this expression on each branches starting on \( s \).

\[\text{Figure 2.5: Example tree. Note the branches } T_t, T_u, T_v \text{ and } T_w \text{ starting on its root.}\]

For the tree shown in Fig. 2.5, for example, it will be

\(^1\)Note that allowing non-uniform coupling between neighbors allows for systems with much more complex behaviors than just a simple ferromagnetic-paramagnetic transition. For an example, see the Edwards-Anderson model [Edwards 75].
\[ P(x_s) = \frac{1}{Z} \left[ \sum_{\{x_r\}_{r \in V(T_t)}} p_{s,t}(x_s, x_t) \prod_{(r,d) \in E(T_t)} p_{r,d}(x_r, x_d) \right] \times \]
\[ \times \left[ \sum_{\{x_r\}_{r \in V(T_u)}} p_{s,u}(x_s, x_u) \prod_{(r,d) \in E(T_u)} p_{r,d}(x_r, x_d) \right] \times \]
\[ \times \left[ \sum_{\{x_r\}_{r \in V(T_v)}} p_{s,v}(x_s, x_v) \prod_{(r,d) \in E(T_v)} p_{r,d}(x_r, x_d) \right] \times \]
\[ \times \left[ \sum_{\{x_r\}_{r \in V(T_w)}} p_{s,w}(x_s, x_w) \prod_{(r,d) \in E(T_w)} p_{r,d}(x_r, x_d) \right] \]

where each term in the product represents the contribution of one branch. As we can see, we transformed the Eq. (2.42) in four independent problems defined in each branch which can be solved separately. By repeating the procedure recursively, it is possible to solve the problem with a small number of operations. Note that the same divide-and-conquer method can be used also for evaluating \( Z \).

We now would like to reformulate this solution as an algorithm that would also be well defined in graphs with cycles, even if not to give an exact solution nor being guaranteed to converge. The algorithm work by passing in each iteration messages \( M_{st} \) from every two vertex \( s \) and \( t \) connected by an edge, corresponding to an iterative relation

\[ M_{tr}(x_r) \leftarrow \kappa \sum_{x'_t} \left[ p_{rt}(x_r, x'_t) \prod_{u \in N(t), u \neq r} M_{ut}(x'_t) \right], \tag{2.44} \]

where \( N(t) \) is the set of neighbors of \( t \) and \( \kappa \) is a normalization constant fixing \( \sum_{x_r} \prod_{t \in N(t)} M_{tr}(x_r) = 1 \).

We can recover \( P(x_s) \) with the formula

\[ P(x_s) = \kappa \prod_{t \in N(s)} M_{ts}(x_s). \tag{2.45} \]

Note that the fixed point of this algorithm is the solution of (2.43). This algorithm is the simplest message-passing algorithm and is known as belief propagation. Several variations of this algorithm can be found in the literature [Wainwright 08].
Chapter 3
Inverse Problems

As exemplified in the previous chapters, most of the problems in statistical mechanics consist of describing the collective behavior of a large number of interacting parts. In general, the individual behavior of parts and how they interact are either described by first principles or can be very accurately measured. Unfortunately, as we have seen in chapter 1, for a few problems like neuron networks, the behavior of the parts and/or how they interact is not known, even if we can measure their collective behavior. In these cases, we would like to deduce the behavior and interactions of the parts from the available data. We talk then of inverse problems.

Inverse problems are often ill posed, i.e., there is more than one possible set of laws or parameters that can describe the observed data. To give an example, suppose all we know about a real-valued random variable $x$ is that $\langle x \rangle = 0$ and $\langle x^2 \rangle = 1$. Even if we restrain ourselves to Bernoulli distributions, there is an infinity of distributions satisfying our conditions: for any real $a$, $P(x = a) = 1/(1 + a^2)$ and $P(x = -1/a) = 1 - 1/(1 + a^2)$ meet our requirements.

Intuitively, a possible criterion for choosing one among all these distributions is to look for the least “restrictive” one, i.e., the one which allows as many different values as possible. To formalize this criterion, we need to define the Shannon entropy of a statistical distribution. We will start thus this chapter by defining this entropy and presenting how to optimize it to put inverse problems in a well-defined framework. In the sequence, we will present the Bayesian inference, which is a complementary approach to the entropy optimization. Finally, we will define and present some known results for the inverse problem of most interest for this work: the inverse Ising problem.

3.1 Maximal entropy distribution

The Shannon entropy of a random variable is a measure of the quantity of information unknown about it. It is defined by the sum

$$S = -\sum_{\Omega} P(\Omega) \log P(\Omega),$$

where $P(\Omega)$ is the probability of the configuration $\Omega$ of the system. Its interpretation as the quantity of information comes from the Shannon’s source coding theorem,
which states that the best theoretically possible compression algorithm can encode a sampling of \(N\) values taken with the distribution \(P\) using \(NS\) bits in the \(N \to \infty\) limit.

If we are looking for the most general distribution that reproduces a set of averages \(f_i = \langle f_i(X) \rangle\), it is reasonable to look for the one that maximizes \(S\). This is known as the principle of maximum entropy. It can be interpreted as the model that satisfies our constraints, i.e., reproducing the prescribed set of averages, while imposing as few extra conditions as possible.

Let us now consider the interesting case of random binary variables \(\sigma_i = \pm 1\), constraint to satisfy a set of local averages \(\langle \sigma_i \rangle = m_i\) and correlations \(\langle \sigma_i \sigma_j \rangle = C_{ij}\) [Tkacik 06]. In principle, one could also consider imposing higher order correlations, like the three-site ones \(C_{ijk} = \langle \sigma_i \sigma_j \sigma_k \rangle\), but doing so would only be useful in situations where one knows such high-order couplings precisely. Unfortunately, to extract such data from an experimental system one needs to measure a very large number of configurations of the system, which is rarely possible. We choose then to deal with only one and two-site correlations. In this case, we define generically the probability \(P(\{\sigma_i\}) = p_{\sigma_1,\ldots,\sigma_N}\) of a configuration \(\{\sigma_1,\ldots,\sigma_N\}\) and we can write the entropy as

\[
S = - \sum_{\{\sigma\}} p_{\sigma_1,\ldots,\sigma_N} \log p_{\sigma_1,\ldots,\sigma_N} .
\]

In order to impose the constraints on the averages and correlations, we add the Lagrange multipliers \(h_i, J_{ij}\) and \(\lambda\) respectively associated to \(m_i = \langle \sigma_i \rangle, C_{ij} = \langle \sigma_i \sigma_j \rangle\) and to the normalization of the probability \(\sum_{\{\sigma\}} p_{\sigma_1,\ldots,\sigma_N} = 1\). We obtain

\[
S = - \sum_{\{\sigma\}} p_{\sigma_1,\ldots,\sigma_N} \log p_{\sigma_1,\ldots,\sigma_N} + \sum_i h_i \left( m_i - \sum_{\{\sigma\}} p_{\sigma_1,\ldots,\sigma_N} \sigma_i \right)
+ \sum_{ij} J_{ij} \left( C_{ij} - \sum_{\{\sigma\}} p_{\sigma_1,\ldots,\sigma_N} \sigma_i \sigma_j \right) + \lambda \left( \sum_{\{\sigma\}} p_{\sigma_1,\ldots,\sigma_N} - 1 \right) .
\]

Optimizing \(S\) on \(p_{\sigma_1,\ldots,\sigma_N}\) we obtain

\[
0 = \lambda - 1 - \log p_{\sigma_1,\ldots,\sigma_N} + \sum_i h_i \sigma_i + \sum_{ij} J_{ij} \sigma_i \sigma_j .
\]

Solving Eq. (3.4), we derive the probability distribution

\[
P(\{\sigma\}) = e^{\lambda - 1} \exp \left( \sum_{ij} J_{ij} \sigma_i \sigma_j + \sum_i h_i \sigma_i \right) ,
\]

which corresponds exactly to the Boltzmann distribution for the generalized Ising model we presented in the beginning of chapter 2 (Eqs. (2.2) and (2.9)) for \(\lambda - 1 = - \log Z\).

At this point, we know how the probability distribution depends on \(J_{ij}\) and on \(h_i\). To solve completely this problem, we need to express \(J_{ij}\) and \(h_i\) in terms of the
imposed averages and correlations. Since \( J_{ij} \) and \( h_i \) are Lagrange multipliers, the values they should take to reproduce our averages and correlations correspond to an extrema of the entropy. To know whether it is a maximum or a minimum, we can do an explicit calculation of \( \frac{\partial S}{\partial J_{ij}} \) and \( \frac{\partial S}{\partial h_i} \) to see that the entropy is a convex function of the parameters \( J_{ij} \) and \( h_i \). Thus, we need to look for the set of parameters that minimizes the entropy. Moreover, the convexity assures that if a minimum exists, it is unique.

To illustrate, let’s examine the case of a two-spin system with \( \langle \sigma_1 \rangle = m_1, \langle \sigma_2 \rangle = m_2 \) and \( \langle \sigma_1 \sigma_2 \rangle = C \). The entropy is given by

\[
S = \log \left\{ \sum_{\sigma_1 = \pm 1} \sum_{\sigma_2 = \pm 1} \exp \left[ J \sigma_1 \sigma_2 + h_1 \sigma_1 + h_2 \sigma_2 \right] \right\} - JC - h_1 m_1 - h_2 m_2,
\]

\[
= \log \left\{ e^{J+h_1+h_2} + e^{J-h_1-h_2} + e^{-J+h_1-h_2} + e^{-J-h_1+h_2} \right\}
- JC - h_1 m_1 - h_2 m_2. \tag{3.6}
\]

Since we have only two spins, the optimization of \( S \) with respect to \( h_1, h_2 \) and \( J \) can be done explicitly and we obtain

\[
J = \frac{1}{4} \log \left[ \frac{(1+C-m_1-m_2)(1+C+m_1+m_2)}{(1-C-m_1+m_2)(1-C+m_1-m_2)} \right], \tag{3.7}
\]

\[
h_1 = \frac{1}{4} \log \left[ \frac{(1-C+m_1-m_2)(1+C+m_1+m_2)}{(1+C-m_1+m_2)(1-C-m_1-m_2)} \right], \tag{3.8}
\]

\[
h_2 = \frac{1}{4} \log \left[ \frac{(1-C-m_1+m_2)(1+C+m_1+m_2)}{(1+C-m_1-m_2)(1-C+m_1-m_2)} \right]. \tag{3.9}
\]

### 3.2 Bayesian inference

Suppose now that we are not only interested in finding the best parameters to fit some data, but also in attributing a probability distribution to the set of these possible parameters. If our model depends on a set of unknown parameters \( \{ \lambda_i \} \), we could in principle write the probability \( P(\{X_i\}|\{\lambda_i\}) \) of measuring any set of configurations \( \{X_i\} \). The Bayes theorem states that the probability of a set of parameters \( \{ \lambda_i \} \) as a function of a set of measures \( \{ X_i \} \) is

\[
P(\{\lambda_i\}|\{X_i\}) = \frac{P(\{X_i\}|\{\lambda_i\})P_0(\{\lambda_i\})}{P(\{X_i\})}, \tag{3.10}
\]

where \( P_0(\{\lambda_i\}) \) is the a priori probability of the parameters \( \{ \lambda_i \} \) and \( P(\{X_i\}) \) is the marginal probability of \( \{ X_i \} \), which can also be interpreted as a normalization constant:

\[
P(\{X_i\}) = \sum_{\{\lambda_i\}} P(\{X_i\}|\{\lambda_i\})P_0(\{\lambda_i\}). \tag{3.11}
\]

If one is looking to the set of parameters \( \{ \lambda_i \} \) that best describes the measures \( \{ X_i \} \), a natural choice is the one that maximizes Eq. (3.10). Such choice is known as the maximum a posteriori (MAP) estimator.
On the other hand, when the prior is not known, a common procedure is to look for the set of \( \{ \lambda_i \} \) that maximizes \( P(\{X_i\} | \{\lambda_i\}) \), which is the same as setting the prior to \( P_0(\{\lambda_i\}) = 1 \). We call such procedure the maximum likelihood estimation.

To illustrate, suppose that we have a coin that we know is biased in the following way:
\[
P(\text{favored side}) = \frac{1}{2} + \epsilon \quad \text{and} \quad P(\text{unfavored side}) = \frac{1}{2} - \epsilon,
\]
but we do not know if head or tails is favored. We toss this coin three times and get three heads. Using the Bayes theorem, we have
\[
P(\text{tails are favored} | 3 \text{ heads}) = \frac{P(3 \text{ heads} | \text{tails favored}) P_0(\text{tails favored})}{P(3 \text{ heads})}.
\]

Since we have no prior knowledge whether head or tails is favored, we have \( P_0(\text{tails favored}) = P_0(\text{heads favored}) = \frac{1}{2} \), which leads to
\[
P(\text{tails are favored} | 3 \text{ heads}) = \left( \frac{1}{2} - \epsilon \right)^3 \left( \frac{1}{2} + \epsilon \right)^3,
\]
and
\[
P(\text{heads are favored} | 3 \text{ heads}) = \left( \frac{1}{2} + \epsilon \right)^3 \left( \frac{1}{2} - \epsilon \right)^3.
\]

Unsurprisingly, we conclude that it is more likely that the coin’s favored side is heads.

Let us now look at a slightly different situation where the bias \( \epsilon \) is unknown. As before, there is an unknown favored side and heads are obtained three times. We would like to determine \( \epsilon \). From Eq. (3.10), we obtain an expression similar to Eq. (3.12)
\[
P(\epsilon | 3 \text{ heads}) = \frac{\left( \frac{1}{2} + \epsilon \right)^3 P_0(\epsilon)}{\int_{-1/2}^{1/2} \left( \frac{1}{2} + \epsilon' \right)^3 P_0(\epsilon') d\epsilon'}.
\]

Remark in the denominator the normalization according to Eq. (3.11). In this case the probability has a strong dependence on the prior, which is unknown in the majority of inference problems. Fortunately, this problem gets less and less important when one increases the amount of data. For example, suppose that instead of doing just three coin tosses, we toss it a large number of times, getting \( N \) heads and \( M \) tails. In this case, Eq. (3.15) becomes
\[
P(\epsilon | N \text{ heads}, M \text{ tails}) = \frac{\left( \frac{1}{2} + \epsilon \right)^N \left( \frac{1}{2} - \epsilon \right)^M P_0(\epsilon)}{\int_{-1/2}^{1/2} \left( \frac{1}{2} + \epsilon' \right)^N \left( \frac{1}{2} - \epsilon' \right)^M P_0(\epsilon') d\epsilon'},
\]
where the binomial term \( \binom{N + M}{N} \) gets canceled out with the normalization.

Since the function \( \left( \frac{1}{2} + \epsilon \right)^N \left( \frac{1}{2} - \epsilon \right)^M \) has a very sharp peak around \( (N - M)/(2M + 2N) \), we can do the following approximation:
\[
\left( \frac{1}{2} + \epsilon \right)^N \left( \frac{1}{2} - \epsilon \right)^M P_0(\epsilon) \simeq \left( \frac{1}{2} + \epsilon \right)^N \left( \frac{1}{2} - \epsilon \right)^M P_0\left( \frac{N - M}{2M + 2N} \right).
\]
If we apply this approximation to Eq. (3.15), the value \( P_0 \left( \frac{N-M}{2M+2N} \right) \) appears both in the numerator and in the denominator and will cancel out. The probability is thus independent of the unknown function \( P_0(\epsilon) \).

In other situations, the prior might be useful to make an inference procedure more robust. Suppose for example that we are measuring a system composed by a large number of spins \( \{\sigma_i\} \). By pure coincidence (or lack of data), two particular sites, \( i \) and \( j \), have identical spin values in all the measured configurations. Without defining a prior (i.e., setting \( P_0(\alpha) = 1 \)), the algorithm will infer an infinite-valued coupling between the two sites to account for this, which is non-physical and numerically problematic. On the other hand, if we suppose that \( P_0(\alpha) \) is a Gaussian distribution, the prior will skew the inferred values away from very large values, avoiding the problematic solutions.

### 3.2.1 Relationship with entropy maximization

Suppose that we make \( L \) independent measurements \( \{\sigma_l\} \) of a system we would like to describe using a set of parameters \( \alpha \). Since the measures are independent, we can write

\[
\log P(\{\sigma\}|\alpha) = \sum_{l=1}^{L} \log P(\sigma_l|\alpha) . \tag{3.18}
\]

Using the maximum a posteriori principle and the Bayes theorem, the set of \( \alpha \) that best describes the data is

\[
\alpha = \arg\max_{\alpha'} \left[ \log P_0(\alpha') + \sum_{l=1}^{L} \log P(\sigma_l|\alpha') \right] , \tag{3.19}
\]

where \( P_0(\alpha) \) is the prior probability of \( \alpha \). If we want to use the principle of the maximization of the entropy, one should estimate the entropy from the data as

\[
S(\alpha) = -\frac{1}{L} \sum_{l=1}^{L} \log P(\sigma_l|\alpha) \simeq -\langle \log P(\sigma|\alpha) \rangle_\sigma , \tag{3.20}
\]

using the definition of an average, we can show that \( S(\alpha) \) corresponds to the usual definition of the entropy

\[
S(\alpha) \simeq - \sum_{\{\sigma\}} P(\sigma|\alpha) \log P(\sigma|\alpha) . \tag{3.21}
\]

As we saw in the last section, we should then minimize \( S(\alpha) \) with respect to the parameters \( \alpha \), what corresponds exactly to maximizing \( P(\{\sigma\}|\alpha) \), as one would do using the maximum likelihood method.

### 3.3 The inverse Ising problem: some results from the literature

We call the problem of finding the set of couplings \( \{J_{ij}\} \) and local fields \( \{h_i\} \) from the set of magnetizations \( \{m_i\} \) and correlations \( \{C_{ij}\} \) of a generalized Ising
model the inverse generalized Ising problem [Schneidman 06]. In the following, we will omit the mention “generalized” for simplicity. We expect this problem to be particularly hard, since as we have seen in chapter 2, the direct problem of finding the magnetizations from the model’s parameters is already a non-trivial one.

### 3.3.1 Monte Carlo optimization

One can use the fact that the direct problem is numerically solvable with Monte Carlo (MC) methods [Krauth 06] to solve the inverse problem with the following algorithm [Ackley 85]:

1. start with an initial guess for the parameters $J^{0}_{ij}$ and $h^{0}_{i}$.

2. do a Monte-Carlo simulation to find the set of magnetization $m^{\text{est}}_{i}$ and correlations $C^{\text{est}}_{ij}$ corresponding to these parameters.

3. update $J_{ij}$ according to $J^{t+1}_{ij} = J^{t}_{ij} + \eta(t)\left(C_{ij} - C^{\text{est}}_{ij}\right) + \alpha\left(J^{t}_{ij} - J^{t-1}_{ij}\right)$ for some chosen function $\eta$ and constant $\alpha$.

4. update $h_{i}$ analogously to $J_{ij}$.

5. repeat steps 2 – 4 until $\max_{i,j}\left(C_{ij} - C^{\text{est}}_{ij}\right) < \epsilon$.

The number of steps necessary to reach a certain accuracy depends both on the initial parameters, the function $\eta$ and the parameter $\alpha$. An important drawback of this algorithm is that it is very inefficient: at each step one must do a Monte-Carlo simulation that is very time-consuming if one needs an accurate result. There are others modified versions of this algorithm that improve the number of necessary steps [Broderick 07], but they all involve doing a MC simulation at every step and thus have the same drawbacks.

### 3.3.2 Susceptibility propagation

In 2008, M. Mézard and T. Mora had the interesting idea of modifying the message passing algorithm we have seen in section 2.5.1 to solve the inverse Ising problem [Mezard 08, Marinari 10].

In their paper, the authors first write the Belief Propagation equations to find the values of $C_{ij}$ and $m_{i}$. They reinterpret these equations by identifying $\{J_{ij}, h_{i}\}$ as the unknowns and $\{C_{ij}, m_{i}\}$ as the input data and describe a message passing procedure that converges to the right fixed-point in trees. The details can be found in [Marinari 10].

This procedure, in the same way as the belief propagation for the direct problem, is exact on trees and an approximation for graphs that contain loops. If it converges (which is not guaranteed in graphs with loops), it do so in polynomial time, which makes it much faster than the Monte Carlo optimization. The main drawback of this method is that for graphs with loops the resulting approximated solution might be very far from the optimal solution of the problem.
3.3.3 Inversion of TAP equations

Another approach for solving the inverse Ising problem was proposed by Roudi et al. [Roudi 09]. Their starting point are the TAP equations we already saw in section 2.3:

\[
\tanh^{-1} m_i = h_i + \sum_{j \neq i} J_{ij} m_j - m_i \sum_{j \neq i} J_{ij}^2 (1 - m_j^2). \tag{3.22}
\]

Taking the derivative of this expression with respect to \(m_j\) and noting that \((C^{-1})_{ij} = \partial h_i / \partial m_j\), we have

\[
(C^{-1})_{ij} = - J_{ij} - 2 J_{ij}^2 m_i m_j + (1 - m_i^2)^{-1} \delta_{ij}, \tag{3.23}
\]

which is easily solvable for \(J_{ij}\).

Note that if \(J_{ij}\) is small, we can neglect the \(J_{ij}^2\) term, yielding an explicit solution for the couplings

\[
J_{ij} = (C^{-1})_{ij} - (1 - m_i^2)^{-1} \delta_{ij}. \tag{3.24}
\]

The inversion of Eq. (3.23) has the same strengths and drawbacks of the use of the TAP equations in the direct problem: it is exact in the large size limit for the SK model and we might expect it to work well only in models where the couplings are small.

3.3.4 Auto-consistent equations

Recently, a novel approach for finding the parameters of an Ising model was proposed by the statistics community [Wainwright 10]. Its main idea reposes on the fact that for a Ising system, the magnetization respects

\[
m_i = \sum_{\{\sigma_k\}_{k \neq i}, \sigma_i = \pm 1} \sigma_i \exp \left[ \sigma_i \sum_k J_{ij} \sigma_j + \sum_{j < k} J_{jk} \sigma_j \sigma_k + \sum_j h_j \sigma_j + h_i \sigma_i \right]
\]

\[
= \left\langle \tanh \left( \sum_{j \neq i} J_{ij} \sigma_j + h_i \right) \right\rangle, \tag{3.25}
\]

where we used the fact that \(\sum_{\sigma = \pm 1} \sigma e^{\sigma A} = \tanh(A) \sum_{\sigma = \pm 1} e^{\sigma A}\). An analogous expression can be derived for the correlations:

\[
C_{ij} = \left\langle A_{ij}(\sigma, +, +) - A_{ij}(\sigma, +, -) - A_{ij}(\sigma, -, +) + A_{ij}(\sigma, -, -) \right\rangle, \tag{3.26}
\]

where

\[
A_{ij}(\sigma, \tau, \rho) = \exp \left[ \rho \tau J_{ij} + \rho \sum_k J_{ik} \sigma_k + \tau \sum_k J_{jk} \sigma_k + \tau h_i + \rho h_j \right]. \tag{3.27}
\]
CHAPTER 3. INVERSE PROBLEMS

Suppose now that we have a set of $L$ independent measures of the full spin configuration of our system $\{\sigma^1, ..., \sigma^L\}$, with $\sigma^k = \{\sigma^k_1, ..., \sigma^k_N\}$. We can then estimate Eqs. (3.25) and (3.26):

$$\frac{1}{L} \sum_{l=1}^{L} \sigma^l_i = \frac{1}{L} \sum_{l=1}^{L} \tanh \left( \sum_{j (\neq i)} J_{ij} \sigma^l_j + h_i \right),$$

and, respectively,

$$\frac{1}{L} \sum_{l=1}^{L} \sigma^l_i \sigma^l_j = \frac{1}{L} \sum_{l=1}^{L} A_{ij}(\sigma^l_i, +, +) - A_{ij}(\sigma^l_i, +, -) - A_{ij}(\sigma^l_i, -, +) + A_{ij}(\sigma^l_i, -, -).$$

We have thus a system of coupled non-linear equations for $J_{ij}$ and $h_i$ which can be solved without the need to evaluate the partition function $Z$.

This procedure allows one to find the couplings from the measured data in polynomial time, but it has a few drawbacks. First of all, this procedure is not optimal according to the Bayes theorem. It depends on all high-order correlations while the optimal Bayes inference depends only on magnetizations and correlations. Accordingly, this method does not work if the Hamiltonian used to generate the data has any three or higher order couplings. This is particularly awkward for the case of inferring neural synapses where the hypothesis of the Ising model is just an approximation. Finally, solving the set of equations for $J_{ij}$ is a non-trivial problem. The original paper [Wainwright 10] proposes an algorithm to solve it that unfortunately does not work in the low-temperature regime.
Part II

Some results on the inverse Ising problem
Chapter 4

The inverse Ising problem in the small-correlation limit

In section 3.3, we have introduced the inverse Ising problem and discussed what has been done in the literature to solve it. In this chapter, we propose a small-correlation expansion procedure that allows one to find the couplings and magnetizations up to any given power on the correlations [Sessak 09]. We will find an explicit expression for the couplings and magnetizations that is correct up to $O((\text{largest connected correlation})^3)$.

We consider the generalized Ising model for a system composed of $N$ spins $\sigma_i = \pm 1$, $i = 1, \ldots, N$, whose Hamiltonian is given by

$$H(\{\sigma_i\}) = -\sum_{i<j} J_{ij} \sigma_i \sigma_j - \sum_i h_i \sigma_i,$$  \hspace{1cm} (4.1)

as we have already introduced in chap. 2, in Eq. (2.9). We want to find the values of couplings $J_{ij}^*$ and fields $h_i^*$ such that the average values of the spins and of the spin-spin correlations match the prescribed magnetizations $m_i$, given by

$$m_i = \langle \sigma_i \rangle,$$  \hspace{1cm} (4.2)

and connected correlations $c_{ij}$, defined by

$$c_{ij} = \langle \sigma_i \sigma_j \rangle - m_i m_j.$$  \hspace{1cm} (4.3)

For given fixed magnetizations and correlations, the entropy of the generalized Ising model, obtained in section 3.1, is given by

$$S(\{J_{ij}\}, \{\lambda_i\}; \{m_i\}; \{c_{ij}\}) = \log Z(\{J_{ij}\}, \{h_i\}) - \sum_{i<j} J_{ij} (c_{ij} + m_i m_j) - \sum_i h_i m_i,$$

$$= \log \sum_{\{\sigma_i\}} \exp \left\{ \sum_{i<j} J_{ij} [\sigma_i \sigma_j - c_{ij} - m_i m_j] + \sum_i h_i (\sigma_i - m_i) \right\},$$

$$= \log \sum_{\{\sigma_i\}} \exp \left\{ \sum_{i<j} J_{ij} [(\sigma_i - m_i)(\sigma_j - m_j) - c_{ij}] + \sum_i \lambda_i (\sigma_i - m_i) \right\},$$  \hspace{1cm} (4.4)
where the new fields $\lambda_i$ are simply related to the physical fields $h_i$ through $\lambda_i = h_i + \sum_j J_{ij} m_j$. In this same section, we have seen that the couplings $J_{ij}^*$ and fields $h_i^*$ are the ones that minimize the entropy. As discussed in chap. 2, the exact evaluation of the entropy shown in Eq. (4.4) for a given set of $J_{ij}$ and $\lambda_i$ is, in general, a computationally challenging task, not to say about its minimization. To obtain a tractable expression we multiply all connected correlations $c_{ij}$ in Eq. (4.4) by the same small parameter $\beta$, which can be interpreted as a fictitious inverse temperature. Our entropy is thus

$$
S(\{J_{ij}\}, \{\lambda_i\}; \{m_i\}, \{\beta c_{ij}\}) = \log \sum_{\{\sigma_i\}} \exp \left\{ \sum_{i<j} J_{ij} [(\sigma_i - m_i)(\sigma_j - m_j) - \beta c_{ij}] + \sum_i \lambda_i (\sigma_i - m_i) \right\}, \quad (4.5)
$$

In this chapter we want to expand the entropy in powers of $\beta$ as a function of the magnetizations and correlations:

$$
S(\{m_i\}, \{\beta c_{ij}\}) = S^0 + \beta S^1 + \beta^2 S^2 + \ldots, \quad (4.6)
$$

Accordingly, $J_{ij}^*$ and $\lambda_i^*$ can also be written as series on $\beta$:

$$
J_{ij}^*(\{m_i\}, \{\beta c_{ij}\}) = J_{ij}^0 + \beta J_{ij}^1 + \beta^2 J_{ij}^2 + \ldots, \quad (4.7)
$$

$$
\lambda_i^*(\{m_i\}, \{\beta c_{ij}\}) = \lambda_i^0 + \beta \lambda_i^1 + \beta^2 \lambda_i^2 + \ldots, \quad (4.8)
$$

where we omit the dependency of the terms on $\{m_i\}$ and $\{c_{ij}\}$ to make notations lighter. The entropy we are looking for will be obtained when setting $\beta = 1$ in the expansion. Since the parameter $\beta$ multiply every value of $c_{ij}$, we have that $S^k = O(c_{ij}^k)$. We can thus deduce that our expansion for $S$ will be convergent for small enough couplings. Note that once we have expressed the entropy as a series on $\beta$, we can retrieve an expansion for couplings and fields using the following identities, that follow from the definition of the entropy:

$$
\frac{\partial S(\{m_i\}, \{\beta c_{ij}\})}{\partial c_{ij}} = -\beta J_{ij}^*(\beta), \quad (4.9)
$$

and

$$
\frac{\partial S(\{m_i\}, \{\beta c_{ij}\})}{\partial m_i} = -\lambda_i^*(\beta). \quad (4.10)
$$

Thus, once we have found an expansion for $S$, it is trivial to deduce from it an expansion for $J_{ij}^*$ and $\lambda_i^*$.

The calculation of the entropy $S(\{m_i\}, \{\beta c_{ij}\})$ is straightforward for $\beta = 0$ since spins are uncoupled in this limit. In this case, the values of the couplings and fields minimizing the entropy are thus

$$
J_{ij}^0 = 0 \quad \text{and} \quad \lambda_i^0 = \tanh^{-1}(m_i). \quad (4.11)
$$

Accordingly, the entropy for $\beta = 0$ is

$$
S^0 = - \sum_i \left[ \frac{1 + m_i}{2} \ln \frac{1 + m_i}{2} + \frac{1 - m_i}{2} \ln \frac{1 - m_i}{2} \right]. \quad (4.12)
$$
To find the non-trivial terms of the entropy we proceed in the following way: first we define a potential $U$ over the spin configurations at inverse temperature $\beta$ through (note the new last term)

$$U(\{\sigma_i\}) = \sum_{i<j} J_{ij}^*(\beta) [\sigma_i - m_i] [\sigma_j - m_j] - \beta c_{ij} + \sum_i \lambda_i^*(\beta) [\sigma_i - m_i]$$

and a modified entropy (compare to Eq. (4.4))

$$\tilde{S}(\{m_i\}, \{c_{ij}\}, \beta) = \log \sum_{\{\sigma_i\}} e^{U(\sigma_i)} .$$

Notice that $U$ depends on the coupling values $J_{ij}^*(\beta')$ at all inverse temperatures $\beta' < \beta$. The true entropy (at its minimum) and the modified entropy are simply related to each other through

$$S(\{m_i\}, \{c_{ij}\}, \beta) = \tilde{S}(\{m_i\}, \{c_{ij}\}, \beta) - \sum_{i<j} c_{ij} \int_0^\beta d\beta' J_{ij}^*(\beta') .$$

The modified entropy $\tilde{S}$ in Eq. (4.14) was chosen to be independent of $\beta$. Indeed, it has an explicit dependence on $\beta$ through the potential $U$ (Eq. (4.13)), and an implicit dependence through the couplings and the fields. As the latter are chosen to minimize $S$, the full derivative of $\tilde{S}$ with respect to $\beta$ coincides with its partial derivative, and we get

$$\frac{d\tilde{S}}{d\beta} = \frac{\partial \tilde{S}}{\partial \beta} = -\sum_{i<j} c_{ij} J_{ij}(\beta) + \sum_{i<j} c_{ij} J_{ij}^*(\beta) = 0 .$$

The above equality is true for any $\beta$. Consequently, $\tilde{S}$ is constant and equal to its value at $\beta = 0$, $S^0$, given in Eq. (4.12).

