GLOBAL ATTRACTORS FOR NONLINEAR VISCOELASTIC EQUATIONS WITH MEMORY

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Abstract. We study the asymptotic properties of the semigroup \( S(t) \) arising from the nonlinear viscoelastic equation with hereditary memory on a bounded three-dimensional domain

\[
\begin{aligned}
|\partial_t u|^{\rho} \partial_t u - \Delta \partial_t u - \Delta \partial_t u - \int_0^\infty \mu(s) \Delta \eta(s) \, ds + f(u) = h \\
\partial_t \eta = -\partial_s \eta + \partial_t u
\end{aligned}
\]

written in the past history framework of Dafermos [10]. We establish the existence of the global attractor of optimal regularity for \( S(t) \) when \( \rho \in [0, 4) \) and \( f \) has polynomial growth of (at most) critical order 5.

1. Introduction.

1.1. The model system. Given a bounded domain \( \Omega \subset \mathbb{R}^3 \) with smooth boundary \( \partial \Omega \) and \( \rho \in [0, 4] \), we consider for \( t > 0 \) the system of equations

\[
\begin{cases}
|\partial_t u|^{\rho} \partial_t u - \Delta \partial_t u - \Delta \partial_t u - \int_0^\infty \mu(s) \Delta \eta(s) \, ds + f(u) = h \\
\partial_t \eta = -\partial_s \eta + \partial_t u
\end{cases}
\]

(1.1)

in the real-valued unknowns

\[ u = u(x, t) \quad \text{and} \quad \eta = \eta^t(x, s), \]

where \( x \in \Omega, \; t \in [0, \infty) \) and \( s \in \mathbb{R}^+ = (0, \infty) \). System (1.1) is complemented by the Dirichlet boundary condition

\[ u(x, t)_{|x \in \partial \Omega} = 0, \]

(1.2)

and by the “boundary condition” for \( \eta \)

\[ \lim_{s \to 0} \eta^t(x, s) = 0. \]

(1.3)

The model is subject to the initial conditions (the dependence on \( x \) is omitted)

\[ u(0) = u_0, \quad \partial_t u(0) = v_0, \quad \eta^0 = \eta_0, \]

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where \( u_0, v_0 : \Omega \to \mathbb{R} \) and \( \eta_0 : \Omega \times \mathbb{R}^+ \to \mathbb{R} \) are prescribed functions. The external force \( h \) is time-independent, while the locally Lipschitz nonlinearity \( f \), with \( f(0) = 0 \), fulfills the critical growth restriction

\[
|f(u) - f(v)| \leq c|u - v|(1 + |u|^4 + |v|^4),
\]

along with the dissipation conditions\(^1\)

\[
f(u)u \geq F(u) - \frac{\lambda_1}{2}(1 - \nu)|u|^2 - m_f \tag{1.5}
\]

\[
F(u) \geq -\frac{\lambda_1}{2}(1 - \nu)|u|^2 - m_f \tag{1.6}
\]

for some \( \nu \in (0, 1) \) and \( m_f \geq 0 \). Here \( \lambda_1 > 0 \) denotes the first eigenvalue of the Dirichlet operator \(-\Delta\) and

\[
F(u) = \int_0^u f(y) \, dy.
\]

Finally, the convolution (or memory) kernel \( \mu \) is a nonnegative, nonincreasing, piecewise absolutely continuous function on \( \mathbb{R}^+ \) of finite total mass

\[
\int_0^\infty \mu(s) \, ds = \kappa \geq 0
\]

complying with the further assumption

\[
\int_{s}^{\infty} \mu(\sigma) \, d\sigma \leq \Theta \mu(s), \tag{1.7}
\]

for some \( \Theta > 0 \). In particular, \( \mu \) is allowed to exhibit (even infinitely many) jumps, and can be unbounded about the origin. At the same time, \( \mu \) can be identically zero, yielding the equation

\[
|\partial_t u|^\rho \partial_{tt} u - \Delta \partial_{tt} u - \Delta \partial_t u - \Delta u + f(u) = h.
\]

**Remark 1.** Assuming the past history of \( u \) to be known, from the second equation of (1.1) together with (1.3) one deduces the formal equality (see [10])

\[
\eta^f(t) = u(t) - u(t - s). \tag{1.8}
\]

Accordingly, the first equation becomes

\[
|\partial_t u|^\rho \partial_{tt} u - \Delta \partial_{tt} u - \Delta \partial_t u - (1 + \kappa)\Delta u + \int_0^\infty \mu(s)\Delta u(t - s) \, ds + f(u) = h.
\]

This provides a generalization, accounting for memory effects in the material, of equations of the form

\[
\rho(\partial_t u)\partial_{tt} u - \Delta \partial_{tt} u - \Delta \partial_t u - \Delta u + f(u) = h,
\]

arising in the description of the vibrations of thin rods whose density \( \rho \) depends on the velocity \( \partial_t u \) (see e.g. [20]).

\(^1\)Conditions (1.5)-(1.6) follow for instance by requiring \( f \in \mathcal{C}^1(\mathbb{R}) \) with \( \liminf_{|u| \to \infty} f'(u) > -\lambda_1 \).
1.2. Earlier contributions. The Volterra version of (1.1) with $f = h \equiv 0$

$$|\partial_t u|\partial_{tt}u - \Delta \partial_{tt}u - \Delta \partial_t u - (1 + \kappa)\Delta u + \int_0^t \mu(s)\Delta u(t - s)\,ds = 0,$$

corresponding to the choice of the initial datum $\eta_0 = u_0$, has been considered by several authors, also with different kind of damping terms, in concern with the decay pattern of solutions (see [3, 14, 15, 18, 19, 21, 22, 23, 24, 25, 28]). On the contrary, the asymptotic analysis of the whole system (1.1) has been tackled only in the recent work [1], where the authors prove the existence of the global attractor (without any additional regularity) within the following set of hypotheses:

- The nonlinearity $f$ has at most polynomial growth 3 and

$$f(u)u \geq F(u) \geq 0.$$  

- The nonnegative kernel $\mu \in C^1(\mathbb{R}^+) \cap L^1(\mathbb{R}^+)$ fulfills for some $\delta > 0$ and every $s \in \mathbb{R}^+$ the relation

$$\mu'(s) + \delta \mu(s) \leq 0.$$  

- The parameter $\rho \in (1, 2].$

Remark 2. Actually, analogously to what done in all the other papers on the Volterra case, the (exponential) decay rate turns out to depend on the size of the initial data. As we will see in the next Section 4, a simple argument allows to get rid of such a dependence.

The restriction on $\rho$ is also motivated by the fact that the well-posedness result for (1.1), hence the existence of the semigroup, was available only for $\rho \in (1, 2]$ (besides for the much simpler case $\rho = 0$). On the other hand, after [7] now we know that (1.1) generates a strongly continuous semigroup in our more general assumptions, and in particular, for all $\rho \in [0, 4]$. This, of course, opens a new scenario which is worth to be investigated.

1.3. The result. In this work, we prove that the strongly continuous semigroup $S(t)$ generated by system (1.1) is dissipative (i.e. possesses bounded absorbing sets) for all $\rho \in [0, 4]$. In particular, the exponential decay of solutions occurs whenever $m_f = 0$ and $h \equiv 0$. Besides, we establish the following theorem.

**Theorem 1.1.** Let $h \in L^2(\Omega)$ and $\rho \in [0, 4)$. Then $S(t)$ possesses the global attractor of optimal regularity.

With respect to the earlier literature, Theorem 1.1 improves the picture in several directions:

- The attractor is bounded in a more regular (in fact, the best possible) space.
- The nonlinearity $f$ is allowed to reach the critical polynomial order 5, under the very general dissipation conditions (1.5)-(1.6), which include for instance terms of the form

$$f(u) = u^5 + au^4 + bu^3 + cu^2 + du + e,$$

not covered by (1.9).
Condition (1.7) on the memory kernel $\mu$ is the most general possible one (among the class of nonincreasing summable kernels), since its failure prevents the uniform decay of solutions to systems with memory, no matter how the equations involved are (see [5]). As shown in [11], the condition can be equivalently stated as

$$\mu(\sigma + s) \leq Ce^{-\delta \sigma} \mu(s)$$

for some $C \geq 1$, $\delta > 0$, every $\sigma \geq 0$ and almost every $s > 0$. Observe that the latter inequality with $C = 1$ boils down to (1.10) (actually, for a.e. $s \in \mathbb{R}^+$).

