Active learning for interactive satellite image change detection

Hichem Sahbi\textsuperscript{1}  Sebastien Deschamps\textsuperscript{1,2}  Andrei Stoian\textsuperscript{2}

\textsuperscript{1}Sorbonne University, UPMC, CNRS, LIP6, France  \textsuperscript{2}Theresis Thales, France

Abstract

We introduce in this paper a novel active learning algorithm for satellite image change detection. The proposed solution is interactive and based on a question & answer model, which asks an oracle (annotator) the most informative questions about the relevance of sampled satellite image pairs, and according to the oracle’s responses, updates a decision function iteratively. We investigate a novel framework which models the probability that samples are relevant; this probability is obtained by minimizing an objective function capturing representativity, diversity and ambiguity. Only data with a high probability according to these criteria are selected and displayed to the oracle for further annotation. Extensive experiments on the task of satellite image change detection after natural hazards (namely tornadoes) show the relevance of the proposed method against the related work.

keywords: Frugal learning, interactive satellite image change detection.

1 INTRODUCTION

Satellite image change detection is the process of identifying occurrences of targeted changes in a scene, at a given instant $t_1$, w.r.t. the same scene acquired at an earlier instant $t_0$. One of the major applications of change detection is damage assessment after natural hazards (e.g., tornadoes, earth-quakes, etc.) in the purpose of prioritizing disaster response accordingly. This task consists in finding relevant changes (such as building destruction, damage of transportation routes and infrastructures, etc.) while discarding irrelevant ones (due to weather conditions, occlusions, sensor artefact and alignment errors, as well as effects due to oscillating objects, trees, etc.).

Early change detection solutions were initially based on simple comparisons of multi-temporal signals, via image differences and thresholding, using vegetation indices, principal component and change vector analyses (see \cite{1}–\cite{3}, \cite{5}, \cite{6}, \cite{9} and references therein). These methods also rely on a preliminary pre-processing step that attenuates the effects of irrelevant changes, by finding parameters of sensors for registration as well as correcting radiometric effects, occlusions and shadows (see for instance \cite{10}–\cite{12}, \cite{14}–\cite{16}). Other methods either ignore irrelevant changes or consider them as a part of appearance model design and are able to detect relevant changes while being resilient to irrelevant ones \cite{17}–\cite{21}. In particular, machine learning methods are promising \cite{7}, \cite{8}, but their success is highly dependent on the availability of large collections of hand-labeled training data \cite{4}, \cite{23}, \cite{50}, \cite{37}. Indeed, these approaches are limited by the huge scene variability and the lack of labeled training data in order to characterize rare relevant changes and abundant irrelevant ones. Besides, even when labeled data are available, these labels could be erroneous and oblivious to the annotator’s (user’s) subjectivity and intention.

Many existing solutions try to bypass the aforementioned limitations by making learning frugal and less dependent on large collections of labeled data; this includes zero/few shot \cite{13}, \cite{22}, \cite{94}, \cite{95}, \cite{97}–\cite{99}.
oracle, weakly-supervised, self-supervised learning. However, these solutions are limited as their design is agnostic to the user’s subjectivity and intention. Weakly-supervised and active learning solutions are rather more appropriate where users annotate very few samples of the most relevant and irrelevant changes. In this paper, we follow this line and introduce a novel interactive satellite image change detection algorithm which asks the user the most informative questions about the relevance of changes and according to the user’s responses updates a change detection criterion. The new proposed model is probabilistic and assigns for each unlabeled training sample a measure which captures how critical is that sample in order to update the decision criteria. We obtain this measure as the optimum of a constrained objective function mixing representativity, diversity, ambiguity and cardinality. In contrast to related active learning solutions, which are basically heuristics, the one proposed in this paper is probabilistic and unifies all the aforementioned terms in a single objective function whose solution models the probability of relevance of samples when learning decision functions. Extensive experiments conducted on the highly imbalanced task of satellite image change detection show the effectiveness of the proposed model.

