Existence and Ulam–Hyers stability of a kind of fractional-order multiple point BVP involving noninstantaneous impulses and abstract bounded operator

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Abstract

In this paper, we mainly study a kind of fractional-order multiple point boundary value problem involving noninstantaneous impulse and abstract bounded operator. The existence and uniqueness is obtained by the Banach contraction principle. And by applying direct analysis methods, we establish some conditions of the Ulam–Hyers stability for this problem. Finally, an interesting application example is given to illustrate the validity of the results.

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1 Introduction

As a useful mathematical model, the multiple point boundary value problem of fractional-order differential equation is used to describe many phenomena and processes such as in blood flow, chemical engineering, thermo-elasticity, underground water flow, population dynamics, and so on. The existence and attractivity of solutions for fractional differential boundary value problems is always a hot topic, and the latest research results can be found in the literature [1–6]. However, in practical applications, people pay more attention to whether a system is stable or not. So concepts and theories of stability such as those of Lyapunov, Lagrange, Poisson, Popov, and so forth, have been proposed. A kind of stability known as Ulam–Hyers stability has been put forward by Ulam and Hyers [7, 8]. This type of stability has been widely studied by many scholars since it was proposed. There have been many papers on this stability (see [9–20]).

It is well known that impulse phenomenon is universal and inevitable in some fields of natural science, engineering technology, and even social science. The most important type of impulse is called the noninstantaneous impulse. This type of impulsive process is not instantaneous, but takes some time to complete. For example, in a similar process, drugs are absorbed, diffused, and metabolized in the human body. The noninstantaneous impulses...
are common in pharmacokinetics, agricultural pest control, sustainable fisheries production, and wildlife conservation. In the functional differential equation, the instantaneous pulse only changes the behavior of the solution of the equation at the point of the pulse, while the noninstantaneous pulse changes the behavior of the solution of the equation on a continuous interval. In contrast, the study of a noninstantaneous impulse functional differential equation is more difficult than that of a differential equation. In recent years, the study of noninstantaneous impulsive fractional order differential systems has attracted the attention of some researchers, and some good results have been obtained (see [21–30]). However, relatively little research has been done on the fractional-order differential equation involving noninstantaneous impulses.

Inspired by the above reasons, this paper mainly considers the following fractional-order multiple point boundary value problem involving noninstantaneous impulse and abstract bounded operator of the form:

\[
\begin{aligned}
\begin{cases}
\mathcal{D}_I^\alpha x(t) = f(t, x(t), \mathcal{D}_I^\beta x(t)) & t \in (s_i, t_{i+1}] \cap J, i = 0, 1, \ldots, m, \\
x(t) = g_i(t, x(t)) & t \in (t_i, s_i] \cap J, i = 1, 2, \ldots, m, \\
x(0) = x(1) = x(\eta_{i+1}) = x(\xi_{i+1}) = 0, & \eta_{i+1}, \xi_{i+1} \in (s_i, t_{i+1}) \cap J, i = 0, 1, \ldots, m,
\end{cases}
\end{aligned}
\]

where \( J = [0, 1], 0 < \alpha < 1, 1 < \beta < 2, \mathcal{D}_I^\alpha \) stands for the Caputo fractional derivative of order \( \alpha \); \( \mathcal{A} \in C^2(\mathbb{R}, \mathbb{R}) \) is a bounded operator; \( f \in C^2(J \times \mathbb{R}^2, \mathbb{R}), g_i \in C([t_i, s_i] \times \mathbb{R}, \mathbb{R}) \) are called noninstantaneous impulsive functions, for all \( i = 1, 2, \ldots, m \). The impulsive points and boundary points satisfy \( 0 = s_0 < \eta_1 < \xi_1 < t_1 < s_1 < \eta_2 < \xi_2 < t_2 < \cdots < t_m < s_m < \eta_m < \xi_m < t_{m+1} = 1 \).

Furthermore, the investigation of (1.1) was also motivated by the work of Zada et al. [31]. They discussed nonlinear implicit fractional differential equations with noninstantaneous integral impulses as follows:

\[
\begin{aligned}
\begin{cases}
\mathcal{D}_I^\beta y(t) = f(t, y(t), \mathcal{D}_I^\beta y(t)) & t \in (t_k, s_k) \cap J, k = 0, 1, \ldots, m, 0 < \beta \leq 1, \\
y(t) = I_{t_k-s_k}^\gamma \xi_k(t, y(t)) & t \in (s_k, t_k) \cap J, k = 1, 2, \ldots, m, \\
y(0) = I_{0+}^\gamma y(t(y(t)),
\end{cases}
\end{aligned}
\]

where \( T > 0, J = [0, T], 0 = t_0 < s_0 < t_1 < s_1 < \cdots < t_m = T, \mathcal{D}_I^\beta \) stands the Caputo fractional derivative of order \( \beta \); \( f \in C(J \times \mathbb{R}^2, \mathbb{R}), \eta \in C([0, T] \times \mathbb{R}, \mathbb{R}), \xi_k \in C([s_k-1, t_k] \times \mathbb{R}, \mathbb{R}) \) are noninstantaneous impulsive functions, for all \( i = 1, 2, \ldots, m \); \( I_{t_k-s_k}^\gamma \) and \( I_{0+}^\gamma \) are given to fractional integrals, respectively. By the generalized Diaz–Margolis’s fixed point theorem, the authors obtained Ulam–Hyers, Ulam–Hyers–Rassias, and generalized Ulam–Hyers–Rassias stability for this problem.

Our aim is to study the existence, uniqueness, and Ulam-type stability for problem (1.1) in this paper. The rest of the paper is organized as follows. Section 2 contains some useful notations and lemmas. The main results are proved in Sect. 3. In Sect. 5, an example is given to illustrate our main results. Finally, we conclude with a discussion of the importance of the studied problem (1.1) and summarize our obtained results in Sect. 5.

2 Preliminaries

In this section, we introduce some necessary definitions and lemmas of fractional calculus and present preliminary results. At the same time, we need to define some Banach
spaces. Let $C(f, \mathbb{R})$ be the Banach space of all continuous functions from $f$ into $\mathbb{R}$ with the norm $\|x\|_C = \sup_{t \in f} |x(t)|$. To discuss the existence and Ulam–Hyers stability of solutions for problem (1.1), we need to introduce the space $X = PC^3(f, \mathbb{R})$ of piecewise continuous functions

$$X = PC^3(f, \mathbb{R}) = \left\{x \in C^3(f, \mathbb{R}) : x \in C([t_i, s_i], \mathbb{R}), x(t_i^+) \text{ and } x(s_i^-) \right\}$$

exist with $x(s_i^+) = x(s_i), i = 1, \ldots, m$.

Clearly, $X = PC^3(f, \mathbb{R})$ is a Banach spaces equipped with the norm

$$\|x\|_X = \max \left\{ \sup_{t \in f} |x(t)|, \max_{0 \leq i \leq m} \sup_{s_i < t \leq s_{i+1}} |D^3_{i+1} x(t)| \right\}.$$

**Definition 2.1 ([32])** The Riemann–Liouville fractional integral of order $\alpha > 0$ of a continuous function $f : [0, \infty) \to R$ is defined by

$$I^\alpha_0 f(t) = \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} f(s) \, ds,$$

provided that the right-hand side is pointwise defined on $[0, \infty)$.

**Definition 2.2 ([32])** The Riemann–Liouville fractional derivative of order $\alpha > 0$ of a continuous function $f : [0, \infty) \to R$ is defined by

$$D^\alpha_0 f(t) = \frac{1}{\Gamma(n-\alpha)} \frac{d^n}{dt^n} \int_0^t (t-s)^{n-\alpha-1} f(s) \, ds,$$

where $n - 1 < \alpha \leq n$, provided that the right-hand side is pointwise defined on $[0, \infty)$.

**Definition 2.3 ([32])** If $f \in C^n[0, \infty)$ and $\alpha > 0$, then the Caputo fractional derivative of order $\alpha$ is given by

$$cD^\alpha_0 f(t) = \frac{1}{\Gamma(n-\alpha)} \int_0^t (t-s)^{n-\alpha-1} f^{(n)}(s) \, ds,$$

where $n - 1 < \alpha \leq n$, provided that the right-hand side is pointwise defined on $[0, \infty)$.

