ENTRY TIMES DISTRIBUTION FOR MIXING SYSTEMS

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Abstract. We consider the return times dynamics to Bowen balls for continuous maps on metric spaces which have invariant probability measures with certain mixing properties. These mixing properties are satisfied for instance by systems that allow Young tower constructions. We show that the higher order return times to Bowen balls are in the limit Poisson distributed. We also provide a general result for the asymptotic behavior of the recurrence time for Bowen balls for ergodic systems and those with specification.

1. Introduction

Recently there has been a great interest in the statistics of return times to small sets and their limiting distributions as the target sets shrink to a point and the observation time is scaled accordingly as suggested by Kac’s theorem. Lacroix and Kupsa [18, 19] have shown that the shrinking of the target sets has to done in a dynamical or geometric regular way as their examples show that otherwise any limiting distribution could be achieved. The first dynamical result is due to Doeblin [10] who showed that for the Gauss map higher order returns in the neighbourhood of the origin are Poissonian distributed in the limit. In mainstream dynamics, Pitskel was the first one consider the limiting distribution for Axiom A systems and showed in 1990 that for cylinders the return times are Poissonian in the limit and, by an approximation argument, also for metric balls for hyperbolic maps on two dimensional torii. In the successive years, a sequence of results then established that returns to cylinder sets in the limit become Poissonian under increasingly general conditions (see e.g. [8, 16, 25, 9, 2, 3, 13, 17]. Similar results have recently been proven for geometric balls (see e.g. [7, 14, 20]). For dynamical balls, which are the metric equivalent of cylinder sets and which are are used in the construction of equilibrium states and the formulation of entropy for continuous maps on metric spaces, much less is known. According to a result of Varandas [23] the exponential growth rate of

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the recurrence time equals the entropy. Previously, Brin and Katok [6] have proven a Shannon-McMillan-Breiman type theorem for Bowen balls. This paper builds on [15] where limiting distributions of entry and return times were determined together and rates of convergence we given. The principal assumption is that the given invariant probability measure is $\phi$-mixing or $\alpha$-mixing. Although this seems restrictive, all systems that allow a Young tower construction [26, 27] do satisfy the $\alpha$-mixing property.

In the next section we give the main results. In Section 3 we prove Theorem 3 which states that for ergodic, positive entropy systems the minimal recurrence time grows at least linearly. In Section 4 we prove a general result on the higher order return distributions for $\alpha$-mixing systems, where the return sets can be unions of cylinders over a countably infinite alphabet. For that purpose we use the Chen-Stein method of which we give a short sketch at the beginning of the section. This result is then used in Section 5 to prove the first two main theorems which in fact follow from the more general Theorem 5.

2. Main results

Let $(X, T, \mu)$ be a measure preserving system with $T : X \to X$ continuous and $\mu$ a $T$-invariant probability measure which we assume to be ergodic with entropy $h(\mu) > 0$. For $A \subset X$ we denote by $W_{A,m}(x)$ the number of visits of the orbit \{\(T(x), T^2(x), \ldots, T^m(x)\)\} (for some $m \in \mathbb{N}$) to the set $A$, i.e.

$$W_{A,m}(x) = \sum_{j=1}^{m} \chi_A(T^j(x))$$

where $\chi_A$ is the characteristic function of the set $A$, i.e. $\chi_A(x) = 1$ if $x \in A$ and $\chi_A(x) = 0$ otherwise. The purpose of this paper is to get results on the distributions of $W$ in the case when the return set $A$ is a Bowen ball and the cutoff values $m$ for the length of the orbits are scaled by the measures of the return set. Clearly $W_{A,m}(x) = 0$ if the entry/return time $\tau_A(x)$ is larger than $m$, where $\tau_A(x) = \min\{j \geq 1 : T^j x \in A\}$.

Let $\mathcal{A}$ be a finite measurable partition and denote by $\mathcal{A}^n = \bigvee_{j=0}^{n-1} T^{-1} \mathcal{A}$ the $n$th join (n-cylinders). We assume that $\mathcal{A}$ is generating, i.e. that $\mathcal{A}^\infty$ consists of single points. For a set $Y \subset X$ we shall use the notation $A_n(Y) = \bigcup_{A \in \mathcal{A}^n, A \cap Y \neq \emptyset} A$ as the smallest union of $n$-cylinders that approximates $Y$ from the outside. In particular $A_n(x)$ denotes the $n$-cylinder that contains $x$.

We shall require that the measure $\mu$ have some mixing property with respect to this partition $\mathcal{A}$. To be more precise, we say that $\mu$ is $\phi$-mixing if

$$|\mu(A \cap T^{-n-k}B) - \mu(A)\mu(B)| \leq \phi(k)\mu(B)$$
for all $A \in \sigma(A^n)$, $B \in \sigma(\bigcup_j A^j)$, where $\phi(k)$ is a decreasing function that converges to 0. Similarly, we say that $\mu$ is $\phi$-mixing if

$$|\mu(A \cap T^{-n-k}B) - \mu(A)\mu(B)| \leq \phi(k)$$

for some decreasing function $\phi(k)$ that converges to 0.

We will also require some regularity of the measure. For $x \in X$, $0 < \delta < \epsilon$ we define

$$\psi(\epsilon, \delta, x) = \frac{\mu(B(x, \epsilon + \delta)) - \mu(B(x, \epsilon - \delta))}{\mu(B(x, \epsilon))}$$

as in [15]. $\psi$ measures the proportion of the measure of the annulus $B(x, \epsilon + \delta) \setminus B(x, \epsilon - \delta)$ to the ball $B(x, \epsilon)$.

For $\epsilon > 0$ and $n \in \mathbb{N}$ we define the $(\epsilon, n)$-Bowen ball as usual:

$$B_{\epsilon,n}(x) = \{y : \sup_{0 \leq k < n} d(T^k x, T^k y) < \epsilon\}.$$  

Bowen balls have the property that they capture the local dynamics in metric spaces and are used to define entropy, pressure and prove the existence of equilibrium states for given potential functions (see e.g. [24]). In many ways Bowen balls play on metric spaces the role that cylinder sets play in symbolic systems. For instance, according to Brin and Katok [6] one has the metric analogue of the theorem of Shannon-McMillan-Breimann:

$$\lim_{\epsilon \to 0} \lim_{n \to \infty} \frac{1}{n} |\log \mu(B_{\epsilon,n}(x))| = h(\mu)$$

for $\mu$-almost every $x$ provided $\mu$ is ergodic. Similarly, Varandas [23] provided us with the metric equivalent of Ornstein-Weiss’ formula for the recurrence time $R_{\epsilon,n}(x) = \min\{j \geq 1 : T^j x \in B_{\epsilon,n}(x)(x)\}$, according to which

$$\lim_{\epsilon \to 0} \lim_{n \to \infty} \frac{1}{n} \log R_{\epsilon,n}(x) = h(\mu)$$

$\mu$ almost everywhere for ergodic $\mu$. In a previous paper [15] we studied the distribution of the first entry and return times. Here we take up the subject of higher order returns. We have the following result.

**Theorem 1.** Assume that the invariant measure $\mu$ is $\phi$-mixing where $\phi(n) = O\left(\frac{1}{n^{2+\varepsilon}}\right)$ and $\text{diam}(A^n) = O(\gamma^n)$ for some $\gamma < 1$, $\xi \leq 1$. Moreover assume that $\mu$ satisfies the following regularity condition

$$\psi(\epsilon, \delta, x) \leq \frac{C_\epsilon}{|\log \delta|^\zeta}$$

for some $\zeta > 1/\xi$, $C_\epsilon > 0$ independent of $x$. Put $m = \frac{1}{\mu(B_{\epsilon,n}(x))}$. 
Then there exists $\epsilon_0 > 0$ so that for every $\epsilon < \epsilon_0$ we have
\[
\lim_{n \to \infty} \mathbb{P}(W_{B, n}(x) = m) = e^{-\frac{\tau^{(k)}}{k!}}
\]
almost surely.

