New knotted solutions of Maxwell’s equations

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Abstract

In this paper we have further developed the study of topologically non-trivial solutions of vacuum electrodynamics. We have discovered a novel method of generating such solutions by applying conformal transformations with complex parameters on known solutions expressed in terms of Bateman’s variables. This has enabled us to obtain a wide class of solutions from the basic configuration, such as constant electromagnetic fields and plane-waves. We have introduced a covariant formulation of Bateman’s construction and discussed the conserved charges associated with the conformal group as well as a set of four types of conserved helicities. We have also given a formulation in terms of quaternions. This led to a simple map between the electromagnetic knotted and linked solutions into flat connections of SU(2) gauge theory. We have computed the corresponding Chern–Simons charge in a class of solutions and the charge takes integer values.

Keywords: classical electrodynamics, topological solutions, complex conformal transformation, quaternions, abelian-non abelian map, knots

(Some figures may appear in colour only in the online journal)

1. Introduction

It is commonly understood that topological non-trivial solutions in field theory associate only with non-linear equations of motion. This is the case, for instance, for two-dimensional solitons, magnetic monopoles and four-dimensional Yang–Mills instantons. In fact it turns out that this statement is false and there are also non-trivial configurations which solve linear
equations of motion. In particular, there are known solutions of free Maxwell’s equations in flat space-time that admit a non-trivial topology, the Hopfion solution constructed in [3]. Since then there have been several studies of these solutions [4–7], which were recently revived in [8–12]. These solutions were studied as null electromagnetic solutions in Bateman’s [2] construction in [13, 14]. The generalization and classification of analog solutions in higher spin fields was studied in [15–18]. Linked and knotted non-null solutions of electrodynamics were studied in [19]. A collection of comprehensive notes and references for such solutions in electrodynamics and other areas of physics can be found in [20].

Since the original determination by Maxwell of the equations of motion of electrodynamics, many methods have been proposed to determine the evolution in space and time of the electric and magnetic fields. The method we will use in this paper is the so called Bateman’s construction [2] which is based on grouping the electric and magnetic fields into a complex vector field (the Riemann–Silberstein vector [21, 25]) and expressing it in terms of two complex functions \( \alpha \) and \( \beta \) as follows,

\[
\begin{align*}
\mathbf{F} &= \mathbf{E} + i\mathbf{B} \\
&= \nabla \alpha \times \nabla \beta.
\end{align*}
\]

For this ansatz of the fields the solutions of the equations of motion are necessarily null, namely

\[
\mathbf{F}^2 = 0 \quad \Rightarrow \quad \mathbf{E}^2 - \mathbf{B}^2 = 0, \quad \mathbf{E} \cdot \mathbf{B} = 0.
\]

Certain solutions of the equations of motion have a very cumbersome form when expressed directly in terms of \( \mathbf{E} \) and \( \mathbf{B} \) but are very compact in terms of \( \alpha \) and \( \beta \). An example of this is the remarkable solution which admits a non-trivial linking between the electric and magnetic fields, which takes the form [14],

\[
\alpha = \frac{A - 1 + i z}{A + it}, \quad \beta = \frac{(x - iy)}{A + it}.
\]

where \( A = \frac{1}{2}(x^2 + y^2 + z^2 - t^2 + 1) \). The solution has an implicit dependence on a scale that we have set to one. We can make the dependence explicit by rescaling the coordinates \((t, x, y, z) \rightarrow \lambda(t, x, y, z)\). Note also that the solution is valid for any conformally flat metric, since Maxwell’s equations do not change. This space- and time-dependent solution has finite energy, momentum, angular momentum, etc. The topological nature of this solution manifests itself in the fact that it carries non-trivial ‘Chern–Simons (CS) helicity charges’. Exactly the same charges also characterize the so called Hopfion solution of Maxwell’s equation [3, 4] which can be derived from the basic Hopf map \( S^3 \rightarrow S^2 \). It was shown in [13, 14] that there is in fact an infinitely large family of solutions that can be derived from the basic one by mapping \( \alpha \rightarrow f(\alpha, \beta) \) and \( \beta \rightarrow g(\alpha, \beta) \), where \( f \) and \( g \) are two arbitrary holomorphic functions. One may wonder if there are other ways to easily generate new families of solutions; in this paper we show that the answer is in the affirmative. We will prove that any transformation associated with the full conformal group \( SO(2, 4) \), but with complex rather than real parameters of a given solution, is also a solution of Maxwell’s equation. Obviously such transformations are not symmetries of Maxwell’s action, however, they do yield new solutions. Implementing this idea we found out that applying a temporal special conformal transformation (TSCT) with an imaginary parameter on constant electric and magnetic perpendicular fields produces the topologically non-trivial solution of (1.3). We further generated new solutions by applying such transformations on plane waves and on the Hopfion (1.3) itself. One remarkable property of these transformations is that they map solutions of infinite energy and Noether charges to solutions with finite energy and charges.
We have discovered another interesting property of the knotted solutions of Maxwell’s equation. They can be mapped into $SU(2)$ flat gauge connections. Defining a quaternionic-valued function

$$q = \frac{1}{\sqrt{|\alpha|^2 + |\beta|^2}} (\alpha + \beta),$$  \hspace{1cm} (1.4)$$
we can map the unit quaternions to elements of $SU(2)$ using a representation in terms of Pauli matrices. Then, we write down a flat gauge connection as $Q_\mu = q (\partial_\mu q^\dagger)$. We determine the winding number from the calculation of the non-abelian CS.

The paper is organized as follows. In the following section we review Bateman’s construction of Maxwell’s equations. We present the variables, the constraint equations and the method to deduce from them the electric and magnetic fields. The conserved charges associated with the conformal symmetry group that characterize the solutions are presented. We then describe, using Bateman’s construction variables, three particular solutions: (i) constant perpendicular electric and magnetic fields, (ii) the plane wave solution and (iii) the Hopfion solution. The latter is the basic prototype solution that admits a non-trivial topology. In section 3 we describe the new method for generating novel non-trivial solutions. The method utilizes transformations of the full conformal group with complex rather than real parameters. We first prove that the transformed configurations are indeed solutions of the equations of motion. We then show in section 3.2 how one can obtain the topologically non-trivial $(p, q)$ solutions from constant electric and magnetic fields. Next we obtain knotted solutions from plane waves and in section 3.4 we apply the complex transformation on the Hopfion configuration, in particular time translations, space translations, rotations, boosts, scalings and special conformal transformations (SCTs). Section 4 is devoted to additional formal aspects of Bateman’s construction and knot solutions. In section 4.1 we present a covariant formulation of the construction and then in section 4.2 we derive general formulas for the helicities of the solutions. In section 4.3 we reformulate Bateman’s construction using quaternionic fields. We show that this naturally leads to a relation between the knotted abelian solutions and flat $SU(2)$ non-abelian gauge connections with non-zero winding number. Section 5 is devoted to a summary and a list of open questions. Three appendices are included: in the first the Noether charges are determined, the second describes a different formulation of the Hopfion solutions and in the third we present explicit expressions for the components of the electric and magnetic fields.

2. Bateman’s construction

A procedure to construct topologically non-trivial solutions in Maxwell’s equations is to use Bateman’s construction [2]. In 3+1 dimensions we can group the electric and magnetic fields in a single complex vector field, the Riemann–Silberstein vector $[21, 25]$

$$F = E + iB.$$ \hspace{1cm} (2.1)$$
In the absence of charged matter, Maxwell’s equations for the complex field are

$$\nabla \cdot F = 0, \quad i\partial T F = \nabla \times F.$$ \hspace{1cm} (2.2)$$
We can satisfy the divergenceless condition with the general ansatz

$$F = \nabla \alpha \times \nabla \beta,$$ \hspace{1cm} (2.3)$$
where $\alpha$ and $\beta$ are complex. Then, the dynamical equation becomes
\[ i \nabla \times (\partial_\alpha V \beta - \partial_\beta V \alpha) = \nabla \times F. \] (2.4)
Which will be satisfied if
\[ i(\partial_\alpha V \beta - \partial_\beta V \alpha) = F = \nabla \alpha \times \nabla \beta. \] (2.5)
Solutions of this form have null norm
\[ F^2 = i(\partial_\alpha V \beta - \partial_\beta V \alpha) \cdot (\nabla \alpha \times \nabla \beta) = 0 \Rightarrow E^2 - B^2 = 0, \quad E \cdot B = 0. \] (2.6)
For this reason, they are also known as null solutions [13, 14].

2.1. Conserved charges
We will characterize solutions by their conserved charges. Initially we have the usual conserved charges: energy $E$, momentum $P$ and angular momentum $L$. They can be written as integrals over space of the following gauge-invariant charge densities:

- Energy density: $E = \frac{1}{2}(E^2 + B^2)$.
- Momentum density: $p = (E \times B)$.
- Angular momentum density: $\ell = (p \times x)$.

Since Maxwell’s theory is invariant under conformal transformations, we have additional charge densities associated to the following transformations:\(^3\)

- Boosts: $b_\nu = (\xi \cdot x - \xi_\nu)$.
- Dilatations: $d = (p \cdot x - \xi \cdot \xi)$.
- TSCT: $k^0 = \left( (x^2 + r^2)\xi - 2\, i(p \cdot x) \right)$.
- Spatial SCT (SSCT): $k = \left( 2x(p \cdot x) - 2ii\xi x - (x^2 - r^2)p \right)$.

We will denote the conserved charges as $B_\nu, D, K^\nu$ and $K$, respectively.

For the null solutions we have an additional set of conserved charges that do not have a gauge-invariant density, or electric and magnetic helicities. We define them as the integral over space of the CS form of the gauge potentials.

Let us first define the complex vector potential $V$, such that $F = \nabla \times V$. We can decompose it in real and imaginary parts $V = C + iA$, so it is clear that $A$ is the usual gauge potential and $C$ is the ‘dual’ potential in the sense of electromagnetic duality
\[ E = \nabla \times C, \quad B = \nabla \times A. \] (2.7)
From (2.3), we can derive the relation between the gauge potentials and the functions $\alpha$ and $\beta$. Up to gauge transformations
\[ V = C + iA = \alpha \nabla \beta, \] (2.8)
\[ C = \text{Re}(\alpha \nabla \beta), \quad A = \text{Im}(\alpha \nabla \beta). \] (2.9)
In this language, electromagnetic duality is simply the transformation $\alpha \rightarrow i\alpha$ or $\beta \rightarrow i\beta$, which clearly is a symmetry of the equations of motion (2.5).

