Global Well-Posedness of the Incompressible Magnetohydrodynamics

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Abstract

This paper studies the Cauchy problem of the incompressible magnetohydrodynamic systems with or without viscosity $\nu$. Under the assumption that the initial velocity field and the displacement of the initial magnetic field from a non-zero constant are sufficiently small in certain weighted Sobolev spaces, the Cauchy problem is shown to be globally well-posed for all $\nu \geq 0$ and all spaces with dimension $n \geq 2$. Such a result holds true uniformly in nonnegative viscosity parameters. The proof is based on the inherent strong null structure of the systems introduced by Lei (Commun Pure Appl Math 69(11):2072–2106, 2016) and the ghost weight technique introduced by Alinhac (Invent Math 145(3):597–618, 2001).

1. Introduction

Magnetohydrodynamics (MHD) is one of most fundamental equations in magneto-fluid mechanics. It describes the dynamics of electrically conducting fluids arising from plasmas or some other physical phenomena (see, for instance [10]). In this paper, we consider the Cauchy problem for the following incompressible MHD system in $\mathbb{R}^n$ for $n \geq 2$:

$$\begin{cases}
\partial_t v + v \cdot \nabla v + \nabla \tilde{p} = \nu \Delta v - H \times (\nabla \times H), \\
\partial_t H + v \cdot \nabla H = \nu \Delta H + H \cdot \nabla v, \\
\nabla \cdot v = 0, \quad \nabla \cdot H = 0.
\end{cases}$$

(1.1)

Here $v$ represents the velocity, $H$ the magnetic field, $\tilde{p}$ the scalar pressure and $\nu \geq 0$ the nonnegative viscosity constant. We will consider the problem in a strong magnetic background $e$, which is set to be $(1, 0, \ldots, 0) \in \mathbb{R}^n$, without loss of generality. We show that the trivial steady solution $(u, H) = (0, e)$ is nonlinearly stable under small initial perturbations uniformly in $\nu \geq 0$. Such types of solutions
are referred to as Alfvén waves (see, for instance, [2]). The proof is based on the inherent strong null structure of the system which was first introduced for incompressible elastodynamics by the second author in [11] and Alinhac’s ghost weight technique for scalar wave equations [3]. We emphasize that in the presence of a strong magnetic background and viscosity, system (1.1) is not scaling, rotation and Lorentz invariant. Thus Klainerman’s vector field theory is not applicable in our situation.

To put our results into context, let us highlight some recent progress on this system. The local well-posedness of classical solutions for fully viscous MHD is established in [16], in which the global well-posedness is also proved in two dimensions. In [4], C. Bardos, C. Sulem, P.-L. Sulem introduced the following good unknowns:

\[ \Lambda^\pm = v \pm (H - e). \]

In terms of the above good knowns, the MHD system (1.1) can be rewritten as

\[
\begin{align*}
\partial_t \Lambda^+ - e \cdot \nabla \Lambda^+ + \Lambda^- \cdot \nabla \Lambda^+ + \nabla p &= \nu \Delta \Lambda^+, \\
\partial_t \Lambda^- + e \cdot \nabla \Lambda^- + \Lambda^+ \cdot \nabla \Lambda^- + \nabla p &= \nu \Delta \Lambda^-, \\
\nabla \cdot \Lambda^+ &= 0, \quad \nabla \cdot \Lambda^- = 0.
\end{align*}
\]

Here \( p = \tilde{p} + \frac{|H|^2}{2} \). In the inviscid case \( \nu = 0 \), Bardos, Sulem and Sulem proved that system (1.2) is globally well-posed for small initial \( \Lambda^\pm \) in a certain weighted Hölder space. Very recently, for the ideal MHD system (where there is viscosity in the momentum equation but there is no resistivity in the magnetic equation), Lin et al. [14] obtained the global well-posedness in the two-dimensional case for small initial \( u \) and \( H - e \) in appropriate Sobolev spaces (see also some further results in [5,8,19,21]). The three-dimensional case was then solved by Xu and Zhang [20], see also [1,15]. Lei was the first to construct a family of solutions without any smallness constraints in the presence of axis symmetry [12] in three dimensions.

In [11], the second author explored the fact that incompressible elastodynamics automatically enjoys a strong inherent structure. Based on the inherent strong degenerate structure and Alinhac’s ghost technique which was originally introduced in [3], the second author proved the global well-posedness of small solutions to the two-dimensional incompressible elastodynamics. Roughly speaking, we say that a system satisfies a strong null condition if the good unknowns in nonlinearities are always applied by a space or time derivative. For nonlinear wave equations or elastodynamics, good unknowns are the tangential derivative of unknowns along light cones.

For the MHD system (1.2), we observe that the unknown \( \Lambda^+ (\Lambda^-) \) can be viewed as a good unknown in \( \Lambda^+ \)-equation (\( \Lambda^- \)-equation, respectively). On the other hand, in the nonlinearity of \( \Lambda^- \cdot \nabla \Lambda^+ \) in \( \Lambda^+ \)-equation (heuristically, let us first forget about the pressure term), the good unknown \( \Lambda^+ \) is applied by a space derivative \( \nabla \), and \( \Lambda^\pm \) are transported along different characteristics. A similar phenomenon is also true for \( \Lambda^- \)-equation. Thus the strong null structure is present in the incompressible MHD equations (1.2) and global well-posedness is expected for all \( n \geq 2 \). By nature this is philosophically similar to the space-time resonance
introduced by Germain et al. [6]. Note that in the presence of strong magnetic background and viscosity, Klainerman’s vector field theory is not applicable for system (1.2). We will still confirm the intuitive expectation in this article. Our result holds true for all $\nu \geq 0$.

The weighted energy $E_k$, the dissipative ghost weight energy $W_k$, the modified weighted energy $\hat{E}_k$, the dissipative energy $V_k$ and other notations appearing in the following theorems will be explained in Section 2. The first main result of this paper concerns the MHD system without viscosity, which can be stated as follows.

**Theorem 1.1.** Let $\nu = 0$, $1/2 < \mu < 2/3$, $(\Lambda^+_0, \Lambda^-_0) \in H^k(\mathbb{R}^n)$ with $k \geq n + 3$, $n \geq 2$. Suppose that $(\Lambda^+_0, \Lambda^-_0)$ is divergence-free and satisfies

$$
\sum_{1 \leq |a| \leq k} \int_{\mathbb{R}^n} |\langle x \rangle^{2\mu} \nabla^a \Lambda^+_0(x)|^2 + |\langle x \rangle^{2\mu} \nabla^a \Lambda^-_0(x)|^2 \, dx \\
+ \int_{\mathbb{R}^n} |\langle x \rangle^\mu \Lambda^+_0(x)|^2 + |\langle x \rangle^\mu \Lambda^-_0(x)|^2 \, dx \leq \varepsilon.
$$

There exists a positive constant $\varepsilon_0$ which depends only on $k$, $\mu$ and $n$ such that, if $\varepsilon \leq \varepsilon_0$, then the MHD system (1.2) with initial data

$$
\Lambda^+(0, x) = \Lambda^+_0(x) \quad \Lambda^-(0, x) = \Lambda^-_0(x)
$$

has a unique global classical solution which satisfies

$$
E_k(t) + W_k(t) \leq C_0 \varepsilon
$$

for some $C_0 > 1$ uniformly in $t$.

The second main result of this paper is concerned with the MHD system with viscosity, which is stated as follows:

**Theorem 1.2.** Let $\nu \geq 0$, $1/2 < \mu < 2/3$. Let $(\Lambda^+_0(x), \Lambda^-_0(x)) \in H^k(\mathbb{R}^n)$ with $k \geq n + 3$, $n \geq 2$. Suppose that $(\Lambda^+_0(x), \Lambda^-_0(x))$ is divergence-free and satisfies

$$
\sum_{1 \leq |a| \leq k} \int_{\mathbb{R}^n} |\langle x \rangle^{2\mu} \nabla^a \Lambda^+_0(x)|^2 + |\langle x \rangle^{2\mu} \nabla^a \Lambda^-_0(x)|^2 \, dx \\
+ \int_{\mathbb{R}^n} |\langle x \rangle^\mu \Lambda^+_0(x)|^2 + |\langle x \rangle^\mu \Lambda^-_0(x)|^2 \, dx \\
+ \int_{\mathbb{R}^n} |\nabla^{-1} \Lambda^+_0(x)|^2 + |\nabla^{-1} \Lambda^-_0(x)|^2 \, dx \leq \varepsilon.
$$

There exists a positive constant $\varepsilon_0$ which depends only on $k$, $\mu$ and $n$, but is independent of the viscosity $\nu \geq 0$, such that, if $\varepsilon \leq \varepsilon_0$, then the MHD system (1.2) and initial data

$$
\Lambda^+(0, x) = \Lambda^+_0(x) \quad \Lambda^-(0, x) = \Lambda^-_0(x)
$$

has a unique global solution which satisfies

$$
\hat{E}_k(t) + V_k(t) + W_k(t) \leq C_0 \varepsilon
$$

for some $C_0 > 1$ uniformly in $t$. 
Remark 1.1. Theorem 1.1 can be viewed as a generalization of Bardos et al. [4] in the framework of Sobolev spaces.

We emphasize that the viscosity wouldn’t help us during the proof since our result is independent of \( \nu \geq 0 \). At first glance there is no hope of obtaining the time decay of the \( L^\infty \) norm of \( \Lambda^\pm \) since it is transported when looking at the linearized equations. Then the \( L^1 \)-time integrability of the \( L^\infty \) norm of unknowns seems to be a tough task for the global existence of solutions. Some of our ideas are inspired by the recent work of Lei [11] on global solutions for 2D incompressible Elastodynamics and the work of Bardos et al. [4]. As has been observed in [4], when linearizing the system (1.2) with \( \nu = 0 \), one sees that \( \Lambda^+ \) and \( \Lambda^- \) propagate along the background magnetic field \( e \) in opposite directions. In fact, this phenomenon has been found by Alfvén [2]. Our first observation is that the nonlinearities in \( \Lambda^+ \)-equation always contain the good unknown \( \Lambda^+ \), which is applied by a spatial derivative (the same in \( \Lambda^- \)-equation). This gives us the so-called strong null condition of Lei. To capture this strong null structure, we introduce an interactive ghost weight energy (which is a modification of the original one of Alinhac [3]) and perform two different orders of energy estimates with different weights (in the viscous case, we need three different orders of energy estimates with different weights) to yield the fact that energies of good unknowns with appropriate weights are always integrable in time.