If the measure has better regularity then we can relax the condition on the diameter of cylinders and obtain the following statement:

**Theorem 2.** Assume that there exist constants $\alpha, \kappa, \xi > 0$ satisfying $\alpha \xi > 1$, such that $\text{diam}({\mathcal A}^n) = \mathcal{O}(n^{-\alpha})$, $\phi(n) = \mathcal{O}(n^{-(2+\kappa)})$ and
\[
\psi(\epsilon, \delta, x) \leq C \epsilon \delta^\xi
\]
for some constant $C_\epsilon$ independent of $\delta$ and $x$.

Then there exists $\epsilon_0 > 0$ so that for every $\epsilon < \epsilon_0$ we have
\[
\lim_{n \to \infty} \mathbb{P}(W_{B, n}(x) = m) = e^{-\frac{\tau^{(k)}}{k!}}
\]
almost surely, where $m = \frac{1}{\mu(B, n(x))}$.

The proof of these two theorems is in Section 5. In the proof of these theorems we need some estimate on the minimum return time of points in $B_{\epsilon, n}(x)$, which is in the next section.

### 3. Recurrence time for dynamical balls

For a set $A \subset X$ we have the first hitting time of a point $x$ given by $\tau_A(x) = \min\{k > 0 : T^k(x) \in A\}$. The period of the set $A$ is then given by
\[
\tau(A) = \min\{k > 0 : T^{-k}(A) \cap A \neq \emptyset\}
\]
which evidently equals $\tau(A) = \min_{x \in A} \tau_A(x)$. The statement of the following theorem is well known for cylinder sets [22] and will here be proven for Bowen balls.

**Theorem 3.** Assume that $\mu$ is ergodic with entropy $h(\mu) > 0$.

(i) Then for almost every $x \in X$
\[
\lim_{\epsilon \to 0} \liminf_{n \to \infty} \frac{\tau(B_{\epsilon, n}(x))}{n} \geq 1.
\]

(ii) If, moreover, the map $T$ has specification, then
\[
\limsup_{n \to \infty} \frac{\tau(B_{\epsilon, n}(x))}{n} \leq 1
\]
for all $\epsilon$ small enough.
Let us recall that a map \( T : X \rightarrow X \) has specification if for every \( \epsilon > 0 \) there exists a separation time \( K(\epsilon) \) so that any two (in fact arbitrarily many) orbit segments \( T^jx, j = 0, 1, \ldots, n_x \) and \( T^jy, j = 0, 1, \ldots, n_y \) can be \( \epsilon \)-shadowed by an actual orbit, that is there exist a point \( z \in X \) and \( m \leq K \) such that \( d(T^jz, T^jx) < \epsilon \) for \( j = 0, 1, \ldots, n_x \) and \( d(T^n + 1 + m + jz, T^jy) < \epsilon \) for \( j = 0, 1, \ldots, n_y \).

In order to prove the lower bound (i) we need the following lemma.

**Lemma 1.** [6] Let \( \mathcal{A} \) be a finite generating partition with \( \mu(\partial \mathcal{A}) = 0 \). Then for all \( \delta > 0 \) there exist \( N > 0 \) and a set \( D_N \) with \( \mu(D_N) > 1 - \delta \), such that

\[
|\{ A \in \mathcal{A}^n : A \cap B_{\epsilon,n}(x) \neq \emptyset \}| \leq \epsilon^{\delta n} \quad \forall x \in D_N
\]

for all \( \epsilon \) small enough and \( n \geq N \).

**Proof.** For all \( \epsilon > 0 \), define \( U_\epsilon(\mathcal{A}) = \bigcup_{A \in \mathcal{A}} U_\epsilon(A) \) where

\[
U_\epsilon(A) = \{ x \in A : \text{there exist } y \in X \setminus A \text{ with } d(x, y) < \epsilon \} = A \cap B(X \setminus A, \epsilon).
\]

Since \( \bigcap_{\epsilon > 0} U_\epsilon(A) = \partial(A) \), we have \( \lim_{\epsilon \rightarrow 0} \mu(U_\epsilon(A)) = 0 \), and thus for every \( \beta > 0 \), there exists \( \epsilon_0 \) small enough so that

\[
\mu(U_\epsilon(A)) < \beta/2, \text{ for all } \epsilon < \epsilon_0.
\]

By the Birkhoff ergodic theorem,

\[
\lim_{n \rightarrow \infty} \frac{1}{n} \sum_{k=0}^{n-1} \chi_{\mathcal{A}}(T^k(x)) < \beta/2, \text{ for a.e } x \in X.
\]

Take \( N_1 \) so that the set \( D_N \) defined by

\[
D_N = \{ x \in X : \frac{1}{n} \sum_{k=0}^{n-1} \chi_{\mathcal{A}}(T^k(x)) < \beta \quad \forall n \geq N \}
\]

satisfies

\[
\mu(D_N) > 1 - \delta, \text{ for all } N > N_1.
\]

Every \( n \)-cylinder \( A_n(x) \) is identified by the \( n \)-word \( x_0x_1 \cdots x_{n-1} \) where \( x_k \in \mathcal{A} \). We call this word the \((\mathcal{A}, n)\)-name of \( A_n(x) \). For all \( y \in B_{\epsilon,n}(x) \) and \( 0 \leq k \leq n - 1 \), either \( T^k(y) \in A_1(T^k(x)) \), or \( T^k(x) \in U_\epsilon(\mathcal{A}) \). Now let us note that for all \( x \) in \( D_N \), the frequency of the latter possibility (i.e. \( T^k(x) \in U_\epsilon(\mathcal{A}) \)) is less than \( \beta \). In other words, \( d^H_{n}(x,y) < \beta \) for all \( y \in B_{\epsilon,n}(x) \), \( x \in D_N \) and \( n > N \), where \( d^H_{n} \) is the Hamming distance given by \( d^H_{n}(x,y) = \frac{1}{n} \sum_{k=0}^{n-1} (1 - \delta_{x_k,y_k}) \) with \( \delta \) denoting the Kronecker symbol.

If we denote \( C_{\beta,n}(x) = \{ y : d^H_{n}(x,y) < \beta \} \) the cluster of \( n \)-cylinders centred at \( x \) then

\[
B_{\epsilon,n}(x) \subset A_n(B_{\epsilon,n}(x)) \subset C_{\beta,n}(x), \quad \forall x \in D_N, n > N.
\]
Using Stirling’s formula, it is easy to show that
\[ \lambda_n \leq \sum_{m=0}^{[\log n]} |A|^m \left( \begin{array}{c} n \\ m \end{array} \right). \]

Using Stirling’s formula, it is easy to show that
\[ \limsup_{n \to \infty} \frac{\log \lambda_n}{n} \leq \beta \log |A| - \beta \log \beta - (1 - \beta) \log(1 - \beta). \]

The right-hand-side converges to 0 as \( \beta \) approaches 0. For any given \( \delta > 0 \) we can take \( \beta \) small enough such that \( \lambda_n \leq e^{\delta n} \) for all \( n \geq N \) for some large enough \( N \). In particular
\[ \left| \{ A \in \mathcal{A}^n, A \cap B_{\epsilon,n}(x) \neq \emptyset \} \right| \leq e^{\delta n}. \]

**Proof of Theorem 3.** Let \( \delta > 0 \) and \( D_N, N \) as in Lemma 1. Then for all \( x \in D_N \) we have \( B_{\epsilon,n}(x) \subset C_{\beta,n}(x) \), where \( C_{\beta,n}(x) = \{ y : d_n^H(x,y) < \beta \} \) with \( \beta > 0 \) being chosen below. Hence
\[ \tau(B_{\epsilon,n}(x)) \geq \tau(C_{\beta,n}(x)). \]

For arbitrary \( \eta < 1 \), fix \( \zeta < \frac{1}{8} h \) small and let \( E_N = \{ x : e^{-(h+\zeta)n} \leq \mu(\mathcal{A}^n(x)) \leq e^{-(h-\zeta)n} \) for all \( n \geq N \}. \) By the Theorem of Shannon-McMillan-Breiman, we can take \( N \) large such that \( \mu(E_N) \geq 1-\delta \). Set \( G_N = D_N \cap E_N \), we have \( \mu(G_N) \geq 1-2\delta \). For a large enough constant \( c_1 \) (depending on \( N \)) we achieve that \( c_1^{-1} e^{-(h+\zeta)n} \leq \mu(\mathcal{A}^n(x)) \leq c_1 e^{-(h-\zeta)n} \) hold for all \( n > 0 \).

