MAPPING CLUSTER MASS DISTRIBUTIONS VIA GRAVITATIONAL LENSING OF BACKGROUND GALAXIES

T.J. BROADHURST
Royal Observatory, Blackford Hill, Edinburgh EH9 3HJ, UK
Physics and Astronomy Dept., Johns Hopkins University, Baltimore, Maryland, MD 21218, USA

A.N. TAYLOR
Department of Astronomy, University of Edinburgh, Blackford Hill, Edinburgh EH9 3HJ, UK

AND

J.A. PEACOCK
Royal Observatory, Blackford Hill, Edinburgh EH9 3HJ, UK

Abstract
We present a new method for measuring the projected mass distributions of galaxy clusters, based solely on the gravitational lens amplification of background galaxies by the cluster potential field. The gravitational amplification is measured by comparing the joint distribution in redshift and magnitude of galaxies behind the cluster with that of the average distribution of field galaxies. Lensing shifts the magnitude distribution in a characteristic redshift–dependent way, and simultaneously dilutes the surface density of galaxies. These effects oppose, with the latter dominating at low redshift and the former at high redshift, owing to the curvature of the galaxy luminosity function. Lensing by a foreground cluster thus induces an excess of bright high-redshift galaxies, from which the lens amplification may be inferred.

We show that the total amplification is directly related to the surface mass density in the weak field limit, and so it is possible to map the mass distribution of the cluster. The method is shown to be limited by discreteness noise and galaxy clustering behind the lens. Galaxy clustering sets a lower limit to the error along the redshift direction, but a clustering independent lensing signature may be obtained from the magnitude distribution at fixed redshift. Provided the luminosity function deviates from a pure power law, the lens–induced brightening can be measured directly by comparison with the field. In the limit that galaxy luminosities are independent of environment, this method is only shot–noise limited.

Statistical techniques are developed for estimating the surface mass density of the cluster. We extend these methods to account for any obscuration by cluster halo dust, which may be mapped independently of the dark matter. We apply the method to a series of numerical simulations and show the the feasibility of the approach. We consider the use of approximate redshift information, and show how the mass estimates are degraded; finally we discuss the data required to map the dark matter in clusters from photometry alone.
1 Introduction

Quantifying the distribution of dark matter in the Universe is one of the most important challenges for modern cosmology. Galactic rotation and the dynamical behaviour of groups of galaxies have long shown the presence of mass far in excess of that due to normal stellar populations. As the characteristic scale of structure increases, it appears that dynamical-to-luminous mass ratios increase, consistent with a scenario in which luminous matter is biased towards high density environments. On the largest scales, 30 to 100 $h^{-1}$Mpc, the situation favoured by large-scale flows and perturbations in the galaxy number density is one in which mass roughly traces light and the mean mass density is near critical (e.g. Dekel 1994).

On intermediate scales, rich clusters are of special interest as they represent the largest gravitationally bound objects. Measurement of cluster mass profiles would provide information on the formation history of structure—a problem inexorably bound up with the thermal properties of the dark matter and the cosmological model. The line-of-sight velocity dispersions of galaxies, plus thermal X-ray data, indicate a density parameter of $\Omega_0 \simeq 0.1$ if the $M/L$ ratios from the central 1–2 $h^{-1}$Mpc of clusters are representative. However, these observations are limited in two respects. Firstly, both estimates rely on the assumption of equilibrium models to relate observables to the mass distribution. Substructure in the density or velocity fields is neglected, as are perturbations due to accretion, a simplification which is no longer supported by detailed observations (White, Briel & Henry 1993). Secondly, as both methods rely on galaxies or gas to act as tracers, they are restricted to the central core of the cluster. In order for $\Omega = 1$ to be tenable, we either require existing central mass estimates for clusters to be a severe underestimate, or that more mass is lurking at larger radii. In all bias models that have been discussed, this would take the form of an isothermal halo extending out to roughly 10 $h^{-1}$ Mpc.

It is clearly of great importance to test these alternatives, and a new powerful method has been to use the properties of gravitational lensing of images behind the cluster to probe the integrated mass profile. The shear distortion of images by gravitational lensing has been explored in detail since the pioneering work of Tyson et al. (1984). The statistical distortion of off-axis images behind extended mass distributions has been well explored theoretically (e.g. Kochanek 1990, Miralda-Escudé 1991, Kaiser & Squires 1993) and there is widespread interest in using observational data to detect and interpret this effect (Tyson et al. 1990; Kneib et al. 1994; Smail et al. 1993, 1994; Fahlman et al. 1994; Bonnet, Mellier & Fort 1994). Conclusive detections are difficult due to the requirement of obtaining data of high enough quality that higher order moments of faint galaxy images can be measured in the presence of atmospheric seeing and the fundamental limitation imposed by the intrinsic dispersion of galaxy ellipticities. Also, the forms of cluster mass distributions are not known in advance so that ambiguity arises in choosing appropriate potentials to test against the data.

This latter problem has been overcome, in the limit of weak amplifications, by Kaiser & Squires (1993). They demonstrate a nonlocal reconstruction technique for deriving an arbitrary projected potential based on the distortion of galaxy ellipticities.
Initial applications of this method by Fahlman et al. 1994, Smail et al. 1994 and Bonnet et al. 1994 have yielded very encouraging detections of dark matter in the central \( \sim 1 \) Mpc of several clusters. However, this approach is still not completely general. In the case of sheet-like matter distributions, images are not distorted, and hence the potential cannot be recovered. By working only with the shear, the first-order effect of the lens (its amplification) is ignored. Although large numbers of galaxies allow the higher order effects of derivatives of the mass distribution to be detected in principle, it would clearly be preferable to have a more direct method.

In this paper we investigate an alternative approach to recovering the surface potential of clusters which relies solely on the amplification of galaxies in the cluster background. Our method is simply to compare the bivariate distribution of redshift and magnitude, \( N(m, z) \), of galaxies behind the cluster with that of the general field, to the same magnitude limit. The observable difference arises solely from the amplification of distant galaxy images. We show that in the weak field limit this amplification can be related directly to the surface mass density. This allows us to use the transformation of \( N(m, z) \) with radius from the center of the cluster as a model independent estimate of the mass distribution of the cluster.

The method is of course limited by the shot noise due to finite numbers of background galaxies. Fluctuations in the redshift and magnitude distribution due to the intrinsic clustering of galaxies in the background are also a potential problem. However, these only affect the redshift distribution; the magnitude distribution at each redshift can be used to give a mass estimate which may be compared with the independent measurement obtained from distortion in the redshift distribution.

In general, the methods we present here can be thought of as a natural extension of the faint imaging work by the addition of redshift information for the faint galaxies. Imaging at high spatial resolution can constrain the shape of the potential with a smoothing scale of 0.5 – 1 arcmin. However, we argue that the depth of the potential, and therefore the general M/L, is most reliably constrained by full redshift-magnitude information. The angular resolution that our method can attain is coarser by a factor of a few than what is possible with imaging (in a given area of sky there are many fewer galaxies to a practical spectroscopic limit to average over, but the signal is stronger). The alternatives of image shear and redshift information are thus complementary, allowing the fullest characterisation of the cluster potential.

