Quartic Spectrahedra

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Abstract
Quartic spectrahedra in 3-space form a semialgebraic set of dimension 24. This set is stratified by the location of its ten nodes. There are twenty maximal strata, identified recently by Degtyarev and Itenberg, via the global Torelli Theorem for real K3 surfaces. We here give a new proof that is self-contained and algorithmic. This involves extending Cayley’s characterization of quartic symmetroids, by the property that the branch locus of the projection from a node consists of two cubic curves. This paper represents a first step towards the classification of all spectrahedra of a given degree and dimension.

1 Introduction
Spectrahedra are fundamental objects in convex algebraic geometry [2]. A spectrahedron is the intersection of the cone of positive-semidefinite matrices with an affine subspace of the space of real symmetric \( n \times n \)-matrices. In this paper, the subspace has dimension three and is identified with \( \mathbb{R}^3 \). The algebraic boundary of a three-dimensional spectrahedron in \( \mathbb{R}^3 \) is a surface \( V(f) \) in complex projective space \( \mathbb{CP}^3 \). Its defining polynomial \( f(x) = f(x_0, x_1, x_2, x_3) \) is the determinant of a symmetric matrix \( A(x) \) of linear forms. Explicitly,

\[
A(x) = A_0 x_0 + A_1 x_1 + A_2 x_2 + A_3 x_3.
\]

(1.1)

The surfaces \( V(f) \) are known as symmetroids in classical algebraic geometry [3, 4, 5, 13]. Generally, we allow the entries in the symmetric \( n \times n \)-matrices \( A_0, A_1, A_2, A_3 \) to be arbitrary complex numbers. We say that \( V(f) \) is a real symmetroid if all \( \binom{n+3}{3} \) coefficients of \( f \) are real numbers and that \( V(f) \) is a very real symmetroid if \( A_0, A_1, A_2, A_3 \) can be chosen to have real entries. The spectrahedron associated to a very real symmetroid \( V(f) \) is the set

\[
S(f) = \{ x \in \mathbb{RP}^3 : A(x) = A_0 x_0 + A_1 x_1 + A_2 x_2 + A_3 x_3 \text{ is semidefinite} \}.
\]

Using Gårding’s theory of hyperbolic polynomials [10, 16], one sees that \( S(f) \) is determined by \( f(x) \), i.e. the matrices \( A_0, A_1, A_2, A_3 \) are not needed to identify the set \( S(f) \). We say that a symmetroid \( V(f) \) is spectrahedral if it is very real and \( S(f) \) is full-dimensional in \( \mathbb{RP}^3 \).
A symmetroid is called *nodal* if all its singular points are nodes, i.e. isolated quadratic singularities. Generically there are \( \binom{n+1}{3} \) nodes on \( V(f) \). A point \( x \in \mathbb{RP}^3 \) where the matrix \( A(x) \) has rank \( n-2 \) will be called a *rank-(n-2)-point*. Such a point is singular on the surface \( V(f) \) and generically it is a node. A nodal symmetroid is *transversal* if the number of nodes equals \( \binom{n+1}{3} \), in which case all the nodes are rank-(n-2) points. A spectrahedron \( S(f) \) is *nodal* resp. *transversal* its symmetroid \( V(f) \) has this property. For example, the *Kummer symmetroid* in Figure [9] is nodal but not transversal: it has 16 nodes, not just 10.

The set \( S \) of symmetroids forms an irreducible variety in the projective space \( \mathbb{CP}^{\binom{n+3}{3}-1} \) of all surfaces of degree \( n \) in \( \mathbb{CP}^3 \), and a generic point in \( S \) corresponds to a transversal symmetroid. The set \( S_{\text{spec}} \) of spectrahedral symmetroids is Zariski dense in the variety \( S \) of complex symmetroids. The objects above form a nested sequence of semialgebraic subsets:

\[
S_{\text{spec}} \subseteq S_{\text{veryreal}} \subseteq S_{\text{real}} = S \cap \mathbb{RP}^{\binom{n+3}{3}-1}.
\]

For \( n = 1 \), every spectrahedron is a halfspace. For \( n = 2 \), a spectrahedron is a quadratic cone and the left inclusion in (1.2) is an equality. The quadric \( x_0^2 + x_1^2 + x_2^2 \) lies in \( S_{\text{real}} \setminus S_{\text{veryreal}} \), because no triple of real symmetric \( 2 \times 2 \)-matrices satisfies \( \det(A_i) = 1 \) and \( \det(A_j + A_k) = 2 \).

![Figure 1: A transversal cubic spectrahedron has either four nodes or two nodes.](image)

The case \( n = 3 \) of cubic spectrahedra is visualized by the two pictures in Figure [1]. Here, the algebraic boundary is Cayley’s *cubic symmetroid*. Such a cubic surface has four complex nodes, and it is unique up to projective transformations over \( \mathbb{C} \). It is obtained by blowing up \( \mathbb{CP}^2 \) at the six intersection points of four general lines. Cubic symmetroids in \( S_{\text{real}} \) correspond to configurations of four lines that can be defined collectively over \( \mathbb{R} \). There are three types:

(a) All four lines are defined over \( \mathbb{R} \). This gives the left picture with four real nodes.

(b) Two lines are defined over \( \mathbb{R} \) and the others form a complex conjugate pair of lines. This gives the right picture, with two real nodes, both in the boundary of the spectrahedron.
There are two complex conjugate pairs of lines. The two first types are shown in Figure 1. Very real cubic symmetroids of type (c) have no real nodes, and they belong to the set $S_{\text{veryreal}} \setminus S_{\text{spec}}$ (cf. Remark 4.3 and Example 4.4).

In this paper we investigate the case $n = 4$ of quartic spectrahedra. The corresponding variety $S$ has codimension 10 in the $\mathbb{CP}^3$ of all quartics. In the context of convex algebraic geometry it has appeared in [1, Theorem 3], where it parametrizes extremal non-negative quartics that are not sums of squares. Such symmetroids, like the Choi-Lam-Reznick quartic in [1, (8)], are in $S_{\text{real}} \setminus S_{\text{veryreal}}$. See Example 4.4 for a quartic symmetroid in $S_{\text{veryreal}} \setminus S_{\text{spec}}$.

In response to a question by the third author, Degtyarev and Itenberg [6] studied the location of the ten nodes on a spectrahedral symmetroid. They proved the following result:

**Theorem 1.1.** There exists a transversal quartic spectrahedron with $\sigma$ nodes on its boundary and $\rho$ real nodes in its symmetroid if and only if $0 \leq \sigma \leq \rho$, both are even, and $2 \leq \rho \leq 10$.

The proof given by Degtyarev and Itenberg in [6] is very indirect. It translates the problem into the period domain for K3 surfaces via the Global Torelli Theorem, and it proceeds by characterizing the various strata in $S$ in terms of intersection lattices. That approach cannot be used to actually construct matrices $A(x)$ for quartic spectrahedra.

We here present a new proof which is elementary, computational, and self-contained. For the if-direction of Theorem 1.1 Section 2 exhibits twenty matrices $A(x)$ which realize the allowed pairs of parameters $(\rho, \sigma)$. That list generalizes Figure 1 which depicts the classification of cubic spectrahedra into two types, $(\rho, \sigma) = (2, 2)$ and $(\rho, \sigma) = (4, 4)$.

Our proof of the only-if direction uses classical projective geometry, and it will be given in Section 4. The idea is to build an explicit parametrization of the semi-algebraic set $S_{\text{spec}}$ in terms of the ramification data of the projection of a symmetroid from one of its nodes.

The projection of a quartic surface from a node $p$ is a double cover of $\mathbb{CP}^2$ ramified along a sextic plane curve $R_p$, with a totally tangent conic $C_p$, the image of the tangent cone at $p$. This picture goes back to Cayley [3] who used it to characterize nodes on quartic symmetroids. We extend Cayley’s result to the real numbers, with focus on spectrahedra.

**Theorem 1.2.** Let $p$ be a node on a quartic surface $X$ in $\mathbb{CP}^3$. Then $X$ is a transversal symmetroid with no line through $p$ if and only if the ramification curve is the union of two smooth cubic curves $R_p = R_1 \cup R_2$ intersecting transversally in 9 points. The surface $X$ and the point $p$ are real if and only if the curves $R_1 \cup R_2$ and $C_p$ are real. Furthermore,

1. $X$ is very real and $p$ is real if and only if $R_1 \cup R_2$ is real and $C_p$ has a real point.

2. $X$ is spectrahedral and $p$ lies on the spectrahedron if and only if the cubics $R_1$ and $R_2$ are complex conjugates and the conic $C_p$ has a real point.

3. $X$ is very real and $p$ is a real node that does not lie on a spectrahedron if and only if the cubics $R_1$ and $R_2$ are real and the conic $C_p$ has a real point.
Theorem 1.2 characterizes the location of generic points in the various strata of (1.2). Special points are obtained as limits of these. A special symmetroid may contain a line that passes through a node $p$, and the cubics $R_1, R_2$ may be singular. For instance, the Kummer symmetroid shown in Figure 9 contains 16 lines and each cubic $R_i$ factors into three lines.

The paper is organized as follows. Section 2 contains our gallery of transversal quartic spectrahedra. Section 3 develops the projective geometry of (real) quartic symmetroids and their projections from nodes. It furnishes a self-contained proof of Theorem 1.2. Section 4 completes the proof of Theorem 1.1 and develops a further extension of Theorem 1.2 in terms of interlacing cubics. Section 5 serves “spectrahedral treats”: various families of quartics seen in the convex algebraic geometry literature. We explain how they fit into our general theory.

![Figure 2: Two quartic spectrahedra, of type $(\rho, \sigma) = (10, 10)$ and of type $(\rho, \sigma) = (10, 8)$.](image)

## 2 Twenty Types of Transversal Spectrahedra

A transversal quartic symmetroid is a surface in $\mathbb{CP}^3$ with 10 nodes. We are primarily interested in real symmetroids, those defined over $\mathbb{R}$. A transversal quartic spectrahedron is a convex body in $\mathbb{RP}^3$ whose (topological) boundary has a transversal quartic symmetroid as its Zariski closure. The type $(\rho, \sigma)$ of a transversal quartic spectrahedron records the number $\rho$ of real nodes of the symmetroid and the number $\sigma$ of nodes that lie on the spectrahedron. Since the spectrahedron’s boundary is part of the real symmetroid, we always have $\sigma \leq \rho$.

