Molecular circuits for associative learning in single-celled organisms

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We demonstrate how a single-celled organism could undertake associative learning. Although to date only one previous study has found experimental evidence for such learning, there is no reason in principle why it should not occur. We propose a gene regulatory network that is capable of associative learning between any pre-specified set of chemical signals, in a Hebbian manner, within a single cell. A mathematical model is developed, and simulations show a clear learned response. A preliminary design for implementing this model using plasmids within Escherichia coli is presented, along with an alternative approach, based on double-phosphorylated protein kinases.

Keywords: associative learning; Hebbian learning; single-celled organism; plasmid; synthetic biology

1. ASSOCIATIVE LEARNING IN A SINGLE CELL

Associative learning is traditionally thought to be confined to animals with nervous systems (Walters et al. 1979; Kandel et al. 2000; Fanselow & Poulos 2004). The most famous example is Pavlov’s dog, which learned to associate the sound of a bell (the conditioned stimulus) with the smell of food (the unconditioned stimulus) and so salivate when the bell was rung. In multi-cellular organisms, the memory trace is stored as a modification of the connectivity between cells, for example as changes in the synaptic strengths between neurons. However, recent work in systems biology reveals molecular circuits that are rather similar to neural networks (Bray 2003) and logic gates (Buchler et al. 2003) within individual cells. Because chemical kinetics is Turing universal (Magnasco 1997) and can therefore at least in principle implement arbitrary neural networks (Hjelmfelt et al. 1991) and finite state automata (Hjelmfelt et al. 1992), there is no reason for biological mechanisms that sustain associative learning to be confined to neural systems.

Hennesssey (1979) showed that the single-celled ciliate Paramecium caudatum might possibly be capable of being classically conditioned. A paramecium was successfully trained to exhibit an avoidance response to a conditioned vibration stimulus, using an electric shock as the unconditioned stimulus. This response persisted over the entire lifetime of the paramecium, although no inheritance of this response was studied. Associative sensitization and pseudo-conditioning were not ruled out in the experiment, the repetition of which we would welcome.

Although adaptive sensitization and habituation (non-associative learning) have been demonstrated in bacteria (Yi et al. 2000), associative learning within a single lifetime has not. An example of sensitization is the autocalytic upregulation of phoA and phoB after prior phosphate limitation, resulting in a stronger response to subsequent phosphate limitation (Hoffer et al. 2001). Associative learning is distinct from sensitization because it requires learning a correlation between two different stimuli.

A plausible proof of principle of associative learning in single cells, based on autocalytic RNA, has been recently proposed (Gandhi et al. 2007). The motivation of that paper was to demonstrate an important potential function for regulatory RNA networks. One of the mechanisms uses RNA polymerases to replicate RNA strands capable of reversible ligation and cleavage. Our paper differs in three respects. Firstly, Gandhi et al’s mechanism is associative, but, interestingly, it does not use a Hebbian process (Gerstner & Kistler 2002). It is analogous to a hypothetical single symmetric bidirectional synapse, whereas our model is analogous to a single-layer perceptron (Haykin 1998). Secondly, Gandhi et al’s motivation is not to devise a system primarily for ease of synthesis using standard
Table 1. Parameter values used in circuit simulations.

| Parameter | Value |
|-----------|-------|
| \(v_p\)   | 1.0   |
| \(v_w\)   | 1.0   |
| \(\delta_p\) | 0.0005 |
| \(\delta_w\) | 0.0001 |
| \(\epsilon\) | 0.05 |
| \(K_w\)   | 50    |
| \(K_r\)   | 0.05  |
| \(K_p\)   | 50    |
| \(R\)     | 10    |
| \(k\)     | 10    |

molecular biology techniques, although certainly a distinct Hebbian (deoxy-ribozyme circuit is potentially within the scope of constructability using AND-gates (Stojanovic et al. 2002). Thirdly, Ghandi et al. (2007) use composite variables consisting of the sum of two species concentrations to represent the responses to learning (e.g. \(n_a = [A] + [AB]\), where \(n_a\) is the variable considered to represent the output of learning, and A and AB are individual chemicals. The outputs of our system are not composite variables, but the concentrations of single transcription factors. Our circuit also exhibits extinction as observed in Pavlovian conditioning. We use realistic units (see table 1), which allow us to predict the time scales over which conditioning would be expected to occur in the laboratory.

