Mining Frequent Sequential Rules with An Efficient Parallel Algorithm

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Abstract: Sequential rule mining is one of the most common data mining techniques. It intends to find desired rules in large sequence databases. It can decide the essential information that helps acquire knowledge from large search spaces and select curiously rules from sequence databases. The key challenge is to avoid wasting time, which is particularly difficult in large sequence databases. This paper studies the mining rules from two representations of sequential patterns to have compact databases without affecting the final result. In addition, execute a parallel approach by utilizing multi core processor architecture for mining non-redundant sequential rules. Also, perform pruning techniques to enhance the efficiency of the generated rules. The evaluation of the proposed algorithm was accomplished by comparing it with another non-redundant sequential rule algorithm called Non-Redundant with Dynamic Bit Vector (NRD-DBV). Both algorithms were performed on four real datasets with different characteristics. Our experiments show the performance of the proposed algorithm in terms of execution time and computational cost. It achieves the highest efficiency, especially for large datasets and with low values of minimum support, as it takes approximately half the time consumed by the compared algorithm.

Keyword: Non-redundant rule, multi-core processors, dynamic bit vector, closed sequential patterns, sequential generator pattern.

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1. Introduction

Pattern mining is a data mining technique that includes two subsections called itemset mining and Sequential Pattern Mining (SPM). The extraction of frequent sequences from large datasets is known as SPM. It has only one measure named minimum Support (minSup) that calculates existence items in sequence databases. It may be deceptive and insufficient to make a prediction.

Sequential Rule Mining (SRM) is proposed as a solution to the limitation of SPM. It takes into account another measure called; minimum confidence (minConf) that calculates the expectation of the following pattern. It aids in predicting situations by identifying relationships between sequential items occurrences. The mining process consists of two stages: first, mining frequent sequential patterns Fournier-Viger et al. [4]. Second, produce sequential rules which depend on the first phase. So, many researchers concentrate on enhancing the efficiency of mining sequential patterns Upadhyay et al. [26]. There are three concise representations for mining sequential patterns; Closed Sequential Patterns (CSP), Sequence Generator Patterns (SGP), and maximal sequential patterns. Most recent enhanced algorithms intend to discover non-redundant sequential rules based on only one representation. This method depends on data structure with many tasks implementing the same process. It suffers from consuming time and causes CPU idle, especially with low values of minSup. However, generating sequential rules based on compact information to reduce the time required for generating the rules as in closed sequential patterns requires expensive computations on cost and time. As a result, an enhanced algorithm for mining rules is required, particularly for large databases and with low values of minSup.

Utilizing two types of patterns concise (CSP and SGP) can resolve previous obstacles of producing many candidates. First, it can reduce the search space with the lowest values of minSup. Second, it can assist users analyze the sequences in large datasets efficiently.

Another aspect of improving the efficiency of sequential rules is using a parallel approach. One method to perform this approach is a multi-core processor. It can increase performance by applying many tasks simultaneously. So that large datasets can be analyzed in a reasonable time.

In this paper, we propose an enhanced algorithm for mining non-redundant sequential rules as follows:

- Performing sequential pattern mining based on blinding closed with sequential generator patterns in the same procedure. It aids in acquiring more information with a more compact database than
mining the complete set of sequential patterns.

- Multi core processor architecture is performed on only two procedures of the proposed algorithm to achieve the highest possible efficiency.

The rest of this paper is organized as follows: Section 2 introduces the definition of the problem and related work. Section 3 shows the data structure in a parallel approach. Section 4 represents the proposed algorithm. Section 5 discusses the experimental results. The conclusions are presented in section 6. Finally, recommendations and future works are summarized in section 7.

2. Background

2.1. Problem Definition

Suppose I={i_1, i_2, ..., i_n} is a collection of n distinct items, and I_j are items or events where 1 ≤ j ≤ n. An itemset X is a set of unordered items that are represented with brackets. Such as (AC) indicates an itemset with two items ‘A’ and ‘C’. A sequence includes an ordered itemset denoted S = {I_1, I_2, ..., I_m} where I_j is an itemset and 1 ≤ j ≤ m. The number of events in a sequence named the sequence length. The frequent first sequence refers to F1-S; for example, the sample sequence database in Figure 1.

