Event Structure Semantics for Multiparty Sessions

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Abstract

We propose an interpretation of multiparty sessions as \textit{Flow Event Structures}, which allows concurrency within sessions to be explicitly represented. We show that this interpretation is equivalent, when the multiparty sessions can be described by global types, to an interpretation of such global types as \textit{Prime Event Structures}.

Keywords: Communication-centric Systems, Communication-based Programming, Process Calculi, Event Structures, Multiparty Session Types.

1. Introduction

Session types were proposed in the mid-nineties [53, 37], as a tool for specifying and analysing web services and communication protocols. They were first introduced in a variant of the $\pi$-calculus to describe binary interactions between processes. Such binary interactions may often be viewed as client-server protocols. Subsequently, session types were extended to \textit{multiparty sessions} [38, 39], where several participants may interact with each other. A multiparty session is an interaction among peers, and there is no need to distinguish one of the participants as representing the server. All one needs is an abstract specification of the protocol that guides the interaction. This is called the \textit{global type} of the session. The global type describes the behaviour of the whole session, as opposed to the local types that describe the behaviours of single participants. In a multiparty session, local types may be retrieved as projections from the global type.

Typical safety properties ensured by session types are \textit{communication safety} (absence of communication errors), \textit{session fidelity} (agreement with the protocol) and \textit{deadlock-freedom} [39]. When dealing with multiparty sessions, the type system is often enhanced so as to guarantee also the liveness property known as \textit{progress} (no participant gets stuck) [40].

Some simple examples of sessions not satisfying the above properties are: 1) a

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sender emitting a message while the receiver expects a different message (communication error); 2) two participants both waiting to receive a message from the other one (deadlock due to a protocol violation); 3) a three-party session where the first participant waits to receive a message from the second participant, which keeps interacting forever with the third participant (starvation, although the session is not deadlocked).

What makes session types particularly attractive is that they offer several advantages at once: 1) static safety guarantees, 2) automatic check of protocol implementation correctness, based on local types, and 3) a strong connection with linear logics [13, 54, 58, 51, 14], and with concurrency models such as communicating automata [32], graphical choreographies [43, 55] and message-sequence charts [39].

In this paper we further investigate the relationship between multiparty session types and concurrency models, by focussing on Event Structures [62]. We consider a standard multiparty session calculus where sessions are described as networks of sequential processes [32]. Each process implements a participant in the session. We propose an interpretation of such networks as Flow Event Structures (FESs) [8, 10] (a subclass of Winskel’s Stable Event Structures [62]), which allows concurrency between session communications to be explicitly represented. We then introduce global types for these networks, and define an interpretation of them as Prime Event Structures (PESs) [59, 48]. Since the syntax of global types does not allow all the concurrency among communications to be expressed, the events of the associated PES need to be defined as equivalence classes of communication sequences up to permutation equivalence. We show that when a network is typable by a global type, the FES semantics of the former is equivalent, in a precise technical sense, to the PES semantics of the latter. In a companion paper [16], we investigated a similar Event Structure semantics for a session calculus with asynchronous communication, which led to a quite different treatment as it made use of a new notion of asynchronous global type. A detailed comparison with [16] will be given in Section 9.

This paper is an expanded and amended version of [15]. The main novelty is that we use a coinductive definition for processes and global types, which simplifies several definitions and proofs, and a more stringent definition for network events. This definition relies on the new notion of causal set, which is crucial for the correctness of our ES semantics. Finally, the present paper includes all proofs of results, some of which require ingenuity.

The paper is organised as follows. Section 2 introduces our multiparty session calculus. In Section 3 we recall the definitions of PESs and FESs, which will be used to interpret processes (Section 4) and networks (Section 5), respectively. PESs are also used to interpret global types (Section 7), which are defined in Section 6. In Section 8 we prove the equivalence between the FES semantics of a network and the PES semantics of its global type. Section 9 discusses related work and sketches directions for future work. The Appendix contains some technical proofs.
2. A Core Calculus for Multiparty Sessions

We now formally introduce our calculus, where multiparty sessions are represented as networks of processes. We assume the following base sets: session participants, ranged over by $p, q, r, \ldots$ and forming the set Part, and messages, ranged over by $\lambda, \lambda', \ldots$ and forming the set $\text{Msg}$.

Let $\pi \in \{ p!\lambda, p?\lambda \mid p \in \text{Part}, \lambda \in \text{Msg} \}$ denote an action. The action $p!\lambda$ represents an output of message $\lambda$ to participant $p$, while the action $p?\lambda$ represents an input of message $\lambda$ from participant $p$. The participant of an action, $\text{pt}(\pi)$, is defined by $\text{pt}(p!\lambda) = \text{pt}(p?\lambda) = p$.

**Definition 2.1 (Processes).** Processes are defined by:

$$ P ::= \coind \bigoplus_{i \in I} p!\lambda_i; P_i \mid \Sigma_{i \in I} p?\lambda_i; P_i \mid 0 $$

where $I$ is non-empty and $\lambda_h \neq \lambda_k$ for all $h, k \in I, h \neq k$, i.e. messages in choices are all different.

Processes of the shape $\bigoplus_{i \in I} p!\lambda_i; P_i$ and $\Sigma_{i \in I} p?\lambda_i; P_i$ are called output and input processes, respectively.

The symbol ::=, in the definition above and in later definitions, indicates that the productions should be interpreted coinductively. Namely, they define possibly infinite processes. However, we assume such processes to be regular, that is, with finitely many distinct subprocesses. In this way, we only obtain processes which are solutions of finite sets of equations, see [20]. So, when writing processes, we shall use (mutually) recursive equations.

Sequential composition ($;$) has higher precedence than choices ($\bigoplus$, $\Sigma$). When $I$ is a singleton, $\bigoplus_{i \in I} p!\lambda_i; P_i$ will be rendered as $p!\lambda; P$ and $\Sigma_{i \in I} p?\lambda_i; P_i$ will be rendered as $p?\lambda; P$. Trailing 0 processes will be omitted.

In a full-fledged calculus, messages would carry values, namely they would be of the form $\lambda(v)$. For simplicity, we consider only pure messages here. This will allow us to project global types directly to processes, without having to explicitly introduce local types, see Section 6.

Networks are comprised of pairs of the form $p[[P]]$ composed in parallel, each with a different participant $p$.

**Definition 2.2 (Networks).** Networks are defined by:

$$ N = p_1[[P_1]] \parallel \cdots \parallel p_n[[P_n]] \quad n \geq 1, \quad p_h \neq p_k \text{ for any } h, k (1 \leq h, k \leq n). $$

We assume the standard structural congruence $\equiv$ on networks, stating that parallel composition is associative and commutative and has neutral element $p[[0]]$ for any fresh $p$.

If $P \neq 0$ we write $p[[P]] \in N$ as short for $N \equiv p[[P]] \parallel N'$ for some $N'$.

To express the operational semantics of networks, we use an LTS whose labels record the message exchanged during a communication together with its sender and receiver. The set of communications, ranged over by $\alpha, \alpha'$, is defined to be
\[ p \bigoplus_{i \in I} q!\lambda_i; P_i \parallel q\Sigma_{j \in J} p?\lambda_j; Q_j \parallel N \overset{pq\lambda}{\longrightarrow} p[P_k \parallel qQ_k \parallel N \text{ where } k \in I \cap J] \]  

*Figure 1: LTS for networks.*

\[ \{pq\lambda \mid p, q \in \text{Part}, \lambda \in \text{Msg} \}, \text{ where } pq\lambda \text{ represents the emission of a message } \lambda \text{ from participant } p \text{ to participant } q. \]

The LTS semantics of networks is specified by the unique rule [Com] given in Figure 1. Notice that rule [Com] is symmetric with respect to input and output choices. In a well-typed network (see Section 6) it will always be the case that \( I \subseteq J \), ensuring that participant \( p \) can freely choose an output, since participant \( q \) offers all corresponding inputs.

In the following we will make an extensive use of finite (and possibly empty) sequences of communications. As usual we define them as traces.

**Definition 2.3 (Traces).** (Finite) traces \( \sigma \in \text{Traces} \) are defined by:

\[ \sigma ::= e \mid \alpha \cdot \sigma \]

We use \( |\sigma| \) to denote the length of the trace \( \sigma \).

The set of participants of a trace, notation \( \text{part}(\sigma) \), is defined by \( \text{part}(e) = \emptyset \) and \( \text{part}(pq\lambda \cdot \sigma) = \{p, q\} \cup \text{part}(\sigma) \).

When \( \sigma = \alpha_1 \cdot \ldots \cdot \alpha_n \) (\( n \geq 1 \)) we write \( N \overset{\sigma}{\longrightarrow} N' \) as short for \( N \overset{\alpha_1}{\longrightarrow} N_1 \cdots \overset{\alpha_n}{\longrightarrow} N_n = N' \).

### 3. Event Structures

We recall now the definitions of *Prime Event Structure* (PES) from [59, 48] and *Flow Event Structure* (FES) from [8]. The class of FESs is more general than that of PESs: for a precise comparison of various classes of event structures, we refer the reader to [9]. As we shall see in Sections 4 and 5, while PESs are sufficient to interpret processes, the greater generality of FESs is needed to interpret networks.

**Definition 3.1 (Prime Event Structure).** A prime event structure (PES) is a tuple \( S = (E, \leq, \#) \) where:

1. \( E \) is a denumerable set of events;
2. \( \leq \subseteq (E \times E) \) is a partial order relation, called the causality relation;
3. \( \# \subseteq (E \times E) \) is an irreflexive symmetric relation, called the conflict relation, satisfying the property: \( \forall e, e', e'' \in E : e \# e' \leq e'' \Rightarrow e \# e'' \) (conflict hereditariness).

**Definition 3.2 (Flow Event Structure).** A flow event structure (FES) is a tuple \( S = (E, \prec, \#) \) where:

1. \( E \) is a denumerable set of events;
2. \(<\subseteq (E \times E)\) is an irreflexive relation, called the flow relation;

3. \(# \subseteq (E \times E)\) is a symmetric relation, called the conflict relation.

Note that the flow relation is not required to be transitive, nor acyclic (its reflexive and transitive closure is just a preorder, not necessarily a partial order). Intuitively, the flow relation represents a possible direct causality between two events. Moreover, in a FES the conflict relation is not required to be irreflexive nor hereditary; indeed, FESs may exhibit self-conflicting events, as well as disjunctive causality (an event may have conflicting causes).

Any PES \(S = (E, \leq, \#)\) may be regarded as a FES, with \(<\) given by \(<\) (the strict ordering) or by the covering relation of \(\leq\).

We now recall the definition of configuration for event structures. Intuitively, a configuration is a set of events having occurred at some stage of the computation. Thus, the semantics of an event structure \(S\) is given by its poset of configurations ordered by set inclusion, where \(X_1 \subset X_2\) means that \(S\) may evolve from \(X_1\) to \(X_2\).

**Definition 3.3 (PES configuration).** Let \(S = (E, \leq, \#)\) be a prime event structure. A configuration of \(S\) is a finite subset \(X\) of \(E\) such that:

1. \(X\) is downward-closed: \(e' \leq e \in X \Rightarrow e' \in X\);
2. \(X\) is conflict-free: \(\forall e, e' \in X, \neg(e \# e')\).

The definition of configuration for FESs is slightly more elaborated. For a subset \(X\) of \(E\), let \(<_X\) be the restriction of the flow relation to \(X\) and \(<^*_X\) be its transitive and reflexive closure.

**Definition 3.4 (FES configuration).** Let \(S = (E, <, \#)\) be a flow event structure. A configuration of \(S\) is a finite subset \(X\) of \(E\) such that:

1. \(X\) is downward-closed up to conflicts: \(e' < e \in X, e' \notin X \Rightarrow \exists e'' \in X. e' \# e'' < e\);
2. \(X\) is conflict-free: \(\forall e, e' \in X, \neg(e \# e')\);
3. \(X\) has no causality cycles: the relation \(<^*_X\) is a partial order.

Condition (2) is the same as for prime event structures. Condition (1) is adapted to account for the more general – non-hereditary – conflict relation. It states that any event appears in a configuration with a "complete set of causes". Condition (3) ensures that any event in a configuration is actually reachable at some stage of the computation.

If \(S\) is a prime or flow event structure, we denote by \(C(S)\) its set of configurations. Then, the domain of configurations of \(S\) is defined as follows:

**Definition 3.5 (ES configuration domain).** Let \(S\) be a prime or flow event structure with set of configurations \(C(S)\). The domain of configurations of \(S\) is the partially ordered set \(\mathcal{D}(S) =_{def} (C(S), \subseteq)\).
We recall from [9] a useful characterisation for configurations of FESs, which is based on the notion of proving sequence, defined as follows:

**Definition 3.6 (Proving sequence).** Given a flow event structure \( S = (E, \prec, \#) \), a proving sequence in \( S \) is a sequence \( e_1; \cdots; e_n \) of distinct non-conflicting events (i.e. \( i \neq j \Rightarrow e_i \neq e_j \) and \( \neg(e_i \# e_j) \) for all \( i, j \)) satisfying:

\[
\forall i \leq n \forall e \in E : \ e < e_i \Rightarrow \exists j < i. \ either \ e = e_j \ or \ e \# e_j < e_i
\]

Note that any prefix of a proving sequence is itself a proving sequence.

We have the following characterisation of configurations of FESs in terms of proving sequences.

**Proposition 3.7 (Representation of FES configurations as proving sequences [9]).** Given a flow event structure \( S = (E, \prec, \#) \), a subset \( X \) of \( E \) is a configuration of \( S \) if and only if it can be enumerated as a proving sequence \( e_1; \cdots; e_n \).

Since PESs may be viewed as particular FESs, we may use Definition 3.6 and Proposition 3.7 both for the FESs associated with networks (see Sections 5) and for the PESs associated with global types (see Section 7). Note that for a PES the condition of Definition 3.6 simplifies to

\[
\forall i \leq n \forall e \in E : \ e < e_i \Rightarrow \exists j < i. \ e = e_j
\]

To conclude this section, we recall from [17] the definition of downward surjectivity (or downward-onto, as it was called there), a property that is required for partial functions between two FESs in order to ensure that they preserve configurations. We will make use of this property in Section 5.

**Definition 3.8 (Downward surjectivity).** Let \( S_i = (E_i, \prec_i, \#_i) \), be a flow event structure, \( i = 0, 1 \). Let \( e, e' \) range over \( E_i \), \( i = 0, 1 \). A partial function \( f : E_0 \rightarrow E_1 \) is downward surjective if it satisfies the condition:

\[
e_1 \prec_1 f(e_0) \implies \exists e'_0 \in E_0. \ e_1 = f(e'_0)
\]

4. Event Structure Semantics of Processes

In this section, we define an event structure semantics for processes, and show that the obtained event structures are PESs. This semantics will be the basis for defining the ES semantics for networks in Section 5. We start by introducing process events, which are non-empty sequences of actions.

**Definition 4.1 (Process event).** Process events \( \eta, \eta' \), also called p-events, are defined by:

\[
\eta ::= \pi \mid \pi \cdot \eta \quad \pi \in \{p!\lambda, p?\lambda \mid p \in \text{Part}, \lambda \in \text{Msg}\}
\]

We denote by \( \mathcal{PE} \) the set of p-events, and by \( |\eta| \) the length of the sequence of actions in the p-event \( \eta \).
Let \( \zeta \) denote a (possibly empty) sequence of actions, and \( \sqsubseteq \) denote the prefix ordering on such sequences. Each p-event \( \eta \) may be written either in the form \( \eta = \pi \cdot \zeta \) or in the form \( \eta = \zeta \cdot \pi \). We shall feel free to use any of these forms. When a p-event is written as \( \eta = \zeta \cdot \pi \), then \( \zeta \) may be viewed as the causal history of \( \eta \), namely the sequence of past actions that must have happened in the process for \( \eta \) to be able to happen.

We define the action of a p-event to be its last action:

\[
\text{act}(\zeta \cdot \pi) = \pi
\]

**Definition 4.2 (Causality and conflict relations on process events).** The causality relation \( \leq \) and the conflict relation \( \# \) on the set of p-events \( \mathcal{PE} \) are defined by:

1. \( \eta \sqsubseteq \eta' \Rightarrow \eta \leq \eta' \);
2. \( \pi \neq \pi' \Rightarrow \zeta \cdot \pi \cdot \zeta' \# \zeta \cdot \pi' \cdot \zeta'' \).

**Definition 4.3 (Event structure of a process).** The event structure of process \( P \) is the triple

\[
S^P(P) = (\mathcal{PE}(P), \leq_P, \#_P)
\]

where:

1. \( \mathcal{PE}(P) \subseteq \mathcal{PE} \) is the set of non-empty sequences of labels along the nodes and edges of a path from the root to an edge in the tree of \( P \);
2. \( \leq_P \) is the restriction of \( \leq \) to the set \( \mathcal{PE}(P) \);
3. \( \#_P \) is the restriction of \( \# \) to the set \( \mathcal{PE}(P) \).

It is easy to see that \( \#_P = (\mathcal{PE}(P) \times \mathcal{PE}(P)) \setminus (\leq_P \cup \geq_P) \). In the following we shall feel free to drop the subscript in \( \leq_P \) and \( \#_P \).

Note that the set \( \mathcal{PE}(P) \) may be denumerable, as shown by the following example.

**Example 4.4.** If \( P = q!\lambda; P + q!\lambda' \), then \( \mathcal{PE}(P) = \{ q!\lambda \cdot \ldots \cdot q!\lambda \mid n \geq 1 \} \cup \{ q!\lambda \cdot \ldots \cdot q!\lambda \cdot q!\lambda' \mid n \geq 0 \} \).

**Proposition 4.5.** Let \( P \) be a process. Then \( S^P(P) \) is a prime event structure.

**Proof** We show that \( \leq \) and \( \# \) satisfy Properties 2 and 3 of Definition 3.1. Reflexivity, transitivity and antisymmetry of \( \leq \) follow from the corresponding properties of \( \sqsubseteq \). As for irreflexivity and symmetry of \( \# \), they follow from Clause 2 of Definition 4.2 and the corresponding properties of inequality. To show conflict hereditariness, suppose that \( \eta \# \eta' \leq \eta'' \). From Clause 2 of Definition 4.2 there are \( \pi, \pi', \zeta, \zeta' \) and \( \zeta'' \) such that \( \pi \neq \pi' \) and \( \eta = \zeta \cdot \pi \cdot \zeta' \) and \( \eta' = \zeta \cdot \pi' \cdot \zeta'' \). From \( \eta' \leq \eta'' \) we derive that \( \eta'' = \zeta \cdot \pi' \cdot \zeta'' \cdot \zeta_1 \) for some \( \zeta_1 \). Therefore \( \eta \# \eta'' \), again from Clause 2.
5. Event Structure Semantics of Networks

In this section we define the ES semantics of networks and show that the resulting ESs, which we call network ESs, are FESs. We also show that when the network is binary, namely when it has only two participants, then the obtained FES is a PES. The formal treatment involves defining the set of potential events of network ESs, which we call network events, as well as introducing the notion of causal set of a network event and the notion of narrowing of a set of network events. This will be the subject of Section 5.1.

In Section 5.2 we first prove some properties of the conflict relation in network ESs. Then, we come back to causal sets and we show that they are always finite and that each configuration includes a unique causal set for each of its n-events. We also discuss the relationship between causal sets and prime configurations, which are specific configurations that are in 1-1 correspondence with events in ESs. Finally, we define a notion of projection from n-events to p-events, and prove that this projection (extended to sets of n-events) is downward surjective and preserves configurations.

5.1. Definitions and Main Properties

We start by defining network events, the potential events of network ESs. Since these events represent communications between two network participants p and q, they should be pairs of dual p-events, namely, of p-events emanating respectively from p and q, which have both dual actions and dual causal histories.

Formally, to define network events we need to specify the location of p-events, namely the participant to which they belong:

**Definition 5.1 (Located event).** We call located event a p-event \( \eta \) pertaining to a participant \( p \), written \( p :: \eta \).

As hinted above, network events should be pairs of dual located events \( p :: \zeta \cdot \pi \) and \( q :: \zeta' \cdot \pi' \) with matching actions \( \pi \) and \( \pi' \) and matching histories \( \zeta \) and \( \zeta' \). To formalise the matching condition, we first define the projections of process events on participants, which yield sequences of undirected actions of the form \(!\lambda\) and \(?\lambda\), or the empty sequence \(\epsilon\). Then we introduce a notion of duality between located events, based on a notion of duality between undirected actions.

Let \( \delta \) range over \(!\lambda\) and \(?\lambda\), and \( \Theta \) range over (possibly empty) sequences of \( \delta \)'s.

**Definition 5.2 (Projection of p-events).** The projection of a p-event \( \eta \) on a participant \( p \), written \( \eta^p p \), is defined by:

\[
q!\lambda^p p = \begin{cases} 
!\lambda & \text{if } p = q \\
\epsilon & \text{otherwise}
\end{cases}
\]

\[
q?\lambda^p p = \begin{cases} 
?\lambda & \text{if } p = q \\
\epsilon & \text{otherwise}
\end{cases}
\]

\[
(\pi \cdot \eta)^p p = \pi^p p \cdot \eta^p p
\]

**Definition 5.3 (Duality of undirected action sequences).** The duality of undirected action sequences, written \( \Theta \bowtie \Theta' \), is the symmetric relation induced by:

\[
\epsilon \bowtie \epsilon \quad \Theta \bowtie \Theta' \Rightarrow !\lambda \bowtie ?\lambda \bowtie \Theta'
\]
Definition 5.4 (Duality of located events). Two located events \( p \circ \eta, q \circ \eta' \) are dual, written \( p \circ \eta \quad \bowtie \quad q \circ \eta' \), if \( \eta \bowtie \eta' \) and \( p(\text{act}(\eta)) = q \) and \( p(\text{act}(\eta')) = p \).

Dual located events may be sequences of actions of different length. For instance \( p : q! \lambda \cdot r! \lambda' \bowtie r :: p? \lambda' \) and \( p :: q! \lambda \bowtie q :: r! \lambda' \cdot p? \lambda \).

Definition 5.5 (Network event). Network events \( v, v' \), also called n-events, are unordered pairs of dual located events, namely:

\[
\nu ::= \{ p :: \eta, q :: \eta' \} \quad \text{where} \quad p :: \eta \bowtie q :: \eta'
\]

We denote by \( \mathcal{DE} \) the set of n-events.

We define the communication of the event \( v \), notation \( \text{cm}(v) \), by \( \text{cm}(v) = pq\lambda \) if \( v = \{ p :: \zeta \cdot q! \lambda, q :: \zeta' \cdot p? \lambda \} \) and we say that the n-event \( v \) represents the communication \( pq\lambda \). We also define the set of locations of an n-event to be \( \text{loc}(\{ \nu :: \eta, q :: \eta' \}) = \{ p, q \} \).

It is handy to have a notion of occurrence of a located event in a set of network events:

Definition 5.6. A located event \( p :: \eta \) occurs in a set \( E \) of n-events, notation \( p :: \eta \in E \), if \( p :: \eta \in v \) and \( v \in E \) for some \( v \).

We define now the flow and conflict relations on network events. While the flow relation is the expected one (a network event inherits the causality from its constituent processes), the conflict relation is more subtle, as it can arise also between network events with disjoint sets of locations.

