User-Friendly Expressions of the Coefficients of Some Exponentially Fitted Methods

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Abstract. The purpose of this work consists in reformulating the coefficients of some exponentially-fitted (EF) methods with the aim of avoiding numerical cancellations and loss of precision. Usually the coefficients of an EF method are expressed in terms of \( \nu = \omega h \), where \( \omega \) is the frequency and \( h \) is the step size. Often, these coefficients exhibit a 0/0 indeterminate form when \( \nu \to 0 \). To avoid this feature we will use two sets of functions, called \( C \) and \( S \), which have been introduced by Ixaru in [61]. We show that the reformulation of the coefficients in terms of these functions leads to a complete removal of the indeterminacy and thus the convergence of the corresponding EF method is restored. Numerical results will be shown to highlight these properties.

Keywords: Exponential fitting · \( C \) and \( S \) sets of functions · \( \eta_m \) set of functions

1 Introduction

Exponential fitting is a mathematical procedure to generate numerical methods for different problems with a pronounced oscillatory or hyperbolic behaviour, usually occurring in interpolation, numerical differentiation and quadrature [30,31,33,35,60,64,65,70,78], numerical solution of first order ordinary differential equations [3,4,27,40,43,49,60,68,72,73,75,76,79], second order differential equations...
equations [54,63], integral equations [15,16], fractional differential equations [1], partial differential equations [14,45,46,50,52]. This procedure has been introduced in [62]. Its central idea consists in determining the coefficients of a numerical method by asking that the method is exact for the following set of functions, which is called a fitting space:

$$\mathcal{F} = \{1, x, \ldots, x^K, e^{\pm \mu x}, xe^{\pm \mu x}, \ldots, x^P e^{\pm \mu x}\}$$ (1)

where $\mu$ may be real or imaginary. The coefficients are functions of the parameter $\nu = \omega h$, where $\omega$ is the frequency of the oscillatory or hyperbolic functions and $h$ is the step size. The values of $\mu$ to be used in (1) are the imaginary $\mu = i\omega$ and real $\mu = \omega$, respectively.

Often, these coefficients exhibit the indeterminate form 0/0 when $\nu \to 0$ such that, in order to restore the convergence of the corresponding numerical methods when $\nu$ is small (in practice this depends on how small is the step size $h$), it is necessary to make use of the Taylor series of the coefficients. Expressed in different words, an accurate computation of the EF coefficients requires the knowledge of four different formulas (an analytic formula valid for big $\nu$ and a power series for small $\nu$, for each of the trigonometrical or hyperbolic fitting).

In the paper [61] a method was described to replace the four formulas by a single one. The coefficients have been expressed in terms of two sets of particular functions, called $C(Z)$ and $S(Z)$, where $Z = \pm \nu^2$, for real and imaginary $\mu$. A similar method has been introduced in the paper [30], in which the coefficients are expressed in terms of $\eta_m(Z)$ functions.

The work is organized as follows. In Sect. 2 we recall the two sets of $C$ and $S$ functions, and in Sect. 3 the general procedure for the conversion of the coefficient in terms of $C$ and $S$ functions is briefly presented. In Sect. 4 we reformulate the coefficients for the methods in [67,69]. In Sect. 5 numerical experiments are presented to show how the converted coefficients restore the convergence of the method.

## 2 C and S Functions

The original $\nu = \mu h$ is replaced by the new $Z = \nu^2$ which is negative if $\nu$ is imaginary and positive when $\nu$ is real. Thus, $Z < 0$ and $Z > 0$ cover the trigonometric and hyperbolic case, respectively.