Figure 2 illustrates the situation. Spectrahedral symmetroids have one distinguished connected component in their complement in $\mathbb{RP}^3$, namely the spectrahedron itself. This is
a convex body which serves as the set of feasible points in semidefinite programming (SDP) [2]. Both symmetroids in Figure 2 have all 10 nodes real. The one on the left has all 10 nodes on the spectrahedron. The symmetroid on the right has 8 nodes on the spectrahedron and 2 nodes off the spectrahedron. Concretely, the spectrahedron on the left is the compact convex set defined by requiring that the following matrix $A(x)$ is positive semidefinite:

\[
\begin{bmatrix}
45x_0 + 40x_1 + 65x_2 + 72x_3 & 33x_0 + 50x_1 + 7x_2 - 60x_3 & -84x_0 + 12x_1 + 3x_2 - 54x_3 & -21x_0 + 16x_1 + 54x_2 - 18x_3 \\
33x_0 + 50x_1 + 7x_2 - 60x_3 & 82x_0 + 85x_1 + 2x_2 + 82x_3 & -99x_0 + 12x_1 + 6x_2 + 25x_3 & -46x_0 + 41x_1 + 18x_2 + 51x_3 \\
-84x_0 + 12x_1 + 3x_2 - 54x_3 & -99x_0 + 12x_1 + 6x_2 + 25x_3 & 181x_0 + 4x_1 + 26x_2 + 53x_3 & 59x_0 + 2x_1 + 58x_2 - 9x_3 \\
-21x_0 + 16x_1 + 54x_2 - 18x_3 & -46x_0 + 41x_1 + 18x_2 + 51x_3 & 59x_0 + 2x_1 + 58x_2 - 9x_3 & 26x_0 + 26x_1 + 164x_2 + 45x_3
\end{bmatrix}
\]

In the optimization literature, this constraint is denoted $A(x) \succeq 0$. This is called a linear matrix inequality (LMI). One maximizes a linear function over the spectrahedron. The optimal solution $A(x)$ has either rank 3 and is attained at a smooth point in the boundary, or it has rank 2 and is attained at one of the nodes. For the types with $\sigma = 0$, none of the nodes lie in the boundary of the spectrahedron. In this case, the rank of the optimal solution to the SDP is always 3, for any choice of linear cost function. Here is a specimen.

Figure 3: A quartic spectrahedron of type $(\rho, \sigma) = (10, 0)$, and its projection from a node.

**Example 2.1.** Figure 3 shows a quartic symmetroid with 10 real nodes. None of them lies on the spectrahedron. The topological boundary of the spectrahedron is a smooth 2-sphere $S^2$. As argued in Figure 1 and Remark 4.3 no such smooth spectrahedra exist for $n = 3$. ♦
Here is one more contribution to our picture gallery. Figure 4 shows a quartic spectrahedron that has two nodes in its boundary, and no further real nodes on the symmetroid. In this diagram, the real part of the symmetroid is a compact surface in affine 3-space.

Figure 4: A quartic symmetroid of type \((\rho, \sigma) = (2, 2)\).

We now establish the existence part of the Degtyarev-Itenberg theorem.

Proof of the if direction in Theorem 1.1. The constraints \(0 \leq \sigma \leq \rho \leq 10\) and \(\rho \geq 2\) allow for 20 solutions \((\rho, \sigma)\) among even integers. In the following table we list the twenty pairs \((\rho, \sigma)\) followed by four symmetric \(4 \times 4\)-matrices \(A_0, A_1, A_2, A_3\) with integer entries. Each quadruple specifies a matrix \(A(x)\) as in (1.1) whose symmetroid \(f = \det(A(x))\) is transversal and has a non-empty spectrahedron \(S(f)\). To verify the correctness of the list, one computes the ten complex nodes, one checks that \(\rho\) of them are real, and one examines how many lie on the spectrahedron. The latter test is done by computing the eigenvalues of the matrix \(A(x)\) at each node \(x\). If all eigenvalues have the same sign then \(x\) is on the spectrahedron. The list starts with \((\rho, \sigma) = (2, 2)\), as in Figure 4, and ends with \((\rho, \sigma) = (10, 0)\), as in Figure 3.

\[
\begin{align*}
(2, 2) : & \begin{bmatrix} 3 & 4 & 1 & -4 \\ 4 & 14 & -6 & -10 \\ 1 & -6 & 9 & 2 \\ -4 & -10 & 2 & 8 \end{bmatrix} \\
& \begin{bmatrix} 11 & 0 & 2 & 2 \\ 0 & 6 & -1 & 4 \\ 2 & -1 & 6 & 2 \\ 2 & 4 & 2 & 4 \end{bmatrix} \\
& \begin{bmatrix} 17 & -3 & 2 & 9 \\ -3 & 6 & -4 & 1 \\ 2 & -4 & 13 & 10 \\ 9 & 1 & 10 & 17 \end{bmatrix} \\
& \begin{bmatrix} 9 & -3 & 9 & 3 \\ -3 & 10 & 6 & -7 \\ 9 & 6 & 18 & -3 \\ 3 & -7 & -3 & 5 \end{bmatrix} \\
(4, 4) : & \begin{bmatrix} 18 & 3 & 9 & 6 \\ 3 & 5 & -1 & -3 \\ 9 & -1 & 13 & 7 \\ 6 & -3 & 7 & 6 \end{bmatrix} \\
& \begin{bmatrix} 17 & -10 & 4 & 3 \\ -10 & 14 & -1 & -3 \\ 4 & -1 & 5 & -4 \\ 3 & -3 & -4 & 6 \end{bmatrix} \\
& \begin{bmatrix} 8 & 6 & 10 & 10 \\ 6 & 18 & 6 & 15 \\ 10 & 6 & 14 & 9 \\ 10 & 15 & 9 & 22 \end{bmatrix} \\
& \begin{bmatrix} 8 & -4 & 8 & 0 \\ -4 & 10 & -4 & 0 \\ 8 & -4 & 8 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}
\end{align*}
\]
\[
\begin{align*}
(6,6) : \\
\begin{bmatrix}
10 & 8 & 2 & 6 \\
8 & 14 & 0 & 2 \\
2 & 0 & 5 & 7 \\
6 & 2 & 7 & 11 \\
\end{bmatrix} & \begin{bmatrix}
11 & -6 & 10 & 9 \\
-10 & -15 & 11 & 7 \\
10 & -5 & 14 & 11 \\
9 & -5 & 11 & 9 \\
\end{bmatrix} & \begin{bmatrix}
6 & 2 & 6 & -5 \\
2 & 9 & 2 & 0 \\
6 & 2 & 6 & -5 \\
-5 & 0 & -5 & 5 \\
\end{bmatrix} & \begin{bmatrix}
8 & 6 & 2 & -2 \\
6 & 9 & 9 & 6 \\
6 & 9 & 9 & 6 \\
-2 & 6 & 12 & 13 \\
\end{bmatrix} \\
(8,8) : \\
\begin{bmatrix}
5 & 3 & -3 & -4 \\
3 & 6 & -3 & -2 \\
-3 & -3 & 6 & 4 \\
-4 & -2 & 4 & 4 \\
\end{bmatrix} & \begin{bmatrix}
19 & 10 & 12 & 17 \\
10 & 14 & 10 & 7 \\
12 & 10 & 10 & 11 \\
17 & 7 & 11 & 17 \\
\end{bmatrix} & \begin{bmatrix}
5 & 1 & 3 & -3 \\
1 & 5 & -7 & -1 \\
3 & -7 & 22 & 7 \\
3 & -1 & 7 & 10 \\
\end{bmatrix} & \begin{bmatrix}
1 & 1 & 0 & 2 \\
1 & 1 & 0 & 2 \\
0 & 0 & 4 & 4 \\
2 & 2 & 4 & 8 \\
\end{bmatrix} \\
(10,10) : \\
\begin{bmatrix}
18 & 6 & 6 & -6 \\
6 & 2 & 2 & -2 \\
6 & 2 & 2 & -2 \\
-6 & -2 & -2 & 4 \\
\end{bmatrix} & \begin{bmatrix}
4 & -6 & 6 & 4 \\
-6 & 13 & -9 & -8 \\
6 & -9 & 9 & 6 \\
4 & -8 & 6 & 5 \\
\end{bmatrix} & \begin{bmatrix}
1 & 0 & -3 & 0 \\
0 & 4 & 0 & 6 \\
-3 & 0 & 9 & 0 \\
0 & 6 & 0 & 9 \\
\end{bmatrix} & \begin{bmatrix}
9 & -3 & 0 & 0 \\
-3 & 10 & 9 & -6 \\
0 & 9 & 9 & -6 \\
0 & -6 & -6 & 4 \\
\end{bmatrix} \\
\end{align*}
\]
defines a rational $2:1$ map to the plane role in Huh’s recent counterexample to the geometric Chevalley-Warning conjecture [12].

develop this approach over $\mathbb{R}$ [13]. See also Cossec [5] and Dolgachev [8] for modern proofs of some of the results. We here

The classical approach to nodal quartics in 3-space is via their double cover of the plane

3 Ramification and Cayley’s Theorem

The classical approach to nodal quartics in 3-space is via their double cover of the plane when projected from a node. Relevant references include Cayley [3], Coble [4], and Jessop [13]. See also Cossec [5] and Dolgachev [8] for modern proofs of some of the results. We here develop this approach over $\mathbb{R}$, for quartic spectrahedra. The goal is to prove Theorem [1.2].

We note that quartic symmetroids and their ramification over two cubics play a crucial role in Huh’s recent counterexample to the geometric Chevalley-Warning conjecture [12].

Let $X = V(f) \subset \mathbb{C}P^3$ be a quartic surface and $p$ a node on $X$. The projection from $p$ defines a rational $2:1$ map to the plane $\mathbb{C}P^2$. It extends to a morphism on the blowup $\tilde{X} \to X$ with exceptional curve $E_p$ lying over $p$. We denote this extended double cover by

\[ \pi_p = \pi_p(\mathbb{C}) : \tilde{X} \to \mathbb{C}P^2. \]
If \( p \) is a real point, then \( \pi_p \) maps the real part of \( X \) to the real projective plane:

\[
\pi_p(\mathbb{R}) : \tilde{X}_R \rightarrow \mathbb{RP}^2.
\]

Assume \( p = (1 : 0 : 0 : 0) \). Then \( f = ax_0^2 + bx_0 + c \) with \( a, b, c \in \mathbb{C}[x_1, x_2, x_3] \). The fiber of \( \pi_p \) is given by the roots of \( f \), and the ramification locus is the sextic curve \( R_p = V(b^2 - 4ac) \).