The paper is organized as follows. In Section 2 we set out the basic principles of the lensing distortion effect on the redshift-magnitude distribution. The lens amplification and the background population of galaxies are also discussed. In Section 3 we show that in the regime of weak gravitational lensing, the distortion can be related to the surface potential of the lensing cluster for any reasonably smooth, but otherwise arbitrary potential distribution. The effects of the background cosmological model on the distortion and possible confusion with extinction by cluster dust is also considered. Maximum likelihood reconstruction techniques are presented in Section 4, where we consider the effects of intrinsic galaxy clustering and discreteness. Section 5 discusses the application of these methods in practice. We present a number of numerical realizations of the effect and apply the likelihood estimators to these. We consider observational strategies to minimize the amount of telescope time needed to detect dark matter, either in an individual cluster or statistically by averaging over clusters. Section 6 considers the price paid in accuracy and bias of the results if red-
shift estimates of restricted accuracy are used. Finally, in Section 7, we summarize our conclusions.

2 Lensing of background galaxies

The general distribution of galaxies in redshift and luminosity is described by a bivariate luminosity function, \( \phi(L, z) \), which gives the comoving number density of galaxies per unit interval in redshift and luminosity. Allowing for galaxy clustering, this can be decomposed into

\[
\phi(L, z) = \phi_0(L, z)[1 + \delta(x, L)],
\]

where \( \phi_0 \) is the (evolving) expectation of the luminosity function. In the limit that galaxy luminosity is independent of environment (assumed hereafter), the density perturbation \( \delta \) is independent of \( L \).

The relation of this luminosity function to the observed bivariate distribution \( N(m, z) \) is just

\[
N(m, z) \, dm \, dz = \phi(L, z) \, dL \, dV(z).
\]

Here \( N(m, z) \) is the number of objects per steradian in the interval \( dm \, dz \). The luminosity \( L(z) \) is given by

\[
L(z) = 4\pi S d^2_\text{L}(z)(1 + z)^{\alpha - 1},
\]

where \( d_\text{L}(z) \) is the luminosity distance to the source, \( S \) is the flux density of the source, and \( \alpha \) is the effective spectral index of the source (in the sense \( S \propto \nu^{-\alpha} \)); note that we do not assume power-law spectra – this is just another way of writing the K-correction.

What is the effect of a gravitational lens on a background population of galaxies? Lensing is well-known to conserve surface brightness, distorting image shapes and increasing their area by some amplification factor \( A \). The effect this has on a galaxy catalogue created from lensed data depends on how galaxy magnitudes are defined. Most commonly these are isophotal, in which case the effect of lensing is to scale galaxy fluxes in the same way as for a point source: increase by a factor \( A \). For fixed angular apertures things are more complex, however. If the growth curve for galaxy flux is a power law in radius, \( L(< r) \propto r^\epsilon \), then lensing increases apparent fluxes by \( A^{1-\epsilon/2} \). Since realistic values of \( \epsilon \) are \( \approx 0.5 \), this is not very different from the behaviour of isophotal magnitudes; the use of apertures thus weakens the sensitivity of the methods discussed here by a factor \( \approx 0.75 \). In what follows, we shall assume isophotal magnitudes, and neglect this factor.

The effect of the foreground lens is then simply to translate the apparent magnitude distribution of background galaxies by some redshift-dependent amplification factor, \( A(z) \), and to reduce the surface density through the simultaneous distortion of the angular distances between galaxies:

\[
N'(m, z) = N(m + 2.5 \log_{10} A(z), z) / A(z).
\]

We show below that the function \( A(z) \) will usually depend on only one parameter: the surface density of the lens. Given knowledge of the unperturbed counts, it would then be tempting to use maximum likelihood and the above equation to determine the lens density by fitting to the 2-dimensional \((m, z)\) distribution. However, this is not
so straightforward because the numbers of galaxies in a given redshift bin are subject to fluctuations caused by galaxy clustering. In contrast, the distribution in magnitude can be renormalized at each redshift slice to eliminate clustering variations. It therefore makes sense to consider extracting information from the redshift and magnitude axes separately.

2.1 Lensing and the Redshift Distribution

Suppose we integrate over apparent magnitude to obtain \( n(z) \) – the number of galaxies in the redshift interval \( dz \) per steradian:

\[
n(z) \, dz = dV(z) \int_{L_{\text{min}}}^{\infty} \phi(L, z) \, dL,
\]

(5)

with intrinsic luminosity above the limiting luminosity set by the flux limit of the detector. The effect of placing a lens in front of a magnitude limited galaxy distribution is to decrease the effective flux limit, due to conservation of surface brightness. From equation (4), we see that the effect of lensing on the redshift distribution is

\[
n'(z) \, dz = A^{-1} \Phi[L_{\text{min}}(z)/A, z] \, dV(z),
\]

\[
\simeq A^{\beta(z)-1} n(z) \, dz,
\]

(6)

where the integral luminosity function is denoted by \( \Phi \). Here we have approximated the luminosity function as a power law, where

\[
\beta(z) \equiv - \frac{d \ln \Phi[L(z), z]}{d \ln L(z)}
\]

(7)

is the effective index of the luminosity function. As far as the redshift-distribution distortions are concerned, this is a quite accurate enough approximation and considerably simplifies the analysis. From this definition of \( \beta(z) \) and \( L(z) \), we see that at small redshift the angular scattering of images by the lens will dominate, and the redshift distribution will drop. Meanwhile at large redshift the increase in the total number of observable galaxies will dominate. In Figure 1 we show this distortion for a range of amplification factors. As expected, there is a node where the effects cancel. Hence, given a suitable model for the unlensed distribution function’s power-law index (see Section 2.4) the change in the shape of \( n(z) \) with redshift can be measured, thus yielding \( A(z) \). Although this increasing tail of high-redshift objects is clear enough in theory, the accuracy to which the shape of \( n(z) \) can be determined is limited by galaxy clustering fluctuations and shot noise. We consider these in quantitative detail in Section 4.2.

2.2 Lensing and the Luminosity Distribution

Even in the presence of very large and unknown density fluctuations as a function of redshift, it is still possible to detect a lensing signal. The amplification of galaxy luminosities due to the lens results in a shift in the luminosity function, which can be studied in a clustering-independent manner if the luminosity function is renormalized to become the probability distribution, \( P(m|z) \). In the limiting case of a pure power
law luminosity function, $\Phi(L) \propto L^\beta$, this probability distribution is invariant to any shift, and no distortion can be measured. However, realistic distributions in luminosity have a non–power law cutoff. As an example, consider an exponential luminosity function $\Phi = \exp(-L/L_*)$. It is a simple exercise to use the normalized version of this distribution to obtain the maximum-likelihood estimate of $L_*$ and its uncertainty from a set of $n$ galaxies (see Section 4). For an assumed $L_*$, this gives an estimate of the amplification, with a fractional rms accuracy

$$\frac{\sigma_A}{A} = \frac{1}{\sqrt{n}}$$  \hspace{1cm} (8)

Although it is possible to find pathological examples such as the top hat distribution where the existence of a sharp feature means that the fractional error in $A$ goes as $1/n$, any distributions of practical interest will always obey the $1/\sqrt{n}$ scaling – although the coefficient may be $\gg 1$ if the distribution is close to a power law.

These methods provide us with two independent methods for estimating the strength of the lens. One results from the net effect of the amplification and area dilution in redshift, the second is a redshift dependent shift in the magnitude distribution from the amplification alone. Each method provides an independent measure of the lens amplification, and has the advantage of restricting the effects of galaxy clustering to only one of the methods.

