Guided Modes of Elliptical Metamaterial Waveguides

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The propagation of guided electromagnetic waves in open elliptical metamaterial waveguide structures is investigated. The waveguide contains a negative-index media core, where the permittivity, \( \varepsilon \), and permeability, \( \mu \), are negative over a given bandwidth. The allowed mode spectrum for these structures is numerically calculated by solving a dispersion relation that is expressed in terms of Mathieu functions. By probing certain regions of parameter space, we find the possibility exists to have extremely localized waves that transmit along the surface of the waveguide.

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Waveguides are structures that are typically designed to transmit energy along a specified trajectory with minimal attenuation and signal distortion. When transmitting surface waves, this implies confining the traveling wave within or adjacent to the waveguide walls [1]. Various avenues can be pursued when attempting to improve on a waveguides’ capabilities, including modifying the constitutive effective material parameters of the guide. The recent surge of interest in negative index of refraction materials [2], or negative index media (NIM), has prompted a reanalysis of many conventional results for waveguide devices, and a subsequent search for exotic transmission characteristics when incorporating this particular composite media, or metamaterial, into a variety of waveguide configurations.

A crucial feature of NIM, is the frequency dispersion of the permittivity, \( \varepsilon \), and permeability, \( \mu \), with \( \varepsilon \) and \( \mu \) simultaneously rendered negative over a particular bandwidth. This results in wave propagation in which the phase velocity and energy flow of an electromagnetic wave can be antiparallel, and also the possibility of a negative index of refraction, proposed long ago [3]. The study of various NIM based open waveguide structures and resonators during the past few years has demonstrated a number of interesting effects: it was shown [4] that a quasi 1-D bilayer resonator containing a NIM layer can be substantially smaller than the usual cavity size due to phase cancellation. For the case of a thin planar NIM waveguide, the TM mode can propagate for arbitrary widths and possesses a single mode for slow waves [4]. Guided TE modes were also shown to have electric field profiles containing nodes [5], and exhibit a sign-varying Poynting vector [5, 6]. Similar results were reported in circular NIM fibers [7].

Distortion of the circular dielectric waveguide into an elliptical guide, while maintaining the cross sectional area, has been shown to reduce attenuation of the dominant mode [8] and modal degeneracy, allowing for practical guiding of traveling electromagnetic waves. Attenuation effects and power flow expressions were achieved for wave propagation in a surface wave transmission line with an elliptical cross section [13]. It was found that some modes in the guide have lower attenuation than the corresponding modes in a circular guide. The slow and fast hybrid mode spectrum in a metallic elliptical waveguide with a confocal dielectric lining was also calculated [14], demonstrating the potential for a surface wave transmission device. Moreover, the distribution of electromagnetic fields in a double layer elliptical waveguide was calculated to first order and revealed in some cases, dispersion solutions where the power and phase velocity directions are antiparallel [8]. Spurred by the recent theoretical and experimental advances in NIM waveguides and resonators, we examine in this paper, open NIM waveguides with elliptical cross sections, affording a greater flexibility in the parameter space determined by the geometry and material constraints. For a given eccentricity, \( \varepsilon \), we calculate the permitted propagation constants over a range of frequencies. The allowed modes are separated into fast and slow propagating regions of the dispersion diagram, where wave localization is demonstrated in the form of electric field distributions.

When searching for exact solutions to Maxwell’s equa-
tions, it is convenient to work in a coordinate system in which the boundary of the structure coincides with one of the coordinates being held constant. It is thus appropriate for the geometry under consideration to work in an orthogonal elliptical coordinate system described by the coordinates $\xi$ and $\eta$, depicted in Fig. 1. Elliptical coordinates are related to their rectangular counterparts via $x = p \cosh \xi \cos \eta$ and $y = p \sinh \xi \sin \eta$, for $0 \leq \xi < \infty$ and $0 \leq \eta \leq 2\pi$, where $p = (a^2 - b^2)^{1/2}$ is the semiaxial length of the ellipse expressed in terms of the semimajor and semiminor axes $a$ and $b$ respectively. The waveguide boundary is located at $\xi = \xi_0$, and hence $a = p \cosh \xi_0$ and $b = p \sinh \xi_0$. It then follows that the eccentricity, $e$, is written $e = [1 - (b/a)^2]^{1/2} = 1/cosh \xi_0$, such that $0 \leq e < 1$, with $e = 0$ corresponding to a circular cross section. In order to obtain the electric ($E$) and magnetic ($H$) fields, we must solve the vector Helmholtz wave equation obtained from Maxwell’s equations. This yields three coupled second order differential equations for either $E$ or $H$. The waveguide along the axial (z) direction is translationally invariant and thus the form of the equation governing the longitudinal $E_z$ (or $H_z$) is identical to the scalar Helmholtz equation in elliptic coordinates, permitting a semi-analytic and more tractable solution. The fields are assumed to vary harmonically in time and propagation occurs in the positive z direction. The wave equation then reduces to the following form:

\[
\frac{1}{k^2} \left( \frac{\partial^2}{\partial \xi^2} + \frac{\partial^2}{\partial \eta^2} \right) E_{\xi i}(\xi, \eta) + k^2 E_{\eta i}(\xi, \eta) = 0, \quad (1)
\]

where the index $i$ denotes the region, $\sqrt{2k} = p \sqrt{\cosh(2\xi) - \cos(2\eta)}$, $k^2_\xi = \mu_i(\omega)\varepsilon_i(\omega)\omega^2/c^2 - k^2_\eta$, and for the unattenuated modes of interest here, $k_\eta$ is the real propagation constant along the z-direction. We have also suppressed the usual $\exp(ik_z z - i\omega t)$ factor. A similar equation exists for $H_z$. Due to the cylindrical symmetry, the transverse field components ($E_{\eta i}, E_{\xi i}$) and ($H_{\eta i}, H_{\xi i}$) can be determined \[10\] from $E_{\xi i}$ and $H_{\xi i}$:

\[
E_{\eta i}(\xi, \eta) = \frac{ik_z}{k_\xi} \left( \frac{\partial E_{\xi i}}{\partial \eta} - \mu_i \frac{k_0}{k_\xi} \frac{\partial H_{\xi i}}{\partial \xi} \right), \quad (2a)
\]

\[
E_{\xi i}(\xi, \eta) = \frac{ik_z}{k_\eta} \left( \frac{\partial E_{\eta i}}{\partial \xi} + \mu_i \frac{k_0}{k_\eta} \frac{\partial H_{\eta i}}{\partial \eta} \right), \quad (2b)
\]

\[
H_{\eta i}(\xi, \eta) = \frac{ik_z}{k_\eta} \left( \frac{\partial H_{\xi i}}{\partial \eta} + \epsilon_i \frac{k_0}{k_\eta} \frac{\partial E_{\xi i}}{\partial \xi} \right), \quad (2c)
\]

\[
H_{\xi i}(\xi, \eta) = -\frac{ik_z}{k_\xi} \left( \frac{\partial H_{\eta i}}{\partial \xi} - \epsilon_i \frac{k_0}{k_\xi} \frac{\partial E_{\eta i}}{\partial \eta} \right). \quad (2d)
\]

We proceed by inserting $E_{\xi i}(\xi, \eta) = U_i(\xi)V_i(\eta)$ into Eq. (1), splitting it into two ordinary differential equations with separation constant $\Lambda$:

\[
\frac{d^2 V_i(\eta)}{d\eta^2} + (\Lambda - 2q_i \cos \eta) V_i(\eta) = 0, \quad (3a)
\]

\[
\frac{d^2 U_i(\xi)}{d\xi^2} - (\Lambda - 2q_i \cosh 2\xi) U_i(\xi) = 0, \quad (3b)
\]

where $q_1 = (k_1 p/2)^2$, and $q_2 = -(k_2 p/2)^2$.

The angular Mathieu equation [Eq. (3a)] describes the angular variation of the field around the ellipse. Two linearly independent periodic solutions exist, akin to the trigonometric sin and cos functions: the even and odd angular Mathieu functions, denoted $ce_n(\eta;q_i)$ and $se_n(\eta;q_i)$, respectively. For the elliptical waveguide problem, the angular Mathieu functions must be periodic with period $2\pi$ and of integer order, otherwise the solution set is nonperiodic and can be unstable \[15\]. We can thus expand the angular Mathieu functions in a Fourier series, where the expansion coefficients can be found recursively by substituting the expansions back into Eq. (3a). The parameter $\Lambda$ found in Eqs. (3) can be solved using a method of continued fractions \[15\]. The orthogonality and normalization relations of the angular Mathieu functions are given by Eq. (3a). The angular Mathieu functions are also periodic in $\eta$ only for special characteristic values of $\Lambda$, denoted here as $a_n(q_i)$ for the even solutions and $b_n(q_i)$ for the odd ones.