To define the sets of functions $C$ and $S$ we rely on the family of functions $\eta_m(Z)$ functions, $m = -1, 0, 1, \ldots, \ldots$:

$$\eta_{-1}(Z) = \begin{cases} \cos(|Z|^{1/2}) & \text{if } Z \leq 0 \\ \cosh(Z^{1/2}) & \text{if } Z > 0 \end{cases}, \quad \eta_0(Z) = \begin{cases} \sin(|Z|^{1/2})/|Z|^{1/2} & \text{if } Z < 0 \\ 1 & \text{if } Z = 0 \\ \sinh(Z^{1/2})/Z^{1/2} & \text{if } Z > 0 \end{cases}$$ (2)

and, for $Z \neq 0$,

$$\eta_m(Z) = [\eta_{m-2}(Z) - (2m - 1)\eta_{m-1}(Z)]/Z, \quad m = 1, 2, 3, \ldots$$ (3)
while for $Z = 0$, 
$$
\eta_m(0) = 1/(2m + 1)!!, \ m = 1,\ 2,\ 3,\ ...
$$
(4)

The two sets of $C$ and $S$ functions are defined as follows: $C_{-1}(Z)$ and $S_{-1}(Z)$ are given by the first two $\eta$ functions, 
$$
C_{-1}(Z) = \eta_{-1}(Z), \ S_{-1}(Z) = \eta_0(Z)
$$
(5)

while the next ones are derived by recurrence for $Z \neq 0$, 
$$
C_n(Z) = \frac{C_{n-1}(Z) - C_{n-1}(0)}{Z}, \ S_n(Z) = \frac{S_{n-1}(Z) - S_{n-1}(0)}{Z}, \text{for } n = 0, 1, 2, \ldots,
$$
(6)

and by the following values at $Z = 0$, 
$$
C_n(0) = \frac{1}{(2n + 2)!}, \ S_n(0) = \frac{1}{(2n + 3)!}, \text{for any } n = 0, 1, 2, \ldots.
$$
(7)

An important property is the reverse relations: 
$$
C_n(Z) = ZC_{n+1}(Z) + C_n(0), \ S_n(Z) = ZS_{n+1} + S_n(0).
$$
(8)

for $n = -1, 0, 1, \ldots$. For an accurate computation of these functions, it is necessary to introduce their series expansions:
$$
C_n(Z) = \sum_{k=0}^{\infty} \frac{Z^k}{[2(k+n+1)]!!}, \ S_n(Z) = \sum_{k=0}^{\infty} \frac{Z^k}{[2(k+n) + 3]!}.
$$
(9)

Note: We acknowledge with thanks a recent private communication by Prof. Ander Murua that sets $C$ and $S$ are directly related to the Stumpff functions $c_n(Z)(n = 0, 1, 2, 3, \ldots)$:
$$
C_n(Z) = c_{2n+2}(-Z), \ S_n(Z) = c_{2n+3}(-Z).
$$

For the Stumpff functions see [81] and references therein.

### 3 Procedure for the Conversion of Coefficients

Now we describe the procedure introduced in [61] for the conversion of the coefficients. Let $\sigma(z)$, a generic coefficient derived by EF technique:
$$
\sigma(z) = \frac{N(z)}{D(z)}
$$

where $N(z)$ and $D(z)$ contains trigonometrical or hyperbolic functions and tend to 0 when $z \to 0$.

Let us denote generically by $\overline{F}$ any of numerator $\overline{N}$ or denominator $\overline{D}$, and treated separately these two functions. The procedure has two steps.
In the first step, $F(z)$ is expressed in terms of $Z$ in the following way:

$$F(z) = z^k F(Z)$$ \quad (10)

where $k = 0, 1$ and

$$F(Z) = \sum_{m=0}^{M} Z^m F_m(Z).$$ \quad (11)

The second step consists in factorizing $Z$ in $F(Z)$ as many times as possible until the form

$$F(Z) = Z^m F^*(Z)$$ \quad (12)

where $m \geq 0$ and $F^*(Z) \neq 0$.