Let us explain our strategy in a little bit more detail. In the inviscid case of \( \nu = 0 \), as has been indicated above, it is impossible to obtain the \( L^1 \) time integrability of the \( L^\infty \) norm of all unknowns even in the linear case. Take the \( \Lambda^+ \)-equation as an example, in which we view \( \Lambda^+ \) as the good unknown. We first apply the technique of Alinhac’s ghost weight energy estimate to produce a damping term
\[
\int \frac{|\nabla k \Lambda^+|^2}{(e \cdot x - t)^{2\mu}} \, dx,
\]
which requires that \( \mu > \frac{1}{2} \). To use this damping term to kill the nonlinearity in \( \Lambda^+ \)-equation when doing the energy estimate, motivated by [4], we perform the weighted energy estimate for
\[
\langle x + et \rangle^{4\mu} \nabla k \Lambda^+
\]
instead which produces a damping term
\[
\int \frac{|\langle x + et \rangle^{4\mu} \nabla k \Lambda^+|^2}{(e \cdot x - t)^{2\mu}} \, dx.
\]
Clearly, this damping term is sufficient to kill the nonlinearity \( \nabla k (\Lambda^- \cdot \nabla \Lambda^+) \) if we also add the weight \( \langle x - et \rangle^{2\mu} \) to \( \Lambda^- \) and do a ghost weight energy estimate for \( \langle x \pm et \rangle^{2\mu} \nabla k \Lambda^\pm \) with two different weights, but then we run into a technically difficult situation when estimating the pressure term due to the presence of the non-local Riesz operator. The reason is that one needs to commute certain weights with the Riesz operator in \( L^2 \), but in two dimensions the weights are not of \( A_2 \) class if \( \mu > \frac{1}{2} \). Our strategy is to do energy estimates for \( \langle x + et \rangle^{\mu} \Lambda^+ \) and \( \langle x + et \rangle^{2\mu} \nabla k \Lambda^+ \) \( (k \geq 1) \), respectively, with different weights. More details are presented in Section 4. We emphasize that in three dimensions the argument is much easier, since the weights are of \( A_2 \) class for \( \frac{1}{2} \mu < \frac{3}{4} \) and the pressure term can be estimated by using weighted Calderon–Zygmund theory.

When the viscosity is present, the problem is more involved. The main difficulty is that the weights \( \langle x \pm et \rangle^{2\mu} \) are not compatible with the dissipative system. To see this, let us take the \( L^2 \) inner product of the \( \nabla k \Lambda^+ \) equation of (1.2) with \( \langle x + et \rangle^{4\mu} \nabla k \Lambda^+ \) to derive that (below we have ignored the ghost weight for the simplicity of presentation of ideas)
\[
\frac{1}{2} \partial_t \int_{\mathbb{R}^n} |(x + et)^{2\mu} \nabla^k \Lambda^+|^2 \, dx + \nu \int |(x + et)^{2\mu} \nabla \nabla^k \Lambda^+|^2 \, dx \\
= -2\nu \int (\nabla (x + et)^{2\mu} \cdot \nabla) \nabla^k \Lambda^+ \cdot (x + et)^{2\mu} \nabla \Lambda^+ \, dx + \cdots, \quad k \geq 1,
\] (1.3)

and take \( L^2 \) inner product of the \( \Lambda_+ \) equation of (1.2) with \( (x + et)^{2\mu} \Lambda^+ \) to get
\[
\frac{1}{2} \partial_t \int_{\mathbb{R}^n} |(x + et)^{\mu} \Lambda^+|^2 \, dx + \nu \int |(x + et)^{\mu} \nabla \Lambda^+|^2 \, dx \\
= -2\nu \int (\nabla (x + et)^{\mu} \cdot \nabla) \Lambda^+ \cdot (x + et)^{\mu} \Lambda^+ \, dx + \cdots.
\] (1.4)

The right hand side of (1.3) will be killed by certain combination of dissipative terms on the left hand sides of (1.3)–(1.4) for \( k \geq 0 \). To control the remaining term on the right hand side of (1.4), our strategy is to do an extra \(-1\) order energy estimate without weights. The strong null structure of nonlinearities is the key to closing the above arguments.

The remaining part of this paper is organized as follows. In Section 2 we will introduce some notations and some preliminary estimates. The pressure gradient will be estimated in Section 3. Section 4 is devoted to energy estimate of MHD without viscosity. In Section 5, we will prove the energy estimate in the presence of viscosity.

**Remark 1.2.** After the completion of this work, it came to our attention that He et al. [9] proved similar results in the three-dimensional case. The arXiv number of their paper is arXiv:1603.08205, which is earlier than ours (arXiv:1605.00439). However, these two works are independent of each other. On one hand, their proof is inspired by the nonlinear stability of Minkowski space-time [7] and based on some observations on conformal symmetry structure of the system, but ours are closely related to the combined generalized energy methods of Klainerman and Alinhac which are extensively used in the context of nonlinear wave equations. On the other hand, there are also many differences between these two works. Firstly, our proof works for both two and three dimensions. At least for us, their proof seems not to be automatically applied to the two dimensional case, since the Hardy inequality played a key role in their proof (in two dimensions the use of Hardy inequality will lead to a logarithmic loss, which turns out to be a key difficulty in the context of nonlinear wave equations, see [3,11,13]). Secondly, for the higher-order energy estimate, they used the vorticity of the fluid and the magnetic field to avoid a direct estimate of the pressure, while we directly worked on the velocity, magnetic field and the pressure themselves. Our argument relies on the inherent strong null structure of the system introduced by the second author years ago. Thirdly, they use a kind of ‘quasi-linear’ approach to study the problem. Specifically speaking, the characteristic surfaces are defined by the solution and the choice of weight also depends on the solution. This method goes back to the work on nonlinear stability of Minkowski spacetime by Christodoulou and Klainerman in general relativity [7]. Compared with theirs, our method is a ‘linear’ approach. Finally, we emphasize
that the weights applied to data are quite similar in these two works. For us, these kinds of weights are very common. One can trace back to the work of Themases and Sideris \cite{18} and our earlier work \cite{11,13} on incompressible elastodynamics, in which the data is assumed to satisfy \( \| < x >^k \nabla^k u_0 \|_{L^2} \ll 1 \) for all \( 0 \leq k \leq s \) for some integer positive \( s \).

2. Preliminaries

In this section we will first introduce the notations for the weighted energy \( E_k \), the dissipative ghost weight energy \( W_k \), the modified weighted energy \( \mathcal{E}_k \), the dissipative energy \( V_k \), etc. Then we study the commutation property of weights with the equations. We will also give an elementary imbedding inequality.

2.1. Notations

We first introduce some notations. Partial derivatives with respect to Eulerian coordinate are abbreviated as \( \partial_t = \frac{\partial}{\partial t}, \partial_i = \frac{\partial}{\partial x_i}, \nabla = (\partial_1, \ldots, \partial_n) \). The mix norm \( \| f \|_{L^p_t L^q_x} \) means \( \| f(t, x) \|_{L^q(\mathbb{R}^n)} \|_{L^p([0, t])} \). When \( p = q \), we use the abbreviation \( \| f \|_{L^p_t L^q_x} \).

As in \cite{4}, we will estimate the energies of unknowns with weights. It is clear that \( \Lambda^\pm(t, x) = \phi(x \pm et), \quad p(t, x) = 0 \) are solutions of the linearized equations when viscosity \( \nu = 0 \). This motivates us to choose \( \phi(x \pm et) \Lambda^\pm(t, x) \) as unknowns for some weight function \( \phi \). Below we will choose \( \phi(x) = \langle x \rangle^{2\mu} (\frac{1}{2} < \mu < \frac{2}{3}) \) for higher-order energy estimate, and \( \phi(x) = \langle x \rangle^\mu \) for zero-order energy estimate, in which \( \langle \sigma \rangle = \sqrt{1 + |\sigma|^2} \). Such a choice of different weights is to make full use of the inherent strong degenerate structure of the system.

In the inviscid case of \( \nu = 0 \), we define the weighted energy for the MHD system (1.2) as follows:

\[
E_k(t) = \sum_{1 \leq |a| \leq k} \int_{\mathbb{R}^n} |\langle x + et \rangle^{2\mu} \nabla^a \Lambda^+(x, t)|^2 + |\langle x - et \rangle^{2\mu} \nabla^a \Lambda^-(x, t)|^2 dx
+ \int_{\mathbb{R}^n} |\langle x + et \rangle^\mu \Lambda^+(x, t)|^2 + |\langle x - et \rangle^\mu \Lambda^-(x, t)|^2 dx.
\]

We emphasize that in the above we use different weights for the lowest and higher order energies. Such a choice will be used to take care of the pressure terms.

In the viscous case of \( \nu > 0 \), we introduce an extra energy of \(-1\) order. More precisely, we define the modified weighted energy by

\[
\mathcal{E}_k(t) = E_k(t) + \int_{\mathbb{R}^n} |\nabla^{-1} \Lambda^+(x, t)|^2 + |\nabla^{-1} \Lambda^-(x, t)|^2 dx.
\]

The introduction of \(-1\) order energy will be used to kill some extra term caused by viscosity. We remark that no weight is applied on this lowest order energy.
To make the argument of the energy estimate simpler, we also introduce the two extra notations for energies:

\[ \tilde{E}_k(t) = \sup_{0 \leq \tau \leq t} E_k(\tau), \quad \tilde{E}_k(t) = \sup_{0 \leq \tau \leq t} \mathcal{E}_k(\tau). \]

It’s obvious that

\[ E_k(t) \leq \tilde{E}_k(t), \quad \tilde{E}_k(t) \leq \tilde{E}_k(t). \]

In addition, we denote the dissipative energy by

\[ V_k(t) = \sum_{2 \leq j \leq k+1} v \int_0^t \int_{\mathbb{R}^n} |\langle x + e\tau \rangle^{2\mu} \nabla^j \Lambda^+|^2 \, dx \, d\tau \]

\[ + v \int_0^t \int_{\mathbb{R}^n} |\langle x + e\tau \rangle^{2\mu} \nabla^j \Lambda^-|^2 \, dx \, d\tau \]

where

\[ \nabla^j \Lambda^\pm = \{ \nabla^a \Lambda^\pm; |a| = j \}, \quad j \in \mathbb{N}. \]

We define the ghost weight energy as follows:

\[ W_k(t) = \sum_{1 \leq |a| \leq k} \left( \int_0^t \int_{\mathbb{R}^n} \frac{|\langle x + e\tau \rangle^{2\mu} \nabla^a \Lambda^+(x, \tau)|^2}{\langle x \cdot e - \tau \rangle^{2\mu}} 
- \frac{|\langle x + e\tau \rangle^{2\mu} \nabla^a \Lambda^-(x, \tau)|^2}{\langle x \cdot e + \tau \rangle^{2\mu}} \, dx \, d\tau \right) \]

\[ + \int_0^t \int_{\mathbb{R}^n} \frac{|\langle x + e\tau \rangle^{2\mu} \nabla^a \Lambda^+(x, \tau)|^2}{\langle x \cdot e - \tau \rangle^{2\mu}} + \frac{|\langle x + e\tau \rangle^{2\mu} \nabla^a \Lambda^-(x, \tau)|^2}{\langle x \cdot e + \tau \rangle^{2\mu}} \, dx \, d\tau. \]

The ghost weight energy plays a central role for the existence of global solutions. Such a damping mechanism is due to the presence of steady magnetic background \( e \), and technically realized by Alinhac’s ghost weight method. Together with the strong null structure of nonlinearities, this damping mechanism can be used to capture the decay of nonlinearities in time.

