A DENSITY RESULT FOR SOBOLEV SPACES IN DIMENSION TWO, AND APPLICATIONS TO STABILITY OF NONLINEAR NEUMANN PROBLEMS

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ABSTRACT. We prove that if \( \Omega \subseteq \mathbb{R}^2 \) is bounded and \( \mathbb{R}^2 \setminus \Omega \) satisfies suitable structural assumptions (for example it has a countable number of connected components), then \( W^{1,2}(\Omega) \) is dense in \( W^{1,p}(\Omega) \) for every \( 1 \leq p < 2 \). The main application of this density result is the study of stability under boundary variations for nonlinear Neumann problems of the form

\[
\begin{align*}
-\text{div} A(x, \nabla u) + B(x, u) &= 0 \quad \text{in } \Omega, \\
A(x, \nabla u) \cdot \nu &= 0 \quad \text{on } \partial \Omega,
\end{align*}
\]

where \( A: \mathbb{R}^2 \times \mathbb{R}^2 \to \mathbb{R}^2 \) and \( B: \mathbb{R}^2 \times \mathbb{R} \to \mathbb{R} \) are Carathéodory functions which satisfy standard monotonicity and growth conditions of order \( p \).

Keywords: Sobolev spaces, capacity, Hausdorff measure, Hausdorff metric, nonlinear elliptic equations, Mosco convergence.

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1. Introduction

In this paper we prove a density result for Sobolev spaces defined on two dimensional open bounded sets. More precisely, for \( 1 \leq p < 2 \) and \( \Omega \subseteq \mathbb{R}^2 \) open, bounded and belonging to the class \( \mathcal{A}_p(\mathbb{R}^2) \) of admissible domains (see Definition 3.1), we prove that the Sobolev space \( W^{1,2}(\Omega) \) is dense in \( W^{1,p}(\Omega) \). The class \( \mathcal{A}_p(\mathbb{R}^2) \) contains for example domains whose complements have a countable number of connected components or even whose complements are Cantor sets with small dimension.

In the case \( \Omega \) is sufficiently regular (for example if it satisfies a cone condition), this density result is trivial because by means of extension operators and convolutions one can prove that \( C^\infty(\overline{\Omega}) \) is dense in \( W^{1,p}(\Omega) \). The situation is different when \( \Omega \) is irregular: extension operators cannot be employed, and the density of \( C^\infty(\overline{\Omega}) \) in \( W^{1,p}(\Omega) \) can fail, as in the case the domain contains a crack. Even the density of \( C^\infty(\Omega) \) in \( W^{1,p}(\Omega) \) proved by Meyers and Serrin [27] which holds for every open bounded set \( \Omega \) cannot be used because the control on the energy of order 2 is available only well inside, and can be lost approaching the boundary. In this direction, we refer the reader to the paper of O’Farrel [28] for a counterexample to the density of \( W^{1,\infty}(\Omega) \) in \( W^{1,p}(\Omega) \) in the case \( \Omega \) is too irregular.
The main motivation of our density result is the study of stability under boundary variations for two dimensional nonlinear Neumann problems of the form

\begin{align}
-\text{div}A(x,\nabla u) + B(x, u) &= 0 \quad \text{in } \Omega \\
A(x,\nabla u) \cdot \nu &= 0 \quad \text{on } \partial \Omega,
\end{align}

where \(A: \mathbb{R}^2 \times \mathbb{R}^2 \to \mathbb{R}^2 \) and \(B: \mathbb{R}^2 \times \mathbb{R} \to \mathbb{R} \) are Carathéodory functions satisfying standard monotonicity and growth conditions of order \(p \) (see conditions (1.3)-(1.5)). Namely we are interested in the continuity of the map \( \Omega \to u_\Omega \), where \( u_\Omega \in W^{1,p}(\Omega) \) is the solution of (1.1) in \( \Omega \) (see Section 2 for the precise sense of the continuity of this mapping).

The density of \( W^{1,2} \) in \( W^{1,p} \) is a key point to infer stability for problem (1.1) from that of the linear equation

\begin{align}
-\Delta u + u &= f \quad \text{in } \Omega \\
\frac{\partial u}{\partial \nu} &= 0 \quad \text{on } \partial \Omega.
\end{align}

Stability results for problem (1.2) have been obtained by several authors (see for example [10], [11], [12], [13], [14], [15], [8], [9]). These results hold in generic dimension \( N \) under quite restrictive assumptions on \( \Omega \) and its possible perturbations. For example Chenais [15] proved stability for (1.2) under a uniform cone condition for the perturbed domains, and this condition excludes several interesting cases like those of domains containing cracks which are of interest in fracture mechanics. Moreover, the cone condition implies the existence of extension operators, and the density of \( W^{1,2} \) in \( W^{1,p} \) is trivial, so that the stability of (1.1) holds under the same assumptions.

In dimension \( N = 2 \) the situation is different, and restrictions only on the topological nature of the domains have been individuated in order to achieve stability for (1.2): this is the reason why we are interested in density for Sobolev spaces defined on two dimensional, possibly irregular, domains. Bucur and Varchon [8] consider domains whose complements have a uniformly bounded number of connected components and prove that, if \( \Omega_n \to \Omega \) in the Hausdorff complementary topology (see Section 2 for a definition), we have the stability \( u_{\Omega_n} \to u_\Omega \) if and only if

\[ \text{meas}(\Omega_n) \to \text{meas}(\Omega). \]

Under strict monotonicity assumptions for \( A \) and \( B \), Dal Maso, Ebobisse and Ponsiglione [15] proved that the same conclusion holds for problem (1.1) in the case \( 1 < p < 2 \), while for \( p > 2 \) stability is in general false (see [15] Remark 3.7)). The main tool they employ is the Mosco convergence of \( W^{1,p}(\Omega_n) \) to \( W^{1,p}(\Omega) \) (see Section 2 for a definition) which is equivalent to the stability of (1.1) for every admissible \( A \) and \( B \). The Mosco convergence in the case \( p = 2 \) is indeed a corollary of the stability result by Bucur and Varchon [8]. Since they make use of conformal mappings, and these are not useful in a nonlinear setting, Dal Maso, Ebobisse and Ponsiglione provide a different proof of the Mosco convergence based on nonlinear harmonic conjugates. In view of our density result, the Mosco convergence when \( 1 < p < 2 \) (and hence the stability result for (1.1)) can be deduced from the case for \( p = 2 \) (see Proposition 4.3).

In Section 4 we consider the nonlinear Neumann problems

\begin{align}
-\text{div}A(x,\nabla u) + b(x)|u|^{p-2}u &= h \quad \text{in } \Omega \\
A(x,\nabla u) \cdot \nu &= 0 \quad \text{on } \partial \Omega,
\end{align}

where \( b \in L^\infty(\mathbb{R}^2) \) is such that \( b \geq 0 \), and \( h \) satisfies suitable assumptions in order to guarantee the existence of a solution. These problems introduce some degeneracy with respect to problems (1.1) because \( b \) can vanish on subsets of \( \Omega \) with positive measure. As a consequence stability cannot be studied in terms of Mosco convergence of suitable functional spaces, because the two notions are in general not equivalent (see [3] Remark 5.2)), and so in order to prove stability for (1.3), the results of Dal Maso, Ebobisse and Ponsiglione cannot be directly used.

In the case \( p = 2 \), and with \( A(x, \xi) = \xi \), Bucur and Varchon [10] proved that if the complement of \( \Omega_n \) has a uniformly bounded number of connected components and \( \Omega_n \to \Omega \) in the Hausdorff complementary topology, then stability holds if and only if

\[ \text{meas}(\Omega_n \cap \{ b > 0 \}) \to \text{meas}(\Omega \cap \{ b > 0 \}). \]
We prove (Proposition 4.4) that the same result holds in the nonlinear case $1 < p < 2$. In the case
$p > 2$, stability does not hold in general (see Remark 3.7).

A second application of our density result is to a shape optimization problem, namely the
optimal cutting of a membrane. The admissible cuts we consider are compact and connected
sets which contain two given points. The case of a quadratic energy has been treated by Bucur,
Buttazzo and Varchon in [5]. In Proposition 4.5 we prove the existence of an optimal cut for
a nonlinear energy density $f(x, \xi)$ with growth of order $1 < p \leq 2$ in $\xi$. Moreover we prove a
stability result for the associated Euler-Lagrange equation, which is of Neumann-Dirichlet type.
We remark that in order to establish the existence of the optimal cut and the stability for
the associated equation, the approximation results of Dal Maso, Ebobisse and Fonseglione [13] in terms
of Mosco convergence cannot be used (see Remark 4.7).

Finally, in the Appendix, we show how the arguments of Section 3 provide a new proof of a
result due to Chambolle [13] concerning the density of
$W^{1,2}(\Omega)$ in $L^p(\Omega)$ at the level of the gradients. More precisely we prove that for every
$u \in W^{1,p}(\Omega)$ we have $\nabla u \in H$, where

$$H := \{ \nabla v : v \in W^{1,2}(\Omega) \} \subseteq L^p(\Omega, \mathbb{R}^2).$$

We use the fact that $H = (H^1)^\perp$, where $(\cdot)^\perp$ denotes the orthogonal in the sense of Banach spaces. Using Helmholtz Decomposition Theorem, in Lemma 3.3 we characterize $H^1$ as the family of
fields $\psi$ such that $R\psi = \nabla \phi$ with $\phi \in W^{1,2}(\mathbb{R}^2)$ constant on the connected components of $\mathbb{R}^2 \setminus \Omega$, where $p'$ is the conjugate exponent of $p$ and $R$ denotes a rotation of 90 degrees counterclockwise.
Moreover, using the approximation given in Lemma 3.3 and the fact that $\Omega \in A_p(\mathbb{R}^2)$, we can approximate $\phi$ through functions $\phi_n \in W^{1,p'}(\mathbb{R}^2)$ which are constant on a neighborhood of $\mathbb{R}^2 \setminus \Omega$. Then the orthogonality of $\nabla u$ and $\psi$ follows by integration by parts.

The paper is organized as follows. In Section 2 we introduce the notation and recall some useful
notations employed in rest of the paper. Section 3 contains the density result (Theorem 3.3), while
Section 4 contains the applications to stability of nonlinear Neumann problems and to the optimal
cutting of a membrane. In the Appendix we prove the density of $W^{1,2}$ in the spaces of planar elasticity.

2. Notation and Preliminaries

In this section we introduce the basic notation and recall some notions employed in the rest of the
paper.

If $A \subseteq \mathbb{R}^N$ is open and $1 \leq p \leq +\infty$, we denote by $L^p(A)$ the usual space of $p$-summable functions
on $A$ with norm indicated by $\| \cdot \|_p$. $W^{1,p}(A)$ will denote the Sobolev space of functions
in $L^p(A)$ whose gradient in the sense of distributions belongs to $L^p(A, \mathbb{R}^N)$, and we denote by
$W^{1,p}(A)$ the closure in $W^{1,p}(A)$ of smooth functions with compact support.

If $E \subseteq \mathbb{R}^N$, we will denote with $\text{meas}(E)$ its $N$-dimensional Lebesgue measure, and by $\mathcal{H}^N(E)$
its $N$-dimensional Hausdorff measure (see Chapter 2 for a definition). Moreover, we denote by $E^c$
the complementary set of $E$, and by $1_E$ its characteristic function, i.e., $1_E(x) = 1$ if $x \in E$
else $0$ otherwise.

**Capacity.** Let $1 < p < +\infty$, and let $E \subseteq \mathbb{R}^N$. We set

$$c_p(E) := \inf \left\{ \int_{\mathbb{R}^2} |\nabla u|^p + |u|^p \, dx : u \in W^{1,p}(\mathbb{R}^2), u \geq 1 \text{ a.e. on } E \right\}.$$  

For the properties of capacity, and its relevance in the theory of Sobolev spaces, we refer the reader to [19].

We say that a property $P(x)$ holds $c_p$-quasi everywhere (abbreviated $c_p$-q.e.) on a set $E \subseteq \mathbb{R}^N$
if it holds for every $x \in E$ except a subset $N$ of $E$ such that $c_p(N) = 0$. 


If $A \subseteq \mathbb{R}^N$ is open, every function $u \in W^{1,p}(A)$ admits a quasicontinuous representative, i.e., a representative $\hat{u}$ such that for every $\varepsilon > 0$ there exists an open set $B_\varepsilon$ with $c_p(B_\varepsilon) < \varepsilon$ and $\hat{u}|_{A\setminus B_\varepsilon}$ is continuous. Throughout the paper, we will identify a Sobolev function with its quasicontinuous representative. Notice that for $p > N$, the continuous representative of $u$ (which exists by Sobolev Embedding Theorem) is precisely the quasicontinuous representative. We will use the following fact: if $u_n \to u$ strongly in $W^{1,p}(A)$, we have that up to a subsequence $u_n \to u$ $c_p$-q.e. on $A$.

The following lemma will be useful in Section 4 and in the Appendix (a different proof can be obtained using the arguments contained in [7, Lemma 5.1, Lemma 5.2]).

**Lemma 2.1.** Let $u \in C(\mathbb{R}^2)$, $K \subseteq \mathbb{R}^2$ connected, and let $c \in \mathbb{R}$. If $u(x) = c$ for $c_2$-q.e. $x \in K$, then $u(x) = c$ for every $x \in K$.

**Proof.** By assumption we have that there exists $N \subseteq K$ such that $c_2(N) = 0$ and $u(x) = c$ for every $x \in K \setminus N$. If for every $x \in N$ there exists $x_n \in K \setminus N$ such that $x_n \to x$, by continuity of $u$ we conclude that also $u(x) = c$ and the result follows.