- **Definition 1**: (prefix and postfix), set two sequences s_j=<y_1, y_2, ..., y_m> and s_k=<z_1, z_2, ..., z_m>, (m≤n). The sequence s_j is a prefix of s_k if only z=y for (1 ≤ i ≤ m). We indicate s_j as a subsequence of s_y, and s_y refers to the super sequence of s_j as s_j⊂s_y.

- **Definition 2**: (substring of length), suppose s_y is a sequence and sub n, m(s_y), (n≤m) refer to the portion from locus n to locus m of s_y. Substring of length calculated as (m-n+1). For example, sub3,5 of (〈AB(AC)D〉) is (〈AC)D〉.

- **Definition 3**: (frequent sequence), a support measure is the number of included items in a database divided by [DB]. Frequent sequences are composed of sequence items that satisfy the minimum support threshold (minSup) and are referred to as sup (S_y) ≥ minSup. When given a minimum support threshold, the main challenge is to find the complete set of frequent subsequences.

- **Definition 4**: (frequently closed sequence), respect two frequent sequential patterns; s_y and s_z. Frequent Closed Sequential Patterns (FCSP) indicate that no s_z such that s_z⊂s_y ∧ sup(s_z) = sub (s_z), s_y. FCSP is more compressed than mining the whole set of sequential patterns. It keeps information fully extracted without affecting the results. If the subsequence (s_y) has the same support value of the super sequence (s_z); (s_y) will be ingested by (s_z).

- **Definition 5**: (frequent generator patterns) if there is no subsequence s_y with the same support of the s_z; this called Frequent Sequential Generator Patterns (FSGP). FGSP is shorter than FCSP and indulgent to the noise produced in training data. It has more accuracy for the classification of the sequence.

- **Definition 6**: (combine FCSP with FGSP), based on definitions 4 and 5, it takes advantage of fetching additional information. The FCSP can’t produce alone non-redundant sequential rules with higher accuracy.

- **Definition 7**: (sequential rule and frequent sequential rules) suppose r is a sequential rule in the form x→y, which states that if x happens, y will obey. Consider x, y are frequent sequences, and r has two measures (Sup,Conf). The support value is referred to as (minSup) that equals sup(X+Y), where the confidence value is indicated as (minConf) that regards the probability of the following patterns and equal to sup(X+Y)/sup(X). A rule that achieved a minSup threshold is named a frequent sequential rule. While, the rule that reached a min Conf value is a strong sequential rule.

- **Definition 8**: (redundant rule and non-redundant rule), if a rule can be deduced by another rule, it regards a redundant rule. For example, suppose two rules r_1: <B>-< (AC) CD> and r_2: <B>-<CD>. So, r_2 is a redundant rule if it is included in r_1 and has the same support as r_1. Otherwise, a rule is non-redundant if x+yEFCS and x∈k’ such as k∈k’ (k’) =sup (k) referred to as a prefixed generator.

![Sample sequence database.](image)

2.2. Related Work

Sequential Pattern Mining is a significant phase for producing sequential rules. It is proposed by Ravikumar et al. [20] within the Apriori All technique. The purpose of this phase is to discover all sets of patterns from large search spaces. It includes two principal processes called s-extension and i-extension that are needed for growing the patterns.

The GSP algorithm appeared to solve the database's multiple scans problem that caused complex computations in cost and time. It is determined by the horizontal database and the downward closure property. Titarenko et al. [25]. Many database searches, non-existent candidates, and holding candidates in memory are just some of the drawbacks. As a result, the depth-first search algorithms have been developed (vertical format). As an example, Spade Zaki [33], Prefix Span Mollenhauer et al. [15], Spam Wang and Cao [29], LapinSpam Alja’am et al. [1]. CM- Spam, and CM-Spade Naseer and Malsoru [16]. The algorithms can
increase the mining performance by searching the database once and calculating the pattern's support quickly. There are also various short representations of producing sequential patterns with higher precision and less time required than mining all sequential patterns Fournier-Viger, et al. [4]. Closed sequential patterns are one of these representations. It is compact with fully extracted information.

A sequential generator pattern is the other succinct representation. It's more tolerant regarding the noise in candidate patterns. Gen Miner Wu et al. [30], FSGP Muklash et al. [15], and VGEN Husák et al. [8]. Closed patterns are associated with generator patterns to generate a sequential rule that provides more detail than closed patterns alone Guyet [7]. However, still consumes time in building the candidate patterns.

