Linear Independence of Generalized Poincaré Series for Anti-de Sitter 3-Manifolds

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Received May 13, 2020, in final form April 13, 2021; Published online April 23, 2021
https://doi.org/10.3842/SIGMA.2021.042

Abstract. Let $\Gamma$ be a discrete group acting properly discontinuously and isometrically on the three-dimensional anti-de Sitter space $\text{AdS}^3$, and $\Box$ the Laplacian which is a second-order hyperbolic differential operator. We study linear independence of a family of generalized Poincaré series introduced by Kassel–Kobayashi [Adv. Math. 287 (2016), 123–236, arXiv:1209.4075], which are defined by the $\Gamma$-average of certain eigenfunctions on $\text{AdS}^3$. We prove that the multiplicities of $L^2$-eigenvalues of the hyperbolic Laplacian $\Box$ on $\Gamma \backslash \text{AdS}^3$ are unbounded when $\Gamma$ is finitely generated. Moreover, we prove that the multiplicities of stable $L^2$-eigenvalues for compact anti-de Sitter 3-manifolds are unbounded.

Key words: anti-de Sitter 3-manifold; Laplacian; stable $L^2$-eigenvalue

2020 Mathematics Subject Classification: 58J50; 53C50; 22E40

1 Introduction

A pseudo-Riemannian manifold is a smooth manifold $M$ equipped with a smooth non-degenerate symmetric bilinear tensor $g$ of signature $(p,q)$ on $M$. It is called Riemannian if $q = 0$, and Lorentzian if $q = 1$. As in the Riemannian case, the Laplacian $\Box_M := \text{div}_M \circ \text{grad}_M$ is defined as a second-order differential operator on $M$. We note that it is a hyperbolic differential operator if $M$ is Lorentzian. We write $L^2(M)$ for the Hilbert space of square-integrable functions on $M$ with respect to the Radon measure induced by the pseudo-Riemannian structure. For $\lambda \in \mathbb{C}$, we denote by

$$L^2_\lambda(M) := \{ f \in L^2(M) \mid \Box_M f = \lambda f \text{ in the weak sense} \}.$$ 

The set of $L^2$-eigenvalues $\text{Spec}_d(\Box_M) := \{ \lambda \in \mathbb{C} \mid L^2_\lambda(M) \neq 0 \}$ is called the discrete spectrum of $\Box_M$.

Our interest is the multiplicities of $L^2$-eigenvalues $\lambda$ of $\Box_M$, denoted by

$$\mathcal{N}_M(\lambda) := \dim_{\mathbb{C}} L^2_\lambda(M) \in \mathbb{N} \cup \{\infty\}.$$ 

In the Riemannian case, the Laplacian is an elliptic differential operator and the distribution of its discrete spectrum has been investigated extensively, such as the Weyl law for compact Riemannian manifolds. However, it is not the case for non-Riemannian manifolds. Kobayashi [19], and later Fox–Strichartz [4], investigated the distribution of the discrete spectrum of the Laplacian $\Box_M$ of some pseudo-Riemannian manifolds, i.e., when $M$ is the flat pseudo-Riemannian manifold $\mathbb{R}^{p,q}/\mathbb{Z}^{p+q}$ and is the Lorentzian manifold $S^1 \times S^q$, respectively.

Let us recall some basic notions. A discontinuous group for a homogeneous manifold $X = G/H$ is a discrete subgroup $\Gamma$ of $G$ acting properly discontinuously and freely on $X$ (Kobayashi [18, Definition 1.3]). In this case, the quotient space $X_\Gamma := \Gamma \backslash X$ carries a $C^\infty$-manifold structure.
such that the quotient map $p_\Gamma: X \to X_\Gamma$ is a covering of $C^\infty$ class, hence $X_\Gamma$ has a $(G,X)$-structure induced by $p_\Gamma$. If we drop the assumption of freeness, $X_\Gamma$ is not always a manifold but carries a nice structure called an orbifold or $V$-manifold. Proper discontinuity is a more serious assumption which assures $X_\Gamma$ to be Hausdorff in the quotient topology. We remark that the action of a discrete subgroup $\Gamma$ on $X$ may fail to be properly discontinuous when $H$ is noncompact. In order to overcome this difficulty, Kobayashi [16] and Benoist [1] established the properness criterion for reductive $G$ generalizing the original criterion by Kobayashi [15].

Whereas discontinuous groups for the de Sitter space $dS^n := SO(0,n,1)/SO(n-1,1)$ are always finite groups (the Calabi–Markus phenomenon, see [3, 15]), there are a rich family of discontinuous groups for the anti-de Sitter space, see, e.g., [5, 17, 23]. We treat, in this article, the three-dimensional anti-de Sitter space $AdS^3 := SO_0(2,2)/(\{\pm 1\} \times SO_0(2,1))$.