**Lemma 2.1 ([9])** If $u \in C^n[0,1]$ and $n - 1 < p \leq n$, then

$$I_p^\alpha \left( I_0^\alpha u(t) \right) = u(t) - \sum_{k=0}^{n-1} \frac{u^{(k)}(0)}{k!} t^k.$$

To investigate the existence and Ulam–Hyers stability of solutions for the problem (1.1), we need to consider the impulsive integral nonlinear equation (2.1) as follows:

$$x(t) = \begin{cases} F_0(t) - \frac{\mu^{p+1} - \nu_{11}^p}{\zeta_1^{p+1}} F_0(\zeta_1) - \frac{\nu_{12}^{p+1} - \mu^{p+1}}{\zeta_1^{p+1}} F_0(\eta_1), & t \in [0, t_1], \\ g_i(t, x(s_i^+)), & t \in (t_i, s_i], i = 1, 2, \ldots, m, \\ F_i(t) - c_{1i}^p \nu_{11}^p - c_{12}^p \mu^p - c_{13}^p \zeta_1^p, & t \in (s_i, t_i+1], i = 1, 2, \ldots, m, \end{cases}$$

$$t \in [0, t_1],$$

$$t \in (t_i, s_i], i = 1, 2, \ldots, m, \quad t \in (s_i, t_i+1], i = 1, 2, \ldots, m,$$
where

\[ F_i(t) = \int_{s_i}^t (t - u)^{\alpha-1} \left( \int_{s_i}^u (u-s)^{\beta-1} f(s, x(s), D_s^\alpha x(s)) \, ds \right) \frac{du}{\Gamma(\alpha)} - (Ax)(u) \, du \]

\[ = F_i(0) \left[ \int_{s_i}^t f(u, x(u), D_u^\alpha x(u)) - (Ax)(u) \right](t), \]

\[ M_i = \frac{1}{\left( \eta_{i+1}^\alpha - \xi_{i+1}^\alpha \right) \left( \xi_{i+1}^\alpha - s_i^\alpha \right) - \left( \eta_{i+1}^\alpha - s_i^\alpha \right) \left( \eta_{i+1}^\alpha - s_i^\alpha \right)}, \]

\[ c_0 = M_i \left[ (\xi_{i+1}^\alpha - s_i^\alpha) F_i(\eta_{i+1}) - (\eta_{i+1}^\alpha - s_i^\alpha) F_i(\xi_{i+1}) - (\xi_{i+1}^\alpha - \eta_{i+1}^\alpha) \xi_{i+1} \left( s_i, x(t_i) \right) \right], \]

\[ c_2 = M_i \left[ (\xi_{i+1}^\alpha - s_i^\alpha) F_i(\xi_{i+1}) - (\eta_{i+1}^\alpha - s_i^\alpha) F_i(\xi_{i+1}) + \left( \xi_{i+1}^\alpha - \eta_{i+1}^\alpha \right) \xi_{i+1} \left( s_i, x(t_i) \right) \right], \]

\[ c_3 = M_i \left[ (\xi_{i+1}^\alpha - s_i^\alpha) F_i(\eta_{i+1}) - \left( \eta_{i+1}^\alpha - s_i^\alpha \right) F_i(\xi_{i+1}) - \left( \xi_{i+1}^\alpha - \eta_{i+1}^\alpha \right) \xi_{i+1} \left( s_i, x(t_i) \right) \right]. \]

**Lemma 2.2** Assume that \( A \in C^2(\mathbb{R}, \mathbb{R}) \) is a bounded operator, and \( f \in C^1(J \times \mathbb{R}^2, \mathbb{R}) \). Then \( x(t) \in X \) is a solution of the problem (1.1) if and only if \( x(t) \in X \) is also a solution of the integral equation (2.1).

**Proof** Assume that \( x(t) \in X \) is a known solution of (1.1). When \( t \in [s_0, t_1] = [0, t_1] \), according to Lemma 2.1, we have

\[ x(t) = \int_0^t (t-u)^{\alpha-1} \left( \int_0^u (u-s)^{\beta-1} f(s, x(s), D_s^\alpha x(s)) \, ds \right) \frac{du}{\Gamma(\alpha)} - c_01 \frac{t^\alpha}{\Gamma(\alpha + 2)} - c_02 \frac{t^\alpha}{\Gamma(\alpha + 1)} - c_03. \]  

(2.2)

Using the conditions \( x(0) = x(\xi_1) = 0 \), we obtain

\[ c_01 = \Gamma(\alpha + 2) \eta_1^{\alpha+1} F_0(\xi_1) - \xi_1^{\alpha+1} F_0(\eta_1) \frac{\eta_1^{\alpha+1} - \xi_1^{\alpha+1}}{\xi_1^{\alpha+1} - \eta_1^{\alpha+1}}, \quad c_02 = \Gamma(\alpha + 1) \xi_1^{\alpha+1} F_0(\eta_1) - \eta_1^{\alpha+1} F_0(\xi_1) \frac{\xi_1^{\alpha+1} - \eta_1^{\alpha+1}}{\xi_1^{\alpha+1} - \eta_1^{\alpha+1}}, \]

\[ c_03 = 0. \]

Substituting \( c_01, c_02, \) and \( c_03 \) into (2.2), we get

\[ x(t) = F_0(t) - \frac{t^\alpha + 1 - t^\alpha \eta_1}{\xi_1^{\alpha+1} - \eta_1^{\alpha+1}} F_0(\xi_1) - \frac{t^\alpha \xi_1 - t^\alpha + 1}{\xi_1^{\alpha+1} - \eta_1^{\alpha+1}} F_0(\eta_1). \]

When \( t \in (t_1, s_1] \), it follows from (2.1) that

\[ x(t) = g_1(t, x(t_1)). \]

When \( t \in (s_1, t_2] \), from Lemma 2.1, we have

\[ x(t) = \int_{s_1}^t (t-u)^{\alpha-1} \left( \int_{s_1}^u (u-s)^{\beta-1} f(s, x(s), D_s^\alpha x(s)) \, ds \right) \frac{du}{\Gamma(\alpha)} - c_{11} \frac{t^\alpha}{\Gamma(\alpha + 2)} - c_{12} \frac{t^\alpha}{\Gamma(\alpha + 1)} - c_{13}. \]  

(2.3)
In view the conditions $x(s_1) = x(s_1^*)$ and $x(\xi_2) = x(\eta_2) = 0$, we derive that

\[
\begin{align*}
&c_1 t^\alpha + c_2 t^{\alpha+1} + c_3 = g_1(s_1, x(t_1)), \\
&c_1 t^\alpha + c_2 t^{\alpha+1} + c_3 = F_1(\eta_2), \\
&c_1 t^\alpha + c_2 t^{\alpha+1} + c_3 = F_1(\xi_2),
\end{align*}
\]

which implies that

\[
\begin{align*}
c_{11} &= \Gamma(\alpha + 2)M_1\left[ (\xi_2^\alpha - s_1^\alpha)(F_1(\eta_2) - g_1(s_1, x(t_1))) ight. \\
&\quad - \left( \eta_2^\alpha - s_1^\alpha \right)(F_1(\xi_2) - g_1(s_1, x(t_1)))], \\
c_{12} &= \Gamma(\alpha + 1)M_1\left[ (\eta_2^\alpha - s_1^\alpha)(F_1(\xi_2) - g_1(s_1, x(t_1))) ight. \\
&\quad - \left( \xi_2^\alpha - s_1^\alpha \right)(F_1(\eta_2) - g_1(s_1, x(t_1)))], \\
c_{13} &= M_1\left[ (\xi_2^\alpha s_1^\alpha - s_1^\alpha)(F_1(\eta_2) - g_1(s_1, x(t_1))) ight. \\
&\quad - \left( \eta_2^\alpha s_1^\alpha - s_1^\alpha \right)(F_1(\xi_2) - g_1(s_1, x(t_1)))].
\end{align*}
\]

