Global smooth solutions of 3-D null-form wave equations in
exterior domains with Neumann boundary conditions

Li Jun\textsuperscript{1,*}, Yin Huicheng\textsuperscript{2,*}

1. Department of Mathematics and IMS, Nanjing University, Nanjing 210093, P.R.China.
2. School of Mathematical Sciences, Nanjing Normal University, Nanjing 210023, P.R.China.

Abstract

The paper is devoted to investigating long time behavior of smooth small data solutions to
3-D quasilinear wave equations outside of compact convex obstacles with Neumann boundary
conditions. Concretely speaking, when the surface of a 3-D compact convex obstacle is smooth
and the quasilinear wave equation fulfills the null condition, we prove that the smooth small data
solution exists globally provided that the Neumann boundary condition on the exterior domain is
given. The approach is based on the weighted $L^2$ time-space energy estimates associated with
modified Klainerman vector fields which are introduced by Keel-Smith-Sogge \cite{22} and Metcalfe-
Sogge \cite{32} as well as the classical energy decay estimates on the first order derivatives of solutions
for the linear wave equation with Neumann boundary condition by Morawetz \cite{36}. One of the
main ingredients in the current paper is the establishment of local energy decay estimates of the
solution itself. As an application of the main result, the global stability to 3-D static compressible
Chaplygin gases in exterior domain is shown under the initial irrotational perturbation with small
amplitude.

Keywords: Quasilinear wave equation, exterior domain, Neumann boundary condition, null
condition, convex obstacle, elliptic regularity

Mathematical Subject Classification 2000: 35L10, 35L71, 35L05.

1 Introduction

In this paper, we provide a rigorous mathematical analysis on the global existence of smooth small
data solutions to 3-D quasilinear wave equations outside of compact convex obstacles with smooth
boundaries. There are two main starting points for investigating this problem. Mathematically, the
problem is one of the fundamental topics in studying initial-boundary value problems for nonlinear
wave equations; Physically, this problem is closely associated with some mathematical problems

*Li Jun (lijun@nju.edu.cn) and Yin Huicheng (huicheng@nju.edu.cn, 05407@nju.edu.cn) are supported by the
NSFC (No.11371189, No.11571177), and the Priority Academic Program Development of Jiangsu Higher Education
Institutions.
arising from aerodynamics, such as the long time stability of motion of compressible gases in exterior domains. To achieve our destination of global existence, as in the well-known works done by Christodoulou [9] and S.Klainerman [25] for the Cauchy problem of 3-D quasilinear wave equations, we require that the nonlinearities of the equations involve null forms.

So far the blowup or global existence of smooth small data solutions have been systematically studied for the initial data problem of quasilinear wave equations in $\mathbb{R}_+ \times \mathbb{R}^n$  

\[
\begin{cases}
Q^{\alpha\beta}(u, \partial u)\partial^2_{\alpha\beta} u = 0, \\
(u, \partial_t u)(0, x) = \varepsilon(u_0, u_1)(x),
\end{cases}
\]  

where $x_0 = t, x = (x_1, ..., x_n), \varepsilon > 0$ is a sufficiently small constant, $u_0(x), u_1(x) \in C^\infty_0(\mathbb{R}^n)$, $Q^{\alpha\beta}(u, \partial u) = Q^{\beta\alpha}(u, \partial u)$ are smooth functions in their arguments. Without loss of generality, one can write  

\[
Q^\alpha{}^\beta(u, \partial u) = c^\alpha{}^\beta + d^\alpha{}^\beta u + e^\alpha{}^\beta \partial_\gamma u + O(|u|^2 + |\partial u|^2),
\]

where $c^\alpha{}^\beta, d^\alpha{}^\beta$ and $e^\alpha{}^\beta$ are constants, $c^\alpha{}^\beta \partial_\gamma = \Box \equiv \partial^2 - \Delta$. By the well-known results in [13], [24], [26], [28] and [29], one has that (1.1) admits a global smooth small data solution for $n \geq 4$. If $n = 3$, the blowup or global existence of smooth solutions to (1.1) have been basically established, one can see [2], [5], [6], [7], [9], [10], [13], [25], [30], [31], [39], [41] and the references therein. If $n = 2$ and the 2-D nonlinear wave in (1.1) admits such a form (whose coefficients depend only on the first order derivatives $\partial u$)

\[
\begin{cases}
Q^\alpha{}^\beta(\partial u)\partial^2_{\alpha\beta} u = 0, \\
(u, \partial_t u)(0, x) = \varepsilon(u_0, u_1)(x), \\
x \in \mathbb{R}^2,
\end{cases}
\]

where $Q^\alpha{}^\beta(\partial u) = Q^\beta\alpha(\partial u) = c^\alpha{}^\beta + e^\alpha{}^\beta \partial_\gamma u + e^\alpha{}^\beta \partial_\gamma u + O(|\partial u|^2)$. It is well-known that when $e^\alpha{}^\beta \omega_\alpha \omega_\beta \omega_\gamma \neq 0$ or $e^\alpha{}^\beta \omega_\alpha \omega_\beta \omega_\gamma \omega_\mu \neq 0$ for $\omega_0 = -1$ and $\omega = (\omega_1, \omega_2) \in \mathbb{S}^1$, the smooth solution $u$ to (1.2) blows up in finite time as long as $(u_0(x), u_1(x)) \neq 0$ (see [2], [4], [18] and so on); when $e^\alpha{}^\beta \omega_\alpha \omega_\beta \omega_\gamma \equiv 0$ and $e^\alpha{}^\beta \omega_\alpha \omega_\beta \omega_\gamma \omega_\mu \equiv 0$, (1.2) has a global smooth solution $u$ (see [3]).

Compared with Cauchy problems (1.1) and (1.2), Dirichlet-wave equations and Neumann-wave equations are also attractive for their theoretical significance and applicable values. The Neumann-wave equation as well as the Dirichlet-wave equation are two fundamental models in studying initial-boundary value problems of quasilinear wave equations. For the Dirichlet-wave equations, there have been many interesting works on almost global/global existence of smooth small data solutions to 2-D/3-D quasilinear scalar equations or systems with multiple speeds (one can see [12], [20]-[23], [32]-[35], [40] and the references therein). While, for the Neumann-wave equation, to our best knowledge, so far there have been few global existence results for the 3-D quasilinear equations in (1.1) except the symmetric solution case (see [15] and so on). In this paper, we focus on this problem under the convex condition of compact smooth obstacles. It is

1Hereafter, the Greek letters $\alpha, \beta, \cdots$ are used to denote an index from 0 to $n$ with 0 standing for the time variable and Latin letters $i, j, k, \cdots$ are used to denote an index from 1 to $n$. Moreover, we use $\partial$ and $\nabla$ to denote the time-space gradient and the space gradient respectively. In addition, repeated indices are always understood as summations.
proved that the smooth small data solutions on the exterior of the convex domain exist globally when the null conditions are satisfied and some “admissible condition” is posed. More concretely, the following initial-boundary value problem of 3-D quasilinear wave equation is considered:

\[
\begin{aligned}
\Box u &= N(\partial u, \partial^2 u), \quad (t, x) \in \mathbb{R}_+ \times \Omega, \\
\partial_\nu u &= 0, \quad (t, x) \in \mathbb{R}_+ \times \partial \Omega, \\
(u, \partial_t u)(0, x) &= \varepsilon(u_0, u_1)(x), \quad x \in \Omega,
\end{aligned}
\]  

(1.3)

where the nonlinearity \( N(\partial u, \partial^2 u) \) is smooth in its arguments and linear in \( \partial^2 u \), \( \Omega = \mathbb{R}^3 \setminus K \) and \( K \) is a compact convex obstacle with smooth boundary, \( \nu \) stands for the unit outer normal direction of \( \mathbb{R}_+ \times \partial \Omega \). Without loss of generality, we assume throughout that \( K \) contains the origin point and

\[
K = \{ x = r\omega \in \mathbb{R}^3 : r < b(\omega), \omega \in S^2 \}
\]

(1.4)

with \( b \) being a smooth convex function and \( \frac{3}{4} < b(\omega) < 1 \).

In addition, \( N(\partial u, \partial^2 u) \) can be written as

\[
N(\partial u, \partial^2 u) = S(\partial u) + Q^{\alpha\beta}(\partial u)\partial^2_{\alpha\beta}u
\]

(1.5)

with

\[
S(\partial u) = S^{\alpha\beta}\partial_\alpha u\partial_\beta u + O(|\partial u|), \quad Q^{\alpha\beta}(\partial u) = Q^{\alpha\beta}_\mu \partial_\mu u + O(|\partial u|),
\]

where \( Q^{\alpha\beta}(\partial u) = Q^{\beta\alpha}(\partial u) \), \( S^{\alpha\beta} = S^{\beta\alpha} \) and \( Q^{\alpha\beta}_\mu = Q^{\beta\alpha}_\mu \) are some constants. Meanwhile, \( N(\partial u, \partial^2 u) \) is assumed to satisfy the null conditions:

\[
S^{\alpha\beta}\omega_\alpha\omega_\beta \equiv 0 \quad \text{and} \quad Q^{\alpha\beta}_\mu \omega_\mu\omega_\alpha\omega_\beta \equiv 0 \quad \text{on} \quad \omega_0^2 = \sum_{i=1}^{3} \omega_i^2.
\]

(1.6)

On the other hand, motivated by the fixed wall condition of compressible Chaplygin gases on the exterior domain, we will pose the following “admissible condition” on \( N(\partial u, \partial^2 u) \) for arbitrary smooth functions \( v \) and \( w \) satisfying \( \partial_\nu v|_{\mathbb{R}_+ \times \partial \Omega} = 0 \) and \( \partial_\nu w|_{\mathbb{R}_+ \times \partial \Omega} = 0 \):

\[
Q^{\alpha\beta}(\partial v)\nu^\alpha \partial_\beta w \equiv 0, \quad (t, x) \in \mathbb{R}_+ \times \partial \Omega,
\]

(1.7)

where \( \nu^\alpha \) stands for the \( \alpha \)th component of \( \nu \). Some explanations on condition (1.7) will be given in Remark 1.1 below.

The goal of the current paper is to find the global smooth small data solution \( u \) to (1.3) with conditions (1.5)-(1.7) and compatibility conditions up to infinite order for the initial-boundary values. Here we point out that in order to obtain the smooth solution \( u \) of (1.3), it is necessary to pose the corresponding compatible conditions for the initial-boundary values (see Remark 1.2).

To state the main results conveniently, we now introduce some notations and functional spaces throughout the paper. Let \( \| \cdot \|_{L^2(D)} \) stand for the usual \( L^2 \)–norm on domain \( D \) and \( \| \cdot \| \) denote \( \| \cdot \|_{L^2(\Omega)} \). In addition, \( \langle \cdot \rangle := \sqrt{1 + |\cdot|^2} \). A \( \lesssim B \) means that there exists a universal positive constant \( C \) such that \( A \leq CB \). The main result of this paper is:
Theorem 1.1. For the given compact convex obstacle $K$ in (1.4), if the nonlinearity $N(\partial u, \partial^2 u)$ satisfies (1.5)-(1.7) and the initial smooth data $(u_0(x), u_1(x))$ satisfy the compatibility conditions up to infinite order, then there is a constant $\varepsilon_0 > 0$ such that for all $0 < \varepsilon \leq \varepsilon_0$, when

$$
\sum_{|\beta| \leq 69} \| \langle x \rangle^{|\beta|} \nabla^\beta u_0 \| + \sum_{|\beta| \leq 68} \| \langle x \rangle^{1+|\beta|} \nabla^\beta u_1 \| \lesssim 1, \quad (1.8)
$$

the problem (1.3) has a unique global smooth solution $u \in C^\infty(\mathbb{R}_+ \times \mathcal{O})$. Moreover,

$$(1 + t + |x|)(|u(t,x)| + |\partial u(t,x)|) \lesssim \varepsilon. \quad (1.9)$$

Remark 1.1. We pose the “admissible condition” (1.7) in Theorem 1.1 due to the following two reasons: First, this kind of condition naturally comes from the fixed wall condition of Chaplygin gases on the exterior domain (see details in Sect.7 below). Second, under condition (1.7) one still obtains the Neumann-type boundary condition for (1.4) when the commutator arguments are taken (see the whole Sect.3 below).

Remark 1.2. We give some illustrations on the compatibility conditions of initial-boundary values mentioned in Theorem 1.1. Let $I = \{\nabla^\beta u : 1 \leq |\beta| \leq k\}$ be the collection of all spatial derivatives up to $k$ order of $u$. If $u \in \bigcap_{m=0}^{\infty} C^k([0,T], H^{m-k}(\mathcal{O})) \ (m \geq 2)$ is a local solution of (1.3), one then has $\partial^0_\alpha u(0,\cdot) = \psi_k(J_k u_0, J_{k-1} u_1) \ (0 \leq k \leq m)$ for certain functions $\psi_k$ depending on the nonlinearity $N$. In this case, the $m$th order compatibility condition for (1.3) is just the requirement that all the $\partial_\nu \psi_k$ vanish on $\partial \mathcal{O}$ for $0 \leq k \leq m - 1$. In addition, $(u_0, u_1) \in C^\infty(\mathcal{O})$ is said to satisfy the compatibility conditions up to infinite order if $m$th order compatibility condition holds for all $m \in \mathbb{N}$.

Remark 1.3. For the Dirichlet boundary value problem, some authors have established the almost global or global existence of smooth small data solutions to quasilinear scalar wave equations or systems with multiple speeds (see [20]–[23], [32]–[35]). The advantage of homogenous Dirichlet boundary value for wave equations is that the local-in-space $L^2$ norm of solution $u$ itself can be directly derived through the resulting energy estimates of the first derivatives $\partial u$ (one can also be referred to (14)). However, for the Neumann-wave equations, the cases are different as pointed out in [8] and [17] due to the lack of the value of solution $u$ on the boundary. Fortunately, for the Neumann boundary value problem (1.3), we can establish the local-in-space $L^2$ norm of the solution $u$ itself in this paper.

The proof of Theorem 1.1 will follow some key ideas of Klainerman [25] and Metcalfe-Sogge [32] associated with the method of Klainerman’s vector fields and the exponential decay estimate of local energy with respect to Neumann-wave equations shown in [36]. The classical Klainerman’s vector fields contain the generators of spatial rotations and time-space translations, the hyperbolic rotations as well as the scaling vector field, namely,

$$Z = \{\partial_\alpha, \Omega\}, \quad L_i = x_i \partial_0 + t \partial_i, \quad L = t \partial_0 + x_i \partial_i$$

with $\Omega = \{x_2 \partial_3 - x_3 \partial_2, x_3 \partial_1 - x_1 \partial_3, x_1 \partial_2 - x_2 \partial_1\}$. As pointed in [8], [14], [32] and so on, the hyperbolic rotations $\{L_i\}$ are not applicable to the current initial-boundary value problems of
quasilinear wave equations. This leads to a key difficulty that we cannot use Klainerman’s argument in [25] to obtain the standard $t^{-1}$ decay of solution $u$ and $t^{-1} (r - t)^{-1/2}$ decay of $\partial u$. More precisely, due to the lack of the hyperbolic rotations $\{L_i\}$, one cannot obtain the pointwise decay estimates directly from weighted energy estimates associated with Klainerman’s vector fields by Klainerman’s inequality. Alternatively, as in [32], to compensate the lack of the hyperbolic rotations $\{L_i\}$, one may use elliptic regularity estimates to improve the spatial regularities of solution $u$. In this situation, new difficulties can be overcome by establishing the weighted time-space $L^2$ estimates associated with Klainerman’s vector fields $Z$ and $L$ (this can be regarded as the variation version of Keel-Smith-Sogge estimates in [22]) as well as the pointwise estimates established in Sect. 4. From this, one can convert the $(x)^{-1}$ decay of solution $u$, obtained from the above estimates, to the expected decay (1.9) for deriving the global existence of $u$. Compared with the classical Klainerman’ vector field method for treating the initial data problem of the quasilinear wave equation in (1.3) (see [25], [31] and so on), we require to establish the local-in-space estimate on the solution $u$ itself other than only for $\partial u$ as in [25] and [31] since we shall consider $\chi(x) u$ instead of $u$ for some truncated function $\chi(x)$ so that problem (1.3) can be reduced to the boundaryless case. However, unlike the Dirichlet boundary value problem in [32], there is no direct estimate on the solution $u$ itself for the Neumann boundary value problem due to the lack of the boundary value of $u$. To overcome this difficulty, on one hand, we establish the exponential-type decay estimate of solution $u$ in Lemma 2.3 on the other hand, based on the new observation that $L^2$ energy of $\partial u$ is bounded under the Neumann boundary value condition (see Lemma 3.1), we will develop a closed elliptic regularity estimate in Lemma 2.3 by utilizing the $L^2$ norm of $\partial u$ to replace the $L^2$ norm of $u$ itself. Combining these two key Lemmas with $L^2$ time-space estimates and pointwise estimates, motivated by [32], we eventually complete the proof of Theorem 1.1.

The paper is organized as follows. In Sect. 2 some basic lemmas associated with null conditions, Sobolev inequality and elliptic regularity estimates are given. In Sect. 3 Sect. 4 we establish the weighted time-space $L^2$ estimates associated with partial modified Klainerman’s vector fields and further derive the pointwise decay estimates of solution $u$ to problem (1.3). These estimates will play an essential role in proving Theorem 1.1 by the continuity induction argument. In Sect. 5 the assumption used in continuity induction argument is closed, and then Theorem 1.1 is shown. In Sect. 6 the local existence of solution to problem (1.3) is established based on the “admissible condition” (1.7) and some compatible conditions. In Sect. 7 as an application of Theorem 1.1, we prove the global stability of the 3-D static compressible Chaplygin gases in an exterior domain under initial irrotational small-amplitude perturbation. In Appendix A we establish two auxiliary lemmas in the application of Theorem 1.1.

In addition, throughout the paper, we will use the following notations and functional spaces.

- For the operator vector field $W = (W_1, \cdots, W_l)$ and $k \in (\mathbb{N} \cup \{0\})^l$ for any integer $l$, $W^k = \prod_{i=1}^{l} W_i^{k_i}$.
- For any positive constants $R_1 > R_2 > 1$ ($i = 1, 2$) and $r = |x| = \sqrt{x^2_1 + x^2_2 + x^2_3}$, define $\{r \leq R_1\} = \{x \in \mathcal{O} : r \leq R_1\}$ and $\{R_2 < r < R_1\} = \{x \in \mathcal{O} : R_2 < r < R_1\}$.
- Let $\| \cdot \|_{H^k(D)}$ ($\| \cdot \|_{L^2(D)}$) stand for the usual $H^k$ ($L^2$)–norm on the domain $D$ and $\| \cdot \|_{H^k(\mathcal{O})}$ ($\| \cdot \|_{L^2(\mathcal{O})}$) denote $\| \cdot \|_{H^k(\mathcal{O})}$ ($\| \cdot \|_{L^2(\mathcal{O})}$).
- $C(\cdot)$ is a positive constant only depending on the variable $\cdot$. 
\[ L = t\partial_t + g(x)x^i \partial_i \] is the modified operator of \( L = t\partial_t + x_i \partial_i \), where \( g(x) = g(|x|) \) is a smooth radial symmetric function with \( g(|x|) = 1 \) for \(|x| \geq 3/2\), \( g(|x|) = 0 \) for \(|x| \leq 1\) and \( 0 \leq g'(|x|) \leq 2\).

## 2 Preliminaries

In this section, some basic results will be listed or established. These results will play a key role in proving Theorem 1.1.