To be able to factorize $Z$ in $F(Z)$, we have to first evaluate $F_0(Z)$ at $Z = 0$. If $F_0(0) \neq 0$, then no $Z$ factorization is possible and the procedure is stopped. Instead, if $F_0(0) = 0$, then

$$F(Z) = F_0(Z) = Z \Delta F_0(Z),$$

and

$$\Delta F_m(Z) = \sum_{j \geq -1} [a_j \alpha_j C_{j+1}(\alpha_j Z) + b_j \beta_j S_{j+1}(\beta_j Z)].$$ \quad (17)
After applying the procedure described for the numerator and the denominator of the coefficient, the user-friendly reformulation of the coefficient is obtained:

$$\sigma(Z) = \frac{N^*(Z)}{D^*(Z)},$$  \hspace{1cm} (18)

where \(N^*(0) \neq 0\) and \(D^*(0) \neq 0\).

4 Reformulation of the Coefficients

In this Section we reformulate the coefficients of two relevant classes of EF numerical methods [67,69] in terms of the \(C\) and \(S\) functions.

Example 1: The first class of methods, developed by Simos et al. in [67] regards the numerical solution of the second-order Initial Value Problems (IVPs) of the form:

$$\begin{cases}
y'' = f(x, y(x)) \\
y(x_0) = y_0 \\
y'(x_0) = y'_0
\end{cases}$$ \hspace{1cm} (19)

The scheme examined in [67] is of the form:

$$y_{n+1} + d_0 y_n + d_1 y_{n-1} + d_2 y_{n-2} + d_1 y_{n-3} + d_0 y_{n-4} + y_{n-5} = h^2 \left( \tilde{d}_0 \tilde{y}_{n+1}'' + \tilde{d}_1 \tilde{y}_n'' + \tilde{d}_2 \tilde{y}_{n-1}'' + \tilde{d}_3 \tilde{y}_{n-2}'' + \tilde{d}_1 \tilde{y}_{n-3}'' + \tilde{d}_0 \tilde{y}_{n-4}'' \right)$$ \hspace{1cm} (20)

where \(\tilde{y}_{n+1}\) is determined by solving

$$\tilde{y}_{n+1} + c_0 y_n + c_1 y_{n-1} + c_2 y_{n-2} + c_1 y_{n-3} + c_0 y_{n-4} + y_{n-5} = h^2 \left( \tilde{c}_0 \tilde{y}_{n+1}'' + \tilde{c}_1 \tilde{y}_n'' + \tilde{c}_2 \tilde{y}_{n-1}'' + \tilde{c}_3 \tilde{y}_{n-2}'' + \tilde{c}_1 \tilde{y}_{n-3}'' + \tilde{c}_0 \tilde{y}_{n-4}'' \right).$$ \hspace{1cm} (21)

and using \(\tilde{y}_{n+1}'' = f(x_{n+1}, \tilde{y}_{n+1})\) in (20).

The classical version has the constant coefficients:

$$c_0^{\text{class}} = \frac{51484823}{17645880}, c_1^{\text{class}} = \frac{23362512}{735245}, c_2^{\text{class}} = -\frac{723342859}{8822940}$$ \hspace{1cm} (22)

$$c_0 = \frac{12519323}{504168}, c_1 = \frac{2712635}{63021}, c_2 = -\frac{551}{4}.$$ \hspace{1cm} (23)

$$d_0 = \frac{23362512}{735245}, d_1 = \frac{84437}{105035}, d_2 = -\frac{9}{5}.$$ \hspace{1cm}

$$\tilde{d}_0 = \frac{1}{15}, \tilde{d}_1 = \frac{209837}{210070}, \tilde{d}_2 = \frac{320221}{315105}, \tilde{d}_3 = \frac{638003}{315105}.$$ \hspace{1cm} (23)

see [56].
In [67] the exponential fitting procedure is applied to produce the following \( \nu \) dependent expressions for the \( \tilde{c} \) coefficients:

\[
\begin{align*}
\tilde{c}^e_0 &= -\frac{1}{20166726^6 \sin^3(\nu)} \left( 3(4965191\nu^4 - 82890689\nu^2 + 22589400) \sin(\nu) \right. \\
&\quad - 48(60329\nu^2 - 308970) \sin(2\nu) - (4965191\nu^4 - 8059857\nu^2 + 68357160) \sin(3\nu) \\
&\quad + 7062520(3\nu^2 - 10) \sin(4\nu) - (5993529\nu^2 - 95582232\nu \cos(\nu)) \\
&\quad - 32(437993\nu^2 + 2928636) \nu \cos(2\nu) - 3(4965191\nu^4 + 13671432) \nu \cos(3\nu) \\
&\left. + 7562500 \nu \cos(4\nu) + 48(8759862\nu - 759933) \nu \right) \\
&\quad \text{(24)} \\
\tilde{c}^e_1 = \frac{1}{20166726^6 \sin^3(\nu)} \left( -24(8759862\nu^4 + 231349\nu^2 - 617940) \sin(\nu) \right. \\
&\quad - 18(14126869\nu^2 - 7562520) \sin(2\nu) + 4(1751972\nu^4 + 9751899\nu^2 - 15198660) \sin(3\nu) \\
&\quad + 3(4965191\nu^4 + 2785720) \sin(4\nu) + 3781260(3\nu^2 - 20) \sin(5\nu) \\
&\quad + 64(8759862\nu^2 - 2650563) \nu \cos(\nu) - 12(14126869\nu^2 - 4537512) \nu \cos(2\nu) \\
&\quad - 2(4965191\nu^4 + 13671432) \nu \cos(3\nu) + 60500160 \nu \cos(5\nu) \\
&\left. + 6(4965191\nu^4 + 13671432) \nu \right). \\
&\quad \text{(25)} \\
\tilde{c}^e_2 = \frac{1}{20166726^6 \sin^3(\nu)} \left( 6(42380607\nu^4 + 125300744\nu^2 - 45276960) \sin(\nu) \right. \\
&\quad - 24(2281331\nu^2 - 679290) \sin(2\nu) - 3(28253738\nu^4 - 74403153\nu^2 + 113732280) \sin(3\nu) \\
&\quad + 48(1821301\nu^2 - 59933130) \sin(4\nu) - 3(4965191\nu^4 + 2785720) \sin(5\nu) \\
&\quad - 7562520(3\nu^2 - 10) \sin(6\nu) + 160(906559\nu^2 - 2390292) \nu \cos(\nu) \\
&\quad - 16(1751972\nu^2 - 21371481) \nu \cos(2\nu) + 9(33218929\nu^2 - 4596408) \nu \cos(3\nu) \\
&\quad - 32(437993\nu^2 + 6709896) \nu \cos(4\nu) + (4965191\nu^4 + 13671432) \nu \cos(5\nu) \\
&\quad - 45375120 \nu \cos(6\nu) - 288(437993\nu^2 - 852624) \nu \right). \\
&\quad \text{(26)}
\end{align*}
\]

The other coefficients are untouched. They remain the same as in (23).

Theoretically we must have

\[
\lim_{\nu \to 0} \tilde{c}^e_i = \tilde{c}^\text{class}_i
\]

for \( i = 1, 2, 3 \), but a direct examination of the EF expressions given in (24–26), shows that these have an indeterminate form \( 0/0 \) for \( \nu \to 0 \) such that, in a numerical approach, a blow up of each coefficient will be obtained when \( h \) is decreased (we remind that \( \nu = \omega h \)).