\(^3\) The charge densities for SCT given here differ from those in [8], although their values agree at $t = 0$. We provide a derivation of the correct charges in appendix A. We have explicitly checked that they are time-independent.
The electric and magnetic helicities are defined as

\[ h_{ee} = \int d^3x \, \mathbf{C} \cdot \mathbf{E}, \quad h_{mm} = \int d^3x \, \mathbf{A} \cdot \mathbf{B}. \]  

(2.10)

They are gauge invariant when the integral is over all space, since \( \nabla \cdot \mathbf{E} = \nabla \cdot \mathbf{B} = 0 \). In addition, we can define the cross helicities

\[ h_{em} = \int d^3x \, \mathbf{C} \cdot \mathbf{B}, \quad h_{me} = \int d^3x \, \mathbf{A} \cdot \mathbf{E}. \]  

(2.11)

They are also gauge invariant when the integral is over all space.

To show that the helicities are conserved for the null solutions is very simple. For the magnetic helicity we have

\[ \partial_t h_{mm} = \int d^3x \, (\partial_t A \cdot B + A \cdot \partial_t B) \]

\[ = -\int d^3x \, ((E + \nabla\phi) \cdot B + A \cdot (\nabla \times E)) \]

\[ = \int d^3x \, (\phi \nabla \cdot B - E \cdot (\nabla \times A)) = -\int d^3x \, E \cdot B = 0. \]  

(2.12)

We have used that \( E = -\partial_t A - \nabla \phi \) and \( E \cdot B = 0 \) (\( A \) and \( \phi \) are the vector and scalar electromagnetic potentials, respectively). We can repeat the same calculation for the electric helicity \( h_{ee} \) using the dual potential. For the cross helicities we can also show that they are conserved. For \( h_{me} \)

\[ \partial_t h_{me} = \int d^3x \, (\partial_t A \cdot E + A \cdot \partial_t E) \]

\[ = \int d^3x \, (-E \cdot \nabla \phi + \nabla A \cdot \nabla \phi) \]

\[ = \int d^3x \, -E^2 + \phi \nabla \cdot E + B \cdot (\nabla \times A) = -\int d^3x \, (E^2 - B^2) = 0. \]  

(2.13)

And a similar calculation can be performed for \( h_{em} \).

In fact, for solutions found using Bateman’s construction, the two helicities have the same value and the two cross helicities have opposite signs. One can show this using the fact that the complex potential is orthogonal to the complex field strength

\[ \nabla \cdot \mathbf{F} = \alpha \nabla \phi \cdot (\nabla \alpha \times \nabla \phi) = 0 \quad \Rightarrow \ C \cdot \mathbf{E} = \alpha \cdot \mathbf{B} = 0, \quad C \cdot \mathbf{B} = \alpha \cdot \mathbf{E} = 0. \]  

(2.14)

Therefore, all the solutions will have \( h_{ee} = h_{mm} \), \( h_{me} = -h_{em} \).

2.2. Examples

There are several kinds of known solutions to Maxwell’s equations that can be found using Bateman’s construction. The simplest solution one can consider is that corresponding to a constant electric and magnetic field,

\[ \alpha = 2i(t + z) - 1; \quad \beta = 2(x - iy). \]  

(2.15)

The corresponding electric and magnetic fields are null and perpendicular to each other,

\[ \mathbf{E} = (-4, 0, 0); \quad \mathbf{B} = (0, 4, 0). \]  

(2.16)

This solution has diverging total energy and total helicity.
The next simplest are plane waves. An example is \[ \alpha = e^{i(z-t)}, \quad \beta = x + iy. \] (2.17)

Then,

\[ \mathbf{F} = (\dot{x} + iy\dot{y})e^{i(z-t)}. \] (2.18)

This is a linearly polarized plane wave moving along the \( z \) direction. These solutions have finite energy density and momentum, but all the charges diverge when integrated over the full space. Therefore, we cannot associate well defined helicities to them.

A more interesting kind of solution is the Hopfion, which we describe in detail in appendix B.2. The Hopfion was originally found in [3] and the same solution was constructed again later using Bateman’s construction in [14]4.

\[ \alpha = A - 1 + iz, \quad \beta = \frac{(x - iy)}{A + ir}. \] (2.19)

where \( A = \frac{1}{2}(x^2 + y^2 + z^2 - t^2 + 1) \). In this form, the functions \( \alpha \) and \( \beta \) satisfy the additional condition \( |\alpha|^2 + |\beta|^2 = 1 \), so for fixed time they can be seen as the inverse of a stereographic map of \( S^3 \) to \( \mathbb{R}^3 \cup \{\infty\} \). We use this later to provide a general formula for the helicity that is independent of the functional forms of \( \alpha \) and \( \beta \). We must point out that although this is a nice representation, it is not unique, in other representations \( |\alpha|^2 + |\beta|^2 \) may not be a constant [14]. The explicit forms of the components of the electric and magnetic fields are given in appendix C (similar expressions can also be found in the original work [4]. See also [18] for a review).

The Hopfion solution has finite energy \( E \), momentum \( \mathbf{P} = (0, 0, -E/2) \) and angular momentum \( \mathbf{L} = (0, 0, E/2) \). It also has finite helicities \( h_\infty = h_{\text{mim}} = E/2 \). The Hopfion solution is topologically non-trivial in the sense that electric and magnetic field lines are linked with each other (figure 1(b)).

The Hopfion solution was used in [14] to generate a large family of topologically non-trivial solutions with different kinds of knots and links. The new solutions were found using the following observation: each pair \( (\alpha, \beta) \) in Bateman’s construction generates a whole family of solutions by simply defining new functions \( (f, g) \) that depend holomorphically on \( \alpha \) and \( \beta \). The new field strength is changed to

\[ \mathbf{F} = \nabla f(\alpha, \beta) \times \nabla g(\alpha, \beta) = h(\alpha, \beta) \nabla \alpha \times \nabla \beta, \] (2.21)

\[ i(\partial_f \nabla g - \partial_g \nabla f) = h(\alpha, \beta) i(\partial_i \alpha \nabla \beta - \partial_i \beta \nabla \alpha) \] (2.22)

where \( h = \partial_i f \partial_g g - \partial_i g \partial_f f \). Clearly, if \( (\alpha, \beta) \) satisfy the equations of motion, so do \( (f, g) \). The new solutions have \( f = \alpha^p \) and \( g = \beta^q \). For co-prime integers \((p, q)\) one finds various knots. The \((p, q)\)-knot solutions have finite energy \( E \), which depends on the amplitude of the solutions. The other charges are:

- Momentum: \( \mathbf{P} = (0, 0, -\frac{p}{\rho + q}E) \).

- Angular momentum: \( \mathbf{L} = (0, 0, \frac{q}{\rho + q}E) \).

4 This solution (field strength) is the same up to a trivial constant factor as described in appendix B.2, after the identification \( t \rightarrow -t \) and \( \phi \rightarrow \theta \).
Boosts: $B_i = (0, 0, 0)$.
Dilatations: $D = 0$.
TSCT: $K^0 = E$.
SSCT: $K = (0, 0, -\frac{p}{p + q}E)$.
Helicities: $h_{ee} = h_{mm} = \frac{1}{p + q}E$.
Cross helicities: $h_{em} = -h_{me} = 0$.

We can obtain the field lines corresponding to a vector field $V^i(x')$ by solving for curves given by $x^i(\tau)$, where,

$$\frac{dx^i(\tau)}{d\tau} = V^i(x^i(\tau)). \tag{2.23}$$

This first order differential equation, along with the boundary condition $x^i(\tau = 0) = x_0^i$, gives a field line passing through the point $x_0^i$. For the case of electric or magnetic lines, we use a normalized electric or magnetic field at a given time as $V^i$. To check the periodicity of these lines of force we can plot $\ln(\ln(|x^i(\tau) - x^i(0)|))$ as a function of $\tau$. For the Hopfion such a plot is given in figure 1(a). We also solve numerically field lines for the Hopfion and plot them in figure 1(b).

Alternatively, the structure of the solutions can be studied using surfaces that contain electric and magnetic field lines, which we define below. For the $(p, q)$ solutions with
\(|\alpha|^2 + |\beta|^2 = 1\), we can find a gradient field orthogonal to the electric and magnetic fields given by [14],

\[ \phi = \phi_B + i\phi_E = \alpha^p \beta^q; \quad \mathbf{B} \cdot \nabla \phi_B = \mathbf{E} \cdot \nabla \phi_E = 0. \quad (2.24) \]

So we can visualize the geometrical properties of these solutions by plotting the isosurfaces of \(\phi_B\) and \(\phi_E\), which contain the electric and magnetic field lines. Figures 1(c) and 1(d) show such isosurfaces for the Hopfion. The properties of these isosurfaces were studied in detail in [14].

3. Generating new solutions

There are multiple possibilities to generate new solutions. One way that we have already explained is to substitute \(\alpha\) and \(\beta\) in Bateman’s construction by holomorphic functions of the same solutions, with arbitrary complex coefficients. Another way is to use the symmetries of the equations to produce new solutions. Clearly if we do a Poincaré transformation we will trivially obtain a new solution. Translations will not affect the charges of the solutions, while rotations will rotate momentum and angular momentum and boosts will also change the energy and conformal charges. However, we do not see them as truly new solutions, since we can recover the original form of the solution by simply changing the frame of reference.

A more interesting possibility is to consider other kinds of deformations, such as scaling and squeezing, or conformal transformations [28]. This is used sometimes in a different context in order to check the stability of soliton solutions (see e.g. [32, 33]). In general, not all transformations will lead to a new solution, in order for this to happen it is necessary that the equations of motion are on-shell invariant. In the case of Bateman’s construction there is a new interesting generalization. Since the equations are complex, the deformations can also be made complex\(^5\). In practice this could be interpreted as mixing usual deformations with electromagnetic duality, which, as we have seen, corresponds to introducing imaginary factors in the solutions.

We will first use infinitesimal transformations to learn which ones can be used to generate new solutions. Then, we will perform finite transformations of the solutions and study their properties. In all cases we have checked explicitly that the equations of motion are satisfied by the new deformed solutions. Although these complex transformations on the solutions generate ‘new’ solutions to the equations of motion, they might be sometimes related to each other by a real transformation and thus be in the same class.