For $m \in \mathbb{N}$, we set
\[
\lambda_m := 4m(m-1).
\]

We prove:

**Theorem 1.1.** For any finitely generated discontinuous group $\Gamma$ for $AdS^3$,
\[
\lim_{m \to \infty} N_{\Gamma \setminus AdS^3}(\lambda_m) = \infty.
\]

**Remark 1.2.**

1. A discontinuous group $\Gamma$ for $AdS^3$ is called standard [10, Definition 1.4] if it is contained in a reductive subgroup of $SO_0(2,2)$ which acts properly on $AdS^3$ such as $SU(1,1)$. When $\Gamma$ is torsion-free and standard, Kassel–Kobayashi [11, 12] established the theory of spectral decomposition of $L^2(\Gamma \setminus AdS^3)$ into eigenfunctions of the (hyperbolic) Laplacian. Moreover, a stronger result than Theorem 1.1 holds in this case: $N_{\Gamma \setminus AdS^3}(\lambda_m) = \infty$ for sufficiently large $m \in \mathbb{N}$ (Kassel–Kobayashi [13]). On the other hand, a full spectral decomposition is not known. The construction of $L^2$-eigenfunctions by generalized Poincaré series still works for the non-standard case, showing that $\lambda_m$ is an $L^2$-eigenvalue on $\Gamma \setminus AdS^3$ for sufficiently large $m \in \mathbb{N}$ [10]. Theorem 1.1 is also applicable to non-standard $\Gamma$, for example, in the case where $\Gamma$ is Zariski dense in $SO(2,2)$.

2. The assumption that $\Gamma$ is finitely generated could be relaxed. In fact, the exponential growth condition (see (2.9)) for $\Gamma$-orbits is essential in the proof of Theorem 1.1, and there exist infinitely generated discontinuous groups $\Gamma$ satisfying (2.9) and the conclusion of Theorem 1.1 holds for such $\Gamma$ (see Theorem 3.1 which is proved without finitely generated assumption).

3. An analogous statement to Theorem 1.1 also holds when $\Gamma \setminus AdS^3$ is an orbifold. See Section 2.3 for the argument when we drop the assumption that the $\Gamma$-action is free.

Now we consider a small deformation of a discrete subgroup. The study of stability for properness was initiated by Kobayashi [17] and Kobayashi–Nasrin [20] and has been developed by Kassel [9] and others. Moreover, Kassel–Kobayashi [10] proved the existence of infinite stable $L^2$-eigenvalues under any small deformation of discontinuous groups. In this article, we also consider the multiplicities of stable $L^2$-eigenvalues (Definition 1.3) and prove that they are unbounded.

To be precise, let $X_n$ be the $n$-fold covering of $X_1 := AdS^3$ for $1 \leq n \leq \infty$, and $G_n$ the Lie group of its isometries. Every compact anti-de Sitter 3-manifold $M$ is of the form $M \cong \Gamma \setminus X_n$ for some finite $n$, where $\Gamma(\subset G_n)$ is a discontinuous group for $X_n$ by Kulkarni–Raymond [21, Theorem 7.2] and Klingler [14]. We take $n$ to be the smallest integer of this property.
Let $\text{Hom}(\Gamma, G_n)$ be the set of group homomorphisms with compact-open topology, and $\mathcal{U}_\Gamma$ the set of neighborhoods $W$ in $\text{Hom}(\Gamma, G_n)$ of the natural inclusion $\Gamma \subset G_n$ such that for any $\varphi \in W$, the map $\varphi$ is injective and $\varphi(\Gamma)$ acts properly discontinuously on $X_n$. One knows $\mathcal{U}_\Gamma \neq \emptyset$ [14, 17]. By definition, $\lambda$ is a stable $L^2$-eigenvalue if $\min_{\varphi \in W} N_{\varphi(\Gamma)\backslash X_n}(\lambda) \neq 0$ for some $W \in \mathcal{U}_\Gamma$. Moreover, for any $\lambda \in \mathbb{C}$ and any inclusion $W' \subset W$ in $\mathcal{U}_\Gamma$, we have an obvious inequality
\[
\min_{\varphi \in W'} N_{\varphi(\Gamma)\backslash X_n}(\lambda) \geq \min_{\varphi \in W} N_{\varphi(\Gamma)\backslash X_n}(\lambda).
\]

**Definition 1.3.** For a compact anti-de Sitter 3-manifold $M$, we say that
\[
\tilde{N}_M(\lambda) := \sup_{W \in \mathcal{U}_\Gamma} \min_{\varphi \in W} N_{\varphi(\Gamma)\backslash X_n}(\lambda)
\]
is the multiplicity of a stable $L^2$-eigenvalue $\lambda$.

There exist infinitely many $m \in \mathbb{N}$ such that $\tilde{N}_M(\lambda_m) \geq 1$, namely $\lambda_m$ is a stable $L^2$-eigenvalue for sufficiently large $m$ [10, Corollary 9.10]. However, to the best knowledge of the author, it is not known whether $\tilde{N}_M(\lambda_m)$ is finite. We prove:

**Theorem 1.4.** For any compact anti-de Sitter 3-manifold $M$,
\[
\lim_{m \to \infty} \tilde{N}_M(\lambda_m) = \infty.
\]

The organization of this article is as follows. A key step to our proof is to find a family of $L^2$-eigenfunctions of $\Box_{\text{AdS}^3}$ with eigenvalue $\lambda_m$ on $\text{AdS}^3$ for which the corresponding “generalized Poincaré series” are linearly independent, see Proposition 3.2. In Section 2, we recall some facts about $L^2$-eigenfunctions of $\Box_{\text{AdS}^3}$ and their generalized Poincaré series which were introduced in [10] as the $\Gamma$-average of these eigenfunctions. We then give a uniform estimate of the “pseudo-distance” between the origin and the second closest point of each $\Gamma$-orbit (see Section 2.4). In Section 3, we complete a proof of Proposition 3.2. In Section 4, we prove a generalization of Theorem 1.4 to the case of convex cocompact groups (Definition 4.3).

