Radio-flaring Ultracool Dwarf Population Synthesis

Matthew Route1,2,3,4

1 Department of Astronomy and Astrophysics, the Pennsylvania State University, 525 Davey Laboratory, University Park, PA 16802, USA
2 Center for Exoplanets and Habitable Worlds, the Pennsylvania State University, 525 Davey Laboratory, University Park, PA 16802, USA; mroute@purdue.edu
3 Northrop Grumman Electronic Systems, 6120 Longbow Drive, Boulder, CO 80301, USA

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Abstract

Over a dozen ultracool dwarfs (UCDs), low-mass objects of spectral types $\geq$ M7, are known to be sources of radio flares. These typically several-minutes-long radio bursts can be up to 100% circularly polarized and have high brightness temperatures, consistent with coherent emission via the electron cyclotron maser operating in approximately kilogauss magnetic fields. Recently, the statistical properties of the bulk physical parameters that describe these UCDs have become described adequately enough to permit synthesis of the population of radio-flaring objects. For the first time, I construct a Monte Carlo simulator to model the population of these radio-flaring UCDs. This simulator is powered by Intel Secure Key (ISK), a new processor technology that uses a local entropy source to improve random number generation that has heretofore been used to improve cryptography. The results from this simulator indicate that only $\sim$5% of radio-flaring UCDs within the local interstellar neighborhood ($<25$ pc away) have been discovered. I discuss a number of scenarios that may explain this radio-flaring fraction and suggest that the observed behavior is likely a result of several factors. The performance of ISK as compared to other pseudorandom number generators is also evaluated, and its potential utility for other astrophysical codes is briefly described.

Key words: brown dwarfs – methods: numerical – methods: statistical – radio continuum: stars – stars: activity – stars: low-mass

1. Introduction

Ultracool dwarfs (UCDs) include stars at the lower-mass end of the hydrogen-burning main sequence and substellar-mass objects that allow us to probe the stellar–substellar–planetary transition (Kirkpatrick et al. 1997). At spectral types $\geq$ M3 (0.35 $M_\odot$), stellar evolutionary models indicate that the interiors of these objects become fully convective (Chabrier & Baraffe 1997, 2000). This property coincides with the elimination of a radiative core and a tachocline, the component thought to be key to generating large-scale and strong magnetic fields.

In stellar and substellar atmospheres, magnetic activity is manifested through a number of indicators that operate in specific layers, including X-ray (corona), Ca II H and K (chromosphere), Fe XIV (corona), Balmer H$\alpha$ (chromosphere), and radio (upper chromosphere–corona) (Hall 2008; Benz & Güdel 2010; Shibasaki et al. 2011; McIntosh et al. 2014). One might be forgiven for suspecting that at spectral type $\sim$ M3, measurements of these activity indicators would yield reduced luminosities and variations. However, this is not observed. Instead, the fraction of M dwarfs with detected X-ray and H$\alpha$ emission appears to decline with spectral type at M7 and beyond (McLean et al. 2012; Pineda et al. 2016). Meanwhile, radio luminosities remain roughly constant (Audard et al. 2007; Route & Wolszczan 2016b). Thus, if UCDs transition to a different dynamo mechanism in their interiors, such as the $\alpha^2$ or turbulent dynamo mechanisms (Durney et al. 1993; Chabrier & Küker 2006), there is no observable manifestation of it. Interestingly, there are two pieces of evidence that magnetic activity is created in the convective zone, with consequent similar patterns in magnetic activity existing from spectral types F–T (and presumably Y as well). This includes the detection of correlated X-ray activity and rotational periods for four M4–5.5 stars, as occurs for solar-like stars (Wright & Drake 2016), and the recent hypothesis that UCDs exhibit cycles of magnetic activity as revealed by alterations in the helicity of their radio emission, which may come from reversals in their global or local magnetic field orientations (Route 2016).

That radio emission from UCDs appears to be uncorrelated with effective temperature and spectral type presents an opportunity: it permits a consistent means by which to probe the magnetic field strengths and topologies across all UCDs. The radio flares that emanate from some UCDs are themselves perplexing because their circular polarization fractions can approach $\sim$100% and their brightness temperatures can exceed $10^8$ K, leading to differing explanations as to their emission mechanisms, including mildly relativistic synchrotron (gyrosynchrotron) radiation (Berger 2002) similar to that found on the Sun, and the electron cyclotron maser (ECM), which is reminiscent of auroral radio emission from the magnetized solar system planets, such as Jupiter (Hallinan et al. 2008).

Moreover, many of these radio flares have been detected at radio frequencies of 4.5–8.5 GHz, indicating that a number of UCDs host magnetic fields of $B \sim 3$ kG. On the other hand, a number of UCDs only display quiescent, steady, or sinusoidally varying radio emission that lacks flaring activity (e.g., the L5 dwarf 2MASSW J0004348-404405, Lynch et al. 2016). Although this low-level activity is generally thought to be caused by gyrosynchrotron emission, depolarized ECM has also been proposed (Hallinan et al. 2008). Unfortunately, radio surveys of UCDs have become exceedingly rare these days, on account of the large time allocations and great sensitivities required, which have generally yielded detection rates of $\sim$5%–10% across M7–M9, L, and T spectral types (Route & Wolszczan 2016b).
The decoupling of X-ray and radio emission trends among UCDs is not well understood. This curious magnetic behavior defies the Güdel–Benz relationship, which links these types of nonthermal radiation to magnetic reconnection flaring events on the Sun and other stars (Benz & Güdel 2010). Although a number of mechanisms have been proposed to account for this unbundling of trends, including the suppression of X-ray emission by the cooler temperatures and increasingly neutral photospheres of the objects (Mohanty et al. 2002; Rodríguez-Barrera et al. 2015), geometric effects (Hallinan et al. 2008), the presence of two distinct populations of UCDs (Stelzer et al. 2012), and the varying temporal properties of the magnetic topology (Route 2016), too little evidence exists to evaluate these hypotheses.

It is in this environment that I construct a Monte Carlo simulator of UCD flaring radio activity, in an attempt to better understand and characterize the observed magnetic activity. Other more computationally intensive problems exist in astrophysics, including the modeling of magnetohydrodynamic phenomena and N-body simulations. However, the radio-flaring UCD population synthesis is an exciting new astrophysical problem, since only recently have the properties of UCDs become well-enough understood that they can be modeled even approximately in a Monte Carlo simulator. This paper describes the construction and results of this simulator, with the primary goal of examining the question of why such a small fraction of UCDs appear to have detected flaring radio emission, whereas all UCDs ought to have radio-flaring reconnection events that occur within magnetospheres with properties that exist along a continuum connecting the Sun and Jupiter. A secondary goal of this paper is to evaluate the computational results and performance of Intel Secure Key (ISK) with respect to scientific computing.

Section 2 explains the construction of a Monte Carlo simulator to model the radio-flaring UCD population, describing the physical properties of UCDs and the properties of radio survey instrumentation used to detect UCDs. Section 3 describes the scientific and computational results from the simulator. Section 4 presents a number of physical scenarios to explain the simulator-derived radio-flaring occurrence rate. Section 5 discusses the advantages and disadvantages of utilizing ISK, especially as compared to other random number generators. Section 6, the conclusion, illuminates the scientific and computational significance of this work, while the Appendix provides details on the software implementation of various random number distributions using ISK.