For convenience we will use components rather than vectorial notation. Greek indices \(\mu, \nu = 0, 1, 2, 3\) refer to space-time directions and Latin indices \(i, j = 1, 2, 3\) refer to spatial directions. For a spatial vector the curl and the divergence are

\[ (\nabla \times \mathbf{A})^i = \epsilon^{ijk} \partial_j A_k, \quad (\nabla \cdot \mathbf{A}) = \partial_i A^i. \quad (3.1) \]

For four-vectors we will raise and lower indices with the mostly plus metric \(\eta_{\mu\nu} = \text{diag} (-1, 1, 1, 1)\) and define the epsilon tensor with space-time indices as \(\epsilon^{ijkl} = -\epsilon^{iklj}\).

\(^5\) It was pointed out to us (after the appearance of our preprint in arXiv) that the complex transformation of Maxwell solutions was studied previously in [22–25]. See also [26, 27].
3.1. Infinitesimal transformations of the solutions

Under an infinitesimal (complex) coordinate transformation \( x^\mu \to x^\mu + \xi^\mu \), the functions \( \alpha \) and \( \beta \) change as

\[
\delta \alpha = \xi^i \partial_\lambda \alpha, \quad \delta \beta = \xi^i \partial_\lambda \beta.
\]

(3.2)

The equation of motion is

\[
i \left( \partial_\lambda \alpha \partial^\lambda \beta - \partial^\lambda \alpha \partial_\lambda \beta \right) - \epsilon^{ijk} \partial_\lambda \alpha \partial_\mu \beta = 0.
\]

(3.3)

Under the infinitesimal transformation there is a part \( \sim \xi^i \partial_\lambda \)(equation) which vanishes trivially on-shell and then there are the contributions

\[
0 = i \partial_0 \xi^i \left( \partial_\lambda \alpha \partial^\lambda \beta - \partial^\lambda \alpha \partial_\lambda \beta \right) + i \partial_0 \xi^i \left( \partial_\nu \alpha \partial^\nu \beta - \partial^\nu \alpha \partial_\nu \beta \right)
\]

\[
- \partial_0 \xi^i \epsilon^{ijk} \left( \partial_\lambda \alpha \partial_\mu \beta - \partial_\mu \alpha \partial_\lambda \beta \right).
\]

(3.4)

We can write each term as follows using the equations of motion

\[
i \partial_0 \xi^i \left( \partial_\lambda \alpha \partial^\lambda \beta - \partial^\lambda \alpha \partial_\lambda \beta \right) = \left( \partial_0 \xi^0 - \partial_n \xi^n \right) 0^i + i \left( \partial_0 \xi^n - \partial_n \xi^0 \right) 0^i + \partial_0 \xi^1 + \partial_0 \xi^2 + \partial_0 \xi^3
\]

(3.5)

All together, we find the condition

\[
0 = \left[ \left( \partial_0 \xi^0 - \partial_n \xi^n \right) 0^i + i \left( \partial_0 \xi^n - \partial_n \xi^0 \right) 0^i + \partial_0 \xi^1 + \partial_0 \xi^2 + \partial_0 \xi^3 \right] \epsilon^{ijk} \partial_\lambda \alpha \partial_\mu \beta.
\]

(3.6)

It is immediate to see that this is satisfied for translations in all coordinates \( \xi^\mu = c^\mu \), Lorentz transformations \( \xi^\mu = A^\nu \xi^\nu \), with \( A_{\mu\nu} = -A_{\nu\mu} \) and dilatations \( \xi^\mu = \lambda x^\mu \).

Let us write the derivative in the general form

\[
\partial_\lambda \xi = \frac{1}{3} \delta_\lambda \partial_n \xi^n + \frac{1}{2} \sigma_\lambda + \frac{1}{2} \omega_\lambda.
\]

(3.7)

where \( \omega_{ij} \) is the antisymmetric part and \( \sigma_{ij} \) is symmetric and traceless. Then,

\[
0 = \left[ \left( \partial_0 \xi^0 - \frac{1}{3} \partial_n \xi^n \right) 0^i + i \left( \partial_0 \xi^n - \partial_n \xi^0 \right) 0^i + \sigma^{ij} \right] \epsilon^{ijk} \partial_\lambda \alpha \partial_\mu \beta.
\]

(3.8)

We see that the following conditions should be satisfied in general:

\[
\sigma_{ij} = 0, \quad \partial_0 \xi^0 - \frac{1}{3} \partial_n \xi^n = 0, \quad \partial_0 \xi^n - \partial_n \xi^0 = 0.
\]

(3.9)

Note that these conditions are also satisfied by SCTs

\[
\xi^\mu = a^\mu x^2 - 2 a^\lambda x^i x^\lambda.
\]

(3.10)

So new solutions can be generated using conformal transformations with complex parameters. Shear deformations on the other hand do not produce new solutions.
3.2. \((p, q)\)-knots from constant electric and magnetic fields

As a very simple application of complex deformations let us show how the Hopfion solution or \((1,1)\)-knot can be obtained through a conformal transformation of a solution with constant electric and magnetic fields.

Let us choose the solution with constant field strength as given in (2.15),

\[
\alpha = 2i(t + z) - 1; \quad \beta = 2(x - iy).
\]

The corresponding electric and magnetic fields are constant and have diverging total energy and helicity. Now let us consider a SCT,

\[
x^\mu \rightarrow \frac{x^\mu - b^\mu x_\sigma x^\sigma}{1 - 2b_\sigma x^\sigma + b_\mu b^\sigma x_\sigma x^\mu}.
\]

With the choice of the parameter, \(b^\mu = i(1, 0, 0, 0)\) the new \((\alpha, \beta)\) obtained by this transformation is the same as the Hopfion solution given by (2.19) and (2.20). If we consider a more general choice of the parameter \(b^\mu\), we can generate linked solution with various values of conserved charges.

Other knotted solutions can be generated by considering integer powers of \((\alpha, \beta)\) given in (2.15), i.e. \((\alpha, \beta) \rightarrow (\alpha^p, \beta^q)\), and then considering a SCT with parameter \(b^\mu = i(1, 0, 0, 0)\). Figure 2 shows an isosurface of \(\phi_E\) (as defined in (2.24)) for a \((p = 2, q = 3)\)-knot. The final \((\alpha, \beta)\) obtained here is the same as that given in section 2.2 for \((p, q)\) knots. So generating a new solution using SCT and considering holomorphic functions of a solution commutes with each other. The solution before considering the SCT, given by \((\alpha^p, \beta^q)\), has non-constant electric and magnetic fields with divergent total energy and helicity.

\[\text{Figure 2. Plot of the } \phi_E = 0.05 \text{ surface for a } (2, 3)\text{-knot at } t = 0.\]

\[\text{It was pointed out to us (after the appearance of our preprint in arXiv) that, in [24], it was shown that similar linked solutions of Maxwell's equations can be obtained from constant solutions by a coordinate transformation given by conformal reflection accompanied by a shift in time direction by an imaginary constant. See also [27].}\]
3.3. Knotted solutions from plane waves

We can also use complex transformations to generate new solutions from the plane wave (2.17). Let us write here again the solution,
\[\alpha = e^{i(x-t)}, \quad \beta = x + iy.\] (3.13)

We can easily see that not all complex transformations will generate new solutions. An imaginary translation in \(x\) or \(y\) is equivalent to a real space translation along \(y\) or \(x\), respectively. An imaginary translation in \(z\) or \(t\) is equivalent to the same solution (i.e. field strength) up to an overall scale.

The only transformations that are left to produce new solutions are SCTs given by (3.12). Let us choose \(b^\mu\) as \((i, 0, 0, 0)\). The new solution for \(\alpha, \beta\) is given by:
\[\alpha = e^{\left(-1+\frac{i(t+z-2c)}{1-t^2+x^2+y^2+z^2+2i\tau}\right)},\] (3.14)
\[\beta = \frac{x + iy}{1 - t^2 + x^2 + y^2 + z^2 + 2i\tau}.\] (3.15)

Note that the solution is smooth. This is not true in general for real conformal transformations. In contrast to the plane wave solution, this solution has finite energy \(E\) and the following finite conserved charges fixing \(E = 1\):
- Momentum: \(P = (0, 0, 0.613)\).
- Angular momentum: \(L = (0, 0, -0.387)\).
- Boosts: \(B = (0, 0, 0)\).
- Dilations: \(D = 0\).
- TSCT: \(K^0 = 0.613\).
- SSCT: \(K = (0, 0, 0.225)\).
- Helicities: \(h_{ec} = h_{mn} = 0.387\).
- Cross helicities: \(h_{em} = h_{me} = 0\).

A plot of the field lines (figure 3) shows that the electric and magnetic field lines lie on a torus and are linked to each other, so the solution is topologically non-trivial.

3.4. Complex deformations of Hopfions

For the Hopfions we find that all complex transformations lead to new solutions. We list the form of the new solutions and the conserved charges below.

- **Time translation**: The solutions generated by the imaginary time translation \(t \to t + ic\), with \(c\) a constant real parameter are,
\[\alpha = N_i \frac{A - 1 + iz}{A + i(t + ic)},\] (3.16)
\[\beta = N_i \frac{(x - iy)}{A + i(t + ic)},\] (3.17)
where \(A = \frac{1}{2}(x^2 + y^2 + z^2 - (t + ic)^2 + 1)\). We introduce a factor \(N_i\) as the overall normalization, which is related to the energy \(E\) as \(N_i^4 = \frac{E(1 - c\beta)}{2\pi^2}\).

The conserved charges for this solution are:
– Momentum: \( \mathbf{P} = (0, 0, \frac{-E}{2}) \).
– Angular momentum: \( \mathbf{L} = (0, 0, \frac{1-c^2E}{2}) \).
– Boosts: \( \mathbf{B}_c = (0, 0, 0) \).
– Dilatations: \( D = 0 \).
– TSCT: \( K^0 = (1 - c^2E) \).
– SSCT: \( \mathbf{K} = (0, 0, \frac{-1}{2}(1 - c^2E)) \).
– Helicities: \( h_{ee} = h_{mm} = \frac{1-c^2E}{2} \).
– Cross helicities: \( h_{em} = -h_{me} = 0 \).

The helicity in units of energy is a continuous function of the parameter \( c \), but the structures of the electric and magnetic lines are the same as those of Hopflion for all values of \( c \neq 1 \).