**Lemma 2.1. (Sobolev type inequality [25])** Suppose that \( v \in C^\infty(\mathcal{O}) \), then for \( R \geq 4 \),

\[
\|v\|_{L^\infty(R/2 \leq |x| \leq R)} \lesssim R^{-1} \sum_{|\alpha|+|\beta| \leq 2} \|\Omega^\alpha \nabla^\beta v\|_{L^2(R/4 \leq |x| \leq 2R)},
\]

and

\[
\|v\|_{L^\infty(R \leq |x| \leq R+1)} \lesssim R^{-1} \sum_{|\alpha|+|\beta| \leq 2} \|\Omega^\alpha \nabla^\beta v\|_{L^2(R-1 \leq |x| \leq R+2)}.
\]

**Lemma 2.2. (Hardy type inequality)** For any smooth function \( v \in C^\infty(\mathcal{O}) \) decaying fast at infinity, then

\[
\|v/r\| \leq 2 \|\partial v\|.
\]  

**Proof.** It follows from (1.4) that

\[
\|v/r\|^2 = \int_{S^2} \int_0^{+\infty} v^2(r, \omega) dr d\sigma
\]

\[
= -\int_{S^2} \int_0^{+\infty} 2r (v \partial_r v)(r, \omega) dr d\sigma - \int_{S^2} b(\omega) v^2(b(\omega), \omega) d\sigma
\]

\[
\leq 2 \|v/r\| \|\partial v\|,
\]

which yields (2.1). \qed

**Lemma 2.3. (Elliptic regularity estimate)** Suppose that \( \psi \in C^\infty(\mathcal{O}) \) satisfies \( \partial_{\nu} \psi = 0 \) on \( \partial \mathcal{O} \). Then one has that for any \( R \geq 2 \) and any nonnegative integer \( k \),

\[
\|\nabla^2 \psi\|_{H^k(R \leq |x| \leq R+1)} \leq C(k)(\|\nabla \psi\|_{L^2(R-1 \leq |x| \leq R+2)} + \|\Delta \psi\|_{H^k(R-1 \leq |x| \leq R+2)}).
\]  

In addition, the following elliptic estimate near boundary \( \partial \mathcal{O} \) holds

\[
\|\nabla^2 \psi\|_{H^k(|x| \leq 3)} \leq C(k)(\|\nabla \psi\|_{L^2(|x| \leq 4)} + \|\Delta \psi\|_{H^k(|x| \leq 4)}).
\]  

**Proof.** At first, we point out that estimate (2.2) does not depend on the boundary condition of \( \psi \) and it just comes from the standard elliptic interior regularity estimate (see Chapter 6 of [13]).
As for the estimate (2.3), we define \( \tilde{\psi} = \frac{1}{|\{ |x| \leq 4 \}|} \int_{\{ |x| \leq 4 \}} \psi dx \). Then it follows from the elliptic regularity estimates near the boundary for Neumann boundary conditions (see Theorem 15.2 in [1]) and Poincare inequality that
\[
\| \nabla^2 \psi \|_{H^k(|x| \leq 3)} = \| \nabla^2 (\psi - \tilde{\psi}) \|_{H^k(|x| \leq 3)} \\
\leq C(k) \left( \| \psi - \tilde{\psi} \|_{L^2(|x| \leq 4)} + \| \Delta (\psi - \tilde{\psi}) \|_{H^k(|x| \leq 4)} \right) \\
\leq C(k) \left( \| \nabla \psi \|_{L^2(|x| \leq 4)} + \| \Delta \psi \|_{H^k(|x| \leq 4)} \right),
\]
which derives (2.3).

Next we consider the following linear Neumann-wave equation problem

\[
\begin{cases}
\Box v = F, & (t, x) \in \mathbb{R}_+ \times \mathcal{O}, \\
\partial_{\nu} v = 0, & (t, x) \in \mathbb{R}_+ \times \partial \mathcal{O}, \\
v(t, x) \equiv 0, & t \leq 0.
\end{cases}
\]

(2.4)

Then we have that

**Lemma 2.4.** For the smooth solution of problem (2.4), one has that for any nonnegative integer \( k \),
\[
\sum_{0 \leq |\alpha| \leq k} \| \partial^\alpha v(t, \cdot) \| \leq C(k) \left( \sum_{0 \leq j \leq k} \int_0^t \| \partial^j_0 F(s, \cdot) \| ds + \sum_{0 \leq |\alpha| \leq k-1} \| \partial^\alpha F(t, \cdot) \| \right). \tag{2.5}
\]

**Proof.** For any nonnegative integer \( j \), by \( \partial_{\nu} \partial^j_0 v = 0 \) on \( \mathbb{R}_+ \times \partial \mathcal{O} \) and the standard energy estimate (see Lemma 3.1), we get
\[
\| \partial \partial^j_0 v(t, \cdot) \| \leq \int_0^t \| \partial^j_1 F(s, \cdot) \| ds. \tag{2.6}
\]

In addition, by Lemma 2.3 one has that for \( 0 \leq j \leq k - 1 \),
\[
\| \partial^2 \partial^j_0 v(t, \cdot) \|_{k-j-1} \leq \| \partial \partial^j_0 v(t, \cdot) \| + \| \partial^j_0 \Box v(t, \cdot) \|_{k-j-1} + \| \partial^{j+2} v(t, \cdot) \|_{k-j-1}.
\]

Then by induction argument on \( j \) from 0 to \( k - 1 \), we have
\[
\sum_{0 \leq |\alpha| \leq k} \| \partial^\alpha v(t, \cdot) \| \leq C(k) \left( \sum_{0 \leq j \leq k} \| \partial^j_0 v(t, \cdot) \| + \sum_{0 \leq |\alpha| \leq k-1} \| \partial^\alpha F(t, \cdot) \| \right). \tag{2.7}
\]

Thus, (2.5) is obtained from (2.6) and (2.7) by induction argument on \( j \) from 0 to \( k - 1 \).
Lemma 2.5. (Exponential-type decay estimate) For problem (2.4), suppose that assumption (1.4) holds, and $F$ is smooth and supported in $\{ |x| \leq R \}$ for some positive $R > 1$. Then there exist two positive constants $\kappa$ and $c < 1$ depending on $R$ and the geometry of $\partial \mathcal{O}$ such that for the smooth solution $v$ of (2.4),
\begin{align}
\| \partial v(t, \cdot) \|_{L^2(|x| \leq 5)} & \leq \kappa \int_0^t e^{-c(t-s)} \| F(s, \cdot) \| ds, \tag{2.8}
\end{align}
and
\begin{align}
\| v(t, \cdot) \|_{L^2(|x| \leq 4)} & \leq \kappa \sum_{0 \leq j \leq 1} \int_0^t e^{-c(t-s)} \| \partial_j^0 F(s, \cdot) \| ds. \tag{2.9}
\end{align}

Proof. Note that estimate (2.8) directly comes from THE MAIN THEOREM of [36] and the Duhamel principle.

In addition, by $\partial_\nu \partial_0 v = 0$ on $\mathbb{R}_+ \times \partial \mathcal{O}$, it follows from (2.8) with $\partial_0 v$ that
\begin{align}
\sum_{0 \leq j \leq 1} \| \partial_j^0 v(t, \cdot) \|_{L^2(|x| \leq 5)} & \leq \sum_{0 \leq j \leq 1} \int_0^t e^{-c(t-s)} \| \partial_j^0 F(s, \cdot) \| ds.
\end{align}
Combining this with (2.7) in Lemma 2.4 for $k = 1$ that
\begin{align}
\sum_{0 \leq |\alpha| \leq 1} \| \partial^\alpha v(t, \cdot) \| & \lesssim \left( \sum_{0 \leq j \leq 1} \int_0^t e^{-c(t-s)} \| \partial_j^0 F(s, \cdot) \| ds + \| F(t, \cdot) \| \right). \tag{2.10}
\end{align}

Based on (2.10), we now derive (2.9). For this purpose, at first we take a coordinate transformation such that $\partial \mathcal{O}$ is changed into $S^2$. Let
\begin{align}
y = \frac{x}{(1 - g(x/2)) b(\omega) + g(x/2)}. \tag{2.11}
\end{align}

Obviously, one has
\begin{align}
\partial_r \left( \frac{r}{(1 - g(r/2)) b(\omega) + g(r/2)} \right) & = \frac{b(\omega) + (1 - b(\omega)) g(r/2) - 1/2(1 - b(\omega)) g'(r/2)}{((1 - g(r/2)) b(\omega) + g(r/2))^2} \tag{2.12}
\end{align}

> 0,

where the last inequality comes from the assumption of $b(\omega)$ in (1.4) and the definition of $g$ in the end of Sect.1.2.

With (2.12) and the definition of $g$, the transformation (2.11) is a diffeomorphism from $\mathcal{O}$ to $\mathbb{R}^3 \setminus B_1(0)$. In addition, it is easy to know that the Jacobian matrices $\partial y/\partial x$ and $\partial x/\partial y$ satisfy for any nonnegative integer $k$,
\begin{align}
\| \partial y/\partial x - I_3 \|_{C^k_b(|x| \leq 3)} + \| \partial x/\partial y - I_3 \|_{C^k_b(|y| \leq 3)} & \leq C(k), \tag{2.13}
\end{align}

If $b(\omega)$ in (1.4) is defined to fulfill $K < b(\omega) < 1$ for some positive constant $K$, then (2.12) also stands if we select the function $g$ such that $|g'(r)| \leq \frac{2K}{r^2}$.
where $I_3$ represents the $3 \times 3$ unit matrix. Under transformation (2.11), with the help of (2.13), problem (2.4) is converted into

$$\\begin{cases} \Box v = F + \chi_{\{|y| \leq 3\}}(y)L_1(\partial v, \partial^2 v), & (t, y) \in \mathbb{R}^+ \times \mathbb{R}^3 \setminus B_1(0), \\ \partial_r v = L_2(\partial v), & (t, y) \in \mathbb{R}^+ \times \partial B_1(0), \\ v(t, y) = 0, & t < 0, \end{cases} \quad (2.14)$$

where $\chi_{\{|y| \leq 3\}}$ is the characteristic function of domain $\{y : 1 \leq |y| \leq 3\}$, $L_1(\partial v, \partial^2 v)$ and $L_2(\partial v)$ are linear with respect to their arguments, and satisfies

$$|L_1(\partial v, \partial^2 v)| \lesssim |\partial v| + |\partial^2 v| \quad \text{and} \quad |L_2(\partial v)| \lesssim |\partial v|.$$  

Set $V = \int_{S^2} vd\sigma/|S^2|$, one has from (2.14) that

$$\\begin{cases} \partial^2 V - \Box V - \frac{2}{r} \partial_r V = F_1, & (t, r) \in \mathbb{R}^+ \times (1, +\infty), \\ \partial_r V = F_2, & (t, r) \in \mathbb{R}^+ \times \{1\}, \\ V(t, r) = 0, & t < 0, \end{cases} \quad (2.15)$$

where $F_1 = \int_{S^2} \Box v d\sigma/|S^2|$ and $F_2 = \int_{S^2} \partial_r v d\sigma/|S^2|$. It follows from (2.15) and the characteristics method that $V$ admits the following explicit expression

$$V(t, r) = \frac{1}{r} V_0(t - r + 1) + \frac{1}{r} \int_1^r \left[ \int_{t - r + 2r'} e^{-l} sF_1(t - r + 2r' - s, s) ds \right] dr'.$$

where $V_0(p)$ is expressed as

$$V_0(p) = e^{-p} \int_0^p e^l \left[ \int_1^{l+1} sF_1(l + 1 - s, s) ds - F_2(l, 1) \right] dl. \quad (2.17)$$

By (2.16), Poincare inequality and (2.11)-(2.13), we arrive at

$$\|v\|_{L^2(|x| \leq 4)} \lesssim \|v - V(t, 1)\|_{L^2(|x| \leq 4)} + |V(t, 1)|$$

$$\lesssim \|\partial v\|_{L^2(|x| \leq 4)} + |V_0(t)|$$

$$\lesssim \|\partial v\|_{L^2(|x| \leq 4)} + \int_0^t e^{-(t-s)} \|F_1(s, \cdot)\| ds + e^{-t} \int_0^t |F_2(l, 1)| dl. \quad (2.18)$$

With the definitions of $F_i$ ($i = 1, 2$) in (2.14) and (2.15), it derives from (2.17)-(2.18) and Sobolev trace theorem that

$$\|v\|_{L^2(|x| \leq 4)} \lesssim \|\partial v\|_{L^2(|x| \leq 4)} + \int_0^t e^{-(t-s)} \|F(s, \cdot)\| ds$$

$$+ \int_0^t e^{-(t-s)} \|\partial v, \partial^2 v)(s, \cdot)\|_{L^2(|x| \leq 4)} ds + e^{-t} \int_0^t \|\partial v, \partial^2 v)(s, \cdot)\|_{L^2(|x| \leq 4)} ds.$$

Combining this with (2.10) yields (2.9).
Remark 2.1. Under the assumptions in Lemma 2.5, similar to (2.10), estimate (2.5) can be improved as
\[
\sum_{0 \leq |\alpha| \leq k} \| \partial^\alpha \varphi(t, \cdot) \| \leq C(k) \left( \sum_{0 \leq j \leq k} \int_0^t e^{-c(t-s)} \| \partial_j^\alpha F(s, \cdot) \| \, ds + \sum_{0 \leq |\alpha| \leq k-1} \| \partial^\alpha F(t, \cdot) \| \right).
\]

Next two lemmas show the relations between null conditions in (1.6) and the partial Klainerman’s vector fields \( \Gamma = \{ Z, L \} \), which can be found in [22] and [32].

Lemma 2.6. (Estimates under null conditions) Suppose that the null conditions (1.6) hold. Then
\[
|S^{\alpha\beta} \partial_\alpha w \partial_\beta v| \lesssim \langle r \rangle^{-1} \left( |\Gamma w| |\partial v| + |\partial w| |\Gamma v| \right)
\]
and
\[
|Q_\mu^{\alpha\beta} \partial_\mu \partial_\alpha^2 v| \lesssim \langle r \rangle^{-1} \left( |\Gamma w| |\partial^2 v| + |\partial w| |\partial \Gamma v| \right) + \frac{(t-r)}{(t+r)} |\partial w| |\partial^2 v|.
\]

Lemma 2.7. (Weighted energy estimates [22]) Suppose that \( v \in C^\infty(\mathbb{R} \times \mathbb{R}^3) \) vanishes for large \( x \) and \( v(t, x) \equiv 0 \) for \( t \leq 0 \), then one has that for any given nonnegative integers \( \mu \) and \( \alpha \),
\[
(\ln(2 + T))^{-1/2} \| \langle x \rangle^{-1/2} \partial(t^\mu Z^\alpha v) \|_{L^2([0,T] \times \mathbb{R}^3)} \lesssim \int_0^T \| \Box t^\mu Z^\alpha v(s, \cdot) \|_{L^2(\mathbb{R}^3)} \, ds.
\]
In particular,
\[
\sum_{|\beta| \leq 1} \| t^\mu Z^\alpha \partial_\beta^2 v \|_{L^2([0,T] \times \{ |x| \leq 4 \})} \lesssim \int_0^T \sum_{\nu \leq \mu} \| \Box t^\nu Z^\alpha v(s, \cdot) \|_{L^2(\mathbb{R}^3)} \, ds. \tag{2.19}
\]

3 \( L^2 \) spatial-energy and time-space energy estimates

In this section, we will focus on some fundamental energy estimates of smooth solutions \( u \) to the following linear Neumann-wave equation with variable coefficients
\[
\begin{cases}
\Box_h u = F, & (t, x) \in \mathbb{R}_+ \times \mathcal{O}, \\
\partial_\nu u = 0, & (t, x) \in \mathbb{R}_+ \times \partial \mathcal{O}, \\
(u, \partial_t u)(t, x) = (f, g)(x), & x \in \mathcal{O},
\end{cases}
\tag{3.1}
\]
where \( \Box_h = \Box + h^{\alpha\beta}(t, x) \partial_\alpha^2 \partial_\beta \) with \( h^{\alpha\beta} = h^{\beta\alpha} \). To simplify notations, we set
\[
\| h(t) \| = \sum_{\alpha, \beta = 0}^3 \| h^{\alpha\beta}(t, \cdot) \|_{L^\infty}, \quad \| \partial h(t) \| = \sum_{\alpha, \beta = 0}^3 \| \partial h^{\alpha\beta}(t, \cdot) \|_{L^\infty}. \tag{3.2}
\]
In addition, $h^{\alpha\beta}$ is always assumed to satisfy the “admissible condition” for any smooth function $w$ with $\partial_\nu w|_{\mathbb{R}_+ \times \partial \mathcal{O}} = 0$

$$h^{\alpha\beta} \nu^\alpha \partial_\beta w = 0, \quad (t, x) \in \mathbb{R}_+ \times \partial \mathcal{O}. \quad (3.3)$$

Furthermore, we assume that $h^{\alpha\beta}$ satisfies for some suitably small $\delta > 0$,

$$\|h(t)\| \leq \frac{\delta}{1 + t}. \quad (3.4)$$

Define the energy forms $\{e_\alpha(u)\}$ associated with $\Box_h$ as follows

$$e_0(u) = |\partial u|^2 + 2t^{0\beta} \partial_\beta u - h^{\alpha\beta} \partial_\alpha u \partial_\beta u, \quad e_1(u) = -2\partial_0 u \partial_t u + 2h^{i\beta} \partial_0 u \partial_\beta u. \quad (3.5)$$

In addition, we define the following energy functionals for any nonnegative integers $\mu$ and $\nu$,

$$E_{\mu,\nu}(t) = \sum_{i \leq \mu, \ j \leq \nu} \int_\mathcal{O} e_0(L^i L^j u)(t, x) \, dx, \quad E_{\mu,\nu}(t) = \sum_{i \leq \mu, \ |\alpha| \leq \nu} \int_\mathcal{O} e_0(L^i Z^\alpha u)(t, x) \, dx. \quad (3.6)$$

Under assumption (3.4) and the smallness of $\delta > 0$ (for instance, $\delta < \frac{1}{11}$), $e_0(u)$ in (3.5) satisfies

$$1/2|\partial u|^2 < e_0(u) < 2|\partial u|^2. \quad (3.7)$$

### 3.1 Spatial energy estimates

We now establish some spatial energy estimates for operator $\Box_h$.

**Lemma 3.1.** Under the “admissible condition” (3.3), if $u$ is a smooth solution of (3.1) which vanishes for large $x$, then we have that for any nonnegative integers $\mu$ and $\nu$,

$$\partial_0 E_{\mu,\nu}^{1/2}(t) \lesssim \sum_{i \leq \mu, \ j \leq \nu} \|\Box_h (L^i L^j u)(t, \cdot)\| + \|h(t)\| E_{\mu,\nu}^{1/2}(t). \quad (3.8)$$

**Proof.** We only give the proof of (3.8) for $\mu, \nu = 0$ since the other cases for general $\mu, \nu$ can be done in the same way with the fact that $\partial_\nu L^i L^j u = 0$ on $\mathbb{R}_+ \times \partial \mathcal{O}$ for $0 \leq i \leq \mu$ and $0 \leq j \leq \nu$.

It follows from a direct computation that

$$2\Box_h u \cdot \partial_0 u = \partial_\alpha e_\alpha(u) - 2\partial_\alpha h^{\alpha\beta} \partial_0 u \partial_\beta u + \partial_0 h^{\alpha\beta} \partial_\alpha u \partial_\beta u.$$ Integrating this identity over $\mathcal{O}$ and using (3.7) yield

$$\partial_0 \mathcal{E}_{0,0}(t) \lesssim \|\Box_h u(t, \cdot)\| \|\partial_0 u(t, \cdot)\| + \|h(t)\| \|\partial_0 u(t, \cdot)\|^2 - \int_\mathcal{O} e_1(u) \nu^i \, d\sigma$$

$$\lesssim \|\Box_h u(t, \cdot)\| E_{0,0}^{1/2}(t) + \|h(t)\| E_{0,0}(t) - \int_\mathcal{O} e_1(u) \nu^i \, d\sigma. \quad (3.9)$$

Note that $\int_\mathcal{O} e_1(u) \nu^i \, d\sigma = 0$ holds due to the Neumann boundary condition $\partial_\nu u = 0$ on $\mathbb{R}_+ \times \partial \mathcal{O}$ and (3.3). Then estimate (3.8) comes from (3.9) directly. \hfill $\Box$
Let commutator $[O, P] = OP - PO$ stand for two differential operators $O$ and $P$. Direct computation yields
\[
|\Box h (L^i \partial_0^j u)| \leq |L^i \partial_0^{j} \Box h u| + |[L^i, \Box] \partial_0^{j} u| + |[L^i, h^\alpha \beta \partial_0^{j}] u| \tag{3.10}
\]
and
\[
|[L^i, \Box] \partial_0^{j} u| \lesssim \sum_{k \leq i-1} |L^k \partial_0^{j} \Box u| + x(|x| \leq 2) \sum_{k+|\alpha| \leq i+j, \ k \leq i-1} |L^k \partial^\alpha u|, \tag{3.11}
\]

here $x(|x| \leq 2)$ is the characteristic function of the domain $\{|x| \leq 2\}$. Combining (3.10)-(3.11) with (3.3) in Lemma 3.1 shows:

**Lemma 3.2.** Under the assumptions in Lemma 3.1 for any nonnegative integers $\mu, \nu$, one has
\[
\partial_0^2 \mathcal{E}_{\mu, \nu}^1(t) \lesssim \sum_{i \leq \mu, j \leq \nu} \|L^i \partial_0^j \Box h u(t, \cdot)\| + \|\partial h(t)\| \mathcal{E}_{\mu, \nu}^1(t)
\]
\[+ \sum_{i \leq \mu, j \leq \nu} \|[L^i, \partial_0^j] h^\alpha \beta \partial_0^{j} u(t, \cdot)\| + \sum_{i \leq \mu-1, j \leq \nu} \|L^i \partial_0^j \Box u(t, \cdot)\|
\]
\[+ \sum_{k+|\alpha| \leq \mu+\nu, k \leq \mu-1} \|L^k \partial^\alpha u(t, \cdot)\|_{L^2(|x| \leq 2)}. \tag{3.12}
\]

Next we establish a higher order energy estimate for the wave operator.

