SOME CRITICAL POINT RESULTS FOR FRÉCHET MANIFOLDS

KAVEH EFTEKHARINASAB

Abstract. We prove a so-called linking theorem and some of its corollaries, namely a mountain pass theorem and a three critical points theorem for Keller $C^1$-functional on $C^1$-Fréchet manifolds. Our approach relies on a deformation result which is not implemented by considering the negative pseudo-gradient flows. Furthermore, for mappings between Fréchet manifolds we provide a set of sufficient conditions in terms of the Palais-Smale condition that indicates when a local diffeomorphism is a global one.

1. Introduction

For Banach and Hilbert manifolds there are two approaches to the critical point theory. One is based on deformation techniques along the negative gradient flow or a suitable substitute of it, namely the pseudo-gradient flow. The other one relies on various versions of Ekeland’s variational principle. At the core of both approaches lie Palais-Smale compactness-type conditions. However, as pointed out in [4] these approaches do not work in full extent for more general context of Fréchet manifolds. Since for Fréchet manifolds cotangent bundles do not admit smooth manifold structures and consequently the notion of pseudo-gradient vector fields and Finsler structures on cotangent bundles make no sense.

In this regard, it was introduced the Palais-Smale condition on Fréchet manifolds by using an auxiliary function to detour the need of a smooth structure on cotangent bundles in [4]. The idea behind the definition is that on sets where a real-valued functional on a manifold has no critical points and satisfies the proposed Palais-Smale condition, the associated auxiliary function is negative (Lemma 3.1). In this case, the functional satisfies the hypotheses of the deformation result (Lemma 3.2) which requires that the associated auxiliary function be negative. Moreover, by imposing the closedness assumption on mappings and applying the deformation result along with the Palais-Smale condition the Minimax principle (Theorem 3.3) was obtained. The closedness assumption is crucial in the Minimax principle, without it the theorem is not valid.

In this paper following the ideas of [4] and applying the mentioned results we develop the critical point theory for Fréchet manifolds. First, we prove a so-called linking theorem (Theorem 3.1). Then, we obtain some of its corollaries, namely a mountain pass theorem (Theorem 3.2) and a three critical points theorem (Theorem 3.6). Furthermore, we apply the mountain pass theorem and the Palais-Smale condition to provide a set of sufficient conditions that indicates when a local diffeomorphism is a global one (Theorem 3.4).

2. Preliminaries

In this section we briefly recall the basic concepts of the theory of Fréchet manifolds and establish our notations.

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By $U \subseteq T$ we mean that $U$ is an open subset of a topological space $T$. If $S$ is another topological space, then we denote by $\mathcal{C}(T, S)$ the set of continuous mappings from $T$ into $S$.

We denote by $F$ a Fréchet space whose topology is defined by a sequence of seminorms $(\|\cdot\|_{F,n})_{n \in \mathbb{N}}$, which we can always assume to be increasing (by considering $\max_{k \leq n} \|\cdot\|_{F,n}$ if necessary). Moreover, the complete translation-invariant metric

$$d_F(x, y) := \sum_{n \in \mathbb{N}} \frac{1}{2^n} \cdot \frac{\|x - y\|_{F,n}}{1 + \|x - y\|_{F,n}}$$

induces the same topology on $F$.

Define a closed unit semi-ball centered at the zero vector $0_F$ of $F$ by

$$B^n(0_F, 1) = \{ x \in F \mid \|x\|_{F,n} \leq 1 \}$$

for each seminorm $\|\cdot\|_{F,n}$. Let

$$B_x(0_F) = \bigcap_{i=1}^{\infty} B^i(0_F, 1). \quad (2.1)$$

The set $B_x(0_F)$ is not empty ($0_F \in B_x(0_F)$) and is infinite (because it is convex so by the Kolmogorov theorem it is bounded only in Banach spaces).

We recall that a family $B$ of subsets of $F$ that covers $F$ is called a bornology on $F$ if

(B1): $\forall A, B \in B$ there exists $C \in B$ such that $A \cup B \subseteq C$,

(B2): $\forall B \in B$ and $\forall r \in \mathbb{R}$ there is a $C \in B$ such that $r \cdot B \subseteq C$.

Throughout the paper we assume that $F, E$ are Fréchet spaces and $L(E, F)$ is the set of all continuous linear mappings from $E$ to $F$. Let $B$ a bornology on $E$. We define on $L(E, F)$ the $B$-topology which is a Hausdorff locally convex topology defined by all seminorms:

$$\|L\|_{B,n} := \sup \{ \|e\|_{F,n} \mid e \in B \},$$

where $B \in B, n \in \mathbb{N}$. We shall always assume that $B$ contains all compact subsets (for simplicity we refer to such bornologies as compact bornologies).