Mining non-redundant sequential rules, such as CNR, Patel and Malviya [17] Spiliopoulou [21] is also more efficient than mining sequential rules. Several researchers have improved SRM algorithms by relying on the prefix tree to enhance their efficiency. They reducing search space as included in MNSR and IMSR pre-Tree. However still suffer from efficiency regarding the consuming time Pham et al. [19] and Van et al. [27] particularly for large databases. There were two directions for most researchers to improve sequential rule mining algorithms. The first direction is using the set of procedures that deletes un-candidate patterns from the beginning, thus enhancing the efficiency of the generated rules and improving memory usage. However, it was going through many steps, leading to an increase in the required time. The second direction is appending an additional constraint for producing an extension of the previous algorithm, as it is in the TRuleGrowth algorithm. It considers window size parameters to control the maximum number of the generated rules, but it proved limited efficiency with the large datasets Youssef et al. [32].

Numerous researchers fixed this problem by using a parallel technique to minimize the processor's execution time. Pspade Zhou et al. [34], PHUSP Zihayat et al. [35], and other distributed memory-based parallel algorithms have appeared. In addition, use a parallel approach in generating sequential pattern mining to reduce run time and memory consumption, but it has limitations by causing data corruption and overheating Huynh et al. [10].

The multicore processor has emerged as a result of enormous developments in modern processor engineering, and it has proven to be effective in improving performance. It allows several tasks completed at the same time Jamsheela and Gopalakrishna [11], Huynh et al. [9] Parallel algorithms have been used to solve several problems, including improving load balancing and achieving lock-free parallelism Le et al. [13]. Various researches have been proposed for improving association rule mining algorithms using a multitasking approach to avoid time-consuming, but they are still mining all patterns in the sequence database TAŞER et al. [24] Suresh Kumar and Thangamani [22], Kuriakose and Nedunchezhian [12].

Although these algorithms outperform serial algorithms efficiently, they require a lot of memory and go through multiple phases to construct the data structure. There is no previous research that concentrated on generating sequential rules and improving sequential pattern mining simultaneously. The mining process passes through many tasks executes the same processes that consume time and using a lot of memory. There is a constant needed to gain knowledge, predict patterns, and discover sequential rules in a reasonable time. Enhancing the efficiency of the sequential rule mining algorithms is one solution for this challenge.

3. Data Structure for Parallel Mining NRD-Rules

3.1. Architecture of Multi-Core Processor

Large datasets are searched in a short amount of time using a parallel mining method. A multi-core processor is one way to implement this strategy. On a single chip, it has several processor cores. It can improve productivity by doing several tasks at once.

Two or more autonomous cores are located in the same physical package in a multi-core processor Upadhyay et al. [26] Czarnul et al. [2]. As seen in Figure 2, each processor core has its memory and shares the main memory.

![Quad-core processor diagram](image)

Figure 2. Quad-core processor diagram.

Each core has its L1, and L2 cache, with a single L3 cache for all cores. The highest resource use is accomplished by sharing more resources between cores. The data duplication is decreased through the shared cache. As a result, communications will be more efficient. We can implement it through the multiproccessing package in a python that performs multiple tasks simultaneously on a multi-core CPU. There are four modules included in Python for achieving parallelization. The first module is the threading module that suitable for I/O operations.
When a processor is waiting for the data from remote resources, it is in idle mode. It performs inefficiently for basic tasks. It increases the complexity degree of the program, and causes overhead during managing threads. Second, is utilizing the system method in the OS module. It allows the external command-line programs to run in a separate process. It causes overhead and makes it much more expensive than others. Third, the subprocess module that is depending on facilitates spawning processes. It connects them through signals and gathers the produced output with their fault message. It doesn’t protect operations from the fault message. Fourth, the multiprocessing package can perform parallel execution through processes, pools, queues, and pipes. It provides both local and remote synchronization. It can effectively lock the global interpreter by using subprocess rather than threads.

The current study proposes apNRD-CloGen algorithm for parallel mining to enhance the execution time based on the multi-core processor. Utilizing the multiprocessing module with Pool class has the advantage of controls the execution of processes. It supports either synchronous or asynchronous parallel implementation. Figure 3 shows the applied method for the proposed parallel algorithm.