This is removed by applying the procedure described in the previous Section. Indeed, now we have:

\[
\begin{align*}
\tilde{c}^\text{CS}_0 &= \frac{1}{20166726^3 \sin^3(2\nu)} \left( -59935259 C_2(2) - 897009664 C_2(4) Z - 10858872717 C_2(9) Z \right. \\
&\quad - 95582232 C_3(2) + 2399186112 C_3(4) Z + 269004796056 C_3(9) Z + 4956173107200 C_3(16) Z \\
&\quad - 148955731 S_1(2) + 1206541413 S_1(9) Z - 117752067 S_2(2) Z - 425957376 S_2(9) Z \\
&\quad + 13457398208 S_3(9) Z - 1982469248800 S_3(16) Z) \\
&\quad \text{(28)} \\
\tilde{c}^\text{CS}_1 &= \frac{1}{2520848^3 \sin^3(2\nu)} \left( -14015776 C_2(2) + 2712358848 C_2(4) Z + 10168711168 C_2(16) Z \right. \\
&\quad - 42409008 C_3(2) + 3484809216 C_3(4) Z - 44798448776 C_3(16) Z + 598081785000 C_3(25) Z \\
&\quad - 52059163 S_1(2) + 4257291963 S_1(9) Z + 1388094 S_2(2) Z + 8137076544 S_2(9) Z \\
&\quad + 2137240133 S_3(9) Z - 6101226708 S_3(16) Z - 221558203125 S_3(25) Z + 3707640 S_3(16) Z \\
&\quad + 17424604080 S_3(25) Z + 29915524780 S_3(9) Z + 447985487760 S_3(16) Z \\
&\quad - 36926367185000 S_3(25) Z) \\
&\quad \text{(29)}
\end{align*}
\]
\[ c^\text{CS}_2 = \frac{1}{2016672 S_1^2(Z)} \left( -145049440 C_2(Z) + 1794019328 C_2(4Z) - 21794393169 C_2(9Z) \\
+ 57408618496 C_2(16Z) - 77581109375 C_2(25Z) - 382446720 C_3(Z) + 8753586176 C_3(4Z) \\
+ 27141329592 C_3(9Z) - 140716716192 C_3(16Z) + 53404031250 C_3(25Z) \\
- 76212775392 C_3(36Z) + 254283642 S_2(4Z) + 2056975002 S_2(9Z) - 751804464 S_2(16Z) \\
+ 7008193536 S_2(25Z) + 1163716640625 S_2(36Z) - 217661760 S_3(4Z) - 2056975002 S_3(9Z) \\
+ 751804464 S_3(16Z) - 77581109375 S_3(25Z) \\
+ 57408618496 S_3(36Z) + 21794393169 S_3(45Z) - 21794393169 S_3(54Z) \right). \]  

(30)

The new expressions are also quotients of two \( \nu \) dependent functions but, as expected, they do no longer exhibit indeterminacy when \( \nu \to 0 \). Also worth mentioning is that the power of \( Z \) in (13) for all these three coefficients is \( m = 4 \).

The use of \( \eta \) functions has the same effect. In fact, by applying the procedure described in [30], the coefficients expressed by these functions are (see also [23]):

\[ \tilde{c}_0^\eta = -\frac{1071987210 \eta_0^4(Z/64) - 535993605 \eta_0^2(Z/256)(1 + \eta_0(Z/64)) + \cdots}{13552035840(2 + Z \eta_0^2(Z/4) - 2Z \eta_1(Z))^3} \]  

(31)

\[ \tilde{c}_1^\eta = -\frac{2031821820 \eta_0^4(Z/64) - 1015910910 \eta_0^2(Z/256)(1 + \eta_0(Z/64)) + \cdots}{13552035840(2 + Z \eta_0^2(Z/4) - 2Z \eta_1(Z))^3} \]  

(32)

\[ \tilde{c}_2^\eta = -\frac{2146293450 \eta_0^4(Z/64) - 1073146725 \eta_0^2(Z/256)(1 + \eta_0(Z/64)) + \cdots}{6776017920(2 + Z \eta_0^2(Z/4) - 2Z \eta_1(Z))^3} \]  

(33)

The full expressions can be obtained using the Mathematica modules in [30]. Both ways of deriving single formulae, instead of four, are then acceptable, and the expected theoretical behavior

\[ \lim_{Z \to 0} \tilde{c}_i^\text{CS} = \lim_{Z \to 0} \tilde{c}_i^0 = \tilde{c}_i^{\text{class}}, \]  

(34)

is preserved.