By contradiction, let us assume that there exists $x \in N$ such that $x \notin \overline{K \setminus N}$. Then there exists $\bar{r} > 0$ such that $B(x, \bar{r}) \cap (K \setminus N) = \emptyset$ for $r < \bar{r}$. Since $c_2(N) = 0$, by [10] Section 4.7.2, Theorem 4 we have that $\mathcal{H}^\alpha(N) = 0$ for every $\alpha > 0$, and in particular $\mathcal{H}^1(N) = 0$. As a consequence, for every $0 < \varepsilon < \bar{r}$ we can find a covering $\{B(x_i, r_i)\}_{i \in \mathbb{N}}$ of $N$ such that $\sum_{i \in \mathbb{N}} r_i < \varepsilon$. Let $\mathcal{B} := \bigcup_i B(x_i, r_i)$ and $S := \{r \in ]0, \bar{r}[ : \partial B(x, r) \cap \mathcal{B} \neq \emptyset\}$. We have that $\text{meas}(S) < \varepsilon$, so that we can find $r < \bar{r}$ with $\partial B(x, r) \cap N = \emptyset$. Moreover, up to reducing $\varepsilon$, we can assume that $N \setminus B(x, r) \neq \emptyset$, because otherwise we would get that $N = \{x\}$ with $x$ isolated from the rest of $K$, against its connectedness.

Let us consider $$K_1 := K \cap \overline{B(x, r)} \quad \text{and} \quad K_2 := K \setminus B(x, r).$$

$K_1$ and $K_2$ are closed in the relative topology of $K$. By construction they are not empty, disjoint and such that $K = K_1 \cup K_2$. But this is against the fact that $K$ is connected, and the proof is concluded. \hfill $\Box$

**Hausdorff metric on compact sets and Hausdorff complementary topology.** Let $A$ be open and bounded in $\mathbb{R}^N$. We indicate the family of all compact subsets of $\overline{A}$ by $\mathcal{K}(\overline{A})$. $\mathcal{K}(\overline{A})$ can be endowed with the Hausdorff metric $d_H$ defined by

$$d_H(K_1, K_2) := \max\{\sup_{x \in K_1} \text{dist}(x, K_2), \sup_{y \in K_2} \text{dist}(y, K_1)\}$$

with the conventions $\text{dist}(x, \emptyset) = \text{diam}(A)$ and $\sup \emptyset = 0$, so that $d_H(\emptyset, K) = 0$ if $K = \emptyset$ and $d_H(\emptyset, K) = \text{diam}(A)$ if $K \neq \emptyset$. It turns out that $\mathcal{K}(\overline{A})$ endowed with the Hausdorff metric is a compact space (see e.g. [20]).

In order to treat the stability of Neumann problems under boundary variations (see Section 4), we will use the Hausdorff complementary topology on the family of open sets which is defined as follows. Let $(\Omega_n)_{n \in \mathbb{N}}$ be a sequence of open sets in $\mathbb{R}^N$. We say that $\Omega_n \to \Omega$ in the Hausdorff complementary topology if for every closed ball $B \subseteq \mathbb{R}^N$ we have

$$B \cap \Omega_n^c \to B \cap \Omega^c$$

in the Hausdorff metric.

**The Mosco convergence of Sobolev spaces.** In Section 4 we will refer to the notion of Mosco convergence of Sobolev spaces in connection with stability results for nonlinear Neumann problems. For the reader’s convenience, we recall here the definition.

Let $(\Omega_n)_{n \in \mathbb{N}}$ be a sequence of uniformly bounded open subsets of $\mathbb{R}^N$, and let $1 < p < +\infty$. For every $u_n \in W^{1,p}(\Omega_n)$, let us denote by $u_n 1_{\Omega_n}$ and by $\nabla u_n 1_{\Omega_n}$ the extension to zero outside $\Omega_n$ of $u_n$ and $\nabla u_n$ respectively.
If \( \Omega \) is a bounded open set in \( \mathbb{R}^N \), we say that \( W^{1,p}(\Omega_n) \) converges to \( W^{1,p}(\Omega) \) in the sense of Mosco if the following two conditions hold.

(M1) Mosco-limsup condition. For every \( u \in W^{1,p}(\Omega) \) there exists \( u_n \in W^{1,p}(\Omega_n) \) such that
\[
\nabla u_n 1_{\Omega_n} \rightharpoonup \nabla u 1_{\Omega} \quad \text{strongly in } L^p(\mathbb{R}^N, \mathbb{R}^N)
\]
and
\[
u_n 1_{\Omega_n} \rightarrow u 1_{\Omega} \quad \text{strongly in } L^p(\mathbb{R}^N).
\](M2) Mosco-limsinf condition. If \( n_k \) is a sequence of indices converging to +\( \infty \), \((u_k)_k \subseteq \mathbb{N}\) is a sequence such that \( u_k \in W^{1,p}(\Omega_{n_k}) \) for every \( k \), and \( u_k 1_{\Omega_{n_k}} \) converges weakly in \( L^p(\mathbb{R}^N) \) to a function \( \varphi \), while \( \nabla u_k 1_{\Omega_{n_k}} \) converges weakly in \( L^p(\mathbb{R}^N, \mathbb{R}^N) \) to a function \( \Phi \), then there exists \( u \in W^{1,p}(\Omega) \) such that \( \varphi = u 1_{\Omega} \) and \( \Phi = \nabla u 1_{\Omega} \).

Using a diagonal argument, we have that in order to establish (M1), it suffices to approximate functions belonging to a dense subset of \( W^{1,p}(\Omega) \). This fact will be used several times in Section 3.

3. The density result

This section is devoted to the proof of the density of \( W^{1,2} \) into \( W^{1,p} \) with \( 1 \leq p < 2 \) on a two-dimensional domain which satisfies a suitable structural assumption, for example if its complement has a countable number of connected components. Recall that the two-dimensional domain is not assumed to be regular (for example it may contain a crack), so that extension operators cannot be used.

First of all, we establish the density result at the level of the gradients (Theorem 3.3). The extension to the full result on Sobolev spaces (Theorem 3.8) is then obtained through a truncation argument.

The class of admissible domains we consider is given in the following definition.

Definition 3.1. (The class \( \mathcal{A}_p(\mathbb{R}^2) \) of admissible domains) Let \( 1 \leq p < 2 \), and let \( \Omega \subseteq \mathbb{R}^2 \) be open and bounded. Let \( \{K_i\}_{i \in I} \) be the family of the connected components of \( \Omega^c \). We say that \( \Omega \) belongs to the class \( \mathcal{A}_p(\mathbb{R}^2) \) of admissible domains if for every \( i \in I \) there exists \( x_i \in K_i \) such that setting \( E := \{x_i, i \in I\} \) we have
\[
\mathcal{H}^{2-p}(E) = 0.
\]

Notice that the class \( \mathcal{O}(\mathbb{R}^2) \) of two-dimensional domains such that their complements have at most \( l \) connected components (which is relevant for stability of nonlinear Neumann problems, see Section 1) is contained in \( \mathcal{A}_p(\mathbb{R}^2) \). Moreover \( \mathcal{A}_p(\mathbb{R}^2) \) contains domains \( \Omega \) such that \( \Omega^c \) has a countable number of connected components, or even an uncountable number provided that there exists a suitable selection \( E \) of \( \{K_i\}_{i \in I} \) with zero Hausdorff measure of order \( 2 - p \). We remark that condition (3.1) is not referred to the connected components \( K_i \) of \( \Omega^c \) but to a selection \( E \) of \( \{K_i\}_{i \in I} \): in particular it can be \( \text{meas}(K_i) > 0 \) (not only for the unbounded connected component).

The following lemmas will be useful in the proof of Theorem 3.5.

Lemma 3.2. Let \( A \subseteq \mathbb{R}^2 \) be open, and let \( u \in W^{1,q}(A) \) with \( q > 2 \). Then we have \( \text{meas}(u(E)) = 0 \) for every \( E \subseteq A \) such that \( \mathcal{H}^{q-2}(E) = 0 \) (in the case \( q = +\infty \) we mean \( \mathcal{H}^{1}(E) = 0 \)).

Proof. If \( q = +\infty \), the result follows because \( u \) is a locally Lipschitz function and \( \text{meas}(f(C)) = \mathcal{H}^1(f(C)) \leq L\mathcal{H}^1(C) \) for every \( L \)-Lipschitz function \( f \) and every set \( C \) (see [13] Theorem 1, Section 2.4.1)).

In the case \( 2 < q < +\infty \), we follow the approach that Marcus and Mizel [24] developed to deal with \( N \)-property of Sobolev transformations (see [20] for a description of the problem of \( N \)-property, and [20] Theorem 5.28]). By Sobolev Embedding Theorem \( u \) is a Hölder continuous function. Moreover, for any square \( Q_r \subseteq A \) of side \( r \) we have
\[
|u(x) - \bar{u}_{Q_r}| \leq C_q \|\nabla u\|_{L^q(Q_r \times \mathbb{R}^2)} r^{1-2/q},
\]
where \( \bar{u}_{Q_r} \) denotes the average of \( u \) on \( Q_r \), and \( C_q \) depends only on \( q \). From (3.2) we deduce that \( u(Q_r) \) is contained in an interval \( I_{Q_r} \) of length at most

\[
l_{Q_r} := 2C_q \| \nabla u \|_{L^q(Q_r, \mathbb{R}^2)} r^{1-2/q}.
\]

Let \( E \subseteq A \) be such that \( \mathcal{H}^{\frac{2}{q-1}}(E) = 0 \), and let us fix \( \varepsilon > 0 \) and \( \delta > 0 \). Since \( \mathcal{H}^{\frac{2}{q-1}}(E) = 0 \), we can find a covering \( F = \{Q_{r_i}(x_i)\}_{i \in \mathbb{N}} \) of \( E \) with \( Q_{r_i}(x_i) \subseteq A \),

\[
(3.3) \quad \sum_{i=0}^{+\infty} \frac{r_i^{q-2}}{r_i^q} < \varepsilon
\]

and such that

\[
l_i := 2C_q \| \nabla u \|_{L^q(Q_{r_i}(x_i), \mathbb{R}^2)} r_i^{1-2/q} < \delta.
\]

By Besicovitch Covering Theorem (see [19, Section 1.5.2, Theorem 2]) there exist \( m \) families \( F_1, F_2, \ldots, F_m \subseteq F \) of disjoint squares \( \{Q_{r_{ij}}(x_{ij})\}_{i \in \mathbb{N}} \) such that

\[
E \subseteq \bigcup_{j=1}^{m} \bigcup_{i=0}^{+\infty} Q_{r_{ij}}(x_{ij}). \tag{3.4}
\]

By Hölder inequality and by (3.3) we deduce that

\[
\sum_{j=1}^{m} \sum_{i=0}^{+\infty} l_{i,j} = 2C_q \sum_{j=1}^{m} \sum_{i=0}^{+\infty} \| \nabla u \|_{L^q(Q_{r_{ij}}(x_{ij}), \mathbb{R}^2)} r_i^{1-2/q}
\]

\[
\leq 2C_q \left( \sum_{j=1}^{m} \sum_{i=0}^{+\infty} \| \nabla u \|_{L^q(Q_{r_{ij}}(x_{ij}), \mathbb{R}^2)}^q \right)^{\frac{1}{q}} \left( \sum_{j=1}^{m} \sum_{i=0}^{+\infty} r_i^{q-2} \right)^{\frac{q-1}{q}}
\]

\[
\leq 2C_q m \| \nabla u \|_{L^q(A, \mathbb{R}^2)} \varepsilon \frac{q-1}{q},
\]

so that

\[
\mathcal{H}^1_\varepsilon(u(E)) \leq 2C_q m \| \nabla u \|_{L^q(A, \mathbb{R}^2)} \varepsilon \frac{q-1}{q},
\]

where \( \mathcal{H}^1_\varepsilon(E) \) denotes the \((1, \varepsilon)\)-Hausdorff pre-measure. Since \( \mathcal{H}^1(u(E)) = \lim_{\delta \to 0} \mathcal{H}^1_\varepsilon(u(E)) \), and \( \mathcal{H}^1(u(E)) = \text{meas}(u(E)) \), we conclude that

\[
\text{meas}(u(E)) \leq 2C_q m \| \nabla u \|_{L^q(A, \mathbb{R}^2)} \varepsilon \frac{q-1}{q}.
\]

Since \( \varepsilon \) is arbitrary, we deduce that \( \text{meas}(u(E)) = 0 \). \hfill \Box

**Lemma 3.3.** Let \( \phi \in W^{1,p}(\mathbb{R}^N) \cap C^0(\mathbb{R}^N) \) with \( p \in [1, +\infty] \). Let \( K \subseteq \mathbb{R}^N \) be such that \( \phi(K) \) is compact and \( \text{meas}(\phi(K)) = 0 \). Then there exists \( \phi_n \in W^{1,p}(\mathbb{R}^N) \cap C^0(\mathbb{R}^N) \) with

\[
(3.4) \quad \phi_n \to \phi \quad \text{strongly in } W^{1,p}(\mathbb{R}^N) \quad \text{if } 1 \leq p < +\infty,
\]

\[
(3.5) \quad (\phi_n, \nabla \phi_n) \rightharpoonup (\phi, \nabla \phi) \quad \text{weakly* in } L^\infty(\mathbb{R}^N, \mathbb{R}^{N+1}) \quad \text{if } p = +\infty,
\]

and such that \( \phi_n \) is locally constant on a neighborhood of \( K \), i.e., \( \nabla \phi_n = 0 \) a.e. on a neighborhood \( A_n \) of \( K \).