![Parallel approach for a proposed PNRD-CloGen algorithm.](image)

3.2. Generators with Closed-DBV Patterns

3.2.1. Closed-DBV Patterns

Closed sequential pattern algorithms that rely on a vertical format are more efficient than those dependent on a horizontal data format Gan et al. [5]. It has a significant advantage in that it scans the database only once and speedily calculates the support count of sequences. Those formats store additional information. So, it demands a great deal of memory.

A bit vector solves this problem that represents itemsets as several transactions Xie and Tan [31]. However, it has an obstacle that increases the required memory and execution time because depending on a fixed size. The size depends on the appearance of each item that is expressed by ‘1’ otherwise ‘0’. To overcome this problem, they proposed a Dynamic Bit Vector (DBV). After clearing the ‘0’ bits at the beginning and end of the vector, it generates a bit vector. It improves efficiency for item sets with many ‘0’ bits Tang et al. [23] Gokulapriya and Kumar [6] Consider the case where the sequence database has 16 transactions. It denotes the presence of two things, one with a ‘1’ and the other with a ‘0’. As seen in Figure 4, the bit vector takes 16 bytes to store this operation, while DBV only considers the start of the index and the series from the first to the last ‘1’. The proposed algorithm uses the DBV structure to save sequences in vertical format. It facilitates the computations of sequence support. By combining the location of two items concerning the position of each item, it performs well in the ANDING operation. It provides a more accurate result. When performing the ANDING operation of item <C> to obtain <CB>, the result of DBV only is (111). When we consider the structure of DBV, terms of position, it is clear that it does not include the <CB>, and the correct result is (00000). The ANDING method should produce the precise outcome, which is (111) for <BC>. For example in Figure 1, item <B> in sequence database that existence in sequences 1, 2, and 3. The bit vector for <B> is (1,1,0,0,0) that the first appearance of item <B> in sequence 1 in the second and third position denoted as 2: {2,3}. Figure 5 represents the DBV structure of item <B>.

![Example of bit vector.](image)

![DBV structure for item <B>.](image)

3.2.2. Generators Patterns

Sequential generator patterns are more compressed than closed sequential patterns. Numerous algorithms are proposed, such as the GenMiner algorithm. It has three-phases; compact /generate/ and filter Veroneze et al. [28]. The FEAT Mukhlash et al. [15] and Mollenhauer and Atzmueller [14] algorithm that relies on growth with forward and backward pruning techniques helps speed up the mining process. Mining Sequential Generator Patterns (MSGPs) Wu et al. [30] algorithm depends on sequential generator patterns feature and sequence extensions to discover all
generator patterns Upadhyay et al. [26]. Generator patterns are the prioritized representation of the classes in classification and model selection.

3.2.3. Blend Sequential Closed with Generator Patterns

Using closed with sequential generator patterns can add more information than closed alone can’t be provided. It can generate non-redundant rules with a high degree of Precision.

CSGM method is used to mine both patterns simultaneously, but it consumes much time to form databases Pham et al. [18]. So we propose the pNRD-CloGen algorithm to mine both type of sequential patterns and prove the higher performance in runtime.

4. The Proposed Algorithm

The proposed parallel NRD-CloGen (pNRD-CloGen) algorithm is described in this section. It performs in a parallel approach and depends on mining patterns from two concise representations. The first representation is frequent closed sequential patterns that use DBV data structure. The second representation is sequential generator patterns.

In the parallel mining approach, each branch in the prefix tree is distributed as a single task. Each node is dealt with as a separate task, and the total computations can perform in a parallel approach. Then, tasks are distributed within the available processor cores and independently handled to generate pNRD-CloGen rules.

The pNRD-CloGen algorithm consists of six steps:

1. Converting sequence dataset to DBV structure. Producing the first frequent sequence and assigning them in a prefix tree.
2. Utilizing a parallel approach for generated sequential patterns.
3. Pruning the prefix generator.
4. Sequence extension.
5. Generating pNRD-CloGen rules as shown in Figure 6.

The pseudo-code of the pNRD-CloGen algorithm is shown in Algorithm (1). The DB is scanned to create the list of items. Next, discovers all Frequent First Sequences (F1-S) that achieve the minSup threshold. The items in F1-S are set as child nodes in the prefix tree. Then, pNRD-CloGen creates new tasks for each node of the root. Each task implements the method CloGen-extension.