2. Construction of a UCD Population Synthesis Simulator

2.1. Simulator Probability Density Functions

2.1.1. Distributions for UCD Astrophysical Properties

Multimwavelength observations of UCDs have revealed a number of magnetic properties of these objects, including their detection statistics, which can be modeled by Monte Carlo simulation. In particular, unbiased radio surveys conducted at Arecibo Observatory (AO; Route & Wolszczan 2013, 2016b) resulted in a pair of newly discovered sources (Route & Wolszczan 2012, 2016a). These sources permit a careful characterization of instrumental performance that enables the properties of the magnetized UCD population responsible for the production of the flares described to be inferred. A number of unbiased, targeted radio surveys conducted over the years at AO, the Very Large Array (VLA), and the Australia Telescope Compact Array (ATCA) examined the temporal properties of surveyed UCDs. These survey detection statistics may be combined since the observations and analysis were sensitive to radio flares from targets that are several minutes in duration. By this standard, the compiled results from the surveys conducted by Antonova et al. (2008, 2013), Berger (2002, 2006), Burgasser & Putman (2005), Phan-Bao et al. (2007), McLean et al. (2012), Route & Wolszczan (2013, 2016b), and Lynch et al. (2016) yield a detection probability of 6/132 for spectral types M7 to T6.5. Note that a single detection probability is used for all spectral types, an assumption supported by the fact that UCD radio luminosity appears to be independent of spectral type through the end of spectral type T (Route & Wolszczan 2016b).

UCDs may appear magnetically inactive for a number of reasons. Their magnetic fields may be weaker than those corresponding to the radio frequencies observed. Alternatively, viewing geometry effects or monitoring sources during the “solar minimum” phase of their magnetic activity cycles may also prevent detection (Route 2016). Detected radio-flaring UCDs can be categorized as sporadically flaring, perhaps due to the varying properties of the interstellar medium impinging on the UCD magnetosphere (Schrijver 2009; Nichols et al. 2012), or periodically flaring, with their flaring periods equivalent to their rotational periods, similar to the phenomenon observed at Jupiter and Saturn (Zarka 1998). The probability that any detected UCD flares periodically is 11/14, as determined from a compiled list of known radio-flaring UCDs (Route 2016). The other 3/14 sources are modeled as sporadically flaring sources that flare at intervals much longer than their rotational periods. Observations may later reveal that these “sporadic” sources are actually periodically flaring sources that exhibit a large range of flare amplitudes. However, at this time, I create this category for these ill-constrained sources.

To accurately model the population of UCDs that emit radio flares once per revolution, we must characterize the underlying UCD rotation period probability distribution. A lognormal rotational period distribution has been derived for L and T dwarfs by Radigan et al. (2014) and takes the form

\[ f(P) = \frac{1}{P \sigma \sqrt{2\pi}} e^{-\frac{(\ln P - \mu)^2}{2\sigma^2}}, \]

where rotational periods, \( P \), are measured in hours, and the parameters \( \mu = 1.41 \) (mean) and \( \sigma = 0.48 \) (standard deviation) are empirically derived. This model relied on a high-resolution spectroscopic survey of 45 L0–L8 dwarfs by Reiners & Basri (2008), with the majority of their sources having spectral types \( \leq L3.0 \), and 15 L/T dwarfs observed by Zapatero Osorio et al. (2006), which mainly focused on late-L and late-T dwarfs. However, this period distribution is only based on \( v \sin i \) measurements, under the assumption of an isotropic distribution of inclination angles. I also note nearly one-third of the brown dwarf rotational periods measured by Metchev et al. (2015) may exceed 10 hr, and that the recent detection of a 0.288 hr rotational period for the T6 dwarf WISEPC J112254.73+255021.5 (J1122+25) (Route & Wolszczan 2016a) suggests that this functional form may underestimate the number of objects at rotational periods \( \leq 1 \) hr and \( \geq 10 \) hr. Although a detailed discussion of these considerations will be presented in a...
forthcoming publication, I nevertheless implement the lognormal functional form but use \( \mu = 1.22 \) and \( \sigma = 0.49 \), based on near-infrared and radio rotational period measurements that span the M7–T7 spectral range (Metchev et al. 2015; Route 2016).

Another key simulation component is the modeling of the radio flare flux density distribution, in units of mJy. Thus far, UCD sources are observed too infrequently for detailed studies of the population statistics of the flare energy amplitudes to be conducted. The next promising choice is to inspect the body of observations that have been collected on cool star flares at various wavelengths. Although cool star (spectral classes F–M) flare amplitude frequency distributions are rare at radio wavelengths, a number of distributions at extreme ultraviolet (EUV) and X-ray wavelengths have been formulated. These distributions take the form of

\[
N(>x) = \int_x^{\infty} dN = \int_x^{\infty} kE^{-\alpha}dE = \frac{k}{\alpha - 1}E^{-\alpha+1},
\]

where \( dN \) is the number of flares with energy between \( E \) and \( E + dE \), \( k \) is a normalization constant, and \( \alpha \) is the power-law index; \( \alpha \) can be determined via a least-squares fit to the slope of the flare energy frequency distribution (Crosby et al. 1993).

This integral converges for \( \alpha > 1 \), permitting normalization over the observed flare energy range. Normalization is achieved by setting a lower bound to the flare energy, which here is set to the 1\( \sigma \) theoretical sensitivity of AO radio observations of UCDs, of \( \sim 0.15 \) mJy (Route & Wolszczan 2016b). Although the distribution is used to create flare energies, this relationship also holds for the distribution of peak flare energies, which is more applicable to the problem of flare detection (Crosby et al. 1993). For a minimum flare energy, \( E_{\text{min}} \), \( k = (\alpha - 1)E_{\text{min}}^{-(\alpha-1)} \). Empirical studies of \( \alpha \) spanning radio to X-ray wavelengths determined that it ranged from 1.5 to 2.7 among cooler stars, including early- to mid-M dwarfs, although the distribution may become shallower at cooler temperatures and later spectral types (Crosby et al. 1993; Güdel et al. 2003 and references therein). I, therefore, simply choose the approximate mean of the available estimates, \( \alpha = 2 \), for the purposes of this simulation.

Although it may seem that modeling the flare flux density distribution would require every flaring object to have both its distance and its flare luminosities modeled, only the overall functional form of the flare amplitude flux density distribution matters. The distance between the observer and the flaring object, although necessary to calculate a flare flux density distribution, in effect acts as a lower energy threshold below which flares are not detected. Since every flare generated by every modeled UCD probes the same power-law peak energy distribution, I simply use a flare amplitude distribution to generate the peak flare flux density distribution for each source, which has a lower energy limit far below the radio telescope sensitivity limit.

For this simulation, the temporal evolution of the radio flares is ignored; this is a direct result of the exquisite sensitivity and high temporal resolution of AO science scans. Solar and stellar flares may exhibit rise and decay times that span seconds to weeks (Benz & Güdel 2010), but they are generally modeled by an impulsive rise phase followed by an exponential decay phase (Güdel et al. 2003).

Radio flares that are rather more impulsive, with rise and decay times of \( \sim 10 \) s on UCDs as diverse as the M9 dwarf TVLM 513-46546 (TVLM 513), the L0+L1.5 binary system 2MASSW 0746425+200032 AB (J0746+20) (Route 2013), and the T dwarfs J1122+25 and 2MASS J10475385+2124234 (Route & Wolszczan 2012, 2016a). Thus, UCD flares are modeled as delta functions, where they instantaneously achieve their peak luminosities, and are immediately detected if they surpass the 3\( \sigma \) sensitivity threshold, due to the 0.9 s Mock spectrometer integration time.

