Additive normal tempered stable processes for equity derivatives and power law scaling

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Abstract

We introduce a simple additive process for equity index derivatives. The model generalizes Lévy Normal Tempered Stable processes (e.g. NIG and VG) with time-dependent parameters. It accurately fits the equity index volatility surfaces in the whole time range of quoted instruments, including options with small time-horizon (days) and long time-horizon (years). We introduce the model via its characteristic function. This allows using classical Fourier pricing techniques. We discuss the calibration issues in detail and we show that, in terms of mean squared error, calibration is on average two orders of magnitude better than both Lévy and Sato processes alternatives.

We show that even if the model loses the classical stationarity property of Lévy processes, it presents interesting scaling properties for the calibrated parameters.

Keywords: Additive process, volatility surface, calibration.

JEL Classification: C51, G13.

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1 Introduction

Following the seminal work of Madan and Seneta (1990), Lévy processes have become a powerful modeling solution that provides parsimonious models consistent with option prices and with underlying asset prices. There are several advantages of this modeling approach: this model class admits a simple closed formula (Carr and Madan 1999, Lewis 2001) and it is a parsimonious description of some key features of the market volatility surface. In particular, the class of Lévy normal tempered stable processes (LTS) appears to be rather flexible and it involves very few parameters. LTS are pure jump processes, obtained via the well-established Lévy subordination technique (see, e.g. Cont and Tankov 2003, Schoutens 2003). Specifically, most of these applications involve two processes in the LTS family: Normal Inverse Gaussian (NIG) (Barndorff-Nielsen 1997) and Variance Gamma (VG) (Madan et al. 1998), which are obtained via two different Lévy subordinators. Both NIG and VG are characterized by three parameters: $\sigma$, which controls the average level of the volatility surface; $k$, which is related to the convexity of the implied volatility surface; and $\eta$, which is linked to the volatility skew (for a definition see, e.g. Gatheral 2011, Ch.3, p.35).

Unfortunately, the recent literature has shown that these models do not reproduce the implied volatilities that are observed in the market data at different time horizons with sufficient precision (see, e.g. Cont and Tankov 2003, Ch.14). Lévy normal tempered stable processes are pure jump models with independent and stationary increments. The key question is as follows: is it reasonable to consider stationary increments when modeling implied volatility? Jump stationarity is a feature that significantly simplifies the model’s characteristics but it is rather difficult to justify a priori from a financial point of view. For example, a market maker in the option market does not consider the consequences of a jump to be equivalent on options with different maturities. He cares about the amount of trading in the underlying required to replicate the option after a jump arrival. The impact of such a jump on the hedging policy is inhomogeneous with option maturity. Hence, a priori, it is not probable that a stationary model can adequately describe implied volatilities.

Additive processes have been proposed to overcome this problem. Additive processes are an extension of Lévy processes that consider independent but not stationary increments. Given an additive process, for every fixed time $t$, it is always possible to define a Lévy process that at time $t$ has the same law as the additive process. This feature allows us to maintain several properties (both analytical and numerical) of the Lévy processes.

The probability description of additive processes is well-established (Sato 1999) but the applications in quantitative finance are relatively few. A first application of additive processes to option pricing is developed by Carr et al. (2007), who investigate Sato processes (Sato 1991) in derivative modeling (see also Eberlein and Madan 2009). Benth and Sgarra (2012) use additive processes, which they call time-inhomogeneous Levy processes, in the electricity market. In their paper, the electricity spot price is characterized by Ornstein-Uhlenbeck processes, which are driven by additive processes. More recently, Li et al. (2016) have considered a larger class of additive processes. Their paper studies additive subordination, which (they show) is a useful technique for

1The relevance of pure jump dynamics in the equity and commodity asset classes has been discussed in the recent literature, see, e.g. Ornthanalai (2014), Li and Linetsky (2014), Ballotta and Rayée (2018).

2Gamma is the Greek measure that quantifies the amount of this hedging and, generally, it decreases with time-to-maturity.
constructing time inhomogeneous Markov processes with an analytically tractable characteristic function. This technique is a natural generalization of Lévy subordination.

We introduce a new class of (pure-jump) additive processes through their characteristic function which are named additive normal tempered stable (ATS) processes. ATS processes (in general) cannot be obtained via a time-change as in the additive subordination of Li et al. (2016) and are not Sato processes. There is a subclass of ATS obtained via additive subordination and a subclass of Sato ATS process. The main advantage of this new class of models is the possibility to “exactly” calibrate the term structure of observed implied volatility surfaces, while maintaining the parsimony of LTS.

We provide a calibration example of the ATS on the S&P 500 and EURO STOXX 50 implied volatility surfaces of the 30th of May 2013. The ATS calibration is on average two orders of magnitude better than the corresponding LTS in terms of mean squared error. We show that the calibrated time-dependent parameters present an interesting and statistically relevant self-similar behavior compatible with a power-law scaling subcase of ATS. Moreover, we have verified that these results are robust over time.

The main contributions of this paper are threefold. First, we introduce a new broad family of additive processes, which we call additive normal tempered stable (ATS) processes. Second, we calibrate the ATS processes on S&P 500 and EURO STOXX 50 volatility surfaces. We show that ATS have better calibration features (in terms of both the Mean Squared Error and the Mean Absolute Percentage Error) than LTS and Sato processes. Finally, we consider a re-scaled ATS process via a time-change based on the implied volatility term structure. We show that the calibrated parameters exhibit a self-similar behavior w.r.t. the new time. The statistical relevance of these scaling properties is verified.

The rest of the paper is organized as follows. In Section 2, we introduce the model: we prove that there exists a new family of additive processes as the natural extension of the corresponding Lévy processes. In Section 3, we describe the dataset used in the calibration, the calibration results for ATS, LTS, and Sato processes and an interesting scaling property of the calibrated parameters. In Section 4, we show that LTS and Sato processes fail to reproduce some stylized facts observed in market data, which are adequately described by ATS processes and we present a robustness analysis. Finally, Section 5 concludes.

2 The model

In this Section, we introduce the ATS process, as a natural extension of the LTS process, that, on the one hand, maintains the increments’ independence as in the corresponding Levy process, and, on the other hand, allows for time-inhomogeneous parameters. First, we prove a sufficient condition for the existence of ATS processes (Theorem 2.1) and the martingale property for the corresponding forward process (Proposition 2.2). Then, we introduce the power-law scaling ATS as a subcase of a generic ATS (Theorem 2.3): we show in the next Section that this model describes accurately the implied volatility surface. Finally, we prove a key model feature: the model allows to reproduce a generic volatility term structure (Proposition 2.4).

Lévy normal tempered stable processes (LTS) are commonly used in the financial industry for derivative pricing. According to this modeling approach, the forward with expiry $T$ is an exponential Lévy; i.e.

\[ F_t(T) := F_0(T) \exp(f_t), \]  
(1)
with \( f_t \) a LTS
\[
f_t = -\left( \frac{1}{2} + \eta \right) \sigma^2 S_t + \sigma W_{S_t} + \varphi t \quad \forall t \in [0, T],
\]
where \( \eta, \sigma \) are two real parameters (\( \eta \in \mathbb{R}, \sigma \in \mathbb{R}^+ \)), while \( \varphi \) is obtained by imposing the martingale condition on \( F_t(T) \). \( W_t \) is a Brownian motion and \( S_t \) is a Lévy tempered stable subordinator independent from the Brownian motion with variance per unit of time \( k \). Examples of LTS subordinators are the Inverse Gaussian process for NIG or the Gamma process for VG.

It is possible to write the characteristic function of \( f_t \) as
\[
\mathbb{E} \left[ e^{iu f_t} \right] = \mathcal{L}_t \left( iu \left( \frac{1}{2} + \eta \right) \sigma^2 + \frac{u^2 \sigma^2}{2}; k, \alpha \right) e^{iu\varphi t}, \tag{2}
\]
where \( \alpha \in [0, 1) \) is the LTS index of stability and \( \mathcal{L}_t \) is the Laplace transform of \( S_t \)
\[
\ln \mathcal{L}_t (u; k, \alpha) := \begin{cases} 
\frac{t}{k} \ln \left( 1 + u k \right) & \text{if } \alpha = 0 \\
\frac{t}{k} \ln \left( 1 + u k \right) - \frac{1}{\alpha} \left( 1 - \left( 1 + \frac{u k}{1 - \alpha} \right)^{\alpha} \right) & \text{if } 0 < \alpha < 1
\end{cases} . \tag{3}
\]

This theory is well known and can be found in many excellent textbooks (see, e.g. Cont and Tankov 2003, Schoutens 2003).