In the following definition we use \( |\Theta| \) to denote the length of the sequence \( \Theta \).

Definition 5.7 (Flow and conflict relations on n-events). The flow relation \( < \) and the conflict relation \( \# \) on the set of n-events \( \mathcal{DE} \) are defined by:

1. \( v < v' \) if \( p :: \eta \in v \) and \( p :: \eta' \in v' \) and \( \eta < \eta' \);
2. \( v \# v' \) if
   
   (a) \( \text{either} \ p :: \eta \in v \) and \( p :: \eta' \in v' \) and \( \eta \# \eta' \);
   
   (b) \( \text{or} \ p :: \eta \in v \) and \( q :: \eta' \in v' \) and \( p \neq q \) and \( |\eta \bowtie q| = |\eta' \bowtie p| \) and \( \neg(\eta \bowtie q \bowtie \eta' \bowtie p) \).

Two n-events are in conflict if they share a participant with conflicting p-events (Clause (2a)) or if some of their participants have communicated with each other in the past in incompatible ways (Clause (2b)). Note that the two clauses are not exclusive, as shown in the following example.

Example 5.8. This example illustrates the use of Definition 5.7 in various cases. It also shows that the flow and conflict relations may be overlapping on n-events.

1. Let \( v = \{ p :: q! \lambda_1 \cdot r! \lambda, r :: p? \lambda \} \) and \( v' = \{ p :: q! \lambda_2, q :: p? \lambda_2 \} \). Then \( v \# v' \) by Clause (2a) since \( q! \lambda_1 \cdot r! \lambda \# q! \lambda_2 \). Note that \( v \# v' \) can be also deduced by Clause (2b), since \( (q! \lambda_1 \cdot r! \lambda) \bowtie q = |q| \lambda_1 \) and \( p? \lambda_2 \bowtie p = |p| \lambda_2 \) and \( |\lambda_1| = |\lambda_2| \) and \( \neg(\lambda_1 \bowtie \lambda_2) \).
2. Let \( v \) be as in (1) and \( \nu' = \{p :: q!\lambda_2 \cdot q!\lambda, q :: p?\lambda_2 \cdot p?\lambda\} \). Again, we can deduce \( \nu \neq \nu' \) using Clause (2a) since \( q!\lambda_1 \cdot r!\lambda \neq q!\lambda_2 \cdot q!\lambda \). On the other hand, Clause (2b) does not apply in this case since \( (q!\lambda_1 \cdot r!\lambda)^p q = !\lambda_1 \) and \( (p?\lambda_2 \cdot p?\lambda)^p p = ?\lambda_2 ?\lambda \) and thus \(|!\lambda_1| \neq |!\lambda_2 ?\lambda| \).

3. Let \( v \) be as in (1) and \( \nu' = \{q :: p?\lambda_2 \cdot s!\lambda, s :: q?\lambda\} \). Here \( \text{loc}(v) \cap \text{loc}(\nu') = \emptyset \), so clearly Clause (2a) does not apply. On the other hand, \( \nu \neq \nu' \) can be deduced by Clause (2b) since \( (q!\lambda_1 \cdot r!\lambda)^p q = !\lambda_1 \) and \( (p?\lambda_2 \cdot s!\lambda)^p p = ?\lambda_2 ?\lambda \) and \(-(!\lambda_1 \Rightarrow ?\lambda_2)\).

4. Let \( v \) be as in (1) and \( \nu' = \{p :: q!\lambda_2 \cdot r!\lambda \cdot r!\lambda', r :: p?\lambda \cdot p?\lambda\} \). In this case we have both \( \nu < \nu' \) by Clause (1) and \( \nu \neq \nu' \) by Clause (2a), namely, causality is inherited from participant \( r \) and conflict from participant \( p \).

We introduce now the notion of causal set of an n-event \( v \) in a given set of events \( Ev \). Intuitively, a causal set of \( v \) in \( Ev \) is a complete set of non-conflicting direct causes of \( v \) which is included in \( Ev \).

**Definition 5.9 (Causal set).** Let \( v \in Ev \subseteq \mathcal{D} \mathcal{E} \). A set of n-events \( E \) is a causal set of \( v \) in \( Ev \) if \( E \) is a minimal subset of \( Ev \) such that

1. \( E \cup \{v\} \) is conflict-free and
2. \( p :: \eta \in v \) and \( \eta' < \eta \) imply \( p :: \eta' \in E \).

Note that in the above definition, the conjunction of minimality and Clause (2) implies that, if \( \nu' \in E \), then \( \nu' < \nu \). Thus \( E \) is a set of direct causes of \( v \). Moreover, a causal set of an n-event cannot be included in another causal set of the same n-event, as this would contradict the minimality of the larger set. Hence, Definition 5.9 indeed formalises the idea that causal sets should be complete sets of compatible direct causes of a given n-event.

**Example 5.10.** Let \( v_1 = \{p :: q!\lambda_1 \cdot r!\lambda, r :: p?\lambda\} \) and \( v_2 = \{p :: q!\lambda_2 \cdot r!\lambda, r :: p?\lambda\} \). Then both \( \{v_1\} \) and \( \{v_2\} \) are causal sets of \( v = \{r :: p?\lambda \cdot s!\lambda', s :: r!\lambda'\} \) in \( Ev = \{v_1, v_2, v\} \). Note that \( v_1 \neq v_2 \) and that neither \( v_1 \) nor \( v_2 \) has a causal set in \( Ev \).

Let us now consider also \( v'_1 = \{p :: q!\lambda_1, q :: p?\lambda_1\} \) and \( v'_2 = \{p :: q!\lambda_2, q :: p?\lambda_2\} \). Then \( v \) still has the same causal sets \( \{v_1\} \) and \( \{v_2\} \) in \( Ev' = \{v'_1, v'_2, v_1, v_2, v\} \), while each \( v_i \), \( i = 1, 2 \), has the unique causal set \( \{v'_i\} \) in \( Ev' \), and each \( v'_i \), \( i = 1, 2 \), has the empty causal set in \( Ev' \).

Finally, \( v \) has infinitely many causal sets in \( \mathcal{D} \mathcal{E} \). For instance, if for every natural number \( n \) we let \( v_n = \{p :: q!\lambda_1 \cdot r!\lambda, r :: p?\lambda\} \), then each \( \{v_n\} \) is a causal set of \( v \) in \( \mathcal{D} \mathcal{E} \). Symmetrically, a causal set may cause infinitely many events in \( \mathcal{D} \mathcal{E} \). For instance, the above causal sets \( \{v_1\} \) and \( \{v_2\} \) of \( v \) could also act as causal sets for any n-event \( v''_n = \{r :: p?\lambda \cdot s!\lambda_n, s :: r?\lambda_n\} \) or, assuming the set of participants to be denumerable, for any event \( v'''_n = \{r :: p?\lambda \cdot s_n!\lambda', s_n :: r?\lambda'\} \).

When defining the set of events of a network ES, we want to prune out all the n-events that do not have a causal set in the set itself. The reason is that such n-events cannot happen. This pruning is achieved by means of the following narrowing function.
Definition 5.11 (Narrowing of a set of n-events). The narrowing of a set $E$ of n-events, denoted by $n(E)$, is the greatest fixpoint of the function $f_E$ on sets of n-events defined by:

$$f_E(X) = \{v \in E \mid \exists E' \subseteq X. E' \text{ is a causal set of } v \text{ in } X\}$$

Note that we could not have taken $n(E)$ to be the least fixpoint of $f_E$ rather than its greatest fixpoint. Indeed, the least fixpoint of $f_E$ would be the empty set.

Example 5.12. The following two examples illustrate the notions of causal set and narrowing.

Let $v_1 = [r :: s? \lambda_1, s :: r! \lambda_1]$, $v_2 = [r :: s? \lambda_2, s :: r! \lambda_2]$, $v_3 = [p :: r? \lambda_1, r :: s? \lambda_1 \cdot p! \lambda_1]$, $v_4 = [q :: s? \lambda_2, q :: r! \lambda_2]$, $v_5 = [p :: r? \lambda_1 \cdot q! \lambda, q :: s? \lambda_2 \cdot p? \lambda]$. Then $n([v_1, \ldots, v_5]) = \{v_1, \ldots, v_4\}$, because a causal set for $v_5$ would need to contain both $v_3$ and $v_4$, but this is not possible since $v_3 \# v_4$ by Clause $2b$ of Definition 5.7. In fact $(s? \lambda_1 \cdot p! \lambda_1) \# s = \# \lambda_1$ and $(r! \lambda_2 \cdot q! \lambda_2) \# r = \# \lambda_2$ and $(\# \lambda_1) = \# \lambda_2$ and $-(\# \lambda_1 \cdot \# \lambda_2)$.

Let $v_1 = [r :: s? \lambda_1, s :: r! \lambda_1]$, $v_2 = [r :: s? \lambda_2, s :: r! \lambda_2]$, $v_3 = [p :: r? \lambda_1, r :: s? \lambda_1 \cdot p! \lambda_1]$, $v_4 = [p :: r? \lambda_1 \cdot s? \lambda_2, s :: r! \lambda_2 \cdot p! \lambda_2]$, $v_5 = [p :: r? \lambda_1 \cdot s? \lambda_2 \cdot q! \lambda q :: p? \lambda]$. Here $n([v_1, \ldots, v_5]) = \{v_1, v_2, v_3\}$. Indeed, a causal set for $v_4$ would need to contain both $v_2$ and $v_3$, but this is not possible since $v_2 \# v_3$ by Clause $2b$ of Definition 5.7. In fact $s? \lambda_2 \# s? \lambda_1 \cdot p! \lambda_1$. Then, $v_5$ will also be pruned by the narrowing since any causal set for $v_5$ should contain $v_4$.

We can now finally define the event structure associated with a network:

Definition 5.13 (Event structure of a network). The event structure of network $N$ is the triple

$$S^N(N) = (\mathcal{NE}(N), <_N, \#_N)$$

where:

1. $\mathcal{NE}(N) = n(\mathcal{DE}(N))$ with $\mathcal{DE}(N) = \{[p :: \eta, q :: \eta'] | p \parallel P \in N, q \parallel Q \in N, \eta \in \mathcal{PE}(P), \eta' \in \mathcal{PE}(Q), p :: \eta \not\sim q :: \eta'\}$

2. $<_N$ is the restriction of $<$ to the set $\mathcal{NE}(N)$;

3. $\#_N$ is the restriction of $\#$ to the set $\mathcal{NE}(N)$.

The set of n-events of a network ES can be infinite, as shown by the following example.

Example 5.14. Let $P$ be as in Example 4.4; $Q = p? \lambda ; Q + p? \lambda'$ and $N = p \parallel P \parallel q \parallel Q$. Then

$$\mathcal{NE}(N) = \{[p :: q^1 \lambda \cdot \ldots \cdot q^n \lambda q :: p^n \lambda \cdot \ldots \cdot p? \lambda] \mid n \geq 1\} \cup \{[p :: q^n \lambda \cdot \ldots \cdot q^n \lambda q' :: p^n \lambda \cdot \ldots \cdot p? \lambda \cdot p? \lambda'] \mid n \geq 0\}$$
A simple variation of this example shows that even within the events of a network ES, an 
$n$-event $v$ may have an infinite number of causal sets. Let $v = \{ r :: p?\lambda \cdot s!\lambda', s :: r?\lambda' \}$ be 
as in Example 5.10. Consider the network $N' = N || q1 || r || s || \nu || \nu || \nu'$ where 
$P' = q!\lambda; P' \oplus q!\lambda'; r!\lambda', Q$ is as above, $R = p?\lambda; s!\lambda'$ and $S = r?\lambda'$. 

Then $v$ has an infinite number of causal sets $E_n = \{\nu_n\}$ in $\mathcal{NE}(N')$, where 
\[
\nu_n = \{ p :: q!\lambda \cdot \ldots \cdot q!\lambda \cdot q!\lambda' \cdot r!\lambda, r :: p?\lambda \}
\]

On the other hand, a causal set may only cause a finite number of events in a network ES, 
since the number of branches in any choice is finite, as well as the number of participants in 
the network.

Theorem 5.15. Let $N$ be a network. Then $S^N(N)$ is a flow event structure with an 
irreflexive conflict relation.

Proof The relation $\prec_N$ is irreflexive since $\eta < \eta'$ implies $\nu \neq \nu'$, where $\eta, \eta', \nu, \nu'$ are 
as in Definition 5.7(1). As for the conflict relation, note first that a conflict between 
an $n$-event and itself could not be derived by Clause (2b) of Definition 5.7 since 
the two located events of an $n$-event are dual by construction. Then, symmetry 
and irreflexivity of the conflict relation follow from the corresponding properties of 
conflict between p-events.

Notably, $n$-events with disjoint sets of locations may be related by the transitive 
closure of the flow relation, as illustrated by the following example, which also 
shows how $n$-events inherit the flow relation from the causality relation of their 
p-events.

Example 5.16. Let $N$ be the network 
\[
p || q!\lambda_1 || q || p?\lambda_1; r!\lambda_2 || r || q?\lambda_2; s!\lambda_3 || s || r?\lambda_3
\]

Then $S^N(N)$ has three network events 
\[
v_1 = \{ p :: q!\lambda_1, q :: p?\lambda_1 \} \quad v_2 = \{ q :: p?\lambda_1 \cdot r!\lambda_2, r :: q?\lambda_2 \} \quad v_3 = \{ r :: q?\lambda_2 \cdot s!\lambda_3, s :: r?\lambda_3 \}
\]
The flow relation obtained by Definition 5.13 is: $v_1 < v_2$ and $v_2 < v_3$. Note that each time 
the flow relation is inherited from the causality within a different participant, $q$ in the first 
case and $r$ in the second case. The nonempty configurations are $\{v_1\}, \{v_1, v_2\}$ and $\{v_1, v_2, v_3\}$. 
Note that $S^N(N)$ has only one proving sequence per configuration (which is the one 
given by the numbering of events).

If a network is binary, then its FES may be turned into a PES by replacing $<$ with $\prec$.
To prove this result, we first show a property of $n$-events of binary networks. 
We say that an $n$-event $v$ is binary if the participants occurring in the p-events of $v$ 
are contained in $\text{loc}(v)$.

Lemma 5.17. Let $v$ and $v'$ be binary $n$-events with $\text{loc}(v) = \text{loc}(v')$. Then $v \not\prec v'$ iff 
$p :: \eta \in v$ and $p :: \eta' \in v'$ imply $\eta \neq \eta'$.
Proof The “if” direction holds by Definition \ref{def:cat}(2a). We show the “only-if” direction. First observe that for any n-event $\nu = (p :: \eta_1, q :: \eta_2)$ the condition $p :: \eta_1 \bowtie q :: \eta_2$ of Definition \ref{def:cat} implies $\eta_1 \bowtie q \bowtie \eta_2 \bowtie p$ by Definition \ref{def:equivalence}, which in turn implies $|\eta_1 \bowtie q| = |\eta_2 \bowtie p|$ by Definition \ref{def:equivalence}. If $\nu$ is a binary event, we also have $|\eta_i| = |\eta_1 \bowtie q|$ and $|\eta_2| = |\eta_2 \bowtie p|$ by Definition \ref{def:cat} since all the actions of $\eta_1$ involve $q$ and all the actions of $\eta_2$ involve $p$, and thus the projections do not erase actions. Assume now $\nu' = (p :: \eta'_1, q :: \eta'_2)$. We consider two cases (the others being symmetric):

- $\nu \mathbin{\#} \nu'$ because $\eta_1 \neq \eta_1'$. Then $\eta_1 \bowtie q \bowtie \eta_2 \bowtie p$ and $\eta_1' \bowtie q \bowtie \eta_2' \bowtie p$ imply $\eta_2 \neq \eta_2'$;

- $\nu \mathbin{\#} \nu'$ because $|\eta_1 \bowtie q| = |\eta_1' \bowtie p|$ and $-(\eta_1 \bowtie q \bowtie \eta_2 \bowtie p)$. As argued before, we have $|\eta_2 \bowtie p| = |\eta_1 \bowtie q|$ and $|\eta_2' \bowtie p| = |\eta_1' \bowtie q|$. Then, from $|\eta_1 \bowtie q| = |\eta_2 \bowtie p|$ and the above remark about binary events, we get $|\eta_2| = |\eta_1| = |\eta_2'| = |\eta_1'|$. From $-(\eta_1 \bowtie q \bowtie \eta_2 \bowtie p)$ it follows that $\eta_1 \neq \eta_1'$ and $\eta_2 \neq \eta_2'$. Then we may conclude, since $|\eta_i| = |\eta_i'|$ and $\eta_i \neq \eta_i'$ imply $\eta_i \mathbin{\#} \eta_i'$ for $i = 1, 2$.

Theorem \ref{thm:cat}. Let $N = p_1 \parallel p_1 \parallel p_2 \parallel p_2$ and $S^N(N) = (\mathcal{NE}(N), \prec_N, \#)$. Then $n(\mathcal{DE}(N)) = \mathcal{DE}(N)$ and the structure $S^N(N) = \text{def}(\mathcal{NE}(N), \prec_N, \#)$ is a prime event structure.

Proof We first show that $n(\mathcal{DE}(N)) = \mathcal{DE}(N)$. By Definition \ref{def:cat}(1)

\[ \mathcal{DE}(N) = \{ (p_1 :: \eta_1, p_2 :: \eta_2) | (\eta_1 \bowtie q \bowtie \eta_2 \bowtie p) : \mathcal{PE}(P_1), \eta_2 \bowtie q \bowtie \eta_2 \bowtie p : \mathcal{PE}(P_2) \} \]

Let $\{p_1 :: \eta_1, p_2 :: \eta_2\} \in \mathcal{DE}(N)$. Since $p_1 :: \eta_1 \bowtie p_2 :: \eta_2$ and all the actions in $\eta_1$ involve $p_2$ and all the actions in $\eta_2$ involve $p_1$, we know that $\eta_1$ and $\eta_2$ have the same length $n \geq 1$ and for each $i, 1 \leq i \leq n$, the prefixes of length $i$ of $\eta_1$ and $\eta_2$, written $\eta'_1$ and $\eta'_2$, must themselves be dual. Then $\{p_1 :: \eta'_1, p_2 :: \eta'_2\} \in \mathcal{DE}(N)$ for each $i, 1 \leq i \leq n$, hence $\{p_1 :: \eta_1, p_2 :: \eta_2\}$ has a causal set in $\mathcal{DE}(N)$.

We prove now that the reflexive and transitive closure $\prec_N$ of $\prec_N$ is a partial order. Since by definition $\prec_N$ is a preorder, we only need to show that it is antisymmetric. Define the length of an n-event $\nu = (p_1 :: \eta_1, p_2 :: \eta_2)$ to be $\text{length}(\nu) = |\eta_1| + |\eta_2|$ (where $|\eta|$ is the length of $\eta$, as given by Definition \ref{def:cat}(1)). Let now $\nu, \nu' \in \mathcal{NE}(N)$, with $\nu = \{p_1 :: \eta_1, p_2 :: \eta_2\}$ and $\nu' = \{p_1 :: \eta'_1, p_2 :: \eta'_2\}$. By definition $\nu \prec_N \nu'$ implies $\eta_i \bowtie \eta'_i$ for some $i = 1, 2$, which in turn implies $\eta_i \bowtie \eta'_i$. As observed above, $\eta_i$ and $\eta'_i$ must have the same length, and so must $\eta'_1$ and $\eta'_2$. This means that if $\nu \prec_N \nu'$ then $\text{length}(\nu) = |\eta_1| + |\eta_2| < |\eta'_1| + |\eta'_2| = \text{length}(\nu')$. From this we can conclude that if $\nu \prec_N \nu'$ and $\nu' \prec_N \nu$, then necessarily $\nu = \nu'$.

Finally we show that the relation $\#$ satisfies the required properties. By Theorem \ref{thm:cat} we only need to prove that $\#$ is hereditary. Let $\nu$ and $\nu'$ be as above. If $\nu \mathbin{\#} \nu'$, then by Lemma \ref{lem:cat} $\eta_i \mathbin{\#} \eta'_i$ and $\eta_2 \mathbin{\#} \eta_2'$. Let now $\nu'' = (p_1 :: \eta''_1, p_2 :: \eta''_2)$. If $\nu' \prec_N \nu''$, then $\nu' \prec_N \nu''$, which means that there exist $v_1, \ldots, v_n$ such that $\nu' \prec_N v_1 \cdots \prec_N v_n = \nu''$. We prove by induction on $n$ that $\nu \mathbin{\#} \nu''$. For $n = 1$ we have $\nu' \prec_N \nu''$. Then by Clause (1) of Definition \ref{def:cat} we have $\eta_j' < \eta_j''$ for some $j \in \{1, 2\}$. Since $\eta_i \mathbin{\#} \eta_i'$ for all $i \in \{1, 2\}$ and $\#$ is hereditary on p-events, we deduce $\eta_j \mathbin{\#} \eta_j''$, which implies $\nu \mathbin{\#} \nu''$. Suppose now $n > 1$. By induction $\nu \mathbin{\#} \nu_{n-1}$. Since $\nu_{n-1} \prec_N \nu_n = \nu''$ we then obtain $\nu \mathbin{\#} \nu''$ by the same argument as in the base case.
If a network has more than two participants, then the duality requirement on its n-events is not sufficient to ensure the absence of circular dependencies. For instance, in the following ternary network (which may be viewed as representing the 3-philosopher deadlock) the relation \(<^*\) is not a partial order.

**Example 5.19.** Let \(N\) be the network
\[
\mathsf{p} \oplus \mathsf{r}?\mathsf{\lambda}; \mathsf{q}!\mathsf{\lambda}' \parallel \mathsf{q} \oplus \mathsf{p}?\mathsf{\lambda}'; \mathsf{r}?\mathsf{\lambda}'' \parallel \mathsf{r} \oplus \mathsf{q}?\mathsf{\lambda}''; \mathsf{p}!\mathsf{\lambda} \parallel
\]
Then \(S^N(N)\) has three n-events
\[
\nu_1 = \{\mathsf{p} :: \mathsf{r}?\mathsf{\lambda}, \mathsf{r} :: \mathsf{q}?\mathsf{\lambda}'' \cdot \mathsf{p}!\mathsf{\lambda}\}, \quad \nu_2 = \{\mathsf{p} :: \mathsf{r}?\mathsf{\lambda} \cdot \mathsf{q}!\mathsf{\lambda}', \mathsf{q} :: \mathsf{p}?\mathsf{\lambda}'\},
\]
\[
\nu_3 = \{\mathsf{q} :: \mathsf{p}?\mathsf{\lambda}' \cdot \mathsf{r}?\mathsf{\lambda}''', \mathsf{r} :: \mathsf{q}?\mathsf{\lambda}''\}
\]

By Definition (5.13) we have \(\nu_1 < \nu_2 < \nu_3\) and \(\nu_3 < \nu_1\). The only configuration of \(S^N(N)\) is the empty configuration, because the only set of n-events that satisfies downward-closure up to conflicts is \(X = \{\nu_1, \nu_2, \nu_3\}\), but this is not a configuration because \(<^*_X\) is not a partial order (recall that \(<^*_X\) is the restriction of \(<\) to \(X\)) and hence the condition (3) of Definition (3.4) is not satisfied.