2.1.2. Distributions for AO Instrumentation

With the UCD source properties reproduced in the simulator, we now examine the observation length and instrumental sensitivity properties of the surveys conducted at AO. These surveys leveraged the 305 m diameter Arecibo radio telescope, coupled with its C-band receiver (center frequency = 4.75 GHz) and \( \sim 1 \) GHz bandpass Mock spectrometer (Route & Wolszczan 2016b). Each observing session continuously monitors a single source for radio-flaring activity with 20 s calibration scans interleaved between 600 s science scans. High-temporal-resolution observations of the source 2MASS J10475385+2124234 (Route & Wolszczan 2012) indicate that radio flare durations are \( \gtrsim 60 \) s, meaning that calibration scans should not cause radio pulses to be missed. I therefore model the sequence of science and calibration scans as a continuous observing session. A histogram of the durations of the continuous observing sessions may be constructed from the three AO UCD radio surveys conducted, which span from 2010 January 6 to 2011 September 7 and 2011 October 10 to 2012 April 29 (Route & Wolszczan 2013), and 2013 March 5 to May 15 (Route & Wolszczan 2016b), each of which attempted to observe targets for approximately 2 hr continuously (Figure 1). A detailed description of the observing log for the objects observed for the A2471 and A2623 surveys can be found in Route & Wolszczan (2013). The Monte Carlo simulator draws from the illustrated observation length probability density function to determine the length of each observation, with each session a multiple of 600 s in length. While the observational sample could be expanded to include observation durations from other published surveys, I would also need their associated sensitivity information for use in our simulator. Therefore, I solely rely on the instrumental properties from the Mock spectrometer at Arecibo Observatory.

Similarly, a normalized histogram of Mock spectrometer dynamic spectra sensitivities can be constructed using the same three AO UCD surveys used to model the observation lengths (Figure 2). This sensitivity is equivalent to the 3\( \sigma \) Stokes V standard deviation in the cleanest of seven subband boxes of the Mock spectrometer for each scan, as described in Route & Wolszczan (2016b). These per-scan sensitivity values include the effects of radio frequency interference (RFI) on the instrumental sensitivity. Each modeled observing session has a sensitivity drawn from this distribution. Any modestly (\( \geq 10\% \)) circularly polarized flare with a flux density greater in magnitude than the computed sensitivity floor will be detectable. This probability density function, then, provides the lower sensitivity threshold for the simulator. The histogram (Figure 2) is best fit by a double Gaussian characterized by mean values of \( \mu_1 = 1.04 \) and \( \mu_2 = 1.39 \) mJy, to represent the asymmetrical structure offset along the \( X \) axis from 0. This
functional form has the added advantage of being easy to compute using the functions given in the Appendix.

2.2. Monte Carlo Simulator Software Implementation

The Monte Carlo simulator is implemented in Python 2.7, with the exception of a uniform random number generator, which is implemented in C. This number generator is written in C since it is fast, but more importantly because it is the default language that the ISK subroutines are coded in. This Monte Carlo simulator represents the first published application of ISK to scientific computing, with accompanying descriptions of its implementation, performance results, and a discussion of its overall utility. Section 2.2.1 provides a brief description of the engineering aspects of this new technology, before returning to the details of the construction of the simulator (Section 2.3). Details on how uniform, Gaussian, and lognormal distributions are created with ISK are presented in the Appendix. These methods can be easily adapted to a wide variety of scientific computing scenarios that have applicability within many disciplines in astrophysics.

2.2.1. Introduction to ISK

Intel Corporation recently implemented an entropy-based digital random number generator (DRNG) formally called ISK, code-named “Bull Mountain Technology.” This effort provides random number generation and seeding capabilities to both Intel 64 and IA-32 architectures. The technology was first introduced in 2012 with its Ivy Bridge (Intel Series 7) chip set and has since appeared in all subsequent chip set releases (Taylor & Cox 2011).

The DRNG is a cascade construction random number generator, meaning that it uses an on-chip entropy source to provide a pool of entropy that repeatedly seeds a hardware-implemented, cryptographically secure, pseudorandom number generator (CSPRNG). This DRNG is the mechanism that most similarly operates like a true random number generator (TRNG) in existence today. The DRNG component architecture is shown in Figure 3, and the number-generation pipeline is described below (Intel Corporation 2014). First, an entropy source (uppermost block), which consists of a self-timed circuit that measures the thermal noise in silicon produces a random stream of bits at a rate of 3 Gbps. Second, a conditioner ingests pairs of 256 bit entropy samples and distills them into a single high-quality nondeterministic 256 bit entropy sample using Advanced Encryption Standard, Cipher Block Chaining Message Authentication Code, which conforms to NIST SP 800-38A (Hardware AES-CBC-MAC block). Third, an alternating switch directs these numbers to either a deterministic random bit generator (DRBG) or an enhanced, nondeterministic random number generator (ENRNG). The DRBG is a hardware CSPRNG whose function is to randomly generate random values from a single nondeterministic seed. It accomplishes this using the block-cipher algorithm CTR_DRBG as described in NIST SP 800-90A. The DRBG autonomously determines when it needs to be reseeded by the conditioner in an unpredictable manner. DRBG-derived values are accessible using the RDRAND instruction. The ENRNG, on the other hand, provides entropy numbers directly to other software DRBGs for use as seeds, which are accessible via the RDSEED instruction. The DRNG is fully compliant with modern information security standards, including NIST SP 800-90Ar1, B,6 and C,7 FIPS-140-2,8 and ANSI X9.82. Random number quality is validated by online health tests and built-in self tests that execute after startup. In the event that the DRNG does not function properly, it will fail to generate random numbers rather than create low-quality numbers.

The DRNG library provided by Intel9 consists of RDRAND and RDSEED: only RDRAND is central to the implementation of this Monte Carlo simulator. RDRAND can generate 16, 32, or 64 bit unsigned integers using the DRBG. These are then converted to double or long double precision numbers in the range [0,1) by dividing the unsigned integer by the maximum unsigned integer of appropriate bit length to generate uniform deviates (see the Appendix). The DRNG library is implemented in C, and its source code is available for online download for Linux, OS X, and Windows directly from Intel.

5 “Recommendation for Random Number Generation Using Deterministic Random Bit Generators,” at http://doi.org/10.6028/NIST.SP.800-90Ar1.
6 “Recommendation for the Entropy Sources Used for Random Bit Generation,” at http://csrc.nist.gov/publications/drafts/800-90/sp800-90b_second_draft.pdf.
7 “Recommendation for Random Bit Generator (RBG) Constructions,” at http://csrc.nist.gov/publications/drafts/800-90/draft-sp800-90c.pdf.
8 “Security Requirements for Cryptographic Modules,” at https://doi.org/10.6028/NIST.FIPS.140-2.
9 “The DRNG Library and Manual,” at https://software.intel.com/en-us/articles/the-drng-library-and-manual.
2.3. Monte Carlo Simulator Execution

The ISK number generator creates \( n \) uniformly distributed random numbers, where \( n = 10^7 \) in our example. Every seven-element array describes the input parameters for a particular UCD. All numbers within the arrays are of type \textit{float}. Depending on the distributions used, these numbers may be conditioned by Gaussian or lognormal distributions using the methods described in the Appendix, and then used to create the rotational period, emission type, flare flux density, observation length, observation sensitivity, and flare detection probability for each UCD. Due to the complexity of the observation sensitivity model, two random numbers are used to generate this distribution. The output of the simulator records the rotational period (minutes), object emission type (numerical codes to denote nonflaring, sporadically flaring, or periodically flaring), flare flux density (mJy), observation length (minutes), observation sensitivity (mJy), and whether the flare was detected or not.