2 Proposed method
Let \( \mathcal{I}_t = \{p_1, \ldots, p_n\} \) be two satellite images captured at two different instants \( t_0 \) and \( t_1 \) with \( t_0 < t_1 \), \( p_i \in \mathbb{R}^d \) (here \( d = 30 \times 30 \times 3 \), see experiments). \( \mathcal{I}_r, \mathcal{I}_t \) referred to as reference and test images respectively, are assumed registered, i.e., pixels in pairs \( \{(p_i, q_i)\} \) correspond to the same locations. Now, we define \( \mathcal{I} = \{x_1, \ldots, x_n\} \), with \( x_i = (p_i, q_i) \), and \( \mathcal{Y} = \{y_1, \ldots, y_n\} \) the underlying unknown labels. Our goal is to design a change detection function \( f : \mathcal{I} \rightarrow \{-1, +1\} \) which predicts the unknown labels in \( \{y_i\} \); if \( y_i = +1 \) if the test patch \( q_i \in \mathcal{I}_t \) corresponds to a “change” w.r.t. its reference patch \( p_i \in \mathcal{I}_r \). As “changes” are scarce, it is very reasonable to assume that \( |\{x_i : y_i = +1\}| \ll |\{x_i : y_i = -1\}| \). Learning \( f \) requires a subset of training data annotated by an oracle. As these annotations are usually highly expensive, the design of \( f \) should consider as few annotations as possible while minimizing the generalization error \( P(f(X) \neq Y) \).

2.1 Interactive satellite image change detection
Our design principle is iterative and relies on a question & answer model, which suggests the most informative display to an oracle, collects annotations and updates the decision function \( f \) accordingly. Let \( \mathcal{D}_t \subset \mathcal{I} \) be a subset of images shown to an oracle at iteration \( t \) and let \( \mathcal{Y}_t \) be the unknown labels of \( \mathcal{D}_t \); in practice \( |\mathcal{D}_t| \) is fixed depending on the targeted annotation budget. We build our learning function \( f \) iteratively by asking the oracle “questions” about labels in \( \mathcal{D}_t \) according to the following steps.

Display zero. Select a display \( \mathcal{D}_0 \) including representatives of \( \mathcal{I} \). In practice, \( \mathcal{D}_0 \) corresponds to centroids of a partition \( \{h_1, \ldots, h_K\} \) of \( \mathcal{I} \) obtained with K-means clustering.

Run the following steps for \( t = 0, \ldots, T - 1 \) (\( T \) may also depend on a predefined annotation budget):

-Oracle model. Label display \( \mathcal{D}_t \) with an oracle function (denoted \( \mathcal{C}(.) \)) and assign \( \mathcal{C}(\mathcal{D}_t) \) to \( \mathcal{Y}_t \).

-Learning model. Train a decision function \( f_t(.) \) on data labeled, so far, \( \cup_{k=0}^{t}(\mathcal{D}_k, \mathcal{Y}_k) \) and use it to predict labels on test data depending on \( f_t(.) \). In practice, we use support vector machines (SVMs) in order to build/update \( f_t(.) \).

-Display model. Select the next display \( \mathcal{D}_{t+1} \subset \mathcal{I} \backslash \cup_{k=0}^{t} \mathcal{D}_k \) (to show to the oracle) that minimizes \( P(f_{t+1}(X) \neq Y) \). It is clear that a brute force strategy that (i) considers all the possible displays \( \mathcal{D} \subset \mathcal{I} \backslash \cup_{k=0}^{t} \mathcal{D}_k \), (ii) learns the underlying classifiers \( f_{t+1}(.) \) on \( \mathcal{D} \cup_{k=0}^{t} \mathcal{D}_t \), and (iii) evaluates their generalization.
error is highly combinatorial and out of reach. Display selection heuristics, related to active learning [27],
are usually used instead, but one should be cautious when using these heuristics since many of them can
perform worse than the basic display strategy consisting in choosing data uniformly randomly (see [34] and
references within). Our alternative display model proposed in this paper, combines diversity and ambiguity
as well as representativity; diversity aims to select data in order to discover different modes of \( f_{t+1}(.) \) while
ambiguity seeks to locally refine the decision boundary of \( f_{t+1}(.) \). Details about our display model, shown
subsequently, constitute the main contribution of this work.