**Proof.** By assumption \( C := \phi(K) \) is compact and such that \( \text{meas}(C) = 0 \). Let us set

\[
C_n := \left\{ y \in \mathbb{R} : \text{dist}(y, C) \leq \frac{1}{n} \right\}
\]

and

\[
T_n(y) := \int_0^y 1_{\mathbb{R} \setminus C_n}(s) \, ds.
\]

Since \( \text{meas}(C_n) \to 0 \) as \( n \to +\infty \), we get that

\[
(3.6) \quad T_n \to I_d \quad \text{pointwise.}
\]
Moreover, $T_n$ is 1-Lipschitz, $T'_n = 0$ a.e. on $C_n$, and
\begin{equation}
T'_n(y) \to 1 \quad \text{for a.e. } y \in \mathbb{R}.
\end{equation}
Let us set
\begin{equation}
\phi_n := T_n \circ \phi.
\end{equation}
We have that $\phi_n \in W^{1,p}(\mathbb{R}^N) \cap C^0(\mathbb{R}^N)$, and by the Chain Rule Formula for Sobolev functions (see for instance [3, Theorem 3.99]) we get for a.e. $x \in \mathbb{R}^N$
\begin{equation}
\nabla \phi_n(x) = T'_n(\phi(x)) \nabla \phi(x)
\end{equation}
(recall that $\nabla \phi = 0$ a.e. on $\phi^{-1}(C)$ since $C$ has zero measure [3 Proposition 3.92]).

In view of (3.9), $\nabla \phi_n = 0$ on $A_n := \phi^{-1}(C_n)$ which is a neighborhood of $K$. Moreover, by (3.6) and (3.7), we have that (3.8) and (3.9) imply that
\begin{equation}
\phi_n \to \phi \quad \text{and} \quad \nabla \phi_n \to \nabla \phi \quad \text{a.e. on } \mathbb{R}^N.
\end{equation}
Since $|\phi_n| \leq |\phi|$ and $|\nabla \phi_n| \leq |\nabla \phi|$, we deduce that (3.1) and (3.5) hold.

The following lemma is very close in spirit to [3, Lemma 3.6]

**Lemma 3.4.** Let $\Omega \subseteq \mathbb{R}^2$ be open and bounded, and let $q \geq 2$. Let $\psi \in L^q(\Omega, \mathbb{R}^2)$ be such that
\begin{equation}
\int_\Omega \psi \cdot \nabla u \, dx = 0 \quad \text{for every } u \in W^{1,2}(\Omega).
\end{equation}
Then there exists $\phi \in W^{1,q}(\mathbb{R}^2)$ constant on the connected components of $\Omega^c$ (in the case $q = 2$ constant $c_2$-quasi everywhere) and such that
\begin{equation}
\nabla \phi = R\psi,
\end{equation}
where $R(a,b) := (-b,a)$ denotes a rotation of 90 degrees counterclockwise.

**Proof.** Let us denote by $K_i$, $i \in I$, the connected components of $\Omega^c$, and let $K_0$ be the unbounded one.

Since $\psi \in L^2(\Omega, \mathbb{R}^2)$, by Helmholtz decomposition of the space $L^2(\Omega, \mathbb{R}^2)$ (see [21 Theorem 1.1, Chapter III]), there exists $\psi_n \in C^\infty_c(\Omega, \mathbb{R}^2)$ with $\text{div } \psi_n = 0$ and
\begin{equation}
\psi_n \to \psi \quad \text{strongly in } L^2(\Omega, \mathbb{R}^2).
\end{equation}
By setting $\psi_n = 0$ outside $\Omega$, we can consider $\psi_n$ as defined on the entire $\mathbb{R}^2$. Let us consider $\varphi_n := R\psi_n$. Since $\mathbb{R}^2$ is simply connected, and $\varphi_n$ has zero-curl, we have that there exists $\phi_n \in C^\infty(\mathbb{R}^2)$ such that
\begin{equation}
\nabla \phi_n = R\psi_n.
\end{equation}
In particular $\nabla \phi_n = 0$ on a neighborhood $A^n$ of $\Omega^c$, so that for every $i \in I$ there exists $c^n_i \in \mathbb{R}$ such that
\begin{equation}
\phi_n = c^n_i \quad \text{on a neighborhood } A^n_i \text{ of } K_i.
\end{equation}
Since $\phi_n$ is well defined up to a constant, we can assume that $\phi_n = 0$ on $K_0$. Let $D$ be a disk centered at the origin and such that $\overline{\Omega} \subseteq D$. By (3.10) we deduce that there exists $\phi \in W^{1,2}_0(D)$ such that
\begin{equation}
\phi_n \to \phi \quad \text{strongly in } W^{1,2}_0(D).
\end{equation}
We have that
\begin{equation}
\nabla \phi = R\psi \in L^6(\Omega, \mathbb{R}^2).
\end{equation}
We deduce that $\phi \in W^{1,q}_0(D)$, and in particular $\phi \in W^{1,q}(\mathbb{R}^2)$. Since up to a subsequence $\phi_n \to \phi$ $c_2$-q.e., from (3.11) we deduce that there exists $c_i \in \mathbb{R}$, $i \in I$, such that
\begin{equation}
\phi = c_i \quad c_2\text{-q.e. on } K_i.
\end{equation}

In the case $q > 2$, we have that $\phi$ is Hölder continuous by Sobolev Embedding Theorem. So by Lemma 24, we get that (3.12) implies that $\phi$ is constant on $K_i$, and the proof is concluded. \qed

The following theorem contains the density result for the gradients.
**Theorem 3.5.** Let \( 1 \leq p < 2 \), and let \( \Omega \in \mathcal{A}_p(\mathbb{R}^2) \) be an admissible domain. Then for every \( u \in W^{1,p}(\Omega) \) there exists \( (u_n)_{n \in \mathbb{N}} \) sequence in \( W^{1,2}(\Omega) \) such that
\[
\nabla u_n \rightharpoonup \nabla u \quad \text{strongly in } L^p(\Omega, \mathbb{R}^2).
\]

**Proof.** Let \( K_i, i \in I, \) be the connected components of \( \Omega^c \). Let us consider
\[
H := \{ \nabla v : v \in W^{1,2}(\Omega) \} \subseteq L^p(\Omega, \mathbb{R}^2).
\]

In order to prove the density result, it suffices to check that for every \( u \in W^{1,p}(\Omega) \) we have
\[
\nabla u \in \overline{H},
\]
where \( \overline{H} \) denotes the closure of \( H \) in the \( L^p \)-norm. Since
\[
\overline{H} = (H^\perp)^\perp,
\]
where \( (\cdot)^\perp \) denotes the orthogonal space in the sense of Banach spaces, we have to check that
\[
\nabla u \in (H^\perp)^\perp.
\]

Our strategy to prove (3.14) is the following. Firstly we characterize the functions \( \psi \in H^\perp \), and then we prove that for every \( u \in W^{1,p}(\Omega) \) we have the orthogonality condition
\[
\int_{\Omega} \psi \cdot \nabla u \, dx = 0.
\]

**Step 1: Characterization of \( H^\perp \).** Let \( \psi \in H^\perp \subseteq L^{p'}(\Omega, \mathbb{R}^2) \), where \( p' > 2 \) is the conjugate exponent of \( p \) \( (p' = \frac{p}{p-1} \text{ if } p \in ]1, 2[, \ p' = +\infty \text{ if } p = 1) \). By definition of \( H^\perp \), we have that for every \( v \in W^{1,2}(\Omega) \)
\[
\int_{\Omega} \psi \cdot \nabla v \, dx = 0.
\]

By Lemma 3.3, we deduce that there exists \( \phi \in W^{1,p'}(\mathbb{R}^2) \) with \( \nabla \phi = R\psi \) \((R(a,b) := (-b,a) \text{ is the rotation of } 90 \text{ degrees counterclockwise})\), and such that for every \( i \in I \)
\[
\phi = c_i \quad \text{on } K_i
\]
for suitable \( c_i \in \mathbb{R} \).

**Step 2: Checking the orthogonality condition.** In order to conclude the proof, it suffices to check that (3.16) holds for every \( u \in W^{1,p}(\Omega) \). By Step 1, we need to check that
\[
\int_{\Omega} \psi \cdot \nabla u \, dx = -\int_{\Omega} R\nabla \phi \cdot \nabla u \, dx = 0,
\]
where \( \phi \in W^{1,p'}(\mathbb{R}^2) \) satisfies (3.16) for some \( c_i \in \mathbb{R}, i \in I \).

Notice that \( \phi(\Omega^c) \) is compact. Moreover, since \( \Omega \in \mathcal{A}_p(\mathbb{R}^2) \), there exists a selection \( E \) of the connected components \( K_i \) of \( \Omega^c \) such that
\[
\mathcal{H}^{p-1}_{p'-1}(E) = \mathcal{H}^{2-p}(E) = 0 \quad \text{if } 1 < p < 2
\]
and
\[
\mathcal{H}^1(E) = 0 \quad \text{if } p = 1.
\]

By (3.16) we get \( \phi(\Omega^c) = \phi(E) \), and by Lemma 3.2 we have that \( \text{meas}(\phi(\Omega^c)) = \text{meas} (\phi(E)) = 0 \). Applying Lemma 3.3, there exists \( \phi_n \in W^{1,p'}(\mathbb{R}^2) \) such that
\[
\phi_n \rightharpoonup \phi \quad \text{strongly in } W^{1,p'}(\mathbb{R}^2) \quad \text{if } 1 < p < 2,
\]
and
\[
\phi_n \rightharpoonup \phi \quad \text{weakly in } L^\infty(\mathbb{R}^2, \mathbb{R}^3) \quad \text{if } p = 1,
\]
and
\[
\nabla \phi_n \rightarrow 0 \quad \text{on a neighborhood } A_n \text{ of } \Omega^c.
\]
Notice that $R\nabla \phi_n$ is divergence-free. Up to reducing $A_n$, we can assume that $\Omega \setminus A_n$ is regular, and that the support of $R\nabla \phi_n$ is contained in $\Omega \setminus A_n$. Then we have
\[
\int_{\Omega} R\nabla \phi \cdot \nabla u \, dx = \lim_{n \to +\infty} \int_{\Omega} R\nabla \phi_n \cdot \nabla u \, dx = \lim_{n \to +\infty} \int_{\Omega \setminus A_n} R\nabla \phi_n \cdot \nabla u \, dx,
\]
and integrating by parts we deduce that
\[
\lim_{n \to +\infty} \int_{\Omega \setminus A_n} R\nabla \phi_n \cdot \nabla u \, dx = \lim_{n \to +\infty} \int_{\Omega \setminus A_n} \text{div} (R\nabla \phi_n) \, u \, dx = 0,
\]
so that (3.17) is proved, and the proof is concluded. \hfill \Box

**Remark 3.6.** As mentioned in the Introduction, the density result given by Theorem 3.5 (and the similar result for Sobolev spaces Theorem 3.8) is useful to establish a link between stability results for linear and nonlinear Neumann problems. Since stability results usually hold under the assumption of a uniform bound on the number of the connected components of the complements of the varying domains (see Section 4.1), the case $\Omega^c$ has a finite number of connected components is the relevant one for the applications.

In this case, the existence of the function $\phi_n$ satisfying conditions (3.18) and (3.20) in Step 2 of the proof of Theorem 3.5 can be established more directly without using the approximation Lemma 3.3 as follows (the case $p = 1$ is usually not considered in the study of nonlinear Neumann problems in view of a lack of compactness of $W^{1,1}$).

Let $K_0, K_1, \ldots, K_m$ be the connected components of $\Omega^c$, where $K_0$ is the unbounded one. Let us consider $\xi_0 \in C^\infty(\mathbb{R}^2)$ and $\xi_i \in C^\infty(\mathbb{R}^2), i = 1, \ldots, m$ such that $\xi_0 = 1$ on a neighborhood of $K_0, \xi_i = 1$ on a neighborhood of $K_i$, and
\[
\text{supp}(\xi_k) \cap \text{supp}(\xi_k) = \emptyset \quad \text{for } h \neq k.
\]
By [2, Theorem 9.1.3] for every $i = 0, 1, \ldots, m$ we can find $\phi^i_n \in C^\infty(\mathbb{R}^2)$ with
\[
\phi^i_n = c_i \quad \text{on a neighborhood of } K_i
\]
and such that
\[
\phi^i_n \to \phi \quad \text{strongly in } W^{1,p'}(\mathbb{R}^2).
\]
Setting
\[
\phi_n := \left(1 - \sum_{i=0}^{m} \xi_i\right) \phi + \sum_{i=0}^{m} \xi_i \phi^i_n,
\]
we get that (3.18) and (3.20) hold.

**Remark 3.7.** In the proof of Theorem 3.5 we used the assumption that $\Omega$ belongs to the class $A_p(\mathbb{R}^2)$ in order to apply the approximation Lemma 3.3 and recover the functions $\phi_n$ satisfying (3.18), (3.20) and (3.21). Lemma 3.3 requires that $\text{meas}(\phi(\Omega^c)) = 0$, and for $\Omega \in A_p(\mathbb{R}^2)$ every function $\phi \in W^{1,p'}(\mathbb{R}^2)$ constant on the connected components of $\Omega^c$ is such that $\text{meas}(\phi(\Omega^c)) = 0$. In particular this is the case for the functions we need to approximate, that is $\phi \in W^{1,p'}(\mathbb{R}^2)$ such that $R\nabla \phi \in H^{-1}$.

We do not know if for a general $\Omega$ we can have $\text{meas}(\phi(\Omega^c)) = 0$ for any $\phi \in W^{1,p'}(\mathbb{R}^2)$ determining an element of $H^{-1}$. For such a $\phi$, by Step 1 (and in view of the proof of Lemma 3.3), we have that there exists a sequence of smooth functions $\phi_n$ such that
\[
\nabla \phi_n = 0 \quad \text{on a neighborhood of } \Omega^c
\]
and
\[
\phi_n \to \phi \quad \text{strongly in } W^{1,2}(\mathbb{R}^2).
\]
In particular $\phi_n(\Omega^c)$ is finite so that $\text{meas}(\phi_n(\Omega^c)) = 0$. If this always implies that in the limit $\text{meas}(\phi(\Omega^c)) = 0$, the fact that $\phi$ is energetically more regular than $\phi_n$, i.e., $\phi \in W^{1,p'}(\mathbb{R}^2)$, plays an essential role.