The lines in \( X \) through \( p \) and the singular points of \( X \setminus p \) map to the singular points of \( R_p \). Each node of \( R_p \) is the image of a node on \( X \setminus p \) or the image of a line in \( X \) through \( p \).

The real projection \( \pi_p(\mathbb{R}) \) is ramified in the real points of the sextic curve \( R_p \). The quadratic equation \( a = 0 \) defines in \( \mathbb{CP}^3 \) the tangent cone of \( X \) at \( p \). In \( \mathbb{CP}^2 \) it defines a conic section, the image \( C_p \) under \( \pi_p \) of the exceptional curve \( E_p \) on \( \tilde{X} \). Since the equation \( b^2 - 4ac \) of \( R_p \) is a square modulo \( a \), the sextic \( R_p \) is totally tangent to the conic \( C_p \).

Suppose now that \( f(x) = \det(A(x)) \) as in (1.1). A node \( p \) on the symmetroid \( X = V(f) \) has rank 2 or 3. If \( X \) is transversal then every node has rank 2. A real node \( p \) on a very real symmetroid \( X \) is an \((m, n)\)-node if the matrix \( A(p) \) has \( m \) positive and \( n \) negative eigenvalues. Because we are working projectively, we can always take \( m \geq n \). Thus there are two types of rank-2 nodes: (2,0)-nodes that lie on the spectrahedron \( S(f) \) and (1,1)-nodes that do not.

Cayley discovered that if the node \( p \) has rank 2, then the ramification locus is the union of two cubic curves and vice versa (cf. [3, 5, 13]). We now prove our extension of his result.

**Proof of Theorem 1.2.** \((\Rightarrow)\) Suppose that \( p \) is a rank-2 node on the symmetroid \( X = V(f) \). After a change of coordinates, we can take \( p = (1 : 0 : 0 : 0) \). By conjugating with an appropriate matrix (over \( \mathbb{C} \)), we can write \( f \) as the determinant of the symmetric matrix

\[
\begin{bmatrix}
m_{11} & x_0 + m_{12} & m_{13} & m_{14} \\
x_0 + m_{12} & m_{22} & m_{23} & m_{24} \\
m_{13} & m_{23} & m_{33} & m_{34} \\
m_{14} & m_{24} & m_{34} & m_{44}
\end{bmatrix}
\]

(3.1)

where each \( m_{jk} \) is a linear form in \( x_1, x_2, x_3 \). This determinant equals

\[
f = -q \cdot x_0^2 + 2F_{12} \cdot x_0 + \Delta, \quad \text{where} \quad q = \begin{vmatrix} m_{33} & m_{34} \\ m_{34} & m_{44} \end{vmatrix}.
\]

(3.2)

Here \( \Delta \) is the determinant of the matrix \((m_{jk})\), and the cubic \( F_{jk} \) denotes the cofactor of \( m_{jk} \) in this matrix. The ramification locus \( R_p \) is the curve in \( \mathbb{CP}^2 \) defined by the sextic equation

\[
0 = (2F_{12})^2 - 4(-q)\Delta = 4(F_{12}^2 + q\Delta).
\]

Using the determinantal formula \( q\Delta = F_{11}F_{22} - F_{12}^2 \), this sextic factors into two cubics:

\[
F_{12}^2 + q\Delta = F_{11} \cdot F_{22}.
\]
Any singular point of $R_p$ gives a singular point of $X$, so if $X$ is transversal, $F_11$ and $F_22$ are both smooth.

$(1.2.3 \Rightarrow)$ Suppose that the symmetroid $f$ is very real and $p$ is a $(1,1)$-node. There exists a real change of coordinates taking $p$ to $(1:0:0:0)$. The quartic $f$ can be written as the determinant (3.1) where the $m_{jk}$ are linear forms in $\mathbb{R}[x_1,x_2,x_3]$. The above argument shows that the two ramification cubics $F_{11}$ and $F_{22}$ are real.

$(1.2.2 \Rightarrow)$ Suppose instead that $f$ is very real and $p$ is a $(2,0)$-node. We again make a real change of coordinates so that $p = (1:0:0:0)$. Then $f$ has a determinantal representation

$$
\begin{vmatrix}
\frac{1}{2}x_0 + \ell_{11} & \ell_{12} & \ell_{13} & \ell_{14} \\
\ell_{12} & \frac{1}{2}x_0 + \ell_{22} & \ell_{23} & \ell_{24} \\
\ell_{13} & \ell_{23} & \ell_{33} & \ell_{34} \\
\ell_{14} & \ell_{24} & \ell_{34} & \ell_{44}
\end{vmatrix} = -\frac{1}{4}
\begin{vmatrix}
\ell_{11} - \ell_{22} + 2i\ell_{12} & \ell_{11} + \ell_{22} + x_0 & \ell_{13} + i\ell_{23} & \ell_{14} + i\ell_{24} \\
\ell_{11} + \ell_{22} + x_0 & \ell_{11} - \ell_{22} - 2i\ell_{12} & \ell_{13} - i\ell_{23} & \ell_{14} - i\ell_{24} \\
\ell_{13} + i\ell_{23} & \ell_{13} - i\ell_{23} & \ell_{33} & \ell_{34} \\
\ell_{14} + i\ell_{24} & \ell_{14} - i\ell_{24} & \ell_{34} & \ell_{44}
\end{vmatrix}
$$

with real linear forms $\ell_{jk} \in \mathbb{R}[x_1,x_2,x_3]$. The right matrix is obtained by conjugating the left with an appropriate complex matrix to return it to the form (3.1). The ramification cubics are still given by the cofactors $F_{11}$, $F_{22}$ of the right-hand matrix, which are complex conjugates.

$(1.2.1 \Rightarrow)$ This is immediate from the statements $(1.2.2 \Rightarrow)$ and $(1.2.3 \Rightarrow)$.

To finish the “forward” directions of Theorem 1.2, note that in both of these real cases, the quadratic $q$ defining $C_p$ has a real symmetric determinantal representation (3.2). This implies that $C_p$ must have a real point, since a positive quadratic form is not very real.

$(\Leftarrow)$ Suppose that $X = V(f)$ is a quartic surface with a node at $p = (1:0:0:0)$ and that the ramification locus factors into two smooth cubic curves $R_1 = V(F_{11})$ and $R_2 = V(F_{22})$. We suppose furthermore that $R_1$ and $R_2$ intersect transversally in 9 points. Then $X$ has precisely 10 nodes, and the quartic has the form $f = -qx_0^2 + 2gx_0 + \Delta$, where $V(q)$ is a smooth conic, $V(\Delta)$ is a smooth quartic, and $V(q,g,\Delta) = \emptyset$. We shall verify that $X$ is a symmetroid by constructing a symmetric determinantal representation, up to sign, of $f$.

We first construct a symmetric determinantal representation for the ternary quartic $\Delta$. This will be done using Dixon’s method [7]. Up to rescaling of $F_{11}$, we have

$$
F_{11}F_{22} = ((2g)^2 - (-q)\Delta)/4 = g^2 + q\Delta \quad \text{in } \mathbb{C}[x_1,x_2,x_3].
$$

Since $q\Delta$ is a square modulo $F_{11}$, there are subschemes $Z_q$ and $Z_\Delta$ in $V(F_{11})$, satisfying

$$
2Z_q = V(q,F_{11}) \quad \text{and} \quad 2Z_\Delta = V(\Delta,F_{11}),
$$

of length 3 and 6 (resp.). Since $V(q,g,\Delta) = \emptyset$, these are disjoint and $Z_q \cup Z_\Delta = V(g,F_{11})$.

We claim that $Z_\Delta$ is not contained in a conic. If it were, this conic together with a line $L$ through any length 2 subscheme of $Z_q$ is a cubic curve through a subscheme of length 8 in $V(g,F_{11})$. By the Cayley-Bacharach Theorem, this cubic contains all of $V(g,F_{11})$. Hence $L$ contains $Z_q$. But this is impossible since $Z_q$ is a length 3 subscheme of the smooth conic $V(q)$. 10
Consider now the space of cubics in $\mathbb{C}[x_1, x_2, x_3]_3$ vanishing on $Z_\Delta$. This space is 4-dimensional. We extend $F_{11}$ and $F_{12} := g$ to a basis $\{F_{11}, F_{12}, F_{13}, F_{14}\}$ of that linear space. For each $2 \leq j \leq k \leq 4$, the polynomial $F_{1j}F_{1k}$ vanishes to order two on $Z_\Delta$ and hence lies in $\langle F_{11}, \Delta \rangle$. We can find a cubic $F_{jk} \in \mathbb{C}[x_1, x_2, x_3]_3$ and a conic $q_{jk} \in \mathbb{C}[x_1, x_2, x_3]_2$ satisfying

$$F_{1j}F_{1k} = F_{11}F_{jk} + q_{jk}\Delta.$$ 

Let $F$ be the symmetric matrix of cubics $(F_{jk})$. By construction, the $2 \times 2$ minors of $F$ lie in $\langle \Delta \rangle$. It follows that $\Delta^2$ divides the $3 \times 3$ minors of $F$, and $\Delta^3$ divides the determinant of $F$. Since both $\Delta^3$ and $\det(F)$ have degree 12, we have $\det(F) = c \cdot \Delta^3$ for some constant $c \in \mathbb{C}$. The fact that $Z_\Delta$ is not contained in a conic ensures that $c \neq 0$, so we get a determinantal representation for $X$. This was proved by Dixon [7]. It is also featured in [14, Theorem 2.3].