Substituting $c_{11}$, $c_{12}$, and $c_{13}$ into (2.3), we get

\[
x(t) = F_1(t) - c_{11}^\alpha t^\alpha - c_{12}^\alpha t^{\alpha+1} - c_{13}^\alpha,
\]

where

\[
\begin{align*}
c_{11}^\alpha &= M_1\left[ (\xi_2^\alpha - s_1^\alpha)F_1(\eta_2) - (\eta_2^\alpha - s_1^\alpha)F_1(\xi_2) - (\xi_2^\alpha - \eta_2^\alpha)g_1(s_1, x(t_1))] \\
c_{12}^\alpha &= M_1\left[ (\eta_2^\alpha - s_1^\alpha)F_1(\xi_2) - (\xi_2^\alpha - s_1^\alpha)F_1(\eta_2) + (\xi_2^\alpha - \eta_2^\alpha)g_1(s_1, x(t_1))] \\
c_{13}^\alpha &= M_1\left[ (\xi_2^\alpha s_1^\alpha - s_1^\alpha)F_1(\eta_2) - (\eta_2^\alpha s_1^\alpha - s_1^\alpha)F_1(\xi_2) - (\xi_2^\alpha s_1^\alpha - \eta_2^\alpha s_1^\alpha)g_1(s_1, x(t_1))].
\end{align*}
\]

Repeating the above arguments, we obtain

\[
x(t) = g_i(t, x(t_i)), \quad t \in (t_i, s_i), i = 2, 3, \ldots, m, \\
x(t) = F_i(t) - c_{i1}^\alpha t^\alpha - c_{i2}^\alpha t^{\alpha+1} - c_{i3}^\alpha, \quad t \in (s_i, t_{i+1}), i = 2, 3, \ldots, m.
\]

Thus $x(t) \in X$ satisfies (2.1).

Now we shall show that if $x(t) \in X$ is a solution of (2.1), then $x(t) \in X$ is also a solution of (1.1). In fact, let $x(t) \in X$ be a solution of (2.1). When $t \in [0, t_1]$, taking the Caputo fractional derivative of order $\alpha$ on both sides of the first equation of (2.1), we obtain

\[
^C D_0^\alpha x(t) = ^C D_0^\alpha F_0(t) - \frac{F_0(t) - F_0(s_1)}{\xi_1^\alpha - \eta_1^\alpha} (t^\alpha - t^\alpha s_1) - \frac{F_0(t) - F_0(s_1)}{\xi_1^\alpha - \eta_1^\alpha} (t^\alpha s_1 - t^\alpha s_1) \\
= \beta \left[ f(t, x(t), ^C D_0^\alpha x(t)) - (Ax)(t) - \frac{F_0(t)}{\xi_1^\alpha - \eta_1^\alpha} (\Gamma(\alpha + 2) - \Gamma(\alpha + 1) s_1) \\
- \frac{F_0(s_1)}{\xi_1^\alpha - \eta_1^\alpha} (\Gamma(\alpha + 1) s_1 - \Gamma(\alpha + 2)),
\right.
\]

(2.4)
which implies that
\[
\mathcal{D}_0^\beta x(t) + (Ax)(t) = f(t, x(t), \mathcal{D}_0^\alpha x(t)) - \frac{F_0(\zeta_1)}{\zeta_1^{\alpha+1} - \zeta_1^{\alpha+1}} (\Gamma(\alpha + 2) - \Gamma(\alpha + 1)\eta_1) \\
- \frac{F_0(\eta_1)}{\zeta_1^{\alpha+1} - \zeta_1^{\alpha+1}} (\Gamma(\alpha + 1)\zeta_1 - \Gamma(\alpha + 2)).
\] (2.5)

Computing the Caputo fractional derivative of order $\beta$ on both sides of (2.5), we derive
\[
\mathcal{D}_0^\beta (\mathcal{D}_0^\alpha x(t) + (Ax)(t)) = f(t, x(t), \mathcal{D}_0^\alpha x(t)) ,
\]
that is,
\[
\mathcal{D}_0^\beta, (\mathcal{D}_0^\alpha + (A)x(t)) = f(t, x(t), \mathcal{D}_0^\alpha, x(t)).
\] (2.6)

It follows from the first equation of (2.1) that
\[
x(0) = x(\eta_1) = x(\zeta_1) = 0.
\] (2.7)

When $t \in (s_i, t_{i+1}]$, $i = 1, 2, \ldots, m$, by employing similar arguments, as those used to obtain (2.4)–(2.7), on the third equation of (2.1), we get
\[
\mathcal{D}_{s_i}^\beta (\mathcal{D}_{s_i}^\alpha + A)x(t) = f(t, x(t), \mathcal{D}_{s_i}^\alpha x(t)),
\]
\[
x(\eta_i) = x(\zeta_i) = 0.
\] (2.9)

When $t \in (t_i, s_i]$, $i = 1, 2, \ldots, m$, we notice that the second equation of (1.1) and (2.1) have the same expression. Thus we verify that $x(t) \in X$ also satisfies (1.1). The proof is completed.

Next we state the Ulam–Hyers stability concept and some facts.

Let $y \in X$ and $\varepsilon > 0$. Consider the following inequality:
\[
\left\{ \begin{array}{l}
\mathcal{D}_{s_i}^\beta (\mathcal{D}_{s_i}^\alpha + A)y(t) - f(t, y(t), \mathcal{D}_{s_i}^\alpha y(t)) \leq \varepsilon, \quad t \in (s_i, t_{i+1}], \\
|y(t) - g(t, y(t))] \leq \varepsilon, \quad t \in (t_i, s_i].
\end{array} \right.
\] (2.10)

**Definition 2.4** The problem (1.1) is Ulam–Hyers stable if for a given $\varepsilon > 0$ and for each solution $y \in X$ of the inequality (2.10), there exist a constant $c_{f, \alpha, \beta, g} > 0$ and a solution $x \in X$ of the problem (1.1) such that
\[
|y(t) - x(t)| \leq c_{f, \alpha, \beta, g}\varepsilon.
\]

**Remark 2.1** Assume that $A \in C^2(\mathbb{R}, \mathbb{R})$ is a bounded operator, and $f \in C^1(J \times \mathbb{R}^2, \mathbb{R})$. A function $y \in X$ is a solution of the inequality (2.10) if and only if there exist a function $B(t) \in X$ and a sequence $\{B_i\}_{i=1}^m$ such that
(i) $|B(t)| \leq \varepsilon$, $t \in J$ and $|B_i| \leq \varepsilon$, $i = 1, 2, \ldots, m$;
(ii) $\mathcal{D}_{s_i}^\beta (\mathcal{D}_{s_i}^\alpha + A)y(t) = f(t, y(t), \mathcal{D}_{s_i}^\alpha y(t)) + B(t)$;
(iii) $y(t) = g(t, y(t)) + B_i$, $i = 1, 2, \ldots, m$. 
Lemma 2.3 Assume that $A \in C^2(\mathbb{R}, \mathbb{R})$ is a bounded operator, and $f \in C^1(f \times \mathbb{R}^2, \mathbb{R})$. If the function $y \in X$ is a solution of inequality (2.10), then $y$ is a solution of the following inequality:

$$
|y(t) - F_0(t) + \frac{e^{s_{i+1} - s_{i}}}{\alpha_i + 1} F_0(\zeta_i) + \frac{e^{s_{i+1} - s_{i}}}{\beta_i - \xi_i + 1} F_0(\eta_i)| \\
\leq \frac{e}{(\alpha_i + 1)} \left( \frac{\zeta_i^{\alpha_i} + \frac{\xi_i - \eta_i}{\alpha_i - \beta_i} \eta_i^{\alpha_i}}{\eta_i^{\alpha_i}} \right), \quad t \in [0, t_1],
$$

$$
|y(t) - g_i(t, x(t_i))| \leq \epsilon, \quad t \in (s_i, t_1], i = 1, 2, \ldots, m,
$$

$$
|y(t) - F_i(t) + c_i^{\alpha_i} + c_i^{\beta_i} + c_i^{33}| \\
\leq \frac{e}{(\alpha_i + 1)} \left( \frac{\zeta_i^{\alpha_i} + \frac{\xi_i - \eta_i}{\alpha_i - \beta_i} \eta_i^{\alpha_i}}{\eta_i^{\alpha_i}} \right) + |M_c|_{i=1}^{\alpha_i} \\
\times \left[ (\zeta_i^{\alpha_i} - \eta_i^{\alpha_i}) + (\eta_i^{\alpha_i} - s_i) \right] + |M_c|_{i=1}^{\alpha_i} \left[ (\zeta_i^{\alpha_i} - \eta_i^{\alpha_i}) \right] + |M_c|_{i=1}^{\alpha_i} \left[ (\zeta_i^{\alpha_i} - \eta_i^{\alpha_i}) \right] + |M_c|_{i=1}^{\alpha_i} \left[ (\zeta_i^{\alpha_i} - \eta_i^{\alpha_i}) \right], \quad t \in (s_i, t_1], i = 1, 2, \ldots, m.
$$