**Example 2:** We consider the numerical method developed by Ndukum et al. [69] to solve the first-order IVP:

\[ \begin{cases} 
  y' = f(x, y(x)) \\
  y(a) = y_0 
\end{cases} \]  

with \( x \in [a, b] \).

The scheme used is a \( k \)-step numerical method of the form:

\[ y_{n+k} = \sum_{r=0}^{k-1} \alpha_r(\nu)y_{n+r} + h(\beta_k(\nu)f_{n+k} + \beta_{k+1}(\nu)f_{m+k+1}). \]  

(36)

In the paper [69] the authors presented the coefficients of the method corresponding to \( k = 1, 2, 3, 4, 5 \). In the paper [61] the case \( k = 2 \) has been considered.
In the following we consider the case \( k = 3 \).

By applying the exponential fitting procedure, the coefficients are [69]:

\[
\alpha_0^\text{ef} = \frac{5\nu - 11\nu \cos \nu + 7\nu \cos 2\nu - \nu \cos 3\nu + 4 \sin \nu + 2\nu^2 \sin \nu - 2 \sin 2\nu}{7\nu \cos \nu - 17\nu \cos 2\nu + 13\nu \cos 3\nu - 3\nu \cos 4\nu + 4 \sin \nu + 2\nu^2 \sin 2\nu - 2 \sin 2\nu}
\]

\[
\alpha_1^\text{ef} = \frac{-12\nu + 23\nu \cos \nu - 9\nu \cos 2\nu - 3\nu \cos 3\nu + \nu \cos 4\nu - 2 \sin \nu - 6\nu^2 \sin \nu - 2 \sin 2\nu + 2 \sin 3\nu}{7\nu \cos \nu - 17\nu \cos 2\nu + 13\nu \cos 3\nu - 3\nu \cos 4\nu + 4 \sin \nu + 2\nu^2 \sin 2\nu - 2 \sin 2\nu}
\]

\[
\alpha_2^\text{ef} = \frac{7\nu \cos \nu - 15\nu \cos 2\nu + 17\nu \cos 3\nu - 4\nu \cos 4\nu + 2 \sin \nu + 6\nu^2 \sin \nu + 2 \sin 2\nu - 2 \sin 3\nu}{7\nu \cos \nu - 17\nu \cos 2\nu + 13\nu \cos 3\nu - 3\nu \cos 4\nu + 4 \sin \nu + 2\nu^2 \sin 2\nu - 2 \sin 2\nu}
\]

which all exhibit the 0/0 indeterminacy.

The coefficients modified by means of the the procedure described in the previous Section are:

\[
\alpha_0^\text{CS} = \frac{1 + (63C_2^3(Z) - 256C_2^4(2Z) + 1701C_2^4(9Z) - 2048C_2^4(16Z))}{-7C_2^3(Z) + 1088C_2^4(4Z) - 9477C_2^4(9Z) + 12288C_2^4(16Z) + 2S_1(Z) - 85S_2(Z) + 256S_2(16Z)}
\]

\[
\alpha_1^\text{CS} = \frac{23C_2^3(Z) - 576C_2^4(4Z) - 2187C_2^4(9Z) + 4906C_2^4(16Z) + 6S_1(Z) - 2S_2(Z) - 256S_2(4Z) + 4374S_2(9Z)}{7C_2^3(Z) - 1088C_2^4(4Z) + 9477C_2^4(9Z) - 2(6144C_2^4(16Z) + S_1(Z) - 2S_2(Z) + 128S_2(4Z))}
\]