In the inviscid case, we will show following a priori estimate:

\[ E_k(t) + W_k(t) \lesssim E_k(0) + W_k(t) \tilde{E}_k^{\frac{1}{2}}(t). \] (2.1)

In the viscous case, we will prove the following a priori estimate:

\[ \mathcal{E}_k(t) + V_k(t) + W_k(t) \lesssim \mathcal{E}_k(0) + W_k(t) \tilde{E}_k^{\frac{1}{2}}(t). \] (2.2)

Once the above a priori estimate is obtained, one can easily prove Theorems 1.1 and 1.2 by standard continuity arguments.

Throughout this paper, we use \( A \lesssim B \) to denote \( A \leq CB \) for some absolute positive constant \( C \), whose meaning may change from line to line. Without specification, the constant \( C \) depends only on \( \mu, k, n \), but never depends on \( t \) or \( v \).
2.2. Commutation

For any multi-index \( a \in \mathbb{N}^n \), one can easily deduce from (1.2) that

\[
\begin{align*}
\partial_t \nabla^a \Lambda^+ - \nu \Delta \nabla^a \Lambda^+ - e \cdot \nabla \nabla^a \Lambda^+ \\
+ \sum_{b+c=a} C^b_a \left( \nabla^b \Lambda^- \cdot \nabla^c \Lambda^+ \right) + \nabla \nabla^a p &= 0, \\
\partial_t \nabla^a \Lambda^- - \nu \Delta \nabla^a \Lambda^- + e \cdot \nabla \nabla^a \Lambda^- \\
+ \sum_{b+c=a} C^b_a \left( \nabla^b \Lambda^+ \cdot \nabla^c \Lambda^- \right) + \nabla \nabla^a p &= 0 \\
\nabla \cdot \nabla^a \Lambda^+ &= 0, \\
\nabla \cdot \nabla^a \Lambda^- &= 0,
\end{align*}
\tag{2.3}
\]

where the binomial coefficient \( C^b_a \) is given by \( C^b_a = \binom{a}{b} \). Moreover, for any \( \mu \in \mathbb{R} \), we can apply weights \( \langle x \pm et \rangle^{2\mu} \) to the above equation to get that

\[
\begin{align*}
\partial_t \langle x + et \rangle^{2\mu} \nabla^a \Lambda^+ - \langle x + et \rangle^{2\mu} \nu \Delta \nabla^a \Lambda^+ - e \cdot \nabla \langle x + et \rangle^{2\mu} \nabla^a \Lambda^+ \\
+ \sum_{b+c=a} \left[ \langle x + et \rangle^{2\mu} C^b_a \left( \nabla^b \Lambda^- \cdot \nabla^c \Lambda^+ \right) + \nabla \nabla^a p \right] &= 0, \\
\partial_t \langle x - et \rangle^{2\mu} \nabla^a \Lambda^- - \langle x - et \rangle^{2\mu} \nu \Delta \nabla^a \Lambda^- + e \cdot \nabla \langle x - et \rangle^{2\mu} \nabla^a \Lambda^- \\
+ \sum_{b+c=a} \left[ \langle x - et \rangle^{2\mu} C^b_a \left( \nabla^b \Lambda^+ \cdot \nabla^c \Lambda^- \right) + \nabla \nabla^a p \right] &= 0 \\
\nabla \cdot \langle x \pm et \rangle^{2\mu} \nabla^a \Lambda^+ &= 0, \\
\nabla \cdot \langle x \pm et \rangle^{2\mu} \nabla^a \Lambda^- &= 0.
\end{align*}
\tag{2.4}
\]

We will perform energy estimate for (2.3) and (2.4). We remark that the weights \( \langle x \pm et \rangle^{2\mu} \) commute with the hyperbolic operators \( \partial_t \pm e \cdot \nabla \), while they don’t commute with the Laplacian operator.

2.3. An Elementary Imbedding Estimate

In what follows, we state a simple imbedding inequality. It is just a consequence of the standard Sobolev imbedding theorem \( H^{\frac{n}{2}+1}(\mathbb{R}^n) \hookrightarrow L^\infty(\mathbb{R}^n) \).

Lemma 2.1. For any multi-index \( a \) and any \( \lambda \geq 0, \mu \geq 0 \), there hold

\[
\| \langle x \pm et \rangle^\lambda f(t,x) \|_{L^\infty_x} \lesssim \sum_{|b| \leq \lfloor \frac{\lambda}{2} \rfloor + 1} \| \langle x \pm et \rangle^\lambda \nabla^b f(t,x) \|_{L^2_x},
\tag{2.5}
\]

\[
\| \langle x \pm et \rangle^\lambda f(t,x) \|_{L^\infty_x} \lesssim \sum_{|b| \leq \lfloor \frac{\lambda}{2} \rfloor + 1} \| \nabla^b (\langle x \pm et \rangle^\lambda f(t,x)) \|_{L^2_x},
\tag{2.6}
\]

provided that the right hand side is finite.

Proof. Firstly, by \( H^{\frac{n}{2}+1}(\mathbb{R}^n) \hookrightarrow L^\infty(\mathbb{R}^n) \), we have

\[
\| \langle x \pm et \rangle^\lambda f(t,x) \|_{L^\infty_x} \lesssim \sum_{|b| \leq \lfloor \frac{\lambda}{2} \rfloor + 1} \| \nabla^b (\langle x \pm et \rangle^\lambda f(t,x)) \|_{L^2_x} \lesssim \sum_{|b| \leq \lfloor \frac{\lambda}{2} \rfloor + 1} \| \langle x \pm et \rangle^\lambda \nabla^b f(t,x) \|_{L^2_x}.
\]

Then (2.5) follows from the above estimate.
The proof of (2.6) is similar. By the Sobolev imbedding $H^{1/2} + 1(\mathbb{R}^n) \hookrightarrow L^\infty(\mathbb{R}^n)$, one gets
\[
\| \langle x \pm et \rangle^\lambda f(t, x) \|_{L^\infty_x} \lesssim \sum_{|b| \leq [\frac{n}{2}] + 1} \| \nabla^b \langle x \pm et \rangle^\lambda f(t, x) \|_{L^2_t L^2_x} \lesssim \sum_{|b| \leq [\frac{n}{2}] + 1} \| \langle x \pm et \rangle^\lambda \nabla^b f(t, x) \|_{L^2_t L^2_x}.
\]
This ends the proof of the lemma. \(\square\)

3. Estimate for the Pressure

In this section, we are going to estimate the pressure gradient, which is treated as a nonlinear term. One key point of following estimate is that the pressure gradient always keeps the interaction between $\Lambda^+$ and $\Lambda^-$, which means that we have the strong null structure in the pressure term as in [11].

A surprising effect of Lemma 3.2 presented below is that although $\langle x \rangle^{4\mu} \langle 1/2 < \mu < 2/3 \rangle$ is not a $A_2$ weight in $\mathbb{R}^2$, we can still pass the weight $\langle x \pm et \rangle^{2\mu}$ through the Riesz transform for pressure in $\mathbb{R}^n \,(n \geq 2)$. These surprising properties are based on the inherent strong degenerate structure of the system and the choice of different weights on different orders of energy estimates. We emphasize that in three and higher dimensions, the results in the lemmas to follow are standard, and can be deduced from the classical weighted Calderon–Zygmund theory.

One should note that we impose weights $\langle x \pm et \rangle^{2\mu}$ on the higher-order energy estimate and apply weights $\langle x \pm et \rangle^{\mu}$ on the zero-order one. Thus we need be careful when dealing with the unknowns with derivatives and the ones without derivatives.

We first give a preliminary estimate for the pressure, which is a direct consequence of Calderon–Zygmund theory with $A_p$ weights (see [17]). We remark that the $A_p$ weight has a translation invariance property, which guarantees that the constant in the following lemma is independent of $t$:

**Lemma 3.1.** Let $k \geq n + 3, \, \frac{1}{2} < \mu < \frac{2}{3}$, then for any index $a$ satisfying $0 \leq |a| \leq k$, there holds
\[
\| p \|_{L^1_t L^2_x} \leq CW_k(t),
\]
\[
\| \langle x \pm et \rangle^\mu \nabla^a \|_{L^2_{t,x}} \leq C \tilde{E}^{\frac{1}{2}}_k(t) W^{\frac{1}{2}}_k(t).
\]
Moreover, for any index $a$ satisfying $0 \leq |a| \leq k - 1$, there holds
\[
\| \langle x \pm et \rangle^{2\mu - 1} \nabla^a \|_{L^2_{t,x}} \leq CW^{\frac{1}{2}}_k(t) \tilde{E}^{\frac{1}{2}}_k(t),
\]
\[
\| \langle x \pm et \rangle^{3\mu - 1} \nabla^a \|_{L^2_{t,x}} \leq CW^{\frac{1}{2}}_k(t) \tilde{E}^{\frac{1}{2}}_k(t),
\]
where $C$ is a constant which depends on $a$, $\mu$ and $n$ but doesn’t depend on $t$ or the viscosity $\nu$. 
Proof. We first treat (3.1). By taking the divergence of the first equation of (1.2), one gets

$$-\Delta p = \nabla_i \nabla_j (\Lambda_i^- \Lambda_j^+).$$

Hence by the $L^2$ boundedness of the Riesz operator, we have

$$\|p\|_{L^1_t L^2_x} \leq \|\Lambda^+ \|_{L^1_t L^2_x} \|p\|_{L^1_t L^2_x} \leq \int_0^t \|\langle x + et \rangle^{\mu} \Lambda^+ \|_{L^2}\|\langle x - et \rangle^{\mu} \Lambda^- \|_{L^2} d\tau$$

$$\leq \int_0^t \|\langle x + et \rangle^{\mu} \Lambda^+ \|_{L^2} \|\langle x - et \rangle^{\mu} \Lambda^- \|_{L^2} \leq W_k(t).$$

We now take care of (3.2). Since the estimate for $\langle x + et \rangle^{\mu} \nabla^a p$ is the same as $\langle x - et \rangle^{\mu} \nabla^a p$, we only treat the former one.