The Monte Carlo simulator modeled \( 10^7 \) observing instances where sources had designated rotational periods, emission types, radio flare amplitudes, and the associated observational parameters of durations and sensitivities. This number of observations was chosen to simultaneously ensure the statistical robustness of the scientific and computational performance results. For a source to be detected by our simulator, the source radio flare amplitude must be greater than or equal to the 3\( \sigma \) instrumental sensitivity, and the flare must come from either a periodically or sporadically radio-flaring UCD. Unless both conditions are true, no more evaluation of the potential detection occurs, and the source is not detected. If the radio burst comes from a periodically radio-flaring UCD, the flare may be detected in two cases. If the observation duration is longer than or equivalent to the source’s rotational period, then a radio flare will definitely be detected. On the other hand, if the UCD is monitored for less than the duration of its rotational period, the probability of detection is computed by dividing the observation length by the rotational period, so that the chance of observing a flare linearly increases with the observation duration. A random number drawn from a uniform density distribution is then compared to this value; values less than or equal to this fraction result in detections.

Radio bursts emitted by sporadically flaring sources with amplitudes greater than the sensitivity floor are automatically detected, as a matter of definition and simplification. One reason for this is that several sporadically flaring sources have only a limited number of nonphased flares detected (e.g., DENIS 1048-3956, Burgasser & Putman 2005), so the simulator must also reproduce this behavior. A second reason is that sporadic sources have duty cycles so ill constrained that there is no other plausible way to model their temporal behavior. Although it is tempting to model sporadic sources as randomly flaring in time, this would result in the implicit assumption of an underlying duty cycle function. I note, though, that it may later be revealed that all sporadic flarers that are monitored for long enough, and with great enough

\begin{figure}[h]
\centering
\includegraphics[width=0.5\textwidth]{figure2.png}
\caption{Normalized histogram of instrumental sensitivity, which includes the negative effects of RFI, binned in 0.1 mJy increments. This histogram uses individual scan sensitivity data aggregated from all three AO radio surveys (Route & Wolszczan 2013, 2016b).}
\end{figure}

\begin{figure}[h]
\centering
\includegraphics[width=0.5\textwidth]{figure3.png}
\caption{DRNG component architecture schematic, which results in the generation of directly usable random numbers or random number seeds to be used with other RNGs. Adapted from Intel Corporation (2014).}
\end{figure}
sensitivity, are determined to be periodically flaring sources. However, in light of these considerations, the current implementation appropriately mimics the observed behavior.

3. Population Synthesis Results

3.1. Scientific Results

The 10^7 observing events can be scaled by the likely number of UCDs that exist within a spatial volume centered on the Sun to estimate the number of potentially detectable radio-flaring UCDs. The space density of M7–L8 dwarfs is ~8.7 × 10^{-3} pc^{-3} (Cruz et al. 2007), of T0–T5 dwarfs is ~1.4 × 10^{-3} pc^{-3} (Reylé et al. 2010), of T6–T9.5 dwarfs is ~3.4 × 10^{-3} pc^{-3}, and of ≥Y0 dwarfs is ~1.2 × 10^{-3} pc^{-3} (Kirkpatrick et al. 2011), yielding a total UCD space density of ~1.5 × 10^{-2} pc^{-3}. This total UCD space density indicates that 962 UCDs are located within 25 pc of the Sun, of which three would be detectable by the current UCD observing strategy. Yet the inferred population of additional radio-flaring UCDs that await discovery is computed to be 41 in the same volume. Combining the three currently detectable UCDs with the 41 inferred to be radio-active and dividing this sum by the 962 UCDs in the local neighborhood yields ~4.6% of UCDs that should exhibit radio-flaring magnetic activity.

This Monte Carlo simulator enables evaluation of the observing strategy conducted at AO, permitting an investigation of the adverse effects of RFI that had been qualitatively described previously in Route & Wolszczan (2016b). The simulator indicates that among the undetected, radio-loud UCDs, ~93% were not detected because of insufficient instrumental sensitivity, ~49% because the observation duration was too short, and ~42% were undetected because of both effects. One obvious way to improve the detection rate of UCDs is to observe sources repeatedly, but these results indicate that improving the sensitivity of the observations, which can most readily be accomplished by decreasing RFI in the local environment, would yield the largest gains.

The emission type distribution was also adjusted to examine the possibility that all radio-flaring UCDs flare periodically and there are no sporadic emitters. After changing the emission type distribution to 14/14 for periodic emitters, I recompute the results for 10^7 trials and again scale the results to the 962 UCDs in the local neighborhood. The removal of sporadic emitters results in the detection of only two UCDs with the current observing strategy, with another 41 radio-flaring sources not detected. This slight decline in the size of the magnetically active population to ~4.5% is unsurprising since sporadic emitters are modeled as always detected on account of the lack of information about their temporal emission properties. However, if so-called sporadically flaring sources are actually periodic sources, this alters the calculus as to how to improve the detection of flaring sources. The simulator demonstrates that, in this case, ~93% of sources are not detected due to poor instrumental sensitivity (as before), but ~61% were not observed for a long enough duration. Together, these effects increase to ~51% the number of undetected, magnetically active UCDs missed because of insufficient observation duration and instrumental sensitivity. Thus, while increasing instrumental sensitivity and decreasing RFI would yield the greatest gains in radio-flaring UCD detection, over half of the sources would also benefit from being monitored for greater fractions of their rotation periods, or reobserving sources at different phases of their rotation.

In either case, the simulated fraction of radio-flaring objects closely mirrors the fraction of UCDs with detected radio emission, despite accounting for instrumental effects. Antonova et al. (2013), summarizing previous results, found that ~6% of UCDs stretching from spectral types M7–T6.5 have detectable flaring or nonflaring (quiescent) radio emission. However, they noted that it may be more accurate to report a detection efficiency of ~9% for M7–L3.5 UCDs since only one radio-emitting T dwarf had been detected. Route & Wolszczan (2013, with corrections from Route & Wolszczan 2016b) found that ~3% of L0–T8.5 sources observed at Arecibo Observatory had detectable flaring radio emission. Lynch et al. (2016) discovered one quiescent radio-emitting source out of 13 M7–L8 UCDs newly observed with ACTA, indicating a detection rate of ~8% for both flaring and nonflaring emission. Finally, in their most recent flaring-sensitive Arecibo survey, Route & Wolszczan (2016b) measured a detection efficiency of ~5% for a target list spanning spectral types M9 to T8.5. These results are also similar to the ~9% rate for detection of Hα emission from L4 to T8 UCDs (Pineda et al. 2016).

3.2. Computational Performance and Resource Utilization Results

This Monte Carlo simulator was constructed to leverage the new ISK random number technology to investigate the potential influence of a nearly true random number generation on scientific results and to evaluate its performance characteristics. The simulator software only devotes a few lines of code to the creation of random numbers for the population synthesis model, which can be easily replaced by other pseudorandom number generators (PRNGs) to test ISK performance versus these older PRNGs. This performance comparison appears in Section 5.2. In this section, though, I only report the computational results from the population synthesis simulator driven by ISK number generation.

The Monte Carlo simulator was run on a quad core Intel i7-3740 QM processor, which can operate up to a clock frequency of 3.7 GHz, with 16 GB of RAM. When executed to simulate 10^7 UCD observation events, ≤1.65 GB of memory is used. The run time for random number generation and simulation was 72 ± 3 s, excluding I/O operations. Both random number inputs and simulator results are written to files to enable analysis of the random numbers input into the simulation and postprocessing of simulator results. These files are written in human-readable ASCII format and require ~2.4 GB of hard disk space. Since the random number generation component makes up such a tiny fraction of the run time, these resource requirements and complete simulator run time results are practically independent of the number generator used.