In the following, we will use the fact that $\tilde{S}$ does not depend on $\beta$ to write self-consistency equations from which we will deduce our expansion. We will start by presenting $S^1$ and $S^2$ since their calculations differ from those used for higher orders. Afterwards, we will present the calculations for $S^3$ as a generalizable example of the general method, which will be presented in the sequence.

### 4.1 Evaluation of $S^1$ and $S^2$

To find $S^1$, we derive Eq. (4.15) with respect to $\beta$:

$$S^1 = \frac{\partial S}{\partial \beta} \bigg|_0 = \frac{\partial \tilde{S}}{\partial \beta} \bigg|_0 - \sum_{i<j} c_{ij} J_{ij}^*(0) ,$$

$$= 0 .$$

4.1. EVALUATION OF $S^1$ AND $S^2$
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since \( \tilde{S} \) does not depend on \( \beta \) (Eq. (4.16)) and \( J_{ij}^0(0) = J_{ij}^0 = 0 \) (Eq. (4.11)). A direct consequence of this, deriving from Eq. (4.10), is

\[
\frac{\partial \lambda_i}{\partial \beta} \bigg|_0 = 0 = \lambda_i^1.
\] (4.18)

To evaluate the next term \( S^2 \), we note that since \( \frac{d \tilde{S}}{d \beta} = 0 \) for any \( \beta \), we have in particular that

\[
\frac{\partial \tilde{S}}{\partial \beta} = 0 = \sum_{\{\sigma\}} \frac{\partial U(\{\sigma\})}{\partial \beta} e^{U(\{\sigma\})} = \left\langle \frac{\partial U}{\partial \beta} \right\rangle.
\] (4.19)

Evaluating Eq. (4.19) explicitly for \( \beta = 0 \) yields

\[
0 = -\sum_{i<j} c_{ij} J_{ij}^* (0) + \sum_{i<j} \left. \frac{\partial J_{ij}^*}{\partial \beta} \right|_0 \left\langle (\sigma_i - m_i)(\sigma_j - m_j) \right\rangle_0,
\] (4.20)

This equality is trivial, since we know that \( J_{ij}^* (0) = 0 \) and the averages also vanish since the spins are uncoupled for \( \beta = 0 \). We must thus look at the second derivative of \( \tilde{S} \):

\[
\frac{\partial^2 \tilde{S}}{\partial \beta^2} = 0 = \left\langle \frac{\partial^2 U}{\partial \beta^2} \right\rangle + \left\langle \left( \frac{\partial U}{\partial \beta} \right)^2 \right\rangle - \left\langle \frac{\partial U}{\partial \beta} \right\rangle^2.
\] (4.21)

Explicitly, the first term corresponds to

\[
\frac{\partial^2 U}{\partial \beta^2} = \sum_{i<j} \frac{\partial^2 J_{ij}^*}{\partial \beta^2} (\sigma_i - m_i)(\sigma_j - m_j) + \sum_i \frac{\partial^2 \lambda_i^*}{\partial \beta^2} (\sigma_i - m_i)
- \sum_{i<j} \frac{\partial J_{ij}^*}{\partial \beta} c_{ij} - \beta \sum_{i<j} \frac{\partial^2 J_{ij}^*}{\partial \beta^2} c_{ij},
\] (4.22)

which for \( \beta = 0 \) yields

\[
\left. \frac{\partial^2 U}{\partial \beta^2} \right|_0 = -\sum_{i<j} c_{ij} \left. \frac{\partial J_{ij}^*}{\partial \beta} \right|_0,
\] (4.23)

The next one is given by

\[
\left( \frac{\partial U}{\partial \beta} \right|_0 = \sum_{i<j} \sum_{k<l} \frac{\partial J_{ij}^*}{\partial \beta} \frac{\partial J_{kl}^*}{\partial \beta} (\sigma_i - m_i) (\sigma_j - m_j) (\sigma_k - m_k) (\sigma_l - m_l)
+ \sum_{i,j} \frac{\partial \lambda_i^*}{\partial \beta} \frac{\partial \lambda_j^*}{\partial \beta} (\sigma_i - m_i)(\sigma_j - m_j)
+ 2 \sum_{i<j} \sum_k \frac{\partial J_{ij}^*}{\partial \beta} \frac{\partial \lambda_k^*}{\partial \beta} (\sigma_i - m_i)(\sigma_j - m_j)(\sigma_k - m_k),
\] (4.24)

which for \( \beta = 0 \) reduces to

\[
\left\langle \left( \frac{\partial U}{\partial \beta} \right)^2 \right\rangle_0 = \sum_{i<j} \left( \left. \frac{\partial J_{ij}^*}{\partial \beta} \right|_0 \right)^2 (1 - m_i^2)(1 - m_j^2),
\] (4.25)
where we used in the last equation the fact that \( \frac{\partial \lambda^*_i}{\partial \beta} \bigg|_0 = \lambda^*_i = 0 \) (Eq. (4.18)). The last term vanishes as consequence of Eq. (4.19).

Finally, we can rewrite Eq. (4.21) as

\[ \sum_{i<j} c_{ij} \frac{\partial J^*_ij}{\partial \beta} \bigg|_0 = \sum_{i<j} \left( \frac{\partial J^*_ij}{\partial \beta} \right) \bigg|_0^2 (1 - m^2_i)(1 - m^2_j), \quad (4.26) \]

whose simpler solution is given by

\[ \frac{\partial J^*_ij}{\partial \beta} \bigg|_0 = \frac{c_{ij}}{(1 - m^2_i)(1 - m^2_j)} = J^*_ij, \quad (4.27) \]

Using Eqs. (4.15) and (4.10) we can now deduce

\[ S^2 = -\frac{1}{2} \sum_{i<j} \frac{c^2_{ij}}{(1 - m^2_i)(1 - m^2_j)}, \quad (4.28) \]

and

\[ \frac{\partial^2 \lambda^*_i}{\partial \beta^2} \bigg|_0 = 2m_i \sum_j \frac{c^2_{ij}}{(1 - m^2_i)(1 - m^2_j)^2} = 2\lambda^*_i. \quad (4.29) \]

Finally, we have the value of \( \lambda^*_i, S^2 \) and our first non-trivial estimation of \( J^*_ij \). We can verify the correctness of Eq. (4.27) by noting it is the first-order approximation of Eq. (3.7) for small \( c \).

### 4.2 Evaluation of \( S^3 \)

Like in previous section, we calculate the third derivative of \( \hat{S} \) with respect to \( \beta \):

\[ 0 = \frac{\partial^3 \hat{S}}{\partial \beta^3} = \left\langle \frac{\partial^3 U}{\partial \beta^3} \right\rangle + 3 \left\langle \frac{\partial^2 U}{\partial \beta^2} \frac{\partial U}{\partial \beta} \right\rangle + \left\langle \left( \frac{\partial U}{\partial \beta} \right)^3 \right\rangle, \quad (4.30) \]

which yields, after evaluating the averages (see appendix A):

\[ \sum_{i<j} c_{ij} \frac{\partial^2 J^*_ij}{\partial \beta^2} \bigg|_0 = -4 \sum_{i<j} \frac{c^3_{ij}m_im_j}{(1 - m^2_i)^2(1 - m^2_j)^2} - 6 \sum_{i<j<k} \frac{c_{ij}c_{jk}c_{ki}}{(1 - m^2_i)(1 - m^2_j)(1 - m^2_k)}. \quad (4.31) \]

Taking the third derivative of Eq. (4.15), we can show that

\[ -\sum_{i<j} c_{ij} \frac{\partial^2 J^*_ij}{\partial \beta^2} \bigg|_0 = \frac{\partial^3 S}{\partial \beta^3} \bigg|_0 = 6S^3. \quad (4.32) \]

Comparing the two last equations, we finally find the expression for \( S^3 \):

\[ S^3 = \frac{2}{3} \sum_{i<j} \frac{c^3_{ij}m_im_j}{(1 - m^2_i)^2(1 - m^2_j)^2} + \sum_{i<j<k} \frac{c_{ij}c_{jk}c_{ki}}{(1 - m^2_i)(1 - m^2_j)(1 - m^2_k)}. \quad (4.33) \]
4.3 Higher orders

The expansion procedure can be continued order by order using the same procedure as in section 4.2. To evaluate $S^k$ having already evaluated all $S^n$ for $n < k$, one must evaluate $\frac{\partial^k S}{\partial \beta^k} \bigg|_0$ as a sum of averages with respect to uncoupled spins. After evaluating explicitly the averages, one will have

$$\frac{\partial^k \tilde{S}}{\partial \beta^k} \bigg|_0 = - \sum_{i<j} c_{ij} \frac{\partial^{k-1} J_{ij}}{\partial \beta^{k-1}} \bigg|_0 + Q_k,$$

where $Q_k$ is a (known) function of the magnetizations, correlations, and of the derivatives in $\beta = 0$ of the couplings $J_{ij}^*$ and fields $\lambda_i^*$ of order $\leq \max(1, k - 2)$. See Appendices A and B.

Finally, as $\tilde{S}$ is constant by virtue of Eq. (4.16), both sides of Eq. (4.34) vanish. Using Eq. (4.15), we have

$$S^k = - \frac{Q_k}{k!},$$

which allows then to find the fields and couplings using Eqs. (4.9-4.10).

Using this procedure, we could go up to $S^4$ (details are on Appendix A). Using the notations

$$L_i = \langle (\sigma_i - m_i)^2 \rangle_0 = 1 - m_i^2,$$

which is basically the variance of an independent spin of average $m_i$ and

$$K_{ij} = (1 - \delta_{ij}) \frac{\langle (\sigma_i - m_i) (\sigma_j - m_j) \rangle_0}{\langle (\sigma_i - m_i)^2 \rangle_0 \langle (\sigma_j - m_j)^2 \rangle_0} = (1 - \delta_{ij}) \frac{c_{ij}}{L_i L_j},$$

where we have multiplied our definition of $K_{ij}$ by one minus a Kronecker symbol so that $K_{ii} = 0$, what makes our notations simpler. With these definitions, we have

$$S = - \sum_i \left[ \frac{1 + m_i}{2} \ln \frac{1 + m_i}{2} + \frac{1 - m_i}{2} \ln \frac{1 - m_i}{2} \right]$$

$$- \frac{\beta^2}{2} \sum_{i<j} K_{ij}^2 L_i L_j + \frac{2}{3} \beta^3 \sum_{i<j} K_{ij}^3 m_i m_j L_i L_j + \beta^3 \sum_{i<j<k} K_{ij} K_{jk} K_{ki} L_i L_j L_k$$

$$- \frac{\beta^4}{12} \sum_{i<j} K_{ij}^4 \left[ 1 + 3m_i^2 + 3m_j^2 + 9m_i^2 m_j^2 \right] L_i L_j - \frac{\beta^4}{2} \sum_k \sum_{i<j<k} K_{ik}^2 K_{kj}^2 L_i^2 L_j L_k$$

$$- \beta^4 \sum_{i<j<k<l} (K_{ij} K_{jk} K_{kl} K_{li} + K_{ik} K_{kj} K_{jl} K_{li} + K_{ij} K_{jk} K_{kl} K_{li}) L_i L_j L_k L_l$$

$$+ O(\beta^5).$$

4.3. HIGHER ORDERS
The result for $J^*_i$ is

$$J^*_i(c_{kl}, \{m_i\}, \beta) = \beta K_{ij} - 2\beta^2 m_i m_j K^2_{ij} - \beta^2 \sum_k K_{jk} K_{ki} L_k$$

$$+ \frac{1}{3} \beta^3 K^3_{ij} [1 + 3m_i^2 + 3m_j^2 + 9m_i^2 m_j^2]$$

$$+ \beta^3 \sum_{(\neq i, \neq j)} K_{ij} (K^2_{ik} L_i + K^2_{ki} L_i) L_k$$

$$+ \beta^3 \sum_{k,l, (k \neq i, l \neq j)} K_{jk} K_{kl} L_k L_l + O(\beta^4),$$

and the physical field is given by

$$h^*_i(c_{ij}, \{m_i\}, \beta) = \frac{1}{2} \ln \left( \frac{1 + m_i}{1 - m_i} \right) - \sum_j J^*_j m_j + \beta^2 \sum_{j(\neq i)} K^2_{ij} m_i L_j$$

$$- \frac{2}{3} \beta^3 (1 + 3m_i^2) \sum_{j(\neq i)} K^3_{ij} m_j L_j - 2\beta^3 m_i \sum_{j<k} K_{ij} K_{jk} K_{ki} L_i L_j L_k$$

$$+ 2\beta^4 m_i \sum_{i<j} \sum_k K_{ik} K_{kj} K_{il} K_{jl} L_i L_j L_k$$

$$+ \beta^4 m_i \sum_j K^4_{ij} L_j [1 + m_i^2 + 3m_j^2 + 3m_i^2 m_j^2]$$

$$+ \beta^4 m_i \sum_{i(\neq i)} \sum_j K^2_{ij} K^2_{j} L_i L_j + O(\beta^5).$$

### 4.4 Checking the correctness of the expansion

As we can see in Appendix A, the calculations for getting to Eq. (4.38) are long and error-prone. In this section, we will look at the different methods used to verify the correctness of these calculations.

#### 4.4.1 Comparing the values of the external field with TAP equations

In section 2.3, we presented an expansion of the free energy of the direct Ising model for small couplings. The first two orders were developed by Thouless et al. to solve the SK model, and are given in Eq. (2.30). In 1991 A. Georges and J.
Yedidia [Georges 91] published the next two orders of this expansion. They found

\[-\beta F(\{\beta J_{ij}\}, \{m_i\}) = -\sum_i \left[ \frac{1 + m_i}{2} \ln \frac{1 + m_i}{2} + \frac{1 - m_i}{2} \ln \frac{1 - m_i}{2} \right] + \beta \sum_{i<j} J_{ij} m_i m_j + \frac{\beta^2}{2} \sum_{i<j} J_{ij}^2 L_i L_j + \frac{2\beta^3}{3} \sum_{i<j} J_{ij}^3 m_i m_j L_i L_j + \beta^3 \sum_{i<j<k} J_{ij} J_{jk} J_{ki} L_i L_j L_k - \frac{\beta^4}{12} \sum_{i<j} J_{ij}^4 \left( 1 + 3m_i^2 + 3m_j^2 - 15m_i^2 m_j^2 \right) L_i L_j + 2\beta^4 \sum_{i<j} \sum_k J_{ij}^2 J_{ik} \left( J_{jk} L_i + J_{kj} J_{ki} L_i \right) + \beta^4 \sum_{i<j<k<l} \left( J_{ij} J_{jk} J_{kl} L_i + J_{ik} J_{kl} J_{li} + J_{ij} J_{jl} J_{ki} L_i \right) L_i L_j L_k L_l. \] (4.41)

From this result, we can derive the external fields as a function of $J_{ij}$ and $m_i$ through:

\[ h_i(\{J_{ij}\}, \{m_i\}) = \frac{\partial F}{\partial m_i}. \] (4.42)

For example, up to $J^2$, we have

\[ h_i = \frac{1}{2} \ln \left( \frac{1 - m_i}{1 - m_j} \right) - \sum_j J_{ij} m_j + \sum_j J_{ij}^2 m_i L_j + O(J^3). \] (4.43)

We would like to compare this equation to our result for $h_i(\{c_{ij}\}, \{m_i\})$, given in Eq. (4.40), in order to check the correctness of our expansion. To rewrite Eq. (4.43) as a function of $\{c_{ij}\}$, we use the expansion for $J_{ij}(\{c\}, \{m\})$ obtained by us, $J_{ij} = K_{ij} + O(c^2)$. We rewrite then Eq. (4.43) as

\[ h_i = \frac{1}{2} \ln \left( \frac{1 - m_i}{1 - m_j} \right) - \sum_j J_{ij} m_j + \sum_j K_{ij}^2 m_i L_j + O(c^3), \] (4.44)

which corresponds exactly to the first three terms of Eq. (4.40). We followed the same procedure using all the terms of Eq. (4.41) and the expansion of $J_{ij}$. We could verify then all the orders of Eq. (4.40). The details are in Appendix C.

### 4.4.2 Numerical minimum-squares fit

In this section, we present a method to verify our expansion for $S$ given in Eq. (4.38) numerically. For that, we rewrite our result in a slightly more general
way, introducing the coefficients \{a_1, \ldots, a_6\}: 

\[ S^{\text{dev}} = - \sum_i \left[ \frac{1 + m_i}{2} \ln \frac{1 + m_i}{2} + \frac{1 - m_i}{2} \ln \frac{1 - m_i}{2} \right] \]

\[ + a_1 \sum_{i<j} K_{ij}^3 L_i L_j + a_2 \sum_{i<j} m_i m_j L_i L_j + a_3 \sum_{i<j<k} K_{ij} K_{jk} K_{ki} L_i L_j L_k \]

\[ + a_4 \sum_{i<j} K_{ij}^3 \left[ 1 + 3m_i^2 + 3m_j^2 + 9m_i^2 m_j^2 \right] L_i L_j + a_5 \sum_{i<j<k} K_{ik}^2 K_{kj}^2 L_i^2 L_j L_k \]

\[ + a_6 \sum_{i<j<k<l} (K_{ij} K_{jk} K_{kl} K_{li} + K_{ik} K_{kj} K_{li} K_{il} + K_{ij} K_{jl} K_{ik} K_{kl}) L_i L_j L_k L_l. \]

(4.45)

We would like to obtain these coefficients through a numerical fit using data generated by exact enumeration. Afterwards, we can verify if these results match those derived formerly in this chapter.

We proceeded in the following way:

1. We choose randomly \{c_{ij}\} and \{m_i\} for a system with \(N = 5\) spins. Both the correlations \{c_{ij}\} and the magnetizations \{m_i\} are chosen randomly with an uniform distribution in the interval \([-10^{-12}, 10^{-12}]\) and \([-1, 1]\), respectively. The values of \(c_{ij}\) are very small so that the terms on \(c^{k+1}\) in the expansion of \(S\) are negligable with respect to those in \(c^k\).

2. We find numerically the minimum \(S^{\text{num}}\) of the entropy \(S\) with respect to \(J_{ij}\) and \(h_i\). This calculation has to be done with a very large numerical precision to account for the very small values of \(c_{ij}\). We used 400 decimal units.

3. We repeat steps 1 and 2 for different samplings of \{c_{ij}\} and \{m_i\} to evaluate \(D = \langle (S^{\text{dev}} - S^{\text{num}})^2 \rangle_{\{c_{ij}\}, \{m_i\}}\). In our case, we used 60 different random values of \{c_{ij}\} and \{m_i\}.

4. We find the set of \(a = \{a_1, \ldots, a_6\}\) that minimizes \(D\). Note that since \(D\) is a quadratic function of the coefficients \(a_i\), this method can still be done efficiently if we go further in the expansion and have a much larger set \(a\).

The obtained values of \{a_1, \ldots, a_6\} (see table 4.1) show a very good agreement with Eq. (4.38), giving support to our derivation.

| Constant | \(a_1\) | \(a_2\) | \(a_3\) | \(a_4\) | \(a_5\) | \(a_6\) |
|----------|--------|--------|--------|--------|--------|--------|
| Error    | \(3.7 \cdot 10^{-32}\) | \(5.4 \cdot 10^{-20}\) | \(2.1 \cdot 10^{-18}\) | \(8.2 \cdot 10^{-12}\) | \(6.7 \cdot 10^{-8}\) | \(3.8 \cdot 10^{-6}\) |

Table 4.1: Agreement between theoretical and numerical values of \{a_1, \ldots, a_6\}
CHAPTER 4. THE INVERSE ISING PROBLEM IN THE SMALL-CORRELATION LIMIT

4.4. CHECKING THE CORRECTNESS OF THE EXPANSION
Chapter 5

Further results based on our expansion for the inverse Ising model

In this chapter, we will see some useful results that follow from the expansion made in the last chapter. In particular, we will sum some infinite subsets of the expansion, what will make the expansion more robust.

To make some results in the following more visual, we will introduce a diagrammatical notation. A point in a diagram represents a spin and a line represents a $\beta K_{ij}$ link. We do not represent the polynomial in the variables $\{m_i\}$ that multiplies each link. Summation over the indices is implicit. Using these conventions, we can write our entropy as:

$$S(\{c_{kl}\}, \{m_i\}, \beta) = -\frac{1}{2} - \frac{1}{12} + \frac{2}{3} + \frac{1}{2} + \frac{1}{2}.$$  \hspace{1cm} (5.1)

We can also represent $J^*_{ij}$ diagrammatically, with the difference that we connect the $i$ and $j$ sites with a dashed line that do not represent any term in the expansion. The summation over indices are only done in sites that are not connected by a dashed line. We obtain

$$J^*_{ij} = -\frac{1}{2} - \frac{1}{12} + \frac{1}{3} + \frac{1}{3} + \frac{1}{3} + \frac{1}{3} + \frac{1}{3}.$$  \hspace{1cm} (5.2)
5.1 Loop summation

If we rewrite Eq. (4.38) in a slightly different form, a particular subset of the terms in the expansion seems to follow a regular pattern (mind the last three terms):

\[
S = -\sum_i \left[ \frac{1 + m_i}{2} \ln \frac{1 + m_i}{2} + \frac{1 - m_i}{2} \ln \frac{1 - m_i}{2} \right] + \frac{2}{3} \beta^3 \sum_{i<j} K_{ij}^3 m_i m_j L_i L_j
\]

\[
+ \frac{\beta^4}{6} \sum_{i<j} K_{ij}^4 \left[ 1 - 3m_i^2 - 3m_j^2 - 3m_i^2m_j^2 \right] L_i L_j
\]

\[
- \frac{\beta^2}{2} \sum_{i<j} K_{ij}^2 L_i L_j + \beta^3 \sum_{i<j<k} K_{ij} K_{jk} K_{ki} L_i L_j L_k
\]

\[
- \frac{\beta^4}{8} \sum_{i,j,k,l} K_{ij} K_{jk} K_{kl} L_i L_j L_k L_l
\]

\[+ O(\beta^5), \tag{5.3}\]

where we have used the identity

\[
- \frac{\beta^4}{8} \sum_{i,j,k,l} K_{ij} K_{jk} K_{kl} L_i L_j L_k L_l = -\frac{\beta^4}{2} \sum_{i<j} \sum_k K_{ik}^2 L_i^2 L_k^2 L_j L_l - \frac{\beta^4}{4} \sum_{i<j} K_{ij}^4 L_i^2 L_j^2
\]

\[
- \beta^4 \sum_{i<j<k<l} (K_{ij} K_{jk} K_{kl} + K_{ik} K_{jk} K_{il} + K_{kj} K_{ji} K_{id} + K_{ij} K_{ji} K_{ki}) L_i L_j L_k L_l. \tag{5.4}\]

The last three terms of Eq. (5.3) can be written in a different form:

\[
S_{\text{loop}} = -\frac{\beta^2}{4} \sum_{i,j} K_{ij}^2 L_i L_j + \frac{\beta^3}{6} \sum_{i,j,k} K_{ij} K_{jk} K_{ki} L_i L_j L_k
\]

\[
- \frac{\beta^4}{8} \sum_{i,j,k,l} K_{ij} K_{jk} K_{kl} L_i L_j L_k L_l,
\]

\[
= -\frac{\beta^2}{4} \text{Tr}(M^2) + \frac{\beta^3}{6} \text{Tr}(M^3) - \frac{\beta^4}{8} \text{Tr}(M^4), \tag{5.5}\]

where \( M \) is the matrix defined by \( M_{ij} = K_{ij} \sqrt{L_i L_j} \) and we will justify in the following the notation \( S_{\text{loop}} \). Since \( K_{ii} = 0 \), we have \( \text{Tr} M = 0 \), which implies that Eq. (5.5) can be rewritten as

\[
S_{\text{loop}} = \frac{1}{2} \text{Tr} \left( \beta M - \frac{\beta^2}{2} M^2 + \frac{\beta^3}{3} M^3 - \frac{\beta^4}{4} M^4 \right). \tag{5.6}\]

We now make the hypothesis that if we continue this expansion to higher orders on \( \beta \) we will found all the other terms on \( (-M)^k/k \). Thus,

\[
S_{\text{loop}} = \frac{1}{2} \text{Tr} \left( \beta M - \frac{\beta^2}{2} M^2 + \frac{\beta^3}{3} M^3 - \frac{\beta^4}{4} M^4 + \cdots \right)
\]

\[
= \text{Tr} \left[ \log(1 + \beta M) \right] = \log \left[ \det(1 + \beta M) \right]. \tag{5.7}\]
In diagrammatic terms, Eq. (5.7) corresponds to summing all single-loop diagrams and their possible contractions (see Eq. (5.4) for example):

\[ S_{\text{loop}} = \frac{1}{2} \quad + \quad - \quad + \quad + \ldots \]

\[ -\frac{1}{2} \quad - \quad - \frac{1}{4} \quad - \quad - \frac{1}{3} \quad + \quad + \ldots . \] (5.8)

From Eqs. (5.7) and (4.9), we can also derive a formula for the contribution \( J_{ij}^{\text{loop}} \) of \( S_{\text{loop}} \) to \( J_{ij}^{*} \):

\[ J_{ij}^{\text{loop}} = \frac{1}{\sqrt{(1 - m_i^2)(1 - m_j^2)}} [M(M + 1)^{-1}]_{ij} , \] (5.9)

which is exactly the formula for the mean-field approximation found in Eq. (3.24). This is not only a very good evidence that the hypothesis we used on Eq. (5.7) is correct but also gives a physical interpretation to \( S_{\text{loop}} \). Finally, we can combine this result with the previous ones, yielding:

\[ S = S_{\text{loop}} - \sum_i \left[ \frac{1 + m_i}{2} \ln \frac{1 + m_i}{2} + \frac{1 - m_i}{2} \ln \frac{1 - m_i}{2} \right] + \frac{2}{3} \sum_{i \neq j} K_{ij}^3 m_i m_j L_i L_j \\
+ \frac{\beta^4}{6} \sum_{i < j} K_{ij}^4 \left[ 1 - 3 m_i^2 - 3 m_j^2 - 3 m_i^2 m_j^2 \right] L_i L_j + O(\beta^5) , \] (5.10)

and

\[ J_{ij}^{*} = J_{ij}^{\text{loop}} - 2\beta^2 m_i m_j K_{ij}^2 \\
- \frac{2}{3} \beta^3 K_{ij}^3 \left[ 1 - 3 m_i^2 - 3 m_j^2 - 3 m_i^2 m_j^2 \right] + O(\beta^4) . \] (5.11)

Note that the infinite series shown in Eq. (5.7) is divergent when one of the eigenvectors of \( M \) is greater than one, while Eqs. (5.7) and (5.9) remain stable for all positive eigenvalues of \( M \). In practical terms, the loop summation is much more robust for inferring the couplings than the simple power expansion in Eq. (4.38). In the next section, we propose a simple numerical verification of our hypothesis that confirm this assertion.

**Numerical verification of our series expansion and the loop sum**

We have tested the behavior of the series on the Sherrington-Kirkpatrick model in the paramagnetic phase. We randomly drew a set of \( N \times (N - 1)/2 \) couplings \( J_{ij}^{\text{true}} \) from uncorrelated normal distributions of variance \( J^2/N \). From Monte-Carlo simulations, we calculated the correlations and magnetizations, inferring the couplings...
$J_{ij}^*$ from Eqs. (4.39) and (5.11) and compared the outcome to the true couplings through the estimator

$$\Delta = \sqrt{\frac{2}{N(N-1)} J^2 \sum_{i<j} \left( J_{ij}^* - J_{ij}^{true} \right)^2}.$$  \hspace{1cm} (5.12)

The quality of inference can be seen in Figure 5.1 for orders (powers of $\beta$) 1, 2, and 3 (corresponding respectively to the symbols +, × and □). For large couplings the inference gets worse as the order of the expansion increases due to the presence of terms with alternating signs in the expansion as discussed. Indeed, in the inset we show that for $J \approx 0.3$ the highest eigenvalue approaches 1. In this figure, we plot also the value for $J_{ij}^*$ obtained from Eq. (5.11) (as circles) and we can clearly see that it outperforms the other formulas.

Figure 5.1: Relative error $\Delta$ given in Eq. (5.12) on the inferred couplings as a function of the parameter $J$ of the Sherrington-Kirkpatrick model with $N = 200$ spins. Monte Carlo simulations are run over 100 steps. Averages and error bars are computed over 100 samples. Top: orders $\beta$, $\beta^2$ and $\beta^3$ of the expansion. Bottom: expression (5.11) which includes the sum over all loop diagrams. Inset: largest eigenvalue $\Lambda$ of matrix $M$ as a function of $J$.

If we try to use the same procedure to test the performance of our loop summation formula, we get results like the ones shown in Figure 5.2:
CHAPTER 5. FURTHER RESULTS BASED ON OUR EXPANSION FOR THE INVERSE ISING MODEL

Figure 5.2: Absolute error $J \times \Delta$ on the inferred couplings as a function of the parameter $J$ of the Sherrington-Kirkpatrick model. Inference is done through formula (5.11), which takes into account all loop diagrams. The error decreases with the number of spins and the number of Monte Carlo steps (shown on the figure).

We can clearly see above that the error on the inferred couplings for the Sherrington-Kirkpatrick model is essentially due to the noise in the MC estimates of the correlations and magnetizations, since it decreases with the number of steps.