By taking the divergence of the first equation of (2.3), one gets

$$-\Delta \nabla^a p = \sum_{b+c=a} C^b_a \nabla_i \nabla_j (\nabla^b \Lambda_i^- \nabla^c \Lambda_j^+).$$  \hspace{1cm} (3.5)

Noting the fact that if $\frac{1}{2} < \mu < \frac{2}{3}$, then $\langle x \rangle^{2\mu}$ belongs to $A_2$ class in $\mathbb{R}^n$ ($n \geq 2$) (see [17]). Hence, we can deduce from (3.5) that

$$\|\langle x + et \rangle^{\mu} \nabla^a p\|_{L^2_t}$$

$$\leq \sum_{b+c=a} C^b_a \|\langle x + et \rangle^{\mu} \nabla_i \nabla_j (\nabla^b \Lambda_i^- \nabla^c \Lambda_j^+)\|_{L^2_t}$$

$$\leq \sum_{b+c=a} \|\langle x + et \rangle^{\mu} \nabla^b \Lambda^- \|_{L^2_t} \|\langle x - et \rangle^{\mu} \nabla^c \Lambda^+ \|_{L^2_t}$$

$$\leq \sum_{b+c=a} \|\langle x - et \rangle^{\mu} \nabla^b \Lambda^- \|_{L^2_t} \|\langle x + et \rangle^{\mu} \nabla^c \Lambda^+ \|_{L^2_t} \|\langle x - et \rangle^{\mu} \nabla^b \Lambda^- \|_{L^\infty_t}$$

$$+ \sum_{b+c=a} \|\langle x - et \rangle^{\mu} \nabla^b \Lambda^- \|_{L^\infty_t} \|\langle x + et \rangle^{\mu} \nabla^c \Lambda^+ \|_{L^2_t}.$$  

If $|b| \geq |c|$, then $|c| \leq \frac{k}{2}$. By the assumption that $k \geq n + 3$, one infers $|c| + [n/2] + 1 \leq k$. Otherwise if $|b| \leq |c|$, one also infers $|b| + [n/2] + 1 \leq k$. Hence for the above estimate, taking the $L^2$ norm in time on $[0, t)$ and employing Lemma 2.1, one deduces that
\[
\| (x + e^t)^\mu \nabla^a p \|_{L_t^2 L_x^\infty} \lesssim \sum_{|b|, |a| \leq k} \| (x - e^t)^\mu \nabla^b \Lambda^+ \|_{L_t^\infty L_x^2} \| (x + e^t)^\mu \nabla^c \Lambda^+ \|_{L_t^2 L_x^\infty} \\
+ \sum_{|c|, |a| \leq k} \| (x - e^t)^\mu \nabla^b \Lambda^- \|_{L_t^\infty L_x^2} \| (x + e^t)^\mu \nabla^c \Lambda^+ \|_{L_t^2 L_x^\infty} \\
\lesssim W_k^{1/2} (t) \tilde{E}_k^{1/2} (t). \tag{3.6}
\]

Thus (3.2) is obtained.

To estimate (3.3), one can organize (3.5) as

\[
-\Delta \nabla^a p = \sum_{b+c=a} C_{a}^{b} \nabla_j \left( \nabla^b \Lambda_i^- \nabla_i \nabla^c \Lambda_j^+ \right).
\]

Note that \( (x + et)^{6\mu - 2} \) and \( (x - et)^{6\mu - 2} \) belong to \( \mathcal{A}_2 \) class since \( 0 < 6\mu - 2 < 2 \). Interpolating between the above \( \mathcal{A}_2 \) weights [17], we infer that

\[
\langle x \pm et \rangle^{4\mu - 2} \langle x \mp et \rangle^{2\mu}
\]

also belongs to \( \mathcal{A}_2 \) class. Hence one gets

\[
\| (x + e^t)^{2\mu - 1} \langle x - e^t \rangle^\mu \nabla^a p \|_{L_t^2} \leq \sum_{b+c=a} C_{a}^{b} \| (x + e^t)^{2\mu - 1} \langle x - e^t \rangle^\mu \nabla \nabla_j (-\Delta)^{-1} \left( \nabla^b \Lambda_i^- \nabla_i \nabla^c \Lambda_j^+ \right) \|_{L_t^2} \\
\lesssim \sum_{b+c=a} \| (x + e^t)^{2\mu - 1} \langle x - e^t \rangle^\mu [\nabla^b \Lambda^-] \|_{\| \nabla |c|+1 \Lambda^+ \|_{L_t^2}} \\
\lesssim \sum_{b+c=a} \| \langle x - e^t \rangle^{\mu - 1} [\nabla^b \Lambda^-] / (e \cdot x + t)^\mu \|_{\| \nabla |c|+1 \Lambda^+ \|_{L_t^2}}.
\]

By the fact that

\[
3\mu - 1 \leq 2\mu
\]

for \( \frac{1}{2} < \mu < \frac{3}{2} \), we have

\[
\| (x + e^t)^{2\mu - 1} \langle x - e^t \rangle^\mu \nabla^a p \|_{L_t^2} \lesssim \sum_{b+c=a} \| \langle x - e^t \rangle^{\mu - 1} [\nabla^b \Lambda^-] / (e \cdot x + t)^\mu \|_{\| \nabla |c|+1 \Lambda^+ \|_{L_t^2}}.
\]

Similar to the estimate in (3.6), taking the \( L^2 \) norm in time on \([0, t]\) and employing Lemma 2.1, we immediately have the second estimate (3.3).

The estimate for (3.4) is similar to that for (3.3). Since \( (x + et)^{6\mu - 2} \) belongs to \( \mathcal{A}_2 \) class for \( \frac{1}{2} < \mu < \frac{3}{2} \), we calculate that
\[ \| (x + et)^{3\mu - 1} \nabla \nabla^a p \|_{L^2_t} \leq \sum_{b+c=a} C_a^b \| (x + et)^{3\mu - 1} \nabla \nabla_j (\nabla^b \Lambda_i^- \nabla_i \nabla^c \Lambda_j^+ \nabla) \|_{L^2_t} \]
\[ \leq \sum_{b+c=a} \| (x + et)^{3\mu - 1} \nabla^b \Lambda^- \| \| \nabla |c| + 1 \Lambda^+ \|_{L^2_t} \]
\[ \leq \sum_{b+c=a} \| (x - et)^{\mu} \nabla^b \Lambda^- \| (x + et)^{3\mu - 1} \|\frac{(e \cdot x - t)^{\mu}}{\Lambda^1} \| \| \nabla |c| + 1 \Lambda^+ \|_{L^2_t}. \]

Taking the \( L^2 \) norm in time on \([0, t] \) and employing Lemma 2.1 and similar techniques as to (3.6), we have the estimate (3.4). \( \Box \)

Now we are going to show the main weighted estimate for the pressure.

**Lemma 3.2.** Let \( \frac{1}{2} < \mu < \frac{2}{3}, \) \( k \geq n + 3. \) Then for any \( 0 \leq |a| \leq k - 1, \) there holds
\[ \| (x \pm et)^{2\mu} \nabla \nabla^a p \|_{L^2_t} \leq C W_k^2 (t) E_k^2 (t), \]
where \( C \) is a constant which depends on \( a, \mu \) and \( n \) but doesn't depend on \( t \) or viscosity \( \nu. \)

**Proof.** We only take care of the positive sign case. The negative one can be treated similarly.

Employing integration by parts, we write
\[ \| (x + et)^{2\mu} \nabla \nabla^a p \|_{L^2_t}^2 \]
\[ = - \int_{\mathbb{R}^n} \nabla (x + et)^{4\mu} \nabla^a p \cdot \nabla \nabla^a p \, dx - \int_{\mathbb{R}^n} (x + et)^{4\mu} \nabla^a p \Delta \nabla^a p \, dx \]
\[ = - \int_{\mathbb{R}^n} \nabla ((x + et)^{4\mu} \nabla^a p \cdot \nabla \nabla^a p) \, dx \]
\[ + \sum_{b+c=a} C_a^b \int_{\mathbb{R}^n} (x + et)^{4\mu} \nabla^a p \nabla_j (\nabla^b \Lambda_i^- \nabla_i \nabla^c \Lambda_j^+) \, dx \]
\[ = - \int_{\mathbb{R}^n} \nabla (x + et)^{4\mu} \nabla^a p \cdot \nabla \nabla^a p) \, dx \]
\[ - \sum_{b+c=a} C_a^b \int_{\mathbb{R}^n} \nabla_j (x + et)^{4\mu} \nabla^a p \left( \nabla^b \Lambda_i^- \nabla_i \nabla^c \Lambda_j^+ \right) \, dx \]
\[ - \sum_{b+c=a} C_a^b \int_{\mathbb{R}^n} (x + et)^{4\mu} \nabla_j \nabla^a p \left( \nabla^b \Lambda_i^- \nabla_i \nabla^c \Lambda_j^+ \right) \, dx. \] (3.7)

For the last line in the above, we have
\[ - \sum_{b+c=a} C_a^b \int_{\mathbb{R}^n} (x + et)^{4\mu} \nabla_j \nabla^a p (\nabla^b \Lambda_i^- \nabla_i \nabla^c \Lambda_j^+) \, dx \]
\[ \leq \frac{1}{2} \| (x + et)^{2\mu} \nabla \nabla^a p \|_{L^2_t}^2 + \frac{1}{2} \sum_{b+c=a} (C_a^b)^2 \| (x + et)^{2\mu} |\nabla^b \Lambda^-| |\nabla |c| + 1 \Lambda^+ | \|_{L^2_t}. \]
Consequently, we obtain
\[
\| (x + et)^{2\mu} \nabla \nabla^a p \|_{L^2_x}^2 \leq -2 \int_{\mathbb{R}^n} \nabla \left( (x + et)^{4\mu} \nabla^a p \cdot \nabla \nabla^a p \right) dx \\
- 2 \sum_{b+c=a} C^b_a \int_{\mathbb{R}^n} \nabla_j (x + et)^{4\mu} \nabla^a p \left( \nabla^b \Lambda_j^c - \nabla^a \Lambda_j^c \right) dx \\
+ \sum_{b+c=a} C^b_a \| (x + et)^{2\mu} |\nabla^b \Lambda^c - |\nabla^{c+1} \Lambda^+| \|_{L^2_x}^2.
\]

Taking the \(L^1\) norm in time on \([0, t]\) and employing Lemmas 2.1 and 3.1, we have
\[
\| (x + et)^{2\mu} \nabla \nabla^a p \|_{L^2_t,L^2_x}^2 \lesssim \| (x + et)^{\mu} \nabla^a p \|_{L^2_t,L^2_x}^2 + \| (x + et)^{3\mu-1} \nabla \nabla^a p \|_{L^2_{t,x}}^2 \\
+ \sum_{b+c=a} \| (x + et)^{2\mu} |\nabla^b \Lambda^c - |\nabla^{c+1} \Lambda^+| \|_{L^2_{t,x}}^2 \lesssim \mathcal{E}_k(t) W_k(t).
\]

Here we used similar techniques as to (3.6). Thus the desired estimate is obtained. \(\Box\)

4. Energy Estimate Without Viscosity

In this section, we present the energy estimate for the MHD system without viscosity. One essential point is the refinement of Alinhac’s ghost weight, which is responsible for existence of the global solutions. We split the proof into a higher-order \((k \geq 1)\) energy estimate and a zero-order \((k = 0)\) energy estimate. The main difference is that, in the high-order energy estimate, we use the weights \(\langle x \pm et \rangle^{2\mu} \nabla \nabla^a \), but in the zero-order energy estimate, we use the weights \(\langle x \pm et \rangle^{\mu} \).