Let $\varphi : U \subseteq E \to F$ be a continuous map and $B$ the compact bornology on $E$. If the directional derivatives

$$D\varphi(x)h = \lim_{t \to 0} \frac{\varphi(x + th) - \varphi(x)}{t}$$

exist for all $x \in U$ and all $h \in E$, and the induced map $D\varphi(x) : U \to L(E, F)$ is continuous for all $x \in U$, then we say that $\varphi$ is a Keller’s differentiable map of class $C^1$, see [6]. Here, $L(E, F)$ is endowed by the $B$-topology which coincides with the compact-open topology.

A $C^1$-Fréchet manifold $M$ is a Hausdorff second countable manifold modeled on a Fréchet space $F$ with an atlas of coordinate charts such that the coordinate transition functions are all Keller $C^1$-mappings.

If $\varphi : F \to \mathbb{R}$ at $x$ is of class $C^1$, the derivative of $\varphi$ at $x$, $\varphi'(x)$, is an element of the dual space $F'$. The directional derivative of $\varphi$ at $x$ toward $h \in E$ is given by

$$D\varphi(x)h = \langle \varphi'(x), h \rangle,$$

where $\langle \cdot, \cdot \rangle$ is duality pairing. Let $x \in M$ and $h \in T_x M$. A chart $(x \in U, \psi)$ induces a canonical map $\psi_*$ from $T_x M$ onto $F$. Let $\varphi : M \to \mathbb{R}$ be a $C^1$-functional, then

$$\varphi'(x, h) = \lim_{t \to 0} \frac{\varphi(\psi^{-1}(\varphi(x) + t\psi_*(x)(h))) - \varphi(x)}{t}.$$
Definition 2.1. [7] Let $\mathbb{F}$ be a Fréchet space, $T$ a topological space and $V = T \times \mathbb{F}$ the trivial bundle with fiber $\mathbb{F}$ over $T$. A Finsler structure for $V$ is a collection of continuous functions $\| \cdot \|_{V,n}: V \to \mathbb{R}^+$, $n \in \mathbb{N}$, such that

(F1): For $b \in T$ fixed, $\|x\|_{V,n}^b := \|(b, x)\|_{V,n}$ is a collection of seminorms on $\mathbb{F}$ which gives the topology of $\mathbb{F}$.

(F2): Given $k > 1$ and $x_0 \in T$, there exists a neighborhood $W$ of $x_0$ such that

$$\frac{1}{k} \|x\|_{V,n}^x \leq \|x\|_{V,n}^w \leq k \|x\|_{V,n}^x \quad \text{for all} \quad w \in W, n \in \mathbb{N}, x \in F.$$

Suppose $M$ is a Fréchet manifold modeled on $\mathbb{F}$. Let $\pi_M: TM \to M$ be the tangent bundle and let $\|\cdot\|_{M,n}: TM \to \mathbb{R}^+$ be a collection of continuous functions, $n \in \mathbb{N}$. We say that $\{\|\cdot\|_{M,n}\}_{n \in \mathbb{N}}$ is a Finsler structure for $TM$ if for a given $x \in M$ there exists a bundle chart $\psi: U \times \mathbb{F} \simeq TM|_U$ with $x \in U$ such that

$$\{\|\cdot\|_{V,n} \circ \psi^{-1}\}_{n \in \mathbb{N}}$$

is a Finsler structure for $V = U \times \mathbb{F}$.

A Fréchet Finsler manifold is a Fréchet manifold together with a Finsler structure on its tangent bundle. Regular (in particular paracompact) manifolds admit Finsler structures.

If $\{\|\cdot\|_{M,n}\}_{n \in \mathbb{N}}$ is a Finsler structure for $M$ then we can obtain a graded Finsler structure, denoted by $\{\|\cdot\|_{M,n}\}_{n \in \mathbb{N}}$, that is $\|\cdot\|_{M,i} \leq \|\cdot\|_{M,i+1}$ for all $i \in \mathbb{N}$.

We define the length of a $C^1$-curve $\gamma: [a, b] \to M$ with respect to the $n$-th component by

$$L_n(\gamma) = \int_a^b \|\gamma'(t)\|_{M,n} \, dt.$$

The length of a piecewise path with respect to the $n$-th component is the sum over the curves constituting to the path. On each connected component of $M$, the distance is defined by

$$\rho_n(x, y) = \inf_{\gamma} L_n(\gamma),$$

where infimum is taken over all piecewise $C^1$-curve connecting $x$ to $y$. Thus, we obtain an increasing sequence of metrics $\rho_n(x, y)$ and define the distance $\rho$ by

$$\rho(x, y) = \sum_{n=1}^{\infty} \frac{1}{2^n} \cdot \frac{\rho_n(x, y)}{1 + \rho_n(x, y)}.$$  \hspace{1cm} (2.2)

The distance $\rho$ defined by (2.2) is a metric for $M$ which is bounded by 1. Furthermore, the topology induced by this metric coincides with the original topology of $M$ (see [7]).

