Communication-Efficient Federated Learning with Adaptive Quantization

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Federated learning (FL) has attracted tremendous attentions in recent years due to its privacy-preserving measures and great potential in some distributed but privacy-sensitive applications, such as finance and health. However, high communication overloads for transmitting high-dimensional networks and extra security masks remain a bottleneck of FL. This article proposes a communication-efficient FL framework with an Adaptive Quantized Gradient (AQG), which adaptively adjusts the quantization level based on a local gradient’s update to fully utilize the heterogeneity of local data distribution for reducing unnecessary transmissions. In addition, client dropout issues are taken into account and an Augmented AQG is developed, which could limit the dropout noise with an appropriate amplification mechanism for transmitted gradients. Theoretical analysis and experiment results show that the proposed AQG leads to 18% to 50% of additional transmission reduction as compared with existing popular methods, including Quantized Gradient Descent.
(QGD) and Lazily Aggregated Quantized (LAQ) gradient-based methods without deteriorating convergence properties. Experiments with heterogeneous data distributions corroborate a more significant transmission reduction compared with independent identical data distributions. The proposed AQG is robust to a client dropping rate up to 90% empirically, and the Augmented AQG manages to further improve the FL system’s communication efficiency with the presence of moderate-scale client dropouts commonly seen in practical FL scenarios.

CCS Concepts: • Computing methodologies → Artificial intelligence; Machine learning; Distributed computing methodologies; • Security and privacy; • Networks → Network reliability;

Additional Key Words and Phrases: Federated learning, information compression, communication efficiency

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1 INTRODUCTION

The deployment of the Internet of things (IoT), ubiquitous sensing, edge computing, and many other distributed systems have enabled the rapid development of distributed learning techniques in recent years [10, 12, 20]. Distributed learning could fully utilize low-cost computing resources throughout the network and achieve comparable performance with centralized learning. Nevertheless, the leakage of data, gradients, and even models during the updating and transmitting process in distributed learning has raised the concerns of user privacy and security, which greatly limit its applications in some specific fields, such as finance and health. To this end, federated learning (FL), which prevents privacy leakage by avoiding data exposition, has been proposed by Google and other researchers, attracting tremendous attention from both academia and industry [22].

Many approaches — such as differential privacy [1], secret-sharing techniques [5], and homomorphic encryption [21] — have been developed to mask transmitted gradients and can mostly well address the security issues in FL. However, high-dimensional neural networks and extra security masks [8, 16, 31] may lead to high communication overhead, which becomes a main bottleneck of FL systems. In this context, communication-efficient learning algorithms have been proposed mainly to reduce transmission bits based on gradient quantization, which maps a real-valued vector to a constant number of bits. Representative gradient quantization algorithms for distributed systems include Quantized Stochastic Gradient Descent (QSGD) [3], 1-bit SGD [25], and SignSGD [4]. However, these methods communicate at all iterations (transmit all computed gradients) with a fixed number of quantization bits, which is not efficient enough for FL, in which non-IID (Independently Identically Distributed) data distribution is common. To address this problem, Sun et al. proposed a gradient innovation-based Lazily Aggregated Quantized (LAQ) gradient method, which utilizes the differences between local loss functions and skips the transmission of slowly varying quantized gradients [15]. Although the LAQ method reduces transmission overload by skipping unnecessary communication rounds, it still fixes the number of bits for all transmitted gradients, which remains to be improved.

In order to further reduce overall transmitted bits, this article proposes a communication-efficient FL framework with an Adaptive Quantized Gradient (AQG), in which the quantization level is adjusted according to the local gradient’s updates adaptively. Specifically, gradients with a larger amount of updates are quantized and transmitted with more bits and vice versa. In addition, this article takes client dropouts into account, which is another main challenge faced by FL system due to limited device reliability [5]. In order to improve the performance of an AQG with the presence of the noise introduced by client dropouts, the proposed FL framework with an

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AQG is augmented by a variance-reduced method in which transmitted gradients are appropriately amplified to keep the unbiased estimators.

Theoretical analysis and experiment results show that the proposed AQG outperforms existing methods in terms of overall transmitted bits without deteriorating convergence properties. The AQG is robust to a client dropping rate up to 90% empirically, and the Augmented AQG with gradient amplification acts as a competitive solution to achieve an even more significant transmission reduction, with a moderate client dropping scale commonly seen in practical FL scenarios.

The remainder of the article is organized as follows. Section 2 provides an overview of the FL system and discusses our motivations. The proposed Adaptive Quantized Gradient method is elaborated in Section 3. A theoretical analysis and convergence guarantee of AQG are provided in Section 4. We evaluate the performance of AQG with extensive experiments in Section 5 and present our conclusions in Section 6.

Notations. The notations used in this article are listed in Table 1.

### Table 1. Notations

| Symbol | Description |
|--------|-------------|
| $g^k_m$ | gradient computed by client $m$ at iteration $k$ |
| $\hat{g}^k_m$ | gradient used for aggregation from client $m$ at iteration $k$ |
| $b_{\text{max}}$ | upper bound for the number of bits after quantization |
| $b^k_m$ | the quantization bit number chosen by client $m$ at iteration $k$ |
| $\hat{b}^k_m$ | the quantization bit number chosen by client $m$ for $\hat{g}^k_m$ |
| $Q_b(g^k_m)$ | $g^k_m$ quantized with $b$ bits |
| $\theta^k$ | the aggregated global model broadcast at iteration $k$ |
| $e_b(g^k_m)$ | quantization error $(Q_b(g^k_m) - g^k_m)$ |
| $\mathcal{M}$ | client set |
| $\mathcal{M}^k_b$ | subset of clients uploading gradients with $b$ bits at iteration $k$ |
| $p$ | client dropping rate |
| $\lceil a \rceil$ | the ceiling of $a$ |
| $\| x \|_2$ | $l_2$-norm of $x$ |
| $\| x \|_\infty$ | $l_\infty$-norm of $x$ |

### 2 SYSTEM OVERVIEW AND MOTIVATIONS

#### 2.1 Federated Learning System

FL is designed to collaboratively train a global machine learning model with heterogeneous local data distribution across multiple privacy-sensitive clients. A typical architecture for a FL system with $M$ distributed clients and a server is shown in Figure 1. Similar to most distributed learning systems, an FL system uses a server to receive locally computed gradients and update the global model by aggregation. However, in order to prevent privacy leakage from raw gradients, distributed clients have to mask or encrypt the local gradients before transmission. Therefore, the communication burden in FL systems tends to be heavier compared with other distributed learning systems [5]. In addition, distributed clients in FL systems, such as mobile devices in wireless networks, usually have limited computation and communication resources, which may lead to the dropout of the participants in each iteration, like the client $M$ shown in Figure 1. Thus, the robustness to client dropout is another practical requirement for FL systems [5].

#### 2.2 Motivations

FL is bottlenecked by high communication overhead and limited device reliability. The lack of efficient transmission and robustness to client dropouts may lead to slow, expensive, and unstable
learning. In this article, the FL framework with the proposed AQG method provides opportunities for communication-efficient FL with large-scale of client dropouts.

First, AQG focuses on reducing unnecessary transmission by fully utilizing the heterogeneous property of FL. Due to the heterogeneity of local data distribution, local optimization objectives decrease at different rates. Therefore, adaptively adjusting the quantization level according to a gradient’s update amount provides a more efficient way to communicate with the server by quantizing slowly varying gradients with less amount of bits.

Second, AQG aims to address the noise induced by client dropouts. When a client dropout occurs, all coordinates of a transmitted gradient are lost, which can be regarded as an extreme example of gradient sparsification [2, 19, 28, 29]. In order to limit the variance increase of a sparsified gradient, Wangni et al. proposed keeping the unbiasedness of the sparsified gradient by appropriately amplifying the remaining coordinates [30]. Inspired by this idea, the AQG tries to stay robust to client dropouts or even further improve the communication efficiency of FL with client dropouts by further adjusting the transmitted gradients and suppressing the noise.

3 AQG: ADAPTIVE QUANTIZED GRADIENT

To reduce transmission overhead, a multilevel adaptive quantization scheme is proposed in this section. As illustrated in Figure 2(a), the FL system with an AQG can be implemented as follows. At iteration \( k \), the server broadcasts global model \( \theta^k \) to all clients. Each client computes gradient \( \nabla f_m(X_m; \theta^k) \):

\[
g_m^k = \nabla f_m(X_m; \theta^k). \tag{1}
\]

After gradient computation, each client needs to make two decisions: (1) is it necessary to send its quantized gradient? and (2) how many bits \( b_m^k \) should be used to quantize and send its newly computed gradient? The first decision is the key idea in the LAQ method [15]. In this article, it is considered to be a special case of the second decision, where \( b_m^k \) is chosen as zero if the client decides to send nothing.

If client \( m \) chooses a non-zero \( b_m^k \) and updates its newly quantized gradient, then \( Q_{b_m^k} (g_m^k) \) is one of the quantized gradients that actually participates in gradient aggregation on the server side at iteration \( k \). Otherwise, the server reuses the old quantized-gradient \( Q_{b_m^{k-1}} (\hat{g}_m^{k-1}) \) from the last iteration to represent client \( m \) in the aggregation. In summary, an iteration step of the proposed AQG is as follows:

\[
Q_{b_m^k} (g_m^k) = \begin{cases} Q_{b_m^k} (g_m^k), & m \in M \setminus M_0^k \\ Q_{b_m^{k-1}} (\hat{g}_m^{k-1}), & m \in M_0^k \end{cases} \tag{2}
\]
The schematic illustration of the communication-efficient FL with an AQG in comparison with the LAQ method. In LAQ, the quantization level is fixed at $b$, while the AQG adaptively adjusts the quantization level for every client at each iteration, as indicated by (a), in which the red lines indicating the transmission of quantized gradients are drawn in different thicknesses to represent different quantization levels selected by various clients. In addition, the AQG addresses potential client dropouts with appropriate gradient amplification.