4.1. Higher-Order Energy Estimate

This subsection is devoted to the high-order \((k \geq 1)\) energy estimate. Let \(1/2 < \mu < 2/3\), \(q(s) = \int_0^s (\tau)^{-2\mu} d\tau\), thus \(|q(s)| \lesssim 1\). Let \(\sigma^\pm = \pm e \cdot x - t\), \(1 \leq |a| \leq k \leq n + 3\). Note that in this case the viscosity parameter \(\nu\) is zero. Taking space \(L^2\) as the inner product of the first and the second equations of (2.4) with \(\langle x + et \rangle^{2\mu} \nabla^a \Lambda^+ e^{q(\sigma^+)}\) and \(\langle x - et \rangle^{2\mu} \nabla^a \Lambda^- e^{q(\sigma^-)}\), respectively, then adding them up, we have
\[
\frac{1}{2} \partial_t \int_{\mathbb{R}^n} |\langle x + et \rangle^{2\mu} \nabla^a \Lambda^+|^2 e^{q(\sigma^+)} + |\langle x - et \rangle^{2\mu} \nabla^a \Lambda^-|^2 e^{q(\sigma^-)} dx \\
+ \int_{\mathbb{R}^n} \frac{|\langle x + et \rangle^{2\mu} \nabla^a \Lambda^+|^2}{\langle e \cdot x - t \rangle^{2\mu}} e^{q(\sigma^+)} + \frac{|\langle x - et \rangle^{2\mu} \nabla^a \Lambda^-|^2}{\langle e \cdot x + t \rangle^{2\mu}} e^{q(\sigma^-)} dx
\]
In this paper, we are going to estimate (4.1) line by line. Note that we have used take care of the first line. We re-organize it as follows:

\[
\int_{\mathbb{R}^n} \left[ \sum_{b+c=a} C_b^b (\nabla_b \Lambda^- \cdot \nabla \nabla_c \Lambda^+) + \nabla \nabla a p \right] \cdot (x + et)^{4\mu} \nabla^a \Lambda^+ e^{q(\sigma^+)} \, dx
\]

Integrating both sides of the above equality in time on \([0, t]\) and summing over \(1 \leq |a| \leq k\), we obtain

\[
\sum_{1 \leq |a| \leq k} \int_{\mathbb{R}^n} \left[ \sum_{b+c=a} C_b^b (\nabla_b \Lambda^- \cdot \nabla \nabla_c \Lambda^+) + \nabla \nabla a p \right] \cdot (x + et)^{4\mu} \nabla^a \Lambda^+ e^{q(\sigma^+)} \, dx \, d\tau
\]

\[
+ \sum_{1 \leq |a| \leq k} \int_{\mathbb{R}^n} \left[ \sum_{b+c=a} C_b^b (\nabla_b \Lambda^- \cdot \nabla \nabla_c \Lambda^+) + \nabla \nabla a p \right] \cdot (x + et)^{4\mu} \nabla^a \Lambda^- e^{q(\sigma^-)} \, dx \, d\tau
\]

Note that we have used \(e^{\pm q(\sigma^\pm)} \sim 1\). We need to deal with the first two lines on the right hand side in the above. Since they can be treated in the same fashion, we only take care of the first line. We re-organize it as follows:

\[
= - \sum_{1 \leq |a| \leq k} \int_{\mathbb{R}^n} \left[ \sum_{b+c=a} C_b^b (\nabla_b \Lambda^- \cdot \nabla \nabla_c \Lambda^+) + \nabla \nabla a p \right] \cdot (x + et)^{4\mu} \nabla^a \Lambda^+ e^{q(\sigma^+)} \, dx \, d\tau
\]

\[
+ \sum_{1 \leq |a| \leq k} \int_{\mathbb{R}^n} \left[ \sum_{b+c=a} C_b^b (\nabla_b \Lambda^- \cdot \nabla \nabla_c \Lambda^-) + \nabla \nabla a p \right] \cdot (x + et)^{4\mu} \nabla^a \Lambda^- e^{q(\sigma^-)} \, dx \, d\tau
\]

In this paper, we are going to estimate (4.1) line by line. The first line of (4.1) refers to the group which contains the highest order terms. At first sight, they may lose one derivative, but thanks to the symmetry of the system, we compute by Lemma 2.1 that

\[
\text{(4.1)}
\]
In the above, we have used the fact that

\[ |\langle x + e\tau \rangle^{2\mu} \nabla^a \Lambda^+| \cdot |\langle x + e\tau \rangle^{2\mu} \nabla^a \Lambda^+ e^{q(\sigma)}| \, dx \, d\tau \]

Next, by Lemma 2.1, the second line of (4.1) is estimated by

\[ \sum_{1 \leq |a| \leq k} \left| \frac{|\langle x + e\tau \rangle^{2\mu} \nabla^a \Lambda^+|^2}{\langle e \cdot x - \tau \rangle^{2\mu}} \right|_{L^1_{t,x}} \left| \Lambda^e \right|_{L^\infty_{t,x}} \]

\[ \lesssim W_k(t) \tilde{E}_k(t)^{\frac{1}{2}}. \quad (4.2) \]

In the above, we have used the fact that

\[ 3\mu - 1 \leq 2\mu \]

for \( \frac{1}{2} < \mu < \frac{2}{3} \).

The third line of (4.1) is bounded by

\[ \sum_{|b| + |c| = |a| + 1} \int_0^t \int_{\mathbb{R}^n} |\langle x + e\tau \rangle^{4\mu} \nabla^b \Lambda^-| |\nabla^c \Lambda^+| |\nabla^a \Lambda^+| \, dx \, d\tau \]

\[ \lesssim \sum_{|b| + |c| = |a| + 1} \int_0^t \int_{\mathbb{R}^n} \left| \frac{|\langle x + e\tau \rangle^{2\mu} \nabla^c \Lambda^+|}{\langle e \cdot x - \tau \rangle^{2\mu}} \right| \left| \frac{|\langle x + e\tau \rangle^{2\mu} \nabla^b \Lambda^-|}{\langle e \cdot x - \tau \rangle^{2\mu}} \right| \left| \frac{|\langle x + e\tau \rangle^{2\mu} \nabla^a \Lambda^+|}{\langle e \cdot x - \tau \rangle^{2\mu}} \right| \, dx \, d\tau. \quad (4.4) \]

If \( |b| \geq |c| \), then \( |c| \leq [(k + 1)/2] \), and by the assumption \( k \geq n + 3 \), one infers that \( |c| + [n/2] + 1 \leq k \). By Lemma 2.1, (4.4) can be bounded by

\[ \sum_{|b| + |c| = |a| + 1} \left| \frac{|\langle x + e\tau \rangle^{2\mu} \nabla^a \Lambda^+|}{\langle e \cdot x - \tau \rangle^{2\mu}} \right|_{L^1_{t,x}} \left| \frac{|\langle x + e\tau \rangle^{2\mu} \nabla^b \Lambda^-|}{\langle e \cdot x - \tau \rangle^{2\mu}} \right|_{L^\infty_{t,x}} \]

\[ \left| \frac{|\langle x + e\tau \rangle^{2\mu} \nabla^a \Lambda^+|}{\langle e \cdot x - \tau \rangle^{2\mu}} \right|_{L^1_{t,x}} \left| \frac{|\langle x + e\tau \rangle^{2\mu} \nabla^b \Lambda^-|}{\langle e \cdot x - \tau \rangle^{2\mu}} \right|_{L^\infty_{t,x}} \]

\[ \left| \frac{|\langle x + e\tau \rangle^{2\mu} \nabla^a \Lambda^+|}{\langle e \cdot x - \tau \rangle^{2\mu}} \right|_{L^1_{t,x}} \left| \frac{|\langle x + e\tau \rangle^{2\mu} \nabla^b \Lambda^-|}{\langle e \cdot x - \tau \rangle^{2\mu}} \right|_{L^\infty_{t,x}}. \]
which is further bounded by

\[ W_k(t) \tilde{E}_k(t)^{1/2}. \]

Otherwise, if \(|b| \leq |c|\), one similarly infers that \(|b| + [n/2] + 1 \leq k\). By Lemma 2.1, (4.4) can be bounded by \( W_k(t) \tilde{E}_k(t)^{1/2} \).

Finally, we are going to estimate the last line of (4.1). Employing integration by parts, one deduces that

\[
- \sum_{1 \leq |a| \leq k} \int_0^t \int_{\mathbb{R}^n} \nabla \nabla^a p \cdot (x + e\tau)^{4\mu} \nabla^a \Lambda^+ e^{q(\sigma^+)} \, dx \, d\tau
\]

\[
= \sum_{1 \leq |a| \leq k} \int_0^t \int_{\mathbb{R}^n} \nabla^a p \cdot 4\mu (x + e\tau)^{4\mu-2}(x + e\tau) \nabla^a \Lambda^+ e^{q(\sigma^+)} \, dx \, d\tau
\]

\[
+ \sum_{1 \leq |a| \leq k} \int_0^t \int_{\mathbb{R}^n} \nabla^a p \cdot (x + e\tau)^{4\mu} \nabla^a \Lambda^+ \frac{e^{q(\sigma^+)}}{(e \cdot x - \tau)^{2\mu}} \, dx \, d\tau.
\]

Then by Lemmas 3.1 and 3.2, we estimate the above by

\[
\sum_{1 \leq |a| \leq k} \int_0^t \int_{\mathbb{R}^n} 4\mu (x + e\tau)^{2\mu-1}(x - e\tau)^{\mu} |\nabla^a p| \frac{(x + e\tau)^{2\mu} |\nabla^a \Lambda^+|}{(e \cdot x - \tau)^{\mu}} \, dx \, d\tau
\]

\[
+ \sum_{1 \leq |a| \leq k} \int_0^t \int_{\mathbb{R}^n} (x + e\tau)^{2\mu} |\nabla^a p| \frac{(x + e\tau)^{2\mu} |\nabla^a \Lambda^+|}{(e \cdot x - \tau)^{\mu}} \, dx \, d\tau
\]

\[
\leq 4\mu \sum_{1 \leq |a| \leq k} \| \langle x + e\tau \rangle^{2\mu-1}(x - e\tau)^{\mu} \nabla^a p \|_{L^2_{t,x}} \frac{\| (x + e\tau)^{2\mu} |\nabla^a \Lambda^+| \|_{L^2_{t,x}}}{(e \cdot x - \tau)^{\mu}} + \sum_{1 \leq |a| \leq k} \| \langle x + e\tau \rangle^{2\mu} \nabla^a p \|_{L^2_{t,x}} \frac{\| (x + e\tau)^{2\mu} |\nabla^a \Lambda^+| \|_{L^2_{t,x}}}{(e \cdot x - \tau)^{\mu}}
\]

\[
\lesssim W_k(t) \tilde{E}_k(t)^{1/2}.
\]