### 5.2. Further Properties

In this subsection, we first prove two properties of the conflict relation in network ESs: non disjoint n-events are always in conflict, and conflict induced by Clause (2b) of Definition (5.7) is semantically inherited. We then discuss the relationship between causal sets and prime configurations and prove two further properties of causal sets, which are shared with prime configurations: finiteness, and the existence of a causal set for each event in a configuration. Finally, observing that the FES of a network may be viewed as the product of the PESs of its processes, we proceed to prove a classical property for ES products, namely that their projections on their components preserve configurations. To this end, we define a projection function from n-events to participants, yielding p-events, and we show that configurations of a network ES project down to configurations of the PESs of its processes.

Let us start with the conflict properties. By definition, two n-events intersect each other if and only if they share a located event \(\mathsf{p} :: \eta\). Otherwise, the two n-events are disjoint. Note that if \(\mathsf{p} :: \eta \in (\nu \cap \nu')\), then \(\text{loc}(\nu) = \text{loc}(\nu') = \{\mathsf{p}, \mathsf{q}\}\), where \(\mathsf{q} = \mathsf{pt}(\text{act}(\eta))\). The next proposition establishes that two distinct intersecting n-events in \(\mathcal{DE}\) are in conflict.

**Proposition 5.20 (Sharing of located events implies conflict).** If \(\nu, \nu' \in \mathcal{DE}\) and \(\nu \neq \nu'\) and \((\nu \cap \nu') \neq \emptyset\), then \(\nu \not\equiv \nu'\).

**Proof** Let \(\mathsf{p} :: \eta \in (\nu \cap \nu')\) and \(\text{loc}(\nu) = \text{loc}(\nu') = \{\mathsf{p}, \mathsf{q}\}\). Then there must exist \(\eta_0, \eta'_0\) such that \(\mathsf{q} :: \eta_0 \in \nu\) and \(\mathsf{q} :: \eta' \in \nu'\). From \(\mathsf{p} :: \eta \not\equiv \mathsf{q} :: \eta_0\) and \(\mathsf{p} :: \eta \not\equiv \mathsf{q} :: \eta'\), it follows that \(\eta_0 \not\equiv \mathsf{p} = \eta' \not\equiv \mathsf{p}\). This, in conjunction with the fact that \(\mathsf{pt}(\text{act}(\eta_0)) = \mathsf{pt}(\text{act}(\eta'_0)) = \mathsf{p}\), implies that neither \(\eta_0 < \eta'_0\) nor \(\eta'_0 < \eta_0\). Thus \(\eta_0 \not\equiv \eta'_0\) and therefore \(\nu \not\equiv \nu'\) by Definition (5.7).

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3This is a well-known issue in multiparty session types, which motivated the introduction of global types in \([38]\), see Section (6)
Although conflict is not hereditary in FESs, we prove that a conflict due to incompatible mutual projections (i.e., a conflict derived by Clause (2b) of Definition [5.7]) is semantically inherited. Let $\delta \setminus \gamma_n$ denote the prefix of length $n$ of $\delta$.

**Proposition 5.21 (Semantic conflict hereditariness).** Let $p \:: \eta \in \nu$ and $q :: \eta' \in \nu'$ with $p \neq q$. Let $n = \min(|\eta \uparrow q|, |\eta' \uparrow p|)$. If $\neg((\eta \uparrow q) \setminus \gamma_n \bowtie (\eta' \uparrow p) \setminus \gamma_n)$, then there exists no configuration $X$ such that $v, v' \in X$.

**Proof** Suppose ad absurdum that $X$ is a configuration such that $v, v' \in X$. If $|\eta \uparrow q| = |\eta' \uparrow p|$ then $v \neq v'$ by Definition [5.7(2b)] and we reach immediately a contradiction. So, assume $|\eta \uparrow q| > |\eta' \uparrow p| = n$. This means that $|\eta| > 1$ and thus there exists a non-empty causal set $E_v$ of $v$ such that $E_v \not\subseteq X$. Let $\eta_0 < \eta$ be such that $|\eta_0 \uparrow q| = |\eta' \uparrow p| = n$. By definition of causal set, there exists $v_0 \in E_v$ such that $p :: \eta_0 \in v_0$. By Definition [5.7(2b)] we have then $v_0 \neq v'$, contradicting the fact that $X$ is conflict-free.

We prove now two further properties of causal sets. For the reader familiar with ESs, the notion of causal set may be reminiscent of that of prime configuration [63], which similarly consists of a complete set of causes for a given event. However, there are some important differences: the first is that a causal set does not include the event it causes, unlike a prime configuration. The second is that a causal set only contains direct causes of an event, and thus it is not downward-closed up to conflicts, as opposed to a prime configuration. The last difference is that, while a prime configuration uniquely identifies its caused event, a causal set may cause different events, as shown in Example [5.10].

A common feature of prime configurations and causal sets is that they are both finite. For causal sets, this is implied by minimality together with Clause (2) of Definition [5.9] as shown by the following lemma.

**Lemma 5.22.** Let $v \in E_v \subseteq \mathcal{D}E$. If $E$ is a causal set of $v$ in $E_v$, then $E$ is finite.

**Proof** Suppose $v = \{p :: \eta, q :: \eta'\}$. We show that $|E| \leq |\eta| + |\eta'| - 2$, where $|E|$ is the cardinality of $E$. By Condition (2) of Definition [5.9] for each $\eta_0 < \eta$ and $\eta'_0 < \eta'$ there must be $v_0, v'_0 \in E$ such that $p :: \eta_0 \in v_0$ and $q :: \eta'_0 \in v'_0$. Note that $v_0$ and $v'_0$ could possibly coincide. Moreover, there cannot be $v' \in E$ such that $p :: \eta_0 \in v' \neq v_0$ or $q :: \eta'_0 \in v' \neq v'_0$, since this would contradict the minimality of $E$ (and also its conflict-freeness, since by Proposition [5.20] we would have $v' \neq v_0$). Hence the number of events in $E$ is at most $(|\eta| - 1) + (|\eta'| - 1)$.

A key property of causal sets, which is again shared with prime configurations, is that each configuration includes a unique causal set for each $n$-event in the configuration.

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4In PESs, the prime configuration associated with an event is unique, while it is not unique in FESs and more generally in Stable ESs, just like a causal set.
Lemma 5.23. If \( \mathcal{X} \) is a configuration of \( S^N(N) \) and \( \nu \in \mathcal{X} \), then there is a unique causal set \( E \subseteq \mathcal{X} \).

Proof By Definition 5.11, if \( \nu \in \mathcal{NE}(N) \), then \( \nu \) has at least one causal set included in \( \mathcal{NE}(N) \). Let \( E' = \{ \nu' \in \mathcal{X} \mid \nu' < \nu \} \). By Definition 3.4, \( E' \cup \{ \nu \} \) is conflict-free. Moreover, if \( p :: \eta \in \nu \) and \( \eta' < \eta \), then by Proposition 5.20, there is at most one \( \nu'' \in E' \) such that \( p :: \eta' \in \nu'' \). Therefore, \( E' \subseteq E \) for some causal set \( E \) of \( \nu \) by Definition 3.9. We show that \( E \subseteq E' \). Assume ad absurdum that \( \nu_0 \in E \setminus E' \). By definition of causal set, \( \nu_0 < \nu \). By definition of \( E' \), \( \nu_0 \notin E' \) implies \( \nu_0 \notin E \). By Definition 3.4 this implies \( \nu_0 \# \nu_1 < \nu \) for some \( \nu_1 \in \mathcal{X} \). Then \( \nu_1 \notin E' \) by definition of \( E' \), and thus \( \nu_1 \in E \). Hence \( \nu_0, \nu_1 \in E \) and \( \nu_0 \# \nu_1 \), contradicting Definition 5.9.

In the remainder of this section we show that projections of n-event configurations give p-event configurations. We start by formalising the projection function of n-events to p-events and showing that it is downward surjective.

Definition 5.24 (Projection of n-events to p-events).

\[
\text{proj}_p(\nu) = \begin{cases} 
\eta & \text{if } p :: \eta \in \nu, \\
\text{undefined} & \text{otherwise}.
\end{cases}
\]

The projection function \( \text{proj}_p(\cdot) \) is extended to sets of n-events in the obvious way:

\[
\text{proj}_p(X) = \{ \eta \mid \exists \nu \in X. \text{proj}_p(\nu) = \eta \}
\]

Example 5.25. Let \( \{\nu_1, \nu_2, \nu_3\} \) be the configuration defined in Example 5.16. We get

\[
\text{proj}_q(\{\nu_1, \nu_2, \nu_3\}) = \{p?\lambda_1, p?\lambda_1 \cdot r!\lambda_2\}
\]

Example 5.26. Let \( N = p[r?\lambda; q?\lambda'] \parallel q[p!\lambda'] \). Then

\[
\mathcal{NE}(N) = n(\{p :: r?\lambda \cdot q?\lambda', q :: p!\lambda'\}) = \emptyset
\]

Note that if we did not apply narrowing the set of events of \( S^N(N) \) would be the singleton \( \{p :: r?\lambda \cdot q?\lambda', q :: p!\lambda\} \), which would also be a configuration \( X \) of \( S^N(N) \). However, \( \text{proj}_p(\nu) = \{r?\lambda \cdot q?\lambda'\} \) would not be configuration in \( \mathcal{PE}(P) \), since it would contain the event \( r?\lambda \cdot q?\lambda' \) without its cause \( r?\lambda \).

Narrowing ensures that each projection of the set of n-events of a network FES on one of its participants is downward surjective (according to Definition 3.8):

Lemma 5.27 (Downward surjectivity of projections). Let \( S^N(N) = (\mathcal{NE}(N), \preceq_N, \#_N) \) and \( S^P(P) = (\mathcal{PE}(P), \preceq_P, \#_P) \) and \( p \parallel P \in N \). Then the partial function \( \text{proj}_p : \mathcal{NE}(N) \rightarrow \mathcal{PE}(P) \) is downward surjective.

Proof As mentioned already in Section 3, any PES \( S = (E, \preceq, \#) \) may be viewed as a FES, with \( < \) given by \( < \) (the strict ordering underlying \( \preceq \)). Let \( \eta \in \mathcal{PE}(P) \) and \( \nu \in \mathcal{NE}(N) \). Then the property we need to show is:

\[
\eta <_p \text{proj}_p(\nu) \Rightarrow \exists \nu' \in \mathcal{NE}(N). \eta = \text{proj}_p(\nu')
\]
Note that $\eta <_p \text{proj}_p(\nu)$ implies $\text{proj}_p(\nu) = \eta \cdot \eta'$ for some $\eta'$. Recall that $\mathcal{N}(\mathcal{N}) = \eta(\mathcal{E}(\mathcal{N}))$, where $\eta(\cdot)$ is the narrowing function (Definition 5.11).

By definition of narrowing, $p : \eta \cdot \eta' \in \mathcal{N}(\mathcal{N})$ implies that there is $E \subseteq \mathcal{N}(\mathcal{N})$ such that $E$ is a causal set of $\nu$ in $\mathcal{N}(\mathcal{N})$. Therefore $p : \eta \cdot \eta' \in \nu$ implies $p : \eta \in E$ and so $p : \eta \in \mathcal{N}(\mathcal{N})$, which is what we wanted to show.

**Theorem 5.28 (Projection preserves configurations).** If $p \parallel P \parallel \in \mathcal{N}$, then $\chi \in C(S^N(\mathcal{N}))$ implies $\text{proj}_p(\chi) \in C(S^P(P))$.

**Proof** Clearly, $\text{proj}_p(\chi)$ is conflict-free. We show that it is also downward-closed. If $\nu \in \chi$, by Lemma 5.23 there is a causal set $E$ of $\nu$ such that $E \subseteq \chi$. If $p : \eta \in \nu$ and $\eta' < \eta$, by Definition 5.9 there is $\nu' \in E$ such that $p : \eta' \in \nu'$. We conclude that $\nu' \in \chi$, and therefore $\eta' \in \text{proj}_p(\chi)$.

The reader may wonder why our ES semantics for sessions is not cast in categorical terms, like classical ES semantics for process calculi [59, 17], where process constructions arise as categorical constructions (e.g., parallel composition arises as a categorical product). In fact, a categorical formulation of our semantics would not be possible, due to our two-level syntax for processes and networks, which does not allow networks to be further composed in parallel. However, it should be clear that our construction of a network FES from the process PESs of its components is a form of parallel composition, and the properties expressed by Lemma 5.27 and Theorem 5.28 give some evidence that this construction enjoys the properties usually required for a categorical product of ESs.

### 6. Global Types

This section is devoted to our type system for multiparty sessions. Global types describe the communication protocols involving all session participants. Usually, global types are projected into local types and typing rules are used to derive local types for processes [38, 19, 39]. The simplicity of our calculus allows us to project directly global types into processes and to have exactly one typing rule, see Figure 3.

This section is split in two subsections. The first subsection presents the projection of global types onto processes, together with the proof of its soundness. Moreover it introduces a boundedness condition on global types, which is crucial for our type system to ensure progress. The second subsection presents the type system, as well as an LTS for global types. Lastly, the properties of Subject Reduction, Session Fidelity and Progress are shown.

#### 6.1. Well-formed Global Types

Global types are built from choices among communications.

**Definition 6.1 (Global types).** Global types $G$ are defined by:

$$G ::= \langle \text{coind} \rangle \quad \quad p \rightarrow q : \bigvee_{i \in I} \lambda_i ; G_i \mid \text{End}$$

where $I$ is not empty, $\lambda_h \neq \lambda_k$ for all $h, k \in I$, $h \neq k$, i.e. messages in choices are all different.
As for processes, \( \cong^{\text{coind}} \) indicates that global types are defined coinductively.

Again, we focus on regular terms.

Sequential composition (\( ; \)) has higher precedence than choice (\( \oplus \)). When \( I \) is a singleton, a choice \( p \to q : \bigoplus_{i \in I} \lambda_i ; G_i \) will be rendered simply as \( p \overset{\lambda}{\to} q ; G \). In writing global types, we omit the final \( \text{End} \).

Given a global type, the sequences of decorations of nodes and edges on the path from the root to an edge in the tree of the global type are traces, in the sense of Definition 2.3. We denote by \( \text{Tr}^+(G) \) the set of traces of \( G \). By definition, \( \text{Tr}^+(\text{End}) = \emptyset \) and each trace in \( \text{Tr}^+(G) \) is non-empty.

The set of participants of a global type \( G \), \( \text{part}(G) \), is defined to be the union of the sets of participants of all its traces, namely

\[
\text{part}(G) = \bigcup_{\sigma \in \text{Tr}^+(G)} \text{part}(\sigma)
\]

Note that the regularity assumption ensures that the set of participants is finite.

The projection of a global type onto participants is given in Figure 2. As usual, projection is defined only when it is defined on all participants. Because of the simplicity of our calculus, the projection of a global type, when defined, is simply a process. The definition is coinductive, so a global type with an infinite (regular) tree produces a process with a regular tree. The projection of a choice type on the sender produces an output choice, i.e. a process sending one of its possible messages to the receiver and then acting according to the projection of the corresponding branch. Similarly for the projection on the receiver, which produces a process which is an input choice. Projection of a choice type on the other participants is defined only if it produces the same process for all the branches of the choice. This is a standard condition for multiparty session types [38].

Our coinductive definition of global types is more permissive than that based on the standard \( \mu \)-notation used in [38], because it allows more global types to be projected, as shown by the following example.

**Example 6.2.** The global type \( G = p \to q : (\lambda_1 ; q \overset{\lambda}{\to} r \bigoplus \lambda_2 ; G) \) is projectable and

- \( G \upharpoonright p = P = q!\lambda_1 \oplus q!\lambda_2 ; P \)
- \( G \upharpoonright q = Q = p?\lambda_1 ; r!\lambda_3 + p?\lambda_2 ; Q \)
On the other hand, the corresponding global type based on the $\mu$-notation

$$G' = \mu t. p \rightarrow q : (\lambda_1; q \rightarrow_\lambda_3 r \bigoplus \lambda_2; t)$$

is not projectable because $G' \uparrow r$ is not defined.

To achieve progress, we need to ensure that each network participant occurs in every computation, whether finite or infinite. This means that each type participant must occur in every path of the tree of the type. Projectability already ensures that each participant of a choice type occurs in all its branches. This implies that if one branch of the choice gives rise to an infinite path, either the participant occurs at some finite depth in this path, or this path crosses infinitely many branching points in which the participant occurs in all branches. In the latter case, since the depth of the participant increases when crossing each branching point, there is no bound on the depth of the participant over all paths of the type. Hence, to ensure that all type participants occur in all paths, it is enough to require the existence of such bounds. This motivates the following definition of depth and boundedness.

**Definition 6.3 (Depth and boundedness).**

Let the two functions $\text{depth}(\sigma, p)$ and $\text{depth}(G, p)$ be defined by:

$$\text{depth}(\sigma, p) = \begin{cases} 
  n & \text{if } \sigma = \sigma_1 \cdot \alpha \cdot \sigma_2 \text{ and } |\sigma_1| = n - 1 \text{ and } p \notin \text{part}(\sigma_1) \text{ and } p \in \text{part}(\alpha) \\
  0 & \text{otherwise}
\end{cases}$$

Then

$$\text{depth}(G, p) = \sup\{\text{depth}(\sigma, p) | \sigma \in \text{Tr}^+(G)\}$$

We say that a global type $G$ is **bounded** if $\text{depth}(G', p)$ is finite for all subtrees $G'$ of $G$ and for all participants $p$.

If $\text{depth}(G, p)$ is finite, then there are no paths in the tree of $G$ in which $p$ is delayed indefinitely. Note that if $\text{depth}(G, p)$ is finite, $G$ may have subtrees $G'$ for which $\text{depth}(G', p)$ is infinite as the following example shows.

**Example 6.4.** Consider $G' = q \rightarrow_\lambda r; G$ where $G$ is as defined in Example 6.2. Then we have:

$$\text{depth}(G', p) = 2 \quad \text{depth}(G', q) = 1 \quad \text{depth}(G', r) = 1$$

whereas

$$\text{depth}(G, p) = 1 \quad \text{depth}(G, q) = 1 \quad \text{depth}(G, r) = \infty$$

since

$$\text{Tr}^+(G) = \{pq \lambda_2 \cdots pq \lambda_2 \cdot q r \lambda_3 | n \geq 0\} \cup \{pq \lambda_2 \cdots pq \lambda_2 \cdots\}$$

and $\sup\{2, 3, \ldots\} = \infty$. 
The depths of the participants in $G$ which are not participants of its root communication decrease in the immediate subtrees of $G$.

**Proposition 6.5.** If $G = p \rightarrow q : \bigoplus_{i \in I} \lambda_i; G$, and $r \in \text{part}(G) \setminus \{p, q\}$, then depth$(G, r) >$ depth$(G_i, r)$ for all $i \in I$.

**Proof.** Each trace $\sigma \in \text{Tr}^+(G)$ is of the shape $pq\lambda_i \cdot \sigma'$ where $i \in I$ and $\sigma' \in \text{Tr}^+(G_i)$.

We can now show that the definition of projection given in Figure 2 is sound for bounded global types.

**Lemma 6.6.** If $G$ is bounded, then $G \upharpoonright r$ is a partial function for all $r$.

Boundedness and projectability single out the global types we want to use in our type system.

**Definition 6.7 (Well-formed global types).** We say that the global type $G$ is well formed if $G$ is bounded and $G \upharpoonright p$ is defined for all $p$.

Clearly it is sufficient to check that $G \upharpoonright p$ is defined for all $p \in \text{part}(G)$, since otherwise $G \upharpoonright p = 0$.

### 6.2. Type System

The definition of well-typed network is given in Figure 3. We first define a preorder on processes, $P \leq Q$, meaning that process $P$ can be used where we expect process $Q$. More precisely, $P \leq Q$ if either $P$ is equal to $Q$, or we are in one of two situations: either both $P$ and $Q$ are output processes with the same receiver and choice of messages, and their continuations after the send are two processes $P'$ and $Q'$ such that $P' \leq Q'$; or they are both input processes with the same sender and choice of messages, and $P$ may receive more messages than $Q$ (and thus have more behaviours) but whenever it receives the same message as $Q$ their continuations are two processes $P'$ and $Q'$ such that $P' \leq Q'$. The rules are interpreted coinductively, since the processes may have infinite (regular) trees.

A network is well typed if all its participants have associated processes that behave as specified by the projections of a global type. In Rule $[\text{Net}]$, the condition $\text{part}(G) \subseteq \{p_i | i \in I\}$ ensures that all participants of the global type appear in the network. Moreover it permits additional participants that do not appear in the global type, allowing the typing of sessions containing $p\|0\|$ for a fresh $p$ — a property required to guarantee invariance of types under structural congruence of networks.
Example 6.8. The first network of Example 5.14 and the network of Example 5.16 can be typed respectively by

\[ \begin{align*}
G &= p \rightarrow q : (\lambda ; G \bigcirc \lambda') \\
G' &= p \rightarrow q; q \rightarrow r; r \rightarrow s
\end{align*} \]

It is handy to define the LTS for global types given in Figure 4. Rule [Icomm] is justified by the fact that in a projectable global type \( p \rightarrow q : (\lambda ; G \bigcirc \lambda') \), the behaviours of the participants different from \( p \) and \( q \) are the same in all branches, and hence they are independent from the choice and may be executed before it. This LTS respects well-formedness of global types, as shown in Proposition 6.10.

We start with a lemma relating the projections of a well-formed global type with its transitions.

Lemma 6.9. Let \( G \) be a well-formed global type.

1. If \( \vdash G \upharpoonright p = \bigoplus_{i \in I} q_i \lambda_i; P_i \) and \( \vdash G \upharpoonright q = \sum_{j \in J} p_j ? \lambda'_j; Q_j \), then \( I = J \), \( \lambda_i = \lambda'_j \), \( G \xrightarrow{pq\lambda_i} G_i \), \( G_i \upharpoonright p = P_i \) and \( G_i \upharpoonright q = Q_i \) for all \( i \in I \).
2. If \( G \xrightarrow{pq\lambda} G' \), then \( G \upharpoonright p = \bigoplus_{i \in I} q_i \lambda_i; P_i \), \( G \upharpoonright q = \sum_{i \in I} p_i \lambda_i; Q_i \), where \( \lambda_i = \lambda \) for some \( i \in I \), and \( G' \upharpoonright r = G \upharpoonright r \) for all \( r \neq \{p, q\} \).

Proposition 6.10. If \( G \) is a well-formed global type and \( G \xrightarrow{pq\lambda} G' \), then \( G' \) is a well-formed global type.

Proof If \( G \xrightarrow{pq\lambda} G' \), by Lemma 6.9(1) and (2) \( G' \upharpoonright r \) is defined for all \( r \). The proof that \( \text{depth}(G', r) \) for all \( r \) and \( G'' \) subtree of \( G' \) is easy by induction on the transition rules of Figure 4.

Given the previous proposition, we will focus on well-formed global types from now on.

We end this section with the expected proofs of Subject Reduction, Session Fidelity [38, 39] and Progress [19, 50], which use Inversion and Canonical Form lemmas.

Lemma 6.11 (Inversion). If \( \vdash N : G \), then \( P \leq G \upharpoonright p \) for all \( p \in P \).
Lemma 6.12 (Canonical Form). If \( \vdash N : G \) and \( p \in \text{part}(G) \), then \( \text{p[a]} P \mapsto \text{p[a]} N \) and \( P \leq G \vdash p \).