Proof According to Remark 2.1, we have

$$
\begin{align*}
&\left\{ \begin{array}{ll}
\frac{^cD}{D}y + Ay(t) = f(t, y(t), ^cDy, y(t)) + B(t), & t \in (s_i, t_1], i = 0, 1, \ldots, m, \\
y(t) = g_i(t, y(t)), & t \in (s_i, s_i], i = 0, 1, \ldots, m, \\
y(0) = y(T) = y(\xi_i) = y(\eta_i) = 0, & \eta_i, \xi_i \in (s_i, t_1), i = 0, 1, \ldots, m.
\end{array} \right.
\end{align*}
$$

By Lemma 2.2 and (2.12), we obtain

$$
y(t) = \left\{ \begin{array}{ll}
\widetilde{F}_i(t) - \frac{e^{s_{i+1} - s_{i}}}{\alpha_i + 1} \widetilde{F}_0(\zeta_i) - \frac{e^{s_{i+1} - s_{i}}}{\beta_i - \xi_i + 1} \widetilde{F}_0(\eta_i), & t \in [0, t_1], \\
g_i(t, y(t)) + B_i, & t \in (s_i, s_i], i = 1, 2, \ldots, m, \\
\widetilde{F}_i(t) - c_i^{\alpha_i} - c_i^{\beta_i} - c_i^{33}, & t \in (s_i, t_1], i = 1, 2, \ldots, m.
\end{array} \right.
$$

where

$$
\widetilde{F}_i(t) = \int_{s_i}^{t} \frac{(u - s)^{\alpha_i - 1}}{\Gamma(\alpha_i)} \left( \int_{s_i}^{u} \frac{(u - s)^{\beta_i - 1}}{\Gamma(\beta_i)} \left( f(s, y(s), ^cDy, y(s)) + B(s) \right) ds - (Ay)(u) \right) du,
$$

$$
c_i = M_c \left[ \left( \zeta_i^{\alpha_i} - \eta_i^{\alpha_i} \right) \right] + M_c \left[ \left( \zeta_i^{\alpha_i} - \eta_i^{\alpha_i} \right) \right] + M_c \left[ \left( \zeta_i^{\alpha_i} - \eta_i^{\alpha_i} \right) \right].
$$

It is worth noticing that the Beta function $B(\cdot, \cdot)$ will be extensively used in the following calculation. So we introduce it as follows:

$$
B(\beta + 1, \alpha) = \int_0^1 (1 - u)^{\alpha - 1} u^\beta du = \frac{\Gamma(\alpha)\Gamma(\beta + 1)}{\Gamma(\alpha + \beta + 1)},
$$

$$
\int_0^1 (t - u)^{\alpha - 1} \int_0^u (u - s)^{\beta - 1} ds du = \int_0^1 (t - u)^{\alpha - 1} u^\beta du = \frac{\Gamma(\alpha)\Gamma(\beta + 1)}{\Gamma(\alpha + \beta + 1)} t^\alpha u^\beta.
$$
When $t \in [0, t_1]$, we have

\[
\begin{aligned}
|y(t) - F_0(t) + \frac{t^{\alpha+1} - t^\alpha \eta_1}{\zeta_1^{\alpha+1} - \zeta_1^\alpha}F_0(t_1) + \frac{t^{\alpha} \zeta_1 - t^{\alpha+1}}{\xi_1 \eta_1^\alpha - \eta_1^{\alpha+1}}F_0(\eta_1)|
\end{aligned}
\]

\[
= \int_0^t \frac{t - u}{\Gamma(\alpha)} \int_0^u \frac{(u - s)^{\beta-1}}{\Gamma(\beta)} |B(s)| \ ds \ du
\]

\[
- \frac{t^{\alpha+1} - t^\alpha \eta_1}{\zeta_1^{\alpha+1} - \zeta_1^\alpha} \int_0^t \frac{t - u}{\Gamma(\alpha)} \int_0^u \frac{(u - s)^{\beta-1}}{\Gamma(\beta)} |B(s)| \ ds \ du
\]

\[
- \frac{t^{\alpha} \zeta_1 - t^{\alpha+1}}{\xi_1 \eta_1^\alpha - \eta_1^{\alpha+1}} \int_0^t \frac{t - u}{\Gamma(\alpha)} \int_0^u \frac{(u - s)^{\beta-1}}{\Gamma(\beta)} |B(s)| \ ds \ du
\]

\[
\leq \frac{\varepsilon^{\alpha+\beta}}{\Gamma(\alpha + \beta + 1)} \frac{\varepsilon \xi_1^{\alpha+\beta}}{\Gamma(\alpha + \beta + 1)} \frac{t^{\alpha+1} - t^\alpha \eta_1}{\zeta_1^{\alpha+1} - \zeta_1^\alpha} \frac{t^{\alpha} \eta_1^{\alpha+1}}{\xi_1 \eta_1^\alpha - \eta_1^{\alpha+1}} + \frac{\varepsilon^{\alpha+\beta}}{\Gamma(\alpha + \beta + 1)} \frac{t^{\alpha} \zeta_1 - t^{\alpha+1}}{\xi_1 \eta_1^\alpha - \eta_1^{\alpha+1}}
\]

When $t \in (t_i, s_i]$, $i = 1, 2, \ldots, m$, we get

\[
|y(t) - g(t, y(t))| = |B_i| \leq \varepsilon.
\]

When $t \in (s_i, t_{i+1}]$, $i = 1, 2, \ldots, m$, it follows that

\[
|y(t) - F_i(t) + c_1^{\alpha+1} + c_2 t^\alpha + c_3|
\]

\[
= \int_{s_i}^t \frac{t - u}{\Gamma(\alpha)} \int_{s_i}^u \frac{(u - s)^{\beta-1}}{\Gamma(\beta)} |B(s)| \ ds \ du - M_1 t^{\alpha+1} \int_{s_i}^{\epsilon_1} (\zeta_1^{\alpha+1} - \zeta_1^\alpha) (\tilde{F}_i(\eta_1^{\alpha+1}) - F(\eta_1^{\alpha+1}))
\]

\[
- (\eta_1^{\alpha+1} - \zeta_1^\alpha) (\tilde{F}_i(\zeta_1^{\alpha+1}) - F(\zeta_1^{\alpha+1})) - M_1 t^\alpha \int_{s_i}^{\epsilon_1} (\eta_1^{\alpha+1} - \zeta_1^\alpha) (\tilde{F}_i(\eta_1^{\alpha+1}) - F(\eta_1^{\alpha+1}))
\]

\[
- (\eta_1^{\alpha+1} - \zeta_1^\alpha) (\tilde{F}_i(\zeta_1^{\alpha+1}) - F(\zeta_1^{\alpha+1})) - (\eta_1^{\alpha+1} - \zeta_1^\alpha) (\tilde{F}_i(\zeta_1^{\alpha+1}) - F(\zeta_1^{\alpha+1}))
\]

\[
\leq \int_{s_i}^t \frac{t - u}{\Gamma(\alpha)} \int_{s_i}^u \frac{(u - s)^{\beta-1}}{\Gamma(\beta)} |B(s)| \ ds \ du
\]

\[
+ M_1 t^{\alpha+1} \int_{s_i}^{\epsilon_1} \frac{(\zeta_1^{\alpha+1} - \zeta_1^\alpha)}{\Gamma(\alpha)} \int_{s_i}^u \frac{(u - s)^{\beta-1}}{\Gamma(\beta)} |B(s)| \ ds \ du
\]

\[
+ (\eta_1^{\alpha+1} - \zeta_1^\alpha) \int_{s_i}^{\epsilon_1} \frac{(\zeta_1^{\alpha+1} - \zeta_1^\alpha)}{\Gamma(\alpha)} \int_{s_i}^u \frac{(u - s)^{\beta-1}}{\Gamma(\beta)} |B(s)| \ ds \ du
\]

\[
+ M_1 t^\alpha \int_{s_i}^{\epsilon_1} \frac{(\eta_1^{\alpha+1} - \zeta_1^\alpha)}{\Gamma(\alpha)} \int_{s_i}^u \frac{(u - s)^{\beta-1}}{\Gamma(\beta)} |B(s)| \ ds \ du
\]
Thus we conclude that the inequality (2.11) holds. The proof is completed. \(\square\)