We denote by $B_p(x, r)$ an open ball with center $x$ and radius $r > 0$. We do not write the metric $\rho$ when it does not cause confusion.

3. Linking Results and Corollaries

Henceforth we assume that $M$ is a connected $C^1$-Fréchet manifold modeled on $\mathbb{F}$ endowed with a complete Finsler metric $\rho$ (2.2), and that $\varphi: M \to \mathbb{R}$ is a non-constant $C^1$-functional. Let $x \in M$, we shall say that $x$ is a critical point of $\varphi$ if $(\varphi \psi^{-1})'(\psi(x)) = 0$ for a chart $(x \in U, \psi)$ and hence for every chart whose domain contains $x$.

Let $\{\|\cdot\|_{M,n}\}_{n \in \mathbb{N}}$ be a graded Finsler structure on $TM$. Define a closed unit semi-ball centered at the zero vector $0_x$ of $T_xM$ by

$$B^n(0_x, 1) = \{h \in T_xM : \|h\|_{M,n}^x \leq 1\}$$
for each \( x \in \mathbb{M} \) and each \( \| h \|_\mathbb{M,n} \). Let

\[
\mathbb{B}_\infty(0_x) = \bigcap_{n=1}^\infty \mathbb{B}^n(0_x, 1).
\]

The set \( \mathbb{B}_\infty(0_x) \) is not empty and infinite because it can be identified with a convex neighborhood of the zero of the Fréchet space \( U \times \mathbb{F} \), where \( U \) is an open neighborhood of \( x \).

Let \( \varphi : \mathbb{M} \to \mathbb{R} \) be a \( C^1 \)-functional and \( x \in \mathbb{M} \). Define

\[
\Phi_\varphi(x) = \inf \{ \varphi'(x, h) : h \in \mathbb{B}_\infty(0_x) \}.
\]

**Definition 3.1** (The \((PS)_c\)-condition for Fréchet manifolds, [4]). We say that a \( C^1 \)-functional \( \varphi : \mathbb{M} \to \mathbb{R} \) satisfies the Palais-Smale condition at a level \( c \in \mathbb{R} \), \((PS)_c\) in short, in a set \( A \subset \mathbb{M} \) if any sequence \( (m_i)_{i\in\mathbb{N}} \subset A \) such that

\[
\varphi(m_i) \to c \quad \text{and} \quad \Phi_\varphi(m_i) \to 0,
\]

has a convergent subsequent.

For Fréchet spaces this version of the \((PS)_c\)-condition will become as follows.

Let \( \varphi : \mathbb{F} \to \mathbb{R} \) be a \( C^1 \)-functional and \( x \in \mathbb{F} \). Define

\[
\Psi_\varphi(x) = \inf \{ \langle \varphi'(x), h \rangle : h \in \mathbb{B}_\infty(0_\mathbb{F}) \}.
\]

**Definition 3.2** (The \((PS)_c\)-condition for Fréchet spaces). We say that a \( C^1 \)-functional \( \varphi : \mathbb{F} \to \mathbb{R} \) satisfies the Palais-Smale condition at a level \( c \in \mathbb{R} \), \((PS)_c\) in short, in a set \( A \subset \mathbb{F} \) if for any sequence \( (m_i)_{i\in\mathbb{N}} \subset A \) such that

\[
\varphi(m_i) \to c \quad \text{and} \quad \Psi_\varphi(m_i) \to 0,
\]

has a convergent subsequent.

**Remark 3.1.** The above version of the Palais-Smale condition is equivalent to the one which was introduced in [3]. Indeed, since the set \( \mathbb{B}_\infty(0_\mathbb{F}) \) is absorbing it follows that for any \( x \in \mathbb{F} \) there is a \( k > 0 \) such that \( x = kp \) for some \( p \in \mathbb{B}_\infty(0_\mathbb{F}) \). Thus, \( \Psi_\varphi(m_i) \to 0 \) implies \( \varphi'(m_i) \to 0 \) and vice versa. However, for technical reasons in many situations it is more convenient to work with Definition 3.2.