As already discussed in the Introduction, LTS processes do not properly describe short and long maturities at the same time, while they allow an excellent calibration for a fixed maturity. For this reason, we would like to select a process that allows independent but non-stationary increments: i.e. an additive process. The simplest way to obtain this modeling feature is to consider an additive process with a characteristic function of the same form of (2) but with time-dependent parameters
\[
\mathbb{E} \left[ e^{iu f_t} \right] = \mathcal{L}_t \left( iu \left( \frac{1}{2} + \eta_t \right) \sigma_t^2 + \frac{u^2 \sigma_t^2}{2}; k_t, \alpha \right) e^{iu\varphi_t t}, \tag{4}
\]
where \( \sigma_t, k_t \) are continuous on \([0, \infty)\) and \( \eta_t, \varphi_t \) are continuous on \((0, \infty)\) with \( \sigma_t > 0, k_t \geq 0 \) and \( \varphi_t t \) goes to zero as \( t \) goes to zero. \( \alpha \in [0, 1) \) as in the LTS case.

In Theorem 2.1 we prove that this process exists if some conditions on \( \sigma_t, \eta_t \) and \( k_t \) are satisfied.

An additive process is a cádlág stochastic process on \( \mathbb{R} \times \{X_t\}_{t \geq 0} \), with \( X_0 = 0 \) a.s. and characterized by independent increments and stochastic continuity (see, e.g. Cont and Tankov 2003, Def.14.1 p.455). It can be proven that the distribution of an additive process at time \( t \) is infinitely divisible. \( (A_t, \nu_t, \gamma_t) \) is the generating triplet that characterizes the additive process \( \{X_t\}_{t \geq 0} \). \( A_t, \nu_t \) and \( \gamma_t \) are called respectively the diffusion term, the Lévy measure and the drift term (see Sato 1999, pp.38-39)\(^3\).

Sato (1999, Th.9.8, p.52) proves a powerful link between a system of infinitely divisible probability distributions and the existence of an additive process. In particular, Sato requires two main classes of conditions on the generating triplet: i) some conditions of monotonicity, necessary to avoid meaningless negative diffusion term or negative Lévy measure for the process increments and ii) some continuity conditions, in order to obtain the stochastic continuity.

We use Sato (1999, Th.9.8, p.52) to prove the main theoretical results in this paper: there exists a family of additive processes with characteristic function (4).

\(^3\)A parametrization scheme of the drift in terms of \( \eta \) can be suitable for some applications: \( \eta \) controls the volatility skew. In particular, it can be proven that for \( \eta = 0 \) the smile is symmetric, i.e. the implied volatility skew is zero (see, e.g. Baviera 2007, Prop. p.21).

\(^4\)In this paper, the notation follows closely the one in Sato (1999).
Theorem 2.1. Sufficient conditions for existence of ATS

There exists an additive process \( \{ f_t \}_{t \geq 0} \) with the characteristic function (4) if the following two conditions hold.

1. \( g_1(t), g_2(t), \) and \( g_3(t) \) are non-decreasing, where
   \[
   g_1(t) := (1/2 + \eta_t) - \sqrt{(1/2 + \eta_t)^2 + 2(1 - \alpha)/(\sigma_t^2 k_t)} \\
   g_2(t) := -(1/2 + \eta_t) - \sqrt{(1/2 + \eta_t)^2 + 2(1 - \alpha)/(\sigma_t^2 k_t)} \\
   g_3(t) := \frac{t^{1/\alpha} \sigma_t}{k_t^{(1-\alpha)/\alpha}} \sqrt{(1/2 + \eta_t)^2 + 2(1 - \alpha)/(\sigma_t^2 k_t)} ;
   \]

2. Both \( t \sigma_t^2 \eta_t \) and \( t \sigma_t^{2\alpha} \eta_t^\alpha / k_t^{1-\alpha} \) go to zero as \( t \) goes to zero.

Proof. See Appendix A

Let us emphasize that the conditions of Theorem 2.1 are quite general. In the market, we observe only a limited number of maturities, and thus, there is a large set of functions of time that reproduce market data and satisfy the conditions of the theorem. Furthermore, we prove in Theorem 2.3 that the conditions of Theorem 2.1 are satisfied by a simple sub-case of ATS with power-law scaling \( \eta_t \) and \( k_t \) and constant \( \sigma_t \). Finally, we also prove in Proposition 2.4 that ATS models allow a generic volatility term structure \( \sigma_t \).

In a similar way to the LTS case, it is possible to consider a forward price \( F_t(T) \) as the exponential of the ATS process \( \{ f_t \}_{t \geq 0} \) with the characteristic function (4). The deterministic function of time \( \phi_t \) can be chosen s.t. the process \( F_t(T) \) satisfies the martingale property, as shown in the next proposition.

Proposition 2.2. Martingale property

The forward \( \{ F_t(T) \}_{t \geq 0} \), modeled via an exponential additive process characterized by an ATS process \( \{ f_t \}_{t \geq 0} \) is a martingale if and only if

\[
\phi_t = -\ln L_t (\sigma_t^2 \eta_t; k_t, \alpha) ,
\]

where \( L_t \) is the Laplace transform in (3).

Proof. See Appendix A

We introduce a sub-case of ATS, determined by self-similar functions of time. In Subsection 3.3 we show that this family of processes describes accurately market implied volatility surfaces. Power-law scaling functions of time allow us to rewrite Theorem 2.1 conditions as simple inequalities on the scaling parameters.

Theorem 2.3. Power-law scaling ATS

There exists an ATS with

\[
k_t = \bar{k} t^{\beta} , \quad \eta_t = \bar{\eta} t^{\delta} , \quad \sigma_t = \bar{\sigma} ,
\]

where \( \alpha \in [0, 1) \), \( \bar{\sigma}, \bar{k}, \bar{\eta} \in \mathbb{R}^+ \), and \( \beta, \delta \in \mathbb{R} \) that satisfy the following conditions:

1. \( 0 \leq \beta \leq \frac{1}{1 - \alpha/2} \);
\[ 2. \quad - \min \left( \beta, \frac{1 - \beta (1 - \alpha)}{\alpha} \right) < \delta \leq 0; \]

where the second condition reduces to \(-\beta < \delta \leq 0\) for \(\alpha = 0\).

\textbf{Proof.} See Appendix A

It is interesting to observe that the LTS case falls in the subcase described by this theorem. This corresponds to the case with both \(k_t\) and \(\eta_t\) time independent; that is, \(\beta\) and \(\delta\) equal to zero.

The following result allows us to obtain a new additive process from a known one with a deterministic time change.

\textbf{Proposition 2.4. Deterministic time change of additive process}

Given an additive process \(\{X_t\}_{t \geq 0}\) and a real continuous increasing function of time \(r_t\) s.t. \(r_0 = 0\), then \(\{X_{r_t}\}_{t \geq 0}\) is an additive process.

\textbf{Proof.} See Appendix A

Thanks to \textbf{Proposition 2.4}, it is possible to extend the ATS power-law scaling sub-case to a case with time-dependent \(\sigma_t\). Indeed, if \(\sigma_t^2\) is non decreasing, we can use it to time-change a power-law scaling ATS without losing the property of independent increments: being able to reproduce the volatility term structure is an important feature from a practitioner perspective.

In the next Section, we show that the ATS model introduced in this Section describes accurately volatility surfaces observed in the equity derivative market.

\section{Model calibration and power law scaling}

In this Section, we show that the ATS processes achieve excellent calibration results on the S&P 500 and EURO STOXX 50 volatility surfaces; moreover, we show that power-law scaling parameters are observed in market data.

First, after having described the dataset, we illustrate the model calibration procedure and compare the performance of ATS processes with some benchmarks (LTS processes and Sato processes in \textit{Carr et al. (2007)}). Then, we outline some statistical evidence that the market-implied volatility surface is compatible with a power-law scaling of ATS parameters.

\subsection{Dataset}

We analyze all quoted S&P 500 and EURO STOXX 50 option prices observed at 11:00 am New York Time on the 30th of May 2013. The dataset is composed of real market quotes (no smoothing or interpolation). Let us recall that the options on these two indices are the most liquid options in the equity market at the world level. For both indices, options expire on the third Friday of March, June, September, and December in the front year and June and December in the next year. In the EURO STOXX 50 case also December contracts for the following three years are available. The dataset includes the risk-free interest rate curves bootstrapped from (USD and EUR) OIS curves. Financial data are provided by Bloomberg. The dataset contains all bid/ask prices for both call and put. The strikes are in a regular grid for each available maturity. We exclude options that do not satisfy two simple liquidity thresholds. We discard options whose price is less than 10\% the minimum difference in the grid of market strikes (the so-called penny options) and options with bid-ask over bid bigger than 60\%. The last condition filters out strikes for which either a bid or an ask price is missing.
We use the synthetic forward, as forward price, because this allows a perfect synchronization with option prices and, for several maturities, it identifies the most liquid forward in the market. The synthetic forward price is obtained for every maturity, from very liquid options as the (algebraic) mean of the lowest forward ask and the highest forward bid.

We implement a simple iterated algorithm that identifies the synthetic forward price at a given maturity $T$: let us briefly describe it. We start selecting the call and put options with strike price nearest to the spot price for the shortest maturity or to the previous maturity forward price for the next maturities. We compute forward bid, ask, and mid prices for that strike price. We consider the options with the nearest superior strike. If the forward mid-price computed previously falls within the new bid-ask interval, then the updated forward bid is the highest value among the two forward bids, while the updated ask is the lowest value among the two ask prices. The updated forward mid-price corresponds to the mean of the updated bid and ask. Then, we consider the nearest inferior strike and iterate the same procedure comparing the updated forward mid-price with the new bid/ask prices relative to this new strike. This procedure is iterated with the next superior strike and then with the next inferior strike, and so on for all the options present at that maturity $T$.

