THE VIRTUAL HAKEN CONJECTURE

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WITH AN APPENDIX BY IAN AGOL, DANIEL GROVES, AND JASON MANNING

Dedicated to Mike Freedman on the occasion of his 60th birthday

Abstract. We prove that cubulated hyperbolic groups are virtually special. The proof relies on results of Haglund and Wise which also imply that they are linear groups, and quasi-convex subgroups are separable. A consequence is that closed hyperbolic 3-manifolds have finite-sheeted Haken covers, which resolves the virtual Haken question of Waldhausen and Thurston’s virtual fibering question. An appendix to this paper by Agol, Groves, and Manning proves a generalization of the main result of [1].

1. Introduction

In this paper, we will be interested in fundamental groups of non-positively curved (NPC) cube complexes.

Theorem 1.1. [21, Problem 11.7] [45, Conjecture 19.5] Let $G$ be a word-hyperbolic group acting properly and cocompactly on a CAT(0) cube complex $X$. Then $G$ has a finite index subgroup $F$ acting specially on $X$.

Remark: The condition here that $G$ is word-hyperbolic is necessary, since there are examples of simple groups acting properly cocompactly on a product of trees [9].

Corollary 1.2. Let $G$ be a non-elementary word-hyperbolic group acting properly and cocompactly on a CAT(0) cube complex. The $G$ is linear, large, and quasi-convex subgroups are separable.

Theorem 9.1. Let $M$ be a closed aspherical 3-manifold. Then there is a finite-sheeted cover $\tilde{M} \to M$ such that $\tilde{M}$ is Haken.

Theorem 9.2. Let $M$ be a closed hyperbolic 3-manifold. Then there is a finite-sheeted cover $\tilde{M} \to M$ such that $\tilde{M}$ fibers over the circle. Moreover, $\pi_1(M)$ is LERF and large.

Theorem 9.1 resolves a question of Waldhausen [44]. Moreover, Theorem 9.2 resolves [26, Problems 3.50-51] from Kirby’s problem list, as well as [43, Questions 15-18].

There has been much work on the virtual Haken conjecture before for certain classes of manifolds. These include manifolds in the Snappea census [14], surgeries on various classes of cusped hyperbolic manifolds [2, 3, 4, 7, 10, 11, 12, 27, 33, 34], certain arithmetic hyperbolic 3-manifolds (see [41] and references therein), and manifolds satisfying various

Date: May 10, 2014.
Agol supported by DMS-0806027, DMS-1105738 and the Clay Foundation.
Groves supported by DMS-0804365 and CAREER DMS-0953794.
Manning supported by DMS-1104703.
The approach in this paper uses techniques from geometric group theory, and as such does not specifically rely on 3-manifold techniques, although some of the arguments (such as word-hyperbolic Dehn surgery and hierarchies) are inspired by 3-manifold techniques.

Here is a short summary of the approach to the proof of Theorem 1.1. In Section 4 we use a weak separability result (Theorem A.1) to find an infinite-sheeted regular cover $X$ of $X/G$ which has embedded compact 2-sided walls. This covering space has a finite hierarchy obtained by labeling the walls with finitely many numbers (which we think of as colors), so that walls with the same color do not intersect, and cutting successively along the walls ordered by their labels to get an infinite collection of “cubical polyhedra”. The goal is to construct a finite-sheeted cover which is “modeled” on this hierarchy for $X$. We first construct a measure on the space of colorings of the wall graph of $X$ in Section 5. We then refine the colors to reflect how each wall is cut up by previous stages of the hierarchy in Section 6. We use the measure to find a solution to certain gluing equations on the colored cubical polyhedra defined by the refined colorings, and use solutions to these equations to get the base case of the hierarchy in Section 7. We glue up successively each stage of the hierarchy, using a gluing theorem 3.1 to glue at each stage after passing to a finite-sheeted cover. The inductive hypotheses and inductive step of the proof of Theorem 1.1 are given in section 8.

Theorem A.1 generalizes the main result of [1], and is proved in the appendix which is joint work with Groves and Manning. The proof of Theorem A.1 relies on Theorem A.8 which is a result of Wise [45, Theorem 12.3].

Acknowledgements: We thank Nathan Dunfield and Dani Wise for helpful conversations, and Martin Bridson, Frédéric Haglund, Yi Liu, Eduardo Martinez-Pedroza, and Henry Wilton for comments on an earlier draft.

2. Definitions

We expect the reader to be familiar with non-positively curved (NPC) cube complexes [8], special cube complexes [21], and hyperbolic groups [16].

**Definition 2.1.** A flag simplicial complex is a complex determined by its 1-skeleton: for every clique (complete subgraph) of the 1-skeleton, there is a simplex with 1-skeleton equal to that subgraph. A non-positively curved (NPC) cube complex is a cube complex $X$ such that for each vertex $v \in X$, the link $\text{link}_X(v)$ is a flag simplicial complex. If $X$ is simply-connected, then $X$ is CAT(0) [8]. More generally, an NPC cube orbicomplex or orbihedron is a pair $(G, X)$, where each component of $X$ is a CAT(0) cube complex and $G \to \text{Aut}(X)$ is a proper cocompact effective action. We will also call such pairs cubulated groups when $X$ is connected. If $G$ is torsion-free, then $X/G$ is an NPC cube complex. When $G$ has torsion, we may also think of the quotient $X/G$ as an orbi-space in the sense of Haefliger [18, 19]. The orbihedra we will consider in this paper will have covering spaces which are cube complexes, so they are developable, in which case we can ignore subtleties arising in the theory of general orbi-spaces.

Gluing the cubes isometrically out of unit Euclidean cubes gives a canonical metric on an NPC cube complex.
**Definition 2.2.** Given an NPC cube complex $X$, the *wall* of $X$ is an immersed NPC cube complex $W$ (possibly disconnected). For each $n$-cube $C \subset X$, take the $n$ $n-1$-cubes obtained by cutting the cube in half (setting one coordinate = 0), called the *hyperplanes* of $C$. If a $k$-cube $D$ is a face of an $n$-cube $C$, then there is a corresponding embedding of the hyperplanes of $D$ as faces of the hyperplanes of $C$. Take the cube complex $W$ with cubes given by hyperplanes of the cubes of $X$, and gluings given by inclusion of hyperplanes. This cube complex immerses into the cube complex $X$. We will call this immersed cube complex the *wall complex* of $X$. There is a natural line bundle over $W$ obtained by piecing together the normal bundles in each cube. If this line bundle is non-orientable, then the wall $W$ is one-sided. Otherwise, it is 2-sided or co-orientable, and there are two possible co-orientations.

**Definition 2.3.** Let $X$ be an NPC cube complex. A subcomplex $Y \subset X$ is *locally convex* if the embedding $Y \to X$ is a local isometry. Similarly, a combinatorial map $Y \leftrightarrow X$ between NPC cube complexes is called locally convex if it is a local isometry.

The condition of being a local isometry is equivalent to saying that $Y$ is NPC, and for each vertex $v \in Y$, $\text{link}_Y(v) \subset \text{link}_X(v)$ is a very full subcomplex, which means that for any two vertices of $\text{link}_Y(v)$ which are joined by an edge in $\text{link}_X(v)$, they are also joined by an edge in $\text{link}_Y(v)$. For example, an embedded cube in an NPC cube complex is a locally convex subcomplex.

**Definition 2.4** *(Almost malnormal Collection)*. A collection of subgroups $H_1, \ldots, H_g$ of $G$ is almost malnormal provided that $|H_i \cap H_j| < \infty$ unless $i = j$ and $g \in H_i$.

For example, finite collections maximal elementary subgroups of a torsion-free hyperbolic group form an almost malnormal collection.

**Definition 2.5.** Let $X$ be an NPC cube complex, $Y \subset X$ a locally convex subcomplex. We say that $Y$ is *acylindrical* if for any map $(S^1 \times [0, 1], S^1 \times \{0, 1\}) \to (X, Y)$ which is injective on $\pi_1$ is relatively homotopic to a map $(S^1 \times [0, 1], S^1 \times \{0, 1\}) \to (Y, Y)$.

In particular, if $Y \subset X$ is acylindrical, then the collection of subgroups of the fundamental groups of its components form a malnormal collection of subgroups of $\pi_1(X)$.

**Definition 2.6.** ([45, Definition 11.5]) Let $\mathcal{QVH}$ denote the smallest class of hyperbolic groups that is closed under the following operations.

1. $1 \in \mathcal{QVH}$
2. If $G = A \ast_B C$ and $A, C \in \mathcal{QVH}$ and $B$ is finitely generated and embeds by a quasi-isometry in $G$, then $G$ is in $\mathcal{QVH}$.
3. If $G = A \ast_B$ and $A \in \mathcal{QVH}$ and $B$ is f.g. and embeds by a quasi-isometry, then $G$ is in $\mathcal{QVH}$.
4. Let $H < G$ with $[G : H] < \infty$. If $H \in \mathcal{QVH}$ then $G \in \mathcal{QVH}$.

The notation $\mathcal{QVH}$ is meant to be an abbreviation for “quasi-convex virtual hierarchy”. In particular, items (2) and (3) may be replaced by $G$ is a graph of groups, with vertex groups in $\mathcal{QVH}$ and edge groups quasi-convex and f.g. in $G$. A motivating example of a group in $\mathcal{QVH}$ is a 1-relator group with torsion [45, Theorem 18.1], or a closed-hyperbolic 3-manifold which contains an embedded quasi-fuchsian surface.
We will not define special cube complexes in this paper (see [21]). However, we note that a special cube complex with hyperbolic fundamental group has embedded components of the wall subcomplex, and therefore its fundamental group is in the class $QVH$. Moreover, we have

**Theorem 2.7.** [45, Theorem 13.5] A torsion-free hyperbolic group is in $QVH$ if and only if it is the fundamental group of a virtually special cube complex.

This theorem is generalized in the appendix:

**Theorem A.42.** A word-hyperbolic group is in $QVH$ if and only if it is virtually special.

The reader not familiar with virtually special cube complexes or their fundamental groups may therefore take this theorem as the defining property for a virtually special group which will be used in this paper.

We state here a lemma which will be used in the case that $G$ has torsion.

**Lemma 2.8.** Let $G \in QVH$, and suppose that $G'$ is an extension of $G$ by a finite group $K < G'$, so there is a homomorphism $\varphi : G' \to G$ such that $\ker(\varphi) = K$. Then $G' \in QVH$.

**Proof.** First, we remark that we need only check this for central extensions of $G$, since the kernel of the homomorphism $G' \to \text{Aut}(K)$ given by the conjugacy action will be a finite central extension of a finite-index subgroup of $G$. However, this observation does not seem to simplify the argument.

We prove this by induction on the defining properties of $QVH$. Consider the set of all extensions of groups in $QVH$ by the finite group $K$. We prove that this class lies in $QVH$ by showing that these groups are closed under the four operations defining $QVH$.

1. The extension of 1 by $K$ is in $QVH$ by property (4), so $K \in QVH$.
2. Suppose $G = A *_B C$ and $A, C \in QVH$ and $B$ is finitely generated and embeds by a quasi-isometry in $G$.
   We see that for $A' = \varphi^{-1}(A), B' = \varphi^{-1}(B), C' = \varphi^{-1}(C)$, then $\varphi$ is a quasi-isometry, so $B' < G'$ embeds quasi-isometrically in $G'$, and is finitely generated since $B$ is. Also, $A', B', C'$ are finite extensions of $A, B, C$ by $K$ respectively. If $A', B', C' \in QVH$, then $G' \in QVH$ by condition (2).
3. Suppose $G = A *_B A \in QVH$ and $B$ is f.g. and embeds by a quasi-isometry.
   We see that for $A' = \varphi^{-1}(A), B' = \varphi^{-1}(B)$, then $\varphi$ is a quasi-isometry, so $B' < G'$ embeds quasi-isometrically in $G'$, and is finitely generated since $B$ is. Also, $A', B'$ are finite extensions of $A, B$ by $K$ respectively. If $A', B' \in QVH$, then $G' \in QVH$ by condition (3).
4. Suppose $H < G$ with $[G : H] < \infty$ and $H \in QVH$.
   Then for $H' = \varphi^{-1}(H)$, we have $[G' : H'] = [G : H] < \infty$, so if $H' \in QVH$, and $H'$ is a finite extension of $H$ by $K$, then $G' \in QVH$ by condition (4).

Thus, we see that finite extensions of elements of $QVH$ by $K$ are in $QVH$ by induction, so $G' \in QVH$. \[\square\]

### 3. Virtual gluing

In this section, we introduce a technical theorem which will be used in the proof of Theorem 1.1.
**Theorem 3.1.** Let $X$ be a compact cube complex which is virtually special and $\pi_1(X)$ hyperbolic (for each component of $X$ if $X$ is disconnected). Let $Y \subset X$ be an embedded locally convex acylindrical subcomplex such that there is an NPC cube orbi-complex $Y_0$ and a cover $\pi : Y \to Y_0$. Then there exists a regular cover $\overline{X} \to X$ such that the preimage of $Y \leftarrow \overline{Y} \subset \overline{X}$ is a regular orbi-cover $\overline{Y} \to Y_0$.

**Remark:** Keep in mind that all of the complexes in the statement of this theorem may be disconnected.

**Proof.** Let $C\pi$ be the mapping cylinder of $\pi$. Take $X' = X \cup_Y C\pi$ (we’ll assume now that $X'$ is connected; the general case reduces to this case by considering components). Then $X'$ is an NPC cube orbi-complex by [8, Theorem 11.1], and the subspace $Y_0 \subset X'$ is locally convex. By [18], the complex $X'$ is developable, so $X' = \tilde{X}'/G'$ for a hyperbolic group $G' \cong \pi_1(X')$. Moreover, since $Y$ is acylindrical, $Y_0 \subset X'$ is also acylindrical (the reader uncomfortable with oribispaces may just think of $G' = \pi_1(X')$ as an acylindrical graph of groups with quasiconvex edge groups, and apply [25]). The subspace $Y \subset X'$ is $\pi_1$-injective, and cutting along it gives back $X$ and $C\pi$. The cone $C\pi \simeq Y_0$ is virtually special, since $Y \subset X$ is virtually special being a convex subcomplex of a virtually special complex with hyperbolic fundamental group, and $Y \to Y_0$ is a covering orbi-space. We may think of $C\pi \to Y_0$ as a $*$-bundle over $Y_0$, where $*$ is a wedge of $\deg(\pi)$ intervals. By the combination theorem of Bestvina-Feighn [6, Corollary 7], $\pi_1(X')$ is hyperbolic. Therefore $X'$ is in $\mathcal{QVH}$ and virtually special by Theorem A.42. Let $Y' \to Y_0$ be a regular covering space factoring through $Y \to Y_0$. Then there exists a finite-sheeted cover $X'' \to X'$ in which $Y''$ lifts to an embedding since each component of $Y'$ is quasi-convex in $X'$, and therefore is separable by [21, Corollary 7.4]. In particular, the preimage of $C\pi$ meeting $Y'$ in $X''$ is a product $Y' \times *$, where $*$ is a wedge of intervals. Taking a further regular cover of $X'$ gives a covering space in which the induced cover of $Y$ is a regular cover of $Y_0$. \hfill $\Box$

**Remark:** It is possible to give a proof of this theorem using the techniques of [20, Theorem 6.1] rather than citing [45].