### 3 Existence and Ulam–Hyers stability

In this section, we shall discuss the existence and Ulam–Hyers stability for the problem (1.1). Now we introduce some assumptions to ensure that the problem (1.1) has a unique solution which is Ulam–Hyers stable. So consider

\((H_1)\) \(f \in C^1(I \times \mathbb{R}^2, \mathbb{R})\) and there exist some constants \(L_{1f}, L_{2f} > 0\) such that

\[
|f(t, \omega_1, \overline{\omega}_1) - f(t, \omega_2, \overline{\omega}_2)|
\leq L_{1f}|\omega_1 - \omega_2| + L_{2f}|\overline{\omega}_1 - \overline{\omega}_2|, \quad t \in I, \omega_1, \overline{\omega}_1, \omega_2, \overline{\omega}_2 \in \mathbb{R};
\]
(H2) \( g_i \in C(t_i, s_i] \times \mathbb{R}, \mathbb{R}) \) and there exist some constants \( L_{g_i} > 0, i = 1, 2, \ldots, m \) such that

\[
|g_i(t, \omega) - g_i(t, \omega_1)| \leq L_{g_i} |\omega - \omega_1|, \quad t \in (t_i, s_i], \omega, \omega_1 \in \mathbb{R};
\]

(H3) \( A \in C^2(\mathbb{R}, \mathbb{R}) \) and there exists a constant \( L_A > 0 \) such that

\[
|Ax - Ay| \leq L_A |x - y|, \quad t \in J, x, y \in \mathbb{R};
\]

(H4) \( 0 < \lambda < 1, \) where \( \lambda = \max\{\lambda_0, \lambda_1, \ldots, \lambda_m, \mu_0, \mu_1, \ldots, \mu_m, L_{g_1}, \ldots, L_{g_m}\}, \)

\[
\lambda_0 = \frac{L_{j_1} + L_{j_2}}{\Gamma(\alpha + \beta + 1)} \left( t_1^{\alpha + \beta} + \frac{t_1^{\alpha + 1} - t_1^\alpha \eta_1}{\zeta_1^{\alpha + \beta} + \eta_1^{\alpha + 1} \xi_1^{\alpha + \beta}} + \frac{t_1^{\alpha + 1} - t_1^\alpha \xi_1}{\eta_1^{\alpha + 1} \zeta_1^{\alpha + \beta} - \eta_1^{\alpha + 1} \xi_1^{\alpha + \beta}} \right)
\]

\[
+ \frac{L_A}{\Gamma(\alpha + 1)} \left( t_1^{\alpha + 1} - t_1^\alpha \eta_1 \xi_1^{\alpha + \beta} + \frac{t_1^{\alpha + 1} - t_1^\alpha \xi_1 \eta_1}{\eta_1^{\alpha + 1} \zeta_1^{\alpha + \beta} - \eta_1^{\alpha + 1} \xi_1^{\alpha + \beta}} \right),
\]

\[
\mu_0 = (L_{j_1} + L_{j_2}) \left[ \frac{t_1^{\beta}}{\Gamma(\alpha + \beta + 1)} + \frac{1}{\Gamma(\alpha + \beta + 1)} \left( t_1^{\beta}(\alpha + 2) - \Gamma(\alpha + 1) \eta_1 \xi_1^{\alpha + \beta} \right) \right] + L_A \left[ 1 + \frac{1}{\Gamma(\alpha + 1)} \right] \left( t_1^{\beta} \Gamma(\alpha + 2) - \Gamma(\alpha + 1) \eta_1 \xi_1^{\alpha + \beta} \right) \right] \left( t_1^{\beta} \Gamma(\alpha + 2) - \Gamma(\alpha + 1) \eta_1 \xi_1^{\alpha + \beta} \right),
\]

\[
\lambda_i = \frac{L_{j_1} + L_{j_2}}{\Gamma(\alpha + \beta + 1)} \left( t_1^{\alpha + \beta} + |M_i| t_1^{\alpha + 1} \left( (\xi_1^{\alpha + 1} - \sigma_i^{\alpha + 1}) \eta_1^{\alpha + \beta} + \eta_1^{\alpha + 1} \xi_1^{\alpha + \beta} \right) + |M_i| \left( \xi_1^{\alpha + 1} \eta_1^{\alpha + 1} \right) \right)
\]

\[
+ \frac{L_A}{\Gamma(\alpha + 1)} \left( t_1^{\alpha + 1} - t_1^\alpha \eta_1 \xi_1^{\alpha + \beta} + \frac{t_1^{\alpha + 1} - t_1^\alpha \xi_1 \eta_1}{\eta_1^{\alpha + 1} \zeta_1^{\alpha + \beta} - \eta_1^{\alpha + 1} \xi_1^{\alpha + \beta}} \right),
\]

\[
\mu_i = (L_{j_1} + L_{j_2}) \left( \frac{t_1^{\beta}}{\Gamma(\alpha + \beta + 1)} + \frac{|M_i| \Gamma(\alpha + 2)}{\Gamma(\alpha + \beta + 1)} \right) \left( (\xi_1^{\alpha + 1} - \sigma_i^{\alpha + 1}) \eta_1^{\alpha + \beta} + \eta_1^{\alpha + 1} \xi_1^{\alpha + \beta} \right)
\]

\[
+ \frac{|M_i| \Gamma(\alpha + 2)}{\Gamma(\alpha + \beta + 1)} \left( (\xi_1^{\alpha + 1} - \sigma_i^{\alpha + 1}) \eta_1^{\alpha + \beta} + \eta_1^{\alpha + 1} \xi_1^{\alpha + \beta} \right) \right] \left( t_1^{\beta} \Gamma(\alpha + 2) - \Gamma(\alpha + 1) \eta_1 \xi_1^{\alpha + \beta} \right),
\]

Theorem 3.1 Assume that (H1)–(H3) hold. Then the following assertions are true:
(1) The problem (1.1) has a unique solution \( y_0 \in X \) and satisfies the integral equation (2.1), namely,

\[
y_0(t) = \begin{cases} 
F_0(t) - \frac{\mu^{a_1, a_2}}{t_1^{a_1, a_2}} F_0(\xi_1) - \frac{\mu^{a_2 - a_1}}{t_1^{a_2 - a_1}} F_0(\eta_1), & t \in [0, t_1], \\
g_i(t, y(s_i^*)) , & t \in (t_i, s_i], i = 1, 2, \ldots, m, \\
F_i(t) - c_{i1} t^{a_1} - c_{i2} t^{a_2} - c_{i3} , & t \in (s_i, t_{i+1}], i = 1, 2, \ldots, m, 
\end{cases}
\]

(3.1)

where \( c_{i1}, c_{i2}, \) and \( c_{i3} \) are the same as in (2.1), and

\[
F_i(t) = \int_s^t \frac{(t - u)^{\alpha - 1}}{\Gamma(\alpha)} \left( \int_s^{u} \frac{(u - s)^{\beta - 1}}{\Gamma(\beta)} f(s, y_0(s), D_0^{\alpha} y_0(s)) \, ds \right) \, du.
\]

