**m⁴Adapter: Multilingual Multi-Domain Adaptation for Machine Translation with a Meta-Adapter**

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**Abstract**

Multilingual neural machine translation models (MNMT) yield state-of-the-art performance when evaluated on data from a domain and language pair seen at training time. However, when a MNMT model is used to translate under domain shift or to a new language pair, performance drops dramatically. We consider a very challenging scenario: adapting the MNMT model both to a new domain and to a new language pair at the same time. In this paper, we propose m⁴Adapter (Multilingual Multi-Domain Adaptation for Machine Translation with a Meta-Adapter), which combines domain and language knowledge using meta-learning with adapters. We present results showing that our approach is a parameter-efficient solution which effectively adapts a model to both a new language pair and a new domain, while outperforming other adapter methods. An ablation study also shows that our approach more effectively transfers domain knowledge across different languages and language information across different domains.¹

1 Introduction

Multilingual neural machine translation (MNMT; Johnson et al., 2017; Aharoni et al., 2019; Fan et al., 2021), uses a single model to handle translation between multiple language pairs. There are two reasons why MNMT is appealing: first, it has been proved to be effective on transferring knowledge from high-resource languages to low-resource languages, especially in zero-shot scenarios (Gu et al., 2019; Zhang et al., 2020); second, it significantly reduces training and inference cost, as it requires training only a single multilingual model, instead of a separate model for each language pair.

Adapting MNMT models to multiple domains is still a challenging task, particularly when domains are distant to the domain of the training corpus. One approach to address this is fine-tuning the model on out-of-domain data for NMT (Freitag and Al-Onaizan, 2016; Dakwale and Monz, 2017). Another approach is to use lightweight, learnable units inserted between transformer layers, which are called adapters (Bapna and Firat, 2019) for each new domain. Similarly, there is research work on adapting MNMT models to a new language pair using fine-tuning (Neubig and Hu, 2018) and adapters (Bapna and Firat, 2019; Philip et al., 2020; Cooper Stickland et al., 2021b).

Although effective, the above approaches have some limitations: i) Fine-tuning methods require updating the parameters of the whole model for each new domain, which is costly; ii) when fine-tuning on a new domain, catastrophic forgetting (McCloskey and Cohen, 1989) reduces the performance on all other domains, and proves to be a significant issue when data resources are limited. iii) adapter-based approaches require training domain adapters for each domain and language adapters for all languages, which also becomes parameter-inefficient when adapting to a new domain and a new language because the parameters scale linearly with the number of domains and languages.

In recent work, Cooper Stickland et al. (2021a) compose language adapters and domain adapters in MNMT and explore to what extent domain knowledge can be transferred across languages. They find that it is hard to decouple language knowledge from domain knowledge and that adapters often cause the ‘off-target’ problem (i.e., translating into a wrong target language (Zhang et al., 2020)) when new domains and new language pairs are combined together. They address this problem by using additional in-domain monolingual data to generate synthetic data (i.e., back-translation; Senstrich et al., 2016) and randomly dropping some domain adapter layers (AdapterDrop; Rücklé et al., 2021).

Motivated by Cooper Stickland et al. (2021a),

¹Our source code is available at https://github.com/lavine-lmu/m4Adapter
we consider a challenging scenario: adapting a
MNMT model to multiple new domains and new
language directions simultaneously in low-resource
settings without using extra monolingual data for
back-translation. This scenario could arise when
one tries to translate a domain-specific corpus with
a commercial translation system. Using our ap-
proach, we adapt a model to a new domain and
a new language pair using just 500 domain- and
language-specific sentences.

To this end, we propose $m^4$Adapter
(Multilingual Multi-Domain Adaptation for
Machine Translation with Meta-Adapter), which
facilitates the transfer between different domains
and languages using meta-learning (Finn et al.,
2017) with adapters. Our hypothesis is that we
can formulate the task, which is to adapt to new
languages and domains, as a multi-task learning
problem (and denote it as $D_1,L_1,L_2$, which stands
for translating from a language $L_1$ to a language
$L_2$ in a specific domain $D_1$). Our approach is
two-step: initially, we perform meta-learning with
adapters to efficiently learn parameters in a shared
representation space across multiple tasks using
a small amount of training data (5000 samples);
we refer to this as the meta-training step. Then,
we fine-tune the trained model to a new domain
and language pair simultaneously using an even
smaller dataset (500 samples); we refer to this as
the meta-adaptation step.