### 4. Quotient Complex with Compact Walls

Let $X$ be a CAT(0) cube complex, $G$ a hyperbolic group acting properly and cocompactly on $X$. Recall that we say that $(G, X)$ is a cubulated hyperbolic group. Since the action of $G$ is proper and cocompact, the cube complex $X$ is finite dimensional, locally finite, and quasi-isometric to $G$. By Lemma 2.8, we may assume that $G$ acts faithfully on $X$, since properness implies that the subgroup acting trivially must be finite. The quotient $X/G$ may be interpreted as an orbihedron [18, 19] if $G$ has torsion. Moreover, there are finitely many orbits of walls $W \subset X$. The stabilizer of a wall $G_W$ is quasi-isometric to $W$, and therefore is a quasi-convex subgroup of $G$ since $W$ is totally geodesic and therefore convex in $X$. Let $\{W_1, \ldots, W_m\}$ be orbit representatives for the walls of $X$ under the action of $G$. By induction on the maximal dimension of a cube and Lemma 2.8, we may assume that $G_{W_i}$ is virtually special for $1 \leq i \leq m$. In particular, for each $i$, there is a finite index torsion-free normal subgroup $G_i' \leq G_{W_i}$ such that $W_i/G_i'$ is a special cube complex. There exists $R > 0$ such that if two walls $W, W' \subset X$ have the property that $d(W, W') > R$, then $|G_W \cap G_{W'}| < \infty$. 
For each $1 \leq i \leq m$, let

$$\mathcal{A}_i = \{G_{W_i}gG_{W_i}| d(g(W_i), W_i) \leq R\} - \{G_{W_i}\}.$$ 

Then $\mathcal{A}_i$ is finite for all $i$.

**Lemma 4.1.** We may find a quotient group homomorphism $\phi : G \to \mathcal{G}$ such that for all $1 \leq i \leq m$ and for all $G_{W_i}gG_{W_i} \in \mathcal{A}_i$, $\phi(g) \notin \phi(G_{W_i})$ and $\phi(G_{W_i})$ is finite for all $j$. Moreover, we may assume that the action of $G_{W_i} \cap \ker(\phi)$ does not exchange the sides of $W_i$ (preserves the co-orientation), and that $\ker(\phi)$ is torsion-free and $X^{(1)}/\ker(\phi)$ contains no closed loops.

**Proof.** For each $W_i$, the set of double cosets $\mathcal{A}_i = \{G_{W_i}gG_{W_i}, d(g(W_i), W_i) \leq 2R\} - \{G_{W_i}\}$ is finite. Fix an element $g$ such that $G_{W_i}gG_{W_i} \in \mathcal{A}_i$. Choose elements $g_1, \ldots, g_m$ such that $g_i = 1$ and $H = \langle G_{W_1}, \ldots, G_{W_i}, \ldots, G_{W_m} \rangle \cong G_{W_1^1} \ast \cdots \ast G_{W_i^1} \ast \cdots \ast G_{W_m^1}$ and $g \notin H$, and $H < G$ is quasiconvex. This may be arranged by standard ping-pong arguments. Then $H$ is virtually special since it is a free product of virtually special groups. By Theorem A.1, we may find a quotient $\phi_g : G \to \mathcal{G}_g$ such that $\phi_g(g) \notin \phi(H)$ and $\phi_g(H)$ is finite. Clearly then $\phi_g(G_{W_i})$ is finite for all $j$. Moreover, we may assume that $\ker(\phi_g) \cap G_{W_i}$ is contained in the subgroup preserving the orientation on the normal bundle to $W_i$. Let $\mathcal{A}$ be the finitely many double coset representatives for $\cup_i \mathcal{A}_i$; we use this construction.

Let $T \subset G$ be a finite set of representatives for each conjugacy class of torsion elements of $G$, such that $T \cap G_{W_j} = \emptyset$ for all $j$, and conjugacy class representatives of any group elements identifying endpoints of edges of $X^{(1)}$. We may also apply the same technique to find for each $g \in T$ a homomorphism $\psi_g : G \to \mathcal{G}'$ such that $\psi_g(g) \neq 1$ and $\psi_g(G_{W_i})$ is finite for all $i$.

Define $\phi$ by $\ker(\phi) = \cap_{g \in \mathcal{A}} \ker(\phi_g) \cap \ker(\psi_g)$, then $\phi : G \to \mathcal{G} = G/\ker(\phi)$ has the desired properties. \qed

Let $K = \ker(\phi)$, where $\phi$ comes from the previous lemma, and let $\mathcal{X} = X/K$. Then $\mathcal{X}$ is an NPC cube complex, and for each $i$, the quotient $\mathcal{N}_R(W_i)/(G_{W_i} \cap K)$ embeds in $\mathcal{X}$ under the natural covering map, where $\mathcal{N}_R(W_i)$ is the neighborhood of radius $R$ about $W_i$.

**Definition 4.2.** Form a graph $\Gamma(\mathcal{X})$, with vertices $V(\Gamma(\mathcal{X}))$ consisting of the wall components of $W \subset \mathcal{X}$, and edges $E(\Gamma(\mathcal{X}))$ consisting of pairs of walls $(W_1, W_2)$ in $\mathcal{X}$ such that $d(W_1, W_2) \leq R$. We have a natural action of $\mathcal{G}$ on $\Gamma(\mathcal{X})$.

5. Invariant coloring measures

Let $\Gamma$ be a (simplicial) graph of bounded valence $\leq k$, and let $G$ be a group acting cocompactly on $\Gamma$. Note that the quotient graph $\Gamma/G$ may have loops and multi-edges, so in particular may not be simplicial. We will denote the vertices of $\Gamma$ by $V(\Gamma)$, and the edges by $E(\Gamma) \subset V(\Gamma) \times V(\Gamma)$ consisting of the symmetric relation of pairs of adjacent vertices in $\Gamma$, so that $\Gamma$ is defined by the pair $\Gamma = (V(\Gamma), E(\Gamma))$. Since $\Gamma$ is simplicial, it has no loops, and therefore $E(\Gamma)$ does not meet the diagonal of $V(\Gamma) \times V(\Gamma)$.

**Definition 5.1.** An $n$-coloring of $\Gamma$ is a map $c : V(\Gamma) \to \{1, \ldots, n\} = [n]$ such that for every edge $(u, v) \in E(\Gamma)$, we have $c(u) \neq c(v)$. Let $[n]^{V(\Gamma)}$ be the space of all $n$-colorings of the trivial graph $(V(\Gamma), \emptyset)$, and endow this with the product topology to make it a
compact space (Cantor set). Then the space of $n$-colorings of $\Gamma$ is naturally a closed $G$-

invariant subspace of $[n]^{V(\Gamma)}$ which we will denote $C_n(\Gamma)$. The set $M(C_n(\Gamma))$ of probability
tables on $C_n(\Gamma)$ endowed with the weak* topology is a convex compact metrizable set.

Let $M_G(C_n(\Gamma)) \subset M(C_n(\Gamma)) \subset M([n]^{V(\Gamma)})$ denote the $G$-invariant measures.

Since we have assumed that the degree of every vertex of $\Gamma$ is $\leq k$, then clearly $C_{k+1}(\Gamma)$
is non-trivial: order the vertices, and color each vertex inductively by one of $k+1$ colors
not already used by one of its $\leq k$ neighbors.

**Theorem 5.2.** The set $M_G(C_{k+1}(\Gamma))$ is non-empty, that is, there exists a $G$-invariant
probability measure on the space of $k+1$-colorings of the graph $\Gamma$.

**Proof.** For a $G$-invariant measure $\nu \in M_G([n]^{V(\Gamma)})$, we want to define a quantity which
measures how far $\nu$ is from giving a $G$-invariant coloring measure in $M_G(C_n(\Gamma))$. For an
dge $e = (u, v) \in E(\Gamma)$, let $B_e = \{ f \in [n]^{V(\Gamma)} | f(u) = f(v) \}$. This is the subset of colorings
of $V(\Gamma)$ which violate the coloring condition for $\Gamma$ at the edge $e$, so that $C_n(\Gamma) = \cap_{e \in E(\Gamma)} B_e^c$.
Let $\{e_1, \ldots, e_m\} \subset E(\Gamma)$ be a complete set of representatives of the orbits of the action of
$G$ on $E(\Gamma)$, which exists because we have assumed that the action of $G$ on $\Gamma$ is co-compact.

For $\nu \in M_G([n]^{V(\Gamma)})$ define $\text{weight}(\nu) = \sum_{i=1}^m \nu(B_{e_i})$. If $\nu$ is a $G$-invariant coloring
measure of $\Gamma$, then regarding $\nu \in M_G(C_n(\Gamma)) \subset M_G([n]^{V(\Gamma)})$, we have $\text{weight}(\nu) = 0$. Conversely, if
$\text{weight}(\nu) = 0$ for $\nu \in M_G([n]^{V(\Gamma)})$, then $\nu \in M_G(C_n(\Gamma))$. To see this, let $\text{supp}(\nu) \subset [n]^{V(\Gamma)}$
be the support of $\nu$, which is $\cap_{C \text{ compact}, \nu(C) = 1} C$. Let $e \in E(\Gamma)$, then $\nu(B_e) = 0$, since
there exists $e_i, g \in G$ such that $e = g(e_i)$, so $\nu(B_e) = \nu(B_{g(e_i)}) = \nu(B_{e_i}) = 0$ by $G$-
invariance of $\nu$ and $\text{weight}(\nu) = 0$. Therefore $\text{supp}(\nu) \subset B_e^c$ for all $e \in E(\Gamma)$, and therefore
$\text{supp}(\nu) \subset \cap_{e \in E(\Gamma)} B_e^c = C_n(\Gamma)$. So $\nu \in M_G(C_n(\Gamma))$.

Take the uniform measure $\mu_n$ on $[n]^{V(\Gamma)}$, which is the product of $V(\Gamma)$ copies of the
uniform measure on $[n]$, so $\mu_n \in M([n]^{V(\Gamma)})$. Clearly $\mu_n$ is $G$-invariant under the action of
$G$ on $V(\Gamma)$, $\mu_n \in M_G([n]^{V(\Gamma)})$, since $G$ permutes the uniform measures on $[n]$. We note that
for the uniform measure $\mu_n$ we have $\mu_n(B_e) = 1/n$. Then we see that $\text{weight}(\mu_n) = m/n$.

For $n > k+1$, we define a map $p_n : [n]^{V(\Gamma)} \to [n-1]^{V(\Gamma)}$ which depends on $\Gamma$ and which
is $G$-equivariant. For $c \in [n]^{V(\Gamma)}$ and $v \in V(\Gamma)$, define $p_n(c)(v) = c(v)$ if $c(v) < n$, and if
c($v$) = $n$, then $p_n(c)(v) = \min\{1, \ldots, n-1\} - \{c(u) | (u, v) \in E(\Gamma)\}$. Since the degree of
$v$ is $\leq k$, this set is non-empty, and has a well-defined minimum which is $\leq k+1$. In other
words, $p_n(c)$ assigns to each vertex colored $n$ the smallest color not used by its neighbors,
and otherwise does not change the color. Then $p_n(c)$ has the property that for any two
vertices $u, v \in V(\Gamma)$ with $p_n(c)(u) = p_n(c)(v)$, then $c(u) = c(v)$. In particular, if $c$ is an
$n$-coloring of $\Gamma$, then $p_n(c)$ is an $n-1$-coloring of $\Gamma$. This implies that for all measures
$\nu \in M_G([n]^{V(\Gamma)})$, $\text{weight}(p_n(\nu)) \leq \text{weight}(\nu)$, where $p_n(\nu)$ is the push-forward measure.
Notice that the map $p_n$ is continuous, since its definition is local, so that the push-forward is well-defined.

This gives a map $P_n : [n]^{V(\Gamma)} \to [k+1]^{V(\Gamma)}$ defined by $P_n = p_{k+1} \circ p_{k+2} \circ \cdots \circ p_n$. We
get induced a map $P_n^* : M([n]^{V(\Gamma)}) \to M([k+1]^{V(\Gamma)})$ by push-forward of measures, and
induces a map by restriction $P_n^* : M_G([n]^{V(\Gamma)}) \to M_G([k+1]^{V(\Gamma)})$ because the maps $p_n$ are
$G$-equivariant.

Finally, we have $\text{weight}(P_n^*(\mu)) \leq \text{weight}(\mu)$ for any $\mu \in M_G([n]^{V(\Gamma)})$. In particular,
$\text{weight}(P_n^*(\mu_n)) \leq \text{weight}(\mu_n) = m/n$. Take a subsequence of $\{P_n^*(\mu_n)\}$ converging to
a $G$-invariant measure $\mu_\infty \in M_G([k + 1]^V(\Gamma))$. Then \(\text{weight}(\mu_\infty) = 0\), which implies that $\mu_\infty \in M_G(C_{k+1}(\Gamma))$. \(\square\)

6. Cube complexes with boundary patterns

Given a locally finite cube complex $X$, subdivide each $n$-cube into $2^n$ cubes of half the size to get a cube complex $\hat{X}$ (Figure 1(b)). This is called the cubical barycentric subdivision, and is analogous to the barycentric subdivision of a complex, in that one inserts new vertices in the barycenter of each cube, and connects each new barycenter vertex of each cube to the barycenter vertex of each cube containing it, then filling in cubes using the flag condition (the difference with the usual barycentric subdivision is that one does not connect the vertices of $X$ to the new barycenter vertices, which would give a simplicial complex). We may then regard the union of the hyperplanes $W \subset X$ as the union of the new topological codimension-one cubes of $\hat{X}$, which is the locally convex subcomplex $\hat{W} \subset \hat{X}$ spanned by the barycenter vertices of $\hat{X}$. Consider splitting $X$ along the hyperplanes $W$. By this, we mean remove each hyperplane, getting a disconnected complex, then put in $2^k$ copies of each codimension-$k$ cube that is removed to get a complex $X \setminus \setminus W = \hat{X} \setminus \setminus \hat{W}$ (see Figure 1(c)). We will think of this as a cube complex “with boundary”, where the boundary consists of the new cubes that were attached at the missing hyperplanes. What remains are stars of the vertices of $X$.

![Figure 1. Subdividing and splitting a cube complex](image)

**Definition 6.1.** A cubical polyhedron $P$ is a CAT(0) cube complex with a distinguished vertex $v \in P$ which is contained in every maximal cube. The polyhedron is determined by a simplicial graph $\Gamma$ which is the 1-skeleton of $\text{link}(v)$, which is a flag CAT(1) spherical simplicial complex. To recover $P$ from a connected simplicial graph $\Gamma$, we may make a spherical complex by taking a right-angled spherical $k$-simplex for each $k + 1$ clique of $\Gamma$. 
glued together by the natural inclusion of cliques. This gives a CAT(1) spherical complex since it is flag \[8, \text{Theorem 5.18}\]. Then attach the corner of a Euclidean \(k + 1\) cube to each spherical \(k\)-simplex to get a cubical polyhedron. This is a non-positively curved cube complex \(P(\Gamma)\) \[8, \text{Theorem 5.20}\].