## 2 Preliminaries about the anti-de Sitter space

In this section, we collect some preliminary results about $\text{AdS}^3$. We refer to [10, Section 9] where they illustrate their general theory for reductive symmetric spaces $X = G/H$ in details in the special setting where $X = \text{AdS}^3$. See also [7].

Let $Q$ be a quadratic form on $\mathbb{R}^4$ defined by $Q(x) = x_1^2 + x_2^2 - x_3^2 - x_4^2$ for $x = (x_1, x_2, x_3, x_4)$ and we set
\[
\mathbb{H}^{2,1} := \{x = (x_1, x_2, x_3, x_4) \in \mathbb{R}^4 \mid Q(x) = 1\} \cong \text{SO}_0(2, 2)/\text{SO}_0(2, 1).
\]

The tangent space $T_x(\mathbb{H}^{2,1})$ at $x \in \mathbb{H}^{2,1}$ is isomorphic to the orthogonal complement $(\mathbb{R}x)^\perp$ with respect to $Q$. Then $-Q|_{(\mathbb{R}x)^\perp}$ is a quadratic form of signature $(2, 1)$ on $T_x(\mathbb{H}^{2,1}) \cong (\mathbb{R}x)^\perp$ and thus $-Q$ induces a Lorentzian structure on $\mathbb{H}^{2,1}$ with constant sectional curvature $-1$. The 3-dimensional anti-de Sitter space
\[
\text{AdS}^3 := \mathbb{H}^{2,1}/\{\pm 1\} \cong \text{SO}_0(2, 2)/((\{\pm 1\} \times \text{SO}_0(2, 1)),
\]
inherits a Lorentzian structure through the double covering $\pi: \mathbb{H}^{2,1} \to \text{AdS}^3$. 
2.1 Some coordinates and “pseudo-balls”

In this subsection, we work with coordinates on \( \mathbb{H}^{2,1} \) and consider “pseudo-balls” in \( \text{AdS}^3 \). We identify \( \mathbb{H}^{2,1} \) with \( \text{SL}(2, \mathbb{R}) \) using the isomorphism

\[
\mathbb{H}^{2,1} \xrightarrow{\cong} \text{SL}(2, \mathbb{R}),
\]

\[
x = (x_1, x_2, x_3, x_4) \mapsto \left( \frac{x_1 + x_4}{x_2 + x_3}, \frac{x_2 + x_3}{x_1 - x_4} \right).
\]

(2.1)

For \( t \geq 0 \) and \( \theta \in \mathbb{R} \), we use the notations

\[
k(\theta) = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}, \quad a(t) = \begin{pmatrix} e^t & 0 \\ 0 & e^{-t} \end{pmatrix}.
\]

(2.2)

We embed \( \mathbb{H}^{2,1} \) into \( \mathbb{C}^2 \) by

\[
x \mapsto (z_1, z_2) = \left( x_1 + \sqrt{-1}x_2, x_3 + \sqrt{-1}x_4 \right).
\]

(2.3)

We note that \( z_1 \neq 0 \) if \( x \in \mathbb{H}^{2,1} \). Via the identification (2.1), we have

\[
(z_1, z_2) = \left( (\cosh t)e^{\sqrt{-1}(\theta_1 + \theta_2)}, (\sinh t)e^{\sqrt{-1}(\theta_1 - \theta_2)} \right),
\]

if \( x = k(\theta_1)a(t)k(\theta_2) \in \text{SL}(2, \mathbb{R}) \) (a “polar coordinate”). In particular, we have

\[
cosh 2t = x_1^2 + x_2^2 + x_3^2 + x_4^2.
\]

Next, we consider pseudo-balls on \( \text{AdS}^3 \), as a special case of Kassel–Kobayashi [10] for reductive symmetric spaces.

**Definition 2.1.** For \( x = (x_1, x_2, x_3, x_4) \in \mathbb{H}^{2,1} \), \( \|x\| \in \mathbb{R}_{\geq 0} \) is defined by

\[
cosh \|x\| := x_1^2 + x_2^2 + x_3^2 + x_4^2 \quad (= \cosh(2t)).
\]

This function is invariant under \( x \mapsto -x \), hence defines a function on \( \text{AdS}^3 \), to be also denoted by \( \|\cdot\| \) (a “pseudo-distance” from the origin). The compact set

\[
B(R) := \{ y \in \text{AdS}^3 \mid \|y\| \leq R \}
\]

is called a pseudo-ball of radius \( R \).