**Gradient Aggregation**

$$\theta^{k+1} = \theta^k - \alpha \sum_{m\in M^k} Q_{b_m}(\hat{\theta}_m^k),$$  \hspace{1cm} (3)

where $M^k_0$ denotes the subset of clients that sets $b_m^k = 0$ and uploads nothing at iteration $k$. For client $m$, $Q_{b_m}(\hat{\theta}_m^k)$ represents the quantized gradient actually used for aggregation at iteration $k$, which may be outdated if $m \in M^k_0$.

The target problems of AQG are that:

1. For adaptive quantization of lazily aggregated gradients, a precision selection criterion that can cooperate with a lazy aggregation scheme and adaptively decide the quantization level for each newly computed gradient is required.

2. For an FL scenario in which client dropouts are relatively frequent, methods to limit the noise introduced by gradient lossing are also in great need.

The next section presents the precision selection criterion developed in this article and the quantization scheme applied in the proposed AQG. In Section 3.3, an optional augmentation of AQG is proposed to address potential client dropouts.

### 3.1 Precision Selection Criterion

As mentioned before, the LAQ algorithm proposed by Sun et al. skips the uploads of quantized gradients with small innovations — the difference between $Q_b(\hat{\theta}_m^k)$ and the last upload $Q_b(\hat{\theta}_m^{k-1})$, where $b$ is the fixed number of bits after quantization [15]. In order to decide whether client $m$ needs to upload its newly quantized gradient $Q_b(\hat{\theta}_m^k)$ at iteration $k$, the LAQ method develops a communication selection criterion as follows:

$$\|Q_b(\hat{\theta}_m^{k-1}) - Q_b(\hat{\theta}_m^k)\|_2^2 \geq \frac{1}{\alpha^2 M^2} \sum_{d=1}^D \xi_d \|\theta^{k+1-d} - \theta^{k-d}\|_2^2 + 3 \left( \|\epsilon_b(\hat{\theta}_m^{k-1})\|_2^2 + \|\epsilon_b(\hat{\theta}_m^k)\|_2^2 \right),$$  \hspace{1cm} (4)

where $\epsilon_b(\hat{\theta}_m^{k-1})$ and $\epsilon_b(\hat{\theta}_m^k)$ denote quantization errors, and $\{\xi_d\}_{d=1}^D$ are predetermined constant weights used to balance the impact of global model updates from previous $D$ steps. In LAQ, client $m$ sends its newly quantized local gradient $Q_b(\hat{\theta}_m^k)$ at iteration $k$ only when the difference between $Q_b(\hat{\theta}_m^k)$ and the last upload $Q_b(\hat{\theta}_m^{k-1})$ is larger than a threshold, which takes the quantization error and global model’s innovation into account [15]. Note that the quantization level $b$ in LAQ is fixed.
This article extends the single precision level LAQ with communication selection criterion (4) to multilevel adaptive quantization for transmitted gradients. The key idea of the AQG is that under a preset upper bound \( b_{\text{max}} \) for the number of bits after quantization, gradients with smaller innovations can be quantized with a lower number of bits, since the negative impact of their precision losses on convergence is limited.

In order to decide how many bits \( b^k_m \) should be used to quantize and send client \( m \)'s newly computed gradient \( \hat{g}^k_m \), we develop the following precision selection criterion:

\[
\frac{1}{\alpha^2 M^2} \sum_{d=1}^{D} \xi_d \| \theta^{k+1-d} - \theta^{k-d} \|_2^2 \geq \frac{1}{\alpha^2 M^2} \sum_{d=1}^{D} \xi_d \| \theta^{k+1-d} - \theta^{k-d} \|_2^2 + 3 \left( \| \epsilon_{b_{\text{max}}-b+1}(\hat{g}^{k-1}_m) \|_2^2 + \| \epsilon_{b_{\text{max}}-b+1}(g^{k}_m) \|_2^2 \right). \tag{5}
\]

As illustrated in Figure 3, the precision selection criterion (5) in the AQG quantizes larger updates with more bits and vice versa. Specifically, with quantization levels \([1, \ldots, b_{\text{max}}]\), the quantization errors for any given vector \( g \) always satisfy \( \epsilon_{b_{\text{max}}}(g) \leq \epsilon_{b_{\text{max}}-1}(g) \cdots \leq \epsilon_1(g) \). Therefore, with \( b_{\text{max}} \) quantization levels in total, the range of each gradient innovation \( \| Q_{b_{\text{max}}-1}(\hat{g}^{k-1}_m) - Q_{b_{\text{max}}}(g^{k}_m) \|_2^2 \) can be divided into \( b_{\text{max}} + 1 \) intervals, as shown in Figure 3(a). Then, we allocate the higher quantization level for clients with larger gradient innovations, as indicated by Figure 3(b). Thus, the proposed precision selection criterion divides the entire client set \( M \) into \( b_{\text{max}} + 1 \) non-overlapping subsets as follows:

\[
\begin{align*}
M^k_0 & \cup M^k_1 \cup M^k_2 \cup \cdots \cup M^k_{b_{\text{max}}} = M^k, \tag{6a} \\
M^k_0 \cap M^k_1 \cap M^k_2 \cap \cdots \cap M^k_{b_{\text{max}}} = \emptyset, \tag{6b}
\end{align*}
\]

where \( M^k_b \) denotes the subset of clients that send gradients quantized by \( b \) bits at iteration \( k \). \( M^k_0 \) denotes the subset of clients that skip the update.

FL with an AQG is summarized in Algorithm 1. At iteration \( k \), each client checks where its innovation locates in Figure 3(a), and then re-quantizes its gradient with the corresponding number of bits for the update. Theoretical analysis of a multilevel AQG with (5) is provided in Section 4.

For computation simplicity, a two-level variant of the AQG is also proposed in this article. At each iteration:

**Two-level AQG.** There are only two precision levels to be selected for each client. In other words, \( b \) in criterion (5) only has two options: \( \lceil \frac{b_{\text{max}}}{2} \rceil \) and \( b_{\text{max}} \).

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ALGORITHM 1: AQG

Input: stepsizes $\alpha > 0$, $b_{\text{max}}$, $D$, and $\{\xi_d\}^D_{d=1}$.

Initialize: $\theta^1$.

1: for $k = 1, 2, \ldots, K$ do
2: Server broadcasts $\theta^k$ to all workers.
3: for each client $m \in \mathcal{M}$ in parallel do
4: Worker $m$ computes $g^k_m$ and $Q_{b_{\text{max}}}(g^k_m)$.
5: if (5) with $b = 1$ holds for worker $m$ then
6: for $b = b_{\text{max}}, b_{\text{max}} - 1, \ldots, 1$ do
7: if (5) with $b$ holds for worker $m$ then
8: Worker $m$ computes and sends $Q^b(g^k_m)$.
9: Set $b^k_m = b$.
10: Set $g^k_m = g^k_m$ and $b^k_m = b$ on both sides.
11: Break.
12: end if
13: end for
14: else
15: Worker $m$ sends nothing.
16: Set $b^k_m = 0$.
17: Set $g^k_m = g^{k-1}_m$ and $b^k_m = b^{k-1}_m$ on both sides.
18: end if
19: end for
20: Server updates $\theta^{k+1}$ by $\theta^k - \alpha \sum_{m=1}^M Q_{b^k_m}(g^k_m)$.
21: end for

3.2 Quantization Scheme

For better comparison, we adapt the quantization scheme used in the LAQ algorithm [15]. The scheme quantizes the difference between the new gradient $g^k_m$ and the last quantized upload $Q_{b^{k-1}_{\text{max}}}(g^{k-1}_m)$:

$$\Delta = g^k_m - Q_{b^{k-1}_{\text{max}}}(g^{k-1}_m).$$

(7)

With $b$ bits used for quantization, the value range of $\Delta$’s elements can be represented by a uniformly discretized grid with $2^b - 1$ quantized values, as shown in Figure 4. By projecting every real number in this range to the closest quantized value, $g^k_m$ can be represented by $Q_b(g^k_m)$ with $b$ bits for each element instead of 32/64 bits by default.

3.3 Augmented AQG for Client Dropouts

This article also considers random client dropout in FL and uses $z^k_m$ to control the participation of client $m$ at iteration $k$. With a client dropping rate $p$:

$$z^k_m \sim \text{Bernoulli}(p).$$

If $z^k_m = 1$, client $m$ drops out and fails to perform gradient computation at iteration $k$. It is obvious that with a dropping rate $p$, the percentage of active clients is approximately $1 - p$ at each iteration.

With this setting, the expectation of client $m$’s upload is as follows:

$$E\left[Q_{b^k_m}(g^k_m)\right] = (1 - p) \cdot Q_{b^k_m}(g^k_m) + p \cdot \mathbf{0},$$

(8)

where $\mathbf{0}$ is a zero vector of the same shape as $Q_{b^k_m}(g^k_m)$.
In order to get an unbiased expectation, the upload is adjusted to $Q_{b_m}^k(g_m^k)/(1 - p)$. Then,

$$E\left[Q_{b_m}^k(g_m^k)\right] = (1 - p) \cdot \left(Q_{b_m}^k(g_m^k)/(1 - p)\right) + p \cdot 0 = Q_{b_m}^k(g_m^k).$$  

(9)

The Augmented AQG is summarized in Algorithm 2. The intuitive explanation for gradient amplification is that the loss function $f_m$ is smooth, which means the new update $Q_{b_m}^k(g_m^k)$ tends to be approximate to recent previous updates that may have been lost due to client dropouts.