Define
\[ B_n = \{ x \in G_N : \tau(B_{\epsilon,n}(x)) < \eta n \} \]
and
\[ \tilde{B}_n = \{ x \in G_N : \tau(C_{\beta,n}(x)) < \eta n \}. \]

Clearly \( B_n \subset \tilde{B}_n \) for all \( n \leq N \).

If we put \( R_n(k) = \{ x : \tau(C_{\beta,n}(x)) = k \} \) for \( k \leq [\eta n] \) then \( \tilde{B}_n = \bigcup_{k=1}^{[\eta n]} R_n(k) \) (disjoint union). In other words, if \( x \in R_n(k) \) then \( T_j^{\tau(C_{\beta,n}(x))} \cap \mathcal{A}^n \neq \emptyset \) for \( j = 1, \ldots, k-1 \) and there exists some \( y \in C_{\beta,n}(x) \) such that \( T^k(y) \in \mathcal{A}^n \). Hence we have \( d_n^H(y,T^k y) \leq d_n^H(y,x) + d_n^H(x,T^k y) \leq 2 \beta \). Set \( \tilde{R}_n(k) = \{ y : d_n^H(y,T^k y) \leq 2 \beta \} \) and we obtain
\[ R_n(k) \subset \{ x : \text{there exist } y \in \tilde{R}_n(k) \text{ such that } d_n^H(x,y) \leq \beta \}. \]

First we estimate \( \mu(\tilde{R}_n(k)) \). For every \( y \in \tilde{R}_n(k) \), let
\[ A_n(y) = (y_1 \ldots y_\lambda y_{\lambda+1} \ldots y_{2\lambda} \ldots y_{\lambda+\lambda} \ldots y_n) \]
with \( y_i \in \mathcal{A}, m = \lfloor \frac{n}{k} \rfloor \), then

\[ A_n(T^k y) = (y_{k+1} \ldots y_{2k} y_{2k+1} \ldots y_{3k} \ldots y_{(m+1)k+1} \ldots y_{n+k}). \]

Let \( g_i = \sum_{j=k+1}^{(i+1)k} (1 - \delta_{y_j,y_{j+k}}) \) for \( i = 1, 2, \ldots, m \), where \( \delta_{a,b} \) is the standard Kronecker symbol. That is \( g_i \) is the number of coordinates on which \( y_{ik+1} \ldots y_{(i+1)k} \) and \( y_{(i+1)k+1} \ldots y_{(i+2)k} \) differ. Obviously \( g_i \leq k \) and also \( \sum_{i=1}^{m} g_i \leq 2\beta n \) as \( y \in \tilde{R}^n(k) \).

For given \((g_1, g_2, \ldots, g_m)\) and given \( k\)-word \( y_1 y_2 \cdots y_k \), the total number of \( n\)-cylinders \( A_n(y) \) that lie in the given \( A_k(y) = (y_1 y_2 \cdots y_k) \) and for which \( y \in \tilde{R}^n(k) \) is bounded from above by

\[ a_{n,y_1,\ldots,y_k;g_1,\ldots,g_m} \leq \left( \begin{array}{c} k \\ g_1 \end{array} \right) |\mathcal{A}|^{g_1} \left( \begin{array}{c} k \\ g_2 \end{array} \right) |\mathcal{A}|^{g_2} \cdots \left( \begin{array}{c} k \\ h_m \end{array} \right) |\mathcal{A}|^{g_m} \leq \left( \frac{n}{2\beta n} \right) |\mathcal{A}|^{2\beta n}. \]

To simplify notation, we abbreviate the LHS to \( a_n \). By Stirling’s formula

\[ \frac{\log a_n}{n} \leq 2\beta \log |\mathcal{A}| - (1 - 2\beta) \log(1 - 2\beta) - 2\beta \log 2\beta \to 0 \]

as \( \beta \to 0 \). We can take \( \beta \) small such that \( a_n \leq e^{\delta n} \) where \( \delta > 0 \) is as above.

Denote by \( b_{n,k} \) the total number of such possible \((g_1, \ldots, g_m) \in \{1, 2, \ldots, k\}^m\). Then

\[ b_{n,k} = \sum_{j=0}^{[2\beta n]} \binom{j + m - 1}{m - 1} = \binom{[2\beta n] + m}{m} = \binom{[2\beta n] + n}{\frac{n}{k}} \]

which, again by Stirling’s formula, can be bound as follows:

\[ \frac{\log b_{n,k}}{n} \leq f(2\beta + \frac{1}{k}) - f\left( \frac{1}{k} \right) - f(2\beta), \]

where we put \( f(x) = x \log x \). Since \( f(x) \to 0 \) as \( x \to 0 \) and \( f(x) \) is uniformly continuous on \((0, 2]\), we have \( \lim_{\beta \to 0} \frac{\log b_{n,k}}{n} = 0 \) and in particular

\[ b_{n,k} \leq e^{\delta n} \]

if we only take \( \beta \) small enough.

All the above estimates combined now yield:

\[ \mu(\tilde{R}^n(k)) \leq \sum_{y \in \tilde{R}^n(k)} \mu(A_n(y)) \]
\[ \mu(\tilde{R}^n(k)) \leq \sum_{A_k(y), y \in \tilde{R}^n(k)} c_1 e^{-(\epsilon - \delta)n} \]
\[ \leq \sum_{A_k(y), y \in \tilde{R}^n(k)} b_n, k c_1 e^{-(\epsilon - \delta)n} \]
\[ \leq \sum_{A_k(y), y \in \tilde{R}^n(k)} c_1 e^{-(\epsilon - 2\delta)n}. \]

For \( y \in \tilde{R}^n(k) \subset G_N \), we have \( c_1^{-1} e^{-(\epsilon + \gamma)k} \leq \mu(A_k(y)) \), hence \( 1 \leq c_1 (\epsilon + \gamma) \mu(A_k(y)) \). Therefore
\[ \mu(\tilde{R}^n(k)) \leq \sum_{A_k(y), y \in \tilde{R}^n(k)} c_1^2 e^{-(\epsilon - \gamma - 2\delta)n} k \epsilon (A_k(y)) \leq c_1^2 e^{-(\epsilon - \gamma - 2\delta)n} (\epsilon + \gamma) k \]
\[ \leq c_1^2 e^{-(\epsilon - \gamma - 2\delta)n} + (\epsilon + \gamma) k. \]

Since \( c_1^{-1} e^{-(\epsilon + \gamma)n} \leq \mu(A_n(x)) \leq c_1 e^{-(\epsilon - \gamma)n} \) for every \( n \)-cylinder in \( G_N \), \( \tilde{R}^n(k) \) can be covered by at most \( c_1^3 e^{-(\epsilon - \gamma - 2\delta)n} + (\epsilon + \gamma) k + (\epsilon + \gamma)n \) many \( n \)-cylinders. Since \( \tilde{R}^n(k) \) is contained in the \( \beta \)-neighbourhood of \( \tilde{R}^n(k) \) (under the Hamming metric \( d_N^H \)), and every \( \beta \)-neighbourhood of an \( n \)-cylinder contains at most \( \lambda_n < e^{\delta n} \) many \( n \)-cylinders according to (I), the total number of \( n \)-cylinders that intersects \( R^m(k) \) is bounded from above by
\[ \lambda_n c_1^3 e^{-(\epsilon - \gamma - 2\delta)n} + (\epsilon + \gamma) k + (\epsilon + \gamma)n \leq c_1^3 e^{(\gamma + 3\delta)n} (\epsilon + \gamma) k. \]

Therefore,
\[ \mu(R^m(k)) \leq c_1^3 e^{(\gamma + 3\delta)n} k \epsilon (R^m(k)) \leq c_1^4 e^{(\gamma + 3\delta)n} + (\epsilon + \gamma) k. \]