(2) The problem (1.1) is Ulam–Hyers stable, that is, if \( y \in X \) is a solution of the inequality (2.10), then

\[
|y(t) - y_0(t)| \leq \kappa e, \quad t \in J,
\]

where \( \kappa = \max\{1, \kappa_0, \kappa_1, \ldots, \kappa_m\}, \)

\[
\kappa_0 = \frac{1}{\Gamma(\alpha + \beta + 1)} \left( t_1^{a_1 + \beta} + \frac{\mu^{a_1 + 1}}{t_1^{a_1 + 1}} - \frac{\mu^{a_1}}{t_1^{a_1}} \right) \xi_1^{a_1 + \beta} + \frac{\mu^{a_2}}{t_1^{a_2}} (\xi_1^{a_2} - \eta_1^{a_2}),
\]

\[
\kappa_1 = \frac{1}{\Gamma(\alpha + \beta + 1)} \left( t_1^{a_1 + \beta} \xi_1^{a_1 + \beta} + \frac{\mu^{a_1 + 1}}{t_1^{a_1 + 1}} - \frac{\mu^{a_1}}{t_1^{a_1}} \right) \xi_1^{a_1 + \beta} + \frac{\mu^{a_2}}{t_1^{a_2}} (\xi_1^{a_2} - \eta_1^{a_2}) + \|A\| \left| \int_{s_i}^{t_i} \left[ (\eta_i^{a_1} - s_1^{a_1}) \xi_i^{a_1 + \beta} + (\xi_i^{a_1} - s_i^{a_1}) \eta_i^{a_1 + \beta} \right] \, du \right|.
\]

Proof For all \( x \in X, t \in J \), we define the operator \( Q : X \to X \) by

\[
(Qx)(t) = \begin{cases} 
F_0(t) - \frac{\mu^{a_1, a_2}}{t_1^{a_1, a_2}} F_0(\xi_1) - \frac{\mu^{a_2 - a_1}}{t_1^{a_2 - a_1}} F_0(\eta_1), & t \in [0, t_1], \\
g_i(t, x(s_i^*)) , & t \in (t_i, s_i], i = 1, 2, \ldots, m, \\
F_i(t) - c_{i1} t^{a_1} - c_{i2} t^{a_2} - c_{i3} , & t \in (s_i, t_{i+1}], i = 1, 2, \ldots, m. 
\end{cases}
\]

(3.2)

Since \( x(t) \in X, f \in C^1(I \times \mathbb{R}^2, \mathbb{R}), g_i \in C(t_i, s_i] \times \mathbb{R}, \mathbb{R}, A \in C^2(\mathbb{R}, \mathbb{R}), \) and due to the expression of \((Qx)(t)\), we know that if \( x(t) \in X \), then \((Qx)(t) \in X \).

We firstly apply the Banach contraction principle to prove that (1) of Theorem 3.1 holds. To do so, we need to prove that \( Q \) is strictly contractive on \( X \). In fact, for any \( v_1, v_2 \in X \), in view of (H1)–(H3), we have

\[
|(Qv_1)(t) - (Qv_2)(t)| \\
\leq \int_0^t \frac{(t - u)^{\alpha - 1}}{\Gamma(\alpha)} \left( \int_0^u \frac{(u - s)^{\beta - 1}}{\Gamma(\beta)} |f(s, v_1(s), D_0^{\alpha} v_1(s)) - f(s, v_2(s), D_0^{\alpha} v_2(s))| \, ds \right) \, du.
\]
\[ \frac{t^\alpha}{\zeta_1^\alpha - \zeta_1^{-1}} \frac{\Gamma(\alpha)}{\zeta_1^\alpha - \zeta_1^{-1}} + \int_0^\xi (\xi - u)^{\alpha - 1} \left( \int_0^t (u - s)^{\beta - 1} \frac{f(s, v_1(s), \mathcal{D}^\alpha_{\nu}, v_1(s))}{\Gamma(\beta)} \right) ds + \left( (\mathcal{A}v_1)(u) - (\mathcal{A}v_2)(u) \right) du \]

\[ \frac{t^\alpha}{\zeta_1^\alpha - \zeta_1^{-1}} \frac{\Gamma(\alpha)}{\zeta_1^\alpha - \zeta_1^{-1}} + \int_0^\xi (\xi - u)^{\alpha - 1} \left( \int_0^t (u - s)^{\beta - 1} \frac{f(s, v_1(t), \mathcal{D}^\alpha_{\nu}, v_1(s))}{\Gamma(\beta)} \right) ds + \left( (\mathcal{A}v_1)(u) - (\mathcal{A}v_2)(u) \right) du \]

\[ \lambda \leq \int_0^t (t - s)^{\alpha - 1} \left( \int_0^t (u - s)^{\beta - 1} \frac{f(s, v_1(s), \mathcal{D}^\alpha_{\nu}, v_1(s))}{\Gamma(\beta)} \right) ds + \left( (\mathcal{A}v_1)(u) - (\mathcal{A}v_2)(u) \right) du \]

\[ \|D^\alpha_{\nu}(Qv_1)(t) - D^\alpha_{\nu}(Qv_2)(t)\| \leq \int_0^t (t - s)^{\beta - 1} \left| f(s, v_1(s), \mathcal{D}^\alpha_{\nu}, v_1(s)) - f(s, v_2(s), \mathcal{D}^\alpha_{\nu}, v_2(s)) \right| ds \]

\[ + \left( (\mathcal{A}v_1)(t) - (\mathcal{A}v_2)(t) \right) + \left( \int_0^t (t - s)^{\alpha - 1} \left( \int_0^t (u - s)^{\beta - 1} \frac{f(s, v_1(s), \mathcal{D}^\alpha_{\nu}, v_1(s))}{\Gamma(\beta)} \right) ds + \left( (\mathcal{A}v_1)(u) - (\mathcal{A}v_2)(u) \right) du \]
\[
\frac{1}{\Gamma(1-\alpha)} \int_0^{t} (t-s)^{-\alpha} \left( s^\alpha \zeta_1 - s^{\alpha+1} \right) \frac{d^\alpha}{ds^{\alpha}} \left( \frac{\eta_1}{\zeta_1} \right) ds \left\| f(s,v_1(s),cD_t^\alpha v_1(s)) - f(s,v_2(s),cD_t^\alpha v_2(s)) \right\| ds \\
+ \left( \int_0^{t} \frac{(t-s)^{\beta-1}}{\Gamma(\beta)} \left| f(s,v_1(s),cD_t^\beta v_1(s)) - f(s,v_2(s),cD_t^\beta v_2(s)) \right| ds \\
+ L_A \left| v_1(t) - v_2(t) \right| \right) \\
\leq \left( \int_0^{t} \frac{(t-s)^{\beta+1}}{\Gamma(\beta)} \left| f(s,v_1(s),cD_t^\beta v_1(s)) - f(s,v_2(s),cD_t^\beta v_2(s)) \right| ds \\
+ L_A \left| v_1(t) - v_2(t) \right| \right) \\
\leq \left( \frac{L_f}{\Gamma(\beta+1)} + L_A \right) \left| v_1 - v_2 \right| + \left( \frac{L_f}{\Gamma(\beta+1)} \right) \left| \frac{\eta_1}{\zeta_1} \right| \left| v_1 - v_2 \right|
\]

\[-f(s, v_2(s), ^{\alpha}D^\alpha_{t^j} v_2(s)) \, ds + |(A\nu_1)(u) - (A\nu_2)(u)| \, du \]

\[+ |M_1|^{\alpha+1} \left[ (\xi^{\alpha+1}_{i+1} - s^\alpha_i) \int_{s_i}^{n_{i+1}} \frac{(\eta_i+1-u)^{\alpha-1}}{\Gamma(\alpha)} \left( \int_{s_i}^{u} \frac{(u-s)^{\beta-1}}{\Gamma(\beta)} \right) \right] \]

\[\times |f(s, v_1(s), ^{\alpha}D^\alpha_{t^j} v_1(s)) - f(s, v_2(s), ^{\alpha}D^\alpha_{t^j} v_2(s))| \, ds \]

\[+ |(A\nu_1)(u) - (A\nu_2)(u)| \, du + (\eta^{\alpha+1}_{i+1} - s^\alpha_i) \int_{s_i}^{n_{i+1}} \frac{(\xi^{\alpha+1}_{i+1} - u)^{\alpha-1}}{\Gamma(\alpha)} \left( \int_{s_i}^{u} \frac{(u-s)^{\beta-1}}{\Gamma(\beta)} \right) \]

\[\times |f(s, v_1(s), ^{\alpha}D^\alpha_{t^j} v_1(s)) - f(s, v_2(s), ^{\alpha}D^\alpha_{t^j} v_2(s))| \, ds \]

\[\times |(A\nu_1)(u) - (A\nu_2)(u)| \, du \]

\[\times \frac{\int_{s_i}^{n_{i+1}} (\eta_i+1-u)^{\alpha-1}}{\Gamma(\alpha)} \left( \int_{s_i}^{u} \frac{(u-s)^{\beta-1}}{\Gamma(\beta)} \right) \]