We can consider indeed the following example which shows a sequence $(\phi_n)_{n \in \mathbb{N}}$ of smooth functions satisfying (3.21) and (3.22) but with $\phi \in W^{1,2}(\mathbb{R}^2) \cap C(\mathbb{R}^2)$ and such that $\phi(\Omega^c)$ is the
interval $[-1, 1]$. Moreover $\Omega^c$ can be chosen such that its connected components admit a selection $E$ with dimension zero, i.e., $\mathcal{H}^\alpha (E) = 0$ for every $\alpha > 0$, so that $\Omega \in \mathcal{A}_p(\mathbb{R}^2)$. This example heavily relies on a construction proposed by Malý and Martio \cite{Malý-Martio91} in connection with the $N$-property of Sobolev transformations.

Let us consider the square $Q := [-2, 2] \times [-2, 2]$ in $\mathbb{R}^2$, $J := \{(t, 0) : -1 \leq t \leq 1\}$, and $\alpha_n \searrow 0$. Since a point has $c_2$-capacity zero, there are functions $u_m \in C^\infty (\mathbb{R}^2)$ such that

$$u_m \to 0 \text{ strongly in } W^{1,2}(\mathbb{R}^2)$$

and such that $0 \leq u_m \leq 1$, $0 \in \text{int}\{u_m = 1\}$, and $u_m = 0$ outside the ball $B(0, 1)$. Let $z_1, z_2 \in J$ and $r_0 > 0$ be such that the balls $B(z_1, r_0)$ and $B(z_2, r_0)$ are disjoint. We set

$$g_m(x) := \frac{1}{2} u_m \left( \frac{x - z_1}{r_0} \right) - \frac{1}{2} u_m \left( \frac{x - z_2}{r_0} \right).$$

The functions $\phi_n \in C^\infty (\mathbb{R}^2)$ are constructed as follows. Let $\phi_0$ be the constant function equal to 0. If $n \geq 1$, let us divide the interval $I := [-1, 1]$ in $n$ intervals $I^n_i$ of length $2/n$: we can find points $x^n_i \in J$ and a radius $r_n$ so small that $nr_n^\alpha \to 0$ and $\phi_{n-1}$ maps $B(x^n_i, r_n)$ to the middle point of $I^n_i$. Let $B_n := \bigcup_{i=1}^n B(x^n_i, r_n)$,

$$h_{m,n}(x) := \begin{cases} 2^{-n+1} g_m \left( \frac{x-x^n_i}{r_n} \right) & \text{if } |x-x^n_i| \leq r_n \text{ for some } i \\ 0 & \text{otherwise,} \end{cases}$$

and let $m_n$ be such that

$$\|h_{m_n,n}\|_{W^{1,2}(\mathbb{R}^2)} \leq 2^{-n}.$$

We set

$$\phi_n := \phi_{n-1} + h_{m_n,n},$$

and we denote by $\phi$ the strong limit in $W^{1,2}(\mathbb{R}^2)$ of $(\phi_n)_{n \in \mathbb{N}}$, which is by construction a Cauchy sequence. Notice that $\phi \in W^{1,2}(\mathbb{R}^2) \cap C(\mathbb{R}^2)$, and that the convergence is also uniform.

Let $\Omega := Q \setminus \bigcap_{n \in \mathbb{N}} B_n$. We have that $\Omega^c = Q^c \cup \bigcap_{n \in \mathbb{N}} B_n$. Since $nr_n^\alpha \to 0$, we have that $\mathcal{H}^\alpha (\cap_{n \in \mathbb{N}} B_n) = 0$ for every $\alpha > 0$. As a consequence, the connected components of $\Omega^c$ admit a selection $E$ such that $\mathcal{H}^\alpha (E) = 0$ for every $\alpha > 0$. In particular $\Omega \in \mathcal{A}_p(\mathbb{R}^2)$.

By construction we have that $\phi_n$ is constant on a neighborhood of $\Omega^c$ but, since $\phi_n \to \phi$ uniformly, it is easy to see that $\phi(\Omega^c) = [-1, 1]$. Clearly $\phi$ cannot belong to $W^{1,q}(\mathbb{R}^2)$ for some $q > 2$, because otherwise its Hölder continuity would imply $\text{meas} (\phi(\Omega^c)) = 0$.

We are now in a position to prove the main density result of this paper.

**Theorem 3.8.** Let $1 \leq p < 2$, and let $\Omega \in \mathcal{A}_p(\mathbb{R}^2)$ be an admissible domain. Then $W^{1,2}(\Omega)$ is dense in $W^{1,p}(\Omega)$.

**Proof.** The main ingredients in the proof are Theorems \ref{theo:completeness} and a truncation argument. It is not restrictive to assume that $\Omega$ is connected, because we can work on each connected component.

Let $u \in W^{1,p}(\Omega)$. The density result will be proved if we show that for every $\varepsilon > 0$ we can find $(u_n)_{n \in \mathbb{N}}$ sequence in $W^{1,2}(\Omega)$ such that

\begin{equation}
\limsup_{n \to +\infty} \|u_n - u\|_{W^{1,p}(\Omega)} \leq \varepsilon,
\end{equation}

where $e_\varepsilon \to 0$ as $\varepsilon \to 0$.

It is not restrictive to assume that

$$u \in W^{1,p}(\Omega) \cap L^\infty (\Omega).$$

In fact, if $k > 0$ and

$$T_k(u) := \min \{ \max \{ u - k \}, k \},$$

we have $T_k(u) \in W^{1,p}(\Omega) \cap L^\infty (\Omega)$ and $T_k(u) \rightarrow u$ strongly in $W^{1,p}(\Omega)$ as $k \to +\infty$. Then if \eqref{eq:limsup} holds for $T_k(u)$, by a diagonal argument it also holds for $u$.

Let $A \subset \subset \Omega$, $A$ regular and connected, such that

\begin{equation}
\| \nabla u \|_{L^p(\Omega \setminus A)} + \| u \|_{L^p(\Omega \setminus A)} < \varepsilon.
\end{equation}
By Theorem 3.20 there exists \( v_n \in W^{1,2}(\Omega) \) such that
\[
\nabla v_n \to \nabla u \quad \text{strongly in } L^p(\Omega, \mathbb{R}^2).
\]
We claim that, up to adding a constant to \( v_n \), we can assume that
\[
v_n \to u \quad \text{strongly in } W^{1,p}(A).
\]
Let us set
\[
u_n := \min\{\max\{v_n, -\|u\|_\infty\}, \|u\|_\infty\}.
\]
Notice that \( u_n \in W^{1,2}(\Omega) \),
\[
u_n \to u \quad \text{strongly in } W^{1,p}(A),
\]
and that
\[
|\nabla u_n| \leq |\nabla v_n| \quad \text{a.e. in } \Omega.
\]
In view of (3.28), (3.29), (3.25), (3.27), and (3.24), we deduce that
\[
\limsup_{n \to +\infty} \|u_n - u\|_{W^{1,p}(\Omega)}^p \leq \limsup_{n \to +\infty} \|u_n - u\|_{W^{1,p}(A)}^p + \limsup_{n \to +\infty} \|u_n - u\|_{W^{1,p}(\Omega \setminus A)}^p
\]
\[
= \limsup_{n \to +\infty} \|u_n - u\|_{W^{1,p}(\Omega)}^p \leq \limsup_{n \to +\infty} 2^{p-1} \left( \int_{\Omega \setminus A} |\nabla u_n|^p + |\nabla u|^p + |u_n|^p + |u|^p \, dx \right)
\]
\[
\leq 2^p (\|\nabla u\|_{L^p(\Omega \setminus A)}^p + \|u\|_{L^p(\Omega \setminus A)}^p) \leq 2^p \varepsilon
\]
so that (3.26) is proved.

In order to complete the proof, let us check that claim (3.26) holds. If
\[
c_n := \frac{1}{|A|} \int_A v_n \, dx,
\]
since \( A \) is regular, by Poincaré inequality we have
\[
v_n = v - c_n \quad \text{is bounded in } W^{1,p}(A).
\]
Moreover, by the compact embedding of \( W^{1,p}(A) \) in \( L^p(A) \), there exists \( \tilde{v} \in L^p(A) \) such that up to a subsequence
\[
v_n \to \tilde{v} \quad \text{strongly in } L^p(A).
\]
Since \( \nabla v_n = \nabla u_n \) on \( A \), and in view of (3.25), we get that \( \nabla \tilde{v} = \nabla u \) in the sense of distributions on \( A \). We deduce that \( \tilde{v} \in W^{1,p}(A) \),
\[
\tilde{v}_n \to \tilde{v} \quad \text{strongly in } W^{1,p}(A),
\]
and since \( A \) is connected
\[
\tilde{v} = u + c_A
\]
for some constant \( c_A \in \mathbb{R} \). If we set \( \hat{v}_n := v_n - c_n - c_A \) we get
\[
\hat{v}_n \to u \quad \text{strongly in } W^{1,p}(A),
\]
so that claim (3.26) is proved.

**Remark 3.9.** *(The case \( \Omega \) unbounded)* The density of \( W^{1,2}(\Omega) \) into \( W^{1,p}(\Omega) \) when \( 1 \leq p < 2 \) holds also in the case \( \Omega \) is unbounded but there exists \( r_n \to +\infty \) with \( \Omega_n := \Omega \cap B(0, r_n) \in A_p(\mathbb{R}^2) \). In fact, if \( u \in W^{1,p}(\Omega) \), we have \( u \in W^{1,p}(\Omega_n) \) so that there exists \( v_{k_n} \in W^{1,2}(\Omega_n) \) with \( v_{k_n} \to u \) strongly in \( W^{1,p}(\Omega_n) \) as \( k \to +\infty \). If \( \chi_n \) is \( C^\infty \) function with \( 0 \leq \chi_n \leq 1 \), \( \chi_n = 1 \) on \( B(0, r_n/2) \) and \( \chi_n = 0 \) outside \( B(0, r_n) \), in order to conclude it suffices to choose \( u_n := v_{k_n} \chi_n \in W^{1,2}(\Omega) \) for \( k_n \) sufficiently large.
4. Applications

In this section, we give some applications of Theorem 3.8 to stability under boundary variations of nonlinear Neumann problems, and to the optimal cutting of a membrane.

Since we work on domains which are not assumed to be regular (for example they may contain cracks), we will use Deny-Lions spaces. They are defined as follows. Let \( \Omega \) be an open subset of \( \mathbb{R}^N \), \( p \in [1, \infty] \), and \( b \in L^\infty(\mathbb{R}^N) \) with \( b \geq 0 \). Let us set

\[
L_b^{1,p}(\Omega) := \{ u \in L^p_{\text{loc}}(\Omega) : \nabla u \in L^p(\Omega, \mathbb{R}^N), \int_\Omega |u|^{p} b \, dx < +\infty \}.
\]

We say that \( u \mathcal{R}_b v \) if

\[
\int_\Omega (|\nabla u - \nabla v|^p + b|u - v|^p) \, dx = 0,
\]

and we set

\[
L_b^{1,p}(\Omega) := \frac{L_b^{1,p}(\Omega)}{\mathcal{R}_b}
\]

endowed with the norm \( \|u\| := \|\nabla u\|_{L^p(\Omega, \mathbb{R}^N)} + (\int_\Omega |u|^{p} b \, dx)^{1/p} \). \( L_b^{1,p}(\Omega) \) is the Deny-Lions space of exponent \( p \) and weight \( b \). In the case \( b \equiv 0 \), it is usually denoted by \( L^1(\Omega) \).

Notice that \( W^{1,p}(\Omega) \subseteq L_b^{1,p}(\Omega) \). In the case \( b \geq c > 0 \) and \( \Omega \) is Lipschitz, we have that equality holds, while if \( b \) vanishes on subsets with positive measure or \( \Omega \) is irregular, the inclusion can be strict (see for example [29] Section 2.7). Moreover \( W^{1,p}(\Omega) \) is always dense in \( L_b^{1,p}(\Omega) \), as one can check by truncation. As a consequence, in view of Theorem 3.8 we have the following density result.

**Proposition 4.1.** Let \( \Omega \in \mathcal{A}_p(\mathbb{R}^2) \) be an admissible domain (see Definition 3.1), and let \( b \in L^\infty(\mathbb{R}^2) \) such that \( b \geq 0 \). Then \( W^{1,2}(\Omega) \) is dense in \( L_b^{1,p}(\Omega) \) for \( 1 \leq p < 2 \).

Let

\[
\mathcal{O}_l(\mathbb{R}^2) := \{ A \subseteq \mathbb{R}^2 \text{ open} : \mathbb{R}^2 \setminus A \text{ has at most } l \text{ connected components} \}.
\]

For every \( u \in L_b^{1,p}(\Omega) \), we denote by \( \nabla u 1_{\Omega} \) and \( u 1_{\Omega} \) the extension to zero outside \( \Omega \) of \( \nabla u \) and \( u \) respectively. We will use the following proposition due to Bucur and Varchon (see [8] and [9, Theorem 4.1, Remark 5.2]), which is a sort of Mosco limsup condition (see Section 2) for the spaces \( L_b^{1,2} \).