At the same time, when $C > 1$ a much wider class of memory kernels is admissible (see [5] for more comments).

The parameter $\rho$ belongs to the interval $[0, 4)$. Nonetheless, the existence of the global attractor in the case $\rho = 4$, which is critical for the Sobolev embedding, seems to be out of reach at the moment.

Plan of the paper. After introducing the functional setting (Section 2), we dwell on the existence of the solution semigroup (Section 3), whose dissipative features are discussed in Section 4. Our main results on the existence of the global attractor of optimal regularity are presented in Section 5. The remaining three Sections 6-8 are devoted to the proofs. The final Appendix contains some technical lemmas.

2. Functional setting. We denote by $A = -\Delta$ the Dirichlet operator on $L^2(\Omega)$ with domain $H^2(\Omega) \cap H^1_0(\Omega)$. For $r \in \mathbb{R}$, we define the scale of compactly nested Hilbert spaces

$$H^r = \text{Dom}(A^r), \quad \langle u, v \rangle_r = \langle A^r u, A^r v \rangle_{L^2(\Omega)}, \quad \|u\|_r = \|A^r u\|_{L^2(\Omega)}.$$  

The index $r$ is omitted whenever zero. In particular,

$$H^{-1} = H^{-1}(\Omega), \quad H = L^2(\Omega), \quad H^1 = H^1_0(\Omega), \quad H^2 = H^2(\Omega) \cap H^1_0(\Omega),$$

and we have the generalized Poincaré inequalities

$$\lambda_1 \|u\|^2 \leq \|u\|_{1+r}^2.$$  

Remark 3. It is readily seen that the dissipation conditions (1.5)-(1.6) imply

$$\langle f(u), u \rangle \geq \langle F(u), 1 \rangle - \frac{1}{2}(1 - \nu)\|u\|_1^2 - M_f,$$

$$\langle F(u), 1 \rangle \geq -\frac{1}{2}(1 - \nu)\|u\|_1^2 - M_f,$$

where $M_f = m_f |\Omega|$.

Next, we introduce the history spaces

$$\mathcal{M}^r = L^2(\mathbb{R}^+; H^{1+r})$$

endowed with the inner products

$$\langle \eta, \xi \rangle_{\mathcal{M}^r} = \int_0^\infty \mu(s) \langle \eta(s), \xi(s) \rangle_{1+r} \, ds.$$  

We will also consider the infinitesimal generator $T$ of the right-translation semigroup on $\mathcal{M}$ defined as

$$T \eta = -\eta', \quad \text{Dom}(T) = \{ \eta \in \mathcal{M} : \eta' \in \mathcal{M}, \ \eta(0) = 0 \},$$

the prime standing for weak derivative. The following inequality holds (see e.g. [12])

$$\langle T \eta, \eta \rangle_{\mathcal{M}} \leq 0, \quad \forall \eta \in \text{Dom}(T).$$
Finally, we introduce the extended history spaces
\[ \mathcal{H}^r = H^{1+r} \times H^{1+r} \times \mathcal{M}^r. \]

**Notation.** Throughout the paper, \( c \geq 0 \) and \( Q(\cdot) \) will stand for a generic constant and a generic increasing positive function, respectively. We will use, often without explicit mention, the usual Sobolev embeddings, as well as the Young, Hölder and Poincaré inequalities.

3. **The gradient system.** Rewriting (1.1)-(1.3) in the form
\[
\begin{aligned}
&\partial_t u + A \partial_{tt} u + A \partial_t u + Au + \int_0^\infty \mu(s) A \eta(s) \, ds + f(u) = h, \\
&\partial_t \eta = T \eta + \partial_t u,
\end{aligned}
\]  
the following result is proved in [7].

**Theorem 3.1.** Let \( h \in H^{-1} \) and \( \rho \in [0, 4] \). Then system (3.1) generates a solution semigroup \( S(t) : \mathcal{H} \to \mathcal{H} \) that satisfies the joint continuity
\[
(t, z) \mapsto S(t)z \in C([0, \infty) \times \mathcal{H}, \mathcal{H}).
\]

Besides, given any initial data \( z = (u_0, v_0, \eta_0) \in \mathcal{H} \) and denoting the corresponding solution by
\[
(u(t), \partial_t u(t), \eta^t) = S(t)z,
\]
we have the explicit representation formula
\[
\eta^t(s) = \begin{cases} 
  u(t) - u(t-s) & 0 < s \leq t, \\
  \eta_0(s-t) + u(t) - u_0 & s > t.
\end{cases}
\]  

Moreover, defining the energy at time \( t \) of the solution \( S(t)z \) as
\[
E(t) = \frac{1}{2} \|S(t)z\|_{\mathcal{H}}^2 = \frac{1}{2} \left( \|u(t)\|_1^2 + \|\partial_t u(t)\|_1^2 + \|\eta^t\|_{\mathcal{M}}^2 \right),
\]  
we have (see [7])

**Proposition 3.2.** The uniform estimates
\[
E(t) + \|\partial_{tt} u(t)\|_1 \leq Q(R)
\]
and
\[
\int_0^\infty \|\partial_t u(t)\|_1^2 \, dt \leq Q(R)
\]
hold for every initial data \( z \in \mathcal{H} \) with \( \|z\|_{\mathcal{H}} \leq R \).

Finally, we show the existence of a gradient system structure. We first recall the definition.

**Definition 3.3.** A function \( \mathcal{L} \in C(\mathcal{H}, \mathbb{R}) \) is called a Lyapunov functional if

(i) \( \mathcal{L}(\cdot) \to \infty \) if and only if \( \|\cdot\|_{\mathcal{H}} \to \infty \);

(ii) \( \mathcal{L}(S(t)z) \) is nonincreasing for any \( z \in \mathcal{H} \);

(iii) if \( \mathcal{L}(S(t)z) = \mathcal{L}(z) \) for all \( t > 0 \), then \( z \) is a stationary point for \( S(t) \).

If there exists a Lyapunov functional, then \( S(t) \) is called a gradient system.

**Proposition 3.4.** \( S(t) \) is a gradient system on \( \mathcal{H} \).
Proof. For $\zeta = (u, v, \eta)$, let us define
\[
L(\zeta) = \frac{1}{\rho + 2} \int_{\Omega} |v|^{p+2} \, dx + \frac{1}{2} \|\zeta\|_{H}^{2} + \langle F(u), 1 \rangle - \langle h, u \rangle.
\]
In light of (1.4) and (2.2), it is readily seen that
\[
\frac{\nu}{4}\|\zeta\|^{2}_{H} - c_{f,h} \leq L(\zeta) \leq c\|\zeta\|_{H}^{2} (1 + \|\zeta\|_{H}^{4}) + \|h\|^{2}_{-1},
\]
where
\[
c_{f,h} = M_{f} + \frac{1}{\nu} \|h\|^{2}_{-1}.
\]
This proves (i). For sufficiently regular initial data $z$, testing system (3.1) with $(\partial_{t}u, \eta)$ in $H \times M$ and recalling (2.3), we get
\[
\frac{d}{dt} L(S(t)z) + \|\partial_{t}u(t)\|_{H}^{2} = \langle T\eta', \eta' \rangle_{M} \leq 0,
\]
so establishing (ii). To prove (iii), we note that if $L(S(t)z)$ is constant, it follows that
\[
\|\partial_{t}u(t)\|_{H}^{2} = \langle T\eta', \eta' \rangle_{M} = 0.
\]
Therefore $\partial_{t}u(t) \equiv 0$, so that $u(t) = u_{0}$ for all $t$. In particular, the second equation of (3.1) reduces to
\[
\partial_{t}\eta = T\eta,
\]
and a multiplication by $\eta$ gives
\[
\|\eta'\|_{M} = \|\eta_{0}\|_{M}, \quad \forall t \geq 0.
\]
On the other hand, we learn from (3.2) that
\[
\eta'(s) = \begin{cases}
0 & 0 < s \leq t, \\
\eta_{0}(s - t) & s > t,
\end{cases}
\]
thus, in light of (1.11)
\[
\|\eta_{0}\|_{M}^{2} = \|\eta'\|_{M}^{2} = \int_{0}^{\infty} \mu(t + s)\|\eta_{0}(s)\|_{H}^{2} \, ds \leq C e^{-\delta t} \|\eta_{0}\|_{M}^{2},
\]
which forces the equality $\eta_{0} = 0$. In conclusion,
\[
S(t)z = z = (u_{0}, 0, 0),
\]
meaning that $z$ is a stationary point. \hfill \qed

4. Dissipativity. The dissipativity of $S(t)$ follows from the existence of a bounded absorbing set. This is a straightforward consequence of the next result.