**Lemma 3.3.** For fixed integers $N_0$ and $\mu_0$, one has
\[
\sum_{|\alpha| \leq N_0} \|L^\mu \partial^\alpha u(t, \cdot)\| \lesssim \sum_{\mu + |\alpha| \leq N_0 + \mu_0} \|L^\mu \partial_0^\alpha u(t, \cdot)\| + \sum_{\mu + |\alpha| \leq N_0 + \mu_0 - 1} \|L^\mu \partial^\alpha \Box u(t, \cdot)\|. \tag{3.13}
\]

**Proof.** At first, it follows from (2.7) in Lemma 2.4 that
\[
\sum_{|\alpha| \leq N_0} \|\partial^\alpha u(t, \cdot)\| \lesssim \sum_{\beta \leq N_0} \|\partial_0^\beta u(t, \cdot)\| + \sum_{|\alpha| \leq N_0 - 1} \|\partial^\alpha \Box u(t, \cdot)\|. \tag{3.14}
\]
This shows (3.13) for $\mu_0 = 0$.

Next, we prove (3.13) for general $\mu_0$. Since $[\Box, L] = 2\Box$, with the help of (2.2) in Lemma 2.3 one has
\[
\sum_{|\alpha| \leq N_0} \|L^\mu \partial^\alpha u(t, \cdot)\|_{L^2(|x| \geq 2)} \lesssim \sum_{\mu + |\alpha| \leq N_0 + \mu_0} \|L^\mu \partial_0^\alpha u(t, \cdot)\| + \sum_{\mu + |\alpha| \leq N_0 + \mu_0 - 1} \|L^\mu \partial^\alpha \Box u(t, \cdot)\|. \tag{3.15}
\]
In addition, by (2.3) in Lemma 2.3, we arrive at

\[
\sum_{|\alpha| \leq N_0} \| L^{\mu} \partial^{\alpha} \partial u(t, \cdot) \|_{L^2(|x| \leq 2)} \leq \sum_{\mu + \beta \leq N_0 + \mu_0 \atop \mu \leq \mu_0} \| \partial^{\mu+\beta} \partial u(t, \cdot) \|_{L^2(|x| \leq 2)} + \sum_{\mu + \beta \leq N_0 + \mu_0 \atop \mu \leq \mu_0} \| \partial^{\beta} \Box u(t, \cdot) \|_{L^2(|x| \leq 4)}
\]

\[
\leq \sum_{\beta \leq N_0} \| L^{\mu} \partial^{\beta} \Box u(t, \cdot) \|_{L^2(|x| \leq 2)} + \sum_{\mu + \beta \leq N_0 + \mu_0 \atop \mu \leq \mu_0} \| \partial^{\mu} \partial^{\alpha} \partial u(t, \cdot) \|_{L^2(|x| \leq 4)} \]

Combining (3.16) with (3.14) and (3.15) yields (3.13) by induction method on \( \mu_0 \).

Proposition 3.4. Assume that \( \| \partial h(t) \| \leq \frac{\delta}{1+t} \) holds for small \( \delta > 0 \). In addition, suppose

\[
\sum_{\mu + \beta \leq N_0 + \mu_0 \atop \mu \leq \mu_0} \left( \| L^{\mu} \partial^{\beta} \Box h(t, \cdot) \| + \| [L^{\mu} \partial^{\beta} h, \partial^{\alpha} \partial] u(t, \cdot) \| \right) \leq \frac{\delta}{1+t} \sum_{\mu + \beta \leq N_0 + \mu_0 \atop \mu \leq \mu_0} \| L^{\mu} \partial^{\alpha} \partial u(t, \cdot) \| + H_{\mu_0, N_0}(t)
\]

(3.17)

for fixed numbers \( N_0 \) and \( \mu_0 \), and a positive function \( H_{\mu_0, N_0}(t) \). Then there exists a positive constant \( A \) such that

\[
\sum_{\nu + |\alpha| \leq N_0 + \mu_0 \atop \mu \leq \mu_0} \| L^{\mu} \partial^{\alpha} \partial u(t, \cdot) \| \leq \sum_{\mu + \alpha \leq N_0 + \mu_0 - 1 \atop \mu \leq \mu_0} \| L^{\mu} \partial^{\alpha} \Box u(t, \cdot) \| + (1 + t)^A \delta \mathcal{E}^{1/2}_{\mu, \nu}(0)
\]

\[
+ (1 + t)^A \int_0^t \sum_{\mu + |\alpha| \leq N_0 + \mu_0 - 1 \atop \mu \leq \mu_0 - 1} \| L^{\mu} \partial^{\alpha} \Box u(s, \cdot) \| ds + (1 + t)^A \delta \int_0^t H_{\mu_0, N_0}(s) ds
\]

\[
+ (1 + t)^A \delta \int_0^t \sum_{\mu + |\alpha| \leq N_0 + \mu_0 \atop \mu \leq \mu_0 - 1} \| L^{\mu} \partial^{\alpha} \partial u(s, \cdot) \|_{L^2(|x| \leq 2)} ds.
\]

(3.18)
Proof. It follows from (3.12) in Lemma 3.2 and the assumptions in Proposition 3.4 that

\[
\partial_0 \mathcal{E}_{\mu_0, N_0}^{1/2}(t) \leq \frac{A\delta}{1 + \epsilon} \mathcal{E}_{\mu_0, N_0}^{1/2}(t) + A H_{\mu_0, N_0}(t) + A \sum_{\mu + \beta \leq N_0 + \mu_0 - \nu \leq \mu_0 - 1} \| L^\mu \partial_0^\beta \Box u(t, \cdot) \|
\]

\[
+ A \sum_{\mu + |\alpha| \leq N_0 + \mu_0 \atop \nu \leq \mu_0} \| L^\mu \partial^\alpha \partial u(t, \cdot) \|_{L^2(|x| \leq 2)},
\]

(3.19)

where \( A > 0 \) is a generic constant. From (3.19), \( \mathcal{E}_{\mu_0, N_0}^{1/2} \) can be controlled by the right hand side of (3.18) via using Gronwall’s inequality.

On the other hand, it is derived from (3.13) in Lemma 3.3 and the definition of \( \mathcal{L} \) that

\[
\sum_{\mu + \beta \leq N_0 + \mu_0 \atop \nu \leq \mu_0} \| L^\mu \partial^\alpha \partial u(t, \cdot) \| \leq \sum_{\mu + |\alpha| \leq N_0 + \mu_0 \atop \nu \leq \mu_0} \| L^\mu \partial^\alpha \partial u(t, \cdot) \| \]

\[
\leq \sum_{\mu + |\alpha| \leq N_0 + \mu_0 \atop \nu \leq \mu_0} \| L^\mu \partial^\alpha \partial u(t, \cdot) \| \leq \sum_{\mu + |\alpha| \leq N_0 + \mu_0 \atop \nu \leq \mu_0} \| L^\mu \partial^\alpha \partial u(t, \cdot) \|. \quad \text{(3.20)}
\]

Meanwhile, it follows from (3.6) and (3.7) that

\[
\sum_{\mu + \beta \leq N_0 + \mu_0 \atop \nu \leq \mu_0} \| L^\mu \partial^\beta \partial \partial u(t, \cdot) \| \leq 2 \mathcal{E}_{\mu_0, N_0}^{1/2}(t).
\]

Combining this with (3.20) and the mentioned estimate for \( \mathcal{E}_{\mu_0, N_0}^{1/2} \) yields (3.18). \( \square \)

We now derive the estimate of \( E_{\mu, \nu} \) defined in (3.6).

Lemma 3.5. Suppose that \( \| \partial h(t) \| \leq \frac{\delta}{1 + t} \) holds for sufficiently small \( \delta > 0 \), then

\[
\partial_0 E_{\mu_0, N_0}(t) \leq \sum_{\mu + |\alpha| \leq N_0 + \mu_0 \atop \nu \leq \mu_0} \| \Box h L^\mu Z^\alpha u(t, \cdot) \| E_{\mu_0, N_0}^{1/2}
\]

\[
+ \| \partial h(t) \| E_{\mu_0, N_0} + \sum_{\mu + |\alpha| \leq N_0 + \mu_0 + 1 \atop \nu \leq \mu_0} \| L^\mu \partial^\alpha \partial u(t, \cdot) \|_{L^2(|x| \leq 2)}^2. \quad \text{(3.21)}
\]

Proof. By the analogous argument in Lemma 3.1 we have that

\[
\partial_0 E_{\mu_0, N_0}(t) \leq \sum_{\mu + |\alpha| \leq N_0 + \mu_0 \atop \nu \leq \mu_0} \| \Box h L^\mu Z^\alpha u(t, \cdot) \| E_{\mu_0, N_0}^{1/2}
\]

\[
+ \| \partial h(t) \| E_{\mu_0, N_0} + \sum_{\mu + |\alpha| \leq N_0 + \mu_0 \atop \nu \leq \mu_0} \int_{\partial D} |e_j(L^\mu Z^\alpha u) v^j| d\sigma. \quad \text{(3.22)}
\]
In addition, it follows from Sobolev trace theory that
\[
\sum_{\mu+|\alpha| \leq N_0 + \mu_0} \int_{\partial \Omega} |e_j(L^\mu Z^\alpha u)^\nu| \, d\sigma \lesssim \sum_{\mu+|\alpha| \leq N_0 + \mu_0} \|L^\mu \partial^\alpha u(t, \cdot\|)^2_{L^2(\partial \Omega)} \lesssim \sum_{\mu+|\alpha| \leq N_0 + \mu_0 + 1} \|L^\mu \partial^\alpha u(t, \cdot\|)^2_{L^2(|x| \leq 1)}.
\]

Substituting this into (3.22) yields (3.21).

**Lemma 3.6.** Suppose that \( \Box u = 0 \) for \( |x| > 4 \), \( \partial_\nu u = 0 \) on \( \mathbb{R}^4 \times \partial \Omega \), and \( u \equiv 0 \) for \( t \leq 0 \). Then
\[
\sum_{\mu+|\alpha| \leq N_0 + \mu_0} \|L^\mu \partial^\alpha u(t, \cdot\|)^2_{L^2(|x| \leq 2)} \lesssim \sum_{\mu+|\alpha| \leq N_0 + \mu_0 - 1} \|L^\mu \partial^\alpha \Box u(t, \cdot\|)^2_{L^2(|x| \leq 2)} + \int_0^t e^{-c/2(t-s)} \sum_{\mu+|\alpha| \leq N_0 + \mu_0} \|L^\mu \partial^\alpha \Box u(s, \cdot\|)^2_{L^2(|x| \leq 4)} \, ds.
\]  
(3.23)

**Proof.** It follows from (3.16) and the definition of \( L \) that
\[
\sum_{\mu+|\alpha| \leq N_0 + \mu_0} \|L^\mu \partial^\alpha u(t, \cdot\|)^2_{L^2(|x| \leq 2)} \lesssim \sum_{\mu+|\alpha| \leq N_0 + \mu_0 - 1} t^\mu \|L^\mu \partial^\alpha \Box u(t, \cdot\|)^2_{L^2(|x| \leq 2)} + \sum_{\mu+|\alpha| \leq N_0 + \mu_0 - 1} \|L^\mu \partial^\alpha \Box u(t, \cdot\|)^2_{L^2(|x| \leq 4)} \, ds.
\]  
(3.24)

Next we manage to control the first term in the right hand side of (3.24). By \( \partial_\nu \partial_0^{\mu+\beta} u = 0 \) on \( \mathbb{R}^4 \times \partial \Omega \), it follows from Lemma 2.5 that,
\[
\sum_{\mu+|\alpha| \leq N_0 + \mu_0} t^\mu \|\partial_0^{\mu+\beta} \partial u(t, \cdot\|)^2_{L^2(|x| \leq 2)} \lesssim \int_0^t e^{-c(t-s)} \|\partial_0^{\mu+\beta} \Box u(s, \cdot\|)^2_{L^2(|x| \leq 2)} \, ds
\]
\[
\lesssim \sum_{\mu+|\alpha| \leq N_0 + \mu_0} \left\{ \int_0^t e^{-c(t-s)} (t-s)^\mu \|\partial_0^{\mu+\beta} \Box u(s, \cdot\|)^2_{L^2(|x| \leq 2)} \, ds + \int_0^t e^{-c(t-s)} s^\mu \|\partial_0^{\mu+\beta} \Box u(s, \cdot\|)^2_{L^2(|x| \leq 2)} \, ds \right\}
\]
\[
\lesssim \sum_{\mu+|\alpha| \leq N_0 + \mu_0} \int_0^t e^{-c/2(t-s)} \|L^\mu \partial^\alpha \Box u(s, \cdot\|)^2_{L^2(|x| \leq 2)} \, ds.
\]

Combining this with (3.24) yields (3.23). \( \square \)
Lemma 3.7. Suppose $\partial^\nu u = 0$ on $\mathbb{R}_+ \times \partial\mathcal{O}$ and $u \equiv 0$ when $t \leq 0$. Then for fixed integers $\mu_0$ and $N_0$, we have

$$\sum_{\mu + |\alpha| \leq N_0 + \mu_0, \mu \leq \mu_0} \| L^\mu \partial^\alpha \partial u(t, \cdot) \|_{L^2(|x| \leq 2)}$$

$$\lesssim \sum_{\mu + |\alpha| \leq N_0 + \mu_0, \mu \leq \mu_0} \int_0^t e^{-\frac{\mu}{2}(t-s)} \| L^\mu \partial^\alpha u(s, \cdot) \|_{L^2(|x| \leq 4)} ds + \sum_{\mu + |\alpha| \leq N_0 + \mu_0 - 1, \mu \leq \mu_0} \| L^\mu \partial^\alpha \Box u(t, \cdot) \|_{L^2(|x| \leq 4)}$$

$$+ \int_0^t e^{-\frac{\mu}{2}(t-s)} \left( \int_0^s \| L^\mu \partial^\alpha \Box u(\tau, \cdot) \|_{L^2(\{x: |x| -(s-\tau) < 10\})} d\tau \right) ds$$

$$+ \sum_{\mu + |\alpha| \leq N_0 + \mu_0, \mu \leq \mu_0} \int_0^t \| L^\mu \partial^\alpha \Box u(s, \cdot) \|_{L^2(\{x: |x| -(t-s) < 10\})} ds.$$  \hspace{1cm} (3.25)

In addition, if $t > 2$,

$$\sum_{\mu + |\alpha| \leq N_0 + \mu_0, \mu \leq \mu_0} \int_0^t \| L^\mu \partial^\alpha u(s, \cdot) \|_{L^2(|x| \leq 2)} ds$$

$$\lesssim \sum_{\mu + |\alpha| \leq N_0 + \mu_0 + 1, \mu \leq \mu_0} \int_0^t \int_0^s \| L^\mu \partial^\alpha \Box u(\tau, \cdot) \|_{L^2(\{x: |x| -(s-\tau) < 10\})} d\tau ds.$$  \hspace{1cm} (3.26)

Proof. It suffices only to prove (3.25) since (3.26) directly comes from (3.25).

Assume that $u$ satisfies

$$\begin{cases}
\Box u = G(t, x), \quad (t, x) \in \mathbb{R}_+ \times \mathcal{O}, \\
\partial^\nu u = 0, \quad (t, x) \in \mathbb{R}_+ \times \partial\mathcal{O}, \\
u(t, x) \equiv 0, \quad t \leq 0.
\end{cases}$$

Let $u_i \ (i = 1, 2)$ satisfy

$$\begin{cases}
\Box u_i = (2 - i + (2i - 3)g(x/2))G(t, x), \quad (t, x) \in \mathbb{R}_+ \times \mathcal{O}, \\
\partial^\nu u_i = 0, \quad (t, x) \in \mathbb{R}_+ \times \partial\mathcal{O}, \\
u_i(t, x) \equiv 0, \quad t \leq 0.
\end{cases}$$

Then $u = u_1 + u_2$. It follows from Lemma 3.6 that (3.25) holds for $u_1$. Next we estimate $u_2$. For this purpose, we set $u_2 = w_0 + w_1$ where $w_0$ solves the following problem

$$\begin{cases}
\Box w_0 = \Box u_2, \quad |x| \geq 2; \\
0, \quad \text{otherwise},
\end{cases}$$  \hspace{1cm} (3.27)

$$w_0(t, x) \equiv 0, \quad t \leq 0.$$
In addition, set \( \hat{u} = (1 - \varphi(x/2))w_0 + w_1 \). Then \( \Box \hat{u} \) is supported in \( \{|x| \leq 4\} \) due to

\[
\Box \hat{u} = \nabla \varphi(x/2) \cdot \nabla w_0 + 2\Delta \varphi(x/2)w_0.
\]

Consequently, as in the treatment on \( u_1 \), by Lemma 3.6 and the fact that \( u_2 = \hat{u} \) when \( |x| \leq 2 \), one has that

\[
\sum_{\mu + |\alpha| \leq N_0 + \mu_0 \atop \nu \leq \mu_0} \| L^\mu \partial^\alpha \partial u_2(t, \cdot) \|_{L^2(|x| \leq 2)}
\]

\[
= \sum_{\mu + |\alpha| \leq N_0 + \mu_0 \atop \nu \leq \mu_0} \| L^\mu \partial^\alpha \hat{u}(t, \cdot) \|_{L^2(|x| \leq 2)}
\]

\[
\lesssim \sum_{\mu + |\alpha| \leq N_0 + \mu_0 \atop \nu \leq \mu_0} \int_0^t e^{-\frac{T}{2}(t-s)} \| L^\mu \partial^\alpha \Box \hat{u}(s, \cdot) \| ds + \sum_{\mu + |\alpha| \leq N_0 + \mu_0-1 \atop \nu \leq \mu_0} \| L^\mu \partial^\alpha \Box \hat{u}(t, \cdot) \|
\]

\[
\lesssim \sum_{\mu + |\alpha| \leq N_0 + \mu_0+1 \atop \nu \leq \mu_0} \int_0^t e^{-\frac{T}{2}(t-s)} \| L^\mu \partial^\alpha w_0(s, \cdot) \|_{L^2(|x| \leq 4)} ds + \sum_{\mu + |\alpha| \leq N_0 + \mu_0 \atop \nu \leq \mu_0} \| L^\mu \partial^\alpha w_0(t, \cdot) \|_{L^2(|x| \leq 4)}.
\]

(3.28)

Since \( w_0 \) satisfies the boundaryless problem (3.27), one has that for any \( \mu \) and \( \alpha \),

\[
\| L^\mu \partial^\alpha w_0(t, \cdot) \|_{L^2(|x| \leq 4)} \lesssim \sum_{\nu + |\beta| \leq \mu + |\alpha| \atop \nu \leq \mu} \int_0^t \| L^\mu \partial^\beta \Box w_0(\tau, \cdot) \|_{L^2(|x|:|x|-(T-\tau)|<10)} d\tau
\]

\[
\lesssim \sum_{\nu + |\beta| \leq \mu + |\alpha| \atop \nu \leq \mu} \int_0^t \| L^\mu \partial^\beta \Box u(\tau, \cdot) \|_{L^2(|x|:|x|-(T-\tau)|<10)} d\tau.
\]

Combining this with (3.28) and the estimate of \( u_1 \) yields (3.25). And then we complete the proof of Lemma 3.7

\[ \square \]

3.2 Time-space energy estimates

In this subsection, some key weighted \( L^2 \) time-space energy estimates, which can be thought as the modified version of Keel-Smith-Sogge estimate in [22], are established for the solution \( u \) of (3.1). Denote by \( S_T = [0, T] \times O \) for any \( T > 0 \).

