DAMSL: Domain Agnostic Meta Score-based Learning

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Abstract

In this paper, we propose Domain Agnostic Meta Score-based Learning (DAMSL), a novel, versatile and highly effective solution that delivers significant out-performance over state-of-the-art methods for cross-domain few-shot learning. We identify key problems in previous meta-learning methods over-fitting to the source domain, and previous transfer-learning methods under-utilizing the structure of the support set. The core idea behind our method is that instead of directly using the scores from a fine-tuned feature encoder, we use these scores to create input coordinates for a domain agnostic metric space. A graph neural network is applied to learn an embedding and relation function over these coordinates to process all information contained in the score distribution of the support set. We test our model on both established CD-FSL benchmarks and new domains and show that our method overcomes the limitations of previous meta-learning and transfer-learning methods to deliver substantial improvements in accuracy across both smaller and larger domain shifts.

1. Introduction

Few-shot learning methods promise to solve one of the most challenging issues in deep learning: the reliance on copious amounts of labelled examples to achieve high accuracies. By doing so, we can achieve cost savings and accurately classify rare classes of images (e.g. plane crashes) where labelled examples are limited. The problem, however, is that few-shot learning methods fail to perform well when there is a domain-shift. Hence, the practical applications of few-shot learning are severely limited as the few-shot models trained on well-labelled and well-structured research datasets cannot be applied to domains in industry.

The above problem is exacerbated under sharp domain shifts, as shown in the Broader Study of Cross-Domain Few-Shot Learning (BSCD-FSL) [7]. The study found that many few-shot learning methods significantly under-performed compared to transfer-learning as few-shot learning overfitted to the source domain. While transfer-learning methods did perform better, they omitted distributional information contained in the each episode’s support set is omitted. This is clearly sub-optimal given the need to maximally use information in the sparse setting [20] [17].

To solve the above issues, we propose Domain Agnostic Meta Score-based Learning (DAMSL). The fundamental idea behind our method is to apply transfer-learning to prevent over-fitting to the source domain, while using metric-learning to exploit the information in each episode’s support samples. Furthermore, as metric-learners built on image features are shown to suffer greatly from overfitting to the source domain, we make our metric-learner domain-agnostic by fitting to pre-softmax classification scores from fine-tuned feature encoders.

In our work, we use the BSCD-FSL benchmark [7] and augment it with 4 more test domains for further comparisons. We demonstrate the superiority of our method over existing methods across these 8 distinct test domains, and show a new research direction for score-based boosting in the few-shot classification setting.

2. Relevant Work

Metric-based methods, such as prototypical networks [16], aim to learn a metric function $\phi_p$, that can be used to classify query images based on their relations to the images in the support set. The key metric-based method that we use is Graph Neural Network (GNN) as graph-based convolutions can create more flexible representations [1].

Transfer learning involves reusing features learned from base classes [14], typically by fine-tuning a pre-trained model. A simple extension of fine-tuning would be to learn to fine-tune. Methods such as MAML [4] learn an internal representation that can be fine-tuned in a few gradient steps.
3. Methodology

The training process during each episode for our model is shown in Figure 1. On test domains, the same fine-tuning process occurs over the labelled support set, but with gradient updates only within episodes and not between episodes.

3.1. Score-based Metric Learning

Given only a sparse support set from the test domain, it is difficult to precisely fit the feature encoder in a way that neither overfits nor underfits [12]. Creating a hold-out validation set is also prohibitively costly under such conditions. We begin by fine-tuning a feature vector to obtain \( \tilde{\phi}_f(X_s) \in \mathbb{R}^{512} \). Then, we take the linear classifier \( \tilde{\phi}_c \) to produce a pre-softmax score vector \( \tilde{\phi}_c(\tilde{\phi}_f(X_i)) \in \mathbb{R}^5 \), which corresponds to our 5-way classification problem. A typical transfer-learning approach would directly use the score vector for prediction \( \hat{Y}_q = \arg\max_{q \in 1,...,5} \tilde{\phi}_c(\tilde{\phi}_f(X_q)) \).

Instead, we post-process the score vector by using a metric-learning network \( \phi_m \). Formally, this gives us: \( \hat{Y}_q = \arg\max_{\phi_m(Y_s, \tilde{\phi}_c(\tilde{\phi}_f(X_q)) \in \mathbb{R}^5} \). Thus, we explicitly incorporate information contained in the predictions we can make on the support sets \( X_s \) and how these predictions correspond to the labels \( Y_s \). Any biases found in the feature encoder \( \phi_f \) and linear classifier \( \phi_c \) can be corrected by inferring a distribution from the support set scores, and using that distribution to match the scores of our query samples. These learned edge features are used to propagate information in the graph through the graph convolution in equation 1. Initial vertex features are constructed by taking the score projections and one-hot encoding of labels for the support set or a uniform distribution for the query samples.