\[
\alpha_2^\text{CS} = \frac{-5C_2^3(Z) - 900C_2^4(4Z) + 1239C_2^4(9Z) - 16384C_2^4(16Z) - 6S_1(Z) + 2S_2(Z) + 256S_2(4Z) - 4374S_2(9Z)}{7C_2^3(Z) - 1088C_2^4(4Z) + 9477C_2^4(9Z) - 2(6144C_2^4(16Z) + S_1(Z) - 2S_2(Z) + 128S_2(4Z))}
\]

\[
\beta_3^\text{CS} = \frac{2C_2^3(Z) - 384C_2^4(4Z) + 4374C_2^4(9Z) - 8192C_2^4(16Z) + 25S_2(Z) - 2560S_2(4Z) + 10935S_2(9Z)}{7C_2^3(Z) - 1088C_2^4(4Z) + 9477C_2^4(9Z) - 2(6144C_2^4(16Z) + S_1(Z) - 2S_2(Z) + 128S_2(4Z))}
\]

\[
\beta_4^\text{CS} = \frac{3(2C_2^3(Z) - 128C_2^4(4Z) + 486C_2^4(9Z) - 55S_2(Z) + 512S_2(4Z) - 2187S_2(9Z))}{7C_2^3(Z) - 1088C_2^4(4Z) + 9477C_2^4(9Z) - 2(6144C_2^4(16Z) + S_1(Z) - 2S_2(Z) + 128S_2(4Z))}
\]

We observe that in all five coefficient the power of \( Z \) in (13) is \( m = 3 \). As for the coefficients expressed in terms of \( \eta_m(Z) \) functions, these are:

\[
\tilde{\alpha}_0^\eta = \frac{-210\eta_0^4(Z/16) - 10\eta_0^2(Z/64)(1 + \eta_0(Z/16)) + \ldots}{165\eta_0^2(Z/64)(1 + \eta_0(Z/16)) + \ldots}
\]

\[
\tilde{\alpha}_1^\eta = \frac{630\eta_0^4(Z/16) + 315\eta_0^2(Z/64)(1 + \eta_0(Z/16)) - \ldots}{165\eta_0^2(Z/64)(1 + \eta_0(Z/16)) + \ldots}
\]

\[
\tilde{\alpha}_2^\eta = \frac{-90\eta_0^4(Z/16) - 45\eta_0^2(Z/64)(1 + eta(Z/16)) + \ldots}{165\eta_0^2(Z/64)(1 + \eta_0(Z/16)) + \ldots}
\]

\[
\tilde{\beta}_3^\eta = \frac{5(162\eta_0^4(Z/16) + 81\eta_0^2(Z/64)(1 + \eta_0(Z/16)) - \ldots}{165\eta_0^2(Z/64)(1 + \eta_0(Z/16)) + \ldots}
\]

\[
\tilde{\beta}_4^\eta = \frac{-3(90\eta_0^4(Z/16) + 45\eta_0^2(Z/64)(1 + \eta_0(Z/16)) - \ldots}{165\eta_0^2(Z/64)(1 + \eta_0(Z/16)) + \ldots}
\]

Similar to the previous case, the full expression of the coefficients can be obtained using the Mathematica modules in [30].
5 A Check on the Effectiveness of the Approach

In this Section we show the graphs of the behavior of the coefficients and how our reformulation restores the convergence of the corresponding method.

On the left column of Fig. 1 we show the $h$ dependence of the coefficients $\tilde{c}_{i}^{\text{ef}}(\nu)$, $\nu = \omega h$, for $\omega = 10$ and $i = 0, 1, 2$ of Example 1 compared with the reformulated $\tilde{c}_{i}^{\text{CS}}(Z)$, $Z = -\nu^2 = -(\omega h)^2$, by means of $C(Z)$ and $S(Z)$ functions, and $\tilde{c}_{i}^{\eta}(Z)$ by means of $\eta_{m}(Z)$ functions. In particular, we observe that the coefficients expressed in terms of $\eta_{m}(Z)$ functions and the coefficients expressed in terms of $C$ and $S$ functions converge to the classical value, while the coefficients $\tilde{c}_{0}^{\text{eg}}, \tilde{c}_{1}^{\text{eg}}$, and $\tilde{c}_{2}^{\text{eg}}$ blow up when $h$ is decreased. From the numerical point of view