### 2.3 Lens Amplification

The amplification factor, $A(z)$, is the determinant of the deformation tensor describing the mapping from source plane to the image plane (see Section 3), and can in general be expressed in terms of the convergence and shear distortions of an object in the source plane onto the image plane (Young 1981; Miralda–Escudé 1991). Thus the amplification can be expressed as the increase in total surface area,

$$A = \frac{1}{(1 - \kappa)^2 - \gamma^2},$$  \hspace{1cm} (9)

where $\kappa$ is the amplitude of the convergence and $\gamma$ the amplitude of the shear of the image. For example, in the case of a singular isothermal cluster, $\gamma = \kappa = \Sigma/\Sigma_C$, where $\Sigma_C$ is the critical surface density producing a caustic for a sheet lens:

$$\Sigma_C(z) \equiv \frac{c^2 D_S}{4\pi G D_L D_{LS}}.$$

$D_L$ and $D_S$ are the angular distances to the lens and source, and $D_{LS}$ is the angular distance of the source as seen at the lens (we shall use the filled–beam approximation). In the specific case of $\Omega_0 = 1$, the angular distance is

$$D_{LS}(z_L, z_S) = \frac{2c}{H_0} \frac{[(1 + z_L)^{-1/2} - (1 + z_S)^{-1/2}]}{(1 + z_S)}.$$  \hspace{1cm} (11)

where $z_L$ and $z_S$ are the redshifts of the lens and source, respectively. In Section 3.2 we shall discuss the effects of altering the cosmological model.

We have now assembled the necessary expressions for reconstructing the surface density of clusters. Given the lens-distorted $N'(m, z)$ and a form for the true $N(m, z)$,
we can calculate the amplification factor. In the next Section we shall discuss what is known empirically of the background population, while in Section 3 we show under what general conditions the amplification factor can be related to the surface density.

2.4 The background galaxy population

The redshift distribution of faint field galaxies, and its magnitude dependence, is now being defined directly by redshift surveys (e.g. Colless et al. 1993; Glazebrook et al. 1994). We shall use results from a model designed to fit these data by making specific assumptions about cosmology and evolution of the luminosity function. However, it is important to emphasize that the functions we require \( N(m,z), n(z), \beta(z) \), defined in equations 2, 5 and 7 are in principle directly observable and model-independent.

One possibility would be to use the model discussed by Broadhurst, Ellis & Glazebrook (1992). This assumes \( \Omega = 1 \) and a galaxy population divided into five distinct types from irregular to elliptical, together with appropriate K-corrections. The luminosity function undergoes ‘merging’ evolution in which galaxies are typically less luminous but more numerous in the past; this yields the required excess numbers of faint galaxies without producing a large number of (unobserved) galaxies at \( z > \sim 1 \).

It would be possible to work directly with the population of the \((m,z)\) grid output by such a model. However, since this model is relatively complex, we have chosen to illustrate the results of this paper in terms of a simpler analytic construction. We use a single Schechter function which undergoes a combination of luminosity and density evolution:

\[
\phi(L) = \phi^*(z) \exp\left[-\frac{L}{L_*}\right],
\]

(12)

where \( \phi^*(z) = 0.02h^3(1+z)^2 h^{-1}\text{Mpc}^{-3} \), and luminosity evolution is simulated by assuming a constant \( L_* \), and a constant spectral index \( \alpha = 3 \) (i.e. \( K(z) = 5 \log_{10}[1+z] \)); For practical comparisons, we choose to work in the \( R \) band, in which the value \( M_R^* = -21.5 \) for \( h = 1 \) is appropriate for this model. \( \Omega = 1 \) is assumed, but all that is needed is the empirical \( m-z \) distribution, which is independent of cosmological assumptions. This model is in fact quite realistic: it gives a good fit to the observed \( R \)-band counts (Metcalf et al. 1994), and predicts median redshifts in accord with observation to the limit of existing data.

Given the luminosity function, it is easy to find the numerical results for \( n(z) \), and \( \beta(z) \). For practical purposes, we will often be interested in working at the faint limit for spectroscopy, which we take to be \( R = 22.5 \). The \( n(z) \) and \( \beta(z) \) functions for this case may be fitted directly by the following expressions, which we have adopted for convenience at the appropriate points of the analysis:

\[
n(z) = 11.7 z^{1.63} \exp\left[-(z/0.51)^{1.74}\right],
\]

(13)

\[
\beta(z) = 0.15 + 0.6z + 1.1z^{3.2}.
\]

(14)

Recall that \( n(z) \) refers to the probability distribution for redshift and may be normalised to the cumulative surface density (which at \( R = 22.5 \) is approximately 20,000 per square degree).

3 Weak lensing limit
3.1 Smooth lensing potentials

We have shown above that, in principle, the mean amplification over part of a cluster can be produced by obtaining data for background galaxies. The question now is what information this would give us about the mass distribution. In fact, under certain very reasonable assumptions, it turns out that one is able to recover the projected mass distribution of the cluster directly.

Consider the case of sources at a given redshift, so that the lensing equation can be written in terms of the lensing potential:

\[ \theta = \phi + \nabla \psi. \]  

(15)

The amplification of background images is just the reciprocal of the Jacobian determinant, given by

\[ A^{-1} = \left| \det \left( \delta_{ij} - \frac{\partial^2 \psi}{\partial \theta_i \partial \theta_j} \right) \right|. \]  

(16)

Except in the case of strong lensing, the determinant is always positive and the amplification becomes

\[ A^{-1} = 1 - \nabla^2 \psi + \frac{\partial^2 \psi \partial^2 \psi}{\partial x^2 \partial y^2} - \left[ \frac{\partial^2 \psi}{\partial x \partial y} \right]^2 \]  

(17)

(definition 2D angular cartesian coordinates \( x \) & \( y \): \( \theta = \sqrt{x^2 + y^2} \)). Since Poisson’s equation in this context says

\[ \nabla^2 \psi = 2 \Sigma \Sigma, \]  

(18)

the surface density of the lens may be measured directly if the terms nonlinear in potential derivatives may be dropped. This would be the case if the lens was simply a screen of constant surface density; the question is therefore to what extent this is a reasonable approximation to the mass distribution in the outer parts of clusters.

Although we will almost always be working in the weak lensing regime \( A - 1 \ll 1 \), this alone does not guarantee that the shear terms are negligible: any given amplification can be achieved with zero surface density, given an appropriate degree of shear. To make progress, we need in addition to assume that the lens is smooth. This is a reasonable assumption in the case of cluster dark matter, where there is a characteristic angle in the form of the Einstein-ring radius \( \theta_E \). We know from the lack of multiply-imaged galaxies in the outer parts of clusters that the dark matter does not contain structure on the arcsecond scale (apart from individual cluster galaxies, which must be allowed for separately). A general lens may have its lensing potential described as a 2D Fourier transform: \( \psi = \sum \psi_k \exp(-ik \cdot r) \). Constructing the second derivatives of this expression and squaring, we see that all derivatives will have similar mean square values if the potential fluctuations are reasonably isotropic

\[ \langle \psi_{xx}^2 \rangle \sim \langle \psi_{yy}^2 \rangle \sim \langle \psi_{xy}^2 \rangle \sim \sum |\psi_k|^2 k^4 \sim \left[ \frac{\Sigma \Sigma}{\Sigma \Sigma} \right]^2, \]  

(19)

where we have used Poisson’s equation to define a typical surface density, \( \Sigma_\star \), about which the lens fluctuates. If the potential is grossly anisotropic, so that it contains
wavevectors pointing only in one direction, the shear vanishes, so statistical isotropy is the worst case. We can therefore write

$$\frac{\Sigma}{\Sigma_{C}} = 1 - A^{-1} + O\left(\left(\frac{\Sigma_{\ast}}{\Sigma_{C}}\right)^{2}\right). \tag{20}$$

Since it is reasonable to assume that the typical surface density declines roughly monotonically with radius in a cluster, it should therefore be a good approximation in practice to neglect shear and deduce the surface density directly from amplification, provided only that the amplification factor is close to unity. This procedure must break down sufficiently near the center, but at this point there are in any case few background galaxies over which to average; it is better to constrain the central projected mass by using arcs from individual galaxies near caustics.