In Figure 1, we show, for a given underlying and a given maturity, the values considered in the forward price construction and the value selected by the procedure.

Figure 1: EURO STOXX 50 synthetic forward prices on the 30th of May 2013 at 11 am NT for the JUN14 maturity: bid, ask, and mid forward prices. Only prices not discarded by the two liquidity criteria are shown in the figure. According to the algorithm described in the text also the price related to the strike 1700 is discarded from the forward price computation. We show in red the corresponding forward bid-ask prices and with a diamond, the selected forward price $F_0(T)$ relative to this expiry.

In Figure 2 we plot the bid, ask, and mid synthetic forward prices for the different maturities available for the S&P 500 and the EURO STOXX 50.
3.2 Calibration

We calibrate the ATS following the procedure discussed by Cont and Tankov (2003, Ch.14, pp.464-465). We cut the volatility surface into slices, each one containing options with the same maturity, and calibrate each slice separately. Hereinafter, we focus on \( \alpha = 1/2 \) (NIG) and \( \alpha = 0 \) (VG), which are the two (ATS and Sato) generalizations of the two most frequently used LTS processes. For every fixed maturity \( T \), it is possible to define a new Lévy normal tempered stable process such that, at time \( T \), its marginal distribution is equal to the marginal distribution of an ATS. A different Lévy NIG and VG is calibrated for every different maturity and the three time-dependent parameters \( k_T, \eta_T, \sigma_T \) are obtained. The calibration is performed imposing the conditions of monotonicity of Theorem 2.1.

Beneath the ATS processes, we consider the calibration of the standard Lévy processes and of the (four parameters) Sato processes proposed by Carr et al. (2007). We remind that the latter are additive and self-similar processes (see, e.g. Sato 1991). Call option prices, with strike \( K \) and maturity \( T \), are computed using the Lewis (2001) formula

\[
C(K, T) = B_T F_0(T) \left\{ 1 - e^{x^2/2} \int_{-\infty}^{\infty} \frac{dz}{2\pi} e^{izx} \phi_C\left(-z - \frac{i}{2}\right) \frac{1}{z^2 + \frac{1}{4}} \right\},
\]

where \( \phi_C(u) \) is the characteristic function of \( f_T \), \( x := \ln K/F_0(T) \) is the moneyness, and \( B_T \) is the discount factor between value date and \( T \).

The calibration is performed by minimizing the Euclidean distance between model and market prices. The simplex method is used to calibrate every maturity of the ATS process. For Lévy processes and Sato processes, because standard routines for global minimum algorithms are not satisfactory, we consider a differential evolution algorithm together with a multi-start simplex method.

5We underline that, in both cases (LTS and Sato), model parameters are obtained through a global calibration of the whole volatility surface.
The calibration performance is reported in Table 1 in terms of Mean Squared Error (MSE) and Mean Absolute Percentage Error (MAPE). It is possible to observe that Sato processes slightly improve Lévy performance, as reported in the literature (see, e.g. [Carr et al. 2007]), while the ATS processes improvement is, on average, above two orders of magnitude. Although we present the results for VG and NIG, similar results can be obtained for all ATS processes with \( \alpha \in [0, 1) \). The worst results are observed in the VG case.

| Index       | Model | MSE | MAPE |
|-------------|-------|-----|------|
| S&P 500     | NIG   | 4.56| 3.13%| 0.23%|
|             | VG    | 8.49| 4.31%| 0.79%|
| Euro Stoxx 50 | NIG | 22.15 | 1.75%| 0.09%|
|             | VG    | 55.81 | 2.85%| 0.21%|

Table 1: Calibration performance for the S&P 500 and EURO STOXX 50 in terms of MSE and MAPE. In the NIG (\( \alpha = 1/2 \)) and VG (\( \alpha = 0 \)) cases, we consider the standard Lévy process, the Sato process, and the corresponding ATS process. Sato processes perform better than Lévy processes but ATS improvement is far more significant: two orders of magnitude for MSE and one order of magnitude for MAPE.

Figure 3 shows the differences of MSE w.r.t. the different times to maturity for S&P 500 volatility surface calibrated with a NIG process. Sato and Lévy LTS have a MSE of the same order of magnitude, while the improvement of ATS is of two orders of magnitude and particularly significant at short-time. The short-time improvement in implied volatility calibration is particularly evident, as shown in Figure 4.

![MSE comparison](image)

In Figure 4, we plot the market implied volatility and the volatility replicated via ATS, LTS, and Sato processes at the 22 days (on the left) and 9 months and 21 days (on the right) maturities. We observe that the ATS implied volatility is the closest to the market implied volatility in any case and it significantly improves both LTS and Sato processes, particularly for small maturities. Similar results hold for all other ATS.

\(^6\)Calibrated model parameters are available upon request.
Figure 4: Implied volatility smile for S&P 500 for a given time to maturity: 22 days (on the left) and 9 months and 21 days (on the right). The NIG ATS process, Sato process, and LTS process implied volatilities are plotted together with the market-implied volatility. ATS reproduces the smile significantly better than the alternatives, the improvement is particularly evident for small maturities.

In Figure 5, we plot the market and the ATS implied volatility skew for EURO STOXX 50 w.r.t. the times to maturity. We observe that the calibrated ATS replicates accurately the market implied volatility skew.

Figure 5: The market and the NIG ATS implied volatility skew for EURO STOXX 50 w.r.t. the times to maturity. ATS replicates the market implied volatility skew behavior.

The calibration results of ATS are startling. In particular, we have a model that reproduces “exactly” the volatility term structure observed in the market.

It is useful to stop and comment. The ATS model allows us to calibrate slice-by-slice the surface; we have only to impose the monotonicity conditions of Theorem 2.1. With the slice-by-slice approach, we use 3 parameters for every expiry (e.g. 18 parameters in the S&P case). We have observed that ATS outperforms Levy and Sato processes, the benchmark pure-jump processes in
the literature. It could seem unfair to compare the calibration results of ATS with a Levy (3 parameters) and a Sato (4 parameters).

In the next Subsection, we show that this family of additive processes combines parsimony with the desired property of a perfect fit of the volatility term structure: we show that, once the term structure has been taken into account, only 2 free parameters allow a detailed calibration of the whole volatility surface.

3.3 Scaling properties

In this Subsection, we show that power-law scaling parameters are observed in market data. This stylized fact is extremely relevant: we observe statistical evidence that the market-implied volatility surface is compatible with a power-law scaling ATS of Theorem 2.3.

We introduce a new ATS process, w.r.t. the time \( \theta := T\sigma_T^2 \).

We define \( \hat{k}_\theta := k_T\sigma_T^2 \) and \( \hat{\eta}_\theta := \eta_T \). We call \( \hat{f}_\theta \) the ATS with parameters \( k_\theta, \eta_\theta \) and \( \sigma_\theta := 1 \). Notice that for every maturity \( \hat{f}_\theta \) has the same characteristic function of the calibrated ATS \( f_T \).

We analyze the re-scaled parameters, in both S&P 500 and EURO STOXX 50 cases. We observe a self-similar behavior of \( \hat{k}_\theta \) and \( \hat{\eta}_\theta \); that is,

\[
\begin{align*}
\hat{k}_\theta &= \bar{k}_\theta \theta^\beta \\
\hat{\eta}_\theta &= \bar{\eta}_\theta \theta^\delta,
\end{align*}
\]

where \( \bar{k}, \bar{\eta} \) are positive constants and \( \beta, \delta \) are real constant parameters. To investigate this behavior and to infer the value of the scaling parameters we consider equations (7) in the log-log scale.

In Figures 6 and 7 we plot the weighted regression lines and the observed time-dependent parameters \( \ln \hat{k}_\theta \) and \( \ln \hat{\eta}_\theta \) with their confidence intervals for S&P 500 and EURO STOXX 50. The confidence intervals are two times the standard deviations of \( \ln \hat{k}_\theta \), of \( \ln \hat{\eta}_\theta \) and of \( \ln \theta \). In Appendix B, we discuss the estimation of the standard deviations via a confidence interval propagation technique and the selection of the weights.
Figure 6: Weighted regression line and the observed time-dependent parameters $\ln \hat{k}_\theta$ and $\ln \hat{\eta}_\theta$ w.r.t. $\ln \theta$ for the NIG calibrated model for S&P 500. We plot a confidence interval equal to two times the corresponding standard deviation. Notice that confidence intervals on $\ln \hat{k}_\theta$ and $\ln \hat{\eta}_\theta$ are one order of magnitude wider than confidence intervals on $\ln \theta$. The scalings of $\hat{k}_\theta$ and $\hat{\eta}_\theta$ in (7) are statistically consistent with $\beta = 1$ and $\delta = -1/2$. The values of $\theta$ correspond to times to maturity that goes from 22 days to two years.