Theorem 6.13 (Subject Reduction). If \( \vdash N : G \) and \( N \xrightarrow{a} N' \), then \( G \xrightarrow{a} G' \) and \( \vdash N' : G' \).

Proof Let \( \alpha = pq\lambda \). By Rule [Com] of Figure 1, \( G \vdash p \mapsto G' \) and \( G \vdash q \mapsto G'' \). From Lemma 6.11 and Lemma 6.12 we get

1. \( G \vdash p = \bigoplus_{i \in I} q! \lambda_i; p_i \) with \( p_i \leq p_i' \) for all \( i \in I \), from Rule [\( \leq -\text{Out} \)] of Figure 3 and
2. \( G \vdash q = \sum_{i \notin I} p? \lambda_i; q_i' \) with \( q_j \leq q_j' \) for all \( j \notin J \), from Rule [\( \leq -\text{In} \)] of Figure 3 and
3. \( R \leq G \vdash R \) for all \( R \in N'' \).

By Lemma 6.9(1) \( G \xrightarrow{pq\lambda} G_i \) and \( G_i \vdash p = p_i' \) and \( G_i \vdash q = q_i' \). By Lemma 6.9(2) \( G_i \vdash R = G \vdash R \) for all \( R \notin \{p, q\} \). We can then choose \( G' = G_i \).

Theorem 6.14 (Session Fidelity). If \( \vdash N : G \) and \( G \xrightarrow{a} G' \), then \( N \xrightarrow{a} N' \) and \( \vdash N' : G' \).

Proof Let \( \alpha = pq\lambda \). By Lemma 6.9(2) \( G \vdash p = \bigoplus_{i \in I} p! \lambda_i; p_i \) and \( G \vdash q = \sum_{i \notin I} p? \lambda_i; q_i \) and \( \lambda = \lambda_i \) for some \( i \in I \) and \( G' \vdash R = G \vdash R \) for all \( R \notin \{p, q\} \). By Lemma 6.9(1) \( G' \vdash p = p_i \) and \( G' \vdash q = q_i \). From Lemma 6.12 and Lemma 6.11 we get

1. \( P = \bigoplus_{i \in I} q! \lambda_i; p_i' \) with \( p_i' \leq p_i \) for all \( i \in I \), from Rule [\( \leq -\text{Out} \)] of Figure 3 and
2. \( Q = \sum_{i \notin I} p? \lambda_i; q_i' \) with \( q_j \leq q_j' \) for all \( j \notin J \), from Rule [\( \leq -\text{In} \)] of Figure 3 and
3. \( R \leq G \vdash R \) for all \( R \in N'' \).

We can then choose \( N' = \text{p[a]} P_i' \) and \( \text{q[a]} Q_i' \) and \( N'' \).

We are now able to prove that in a typable network, every participant whose process is not terminated may eventually perform a communication. This property is generally referred to as progress.

Theorem 6.15 (Progress). If \( \vdash N : G \) and \( \text{p[a]} P \mapsto N \), then \( N \xrightarrow{a} N' \) and \( \text{p[a]} N \).

Proof We prove by induction on \( d = \text{depth}(G, p) \) that: if \( \vdash N : G \) and \( \text{p[a]} P \mapsto N \), then \( G \xrightarrow{a} G' \) with \( \text{p[a]} P \mapsto \text{p[a]} N \). This will imply \( N \xrightarrow{a} N' \) by Session Fidelity (Theorem 6.14).

Case \( d = 1 \). In this case \( G = q \rightarrow r : \bigoplus_{i \in I} \lambda_i; G_i \) and \( p \in \{q, r\} \) and \( G \xrightarrow{qr\lambda_h} G_i \) for some \( h \in I \) by Rule [Ecomm].

Case \( d > 1 \). In this case \( G = q \rightarrow r : \bigoplus_{i \in I} \lambda_i; G_i \) and \( p \notin \{q, r\} \). By Lemma 6.5 this implies \( \text{depth}(G_i, p) < d \) for all \( i \in I \). Using Rule [Ecomm] we get \( G \xrightarrow{qr\lambda_i} G_i \) for all
By Session Fidelity, \( N \xrightarrow{qr} N_i \) and \( + N_i : G_i \) for all \( i \in I \). Moreover, since \( p \notin \{q, r\} \) we also have \( p \parallel [P] \in N_i \) for all \( i \in I \). By induction \( G_i \xrightarrow{a_i \cdot a_i} G'_i \) with \( p \in \text{part}(\alpha_i) \) for all \( i \in I \). We conclude \( G \xrightarrow{qr \lambda \cdot \alpha \cdot \sigma_i} G'_i \) for all \( i \in I \).

The proof of the progress theorem shows that the execution strategy which uses only Rule [EComm] is fair, since there are no infinite transition sequences where some participant is stuck. This is due to the boundedness condition on global types.

**Example 6.16.** The second network of Example 5.14 and the network of Example 5.19 cannot be typed because they do not enjoy progress. Notice that the candidate global type for the second network of Example 5.14:

\[ G'' = p \rightarrow q : (\lambda; G'' \boxplus \lambda'; p \xrightarrow{\lambda} r; r \xrightarrow{\lambda'} s) \]

is not bounded, given that \( \text{depth}(G'', r) \) and \( \text{depth}(G'', s) \) are not finite. Moreover we cannot define a global type whose projections are greater than or equal to the processes associated with the network of Example 5.19.

### 7. Event Structure Semantics of Global Types

We define now the event structure associated with a global type, which will be a PES whose events are equivalence classes of particular traces.

We recall that a trace \( \sigma \in \text{Traces} \) is a finite sequence of communications (see Definition 2.3). We will use the following notational conventions:

- We denote by \( \sigma[i] \) the \( i \)-th element of \( \sigma \), \( i > 0 \).
- If \( i \leq j \), we define \( \sigma[i ... j] = \sigma[i] \cdots \sigma[j] \) to be the subtrace of \( \sigma \) consisting of the \((j - i + 1)\) elements starting from the \( i \)-th one and ending with the \( j \)-th one. If \( i > j \), we convene \( \sigma[i ... j] \) to be the empty trace \( \epsilon \).

If not otherwise stated we assume that \( \sigma \) has \( n \) elements, so \( \sigma = \sigma[1 ... n] \).

We start by defining an equivalence relation on \( \text{Traces} \) which allows swapping of communications with disjoint participants.

**Definition 7.1 (Permutation equivalence).** The permutation equivalence on \( \text{Traces} \) is the least equivalence \( \sim \) such that

\[ \sigma \cdot \alpha \cdot \sigma' \sim \sigma \cdot \alpha' \cdot \sigma' \quad \text{if} \quad \text{part}(\alpha) \cap \text{part}(\alpha') = \emptyset \]

We denote by \([\sigma]_\sim \) the equivalence class of the trace \( \sigma \), and by \( \text{Traces}/\sim \) the set of equivalence classes on \( \text{Traces} \). Note that \([\epsilon]_\sim = [\epsilon] \in \text{Traces}/\sim \), and \([\alpha]_\sim = [\alpha] \in \text{Traces}/\sim \) for any \( \alpha \). Moreover \([\sigma'] = [\sigma] \) for all \( \sigma' \in [\sigma]_\sim \).

The events associated with a global type, called g-events and denoted by \( \gamma, \gamma' \), are equivalence classes of particular traces that we call pointed. Intuitively, in a pointed trace all communications but the last one are causes of some subsequent communication. Formally:
Definition 7.2 (Pointed trace). A trace $\sigma = \sigma[1...n]$ is said to be pointed if

$$\text{for all } i, 1 \leq i < n, \text{ part}(\sigma[i]) \cap \text{ part}(\sigma[(i+1)...n]) \neq \emptyset$$

Note that the condition of Definition 7.2 must be satisfied only by the $\sigma[i]$ with $i < n$, thus it is vacuously satisfied by any trace of length 1.

Example 7.3. Let $\alpha_1 = pq\lambda_1$, $\alpha_2 = rs\lambda_2$ and $\alpha_3 = rp\lambda_3$. Then $\alpha_1 = \alpha_1$ and $\alpha_3 = \alpha_1 \cdot \alpha_2 \cdot \alpha_3$ are pointed traces, while $\alpha_2 = \alpha_1 \cdot \alpha_2$ is not a pointed trace.

We use $\text{last}(\sigma)$ to denote the last communication of $\sigma$.

Lemma 7.4. Let $\sigma$ be a pointed trace. If $\sigma \sim \sigma'$, then $\sigma'$ is a pointed trace and $\text{last}(\sigma) = \text{last}(\sigma')$.

Proof Let $\sigma \sim \sigma'$. By Definition 7.1 $\sigma'$ is obtained from $\sigma$ by $m$ swaps of adjacent communications. The proof is by induction on such a number $m$.

If $m = 0$ the result is obvious.

If $m > 0$, then there exists $\sigma_0$ obtained from $\sigma$ by $m - 1$ swaps of adjacent communications and there are $\sigma_1$, $\sigma_2$, $\alpha$ and $\alpha'$ such that

$$\sigma_0 = \sigma_1 \cdot \alpha \cdot \alpha' \cdot \sigma_2 \sim \sigma_1 \cdot \alpha' \cdot \alpha \cdot \sigma_2 = \sigma'$$

and $\text{part}(\sigma) \cap \text{part}(\sigma') = \emptyset$.

By induction hypothesis $\sigma_0$ is a pointed trace and $\text{last}(\sigma) = \text{last}(\sigma_0)$. Therefore $\sigma_2 \neq \emptyset$ since otherwise $\alpha'$ would be the last communication of $\sigma_0$ and it cannot be $\text{part}(\sigma) \cap \text{part}(\sigma') = \emptyset$. This implies $\text{last}(\sigma) = \text{last}(\sigma')$.

To show that $\sigma'$ is pointed, since all the communications in $\sigma_1$ and $\sigma_2$ have the same successors in $\sigma_0$ and $\sigma'$, all we have to prove is that the required property holds for the two swapped communications $\alpha'$ and $\alpha$ in $\sigma'$, namely:

$$\text{part}(\sigma') \cap \text{part}(\sigma) \neq \emptyset$$

$$\text{part}(\sigma') \cap \text{part}(\sigma) \neq \emptyset$$

Since $\text{part}(\sigma) \cap \text{part}(\sigma') = \emptyset$, these two statements are respectively equivalent to:

$$\text{part}(\sigma') \cap \text{part}(\sigma) \neq \emptyset$$

$$\text{part}(\sigma') \cap \text{part}(\sigma) \neq \emptyset$$

The last two statements are known to hold since $\sigma_0$ is pointed by induction hypothesis.

Definition 7.5 (Global event). Let $\sigma = \alpha' \cdot \alpha$ be a pointed trace. Then $\gamma = [\sigma]_-$ is a global event, also called g-event, with communication $\alpha$, notation $\text{cm}(\gamma) = \alpha$.

We denote by $\mathcal{GE}$ the set of g-events.

Notice that $\text{cm}(\cdot)$ is well defined due to Lemma 7.4.

We now introduce an operator called “retrieval”, which applied to a communication $\alpha$ and a g-event $\gamma$, yields the g-event corresponding to $\gamma$ before the communication $\alpha$ is executed.
Definition 7.6 (Retrieval of g-events before communications).

1. The retrieval operator $\circ$ applied to a communication and a g-event is defined by

$$\alpha \circ \sigma = \begin{cases} \{ \alpha \cdot \sigma \} \text{ if } \text{part}(\alpha) \cap \text{part}(\sigma) \neq \emptyset \\ \{ \sigma \} \text{ otherwise} \end{cases}$$

2. The operator $\circ$ naturally extends to nonempty traces

$$(\alpha \cdot \sigma) \circ \gamma = \alpha \circ (\sigma \circ \gamma) \quad \sigma \neq \epsilon$$

Using the retrieval, we can define the mapping $\text{ev}(\cdot)$ which, applied to a trace $\sigma$, gives the g-event representing the communication $\text{last}(\sigma)$ prefixed by its causes occurring in $\sigma$.

Definition 7.7. The g-event generated by a trace is defined by:

$$\text{ev}(\sigma \cdot \alpha) = \sigma \circ \{ \alpha \}$$

Clearly $\text{cm}(\text{ev}(\sigma)) = \text{last}(\sigma)$.

We proceed now to define the causality and conflict relations on g-events. To define the conflict relation, it is handy to define the projection of a trace on a participant, which gives the sequence of the participant’s actions in the trace.

Definition 7.8 (Projection). 1. The projection of $\alpha$ onto $r$, $\alpha @ r$, is defined by:

$$pq@r = \begin{cases} q! \lambda & \text{if } r = p \\ p? \lambda & \text{if } r = q \\ \epsilon & \text{if } r \notin \{p, q\} \end{cases}$$

2. The projection of a trace $\sigma$ onto $r$, $\sigma @ r$, is defined by:

$$\epsilon @ r = \epsilon \quad (\alpha \cdot \sigma) @ r = \alpha @ r \cdot \sigma @ r$$

Definition 7.9 (Causality and conflict relations on g-events). The causality relation $\leq$ and the conflict relation $#$ on the set of g-events $\mathcal{G}$ are defined by:

1. $\gamma \leq \gamma'$ if $\gamma = [\sigma]_-$ and $\gamma' = [\sigma \cdot \alpha']_-$ for some $\sigma, \sigma'$;

2. $[\sigma]_-, [\sigma']_-$ if $\sigma @ p \neq \sigma' @ p$ for some $p$.

If $\gamma = [\sigma \cdot \alpha \cdot \alpha']_-$, then the communication $\alpha$ must be done before the communication $\alpha'$. This is expressed by the causality $[\sigma \cdot \alpha]_- \leq \gamma$. An example is $[pq\lambda]_- \leq [rs\lambda' \cdot pq\lambda \cdot sq\lambda']_-$. As regards conflict, note that if $\sigma \sim \sigma'$ then $\sigma @ p = \sigma' @ p$ for all $p$, because $\sim$ does not swap communications which share some participant. Hence, conflict is well defined, since it does not depend on the trace chosen in the equivalence class. The condition $\sigma @ p \neq \sigma' @ p$ states that participant $p$ does the same actions in both traces up to some point, after which it performs two different actions in $\sigma$ and $\sigma'$. For example $[pq\lambda \cdot rp\lambda_1 \cdot qp\lambda']_- \neq [pq\lambda \cdot rp\lambda_2]_-$, since $(pq\lambda \cdot rp\lambda_1 \cdot qp\lambda') @ p = q! \lambda \cdot r? \lambda_1 \cdot q? \lambda' \# q! \lambda \cdot r? \lambda_2 = (pq\lambda \cdot rp\lambda_2) @ p$. 

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Definition 7.10 (Event structure of a global type). The event structure of the global type $G$ is the triple

$$S^G(G) = (\mathcal{GE}(G), \leq_G, \#_G)$$

where:

1. $\mathcal{GE}(G) = \{ev(\sigma) \mid \sigma \in Tr^+(G)\}$
2. $\leq_G$ is the restriction of $\leq$ to the set $\mathcal{GE}(G)$;
3. $\#_G$ is the restriction of $\#$ to the set $\mathcal{GE}(G)$.

Note that, in case the tree of $G$ is infinite, the set $\mathcal{GE}(G)$ is denumerable.

Example 7.11. Let $G_1 = p \rightarrow a; r \rightarrow s; r \rightarrow p$ and $G_2 = r \rightarrow s; p \rightarrow q; r \rightarrow p$. Then $\mathcal{GE}(G_1) = \mathcal{GE}(G_2) = \{\gamma_1, \gamma_2, \gamma_3\}$ where

$$\gamma_1 = \{pq, l_1\} \quad \gamma_2 = \{rs, l_2\} \quad \gamma_3 = \{pq, l_1 \cdot rs, l_2 \cdot rp, l_3, rs, l_2 \cdot pq, l_1 \cdot rp, l_3\}$$

with $\gamma_1 \leq \gamma_3$ and $\gamma_2 \leq \gamma_3$. The configurations are $\{\gamma_1\}, \{\gamma_2\}, \{\gamma_1, \gamma_2\}$ and $\{\gamma_1, \gamma_2, \gamma_3\}$, and the proving sequences are

$$\gamma_1 \quad \gamma_2 \quad \gamma_1; \gamma_2 \quad \gamma_2; \gamma_1 \quad \gamma_1; \gamma_2; \gamma_3 \quad \gamma_2; \gamma_1; \gamma_3$$

If $G'$ is as in Example 6.8 then $\mathcal{GE}(G') = \{\gamma_1, \gamma_2, \gamma_3\}$ where

$$\gamma_1 = \{pq, l_1\} \quad \gamma_2 = \{pq, l_1 \cdot qr, l_2\} \quad \gamma_3 = \{pq, l_1 \cdot qr, l_2 \cdot rs, l_3\}$$

with $\gamma_1 \leq \gamma_2 \leq \gamma_3$. The configurations are $\{\gamma_1\}, \{\gamma_1, \gamma_2\}$ and $\{\gamma_1, \gamma_2, \gamma_3\}$, and there is a unique proving sequence corresponding to each configuration.

Theorem 7.12. Let $G$ be a global type. Then $S^G(G)$ is a prime event structure.

Proof. We show that $\leq$ and $\#$ satisfy Properties (2) and (3) of Definition 3.1. Reflexivity and transitivity of $\leq$ follow from the properties of concatenation and of permutation equivalence. As for antisymmetry, by Definition 7.9.1 $[\sigma]_\leq \leq [\sigma']_\leq$ implies $\sigma' \sim \sigma \cdot \sigma_1$ for some $\sigma_1$ and $[\sigma']_\leq \leq [\sigma]_\leq$ implies $\sigma \sim \sigma' \cdot \sigma_2$ for some $\sigma_2$. Hence $\sigma \sim \sigma \cdot \sigma_1 \cdot \sigma_2$, which implies $\sigma_1 = \sigma_2 = \varepsilon$. Irreflexivity and symmetry of $\#$ follow from the corresponding properties of $\#$ on $p$-events.

As for conflict hereditariness, suppose that $[\sigma]_\leq \# [\sigma'']_\leq$. By Definition 7.9.1 and (2) we have respectively that $\sigma' \cdot \sigma_1 \sim \sigma''$ for some $\sigma_1$ and $\sigma \oplus p \# \sigma' \oplus p$ for some $p$. Hence also $\sigma \oplus p \# (\sigma' \cdot \sigma_1) \oplus p$, whence by Definition 7.9.2 we conclude that $[\sigma]_\leq \# [\sigma'']_\leq$.

Observe that while our interpretation of networks as FESs exactly reflects the concurrency expressed by the syntax of networks, our interpretation of global types as PESs exhibits more concurrency than that given by the syntax of global types.

We conclude this section with two pictures that summarise the features of our ES semantics and illustrate the difference between the FES of a network and the...
the n-events on the right of the line. In particular, notice that the conflicts between
flow relation and all the n-events on the left of the dotted line are in conflict with all
network is itself a PES.

Consider the network FES pictured in Figure 5, where the arrows represent the
\[ \gamma_1 = \{\text{pq} \lambda_1\} \]
\[ \gamma = \{\text{pq} \lambda_1 \cdot \text{pr} \lambda \cdot \text{qs} \lambda' \cdot \text{rs} \lambda''\} \]
\[ \gamma' = \{\text{pq} \lambda_2 \cdot \text{pr} \lambda \cdot \text{qs} \lambda' \cdot \text{rs} \lambda''\} \]
\[ \gamma' = \{\text{pq} \lambda_2 \cdot \text{pr} \lambda \cdot \text{qs} \lambda' \cdot \text{rs} \lambda''\} \]

Figure 5: FES of the network N.

Figure 6: PES of the type G.

PES of its type. In general these two ESs are not isomorphic, unless the FES of the
network is itself a PES.

Consider the network FES pictured in Figure 5, where the arrows represent the
flow relation and all the n-events on the left of the dotted line are in conflict with all
the n-events on the right of the line. In particular, notice that the conflicts between
n-events with a common location are deduced by Clause (2a) of Definition 5.7 while the conflicts between n-events with disjoint sets of locations, such as $\nu_1'$ and $\nu_2''$, are deduced by Clause (2b) of Definition 5.7. Observe also that the n-event $\nu$ has two different causal sets in $\mathcal{NE}(N)$, namely $\{\nu_1',\nu_1''\}$ and $\{\nu_2',\nu_2''\}$. The reader familiar with ESs will have noticed that there are also two prime configurations whose maximal element is $\nu$, namely $\{\nu_1,\nu_1',\nu_1'',\nu\}$ and $\{\nu_2,\nu_2',\nu_2'',\nu\}$. It is easy to see that the network $N$ can be typed with the global type shown in Figure 6.

Consider now the PES of the type $G$ pictured in Figure 6, where the arrows represent the covering relation of the partial order of causality and inherited conflicts are not shown. Note that while the FES of $N$ has a unique maximal n-event $\nu$, the PES of its type $G$ has two maximal g-events $\gamma$ and $\gamma'$. This is because an n-event only records the computations that occurred at its locations, while a g-event records the global computation and keeps a record of each choice, including those involving locations that are disjoint from those of its last communication. Indeed, g-events correspond exactly to prime configurations.

Note that the FES of a network may be easily recovered from the PES of its global type by using the following function $\text{gn}()$ that maps g-events to n-events:

$$\text{gn}(\gamma) = \{p :: o @ p, q :: o @ q\} \quad \text{if} \quad \gamma = [o] \quad \text{with} \quad \text{part(cm}(\gamma)) = \{p, q\}$$

On the other hand, the inverse construction is not as direct. First of all, an n-event in the network FES may give rise to several g-events in the type PES, as shown by the n-event $\nu$ in Figure 5 which gives rise to the pair of g-events $\gamma$ and $\gamma'$ in Figure 6. Moreover, the local information contained in an n-event is not sufficient to reconstruct the corresponding g-events: for each n-event, we need to consider all the prime configurations that culminate with that event, and then map each of these configurations to a g-event. Hence, we need a function $\text{ng}()$ that maps n-events to sets of prime configurations of the FES, and then maps each such configuration to a g-event. We will not explicitly define this function here, since we miss another important ingredient to compare the FES of a network and the PES of its type, namely a structural characterisation of the FESs that represent typable networks. Indeed, if we started from the FES of a non typable network, this construction would not be correct. Consider for instance the network $N'$ obtained from $N$ by omitting the output $t!\lambda$ from the second branch of the process of $p$. Then the FES of $N'$ would not contain the n-event $\nu_2'$ and the event $\nu$ would have the unique causal set $\{\nu_1',\nu_2''\}$, and the unique prime configuration culminating with $\nu$ would be $\{\nu_1,\nu_1',\nu_1'',\nu\}$. Then our construction would give a PES that differs from that of type $G$ only for the absence of the g-events $\gamma_2'$ and $\gamma'$. However, the network $N'$ is not typable and thus we would expect the construction to fail. Note that in the FES of $N'$, the n-event $\nu_2'$ is a cause of $\nu$ but does not belong to any causal set of $\nu$. Thus a possible well-formedness property to require for FESs to be images of a typable network would be that each cause of each n-event belong to some causal set of that event. However, this would still not be enough to exclude the FES of the non typable network $N''$ obtained from $N'$ by omitting the output $s!\lambda'$ from the

\footnote{A prime configuration is a configuration with a unique maximal element, its culminating event.}
second branch of the process of $q$.