**Proposition 3.8.** Suppose that the smooth function \( u \) admits \( \partial^\nu u = 0 \) on \( \mathbb{R}_+ \times \partial O \) and \( u \equiv 0 \) when \( t \leq 0 \). Then for fix integers \( N_0 \) and \( \mu_0 \), we have

\[
(\ln(2 + T))^{-1/2} \sum_{\mu + |\alpha| \leq N_0 + \mu_0 \atop \nu \leq \mu_0} \| \langle x \rangle^{-1/2} L^\mu \partial^\alpha u \|_{L^2(S_T)}
\]

\[
\lesssim \int_0^T \sum_{\mu + |\alpha| \leq N_0 + \mu_0+1 \atop \nu \leq \mu_0} \| \Box L^\mu \partial^\alpha u(s, \cdot) \| ds + \sum_{\mu + |\alpha| \leq N_0 + \mu_0 \atop \nu \leq \mu_0} \| \Box L^\mu \partial^\alpha u \|_{L^2(S_T)}.
\]

(3.29)
Additionally,

\[
(\ln(2 + T))^{-1/2} \sum_{\mu + |\alpha| \leq N_0 + \mu_0} \| \langle x \rangle^{-1/2} L^\mu Z^\alpha \partial u \|_{L^2(\Omega_T)} \]

\[
\leq \int_0^T \sum_{\mu + |\alpha| \leq N_0 + \mu_0 + 1} \| \Box L^\mu Z^\alpha u(s, \cdot) \|_{L^2(\Omega_T)} ds + \sum_{\mu + |\alpha| \leq N_0 + \mu_0} \| \Box L^\mu Z^\alpha u \|_{L^2(\Omega_T)}.
\]

(3.30)

In order to prove Proposition 3.8, we shall establish the next two lemmas in advance. The first one can be looked as a simple version of Proposition 3.8 and the second one is the local-in-space \(L^2\)–time-space energy estimates.

**Lemma 3.9.** If the smooth function \(u\) admits \(\partial_\nu u = 0\) on \(\mathbb{R}_+ \times \partial \Omega\) and \(u \equiv 0\) when \(t \leq 0\), then for any nonnegative integer \(\beta\),

\[
(\ln(2 + T))^{-1/2} \sum_{\mu + |\alpha| \leq N_0 + \mu_0} \| \langle x \rangle^{-1/2} L^\mu Z^\alpha \partial \partial_\beta u \|_{L^2(\Omega_T)} + \| \Box \partial_\beta u \|_{L^2([0, T] \times \{|x| \leq 4\})} \lesssim \int_0^T \| \Box \partial_\beta u(s, \cdot) \| ds.
\]

(3.31)

**Proof.** We only need to prove (3.31) for \(\beta = 0\) since other cases can be proved in the same way due to \(\partial_\nu \partial_\beta u = 0\) on \(\mathbb{R}_+ \times \partial \Omega\) for \(0 \leq i \leq \beta\). It follows from the energy estimate in Lemma 3.1 that

\[
\| \partial u(t, \cdot) \| \leq 2 \int_0^t \| \Box u(s, \cdot) \| ds.
\]

This immediately implies

\[
(1 + T)^{-1/2} \| \partial u \|_{L^2([0, T] \times \{|x| \leq 4\})} \lesssim \int_0^T \| \Box u(s, \cdot) \| ds.
\]

(3.32)

We continue to use the notation of \(u_i\) \((i = 1, 2)\) defined in the proof of Lemma 3.7 With respect to \(u_1\), by using (2.8) in Lemma 2.5 one has

\[
\| \partial u_1 \|_{L^2([0, T] \times \{|x| \leq 4\})} \lesssim \int_0^t e^{-c(t-s)} \| \Box u(s, \cdot) \| ds \|_{L^2([0, T])} \]

\[
\lesssim \int_0^T \| \Box u(s, \cdot) \| ds,
\]

(3.33)

where the last inequality comes from the Young inequality.

When it comes to \(u_2\), based on the estimate (3.28) in Lemma 3.7 and (2.19) in Lemma 2.7 one has

\[
\| \partial u_2 \|_{L^2([0, T] \times \{|x| \leq 4\})} \lesssim \int_0^T \| \Box u(s, \cdot) \| ds.
\]

Combining this with (3.33) yields

\[
\| \partial u \|_{L^2([0, T] \times \{|x| \leq 4\})} \lesssim \int_0^T \| \Box u(s, \cdot) \| ds.
\]

(3.34)

Based on (3.32) and (3.34), by the scaling method as in the proof of Lemma 2.3 in [22], we can get (3.31) for \(\beta = 0\) and then the proof of Lemma 3.9 is completed.
Lemma 3.10. Under the assumptions in Proposition 3.8, we have

\[
\sum_{\mu + |\alpha| \leq N_0 + \mu_0} \| L^\mu \partial^\alpha \partial u \|_{L^2([0,T] \times \{|x| \leq 2\})} \leq \sum_{\mu + |\alpha| \leq N_0 + \mu_0 - 1} \| \Box L^\mu \partial^\alpha u \|_{L^2(S_T)} + \int_0^T \sum_{\mu + |\alpha| \leq N_0 + \mu_0} \| \Box L^\mu u(s, \cdot) \| \, ds. \tag{3.35}
\]

Proof. We use some notations in the proof of Lemma 3.7. The estimate of \(u_1\) in (3.35) comes from (3.23) by integrating the variable \(t\) from 0 to \(T\) on both sides of (3.23) and by applying Young inequality.

For \(u_2\), one has

\[
\sum_{\mu + |\alpha| \leq N_0 + \mu_0} \| L^\mu \partial^\alpha \partial u \|_{L^2([0,T] \times \{|x| \leq 2\})} = \sum_{\mu + |\alpha| \leq N_0 + \mu_0} \| L^\mu \partial^\alpha \partial \hat{u} \|_{L^2([0,T] \times \{|x| \leq 2\})} \tag{3.36}
\]

Here the first inequality in (3.36) comes from the application of Lemma 3.6 and Young’s inequality. Thus, it follows from (3.36) and estimate (2.19) in Lemma 2.7 to \(w_0\) that (3.35) is proved. \( \square \)

We now start the proof of Proposition 3.8.

Proof of Proposition 3.8: Similar to (3.32) and (3.34) in Lemma 3.9, we have that for \(0 \leq j \leq N_0\),

\[
(1 + t)^{-1/2} \| \partial_0^j u \|_{L^2(S_t)} \leq \int_0^t \| \Box \partial_0^j u(s, \cdot) \|_2 \, ds
\]

and

\[
\| \partial_0^j u \|_{L^2([0,t] \times \{|x| \leq 4\})} \leq \int_0^t \| \Box \partial_0^j u(s, \cdot) \|_2 \, ds.
\]

In addition, due to the elliptic estimate in Lemma 2.3, we have

\[
(1 + t)^{-1/2} \sum_{|\alpha| \leq N_0} \| \partial^\alpha u \|_{L^2(S_t)} \leq (1 + t)^{-1/2} \sum_{|\alpha| \leq N_0 - 1} \| \Box \partial^\alpha u \|_{L^2(S_t)} + \sum_{|\alpha| \leq N_0} \int_0^t \| \Box \partial^\alpha u(s, \cdot) \|_2 \, ds \tag{3.37}
\]
and
\[ \sum_{|\alpha| \leq N_0} \| \partial^\alpha u \|_{L^2([0,t] \times \{|x| \leq 2\})} \]

\[ \lesssim \sum_{|\alpha| \leq N_0 - 1} \| \Box \partial^\alpha u \|_{L^2([0,t] \times \{|x| \leq 4\})} + \sum_{|\alpha| \leq N_0} \int_0^t \| \Box \partial^\alpha u(s, \cdot) \|_2 ds. \] (3.38)

Together with the scaling techniques in [22], it follows from (3.37) and (3.38) that
\[ (\ln(2 + T))^{-1/2} \sum_{|\alpha| \leq N_0} \| \langle x \rangle \|^{1/2}_2 \partial^\alpha u \|_{L^2(S_T)} \]

\[ \lesssim \sum_{|\alpha| \leq N_0 - 1} \| \Box \partial^\alpha u \|_{L^2(S_T)} + \sum_{|\alpha| \leq N_0} \int_0^T \| \Box \partial^\alpha u(s, \cdot) \| ds. \] (3.39)

On the other hand, it follows from Sobolev trace theorem and Lemma 3.5 with \( h^\beta \gamma = 0 \) that for fixed \( \alpha \in \mathbb{N}_0 \),
\[ \| \partial L^{\mu_0} Z^\alpha u(t, \cdot) \|_2 \lesssim \int_0^t \| \Box L^{\mu_0} Z^\alpha u(s, \cdot) \| \cdot \| \partial L^{\mu_0} Z^\alpha u(s, \cdot) \| ds \]

\[ + \sum_{|\beta| \leq 1} \int_0^t \| L^{\mu_0} \partial^{\alpha + \beta} u(s, \cdot) \|_{L^2(|x| \leq 2)}^2 ds. \] (3.40)

For any fixed \( T > 0 \), there exists a maximum \( t_0 \in [0, T] \) such that for \( 0 \leq t \leq t_0 \),
\[ \int_0^t \| \Box L^{\mu_0} Z^\alpha u(s, \cdot) \| \cdot \| \partial L^{\mu_0} Z^\alpha u(s, \cdot) \| ds \leq \sum_{|\beta| \leq 1} \int_0^T \| \partial^\beta \partial L^{\mu_0} Z^\alpha u(s, \cdot) \|_{L^2(|x| \leq 2)}^2 ds. \]

Combining this with (3.40) yields that for \( 0 \leq t \leq t_0 \),
\[ \| \partial L^{\mu_0} Z^\alpha u(t, \cdot) \|_2 \lesssim \sum_{|\beta| \leq 1} \int_0^T \| \partial^\beta \partial L^{\mu_0} Z^\alpha u(s, \cdot) \|_{L^2(|x| \leq 2)}^2 ds, \] (3.41)

and for \( t_0 \leq t \leq T \),
\[ \| \partial L^{\mu_0} Z^\alpha u(t, \cdot) \|_2 \lesssim \int_0^t \| \Box L^{\mu_0} Z^\alpha u(s, \cdot) \| \cdot \| \partial L^{\mu_0} Z^\alpha u(s, \cdot) \| ds. \] (3.42)

If there exists a \( t^* \in [0, t_0] \) such that
\[ \| \partial L^{\mu_0} Z^\alpha u(t^*, \cdot) \| = \sup_{0 < t < T} \| \partial L^{\mu_0} Z^\alpha u(t, \cdot) \|, \]
then it follows from (3.41) that for \( 0 \leq t \leq T \),
\[ \| \partial L^{\mu_0} Z^\alpha u(t, \cdot) \|_2 \lesssim \sum_{|\beta| \leq 1} \int_0^T \| \partial^\beta \partial L^{\mu_0} Z^\alpha u(s, \cdot) \|_{L^2(|x| \leq 2)}^2 ds. \] (3.43)
If there exists a \( t^* \in [t_0, T] \) such that
\[
\| \partial L^\mu Z^\alpha u(t^*, \cdot) \| = \sup_{0 < t < T} \| \partial L^\mu Z^\alpha u(t, \cdot) \|
\]
then it follows from (3.42) and the definition of \( t^* \) that for \( 0 \leq t \leq T \),
\[
\| \partial L^\mu Z^\alpha u(t, \cdot) \| \leq \| \partial L^\mu Z^\alpha u(t^*, \cdot) \|
\]
\[
\lesssim \int_0^{t^*} \| \Box L^\mu Z^\alpha u(s, \cdot) \| ds \leq \int_0^T \| \Box L^\mu Z^\alpha u(s, \cdot) \| ds.
\] (3.44)

Finally, it follows from (3.43) and (3.44) that
\[
\| \partial L^\mu Z^\alpha u(t, \cdot) \|^2 \lesssim \left( \int_0^T \| \Box L^\mu Z^\alpha u(s, \cdot) \| ds \right)^2 + \sum_{\nu \leq \mu_0} \| L^\nu \partial^\beta u(s, \cdot) \|_{L^2(|x| \leq 2)}^2 ds.
\]

Simultaneously, one has that
\[
(1 + T)^{-1/2} \| \partial L^\mu Z^\alpha u \|_{L^2(S_T)}
\]
\[
\lesssim \sum_{\nu \leq \mu_0} \| L^\nu \partial^\beta u(s, \cdot) \|_{L^2([0, T] \times \{|x| \leq 2\})} + \int_0^T \| \Box L^\mu Z^\alpha u(s, \cdot) \| ds.
\]

Combining this with (3.39), Lemma 3.10 and the scaling method in [22] yields Proposition 3.8. □

4 Pointwise decay estimate

In this section, we derive the pointwise decay estimate of the smooth solution \( w \) to the following problem
\[
\left\{ \begin{array}{ll}
\Box w = F(t, x), & (t, x) \in \mathbb{R}_+ \times \mathcal{O}, \\
\partial_\nu w = 0, & (t, x) \in \mathbb{R}_+ \times \partial \mathcal{O}, \\
w(t, x) \equiv 0, & t \leq 0.
\end{array} \right.
\] (4.1)

**Theorem 4.1.** Suppose that \( w \) is a smooth solution of problem (4.1). Then for integers \( \mu \) and \( \alpha \),
one has that
\[
(1 + t + |x|)|L^\mu Z^\alpha w(t, x)|
\]
\[
\lesssim \int_0^t \int_{\mathcal{O}} \sum_{\nu + |\beta| \leq |\alpha| + \mu + 5} \| L^\nu Z^\beta F(s, y) \|_{L^2(|y| \leq 2)} dy ds
\]
\[
+ \int_0^t \sum_{\nu + |\beta| \leq |\alpha| + \mu + 2} \| L^\nu \partial^\beta F(s, \cdot) \|_{L^2(|x| \leq 2)} ds.
\] (4.2)
Proof. At first, we consider the following inhomogeneous wave equation

\[
\begin{aligned}
\Box w_0 &= G_0, \quad (t, x) \in \mathbb{R}_+ \times \mathbb{R}^3, \\
w_0(t, x) &\equiv 0, \quad t \leq 0.
\end{aligned}
\]  

(4.3)

It follows from Proposition 2.1 and Lemma 2.2 in [23] (one can also see Theorem 3.1 in [32]) that

\[
(1 + t + |x|)|w_0(t, x)| \lesssim \int_0^t \int_{\mathbb{R}^3} \sum_{\nu + |\beta| \leq 3 \atop \nu \leq 1} |L^\nu Z^\beta G_0(s, y)| \frac{dyds}{|y|} 
\]  

(4.4)

and

\[
|x||w_0(t, x)| \lesssim \int_0^t \int_{|x|-(t-s)}^{|x|+(t-s)} \sup_{|y| \in \mathbb{S}^2} |G_0(s, r\omega)| rdrds.
\]  

(4.5)

Set \( w_0(t, x) = g(x)L^\mu Z^\alpha w(t, x) \). Then

\[
\begin{aligned}
\Box w_0 &= g(x)\Box L^\mu Z^\alpha w + \hat{G}_0(t, x), \\
w_0(t, x) &\equiv 0, \quad t \leq 0,
\end{aligned}
\]

where \( \hat{G}_0(t, x) = -2\nabla g(x) \cdot \nabla L^\mu Z^\alpha w - (\Delta g)(x)L^\mu Z^\alpha w \). We decompose \( w_0 \) as \( w_0 = \hat{w}_0 + (w_0 - \hat{w}_0) \) with \( \hat{w}_0 \) satisfying the following inhomogeneous equation

\[
\begin{aligned}
\Box \hat{w}_0 &= g(x)\Box L^\mu Z^\alpha w = g(x) \sum_{\nu \leq \mu} C_{\nu\mu} L^\nu Z^\alpha F, \\
\hat{w}_0(t, x) &\equiv 0, \quad t \leq 0.
\end{aligned}
\]

By (4.3) and (4.4), we have that

\[
(1 + t + |x|)|\hat{w}_0(t, x)| \lesssim \int_0^t \int_{\mathbb{R}^3} \sum_{\nu + |\beta| \leq \mu + |\alpha| + 3 \atop \nu \leq \mu + 1} |L^\nu Z^\beta F(s, y)| \frac{dyds}{|y|}.
\]  

(4.6)

In addition, due to the definition of \( \hat{w}_0 \), it also follows from (4.5) that

\[
|x||(w_0 - \hat{w}_0)(t, x)| \lesssim \int_0^t \int_{|x|-(t-s)}^{|x|+(t-s)} \sup_{\omega \in \mathbb{S}^2} |\hat{G}_0(s, r\omega)| rdrds.
\]  

(4.7)

Note that \( \hat{G}_0(t, y) \equiv 0 \) for \(|y| \leq 1 \) and \(|y| \geq 2 \). Then the time integrand in (4.7) is not zero only for \(-2 \leq |x|-(t-s) \leq 2 \) (or equivalently, \((t-|x|)-2 \leq s \leq (t-|x|) + 2 \)). This, together with (4.7) and the definition of \( \hat{G}_0 \), yields

\[
|x||(w_0 - \hat{w}_0)(t, x)| \lesssim \frac{1}{1 + |t-|x||} \sup_{|y| \leq 2} \frac{1}{(t-|x|)-2 \leq s \leq (t-|x|) + 2} (1 + s) \sum_{|\beta| \leq 1} |\partial^\beta L^\mu Z^\alpha w|(s, y).
\]
Combining this with (4.6) shows

\[(1 + t + |x|)|L^u Z^\alpha w(t, x)| \lesssim \int_0^t \int_0^l \sum_{\nu + |\beta| \leq |\alpha| + 3} |L^u \partial_\beta F(s, y)| \frac{dy ds}{|y|}
+ \sup_{0 \leq s \leq l} (1 + s) \sum_{\nu + |\beta| \leq |\alpha| + 1} |L^u \partial_\beta w|(s, y).\] (4.8)

Next we manage to control the last term in the right hand side of (4.8). To this end, it suffices to estimate the term \(\sup_{|x| \leq 2} |w(t, x)|\) since the other cases can be treated in the similar way with the help of Lemma 2.4 and Lemma 2.5. To this end, with the decomposition of \(w\) similar to that of \(v\) in the proof of Lemma 3.7, we only need to consider two cases \(F(t, x) = 0\) for \(|x| \geq 4\) and \(F(t, x) = 0\) for \(|x| \leq 2\).

When \(F(t, x) = 0\) for \(|x| \geq 4\), one has,

\[t |w(t, x)| \leq \sum_{j = 0, 1} \int_0^t |(s\partial_0)^j w(s, x)| ds.

This, together with Sobolev imbedding lemma, (2.8) in Lemma 2.5 and Remark 2.1 yields

\[t \sup_{|x| \leq 2} |w(t, x)| \lesssim \sum_{0 \leq j \leq 1; |\sigma| \leq 2} \int_0^t s^j \|\partial_0^l \nabla^\sigma w(s, x)\|_{L^2(|x| \leq 2)} ds
\]
\[\lesssim \sum_{l \leq 1; j \leq 1} \int_0^t s^j \int_0^s e^{-c(s-\tau)} \|\partial_0^{l+j} F(\tau, \cdot)\| d\tau ds + \sum_{l \leq 1} \int_0^t s^j \|\partial_0^l F(s, \cdot)\| ds
\]
\[\lesssim \sum_{l \leq 1; j \leq 1} \int_0^t s^j \int_0^s e^{-c(s-\tau)} (s-\tau)^l \|\partial_0^{l+j} F(\tau, \cdot)\| d\tau ds + \sum_{l \leq 1} \int_0^t s^j \|\partial_0^l F(s, \cdot)\| ds
\]
\[\quad + \sum_{l \leq 1; j \leq 1} \int_0^t s^j e^{-c(t-s)} \tau^l \|\partial_0^{l+j} F(\tau, \cdot)\| d\tau ds
\]
\[\lesssim \sum_{\mu + |\alpha| \leq 2; \mu \leq 1} \int_0^t \|L^u Z^\alpha F(s, \cdot)\| ds,\] (4.9)

where the last inequality comes from the Young inequality and the definition of \(L\) and \(Z\). Combining (4.9) with (4.8) yields (4.2) when \(F(t, x) = 0\) if \(|x| \geq 4\).