Let \( \varphi : \mathbb{M} \to \mathbb{R} \) be a \( C^1 \)-functional. We denote by \( \text{Cr}(\varphi) \) the set of critical points of \( \varphi \), and for \( c \in \mathbb{R} \) we define the following sets

\[
\text{Cr}(\varphi, c) := \{ x \in \text{Cr}(\varphi) : \varphi(x) = c \},
\]

\[
\varphi^c := \{ x \in \mathbb{M} : \varphi(x) \leq c \}.
\]

A mapping \( \mathcal{H} \in \mathcal{C}([0,1] \times \mathbb{M} \to \mathbb{M}) \) is called a deformation if \( \mathcal{H}(0,x) = x \) for all \( x \in \mathbb{M} \). Let \( C \) be a subset of \( \mathbb{M} \), we say that \( \mathcal{H} \) is a \( C \)-invariant for an interval \( I \subset [0,1] \) if \( \mathcal{H}(t,x) = x \) for all \( x \in C \) and all \( t \in I \).

A family \( \mathcal{F} \) of subset of \( \mathbb{M} \) is said to be deformation invariant if for each \( A \in \mathcal{F} \) and each deformation \( \mathcal{H} \) for \( \mathbb{M} \) it follows that

\[
\mathcal{H}_1(x) := \mathcal{H}(1,x) \in \mathcal{F}.
\]

**Definition 3.3** (linking, cf. [8]). Let \( \mathbb{T} \) be a topological space, \( S_0 \subset S \) and \( C \) be a nonempty sets in \( \mathbb{T} \), and let \( \gamma \in \mathcal{C}(S_0, \mathbb{T}) \). Consider the class of continuous functions

\[
\mathcal{K} := \{ h \in \mathcal{C}(\mathbb{T}) : h|_{\partial S_0} = \gamma \}.
\]

We say that the pair \( \{S_0, S\} \) links \( D \) through \( \gamma \) if the following holds:
**Lemma 3.1** (Lemma 3.2, [4]). If \( \varphi : M \to \mathbb{R} \) satisfies the Palais-Smale condition in \( A \subset M \) and has no critical point in \( A \), then there exists \( \epsilon > 0 \) such that \( \Phi_\varphi(x) < -\epsilon \) for all \( x \in A \).

**Lemma 3.2** ([4], Lemma 3.1). Let \( M \) be a connected \( C^1 \)-Fréchet manifold endowed with a complete Finsler metric \( \rho \). Assume \( \varphi : M \to \mathbb{R} \) is a \( C^1 \)-functional. Let \( B \) and \( A \) be closed disjoint subsets of \( M \) and let \( A \) be compact. Suppose \( k > 1 \) and \( \epsilon > 0 \) are such that \( \Phi_\varphi(x) < -2\epsilon(1 + k^2) \) for all \( x \in A \). Then there exist \( t_0 > 0 \) and \( B \)-invariant deformation \( \mathcal{H} \) for \([0, t_0]\) such that

1. \( \rho(\mathcal{H}(t, x), x) \leq kt \quad \forall x \in M \),
2. \( \varphi(\mathcal{H}(t, x)) - \varphi(x) \leq -2\epsilon(1 + k^2)t \quad \forall x \in M \).

**Corollary 3.1** ([4], Corollary 3.5). Let \( M \) be a connected \( C^1 \)-infinite dimensional Fréchet manifold, \( \varphi : M \to \mathbb{R} \) a closed non-constant \( C^1 \)-functional. Suppose \( \varphi \) satisfies the Palais-Smale condition at all levels.

**(DF1)** If for \( c \in \mathbb{R} \) and \( \delta > 0 \) we have

\[
\varphi^{-1}[c - \delta, c + \delta] \cap \text{Cr}(\varphi) = \emptyset,
\]

then there exists \( t_1 < t_0 \) and \( 0 < \epsilon < \delta \) such that

\[
\mathcal{H}(t_1, \varphi^{c+\epsilon}) \subset \varphi^{c-\epsilon}.
\]  

**Theorem 3.1.** Let \( M \) be a \( C^1 \)-Fréchet manifold endowed with a complete Finsler metric \( \rho \) and let \( \varphi : M \to \mathbb{R} \) be a closed \( C^1 \)-functional. Suppose \( \{S_0, S, C\} \) is a linking set through \( \gamma \in C(S_0, T) \), \( C \) is closed and \( \rho(\gamma(S_0), C) > 0 \). Suppose the following conditions hold

**(LT1):** \( s = \sup_{\gamma(S_0)} \leq \inf_C \varphi = i \),
**(LT2):** \( \varphi \) satisfies the (PS)\(_c\)-condition at

\[
c := \inf_{h \in \mathcal{H}} \sup_{x \in S} \varphi(\gamma(x)),
\]

where

\[
\mathcal{H} := \{ h \in C(S, T) \mid h|_{\partial S_0} = \gamma \}.
\]

Then \( c \) is a critical value and \( c \geq i \). Furthermore, if \( c = i \) then \( \text{Cr}(\varphi, c) \cap C \neq \emptyset \).