In this work, we make the following con-
tributions: i) We present $m^4$Adapter, a meta-
learning approach with adapters that can easily
adapt to new domains and languages using a sin-
gle MNMT model. Experimental results show
that $m^4$Adapter outperforms strong baselines. ii)
Through an ablation study, we show that using
$m^4$Adapter, domain knowledge can be transferred
across languages and language knowledge can also
be transferred across domains without using target-
language monolingual data for back-translation (un-
like the work of Cooper Stickland et al., 2021a).
iii) To the best of our knowledge, this paper is
the first work to explore meta-learning for MNMT
adaptation.

2 Related Work

Domain Adaptation in NMT. Existing work on
domain adaptation for machine translation can be
categorized into two types: data-centric and model-
centric approaches (Chu and Wang, 2018). The
former focus on maximizing the use of in-domain
monolingual, synthetic, and parallel data (Domhan
and Hieber, 2017; Park et al., 2017; van der Wees
et al., 2017), while the latter design specific training
objectives, model architectures or decoding algo-
rithms for domain adaptation (Khayrallah et al.,
2017; Gu et al., 2019; Park et al., 2022). In the
case of MNMT, adapting to new domains is more
challenging because it needs to take into account
transfer between languages (Chu and Dabre, 2019;
Cooper Stickland et al., 2021a).

Meta-Learning for NMT. Meta-learning (Finn
et al., 2017), which aims to learn a generally use-
ful model by training on a distribution of tasks, is
highly effective for fast adaptation and has recently
been shown to be beneficial for many NLP tasks
(Lee et al., 2022). Gu et al. (2018) first introduce a
model-agnostic meta-learning algorithm (MAML;
Finn et al., 2017) for low-resource machine trans-
lation. Sharaf et al. (2020), Zhan et al. (2021) and
Lai et al. (2022) formulate domain adaptation for
NMT as a meta-learning task, and show effective
performance on adapting to new domains. Our ap-
proach leverages meta-learning to adapt a MNMT
model to a new domain and to a new language pair
at the same time.

Adapters for NMT. Bapna and Firat (2019) train
language-pair adapters on top of a pre-trained
generic MNMT model, in order to recover lost
performance on high-resource language pairs com-
pared to bilingual NMT models. Philip et al. (2020)
train adapters for each language and show that
adding them to a trained model improves the per-
formance of zero-shot translation. Chronopoulou
et al. (2022) train adapters for each language fam-
sily and show promising results on multilingual ma-
chine translation. Cooper Stickland et al. (2021b)
train language-agnostic adapters to efficiently fine-
tune a pre-trained model for many language pairs.
More recently, Cooper Stickland et al. (2021a)
stack language adapters and domain adapters on
top of an MNMT model and they conclude that it is
not possible to transfer domain knowledge across
languages, except by employing back-translation
which requires significant in-domain resources. In
this work, we introduce adapters into the meta-
learning algorithm and show that this approach per-
mits transfer between domains and languages.

Our work is mostly related to Cooper Stickland
et al. (2021a), however we note several differences:
i) we study a more realistic scenario: the corpus
of each domain and language pair is low-resource (i.e., the meta-training corpus in each domain for each language pair is limited to 5000 sentences and the fine-tuning corpus to 500 sentences), which is easier to obtain; ii) our approach can simultaneously adapt to new domains and new language pairs without using back-translation. iii) we also show that \( m^4 \) Adapter can transfer domain information across different languages and language knowledge across different domains through a detailed ablation analysis.

3 Method

Our goal is to efficiently adapt an MNMT model to new domains and languages. We propose a novel approach, \( m^4 \) Adapter, which formulates the multilingual multi-domain adaptation task as a multi-task learning problem. To address it, we propose a 2-step approach, which combines meta-learning and meta-adaptation with adapters. Our approach permits sharing parameters across different tasks. The two steps are explained in Subsections 3.1 and 3.2.

3.1 Meta-Training

The goal of meta-learning is to obtain a model that can easily adapt to new tasks. To this end, we meta-train adapters in order to find a good initialization of our model’s parameters using a small training dataset of source tasks \( \{T_1, \ldots, T_i\} \).

We first select \( m \) tasks, as we describe in §3.1.1. Then, for each of the \( m \) sampled tasks, we sample \( n \) examples. We explain the task sampling strategy in §3.1.2. This way, we set up the \( m \)-way-\( n \)-shot task. After setting up the task, we use a meta-learning algorithm, which we describe in §3.1.3, to meta-learn the parameters of the adapter layers. The architecture of the adapters and their optimization objective are presented in §3.1.4. Algorithm 1 details the meta-training process of our approach.