The radial Mathieu equation \[3\], admits two general types of solutions: the radial Mathieu functions of the first and second kind. The solutions of the first kind are divided into even and odd functions denoted as, $Ce_n(\xi;q_i)$ and $Se_n(\xi;q_i)$ respectively. The calculation of the characteristics numbers and the Fourier coefficients are exactly the same as for the angular functions. In identifying a convenient series expansion to compute the radial Mathieu functions, a number of techniques are applicable \[11\]. We found, in agreement with past works, that the Bessel $J_n$ product series are the most stable basis of functions to use \[12\]. Not surprisingly, the $Ce_n$ and $Se_n$ functions coalesce into $J_n$, as the elliptical cross section degenerates to a circular one. The Mathieu functions of the second kind for $q_i > 0$ are denoted $Fe_{n}(\xi;q_i)$ (even), and $Ge_{n}(\xi;q_i)$ (odd), and are calculated similarly, except the series expansion involves products of both the Bessel $Y_n$ and $J_n$ functions. The functions $Fe_{n}$ and $Ge_{n}$ are analogous to the Bessel functions of the second kind, $Y_n$, in circular coordinates. When $q_i < 0$, $Fe_{n}$ and $Ge_{n}$ transform into $Fe_{n}(\xi;q_i)$ and $Ge_{n}(\xi;q_i)$ (analogous to the Bessel $K$ functions), and they are related \[12\], e.g., for even order, $2Fe_{2n}(\xi; -q_i) = (-1)^n [-Fe_{2n}(\xi + i\pi/2; q_i) + iCe_{2n}(\xi + i\pi/2; q_i)]$.

For a general cylindrical open guide with circular cross section, pure TE or TM modes exist only for symmetrical electromagnetic fields, i.e., independent of the azimuthal angle. For an open elliptical waveguide however, the reduction in symmetry forces the electromagnetic modes in a given region to be hybrid in that both the longitudinal fields, $E_{\xi i}$ and $H_{\xi i}$ exist simultaneously (i denotes the region). Based on the discussion above, it is clear that field solutions in an elliptical domain are split into even and odd components: $E_{\xi i} \rightarrow \{E_{\xi i}^e, E_{\xi i}^o\}$ and $H_{\xi i} \rightarrow \{H_{\xi i}^e, H_{\xi i}^o\}$. The procedure adopted here consists of writing $H_{\xi i}^e (H_{\xi i}^o)$ waves as products involving even (odd) Mathieu functions, and $E_{\xi i}^e (E_{\xi i}^o)$ waves in terms of odd (even) Mathieu functions \[3\]. The complete solution
is then expanded as products of angular and radial Mathieu functions of the requisite parity, and that obey the radiative condition. The boundary conditions constrain the types of Mathieu functions used in the expansions [12], as we require “stationary waves” in the transverse \( \eta \) and \( \xi \) direction. Within each region, we thus seek solutions of the form,

\[
E^0_{\pm l}(\xi, \eta, z) = \sum_{m=1}^{\infty} a_{ml} A_{ml}(\xi; q_l) \epsilon_m(\eta; q_l) e^{ik_{l}z}, \quad (4a)
\]

\[
H^0_{\pm l}(\xi, \eta, z) = \sum_{m=0}^{\infty} b_{ml} B_{ml}(\xi; q_l) \epsilon_m(\eta; q_l) e^{ik_{l}z}, \quad (4b)
\]

where \( a_{ml} \) and \( b_{ml} \) are constants, and the coefficients \( A_{ml}(\xi; q_l) \) and \( B_{ml}(\xi; q_l) \) contain the “radial” dependence to the fields, given below. Without loss of generality, the methodology used here will focus on waves of even parity, as the procedure for odd waves is similar.