Algorithm 1: NRD-pCloGen algorithm

Input: SDB, minSup, minConf
Result: NRD-SR
1 Scan DB to create an ID list of items.
2 Calculate DB length & set the 3 minSup value
4 Find F1-S >= minSup
5 Establish DBV structure in a dictionary to have 6 the positions of each item
7 Add F1-S as child nodes, where node = null
8 For each node do 9 Create a new task, then call pCloGen-extension.
11 Set minConf & generate NRD-SR

Consider the database in Figure 1, and set minSup equal to 0.5. The following procedure is executed to find the F1-S, as F1 = {a:5, b:3, c:5}. The procedure that extends the F1-S is shown in Algorithm (2), named CloGen pattern-Extension. This procedure sets the F1-S as child nodes in the prefix tree.

We apply the pruning technique in a parallel approach to eliminate candidates that cannot extend frequent patterns. For example, consider the DB in Figure 1. It is not required to extend prefix ‘B’, as there is an item ‘A’ which has (start position=1) that usually occurs before an item ‘B’ which has (start position=2). The prefix ‘A’ extension already has ‘B’ with the same support. So, ‘B’ will be absorbed. After that, the CloGen pattern extension procedure extends patterns by rendering sequence extension to produce new sequential patterns through a parallel approach.

Algorithm 2: CloGen pattern-Extension

Input: nodes in prefix tree and minSup
Output: set of frequent CloGen patterns
12 set listNode as child nodes
13 For each SP in listNode do
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14 If SP is pruned then
15 set SP as SP node
16 set Spa as SP child node
17 If (sup (Spa)≥minSup) then
18 Add Spa as child node of SP
19 check and set the attribute of SP
20 (closed or prefixed generator)

Algorithm 3. pCloGen algorithm
Input: nodes, F1-S, MinSup
Output: all child nodes ready to generate rules
22 Set process equal to CPUs as pool
23 Set parameters of listNode as Childs
24 Get child node by star-map () in pool

The parallel approach is implemented in python using the multiprocessing package. The package executes many tasks simultaneously depends on Central Processing Unit (CPU) cores. It utilizes a Pool object to perform many tasks and passes them to the Pool object. Starmap () function. This function can accept multiple arguments. So, the user can overcome multiple assumptions of one item having in the list, as seen in Algorithm (3).

After discovering all frequent CloGen patterns, the algorithm initializes to generate all NRD sequential rules, as shown in Algorithm (4). This algorithm produces all rules through a sub-tree. Each child node may be a prefix or closed. The prefix is pre and closed as post of the rule. It performs recursively in parallel until child nodes don’t achieve the minConf value.

Algorithm 4: Generate pNRD-CloGen Rule
Input: root, minConf
Output: pNRD-CloGen Rule
25 Set prefix as a sequence of the root
26 Set sub-node as child node
27 For SP node in the root
28 Search prefix (SP node, rules, minConf)
29 If a node is a prefix
30 Search closed (value of a node, nod,
31 rules, minConf)
32 For a child of a children node
33 search prefix (child, rules,
34 minConf)
35 If a sequence is closed
36 Conf= Sup of seq (Sup)/pre(Sup)
37 If Conf ≥ minConf
38 Set rules = anterior posterior
39 Append the rule
40 Else stop producing rules
41 End if
42 End for
43 Call generate NRD-CloGen Rule
44 End for

5. Experimental Results

5.1. Experiments on a Sample Dataset

We assess the reliability of coding the proposed algorithm in python by using sample data. A sample data set includes 30 transactions with five consumer behavior items that include the purchase of various items. We performed it and have the result manually, then compared the results with the results of the python code. It has proved the validity of the code the emergence of the same results. Set the minSup=0.5 and minConf=0.5, Figure 7 shows the phases of implementing the algorithm. As shown in Figure 8, the tested code prints the number of transactions, objects, the F1-S count, and the CloGen patterns in the tree, generated sequential rules, and the spending time for each operation.

| ID | Sequence   | F1-Seq | Support |
|----|------------|--------|---------|
| 1  | {A, C, D}  | 1      | 0.7     |
| 2  | {B, C, E}  | 1.4    | 0.5     |
| 3  | {B, C, D, E} | 3      | 0.66    |
| 4  | {B, C, E}  | 4      | 0.63    |
|    |            | 2      | 0.63    |

![Figure 7. Sample execution of the NRD-DBV algorithm.](image)

Figure 7. Sample execution of the NRD-DBV algorithm.