Figure 7: Weighted regression line and the observed time-dependent parameters $\ln \hat{k}_\theta$ and $\ln \hat{\eta}_\theta$ w.r.t. $\ln \theta$ for the VG model calibrated on EURO STOXX 50. We plot a confidence interval equal to two times the corresponding standard deviation. Notice that confidence intervals on $\ln \hat{k}_\theta$ and $\ln \hat{\eta}_\theta$ are one order of magnitude wider than confidence intervals on $\ln \theta$. The scalings of $\hat{k}_\theta$ and $\hat{\eta}_\theta$ in (7) are statistically consistent with $\beta = 1$ and $\delta = -1/2$. The values of $\theta$ correspond to times to maturity that goes from 22 days to five years.

We have observed what seems to be a stylized fact of this model class: both $\hat{\eta}_\theta$ and $\hat{k}_\theta$ scale with power-law. The same scaling laws are observed both for short time-horizon (days) and long time-horizon (few years) options. The fitted regression lines provide us with an estimation of $\beta$ and $\delta$. Moreover, let us emphasize that the scaling parameters appear qualitatively compatible to
\( \beta = 1 \) and \( \delta = -\frac{1}{2} \) in all observed cases.

We can test whether there is statistical evidence that our hypotheses are consistent with market data. The estimated scaling parameters together with the p-value of statistical tests are reported in Table 2.

| Surface         | Model | Parameter | Parameter’s Value | p-value |
|-----------------|-------|-----------|-------------------|---------|
| S&P 500         | NIG   | \( \beta \) | 1.10              | 0.228   |
| S&P 500         | NIG   | \( \delta \) | -0.47             | 0.705   |
| S&P 500         | VG    | \( \beta \) | 1.01              | 0.758   |
| S&P 500         | VG    | \( \delta \) | -0.43             | 0.057   |
| EURO STOXX 50  | NIG   | \( \beta \) | 1.02              | 0.816   |
| EURO STOXX 50  | NIG   | \( \delta \) | -0.44             | 0.472   |
| EURO STOXX 50  | VG    | \( \beta \) | 0.99              | 0.690   |
| EURO STOXX 50  | VG    | \( \delta \) | -0.45             | 0.195   |

Table 2: Scaling parameters calibrated from S&P 500 and EURO STOXX 50 volatility surfaces for NIG \((\alpha = 1/2)\) and VG \((\alpha = 0)\). Parameter estimates are provided together with the p-values of the statistical tests that verify whether it is possible to accept the null hypotheses \( \beta = 1 \) and \( \delta = -\frac{1}{2} \).

In all cases, we accept the null hypotheses \((\beta = 1 \text{ and } \delta = -\frac{1}{2})\) with a 5% confidence level. Notice that all p-values, except the S&P 500 VG \( \delta \), are above 19%.

In Table 3 we report an estimation of the parameter \( \bar{k} \) and \( \bar{\eta} \).

| Surface         | Model | Parameter | Parameter’s Value | p-value |
|-----------------|-------|-----------|-------------------|---------|
| S&P 500         | NIG   | \( \bar{k} \) | 1.50              | 0.022   |
| S&P 500         | NIG   | \( \bar{\eta} \) | 0.98              | 0.015   |
| S&P 500         | VG    | \( \bar{k} \) | 1.01              | 0.001   |
| S&P 500         | VG    | \( \bar{\eta} \) | 0.91              | 0.000   |
| EURO STOXX 50  | NIG   | \( \bar{k} \) | 0.68              | 0.023   |
| EURO STOXX 50  | NIG   | \( \bar{\eta} \) | 1.21              | 0.021   |
| EURO STOXX 50  | VG    | \( \bar{k} \) | 0.98              | 0.000   |
| EURO STOXX 50  | VG    | \( \bar{\eta} \) | 0.72              | 0.000   |

Table 3: \( \bar{k} \) and \( \bar{\eta} \) calibrated from S&P 500 and EURO STOXX 50 volatility surfaces. Parameter estimates are provided together with the p-values of the statistical tests that verify whether it is possible to accept the null hypothesis \( \bar{k} = 0 \) and \( \bar{\eta} = 0 \).

We have statistical evidence that in all cases \( \bar{k} \) and \( \bar{\eta} \) are positive (we reject the null hypotheses of \( \bar{k} = 0 \) and \( \bar{\eta} = 0 \) with a 5% confidence level). From these results and from Figure 5 it is possible to infer a connection between a positive \( \bar{\eta} \) and the observed negative skew.

It is interesting to observe that these estimated parameters satisfy the inequalities of Theorem 2.3 for the existence of a power-law scaling ATS \( \hat{f}_\theta \). Moreover, the re-scaled process is additive w.r.t. the “real” time \( T \). This fact is a consequence of the properties of the volatility term structure \( \sigma_T \) (it is always observed on real data that \( \sigma_T^2 T \) is non-decreasing) and of Proposition 2.4. This proposition states that if \( \left\{ \hat{f}_\theta \right\}_{\theta \geq 0} \) is an additive process then \( \left\{ \hat{f}_T \sigma_T^2 \right\}_{T \geq 0} \) is an additive process w.r.t. \( T \).

\(^7\)We have also considered a global calibration of the implied volatility surfaces considering the power-law scaling parameters in \(^7\) with \( \beta = 1 \) and \( \delta = -0.5 \). The results are of the same order of magnitude of Table 1.
4 Model selection and robustness tests

In this Section, we show two additional results for the proposed process class. First, we compare the ATS with two other additive processes already present in the financial literature and propose some statistical tests able to select the most adequate modeling description of the implied volatility surface. Then, we show that the results, described in detail in the previous Section, appear robust over time.

4.1 Model selection via statistical tests

In this Subsection, we compare ATS with two classes of additive processes already present in the financial literature, the Sato processes (see, e.g. Carr et al. 2007) and the additive processes constructed via additive subordination (see, e.g. Li et al. 2016). The comparison is among processes that have the marginal distribution of normal tempered stable type: i.e. with the Sato processes NIGSSD and VGSSD and with the sub-class of ATS constructed through additive subordination.

An ATS process can be obtained as a Brownian motion subordinated with an additive subordinator, as in Li et al. (2016), if and only if \( \eta^T \) is constant. We discuss two features: one related to the \( \eta^T \) parameter and another to the skewness and to the excess kurtosis of the calibrated exponential forward.

A first test is built to verify the adequacy of Sato processes. Given the index of stability for the model (e.g. chosen \( \alpha \) in the Normal Tempered Stable model), it is possible to compute skewness and kurtosis (see, e.g. Cont and Tankov 2003, p.129). For example the ATS NIG skewness is

\[
\frac{\mathbb{E} \left[(f_T - \mathbb{E}[f_T])^3\right]}{(\text{Var}(f_T))^{\frac{3}{2}}} = -3\eta_T^3 \left(\eta_T + \frac{1}{2}\right)^2 \frac{k_T^2 T}{\left(\sigma_T^2 T + k_T T \sigma_T^4 \left(\eta_T + \frac{1}{2}\right)^2\right)^{\frac{3}{2}}}.
\]

A Sato process has skewness and kurtosis constant over time, as it can be deduced by definition (see, e.g. Carr et al. 2007).

We analyze the term structure of these higher-order moments observed in our dataset adopting the same procedure of Konikov and Madan (2002). For both indices, we observe a linear behavior of skewness and kurtosis w.r.t. the squared root of the maturity as shown in Figure 8 in the NIG case. In the Figure, we have plotted also the confidence interval chosen equal to two times the standard deviation, respectively, of the skewness and the kurtosis (cf. Appendix B for the methodology adopted to obtain these standard deviations).

The statistical test is simple. We perform a linear regression statistical analysis of the higher moments behavior w.r.t. the square root of the time to maturity \( \sqrt{T} \): we reject the null hypothesis of no slope in all of the cases that we analyze (both indices and both tempered stable models; that is, NIG and VG) with p-values of the order of \( 10^{-16} \). Similar results hold in all ATS cases.

\(^8\)Proof available upon request.
The other statistical test aims to verify the adequacy of additive processes obtained through additive subordination \cite{Li2016} in volatility surface calibration. As already mentioned the ATS process, when $\hat{\eta}_0$ is equal to a constant $\bar{\eta}$, falls within this class. In Figure 6 and 7 we have already shown the time scaling $\hat{\eta}_0$. We can statistically test the null hypothesis of constant $\hat{\eta}_0$. For both volatility surfaces and for both tested tempered stable models (NIG and VG) we reject the null hypothesis of a constant $\hat{\eta}_0$ with p-values below $10^{-7}$. As already observed, ATS processes are characterized by a power-law scaling in $\hat{\eta}_0$.

4.2 Robustness tests

In this Subsection, we perform a robustness analysis of the results in Section 3. We repeat the analysis on four other days, both on the S&P 500 and EURO STOXX 50 volatility surfaces. We show that the excellent calibration features of the ATS and the power-law scaling properties, observed on the 30th of May 2013, arise also in these other dates.