Compared with the existing LAQ method, the proposed AQG method adjusts the number of quantization bits based on local gradient innovation adaptively. The rationale of AQG is that the proposed precision selection criterion utilizes the inherent heterogeneity of local optimization objectives to reduce unnecessary transmission cost. Theoretical analysis in the next section will prove that the AQG maintains the desired convergence properties of the LAQ method. Experiments show that the AQG advances and fits FL better with the following contributions:

1. The AQG outperforms existing popular methods in terms of overall transmission bits and achieves a more significant transmission reduction with heterogeneous data distribution compared with IID data distribution.
2. The AQG is robust to a client’s dropping rate up to 90%, and the Augmented AQG manages to further reduce transmission overload with a moderate scale of client dropouts.

4 CONVERGENCE ANALYSIS

In this section, the proposed AQG is analyzed theoretically and a convergence guarantee is provided. The theoretical analysis of an AQG is based on the following assumption:

**Assumption 1.** Loss function $f(\theta) = \sum_{m \in M} f_m(\theta)$ is $L$-smooth.

The Lyapunov function of AQG is defined in the same way as the LAQ:

$$\forall(\theta^k) = f(\theta^k) - f(\theta^*) + \sum_{d=1}^{D} \sum_{j=d}^{D} \frac{\xi_j}{\alpha} ||\theta^{k+1-d} - \theta^{k-d}||_2^2,$$

(10)

where $\theta^*$ is the optimal solution of $\min_{\theta} f(\theta)$.

With the quantization errors in precision selection criterion (5) being ignored, the parameter differences term in Lyapunov function helps guarantee that the error induced by skipping gradients decreases with the objective residual in the training process.

4.1 Convergence Guarantee

To ensure convergence, the following inequality should always hold:

$$\forall(\theta^{k+1}) - \forall(\theta^k) \leq 0.$$  

(11)
ALGORITHM 2: Augmented AQG

Input: stepsize $\alpha > 0$, $b_{\text{max}}$, $D$, and $\{\xi_d\}_{d=1}^D$.

Initialize: $\theta^1$.

1: for $k = 1, 2, \ldots, K$ do
2: Server broadcasts $\theta^k$ to all workers.
3: for each client $m \in \mathcal{M}$ in parallel do
4: if $z_m^k = 0$ then
5: Worker $m$ computes $g_m^k$ and $Q_{b_{\text{max}}}(g_m^k)$.
6: if (5) with $b = 1$ holds for worker $m$ then
7: for $b = b_{\text{max}}, b_{\text{max}} - 1, \ldots, 1$ do
8: if (5) with $b$ holds for worker $m$ then
9: Worker $m$ computes and sends $Q_b(g_m^k)$.
10: Set $b_m^k = b$.
11: Set $g_m^k = g_m^{k-1}$ and $b_m^k = b$ on both sides.
12: Break.
13: end if
14: end for
15: end if
16: else
17: Worker $m$ sends nothing.
18: Set $b_m^k = 0$,
19: Set $g_m^k = g_m^{k-1}$ and $b_m^k = b_m^{k-1}$ on both sides.
20: end if
21: end for
22: Server updates $\theta^{k+1}$ by $\theta^k - \alpha \sum_{m=1}^{\mathcal{M}} Q_{b_m^k}(g_m^k)$.
23: end for

Lemma 1. Under Assumption 1, (11) holds if the following three inequalities are satisfied simultaneously:

\[
-\frac{\alpha}{2} + \frac{1}{2} \alpha \rho_1 + (L + 2 \beta_1)(1 + \rho_2)\alpha^2 \leq 0 \quad (12a)
\]

\[
\left[\frac{\alpha}{2} + \left(\frac{L}{2} + \beta_1\right)(1 + \rho_2^{-1})\alpha^2\right] \frac{\xi_D}{\alpha^2} - \beta_D \leq 0 \quad (12b)
\]

\[
\left[\frac{\alpha}{2} + \left(\frac{L}{2} + \beta_1\right)(1 + \rho_2^{-1})\alpha^2\right] \frac{\xi_d}{\alpha^2} + \beta_{d+1} - \beta_d \leq 0, \quad (12c)
\]

where $\rho_1$ and $\rho_2$ are constants. $\beta_d = \frac{1}{\alpha} \sum_{j=d}^{D} \xi_j$, $\forall d \in \{1, \ldots, D\}$. See the Appendix for proof details.

It indicates that if the stepsize $\alpha$ and constants $\{\xi_d\}_{d=1}^D$ satisfy these three inequalities, the convergence of the Lyapunov function (10) is guaranteed theoretically.

4.2 Linear Convergence With Strongly Convex Loss

The theoretical analysis under the strongly convex loss function is based on the following assumption:

Assumption 2. Loss function $f(\theta) = \sum_{m \in \mathcal{M}} f_m(\theta)$ is $\mu$-strongly convex.
Fig. 5. Convergence of loss function with logistic regression and IID data distribution.

Under Assumption 2, there is:

\[ \|\theta - \theta^*\|_2^2 \leq \frac{2}{\mu}[f(\theta) - f(\theta^*)]. \]  

(13)

**Lemma 2.** Under Assumptions 1 and 2, the following inequality holds:

\[
\forall \theta^{k+1} \leq (1 - c)\forall \theta^k \\
+ B \left( \sum_{m=1}^{M} \epsilon_{b_{\text{max}}}^2(\hat{g}^k_m) \right) + B \sum_{m \in M^k_0} \left( \left\| \epsilon_{b_{\text{max}}} (\hat{g}^k_{m-1}) \right\|_2 + \left\| \epsilon_{b_{\text{max}}} (\hat{g}^k_m) \right\|_2 \right) \\
+ B \left( \sum_{b=1}^{b_{\text{max}}} \sum_{m \in M^b_b} \left\| \epsilon_{b_{\text{max}}} (\hat{g}^k_m) \right\|_2 + \sum_{b=1}^{b_{\text{max}}} \sum_{m \in M^b_b \setminus M^b_{b-1}} \left\| \epsilon_{b_{\text{max}}} (\hat{g}^k_m) \right\|_2 \right).
\]  

(14)

where \( c \) and \( B \) are constants depending on \( \mu, \rho_1, \rho_2 \) and parameters involved in selection criterion (5). See the Appendix for proof details.

**Theorem 1.** Under Assumptions 1, 2 and Lemma 2, Lyapunov function and the quantization errors all converge at a linear rate:

\[
\left\| \epsilon_b (\hat{g}^k_m) \right\|_2^2 \leq P \tau_b^2 \sigma^k \forall \theta^1 \\
\forall \theta^{k+1} \leq \sigma^k \forall \theta^1,
\]  

(15a)

(15b)

where \( \sigma \in (0,1) \) and \( \tau_b \) is the quantization granularity with \( 2^b \) quantization levels. \( P \) is a constant based on parameters in Lemma 1. See the Appendix for proof details.

5 EXPERIMENT RESULTS

In this section, the performance of FL with the proposed AQG is evaluated with regularized logistic regression and a neural network, respectively, representing strongly convex and non-convex loss function. Experiment results demonstrate that the AQG outperforms state-of-the-art quantization algorithms in terms of reducing transmission bits and resisting client dropouts.

5.1 Experiment Setup

**Datasets.** In this article, we evaluate the proposed AQG method with a heterogeneous simulation dataset [7], MNIST and CIFAR10, considering both IID and non-IID data distribution. To simulate non-IID data distribution with MNIST and CIFAR10, each client is assigned only two classes of data with a balanced amount. The detailed description of the adopted dataset is provided in the Appendix.
Table 2. Performance Comparison of Gradient-Based Algorithms

| Experiment setting | Iteration # | Communication # | Bit # | Transmission Reduction |
|--------------------|-------------|-----------------|-------|------------------------|
| **Logistic Regression** |             |                 |       |                        |
| IID                | Two-Level AQG | 500             | 3,933 | 7,952 | 41% |
| 4-bit LAQ         | 500          | 3,354           | 1.34 × 10^4 | 38% | 0 |
| 4-bit QGD         | 500          | 9,000           | 3.6 × 10^4 | – |
| Multilevel AQG    | 500          | 4,870           | 1.34 × 10^4 | 51% |  |
| 4-bit LAQ         | 500          | 8,273           | 1.78 × 10^4 | 43% |  |
| 32-bit GD*        | 500          | 9,000           | 2.88 × 10^6 | – |  |
| non-IID           | Two-Level AQG | 2,713           | 854   | 1,708 | 34% |
| 4-bit LAQ         | 2,713        | 974             | 1,928 | 25% |  |
| 4-bit QGD         | 2,890        | 28,900          | 1.16 × 10^6 | – |  |
| Multilevel AQG    | 1,319        | 1030            | 2,060 | 44% |  |
| 4-bit LAQ         | 1,702        | 977             | 1,845 | 49% |  |
| 4-bit QGD         | 1,251        | 12,510          | 50,040 | – |  |

*Since 4-bit QGD fails to converge with logistic regression and non-IID data distribution, the 32-bit vanilla GD is implemented for comparison.
*4-bit QGD definitely costs more bits compared with the baseline 4-bit LAQ.

**Models.** We implement logistic regression with the simulation dataset, a fully-connected network with MNIST, and a ResNet18 model with CIFAR10.

**Parameters.** For the AQG and LAQ, the constant parameter \( D = 10 \), the weights \( \{\xi_d\}_{d=1}^D = 1/D \), and \( M = 10 \). Other standard hyperparameters of the training process are listed in Table 3 in the Appendix.