- **Space translation**: Deformed solutions have generically divergent energy except for a finite range of the translation parameter. Let us consider the case where only the \( z \) direction is shifted \( z \rightarrow z + ic \), with \( c \) a real constant number.
\[ \alpha = N_1 \frac{A - 1 + i(z + i\epsilon)}{A + i\epsilon}, \]  
(3.18)

\[ \beta = N_1 \frac{(x - iy)}{A + i\epsilon}, \]  
(3.19)

where \( A = \frac{1}{2}(x^2 + y^2 + (z + i\epsilon)^2 - i^2 + 1). \) In order to have finite energy solutions we are forced to require \( |\epsilon| < 1. \) It is difficult to find an analytic expression for charges as a function of the parameter. Instead, figure 4 shows a plot of helicity versus the parameter \( c \) in units such that total energy is \( E = 1. \) We have computed numerically the charges for \( c = 0.5 \) and \( E = 1: \)

- Momentum: \( \mathbf{P} = (0, 0, -0.5). \)
- Angular momentum: \( \mathbf{L} = (0, 0, 0.3). \)
- Boosts: \( \mathbf{B}_v = (0, 0, 0). \)
- Dilatations: \( D = 0. \)
- TSCT: \( K^0 = 0.45. \)
- SSCT: \( \mathbf{K} = (0, 0, -0.25). \)
- Helicities: \( h_{ee} = h_{mm} = 0.3. \)
- Cross helicities: \( h_{em} = 0. \)

- \textbf{Rotations:} We can also generate new solutions using rotations along the spatial coordinates with complex angles. Rotations in the \( xy \) plane by a complex angle amount to a rescaling of the solution, thus they do not really generate new solutions. Non-trivial transformations involve the \( z \) direction. Let us consider the following transformation in the \( xz \) plane, \( x \rightarrow x \cos(i\theta) - z \sin(i\theta), \ z \rightarrow z \cos(i\theta) + x \sin(i\theta). \) The new solution produced by this transformation is,

\[ \alpha = N_1 \frac{A - 1 + i(z \cos(i\theta) + x \sin(i\theta))}{A + i\epsilon}, \]  
(3.20)

\[ \beta = N_1 \frac{(x \cos(i\theta) - z \sin(i\theta) - iy)}{A + i\epsilon}, \]  
(3.21)

where \( A = \frac{1}{2}(x^2 + y^2 + z^2 - i^2 + 1). \) The normalization \( N_1 \) is related to the energy \( E \) as \( N_1^4 = \frac{E^2}{2x^2 \cosh^2(\theta)}. \) The charges for these solutions are:

- Momentum: \( \mathbf{P} = (0, \frac{1}{2} \tanh(\theta), -\frac{1}{2} \sech(\theta))E. \)
- Angular momentum: \( \mathbf{L} = (0, -\frac{1}{2} \tanh(\theta), \frac{1}{2} \sech(\theta))E. \)
- Boosts: \( \mathbf{B}_v = (0, 0, 0). \)
- Dilatations: \( D = 0. \)
- TSCT: \( K^0 = E. \)
- SSCT: \( \mathbf{K} = (0, \frac{1}{2} \tanh(\theta), -\frac{1}{2} \sech(\theta))E. \)
- Helicities: \( h_{ee} = h_{mm} = E/2. \)
- Cross helicities: \( h_{em} = -h_{me} = 0. \)

In this case the helicity in units of the energy does not change.
Boosts: An imaginary boost along the $x^i$ direction is given by:

$$t \to t \cosh(i\theta) - x^i \sinh(i\theta), \quad (3.22)$$

$$x^i \to x^i \cosh(i\theta) - t \sinh(i\theta), \quad (3.23)$$

where $\theta$ is real. The expression of $\alpha, \beta$ for Hopfions is rotationally symmetric in the $(x, y)$ plane, so let us consider imaginary boosts along $x$ and $z$ here. We also introduce an overall normalization $N_1$ as before, related to the energy $E$ as $N_1^4 = \frac{E}{3\pi} |\cos \theta|^2$, independent of the direction of the boost.

The charges for the solution generated by the boost along the $x$ direction (of energy $E$):

- Momentum: $P = (0, \frac{E}{2} \sin \theta, -\frac{E}{2} \cos \theta)$.
- Angular momentum: $L = (0, 0, \frac{1}{2} E)$.
- Boosts: $B_0 = (-\sin \theta E, 0, 0)$.
- Dilatations: $D = 0$.
- TSCT: $K^0 = E$.
- SSCT: $K = (0, -\frac{1}{2} \sin \theta E, -\frac{1}{2} \cos \theta E)$.
- Helicities: $h_{ee} = h_{mm} = E \cos \theta E$.
- Cross helicities: $h_{em} = -h_{me} = 0$.

The charges for a solution generated by a boost along $z$ (of energy $E$) are

- Momentum: $P = (0, 0, -\frac{E}{2})$.
- Angular momentum: $L = (0, 0, \frac{1}{2} \cos \theta E)$.
- Boosts: $B_0 = (0, 0, -\sin \theta E)$.
- Dilatations: $D = \frac{1}{2} \sin \theta E$.
- TSCT: $K^0 = E$.
- SSCT: $K = (0, 0, -\frac{1}{2} E)$.
- Helicities: $h_{ee} = h_{mm} = \frac{1}{2} E \cos \theta E$.
- Cross helicities: $h_{em} = -h_{me} = 0$.

Scaling: Complex scalings $x^\mu \to b x^\mu$ generate new solutions, but if $b$ is purely imaginary the energy of the new solutions is always infinite and the helicity is zero. Instead, it is better to consider transformations with $b = 1 + ic$, where $c$ is real. Such solutions have finite and non-zero energy and helicity for a finite range of the parameter $c$. For these solutions it is difficult to obtain the analytic expression of the charges as a function of $c$, but we can easily obtain numerical results. For $c = 1$ and $E = 1$ we find the following values:

- Momentum: $P = (0, 0, -0.5)$.
- Angular momentum: $L = (0, 0, 0.25)$.
- Boosts: $B_0 = (0, 0, 0.25)$.
- Dilatations: $D = -0.5$.
- TSCT: $K^0 = 0.5$.
- SSCT: $K = (0, 0, -0.25)$.
- Helicities: $h_{ee} = h_{mm} = 0.25$.
- Cross helicities: $h_{em} = -h_{me} = 0$.  

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Conformal transformations: We used the conformal transformation (3.12) to generate new solutions from the plane wave. The action of such a transformation on the Hopfon solution can generate new solutions with finite energy and helicity for some finite range of values of the parameter of the transformation. Let us consider $\mu_\beta$ as $(0, i\frac{1}{2}, 0, 0)$. We can compute the charges numerically for $E = 1$:

- Momentum: $P = (0.286, 0, -0.429)$.
- Angular momentum: $L = (0.286, 0, 0.571)$.
- Boosts: $B_\alpha = (0, 0.286, 0)$.
- Dilatations: $D = 0$.
- TSCT: $K^0 = 1.714$.
- SSCT: $K = (-1.143, 0, -0.5714)$.
- Helicities: $h_{ee} = h_{mm} = 0.571$.
- Cross helicities: $h_{em} = -h_{me} = 0$.

Figure 5(b) shows the electric and magnetic field lines for this solution. We can see that the lines are still linked once like Hopfions, but they are deformed. Figure 6 gives a comparison of the energy density (in a plane orthogonal to total momentum) at various times for the Hopfion and the solution found from performing a SCT on the Hopfion with $\mu_\beta$ as $(0, i\frac{1}{2}, 0, 0)$. This comparison clearly illustrates the different nature of the new solution and the Hopfion.

Let us consider the example where the solution is mapped to a solution with constant electric and magnetic fields. For $b^\mu = i(-1, 0, 0, 0)$, the new $\alpha, \beta$ obtained by this map is given by (2.15). The corresponding electric and magnetic fields are constants, as we have seen before, and thus have diverging total energy and helicity. We can study solutions generated by $b^\mu = i(-b, 0, 0, 0)$, with $b$ approaching unity. The radius of the compact electric and magnetic lines increases monotonically to $\infty$ as $b$ approaches unity. This is consistent with the fact that at $b = 1$, we have solutions with constant electric and magnetic fields.
4. Formal aspects of Bateman’s construction and knot solutions

In this section we present a series of results regarding Bateman’s construction and knot solutions that we find interesting and that we have not found explicitly in the existing literature. A summary as follows:

- We present Bateman’s construction in a covariant form.
- We provide expressions for the helicities in terms of integrals over the target space of $\alpha$, $\beta$. We show explicitly that the cross helicities are zero for $(p, q)$-knots.
- We present a quaternionic formulation of Bateman’s construction and relate knot solutions to winding solutions of a non-abelian gauge theory.

4.1. Covariant formulation

Our goal is to write the equations (2.3) and (2.5) in a covariant way\(^7\). We will be using mostly plus signature for the space-time metric. The Levi–Civita symbol is defined as,

$$\epsilon_{ijk} = \epsilon^{ijk}.$$  \hspace{1cm} (4.1)

\(^7\) It was pointed out by an unknown referee that a covariant formulation of Bateman’s construction was also considered in [34].
Equation (2.3) can be written as,
\[ E^i + iB^i = e^{ijk} \partial_i \alpha \partial_j \beta. \]  
(4.2)

Rewriting the equation above in terms of the anti-symmetric field strength \( F_{\mu\nu} \),
\[ F^{0i} + \frac{1}{2} e^{ijk} F_{jk} = e^{ijk} \partial_i \alpha \partial_j \beta, \]  
(4.3)

where we have used \( E^i = F^{0i} \) and \( B^i = \frac{1}{2} e^{ijk} F_{jk} \). This can be written in covariant form as,
\[ F^{\mu\nu} - \frac{1}{2} e^{\mu\nu\rho\sigma} F_{\rho\sigma} = -e^{\mu\nu\rho\sigma} \partial_\rho \alpha \partial_\sigma \beta, \]  
(4.4)

where we define the epsilon tensor as,
\[ \epsilon_{ijk} = \epsilon_{ijk}; \quad \epsilon_{bij} = -\epsilon_{ijk}. \]  
(4.5)

Now the \((i, j)\)-components of \( F^{\mu\nu} \) are,
\[ F^{ij} - i\epsilon^{ijk} F_{k0} = -\epsilon^{ijk} (\partial_i \alpha \partial_j \beta - \partial_i \alpha \partial_j \beta). \]  
(4.6)

This is the same as,
\[ e^{ijk} B_k = i\epsilon^{ijk} E_k = e^{ijk} (\partial_i \alpha \partial_j \beta - \partial_i \alpha \partial_j \beta), \]  
(4.7)

which is equivalent to,
\[ B_k - iE_k = (\partial_i \alpha \partial_j \beta - \partial_i \alpha \partial_j \beta). \]  
(4.8)