2.2 Square-integrable eigenfunctions of the Laplacian on the anti-de Sitter space

In this subsection, we consider square-integrable eigenfunctions of the Laplacian \( \square_{\text{AdS}^3} \) with eigenvalues \( \lambda_m = 4m(m - 1) \). We recall from [10, Section 9] the following decomposition of the open subset \( \{ Q > 0 \} \) of the flat pseudo-Riemannian manifold \( \mathbb{R}^{2,2} = (\mathbb{R}^4, Q(dx)) \):

\[
\{ Q > 0 \} \xrightarrow{\cong} \mathbb{R}_{>0} \times \mathbb{H}^{2,1},
\]

\[
x \mapsto (\sqrt{Q(x)}, x/\sqrt{Q(x)}).
\]

Let \( r = \sqrt{Q(x)} \). Then one has, see [10, p. 215],

\[
-r^2 \square_{\mathbb{R}^{2,2}} = - \left( r \frac{\partial}{\partial r} \right)^2 - 2r \frac{\partial}{\partial r} + \square_{\mathbb{H}^{2,1}}.
\]

(2.5)
Let \( m \) be a positive integer and \( k \) be a non-negative integer. In the coordinates (2.3), the homogeneous function \( z_1^{-(k+2m)} z_2^2 \) of degree \(-2m\) is harmonic with respect to \( \Box_{\mathbb{H}^2,1} \), hence its restriction to the submanifold \( \mathbb{H}^{2,1} \) is an eigenfunction of \( \Box_{\mathbb{H}^2,1} \) with eigenvalue \( \lambda_m = 4m(m-1) \) by the formula (2.5). Moreover, it is square-integrable with respect to the measure \( \sinh(2t)dt d\theta_1 dt d\theta_2 \) in the polar coordinate (2.4) induced from the Lorentzian metric on \( \mathbb{H}^{2,1} \), as in the \( k = 0 \) case [10, Section 9]. This \( L^2 \)-eigenfunction is invariant under \((z_1, z_2) \mapsto (-z_1, -z_2)\), hence defines a real analytic \( L^2 \)-eigenfunction on \( \text{AdS}^3 \) with eigenvalue \( \lambda_m \), to be denoted by \( \psi_{m,k} \). The discrete spectrum \( \text{Spec}_{d}(\Box_{\text{AdS}^3}) \) coincides with \( \{ \lambda_m \mid m \in \mathbb{N} \} \) and \( L^2_{\lambda_m}(\text{AdS}^3) \) is generated by \( \psi_{m,0} \) and its complex conjugate \( \psi_{m,0}^* \) as a representation of \( \text{SO}_0(2,2) \) (see [10, Claim 9.12]). By (2.4), we have

\[
\psi_{m,k}(\pi(x)) = e^{-2\sqrt{-1}(m\theta_1 + (m+k)\theta_2)} \tanh^k t \cosh^{-2m} t
\]

for \( x = k(\theta_1) a(t) k(\theta_2) \in \mathbb{H}^{2,1} \). We refer to \( \psi_{m,k} \) as a spherical function of type \((-m, m+k)\) in accordance with the action of \( \text{SO}(2) \times \text{SO}(2) \).

### 2.3 Convergence of generalized Poincaré series

In this subsection, we explain the fact about the discrete spectrum of locally symmetric spaces by Kassel–Kobayashi [10] in our \( \text{AdS}^3 \) setting. We use the following notation.

**Notation 2.2.**

- Let \( `G = \text{PSL}(2, \mathbb{R}) = \text{SL}(2, \mathbb{R})/\{ \pm 1 \} \) and \( G = `G \times `G \).
- Let \( `K = \text{PSO}(2) = \text{SO}(2)/\{ \pm 1 \} \) and \( K = `K \times `K \).
- Let \( E \) and \( `E \) be respectively the identity elements of \( G \) and \( `G \).

**Remark 2.3.** The double covering \( \text{SO}_0(2,2) \to G \) induces an isomorphism \( \text{AdS}^3 \cong G/\text{diag}`G \) (\( \cong `G \)). From now on, we consider only discontinuous groups \( \Gamma \) for \( \text{AdS}^3 \) which are discrete subgroups of \( G \). This is enough for our purpose.

In order to study \( \text{Spec}_{d}(\Box_{\Gamma\backslash \text{AdS}^3}) \), Kassel–Kobayashi [10] considered the convergence and non-vanishing of generalized Poincaré series

\[
\varphi^\Gamma(\Gamma x) := \sum_{\gamma \in \Gamma} \varphi(\gamma^{-1} x)
\]

for \( K \)-finite square-integrable eigenfunctions \( \varphi \) of \( \Box_{\text{AdS}^3} \). For this, they used an analytic estimate of \( \varphi \) and a geometric estimate of the number of \( \Gamma \)-orbits

\[
N_{\Gamma}(x, R) := \#\{ \gamma \in \Gamma \mid \gamma x \in B(R) \}
\]

in the pseudo-ball \( B(R) \) for \( R > 0 \). Since the \( \Gamma \)-action is properly discontinuous and \( B(R) \) is compact, we have \( N_{\Gamma}(x, R) < \infty \).

The convergence of generalized Poincaré series is proved by [10] as follows. For \( g \in G \) and a function \( f \) on \( \text{AdS}^3 \), \( \ell^g f \) is defined by \( \ell^g f(x) = f(g^{-1}x) \).

**Fact 2.4** (Kassel–Kobayashi [10]). Let \( \Gamma \subset G \) be a discontinuous group for \( \text{AdS}^3 \) satisfying the exponential growth condition

\[
\exists A, a > 0, \quad \forall x \in \text{AdS}^3, \quad \forall R > 0, \quad N_{\Gamma}(x, R) < Ae^{aR}.
\]

Then, for any \( K \)-finite eigenfunction \( \varphi \) of \( \Box_{\text{AdS}^3} \) with eigenvalue \( \lambda_m \) and any \( g \in G \), if \( m > a \), then \( (\ell^g \varphi)^\Gamma \) (see (2.7)) is continuous and square-integrable on \( \Gamma \backslash \text{AdS}^3 \) and an eigenfunction of \( \Box_{\Gamma \backslash \text{AdS}^3} \) with eigenvalue \( \lambda_m \).
Remark 2.5.