The experiment results of logistic regression and the fully connected neural network are shown in Table 2. For logistic regression, all algorithms run 500 iterations. For the fully connected network, all algorithms run 4,000 iterations, and we calculate the number of iterations, communication rounds, and transmission bits when the loss residual decreases to less than \( 1 \times 10^{-6} \). For both tasks, the amount of bits counted for each algorithm in Table 2 is the number of bits used to transmit one dimension of the uploaded gradient. Generally speaking, the proposed AQG achieves transmission reduction in all experimental settings, and the transmission reduction for non-IID data distribution is more significant than that of IID data distribution. The experiment results of ResNet18 with CIFAR10 shown in the Appendix demonstrate a similar trend.

5.2 Performance Analysis

5.2.1 **Performance of the AQG with IID Data Distribution.** Figure 5(a) shows that with IID data distribution, the multi-level AQG and the two-level variant of AQG both reach a linear convergence rate as LAQ and QGD in strongly convex conditions. Meanwhile, AQG significantly saves transmission bits compared with 4-bit LAQ and 4-bit QGD, as shown in Figure 5(c). It can be observed from Figure 5(b) that the reduction of transmission bits is at the cost of a slight increase in communication rounds compared with LAQ, but it is worthwhile due to the significant reduction in overall transmission load.

Figure 6 shows the experiment results with IID data distribution and non-convex loss function. Similar to the results with logistic regression, the multi-level AQG and two-level AQG both require fewer bits to reach convergence without sacrificing the convergence properties of 4-bit LAQ and 4-bit QGD, as depicted in Figures 6(a) and 6(c). Meanwhile, compared with 4-bit QGD, the AQG significantly reduces communication rounds to the same order of magnitude as 4-bit LAQ, as shown in Figure 6(b).
5.2.2 Performance of the AQG with non-IID Data Distribution. Figures 7 and 8 verify that the AQG works well with heterogeneous data distribution. Both variants of AQG manage to reduce the amount of transmitted bits compared with other alternatives in both strongly convex and non-convex optimization. Meanwhile, it is obvious that experiments in non-IID data distribution benefit more from the AQG compared with IID data distribution. The results are consistent with our expectation since the idea of AQGs is to utilize the inherent heterogeneity of local optimization objectives.

5.2.3 Performance of the AQG with Client Dropouts. In this subsection, we focus on the setting of wireless networks with mobile devices, in which computation and communication are both extremely expensive and client dropouts are frequent. Given these constraints, the two-level AQG is applied in experiments with client dropouts as an adaptive solution for both communication and computation efficiency. Figure 9 shows the performance of the AQG with a client dropping rate $p$ of 0.2, 0.5, and 0.7. Experiment results demonstrate that both the AQG and Augmented AQG require
Fig. 9. Convergence of loss function with neural network ($p = 0.2, 0.5$, and $0.7$).

Fig. 10. Convergence of loss function with neural network ($p = 0.8$ and $0.9$).

fewer transmission bits compared with LAQ. Moreover, the Augmented AQG has a stronger ability to reduce transmission bits with the presence of such moderate client dropouts.

Figure 10 shows the performance of the AQG with a client dropping rate $p$ of 0.8 and 0.9. Experiments show that AQG manages to achieve stable convergence with ideal rates and, at the same time, significantly reduces transmission bits even when there are only about 10% of clients participating in gradient computation at each iteration. However, we notice that the augmented version of AQG fails to converge, with a dropping rate higher than 0.8. It may be because when the dropping rate is too high, the unbiased estimation in the Augmented AQG no longer remains accurate and even induces more noise into the training. Thus, the Augmented AQG is recommended for application in FL systems in which the client dropping scale is moderate. Given the fact that the client dropping rate is not likely to be so high in most practical systems, the Augmented AQG–based method is sufficient to address the dropping problem faced by FL.

6 CONCLUSION

This article focuses on communication efficiency and the client dropout issue in FL and proposes the AQG, which not only adaptively adjusts the quantization level depending on the local gradient’s update before transmission, but also appropriately amplifies transmitted gradients to limit the dropout noise. For communication efficiency, the key idea is to quantize less informative gradient with less bits and vice versa. Since the AQG fully utilizes the heterogeneity of local data distribution to reduce unnecessary transmission, it achieves a larger transmission reduction with non-IID data distribution, as expected. Compared with existing popular methods, the AQG leads to 18% to 50% of transmission reduction while keeping the desired convergence properties and shows robustness to large-scale client dropouts, with a dropping rate up to 90%. The Augmented AQG brings extra transmission reduction with moderate-scale client dropouts commonly seen in practical scenarios, which indicates the gradient amplification’s effectiveness in suppressing the noise introduced by client dropouts.
Due to the aforementioned superiorities, the AQG can be used jointly with other communication-efficient methods for FL architectures, such as gradient sparsification [18, 27], client selection based on local resources [13, 23, 32] and adaptively distributing subnetworks for heterogeneous clients [6, 9]. These superiorities and flexibility indicate great potential for the proposed FL framework with the AQG. Future works include deploying the AQG jointly with such techniques in practical FL systems.

APPENDICES

A MATHEMATICAL PROOF

A.1 Proof of Lemma 1

We first derive several preliminary formulas:

1. In the AQG, the aggregated global gradient consists of up-to-date gradients and reused gradients:

\[
\sum_{m=1}^{M} Q_{b_m}^{k} (\hat{g}_m^k) = \sum_{b=1}^{b_{\text{max}}} \sum_{m \in M_b^k} Q_{b_m} (\hat{g}_m^k) + \sum_{m \in M_b^{k-1}} Q_{b_m} (\hat{g}_m^{k-1})
\]

\[
= \sum_{m=1}^{M} Q_{b_{\text{max}}} (\hat{g}_m^k) + \sum_{b=1}^{b_{\text{max}}} \sum_{m \in M_b^k} \left[ Q_{b_m} (\hat{g}_m^k) - Q_{b_{\text{max}}} (\hat{g}_m^k) \right]
\]

\[
+ \sum_{m \in M_b^{k-1}} \left[ Q_{b_m} (\hat{g}_m^{k-1}) - Q_{b_{\text{max}}} (\hat{g}_m^{k-1}) \right].
\]  

(16)

2. From the update rule of the AQG, there is that

\[
\theta^{k+1} - \theta^k = -\alpha \sum_{m=1}^{M} Q_{b_m} (\hat{g}_m^k).
\]  

(17)

3. The definition of the quantization error results in

\[
\sum_{m=1}^{M} Q_{b_{\text{max}}} (\hat{g}_m^k) = \nabla f (\theta^k) - \sum_{m=1}^{M} \epsilon_{b_{\text{max}}} (\hat{g}_m^k).
\]  

(18)

4. With inequality \( \langle a, b \rangle \leq \frac{1}{2} \rho \| a \|_2^2 + \frac{1}{\rho} \| b \|_2^2 \) and (18), we have the following inequality:

\[
-\alpha \nabla f (\theta^k), \sum_{m=1}^{M} Q_{b_{\text{max}}} (\hat{g}_m^k)
\]

\[
= -\alpha \nabla f (\theta^k), \nabla f (\theta^k) - \sum_{m=1}^{M} \epsilon_{b_{\text{max}}} (\hat{g}_m^k)
\]

\[
= -\alpha \| \nabla f (\theta^k) \|_2^2 + \alpha \nabla f (\theta^k), \sum_{m=1}^{M} \epsilon_{b_{\text{max}}} (\hat{g}_m^k)
\]

\[
\leq -\alpha \| \nabla f (\theta^k) \|_2^2 + \frac{\alpha \rho_1}{2} \| \nabla f (\theta^k) \|_2^2 + \frac{\alpha}{2 \rho_1} \sum_{m=1}^{M} \epsilon_{b_{\text{max}}} (\hat{g}_m^k) \|_2^2.
\]  

(19)
(5) Under Assumption 1, there is
\[
    f(\theta^{k+1}) - f(\theta^k) 
\]
\[
\leq \langle \nabla f(\theta^k), \theta^{k+1} - \theta^k \rangle + \frac{L}{2} \| \theta^{k+1} - \theta^k \|_2^2 
\]
\[
\leq \sum_{m=1}^{M} Q_{b_m}^{\beta} (\hat{\theta}_m^k) + \frac{L}{2} \| \theta^{k+1} - \theta^k \|_2^2 
\]
\[
\leq \sum_{m=1}^{M} Q_{b_m} (\hat{\theta}_m^k) + \frac{L}{2} \| \theta^{k+1} - \theta^k \|_2^2 
\]
\[
+ \alpha \left\{ \sum_{b=1}^{b_{\text{max}}} \sum_{m \in \mathcal{Z}_b} \left[ Q_{\hat{b}_m^k} (\hat{\theta}_m^k) - Q_{b_{\text{max}}} (\hat{\theta}_m^k) \right] + \sum_{m \in \mathcal{Z}_b} \left[ Q_{\hat{b}_m^k}^{\beta}(\hat{\theta}_m^{k-1}) - Q_{b_{\text{max}}} (\hat{\theta}_m^k) \right] \right\}. 
\]
\[
\leq \sum_{m=1}^{M} Q_{b_{\text{max}}} (\hat{\theta}_m^k) + \frac{L}{2} \| \theta^{k+1} - \theta^k \|_2^2 + \frac{\alpha}{2} \| \nabla f(\theta^k) \|_2^2 
\]
\[
+ \frac{\alpha}{2} \left\| \sum_{b=1}^{b_{\text{max}}} \sum_{m \in \mathcal{Z}_b} \left[ Q_{\hat{b}_m^k} (\hat{\theta}_m^k) - Q_{b_{\text{max}}} (\hat{\theta}_m^k) \right] + \sum_{m \in \mathcal{Z}_b} \left[ Q_{\hat{b}_m^k}^{\beta}(\hat{\theta}_m^{k-1}) - Q_{b_{\text{max}}} (\hat{\theta}_m^k) \right] \right\|_2^2. 
\]