Gathering the above estimates gives that

\[
\sum_{1 \leq |a| \leq k} \int_{\mathbb{R}^n} |\langle x + e\tau \rangle^{2\mu} \nabla^a \Lambda^+|^2 + |\langle x - e\tau \rangle^{2\mu} \nabla^a \Lambda^-|^2 \, dx
\]

\[
+ \sum_{1 \leq |a| \leq k} \int_{\mathbb{R}^n} \int_0^t \int_{\mathbb{R}^n} |\langle x + e\tau \rangle^{2\mu} \nabla^a \Lambda^+|^2 \frac{1}{(e \cdot x - \tau)^{2\mu}} + \frac{|\langle x - e\tau \rangle^{2\mu} \nabla^a \Lambda^-|^2}{(e \cdot x + \tau)^{2\mu}} \, dx \, d\tau
\]

\[
\lesssim E_k(0) + W_k(t) \tilde{E}_k(t)^{1/2}.
\]

(4.5)

This finishes the higher-order energy estimate.
Remark 4.1. Note that $(x + et)^{4\mu}(x - et)^{2\mu}$ is not in $A_2$ class in $\mathbb{R}^2$ and $\mathbb{R}^3$, so the following natural way to estimate the last line of (4.1) doesn’t work:

$$- \sum_{1 \leq |a| \leq k} \int_0^t \int_{\mathbb{R}^n} \nabla \nabla^a p \cdot (x + e\tau)^{4\mu} \nabla^a \Delta^e g(\sigma^+) \, dx \, d\tau$$

$$\leq \sum_{1 \leq |a| \leq k} \| (x + e\tau)^{2\mu} (x - e\tau)^{\mu} \nabla^a p \|_{L^2_t(x)} \frac{\| (x + e\tau)^{2\mu} \nabla^a \Delta^e g(\sigma^+) \|_{L^2_t(x)}}{|e \cdot x - \tau|^\mu}.$$

4.2. Zero-Order Energy Estimate

This subsection is devoted to the zero-order energy estimate. Let $1/2 < \mu < 2/3$, $q(s) = \int_0^s (\tau)^{-2\mu} \, d\tau$, thus $|q(s)| \lesssim 1$. Let $\sigma^\pm = \pm e \cdot x - t$, and let the viscosity parameter $\nu$ in MHD system be zero. Taking space $L^2$ as the inner product of the first and the second equations of (2.2) with $(x+et)^{2\mu} \Delta^+ e^{q(\sigma^+)}$ and $(x-et)^{2\mu} \Delta^- e^{q(\sigma^-)}$, respectively, and then adding them up, we have

$$\frac{1}{2} \partial_t \int_{\mathbb{R}^n} |(x + et)^{\mu} \Delta^+|^2 e^{q(\sigma^+)} + |(x - et)^{\mu} \Delta^-|^2 e^{q(\sigma^-)} \, dx$$

$$+ \int_{\mathbb{R}^n} \frac{|(x + et)^{\mu} \Delta^+|^2}{(e \cdot x - t)^{2\mu}} e^{q(\sigma^+)} + \frac{|(x - et)^{\mu} \Delta^-|^2}{(e \cdot x + t)^{2\mu}} e^{q(\sigma^-)} \, dx$$

$$= - \int_{\mathbb{R}^n} [(\Delta^- \cdot \nabla \Delta^+) + \nabla p] \cdot (x + et)^{2\mu} \Delta^+ e^{q(\sigma^+)} \, dx$$

$$- \int_{\mathbb{R}^n} [(\Delta^+ \cdot \nabla \Delta^-) + \nabla p] \cdot (x - et)^{2\mu} \Delta^- e^{q(\sigma^-)} \, dx.$$

Noting $e^{q(\sigma^\pm)} \sim 1$, by integrating the above equality in time, we obtain

$$\frac{1}{2} \int_{\mathbb{R}^n} |(x + et)^{\mu} \Delta^+|^2 + |(x - et)^{\mu} \Delta^-|^2 \, dx$$

$$+ \int_0^t \int_{\mathbb{R}^n} \frac{|(x + et)^{\mu} \Delta^+|^2}{(e \cdot x - t)^{2\mu}} + \frac{|(x - et)^{\mu} \Delta^-|^2}{(e \cdot x + t)^{2\mu}} \, dx \, d\tau$$

$$\lesssim E_k(0) - \int_0^t \int_{\mathbb{R}^n} [(\Delta^- \cdot \nabla \Delta^+) + \nabla p] \cdot (x + et)^{2\mu} \Delta^+ e^{q(\sigma^+)} \, dx \, d\tau$$

$$- \int_{\mathbb{R}^n} [(\Delta^+ \cdot \nabla \Delta^-) + \nabla p] \cdot (x - et)^{2\mu} \Delta^- e^{q(\sigma^-)} \, dx \, d\tau.$$

Below we will treat the second term on the right hand side in the above. The third term can be handled similarly and thus we omit the details.

Firstly, we use Lemma 2.1 to estimate that

$$- \int_0^t \int_{\mathbb{R}^n} \Delta^- \cdot \nabla \Delta^+ \cdot (x + et)^{2\mu} \Delta^+ e^{q(\sigma^+)} \, dx \, d\tau$$

$$\lesssim \int_0^t \int_{\mathbb{R}^n} \frac{|(x - et)^{\mu} \Delta^-|^2}{(e \cdot x + t)^{\mu}} \frac{|(x + et)^{2\mu} \nabla \Delta^+|}{(e \cdot x - t)^{\mu}} \frac{|(x + et)^{\mu} \Delta^+|}{dx} \, d\tau$$
Hence we deduce, by gathering the above estimates, that for the term involving the pressure, thanks to integration by parts and Lemma 3.1, we get
\[
- \int_0^t \int_{\mathbb{R}^n} \nabla p \cdot (x + et)^{2\mu} \Delta^+ + e^{q(\sigma^+)} \, dx \, dt \\
\lesssim \int_0^t \int_{\mathbb{R}^n} |p|(x + et)^{2\mu-1}|\Delta^+| + \frac{|p|(x + et)^{2\mu}|\Delta^+|}{(e \cdot x - \tau)^{2\mu}} \, dx \, dt \\
\lesssim \|p\|_{L^1_t L^2_x} \|\dot{x} + \dot{e}t\|_{L^\infty_t L^2_x} + \|x + et\|^\mu \|p\|_{L^\infty_t L^2_x} \|\dot{x} + \dot{e}t\|^\mu \|\dot{p}\|_{L^1_t L^2_x} \\
\lesssim W_k(t) \tilde{E}_k(t)^{\frac{1}{2}}. 
\]

Hence we deduce, by gathering the above estimates, that
\[
\frac{1}{2} \int_{\mathbb{R}^n} |(x + et)^\mu \Delta^+|^2 + |\dot{x} - et\|^\mu \Delta^-|^2 \, dx \\
+ \int_0^t \int_{\mathbb{R}^n} |\dot{x} + \dot{e}t\|^\mu \Delta^+|^2 + |\dot{x} - \dot{e}t\|^\mu \Delta^-|^2 \, dx \, dt \\
\lesssim E_k(0) + W_k(t) \tilde{E}_k(t)^{\frac{1}{2}}. 
\]
Combining (4.5) with (4.6) gives the desired energy estimate (2.1), which finishes the proof of Theorem 1.1.

5. Energy Estimate with Viscosity

In this section, we are going to establish the global solutions for (1.2) uniformly in the viscosity parameter. Note that for small initial data, if \( \nu \) has a positive lower bound, then the problem can be treated by a standard energy estimate and is trivial for experts. Below we always assume that \( \nu \leq \frac{1}{2} \).

The energy estimate is divided into three orders: the higher-order \((k \geq 1)\) energy estimate, the zero-order \((k = 0)\) energy estimate and the \((-1)\)-order \((k = -1)\) energy estimate. In the higher-order energy estimate, we apply weights \( (x \pm et)^{2\mu} \). In the zero-order energy estimate, we apply weights \( (x \pm et)^\mu \). Both in the higher-order energy estimate and in the zero-order energy estimate, we will use the ghost weight energy, but in the \((-1)\)-order energy estimate, no weight is used. The advantage is that we can take care of the extra terms caused by viscosity very well.

**Proof.** We first perform the higher-order \((k \geq 1)\) energy estimate. Let \( 1/2 < \mu < 2/3, \quad q(s) = \int_0^s \tau^{-2\mu} \, d\tau, \) hence \( |q(s)| \lesssim 1 \). Let \( \sigma^\pm = \pm e \cdot x - t, \quad 1 \leq |a| \leq k, k \geq n + 3. \) Taking space-time \( L^2 \) as the inner product of the first and second equations of
\[ (2.4) \text{ with } (x + e\tau)^{2\mu} \nabla^a \Lambda^+ e^{q(\sigma^+)} \text{ and } (x - e\tau)^{2\mu} \nabla^a \Lambda^- e^{q(\sigma^-)}, \text{ respectively, then adding them up, we have} \]

\[
\frac{1}{2} \int_{\mathbb{R}^n} |(x + e\tau)^{2\mu} \nabla^a \Lambda^+|^2 e^{q(\sigma^+)} + |(x - e\tau)^{2\mu} \nabla^a \Lambda^-|^2 e^{q(\sigma^-)} \, dx \\
+ \int_0^t \int_{\mathbb{R}^n} \frac{|(x + e\tau)^{2\mu} \nabla^a \Lambda^+|^2}{(e \cdot x - \tau)^{2\mu}} e^{q(\sigma^+)} + \frac{|(x - e\tau)^{2\mu} \nabla^a \Lambda^-|^2}{(e \cdot x + \tau)^{2\mu}} e^{q(\sigma^-)} \, dx d\tau \\
- \nu \int_0^t \int_{\mathbb{R}^n} (x + e\tau)^{2\mu} \Delta \nabla^a \Lambda^+ \cdot (x + e\tau)^{2\mu} \nabla^a \Lambda^+ e^{q(\sigma^+)} \, dx d\tau \\
- \nu \int_0^t \int_{\mathbb{R}^n} (x - e\tau)^{2\mu} \Delta \nabla^a \Lambda^- \cdot (x - e\tau)^{2\mu} \nabla^a \Lambda^- e^{q(\sigma^-)} \, dx d\tau \\
\leq E_k(0) - \int_0^t \int_{\mathbb{R}^n} \left[ \sum_{b+c=a} C_b^a(\nabla^b \Lambda^+ \cdot \nabla^c \Lambda^+) + \nabla^a p \right] \\
\cdot (x + e\tau)^{4\mu} \nabla^a \Lambda^+ e^{q(\sigma^+)} \, dx d\tau \\
- \int_0^t \int_{\mathbb{R}^n} \left[ \sum_{b+c=a} C_b^a(\nabla^b \Lambda^+ \cdot \nabla^c \Lambda^-) + \nabla^a p \right] \\
\cdot (x - e\tau)^{4\mu} \nabla^a \Lambda^- e^{q(\sigma^-)} \, dx d\tau.
\]

(5.1)

As in the energy estimate from the last section, the last two groups on the right hand side of the above inequality can be bounded by

\[ \tilde{E}_k^{1/2}(t) W_k(t) \leq \tilde{E}_k^{3/2}(t) W_k(t). \]

Hence we only need deal with the third and the fourth line of (5.1), which involve viscosity.