**Proposition 4.2.** Let \( \Omega_n \) be a sequence in \( \mathcal{O}_l(\mathbb{R}^2) \) converging to \( \Omega \) in the Hausdorff complementary topology (see Section 2) and such that

\[
\text{meas}(\Omega_n \cap \{ b > 0 \}) \to \text{meas}(\Omega \cap \{ b > 0 \}).
\]

Then for every \( u \in L_b^{1,2}(\Omega) \) there exists \( u_n \in L_b^{1,2}(\Omega_n) \) such that

\[
\nabla u_n 1_{\Omega_n} \to \nabla u 1_{\Omega} \quad \text{strongly in } L^2(\mathbb{R}^2, \mathbb{R}^2)
\]

and

\[
u_n 1_{\Omega_n} \to u 1_{\Omega} \quad \text{strongly in } L^2(\mathbb{R}^2),
\]

where \( L^2_b(\mathbb{R}^2) \) denotes the \( L^2 \)-space on \( \mathbb{R}^2 \) with weight \( b \).

Propositions 4.1 and 4.2 will be our main tools in dealing with stability of nonlinear Neumann problems and with the optimal cutting of a membrane.

4.1. Stability of nonlinear Neumann problems under boundary variations. Let \( p \in ]1, +\infty[ \), and let \( A : \mathbb{R}^2 \times \mathbb{R}^2 \to \mathbb{R}^2 \) and \( B : \mathbb{R}^2 \times \mathbb{R} \to \mathbb{R} \) be two Carathéodory functions such that the following conditions hold: there exist \( \alpha \in L^{p'}(\mathbb{R}^2) \) \( (p' := \frac{p}{p-1}) \), \( \beta \in L^1(\mathbb{R}^2) \), \( 0 < c_1 \leq c_2 \) such that for almost every \( x \in \mathbb{R}^2 \) and for every \( \xi, \xi_1, \xi_2 \in \mathbb{R}^2 \) with \( \xi_1 \neq \xi_2 \)

\[
(A(x, \xi_1) - A(x, \xi_2))(\xi_1 - \xi_2) > 0,
\]

and

\[
|A(x, \xi)| \leq \alpha(x) + c_2|\xi|^{p-1},
\]
(4.5) \[ A(x, \xi) \cdot \xi \geq \beta(x) + c_1|\xi|^p. \]

We assume that \( B \) satisfies (4.3), (4.4) and (4.5) for almost every \( x \in \mathbb{R}^2 \), and for all \( \xi, \xi_1, \xi_2 \in \mathbb{R} \), with \( \xi_1 \neq \xi_2 \).

Let \( \Omega \) be a bounded open subset of \( \mathbb{R}^2 \). We are interested in the stability under boundary variations of \( \Omega \) of the elliptic equation

\[
\begin{cases}
-\text{div} A(x, \nabla u) + B(x, u) = 0 & \text{in } \Omega, \\
A(x, \nabla u) \cdot \nu = 0 & \text{on } \partial \Omega,
\end{cases}
\]

where \( \nu \) denotes the outer normal to \( \partial \Omega \). Since we do not assume any regularity on \( A, B \) and on the boundary of \( \Omega \), we intend (4.6) in the usual weak sense of Sobolev spaces. More precisely by

\[
\phi \in W^{1,p}(\Omega) \quad \text{such that} \quad \int_{\Omega} [A(x, \nabla u) \nabla \varphi + B(x, u) \varphi] \, dx = 0.
\]

Existence and uniqueness of a solution to (4.6) follow by well known results on nonlinear elliptic equations with strictly monotone operators (see for instance [22]).

Let \( (\Omega_n)_{n \in \mathbb{N}} \) be a sequence of uniformly bounded open sets in \( \mathbb{R}^2 \). We say that \( \Omega \) is stable for the Neumann problems (4.6) along the sequence \( (\Omega_n)_{n \in \mathbb{N}} \) if

\[
u_{\Omega_n} \rightarrow \nu_{\Omega} \quad \text{strongly in } L^p(\mathbb{R}^2)
\]

and

\[
\nabla u_{\Omega_n} \rightarrow \nabla u_{\Omega} \quad \text{strongly in } L^p(\mathbb{R}^2, \mathbb{R}^2).
\]

Dal Maso, Ebobisse and Ponsiglione [13] Theorem 2.3] proved that \( \Omega \) is stable for problem (4.6) along \( (\Omega_n)_{n \in \mathbb{N}} \) for every admissible \( A \) and \( B \) if and only if the space \( W^{1,p}(\Omega_n) \) converges in the sense of Mosco to \( W^{1,p}(\Omega) \) (see Section 2 for a definition).

If \( \Omega_n \) is in the class \( \mathcal{O}(\mathbb{R}^2) \) defined in (4.2), Bucur and Varchon [8] proved that if \( \Omega_n \rightarrow \Omega \) in the Hausdorff complementary topology (see Section 2 for a definition) then \( W^{1,2}(\Omega_n) \) converges in the sense of Mosco to \( W^{1,2}(\Omega) \) if and only if \( \text{meas}(\Omega_n) \rightarrow \text{meas}(\Omega) \).

Dal Maso, Ebobisse and Ponsiglione [13] extend this result to the case \( 1 < p < 2 \) using a technique of nonlinear harmonic conjugates, and they prove that in the case \( p > 2 \) the result is in general false.

In the following proposition, using Theorem 3.8 we prove that the result of [13] can be deduced directly by that of [8].

**Proposition 4.3.** Let \( (\Omega_n)_{n \in \mathbb{N}} \) be a sequence of uniformly bounded sets in \( \mathcal{O}(\mathbb{R}^2) \) such that \( \Omega_n \) converges to \( \Omega \) in the Hausdorff complementary topology, and \( 1 < p < 2 \). Then \( W^{1,p}(\Omega_n) \) converges in the sense of Mosco to \( W^{1,p}(\Omega) \) (and hence problems (4.6) are stable) if and only if

\[
\text{meas}(\Omega_n) \rightarrow \text{meas}(\Omega).
\]

**Proof.** Let us assume that the Mosco convergence holds. Let \( \xi \in \mathbb{R}^2 \) with \( |\xi| = 1 \). Let us consider \( u \in W^{1,p}(\Omega) \) such that \( u(x) := \xi \cdot x \). By (M1)-condition, there exists \( u_n \in W^{1,p}(\Omega_n) \) such that

\[
\nabla u_{\Omega_n} \rightarrow \nabla u_{\Omega} \quad \text{strongly in } L^p(\mathbb{R}^2, \mathbb{R}^2).
\]

Since \( |\nabla u_{\Omega_n} - \nabla u_{\Omega}| = 1 \) a.e. on \( \Omega \setminus \Omega_n \), we get

\[
\limsup_{n \to +\infty} \text{meas}(\Omega \setminus \Omega_n) \leq \lim_{n \to +\infty} \int_{\mathbb{R}^2} |\nabla u_{\Omega_n} - \nabla u_{\Omega}|^p \, dx = 0.
\]

Let us consider \( u_n \in W^{1,p}(\Omega_n) \) such that \( u_n(x) = \xi \cdot x \). By (M2)-condition, up to a subsequence we have that there exists \( u \in W^{1,p}(\Omega) \) such that

\[
\nabla u_{\Omega_n} \rightarrow \nabla u \quad \text{weakly in } L^p(\mathbb{R}^2, \mathbb{R}^2).
\]
Then, if \( D \) is a disk containing \( \Omega_n \) for every \( n \) we get
\[
\xi \lim_{n \to +\infty} \text{meas}(\Omega_n \setminus \Omega) = \lim_{n \to +\infty} \int_{\R^2} \nabla u_n 1_{\Omega_n} 1_{D \setminus \Omega} \, dx = \int_{\R^2} \nabla u 1_{\Omega} 1_{D \setminus \Omega} \, dx = 0.
\]
Combining (4.8) and (4.9), we get that (4.7) holds.

On the contrary, let us assume that (4.7) holds, and let us prove the Mosco convergence of \( W^{1,p}(\Omega_n) \) to \( W^{1,p}(\Omega) \).

Concerning condition (M2), let \( u_k \in W^{1,p}(\Omega_{n_k}) \) be such that
\[
\nabla u_k 1_{\Omega_{n_k}} \rightharpoonup \Phi \quad \text{weakly in } L^p(\R^2, \R^2)
\]
and
\[
u_k \Omega_{n_k} \to \varphi \quad \text{weakly in } L^p(\R^2)
\]
for some \( \Phi \in L^p(\R^2, \R^2) \) and \( \varphi \in L^p(\R^2) \). Clearly, since \( \Omega_n \) converges to \( \Omega \) in the Hausdorff complementary topology, we have that \( \Phi = \nabla \varphi \) on \( \Omega \), so that \( u := (\varphi)_{|\Omega} \in W^{1,p}(\Omega) \). In order to conclude that (M2) holds, we have to prove that \( \Phi = \nabla u 1_{\Omega} \) and \( \varphi = u 1_{\Omega} \). Since \( \Omega_{n_k} \to \Omega \) in the Hausdorff complementary topology and \( \text{meas}(\Omega_n) \to \text{meas}(\Omega) \), we have
\[
1_{\Omega_{n_k}} \rightharpoonup 1_{\Omega} \quad \text{strongly in } L^1(\R^2).
\]
Then for all \( \eta \in C_c^\infty(\R^2, \R^2) \) we deduce
\[
\int_{\R^2} \Phi \cdot \eta \, dx = \lim_{k \to +\infty} \int_{\R^2} |\nabla u_k 1_{\Omega_{n_k}}| \cdot [\eta 1_{\Omega_{n_k}}] \, dx = \lim_{k \to +\infty} \int_{\R^2} |\nabla u 1_{\Omega_{n_k}}| \cdot [\eta 1_{\Omega_{n_k}}] \, dx
\]
which is equal to
\[
\int_{\R^2} \Phi \cdot \eta 1_{\Omega} \, dx = \int_{\R^2} \Phi 1_{\Omega} \cdot \eta \, dx = \int_{\R^2} \nabla u 1_{\Omega} \cdot \eta \, dx
\]
so that \( \Phi = \nabla u 1_{\Omega} \). Similarly we can prove that \( \varphi = u 1_{\Omega} \).

Let us now consider the following nonlinear Neumann problem
\[
\begin{cases}
-\text{div} A(x, \nabla u) + b(x)|u|^{p-2}u = h & \text{in } \Omega, \\
A(x, \nabla u) \cdot \nu = 0 & \text{on } \partial \Omega,
\end{cases}
\]
where \( A \) is a Carathéodory function satisfying conditions (4.8), (4.9), (4.10), \( A(x, 0) = 0 \) for a.e. \( x \in \R^2 \), \( b \in L^\infty(\R^2) \) and \( b \geq 0 \). In order to guarantee the solvability of (4.10), we assume moreover that \( h = bf + g \) with \( f, g \in L^p(\R^2) \), supp \( g \subseteq \Omega \), and \( \int_C g \, dx = 0 \) for every connected component \( C \) of \( \Omega \). We are interested in problem (4.10) because it introduces some degeneracy with respect to problem (1.10) as \( b \) can vanish on regions of \( \Omega \) with positive measure.

By a solution of (4.10) we mean a function \( u_\Omega \in L_b^{1,p}(\Omega) \) (or more precisely an equivalence class, see (1.14) for a definition) such that for every \( \varphi \in L_b^{1,p}(\Omega) \)
\[
\int_{\Omega} [A(x, \nabla u_\Omega) \cdot \nabla \varphi + b(x)|u_\Omega|^{p-2}u_\Omega \varphi] \, dx = \int h \varphi \, dx.
\]
Notice that the integrals appearing in the weak formulation of (4.10) are well defined: in particular notice that, if \( U \) is a regular open set such that supp \( g \subseteq U \subseteq \Omega \), and \( \bar{\varphi} \) denotes the average of \( \varphi \) on \( U \), by Hölder and Poincaré inequalities we get
\[
\left| \int_{\Omega} g \varphi \, dx \right| = \left| \int_U g \varphi \, dx \right| = \left| \int_U g (\varphi - \bar{\varphi}) \, dx \right| \leq C \|g\|_{L^p(\R^2)} \|\nabla \varphi\|_{L^p(\Omega)}.
\]
The existence of a solution \( u_n \) of (4.10) can be established minimizing on \( L^1_b(\Omega) \) the functional

\[
F(u) := \int_\Omega [A(x, \nabla u) \cdot \nabla u + b(x)|u|^p - hu] \, dx
\]

by means of the Direct Method of the Calculus of Variations. Uniqueness of the solution follows by strict convexity of \( F \).

We say that \( \Omega \) is stable for the Neumann problems (4.10) along the sequence \( (\Omega_n)_{n \in \mathbb{N}} \) if

\[
\lim_{n \to +\infty} \int_\Omega \left| \nabla u_{\Omega_n} - \nabla u_{\Omega} \right|^p + b(x) |u_{\Omega_n} - u_{\Omega}|^p \, dx = 0.
\]

The stability of Neumann problems (4.10) has been investigated by Bucur and Varchon in [9], in the case \( p = 2 \) and \( A(x, \xi) = \xi \) (but it easily generalizes to \( A(x, \xi) = a(x)\xi \) with \( a \) giving the correct coercivity).

The main interest in the stability of (4.10) is that, since \( b \) is not assumed to be strictly positive, stability is not equivalent to the Mosco convergence of \( L^1_b(\Omega_n) \) to \( L^1_b(\Omega) \) (see [9, Remark 5.2]). As a consequence, passing to the nonlinear setting with \( 1 < p < 2 \), an approach to stability in the line of Dal Maso, Ebobisse and Ponsiglione [18] based on Mosco convergence cannot be directly used in this situation.

Let \( (\Omega_n)_{n \in \mathbb{N}} \) be a sequence of uniformly bounded open sets in \( \mathbb{R}^2 \). In the case \( p = 2 \), Bucur and Varchon [9] proved that, if \( \Omega_n \in \mathcal{C}(\mathbb{R}^2) \) and \( \Omega_n \to \Omega \) in the Hausdorff complementary topology, then stability of (4.10) holds if and only if \( \text{meas}(\Omega_n \cap \{ b > 0 \}) \to \text{meas}(\Omega \cap \{ b > 0 \}) \). Proposition 4.4 permits to extend this result to problems (4.10).