2.2 Proposed display model

We consider a probabilistic framework which assigns for each sample \( x_i \) a membership degree \( \mu_i \) that
measures the probability of \( x_i \) belonging to the subsequent display \( D_{t+1} \); consequently, \( D_{t+1} \) will correspond
to the unlabeled \( \{x_i\}_i \) with the highest memberships \( \{\mu_i\}_i \). Considering \( \mu \in \mathbb{R}^n \) as a vector of these
memberships \( \{\mu_i\}_i \), we propose to find \( \mu \) as the minimum of the following constrained minimization problem

\[
\min_{\mu \geq 0, \|\mu\|_1 = 1} \text{tr}(\text{diag}(\mu'[C \odot D])) + \alpha |C| \mu' \log |C| \mu
+ \beta \text{tr}(\text{diag}(\mu'[F \circ \log F])) + \gamma \mu' \log \mu,
\]

(1)

here \( \odot \), \( ' \) are respectively the hadamard product and the matrix transpose. \( \| \cdot \|_1 \) is the \( \ell_1 \) norm, \( log \) is applied
entry-wise, and \( \text{diag} \) maps a vector to a diagonal matrix. In the above objective function, (i) \( D \in \mathbb{R}^{n \times K} \) and
\( D_{ik} = d_{ik}^2 \) is the euclidean distance between \( x_i \) and \( k^{th} \) cluster centroid, (ii) \( C \in \mathbb{R}^{n \times K} \) is the indicator matrix
with each entry \( C_{ik} = 1 \) iff \( x_i \) belongs to the \( k^{th} \) cluster (0 otherwise), and (iii) \( F \in \mathbb{R}^{n \times 2} \) is a scoring matrix
with \( (F_{i1}, F_{i2}) = (\hat{f}_t(x_i), 1 - \hat{f}_t(x_i)) \) and \( \hat{f}_t \in [0, 1] \) being a normalized version of \( f_t \). The first term of this
objective function (rewritten as \( \sum_i \sum_k 1{\{x_i \in h_k\}} \mu_i d_{ik}^2 \)) measures the representativity of the selected samples in
\( D \); in other words, it captures how close is each \( x_i \) w.r.t. the centroid of its cluster, so this term reaches its
smallest value when all the selected samples coincide with these centroids. The second term (rewritten as
\( \sum_k \sum_{i=1}^{n} 1{\{x_i \in h_k\}} \mu_i \log \sum_{i=1}^{n} 1{\{x_i \in h_k\}} \mu_i \)) measures the diversity of the selected samples as the entropy of the
probability distribution of the underlying clusters; this measure is minimized when the selected samples belong to
different clusters and vice-versa. The third criterion (equivalent to \( \sum_i \sum_{c} \mu_i F_{ic} \log F_{ic} \)) captures the ambiguity in \( D \) measured as the entropy of the scoring function; this term reaches its smallest value when data are evenly scored w.r.t. different categories. Finally, the fourth term is related to the cardinality of \( D \), measured by the entropy of the distribution \( \mu \); this term also acts as a regularizer and helps obtaining a
closed form solution (as also shown subsequently). The impact of these terms is controlled by \( \alpha, \beta, \gamma \geq 0 \).
We formulate the minimization problem by adding an equality constraint and bounds which ensure a
normalization of the relevance values and allow us to consider \( \{\mu_i\}_i \) as a probability distribution on \( \mathcal{I} \).