Theorem 4.1. There exists $\omega > 0$ such that
\[
E(t) \leq Q(R) e^{-\omega t} + R_{0}
\]
whenever $E(0) \leq R$, having set
\[
R_{0} = \frac{4}{\nu} (c_{f,h} + M_{f}) = \frac{4}{\nu} \left(2M_{f} + \frac{1}{\nu} \|h\|^{2}_{-1}\right).
\]

Remark 4. In light of the theorem, every ball $B$ of $H$ centered at zero with radius strictly greater than $\sqrt{2K_{0}}$ is a (bounded) absorbing set for $S(t)$. Recall that $B$ is called an absorbing set if for every bounded set $\mathcal{B} \subset H$ there exists a time $t_{\mathcal{B}} \geq 0$ such that
\[
S(t)\mathcal{B} \subset B, \quad \forall t \geq t_{\mathcal{B}}.
\]
If $R_0 = 0$ the exponential decay of the energy occurs.

**Corollary 4.2.** Let $h = 0$ and $f$ satisfy (1.5)-(1.6) with $m_f = 0$. Then

$$E(t) \leq Q(R)e^{-\omega t}$$

whenever $E(0) \leq R$.

As a first step, we prove the result in a weaker form, allowing the (exponential) decay rate to depend on $R$.

**Lemma 4.3.** For every $R \geq 0$ there exists a constant $\delta = \delta_R > 0$ such that

$$E(t) \leq \left[ Q(R)E(0) + \frac{4}{\nu} \|h\|_1^2 \right] e^{-\delta t} + R_0$$

whenever $E(0) \leq R$.

**Proof.** For a fixed $\|z\|_H \leq R$, let

$$L(t) = L(S(t)z)$$

be the Lyapunov functional of Proposition 3.4. Then, we introduce the further functionals

$$\Psi(t) = \int_{0}^{\infty} \left( \int_{s}^{\infty} \mu(y) \right) \|\eta^t(s)\|_1^2 \, ds,$$

$$\Phi(t) = \frac{1}{2} \|u(t)\|_1^2 + \langle \partial_t u(t), u(t) \rangle_1 + \frac{1}{\rho + 1} \|\partial_t u(t)\|_{\rho + 2}^2.$$ 

Arguing as in the proof of Lemma A.1 in Appendix,

$$\frac{d}{dt} \Psi + \frac{1}{2} \|\eta\|_{M}^2 \leq 2 \Theta^2 \kappa \|\partial_t u\|_1^2.$$ (4.1)

A multiplication of the first equation of (3.1) by $u$ gives

$$\frac{d}{dt} \Phi + \|u\|_1^2 + \langle f(u), u \rangle - \langle h, u \rangle$$

$$= - \int_{0}^{\infty} \mu(s) \langle \eta(s), u \rangle_1 \, ds + \|\partial_t u\|_1^2 + \frac{1}{\rho + 1} \int_{\Omega} |\partial_t u|_{\rho + 2}^2 \, dx,$$

and from (2.1) we obtain

$$\frac{d}{dt} \Phi + \frac{1 + \nu}{2} \|u\|_1^2 + \langle F(u), 1 \rangle - \langle h, u \rangle$$

$$\leq - \int_{0}^{\infty} \mu(s) \langle \eta(s), u \rangle_1 \, ds + \|\partial_t u\|_1^2 + \frac{1}{\rho + 1} \int_{\Omega} |\partial_t u|_{\rho + 2}^2 \, dx + M_f.$$ (4.2)

Fixing $\varepsilon > 0$ such that

$$1 - 2\varepsilon \Theta^2 \kappa \geq \frac{1}{2},$$

and for $\delta > 0$ to be properly chosen later, we consider the functional

$$\mathcal{E}(t) = \mathcal{L}(t) + \varepsilon \Psi(t) + \delta \Phi(t).$$
Collecting (3.5) and (4.1)-(4.2), we end up with
\[
\frac{d}{dt} \mathcal{E} + \delta \mathcal{L} + \delta^2 \Phi + \frac{\delta}{2} (\nu - \delta) \|u\|_1^2 + \frac{1}{2}(1 - 3\delta) \|\partial_t u\|_1^2 + \frac{1}{2}(\varepsilon - \delta) \|\eta\|^2_M \\
\leq \delta M_f - \delta \int_0^\infty \mu(s) \langle \eta(s), u \rangle_1 \, ds + \delta^2 \langle \partial_t u, u \rangle_1 \\
+ \delta \left( \frac{1}{\rho + 1} + \frac{1}{\rho + 2} \right) \int_\Omega |\partial_t u|^{\rho+2} \, dx + \frac{\delta^2}{\rho + 1} \langle |\partial_t u|^{\rho} \partial_t u, u \rangle.
\]
We estimate the right-hand side above in the following way. For \( \delta > 0 \) sufficiently small, standard computations entail
\[
-\delta \int_0^\infty \mu(s) \langle \eta(s), u \rangle_1 \, ds \leq \delta \sqrt{\kappa} \|\eta\|_M \|u\|_1 \leq \frac{\delta}{8} (\nu - \delta) \|u\|_1^2 + c\delta \|\eta\|^2_M
\]
and
\[
\delta^2 \langle \partial_t u, u \rangle_1 \leq \frac{\delta}{8} (\nu - \delta) \|u\|^2_1 + \frac{1}{4} \|\partial_t u\|^2_1.
\]
Moreover, by Proposition 3.2 and the embedding \( H^1 \subset L^{2(\rho+1)}(\Omega) \),
\[
\delta \left( \frac{1}{\rho + 1} + \frac{1}{\rho + 2} \right) \int_\Omega |\partial_t u|^{\rho+2} \, dx + \frac{\delta^2}{\rho + 1} \langle |\partial_t u|^{\rho} \partial_t u, u \rangle \\
\leq \delta Q(R) \|\partial_t u\|^2_1 + \frac{\delta}{4} (\nu - \delta) \|u\|^2_1.
\]
Therefore, we arrive at
\[
\frac{d}{dt} \mathcal{E} + \delta \mathcal{L} + \delta^2 \Phi + \left( \frac{1}{4} - \frac{3\delta}{2} - \delta Q(R) \right) \|\partial_t u\|^2_1 + \left( \frac{\varepsilon}{2} - c\delta \right) \|\eta\|^2_M \leq \delta M_f.
\]
Hence, we can choose \( \delta = \delta_R \) small enough that
\[
\frac{d}{dt} \mathcal{E} + \delta \mathcal{E} + \varepsilon \left( \frac{1}{4} \|\eta\|^2_M - \delta \Phi \right) \leq \delta M_f.
\]
Actually, since by (1.7)
\[
0 \leq \Phi \leq \Theta \|\eta\|^2_M \leq 2\Theta E,
\]
up to further reducing \( \delta \), we get
\[
\frac{d}{dt} \mathcal{E} + \delta \mathcal{E} \leq \delta M_f,
\]
and an application of the Gronwall lemma leads to
\[
\mathcal{E}(t) \leq \mathcal{E}(0) e^{-\delta t} + M_f.
\]
We now prove that
\[
\nu E_c - c_{f,h} \leq \mathcal{E} \leq Q(R) E + \|h\|^2_{-1}.
\]
Indeed,
\[
|\Phi| \leq \|u\|^2_1 + \frac{1}{2} \|\partial_t u\|^2_1 + \frac{1}{\rho + 1} \int_\Omega |\partial_t u|^{\rho+1} \, dx \\
\leq \|u\|^2_1 + \frac{1}{2} \|\partial_t u\|^2_1 + \frac{1}{\rho + 1} \|\partial_t u\|^{\rho+1}_{L^{\rho+1}(\Omega)} \|u\|_{L^6} \\
\leq \|u\|^2_1 + \frac{1}{2} \|\partial_t u\|^2_1 + c \|\partial_t u\|^2_1 \|\eta\|^2_M \leq Q(R) E.
\]
Therefore, on account of (3.4) and (4.3), we readily get
\[
\mathcal{E}(t) \leq Q(R) E(t) + \|h\|^2_{-1}.
\]
Besides,
\[ E \geq \mathcal{L} - \delta |\Phi| \geq \frac{\nu}{2} E - c_{f,h} - \delta Q(R) E, \]
hence, possibly by further reducing \( \delta \) in dependence of \( R \), we obtain
\[ E \geq \frac{\nu}{4} E - c_{f,h}. \]

