In-vivo Imaging of Magnetic Fields Induced by Transcranial Direct Current Stimulation (tDCS) in Human Brain using MRI

Mayank V. Jog1,2, Robert X. Smith2, Kay Jann3,4, Walter Dunn5,6, Belen Lafon5, Dennis Truong5, Allan Wu2, Lucas Parra5, Marom Bikson5 & Danny J. J. Wang2,3

Transcranial direct current stimulation (tDCS) is an emerging non-invasive neuromodulation technique that applies mA currents at the scalp to modulate cortical excitability. Here, we present a novel magnetic resonance imaging (MRI) technique, which detects magnetic fields induced by tDCS currents. This technique is based on Ampere’s law and exploits the linear relationship between direct current and induced magnetic fields. Following validation on a phantom with a known path of electric current and induced magnetic field, the proposed MRI technique was applied to a human limb (to demonstrate in-vivo feasibility using simple biological tissue) and human heads (to demonstrate feasibility in standard tDCS applications). The results show that the proposed technique detects tDCS induced magnetic fields as small as a nanotesla at millimeter spatial resolution. Through measurements of magnetic fields linearly proportional to the applied tDCS current, our approach opens a new avenue for direct in-vivo visualization of tDCS target engagement.

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1BioMedical Engineering Inter-Departmental Program (BME-IDP), University of California Los Angeles, Los Angeles, California, United States.
2Laboratory of FMRI Technology (LOFT), Department of Neurology, University of California Los Angeles, Los Angeles, California, United States.
3Stevens Neuroimaging and Informatics Institute, University of Southern California, Los Angeles, California, United States.
4Department of Psychiatry, University of California Los Angeles, Los Angeles, California, United States.
5Department of Biomedical Engineering, The City College of The City University of New York, New York, United States.
6Correspondence and requests for materials should be addressed to D.J.J.W. (email: jwang71@gmail.com)
In parallel to identifying neural circuits modulated by tDCS, computational modeling has been used to predict brain regions the tDCS current passes through or directly engages. Based on a finite element human head model, this approach has been applied to derive the optimal electrode montage and dosage for tDCS, as well as the design of ring electrodes with focal distribution of tDCS current. However, the distribution of tDCS current is influenced by a host of interacting factors not fully accounted for by computational models. These include electrode geometry, electrical properties of tissue and cerebrospinal fluid (CSF), CSF flow, and complicated boundary conditions (due to the convoluted brain surface morphology). To date, estimates of tDCS current distribution remain theoretical and await experimental validation. In one approach, BOLD fMRI has been applied on post-mortem subjects to map tDCS effects without associated hemodynamic changes. However, the authors note that imaging physics quantitatively linking the BOLD fMRI signal to current density has yet to be developed. In another study, voltage-recording probes were placed in the head of a cadaver to record the distribution of tDCS current. However, this approach does not account for the effects of CSF flow and perfusion, as well as potential conductivity differences between cadaver and live tissue. At present, no in-vivo gold standard for mapping tDCS currents exists.

In this study, we present a novel MRI-based technique for direct visualization and quantification of the magnetic field changes induced by tDCS current. Detecting the magnetic field changes induced by tDCS is biologically significant since it can be applied as a marker to detect the current distribution and thereby the direct target engagement of tDCS. The proposed technique is based on Ampere’s law, which states that a direct current induces a linearly dependent magnetic field. The induced magnetic field along the static field of the MRI can be detected using field mapping. Exploiting the linear relationship between applied current and induced magnetic field, a concurrent tDCS-MRI experiment was performed where magnetic field maps were acquired for a range of tDCS currents (0–1.5mA, applied in a pseudo random order). Post acquisition, the observed fields were fit to the applied current within the framework of a general linear model (GLM). The slope of such a linear fit can be interpreted as the tDCS-induced field per unit applied-current with a confidence given by the goodness-of-fit.