3.1.1 Task Definition

Motivated by the work of Tarunesh et al. (2021), where a multilingual multi-task NLP task is regarded as a Task-Language Pair (TLP), we address multilingual multi-domain translation as a multi-task learning problem. Specifically, a translation task in a specific textual domain corresponds to a Domain-Language-Pair (DLP). For example, an English-Serbian translation task in the ‘Ubuntu’ domain is denoted as a DLP ‘Ubuntu-en-sr’. Given \( d \) domains and \( l \) languages, we have \( d \cdot l \cdot (l - 1) \) tasks of this form.\(^2\) We denote the proportion of the dataset size of all DLPs for the \( i^{th} \) DLP as \( s_i = \frac{|D_{\text{train}}^{i}|}{(\sum_{n=1}^{n}|P_{\text{train}}^{n}|)} \), where \( s_i \) will be used in temperature-based sampling (see more details in §3.1.2). The probability of sampling a batch from the \( i^{th} \) DLP during meta-training is denoted as \( P_D(i) \). The distribution over all DLPs, is a multinomial (which we denote as \( M \)) over \( P_D(i) \): \( P(i) \sim \mathcal{M} \).

3.1.2 Task Sampling

Given \( d \) domains and \( l \) languages, we sample some DLPs per batch among all \( d \cdot l \cdot (l - 1) \) tasks. We consider a standard \( m \)-way-\( n \)-shot meta-learning scenario: assuming access to \( d \cdot l \cdot (l - 1) \) DLPs, a \( m \)-way-\( n \)-shot task is created by first sampling \( m \) DLPs (\( m \ll d \cdot l \cdot (l - 1) \)); then, for each of the \( m \) sampled DLPs, \( (n + q) \) examples of each DLP are selected; the \( n \) examples for each DLP serve as the support set to update the parameter of pre-trained model, while \( q \) examples constitute the query set to evaluate the model.

Task sampling is an essential step for meta-learning. Traditional meta-learning methods sample the tasks uniformly (Sharaf et al., 2020), through ordered curriculum (Zhan et al., 2021), or dynamically adjust the sampled dataset according to the model parameters (parameterized sampling strategy, Tarunesh et al., 2021). We do not employ these strategies for the following reasons: i) sampling uniformly is simple but does not consider the distribution of the unbalanced data; ii) Although effective, curriculum-based and parameterized sampling consider features of all \( d \cdot l \cdot (l - 1) \) DLPs. Because of this, the amount of DLPs is growing exponentially with the number of languages and domains. In contrast, we follow a temperature-based heuristic sampling strategy (Aharoni et al., 2019), which defines the probability of any dataset as a function of its size. Specifically, given \( s_i \) as the percentage of the \( i^{th} \) DLP in all DLPs, we compute the following probability of the \( i^{th} \) DLP to be sampled:

\[
P_D(i) = s_i^{1/\tau} / \left( \sum_{a=1}^{n} s_a^{1/\tau} \right)
\]

where \( \tau \) is a temperature parameter. \( \tau = 1 \) means that each DLP is sampled in proportion to the size of the corresponding dataset. \( \tau \rightarrow \infty \) refers to sampling DLPs uniformly.

\(^2\) Given \( l \) languages, we focus on complete translation between \( l \cdot (l - 1) \) language directions.
Figure 1: $m^4$Adapter architecture.

3.1.3 Meta-Learning Algorithm

Given $\theta$ as the parameters of the pre-trained model, $\psi$ as the parameters of the adapters, MAML aims to minimize the following objective:

$$\min_{\psi} \sum_{T_i \sim \mathcal{M}} \mathcal{L}_i \left( U^k_i(\theta, \psi) \right)$$

where $\mathcal{M}$ is the multinomial distribution over DLPs, $\mathcal{L}_i$ is the loss function and $U^k_i$ is a function which keeps $\theta$ frozen and only returns $\psi$ after $k$ gradient updates calculated on batches sampled from $T_i$. Note that, to minimize this goal, the traditional MAML algorithm requires computing gradients of the form $\frac{\partial}{\partial \psi} U^k_i(\psi)$, which leads to the costly computation of second-order derivatives. To this end, we follow Reptile (Nichol et al., 2018), an alternative first-order meta-learning algorithm that uses a simple update rule:

$$\psi \leftarrow \psi + \beta \frac{1}{| \{ T_i \} |} \sum_{T_i \sim \mathcal{M}} (\psi^i(k) - \psi)$$

where $\psi^i(k)$ is $U^k_i(\theta, \psi)$ and $\beta$ is a hyper-parameter. Despite its simplicity, it was recently shown that Reptile is at least as effective as MAML in terms of performance (Dou et al., 2019). We therefore employ Reptile for meta-learning in our experiments.