(1) Fact 2.4 does not assert the non-vanishing of the series \((\ell_g^* \varphi)\Gamma\) which is more involved. Kassel–Kobayashi [10] proved that there exists \(g \in G\) such that \((\ell_g^* \psi_{m,0})\Gamma\neq 0\) for sufficiently large \(m \in \mathbb{N}\).

(2) By [10, Lemma 4.6.4], if a discontinuous group \(\Gamma\) is sharp in the sense of [10, Definition 4.2], then \(\Gamma\) satisfies the exponential growth condition (2.9). Moreover, Kassel [8] and Guériatoud–Kassel [6] proved that finitely generated discontinuous groups for \(\text{AdS}^3\) are always sharp (see Fact 4.5 below).

(3) There exist discontinuous groups which do not satisfy the exponential growth condition (2.9). Indeed, for any increasing function \(f: \mathbb{R} \to \mathbb{R}_{>0}\) and any \(x \in \text{AdS}^3\), we constructed a discontinuous group \(\Gamma_{f,x}\) for \(\text{AdS}^3\) satisfying \(N_{\Gamma_{f,x}}(x, R) > f(R)\) for sufficiently large \(R > 0\) in [7].

The conclusion of Fact 2.4 still holds if we drop the assumption that \(\Gamma\) acts freely on \(X = \text{AdS}^3\). In this case, the quotient space \(X_\Gamma = \Gamma \backslash X\) is an orbifold. To formulate more precisely in the orbifold case, we observe that the quotient space \(X_\Gamma\) is Hausdorff, and carries a natural Radon measure (see, e.g., [2, Chapter VII, Section 2, No. 2, Proposition 4]). A continuous function \(g\) on \(X_\Gamma\) is smooth if the pull-back \(p_{\Gamma}^* g\) is a smooth function on \(X\), where \(p_{\Gamma}: X \to X_\Gamma\) is the natural quotient map. We write \(C_c^\infty(X_\Gamma)\) for the set of smooth functions on \(X_\Gamma\) with compact support. For \(g \in C_c^\infty(X_\Gamma)\), we define \(\square_{X_\Gamma} g \in C_c^\infty(X_\Gamma)\) by identifying it with the \(\Gamma\)-invariant function \(\square_X(p_{\Gamma}^* g)\). For \(\lambda \in \mathbb{C}\), we define

\[
L_\lambda^2(X_\Gamma) := \{ f \in L^2(X_\Gamma) \mid \forall g \in C_c^\infty(X_\Gamma), (f, \square_{X_\Gamma} g)_{X_\Gamma} = \lambda (f, g)_{X_\Gamma} \}.
\]

The discrete spectrum \(\text{Spec}_d(\square_{X_\Gamma})\) and its multiplicity \(N_{X_\Gamma}\) are defined similarly to the case where \(\Gamma\) acts also freely.

2.4 “Injectivity radii” of anti-de Sitter 3-manifolds

Let \(\Gamma\) be a discontinuous group for \(\text{AdS}^3\). In this subsection, we give a uniform estimate of the pseudo-distance between the origin and the second closest point of each \(\Gamma\)-orbit.

We recall that \(\Gamma(\subset \text{`G} \times \text{`G})\) acts isometrically on \(\text{AdS}^3(\cong \text{`G})\) by \((\gamma_1, \gamma_2)x = \gamma_1 x \gamma_2^{-1}\) for \((\gamma_1, \gamma_2) \in \Gamma\) and \(x \in \text{`G}\). We set

\[
\varepsilon_\Gamma := \inf_{(\gamma_1, \gamma_2) \in \Gamma \setminus \{E\}} \frac{1}{3} \|\gamma_1\| - \|\gamma_2\|.
\]

By the inequality (see, e.g., [7, Lemma 5.5])

\[
\|(g_1, g_2)x\| \geq \|g_1\| - \|g_2\| - \|x\| \quad \text{for} \quad (g_1, g_2) \in G \quad \text{and} \quad x \in \text{AdS}^3,
\]

we get:

Lemma 2.6. If \(\varepsilon_\Gamma > 0\), then \(\gamma B(\varepsilon_\Gamma) \cap B(\varepsilon_\Gamma) = \emptyset\) for all \(\gamma \in \Gamma \setminus \{E\}\).

Proposition 2.7. Let \(\Gamma\) be a discrete subgroup of \(G\) acting properly discontinuously on \(\text{AdS}^3\). Then there exists \(g \in G\) satisfying \(\varepsilon_{g^{-1}\Gamma g} > 0\).

Remark 2.8. One sees in the proof below that the set of such \(g\) is dense in \(G\).

Proposition 2.7 follows obviously from the proper discontinuity of the \(\Gamma\)-action and the following lemma:
Lemma 2.9. For any countable subset $\Gamma$ of $G$, there exists $g \in G$ such that $\|\gamma_1\| \neq \|\gamma_2\|$ for all $\gamma = (\gamma_1, \gamma_2) \in g^{-1}g \setminus \{E\}$.