The stars of vertices in an NPC cube complex are cubical polyhedra, and if we split \(\hat{X}\) along all of its hyperplanes, we get a union of stars of vertices and therefore cubical polyhedra.

**Definition 6.2.** A cube complex with boundary pattern is a cube complex \(X\) of bounded dimension together with locally convex subcomplexes \(\{\partial_1 X, \ldots, \partial_n X\}\), \(\partial_i X \subset X\) satisfying the following inductive definition (induct on the maximal dimension cube):

- For each \(i\), there is an isometrically embedded open product neighborhood \(\partial_i X = \partial_i X \times 0 \subset \partial_i X \times [0,1) \subset X\). In particular, the dimension of each maximal cube of \(X\) is one less than the dimension of a cube of \(X\) containing it. The intersection of \(\partial_i X\) with each cube must contain at most one face, and the intersection of all of the strata of the boundary pattern which have non-trivial intersection with a fixed cube is a non-empty face.
- For each \(i\), the subcomplex \(\partial_i X\) forms a cube complex with boundary pattern \(\{\partial_j X \cap \partial_i X\} = \{\partial_j X \times [0,1)\} \cap \partial_i X\).

What one may keep in mind for this definition is the analogy of a boundary pattern for a hierarchy of a 3-manifold, arising in the work of Haken \[22\].

If \(X\) is a cube complex with boundary pattern \(\{\partial_1 X, \ldots, \partial_n X\}\), then each \(\partial_i X\) gets a co-orientation of the collar neighborhood \(\partial_i X \times [0,1)\), pointing into \(X\) from 0 to 1 (into the cube complex). We may similarly define a cubical orbihedron with boundary pattern as a cube complex with boundary pattern quotient a group that preserves the boundary pattern.

**Examples:** Take a graph \(X\), and let \(\partial_0 X \subset X\) be the vertices of \(X\) which have degree 1, then \(X\) is a cube complex with boundary pattern \(\partial_0 X\).

Take a cubical polyhedron \(P(\Gamma)\) associated to a simplicial graph \(\Gamma\). For each vertex \(v\) \(\in \Gamma\), consider the subcomplex defined by \(\text{link}(v) \subset \Gamma\), \(P(\text{link}(v)) \subset P(\Gamma)\). Then \([0,1] \times P(\text{link}(v)) \subset P(\Gamma)\). The collection \(\{1\} \times P(\text{link}(v))\) \(v \in V(\Gamma)\) forms a boundary pattern of \(P(\Gamma)\). We will denote the union of this collection as \(\partial P(\Gamma)\). We will call components \(\{1\} \times P(\text{link}(v))\) the **facets** of \(P(\Gamma)\). If a collection of facets of \(P(\Gamma)\) have non-trivial intersection, then their intersection is a convex subcomplex we’ll call a **face**. The minimal faces will be points, which we will call **vertices** of \(P(\Gamma)\).

**Remark:** The choice of terminology **cubical polyhedron** is meant to evoke a polyhedron. When \(X\) is PL equivalent to a manifold, then each component of \(X\) \(\setminus W\) is homeomorphic to a ball, with the boundary pattern corresponding to the facets of the polyhedron.

**Definition 6.3.** Let \(X\) be a cube complex with boundary pattern \(\{\partial_1 X, \ldots, \partial_n X\}\). Suppose there is an isometric involution \(\tau : \partial_n X \to \partial_n X\) without fixed points, and with the property that \(\tau(\partial_i X \cap \partial_n X) = \partial_i X \cap \partial_n X\) for \(i < n\). Then we may form the quotient complex \(X/\tau\), where for each cube \(c \subset \partial_n X\), we amalgamate the cubes \(c \times [-1,0]\) and \(\tau(c) \times [0,1]\) into a single cube isometric to \(c \times [-1,1]\). We obtain an induced boundary
pattern \( \{ \partial_i X / (\tau_{[\partial_i X \cap \partial_n X]} \mid i < n) \} \). This operation on \( X \) is called \textit{gluing a cube complex with boundary pattern}.

**Definition 6.4.** Let \( X \) be a cube complex and let \( W \subset X \) be a union of disjointly embedded 2-sided walls. We may \textit{split} \( X \) along \( W \) by taking the path-metric completion of \( X - W \). This is obtained from \( X - W \) by adjoining two copies of \( W \) on either side of the wall, which we’ll call \( W^+ \) and \( W^- \), with co-orientations pointing into \( X - W \). We will denote this \( X \setminus W \). If \( X \) is a cube complex with boundary pattern \( \{ \partial_1 X, \ldots, \partial_m X \} \), then \( X \setminus W \) is a cube complex with boundary pattern \( \{ \partial_1 X, \ldots, \partial_m X, W^+ \cup W^- \} \). This is the reverse operation from gluing a cube complex with boundary pattern.

If we have a cube complex \( X \) with embedded walls \( W \subset X \), then \( X \setminus W \) (which really means we split \( X \) successively along each component of \( W \)) will be a union of cubical polyhedra which are stars of vertices of \( X \). For the complex \( \mathcal{X} \) with walls \( \mathcal{W} \) constructed at the end of Section 4, let \( \mathcal{P}(\mathcal{X}) \) be the set of cubical polyhedra which are stars of vertices, and let \( P_1, \ldots, P_p \) be orbit representatives under the action of \( \mathcal{G} \) of the cubical polyhedra of \( \mathcal{X} \setminus \mathcal{W} \) which are vertex stars (we will think of these as the polyhedra obtained by splitting \( \mathcal{X} \) along its walls). Similarly, let \( W_1, \ldots, W_w \) be orbit reps. of the walls \( \mathcal{W} \) under the action of \( \mathcal{G} \). Let \( \mathcal{F}(\mathcal{X}) \) denote the set of all cubical polyhedra of the walls \( \mathcal{W} \). These are the stars of midpoints of edges of \( \mathcal{X} \) in \( \mathcal{W} \).

**Definition 6.5.** Let \( k = \text{maxdegree}(\Gamma(\mathcal{X})) \), then \( C_{k+1}(\Gamma(\mathcal{X})) \neq \emptyset \). We want to define an equivalence relation \( \simeq \) on \( V(\Gamma(\mathcal{X})) \times C_{k+1}(\Gamma(\mathcal{X})) \). What this equivalence relation captures in part is how each wall is cut up by the previous walls in the ordering determined by a wall coloring. In other words, a coloring determines a hierarchy for \( \mathcal{X} \), and an induced hierarchy on each wall of \( \mathcal{X} \). The equivalence relation captures how each wall is cut up by previous stages of the hierarchy. This refinement is important for when we reconstruct the hierarchy to make sure after gluing up the \( j \)th level of the hierarchy that the \( j - 1 \)st levels and lower are still matching up to finite index. We define it inductively.

First, for \( (v, c), (w, d) \in V(\Gamma(\mathcal{X})) \times C_{k+1}(\Gamma(\mathcal{X})) \), if \( (v, c) \simeq (w, d) \), then we must have \( v = w \) and \( c(v) = d(w) \) (so the partition respects the vertex type). In other words, we want to define a partition refining the partition \( \{ v \} \times C_{k+1}(\Gamma(\mathcal{X})) \) (but it will depend on the partitions associated to nearby vertices which is why we define it for all vertices simultaneously).

1. We have \( (v, c) \simeq (v, d) \) if \( c(v) = d(v) = 1 \).
2. We have \( (v, c) \simeq (v, d) \) if \( c(v) = d(v) = 2 \) and for all \( w \) such that \( (w, v) \in E(\Gamma(\mathcal{X})) \), we have \( c(w) = 1 \iff d(w) = 1 \).
3. The \( j \)th inductive step of the definition is given by: we have \( (v, c) \simeq (w, d) \) if \( c(v) = d(v) = j \) with \( 2 \leq j \leq k + 1 \), and for all \( w \) such that \( (w, v) \in E(\Gamma(\mathcal{X})) \), we have \( (w, c) \simeq (w, d) \) if \( c(w) < j \) or \( d(w) < j \).

Notice that the equivalence class of \( (v, c) \) where \( c(v) = j \) depends only on \( c \) restricted to the ball of radius \( j - 1 \) about \( v \) in \( \Gamma(\mathcal{X}) \). This implies that the equivalence classes are
clopen sets as subsets of \( \{v\} \times C_{k+1}(\Gamma(X)) \). In fact, if we think of the coloring \( c \) as a Morse function on the vertices \( V(\Gamma) \), then the equivalence class of \( (v, c) \) depends only on the “descending subgraph” of \( v \), consisting of the union of all paths in \( \Gamma(X) \) starting at \( v \) in which the values of \( c \) are decreasing.

We now want to define an equivalence relation \( \simeq \) on the set \( \mathcal{F}(X) \times C_{k+1}(\Gamma(X)) \). We decree \( (E, c) \simeq (E, d) \) if \( \text{wall}(E), c \simeq \text{wall}(E), d \).

We define an equivalence relation \( \simeq \) on \( \mathcal{P}(X) \times C_{k+1}(\Gamma(X)) \) \( (P, c) \simeq (P, d) \) if for every facet \( F \subset \partial P \), \( (F, c) \simeq (F, d) \). In particular, the colors \( c(F) \) of the facets \( F \subset \partial P \) depend only on the \( \simeq \) equivalence class of \( (P, c) \).

We have an action of \( G \) of each of these equivalence relations, by the action for \( g \in G \) given by \( g \cdot (v, c) = (g \cdot v, c \circ g^{-1}) \), for \( (v, c) \in W \times C_{k+1}(\Gamma(X)) \), and a similar formula for the action on faces and polyhedra. There are finitely many \( G \)-orbits of equivalence classes under the action of \( G \), and we may find representatives among \( \{W_1, \ldots, W_w\} \times C_{k+1}(\Gamma(X)), \{F_1, \ldots, F_f\} \times C_{k+1}(\Gamma(X)) \), and \( \{P_1, \ldots, P_p\} \times C_{k+1}(\Gamma(X)) \).

7. Gluing equations

We will consider weights on equivalence classes of polyhedra \( \omega : \mathcal{P}(X) \times C_{k+1}(\Gamma(X)) / \simeq \to \mathbb{R} \) which are invariant under the action of \( G \), so that \( \omega(g \cdot (P, c)) = \omega(P, c) \), for all \( g \in G \) and satisfying the polyhedral gluing equations. A weight \( \omega \) will be determined by its values on \( \{[P_j, c], 1 \leq j \leq p, c \in C_{k+1}(\Gamma(X))\} \), and therefore is determined by finitely many variables. Given polyhedra \( P, P' \subset \hat{X} \) sharing a facet \( F \subset \partial P, F \subset \partial P' \), we get an equation on the weights for each equivalence class of \( \{F\} \times C_{k+1}(\Gamma(X)) / \simeq \). For each equivalence class \( ([F, c]) \in \{F\} \times C_{k+1}(\Gamma(X)) / \simeq \), we have the equation

\[
\sum_{[(P, d)] = (F, c)} \omega([P, d]) = \sum_{[(P', d)] = (F, c)} \omega([P', d]).
\]

The polyhedral gluing equations on the polyhedra equivalence class weights are the equations obtained for each equivalence class \( ([F, c]) \). These equations are also \( G \)-equivariant, so in particular are determined by the equations for equivalence classes \( ([F_i, c]), 1 \leq i \leq f, c \in C_{k+1}(\Gamma(X)) \). Thus, we have finitely many equations determined by equivalence classes \( ([F_i, c]), 1 \leq i \leq f \) on finitely many variables \( \omega([P_j, c]), 1 \leq j \leq p \), together with the equations determined by \( G \)-invariance.

For a measure \( \mu \in M_G(C_{k+1}(\Gamma(X))) \), we get non-negative polyhedral weights \( \mu([P, c]) = \mu([d \in C_{k+1}(\Gamma(X)) | (P, c) \simeq (P, d)]) \) (and \( \mu([F, c]) \) is similarly defined for each facet \( F \)). These weights satisfy the polyhedral gluing equations. Consider a facet \( F = \partial P \cap \partial P' \), and an equivalence class \( ([F, c]) \) which defines a gluing equation. Then using the additivity property of \( \mu \), we have

\[
\sum_{[(P, d)] = (F, c)} \mu([P, d]) = \mu([d \in \partial F, F \simeq (F, c)]) = \mu([F, c]) = \sum_{[(P', d)] = (F, c)} \mu([P', d]).
\]

So \( \mu \) gives a non-negative real solution to the polyhedral gluing equations.
Since these equations are defined by finitely many linear equations with integral coefficients, there is a non-negative non-zero integral weight function satisfying the polyhedral gluing equations, $\Omega : \mathcal{P}(\mathcal{X}) \times C_{k+1}(\Gamma(\mathcal{X})) \rightarrow \mathbb{Z}_{\geq 0}$. In the next section we will use $\Omega$ to create a tower hierarchy which gives a finite-sheeted cover of $X/G$ in $\mathcal{QVH}$.

8. Virtually gluing up the hierarchy

Let $(w,c) \in V(\Gamma(\mathcal{X})) \times C_{k+1}(\Gamma(\mathcal{X}))$. Let $\mathcal{W}_j^c = \cup\{w \in V(\Gamma(\mathcal{X}))|c(w) = j\} \subset \mathcal{W}$, $1 \leq j \leq k + 1$, the union of walls colored $j$ by $c$. Suppose that $c(w) = j > 1$, then define $w^{\circ}_{i} = w\setminus(w \cap \mathcal{W}_j^c)$. We may think of $w^{\circ}_{i}$ as being immersed in the wall $w$. Then define inductively immersed complexes in $w$ by $w^{\circ}_{i} = w^{\circ}_{i-1}\setminus(w^{\circ}_{i-1} \cap \mathcal{W}_j^c)$, for $2 \leq i \leq j - 1$. We don’t split $w$ along $\mathcal{W}_j^c$ since $w \subset \mathcal{W}_j^c$. We will use the notation $w^{\circ}_{j-1} = w^c$, since the $j = c(w)$ is implicitly determined (if $j = 1$, then $w^c = w$). The complex $w^c$ has a boundary pattern, given by $\partial_i(w^c) = w^c \cap \mathcal{W}_i^c$, $1 \leq i \leq j - 1$.

Claim: If $(w,c) \simeq (w,d)$, then $w^c = w^d$ (as cube complexes with boundary pattern). In other words, $w^c$ depends only on the equivalence class $[(w,c)]$. This follows because $w^c$ is determined by $w \cap \mathcal{W}_i^c$, $1 \leq i \leq j - 1$, which depends only on the equivalence class of $(w,c)$ since if $v$ is a component of $\mathcal{W}_i^c$ with $w \cap v \neq \emptyset$, then $(w,v) \in E(\Gamma(\mathcal{X}))$.