### 3.2 Effects of cosmological model in the weak field limit

As we have shown in Section 2, the distortion effect of the lens is completely characterized by the amplification function $A(z)$. It is convenient to write this, in the weak field approximation as

$$A(z) = 1 + 2\kappa(z), \tag{21}$$

where $\kappa$ is the amplitude of the convergence (Section 2.3). As this is a function of the critical surface density, defined by the equation

$$\kappa(z) = \frac{\Sigma}{\Sigma_{C}(z)}, \tag{22}$$

which is itself a function of angular distance, the resulting amplification is also a function of cosmological model. We can absorb some of the dependence on cosmological model by parameterizing the lens via the value of $\kappa$ for a source placed at infinity: $\kappa_{\infty}$. Note that expressing the potential in this limit is done only for theoretical convenience; for practical calculations one must use the smaller quantity $\kappa(z)$.

For the modelling of lensing amplification, we need to know whether the redshift dependent quantity $\kappa/\kappa_{\infty}$ depends significantly on cosmological model. If the cosmological constant is zero, we have

$$\frac{\kappa(z)}{\kappa_{\infty}} = \frac{g(z_{L})[2 - \Omega_{0} + \Omega_{0}z_{0}] - g(z_{0})[2 - \Omega_{0} + \Omega_{0}z_{L}]}{g(z_{L})[2 - \Omega_{0} + \Omega_{0}z_{L} + (\Omega_{0} - 2)g(z_{L})]}, \tag{23}$$

where $g(z) \equiv \sqrt{1 + \Omega_{0}z}$ (Refsdal 1966). Figure 2a shows the ratio $\kappa(z)/\kappa_{\infty}$ for $\Omega_{0} = 0.1$ and $\Omega_{0} = 1$ and for lenses at redshifts $z_{L}$ = 0.1 to 0.4. For a given lens redshift these models differ little over this range.

In the other case of interest, that of a flat model with a nonzero cosmological constant, we must use $D_{L,S} = D(z_{0}) - D(z_{L})/(1 + z_{L})$ and

$$D(z) = \frac{c}{H_{0}} \frac{1}{(1 + z)} \int_{0}^{z} \frac{dz}{[(1 - \Omega_{0}) + \Omega_{0}(1 + z)^{3}]^{1/2}},$$

$$\simeq \frac{c}{H_{0}} \frac{z}{(1 + z)(1 + 3\Omega_{0}z/4)}. \tag{24}$$

As no expression for the angular distance exists in closed form (Dabrowski & Stelmach 1986), we have given an approximate expression in the second line by expanding the
integrand to first order. This is sufficiently accurate for \( z < 1 \). The amplification ratio, \( \kappa(z)/\kappa_\infty \), for this model is shown in Figure 2b for \( \Omega_0 = 0.1 \) and \( \Omega_0 = 1 \), again for a range of lens redshifts. As in the open model, the effect on the amplification is marginal. Hence we shall only consider the Einstein–de-Sitter model, where

\[
\frac{\kappa(z)}{\kappa_\infty} = f(z),
\]

\[
f(z) = \frac{\sqrt{1+z} - \sqrt{1+z_L}}{\sqrt{1+z} - 1}.
\]  

(25)

To relate the dimensionless surface-density measure \( \kappa_\infty \) to physical values, we need the critical value of surface density \( \Sigma_C \)

\[
\Sigma_C = 10^{15.22} \frac{M_\odot}{\text{Mpc}^{-2}} \frac{(D_s/\text{Gpc})^2}{(D_L/\text{Gpc})(D_L/\text{Gpc})},
\]

(26)

Again using Refsdal’s (1966) result, this gives the physical surface density in terms of \( \kappa_\infty \) as

\[
\Sigma = 10^{14.44} h \frac{M_\odot}{\text{Mpc}^{-2}} \times \frac{\Omega^2(1+z_L)^3}{g(z_L)[g(z_L) + (\Omega - 2)(g(z_L) - 1)]} \kappa_\infty.
\]

(27)

(for zero \( \Lambda \)). Again, this is rather insensitive to \( \Omega \), particularly since we are usually interested in relatively low lens redshifts, \( z_L \lesssim 0.5 \). Only a few \% error is introduced by using the \( \Omega = 1 \) form in this regime:

\[
\Sigma = 10^{14.44} h \frac{M_\odot}{\text{Mpc}^{-2}} \frac{(1+z_L)^2}{\sqrt{1+z_L} - 1} \kappa_\infty.
\]

(28)

By comparison, the surface density for an isothermal sphere is

\[
\Sigma = \frac{\sigma^2}{2Gr} = 10^{14.07} \frac{M_\odot}{\text{Mpc}^{-2}} \frac{\sigma^2_{1000}}{r_{\text{Mpc}}^{-1}}.
\]

(29)

As a practical example, we might be interested in measuring \( \Sigma \) at \( 1 h^{-1} \text{Mpc} \) for a system with velocity dispersion \( \sigma = 1000 \text{ km s}^{-1} \), so this corresponds to \( \kappa_\infty = 0.035 \) at \( z_L = 0.3 \). Further examples are the distortion-based measurement of Fahlman et al. (1994) on MS1224 at \( z_L = 0.33 \), which converts to an average \( \kappa_\infty = 0.15 \pm 0.04 \) within a radius of 0.48\( h^{-1} \text{Mpc} \). Alternatively, consider Abell 370 at a redshift \( z_L = 0.374 \). For a source galaxy at \( z_S = 0.724 \), the Einstein radius is inferred from the principal arc curvature to be 25\arcsec (Grossman & Narayan 1989). If the dark matter were a simple isothermal sphere, we would have \( \kappa(0.724) = 0.5 \) at this point (a radius of 0.078\( h^{-1} \text{Mpc} \)). At a radius of 1\( h^{-1} \text{Mpc} \) corresponding to an angular radius of about 5.4\arcmin, we would then expect \( \kappa_\infty \approx 0.09 \). It is therefore clear that an interesting and competitive level of sensitivity for our method will require an rms uncertainty of \( \lesssim 0.05 \) in \( \kappa_\infty \).

### 3.3 Obscuration by cluster halo dust

In addition to lensing, dust in cluster halos will reduce the surface density of observable galaxies. As this is a local effect we model the inclusion of this obscuration by
an additional redshift–independent convergence term, \( \kappa_{\text{dust}} \) (which will generally be negative). In the weak field limit the total convergence measured by an observer is

\[
\kappa(z) = f(z) \kappa_\infty + \kappa_{\text{dust}}. \tag{30}
\]

However, the dust ‘amplification’ will not dilute numbers on the sky by the factor \( 1/A(z) \), due to lensing; this and the different redshift dependence are two ways in which dust can be distinguished from lensing.

Limits can be placed on the abundance of dust in cluster haloes by the cluster avoidance effect of quasars (Boyle et al. 1988), although some dilution is of course expected from lensing itself, given the relatively flat count slope for quasars for \( B>19 \).

More useful are the photometry studies of cluster members (Bower et al. 1992, Ferguson 1993) for which little extinction is claimed. For illustration taking 0.75 of extinction as a fiducial upper limit we find that \( |\kappa_{\text{dust}}| \lesssim 0.3 \). As this introduces an element of uncertainty into the following analysis, we shall leave \( \kappa_{\text{dust}} \) as a free parameter, to be fixed by the observations themselves.

There are two further factors relating to the distribution of dust in the model that we shall now address: the effects of intergalactic dust, or that in intervening galaxies, and the reddening effect of galaxy colours due to scattering by cluster dust. We shall assume there that the intergalactic dust is negligible, since at high redshift this would obscure quasar emission in the optical. Dust in intervening galaxies or clusters is also assumed negligible, given that the probability of multiple objects lying along the line of sight is low (Press & Gunn 1973), and hence so is further obscuration.