Within the waveguide region (see Fig. 1), the solutions are the radial Mathieu functions of the first kind, \( A_{ml}(\xi; q_l) = S_{ml}(\xi; q_l) \), and \( B_{ml}(\xi; q_l) = C_{ml}(\xi; q_l) \). For the guided modes of interest here, the fields must decay from the surface at \( \xi = \xi_0 \), and therefore within the surrounding medium we have, \( A_{ml}(\xi; q_l) \equiv G_{ml}(\xi; -q_l) \) and \( B_{ml}(\xi; q_l) \equiv F_{ml}(\xi; -q_l) \). With this requirement on the fields, and for a given set of material and geometrical parameters, a restricted number of waveguide modes exist. To determine the allowed modes, the tangential \( \mathbf{E} \) and \( \mathbf{H} \) fields are matched at the boundary \( \xi = \xi_0 \) separating the two media. The \( \eta \)-dependence is integrated out by making use of the orthogonality properties of the angular Mathieu functions (see Appendix).

We then cast the boundary matched equations into a linear equation system containing in principle, an infinite hierarchy of Mathieu functions. The higher order Mathieu functions arise from the lack of one-to-one correspondence between the angular Mathieu functions in regions with differing material parameters: the arguments of the angular Mathieu functions depends on the parameter \( q_l \), which in turn depends on \( \varepsilon \) and \( \mu \) of the relative media. This is in contrast to a circular waveguide, where the angular dependence is a function of only integer multiples of the azimuthal coordinate, \( m\phi \).

In order to find the nontrivial solution, the problem of finding the allowed modes thus amounts to finding where the associated determinant of the linear equation system vanishes over a range of frequencies, propagation constants and ellipticities. The methodology we shall discuss is valid for hybrid HE_{11} or EH_{11} (the first letter represents the dominant field) modes [8], with small \( \varepsilon \), and frequencies corresponding to small \( |\varepsilon_1 - \varepsilon_2| \) (and small \( |\mu_1 - \mu_2| \)). Under these conditions, the expansions in Eqs. [4] can be limited to the first few terms. Taking for example, the two lowest order terms in the outer region, yields the following even mode dispersion relation,

\[
\left( \frac{\varepsilon_1}{q_1} S_{e1}(q_1) + \frac{\varepsilon_2}{q_2} G_{e1}(q_2) \right) \left( \frac{\mu_1}{q_1} C_{e1}(q_1) + \frac{\mu_2}{q_2} F_{e1}(q_2) \right) + \frac{k_0^2}{q_0^2} \frac{1}{\alpha_{11} \beta_{11}} \left[ \frac{1}{q_1 q_2} (\psi_{11} C_1 + \tau_{11} C_2) + \frac{1}{q_2} C_1 C_2 \right] + \frac{1}{q_1^2} \tau_{11} \psi_{11} = 0, \quad (5)
\]

where \( k_0 = \omega/c, C_1 = -\beta_{11} \gamma_{11} - \gamma_{13} \beta_{31} \), and \( C_2 = \alpha_{11} \gamma_{11} + \alpha_{31} \gamma_{31} \). The quantities \( \alpha_{mn}, \beta_{mn}, \tau_{mn}, \psi_{mn}, \) and \( \gamma_{mn} \), outlined in the Appendix, arise from the integrals of products of overlapping angular Mathieu functions. Writing the dispersion relation explicitly in this way reduces computational time considerably by avoiding unsuitable numerical determinants of large matrices and the associated multiple function calls to higher order Mathieu functions. The odd mode spectrum is easily obtained via the interchange \( \varepsilon_1 \leftrightarrow -\varepsilon_1 \). As the elliptical cross section degenerates into a circular one, \( C_1 \rightarrow 1, C_2 \rightarrow -1 \), and the Mathieu functions appropriately transform into their corresponding cylindrical Bessel functions: \{ \( C_{e1}(q_1)/C_{e1}(q_1), S_{e1}(q_1)/S_{e1}(q_1) \) \} \rightarrow u_{J_1}(u)/J_1(u), and \{ \( F_{e1}(q_2)/F_{e1}(q_2), G_{e1}(q_2)/G_{e1}(q_2) \) \} \rightarrow v_{K_1}(v)/K_1(v). In this limit, the dispersion relation [5] reduces to the familiar characteristic equation for a circular waveguide:

\[
\left( \varepsilon_1 \frac{J_1'(u)}{u J_1(u)} + \varepsilon_2 \frac{K_1'(v)}{v K_1(v)} \right) \left( \mu_1 \frac{J_1'(u)}{u J_1(u)} + \mu_2 \frac{K_1'(v)}{v K_1(v)} \right) - \left[ k_z \left( u^2 + v^2 \right)^{3/2} \right]^2 = 0, \quad (6)
\]

where \( u^2 = k_1^2 a^2 \) and \( v^2 = -k_2^2 a^2 \).

