Self-tuned criticality: Controlling a neuron near its bifurcation point via temporal correlations

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Previous work showed that the collective activity of large neuronal networks can be tamed to remain near its critical point by a feedback control that maximizes the temporal correlations of the mean-field fluctuations. Since such correlations behave similarly near instabilities across nonlinear dynamical systems, it is expected that the principle should control also low-dimensional dynamical systems exhibiting continuous or discontinuous bifurcations from fixed points to limit cycles. Here we present numerical evidence that the dynamics of a single neuron can be controlled in the vicinity of its bifurcation point. The approach is tested in two models: a two-dimensional generic excitable map and the paradigmatic FitzHugh-Nagumo neuron model. The results show that in both cases, the system can be self-tuned to its bifurcation point by modifying the control parameter according to the first coefficient of the autocorrelation function.

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I. INTRODUCTION

Experimental evidence [1,2], as well as theoretical developments [3–5], suggest that the highly variable spontaneous activity of neuronal networks corresponds to critical phenomena. Current efforts are dedicated to better understanding the behavior of neurons and networks near that critical region. To track this transition, the divergence of the fluctuations (e.g., susceptibility) of the order parameter often is used [6]. Alternatively, in Ref. [7] the autocorrelation coefficient of the order parameter, which peaks at the critical point [8] more smoothly than the susceptibility, was used to control the system near the transition. In this work, we extend this control strategy to a much simpler scenario, namely, a generic excitable dynamic modeled by low-dimensional systems.

The two models selected in the present work belong to a large variety of attempts made to describe the activity of single neurons [9]. From intricate and realistic ionic models [10] to simpler ones, all aim to reproduce the physiological states of neurons in terms of their electrical properties to understand and predict their behavior in response to perturbations. Here we limit ourselves to exploring two models: the first one is a two-dimensional difference equation (so-called Chialvo map), proposed for simulating generic neural dynamics [11]. The second one is a differential equation, the FitzHugh-Nagumo system (FHN) [12–14]. The behavior in parameter space of both models is very well known; they exhibit bifurcations from fixed points to limit cycles and to more complex behavior, such as chaotic bursting, as their parameters are varied. Both have an activation (potential-like) variable and a recovery-like variable.

Previous work has shown the possibility of shifting the system to the critical point employing a feedback mechanism [7]. This method uses the first coefficient of the standard temporal autocorrelation function to modify the control parameter, driving and maintaining the system near the critical point. Low-dimensional models mentioned above are known to exhibit a bifurcation rather than a phase transition. In this case, a vanishing small noise and a constant additive term over the activation variable allow one to estimate the typical slowing down of the dynamic and thus allowing the control of the system in the vicinity of its bifurcation point.

The article is organized as follows: In the next section II we demonstrate the control mechanism in the Chialvo neuron map under two of its regimes: the excitable and the chaotic dynamics. Next, the same procedure demonstrates the control of the excitable regime in the FitzHugh-Nagumo system. We close with a brief comment on the relevance of our results.

II. THE CHIALVO MAP

In physics, the use of maps (i.e., difference equations), instead of differential equations, was championed by Kaneko decades ago [15,16] when he argued that a great variety of complex spatiotemporal phenomenology was not dependent on the precise and detailed account of the local dynamics but rather on the interaction of a large number of nonlinear degrees of freedoms. The approach, known as coupled-map lattices, was used since then to study a variety of complex phenomena [17,18]. It was natural to attempt the modeling
of neuronal activity with maps, because the approach may provide a simple analytical framework to study its bifurcations and chaotic orbits, exact solutions, etc., and at the same time considerably speed up the computations of large neuronal networks. One of the first models, introduced by Chialvo [11] two decades ago, is a two-dimensional map capturing the most generic excitable dynamic including relevant physiological properties, e.g., the behavior of the resting and the membrane action potential, its refractory period, and the periodic oscillations under constant bias input that may bifurcate to chaotic solutions (see reviews of similar approaches in Refs. [19–22]). The model is a two-dimensional difference equation

\[ x_{n+1} = f(x_n, y_n) = x_n^2 \exp(y_n - x_n) + k, \]
\[ y_{n+1} = g(x_n, y_n) = ay_n - bx_n + c, \]

in which \( n \) is an iteration step, \( x \) represents the activation variable, \( y \) acts as a recovery-like variable, \( a \) is the time constant of the recovery (\( a < 1 \)) variable, \( b \) is the activation dependence of the recovery process (\( b < 1 \)), and \( c \) is a constant which sets the fixed point of the recovery variable. The parameter \( k \) can represent a constant bias or a time-dependent additive perturbation and will act as the control parameter. A compact view of the asymptotic behavior of any initial condition can be represented by the vector field in the phase plane of the \( x \) and \( y \) nullclines of the map, which are

\[ x_f = x_f^2 \exp(y_f - x_f) + k, \]
\[ y_f = \frac{c - bx_f}{1 - a}. \]