2.3 Optimization

**Proposition 1.** Let \( 1_{nc}, 1_K \) denote vectors of \( nc \) and \( K \) ones respectively. The optimality conditions of (1)
lead to the solution

\[
\hat{\mu}^{(\tau+1)} := \frac{\hat{\mu}^{(\tau+1)}}{\|\hat{\mu}^{(\tau+1)}\|_1},
\]

(2)

with \( \hat{\mu}^{(\tau+1)} \) being

\[
\exp \left( -\frac{1}{\gamma} [D \circ C] 1_K + \alpha C(\log |C| \mu^{(\tau)} + 1_K) + \beta (F \circ \log F) 1_{nc} \right).
\]

(3)

In view of space, details of the proof are omitted and result from the gradient optimality conditions of
Eq. (1). Considering the above proposition, the optimal solution is obtained iteratively as a fixed point of Eqs (2) and
with \( \mu^{(0)} \) initially set to random values. Note that convergence is observed in practice in few iterations, and the underlying fixed point, denoted as \( \tilde{\mu} \), corresponds to the most relevant samples in the display \( D_{t+1} \) (according to criterion (1)) used to train the subsequent classifier \( f_{t+1} \) (see also algorithm 1).

**Algorithm 1:** Display selection mechanism

**Input:** Images in \( \mathcal{I} \), display \( D_0 \subset \mathcal{I} \), budget \( T, B \).

**Output:** \( \cup_{t=0}^{T-1} (D_t, Y_t) \) and \( \{f_t\}_t \).

for \( t := 0 \) to \( T - 1 \) do

\[ Y_t \leftarrow C(D_t); \]  // Oracle model

\[ f_t \leftarrow \arg \min_f P(f(X) \neq Y); \]  // Learning model (built on top of \( \cup_{k=0}^{t} (D_k, Y_k) \))

\[ \hat{\mu}^{(0)} \leftarrow \text{random}; \mu^{(0)} \leftarrow \frac{\hat{\mu}^{(0)}}{\|\hat{\mu}^{(0)}\|_1}; \tau \leftarrow 0 \]

while \( (\|\mu^{(\tau+1)} - \mu^{(\tau)}\|_1 \geq \epsilon \wedge \tau < \text{maxiter}) \) do

\[ \tau \leftarrow \tau + 1 \]

\[ \tilde{\mu} \leftarrow \mu^{(\tau)} \]

\[ \tau \leftarrow 0 \]

\[ \hat{\mu} \leftarrow \mu^{(0)} \]

\[ \hat{\mu} \leftarrow \mu^{(\tau)} \]

\[ \tilde{\mu} \leftarrow \mu^{(0)} \]

\[ \{x_i \in \mathcal{I} \setminus \cup_{k=0}^{t} D_k : \tilde{\mu}_i \in \mathcal{L}_B(\tilde{\mu})\} \];  // \( \mathcal{L}_B(\tilde{\mu}) \) being the \( B \) largest values of \( \tilde{\mu} \)

3 **Experiments**

We evaluate the performances of our interactive change detection algorithm using a dataset of 2,200 non-overlapping patch pairs (of 30 \( \times \) 30 pixels in RGB) taken from two registered (reference and test) GeoEye-1 satellite images of 2,400 \( \times \) 1,652 pixels with a spatial resolution of 1.65m/pixel. These images correspond to the same area of Jefferson (Alabama) taken respectively in 2010 and in 2011 with many changes due to tornadoes (building destruction, etc.) and no-changes (including irrelevant ones as clouds). The underlying ground truth contains 2,161 negative patch pairs (no-changes and irrelevant ones) and only 39 positive patch pairs (relevant changes), so \(< 2\% \) of these patches correspond to relevant changes; half of this set is used to build the display and the learning models and the other half for evaluation. Performances are reported using equal error rate (EER) on the eval set of \( \mathcal{I} \). EER is the balanced generalization error that equally weights errors in "change" and "no-change" classes. Smaller EER implies better performance.

3.1 **Ablation Study**

Initially, we study the impact of each term of our objective function when taken separately and jointly. Note that cardinality term is always kept as it acts as a regularizer that also defines the closed form solution shown earlier. Table 1 shows the impact of each of these terms individually, pairwise and all jointly taken. We observe that representativity+diversity are the most important criteria at the early stages of the iterative change detection process, while the impact of the ambiguity term comes later during the last iterations (when the modes of data are all explored) in order to locally refine change decision functions. These observations are shown through EER, and for different sampling rates defined at each iteration \( t \) as \( (\sum_{k=0}^{t-1} |D_k|/(|\mathcal{I}|/2)) \times 100 \) with \( |D_k| \) set to 16 in practice and again \( |\mathcal{I}| = 2,200 \).