In these robustness tests, we use bid and ask close prices for the S&P 500 and EURO STOXX 50 options on the 29th of November 2012 (6 months before the date of the analysis of Section 3, the 30th of May 2013), the 27th of February 2013 (3 months before), the 30th of August 2013 (3 months after), and the 29th November 2013 (6 months after). The dataset includes the bootstrapped risk-free rate curve. The data is provided by Reuters Datastream (option data) and Reuters Eikons (rate data). Let us observe that close prices are, in general, less accurate than open market prices (the ones used for the analysis in Section 3).

In Table 4 we report calibration performances for the S&P 500 and EURO STOXX 50 in terms of MSE and MAPE on the four dates considered. In the NIG and VG cases, we consider the standard Lévy process, the Sato process, and the corresponding ATS process. In all considered cases, Sato

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Footnote: These are the penultimate business days of November 2012, February 2013, August 2013, and November 2013.
processes perform better than Lévy processes but ATS improvement is far more significant: on average, two orders of magnitude for MSE and one order of magnitude for MAPE. These results appear coherent with the ones reported in Table 1.

![Table 4](https://example.com/table4.png)

Table 4: Calibration performance for the S&P 500 and EURO STOXX 50 in terms of MSE and MAPE on the 29th of November 2012 (6 months before the date of the analysis), the 27th of February 2013 (3 months before), the 30th of August 2013 (3 months after), and the 29th November 2013 (6 months after). In the NIG and VG cases, we consider the standard Lévy process, the Sato process, and the corresponding ATS process, as in Table 1. In all considered cases, Sato processes perform better than Lévy processes but ATS improvement is far more significant: two orders of magnitude for MSE and one order of magnitude for MAPE.

In Figure 9 we plot the MSE w.r.t. the different times to maturity (in years) for S&P 500 volatility surface calibrated with a NIG process on the four considered dates. We observe that Sato (circles) and Lévy (triangles) have a MSE of the same order of magnitude, while the improvement of ATS (squares) is, on average, of two orders of magnitude and particularly significant at short-time.
Figure 9: MSE w.r.t. the different times to maturity (in years) for S&P 500 volatility surface calibrated with a NIG process on the 29th of November 2012 (6 months before), the 27th of February 2013 (3 months before), the 30th of August 2013 (3 months after), and the 29th of November 2013 (6 months after). Sato (circles) and Lévy (triangles) have a MSE of the same order of magnitude, while the improvement of ATS (squares) is, on average, of two orders of magnitude and particularly significant at short-time.

In Figures 10 and 11 we plot the implied volatility smile for S&P 500 on the 29th of November 2012 (time to maturity of 22 days on the left and of 9 months and 22 days on the right) and on the 29th of November 2013 (time to maturity of 21 days on the left and of 9 months and 21 days on the right). The NIG ATS process, Sato process, and LTS process implied volatility are plotted together with the market-implied volatility. As in the case of the 30th of May 2013 (cf. Figure 4) the ATS reproduces the smiles significantly better than the alternatives, the improvement is particularly evident for small maturities.
Figure 10: Implied volatility smile for S&P 500 at the 29th of November 2012 (6 months before) for a given time to maturity: 22 days (on the left) and 9 months and 22 days (on the right). The NIG ATS process, Sato process, and LTS process implied volatility are plotted together with the market-implied volatility. ATS reproduces the smile significantly better than the alternatives, the improvement is particularly evident for small maturities.

Figure 11: Implied volatility smile for S&P 500 at the 29th of November 2013 (6 months after) for a given time to maturity: 21 days (on the left) and 9 months and 21 days (on the right). The NIG ATS process, Sato process, and LTS process implied volatility are plotted together with the market-implied volatility. ATS reproduces the smile significantly better than the alternatives, the improvement is particularly evident for small maturities.

In Figure 12 we plot the market and the ATS NIG implied volatility skew for EURO STOXX 50 w.r.t. the times to maturity on the 27th of February and on the 30th of August 2013. In both cases, the calibrated ATS replicates accurately the market implied volatility skew, as already observed in Section 3 for the 30th of May 2013. Similar results hold for the other two dates and in the S&P 500 case.
Figure 12: The market and the ATS NIG implied volatility skew for EURO STOXX 50 w.r.t. the times to maturity on the 27th of February and on the 30th of August 2013. Again, ATS replicates the market implied volatility skew.

In Figures 13 and 14, we plot the weighted regression lines and the observed time-dependent parameters $\ln \hat{k}_\theta$ and $\ln \hat{\eta}_\theta$ with their confidence intervals for S&P 500 and EURO STOXX 50 on the 29th of November 2012 (on the top) and on the 29th of November 2013 (on the bottom). The confidence intervals are two times the standard deviations of $\ln \hat{k}_\theta$, of $\ln \hat{\eta}_\theta$ and of $\ln \theta$. In both days, the observed scalings of $\hat{k}_\theta$ and $\hat{\eta}_\theta$ are equivalent to the ones observed in Figures 6 and 7.

10Results for the 27th of February 2013 and the 30th of August 2013 are available upon request.
Figure 13: Weighted regression line and the observed time-dependent parameters $\ln \hat{k}_\theta$ and $\ln \hat{\eta}_\theta$ w.r.t. $\ln \theta$ for the NIG calibrated model for S&P 500 on the 29th of November 2012 (on the top) and on the 29th of November 2013 (on the bottom). We plot a confidence interval equal to two times the corresponding standard deviation. Notice that, also in this case, confidence intervals on $\ln \hat{k}_\theta$ and $\ln \hat{\eta}_\theta$ are one order of magnitude wider than confidence intervals on $\ln \theta$. The observed scalings of $\hat{k}_\theta$ and $\hat{\eta}_\theta$ are equivalents to the ones observed in Figures 6 and 7. The values of $\theta$ correspond to times to maturity that goes from tree weeks to two years and a half (all available maturities on Reuters Datastream dataset).
Figure 14: Weighted regression line and the observed time-dependent parameters $\ln \hat{k}_\theta$ and $\ln \hat{\eta}_\theta$ w.r.t. $\ln \theta$ for the VG calibrated model for EURO STOXX 50 on the 29th of November 2012 (on the top) and on the 30th of November 2013 (on the bottom). We plot a confidence interval equal to two times the corresponding standard deviation. Notice that, also in this case, confidence intervals on $\ln \hat{k}_\theta$ and $\ln \hat{\eta}_\theta$ are one order of magnitude wider than confidence intervals on $\ln \theta$. The observed scalings of $\hat{k}_\theta$ and $\hat{\eta}_\theta$ are equivalents to the ones observed in Figures 6 and 7. The values of $\theta$ correspond to times to maturity that goes from three weeks to five years (all available maturities on Reuters Datastream dataset).

The results presented in Table 4 and in Figures 9-14 are equivalent to the one of Section 3. This analysis confirms the robustness, over a one-year time interval, of the excellent calibration performances and the power scaling behavior of the ATS.

5 Conclusions

In this paper, we introduce a new broad family of stochastic processes that we call additive normal tempered stable processes (ATS). An interesting subcase of ATS presents a power-law scaling of the time-dependent parameters.

We have considered all quoted options on S&P 500 and EURO STOXX 50 at 11:00 am New York Time on the 30th of May 2013. The dataset considers options with a time to maturity starting from three weeks and up to several years. We calibrate the ATS processes on the options of both indices, showing that ATS processes present better calibration features than LTS and Sato processes. The observed improvement of ATS is even of two orders of magnitude in terms of MSE, as reported in Table 1. ATS replicates accurately market implied volatility term structure and skew as observed in Figures 4 and 5.

The quality of ATS calibration results looks quite incredible. In Subsection 3.3 we have shown that once the volatility term structure has been taken into account, the whole implied volatility surface is calibrated accurately with only two free parameters.
We also construct a re-scaled ATS process via a time-change based on the implied volatility term structure. We show that the re-scaled process calibrated parameters exhibit a power-law behavior. The statistical relevance of the scaling properties is discussed in detail.

We have compared some model characteristics with the two alternative additive processes present in the financial literature. These two classes fail to reproduce some stylized facts observed in market data, which are adequately described by ATS processes. Finally, we have verified the robustness, over a one-year time interval, of the excellent calibration performances and the power scaling behavior of the ATS.

As for future research, two main promising directions appear evident. First, it can be interesting to extend ATS processes to the commodity asset class, in general, and to the oil (Shiraya and Takahashi 2011, Kyriakou et al. 2016) and freight markets (Prokopczuk 2011, Nomikos et al. 2013), in particular; this model extension should allow for mean-reversion and seasonality patterns in prices, which are typically found in empirical studies (see, e.g., Benth et al. 2014, and references therein). Second, it would be worthy to develop a fast and reliable simulation algorithm for ATS processes (see, e.g., Azzone and Baviera 2021) and to study pricing techniques for exotic derivatives (e.g., generalizing the techniques for path-dependent exotics products, as Asian options, in Fusai and Meucci 2008, Černý and Kyriakou 2011, Fusai and Kyriakou 2016, through the characteristic function of the ATS increments).