5.2 Combining the two-spin expansion and the loop diagrams

In the previous section, we have identified a set of diagrams whose sum yields the mean-field approximation we saw in chapter 2. In section 3.1, we have inferred exactly the value of $J$ for a system composed of only two spins (Eqs. (3.6-3.9)). We will see that it is easy to identify summable diagrams also in this two-spin case. Our system is composed only by two spins $i$ and $j$, thus there can be no diagrams of more than two vertices in the expansion of $S$. Moreover, since the formula is exact, the expansion in the case of two spins contains all the two-spin diagrams. Indeed, the first four terms of the Taylor expansion of Eq. (3.7) on small $c_{ij}$ are

$$J_{ij} = \beta K_{ij} - 2m_i m_j K_{ij}^2 + \frac{1}{3} K_{ij}^3 \left[ 1 + 3m_i^2 + 3m_j^2 + 9m_i^2 m_j^2 \right] + \ldots ,$$

$$= \circ \circ \circ \circ \circ \circ - 2 \circ \circ \circ \circ \circ + \frac{1}{3} \circ \circ \circ \circ \circ . \quad (5.13)$$

It is easy to identify this formula as the two-spin diagrams in Eq. (4.39). Using the explicit formula for $S^{2\text{-spin}}$ given in Eq. (3.6) and applying Eqs. (3.7–3.9), we obtain
CHAPTER 5. FURTHER RESULTS BASED ON OUR EXPANSION FOR THE INVERSE ISING MODEL

\[ S_{ij}^{2\text{-spin}} = S_{i}^{1\text{-spin}} + S_{j}^{1\text{-spin}} \]
\[ + \frac{1}{4} \log \left[ 1 + \frac{c_{ij}}{(1-m_i)(1-m_j)} \right] \left[ c_{ij} + (1-m_i)(1-m_j) \right] \]
\[ + \frac{1}{4} \log \left[ 1 - \frac{c_{ij}}{(1-m_i)(1+m_j)} \right] \left[ c_{ij} - (1-m_i)(1+m_j) \right] \]
\[ + \frac{1}{4} \log \left[ 1 - \frac{c_{ij}}{(1+m_i)(1-m_j)} \right] \left[ c_{ij} - (1+m_i)(1-m_j) \right] \]
\[ + \frac{1}{4} \log \left[ 1 + \frac{c_{ij}}{(1+m_i)(1+m_j)} \right] \left[ c_{ij} + (1+m_i)(1+m_j) \right] , \quad (5.14) \]

where

\[ S_{i}^{1\text{-spin}} = - \left[ \frac{1+m_i}{2} \ln \frac{1+m_i}{2} + \frac{1-m_i}{2} \ln \frac{1-m_i}{2} \right] . \quad (5.15) \]

We have now an explicit formula for the sum of all two-spin diagrams. To go as far as possible in our expansion, we would like to sum both all the loop and two-spin diagrams. To combine Eq. (5.14) with Eq. (5.7), we need to remove the diagrams that are counted twice, since the loop expansion contains two-spin diagrams (see for ex. the first diagram in Eq. (5.8)). To evaluate the two-spin diagrams of \( S^{\text{loop}} \), we can simply evaluate it for the particular case of \( N = 2 \), where all the diagrams involving three or more spins are zero. Thus,

\[ S^{\text{loop and 2-spin}} = \frac{1}{2} \log \left[ \det \left( \frac{1}{K_{ij}} \sqrt{L_iL_j} \right) \right] = \frac{1}{2} \log \left( 1 - K_{ij}^2 L_iL_j \right) . \quad (5.16) \]

Finally, we can write an equation combining both sums:

\[ S^{2\text{-spin} + \text{loop}} = \sum_{i} S_{i}^{1\text{-spin}} + \sum_{i<j} \left[ S_{ij}^{2\text{-spin}} - S_{i}^{1\text{-spin}} - S_{j}^{1\text{-spin}} \right] \]
\[ + S^{\text{loop}} - \frac{1}{2} \sum_{i<j} \log(1 - K_{ij}^2 L_iL_j) . \quad (5.17) \]

Note that this formula contains all diagrams shown in Eq. (4.38). The corresponding formula for \( J_{ij}^* \) is

\[ J_{ij}^*(2\text{-spin+loop}) = J_{ij}^* \text{loop} + J_{ij}^* \text{2-spin} - \frac{K_{ij}}{1 - K_{ij}^2 L_iL_j} , \quad (5.18) \]

where, as we have already seen in Eq. (3.7),

\[ J_{ij}^*(2\text{-spin}) = \frac{1}{4} \ln \left[ 1 + K_{ij}^2(1+m_i)(1+m_j) \right] \]
\[ + \frac{1}{4} \ln \left[ 1 + K_{ij}^2(1-m_i)(1-m_j) \right] \]
\[ - \frac{1}{4} \ln \left[ 1 - K_{ij}^2(1-m_i)(1+m_j) \right] \]
\[ - \frac{1}{4} \ln \left[ 1 - K_{ij}^2(1+m_i)(1-m_j) \right] . \quad (5.19) \]
5.2.1 Three spin diagrams

In the case of a system with a zero local magnetization, we can find a rather simple expression for couplings $J_{ij}$ of a system composed of only three spins $\sigma_i, \sigma_j, \sigma_k$:

$$J^*_3 \text{spin}_{ij,k} = \frac{1}{4} \log \left[ \frac{1 + c_{ij} - c_{ik} - c_{jk}}{1 - c_{ij} - c_{ik} + c_{jk}} \right] - \frac{1}{4} \log \left[ \frac{1 - c_{ij} + c_{ik} - c_{jk}}{1 - c_{ij} - c_{ik} + c_{jk}} \right] + \frac{1}{4} \log \left[ \frac{1 + c_{ij} + c_{ik} + c_{jk}}{1 - c_{ij} - c_{ik} + c_{jk}} \right].$$

(5.20)

Proceeding in the same way we did with the two-spin diagrams, we can combine this formula with the previous results:

$$J_{ij}^{2\text{-spin}+\text{loop}+3\text{-spin}} = J_{ij}^{2\text{-spin}+\text{loop}} + \sum_{k \neq i, k \neq j} J^*_3 \text{spin}_{ij,k} - \sum_{k \neq i, k \neq j} \left\{ J_{ij}^{2 \text{ spins}} + \frac{c_{ij} - c_{ik}c_{jk}}{1 - c_{ij}^2 - c_{ik}^2 - c_{jk}^2 + 2c_{ij}c_{jk}c_{ki}} - \frac{c_{ij}}{1 - c_{ij}^2} \right\}.$$

(5.21)

5.3 Quality of the inference after summing the loops and 2-3 spin diagrams

In this section, we will look at how our results perform for two different well-known models. First we will look analytically at the one-dimensional Ising model and afterwards we will see numerical results for the Sherrington-Kirkpatrick model. We will test both the inference using just the loop diagrams we saw in Eq. (5.9), the combination of loops and two-spin diagrams we saw in Eq. (5.18) and the combination of loops, 2-spins and 3-spins diagrams we saw in Eq. (5.21).

5.3.1 One-dimensional Ising

For the one-dimensional Ising model, we can evaluate exactly the coupling as a function of the correlations (see Eq. (2.5)):

$$J_{kl} = (\delta_{k+1,l} + \delta_{k-1,l}) \tanh^{-1} \left( \frac{1}{c_{ij}^{[l-j]}} \right),$$

(5.22)

where $\delta_{ij}$ is the Kronecker symbol. Note that the obtained value of $J_{kl}$ should not depend on the pair of sites $i, j$ chosen. Using our formula for $J_{ij}^{2\text{-spin}}$ given in Eq. (5.19), we have

$$J_{ij}^{2\text{-spin}} = \tanh^{-1} c_{ij} = \tanh^{-1} \left[ \tanh J \right]^{[l-j]},$$

(5.23)

which predicts correctly the values of the couplings between closest neighbors $J_{i,i+1} = J$, but gives an non-zero result for the other couplings. On the other hand, using the loop summation formula from Eq. (5.9), we get

$$J_{ij}^{\text{loop}} = \frac{c}{1 - c^2} (\delta_{i,i+1} + \delta_{i,i-1}),$$

(5.24)
where \( c = c_{i,i+1} = \tanh J \) and \( \delta_{i,j} \) is the Kronecker function. The loop sum correctly predicts that the model has only closest-neighbor couplings but does not predict correctly its value.

Finally, using both the 2-spin diagrams and the loop sum (see Eq. (5.18)), we have

\[
J_{ij}^{2\text{-spin}+\text{loop}} = J(\delta_{i,i+1} + \delta_{i,i-1}) + \left[ \tanh c_{ij} - \frac{c_{ij}}{1 - c_{ij}^2} \right] (1 - \delta_{i,i+1})(1 - \delta_{i,i-1})
\]

\[
= J(\delta_{i,i+1} + \delta_{i,i-1}) + O(c^6),
\]

(5.25)

which is correct to the order \( O(c^6) \). As we will see in the following, the next contribution to the couplings coming from the expansion in Eq. (5.28) corresponds to \( \mathcal{A} \), whose leading term is indeed proportional to \( c_{i,i+2} \cdot c_{i,i+1}^2 \cdot c_{i+1,i+2}^2 = c^6 \).

### 5.3.2 Sherrington-Kirkpatrick model

In section 5.1, we saw that when we used Monte-Carlo simulations to evaluate the quality of the inference for the SK model we were limited mostly by the numerical errors of the MC simulation. To have more precise values, we now evaluate the error due to our truncated expansion using a program that calculates \( c_{ij} \) through an exact enumeration of all \( 2^N \) spin configurations. We are limited to small values of \( N \) (10, 15 and 20). However the case of a small number of spins is particularly interesting since, for the SK model, the summation of loop diagrams is exact in the limit \( N \to \infty \), as we discussed in section 2.3. The importance of terms not included in the loop summation is thus better studied at small \( N \).

We compared the quality of the inference using the loop summation (Eq. (5.9)), the combination of loop summation and all diagrams up to three spins (Eq. (5.21)) and the method of susceptibility propagation we discussed in section 3.3.2. Results are shown in Figure 5.3. The error is remarkably small for weak couplings (small \( J \)), and is dominated by finite-digit accuracy \( (10^{-13}) \) in this limit. Not surprisingly it behaves better than simple loop summation, and also outperforms the susceptibility propagation algorithm.
CHAPTER 5. FURTHER RESULTS BASED ON OUR EXPANSION FOR THE INVERSE ISING MODEL

Figure 5.3: Relative error $\Delta$ (Eq. (5.12)) as a function of $J$ for the SK model for our summation $J^{2\text{spin} + \text{loop} + 3\text{spin}}_{ij}$ (Eq. (5.21)) compared to the Susceptibility Propagation method of Mézard and Mora [Mezard 08] and loop resummation $J^\text{loop}_{ij}$ (Eq. (5.9)).

5.4 Numerical evaluation of high-order diagrams

In the two last sections we saw that summing all loop diagrams improved considerably the robustness of the inference. In this section, we will try to find some more terms numerically, in the hope that we might find other classes of exactly summable diagrams. We will proceed in a similar way as in section 4.4.2, where we used a numerical fit to validate our expansion in small $\beta$. We will use the same method to find new diagrams in the expansion by guessing a general form of the lowest-order missing terms and finding numerically their coefficients.

We started by defining a list of several possible corrections to Eq. (5.17) (since Eq. (5.21) is only valid for $m_i = 0$) such as

$$S = S^{2\text{spin} + \text{loop}} + \sum_{i,j,k} K_{ij}K_{jk}K_{ki}[a_1 + a_2(m_i + m_j) + a_3(m_j + m_i)m_k + a_4m_im_j$$

$$+ a_5(m_i^2 + m_j^2) + a_6m_k^2 + a_7(m_i^3 + m_j^3) + a_8m_i^3 + a_9m_im_jm_k + a_{10}m_i^2m_k^2].$$

(5.26)

Note that in the same way as in Eq. (4.38), the numerical coefficients in the expansion must be a fraction of small integers, as a consequence of our expansion procedure.

We followed the same method described in section 4.4.2 for each one of our guesses. We found that for all of them, with the exception of the one shown in Eq. (5.26), the fitted coefficients did not correspond to a fraction of small integers as required. Unlikely, for the guess shown in Eq. (5.26) all the coefficients were zero except $a_4 = -1$ and $a_{10} = 1$. If eventually there was one extra term missing
in Eq. (5.26) (for example a term on \( K^3_{jk} K^3_{ki} \)), the parameters other than \( a_4 \) and \( a_{10} \) would have some bogus value to compensate for the missing term. Accordingly, finding only two non-zero coefficients is a strong evidence of the lack of additional corrections other than those shown in Eq. (5.26). Indeed, this is corroborated by the value of the squared mean deviation, which is of the same order as \( c^6 \), as we would expect in an expansion with no supplementary term on \( c^5 \) missing. Finally, the expansion up to order \( O(c^5) \) is given by

\[
S = S^{2\text{-spin} + \text{loop}} - \sum_{i,j,k} K_{ij} K^2_{jk} K^2_{ki} m_i m_j L_i L_j L^2_k + O(c^6). \tag{5.27}
\]

In the particular case of a system with zero magnetization, the guesses of the corrections are much simpler since there is no arbitrary polynomial on \( m \) multiplying each term. We could then find all the terms of the expansion up to \( O(c^8) \):

\[
S = S^{2\text{-spin} + \text{loop}} - \frac{1}{6} \quad + \quad \frac{2}{3} \quad - \quad \frac{1}{4} \quad - 2 \quad + \quad \frac{1}{5} \quad + \quad \frac{1}{2} \quad + \quad O(c^9). \tag{5.28}
\]

### 5.5 Expansion in n-spin diagrams

All the results seen up to now were only valid on a small correlation limit. Unfortunately, for actual neuron data, there might be two or more neurons with very strongly correlated activity. Consequently, here we will try another approach, based on the fact that neurons spend the most of their time at rest. Their magnetization is thus very close to \(-1\) (or \(+1\), depending on which convention one chooses for the rest state). We derive thus an expansion of the couplings valid for values of magnetization close to \( \pm 1 \). The technical details can be found on appendix B. Our final result is

\[
J^{k\text{-spin} \text{ diagrams}}_{ij} = J^{2\text{-spin}}_{ij} + J^{3\text{-spin}}_{ij} + \ldots J^{k\text{-spin}}_{ij} - (\text{repeated diagrams}), \tag{5.29}
\]

and the error is given by

\[
J^*_{ij} = J^{k\text{-spin} \text{ diagrams}}_{ij} + O \left[ (1 - m^2_i)^{k-2} \right]. \tag{5.30}
\]

where \( J^{k\text{-spin}}_{ij} \) is the sum of all diagrams in the expansion of \( J_{ij} \) involving \( k \) spins.

The results seen previously in this work (see Eq. (4.38)) suggest that \( J^{k\text{-spins}}_{ij} \) is of order \( O(c^k) \), with the lowest order diagram being the loop over \( k \) spins, thus

\[
J^*_{ij} = J^{k\text{-spin} \text{ diagrams}}_{ij} + O \left( c^{k+1} \right). \tag{5.31}
\]

We can then expect that summing all diagrams up to \( k \) spins might be a very good approximation both in the strong magnetization regime (see Eq. (5.30)) and in the week correlation one (see Eq. (5.31)).
Unfortunately, even for values of $k$ as small as $k = 4$, we cannot find an exact expression for $J_{ij}^{k\text{-spin}}$ as we did for $k = 2$ in Eq. (3.7). In their PNAS paper, Cocco et al. [Cocco 09] note that $J_{ij}^{k\text{-spin}}$ can be obtained numerically, by exact enumeration of all $2^k$ possible states of a $k$-spin system. Using this method, they could sum all diagrams up to 7 spins. They could also combine this method with summing all loop diagrams, which has improved the performance of their inference.
CHAPTER 5. FURTHER RESULTS BASED ON OUR EXPANSION FOR THE INVERSE ISING MODEL

5.5. EXPANSION IN N-SPIN DIAGRAMS
Part III

Inference of Hopfield patterns
In part II, we have seen a very general treatment of the inverse Ising problem. In this part, we are interested in a particular case of the same problem: inferring the patterns of a Hopfield model, introduced in section 2.4.

In chap. 6, we deal with the problem of inferring a set of $p$ patterns from the measured data under the supposition that the number of patterns is a non-extensive quantity. We derive explicit formulas for the patterns as a function of the magnetizations and correlations in both the paramagnetic and ferromagnetic phases of the model in the limit of large system size. Interestingly, for the paramagnetic case we find in the leading order the same formula found in section 5.1 for the loop summation.

The goal of chapter 7 is to find an estimation of how many times one needs to measure a Hopfield system to be able to have a good estimate of its patterns. To this end, we use the concept of Shannon entropy introduced in chapter 3 to estimate the quantity of information we lack about the system. We evaluate explicitly the entropy for a typical realization of the system as a function of the number of measurements. We find that when the system is magnetized according to one of the patterns, we can find this pattern using just a non-extensive number of measures. On the other hand, to find the patterns that were not visited in any of our measures one needs an extensive number of measures.
Chapter 6

Pattern inference for the Hopfield model

Up to this point we have dealt with the problem of inferring a coupling matrix \( \{J_{ij}\} \) of a generalized Ising model. In this chapter, we will look at the particular case of a Hopfield model. There are several potential advantages of this model: first, as we saw in section 1.1.2, in some experiments one needs to infer a set of patterns from the measured data. Secondly, we might expect that reducing the number of degrees of freedom might make the inference procedure more stable. Finally, the Hopfield model can be solved analytically and thus we expect to have a better control of the inference errors.

In principle, one could proceed by first inferring the matrix \( \{J_{ij}\} \) from the data, as we have done in part II, and then diagonalizing it to extract a set of patterns. The problem with this approach is that it is not optimal from the Bayes point of view: the inferred patterns are not the ones that maximize the \textit{a posteriori} probability. This is particularly relevant when the assumption that the underlying system is governed by a Hopfield model is just an approximation, as will almost always be the case in biological data. In this case, we cannot guarantee that the patterns obtained by diagonalizing the \( \{J_{ij}\} \) matrix are the ones that best describe the data.

This method was carried out in a paper recently published by Haiping Huang [Huang 10], where several different methods for solving the inverse Ising model was used to find the couplings of a Hopfield model. In their paper, they show that the method presented in chapters 4 and 5 does not perform significantly better than the naive mean-field method for a Hopfield model, which gives yet another reason to look for a method specific to this model.

In this chapter, we suppose that we have measured \( L \) configurations of a system that is governed by a Hopfield model. We would like to deduce both the sign and the magnitude of the patterns from the data using a Bayesian inference, as defined in chapter 3. We suppose that we wait long enough between two successive measures so that they show no temporal correlation, i.e., that our configurations constitute an independent and identically distributed sampling of a Boltzmann distribution.

We will first start with the simple, albeit not very useful, case of Hopfield model with a single pattern. In this case, the calculations can be done in a few lines and allow one to get an idea of the structure of the solution for the general case.
Afterwards, we deal with the case of any number of patterns $p$, which is the main result of this chapter.

### 6.1 A simpler case: inference of a single pattern

In this section we suppose that we have measured $L$ independent configurations of system $\sigma^1, \ldots, \sigma^L$, where each configuration are given by $\sigma^l = \{\sigma^l_1, \ldots, \sigma^l_N\}$ and $\sigma^l_i = \pm 1$. From this data, we can, for example, evaluate the measured correlations and magnetizations

$$m_i = \frac{1}{L} \sum_{l=1}^{L} \sigma^l_i, \quad C_{ij} = \frac{1}{L} \sum_{l=1}^{L} \sigma^l_i \sigma^l_j.$$  \hfill (6.1)

We suppose that our system can be described by a Hopfield pattern with a single pattern. Its Hamiltonian is thus given by

$$H(\{\sigma_i\}) = -\frac{1}{N} \sum_{i<j} \xi_i \xi_j \sigma_i \sigma_j,$$  \hfill (6.2)

where $\xi_i$ are real values that describe the pattern, $\sigma_i$ are the spin variables and $N$ is the number of spins of the system. The partition function is given by

$$Z(\beta, \{\xi_i\}) = \sum_{\{\sigma\}} \exp \left[ -\frac{\beta}{N} \sum_{i<j} \xi_i \xi_j \sigma_i \sigma_j \right].$$  \hfill (6.3)

For the rest of this chapter we will avoid the explicit dependence on $\beta$ by performing the change of variables $\xi_i \rightarrow \xi_i/\sqrt{\beta}$. We will also omit the dependence of the partition function on $\{\xi_i\}$ to simplify notations, posing $Z(\beta, \{\xi_i\}) \equiv Z$.

We would like to infer both the sign and magnitude of $\xi_i$ from the measured configurations $\{\sigma^l\}$. Using the Bayes theorem as announced in Eq. (3.10), the likelihood of the patterns is given by

$$P(\{\xi_i\} | \{\sigma^l\}) = \frac{P_0(\{\xi_i\}) \prod_{l=1}^{L} \exp \left[ \frac{1}{N} \sum_{i<j} \xi_i \xi_j \sigma_i \sigma_j \right]}{Z^L}. \hfill (6.4)$$

Using Eq. (6.1), we can rewrite this expression as

$$\frac{1}{L} \log P(\{\xi_i\} | \{\sigma^l\}) = -\log Z - \log P(\{\sigma^l\})$$

$$+ \frac{1}{L} \log P_0(\{\xi_i\}) + \exp \left[ \frac{1}{N} \sum_{i<j} C_{ij} \xi_i \xi_j \right]. \hfill (6.5)$$

To maximize this expression, we need to evaluate $\log Z$ explicitly. Using an integral transform, Eq. (6.3) becomes

$$Z = \int_{-\infty}^{\infty} \frac{dx}{\sqrt{2\pi N^{-1}}} \sum_{\{\sigma\}} \exp \left[ -\frac{N}{2} x^2 + x \sum_i \xi_i \sigma_i \right], \hfill (6.6)$$

$$= \int_{-\infty}^{\infty} \frac{dx}{\sqrt{2\pi N^{-1}}} \exp \left\{ -\frac{N}{2} x^2 + \sum_i \log [2 \cosh(x \xi_i)] \right\}. \hfill (6.7)$$
In the following, we will set the prior to $P_0(\{\xi_i\}) = 1$, since we can see from Eq. (6.5) that it is irrelevant for large values of $L$. In the following we will treat separately the ferromagnetic case ($m \neq 0$) and the paramagnetic case ($m = 0$).

### 6.1.1 Ferromagnetic case

In the ferromagnetic phase, we can use the saddle-point method to evaluate the integral in Eq. (6.7), yielding

$$\log Z = -\frac{N}{2} x^2 + \sum_i \log [2 \cosh(x\xi_i)] + O(1/N)$$

(6.8)

with $x$ given by

$$x = \frac{1}{N} \sum_i \xi_i \tanh(x\xi_i).$$

(6.9)

To infer $\{\xi_i\}$ from the data, we follow the maximum likelihood principle and maximize Eq. (6.5) with respect to $\{\xi_i\}$, obtaining

$$\frac{1}{N} \sum_j C_{ij} \xi_j = x \tanh(m\xi_i).$$

(6.10)

It is easy to see that for such a system the correlation is dominated by its non-connected part: $C_{ij} = m_i m_j + O(1/N)$. Applying this result to Eq. (6.10), we obtain

$$\xi_i = \frac{1}{x} \tanh^{-1} m_i,$$

(6.11)

and

$$x^2 = \frac{1}{N} \sum_i m_i \tanh^{-1} m_i.$$

(6.12)

We found that the pattern is simply a function of the local magnetization, what is not very surprisingly knowing we are dealing with the ferromagnetic phase.

### 6.1.2 Paramagnetic case

In the paramagnetic case, the saddle point is $x = 0$. Consequently, we need to evaluate the next term in the large $N$ limit to find a non-trivial partition function:

$$Z = \int_{-\infty}^{\infty} \frac{dm}{\sqrt{2\pi N^{-1}}} \exp \left\{ -\frac{N}{2} m^2 + \sum_i \log [2 \cosh(m\xi_i)] \right\},$$

$$= \int_{-\infty}^{\infty} \frac{dm}{\sqrt{2\pi N^{-1}}} \exp \left\{ -\frac{N}{2} m^2 + \frac{m^2}{2} \sum_i \xi_i^2 \right\},$$

$$= \left( 1 - \frac{1}{N} \sum_i \xi_i^2 \right)^{-\frac{1}{2}}.$$ 

(6.13)
Maximizing with respect to $\xi_i$, we obtain
\[
\sum_j C_{ij} \xi_j = \frac{1}{1 - \frac{1}{N} \sum_j \xi_j}. \tag{6.14}
\]
We conclude thus that $\xi_i$ is proportional to an eigenvector $v_i$ of the matrix $C$. The corresponding eigenvalue $\lambda$ allows one to find the proportionality constant
\[
\xi_i = \sqrt{1 - \frac{1}{\lambda}} v_i, \tag{6.15}
\]
where the eigenvectors are normalized in the following way
\[
\frac{1}{N} \sum_j v_i^2 = 1. \tag{6.16}
\]
It still remain to be decided which pair of eigenvalue/eigenvector we should pick to obtain our pattern. Since we suppose our patterns are real-valued, Eq. (6.15) implies that we should choose an eigenvector greater than one. Moreover, if more than one eigenvalue satisfy this condition, we can easily deduce from Eqs. (6.15), (6.16) and (6.4) that the greatest eigenvalue is the one that maximizes the likelihood.

We verified this formula using Monte-Carlo simulations and the inferred patterns showed a good agreement with the real ones used to make the simulation.

### 6.2 Inference of continuous patterns for $p > 1$

In this section, we look at the more general and interesting case of a system with several patterns. In the same way as in the previous section, we will treat the ferromagnetic and paramagnetic case separately. But first, however, we show how the problem is theoretically harder to define in this case.

#### 6.2.1 Discussion on the gauge

A major issue in the inference of the patterns of the Hopfield model is that if the patterns can take real values the problem is ill-defined: there are many patterns that could describe equally well the data. Suppose for example the case $p = 2$:
\[
H = N \left( \frac{1}{N} \sum_i \xi_1^i \sigma_i \right)^2 + N \left( \frac{1}{N} \sum_i \xi_2^i \sigma_i \right)^2. \tag{6.17}
\]
If we define alternative patterns $\tilde{\xi}_1^i = \xi_1^i \cos \theta + \xi_2^i \sin \theta$ and $\tilde{\xi}_2^i = -\xi_1^i \sin \theta + \xi_2^i \cos \theta$, our new Hamiltonian is
\[
\tilde{H} = N \left[ \frac{1}{N} \sum_i (\xi_1^i \cos \theta + \xi_2^i \sin \theta) \sigma_i \right]^2 + N \left[ \frac{1}{N} \sum_i (-\xi_1^i \sin \theta + \xi_2^i \cos \theta) \sigma_i \right]^2, \tag{6.18}
\]
\[
= H. \tag{6.19}
\]

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More generally, if one has \( p \) patterns, doing a rotation in \( p \) dimensions will not change the Hamiltonian of the system. We say that the model has a gauge invariance in respect to such rotations. Thus, for inferring the patterns one need either to add additional constraints to the remove the \( p(p-1)/2 \) degrees of freedom or to add a prior probability to the patterns, which would select a particular preferred rotation. In the following, we will choose the former solution, since it makes our calculations simpler.

### 6.2.2 Ferromagnetic phase

Suppose that we have a sample of \( L \) measures of our system, containing \( l_1 \) measures where the system was magnetized according to the first patterns, \( l_2 \) measures with the system magnetized according to the second and so on. In this case, we have

\[
C_{ij} = \frac{1}{L} \sum_l \sigma_i^l \sigma_j^l = \frac{1}{L} \sum_{k=1}^{p} \frac{1}{L} \sum_{l \in l_k} \sigma_i^l \sigma_j^l = \frac{1}{L} \sum_{k=1}^{p} l_k m_k^i m_k^j + O(1/N),
\]

where

\[
m_k^i = \frac{1}{N} \sum_i \xi_k^i \tanh(m_k \xi_k^i),
\]

and

\[
m_k^i = \tanh(m_k \xi_k^i).
\]

A consequence of Eq. (6.20) is that the matrix \( C_{ij} \) has exactly \( p \) eigenvalues that are extensive and their corresponding eigenvectors are proportional to \( m_k^i \). We can thus easily solve Eqs. (6.20-6.22) by diagonalizing the matrix \( C_{ij} \). Note that we did not have fixed a gauge when writing these equations, but considering that \( m_k^i \) are proportional to the eigenvectors of the matrix \( C_{ij} \) implies that they are orthogonal. Thus, this procedure is equivalent of choosing the gauge that satisfies:

\[
\sum_i \tanh(m_k^i \xi_k^i) \tanh(m_{k'}^i \xi_{k'}^i) = 0, \quad \text{for } k \neq k'.
\]

### 6.2.3 High external field case

In this section, we will suppose that our external field is strong enough so that the spins are not magnetized according to any of the patterns but only according to the external field. We will be interested in inferring both the patterns of our model but also the value of the external fields, which might be site-dependent. The calculations
that will follow can be considerably simplified by replacing our usual Hamiltonian (Eq. (2.32)) by a slightly different one:

$$H = -\frac{1}{N} \sum_{\mu=1}^{p} \sum_{i<j} \xi^\mu_i \xi^\mu_j (\sigma_i - \tanh h_i)(\sigma_j - \tanh h_j) - \sum_i h_i \sigma_i. \quad (6.24)$$

This Hamiltonian can be related to the usual one by a translation on the local fields:

$$h_i \rightarrow h_i - \sum_{\mu} \sum_{j \neq i} \xi^\mu_i \xi^\mu_j \tanh h_j. \quad (6.25)$$

From Eq. (3.10), the a posteriori probability for the inference is then given by

$$P(\{\xi^\mu_i\} | \{\sigma^l\}) = \frac{P_0(\{\xi^\mu_i\})}{Z(\{\xi^\mu_i\})^L P(\{\sigma^l\})} \times \prod_{l=1}^{L} \exp \left[ \frac{\beta}{N} \sum_{\mu=1}^{p} \sum_{i<j} \xi^\mu_i \xi^\mu_j (\sigma^l_i - \tanh h_i)(\sigma^l_j - \tanh h_j) + \beta \sum_i h_i \sigma_i^l \right]. \quad (6.26)$$

Introducing the measured values of the magnetizations and of the connected correlation

$$m_i = \frac{1}{L} \sum_l \sigma_i^l, \quad c_{ij} = \frac{1}{L} \sum_l \sigma_i^l \sigma_j^l - m_i m_j, \quad (6.27)$$

we can rewrite our probability as

$$P(\{\xi^\mu_i\} | \{\sigma^l\}) = \frac{P_0(\{\xi^\mu_i\})}{Z(\{\xi^\mu_i\})^L P(\{\sigma^l\})} \exp \left[ \frac{\beta L}{N} \sum_{\mu=1}^{p} \sum_{i<j} \xi^\mu_i \xi^\mu_j c_{ij} \right. \right.$$

$$\left. + \frac{\beta L}{N} \sum_{\mu} \sum_{i<j} \xi^\mu_i \xi^\mu_j (m_i - \tanh h_i)(m_j - \tanh h_j) + \beta L \sum_i h_i m_i \right]. \quad (6.28)$$

To follow our Bayesian approach of maximizing this probability in respect to the patterns and external fields, we need first to evaluate \(\log Z\) explicitly. Since this calculation is straightforward its details can be found in appendix D. We obtain

$$\log Z = \sum_i \log(2 \cosh h_i) - \frac{1}{2} \sum_{\mu} \log \chi_{\mu} + \frac{1}{4N} \sum_{\mu,\nu} s_{\mu\nu} r_{\mu\nu} ^{\frac{1}{N}} + O(1/N^{3/2}), \quad (6.29)$$

where

$$r_{\mu\nu} = \frac{1}{N} \sum_i (\xi^\mu_i)^2 (\xi^\nu_i)^2 (1 - 3 \tanh^2 h_i)(1 - \tanh^2 h_i), \quad (6.30)$$

$$\chi_{\mu} = 1 - \frac{1}{N} \sum_i (\xi^\mu_i)^2 (1 - \tanh^2 h_i), \quad (6.31)$$

$$s_{\mu\nu} = \frac{1}{\sqrt{N}} \sum_i \xi^\mu_i \xi^\nu_i (1 - \tanh^2 h_i). \quad (6.32)$$
**CHAPTER 6. PATTERN INFERENCE FOR THE HOPFIELD MODEL**

**Optimization of the probability**

In the following, we will ignore the prior, which is justified in the limit \( L \rightarrow \infty \). To maximize Eq. (6.28) one could just maximize the following quantity

\[
\log P = \frac{1}{2N} \sum_{i,j,\mu} \xi_i^\mu \xi_j^\mu + \frac{1}{2N} \sum_{i,j,\mu} \xi_i^\mu \xi_j^\mu (m_i - \tanh h_i)(m_j - \tanh h_j)
\]

\[
+ \sum_i h_i m_i - \log Z. \tag{6.33}
\]

As discussed in section 6.2.1, we need to choose a gauge to make our problem well-defined. From Eq. (6.29), a natural choice to simplify our equations is adding a Lagrange multiplier \( \mu \) to fix the gauge \( \sum_{\mu,\nu} s_{\mu\nu} = 0 \). We obtain thus

\[
\log P = \frac{1}{2N} \sum_{i,j,\mu} \xi_i^\mu \xi_j^\mu + \frac{1}{2N} \sum_{i,j,\mu} \xi_i^\mu \xi_j^\mu (m_i - \tanh h_i)(m_j - \tanh h_j) + \sum_i h_i m_i
\]

\[
- \sum_i \log(2 \cosh h_i) + \frac{1}{2} \sum_\mu \log \chi_\mu - \frac{1}{4N} \sum_{\mu,\nu} r_{\mu\nu} - \frac{1}{N} \sum_{\mu \neq \nu} x_{\mu\nu} s_{\mu\nu}. \tag{6.34}
\]

Optimizing with respect to \( h_i \), we obtain

\[
\frac{\partial \log P}{\partial h_i} = 0 = m_i - \tanh h_i - \sum_\mu (1 - \tanh^2 h_i) \xi_i^\mu \frac{1}{N} \sum_j \xi_j^\mu (m_j - \tanh h_j)
\]

\[
+ \sum_\mu \left( \frac{\xi_i^\mu}{N} \right)^2 \tanh h_i (1 - \tanh^2 h_i) + O(1/N^{3/2}). \tag{6.35}
\]

Posing

\[
\alpha_\mu = \sum_i \xi_i^\mu (m_i - \tanh h_i), \tag{6.36}
\]

we can multiply Eq. (6.35) by \( \xi_i^\mu \) and sum over \( i \), yielding

\[
\chi_\mu \alpha_\nu = -\frac{1}{\sqrt{N}} \sum_\mu \frac{1}{\chi_\mu} \frac{1}{\sqrt{N}} \sum_i \left( \frac{\xi_i^\mu}{N} \right)^2 \xi_i^\nu \tanh h_i (1 - \tanh^2 h_i). \tag{6.37}
\]

Eq. (6.37) shows that unless the matrix \( s_{\mu\nu} \) happens to have an eigenvalue equal to \( \chi_\mu \), \( \alpha_\mu \) is of order \( 1/\sqrt{N} \). We can then rewrite Eq. (6.35) as

\[
m_i - \tanh h_i = -\frac{1}{N} \sum_\mu \left( \frac{\xi_i^\mu}{N} \right)^2 \tanh h_i (1 - \tanh^2 h_i) + O(1/N^{3/2}). \tag{6.38}
\]

which shows clearly that \( m_i = \tanh h_i + O(1/N) \).