The proposed MRI technique was first validated on a phantom where the current path and induced magnetic field was known. Subsequently, in-vivo feasibility in simple biological tissue was established with tDCS-MRI experiments on a human limb (calf), and the result was compared with a computational model of tDCS induced magnetic field changes. Finally, to demonstrate that this technique is practical for standard tDCS applications, the technique was applied to healthy subjects receiving tDCS with a bilateral motor cortex electrode montage. The results show that the proposed technique is able to detect magnetic field changes as small as a nanotesla (nT) with a spatial resolution of a few millimeters. Through measurements of magnetic fields that are linearly proportional to the applied tDCS currents (Ampere’s law), our approach opens a new avenue for direct visualization of tDCS target engagement. In contrast, existing experimental techniques use surrogate markers of the brain’s response (e.g., BOLD, ASL, EEG, MEG), measuring a secondary response to the applied tDCS which may extend beyond the site of stimulation due to brain networks.

**Results**

**Phantom Experiment.** In order to validate our technique, we designed a phantom that channels the tDCS current into a known path. The current distribution was used to predict the current induced magnetic fields, which were compared with the experimentally measured fields. Our phantom consisted of a standard cylindrical MRI phantom with two U-shaped tubes (‘A’ and ‘B’ in Fig. 1a) wrapped around it. Both tubes contained identical

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**Figure 1.** Setup and results of the Phantom experiment: (a) the phantom setup showing the induced magnetic fields intuited using Fleming's right hand rule; (b) simulated magnetic field; (c–e) show experimentally detected current-induced magnetic fields from the ‘Active’, ‘Sham’ and ‘–Active’ sessions respectively. The experimental results were consistent with simulations (Cross-voxel correlations between the slices shown for simulated and ‘Active’; ‘–Active’) were \( r = 0.84, p = 3.8 \times 10^{-267}, N = 989; r = -0.90, p = 2.3 \times 10^{-142}; N = 397 \).
electrolyte solutions and were made of plastic (a natural insulator). The ends of tube ‘A’ were connected to the
tDCS stimulator, whereas the ends of tube ‘B’ were open. Consequently, all applied currents were confined to tube
‘A’. With such a configuration, magnetic fields induced by applied currents can be intuited using Fleming’s right
hand rule (shown for the sagittal view in Fig. 1a). Tube ‘B’ served as a within-session ‘control’, carrying no applied
current at any time.

Quantitative estimates of the current-induced magnetic field were computed using a finite element implemen-
tation of the Biot-Savart law (Fig. 1b), which were plotted alongside experimental results of the ‘Active’ session
(Fig. 1c, thresholded at $p < 0.05$, Cluster corrected $\alpha < 0.05$). As can be clearly seen, current induced magnetic
fields detected by our technique are in close agreement with the simulation results ($r = 0.84; p = 3.8 \times 10^{-267};
N = 989$; cross-voxel correlation between slices shown in Fig. 1b,c). Data from a ‘Sham’ and ‘–Active’ session were
also analyzed. The ‘Sham’ session was a control experiment where the tDCS stimulator was switched off during
data acquisition. As expected, no significant current-induced fields were detected (Fig. 1d). In the ‘–Active’ ses-
sion, the polarity of applied currents was reversed (compared to ‘Active’), which should result in a sign reversal of
the induced magnetic fields while leaving the magnitudes intact (Ampere’s Law, Equation (1) in Methods). The
detected current-induced magnetic fields in the ‘–Active’ session are consistent with this prediction ($r = -0.90;
p = 2.3 \times 10^{-142}; N = 397$; cross-voxel correlation between slices shown in Fig. 1b,e).

Regions of interest (ROIs) consisting of the top (ROI1) and bottom (ROI2) halves of the current carrying
‘A’ tube (Fig. 2a) were selected from the same slice in all three sessions. Figure 2b–d show the average measured
fields within the ROI as a function of applied current for the ‘Active’, ‘Sham’ and ‘–Active’ sessions respectively.
Quantitatively, the measured fields per unit mA applied-current were found to be consistent with those calculated
from simulations (by comparing slopes or $\beta$’s of Fig. 2a with b, d respectively). No significant fields were induced by currents in the ‘Sham’ condition (c).