3.1.4 Meta-Adapter

Adapters (Swietojanski and Renals, 2014; Vilar, 2018; Houlsby et al., 2019) are lightweight feed-forward modules. They are described by the following Equation: $W_{up} f(W_{down} \text{LN}(h)) + h$. An adapter consists of a layer normalization $\text{LN}(\cdot)$ (Ba et al., 2016) of the input $h$, which is passed to a down-projection $W_{down} \in \mathbb{R}^{z \times d}$, a non-linear activation $f(\cdot)$ (in our case, ReLU) and an up-projection $W_{up} \in \mathbb{R}^{d \times z}$, where $d$ is the bottleneck dimension of the adapter module and the only tunable hyperparameter. The output is combined with a residual connection. Adapters are added between sub-layers of a pre-trained Transformer (Vaswani et al., 2017) model (see the right part of Figure 1), usually after the feed-forward layer.

Using adapters is appealing for multiple reasons: i) we only update the adapter parameters $\psi$ during the whole fine-tuning process, which makes training faster especially for large pre-trained models; ii) they obtain a performance comparable to that of traditional fine-tuning. However, as the adapter parameters $\psi$ are randomly initialized they may not perform well in the few-shot setting. Moreover, adding a new set of adapters for each domain or language pair (Bapna and Firat, 2019; Cooper Stickland et al., 2021a) quickly becomes inefficient when we need to adapt to many new domains and language pairs. To address this problem, we propose training a Meta-Adapter, which inserts adapter layers into the meta-learning training process (see the left part of Figure 1). Different from the traditional adapter training process, we only need to train a single meta-adapter to adapt to all new language pairs and domains.

Let $\theta$ denote the parameters of the pre-trained model and $\psi$ the parameters of the adapter. Given a target task $\mathcal{T}$ in the domain $\mathcal{D}_\mathcal{T}$ and a loss function $\mathcal{L}_\mathcal{T}(\cdot)$, we train a meta-adapter to minimize the following objective through gradient descent:

$$\min_{\psi} \mathcal{L}_\mathcal{T} (\theta; \psi; \mathcal{D}_\mathcal{T})$$

where the parameters of pre-trained model $\theta$ are frozen and the adapter parameters $\psi$ are randomly initialized, leading to a size of $\psi \ll \theta$. This makes our approach more efficient than meta-learning an entire model (see more details in Section 6.1).

3.2 Meta-Adaptation

After the meta-training phase, the parameters of the adapter are fine-tuned to adapt to new tasks (as
Algorithm 1 $m^4$Adapter (Multilingual Multi-Domain Adaptation with Meta-Adapter)

**Input:** $D_{\text{train}}$ set of DLPs for meta training; Pre-trained MNMT model $\theta$

1: Initialize $P_D(i)$ based on temperature sampling
2: while not converged do
3:   $>$ Perform Reptile Updates
4:   Sample $m$ DLPs $T_1, T_2, \ldots, T_m$ from $\mathcal{M}$
5:   for $i = 1, 2, \ldots, m$ do
6:     $\psi^{(k)}_i \leftarrow U_i^k(\theta, \psi)$, denoting $k$ gradient updates from $\psi$ on batches of DLP $T_i$
7:     while keeping $\theta$ frozen
8:     $\psi \leftarrow \psi + \beta \sum_{i=1}^{m} (\psi^{(k)}_i - \psi)$
9:   end for
10: return Meta-Adapter parameter $\psi$

both the domain and language pair of interest are not seen during the meta-training stage) using a small amount of data to simulate a low-resource scenario.

We find that this step is essential to our approach, as it permits adapting the parameters of the meta-learned model to the domain and language pair of interest. This step uses a very small amount of data (500 samples), which we believe could realistically be available for each DLP.