Consider now the symmetries of $w^c$ which preserve the equivalence class. That is, consider $Stab(w^c) \leq \mathcal{G}$, given by $g \in \mathcal{G}$ such that $g(w^c) = w^c$ (in particular, $g(w) = w$) and $(w, c \circ g^{-1}) = (g(w), c \circ g^{-1}) \simeq (w,c)$. Now define $w^c_\mathcal{G} = w^c/\text{Stab}(w^c)$, with its corresponding boundary pattern $\partial_i(w^c_\mathcal{G}) = \partial_i(w^c)/\text{Stab}(w^c)$, $1 \leq i \leq j - 1$. In general, $w^c_\mathcal{G}$ will be an orbihedron with boundary pattern.

For each $j$, $1 \leq j \leq k + 1$, let $\mathcal{V}_j = \cup[(w,c),c(w)=j]w^c_\mathcal{G}$ (where we take precisely one $\mathcal{G}$-orbit representative of the equivalence relation $\simeq$ so that there are only finitely many equivalence classes $[(w,c)]$ up to the action of $\mathcal{G}$, and therefore $\mathcal{V}_j$ is a compact cube complex). The orbihedron $\mathcal{V}_j$ has the property that for each $\mathcal{G}$-orbit of equivalence class $[(F,c)]$ with $c(F) = j$, there is a unique representative of $(F,c)$ in the complex $\mathcal{V}_j$. At two extremes, we have $\mathcal{V}_1 = \cup\{W_1/\text{Stab}(W_1),...W_w/\text{Stab}(W_w)\}$, since the equivalence class depends only on the orbit of the walls under the action of $\mathcal{G}$. We have $\mathcal{V}_{k+1} = \cup\{(F,c)/\text{Stab}([F,c])|c(\text{wall}(F)) = k + 1\}$, with boundary pattern $\partial_i(F)/\text{Stab}([F,c]) = (F \cap \mathcal{W}_i^c)/\text{Stab}([F,c])$, $1 \leq i \leq k$. 

Proof of Theorem 1.1. We will construct a sequence of (usually disconnected) finite cube complexes $\mathcal{V}_j$, $k + 1 \geq j \geq 0$, with boundary pattern $\{\partial_1(\mathcal{V}_j),...\partial_j(\mathcal{V}_j)\}$ which have the following properties:

1. there is a locally convex combinatorial immersion $\nu_j : \mathcal{V}_j \rightarrow X/G = \mathcal{X}/\mathcal{G}$
2. $\mathcal{V}_j$ is glued together from copies of $\mathcal{G}$-orbits of equivalence classes of polyhedra $\mathcal{P}(\mathcal{X}) \times C_{k+1}(\Gamma(\mathcal{X}))/\simeq$ in such a way that if polyhedra $P,P' \subset \mathcal{V}_j$ share a facet $F$, then the induced equivalence class of $F$ is the same. More formally, there is a decomposition of $\mathcal{V}_j$ into cubical polyhedra $\{P_h\}$, such that there is a lift $P_h \rightarrow \mathcal{X}$ to a polyhedron of $\mathcal{X}$ (well-defined up to the action of $\mathcal{G}$) which projects to the map $\nu_{j|[P_h]} : P_h \rightarrow \mathcal{X}/\mathcal{G}$. Moreover, there is a coloring $c_h \in C_{k+1}(V(\Gamma(\mathcal{X})))$, with a well-defined equivalence class associated to the lift $P_h \rightarrow \mathcal{X}$. If $P_g,P_h$ share a facet $F$, so that $F = \partial P_g \cap \partial P_h \subset \mathcal{V}_j$, then there is a lift $P_g \cup_F P_h \rightarrow \mathcal{X}$ which projects
to the map $\nu_j : P_g \cup_F P_h \to \hat{X}/G$. We want the colorings to be compatible, in the sense that $(F, c_g) \simeq (F, c_h)$. Thus, there is a well-defined map $c_j : F(\mathcal{V}_j) \to \{k + 1\}$.

(3) The boundary of $\mathcal{V}_j$ is the union of all facets $F$ contained in precisely one polyhedron $\partial P_g \subset \mathcal{V}_j$. Moreover, the boundary pattern $\partial \mathcal{V}_j = \cup_{F \in F(\mathcal{V}_j), c_j(F) = i} F$, $1 \leq i \leq j$. Thus, a facet $F$ is an interior facet (contained in the boundary of two polyhedra) if and only if $c_j(F) > j$.

(4) The multiplicities of $\mathcal{G}$-orbits of equivalence classes of colored polyhedra making up $\mathcal{V}_j$ satisfy the polyhedral gluing equations. In particular, for each equivalence class $[(F, c)]$, $F = \partial P \cap \partial P'$, the number of lifts $P_g \to P$ with coloring $c_g$ which induce equivalent colorings $(F, c_g) \simeq (F, c)$ on $F$ is equal to the number of lifts $P_h \to P'$ which induce equivalent colorings $(F, c_h) \simeq (F, c)$.

The base case $\mathcal{V}_{k+1}$ is the collection of equivalence classes of polyhedra given by the solution to the polyhedral gluing equations $\Omega$ found in the previous section. Recall we proved the existence of $\Omega : \mathcal{P}(\mathcal{X}) \times C_{k+1}(\Gamma(\mathcal{X}))/\simeq \to \mathbb{Z}_{\geq 0}$ satisfying the polyhedral gluing equations. For each equivalence class $[(P_j, c)]$, take $\Omega(P_j, c)$ copies of $P_j$, $1 \leq j \leq p$, keeping track of the coloring $c$ associated to each copy of $P_i$, and take the disjoint union of these to get $\mathcal{V}_{k+1}$. Each polyhedron has a locally convex map to $\hat{X}/G$, so condition (1) holds. These have the empty gluing, each component of $\mathcal{V}_{k+1}$ has a lift to $\hat{X}$ and coloring determined by the polyhedral equivalence class, so condition (2) holds. Every facet of $\mathcal{V}_{k+1}$ is a subset of $\partial \mathcal{V}_{k+1}$, so there are no restrictions on the facets and condition (3) holds. Property (4) holds trivially since $\Omega$ is a solution to the polyhedral gluing equations.

Now, suppose we have constructed $\mathcal{V}_j$ with these properties, for $1 \leq j \leq k + 1$. Let’s prove the existence of $\mathcal{V}_{j-1}$. The way that we will do this is to prove that $\partial \mathcal{V}_j$ covers components of $\mathcal{V}_j$ with degree zero. By degree zero, we mean that for each facet of $\mathcal{V}_j$, the number of facets of $\partial \mathcal{V}_j$ which cover the facet and have one co-orientation is equal to the number with the opposite co-orientation, where the co-orientation points into the adjacent polyhedron. Then we will appeal to Theorem 3.1 to take a cover $\hat{\mathcal{V}}_j$ of $\mathcal{V}_j$ which may be glued along $\partial \mathcal{V}_j$ to form $\mathcal{V}_{j-1}$. We must further check that it satisfies the inductive hypotheses.

**Claim:** $\partial \mathcal{V}_j$ covers components of $\mathcal{V}_j$ with degree zero.

First, note that condition (1) implies that each facet $F$ of $\mathcal{V}_j$ is contained in at most two polyhedra of $\mathcal{V}_j$, because the map $\nu_j : \mathcal{V}_j \to \hat{X}/G$ is locally convex. In particular, the map is injective on links of vertices lifted to $\hat{X}$, and therefore is also injective on links of facets lifted to $\hat{X}$. So the gluing given in condition (2) identifies facets of the polyhedra in pairs. As described in condition (3), the facets contained in exactly one polyhedron form the boundary of $\mathcal{V}_j$, and therefore a facet of $\mathcal{V}_j$ which is not in the boundary of $\mathcal{V}_j$ must be contained in precisely two polyhedra of $\mathcal{V}_j$. Also, because the map $\mathcal{V}_j \to \hat{X}/G$ is locally convex, the link of each polyhedron vertex of $\mathcal{V}_j$ is the link of a product of open intervals and half-open intervals. This implies that any path in $\partial \mathcal{V}_j$ may be deformed to lie in a sequence of adjacent facets of $\partial \mathcal{V}_j$, meeting in codimension-one facets of $\partial \mathcal{V}_j$. In fact, from the inductive construction, $\mathcal{V}_j$ will have a hierarchy of length $k + 1 - j$ that induces such a hierarchy on each boundary component as well.
Consider a polyhedral facet $F$ involved in the boundary pattern $\partial_j \mathcal{V}_j$, which by hypothesis (2) has a lift $F \to \hat{\mathcal{X}}$ and an associated equivalence class $[(F,c)]$, some $c \in C_{k+1}(\Gamma(\mathcal{X}))$. The adjacent polyhedron $\partial P \supset F$ has an equivalence class $[(P,d)]$ that is a polyhedron of $\mathcal{V}_j$ by property (2) such that $(F,d) \simeq (F,c)$. For a facet $F'$ of $\partial P$ adjacent to $F$ with color $d(F') > j$, there must be an adjacent polyhedron $P' \subset \mathcal{V}_j$ containing $F' \subset \partial P'$, since this facet cannot occur as part of the boundary pattern of $\mathcal{V}_j$ by condition (3). Then there is a unique facet $F'' \subset \partial P'$ meeting $F'$ such that $F' \cap F = F'' \cap F'$ and by condition (2) $F \cup_{F \cap F''} F'' \subset P \cup_{P'} P' \to \hat{\mathcal{X}}$ is a lift of the map $\nu_j|_F$ (from condition (1)) such that $F \cup F'' \subset \text{wall}(F)$ (so $\text{wall}(F) = \text{wall}(F'')$, see Figure 2). Let $[(P',d')]$ be the equivalence class associated to $P'$ (which exists by condition (2)). Then $(F',d') \simeq (F',d)$ by the condition (2). We have $(\text{wall}(F),\text{wall}(F')) \in E(\Gamma(\mathcal{X}))$. Also, $d(\text{wall}(F)) < d(\text{wall}(F'))$, $d'(\text{wall}(F'')) < d'(\text{wall}(F'))$, by the inductive hypothesis on $\mathcal{V}_j$. Since $(F',d') \simeq (F',d')$, and therefore $(\text{wall}(F'),d) \simeq (\text{wall}(F'),d')$, we have $(\text{wall}(F),d) = (\text{wall}(F''),d) \simeq (\text{wall}(F''),d')$ by one of the conditions of the equivalence relation $\simeq$. Also, the lift $F \cup_{F \cap F''} F'' \to \text{wall}(F)^d \ni \text{wall}(F)$, since $d(F') > j$.

![Figure 2. Developing $\partial_j \mathcal{V}_j$](image)

Take a path $\alpha : I \to \partial_j \mathcal{V}_j$ starting at $F$, and going through a sequence of facets $F = F_0, F_1, F_2, \ldots, F_m$, such that $F_i$ is associated to a coloring $d_i$. We may assume each of these facets intersects its neighbors in codimension-one facets of $\partial_j \mathcal{V}_j$, by the observation above. We see that once we choose a lift $F \to \text{wall}(F)^d \subset \mathcal{X}$, we get a lift $\tilde{\alpha} : I \to \text{wall}(F)^d$, and corresponding lifts $F_i \to \text{wall}(F)^d$. Moreover, $(\text{wall}(F),d_0) \simeq (\text{wall}(F),d_i)$. If $\alpha$ is a closed path so that $F_k = F$, then the lift $F_k \to \text{wall}(F)^d$ induces an equivalent coloring of $\text{wall}(F)$. Thus, we see that the lift $F \to \text{wall}(F)^d$ is well-defined up to the action of $\text{Stab}(\text{wall}(F)^d)$, so we get a well-defined lift of the component $Z$ of $\partial_j \mathcal{V}_j$ containing $F$ to a map $Z \to \text{wall}(F)^d/\text{Stab}(\text{wall}(F)^d) = \text{wall}(F)^d_G$.

Conversely, if a facet $F' \subset \partial P$ adjacent to $F$ is colored $d(\text{wall}(F')) = i < j = d(\text{wall}(F))$, then $F'$ must be part of the boundary pattern $\partial_i \mathcal{V}_j$ by condition (3). Then $F' \cap F \subset \partial_i (\partial_j \mathcal{V}_j)$. Thus, we have a map $\pi : Z \to \text{wall}(Z)^d_G$ which is a covering projection onto the component of its image. The condition (4) ensures that the map $\partial_j \mathcal{V}_j \to \mathcal{Y}_j$ is degree zero, since for each facet equivalence class $[(F,c)]$ with $c(F) = j$, there is a unique representative of the $G$-orbit of $(F,c)$ in the complex $\mathcal{Y}_j$. Thus, the number of representatives of $[(F,c)]$ in
∂\ JV_j with one co-orientation will cancel with the other co-orientation by the gluing equation
for the class [(F, c)]. This finishes the proof of the claim that ∂V_j covers components of
Y with degree zero.

Next, we need to show that ∂V_j is acylindrical in V_j in order to apply Theorem 3.1.
Suppose that there is an essential cylinder (S^1 × [0,1], S^1 × {0,1}) → (V_j, ∂V_j).
We may assume that for each z ∈ S^1, (z × [0, 1], z × {0, 1}) → (V_j, ∂V_j) is a minimal length
godesic between the components of ∂V_j. There are elevations of each component of
∂V_j → X which map to a locally convex immersion to a wall W ⊂ X. We may therefore
choose a compatible elevation (S^1 × [0, 1], S^1 × {0}, S^1 × {1}) → (X, Y_0, Y_q),
where Y_0, Y_q ∈ V(Γ(X)), which must also be an essential cylinder. Therefore the walls Y_0, Y_q ∈ X
must be distance ≤ R, and therefore (Y_0, Y_q) ∈ E(Γ(X)), so Y_0 and Y_q must have distinct colors
in any coloring c ∈ C_k+1(Γ(X)), so c(Y_0) ≠ c(Y_q). However, because there is a cylinder
between the walls Y_0, Y_q, there must be a sequence of walls Y_0, Y_1, ..., Y_q such that
the geodesic z × [0, 1] intersects this sequence of walls for some generic z. There will also
be a sequence of facets F_0, F_1, ..., F_q, F_i ⊂ Y_i that the geodesic meets, and sequence of
polyhedra P_1, ..., P_q, with F_{i−1} ∪ F_i ⊂ ∂P_i, i = 1, ..., q. Associated to each P_i
is an equivalence class of colorings [(P_i, d_i)], and since the facets F_1, ..., F_{q−1} are interior to V_j,
we must have (F_i, d_{i−1}) ≃ (F_i, d_i). In particular, d_{i−1}(Y_0) = d_i(Y_0), d_{i−1}(Y_q) = d_i(Y_q),
i = 1, ..., q. But then d_0(Y_0) = j, d_0(Y_q) = d_q(Y_q) = j, which contradicts the fact that
d_0(Y_0) ≠ d_0(Y_q) since (Y_0, Y_q) ∈ E(Γ(X)). Thus, we conclude that the cylinder does not exist,
and therefore ∂V_j is acylindrical in V_j.

To recap, we have an acylindrical subcomplex ∂V_j ⊂ V_j. Moreover, the components Z
of ∂V_j are partitioned into equivalence classes determined by the equivalence relation of
the equivalence class of wall(Z) together with coloring. Each component covers a component of
wall(Z)_{eq} for some ≃ equivalence class [(wall(Z), c)]. Thus, there is a union of components
Z_j ⊂ Y_j such that there is a cover ∂V_j → Z_j. Moreover, the cover is degree 0 with
respect to the co-orientation. We split ∂V_j = ∂V_j^+ ∪ ∂V_j^− ∪ ∂V_j^0, determined on each component by whether the cover of the corresponding component of Z_j preserves or reverses co-orientation, unless Stab(wall(Z)^c) exchanges the sides of wall(Z), in which case we may
ignore the orientation and it lies in ∂V_j^0.