We first handle the former line:

\[
- \nu \int_0^t \int_{\mathbb{R}^n} (x + e\tau)^{2\mu} \Delta \nabla^a \Lambda^+ \cdot (x + e\tau)^{2\mu} \nabla^a \Lambda^+ e^{q(\sigma^+)} \, dx d\tau \\
= \nu \int_0^t \int_{\mathbb{R}^n} |(x + e\tau)^{2\mu} \nabla^a \Lambda^+|^2 e^{q(\sigma^+)} \, dx d\tau \\
+ 2\nu \int_0^t \int_{\mathbb{R}^n} \nabla (x + e\tau)^{2\mu} \cdot \nabla \nabla^a \Lambda^+ \cdot (x + e\tau)^{2\mu} \nabla^a \Lambda^+ e^{q(\sigma^+)} \, dx d\tau \\
+ \nu \int_0^t \int_{\mathbb{R}^n} (x + e\tau)^{2\mu} e \cdot \nabla \nabla^a \Lambda^+ \cdot (x + e\tau)^{2\mu} \nabla^a \Lambda^+ e^{q(\sigma^+)} \langle e \cdot x - \tau \rangle^{-2\mu} \, dx d\tau.
\]

(5.2)

Note that

\[ |\nabla (x + e\tau)^{2\mu}| \leq 2\mu (x + e\tau)^{2\mu - 1} \leq 2\mu (x + e\tau)^{\mu} \]
for $\frac{1}{2} < \mu < \frac{2}{3}$. Hence, for the second line on the right hand side of (5.2), we have

$$2\nu \int_0^t \int_{\mathbb{R}^n} \nabla (x + e\tau)^2 \mu \cdot \nabla^a \Lambda^+ \cdot (x + e\tau)^2 \mu \nabla^a \Lambda^+ e^{q(\sigma^+)} \, dx \, d\tau$$

$$\geq -\frac{1}{4} \nu \int_0^t \int_{\mathbb{R}^n} \| (x + e\tau)^2 \mu \nabla^a \Lambda^+ \| e^{q(\sigma^+)} \, dx \, d\tau$$

$$- 4\nu \int_0^t \int_{\mathbb{R}^n} \| \nabla (x + e\tau)^2 \mu \nabla^a \Lambda^+ \| e^{q(\sigma^+)} \, dx \, d\tau$$

$$\geq -\frac{1}{4} \nu \int_0^t \int_{\mathbb{R}^n} \| (x + e\tau)^2 \mu \nabla^a \Lambda^+ \| e^{q(\sigma^+)} \, dx \, d\tau$$

$$- 16\nu \int_0^t \int_{\mathbb{R}^n} \| (x + e\tau)^2 \mu \nabla^a \Lambda^+ \| e^{q(\sigma^+)} \, dx \, d\tau.$$

For the third line on the right hand side of (5.2), one has

$$\nu \int_0^t \int_{\mathbb{R}^n} \langle x + e\tau \rangle^2 \mu e \cdot \nabla^a \Lambda^+ \cdot (x + e\tau)^2 \mu \nabla^a \Lambda^+ \frac{e^{q(\sigma^+)}}{\langle e \cdot x - \tau \rangle^{2\mu}} \, dx \, d\tau$$

$$\geq -\frac{1}{4} \nu \int_0^t \int_{\mathbb{R}^n} \| (x + e\tau)^2 \mu \nabla^a \Lambda^+ \| e^{q(\sigma^+)} \, dx \, d\tau$$

$$- \nu \int_0^t \int_{\mathbb{R}^n} \frac{\| (x + e\tau)^2 \mu \nabla^a \Lambda^+ \|^2}{\langle e \cdot x - \tau \rangle^{2\mu}} e^{q(\sigma^+)} \, dx \, d\tau.$$

Inserting the above two estimates into (5.2), one gets

$$- \nu \int_0^t \int_{\mathbb{R}^n} \langle x + e\tau \rangle^2 \mu \Delta \nabla^a \Lambda^+ \cdot (x + e\tau)^2 \mu \nabla^a \Lambda^+ e^{q(\sigma^+)} \, dx \, d\tau$$

$$\geq \frac{1}{2} \nu \int_0^t \int_{\mathbb{R}^n} \| (x + e\tau)^2 \mu \nabla^a \Lambda^+ \| e^{q(\sigma^+)} \, dx \, d\tau$$

$$- 16\nu \int_0^t \int_{\mathbb{R}^n} \| (x + e\tau)^2 \mu \nabla^a \Lambda^+ \| e^{q(\sigma^+)} \, dx \, d\tau$$

$$- \nu \int_0^t \int_{\mathbb{R}^n} \frac{\| (x + e\tau)^2 \mu \nabla^a \Lambda^+ \|^2}{\langle e \cdot x - \tau \rangle^{2\mu}} e^{q(\sigma^+)} \, dx \, d\tau.$$

Note that one has a similar estimate for the fourth line of (5.1). Thus, employing the assumption that $\nu \leq \frac{1}{2}$, we deduce, by gathering the above estimates, that

$$I_j = \frac{1}{2} \int_{\mathbb{R}^n} \| (x + e\tau)^2 \mu \nabla^a \Lambda^+ e^{q(\sigma^+)} \| + \| (x - e\tau)^2 \mu \nabla^a \Lambda^+ e^{q(\sigma^+)} \| \, dx$$

$$+ \frac{1}{2} \nu \int_0^t \int_{\mathbb{R}^n} \| (x + e\tau)^2 \mu \nabla^a \Lambda^+ \| e^{q(\sigma^+)} \, dx \, d\tau$$

$$+ \frac{1}{2} \nu \int_0^t \int_{\mathbb{R}^n} \| (x - e\tau)^2 \mu \nabla^a \Lambda^+ \| e^{q(\sigma^+)} \, dx \, d\tau$$

$$+ \frac{1}{2} \nu \int_0^t \int_{\mathbb{R}^n} \| (x + e\tau)^2 \mu \nabla^a \Lambda^+ \| e^{q(\sigma^+)} \, dx \, d\tau$$

$$+ \frac{1}{2} \nu \int_0^t \int_{\mathbb{R}^n} \| (x - e\tau)^2 \mu \nabla^a \Lambda^+ \| e^{q(\sigma^+)} \, dx \, d\tau.$$
\[-16\nu \int_0^t \int_{\mathbb{R}^n} |(x + e\tau)^\mu \nabla^j \Lambda^+|^2e^{q(\sigma^+)} + |(x - e\tau)^\mu \nabla^j \Lambda^-|^2e^{q(\sigma^-)} \, dx \, d\tau \leq \mathcal{E}_k(0) + C\mathcal{E}_k^2(t)W_k(t), \tag{5.3}\]

where \(1 \leq j \leq k\), \(C\) is a constant which depends on \(k\), \(\mu\), \(n\) but doesn’t depend on \(\nu\) or \(t\). Here we denote the left hand side of the above inequality (5.3) by \(I_j\). Later we are going to use this estimate.

Next, we perform the zero-order energy estimate. We take the space-time \(L^2\) inner product of the first and the second equations of (1.2) with \(\langle x + et \rangle^{2\mu} \Lambda^+ e^{q(\sigma^+)}\) and \(\langle x - et \rangle^{2\mu} \Lambda^- e^{q(\sigma^-)}\), respectively, then add them up. We can repeat the argument we have done for the higher-order energy estimate in the above with just minor changes: the weights \(\langle x \pm et \rangle^{2\mu}\) are replaced by \(\langle x \pm et \rangle^\mu\), while the weights \(\langle x \pm et \rangle^\mu\) are replaced by 1, the index \(a\) are replaced by 0. As a result, we can get

\[
I_0 = \frac{1}{2} \int_{\mathbb{R}^n} |(x + et)^\mu \Lambda^+|^2e^{q(\sigma^+)} + |(x - et)^\mu \Lambda^-|^2e^{q(\sigma^-)} \, dx \\
+ \frac{1}{2} \nu \int_0^t \int_{\mathbb{R}^n} [\langle x + et \rangle^{2\mu} \Lambda^+]^2 |\nabla \lambda |^{-1} + |\nabla \lambda |^{-1} \Lambda^+|^2e^{q(\sigma^+)} + |\langle x - et \rangle^{2\mu} \Lambda^-|^2e^{q(\sigma^-)} \, dx \, d\tau \\
+ \frac{1}{2} \nu \int_0^t \int_{\mathbb{R}^n} [\langle x + et \rangle^{2\mu} \nabla \Lambda^+]^2 e^{q(\sigma^+)} + |\langle x - et \rangle^{2\mu} \nabla \Lambda^-|^2 e^{q(\sigma^-)} \, dx \, d\tau \\
- 16\nu \int_0^t \int_{\mathbb{R}^n} |\Lambda^+|^2e^{q(\sigma^+)} + |\Lambda^-|^2e^{q(\sigma^-)} \, dx \, d\tau \\
\leq \mathcal{E}_k(0) + C\mathcal{E}_k^2(t)W_k(t). \tag{5.4}\]

We denote the left hand side of the above inequality by \(I_0\). Later we are going to use this estimate.