Multiplying both sides by \( i \),
\[ E_k + iB_k = i(\partial_i \alpha \partial_j \beta - \partial_i \alpha \partial_j \beta). \]  
(4.9)

which is the same as (2.5). Therefore (4.4) contains all the information about the equations of motion. If we use the identity,
\[ \epsilon_{\mu
u\rho\sigma} e^{\mu
u\rho\sigma} = -2 \left( \delta_{\rho_1}^{\sigma_1} \delta_{\sigma_2}^{\sigma_2} - \delta_{\rho_1}^{\sigma_2} \delta_{\sigma_1}^{\sigma_1} \right), \]  
(4.10)

we can show that the combination of field strengths appearing in Bateman’s construction is imaginary anti-self dual
\[ -\frac{1}{2} e^{\alpha\rho} \left[ F^{\mu\nu} - \frac{1}{2} e^{\mu\nu\rho\sigma} F_{\rho\sigma} \right] = F^{\alpha\rho} - \frac{1}{2} e^{\alpha\mu\nu\rho} F_{\mu\nu\rho}. \]  
(4.11)

We can also obtain covariant formulas for the potentials in terms of \( \alpha \) and \( \beta \). From (4.4),
\[ F^{\mu\nu} = -e^{\mu\nu\rho\sigma} \text{Re} \left( \partial_\rho \alpha \partial_\sigma \beta \right), \]  
(4.12)

\[ e^{\mu\nu\rho\sigma} F_{\rho\sigma} = 2e^{\mu\nu\rho\sigma} \text{Im} \left( \partial_\rho \alpha \partial_\sigma \beta \right), \]  
(4.13)

we can rewrite the second equation (4.13) as,
\[ F_{\mu\nu} = \text{Im} \left( \partial_\mu \alpha \partial_\nu \beta - \partial_\mu \alpha \partial_\nu \beta \right) = \partial_\mu A_\nu - \partial_\nu A_\mu, \]  
(4.14)

where,
\[ A_\mu = \text{Im} \left( H_\mu \right); \quad H_\mu = \frac{1}{2} (\alpha \partial_\mu \beta - \beta \partial_\mu \alpha). \]  
(4.15)
The expression of the gauge potential $A_\mu$ or the complex potential $H_\mu$ is unique up to gauge transformations. We can also define a complex field strength corresponding to $H_\mu$ as

$$H_{\mu\nu} = \partial_\mu H_\nu - \partial_\nu H_\mu,$$

so that $F_{\mu\nu} = \text{Im} \left( H_{\mu\nu} \right)$. Similarly let us define $C_\mu$ and $G_{\mu\nu}$ as,

$$G_{\mu\nu} = \frac{1}{2} e_{\mu\nu\rho\sigma} F^{\rho\sigma} = \partial_\mu C_\nu - \partial_\nu C_\mu. \quad (4.16)$$

Then, up to a gauge choice,

$$C_\mu = \text{Re} \left( H_\mu \right). \quad (4.17)$$

Spatial components of $A_\mu$, $C_\mu$ and related to electric and magnetic fields as,

$$E^i = \epsilon^{ijk} \partial_j C_k; \quad B^i = \epsilon^{ijk} \partial_j A_k. \quad (4.18)$$

Then the first equation (4.12) can be rewritten in terms of the complex field strength as,

$$\text{Im} \left( H^{\mu\nu} \right) = -\frac{1}{2} e^{\mu\nu\rho\sigma} \text{Re} \left( H_{\rho\sigma} \right). \quad (4.19)$$

The equation above along with the definition of $H_{\mu\nu}$ in terms of the potential is equivalent to Maxwell’s equations of motion. We can also define a helicity or abelian CS current as,

$$\kappa^\mu = \epsilon^{\mu\nu\rho\sigma} A_\nu F_{\rho\sigma}. \quad (4.20)$$

We can show that this current is conserved for the null solutions as,

$$\partial_\mu \kappa^\mu = \frac{1}{2} e^{\mu\nu\rho\sigma} F_{\mu\nu} F_{\rho\sigma} \propto E \cdot B = 0, \quad (4.21)$$

also,

$$\kappa^0 = -\epsilon^{ijk} A_i F_{jk} = -2 A_i B^i; \quad h_{mn} = -\frac{1}{2} \int d^3x \kappa^0. \quad (4.22)$$

### 4.2. Helicities

In most cases we have to compute the conserved charges of a given solution by evaluating the charge densities on the solution and performing a complicated integral over space. This makes the comparison between different kind of solutions quite cumbersome. However, for the $(p, q)$-knots it turns out that the situation is dramatically improved for the helicities. Indeed, one can find closed expressions in terms of integrals over the target space, which are valid independent of the particular form of the solution in space and time. It is even possible to prove that the cross helicities vanish, as we will show in the following.

Let us define the complex two-form field $H$, related to the electromagnetic field strength $F$ (not to be confused with RS vector $\mathbf{F}$) as

$$H = iF + *F = df \wedge dg,$$

where $*$ represents the Hodge dual, which in terms of the components,

$$\left( *F \right)_{\mu\nu} = \frac{1}{2} e_{\mu\nu\rho\sigma} F^{\rho\sigma}. \quad (4.24)$$

The relation to the complex vector $\mathbf{F} = E + i\mathbf{B}$ is

$$H_{\mu 0} = i(f), \quad H_{ij} = i\epsilon_{ijk}(F)^k. \quad (4.25)$$
It will be convenient to solve the field strength and the dual in terms of the complex form $H$,

$$F = \frac{H - \bar{H}}{2i},$$  \hspace{1cm} (4.26)

$$*F = \frac{H + \bar{H}}{2},$$  \hspace{1cm} (4.27)

where $\bar{H}$ is the complex conjugate of $H$. Let $F = dA$, $*F = dC$ and $H = dh$. Then, the potentials can be written in the following form

$$A = \frac{h - \bar{h}}{2i},$$ \hspace{1cm} (4.28)

$$C = \frac{h + \bar{h}}{2},$$ \hspace{1cm} (4.29)

$$h = \frac{1}{2}(f dg - g df).$$ \hspace{1cm} (4.30)

The cross helicity density $h_{em}$ is given by the space integral of the following expression,

$$\chi_{em} = C \wedge F = \frac{1}{4i}(\bar{h} \wedge H - h \wedge \bar{H}).$$ \hspace{1cm} (4.31)

For $(p, q)$-knot solutions we simply need to evaluate $\chi_{em}$ for $f = \alpha^p, \ g = \beta^q$,

$$h = \frac{1}{2}(\alpha^p d(\beta^q) - \beta^q d(\alpha^p)) = \alpha^{p-1}\beta^q\frac{1}{2}(qa d\beta - p\beta d\alpha),$$ \hspace{1cm} (4.32)

$$H = d(\alpha^p) \wedge d(\beta^q) = pq\alpha^{p-1}\beta^q d\alpha \wedge d\beta,$$ \hspace{1cm} (4.33)

$$|\alpha|^2 + |\beta|^2 = 1.$$ \hspace{1cm} (4.34)

Substituting the above into (4.31),

$$\chi_{em} = \frac{pq}{8i}|\alpha|^{p(q-1)}|\beta|^{q(q-1)} (q \ d(\alpha d\beta) \wedge d\beta \wedge d\beta + p \ d(\beta d\alpha) \wedge d\alpha \wedge d\alpha) = 0,$$ \hspace{1cm} (4.35)

where we have used (4.34) to show that it vanishes. Since $h_{em} = -h_{me}$, both the cross helicities are zero for this class of solutions.

The helicity ($h_{mm}$) is given by the space integral of the following form,

$$\chi_{mm} = A \wedge F = \frac{1}{4}(h \wedge \bar{H} + \bar{h} \wedge H).$$ \hspace{1cm} (4.36)

Let us try to evaluate $\chi$ again for solutions of type $(f = \alpha^p, \ g = \beta^q)$ where $\alpha, \beta$ satisfies (4.34). $H, h$ are given by (4.33) and (4.32). We can parametrize $\alpha, \beta$ as,

$$\alpha = \cos(\phi)e^{i\theta_1},$$ \hspace{1cm} (4.37)

$$\beta = \sin(\phi)e^{i\theta_2},$$ \hspace{1cm} (4.38)

$$d\alpha = -\sin(\phi)e^{i\theta_1}d\phi + \cos(\phi)e^{i\theta_1}d\theta_1,$$ \hspace{1cm} (4.39)

$$d\beta = \cos(\phi)e^{i\theta_2}d\phi + \sin(\phi)e^{i\theta_2}d\theta_2.$$ \hspace{1cm} (4.40)
From these formulas we can show,
\[ d\beta \wedge d\alpha \wedge d\bar{\alpha} = -2 \sin^2(\phi) \cos(\phi) e^{i\theta_1} d\phi \wedge d\theta_1 \wedge d\theta_2. \] (4.41)
\[ d\alpha \wedge d\beta \wedge d\bar{\beta} = -2 \sin(\phi) \cos^2(\phi) e^{i\theta_2} d\phi \wedge d\theta_1 \wedge d\theta_2. \] (4.42)

Also,
\[ \chi_{mn} = \frac{Pq}{8} |\alpha|^{2(q-1)} |\beta|^{2(p-1)} \left( q \bar{d} \alpha \wedge d\beta \wedge d\bar{\beta} + p \bar{d} \beta \wedge d\alpha \wedge d\bar{\alpha} + cc \right) \] (4.43)
\[ = -\frac{Pq}{2} \cos^{2(p-1)} \phi \sin^{2q-1} \phi \left( q \cos^2 \phi + p \sin^2 \phi \right) \sin \phi \wedge d\theta_1 \wedge d\theta_2. \] (4.44)

Note that \( \alpha \) and \( \beta \) for the Hopfion solution at time \( t = 0 \) are simply the inverse of the stereographic projection of the three-sphere \(|\alpha|^2 + |\beta|^2 = 1\) onto the space. Since this is a one-to-one mapping, we can trade the integral over space for an integral over the \( S^3 \) parametrized by \( \alpha \) and \( \beta \). Then,
\[ h_{mn} = -\int_{S^3} \chi_{mn} \]
\[ = \frac{4\pi^2pq}{2} \int_0^{\pi/2} d\phi \left( q \cos^{2p+1} \phi \sin^{2q-1} \phi + p \cos^{2q-1} \phi \sin^{2p+1} \phi \right). \] (4.45)