By Theorem 3.1, there is a regular covering space \hat V_j → V_j, with boundary pattern
{∂_i\hat V_j, ..., ∂_j\hat V_j} given by the preimages of ∂_i V_j, such that the induced covering space
∂_j\hat V_j → Z_j is regular. Since the degree of the cover is zero, we must have that the covers
∂_j\hat V_j^{+} → Z_j and ∂_j\hat V_j^{−} → Z_j are common covers. After gluing the co-oriented components
of ∂_j\hat V_j, we may take two copies of the resulting complex, and glue the non-co-oriented components
∂_j\hat V_j^{eq} by co-orientation reversing isometries which exchange the sides in pairs
(we’ll rename the 2-fold cover \hat V_j for simplicity). Thus, there is an isometric involution
τ_j : ∂_j\hat V_j → ∂_j\hat V_j. We may form the quotient space V_{j−1} = \hat V_j/\tau_j by gluing the boundary pattern by τ_j. We need to check that the inductive hypotheses are satisfied for V_{j−1}.

Since the involution τ_j reverses co-orientation, we can see that the combinatorial immersion
\hat V_j → V_j → X/G extends to an immersion V_{j−1} → X/G. Moreover, since τ_j is an
involution of the boundary pattern, we see that V_{j−1} has locally convex boundary since
∂_j\hat V_j ⊂ \hat V_j has a collar neighborhood, and therefore the map to X/G is locally convex, so
condition (1) is satisfied. The boundary pattern \( \partial_i(\partial_j V_j) \) is preserved by the involution \( \tau_j \), since the coloring of the boundary pattern is locally determined by the equivalence classes of walls being glued together for colors \( i < j \). We define the boundary pattern of \( V_{j-1} \) by \( \partial_i V_{j-1} = \partial_i V_j / \tau_j \). The interior facets will all have color \( > j-1 \), and the boundary facets will have color \( \leq j-1 \). So condition (3) is satisfied. Since we have glued \( V_{j-1} \) out of copies of colored polyhedra in a way consistent with the gluing equations, and taking regular covers preserves the gluing equations, conditions (2) and (4) are satisfied.

So all of the inductive hypotheses are satisfied.

The complex \( V_0 \) has trivial boundary pattern, and a locally convex map \( V_0 \to \hat{X}/G \). Therefore, this map is a finite-sheeted covering space. Moreover, by construction, \( V_0 \) has a quasi-convex hierarchy, so \( \pi_1(V_0) \in QVH \) (in fact, the hierarchy is malnormal, so \( \pi_1(V_0) \in MQH \)). By [45, Theorem 13.3 or Theorem 11.2] (see also Theorem A.42), \( V_0 \) has a finite-sheeted special cover, and thus \( X/G \) does. This finishes the proof of Theorem 1.1.

\[ \square \]

9. Conclusion

Recall that a Haken 3-manifold is a compact irreducible orientable 3-manifold containing an embedded \( \pi_1 \)-injective surface.

**Theorem 9.1** (Virtual Haken conjecture [44]). Let \( M \) be a closed aspherical 3-manifold. Then there is a finite-sheeted cover \( \tilde{M} \to M \) such that \( \tilde{M} \) is Haken.

**Theorem 9.2** (Virtual fibering conjecture, Question 18 [43]). Let \( M \) be a closed hyperbolic 3-manifold. Then there is a finite-sheeted cover \( \tilde{M} \to M \) such that \( \tilde{M} \) fibers over the circle. Moreover, \( \pi_1(M) \) is LERF and large.

**Proof of Theorems 9.1 and 9.2.** From the geometrization theorem [39, 38, 35], it is well-known that the virtual Haken conjecture reduces to the case that \( M \) is a closed hyperbolic 3-manifold. For a closed hyperbolic 3-manifold, we have the following result of Bergeron-Wise based on work of Kahn-Markovic [24] (and making use of seminal results of Sageev on cubulating groups containing codimension-one subgroups [40]).

**Theorem 9.3.** [5, Theorem 5.3] Let \( M \) be a closed hyperbolic 3-manifold. Then \( \pi_1 M \) acts freely and cocompactly on a \( CAT(0) \) cube complex.

Now, by Theorem 1.1, \( \pi_1(M) \) is virtually special. This implies that \( \pi_1 M \) is LERF and large following from the virtual specialness by Cor. 1.2. Therefore \( M \) is virtually Haken, and in fact \( M \) is also virtually fibered by [45, Corollary 14.3]. \[ \square \]

We also have the following corollary, resolving a question of Thurston.

**Corollary 9.4** (Question 15 [43]). Kleinian groups are LERF.

**Proof.** This follows combining 9.2 which proves that compact hyperbolic 3-manifold groups are LERF, together with the implication that therefore all finite-covolume Kleinian groups are LERF by [31, Proposition 5.3]. It is well known that any Kleinian group embeds in a finite covolume Kleinian group [36]. \[ \square \]
Appendix A. Filling virtually special subgroups
by Ian Agol, Daniel Groves, and Jason Manning

This section will be devoted to proving the following theorem, which may be regarded as a generalization of the main theorem of \cite{1}, with the extra ingredient of the malnormal virtually special quotient \cite[Theorem 12.3]{45}.

**Theorem A.1.** Let $G$ be a hyperbolic group, let $H \leq G$ be a quasi-convex virtually special subgroup. For any $g \in G - H$, there is a hyperbolic group $\mathcal{G}$ and a homomorphism $\phi : G \to \mathcal{G}$ such that $\phi(g) \notin \phi(H)$ and $\phi(H)$ is finite.

**Remark A.2.** The conclusion of this theorem may be regarded as a weak version of subgroup separability. Under the hypotheses of the theorem, $H$ is subgroup separable in $G$ if one may also assume that the quotient group $G$ is finite.

**Remark A.3.** It ought to be possible to prove this result using the techniques to prove \cite[Theorem 12.1]{45}. However, we have decided to provide an alternative argument which gives a geometric perspective on the notion of height, and uses hyperbolic Dehn filling arguments from the literature instead of the small-cancellation theory developed in \cite{45}.

**Notation A.4.** In this appendix, we will sometimes use the notation $A \leq B$ to indicate that $A$ is a finite-index subgroup of $B$.

**Definition A.5.** We define the malnormal core of $H$ and peripheral system induced by $H$ on $G$. Let $n$ be the height of $H$ in $G$. By \cite[Corollary 3.5]{1}, there are finitely many $H$-conjugacy classes of minimal infinite subgroups of the form $H \cap H^{g_1} \cap H^{g_2} \cap \cdots \cap H^{g_j}$, where $1 \leq j \leq n$ and $\{g_1, g_2, \ldots, g_n\}$ are essentially distinct, in the sense that $g_iH = g_jH$ if and only if $i = j$.

Choose one $H$-conjugacy class of each such subgroup in $H$, and replace it with its commensurator in $H$ to obtain a collection of quasi-convex subgroups $D_0$ of $H$. Eliminating redundant entries which are $H$-conjugate, we obtain a collection $D$, which we will call the *malnormal core* of $H$ in $G$. The collection $D$ gives rise to a peripheral system of subgroups $\mathcal{P}$ in $G$ in two steps:

1. Change $D$ to $D'$ by replacing each $D \in D$ with $D' < G$ its commensurator in $G$.
2. Eliminate redundant entries of $D'$ to obtain $\mathcal{P} \subset D'$ which contains no two elements which are conjugate in $G$.

Call $\mathcal{P}$ the *peripheral structure on $G$ induced by $H$*. This peripheral structure is only well-defined up to replacement of some elements of $\mathcal{P}$ by conjugates. On the other hand, replacing $H$ by a commensurable subgroup of $G$ does not affect the induced peripheral structure. We consider two peripheral structures on a group to be the same if the same group elements are parabolic (i.e. conjugate into $\bigcup \mathcal{P}$) in the two structures.

**Remark A.6.** Since $H$ is quasiconvex, so are the intersections $H \cap H^{g_1} \cap \cdots \cap H^{g_j}$ \cite[Lemma 2.7]{15}. Because infinite quasiconvex subgroups of hyperbolic groups are finite index in their commensurators \cite[Lemma 2.9]{15}, it follows that each of the elements of $D$ or $\mathcal{P}$ contains some such $H \cap H^{g_1} \cap \cdots \cap H^{g_j}$ as a finite index subgroup.

**Example A.7.** If we have the minimal infinite subgroup $U = H \cap H^{g_1} \cap H^{g_2}$, then $U$ will appear as a subgroup of $H$ in three ways, up to $H$-conjugacy: $U, U^{g_1^{-1}} \cap H \cap \cdots \cap H^{g_2^{-1}}, U^{g_1^{-1}} \cap H \cap \cdots \cap H^{g_2^{-1}}$. 

A.36 \impliedby that there is a finite subset \(A\) of \(G\) and \(A\)'s \(g_1^{-1}g_2^{-1} \cap H\). Thus, there will be \(\leq 3\) \(H\)-commensurators of conjugates of \(U\) appearing in \(D\). There could be strictly fewer: \(U\) and \(U^{g_1^{-1}}\) may be commensurable in \(H\) if \(g_1 \in \text{Comm}_G(U)\). Similarly, we get \(\leq 3\) conjugates of the \(G\)-commensurator of \(U\) in \(G\) in \(D'\), but these are all \(G\)-conjugate, so only one element coming from \(U\) remains in \(P\).

We state also the malnormal virtually special quotient theorem [45, Theorem 12.3] for reference.

**Theorem A.8.** Let \(G\) be a virtually special hyperbolic group. Let \(\{H_1, \ldots, H_m\}\) be an almost malnormal collection of quasiconvex subgroups. Then there exists finite-index subgroups \(H_i \trianglelefteq H_i, i = 1, \ldots, m\) such that for any further finite index subgroups \(H_i' \trianglelefteq H_i\), the quotient \(G/\langle H_1, \ldots, H_m' \rangle\) is virtually special.

**Proof of Theorem A.1.** Let \(H \leq G\) be quasiconvex and virtually special, and let \(g \in G\setminus H\). Let \(h\) be the height of \(H\) in \(G\). We will induct on the height, noting that the height zero \((H\) finite) case holds trivially.

Let \(\mathcal{P} = \{P_1, \ldots, P_m\}\) be the peripheral system associated to \(H \leq G\), and \(\mathcal{D}\) the peripheral system of \(H\) from Definition A.5. By Theorem A.8, there are finite-index subgroups \(\hat{D}_j \trianglelefteq D_j\) for each \(D_j \in \mathcal{D}\) such that for any further finite-index subgroups \(D_j' \trianglelefteq \hat{D}_j\), the quotient \(H(D_j', \ldots, D_n') = H/\langle \bigcup_j D_j' \rangle\) is virtually special.

For each \(D_j \in \mathcal{D}\), there is some unique \(P_{ij}\) and some \(g_j\) so that

\[
g_j^{-1}D_jg_j \trianglelefteq P_{ij}.
\]

The element \(g_j\) is not unique, but if \(g'_j\) is another such element, then \(g_j^{-1}g'_j \in P_{ij}\). In particular, different \(G\)-conjugates of \(D_j\) in \(P_{ij}\) are actually \(P_{ij}\)-conjugates, so there are only finitely many of them.

Let \(P_i \in \mathcal{P}\), and let

\[
S_i = \{\hat{D}_j^g \mid D_j \in \mathcal{D}, g \in G, D_j^g \trianglelefteq P_i\}.
\]

By the way \(\mathcal{D}\) and \(\mathcal{P}\) are defined, \(S_i\) is never empty. By the argument in the last paragraph, \(S_i\) is a finite collection, so \(I_i = \bigcap S_i \trianglelefteq P_i\).

Theorems A.36 and A.16 imply that there is a finite subset \(B \subset \bigcup \mathcal{P}\) so that whenever \(\phi: G \to G(N_1, \ldots, N_m)\) is an \(H\)-filling (see Definition A.11) satisfying \((\bigcup N_i) \cap B = \emptyset\) and \(N_i \trianglelefteq P_i\), then:

1. The image \(\phi(H)\) is quasiconvex of height \(< h\) in the hyperbolic group \(G(N_1, \ldots, N_m)\).
2. \(\phi(H) \cong H(K_1, \ldots, K_n)\), where \(H(K_1, \ldots, K_n)\) is the induced filling of \(H\), described in Remark A.13. (Theorem A.36.(3))
3. \(\phi(g) \notin \phi(H)\). (Theorem A.36.(4))

Since \(H\) is residually finite, and each \(P_i\) is a finite extension of a subgroup of \(H\), each \(P_i\) is residually finite. Hence there are normal subgroups \(N_i \trianglelefteq P_i\) so that \((\bigcup N_i) \cap B = \emptyset\). These normal subgroups need not define an \(H\)-filling, but we can instead consider the subgroups

\[
N_i' = N_i \cap I_i.
\]

Then \(\phi: G \to G(N_1', \ldots, N_m')\) is an \(H\)-filling inducing a filling \(H \to H(K_1, \ldots, K_n)\) satisfying the hypotheses of Theorem A.8. In particular, the image \(\tilde{H}\) of \(H\) in \(\tilde{G} = G(N_1', \ldots, N_m')\)
is virtually special. By Theorem A.16, \( \bar{G} \) is hyperbolic and \( \bar{H} \leq \bar{G} \) is quasiconvex, of height \( < h \). Moreover, Theorem A.36 implies \( \phi(g) \not\in \phi(H) \).

By induction, there is a quotient \( \bar{\phi} : \bar{G} \to \bar{G} \) so that \( \bar{\phi}(\phi(g)) \not\in \bar{\phi}(\phi(H)) \) and \( \bar{\phi}(\phi(H)) \) is finite. \( \square \)

A.1. Definitions.

**Definition A.9.** (See [1, Section 3]) Let \( G \) be a hyperbolic group and \( H \) a quasi-convex subgroup, and let \( \mathcal{P} \) and \( \mathcal{D} \) be the induced peripheral structures on \( G \) and \( H \) described above. Let \( X \) be the cusped space of \((G, \mathcal{P})\) and \( Y \) the cusped space of \((H, \mathcal{D})\) (with respect to choices of generating sets). The inclusion \( \phi : H \to G \) sends peripheral subgroups in \( \mathcal{D} \) into (conjugates of) peripheral subgroups in \( \mathcal{P} \), and so induces a proper \( H \)-equivariant Lipschitz map \( \bar{\phi} : Y \to X \). We say that \((H, \mathcal{D})\) is \( C \)-relatively quasiconvex in \((G, \mathcal{P})\) if \( \bar{\phi} \) is \( C \)-Lipschitz and has \( C \)-quasiconvex image in \( X \).

In [31, Appendix A] it is explained that the above definition agrees with other notions of relative quasiconvexity, such as those in [23].