4 Experiments

**Datasets.** We split the datasets in two groups: meta-training or training dataset (used in step 1, § 3.1) and meta-adapting or adapting dataset (used in step 2, § 3.2). We first meta-learn the adapters on the training dataset (that contains DLPs different to the ones we will evaluate on), then fine-tune to new domains and language pairs on the adapting dataset (a small dataset of the DLPs we will evaluate on). This step uses a very small amount of data (500 samples), which we believe could realistically be available for each DLP.

We preprocess all data using sentencepiece (Kudo and Richardson, 2018). More details for the data used in this paper can be found in the Appendix A.1.

**Evaluation.** We measure case-sensitive detokenized BLEU with SacreBLEU (Post, 2018). For

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\[^5\text{https://github.com/google/sentencepiece}\]
\[^6\text{https://github.com/huggingface/transformers}\]
\[^7\text{https://github.com/microsoft/DeepSpeed}\]
\[^8\text{https://github.com/mjpost/sacrebleu}\]
Chinese we use the SacreBLEU tokenizer (tok zh) and convert all traditional characters generated by the model to simplified characters using HanziConv. We also evaluate our models using chrF (Popović, 2015) due to the recent criticism of BLEU score (Mathur et al., 2020); the results are listed in the Appendix A.3.1.

## 5 Results

Our goal is to evaluate the adaptability of \( m^4 \text{Adapter} \) on a variety of new domains and new language pairs simultaneously. In the meta-training stage, we perform meta-learning of the model on 180 DLPs, which contain 6 domains (EUbookshop, KDE, OpenSubtitles, QED, TED, Ubuntu) and 30 language pairs (en, et, mk, sr, hr, hu), comparing our approach to different baseline systems. In the meta-adaptation stage, we fine-tune both our model and the baselines to 3 domains (UN, Tanzil, Infopankki) and 30 language pairs (using ar, en, es, fr, ru, zh) of the same dataset simultaneously. Table 1 shows the results in the meta-training step and Table 2 presents the main results of our model in the meta-adaptation step compared to the baselines (results for all DLPs are in Appendix A.3.2).

Motivated by Lai et al. (2022), we compare our approach to multiple baselines in terms of domain robustness. As shown in Table 1, \( m^4 \text{Adapter} \) obtains a performance that is on par or better than agnostic-adapter, which is a robust model. Note that \( m^4 \text{Adapter} \) also outperforms m2m+tag, which was shown to be the most robust model in Cooper Stickland et al. (2021a). After showing empirically that we obtain a robust model, we verify its adaptability (see Table 2 and § 6.2.1) and language transfer ability (§ 6.2.2) through a series of experiments.

As shown in Table 2, \( m^4 \text{Adapter} \) performs well when adapting to the meta-adaptation domains and language pairs at the same time. We observe that no baseline system outperforms the original m2m model. This implies that these models are unable to transfer language or domain knowledge from the MNMT model. One possible explanation is that these models already exhibit over-fitting and catastrophic forgetting when trained on meta-training domains and language pairs in such limited resource scenarios.

Because of the unpredictability of the baseline systems’ performance, it is difficult to draw reliable conclusions. For example, in the UN domain, meta-learning is on par with the original m2m model. However, performance on Tanzil and Infopankki is much worse than the one of the original m2m model. The agnostic-adapter also performs comparably with the original m2m model in the same domains, which shows that it is a robust model. Still, it obtains much worse performance on UN. In contrast, \( m^4 \text{Adapter} \) has a more stable performance when adapting to new domains and language pairs.

In addition, \( m^4 \text{Adapter} \) has the ability to improve the performance of some DLPs on which baseline models obtain extremely low BLEU scores, especially in some distant domains. For example, in Tanzil-ar-ru, the traditional meta-learning method only gets 1.70 BLEU score, while \( m^4 \text{Adapter} \) gets 4.33.

## 6 Analysis

In this section, we conduct additional experiments to better understand the strengths of \( m^4 \text{Adapter} \). We first investigate the benefits in terms of speed in \( m^4 \text{Adapter} \) training and adapting (Section 6.1), then investigate the cross-lingual domain transfer and cross-domain language transfer through an ablation study (Section 6.2).