The claim follows from (4.4) and (4.5). \( \square \)

**Proof of Theorem 4.1.** Let \( \|z\|_H \leq R \) for some \( R \geq 0 \). Then, we infer from Lemma 4.3 the existence of \( t_R \geq 0 \) such that
\[ E(t_R) \leq 1 + R_0, \]
and a further application of Lemma 4.3 yields
\[ E(t) = \frac{1}{2} \|S(t - t_R)S(t_R)z\|_H^2 \leq Q(R_0) e^{\omega t_R} e^{-\omega t} + R_0, \quad \forall t > t_R, \]
where \( \omega = \delta_1 + R_0 \). At the same time, again by Lemma 4.3,
\[ E(t) \leq Q(R) + R_0, \quad \forall t \leq t_R. \]
Collecting the two inequalities we are done. \( \square \)

5. **Main results.**

**Theorem 5.1.** The semigroup \( S(t) \) possesses the global attractor \( \mathfrak{A} \).

By definition, the global attractor of \( S(t) \) is the unique compact set \( \mathfrak{A} \subset H \) which is at the same time fully invariant and attracting for the semigroup (see e.g. [2, 13, 16, 27]). Namely,

(i) \( S(t)\mathfrak{A} = \mathfrak{A} \) for every \( t \geq 0 \); and
(ii) for every bounded set \( B \subset H \)
\[ \lim_{t \to \infty} \text{dist}_H(S(t)B, \mathfrak{A}) = 0, \]
where \( \text{dist}_H \) denotes the standard Hausdorff semidistance in \( H \). We also recall that, for an arbitrarily fixed \( \tau \in \mathbb{R} \), the global attractor can be given the form (see [16])
\[ \mathfrak{A} = \{ \zeta(\tau) : \zeta \text{ CBT} \}, \]
where a complete bounded trajectory (CBT) of the semigroup is a function \( \zeta \in C_b(\mathbb{R}, H) \) satisfying
\[ \zeta(\tau) = S(t)\zeta(\tau - t), \quad \forall t \geq 0, \forall \tau \in \mathbb{R}. \]

According to [4, 13], the existence of a Lyapunov function (Proposition 3.4) ensures that \( \mathfrak{A} \) coincides with the unstable manifold of the set \( S \) of equilibria of \( S(t) \), which is compact, nonempty and made of all vectors \( z^* = (u^*, 0, 0) \) with \( u^* \) solution to the elliptic equation \( Au^* + f(u^*) = h \). That is,
\[ \mathfrak{A} = \{ \zeta(0) : \zeta \text{ is a CBT and} \lim_{\tau \to -\infty} \|\zeta(\tau) - S\|_H = 0 \}. \]
Moreover, the following result holds.

**Proposition 5.2.** Any CBT \( \zeta = (u, \partial_t u, \eta) \) fulfills the relation
\[ \lim_{\tau \to \pm \infty} \|\zeta(\tau) - S\|_H = 0. \]

In particular,
\[ \lim_{\tau \to \pm \infty} \|\partial_t u(\tau)\|_1 + \|\eta^*\|_{\mathcal{M}} = 0. \]
Corollary 5.3. If $\mathcal{S}$ is discrete, there exist $z^*, w^* \in \mathcal{S}$ such that $\zeta(\tau) \to z^*$ in $\mathcal{H}$ as $\tau \to \infty$ and $\zeta(\tau) \to w^*$ in $\mathcal{H}$ as $\tau \to -\infty$.

On the other hand, $\mathcal{S}$ might as well be a continuum (e.g. if $F$ is a double-well potential, see [16]). In such a case, the convergence of a given trajectory to a single equilibrium cannot be predicted, and is false in general. Nonetheless, if $f$ is real analytic, there is a well-known tool which can be used in order to guarantee the convergence of trajectories to equilibria: the Łojasiewicz-Simon inequality (see e.g. [17]).

Coming to the regularity of the attractor, we have

Theorem 5.4. The global attractor $\mathfrak{A}$ of $S(t)$ is bounded in $\mathcal{H}^1$.

Theorem 5.1 and Theorem 5.4 subsume the main Theorem 1.1 stated in the introduction.

Observe that, as $\mathcal{S} \subset \mathfrak{A}$, if $h \in \mathcal{H}$ without any further assumption we cannot have more than $\mathcal{H}^2$-regularity for the first component. Thus the inclusion $\mathfrak{A} \subset \mathcal{H}^1$ is optimal.

Proposition 5.5. For every $\zeta = (u, \partial_t u, \eta)$ the formal equality (1.8) holds true for every $t \in \mathbb{R}$. In particular, it follows that $\eta(t) \in \text{Dom}(T)$ for all $t$.

A direct consequence of the proposition is the next corollary, whose proof is left to the reader.

Corollary 5.6. Given $u \in C_b(\mathbb{R}, \mathcal{H}) \cap C^1_b(\mathbb{R}, \mathcal{H})$ and defining $\eta = \eta(t)$ for all real $t$ by the formula (1.8), the vector $\zeta = (u, \partial_t u, \eta)$ is a CBT if and only if $u$ solves the equation

$$
|\partial_t u(t)|^2 \partial_t u(t) + A\partial_t u(t) + A\partial_t u(t) + (1 + \kappa)Au(t) - \int_0^{\infty} \mu(s)Au(t - s) ds + f(u(t)) = h
$$

for every $t \in \mathbb{R}$.

The proofs of the results stated above will be carried out in the subsequent sections.

6. Existence of the global attractor. In what follows, let $\rho \in [0, 4)$. Besides, let $\mathcal{B}$ be a given bounded absorbing set, whose existence is guaranteed by Theorem 4.1.

The main result of the section is

Proposition 6.1. For any $t \geq 0$, there exists a compact set $K(t) \subset \mathcal{H}$ such that

$$
\text{dist}_{\mathcal{H}}(S(t)\mathcal{B}, K(t)) \leq ce^{-\omega t}
$$

for some $c \geq 0$ and $\omega > 0$ depending only on $\mathcal{B}$.

Proposition 6.1 tells that $S(t)$ is asymptotically compact. Hence, invoking a general result of the theory of dynamical systems (see e.g. [2, 6, 13, 16, 27]), $S(t)$ possesses the global attractor $\mathfrak{A}$. This establishes the proof of Theorem 5.1.

In order to prove Proposition 6.1, we need a suitable decomposition of $f$.