The ISK random number generator component of the simulation requires only 0.395 ± 0.007 s to generate 7 × 10^7 uniformly distributed, 64 bit, floating-point random numbers. For a comparison of this performance as compared to PRNGs, see Section 5.2. This run-time figure includes the effects of Highest Optimizations (-O3) by the Intel Compiler, but it is not multithreaded in any way.
4. The Meaning of the \( \sim 5\% \) Radio-flaring Rate for the Underlying Magnetized UCD Population

The following subsections describe in detail a number of possible astrophysical interpretations of the \( \sim 5\% \) radio-flaring UCD rate.

4.1. Lower Latitudinal Boundary of Auroral Radio Emission

Hallinan et al. (2015) argued that radio and \( H_\alpha \) emissions from UCDs are similar to the auroral emissions from the gas giant planets, which span X-ray to radio wavelengths. At Jupiter, magnetic reconnection events in the outer magnetosphere accelerate electrons that precipitate into the molecular hydrogen-rich atmosphere. This process leads to a number of dissociative, electronic, ionized, and vibrational states that create line emissions spanning infrared to ultraviolet (UV) wavelengths. Precipitating ions that charge-strip to highly ionized states undergo charge exchange with molecular hydrogen, resulting in ions in electronically excited states that create radio and X-ray emission (Bhardwaj & Gladstone 2000).

In their review, which mainly focused on infrared to UV emissions, Bhardwaj & Gladstone (2000) found that Jovian auroral emissions were generally localized to latitudes \( \gtrsim 60^\circ \), although some emissions were observed as far equatorward as \( 40^\circ \). Similarly, Zarka (1998) found that giant radio emissions were confined to \( \gtrsim 60^\circ \). If UCD radio flaring is confined to the polar cap regions, as in the auroral model, the \( \sim 5\% \) detection rate may constrain the average magnetic latitudinal boundary of these auroral caps. However, the viewing angle geometry complicates this analysis, since the inclination angle of the UCD may permit observation of one or both polar caps. Furthermore, explaining the UCD radio-flaring fraction in terms of a uniform polar cap region likely oversimplifies the problem, as auroral emissions are usually confined to a latitudinal annulus that is also longitudinally constrained (e.g., Waite et al. 2001). Thus, given an isotropic distribution of magnetic axes in the local neighborhood, the fraction of radio-flaring UCDs may provide an estimate on the lower latitudinal boundary of auroral radio emission.

4.2. Covering Fraction of Active Regions

Both ECM and gyrosynchrotron radio-flaring mechanisms appear to be related to solar flares, sunspots, and active regions (Treumann 2006; Shibasaki et al. 2011). If UCD radio flares also occur above active regions, then the \( \sim 5\% \) radio-flaring fraction may approximate the covering fraction of active regions on UCDs. By comparison, the maximum covering fraction of sunspots within active regions during solar maximum is \(< 1\% \) (Solanki et al. 2005). Morin et al. (2008) leveraged Zeeman Doppler imaging (ZDI) to find that low-contrast, magnetized regions likely cover \( \sim 2\% \) of the rapidly rotating, fully convective M4 dwarf V374 Peg. Similarly, Lynch et al. (2015) modeled radio emission from TVLM 513 and J0746+20 and found that the frequency and temporal emission patterns observed with the expanded Jansky VLA were consistent with gyrosynchrotron radiation emitted from a small number of isolated emitting regions. Morin et al. (2010), reporting ZDI results for six fully convective M5–M6 stars, found Stokes V filling factors that ranged from 6\% to 100\%. Berger et al. (2008) estimated a covering fraction of \( \sim 50\% \) for TVLM 513 based on a multiwavelength observation campaign. Although estimates of the covering fraction of active regions from UCDs spans the unhelpful range of 2\%–100\%, a population-based estimate of \( \sim 5\% \) agrees with estimates provided by other methods. Thus, for an isotropic distribution of UCD magnetic axes, the flaring fraction may provide an upper limit on the surface coverage of magnetized active regions.

4.3. Duty Cycle of Solar Maximum/Bistable Dynamo Activity

ECM radio emission from UCDs is emitted either parallel to the local magnetic field (LO mode) or perpendicular to the field (RX mode) (Treumann 2006). Similarly, the angle between the local magnetic field and gyrosynchrotron emission ranges from \( 30^\circ \) to \( 80^\circ \) (White et al. 2011). Given our line of sight from Earth, these geometric effects likely restrict radio emissions to a limited set of detectable latitudes.

However, it has been known for over a century that the active regions of the Sun migrate as the sunspot cycle progresses. Solar active regions emerge in two bands at latitudes \( \sim 25^\circ \) N/S around the time of solar minimum, and then the centers of these bands march toward the equator, reaching their lowest latitudinal extent just prior to the solar minimum of the next cycle (Hathaway 2010). Solar maximum corresponds to a time of a strong toroidal (but weaker poloidal) component to the solar magnetic field, while solar minimum represents a time of stronger poloidal flux. Route (2016) leveraged multiple lines of argument to hypothesize that UCDs host magnetic activity cycles similar to those found on the Sun. Kitchatinov et al. (2014) constructed theoretical models of oscillatory dynamo behavior inside fully convective M dwarfs and argued that surveys that search for activity on M dwarfs could be used to determine the timescale of M dwarf magnetic reversals, whether they are indicative of solar-like activity cycles or dynamo bistability. The fraction of M dwarfs with observed activity from active regions would indicate the fraction of time that their oscillatory dynamos spend in the strong toroidal field state (solar maximum) as opposed to the strong poloidal field state. Alternatively, Morin et al. (2010, 2011) suggested that bistable dynamos are manifested by cyclic or chaotic activity states. In any case, the discovery of the fraction of UCDs exhibiting activity would enable researchers to infer parameters of stellar convection near the photosphere. Thus, the \( \sim 5\% \) detection rate for radio-flaring UCDs may represent the duration of some component of the magnetic activity cycle or bistable dynamo of these objects. However, in the activity cycle scenario, uncertainties in the flaring mechanism and their modes of operation make it unclear whether UCD radio bursts are manifestations of solar minimum activity focused near the poles (e.g., Hallinan et al. 2006) or solar maximum activity from active regions located at midlatitudes (e.g., Wolszczan & Route 2014), potentially adding an additional complication.

4.4. Parameterization of the Average Electron Velocity in Beamed Emission

If the radio emission is beamed, as is thought to be the case for ECM, then the probability, \( P \), of viewing the emission can be expressed as a function of the half solid angle of the radiation cone, \( \theta \), by \( P = 2\theta/(4\pi) \) (Antonova et al. 2013). This angle is related to the velocity of the electrons, \( v \), and the speed of light, \( c \), by \( v/c = \cos(\theta) \). An \( \sim 5\% \) detection probability yields an average electron beam velocity of \( v = 0.96c \) for
flaring radio emission. Thus, the fraction of radio-flaring UCDs may constrain the mean velocity of the electrons that cause ECM emission.

4.5. Average Radio Flare Duty Cycle

Hallinan et al. (2008) found that TVLM 513 and LSR J1835+3259 have highly polarized radio flare duty cycles of a few percent, and a much larger duty cycle of >30% for the L3.5 dwarf 2MASS J00361617+1821104. Radio observations of J0746+20 revealed a left circularly polarized (LCP) flaring duty cycle of <1% (Berger et al. 2009), while Williams et al. (2015) measured a 20%–35% duty cycle for 100% LCP flaring from the blended M7e 2MASS J13142039+1320011 AB (J1314+13). The duty cycle for the recently reported, potentially ultrarapidly rotating J1122+25 (Route & Wolszczan 2016a) is ≤18%, pending verification of its period. An ~5% detection rate may merely reflect the low duty cycle of reconnection activity for the ensemble of observed UCDs.