3.2 **Comparison**

In order to further investigate the relevance of our method, we compare our display model against three different related strategies, namely maxmin, uncertainty as well as random sampling. Maxmin consists in sampling a display \( D_{t+1} \) greedily at each iteration of the interactive process; each data in
TABLE 1: This table shows an ablation study of our display model. Here rep, amb and div stand for representativity, ambiguity and diversity respectively. These results are shown for different iterations $t = 0, \ldots, T - 1$ (Iter) and the underlying sampling rates ($Samp$) again defined as $(\sum_{k=0}^{t-1} |D_k|/(|I|/2)) \times 100$. 

$x_i \in D_{t+1} \subset I \setminus \bigcup_{k=0}^{t} D_k$ is chosen in order to maximize its minimum distance w.r.t. $\bigcup_{k=0}^{t} D_k$, thereby the display $D_{t+1}$ will correspond to the most distinct samples. Uncertainty sampling consists in choosing the display whose unlabeled samples are the most ambiguous (i.e., whose SVM scores are the closest to zero). Random consists in picking randomly samples from the pool of unlabeled training data. We also compare our method with fully-supervised learning where a monolithic classifier is trained using 100% of the ground truth of training data.

Figure 1 shows EER w.r.t different iterations (and the underlying sampling rates in table 1). We observe the positive impact of our display model compared to the other strategies. As the task is highly imbalanced, all these comparative strategies are unable to spot the rare class (changes) sufficiently; maxmin and random make it possible to capture the diversity of the data without being able to minimize the EER at the latest iterations. Uncertainly refines locally the decision functions but suffers from the lack of diversity. Whereas all these strategies (for $t \leq 1$) have high EERs, interactive change detection (when combined with our display model) rapidly reduces the EER and overtakes all the other strategies, at the end of the iterative process. This comes from the rapid adaptation of decision functions $\{f_t(.)\}_t$ to the oracle when frugally learning from the most relevant samples.

4 CONCLUSION

We introduce in this paper a novel interactive satellite image change detection algorithm. The proposed method is based on a query & answer model which suggests the most informative patch pairs to an oracle and according to the responses of the latter updates a decision criterion that captures the oracle’s intention. Our proposed display model is probabilistic and obtained by minimizing a constrained objective function mixing (i) diversity that explores different modes of data distribution, (ii) representativity which focuses on the most informative samples in these modes and (iii) ambiguity that returns samples with the most ambiguous classifications. We also consider a regularization term that smooths the learned probabilities and allows obtaining closed form solutions. Experiments conducted on the highly imbalanced task of satellite image change detection show the effectiveness of our proposed frugal learning approach.

REFERENCES

[1] D. Brunner et al., Earthquake damage assessment of buildings using vhr optical and sar imagery, IEEE TGRS, 48(5), 2403–2420, 2010.
[2] H. Gokon et al., A method for detecting buildings destroyed by the 2011 tohoku earthquake and tsunami using multitemporal terrasar-x data, GRSL, vol. 12, no. 6, pp. 1277–1281, 2015.
[3] J. Deng, K. Wang, Y. Deng, and G. Qi, PCA-based land-use change detection and analysis using multitemporal and multisensor satellite data, IJRS, vol. 29, no. 16, pp. 4823–4838, 2008.
[4] H. Sahbi. Coarse-to-fine deep kernel networks. Proceedings of the IEEE International Conference on Computer Vision (ICCVW), 2017.
[5] R. Radke, S. Andra, O. Al-Kofahi, and B. Roysam, Image change detection algorithms: A systematic survey, IEEE TIP, 14(3), 294–307, 2005.
Fig. 1: This figure shows a comparison of different sampling strategies w.r.t. different iterations (Iter) and the underlying sampling rates in table 1 (Samp). Here Uncer and Rand stand for uncertainty and random sampling respectively. Note that fully-supervised learning achieves an EER of 0.94%. See again section 3.2 for more details.