The effect of reddening only becomes significant in the event that we wish to use estimates of redshift (see Section 6). In this case a model dependent correction to the colour–magnitude relation may have to be applied before it is used to estimate galaxy redshifts.

4 Maximum-likelihood analysis

4.1 Overview

We now have a model for the changes that a lens of given surface density will produce in the \( N(m,z) \) distribution of galaxies to a given magnitude limit. The next step is to design some procedure to extract an estimate of the surface density from a given set of data, and the obvious candidate is to use the likelihood methodology.

We begin by dividing the redshift and magnitude axes up into \( q_1 \) and \( q_2 \) independent bins, each of which contains \( n \) galaxies and has an expected content of \( \mu \) in the absence of lensing. The desired likelihood function is then given by

\[
\mathcal{L} \propto \prod_{1}^{q} P[n|\mu(\kappa_\infty, z)]. \tag{31}
\]

From this we can obtain an estimate of the lens strength by maximizing \( \mathcal{L} \) with respect to \( \kappa_\infty \), and ‘1\( \sigma \)’ errors on the estimate from

\[
\delta\kappa_\infty = \left( -\frac{\partial^2 \ln \mathcal{L}}{\partial \kappa_\infty^2} \right)^{-1/2}. \tag{32}
\]
The size of the bins is determined in order to fulfill the criteria of statistical independence assumed in equation (31). In the case of magnitude space, each galaxy is randomly selected from the luminosity distribution, and hence completely independent. In this case the bins can be made infinitely small, so that \( q_2 \) is the number of galaxies, and \( n = 1 \) per bin.

It is tempting to do this also in the case of the redshift distribution. However, this would only be a good idea if the expected distribution of background galaxies was Poissonian. In practice a crucial limiting factor in this analysis will be galaxy clustering. There is no point in making the bins shorter in radial extent than the coherence length of galaxy clustering \( \simeq 10h^{-1} \text{ Mpc} \), as they will then experience correlated fluctuations. It is therefore important to calculate fully the probability distribution for \( n \) in the presence of both finite-\( n \) fluctuations and fluctuations from galaxy clustering; this is undertaken in the next section.

The problem of galaxy clustering in the redshift distribution raises one further complication, which we mention here. Gravitational lensing affects the background galaxies in two ways: it changes the shape of the redshift probability distribution by reducing the fraction of low-\( z \) galaxies and boosting the proportion of high-\( z \) galaxies. It also produces a slight boost in total numbers to a fixed apparent magnitude, since the latter effect generally overcomes the former. We shall nevertheless neglect this effect in our analysis, and concentrate only on the shape of the redshift distribution. The reason for this is that in practice it is harder to obtain a robust prediction of the background redshift distribution in absolute terms: galaxy clustering in any normalization field off-cluster means that the background surface density is not known precisely. If we instead focus on the probability distribution for redshift, this uncertainty is unimportant; this procedure also takes out part of the effect of any galaxy clustering in galaxies behind the target cluster, as well as making the calculation less sensitive to any uncertainty in the exact limiting magnitude of the data. In what follows, the expected number of galaxies in a given bin, \( \mu \), will therefore be deduced by normalizing to the total observed number over the redshift range over which the analysis is performed.

4.2 Redshift analysis

4.2.1 Effects of background galaxy clustering

The problem to be solved is to find the probability distribution for the number of galaxies in a given redshift bin, allowing for both Poisson statistics and galaxy clustering. As far as the latter is concerned, it is relatively easy to calculate the fractional rms number fluctuation, if we have some hypothesis for the clustering power spectrum at the redshift of interest. If we call the power spectrum \( \Delta^2(k) \) (meaning power per log wavelength), then the required rms \( \sigma \) is just

\[
\sigma^2 = \int \Delta^2(k) |W(k)|^2 \frac{dk}{k},
\]

(33)

where \( W(k) \) is the azimuthally-averaged Fourier transform of the spatial bin under consideration. One can similarly work out the covariance between the numbers in different bins. For power spectra of interest, this turns out to be negligibly small for all but adjacent bins. For these, there is a small degree of coupling (correlation coefficient \( \simeq 0.2 \)), but we have neglected this and treated the individual cells as independent. To
within the accuracy to which $\sigma^2$ can be calculated, this is an unimportant source of error.

In principle, to work out the cosmic variance for a given power spectrum and form of bin requires a 6-dimensional integral to be performed numerically. Fortunately, things simplify a good deal in cases of practical interest. The bin is defined by some angular selection on the sky, and so its transverse extent is a function of redshift. However, since we want reasonable redshift resolution, $\delta z / z$ is small and it is a reasonable approximation to treat the bin as having constant width. We then have a factorization into the product of a radial window and a transverse window, and the Fourier transform of the bin similarly factorizes into a product of the two $k$-space windows. We can further choose to make life easy by picking windows with analytic Fourier transforms; if the angular window is further chosen to be circularly symmetric, we are left with only a two-dimensional integral over wavenumber $k$ and polar angle in $k$ space.

For example, consider the case of a cylindrical bin of length $L$ and radius $R$; the more practically interesting case of transverse selection in some annulus can be obtained simply from this. The window function is

$$W(k, \mu) = \frac{\sin \frac{\mu k L}{2}}{\frac{\mu k L}{2}} \frac{2}{kR \sqrt{1 - \mu^2}} I_1(kR \sqrt{1 - \mu^2}),$$

where $\mu = \hat{k} \cdot \hat{r}$ is the cosine of the polar angle. Given a power spectrum, we can now find the cosmic variance for any given bin width and length. The simplest model which is realistic is to use the Fourier transform of the canonical small-separation correlation function, $\xi(r) = [r/5h^{-1}\text{Mpc}]^{-1.8}$; the true power spectrum curves below this function at large wavelength (Peacock 1991), so this is a conservative calculation. It will be important to include evolution, since we expect that clustering at high $z$ will be less than today. In general the shape of the power spectrum is expected to alter as well as its amplitude, but we can only allow for this by the rash step of picking a specific physical mechanism for the evolution. We prefer the empirical approach of allowing for a scaling of the clustering amplitude by some power of $(1 + z)$. The model for the power spectrum is thus

$$\Delta^2(k) = 0.903[5(k/h \text{ Mpc}^{-1})]^{1.8} (1 + z)^{-\epsilon}.$$  

We work throughout with comoving length units; $\epsilon = 0$ thus corresponds to the case of ‘painted-on’ clustering that expands with the Hubble flow; $\epsilon = 2$ corresponds to linear-theory evolution, and is close to what appears to be required by recent data on faint-galaxy clustering (e.g. Couch, Jurcevic & Boyle 1993). Figure 3 shows the redshift dependence of the variance with this evolution.

Of course, we need more than just a variance to specify the distribution of galaxy counts. A useful model to adopt for this is the Lognormal (e.g. Coles & Jones 1991). This not only modifies the common assumption of a Gaussian random field to satisfy the physical constraint of positivity, it also has some empirical support going back to Hubble. From the point of view of fitting the lens model, it is not too critical that the lognormal model applies; the reason for adopting it is that it provides a convenient means for generating realistic mock datasets for testing our algorithms. The way the lognormal model works is to generate a Gaussian density fluctuation, $\delta$, of mean zero and rms $\sigma$, and to construct a new density perturbation

$$1 + \delta' = \exp[\delta - \sigma^2/2].$$
The last term here is a normalization factor: \( \langle \exp \delta \rangle = \exp[\sigma^2/2] \). Furthermore, the variance of the lognormal density field as defined above is \( \langle (\delta')^2 \rangle = \exp[\sigma^2] - 1 \); the parameter \( \sigma^2 \) should therefore be

\[
\sigma^2 = \ln \left[ 1 + \langle (\delta')^2 \rangle \right],
\]

(37)

where \( \langle (\delta')^2 \rangle \) is the cosmic variance calculated from the observed power spectrum.