The surface wave dispersion relation [5] is a function of the parameters, \( k_z, \omega, \) and eccentricity, \( e \); only particular combinations of these quantities that satisfy Eq. [6] are allowed mode solutions. The hybrid waves that are explored here can possess even and odd components, and are denoted appropriately in subsequent figures. We present the propagation constant in terms of the convenient dimensionless ratio, \( k_z/k_0 \), and the frequency units are all in GHz. The waveguide cross section is assumed to not deviate greatly from that of a circular guide, reflected in moderate values of \( e \). The permittivity and permeability in the NIM regions, \( \varepsilon_1 \) and \( \mu_1 \), respectively, have the frequency dispersive form, \( \varepsilon_1 = 1 - \left( \omega_p/\omega \right)^2 \) and \( \mu_1 = 1 - \left( \omega_m/\omega \right)^2 \), where \( \omega_p \) and \( \omega_m \) are the effective electrical and magnetic plasma frequencies [6], respectively. Thus for \( \omega \leq \omega_p/\sqrt{2}, \) we have \( \varepsilon_1 \leq -1 \). The study here is concerned with frequency regions of parameter space where \( \mu_1 \) and \( \varepsilon_1 \) are simultaneously negative.

Determining the allowed modes typically involves holding the semimajor and semiminor axes of the waveguide (and hence \( e \)) fixed, and then scanning Eq. [5] over \( k_z \).
calibration characteristics of guided modes. In particular, the first three sets of dispersion curves that satisfy \( \sqrt{\varepsilon_2/\mu_2} \leq k_z/k_0 \leq \sqrt{\varepsilon_1/\mu_1} \) correspond to conventional surface waves. Within this parameter space region, the phase velocity of guided waves, \( v_p \), exceeds the phase velocity of waves in a homogeneous bulk medium, i.e., \( v_p > c/\sqrt{\varepsilon_1\mu_1} \). These fast wave solutions to Maxwell’s equations will decay in the air region, but not necessarily in the waveguide core. Indeed, as the structure increases in size, or as \( f \) decreases (increasing \( |\varepsilon_1| \)), the electric and magnetic fields inside the waveguide oscillate with shorter wavelengths. At cutoff, \( k_z \to 0 \) (thus \( q_2 \to 0 \)), and the ensuing decay length increases outside the guiding surface. This causes a significant portion of the energy flow to occur in the air region, where the fields can then become less sensitive to the relevant geometrical parameters, such as the ratio \( a/b \).

We see in Fig. 2, that for the case of a NIM core, there are also solutions that reside outside of the \( q_1 = 0 \) boundary. These slow wave solutions are noticeably absent when \( \varepsilon_1 \) and \( \mu_1 \) are strictly positive (see bottom panel). The presence of NIM sets up a non-oscillatory field profile that rapidly decays outside the guide, allowing for the possibility of guided modes that are more localized to the surface, akin to surface plasmon waves on metal surfaces studied long ago. Note that as \( k_z \) increases, \( q_2 \) typically increases, in which case the radial Mathieu functions decay sharply, confining the field more to the waveguide. The slow wave solutions seen in the inset of Fig. 2 have dispersion characteristics that depend strongly on frequency. Near cutoff, these modes demonstrate that the direction of the group velocity, \( d\omega/dk_z \), evaluated at a particular \( k_z \), can differ among the even and odd wave solutions. This is related to the (time-averaged) local energy-density flow along \( z \), \( S_{zi} = (1/2)R(E_{zi}\dot{H}_{zi}^* - E_{ni}\dot{H}_{ni}) \). An excited wave with the appropriate frequency, can reverse direction between layers, a hallmark of the peculiar wave propagation that can arise in NIM guiding structures. To address the relationship between net energy flow in the system and group velocity, we show in Fig. 3(a), the total power, \( P \) as a function of the calculated mode frequency, found by summing the power flow in the guided wave \( (P_1) \) and air \( (P_2) \) regions. The power through a given cross sectional area, \( A \), was calculated by integrating the \( z \) component of the Poynting vector over \( A \),