Now consider the adjoint matrix $F^{\text{adj}}$ whose entries are the cofactors of $F$. These entries have degree nine and are divisible by $\Delta^2$. Dividing by $\Delta^2$, we obtain the $4 \times 4$ matrix

$$M = \left(1/\Delta^2\right) \cdot F^{\text{adj}}$$

with linear entries $m_{jk}$. A calculation (or the proof of [15, Theorem 4.6]) shows that

$$\det(M) = c^3 \cdot \Delta, \quad M^{\text{adj}} = c^2 \cdot F, \quad \text{and} \quad \det(M_{34}) = c \cdot q$$

where $M_{34}$ is the $2 \times 2$ submatrix of $M$ with rows and columns $\{3, 4\}$. In particular, $(M^{\text{adj}})_{11} = c^2 \cdot F_{11}$, $(M^{\text{adj}})_{22} = c^2 \cdot F_{22}$, and $(M^{\text{adj}})_{12} = c^2 \cdot g$. Now consider the matrix

$$A(x) = \begin{bmatrix} m_{11} & cx_0 + m_{12} & m_{13} & m_{14} \\ cx_0 + m_{12} & m_{22} & m_{23} & m_{24} \\ m_{13} & m_{23} & m_{33} & m_{34} \\ m_{14} & m_{24} & m_{34} & m_{44} \end{bmatrix}.$$ (3.3)

The determinant of $A(x)$ equals

$$-\det(M_{34}) \cdot (cx_0)^2 + 2(M^{\text{adj}})_{12} \cdot (cx_0) + \det(M) = c^3 \cdot (-q x_0^2 + 2gx_0 + \Delta) = c^3 \cdot f,$$

Since $c \neq 0$, this determinantal representation of $c^3f$ shows that $V(f)$ is a symmetroid.

$(1.3.3 \Leftarrow)$ Suppose that $f$ is real. Then $F_{12}$ and $\Delta$ are real. If, in addition, the ramification cubic $F_{11}$ is real, then the ideal $\langle F_{11}, \Delta \rangle$ is defined over $\mathbb{R}$. Thus all cubics $F_{jk}$ can be taken in $\mathbb{R}[x_1, x_2, x_3]$. It follows that $c \in \mathbb{R}$, and (3.3) gives a real determinantal representation, up to sign, of $f$. Furthermore, we see that $A(p) = A((1:0:0:0))$ is not semidefinite.

$(1.3.2 \Leftarrow)$ Suppose that the ramification cubics $F_{11}, F_{22}$ are complex conjugates. This case is more delicate. Up to real rescaling of $F_{11}$ and $F_{22}$, we only know that $\pm F_{11}F_{22}$ equals the discriminant $F_{12}^2 + q\Delta$. Suppose $-F_{11}F_{22} = F_{12}^2 + q\Delta$. Then $-q\Delta$ is a sum of squares:

$$-q\Delta = F_{12}^2 + F_{11}F_{22} = F_{12}^2 + (\text{Re}(F_{11}))^2 + (\text{Im}(F_{11}))^2.$$
This implies that \( -q \) and \( \Delta \) are both nonpositive or both nonnegative. But this is not possible since the conic \( C_p = V(q) \) has real points. Therefore we can assume \( F_{11}F_{22} = F_{12}^2 + q\Delta \).

In the algorithm above, we can then chose \( F_{1j} \) and \( F_{2j} \) to be complex conjugates, and we can choose \( F_{33}, F_{34}, F_{44} \) to be real. Taking the adjoint of \( F \) and dividing by \( \Delta^2 \) results in a matrix \( M = (m_{jk}) \) with the same real structure, namely that conjugation induces the involution \( (1 \leftrightarrow 2) \) in the indices of the entries \( m_{jk} \). Conjugating (3.3) by an appropriate complex matrix produces the following real determinantal representation of \( f \):

\[
\begin{bmatrix}
2cx_0 + m_{11} + m_{22} + 2m_{12} & i(m_{11} - m_{22}) & m_{13} + m_{23} & m_{14} + m_{24} \\
i(m_{11} - m_{22}) & 2cx_0 - m_{11} - m_{22} + 2m_{12} & i(m_{13} - m_{23}) & i(m_{14} - m_{24}) \\
m_{13} + m_{23} & i(m_{13} - m_{23}) & m_{33} & m_{34} \\
m_{14} + m_{24} & i(m_{14} - m_{24}) & m_{34} & m_{44}
\end{bmatrix}.
\tag{3.4}
\]

This symmetric matrix is real, and it is semidefinite at \( p = (1 : 0 : 0 : 0) \).

(1.3.1 \( \Longleftrightarrow \)) This is immediate from the statements (1.3.2 \( \Longleftrightarrow \)) and (1.3.3 \( \Longleftrightarrow \)).

This concludes our proof of Theorem 1.2. We shall see a refinement in Proposition 4.6.

**Corollary 3.1.** In the situation of Theorem 1.2, the nine intersection points of the cubics \( R_1 \) and \( R_2 \) are precisely the images of the rank-2 nodes on the symmetroid other than \( p \).

**Proof.** A transversal symmetroid has exactly 10 nodes, all of rank 2. The nodes distinct from \( p \) are all mapped to singular points of the sextic \( R_p \). These are the intersection points of the two components \( R_1 \) and \( R_2 \). Since any symmetroid is a limit of transversal symmetroids, the rank-2 nodes are always mapped by \( \pi_p(C) \) to \( R_1 \cap R_2 \), provided \( p \) itself is a rank-2 node.

There exist nodal quartic symmetroids with more than ten nodes. For instance, the Kummer symmetroids in Section 5 have 16 nodes. Six of these have rank 3. Here each of the cubics \( R_1 \) and \( R_2 \) factors into three lines, so \( R_1 \cup R_2 \) has 15 singular points, but \( |R_1 \cap R_2| = 9 \).

For a transversal quartic symmetroid, the representation (1.1) is unique up to conjugation; for a proof see e.g. [1, Proposition 11]. However, if the symmetroid is nodal, but not transversal, then several inequivalent determinantal representations can exist. Each has ten rank-2 nodes, and other nodes of rank 3. For the Kummer symmetroid, the six rank-3 nodes lie on a plane in \( \mathbb{CP}^3 \), and there are 16 such planes. This gives 16 inequivalent determinantal representations. Furthermore, every node has rank 2 in some determinantal representation. There exist other symmetroids, with exactly 11 nodes, where one node \( p \) has rank 3 in every symmetric determinantal representation. If we project from such a node \( p \), then the ramification curve \( R_p \) is a sextic that cannot be decomposed into two cubic curves.

The (\( \Longleftrightarrow \)) direction in the proof above constitutes an algorithm for computing the unique determinantal representation of a transversal symmetroid from its quartic \( f \). We illustrate this algorithm with an example. An alternative algorithm based on syzygies is given in [1, §5].
Example 3.2. The surface $X = V(f)$ shown in Figure 3 is given by the quartic polynomial
\[ f = -q x_0^2 + 2 g x_0 + \Delta, \quad \text{where} \quad q = x_1^2 - x_2^2 - x_3^2, \quad g = 8 x_3^3 - 6 x_1^2 x_3, \quad \text{and} \]
\[ \Delta = x_1^4 - 41 x_1^2 x_2^2 + 16 x_2^4 + 12 x_1^3 x_3 - 36 x_1 x_2 x_3^2 - 5 x_1^2 x_3^2 + 44 x_2^2 x_3^2 - 36 x_1 x_3^3 + 28 x_3^4. \]
The ramification locus from the node $p = (1 : 0 : 0 : 0)$ is the product $F_{11} F_{22}$ of the cubics
\[ F_{11} = x_1^3 + 6 x_1^2 x_2 - 3 x_1 x_2^2 - 4 x_2^3 + 6 x_1^2 x_3 - 6 x_2 x_3^2 - 3 x_1 x_3^2 - 12 x_2 x_3^2 - 6 x_3^3, \quad \text{and} \]
\[ F_{22} = x_1^3 - 6 x_1^2 x_2 - 3 x_1 x_2^2 + 4 x_2^3 + 6 x_1^2 x_3 - 6 x_2 x_3^2 - 3 x_1 x_3^2 + 12 x_2 x_3^2 - 6 x_3^3. \]
We check that $F_{11} F_{22} - g^2 = q \Delta$. The ideal $\sqrt{(F_{11}, \Delta)}$ contains a 4-dimensional space of cubics. We extend $F_{11}$ and $F_{12} = g$ to a basis $\{F_{11}, F_{12}, F_{13}, F_{14}\}$ of this linear space where
\[ F_{13} = 3 x_1 x_2 x_3 + 12 x_2^2 x_3 - 9 x_1 x_3^2 + 18 x_2 x_3^2 + 10 x_3^3, \quad \text{and} \]
\[ F_{14} = x_1^2 x_2 + 7 x_1 x_2^2 + 4 x_2^3 - 18 x_1 x_3^2 + 23 x_1 x_3^2 - 32 x_2 x_3^2 - 26 x_3^3. \]
Then, for example, the product $F_{12} F_{13}$ lies in the ideal $(F_{11}, \Delta)$, and we can write it as
\[ \frac{1}{4} (-x_1^3 + 45 x_1 x_2^2 - 28 x_1^2 - 6 x_1^3 x_3 - 36 x_1 x_2 x_3^2 + 42 x_2^2 x_3^2 + 33 x_1 x_3^3 - 36 x_2 x_3^2 - 30 x_3^3) F_{11} + \frac{1}{4} (x_1^2 + 6 x_1 x_2 - 7 x_2^2 + 5 x_3^2) \Delta. \]
We set $F_{23}$ to be the coefficient of $F_{11}$. Similarly, we find $F_{jk}$ for $2 \leq j \leq k \leq 4$. The determinant of the matrix of cubics $F = (F_{jk})_{jk}$ is $(9/16) \cdot \Delta^3$. Taking the adjoint of the $F$ and dividing by $\Delta^2$ gives a matrix whose determinant is $a (9/16)^3 \Delta$. Adding the appropriate matrix $x_0 A_0$, as in (3.3), gives a determinantal representation of $(9/16)^3 \cdot f$:
\[ \begin{bmatrix} 18 x_1 - 108 x_2 + 108 x_3 & 18 x_0 + 114 x_3 & 24 x_3 - 72 x_2 & -36 x_2 \\ 18 x_0 + 114 x_3 & 19 x_1 + 121 x_2 + 108 x_3 & 4 x_1 + 28 x_2 + 60 x_3 & 30 x_3 \\ 24 x_3 - 72 x_2 & 4 x_1 + 28 x_2 + 60 x_3 & 160 x_1 - 128 x_2 - 96 x_3 & 72 x_1 - 72 x_2 - 24 x_3 \\ -36 x_2 & 30 x_3 & 72 x_1 - 72 x_2 - 24 x_3 & 36 x_1 - 36 x_2 \end{bmatrix}. \]

4 The view from a node

We now take a closer look at the projection of a quartic spectrahedron $S$ from a real node $p$ on its symmetroid $X$. The tangent cone of $X$ at $p$ is a non-empty quadratic cone in $\mathbb{R}P^3$. It is defined by the determinant of a symmetric $2 \times 2$ matrix of real linear forms. A point $q \in \mathbb{R}P^3$ is inside that cone if the projection of the cone from $q$ is ramified only at its apex $p$, while $q$ is outside the cone if the projection from $q$ is ramified along the union of two lines.