A recent paper has described how in silico evolution could be used to produce gene regulatory networks (GRNs) capable of ‘predictive behaviour’ (Tagkopoulos et al. 2008). The environmental affordance that such a mechanism exploits is the existence of environmental temporal regularities that persist for several bacterial generations, for example in marine ecosystems a temperature change may precede a change in O2 concentration, and photon flux may precede temperature changes. In the gut, the need to switch from aerobic to anaerobic respiration may be signalled by molecular changes. In the gut, the need to switch from aerobic to anaerobic respiration may be signalled by molecular changes. In the gut, the need to switch from aerobic to anaerobic respiration may be signalled by molecular changes. In the gut, the need to switch from aerobic to anaerobic respiration may be signalled by molecular changes.

To summarize Tagkopoulos et al’s important and distinct contribution, we clarify what they mean by ‘predictive behaviour’. Whereas metazoan nervous systems (and our proposed circuits) are capable of learning to predict temporal contingencies that vary within lifetimes, i.e. they are capable of learning conditioned stimuli, Tagkopoulos’s mechanism depends on evolution and the fixity of the relationships between lifetimes, i.e. their mechanism is capable of evolving responses to unconditioned stimuli, but not of learning to predict a contingency within a lifetime. Their ‘predictive’ and ‘anticipatory’ behaviour is predictive and anticipatory in the sense that the evolutionary system causes salivation to ‘predict’ or ‘anticipate’ the presence of food after the smell of food.

Our work demonstrates that there exists sufficient variation in intra-cellular circuits to sustain Hebbian learning, the results of which can be epigenetically inherited. There is no doubt that epigenetic inheritance occurs in bacteria, single-celled fungi and protists (Jablonka & Lamb 2005). However, in nature, associative learning may not be observed in bacteria for any of the following reasons. The cost of maintaining associative learning machinery may be too high, and/or environmental affordances may be lacking (Rando & Verstrepen 2007). However, the circuits we propose may in future have medical applications, and therefore warrant a synthetic biological investigation. Synthetic biology was initially concerned with purely reactive behaviours (Eudy 2005). Taking a significant step forward, recent work has dealt with state-dependent processing or ‘sequential logic’ gene circuits (Fritz et al. 2007). These circuits are capable of storing a binary memory vector representing the concentration of dimerizable proteins. Our work is similarly motivated, and adds the potential for Hebbian learning of such continuous vectors. We present designs of biochemical networks capable of associative learning, using GRNs and protein kinase signalling networks. We use mathematical models and simulations of the GRN, with biologically realistic parameters, to demonstrate not only that the system learns but also that it would be possible, in principle, to construct such a system in bacteria.

2. GENE REGULATORY NETWORK IMPLEMENTATION

The genetic circuit shown in part of figure 1b is in two halves, by analogy with the classical Hebbian neural circuit in figure 1a. One-half (on the left in the diagram) represents the known response to the unconditioned stimulus, and the other (on the right) the response to the conditioned stimulus that is to be learned. In practice, circuits could consist of more than two unconditioned stimuli, in which case the circuit could learn to associate any one of these unconditioned stimuli with a conditioned stimulus. Two stimuli are the minimum number required to demonstrate the principle of Hebbian learning.