Proof of Lemma 2.9. For $\gamma \in \Gamma$, the map $f_\gamma : G \to G$ defined by $g \mapsto g^{-1}\gamma g$ is real analytic. For the analytic subset $F = \{(g_1, g_2) \in G \mid \|g_1\| = \|g_2\|\}$ of $G$, we claim that the set $f_\gamma^{-1}(F)$ is a proper subset of $G$ if $\gamma \neq E$. For this, we may assume $\gamma \neq E$ without loss of generality. Then there exists $g_1 \in G$ satisfying $\|g_1^{-1}\gamma g_1\| \neq \|\gamma_1\|$ as one can find $g_1$ depending on the three cases where $\gamma_1$ is hyperbolic, parabolic, or elliptic. Hence $(g_1, \gamma) \notin f_\gamma^{-1}(F)$ if $\|\gamma_1\| = \|\gamma_2\|$, and $E \notin f_\gamma^{-1}(F)$ if not. Thus $f_\gamma^{-1}(F)$ is a proper subset of $G$.

Therefore the analytic set $f_\gamma^{-1}(F)$ has no interior point, and thus so does the countable union $\bigcup_{\gamma \in \Gamma \setminus \{E\}} f_\gamma^{-1}(F)$ by the Baire category theorem (see, e.g., [22, Theorem 2.2]). Hence there exists an element $g$ of $G \setminus \bigcup_{\gamma \in \Gamma \setminus \{E\}} f_\gamma^{-1}(F)$ and we have $\|\gamma_1\| \neq \|\gamma_2\|$ for all $\gamma = (\gamma_1, \gamma_2) \in g^{-1}g \setminus \{E\}$. 

3 Proof of Theorem 1.1

In this section, we prove Theorem 1.1.

More generally, without finitely generated assumption of $\Gamma$, we study linear independence of the generalized Poincaré series of the spherical functions $\psi_{m,k}$ of type $(-m, m + k)$ defined in Section 2.2. By choosing $k = 3^j$ ($j = 0, 1, 2, \ldots$), we prove:

Theorem 3.1. If $\Gamma$ is a discontinuous group for AdS$^3$ satisfying the exponential growth condition (2.9), then

$$\lim_{m \to \infty} N_{\Gamma \setminus \text{AdS}^3}(\lambda_m) = \infty.$$

Theorem 1.1 is a direct consequence of Theorem 3.1 by Remark 2.5(2).

Proposition 3.2. Let $\Gamma$ be a discrete subgroup of $G$ acting properly discontinuously on AdS$^3$ and satisfying the exponential growth condition (2.9). If $\varepsilon_\Gamma > 0$, then there exists a real number $m_\Gamma(k)$ (given explicitly by (3.1)) for $k \in \mathbb{N}$ such that $\{(\text{Re}(\psi_{m,3^j}))^k\}_{j=0}^{k \rightarrow \infty} \subset L^2_{\lambda_m}(\Gamma \setminus \text{AdS}^3)$ are linearly independent for all integers $m > m_\Gamma(k)$.

Postponing the proof of Proposition 3.2 until the end of this section, we prove Theorem 3.1.

Proof of Theorem 3.1. We have an obvious equality of the multiplicity of $L^2$-eigenvalues, $N_{\Gamma \setminus \text{AdS}^3} = N_{(g^{-1}g) \setminus \text{AdS}^3}$ for any $g \in G$ through the natural isomorphism $\Gamma \setminus \text{AdS}^3 \cong (g^{-1}g) \setminus \text{AdS}^3$ as Lorentzian manifolds. By replacing $\Gamma$ with $g^{-1}g$ if necessary, we may and do assume $\varepsilon_\Gamma > 0$ by Proposition 2.7. Then Proposition 3.2 implies that $L^2_{\lambda_m}(\Gamma \setminus \text{AdS}^3)$ contains at least $k$ linearly independent elements if $m > m_\Gamma(k)$ for any fixed $k \in \mathbb{N}$, which means $\dim L^2_{\lambda_m}(\Gamma \setminus \text{AdS}^3) \geq k$. Hence Theorem 3.1 follows.

Kassel–Kobayashi [10] proved the non-vanishing of the generalized Poincaré series $(\psi_{m,0})^\Gamma$ for sufficiently large $m \in \mathbb{N}$ by showing that the first term in the generalized Poincaré series is larger at the origin than the sum of the remaining terms. For this, they utilized the fact that $\psi_{m,0}(E) = 1$. Our strategy for the proof of Proposition 3.2 is along the same line, however, there are some technical difficulties since $\psi_{m,k}$ for $k \geq 1$ vanishes at the origin. We then make use of an observation that $\psi_{m,k}$ decays more slowly at the origin than at infinity, to be precise, by the following formula, see (2.6):

$$|\psi_{m,k}(x)| = \cosh^{-2m}(\|x\|/2) \tanh^{k}(\|x\|/2).$$
Actually, we use an analytic lemma (Lemma 3.3) to prove that the first term in the generalized Poincaré series \((\psi_{m,k})^\Gamma\) is larger at points sufficiently close to the origin than the sum of the remaining terms if \(m \gg 0\). Moreover, we use a combinatorial lemma (Lemma 3.4) to find points at which leading terms of \((\Re(\psi_{m,k}))^\Gamma\) do not cancel each other for any linear combination.