Lemma 6.2. The nonlinearity $f$ admits the decomposition

$$
f(s) = f_0(s) + f_1(s)
$$

for some $f_0, f_1$ with the following properties:
Lemma 6.3. For any \( t \geq 0 \), there exists a closed bounded set \( B_\sigma(t) \subset H^\sigma \) such that
\[
\text{dist}_{H}(S(t)B, B_\sigma(t)) \leq ce^{-\omega t},
\]
for some constants \( c \geq 0 \) and \( \omega > 0 \) depending only on \( \mathbb{B} \).
Proof. We write \( f = f_0 + f_1 \) as in Lemma 6.2. For an arbitrarily fixed \( z \in \mathbb{B} \), let

\[
(\hat{v}(t), \partial_t \hat{v}(t), \hat{\xi}^t) \quad \text{and} \quad (\hat{w}(t), \partial_t \hat{w}(t), \hat{\psi}^t)
\]

be the solutions at time \( t > 0 \) to the problems

\[
\begin{cases}
|\partial_t v|^p \partial_{tt} \hat{v} + A \partial_{tt} \hat{v} + A \partial_t \hat{v} + A \hat{v} + \int_0^\infty \mu(s) A \hat{\xi}(s) \, ds + f_0(\hat{v}) = 0, \\
\partial_t \hat{\xi} = T \hat{\xi} + \partial_t \hat{v}, \\
(\hat{v}(0), \partial_t \hat{v}(0), \hat{\xi}^0) = z,
\end{cases}
\tag{6.3}
\]

and

\[
\begin{cases}
|\partial_t u|^p \partial_{tt} u - |\partial_t u|^p \partial_{tt} \hat{v} + A \partial_{tt} \hat{w} + A \partial_t \hat{w} + A \hat{w} + \int_0^\infty \mu(s) A \hat{\psi}(s) \, ds = g, \\
\partial_t \hat{\psi} = T \hat{\psi} + \partial_t \hat{w}, \\
(\hat{w}(0), \partial_t \hat{w}(0), \hat{\psi}^0) = 0,
\end{cases}
\tag{6.4}
\]

having set

\[
g = h - f_0(u) + f_0(\hat{v}) - f_1(u).
\]

In what follows, the generic constant \( c \geq 0 \) is independent of the choice of \( z \in \mathbb{B} \).

Concerning system (6.3), since the forcing term is null and \( f_0(v) \geq F_0(v) \geq 0 \), an application of Lemma 4.3 yields the exponential decay

\[
\left\| \left( \hat{v}(t), \partial_t \hat{v}(t), \hat{\xi}^t \right) \right\|_{\mathcal{H}} \leq c \| z \|_{\mathcal{H}} e^{-\omega t},
\tag{6.5}
\]

for some \( c \geq 0 \) and \( \omega > 0 \), depending only on \( \mathbb{B} \). Furthermore, a multiplication of the first equation of (6.3) by \( \partial_{tt} \hat{v} \) gives

\[
\| \partial_{tt} \hat{v} \|^2 \leq \langle \partial_t \hat{v}, \partial_{tt} \hat{v} \rangle + \| \partial_{tt} \hat{v} \|^2 \\
= -\langle \partial_t \hat{v}, \partial_t \hat{v} \rangle - \int_0^\infty \mu(s) \langle \hat{\xi}(s), \partial_t \hat{v} \rangle \, ds - \langle f_0(\hat{v}), \partial_{tt} \hat{v} \rangle.
\]

By the growth assumption on \( f_0 \),

\[-\langle f_0(\hat{v}), \partial_{tt} \hat{v} \rangle \leq \| f_0(\hat{v}) \|_{L^{p/2}} \| \partial_{tt} \hat{v} \|_{L^{p}} \leq c \left( 1 + \| \hat{v} \|^2 \right) \| \partial_{tt} \hat{v} \|_{L^1}.
\]

Moreover,

\[-\int_0^\infty \mu(s) \langle \hat{\xi}(s), \partial_t \hat{v} \rangle \, ds \leq \| \partial_{tt} \hat{v} \|_{L^1} \int_0^\infty \mu(s) \| \hat{\xi}(s) \|_{L^1} \, ds,
\]

and

\[\int_0^\infty \mu(s) \| \hat{\xi}(s) \|_{L^1} \, ds \leq \sqrt{\kappa} \| \hat{\xi} \|_{M}.
\]

Thus, we infer from (6.5) that

\[
\| \partial_{tt} \hat{v} \|^2 \leq \left( \| \partial_t \hat{v} \|_1 + \| \hat{v} \|_1 + \sqrt{\kappa} \| \hat{\xi} \|_{M} + c + c \| \hat{v} \|^2 \right) \| \partial_{tt} \hat{v} \|_{L^1} \leq \frac{1}{2} \| \partial_{tt} \hat{v} \|^2_1 + c
\]

implying the bound

\[
\| \partial_{tt} \hat{v} \|_{L^1} \leq c.
\tag{6.6}
\]

Concerning system (6.4), introducing the energy

\[
\hat{E}_\sigma(t) = \frac{1}{2} \left\| \left( \hat{w}(t), \partial_t \hat{w}(t), \hat{\psi}^t \right) \right\|_{\mathcal{H}^\sigma}^2,
\]

we want to prove the estimate

\[
\hat{E}_\sigma(t) \leq e^{ct}.
\tag{6.7}
\]
To this aim, we multiply the first equation of (6.4) by \( A^\sigma \partial_t \hat{w} \), and the second one by \( \hat{\psi} \) in \( \mathcal{M}^\sigma \), so to get

\[
\frac{d}{dt} \hat{E}_\sigma + \| \partial_t \hat{w} \|^2_{1+\sigma} \leq -\| \partial_t u \|^2 \| \partial_t \hat{w} \| + \| \partial_t \hat{v} \|^2 \| \partial_t \hat{w} \|, A^\sigma \partial_t \hat{w} + \langle g, A^\sigma \partial_t \hat{w} \rangle.
\]

Observe that

\[
|g| = |\hat{h} - f_0(u) + f_0(\hat{v}) - f_1(u)| \leq |\hat{h}| + c|\hat{w}|(|u| + |\hat{v}|)^4 + c(1 + |u|).
\]

Thus, the Sobolev embeddings

\[
H^{1+\sigma} \subset L^{\frac{6}{1+\sigma}}(\Omega) \quad \text{and} \quad H^{1-\sigma} \subset L^{\frac{6}{1-\sigma}}(\Omega)
\]

yield

\[
\langle g, A^\sigma \partial_t \hat{w} \rangle \leq \| \hat{h} \| A^\sigma \partial_t \hat{w} \| + c(1 + \| u \|) \| A^\sigma \partial_t \hat{w} \|
\]

\[
+ c(\| u \|_{L^6} + \| \hat{v} \|_{L^6})^4 \| \hat{w} \|_{L^{6/(1-2\sigma)}} \| A^\sigma \partial_t \hat{w} \|_{L^{6/((1+2\sigma)}}
\]

\[
\leq c\| \partial_t \hat{w} \|_{1+\sigma} + c(1 + \| u \|_1) \| \partial_t \hat{w} \|_{1+\sigma}
\]

\[
+ c(\| u \|_1 + \| \hat{v} \|_1)^4 \| \hat{w} \|_{1+\sigma} \| \partial_t \hat{w} \|_{1+\sigma}
\]

\[
\leq c\hat{E}_\sigma + c.
\]

Besides, since \( \frac{3\sigma}{2-\sigma} \leq 6 \), from the embedding \( H^1 \subset L^{\frac{6}{2-\sigma}}(\Omega) \) we find

\[
\langle -|\partial_t u|^6 \| \partial_t \hat{w} \| \leq \| \partial_t u \|_{L^{6/(2-\sigma)}}^6 \| \partial_t \hat{w} \|_{L^{6/(1+2\sigma)}} \| A^\sigma \partial_t \hat{w} \|_{L^{6/(1+2\sigma)}}
\]

\[
\leq \| \partial_t u \|_1^6 \| \partial_t \hat{w} \|_1 \| \partial_t \hat{w} \|_{1+\sigma},
\]

and, analogously,

\[
\langle |\partial_t \hat{v}|^6 \| \partial_t \hat{w} \| \leq \| \partial_t \hat{v} \|_1^6 \| \partial_t \hat{w} \|_{1+\sigma}.
\]

Therefore, in light of Proposition 3.2, (6.5) and (6.6), we have

\[
\langle -|\partial_t u|^6 \| \partial_t \hat{w} \| \leq \| \partial_t \hat{w} \|_{1+\sigma}^2 + c.
\]

Collecting the above inequalities we arrive at

\[
\frac{d}{dt} \hat{E}_\sigma \leq c\hat{E}_\sigma + c.
\]

Recalling that \( \hat{E}_\sigma(0) = 0 \), by the Gronwall lemma we obtain the sought inequality (6.7). This finishes the proof. \( \square \)

Lemma 6.3 is not quite enough to conclude, since the embedding \( \mathcal{H}^\sigma \subset \mathcal{H} \) is not compact (see [26]). Hence, a further argument is needed.