3.2. Graph Neural Network

The meta-learning module we use is the Graph Neural Network (GNN). We follow the formulation of the GNN for the few-shot problem in [15]. In brief, a GNN acts on local operators of a graph \( G = (V,E) \), which for the few-shot learning case is fully connected. A graph convolution layer \( GC(\cdot) \) [15] is performed with linear operations on local signals. Formally, we have:

\[
GC(S^k) = f \left( \sum_{B \in A} B S^k \theta_{B,q} \right), \quad q = d_1, ..., d_{k+1} \tag{1}
\]

In the few-shot learning formulation, we can learn the edge features using the current hidden vertex [15]. We apply a Multi-layer Perceptron (MLP) that takes in the absolute difference between the output vectors of vertices in the graph [9] [5]. Formally, we have:

\[
\tilde{A}^k_{i,j} = \gamma (S^k_i, S^k_j) = MLP(|S^k_i - S^k_j|) \tag{2}
\]

These learned edge features are used to propagate information in the graph through the graph convolution in equation 1. Initial vertex features are constructed by taking the score projections and one-hot encoding of labels for the support set or a uniform distribution for the query samples.

3.3. Backbone Variants

We experiment with two variants of the DAMSL model with different feature backbones. In DAMSL v1, we have a ResNet10 pre-trained using supervised learning and first-order MAML [13]. In DAMSL v2, we have two ResNet10 pre-trained using supervised learning but with different optimization strategies - one trained using Adam while other trained using SGD with momentum.
4. Results and Discussion

4.1. Experimental Setup

First, we test our model on the BSCD-FSL benchmark. We train on miniImageNet and test on CropDisease [11], EuroSAT [8], ISIC [18] [3] and ChestX [19] (in order of decreasing similarity). CropDisease covers plant disease, EuroSAT covers satellite images, ISIC covers dermoscopic skin lesion images and ChestX covers chest X-ray images.

4 other new datasets are also included: Places [21], Describable Textures Dataset (DTD) [2], CIFAR-100 [10] and Caltech256 [6]. While the images in these other datasets are all natural images, they contain very different types of classification tasks from miniImageNet. For instance, DTD [50x170] deals with natural objects, Caltech256 [50x194] with animals, and CIFAR-100 [50x230] with different types of objects.

4.2. Results on the BS-CDFSL Benchmark

From Table 1, DAMSL with both feature backbones outperforms previous methods, even without using data augmentation. We see that DAMSL v1 achieves an average accuracy of 72.13% while DAMSL v2 achieves an average accuracy of 74.34%. With data augmentation, DAMSL v1 (Aug) achieves an average accuracy of 74.06% while DAMSL v2 (Aug) achieves an average accuracy of 74.99%.

We focus on DAMSL v2 in our comparison with other methods as it has the highest performance. DAMSL v2 (Aug) outperforms TransFT by 6.86% and ProtoNet by 15.21%. From Table 1, we see that DAMSL (Aug) v2 still significantly outperforms TransFT (Aug), with the exception of 5-way 5-shot Chest-X. In terms of average accuracy, DAMSL v2 (Aug) outperforms TransFT (Aug) by 3.84%.

Our method is competitive with typical supervised learning on domains closer to the source domain. Typical supervised learning models for EuroSAT and CropDisease have achieved 98.57% and 99.35% respectively [8] [11]. At our 50-shot results for DAMSL v2 (Aug), we achieve 98.60% and 99.87% respectively on EuroSAT and CropDisease.

4.3. Ablation Studies on BSCD-FSL

To investigate the effect of each component separately, we include a Linear Ensemble (L-Ensem), a Fine-Tuned en-
L-Ensem yields 69.23% domain-specific features, and thus fails on distant domains. GNN performs substantially worse than DAMSL. This is in demonstrate the value of score-based metric learning as FT-
resentations, and the fact that it exploits the full distribution
model. We attribute this to the GNN’s more flexible repre-
not match up to the performance of our proposed DASML
formance compared to L-Ensem. However, it still does
ple ProtoNets. On all tasks, the S-Proto delivers a better
ers an improvement when used in conjunction with a sim-
ping MLP and a nearest centroid classifier, to demonstrate
based ProtoNets replaces the GNN module with an embed-
performance boost from score-based learning. The Score-
has been fine-tuned on the support set, to demonstrate the
semble. FT-GNN is directly fitted to a feature vector that
coders, to see the performance from a simple fine-tuned en-
the post-softmax scores from the two fine-tuned feature en-
Coder + GNN (FT-GNN), and Score-based ProtoNets (S-
producers by
4.4. Results on other Test Domains
From Table 2, we clearly see that DAMSL v2 delivers out-performance over the previous baselines across almost all settings and all shots, with the only exception of 5-shot setting for Places. In terms of average accuracy, DAMSL v1 achieves 81.48% while DAMSL v2 achieves 85.46%. These values are considerably higher (> 5%) than the linear ensembles, which yields 74.31% and 77.91% respec-
tively. The results clearly validate our method as DAMSL performs better than previous methods on data-sets other than those in the BSCD-FSL benchmark.

5. Conclusion
We propose Domain Agnostic Meta Score-based Learning (DAMSL) to address the Cross-Domain Few-Shot Learning problem. On BSCD-FSL, DAMSL v2 achieves 74.99% accuracy, which significantly outperforms previous best-performing meta-learning and transfer-learning methods by 15.21% and 6.86% respectively. From Figure 2, we also see that the performance gains from our method are substantially greater than gains from including data augmentation or adding another feature encoder. Moreover, on the 4 other test domains beyond BSCD-FSL, our method continues to consistently outperform strong baselines.

Ultimately, we not only decisively address the CD-FSL problem, but we also outline a new strand of classification boosting modules that can be attached to any existing model to self-correct initial classification scores by utilizing the distributional information of scores from labelled samples.
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