**Proof.** Let \( h \in \mathcal{H} \), then by definition of linking we have \( h(S) \cap C \neq \emptyset \) and so \( c \geq i \).

At first, suppose that \( c > i \). If \( \text{Cr}(\varphi, c) \cap C = \emptyset \), then by Lemma 3.1 there exists \( \epsilon > 0 \) such that \( \Phi_\varphi(x) < -\epsilon \) for all \( x \in M \). Let \( \epsilon := \min \{ \epsilon, s - c \} \) and let

\[
B := \{ x \in M \mid |\varphi(x) - c| \leq \epsilon \}.
\]

Since \( \varphi \) is closed and continuous it follows that its inverse is also closed and so \( B \) is closed. Suppose \( A \) is a compact subset of \( M \) such that \( B \cap A = \emptyset \) and for some \( k > 1 \)

\[
\Phi_\varphi(x) < -2\epsilon(1 + k^2) \quad \forall x \in A.
\]
Then, by Lemma 3.2 there exist \( t_0 > 0 \) and \( B \)-invariant deformation \( \mathcal{H} \) for \( [0, t_0) \).

By Lemma 3.1(DF1) then we can find \( t_1 < t_0 \) and \( \varepsilon < \epsilon \) such that
\[
\mathcal{H}(t_1, \phi^{t+\varepsilon}) \subset \phi^{t-\varepsilon}.
\]  
(3.6)

Fix \( h \in \mathcal{H} \) such that
\[
\phi(h(x)) \leq c + \varepsilon \quad \forall x \in S.
\]  
(3.7)

Define the mapping
\[
\gamma = \mathcal{H}(t_1, h(x)) \quad \forall x \in S.
\]  
(3.8)

Thus, \( \gamma \in \mathcal{C}(S, M) \) and if \( x \in S_0 \), then by (3.7)
\[
\phi(h(x)) = \phi(\gamma(x)) \leq s \leq c - \varepsilon.
\]  
(3.9)

Therefore, as \( \mathcal{H} \) is \( B \)-invariant by Lemma 3.2, it follows that \( \gamma|_{S_0} = \gamma \) whence \( \gamma \in \mathcal{H} \). But by (3.6) we have \( \phi(\gamma(x)) \leq c - \varepsilon \) for all \( x \in S \). This contradicts (3.5), and so \( \text{Cr}(\phi, c) \cap C \neq \emptyset \).

Now assume that \( c = i \). From \( \rho(\gamma(S_0), C) > 0 \) it follows that one can find a closed neighborhood \( U \) of \( \gamma(S_0) \) such that
\[
\rho(U, C) > 0 \quad \text{and} \quad \rho(\gamma(S_0), \overline{U}) > 0.
\]

Now suppose that \( c = i > s \) and \( \text{Cr}(\phi, c) \cap C = \emptyset \). As before, one can find \( \varepsilon > 0, t_1 > 0 \) and a deformation \( \mathcal{H} \) that satisfies (3.6). Also, again we fix \( h \in \mathcal{H} \) such that \( \phi(h(x)) \leq c + \varepsilon \) for all \( x \in S \), and define the mapping \( \gamma(x) = \mathcal{H}(t_1, h(x)) \) for all \( x \in S \). As above \( \gamma \in \mathcal{H} \). From (3.6) it follows that for all \( x \in S \) we have
\[
\phi(\gamma(x)) \leq c - \varepsilon < \inf_C \phi \quad \text{or} \quad \gamma(x) \in \emptyset C.
\]

Thus, \( \gamma \notin C \) for all \( x \in S \) and so \( \gamma(S) \cap C = \emptyset \), which is a contradiction.