Limb Experiment. The purpose of this experiment was to evaluate our technique in an in-vivo setting
involving relatively simple and electrically conductive biological tissues – a human calf. Figure 3a illustrates the
experiment setup, with electrodes placed laterally on both sides of the left calf. Using the same experimental
paradigm as the Phantom experiment, current-induced magnetic fields along $B_z$ were measured for ‘Active’ and
‘Sham’ sessions respectively (Fig. 3b,c, thresholded to $p < 0.05$, Cluster corrected $\alpha < 0.05$). In the ‘Active’ ses-
sion, magnetic fields close to the cathode electrode were observed to decrease with current while an increase
of magnetic fields was observed on the ventral calf. No significant induced fields were detected for the ‘Sham’
session. Figure 3d shows corresponding scatter plots for the two clusters (identified with an asterisk ‘∗’ in Fig. 3b).
Measured current-induced fields were strongly correlated with the applied current in both clusters, with the magnitude of induced fields per unit applied-current in the range of 30–45 nT/mA.

We further compared the in-vivo results with simulated tDCS induced magnetic fields. The simulations were based on a finite element computational model of the human calf, utilizing tissue conductivity values from literature. In order to show the match between our experimental results and the simulated magnetic fields that are smooth in space, we had to apply a more liberal threshold of statistical significance for our experimental data (p < 0.1 and Cluster corrected at α < 0.1, Fig. 4). As can be seen in Fig. 4, the in-vivo detected magnetic fields match qualitatively well with the theoretically predicted magnetic fields in terms of their polarity, but show variations in spatial distribution (Spearman correlation between slices shown in Fig. 4: r = 0.43; p = 2.4 × 10−94; N = 2072 (middle row) and r = 0.20; p = 1.5 × 10−42; N = 4571 (bottom row)). Additionally, the magnitude of in-vivo detected magnetic fields was greater than those of simulated fields (which will be discussed below). No significant tDCS induced magnetic fields were detected for the ‘Sham’ session even with the more liberal threshold.

**Head Experiment.** Finally, we applied our technique on healthy volunteers receiving tDCS according to a common tDCS montage and standard stimulation parameters, with the anode placed over the right motor cortex and cathode over the left motor cortex (C4/C3, based on the 10–20 system) (Fig. 5a). The purpose of this experiment was to demonstrate the validity of the proposed technique for a commonly used tDCS setup. Using an experimental paradigm identical to the limb and phantom experiments, MRI field mapping data were collected for ‘Active’ and ‘Sham’ sessions (counterbalanced across 12 healthy subjects). Group level analyses identified consistently reduced magnetic fields (along Bz) at the left central sulcus under the cathode and in the precuneus region between the cathode and the anode electrodes (Fig. 5b). No significant induced magnetic fields were observed for the ‘Sham’ session (Fig. 5c). Scatter plots (Fig. 5d) show the average induced fields as a function of applied current for the two significant regions. Measured current-induced fields were negatively correlated with applied current, with the magnitude of the induced fields per unit applied-current in the range of 5–8 nT/mA. Note the wider spread of data points at 0 mA (also seen in the calf and phantom scatter plots) is due to the fact that there were 7 measurements at 0 mA versus 2 measurements at 0.5, 1 and 1.5 mA respectively.

Although voxel-wise group analysis did not show significant magnetic field changes under or around the anode electrode in the ‘Active’ session, region-of-interest (ROI) analysis based on the cortical location of C3/C4 electrodes revealed significant magnetic field reductions with applied tDCS current under both electrodes (−6.1 nT/mA, −4.4 nT/mA; p = 0.036, 0.044; for C3/C4 respectively, N = 12 subjects, see Supplemental Fig. S1). No such fields were detected for the ‘Sham’ session.