We will now optimize our probability with respect to \( \xi_i^\mu \):

\[
\frac{1}{N} \sum_j c_{ij} \xi_j^\mu = \frac{1}{N} \frac{1}{\chi_\mu} \frac{1}{\sqrt{N}} \left( 1 - \tanh^2 h_i \right) - \frac{1}{N^2} \sum_\nu \frac{\xi_i^\mu (\xi_i^\nu)^2}{\chi_\mu \chi_\nu} (1 - 3 \tanh^2 h_i) (1 - \tanh^2 h_i)
\]

\[
- \frac{1}{N^2} \sum_\mu \frac{r_{\mu\nu}}{\chi_\mu \chi_\nu} \xi_i^\mu (1 - \tanh^2 h_i) - \frac{2}{N^2} \sum_{\nu \neq \mu} x_{\mu\nu} \xi_i^\nu (1 - \tanh^2 h_i)
\]

\[+ O(1/N^{5/2}), \tag{6.39}
\]

6.2. INFERENCE OF CONTINUOUS PATTERNS FOR \( p > 1 \)
Where we used the fact that \( \frac{1}{N} \alpha \rho_i (m_i - \tanh h_i) = O(1/N^{5/2}) \) to ignore subleading terms. In the following, we will start by solving this equation in the leading order on \( N \).

**Solution in the leading order**

We want to find the solutions \( \xi_{i,0}^\mu \) and \( h_i^0 \) of Eqs. (6.38) and (6.39) up to the leading order on \( N \). Ignoring sub-leading terms, this equations are respectively given by

\[
\frac{1}{N} \sum_j c_{ij} \xi_{j,0}^\mu = \frac{1}{N} \frac{1}{\chi^\mu} \xi_{i,0}^\mu \left( 1 - \tanh^2 h_i^0 \right),
\]

and

\[
h_i^0 = \tanh^{-1} m_i.
\]

If we define \( v_i^\alpha \) as the eigenvector associated to the eigenvalue \( \lambda_\alpha \) of the matrix

\[
M_{ij} = \frac{c_{ij}}{\sqrt{1 - \tanh^2 h_i^0} \sqrt{1 - \tanh^2 h_j^0}},
\]

we have

\[
\xi_i^{\mu,0} = \sqrt{1 - \frac{1}{\lambda_\mu} \frac{v_i^\mu}{\sqrt{1 - \tanh^2 h_i^0}}},
\]

Note that the orthogonality of the eigenvectors assures that our gauge \( s_{\mu\nu} = 0 \) is respected.

The procedure of diagonalizing the correlation matrix to extract underlying information is known in the statistics literature by the name of Principal Component Analysis. We already mentioned in the end of section 1.1.2 how this method is currently used to find patterns in neuronal data. It was also used by Ranganathan et al. [Halabi 09] to find functional groups in proteins. Our approach gives a Bayesian justification for using the PCA for neuron data and allows us to write the probability distribution for the measured system: it is just the Boltzmann distribution for the obtained Hopfield model.

Note that Eq. (6.42) implies

\[
J_{ij} = \sum_\alpha \frac{\lambda_\alpha - 1}{\lambda_\alpha} \frac{v_i^\alpha v_j^\alpha}{\sqrt{(1 - m_i^2)(1 - m_j^2)}}
= \frac{1}{\sqrt{(1 - m_i^2)(1 - m_j^2)}} \left[ M^{-1}(M - 1) \right]_{ij},
\]

which is exactly the same formula found in section 5.1 for the loop summation, but using the convention of \( M_{ii} = 1 \) instead of \( M_{ii} = 0 \). While this is an encouraging sign that our calculations are correct, it does not bring any new result. We will thus now try to go beyond the leading terms in \( N \) and look for the first correction to this expression.
Sub-dominant corrections

Applying our first approximation of the patterns $\xi^{\mu,0}$ to Eq. (6.38), we can evaluate the first correction to the field $h_i$. Posing $h_i = h_i^0 + h_i^1$, we have

$$h_i^1 = \frac{1}{1 - \tanh^2 h_i^0} \frac{1}{N} \sum_{\mu} \frac{(\xi^{\mu,0}_{i})^2}{\chi^{\mu}_{0}} \tanh h_i^0 (1 - \tanh^2 h_i^0)$$

(6.45)

Since now we have a more precise value of $h_i$, we can redo the procedure of solving Eq. (6.40) we used for the leading order using this new value. We will denote the obtained patterns $\xi^{\mu,1}_{i}$. Note that $\xi^{\mu,1}_{i}$ is correct up to the leading order in $N$, in the same way as $\xi^{\mu,0}_{i}$, since it neglects the subdominant terms in Eq. (6.39). Finally, to find an expression for the patterns that is correct up to the first leading order, $\xi^{\mu,2}_{i} = \xi^{\mu,1}_{i} + \delta^{\mu}_{i}$, we do a Taylor expansion of the dominant orders of Eq. (6.39) around $\xi^{\mu}_{i} = \xi^{\mu,1}_{i}$:

$$\frac{1}{N} \sum_{i} c_{ij} \delta^{\mu}_{j} - \frac{1}{N} \chi^{\mu}_{\mu} \delta^{\mu}_{i} (1 - \tanh^2 h_i) + \frac{2}{N^2} \sum_{\nu (\neq \mu)} x_{\mu \nu} \xi^{\nu,1}_{i} (1 - \tanh^2 h_i)$$

$$- \frac{2}{N^2 \chi^{\mu}_{\mu}} \sum_{i} \xi^{\mu,1}_{i} \xi^{\nu,1}_{i} \delta^{\mu}_{i} (1 - \tanh^2 h_i)(1 - \tanh^2 h_j) =$$

$$= - \frac{1}{N^2} \sum_{\nu} \frac{\xi^{\mu,1}_{i} (\xi^{\nu,1}_{i})^2}{\chi^{\mu}_{\mu} \chi^{\nu}_{\nu}} (1 - 3 \tanh^2 h_i)(1 - \tanh^2 h_i)$$

$$- \frac{1}{N^2} \sum_{\mu} \frac{r_{\mu \nu}}{\chi^{\mu}_{\mu} \chi^{\nu}_{\nu}} \xi^{\mu,1}_{i} (1 - \tanh^2 h_i).$$

(6.46)

Similarly, our gauge equations $s_{\mu \nu} = 0$ yields

$$\frac{1}{\sqrt{N}} \sum_{i} (\xi^{\mu,1}_{i} \delta^{\mu}_{i} + \xi^{\nu,1}_{i} \delta^{\nu}_{i}) (1 - \tanh^2 h_i) = 0.$$  

(6.47)

At last, Eqs. (6.46) and (6.47) form a non-homogeneous linear system in the variables $\delta^{\mu}_{i}$ and $x_{\mu \nu}$ ($\mu < \nu$) which can be solved numerically by a simple matrix inversion.

6.2.4 Numerical verification

In this section we will verify numerically the correctness of both the inference up to the dominant order shown in Eqs. (6.42) and (6.43) and its subdominant corrections shown in Eqs. (6.46) and (6.47). We will proceed in the following way: first, we will choose a set of patterns $\{\xi^{\mu}_{i}\}$ and fields $\{h_i\}$. Then, we will use a numerical method (that we will explain in the following) to compute the correlations and local magnetizations of the corresponding Hopfield model. Using these quantities, we will use our inference procedure to find the inferred patterns, both in the dominant order $\{\xi^{\mu,0}_{i}\}$ and with the subdominant corrections $\{\xi^{\mu,2}_{i}\}$. Finally, we will compare the obtained patterns with our initially chosen ones to estimate the quality of our inference.
Numerical evaluation of the correlations of the Hopfield model

To verify the validity of our inference, we needed a numerical method that produced very precise values for the correlations, so we could be sure that any disagreement between the real patterns and the inferred ones were due to shortcomings of the inference procedure and not due to numerical errors. Moreover, we wanted a numerical simulation that scales well for increasing $N$, since our equations are correct in the large $N$ limit.

To be able to satisfy these requirements, we restricted our input patterns and fields to a four-block configuration:

\[
\begin{align*}
\xi^1 &= \{a_1, \ldots, a_1, b_1, \ldots, b_1, c_1, \ldots, c_1, d_1, \ldots, d_1\}, \\
\xi^2 &= \{a_2, \ldots, a_2, b_2, \ldots, b_2, c_2, \ldots, c_2, d_2, \ldots, d_2\}, \\
\xi^3 &= \{a_3, \ldots, a_3, b_3, \ldots, b_3, c_3, \ldots, c_3, d_3, \ldots, d_3\}, \\
h &= \{h_1, \ldots, h_1, h_2, \ldots, h_2, h_3, \ldots, h_3, h_4, \ldots, h_4\},
\end{align*}
\]

where \(\{a_i\}, \{b_i\}, \ldots\) are real values. Since in our calculations we suppose that \(\sum_i \xi_i^\mu \xi_i^\nu = O(\sqrt{N})\) and \(\sum_i \xi_i^\mu \tanh h_i = O(\sqrt{N})\), we have restricted our number of patterns to three since it is impossible using four blocks to satisfy these conditions for more patterns. In our simulation we have chosen values of \(\{a_i\}, \{b_i\}, \ldots\) so that the patterns obey our orthogonality condition and that the magnitude of the patterns are small enough not to be too close to the phase transition at \(|\xi_i^\mu| = 1\).

With the choice of patterns shown in Eq. \((6.48)\), the partition function is

\[
Z = \sum_{\{\sigma\}} \exp \left\{ N \sum_{\mu=1}^{3} \left[ a_\mu^2 \left( \frac{1}{N} \sum_{i=1}^{N/4} \sigma_i \right)^2 + b_\mu^2 \left( \frac{1}{N} \sum_{i=N/4+1}^{N/2} \sigma_i \right)^2 \right. \right. \\
+ c_\mu^2 \left( \frac{1}{N} \sum_{i=N/2+1}^{3N/4} \sigma_i \right)^2 + d_\mu^2 \left( \frac{1}{N} \sum_{i=3N/4+1}^{N} \sigma_i \right)^2 \left. \right] \right\},
\]

\((6.49)\)

We can see that the Hamiltonian depends only on \(m_1 = \sum_{i=1}^{N/4} \sigma_i, m_2 = \sum_{i=N/4+1}^{N/2} \sigma_i\), etc. Now we replace the sum over all the spin configurations by a sum over all possible values of \(m_1, m_2, m_3\) and \(m_4\), which allows one to evaluate the partition function, the correlations and the magnetizations with a complexity of \(O(N^4)\).

Comparison of the inferred with the real patterns

We cannot directly compare the inferred patterns with the real ones to evaluate the error of our procedure since they might differ in gauge. Thus, we used in our comparison a value that does not depend on the gauge: \(J_{ij} = \sum_\mu \xi_i^\mu \xi_j^\mu\). The results of the comparison of the real patterns with the inferred ones can be seen in the following graph.
Figure 6.1: Inference error for the different elements of the matrix $J_{ij}$ for $N = 100$. In blue we have $J_{ij}^{\text{real}} = \sum_\mu \xi_\mu^0 \xi_j^0$ and in red we have $J_{ij}^{\text{real}} = \sum_\mu \xi_\mu^2 \xi_j^2$. In this graph, we have $\{a_1, b_1, c_1, d_1\} = \{0.693, 0.4, -0.8, 0.4\}$, $\{a_2, b_2, c_2, d_2\} = \{0.693, -0.8, 0.4, 0.4\}$, $\{a_3, b_3, c_3, d_3\} = \{0, 0.693, 0.693, 0.693\}$ and $\{h_1, h_2, h_3, h_4\} = \{0.254, -0.283, 0.416, -0.380\}$.

We can see clearly in Figure 6.1 that the subdominant corrections improve the inference quality. Unfortunately, these corrections are very sensible to noisy data, and we could not see an improvement of the inference for both Monte-Carlo and real neuron data.
6.2. INFERENCE OF CONTINUOUS PATTERNS FOR $p > 1$
Chapter 7

Evaluation of the inference entropy for the Hopfield model

As introduced in section 3.1, a good estimate of how much data is needed to infer a pattern is given by the information-theoretical entropy (Eq. (3.1)) of the a posteriori probability of the patterns, given by

\[
S[\{\sigma_i^l\}] = - \sum_{\{\xi\}} P[\{\xi^\mu\}|\{\sigma_i^l\}] \log P[\{\xi^\mu\}|\{\sigma_i^l\}],
\]

(7.1)

where \{\xi^\mu\} are the patterns of our Hopfield model (see section 2.4) and \{\sigma_i^l\} are a set of \(L\) measured configurations of the system.

The entropy can be interpreted as the quantity of information that is missing about our system. Thus, when \(S \ll 1\), we can say that we have enough data to infer with very little error the patterns. In this chapter we will evaluate the entropy for the inference of the Hopfield model. As before, we will first treat the simpler case of a single pattern before dealing with the more general and interesting case of an arbitrary number of patterns \(p\).

7.1 Case of a single binary pattern

Let us recall the usual partition function of the Hopfield model (Eq. (2.32)) for \(p = 1\)

\[
Z(\beta, \{\xi\}) = \sum_{\{\sigma\}} \exp \left[ \frac{\beta}{N} \sum_{i<j} \xi_i \xi_j \sigma_i \sigma_j \right].
\]

(7.2)

In the particular case where \(\xi_i = \pm 1\), we can pose \(\sigma_i' = \xi_i \sigma_i\) and rewrite the partition function as

\[
Z(\beta) = \sum_{\{\sigma'\}} \exp \left[ \frac{\beta}{N} \sum_{i<j} \sigma_i' \sigma_j' \right].
\]

(7.3)

This equation is exactly the same as Eq. (2.6) for zero external field, which means that the thermodynamics of this model is identical to the infinite-dimensional Ising
model presented in chapter 2. From a more technical point of view, contrary to
the usual Hopfield model with \( p > 1 \), the partition function is independent of the
pattern, which makes the calculations considerably simpler.

In this case, the Bayes a posteriori probability is given by Eq. (6.4), which we
recall here:

\[
P(\{\xi_i\} | \{\sigma_i^l\}) = \frac{P_0(\{\xi_i\})}{Z(\beta)^L N(\beta, \{\sigma_i^l\})} \prod_{l=1}^{L} \exp \left[ \frac{1}{N} \sum_{i<j} \xi_i \xi_j \sigma_i^l \sigma_j^l \right],
\]

where we used a different notation for the normalization \( N \). Applying this result to
Eq. (7.1) and setting the prior \( P_0(\{\xi_i\}) = 1 \), we obtain

\[
S[\{\sigma_i^l\}] = -\frac{1}{N[\{\sigma_i^l\}] Z(\beta)^L} \sum_{\{\xi\}} \exp \left( \frac{\beta}{N} \sum_{l=0}^{L} \sum_{i<j} \xi_i \xi_j \sigma_i^l \sigma_j^l \right) \times
\]

\[
\times \left[ -\log (N[\{\sigma_i^l\}] Z(\beta)^L) + \left( \frac{\beta}{N} \sum_{l=0}^{L} \sum_{i<j} \xi_i \xi_j \sigma_i^l \sigma_j^l \right) \right].
\]

Introducing the variable

\[
\tilde{N}[\{\sigma_i^l\}] = \sum_{\{\xi\}} \exp \left( \frac{\beta}{N} \sum_{l=0}^{L} \sum_{i<j} \xi_i \xi_j \sigma_i^l \sigma_j^l \right),
\]

we can rewrite Eq. (7.5) as

\[
S[\{\sigma_i^l\}] = -\frac{\log \tilde{N}[\{\sigma_i^l\}]}{N[\{\sigma_i^l\}]} \sum_{\{\xi\}} \exp \left( \frac{\beta}{N} \sum_{l=0}^{L} \sum_{i<j} \xi_i \xi_j \sigma_i^l \sigma_j^l \right) \times
\]

\[
\times \left[ -\log \tilde{N}[\{\sigma_i^l\}] Z(\beta)^L + \left( \frac{\beta}{N} \sum_{l=0}^{L} \sum_{i<j} \xi_i \xi_j \sigma_i^l \sigma_j^l \right) \right].
\]

Thus, the entropy can be trivially evaluated from \( \tilde{N}[\{\sigma_i^l\}] \).

We can see in Eq. (7.6) that the expression for \( N \) is formally identical to the
partition function of a Hopfield model where the \( L \) measured configurations \( \{\sigma_i^l\} \)
play the role of the patterns and \( \{\xi_i\} \) replace the spin variables:

\[
Z_{\text{Hop}} = \sum_{\{\sigma\}} \exp \left( \frac{\beta}{N} \sum_{\mu=1}^{L} \sum_{i<j} \xi_i^\mu \xi_j^\mu \sigma_i \sigma_j \right).
\]

For such analogy, the inference entropy shown in Eq. (7.7) has a thermodynamic
meaning: it is the thermodynamic entropy of the model.

Eqs. (7.6) and (7.7) give the entropy of the system for a particular set of measures
\( \{\sigma_i^l\} \). Now, it is natural to expect the entropy to be very reproducible across different
sets of measurements. In this context, we are interested in evaluating the average of the entropy with respect to all possible measurements. Supposing that the data is produced measuring an actual Hopfield model with a pattern \(\{\tilde{\xi}_i\}\), we have

\[
\langle S \rangle = \left. \langle \log \tilde{N}[\{\sigma_i^l\}] \rangle \right|_{\tilde{\beta}=\beta} - \beta \frac{\partial}{\partial \tilde{\beta}} \left. \langle \log \tilde{N}[\{\sigma_i^l\}] \rangle \right|_{\tilde{\beta}=\beta},
\]

with

\[
\left. \langle \log \tilde{N} \rangle \right|_{\tilde{\beta}=\beta} = \frac{1}{Z(\tilde{\beta})} \sum_{\{\sigma\}} \exp \left( \frac{\tilde{\beta}}{N} \sum_{l=0}^{L} \sum_{i<j} \tilde{\xi}_i \tilde{\xi}_j \sigma_i^l \sigma_j^l \right) \log \tilde{N}[\{\sigma_i^l\}],
\]

where we replaced our usual inverse temperature \(\beta\) by a new variable \(\tilde{\beta}\) since we should not take the derivative in respect to it in Eq. (7.9).

The entropy of the system is very different if \(\beta < 1\) and the system is in the paramagnetic phase or if \(\beta > 1\) in which case the system is in the ferromagnetic phase. We will see these two cases separately in the following sections.

### 7.1.1 Ferromagnetic case

In the ferromagnetic case, if we want to evaluate a thermal average of some quantity \(X\), we have

\[
\langle X \rangle = \frac{1}{Z L(\tilde{\beta})} \sum_{\{\sigma\}} X(\{\sigma_i^l\}) \exp \left( \frac{\tilde{\beta}}{N} \sum_{l=0}^{L} \sum_{i<j} \tilde{\xi}_i \tilde{\xi}_j \sigma_i^l \sigma_j^l \right) \log \tilde{N}[\{\sigma_i^l\}],
\]

where \(m^*\) is the solution of the equation \(m^* = \tanh(\tilde{\beta} m^*)\).

Since \(\log \tilde{N}\) is formally identical to the free-energy of the Hopfield model, we start with the saddle-point solution obtained in chap. 2, given in Eqs. (2.35) and (2.36):

\[
\log \tilde{N} = -\frac{\beta N}{2} \sum_{l=1}^{L} m_l^2 + \sum_i \log \left[ 2 \cosh \left( \beta \sum_{l=1}^{L} m_l \sigma_i^l \right) \right],
\]

and

\[
m_l = \frac{1}{N} \sum_i \sigma_i^l \tanh \left( \beta \sum_s m_s \sigma_i^s \right).
\]

We recall that the physical meaning of \(m_\mu\) in the Hopfield model is the magnetization of the spins according to the pattern \(\mu\). In our case, it represents the overlap between the pattern we are inferring and the \(l\)-th configuration: \(m_l = \frac{1}{N} \sum_i \xi_i \sigma_i^l\).

Eq. (7.13) has always a solution in the form \(\{m_l\} = \{m, m, ..., m\}\) [Amit 85a]. Since \(\{\sigma_i^l\}\) are measured configurations of an Ising system in the ferromagnetic phase,
we expect them to be very similar: they are all close to the same minimum of the free energy of the Ising model. We expect thus that the solution \( \{ m_l \} = \{ m, m, ..., m \} \) to be the minimum of our modified free-energy of Eq. (7.12). Under this hypothesis, the entropy reads

\[
\langle S \rangle / N = \left\langle \ln \left[ 2 \cosh \left( \beta m \sum_i \sigma^I_i \right) \right] \right\rangle - \left\langle \left( \beta m \sum_i \sigma^I_i \right) \tanh \left( \beta m \sum_i \sigma^I_i \right) \right\rangle,
\]

(7.14)

where the value of \( m \) that satisfies Eq. (7.13) is \( m = m^* \), fact proven in Appendix E.

**Asymptotic behavior**

One can note that the entropy of this system is the same of the system composed of a single spin \( \rho = \pm 1 \) connected with \( L \) independent, magnetized spins. The partition function for this system of a single spin is

\[
Z = 2 \cosh \left( \beta m \sum_i \sigma^I_i \right),
\]

(7.15)

and the free-energy reads

\[
F = \left\langle \log \left[ 2 \cosh \left( \beta m \sum_i \sigma^I_i \right) \right] \right\rangle_{\sigma^I_i},
\]

(7.16)

where the average is done with respect to independent spins \( \sigma^I \) with magnetization \( m \). If we want to calculate the average entropy of this system, we note that for large \( x \), \( \log (2 \cosh x) - x \tanh x \approx (1 + 2|x|)e^{-2|x|} \). Consequently

\[
\langle S \rangle \approx \sum_{k=0}^{L} \binom{L}{k} \frac{e^{\beta m(L-2k)}}{[2 \cosh(\beta m)]^L} e^{-2\beta m |L-2k|}.
\]

(7.17)

One may remark that the probability that our single spin \( \rho \) is not aligned with its partners is exponentially small on \( L \). There are two extreme cases that contributes to this probability

1. The spins \( \sigma_i \) obeys \( \sum_i \sigma_i \approx 0 \) (which is very unlikely) and consequently our spin \( \rho \) is random.

2. We have the highly probable situation of \( \sum_i \sigma_i \approx mL \), but our spin \( \rho \) is misaligned with the others, which is very unlikely.

The case 1 has a probability \( \approx [\cosh(\beta m)]^{-L} \) and gives a log 2 contribution to the entropy, while the case 2 has a probability \( O(1) \) but gives a contribution of order \( e^{-2\beta m^2 L} \) to the entropy. Since for all \( \beta \), \( \log \cosh(\beta m) < 2\beta m^2 \) (note that \( m \) is an implicit function of \( \beta \)), case 1 dominates the behavior of the system for \( L \to \infty \). So, for large \( L \), we have the general behavior

\[
S \propto e^{-\gamma L},
\]

(7.18)
with
\[ \gamma = \log \cosh (\beta m). \] (7.19)

We can see how well the entropy converges to this asymptotic behavior in Fig. 7.1.

![Figure 7.1](image)

**Figure 7.1:** Entropy per spin as a function of \( L \) for \( \beta = 1.1 \) according to Eq. (7.14).

We can thus conclude that for \( L \gg 1/\gamma \) we can infer the unknown pattern with a very small probability of error.

### 7.1.2 Paramagnetic case

In the paramagnetic phase we have \( m = 0 \). According to Eq. (7.14), the entropy is thus equal to \( \log 2 \) for all values of \( L \). This is correct under the hypothesis that \( L \) remains finite when \( N \to \infty \). For \( L = \alpha N \), the results of the previous section do not hold since we cannot use the saddle-point approximation for \( \log Z \).

We start with Eq. (2.33)

\[ \tilde{N} = \int \prod_{l=1}^{L} \frac{dm_l}{\sqrt{2\pi\beta^{-1}N^{-1}}} \exp \left[ -\frac{\beta N}{2} \sum_{l=1}^{L} m_l^2 + \beta \sum_{l=1}^{L} m_l \sum_{i} \sigma_i \xi_i \right] \] (7.20)

and we would like to find the average \( \langle \tilde{N} \rangle \) with respect to all possible realizations of the measures \( \{\sigma_i\} \), like we have done in the ferromagnetic case. The main difference is that now the saddle-point values of \( m_l \) are of order \( O(1/\sqrt{N}) \).

To find the correct solution under these conditions, we need to use the replica trick as explained in section 2.4. The calculations are very similar to those done in the solution of the Hopfield model by Amit et al. [Amit 85b] and the details can be
found in Appendix F. The obtained value for the entropy is given by

\[
\langle S \rangle_\sigma = -\frac{\alpha \beta (1-q) \{1 - \beta [2 - 2q(1 - \beta) - (1 + t^2)\beta]\}}{2(1 - \beta) [1 - (1 - q)\beta]^2} - \frac{\alpha}{2} \ln [1 - (1 - q)\beta] \\
+ \left\langle \ln \left[ 2 \cosh \left( \frac{\hat{t}}{\alpha^2} + z \sqrt{\alpha \hat{q}} \right) \right] \right\rangle_z - \frac{\alpha}{2} [(1-q)\hat{q} + t\hat{t}],
\]

(7.21)

where \( \langle f \rangle_z = \int_{-\infty}^{\infty} f(z) e^{-z^2/2} \, dz \), we remind that \( \alpha = L/N \) and

\[
t = \langle \sigma'_l \xi_l \rangle_\sigma = \left\langle \tanh \left( \frac{\alpha}{2} \hat{t} + z \sqrt{\alpha \hat{q}} \right) \right\rangle_z, 
\]

(7.22)

\[
q = \left\langle \left( \frac{1}{N} \sum_i \xi_i \sigma'_i \right)^2 \right\rangle_\sigma = \left\langle \left[ \tanh \left( \frac{\alpha}{2} \hat{t} + z \sqrt{\alpha \hat{q}} \right) \right]^2 \right\rangle_z, 
\]

(7.23)

\[
\hat{t} = \frac{2t\beta^2}{(1 - \beta) [1 - (1 - q)\beta]},
\]

(7.24)

\[
\hat{q} = \beta^2 - \frac{q(1 - \beta) + t^2 \beta}{(1 - \beta) [1 - (1 - q)\beta]^2}.
\]

(7.25)

where we remind that \( t \) is the overlap between the real and the inferred pattern. One can verify that we only have a non-zero solution to these equations when \( \alpha > \alpha_c \), with \( \alpha_c = \left( 1 - \frac{1}{\beta} \right)^2 \). In this case both \( q \) and \( t \) are non-zero.

When \( \alpha < \alpha_c \), \( t \) is zero which implies that the inferred pattern has no resemblance to the real one. Surprisingly, the entropy decreases linearly in this regime for increasing \( \alpha \), which can be possibly interpreted as a growth of the set of patterns known to be incompatible with the data.

Note that in contradistinction with the ferromagnetic case, to infer the patterns in the paramagnetic phase it takes a number of measures that is proportional to the size of the system, implying that is much harder to extract information from it.