4.6. The Fraction of UCDs That Have ~1–3 kG Magnetic Field Strengths

Radio observations of UCDs have been conducted over a range of frequencies for various sources, at maximum spanning 1.4–22.5 GHz for J1314+13 (e.g., McLean et al. 2011). However, most surveys that have sought to discover new radio sources probed a narrower range of frequencies, usually within a 100 MHz bandpass around either 4.8 GHz or 2.28 GHz–8 GHz (Burgasser 2002; Burgasser & Putman 2005; Berger et al. 2009; Antonova et al. 2008, 2013). Even the WIDAR correlator only allows a study of flaring across a ~1.4 kG range, which is roughly equivalent to one-half the magnetic field strength found above sunspots (Solanki et al. 2005). Another issue is that UCDs that lack magnetic activity at 8.5 GHz, corresponding to stronger fields, are not necessarily inactive, nonmagnetic, or without detectable radio emission; it could simply be that many of these sources have detectable magnetic activity at lower frequencies and, hence, lower magnetic field strengths.

4.7. Detected Radio-flaring UCDs Represent Only a Narrow Range of Ages and Masses

Another concern is whether the detected UCDs are “special” in some way. Christensen et al. (2009) used an empirical scaling law to describe how the internal convected energy flux within objects spanning from planets to fully convective, rapidly rotating stars is related to their magnetic field strengths. Kao et al. (2016) subsequently found that while flaring late-L dwarfs fit this law, the radio-flaring T dwarfs they analyzed mildly violated it, due to stronger magnetic fields than expected. With few known magnetized T dwarfs, it remains to be seen whether most T dwarfs follow the scaling law, or whether the magnetic activity of radio-flaring T dwarfs is uncommonly energetic.

Given the magnetic field strengths probed by the described surveys, the narrow subset of magnetic field strengths and internal magnetic energies probed may also correspond to the examination of brown dwarfs within a restricted range of ages and masses. Reiners & Christensen (2010) leveraged a number of scaling relations, including the one developed by Christensen et al. (2009), to investigate the evolution of exoplanet and brown dwarf magnetic fields over time. They found that while exoplanet magnetic fields systematically decline with age, brown dwarf magnetic fields grow until interior deuterium burning stops (∼10^9 year for a 70 M_J object), at which point the field strengths decay. These models indicate that the frequency space searched for radio emission is probing only a narrow range of brown dwarf ages and masses.

4.8. Do Flaring UCDs Have Nearby, Unresolved Companions?

The source of the magnetospheric plasma and the energetics of its radio emission in increasingly cool, neutral atmospheres remain open questions. Rodríguez-Barrera et al. (2015) found that the thermal ionization of H, Na, K, Mg, and Fe would be sufficient to allow at least partial coupling of UCD atmospheres to their magnetic fields for temperatures ≥1400 K. The authors also summarize how dust–dust collisions within clouds, lightning, Alfvén ionization, and cosmic-ray impacts may also increase ionization.

Schrijver (2009) suggested that the radio-emitting plasma would be present in a hot, tenuous stellar corona heated by solar-like dynamo activity or magnetospheric activity linked to corotation breakdown, with the contributions of each component shifting toward the latter at later spectral types. Using the Jovian aurorae as a template, Nichols et al. (2012) quantified the effects of corotation breakdown. They found that the coupling of UCD magnetospheres with the surrounding ISM environment led to angular velocity shear at high latitudes that drove strong currents. This current model proved to be...
sufficient to power the observed radio emissions from several UCDs. Both works suggested that the interstellar medium would provide both plasma and energy to help drive auroral activity.

Alternatively, Hallinan et al. (2015) suggested that the plasma may be provided by aurora-induced sputtering of the atmosphere, a volcanically active orbiting moon or planet, or photospheric reconnection. In the case of the M8.5 dwarf LSR J1835+3259, they argued that unipolar induction by an Earth-mass planet moving within 20 stellar radii of the UCD would provide the energy necessary to power auroral currents and the observed radio emission, thus operating in a manner similar to the Jupiter–Io system.

Potential evidence of the influence of unresolved companions comes from Very Long Baseline Array observations of TVLM 513 at 8.5 GHz. These observations may have marginally resolved its radio emission into two components separated by ∼20 stellar radii (∼0.01 au). If real, Forbrich & Berger (2009) argued that the emission would likely indicate the presence of a nearly equal mass binary. On the other hand, the periodic radio flares from the secondary component of the J0746+20 system do not support this scenario, as the 2.7 au separation of the components is too large to result in magnetic interaction (Harding et al. 2013). Thus, not all known radio-flaring UCD systems can be explained with this mechanism. Nevertheless, the ∼5% detection rate potentially estimates the fraction of UCDs that have planetary-mass companions embedded in their magnetospheres.

However, the work does not permit us to discriminate among these scenarios and speculates that the ∼5% radio-flaring UCD rate represents the convolution of at least several effects from this list. Assuming that the 5% magnetized UCD rate represents only one of these scenarios would then lead to an underestimation of these competing effects. More observations are required to better understand the source size and magnetic reconnection phenomenology that give rise to flaring radio emission. Furthermore, I note that the radio observations leveraged in this Monte Carlo simulator are restricted in radio frequency, corresponding to observations that only probe a restricted range of magnetic field strengths. Most likely, every UCD has detectable radio emission, given sufficiently sensitive instrumentation tuned to frequencies that correspond to the magnetic field strengths present in each source.

5. ISK Utility and Performance Considerations

5.1. ISK Advantages and Disadvantages

One disadvantage of using a DRNG such as ISK is that it will make Monte Carlo simulation debugging more difficult than when simpler PRNGs are used, as it will not be possible to replicate problems that occur when particular seeds are used (Bevington & Robinson 2003). Thus, PRNGs retain their importance in the testing phase of software development, even if they are supplanted in final products. Another obvious downside is the limited portability of software designed with ISK, since only more recent processors, such as the 2013 Intel Series 7 (Ivy Bridge), 2015 AMD FX-8000 series, and later processors have the necessary hardware entropy source. In the absence of the entropy source, code would need to default to a standard PRNG. However, support for the RDRAND and RDSEED instruction sets was introduced in all major compilers starting with GCC 4.6, Intel 12.1, and Microsoft Visual Studio 2012.10

There are several advantages of using a hardware-based TRNG, yet these are mainly to be found in number generation randomness. ISK was originally devised to increase cryptographic security for number generation. In 2006, various researchers demonstrated that a PRNG algorithm called Dual Elliptic Curve Deterministic Random Bit Generator (Dual EC) was extremely slow and, although compliant with NIST SP 800-90, contained an exploitable back door. This security vulnerability would permit the decryption of SSL/TLS traffic over computer networks (Checkoway et al. 2014). ISK is unaffected by the security concerns that trouble PRNGs due to its more elaborate seed mechanism, leaving the system unexploitable unless an attacker has physical access to the entropy block (Shrimpton & Terashima 2015).

However, the generation of high-quality random numbers is not just an esoteric or security concern. The generation of high-quality random numbers is important to the computation of accurate solutions, as many simulations are constructed and executed under the assumption of perfect random number generation. For example, subtle correlations in the sequence of normal deviates used in Monte Carlo simulations of fising square lattices with periodic boundary conditions caused systematically incorrect results in internal energy and specific heat for various PRNGs (Ferrenberg et al. 1992). This leads to the prescription that the results of algorithms from multiple number generators must be compared and verified to prevent the occurrence and propagation of such systematic errors. Similarly, it took a number of years for researchers to realize that the generation of k random numbers created from linear congruential generators (LCGs) and multiplicative LCGs (MGLCs) resulted in points in k-dimensional space that tended to lie on planes (Press et al. 2007).