To conclude, in the absence of a semantic counterpart for the well-formedness properties of global types, which eludes us for the time being, we will follow another approach here, namely we will compare the FESs of networks and the PESs of their types at a more operational level, by looking at their configuration domains and by relating their configurations to the transition sequences of the underlying networks and types.

8. Equivalence of the two Event Structure Semantics

![Diagram of isomorphism proof in a nutshell.](image)

In this section we establish our main result for typable networks, namely the isomorphism between the domain of configurations of the FES of such a network and the domain of configurations of the PES of its global type. To do so, we will first relate the transition sequences of networks and global types to the configurations of their respective ESs. Then, we will exploit our results of Subject Reduction (Theorem 6.13) and Session Fidelity (Theorem 6.14), which relate the transition sequences of networks and their global types, to derive a similar relation between the configurations of their respective ESs. The schema of our proof is described by the diagram in Figure 7. Here, SR stands for Subject Reduction and SF for Session Fidelity, $\nu_1;\cdots;\nu_n$ and $\gamma_1;\cdots;\gamma_n$ are proving sequences of $S^N(N)$ and $S^G(G)$, respectively. Finally $\text{nect}(\sigma)$ and $\text{gec}(\sigma)$ denote the proving sequence of $n$-events and the proving sequence of $g$-events corresponding to the trace $\sigma$ (as given in Definition 8.3 and Definition 8.13). Theorem 8.8 says that, if $\nu_1;\cdots;\nu_n$ is a proving sequence of $S^N(N)$, then $N \overset{\text{nect}(\sigma)}{\rightarrow} N'$, where $\sigma = \text{cm}(\nu_1) \cdots \text{cm}(\nu_n)$. By Subject Reduction (Theorem 6.13) $G \overset{\text{gec}(\sigma)}{\rightarrow} G'$. This implies that $\text{gec}(\sigma)$ is a proving sequence of $S^G(G)$ by Theorem 8.15. Dually, Theorem 8.16 says that, if $\gamma_1;\cdots;\gamma_n$ is a proving sequence of $S^G(G)$, then $G \overset{\text{gec}(\sigma)}{\rightarrow} G'$, where $\sigma = \text{cm}(\gamma_1) \cdots \text{cm}(\gamma_n)$. By Session Fidelity (Theorem 6.14) $N \overset{\text{gec}(\sigma)}{\rightarrow} N'$.

Lastly $\text{nect}(\sigma)$ is a proving sequence of $S^N(N)$ by Theorem 8.7. The equalities in the top and bottom lines are proved in Lemmas 8.4(1a) and 8.14(1).

This section is divided in two subsections: Section 8.1 which handles the upper part of the above diagram, and Section 8.2 which handles the lower part of the diagram and then connects the two parts using both SR and SF within Theorem 8.18, our closing result.
8.1. Relating Transition Sequences of Networks and Proving Sequences of their ESs

The aim of this subsection is to relate the traces that label the transition sequences of networks with the configurations of their ESs. We start by showing how network communications affect n-events in the associated ES. To this end we define two partial operators ♦ and ♦, which applied to a communication α and an n-event ν yield another n-event ν′ (when defined), which represents the event ν before the communication α or after the communication α, respectively. We call “retrieval” the ♦ operator (in agreement with Definition 7.6) and “residual” the ♦ operator.

Formally, the operators ♦ and ♦ are defined as follows.

**Definition 8.1 (Retrieval and residual of n-events with respect to communications).**

1. The retrieval operator ♦ applied to a communication and a located event returns the located event obtained by prefixing the process event by the projection of the communication:
   \[ α ♦ (p :: η) = p :: (α@p) · η \]

2. The residual operator ♦ applied to a communication and a located event returns the located event obtained by erasing from the process event the projection of the communication (if possible):
   \[ α ♦ (p :: η) = p :: η' \quad \text{if} \quad η = (α@p) · η' \]

3. The operators ♦ and ♦ naturally extend to n-events and to traces:

   - \[ α ♦ ((p :: η, q :: η')) = {α ♦ (p :: η), α ♦ (q :: η')} \]
   - \[ α ♦ ((p :: η, q :: η')) = {α ♦ (p :: η), α ♦ (q :: η')} \]
   - \[ e ♦ ν = ν \quad (α · σ) ♦ ν = α ♦ (σ ν) \quad (α · σ) ♦ ν = σ ♦ (α ♦ ν) \quad σ ≠ e \]

Note that the operator ♦ is always defined. Instead \[ pqλ ♦ r :: η \] is undefined if \[ r ∈ \{p, q\} \] and either η is just one atomic action or \[ pqλ@r \] is not the first atomic action of η.

The retrieval and residual operators are inverse of each other. Moreover they preserve the flow and conflict relations.

**Lemma 8.2 (Properties of retrieval and residual for n-events).**

1. If \[ α ♦ ν \] is defined, then \[ α ♦ (α ♦ ν) = ν \]
2. \[ α ♦ (α ♦ ν) = ν \]
3. If \[ ν < ν' \], then \[ α ♦ ν < α ♦ ν' \]
4. If \[ ν < ν' \] and both \[ α ♦ ν \] and \[ α ♦ ν' \] are defined, then \[ α ♦ ν < α ♦ ν' \]
5. If \[ ν # ν' \], then \[ α ♦ ν # α ♦ ν' \]
6. If \( \nu \neq \nu' \) and both \( \alpha \cdot \nu \) and \( \alpha \cdot \nu' \) are defined, then \( \alpha \cdot \nu \neq \alpha \cdot \nu' \).

7. If \( \alpha \circ \nu \neq \alpha \circ \nu' \), then \( \nu \neq \nu' \).

Starting from the trace \( \sigma \neq \epsilon \) that labels a transition sequence in a network, one can reconstruct the corresponding sequence of n-events in its FES. Recall that \( \sigma[1 \ldots i] \) is the prefix of length \( i \) of \( \sigma \) and \( \sigma[i \ldots j] \) is the empty trace if \( i \geq j \).

**Definition 8.3 (Building sequences of n-events from traces).** If \( \sigma \) is a trace with \( \sigma[i] = p_i q_i \lambda_i, 1 \leq i \leq n \), we define the sequence of n-events corresponding to \( \sigma \) by

\[
\text{nec}(\sigma) = v_1; \cdots ; v_n
\]

where \( v_i = \sigma[1 \ldots i - 1] \circ (p_i :: q_i! \lambda_i, q_i :: p_i \lambda_i) \) for \( 1 \leq i \leq n \).

It is immediate to see that, if \( \sigma = pq\lambda \), then \( \text{nec}(\sigma) \) is the event \( (p :: q! \lambda, q :: p \lambda) \).

We show now that two n-events occurring in \( \text{nec}(\sigma) \) cannot be in conflict and that from \( \text{nec}(\sigma) \) we can recover \( \sigma \). Moreover we relate the retrieval and residual operators with the mapping \( \text{nec}(-) \).

**Lemma 8.4 (Properties of \( \text{nec}(-) \)).**

1. Let \( \text{nec}(\sigma) = v_1; \cdots ; v_n \). Then
   
   (a) \( \text{cm}(v_i) = \sigma[i] \) for all \( i, 1 \leq i \leq n \);
   
   (b) If \( 1 \leq h, k \leq n \), then \( \neg(v_h \neq v_k) \).

2. \( \neg(\text{nec}(\alpha) \# \alpha \circ \nu) \) for all \( \nu \).

3. Let \( \sigma = \alpha \cdot \sigma' \) and \( \sigma' \neq \epsilon \). If \( \text{nec}(\sigma) = v_1; \cdots ; v_n \) and \( \text{nec}(\alpha') = v'_2; \cdots ; v'_n \), then
   
   \( \alpha \circ v'_i = v_i \) and \( \alpha \cdot v_i = v'_i \) for all \( i, 2 \leq i \leq n \).

**Proof**

1. (a) Immediate from Definition 8.3 since \( \text{cm}(\alpha \in \nu) = \text{cm}(\nu) \) for any event \( \nu \).

2. (b) We show that neither Clause (2a) nor Clause (2b) of Definition 5.7 can be used to derive \( v_h \neq v_k \). Notice that \( v_i = [p_i :: \sigma[1 \ldots i] \circ p_i, q_i :: \sigma[1 \ldots i] \circ q_i] \). So if \( p :: \eta \in v_h \) and \( p' :: \eta' \in v_k \) with \( h \neq k \), then either \( \eta \neq \eta' \) or \( \eta = \eta' \). Therefore Clause (2a) does not apply. If \( p :: \eta \in v_h \) and \( q :: \eta' \in v_k \) and \( p \neq q \) and \( |\eta \upharpoonright q | = |\eta' \upharpoonright p | \), then it must be \( \eta \upharpoonright q = (\sigma[1 \ldots h] \circ p) \upharpoonright q \cong (\sigma[1 \ldots k] \circ q) \upharpoonright p = \eta' \upharpoonright p \). Therefore Clause (2b) cannot be used.

2. (b) We show that neither Clause (2a) nor Clause (2b) of Definition 5.7 can be used to derive \( \text{nec}(\alpha) \# \alpha \circ \nu \). Let \( \text{part}(\alpha) = \{p, q\} \). Then \( \text{nec}(\alpha) = \{p :: \alpha \circ p, q :: \alpha \circ q\} \).

Note that \( p :: \eta \in \alpha \circ \nu \) iff \( \eta = (\alpha \circ p) \cdot \eta' \) and \( p :: \eta' \in \nu \). Since \( \alpha \circ p < (\alpha \circ p) \cdot \eta' \), Clause (2a) of Definition 5.7 cannot be used. Now suppose \( r :: \eta \in \alpha \circ \nu \) for some \( r \notin \{p, q\} \). In this case \( (\alpha \circ p) \upharpoonright r = (\alpha \circ q) \upharpoonright r = \epsilon \). Therefore, since \( \epsilon \cong \epsilon \), Clause (2b) of Definition 5.7 does not apply.

3. Notice that \( \sigma[i] = \sigma'[i - 1] \) for all \( i, 2 \leq i \leq n \). Then, by Definition 8.3

\[
v_i = \sigma[1 \ldots i - 1] \circ \text{nec}(\sigma[i]) = \alpha \circ (\sigma[2 \ldots i - 1] \circ \text{nec}(\sigma[i])) = \alpha \circ (\sigma'[1 \ldots i - 2] \circ \text{nec}(\sigma'[i - 1])) = \alpha \circ v'_i
\]

for all \( i, 2 \leq i \leq n \).

By Lemma 8.2 \( \alpha \circ v'_i = v_i \) implies \( \alpha \cdot v_i = v'_i \) for all \( i, 2 \leq i \leq n \).
It is handy to notice that if $\alpha \uparrow v$ is undefined and $v$ is an event of a network with communication $\alpha$, then either $v = \text{nec}(\alpha)$ or $v \# \text{nec}(\alpha)$.

**Lemma 8.5**. If $N \xrightarrow{\alpha} N'$ and $v \in \mathcal{NE}(N)$, then $v = \text{nec}(\alpha)$ or $v \# \text{nec}(\alpha)$ or $\alpha \uparrow v$ is defined.

**Proof** Let $\text{nec}(\alpha) = \{p :: \alpha@p, q :: \alpha@q\}$ and $v = \{r :: \eta, s :: \eta'\}$. By Definition 8.1(3) $\alpha \uparrow v$ is defined iff $\eta = (\alpha@r) \cdot \eta_0$ and $\eta' = (\alpha@s) \cdot \eta'_0$ for some $\eta_0, \eta'_0$.

There are 2 possibilities:

- $\{r, s\} \cap \{p, q\} = \emptyset$. Then $\alpha@r = \alpha@s = \epsilon$ and $\alpha \uparrow v = v$;
- $\{r, s\} \cap \{p, q\} \neq \emptyset$. Suppose $r = p$.

There are three possible subcases:

1. $\eta = \pi \cdot \zeta$ with $\pi \neq \alpha@p$. Then $r :: \eta \# p :: \alpha@p$ and thus $v \# \text{nec}(\alpha)$;
2. $\eta = \alpha@p$. Then either $\eta' = \alpha@q$ and $v = \text{nec}(\alpha)$, or $\eta' \neq \alpha@q$ and $v \# \text{nec}(\alpha)$ by Proposition 5.20;
3. $\eta = (\alpha@p) \cdot \eta_0$. Then $\alpha \uparrow p :: \eta = p :: \eta_0$. Now, if $s \neq q$ we have $\alpha \uparrow s :: \eta' = s :: \eta'$, and thus $\alpha \uparrow v = \{p :: \eta_0, s :: \eta'\}$. Otherwise, $v = \{p :: (\alpha@p) \cdot \eta_0, q :: \eta'\}$.

By Definition 5.5 $p :: (\alpha@p) \cdot \eta_0 \not\approx q :: \eta'$, which implies $\eta' = (\alpha@q) \cdot \eta'_0$ for some $\eta'_0$.

The following lemma, which is technically quite challenging, relates the n-events of two networks which differ for one communication by means of the retrieval and residual operators.

**Lemma 8.6**. Let $N \xrightarrow{\alpha} N'$. Then

1. $\{\text{nec}(\alpha)\} \cup \{\alpha \uparrow v \mid v \in \mathcal{NE}(N')\} \subseteq \mathcal{NE}(N)$;
2. $\{\alpha \uparrow v \mid v \in \mathcal{NE}(N) \text{ and } \alpha \uparrow v \text{ defined} \} \subseteq \mathcal{NE}(N')$.

We may now prove the correspondence between the traces labelling the transition sequences of a network and the proving sequences of its FES.

**Theorem 8.7**. If $N \xrightarrow{\sigma} N'$, then $\text{nec}(\sigma)$ is a proving sequence in $\mathcal{SN}(N)$.

**Proof** The proof is by induction on $\sigma$.

**Base case.** Let $\sigma = \alpha$. From $N \xrightarrow{\alpha} N'$ and Lemma 8.6 we conclude that $\text{nec}(\alpha)$ is a proving sequence in $\mathcal{SN}(N)$.

**Inductive case.** Let $\sigma = \alpha \cdot \sigma'$. From $N \xrightarrow{\sigma} N'$ we get $N \xrightarrow{\alpha} N'' \xrightarrow{\sigma'} N'$ for some $N''$. Let $\text{nec}(\sigma) = v_1; \cdots; v_n$ and $\text{nec}(\sigma') = v'_1; \cdots; v'_{n'}$. By induction $\text{nec}(\sigma')$ is a proving sequence in $\mathcal{SN}(N'')$.

We show that $\text{nec}(\sigma)$ is a proving sequence in $\mathcal{SN}(N)$. By Lemma 8.4(1b) $\text{nec}(\sigma')$ is conflict free. By Lemma 8.4(3) $v_i = \alpha \uparrow v'_i$ for all $i, 2 \leq i \leq n$. This implies $v_i \in \mathcal{NE}(N)$ for all $i, 2 \leq i \leq n$ by Lemma 8.6(1) and $\neg(v_1 \# v_i)$ for all $i, j, 2 \leq i, j \leq n$ by Lemma 8.2(7). Finally, since $v_1 = \text{nec}(\alpha)$, by Lemma 8.4(2) we obtain $\neg(v_1 \# v_i)$ for all $i, 2 \leq i \leq n$. We conclude that $\text{nec}(\sigma)$ is conflict-free and included in $\mathcal{NE}(N)$.  

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Let \( v \in \mathcal{NE}(N) \) and \( v < v_k \) for some \( k, 1 \leq k \leq n \). This implies \( k > 1 \) since \( \text{nc}(\alpha) \) has no causes. Hence \( v_k = v \iff v_k \). By Lemma 5.5, we know that \( v = \text{nc}(\alpha) \) or \( v \# \text{nc}(\alpha) \) or \( \alpha \vdash v \) is defined. We consider the three cases. Let \( \text{part}(\alpha) = \{p, q\} \).

**Case** \( v = \text{nc}(\alpha) \). In this case we conclude immediately since \( \text{nc}(\alpha) = v_1 \) and \( 1 < k \).

**Case** \( v \neq \text{nc}(\alpha) \). Since \( \text{nc}(\alpha) = v_1 \), if \( v_1 < v_k \) we are done. If \( v_1 \neq v_k \), then \( \text{loc}(v_k) \cap \{p, q\} = \emptyset \) otherwise \( v_1 \neq v_k \). We get \( v_k = \alpha \vdash v_k = v \). Since \( v < v_k \), there exists \( r \vdash \eta \in v \) and \( r \vdash \eta' \in v = v_k \) such that \( \eta < \eta' \), where \( r \not\in \{p, q\} \) because \( r \in \text{loc}(v_k) \). Since \( \text{nc}(\alpha) \) is a proving sequence in \( S^N(N') \), by Lemma 5.2.3 there is \( v'' \in \mathcal{NE}(\mathcal{N}) \) such that \( r \vdash \eta \in v'' \). Since \( \alpha \vdash r \vdash \eta = r \vdash : \eta \in v_h \). This implies \( v_h < v_k \), where \( v_h \neq v \) by Proposition 5.20.

**Case** \( \alpha \vdash v \) defined. We get \( \alpha \vdash v < v' \) by Lemma 8.2.4. Since \( \text{nc}(\alpha') \) is a proving sequence in \( S^N(N') \), there is \( h < k \) such that either \( \alpha \vdash v = v' \) or \( \alpha \vdash v' < v' \). In the first case \( v = \alpha \vdash (\alpha \vdash v) = \alpha \vdash v' = v_h \) by Lemma 8.2.1. In the second case:

- from \( \alpha \vdash v < v' \) we get \( (\alpha \vdash (\alpha \vdash v)) < (\alpha \vdash v') \) by Lemma 8.2.5, which implies \( v \vdash v' \) by Lemma 8.2.1, and
- from \( v' < v_k \) we get \( (\alpha \vdash v') < (\alpha \vdash v') \) by Lemma 8.2.3, namely \( v_h < v_k \).

**Theorem 8.8.** If \( v_1, \ldots, v_n \) is a proving sequence in \( S^N(N) \), then \( N \rightarrow N' \), where \( \sigma = \text{cm}(v_1) \cdots \text{cm}(v_n) \).

**Proof** The proof is by induction on \( n \).

Case \( n = 1 \). Let \( v_1 = \{p \vdash \zeta \cdot \lambda, q \vdash \zeta' \cdot p?\lambda\} \). Then \( \text{cm}(v_1) = p!\lambda \). We first show that \( \zeta = \zeta' = \epsilon \). Assume ad absurdum that \( \zeta \neq \epsilon \) or \( \zeta' \neq \epsilon \). By narrowing, this implies that there is \( v \in \mathcal{NE}(N) \) such that \( v < v_1 \), contradicting the fact that \( v_1 \) is a proving sequence.

By Definition 5.13.1 we have \( N = p || P || q || Q || N_0 \) with \( p!\lambda \in \mathcal{PE}(P) \) and \( p?\lambda \in \mathcal{PE}(Q) \). Whence by Definition 4.3.1 we get \( P = \bigoplus_{i \in I} q!\lambda_i; P_i \) and \( Q = \bigoplus_{j \in J} p?\lambda_j; Q_j \) where \( \lambda = \lambda_k \) for some \( k \in I \cap J \). Therefore

\[
N \stackrel{pq}{\longrightarrow} p || P_k || q || Q_k || N_0
\]

Case \( n > 1 \). Let \( v_1 \) and \( N \) be as in the basic case, \( N' = p || P_k || q || Q_k || N_0 \) and \( \alpha = p!\lambda \). Since \( v_1, \ldots, v_n \) is a proving sequence, we have \( \neg(v_i \# v_j) \) for all \( i, j \) such that \( 1 \leq i, j \leq n \). Moreover, for all \( l, 2 \leq i, j \leq n \) we have \( v_i \neq v_1 = \text{nc}(\alpha) \), thus \( \alpha \vdash v_1 \) is defined by Lemma 8.5. Let \( v' = \alpha \vdash v_1 \) for all \( l, 2 \leq i, j \leq n \), then \( v' \in \mathcal{NE}(\mathcal{N}') \) by Lemma 8.6.2.

We show that \( v' \vdash \ldots \vdash v_n \) is a proving sequence in \( S^N(N') \). First notice that for all \( l, 2 \leq i, j \leq n \), \( \neg(v_i \# v_j) \) implies \( \neg(v_i' \# v_j') \) by Lemma 8.2.5 and (1). Let now \( v < v' \) for some \( h, 2 \leq h \leq n \). By Lemma 8.2.3 and (1) \( \alpha \vdash v < (\alpha \vdash v_h) = v_h \). This implies by Definition 5.6 that there is \( h' < h \) such that either \( \alpha \vdash v = v_{h'} \) or \( \alpha \vdash v < v_{h'} < v_h \). Therefore, since \( v' \) is defined for all \( l, 2 \leq i, j \leq n \), we get either \( v = v' \) by Lemma 8.2.2 or \( v \neq v' < v_h \) by Lemma 8.2.6 and (4).

By induction \( N' \rightarrow N' \rightarrow N' \rightarrow N' \rightarrow N' \) is the required transition sequence.
8.2. Relating Transition Sequences of Global Types and Proving Sequences of their ESs

In this subsection, we relate the traces that label the transition sequences of global types with the configurations of their PESs. As for n-events, we need retrieval and residual operators for g-events. The first operator was already introduced in Definition 7.6, so we only need to define the second, which is given next.

Definition 8.9 (Residual of g-events after communications).

1. The residual operator $\bullet$ applied to a communication and a g-event is defined by:

   $$
   \alpha \cdot [\sigma]_\sim = \begin{cases} 
   [\sigma']_\sim & \text{if } \sigma \sim \alpha \cdot \sigma' \text{ and } \sigma' \neq \epsilon \\
   [\sigma]_\sim & \text{if } \text{part}(\alpha) \cap \text{part}(\sigma) = \emptyset
   \end{cases}
   $$

2. The operator $\bullet$ naturally extends to nonempty traces:

   $$(\alpha \cdot \sigma) \bullet \gamma = \sigma \bullet (\alpha \bullet \gamma) \quad \sigma \neq \epsilon$$

The operator $\bullet$ gives the global event obtained by erasing the communication, if it occurs in head position (modulo $\sim$) in the event and leaves the event unchanged if the participants of the global event and of the communication are disjoint. Note that the operator $\alpha \bullet [\sigma]_\sim$ is undefined whenever either $[\sigma]_\sim = \{\alpha\}$ or one of the participants of $\alpha$ occurs in $\sigma$ but its first communication is different from $\alpha$.

The following lemma gives some simple properties of the retrieval and residual operators for g-events. The first five statements correspond to those of Lemma 8.2 for n-events. The last three statements give properties that are relevant only for the operators $\circ$ and $\bullet$.

Lemma 8.10 (Properties of retrieval and residual for g-events).