Now, using the identity
\[ \int_0^{\pi/2} d\theta \sin(\theta)^m \cos(\theta)^n = \frac{\Gamma \left( \frac{m+1}{2} \right) \Gamma \left( \frac{n+1}{2} \right)}{2 \Gamma \left( \frac{m+n+2}{2} \right)} \], (4.46)
we find the following value of the helicity
\[ h_{mn} = 2\pi^2 \frac{pq}{2} \frac{\Gamma(p+1) \Gamma(q+1)}{\Gamma(p+q+1)} = 2\pi^2 \frac{pq}{p+q} \frac{p!q!}{(p+q)!}, \] (4.47)
for \( p = q = 1 \). \( \int_{S^3} \chi = \pi^2 \). Note the result is symmetric under interchange of \( (p, q) \). For more general holomorphic functions of \( \alpha, \beta \) satisfying (4.34), we find the following expressions for the helicity density:
\[ h = \frac{1}{2} (f(\alpha, \beta) \overline{d(g(\alpha, \beta))} - g(\alpha, \beta) \overline{d(f(\alpha, \beta))}), \] (4.48)
\[ H = d(f(\alpha, \beta)) \wedge \overline{d(g(\alpha, \beta))}, \] (4.49)
\[ \chi_{mn} = \frac{1}{2} \left[ \text{Re} \left( \frac{\partial f \partial \beta \bar{g} - (\partial_{\alpha} \bar{g} \partial_{\beta} f)(f \partial_{\alpha} \bar{g} - g \partial_{f} \alpha)}{\beta} \right) \sin^3(\phi) \cos(\phi) \right] \]
\[ - \text{Re} \left( \frac{\partial f \partial \beta \bar{g} - (\partial_{\alpha} \bar{g} \partial_{\beta} f)(f \partial_{\alpha} \bar{g} - g \partial_{f} \alpha)}{\alpha} \right) \sin(\phi) \cos^3(\phi) \]
\[ d\phi \wedge d\theta_1 \wedge d\theta_2. \] (4.50)
4.3. Quaternionic formulation and map to non-abelian theories

There is an interesting map between Bateman’s construction and quaternions that can be used to embed the Hopfion solution in a non-abelian Yang–Mills theory. The non-abelian solution is pure gauge with a winding number different to zero. Similar embeddings of knot solutions have been studied in the past [29–31], the main differences in this case are that the knot is not static and that it is a solution of Maxwell’s theory.

Using \( \alpha \) and \( \beta \) we can define a quaternion \( q \),

\[
q = \frac{1}{m} (\alpha + \beta j), \tag{4.51}
\]

\[
m = \sqrt{|\alpha|^2 + |\beta|^2}, \tag{4.52}
\]

\[
\alpha = \alpha_0 + \alpha_1 t; \quad \beta = \beta_0 + \beta_1 t, \tag{4.53}
\]

where \( \alpha_0, \alpha_1, \beta_0, \beta_1 \) are real functions depending on space-time. The conjugate quaternion is

\[
q^* = \frac{1}{m} (\alpha^* - \beta j). \tag{4.54}
\]

We will define the following quaternionic-valued potential:

\[
Q_\mu = q (\partial_\mu q^*). \tag{4.55}
\]

We can easily show that,

\[
Q_\mu = -Q^*_\mu. \tag{4.56}
\]

We will write the components of the quaternionic potential in the following form:

\[
Q_\mu = \frac{1}{m^2} \text{Im} \left( \alpha \partial_\mu \alpha^* + \beta \partial_\mu \beta^* \right) i - \frac{2}{m^2} H_\mu j. \tag{4.57}
\]

where the complex potential \( H_\mu \) is defined in (4.15).

Associated to the quaternionic potential we can define a quaternionic field strength,

\[
Q_{\mu\nu} = \partial_\nu Q_\mu - \partial_\mu Q_\nu = \left( \partial_\nu q_\mu q^* - \partial_\nu q_\mu q^* \right). \tag{4.58}
\]

Then,

\[
Q_{\mu\nu} = \frac{2}{m^2} \text{Im} \left( \partial_\nu \alpha \partial_\mu \alpha^* + \partial_\nu \beta \partial_\mu \beta^* \right) i - \frac{2}{m^2} H_{\mu\nu} j + J_{\mu\nu}. \tag{4.59}
\]

\[
J_{\mu\nu} = m^2 \partial_\mu \left( \frac{1}{m^2} \right) Q_\nu - m^2 \partial_\nu \left( \frac{1}{m^2} \right) Q_\mu. \tag{4.60}
\]

Note that \( J_{\mu\nu} = 0 \) for cases where \( m \) is constant. The equation of motion given by (4.19) can be rewritten as,

\[
\left( Q^{\mu\nu} - J^{\mu\nu} \right) _\kappa = -\frac{1}{2} \epsilon_{\mu\rho\sigma} \left( Q_{\rho\sigma} - J_{\rho\sigma} \right) _\kappa, \tag{4.61}
\]

since,

\[
q q^* = 1. \tag{4.62}
\]
Then we can show,

\[ Q_{\mu\nu} = \partial_\mu Q_\nu - \partial_\nu Q_\mu = -[Q_\mu, Q_\nu]. \]  (4.63)

Note that we can interpret (4.55) as a non-abelian $SU(2)$ gauge potential using Pauli matrices as a representation of the quaternion components $1, i, j, k$

\[ 1 \equiv 1_{2\times2}, \quad i \equiv -i\sigma_1, \quad j \equiv -i\sigma_2, \quad k \equiv -i\sigma_3. \]  (4.64)

Using (4.63) it is clear that the non-abelian field strength is zero and therefore this is a pure gauge solution. We will show now that the winding number is non-zero and in fact it is directly related to the helicities of the abelian solution.

### 4.3.1. Winding number of non-abelian solutions.

The winding number of non-abelian solutions is measured by the integral over space of the CS three-form

\[ w = -\frac{1}{8\pi^2} \int_{S^3} \text{tr} \,(K). \]  (4.65)

where the CS three-form is

\[ K = Q \wedge dQ + \frac{2}{3} Q \wedge Q \wedge Q. \]  (4.66)

For smooth pure gauge non-abelian configurations in a compact space $w$ is an integer. We can define a current one-form using the Hodge dual $J_{CS} \equiv *K$. We can show that the current is conserved when the non-abelian pure gauge configuration is obtained from a null abelian solution obeying (4.63) $(dQ = -Q \wedge Q)$.

\[ \frac{d}{*} J_{CS} = *dK = *[(dQ + Q \wedge Q) \wedge (dQ + Q \wedge Q) - *Q \wedge Q \wedge Q \wedge Q) \]

\[ = -* (dQ \wedge dQ) \propto E \cdot B = 0. \]  (4.67)

The non-abelian CS current for a solution obeying (4.63) is

\[ J_{CS} = \frac{1}{3} * (Q \wedge dQ). \]  (4.68)

In components, this is

\[ J_{CS}^\mu = \frac{1}{6} \varepsilon^{\mu\nu\rho\sigma} Q_\nu Q_\rho Q_\sigma. \]  (4.69)

Using $Q_\mu = -Q_{\mu}$ we can show,

\[ J_{CS}^\mu = (J_{CS}^\mu)^\dagger. \]  (4.70)

Let us evaluate $J_{CS}^\mu$ in terms of components,

\[ J_{CS}^\mu = \frac{1}{6} \varepsilon^{\mu\nu\rho\sigma} \sum_{a \in \{i, j, k\}} (Q_a)_{\alpha} (Q_{\rho\sigma})_{\alpha} + \cdots. \]  (4.71)

The $\cdots$ denotes terms that are proportional to $i, j, k$, which we can set to zero even without calculation as $J_{CS}^\mu$ is real. Now using (4.60),
\[ J_{\text{CS}}^\mu = \frac{1}{6} \epsilon^{\mu
u\rho\sigma} \sum_{a \in \{i,j,k\}} (Q_a)_a (Q_{\rho a} - J_{\rho a})_a. \]  
(4.72)

We can show that (there is no summation over the index \( a \)),
\[ \epsilon^{\mu\nu\rho\sigma} (Q_a)_a (Q_{\rho a} - J_{\rho a})_a = \frac{4}{m^2} \epsilon^{\mu\nu\rho\sigma} A_\nu F_{\rho\sigma} 1_{2 \times 2} = \frac{4}{m^2} \kappa^\mu 1_{2 \times 2} \quad \forall \alpha \in \{ i, j, k \}, \]  
(4.73)

where \( \kappa^\mu \) (4.20) is the abelian CS current. So the relation between abelian and non-abelian (quaternionic) CS is given by,
\[ J_{\text{CS}}^\mu = \frac{2}{m^4} \kappa^\mu 1_{2 \times 2}. \]  
(4.74)

Both of the currents, \( J_{\text{CS}}^\mu \) and \( \kappa^\mu \) were shown to be conserved in (4.67) and (4.21). This gives a non-trivial constraint on the derivative of \( m \) : \( \kappa^\mu \partial_\mu m = 0 \).

For \( \alpha = \tilde{\alpha}^p, \quad \beta = \tilde{\beta}^q \) with \( |\tilde{\alpha}|^2 + |\tilde{\beta}|^2 = 1 \), \( \int d^3x \kappa_0 = 2 \int x_{\text{min}} \) is calculated for these solutions in (4.44). Then the corresponding winding number of the non-abelian solution is given by
\[ w = -\frac{1}{8\pi^2} \int S^1 \text{tr} J_{\text{CS}}^0 = -\frac{2}{8\pi^2} \int S^3 \frac{4}{m^2} x_{\text{min}} \]  
\[ = \frac{2}{8\pi^2} \int_{\pi/2}^{\pi/2} d\phi \left( \cos(\phi)^{2p} + \sin(\phi)^{2q} \right)^2 \frac{4\pi^2 pq}{2} \times \left( q \cos^{2p+1} \phi \sin^{2q-1} \phi + p \cos^{2p-1} \phi \sin^{2q+1} \phi \right) \]  
(4.75)

In contrast with the values of the abelian helicities, which were not integers, the corresponding non-abelian winding number is quantized in integer values. Note that the Hopfion solution has winding number \( w = 1 \) as expected. We can also use the abelian Hopfion solution to construct higher winding non-abelian solutions. Consider the non-abelian (quaternionic) potential,
\[ \tilde{Q}_\mu = \tilde{q} \left( \partial_\mu \tilde{q}^* \right) \]  
(4.76)

where,
\[ \tilde{q} = \tilde{\alpha} + \tilde{\beta} j = q^\alpha = (\alpha + \beta j)^\alpha. \]  
(4.77)

Note that,
\[ \tilde{q} \tilde{q}^* = \left( \tilde{q} \tilde{q}^* \right)^n = 1 \]  
(4.78)

and \( \alpha, \beta \) are given by the abelian solutions (2.19) and (2.20). The non-abelian gauge potential \( \tilde{Q}_\mu \) naturally gives a flat gauge connection due to its structure. We expect these to be solutions with a winding number \( n \)-times that of the solution with a potential given by \( q \), we have checked for \( n = 2 \) that this is indeed the case. These higher winding non-abelian solutions \( \tilde{\alpha} \) and \( \tilde{\beta} \) are not solutions of Maxwell’s equations.