The two halves of the circuit are structurally identical, with one exception: there is a non-zero basal concentration of the ‘weight’ molecule corresponding to the
unconditioned stimulus (denoted $w_1$). When the corresponding input molecule $u_1$ enters the cell, it binds with the repressor molecule $r_1$, leading to loss of repression. Together with the background supply of $w_1$, an activator of gene expression, this has the effect of producing the output response molecule $p$. Moreover, the generation of $p$ then feeds back and allows further production of the $w_1$ molecule. This is a molecular implementation of Hebbian learning in which pairing of output activity and input activity strengthens the coupling between the two (Hebb 1949; Gerstner & Kistler 2002). The use of the repressor in the genetic circuit (which does not appear in the neural implementation) is simply because the input molecule will be small (so as to quickly cross the cell membrane) and would not typically be a direct activator of gene expression.
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Figure 2. (a) The concentration of \( p \). (b) The ‘weight’ molecule concentrations, \( w_1 \) (thin line) and \( w_2 \) (thick line). (c) The (unconditioned) \( u_1 \) input concentration. (d) The (conditioned) \( u_2 \) input concentration. The circuit responds by producing an output \( p \) (see the first peak of (a)) to input \( u_1 \) at 2000 s (see the first peak of (c)). This demonstrates that \( u_1 \) is the unconditioned stimulus. The circuit does not respond to the conditioned stimulus input \( u_2 \) (see the first peak in (d)) at 6000 s when it is presented alone before pairing. Both \( u_1 \) and \( u_2 \) are presented paired together at time 10000 s, resulting in an output of \( p \) (see the second peaks in (c) and (d) and the corresponding output \( p \) in (a)), and an increase in \( w_2 \) from baseline to approximately 1000 nM in concentration (see (b)). The circuit then responds to \( u_2 \) occurring 30000 s later (third peak in (d)) by expressing \( p \) (see the third peak in (a)), where, before pairing, it had not responded to \( u_2 \) at all (see absence of peak in (a) at 6000 s when \( u_2 \) is presented for the first time). This demonstrates associative learning has indeed taken place.

In the other half of the circuit, however, there is no background level of the \( w_2 \) molecule. This means that the corresponding input molecule, \( u_2 \) (corresponding approximately to the bell in Pavlov’s experiment), while binding to the repressor \( r_2 \), is insufficient to generate the output response \( p \). However, presenting the two inputs \( u_1 \) and \( u_2 \) simultaneously (the ‘smell’ and the ‘bell’) will produce sufficient quantities of \( p \) so that the molecule \( w_2 \) will be produced in abundance. Moreover, a relatively slow decay rate for \( w_2 \) will then ensure that, for some subsequent time period, the circuit can produce \( p \) in response to \( u_2 \) alone. The circuit has learned to associate the two inputs together, through a (temporary) increase in the concentration of the \( w_2 \) molecule.

The equations governing the circuit are

\[
\frac{dp}{dt} = \sum_{j=1}^{N} \left[ v_p \left( \frac{w_j}{K_u + w_j} \right) \left( 1 - \frac{r_j}{K_r + r_j} \right) \right] - \delta_p p, \tag{2.1}
\]

\[
\frac{dw_j}{dt} = v_w \left( \frac{p^2}{K_u^2 + p^2} \right) \left( 1 - \frac{r_j}{K_r^2 + r_j} \right) - \delta_w w_j + \epsilon_1. \tag{2.2}
\]

For the two stimulus case in figure 1, \( N=2 \). Notice that the equations are symmetrical in \( w_1 \) and \( w_2 \), with the exception of the basal rate \( \epsilon_1 \) that is non-zero for weights representing unconditioned stimuli, i.e. \( w_1 \). We assume all binding sites bind dimers: this creates a relatively sharp switching behaviour. In addition, the binding of the weight molecules \( w_1 \) and \( w_2 \) as promoters for \( p \) require two dimers to be bound cooperatively (as indicated by the Hill coefficient of four). The purpose of this (along with the relatively high Michaelis constant \( K_u \)) is to create a small delay in the start of the \( p \) response. This is necessary to create a clear separation between the ‘on’ and ‘off’ responses to \( u_2 \), so that the response to the conditioned stimulus will not accidentally be switched on by a few stray molecules. This means that the circuit will be robust to small fluctuations in the numbers of protein molecules. We use a relatively high production and degradation rate for \( p \) to give a strong response to the presence and absence of the input molecules. The weight molecules, on the other hand, degrade slowly. The model that we describe is deterministic and thus describes the average behaviour of a population of bacterial cells. It would be possible to formulate the model in a stochastic form that could capture the fluctuations in the numbers of proteins between individual cells in the population (Swain et al. 2002). While such a model would have the value of added realism, the structural properties of the system that give rise to associative learning are more clearly expounded and analysed with the small number of differential equations that we present.