1. If $\alpha \bullet \gamma$ is defined, then $\alpha \circ (\alpha \bullet \gamma) = \gamma$;
2. $\alpha \bullet (\alpha \circ \gamma) = \gamma$;
3. If $\gamma_1 < \gamma_2$, then $\alpha \circ \gamma_1 < \alpha \circ \gamma_2$;
4. If $\gamma_1 < \gamma_2$ and both $\alpha \bullet \gamma_1$ and $\alpha \bullet \gamma_2$ are defined, then $\alpha \bullet \gamma_1 < \alpha \bullet \gamma_2$;
5. If $\gamma_1 \neq \gamma_2$, then $\alpha \circ \gamma_1 \neq \alpha \circ \gamma_2$;
6. If $\gamma < \alpha \circ \gamma'$, then either $\gamma = [\alpha]_\sim$ or $\alpha \bullet \gamma < \gamma'$;
7. If $\text{part}(\alpha_1) \cap \text{part}(\alpha_2) = \emptyset$, then $\alpha_1 \circ (\alpha_2 \circ \gamma) = \alpha_2 \circ (\alpha_1 \circ \gamma)$;
8. If $\text{part}(\alpha_1) \cap \text{part}(\alpha_2) = \emptyset$ and both $\alpha_2 \bullet (\alpha_1 \circ \gamma)$, $\alpha_2 \bullet \gamma$ are defined, then $\alpha_1 \circ (\alpha_2 \bullet \gamma) = \alpha_2 \bullet (\alpha_1 \circ \gamma)$.

The next lemma relates the retrieval and residual operator with the global types which are branches of choices.
Lemma 8.11. The following hold:

1. If \( \gamma \in \mathcal{GE}(G) \), then \( pq\lambda \circ \gamma \in \mathcal{GE}(p \rightarrow q : \bigoplus_{i \in I} \lambda_i; G_i) \), where \( \lambda = \lambda_k \) and \( G = G_k \) for some \( k \in I \).

2. If \( \gamma \in \mathcal{GE}(p \rightarrow q : \bigoplus_{i \in I} \lambda_i; G_i) \) and \( pq\lambda_k \circ \gamma \) is defined, then \( pq\lambda_k \circ \gamma \in \mathcal{GE}(G_k) \), where \( k \in I \).

Proof (1) By Definition 7.10(1) \( \gamma \in \mathcal{GE}(G) \) implies \( \gamma = \text{ev}(\sigma) \) for some \( \sigma \in \text{Tr}^+(G) \). Since \( pq\lambda \circ \gamma = \text{ev}(pq\lambda \circ \sigma) \) by Definition 7.6 and \( pq\lambda \circ \sigma \in \text{Tr}^+(p \rightarrow q : \bigoplus_{i \in I} \lambda_i; G_i) \) we conclude \( pq\lambda \circ \gamma \in \mathcal{GE}(p \rightarrow q : \bigoplus_{i \in I} \lambda_i; G_i) \) by Definition 7.10(1).

(2) By Definition 7.10(1) \( \gamma \in \mathcal{GE}(p \rightarrow q : \bigoplus_{i \in I} \lambda_i; G_i) \) implies \( \gamma = \text{ev}(\sigma) \) for some \( \sigma \in \text{Tr}^+(p \rightarrow q : \bigoplus_{i \in I} \lambda_i; G_i) \). We get \( \sigma = pq\lambda_h \circ \sigma' \) with \( \sigma' \in \text{Tr}^+(G_h) \) or \( \sigma' = \epsilon \) for some \( h \in I \). The hypothesis \( pq\lambda_h \circ \gamma \) defined implies either \( h = k \) and \( \sigma' \neq \epsilon \) or \( \text{part}(\sigma') \cap \{p,q\} = \emptyset \) and \( pq\lambda_k \circ \gamma = \text{ev}(\sigma') \) by Definition 8.9(1). In the first case \( \sigma' \in \text{Tr}^+(G_k) \). In the second case \( \sigma'' \in \text{Tr}^+(G_k) \) for some \( \sigma'' \sim \sigma' \) by definition of projection, which prescribes the same behaviours to all participants different from \( p,q \), see Figure 2. We conclude \( pq\lambda_k \circ \gamma \in \mathcal{GE}(G_k) \) by Definition 7.10(1).

The following lemma plays the role of Lemma 8.6 for n-events.

Lemma 8.12. Let \( G \xrightarrow{\alpha} G' \).

1. If \( \gamma \in \mathcal{GE}(G') \), then \( \alpha \circ \gamma \in \mathcal{GE}(G) \);

2. If \( \gamma \in \mathcal{GE}(G) \) and \( \alpha \circ \gamma \) is defined, then \( \alpha \circ \gamma \in \mathcal{GE}(G') \).

We show next that each trace gives rise to a sequence of g-events, compare with Definition 8.3

Definition 8.13 (Building sequences of g-events from traces). We define the sequence of global events corresponding to a trace \( \sigma \) by

\[
\text{gec}(\sigma) = \gamma_1; \cdots; \gamma_n
\]

where \( \gamma_i = \text{ev}(\sigma[1...i]) \) for all \( i, 1 \leq i \leq n \).

We show that \( \text{gec}(\cdot) \) has similar properties as \( \text{nec}(\cdot) \), see Lemma 8.4(1). The proof is straightforward.

Lemma 8.14. Let \( \text{gec}(\sigma) = \gamma_1; \cdots; \gamma_n \).

1. \( \text{cm}(\gamma_i) = \sigma[i] \) for all \( i, 1 \leq i \leq n \).

2. If \( 1 \leq h,k \leq n \), then \( \neg(\gamma_h \# \gamma_k) \).

We may now prove the correspondence between the traces labelling the transition sequences of a global type and the proving sequences of its PES. Let us stress the difference between the set of traces \( \text{Tr}^+(G) \) of a global type \( G \) as defined at page 18 and the set of traces that label the transition sequences of \( G \), which is a larger set due to the internal Rule [Icomm] of the LTS for global types given in Figure 4.
Theorem 8.15. If \( G \xrightarrow{\sigma} G' \), then \( \text{gec}(\sigma) \) is a proving sequence in \( S^G(G) \).

**Proof** By induction on \( \sigma \).

*Base case.* Let \( \sigma = \alpha \), then \( \text{gec}(\alpha) = \{\alpha\}_- \). We use a further induction on the inference of the transition \( G \xrightarrow{\sigma} G' \).

Let \( G = p \rightarrow q : \bigoplus_{i \in I} \lambda_i ; G_i, G' = G_h \) and \( \alpha = pq\lambda_i \) for some \( h \in I \). By Definition 7.10(1) \( \{pq\lambda_i\}_- \in \text{G}(G) \).

Let \( G = p \rightarrow q : \bigoplus_{i \in I} \lambda_i ; G_i \) and \( G' = p \rightarrow q : \bigoplus_{i \in I} \lambda_i ; G_i \xrightarrow{\sigma} G'_i \) for all \( i \in I \) and \( \text{part}(\alpha) \cap \{p, q\} = \emptyset \). By induction \( \{\alpha\}_- \in \text{G}(G_i) \) for all \( i \in I \). By Lemma 8.11(1) \( \text{part}(\alpha) \cap \{p, q\} = \emptyset \). We conclude \( \{\alpha\}_- \in \text{G}(G) \).

*Inductive case.* Let \( \sigma = \alpha \cdot \sigma' \) with \( \sigma' \neq e \). From \( G \xrightarrow{\sigma} G' \) we get \( G \xrightarrow{\alpha} G_0 \xrightarrow{\sigma'} G' \) for some \( G_0 \). Let \( \text{gec}(\sigma) = \gamma_1 ; \cdots ; \gamma_n \) and \( \text{gec}(\sigma') = \gamma'_1 ; \cdots ; \gamma'_n \). By induction \( \text{gec}(\sigma') \) is a proving sequence in \( S^G(G_0) \). By Definitions 8.13 and 7.6 \( \gamma_i = \alpha \circ \gamma'_i \), which implies \( \alpha \cdot \gamma_i = \gamma'_i \) by Lemma 8.10(2) for all \( i, 2 \leq i \leq n \).

We can show that \( \gamma_1 = \{\alpha\}_- \in \text{G}(G) \) as in the proof of the base case. By Lemma 8.12(1) \( \gamma_1 \in \text{G}(G) \) since \( \gamma'_1 \in \text{G}(G_0) \) and \( \alpha \cdot \gamma_i = \gamma'_i \) for all \( i, 2 \leq i \leq n \).

We prove that \( \text{gec}(\sigma) \) is a proving sequence in \( S^G(G) \). Let \( \gamma < \gamma_1 \) for some \( k, 1 \leq k \leq n \). Note that this implies \( \gamma > 1 \). Since \( \gamma_1 = \alpha \circ \gamma'_1 \) by Lemma 8.10(6) either \( \gamma = \{\alpha\}_- \) or \( \alpha \cdot \gamma = \gamma'_1 \). If \( \gamma = \{\alpha\}_- \) we are done. Otherwise \( \alpha \cdot \gamma = \text{G}(G_0) \) by Lemma 8.11(2). Since \( \text{gec}(\sigma') \) is a proving sequence in \( S^G(G_0) \), there is \( h < k \) such that \( \alpha \cdot \gamma = \gamma'_h \) and this implies \( \gamma = \alpha \circ (\alpha \cdot \gamma) = \alpha \circ \gamma'_h = \gamma'_h \) by Lemma 8.10(1).

Theorem 8.16. If \( \gamma_1 ; \cdots ; \gamma_n \) is a proving sequence in \( S^G(G) \), then \( G \xrightarrow{\sigma} G' \), where \( \sigma = \text{cm}(\gamma_1) \cdot \cdots \cdot \text{cm}(\gamma_n) \).

**Proof** The proof is by induction on the length \( n \) of the proving sequence. Let \( \text{cm}(\gamma_1) = \alpha \) and \( \{p, q\} = \text{part}(\alpha) \).

*Case* \( n = 1 \). Since \( \gamma_1 \) is the first event of a proving sequence, we have \( \gamma_1 = \{\alpha\}_- \). We show this case by induction on \( d = \text{depth}(G, p) = \text{depth}(G, q) \).

*Case* \( d = 1 \). Let \( \alpha = pq\lambda_i \) and \( G = p \rightarrow q : \bigoplus_{i \in I} \lambda_i ; G_i \) and \( \lambda = \lambda_i \) for some \( h \in I \). Then \( G \xrightarrow{\alpha} G_h \) by rule [Ecomm].

*Case* \( d > 1 \). Let \( G = r \rightarrow s : \bigoplus_{i \in I} \lambda_i ; G_i \) and \( \{r, s\} \cap \{p, q\} = \emptyset \). By Definition 8.9(1) \( rs\lambda_i \cdot \gamma_1 \) is defined for all \( i \in I \) since \( \{r, s\} \cap \{p, q\} = \emptyset \). This implies \( rs\lambda_i \cdot \gamma_1 \in \text{G}(G_i) \) for all \( i \in I \) by Lemma 8.11(2). By induction hypothesis \( G_i \xrightarrow{\sigma_i} G'_i \) for all \( i \in I \). Then we can apply rule [Ecomm] to derive \( G \xrightarrow{\sigma} r \rightarrow s : \bigoplus_{i \in I} \lambda_i ; G'_i \).

*Case* \( n > 1 \). Let \( G \xrightarrow{\sigma} G' \) be the transition as obtained from the base case. We show that \( \alpha \cdot \gamma_j \) is defined for all \( j, 2 \leq j \leq n \). If \( \alpha \cdot \gamma_k \) were undefined for some \( k, 2 \leq k \leq n \), then by Definition 8.9(1) either \( \gamma_k = \gamma_1 \) or \( \gamma_k = \{\sigma\}_- \). with \( \sigma = \alpha \cdot \sigma' \) and \( \text{part}(\alpha) \cap \text{part}(\sigma) \neq \emptyset \). In the second case \( \alpha \circ p @ \sigma @ p \) or \( \alpha @ q # \sigma @ q \), which implies \( \gamma_k \neq \gamma_1 \). So both cases are impossible. If \( \alpha \cdot \gamma_j \) is defined, by Lemma 8.12(2) we get \( \alpha \cdot \gamma_j \in \text{G}(G') \) for all \( j, 2 \leq j \leq n \).

We show that \( \gamma'_2 ; \cdots ; \gamma'_n \) is a proving sequence in \( S^G(G') \) where \( \gamma'_j = \alpha \cdot \gamma_j \) for all \( j, 2 \leq j \leq n \). By Lemma 8.11(1) \( \gamma_j = \alpha \circ \gamma'_j \) for all \( j, 2 \leq j \leq n \). Then by Lemma 8.10(5) no two events in the sequence \( \gamma'_2 ; \cdots ; \gamma'_n \) can be in conflict. Let \( \gamma \in \text{G}(G') \) and
\( \gamma < \gamma'_h \) for some \( h, 2 \leq h \leq n \). By Lemma 8.12(1) \( \alpha \circ \gamma \) and \( \alpha \circ \gamma'_h \) belong to \( \mathcal{G}(G) \). By Lemma 8.10(3) \( \alpha \circ \gamma < \alpha \circ \gamma'_h \). By Lemma 8.11(1) \( \alpha \circ \gamma'_h = \gamma_h \). Let \( \gamma' = \alpha \circ \gamma \). Then \( \gamma' < \gamma_h \) implies, by Definition 3.6 and the fact that \( \mathcal{S}(\mathcal{G}(G)) \) is a PES, that there is \( k < h \) such that \( \gamma' = \gamma_k \). By Lemma 8.11 we get \( \gamma = \alpha \circ \gamma' = \alpha \circ \gamma_k = \gamma'_k \).

Since \( \gamma'_2; \ldots; \gamma'_n \) is a proving sequence in \( \mathcal{S}(\mathcal{G}(G')) \), by induction \( G'' \overset{\alpha}{\rightarrow} G' \) where \( \sigma' = \text{cm}(\gamma'_2) \cdot \ldots \cdot \text{cm}(\gamma'_n) \). Let \( \sigma = \text{cm}(\gamma_1) \cdot \ldots \cdot \text{cm}(\gamma_j) \). Since \( \text{cm}(\gamma'_j) = \text{cm}(\gamma_j) \) for all \( j, 2 \leq j \leq n \), we have \( \sigma = \alpha \cdot \sigma' \). Hence \( G \overset{\alpha}{\rightarrow} G'' \overset{\alpha}{\rightarrow} G' \) is the required transition sequence.

The last ingredient required to prove our main theorem is the following separation result from [9] (Lemma 2.8 p. 12):

**Lemma 8.17 (Separation [9]).** Let \( S = (E, \prec, \#) \) be a flow event structure and \( X, X' \subseteq C(S) \) be such that \( X \subseteq X' \). Then there exist \( e \in X' \setminus X \) such that \( X \cup \{e\} \subseteq C(S) \).

We may now finally show the correspondence between the configurations of the FES of a network and the configurations of the PES of its global type. Let \( \simeq \) denote isomorphism on domains of configurations.

**Theorem 8.18 (Isomorphism).** If \( \vdash N : G \), then \( \mathcal{D}(S(N)) \simeq \mathcal{D}(\mathcal{G}(G)) \).

**Proof** By Theorem 8.8 if \( v_1; \ldots; v_n \) is a proving sequence of \( S(N) \), then \( N \overset{\sigma}{\rightarrow} N' \) where \( \sigma = \text{cm}(v_1) \cdot \ldots \cdot \text{cm}(v_n) \). By applying iteratively Subject Reduction (Theorem 6.13) \( G \overset{\sigma}{\rightarrow} G' \) and \( \vdash N' : G' \). By Theorem 8.15 \( \text{gec}(\sigma) \) is a proving sequence of \( \mathcal{S}(\mathcal{G}(G)) \).

By Theorem 8.16 if \( \gamma_1; \ldots; \gamma_n \) is a proving sequence of \( \mathcal{S}(\mathcal{G}(G)) \), then \( G \overset{\gamma}{\rightarrow} G' \) where \( \gamma = \text{cm}(\gamma_1) \cdot \ldots \cdot \text{cm}(\gamma_n) \). By applying iteratively Session Fidelity (Theorem 6.14) \( N \overset{\gamma}{\rightarrow} N' \) and \( \vdash N' : G' \). By Theorem 8.7 \( \text{nec}(\gamma) \) is a proving sequence of \( S(N) \).

We show now that this bijection preserves inclusion of configurations. By Lemma 8.17 it is enough to prove that if \( v_1; \ldots; v_n \in C(S(N)) \) is mapped to \( \gamma_1; \ldots; \gamma_n \in C(S(\mathcal{G}(G))) \), then \( v_1; \ldots; v_n; v \in C(S(N)) \) iff \( \gamma_1; \ldots; \gamma_n; \gamma \in C(S(\mathcal{G}(G))) \), where \( \gamma_1; \ldots; \gamma_n; \gamma \) is the image of \( v_1; \ldots; v_n; v \) under the bijection. I.e. let \( \text{nec}(\gamma) \cdot \alpha = v_1; \ldots; v_n; v \) and \( \text{gec}(\sigma \cdot \alpha) = \gamma_1; \ldots; \gamma_n; \gamma \). This implies \( \sigma = \text{cm}(v_1) \cdot \ldots \cdot \text{cm}(v_n) = \text{cm}(\gamma_1) \cdot \ldots \cdot \text{cm}(\gamma_n) \) and \( \alpha = \text{cm}(v) = \text{cm}(\gamma) \) by Lemmas 8.4 and 8.14.

By Theorem 8.8 if \( v_1; \ldots; v_n; v \) is a proving sequence of \( S(N) \), then \( N \overset{\sigma}{\rightarrow} N_0 \overset{\alpha}{\rightarrow} N' \). By applying iteratively Subject Reduction (Theorem 6.13) \( G \overset{\sigma}{\rightarrow} G_0 \overset{\alpha}{\rightarrow} G' \) and \( \vdash N' : G' \). By Theorem 8.15 \( \text{gec}(\sigma \cdot \alpha) \) is a proving sequence of \( \mathcal{S}(\mathcal{G}(G)) \).

By Theorem 8.16 if \( \gamma_1; \ldots; \gamma_n; \gamma \) is a proving sequence of \( \mathcal{S}(\mathcal{G}(G)) \), then \( G \overset{\gamma}{\rightarrow} G_0 \overset{\gamma}{\rightarrow} G' \). By applying iteratively Session Fidelity (Theorem 6.14) \( N \overset{\gamma}{\rightarrow} N_0 \overset{\gamma}{\rightarrow} N' \) and \( \vdash N' : G' \). By Theorem 8.7 \( \text{nec}(\gamma) \) is a proving sequence of \( S(N) \).
9. Related Work and Conclusions

Event Structures (ESs) were introduced in Winskel’s PhD Thesis [59] and in the seminal paper by Nielsen, Plotkin and Winskel [48], roughly in the same frame of time as Milner’s calculus CCS [46]. It is therefore not surprising that the relationship between these two approaches for modelling concurrent computations started to be investigated very soon afterwards. The first interpretation of CCS into ESs was proposed by Winskel in [61]. This interpretation made use of Stable ESs, because PESs, the simplest form of ESs, appeared not to be flexible enough to account for CCS parallel composition. Indeed, since CCS parallel composition allows for two concurrent complementary actions to either synchronise or occur independently in any order, each pair of such actions gives rise to two forking computations: this requires duplication of the same continuation process for these forking computations in PESs, while the continuation process may be shared by the forking computations in Stable ESs, which allow for disjunctive causality. Subsequently, ESs (as well as other nonsequential “denotational models” for concurrency such as Petri Nets) have been used as the touchstone for assessing noninterleaving operational semantics for CCS: for instance, the pomset semantics for CCS by Boudol and Castellani [7, 8] and the semantics based on “concurrent histories” proposed by Degano, De Nicola and Montanari [29, 27, 28], were both shown to agree with an interpretation of CCS processes into some class of ESs (PESs for [27, 28], PESs with non-hereditary conflict for [7], and FESs for [8]). Among the early interpretations of process calculi into ESs, we should also mention the PES semantics for TCSP (Theoretical CSP [11, 49]), proposed by Goltz and Loogen [45] and later generalised by Baier and Majster-Cederbaum [2], and the Bundle ES semantics for LOTOS, proposed by Langerak [44] and extended by Katoen [42]. Like FESs, Bundle ESs are a subclass of Stable ESs. We recall the relationships between the above classes of ESs (the reader is referred to [10] for separating examples):

Prime ESs \subset Bundle ESs \subset Flow ESs \subset Stable ESs \subset General ESs

More sophisticated ES semantics for CCS, based on FESs and designed to be robust under action refinement [1, 26, 33], were subsequently proposed by Goltz and van Glabbeek [56]. Importantly, all the above-mentioned classes of ESs, except General ESs, give rise to the same prime algebraic domains of configurations, from which one can recover a PES by selecting the complete prime elements.

More recently, ES semantics have been investigated for the \( \pi \)-calculus by Crafa, Varacca and Yoshida [21, 57, 22] and by Cristescu, Krivine and Varacca [23, 24, 25]. Previously, other causal models for the \( \pi \)-calculus had already been put forward by Jategaonkar and Jagadeesan [41], by Montanari and Pistore [47], by Cattani and Sewell [18] and by Bruni, Melgratti and Montanari [12]. The main new issue, when addressing causality-based semantics for the \( \pi \)-calculus, is the implicit causality induced by scope extrusion. Two alternative views of such implicit causality had been proposed in early work on noninterleaving operational semantics for the \( \pi \)-calculus, respectively by Boreale and Sangiorgi [6] and by Degano and Priami [30]. Essentially, in [6] an extruder (that is, an output of a private name) is considered to cause any action that uses the extruded name, whether in subject or object position,
while in [30] it is considered to cause only the actions that use the extruded name in subject position. Thus, for instance, in the process $P = va(\overline{b(a)} | \overline{c(a)} | a)$, the two parallel extruders are considered to be causally dependent in the former approach, and independent in the latter. All the causal models for the π-calculus mentioned above, including the ES-based ones, take one or the other of these two stands. Note that opting for the second one leads necessarily to a non-stable ES model, where there may be causal ambiguity within the configurations themselves: for instance, in the above example the maximal configuration contains three events, the extruders $\overline{b(a)}$, $\overline{c(a)}$ and the input on $a$, and one does not know which of the two extruders enabled the input. Indeed, the paper [22] uses non-stable ESs. The use of non-stable ESs (General ESs) to express situations where a computational step can merge parts of the state is advocated for instance by Baldan, Corradini and Gadducci in [3]. These ESs give rise to configuration domains that are not prime algebraic, hence the classical representation theorems have to be adjusted.

In our simple setting, where we deal only with single sessions and do not consider session interleaving nor delegation, we can dispense with channels altogether, and therefore the question of parallel extrusion does not arise. In this sense, our notion of causality is closer to that of CCS than to the more complex one of the π-calculus. However, even in a more general setting, where participants would be paired with the channel name of the session they pertain to, the issue of parallel extrusion would not arise: indeed, in the above example $b$ and $c$ should be equal, because participants can only delegate their own channel, but then they could not be in parallel because of linearity, one of the distinguishing features enforced by session types. Hence we believe that in a session-based framework the two above views of implicit causality should collapse into just one.

We now briefly discuss our design choices.

- The calculus considered in the present paper uses synchronous communication - rather than asynchronous, buffered communication - because this is how communication is classically modelled in ESs, when they are used to give semantics to process calculi. We should mention however that after first proposing the present study in [15], we also considered a calculus with asynchronous communication in the companion paper [16]. In that work too, networks are interpreted as FESs, and their associated global types, which we called asynchronous types as they split communications into outputs and inputs, are interpreted as PESs. The key result is again an isomorphism between the configuration domain of the FES of a typed network and that of the PES of its type.

- Concerning the choice operator, we adopted here the basic (and most restrictive) variant for it, as it was originally proposed for multiparty session calculi in [38]. This is essentially a simplifying assumption, and we do not foresee any difficulty in extending our results to a more general choice operator, where the projection is rendered more flexible through the use of a merge operator [31].