When \(F(t, x) = 0\) if \(|x| \leq 2\), as in the proof of Lemma 3.7 we set \(w = w_0 + w_2\) with \(w_0\) defined by (4.3) and the corresponding \(G_0\) replaced by \(F\). In addition, we set \(\tilde{w}_0 = (1 - \varphi(x/2))w_0 + w_2\), with \(\Box \tilde{w}_0\) supported in \(|x| \leq 4\) due to \(\Box \tilde{w} = \nabla \varphi(x/2) \cdot \nabla w_0 + 2\Delta \varphi(x/2)w_0\). Then \(w = \tilde{w}\) when \(|x| \leq 2\). Following the proof for the case of \(F(t, x) = 0\) when \(|x| \geq 4\), we
arrive at
\[ t \sup_{|x| \leq 2} |L^\nu \partial^2 w(t, x)| = t \sup_{|x| \leq 2} |L^\nu \partial^2 \hat{w}(t, x)| \leq \int_0^t \sum_{l + |\sigma| \leq \nu + |\beta| + 3} \|L^l \partial^{\sigma} \square \hat{w}(s, \cdot)\| ds \]
(4.10)

On the other hand, by (4.5) and Lemma 2.1
\[ \sup_{2 \leq |x| \leq 4} |L^l \partial^{\sigma} w_0(s, x)| \leq \sum_{l' + |\sigma'| \leq l + |\sigma| + 1} \int_0^s \int_{|s - \tau - |y|| \leq 4} |L^{l'} Z^{\sigma'} F(\tau, y)| \frac{dyd\tau}{|y|}. \]
(4.11)

Note that \( \{(\tau, y) : 0 \leq \tau \leq s, |s - \tau - |y|| \leq 4\} \cap \{(\tau, y) : 0 \leq \tau \leq s', |s' - \tau - |y|| \leq 4\} = \emptyset \) when \( |s - s'| \geq 10 \). Then substituting (4.11) into (4.10) leads to
\[ \sup_{|y| \leq 2} (1 + t) \sum_{\nu + |\beta| \leq \mu + |\alpha| + 1} |L^{\nu} \partial^\beta w(s, y)| \approx \int_0^t \int_{\nu + |\beta| \leq \mu + |\alpha| + 5} \frac{|L^{\nu} Z^{\beta} F(s, y)| \, dyds}{y}. \]

Combining this with (4.8) and (4.9) shows (4.2). \( \square \)

5 Continuity induction argument and proof of Theorem 1.1

In this section, based on Sect. 2-Sect. 4 and the local existence of problem (1.3) shown in Sect. 6 below, we start to prove Theorem 1.1 by the continuity induction argument.

It follows from Theorem 6.2 and Remark 6.1 in Sect. 6 that the solution \( u \) of problem (1.3) uniquely exists for \( 0 \leq t \leq 4 \) and
\[ \sup_{0 < t \leq 4} \sum_{|\alpha| \leq 69} \| (x)^\alpha \partial^\alpha u(t, \cdot)\| \approx \varepsilon. \]
(5.1)

In addition, as shown in Sect. 5 of [32], the solution of problem (1.3) exists in the region \( \{(t, x) : \)}
\(0 \leq 2t \leq |x|\) and satisfies
\[
\sup_{t \geq 0} \sum_{|\alpha| \leq 69} \| \langle x \rangle^\alpha \partial^\alpha u(t, \cdot) \|_{L^2(\{x: |x| \geq 2t\})} \lesssim \varepsilon. \tag{5.2}
\]
Combining (5.2) with (5.1) yields that
\[
\sup_{0 < t < +\infty} \sum_{|\alpha| \leq 69} \| \langle x \rangle^\alpha \partial^\alpha u(t, \cdot) \|_{L^2(\{x: |x| \geq 2t\})} \lesssim \varepsilon, \tag{5.3}
\]
where \(D_0 = \{(t, x): 0 \leq 2t \leq |x|, x \in \mathcal{O}\} \cap \{(t, x): 0 \leq t \leq 4, x \in \mathcal{O}\} \).

To prove the global existence theorem, we will do some preparations based on (5.3) first. Set
\[
u_0(t, x) = \zeta(t, x) u(t, x), \tag{5.4}
\]
where \(\zeta(t, x) = \eta(t V(x))\). Choose the functions \(\eta \in C^\infty(\mathbb{R})\) and \(V(x) \in C^\infty(\mathcal{O})\) such that
\[
\eta(s) = 1 \text{ for } s \leq 1/8; \quad \eta(s) = 0 \text{ for } s \geq 1/4,
\]
\[
0 < V(x) \leq 1; \quad V(x) = 1 \text{ for } |x| \leq 4; \quad V(x) = |x|^{-1} \text{ for } |x| \geq 8.
\]
Direct computation yields
\[
\Box u_0 = \zeta \mathcal{N}(\partial u, \partial^2 u) + [\Box, \zeta] u.
\]
It follows from (5.3)-(5.4) and Lemma 2.1 that there exists an absolute constant \(\kappa_0\) such that
\[
(1 + t + |x|) \sum_{\mu + |\alpha| \leq 67} |L^\mu Z^\alpha u_0(t, x)| + \sum_{\mu + |\alpha| + |\beta| \leq 69} \| \langle t + r \rangle^{|eta|} L^\mu Z^\alpha \partial^\beta u_0(t, \cdot) \| \leq \kappa_0 \varepsilon. \tag{5.5}
\]
Let \(u = u_0 + w\) with \(w\) satisfying
\[
\begin{aligned}
\Box w &= (1 - \zeta) \mathcal{N}(\partial u, \partial^2 u) - [\Box, \zeta] u, & (t, x) \in \mathbb{R}_+ \times \mathcal{O}, \\
\partial_\nu w &= 0, & (t, x) \in \mathbb{R}_+ \times \partial \mathcal{O}, \\
w(t, x) &\equiv 0, & t \leq 0.
\end{aligned} \tag{5.6}
\]
To prove Theorem 1.1 by the continuity induction argument, we require to establish the weighted estimate of \(w\).

First, let \(v\) be the solution of the following problem
\[
\begin{aligned}
\Box v &= -[\Box, \zeta] u, & (t, x) \in \mathbb{R}_+ \times \mathcal{O}, \\
\partial_\nu v &= 0, & (t, x) \in \mathbb{R}_+ \times \partial \mathcal{O}, \\
v(t, x) &\equiv 0, & t \leq 0.
\end{aligned} \tag{5.7}
\]

\[^3\text{If the initial date \((u_0, u_1)\) in (1.8) is compactly supported, then due to the weak Huygens principle, the solution } u \text{ in this domain is identically zero.}\]
By (5.3) and Theorem 4.1, we can derive that there exists an absolute constant \( \kappa_1 > 0 \) such that

\[
(1 + t + |x|) \sum_{\mu + |\alpha| \leq 60} |L^\mu Z^\alpha v(t, x)| \leq \kappa_1 \varepsilon. \tag{5.8}
\]

Indeed, by Theorem 4.1

\[
(1 + t + |x|) \sum_{\mu + |\alpha| \leq 65} |L^\mu Z^\alpha(\square, \zeta)u(s, x)| \leq 60|L^\mu Z^\alpha v(t, x)| \leq \kappa_1 \varepsilon.
\]

With (5.3)-(5.4) and the pseudo homogeneity of \( \zeta \), we arrive at

\[
I_0 \lesssim \varepsilon + \int_0^t \int_{\{x \in \Omega: |x| \geq 8s \}} \left( \frac{1}{|x|^2} |L^\mu Z^\alpha u| + \frac{1}{|x|} |L^\mu Z^\alpha \partial u| \right) \, dx \, ds
\]

\[
\lesssim \varepsilon \int_0^t \left( \int_{\{x \in \Omega: |x| \geq 4s \}} \frac{1}{|x|^b} \, dx \right)^{1/2} \, ds
\]

\[
\lesssim \varepsilon, \quad II_0 \lesssim \varepsilon,
\]

here the last estimate for \( II_0 \) comes from the property of function \( \zeta \).

We now start to set up the continuity induction argument. Suppose that

\[
(1 + t + r) \sum_{|\alpha| \leq 24} (|Z^\alpha w(t, x)| + |Z^\alpha \partial w(t, x)|) \leq 4\kappa_1 \varepsilon, \tag{5.9}
\]

where \( \kappa_1 \) is given in (5.8). To prove Theorem 1.1 by the continuity induction argument, we shall prove that for small \( \varepsilon > 0 \),

\[
(1 + t + r) \sum_{|\alpha| \leq 24} (|Z^\alpha w(t, x)| + |Z^\alpha \partial w(t, x)|) \leq 2\kappa_1 \varepsilon. \tag{5.10}
\]

The proof process will be divided into the following three parts.
Part I. Under assumption (5.9), the following estimates hold:

\[
(1 + t + r) \sum_{|\alpha| + \rho \leq 32 \atop \mu \leq 2} |L^\mu Z^\alpha w(t, x)| \leq B_1 \varepsilon (1 + t)^{1/5} \ln(2 + t), \tag{5.11}
\]

\[
\sum_{|\alpha| \leq 68} \| \partial^\alpha w(t, \cdot) \| \leq B_2 \varepsilon (1 + t)^{1/20}, \tag{5.12}
\]

\[
\sum_{|\alpha| + \rho \leq 47 \atop \mu \leq 3} \| L^\mu Z^\alpha \partial w(t, \cdot) \| \leq B_3 \varepsilon (1 + t)^{1/10}, \tag{5.13}
\]

and

\[
\sum_{|\alpha| + \rho \leq 39 \atop \mu \leq 3} \| \langle x \rangle^{-1/2} L^\mu Z^\alpha \partial w \|_{L^2(S_t)} \leq B_4 \varepsilon (1 + t)^{1/10} (\ln(2 + t))^{1/2}. \tag{5.14}
\]

By (1.5), we can rewrite the equation in (1.3) as

\[
\Box h u = S(\partial u), \tag{5.15}
\]

where \( h^{\alpha \beta}(\partial u) = -Q^{\alpha \beta}(\partial u) \). Since \( u = u_0 + w \), it follows from (5.5), (5.9) and (3.2) that

\[
\sum_{|\alpha| \leq 24} \| \Box h \partial_{\alpha} u \| \leq \varepsilon / (1 + t) \tag{5.16}
\]

This, together with (3.8) in Lemma 3.1, yields that for \( 0 \leq M \leq 68 \),

\[
\partial_0 \varepsilon^{1/2}_{0, M}(t) \lesssim \sum_{0 \leq j \leq M} \| \Box h \partial_j^0 u(t, \cdot) \| + \frac{\varepsilon}{1 + t} \varepsilon^{1/2}_{0, M}(t). \tag{5.17}
\]

Note that

\[
\sum_{j \leq M} \| \Box h \partial_j^0 u \|
\lesssim \sum_{j \leq M} \left( \| \Box h \partial_j^0 u \| + \| \partial_j^0 S(\partial u) \| \right)
\lesssim (\sum_{j \leq M} \| \partial_j^0 \partial u \| + \sum_{j \leq M-1} \| \partial_j^0 \partial^2 u \|) \sum_{|\alpha| \leq 24} \| \partial^\alpha \partial u \| + \sum_{|\alpha| < M-24} \| \partial^\alpha \partial u \| \sum_{24 < |\beta| \leq M/2} \| \partial^\beta \partial u \|
\lesssim \frac{\varepsilon}{1 + t} \left( \sum_{j \leq M} \| \partial_j^0 \partial u \| + \sum_{j \leq M-1} \| \partial_j^0 \partial^2 u \| \right) + \sum_{|\alpha| < M-24} \| \partial^\alpha \partial u \| \sum_{24 < |\beta| \leq M/2} \| \partial^\beta \partial u \|,
\]

here the cubic terms in \( N(\partial u, \partial^2 u) \) are neglected since (5.5) and (5.9) imply \( |\partial^\alpha \partial u| \lesssim \varepsilon / (1 + t) \) for \( |\alpha| \leq 24 \). Furthermore, by using Lemma 2.3 and repeating the above argument, we have that
for \(0 < \varepsilon \leq \varepsilon_0\),
\[
\sum_{j \leq M-1} \| \partial_j^2 u(t, \cdot) \|_L^{1/2} \\
\lesssim \sum_{j \leq M} \| \partial_j^2 u(t, \cdot) \| + \sum_{j \leq M-1} \| \partial_j \Box u(t, \cdot) \| \\
\lesssim \sum_{j \leq M} \| \partial_j^2 u(t, \cdot) \| + \frac{\varepsilon}{1 + t} \sum_{j \leq M-1} \| \partial_j^2 u(t, \cdot) \| + \sum_{|\alpha| < M-24, |\beta| \leq M/2} \| \partial^\alpha u(t, \cdot) \partial^\beta u(t, \cdot) \|. 
\] (5.19)

In addition, for small \(\varepsilon > 0\), it follows from (5.16)-(5.19) and (3.7) that
\[
\partial_0 \mathcal{E}_{0,M}^{1/2}(t) \lesssim \frac{\varepsilon}{1 + t} \mathcal{E}_{0,M}^{1/2}(t) + \sum_{|\alpha| < M-24, |\beta| \leq M/2} \| \partial^\alpha u(t, \cdot) \partial^\beta u(t, \cdot) \|. 
\] (5.20)

If \(M = 24\), the last term in (5.20) does not appear. Then by Gronwall’s inequality and \(\mathcal{E}_{0,M}^{1/2}(0) \lesssim \varepsilon\) due to (5.1), one has that
\[
\sum_{j \leq 24} \| \partial_j^2 u(t, \cdot) \| \leq 2\varepsilon_{24}^{1/2}(t) \lesssim \varepsilon(1 + t)^{C\varepsilon}. 
\] (5.21)

Together with (5.19), elliptic regularity estimate (2.7) in Lemma 2.4 and the similar argument of (5.18) for \(\Box u\), (5.21) yields
\[
\sum_{|\alpha| \leq 24} \| \partial^\alpha u(t, \cdot) \| \lesssim \varepsilon(1 + t)^{C\varepsilon}. 
\] (5.22)

If \(24 < M \leq 68\), we shall deal with the last term in (5.20). It follows from Lemma 2.1 that
\[
\sum_{|\alpha| \leq M-24, |\beta| \leq M/2} \| (\partial^\alpha u \partial^\beta u)(t, \cdot) \| \lesssim \sum_{|\alpha| = \max(M-22,2+M/2)} \| (x)^{-1/2} \sigma \partial u(t, \cdot) \|^2. 
\]

This, together with (5.1), (5.20) and Gronwall’s inequality, yields
\[
\mathcal{E}_{0,M}^{1/2}(t) \lesssim (1 + t)^{C\varepsilon} \left( \varepsilon + \sum_{|\alpha| \leq \max(M-22,2+M/2)} \| (x)^{-1/2} \sigma \partial u \|_{L^2(S_t)} \right). 
\] (5.23)

To treat \(\mathcal{E}_{0,M}(t)\) better and finish the proof in Part I, we require to establish the following Proposition.

**Proposition 5.1.** For given nonnegative integer \(\mu_0 \leq 3\), we define the integer \(M \leq 68 - 8\mu_0\) in the following three inequalities respectively. If
\[
\sum_{|\alpha| \leq M-3} \| (x)^{-1/2} L^\mu \sigma \partial u \|_{L^2(S_t)} + \sum_{|\alpha| \leq M-4} \| L^\mu \sigma \partial u(t, \cdot) \| + \sum_{|\alpha| \leq M-6} \| (x)^{-1/2} L^\mu \sigma \partial u \|_{L^2(S_t)} \\
\lesssim \varepsilon(1 + t)^{C\varepsilon + \sigma} 
\] (5.24)
holds with some $\sigma > 0$ for $\mu_0 = 0, 1, 2$, then there is a constant $C' > 0$ such that

\[
\sum_{\mu + |\alpha| \leq M - 2} \| \langle x \rangle^{-1/2} L^\mu \partial^\alpha u \|_{L^2(S_t)} + \sum_{\mu + |\alpha| \leq M - 3} \| L^\mu Z^\alpha \partial u(t, \cdot) \|_{L^2(S_t)} + \sum_{\mu + |\alpha| \leq M - 5} \| \langle x \rangle^{-1/2} L^\mu \partial^\alpha u \|_{L^2(S_t)} \lesssim \varepsilon (1 + t)^{C'\varepsilon + C'\sigma}, \quad \mu_0 = 0, 1, 2, 3,
\]

and

\[
\sum_{\mu + |\alpha| \leq M} \| L^\mu \partial^\alpha \partial u(t, \cdot) \| \lesssim \varepsilon (1 + t)^{C'\varepsilon + C'\sigma}, \quad \mu_0 = 0, 1, 2, 3.
\]

We shall postpone the proof of Proposition 5.1 in the subsequent Part II. Now we give some illustrations for this Proposition. When $\mu_0 = 0$ in (5.24), starting from (5.22), by an induction argument on $M$, (5.25) and (5.26) will stand for $\mu_0 = 0, 1$ respectively. Other left cases can be also obtained by induction argument both on $\mu_0$ and $M$.

Based on Proposition 5.1 and the fact that $u = w + u_0$ with $u_0$ satisfying (5.5), (5.12) comes from (5.26) for the case $\mu_0 = 0$ and $C'\varepsilon + C'\sigma = 1/20$; (5.13) and (5.14) are derived from (5.25) for the case $\mu_0 = 3$ and $C'\varepsilon + C'\sigma = 1/10$. In addition, (5.11) follows from Theorem 4.1, (5.5), (5.8) and (5.14) via a direct verification.

**Part II. The proof of Proposition 5.1**

It suffices to prove (5.25) and (5.26) for $\mu_0 = 0$ since the other cases can be treated in the same way. The proof is divided into three steps.

**Step 1. Proof of (5.25) for $\mu_0 = 0$**

Since $u = w + u_0$, by (5.5) and (3.29) in Proposition 3.8 we have

\[
(\ln(2 + t))^{-1/2} \sum_{|\alpha| \leq M - 2} \| \langle x \rangle^{-1/2} \partial^\alpha u \|_{L^2(S_t)} \lesssim \varepsilon + (\ln(2 + t))^{-1/2} \sum_{|\alpha| \leq M - 2} \| \langle x \rangle^{-1/2} \partial^\alpha w \|_{L^2(S_t)}
\]

\[
\lesssim \varepsilon + \sum_{|\alpha| \leq M - 1} \int_0^t \| \partial^\alpha \Box w \| ds + \sum_{|\alpha| \leq M - 2} \| \partial^\alpha \Box w \|_{L^2(S_t)}
\]

\[
\lesssim \varepsilon + \sum_{|\alpha| \leq M - 1} \int_0^t \| \partial^\alpha \Box u(s, \cdot) \| ds + \sum_{|\alpha| \leq M - 2} \| \partial^\alpha \Box u \|_{L^2(S_t)}.
\]

If $M \leq 24$, it follows from (5.5), (5.9) and equation (5.15) that

\[
\sum_{|\alpha| \leq 23} \| \partial^\alpha \Box u \| \lesssim \sum_{|\alpha| \leq 24} \| \partial^\alpha \Box u \| \lesssim \frac{\varepsilon}{1 + t} \sum_{|\alpha| \leq 24} \| \partial^\alpha \partial u \|.
\]
Combining this with (5.22) and (5.27) yields
\[
(\ln(2 + t))^{-1/2} \sum_{|\alpha| \leq M - 2} \| \langle x \rangle^{-1/2} \partial^{\alpha} u \|_{L^2(S_t)} \lesssim \varepsilon (1 + t)^{C \varepsilon + \sigma}.
\] (5.28)

If $24 < M \leq 68$, by repeating the argument for (5.23) and applying (5.24) for $\mu_0 = 0$, we then arrive at
\[
(\ln(2 + t))^{-1/2} \sum_{|\alpha| \leq M - 2} \| \langle x \rangle^{-1/2} \partial^{\alpha} u \|_{L^2(S_t)} \lesssim \varepsilon (1 + t)^{2C \varepsilon + 2\sigma} + \sum_{|\alpha| \leq \max(M - 22, 2 + M/2)} \| \langle x \rangle^{-1/2} Z^{\alpha} \partial u \|_{L^2(S_t)}^2
\]
\[
+ \sup_{0 \leq s \leq t} \left( \sum_{|\alpha| \leq M - 6} \| Z^{\alpha} \partial u(s, \cdot) \| \right) \sum_{|\alpha| \leq \max(M - 22, 2 + M/2)} \| \langle x \rangle^{-1/2} Z^{\alpha} \partial u \|_{L^2(S_t)}
\]
\[
\lesssim \varepsilon (1 + t)^{2C \varepsilon + 2\sigma}.
\]

Combining this with (5.28) yields for $M \leq 68$
\[
\sum_{|\alpha| \leq M - 2} \| \langle x \rangle^{-1/2} \partial^{\alpha} u \|_{L^2(S_t)} \lesssim \varepsilon (1 + t)^{2C \varepsilon + 2\sigma} \ln(2 + t).
\] (5.29)

This derives the estimate of the first term in the left hand side of (5.25).