Summing over \( k \), we finally obtain
\[ \mu(\tilde{B}_n) = \sum_{k=1}^{\eta} \mu(R^m(k)) \]
\[ \leq \sum_{k=1}^{\eta} c_1^4 e^{(\gamma + 3\delta)n} + (\epsilon + \gamma) k \]
\[ \leq c_2 e^{(\gamma + 3\delta)n} n (\epsilon + \gamma) \eta \]
\[ \leq c_2 e^{(\gamma + 4\delta + 3\delta)n}. \]

Since \( B_n \subset \tilde{B}_n \) for all \( n \geq N \), we have
\[ \sum_n \mu(B_n) \leq N + \sum_{n>N} \mu(\tilde{B}_n) \leq N + \sum_{n>N} c_2 e^{-(1 - \eta)h + 4\gamma + 3\delta)n}. \]
We can choose \( \delta < \frac{1-n}{8} \) and \( \zeta < \frac{1-n}{8} h \), hence

\[-(1 - \eta)h + 4\zeta + 3\delta \leq -\frac{1-\eta}{8}h < 0.\]

Therefore \( \sum_{n} \mu(B_n) < \infty \). By the Borel-Contelli lemma, for almost every \( x \in G_N \) we have \( \liminf_{n} \frac{\tau(B_{\epsilon,n}(x))}{n} \geq \eta \). Since \( \eta < 1 \) is arbitrary, the lower bound (i) of the theorem follows.

Therefore \( \sum_{n} \mu(B_{\epsilon,n}(x)) < \infty \). By the Borel-Contelli lemma, for almost every \( x \in G_N \) we have \( \liminf_{n} \frac{\tau(B_{\epsilon,n}(x))}{n} \geq \eta \). Since \( \eta < 1 \) is arbitrary, the lower bound (i) of the theorem follows.

In order to get the upper bound (ii) for a map with specification let \( K(\epsilon) \) be the separation time. Then there exists a point \( z \in B_{\epsilon,n}(x) \) and an \( m \leq K \) so that \( T_{n+m} \in B_{\epsilon,n}(x) \). Hence \( \tau(B_{\epsilon,n}(x)) \leq n + K \) and consequently \( \lim_{n \to \infty} \frac{1}{n} \tau(B_{\epsilon,n}(x)) \leq 1 \). □

4. \( \alpha \)-mixing system have Poisson distributed return times for unions of cylinders

This section is on the return times to sets that are unions of cylinders, where the underlying partition \( \mathcal{A} \) is allowed to be countably infinite. Recall that \( W_{A,m}(x) \) is the number of visits of the orbit \( \{T(x), T^2(x), \ldots, T^m(x)\} \) to the set \( A \), i.e.

\[ W_{A,m}(x) = \sum_{j=1}^{m} \chi_A(T^j(x)). \]

We then have the following result.

**Theorem 4.** Let \( \mu \) be \( \alpha \)-mixing w.r.t. a finite or countably infinite partition \( \mathcal{A} \) and let \( A \in \sigma(\mathcal{A}^n) \). As before, let \( \tau(A) \) be the period of \( A \). For any \( t > 0 \), let \( m = \frac{t}{\mu(A)} \) and denote by \( \nu_t \) the Poisson measure on \( \mathbb{N}_0 \) with parameter \( t \). Then there exists a constant \( C_1 \) so that for every set \( E \subset \mathbb{N}_0 \)

\[
|P(W_{A,m} \in E) - \nu_t(E)| 
\leq C_1 \min_{\tau(A) \leq \Delta \leq m} \left( \frac{\alpha(\Delta)}{\mu(A)} + \Delta \mu(A) + P_A(\tau_A \leq \Delta) \right) \left( t + \log m \right).
\]

For similar result see [2, 4, 3] where the Poisson distribution for \( \phi \)-mixing measures was shown for single cylinders centred at a generic point. To prove this theorem we use the Chen-Stein method similar to [13] where it was laid out in more detail than we do here although we shall proceed to give a summary of the procedure.

Let \( \nu \) be a probability measure on \( \mathbb{N}_0 \) (equipped with the power \( \sigma \)-algebra \( \mathcal{B}_{\mathbb{N}_0} \)). If we denote by \( \mathcal{F} \) the set of all real-valued functions on \( \mathbb{N}_0 \), then the Stein operator \( S : \mathcal{F} \to \mathcal{F} \) is defined by

\[
Sf(k) = tf(k+1) - kf(k), \quad \forall k \in \mathbb{N}_0.
\]

(2)
Denote by $\nu_t$ the Poisson-distribution measure with mean $t$, i.e. $\mathbb{P}_{\nu_t}(\{k\}) = \frac{e^{-tk}}{k!}$. \forall k \in \mathbb{N}_0$ then the Stein equation

$$(3)\quad Sf = h - \int_{\mathbb{N}_0} h d\nu_t$$

has a solution $f$ for each $\nu_t$-integrable $h \in F$ (see [5]). The solution $f$ is unique except for $f(0)$, which can be chosen arbitrarily.\footnote{1} In particular, if $h : \mathbb{N}_0 \to \mathbb{R}$ is bounded then so is the associated Stein solution $f$. A probability measure $\nu$ on $(\mathbb{N}_0, \mathcal{B}_{\mathbb{N}_0})$ is Poisson (with parameter $t$) if and only if \footnote{2} $\int_{\mathbb{N}_0} Sf d\nu = 0$ for all bounded functions $f : \mathbb{N}_0 \to \mathbb{R}$. The total variation distance of a probability measure $\nu$ from the Poisson distribution $\nu_t$ can then be estimated as follows:

$$|\nu(E) - \nu_t(E)| = \left| \int_{\mathbb{N}_0} Sf d\nu \right| = \left| \int_{\mathbb{N}_0} (tf(k+1) - kf(k)) d\nu \right|$$

where $E \subset \mathbb{N}_0$ and $f$ is the Stein solution that corresponds to the indicator function $\chi_E$. The following lemma on the function $f$ associated to characteristic functions was proven in [13].

**Lemma 2.** For the Poisson distribution $\mu_0$, the Stein solution of the Stein equation $(3)$ that corresponds to the indicator function $h = \chi_E$, with $E \subset \mathbb{N}_0$, satisfies

$$(5)\quad |f_{\chi_E}(k)| \leq \begin{cases} 1 & \text{if } k \leq t \\ \frac{2 + t}{k} & \text{if } k > t \end{cases}$$

In particular

$$(6)\quad \sum_{k=1}^{m} |f_{\chi_E}(k)| \leq \begin{cases} m & \text{if } m \leq t \\ t + (2 + t) \log \frac{m}{t} & \text{if } m > t \end{cases}$$

### 4.1. Return times distribution.

**Proof of Theorem 4.** The Poisson parameter $t$ is the expected value of $W_{A,m}$ which implies $t = \sum_{i=1}^{m} \mu(\chi_A T^i) = m \mu(A)$, where $\mu(T^{-i} A) = \mu(A)$ by invariance. If $h = \chi_E$ with $E \subset \mathbb{N}_0$ an arbitrary subset of the positive integers, then we obtain from (4) and (2)

$|\nu(Sf)| = |\nu(h) - \nu_t(h)| = |\mathbb{P}(W_{A,m} \in E) - \nu_t(E)| = |\mathbb{E}(tf(W_{A,m} + 1) - W_{A,m}f(W_{A,m}))|$.\footnote{1} $f$ can be computed recursively from the Stein equation:

$$f(k) = \frac{(k-1)!}{t^k} \sum_{i=0}^{k-1} (h(i) - \mu_0(h)) \frac{t^i}{i!} = -\frac{(k-1)!}{t^k} \sum_{i=k}^{\infty} (h(i) - \mu_0(h)) \frac{t^i}{i!}, \quad \forall k \in \mathbb{N}.$$
Hence we can proceed as follows:

\[ |P(W_{A,m} \in E) - \nu_t(E)| = \left| tE \{ f(W_{A,m} + 1) - E \left( \sum_{i=1}^{m} I_i f(W_{A,m}) \right) \} \right| \]

\[ = \left| \sum_{i=1}^{m} p_i \{ f(W_{A,m} + 1) - f(W_{A,m}) I_i \} \right| \]

\[ = \sum_{i=1}^{m} p_i \left( \sum_{a=0}^{m} f(a + 1)P(W_{A,m} = a) - \sum_{a=0}^{m} f(a)P(W_{A,m} = a|I_i = 1) \right) \]

\[ = \sum_{i=1}^{m} p_i \sum_{a=0}^{m} f(a + 1)\epsilon_{a,i}, \tag{7} \]

where we put \( I_i(x) = \chi_A T^i(x) \) for the characteristic function of the set \( T^{-i}A \) and

\[ \epsilon_{a,i} = |P(W_{A,m} = a) - P(W_{A,m} = a+1|I_i = 1)|. \tag{8} \]

The function \( f \) above is the solution of the Stein equation \( \xi \) that corresponds to the indicator function \( h = \chi_E \) in the Stein method and has been bounded in Lemma \( \Sigma \).