5. Summary

In this paper we have further developed the study of topologically non-trivial solutions of electrodynamics. We have discovered a novel method of generating such solutions by applying
conformal transformations with complex parameters on known solutions expressed in terms of Bateman’s variables. This in fact enabled us to obtain a wide class of solutions from the basic configuration of constant electric and magnetic fields. We have introduced a covariant formulation of Bateman’s construction and discussed the conserved charges associated with the conformal group as well as a set of four types of conserved helicities. One way to implement the covariant formulation is to use a quaternionic formulation. This led to a simple map between the electromagnetic knotted solutions into flat connections of $SU(2)$ gauge theory. We computed the corresponding CS charge and showed that it takes an integer value.

There is an great variety of open questions related to the study of the knotted solutions of electrodynamics. Here we mention few of them.

- Obviously the most interesting issue is how to realize the Hopfion or any of its cousins in the laboratory. The question is whether we can supply our experimental colleagues with additional information that will enable them to produce these non-trivial electromagnetic configurations. A proposal for constructing Hopf solutions in a laboratory was given in [8].
- The solutions discussed in this paper, from the constants $E$ and $B$ all the way to the generalization of the Hopfions, were expressed in Cartesian coordinates. Obviously there are electromagnetic configurations that are naturally described in cylindrical and spherical coordinates. One can search for their expressions in terms of Bateman’s variables which will now be complex functions of spherical, cylindrical or more general coordinates. Performing the conformal transformation with complex coordinates can also be performed using various different coordinate systems.
- An interesting question is obviously deciphering the trajectories of charged particles in the topologically non-trivial electromagnetic fields. Do these trajectories admit some topology? A class of charged particle trajectories in a Hopfion background was studied numerically in [10]. A more general question is looking for similar topological solutions to the equations of motion of electrodynamics coupled to currents and charge densities.
- A more theoretical issue is the classification of all solutions that follow from Bateman’s construction; the class of solutions based on taking any holomorphic function of the basic Hopfion $\alpha$ and $\beta$, as well as all other solutions that one obtains by applying all possible conformal transformations with complex parameters.
- A similar issue relates to the classification of the corresponding $SU(2)$ flat gauge connections. Are there $SU(2)$ flat gauge connections that cannot be mapped into the electromagnetic topologically non-trivial configurations? If yes, what characterizes those that can be mapped?
- We have mentioned that the solutions found in this note are in fact valid in any conformal flat background of which $AdS_4$ (anti-de Sitter four-dimensional space-time) is a special case. One may wonder in the context of holography [35–37] with electromagnetic fields in the bulk, what are the corresponding dual (topological?) configurations on the boundary conformal field theory?

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Appendix A. Noether charges

Let us consider a gauge potential $A_\mu$ and the corresponding field strength $F_{\mu\nu} = \partial_\mu A_\nu - \partial_\nu A_\mu$ to be solutions of four-dimensional vacuum Maxwell equations $\partial_\mu F^{\mu\nu} = 0$. The electric and magnetic fields are given by,

$$E^i = F^{0i} = F_{0i}$$

$$B^i = \frac{1}{2} \epsilon^{ijk} F_{jk} \quad \text{or} \quad F_{ij} = \epsilon_{ijk} B^k$$

where we have assumed a mostly positive signature for the space-time metric. Then,

$$-\frac{1}{4} F_{\mu\nu} F^{\mu\nu} = \frac{1}{2} (E \cdot E - B \cdot B)$$

The stress–energy tensor is

$$T_{\mu\nu} = -F_{\mu\rho} F^{\rho\nu} + \frac{1}{4} \eta_{\mu\rho} F_{\alpha\beta} F^{\alpha\beta}$$

Explicit expressions of the components of the stress–energy tensor are

$$T_{00} = \frac{1}{2} (E \cdot E + B \cdot B)$$

$$T_{0i} = -(E \times B)_i$$

$$T_{ij} = \delta_{ij} \frac{1}{2} (E \cdot E + B \cdot B) - E_i E_j - B_i B_j$$

The stress–energy tensor satisfies,

$$\partial_\mu T^{\mu\nu} = 0; \quad T^{\mu\nu} = 0.$$ 

Then the list of conserved charge densities from conservation of the stress tensor are given by,

Energy: \( \mathcal{E} = T^{00} = \frac{1}{2} (E \cdot E + B \cdot B) \).

Momentum: \( p^i = T^{0i} = (E \times B)_i \).

Now let us consider the conserved current corresponding to the Lorentz symmetry,

$$J_{\lambda}^{(a\beta)} = T^{\mu a} x_\beta - T^{\mu\beta} x_a$$

$$\partial_\mu J_{\lambda}^{(a\beta)} = T^{\lambda a\beta} - T^{\lambda\beta a} = 0$$

using the symmetry properties of the stress tensor. The corresponding charges are given by, $J_{\lambda}^{(a\beta)}$, which is antisymmetric in $(a, \beta)$. Then the spatial and temporal charges given by $J_{\lambda}^{0(\alpha\beta)}$ are,
Momentum: \( l' = \sum_{j<k} e^{|jk|} J_{jk}^{(j,k)} = (p \times x)' \). (A.13)

Boost: \( b' = J_{(0)}^0 = \mathcal{E}x^i - p't \). (A.14)

Now consider the current corresponding to dilatation symmetry,
\[ J_0^0 = T_\mu^\nu x^\nu \] (A.15)
\[ \partial_\mu J_0^\mu = T_\mu^\nu = 0. \] (A.16)

The corresponding conserved charge density is given by,
\[ \text{Dilatation: } d = J_0^0 = -\mathcal{E}t + \sum_i p^i x^i. \] (A.17)

Now let us consider the current corresponding to the SCT,
\[ J_\mu^{(\nu)} = x^\nu x_\sigma T_\mu^{\sigma \nu} - 2 T_\mu^{\nu \nu} x^\nu x^\nu \] (A.18)
\[ \partial_\mu J_\mu^{(\nu)} = -2 T_\mu^{\nu \nu} x^\nu = 0. \] (A.19)

Then the corresponding temporal and spatial charges are given by,
\[ \text{TSCT: } k_0 = J_\mu^{(0)} = \left( x^i x_i + t^2 \right) \mathcal{E} - 2 m x^i. \] (A.20)
\[ \text{SSCT: } k^i = -J_\mu^{(i)} = 2 x^i p_j x^j - 2 \mathcal{E} t x^i - \left( x^i x_i - t^2 \right) p^i. \] (A.21)

**Appendix B. \( \theta, \phi \) formulation**

**B.1. Hopf index in three dimensions**

Consider a complex scalar field \( \phi(x_1, x_2, x_3) \) defined on \( \mathbb{R}^3 \). Let the field be well defined as \( r \to \infty \), where \( r = \sqrt{x_1^2 + x_2^2 + x_3^2} \), i.e. the map does not depend on the direction. Then the map can be identified as \( \phi: S^3 \to S^2 \), as \( S^3 \equiv \mathbb{R}^3 \cup \{ \infty \} \) and \( S^2 \equiv \mathbb{C} \cup \{ \infty \} \). These classes of maps are generally classified in various homotopy classes specified by a topological invariant called the Hopf index.

Consider the area two-form [5],
\[ \mathcal{P} = \frac{1}{2\pi i} \frac{d\phi^* \wedge d\phi}{1 + \phi \phi^*}. \] (B.1)

Since \( \mathcal{P} \) is closed in \( S^3 \), it must also be exact, i.e. there is a one-form \( A \) such that \( \mathcal{P} = dA \). Then the Hopf index is given by [1],
\[ n = \int_{S^3} A \wedge \mathcal{P}. \] (B.2)

The pull back of the form \( \mathcal{P} \) in \( \mathbb{R}^3 \) is given by,
\[ \mathcal{P} = \frac{1}{2} F_{ij} dx^i \wedge dx^j = \frac{1}{4\pi i} \frac{\partial \phi \phi^* \partial \phi - \partial \phi \phi^* \partial \phi}{\left( 1 + \phi \phi^* \right)^2} dx^i \wedge dx^j. \] (B.3)
We can also express $F$ in terms of a vector field defined as,

$$B^i = B_i = \frac{1}{2} \epsilon^{ijk} F_{jk}. \quad (B.4)$$

$B = B_i \, dx^i = W(\phi)$ is called the Whitehead vector of the map $\phi$. By definition, $B \cdot \nabla \phi = 0$, i.e. the vector $B$ is always tangential to the surfaces $\phi = \text{constant}$.

Let us parametrize the map $\phi$ as,

$$\phi = S e^{2\pi \psi}; \quad \rho = -\frac{1}{1 + S^2} \quad (B.5)$$

where $S, \psi, \rho$ are real maps from $\mathbb{R}^3 \to \mathbb{R}$. Then,

$$F = d\rho \wedge d\psi; \quad A = \rho d\psi + d\xi. \quad (B.6)$$

$\xi$ is some arbitrary function from $\mathbb{R}^3 \to \mathbb{R}$. Then,

$$n = \int_{S^3} d(\xi d\rho \wedge d\psi) \quad (B.7)$$

is zero by Gauss’ theorem unless $\psi$ or $\rho$ is multiple-valued. We will assume $\psi$ to be multiple-valued and $\nabla \psi$ to be a single-valued function.

**Hopf map.** The simplest example of a map $\phi: S^3 \to S^2$ with a non-zero Hopf index is

$$\phi_H(x, y, z) = \frac{2(x + iy)}{2z + i(r^2 - 1)}; \quad r^2 = x^2 + y^2 + z^2. \quad (B.8)$$

The Hopf index is unity for this map.