**Numerical verification**

In Figure 7.2, one can see the behavior of the entropy as a function of \( \alpha \) for a fixed inverse temperature \( \beta = 0.5 \).
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Figure 7.2: Entropy per spin as a function of $\alpha$ for $\beta = 0.5$. The solid line correspond to Eqs. (7.21–7.25) while the points correspond to numerical values obtained by exact enumeration. The dashed line corresponds to the behavior of $\langle S \rangle$ in the regime of $q = t = 0$ while the vertical line indicates $\alpha_c$.

To evaluate numerically $\langle S \rangle$ as shown in Fig. 7.2, we used the following algorithm:

1. Evaluate $Z$ by exact enumeration;
2. Generate $L = \alpha N$ configurations $\{\sigma_i^t\}$ according to the Boltzmann weight by rejection sampling;
3. Evaluate $N[\{\sigma_i^t\}]$ by exact enumeration;
4. Evaluate $S[\{\sigma_i^t\}]$ by exact enumeration.

For every $\alpha$, we repeated this procedure one hundred times with different random seeds, which gives different configurations $\{\sigma_i^t\}$ in step 2. The points in the graph correspond to the averages of the set of obtained values of $S$ and the error bars were calculated using the standard deviation. The result of this procedure supports our analytical results. Indeed, in Figure 7.2 we notice that the bigger values of $N$ are much closer to the analytical curve, which suggests that the difference between the analytical and numerical results is due to the small value of $N$ used in the numerical calculations.

7.1. CASE OF A SINGLE BINARY PATTERN
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7.2 Case of a single pattern $\xi_i \in \mathbb{R}$

The results of the previous section are valid only if our pattern takes bimodal values, what might be a very particular case. To verify if the inference of a real-valued pattern presents any qualitative difference with respect to the bimodal case, we propose ourselves to evaluate explicitly the entropy for the real-valued case in this section.

The calculations are similar to those of the last section, but with the supplementary complication that the partition function depends on the exact values of the pattern whereas in the bimodal case it depended only on the temperature. The partition function is given by

$$\log Z [\{\xi_i\}] = - \frac{N}{2} m[\{\xi_i\}]^2 + \sum_i \log [2 \cosh (m \xi_i)] ,$$

(7.26)

with

$$m[\{\xi_i\}] = \frac{1}{N} \sum_i \xi_i \tanh (\xi_i m[\{\xi_i\}]).$$

(7.27)

Since $\xi_i$ is continuous, we must modify the definition of the entropy replacing the sum by an integral

$$S[\{\sigma'_i\}] = - \int \prod_i d\xi_i P[\{\xi_i\}|\{\sigma'_i\}] \log P[\{\xi_i\}|\{\sigma'_i\}] .$$

(7.28)

Using Bayes’ theorem, we obtain

$$S[\{\sigma'_i\}] = - \frac{1}{\mathcal{N}[\{\sigma'_i\}]} \int \prod_i d\xi_i P_0[\{\xi_i\}] \frac{1}{Z^L(\{\xi_i\})} \exp \left( \frac{1}{N} \sum_{l=0}^{L} \sum_{i<j} \xi_i \xi_j \sigma'_i \sigma'_j \right) \times$$

$$\times \left[ - \log \mathcal{N}[\{\sigma'_i\}] - L \log Z(\{\xi_i\}) + \log P_0(\{\xi_i\}) + \frac{1}{N} \sum_{l=0}^{L} \sum_{i<j} \xi_i \xi_j \sigma'_i \sigma'_j \right] ,$$

(7.29)

where $\mathcal{N}[\{\sigma'_i\}]$ is given by

$$\mathcal{N}[\{\sigma'_i\}] = \int \prod_i d\xi_i P[\{\xi_i\}|\{\sigma'_i\}]$$

(7.30)

$$= \int \prod_i d\xi_i \frac{P_0(\{\xi_i\})}{Z^L(\{\xi_i\})} \exp \left( \frac{1}{N} \sum_{l=0}^{L} \sum_{i<j} \xi_i \xi_j \sigma'_i \sigma'_j \right) .$$

(7.31)

As in the previous section, we would like to write $S$ as a derivative of the normalization. For that, we define a modified normalization $\tilde{N}$ by introducing a parameter $\beta$ to $\mathcal{N}$:

$$\tilde{N}[\{\sigma'_i\}, \beta] =$$

$$= \int \prod_i d\xi_i \exp \left( \frac{\beta}{N} \sum_{l=0}^{L} \sum_{i<j} \xi_i \xi_j \sigma'_i \sigma'_j + \beta \log P_0(\{\xi_i\}) - \beta L \log Z(\{\xi_i\}) \right) .$$

(7.32)
Note that while $\beta$ is similar to an inverse temperature, it is not strictly one, since it multiplies also the partition function. Using this definition, we can rewrite our entropy as

$$S[\{\sigma_i^l\}] = \log \tilde{N}[\{\sigma_i^l\}] - \left. \frac{\partial \log \tilde{N}[\{\sigma_i^l\}, \beta]}{\partial \beta} \right|_{\beta=1}. \quad (7.33)$$

A supplementary difficulty of the continuous case is the dependence of $\log Z$ on $m[\{\xi\}]$, which depends on the patterns implicitly according to Eq. (7.27). To make that dependence explicit, we introduce the following identity

$$f(m[\xi]) = \int dm \int dx f(m) \exp \left[ -iNxm + i \sum_i \xi_i \tanh(m\xi_i) \right], \quad (7.34)$$

which is just Dirac’s delta written in the integral form. We can thus write the $e^{-\beta L \log Z}$ term in Eq. (7.32) as

$$e^{-\beta L \log Z} = \int dm \int dx \exp \left\{ \frac{\beta LN}{2} m^2 - \beta L \sum_i \log [2 \cosh(m\xi_i)] ight. \left. - iNxm + i \sum_i \xi_i \tanh(m\xi_i) \right\}. \quad (7.35)$$

Like in the previous section, we would like to evaluate the average of the entropy with respect to the different possible measures and to the different real pattern $\{\tilde{\xi}_i\}$:

$$\langle S \rangle = \prod_i \int d\tilde{\xi}_i P_0(\{\tilde{\xi}_i\}) \sum_{\sigma} \frac{1}{Z(\{\xi_i\})} S(\{\sigma_i^l\}) \exp \left[ \frac{1}{N} \sum_{l=1}^L \sum_{i<j} \tilde{\xi}_i \tilde{\xi}_j \sigma_i^l \sigma_j^l \right]. \quad (7.36)$$

where we impose that the distribution of the unknown real patterns $\{\tilde{\xi}_i\}$ is the same of our prior distribution $P_0(\{\xi_i\})$.

The details of the replica calculation, similar to the last section, can be found in Appendix G. It yields

$$\frac{1}{N} \langle \log \tilde{N} \rangle = \frac{\beta}{2} \sum_{l=1}^L Q_i^2 + \frac{\beta L m^2}{2} \quad + \int d\hat{\xi} p_0(\hat{\xi}) \sum_{\{\sigma^l\}} \exp \left[ \hat{m}^2 \sum_{l=1}^L \sigma_i^l - L \log(2 \cosh(\hat{m})) \right] \times \quad (7.37)$$

$$\times \log \left\{ \int d\xi \exp \left[ \beta \sum_{l=1}^L Q_i \sigma_i^l - \beta L \log(2 \cosh(m\xi)) + \beta \log p_0(\xi) \right] \right\},$$

7.2. CASE OF A SINGLE PATTERN $\xi_i \in \mathbb{R}$
CHAPTER 7. EVALUATION OF THE INFERENCE ENTROPY FOR THE HOPFIELD MODEL

where

\[ \tilde{m} = \int d\tilde{\xi} p_0(\tilde{\xi}) \tanh(\tilde{m}\tilde{\xi}) = \langle \tanh(\tilde{m}\tilde{\xi}) \rangle, \quad (7.38) \]

\[ m = \int d\tilde{\xi} \sum_{\{\sigma\}} \exp \left[ \sum_{l=1}^{L} \tilde{m}\tilde{\xi}\sigma^l - L \log 2 \cosh(\tilde{m}\tilde{\xi}) \right] \times \]

\[ \times \frac{\int d\xi p_0(\xi) \tanh(m\xi) \exp \left[ \sum_{l=1}^{L} Q^l\sigma^l\xi - L \log 2 \cosh(m\xi) \right]}{\int d\xi p_0(\xi) \exp \left[ \sum_{l=1}^{L} Q^l\sigma^l\xi - L \log 2 \cosh(m\xi) \right]}, \quad (7.39) \]

\[ Q_k = \int d\tilde{\xi} \sum_{\{\sigma\}} \exp \left[ \sum_{l=1}^{L} \tilde{m}\tilde{\xi}\sigma^l - L \log 2 \cosh(\tilde{m}\tilde{\xi}) \right] \times \]

\[ \times \frac{\int d\xi p_0(\xi) \tanh(m\xi) \exp \left[ \sum_{l=1}^{L} Q^l\sigma^l\xi - L \log 2 \cosh(m\xi) \right]}{\int d\xi p_0(\xi) \exp \left[ \sum_{l=1}^{L} Q^l\sigma^l\xi - L \log 2 \cosh(m\xi) \right]}, \quad (7.40) \]

and \( \prod_i e^{P_0(\xi_i)} = P_0(\{\xi\}) \) is the prior probability of the pattern and the probability distribution we used to average over the real pattern, supposed to be identical.

From this last equation it is straightforward to evaluate the entropy using Eq. (7.33).

### 7.3 Case of a system with \( p \) patterns, magnetized following a strong external field

In this section we consider the same conditions as we had in section 6.2.3 for the inference: we have a Hopfield model with \( p \) patterns and we introduce a local external field strong enough so that the system is not magnetized according to any of the patterns. The Hamiltonian is thus the same as Eq. (2.32). The calculations are very similar to those of section 7.4, so they can be found in Appendix I. We find that the entropy associated with each one of the patterns is described by exactly the same equations as single pattern in the paramagnetic phase, seen in section 7.1.2. We have thus the same behavior: we need thus a number of measures that is proportional to the size of the system and the exact form of the entropy is given by Eqs. (7.21–7.25).

### 7.4 A particular case: a system with two patterns, magnetized according to the first

In last section, we saw that when our system does not visit any one of the patterns the inference of each one of them is as hard as describing a system composed of a single pattern in the paramagnetic phase. In this section, we will see if there is any qualitative change in the situation where the system is magnetized according to one pattern but we would like to infer a second, non-visited one.
We suppose that our system’s Hamiltonian is given by

\[ H = -\beta \sum_{i<j} (\xi_1^i \xi_1^j + \xi_2^i \xi_2^j) \sigma_i \sigma_j, \]

where the patterns \( \xi_\mu^i = \pm 1 \) are binary. We suppose we did \( L = \alpha N \) measures of the configuration of this system, all of them while the system was magnetized following the first pattern. Supposing that the first pattern is perfectly known (what is reasonable since our entropy on it goes with \( e^{-\gamma L} = e^{O(N)} \) as the inference of the first pattern is very similar to the ferromagnetic case we saw previously), we study the entropy of the a posteriori distribution of the second pattern

\[ S = -\sum_{\{\xi_1^i\}} P[\{\xi_2^i\} | \{\xi_1^i\}, \{\sigma_1^i\}] \log P[\{\xi_2^i\} | \{\xi_1^i\}, \{\sigma_1^i\}]. \] (7.41)

In the same way we did with the single pattern case in section 7.1, we average this entropy with respect both to the first pattern and to the measured configurations. The probability is given by

\[ P[\{\xi_2^i\} | \{\xi_1^i\}, \{\sigma_1^i\}] = \frac{P[\{\sigma_1^i\} | \{\xi_1^i\}, \{\xi_2^i\}] P[\{\xi_2^i\}]}{\mathcal{N}[\{\xi_1^i\}, \{\sigma_1^i\}]}, \] (7.42)

\[ P[\{\sigma_1^i\} | \{\xi_1^i\}, \{\xi_2^i\}] = \frac{1}{Z_{\text{Hop}}[\beta, \{\xi_1^i\}, \{\xi_2^i\}]^L} \exp \left[ \frac{\beta}{N} \sum_{\mu=1,2} \sum_{l=1}^L \sum_{i<j} \sigma_l^i \sigma_l^j \xi_\mu^i \xi_\mu^j \right], \] (7.43)

where the normalization of the probability \( \mathcal{N} \) is given by

\[ \mathcal{N}[\{\xi_1^i\}, \{\sigma_1^i\}] = \sum_{\{\xi_2^i\}} \frac{1}{Z_{\text{Hop}}[\beta, \{\xi_1^i\}, \{\xi_2^i\}]^L} \exp \left[ \frac{\beta}{N} \sum_{\mu=1,2} \sum_{l=1}^L \sum_{i<j} \sigma_l^i \sigma_l^j \xi_\mu^i \xi_\mu^j \right] P[\xi_2^i]. \] (7.44)

As done in Section 7.1, we write our entropy as a derivative of a modified normalization \( \tilde{\mathcal{N}} \) given by

\[ \tilde{\mathcal{N}}[\{\xi_1^i\}, \{\sigma_1^i\}] = \sum_{\{\xi_2^i\}} \exp \left[ \frac{\beta}{N} \sum_{\mu=1,2} \sum_{l=1}^L \sum_{i<j} \sigma_l^i \sigma_l^j \xi_\mu^i \xi_\mu^j \right. \\
\left. - \frac{\beta}{\beta} L \log Z_{\text{Hop}}[\beta, \{\xi_1^i\}, \{\sigma_1^i\}] \right], \] (7.45)

so that we can easily deduce the entropy as

\[ S = \log \tilde{\mathcal{N}} \bigg|_{\beta=\tilde{\beta}} - \frac{\partial \log \tilde{\mathcal{N}}}{\partial \beta} \bigg|_{\beta=\tilde{\beta}}, \] (7.46)

where we have supposed \( P[\xi_2^i] = 2^{-N} \). We will now evaluate this quantity explicitly.
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Doing a calculation very similar to the derivation of Eq. (6.29), we can write the partition function of the Hopfield model for \( p = 2 \) for a system magnetized in the first pattern, obtaining:

\[
\log Z_{\text{Hop}} = -\frac{\beta N}{2}m^* + N\log[2\cosh(\beta m^*)] - \log[1 - \beta(1 - m^*)] + \frac{1}{2\beta N}\sum_{i}^{m^*} \xi_i^2 \]

with \( m^* \) given by \( m^* = \tanh(\beta m^*) \).

7.4.1 Evaluation of \( \langle \log \tilde{N} \rangle \)

To evaluate \( \langle \log \tilde{N} \rangle \), we use again the replica trick, obtaining

\[
\langle N^n \rangle = \frac{1}{2^N} \left\{ \frac{1}{2^N} \sum_{\{\xi^1\}} \sum_{\{\xi^2\}} \sum_{\{\xi^2,\nu\}} \exp \left[ \beta \sum_{\nu=1}^{L} \sum_{i,j} \sigma_i^j \right] \right. \\
- \frac{\beta}{\beta L} \log Z_{\text{Hop}} \left[ \tilde{\beta}, \{\xi^1\}, \{\xi^2,\nu\} \right]
\]

where we denote by \( \tilde{\xi}^2 \) the real second pattern and by \( \xi^2 \) the inferred one.

That expression can be simplified to (see Appendix H)

\[
\langle N^n \rangle = \sum_{\{\xi^1\}} \sum_{\{\xi^2\}} \sum_{\{\xi^2,\nu\}} \exp \left[ C_1 - \frac{L}{2} \frac{\tilde{\beta}m^*u^2}{1 - \beta(1 - m^*)} - \frac{L}{2} \frac{\beta m^*2}{1 - \beta(1 - m^*)} \sum_{\nu} s_{\nu}^2 
- \frac{L}{2} \log \det M + \frac{L}{2} A^T M^{-1} A \right],
\]

where

\[
\begin{align*}
    u &= \frac{1}{\sqrt{N}} \sum_{i} \xi_i^1 \xi_i^2, \\
    t_{\mu} &= \frac{1}{N} \sum_{i} \tilde{\xi}_i^1 \xi_i^2, \\
    s_{\mu} &= \frac{1}{\sqrt{N}} \sum_{i} \xi_i^1 \xi_i^2 - \mu, \\
    q_{\mu,\nu} &= \frac{1}{N} \sum_{i} \xi_i^2 \xi_i^2 - \mu
\end{align*}
\]

\[
M = \begin{pmatrix}
    d_1 & \tilde{u} & \tilde{s}_1 & \tilde{s}_2 & \tilde{s}_3 & \ldots & \tilde{s}_n \\
    \tilde{u} & d_2 & \tilde{t}_1 & \tilde{t}_2 & \tilde{t}_3 & \ldots & \tilde{t}_n \\
    \tilde{s}_1 & \tilde{t}_1 & d_3 & \tilde{q}_{1,2} & \tilde{q}_{1,3} & \ldots & \tilde{q}_{1,n} \\
    \tilde{s}_2 & \tilde{t}_2 & \tilde{q}_{1,2} & d_3 & \tilde{q}_{2,3} & \ldots & \tilde{q}_{2,n} \\
    \vdots & \vdots & \vdots & \vdots & \ddots & \ddots & \vdots \\
    \tilde{s}_n & \tilde{t}_n & \tilde{q}_{1,n} & \ldots & \ldots & d_3 & \tilde{d}_3
\end{pmatrix}
\]

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\[ A = \left( \sqrt{N}(\tilde{m}^* - m^*)(\beta n + \tilde{\beta}) \ m^*\tilde{\beta}u \ m^*\beta s_1 \ m^*\beta s_2 \ \cdots \ m^*\beta s_n \right), \]

and

\[
\begin{align*}
d_1 &= (\beta n + \tilde{\beta}) \left[ 1 - (\beta n + \tilde{\beta})(1 - \tilde{m}^*^2) \right], \\
d_2 &= \tilde{\beta} \left[ 1 - \tilde{\beta}(1 - \tilde{m}^*^2) \right], \\
d_3 &= \beta \left[ 1 - \beta(1 - \tilde{m}^*^2) \right], \\
\tilde{u}_\nu &= -(1 - \tilde{m}^*^2)\tilde{\beta}(\beta n + \tilde{\beta})u_\nu, \\
\tilde{t}_\nu &= -(1 - \tilde{m}^*^2)\beta\tilde{\beta}t_\nu, \\
\tilde{s}_\nu &= -(1 - \tilde{m}^*^2)\beta(\beta n + \tilde{\beta})s_\nu, \\
\tilde{q}_{\nu,\sigma} &= -(1 - \tilde{m}^*^2)\beta^2 q_{\nu,\sigma}.
\end{align*}
\]

Interestingly, the value of the entropy for the replica-symmetric case of this system is exactly the same of section 7.1.2 (Eqs. (7.21)–(7.25)), but with a equivalent inverse temperature of \( \beta' = \beta(1 - m^2) \). We show thus that the behavior saw in the last section remains valid in this case.
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7.4. TWO PATTERNS, MAGNETIZED ACCORDING TO THE FIRST
In this work we have studied the general problem of extracting information from the measured activity of interacting parts. This problem is a recurring one in several domains, like biology (with the study of neuron networks and proteins), physics, social science and economics.

To solve such a problem, one needs to make a supposition about the underlying system that has generated the data. Our results can thus be separated in two main parts: in the first, we supposed that our system is described by a generalized Ising model, i.e., an Ising model with a Hamiltonian given by

$$H\left(\{\sigma_i\}\right) = \sum_{i<j} J_{ij} \sigma_i \sigma_j + \sum_i h_i \sigma_i.$$  

In this case, the underlying information to be extracted are the couplings $J_{ij}$ and external fields $h_i$ used in the Hamiltonian. A second part of our results deals with the case where the underlying system is described by the Hopfield model of $p$ patterns, with an Hamiltonian given by

$$H\left(\{\sigma_i\}\right) = \sum_{i<j} \sum_{\mu=1}^p \xi_{\mu i} \xi_{\mu j} \sigma_i \sigma_j + \sum_i h_i \sigma_i.$$  

In this case, the information to be obtained are the values of the patterns $\{\xi_{\mu i}\}$ and of the external fields $h_i$.

In part II of this thesis, we derived an explicit formula for the couplings $J_{ij}$ and external fields $h_i$ as a function of the magnetizations $m_i = \langle \sigma_i \rangle$ and connected correlations $c_{ij} = \langle \sigma_i \sigma_j \rangle - m_i m_j$. That formula was obtained through a small-correlation expansion and was evaluated up to order three on the correlations. We developed also a general method through which one could continue the expansion up to any desired order.

Unfortunately, the performance of our approximation up to order three degraded very quickly when increasing the values of the correlations. To workaround this limitation, we identified some terms of our expansion that, once grouped together, corresponded exactly to the first terms of a mean-field approximation already known in the literature. We could then replace these terms by the full mean-field approximation to find a formula that was much more robust against large values of correlation. Moreover, we could identify a second set of terms easy to interpret: all the terms that involve only two sites can be shown to represent the exact solution of a system composed of only two spins. Thus, in the same way, we replaced these terms by their corresponding sum. Finally, we obtained a fairly simple formula that was very stable numerically and had a straightforward interpretation: it unifies the contribution of a mean-field approximation (which works very well in systems with several small couplings) with an independent-pair approximation (which performs well in systems...
with few, but strong, couplings). We verified that our formula outperforms existing methods for the inverse Ising model.

A possible future extension of this work might be to find out if other methods of solving the inverse Ising problem can be interpreted in the framework of our expansion. For instance, the susceptibility propagation method is exact on trees, and an interesting perspective would be to associate this method with the exact sum of all terms that are not zero in this case (in the diagrammatic notation we introduced in chapter 5 it should correspond to diagrams that do not contain loops). It might be interesting then to add to our formula the exact sum of all those terms. Another promising venue of research would be to understand what dominates the error of our formula for systems with small couplings, beyond the loop summation we discussed in chapter 5.

Unfortunately, our results have a few limitations. First of all, they cannot work for a system that is magnetized in a ferromagnetic or glassy state or any other system with high correlations. Secondly, while our method of expanding on small-correlation is valid up to any given order, the calculations are impractically long beyond order four.

In the last part this thesis we dealt with the inference of the patterns of a Hopfield model. This approach has several potential advantages: first of all, the Hopfield model can be solved analytically, which should make our calculations more precise and simpler. Moreover, for a fixed number of patterns \( p \), we have only \( pN \) real values to infer while for the inverse Ising problem we had all the \( N(N-1)/2 \) elements of the matrix \( J_{ij} \). Having a smaller number of degrees of freedom can potentially improve the quality of our inference when the input data is noisy, since it can avoid “fitting the noise”. Finally, this model is potentially valid also in the ferromagnetic phase.

To infer the patterns from the data, we used a Bayesian approach: we looked for the set of patterns that maximized the a posteriori probability. We found an explicit result exact in the large system size limit for the patterns in terms of the measured correlations and magnetizations. Since the Hopfield model is a particular case of the generalized Ising model, we could compare this formula with our previous results to show they correspond to the mean-field approximation of part II. The formula corresponds also a the well-known method for extracting patterns from data: the Principal Component Analysis (PCA). Thus, our calculations provide a rigorous justification for this method.

To find a formula that provides a better inference than the mean-field formula, we evaluated the first subleading correction to the patterns. We found a formula that works well with synthetic data obtained by exact enumeration but quickly falls apart for noisy input.

Besides finding an explicit formula for the patterns, we wanted to evaluate how much data is needed for finding a precise estimation of the patterns. For that, we computed the information-theoretical entropy of the inference for a typical realization of the measurements. We find that if the system is magnetized according to a given pattern, the quality of our estimation grows exponentially with the number of measures. Interestingly, this number does not depend of the size of the system in the limit of a very large system. On the other hand, if we are looking for a pattern where none of the measurements were magnetized, one needs a number of measures
that is proportional to the size of the system.

An interesting perspective for future work would be to try to apply the Hopfield results for the data analysis of groups of homologous proteins, where both the PCA and a Hopfield-like Hamiltonian have shown to yield interesting results.

A final remark is that our results can only be used to extract information from data constituting independent samples from a Gibbs distribution, which is not normally true for biological experiments. More precisely, a fundamental premise of our derivations is that the probability of $L$ measured configurations is just the product of $L$ Boltzmann weights.

Concerning experimental data, neuron activity usually present strong temporal correlations. As the free-energy landscape has potentially many minima, it might be that the measured configurations correspond to a very particular subset of all the states and thus the measures are not independent. In the case of protein families, the situation is particularly bad: due to their common evolutionary origin, there is a strong bias favoring sampling proteins similar to their common ancestor. In future investigations, it would be interesting to work around this problem or at least see to which extent it interferes with the inference procedure. A possibility would be to take into consideration two contributions to the probability: a term associated to the fitness of the protein, similar to what was done here, and a term that accounts for the evolutionary history of the family.
Appendix A

Details of the small-$\beta$ expansion

Let $O$ be an observable of the spin configuration (which can explicitly depend on the inverse temperature $\beta$), and

$$\langle O \rangle = \frac{1}{Z} \sum_{\{\sigma\}} O(\{\sigma\}) e^{U(\{\sigma\})}$$  \hspace{1cm} (A.1)

its average value, where $U$ is defined in (4.13), and $Z = \exp(\tilde{S})$. The derivative of the average value of $O$ fulfills the following identity,

$$\frac{\partial \langle O \rangle}{\partial \beta} = \frac{1}{Z} \sum_{\{\sigma\}} \left[ \frac{\partial O}{\partial \beta} + O \frac{\partial U}{\partial \beta} \right] e^U - \frac{1}{Z^2} \frac{\partial Z}{\partial \beta} \sum_{\{\sigma\}} O e^{U} = \left< \frac{\partial O}{\partial \beta} \right> + \left< O \frac{\partial U}{\partial \beta} \right>$$  \hspace{1cm} (A.2)

where the term in $Z^{-2}$ vanishes as a consequence of (4.16).

A.1 Second order expansion

Using (A.2) and (4.21)

$$0 = \frac{\partial^3 \tilde{S}}{\partial \beta^3} = \frac{\partial}{\partial \beta} \left[ \left< \frac{\partial^2 U}{\partial \beta^2} \right> + \left< \frac{\partial U}{\partial \beta} \right> \right] = \left< \frac{\partial^3 U}{\partial \beta^3} \right> + 3 \left< \frac{\partial^2 U \frac{\partial U}{\partial \beta}}{\partial \beta^2} \right> + \left< \frac{\partial U}{\partial \beta} \right>$$  \hspace{1cm} (A.3)

A straightforward calculation gives (where we omit for clarity the notation $|0$ and the $\ast$ subscript from $J_{ij}$ and $\lambda_i$)

$$\left< \frac{\partial^3 U}{\partial \beta^3} \right>_0 = -2 \sum_{i<j} \frac{\partial^2 J_{ij}}{\partial \beta^2} c_{ij}$$  \hspace{1cm} (A.4)

$$\left< \frac{\partial^2 U \frac{\partial U}{\partial \beta}}{\partial \beta^2} \right>_0 = \sum_{i<j} \frac{\partial^2 J_{ij}}{\partial \beta^2} \frac{\partial J_{ij}}{\partial \beta} L_i L_j + \sum_i \frac{\partial^2 \lambda_i}{\partial \beta^2} \frac{\partial \lambda_i}{\partial \beta} L_i$$  \hspace{1cm} (A.5)

$$\left< \frac{\partial U}{\partial \beta} \right>_0^3 = 6 \sum_{i<j<k} \frac{\partial J_{ij}}{\partial \beta} \frac{\partial J_{jk}}{\partial \beta} \frac{\partial J_{ki}}{\partial \beta} L_i L_j L_k +$$

$$+ \sum_{i<j} \left( \frac{\partial J_{ij}}{\partial \beta} \right)^3 4m_i m_j L_i L_j + 6 \sum_{i<j} \frac{\partial J_{ij}}{\partial \beta} \frac{\partial \lambda_i}{\partial \beta} \frac{\partial \lambda_j}{\partial \beta} L_i L_j$$  \hspace{1cm} (A.6)
Using (A.3), the expressions of the derivatives of \( \lambda_i \) in \( \beta = 0 \), we obtain

\[
Q_2 = -4 \sum_{i<j} \frac{c_{ij}^3 m_i m_j}{(1-m_i^2)(1-m_j^2)^2} - 6 \sum_{i<j<k} \frac{c_{ij} c_{jk} c_{ki}}{(1-m_i^2)(1-m_j^2)(1-m_k^2)}
\]  

(A.7)

from which we deduce

\[
\left. \frac{\partial^3 S}{\partial \beta^3} \right|_0 = 4 \sum_{i<j} K_{ij}^3 m_i m_j L_i L_j + 6 \sum_{i<j<k} K_{ij} K_{jk} K_{ki} L_i L_j L_k
\]

(A.8)

and

\[
\left. \frac{\partial^2 J_{ij}}{\partial \beta^2} \right|_0 = -4 m_i m_j K_{ij}^2 - 2 \sum_{k(\neq i, \neq j)} K_{ij} K_{ki} L_k.
\]

(A.9)

### A.2 Third order expansion

The procedure to derive the third order expansion for the coupling is identical to the second order one. We start from

\[
0 = \left. \frac{\partial^4 \hat{S}}{\partial \beta^4} \right|_0 = 3 \left\langle \frac{\partial^4 U}{\partial \beta^4} \right\rangle + 3 \left( \left\langle \frac{\partial^2 U}{\partial \beta^2} \right\rangle \right)^2 + 4 \left( \left\langle \frac{\partial^2 U}{\partial \beta^2} \right\rangle \right)^2 + 2 \left( \left\langle \frac{\partial U}{\partial \beta} \right\rangle \right)^2 + \left\langle \left( \frac{\partial U}{\partial \beta} \right)^4 \right\rangle
\]

(A.10)

and evaluate each term in the sum:

\[
\left\langle \frac{\partial^4 U}{\partial \beta^4} \right\rangle_0 = -3 \sum_{i<j} \left. \frac{\partial^3 J_{ij}}{\partial \beta^3} \right|_0 K_{ij} L_i L_j
\]

(A.11)

\[
\left\langle \left( \frac{\partial^2 U}{\partial \beta^2} \right)^2 \right\rangle_0 = \sum_{i<j} \left( \left\langle \frac{\partial^2 J_{ij}}{\partial \beta^2} \right\rangle \right)^2 L_i L_j + \sum_i \left( \left\langle \frac{\partial^2 \lambda_i}{\partial \beta^2} \right\rangle \right)^2 L_i + \left[ \sum_{i<j} K_{ij}^2 L_i L_j \right]^2
\]

(A.12)

\[
\left\langle \frac{\partial U}{\partial \beta} \right\rangle_0 = \sum_{i<j} K_{ij} \left. \frac{\partial^2 J_{ij}}{\partial \beta^2} \right|_0 L_i L_j
\]

(A.13)

\[
\left\langle \left( \frac{\partial U}{\partial \beta} \right)^4 \right\rangle_0 = \sum_{i<j} K_{ij}^4 (3m_i^2 + 1) L_i (3m_j^2 + 1) L_j + 3 \sum_{i<j, k<l(\neq i,\neq j)} K_{ij}^2 K_{kl}^2 L_i L_j L_k L_l + 6 \sum_{i<j} K_{ij}^2 (3m_i^2 + 1) L_i L_j L_k + 12 \sum_{i<j} K_{ij} K_{jk} K_{kl} L_i L_j L_k L_l [4m_i m_j K_{ij} + 4m_i m_k K_{ij} + 4m_k m_i K_{ki}]
\]