Then, given the following Lyapunov function of AQG:
\[
\nabla(\theta^k) = f(\theta^k) - f(\theta^*) + \sum_{d=1}^{D} \sum_{j=d}^{D} \beta_d \| \theta^{k+1-d} - \theta^{d-k-1} \|_2^2 
\]
if we set \( \beta_d = \frac{1}{D} \sum_{j=d}^{D} \beta_j, \forall d \in \{1, \ldots, D\} \), then:
\[
\nabla(\theta^k) = f(\theta^k) - f(\theta^*) + \sum_{d=1}^{D} \beta_d \| \theta^{k+1-d} - \theta^{d-k-1} \|_2^2. 
\]

Therefore, the Lyapunov function results in the following inequality:
\[
\nabla(\theta^{k+1}) - \nabla(\theta^k) 
\]
\[
= f(\theta^{k+1}) - f(\theta^k) 
\]
\[
+ \sum_{d=1}^{D} \beta_d \| \theta^{k+1-(d-1)} - \theta^{d-k-1} \|_2^2 - \sum_{d=1}^{D} \beta_d \| \theta^{k+1-d} - \theta^{d-k} \|_2^2 
\]
\[
= f(\theta^{k+1}) - f(\theta^k) + \sum_{d=1}^{D} \beta_d \| \theta^{k+1-d} - \theta^{d-k} \|_2^2 
\]
\[
+ \sum_{d=1}^{D-1} (\beta_{d+1} - \beta_d) \| \theta^{k+1-d} - \theta^{d-k} \|_2^2 - \beta_D \| \theta^{k+1-D} - \theta^{D-k} \|_2^2 
\]
\[
\leq -\alpha \left\{ \nabla f(\theta^k), \sum_{m=1}^{M} Q_{b_{\text{max}}} (\hat{\theta}_m^k) \right\} + \frac{\alpha}{2} \| \nabla f(\theta^k) \|_2^2 
\]
\[
+ \frac{\alpha}{2} \left\| \sum_{b=1}^{b_{\text{max}}} \sum_{m \in \mathcal{Z}_b} \left[ Q_{\hat{b}_m^k} (\hat{\theta}_m^k) - Q_{b_{\text{max}}} (\hat{\theta}_m^k) \right] + \sum_{m \in \mathcal{Z}_b} \left[ Q_{\hat{b}_m^k}^{\beta}(\hat{\theta}_m^{k-1}) - Q_{b_{\text{max}}} (\hat{\theta}_m^k) \right] \right\|_2^2 
\]
\[ + \sum_{d=1}^{D-1} (\beta_{d+1} - \beta_d) \|\theta^{k+1-d} - \theta^{k-d}\|_2^2 - \beta_D \|\theta^{k+1-D} - \theta^{k-D}\|_2^2 \]
\[ + \left( \frac{L}{2} + \beta_1 \right) \|\theta^{k+1} - \theta^k\|_2^2 \]
\[= -\alpha \left( \nabla f(\theta^k), \sum_{m=1}^{M} Q_{b_{\text{max}}}(\hat{g}_m^k) \right) + \frac{\alpha}{2} \|\nabla f(\theta^k)\|_2^2 \]
\[+ \sum_{d=1}^{D-1} (\beta_{d+1} - \beta_d) \|\theta^{k+1-d} - \theta^{k-d}\|_2^2 - \beta_D \|\theta^{k+1-D} - \theta^{k-D}\|_2^2 \]
\[+ \frac{\alpha}{2} \sum_{b=1}^{b_{\text{max}}} \sum_{m \in \mathcal{M}_b^k} \left[ Q_{b_m^k}(\hat{g}_m^k) - Q_{b_{\text{max}}}(\hat{g}_m^k) \right] + \sum_{m \in \mathcal{M}_0^k} \left[ Q_{b_{m-1}^k}(\hat{g}_m^{k-1}) - Q_{b_{\text{max}}}(\hat{g}_m^k) \right] \|_2^2 + A_1, \quad (23) \]

where

\[ A_1 = \left( \frac{L}{2} + \beta_1 \right) \alpha \left[ \sum_{m=1}^{M} Q_{b_{\text{max}}}(\hat{g}_m^k) + \sum_{b=1}^{b_{\text{max}}} \sum_{m \in \mathcal{M}_b^k} \left[ Q_{b_m^k}(\hat{g}_m^k) - Q_{b_{\text{max}}}(\hat{g}_m^k) \right] + \sum_{m \in \mathcal{M}_0^k} \left[ Q_{b_{m-1}^k}(\hat{g}_m^{k-1}) - Q_{b_{\text{max}}}(\hat{g}_m^k) \right] \|_2^2 \]

From Young’s Equality \( \|a + b\|_2^2 \leq (1 + \rho)\|a\|_2^2 + (1 + \rho^{-1})\|b\|_2^2 \), there is that

\[ A_1 \leq \left( \frac{L}{2} + \beta_1 \right) (1 + \rho_2^{-1}) \alpha^2 \sum_{b=1}^{b_{\text{max}}} \sum_{m \in \mathcal{M}_b^k} \left[ Q_{b_m^k}(\hat{g}_m^k) - Q_{b_{\text{max}}}(\hat{g}_m^k) \right] + \sum_{m \in \mathcal{M}_0^k} \left[ Q_{b_{m-1}^k}(\hat{g}_m^{k-1}) - Q_{b_{\text{max}}}(\hat{g}_m^k) \right] \|_2^2 \]
\[+ \left( \frac{L}{2} + \beta_1 \right) (1 + \rho_2) \alpha^2 \sum_{m=1}^{M} Q_{b_{\text{max}}}(\hat{g}_m^k) \|_2^2. \quad (24) \]

From \( \| \sum_{i=1}^{n} a_i \|_2^2 \leq n \sum_{i=1}^{n} \|a_i\|_2^2 \), there is that

\[ \sum_{b=1}^{b_{\text{max}}} \sum_{m \in \mathcal{M}_b^k} \left[ Q_{b_m^k}(\hat{g}_m^k) - Q_{b_{\text{max}}}(\hat{g}_m^k) \right] + \sum_{m \in \mathcal{M}_0^k} \left[ Q_{b_{m-1}^k}(\hat{g}_m^{k-1}) - Q_{b_{\text{max}}}(\hat{g}_m^k) \right] \|_2^2 \]
\[\leq M \sum_{b=1}^{b_{\text{max}}} \sum_{m \in \mathcal{M}_b^k} \left[ Q_{b_m^k}(\hat{g}_m^k) - Q_{b_{\text{max}}}(\hat{g}_m^k) \right] \|_2^2 + M \sum_{m \in \mathcal{M}_0^k} \left[ Q_{b_{m-1}^k}(\hat{g}_m^{k-1}) - Q_{b_{\text{max}}}(\hat{g}_m^k) \right] \|_2^2 \]
\[= 2M \sum_{b=1}^{b_{\text{max}}} \sum_{m \in \mathcal{M}_b^k} \left[ Q_{b_m^k}(\hat{g}_m^k) \right] \|_2^2 + 2M \sum_{m \in \mathcal{M}_0^k} \left[ Q_{b_{m-1}^k}(\hat{g}_m^{k-1}) - Q_{b_{\text{max}}}(\hat{g}_m^k) \right] \|_2^2. \quad (25) \]

Therefore, with (24) and (25):

\[ \nabla(\theta^{k+1}) - \nabla(\theta^k) \leq -\alpha \left( \nabla f(\theta^k), \sum_{m=1}^{M} Q_{b_{\text{max}}}(\hat{g}_m^k) \right) + \frac{\alpha}{2} \|\nabla f(\theta^k)\|_2^2 \]
\[+ \left( \frac{L}{2} + \beta_1 \right) (1 + \rho_2) \alpha^2 \sum_{m=1}^{M} Q_{b_{\text{max}}}(\hat{g}_m^k) \|_2^2 + \sum_{d=1}^{D-1} (\beta_{d+1} - \beta_d) \|\theta^{k+1-d} - \theta^{k-d}\|_2^2 - \beta_D \|\theta^{k+1-D} - \theta^{k-D}\|_2^2 \]
\[+ \left[ \frac{\alpha}{2} + \left( \frac{L}{2} + \beta_1 \right) (1 + \rho_2^{-1}) \alpha^2 \right] \sum_{b=1}^{b_{\text{max}}} \sum_{m \in \mathcal{M}_b^k} \left[ Q_{b_m^k}(\hat{g}_m^k) - Q_{b_{\text{max}}}(\hat{g}_m^k) \right] + \sum_{m \in \mathcal{M}_0^k} \left[ Q_{b_{m-1}^k}(\hat{g}_m^{k-1}) - Q_{b_{\text{max}}}(\hat{g}_m^k) \right] \|_2^2 \]
\[
\begin{align*}
\leq -\alpha \left( \nabla f(\theta^k), \sum_{m=1}^{M} Q_{b_{\max}}(\hat{g}_m^k) \right) + \frac{\alpha}{2} \nabla f(\theta^k) \parallel^2 + (\frac{L}{2} + \beta_1)(1 + \rho_2)\alpha^2 \sum_{m=1}^{M} Q_{b_{\max}}(\hat{g}_m^k) \parallel^2 \\
+ \sum_{d=1}^{D-1} (\beta_{d+1} - \beta_d) \parallel\theta^{k+1-d} - \theta^{k-d} \parallel^2 - \beta_D \parallel\theta^{k+1-D} - \theta^{k-D} \parallel^2 \\
+ 2 \left[ \frac{\alpha}{2} + \left( \frac{L}{2} + \beta_1 \right)(1 + \rho_2^{-1})\alpha^2 \right] M \left( \sum_{b=1}^{b_{\max}} \sum_{m \in \mathbb{M}_b^k} \parallel f_{b_{\max}}(\hat{g}_m^k) \parallel^2 + \sum_{b=1}^{b_{\max}} \sum_{m \in \mathbb{M}_b^k} \parallel f_{b_{\max}}(\hat{g}_m^k) \parallel^2 \right) \\
+ \left[ \frac{\alpha}{2} + \left( \frac{L}{2} + \beta_1 \right)(1 + \rho_2^{-1})\alpha^2 \right] M \sum_{m \in \mathbb{M}_0^k} \parallel Q_{b_{\max}}(\hat{g}_m^{k-1}) - Q_{b_{\max}}(\hat{g}_m^k) \parallel^2 .
\end{align*}
\] (26)