Next, we estimate the second term in the left hand side of (5.25). For $E_{\mu, \nu}(t)$ defined by (3.6), with the help of (5.5) and (5.9) which can be used to deal with the cubic terms in $N(\partial u, \partial^{2} u)$, we have
\[
\sum_{|\alpha| \leq M - 3} \| \Box_h Z^{\alpha} u(t, \cdot) \|
\]
\[
\lesssim \sum_{|\alpha| + |\beta| \leq M - 3} \| Z^{\alpha} \partial u(t, \cdot) Z^{\beta} \partial u(t, \cdot) \| + \sum_{|\alpha| + |\beta| \leq M - 3 \atop |\alpha| \geq 1} \| Z^{\alpha} \partial u(t, \cdot) Z^{\beta} \partial^{2} u(t, \cdot) \|
\]
\[
\lesssim \sum_{|\alpha| \leq M - 3 \atop |\beta| \leq 24} \| Z^{\alpha} \partial u(t, \cdot) \| \| Z^{\beta} \partial u(t, \cdot) \|_{\infty} + \sum_{|\alpha| \leq M - 27; |\beta| \leq M - 27} \| Z^{\alpha} \partial u(t, \cdot) Z^{\beta} \partial u(t, \cdot) \|
\] (5.30)

here we point out that the last inequality comes from (5.5), (5.9) and Lemma 2.1 Substituting (5.30) into (3.21) derives
\[
\partial_0 E_{0, M - 3}(t) \lesssim \frac{\varepsilon}{1 + t} E_{0, M - 3}(t) + \sum_{|\alpha| \leq M - 25} \| \langle x \rangle^{-1/2} Z^{\alpha} \partial u(t, \cdot) \|^2 E_{0, M - 3}(t)
\]
\[
+ \sum_{|\alpha| \leq M - 2} \| \langle x \rangle^{-1/2} \partial^{\alpha} u(t, \cdot) \|^2.
\]
Then it follows from Gronwall’s inequality, (5.1) and (5.29) that

\[
\sum_{|\alpha| \leq M-3} \| Z^\alpha \partial u(t, \cdot) \|^2 \lesssim E_{0,M-3}(t)
\]

\[\lesssim (1 + t)^{C\varepsilon} \left( \varepsilon^2 + \sum_{|\alpha| \leq M-25} \| \langle x \rangle^{-1/2} Z^\alpha \partial u(t, \cdot) \|^2_{L^2(S_t)} \right) \sup_{0 < s < t} E_{0,M-3}^{1/2}(s) \]

\[+ \sum_{|\alpha| \leq M-2} \| \langle x \rangle^{-1/2} \partial^\alpha \partial u(t, \cdot) \|^2_{L^2(S_t)} \]

\[\lesssim \varepsilon (1 + t)^{C\varepsilon + C\sigma}. \]  

(5.31)

Here, the last inequality comes from (5.24) for \( \nu = 0 \). Analogously, the estimate on the third term in (5.25) comes from (3.30), (5.31) and (5.24) for \( \mu_0 = 0 \).

**Step 2. Proof of (5.26) for \( \mu_0 = 0 \)**

It derives from (5.23) and (5.25) for \( \mu_0 = 0 \) that for arbitrarily \( \sigma > 0 \),

\[ E_{0,M}^{1/2}(t) \lesssim \varepsilon (1 + t)^{C\varepsilon + \sigma}. \]  

(5.32)

In addition, based on (5.25) for \( \mu_0 = 0 \) and (5.32), by Lemma 2.3 with the similar analysis as (5.18), one obtains

\[ \sum_{|\alpha| \leq M} \| \partial^\alpha \partial u(t, \cdot) \| \lesssim (1 + t)^{C\varepsilon + \sigma}. \]

This shows (5.26) for \( \mu_0 = 0 \).

**Step 3. Proof of (5.25) and (5.26) for \( \mu_0 = 1 \)**

At first, we establish a suitable version of (5.17) for \( N_0 + \mu_0 \leq 60 \) and \( \mu_0 = 1 \). It is noticed that for \( M \leq 60 \),

\[
\sum_{\mu + \alpha \leq M, \mu \leq 1} \left( | \mathcal{L}^\mu \partial_0^\alpha \Box h u | + | [ \mathcal{L}^\mu \partial_0^\alpha, h^{\alpha\beta} \partial_0^{2\beta} ] u | \right)
\]

\[\lesssim \left( \sum_{|\alpha| \leq M-1} | \mathcal{L} \partial_0^\alpha \partial u | + \sum_{|\alpha| \leq M-2} | \mathcal{L} \partial_0^\alpha \partial^2 u | \right) \sum_{|\beta| \leq 24} | \partial^\beta \partial u |
\]

\[+ \sum_{|\alpha| \leq M-25} | \mathcal{L} \partial^\alpha \partial u | \sum_{|\beta| \leq M} | \partial^\beta \partial u | + \sum_{|\alpha| \leq M} | \partial^\alpha \partial u | \sum_{|\beta| \leq 24} | \partial^\beta \partial u |.
\]
Combining this with (5.5), (5.9), Lemma 2.1 and Lemma 2.3 yields that for $M \leq 60$,

$$
\sum_{\mu + |\alpha| \leq M} \left( \| L \partial_{\alpha}^\mu \square h u(t, \cdot) \| + \| L \partial_{\alpha}^\mu h^\alpha \partial_{\alpha}^2 \right) u(t, \cdot) \| \right) 
\leq \frac{\varepsilon}{1 + t} \sum_{\mu + |\alpha| \leq M} \| L \partial_{\alpha}^\mu u(t, \cdot) \| + \sum_{|\alpha| \leq \max(M, 2 + M/2)} \| x \|^{-1/2} Z^\alpha \partial u(t, \cdot) \|^2 
+ \sum_{|\alpha| \leq M - 25} \| x \|^{-1/2} L \partial^\alpha \partial u(t, \cdot) \| \sum_{|\alpha| \leq 34} \| x \|^{-1/2} Z^\alpha \partial u(t, \cdot) \|.
$$

Based on this, for small $\varepsilon > 0$, (3.17) holds with $\delta = C \varepsilon$ and

$$
H_{1, M-1}(t) = \sum_{|\alpha| \leq M - 25} \| x \|^{-1/2} L \partial^\alpha \partial u(t, \cdot) \|^2 + \sum_{|\alpha| \leq 62} \| x \|^{-1/2} Z^\alpha \partial u(t, \cdot) \|^2.
$$

Since $E_{\mu, \nu}(0) \lesssim \varepsilon$ for $\mu + \nu \leq 68$ by (5.1), it follows from (3.18) and (5.25) for $\mu_0 = 0$ that for $M \leq 60$,

$$
\sum_{\mu + |\alpha| \leq M} \| L^\mu \partial^\alpha \partial u(t, \cdot) \| 
\lesssim \varepsilon (1 + t)^{C \varepsilon + \sigma} + (1 + t)^{C \varepsilon} \sum_{|\alpha| \leq M - 25} \| x \|^{-1/2} L \partial^\alpha \partial u(t, \cdot) \|_{L^2(S_t)} \|^2 
+ (1 + t)^{C \varepsilon} \int_0^t \sum_{|\alpha| \leq M + 1} \| \partial^\alpha \partial u(s, \cdot) \|_{L^2(|x| \leq 1)} ds.
$$

By (3.26), one has that

$$
\int_0^t \sum_{|\alpha| \leq M + 1} \| \partial^\alpha \partial w(s, \cdot) \|_{L^2(|x| \leq 2)} ds \lesssim \sum_{|\alpha| \leq M + 2} \int_0^t \int_0^s \| \partial^\alpha \square w(\tau, \cdot) \|_{L^2(|x| = (s - \tau)| < 10 \cap O)} d\tau ds.
$$

In addition, it follows from (5.5) that

$$
\sum_{|\alpha| \leq M + 3} \int_0^t \| \partial^\alpha \partial u(s, \cdot) \|_{L^2(|x| \leq 2)} ds 
\lesssim \varepsilon \ln(2 + t) + \sum_{|\alpha| \leq M + 2} \int_0^t \int_0^s \| \partial^\alpha \square u(\tau, \cdot) \|_{L^2(|x| = (s - \tau)| < 10 \cap O)} d\tau ds.
$$

Note that

$$
\sum_{|\alpha| \leq M + 2} |\partial^\alpha \square u| \lesssim \sum_{|\alpha| \leq M + 3} |\partial^\alpha \partial u| \sum_{|\alpha| \leq 1 + M/2} |\partial^\alpha \partial u|.
$$
This, together with Lemma 2.1 and the fact of \( M \leq 60 \), yields

\[
\sum_{|\alpha| \leq M+2} \| \partial^\alpha \Box u(\tau, \cdot) \|_{L^2((x:|x|-(s-\tau)|<10)\cap \mathcal{O})} \lesssim \sum_{|\alpha| \leq 63} \| \langle x \rangle^{-1/2} Z^\alpha \partial u \|_{L^2((x:|x|-(s-\tau)|<20)\cap \mathcal{O})}.
\]  

(5.36)

Thus for \( M \leq 60 \), by (5.25) in Lemma 5.1 and (5.35)-(5.36), we have

\[
\sum_{|\alpha| \leq M+2} \int_0^t \| \partial^\alpha \partial u(s, \cdot) \|_{L^2(|x|\leq 1)} ds \lesssim \varepsilon \ln(2 + t) + \sum_{|\alpha| \leq 63} \| \langle x \rangle^{-1/2} Z^\alpha \partial u \|_{L^2(S_t)}^2 \lesssim \varepsilon (1 + t)^{C\varepsilon + \sigma}.
\]

(5.37)

Meanwhile, by (5.33) and (5.34)-(5.36), we arrive at

\[
\sum_{\mu + |\alpha| \leq M+1} \| L^\mu \partial^\alpha \partial w(t, \cdot) \| \lesssim \varepsilon (1 + t)^{C\varepsilon + \sigma} + (1 + t)^{C\varepsilon} \sum_{|\alpha| \leq M-25} \| \langle x \rangle^{-1/2} L\partial^\alpha \partial u \|_{L^2(S_t)}^2.
\]

(5.38)

This gives the desired bounds for \( M \leq 24 \).

If we utilize (5.29) with \( \mu_0 = 1 \) and \( N_0 + \mu_0 = 60 \), then by analogous proof of Lemma 5.1 when \( M = 68 \) is replaced by \( M = 60 \) and \( u \) is replaced by \( Lu \) respectively, we can get

\[
\sum_{\mu + |\alpha| \leq 58 \atop \mu \leq 1} \| \langle x \rangle^{-1/2} L^\mu \partial^\alpha \partial w \|_{L^2(S_t)} + \sum_{\mu + |\alpha| \leq 57 \atop \mu \leq 1} \| L^\mu Z^\alpha \partial w(t, \cdot) \| \\
+ \sum_{\mu + |\alpha| \leq 55 \atop \mu \leq 1} \| \langle x \rangle^{-1/2} L^\mu Z^\alpha \partial w \|_{L^2(S_t)} \\
\lesssim \varepsilon (1 + t)^{C\varepsilon + 2C\sigma}.
\]

This is just only (5.25) of \( \mu_0 = 1 \). Consequently, it follows from (5.37) and (5.38) that (5.26) stands for \( \mu_0 = 1 \).

**Part III. Proof of (5.10)**

By Theorem 4.1 and (5.6)-(5.8), in order to prove (5.10), it suffices to show

\[
I + II \lesssim \varepsilon^2,
\]

(5.39)

where

\[
I = \int_0^t \int_{\mathcal{O}} \sum_{\nu + |\beta| \leq 29 \atop \nu \leq 1} |L^\nu Z^\beta N(\partial u, \partial^2 u)(s, y)| \frac{dy ds}{|y|},
\]

\[
II = \int_0^t \sum_{\nu + |\beta| \leq 26 \atop \nu \leq 1} \| L^\nu \partial^\beta N(\partial u, \partial^2 u)(s, \cdot) \|_{L^2(|x|\leq 2)} ds.
\]
By (1.5), we write
\[ N(\partial u, \partial^2 u) = S^{\alpha\beta} \partial_\alpha \partial_\beta u + Q^{\alpha\beta}_\mu \partial_\mu \partial_{\alpha\beta} u + R(\partial u, \partial^2 u), \tag{5.40} \]
where \( R(\partial u, \partial^2 u) \) is the cubic term and linear in \( \partial^2 u \). Making use of Lemma 2.6, one has
\[
\sum_{\nu + |\beta| \leq 29} \frac{1}{|y|} \sum_{\mu + |\alpha| \leq 31} |L^\mu Z^\alpha \partial \partial_\gamma u| \sum_{\nu + |\beta| \leq 29} |L^\nu Z^\beta \partial_\alpha u| \]
\[
+ \frac{\langle t - r \rangle}{\langle t + r \rangle} \sum_{\nu + |\alpha| \leq 29} |L^\nu Z^\alpha \partial u| \sum_{\nu + |\alpha| \leq 29} |L^\nu Z^\alpha \partial^2 u|
\]
\[
= I_1 + I_2. \tag{5.41} \]

By (5.11) and (5.14) with (5.5), for \( 0 < \delta < 1/10 \),
\[
\int_0^t \int_\Omega I_1 \frac{dyds}{|y|} \leq C(\delta) \varepsilon \int_0^t \sum_{\mu + |\alpha| \leq 32} \| \langle \cdot \rangle^{-1/2} L^\mu Z^\alpha \partial u(s, \cdot) \| \langle s \rangle^{-4/5+\delta} ds
\]
\[
=: C(\delta) \varepsilon I_{11}, \tag{5.42} \]
where the first inequality comes from the Young inequality together with (5.14) and (5.5). Direct computation yields
\[
I_{11}^2 \lesssim (t)^{-2/5} \sum_{\mu + |\alpha| \leq 32} \| \langle \cdot \rangle L^\mu Z^\alpha \partial u(s, \cdot) \|_{L^2(S_t)}^2 + \int_0^t \sum_{\mu + |\alpha| \leq 32} \langle s \rangle^{-7/5} \| \langle \cdot \rangle^{-1/2} L^\mu Z^\alpha \partial u \|_{L^2(S_t)}^2 ds
\]
\[
\lesssim \varepsilon^2. \tag{5.43} \]
Substituting this into (5.42) yields that
\[
\int_0^t \int_\Omega I_1 \frac{dyds}{|y|} \lesssim \varepsilon^2. \tag{5.44} \]
In addition, we have that from the proof of Lemma A.2,
\[
\begin{align*}
\int_0^t \int_0^t \sum_{\frac{t}{2} < t \leq R} & \sum_{\mu+|\alpha| \leq 30} \|L^\mu Z^\alpha \partial u(s, \cdot)\| + \sum_{\mu+|\alpha| \leq 30} \| (t+r) \sum_{\mu+|\alpha| \leq 30} \|L^\mu Z^\alpha \partial u(s, \cdot)\| \\
\times & \sum_{\mu+|\alpha| \leq 30} \| \langle y \rangle^{-1} L^\mu Z^\alpha \partial u(s, \cdot)\| ds \\
+ & \int_0^t \sum_{R=2^k < t/2} \sum_{\mu+|\alpha| \leq 30} \| \langle y \rangle^{-1} \sum_{\mu+|\alpha| \leq 30} \|L^\mu Z^\alpha \partial u(s, \cdot)\| ds
\end{align*}
\]
\[\times \sum_{\mu+|\alpha| \leq 30} \| \langle y \rangle^{-1} L^\mu Z^\alpha \partial u(s, \cdot)\|_{L^2(R/2 \leq |x| \leq R)}
\]
\[= I_{21} + I_{22}.
\]
Similar to the estimate for \( I_1 \), it follows from (5.5), (5.11) and (5.14) that
\[I_{22} \lesssim \varepsilon \int_0^t \langle s \rangle^{-4/5} \sum_{\mu+|\alpha| \leq 30} \| \langle y \rangle^{-1} L^\mu Z^\alpha \partial u(s, \cdot)\| ds
\]
\[\lesssim \varepsilon \sum_{\mu+|\alpha| \leq 30} \| \langle s \rangle^{-7/25} \langle y \rangle^{-1} L^\mu Z^\alpha \partial u(s, y)\|_{L^2(S_t)}
\]
\[\lesssim \varepsilon^2,
\]
here the last inequality is derived as for the estimate in (5.43).

In the similar way, it follows from (5.5), (5.11) and (5.13)-(5.14) that
\[I_{21} \lesssim \varepsilon \int_0^t \langle s \rangle^{-1+1/10} (1 + \ln(2 + s) \langle s \rangle^{1/5}) \sum_{\mu+|\alpha| \leq 30} \| \langle y \rangle^{-1} L^\mu Z^\alpha \partial u(s, \cdot)\| ds
\]
\[\lesssim \varepsilon^2
\]
holds by applying the fact that
\[(s + r) \sum_{\mu+|\alpha| \leq 30} \|L^\mu Z^\alpha \partial u\| \lesssim (s + r) \sum_{\mu+|\alpha| \leq 30} \|L^\mu Z^\alpha \partial u\|^2
\]
\[\lesssim \varepsilon \ln(2 + s)(1 + s)^{1/5} \sum_{\mu+|\alpha| \leq 30} \|L^\mu Z^\alpha \partial u\|.\]
Based on Theorem 4.1, (5.5) and (5.11)-(5.14), it is clear that the cubic term \( R(\partial u, \partial^2 u) \) in (5.40) admits the following estimates
\[
\int_0^t \int_\Omega \sum_{\mu+|\alpha| \leq 30} |L^\mu Z^\alpha R(\partial u, \partial^2 u)|(s,y) \frac{dy ds}{|y|} \lesssim \varepsilon^2.
\]
Combining this with (5.40)-(5.46) yields that I satisfies estimate (5.39). We now deal with II in (5.39). It follows from direction verification and (5.11) that
\[
II \lesssim \varepsilon \int_0^t \langle s \rangle^{-4/5} \ln(2 + s) \sum_{\mu+|\alpha| \leq 31} \|L^\mu Z^\alpha \partial u(s, \cdot)\|_{L^2(|y| \leq 2)} ds \lesssim \varepsilon^2.
\]
This, together with the estimate of I, shows that (5.10) can be derived by (5.11)-(5.14). Thus the proof of Theorem 1.1 is completed by the continuity induction argument together with the local existence of problem (1.3) in Sect.6 below.

6 Local existence of problem (1.3)

In this section, we establish the local existence of solution to general n-dimensional problem (1.3) for \( n \geq 2 \) under “admissible condition” (1.7) and the compatible conditions of the initial-boundary values. In addition, we assume \( \Omega \) is the exterior domain of n-dimensional compact convex domain \( K \) with smooth boundary.

Using the notation \( J_k u = \{ \nabla^\alpha u : 1 \leq |\alpha| \leq k \} \), problem (1.3) can be rewritten as
\[
\begin{cases}
\Box u = Q^{\alpha\beta}(\partial_0 u, J_1 u)\partial^{2\alpha\beta} u + S(\partial_0 u, J_1 u), & (t, x) \in \mathbb{R}_+ \times \Omega, \\
\partial_\nu u = 0, & (t, x) \in \mathbb{R}_+ \times \partial \Omega, \\
(u, \partial_t u)(0, x) = \varepsilon(u_0, u_1)(x), & x \in \Omega.
\end{cases}
\]
(6.1)

In addition, it is assumed that for some fixed positive constant \( M \) and integer \( s > 6 + 3n/2 \),
\[
\|u_0\|_{H^{s+1}} + \|u_1\|_{H^s} \leq M.
\]
(6.2)

6.1 Description of compatible conditions

Due to the smallness of solution \( u \) and the form of \( Q^{\alpha\beta}(\partial_0 u, J_1 u) \) in (1.5), without loss of generality, it is assumed that
\[
Q^{00} = 0, \quad \sum_{\alpha,\beta = 0}^n |Q^{\alpha\beta}| \leq 1/2.
\]
(6.3)

In this situation, the equation in (6.1) has the form
\[
\partial^2_0 u = F(J_1 \partial_0 u, J_2 u)
\]
for certain function $\mathcal{F}$ smooth in its arguments. Set $\psi_0 = \varepsilon u_0$, $\psi_1 = \varepsilon \psi_1$ and $\psi_2 = \mathcal{F}(J_2 u_0, J_1 u_1)$. As shown in Sect.9 of [21], for $k \in \mathbb{N}$, there exists a compatible function sequence $\{\psi_k\}$ such that the smooth solution $u$ to problem (6.1) satisfies
\[
\partial_0^k u(0, x) = \psi_k(J_k u_0, J_{k-1} u_1).
\]
(6.4)

Then the compatible conditions to problem (6.1) can be stated as:

**Definition 6.1.** Under assumption (6.3), the compatible conditions for problem (6.1) are called to be of $s$–order if $\partial_\nu \psi_j$ vanishes on $\mathbb{R}_+ \times \partial \mathcal{O}$ for all $0 \leq j \leq s - 1$.

It is well known that the compatible conditions are necessary to obtain the local existence of smooth solutions to the initial-boundary value problem (6.1). The following result is helpful to choose the iteration scheme for establishing the local existence of (6.1).