(A.14)

\[
+ 3 \sum_{i,j,k,l(\neq)} K_{ij} K_{jk} K_{kl} L_i L_j L_k L_l
\]

(A.15)
Using the results of Eq. (4.9) and (4.10) we can write all the terms above in the same form

\[-3 \left[ \sum_{i<j} K_{ij}^2 L_i L_j \right]^2 = -3 \sum_{i<j, k<l (k \neq i, l \neq j)} K_{ik}^2 K_{jl}^2 L_i L_j L_k L_l \]

\[-6 \sum_{i<j} K_{ik}^2 K_{kj}^2 L_i L_j L_l^2 \]

\[-3 \sum_{i<j} K_{ij}^2 L_i^2 L_j^2 \]  \hspace{1cm} (A.16)

\[12 \sum_{i<j} \sum_{k} K_{ik} K_{kj} \frac{\partial^2 J_{ij}}{\partial \beta^2} L_i L_j L_k = -48 \sum_{i<j} \sum_{k} K_{ij}^2 K_{kj} m_i m_j L_i L_j L_k - 12 \sum_{i,j,k,l (\neq)} K_{ij} K_{jk} K_{kl} L_i L_j L_k L_l - 24 \sum_{i<j} \sum_{k} K_{ik}^2 K_{kj}^2 L_i L_j L_k^2 \]  \hspace{1cm} (A.17)

\[\sum_{i<j} K_{ij}^2 \frac{\partial^2 J_{ij}}{\partial \beta^2} m_i m_j L_i L_j = -4 \sum_{i<j} K_{ij}^2 m_i^2 m_j^2 L_i L_j - 2 \sum_{i<j} \sum_{k} K_{ij}^2 K_{jk} m_i m_j L_i L_j L_k \]  \hspace{1cm} (A.18)

\[3 \sum_{i<j} \left( \frac{\partial^2 J_{ij}}{\partial \beta^2} \right)^2 L_i L_j = 48 \sum_{i<j} K_{ij}^4 m_i^2 m_j^2 L_i L_j + 48 \sum_{i<j} \sum_{k} K_{ij}^2 K_{kj} m_i m_j L_i L_j L_k + 6 \sum_{i,j,k,l (\neq)} K_{ij} K_{jk} K_{kl} L_i L_j L_k L_l + 12 \sum_{i<j} \sum_{k} K_{ik}^2 K_{kj}^2 L_i^2 L_j L_k \]  \hspace{1cm} (A.19)

\[6 \sum_{i} \sum_{j} K_{ij}^2 \frac{\partial^2 \lambda_i}{\partial \beta^2} (-2 m_i) L_i L_j = -24 \sum_{i} \sum_{j} K_{ij}^4 m_i^2 (1 - m_i^2) L_i L_j - 48 \sum_{i<j} \sum_{k} K_{ik}^2 K_{kj}^2 m_i^2 L_i L_j L_k \]  \hspace{1cm} (A.20)

\[3 \sum_{k} \left( \frac{\partial^2 \lambda_k}{\partial \beta^2} \right)^2 L_k = 24 \sum_{i<j} \sum_{k} K_{ik}^2 K_{jk}^2 m_i^2 L_i L_j L_k + 12 \sum_{i} \sum_{j} K_{ij}^4 m_i^2 L_i L_j^2 \]  \hspace{1cm} (A.21)
Again we find equation (4.34) with
\[
Q_3 = - \sum_{i<j} K_{ij}^4 \left[ (3m_i^2 + 1)(3m_j^2 + 1) - 48m_i^2 m_j^2 \right] L_i L_j + 12 \sum_{i<j} K_{ik}^2 K_{jk}^2 L_i L_j L_k L_l + 12 \sum_{i} K_{ij}^4 m_i^2 L_i L_j^2 + 3 \sum_{i<j} K_{ij}^4 L_i^2 L_j^2 \tag{A.22}
\]
which gives the fourth order contribution to the entropy,
\[
\frac{\partial^4 S}{\partial \beta^4} = -2 \sum_{i<j} K_{ij}^4 \left[ 1 + 3m_i^2 + 3m_j^2 + 9m_i^2 m_j^2 \right] L_i L_j - 12 \sum_{i<j} \sum_k K_{ik}^2 K_{kj}^2 L_i L_j L_k L_l - 24 \sum_{i<j<k<l} (K_{ij} K_{jk} K_{kl} + K_{ik} K_{kj} K_{il} + K_{ij} K_{jl} K_{ki} + K_{ij} K_{kl} K_{li}) L_i L_j L_k L_l \tag{A.23}
\]
and the third order contribution to the coupling,
\[
\frac{\partial^3 J_{ij}}{\partial \beta^3} \bigg|_0 = 2K_{ij}^3 \left[ 1 + 3m_i^2 + 3m_j^2 + 9m_i^2 m_j^2 \right] + 6 \sum_{k (\neq i, \neq j)} K_{ij} (K_{jk}^2 L_j + K_{ki}^2 L_i) L_k + 6 \sum_{k,l (k \neq i, l \neq j)} K_{jk} K_{kl} K_{li} L_k L_l \tag{A.24}
\]
Equation (4.39) suggests that to expand $J^*_{ij}$ to the order of $(L_i)^k$ one has to sum all the diagrams with up to $k + 2$ spins. This statement is true if the expansion for $J^*_{ij}$ is of the form

$$J^*_{ij} = A_{ij} + \sum_k L_k A_{ijk} + \sum_k \sum_l L_k L_l A_{ijkl} + \ldots$$  \hspace{1cm} (B.1)

where the coefficients $A_{i_1 i_2 \ldots i_n}$ are polynomials in the couplings $K_{i_\alpha i_\beta}$ and the magnetizations $m_{\alpha}$ ($\alpha, \beta < n$). In the following we will show that the above statement is true to any order of the expansion in $\beta$ by recurrence. First of all, from (4.10) we see that if $J^*_{ij}$ is of the form (B.1) up to the order $k$, so is $\lambda^*_{ij}$ to the same order.

As we saw in section 4, to find an equation for $\partial_k S / \partial \beta^k$, one must evaluate $\partial_{k+1} \tilde{S} / \partial \beta^{k+1}$. Using Eq. A.2, we can write

$$\frac{\partial^{k+1} \tilde{S}}{\partial \beta^{k+1}} = \left\langle \left( \frac{\partial}{\partial \beta} + \frac{\partial U}{\partial \beta} \right)^k \frac{\partial U}{\partial \beta} \right\rangle = \sum_{\alpha} P_{\alpha} \left\langle \prod_{j=1}^{k+1} \frac{\partial^{\alpha_j} U}{\partial \beta^{\alpha_j}} \right\rangle$$  \hspace{1cm} (B.2)

where $\alpha$ is a multi-index with $|\alpha| = k + 1$ and $P_{\alpha}$ a multiplicity coefficient. The highest order term of this expression evaluates to $\sum_{ij} L_i L_j K_{ij} \partial^{\alpha_j} U / \partial \beta^{\alpha_j} = \partial \tilde{S} / \partial \beta^{k+1}$.

Due to the structure of $U$, spin dependence in (B.2) will come either from the lower derivatives of $J^*_{ij}$ (of the form (B.1) by hypothesis), from the derivatives of $\lambda^*_{ij}$, or explicitly from $\tilde{U}$. In the later case we get a multiplicative factor $(\sigma_i - m_i)$. Hence we end up with computing a term, with $k \geq 1$, of the form

$$\left\langle (\sigma_i - m_i)^k \right\rangle = (-1)^k (1 - m_i^2)^{k-1} = \frac{(m + 1)^{k-1} - (m - 1)^{k-1}}{2}$$  \hspace{1cm} (B.3)

Clearly any term including $(\sigma_i - m_i)$ will give a multiplicative factor $L_i$ after averaging. As spins are decoupled in the $\beta = 0$ limit we obtain the product of those factors over the spins in the diagram as claimed.
APPENDIX B. LARGE MAGNETIZATION EXPANSION
Appendix C

Verification of $h_i(\{c\}, \{m\})$

In this appendix, we used the procedure described in section 4.4.1 to verify all the terms of Eq. (4.40). We start by posing

$$h_i = \frac{1}{2} \ln \left( \frac{1 - m_i}{1 - m_j} \right) - \sum_j J_{ij} m_j + \sum_j K_{ij}^2 m_i L_j + h_i^{(3)} + h_i^{(4)} + O(\epsilon^5) , \quad (C.1)$$

and we will now proceed to evaluate each one of the $h_i^{(k)}$.

C.1 Evaluation of $h_i^{(3)}(\{J\})$

Using Eqs. (4.41) and (4.42), we have

$$6h_i^{(3)} = \frac{\partial}{\partial m_l} \frac{\partial^3 (\beta F)}{\partial \beta^3}$$

$$= -4 \sum_{i<j} J_{ij}^3 \frac{\partial}{\partial m_l} \left[ m_i(1 - m_i^2) m_j(1 - m_j^2) \right]$$

$$- 6 \sum_{i<j<k} J_{ij} J_{jk} J_{ki} \frac{\partial}{\partial m_l} \left[ (1 - m_i^2)(1 - m_j^2)(1 - m_k^2) \right] , \quad (C.2)$$

which can be simplified to

$$6h_i^{(3)} = -4 \sum_{i<j} J_{ij}^3 \left[ \delta_{il}(1 - m_i^2)m_j(1 - m_j^2) - 2 \delta_{im} m_i^2 m_j(1 - m_j^2) \right]$$

$$+ \delta_{jl}(1 - m_j^2)m_i(1 - m_i^2) - 2 \delta_{jm} m_j^2 m_i(1 - m_i^2)$$

$$+ 12 \sum_{i<j<k} J_{ij} J_{jk} J_{ki} \left[ \delta_{im}(1 - m_i^2)(1 - m_k^2) + \delta_{jm}(1 - m_j^2)(1 - m_k^2) \right]$$

$$+ \delta_{km}(1 - m_k^2)(1 - m_j^2) \right] . \quad (C.3)$$
Finally, we get

$$6h_i^{(3)} = -4(1 - m_i^2) \sum_{i \neq l} J_{il}^3 m_i (1 - m_l^2) + 8m_i^2 \sum_{i \neq l} J_{il}^3 m_i (1 - m_l^2) + 12m_i \sum_{i < j \ (i, j \neq l)} J_{il} J_{ij} J_{jl} (1 - m_i^2)(1 - m_j^2).$$

(C.4)

### C.2 Evaluation of $h_i^{(3)}(\{c\})$

We will now use Eq. (C.4) to verify the terms of order $\beta^3$ of Eq. (4.40). We start with Eqs. (C.1) and (C.4)

$$h_i(\{J_{ij}\}) = -\frac{1}{2} \ln \left( \frac{1 - m_i}{1 + m_i} \right) - \sum_{j \neq i} J_{ij} m_j + \sum_{j \neq i} J_{ij}^2 m_i (1 - m_j^2)$$

$$- \frac{2}{3} (1 - m_i^2) \sum_{j \neq i} J_{ij}^3 m_j (1 - m_j^2) + \frac{4}{3} m_i^2 \sum_{j \neq i} J_{ij}^3 m_j (1 - m_j^2)$$

$$+ 2m_i \sum_{j < k \ (j, k \neq i)} J_{ij} J_{jk} J_{ki} (1 - m_j^2)(1 - m_k^2).$$

(C.5)

Using Eq. (4.39), we pose $J_{ij} = K_{ij} - 2K_{ij}^2 m_i m_j - \sum_k K_{jk} K_{ki} (1 - m_k^2) + O(c^3)$, yielding

$$h_i(\{c\}) = -\frac{1}{2} \ln \left( \frac{1 - m_i}{1 + m_i} \right) - \sum_{j \neq i} J_{ij} m_j$$

$$+ \sum_{j \neq i} m_i \left[ K_{ij} - 2K_{ij}^2 m_i m_j - \sum_k K_{jk} K_{ki} (1 - m_k^2) \right]^2 (1 - m_j^2)$$

$$- \frac{2}{3} (1 - m_i^2) \sum_{j \neq i} K_{ij}^3 m_j (1 - m_j^2) + \frac{4}{3} m_i^2 \sum_{j \neq i} K_{ij}^3 m_j (1 - m_j^2)$$

$$+ 2m_i \sum_{j < k} K_{ij} K_{jk} K_{ki} (1 - m_j^2)(1 - m_k^2) + O(c^4).$$

(C.6)

Simplifying this expression, we get

$$h_i(\{J_{ij}\}) = -\frac{1}{2} \ln \left( \frac{1 - m_i}{1 + m_i} \right) - \sum_{j \neq i} J_{ij} m_j + \sum_{j \neq i} K_{ij}^2 m_i (1 - m_j^2)$$

$$- 4 \sum_{j \neq i} K_{ij}^3 m_i^2 m_j (1 - m_j^2)$$

$$- 2 \sum_{j < k} K_{ij} K_{jk} K_{ki} m_i (1 - m_k^2)(1 - m_j^2)$$

$$- \frac{2}{3} (1 - m_i^2) \sum_{j \neq i} K_{ij}^3 m_j (1 - m_j^2) + \frac{4}{3} m_i^2 \sum_{j \neq i} K_{ij}^3 m_j (1 - m_j^2)$$

$$+ 2m_i \sum_{j < k} K_{ij} K_{jk} K_{ki} (1 - m_j^2)(1 - m_k^2) + O(c^4),$$

(C.7)
APPENDIX C. VERIFICATION OF $h_i(\{C\},\{M\})$

and finally

$$h_i(\{J_{ij}\}) = -\frac{1}{2} \ln \left( \frac{1 - m_i}{1 + m_i} \right) - \sum_{j(\neq i)} J_{ij} m_j + \sum_{j(\neq i)} K_{ij}^2 m_i (1 - m_j^2)$$

$$- \frac{2}{3} (1 + 3m_i^2) \sum_{j(\neq i)} K_{ij}^3 m_j (1 - m_j^2)$$

$$- 2m_i \sum_{j < k} K_{ij} K_{jk} K_{ki} (1 - m_j^2)(1 - m_k^2) + O(c^4).$$

Which matches exactly Eq. (4.40).
C.3 Evaluation of $h_i^{(4)}(\{J\})$

Proceeding in the same way as in the last section, we use that $24h_i^{(4)} = \frac{\partial}{\partial m_i} \frac{\partial^4 A}{\partial \beta^4}$ to evaluate this quantity explicitly:

$$24h_i^{(4)} = \frac{\partial}{\partial m_i} \left[ 2 \sum_{i<j} J_{ij}^4 (1 - m_i^2)(1 - m_j^2)(1 + 3m_i^2 + 3m_j^2 - 15m_i^2m_j^2) ight]$$

$$- 48 \sum_{i<j<k} J_{ij}J_{jk}J_{ki}(J_{ij}m_im_j + J_{jk}m_jm_k + J_{ki}m_km_i)(1 - m_i^2)(1 - m_j^2)(1 - m_k^2)$$

$$- 24 \sum_{i<j<k<l} (J_{ij}J_{jk}J_{kl}J_{li} + J_{ik}J_{kj}J_{li}J_{jl} + J_{ij}J_{ji}J_{ki}J_{lk})(1 - m_i^2)(1 - m_j^2)(1 - m_k^2)(1 - m_l^2) \right],$$

$$= 8m_l \sum_{i(\neq l)} J_{il}^4 (1 - m_i^2)(1 - 3m_i^2 - 9m_i^2 + 15m_i^2m_i^2) + 48(3m_l^2 - 1) \sum_i \sum_{j(\neq i)} J_{ij}^2 J_{il}J_{ij}m_i(1 - m_i^2)(1 - m_l^2)$$

$$+ 48m_l \sum_{i} \sum_{j} J_{ij}^2 J_{il}J_{ij}m_i(1 - m_i^2)(1 - m_l^2) + 48m_l \sum_{i} \sum_{j} \sum_{k} J_{ik}J_{jk}J_{ji}J_{il}L_iL_jL_l - 24m_lL_l \sum_{i} \sum_{j} J_{il}^2 J_{ij}L_iL_j L_l \right].$$

Finally, the full value of $h_i(\{J\})$ is

$$h_i(\{J\}) = -\frac{1}{2} \ln \left( \frac{1 - m_l}{1 + m_l} \right) - \sum_{j(\neq i)} J_{ij}m_j + \sum_{j(\neq i)} J_{ij}^2 m_i(1 - m_j^2) - \frac{2}{3}(1 - m_j^2) \sum_{j(\neq i)} J_{ij}^3 m_j(1 - m_j^2) + \frac{4}{3} m_l^2 \sum_{j(\neq i)} J_{ij}^3 m_j(1 - m_j^2)$$

$$+ 2m_l \sum_{j<k} J_{ij}J_{jk}J_{kl}(1 - m_i^2)(1 - m_j^2)(1 - m_k^2) + \frac{1}{3} m_l \sum_{i(\neq l)} J_{il}^4 (1 - m_l^2)(1 - 3m_i^2 - 9m_i^2 + 15m_i^2m_i^2)$$

$$+ 2(3m_l^2 - 1) \sum_{i(\neq l)} \sum_{j(\neq i)} J_{ij}^2 J_{il}J_{ij}m_i(1 - m_i^2)(1 - m_l^2) + 2m_l \sum_{i} \sum_{j} J_{ij}^2 J_{il}J_{ij}m_i(1 - m_i^2)(1 - m_l^2)$$

$$+ 2m_l \sum_{i} \sum_{j} \sum_{k} J_{ik}J_{kj}J_{ji}J_{il}L_iL_jL_l - m_lL_l \sum_{i} \sum_{j} J_{il}^2 J_{ij}L_iL_jL_l \right].$$

(C.10)
C.4 Evaluation of $h_i^{(4)}(\{c\})$

We will now repeat the same procedure of section C.2 up to the order $\beta^4$. Using Eqs. (C.10) and (4.39), we have

$$h_l(\{c\}) = -\frac{1}{2} \ln \left(\frac{1-m_l}{1+m_l}\right) - \sum_{j(\neq l)} J_{ij} m_j + \sum_{j(\neq l)} m_l \left[ K_{ij} - 2K_{lj}^2 m_l m_j - \sum_k K_{jk} K_{kl} (1-m_k^2) + \frac{1}{6} \frac{\partial^3 J_{ij}}{\partial \beta^3} + \ldots \right] (1-m_j^2)$$

$$- \frac{2}{3} (1-m_l^2) \sum_{j(\neq l)} \left[ K_{ij} - 2K_{lj}^2 m_l m_j - \sum_k K_{jk} K_{kl} (1-m_k^2) + \ldots \right] m_j (1-m_j^2)$$

$$+ \frac{4}{3} m_l^2 \sum_{j(\neq l)} \left[ K_{ij} - 2K_{lj}^2 m_l m_j - \sum_k K_{jk} K_{kl} (1-m_k^2) + \ldots \right] m_j (1-m_j^2)$$

$$+ 2m_l \sum_{j<k, (j,k \neq l)} \left[ K_{ij} - 2K_{lj}^2 m_l m_j - \sum_m K_{lm} K_{mj} (1-m_m^2) + \ldots \right] \times

\times \left[ K_{jk} - 2K_{jk}^2 m_j m_k - \sum_m K_{jm} K_{mk} (1-m_m^2) + \ldots \right] \times

\times \left[ K_{kl} - 2K_{kl}^2 m_l m_k - \sum_m K_{km} K_{ml} (1-m_m^2) + \ldots \right] (1-m_j^2)(1-m_k^2)$$

$$+ \frac{1}{3} m_l \sum_{i(\neq l)} K_{il}^2 (1-m_i^2) (1-3m_i^2 - 9m_i^4 + 15m_i^2 m_l^2) + 2(3m_l^2 - 1) \sum_{i, j(\neq i)} K_{il}^2 K_{ij} K_{ij} m_i (1-m_i^2)(1-m_j^2)$$

$$+ m_l \sum_i \sum_{j} K_{ij}^2 K_{ij} K_{ij} m_i (1-m_i^2)(1-m_j^2) + 2m_l \sum_{i<j<k} K_{il} K_{ij} K_{jk} L_i L_j L_k - m_l L_l \sum_j K_{il}^2 K_{lj}^2 L_i L_j .$$
Posing $V_{ij} \equiv -2K_{ij}^2 m_i m_j - \sum_k K_{ik} K_{kj} (1 - m_k^2)$ and ignoring all the terms of order other than $c^4$, we obtain

\begin{align*}
h_i^{(4)}(\{c\}) &= \frac{1}{3} \sum_{j(\neq l)} m_l \frac{\partial^3 J_{ij}}{\partial \beta^3} K_{ij} (1 - m_j^2) + \sum_{j(\neq l)} m_l V_{ij}^2 (1 - m_j^2) - 2(1 - m_l^2) \sum_{j(\neq l)} K_{ij}^2 V_{ij} m_j (1 - m_j^2) \\
&\quad + 4m_l^2 \sum_{j(\neq l)} K_{ij}^2 V_{ij} m_j (1 - m_j^2) + 2m_l \sum_{j < k} (V_{ij} K_{jk} K_{kl} + K_{ij} V_{jk} K_{kl} + K_{ij} K_{jk} V_{kl}) (1 - m_j^2) (1 - m_k^2) \\
&\quad + \frac{1}{3} m_l \sum_{i(\neq l)} K_{il}^4 (1 - m_i^2) (1 - 3m_i^2 - 9m_i^4 + 15m_i^2 m_i^2) + 2(3m_l^2 - 1) \sum_{j(\neq l)} \sum_{j(\neq i)} K_{ij}^2 K_{ij} m_i (1 - m_i^2) (1 - m_j^2) \\
&\quad + 2m_l \sum_{i < j} \sum_{k} K_{ik}^2 K_{ik} K_{jk} m_i m_j (1 - m_i^2) (1 - m_j^2) + 2m_l \sum_{i < j} \sum_{k} K_{ik} K_{jk} K_{kl} L_{ij} L_{jl} L_{ik} - m_l L_l \sum_{i} \sum_{j} K_{ij}^2 K_{ij} L_i L_j.
\end{align*}

We now need to evaluate explicitly the terms in $V_{ij}$, yielding

\begin{align*}
\sum_{j(\neq l)} m_l V_{ij}^2 L_j &= 4m_l^3 \sum_{j(\neq l)} K_{ij}^2 m_j^2 L_j + m_l \sum_{j} \sum_{k(\neq j)} K_{ik}^2 K_{kj} L_k^2 L_j + 2m_l \sum_{i < j} \sum_{k} K_{ik} K_{jk} K_{kl} L_i L_j L_k \\
&\quad - m_l L_l \sum_{j} \sum_{k(\neq j)} K_{ik}^2 K_{ij} L_j L_k + 4m_l^2 \sum_{j} \sum_{k} K_{ij}^2 K_{ik} m_k L_k L_j - 2(1 - m_l^2) \sum_{j} K_{ij}^2 V_{ij} m_j L_j \\
&= 4m_l L_l \sum_{j} K_{ij}^4 m_j^2 L_j + 2L_l \sum_{j} \sum_{k} K_{ij}^2 K_{ik} K_{kj} m_j L_j L_k,
\end{align*}

\text{(C.12)}
\[ 4m_t^2 \sum_{j(\neq l)} K_{lj}^3 V_{lj} m_j L_j = -8m_t^3 \sum_{j} K_{lj}^4 m_j^2 L_j - 4m_t^2 \sum_{j} \sum_{k} K_{lj}^3 K_{lk} K_{k,j} m_j L_j L_k \]
\[ + 2m_i \sum_{j < k (j,k \neq l)} (V_{lj} K_{jk} K_{kl} + K_{lj} V_{lk} K_{kl} + K_{lj} K_{jk} V_{kl}) (1 - m_j^2)(1 - m_k^2) \]
\[ = -4m_t^2 \sum_{j} \sum_{k} K_{lj}^2 K_{kl} K_{k,j} m_j L_j L_k - 2m_i \sum_{k} \sum_{j} K_{lj}^2 K_{lk} K_{ik} m_j m_k L_j L_k - \]
\[ -6m_i \sum_{i < j} \sum_{k} K_{ik} K_{kj} K_{ji} K_{il} L_j L_k L_k - 2m_i \sum_{k} \sum_{j} K_{ik}^2 K_{kj}^2 L_j^2 L_k + 2m_i L_i \sum_{j} \sum_{k} K_{ik}^2 K_{kj}^2 L_k L_j \]  
(C.14)

Using these results, we can write \( h_i^4 \) explicitly:

\[ h_i^4 \{ \{ c \} \} = \frac{1}{3} \sum_{j(\neq l)} m_j \frac{\partial^3 J_{lj}(1 - m_j^2)}{\partial j^3} K_{lj} + 4m_t^3 \sum_{j(\neq l)} K_{lj}^4 m_j^2 L_j + m_i \sum_{j} \sum_{k} K_{lk}^2 K_{kj} L_k L_j - m_i L_i \sum_{j} \sum_{k} K_{lk}^2 K_{lj} L_j L_k \]
\[ + 2m_i \sum_{i < j} \sum_{k} K_{ik} K_{kj} K_{ji} L_i L_j L_k + 4m_t^2 \sum_{j} \sum_{k} K_{lj}^2 K_{lk} K_{k,j} m_k L_j L_k + 4m_i L_i \sum_{j} \sum_{k} K_{lj}^2 m_j^2 L_j \]
\[ + 2L_i \sum_{j} \sum_{k} K_{lj}^2 K_{k,j} m_j L_j L_k - 8m_t^2 \sum_{j} \sum_{k} K_{lj}^2 m_j^2 L_j - 4m_t^2 \sum_{j} \sum_{k} K_{lj}^2 K_{lk} K_{ik} m_j m_k L_j L_k \]
\[ - 4m_i^2 \sum_{j} \sum_{k} K_{lj}^2 K_{kl} K_{k,j} L_j L_k - 2m_i \sum_{k} \sum_{j} K_{lk}^2 K_{jl} K_{ik} m_j m_k L_j L_k - 6m_i \sum_{i < j} \sum_{k} K_{ik} K_{kj} K_{ji} K_{il} L_j L_k \]
\[ - 2m_i \sum_{j} \sum_{k} K_{ik}^2 K_{jk}^2 L_k^2 L_j + 2m_i L_i \sum_{j} \sum_{k} K_{ik}^2 K_{jl} L_k L_j + \frac{1}{3} m_i \sum_{i(\neq l)} K_{il}^3 (1 - m_l^2)(1 - 3m_i^2 - 9m_i^2 + 15m_i^2 m_l^2) \]
\[ + 2(3m_i^2 - 1) \sum_{j(\neq l)} K_{lj}^2 K_{lj} m_j m_i L_i L_j + 2m_i \sum_{j} \sum_{k} K_{ik}^2 K_{jl} K_{j,i} m_j L_i L_j \]
\[ + 2m_i \sum_{i < j} \sum_{k} K_{ik} K_{kj} K_{ji} L_i L_j L_k - m_i L_i \sum_{j} \sum_{k} K_{ij}^2 K_{ji}^2 L_k L_j . \]
This expression can be simplified considerably, yielding

\[
h_i^{(4)}(\{c\}) = \frac{1}{3} \sum_{j(\neq l)} m_l \frac{\partial^3 J_{ij}}{\partial \beta^3} K_{ij} (1 - m_j^2) - m_l \sum_{j(\neq l)} \sum_k K_{ik}^2 K_{kj} L_i^2 L_j - 2m_l \sum_{i<j} \sum_k K_{ik} K_{kj} K_{li} L_i L_j L_k
\]

\[
+ \frac{1}{3} m_l \sum_{i(\neq l)} K_{il}^4 (1 - 3m_i^2 + 3m_i^2 - 9m_i^2 m_l^2) L_i .
\]  

(C.16)

Using our result for \( \frac{\partial^3 J_{ij}}{\partial \beta^3} \), we get

\[
h_i^{(4)}(\{c\}) = \frac{2}{3} m_l \sum_{j(\neq l)} K_{ij}^4 [1 + 3m_i^2 + 3m_j^2 + 9m_i^2 m_j^2] L_j + 2m_l \sum_{j(\neq l)} \sum_{k(\neq l, \neq j)} K_{ij}^2 (K_{jk}^2 L_j + K_{kl}^2 L_k) L_j L_k
\]

\[
+ 2m_l \sum_{j(\neq l)} \sum_{k,m(\text{\textit{distincts}})} K_{ij} K_{jk} K_{km} K_{ml} L_j L_k - m_l \sum_{j(\neq l)} \sum_k K_{ik}^2 K_{kj}^2 L_k^2 L_j
\]

\[
- 2m_l \sum_{i<j} \sum_k K_{ik} K_{kj} K_{li} L_i L_j L_k + \frac{1}{3} m_l \sum_{i(\neq l)} K_{il}^4 (1 - 3m_i^2 + 3m_i^2 - 9m_i^2 m_l^2) L_i .
\]  

(C.17)

Finally, using the identity

\[
2m_l \sum_{j(\neq l)} \sum_{k,m(\text{ \textit{distincts}})} K_{ij} K_{jk} K_{km} K_{ml} L_j L_k L_m = 4m_l \sum_{i<j} \sum_k K_{ik} K_{kj} K_{li} L_i L_j L_k - 2m_l L_i \sum_{j(\neq l)} \sum_k K_{ij}^2 K_{kj}^2 L_i L_j L_k, \tag{C.18}
\]
we get to our final result:

\[
\begin{align*}
    h_1^{(4)}(\{c\}) &= m_l \sum_{j \neq l} K_{lj}^4 \left[ 1 + m_l^2 + 3m_j^2 + 3m_l^2 m_j^2 \right] L_j + m_l \sum_{j \neq l} \sum_k K_{lk} K_{kj} L_k^2 L_j \\
    &\quad + 2m_l \sum_{i < j} \sum_k K_{ik} K_{kj} K_{ii} L_i L_j L_k - 2m_l L_l \sum_i \sum_l K_{il}^2 K_{lj} L_i L_j \\
    &\quad + 2m_l L_i \sum_{j < k} K_{ik}^2 K_{ij}^2 L_j L_k \\
    &= 2m_l \sum_{i < j} \sum_k K_{ik} K_{kj} K_{ii} L_i L_j L_k + m_l \sum_{j \neq l} K_{lj}^4 \left[ 1 + m_l^2 + 3m_j^2 + 3m_l^2 m_j^2 \right] L_j + m_l \sum_{j \neq l} \sum_k K_{lk} K_{kj} L_k^2 L_j. \tag{C.19}
\end{align*}
\]

That confirms, once again, the result found on Eq. (4.40).
APPENDIX C. VERIFICATION OF $h_i(\{C\},\{M\})$
Appendix D