With the precision selection criterion (5), we have that

\[
M \sum_{m \in \mathbb{M}_0^k} \parallel Q_{b_{\max}}(\hat{g}_m^{k-1}) - Q_{b_{\max}}(\hat{g}_m^k) \parallel^2
\leq \frac{M^2}{\alpha^2M^2} \sum_{d=1}^{D} \xi_d \parallel\theta^{k+1-d} - \theta^{k-d} \parallel^2 + 3M \sum_{m \in \mathbb{M}_0^k} \left( \parallel \epsilon_{b_{\max}}(\hat{g}_m^{k-1}) \parallel^2 + \parallel \epsilon_{b_{\max}}(\hat{g}_m^k) \parallel^2 \right) ,
\] (27)

then,

\[
\nabla(\theta^{k+1}) - \nabla(\theta^k)
\leq -\alpha \left( \nabla f(\theta^k), \sum_{m=1}^{M} Q_{b_{\max}}(\hat{g}_m^k) \right) + \frac{\alpha}{2} \nabla f(\theta^k) \parallel^2 + (\frac{L}{2} + \beta_1)(1 + \rho_2)\alpha^2 \sum_{m=1}^{M} Q_{b_{\max}}(\hat{g}_m^k) \parallel^2 \\
+ \sum_{d=1}^{D-1} (\beta_{d+1} - \beta_d) \parallel\theta^{k+1-d} - \theta^{k-d} \parallel^2 - \beta_D \parallel\theta^{k+1-D} - \theta^{k-D} \parallel^2 \\
+ 2 \left[ \frac{\alpha}{2} + \left( \frac{L}{2} + \beta_1 \right)(1 + \rho_2^{-1})\alpha^2 \right] M \left( \sum_{b=1}^{b_{\max}} \sum_{m \in \mathbb{M}_b^k} \parallel f_{b_{\max}}(\hat{g}_m^k) \parallel^2 + \sum_{b=1}^{b_{\max}} \sum_{m \in \mathbb{M}_b^k} \parallel f_{b_{\max}}(\hat{g}_m^k) \parallel^2 \right) \\
+ \left[ \frac{\alpha}{2} + \left( \frac{L}{2} + \beta_1 \right)(1 + \rho_2^{-1})\alpha^2 \right] M \sum_{m \in \mathbb{M}_0^k} \left( \parallel \epsilon_{b_{\max}}(\hat{g}_m^{k-1}) \parallel^2 + \parallel \epsilon_{b_{\max}}(\hat{g}_m^k) \parallel^2 \right) \] (28)

\[
\leq \left( -\frac{\alpha}{2} + \frac{\alpha \rho_1}{2} \right) \nabla f(\theta^k) \parallel^2 + \frac{\alpha}{2\rho_1} \sum_{m=1}^{M} \epsilon_{b_{\max}}(\hat{g}_m^k) \parallel^2 + (\frac{L}{2} + \beta_1)(1 + \rho_2)\alpha^2 \sum_{m=1}^{M} Q_{b_{\max}}(\hat{g}_m^k) \parallel^2 \\
+ \sum_{d=1}^{D-1} (\beta_{d+1} - \beta_d) \parallel\theta^{k+1-d} - \theta^{k-d} \parallel^2 - \beta_D \parallel\theta^{k+1-D} - \theta^{k-D} \parallel^2 \\
+ \left[ \frac{\alpha}{2} + \left( \frac{L}{2} + \beta_1 \right)(1 + \rho_2^{-1})\alpha^2 \right] \frac{1}{\alpha^2} \sum_{d=1}^{D} \xi_d \parallel\theta^{k+1-d} - \theta^{k-d} \parallel^2 \\
+ \left[ \frac{\alpha}{2} + \left( \frac{L}{2} + \beta_1 \right)(1 + \rho_2^{-1})\alpha^2 \right] M \sum_{m \in \mathbb{M}_0^k} \left( \parallel \epsilon_{b_{\max}}(\hat{g}_m^{k-1}) \parallel^2 + \parallel \epsilon_{b_{\max}}(\hat{g}_m^k) \parallel^2 \right)
\]
\begin{align}
&+ 2 \left[ \frac{\alpha}{2} + \left( \frac{L}{2} + \beta_1 \right) (1 + \rho_2^{-1}) \alpha^2 \right] M \left( \sum_{b=1}^{b_{\text{max}}} \sum_{m \in \mathcal{M}_b^k} \| \xi_{b,m}^k (\mathbf{g}_m^k) \|_2^2 + \sum_{b=1}^{b_{\text{max}}} \sum_{m \in \mathcal{M}_b^k} \| \xi_{b,max} (\mathbf{g}_m^k) \|_2^2 \right) \tag{29} \\
&= \left( -\frac{\alpha}{2} + \frac{\alpha \rho_1}{2} \right) \| \nabla f (\theta^k) \|_2^2 + \frac{\alpha}{2 \rho_1} \left( \sum_{m=1}^{M} \xi_{b,max} (\mathbf{g}_m^k) \right)^2 + \left( \frac{L}{2} + \beta_1 \right) (1 + \rho_2) \alpha^2 \left\| \nabla f (\theta^k) - \sum_{m=1}^{M} \xi_{b,max} (\mathbf{g}_m^k) \right\|^2_2 \\
&+ \sum_{d=1}^{D-1} (\beta_{d+1} - \beta_d) \| \theta^{k+1-d} - \theta^{k-d} \|_2^2 - \beta_D \| \theta^{k+1-D} - \theta^{k-D} \|_2^2 \\
&+ \left[ \frac{\alpha}{2} + \left( \frac{L}{2} + \beta_1 \right) (1 + \rho_2^{-1}) \alpha^2 \right] \frac{1}{\alpha^2} \sum_{d=1}^{D} \xi_d \| \theta^{k+1-d} - \theta^{k-d} \|_2^2 \\
&+ 3 \left[ \frac{\alpha}{2} + \left( \frac{L}{2} + \beta_1 \right) (1 + \rho_2^{-1}) \alpha^2 \right] M \sum_{m \in \mathcal{M}_b^k} \left( \| \xi_{b,max} (\mathbf{g}_m^k) \|_2^2 + \| \xi_{b,b} (\mathbf{g}_m^k) \|_2^2 \right) \\
&+ 2 \left[ \frac{\alpha}{2} + \left( \frac{L}{2} + \beta_1 \right) (1 + \rho_2^{-1}) \alpha^2 \right] M \left( \sum_{b=1}^{b_{\text{max}}} \sum_{m \in \mathcal{M}_b^k} \| \xi_{b,b} (\mathbf{g}_m^k) \|_2^2 + \sum_{b=1}^{b_{\text{max}}} \sum_{m \in \mathcal{M}_b^k} \| \xi_{b,b} (\mathbf{g}_m^k) \|_2^2 \right). \tag{30}\end{align}

Ignoring the quantization errors, the following three inequalities should hold simultaneously for \( d \in \{1, \ldots, D\} \) in order to ensure that \( \nabla (\theta^{k+1}) - \nabla (\theta^k) \leq 0 \):

\begin{align}
&- \frac{\alpha}{2} + \frac{1}{2} \alpha \rho_1 + (L + 2 \beta_1) (1 + \rho_2) \alpha^2 \leq 0 \\
&\left[ \frac{\alpha}{2} + \left( \frac{L}{2} + \beta_1 \right) (1 + \rho_2^{-1}) \alpha^2 \right] \frac{\xi_d}{\alpha^2} - \beta_D \leq 0 \\
&\left[ \frac{\alpha}{2} + \left( \frac{L}{2} + \beta_1 \right) (1 + \rho_2^{-1}) \alpha^2 \right] \frac{\xi_d}{\alpha^2} + \beta_{d+1} - \beta_d \leq 0. \tag{32}\end{align}

(32) provides the choice of range in terms of stepsize \( \alpha \) and weights \( \{ \xi_d \}_{d=1}^{D} \):

\begin{align}
&\sum_{d=1}^{D} \xi_d \leq \min \left\{ \frac{1 - \rho_1}{4 (1 + \rho_2)} , \frac{1}{2 (1 + \rho_2^{-1})} \right\} \tag{33a} \\
&\alpha \leq \min \left\{ \frac{2}{L} \left[ \frac{1 - \rho_1}{4 (1 + \rho_2)} - \sum_{d=1}^{D} \xi_d \right], \frac{2}{L} \left[ \frac{1}{2 (1 + \rho_2^{-1})} - \sum_{d=1}^{D} \xi_d \right] \right\}. \tag{33b}\end{align}
This analysis indicates that there is no need to modify these two parameters involved in LAQ [15].