![Graphs showing the behavior of coefficients and their error](image-url)

Fig. 1. Left: Coefficients $\tilde{c}_{i}^{\text{ef}}, \tilde{c}_{i}^{\text{CS}}, \tilde{c}_{i}^{\eta}$ of Example 1 for $\omega = 10$; Right: Error of $\tilde{c}_{i}^{\text{bf}}$ and $\tilde{c}_{i}^{\text{CS}}$ coefficients with respect to $\tilde{c}_{i}^{\eta}$.
the limit tendency (27) is not verified but (34) holds true. On the right column of the same figure we give additional details. On it we present the deviations of the coefficients computed by the first two approaches with respect to those expressed in terms of the $\eta_m(Z)$ functions. It is seen that the two reformulations (28)–(30) and (31)–(33) differ by a factor of only $10^{-10}$ irrespective of $h$ while the EF coefficients (24)–(26) exhibit an error which increases as $h \to 0$ to reach a value of about $10^2$ for $h = 10^{-3}$.

The same data are presented on Figs. 2 and 3 for the coefficients of Example 2. Again, the coefficients obtained in the frame of the original EF approach of [69] are oscillating and inaccurate when $h \to 0$, in contrast with those in the
other two approaches. The results from the latter two approaches are actually in agreement within $10^{-15}$.

Also instructive is that, in contrast with Example 1, the blow up of the original EF estimates occurs at values of $h$ much smaller than before, and this is due to the power $m$ in (13) which for the previous case was $m = 4$ while it is $m = 3$ by now. This allows concluding that the need of reformulations in the spirit of the approach presented in this paper is more and more stringent when $m$ is increased.

An important issue is that of checking in what extent the accuracy in the evaluation of the coefficients affects the accuracy of the results when solving numerically a differential equation. To illustrate this we consider the following problem:

$$
\begin{cases}
y'' = -100y(t) + 99\sin(t) \\
y(0) = 1 \\
y'(0) = 11
\end{cases}
$$

with $t \in [0, 20\pi]$, whose analytic solution is $y(t) = \cos(10t) + \sin(10t) + \sin(t)$. In Fig. 4, we compare the method (20)–(21) for three versions of the coefficients; in particular we denote:

- EF: the method with coefficients (23)–(24)–(25)–(26);
Fig. 4. Absolute error in $t = 20\pi$ of method (20)–(21) on problem (52)

- EF converted CS: the method with coefficients (23)–(28)–(29)–(30) converted by means of $C$ and $S$ functions;
- EF converted $\eta_m(Z)$: the method with coefficients (23)–(31)–(32)–(33) converted by $\eta_m(Z)$ functions.

Figure 4 shows that the reformulation of the coefficients in terms of either $C$ and $S$ or of $\eta$ functions fully restores the convergence of the method.

6 Conclusions

We have shown that the reformulation of the expressions of the coefficients of EF-based numerical methods for differential equations in terms of the sets of functions $C$ and $S$ has two main advantages:

1. it allows reducing the original set of four expressions for each coefficient to a single one with universal use;
2. it removes completely the potential inaccuracy of the numerical solution when the step size $h$ is small.

The procedure is then recommended as a reliable alternative to that based on $\eta$ functions.

Further developments of this research will be oriented to the reformulation, through $C$ and $S$ functions, of existing methods for ordinary differential equations [2,17,20,25,26,28,37–39,41,42,44,48,51,53,56,77,80], integral equations [5–8,10,11,24,29,32,34,55,71], stochastic problems [9,12,13,18,19,29,47], fractional equations [12,13,21,22,36], partial differential equations [57–59,66,74].
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