- As regards the preorder on processes, which is akin to a subtyping relation, we envisaged to use the standard subtyping, in which a process with fewer
outputs can be used in place of a process with more outputs. However, in that case Session Fidelity would become weaker, since a transition in the LTS of a global type would only ensure a transition in the LTS of the corresponding network, but not necessarily with the same labelling communication. The main drawback would be that Theorem 8.18 would no longer hold: more precisely, the domains of network configurations would only be embedded in (and not isomorphic to) the domains of their global type configurations. Notably, typability is independent from the use of our preorder or of the standard one, as proved in [4].

As regards future work, we plan to define an asynchronous transition system (ATS) [3] for our calculus, along the lines of [10], and show that it provides a noninterleaving operational semantics for networks that is equivalent to their FES semantics. This would enable us also to investigate the issue of reversibility, jointly on our networks and on their FES representations, since the ATS semantics would give us the handle to unwind networks, while the corresponding FESs could be unrolled following one of the methods proposed in existing work on reversible event structures [52, 25, 35, 36, 34].

As mentioned at the end of Section 7, the quest for a semantic counterpart of our well-formedness conditions on global types – namely, for properties that characterise the FESs obtained from typable networks – is still open. By way of comparison, such semantic well-formedness conditions have been proposed in [55] for graphical choreographies, a truly concurrent graphical model for global specifications with two kinds of forking nodes, representing respectively choice and parallel composition. In [55], those well-formedness conditions, called well-sequencing and well-branchedness, were shown to be sufficient to ensure projectability on local specifications. In our case, the property corresponding to well-sequencing is automatically ensured by our ES semantics, and we conjecture that the well-branchedness condition for choice nodes (corresponding to projectability) could amount in our simpler setting to the following semantic condition:

Let \( v_1, v_2 \in \mathcal{NE}(N) \) and \( p :: \zeta \cdot \pi \in v_1 \) and \( p :: \zeta \cdot \pi' \in v_2 \) with \( \pi \neq \pi' \) and \( q = pt(\pi) = pt(\pi') \) If \( v_1 \prec v'_1 \) for some \( v'_1 \in \mathcal{NE}(N) \) such that \( r \in \text{loc}(v'_1) \) with \( r \notin \{p, q\} \), then \( v_2 \prec v'_2 \) for some \( v'_2 \in \mathcal{NE}(N) \) such that \( r \in \text{loc}(v'_2) \).

This condition would allow us to rule out the FESs of both networks \( N' \) and \( N'' \) discussed at page 29. However, it should be completed with a condition corresponding to boundedness, and the conjunction of these two conditions might still not be sufficient in general to ensure typability. We plan to further investigate this question in the near future.

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Appendix A.

This Appendix contains the proofs of Lemmas 6.6, 6.9, 8.2, 8.6, 8.10, and 8.12.

**Lemma 6.6** If $G$ is bounded, then $G \upharpoonright r$ is a partial function for all $r$.

**Proof** We redefine the projection $\downarrow r$ as the largest relation between global types and processes such that $(G, P) \in \downarrow r$ implies:

i) if $r \not\in \text{part}(G)$, then $P = 0$;

ii) if $G = r \rightarrow p : \bigoplus_{i \in I} \lambda_i ; G_i$, then $P = \bigoplus_{i \in I} q \lambda_i ; P_i$ and $(G_i, P_i) \in \downarrow r$ for all $i \in I$;

iii) if $G = p \rightarrow r : \bigoplus_{i \in I} \lambda_i ; G_i$, then $P = \bigoplus_{i \in I} p \lambda_i ; P_i$ and $(G_i, P_i) \in \downarrow r$ for all $i \in I$;

iv) if $G = p \rightarrow q : \bigoplus_{i \in I} \lambda_i ; G_i$ and $r \not\in \{p, q\}$ and $r \in \text{part}(G_i)$, then $(G_i, P) \in \downarrow r$ for all $i \in I$.

The equality $E$ of processes is the largest symmetric binary relation $R$ on processes such that $(P, Q) \in R$ implies:

(a) if $P = \bigoplus_{i \in I} p \lambda_i ; P_i$, then $Q = \bigoplus_{i \in I} p \lambda_i ; Q_i$ and $(P_i, Q_i) \in R$ for all $i \in I$;

(b) if $P = \bigoplus_{i \in I} p \lambda_i ; P_i$, then $Q = \bigoplus_{i \in I} p \lambda_i ; Q_i$ and $(P_i, Q_i) \in R$ for all $i \in I$.

It is then enough to show that the relation $R_r = \{(P, Q) \mid \exists G. (G, P) \in \downarrow r \text{ and } (G, Q) \in \downarrow r \}$ satisfies Clauses [a] and [b] (with $R$ replaced by $R_r$), since this will imply $R_r \subseteq E$. Note first that $(0, 0) \in R_r$ because $(\text{End}, 0) \in \downarrow r$, and that $(0, 0) \in E$ because Clauses [a] and [b] are vacuously satisfied by the pair $(0, 0)$. The proof is by induction on $d = \text{depth}(G, r)$. We only consider Clause [b]; the proof for Clause [a] being similar. So, assume $(P, Q) \in R_r$ and $P = \bigoplus_{i \in I} p \lambda_i ; P_i$.

Case $d = 1$. In this case $G = p \rightarrow r : \bigoplus_{i \in I} \lambda_i ; G_i$ and $P = \bigoplus_{i \in I} p \lambda_i ; P_i$ and $(G_i, P_i) \in \downarrow r$ for all $i \in I$. From $(G, Q) \in \downarrow r$, we get $Q = \bigoplus_{i \in I} p \lambda_i ; Q_i$ and $(G_i, Q_i) \in \downarrow r$ for all $i \in I$. Hence $Q$ has the required form and $(P_i, Q_i) \in R_r$ for all $i \in I$.

Case $d > 1$. In this case $G = p \rightarrow q : \bigoplus_{i \in I} \lambda_i^j ; G_i$ and $r \not\in \{p, q\}$ and $(G_i, P_i) \in \downarrow r$ for all $j \in J$. From $(G, Q) \in \downarrow r$, we get $(G_j, Q) \in \downarrow r$ for all $j \in J$. Then $(P, Q) \in R_r$.

**Lemma 6.9** Let $G$ be a well-formed global type.

1. If $G \upharpoonright p = \bigoplus_{i \in I} q \lambda_i ; P_i$ and $G \upharpoonright q = \bigoplus_{j \in J} p \lambda_j ; Q_j$, then $I = J$, $\lambda_i = \lambda_j^i$, $G \xrightarrow{pq\lambda_i} G_i$, $G_i \upharpoonright p = P_i$, and $G_i \upharpoonright q = Q_i$ for all $i \in I$.

2. If $G \xrightarrow{pq\lambda_i} G'$, then $G \upharpoonright p = \bigoplus_{i \in I} q \lambda_i ; P_i$, $G \upharpoonright q = \bigoplus_{i \in I} p \lambda_i ; Q_i$, where $\lambda_i = \lambda$ for some $i \in I$, and $G' \upharpoonright r = G \upharpoonright r$ for all $r \not\in \{p, q\}$.

**Proof** (1). The proof is by induction on $d = \text{depth}(G, p)$.

If $d = 1$, then by definition of projection (see Figure 2), $G \upharpoonright p = \bigoplus_{i \in I} q \lambda_i ; P_i$ implies $G = p \rightarrow q : \bigoplus_{i \in I} \lambda_i ; G_i$ with $G_i \upharpoonright p = P_i$. By the same definition it follows that $J = I$ and $\lambda_j^i = \lambda_j$ and $Q_j = G_j \upharpoonright q$ for all $j \in J$. Moreover $G \xrightarrow{pq\lambda_i} G_i$ by Rule [Ecomm] for
all i ∈ I.

If d > 1, then G = r → s : \( \bigoplus_{h \in H} \lambda_h' \) with \( (p, q) \cap (r, s) = \emptyset \). By definition of projection \( G \upharpoonright p = G_h' \upharpoonright p \) and \( G \upharpoonright q = G_h' \upharpoonright q \) for all \( h \in H \). By Proposition \( \text{depth}(G, p) > \text{depth}(G_h', p) \) for all \( h \in H \). Then by induction \( I = J \),

\( \lambda_i = \lambda_i' \), \( G_h' \upharpoonright p = P_i \) and \( G_h' \upharpoonright q = Q_i \) for all \( i \in I \) and all \( h \in H \).

Let \( G_i = r → s : \bigoplus_{h \in H} \lambda_i' \) with \( \lambda_i = \lambda_i' \). By Rule \([\text{ICOMM}]\) \( G \upharpoonright p = G_i \) for all \( i \in I \). By definition of projection \( G_i \upharpoonright p = P_i \) and \( G_i \upharpoonright q = Q_i \) for all \( i \in I \).

(2) The proof is by induction on the transition rules of Figure 4.

The interesting case is:

\[ \text{ICOMM} \quad s \rightarrow t : \bigoplus_{h \in H} \lambda_h' \quad G_h' \upharpoonright p = \bigoplus_{h \in H} \lambda_h' \quad G_h' \upharpoonright q \]

with \( G = s \rightarrow t : \bigoplus_{h \in H} \lambda_h' \quad G_h' \) and \( G' = s \rightarrow t : \bigoplus_{h \in H} \lambda_h' \quad G_h' \). By induction \( G \upharpoonright p = \bigoplus_{i \in I} q! \lambda_i; P_i \) and \( G \upharpoonright q = \sum_{i \in I} p? \lambda_i; Q_i \), \( \lambda = \lambda_i \) for some \( i \in I \) and \( G \upharpoonright r = G_h \upharpoonright r \) for all \( r \notin (p, q) \) and all \( h \in H \). By definition of projection \( G \upharpoonright p = G_h \upharpoonright p \) and \( G \upharpoonright q = G_h \upharpoonright q \) for all \( h \in H \). For \( r \notin (p, q) \) we get \( G \upharpoonright r = G_h \upharpoonright r = G_h \upharpoonright r = G \upharpoonright r \).

Moreover \( G' \upharpoonright s = \bigoplus_{i \in I} q! \lambda_i; G_h' \upharpoonright s = \bigoplus_{i \in I} p? \lambda_i; G_h' \upharpoonright s = G \upharpoonright s \) and \( G' \upharpoonright t = \sum_{i \in I} \lambda_i; G_h' \upharpoonright t = G \upharpoonright t \).

Lemma 8.2 1. If \( \alpha \uplus \nu \) is defined, then \( \alpha \uplus (\alpha \uplus \nu) = \nu \);

2. \( \alpha \uplus (\alpha \uplus \nu) = \nu \);

3. If \( \nu < \nu' \), then \( \alpha \uplus \nu < \alpha \uplus \nu' \);

4. If \( \nu < \nu' \) and both \( \alpha \uplus \nu \) and \( \alpha \uplus \nu' \) are defined, then \( \alpha \uplus \nu < \alpha \uplus \nu' \);

5. If \( \nu \neq \nu' \), then \( \alpha \uplus \nu \neq \alpha \uplus \nu' \);

6. If \( \nu \neq \nu' \) and both \( \alpha \uplus \nu \) and \( \alpha \uplus \nu' \) are defined, then \( \alpha \uplus \nu \neq \alpha \uplus \nu' \);

7. If \( \alpha \uplus \nu \neq \alpha \uplus \nu' \), then \( \nu \neq \nu' \).

Proof For (1) and (2) it is enough to show the corresponding properties for located events.

(1) Since \( \alpha \uplus (p :: \eta) \) is defined, we have \( \eta = (\alpha \uplus p) \cdot \eta' \) and \( \alpha \uplus (p :: \eta) = p :: \eta' \) for some \( \eta' \). Then \( \alpha \uplus (\alpha \uplus (p :: \eta)) = \alpha \uplus (p :: \eta') = p :: (\alpha \uplus p) \cdot \eta' = p :: \eta \).

(2) Since \( \alpha \uplus (p :: \eta) = p :: (\alpha \uplus p) \cdot \eta \) is always defined, we immediately get \( \alpha \uplus (\alpha \uplus (p :: \eta)) = \alpha \uplus (p :: (\alpha \uplus p) \cdot \eta) = p :: \eta \).

(3) Let \( \nu < \nu' \). By Definition 5.7, there are \( p :: \eta \in \nu \) and \( p :: \eta' \in \nu' \) such that \( \eta < \eta' \). Then \( \alpha \uplus (p :: \eta) = p :: (\alpha \uplus p) \cdot \eta \in \alpha \uplus \nu \) and \( \alpha \uplus (p :: \eta') = p :: (\alpha \uplus p) \cdot \eta' \in \alpha \uplus \nu' \). Since \( \eta < \eta' \) implies \( \alpha \uplus (p :: \eta) < \alpha \uplus (p :: \eta') \), we conclude that \( \alpha \uplus \nu < \alpha \uplus \nu' \).

(4) As in the previous case, there are \( p :: \eta \in \nu \) and \( p :: \eta' \in \nu' \) such that \( \eta < \eta' \). Since both \( \alpha \uplus \nu \) and \( \alpha \uplus \nu' \) are defined, there exist \( \eta_0 \) and \( \eta'_0 \) such that \( \eta = (\alpha \uplus p) \cdot \eta_0 \) and \( \eta' = (\alpha \uplus p) \cdot \eta'_0 \) and \( \alpha \uplus (p :: \eta) = p :: \eta_0 \) and \( \alpha \uplus (p :: \eta') = p :: \eta'_0 \). Since \( \eta < \eta' \) implies \( \eta_0 < \eta'_0 \), we conclude that \( \alpha \uplus \nu < \alpha \uplus \nu' \).

(5) Let \( \nu \neq \nu' \). If Clause (2a) of Definition 5.7 applies, then there are \( p :: \eta \in \nu \) and \( p :: \eta' \in \nu' \) such that \( \eta \neq \eta' \). From \( \alpha \uplus (p :: \eta) = p :: (\alpha \uplus p) \cdot \eta \) and \( \alpha \uplus (p :: \eta') = p :: (\alpha \uplus p) \cdot \eta' \), we conclude that \( \alpha \uplus \nu \neq \alpha \uplus \nu' \).
By Definition 5.13(1) and prove that Clause (2b) of Definition 5.7 applies, then there are $p \vdash \alpha$ defined.

The proof is similar to that of Point (5), considering that $\alpha \vdash \nu$ and $\alpha \vdash \nu'$ are defined.

Let $\alpha \vdash \nu \neq \alpha \vdash \nu'$. If Clause (2a) of Definition 5.7 applies, then there are $p \vdash \eta \in \nu$ and $p \vdash \eta' \in \nu'$ such that $(\alpha \vdash p) \cdot \eta \# (\alpha \vdash p) \cdot \eta'$. Therefore $\eta \neq \eta'$ and thus $\nu \neq \nu'$. If Clause (2b) of Definition 5.7 applies, then there are $\eta_0 = \alpha \vdash (p \vdash \eta)$ in $\alpha \vdash \nu$ and $q \vdash \eta_0' = \alpha \vdash (q \vdash \eta')$ in $\alpha \vdash \nu'$ with $p \neq q$ such that $|\eta_0 \cup q| = |\eta_0' \cup p|$ and $-(\eta_0 \cup q \models \eta_0' \cup p)$. Let $\eta_0 = (\alpha \vdash p) \cdot \eta$ and $\eta_0' = (\alpha \vdash q) \cdot \eta'$ and $p \vdash \eta \in \nu$ and $q \vdash \eta' \in \nu'$. If part$(\alpha) \neq [p, q]$, then $(\alpha \vdash p) \vdash \eta = \epsilon = (\alpha \vdash q)$ \vdash \eta$ and thus $\eta \models q = \eta_0 \cup q$ and $\eta' \models p = \eta_0' \cup p$. If part$(\alpha) = [p, q]$, say $\alpha = pq\lambda$, then $\eta_0 = q!\lambda \cdot \eta$ and $\eta_0' = q!\lambda \cdot \eta'$, and thus $|\eta \cup q| = |\eta_0 \cup q| - 1 = |\eta_0' \cup p| - 1 = |\eta' \cup p|$ and $-(\eta \cup q \models \eta_0' \cup p)$. In both cases we conclude that $\alpha \vdash \nu \neq \alpha \vdash \nu'$.

Lemma 8.6 Let $N \vdash N'$. Then

1. $|\text{neq}(\alpha)| \cup [\alpha \vdash \nu \mid \nu \in \text{NE}(N')] \subseteq \text{NE}(N)$;

2. $[\alpha \vdash \nu \mid \nu \in \text{NE}(N)] \cup [\alpha \vdash \nu \mid \nu \in \text{NE}(N')] \subseteq \text{NE}(N')$.

Proof Let $\alpha = pq\lambda$. From $N \vdash N'$ we get

$$N = p\ll \bigoplus_{i \in I} q!\lambda_i; P \| q! \Sigma_{j \in J} p?\lambda_i; Q_j \| N_0$$

where for some $k \in (I \cap J)$ we have $\lambda_k = \lambda$ and

$$N' = p\ll P_k \| q! \ll Q_k \| N_0$$

(1) Let $RT = |\text{neq}(\alpha)| \cup [\alpha \vdash \nu \mid \nu \in \text{NE}(N')]$. We first show that $RT \subseteq \text{DE}(N)$. By Definition 5.13(1) $\text{neq}(\alpha) \in \text{DE}(N)$. Let $\nu = [r \vdash \eta, s \vdash \eta'] \in \text{NE}(N')$. We want to prove that $\alpha \vdash \nu \in \text{DE}(N)$. By Definition 5.13(1) there are $R, S$ such that $r\ll R \pp N'$ and $s\ll S \pp N'$ and $\eta \in \text{PE}(R)$ and $\eta' \in \text{PE}(S)$. There are two possible cases:

- $[r, s] \cap [p, q] = \emptyset$. Then $r\ll R \pp N$ and $s\ll S \pp N$ and thus $\alpha \vdash \nu = \nu \in \text{DE}(N)$;

- $[r, s] \cap [p, q] \neq \emptyset$. Suppose $r = p$. Then $\eta \in \text{PE}(P_k)$ and $p \vdash q!\lambda_k \cdot \eta \in \alpha \vdash \nu$ and $q!\lambda_k \cdot \eta \in \text{PE}(\bigoplus_{i \in I} q!\lambda_i; P_i)$. There are two subcases:

  - $s = q$. Then $\eta' \in \text{PE}(Q_k)$ and $q \vdash p?\lambda_k \cdot \eta' \in \alpha \vdash \nu$ and $q!\lambda_k \cdot \eta' \in \text{PE}(\bigoplus_{i \in J} p?\lambda_i; Q_j)$. In this case we have $\alpha \vdash \nu = \pil p\vdash q!\lambda_k \cdot \eta, q \vdash p?\lambda_k \cdot \eta' \pir \in \text{DE}(N)$;

  - $s \neq q$. Then $\alpha \vdash s :: \eta' = s :: \eta'$, and thus $\alpha \vdash \nu = \pil p \vdash q!\lambda_k \cdot \eta, s :: \eta' \pir \in \text{DE}(N)$.

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Therefore, \(\alpha \bowtie v \in \mathcal{DE}(N)\). Hence \(RT \subseteq \mathcal{DE}(N)\). We want now to show that \(RT \subseteq \mathcal{NE}(N)\).

Recall from Section 5 that \(\mathcal{NE}(N)\) is the greatest fixed point of the function

\[
f_{\mathcal{DE}(N)}(X) = \{v_0 \in \mathcal{DE}(N) \mid \exists E_0 \subseteq X. E_0 \text{ is a causal set of } v_0 \text{ in } X\}
\]

Then \(\mathcal{NE}(N)\) is also the greatest post-fixed point of \(f_{\mathcal{DE}(N)}(X)\), namely the greatest X such that \(X \subseteq f_{\mathcal{DE}(N)}(X)\). Therefore, to show that \(RT \subseteq \mathcal{NE}(N)\), it is enough to show that \(RT\) is also a post-fixed point of \(f_{\mathcal{DE}(N)}(N)\), namely that \(RT \subseteq f_{\mathcal{DE}(N)}(RT)\).

Consider first the event \(\text{nec}(\alpha)\). Since the only causal set of \(\text{nec}(\alpha)\) in any set is \(\emptyset\), it is immediate that \(\text{nec}(\alpha) \in f_{RT}(RT)\). Consider now \(\alpha \bowtie v \in RT\) for some \(v \in \mathcal{NE}(N)\) with \(\text{loc}(v) = \{r, s\}\). Define

\[
\text{pre}(\alpha, E, v) = \begin{cases} \Xi & \text{if } \{r, s\} \cap \{p, q\} = \emptyset \\ (\text{nec}(\alpha)) \cup \Xi & \text{otherwise} \end{cases}
\]

where \(\Xi = \{\alpha \bowtie v' \mid v' \in E\) and \(E\) is a causal set of \(v\) in \(\mathcal{NE}(N')\).

We show that \(\text{pre}(\alpha, E, v)\) is a causal set of \(\alpha \bowtie v\) in \(RT\), namely that it is a minimal subset of \(RT\) satisfying Conditions (1) and (2) of Definition 5.9.

**Condition (1)** If \(\text{nec}(\alpha) \in \text{pre}(\alpha, E, v)\), then \(\{r, s\} \cap \{p, q\} \neq \emptyset\). A conflict between \(\text{nec}(\alpha)\) and any other event of \(\text{pre}(\alpha, E, v)\) \(\cup\) \(\{\alpha \bowtie v\}\) can only be derived by Clause (2a) of Definition 5.9, since \(\text{nec}(\alpha) = \{p \bowtie \eta_0, q \bowtie p \bowtie \lambda\}\) and \(\{\alpha \bowtie q\} \uplus \{p \bowtie \eta_{\lambda}\}\) for all \(t \notin \{p, q\}\). Suppose \(r = p\). Then \(p \bowtie \eta_0 \bowtie t \in \alpha \bowtie v\). Since \(\alpha \bowtie v_0 \bowtie \eta_{\lambda} < \alpha \bowtie v\), we cannot be used to derive a conflict \(\text{nec}(\alpha) \bowtie \alpha \bowtie v\). Similarly, if \(\alpha \bowtie v_1 \bowtie \alpha \bowtie v_1\) by Lemma 8.2(2).