### 6.1 Efficiency of \( m^4 \text{Adapter} \)

We compare the efficiency of baselines to traditional fine-tuning and list their number of trainable parameters and training/adapting time in Table 3. \( m^4 \text{Adapter} \) only updates the adapter parameters while freezing the MNMT model's parameters (just like agnostic-adapter). Therefore, it has fewer trainable parameters compared to fine-tuning (0.75% of the parameters of the entire model).
6.2.1 Domain Transfer via Languages

To investigate the capacity of our models to transfer domain knowledge across different languages, we define domain transfer via languages, i.e., the ability to transfer domains while keeping the languages unchanged. We first fine-tune the MNMT model in some of the meta-training domains under the specified language pair, and then we adapt these trained models to new meta-adaptation domains of the same language pair. To be more specific, we first choose 6 languages (en, et, mk, sr, hr, hu), forming 30 language pairs. Then, we choose six of these seven domains (EUbookshop, KDE, OpenSubtitles, QED, TED, Ubuntu, Bible) across all selected 30 language pairs as the meta-training dataset (180 DLPs) to fine-tune the MNMT model, and another one domain as the adapting domain across all selected language pairs (30 DLPs) to evaluate the adaptability of the fine-tuned MNMT model to the new domain. Table 4 provides the results for domain transfer across languages.

From Table 4, we observe that almost all baseline systems and \(m^4\)Adapter outperform the original m2m model (except for the EUbookshop domain), indicating that the model encodes language knowledge and can transfer this knowledge to new meta-adaptation domains. Our approach is comparable to the performance of agnostic-adapter, which performs the best among all baseline systems.

We also discover that domain transfer through languages is desirable in some distant domains. For example, the original m2m model only got BLEU scores of 2.01 and 19.01 in the Bible and OpenSubtitles domain (hr-sr language pair). However, domain transfer through \(m^4\)Adapter resulted in a considerable performance boost and achieved a BLEU score of 13.69 and 54.30.

We notice that none of the baselines outperforms the original m2m model in the EUbookshop domain, which means that the language knowledge learned from the baseline model does not transfer to this particular domain. Our approach, on the other hand, has a strong domain transfer ability. We investigated the reason, which was caused

Table 2: Main results on the meta-adaptation stage: average BLEU scores on all DLPs with different adaptation domain (left) and BLEU scores on some examples of specific DLP (right). \(\Delta\) denotes improvement over m2m.

| Method          | #Param. | Time\(_F\) | Time\(_A\) |
|-----------------|---------|------------|------------|
| m2m             | 418M (100%) | -         | -         |
| m2m + FT        | 418M (100%) | 100%       | 100%       |
| m2m + tag       | 418M (100%) | 100%       | 100%       |
| agnostic-adapter| 3.17M (0.75%) | 42%       | 150%      |
| stack-adapter   | 3.17M (k: 0.75%) | 42%       | 200%      |
| meta-learning   | 418M (100%) | 75%       | 500%      |
| \(m^4\)Adapter  | 3.17M (0.75%) | 34%       | 300%      |

Table 3: Number of trainable parameters and Training/Adapting time relative to fine-tuning. \(k\) denotes the number of DLPs during the training process.
Similarly, m4Adapter has demonstrated significant language transfer ability in distant domains. In contrast, adapter-based methods (agnostic-adapter and m4Adapter) permit cross-lingual transfer across domains. m4Adapter shows a performance that is on par or better than the agnostic-adapter, the most competitive model in all baseline systems. The results of the stack-adapter show that it cannot perform language transfer across domains through naively stacking domain adapters and language adapters. This is consistent with the conclusions of Cooper Stickland et al. (2021a).

Similarly, m4Adapter has demonstrated significant language transfer ability in distant domains. In traditional fine-tuning approaches (m2m+FT, m2m+tag) are poorer than the original m2m model, which means that these methods do not transfer the learned domain knowledge to the new meta-adaptation language pair. This meets our expectation since m2m is trained on a big dataset and learns a great quantity of linguistic information, which limits its capacity to transfer language information in small datasets. This explanation can be demonstrated by the results of the meta-learning approach. As shown in Table 5, meta-learning yields slightly higher BLEU scores compared to the original m2m model, which arguably supports the conclusion that the original m2m model already has strong linguistic information. These small improvements from meta-learning can be attributed to leveraging the limited data available.

In contrast, adapter-based methods (agnostic-adapter and m4Adapter) permit cross-lingual transfer across domains. m4Adapter shows a performance that is on par or better than the agnostic-adapter, the most competitive model in all baseline systems. The results of the stack-adapter show that it cannot perform language transfer across domains through naively stacking domain adapters and language adapters. This is consistent with the conclusions of Cooper Stickland et al. (2021a).
ubuntu-de-en, for example, $m^4$ Adapter achieves a BLEU score of 43.24, which is significantly higher than the original m2m model’s BLEU of 30.65.