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### Notation

| Symbol | Description |
|--------|-------------|
| $A_t$  | diffusion term of the additive process $\{X_t\}_{t \geq 0}$ |
| $B_T$  | discount factor between value date and $T$ |
| $\mathcal{B}(\mathbb{R})$ | Borel sigma algebra on $\mathbb{R}$ |
| $C(T, K)$ | call option price at value date with maturity $T$ and strike $K$ |
| $\{f_t\}_{t \geq 0}$ | ATS process that models the forward exponent |
| $\{\hat{f}_\theta\}_{\theta \geq 0}$ | re-scaled ATS process w.r.t. the time $\theta = \sigma_T^2 T$ |
| $F_t(T)$ | price at time $t$ of a Forward contract with maturity $T$ |
| $k$ | variance of jumps of LTS |
| $k_t$ | variance of jumps of ATS |
| $\hat{k}_\theta$ | re-scaled variance of jumps of ATS |
| $\bar{k}$ | constant part of the re-scaled variance of jumps of ATS $\hat{k}_\theta$ |
| $L_t$ | Laplace transform of the subordinator $S_t$ in (3) |
| $\{S_t\}_{t \geq 0}$ | Lévy subordinator |
| $T$ | option time to maturity |
| $W_t$ | Brownian motion |
| $x$ | option moneyness |
| $\alpha$ | Index of stability: tempered stable parameter of ATS, $\alpha \in [0, 1]$ |
| $\beta$ | scaling parameter of $\hat{k}_\theta$ |
| $\gamma_t$ | drift term of additive process $\{X_t\}_{t \geq 0}$ |
| $\Gamma(*)$ | Gamma function evaluated in $*$ |
| $\delta$ | scaling parameter of $\hat{\eta}_\theta$ |
| $\varphi$ | deterministic drift term of LTS |
| $\varphi_t$ | deterministic drift term of ATS |
| $\phi^c$ | characteristic function of the forward exponent |
| $\eta$ | skew parameter of LTS |
| $\eta_t$ | skew parameter of ATS |
| $\hat{\eta}_\theta$ | re-scaled skew parameter of ATS |
| $\bar{\eta}$ | constant part of the re-scaled ATS skew parameter $\hat{\eta}_\theta$ |
| $\nu_t$ | Lévy measure of the additive process $\{X_t\}_{t \geq 0}$ |
| $\sigma$ | diffusion parameter of LTS |
| $\sigma_t$ | diffusion parameter of ATS |
| $\hat{\sigma}_\theta$ | re-scaled diffusion parameter of ATS, equal to one |
| $\bar{\sigma}$ | constant diffusion parameter of ATS |
| $\theta$ | re-scaled maturity, defined as $\sigma_T^2 T$ |
Appendix A  Proofs

We start proving a technical Lemma that we use in the proof of Theorem 2.1.

Lemma A.1.
If \( \lim_{t \to 0} t \sigma_t^2 \eta_t = 0 \), then

\[
\lim_{t \to 0} \int_0^\infty ds \frac{t}{\Gamma(1-\alpha)} \left( \frac{1-\alpha}{k_t} \right)^{1-\alpha} \left( e^{-(1-\alpha) s/k_t} \right) \int_{|x|<1} dx \frac{x}{\sqrt{2\pi s \sigma_t}} e^{-\left( \frac{x + \eta t^2 (\eta_t + 1/2)}{\sigma_t} \right)^2} = 0 .
\]

Proof.

\[
\left| \int_{|x|<1} dx \frac{x}{\sqrt{2\pi s \sigma_t}} e^{-\left( \frac{x + \eta t^2 (\eta_t + 1/2)}{\sigma_t} \right)^2} \right| \leq \int_{|x|<1} dx \frac{x}{\sqrt{2\pi s \sigma_t}} e^{-\left( \frac{x + \eta t^2 (\eta_t + 1/2)}{\sigma_t} \right)^2} + \int_{1}^\infty dx \frac{x}{\sqrt{2\pi s \sigma_t}} \left( e^{-\left( \frac{x + \eta t^2 (\eta_t + 1/2)}{\sigma_t} \right)^2} - e^{-\left( \frac{-x + \eta t^2 (\eta_t + 1/2)}{\sigma_t} \right)^2} \right) = \sigma_t^2 s \left| \frac{1}{2} + \eta_t \right| .
\]

The inequality is due to the fact that both terms inside the right-hand side absolute value are positive if \((1/2 + \eta_t)\) is positive and are negative if \((1/2 + \eta_t)\) is negative. Now it is possible to write the following bound

\[
\left| \int_0^\infty ds \frac{t}{\Gamma(1-\alpha)} \left( \frac{1-\alpha}{k_t} \right)^{1-\alpha} \left( e^{-(1-\alpha) s/k_t} \right) \int_{|x|<1} dx \frac{x}{\sqrt{2\pi s \sigma_t}} e^{-\left( \frac{x + \eta t^2 (\eta_t + 1/2)}{\sigma_t} \right)^2} \right| \leq \sigma_t^2 \left| \frac{1}{2} + \eta_t \right| \int_0^\infty ds \frac{t}{\Gamma(1-\alpha)} \left( \frac{1-\alpha}{k_t} \right)^{1-\alpha} \left( e^{-(1-\alpha) s/k_t} \right) = t \sigma_t^2 \left| \frac{1}{2} + \eta_t \right| ,
\]

where the last equality is due to the definition of \( \Gamma(1-\alpha) \). We prove the thesis by the squeeze theorem.

Proof of Theorem 2.1

The idea of this proof is to show that there exists an additive process with the characteristic function in (4) using the result in Sato (1999, Th.9.8, p.52).

At any given time \( t > 0 \) the characteristic function in (4) is the characteristic function of a LTS (2), at time \( t \), with parameters \( k = k_t, \eta = \eta_t, \sigma = \sigma_t \) and \( \varphi = \varphi_t \). Hence, we have an expression for the generating triplet of (4) (see, e.g. Cont and Tankov 2003, eq. 4.24, p.130)

\[
\begin{align*}
A_t &= 0 \\
\gamma_t &= \int_0^\infty ds \frac{t}{\Gamma(1-\alpha)} \left( \frac{1-\alpha}{k_t} \right)^{1-\alpha} \left( e^{-(1-\alpha) s/k_t} \right) \int_{|x|<1} dx \frac{x}{\sqrt{2\pi s \sigma_t}} e^{-\left( \frac{x + \eta t^2 (\eta_t + 1/2)}{\sigma_t} \right)^2} + t \varphi_t \\
\nu_t(x) &= \frac{t C(\alpha, k_t, \sigma_t, \eta_t)}{|x|^{1+\alpha}} e^{-\left( \frac{\eta t + 1/2}{2} \right)} K_{\alpha+1/2} \left( \frac{x}{\sqrt{(1/2 + \eta_t)^2 + 2(1-\alpha)/(k_t \sigma_t^2)}} \right)
\end{align*}
\]
with
\[
C(\alpha, k_t, \sigma_t, \eta_t) := \frac{2}{\Gamma(1-\alpha)\sqrt{2\pi}} \left(\frac{1-\alpha}{k_t}\right)^{1-\alpha} \sigma_t^{2\alpha} \left((1/2 + \eta_t)^2 + 2(1-\alpha)/(k_t \sigma_t^2)\right)^{\alpha/2+1/4},
\]
and
\[
K_\nu(z) := \frac{e^{-z}}{\Gamma(\nu + \frac{1}{2})} \sqrt{\frac{\pi}{2z}} \int_0^\infty e^{-s} s^{\nu-1/2} \left(\frac{s}{2z} + 1\right)^{\nu-1/2} \, ds
\]
is the modified Bessel function of the second kind (see, e.g. [Abramowitz and Stegun 1948, Ch.9 p.376]). For \(t = 0\), as usual in additive processes, we set \(\gamma_0 = 0\), \(A_0 = 0\) and \(\nu_0 = 0\).

First, we verify that \(\nu_t(x)\) is a non decreasing function of \(t\). It is possible to identify two expressions in the jump measure \(\nu_t(x)\)
\[
e^{-x(1/2+\eta_t)-|x|\sqrt{(1/2+\eta_t)^2+2(1-\alpha)/(\sigma_t^2 k_t)}} t^{1/\alpha} \sigma_t^2 \left(s/|x| + \sqrt{(1/2 + \eta_t)^2 + 2(1-\alpha)/(\sigma_t^2 k_t)}\right) . \tag{8}
\]
\[
\frac{t^{1/\alpha} \sigma_t^2}{k_t(1-\alpha)^{1/\alpha}} \left(s/|x| + \sqrt{(1/2 + \eta_t)^2 + 2(1-\alpha)/(\sigma_t^2 k_t)}\right) . \tag{9}
\]
We point out that expression (9) is inside the integral and depends on the integration variable \(s \geq 0\). If these two expressions, (8) and (9), are non decreasing w.r.t. \(t\) for any \(t, x\) and \(s \geq 0\) then the jump measure is non decreasing. Expression (6) is non decreasing because \(g_1\) and \(g_2\) are non decreasing by hypothesis 1. Hypothesis 1 on \(g_1\) and \(g_2\) also implied that the squared root in (9) is non increasing for any \(t\) and then, because condition 1 on \(g_3\) holds, the prefactor \(t^{1/\alpha} \sigma_t^2 / k_t^{(1-\alpha)/\alpha}\) is non decreasing (even multiplied by \(s/|x|\)). Thus, (9) is non decreasing for any \(t, x\) and \(s \geq 0\) because it is the sum of a non decreasing function and \(g_3\), a non decreasing function by hypothesis. This proves that \(\nu_t(x)\) is non decreasing in \(t\).