Now suppose that \( c = i = s \). Let \( f : M \to \mathbb{R} \) be a mapping of class \( C^1 \) such that
\[
f|_{\gamma(S_0)} = 0 \quad \text{and} \quad f|_{\overline{U}} = 1.
\]

We may replace \( \phi(x) \) by \( \phi(x) + (1 - s) \) and assume that \( s > 0 \). Define
\[
\phi(x) = (f \phi)(x) \quad \text{and} \quad c = \inf_{h \in \mathcal{H}} \sup_{x \in S} \phi(h(x)).
\]

On \( \mathcal{C}S \) we have \( \phi = \varphi \), therefore, \( \phi \) satisfies the \((\text{PS})_c\)-condition on \( \mathcal{C}S \) and
\[
\sup_{\gamma(S_0)} \phi = 0 < i = \inf_C \phi.
\]

Thus, for \( \phi \) we have \( c = i > s \) and by repeating the above arguments we obtain
\[
\text{Cr}(\phi, c) \cap C \neq \emptyset.
\]

Since \( \phi = \varphi \) on \( \mathcal{C}S \supset C \), it follows that
\[
\text{Cr}(\phi, c) \cap C \subset \text{Cr}(\phi, c) \cap C.
\]

We will show that \( c = c \). For \( h \in \mathcal{H} \), by the linking assumption we have
\[
\phi(h(x)) = \phi(h(x)) \geq i = c \quad \text{for } x \in S \text{ such that } h(x) \in C.
\]

Thereby, \( c \geq c \). Besides, since \( f(h(x)) \in [0, 1] \) and \( \sup_{\mathcal{E}}(\varphi \circ h) \geq c > 0 \) it follows that
\[
\phi(h(x)) \leq \sup_{\mathcal{S}}(\varphi \circ h) \quad x \in S.
\]

Thus, \( c \leq c \) by the definitions of \( c \) and \( c \). This concludes the proof. \( \Box \)

An immediate corollary of Theorem 3.1 is the following mountain pass theorem.
**Theorem 3.2.** Suppose that \( x_0, x_1 \in M \) and \( x_0 \in U \subseteq M, x_1 \notin U \). Let \( \varphi : M \to \mathbb{R} \) be a closed \( C^1 \)-functional satisfying the following condition:

(M1) \( \max \{ \varphi(x_0), \varphi(x_1) \} \leq \inf_{\partial U} \varphi(x) =: i \);

(M2) \( \varphi \) satisfies the (PS)_c-condition at

\[
c := \inf_{h \in \mathcal{C}} \sup_{t \in [0,1]} \varphi(h(t)),
\]

where

\[
\mathcal{C} := \{ h \in \mathcal{C}([0,1], M) \mid h(0) = x_0, h(1) = x_1 \}.
\]

Then \( c \) is a critical value and \( c \geq i \). If \( c = i \) then \( \text{Cr}(\varphi, c) \cap U \neq \emptyset \).

**Proof.** Define the following sets:

\[
S := \{ x \in M \mid (1 - t)x_0 + tx_1, t \in [0,1] \}, \quad S_0 := \{ x_0, x_1 \} \quad \text{and} \quad C = \partial U.
\]

Pick \( \gamma \in \mathcal{C}(S, M) \) such that \( \gamma(x_0) = x_0 \) and \( \gamma(x_1) = x_1 \). The image \( \gamma(S) \) is connected. Assume that \( \gamma(S) \cap C = \emptyset \), then \( \gamma(S) = U_1 \cup U_2 \), where

\[
U_1 := \gamma(S) \cap U, \quad U_2 := \gamma(S) \cap \overline{U}.
\]

But \( U_0, U_1 \) are open, this contradicts the connectivity of \( \gamma(S) \). Thus, \( \{S, S_0, C\} \) is a linking set through \( \gamma \). If we apply Theorem 3.1 for the linking set \( \{S, S_0, C\} \) through \( \gamma \) we conclude the proof. \( \square \)

**Remark 3.2.** If the inequality in the condition (M1) is strict (<) then \( c < i \), which means \( \varphi \) has a critical point at \( x_3 \) and \( x_3 \neq x_0, x_1 \).

We shall apply this theorem to generalize to Fréchet manifolds global diffeomorphism theorems for Fréchet spaces (see [1, Theorem 3.1] and [2, Theorem 4.1]). The proof is almost identical to the case of Fréchet spaces. However, for the existence of critical points we apply the following Minimax principle which is not yet available for the case of Fréchet spaces.

**Theorem 3.3** (Theorem 3.6, [4]). Let \( M \) be a connected \( C^1 \)- Fréchet manifold and let \( \varphi : M \to \mathbb{R} \) be a non-constant closed \( C^1 \)-functional satisfying the (PS) condition at all levels. Suppose that \( \mathcal{F} \) is a deformation invariant class of subsets of \( M \) and suppose that

\[
c = c(\varphi, \mathcal{F}) := \inf_{A \in \mathcal{F}} \sup_{x \in A} \varphi(x)
\]

is finite, then \( c \) is the critical value for \( \varphi \).