In order to estimate the error term \( \epsilon_{a,i} \) put \( W_{A,m} = W_{A,m} - \chi_A \circ T^i = \sum_{1 \leq j \leq m} \chi_A \circ T_j \) (punctured sum). Then

\[ \epsilon_{a,i} = \left| P(W_{A,m} = a) - \frac{P(\{W_{A,m}^i = a\} \cap T^{-i}A)}{\mu(A)} \right| \leq \left| P(W_{A,m} = a) - P(W_{A,m}^i = a) \right| + \frac{\xi_a}{\mu(A)} \]

where \( \xi_a = \max_i \left| P(\{W_{A,m}^i = a\} \cap T^{-i}A) - P(W_{A,m}^i = a) \right| \mu(A) \) is zero if all \( I_i \) are independent of each other. The first term is estimated by

\[ \left| P(W_{A,m} = a) - P(W_{A,m}^i = a) \right| \leq P(I_i = 1) = \mu(A). \]

For the second term, which contains \( \xi_a \), we proceed as follows.

Let \( \Delta \ll m \) be a positive integer (the halfwidth of the gap) and put for every \( i \in (0, m] \)

\[ W_{A,m}^{-i} = \sum_{j=1}^{i-(\Delta+1)} \chi_A \circ T^j, \]

\[ W_{A,m}^{+i} = \sum_{j=i+\Delta+1}^{m} \chi_A \circ T^j, \]

\[ U_m^{-i} = \sum_{j=i-\Delta}^{i-1} \chi_A \circ T^j, \]

\[ U_m^{+i} = \sum_{j=i+1}^{i+\Delta} \chi_A \circ T^j \]

with the obvious modifications if \( i < \Delta \) or \( i > m - \Delta \). With these partial sums we distinguish between the hits that occur near the \( i^{th} \) iteration, namely \( U_{m}^{-i} \) and \( U_{m}^{+i} \), and the hits that occur away from the \( i^{th} \) iteration, namely \( W_{A,m}^{-i} \) and \( W_{A,m}^{+i} \). Let us
put $\tilde{W}_{A,m}^{i} = W_{A,m}^{i} - U_{m}^{i} = W_{A,m}^{i,-} + W_{A,m}^{i,+}$ for the total sum minus the $2\Delta + 1$ terms in the gap surrounding the coordinate $i$. The gap allows us to use the mixing property in the terms $W_{A,m}^{i,\pm}$ and its size will be determined later when we optimise the error term.

Note that for $a \in N_0$

$$
\mathbb{P} (\{W_{A,m} = a + 1\} \cap T^{-i}A) = \mathbb{P} (\{W_{A,m}^i = a\} \cap T^{-i}A) = \sum_{\tilde{a} = (a^-, a^0, a^+, a^+)} \mathbb{P} (\{W_{A,m}^{i,\tilde{a}} = a^{\pm}\} \cap \{U_{m}^{i,\tilde{a}} = a^{0,\pm}\} \cap T^{-i}A).
$$

We split the following sum into three terms

$$
\sum_{a} |f(a + 1)| \cdot |\mathbb{P} (\{W_{A,m} = a\} \cap T^{-i}A) - \mathbb{P} (W_{A,m}^i = a) \mu(A)| \leq R_1 + R_2 + R_3
$$

and will estimate the three terms

$$
R_1 = \sum_{a} |f(a + 1)| \cdot |\mathbb{P} (\{W_{A,m}^i = a\} \cap T^{-i}A) - \mathbb{P} (\tilde{W}_{A,m}^i = a) \cap T^{-i}A)|
$$

$$
R_2 = \sum_{a} |f(a + 1)| \cdot |\mathbb{P} (\tilde{W}_{A,m}^i = a) \cap T^{-i}A) - \mathbb{P} (\tilde{W}_{A,m}^i = a) \cap (I_i = 1)|
$$

$$
R_3 = \sum_{a} |f(a + 1)| \cdot |\mathbb{P} (\tilde{W}_{A,m}^i = a) - \mathbb{P}(W_{A,m}^i = a)| \mu(A)
$$

separately.

**Estimate of $R_1$:** Observe that

$$
\{W_{A,m} = a\} \cap T^{-i}A \subset \{\tilde{W}_{A,m}^i = a\} \cap T^{-i}A \cup \{U_{m}^i > 0\} \cap T^{-i}A
$$

$$
\{\tilde{W}_{A,m}^i = a\} \cap T^{-i}A \subset \{W_{A,m}^i = a\} \cap T^{-i}A \cup \{U_{m}^i > 0\} \cap T^{-i}A.
$$

Since $U_{m}^i = U_{m}^{i,+} + U_{m}^{i,-} > 0$ implies that either $U_{m}^{i,+} > 0$ or $U_{m}^{i,-} > 0$ we get

$$
|\mathbb{P} (\{W_{A,m}^i = a\} \cap T^{-i}A) - \mathbb{P}(\tilde{W}_{A,m}^i = a) \cap T^{-i}A)| \leq \mathbb{P}(\{U_{m}^i > 0\} \cap T^{-i}A) \leq b_i^- + b_i^+
$$

where

$$
b_i^- = \mathbb{P}(\{U_{m}^{i,-} > 0\} \cap T^{-i}A) \quad \text{and} \quad b_i^+ = \mathbb{P}(\{U_{m}^{i,+} > 0\} \cap T^{-i}A).
$$

For $b_i^+$ we obtain the estimate

$$
b_i^+ = \mathbb{P}(\{U_{m}^{i,+} > 0\} \cap T^{-i}A) = \mathbb{P}(U_{m}^{i,+} > 0|I_i = 1) \mu(A) = \mathbb{P}A(\tau_A \leq \Delta) \mu(A)
$$
and since in [13] it was shown that $b_i^- = b_i^+$ we obtain
\[ R_1 \leq c_2 P_A(\tau_A \leq \Delta) \mu(A) \sum_a |f(a + 1)| \leq c_3 P_A(\tau_A \leq \Delta) \mu(A)(t + \log m) \]

for some $c_3$ where we used Lemma 2 to estimate the sum over $a$.

**Estimate of $R_3$:** In order to show that short returns are negligible note that
\[
\begin{align*}
\{W_{A,m}^i = a\} & \subset \{\tilde{W}_{A,m}^i = a\} \cup \{U_m^i > 0\} \\
\{\tilde{W}_{A,m}^i = a\} & \subset \{W_{A,m}^i = a\} \cup \{U_m^i > 0\}
\end{align*}
\]

which yields
\[
\left| P(\tilde{W}_{A,m}^i = a) - P(W_{A,m}^i = a) \right| \leq P(U_m^i > 0) \leq 2 P\left( \bigcup_{k=1}^{\Delta} \{I_{i+k} = 1\} \right) \leq 2 \Delta \mu(A),
\]

and therefore
\[ R_3 \leq 2 \Delta \mu(A)^2 \sum_a |f(a + 1)| \leq c_4 \Delta \mu(A)^2 (t + \log m). \]