The following is proved in [1] under the assumption that \( G \) is torsion-free. It was extended to the general setting in [32].

**Proposition A.10.** [1, Proposition 3.12],[32, Corollary 1.9] The pairs \((H, \mathcal{D})\) and \((G, \mathcal{P})\) are both relatively hyperbolic and with these peripheral structures \((H, \mathcal{D})\) is a relatively quasiconvex subgroup of \((G, \mathcal{P})\).

**Definition A.11.** Let \((H, \mathcal{D})\) be a relatively quasiconvex subgroup of \((G, \mathcal{P})\), where \( \mathcal{P} = \{P_1, \ldots, P_m\} \). Let \( \{N_i \lhd P_i\} \) be given. The quotient
\[
G(N_1, \ldots, N_m) := G/ \ll N_1 \cup \cdots \cup N_m \gg
\]
is a filling of \((G, \mathcal{P})\). It is an \( H \)-filling if \( N_i^a \subset P_i^a \cap H \) whenever \( H \cap P_i^a \) is infinite.

**Remark A.12.** The current definition of \( H \)-filling agrees with the one in [1] only in case \( G \) is torsion-free. As explained in [31, Appendix B], Definition A.11 is the correct extension in case there is torsion.

**Remark A.13.** As explained in [1, Definition 3.2], an \( H \)-filling \( G(N_1, \ldots, N_m) \) induces a filling \( H(K_1, \ldots, K_n) \) of \( H \): For each \( D_i \in \mathcal{D} \), there is a \( c_i \in G \) and \( P_i \in \mathcal{P} \) so that \( D_i \subset c_i P_i c_i^{-1} \). Then \( K_i = c_i N_j c_i^{-1} \cap D_i \). The inclusion \( H \hookrightarrow G \) induces a homomorphism \( H(K_1, \ldots, K_n) \to G(N_1, \ldots, N_m) \).

**Definition A.14.** Let \((G, \mathcal{P})\) be a relatively hyperbolic group. We say that a statement \( S \) about fillings \( G(N_1, \ldots, N_m) \) holds for all sufficiently long fillings if there is a finite set \( B \subset \bigcup \mathcal{P} \) so that whenever \( G(N_1, \ldots, N_m) \) is a filling so that \( \bigcup_{i=1}^n N_i \) does not contain \( B \), then \( S \) holds.

Similarly, if \((H, \mathcal{D})\) is a relatively quasiconvex subgroup of \((G, \mathcal{P})\), a statement \( S \) holds for all sufficiently long \( H \)-fillings if there is a finite set \( B \subset \bigcup \mathcal{P} \) so the statement \( S \) holds for all \( H \)-fillings \( G(N_1, \ldots, N_m) \) so that \( \bigcup_{i=1}^n N_i \) does not contain \( B \).

Obviously if \( S \) holds for all sufficiently long fillings, then \( S \) holds for all sufficiently long \( H \)-fillings. The fundamental theorem of relatively hyperbolic Dehn filling can be stated:
Theorem A.15. [37, 13] (cf. [17] in the torsion-free case) Let $G$ be a group and $\mathcal{P} = \{P_1, \ldots, P_m\}$ a collection of subgroups so that $(G, \mathcal{P})$ is relatively hyperbolic, and let $F \subset G$ be finite. Then for all sufficiently long fillings $\phi : G \to \tilde{G} := G(N_1, \ldots, N_m)$,

1. $\ker(\phi|_{P_i}) = N_i$ for each $P_i \in \mathcal{P};$
2. $(\tilde{G}, \{\phi(P_1), \ldots, \phi(P_m)\})$ is relatively hyperbolic; and
3. $\phi|_F$ is injective.

Our chief new Dehn filling result in this appendix is the following:

Theorem A.16. Let $G$ be hyperbolic, and let $H$ be height $k \geq 1$ and quasi-convex in $G$. Suppose that $\mathcal{D}$ and $\mathcal{P} = \{P_1, \ldots, P_m\}$ are as in Definition A.5. Then for all sufficiently long $H$–fillings

$$\phi : G \to \tilde{G} := G(N_1, \ldots, N_m)$$

with $N_i \triangleleft P_i$ finite index for all $i$, the subgroup $\phi(H)$ is quasi-convex of height strictly less than $k$ in the hyperbolic group $G$.

Remark A.17. We proved Theorem A.16 in [1] under the assumption that $G$ was torsion-free. Much of the proof from [1] still works without that assumption, but our argument that height is reduced in the quotient depended on the machinery of Part 2 of [17], in which torsion-freeness is assumed. Our main innovation in this appendix is a completely different proof that height decreases under Dehn filling.

A.2. Geometric finiteness. Geometric finiteness is a dynamical condition. We recall the relevant definitions.

Definition A.18. Let $M$ be a compact metrizable space with at least 3 points, and let $\Theta(M)$ be the set of unordered distinct triples of points in $M$. Any action of $G$ on $M$ induces an action on $\Theta(M)$. The action of $G$ on $M$ is said to be a convergence group action if the induced action on $\Theta(M)$ is properly discontinuous.

Definition A.19. Suppose $G \curvearrowright M$ is a convergence group action. A point $p \in M$ is a conical limit point if there is a sequence $\{g_i\}_{i \in \mathbb{N}}$ and a pair of points $a, b$ so that $g_ip \to b$ but for every $x \in M \setminus \{p\}$, we have $g_i x \to a$.

A point $p$ is parabolic if $\text{Stab}_G(p)$ is infinite but there is no infinite order $g \in G$ and $q \neq p \in M$ so that $\text{Fix}(g) = \{p, q\}$.

A parabolic point $p$ is called bounded parabolic if $\text{Stab}_G(p)$ acts cocompactly on $M \setminus \{p\}$.

Definition A.20. The action $G \curvearrowright M$ is geometrically finite if every point in $M$ is a conical limit point or a bounded parabolic point. Say that $(G, \mathcal{P})$ acts geometrically finitely on $M$ if all of the following hold:

1. $G \curvearrowright M$ is a geometrically finite convergence action.
2. Each $P \in \mathcal{P}$ is equal to $\text{Stab}_G(p)$ for some bounded parabolic point $p$.
3. For any bounded parabolic point $p$, the stabilizer $\text{Stab}_G(p)$ is conjugate to exactly one element of $\mathcal{P}$.

Let $X$ be a $\delta$–hyperbolic $G$–space, so that $(G, \mathcal{P})$ acts geometrically finitely on $\partial X$. Then we say that $(G, \mathcal{P})$ acts geometrically finitely on $X$.

It is useful when talking about Dehn filling to allow parabolic subgroups to be finite. We will use the following definitions:
Definition A.21. Let $G \curvearrowright M$ be a convergence action, and say that $p \in M$ is a finite parabolic point if $p$ is isolated and has finite stabilizer.

For $\mathcal{P}$ a finite collection of subgroups of $G$, write $\mathcal{P}_\infty$ for the subcollection of infinite subgroups, and $\mathcal{P}_f$ for the subcollection of finite subgroups. Suppose $G$ acts on the compact metrizable space $M$. Let $M'$ be obtained from $M$ by removing all isolated points. Say that $(G, \mathcal{P})$ acts weakly geometrically finitely on $M$ (or that the action is WGF) if all of the following occur:

1. $(G, \mathcal{P}_\infty)$ acts geometrically finitely on $M'$.
2. Each $P \in \mathcal{P}_f$ is equal to $\text{Stab}_G(p)$ for some $p \in M \setminus M'$.
3. Every $p \in M \setminus M'$ is a finite parabolic point, with stabilizer conjugate to exactly one element of $\mathcal{P}_f$.

Finally, if $X$ is a $\delta$–hyperbolic $G$–space, then we say that the action of $(G, \mathcal{P})$ on $X$ is WGF whenever the action of $(G, \mathcal{P})$ on $\partial X$ is WGF.

Proposition A.22. Let $(G, \mathcal{P})$ be relatively hyperbolic. Then the action of $(G, \mathcal{P})$ on its cusped space is WGF.

Conversely, if $(G, \mathcal{P})$ has a WGF action on a space $M$, then $(G, \mathcal{P})$ is relatively hyperbolic.

Proof. For $\mathcal{P} = \mathcal{P}_\infty$, a proof of the equivalence can be found in [23].

The pair $(G, \mathcal{P})$ is relatively hyperbolic if and only if $(G, \mathcal{P}_\infty)$ is relatively hyperbolic. Indeed, for any generating set $S$ of $G$, the cusped space $X_\infty = X(G, \mathcal{P}_\infty, S)$ quasi-isometrically embeds into $X = X(G, \mathcal{P}, S)$. The complement $X \setminus X_\infty$ is composed of combinatorial horoballs based on finite graphs. Thus $X$ is quasi-isometric to $X_\infty$ with $\#(\mathcal{P}_f)$ rays attached to vertex of the Cayley graph of $G$.

Suppose that $(G, \mathcal{P})$ is relatively hyperbolic, so that $X$ is Gromov hyperbolic. Then $X_\infty$ is also Gromov hyperbolic, and $\partial X'$ can be canonically identified with $\partial X_\infty$. Thus $G$ acts geometrically finitely on $\partial X'$. Moreover, the isolated points of $\partial X$ are in one to one correspondence with the left cosets of elements of $\mathcal{P}_f$; the point corresponding to $tP$ has (finite) stabilizer equal to $tPt^{-1}$. Thus $(G, \mathcal{P})$ acts weakly geometrically finitely on $X$.

Conversely, if $(G, \mathcal{P})$ has a WGF action on $M$, then $(G, \mathcal{P}_\infty)$ has a geometrically finite action on $M'$, so $(G, \mathcal{P}_\infty)$ is relatively hyperbolic. Since $\mathcal{P} \setminus \mathcal{P}_\infty$ is composed of finite subgroups of $G$, the pair $(G, \mathcal{P})$ is also relatively hyperbolic.

Remark A.23. Given that $(G, \mathcal{P})$ is relatively hyperbolic if and only if $(G, \mathcal{P}_\infty)$ is relatively hyperbolic, it is often convenient to simply ignore the possibility of finite parabolics, as for example in [23]. In the present setting it is important to keep track of them, as otherwise we would not get uniform control of the geometry of cusped spaces of quotients, as in Theorem A.36 below.

Suppose that $X$ and $Y$ are $\delta$–hyperbolic $G$–spaces. A $G$–equivariant quasi-isometry from $X$ to $Y$ induces a $G$–equivariant homeomorphism from $\partial X$ to $\partial Y$. Since the property of being a (weakly) geometrically finite action on a $\delta$–hyperbolic space is defined in terms of the boundary, we have the following result.

Lemma A.24. Suppose that $(G, \mathcal{P})$ admits a WGF action on a $\delta$–hyperbolic space $X$ (as in Definition A.20) and that $f : X \to Y$ is a $G$–equivariant quasi-isometry to another $\delta$–hyperbolic $G$–space. Then the action of $G$ on $Y$ is WGF.
Remark A.25. In the presence of 2–torsion, the action of \( G \) on the cusped space \( X(G, \mathcal{P}, S) \) may not be free, though it is always free on the vertex set. In what follows, it is convenient to replace the graph \( X(G, \mathcal{P}, S) \) as defined in [17] with a graph having the same vertex set, but on which \( G \) acts freely. Since \( G \) acts freely on the vertex set already, we can modify \( X(G, \mathcal{P}, S) \) to a graph with a free \( G \)–action by replacing each edge by two edges, corresponding to the two choices of orienting the edge. This does not change the coarse geometry of \( G \) or any of the statements we apply from [17, 1, 31, 23]. From now on, when we refer to the cusped space, we will assume it has been modified as just explained to make the action free.

A.3. Height from multiplicity.

**Definition A.26.** \((H, \mathcal{D}) < (G, \mathcal{P})\) is fully quasiconvex if it is relatively quasiconvex and whenever \( gDg^{-1} \cap \mathcal{P} \) is infinite, for \( D \in \mathcal{D} \), \( P \in \mathcal{P} \), then \([P : gDg^{-1}] < \infty\).

In this section, \((G, \mathcal{P})\) is relatively hyperbolic, and \((H, \mathcal{D})\) is a fully quasiconvex subgroup. We allow the possibility that \( \mathcal{P} \) and \( \mathcal{D} \) are empty.

If \( \mathcal{P} \) (and therefore \( \mathcal{D} \)) is empty, we take \( \Gamma \) to be any graph on which \( G \) acts freely and cocompactly, and choose \( \ast \) to be some arbitrary vertex. Otherwise, we take \( \Gamma \) to be the 1–skeleton of a cusped space \( X(G, \mathcal{P}, S) \), modified to have a free \( G \)–action as in Remark A.25. \(^1\) In this case \( \Gamma \) contains a Cayley graph for \( G \), and we take \( \ast = 1 \in G \subset \Gamma \).

**Definition A.27.** Let \( R \geq 0 \). An \( R \)-hull for \( H \) acting on \( \Gamma \) is a connected \( H \)-invariant sub-graph \( \tilde{Z} \subset \Gamma \) so that all of the following hold.

1. \( \ast \in \tilde{Z} \).
2. If \( \gamma \) is a geodesic in \( \Gamma \) with endpoints in the limit set of \( H \), then the \( R \)–neighborhood of \( \gamma \) is contained in \( \tilde{Z} \).
3. If \( \mathcal{P} \) is nonempty and \( B \) is a horoball of \( \Gamma \) whose stabilizer in \( H \) is infinite, then \( B' \subset \tilde{Z} \) where \( B' \) is some horoball nested in \( B \).
4. The action of \((H, \mathcal{D})\) on \( \tilde{Z} \) is WGF.

Let \( \tilde{Z} \) be an \( R \)–hull for \( H \) acting on \( \Gamma \), let \( Z = \tilde{Z}/H \) be the quotient of \( \tilde{Z} \) by the \( H \)–action, and let \( Y = \Gamma / G \) be the quotient of \( \Gamma \) by the \( G \)–action. If we let \( \ast_H \in \tilde{Z} \) and \( \ast \in Y \) be the images of \( \ast \), we obtain canonical surjections \( s: \pi_1(Z, \ast_H) \to H \) and \( s: \pi_1(Y, \ast) \to G \). Moreover the canonical map

\[ i : Z \to Y \]

which is the composition of the inclusion \( Z \hookrightarrow \Gamma / H \) with the quotient map \( \Gamma / H \to Y = \Gamma / G \) agrees with the inclusion of \( H \) into \( G \).

**Definition A.28.** Let \( n > 0 \), and define the following subset of \( Z^n \):

1. \( S_n = \{(z_1, \ldots, z_n) \mid i(z_1) = \cdots = i(z_n)\} \setminus \Delta \)

\(^1\)Below, when applying Theorem A.36 to a quotient of \( \Gamma \) by \( G \), we will consider a graph which is the cusped space with some extra loops attached (in an equivariant way) to some vertices. It is straightforward to check that our arguments work as written for this slightly different space. In fact, with only a little extra work, one can take \( \Gamma \) to be any graph with a free WGF \( G \)-action, but we decided to stick with the more restrictive setting in the interests of brevity.
where $\Delta = \{(z_1, \ldots, z_n) \mid z_i = z_j \text{ for some } i \neq j\}$ is the “fat diagonal” of $Z^n$. Let $s : \pi_1(Z, \ast_H) \to H$ be the canonical surjection. Let $\pi_1, \ldots, \pi_n$ be the $n$ projections of $S_n$ to $Z$.