**Theorem 3.4.** Let \( M, N \) be connected \( C^1 \)- Fréchet manifolds endowed with complete Finsler metrics \( \delta, \rho \) respectively. Assume that \( \varphi : M \to N \) is a local diffeomorphism of class \( C^1 \). Let \( J : N \to [0, \infty] \) be a closed \( C^1 \)-functional such that \( J(x) = 0 \) if and only if \( x = 0 \) and \( J'(x) = 0 \) if and only if \( x = 0 \). If for any \( q \in N \) the functional \( \varphi_q \) defined by

\[
\varphi_q(x) = J(\varphi(x) - q)
\]

satisfies the (PS)-condition at all levels, then \( \varphi \) is a \( C^1 \)-global diffeomorphism.

**Proof.** **Surjectivity:** Let \( q \in N \) be a given point. Let \( V \subset N \) be a neighborhood of \( q \), if necessarily shrink it, so that \( \varphi \) is diffeomorphism on \( U := \varphi^{-1}(V) \). The functional \( \varphi_q(x) \) is bounded below by 0, it is of class \( C^1 \) (since the composition of two \( C^1 \)-maps is again \( C^1 \)), and it satisfies the (PS)-condition. Therefore, if in Theorem 3.3 we let

\[
\mathcal{F} = \{ \{x\} \mid x \in U \},
\]
then \( c = \inf_{x \in U} \varphi(x) \) is a critical value of \( \varphi_q \). Therefore, for some critical point \( p \in U \) we have \( \varphi_q(p) = c, \varphi'(p) = 0 \). Then, by the chain rule

\[
\varphi'_q(p) = \mathcal{J}'(\varphi(p) - q) \circ \varphi'(p) = 0.
\]  

(3.12)

Since \( \varphi' \) on \( U \) is locally invertible, it follows that (3.12) yields \( \mathcal{J}'(\varphi(p) - q) = 0 \) and thus \( \varphi(p) = q \).

**Injectivity:** Assume that \( x_1 \neq x_2 \in M \) and \( \varphi(x_1) \neq \varphi(x_2) = q \). Let \( V \subset N \) be a neighborhood of \( q \), if necessarily shrink it, so that \( \varphi \) is diffeomorphism on \( U := \varphi^{-1}(V) \).

The mapping \( \varphi \) is open as it is local diffeomorphism, therefore, for \( r > 0 \) there is \( a_r > 0 \) such that

\[
\mathcal{B}_r(q, a_r) \subset \varphi(\mathcal{B}_{\delta}(x_1, r)) \subset V.
\]  

(3.13)

Let \( r > 0 \) be small enough such that

\[
x_2 \notin \mathcal{B}_r(x_1, r).
\]  

(3.14)

Consider the functional \( \varphi_q(\varphi(x) - q) \). Then

\[
\varphi_q(x_1) = \varphi_q(x_2) = 0.
\]

For \( x \in \partial \mathcal{B}_r(x_1, r) \) in view of (3.13) we obtain that \( \varphi(x) \notin \mathcal{B}_r(q, a_r) \) so \( \varphi(x) \neq q \) on \( \partial \mathcal{B}_r(x_1, r) \). Thus,

\[
\varphi_q(x) > 0 = \max \{ \varphi_q(x_1), \varphi_q(x_2) \} \quad \text{on} \quad \partial \mathcal{B}_r(x_1, r).
\]  

(3.15)

Thereby, all the assumptions of Theorem 3.2 satisfies, therefore, there exists a critical point \( c \in U \) with \( \varphi_q(c) = c \) for some \( c > 0 \) (see Remark 3.2). But \( c = \mathcal{J}(\varphi(c) - q) > 0 \), so

\[
\varphi(c) \neq q.
\]  

(3.16)

By the chain rule we have \( \varphi'_q(c) = \mathcal{J}'(\varphi(c) - q) \circ \varphi'(c) = 0 \). Since \( \varphi' \) is invertiable on \( U \), it follows that \( \mathcal{J}(\varphi(c) - q) = 0 \). Thus, \( \varphi(c) = q \) which contradicts (3.16).

Now we prove the three critical points theorem. We shall need the following strong version of Ekeland’s variational principle.

**Theorem 3.5** ([5], Theorem 4.7). Let \((M, \mathcal{m})\) be a complete metric space. Let a functional \( \phi : M \to (-\infty, \infty] \) be lower semi-continuous, bounded from below and not identical to \( \infty \). Let \( \varepsilon > 0 \) be an arbitrary real number, \( m \in M \) a point such that

\[
\phi(m) \leq \inf_{x \in M} \phi(x) + \varepsilon.
\]

Then for an arbitrary \( r > 0 \), there exists a point \( m_r \in M \) such that

- (EK1) \( \phi(m_r) \leq \phi(m) \);
- (EK2) \( \mathcal{m}(m_r, m) < r \);
- (EK3) \( \phi(m_r) < \phi(x) + \frac{\varepsilon}{r} \mathcal{m}(m_r, x) \forall x \in M \setminus \{m_r\} \).