Second, we prove that \(\lim_{t \to 0} \nu_t(x) = 0\) for \(x \neq 0\); this is equivalent to demonstrate that (8) or (9) go to zero as \(t\) goes to zero. We show that this happens in all possible cases. We first consider the case where
\[
\lim_{t \to 0} k_t > 0 \quad \text{and} \quad \lim_{t \to 0} |(1/2 + \eta_t)| < \infty . \tag{10}
\]
In this case is evident that expression (9) goes to zero for small \(t\). Otherwise, when (10) is not true, we have to distinguish two further cases depending on whether
\[
\lim_{t \to 0} (1/2 + \eta_t) k_t \sigma_t^2 = 0 \tag{11}
\]
holds. If (11) is true expression (8) goes to zero, otherwise, because of condition 2 on \(t \eta_t^2 \sigma_t^{2\alpha} / k_t^{1-\alpha}\), expression (9) goes to zero. This proves that \(\lim_{t \to 0} \nu_t(x) = 0\) for any \(x \neq 0\).

We can now check whether the triplet satisfies the conditions in [Sato 1999, Th.9.8, p.52].

1. The triplet has no diffusion term.
2. \(\nu_t\) is not decreasing in \(t\).
3. The continuity of \(\nu_t(B)\) and \(\gamma_t\), where \(B \in \mathbb{B}(\mathbb{R}^+)\) and \(B \subset \{x : |x| > \epsilon > 0\}\), is obvious for \(t > 0\): it is a natural consequence of the composition of continuous functions. For \(t = 0\) we have to prove that the limits of \(\nu_t(B)\) and \(\gamma_t\) are 0. We have already proven that \(\nu_t(x)\) is non decreasing in \(t\) and that \(\lim_{t \to 0} \nu_t(x) = 0, \forall x \neq 0\). The convergence of \(\nu_t(B)\) to 0 is due to the dominated convergence theorem. The convergence of \(\gamma_t\) is because of Lemma [A.1] and because \(t \varphi\) goes to zero by definition of ATS.
Proof of Proposition 2.2
A forward contract, valued in $t$ with delivery in $T$, is $F_t(T) = F_0(T) e^{ft}$, also for an ATS, as in [1] for the LTS.
Let us prove the sufficient condition. If the forward is martingale
\[ \mathbb{E}[F_t(T) | F_0] = F_0(T) . \]
This is equivalent to impose that
\[ \mathbb{E} [e^{ft} | F_0] = 1 , \quad (12) \]
that is, the characteristic function of $f_t$ computed in $-i$ is equal to one. From equation (4)
\[ \mathbb{E}[e^{ft} | F_0] = \mathcal{L}_t \left( \left( \eta_t + \frac{1}{2} \right) \sigma_t^2 - \frac{\sigma_t^2}{2} ; k_t, \alpha \right) e^{\varphi_t t} = \mathcal{L}_t \left( \sigma_t^2 \eta_t ; k_t, \alpha \right) e^{\varphi_t t} . \quad (13) \]
Imposing the condition (12), we get $\varphi_t$.
Let us prove the necessary condition in two steps. First, given $\varphi_t$ by equation (5) we prove that $\mathbb{E}[e^{ft} | F_0] = 1, \forall t \geq 0$. This fact is a consequence of equation (13).
Second, we check the martingale condition; that is, $\forall s, t$ s.t $0 \leq s \leq t$
\[ \mathbb{E} [F_t(T) | F_s] = F_0(T) \mathbb{E} [e^{ft-fs} | F_s] = e^{fs} F_0(T) \mathbb{E} [e^{ft-fs}] = F_s(T) \mathbb{E} [e^{ft-fs}] . \]
The proposition is proven once we prove that $\mathbb{E} [e^{ft-fs}] = 1$.
This equality holds because $f_t$ is additive; that is, process increments are independent
\[ \mathbb{E} [e^{ft} | F_0] = \mathbb{E} [e^{ft-fs} | F_0] \mathbb{E} [e^{fs} | F_0] , \]
then
\[ \mathbb{E} [e^{ft-fs}] = \mathbb{E} [e^{ft-fs} | F_0] = \frac{\mathbb{E} [e^{fs} | F_0]}{\mathbb{E} [e^{ft} | F_0]} = 1 . \]

Proof of Theorem 2.3
We check that the power-law sub-case of ATS satisfies the two conditions of Theorem 2.1
First, we verify that $g_1(t), g_2(t), \text{ and } g_3(t)$ are non decreasing.
1. $g_1(t) = (1/2 + \bar{\eta} t^\delta) - \sqrt{(1/2 + \bar{\eta} t^\delta)^2 + 2\sigma^2(1 - \alpha)/(\bar{k} t^\beta)}$
is non decreasing because its derivative w.r.t. $t$ is always greater or equal than zero for any $t \geq 0$.
\[ \frac{d}{dt} \left( (1/2 + \bar{\eta} t^\delta) - \sqrt{(1/2 + \bar{\eta} t^\delta)^2 + 2(1 - \alpha) t^{-\beta} / \bar{\sigma}^2 \bar{k}} \right) \geq 0 \]
\[ \frac{1 - \alpha}{2\bar{\sigma}^2 \bar{k}} \left( \frac{\beta t^{-\beta-\delta/2}}{\bar{\eta}^\delta} \right)^2 - \frac{\beta t^{-\delta}}{2\bar{\eta}^\delta} - \frac{\beta}{\delta} \geq 1 . \]
The last inequality is verified for any $t$ if and only if $\beta \geq -\delta$. The inequality holds due to the hypotheses $\delta \leq 0$ and $\beta > -\delta$.
2. $g_2(t) = -(1/2 + \bar{\eta} t^\delta) - \sqrt{(1/2 + \bar{\eta} t^\delta)^2 + 2\sigma^2(1 - \alpha)/(\bar{k} t^\beta)}$
is non decreasing for any $t \geq 0$: it is the sum of two non decreasing functions because of the conditions $\beta \geq 0$ and $\delta \leq 0$.
3.
\[ g_3(t) = \sqrt{\sigma^4 t^{2/\alpha-2\beta(1-\alpha)/\alpha} (1/2 + \eta t^{\delta})^2 + 2t^{-\beta+2/\alpha-2\beta(1-\alpha)/\alpha} \sigma^2 (1-\alpha)/(\bar{k})} \]

is non decreasing for any \( t \geq 0 \): it is the sum of three non decreasing functions of \( t \) (positive powers) elevated to a positive power because of the conditions \( \beta \leq \frac{1}{1-\alpha/2} \) and \( \delta > \frac{\beta(1-\alpha)-1}{\alpha} \).

Second, we verify that \( t \sigma^2 \eta_t \) and \( t \sigma^2 \eta_t^\alpha / \bar{k}_t^{1-\alpha} \) go to zero. The expressions \( t^{1+\delta} \sigma^2 \eta \) and \( t^{1+\delta-\beta(1-\alpha)/\alpha} \sigma^2 \eta_t^\alpha / \bar{k}_t^{1-\alpha} \) go to zero as \( t \) goes to zero because of the conditions \( \delta > -\min\left(\beta, \frac{1-\beta(1-\alpha)}{\alpha}\right) \) and \( \beta \leq \frac{1}{1-\alpha/2} \).

**Proof of Proposition 2.4**
We prove the thesis using the definition of additive process (Cont and Tankov 2003, Def.14.1 p.455).

1. By hypothesis \( r_0 = 0 \) and by definition of additive process \( X_0 = 0 \) almost surely. Thus, \( X_{r_0} = 0 \) almost surely.

2. Independence of increments follows from the monotonicity of \( r_t \).

3. Stochastic continuity w.r.t. time follows from stochastic continuity of the additive process and continuity of the function \( r_t \)

**Appendix B  Parameter estimation**

In physics and engineering, all measurements are subject to some uncertainties or “errors”. Error analysis is a vital part of any quantitative study (see, e.g. Taylor 1997). In this appendix, we estimate pricing errors and “propagate” them to model parameters. This is a crucial passage to verify the quality of the proposed model.

First, we estimate pricing errors. In finance, the idea of considering the bid-ask spread in market prices as a sort of measurement error of “true” prices is well known and goes back to the seminal paper of Roll (1984). He considers the price \( y = y^* + q(y_{\text{ask}} - y_{\text{bid}})/2 \), where \( y \) is the observed price, \( y^* \) the unobserved true price, and \( q \) a binomial r.v. that takes value in \{-1, 1\} with equal probability, where \(-1\) corresponds to the bid price and \(+1\) to the ask price. Modeling the uncertainty with such a distribution, the relation between bid-ask spread and price standard deviation \( \Sigma_y \) is \( \Sigma_y = (y_{\text{ask}} - y_{\text{bid}})/2 \). More recently, George et al. (1991) propose an extended formulation of the price \( y = y^* + \pi q(y_{\text{ask}} - y_{\text{bid}})/2 \), where \( \pi \) is the unobserved proportion of the spread due to the so-called order processing cost; \( \pi \) is estimated from market data as a value 0.8 and in all cases analyzed in George et al. (1991) is observed a value greater than 0.5. Conservatively, \( \pi \) can be chosen as 0.5, obtaining the relation \( \Sigma_y = (y_{\text{ask}} - y_{\text{bid}})/4 \).