**Discussion**

**Feasibility and Validity of the Proposed Technique.** The key innovation of our technique is that it provides quantification of magnetic fields directly induced by tDCS currents as a means to visualize target engagement. This is in contrast to present in-vivo imaging approaches that use surrogate markers to record the brain’s neurovascular and neurophysiological responses to tDCS stimulation (e.g., BOLD/ASL fMRI, EEG and MEG ). Proof of concept was established through the phantom experiment where the measured current-induced magnetic field was in excellent agreement with simulations (r = 0.84, p = 3.8 × 10−267, N = 989). The phantom results also demonstrated excellent specificity as no significant magnetic fields were detected in either the within-session control (Tube ‘B’), or during the control session (‘Sham’). In its present implementation, our technique is capable...
of detecting fields as low as one nT per mA of applied current (Supplemental S1) with a spatial resolution of a few millimeters.

The limb experiment demonstrated in-vivo feasibility of our technique in a relatively simple and electrically conductive biological tissue. While no field changes were detected during the ‘Sham’ session, magnetic field changes greater than 30nT/mA were observed during the ‘Active’ session. The experimental results also qualitatively matched the theoretically predicted magnetic fields based on a finite element model of the human calf \( r = 0.43, p = 2.4 \times 10^{-94}; N = 2072 \) (middle row) and \( r = 0.20, p = 1.5 \times 10^{-42} \), \( N = 4571 \) (bottom row). No significant fields were detected for the ‘Sham’ session (Column 3).

Finally we performed the brain experiment with a common tDCS montage (bilateral-M1) on 12 healthy volunteers. A group level analysis revealed relatively weak (5–8nT/mA) yet statistically significant magnetic field reductions around the central sulcus (underneath the cathode) as well as in the precuneus region (around mid-way between the electrodes). Our observations are consistent with modeling studies which have predicted peak current densities to exist under the electrodes and for large electrodes (25–35 cm²) less than 10 cm apart, a single peak current density to exist between the electrodes. Moreover, the magnitude of the experimentally detected fields, 0–10 nT/mA, was found to be the same order as that of simulated fields reported in a recent study (although the study used a different cathode positioning). Furthermore, although significant field changes were not detected under or around the anode in voxel-wise group analysis, an ROI analysis (Supplemental Fig. S1 with the method described in Supplemental S5) revealed significant field changes under both electrodes (and none

**Figure 4.** Comparison of the experimental results with simulated current-induced magnetic fields in a human calf. Column 1 shows the experimental results from the ‘Active’ session, which matches qualitatively well with the simulations in Column 2 (Cross-voxel Spearman correlations between the slices shown for simulated and ‘Active’ were \( r = 0.43, p = 2.4 \times 10^{-94}; N = 2072 \) (middle row) and \( r = 0.20, p = 1.5 \times 10^{-42} \), \( N = 4571 \) (bottom row). No significant fields were detected for the ‘Sham’ session (Column 3).
during Sham). These field changes were also observed to have the same sign; which is intuitive given that the direction of tDCS current flow is the same (from anode to cathode) at both electrodes. However, it is not clear why the field changes were more significant under cathode than anode in our experiment. One potential explanation is the relatively large electrode size making the induced electromagnetic fields "diffuse", and such effect may be asymmetric between anode and cathode. With improved sensitivity of our technique (see below) and improved focality of tDCS montage (e.g., high-definition tDCS)\textsuperscript{20}, we will be able to evaluate such hypothesis in future studies.

**Advantages of the Proposed Technique.** The proposed approach for visualizing tDCS target engagement through its induced magnetic fields is appealing since the magnetic field is directly induced by and linearly proportional to the applied current (as described by Ampere’s law). Moreover, the physical constant involved in the relationship between magnetic field and direct current is highly stable across biological tissues (variation of magnetic permeability is on the order of ~ppm\textsuperscript{26}). In contrast, existing experimental techniques use surrogate markers of the brain’s response to tDCS stimulation (e.g., BOLD, ASL, EEG, MEG). These represent a secondary response to the applied stimulation, and may extend beyond the site of stimulation due to brain networks. Additionally, unlike the physical relationship between magnetic fields and applied current, the relationship between these markers and the applied tDCS current is highly complicated, and not easy to interpret.