For \(C, a, \varepsilon > 0\) and \(s \in \mathbb{N}\), we set

\[
m(C, a, \varepsilon, s) := \frac{(\log 2)s + 2a\varepsilon + \log \left(1 + 2^sCe^{6a\varepsilon}\right)}{\log \cosh \varepsilon}
\]

and

\[
\tilde{m}(C, a, \delta, s) := \inf_{0<\varepsilon<\delta} m(C, a, \varepsilon, s).
\]

Note that \(\tilde{m}(C, a, \delta, s) = O(\delta^{-2})\) as \(\delta \to 0\) and \(= O(1)\) as \(\delta \to \infty\).

**Lemma 3.3.** For any integer \(m > m(C, a, \varepsilon, s)\) and any one-variable polynomial \(f\) of degree \(\leq s\) with non-negative coefficients,

\[
C \sum_{n=1}^{\infty} e^{4a(n+1)\varepsilon}(\cosh 2n\varepsilon)^{-m} f(\tanh 2(n+1)\varepsilon) < (\cosh \varepsilon)^{-m} f(\tanh \varepsilon).
\]

**Proof.** We may assume that \(f(x) = x^j\) for \(j = 0, 1, \ldots, s\). Since

\[
1 \leq \frac{\tanh nx}{\tanh x} \leq n, \quad (\cosh x)^n \leq \cosh nx
\]

for \(x \in \mathbb{R}\), we have

\[
\frac{(\text{LHS})}{(\text{RHS})} = C \sum_{n=1}^{\infty} e^{4a(n+1)\varepsilon}(\cosh 2n\varepsilon)^{-m} \left(\frac{\tanh 2(n+1)\varepsilon}{\tanh \varepsilon}\right)^j
\leq Ce^{6a\varepsilon} \sum_{n=1}^{\infty} (e^{2a\varepsilon}(\cosh \varepsilon)^{-m})^{2n-1}(2(n+1))^s.
\]

We set \(d := e^{2a\varepsilon}(\cosh \varepsilon)^{-m}\). Then \(d < 1\) by \(m > m(C, a, \varepsilon, s)\). Since \(n+1 \leq 2^n\) for all \(n \in \mathbb{N}\), we have

\[
\frac{(\text{LHS})}{(\text{RHS})} \leq 2^sCe^{6a\varepsilon} \sum_{n=1}^{\infty} (2^s d)^n = 2^sCe^{6a\varepsilon} \frac{2^s d}{1 - 2^s d'}.
\]

Again by \(m > m(C, a, \varepsilon, s)\), we have \(2^s d < (1 + 2^sCe^{6a\varepsilon})^{-1}\). Therefore we obtain

\[
\frac{(\text{LHS})}{(\text{RHS})} < 1.
\]

**Lemma 3.4.** For any \(a = (a_0, \ldots, a_{k-1}) \in \{\pm 1\}^k\) and any odd integer \(N \geq 3\), we have

\[
a_j \cos (N^j \theta_{a,N}) > 0 \quad \text{for} \quad j = 0, 1, \ldots, k - 1.
\]

Let \(\chi: \{\pm 1\} \to \{0, 1\}\) be the map defined by \(\chi(1) = 0\) and \(\chi(-1) = 1\). For \(a = (a_j)_{j=0}^{k-1} \in \{\pm 1\}^k\) and an odd integer \(N \geq 3\), we set

\[
\theta_{a,N} := \pi \sum_{i=0}^{k-1} (\chi(a_i) - \chi(a_{i-1}))N^{-i}.
\]

Here we use the convention \(a_{-1} = 1\).
**Proof.** Since $N^{k-1} \theta_{a,N} \equiv \pi \chi(a_{k-1}) \pmod{2\pi}$, we have $\cos(N^{k-1} \theta_{a,N}) = a_{k-1}$. It is easy to check that $|N^j \theta_{a,N} - N^j \theta(a_{0}, \ldots, a_j), N| < \pi/2$ for $j = 0, 1, \ldots, k - 1$, hence the signature of $\cos(N^j \theta_{a,N})$ is equal to that of $\cos(N^j \theta(a_{0}, \ldots, a_j), N) = a_j$. \hfill \quad \blacksquare

**Remark 3.5.** We have used the geometric progression $(N^j)_{j=0}^{k-1}$ in Lemma 3.4. On the other hand, an analogous statement does not hold if we use arithmetic progressions. For example, there does not exist $\theta \in \mathbb{R}$ satisfying $a_j \cos m_j \theta > 0$ for all $j = 0, 1, 2, 3, 4$ if we choose $(a_j)_{j=0}^4 = (1, 1, 1, -1, 1)$ and an arithmetic progression $(m_j)_{j=0}^4$.

For a discontinuous group $\Gamma$ and $k \in \mathbb{N}$, one can take $m_\Gamma(k)$ in Proposition 3.1 by

$$m_\Gamma(k) = \inf_{(A, a) \in C_{\text{exp}}(\Gamma)} \max \{ \bar{m}(3^{k-1}A, a, \varepsilon/4, 3^{k-1})/2, a \},$$

(3.1)

where $C_{\text{exp}}(\Gamma) := \{ (A, a) \in \mathbb{R}^2 \mid \forall x \in \text{AdS}^3, \forall R > 0, N_\Gamma(x, R) < Ae^{\theta R} \}$. Here, we adopt the convention that $\inf_{\mathcal{A}} f = \infty$ for a real-valued function $f$. In particular, $m_\Gamma(k) = \infty$ when $C_{\text{exp}}(\Gamma) = \emptyset$ or $\varepsilon_\Gamma = 0$.