The control strategy discussed here relies on the behavior of the system’s fluctuations near instabilities. Near such points, the amplitude of the fluctuations typically increases, and its temporal correlations slow down [23]. Because we consider here a deterministic single neuron model by itself devoid of any fluctuation, it becomes necessary to add a vanishing small Gaussian noise term to the activation variable. When the system is far from the bifurcation point, these perturbations will decay fast, resulting in a relatively low autocorrelation value. Conversely, as the system moves to the unstable regime, there is the typical critical slowdown of the perturbations and the autocorrelation grows. An estimator of this behavior is the autocorrelation function computed from a short time series of a system variable of interest. Here we used the value of the autocorrelation function at a sufficiently short lag, usually termed \( AC(1) \).

FIG. 2. Adaptive control of the Chialvo’s neuron map in the excitable regime. All of the results were averaged over 100 samples. Data correspond to numerical solutions of the model starting from ten different initial conditions of the parameter \( k \) from 0.024 (black) to 0.033 (magenta). Different colors denote the evolution of the variables toward the bifurcation point for each initial condition. Panels (a) and (c) show the evolution of \( AC(1) \) and control parameter \( k \), respectively. Panel (b) shows \( AC(1) \) as a function of the control parameter \( k \). Parameters \((a, b, c) = (0.89, 0.60, 0.28) \).
The data in Fig. 1 shows the variation of AC(1) as a function of the bias for Chialvo’s map and FHN model. Notice that in the three examples, the value of the autocorrelation decays as the control parameter moves away from the critical point, a feature that is expected from the theory (see, for instance, a recent review [24], as well as some relevant examples in Refs. [7,25–27]). Note the hysteresis [inset in panel (a)] already described [11] for the excitable regime of the Chialvo map. For the three cases to be described, the behavior of AC(1) as a function of the control parameter is similar, with some peculiarities to be discussed later. According to the previous work of Ref. [7], control can be implemented via the parameter $k$ in Eq. (1), which could correspond to the neuron’s threshold or the number of postsynaptic receptors, controlling the current it receives from other neurons. The procedure starts by selecting an initial random value of $k$ and simulating the dynamics of Eq. (1) for a large number of iterations. After that, we estimate the average value of AC(1) of the activation variable $x_n$ during these iterations. We then compare the AC(1) value at the control step $i$ with the one computed at the previous step $i-1$ [see Eq. (3)], which determines the sign of $d_i$. Finally, the gradient to the maximum (i.e., AC=1) value $d_i$ is computed and used to adjust $k$ for the next control step. As the process is repeated, eventually, the gradient to AC=1 vanishes.

$$d_i = d_{i-1} \text{sgn}[\text{AC}(i) - \text{AC}(i-1)],$$

$$\delta_i = (1 - \text{AC}(i))^{\kappa},$$

$$k_{i+1} = k_i + \delta_i d_i \kappa. \quad (3)$$

More details about the control method in other models can be consulted in Ref. [7]. For the maps studied here, we use the value of the AC function at the shortest nonzero lag, usually termed AC(1). For the FHN model, we arbitrarily take the 30th lag given the fact that the FHN is a differential equation which offers a finer time resolution. The constant $\kappa$ is a small constant ($\kappa = 0.0025$) that determines the timescale at which the control parameter is adjusted. Note that, as mentioned above, the autocorrelation measured represents the timescale of the model dynamic in response to a very small Gaussian perturbation (variance $\sigma \sim 10^{-6}$ for the map model and $\sigma \sim 10^{-5}$ for the FHN model).

III. CHIALVO MAP EXCITABLE REGIME

First, we explore the control of the map Eq. (1) for conditions in which the system exhibits an excitable regime, corresponding to parameter values $(a, b, c) = (0.89, 0.60, 0.28)$. The control is performed for $10^3$ adaptation steps, denoted with index $i$ in Eq. (3) which in turn, each adaptation lasts $4 \times 10^4$ iterations of the map Eq. (1) after discarding the transient ($3 \times 10^2$ iterations).