**Estimate of $R_2$:** This is the principal term and the speed of mixing now becomes relevant. Recall that $\tilde{W}_{A,m}^i(x) = W_{i,m}^i(x) + W_{i,m}^{i,+}(x)$ and we want to estimate
\[
R_2 \leq \sum_a |f(a + 1)| \left| P\left( \tilde{W}_{A,m}^i = a \right) - P(W_{A,m}^i = a) \mu(A) \right| \\
\leq \sum_{a^-} \sum_{a^+} |f(a^- + a^+ + 1)| \left( P\left( \tilde{W}_{m}^{i,\pm} = a^\pm \right) \cap T^{-i} A \right) - P\left( \tilde{W}_{m}^{i,\pm} = a^\pm \right) \mu(A) \epsilon_{a^-,a^+},
\]

where $\epsilon_{a^-,a^+} = \text{sgn}(P\left( \tilde{W}_{A,m}^i = a^- \right) \cap T^{-i} A - P\left( \tilde{W}_{A,m}^i = a^+ \right) \mu(A))$. If we put
\[
W^+(a^-) = \bigcup_{a^+: \epsilon_{a^-,a^+} = +1} \{\tilde{W}_{m}^{i,+} = a^+\}, \quad W^-(a^-) = \bigcup_{a^+: \epsilon_{a^-,a^+} = -1} \{\tilde{W}_{m}^{i,-} = a^+\},
\]

both disjoint unions, then
\[
R_2 \leq \sum_a |\varphi(a)| \left( P\left( \tilde{W}_{m}^{i,-} = a^- \right) \cap W^+(a^-) \cap T^{-i} A \right) - P\left( \tilde{W}_{m}^{i,-} = a^- \right) \mu(W^+(a^-)) \mu(A) \\
+ \sum_a |\varphi(a)| \left( P\left( \tilde{W}_{m}^{i,+} = a^+ \right) \cap W^-(a^+) \cap T^{-i} A \right) - P\left( \tilde{W}_{m}^{i,+} = a^+ \right) \mu(W^-(a^+)) \mu(A)
\]

where \( \varphi(a) = \sup_{a' \geq a} |f(a')| \) satisfies by Lemma 2 \( \varphi(a) \leq \min(1, \frac{c}{a}) \). We gave to estimate the two mixing terms, the first of which is for \( a^- \geq 0 \):

\[
\left| \mathbb{P} \left( \{ \hat{W}_m^{i^-} = a^- \} \cap \mathcal{W}^+(a^-) \cap T^{-i}A \right) - \mathbb{P} \left( \hat{W}_m^{i^-} = a^- \right) \mu \left( \mathcal{W}^+(a^-) \right) \mu(A) \right| \leq R_{2,1} + R_{2,2} + R_{2,3}
\]

where

\[
R_{2,1} = \left| \mathbb{P} \left( \{ \hat{W}_m^{i^-} = a^- \} \cap \mathcal{W}^+(a^-) \cap T^{-i}A \right) - \mathbb{P} \left( \{ \hat{W}_m^{i^-} = a^- \} \cap T^{-i}A \right) \mu \left( \mathcal{W}^+(a^-) \right) \right|
\]

\[
R_{2,2} = \left| \mathbb{P} \left( \{ W_{A,m}^{i^-} = a^- \} \cap T^{-i}A \right) - \mathbb{P} \left( W_{A,m}^{i^-} = a^- \right) \mu(A) \mu \left( \mathcal{W}^+(a^-) \right) \right|
\]

\[
R_{2,3} = \left| \mathbb{P} \left( W_{A,m}^{i^-} = a^- \right) \mu \left( \mathcal{W}^+(a^-) \right) - \mathbb{P} \left( \{ \hat{W}_m^{i^-} = a^- \} \cap \mathcal{W}^+(a^-) \right) \mu(A) \right|
\]

We now bound the three terms separately: Due to the mixing property we get for the first term the estimate

\[ R_{2,1} \leq \alpha(\Delta). \]

Similarly for the second term

\[ R_{2,2} \leq \alpha(\Delta) \mu \left( \mathcal{W}^+(a^-) \right), \]

while the third term is estimated by

\[ R_{2,3} \leq \alpha(2\Delta) \mu(A). \]

Combining these estimates and considering that the second term in the above estimate of \( R_2 \) is estimated in the same manner we obtain

\[ R_2 \leq c_4 \alpha(\Delta) \sum_a \varphi(a) \leq c_6 \alpha(\Delta)(t + \log m) \]

for some constant \( c_4 \).

Finally, putting together the error terms \( R_1, R_2 \) and \( R_3 \) yields

\[
|\mathbb{P}(W_{A,m} \in E) - \nu_t(E)|
\]

\[
\leq \sum_{i=1}^m p_i \left( \sum_{a=0}^m |f(a + 1)| \mu(A) + c_7 \left( \frac{\alpha(\Delta)}{\mu(A)} + 2\Delta \mu(A) + \mathbb{P}_A(\tau_A \leq \Delta) \right) (t + \log m) \right)
\]

\[
\leq c_8 \left( \mu(A) + \frac{\alpha(\Delta)}{\mu(A)} + \Delta \mu(A) + \mathbb{P}_A(\tau_A \leq \Delta) \right) (t + \log m)
\]

for some \( c_8 \) independent of \( A \). \( \square \)
5. Poisson distributed return times for Bowen balls

In this section we will prove Theorem 1. Recall that
\[ \psi(\epsilon, \delta, x) = \frac{\mu(B(x, \epsilon + \delta) \setminus B(x, \epsilon - \delta))}{\mu(B(x, \epsilon))} \]
is the proportion of the measure of the annulus \( B(x, \epsilon + \delta) \setminus B(x, \epsilon - \delta) \) to the ball \( B(x, \epsilon) \). Put \( \tau^k_A(x) = \tau_A \circ T_{\tau^{k-1}_A} \) for the \( k \)th return of \( x \) to the set \( A \):
\[
\tau^k_A(x) = \min \{ k > \tau^{k-1}_A(x) : T^k(x) \in A \}
\]
where \( \tau^1_A = \tau_A \).

We will prove the following more general theorem and then deduce Theorem 1 and Theorem 2.

**Theorem 5.** Let \( \mu \) be a \( \phi \)-mixing \( T \)-invariant ergodic measure with positive entropy. Let \( \gamma_n = \text{diam}(A^n) \). Assume that there exist \( \epsilon_0 > 0 \) and an increasing sequence \( \{N(n)\}_{n=1}^{\infty} \) satisfying \( n < N(n) < \frac{1}{\epsilon} \mu(B_{\epsilon,n}(x))^{-1} \) such that
\[
\psi(\epsilon, \gamma_{N(n)-k}, T^k x) \leq \vartheta_n(\epsilon) \cdot \frac{\mu(B_{\epsilon,n}(x))}{n}
\]
for all \( \epsilon < \epsilon_0, x \in X, 0 \leq k < n \), where \( \vartheta_n(\epsilon) \to 0 \) as \( n \to \infty \) (\( \forall \epsilon < \epsilon_0 \)).

Then for all \( t > 0 \) one has
\[
\lim_{n \to \infty} \mathbb{P}(W_{B_{\epsilon,n}(x), m} = k) = e^{-t^k_k} \frac{t^k_k}{k!},
\]
where \( m = \frac{t}{\mu(B_{\epsilon,n}(x))} \).

The idea of the proof is to use cluster of cylinders sets to approximate Bowen balls. For this purpose, for some integer \( N(n) \gg n \), define
\[
\tilde{B}_{\epsilon,n}(x) = \bigcup_{A \in A^{N(n)}, A \subset B_{\epsilon,n}(x)} A
\]
the union of all \( N(n) \)-cylinders contained in \( B_{\epsilon,n}(x) \). If we put
\[
\tilde{\partial}B_{\epsilon,n}(x) = \bigcup_{A \in A^{N(n)}, A \cap \partial B_{\epsilon,n}(x) \neq \emptyset} A
\]
as the union of all cylinders which intersect the boundary of \( B_{\epsilon,n}(x) \), then
\[
B_{\epsilon,n}(x) \setminus \tilde{B}_{\epsilon,n}(x) \subset \tilde{\partial}B_{\epsilon,n}(x).
\]

The next lemma (c.f. [15]) allows us to estimate the difference between \( \tilde{B}_{\epsilon,n}(x) \) and \( B_{\epsilon,n}(x) \).
Lemma 3. Under the hypothesis of Theorem 1 we have
\[ \mu(\partial B_{\epsilon,n}(x)) \leq \vartheta_n(\epsilon) \mu(B_{\epsilon,n}(x)) \]
and in particular, \( \mu(B_{\epsilon,n}(x))/\mu(\widetilde{B}_{\epsilon,n}(x)) = O(1) \).