**Proposition 4.4.** Let \( (\Omega_n)_{n \in \mathbb{N}} \) be a sequence of uniformly bounded open sets in \( \mathcal{C}(\mathbb{R}^2) \) converging to \( \Omega \) in the Hausdorff complementary topology. Then \( \Omega \) is stable along \( (\Omega_n)_{n \in \mathbb{N}} \) for the Neumann problems (4.10) if and only if

\[
\text{meas}(\Omega_n \cap \{ b > 0 \}) \to \text{meas}(\Omega \cap \{ b > 0 \}).
\]

**Proof.** Let us assume that stability holds. Then if we choose \( f = 1 \) and \( g = 0 \) so that \( h = b \), we deduce that

\[
u_{\Omega_n} = 1_{\Omega_n} \quad \text{and} \quad u_{\Omega} = 1_{\Omega}
\]

and that

\[
1_{\Omega_n} \to 1_{\Omega} \quad \text{strongly in} \quad L^b_1(\mathbb{R}^2),
\]

where \( L^b_1(\mathbb{R}^2) \) denotes the \( L^b \)-space with weight \( b \). In particular

\[
\text{meas}(\Omega_n \Delta \Omega \cap \{ b > 0 \}) \to 0,
\]

where \( C \Delta D \) denotes the symmetric difference of \( C \) and \( D \). In fact, if (4.13) does not hold, we have that there exists \( \chi \in L^\infty(\mathbb{R}^2) \) with \( \chi 1_{\{b > 0\}} = 0, \chi \neq 0 \) and

\[
1_{|\Omega_n \Delta \Omega| \cap \{ b > 0 \}} \rightharpoonup \chi \quad \text{weakly* in} \quad L^\infty(\mathbb{R}^2).
\]

As a consequence it would be

\[
\int_{\mathbb{R}^2} b 1_{|\Omega_n \Delta \Omega|} \, dx = \int_{\mathbb{R}^2} b 1_{|\Omega_n \Delta \Omega| \cap \{ b > 0 \}} \, dx \to \int_{\mathbb{R}^2} b \chi \, dx > 0
\]

which is against (4.12). Since

\[
|\text{meas}(\Omega_n \cap \{b > 0\}) - \text{meas}(\Omega \cap \{b > 0\})| \leq \text{meas}(\Omega_n \Delta \Omega \cap \{b > 0\}) \to 0,
\]

we deduce that (4.14) holds.

Let us assume now that (4.14) holds. Let us set \( u_n := u_{\Omega_n} \). Choosing \( u_n \) as a test in (4.10) we deduce that \( u_n \) is bounded in \( L^1 b_1(\mathbb{R}^2) \). Up to a subsequence we have that there exist \( \Phi \in L^p(\mathbb{R}^2, \mathbb{R}^2) \) and \( \varphi \in L^b_1(\mathbb{R}^2) \) such that

\[
\nabla u_n 1_{\Omega_n} \rightharpoonup \Phi \quad \text{weakly in} \quad L^p(\mathbb{R}^2, \mathbb{R}^2)
\]

and

\[
u_n 1_{\Omega_n} \rightharpoonup \varphi \quad \text{weakly in} \quad L^b_1(\mathbb{R}^2).
\]
By the convergence of $\Omega_n$ to $\Omega$ in the Hausdorff complementary topology, we have that $\Phi = \nabla \varphi$ on $\Omega$. In fact let $\Psi \in C^\infty(\Omega, \mathbb{R}^2)$ and let $U$ be a regular subset of $\Omega$ such that $\text{supp}(\Psi) \subseteq U \subseteq \overline{U} \subseteq \Omega$. Then $U \subseteq \Omega_n$ for $n$ large and

$$
\int_U \nabla u_n \cdot \Psi \, dx = - \int_U u_n \text{div} \Psi \, dx.
$$

Let $c_n$ be the average of $u_n$ on $U$. By Poincaré inequality and Rellich Compact Embedding of $W^{1,p}(U)$ into $L^p(U)$ we get up to a further subsequence

$$
(4.16) \quad (u_n - c_n) \rightarrow \tilde{u} \quad \text{strongly in } L^p(U).
$$

In particular the convergence is strong in $L^p_b(U)$ and

$$
(4.17) \quad \int_U \Phi \cdot \Psi \, dx = - \int_U \tilde{u} \text{div} \Psi \, dx.
$$

By (4.15) and (4.16) we deduce that $c_n = u_n - (u_n - c_n)$ converges to some $c \in \mathbb{R}$. We conclude that $\tilde{u} = \varphi - c$ and by (4.17) we get

$$
\int_U \Phi \cdot \Psi \, dx = - \int_U \varphi \text{div} \Psi \, dx
$$

which means that $\Phi = \nabla \varphi$ on $\Omega$.

Notice moreover that (4.11) and (4.15) imply that

$$
(4.18) \quad \lim_{n \rightarrow +\infty} \int_{\mathbb{R}^2} u_n 1_{\Omega_n} h \, dx = \int_{\Omega} \varphi h \, dx.
$$

In fact, since $h = bf + g$ and $\text{supp}(g) \subseteq \Omega$, it suffices to check that

$$
\lim_{n \rightarrow +\infty} \int_{\mathbb{R}^2} u_n 1_{\Omega_n} bf \, dx = \int_{\mathbb{R}^2} \varphi bf \, dx.
$$

Since $1_{\Omega_n \cap \{b>0\}} \rightarrow 1_{\Omega \cap \{b>0\}}$ strongly in $L^1(\mathbb{R}^2)$ we have

$$
\lim_{n \rightarrow +\infty} \int_{\mathbb{R}^2} u_n 1_{\Omega_n} bf \, dx = \lim_{n \rightarrow +\infty} \int_{\mathbb{R}^2} u_n 1_{\Omega_n} 1_{b>0} \, dx = \int_{\mathbb{R}^2} \varphi bf 1_{\Omega \cap \{b>0\}} \, dx.
$$

Let us prove that $\varphi = u_\Omega$ on $\Omega$. In fact, for every $v \in L^1_b(\Omega)$, by monotonicity we have that

$$
(4.19) \quad \int_{\mathbb{R}^2} [A(x, \nabla v_1) \cdot (\nabla u_\Omega - \nabla u_n 1_{\Omega_n}) + B(x, v_1)(v_1 - u_n 1_{\Omega_n})] \, dx
\geq \int_{\mathbb{R}^2} [A(x, \nabla u_n 1_{\Omega_n}) \cdot (\nabla v_1 - \nabla u_n 1_{\Omega_n}) + B(x, u_n 1_{\Omega_n})(v_1 - u_n 1_{\Omega_n})] \, dx,
$$

where

$$
B(x, \xi) := b(x)|\xi|^{p-2} \xi - h(x).
$$

We claim that there exists $v_n \in L^1_b(\Omega)$ such that

$$
(4.20) \quad \nabla v_n 1_{\Omega_n} \rightarrow \nabla v_1 \Omega \quad \text{strongly in } L^p(\mathbb{R}^2, \mathbb{R}^2)
$$

and

$$
(4.21) \quad v_n 1_{\Omega_n} \rightarrow v_1 \Omega \quad \text{strongly in } L^p_b(\mathbb{R}^2).
$$

Notice that

$$
(4.22) \quad \lim_{n \rightarrow +\infty} \int_{\mathbb{R}^2} hv_n 1_{\Omega_n} \, dx = \int_{\mathbb{R}^2} hv_1 \Omega \, dx.
$$

In fact, because of (4.21), we have

$$
\lim_{n \rightarrow +\infty} \int_{\mathbb{R}^2} bf v_n 1_{\Omega_n} \, dx = \int_{\mathbb{R}^2} bf v_1 \Omega \, dx.
$$

Moreover, if $U$ is regular and with $\text{supp}(g) \subseteq U \subseteq \overline{U} \subseteq \Omega$ we have by Poincaré inequality

$$
\left| \int_U g(v_n - v) \, dx \right| \leq \|g\|_{L^p(U)} \|\nabla v_n - \nabla v\|_{L^p(U, \mathbb{R}^2)} \rightarrow 0.
$$
Since $U \subseteq \Omega_n$ for $n$ large enough, we conclude that (1.22) holds.

Using $v_n - u_n$ as a test function in (1.10) we can rewrite the right-hand side of (1.10) as

\begin{equation}
(4.23) \quad \int_{\mathbb{R}^2} \left[ A(x, \nabla u_n 1_{\Omega_n}) \cdot (\nabla v_1 - \nabla u_n 1_{\Omega_n}) + B(x, u_n 1_{\Omega_n})(v_1 - u_n 1_{\Omega_n}) \right] \, dx
\end{equation}

\begin{equation*}
= \int_{\mathbb{R}^2} \left[ A(x, \nabla u_n 1_{\Omega_n}) \cdot (\nabla v_1 - \nabla v_n 1_{\Omega_n}) + B(x, u_n 1_{\Omega_n})(v_1 - u_n 1_{\Omega_n}) \right] \, dx.
\end{equation*}

Since $A(x, \nabla u_n 1_{\Omega_n})$ is bounded in $L^p(\mathbb{R}^2, \mathbb{R}^2)$ and $|u_n|^{p-2} u_n 1_{\Omega_n}$ is bounded in $L^p(\mathbb{R}^2)$, passing to the limit in (4.19) and in (4.23), by claims (4.20) and (4.21), and in view of (4.18) and of the fact that $A(x, 0) = 0$, we obtain

\begin{equation}
(4.24) \quad \int_{\Omega} \left[ A(x, \nabla v) \cdot (\nabla v - \nabla \varphi) + B(x, v)(v - \varphi) \right] \, dx
\end{equation}

\begin{equation}
\geq \lim_{n \to +\infty} \int_{\mathbb{R}^2} \left[ A(x, \nabla u_n 1_{\Omega_n}) \cdot (\nabla v_1 - \nabla v_n 1_{\Omega_n}) + B(x, u_n 1_{\Omega_n})(v_1 - u_n 1_{\Omega_n}) \right] \, dx = 0.
\end{equation}

Taking $v = \varphi \pm \varepsilon$ in (4.24), with $\varepsilon \in L^1_b(\Omega)$ and $\varepsilon > 0$, dividing by $\varepsilon$, and passing to the limit as $\varepsilon \to 0$, we obtain that $\varphi = u_1 \Omega_n$.

Let us now prove that $\varphi = u_1 \Omega_n$, $\Phi = \nabla u_1 \Omega_n$, and that the convergences in (4.20) and (4.21) are indeed strong. Let us take $v = u_1 \Omega_n$ in (4.23). Since $A(x, 0) = 0$ we obtain that

\begin{equation}
\lim_{n \to +\infty} \int_{\mathbb{R}^2} \left[ A(x, \nabla u_n 1_{\Omega_n}) - A(x, \nabla u_1 \Omega_n) \right] \cdot (\nabla u_n 1_{\Omega_n} - \nabla u_1 \Omega_n) \, dx
\end{equation}

\begin{equation}
+ \int_{\mathbb{R}^2} b(x)(|u_n|^{p-2} u_n 1_{\Omega_n} - |u_1|^{p-2} u_1 \Omega_n)(u_n 1_{\Omega_n} - u_1 \Omega_n) \, dx = 0.
\end{equation}

By monotonicity we get that each integral tends to zero. Now, the strong convergence of $\nabla u_n 1_{\Omega_n}$ to $\nabla u_1 \Omega_n$ in $L^p(\mathbb{R}^2, \mathbb{R}^2)$ and of $u_n 1_{\Omega_n}$ to $u_1 \Omega_n$ in $L^p(\mathbb{R}^2)$ is a consequence of [18, Lemma 2.4].

In order to conclude the proof, we have to prove our claim on the existence of $v_n \in L^1_b(\Omega_n)$ satisfying (4.20) and (4.21). By Proposition 4.2, every function $z \in L^{1,2}(\Omega)$ is strong limit of a sequence of functions $z_n \in L^{1,2}(\Omega_n)$ (with the usual extension to zero outside $\Omega$ and $\Omega_n$ respectively). Since $\Omega \in A_p(\mathbb{R}^2)$, by Proposition 4.1, $v$ is a strong limit in $L^1_b(\Omega)$ of functions in $W^{1,2}(\Omega)$, in particular are in $L^{1,2}(\Omega)$. Then the strong approximability for $v$ that we need follows easily using a diagonal argument.

\[\square\]

4.2. Nonlinear optimal cutting problem. In this subsection, we apply Theorem 3.8 to the problem of optimal cutting for a membrane governed by a nonlinear energy.

Let $\Omega \subseteq \mathbb{R}^2$ be open, bounded, and with a Lipschitz boundary, and let $x_1, x_2 \in \Omega$. Let us set

\[\mathcal{K}(\Omega) := \{ K \subseteq \Omega : K \text{ is compact and connected with } x_1, x_2 \in K \}.\]

Let $f : \mathbb{R}^2 \times \mathbb{R}^2 \to [0, +\infty]$ be a Carathéodory function such that $f(x, 0) = 0$ and satisfying the following growth estimate

\begin{equation}
(4.25) \quad \alpha|\xi|^p \leq f(x, \xi) \leq \alpha(|\xi|^p + 1),
\end{equation}

where $\alpha > 0$ and $p \in [1, +\infty[$.