Evaluation of log $Z$

Using Eq. (6.24) and doing an integral transform, we get

$$ \log Z = \int \prod_{\mu=1}^{P} \frac{dm_\mu}{\sqrt{2\pi}} \sum_{\{\sigma\}} \exp \left\{ -\frac{1}{2} \sum_{\mu=1}^{P} m_\mu^2 + \sum_{i} h_i \sigma_i \right\} $$

$$ + \frac{1}{\sqrt{N}} \sum_{\mu} \sum_{i} m_\mu \xi_i^\mu (\sigma_i - \tanh h_i) \right\} , $$

which is just Eq. (2.34) supposing that the magnetizations $m_\mu$ are $O(1/\sqrt{N})$. Doing a Taylor expansion of this equation for large $N$, we have

$$ Z = \exp \left[ \sum_{i} \log(2 \cosh h_i) \right] \int \prod_{\mu} \frac{dm_\mu}{\sqrt{2\pi}} \exp \left[ -\frac{1}{2} \sum_{\mu} \chi_\mu m_\mu^2 \right. $$

$$ + \frac{1}{2\sqrt{N}} \sum_{\mu \neq \nu} s_{\mu \nu} m_\mu m_\nu $$

$$ \left. - \frac{1}{12N} \sum_{i} \left( \sum_{\mu} m_\mu \xi_i^\mu \right)^4 (1 - 3 \tanh^2 h_i)(1 - \tanh^2 h_i) \right] $$

$$ + O(1/N^2) \right] , $$

where

$$ \chi_\mu = 1 - \frac{1}{N} \sum_{i} (\xi_i^\mu)^2 (1 - \tanh^2 h_i) , $$

and

$$ s_{\mu \nu} = \frac{1}{\sqrt{N}} \sum_{\xi_i^\mu \xi_i^\nu} (1 - \tanh^2 h_i) . $$
We use the expansion of $e^x = 1 + x + \cdots$ to write this equation as a gaussian integral

$$Z = \exp \left[ \sum_i \log(2 \cosh h_i) \right] \int \prod_{\mu} \frac{dm_\mu}{\sqrt{2\pi}} \left[ 1 + \frac{1}{2\sqrt{N}} \sum_{\mu \neq \nu} s_{\mu\nu} m_\mu m_\nu \right.$$

$$\left. + \frac{1}{8N} \left( \sum_{\mu \neq \nu} s_{\mu\nu} m_\mu m_\nu \right)^2 \right.$$

$$\left. - \frac{1}{12N^2} \sum_i \left( \sum_{\mu} m_\mu \xi_\mu^i \right)^4 (1 - 3 \tanh^2 h_i)(1 - \tanh^2 h_i) \right]$$

$$\cdot \exp \left[ -\frac{1}{2} \sum_{\mu} \chi_\mu m_\mu^2 \right], \quad \text{(D.5)}$$

which can be rewritten as averages in respect to a gaussian distribution

$$Z = \exp \left[ \sum_i \log(2 \cosh h_i) - \frac{1}{2} \sum_{\mu} \log \chi_\mu \right] .$$

$$\left\langle 1 + \frac{1}{4N} \sum_{\mu \neq \nu} s_{\mu\nu}^2 m_\mu^2 m_\nu^2 \right.$$

$$\left. - \frac{1}{12N^2} \sum_i \left( \sum_{\mu} m_\mu \xi_\mu^i \right)^4 (1 - 3 \tanh^2 h_i)(1 - \tanh^2 h_i) \right.$$

$$\left. + O(1/N^{3/2}) \right\rangle_m. \quad \text{(D.6)}$$

Those averages can be easily calculated:

$$\left\langle \frac{1}{4N} \sum_{\mu \neq \nu} s_{\mu\nu}^2 m_\mu^2 m_\nu^2 \right\rangle_m = \frac{1}{4N} \sum_{\mu \neq \nu} s_{\mu\nu}^2 \chi_\mu \chi_\nu, \quad \text{(D.7)}$$

$$\left\langle \left( \sum_{\mu} m_\mu \xi_\mu^i \right)^4 \right\rangle_m = \left\langle \sum_{\mu} m_\mu^4 (\xi_\mu^i)^4 \right\rangle_m + 3 \left\langle \sum_{\mu \neq \nu} m_\mu^2 m_\nu^2 (\xi_\mu^i)^2 (\xi_\nu^i)^2 \right\rangle_m + \text{odd terms} =$$

$$= 3 \sum_{\mu} \frac{(\xi_\mu^i)^4}{\chi_\mu^2} + 3 \sum_{\mu \neq \nu} \frac{(\xi_\mu^i)^2 (\xi_\nu^i)^2}{\chi_\mu \chi_\nu} \quad \text{(D.8)}$$

Finally, we pose

$$r_{\mu\nu} = \frac{1}{N} \sum_i (\xi_\mu^i)^2 (\xi_\nu^i)^2 (1 - 3 \tanh^2 h_i)(1 - \tanh^2 h_i), \quad \text{(D.9)}$$

and

$$s_{\mu\mu} = 0 \; \text{.} \quad \text{(D.10)}$$
which gives an explicit form for \( \log Z \):

\[
\log Z = \sum_i \log(2 \cosh h_i) - \frac{1}{2} \sum_\mu \log \chi_\mu + \frac{1}{4N} \sum_{\mu,\nu} \frac{(1 - \delta_{\mu\nu}) s_{\mu\nu}^2 - r_{\mu\nu}}{\chi_\mu \chi_\nu} a + O(1/N^{3/2}),
\]

(D.11)

where \( \delta_{\mu\nu} \) is the Kronecker symbol.
Appendix E

Evaluation of $m$ for the entropy of the Ising model

Starting with Eq. (7.13):

$$m_l = \frac{1}{N} \sum_i \sigma_i \tanh \left( \beta \sum_s m_s \sigma_i^s \right), \quad (E.1)$$

which under the hypothesis of $m_l = m$ can be rewritten as

$$m = \left\langle \frac{1}{N} \sum_i \sigma_i \tanh \left( \beta \sum_s m_s \sigma_i^s \right) \right\rangle,$$

$$= \sum_{\{\sigma\}} \sigma^l \tanh \left( \beta m \sum \sigma^l \right) \prod_{l=1}^{L} \frac{e^{\beta m^* \sigma^l \tilde{\xi}}}{2 \cosh(\beta m^*)}. \quad (E.2)$$

This last equation can be simplified using the variable change $\sigma^l \to \sigma^l \tilde{\xi}$:

$$m = \sum_{\{\sigma\}} \sigma^l \tanh \left( \beta m \sum \sigma^l \right) \prod_{l=1}^{L} \frac{e^{\beta m^* \sigma^l \tilde{\xi}}}{2 \cosh(\beta m^*)}, \quad (E.3)$$

$$= \frac{1}{L} \sum_{\{\sigma\}} \left( \sum_l \sigma^l \right) \tanh \left( \beta m \sum \sigma^l \right) \prod_{l=1}^{L} \frac{e^{\beta m^* \sigma^l \tilde{\xi}}}{2 \cosh(\beta m^*)}, \quad (E.4)$$

$$= \frac{1}{2L \left[ 2 \cosh(\beta m^*) \right]^L} \left[ \sum_{\{\sigma\}} \left( \sum_l \sigma^l \right) \tanh \left( \beta m \sum \sigma^l \right) \exp \left( \beta m^* \sum_{l=1}^{L} \sigma^l \right) \right.$$  

$$+ \sum_{\{\sigma\}} \left( \sum_l \sigma^l \right) \tanh \left( \beta m \sum \sigma^l \right) \exp \left( \beta m^* \sum_{l=1}^{L} \sigma^l \right) \left]. \quad (E.5)$$

Using the global symmetry $\sigma^l \to -\sigma^l$:

$$m = \frac{1}{L \left[ 2 \cosh(\beta m^*) \right]^L} \sum_{\{\sigma\}} \left( \sum_l \sigma^l \right) \tanh \left( \beta m \sum \sigma^l \right) \cosh \left( \beta m^* \sum_{l=1}^{L} \sigma^l \right).$$
We verify the solution of this equation is $m = m^*$:

$$m = 1/L [2 \cosh(\beta m)]^L \sum_{\{\sigma\}} \left( \sum_l \sigma_l \right) \sinh \left( \beta m \sum_l \sigma_l \right)$$

$$= 1/\beta L [2 \cosh(\beta m)]^L \frac{\partial}{\partial m} \sum_{\{\sigma\}} \cosh \left( \beta m \sum_l \sigma_l \right)$$

$$= 1/\beta L [2 \cosh(\beta m)]^L \frac{\partial}{\partial m} [2 \cosh(\beta m)]^L$$

$$= \tanh(\beta m). \quad (E.6)$$

From which follows the result, since $m^*$ is defined as the solution of $m^* = \tanh(\beta m^*)$. 

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Appendix F

Evaluation of $\tilde{N}$ in the paramagnetic phase

We start with Eq. (7.20):

\[
\tilde{N} = \int \prod_{l=1}^{L} \frac{d\tilde{m}_l}{\sqrt{2\pi}^{N-1}} \sum_{\{\xi\}} \exp \left[ -\frac{\beta N}{2} \sum_{l=1}^{L} m_l^2 + \right. \\
+ \beta \sum_{l=1}^{L} m_l \sum_i \sigma_l^i \xi_i \left. \right]\, , \tag{F.1}
\]

which after averaging yields

\[
\langle \tilde{N}^n \rangle = e^{-\beta L n/2} \sum_{\{\xi\}} \int \prod_{l=1}^{L} \prod_{\rho=1}^{n} \frac{d\tilde{m}_l^\rho}{\sqrt{2\pi}} \times \\
\quad \times \left\langle \exp \left\{ \beta N \left[ -\frac{1}{2} \sum_{l,\rho} (m_l^\rho)^2 + \sum_{l,\rho} m_l^\rho \frac{1}{N} \sum_i \xi_i^\rho \sigma_i^l \right] \right\} \right\rangle \\
= e^{-\beta L n/2} \sum_{\{\xi\}} \int \prod_{l=1}^{L} \prod_{\rho=1}^{n} \frac{d\tilde{m}_l^\rho}{\sqrt{2\pi}} \sum_{\{\xi\},\{\sigma\}} \exp \left[ -\frac{\beta N}{2} \sum_{l,\rho} (m_l^\rho)^2 + \right. \\
+ \beta N \sum_{l,\rho} m_l^\rho \frac{1}{N} \sum_i \xi_i^\rho \sigma_i^l + \frac{\tilde{\beta}}{N} \sum_i \sum_{i<j} \sigma_i^l \sigma_j^l \tilde{\xi}_i \tilde{\xi}_j \left. \right]\, . \tag{F.2}
\]

Doing an integral transformation and making the sum over $\sigma$, we obtain

\[
\langle \tilde{N}^n \rangle = e^{-\beta L n/2} \sum_{\{\xi\},\{\xi\}} \int \prod_{l=1}^{L} \frac{d\tilde{m}_l^\rho}{\sqrt{2\pi}} \frac{d\tilde{m}_l^\rho}{\sqrt{2\pi}} \exp \left[ -\frac{\beta N}{2} \sum_{l,\rho} (m_l^\rho)^2 + \right. \\
-\frac{\beta N}{2} \sum_{l} (\tilde{m}_l)^2 + \sum_{l,l} \ln 2 \cosh \left( \beta \sum_{\rho} m_l^\rho \xi_i^\rho + \tilde{\beta} \tilde{m}_l \tilde{\xi}_l \right) \left. \right]\, . \tag{F.3}
\]
Applying the variable change $\frac{4}{N}m^2 \to m^2$, $\frac{\beta}{N}\tilde{m}^2 \to \tilde{m}^2$, we have

\[
\langle \tilde{N}^n \rangle = e^{-\beta N/2} \sum_{\{\xi_1, \ldots, \xi_i\}} \int \prod_{l, \rho} \frac{d\xi^\rho_l}{\sqrt{2\pi}} \frac{d\tilde{m}_l}{\sqrt{2\pi}} \exp \left[ -\frac{1}{2} \sum_{l, \rho} (\xi^\rho_l)^2 - \frac{1}{2} \sum_l (\tilde{m}_l)^2 \right] \\
+ \sum_{i, l} \ln 2 \cosh \left( \sqrt{\frac{\beta}{N}} \sum_{\rho} m^\rho_i \xi^\rho_l + \sqrt{\frac{\beta}{N}} \tilde{m}_l \tilde{\xi}_i \right). \quad (F.4)
\]

Since that for small $x$, $\ln [2 \cosh(x)] = \ln(2) + \frac{x^2}{2} + O(x^4)$, we can approximate this expression by

\[
\langle \tilde{N}^n \rangle \approx e^{-\beta N/2} \sum_{\{\xi_1, \ldots, \xi_i\}} \int \prod_{l, \rho} \frac{d\xi^\rho_l}{\sqrt{2\pi}} \frac{d\tilde{m}_l}{\sqrt{2\pi}} \exp \left[ -\frac{1}{2} \sum_{l, \rho} (\xi^\rho_l)^2 - \frac{1}{2} \sum_l (\tilde{m}_l)^2 + L \ln 2 + \sum_{i, l, \rho, \alpha} m^\rho_i m_\rho^\alpha \xi^\rho_l \xi^\alpha_i + \frac{\beta}{2} \sum_l (\tilde{m}_l)^2 + \sqrt{\frac{\beta \beta}{N}} \sum_{l, \rho, i} m^\rho_i \tilde{m}_l \xi^\rho_l \tilde{\xi}_i \right] \\
\approx \sum_{\{\xi_1, \ldots, \xi_i\}} [\det M]^{-L/2} e^{-\beta N/2}, \quad (F.5)
\]

where $M$ is the matrix

\[
\begin{pmatrix}
1 - \tilde{\beta} & -\sqrt{\frac{\beta}{N}} \sum_i \xi^1_i \tilde{\xi}_i & -\sqrt{\frac{\beta}{N}} \sum_i \xi^2_i \tilde{\xi}_i & \cdots & -\sqrt{\frac{\beta}{N}} \sum_i \xi^n_i \tilde{\xi}_i \\
-\sqrt{\frac{\beta}{N}} \sum_i \xi^1_i \tilde{\xi}_i & 1 - \beta & -\frac{\beta}{N} \sum_i \xi^1_i \xi^2_i & \cdots & -\frac{\beta}{N} \sum_i \xi^1_i \xi^n_i \\
-\sqrt{\frac{\beta}{N}} \sum_i \xi^2_i \tilde{\xi}_i & -\frac{\beta}{N} \sum_i \xi^1_i \xi^2_i & 1 - \beta & \cdots & -\frac{\beta}{N} \sum_i \xi^2_i \xi^n_i \\
\vdots & \vdots & \vdots & \ddots & \vdots \\
-\sqrt{\frac{\beta}{N}} \sum_i \xi^n_i \tilde{\xi}_i & -\frac{\beta}{N} \sum_i \xi^1_i \xi^n_i & -\frac{\beta}{N} \sum_i \xi^2_i \xi^n_i & \cdots & 1 - \beta
\end{pmatrix}. \quad (F.6)
\]

Fixing $q_{\rho\sigma} = \frac{1}{N} \sum_i \xi^\rho_i \xi^\sigma_i$ and $\rho = \frac{1}{N} \sum_i \xi^\rho_i \tilde{\xi}_i$ with the Lagrange multipliers $\hat{q}_{\rho\sigma}$ and $\hat{\rho}$, we have

\[
\langle \tilde{N}^n \rangle = \int \prod_{\rho < \sigma} dq_{\rho\sigma} \, d\hat{q}_{\rho\sigma} \, dt_\rho \, d\hat{\rho} \sum_{\{\xi_1, \ldots, \xi_i\}} \exp N \cdot \left[ -\frac{\alpha}{2} \log \det M - \frac{\alpha}{2} \sum_{\rho < \sigma} \hat{q}_{\rho\sigma} q_{\rho\sigma} \right. \\
\left. - \frac{\alpha}{2} \sum_\rho \hat{\rho} t_\rho + \frac{\alpha}{2} \sum_{\rho < \sigma} \frac{1}{N} \sum_i \hat{q}_{\rho\sigma} \xi^\rho_i \xi^\sigma_i + \frac{\alpha}{2} \sum_\rho \hat{\rho} \frac{1}{N} \tilde{\xi}_i \xi^\rho_i - \frac{\alpha \beta n}{2} \right]. \quad (F.7)
\]

Since now the sites are completely uncorrelated, we can write this expression in a form solvable by the saddle-point method:

\[
\langle \tilde{N}^n \rangle = \int \prod_{\rho < \sigma} dq_{\rho\sigma} \, d\hat{q}_{\rho\sigma} \, dt_\rho \, d\hat{\rho} \, H^N, \quad (F.8)
\]
where $H$ is given by

$$
H = \sum_{\{\xi\}, \{\tilde{\xi}\}} \exp \left[ -\frac{\alpha}{2} \log \det M - \alpha \sum_{\rho<\sigma} \hat{q}_{\rho\sigma} q_{\rho\sigma} - \frac{\alpha}{2} \sum_{\rho} \hat{q}_\rho \hat{\xi}_\rho - \frac{\alpha \beta n}{2} \right]. \tag{F.9}
$$

We will look to the replica-symmetric saddle point of $H$. Posing $q_{\rho\sigma} = q$, $t_\rho = t$, $\hat{q}_{\rho\sigma} = \hat{q}$ and $\hat{t}_{\rho} = \hat{t}$, we have

$$
H = \sum_{\{\xi\}, \{\tilde{\xi}\}} \exp \left[ -\frac{\alpha}{2} \log \det M - \frac{\alpha n(n-1)}{2} \hat{q} q - \frac{\alpha}{2} \sum_{\rho<\sigma} \xi_\rho \xi_\sigma - \frac{\alpha}{2} \sum_{\rho} \hat{\xi}_\rho - \frac{\alpha \beta n}{2} \right], \tag{F.10}
$$

Since we can do a variable change $\xi_\rho \to \xi_\rho \tilde{\xi}$, this expression evaluates to

$$
H = \int_0^\infty \frac{dz}{\sqrt{2\pi}} \sum_{\{\xi\}, \{\tilde{\xi}\}} \exp \left[ -\frac{z^2}{2} - \frac{\alpha}{2} \log \det M - \frac{\alpha n(n-1)}{4} \hat{q} q - \frac{\alpha}{2} \sum_{\rho<\sigma} \xi_\rho \xi_\sigma - \frac{\alpha}{2} \sum_{\rho} \hat{\xi}_\rho - \frac{\alpha \beta n}{2} \right]. \tag{F.11}
$$

Now we need to evaluate explicitly $\det M$ in the replica-symmetric hypothesis:

$$
\det M = (1 - \beta + \beta q)^{n-1} \times \left[ (1 - \beta)(1 - \beta) - (n - 1)(1 - \beta^2) q - n\beta \hat{t}^2 \right], \tag{F.12}
$$

$$
\log(\det M) = \log(1 - \beta) + n \log [1 - \beta(1 - q)] - \frac{n\beta}{1 - (1 - q)\beta} \left( \frac{t^2 \hat{t}}{1 - \beta} + q \right) + O(n^2). \tag{F.13}
$$

After a small calculation, we find the saddle-point equations

$$
t = \left\langle \tanh \left( \frac{\alpha t}{2} + z \sqrt{\alpha q} \right) \right\rangle, \tag{F.14}
$$

$$
q = \left\langle \left[ \tanh \left( \frac{\alpha t}{2} + z \sqrt{\alpha q} \right) \right]^2 \right\rangle, \tag{F.15}
$$

$$
\hat{t} = \frac{2t \beta^2}{(1 - \beta)(1 - (1 - q)\beta)}, \tag{F.16}
$$

$$
\hat{q} = \beta^2 \frac{q(1 - \beta) + t^2 \beta}{(1 - \beta)(1 - (1 - q)\beta)^2}. \tag{F.17}
$$
where the average $\langle \cdot \rangle$ is in respect to the gaussian variable $z$ of zero mean and standard deviation $\sigma = 1$.

Finally, the entropy can be written as

$$
\langle S \rangle = -\frac{\alpha \beta (1 - q) \{1 - \beta [2 - 2q(1 - \beta) - (1 + t^2)\beta]\}}{2(1 - \beta) [1 - (1 - q)\beta]^2} - \frac{\alpha}{2} \ln [1 - (1 - q)\beta] \\
+ \left\langle \ln \left[ 2 \cosh \left( \frac{\alpha}{2} \tilde{t} + z \sqrt{\alpha q} \right) \right] \right\rangle - \frac{\alpha}{2} \left[ (1 - q)\tilde{q} + t\tilde{t} \right].
$$

(F.18)
Appendix G

Entropy calculations details for continuous patterns

Our starting points are Eqs. (7.32) and (7.35):

\[
\tilde{N}[(\sigma^\nu), \beta] = \int dx \int dm \prod_{i} d\xi_i \exp \left( \frac{\beta}{N} \sum_{l=0}^{L} \sum_{i<j} \xi_i \sigma^l_i \sigma^l_j + \frac{\beta LN}{2} m^2 - \beta L \sum_{i} \log [2 \cosh(m \xi_i)] \right. \\
+ \beta \sum_{\nu=1}^{n} \sum_{\nu'=1}^{n} \log P_0(\{\xi^\nu_i\}) - i N x m + i \sum_{i} \xi_i \tanh(m \xi_i) \right). \\
\text{(G.1)}
\]

In the same way as with continuous patterns, we will use the replica trick to evaluate \( \log \tilde{N} \)

\[
\tilde{N}[(\sigma^\nu), \beta]^{n} = \int \prod_{\nu} dx^\nu \int \prod_{\nu} dm^\nu \prod_{i=1}^{n} \prod_{\nu} d\xi^\nu_i \exp \left\{ \right. \\
\frac{\beta}{N} \sum_{i<j}^{n} \sum_{\nu=1}^{n} \sum_{l=1}^{L} \xi^\nu_i \xi^\nu_j \sigma^l_i \sigma^l_j + \beta \sum_{\nu=1}^{n} \log P_0(\{\xi^\nu_i\}) \\
+ \frac{\beta LN}{2} \sum_{\nu=1}^{n} (m^\nu)^2 - \beta L \sum_{\nu=1}^{n} \sum_{i} \log [2 \cosh(m^\nu \xi^\nu_i)] \\
- i N \sum_{\nu} x^\nu m^\nu + i \sum_{\nu} \sum_{i} \xi^\nu_i \tanh(m^\nu \xi^\nu_i) \left\} \right., \\
\text{(G.2)}
\]

and we will average the entropy with respect to all possible realizations of the measurements taken from a system where the patterns are given by \( \{\tilde{\xi}_i\} \):

\[
\langle \tilde{N}[(\sigma^\nu), \beta]^{n} \rangle = \sum_{(\sigma)} \frac{1}{Z(\{\tilde{\xi}_i\})} \tilde{N}[(\sigma^\nu), \beta]^{n} \exp \left[ \frac{1}{N} \sum_{l=1}^{L} \sum_{i<j} \tilde{\xi}_i \tilde{\xi}_j \sigma^l_i \sigma^l_j \right]. \\
\text{(G.3)}
\]
Finally we average in respect to the underlying patterns \( \{ \tilde{\xi}_i \} \)

\[
\left\langle \tilde{N} \{ \sigma \}, \beta \right\rangle^n = \int \prod_i d\tilde{\xi}_i \sum_{\{\sigma\}} \frac{1}{Z(\{\xi_i\})^L} \tilde{N}[\{\sigma'\}, \beta]^n \exp \left[ \frac{1}{N} \sum_{l=1}^L \sum_{i<j} \tilde{\xi}_i \tilde{\xi}_j \sigma'_i \sigma'_j + \log P(0(\tilde{\xi}_i)) \right] 
\]

(G.4)

Note that we used the same function \( P(0(\{\xi_i\})) \) both as the prior and as the distribution of the “real” patterns \( \{ \tilde{\xi}_i \} \). It is equivalent to say that one knows the statistical distribution of \( \{ \tilde{\xi}_i \} \), but wants to infer one particular realization of this distribution.

Writing the average explicitly and doing a gaussian transform, we have

\[
\left\langle \tilde{N} \{ \sigma \}, \beta \right\rangle^n = \int \left( \prod_{\nu=1}^n \prod_i d\xi^\nu_i \right) \left( \prod_i d\tilde{\xi}_i \right) \left( \prod_{\nu=1}^n \prod_{l=1}^L \frac{dQ^\nu_l}{\sqrt{2\pi}} \right) \left( \prod_{l=1}^L \frac{d\tilde{Q}_{ll}}{\sqrt{2\pi}} \right) \times
\]

\[
\left( \prod_{\nu=1}^n \int d\mu^{\nu} \right) \left( \prod_{\nu=1}^n \frac{dx^{\nu}}{\sqrt{2\pi}} \right) \frac{dy}{\sqrt{2\pi}} d\tilde{m} \sum_{\{\sigma\}} \exp(H),
\]

(G.5)

where

\[
H = -\frac{\beta N}{2} \sum_{\nu=1}^n \sum_{l=1}^L (Q^\nu_l)^2 - \frac{N}{2} \sum_{l=1}^L (\tilde{Q}_l)^2 + \beta \sum_{\nu=1}^n \sum_{l=1}^L (Q^\nu_l \xi^\nu_l \sigma^l) + \beta \sum_{\nu=1}^n \sum_{i=1} \tilde{Q}_l \tilde{\xi}_i \sigma^l + \beta \sum_{\nu=1}^n \log P(\xi^\nu) + \log P(\tilde{\xi})
\]

\[
+ \frac{\beta L N}{2} \sum_{\nu=1}^n \sum_{i=1}^n (m^\nu_i)^2 + \frac{LN}{2} \tilde{m}^2 - \beta L \sum_{\nu=1}^n \sum_{i=1} \log [2 \cosh(m^\nu_i \xi^\nu_i)]
\]

\[
- L \sum_{\nu=1}^n \log \left[ 2 \cosh(\tilde{m} \xi^\nu_i) \right] - iN \sum_{\nu=1}^n x^{\nu} m^\nu - iNy \tilde{m} + i \sum_{\nu=1}^n \sum_{i=1} x^{\nu} \xi^\nu_i \tanh(m^\nu_i \xi^\nu_i) + iy \sum_{i=1}^n \tilde{\xi}_i \tanh(\tilde{m} \xi^\nu_i).
\]

(G.6)

We now suppose that the prior probability of the patterns are independent and identically distributed across the sites. Mathematically, that means that \( P(0(\{\xi_i\})) = \prod_i p(0(\xi_i)) \). Under that supposition we can make the sites decoupled, so we have

\[
\left\langle \tilde{N} \{ \sigma \}, \beta \right\rangle^n = \int \left( \prod_{\nu=1}^n \prod_{l=1}^L \frac{dQ^\nu_l}{\sqrt{2\pi}} \right) \left( \prod_{l=1}^L \frac{d\tilde{Q}_l}{\sqrt{2\pi}} \right) \left( \prod_{\nu=1}^n dm^{\nu} \right) \times
\]

\[
\left( \prod_{\nu=1}^n \frac{dx^{\nu}}{\sqrt{2\pi}} \right) \frac{dy}{\sqrt{2\pi}} \tilde{m} A^N \exp(NB),
\]

(G.7)
where

\[
B = \frac{\beta}{2} \sum_{\nu=1}^{n} \sum_{l=1}^{L} (Q_{l}^{\nu})^{2} - \frac{1}{2} \sum_{l=1}^{L} (\dot{Q}_{l})^{2} + \frac{\beta L}{2} \sum_{\nu=1}^{n} (m^{\nu})^{2} \\
+ \frac{L}{2} \hat{m}^{2} - i \sum_{\nu=1}^{n} x^{\nu} m^{\nu} - iy \hat{m},
\]

\( (G.8) \)

\[
A = \int d\hat{\xi}p_{0}(\hat{\xi}) \sum_{\{\sigma\}} \exp \left[ \sum_{l=1}^{L} \dot{Q}_{l} \tilde{\xi} \sigma^{l} - L \log (2 \cosh (\hat{m} \tilde{\xi})) \right] \\
+ iy \hat{\xi} \tanh (\hat{m} \tilde{\xi}) + \sum_{\nu=1}^{n} \log C_{\nu},
\]

\( (G.9) \)

\[
C_{\nu} = \int d\xi \exp \left[ \beta \sum_{l=1}^{L} Q_{l}^{\nu} \xi \sigma^{l} + \beta \log p_{0}(\xi) \right] \\
- \beta L \log (2 \cosh (m^{\nu} \xi)) + ix^{\nu} \xi \tanh (m^{\nu} \xi).
\]

\( (G.10) \)

Like we did previously, we look for the replica-symmetric saddle-point of this integral

\[
\dot{Q}_{l} = \hat{m} = \int d\hat{\xi}p_{0}(\hat{\xi}) \tilde{\xi} \tanh (\hat{m} \tilde{\xi}) = \left\langle \tilde{\xi} \tanh (\hat{m} \tilde{\xi}) \right\rangle,
\]

\( (G.11) \)

\[
m = \int d\tilde{\xi} \sum_{\{\sigma\}} \exp \left[ \sum_{l=1}^{L} \dot{m} \tilde{\xi} \sigma^{l} - L \log 2 \cosh (\hat{m} \tilde{\xi}) \right] \times \\
\int d\xi p_{0}(\xi) \xi \tanh (m \xi) \exp \left[ \sum_{l=1}^{L} Q_{l} \sigma^{l} \xi - L \log 2 \cosh (m \xi) \right] ,
\]

\( (G.12) \)

\[
Q_{k} = \int d\xi \sum_{\{\sigma\}} \exp \left[ \sum_{l=1}^{L} \dot{m} \tilde{\xi} \sigma^{l} - L \log 2 \cosh (\hat{m} \tilde{\xi}) \right] \times \\
\int d\xi p_{0}(\xi) \xi \sigma^{l} \exp \left[ \sum_{l=1}^{L} Q_{l} \sigma^{l} \xi - L \log 2 \cosh (m \xi) \right] ,
\]

\( (G.13) \)
Finally, we have

\[
\frac{1}{N} \langle \log \tilde{N} \rangle = \frac{\beta}{2} \sum_{l=1}^{L} Q_l^2 + \frac{\beta L m^2}{2} \\
+ \int d\tilde{\xi} p_0(\tilde{\xi}) \sum_{\{\sigma^l\}} \exp \left[ \tilde{m} \tilde{\xi} \sum_{l=1}^{L} \sigma^l - L \log(2 \cosh(\tilde{m} \tilde{\xi})) \right] \times \\
\times \log \left\{ \int d\xi \exp \left[ \beta \sum_{l=1}^{L} Q_l \xi \sigma^l - \beta L \log(2 \cosh(m \xi)) + \beta \log p_0(\xi) \right] \right\},
\]

from which it is straightforward to evaluate the entropy using Eq. (7.33).
Appendix H