In applications involving milliampere currents, the primary challenge for detecting current-induced magnetic fields is the weak signal relative to noise (SNR). Existing techniques to detect weak magnetic fields attempt to overcome the SNR limitation primarily through enhancing the ‘signal’, e.g., by increasing the current intensity and/or using time varying currents (~1 Hz or higher)\textsuperscript{27–29}. In contrast, our technique addresses the SNR limitation by statistically modeling out a range of ‘noise’ sources by exploiting the linear relationship between applied-current and induced magnetic fields, and is thus able to detect small magnetic fields with high sensitivity and spatial resolution.

In the proposed technique, a general linear model (GLM) was employed to model a set of magnetic field maps with applied current as well as systematic noise sources, similar to linear regression analysis commonly used in fMRI. Our choice of a GLM is supported by the fact that the relationship between applied current and measured magnetic field is linear (Ampere’s Law), and by ensuring the stochastic-noise distribution is Gaussian (see Supplemental S5, ‘Preprocessing’). Another advantage of using GLM is that many statistical methods developed for fMRI can be adapted for the proposed technique. For instance, in an experimental paradigm involving tasks, tDCS induced signals could be separated from task-related brain signals\textsuperscript{26} by designing the tDCS and task stimuli to be sufficiently orthogonal (similar to optimal stimulus design in fMRI). In one possible implementation, a study could involve two identical task sessions: one with ‘Active’ tDCS currents, and another with ‘Sham’. The contrast between ‘Active’ and ‘Sham’ sessions would detect magnetic field changes specifically induced by tDCS, controlling for task related brain-activity signals. The use of a GLM does assume (implicitly) the invariance of current path with different intensities of applied currents. This assumption is reasonable considering the small magnitude of currents used (will not induce neuronal discharge) and the fact that all currents were applied in the same direction.

**Potential Clinical Applications.** In the present study, we were able to visualize tDCS current-induced magnetic fields in human brains at the group level. This is a significant first step to experimental verification of target engagement. In addition to verification, our technique can also help advance focal stimulation, which has been shown to be more efficient than conventional tDCS\textsuperscript{31}. By identifying group-wide peak-intensity areas from...
imaging studies (performed for conventional tDCS), our technique can potentially (a) provide target engagement confirmation for a conventional tDCS trial; and if treatment effects are observed, (b) identify target sites for future studies with focal stimulations with a reasonable expectation of the same treatment effects. Once we reach the capability for reliable mapping of electromagnetic fields induced by tDCS in individual subjects with the proposed technical developments (see below), our technique may open the door to a new field of individualized, precise, noninvasive neuromodulation using tDCS.

**Limitations and Future Developments.** With the present implementation (single-channel coil and standard field mapping sequence), we were able to reliably detect significant field changes during the head experiment at the group level but not in individual subjects. To address this shortcoming, future studies will use faster field mapping sequences to increase the number of measurements per session (thereby increasing statistical power) together with multi channel coils to improve SNR. The increased SNR may also improve the sensitivity of the proposed technique (~1.2 nT/mA of the present implementation, see Supplemental S1). The capability to reliably map tDCS current-induced fields in individual subjects may also overcome the potential averaging effects of group analysis, given the variability of cortical geometry and current distribution across subjects, and allow direct comparison with computational models.

It should be noted that our present technique maps only the magnetic field changes along $B_z$. In the absence of additional information, mapping electric current requires measuring all three spatial components of the induced field. One possible solution is to map the induced fields of a subject in at least three different orientations, which may be feasible with an open magnet. Alternatively, constraining computational current prediction models with a single experimentally verified component of the induced field could improve the accuracy for predicting current distribution.