**Proof of Proposition 6.1.** In the previous notation, for any \( z \in \mathbb{B} \) and any fixed \( t \geq 0 \) we set

\[
\Xi_z = \bigcup_{t \geq 0} \hat{\psi}^z.
\]

Exploiting the representation formula for \( \hat{\psi}^z \)

\[
\hat{\psi}^z(s) = \begin{cases} 
\hat{w}(t) - \hat{w}(t-s) & 0 < s \leq t, \\
\hat{w}(t) & s > t,
\end{cases}
\]

and taking into account that \( \partial_t \hat{w} \in L^\infty(0, \infty; H^1) \), we learn that \( \Xi_z \subset \text{Dom}(T) \), and by elementary computations we obtain

\[
\sup_{z \in \mathbb{B}} \| T \hat{\psi}^z \|_{\mathcal{M}} \leq c \quad \text{and} \quad \sup_{z \in \mathbb{B}} \| \hat{\psi}^z(s) \|_{1}^2 \leq c.
\]
Besides, by (6.7),
\[ \sup_{z \in B} \| \hat{\psi}^t \|_{\mathcal{M}^\sigma} \leq Q(t). \]
Since
\[ s \mapsto c\mu(s) \in L^1(\mathbb{R}^+), \]
we infer from Lemma A.2 that \( \Xi_t \) is precompact in \( \mathcal{M} \). At this point, exploiting (6.7) again, let \( B(t) \) be the closed ball of \( H^{1+\sigma} \times H^{1+\sigma} \) centered at zero of a suitable radius \( Q(t) \) such that
\[ \sup_{z \in B} \| (\hat{w}(t), \partial_t \hat{w}(t)) \|_{H^{1+\sigma} \times H^{1+\sigma}} \leq Q(t). \]
Finally, define
\[ K(t) = B(t) \times \Xi_t, \]
the bar standing for the closure in \( \mathcal{M} \). Then \( K(t) \) is compact in \( \mathcal{H} \) and fulfills the claim.

**Remark 5.** Actually, relying on the gradient system structure of \( S(t) \) provided by Proposition 3.4, one could prove the existence of the global attractor without passing through the existence of a bounded absorbing set, which is then recovered as a byproduct (see e.g. [8, 13]). The disadvantage of this scheme is that it does not provide any estimate of the entering time into the absorbing set.

7. Further regularity.

**Proposition 7.1.** The global attractor \( \mathfrak{A} \) is bounded in \( \mathcal{H}^\sigma \).

**Proof.** The global attractor \( \mathfrak{A} \), being fully invariant, is contained in every closed attracting set. Hence, to prove the lemma it is enough to exhibit a (closed) ball \( \mathcal{B}_\sigma \subset \mathcal{H}^\sigma \) which attracts the bounded absorbing set \( \mathcal{B} \). Indeed, by applying Lemma A.3 with \( r = \sigma \), we will show that
\[ \text{dist}_{\mathcal{H}}(S(t)\mathcal{B}, \mathcal{B}_\sigma) \leq c e^{-\vartheta t}, \]
for some \( \vartheta > 0 \). To this end, let \( z \in \mathcal{B} \) be fixed, and let \( y \in \mathcal{B} \) and \( x \in \mathcal{H}^\sigma \) be any pair satisfying \( y + x = z \). We define the operators
\[ V_z(t)y = (v(t), \partial_t v(t), \xi^t) \quad \text{and} \quad U_z(t)x = (w(t), \partial_t w(t), \psi^t), \]
where \( (v(t), \partial_t v(t), \xi^t) \) and \( (w(t), \partial_t w(t), \psi^t) \) solve systems (6.3) and (6.4) without the hats, with initial data
\[ (v(0), \partial_t v(0), \xi^0) = y \quad \text{and} \quad (w(0), \partial_t w(0), \psi^0) = x. \]

Condition (i) of Lemma A.3 holds by construction, while (ii) follows by the exponential decay (6.5), which now reads
\[ \|(v(t), \partial_t v(t), \xi^t)\|_{\mathcal{H}} = \|V_z(t)y\|_{\mathcal{H}} \leq c\|y\|_{\mathcal{H}} e^{-\vartheta t}. \] (7.1)
Arguing as in the proof of (6.6) we also get
\[ \|\partial_t v\|_1 \leq c. \] (7.2)
In order to prove (iii), we set
\[ E_\sigma(t) = \frac{1}{2} \|U_z(t)x\|_{\mathcal{H}^\sigma}^2. \]
An application of Lemma A.1 provides a functional \( \Lambda_\sigma \) satisfying
\[ \frac{1}{2} E_\sigma \leq \Lambda_\sigma \leq 2 E_\sigma, \] (7.3)
jointly with the differential inequality
\[
\frac{d}{dt} \Lambda_\sigma + \delta E_\sigma \leq \langle \gamma, \partial_t u \rangle_\sigma + \delta \langle \gamma, w \rangle_\sigma,
\]
which holds for all \( \delta > 0 \) small enough. Here, \( \gamma \) is defined by
\[
\gamma = g - |\partial_t u|^2 \partial_t u + |\partial_t v|^2 \partial_t v
\]
where
\[
g = h - f_0(u) + f_0(v) - f_1(u).
\]

We estimate the nonlinearity \( g \) as follows: we write
\[
|g| \leq |h| + c |w| (|u| + |v|)^4 + c(1 + |u|)
\]
\[
\leq |h| + c |w|(|\tilde{w}| + |v|)^4 + c(|u| + |v|)|\tilde{w}|^4 + c(1 + |u|)
\]
and, with analogous computations as in (6.8), we obtain
\[
\langle g, A^\sigma \partial_t w \rangle \leq \|h\| \|A^\sigma \partial_t w\| + c(\|v\|_{L^6} + \|\tilde{w}\|_{L^6})^4 \|w\|_{L^{6/(1-2\sigma)}} \|A^\sigma \partial_t w\|_{L^{6/(1+2\sigma)}}
\]
\[
+ c(\|u\|_{L^6} + \|v\|_{L^6}) \|\tilde{w}\|_{L^{6/(1-2\sigma)}}^4 \|A^\sigma \partial_t w\|_{L^{6/(1+2\sigma)}} + c(1 + \|u\|) \|A^\sigma \partial_t w\|
\]
\[
\leq c\|\partial_t w\|_{1+\sigma} + c(\|v\|_1 + \|\tilde{w}\|_1)^4 \|w\|_{1+\sigma} \|\partial_t w\|_{1+\sigma}
\]
\[
+ c(\|u\|_1 + \|v\|_1) \|\tilde{w}\|_{1+\sigma}^4 \|\partial_t w\|_{1+\sigma} + c(1 + \|u\|_1) \|\partial_t w\|_{1+\sigma}.
\]

Exploiting the decay estimates (6.5) and (7.1) together with (6.7), we arrive at
\[
\langle g(t), A^\sigma \partial_t w(t) \rangle \leq \frac{\delta}{8} \|\partial_t w(t)\|_{1+\sigma}^2 + \frac{c e^{-4\omega t}}{8} \|w(t)\|_{1+\sigma}^2 + \|\partial_t w(t)\|_{1+\sigma}^2 + Q(t),
\]
for some \( Q(\cdot) \) independent of \( x \). Besides, arguing exactly as in the proof of Lemma 6.3,
\[
\langle -|\partial_t u|^2 \partial_t u + |\partial_t v|^2 \partial_t v, A^\sigma \partial_t w \rangle \leq \frac{\delta}{8} \|\partial_t w\|_{1+\sigma}^2 + c.
\]
where we used Proposition 3.2, (7.1) and (7.2). By analogous computations, we draw
\[
\langle \gamma(t), A^\sigma w(t) \rangle \leq \left( \frac{\delta}{4} + \frac{c e^{-4\omega t}}{4} \right) \|w(t)\|_{1+\sigma}^2 + Q(t),
\]
for some \( Q(\cdot) \) independent of \( x \). We finally end up with the differential inequality
\[
\frac{d}{dt} \Lambda_\sigma(t) + \frac{\delta}{2} E_\sigma(t) \leq c e^{-4\omega t} E_\sigma(t) + Q(t).
\]
In light of (7.3), we infer from the Gronwall lemma that
\[
\|U_\varepsilon(t)x\|_{H^\sigma} \leq c e^{-\frac{4\omega t}{\varepsilon}} \|x\|_{H^\sigma} + Q(t).
\]
This proves (iii). \( \square \)

A further regularization for \( \partial_t u \) will be needed.