**B.2. $(n, m)$-link solutions in $3+1$ dimensions**

Now consider two such maps $\phi, \theta: S^3 \times \mathbb{R} \to S^2$. Then let us consider the electric and magnetic fields to be Whitehead vectors of the two maps, $B = W(\phi)$ and $E = W(\theta)$. The maps now depend on an extra time parameter and, to make the equations consistent with the $3+1$-dimensional Maxwell equations,

$$M_{\mu \nu} = \frac{1}{2} \epsilon_{\mu \nu \rho \sigma} F^{\rho \sigma} \quad (B.9)$$

$$F_{\mu \nu} = f_{\mu \nu}(\phi) = \frac{1}{2\pi i} \frac{\partial_{\mu} \phi^* \partial_{\nu} \phi - \partial_{\nu} \phi^* \partial_{\mu} \phi}{\left(1 + \phi \phi^*\right)^2} \quad (B.10)$$

$$M_{\mu \nu} = f_{\mu \nu}(\theta) = \frac{1}{2\pi i} \frac{\partial_{\mu} \theta^* \partial_{\nu} \theta - \partial_{\nu} \theta^* \partial_{\mu} \theta}{\left(1 + \theta \theta^*\right)^2} \quad (B.11)$$

where$^8$,

$$E_i = F_{i0} = \frac{1}{2} \epsilon_{ijk} M^{jk}; \quad B_i = M_{i0} = \frac{1}{2} \epsilon_{ijk} F^{jk}. \quad (B.12)$$

Note our definitions are the same as those of [5] up to some signs. For solutions parametrized as (B.9)–(B.11), we can show,

$^8$ We define $\epsilon_{ijk} = -\epsilon^{ijk} = \epsilon^{0ik} = \epsilon_{ijk}$. 
\[ \mathbf{E} \cdot \mathbf{B} = \frac{1}{2} \epsilon_{ijkl} M_{(i} M_{j)} = -\frac{1}{2} \epsilon^{\mu
u\rho\sigma} M_{\mu\nu} M_{\rho\sigma} = 0 \]  

(B.13)

as a consequence the helicities defined \((\mathbf{B} = \nabla \times \mathbf{A} \text{ and } \mathbf{E} = \nabla \times \mathbf{C})\) as,

\[ h_x = \int_{S^3} A \cdot B \]  

(B.14)

\[ h_m = \int_{S^3} C \cdot E \]  

(B.15)

are time-independent. Also these are proportional to the Hopf index (B.2) of the two maps \(\theta\) and \(\phi\). Since Hopf indices are integers, the helicities will be given by an integer multiple of some constant number.

**Hopfian I.** The simplest solution with \(h_x = h_m\) is given by [4, 6, 8],

\[ \phi = \frac{(Ax + t(A - 1)) + i(tx - Ay)}{(Ax + ty) + i(A(A - 1) - tz)} \]  

(B.16)

\[ \theta = \frac{(Ax + ty) + i(Az + t(A - 1))}{(tx - Ay) + i(A(A - 1) - tz)} \]  

(B.17)

\[ A = \frac{1}{2} \left( x^2 + y^2 + z^2 - t^2 + 1 \right) \]  

(B.18)

which at \(t = 0\) reduces to Hopf map (B.8),

\[ \phi(t = 0, x, y, z) = \frac{2(z - iy)}{2x + i(r^2 - 1)} = \phi_H(z, -y, x) \]  

(B.19)

\[ \theta(t = 0, x, y, z) = \frac{2(x + iz)}{-2y + i(r^2 - 1)} = \phi_H(x, z, -y). \]  

(B.20)

Vacuum electrodynamics have the conformal group as a symmetry group. A list of conserved charges and their values are given [8] (in units in which energy = 1) in table B1. The energy density of the solution is given by,

\[ \mathcal{E} = \frac{1}{2} (E^2 + B^2) = \frac{16 \left( 1 + x^2 + y^2 + (t + z)^2 \right)^2}{\pi^2 \left( (1 - t^2 + x^2 + y^2 + z^2)^2 + 4r^2 \right)^3}. \]  

(B.21)

The electric field and magnetic field at \(t = 0\) are given by,

\[ \mathbf{E}(t = 0) = \frac{4}{\pi \left( 1 + x^2 + y^2 + z^2 \right)^2} \left( -2(xy + z), \left( x^2 - y^2 + z^2 - 1 \right), -2(yz - x) \right) \]  

(B.22)

\[ \mathbf{B}(t = 0) = \frac{4}{\pi \left( 1 + x^2 + y^2 + z^2 \right)^2} \left( \left( x^2 - y^2 - z^2 + 1 \right), 2(xy - z), 2(xz + y) \right). \]
Then the vector potentials $\mathbf{A}$, $\mathbf{C}$ are given by,

$$\mathbf{C}(t = 0) = \frac{2}{\pi \left(1 + x^2 + y^2 + z^2\right)^2} [-z, -1, x]$$

(B.23)

$$\mathbf{A}(t = 0) = \frac{2}{\pi \left(1 + x^2 + y^2 + z^2\right)^2} [1, -z, y].$$

(B.24)

We can then show that the helicities (in units of energy = 1),

$$h_{ee} = h_{mm} = \frac{1}{2}.$$  

(B.25)

The Fourier transform of the Hopfion solution is written in terms of vector spherical harmonics [8],

$$\mathbf{A}_{lm}^{TE}(k, \mathbf{r}) = \frac{1}{i\omega} \frac{j_{l}(kr)}{\sqrt{l(l+1)}} \mathbf{L} Y_{lm}(\theta, \phi)$$

(B.26)

$$\mathbf{A}_{lm}^{TM}(k, \mathbf{r}) = \frac{1}{k^2} \mathbf{V} \times \left( \frac{j_{l}(kr)}{\sqrt{l(l+1)}} \mathbf{L} Y_{lm}(\theta, \phi) \right)$$

(B.27)

where $\mathbf{L} = -i\mathbf{r} \times \nabla$, $Y_{lm}(\theta, \phi)$ are spherical harmonics and $j_{l}(kr)$ are spherical Bessel functions. Also $l \geq 1$ and $-l < m < l$. Then the vector potential ($B = \nabla \times \mathbf{A}$) for the Hopfion is given by [4, 8],

$$\mathbf{A}(\mathbf{r}, t) = \int_{0}^{\infty} dk \left( \mathbf{A}(k, \mathbf{r}) + \mathbf{A}(k, \mathbf{r})^{*} \right)$$

(B.28)

$$\mathbf{A}(k, \mathbf{r}) = \frac{4}{3\pi} k^{3} e^{-ik} \left[ \mathbf{A}_{1,1}^{TE}(k, \mathbf{r}) - i \mathbf{A}_{1,1}^{TM}(k, \mathbf{r}) \right] e^{-imt}.$$  

(B.29)

The superpositions $\left[A_{1,lm}^{TE} - iA_{1,lm}^{TM}\right]$ are eigenstates of the curl operator and are known as Chandrasekhar–Kendall states.

$$\nabla \times \left[ A_{1,lm}^{TE}(k, \mathbf{r}) \pm iA_{1,lm}^{TM}(k, \mathbf{r}) \right] = \mp k \left[ A_{1,lm}^{TE}(k, \mathbf{r}) \pm iA_{1,lm}^{TM}(k, \mathbf{r}) \right].$$  

(B.30)
The corresponding electric and magnetic fields are then given by,
\[
\mathbf{B}(k, r) = \nabla \times \left( \mathbf{A}(k, r) + \mathbf{A}(k, r)^* \right) = k \left( \mathbf{A}(k, r) + \mathbf{A}(k, r)^* \right) \tag{B.31}
\]
\[
\mathbf{E}(k, r) = -\partial_t \left( \mathbf{A}(k, r) + \mathbf{A}(k, r)^* \right) = i\omega \left( \mathbf{A}(k, r) - \mathbf{A}(k, r)^* \right). \tag{B.32}
\]

**Generalization to \((p, q)\)-knots in the \((\theta, \phi)\) formulation.** There were various attempts to construct general knotted solution with a preserved topological structure in \([9, 12]\). But although helicity was conserved, the topological structure varies with time in the class of solutions described in \([9, 12]\). In a recent paper \([14]\), the authors were able to construct solutions using Bateman’’s construction \([2]\) knotted solutions which preserve their structure over time. Let us describe the prescription given in \([9]\). We can easily generalize to \((p, q)\) -knots by modifying (B.29) as given in \([9]\),
\[
\pi = -\omega \left[ \mathbf{A}_{1,1}^{\text{TE}}(k, r) - i\frac{p}{q} \mathbf{A}_{1,1}^{\text{TM}}(k, r) \right] e^{-k_{\text{int}}}. \tag{B.33}
\]

For general \((p, q)\) co-prime integers, this corresponds to all possible knots. An important point about these solution as emphasized in \([9]\), is that \(E \neq B\) but \(\int \mathbf{E} \cdot \mathbf{B} = 0\). So in these cases the helicity is conserved but if we look at the topological structure of individual field lines, it changes with time. So the knot structure implied by co-prime integers \((p, q)\) is only valid at \(t = 0\).

**Appendix C. Explicit expression of electric and magnetic fields for Hopfion**

The Riemann–Silberstein vector for the Hopfion solution given by (2.19), (2.20) is,
\[
\mathbf{F} = \frac{4}{(A + 2it)^3} \left\{ (t - x - z + i(y - 1))(t + x - z - i(y + 1)) \right. \\
\left. - i(t - y - z - i(x + 1))(t + y - z + i(x - 1)) \right\} 2(x - iy)(t - z - i) \tag{C.1}
\]
where \(A = x^2 + y^2 + z^2 - t^2 + 1\). The electric and magnetic fields can be read of directly from \(\mathbf{F}\) as the real and imaginary parts, respectively. Generally the expressions of the electric and magnetic fields look complicated but can be written in a more compact form as a polynomial in \(A\). We illustrate this for one of the components for the electric field,
\[
E_x = -4 \left[ A^4 - 8 A^3 \left( y^2 + z^2 - t^2 \right) - 12 A^2 t (xy + z) + 24 A t^2 \left( y^2 + z^2 - t^2 \right) \\
+ 16 t^3 (-t + xy + z) \right] / \left( A^2 + 4t^2 \right)^3. \tag{C.2}
\]

For \(t = 0\) this reduces to
\[
E_x(t = 0) = -4 \left( 1 + x^2 - y^2 - z^2 \right) \tag{C.3}
\]
which is identical to \(E_y\) of (B.22) upon interchanging \(x \leftrightarrow y\). At the origin \(\mathbf{r} = 0\) we find
\[
E_x = -4 \frac{(1 - 3t^2)}{(1 + t^2)}. \tag{C.4}
\]
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