A promising direction for research involves integrating fMRI with our field mapping technique. While our technique uses the phase information in an MRI image, most existing fMRI methods use magnitude information. Since every MRI acquisition generates phase and magnitude images, it is conceivable that target engagement (through mapping tDCS induced magnetic fields) and ensuing neurophysiological effects (through BOLD/ASL fMRI) could be simultaneously measured during a single tDCS session. One such promising technique is ASL with dual-echo EPI32 readout to simultaneously map current induced fields, perfusion and blood oxygenation.

**Methods**

**Theory.** “*Electrical current induces Magnetic Fields*.“ In classical electrodynamics, Maxwell’s equations describe the generation and interaction of electrical and magnetic fields. In particular, Ampere’s law (Equation 1) describes that an applied electrical current induces a magnetic field

$$\nabla \times \vec{B} = \mu \vec{J} + \mu \frac{\partial \vec{E}}{\partial t}$$

(1)

Here, $\vec{B}$ is the induced magnetic field, $\vec{J}$ is applied tDCS current density, $t$ is time, $\mu$, $\varepsilon$ are physical constants (magnetic permeability and electrical permittivity respectively, of biological tissue), $\vec{E}$ is the electrical field and $\nabla$ is the curl operator (details provided in Supplemental S6). For direct current, as is the case of tDCS, the electric fields do not vary with time making the last term $\partial \vec{E}/\partial t$ zero. Consequently, the induced magnetic field is directly proportional to the applied tDCS current density (along an orthogonal direction).

“*MRI detects induced magnetic fields*.“ Magnetic resonance imaging (MRI) is able to map changes in magnetic field along the static magnetic field ($B_z$). Field disturbances perpendicular to $B_z$ are generally invisible to MRI, as a consequence of the fact that (a) the $B_z$ magnetic field is orders of magnitude larger than any typical disturbance and (b) magnetic fields add vectorially (Supplemental S2). Using MRI field mapping, field variations along $B_z$ can be measured as phase angles according to

$$\Phi_m = (\gamma \times \Delta B_z \times TE) \mod (2\pi)$$

(2)

where $\Phi_m$ is the measured phase angle between 0 and $2\pi$ radians, $\gamma$ is gyromagnetic ratio (a constant), $\Delta B_z$ is the field deviation along $B_z$ and $TE$ is the echo time. A practical aspect of phase measurement is that phase angles outside $(0, 2\pi)$ are mapped back onto this range causing a ‘wrap’ (represented by the modulo operation in Equation (2)). An acquired phase-map has to be unwrapped to calculate the correct phase to infer the underlying field.

**Simulation.** Simulations were employed to validate the proposed technique. Our first experiment involved a phantom specifically designed to confine the applied current to a known path. This enabled the calculation of the current-induced magnetic field using the Biot-Savart law:

$$\vec{B}(\vec{r}) = \frac{\mu}{4\pi} \oint_V \left( \vec{J} d\vec{V} \times (\vec{r} - \vec{r}_a) \right) / |\vec{r} - \vec{r}_a|^3$$

(3)

where $\vec{B}(\vec{r})$ is the magnetic field at the position $\vec{r}$, $\mu$ is the magnetic permeability, $\vec{J}$ and $\vec{r}_a$ are the current density and position vectors respectively of the finite volume element $dV$, and the integral sum is over the entire volume $V$. In the case of our second experiment (calf), the currents were calculated using a finite element model (FEM) solver. The implementation details of the finite element simulations are provided in Supplemental S3 (Phantom) and Supplemental S4 (Calf).
Experimental Design. All data were acquired on Siemens 3T MR scanners using single-channel Tx/Rx coils and a custom built MRI-compatible tDCS system. In-vivo data were acquired from 13 healthy participants (1M, 36 yrs, calf; 7M/5F, 29.7 ± 8.2 yrs, head). Subjects were screened for neurological/psychiatric disorders. Written informed consent was obtained from all participants. The study was approved by the Institutional Review Board (IRB) at the University of California Los Angeles. All experiments and data acquisition were performed in accordance with the guidelines and regulations set by the Institutional Review Board (IRB) at the University of California Los Angeles.