To incorporate finite-N fluctuations, we assume that the observed number of galaxies, \( n \), is drawn Poissonianly from an expected number, \( \bar{n} \), which is itself subject to lognormal fluctuations about some ensemble average \( \mu \). The overall probability of getting \( n \) galaxies is then given in terms of the Poisson and Gaussian distributions by

\[
P(n|\mu, \sigma) = \int P_P[n|\mu \exp(x)] \, dP_G(x).
\]

(38)

The parameter \( \mu \) in this equation is \( \exp -\sigma^2/2 \) times the ensemble mean, for the reasons of normalization discussed above.

In Figure 4, we show a series of background redshift distributions to demonstrate the effect of varying the lens amplification and of the variance due to lognormal density fluctuations. The lognormal field (filled dots) can be seen to fluctuate increasingly about the underlying mean observed density field (solid line) as the variance is increased (from left to right). Further scatter about the mean field is induced by the Poissonian sampling of the lognormal field (histogram). Clearly, in extreme cases of a highly evolved density field (\( \sigma = 1 \)), the underlying mean field is difficult to recover.

### 4.2.2 Maximum likelihood analysis of the redshift distribution

Using this statistical procedure we can now construct a maximum likelihood function, based on the random sampling of a lognormal density field. We divide the redshift distribution into bins larger than the correlation length of clustering, and assume that each bin is uncorrelated. Using the probability distribution of equation (38) for the number of galaxies in a cell, the likelihood function over all bins is

\[
\mathcal{L}(\kappa_\infty|n, \mu, \sigma) = \prod_i P(n_i|\mu, \sigma_i),
\]

(39)

where we have again parameterized the distortion in terms of the surface density at infinity.

In Figure 5a,b we show the unlensed and lensed redshift distributions of a Poisson sampled lognormal field of 300 galaxies. For the bin size of \( \Delta z = 0.05 \) and radius 5’ used here, we expect the variance to be approximately \( \sigma = 0.2 \) at redshift of 0.5 (Figure 3). We used a singular isothermal cluster model placed at a redshift of \( z = 0.2 \), and with a lens convergence amplitude at infinity of \( \kappa_\infty = 0.2 \). This value for the mean convergence interior to the limiting radius corresponds to a 1D velocity dispersion \( \sigma_v \approx 1500 \text{ km s}^{-1} \) for an isothermal sphere.

Figure 5c shows the normalized likelihood function as a function of \( \kappa_\infty \) for the reconstructed lens producing a maximum likelihood value of \( \kappa_\infty = 0.2 \pm 0.06 \), which demonstrates that the input amplification can be recovered. Extending the model to include a homogeneous, negative contribution from cluster dust, parameterized by
\( \kappa_{\text{dust}} = -0.2 \), the lensed and dust obscured redshift distribution is shown in Figure 6a,b. Keeping the dust obscuration as a free parameter, the calculated likelihood contours are calculated and plotted in Figure 6c. The contours are separated by \( \Delta \ln L = -0.5 \). The likelihood function is maximized in parameter space for values of \( \kappa_{\infty} = 0.2 \pm 0.07 \) and \( |\kappa_{\text{dust}}| = 0.18 \pm 0.015 \). Note we actually have more information of the values of \( \kappa_{\infty} \) and \( \kappa_{\text{dust}} \), given that these must be, respectively, positive-definite and negative-definite parameters. It is apparent from these figures that the recovery of the amplification factor of the lens along the redshift axis is viable, even with the inclusion of obscuration by dust.

### 4.3 Magnitude–space analysis

As noted earlier, the statistical analysis in magnitude–space is considerably easier than redshift–space due to the statistical independence of galaxies. This follows directly from equation (1) in the limit that galaxy luminosities are independent of environment.

The shift in apparent magnitude distribution at each redshift compared with the field can be modelled by the conditional probability function

\[
p(m|\kappa_{\infty}, z) = \frac{N(m + 2.5 \log_{10} A(z), z)}{\int N(m + 2.5 \log_{10} A(z), z) \, dm}
\]

where we use the model Schechter function luminosity function (Section 2.4), normalized in each redshift bin to the mean field value. Thus fluctuations in the amplitude of the luminosity function due to density perturbations are normalized away.

In this case, we can once again use a likelihood analysis, only this time there is no objection to making the bins infinitesimally small. Since the galaxy population randomly samples luminosity space, each slice in redshift space is statistically independent. Using equation (40) for the probability distribution of luminosities in a redshift slice, the probability of each galaxy occurring in thin slice can be calculated. Hence the likelihood of finding each galaxy in a small volume about \((m_i, z_i)\) in redshift/magnitude space is

\[
\mathcal{L}(\kappa_{\infty}|m) = \prod_{i=1}^{n} p(m_i|\kappa_{\infty}, z_i),
\]

where the product is over all galaxies, \( n \) is the total number of galaxies, and again we have parameterized the amplification in terms if the surface density at infinity.

Figure 7a,b shows two realizations of the distribution in redshift/magnitude space. Figure 7a is the unlensed case, while Figure 7b has the singular isothermal lens at \( z_L = 0.2 \), as before. Again we use a lens magnification corresponding to \( \kappa_{\infty} = 0.2 \). The brightening of galaxies beyond the lens is clearly discernible, while the fluctuations in front of the lens are due to shot noise and clustering.

Figure 7c shows the normalized likelihood function, which is maximized for \( \kappa_{\infty} = 0.22 \pm 0.06 \). While this is comparable with the redshift–distribution method for this particular sample size, as we have already discussed and shall show quantitatively in the next section, there is no lower bound on the accuracy of this method caused by the intrinsic galaxy clustering.

Extending the model to include the homogeneous dust distribution, with \( \kappa_{\text{dust}} = -0.2 \) and no lensing, Figure 8a shows that the high redshift amplification is again
heavily suppressed. Figure 8b shows how the lens acts against this obscuration. The likelihood contours for this model are shown in Figure 8c, where the spacing of contours is 0.5 in log likelihood. The outer contour corresponds to the normalized likelihood of \( e^{-5} \). Maximising the function gives us a solution of \( \kappa_{\infty} = 0.21 \pm 0.05 \) and \( |\kappa_{dust}| = 0.22 \pm 0.015 \).

Given these results for the simulated lensing case, we now proceed to compare the two methods as a function of sample size, and discuss the robustness of our results.

5 Practical application

5.1 Comparison of methods as a function of sample size

In order to compare the two methods, we have run simulations on the above lines, varying the interesting parameters of lens redshift, depth and area on the sky.

For the redshift-distribution method, the error in \( \kappa_{\infty} \) can be modelled by

\[
\sigma_{(z)}^2 = S_1^2(z_L, m_{lim}) + S_2^2(z_L, m_{lim}, \theta),
\]

where

\[
S_1 \approx \frac{1.1 + z_L 10^{-0.2(m_{lim}-22.5)}}{\sqrt{n}} \quad (43)
\]

\[
S_2 \approx 0.05 10^{-0.56z_L(m_{lim}-19.5)} \quad (44)
\]

Interestingly, \( S_2 \) turns out to be almost independent of \( \theta \): the pencil beams of practical relevance (\( \theta \sim 10' \)) are so thin as to be dominated by structures much larger than their widths.