Details of the evaluation of the entropy for the Hopfield model

Starting with Eq. (7.48), we have

\[
\langle N^n \rangle = \frac{1}{2N} \sum_{\{\xi^1\}} \frac{1}{2N} \sum_{\{\xi^2\}} \sum_{\{\sigma\}} \sum_{\{\xi^{2,\nu}\}} \exp \left\{ \beta \sum_{\nu=1}^{N} \sum_{l=1}^{L} \sum_{i,j} \sigma_i^l \sigma_j^l (\xi_i^1 \xi_j^2 + \xi_i^{2,\nu} \xi_j^{2,\nu}) \right. \\
- \beta \sum_{\nu=1}^{N} \sum_{l=1}^{L} \sum_{i,j} \sigma_i^l \sigma_j^l (\xi_i^1 \xi_j^2 + \xi_i^{2,\nu} \xi_j^{2,\nu}) \\
- \beta \sum_{\nu=1}^{N} \sum_{l=1}^{L} \sum_{i,j} \sigma_i^l \sigma_j^l (\xi_i^{2,\nu} \xi_j^{2,\nu}) \\
- \beta \sum_{\nu=1}^{N} \sum_{l=1}^{L} \sum_{i,j} \sigma_i^l \sigma_j^l (\xi_i^{2,\nu} \xi_j^{2,\nu}) \\
\left. \right\} \cdot \\
\sum_{\{\xi^1\}} \sum_{\{\xi^2\}} \sum_{\{\sigma\}} \sum_{\{\xi^{2,\nu}\}} \int \left( \prod_{l} \frac{\text{d}m_l^1}{\sqrt{2\pi}} \right) \left( \prod_{l,\nu} \frac{\text{d}m_l^{2,\nu}}{\sqrt{2\pi}} \right) \left( \prod_{l} \frac{\text{d}\tilde{m}_l}{\sqrt{2\pi}} \right) e^{N E_1},
\]  

(H.1)

where

\[
E_1 = (\beta n + \tilde{\beta}) \frac{1}{N} \sum_{i} \sum_{l} \sigma_i^l \xi_i^1 m_l^1 + \beta \frac{1}{N} \sum_{i} \sum_{l} \sum_{\nu} \sigma_i^l \xi_i^{2,\nu} m_l^{2,\nu} + \tilde{\beta} \frac{1}{N} \sum_{i} \sum_{l} \sigma_i^l \tilde{\xi}_i^2 \tilde{m}_l \\
- \beta n + \tilde{\beta} \frac{2}{}\sum_{l} (m_l^1)^2 - \beta \frac{2}{}\sum_{l,\nu} (m_l^{2,\nu})^2 - \tilde{\beta} \frac{2}{}\sum_{l} \tilde{m}_l^2 - 2 \log 2 \\
- \frac{L}{N} \log Z_{\text{Hop}} \left[ \tilde{\beta}, \{\xi^1\}, \{\xi^{2}\} \right] - \frac{\beta}{\tilde{\beta}} \frac{L}{N} \sum_{\nu} \log Z_{\text{Hop}} \left[ \tilde{\beta}, \{\xi^1\}, \{\xi^{2,\nu}\} \right]
\]  

(H.2)

Making the sum over \{\sigma\}, we obtain

\[
\langle N^n \rangle = \sum_{\{\xi^1\}} \sum_{\{\xi^2\}} \sum_{\{\xi^{2,\nu}\}} \int \left( \prod_{l} \frac{\text{d}m_l^1}{\sqrt{2\pi}} \right) \left( \prod_{l,\nu} \frac{\text{d}m_l^{2,\nu}}{\sqrt{2\pi}} \right) \left( \prod_{l} \frac{\text{d}\tilde{m}_l}{\sqrt{2\pi}} \right) e^{N E_3}
\]  

(H.3)
where

\[ E_3 = \frac{L}{2N} \log[(\beta n + \tilde{\beta})N] + \frac{L_n}{2N} \log(\beta N) + \frac{L}{2N} \log(\tilde{\beta}N) - 2 \log 2 \]

\[ + \frac{1}{N} \sum_i \sum_l \log \cosh \left[ (\beta n + \tilde{\beta}) \xi_l^1 m_l^1 + \beta \sum_{\nu} \xi_l^{2,\nu} m_l^{2,\nu} + \tilde{\beta} \xi_l^2 \tilde{m}_l \right] - \frac{\beta n + \tilde{\beta}}{2} \sum_l (m_l^1)^2 \]

\[ - \frac{\beta}{2} \sum_{l,\nu} (m_{l,\nu}^1)^2 - \frac{\tilde{\beta}}{2} \sum_l \tilde{m}_l^2 - \frac{L}{N} \log Z_{\text{Hop}} \left[ \tilde{\beta}, \{\xi^1\}, \{\tilde{\xi}^2\} \right] \]

\[ - \frac{\beta}{\beta N} \sum_{\nu} \log Z_{\text{Hop}} \left[ \tilde{\beta}, \{\xi^1\}, \{\xi^{2,\nu}\} \right]. \] (H.4)

Using the following change of variables,

\[
\begin{cases}
    m_l^1 &\to m^* + \delta m_l/\sqrt{N} \\
    \tilde{m}_l &\to \tilde{m}_l/\sqrt{N} \\
    m_{l,\nu}^{2,\nu} &\to m_{l,\nu}^{2,\nu}/\sqrt{N}
\end{cases}
\]

we have

\[ \langle N^\nu \rangle = \sum_{\{\xi^1\}} \sum_{\{\tilde{\xi}^2\}} \sum_{\{\xi^{2,\nu}\}} \int \left( \prod_l \frac{d\delta m_l}{\sqrt{2\pi}} \right) \left( \prod_{l,\nu} \frac{dm_{l,\nu}^{2,\nu}}{\sqrt{2\pi}} \right) \left( \prod_l \frac{d\tilde{m}_l}{\sqrt{2\pi}} \right) e^{NE_4}, \] (H.5)

\[ E_4 = C_1 + \frac{1}{N} \sum_i \sum_l \log \cosh \left[ (\beta n + \tilde{\beta}) \xi_l^1 m_l^* + \frac{\beta n + \tilde{\beta}}{\sqrt{N}} \xi_l^1 \delta m_l \right] \]

\[ + \frac{\beta}{\sqrt{N}} \sum_{\nu} \xi_l^{2,\nu} m_l^{2,\nu} + \frac{\tilde{\beta}}{\sqrt{N}} \xi_l^2 \tilde{m}_l \]

\[-L \log \cosh \left[ (\beta n + \tilde{\beta}) m_l^* \right] - \frac{\beta n + \tilde{\beta}}{2} \frac{1}{N} \sum_l (\delta m_l)^2 - \frac{(\beta n + \tilde{\beta}) m_l^*}{\sqrt{N}} \sum_l \delta m_l \]

\[-\frac{\beta}{2} \sum_{l,\nu} (m_{l,\nu}^{2,\nu})^2 - \frac{\tilde{\beta}}{2} \sum_l \tilde{m}_l^2 - \frac{L}{2N} \frac{\tilde{\beta} m_l^*}{1 - \beta (1 - m^2)} \frac{1}{\sqrt{N}} \sum_i \xi_l^1 \xi_i^2 \]

\[-\frac{L}{2N} \frac{\beta m_l^*}{1 - \beta (1 - m^2)} \sum_{\nu} \left[ \frac{1}{\sqrt{N}} \sum_i \xi_i^1 \xi_i^{2,\nu} \right]^2, \] (H.6)

where

\[ C_1 = \frac{L}{2N} \log \left[ (\beta n + \tilde{\beta})N \right] + \frac{L_n}{2N} \log(\beta N) + \frac{L}{2N} \log(\tilde{\beta}N) - 2 \log 2 + L(\beta n + \tilde{\beta}) m^2 \]

\[-L \left( 1 + \frac{\beta n}{\tilde{\beta}} \right) \log \cosh(\beta m^*) + \frac{L}{N} \left( 1 + \frac{\beta n}{\tilde{\beta}} \right) \log \left[ 1 - \beta (1 - m^2) \right] \]

\[ + L \log \cosh \left[ (\beta n + \tilde{\beta}) m^* \right]. \] (H.7)
Posing $\tilde{m}^* = \tanh \left[ (\beta n + \tilde{\beta}) m^* \right]$ and expanding the first term for large $N$, we get

$$E_4 = C_1 - \frac{\beta n - \tilde{\beta}}{2} \left[ 1 - (1 - \tilde{m}^*)^2 \right] \frac{1}{N} \sum_l (\delta m_l)^2$$

$$- \frac{\beta}{2} \left[ 1 - \beta (1 - \tilde{m}^*)^2 \right] \frac{1}{N} \sum l \sum \nu (m_l^2)^2$$

$$- \frac{\tilde{\beta}}{2} \left[ 1 - \tilde{\beta} (1 - \tilde{m}^*)^2 \right] \frac{1}{N} \sum l \sum \nu (\tilde{m}^* - m^*) \sum \delta m_l$$

$$+ \tilde{m}^* \frac{1}{N} \sum l \sum \nu (m_l^2) \frac{1}{\sqrt{N}} \sum \xi_i \xi_{1,i}^2 + \tilde{m}^* \frac{1}{N} \sum l \sum \nu (\tilde{m}^* - m^*) \sum \delta m_l$$

$$+ (1 - \tilde{m}^*) \frac{2}{2N} \sum i,l \sum \nu \neq \sigma (m_l^2 \delta m_l \xi_i \xi_{1,i}^2)$$

$$+ (1 - \tilde{m}^*) \tilde{\beta} \frac{1}{N} \sum i,l \sum \nu \bar{m}_l \xi_i \xi_{1,i}^2$$

$$+ \beta (\beta n + \tilde{\beta}) (1 - \tilde{m}^*) \frac{1}{N^2} \sum i,l \sum \nu \delta m_l \xi_i \xi_{1,i}^2$$

$$+ \left( 1 - \tilde{m}^* \right) \beta (\beta n + \tilde{\beta}) \frac{1}{N^2} \sum i,l \sum \nu \delta m_l \bar{m}_l \xi_i \xi_{1,i}^2$$

$$- \frac{L}{2N} \frac{\tilde{\beta} m^*}{1 - \beta (1 - m^*)^2} \left[ \frac{1}{\sqrt{N}} \sum \xi_i \xi_{1,i}^2 \right]^2$$

$$- \frac{L}{2N} \frac{\beta m^*}{1 - \beta (1 - m^*)^2} \sum \nu \left[ \frac{1}{\sqrt{N}} \sum \xi_i \xi_{1,i}^2 \right]^2.$$  \hspace{1cm} (H.8)

One may note that this expression is linear on $l$, so it can be rewritten as

$$\langle N^n \rangle = \sum_{\{e_1\}} \sum_{\{\xi_1\}} \sum_{\{\xi_{2,i}\}} \left[ \int \frac{d\delta m_l}{\sqrt{2\pi}} \left( \prod_{\nu} \frac{dm_{l,\nu}^2}{\sqrt{2\pi}} \right) \frac{d\tilde{m}_l}{\sqrt{2\pi}} e^{E_h} \right]^L.$$  \hspace{1cm} (H.9)

We define

$$u = \frac{1}{\sqrt{N}} \sum \xi_i \xi_{1,i}^2 \hspace{1cm} t_\nu = \frac{1}{N} \sum \xi_i \xi_{2,\nu}^2 \hspace{1cm} s_\mu = \frac{1}{\sqrt{N}} \sum \xi_i \xi_{2,\mu}^2 \hspace{1cm} q_{\mu,\nu} = \frac{1}{N} \sum \xi_i \xi_{2,\nu} \xi_{2,\mu}^2$$

and we do the gaussian integral in (H.9):

$$\langle N^n \rangle = \sum_{\{e_1\}} \sum_{\{\xi_1\}} \sum_{\{\xi_{2,i}\}} \exp \left[ C_1 - \frac{L}{2} \frac{\tilde{\beta} m^* u^2}{1 - \beta (1 - m^*)^2} - \frac{L}{2} \frac{\beta m^*}{1 - \beta (1 - m^*)^2} \sum \nu \right.$$  

$$- \frac{L}{2} \log \det M + \frac{L}{2} A^t M^{-1} A \right],$$  \hspace{1cm} (H.10)
where

\[
M = \begin{pmatrix}
  (d_1 \tilde{u} \tilde{s}_1 \tilde{s}_2 \ldots \tilde{s}_n) \\
  (\tilde{u} d_2 \tilde{t}_1 \tilde{t}_2 \ldots \tilde{t}_n) \\
  (\tilde{s}_1 \tilde{t}_1 d_3 \tilde{q}_{1,2} \tilde{q}_{1,3} \ldots \tilde{q}_{1,n}) \\
  (\tilde{s}_2 \tilde{t}_2 d_3 \tilde{q}_{2,3} \ldots \tilde{q}_{2,n}) \\
  \vdots \\
  \vdots \\
  (\tilde{s}_n \tilde{t}_n \tilde{q}_{1,n} \ldots \ldots \tilde{q}_{n-1,n} d_3)
\end{pmatrix}, \quad (H.11)
\]

\[
A = (\sqrt{N}(\tilde{m}^* - m^*)(\bar{\beta}n + \bar{\beta}) \tilde{m}^*\tilde{\beta}u \tilde{m}^*\beta s_1 \tilde{m}^*\beta s_2 \ldots \tilde{m}^*\beta s_n), \quad (H.12)
\]

and

\[
d_1 = (\bar{\beta}n + \bar{\beta}) \left[ 1 - (\bar{\beta}n + \bar{\beta})(1 - \tilde{m}^*)^2 \right], \quad (H.13)
\]
\[
d_2 = \bar{\beta} \left[ 1 - \tilde{\beta}(1 - \tilde{m}^*)^2 \right], \quad (H.14)
\]
\[
d_3 = \beta \left[ 1 - \beta(1 - \tilde{m}^*)^2 \right], \quad (H.15)
\]
\[
\tilde{u}_\nu = -(1 - \tilde{m}^*) \tilde{\beta}(\beta n + \tilde{\beta})u_\nu, \quad (H.16)
\]
\[
\tilde{t}_\nu = -(1 - \tilde{m}^*) \beta \tilde{\beta}t_\nu, \quad (H.17)
\]
\[
\tilde{s}_\nu = -(1 - \tilde{m}^*) \beta(\beta n + \tilde{\beta})s_\nu, \quad (H.18)
\]
\[
\tilde{q}_{\nu,\sigma} = -(1 - \tilde{m}^*) \beta^2 q_{\nu,\sigma}. \quad (H.19)
\]

We can now add the Lagrange multipliers

\[
\langle N^n \rangle = \sum_{\{\xi^1\}} \sum_{\{\xi^2\}} \sum_{\{\xi^{2,\nu}\}} \int \prod_{\rho<\sigma} dq_{\rho,\sigma} \prod_{\rho<\sigma} d\tilde{q}_{\rho,\sigma} \prod_{\rho} ds_{\rho} \prod_{\rho} d\tilde{s}_{\rho} \prod_{\rho} dt_{\rho} \prod_{\rho} d\tilde{t}_{\rho} du d\tilde{u} e^{N(H.20)}
\]

\[
F = \frac{C_1}{N} - \frac{\alpha}{2} \tilde{\beta}\tilde{m}^* u^2 - \frac{\alpha}{2} \frac{\beta m^2}{1 - \tilde{\beta}(1 - \tilde{m}^*)} \sum_\nu s_\nu^2 - \frac{\alpha}{2} \log \det M + \frac{\alpha}{2} A^T M^{-1} A
\]

\[
- \frac{1}{2} \sum_{\rho,\sigma} q_{\rho,\sigma} \tilde{q}_{\rho,\sigma} - \frac{1}{2\sqrt{N}} \sum_\rho \left( s_\rho \tilde{s}_\rho - \frac{1}{2} \sum_\rho t_\rho \tilde{t}_\rho - \frac{1}{2\sqrt{N}} \tilde{u} \tilde{u} + \frac{1}{2\sqrt{N}} \tilde{q}_{\rho,\sigma} \xi_i^{2,\rho} \xi_i^{2,\sigma} \right)
\]

\[
+ \frac{1}{2\sqrt{N}} \sum_{i,\rho} \tilde{s}_\rho \xi_i^{1,\rho} + \frac{1}{2\sqrt{N}} \sum_{i,\rho} \tilde{t}_\rho \xi_i^{2,\rho} + \frac{1}{2\sqrt{N}} \sum_i \tilde{u} \xi_i^{1,2} \quad (H.21)
\]

and we have finally the expression presented in chapter 7.
Appendix I

Details of the evaluation of $\langle \tilde{N} \rangle$ for the Hopfield model with large $h$

We start with

$$S = - \sum_{\{\xi^2\}} P[\{\xi^2\}, \{\xi^1\} | \{\sigma^l\}] \log P[\{\xi^2\}, \{\xi^1\} | \{\sigma^l\}], \quad (I.1)$$

and average this entropy in respect to both the first pattern and the measured configurations. The probability is given by

$$P[\{\xi^2\}, \{\xi^1\} | \{\sigma^l\}] = \frac{P[[\{\sigma^l\}]|\{\xi^1\}, \{\xi^2\}] P[[\{\xi^1\}, \{\xi^2\}]}{N[\{\sigma^l\}]} \quad (I.2)$$

$$P[[\{\sigma^l\}]|\{\xi^1\}, \{\xi^2\}] = \frac{1}{Z_{\text{Hop}}[\beta, \{\xi^1\}, \{\xi^2\}]} \exp \left[ \frac{\beta}{N} \sum_{\mu=1,2} \sum_{l=1}^{L} \sum_{i<j} \sigma^l_i \sigma^l_j \xi^\mu_i \xi^\mu_j \right.$$}

$$+ \beta \sum_{i} \sum_{l=1}^{L} h_i \sigma^l_i \quad (I.3)$$

The normalization $N$ is given by

$$N[\{\sigma^l\}] = \sum_{\{\xi^1\}} \sum_{\{\xi^2\}} \frac{P[[\{\xi^1\}, \{\xi^2\}]}{Z_{\text{Hop}}[\beta, \{\xi^1\}, \{\xi^2\}]} \exp \left[ \frac{\beta}{N} \sum_{\mu=1,2} \sum_{l=1}^{L} \sum_{i<j} \sigma^l_i \sigma^l_j \xi^\mu_i \xi^\mu_j \right.$$}

$$+ \beta \sum_{i} \sum_{l=1}^{L} h_i \sigma^l_i \quad (I.4)$$

As done in Section 7.1, we write our entropy as a derivative of a modified normal-
APPENDIX I. DETAILS OF THE EVALUATION OF \( \langle \tilde{N} \rangle \) FOR THE HOPFIELD MODEL WITH LARGE \( h \)

\[
\tilde{N}[\sigma^l] = \sum_{\{\xi^1\}} \sum_{\{\xi^2\}} \exp \left[ \frac{\beta}{N} \sum_{\mu=1,2} \sum_{l=1}^{L} \sum_{i<j} \sigma^l_i \xi^l_{ij} + \beta \sum_{i=1}^{L} h_i \sigma^l_i ight. \\
\left. - \frac{\beta}{\beta} L \log Z_{\text{Hop}}[\tilde{\beta}, \{\xi^1\}, \{\xi^2\}, \{\sigma^l\}] \right],
\] (I.5)

\[
S = \log \tilde{N} \bigg|_{\beta = \tilde{\beta}} - \frac{\partial \log \tilde{N}}{\partial \beta} \bigg|_{\beta = \tilde{\beta}},
\] (I.6)

where we have supposed \( P[\{\xi^1\}, \{\xi^2\}] = 2^{-2N} \).

**I.1 Determination of log \( Z_{\text{Hop}} \)**

To write an explicit expression for \( \tilde{N} \), we have to evaluate \( Z_{\text{Hop}} \):

\[
Z_{\text{Hop}} = \int \frac{dm_1}{\sqrt{2\pi}} \frac{dm_2}{\sqrt{2\pi}} \exp \left\{ -\frac{\beta}{2} m_1^2 - \frac{\beta}{2} m_2^2 
+ \sum_i \log \left[ 2 \cosh \left( \beta h_i + \frac{\beta}{\sqrt{N}} m_1 \xi^1_i + \frac{\beta}{\sqrt{N}} m_2 \xi^2_i \right) \right] \right\}
\]

\[
= \int \frac{dm_1}{\sqrt{2\pi}} \frac{dm_2}{\sqrt{2\pi}} \exp \left\{ -\frac{\beta}{2} m_1^2 - \frac{\beta}{2} m_2^2 + \sum_i \log \left[ 2 \cosh(\beta h_i) \right] 
+ \sum_i \left[ \frac{\beta}{\sqrt{N}} m_1 \xi^1_i + \frac{\beta}{\sqrt{N}} m_2 \xi^2_i \right] \tanh h_i 
+ \frac{1}{2} \sum_i \left[ \frac{\beta}{\sqrt{N}} m_1 \xi^1_i + \frac{\beta}{\sqrt{N}} m_2 \xi^2_i \right]^2 (1 - \tanh^2 h_i) + O(1/\sqrt{N}) \right\}
\]

\[
= \int \frac{dm_1}{\sqrt{2\pi}} \frac{dm_2}{\sqrt{2\pi}} \exp \left\{ -\frac{\beta \chi}{2} m_1^2 - \frac{\beta \chi}{2} m_2^2 + \beta m_1 q_1 + \beta m_2 q_2 
+ \sum_i \log \left[ 2 \cosh(\beta h_i) \right] + O(1/\sqrt{N}) \right\},
\] (I.7)

where

\[
q_\mu = \frac{1}{\sqrt{N}} \sum_i \xi^\mu_i \tanh(\beta h_i),
\] (I.8)

\[
\chi = 1 - \frac{\beta}{N} \sum_i [1 - \tanh^2(\beta h_i)].
\] (I.9)

Finally

\[
\log Z_{\text{Hop}} = \sum_i \log \left[ 2 \cosh(\beta h_i) \right] - \log(\beta \chi) + \frac{\beta}{2 \chi} (q_1^2 + q_2^2) + O(1/\sqrt{N}).
\] (I.10)
APPENDIX I. DETAILS OF THE EVALUATION OF $\langle \hat{N} \rangle$ FOR THE HOPFIELD MODEL WITH LARGE $h$

I.2 Determination of $\langle \log \hat{N} \rangle$

To determine $\langle \log \hat{N} \rangle$, we use again the replica trick,

$$
\langle \hat{N}^n \rangle = \frac{1}{2^N} \sum_{\{\xi^1\}} \sum_{\{\xi^2\}} \sum_{\{\sigma^1\}} \sum_{\{\sigma^2\}} \sum \exp \left\{ (\beta n + \tilde{\beta}) \sum_i \sum_{l=1}^L h_i \sigma^l_i \right. \\
+ \frac{\beta}{2N} \sum_{i,j} \sum_{l=1}^L \sum^L \sigma^l_i \sigma^l_j (\xi^1_i \xi^1_j + \xi^2_i \xi^2_j) - \frac{\beta}{\tilde{\beta}} L \sum_{\nu=1}^n \log Z_{\text{Hop}} \left[ \tilde{\beta}, \{\xi^1\}, \{\xi^2\} \right] \\
+ \tilde{\beta} \sum_{i,j} \sum^L \sigma^l_i \sigma^l_j (\tilde{\xi}^1_i \tilde{\xi}^1_j + \tilde{\xi}^2_i \tilde{\xi}^2_j) - L \log Z_{\text{Hop}} \left[ \tilde{\beta}, \{\tilde{\xi}^1\}, \{\tilde{\xi}^2\} \right] \right\} \\
(I.11)
$$

After doing an integral transform, we obtain

$$
\langle \hat{N}^n \rangle = \sum_{\{\xi^1\}} \sum_{\{\xi^2\}} \sum_{\sigma^1} \sum_{\sigma^2} \int \left( \prod_{l,\nu} \frac{\text{d}m^1_{l,\nu}}{\sqrt{2\pi} \beta} \right) \left( \prod_{l,\nu} \frac{\text{d}m^2_{l,\nu}}{\sqrt{2\pi} \beta} \right) \left( \prod_l \frac{\text{d}m^1_l}{\sqrt{2\pi} \beta} \right) e^{NE_1},
$$

(I.12)

where

$$
E_1 = \frac{\beta}{\sqrt{N}} \sum_i \sum_{l,\nu} \sigma^l_i \xi^1_{i,\nu} m^1_{l,\nu} + \frac{\beta}{\sqrt{N}} \sum_i \sum_{l,\nu} \sigma^l_i \xi^2_{i,\nu} m^2_{l,\nu} \\
+ \frac{\beta}{\sqrt{N}} \sum_i \sum_{l,\nu} \sigma^l_i \tilde{\xi}^1_l \tilde{m}^1_l + \frac{\tilde{\beta}}{\sqrt{N}} \sum_i \sum_{l,\nu} \sigma^l_i \tilde{\xi}^2_l \tilde{m}^2_l \\
- \frac{\beta}{2} \sum_{l,\nu} (m^1_{l,\nu})^2 - \frac{\beta}{2} \sum_{l,\nu} (m^2_{l,\nu})^2 - \frac{\beta}{2} \sum_l (\tilde{m}^1_l)^2 - \frac{\beta}{2} \sum_l (\tilde{m}^2_l)^2 \\
- \frac{L}{N} \log Z_{\text{Hop}} \left[ \tilde{\beta}, \{\xi^1\}, \{\xi^2\} \right] - \frac{\beta}{\tilde{\beta} N} \sum_{\nu} \log Z_{\text{Hop}} \left[ \tilde{\beta}, \{\xi^1\}, \{\xi^2\} \right] \\
+(\beta n + \tilde{\beta}) \sum_i \sum_{l=1}^L h_i \sigma^l_i
$$

(I.13)
Summing over the spin variables $\sigma$ yields

\[
\tilde{N} = \sum_{\{\xi^1\}} \sum_{\{\xi^2\}} \left[ \int \left( \prod_{\nu} \frac{dm_{1,\nu}}{\sqrt{2\pi}} \right) \left( \prod_{\nu} \frac{dm_{2,\nu}}{\sqrt{2\pi}} \right) \left( \frac{d\tilde{m}_1 d\tilde{m}_2}{2\pi} \right) e^{E_3} \right]^L
\]

\[
E_3 = \frac{n}{N} \log(\beta N) + \frac{1}{N} \log(\tilde{\beta} N) - \frac{\beta}{2} \sum_{\nu} (m_{1,\nu})^2 - \frac{\beta}{2} \sum_{\nu} (m_{2,\nu})^2 - \frac{\tilde{\beta}}{2} (\tilde{m}_1)^2 - \frac{\tilde{\beta}}{2} (\tilde{m}_2)^2
\]

\[
- \frac{1}{N} \log Z_{\text{Hop}} \left[ \tilde{\beta}, \{\xi^1\}, \{\xi^2\} \right] - \frac{\tilde{\beta}}{N} \sum_{\nu} \log Z_{\text{Hop}} [\tilde{\beta}, \{\xi^{1,\nu}\}, \{\xi^{2,\nu}\}]
\]

\[
+ \sum_{i} \log 2 \cosh [(\beta n + \tilde{\beta})h_i] + \frac{\tilde{\beta}}{\sqrt{N}} \sum_{i} \xi^{1,\nu} m_{1,\nu} + \frac{\tilde{\beta}}{\sqrt{N}} \sum_{i} \xi^{2,\nu} m_{2,\nu} + \frac{\tilde{\beta}}{\sqrt{N}} \xi^{1,\nu} \tilde{m}_1 + \frac{\tilde{\beta}}{\sqrt{N}} \xi^{2,\nu} \tilde{m}_2
\]

Doing a Taylor expansion and using the result for $\log Z_{\text{Hop}}$ we have

\[
E_3 = \frac{n}{N} \log(\beta N) + \frac{1}{N} \log(\tilde{\beta} N) - \frac{\beta}{2} \sum_{\nu} m_{1,\nu}^2 - \frac{\beta}{2} \sum_{\nu} m_{2,\nu}^2 - \frac{\tilde{\beta}}{2} \tilde{m}_1^2 - \frac{\tilde{\beta}}{2} \tilde{m}_2^2
\]

\[
- \frac{\beta n + \tilde{\beta}}{\beta} \sum_{i} \log \left[ 2 \cosh(\tilde{\beta} h_i) \right] + \frac{\beta n + \tilde{\beta}}{\beta} \log(\tilde{\beta} \tilde{X}) + \frac{\tilde{\beta}}{2} (\tilde{q}_1^2 + \tilde{q}_2^2) + \frac{\tilde{\beta}}{2} \sum_{\nu} (q_{1,\nu}^2 + q_{2,\nu}^2)
\]

\[
+ \sum_{i} \log \left[ 2 \cosh((\beta n + \tilde{\beta})h_i) \right] + \frac{\tilde{\beta}}{\sqrt{N}} \sum_{\nu} \tilde{m}_\mu \sum_{i} [1 - \tanh^2((\beta n + \tilde{\beta})h_i)]
\]

\[
+ \frac{\tilde{\beta}^2}{2N} \sum_{\mu=1,2} \sum_{\nu} m_{1,\mu} m_{2,\nu} \sum_{i} \xi_{i}^{1,\nu} \xi_{i}^{2,\rho} [1 - \tanh^2((\beta n + \tilde{\beta})h_i)]
\]

\[
+ \frac{\tilde{\beta}^2}{N} \sum_{\nu,\rho} m_{1,\nu} m_{2,\rho} \sum_{i} \xi_{i}^{1,\nu} \xi_{i}^{2,\rho} [1 - \tanh^2((\beta n + \tilde{\beta})h_i)]
\]

\[
+ \frac{\tilde{\beta}^2}{N} \sum_{\mu=1,2} \sum_{\nu} m_{\mu,\nu} m_{\mu,\rho} \sum_{i} \xi_{i}^{1,\nu} \xi_{i}^{2,\rho} [1 - \tanh^2((\beta n + \tilde{\beta})h_i)]
\]

\[
+ \frac{\tilde{\beta}^2}{N} \sum_{\mu=1,2} \sum_{\nu} m_{\mu,\nu} \tilde{m}_\mu \sum_{i} \xi_{i}^{1,\nu} \xi_{i}^{2,\rho} [1 - \tanh^2((\beta n + \tilde{\beta})h_i)]
\]

Several of these terms can be ignored: first of all, $\frac{1}{N} \sum_{i} \xi_{i}^{1,\nu} \xi_{i}^{2,\rho} [1 - \tanh^2((\beta n + \tilde{\beta})h_i)]$ can be considered of order $O(1/\sqrt{N})$, since we suppose that the patterns are orthogonal in the leading order. The same thing can be said to the inferred patterns, so $\frac{1}{N} \sum_{i} \xi_{i}^{1,\nu} \xi_{i}^{2,\rho} [1 - \tanh^2((\beta n + \tilde{\beta})h_i)] = O(1/\sqrt{N})$. Finally, since we can permute
\(\xi^1 \leftrightarrow \xi^2\), we will only lose one unity of entropy if we suppose that \(\xi^1\) is an approximation to \(\tilde{\xi}^1\) and not \(\tilde{\xi}^2\). We can consider thus 
\[
\frac{1}{N} \sum_i \xi_i^{\mu,\nu} \tilde{\xi}_i^{\mu'} \left[1 - \tanh^2((\beta n + \tilde{\beta}) h_i)\right] = O(1/\sqrt{N}) \text{ for } \mu \neq \mu'.
\]

After neglecting these terms, we can see that the two different patterns are completely decorrelated in \(\tilde{N}\), with no extra term accounting for an effective influence of one pattern over the other. We can hence conclude that the results taken for the Mattis model can be applied for this system.
APPENDIX I. DETAILS OF THE EVALUATION OF $\langle \hat{N} \rangle$ FOR THE HOPFIELD MODEL WITH LARGE $h$

I.2. DETERMINATION OF $\langle \log \hat{N} \rangle$
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