Let $g \in W^{1,p}(\mathbb{R}^2)$. For every $K \in \mathcal{K}(\Omega)$ let us set

\begin{equation}
(4.26) \quad \mathcal{E}(K) := \inf \left\{ \int_{\Omega \setminus K} f(x, \nabla u) \, dx : u \in L^1(\Omega \setminus K), u = g \text{ on } \partial \Omega \setminus K \right\},
\end{equation}

where $L^1(\Omega \setminus K)$ is the Deny-Lions space defined in (4.31) with $b \equiv 0$. Notice that it is natural to consider displacements in $L^1(\Omega \setminus K)$ because the energy involves only $\nabla u$, and so we cannot expect to control the $L^p$-norm of $u$. Moreover, notice that the boundary condition on $\partial \Omega \setminus K$ is well defined since $\Omega$ is Lipschitz and $u \in W^{1,p}(\Omega \cap B_r(x))$ for every $x \in \partial \Omega \setminus K$ and $r$ such that $B_r(x) \cap \Omega = \emptyset$. 

We have that \( \mathcal{E}(K) \) can be rewritten as
\[
\mathcal{E}(K) = \inf \left\{ \int_{\Omega \setminus K} f(x, \nabla u) \, dx : u \in W^{1,p}(\Omega \setminus K), u = g \text{ on } \partial \Omega \setminus K \right\}
\]
This is due to the density of \( W^{1,p}(\Omega \setminus K) \) in \( L^{1,p}(\Omega \setminus K) \), but a little care should be paid for the boundary condition. In particular, denoting by \( T_M \) the truncation operator \( T_M u := \min\{\max\{u, -M\}, M\} \), we have for every \( u \in L^{1,p}(\Omega \setminus K) \)
\[
\int_{\Omega \setminus K} f(x, \nabla u) \, dx = \lim_{M \to +\infty} \int_{\Omega \setminus K} f(x, \nabla T_M u - \nabla T_M g + \nabla g) \, dx
\]
so that (4.27) holds.

The optimal cutting problem consists in finding the "cut" \( K \in \mathcal{K}(\overline{\Omega}) \) which maximizes \( \mathcal{E} \) among all admissible cuts, i.e., to solve the problem
\[
\max_{K \in \mathcal{K}(\overline{\Omega})} \mathcal{E}(K).
\]
The existence of an optimal cutting has been established by Bucur, Buttazzo and Varchon in [5] in the case \( p = 2 \) and with a quadratic energy density \( f(x, \xi) = A\xi \cdot \xi \). In view of Theorem 4.5, the existence of an optimal cut can be proved also in the nonlinear case \( 1 < p < 2 \). The following result holds.

**Proposition 4.5.** Let \( 1 < p < 2 \). Then problem (4.28) has a solution.

In order to prove Proposition 4.5 we need the following lemma which is based on Theorem 3.8 and on the first condition of Mosco convergence for Sobolev spaces \( W^{1,2} \) proved in [9].

**Lemma 4.6.** Let \( 1 < p < 2 \), and let \( (K_n)_{n \in \mathbb{N}} \) be a sequence in \( \mathcal{K}(\overline{\Omega}) \) converging in the Hausdorff metric to \( K \). Then for every \( u \in W^{1,p}(\Omega \setminus K) \) with \( u = g \) on \( \partial \Omega \setminus K \) there exists \( u_n \in W^{1,p}(\Omega \setminus K_n) \) with \( u_n \rightharpoonup u \) on \( \partial \Omega \setminus K_n \) such that
\[
\nabla u_n 1_{\Omega \setminus K_n} \rightharpoonup \nabla u 1_{\Omega \setminus K} \quad \text{strongly in } L^p(\mathbb{R}^2, \mathbb{R}^2).
\]

**Proof.** Let \( B \) be an open ball containing \( \overline{\Omega} \). Let us consider
\[
\hat{u} := \begin{cases} 
  u & \text{in } \Omega \setminus K \\
  g & \text{in } B \setminus \overline{\Omega}.
\end{cases}
\]
Notice that \( \hat{u} \in W^{1,p}(B \setminus K) \). By applying Theorem 3.8 to \( (B \setminus K) \in \mathcal{A}_p(\mathbb{R}^2) \) we have that there exists \( \hat{v}_h \in W^{1,2}(B \setminus K) \) such that
\[
\hat{v}_h \rightharpoonup \hat{u} \quad \text{strongly in } W^{1,p}(B \setminus K).
\]
By Proposition 1.2 (with \( b \equiv 0 \), so that the convergence of the measures is automatically satisfied), for each \( h \in \mathbb{N} \) there exists \( \tilde{v}_h \in W^{1,2}(B \setminus K_n) \) such that
\[
\nabla \tilde{v}_h 1_{B \setminus K_n} \rightharpoonup \nabla \hat{v}_h 1_{B \setminus K} \quad \text{strongly in } L^2(\mathbb{R}^2, \mathbb{R}^2).
\]
Using a diagonal argument, and since the \( L^2 \)-convergence is stronger than \( L^p \)-convergence on bounded domains \( (1 < p < 2) \), we can find \( \tilde{v}_n \in W^{1,2}(B \setminus K_n) \) such that
\[
\nabla \tilde{v}_n 1_{B \setminus K_n} \rightharpoonup \nabla \hat{u} 1_{B \setminus K} \quad \text{strongly in } L^p(\mathbb{R}^2, \mathbb{R}^2).
\]
The functions \( \tilde{v}_n \) do not satisfy a-priori the required boundary condition, so that we have to modify them. We follow here an idea due to Chambolle [13]. Up to adding a constant to \( \tilde{v}_n \), we can assume that
\[
\tilde{v}_n \rightharpoonup g \quad \text{strongly in } W^{1,p}(B \setminus \overline{\Omega}).
\]
Let us consider \( \hat{g}_n := (g - \tilde{v}_n)|_{B \setminus \overline{\Omega}} \). We have that \( \hat{g}_n \in W^{1,p}(B \setminus \overline{\Omega}) \) with \( \hat{g}_n \to 0 \) strongly in \( W^{1,p}(B \setminus \overline{\Omega}) \). Let \( E \) denote a linear extension operator from \( W^{1,p}(B \setminus \overline{\Omega}) \) to \( W^{1,p}(B) \) such an \( E \) exists because \( \Omega \) has a Lipschitz boundary. Let us set
\[
u_n := (\tilde{v}_n + E\hat{g}_n)|_{\Omega \setminus K_n}.
\]
We have \( u_n \in W^{1,p}(\Omega \setminus K_n) \) with \( u_n = g \) on \( \partial \Omega \setminus K_n \). Moreover, since \( E\tilde{g}_n \to 0 \) strongly in \( W^{1,p}(B) \), in view of (4.29), we deduce that \((u_n)_{n \in \mathbb{N}}\) is the required sequence.

We are now in a position to prove Proposition 4.5.

**Proof of Proposition 4.5.** Let \((K_n)_{n \in \mathbb{N}}\) be a maximizing sequence for the optimal cutting problem, i.e.,
\[
\mathcal{E}(K_n) \to \sup\{\mathcal{E}(K) : K \in \mathcal{K}(\overline{\Omega})\}.
\]

Up to a subsequence, we can assume that \( K_n \to K \) in the Hausdorff metric. We have that \( K \) is an admissible cut, that is \( K \in \mathcal{K}(\overline{\Omega}) \).

By Lemma 4.6, for every \( u \in W^{1,p}(\Omega \setminus K) \) with \( u = g \) on \( \partial \Omega \setminus K \) there exists \( u_n \in W^{1,p}(\Omega \setminus K_n) \) with \( u_n = g \) on \( \partial \Omega \setminus K_n \) such that
\[
\nabla u_n 1_{\Omega \setminus K_n} \to \nabla u 1_{\Omega \setminus K} \quad \text{strongly in } L^p(\mathbb{R}^2, \mathbb{R}^2).
\]

Since \( f(x,0) = 0 \), we deduce
\[
\int_{\Omega \setminus K} f(x, \nabla u) \, dx = \lim_{n \to +\infty} \int_{\Omega \setminus K_n} f(x, \nabla u_n) \, dx \geq \lim_{n \to +\infty} \mathcal{E}(K_n).
\]

Taking the infimum over all admissible \( u \) we get
\[
\mathcal{E}(K) \geq \lim_{n \to +\infty} \mathcal{E}(K_n)
\]
so that \( K \) is an optimal cut, and the proof is concluded.

**Remark 4.7.** In the proof of Proposition 4.5 it is not clear if \( \text{meas}(K_n) \to \text{meas}(K) \) for \( n \to +\infty \). As a consequence, the result of Dal Maso, Ebobisse and Ponsiglione [18] cannot be applied to recover the approximability of gradients of functions in \( W^{1,p}(\Omega \setminus K) \) through gradients of functions in \( W^{1,p}(\Omega \setminus K_n) \) that we need. It seems essential to use the approximability of the gradients for the relative \( W^{1,2} \)-spaces established in [9] and the density result given by Theorem 3.8.

Let us assume that \( f(x, \xi) \) is strictly convex in \( \xi \) so that the problem
\[
(4.30) \quad \min \left\{ \int_{\Omega \setminus K} f(x, \nabla u) \, dx : u \in L^{1,p}(\Omega \setminus K), u = g \text{ on } \partial \Omega \setminus K \right\}
\]
admits a unique solution \( u_{\Omega \setminus K} \in L^{1,p}(\Omega \setminus K) \). In particular, in view of (4.26) we have
\[
\mathcal{E}(K) = \int_{\Omega \setminus K} f(x, \nabla u_{\Omega \setminus K}) \, dx.
\]

The associated Euler-Lagrange equation is
\[
\begin{cases}
\text{div}_\xi f(x, \nabla u_{\Omega \setminus K}) = 0 & \text{in } \Omega \setminus K \\
\partial_\xi f(x, \nabla u_{\Omega \setminus K}) \cdot \nu = 0 & \text{on } K \\
u_{\Omega \setminus K} = g & \text{on } \partial \Omega \setminus K.
\end{cases}
\]

We deduce that the following stability result for the Neumann-Dirichlet problem (4.30) holds.

**Proposition 4.8.** Let \( 1 < p < 2 \), let \( K \) be a solution of (4.28), and let \((K_n)_{n \in \mathbb{N}}\) be a sequence in \( \mathcal{K}(\overline{\Omega}) \) converging in the Hausdorff metric to \( K \). Then we have that \( \Omega \setminus K \) is stable for (4.30) along the sequence \((\Omega \setminus K_n)_{n \in \mathbb{N}}\), that is
\[
(4.32) \quad \nabla u_{\Omega \setminus K_n} 1_{\Omega \setminus K_n} \to \nabla u_{\Omega \setminus K} 1_{\Omega \setminus K} \quad \text{strongly in } L^p(\mathbb{R}^2, \mathbb{R}^2).
\]

**Proof.** Choosing \( g \) as an admissible displacement in (4.30), we get that \( \nabla u_{\Omega \setminus K_n} 1_{\Omega \setminus K_n} \) is bounded in \( L^p(\mathbb{R}^2, \mathbb{R}^2) \) so that up to a subsequence we have
\[
\nabla u_{\Omega \setminus K_n} 1_{\Omega \setminus K_n} \to \Phi \quad \text{weakly in } L^p(\mathbb{R}^2, \mathbb{R}^2).
\]
Since $K_n \to K$ in the Hausdorff metric, there exists $u \in L^{1,p}(\Omega \setminus K)$ with $u = g$ on $\partial \Omega \setminus K$ such that $\Phi = \nabla u$ on $\Omega \setminus K$. Moreover by lower semicontinuity we have that
\begin{equation}
(4.33) \int_{\Omega \setminus K} f(x, \nabla u) \, dx = \int_{\mathbb{R}^2} f(x, \Phi) \, dx \leq \liminf_{n \to +\infty} \int_{\mathbb{R}^2} f(x, \nabla u_{n,K_n} 1_{\Omega \setminus K_n}) \, dx
\end{equation}
\begin{equation*}
\leq \liminf_{n \to +\infty} \int_{\Omega \setminus K_n} f(x, \nabla u_{n,K_n}) \, dx.
\end{equation*}
Let $v \in L^{1,p}(\Omega \setminus K)$ with $v = g$ on $\partial \Omega \setminus K$. By Lemma 4.6 there exists $v_n \in L^{1,p}(\Omega \setminus K_n)$ with $v_n = g$ on $\partial \Omega \setminus K_n$ such that
\begin{equation*}
\nabla v_n 1_{\Omega \setminus K_n} \to \nabla v 1_{\Omega \setminus K} \quad \text{strongly in } L^p(\mathbb{R}^2, \mathbb{R}^2).
\end{equation*}
Then by (4.33) we get
\begin{equation}
(4.34) \int_{\Omega \setminus K} f(x, \nabla v) \, dx = \lim_{n \to +\infty} \int_{\mathbb{R}^2} f(x, \nabla v_n 1_{\Omega \setminus K_n}) \, dx = \lim_{n \to +\infty} \int_{\Omega \setminus K_n} f(x, \nabla v_n) \, dx
\end{equation}
\begin{equation*}
\geq \liminf_{n \to +\infty} \int_{\Omega \setminus K_n} f(x, \nabla u_{n,K_n}) \, dx \geq \int_{\Omega \setminus K} f(x, \nabla u) \, dx
\end{equation*}
so that $u = u_{\Omega \setminus K}$. Taking $v = u$ in (4.34) we obtain
\begin{equation*}
\lim_{n \to +\infty} \int_{\Omega \setminus K_n} f(x, \nabla u_{n,K_n}) \, dx = \int_{\Omega \setminus K} f(x, \nabla u_{\Omega \setminus K}) \, dx.
\end{equation*}
By 4 we conclude that (4.32) holds, and the proof is concluded.