Proposition 4.1. Let $S$ be a transversal quartic spectrahedron, fix a rank-2 node $p$ on its symmetroid $X$, and let $C_p$ be the image of the tangent cone under $\pi_p(\mathbb{R})$. Suppose no line through $p$ lies in $X$. Then each point in $S$ lies inside the tangent cone of $X$ at $p$. Furthermore:
(a) If \( p \in S \), then the image of \( S \) in \( \mathbb{RP}^2 \) is the convex hull of the conic \( C_p \). Every other node in \( \partial S \) is inside the cone and every node in \( X \setminus S \) is outside the cone.

(b) If \( p \in X \setminus S \), then the image of \( S \) is the intersection of the ovals of the ramification cubics, both contained in the interior of the conic \( C_p \). Every node in \( \partial S \) is mapped to the boundary of this convex set. Each node in \( X \setminus S \) is mapped to a point outside \( C_p \).

**Proof of Proposition 4.1.** Let \( p \) be a node of \( X \). After a change of coordinates, we can take \( p = (1:0:0:0) \), and \( X \) has a real determinantal representation \( A(x) \) given in (3.3) or (3.4), where \( m_{jk} \) are linear forms in \( x_1, x_2, x_3 \). In either case, the conic \( C_p \) is defined by the principal minor \( q = m_{33}m_{44} - m_{23}^2 \). For any point \( (e_0, e) \) in the spectrahedron \( S \), the matrix \( A(e_0, e) \) is positive definite and thus its principal minor \( q \) is positive at \( (e_0, e) \). So, if there exists \( e_0 \in \mathbb{R} \) for which \( (e_0, e) \in S \) then \( q(e) \geq 0 \). This means that the image of the spectrahedron \( S \) is a convex set contained in the convex hull of the conic \( C_p \), namely \( \{ e \in \mathbb{RP}^2 : q(e) \geq 0 \} \).

If \( p \in S \) then \( X \) has a real representation (3.4). If \( q(e) \geq 0 \) then the \( 2 \times 2 \) matrix defining \( q \) is semidefinite. Taking \( e_0 \) sufficiently large makes the matrix (3.4) definite at the point \( (e_0, e) \). Thus the projection of \( S \) is exactly the convex hull of \( C_p \). Furthermore, any line through \( p \) passing through the interior of \( S \) contains another point of the boundary \( \partial S \), at which the line leaves the spectrahedron \( S \). Thus if a line joining \( p \) with another node \( q \in X \) passes through \( S \) then \( q \) must lie in \( \partial S \). These are the only intersections of the line with \( X \).

If \( p \notin S \) then the ramification locus is a pair of real cubic curves totally tangent to the conic \( C_p \). By Proposition 4.6 below, each of these cubics has an oval that the conic \( C_p \) interlaces. Furthermore, the image of the spectrahedron \( S \) is precisely the intersection of the convex hull of these two ovals. Any line through \( p \) passing through the interior of \( S \) has to contain two points in \( \partial S \), both entering and exiting \( S \). So, if a line joining \( p \) with another node \( q \) passes through the spectrahedron, then \( q \in S \) and the line has no other points in \( S \).
corresponding loop of matrices in \( SO_\gamma \) have symmetric matrices contains a non-zero matrix with a multiple eigenvalue. In particular, a result of Friedland et al. on spheres. In order to be self-contained, we include an elementary proof for our special case.

Proof of double eigenvalues: Suppose that for each non-zero \( x = (x_0, x_1, x_2) \), the matrix \( x_0A_0 + x_1A_1 + x_2A_2 \) has four distinct real eigenvalues \( \lambda_1(x) > \lambda_2(x) > \lambda_3(x) > \lambda_4(x) \). Let \( V(x) = (v_1(x), v_2(x), v_3(x), v_4(x)) \) denote the \( 4 \times 4 \) rotation matrix whose rows are the corresponding eigenvectors of unit length. These are defined up to sign. Since \( \mathbb{R}^3 \setminus \{0\} \) is simply connected, we can assume that the \( v_i(x) \) depend continuously on \( x \) and that \( v_1(-x) = v_4(x), v_2(-x) = v_3(x) \) for all \( x \in \mathbb{S}^2 \). We will show that this is impossible.

Consider the closed loop \( \eta(t) = (\cos(2\pi t), \sin(2\pi t), 0) \) in \( \mathbb{S}^2 \), and let \( \gamma(t) = V(\eta(t)) \) be the corresponding loop of matrices in \( SO(4) \). Since \( \eta \) is contractible, also \( \gamma \) is contractible. We have \( \gamma(t + \frac{1}{2}) = J \cdot \gamma(t) \) for all \( t \in [0, \frac{1}{2}] \), where \( J \) is the permutation matrix that reverses the order of the rows of \( \gamma(t) \). We derive a contradiction by showing that \( \gamma \) is not contractible.

S. Thus the intersection points of the two cubic ovals are the images of the spectrahedral nodes, inside \( C_p \). Since the conic interlaces the two cubics, the only other intersections of the two cubics is between their pseudolines, and these necessarily occur outside \( C_p \).

We are now prepared to complete our new proof of the Degtyarev-Itenberg Theorem.

**Proof of Theorem 1.1** Let \( X = V(f) \) be a very real symmetroid whose spectrahedron \( S \) is non-empty. Write \( \mathcal{N} \) for the set of real nodes in \( S \). We claim that \( |\mathcal{N}| \) is even. If all real nodes of \( X \) are in \( S \), we are done, since non-real nodes come in conjugate pairs. We may thus assume that \( X \) has at least one real \((1,1)\)-node \( p \). It suffices to show that \(|\pi_p(\mathcal{N})| \) is even.

By Theorem 1.2 the ramification locus of \( \pi \) is the union \( R_1 \cup R_2 \) of two real cubics. By perturbing the symmetric matrices \( A_i \) in \( f(x) = \det(A(x)) \), we may assume that the cubics are smooth and intersect transversely. In particular, we may assume that \( X \) belongs to the open set of transversal symmetroids that contains no lines. By Proposition 1.1 the image \( \pi(S) \) of the spectrahedron is bounded by the ovals of the cubics \( R_1 \) and \( R_2 \).

Furthermore, \( \pi(\mathcal{N}) \) is the set of intersection points of the ovals of \( R_1 \) and \( R_2 \). But these intersect an even number of times, by the Jordan curve theorem. Thus \(|\mathcal{N}| \) is even.

The following lemma now implies Theorem 1.1.

**Lemma 4.2.** Every quartic symmetroid with non-empty spectrahedral region has a real node.

**Proof.** After conjugating by an appropriate matrix, we may assume that the identity matrix is in the spectrahedron \( S \), i.e., \( f(x) = \det(A(x)) \) where \( A(x) = x_0A_0 + x_1A_1 + x_2A_2 + x_3I \). By a result of Friedland et al. [9, Theorem B], every 3-dimensional real vector space of \( 4 \times 4 \) symmetric matrices contains a non-zero matrix with a multiple eigenvalue. In particular, some linear combination \( A = c_0A_0 + c_1A_1 + c_2A_2 \) has a double eigenvalue \( \lambda \). Since \( \lambda \) is real, \( \lambda I - A \) has rank 2. This corresponds to a real node on the symmetroid \( X \).

The proof of [9, Theorem B] is based on general results by Adams concerning vector fields on spheres. In order to be self-contained, we include an elementary proof for our special case.

**Proof of double eigenvalues:** Suppose that for each non-zero \( x = (x_0, x_1, x_2) \), the matrix \( x_0A_0 + x_1A_1 + x_2A_2 \) has four distinct real eigenvalues \( \lambda_1(x) > \lambda_2(x) > \lambda_3(x) > \lambda_4(x) \). Let \( V(x) = (v_1(x), v_2(x), v_3(x), v_4(x)) \) denote the \( 4 \times 4 \) rotation matrix whose rows are the corresponding eigenvectors of unit length. These are defined up to sign. Since \( \mathbb{R}^3 \setminus \{0\} \) is simply connected, we can assume that the \( v_i(x) \) depend continuously on \( x \) and that \( v_1(-x) = v_4(x), v_2(-x) = v_3(x) \) for all \( x \in \mathbb{S}^2 \). We will show that this is impossible.

Consider the closed loop \( \eta(t) = (\cos(2\pi t), \sin(2\pi t), 0) \) in \( \mathbb{S}^2 \), and let \( \gamma(t) = V(\eta(t)) \) be the corresponding loop of matrices in \( SO(4) \). Since \( \eta \) is contractible, also \( \gamma \) is contractible. We have \( \gamma(t + \frac{1}{2}) = J \cdot \gamma(t) \) for all \( t \in [0, \frac{1}{2}] \), where \( J \) is the permutation matrix that reverses the order of the rows of \( \gamma(t) \). We derive a contradiction by showing that \( \gamma \) is not contractible.
Let $S^3 \subset \mathbb{H} = \{a+bi+cj+dk\}$ denote the group of unit quaternions. The homomorphism \( \pi : S^3 \times S^3 \to SO(4) = SO(\mathbb{H}) \) given by \( \pi(p,q) = (v \mapsto pvq^{-1}) \) is a double covering, and it identifies \( SO(4) \) with \( S^3 \times S^3/\pm (1,1) \) (see e.g., [11, p. 294]). Furthermore, the identity
\[
j(a + bi + cj + dk)i^{-1} = d + ci + bj + ak
\]
shows that the involution \( J \) corresponds to left multiplication by the element \((j,i) \in S^3 \times S^3 \).
In particular, its square \((j,i)^2 = (-1,-1)\) is in the kernel of \( \pi \).