\[\times |f(s, v_1(s), ^{\alpha}D^\alpha_{t^j} v_1(s)) - f(s, v_2(s), ^{\alpha}D^\alpha_{t^j} v_2(s))| \, ds \]

\[\times |(A\nu_1)(u) - (A\nu_2)(u)| \, du \]

\[\times \frac{\int_{s_i}^{n_{i+1}} (\eta_i+1-u)^{\alpha-1}}{\Gamma(\alpha)} \left( \int_{s_i}^{u} \frac{(u-s)^{\beta-1}}{\Gamma(\beta)} \right) \]

\[\times |f(s, v_1(s), ^{\alpha}D^\alpha_{t^j} v_1(s)) - f(s, v_2(s), ^{\alpha}D^\alpha_{t^j} v_2(s))| \, ds \]

\[\times |(A\nu_1)(u) - (A\nu_2)(u)| \, du \]

\[\times \frac{\int_{s_i}^{n_{i+1}} (\eta_i+1-u)^{\alpha-1}}{\Gamma(\alpha)} \left( \int_{s_i}^{u} \frac{(u-s)^{\beta-1}}{\Gamma(\beta)} \right) \]

\[\times |f(s, v_1(s), ^{\alpha}D^\alpha_{t^j} v_1(s)) - f(s, v_2(s), ^{\alpha}D^\alpha_{t^j} v_2(s))| \, ds \]

\[\times |(A\nu_1)(u) - (A\nu_2)(u)| \, du \]

\[+ L_{2}\left| D^\alpha_{t^j} v_1(s) - D^\alpha_{t^j} v_2(s) \right| \, ds + L_A |v_1(u) - v_2(u)| \, du \]

\[+ |M_1|^{\alpha+1} \left[ (\xi^{\alpha+1}_{i+1} + s^\alpha_i) \int_{s_i}^{n_{i+1}} \frac{(\eta_i+1-u)^{\alpha-1}}{\Gamma(\alpha)} \left( \int_{s_i}^{u} \frac{(u-s)^{\beta-1}}{\Gamma(\beta)} \right) \]

\[\times |f(s, v_1(s), ^{\alpha}D^\alpha_{t^j} v_1(s)) - f(s, v_2(s), ^{\alpha}D^\alpha_{t^j} v_2(s))| \, ds \]

\[\times |(A\nu_1)(u) - (A\nu_2)(u)| \, du \]

\[\times \frac{\int_{s_i}^{n_{i+1}} (\eta_i+1-u)^{\alpha-1}}{\Gamma(\alpha)} \left( \int_{s_i}^{u} \frac{(u-s)^{\beta-1}}{\Gamma(\beta)} \right) \]

\[\times |f(s, v_1(s), ^{\alpha}D^\alpha_{t^j} v_1(s)) - f(s, v_2(s), ^{\alpha}D^\alpha_{t^j} v_2(s))| \, ds \]

\[\times |(A\nu_1)(u) - (A\nu_2)(u)| \, du \]

\[\times \frac{\int_{s_i}^{n_{i+1}} (\eta_i+1-u)^{\alpha-1}}{\Gamma(\alpha)} \left( \int_{s_i}^{u} \frac{(u-s)^{\beta-1}}{\Gamma(\beta)} \right) \]

\[\times |f(s, v_1(s), ^{\alpha}D^\alpha_{t^j} v_1(s)) - f(s, v_2(s), ^{\alpha}D^\alpha_{t^j} v_2(s))| \, ds \]

\[\times |(A\nu_1)(u) - (A\nu_2)(u)| \, du \]

\[\times \frac{\int_{s_i}^{n_{i+1}} (\eta_i+1-u)^{\alpha-1}}{\Gamma(\alpha)} \left( \int_{s_i}^{u} \frac{(u-s)^{\beta-1}}{\Gamma(\beta)} \right) \]

\[\times |f(s, v_1(s), ^{\alpha}D^\alpha_{t^j} v_1(s)) - f(s, v_2(s), ^{\alpha}D^\alpha_{t^j} v_2(s))| \, ds \]

\[\times |(A\nu_1)(u) - (A\nu_2)(u)| \, du \]
\[ L_2 \bar{y} + L_2 \int \frac{(\eta_i^{\alpha+1} - \eta_i^{\alpha}) L_g}{\Gamma(\alpha+1)} \left[ \frac{L_2}{\Gamma(\alpha+1)}(\xi_i^{\alpha+1} - \xi_i^{\alpha}) \int_0^{\tau_i} \frac{(\tau_i - u)^{\alpha-1}}{\Gamma(\alpha)} \left( \int_0^{u} \frac{(u - s)^{\beta-1}}{\Gamma(\beta)} [L_2y] v_1(s) - v_2(s) \right) ds + L_A | v_1(u) - v_2(u) | \right] \]
+ \left( \xi_{i+1}^{\alpha} - \xi_{i}^{\alpha} \right) \eta_{i+1}^{\alpha}
 + \left| \mathcal{M}_i \right| \left( \xi_{i+1}^{\alpha} - \xi_{i}^{\alpha} \right) \eta_{i+1}^{\alpha}
 = \lambda_i \| v_1 - v_2 \|_x, \quad t \in (s_i, t_{i+1}], i = 1, 2, \ldots, m,
 \end{align*}

\begin{align*}
\left| \left( v_{i+1}^{\alpha} - v_i^{\alpha} \right) \right| & \leq \int_{s_i}^t \left| f (s, v_1 (s), v_2 (s)) - f (s, v_2 (s), v_2 (s)) \right| ds
\end{align*}
\[
+ \left( \zeta_{i+1}^\alpha - \eta_{i+1}^\alpha \right) L_{g_i} \left| v_1 (t_i) - v_2 (t_i) \right| + |M_i| \Gamma (\alpha + 1) \left[ \left( \eta_{i+1}^{(r+1)} - s_i^{(r+1)} \right) \right] \\
\times \int_0^{\zeta_{i+1}} \frac{\left( \xi_{i+1} + \eta_{i+1}^\alpha - u \right)^{a-1}}{\Gamma (\alpha)} \left( \int_0^u (u-s)^{\beta-1} \Gamma (\beta) \right) \left| L_{y_i} v_1 (s) - v_2 (s) \right| ds + L_{A_1} \left| v_1 (u) - v_2 (u) \right| ds \\
+ \left( \zeta_{i+1}^\alpha - s_i^{(r+1)} \right) \int_0^{\eta_{i+1}^{(r+1)}} \frac{\left( \eta_{i+1}^{(r+1)} - u \right)^{a-1}}{\Gamma (\alpha)} \left( \int_0^u (u-s)^{\beta-1} \Gamma (\beta) \right) \left| L_{y_i} v_1 (s) - v_2 (s) \right| ds + L_{A_1} \left| v_1 (u) - v_2 (u) \right| ds \\
+ \left( \zeta_{i+1}^\alpha - s_i^{(r+1)} \right) L_{g_i} \left| v_1 (t_i) - v_2 (t_i) \right| \\
\leq \left\{ \left( L_{y_i} + L_{2y} \right) t_i^\beta \right\} \frac{1}{\Gamma (\alpha + 1)} + L_{A_1} + |M_i| t_i \Gamma (\alpha + 2) \left[ \left( \eta_{i+1}^{(r+1)} - s_i^{(r+1)} \right) L_{y_i} \right] \\
+ \left( \zeta_{i+1}^\alpha - s_i^{(r+1)} \right) L_{A_1} \eta_{i+1}^\alpha \left[ \left( \eta_{i+1}^{(r+1)} - s_i^{(r+1)} \right) L_{y_i} \right] \left[ \left( \eta_{i+1}^{(r+1)} - s_i^{(r+1)} \right) \right] \left[ \left( \eta_{i+1}^{(r+1)} - s_i^{(r+1)} \right) \right] \\
+ \left( \zeta_{i+1}^\alpha - s_i^{(r+1)} \right) L_{A_1} t_i \Gamma (\alpha + 2) \left[ \left( \eta_{i+1}^{(r+1)} - s_i^{(r+1)} \right) \right] \left[ \left( \eta_{i+1}^{(r+1)} - s_i^{(r+1)} \right) \right] \\
= \mu_i \left| v_1 - v_2 \right| X, \quad t \in (s_i, t_{i+1}], i = 1, 2, \ldots, m. \tag{3.7}
\]

It follows from (3.3)–(3.7) that
\[
\left\| (Qv_1) (t) - (Qv_2) (t) \right\|_X \leq \lambda \left| v_1 - v_2 \right| X. \tag{3.8}
\]

According to (H1) and (3.8), we know that Q is strictly contractive on X. In the light of the Banach contraction principle, we conclude that the problem (1.1) has a unique solution \( y_0 \in X \) and satisfies the integral equation (2.1).