Proof. Since \( T \) is continuous, \( \partial B_{\epsilon,n}(x) \subset \bigcup_{k=0}^{n-1} T^{-k} \partial B(T^k x, \epsilon) \). Hence if \( A_{N(n)} \cap \partial B_{\epsilon,n}(x) \neq \emptyset \) for some \( N(n) \)-cylinder \( A_{N(n)} \), then \( A_{N(n)-k}(T^k y) \cap \partial B(T^k x, \epsilon) \neq \emptyset \) for some \( 0 \leq k \leq n-1 \) and \( y \in A^{N(n)} \). Since \( \text{diam}(A_{N(n)-k}(T^k y)) \leq \gamma_{N(n)-k} \) we obtain
\[
\partial B_{\epsilon,n}(x) \subset \bigcup_{k=0}^{n-1} T^{-k} (B(\partial B(T^k x, \epsilon), \gamma_{N(n)-n})) \subset \bigcup_{k} T^{-k} (B(T^k x, \epsilon + \gamma_{N(n)-k}) \setminus B(T^k x, \epsilon + \gamma_{N(n)-k})),
\]
and consequently
\[
\mu(\partial B_{\epsilon,n}(x)) \leq n \cdot \sup_{0 \leq k \leq n-1} \mu(B(T^k x, \epsilon + \gamma_{N(n)-k}) \setminus B(T^k x, \epsilon + \gamma_{N(n)-k})) = n \cdot \sup_{0 \leq k \leq n-1} \{ \psi(\epsilon, \gamma_{N(n)-k}, T^k x) \cdot \mu(B(T^k x, \epsilon)) \} \leq n \cdot \sup_{0 \leq k \leq n-1} \{ \psi(\epsilon, \gamma_{N(n)-k}, T^k x) \} \leq \partial_n(\epsilon) \mu(B_{\epsilon,n}(x)).
\]

In particular \( \mu(\partial B_{\epsilon,n}(x))/\mu(\widetilde{B}_{\epsilon,n}(x)) = \partial_n \rightarrow 0 \) and therefore \( \mu(B_{\epsilon,n}(x))/\mu(\widetilde{B}_{\epsilon,n}(x)) = O(1) \).

Next we show that the limiting distribution for the hitting times of \( B_{\epsilon,n}(x) \) can be approximated by the distribution of \( \widetilde{B}_{\epsilon,n}(x) \). To simplify notation we write \( B = B_{\epsilon,n}(x) \) and \( \widetilde{B} = \widetilde{B}_{\epsilon,n}(x) \). For \( t > 0 \) we put \( m = \frac{1}{\mu(B)} \) and \( \tilde{m} = \frac{1}{\mu(\widetilde{B})} \) and write for simplicity’s sake
\[
\Theta_{B,m}(k) = \mathbb{P}(W_{B,m} = k), \quad \Theta_{\widetilde{B},\tilde{m}}(k) = \mathbb{P}(W_{\widetilde{B},\tilde{m}} = k)
\]
and others similarly. The following approximation lemma does not depend on the mixing property.

Lemma 4. For all \( t \geq 0 \) we have
\[
\left| \Theta_{B,m}(k) - \Theta_{\widetilde{B},\tilde{m}}(k) \right| \leq 2t \cdot \vartheta_n(\epsilon) \rightarrow 0
\]
as \( n \rightarrow \infty \).

\[ \]
Proof. By the triangle inequality
\[
\left| \Theta_{B,m}(k) - \Theta_{\tilde{B},\tilde{m}}(k) \right| \leq \left| \Theta_{B,m}(k) - \Theta_{\tilde{B},m}(k) \right| + \left| \Theta_{\tilde{B},m}(k) - \Theta_{\tilde{B},\tilde{m}}(k) \right| = I + II.
\]
In order to estimate the first term note that \( \tilde{B} \subset B \) which implies \( W_{B,m} \geq W_{\tilde{B},m} \).
Consequently
\[
I \leq P(W_{B \setminus \tilde{B}, m} > 0) \leq P(\tau_{B \setminus \tilde{B}} < m) \leq m \mu(B \setminus \tilde{B}).
\]
For the second term we proceed as follows:
\[
II = P(\{W_{\tilde{B},m} = k\} \cap \{W_{\tilde{B},\tilde{m}} > k\}) \leq \mu(\tilde{B})(\tilde{m} - m) = m \mu(B \setminus \tilde{B}).
\]
Combining the estimates for \( I \) and \( II \) yields by Lemma 3
\[
\left| \Theta_{B,m}(k) - \Theta_{\tilde{B},\tilde{m}}(k) \right| \leq 2m \cdot \mu(B \setminus \tilde{B}) \leq 2m \cdot \mu(\tilde{B}) \leq 2m \cdot \vartheta_n(\epsilon) \mu(B) \leq 2t \vartheta_n(\epsilon) \rightarrow 0.
\]

Before we prove Theorem 5 let us consider the case of \( \alpha \)-mixing measures. As noted in [15] generalised SRB measures for systems that allow a Young tower construction as in [26, 27] are \( \alpha \)-mixing and thus are prime examples to which the following proposition can be applied. We though have to make an assumption on the short retum times.

Proposition 1. Let \( \mu \) be an \( \alpha \)-mixing measure where \( \alpha(k) \) is decreases exponentially fast to 0. Let \( \Delta = a \| \log \mu(B_{\epsilon,n}(x)) \| \) where \( a > 0 \) is so that \( \frac{\alpha(\Delta)}{\mu(B_{\epsilon,n}(x))} \Delta \rightarrow 0 \) as \( n \rightarrow \infty \). If \( P_{B_{\epsilon,n}(x)}(\tau_{B_{\epsilon,n}(x)} \leq \Delta) \Delta \rightarrow 0 \) then
\[
\lim_{n \rightarrow \infty} P(W_{B_{\epsilon,n}(x),m} = k) = e^{-t \frac{k}{k!}} - t \frac{k}{k!} \rightarrow 0.
\]
Proof. By Lemma 4 it is sufficient to prove that
\[
\lim_{n \rightarrow \infty} \Theta_{\tilde{B},\tilde{m}}(k) = e^{-t \frac{k}{k!}}.
\]
The result the follows from from Theorem 4 with \( m = 1/\mu(B_{\epsilon,n}(x)) \).

Let us now prove Theorem 5 where the \( \phi \)-mixing property is used to control the short return times up to \( \Delta \).
Proof of Theorem 3. Again, by Lemma 4 it is enough to show that \( \Theta_{\tilde{B}, m}(k) \to e^{-t} \frac{k^t}{k!} \) as \( n \to \infty \). We apply Theorem 1 of [13] to the set \( \tilde{B}_{\epsilon, n}(x) \in \sigma(A^{N(n)}) \) and obtain (for some \( c_1 \))

\[
|\Theta_{\tilde{B}, m}(k) - e^{-t} \frac{k^t}{k!}| \leq c_1 t(t \lor 1) \inf_{\Delta > 0} \{ \Delta \mu(\tilde{B}) + \sum_{j=\tau(\tilde{B})}^{\Delta} \delta_{\tilde{B}}(j) + \frac{\phi(\Delta)}{\mu(\tilde{B})} \} \log \mu(\tilde{B}),
\]

where \( \delta_{\tilde{B}}(j) = \min_{1 \leq \omega \leq j \land N(n)} \{ \mu(A(\tilde{B})) + \phi(j - \omega) \} \) and, as before, \( A(\tilde{B}) = \bigcup_{A \in A^\omega, A \cap \tilde{B} \neq \emptyset} A \).