5. APPENDIX: THE DENSITY RESULT FOR THE SYMMETRIZED GRADIENTS

The aim of this appendix is to show how our approach to density explained in Section 3 can be employed to prove the density of the Sobolev space $W^{1,2}_{LD}$ in the spaces $L^{1,p}$ of two dimensional elasticity. The case $p = 2$ is the really interesting one, and has been proved by Chambolle in [13]: using this density, he proves existence for the Cantilever Problem and for the evolution of brittle fractures in the context of planar linearized elasticity. Our approach provides a different proof of Chambolle’s result, and covers also the case $1 < p < 2$.

In order to make the context precise, let $\Omega$ be an open subset of $\mathbb{R}^2$. For $1 \leq p \leq +\infty$, let us set
\begin{equation*}
LD^{1,p}(\Omega) := \left\{ u \in W^{1,1}_{\text{loc}}(\Omega, \mathbb{R}^2) : e(u) \in L^p(\Omega, M^{2\times 2}_{\text{sym}}) \right\},
\end{equation*}
where $e(u) := (\nabla u + (\nabla u)^T)/2$ denotes the symmetrized gradient of $u$, and $M^{2\times 2}_{\text{sym}}$ denotes the space of $2 \times 2$ symmetric matrices. Clearly $W^{1,p}(\Omega, \mathbb{R}^2) \subseteq LD^{1,p}(\Omega)$. If $\Omega$ is Lipschitz, by means of Korn’s inequality, it turns out that $LD^{1,p}(\Omega)$ coincides with $W^{1,p}(\Omega, \mathbb{R}^2)$, while if $\Omega$ is irregular, the inclusion can be strict.

The main result of this section is the following.

**Theorem 5.1.** Let $1 < p \leq 2$, and let $\Omega \subseteq \mathbb{R}^2$ be a bounded open set such that $\Omega^c$ has a finite number of connected components. Then for every $u \in LD^{1,p}(\Omega)$ there exists $u_n \in W^{1,2}(\Omega, \mathbb{R}^2)$ such that $e(u_n) \to e(u)$ strongly in $L^p(\Omega, M^{2\times 2}_{\text{sym}})$.

**Proof.** Let $K_i, i = 0, 1, \ldots, m,$ be the connected components of $\Omega^c$, where $K_0$ is the unbounded one. Let us consider the space
\begin{equation*}
H := \{ e(v) : v \in H^1(\Omega, \mathbb{R}^2) \} \subseteq L^p(\Omega, M^{2\times 2}_{\text{sym}}),
\end{equation*}
where on $M^{2\times 2}_{\text{sym}}$ we consider the scalar product $A : B := \text{tr}(AB^T) = \sum_{i,j} a_{ij} b_{ij}$.

In order to prove the theorem, it suffices to check that for every $u \in LD^{1,p}(\Omega)$ we have
\begin{equation*}
e(u) \in \overline{H},
\end{equation*}
where the closure is taken in the $L^p$-norm.
We employ a functional analysis argument, namely that \( \overline{H} = (H^\perp)^\perp \), where \((\cdot)^\perp\) denotes the orthogonal in the sense of Banach spaces. So our strategy is the following. Firstly we characterize \( H^\perp \), and then we check that \( e(u) \) is orthogonal to every element of \( H^\perp \).

**Step 1: Characterization of \( H^\perp \).** We claim that

\[
H^\perp := \left\{ \widetilde{\text{Hess}}(\varphi) : \varphi \in W_0^{2,p'}(\mathbb{R}^2), \varphi \text{ is linear on } K_i \text{ for } i = 0, 1, \ldots, m \right\},
\]

where \( \widetilde{\text{Hess}}(\varphi) \) is defined as

\[
\widetilde{\text{Hess}}(\varphi) := \begin{pmatrix}
\partial_2^2 \varphi & -\partial_1 \partial_2 \varphi \\
-\partial_1 \partial_2 \varphi & \partial_1^2 \varphi
\end{pmatrix}.
\]

By linearity of \( \varphi \) on \( K_i \) we mean that there exist \( c_i \in \mathbb{R}^2 \) and \( b_i \in \mathbb{R} \) such that (notice that \( W_0^{2,p'}(\mathbb{R}^2) \subseteq C^1(\mathbb{R}^2) \))

\[
\varphi(x) = c_i \cdot x + b_i \quad \text{for } x \in K_i.
\]

Since \( \varphi \in W_0^{2,p'}(\mathbb{R}^2) \), we clearly have \( c_0 = 0 \) and \( b_0 = 0 \).

Let us check (5.1). Let \( \Psi \in L^p(\Omega, M_{sym}^{2\times 2}) \) be an element of \( H^\perp \), where \( p' := p/(p - 1) \) is the conjugate exponent to \( p \), with

\[
\Psi = \begin{pmatrix}
\psi_1 & \psi_2 & \psi_3 \\
\psi_2 & \psi_3 & \psi_1
\end{pmatrix}.
\]

This means that for every \( v \in H^1(\Omega, \mathbb{R}^2) \) we have

\[
\int_\Omega \Psi : e(v) \, dx = 0.
\]

Choosing \( v \in H \) of the form \( v := (v_1, 0) \) with \( v_1 \in H^1(\Omega) \), we deduce that for every \( v_1 \in H^1(\Omega) \)

\[
\int_\Omega (\psi_1, \psi_2) \cdot \nabla v_1 \, dx = 0.
\]

Similarly we deduce that for every \( v_2 \in H^1(\Omega) \)

\[
\int_\Omega (\psi_2, \psi_3) \cdot \nabla v_2 \, dx = 0.
\]

From Lemma 3.4 we conclude that there exist \( \phi_1, \phi_2 \in W^{1,p'}(\mathbb{R}^2) \) and \( c_i \in \mathbb{R}^2 \), \( i = 0, 1, \ldots, m \) such that

\[
\nabla \phi_1 = R(\psi_1, \psi_2), \quad \nabla \phi_2 = R(\psi_2, \psi_3),
\]

(5.4)

\[
(\phi_1, \phi_2) = c_i \quad \text{on } K_i \text{ for } 1 < p < 2,
\]

and

\[
(\phi_1, \phi_2) = c_i \quad \text{c.e. on } K_i \text{ for } p = 2,
\]

(5.5)

where \( R(a, b) := (-b, a) \) denotes a rotation of 90 degrees counterclockwise. We can assume \( c_0 = 0 \), hence \( \phi_1, \phi_2 \in W_0^{1,p'}(\mathbb{R}^2) \).

Let us set

\[
\Phi := (\phi_1, \phi_2) \in W_0^{1,p'}(\mathbb{R}^2, \mathbb{R}^2).
\]

Let \( D \) be a disk centered at the origin and such that \( \overline{\Omega} \subseteq D \). For every \( v \in H^1(D, \mathbb{R}^2) \) we have that

\[
\int_D \Phi \cdot \nabla v \, dx = -\int_D (\text{div } \Phi) \, v \, dx = -\int_D (\partial_1 \phi_1 + \partial_2 \phi_2) v \, dx = -\int_D (\psi_1 + \psi_2) v \, dx = 0.
\]

Using again Lemma 3.4 we get that there exists \( \varphi \in W^{1,p'}(\mathbb{R}^2) \) with \( \varphi = 0 \) on \( \mathbb{R}^2 \setminus D \), and such that

\[
\nabla \varphi = R\Phi = (-\phi_2, \phi_1).
\]
In view of (5.6), we conclude that $\varphi \in W^{2,p'}_0(\mathbb{R}^2)$. Since $p' \geq 2$, by Sobolev Embedding Theorem we have that $\varphi \in C^1(\mathbb{R}^2)$, so that, by Lemma 2.1 from (5.3) and (5.5) we get (up to replacing $c_i$ with $Rc_i$)

(5.7) \[ \nabla \varphi = c_i \text{ on } K_i. \]

By construction we have that $\Psi = \widetilde{\text{Hess}}(\varphi)$. In order to complete the proof of claim (5.1), we need to check (5.3). Let us consider $\varphi_i(x) := \varphi(x) - c_i \cdot x$.

By (5.7), we clearly have that $\nabla \varphi_i = 0$ on $K_i$, i.e., $K_i \subseteq C_i$, where $C_i$ is the set of critical points of $\varphi_i$. By Sard’s Lemma we have that $\text{meas}(\varphi_i(C_i)) = 0$.

Since $\varphi_i(K_i)$ is connected, and $\text{meas}(\varphi_i(K_i)) = 0$, we conclude that $\varphi_i(K_i) = \{b_i\}$ for a suitable $b_i \in \mathbb{R}$, so that (5.3) is proved.

**Step 2: Checking the orthogonality condition.** Let $u \in LD^{1,p}(\Omega)$, and let $\Psi \in H^\perp$. We have to check that

$$\int_\Omega \Psi : e(u) \, dx = 0.$$

According to (5.1), let $\Psi = \widetilde{\text{Hess}}(\varphi)$ with $\varphi \in W^{2,p'}_0(\mathbb{R}^2)$ satisfying (5.3). Let us consider $\xi_0 \in C^\infty(\mathbb{R}^2)$ and $\xi_i \in C_c^\infty(\mathbb{R}^2)$, $i = 1, 2, \ldots, m$, such that $\xi_0 = 1$ on a neighborhood of $K_0$, $\xi_i = 1$ on a neighborhood of $K_i$, and

$$\text{supp}(\xi_h) \cap \text{supp}(\xi_k) = \emptyset \quad \text{for } h \neq k.$$

By [2, Theorem 9.1.3] we can find $\varphi_i^\prime_n \in C^\infty(\mathbb{R}^2)$ with

$$\varphi_i^\prime_n(x) = c_i \cdot x + b_i \quad \text{on a neighborhood of } K_i,$$

and such that

$$\varphi_i^\prime_n \to \varphi \quad \text{strongly in } W^{2,p'}(\mathbb{R}^2).$$

Let us set

$$\varphi_n := \left(1 - \sum_{i=0}^m \xi_i\right) \varphi + \sum_{i=0}^m \xi_i \varphi_i^\prime_n.$$

Clearly we have that

(5.8) \[ \varphi_n \to \varphi \quad \text{strongly in } W^{2,p'}(\mathbb{R}^2), \]

and

(5.9) \[ \widetilde{\text{Hess}}(\varphi_n) = 0 \quad \text{on a neighborhood } A_n \text{ of } \Omega^c. \]

We can assume that $\Omega \setminus \overline{A_n}$ is regular. Then by means of Korn’s inequality we have that

(5.10) \[ u \in W^{1,p}(\Omega \setminus \overline{A_n}, \mathbb{R}^2). \]

By (5.8) and (5.9) we conclude that

$$\int_\Omega \Psi : e(u) \, dx = \int_\Omega \widetilde{\text{Hess}}(\varphi) : e(u) \, dx = \lim_{n \to +\infty} \int_\Omega \widetilde{\text{Hess}}(\varphi_n) : e(u) \, dx = \lim_{n \to +\infty} \int_{\Omega \setminus \overline{A_n}} \widetilde{\text{Hess}}(\varphi_n) : e(u) \, dx.$$

By (5.10) and since $\widetilde{\text{Hess}}(\varphi_n)$ is symmetric, we deduce that

(5.11) \[ \int_{\Omega \setminus \overline{A_n}} \widetilde{\text{Hess}}(\varphi_n) : \nabla u \, dx. \]
Notice that the rows of $\widetilde{\text{Hess}}(\varphi_n)$ are divergence free in $\Omega \setminus \overline{A_n}$, and with null trace on $\partial(\Omega \setminus \overline{A_n})$. Integrating by parts in (5.11), we get
\[ \int_\Omega \Psi : e(u) \, dx = 0, \]
so that the proof is concluded. \hfill \Box

**Remark 5.2.** In his proof of the density of $W^{1,2}(\Omega)$ in $LD^{1,2}(\Omega)$, Chambolle [13] considers $LD^{1,2}(\Omega)$ (up to functions $u$ such that $e(u) = 0$) as a Hilbert space with scalar product $(u, v) := \int_\Omega e(u) : e(v) \, dx$, and proves that
\[ \{e(u) : u \in W^{1,2}(\Omega)\}^\perp = 0, \]
where $(\cdot)^\perp$ is the orthogonal in the sense of Hilbert spaces. In this framework, the function $\Psi$ appearing in our Step 1 is of the form $\Psi = e(v)$ for some $v \in LD^{1,2}(\Omega)$, and the same analysis implies that $e(v) = \text{Hess}(\varphi)$. As a consequence we get $\Delta^2 \varphi = 0$ ($\varphi$ is usually called the Airy function). Chambolle uses some PDE and capacity arguments to show that $\varphi = 0$ in the case $\Omega$ is simply connected, and then proves the general case by reduction to the simply connected one.

In our case, we cannot employ PDE arguments, because we consider $LD^{1,p}(\Omega)$ as a natural subspace of $L^p(\Omega, M^{2} \text{sym}_2)$, and this seems unavoidable in the case $1 < p < 2$. As a consequence our function $\varphi$ does not satisfy $\Delta^2 \varphi = 0$, and we must work out an approximation of $\varphi$ as in Step 2.

**Remark 5.3.** In order to follow the arguments of Step 2, it suffices to approximate $\Psi = \widetilde{\text{Hess}}(\varphi) \in H^\perp$ by $\Psi_n \in L^{p'}(\Omega, M^{2} \text{sym}_2)$ which are null on a neighborhood of $\Omega^c$ and whose rows are divergence free. This is obtained taking $\Psi_n := \widetilde{\text{Hess}}(\varphi_n)$, where $\varphi_n \in W^{2,p'}(\mathbb{R}^2)$ is such that
\[ \varphi_n \rightarrow \varphi \quad \text{strongly in } W^{2,p'}(\mathbb{R}^2), \]
and with $\varphi_n$ linear on a neighborhood of $\Omega^c$. This last constraint cannot be treated using ideas similar to Lemma [13] so that we used partition of unity (which requires $\Omega^c$ with a finite number of connected components) and the approximation result [2] Theorem 9.1.3] (which requires $1 < p < +\infty$).

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