We simulate this system by numerically integrating the above equations, for various input sequences. The parameter values we use are shown in table 1. It should be noted, however, that the behaviour of the circuit is robust to variations (of up to 25%) in these values.

It is assumed that there is a fast reversible reaction between the input molecules and the repressors. This means we can approximate the level of a repressor \( r \) as a function of the corresponding input \( u \) as

\[
r(t) = \frac{R}{1 + ku(t)}, \tag{2.3}
\]

where \( R \) is the total amount of \( r \) in the system and \( k \) is the ratio of the forward to backward reactions.
3. MODEL BEHAVIOUR

The results of a typical simulation are shown in figure 2. A series of input spikes of both \( w_1 \) and \( w_2 \) are presented. The spikes are of concentration 100 nM, and last for 20 min. (A duration of at least 5 min is necessary to get a response.) The system starts in the steady state with no inputs (this is \( [p] = 0 \) nM, \( [w_1] = 500 \) nM, \( [p] = 0 \) nM, \( [w_2] = 500 \) nM, \( [w_2] = 0 \) nM). The first (unconditioned) input \( w_1 \) is presented at \( t=2000 \) s and there is an immediate corresponding output spike of \( p \), which almost attains the equilibrium level of 200 nM, and then swiftly disappears when the input spike finishes. A corresponding increase in the level of \( w_1 \) can also be seen at this time. The presentation of a spike of \( w_2 \) at \( t=6000 \) s produces no response at all. However, when spikes of \( w_1 \) and \( w_2 \) are presented simultaneously at \( t=10000 \) s, we get a large (double) output response. This is because copies of \( w_2 \) are now being rapidly produced, which enables \( p \) to be produced in response to both inputs. More importantly, the level of \( w_2 \) is so large that, even when the inputs are switched off, it remains in the system for a considerable time. This means that when \( w_2 \) is presented alone at \( t=40000 \) s (that is, over 8 hours after the simultaneous presentation of \( w_1 \) and \( w_2 \)), the circuit can still respond and produce a corresponding \( p \) spike.

A mathematical analysis of the equilibrium states of the system, when \( w_2 \) is presented (but \( w_1 \) is not), reveals a bistable switch. One stable state, the off state, has \( [p] = 0.005 \) nM and \( [w_2] = 0.0001 \) nM. The other stable state, the on state, has \( [p] = 200 \) nM and \( [w_2] = 9412 \) nM. They are separated by an unstable intermediate state with \( [p] = 2 \) nM and \( [w_2] = 15.82 \) nM. The level of \( w_2 \) dominates the switch from one state to the other. If this is below the switching threshold, then there is no response by the circuit. Levels of \( w_2 \) above the threshold are able to produce a significant \( p \) response. In the simulation shown, \( w_2 \) has a concentration of 56 nM at the time of the final \( w_2 \) spike; more than enough to generate a full \( p \) spike. With the given set of parameters, the conditioned response continues for approximately 10.5 hours, by which time \( [w_2] = 22.8 \) nM. Any longer and it is lost, as the level of \( w_2 \) goes below the threshold. In practice, the cell would have divided before this time, with the possibility that the offspring can inherit the learned association from the parent (depending on how much \( w_2 \) is diluted by the split).

It should be noted that, although the increase in the \( w_1 \) and \( w_2 \) molecules is dramatic, it would take a long time (over 8 hours with the input molecules present) to get close to the equilibrium level of 9412 nM. Again, the cell would have divided before this occurs.

4. EXPERIMENTAL DESIGN

A preliminary design for the implementation of one-half of this genetic circuit is shown in figure 1c. This design makes use of two extrachromosomal plasmid replicons, within an Escherichia coli host, to maximize modularity and facilitate ‘mix and match’ mutagenesis. The plasmid replicons employed would need to be compatible and carry different antibiotic resistance genes. There are many possible combinations of activator and repressor proteins which could be used. An example set-up is as follows.