**Lemma 3.3.** Let \( M \) be a Fréchet manifold modeled on a Fréchet space \((\mathbb{F}, d)\), \( \mathcal{B} \) the compact bornology on \( \mathbb{F} \) and \( \varphi : M \to \mathbb{R} \) a \( C^1 \)-functional that satisfies the (PS)-condition at all levels. Let \( u \in U \subseteq M \) be such that \( \varphi(u) \leq \varphi(u) \) for all \( u \in U \). Then, for any \( V \subseteq M \) such that \( V \subset U \) either

- (I1) \( \inf_{w \in W} \varphi(w) > \varphi(u) \) for some \( W \subset V \);
- (I2) or for each \( W \subset V \), \( \varphi \) has a local minimum at a point \( c_W \) such that \( \varphi(c_W) = \varphi(u) \).

**Proof.** Suppose \( V \subset U \) is given and (I1) is not valid we shall prove (I2).
Let \((\mathcal{U}_u, \psi_u)\) be a chart at \(u\) such that \(\mathcal{U}_u \cap V \neq \emptyset\), and let \(\varphi := \varphi \circ \psi_u^{-1}\) be the local representative of \(\varphi\) in this chart. Thus, for any given \(W \subseteq V\) such that \(W := W \cap \mathcal{U}_u \neq \emptyset\) we have
\[
\inf_{u \in \partial \psi_u(W)} \varphi(u) = \varphi(u).
\tag{3.17}
\]
Let \(S, S'\) be distinct sets such that \(S \subseteq V, S' \subseteq W\) and \(\overline{S \setminus S'} \cap \mathcal{U}_u \neq \emptyset\). In virtue of (3.17) we can find a sequence \((u_n)_{n \in \mathbb{N}} \subseteq \partial \psi_u(W)\) such that
\[
\varphi(u_n) \leq \varphi(u) + \frac{1}{n}.
\tag{3.18}
\]
The restriction of \(\varphi\) to \(\psi_u(S \setminus S')\) satisfies all the assumption of Theorem 3.5, therefore, there is a sequence \((v_n)_{n \in \mathbb{N}} \subseteq \psi_u(S \setminus S')\) such that
\begin{align*}
(E1) & \quad \varphi(v_n) \leq \varphi(u_n); \\
(E2) & \quad \delta(u_n, v_n) < \frac{1}{n}; \\
(E3) & \quad \varphi(v_n) < \varphi(x) + \frac{1}{n} \delta(v_n, x) \quad \forall x \in \psi_u(S \setminus S').
\end{align*}
It follows from (E2) that \((v_n) \subseteq \text{int} \psi_u(S \setminus S')\) for sufficiently large \(n\). In (E3), let \(x = v_n + tb\) for sufficiently small \(t\) and \(b \in B_x(0_F)\). By Taylor’s expatiation formula of \(\varphi(v_n + tb)\) about \(v_n\) ([6, Theorem 1.4.A]), and letting \(t \to 0\) we obtain
\[
\|\varphi(v_n)\|_B \leq \frac{1}{n} \quad \forall B \in \mathcal{B}.
\tag{3.19}
\]
Thus, along with (EK3) and the (PS)-condition for \(\varphi\) there exists a subsequence of \((v_n)_{n \in \mathbb{N}}\), denoted by \((w_n)_{n \in \mathbb{N}}\), such that \(w_n \to c_W\) for some point \(c_W \in \partial \psi_u(W)\). Whence, \(\varphi(c_W) = \varphi(u), \varphi'(c_W) = 0\). The chain rule then completes the proof. 

\begin{theorem}
(Three Critical Points Theorem) Let \(M\) be a connected Fréchet manifold and \(\varphi : M \to \mathbb{R}\) a closed \(C^1\)- functional satisfying the Palais-Smale condition at all levels. If \(\varphi\) has two minima, then \(\varphi\) has one more critical point.
\end{theorem}

\begin{proof}
It follows from Theorem 3.2 and Lemma 3.3.
\end{proof}

\begin{thebibliography}{99}

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\textbf{Topology lab. Institute of Mathematics of National Academy of Sciences of Ukraine, Tereshchenkovska st. 3, Kyiv, 01601 Ukraine}

\textit{Email address: kaveh@imath.kiev.ua}

\end{thebibliography}