Now we perform the \((-1)\)-order energy estimate. Applying \(|\nabla|^{-1}\) to (1.2), and taking the space-time \(L^2\) inner product of the first and second equation of the resulting system with \(|\nabla|^{-1} \Lambda^+\) and \(|\nabla|^{-1} \Lambda^-\), respectively, we have

\[
\frac{1}{2} \int_{\mathbb{R}^n} \left| |\nabla|^{-1} \Lambda^+ (t, \cdot) \right|_2^2 + \left| |\nabla|^{-1} \Lambda^- (t, \cdot) \right|_2^2 \, dx + \nu \int_0^t \int_{\mathbb{R}^n} |\Lambda^+|^2 + |\Lambda^-|^2 \, dx \, d\tau \\
\leq \mathcal{E}_k(0) - \int_0^t \int_{\mathbb{R}^n} \left[ |\nabla|^{-1} \nabla \cdot (\Lambda^+ \otimes \Lambda^+) + |\nabla|^{-1} \nabla p \right] \cdot |\nabla|^{-1} \Lambda^+ \, dx \, d\tau \\
- \int_0^t \int_{\mathbb{R}^n} \left[ |\nabla|^{-1} \nabla \cdot (\Lambda^+ \otimes \Lambda^-) + |\nabla|^{-1} \nabla p \right] \cdot |\nabla|^{-1} \Lambda^- \, dx \, d\tau.
\]

Recalling the expression of the pressure (3.5) and using the \(L^2\) boundness of the Riesz transform, one can bound the last two groups in the above by

\[
\left( \| \Lambda^+ \|_1, \| \Lambda^- \|_1 \right) \left( \| |\nabla|^{-1} \Lambda^+ \|_{L^2_x} + \| |\nabla|^{-1} \Lambda^- \|_{L^2_x} \right) \leq 2 \| \Lambda^+ \|_1 \| \Lambda^- \|_1 \mathcal{E}_k^2(t).
\]
On the other hand, employing Lemma 2.1, we have

\[ \int_0^t \| \Lambda^+ \| \| \Lambda^- \| L^2_x \, d\tau \leq \int_0^t \left\| \frac{(x + e\tau)^p \Lambda^+}{(e \cdot x - \tau)^p} \right\|_{L^2_x} \, d\tau \]

\[ \leq \left\| \frac{(x + e\tau)^p \Lambda^+}{(e \cdot x - \tau)^p} \right\|_{L^2_x} \left\| \frac{(x - e\tau)^p \Lambda^-}{(e \cdot x + \tau)^p} \right\|_{L^2_x} \lesssim W_k(t). \]

Hence, we have

\[ L^{-1} = \frac{1}{2} \int_{\mathbb{R}^n} |\nabla|^{-1} \Lambda^+|^2 + |\nabla|^{-1} \Lambda^-|^2 \, dx + v \int_0^t \int |\Lambda^+|^2 + |\Lambda^-|^2 \, dx \, d\tau \]

\[ \leq CW_k(t) E_k^2 (t) + E_k(0). \]  

(5.5)

We denote the left hand side of the above inequality by \( L^{-1} \).

Now we are going deduce the desired energy estimate. Multiplying \( I_j \) by \( \left( \frac{64}{j} \right)^j \), then summing over \( 1 \leq j \leq k \). Moreover, we add \( I_0 \) and \( 32C_\mu L^{-1} \), where \( C_\mu \geq e^{q(\sigma^+)} \), then we get

\[ \sum_{1 \leq j \leq k} \frac{1}{2} \int_{\mathbb{R}^n} |\nabla|^{-1} \Lambda^+|^2 + |\nabla|^{-1} \Lambda^-|^2 \, dx \]

\[ + \frac{1}{2} \int_{\mathbb{R}^n} |\nabla|^{-1} \Lambda^+|^2 + |\nabla|^{-1} \Lambda^-|^2 \, dx \]

\[ + 16C_\mu \int_{\mathbb{R}^n} |\nabla|^{-1} \Lambda^+|^2 + |\nabla|^{-1} \Lambda^-|^2 \, dx \]

\[ + \sum_{1 \leq j \leq k} \frac{1}{2} \left( \frac{64}{j} \right)^j \int_{\mathbb{R}^n} |\nabla|^{-1} \Lambda^+|^2 + |\nabla|^{-1} \Lambda^-|^2 \, dx \]

\[ + \left( \frac{64}{j} \right)^j \int_{\mathbb{R}^n} |\nabla|^{-1} \Lambda^+|^2 + |\nabla|^{-1} \Lambda^-|^2 \, dx \]

\[ + 16 \left( \frac{64}{j} \right)^j \int_{\mathbb{R}^n} |\nabla|^{-1} \Lambda^+|^2 + |\nabla|^{-1} \Lambda^-|^2 \, dx \]

\[ + \frac{1}{2} \int_{\mathbb{R}^n} |\nabla|^{-1} \Lambda^+|^2 + |\nabla|^{-1} \Lambda^-|^2 \, dx \]

\[ + \frac{1}{2} \int_{\mathbb{R}^n} |\nabla|^{-1} \Lambda^+|^2 + |\nabla|^{-1} \Lambda^-|^2 \, dx \]

\[ - 16 \int_{\mathbb{R}^n} |\Lambda^+|^2 + |\Lambda^-|^2 \, dx \]

\[ + 32vC_\mu \int_{\mathbb{R}^n} |\Lambda^+|^2 + |\Lambda^-|^2 \, dx \]

\[ + \sum_{1 \leq j \leq k} \left( \frac{64}{j} \right)^j \int_{\mathbb{R}^n} |\nabla|^{-1} \Lambda^+|^2 + |\nabla|^{-1} \Lambda^-|^2 \, dx \]

\[ + \left( \frac{64}{j} \right)^j \int_{\mathbb{R}^n} |\nabla|^{-1} \Lambda^+|^2 + |\nabla|^{-1} \Lambda^-|^2 \, dx \]

\[ + \frac{1}{2} \int_{\mathbb{R}^n} |\nabla|^{-1} \Lambda^+|^2 + |\nabla|^{-1} \Lambda^-|^2 \, dx \]

\[ + \frac{1}{2} \int_{\mathbb{R}^n} |\nabla|^{-1} \Lambda^+|^2 + |\nabla|^{-1} \Lambda^-|^2 \, dx \]
\[ + \frac{1}{2} \int_0^t \int_{\mathbb{R}^n} \frac{|(x + e\tau)^\mu \Lambda^+|^2}{\langle e \cdot x - \tau \rangle^{2\mu}} e^{q(\sigma^+)} + \frac{|(x - e\tau)^\mu \Lambda^-|^2}{\langle e \cdot x + \tau \rangle^{2\mu}} e^{q(\sigma^-)} \, dx \, d\tau \]

\[ \leq C \left[ \sum_{1 \leq j \leq k} \left( \frac{1}{64} \right)^j + 1 + 32C_\mu \right] \times \left[ \mathcal{E}_k(0) + C\tilde{\mathcal{E}}_{k}^1(t)W_k(t) \right]. \quad (5.6) \]

In the sequel we will show that the above (5.6) is equivalent to the desired energy estimate (2.2), which would infer the second main theorem of this paper.

The first three lines of (5.6) refer to the energy part, which are equivalent to \( \mathcal{E}_k(t) \) in the sense of multiplying by a positive constant (where the constant only depends on \( \mu \) and \( k \)). The last two lines on the left hand side of (5.6) refer to the ghost energy part, which are equivalent to \( W_k(t) \). The right hand side of the inequality of (5.6) is equivalent to

\[ \mathcal{E}_k(0) + C\tilde{\mathcal{E}}_{k}^1(t)W_k(t). \]

The fourth line to the seventh line of (5.6) correspond to the viscosity part. In and this paper we will show that they are equivalent to \( V_k \). First of all, they are obviously controlled by \( V_k \). Hence we need show the converse bound. We only consider the quantities for \( \Lambda^+ \); the ones concerning \( \Lambda^- \) can be estimated similarly.

Firstly, we calculate

\[ \sum_{1 \leq j \leq k} \frac{1}{2} \times \left( \frac{1}{64} \right)^j v \int_0^t \int_{\mathbb{R}^n} |(x + e\tau)^\mu \nabla^{j+1} \Lambda^+|^2 e^{q(\sigma^+)} \, dx \, d\tau \]

\[ - \sum_{1 \leq j \leq k} 16 \times \left( \frac{1}{64} \right)^j v \int_0^t \int_{\mathbb{R}^n} |(x + e\tau)^\mu \nabla^j \Lambda^+|^2 e^{q(\sigma^+)} \, dx \, d\tau \]

\[ = \sum_{2 \leq j \leq k+1} 32 \times \left( \frac{1}{64} \right)^j v \int_0^t \int_{\mathbb{R}^n} |(x + e\tau)^\mu \nabla^j \Lambda^+|^2 e^{q(\sigma^+)} \, dx \, d\tau \]

\[ - \sum_{1 \leq j \leq k} 16 \times \left( \frac{1}{64} \right)^j v \int_0^t \int_{\mathbb{R}^n} |(x + e\tau)^\mu \nabla^j \Lambda^+|^2 e^{q(\sigma^+)} \, dx \, d\tau \]

\[ \geq \sum_{2 \leq j \leq k+1} 16 \times \left( \frac{1}{64} \right)^j v \int_0^t \int_{\mathbb{R}^n} |(x + e\tau)^\mu \nabla^j \Lambda^+|^2 e^{q(\sigma^+)} \, dx \, d\tau \]

\[ - \frac{1}{4} v \int_0^t \int_{\mathbb{R}^n} |(x + e\tau)^\mu \nabla \Lambda^+|^2 e^{q(\sigma^+)} \, dx \, d\tau. \]

Hence we deduce that

\[ \sum_{1 \leq j \leq k} \frac{1}{2} \times \left( \frac{1}{64} \right)^j v \int_0^t \int_{\mathbb{R}^n} |(x + e\tau)^\mu \nabla^{j+1} \Lambda^+|^2 e^{q(\sigma^+)} \, dx \, d\tau \]

\[ - \sum_{1 \leq j \leq k} 16 \times \left( \frac{1}{64} \right)^j v \int_0^t \int_{\mathbb{R}^n} |(x + e\tau)^\mu \nabla^j \Lambda^+|^2 e^{q(\sigma^+)} \, dx \, d\tau \]
\[
+ \frac{1}{2} \nu \int_0^t \int_{\mathbb{R}^\times} |(x + e\tau)^\mu \nabla \Lambda^+|^2 e^{\sigma^+} \, dx \, d\tau \\
- 16 \nu \int_0^t \int_{\mathbb{R}^\times} |\Lambda^+|^2 e^{\sigma^+} \, dx \, d\tau + 32 \nu C_\mu \int_0^t \int_{\mathbb{R}^\times} |\Lambda^+|^2 \, dx \, d\tau
\]
\[
\geq \sum_{2 \leq i \leq k+1} 16 \times \left( \frac{1}{64} \right)^i \nu \int_0^t \int_{\mathbb{R}^n} |(x + e\tau)^{2\mu} \nabla \Lambda^+|^2 e^{\sigma^+} \, dx \, d\tau \\
+ \frac{1}{4} \nu \int_0^t \int_{\mathbb{R}^n} |(x + e\tau)^\mu \nabla \Lambda^+|^2 e^{\sigma^+} \, dx \, d\tau \\
+ 16 \nu C_\mu \int_0^t \int_{\mathbb{R}^\times} |\Lambda^+|^2 \, dx \, d\tau,
\]
from which we obtain the converse bound. \(\square\)

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