**Condition (2)** Let \(v = \{r \bowtie \eta, s \bowtie \eta'\}\), we have \(v \bowtie v = \{r \bowtie (\alpha \bowtie r) \cdot \eta, s \bowtie (\alpha \bowtie s) \cdot \eta'\}\). We show that \(\eta_0 < (\alpha \bowtie r) \cdot \eta\), then \(\eta_0 \bowtie v_0 \bowtie v\) for some \(v_0 \bowtie \alpha \bowtie v\). From \(\eta_0 < (\alpha \bowtie r) \cdot \eta\) we have \(\eta_0 = (\alpha \bowtie r) \cdot \zeta\) for some \(\zeta\) such that \(\zeta < \eta\). If \(\zeta \neq \epsilon\), then \(\zeta = \eta_0 < \eta\). Since \(E\) is a causal set, \(\eta_0 < \eta_0\) implies \(r \bowtie \eta_0 \bowtie v\). Hence \(r \bowtie \eta_0 \bowtie \text{pre}(\alpha, E, v)\). If instead \(\zeta = \epsilon\), then it must be \(\eta_0 = (\alpha \bowtie r) \cdot \epsilon\) and \(r \bowtie \eta_0 \bowtie v\). In this case \(\text{nec}(\alpha) \bowtie \alpha \bowtie v\) by Lemma 8.2(3). Assume now that \(\text{pre}(\alpha, E, v)\) is not minimal. Then there is \(E' \bowtie \text{pre}(\alpha, E, v)\) that satisfies Condition (2) of Definition 5.9 for \(\alpha \bowtie v\). Let \(v' \bowtie \text{pre}(\alpha, E, v) \setminus E'\). Then \(v' < \alpha \bowtie v = \{r \bowtie \eta_0, s \bowtie \eta_0\}\). Assume that \(r \bowtie \eta_0 \bowtie v'\) with \(\eta_0 < \eta_0\) (the proof is similar for \(s\)). By Condition 2, there is \(v'' \bowtie E'\) such that \(r \bowtie \eta_0 \bowtie v''\). But then \(v'' \bowtie v''\) by Proposition 5.20, contradicting the fact that \(\text{pre}(\alpha, E, v)\) verifies Condition (1). Therefore \(\text{pre}(\alpha, E, v)\) is minimal.

2 Let \(RS = \{\alpha \bowtie v \mid v \in \mathcal{NE}(N)\) and \(\alpha \bowtie v\) defined\}. We first show that \(RS \subseteq \mathcal{DE}(N')\). Let \(v = \{r \bowtie \eta, s \bowtie \eta'\} \in \mathcal{NE}(N)\) be such that \(\alpha \bowtie v\) is defined. We want to prove that \(\alpha \bowtie v \in \mathcal{DE}(N')\). By Definition 5.13(1), there are \(R, S\) such that \(r[R]_R \in N\) and \(s[S]_S \in N\) and \(r \in \mathcal{PE}(R)\) and \(s \in \mathcal{PE}(S)\). There are two possible cases:
• \( [r, s] \cap [p, q] = \emptyset \). Then \( r \cap R \in \mathbb{N} \) and \( s \cap S \in \mathbb{N} \) and thus \( \alpha \cdot \nu = \nu \in \mathcal{DE}(\mathbb{N}) \);

• \( [r, s] \cap [p, q] \neq \emptyset \). Suppose \( r = p \). Then \( \eta \in \mathcal{PE}(\bigoplus_{i \in I} q! \lambda_i ; P_i) \) and since \( \alpha \cdot \nu \) is defined we have that \( \eta = q! \lambda_k \cdot \eta_k \) where \( \eta_k \in \mathcal{PE}(P_k) \). There are two subcases:

- \( s = q \). Then \( \eta' \in \mathcal{PE}(p! \lambda_i ; Q_i) \) and since \( \alpha \cdot \nu \) is defined \( \eta' = p! \lambda_k \cdot \eta'_k \) where \( \eta'_k \in \mathcal{PE}(Q_k) \). In this case we have \( \alpha \cdot \nu = \{ p :: \eta_k, q :: \eta'_k \} \in \mathcal{DE}(\mathbb{N}) \);

- \( s \neq q \). Then \( \alpha \cdot s :: \eta' = s :: \eta' \), and thus \( \alpha \cdot \nu = \{ p :: \eta_k, s :: \eta'_k \} \in \mathcal{DE}(\mathbb{N}) \).

Therefore \( RS \subseteq \mathcal{DE}(\mathbb{N}) \). We want now to show that \( RS \subseteq \mathcal{NE}(\mathbb{N}) \).

We proceed as in the proof of Statement (1). We know that \( \mathcal{NE}(\mathbb{N}) \) is the greatest

post-fixed point of the function

\[
\mathcal{f}(X) = \{ \nu_0 \in \mathcal{DE}(\mathbb{N}) \mid \exists E_0 \subseteq X. E_0 \text{ is a causal set of } \nu_0 \text{ in } X \}
\]

Then, in order to obtain \( RS \subseteq \mathcal{NE}(\mathbb{N}) \) it is enough to show that \( RS \) is a post-fixed point of \( \mathcal{f}(X) \), namely that \( RS \subseteq \mathcal{f}(RS) \).

Let \( \alpha \cdot \nu \in RS \) for some \( \nu \in \mathcal{NE}(\mathbb{N}) \). Define

\[
\text{post}(\alpha, E, \nu) = \{ \alpha \cdot \nu' \mid \nu' \in E \text{ and } E \text{ is a causal set of } \nu \text{ in } \mathcal{NE}(\mathbb{N}) \}
\]

We show that \( \text{post}(\alpha, E, \nu) \) is a causal set of \( \alpha \cdot \nu \) in \( RS \), namely that it is a minimal subset of \( RS \) satisfying Conditions (1) and (2) of Definition 5.9.

**Condition (1)** Suppose \( \alpha \cdot \nu_1 \in \text{post}(\alpha, E, \nu) \) and \( \alpha \cdot \nu_2 \in \text{post}(\alpha, E, \nu) \). Since \( E \) is a causal set and \( \nu_1, \nu_2 \in E \), we have \( \lnot \nu_1 \cdot \nu_2 \). Thus \( \lnot (\alpha \cdot \nu_1 \cdot \alpha \cdot \nu_2) \) by Lemma 8.2(5) and (1).

**Condition (2)** Since \( \nu = \{ r :: \eta, s :: \eta' \} \) and \( \alpha \cdot \nu \) is defined, we have \( \eta = (\alpha \circ r) \cdot \eta_r \) and \( \eta' = (\alpha \circ s) \cdot \eta_s \) and \( \alpha \cdot \nu = \{ r :: \eta_r, s :: \eta'_s \} \). Let \( \eta_0 < \eta_r \). Then \( (\alpha \circ r) \cdot \eta_0 < (\alpha \circ r) \cdot \eta_r = \eta \). Since \( E \) is a causal set for \( \nu \) in \( \mathcal{NE}(\mathbb{N}) \), this implies \( r :: (\alpha \circ r) \cdot \eta_0 \subseteq E \). Hence \( r :: \eta_0 \in \text{post}(\alpha, E, \nu) \).

As for minimality, we first show that \( \nu' < \alpha \cdot \nu \) for all \( \nu' \in \text{post}(\alpha, E, \nu) \). If \( \nu_1 \in \text{post}(\alpha, E, \nu) \), then there exists \( \nu_1' \in E \) such that \( \nu_1 = \alpha \cdot \nu_1' \). Since \( E \) is a causal set for \( \nu \), we have \( \nu_1' < \nu \). Therefore \( \nu_1 = \alpha \cdot \nu_1' < \alpha \cdot \nu \) by Lemma 8.2(3). Assume now that \( \text{post}(\alpha, E, \nu) \) is not minimal. Then there is \( E' \subset \text{post}(\alpha, E, \nu) \) that verifies Condition (2) of Definition 5.9 for \( \alpha \cdot \nu \). Let \( \nu' \in \text{post}(\alpha, E, \nu) \setminus E' \). Then \( \nu' < \alpha \cdot \nu = \{ r :: \eta_r, s :: \eta_s \} \). Assume that \( r :: \eta'_r \in \nu' \) with \( \eta'_r < \eta_r \) (the proof is similar for \( s \)). By Condition (2), there is \( \nu'' \in E' \) such that \( r :: \eta'_r \in \nu'' \). But then \( \nu' \neq \nu'' \) by Proposition 5.20 contradicting the fact that \( \text{post}(\alpha, E, \nu) \) verifies Condition (1). Therefore \( \text{post}(\alpha, E, \nu) \) is minimal.

**Lemma 8.10** 1. If \( \alpha \cdot \gamma \) is defined, then \( \alpha \circ (\alpha \cdot \gamma) = \gamma \);

2. \( \alpha \cdot (\alpha \circ \gamma) = \gamma \);

3. If \( \gamma_1 < \gamma_2 \), then \( \alpha \circ \gamma_1 < \alpha \circ \gamma_2 \);

4. If \( \gamma_1 < \gamma_2 \) and both \( \alpha \cdot \gamma_1 \) and \( \alpha \cdot \gamma_2 \) are defined, then \( \alpha \cdot \gamma_1 < \alpha \cdot \gamma_2 \);

5. If \( \gamma_1 \neq \gamma_2 \), then \( \alpha \circ \gamma_1 \neq \alpha \circ \gamma_2 \);

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6. If $\gamma < \alpha \circ \gamma'$, then either $\gamma = [\alpha]_-$ or $\alpha \bullet \gamma < \gamma'$.

7. If $\text{part}(a_1) \cap \text{part}(a_2) = \emptyset$, then $a_1 \circ (a_2 \circ \gamma) = a_2 \circ (a_1 \circ \gamma)$;

8. If $\text{part}(a_1) \cap \text{part}(a_2) = \emptyset$ and both $a_2 \bullet (a_1 \circ \gamma)$, $a_2 \bullet \gamma$ are defined, then $a_1 \circ (a_2 \bullet \gamma) = a_2 \bullet (a_1 \circ \gamma)$.

**Proof**

1. If $a \bullet [\sigma]_- = [\sigma]_-$ is defined, then in case $\text{part}(a) \cap \text{part}(\sigma) = \emptyset$ we get $a \bullet [\sigma]_- = [\sigma]_-$ and also $a \circ [\sigma]_- = [\sigma]_-$, so $a \circ (a \bullet [\sigma]_-) = [\sigma]_-$. Instead if $\text{part}(a) \cap \text{part}(\sigma) \neq \emptyset$, then $a \bullet [\sigma]_- = [\sigma]_-$, where $a \sim \sigma \cdot \sigma'$ and $\sigma' \neq \epsilon$. From $\text{part}(a) \cap \text{part}(\sigma) \neq \emptyset$ we get $a \circ [\sigma]_- = [\sigma \cdot \sigma']_-$ by Definition 7.6. This implies $a \circ (a \bullet [\sigma]_-) = [\sigma]_-$. 

2. By Definition 7.6, either $a \circ [\sigma]_- = [\sigma \cdot \sigma']_-$ if $\text{part}(a) \cap \text{part}(\sigma) \neq \emptyset$, or $a \circ [\sigma]_- = [\sigma]_-$.

In the first case, $a \bullet [\sigma \cdot \sigma']_-$ and in the second case $a \bullet [\sigma]_- = [\sigma]_-$, which proves the result.

3. Let $\gamma_1 = [\sigma]_-$ and $\gamma_2 = [\sigma \cdot \sigma']_-$.

If $\text{part}(a) \cap \text{part}(\sigma) \neq \emptyset$, then $\text{part}(a) \cap \text{part}(\sigma \cdot \sigma') 
eq \emptyset$, and we have $a \circ \gamma_1 = [\sigma \cdot \sigma']_-$ and $a \circ \gamma_2 = [\sigma \cdot \sigma']_-$.

4. By Definition 7.6, either $a \circ [\sigma]_- = [\sigma \cdot \sigma']_-$ if $\text{part}(a) \cap \text{part}(\sigma) \neq \emptyset$, or $a \circ [\sigma]_- = [\sigma]_-$.

In the first case, $a \bullet [\sigma \cdot \sigma']_-$ and in the second case $a \bullet [\sigma]_- = [\sigma]_-$, which proves the result.

5. $\gamma_1 = [\sigma]_-$ and $\gamma_2 = [\sigma \cdot \sigma']_-$.

If $a \circ [\sigma]_- = [\sigma \cdot \sigma']_-$, then $a \circ \gamma_1 = [\sigma]_-$ and $a \circ \gamma_2 = [\sigma \cdot \sigma']_-$.

6. Let $\gamma_1 = [\sigma]_-$ and $\gamma_2 = [\sigma \cdot \sigma']_-$.

If $a \circ [\sigma]_- = [\sigma \cdot \sigma']_-$ and by Point 4, $a \circ [\sigma \cdot \sigma']_-$, then either $\gamma = [\alpha]_-$, in which case we are done, or $\text{part}(a) \cap \text{part}(\sigma) 
eq \emptyset$ and $\sigma \neq [\alpha \cdot 0]_-$.

7. Let $\gamma = [\sigma]_-$. By Definition 7.6, we have four cases:

   (a) $a_1 \circ (a_2 \circ \sigma) = [a_1 \cdot (a_2 \cdot \sigma)]_-$ if $\text{part}(a_1) \cap \text{part}(\sigma) 
eq \emptyset$ and $\text{part}(a_2) \cap \text{part}(\sigma) 
eq \emptyset$;

   (b) $a_1 \circ (a_2 \circ \sigma) = [a_1 \cdot \sigma]_-$ if $\text{part}(a_1) \cap \text{part}(\sigma) 
eq \emptyset$ and $\text{part}(a_2) \cap \text{part}(\sigma) = \emptyset$;

   (c) $a_1 \circ (a_2 \circ \sigma) = [a_2 \cdot \sigma]_-$ if $\text{part}(a_1) \cap \text{part}(\sigma) = \emptyset$ and $\text{part}(a_2) \cap \text{part}(\sigma) 
eq \emptyset$;

   (d) $a_1 \circ (a_2 \circ \sigma) = [\sigma]_-$ if $\text{part}(a_1) \cap \text{part}(\sigma) = \emptyset$ and $\text{part}(a_2) \cap \text{part}(\sigma) = \emptyset$.

8. Let $\gamma = [\sigma]_-$. By Definitions 7.6 and 8.9, we have four cases:

   (a) $a_1 \circ (a_2 \circ \sigma) = [a_1 \cdot \sigma]_-$ if $\text{part}(a_1) \cap \text{part}(\sigma) 
eq \emptyset$ and $\sigma \neq a_2 \cdot \sigma'$, which implies $a_1 \cdot \sigma = a_1 \cdot (a_2 \cdot \sigma') \sim a_2 \cdot (a_1 \cdot \sigma')$. Since $\text{part}(a_1) \cap \text{part}(a_2) = \emptyset$;

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(b) \( \alpha_1 \circ (\alpha_2 \cdot \sigma) = [\alpha_1 \cdot \sigma] = \alpha_2 \cdot (\alpha_1 \circ \sigma) \) if \( \text{part}(\alpha_1) \cap \text{part}(\sigma) \neq \emptyset \) and \( \text{part}(\alpha_2) \cap \text{part}(\sigma) = \emptyset \);

(c) \( \alpha_1 \circ (\alpha_2 \cdot \sigma) = [\alpha \cdot \sigma] = \alpha_2 \cdot (\alpha_1 \circ \sigma) \) if \( \text{part}(\alpha_1) \cap \text{part}(\sigma) = \emptyset \) and \( \sigma \sim \alpha_2 \cdot \sigma' \);

(d) \( \alpha_1 \circ (\alpha_2 \cdot \sigma) = [\alpha \cdot \sigma] = \alpha_2 \cdot (\alpha_1 \circ \sigma) \) if \( \text{part}(\alpha_1) \cap \text{part}(\sigma) = \emptyset \) and \( \text{part}(\alpha_2) \cap \text{part}(\sigma) = \emptyset \).

**Lemma 8.12** Let \( G \xrightarrow{a} G' \).

1. If \( \gamma \in \mathcal{GE}(G') \), then \( a \circ \gamma \in \mathcal{GE}(G) \);

2. If \( \gamma \in \mathcal{GE}(G) \) and \( a \cdot \gamma \) is defined, then \( a \cdot \gamma \in \mathcal{GE}(G') \).

**Proof** Both proofs are by induction on the inference of the transition \( G \xrightarrow{a} G' \), see Figure 4.

1. For rule \([\text{Ecomm}]\) we get \( G = p \rightarrow q : \bigoplus_{i \in I} \lambda_i; G_i \) and \( G' = G_k \) for some \( k \in I \). We conclude \( a \cdot \gamma \in \mathcal{GE}(G) \) by Lemma 8.11(1).

2. For rule \([\text{Icomm}]\) we get \( G = p \rightarrow q : \bigoplus_{i \in I} \lambda_i; G_i \) and \( G' = G' \) for all \( i \in I \) and \( \text{part}(a) \cap \{p, q\} = \emptyset \). By Definition 7.10(1) \( \gamma \in \mathcal{GE}(G') \) implies \( \gamma = \text{ev}(\sigma) \) for some \( \sigma \in \text{Tr}^+(G') \). This implies \( \sigma = \text{pq}_{\lambda_k} \cdot \sigma' \) and \( \gamma = [\sigma_0] \), with either \( \sigma_0 \sim \text{pq}_{\lambda_k} \cdot \sigma' \) for some \( k \in I \) or \( \text{part}(\sigma_0) \cap \{p, q\} = \emptyset \) by Definition 7.6. Then \( \text{pq}_{\lambda_k} \cdot \gamma \) is defined unless \( \sigma_0 = \text{pq}_{\lambda_k} \) by Definition 8.9(1). We consider two cases.

If \( \sigma_0 = \text{pq}_{\lambda_k} \), then \( a \circ \gamma = [\sigma_0 \lambda_k] \) since \( \text{part}(a) \cap \{p, q\} = \emptyset \). We conclude \( a \circ \gamma \in \mathcal{GE}(G) \) by Definition 7.10(1).

2. For rule \([\text{Ecomm}]\) we get \( G = p \rightarrow q : \bigoplus_{i \in I} \lambda_i; G_i \) and \( G' = G_k \) for some \( k \in I \). We conclude \( a \cdot \gamma \in \mathcal{GE}(G') \) by Lemma 8.11(2).

For rule \([\text{Icomm}]\) we get \( G = p \rightarrow q : \bigoplus_{i \in I} \lambda_i; G_i \) and \( G = p \rightarrow q : \bigoplus_{i \in I} \lambda_i; G_i' \) and \( G_i \xrightarrow{a} G_i' \) for all \( i \in I \) and \( \text{part}(a) \cap \{p, q\} = \emptyset \). By Definition 7.10(1) \( \gamma \in \mathcal{GE}(G) \) implies \( \gamma = \text{ev}(\sigma) \) for some \( \sigma \in \text{Tr}^+(G) \). This implies \( \sigma = \text{pq}_{\lambda_k} \cdot \sigma' \) and \( \gamma = [\sigma_0] \), with either \( \sigma_0 \sim \text{pq}_{\lambda_k} \cdot \sigma' \) for some \( k \in I \) or \( \text{part}(\sigma_0) \cap \{p, q\} = \emptyset \) by Definition 7.6. Then \( \text{pq}_{\lambda_k} \cdot \gamma \) is defined unless \( \sigma_0 = \text{pq}_{\lambda_k} \) by Definition 8.9(1). We consider two cases.

If \( \sigma_0 = \text{pq}_{\lambda_k} \), then \( a \circ \gamma = [\sigma_0 \lambda_k] \) since \( \text{part}(a) \cap \{p, q\} = \emptyset \). We conclude \( a \circ \gamma \in \mathcal{GE}(G') \) by Definition 7.10(1).

Otherwise let \( \gamma' = \text{pq}_{\lambda_k} \cdot \gamma \). By Lemma 8.11(2) \( \gamma' \in \mathcal{GE}(G_k) \). By Lemma 8.11(1) \( \text{pq}_{\lambda_k} \circ (a \circ \gamma') \in \mathcal{GE}(G_k) \). We now show that \( \text{pq}_{\lambda_k} \circ (a \circ \gamma') = a \circ \gamma \). By Lemma 8.10(7) and \( \text{part}(a) \cap \{p, q\} = \emptyset \) we get \( \text{pq}_{\lambda_k} \circ (a \circ \gamma') = a \circ (\text{pq}_{\lambda_k} \circ \gamma') \) and by Lemma 8.10(1) we have \( \text{pq}_{\lambda_k} \circ \gamma' = \text{pq}_{\lambda_k} \circ (a \circ \gamma') = a \circ \gamma \in \mathcal{GE}(G) \).

We consider two cases.

If \( \sigma_0 = \text{pq}_{\lambda_k} \), then \( a \circ \gamma = [\sigma_0 \lambda_k] \) since \( \text{part}(a) \cap \{p, q\} = \emptyset \). We conclude \( a \circ \gamma \in \mathcal{GE}(G') \) by Definition 7.10(1).

Otherwise let \( \gamma' = \text{pq}_{\lambda_k} \cdot \gamma \). By Lemma 8.11(2) \( \gamma' \in \mathcal{GE}(G) \). We first show that \( a \circ \gamma \) is defined. Since \( a \circ \gamma \) and \( \text{pq}_{\lambda_k} \circ \gamma \) are defined, by Definition 8.9(1) we have four cases:

(a) \( \sigma_0 \sim a \cdot \sigma_1 \) for some \( \sigma_1 \) and \( \sigma_0 \sim \text{pq}_{\lambda_k} \cdot \sigma' \);

(b) \( \sigma_0 \sim a \cdot \sigma_1 \) and \( \text{part}(\sigma_0) \cap \{p, q\} = \emptyset \);

(c) \( \text{part}(a) \cap \text{part}(\sigma_0) = \emptyset \) and \( \sigma_0 \sim \text{pq}_{\lambda_k} \cdot \sigma_0' \);

(d) \( \text{part}(a) \cap \text{part}(\sigma_0) = \emptyset \) and \( \text{part}(\sigma_0) \cap \{p, q\} = \emptyset \).
In case (a) \( \sigma_0 \sim \alpha \cdot p q \lambda_k \cdot \sigma'_1 \sim p q \lambda_k \cdot \alpha \cdot \sigma'_1 \) for some \( \sigma'_1 \) since \( \text{part}(\alpha) \cap \{p, q\} = \emptyset \). Notice that \( \sigma'_1 \neq \varepsilon \) since \( \sigma_0 \) is pointed and \( \text{part}(\alpha) \cap \{p, q\} = \emptyset \). We get \( \gamma' = p q \lambda_k \cdot \gamma = [\alpha \cdot \sigma'_1]_\sim \) and \( \alpha \cdot \gamma' = [\sigma'_1]_\sim \).

In case (b) \( \gamma' = \gamma \) and \( \alpha \cdot \gamma' = [\sigma_0]_\sim \).

In case (c) \( \gamma' = [\sigma'_0]_\sim \) and \( \alpha \cdot \gamma' = [\sigma'_0]_\sim \), since \( \text{part}(\alpha) \cap \text{part}(\sigma_0) = \emptyset \) implies \( \text{part}(\alpha) \cap \text{part}(\sigma'_0) = \emptyset \).

In case (d) \( \gamma' = \gamma \) and \( \alpha \cdot \gamma' = \gamma \).

By induction \( \alpha \cdot \gamma' \in \mathcal{GE}(G') \). By Lemma 8.11(1) \( p q \lambda_k \circ (\alpha \cdot \gamma') \in \mathcal{GE}(G') \).

We now show that \( p q \lambda_k \circ (\alpha \cdot \gamma') = \alpha \cdot \gamma \). From \( \gamma' = p q \lambda_k \cdot \gamma \) and Lemma 8.10(1) \( p q \lambda_k \circ \gamma = \gamma \). Therefore from \( \alpha \cdot \gamma \) defined we have \( \alpha \cdot (p q \lambda_k \circ \gamma') \) defined. Since \( \alpha \cdot \gamma' \) is also defined and \( \text{part}(\alpha) \cap \{p, q\} = \emptyset \), by Lemma 8.10(8) we get \( p q \lambda_k \circ (\alpha \cdot \gamma') = \alpha \cdot (p q \lambda_k \circ \gamma') \). Therefore \( p q \lambda_k \circ (\alpha \cdot \gamma') = \alpha \cdot \gamma \in \mathcal{GE}(G') \).