Another advantage is that while PRNGs have periodicities, which cause the random number sequence to repeat after some large number of draws, ISK does not. PRNGs in use today have periods ranging from $2^{21} - 1$ ($\sim 4.3 \times 10^9$) as in the 32 bit Xorshift RNG (Press et al. 2007) to $2^{9937} - 1$ ($\sim 4.3 \times 10^{3001}$) in the Mersenne Twister (Matsumoto & Nishimura 1998). ISK’s entropy source renders periodicity concerns obsolete, thus permitting unrestricted flexibility in determining the size of models and the production of very large samples of numbers.

However, the greatest advantage in using ISK is in the unpredictability of the numbers generated. No PRNG available today conforms to the previously mentioned specifications for randomness. Although ISK enables almost truly random numbers to be effortlessly generated that obviate many of the given concerns, the effects of this randomness on scientific results may be harder to evaluate.

5.2. Intel Secure Key Performance versus PRNGs

Since ISK number generation is implemented in hardware, it has been reported that it creates random numbers almost an order of magnitude faster than software-implemented PRNGs, with the additional benefit of being more energy efficient as well (Intel Corporation 2012; G. Taylor 2017, private communication).

10 “Intel Xeon Processor E5-2600 V2 Product Family Technical Overview,” at https://software.intel.com/en-us/articles/intel-xeon-processor-e5-2600-v2-product-family-technical-overview.
However, the performance results from this simulator do not support these assertions. Figure 4 compares the run time for the generation of $10^7$ 64-bit, floating-point, random numbers for a handful of random number generators. These results are grouped by programming language implementation, with Python Default (random.random), Python NumPy (numpy.random.random_ sample), and Python RdRand (RdRandom.random) implemented in Python 2.7, and C default (rand), C ISK (_rdrand64_step), and C MT19937-64 (genrand64_real2) being implemented in C. The Mersenne Twister PRNG (MT19937-64) as implemented in C is the fastest, with a run time of 0.018 ± 0.001 s on the system described in Section 3.2. This is followed by the NumPy PRNG (0.126 ± 0.003 s), the C default PRNG (0.197 ± 0.002 s), ISK CSPRNG (0.395 ± 0.007 s), the Python default PRNG (2.143 ± 0.067 s), and the Python implementation of ISK called RdRand (40.193 ± 1.173 s). Although the run times varied across the tested architectures (Ivy Bridge, Haswell, Kaby Lake), platforms (Linux, Mac Os X, Windows), and compilers (GCC, Intel, Microsoft Visual C++), the relative results stayed the same.

For clarification, the Python default and Python NumPy PRNGs are actually Python implementations of the Mersenne Twister. It is interesting to note that these Python routines at their core are coded in C, as is the Python RdRand. Clearly the overhead of interfacing with Python introduces an approximately order-of-magnitude increase in the run time of random number generation, once again proving that for those who require the greatest computational performance, the lower-level programming languages offer superior performance. The only difference between calls to random.random and numpy. random.random is that the former involves additional overhead caused by the retrieval of one number at a time, while this operation is vectorized in NumPy.

However, it is noteworthy that the C-implemented ISK number generator performs roughly 20× slower than the C-implemented Mersenne Twister, even though the production of the nondeterministic random numbers is hardware-encoded. Part of this relatively poor performance may be due to the retrieval by the algorithm of one 64 bit random number at a time, as opposed to tapping into a stream of random bits from the processor. Nevertheless, my implementation of a uniform distribution using ISK is over two orders of magnitude faster than its Python-implemented counterpart.

How ISK number generation scales in a multithreaded environment is beyond the scope of this work, although it may better leverage the hardware-implemented entropy source’s ability to produce random numbers. Previous efforts to improve random number generation performance through parallelization have relied on different processors using diverse random number generation algorithms, or different substreams of one algorithm spread across a number of processors, which may result in correlations among generators or the potential for long-range correlations, respectively (Hellekalek 1998). With ISK, each processor core produces random numbers from a shared on-chip entropy source. Also, in contrast to other common PRNGs, such as the xorshift1024* PRNG behind RANDOM_NUMBER in Fortran 95 and later, the multi-threaded generation of random numbers does not come at the cost of reducing the periodicity of random number generation. ISK multithreading delivers a performance that increases linearly until all available hardware threads are used, potentially providing the first means of producing uncorrelated, high-quality normal deviates in a parallelized fashion (Intel Corporation 2012).

It is difficult to assess what effects an almost-TRNG may have on the accuracy of scientific results. While this topic has been discussed in Section 5.1, it is clear from the sparse literature that analyzes scientific results as a function of PRNGs that this topic is usually not a concern unless strange patterns of behavior emerge, as in the Ising lattice case. In this work, I did not find any statistically significant difference between the scientific results obtained with ISK and those obtained from the Python NumPy PRNG. However, given the simplicity of exchanging random number generators in well-written code, and given the checkered history of random number use, it may be worthwhile to test the robustness of scientific results by varying the number generator. Press et al. (2007) recommended that scientists not use “overengineered” cryptographically secure random number generators. However, ISK represents a significant improvement in the performance of such number generators, providing almost truly random, high-quality

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9.222 RANDOM_NUMBER—Pseudo-random number,” at https://gcc. gnu.org/onlinedocs/gfortran/RANDOM_005fNUMBER.html.
number generation while incurring only a moderate performance penalty.

5.3. Potential Astrophysical Applications of the Intel Secure Key Random Number Generator

A number of potential astrophysical applications of ISK may exist, but here I highlight only three: emcee, ENZO, and the Cratered Terrain Evolution Model (CTEM). Emcee is an affine-invariant ensemble sampler for Markov chain Monte Carlo (MCMC), implemented in Python 2.7 (Foreman-Mackey et al. 2013). Emcee has been used to compare observational data with theoretical models for applications ranging from the analysis of supernovae light curves, to radial velocity searches for exoplanets, to the study of tidal disruption of galaxies. ISK could replace the NumPy PRNG typically used to create the starting values for every parameter value for every ensemble member (walker) that establishes the initial conditions for MCMC to explore. This would lead to revisions of utilities sample_ball and sample_ellipsoid, for example, which initialize walker values for various parameters. Additional calls to generate random numbers using the NumPy PRNG are scattered throughout the Ensemble and Sampler classes. However, as the discussion in Section 5.2 indicates, replacing the NumPy PRNG would likely come with a moderate performance penalty.

Replacement of the NumPy PRNG with ISK would eliminate the need to track the state of the random number generator in the emcee Sampler objects, unless reproducibility is required. The tracking, saving, and loading of random number generator states that are found in emcee may be both advantageous and problematic. Tracking states allows for the reproduction of a sequence of behavior in the Markov chains that may be useful for tracing the evolution of certain ensemble members as they traverse the parameter space. On the other hand, this tracking of states serves the practical purpose of guarding against the repeated draws of the same random number sequence from the deterministic random number generator. The implementation of ISK random number generation in emcee would create the obverse situation: since ISK is an almost true random number generator, the evolution of a set of ensemble members would not be reproducible, yet there would also be no need to guard against repeating the same random number draws from a single PRNG. However, a simple modification to the code to save the ISK-generated random numbers would correct for the first effect.

Another potential application of ISK is to ENZO, an open-source, structured adaptive mesh refinement code used to model astrophysical fluid evolution at a wide range of spatial and temporal scales. It is written in C, Fortran, and Python. ENZO includes support for magnetohydrodynamics, gravity, N-body dynamics, chemistry, radiative cooling and heating, background radiation fields, radiation transport, heat conduction, and star formation and feedback. ENZO has been used to model a wide variety of problems, including star formation, galaxies, and galaxy clusters (Bryan et al. 2014). I note in my perusal of the ENZO 2.5 code that a number of routines make calls to random number seeding and generating routines. Two examples include MAKE_FIELD.f and STAR_MAKER1.f, which generate random field realizations and create galaxy particles, respectively. These routines may benefit from invoking ISK’s RDSEED for improved seeding capabilities, or invoking RDRAND instead, which may obviate the need for the seeding in ENZO altogether due to the improved quality of the random numbers themselves.