**Lemma 6.1. (See Lemma 9.1 and Lemma 9.3 in [21])** Under assumption (6.2) for $s > 6 + 3n/2$ and the compatible conditions of $s$–order, let $\{\psi_k(J_k u_0, J_{k-1} u_1)\}$ be the compatible functions for problem (6.1) introduced in (6.4), then one has

(A) $\psi_k(J_k u_0, J_{k-1} u_1) \in H^{s+1-k}(\mathcal{O})$ for $0 \leq k \leq s + 1$ and

\[
\sum_{0 \leq k \leq s+1} \|\psi_k(J_k u_0, J_{k-1} u_1)\|_{H^{s+1-k}} \lesssim \varepsilon (\|u_0\|_{H^{s+1}} + \|u_1\|_{H^{s+1}}).
\]

(B) Suppose that $v(t, x)$ is a function such that for some $T > 0$ and $0 \leq j \leq s + 1$,

\[
\partial_0^j v \in C([0, T); H^{s+1-j}(\mathcal{O})],
\]

and for $0 \leq k \leq s + 1$,

\[
\partial_0^k v(0, \cdot) = \psi_k(J_k u_0, J_{k-1} u_1), \quad \partial_\nu v = 0 \text{ on } \mathbb{R}_+ \times \partial \mathcal{O}.
\]

Let $\bar{\psi}_j$ be the compatible function of $j$–order for the problem

\[
\begin{cases}
\Box u = \mathcal{Q}^{\alpha\beta} (\partial_0 v, J_1 v) \partial_{\alpha\beta} u + S(\partial_0 v, J_1 v), & (t, x) \in \mathbb{R}_+ \times \mathcal{O}, \\
\partial_\nu u = 0, & (t, x) \in \mathbb{R}_+ \times \partial \mathcal{O}, \\
u(0, x) = u_0, \quad \partial_\nu u(0, x) = u_1, & x \in \mathcal{O}.
\end{cases}
\]

(6.5)

Then for $0 \leq k \leq s + 1$,

\[
\bar{\psi}_k = \psi_k(J_k u_0, J_{k-1} u_1).
\]

### 6.2 Local existence of smooth solutions

**Theorem 6.2.** For problem (6.1) with the initial data $(u_0, u_1)$ satisfying (6.2), if both the admissible condition (1.7) and the compatibility conditions of order $s + 1$ are satisfied, then there exists a constant $\varepsilon_0 > 0$ and a constant $T^* > 0$ depending on $s$ and $\varepsilon_0$ such that when $\varepsilon < \varepsilon_0$, there exists a solution $u$ to problem (6.1) on $[0, T^*] \times \mathcal{O}$, which satisfies

\[
\sup_{0 \leq t \leq T^*} \sum_{0 \leq j \leq s + 1} \|\partial_0^j u(t, \cdot)\|_{H^{s+1-j}} \lesssim \varepsilon (\|u_0\|_{H^{s+1}} + \|u_1\|_{H^{s+1}}).
\]

(6.6)
To prove Theorem 6.2 based on the existence result of linear Neumann-wave problem (see [19] and [38]), we shall establish some estimates for the linear problem (6.5). For $T > 0$, define

$$M_{s+1}(t, v) = \sum_{|\alpha| \leq s+1} \|\partial^\alpha v(t, \cdot)\|, \quad M_{s+1}[v] = \sup_{0 \leq t \leq T} M_{s+1}(v, t)$$

and

$$\|q_v(t)\| = \sum_{\alpha, \beta = 0}^n \|Q^{\alpha\beta}(\partial_0 v, J_1 v)(t, \cdot)\|_\infty, \quad \|\partial q_v(t)\| = \sum_{\alpha, \beta = 0}^n \|\partial Q^{\alpha\beta}(\partial_0 v, J_1 v)(t, \cdot)\|_\infty.$$

Lemma 6.3. Under the assumptions of Lemma 6.1 and the admissible condition (1.7), let $u$ be a solution of problem (6.5) with

$$\partial_0^lu \in C([0, T]; H^{s+1-j}(O)),$$

In addition, we suppose for some $M_0 > 0$

$$\sup_{0 \leq t \leq T} \|q_v(t)\| \leq M_0 \varepsilon.$$

Then there exists a constant $C > 0$ independent of $u$ and $v$, such that for $0 \leq t \leq T$,

$$M_{s+1}(t, u) \leq C e^{CM_{s+1}[v]t} \left( M_{s+1}(0, u) + C(M_{s+1}[v]) M_{s+1}[v] \int_0^t M_{s+1}(\sigma, u) d\sigma \right) + C(M_s[v]) \int_0^t M_s^2(l, v) dl + C(M_s(t, v)) M_s(t, v)(M_{s+1}(t, u) + M_s(t, v)). \quad (6.7)$$

Proof. By (1.7) and Lemma 6.1 (B), one has that for any function $w$ satisfying $\partial_\nu w = 0$ on $\mathbb{R}_+ \times \partial O$,

$$Q^{\alpha\beta}(\partial_0 v, J_1 v)\nu^\alpha \partial_\beta w = 0, \quad (t, x) \in \mathbb{R}_+ \times \partial O. \quad (6.8)$$

Based on (6.8), by Lemma 3.1 and Lemma 2.4, we have

$$\sum_{0 \leq |\alpha| \leq s} \|\partial^\alpha u(t, \cdot)\| \leq \sum_{0 \leq k \leq s-1} \|\nabla^2 \partial_0^k u(t, \cdot)\|_{H^{s-1-k}} + \sum_{0 \leq k \leq s} \|\partial_0^k u(t, \cdot)\| \leq \sum_{0 \leq k \leq s-1} \left( \|Q^{\alpha\beta}(\partial_0 v, J_1 v)\partial_\alpha^2 \partial_\beta^2 \partial_0^k u(t, \cdot)\|_{H^{s-1-k}} + \|F_k(t, \cdot)\|_{H^{s-1-k}} \right) + \sum_{0 \leq k \leq s} e^{CM_{s+1}t} \left( \|\partial_0^k u(0, \cdot)\| + \int_0^t \|F_k(s, \cdot)\| ds \right), \quad (6.9)$$
Combining this with (6.9) yields (6.7).

\[ \Box \]

Theorem 6.4. For problem (6.10) with \( \|h(t, \cdot)\| \leq 1/2 \) and \( h^{\alpha\beta} \) satisfying the “admissible condition” (1.7), assume that for \( k \geq 2 + n/2, \)

\[ h^{\alpha\beta}(t, x) \in C^k([0, T] \times \mathcal{O}), \quad (u_0, u_1) \in H^k(\mathcal{O}) \times H^{k-1}(\mathcal{O}) \]

and

\[ \partial_t^0 G \in C([0, T]; H^{k-2-j}(\mathcal{O})), \quad 0 \leq j \leq k - 2; \quad \partial_t^{k-1} G \in L^1([0, T]; L^2(\mathcal{O})), \]

when the corresponding compatible conditions of order \( k \) are satisfied, then there exists a unique solution \( u \) to problem (6.10) with \( \partial_t^0 u \in C([0, T]; H^{k-j}(\mathcal{O})) \) for \( 0 \leq j \leq k \). Moreover,

\[ M_k(t, u) \leq C_k \left( \varepsilon \|u_0\|_{H^k} + \varepsilon \|u_1\|_{H^{k-1}} + \sup_{0 \leq \kappa \leq k - 2} \|\partial^\kappa G(s, \cdot)\| + \sum_{0 \leq j \leq k-1} \int_0^t \|\partial_t^j G(s, \cdot)\| ds \right), \]

(6.12)

where \( C_k > 0 \) depends on the \( C^k \) norm of \( h^{\alpha\beta} \).

Proof. We just only give the sketch of the proof. When \( \partial_t^j G \in C([0, T]; H^{k-1-j}(\mathcal{O})) \) for \( 0 \leq j \leq k - 1 \), then Theorem 6.4 directly comes from Theorem 1 and Theorem 2 of [19]. In addition, estimate (6.12) is resulted from the proof of Theorem 2 of [19] (one can also see Lemma 3.1 and Lemma 2.4). When \( G \) satisfies (6.11), it follows from (6.12) and an approximate argument that Theorem 6.4 holds.

We now derive the existence of solution \( u \) to the following linear Neumann-wave problem

\[
\begin{align*}
\square u &= h^{\alpha\beta} \partial_{\alpha\beta}^2 u + G(t, x), \quad (t, x) \in \mathbb{R}_+ \times \mathcal{O}, \\
\partial_{\nu} u &= 0, \quad (t, x) \in \mathbb{R}_+ \times \partial \mathcal{O}, \\
(u, \partial_t u)(0, x) &= \varepsilon(u_0, u_1)(x), \quad x \in \mathcal{O}.
\end{align*}
\]

(6.10)

Theorem 6.4 holds.

Lemma 6.5. For problem (6.10) with \( \|h(t, \cdot)\| \leq 1/2 \) and \( h^{\alpha\beta} \) satisfying the “admissible condition” (1.7), if \( s > 6 + 3n/2, \)

\[ h^{\alpha\beta} \in C^j([0, T]; H^{s-j}(\mathcal{O})), \quad 0 \leq j \leq s, \]

next we extend Theorem 6.4 so that it can be used to prove the local existence of problem (1.3).
With the help of Theorem 6.4, we know that problem (6.10) has a unique solution \( u \) such that \( \partial_t^j u \in C([0, T]; H^{s+1-j}(\Omega)) \), \( 0 \leq j \leq s - 1 \); \( \partial_t^k u \in L^1([0, T]; L^2(\Omega)) \), \( (u_0, u_1) \in H^{s+1}(\Omega) \times H^s(\Omega) \), and the compatible conditions of order \( s + 1 \) are satisfied, then problem (6.10) has a unique solution \( u \) such that \( \partial_t^j u \in C([0, T]; H^{s+1-j}(\Omega)) \) for \( 0 \leq j \leq s + 1 \). Moreover,

\[
M_{s+1}(t, u) \leq C \left( \| (u_0, u_1) \|_{H^{s+1} \times H^s} + \sup_{0 \leq \tau \leq t} \| \partial^{\alpha} G(\tau, \cdot) \| + \sum_{0 \leq j \leq s} \int_0^t \| \partial_t^j G(\tau, \cdot) \| d\tau \right),
\]

where \( C > 0 \) depends on the \( C^j([0, T]; H^{s-j}(\Omega)) \) norms of \( h^{\alpha \beta} \) for \( 0 \leq j \leq s \).

**Proof.** We just only give the sketch of the proof. When \( s > 6 + 3n/2 \), then there exists an integer \( k \geq 2 + n/2 \) to be determined later, such that

\[
s - k > n/2, \quad h^{\alpha \beta}(t, x) \in C^k([0, T] \times \Omega).
\]

With the help of Theorem 6.4, we know that problem (6.10) has a unique solution \( u \) with \( \partial_t^j u \in C([0, T]; H^{k-j}(\Omega)) \) for \( 0 \leq j \leq k \).

In addition, if \( \partial_t^j u \in C([0, T]; H^{s+1-j}(\Omega)) \) for \( 0 \leq j \leq s + 1 \), similar to (6.12), we can obtain estimate (6.13). Then only thing left is to improve the regularity of \( u \), namely for \( w = \partial_t^{s+1-k} u \), we should prove \( \partial_t^j w \in C([0, T], H^{k-j}(\Omega)) \) for \( 0 \leq j \leq k \).

To improve the regularity of \( u \), formally, we consider the following problem for \( w = \partial_t^{s+1-k} u \):

\[
\begin{align*}
\Box w - h^{\alpha \beta} \partial_{\alpha \beta} w &= \sum_{0 \leq m \leq s - k} \left( s + 1 - k \right)_m \partial_t^{s+1-k-m} h^{\alpha \beta} \partial_t^m \partial_{\alpha \beta} u + \partial_t^{s+1-k} G, \\
(t, x) &\in [0, T] \times \Omega, \\
\partial_{\nu} w &= 0, \\
(t, x) &\in [0, T] \times \partial \Omega, \\
w(0, x) &= \psi_{s+1-k}(x), \\
\partial_t w(0, x) &= \psi_{s+2-k}(x), \\
x &\in \Omega,
\end{align*}
\]

where \( u \) has the form

\[
u(t, x) = \psi_0(x) + tv_1(x) + \cdots + \frac{t^{s-k}}{(s-k)!} \psi_{s-k}(x) + \int_0^t (t - \tau)^{s-k} \psi_{s-k}(x) + \int_0^t \frac{(t - \tau)^{s-k}}{(s-k)!} w(\tau, x) d\tau.
\]

Obviously, (6.15) with (6.16) can be regarded as a nonlinear problem on \( w(t, x) \).

With the argument in Theorem 9.10 in [21] and Theorem 6.4, if \( u \) given by (6.16) is assumed to satisfy \( \partial_t^j u \in C([0, T]; H^{s+1-j}(\Omega)) \) for \( 0 \leq j \leq s + 1 \) in advance and for \( 0 \leq m \leq s - k \),

\[
\partial_t^{s+1-k-m} h^{\alpha \beta} \partial_t^m \partial_{\alpha \beta} u \in \bigcap_{j=0}^{k-2} C^j([0, T]; H^{k-2-j}(\Omega)),
\]

then problem (6.13) with (6.16) has a unique solution \( w \) such that \( \partial_t^j w \in C([0, T]; H^{k-j}(\Omega)) \) for \( 0 \leq j \leq k \).

By the argument in Theorem 9.10 in [21], (6.17) is fulfilled when \( s - k < k - n/2 \). Combining this with (6.14) and the restriction on \( k \) in Theorem 6.4, we can choose \( k = 1 + \lfloor s/2 \rfloor + \lfloor n/4 \rfloor \) with \( s > 6 + 3n/2 \). In this situation, with Theorem 6.4 and the regularity argument in the proof of Theorem 1.2 in [19], we complete the proof of Lemma 6.5.
Proof of Theorem 6.2. If we have defined \( u_0(t, x) \), then the sequence \( \{u_{l+1}(t, x)\} \) for \( l \geq 0 \) will be determined by

\[
\begin{align*}
\square u_{l+1} &= Q^{a \beta}(\partial_0 u_l, J_1 u_l) \partial_{a \beta}^2 u_{l+1} + S(\partial_0 u_l, J_1 u_l), \quad (t, x) \in \mathbb{R}_+ \times \mathcal{O}, \\
\partial_\nu u_{l+1} &= 0, \\
\big(u_{l+1}(0, x) = u_0(x), \partial u_{l+1}(0, x) = u_1(x), \quad x \in \mathcal{O}. 
\end{align*}
\tag{6.18}
\]

We now give the construction of \( u_0 \). It follows from Lemma 6.1(A), \( \psi_k \in H^{s+1-k} \) for \( 0 \leq k \leq s + 1 \). By the standard extension theorem, we know that there is a function \( \hat{\psi}_k \in H^{s+1-k}(\mathbb{R}^n) \) such that \( \hat{\psi}_k|_{\mathcal{O}} = \psi_k \) and \( \|\hat{\psi}_k\|_{H^{s+1-k}(\mathbb{R}^n)} \leq 2\|\psi_k\|_{s+1-k} \). Let \( (a_{l_k})_{0 \leq l, k \leq s+1} \) be the inverse matrix of \( (i^2(k+1)^2)_{0 \leq l, k \leq s+1} \) with \( i = \sqrt{-1} \), and we set

\[
\hat{V}(t, \xi) = \sum_{l, k=0}^{s+1} \exp(i(l+1)\langle\xi, t\rangle)a_{l_k}\hat{\psi}_k(\xi)\langle\xi\rangle^{-k};
\]

where \( \hat{V}_l \) stands for the Fourier transform of \( V_l \). Define \( u_0(t, x) = V(t, x)|_{\mathcal{O}} \) with \( V(t, x) \) being the inverse Fourier transformation of \( \hat{V}(t, \xi) \). By a straightforward verification and Lemma 6.1(A), one has

\[
M_{s+1}[u_0] \lesssim \varepsilon\|(u_0, u_1)\|_{H^{s+1} \times H^s} \leq C(s, M)\varepsilon, \tag{6.19}
\]

and

\[
\partial_\nu u_0(0, \cdot) = \psi_k \quad (0 \leq k \leq s), \quad \partial_\nu u_0 = 0 \quad \text{on} \partial\mathcal{O}. \tag{6.20}
\]

Based on (6.19)-(6.20) and Lemma 6.1(B), the existence of \( \{u_l\} \) follows from Lemma 6.5.

We now show that for \( M' = 8(1 + C)C(s, M) \) with \( C \) given in (6.13), such that for \( T \) given in Lemma 6.5

\[
M_{s+1}[u_l] \leq M'\varepsilon \tag{6.21}
\]

uniformly hold for all \( l \).

If we assume \( M_{s+1}[u_l] \leq M'\varepsilon \), then by (6.7) in Lemma 6.3 for problem (6.18), there exists a \( 0 < T^* < T \) independent on \( l \) such that for \( t \in [0, T^*] \) and \( 0 < \varepsilon \leq \varepsilon_0 \),

\[
M_{s+1}(t, u_{l+1}) \\
\leq C e^{CM'\varepsilon} \left( M_{s+1}[u_0] + C(M'\varepsilon) \int_0^t M_{s+1}(\sigma, u_{l+1})d\sigma + C(M'\varepsilon)M^2\varepsilon^2 t \right) \\
+ C(M'\varepsilon)M'\varepsilon(M'\varepsilon + M_{s+1}(t, u_{l+1})) \\
\leq C(M'\varepsilon) \left( \int_0^t M_{s+1}(\sigma, u_{l+1})d\sigma + (M'\varepsilon)^2 \right) + 1/4M'\varepsilon \\
\leq M'\varepsilon.
\]

Here the last inequality comes from Gronwall’s inequality. By induction method, we obtain (6.21).
Meanwhile, we have

\[
\begin{aligned}
\Box(u_{l+1} - u_l) - Q^{\alpha\beta}(\partial_0 u_l, J_1 u_l)\partial^2_{\alpha\beta}(u_{l+1} - u_l) &= F^l, \\
(t, x) &\in [0, T^*] \times \mathcal{O},
\end{aligned}
\]

\[\partial_\nu(u_{l+1} - u_l) = 0, \quad (t, x) \in [0, T^*] \times \partial \mathcal{O},
\]

\[\partial_0(u_{l+1} - u_l)(0, x) = 0, \quad \partial_0(u_{l+1} - \partial_0 u_l) = 0, \quad x \in \mathcal{O},
\]

where

\[
F^l = (Q^{\alpha\beta}(\partial_0 u_l, J_1 u_l) - Q^{\alpha\beta}(\partial_0 u_{l-1}, J_1 u_{l-1}))\partial^2_{\alpha\beta}u_l
+ S(\partial_0 u_l, J_1 u_l) - S(\partial_0 u_{l-1}, J_1 u_{l-1}).
\]

Since \(Q^{\alpha\beta}(\partial_0 u_l, J_1 u_l)\) satisfies the “admissible condition” (1.7) and \(\| (q_{v_l}(t), \partial q_{v_l}(t)) \| \lesssim M\varepsilon\) due to (6.21), it follows from the proof of Lemma 3.1 and (6.22) that

\[
\partial_0\| \partial(u_{l+1} - u_l)(t, \cdot) \| \lesssim M\varepsilon\| \partial(u_{l+1} - u_l)(t, \cdot) \| + \| F^l(t, \cdot) \|.
\]

This implies

\[
\| \partial(u_{l+1} - u_l)(t, \cdot) \| \leq C e^{CMt}\int_0^t \| F^l(\sigma, \cdot) \| d\sigma
\]

\[
\leq C(M)\int_0^t \| \partial(u_l - u_{l-1})(\sigma, \cdot) \| d\sigma
\]

\[
\leq 2M'(C(M')T^*)^l l!,
\]

by induction on \(l\). Combining this with (6.21) shows that for \(T^*\) suitably small, there exists a unique solution \(u\) to problem (6.1) with \(\partial^0_0 u \in C([0, T^*]; H^{s+1-l}(\mathcal{O})) (0 \leq j \leq s + 1)\).

In addition, (6.6) follows from Lemma 6.1, (6.13), (6.19), and the induction argument. Here we omit the details. Thus the proof of Theorem 6.2 is completed. \(\Box\)

**Remark 6.1.** When \((u_0, u_1)\) satisfies (1.8), similar to the discussions at the beginning of Sect.5 in [32], we have

\[
\sup_{0 \leq t \leq 4} \sum_{|\alpha| \leq 69} \| \langle x \rangle^\alpha \partial^\alpha u(t, \cdot) \| \lesssim \varepsilon.
\]

In addition, without loss of generality, we assume \(T^* = 4\) in Lemma 6.2 for the simplicity of notations.