[6] S. Liu et al., Sequential spectral change vector analysis for iteratively discovering and detecting multiple changes in hyperspectral images, TGRS, 53(8), 4363–4378, 2015.
[7] H. Sahbi, Interactive satellite image change detection with context-aware canonical correlation analysis. IEEE GRS Letters 14(5), 607-611, 2017.
[8] H. Sahbi. Relevance feedback for satellite image change detection. IEEE ICASSP, 2013.
[9] G. Chen et al., Object-based change detection, IJRS, vol. 33, no. 14, pp. 4434–4457, 2012.
[10] J. Zhu et al., Reducing mis-registration and shadow effects on change detection in wetlands, PERS, 77(4), 325–334, 2011.
[11] N. Bourdis, D. Marraud, and H. Sahbi, Camera pose estimation using visual servoing for aerial video change detection, in IGARSS, 2012.
[12] A. Fournier et al., A contrast equalization procedure for change detection algorithms: applications to remotely sensed images of urban areas, In ICPR, 2008.
[13] Q. Oliveau and H. Sahbi. "Learning attribute representations for remote sensing ship category classification." IEEE Journal of Selected Topics in Applied Earth Observations and Remote Sensing 10.6 (2017): 2830-2840.
[14] Carlotto, Detecting change in images with parallax, In Society of Photo-Optical Instrumentation Engineers, 2007
[15] S. Leprince et al., Automatic and precise orthorectification, coregistration, and subpixel correlation of satellite images, application to ground deformation measurements, TGRS, 45(6), 1529–1558, 2007.
[16] N. Bourdis, D. Marraud, and H. Sahbi, Constrained optical flow for aerial image change detection, in IGARSS, 2011, pp. 4176–4179.
[17] Pollard, Comprehensive 3d change detection using volumetric appearance modeling, Phd, Brown University, 2009.
[18] A. Nielsen, The regularized iteratively reweighted mad method for change detection in multi-and hyperspectral data, IEEE TIP, vol. 16, no. 2, pp. 463–478, 2007.
[19] C. Wu, B. Du, and L. Zhang, Slow feature analysis for change detection in multispectral imagery, TGRS, vol. 52, no. 5, pp. 2858–2874, 2014.
[20] N. Bourdis, D. Marraud, and H. Sahbi, Spatio-temporal interaction for aerial video change detection, in IGARSS, 2012, pp. 2253–2256.
[21] J. Im, J. Jensen, and J. Tullis, Object-based change detection using correlation image analysis and image seg., IJRS, 29(2), 399–423, 2008.
[22] O. Vinyals et al. Matching networks for one shot learning. arXiv preprint arXiv:1606.04089, 2016.
[23] M. Jiu and H. Sahbi. Deep kernel map networks for image annotation. IEEE ICASSP, 2016.
[24] B. Settles. Active learning. Synthesis lectures on artificial intelligence and machine learning, 1-114, 2012.
[25] H. Tianxu et al. An active learning approach with uncertainty, representativeness, and diversity. The Scientific World Journal, 2014.
[26] Joshi et al. Multi-class active learning for image classification. IEEE CVPR, 2009.
[27] H. Sahbi, P. Etyngier, J-Y. Audibert and R. Keriven. Manifold learning using robust graph laplacian for interactive image search. In IEEE Conference on Computer Vision and Pattern Recognition (pp. 1-8), 2008.
[28] S. Dasgupta. Analysis of a greedy active learning strategy. In NIPS, 337-344, 2005.
[29] Houlsby et al., Bayesian active learning for classification and preference learning. arXiv:1112.5743, 2011.
[30] L. Wang and H. Sahbi. "Nonlinear cross-view sample enrichment for action recognition." European Conference on Computer Vision. Springer, 2014.
[31] Campbell & Broderick, Automated scalable Bayesian inference via Hilbert coresets. JMLR, 551–588, 2019.