A.2 Proof of Lemma 2
Under Assumption 2:

\[
\begin{aligned}
\mathbb{V}(\theta^{k+1}) - \mathbb{V}(\theta^k) &\leq 2\mu \left[ -\frac{\alpha}{2} + \frac{\alpha \rho_1}{2} + (L + 2\beta_1)(1 + \rho_2)\alpha^2 \right] |f(\theta^k) - f(\theta^*)| \\
&+ \left[ \frac{\alpha}{2\rho_1} + (L + 2\beta_1)(1 + \rho_2)\alpha^2 \right] \left\| \sum_{m=1}^M \varepsilon_{\text{max}}(\hat{g}_m^k) \right\|_2^2 \\
&+ \beta_D \left\{ \left[ \frac{\alpha}{2} + \left( \frac{L}{2} + \beta_1 \right)(1 + \rho_2^{-1})\alpha^2 \right] \frac{\xi_D}{\alpha^2\beta_D} - 1 \right\} \left\| \theta^{k+1-D} - \theta^{k-D} \right\|^2_2 \\
&+ \sum_{d=1}^{D-1} \beta_d \left\{ \left[ \frac{\alpha}{2} + \left( \frac{L}{2} + \beta_1 \right)(1 + \rho_2^{-1})\alpha^2 \right] \frac{\xi_d}{\alpha^2\beta_d} + \frac{\beta_{d+1}}{\beta_d} - 1 \right\} \left\| \theta^{k+1-d} - \theta^{k-d} \right\|^2_2 \\
&+ 3 \left[ \frac{\alpha}{2} + \left( \frac{L}{2} + \beta_1 \right)(1 + \rho_2^{-1})\alpha^2 \right] M \sum_{m \in \mathcal{M}_b} \left( \left\| \varepsilon_{\text{max}}(\hat{g}_m^{k-1}) \right\|_2^2 + \left\| \varepsilon_{\text{max}}(g_m^k) \right\|_2^2 \right)^{\frac{1}{2}} \\
&+ 2 \left[ \frac{\alpha}{2} + \left( \frac{L}{2} + \beta_1 \right)(1 + \rho_2^{-1})\alpha^2 \right] M \left( \sum_{b=1}^{b_{\text{max}}} \sum_{m \in \mathcal{M}_b} \left\| \hat{g}_m^{k} \right\|_2^2 + \sum_{m \in \mathcal{M}_b} \left\| \varepsilon_{\text{max}}(\hat{g}_m^{k}) \right\|_2^2 \right)^{\frac{1}{2}}. 
\end{aligned}
\]

Let \( c \) and \( B \) be defined as

\[
\begin{aligned}
c &\equiv \min_{d=1, \ldots, D} \left\{ 2\mu \left[ \frac{\alpha}{2} - \frac{\alpha \rho_1}{2} - (L + 2\beta_1)(1 + \rho_2)\alpha^2 \right], 1 - \left[ \frac{\alpha}{2} + \left( \frac{L}{2} + \beta_1 \right)(1 + \rho_2^{-1})\alpha^2 \right] \frac{\xi_D}{\alpha^2\beta_D}, \right. \\
1 - \left[ &\frac{\alpha}{2} + \left( \frac{L}{2} + \beta_1 \right)(1 + \rho_2^{-1})\alpha^2 \right] \frac{\xi_d}{\alpha^2\beta_d} + \frac{\beta_{d+1}}{\beta_d} \right\}. \\
\end{aligned}
\]

\[
\begin{aligned}
B &\equiv \max \left\{ \frac{\alpha}{2\rho_1} + (L + 2\beta_1)(1 + \rho_2)\alpha^2, 3M \left[ \frac{\alpha}{2} + \left( \frac{L}{2} + \beta_1 \right)(1 + \rho_2^{-1})\alpha^2 \right] \right\}. 
\end{aligned}
\]

Then:

\[
\begin{aligned}
\mathbb{V}(\theta^{k+1}) - \mathbb{V}(\theta^k) &\leq -c \left[ f(\theta^k) - f(\theta^*) + \sum_{d=1}^D \beta_d \left\| \theta^{k+1-d} - \theta^{k-d} \right\|_2^2 \right] \\
&+ B \left\| \sum_{m=1}^M \varepsilon_{\text{max}}(\hat{g}_m^k) \right\|_2^2 + B \sum_{m \in \mathcal{M}_b} \left( \left\| \varepsilon_{\text{max}}(\hat{g}_m^{k-1}) \right\|_2^2 + \left\| \varepsilon_{\text{max}}(g_m^k) \right\|_2^2 \right)^{\frac{1}{2}} \\
&+ B \left( \sum_{b=1}^{b_{\text{max}}} \sum_{m \in \mathcal{M}_b} \left\| \hat{g}_m^{k} \right\|_2^2 + \sum_{m \in \mathcal{M}_b} \left\| \varepsilon_{\text{max}}(\hat{g}_m^{k}) \right\|_2^2 \right)^{\frac{1}{2}}. 
\end{aligned}
\]

(36)
\begin{align*}
&= -c \nabla \mathcal{V}(\theta^k) \\
&+ B \left\| \sum_{m=1}^{M} \varepsilon_{b_{\text{max}}} \left( \hat{g}_m^k \right) \right\|_2^2 + B \sum_{m \in \mathcal{M}_0^k} \left( \left\| \varepsilon_{b_{\text{max}}} \left( \hat{g}_{m}^{k-1} \right) \right\|_2^2 + \left\| \varepsilon_{b_{\text{max}}} \left( g_m^k \right) \right\|_2^2 \right) \\
&+ B \left( \sum_{b=1}^{b_{\text{max}}} \sum_{m \in \mathcal{M}_b^k} \left\| \varepsilon_{b_{\text{max}}} \left( \hat{g}_m^k \right) \right\|_2^2 + \sum_{b=1}^{b_{\text{max}}} \sum_{m \in \mathcal{M}_b^k} \left\| \varepsilon_{b_{\text{max}}} \left( g_m^k \right) \right\|_2^2 \right).
\end{align*}

Thus,
\begin{align*}
\mathcal{V}(\theta^{k+1}) &\leq (1-c)\mathcal{V}(\theta^k) \\
&+ B \left\| \sum_{m=1}^{M} \varepsilon_{b_{\text{max}}} \left( \hat{g}_m^k \right) \right\|_2^2 + B \sum_{m \in \mathcal{M}_0^k} \left( \left\| \varepsilon_{b_{\text{max}}} \left( \hat{g}_{m}^{k-1} \right) \right\|_2^2 + \left\| \varepsilon_{b_{\text{max}}} \left( g_m^k \right) \right\|_2^2 \right) \\
&+ B \left( \sum_{b=1}^{b_{\text{max}}} \sum_{m \in \mathcal{M}_b^k} \left\| \varepsilon_{b_{\text{max}}} \left( \hat{g}_m^k \right) \right\|_2^2 + \sum_{b=1}^{b_{\text{max}}} \sum_{m \in \mathcal{M}_b^k} \left\| \varepsilon_{b_{\text{max}}} \left( g_m^k \right) \right\|_2^2 \right). \tag{37}
\end{align*}

\section*{A.3 Proof of Theorem 1}

This part proves that (15) holds for any \( k \geq 0 \) if the following inequalities are satisfied:
\begin{align*}
4BMP \tau_{b_{\text{max}}}^2 + BMP \sum_{b=1}^{b_{\text{max}}} \tau_{b_m}^2 &\leq \sigma_2 - \sigma_1. \tag{39a} \\
\frac{24L^2}{\mu} + 18 \tau_{b_{\text{max}}-b_m}^2 + 3 \tau_{b_{\text{max}}}^2 &\leq \sigma_2. \tag{39b} \\
\alpha &\geq \frac{\mu}{4L^2M^2}. \tag{39c}
\end{align*}

It is assumed that for any \( k \geq 1 \), (15) holds for \( k - 1 \). Let \( \sigma_1 = 1-c \); there is that
\begin{align*}
\mathcal{V}(\theta^{k+1}) &\leq \sigma_1 \mathcal{V}(\theta^k) \\
&+ B \left\| \sum_{m=1}^{M} \varepsilon_{b_{\text{max}}} \left( \hat{g}_m^k \right) \right\|_2^2 + B \sum_{m \in \mathcal{M}_0^k} \left( \left\| \varepsilon_{b_{\text{max}}} \left( \hat{g}_{m}^{k-1} \right) \right\|_2^2 + \left\| \varepsilon_{b_{\text{max}}} \left( g_m^k \right) \right\|_2^2 \right) \\
&+ B \left( \sum_{b=1}^{b_{\text{max}}} \sum_{m \in \mathcal{M}_b^k} \left\| \varepsilon_{b_{\text{max}}} \left( \hat{g}_m^k \right) \right\|_2^2 + \sum_{b=1}^{b_{\text{max}}} \sum_{m \in \mathcal{M}_b^k} \left\| \varepsilon_{b_{\text{max}}} \left( g_m^k \right) \right\|_2^2 \right) \tag{40} \\
&\leq \sigma_1 \sigma_2^{-1} \mathcal{V}(\theta^1) + 4BMP \tau_{b_{\text{max}}}^2 \sigma_2^{-1} \mathcal{V}(\theta^1) + BMP \sum_{b=1}^{b_{\text{max}}} \tau_{b_m}^2 \sigma_2^{-1} \mathcal{V}(\theta^1) \leq \sigma_2 \mathcal{V}(\theta^1), \tag{41}
\end{align*}

where \( \sigma_2 \geq \sigma_1 + 4BMP \tau_{b_{\text{max}}}^2 + BMP \sum_{b=1}^{b_{\text{max}}} \tau_{b_m}^2 \).
Under Assumptions 1 and 2, the following inequality holds for any $\theta_1$ and $\theta_2$ because of convexity:

$$
\| \nabla f_m(\theta_1) - \nabla f_m(\theta_2) \|_\infty \leq \left\| \sum_{m=1}^M (\nabla f_m(\theta_1) - \nabla f_m(\theta_2)) \right\|_\infty \\
= \| \nabla f(\theta_1) - \nabla f(\theta_2) \|_\infty \\
\leq L \| \theta_1 - \theta_2 \|_\infty, \ \forall m \in \{1,\ldots,M\}.
$$