7 Conclusion

We present $m^4$ Adapter, a novel multilingual multi-domain NMT adaptation framework which combines meta-learning and parameter-efficient fine-tuning with adapters. $m^4$ Adapter is effective on adapting to new languages and domains simultaneously in low-resource settings. We find that $m^4$ Adapter also transfers language knowledge across domains and transfers domain information across languages. In addition, $m^4$ Adapter is efficient in training and adaptation, which is practical for online adaptation (Etchegoyhen et al., 2021) to complex scenarios (new languages and new domains) in the real world.

8 Limitations

This work has two main limitations. i) We have only evaluated the proposed method on limited and balanced bilingual training data to simulate the low-resource scenario. However, some domains in our setting are in fact highly imbalanced. ii) We only evaluated $m^4$ Adapter on machine translation, perhaps it would be plausible to expand our method to other NLP tasks, such as text generation or language modeling. Since our framework leverages a multilingual pretrained model and only trains adapters, we believe it could easily be applied to other tasks besides MT.

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A Appendix

A.1 Datasets

All datasets used in our experiments are publicly available on OPUS. Despite the fact that OPUS contains corpora from various domains and languages, some recent works (Aharoni and Goldberg, 2020; Lai et al., 2022) have raised concerns about using OPUS corpora as they can be noisy. We therefore performed the following cleaning and filtering preprocess on the original OPUS corpus: i) remove sentences that contain more than 50% punctuation; ii) to ensure that the training set did not contain any corpora from the validation or test sets, all corpora were de-duplicated; iii) sentences longer than 175 tokens were removed; iv) we used a language detection tool\footnote{https://fasttext.cc/docs/en/language-identification.html} (langid) to filter out sentences with mixed languages.

As described in Section 4, during the training phase, although most of the DLPs were limited to a maximum of 5000 sentences, there was still a fraction of DLPs with a corpus of less than 5000 samples which we list in Table 6.

A.2 Model Configuration

Our $m^4$Adapter model is trained in the following way: it firstsamples $m$ tasks based on temperature $\tau$, then makes $k$ gradient updates for each task $T_i$. Finally, it updates the parameters of $\psi$. In our set of experiments, we use the AdamW (Loshchilov and Hutter, 2018) optimizer, which is shared across all DLPs. We fix the initial learning rate to $5e^{-5}$ with a dropout probability 0.1. In our experiments, we consider values of $m \in \{4, 8, 16\}$, $k \in \{1, 2, 3, 4, 5\}$, $\alpha \in \{0.1, 0.5, 1.0\}$ and $\tau \in \{1, 2, 5, \infty\}$

A.3 Additional Results

A.3.1 chrF Evaluation

In addition to BLEU, we also use chrF (Popović, 2015) as an evaluation metric. Tables 9, 10 and 11 show the results. $m^4Adapter$ is more effective than all baseline systems in terms of chrF, which is consistent with the BLEU scores (that were presented in Tables 2, 4 and 5).

A.3.2 Results on all DLPs

Figure 2 reports the results for all DLPs, which is consistent with the results in Tables 2 and 9.

A.4 Analysis

To better understand our proposed method, we investigate the effect of different parameter settings on the results (as described in Section 3.1.2). We also analyse the poor results on EUbookshop domain as described in Section 6.2.1.
Table 8: Different amounts of shots.

| shots   | avg BLEU |
|---------|----------|
| 2-shots | 23.80    |
| 4-shots | 23.88    |
| 8-shots | **23.89**|
| 16-shots| 23.85    |
| 32-shots| 23.88    |

A.4.1 Effect of temperature sampling
Although the meta-training data of all DLPs is limited to a maximum of 5000 sentences, there are still some DLPs with less than 5000 sentences, so we use temperature sampling for each setting for $\tau = 1, 2, 5$ and $\infty$. We first sample the task-based temperature and show the results in Table 7. We notice that the performance of the various temperature settings is very similar. These results meet our expectation as the data we used was limited to a maximum of 5000 sentences in most DLPs, with the exception of some DLPs in the EUbookshop and Ubuntu domains (see Appendix A.1), which means data is sampled uniformly in different temperature settings.