\[
P_i = \iint_A S_{zi}h^2 \, d\eta d\xi, \quad i = 1, 2,
\]

where \( h \) is the usual coordinate scale factor. The frequencies used in determining \( P \) are governed by the dispersion curve, shown in the inset of Fig. 3(a). The arrows label points where \( d\omega/dk_z \) is zero in the dispersion diagram, and correlate with zero net power flow in the system, i.e., \( P_1 = -P_2 \). In general, we see from the figure that the direction of net power flow coincides with the sign of \( d\omega/dk_z \). A sign change in this slope causes the dispersion curves to bend back in the \( k_z - \omega \) plane, related to the
The normalized effective mode area for slow waves near cutoff ($k_z/k_0 = 1.01$) is shown in Fig. 4 as a function of the eccentricity, $e$. The mode frequencies calculated from Eq. (6) are a weak function of $e$ over the range shown. We see that $A_{\text{eff}}$ in the air region tends to decrease as the guide becomes more circular, while within the guide, the effective area is nearly constant. Thus, as a circular guide is slightly distorted into an ellipse, the exhibited mode localization properties within the NIM structure remain rather robust.

To gain insight into the transmission properties of an elliptical NIM waveguide excited by a particular source, the spatial and angular features of the EM field components is essential. We therefore show in Fig. 5, the three components of the $E$ field near cutoff, and at a frequency corresponding to $\varepsilon_1 = -5.04$ and $\mu_1 = -3.63$. The cross sectional area, $\pi ab$, of the waveguide is held fixed with $e = 0.14$. The left panel, Fig. 5(a), illustrates the normalized $E$ field as a function of $\eta$, for 5 different values of the normalized coordinate, $\xi' \equiv \xi/\xi_0$. The right set of figures, Fig. 5(b), exhibits the normalized electric field as a function of $\xi'$ for 5 different $\eta$. Parenthetically, in comparing field distributions with a circular waveguide, one can scale the coordinates (e.g. for $\eta = \pi/2$): $\xi \rightarrow p \sinh \xi$. From panel (a), we see that the longitudinal $E_z$ and “radial” $E_\xi$ components have the expected behavior along the semimajor axis, since the $\eta$ dependence to those fields involve $se_m(\eta; q_i)$ and $ce'_m(\eta; q_i)$ terms, which vanish at $\eta = 0$. Likewise, $E_\eta$ is comprised of products involving $ce_m(\eta; q_i)$ and $se'_m(\eta; q_i)$ functions, and hence tends toward zero for positions along the semiminor axis ($\eta = \pi/2$). Turning to the $\xi$ dependence in panel (b), it is evident that within the waveguide region, for $\xi = 0$ (along the line $x' = p \cos \eta$), the $z$ and $\eta$ components to the field vanish, while, $E_\xi$ has its maximum there. It is apparent that on average, each of the components are similar in magnitude, with $E_\xi$ dominating slightly.
FIG. 5: The normalized electric field distributions for even wave modes near cutoff in an elliptical waveguide as a function of (a) angular coordinate, \( \eta \), and (b) normalized radial coordinate, \( \xi' \equiv \xi/\xi_0 \). The frequency is set at 3.25 GHz, and the ellipticity, \( e \), has the value \( e = 0.14 \), corresponding to \( \xi_0 = 2.65 \). The vertical dashed line at \( \xi' = 1 \) identifies the waveguide boundary.

over the others in some instances. Another distinguishing feature among the components is the shifting of the peak intensity of the field patterns: \( E_z \) reaches its peak value inside of the waveguide, \( E_\eta \) has its largest value just outside the core boundary, while \( E_\xi \) peaks out along the waveguide walls (\( \xi' = 1 \)), after which it undergoes a discontinuous transition. This behavior is consistent with the boundary condition \( \Delta E_\xi(\xi_0) = (1 - \epsilon_1/\epsilon_2)E_\xi(\xi_0) \).