**7 Global stability of 3-D compressible Chaplygin gases in exterior domain**

In this section, as an application of Theorem 1.1, we are concerned with the global existence of a smooth solution to 3-D compressible isentropic Euler system of Chaplygin gases in the exterior...
domain \( O \). The 3-D compressible isentropic Euler system is

\[
\begin{align*}
\partial_t \rho + \text{div}(\rho u) &= 0, \\
\partial_t (\rho u) + \text{div}(\rho u \otimes u) + \nabla P &= 0,
\end{align*}
\]

(7.1)

where \( u = (u_1, u_2, u_3) \), \( \rho \), \( P \) stand for the velocity, density, pressure respectively. For the Chaplygin gases, the equation of pressure state (one can see [11] and so on) is given by

\[ P = P_0 - \frac{A}{\rho}, \]

where \( P_0 > 0 \) and \( A > 0 \) are two positive constants, and \( P > 0 \) for \( \rho > A/P_0 \). If \( (\rho, u) \in C^1 \) is a solution of (7.1) with \( \rho > A/P_0 \), then (7.1) admits the following equivalent form

\[
\begin{align*}
\partial_t \rho + \text{div}(\rho u) &= 0, \\
\partial_t u + u \cdot \nabla u + \frac{\nabla P}{\rho} &= 0.
\end{align*}
\]

(7.2)

We pose the initial-boundary data of (7.2) as follows:

\[
\begin{align*}
\rho(0, x) &= \bar{\rho} + \varepsilon \rho_0(x), \\
u(0, x) &= \varepsilon u_0(x) = \varepsilon(u_1^0(x), u_2^0(x), u_3^0(x)),
\end{align*}
\]

(7.3)

and

\[ u \cdot \nu = 0, \quad \text{on } \mathbb{R}_+ \times \partial O, \]

(7.4)

where \( \bar{\rho} > A/P_0 \) is a constant, \( \varepsilon > 0 \) is a small parameter, and \( (\rho_0(x), u_0(x)) \in C_0^\infty(B(0, M) \cap O) \) (here and below \( B(0, M) \) stands for a ball centered at the origin with a radius \( M > 0 \), and \( O \cap B(0, M) \neq \emptyset \)). Moreover, \( \rho(0, x) > A/P_0, P_0 - \frac{A}{\rho} > 0 \) hold and \( u_0(x) \) satisfies \( \text{rot } u_0(x) \equiv 0 \) with \( u_0(x) \cdot \nu = 0 \) on \( \mathbb{R}_+ \times \partial O \).

Under the irrotational assumption \( \text{rot } u_0(x) \equiv 0 \), by (7.2) and the finite propagation speed property of hyperbolic systems, we know that \( \text{rot } u(t, x) \equiv 0 \) holds as long as the smooth solution \( (\rho, u) \) of (7.2) exists. Moreover \( u(t, x) \) has a compact support in \( x \) for any fixed \( t \geq 0 \). Consequently, there exists a potential function \( \varphi(t, x) \) such that \( u = \nabla \varphi \). It follows from the Bernoulli’s law that

\[
\partial_t \varphi + \frac{1}{2} |\nabla \varphi|^2 + h(\rho) = 0,
\]

(7.5)

where \( h(\rho) \) with \( h'(\rho) = P'(\rho)/\rho \) and \( h(\bar{\rho}) = 0 \) is the enthalpy of the gases. Without loss of generality, we assume the sound speed \( c(\rho) = \sqrt{P'(\rho)} \equiv 1 \). In this case, \( h(\rho) = \frac{1}{2} - \frac{A}{2\rho^2} \). Substituting (7.5) and the expression of \( h(\rho) \) into the equation \( \partial_t \rho + \text{div}(\rho u) = 0 \) yields

\[
\partial_t^2 \varphi + 2 \partial_t \varphi \partial_t \varphi + \partial_x \varphi \partial_y \varphi \partial_j \varphi - (1 + 2 \partial_t \varphi + |\nabla \varphi|^2) \Delta \varphi = 0.
\]

On \( \mathbb{R}_+ \times \partial O \), by (7.4), we have the following boundary condition

\[ \partial_\nu \varphi = 0, \quad (t, x) \in \mathbb{R}_+ \times \partial O. \]
In addition, by (7.3) and $\text{rot}u_0(x) \equiv 0$, the initial data $\varphi(0, x)$ and $\partial_t \varphi(0, x)$ can be determined as follows:

$$\varphi(0, x) = \varepsilon \int_M^{x_1} w_1^0(s, x_2, x_3) ds, \quad \partial_t \varphi(0, x) = \varepsilon \frac{p_0(x)}{\rho} + \varepsilon^2 g(x, \varepsilon),$$

where $g(x, \varepsilon)$ is smooth in its arguments with compact support in $B(0, M) \cap O$.

Collecting those analysis above, we know that $\varphi$ satisfies the following Neumann-wave equation problem

$$\begin{cases}
\Box \varphi = Q(\partial \varphi, \partial^2 \varphi), & (t, x) \in \mathbb{R}_+ \times O, \\
\partial_\nu \varphi = 0, & (t, x) \in \mathbb{R}_+ \times \partial O, \\
\varphi(0, x) = \varepsilon f_0(x), \quad \partial_t \varphi(0, x) = \varepsilon f_1(x, \varepsilon), & x \in O,
\end{cases} \tag{7.6}$$

where $f_0(x)$ and $f_1(x, \varepsilon)$ are smooth in $x$ and have compact support in $B(0, M) \cap O$, and

$$Q(\partial \varphi, \partial^2 \varphi) = Q^{\alpha\beta}(\partial \varphi) \partial^2_{\alpha\beta} \varphi = -2\partial_t \varphi \partial_\nu \varphi - \partial_\nu \varphi \partial_j \varphi \partial^2_{ij} \varphi + (2\partial_t \varphi + |\nabla \varphi|^2) \Delta \varphi. \tag{7.7}$$

Direct computation yields that the null condition holds for the equation in (7.6). In addition, for any smooth functions $v, w$ satisfying $\partial_\nu v|_{\mathbb{R}_+ \times \partial O} = 0$ and $\partial_\nu w|_{\mathbb{R}_+ \times \partial O} = 0$, we have

$$Q^{\alpha\beta}(\partial v) \nu^\alpha \partial_{\beta} w = (2\partial_t v + |\nabla v|^2) \partial_\nu w - \partial_\nu v \partial_i w \partial_\nu v = 0, \quad \text{for } (t, x) \in \mathbb{R}_+ \times \partial O,$

which means that $Q(\partial \varphi, \partial^2 \varphi)$ in (7.7) satisfies the “admissible condition” (1.7). On the other hand, it is easy to check that the compatibility conditions of arbitrary order for the initial-boundary values in (7.6) holds. Thus as an application of Theorem 1.1 we have

**Theorem 7.1.** For problem (7.2) together with (7.3) and (7.4), when $\varepsilon > 0$ is small, then there exists a global smooth solution $(\rho, u) \in C^\infty(\mathbb{R}_+ \times O)$ with $\rho > A/P_0$ and $\text{rot}u(t, x) \equiv 0$.

**Remark 7.1.** To our best knowledge, there are only few works on the blowup or global existence of smooth solutions to quasilinear wave equations or multi-dimensional compressible Euler systems in exterior domain (see [15]-[16] for the symmetric solutions of 3-D quasilinear wave equations, and [37] for 2-D slightly compressible ideal flow respectively). As an application of Theorem 1.1 the global stability of the static Chaplygin gases outside a three dimensional obstacle $K$ is established in Theorem 7.1.

### A Auxiliary lemmas

In this appendix, we establish the following two lemmas.

**Lemma A.1.** If $v \in C^\infty(O)$ has the property $\partial_\nu v|_{\partial O} = 0$, moreover, $v \equiv 0$ for sufficiently large $|x|$, then if $R < t/2$ and $t \geq 1$,

$$\|\partial^2 v(t, \cdot)\|_{L^2(R/2 \leq |x| \leq R)} \lesssim \frac{1}{t} \sum_{|\alpha| \leq 1} \|\Gamma^\alpha \partial v(t, \cdot)\|_{L^2(R/4 \leq |x| \leq 2R)} + \|\Box v(t, \cdot)\|_{L^2(R/4 \leq |x| \leq 2R)} + \|\langle \cdot \rangle^{-1} \partial v(t, \cdot)\|_{L^2(R/4 \leq |x| \leq 2R)}, \quad \tag{A.1}$$
\[
\| (t - | \cdot |) \partial^2 v(t, \cdot) \|_{L^2(|x| \geq t/4)} \lesssim \sum_{|\alpha| \leq 1} \| \Gamma^\alpha \partial v(t, \cdot) \| + \| (t + | \cdot |) \Box v(t, \cdot) \|
\]

and

\[
\| \partial v(t, \cdot) \|_{L^6(|x| \in [R/2 \leq |x| \leq R])} \lesssim R^{-1} \| \partial v(t, \cdot) \|_{L^2(|x| \leq 2R)} + \| \Delta v(t, \cdot) \|_{L^2(|x| \leq 2R)}.
\]

Combining this estimate with (A.4) shows (A.1).

Next we prove (A.2). By [27], for \( g \in C^\infty_0(\mathbb{R}_+ \times \mathbb{R}^3) \), one has

\[
\| \langle t - | \cdot | \rangle \nabla^2 g(t, \cdot) \|_{L^2(\mathbb{R}^3)} \lesssim \sum_{|\alpha| \leq 1} \| \Gamma^\alpha \partial g(t, \cdot) \|_{L^2(\mathbb{R}^3)} + \| (t + | \cdot |) \Box g \|_{L^2(\mathbb{R}^3)}.
\]

Set \( g(t, x) = \rho(8x/ \langle t \rangle) v(t, x) \). Then one has that from (A.5) and Lemma 2.2

\[
\| \langle t - | \cdot | \rangle \nabla^2 v(t, \cdot) \|_{L^2(|x| \geq t/4)} \lesssim \sum_{|\alpha| \leq 1} \| \Gamma^\alpha \partial v(t, \cdot) \| + \| (t + | \cdot |) \Box v(t, \cdot) \|.
\]

Combining this with (A.4) yields (A.2).

(A.3) comes from the proof of (A.1) and the fact that for \( t \geq 1 \)

\[
\| \partial v(t, \cdot) \|_{L^6(|x| \notin [(1-\delta)t,(1+\delta)t], |x| \geq \delta t) \cap \mathcal{O})} \lesssim \| \nabla \partial v(t, \cdot) \|_{L^2(|x| \notin [(1-\delta/2)t,(1+\delta/2)t], |x| \geq \delta t/2) \cap \mathcal{O})} + \| \partial v(t, \cdot) \|/t,
\]

where the factor \( 1/t \) in the last term comes from the scaling skill.

\[ \square \]

**Lemma A.2.** Let \( v, w \in C^\infty(\mathbb{R}_+ \times \mathcal{O}) \) with \( \partial v|_{\mathbb{R}_+ \times \partial \mathcal{O}} = 0 \) and \( \partial v|_{\mathbb{R}_+ \times \partial \mathcal{O}} = 0 \). Moreover
\( v \equiv 0 \) and \( w \equiv 0 \) for sufficiently large \( |x| \). Then for \( R \geq 1 \) and \( t \geq 1 \),

\[
\int_{\mathcal{O}} \frac{(t - |x|)}{(t + |x|) \langle x \rangle} |\partial^2 v(t, x)| \partial w(t, x)|dx
\]

\[
\lesssim \frac{1}{t} \left( \sum_{|\alpha| \leq 1} \| \Gamma^\alpha \partial v(t, \cdot) \| + \| \langle t + | \cdot | \rangle \Box u(t, \cdot) \| \right) \| \partial w(t, \cdot)/\langle \cdot \rangle \|
\]

\( + \sum_{R=2^k \leq t/2} \left( \frac{1}{\langle \cdot \rangle} \partial v(t, \cdot) \|_{L^2(2R \leq |x| \leq 2R)} + \frac{1}{\langle \cdot \rangle^2} v(t, \cdot) \|_{L^2(2R \leq |x| \leq 2R)} \right)\)

\[
\times \| \frac{1}{\langle \cdot \rangle} \partial w(t, \cdot) \|_{L^2(2R \leq |x| \leq 2R)}. \]

\textbf{Proof.} By Schwartz’s inequality and (A.1)-(A.2) in Lemma A.1 we have

\[
\int_{\mathcal{O}} \frac{(t - |x|)}{(t + |x|) \langle x \rangle} |\partial^2 v(t, x)| \partial w(t, x)|dx
\]

\[
\lesssim t^{-1} \| \langle t - | \cdot | \rangle \partial^2 v(t, \cdot) \|_{L^2(|x| \geq t/4)} \| \langle \cdot \rangle^{-1} \partial w(t, \cdot) \|_{L^2(|x| \geq t/4)}
\]

\[+ \sum_{R=2^k \leq t/2} t^{-1} \| \langle t - | \cdot | \rangle \partial^2 v(t, \cdot) \|_{L^2(2R \leq |x| \leq R)} \| \langle \cdot \rangle^{-1} \partial w(t, \cdot) \|_{L^2(2R \leq |x| \leq R)}
\]

\[
\lesssim t^{-1} \left( \sum_{|\alpha| \leq 1} \| \Gamma^\alpha \partial v(t, \cdot) \| + \| \langle t + | \cdot | \rangle \Box v(t, \cdot) \| \right) \| \langle \cdot \rangle^{-1} \partial w(t, \cdot) \|
\]

\[+ \sum_{R=2^k \leq t/2} \left( \frac{1}{\langle \cdot \rangle} \partial v(t, \cdot) \|_{L^2(2R \leq |x| \leq 2R)} + \frac{1}{\langle \cdot \rangle^2} v(t, \cdot) \|_{L^2(2R \leq |x| \leq 2R)} \right)\]

\[
\times \| \langle \cdot \rangle^{-1} \partial w(t, \cdot) \|_{L^2(2R \leq |x| \leq 2R)}. \]

This yields (A.6) and then Lemma A.2 is proved. \(\square\)

\textbf{References}

[1] S. Agmon, A. Douglis, L. Nirenberg, \textit{Estimates near the boundary for solutions of elliptic partial differential equations satisfying general boundary conditions I}. Comm. Pure Appl. Math. 12 (1959), 623-737.

[2] S. Alinhac, \textit{Blowup of small data solutions for a class of quasilinear wave equations in two space dimensions. II}. Acta Math. 182 (1999), 1-12.

[3] S. Alinhac, \textit{The null condition for quasilinear wave equations in two space dimension I}. Invent. Math. 145 (2001), 597-618.
[4] S. Alinhac, *The null condition for quasilinear wave equations in two space dimension. II.* Amer. J. Math. 123 (2001), 1071-1101.

[5] S. Alinhac, *An example of blowup at infinity for a quasilinear wave equation.* Astérisque 284 (2003), 1-91.

[6] B.B. Ding, Y.B. Liu, H.C. Yin, *The small data solutions of general 3D quasilinear wave equations. I.* SIAM J. Math. Anal. 47 (2015), 4192-4228.

[7] B.B. Ding, Ingo Witt, H.C. Yin, *The small data solutions of general 3D quasilinear wave equations. II.* J. Differential Equations 261 (2016), 1429-1471.

[8] S.X. Chen, Z.P. Xin, H.C. Yin, *The global shock waves for the supersonic flow past a curved cone.* Comm. Math. Phys. 228 (2002), 47-84.

[9] D. Christodoulou, Global solutions of nonlinear hyperbolic equations for small initial data. Comm. Pure Appl. Math. 39 (1986), 267-282.

[10] D. Christodoulou, S. Miao, Compressible flow and Euler’s equations. Surveys of Modern Mathematics, 9. Internationa Press, Someville, MA; Higher Education Press, Beijing, 2014. x+iv+583 pp.

[11] R. Courant, K.O. Friedirchs, *Supersonic flow and shock waves.* Reprinting of the 1948 original. Applied Mathematical Sciences, Vol.21. Springer-Verlag, New York-Heidelberg, 1976. xvi+464 pp.

[12] Y. Du, Y. Zhou, *The lifespan for nonlinear wave equation outside of star-shaped obstacle in three space dimensions.* Comm. Partial Differ. Equations 33 (2008), 1455-1485.

[13] D. Gilbarg, N. Trudinger, *Elliptic partial differential equations of second order.* Reprint of the 1998 edition. Springer-Verlag, Berlin, 2001. xiv+517 pp.

[14] P. Godin, *Global shock waves in some domains for the isentropic irrotational potential flow equations.* Commun. Partial Differ. Equ. 22 (1997), 1929-1997.

[15] P. Godin, *The lifespan of solutions of exterior radial quasilinear Cauchy-Neumann problems.* J. Hyperbolic Differ. Equ. 5 (2008), 519-546.

[16] P. Godin, *The lifespan of spherically symmetric solutions of the compressible Euler equations outside an impermeable sphere.* Ann. Inst. H. Poincaré Anal. Non. Linéaire 26 (2009), 2227-2252.

[17] J. Li, Ingo Witt, H.C. Yin, *On the global existence and stability of a three-dimensional supersonic conic shock wave.* Comm. Math. Phys. 329 (2014), 609-640.

[18] L. Hörmander, *Lectures on nonlinear hyperbolic hyperbolic differential equations.* Math. Appl. 26, Springer-Verlag, Berlin, 1997. viii+289 pp.

[19] M. Ikawa, *Mixed problems for hyperbolic equations of second order.* J. Math. Soc. Japan 20 (1968), 580-608.
[20] M. Keel, H. Smith, C.D. Sogge, *On the global existence for nonlinear wave equations outside of convex obstacles*. Amer. J. Math. **122** (2000), 805-842.

[21] M. Keel, H. Smith, C.D. Sogge, *Global existence for a quasilinear wave equation outside of star-shaped domain*. J. Funct. Anal. **189** (2002), 155-226.

[22] M. Keel, H. Smith, C.D. Sogge, *Almost global existence for some semilinear wave equations*. J. Anal. Math. **87** (2002), 265-279.

[23] M. Keel, H. Smith, C.D. Sogge, *Almost global existence for quasilinear wave equations in three space dimensions*. J. Amer. Math. Soc. **17** (2004), 109-153.

[24] S. Klainerman, *Remarks on the global Sobolev inequalities in the Minkowski space* $\mathbb{R}^{n+1}$, Comm. Pure Appl. Math. 40, 111-117 (1987)

[25] S. Klainerman, *The null condition and global existence to nonlinear wave equations*. Nonlinear systems of partial differential equations in applied mathematics, Part 1 (Santa Fe, N.M., 1984), 293-326, Lectures in Appl. Math., 23, Amer. Math. Soc., Providence, RI, 1986.

[26] S. Klainerman, G. Ponce, *Global, small amplitude solutions to nonlinear evolution equations*, Comm. Pure Appl. Math. 36, no. 1, 133-141 (1983)

[27] S. Klainerman, T.C. Sideris, *On almost global existence for nonrelativistic wave equations in 3D*. Comm. Pure Appl. Math. 49 (1996), 307-321.

[28] T.T. Li, Y.M. Chen, *Initial value problem for nonlinear wave equations*. Comm. Partial Differential Equations **13** (1988), 383-422.

[29] H. Lindblad, *On the lifespan of solutions of nonlinear wave equations with small initial data*. Comm. Pure Appl. Math. **43** (1990), 445-472.

[30] H. Lindblad, *Global solutions of quasilinear wave equations*. Amer. J. Math. **130** (2008), 115-157.

[31] H. Lindblad, M. Nakamura, C.D. Sogge, *Remarks on global solutions for nonlinear wave equations under the standard null conditions*. J. Differential Equations **254** (2013), 1396-1436.

[32] J. Metcalfe, C.D. Sogge, *Hyperbolic trapped rays and global existence of quasilinear wave equations*. Invent. Math. **159** (2005), 75-117.

[33] J. Metcalfe, C.D. Sogge, *Global existence for Dirichlet-wave equations with quadratic nonlinearities in high dimensions*. Math. Ann. **336** (2006), 391-420.

[34] J. Metcalfe, C.D. Sogge, *Long time existence of quasilinear wave equations exterior to star-shaped obstacles via energy method*. SIAM J. Math. Anal. **38** (2006), 188-209.

[35] J. Metcalfe, C.D. Sogge, *Global existence of null-form wave equations in exterior domains*. Math. Z. **256** (2007), 521-549.
[36] C.S. Morawetz, *Decay for solutions of the exterior problem for the wave equation*. Comm. Pure Appl. Math. **28** (1975), 229-264.

[37] P. Secchi, *2D slightly compressible ideal flow in an exterior domain*. J. Math. Fluid Mech. **8** (2006), 564-590.

[38] Y. Shibata, G. Nakamura, *On a local existence theorem of Neumann problem for some quasilinear hyperbolic systems of 2nd order*. Math. Z. **202** (1989), 1-64.

[39] C.D. Sogge, *Lectures on nonlinear wave equation*. Monographs in Analysis, II. International Press, Boston, MA, 1995. vi+159 pp.

[40] C.D. Sogge, *Global existence for nonlinear wave equations with multiple speeds*. Harmonic analysis at Mount Holyoke, 353-366, Contemp. Math., 320, Amer. Math. Soc., Providence, RI, 2003.

[41] J. Speck, *Shock formation in small-data solutions to 3D quasilinear wave equations*, arXiv: 1407.6320 (2014)