Next we show that (2) of Theorem 3.1 also holds. Indeed, let \( y \in X \) be a solution of the inequality (2.10) and \( y_0 \in X \) be a unique solution of (1.1). According to Lemma 2.3 and
Zhao and Deng verify that 

\[ |y(t) - y_0(t)| \leq k_\varepsilon t, \quad t \in [0, t_1], \]

\[ |y(t) - y_0(t)| \leq \varepsilon, \quad t \in (t_i, s_i], i = 1, 2, \ldots, m, \]

\[ |y(t) - y_0(t)| \leq k_\varepsilon t, \quad t \in (s_i, t_{i+1}], i = 1, 2, \ldots, m. \]  

Then (3.9) gives that \( |y(t) - y_0(t)| \leq \kappa \varepsilon, \; t \in J \), namely, the problem (1.1) is Ulam–Hyers stable. The proof of Theorem 3.1 is completed. \( \square \)

### 4 Illustrative example

Consider the fractional-order six-point boundary value problem involving noninstantaneous impulse and bounded operator as follows:

\[
\begin{cases}
\frac{1}{\Gamma(\alpha + 1)} \left( \int_0^t (t^\alpha + \beta + 1) \right) f(t, x(t), D_0^\alpha x(t)) = x(t) \in [0, 1] \cup \left[ \frac{1}{3}, 1 \right], \\
x(t) = \frac{x(t_1)}{\Gamma(\alpha + 1)}, \quad t \in \left( \frac{1}{3}, \frac{2}{3} \right], \\
x(0) = x\left( \frac{1}{3} \right) = x\left( \frac{2}{3} \right) = x\left( \frac{1}{2} \right) = x(1) = 0.
\end{cases}
\]

Obviously, \( \alpha = \frac{1}{2}, \beta = \frac{3}{2}, 0 < s_0 < \eta_1 = \frac{1}{3} < \xi_1 = \frac{1}{4} < t_1 = \frac{1}{3} < s_1 = \frac{2}{3} < \eta_2 = \frac{3}{4} < \xi_2 = \frac{11}{12} < t_2 = 1, f(t, x(t), D_0^\alpha x(t)) = x(t) + \frac{1}{400}, g_1(t, x(t)) = \frac{x(t_1)}{\Gamma(\alpha + 1)} \right) \]

\[ L_{x1} = \frac{1}{200} < 1. \] Let \( (Ax)(t) = \frac{x(t)}{\Gamma(\alpha + 1)} \right) \), then \( L_{x1} = \frac{1}{200} < 1. \) So the conditions \((H_1)-(H_2)\) hold. Next we verify that \((H_4)\) holds. Indeed,

\[
\begin{align*}
\mathcal{M}_1 &= \frac{1}{(\xi_2^\alpha - s_1^\alpha)(\xi_2^\alpha - s_1^\alpha) - (\xi_2^\alpha - s_1^\alpha)(\eta_2^\alpha - s_1^\alpha)} \\
\lambda_0 &= \frac{L_{y1} + L_{2y}}{\Gamma(\alpha + \beta +1)} \left( \frac{t_1^\alpha + \eta_2^\alpha - \xi_1^\alpha - \xi_1^\alpha}{\xi_1^\alpha - \xi_1^\alpha} \right) \\
\mu_0 &= \left( \frac{L_{y1} + L_{2y}}{\Gamma(\alpha + \beta +1)} \right) \left( \frac{1}{\Gamma(\alpha + \beta +1)} \left( \frac{t_1^\alpha + \eta_2^\alpha - \xi_1^\alpha - \xi_1^\alpha}{\xi_1^\alpha - \xi_1^\alpha} \right) + \frac{1}{\Gamma(\alpha + \beta +1)} \right) \\
\lambda_1 &= \left( \frac{L_{y1} + L_{2y}}{\Gamma(\alpha + \beta +1)} \right) \left[ \frac{t_1^\alpha}{\Gamma(\alpha + \beta +1)} + \frac{1}{\Gamma(\alpha + \beta +1)} \left( \frac{t_1^\alpha + \eta_2^\alpha - \xi_1^\alpha - \xi_1^\alpha}{\xi_1^\alpha - \xi_1^\alpha} \right) \right] \left( \frac{1}{\Gamma(\alpha + \beta +1)} \right) \left( \frac{t_1^\alpha + \eta_2^\alpha - \xi_1^\alpha - \xi_1^\alpha}{\xi_1^\alpha - \xi_1^\alpha} \right) \right) \\
\mu_1 &= \left( \frac{L_{y1} + L_{2y}}{\Gamma(\alpha + \beta +1)} \right) \left[ \frac{t_1^\alpha}{\Gamma(\alpha + \beta +1)} + \frac{1}{\Gamma(\alpha + \beta +1)} \left( \frac{t_1^\alpha + \eta_2^\alpha - \xi_1^\alpha - \xi_1^\alpha}{\xi_1^\alpha - \xi_1^\alpha} \right) \right] \left( \frac{1}{\Gamma(\alpha + \beta +1)} \right) \left( \frac{t_1^\alpha + \eta_2^\alpha - \xi_1^\alpha - \xi_1^\alpha}{\xi_1^\alpha - \xi_1^\alpha} \right) \right) \\
\end{align*}
\]
\(-s_1^{a+1}n_2^2\xi_2^a\) + \(L_1\mathcal{M}_1\left[\xi_2^{a+1}(s_2^a - n_2^{a+1}) + t_2^a (s_2^{a+1} - n_2^{a+1})\right]\) 
\(+ (s_2^{a+1}n_2^a - n_2^{a+1}\xi_2^a)\] 
\(\approx 0.7570 < 1,\) 
\(\mu_1 = (L_1f + L_2g)\left(\frac{t_2^a}{\Gamma(\beta + 1)} + \frac{|\mathcal{M}_1|t_2\Gamma(\alpha + 2)}{\Gamma(\alpha + \beta + 1)}\left[(s_2^a - s_1^a)n_2^2 + (n_2^a - s_1^a)\xi_2^a\right] + (s_2^{a+1} - s_1^{a+1})n_2^a + (n_2^{a+1} - s_1^{a+1})\xi_2^a\right)\] 
\(+ L_4(1 + |\mathcal{M}_1|t_2(\alpha + 1))[(s_2^a - s_1^a)n_2^2 + (n_2^a - s_1^a)\xi_2^a]\) 
\(+ |\mathcal{M}_1|[(s_2^{a+1} - s_1^{a+1})n_2^a + (n_2^{a+1} - s_1^{a+1})\xi_2^a]\) 
\(+ L_5|\mathcal{M}_1|\left[t_2\Gamma(\alpha + 2)(s_2^a - n_2^a) + \Gamma(\alpha + 1)(s_2^{a+1} - n_2^{a+1})\right] \approx 0.5313 < 1.\)

Thus all the conditions of Theorem 3.1 hold. Therefore, the problem (4.1) has a unique solution \(y_0(t) \in X.\) Meanwhile, the problem (4.1) is Ulam–Hyers stable.

5 Conclusions

As a useful mathematical model, the multiple point boundary value problem of fractional-order differential equation is used to describe many phenomena and processes such as in blood flow, chemical engineering, thermo-elasticity, underground water flow, population dynamics, and so on. The existence and stability of the solution of this kind of problem is very important in theoretical research and practical application. Therefore, we mainly study the existence and Ulam–Hyers stability of the solution of problem (1.1) in this paper. Some novel and useful criteria have been obtained by the Banach contraction principle and direct analysis methods.

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Authors’ contributions

The authors declare that the study was realized in collaboration with equal responsibility. All authors read and approved the final manuscript.

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