With (42) and the proposed precision selection criterion (5), there is that

$$
\left\| \nabla f_m(\theta^{k+1}) - Q_{b_{m}(\hat{\theta}^k)}(\dot{\theta}^{-1}) \right\|_\infty \\
= \left\| \nabla f_m(\theta^{k+1}) - f_m(\theta^k) - f_m(\theta^k) - Q_{b_{m}max}(\dot{\theta}^{-1}) \right\|_\infty \\
\leq \left\| \nabla f_m(\theta^{k+1}) - f_m(\theta^k) \right\|_\infty + \| f_m(\theta^k) - Q_{b_{m}max}(\dot{\theta}^{-1}) \|_\infty + \| Q_{b_{m}max}(\dot{\theta}^{-1}) - Q_{b_{m}}(\dot{\theta}^{-1}) \|_\infty \\
\leq L \| \theta^{k+1} - \theta^k \|_\infty + \| e_{b_{m}}(\dot{\theta}^{-1}) \|_\infty
$$

$$
+ \sqrt{\frac{1}{\alpha^2 M^2}} \sum_{d=1}^D \varepsilon_d \| \theta^{k+1-d} - \theta^{k-d} \|_2^2 + 3 \left( \| e_{b_{m}}(\dot{\theta}^{-1}) \|_2^2 + \| e_{b_{m}}(\dot{\theta}^{-1}) \|_2^2 \right)
$$

$$
\leq L \left( \| \theta^{k+1} - \theta^* \|_2^2 + \| \theta^* - \theta^k \|_2^2 + \| e_{b_{m}}(\dot{\theta}^{-1}) \|_\infty \right)
$$

$$
+ \sqrt{\frac{1}{\alpha^2 M^2}} \sum_{d=1}^D \varepsilon_d \| \theta^{k+1-d} - \theta^{k-d} \|_2^2 + 3 \left( \| e_{b_{m}}(\dot{\theta}^{-1}) \|_2^2 + \| e_{b_{m}}(\dot{\theta}^{-1}) \|_2^2 \right)
$$

$$
\leq L \left( \| \theta^{k+1} - \theta^* \|_2^2 + \| \theta^* - \theta^k \|_2^2 + \| e_{b_{m}}(\dot{\theta}^{-1}) \|_\infty \right)
$$

Under Assumption 2 with (13),

$$
\left\| \nabla f_m(\theta^{k+1}) - Q_{b_{m}(\dot{\theta}^{-1})}(\dot{\theta}^{-1}) \right\|_\infty^2 \\
\leq \frac{12 L^2}{\mu} \left( f(\theta^{k+1}) - f(\theta^*) + f(\theta^k) - f(\theta^*) \right) + 3 \| e_{b_{m}}(\dot{\theta}^{-1}) \|_\infty^2
$$

$$
+ \frac{3}{\alpha^2 M^2} \sum_{d=1}^D \varepsilon_d \| \theta^{k+1-d} - \theta^{k-d} \|_2^2 + 9 \left( \| e_{b_{m}}(\dot{\theta}^{-1}) \|_\infty^2 + \| e_{b_{m}}(\dot{\theta}^{-1}) \|_\infty^2 \right)
$$

$$
\leq \frac{12 L^2}{\mu} \left( f(\theta^{k+1}) - f(\theta^*) + f(\theta^k) - f(\theta^*) + \frac{\mu}{4 L^2 \alpha^2 M^2} \sum_{d=1}^D \varepsilon_d \| \theta^{k+1-d} - \theta^{k-d} \|_2^2 \right)
$$

$$
+ 18 \varepsilon_{b_{m}}(\dot{\theta}^{-1}) \sigma_2^{-1}(\dot{\theta}^1) + 3 \varepsilon_{b_{m}}(\dot{\theta}^{-1}) \sigma_2^{-1}(\dot{\theta}^1).
$$

With $\alpha \geq \frac{\mu}{4 L^2 M^2}, \frac{\mu \varepsilon_2}{4 L^2 \alpha^2 M^2} \leq \frac{\varepsilon_d}{\alpha} \leq \sum_{j=d}^D \frac{\varepsilon_j}{\alpha}$:

$$
\left\| \nabla f_m(\theta^{k+1}) - Q_{b_{m}}(\dot{\theta}^{-1}) \right\|_\infty^2
$$
\[ \leq \frac{12L^2}{\mu} \left[ f(\theta^{k+1}) - f(\theta^*) + f(\theta^k) - f(\theta^*) + \sum_{d=1}^{D} \sum_{j=d}^{D} \frac{\xi_j}{\sigma} \| \theta^{k+1-d} - \theta^{k-d} \|_2^2 \right] \]
\[ + 18P\tau^2_{b_{\text{max}}-b_m} \sigma_2^{k-1}\gamma(\theta^1) + 3P\tau^2_{b_{\text{max}}} \sigma_2^{k-1}\gamma(\theta^1) \]
\[ \leq \frac{12L^2}{\mu} \left[ V(\theta^{k+1}) + V(\theta^k) + 18P\tau^2_{b_{\text{max}}-b_m} \sigma_2^{k-1}\gamma(\theta^1) + 3P\tau^2_{b_{\text{max}}} \sigma_2^{k-1}\gamma(\theta^1) \right] \]
\[ \leq \frac{24L^2}{\mu} \sigma_2^{k-1}\gamma(\theta^1) + 18P\tau^2_{b_{\text{max}}-b_m} \sigma_2^{k-1}\gamma(\theta^1) + 3P\tau^2_{b_{\text{max}}} \sigma_2^{k-1}\gamma(\theta^1) \]
\[ = \left( \frac{24L^2}{\mu} + 18\tau^2_{b_{\text{max}}-b_m} + 3\tau^2_{b_{\text{max}}} \right) P\sigma_2^{k-1}\gamma(\theta^1) \leq P\sigma_2^{k-1}\gamma(\theta^1). \] (48)

Thus,
\[ \| \varepsilon_b(g_m^k) \|_2^2 \leq \tau_b^2 \| \nabla f_m(\theta^{k+1}) - Q_{b_{	ext{max}}}(\hat{g}_m^k) \|_2^2 \leq P\tau_b^2 \sigma_2^{k-1}\gamma(\theta^1). \] (49)

B SUPPLEMENTARY EXPERIMENTAL INFORMATION

B.1 Hyperparameters

| Dataset | MNIST | CIFAR10 |
|---------|-------|---------|
| Model   | FC    | ResNet18|
| Hidden Size | [784, 10] | [64, 128, 256, 512] |
| Data Distribution | IID | non-IID |
| IID | non-IID |
| Global Epoch \( E \) | 4,000 | 4,000 |
| 5,000 | 100 |
| Local Batch Size \( B \) | / | 100 |
| 100 | |
| Optimizer | GD | GD |
| SGD | SGD |
| Momentum | / | 0.9 |
| 1.0 | 0.9 |
| Weight Decay | / | 5.00E-04 |
| 6.00E-04 | |
| Learning Rate \( \eta \) | 0.02 | 0.02 |
| 0.1 | 0.1 |

B.2 Experiment Results with IID/Non-IID CIFAR10

Note that for experiments with CIFAR10 and ResNet18, we adopt stochastic gradient descend (SGD) and we add two state-of-the-art baselines: AdaQuantFL [14] and STC [24]. The two-level AQG represents an AQG with 6/4 bit transmission for IID CIFAR10 and 5/3 bit transmission for non-IID CIFAR10.

From Figures 11 and 12, we can conclude that the proposed AQG achieves a significant transmission reduction on more complex datasets and models as compared with baselines, including QSGD, fixed-bit LAQ, and AdaQuantFL. Specifically, the transmission reduction is 18.13% for IID CIFAR10 and 25.53% for non-IID CIFAR10, as shown in Figures 11(c) and 12(c), respectively. Note that since STC fails to achieve the same convergence compared with other baselines, we do not include it in the comparison for transmitted bits. The slow convergence of STC and 4-bit LAQ verifies the necessity and effectiveness of our well-designed precision selection criterion (5), which achieves fast convergence with similar low-bit transmission but without degradation of model performance.
Fig. 11. Convergence of loss function with ResNet18 and IID CIFAR10.

Fig. 12. Convergence of loss function with ResNet18 and non-IID CIFAR10.
B.3 Comparison of Converged Accuracy

Table 4 compares the proposed AQG with several baselines in terms of converged test accuracy.

| Dataset                 | Two-level AQG | LAQ   | Q(S)GD | FedAvg |
|-------------------------|---------------|-------|--------|--------|
| IID-MNIST-FC            | 90.81%        | 90.82%| 90.79% | 90.77% |
| non-IID-MNIST-FC        | 90.78%        | 90.77%| 90.77% | 90.62% |
| IID-CIFAR10-ResNet18    | 92.95%        | 92.53%| 93.39% | 93.61% |
| non-IID-CIFAR10-ResNet18| 69.38%        | 69.71%| 70.41% | 69.39% |

FC denotes the 2-layer fully connected neural network adopted in the main text. The quantization levels of two-level AQG is 4/2 bits for MNIST, 6/4 bits for IID CIFAR10 and 5/3 bits for non-IID CIFAR10.

B.4 Heterogeneous Simulation Dataset

To simulate non-IID data distribution, a heterogeneous simulation dataset is used for logistic regression. The three binary classification datasets listed in Table 5 are used together in order to simulate non-IID data distribution as Chen et al. do in the evaluation of LAQ [7]. The number of features is preprocessed to be equal to the minimal number of features among all three datasets, and each dataset is uniformly distributed across six clients.

| Dataset           | # features | # samples | client index     |
|-------------------|------------|-----------|------------------|
| Adult fat [17]    | 113        | 1605      | 1,2,3,4,5,6      |
| Ionosphere [26]   | 34         | 351       | 7,8,9,10,11,12   |
| Derm [11]         | 34         | 358       | 13,14,15,16,17,18|

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