**rules**

```
F1-S count, and the CloGen patterns in the tree, generated sequential rules, and the spending time for each operation.
```

C:\Users\admin\AppData\Local\Programs\Python\Python38-32\python.exe D:\seq_memory/seq-rule/main.py
sample-1.1.txt
** frequent 1-sequences count: 4
** closed sequences:
None
# [1], sup:21.0000
# [1, 4], sup:15.0000
# [3], sup:20.0000
# [4], sup:19.0000
# [2], sup:19.0000
** rules:
[1] -> [4], conf:0.71
# memory peak: 34085 Byte
```

Figure 8. Executed code of sample dataset.

5.2. Experiments on a Real Datasets

We evaluated the proposed algorithm by comparing it with the Non-Redundant with Dynamic Bit Vector (NRD-DBV) algorithm. The algorithms are run on a Windows 7 laptop with an Intel Core i5 2.33GHz processor and 6.58 GB of free RAM. They were implemented in python and run on Jet Brains Pycharm.

Four real datasets with different sizes and features are utilized to assess the performance of the algorithm. The first dataset is named BMSWebView1 (Gazelle), which contains 59601 sequences of click stream data included in an e-commerce website. The second data set called the Sign refers to, sign language utterance. It has 800 sequences transmit from videos and embedded 267 distinct items. The third dataset is
named Korsarak, a large dataset containing 990,000 sequences of click-stream data from an online news portal. The fourth dataset, MSNBC, is huge which has over 1 million transactions. All used datasets are downloaded from SPMF Fournier-Viger et al. [3].

The experiments were applied to compare the runtime of the two algorithms for various minSup values. For this experiment, the minConf value was set to 0.5 % for all states. The parameters’ values were calculated after a variety of preliminary tests to achieve the highest efficiency.

5.2.1. Runtime on a Gazelle Dataset

In the Gazelle dataset, items didn’t iterate multiple times very often. So, we set a lower minSup to get the sequential rules. That means when setting minSup value as included in other experiments; we didn’t have any sequential rules during the mining process. In general, the runtime increases with low minSup values that lead to an increased number of generated rules. Experience shows that the proposed pNRD-CloGen algorithm takes much less time than the NRD-DBV algorithm. When the minSup is set to low values, it has proven to be effective, as the time to generate sequential rules is roughly half that of the NRD-DBV, as shown in Figure 9.

![Figure 9. Runtime of Gazelle dataset.](image)

5.2.2. Runtime on a Sign Dataset

The sign dataset has a variety of characteristics, including sparse, dense, having short and long sequences. It has an average sequence length of 51.997, while the Gazelle dataset has an average of 2.24. These features, related to its small size, allowed the algorithm to generate rules in a fraction of the time it took the Gazelle dataset. In both algorithms, runtime convergence occurs at low minSup values. When setting minSup with the lowest values, the pNRD-CloGen algorithm took less time to reach the highest performance.

As a result, it takes five times as long as the NRD-DBV algorithm. Figure 10, shows that when minSup is set to 0.1, pNRD-CloGen takes 105.6 (s) to complete, while NRD-DBV takes 514.3 (s).

![Figure 10. Runtime of sign dataset.](image)

5.2.3. Runtime on a Korsarak Dataset

Unlike the Gazelle database, both algorithms didn’t generate any rules with low values of min Sup because of the features of a korsarak dataset. Korsarak dataset has an item count of 41, 270 items and an average length equal to 8.1, and the Gazelle dataset has 497 items and 2.24 of average sequence length. The pNRD-CloGen achieved better performance with minimum values of minSup. The execution time required for generating the rules increases with the decreasing minSup values. This is because of increasing the computations for finding increased number of non-redundant sequential rules from a large search space area. The execution time between the two algorithms is approximated when setting high values to the minSup, but the pNRD-CloGen still consumes less time than the NRD-DBV algorithm, as shown in Figure 11.

![Figure 11. Runtime of korsarak dataset.](image)

5.2.4. Runtime on a MSNBC Dataset

This dataset is a massive collection of click-stream data from the MSNBC website. It is a discrete sequence and very dense dataset. The proposed algorithm generated the sequential rules in the shortest amount of time. In terms of time consumption, the proposed algorithm, pNRD-CloGen, was achieved the most effective performance as shown in Figure 12.