The first plasmid, pW1, contains the genes for the repressor (TetR) and for the weight molecule (FNRI). The input stimulation would be sub-antibiotic concentrations of tetracycline, which alleviates repression by TetR and thereby induces FNRI expression. The second plasmid, pRep1, will contain the gene for the output (orfP). This synthetic gene will encode a fused combination of CI activator protein, which activates the expression of the weight gene FNRI, and a GFP reporter protein that causes fluorescence, thus enabling the output to be measured empirically. This gene is activated by FNRI and repressed by TetR.

The output gene for \( p \) will also have a second promoter upstream, pBAD, which may be induced by arabinose, which activates the pBAD promoter via AraC protein and switches on expression of \( p \). This is useful as a manual ‘switch’ for training and testing purposes.

The second half of the circuit would have the same structure, but make use of the lac repressor (to be modulated by the input) and CRP (cAMP receptor protein) as the second weight \( w_2 \). The only structural difference between the two halves is in the basal concentration of the ‘weights’. This can be achieved by having either a leaky promoter for \( w_2 \) or a separate gene on pW1 for generating the required background levels.

Extension of the circuit to \( N \) inputs requires a systematic approach constructing plasmid modules that can rapidly be structured into any desired topology of interactions, such as described in the framework of ‘programmable cells’ (Kobayashi et al. 2004). With our modular design, one can add more new inputs or associations—by adding extra copies of the \( P \) gene (i.e. on plasmids pRep2, pRep3 or more probably on the chromosome) with different promoters that have the required binding sites for new circuits. Of course this might be limited by finding new pairs of regulators with the desired characteristics, but sooner or later these may be available to order as part of coordinated approaches such as the BioBricks project (Knight 2003).

It should be noted that the relevant characteristics of the circuit components can often be readily adjusted by mutagenesis in order to attain an optimal response. In addition, further adaptations may be directed by artificial evolution in vivo, see electronic supplementary material for descriptions of in silico and in vivo evolution of Hebbian learning circuits.

5. PHOSPHORYLATION CYCLE IMPLEMENTATION

An alternative method for implementing the same associative learning process within a single cell is to use a phosphorylation cycle. The basic design is shown in figure 1d. The design requires proteins that can be single- and double-phosphorylated (such as MAPK protein kinases). The output response is given by the double-phosphorylated \( p \) protein. This then
promotes the phosphorylation of the weight proteins, which are then further phosphorylated by the input molecules. The weights and inputs are both required to produce the outputs. All rates are assumed to be fast, except the decay of the double- to single-phosphorylated $w$ proteins. This slow decay again preserves the conditioned learning response. To ensure sensitivity to the input $u_1$, there needs to be a background rate for phosphorylating the $w_1$ protein.

This implementation of the circuit is interesting as it illustrates an alternative mechanism by which associative learning could occur naturally in individual cells, see electronic supplementary material for a simple model of the MAPK system. Moreover, one would expect the response rates using phosphorylation cycles to be much faster than for a GRN implementation. However, for experimental purposes, GRNs on plasmids are easier to synthesize and have the added advantage that they can be further evolved in the laboratory to optimize the behaviour.

We note that combinations of gene circuits and protein–protein interactions may be used to implement sequential logic operations as described by Fritz et al. (2007). Similar techniques could be used to modify our Hebbian circuits; see electronic supplementary material. The construction of novel GRNs is central to the synthetic biology project and there are many published examples of circuits designed to confer novel desired functions on micro-organisms, some of which have been constructed and tested (Elowitz & Leibler 2000; Kobayashi et al. 2004). ‘Toggle-switch’ circuits have been synthesized, conferring a form of memory on bacteria—a prolonged response to transient signals (Gardner et al. 2000).