**Lemma 7.2.** For initial data \( z \in \mathfrak{A} \) we have
\[
\|\partial_t u\|_{1+\sigma} \leq c
\]
for some \( c > 0 \) depending only on \( \mathfrak{A} \).
Proof. A multiplication of the first equation of (3.1) by $A^\sigma \partial_t u$ gives
\[ \| \partial_t u \|^2_{1+\sigma} \leq -\langle \partial_t u, A^\sigma \partial_t u \rangle - \langle \partial_t u, \partial_t u \rangle_{1+\sigma} - \langle u, \partial_t u \rangle_{1+\sigma} \tag{7.4} \]

In order to estimate the terms in the right-hand side, we exploit the bound

Note first that
\[ -\langle \partial_t u, A^\sigma \partial_t u \rangle \leq \| \partial_t u \|^2_{L^6/(1+\sigma)} \| A^\sigma \partial_t u \|_{L^6/(1+\sigma)} \]
\[ \leq c \| \partial_t u \|_{1+\sigma} \]

Moreover, in light of (1.4),
\[ -\langle f(u), A^\sigma \partial_t u \rangle \leq \| f(u) \|_{L^6/(1+\sigma)} \| A^\sigma \partial_t u \|_{L^6/(1+\sigma)} \]
\[ \leq c \| u \|_{1+\sigma} \| \partial_t u \|_{1+\sigma} \]

and
\[ -\int_0^\infty \mu(s) \langle \eta(s), \partial_t u \rangle_{1+\sigma} \, ds \leq \sqrt{\kappa} \| \eta \|_{M^\sigma} \| \partial_t u \|_{1+\sigma}. \]

As a consequence, (7.4) gives
\[ \| \partial_t u \|^2_{1+\sigma} \leq \left( \| \partial_t u \|_{1+\sigma} + \| u \|_{1+\sigma} + \sqrt{\kappa} \| \eta \|_{M^\sigma} + c + \| h \|_{L^6/(1+\sigma)} \right) \| \partial_t u \|_{1+\sigma} \]
\[ \leq \frac{1}{2} \| \partial_t u \|^2_{1+\sigma} + c, \]

concluding the proof. \qed

8. Optimal regularity of the attractor. In this section we prove the optimal regularity of the attractor. The key ingredient is the following lemma.

Lemma 8.1. Given any $r \in [\sigma, 1-\sigma]$ the following holds:
\[ \mathcal{A} \subset H^r \Rightarrow \mathcal{A} \subset H^{r+\sigma}. \]

Proof. Knowing that $\mathcal{A}$ is fully invariant and bounded in $H^r$, we split the solution $S(t)z$ with $z \in \mathcal{X}$ into the sum
\[ S(t)z = L(t)z + K(t)z, \]
where $L(t)z = (v(t), \partial_t v(t), \xi^t)$ and $K(t)z = (w(t), \partial_t w(t), \psi^t)$ solve the systems
\[ \begin{cases} A\partial_t v + A\partial_t v + Av + \int_0^\infty \mu(s)A\xi(s) \, ds = 0, \\ \partial_t \xi = T\xi + \partial_t v, \\ (v(0), \partial_t v(0), \xi^0) = z, \end{cases} \]

and
\[ \begin{cases} A\partial_t w + A\partial_t w + Aw + \int_0^\infty \mu(s)A\psi(s) \, ds = \gamma, \\ \partial_t \psi = T\psi + \partial_t w, \\ (w(0), \partial_t w(0), \psi^0) = 0, \end{cases} \]
Furthermore, since $r = h - f(u) - |\partial_t u|^r \partial_t u$. A direct application of Lemma A.1 together with the Gronwall lemma to the first system shows that the linear semigroup $L(t)$ decays exponentially in $H$, i.e.

$$\|L(t)z\|_H \leq ce^{-\omega t}, \quad (8.1)$$

for some $c = c(\mathfrak{X}) > 0$ and $\omega > 0$. Defining

$$E_{r+\sigma}(t) = \frac{1}{2} \|K(t)z\|_{H^{r+\sigma}},$$

Lemma A.1 applied to the second system provides the existence of a functional $\Lambda_{r+\sigma}$ satisfying

$$\frac{1}{2} E_{r+\sigma} \leq \Lambda_{r+\sigma} \leq 2E_{r+\sigma} \quad (8.2)$$

and

$$\frac{d}{dt} \Lambda_{r+\sigma} + \delta E_{r+\sigma} \leq \langle \gamma, \partial_t w \rangle_{r+\sigma} + \delta \langle \gamma, w \rangle_{r+\sigma}$$

for all $\delta > 0$ sufficiently small. We now exploit the embeddings\(^2\)

$$H^{1+r} \subset L^{\frac{2r}{1+r}}(\Omega) \subset L^{\frac{2}{1+r}}(\Omega)$$

and Lemma 7.2 to estimate the right-hand side as

$$-\langle |\partial_t u|^r \partial_t u, A^{r+\sigma} \partial_t w \rangle \leq \|\partial_t u\|_{L^{3r/(2r-1)}} \|\partial_t u\|_{L^{(1-2n)/(1+2r+2\sigma)}} \|A^{r+\sigma} \partial_t w\|_{L^{(1+2r+2\sigma)/(1+2r+2\sigma)}}$$

$$\leq c \|\partial_t u\|_{L^{6/(5+2r)}} \|\partial_t u\|_{L^{1+2\sigma}} \|\partial_t w\|_{1+r+\sigma}$$

$$\leq c \|\partial_t w\|_{1+r+\sigma}.$$}

Besides, due to (1.4), we have

$$-\langle f(u), A^{r+\sigma} \partial_t w \rangle \leq \|f(u)\|_{L^{6/(5-2r-2\sigma)}} \|A^{r+\sigma} \partial_t w\|_{L^{6/(1+2r+2\sigma)}}$$

$$\leq c(1 + \|u\|^{2r}_{1+r}) \|\partial_t w\|_{1+r+\sigma}$$

$$\leq c \|\partial_t w\|_{1+r+\sigma}.$$}

Furthermore, since $r + \sigma \leq \frac{1+r+\sigma}{2}$,

$$\langle h, A^{r+\sigma} \partial_t w \rangle \leq \|h\| \|A^{r+\sigma} \partial_t w\| \leq c \|h\| \|\partial_t w\|_{1+r+\sigma},$$

showing that

$$\langle \gamma, \partial_t w \rangle_{r+\sigma} \leq c \|\partial_t w\|_{1+r+\sigma}.$$}

Analogous computations provides the estimate

$$\delta \langle \gamma, w \rangle_{r+\sigma} \leq \delta c \|w\|_{1+r+\sigma}.$$}

We thus end up with the differential inequality

$$\frac{d}{dt} \Lambda_{r+\sigma} + \frac{\delta}{2} E_{r+\sigma} \leq c$$

for some $\delta > 0$. In light of (8.2), and recalling that $E_{r+\sigma}(0) = 0$, from the Gronwall lemma we infer that

$$\|K(t)z\|_{H^{r+\sigma}} \leq c, \quad (8.3)$$

for some $c = c(\mathfrak{X}) > 0$. By virtue of (8.1) and (8.3), we conclude that

$$\text{dist}_H(\mathfrak{X}, B_{r+\sigma}) = \text{dist}_H(S(t)\mathfrak{X}, B_{r+\sigma}) \leq ce^{-\omega t} \to 0,$$

\(^2\)If $r \geq \frac{1}{2}$ we exploit $H^{1+r} \subset L^\infty(\Omega)$.
Proof. We multiply (A.1) by (A.2) and ζ with initial data A lying on Λ, so that, in particular, this yields the inclusion Λ ⊂ B_{r+σ}.