A.4.2 Effect of different shots
We also test the performance on different numbers of shots ($n = 2, 4, 6, 8, 16$) and show the results in Table 8. Interestingly, we observe that $m^4$Adapter is not sensitive to different numbers of shots, unlike other NLP (Chen et al., 2022) and Computer Vision tasks (Finn et al., 2017) which use the meta-learning approach. We argue that this is because the meta-adapter is randomly initialized at each batch, resulting in a gap between training and inference. Narrowing this gap is an important future research direction.

A.5 Analysis on EUbookshop domain
As described in Section 6.2.1, we observed that all baseline systems overfit when trained on data from the EUbookshop domain. For example, in the case of the $m2m + FT$ baseline, the training loss converges and stops improving at a very early stage. After that, the model overfits the validation set (Figure 2). On the contrary, the training loss of the $m^4$Adapter does not show signs of overfitting. This is probably due to the much smaller number of parameters that our proposed model trains.
|         | (a) m2m     |         | (b) m2m + FT |         | (c) m2m + tag |         | (d) agnostic-adapter |         | (e) stack-adapter |
|---------|-------------|---------|--------------|---------|--------------|---------|----------------------|---------|-------------------|
| UN      | 38.94       | 33.14   | 30.75        | 22.96   | 28.78        | 43.96   | 37.52                | 32.29   | 32.04             |
| Infopankki | 6.44       | 4.26    | 7.76         | 3.64    | 6.04         | 12.26   | 14.14                | 5.59    | 10.56            |
|         | 22.57       | 18.59   | 21.94        | 15.05   | 13.14        | 19.38   | 23.7                 | 17.19   | 13.08            |
| (a) m2m | 35.11       | 31.95   | 23.51        | 19.1    | 26.26        | 42.72   | 34.45                | 29.21   | 32.51            |
| Infopankki | 6.85       | 5.77    | 6.99         | 3.03    | 5.18         | 12.79   | 12.61                | 4.26    | 10.78            |
|         | 21.33       | 15.55   | 18.76        | 14.19   | 13.06        | 18.16   | 18.85                | 17.8    | 12.15            |
| (b) m2m + FT | 34.39     | 30.77   | 26.35        | 19.17   | 26.46        | 43.75   | 34.38                | 29.93   | 32.68            |
| Infopankki | 6.63       | 5.37    | 6.88         | 2.65    | 5.17         | 11.47   | 11.8                 | 4.66    | 10.82            |
|         | 20.12       | 14.77   | 18.39        | 13.68   | 14.6         | 19.35   | 20.55                | 16.9    | 13.35            |
| (c) m2m + tag | 36.13     | 31.37   | 28.54        | 20.54   | 29.09        | 41.34   | 31.89                | 28.6    | 31.9             |
| Infopankki | 6.12       | 3.07    | 6.71         | 3.63    | 6.62         | 10.87   | 14.23                | 5.57    | 10.06            |
|         | 23.21       | 18.92   | 21.35        | 14.96   | 13.83        | 20.53   | 22.5                 | 18.4    | 12.96            |
| (d) agnostic-adapter | 35.31   | 30.54   | 26.51        | 19.17   | 26.25        | 43.17   | 34.59                | 29.21   | 32.81            |
| Infopankki | 5.83       | 5.24    | 6.94         | 2.34    | 5.09         | 12.31   | 12.71                | 4.28    | 10.28            |
|         | 22.44       | 18.17   | 22.03        | 13.85   | 13.44        | 19.41   | 23.28                | 17.74   | 13.27            |
| (e) stack-adapter | 38.94  | 33.14   | 30.75        | 22.96   | 28.78        | 43.96   | 37.52                | 32.29   | 32.04            |
| Infopankki | 5.83       | 5.24    | 6.94         | 2.34    | 5.09         | 12.31   | 12.71                | 4.28    | 10.28            |
|         | 22.44       | 18.17   | 22.03        | 13.85   | 13.44        | 19.41   | 23.28                | 17.74   | 13.27            |

| (e) stack-adapter | 4295 |
Figure 2: Main result: BLEU scores in all DLPs

Table 9: Main results on the meta-adaptation stage: average chrF scores on all DLPs with different adaptation domain (left) and chrF scores on some examples of specific DLP (right).

Table 10: Domain transfer via languages: average chrF scores on all DLPs in each meta-adaptation language pair (left) and chrF scores on random select one specific DLP in de-en (right).

Table 11: Language transfer via domains: average chrF scores on all DLPs in each meta-adaptation language pair (left) and chrF scores on one specific DLP in de-en (right).