Since \( S^3 \times S^3 \) is simply connected, the loop \( \gamma \) lifts to a path \( \tilde{\gamma} : [0,1] \to S^3 \times S^3 \). The endpoint \( \tilde{\gamma}(1) \) must map to \( \gamma(0) = \gamma(1) \), so \( \tilde{\gamma}(1) = (j,i)^k \cdot \tilde{\gamma}(0) \) for some \( k \in \{0,2\} \). In fact, this \( k \) is a homotopy invariant of \( \gamma \) (by [11, Prop. 1.30]). Since \( \gamma(t+\frac{1}{2}) = J \cdot \gamma(t) \) for \( t \in [0,\frac{1}{2}] \) and \( J \cdot \gamma(0) \neq \gamma(0) \), the lift of \( \gamma \) satisfies \( \tilde{\gamma}(\frac{1}{2} + t) = (j,i)^m \cdot \tilde{\gamma}(t) \) for some \( m \in \{1,3\} \). Hence
\[
\tilde{\gamma}(1) = (j,i)^m \cdot \tilde{\gamma}(\frac{1}{2}) = (j,i)^{2m} \cdot \tilde{\gamma}(0) = (j,i)^2 \cdot \tilde{\gamma}(0) = -\tilde{\gamma}(0).
\]
But, \( \gamma \) being contractible implies \( \tilde{\gamma}(0) = \tilde{\gamma}(1) \). This contradiction completes the proof.

**Remark 4.3.** For cubic symmetroids, we can argue in a similar way: If \( x_0A_0 + x_1A_1 + x_2A_2 \) has distinct real eigenvalues for every \( x = (x_0, x_1, x_2) \), we may choose linearly independent orthonormal eigenvectors \( v_1(x), v_2(x), v_3(x) \), so that \( v_1(-x) = v_3(x) \) and \( v_2(-x) = -v_2(x) \). Let \( J \in SO(3) \) be the corresponding involution on the \( v_i \). Fix the group \( S^3 \) of unit quaternions. There is a double covering \( \pi : S^3 \to SO(3) \) which identifies \( SO(3) \) with \( S^3/\pm 1 \). Explicitly, \( \pi(q) = (v \mapsto qvq^{-1}) \), where \( v = ai + bj + ck \). Under this identification, \( J \) corresponds to left multiplication by \( \frac{1}{\sqrt{2}}(i+k) \in S^3 \). If we define the loop \( \gamma : [0,1] \to SO(3) \) as above, it lifts to a path \( \tilde{\gamma} \) in \( S^3 \) which satisfies \( \tilde{\gamma}(1) = (\frac{1}{\sqrt{2}}(i+k))^2 \tilde{\gamma}(0) = -\tilde{\gamma}(0) \). Again, this implies that \( \gamma \) is not contractible and so the symmetroid has a real node.

**Example 4.4.** The hypothesis that the spectrahedron is non-empty is essential in Lemma 4.2. Consider the symmetroids, of degree 3 and 4 respectively, given by the symmetric matrices
\[
\begin{bmatrix}
x & y & z \\
y & z & w \\
z & w & -x
\end{bmatrix}
\quad \text{and} \quad
\begin{bmatrix}
x & y & z & w \\
y & z & -x & w \\
z & -x & -w & z \\
w & w & z & -y
\end{bmatrix}.
\]
These two symmetroids have no real nodes. They lie in \( S_{\text{veryreal}} \setminus S_{\text{spec}} \). 

Theorem 1.1 concerns transversal spectrahedral symmetroids. These have ten rank-2 nodes as singularities. Non-transversal spectrahedral symmetroids have similar constraints.

**Proposition 4.5.** A real singular point on a spectrahedral quartic symmetroid has rank \( \leq 2 \).
The multiplicity of a root equals the multiplicity of the corresponding intersection point in \( L \cap X \). Since \( p \in \text{Sing}(X) \), the root \( \lambda = 0 \) has multiplicity at least 2. This means \( \text{corank}(A(p)) \geq 2 \), and hence \( \text{rank}(A(p)) \leq 2 \).

The spectrahedral hypotheses in Proposition \([4,5]\) is necessary. This can be seen from Theorem \([5,6]\) below: if the univariate polynomial \( p \in \mathbb{R}[t] \) is positive, then the spectrahedron \( \text{Gram}(p) \) is non-empty and its symmetroid has six complex nodes of rank 3; otherwise, \( \text{Gram}(p) \) is empty and the symmetroid can have up to six real nodes of rank 3.

Our next topic is the derivation of the interlacing property that was used in the proof of Proposition \([4,1]\). Let \( f(x) = \det(A(x)) \) and \( e \in \mathbb{R}^4 \) in the interior of the spectrahedron \( S = S(f) \), so \( A(e) \) is a definite matrix. Then, for every \( x \in \mathbb{R}^4 \), all roots of the univariate polynomial \( f(te + x) \in \mathbb{R}[t] \) are real. A cubic polynomial \( h(x) \) interlaces the quartic \( f(x) \) with respect to \( e \) if, for each \( x \in \mathbb{R}^4 \), the three roots \( \beta_1, \beta_2, \beta_3 \) of the polynomial \( h(te + x) \) are real and interlace the roots \( \alpha_1 \leq \alpha_2 \leq \alpha_3 \leq \alpha_4 \) of \( f(te + x) \). By this we mean

\[
\alpha_1 \leq \beta_1 \leq \alpha_2 \leq \beta_2 \leq \alpha_3 \leq \beta_3 \leq \alpha_4.
\]

Theorem 3.3 of \([15]\) states that the matrix \( A(e) \) is definite if and only if the diagonal cofactors of the matrix \( A(x) \) interlace \( f \) with respect to the point \( e \). In our case, the ramification cubics are such diagonal cofactors. This allows us to add to our extension of Cayley’s Theorem.

**Proposition 4.6.** Let \( p \) be a \((1,1)\)-node on a very real quartic symmetroid \( X = V(f) \) with ramification \( R_1 \cup R_2 \) and no line on \( X \) through \( p \). Let \( C_p \) be the real conic totally tangent to \( R_1 \cup R_2 \). The spectrahedron \( S \) is non-empty if and only if the conic \( C_p \) interlaces the two ramification cubics \( R_1 \) and \( R_2 \) with respect to a common point. In this case the image of \( S \) under projection from \( p \) is the intersection of the convex hull of the ovals of \( R_1 \) and \( R_2 \).

**Proof.** \((\Rightarrow)\) We write \( f \) in the form \([3,1]\) over \( \mathbb{R} \). The ramification cubics \( R_1 \) and \( R_2 \) are the cofactors \( F_{11} \) and \( F_{22} \). Let \( e \in \mathbb{R}P^2 \) be an interior point in the image of the spectrahedron \( S \) under projection from \( p \). For some \( e_0 \in \mathbb{R} \) the point \((e_0, e)\) lies in the interior of \( S \) in \( \mathbb{R}P^3 \). Then the \( 3 \times 3 \) submatrix defined by the rows and columns \( \{2, 3, 4\} \) is also positive definite at \( e \) and the quadric \( q \) defining \( C_p \) is a diagonal cofactor of this matrix. By \([15]\), Theorem 3.3], the conic \( q \) interlaces the \( 3 \times 3 \) determinant \( F_{11} \) with respect to \( e \). Taking instead the \( 3 \times 3 \) principal submatrix indexed by \( \{1, 3, 4\} \), we see that \( C_p \) interlaces \( R_2 \).
(⇐) Let \( p = (1 : 0 : 0 : 0) \) and suppose that \( C_p \) interlaces both \( R_1 \) and \( R_2 \) with respect to \( e \in \mathbb{R}^3 \). Certainly, \( C_p, R_1, \) and \( R_2 \) then have real points. Theorem 1.2 says that \( V(f) \) is very real and \( p \) is a \((1,1)\)-node. Its proof gave a real determinantal representation \( A(x) \), up to sign, for \( f \) via \emph{[3,3]}. It also produced a symmetric 4×4 matrix \( M(x) \) with linear entries in \( \mathbb{R}[x_1, x_2, x_3] \) such that \( R_1 = V((M^{\text{adj}})_{11}), R_2 = V((M^{\text{adj}})_{22}), \) and \( C_p = V(\det(M_{34})) \). By the interlacing hypothesis and \emph{[15] Theorem 3.3}, the two principal 3×3 submatrices of \( M \) indexed by \( \{2, 3, 4\} \) and \( \{1, 3, 4\} \) are both definite at \( e \). Since these two definite submatrices of \( M(e) \) share a 2×2 diagonal block, they are either both positive definite or both negative definite. Without loss of generality we take them to be positive definite. In particular, both of the 3×3 determinants \((M^{\text{adj}})_{11} \) and \((M^{\text{adj}})_{22} \) are positive at the point \( e \).

Consider the matrix \( A(x) \) given in \emph{[3,3]}, where \( m_{jk} \) is the \((j,k)\)-th entry of \( M(x) \). We will show that, for some \( e_0 \in \mathbb{R} \), the matrix \( A(e_0, e) \) is positive definite. Using the notation in the proof of Theorem 1.2 the quadratic polynomial \( \det(A(x_0, e)) \in \mathbb{R}[x_0] \) equals

\[
\det(A(x_0, e)) = c^3 \cdot (-q(e) x_0^2 + 2g(e) x_0 + \Delta(e)). \tag{4.1}
\]

Its discriminant is positive:

\[
4g(e)^2 + 4q(e)\Delta(e) = 4 \cdot (M^{\text{adj}}(e))_{11} \cdot (M^{\text{adj}}(e))_{22} > 0.
\]

Thus, the quadratic (4.1) changes signs, and it is positive at some point \( x_0 = e_0 \in \mathbb{R} \). The matrix \( A(e_0, e) \) is positive definite. Indeed, the lower 3×3 submatrix is the same as that of \( M(e) \). Thus, the principal minors indexed by \( \{4\}, \{3, 4\} \) and \( \{2, 3, 4\} \) are all positive at \( (e_0, e) \). Since the determinant is positive as well, the matrix \( A(e_0, e) \) is positive definite.

The above argument shows that for \( e \in \mathbb{R}^3 \), there exists \( e_0 \in \mathbb{R} \) so that the matrix \( A(e_0, e) \) is definite if and only if the principal 3×3 submatrices defining \( R_1 \) and \( R_2 \) are both definite at \( e \). Thus the projection of the spectrahedron \( S \) is precisely the intersection of the two cubic spectrahedra bounded by the ovals of \( R_1 \) and \( R_2 \). This gives the last statement.

In our discussion so far we have disallowed lines through the projection node on \( X \). We close Section 4 with a discussion of symmetroids with lines, and non-transversal symmetroids.