Proof of Theorem 5.4. By reiterated applications of Lemma 8.1, in a finite number of steps we arrive to show that Λ is bounded in H^{r+σ} with r + σ = 1.

Proof of Proposition 5.5. Let η(t) = (u(t), ∂tu(t), η^t) be a CBT, that is, a solution lying on Λ. Fixed an arbitrary k > 0, let us consider the solution at time τ > 0 with initial data ζ(t – k)

where Λ_{r+σ} is a closed ball of H^{r+σ} of radius sufficiently large. In particular, this yields the inclusion Λ ⊂ B_{r+σ}.

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Appendix: Some technical results.

A.1. An auxiliary problem. Let r ∈ [0, 1]. For a sufficiently regular function γ = γ(t) on [0, ∞), let us consider the Cauchy problem in H^r

\begin{align*}
A∂_t u + A∂_s u + Au + \int_0^∞ μ(s)Aη(s) ds &= γ, \\
∂_s η &= Tη + ∂_su,
\end{align*}

with related energy

\[ E_r(t) = \frac{1}{2} [||u(t)||^2_{1+r} + ||∂_tu(t)||^2_{1+r} + ||η^t||^2_{M^r}] \]

Lemma A.1. For all δ > 0 small, there exists Λ_r satisfying

\[ \frac{1}{2} E_r ≤ Λ_r ≤ 2E_r \]

and

\[ \frac{d}{dt} Λ_r + δE_r ≤ ⟨γ, ∂_tu⟩_r + δ⟨γ, u⟩_r. \]

Proof. We multiply (A.1) by (∂_tu, η) in H^r × M^r, so obtaining

\[ \frac{d}{dt} E_r + ||∂_tu||^2_{1+r} = ⟨TA_2^η, A_2^η⟩_M + ⟨γ, ∂_tu⟩_r ≤ ⟨γ, ∂_tu⟩_r. \]

We now define the functionals

\[ Ψ_r(t) = ∫_0^∞ (∫_s^∞ μ(y) dy) ||η^t(s)||^2_{1+r} ds, \]

\[ Φ_r(t) = \frac{1}{2} ||u(t)||^2_{1+r} + ⟨u(t), ∂_tu(t)⟩_{1+r}, \]

which satisfy the bounds (see (1.7))

\[ 0 ≤ Ψ_r ≤ Θ||η||^2_{M^r}, \]

and

\[ |Φ_r| ≤ ||u||^2_{1+r} + \frac{1}{2} ||∂_tu||^2_{1+r}. \]
Collecting the inequalities above, we end up with

\[ \Lambda_r(t) = E_r(t) + \varepsilon \Psi_r(t) + \delta \Phi_r(t), \]

inequality (A.2) is easily seen to hold for every \( \varepsilon \leq \frac{1}{20} \) and \( \delta \leq \frac{1}{4} \). Taking the time derivative of \( \Psi_r \) we get

\[
\frac{d}{dt} \Psi_r + \frac{1}{2} \| \eta \|_{\mathcal{M}_r}^2 = -\frac{1}{2} \| \eta \|_{\mathcal{M}_r}^2 + 2 \int_0^\infty \left( \int_s^\infty \mu(y) \, dy \right) \langle \eta(s), \partial_t u \rangle_{1+r} \, ds \\
\leq -\frac{1}{2} \| \eta \|_{\mathcal{M}_r}^2 + 2 \Theta \sqrt{k} \| \eta \|_{\mathcal{M}_r} \| \partial_t u \|_{1+r} \\
\leq 2 \Theta^2 k \| \partial_t u \|_{1+r}.
\]

Besides, a multiplication of the first equation of (A.1) by \( A^* u \) provides

\[
\frac{d}{dt} \Phi_r + \frac{1}{2} \| u \|_{1+r}^2 = -\frac{1}{2} \| u \|_{1+r}^2 + \| \partial_t u \|_{1+r}^2 - \int_0^\infty \mu(s) \langle \eta(s), u \rangle_{1+r} \, ds + \langle \gamma, u \rangle_r \\
\leq \| \partial_t u \|_{1+r}^2 + \frac{k}{2} \| \eta \|_{\mathcal{M}_r}^2 + \langle \gamma, u \rangle_r.
\]

Collecting the inequalities above, we end up with

\[
\frac{d}{dt} \Lambda_r + \frac{\delta}{2} \| u \|_{1+r}^2 + (1 - 2\varepsilon \Theta^2 k - \delta) \| \partial_t u \|_{1+r}^2 + \frac{1}{2} (\varepsilon - \delta k) \| \eta \|_{\mathcal{M}_r}^2 \\
\leq \langle \gamma, \partial_t u \rangle_r + \delta \langle \gamma, u \rangle_r.
\]

Fixing \( \varepsilon \in \left(0, \frac{1}{20}\right] \) such that

\[ 1 - 2\varepsilon \Theta^2 k \geq \frac{1}{2}, \]

inequality (A.3) holds for every \( \delta > 0 \) small.

\[ \square \]

A.2. **Two lemmas.** We finally recall two results needed in the investigation. The first is a compactness lemma in the space \( \mathcal{M} \) proved in [26] (see Lemma 5.5 therein), while the second one is Theorem 3.1 from [9], written here in a suitable form for our scopes.

**Lemma A.2.** Let \( \Xi \) be a subset of \( \text{Dom}(T) \), and let \( r > 0 \). If

\[ \sup_{\eta \in \Xi} \left( \| \eta \|_{\mathcal{M}_r} + \| T \eta \|_{\mathcal{M}} \right) < \infty \]

and the map

\[ s \mapsto \sup_{\eta \in \Xi} \mu(s) \| \eta(s) \|_1^2 \]

belongs to \( L^1(\mathbb{R}^+) \), then \( \Xi \) is precompact in \( \mathcal{M} \).

**Lemma A.3.** Let \( \mathcal{B} \subset \mathcal{H} \) be a bounded absorbing set for \( S(t) \), and let \( r > 0 \). For every \( z \in \mathcal{B} \), assume there exist two operators \( V_z(t) \) and \( U_z(t) \) acting on \( \mathcal{H} \) and \( \mathcal{H}_r \), respectively, with the following properties:

(i) given any \( y \in \mathcal{B} \) and any \( x \in \mathcal{H}_r \) satisfying the relation \( y + x = z \),

\[ S(t) z = V_z(t) y + U_z(t) x; \]

(ii) there exists a positive function \( d_1 \) vanishing at infinity such that, for any \( y \in \mathcal{B} \),

\[ \sup_{z \in \mathcal{B}} \| V_z(t) y \|_{\mathcal{H}} \leq d_1(t) \| y \|_{\mathcal{H}}; \]
(iii) there exists a positive function $d_2$ vanishing at infinity such that, for any $x \in \mathcal{H}^r$,
$$
\sup_{z \in \mathcal{B}} \|U_z(t)x\|_{\mathcal{H}^r} \leq d_2(t)\|x\|_{\mathcal{H}^r} + Q(t),
$$
for some $Q(\cdot)$ independent of $x$.

Then, $\mathcal{B}$ is exponentially attracted by a closed ball $\mathcal{B}_r$ of $\mathcal{H}^r$ centered at zero; namely, there exist (strictly) positive constants $c, \theta$ such that
$$
dist_{\mathcal{H}}(S(t)\mathcal{B}, \mathcal{B}_r) \leq ce^{-\theta t}.
$$

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