6. CONCLUSIONS

We have presented a mathematical model of a GRN that is capable of associating two (or more) input signals in a Hebbian fashion. A design for implementing this circuit on plasmids in E. coli has also been described, along with an alternative implementation using phosphorylation cycles. The circuit could be tuned by directed evolution. Moreover, one would also expect to see inheritance of the learned association if the cell divides sufficiently soon after the learning takes place. See Jablonka & Lamb (2005) for a discussion of other mechanisms of epigenetic inheritance.

An important criticism is that the system is capable of learning only associations between $N$ pre-defined dimensions of conditional stimuli, $u_p$ and an unconditioned stimulus. We can give three responses.

Firstly, the inducer $u_p$ which we have loosely been talking of as the stimulus, can without loss of generality be a downstream-regulated component or a second messenger that is activated by a wide range of possible signal transduction cascades. Any stimulus that activates this cascade can be associated with the unconditioned stimulus. The signal transduction cascade that produces $u_p$ defines a perceptual class of stimuli that can be associated. Although it may be asking a lot of a bacterium that ‘a completely new’ association be learned, what would this mean? We argue it would mean that the bacterium was capable of creating a new perceptual class of stimuli to activate a given $u_p$ molecule. One possible mechanism that would be capable of generating a novel perceptual class, within the lifetime of a cell, is intra-cellular natural selection, a process proposed by Wills (2001). If there is a source of sequence variation and heredity in an autocatalytic element of the signal transduction cascade, then natural selection can act between these elements, within the lifetime of a cell. Less ambitious is to propose that a random search process could establish novel perceptual categories. An even simpler mechanism would be if low sequence-fidelity transcription or translation produced variations in the selectivity and sensitivity of the components of a signal transduction system within the lifetime of a cell. We argue that signal transduction-based classifiers are analogous to perceptual areas in nervous systems that are responsible for defining classes of event by using topographic maps that represent increasingly abstract entities or Gestalts (Gibson 1986), rather than signalling atomic stimulus events. Much of the flexibility of an associative learning system depends on this transduction/classification process.

Our second response is that no learning mechanism is completely general, i.e. capable of associating any conditioned stimulus with any unconditioned stimulus. No neural network has the capacity to learn associations between any two inputs within the lifetime of the organism. The opposite belief was once held by the behaviourists who claimed that any reinforcer could strengthen any response (R) in the presence of any stimulus (S), provided that the animal could sense the stimulus and that a response was within its motor capabilities (Watson 1930; Skinner 1976). R and S were considered arbitrary, in effect symbolic items to be manipulated by this general learning system. A classic publication in psychology is ‘The misbehavior of organisms’ that describes experiments showing evolutionary constraints on what can and cannot be conditioned in mammals (Brelend & Breland 1961). Later, Shettleworth denied that general laws of learning existed, claiming that the learning abilities of different species were specifically adapted to ecological constraints, i.e. learning was contingent on particular stimuli and responses and not independent of them (Shettleworth 1998). Further attempts to rectify a general theory of learning were made by Dickinson who claimed that particular features of ‘causes and effects’ in the ecological theory of an animal’s lineage determined the properties of an animal’s learning mechanism (Dickinson 1980).

Thirdly, the lack of flexibility serves to highlight that, although associative learning is possible in a single cell, nervous systems allow greater capacity for constructing novel pathways between arbitrary stimuli, because, instead of the network being defined by unchanging nucleotide and amino acid sequences, the spatial location of a synapse defines the pathway and ‘meaning’ of a signal. Nevertheless, one should point out that spatial localization in single cells does contribute to reaction specificity, and so could be another basis for associative learning (Harold 2005).
Finally, it is interesting to speculate about the potential applications of such molecular circuits. One idea is to use them as intelligent biomarkers for reporting on existing associations between cellular components. To do this, one constructs N plasmids as described above, whereupon Hebbian learning is used to train the resulting gene regulatory perceptron to classify the observed input vector. Secondly, a therapeutic bacterial system might adaptively tailor the anticipatory release of a drug to predict antecedents to a toxin. The genetic engineering of ‘remote-controlled’ bacteria to secrete drugs is already underway (Rao et al. 2005; Loessner et al. 2007). The circuit described provides a potential basis for such systems to learn.

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