(In Stallings’ language [42], $S_n$ is that part of the pullback of $n$ copies of $i : Y \to Z$ which lies outside $\Delta$.)

Let $C$ be a component of $S_n$, with a choice of basepoint $p = (p_1, \ldots, p_n)$. For $i \in \{1, \ldots, n\}$ define maps $\tau_{i,C} : \pi_1(C) \to H$ as follows:

Choose a maximal tree $T$ in $Z$. For each vertex $v$ of $Z$, the tree gives a canonical path $\sigma_v$ from $\ast_H$ to $v$, allowing the fundamental groups of $Z$ at different basepoints to be identified. To simplify notation define $\sigma_i = \sigma_{p_i}$. Now, the map $\omega_i : C \to Z$ induces a well-defined map $(\omega_i)_* : \pi_1(C, p) \to \pi_1(Z, \ast_H)$, taking a loop $\gamma$ based at $p \in C$ to the loop $\sigma_i \gamma \sigma_i$. We define $\tau_{C,i} = s \circ (\omega_i)_* : \pi_1(C, p) \to H$. Since $H$ acts on $\hat{Z}$ by covering translations, the map $s$ can be seen by lifting paths starting and finishing at the basepoint in the usual way. Once we’ve used the path in the maximal tree to make based loops in $C$ map to paths in $Z$ starting and finishing at the basepoint $\ast_H$, the same is true of the maps $\tau_{C,i}$.

**Definition A.29.** The multiplicity of $Z \to Y$ is the largest $n$ so that $S_n$ contains a component $C$ so that for all $i \in 1, \ldots, n$ the group

$$\tau_{C,i}(\pi_1(C))$$

is an infinite subgroup of $H$.

**Lemma A.30.** For a fixed component $C$ of $S_n$, the groups

$$A_i = \tau_{C,i}(\pi_1(C, p)) < H$$

are conjugate in $G$. Specifically, if $\sigma_i$ are defined as above, and $g_{i,j}$ is represented by the loop $i \circ \sigma_i \cdot i \circ \sigma_j$, then $g_{i,j} A_j g_{i,j}^{-1} = A_i$.

**Proof.** As in the above discussion, the basepoint of $C$ is $p = (p_1, \ldots, p_n)$, and for each $i$ there is a canonical path $\sigma_i$ in $T \subset \hat{Z}$ connecting the basepoint $\ast_H$ of $Z$ to $p_i$. We also recall the map $i : Z \to Y$ takes $\ast_H$ to $\ast$ and induces the inclusion $H < G$ in the sense that the diagram

$$\begin{align*}
\pi_1(Z, \ast_H) & \xrightarrow{i} \pi_1(Y, \ast) \\
\downarrow{s} & \downarrow{s} \\
H & \to G
\end{align*}$$

commutes, where the vertical arrows are the canonical surjections.

Let $q = i(p_1) = \cdots = i(p_n)$. The paths $i \circ \sigma_i$ all begin at $\ast$ and end at $q$, so any concatenation of two of them gives a loop in $Y$ representing an element $g_{i,j}$ of $G$ conjugating one of the images of $\pi_1(C, p)$ to another. Precisely, for $i, j \in \{1, \ldots, n\}$ we get an element $g_{i,j}$ represented by $i \circ \sigma_i \cdot i \circ \sigma_j$ so that

$$g_{i,j} \tau_{C,j}(\alpha) g_{i,j}^{-1} = \tau_{C,i}(\alpha), \forall \alpha \in \pi_1(C, p).$$

$\square$

We aim in this section for the following:
Theorem A.31. Let $R$ be bigger than the quasi-geodesic stability constant $D = D(\delta)$ specified in the proof below. With the above notation, the height of $H$ in $G$ is equal to the multiplicity of $Z \to Y$.

Remark A.32. It is instructive to contemplate the proof of this theorem when $G$ is a Kleinian group, and $H$ a geometrically finite subgroup. Then it is not hard to verify that the multiplicity of a convex core of $H$ is equal to the height of $H$. In fact, the arguments in this section are motivated by carrying this geometric argument over to the broader category of hyperbolic groups.

Before doing the proof, we state and prove a corollary.

Corollary A.33. [15] The height of a quasiconvex subgroup of a hyperbolic group is finite.

Proof. Suppose $H$ is quasiconvex in $G$. Let $\Gamma$ be a Cayley graph for $G$, so that $H \subset \Gamma$ is $\lambda$-quasiconvex. It is easy to see that $\tilde{Z} = N_{\lambda+5\delta+R}(H)$ is an $R$-hull for $H$. Since $G$ (resp. $H$) acts cocompactly on $\Gamma$ (resp. $\tilde{Z}$), the complexes $Z$ and $Y$ are both finite. Thus $S_n$ is empty for large $n$. $\square$

Proof of Theorem A.31. We first bound multiplicity from below by height, and then conversely.

(multiplicity $\geq$ height): Suppose that $H$ has height $\geq n$. There are then $(H, g_2H, \ldots, g_nH)$ all distinct so that $J = H \cap H^{g_2} \cap \cdots \cap H^{g_n}$ is infinite. Since $(G, P)$ is relatively hyperbolic, every infinite subgroup of $G$ either contains a hyperbolic element or is conjugate into some $P \in \mathcal{P}$. This follows immediately from the classification of isometries of $\delta$-hyperbolic spaces (see [16, Section 8.2, p. 211]) and from the definition of WGF action. The proof therefore breaks up naturally into these two cases.

Case A.33.1. The intersection $J$ contains a hyperbolic element $a$.

By replacing $a$ by a power we may suppose that $a$ has a $(K, C)$-quasi-geodesic axis $\gamma_a$, where $K$ and $C$ depend only on $\delta$. Quasi-geodesic stability implies that $\gamma_a$ lies Hausdorff distance at most $D$ from a geodesic, where $D$ depends only on $\delta$. So as long as $R > D$, the geodesic $\gamma_a$ lies in $\tilde{Z} \cap g_2\tilde{Z} \cap \cdots \cap g_n\tilde{Z}$. Let $\pi_Z$ be the natural projection from $\tilde{Z}$ to $Z$. For $t \in \mathbb{R}$, define $\gamma_a : \mathbb{R} \to \mathbb{Z}^n$ as follows:

$$\gamma_a(t) = (\pi_Z(\gamma_a(t)), \pi_Z(g_2^{-1}\gamma_a(t)), \ldots, \pi_Z(g_n^{-1}\gamma_a(t)))$$

Since $G$ acts freely and the $g_i$ are essentially distinct, $\gamma_a$ misses the diagonal. Since its coordinates differ only by elements of $g$, $\gamma_a$ has image in $S_n$. Moreover projection of $\gamma_a$ to any component gives a loop of infinite order in $H$. Thus we’ve shown that a component of $S_n$ has an element with infinite order projection to $G$, and therefore the multiplicity of $H$ is $\geq n$.

Case A.33.2. The intersection $J$ is conjugate into $P \in \mathcal{P}$.

In this case $J$ preserves some horoball $B$ of $\Gamma$. By point (3) in the definition of $R$-hull, there is a horoball $B'$ nested inside $B$ so that $B' \subset \tilde{Z}$. By possibly replacing $B'$ with a horoball nested further inside, we have $B' \subset \tilde{Z} \cap g_2\tilde{Z} \cap \cdots \cap g_n\tilde{Z}$. 
It follows that
\[ A = \{ (\pi_Z(b), \pi_Z(g_2^{-1}(b)), \ldots, \pi_Z(g_n^{-1}(b))) \mid b \in B' \} \]
lies in some component \( C \) of \( S_n \). Moreover, each \( \tau_{C,i}(\pi_1(A)) < \tau_{C,i}(\pi_1(C)) \) is conjugate to \( J \), hence infinite.

**(height \( \geq \) multiplicity):** Suppose the multiplicity of \( Z \to Y \) is \( n \). Let \( C \subset S_n \) be a component with infinite fundamental group, and let \( p = (p_1, \ldots, p_n) \in C \). We define the paths \( \sigma_i \) from \(*_H\) to \( p_i \) as in the discussion before Definition A.29. Recall the homomorphisms
\[ \tau_{C,i} : \pi_1(C,p) \to H < G \]
are defined by \( \tau_{C,i}([\gamma]) = [i \circ (\sigma_i \cdot \gamma_i \cdot \bar{\sigma}_i)] \), for any loop \( \gamma = (\gamma_1, \ldots, \gamma_n) \) based at \( p \) in \( C \). According to Lemma A.30, if we let \( A_i = \tau_{C,i}(\pi_1(C,p)) \), and \( g_{i,j} = [i \circ \sigma_i \cdot i \circ \bar{\sigma}_j] \), then
\[ A_{g_{i,j}} = A_i. \]

In particular, writing \( g_i = g_{1,i} \), we have
\[ H \cap H^{g_2} \cdots \cap H^{g_n} \supseteq A_1 \]
is infinite. To establish the height of \( H \) is at least \( n \), we need to show that \( (1, g_2, \ldots, g_n) \) are essentially distinct.

Let \( \tilde{T} \) be the lift of \( T \) to \( \Gamma \) which includes the point \( \tilde{z} \), and let \( \gamma = (\gamma_1, \ldots, \gamma_i) \) be a path in \( C \) based at \( p \). For each \( i \), the path \( \sigma_i \) has a unique lift to \( \tilde{T} \). Let \( \tilde{\gamma_i} \) be the unique lift of \( \gamma_i \) starting at the terminus of \( \tilde{\sigma}_i \). Then \( g_i(\gamma_i) = \gamma_1 \).

Since \( p \in C \) lies outside the fat diagonal of \( Z^n \), the paths \( \gamma_1, \ldots, \gamma_n \) are all distinct. In particular, the lifts \( \tilde{\gamma}_1, \ldots, \tilde{\gamma}_n \) are also distinct.

Suppose that \( (1, g_2, \ldots, g_n) \) are not essentially distinct. Then we would have (writing \( g_1 = 1 \)) \( g_j = g_ih \) for some \( 1 \leq i < j \leq n \) and some \( h \in H \). But then \( \tilde{\gamma}_j = h^{-1}\tilde{\gamma}_i \). Projecting back to \( Z \) we have \( \gamma_j = \gamma_i \), contradicting the fact that \( \gamma \) misses the fat diagonal of \( Z^n \). \( \square \)

A.4. **Height decreases.** Again, we have the setup: \((H, \mathcal{D})\) is fully quasiconvex in \((G, \mathcal{P})\). We now assume that \( \mathcal{D} \) and \( \mathcal{P} \) are nonempty, and that \( \Gamma = X(G, \mathcal{P}, S) \) for some finite generating set \( S \) for \( G \). The graph \( \Gamma \) is acted on weakly geometrically finitely by \((G, \mathcal{P})\). Moreover given any finite generating set \( T \) for \( H \), there is a \( \lambda > 0 \) and an \( H\)–equivariant, proper, \( \lambda\)–Lipschitz map (defined in [1, Section 3])
\[ i : X(H, \mathcal{D}, T) \to \Gamma \]
\( X(H, \mathcal{D}, T) \) with \( \lambda \)–quasiconvex image. Indeed, the existence of such a map is the *definition* of relative quasi-convexity in [1]. This definition is shown to be equivalent to the usual ones in [31, Appendix A].

Recall that the cusped space is built by attaching combinatorial horoballs to a Cayley graph, so there are canonical inclusions \( H \hookrightarrow X(H, \mathcal{D}, T) \) and \( G \hookrightarrow \Gamma \). The map \( i \) extends the natural inclusion map of \( H \) into \( G \).

**Lemma A.34.** There is some \( N \) so that the \( N \)–neighborhood of the image of \( i \) is a 0–hull for the action of \( H \) on \( \Gamma \).
Proof. There are four conditions to check. We will prove that each of them hold for any large enough value of $N$, and then take the maximum of the four lower bounds.

For a number $D \geq 0$ and a subset $A \subset \Gamma$, let $\mathcal{N}_D(A)$ denote the closed $R$-neighborhood of $A$ in $\Gamma$. Let $Y_D = \mathcal{N}_D(\iota(X(H, D, T)))$.

Condition (1): Since $\tilde{x} = 1 \in H \subset G$, we have $\tilde{x} \in Y_D$ for any $D \geq 0$.

Condition (2): Suppose that $\xi_1, \xi_2 \in AH$, the limit set of $H$ in $\partial \Gamma$, and suppose that $l$ is a geodesic between $\xi_1$ and $\xi_2$. To satisfy the second condition of Definition A.27 (with $R = 0$), we need $l$ to be contained in $Y_D$ for large enough $D$. The points $\xi_1$ and $\xi_2$ are limits of elements of $H$. Since $Y_0$ is $\lambda$-quasi-convex, a geodesic between any two elements of $H$ is contained in $Y_\lambda$. It is now straightforward to see that $l$ is contained in $Y_{\lambda+2\delta}$.

Condition (3): Suppose that $B$ is a horoball of $\Gamma$ whose stabilizer in $H$ is infinite. Algebraically, this gives peripheral subgroups $D$ of $H$ and $P$ of $G$, and $g \in G$ so that $gDg^{-1} \cap P$ is infinite. The condition from Definition A.26 ensures that $[P: gDg^{-1}] < \infty$. This implies that there is some $D_0$ so that $B \subset Y_{D_0}$. Since there are only finitely many such $D, P$ and $g$, up to the action of $G$, the number $D_0$ may be taken to work for all such horoballs $B$.

Condition (4): The final condition from Definition A.27 is that $H$ acts weakly geometrically finitely on $Y_N$. This is true for any $N > 0$. Note that $Y_N$ is quasi-convex and quasi-isometric to $Y_0$, the image of $i$. Because the peripheral subgroups of $H$ are finite index in maximal parabolic subgroups of $G$, the map $i$ is a quasi-isometric embedding. (The proof is similar to the proof that a quasiconvex subgroup of a hyperbolic group is quasi-isometrically embedded.) The map $i$ therefore gives an $H$-equivariant quasi-isometry between $X(H, D, T)$ and $Y_N$. Since $(H, D)$ acts weakly geometrically finitely on $X(H, D, T)$, it follows that $(H, D)$ acts weakly geometrically finitely on $Y_N$. □

Definition A.35. Let $\tilde{Z}_0$ be the $N$–neighborhood of $\Im(i)$ for $N$ sufficiently large that $\tilde{Z}_0$ is a 0–null. For $R > 0$, let $\tilde{Z}_R$ be the $R$–neighborhood of $\tilde{Z}_0$. Clearly $\tilde{Z}_R$ is an $R$–hull. Let $Z_R$ be the quotient of $\tilde{Z}_R$ by the $H$–action, and let $Y$ be the quotient of $\Gamma$ by the $G$–action, as in the previous section.

Theorem A.36. Let $G$ be hyperbolic, $H < G$ quasiconvex, and let $g \in G \setminus H$. Let $(G, \mathcal{P})$, $(H, D)$ be the relatively hyperbolic structures from Definition A.5. Let $A$ be a finite set in $G$.