In the case of the magnitude estimator, the variance is invariant to density perturbations and the error is purely shot–noise limited. Again we can model this dependence by

\[
\sigma_{(m)} \approx \frac{0.8 + z_L 10^{-0.2(m_{lim}-23.5)}}{\sqrt{n}} \quad (45)
\]

In both cases, \( n \) is the number of field galaxies to the sample limit (including those in the foreground of the lens). The observed number will of course be augmented by cluster galaxies, but these would be removed in practice by ignoring the redshift bins covering the cluster. The magnitude limit, \( m_{lim} \) is for \( R \) band, but other wavebands could be used by scaling to limits with the same median redshift.

We see that both methods are comparable, and that the redshift estimator is the less accurate, except for small samples and shallow limits. This is reasonable, given that the area dilution effect means that the redshift-estimator signal is largely confined to the few very high-redshift galaxies.

As both approaches are statistically independent of one another, we can simply multiply the two likelihood estimators

\[
\mathcal{L}(\kappa_{\infty}) = \mathcal{L}(\kappa_{\infty} \mid n, \mu, \sigma) \mathcal{L}(\kappa_{\infty} \mid m),
\]

and achieve a total error of \( [1/\sigma_{(z)}^2 + 1/\sigma_{(m)}^2]^{-1/2} \). Clearly, however, it will be preferable to make the two estimates independently and check them for agreement before combining the methods.
The analysis given above assumes that we know the luminosity function of the field population exactly. In practice, this must be estimated from the data. To minimize systematics, the preferable procedure would be to have equivalent data on a cluster and on a number of random comparison fields. We can simulate this procedure here by simulating a field dataset without lens, using a Schechter function of known parameters, fit a new Schechter function to the field realization, and use this to analyze a lens simulation. Clearly, such a procedure will introduce an additional error into any estimate of $\kappa_\infty$, of the same order as that which applies if the luminosity function is known exactly. If several comparison fields exist, this should not be an important source of error.

5.2 Observing strategy

Given the above results, we can ask what is the optimum approach for detecting a given level of dark matter in the minimum telescope time. To see how this scales, we simplify the analysis by assuming Euclidean space and the Poisson limit. This means that the rms error in $\kappa(z_S)$ scales directly as $n^{-1/2}$, for $n$ galaxies. In the low-redshift limit, this says that the number of galaxies required to measure a given $\Sigma$ scales as

$$n \propto \frac{z_S^2}{(z_S - z_L)^2 z_L^2}.$$  \hspace{1cm} (47)

Now, since we are interested in a given area of the cluster, the number of galaxies available is

$$n_{\text{tot}} \propto z_L^{-2} z_S^3.$$ \hspace{1cm} (48)

The maximum signal-to-noise that can be obtained is thus independent of lens redshift for $z_L \ll z_S$, but low lens redshifts require the measurement of more redshifts by virtue of the larger area of sky covered by the cluster.

We now assume that the spectroscopy is background limited, so that the time taken to obtain a given redshift scales as $(\text{flux})^{-2} \propto z_S^4$, and the total time is

$$t \propto z^4 n \propto \frac{z_S^6}{(z_S - z_L)^2 z_L^2}.$$ \hspace{1cm} (49)

The optimum has $z_L = z_S/2$ and the total time scales as $z_S^2$. It is therefore much faster to try to detect the effect by observing bright galaxies and cluster lenses at low redshift. However, the total number of available background galaxies will then be rather small, setting an upper limit to the sensitivity of the measurement. The way round this problem will be to stack clusters statistically, obtaining an average dark matter profile. Although maps for individual clusters would of course be preferable, the increase in speed makes this an attractive way of proceeding initially.

As a concrete example, consider the limit $R = 20$ which is the practical limit for fibre spectrographs; the surface density here is about 1700 deg$^{-2}$. Consider clusters at $z_L = 0.1$, so that $1h^{-1}$ Mpc radius corresponds to 13.5' radius and about 270 available galaxies. For a $\sigma_v = 1000$ km s$^{-1}$ isothermal sphere, the integrated surface density within this radius is $\kappa_\infty = 0.03$. From the above calculations, the redshift and magnitude errors on the $\kappa_\infty$ estimates would be $\sigma_{z(z)} \approx 0.086$ and $\sigma_{m(m)} \approx 0.079$, or a combined rms of 0.062. The observation of 26 clusters would thus permit the detection of this level of dark matter at the 2.5$\sigma$ level.
6 Limited redshift information

6.1 Colour–redshift estimates

The need for redshift information for the above methods can be partly overcome with colour information. At the very least, one can strip away the foreground, by identifying the subset of galaxies redder than the cluster E/S0 galaxies. In principle, given multiwavelength data, it should be possible to estimate redshifts to some limited accuracy for each galaxy. Here one can achieve much fainter magnitudes and hence higher surface densities, trading off the shot–noise contamination against uncertainties in redshift estimation.

Many redshift–independent distance indicators have a power–law relation to the distance, and so the associated errors in redshift may be assumed to have a lognormal distribution. The conditional probability of finding a galaxy at redshift \( z_e \) given that its true redshift is \( z \) is

\[
p(z_e|z)dz = \frac{dz}{\sqrt{2\pi}\sigma_z z} \exp \left( -\frac{1}{2\sigma_z^2} (\ln z_e - \ln z)^2 \right).
\]

(50)

The required probability distribution for the luminosity function is then

\[
p(L|z_e) = \int p(L|z)p(z|z_e)dz.
\]

(51)

The likelihood functions for redshift errors of 5 and 10 % yield uncertainties in \( \kappa_\infty \) of 0.10 and \( \sim 0.4 \) respectively. Clearly errors in the redshift measurement greater than 5 % are unacceptable for our purposes.

6.2 Number–magnitude counts

In the limit that we ignore redshift information altogether, the opportunity to avoid clustering noise is lost. However, the shot–noise contamination is now minimised due to the larger sample size expected from imaging galaxies compared with spectroscopy. Again colour information can be used to remove the cluster E/S0 sequences.

The count slope will be flattened for a fixed amplification since the slope of the magnitude distribution for the field at faint magnitudes is a decreasing function of magnitude, particularly in the near IR where the K-correction dominates over the evolution. This flattening of the count slope is more interesting than the change in amplitude of the counts since it is less susceptible to the clustering fluctuations than the total number.

We may calculate the feasibility of the detection of such a slope change in the background counts by simply projecting our reconstructions into 2–D. Using the usual isothermal lens model at a redshift of \( z_l = 0.2 \), Figure 9 shows the theoretical number–magnitude distribution radially interior to mean convergences of \( \kappa_\infty = 0, 0.1, 0.5 \) and 1 respectively. The main feature is the expected enhanced curvature of the distribution. Superimposed on the plot is the unlensed case of a random selection of 3000 galaxies, in the presence of the same degree of clustering as used above.

We estimate that the error introduced here is of order 0.2 in \( \kappa_\infty \), so this approach is of limited accuracy Furthermore, the required number of galaxies will only be available over areas where \( \kappa_\infty \) is low (\( \kappa_\infty \leq 0.05 \) for 3000 galaxies to \( R = 25.5 \) in this case).
Nevertheless, such a method may be useful for statistical averaging over a number of clusters.