In terms of memory usage, the NRD-DBV algorithm uses less memory than the pNRD-CloGen algorithm on all databases, as shown in Figures 13, 14, 15, and 16. Both algorithms, however, used the same method to store the sequences, with the pNRD-CloGen algorithm requiring more memory due to the parallel technique. It breaks down multiple tasks into smaller chunks and processes each one separately. As a result, more memory is needed to save the data.

Since there were fewer produced rules when the value of minSup was increased, memory consumption and runtime decreased. The proposed pNRD-CloGen algorithm has a significant advantage in that it makes a parallel approach only on two procedures. First, find F1-S and add them as child nodes in a prefix tree. Second, check all nodes whether, prefix or closed, to generate the sequential rules, so helps in minimizing the CPU idle time.

5.2.5. Measuring the Computational Cost

We measure the computational cost to evaluate the performance of the proposed algorithm. Producing non-redundant rules has a complexity of $O(n^c)$, where ‘n’ is the number of nodes and ‘c’ is the average number of child nodes. We must apply (n-1) operations for testing and generating sequential rules such as $k<<n$ for each sequence. As a result, pNRD-CloGen has a complexity equal to $O \approx (n)$. It implies the algorithm’s supreme running time is proportionate to the input size. It is the second-best state of big $O$ notation after the constant state, so the proposed algorithm proves its efficiency.

5.2.6. Measuring the Scalability

Scalability measures the system's capacity to raise or reduce its performance and cost in reply to changes in system processing requirements. We can analyze the scalability of a system by assessing how its performance diversifies as a function of the input size.
growth. We examined the scalability of the two compared algorithms on the MSNBC dataset for various data sizes and a fixed value of minSup equal to 0.03. The analysis shows the influence of generating rules on runtime. The results proved that the pNRD-CloGen algorithm achieved better scalability than the NRD-DBV algorithm, as shown in Figure 17.

![Figure 17. Scalability of compared algorithms for various dataset sizes with minSup=0.03.](image)

**6. Conclusions**

Most algorithms mining sequential rules through only one representation like closed, generator, or maximal are time-consuming. The data structure goes through many steps that follow the same process. In this study, the proposed pNRD-CloGen algorithm is applied on four real datasets with different characteristics: sparse, dense, large, and very large datasets. We utilized a dynamic bit vector structure with a prefix tree to store frequent patterns. Also, pruning techniques are applied to remove uninteresting sequences early. In addition, a parallel approach is implemented on only two processes to acquire the highest efficiency. The first process of the parallel approach is the extension method. The second process is to test all nodes to generate sequential rules. The proposed algorithm proved its efficiency in saving time the approximately half time required from the compared algorithm, especially for large datasets and low values of minSup.

**7. Recommendations and Future Works**

The researcher deduced that not time-saving when implementing the parallel approach to the overall processes of the pNRD-CloGen algorithm. The best uses of the parallel technique are to test the child nodes that achieved the minSup and check each pattern, whether generator or closed pattern, to produce the non-redundant sequential rules.

There is no need to utilize DBV then DBV structure as applied in the NRD-DBV algorithm. It will take extra time. Using the DBV structure is sufficient and more accurate for generating valid rules with actual positions of items.

The use of processes instead of threads provides better memory utilization when memory goes down. The multiprocessing approach prevents data corruption and deadlocks that may appear with a multithreading approach.

The pNRD-DBV algorithm helps in detecting errors, intervening, and detecting bugs in much less time. It is necessary in areas that ordering sequences are needed, such as the therapeutic region (in the case of suffering from a fever). The order of symptoms is decreasing in coagulation levels, appearance a red color on the body. The fact that the quiet will cure dengue fever is tolerable. This timing structure is critical in predicting the right kind of treatment.

For future works, we suggest implementing a maximal patterns mining instead of mining closed generator patterns. Also, try to study the impact on produced sequential rules in terms of the runtime, and the accuracy of rules. Additionally, increasing the number of cores, especially for large data bases and studying the performance. We hope to avoid the increase of the power consumption by increasing the clock frequency, which helps to eliminate overheating.

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