Then for all sufficiently long $H$–fillings $\phi: G \to G(N_1, \ldots, N_m)$:

1. If $K = \ker(\phi)$, then $\Gamma/K$ is $\delta'$–hyperbolic for some $\delta'$ independent of the filling, and is (except for trivial loops) equal to the cusped space for $(G, \mathcal{P})$. In particular $(\bar{G}, \bar{\mathcal{P}})$ is relatively hyperbolic.

2. Let $\phi: \Gamma \to \bar{\Gamma}$. For some $\lambda'$ independent of the filling, $\Im(\phi \circ i)$ is $\lambda'$–quasiconvex. Thus the induced filling $(\bar{H}, \bar{D})$ is relatively quasiconvex in $(\bar{G}, \bar{\mathcal{P}})$.

3. The induced map $H(K_1, \ldots, K_n) \to G(N_1, \ldots, N_m)$ (described in Remark A.13) is injective.

4. $\phi(g) \notin \phi(H)$.

5. $\phi|_A$ is injective.

Proof. It is straightforward to see that $\Gamma/K$ is almost the cusped space for $(G, \mathcal{P})$ as advertised, and we leave the details to the reader. The extra loops come from horizontal
edges in horoballs between elements in the same $K$–orbit. When $G$ is torsion-free, the fact that $\delta'$ is independent of the filling is [1, Proposition 2.3]. If one quotes the filling theorem from [37] (which holds in the presence of torsion) instead of [17], then the proof from [1] works as written.

Again when $G$ is torsion-free, that $(\bar{H}, \bar{D})$ is $\lambda'$-quasiconvex for $\lambda'$ independent of the filling is [1, Proposition 4.3] (with a slightly different definition of $H$-filling, as discussed above). That this works in the presence of torsion is explained in [31, Appendix B], and the addition of the loops to the cusped space for $(\bar{G}, \bar{P})$ as above does not affect this quasiconvexity.

Further (again when $G$ is torsion-free), [1, Proposition 4.4] says that the induced map $H(K_1, \ldots, K_n) \to G(N_1, \ldots, N_m)$ is injective. Once we have noted (as in [31, Appendix B]) that [1, Lemma 4.2] holds in the presence of torsion and with the amended definition of $H$-filling, the proof of [1, Proposition 4.4] works as written.

Now, [1, Proposition 4.5] implies in the torsion-free case that $\phi(g)/\in \phi(H)$ for sufficiently large fillings. Again, the extension of this proposition in the presence of torsion is explained in [31, Appendix B].

Finally, (5) is part of [37, Theorem 1.1].

Proposition A.37. For any $R' > 0$, there is an $R$ so that $q(\tilde{Z}_R)$ is an $R'$–hull for the action of $\bar{H}$ on $\bar{\Gamma}$, for all sufficiently long fillings. (In particular, $R$ does not depend on the choice of long filling.)

Proof. Let $\gamma$ be a geodesic joining limit points of $\bar{H}$. The $\lambda'$–neighborhood of $W := q(\text{Im}(\hat{v}))$ contains $\gamma$, by quasi-convexity. Thus the $R$–neighborhood of $\gamma$ is contained in the $R + \lambda'$–neighborhood of $W$, hence in the image of $Z_{R + \lambda'}$.

The other conditions follow from the relative quasiconvexity of $\bar{H}$ in $\bar{G}$. 

Let $G \to \bar{G}$ be a sufficiently long filling to satisfy the conclusions of Theorem A.36, so that $\bar{\Gamma}$ is $\delta'$–hyperbolic, $\text{Im}(q \circ \hat{v})$ is $\lambda'$–quasiconvex, and so on.

Fix $R'$ bigger than the constant $D(\delta')$ from Theorem A.31. Then $q(\tilde{Z}_R)$ detects height in any sufficiently large filling, in a sense which we will describe below.

Lemma A.38. For all sufficiently long fillings $\phi: G \to G(N_1, \ldots, N_m)$, if $K = \ker(\phi)$, $K_H = K \cap H$ and $k \in K \setminus K_H$, then $k \tilde{Z}_R \cap \tilde{Z}_R = \emptyset$.

Proof. The set $A = \{g \in G \mid g \tilde{Z}_R \cap \tilde{Z}_R \neq \emptyset\}$ is a finite union of left cosets of $H$,

$$A = \bigsqcup_{i=0}^{l} g_i H, \quad g_0 = 1.$$

Applying Theorem A.36 for $g = g_1, \ldots, g = g_l$, we conclude that for all sufficiently long fillings, $\phi(g_i) \notin \phi(H)$ for $i > 0$. Equivalently $g_i h \notin K$ for any $h \in H$, and any $i > 0$. Thus for $k \in K \setminus K_H$, we have $k \notin A$, and so $k \tilde{Z}_R \cap \tilde{Z}_R = \emptyset$. 


Let \( \tilde{Z}_R \) be the quotient of \( \check{Z}_R \) by \( K_H \), and let \( Z_R = Z_R \) be the quotient of \( \tilde{Z}_R \) by the action of \( H \). By Lemma A.38, \( \check{Z}_R \) embeds in \( \check{\Gamma} \). Now we have a commutative diagram,

\[
\begin{array}{ccc}
H & \rightarrow & G \\
\downarrow & & \downarrow \\
\check{Z}_R & \rightarrow & \check{\Gamma} \\
\downarrow & & \downarrow \\
\check{\tilde{Z}}_R & \rightarrow & \check{G}/K
\end{array}
\]

where the horizontal maps are inclusions and the vertical maps are quotients by \( K_H \) and \( K \) respectively. After taking quotients by the relevant groups we get the diagram,

\[
\begin{array}{ccc}
Z_R & \xrightarrow{i} & Y \\
\downarrow & & \downarrow \\
\tilde{Z}_R & \xrightarrow{i} & Y
\end{array}
\]

where the vertical maps are homeomorphisms, and the horizontal maps are immersions inducing the inclusions \( H \rightarrow G \) and \( \check{H} \rightarrow \check{G} \). As maps, \( i \) and \( \tilde{i} \) are exactly the same, so the sets \( S_n \) and \( \tilde{S}_n \) are the same. For each \( i \in \{1, \ldots, n\} \) and each component \( C \) of \( S_n \) we have maps

\[
\tau_{C,i} : \pi_1(C) \rightarrow H,
\]

and

\[
\tilde{\tau}_{C,i} : \pi_1(C) \rightarrow \check{H}.
\]

Since the quotient \( Z_R = \tilde{Z}_R/H \) can also be thought of as \( \tilde{Z}_R/(H/K_H) \), we see that the homomorphisms \( \tilde{\tau}_{i,C} \) all factor as \( \tilde{\tau}_{i,C} = q_{H} \circ \tau_{i,C} \).

In particular, if \( \gamma \) is a loop in \( \tilde{S}_n \) so that \( \tilde{\tau}_{C,i}([\gamma]) \) is infinite for each \( i \in \{1, \ldots, n\} \) then it must be that \( \tau_{C,i}([\gamma]) \) is already infinite for each \( i \). Therefore we have the following result.

**Corollary A.39.** The height of \( \check{H} \) in \( \check{G} \) is at most the height of \( H \) in \( G \).

We now specialize to the case that \((H, D) < (G, P)\) comes from a quasiconvex subgroup \( H \) of a hyperbolic group \( G \), so that \( D \) is the malnormal core of \( H \) and \( P \) the induced peripheral structure on \( G \).

**Theorem A.40.** Assume \( P \) is the peripheral structure induced on \( G \) by the quasiconvex subgroup \( H \), and let \( G \rightarrow G(N_1, \ldots, N_m) \) be a sufficiently long \( H \)-filling. In case every filling kernel \( N_i \) has finite index in \( P_i \), the height of \( \check{H} \) in \( \check{G} \) is strictly less than that of \( H \) in \( G \).

**Proof.** Suppose that \( H \) has height \( n \) in \( G \) and that, contrary to the conclusion, \( \check{H} \) has height \( n \) in \( \check{G} \).

Fix \( R' > 0 \). By Proposition A.37, there is an \( R \) so that for any long enough filling the set \( q(\tilde{Z}_R) \) is an \( R' \)-hull for the action of \( \check{H} \) in \( \check{G} \). We choose \( R' \) large enough so that it satisfies the hypotheses of Theorem A.31. Specifically, we make sure \( R' > D(\delta') \) for the universal constant of hyperbolicity \( \delta' \) from Theorem A.36.
By Theorem A.31, the multiplicity of the map \( \overline{\tau} : \overline{Z_R} \to \overline{Y} \) is \( n \). Let \( \overline{C} \) be a component of \( \overline{S}_n \) (with basepoint \( \overline{p} = (\overline{p}_1, \ldots, \overline{p}_n) \)) so that each of the subgroups \( \overline{A}_i = \overline{\tau}_{C,i} (\pi_1(\overline{C}, \overline{p})) \) are infinite.\(^2\) By Lemma A.30, the groups \( \overline{A}_i \) are all conjugate in \( \overline{H} \), and so there are \( \overline{g}_{i,j} \in \overline{G} \) so that \( \overline{g}_{i,j} \overline{A}_i \overline{g}_{i,j}^{-1} = \overline{A}_i \). Since \( \overline{G} \) is a hyperbolic group, any infinite subgroup contains an infinite order element, so let \( \overline{\gamma}_a \in \overline{A}_1 \) be such an infinite order element, and suppose that \( \gamma_a \) is a loop in \( \overline{C} \) based at \( \overline{p} \) so that \( \overline{\tau}_{C,i}(\gamma_a) \).

Now, consider the diagram (3). The vertical maps are homeomorphisms, and so (as in the above discussion), induce a homeomorphism between \( \overline{S}_n \) and \( S_n \). Let \( C \) be the component of \( S_n \) corresponding to \( \overline{C} \), let \( p \) be the associated basepoint, and let \( \gamma_a \) be the loop in \( C \) associated to \( \gamma_a \). As in the discussion above, the image of each \( \tau_{C,i}([\gamma_a]) \) is infinite in \( H \).

This shows that \( a = \tau_{C,1}([\gamma_a]) \) is an element of infinite order in the intersection in \( G \) of \( n \) essentially distinct conjugate of \( H \). Thus \( a \) lies in a conjugate of an element of \( D \). Since the filling kernels \( N_i \) have finite index in \( P_i \), some power of \( a \) is contained in the kernel of the filling map \( \overline{G} \to \overline{G} \). But the image of \( a \) in \( \overline{G} \) is clearly \( \overline{a} \), which shows that \( \overline{a} \) cannot have infinite order, contrary to assumption. This completes the proof. \( \square \)

We now prove Theorem A.16.

**Proof of Theorem A.16.** We have \( \overline{G} \) hyperbolic, \( H < G \) quasiconvex and height \( k \geq 1 \). We then have \( (\overline{H}, D) \) relatively quasiconvex in \( (\overline{G}, P) \) where \( D \) is the malnormal core of \( \overline{H} \); and \( P = \{P_1, \ldots, P_m\} \) is the peripheral structure induced on \( G \).

Let \( \phi: \overline{G} \to \overline{G}(N_1, \ldots, N_m) \) be a sufficiently long \( H \)-filling, that the conclusions of Theorem A.36 and Theorem A.40 both hold, and suppose \( N_i \leq P_i \) for each \( i \).

By Theorem A.36, \( \overline{G} = \overline{G}(N_1, \ldots, N_m) \) is hyperbolic relative to \( \overline{P} = \{P_1/N_1, \ldots, P_m/N_m\} \), and \( (\overline{H}, D) \) is relatively quasiconvex in \( (\overline{G}, P) \). Since all the peripheral subgroups are finite, \( \overline{G} \) is hyperbolic, and \( \overline{H} \) is a quasiconvex subgroup of \( \overline{G} \). By Theorem A.40, the height of \( \overline{H} \) in \( \overline{G} \) is at most \( k - 1 \). \( \square \)

The next theorem is the same as [45, Theorem 13.1], but we point out some simplifications to the proof.

**Theorem A.41.** Let \( G = A \ast_C B \) be an amalgamated free product with \( C \) quasiconvex in \( G \), and \( G \) hyperbolic. Suppose that \( A, B \) are virtually special. Then \( G \) is virtually special. There is a similar statement in the case that \( G = A \ast_B \) where \( B \) is quasiconvex in \( G \), and \( A, B \) are virtually special.

**Proof.** We will focus on the amalgamated product case; the HNN case is similar, or follows as a corollary by a doubling trick. As in the proof of [45, Theorem 13.1], it suffices to prove that \( C < G \) is separable. Let \( g \notin C \) be an element that we would like to separate from \( C \). By Theorem A.36.(4), for all sufficiently long \( C \)-fillings \( \phi: \overline{G} \to \overline{C}, \phi(g) \notin \phi(C) \).

Now, take a sequence of fillings as in the proof of Theorem A.1, ensuring at each stage that the filling maps separate \( g \) from the image of \( C \), so that we obtain a quotient \( \phi: \overline{G} \to \overline{G} \) so that:

1. \( \overline{G} \) is hyperbolic;
2. \( \overline{C} = \phi(C) \) is finite; and
3. \( \phi(g) \notin \phi(C) \);

\( ^2\)We add a bar to our notation in the obvious way in the quotient.
The maps $\phi_A = \phi|_A \colon A \to \bar{A}$ and $\phi_B \colon B \to \bar{B}$ are fillings of $A$ and $B$ respectively. By choosing the sequence of fillings defining $\bar{G}$ to be sufficiently long and in appropriately chosen subgroups as in the proof of Theorem A.1, we can ensure that at each stage the maps restricted to the images of $A$ and $B$ satisfy the hypotheses of Theorem A.8. Therefore, for a long enough filling we have $\bar{A}$ and $\bar{B}$ are virtually special.

Each of the fillings kernels (taken successively) are normally generated by elements that are in the image of $C$. Therefore, by taking the obvious presentation for $G$ as an amalgamated free product, and adding relations from $C$ to get $\bar{G}$, we see that

$$\bar{G} = \bar{A} \ast_C \bar{B}.$$  

Since $\bar{C}$ is finite, it is almost malnormal and quasiconvex, so by the Malnormal Special Combination Theorem [45, Theorem 11.3] $\bar{G}$ is virtually special, and hence residually finite. Let $\eta \colon \bar{G} \to Q$ be a homomorphism to a finite group $Q$ so that $\eta(\phi(g)) \notin \eta(\bar{C})$. It is clear that the kernel of $\eta \circ \phi$ is a torsion-free subgroup of $G$ of finite-index separating $g$ from $C$.

Now we finish the proof as in [45, Theorem 13.1]. Since $C$ is quasiconvex and separable in $G$, there is a finite-index normal subgroup $G' \triangleleft G$ in which $C' = C \cap G'$ is malnormal in $G'$. Then $G'$ has a graph-of-groups decomposition with virtually special vertex groups and malnormal edge groups. In particular, $G'$ has a malnormal hierarchy terminating in virtually special groups, so $G'$ is virtually special by [45, Theorem 11.2].

Theorem A.42. [45, Theorem 13.3] Every word-hyperbolic group in $\mathcal{QVH}$ is virtually special.

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