6.3 Size shifts

In principle, the most promising method may be one that uses the lens signature directly. If we plot the field-galaxy population as some measure of galaxy size versus surface brightness, then the effect of a lens is to move all galaxies to larger size at constant surface brightness. The fractional increase in size is just \( \kappa(z_0) \), which will typically be a few \% for the examples illustrated earlier. Given sufficient background galaxies, it should be possible to detect this shift. The practicalities involve the effects of seeing, but we note that the reduction in sensitivity to size shifts caused by seeing will be similar to the reduction in sensitivity to shear. For data with 0.5′′ FWHM seeing, Fahlman et al. (1994) demonstrated only a 30\% reduction in shear sensitivity, and obtained rms shear limits of \( \sim 1\% \) by averaging over about 2500 galaxies. Provided any effect due to cluster galaxies can be removed (by using a colour criterion), this paints an encouraging prospect for the direct detection of lensing via shifts in galaxy size. We hope to investigate this method in detail elsewhere.

7 Conclusions

In this paper, we have presented a new method for measuring the mass distribution in the outer parts of galaxy cluster haloes via gravitational lensing. This is certainly one of the most interesting questions in cosmology: if a critical-density universe is to be compatible with observations, clusters should have extended quasi-isothermal dark haloes, and gravitational lensing is probably the only method by which these can be detected directly. We have tested our methods on realistic simulated data, in the presence of shot noise and fluctuations from galaxy clustering. We estimate that our methods can realistically expect to detect any dark matter halo around clusters out to radii of at least \( 1h^{-1}\text{Mpc} \).

Our reconstruction method is limited by finite numbers of galaxies behind the cluster lens: we must average over some area in order to gather sufficient galaxies to define the redshift distribution. To obtain a map of surface density to a given fractional accuracy requires a number of galaxies per pixel which scales roughly as \( r^2 \) for an isothermal halo. Thus, although in principle one might be able to obtain a genuine map of density with arcmin resolution of the central parts of a cluster, in the most interesting outer regions the method can give only a radial profile in a set of increasingly coarse annuli. Nevertheless, such information is quite adequate for answering the critical questions concerning the relative distributions of mass and light. If we are confined to a radial profile, there is no reason not to stack the signal from several clusters in order to obtain a statistical detection of dark matter at large radii.

We have shown that such an experiment can be made relatively economical in terms of telescope time.

Finally, it is interesting to compare our method with that of Kaiser & Squires. Each technique has strengths and weaknesses, which are largely complementary. The virtue of our method is that it measures the surface density directly, rather than effectively having to differentiate the (noisy) shear. Moreover, we thus avoid the
principal drawback of the Kaiser & Squires method, which is its insensitivity to a
costant-density screen and the corresponding need to assume $\Sigma = 0$ at the data 
boundary. Lastly, the signature of lensing in our method are the sensitivity to galaxy clustering, plus the fact that 
spectroscopic data are more time-consuming to obtain than deep imaging. However, 
we believe we have demonstrated that our method can be made to work well with 
datasets of a practical size and quality. The very different approaches of the two 
reconstruction methods is a great virtue: any case for which these techniques yield 
concordant results deserves to be treated with a high degree of confidence.

A.N.T. is supported by a SERC research assistantship. We thank Richard Bower, 
Richard Ellis, Pippa Goldschmidt, Alan Heavens, Ian Smail and Alex Szalay for useful 
discussions.

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Figure 1: Series of graphs showing the distortion of a model galaxy redshift distribution (from section 2.4) with increasing lens amplification, \( A \), according to equation (6). The amplification factor increases from 1 to 2. The effective local index of the luminosity function, \( \beta(z) \), is parameterized in Section 2.4. Because this is a normalized probability distribution, the distribution changes slightly at \( z < z_L \), even though lensing clearly does not affect the number of galaxies there.

Figure 2: The lens convergence amplitude, \( \kappa(z)/\kappa_\infty \), as a function of density parameter, \( \Omega_0 \), in the range 0.1 to 1 and redshift of the lens, \( z_L = 0.1 \) to 0.4 (a) showing the insensitivity to \( \Omega_0 \) for a given lens redshift. Also (b) the dependence of the lens convergence amplitude, \( \kappa(z)/\kappa_\infty \), as a function of \( \Omega_0 \) and lens redshift, \( z_L \), in a flat universe (\( \Omega_0 + \Omega_\Lambda = 1 \)). \( \Omega_0 \) is in the range 0.1 to 1 and \( z_L = 0.1 \) to 0.4. Again, the ratio is highly insensitive to \( \Omega_\Lambda \) for given lens redshift.

Figure 3: Plots of fractional density variance expected due to galaxy clustering in circular bins of angular radius 5\( \arcmin \) and length \( \Delta z = 0.05 \), as a function of redshift. Clustering is assumed to evolve at the linear-theory rate (\( \epsilon = 2 \)).

Figure 4: Lensed redshift distributions for varying fractional density rms \( \sigma \) and lens strength \( \kappa_\infty \), assuming \( z_L = 0.2 \) and a magnitude limit \( R = 22.5 \). The underlying distribution function (solid line), normalised to a sample of 300 galaxies, is used to construct a lognormal density field (large dotted line), which is then Poisson sampled (histogram). The top row has \( \kappa_\infty = 0.1 \), while the bottom row has \( \kappa_\infty = 0.5 \) for an isothermal lens. The three columns have \( \sigma = 0.1, 0.5, \) and 1, respectively.

Figure 5: Unlensed (a) and lensed redshift distributions (b) for a compounded lognormal–Poisson distribution of galaxies. The underlying rms of density fluctuations is set at \( \sigma = 0.5 \), and there are a total of 300 galaxies in the simulation, corresponding to bins of angular size 5\( \arcmin \) and length \( \Delta z = 0.05 \). The convergence factor used is \( \kappa_\infty = 0.2 \), for a singular isothermal cluster. The corresponding likelihood curve for the lensed distribution is shown (c). The amplification is recovered with an rms error in \( \kappa_\infty \) of \( \sigma_{\kappa_\infty} = 0.06 \).

Figure 6: As for Figure 5, but with isothermal cluster model extended to include a homogeneous distribution of dust. The dust acts so as to suppress the effects of lensing. We parameterize the suppression by \( \kappa_{\text{dust}} = -0.2 \). The likelihood corresponding likelihood contours are plotted (c) with a spacing of \( \Delta \ln L = -0.5 \). The function is maximized by the parameters \( \kappa_\infty = 0.2 \pm 0.07 \) and \( \kappa_{\text{dust}} = -0.18 \pm 0.015 \).
Figure 7: Magnitude/Redshift–space distortions. Figure 7a is the unlensed distribution, while Figure 7b is lensed by a constant-density screen. The lens is placed at $z_L = 0.2$, and the lens amplification is parameterized by $\kappa_\infty = 0.2$. The Likelihood function for magnitude–space distortions is shown (c) for this case. Again we find an rms $\kappa_\infty = 0.22 \pm 0.06$, compared with the input value of 0.2.

Figure 8: Magnitude/Redshift–space distortions. As in Figure 7a,b but with a homogeneous distribution of dust, uniformly suppressing the lensing amplification beyond the lens. Figure 8a shows the distortion from dust only, while 8b is both dust and lensing. The negative contribution to the amplification by the dust is parameterized by $\kappa_{\text{dust}} = -0.2$. Figure 8c shows likelihood contours for magnitude–space distortions from lensing and dust obscuration. Again for a sample of 300 galaxies, we find $\kappa_\infty = 0.21 \pm 0.05$ and $|\kappa_{\text{dust}}| = 0.22 \pm 0.015$.

Figure 9: Number–magnitude distribution (normalised). Theoretical curves for an isothermal lens at $z_L = 0.2$ with $\kappa_\infty = 0, 0.1, 0.5, 1$ are shown. Superimposed is the unlensed case for a sample of 3000 galaxies randomly sampled from a lognormal density field with $\sigma = 1$ at zero redshift. The error on the corresponding estimate of $\kappa_\infty$ would be approximately 0.2.