Figure 2 shows that for all cases the system converges to a region in which the control parameter remains fixed, and the autocorrelation achieves a maximum value. Notice, however, that instead of being a single asymptotic value for the control parameter, there are two. This peculiarity is anticipated by the presence of hysteresis already mentioned in the description of the results in Fig. 1. For this model it is known that for $k \approx 0.03$ there is bistability between a locally stable fixed point and a globally stable fixed point.

![Figure 3](image3.png)

**FIG. 3.** Adaptive control of the Chialvo neuron map in the excitable regime. Panel (a) shows the evolution of the two variables (blue dotted lines) and the nullclines of Eq. (2) (black solid lines) without control (fixed $k = 0.031$) corresponding to the data in panels (d) and (g). Panels (b) and (c) show the evolution and the nullclines after the control is switched on and after two perturbations [panels (e) and (h), and panels (f) and (i), respectively].

![Figure 4](image4.png)

**FIG. 4.** Adaptive control of Chialvo’s neuron map in the chaotic regime. Same format as in Fig. 2. Numerical solutions of the model starting from ten different initial conditions of the parameter $k$ from 0.015 (black) to 0.025 (orange), for 100 samples.
point and periodic orbits (see the example of Fig. 8 in Ref. [11]). The basin of attraction of the fixed point lies on a small region inside the orbit, while all initial conditions with values falling outside the orbit converge to the periodic solution. This implies, in the context of the control, that depending on the history (i.e., the initial conditions), the control will converge to one or the other asymptotic control points. This is evidenced by the results in Fig. 3. Each of the three columns presents the results obtained with the same simulations in three panels: the activation and recovery variable in the middle and bottom panels as a function of time. The same data is plotted in the phase space $x$ versus $y$, overimposed to the nullclines of Eq. (2) in the top panels. In the leftmost panels, the figure illustrates (for $k = 0.031$) the noncontrolled dynamics and the two other panels show the results under the control. For the middle panels, two small perturbations are applied and for the rightmost panels, two large perturbations are inserted. We observe that in both cases the system is led back to the controlled trajectories.

**IV. CHIALVO MAP CHAOTIC REGIME**

It is known that for certain regions of parameter space Eq. (1) exhibits chaotic dynamics. For instance, for parameters $(a, b, c, k) = (0.89, 0.18, 0.28, 0.025)$ the system shows chaotic bursting, characterized by aperiodic trajectories spiraling out of a repellor located in the proximity of the $(x = y = 1)$ region in phase space. The control of Chialvo’s neuron map in the chaotic regime is shown in Fig. 4, and an example is shown in Fig. 5.

**V. THE FITZHUGH-NAGUMO NEURON MODEL**

Now we turn to replicate the above results in the paradigmatic FitzHugh-Nagumo model [12–14]. This formulation was inspired by the Van der Pol nonlinear neon-bulb relaxation oscillator [28] model, and also mimics the celebrated Hodgkin-Huxley equations of the neuron membrane [10]. The equations are

\begin{align}
{v}_{t+1} &= v_t + dt[(v_t - a)(1 - v_t) - w_t + I + \eta]/\epsilon, \\
{w}_{t+1} &= w_t + dt(v_t - d w_t - b)
\end{align}

in which $v$ represents the membrane potential, or also called fast variable, $w$ is the slow recovery-like, and $\eta$ is a very small perturbation. In the present simulations we use parameters $a = 0.5$, $b = 0.15$, $d = 1$, $dt = 0.0015$, $\epsilon = 0.005$. The parameter $I$ acts as the control parameter. As shown in Fig. 6, the results for the control of the FitzHugh-Nagumo model are very similar to Chialvo’s map in the excitable regime. This is expected given the fact that for the parameter used here both models share the same bifurcation scenario; namely, the FHN model undergoes a Hopf bifurcation from stable fixed point to a limit cycle oscillation as a function of a constant bias $I$.

The equations for the control are similar to Eq. (3), which explicitly are

\begin{align}
{d}_i &= {d}_{i-1}\text{sgn}[AC(30)_{i(1)} - AC(30)_{i(1-1)}], \\
{\delta}_i &= (1 - AC(30)_{i(1)})^2, \\
{I}_{i+1} &= {I}_i + {\delta}_i {d}_i \kappa,
\end{align}

where $AC(30)_i$ represents a function involving the action of a Schrödinger equation and $\kappa$ is a constant.
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