[32] Gal et al., Deep bayesian active learning with image data. ICML, 2017.
[33] Pang et al., Meta-learning transferable active learning policies by deep reinforcement learning. In arXiv:1806.04798 (2018).
[34] F.R. Bach. Active learning for misspecified generalized linear models. Advances in Neural Information Processing Systems (NIPS), 19, 2006.
[35] A. Kolesnikov, Z. Xiai, L. Beyer. Revisiting Self-Supervised Visual Representation Learning. In IEEE/CVF CVPR, pp. 1920-1929, 2019.
[36] H. Sahbi. A particular Gaussian mixture model for clustering and its application to image retrieval. Soft Computing, 667-676, 2008.
[37] M. Jiu and H. Sahbi. Semi-supervised deep kernel design for image annotation. IEEE ICASSP, 2015.
[38] H. Sahbi, L. Ballan, G. Serra and A. Del Bimbo. Context-dependent logo matching and recognition. IEEE Transactions on Image Processing, 22(3), 1018-1031, 2012.
[39] Chen, Hao, and Zhewei Shi. "A spatial-temporal attention-based method and a new dataset for remote sensing image change detection." Remote Sensing 12.10 (2020): 1662.
[40] Khan, Salman H., et al. "Learning deep structured network for weakly supervised change detection." arXiv preprint arXiv:1606.02009 (2016).
[41] F. Fleuret and H. Sahbi. "Scale-invariance of support vector machines based on the triangular kernel." 3rd International Workshop on Statistical and Computational Theories of Vision. 2003.
[42] Shi, Wenzhong, et al. "Change detection based on artificial intelligence: State-of-the-art and challenges." Remote Sensing 12.10 (2020): 1688.
[43] Acito, Nicola, et al. "Introductory view of anomalous change detection in hyperspectral images within a theoretical Gaussian framework." IEEE Aerospace and Electronic Systems Magazine 32.7 (2017): 2-27.
[44] Vivizler, Yu V., et al. "CHANGE DETECTION VIA MORPHOLOGICAL COMPARATIVE FILTERS." ISPRS Annals of Photogrammetry, Remote Sensing and Spatial Information Sciences 3.3 (2016).
[45] H. Sahbi. "Kernel PCA for similarity invariant shape recognition." Neurocomputing 70.16-18 (2007): 3034-3045.
[46] Han, Pengcheng, et al. "Aerial image change detection using dual regions of interest networks." Neurocomputing 349 (2019): 190-201.
[47] Mesquita, Bruno B., et al. "Fully convolutional siamese autoencoder for change detection in UAV aerial images." IEEE Geoscience and Remote Sensing Letters 17.8 (2019): 1445-1459.
[48] Ignatiev, Vladimir, et al. "Targeted change detection in remote sensing images." Eleventh International Conference on Machine Vision (ICMV 2018). Vol. 11041. International Society for Optics and Photonics, 2019.
[49] H. Sahbi, D. Geman. A Hierarchy of Support Vector Machines for Pattern Detection. Journal of Machine Learning Research 7.10 (2006).
[50] Chianucci, Dan, and Andreas Savakis. "Unsupervised change detection using spatial transformer networks." 2016 IEEE Western New York Image and Signal Processing Workshop (WNYISPW). IEEE, 2016.
[51] Zerrouki, Nabil, Fouzi Harrou, and Ying Sun. "Statistical monitoring of changes to land cover." IEEE Geoscience and Remote Sensing Letters 15.6 (2018): 927-931.
[52] Bu, Shuhui, et al. "Mask-CDNet: A mask based pixel change detection network." Neurocomputing 378 (2020): 166-178.
[53] H. Sahbi, J-Y. Audibert, and R. Keriven. Context-dependent kernels for object classification. IEEE transactions on pattern analysis and machine intelligence 33.4 (2010): 699-708.
[54] Konstantinidis, Dimitrios. "Building detection for monitoring of urban changes." (2017).