**Lemma 4.7.** Let \( L \) be a line in a nodal quartic symmetroid \( X \). Then \( X \) has three nodes on \( L \), and all three nodes have rank 2. Furthermore, if \( X \) is very real, then either all three are \((1,1)\)-nodes or one is a \((1,1)\)-node and the other two are \((2,0)\)-nodes.

**Proof.** The matrices in the pencil parameterized by \( L \) all have rank \( \leq 3 \), so they must have a share a common kernel vector. The discriminant of the pencil is a cubic form that vanishes where the matrices has rank at most 2. Geometrically, this cubic form defines the common intersection of the cubic curves residual to the line \( L \) in plane sections of \( X \). Furthermore, for a node the singularity of the general plane section through the line is also nodal. Thus,
if $X$ is nodal, the general residual cubic curve must intersect the line transversally at three points, and each point is a rank 2 node on $X$. If $X$ is very real, one of the eigenvalues of the matrices parameterized by $L$ changes sign at each node, so if there is a semidefinite rank 3 point on the line, there are exactly two semidefinite rank 2 node, otherwise all three are $(1,1)$-nodes.

Corollary 4.8. Let $X$ be a transversal spectrahedral quartic symmetroid that contains a real line $L$. Let $p$ be a real node on $L$. Then the two cubic ramification curves $R_1$ and $R_2$ under the projection from $p$ intersect on the conic $C_p$, the image of the tangent cone.

Proof. A line through a real node $p$ in a nodal symmetroid lies in the tangent cone at the node. Here, the conic $C_p$ contains the image of the other two rank 2-nodes on this line.

5 Spectrahedral treats

This section features three special families of spectrahedra. Their names were chosen to highlight the connection between convex optimization [2] and classical algebraic geometry [8]. Toeplitz spectrahedra have a curve of singular points in their boundary. Sylvester spectrahedra are transversal but contain 10 lines in their symmetroids. Kummer spectrahedra are nodal but not transversal. Their characterization in Theorem 5.6 may be of independent interest.

Example 5.1. The Toeplitz spectrahedron is the following convex set in affine 3-space:

\[
\left\{(x, y, z) \in \mathbb{R}^3 : \begin{bmatrix} 1 & x & y & z \\ x & 1 & x & y \\ y & x & 1 & x \\ z & y & x & 1 \end{bmatrix} \succeq 0 \right\}.
\] (5.1)
The determinant of the given $4 \times 4$-matrix factors as
\[(x^2 + 2xy + y^2 - xz - x - z - 1)(x^2 - 2xy + y^2 - xz + x + z - 1).\]

The Toeplitz spectrahedron ([5,1]) is the convex hull of the cosine moment curve
\[\{(\cos(\theta), \cos(2\theta), \cos(3\theta)) : \theta \in [0, \pi]\}.\]

The curve and its convex hull are shown on the left in Figure 6. The two endpoints, $(x, y, z) = (1, 1, 1)$ and $(x, y, z) = (-1, 1, -1)$, correspond to rank 1 matrices. All other points on the curve have rank 2. To construct the Toeplitz spectrahedron geometrically, we form the cone from each endpoint over the cosine curve, and we intersect these two quadratic cones. The two cones intersect along this curve and the line through the endpoints of the cosine curve.

Shown on right in Figure 6 is the dual convex body. It is the set of trigonometric polynomials $1 + a_1 \cos(\theta) + a_2 \cos(2\theta) + a_3 \cos(3\theta)$ that are nonnegative on $[0, \pi]$. This convex body is not a spectrahedron because it has a non-exposed edge (cf. [2, Exercise 6.13]).

In the earlier sections we focused on quartic spectrahedra that are transversal, given by generic symmetric matrices $A_0, A_1, A_2, A_3$, so they have precisely 10 nodes. Theorem 1.1 reveals their distribution on and off the spectrahedron. Toeplitz spectrahedra are far from being transversal. They are obtained as the intersection of two quadratic cones. Typically, symmetroids that are defined in this manner contain no rank-1 matrices, but the set of rank-2 matrices is an entire curve. This curve is the singular locus of the symmetroid, and it is generally a quartic curve of genus one. The spectrahedron is the convex hull of that curve.

Figure 7: The pillow is bounded by an irreducible quartic surface.

**Example 5.2.** Figure 7 shows a spectrahedron that appears to be reducible, but it is not:

\[\{(x, y, z) \in \mathbb{R}^3 : \begin{bmatrix} 1 & x & 0 & x \\
 x & 1 & y & 0 \\
 0 & y & 1 & z \\
 x & 0 & z & 1 \end{bmatrix} \succeq 0 \} \]
This spectrahedron was featured in [2, §5.1.1] where it was called the pillow. This symmetroid is an irreducible quartic surface that is singular along two lines in the plane at infinity and in the four corners of the pillow. These four corners are coplanar and form the intersection of two pairs of parallel lines that lie in the symmetroid.

A Sylvester spectrahedron is the derivative, in the sense of Renegar [16] and Sanyal [17], of a 3-dimensional polytope $P$ defined by five linear inequalities. Using homogeneous coordinates, the inequalities are given by linear forms $\ell_1(x), \ell_2(x), \ell_3(x), \ell_4(x), \ell_5(x) \in \mathbb{R}[x_0, x_1, x_2, x_3]$. The symmetroid is the classical polar, with respect to any interior point of $P$, of the quintic $\{x \in \mathbb{C}P^3 : \ell_1(x)\ell_2(x)\ell_3(x)\ell_4(x)\ell_5(x) = 0\}$. Following [17, Theorem 1.1], we use the matrix

$$A(x) = \begin{bmatrix} \ell_1(x) + \ell_5(x) & \ell_2(x) & \ell_3(x) & \ell_4(x) \\ \ell_1(x) & \ell_2(x) + \ell_5(x) & \ell_3(x) & \ell_4(x) \\ \ell_1(x) & \ell_2(x) & \ell_3(x) + \ell_5(x) & \ell_4(x) \\ \ell_1(x) & \ell_2(x) & \ell_3(x) & \ell_4(x) + \ell_5(x) \end{bmatrix}$$

(5.3)

to define the Sylvester spectrahedron. If no four of the $\ell_i(x)$ are linearly dependent, and none of the five inequalities $\ell_i(x) \geq 0$ is redundant, then the polytope $P$ is a triangular prism. Figure 8 shows a Sylvester spectrahedron that is derived from a triangular prism $P$. 

Figure 8: Sylvester spectrahedron derived from a triangular prism and a nodal projection.

The name “Sylvester spectrahedron” is a reference to Sylvester’s Pentahedral Theorem. This theorem states that the polynomial defining a general cubic surface in $\mathbb{C}P^3$ admits a
unique representation, over the complex numbers, as a sum of five powers of linear forms:
\[
f(x) = \ell_1(x)^3 + \ell_2(x)^3 + \ell_3(x)^3 + \ell_4(x)^3 + \ell_5(x)^3.
\]
The Hessian \((\partial^2 f/\partial x_i \partial x_j)\) of this polynomial is the symmetric 4 \times 4-matrix \(\sum_{i=1}^5 \ell_i H_i\), where \(H_i\) is the rank-1 matrix \((\nabla \ell_i)^T(\nabla \ell_i)\). In suitable coordinates, this Hessian matrix is precisely the symmetric matrix \(A(x)\) given in (5.3). Its determinant is the quartic form
\[
\det(A(x)) = \left(\frac{1}{\ell_1(x)} + \frac{1}{\ell_2(x)} + \frac{1}{\ell_3(x)} + \frac{1}{\ell_4(x)} + \frac{1}{\ell_5(x)}\right) \ell_1(x)\ell_2(x)\ell_3(x)\ell_4(x)\ell_5(x).
\]

The Sylvester spectrahedron is transversal, i.e. its singularities exhibit the generic behavior. The corresponding Sylvester symmetroid in \(\mathbb{CP}^3\) has precisely ten nodes, namely the intersection points \(\{\ell_i(x) = \ell_j(x) = \ell_k(x) = 0\}\). All ten nodes are real, so \(\rho = 10\). However, the symmetroid also contains the ten lines \(\{\ell_i(x) = \ell_j(x) = 0\}\). Each line contains three of the nodes. Compare this to the derivative of a tetrahedron shown on the left in Figure 1.

Starting from a triangular prism \(P\), the Sylvester spectrahedron has the six vertices and nine edges in its boundary. These account for six of the nodes and nine of the lines. The remaining four nodes of the symmetroid are outside the spectrahedron. Thus \((\rho, \sigma) = (10, 6)\) in the notation of the census of transversal types in Section 2. The spectrahedron is shown in dark blue in Figure 8. It wraps around the polytope \(P\) and contains its edge graph.

The Sylvester symmetroid is the quartic surface in \(\mathbb{CP}^3\) defined the vanishing of the determinant (5.3). The projection of the surface from one of the nodes maps six nodes in pairs to three nodes of a triangle, and the remaining three nodes to the three intersection points of this triangle with a line. These six points in the plane are the only intersection points of the pair of cubics, the ramification curve of the projection. The two cubics are tangent at the nodes of the triangle, and there is a 4-dimensional family of such pair of cubics with a totally tangent conic, corresponding to the family of cubic forms with parameters \(\ell_1, \ldots, \ell_5\).

A perennial favorite among quartics in \(\mathbb{CP}^3\) is the Kummer surface. It is the quotient of an abelian surface by its involution, so it has 16 nodes, one for each 2-torsion point. All 16 nodes can be real, as seen in Figure 9. Looking at this figure, one may wonder whether the convex body seen in the center is a spectrahedron? We shall see that the answer is “no”.

Let \(\mathcal{K}\) denote the closure in the space \(\mathbb{CP}^{34}\) of all quartics, of the locus of all quartic Kummer surfaces in \(\mathbb{CP}^3\). The Kummer locus \(\mathcal{K}\) is an irreducible variety of dimension 18.