Another possibility, in the plain vanilla option market for equity indices that we consider in this study, is to model the true price \( y \) as a Gaussian random variable with a mean equal to the mid-market price \( (y_{\text{ask}} + y_{\text{bid}})/2 \) and bid and ask prices chosen as symmetric quantiles. This represents more closely what is observed in this derivative market. On the one hand, it is standard for a market player to pass through an options broker to work the order. Generally, real trades are closer to the mid-market than to bid/ask prices (see, e.g. Petersen and Fialkowski 1994). On the other hand, it is not sure that a market player trades within the bid-ask spread. In some rare cases, a trade can take place at a price higher (lower) than the ask (bid) price: it can happen because the bid-ask enlarges due to sudden movements in the underlying or in presence of a very
large trade, such as the hedging of a large exposure. It is rather difficult to estimate how rare these
events are. They can happen roughly around the 5% of the cases (i.e. \( y_{\text{ask}} - y_{\text{bid}} \simeq 2 \times 1.96 \Sigma_y \)).

For this reason, in this paper, we consider the measurement error in prices as Gaussian and related
to the bid-ask spread via \( \Sigma_y = (y_{\text{ask}} - y_{\text{bid}})/4 \). With this choice, the relation between
prices standard deviation and the bid-ask spread is equal to the one obtained by George et al. (1991).

Second, we “propagate” to model parameters this measurement error in prices. In applied statistics,
the propagation of uncertainties is a standard technique (see, e.g. Taylor 1997, Ryan 2008). We
briefly recall some main results present in the literature for the models (14), (16) and (18)
considered; then we describe the calibration procedure adopted in the paper.

Consider the linear model
\[
y = Zg + \epsilon ,
\]
where \( y \in \mathbb{R}^n \) is the response vector, \( Z \in \mathbb{R}^{n \times (r+1)} \) is the explanatory variables matrix, \( \epsilon \sim N_n(0, \Sigma) \), \( \Sigma \in \mathbb{R}^{n \times n} \) is the diagonal response vector variance-covariance matrix, \( g \in \mathbb{R}^{r+1} \) is the
unobserved coefficient vector. We indicate with \( N_n(\mu, \Sigma) \) an \( n \)-dimensional Gaussian distribution
with mean \( \mu \) and variance \( \Sigma \). We perform a weighted linear regression with weights \( W \in \mathbb{R}^{n \times n} \), a
diagonal matrix. The least square solution is
\[
\hat{g} = \left( Z'WZ \right)^{-1} Z'WY ,
\]
where \( Y \in \mathbb{R}^n \) is the observed response vector (see, e.g. Ryan 2008, Ch.3, pp.115-116). Thus, \( \hat{g} \) is
the Gaussian linear combination of Gaussian random variables:
\[
\hat{g} \sim N_{r+1} \left( g, \left( Z'WZ \right)^{-1} Z'W \Sigma W Z' \left( Z'WZ \right)^{-1} \right) .
\]

In the weighted non-linear regression case, it is possible to obtain a similar result (see, e.g.
Seber and Wild 1989, Ch.2, pp.21-24). Consider the model
\[
y_i = f(g, z_i) + \epsilon_i,
\]
where \( y_i \) is the \( i^{th} \) component of the response vector \( y \in \mathbb{R}^n \), \( \epsilon_i \) is the \( i^{th} \) component of the
error vector \( \epsilon \sim N_n(0, \Sigma) \), \( z_i \) is the \( i^{th} \) row of the explanatory variables’ matrix. Similarly, the
coefficients of a non-linear regression are:
\[
\hat{g} \sim N_{r+1} \left( g, \left( F'WF \right)^{-1} F'W \Sigma W F' (F'WF)^{-1} \right) ,
\]
where \( F \in \mathbb{R}^{n \times (r+1)} \) is s.t. its \((i, j)\) element is
\[
F_{i,j} = \frac{\partial f}{\partial g_j} \bigg|_{g, z_i}
\]
and \( g_j \) is the \( j^{th} \) component of \( g \).

In the literature, the case that takes into account Gaussian correlated errors on both the response
vector and the explanatory variables is available for the fitting of a straight line (see, e.g. York 1968). Consider the model
\[
y_i = a + b(z_i + \epsilon_{z_i}) + \epsilon_{y_i} ,
\]
with \( y_i \) and \( z_i \) subjected to Gaussian errors with variance \( \Sigma_{z_i} \) and \( \Sigma_{y_i} \) and covariance \( \Sigma_{z_i,y_i} \). The estimated slope and intercept \( \hat{a} \) and \( \hat{b} \) can be obtained through a fast iterative procedure. In the
first order approximation
\[
\hat{a} \sim N(a, \Sigma_a) \quad \hat{b} \sim N(b, \Sigma_b) ,
\]
where the expressions of $\Sigma_a$ and $\Sigma_b$ are reported in \textcite{York1968}. 1st equation in p.324).

In this paper, the calibration procedure is divided into two steps.

First, for a given maturity $T$, we deal with the non-linear problem and we calibrate from market data the three time-dependent parameters $k_T$, $\sigma_T$ and $\eta_T$ on options with different strikes. The distribution of the estimated parameters can be obtained using equation (17). We construct $\Sigma$ through all observed bid and ask prices at the given maturity: the diagonal value is equal to $(y_{ask} - y_{bid})^2/16$. The matrix of weights $W$, as standard in the option market, is chosen as the identity matrix because the bid-ask spread does not differ significantly in the market prices in the calibration dataset. Consequently, the calibration results of different models can be easily compared as shown in Section 3 where we compare ATS with LTS and Sato models. As result of this step, we obtain a variance-covariance matrix $\Sigma_T \in \mathbb{R}^{3 \times 3}$ of the estimated parameters $(k_T, \sigma_T^2, \eta_T)$ for every maturity $T$.

Then, to estimate the scaling parameters of model (7), we rewrite the parameters definition w.r.t. $\theta := T \sigma_T^2$ in log-log scale as

$$
\ln \hat{k}_\theta = \ln \bar{k} + \beta \ln \theta \\
\ln \hat{\eta}_\theta = \ln \bar{\eta} + \delta \ln \theta
$$

The estimated variance and covariance of $\ln \hat{k}_\theta$, $\ln \hat{\eta}_\theta$ and $\ln \theta$ are obtained by a first-order expansion

$$
\begin{align*}
\text{Var} \left( \ln \hat{k}_\theta \right) &= \frac{\Sigma_1^{1,1}}{k_T^2} + \frac{\Sigma_2^{2,2}}{\sigma_T^4} + 2 \frac{\Sigma_1^{2,1}}{k_T \sigma_T^2} \\
\text{Var} \left( \ln \hat{\eta}_\theta \right) &= \frac{\Sigma_3^{3,3}}{\eta_T^2} \\
\text{Var} \left( \ln \theta \right) &= \frac{\Sigma_1^{2,2}}{\sigma_T^4}
\end{align*}
$$

$$
\begin{align*}
\text{Cov} \left( \ln \hat{k}_\theta, \ln \theta \right) &= \frac{\Sigma_1^{2,2}}{\sigma_T^4} + \frac{\Sigma_1^{2,1}}{k_T \sigma_T^2} \\
\text{Cov} \left( \ln \hat{\eta}_\theta, \ln \theta \right) &= \frac{\Sigma_2^{2,3}}{\eta_T \sigma_T^2}
\end{align*}
$$

where $T$ is the maturity corresponding to the $\theta$ of interest. The distributions of the estimated parameters $\beta$, $\delta$, $\bar{k}$, and $\bar{\eta}$ are the one identified in equation (19). The weights selected in the minimization procedure (see \textcite{York1968}, equation (1), p.320) are $1/	ext{Var}(\ln \hat{k}_\theta)$ in the regression on $\ln \hat{k}_\theta$ and $1/	ext{Var}(\ln \hat{\eta}_\theta)$ in the regression on $\ln \hat{\eta}_\theta$. The weights of the explanatory variable $\ln \theta$ are $1/	ext{Var}(\ln \theta)$.

Finally, from the confidence intervals for $k_T$ and $\eta_T$ we can also get the confidence intervals of the skewness and the excess kurtosis at a given maturity. We are able to obtain skewness and excess kurtosis of ATS thanks to the identity in law with LTS (for the moments of LTS see, e.g. \textcite{ContTankov2003}, p.129). The linear regression of these two higher moments, w.r.t. the squared root of time, is realized by computing the Gaussian errors (15), in the first-order approximations, of skewness and excess kurtosis.