Similarly, the solar system Monte Carlo cratering code CTEM, which has been used to model the Late Heavy Bombardment of the lunar surface, may benefit from the enhanced seeding and random number generation that ISK provides (Minton et al. 2015). Since CTEM is a parallelized FORTRAN code, the application of ISK to CTEM random number generation would also eliminate concerns regarding correlated number generation and reduced periodicity.

Of course, other astrophysical codes may benefit from ISK and can be easily modified to integrate its number-generation capabilities. Noting the concerns described by Ferrenberg et al. (1992) and Press et al. (2007), it may be worthwhile to perform numerical simulations with several random number generators and compare their results.

6. Conclusion

This paper has presented the methods and results from the construction of the first magnetized UCD population synthesis simulator. This simulator has leveraged the latest probability density functions to accurately reproduce the behavior and physical characteristics of these fully convective stars and brown dwarfs. Radio surveys that were sensitive to short-duration radio flares were used to model the likelihood that any single UCD has flaring behavior. Repeated observations were used to estimate the fractions of periodically flaring and sporadically flaring sources (Route 2016). Recent research efforts have enabled the compilation of UCD rotational periods, allowing this simulator to model them using a modified lognormal period distribution (Radigan et al. 2014). UCD radio flare flux densities were modeled to follow the energy distribution of stellar flares in the absence of more comprehensive observations of UCD flares (Crosby et al. 1993; Güdel et al. 2003). Next, these physical parameters for the simulated population of UCDs were combined with the distributions of observation durations and sensitivities that have been compiled from detailed observation logs accumulated over several years (Route 2013; Route & Wolszczan 2013, 2016b).

The simulated results presented here indicate that the population of radio-flaring UCDs is $\sim 13 \times$ larger than that detected thus far, yielding a flaring UCD fraction of $\sim 4.6\%$. This simulator has also allowed us to diagnose why so few of these objects have thus far been detected, with $\sim 93\%$ requiring more sensitive instrumentation than the highly sensitive AO can provide, $\sim 49\%$ of sources requiring longer (or repeated) observing sessions to be detected, and $\sim 42\%$ requiring both more sensitivity and longer observations. As Route & Wolszczan (2016b) pointed out, gains in instrumental sensitivity are not the only means by which more sensitive observations can be obtained; a concerted campaign to reduce the effects of RFI surrounding radio telescopes would also be helpful.

The origin of the $\sim 5\%$ UCD radio-flaring fraction is currently a mystery. In the years since the previous discussion of the nature of the fraction of radio-active UCDs (e.g., Antonova et al. 2013), a number of discoveries have

12. “emcee: The MCMC Hammer,” at http://dan.iel.fm/emcee/current/.
13. “The ENZO Project,” at http://enzo-project.org/.
been made in UCD astrophysics of both observational and theoretical natures. This paper has presented eight scenarios to explain this radio-flaring rate and to help guide future scientific research in this vein. The scenarios described in Section 4, unfortunately, showcase our lack of basic understanding of the processes and phenomenology of radio emission from UCDs. It is also likely that the \( \sim 5\% \) detection rate represents an amalgam of at least several of these explanations.

This paper has also presented the first-ever application of a novel random number generation technology, ISK, to scientific computing. ISK represents a major milestone in random number generation, producing numbers that are the closest yet to truly random. I have demonstrated its usage and the ease by which it can substitute for other PRNGs, through the design and implementation of this Monte Carlo simulator. Key to the software implementation of the described probability distributions was the construction of uniform, normal, and lognormal distributions, each of which leverages the ISK random number generator (Appendix).

The usage of ISK as opposed to the Mersenne Twister that runs at the heart of Python’s random number generators did not result in any statistically significant alteration to the scientific conclusions of this work. I also note that random number generation made up a tiny, insignificant fraction of the Monte Carlo simulator run time, making the utilization of various random number generators hardly noticeable. However, the computational performance results presented here suggest that while ISK may produce random numbers more quickly than a number of PRNGs, it is unable to outperform several implementations of the Mersenne Twister algorithm. Nevertheless, future experimentation with ISK in other scientific applications may yield additional improvements in accuracy and performance.

ISK holds the potential to improve the accuracy of any type of astrophysical computation that requires random number generation. Although this technology has yet to be applied to high-performance computing, preliminary tests by Intel Corporation suggest that improvements in both scalability and computational efficiency await. Nevertheless, many communities, in astrophysics, engineering, the life sciences (e.g., Sipos et al. 2011), finance (e.g., Boyle et al. 1997), and statistics, may wish to investigate the application of ISK and the techniques presented here to Monte Carlo simulation.

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Appendix

A.1. Creation of a Uniform Distribution from Digital Random Numbers

The random number generator implemented at the core of this simulator is based on the C routine RDRAND.c issued in the ISK toolkit. RDRAND.c creates 16, 32, and 64 bit unsigned integers. I then scaled these unsigned integers, which vary in size from 0 to \( 2^n - 1 \), where \( n \) is the bit size of the number (16, 32, or 64), to create a uniform distribution using

\[
x_i = \frac{r_i}{2^n - 1},
\]

where \( r_i \) is the entropy-based, random, unsigned integer provided by the Intel-supplied routine, and \( x_i \) is the uniformly distributed deviate, varying on the domain \([0,1)\). Since a Monte Carlo simulator requires large numbers of such random numbers, the generated \( x_i \) values are stored in an array of type double for 16 and 32 bit numbers and long double for 64 bit values. My uniformly distributed ISK number generator is implemented in C and compiled with the Intel compilation suite.

A.2. Conversion of a Uniform Distribution of Digital Random Numbers into a Normal Distribution

The sensitivity distribution was modeled using a double Gaussian, so for the Monte Carlo simulator to reproduce this behavior using real, digital random numbers, default uniform distribution random number generators are inadequate. Pairs of uniformly distributed random numbers, \((x_i, y_i)\), obtained by the above method are converted via the Box & Muller (1958) method into pairs of normally distributed digital random numbers \((y_i, y_j)\), when normal distribution parameters \( \mu \) (mean) and \( \sigma \) (standard deviation) are supplied:

\[
y_i = \sqrt{-2 \ln(x_i)} \cos(2\pi y_j)
y_j = \sqrt{-2 \ln(x_i)} \sin(2\pi y_j).
\]

This normal distribution generator is implemented in Python 2.7 and vectorized by the NumPy package.

A.3. Creation of a Lognormal Distribution from Digital Random Numbers

The rotational period probability density function is fit by parameters \( \mu \) and \( \sigma \), which are then used in the modified normal distribution function described above. The output from the normal distribution, \( y_i \), is related to the rotational periods by (Mood et al. 1974)

\[
y_i = \ln(P_i).
\]

The lognormally distributed rotational periods, \( P_i \), are then computed by inverting this expression. This routine is also implemented in Python 2.7.

All distributions were validated by comparison with random numbers generated by other PRNGs included with Python and MATLAB, and their bulk statistical properties were very similar, although ISK compliance with NIST SP 800-90A, B,
and C, FIPS-140-2, and ANSI X9.82 makes the numbers that it generates closer to truly random. However, it is beyond the scope of this work to present a detailed statistical analysis and comparison of the ISK-derived random number distributions with those created by PRNGs.

**ORCID iDs**

Matthew Route @ https://orcid.org/0000-0001-6987-6527

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