Let \( \eta' \in (\frac{1}{2+\epsilon}, 1) \) so that the gaps \( \Delta = \mu(\tilde{B})^{-\eta'} \) are larger than \( N(n) \). Then

\[
|\Theta_{\tilde{B}, m}(k) - e^{-t} \frac{k^t}{k!}| \leq c_1 t(t \lor 1) \left( \mu(\tilde{B})^{1 - \eta'} + \sum_{j = \tau(\tilde{B})}^{\Delta} \delta_{\tilde{B}}(j) + \mu(\tilde{B})^{-1 + \eta'(2 + n)} \right) \log \mu(\tilde{B}).
\]

Since \( \mu(\tilde{B}) = O(\mu(B_{\epsilon, n}(x))) \) we conclude by \[6\] \( |\log \mu(\tilde{B})| = O(n) \) and it thus remains to show that \( \sum_{j = \tau(\tilde{B})}^{\Delta} \delta_{\tilde{B}}(j) = o(\frac{1}{n}) \).

Since \( \tilde{B} \subset B \) we get \( A(\tilde{B}) \subset A(B) \) and therefore \( A(B) \subset \tilde{B}_{\epsilon, n}(x) \cup \partial \tilde{B}_{\epsilon, n}(x) \) for all \( \omega \geq N(n) \). As in Lemma 1 let us put

\[
D_{N_0} = \{ x \in X : \frac{1}{n} \sum_{k=0}^{n-1} \chi_{U_n(A)}(T^k(x)) < \beta \ \forall n \geq N_0 \}.
\]

Then \( A_n(B_{\epsilon, n}(x)) \subset A_n(B_{\epsilon, n}(x)) \subset C_{\beta, n}(x) \) for all \( x \in D_{N_0} \) and \( \omega \geq n \geq N_0 \).

By Theorem 3 we can take \( N_0 \) large enough such that the set

\[
\{ x : \tau(B_{\epsilon, n}(x)) > \frac{n}{2} \ \forall n > N_0 \}
\]

has measure arbitrarily close to 1. Since \( \tilde{B}_{\epsilon, n}(x) \subset B_{\epsilon, n}(x) \) we conclude that

\[
E_{N_0} = \{ x : \tau(\tilde{B}_{\epsilon, n}(x)) > \frac{n}{2} \ \forall n > N_0 \}
\]

also has measure arbitrarily close to 1 for \( N_0 \) large enough. For \( x \in G_{N_0} = D_{N_0} \cap E_{N_0} \), and all \( n > 4N_0 \) we then split the following sum into three parts:

\[
\sum_{j = \tau(\tilde{B})}^{\Delta} \delta_{\tilde{B}}(j) = \sum_{j = \tau(\tilde{B})}^{\Delta} \min_{1 \leq \omega \leq j \land N(n)} \{ \mu(A(\tilde{B})) + \phi(j - \omega) \}
\]

\[
\leq \sum_{j = n/2}^{\Delta} \min_{1 \leq \omega \leq j \land N(n)} \{ \mu(A(\tilde{B})) + \phi(j - \omega) \}
\]
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\[
\sum_{j=n/2}^{2n-1} \min_{1 \leq \omega \leq j} \{ \mu(A_\omega(B)) + \phi(j - \omega) \} + \sum_{j=2n}^{N(n)} \min_{1 \leq \omega \leq j} \{ \mu(A_\omega(B)) + \phi(j - \omega) \}
\]

\[
+ \sum_{j=N(n)+1}^{\Delta} \min_{1 \leq \omega \leq N(n)} \{ \mu(A_\omega(B)) + \phi(j - \omega) \}
\]

\[= I + II + III.\]

Since \( \mu \) is \( \phi \)-mixing there exists a \( \nu < 1 \) so that \( \mu(A_m(x)) < \nu^m \) for all \( x \) and \( m \) large enough \([1]\). We now assume that \( \beta > 0 \) is small enough so that the size \( \lambda_m \) of the \( (\beta,m) \)-clusters \( \mathcal{C}_{\beta,m}(x) \) satisfies \( \lambda_m < \nu^\frac{m}{2} \) for all \( x \in D_{N_0} \) (see \([1]\)). Thus

\[
\mu(\mathcal{C}_{\beta,m}(x)) \leq \lambda_m \nu^m < \nu^\frac{m}{2}
\]

for all \( m \) large enough and \( x \in D_{N_0} \). We now estimate the three parts on the RHS above as follows:

(I) For the term \( I \), we also take \( \omega = \frac{j}{2} \). Since \( B_{e,n}(x) \subset B_{e,\frac{n}{4}}(x) \) and \( \frac{j}{2} \geq \frac{n}{4} \geq N_0 \) we have

\[
A_{\frac{j}{2}}(B_{e,n}(x)) \subset A_{\frac{j}{2}}(B_{e,\frac{n}{4}}(x)) \subset A_{\frac{j}{2}}(B_{e,\frac{n}{4}}(x)) \subset \mathcal{C}_{\beta,\frac{n}{4}}(x).
\]

The bound \([10]\) then yields

\[
I \leq \sum_{j=n/2}^{2n-1} \mu(A_{\frac{j}{2}}(B)) + \phi(\frac{j}{2}) \leq 2n \mu(\mathcal{C}_{\beta,\frac{n}{4}}(x)) + \frac{c_2}{n^{1+\kappa}} = o\left(\frac{1}{n}\right).
\]

(II) For the second term we take \( \omega = \frac{j}{2} \) and obtain

\[
II \leq \sum_{j=2n}^{N(n)} \mu(A_{j/2}(B)) + \phi(\frac{j}{2}) \leq \sum_{j=2n}^{N(n)} \mu(\mathcal{C}_{\beta,\frac{j}{2}}(x)) + \frac{c_1}{n^{1+\kappa}}
\]

since \( \frac{j}{2} \geq n > N_0 \). By \([10]\) we conclude that \( II = o\left(\frac{1}{n}\right) \).

(III) For the third term \( III \) we take \( \omega = \frac{N(n)}{2} \). Lemma \([3]\) shows that \( \mu(A_{N(n)/2}(B)) = O(1)\mu(B) \). We obtain

\[
III \leq \sum_{j=N(n)+1}^{\Delta} \left( \mu(A_{N(n)/2}(B)) + \phi(j - \frac{N(n)}{2}) \right)
\]

\[
\leq \sum_{j=N(n)+1}^{\Delta} O(1)\mu(\tilde{B}) + \frac{c_2}{N(n)^{1+\kappa}}
\]

\[= O(1)\Delta \mu(\tilde{B}) + \frac{c_2}{N(n)^{1+\kappa}}.\]
\[ = o\left(\frac{1}{n}\right). \]

The three estimates combined prove Theorem 5.

To prove Theorem 1 and 2, we need to verify that (9) is satisfied.

**Proof of Theorem 1.** Under the hypothesis of Theorem 1, we take \( \eta \in \left(\frac{1}{\xi}, 1\right) \) and put \( N(n) = \mu(B_{e,n}(x))^{-\eta} \). This yields

\[
\frac{n \cdot \psi(\epsilon, \gamma N(n) - k, T^k x)}{\mu(B_{e,n}(x))} \leq \frac{nC_{\epsilon}}{N(n)^{\xi \zeta} \log \gamma^{\xi \zeta} \mu(B_{e,n}(x))} = C'_{\epsilon} \mu(B_{e,n}(x))^{\xi \zeta - 1} \rightarrow 0
\]

since \( \eta \xi \zeta > 1 \). Consequently \( \vartheta_n(\epsilon) \rightarrow 0 \) as \( n \rightarrow \infty \) for every small enough \( \epsilon > 0 \) and the statement of Theorem 1 now follows from Theorem 5.

**Proof of Theorem 2.** Similarly, the choice of \( \eta \in \left(\frac{1}{\alpha \xi}, 1\right) \) and \( N(n) = \mu(B_{e,n}(x))^{-\eta} \) yield

\[
\frac{n \cdot \psi(\epsilon, \gamma N(n) - k, T^k x)}{\mu(B_{e,n}(x))} \leq \frac{nC_{\epsilon} N(n)^{-\alpha \xi}}{\mu(B_{e,n}(x))} = C'_{\epsilon} \mu(B_{e,n}(x))^{\xi \alpha - 1} \rightarrow 0
\]

since \( \eta \alpha \xi > 1 \). Again \( \vartheta_n(\epsilon) \rightarrow 0 \) as \( n \rightarrow \infty \) for every small enough \( \epsilon > 0 \) and the theorem follows from Theorem 5.

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