**Proposition 5.3.** The variety \(\mathcal{K}\) of Kummer surfaces lies in the variety \(\mathcal{S}\) of symmetroids.

**Proof.** The following representation of Kummer surfaces as symmetroids appears in equation (7) on page 143 in Section 41 of Coble’s book [4], where this is attributed to H.F. Baker:
\[
A(x) = \begin{bmatrix}
a_6x_3 & -3a_5x_3 & 3a_4x_3 + x_2 & -a_3x_3 - x_1 \\
-3a_5x_3 & 9a_4x_3 - 2x_2 & -9a_3x_3 + x_1 & 3a_2x_3 + x_0 \\
3a_4x_3 + x_2 & -9a_3x_3 + x_1 & 9a_2x_3 - 2x_0 & -3a_1x_3 \\
-a_3x_3 - x_1 & 3a_2x_3 + x_0 & -3a_1x_3 & a_0x_3
\end{bmatrix}.
\]
Consider the following sextic polynomial in one variable $t$:

$$p(t) = a_0 - 6a_1 t + 15a_2 t^2 - 20a_3 t^3 + 15a_4 t^4 - 6a_5 t^5 + a_6 t^6.$$  \hfill (5.5)

This polynomial is related to the determinantal representation $A(x)$ as follows:

$$x^3 p(t) = \begin{bmatrix} t^3 & t^2 & t & 1 \end{bmatrix} \cdot A(x) \cdot \begin{bmatrix} t^3 & t^2 & t & 1 \end{bmatrix}^T = \begin{bmatrix} t^3 & t^2 & t & 1 \end{bmatrix} \cdot A(x) \cdot \begin{bmatrix} t^3 & t^2 & t & 1 \end{bmatrix}^T. \hfill (5.6)$$

Suppose that $p(t)$ has six distinct complex roots $u_1, u_2, \ldots, u_6$. Then the symmetroid $\{ \det(A(x)) = 0 \}$ has 16 isolated nodes. Ten of these nodes correspond to matrices of rank 2, and we shall describe these below. The other six nodes are $(1 : u_i : u_i^2 : 0)$ and these correspond to rank 3 matrices. All six lie in the plane $\{ x_3 = 0 \}$, so this is one of the 16 planes in the $16_6$ configuration associated with the Kummer surface. The abelian surface corresponding to the Kummer surface $\{ \det(A) = 0 \}$ is the Jacobian of the genus 2 curve $y^2 = p(t)$, obtained as the double cover of $\mathbb{C}\mathbb{P}^1$ ramified at $u_1, u_2, u_3, u_4, u_5, u_6$. Since every smooth curve of genus 2 admits such a representation, and since their Jacobians (taken modulo involution) are dense in the space $\mathcal{K}$ of Kummer surfaces, it follows that $\mathcal{K} \subset \mathcal{S}$.  \hfill \Box

**Remark 5.4.** Kummer symmetroids have the following interpretation in terms of quadrics. Identifying symmetric matrices $A$ with quadrics $z^T A z$, the family $A(x)$ corresponds to a 4-dimensional vector space of quadrics $W$. The symmetroid is the subset $X \subset \mathbb{P}(W)$ parameterizing the singular members of the family. The Kummer symmetroids correspond to those vector spaces $W$ containing a 3-dimensional subspace $V$ whose quadrics define a twisted cubic curve. Indeed, if $X$ is a Kummer surface, then in the notation above, the quadrics of
The kernel of the map

\[ \psi = \langle A_0, A_1, A_2 \rangle \]
defines a twisted cubic curve; \( V = \langle z_2^2 - z_1 z_3, z_0 z_3 - z_1 z_2, z_1^2 - z_0 z_2 \rangle \). Conversely, given \( W \) with a vector subspace \( V \subset W \) defining a twisted cubic, the plane \( \mathbb{P}(V) \subset \mathbb{P}(W) \) intersects the symmetroid in a double conic \( \{ q^2 = 0 \} \). Now if \( \mathbb{P}(V) = \{ x_3 = 0 \} \) and the symmetroid is defined by \( x_3^2 + ax_3^3 + bx_3^2 + cx_3 + q^2 \), with \( a, b, c, q \in \mathbb{C}[x_0, x_1, x_2] \), then \( \{ x_3 = c = q = 0 \} \) defines the six rank 3-nodes on the symmetroid, and so \( X \) is Kummer.

A Kummer spectrahedron is an element of the semialgebraic set \( K_{\text{spec}} = \mathcal{K} \cap \mathcal{S}_{\text{spec}} \). Such a spectrahedron has the following interpretation in convex algebraic geometry. Given a real vector space \( V \) we write \( S^d V \) for the \( d \)-th symmetric power of its dual. Consider the map

\[ \psi : S^2 S^3 \mathbb{R}^2 \to S^6 \mathbb{R}^2, \quad M \mapsto [t^3 \ t^2 \ t \ 1] \cdot M \cdot [t^3 \ t^2 \ t \ 1]^T, \]

(5.7)

which takes quadrics in binary cubics to the corresponding binary sextics. Elements in the 10-dimensional space \( S^2 S^3 \mathbb{R}^2 \) are identified with symmetric \( 4 \times 4 \)-matrices \( M \), and elements in the 7-dimensional space \( S^6 \mathbb{R}^2 \) are identified with univariate polynomials \( p(t) \) of degree 6.

The kernel of the map \( \psi \) is 3-dimensional. Hence the fiber of \( \psi \) over any polynomial \( p(t) \) is a 3-dimensional affine space. That affine space contains the Gram spectrahedron

\[ \text{Gram}(p) = \{ M \in S^2 S^3 \mathbb{R}^2 : M \text{ positive semidefinite and } \psi(M) = p \}. \]

The term “Gram spectrahedron” was coined in [14, §6], where this was studied for ternary quartics \( p \). The points in \( \text{Gram}(p) \) correspond to sum of squares representations of \( p \) over \( \mathbb{R} \). Indeed, a rank \( r \) matrix \( M \) in \( \text{Gram}(p) \) has a real Cholesky decomposition \( M = N \cdot N^T \) where \( N \) has format \( 4 \times r \), and this translates into a sum of squares representation

\[ p(t) = ([t^3 \ t^2 \ t \ 1] \cdot N) \cdot ([t^3 \ t^2 \ t \ 1] \cdot N)^T \]

Clearly, in one variable, such a representation exists if and only if \( p(t) \) is non-negative on \( \mathbb{R} \).

**Lemma 5.5.** The Gram spectrahedron \( \text{Gram}(p) \) of the univariate sextic \( p(t) \) in (5.5) is affinely isomorphic to the Kummer spectrahedron defined by \( 4 \times 4 \)-matrix \( A(x) \) in (5.4).

**Proof.** The kernel of the map \( \psi \) in (5.7) is spanned by the matrices \( A_0, A_1, A_2 \) in the proof of Proposition 5.3. We identify \( \text{kernel}(\psi) \) with the affine space \( \mathbb{R}^3 \) obtained from \( \mathbb{R}^3 \) by setting \( x_3 = 1 \). With this, the spectrahedron defined by our matrix \( A(x) \) consists of all positive semidefinite matrices in the fiber of \( \psi \) over \( p(t) = \psi(A_3) \).

We summarize the findings of our discussion as follows:

**Theorem 5.6.** The spectrahedron \( \text{Gram}(p) \) is non-empty if and only if \( p(t) \) is non-negative. Suppose this holds and \( p(t) \) has simple roots in \( \mathbb{C} \). Then \( \text{Gram}(p) \) is three-dimensional, and its boundary contains precisely four nodes, corresponding to the four representations of \( p(t) \) as sum of two squares over \( \mathbb{R} \). The algebraic boundary of \( \text{Gram}(p) \) is a Kummer surface, associated with the genus 2 curve \( \{ y^2 = p(t) \} \). It contains 12 further complex nodes, six of rank 2 in the affine space \( \{ x_3 = 1 \} \) and six of rank 3 in the hyperplane at infinity \( \{ x_3 = 0 \} \).
Lemma 4.5 confirms that nothing seen in Figure 9 can be a spectrahedron:

**Corollary 5.7.** If a Kummer surface has \( \geq 5 \) real nodes then its spectrahedron is empty.

We present an explicit formula for the four nodes of a Kummer spectrahedron Gram(p). Suppose that \( p(t) \) is a monic sextic with no real roots. Then, over \( \mathbb{R} \), it can be written as

\[
p(t) = ((t - a)^2 + b^2) \cdot ((t - c)^2 + d^2) \cdot ((t - e)^2 + f^2).
\]

The four nodes on Gram(p) are given by the following representations as sums of two squares:

\[
p(t) = \begin{align*}
&((t - a)(t - c)(t - e) - (t - a)df - b(t - c)f - bd(t - e))^2 \\
&+ (bdf - b(t - c)(t - e) - (t - a)d(t - c) - (t - a)(t - c)f)^2 \\
&- ((t - a)(t - c)(t - e) - (t - a)df + b(t - c)f + bd(t - e))^2 \\
&+ (bdf - b(t - c)(t - e) + (t - a)d(t - c) + (t - a)(t - c)f)^2 \\
&- ((t - a)(t - c)(t - e) + (t - a)df - b(t - c)f - bd(t - e))^2 \\
&+ (bdf + b(t - c)(t - e) - (t - a)d(t - c) - (t - a)(t - c)f)^2 \\
&+ (bdf + b(t - c)(t - e) + (t - a)d(t - c) + (t - a)(t - c)f)^2.
\end{align*}
\]

These formulas can be translated into symmetric \( 4 \times 4 \)-matrices \( A(x) \) of rank 2.

Finally, let us also consider the case when all six roots of \( p(t) = \prod_{i=1}^6 (t - u_i) \) are real. In our representation, the ten rank 2 nodes of the symmetroid must have signature \((1, 1)\). They correspond to the ten difference-of-squares representations \( p = (q/2)^2 - (r/2)^2 \), where

\[
q(t) = 2t^3 - (u_1 + u_2 + u_3 + u_4 + u_5 + u_6)t^2 + (u_1u_2 + u_1u_3 + u_2u_3 + u_4u_5 + u_4u_6 + u_5u_6)t - u_1u_2u_3 - u_4u_5u_6,
\]

\[
r(t) = (u_1 + u_2 + u_3 - u_4 - u_5 - u_6)t^2 - (u_1u_2 + u_1u_3 + u_2u_3 - u_4u_5 - u_4u_6 - u_5u_6)t + u_1u_2u_3 - u_4u_5u_6.
\]

As in Figure 9, this Kummer symmetroid has 16 real nodes, ten of rank 2 and six of rank 3.

**Acknowledgements.**

Bernd Sturmfels was supported by the NSF (DMS-0968882) and the Max-Planck Institute für Mathematik in Bonn. Cynthia Vinzant was supported by an NSF postdoc (DMS-1204447).

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