[55] Khan, Salman H., et al. "Weakly supervised change detection in a pair of images." arXiv preprint arXiv:1606.02009 (2016).
[56] Kolos, Maria, et al. "Procedural synthesis of remote sensing images for robust change detection with neural networks." International Symposium on Neural Networks. Springer, Cham, 2019.
[57] M. Jiu and H. Sahbi. Nonlinear deep kernel learning for image annotation. IEEE Transactions on Image Processing 26.4 (2017): 1820-1832.
[58] Shi, Qian, et al. "A Deeply Supervised Attention Metric-Based Network and an Open Aerial Image Dataset for Remote Sensing Change Detection." IEEE Transactions on Geoscience and Remote Sensing (2021).
[59] F. Yuan, G.S. Xia, H. Sahbi and V. Prinet (2012). Mid-level features and spatio-temporal context for activity recognition. Pattern Recognition. 45(12), 4182-4191.
[60] Tian, Shiqi, et al. "Hi-UCD: A large-scale dataset for urban semantic change detection in remote sensing imagery." arXiv preprint arXiv:2011.03247 (2020).
[61] Hytla, Patrick C. Multi-Ratio Fusion Change Detection Framework with Adaptive Statistical Thresholding. Diss. University of Dayton, 2016.
[62] Andermatt, Philipp, and Radu Timofte. "A weakly supervised convolutional network for change segmentation and classification." arXiv preprint arXiv:2011.03577 (2020).
[63] L. Wang and H. Sahbi. Directed acyclic graph kernels for action recognition. Proceedings of the IEEE International Conference on Computer Vision. 2013.
[64] Hamaguchi, Ryuhei, et al. "Epipolar-Guided Deep Object Matching for Scene Change Detection." arXiv preprint arXiv:2007.15540 (2020).
[65] Li, Suicheng, et al. "Change detection in images using shape-aware siamese convolutional network." Engineering Applications of Artificial Intelligence 94 (2020): 103819.
[66] Mroueh, Fatima, Ihab Shetty, and Mohammad Chaitou. "Building Change Detection in Aerial Images." BDCSIntell. 2019.
[67] H. Sahbi. A particular Gaussian mixture model for clustering and its application to image retrieval. Soft Computing, 667-676, 2008.
[68] Resta, Salvatore. Anomalous change detection in multi-temporal hyperspectral images. 2012.
[69] Lee, Haeyun, et al. "Local Similarity Siamese Network for Urban Land Change Detection on Remote Sensing Images." IEEE Journal of Selected Topics in Applied Earth Observations and Remote Sensing 14 (2021): 4139-4149.
[70] H. Sahbi. CNRS-TELECOM ParisTech at ImageCLEF 2013 Scalable Concept Image Annotation Task: Winning Annotations with Context Dependent SVMs. CLEF (Working Notes). 2013.
[71] Shen, Li, et al. "S2Looking: A Satellite Side-Looking Dataset for Building Change Detection." arXiv preprint arXiv:2107.09244 (2021).
[72] Zhang, Lin, et al. "Object-level change detection with a dual correlation attention-guided detector." ISPRS Journal of Photogrammetry and Remote Sensing 177 (2021): 147-160.
[110] H. Sahbi and N. Boujemaa. "From coarse to fine skin and face detection." Proceedings of the eighth ACM international conference on Multimedia. 2000.

[111] Maltezos, Evangelos, et al. "Building Change Detection using Semantic Segmentation on Analogue Aerial Photos." Proceedings of the FIG Congress, Istanbul, Turkey. 2018.

[112] Xie, Guo-Sen, et al. "Attentive region embedding network for zero-shot learning." Proceedings of the IEEE/CVF Conference on Computer Vision and Pattern Recognition. 2019.

[113] H. Sahbi and N. Boujemaa. "Robust matching by dynamic space warping for accurate face recognition." Proceedings 2001 International Conference on Image Processing (Cat. No. 01CH37205). Vol. 1. IEEE, 2001.