Each concurrent tDCS-MRI experiment consisted of two back-to-back sessions (‘Active’ and ‘Sham’) with a single-blinded design. The order of these sessions was counterbalanced across subjects for the head experiment. Each session consisted of 6 currents (and corresponding field mapping scans) applied in a pseudo random order interleaved with zero-current scans (a total of 13 field mapping scans per session, Fig. 6). Before each field mapping acquisition, current was ramped up and maintained for 20 sec. During the ‘Sham’ session, currents were ramped down back to zero before the MRI scan. In the Phantom experiment, an additional ‘–Active’ session was included where the direction of the applied currents was reversed. In all other aspects, ‘Sham’ and ‘–Active’ sessions were identical to ‘Active’.

Field mapping data was acquired using a dual-echo gradient-echo sequence with the following parameters: TE$_1$/TE$_2$ = 4.92/14.76 msec, TR = 1.15 sec, Matrix: 128 × 128, BW = 750 Hz/pix, FA = 25°, 65 slices, 2 × 2 × 3 mm$^3$ Voxel. For the calf experiment, the flip angle, total slices and voxel size were adjusted to 65°, 55 and 1.2 × 1.2 × 3 mm$^3$ respectively. Both magnitude and phase data were acquired from field mapping scans. A T1-weighted MPRAGE structural scan (TE$_1$ = 4.82 msec, TI = 1100 msec, TR = 2.17 sec, Matrix: 256 × 256, BW = 140 Hz/pix, FA = 7°, 192 slices, 1 × 1 × 1 mm$^3$) was also acquired.

General Linear Model Analysis. Measured phase was modeled as:

$$
\Phi_m = \Phi_{Current}(TE, i(s)) + \Phi_0(s) + \Phi_{Non-Current}(TE) + \Phi_{drif} (TE, s) + \Phi_{noise}
$$

(4)

where $\Phi_m$ is the measured phase, $\Phi_{Current}$ is the phase due to current-induced fields, $TE$ is the echo-time, “$s$” refers to the fact that the data is from the $s^{th}$ scan of the session and $i(s)$ is the current applied during the “$s$-th” scan. $\Phi_0$ is the baseline phase, $\Phi_{Non-Current}$ is the phase due to field deviations unrelated to applied current but steady between scans (e.g., off-resonance), $\Phi_{drif}$ is the phase due to inter-scan field-deviations caused by the time-varying drift of the main magnetic field and $\Phi_{noise}$ is the phase due to (Gaussian) noise.

Acquired phase data were fit to the applied current within the framework of a GLM. The slope of this fit was converted to the induced magnetic field per unit mA applied-current using Equation (2). Additional details of the concurrent tDCS-MRI system, data acquisition, data processing, modeling (including that of confounds) and subsequent statistical analysis are discussed in detail in Supplemental S5. By incorporating experimental parameters and hardware constraints ($TE$ and minimum detectable phase-angle respectively) within Equation (2), the theoretical detection limit of our technique in the present implementation was determined to be ~1.2 nT/mA (Supplemental S1).
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**Author Contributions**
M.V.J., R.X.S., K.J. and D.J.J.W. designed and performed the experiments. M.V.J., R.X.S., K.J., W.D. and D.J.J.W. analyzed data. M.V.J., W.D., A.W. and D.J.J.W. wrote the manuscript. B.L., D.T., L.P. and M.B. contributed simulation tools. All authors reviewed the manuscript.

**Additional Information**

**Supplementary information** accompanies this paper at http://www.nature.com/srep

**Competing financial interests:** Drs. Marom Bikson and Lucas Parra are co-inventors for patents on transcranial electric stimulation held by the City University of New York and hold shares in Soterix Medical Inc.

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