To explore the possibility of field localization in the slow wave regime, Fig. 6 illustrates the localized slow wave solutions as a function of \( \eta \) and \( \xi \). The frequency chosen, 5.28 GHz, lies just outside the \( q_1 = 0 \) curve at \( k_z/k_0 \approx 1 \), and approximate frequency (in GHz),

\[
f \approx \frac{\omega_p\omega_m}{2\pi \sqrt{\omega_m^2 + \omega_p^2}} \left( 1 - \frac{(k_z/k_0)^2 - 1}{\omega_m^2\omega_p^2} \right)^{1/2} = 5.26.
\]

Examining the interior of the waveguide, Fig. 6(b) is consistent with Fig. 5(b) at \( \xi = 0 \), where only \( E_\xi \) survives before declining towards the interface. As \( \eta \to \pi/2 \), \( E_\xi \) becomes more weakly dependent upon the coordinate \( \xi \), while if \( \eta \to 0 \), \( E_\xi \) and \( E_z \) vanish and \( E_\eta \) approaches a constant value within the guide. The \( E \) field components transverse to the direction of energy flow, \( E_\eta \) and \( E_\xi \), clearly dominate here, and thus the behavior of these particular modes is quite relevant in the determination of waveguide transmission capabilities. It is further evident from Fig. 6(b) that the length scale of field decay in the air region is at times shorter, demonstrating that the possibility exists to tailor the guide or feed line in a way that transmits ultra-localized waves. The dominant transverse electric field profiles mapped onto a Cartesian coordinate system is shown in Fig. 7. The 2-D contour plots are consistent with the field patterns exhibited in Fig. 6.

In conclusion we have shown that elliptical waveguides with NIM can support both fast and slow wave modes. The power flow in the system was shown to have direct correlations with the group velocity: points on the dispersion curves where the group velocity is zero corresponded to zero net power flow through the entire structure. The Poynting vector was shown to reverse when crossing the boundary between air and NIM. The dispersion relation was shown to admit localized solutions that retain their characteristics under moderate variations of the eccentricity.
FIG. 7: Contour plots of the even transverse electric field amplitudes for $e = 0.59$ and $f = 5.3$ GHz. The top and bottom panels correspond to $E_\eta$ and $E_\xi$ respectively. Bright areas indicate larger field intensities. Each component is normalized to its respective maximum for clarity.

APPENDIX A: OVERLAP INTEGRALS OF ANGULAR MATHEIU FUNCTIONS

When matching the tangential fields at the boundary, the orthogonality properties of the angular Mathieu functions give rise to several overlap integrals, given as,

$$\alpha_{mn} = \frac{1}{\pi} \int_0^{2\pi} d\eta e^{-m\eta\eta} e^{-n\eta\eta},$$  \hspace{1cm} (A1a)  

$$\beta_{mn} = \frac{1}{\pi} \int_0^{2\pi} d\eta s\eta e^{-m\eta\eta} s\eta e^{-n\eta\eta},$$  \hspace{1cm} (A1b)  

$$\tau_{mn} = \frac{1}{\pi} \int_0^{2\pi} d\eta e^{-m\eta\eta} e^{-n\eta\eta},$$  \hspace{1cm} (A1c)  

$$\psi_{mn} = \frac{1}{\pi} \int_0^{2\pi} d\eta e^{-m\eta\eta} s\eta e^{-n\eta\eta},$$  \hspace{1cm} (A1d)  

$$\gamma_{mn} = \frac{1}{\pi} \int_0^{2\pi} d\eta e^{-m\eta\eta} s\eta e^{-n\eta\eta}.$$  \hspace{1cm} (A1e)  

When $q_1 = q_2$, $\beta_{mn} = \delta_{mn}$, and $\alpha_{mn} = \delta_{mn}$. In the limiting case of the ellipse reducing to a circle, then we also have $\tau_{mn} \to m\delta_{mn}$ and $\psi_{mn} \to -m\delta_{mn}$, and $\gamma_{mn} \to -m\delta_{mn}$. In all cases, the integrals are zero if the $m$ is even and $n$ is odd or vice versa, due to the symmetry properties of the products of periodic Mathieu functions.

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