**Proof of Proposition 3.2.** By the exponential growth condition (2.9), $C_{\text{exp}}(\Gamma) \neq \emptyset$ and thus $m_\Gamma(k) < \infty$. We take an integer $m > m_\Gamma(k)$. Then there exist $\varepsilon$ with $0 < \varepsilon < \varepsilon_\Gamma/4$ and $(A, a) \in C_{\text{exp}}(\Gamma)$ satisfying the inequality $m > \max \{ m(3^{k-1}A, a, \varepsilon, 3^{k-1})/2, a \}$.

To see $\mathbb{C}$-linear independence of the real-valued functions $(\text{Re}(\psi_{m,3j}))_{j=0}^{k-1}$, it is enough to prove the non-vanishing of the real part $\text{Re}(\psi_{m,b}^\Gamma) = (\text{Re}(\psi_{m,b}))^\Gamma$ of the generalized Poincaré series of a linear combination

$$\psi_{m,b} := \sum_{j=0}^{k-1} b_j \psi_{m,3j}$$

for any $b = (b_0, b_1, \ldots, b_{k-1}) \in \mathbb{R}^k \setminus \{0\}$. By Lemma 2.6, for $x \in B(4\varepsilon)$, we have

$$\psi_{m,b}^\Gamma(\Gamma x) = \psi_{m,b}(x) + \sum_{\gamma \in \Gamma, \|\gamma^{-1}x\| > 4\varepsilon} \psi_{m,b}(\gamma^{-1}x).$$

(3.2)

By (2.6), for any $y \in \text{AdS}^3$, we get

$$|\psi_{m,b}(y)| \leq \left( \cosh \frac{\|y\|}{2} \right)^{-2m} \sum_{j=0}^{k-1} |b_j| \left( \tanh \frac{\|y\|}{2} \right)^{3j}.$$  

We define $a = (a_j)_{j=0}^{k-1}$ by $a_j = 1$ for $b_j \geq 0$ and $a_j = -1$ for $b_j < 0$, and set

$$f_b(u) := \sum_{j=0}^{k-1} b_j \cos(3^j \theta_{a,3}) u^{3j}.$$  

We note that all the coefficients of $f_b$ are non-negative by Lemma 3.4. Moreover, we get $|\cos(3^j \theta_{a,3})|^{-1} \leq 3^{k-1}$ for all $j = 0, 1, \ldots, k - 1$ by using the inequality $\sin(\pi x/2) \geq x$ for $0 \leq x \leq 1$. Thus

$$|\psi_{m,b}(y)| \leq 3^{k-1} \left( \cosh \frac{\|y\|}{2} \right)^{-2m} f_b \left( \tanh \frac{\|y\|}{2} \right),$$
and, for any \( x \in B(4\varepsilon) \), we have
\[
\left| \sum_{\gamma \in \Gamma} \frac{\text{Re} \left( \psi_{m,b}(\gamma^{-1}x) \right)}{\| \gamma^{-1}x \| > 4\varepsilon} \right| \leq \sum_{n=1}^{\infty} \sum_{\gamma \in \Gamma} \frac{|\psi_{m,b}(\gamma^{-1}x)|}{4^m < \| \gamma^{-1}x \| \leq 4\varepsilon(n+1)}
\]
\[
\leq 3^{k-1} \sum_{n=1}^{\infty} N_{\Gamma}(x, 4\varepsilon(n+1)) \left( \cosh 2\varepsilon n \right)^{-2m} f_b \left( \tanh 2\varepsilon(n+1) \right)
\]
\[
\leq 3^{k-1} A \sum_{n=1}^{\infty} e^{4\alpha \varepsilon(n+1)} \left( \cosh 2\varepsilon n \right)^{-2m} f_b \left( \tanh 2\varepsilon(n+1) \right)
\]
\[
< (\cosh \varepsilon)^{-2m} f_b (\tanh \varepsilon) \tag{3.3}
\]

The third and fourth inequalities respectively follow from the exponential growth condition (2.9) and Lemma 3.3. On the other hand, we set
\[
x_{a,\varepsilon} := k \left( \frac{\theta_{a,3}}{2} \right) a(\varepsilon) k \left( \frac{\theta_{a,3}}{2} \right)^{-1} \in B(4\varepsilon).
\]

Then it follows from (2.6) that
\[
\text{Re} \psi_{m,b}(x_{a,\varepsilon}) = (\cosh \varepsilon)^{-2m} f_b (\tanh \varepsilon) \tag{3.4}
\]

By (3.2), (3.3), and (3.4), we obtain \((\text{Re}(\psi_{m,b})^\Gamma) x_{a,\varepsilon} \neq 0\). Hence we complete the proof by the continuity of \( \psi_{m,b}^\Gamma \) (Fact 2.4).

4 Proof of Theorem 1.4

In this section, we prove Theorem 1.4 by applying Proposition 3.2. We work in the following setting. We allow \( \Delta \) to have torsion.

Setting 4.1.

- \( \Delta \) is a discrete subgroup of \( \hat{G} = \text{PSL}(2,\mathbb{R}) \).
- \( j, \rho: \Delta \to \hat{G} \) are two group homomorphisms with \( j \) injective and discrete.
- \( \Delta^{j,\rho} \) is a discrete subgroup of \( G = \hat{G} \times \hat{G} \) given by \( \{(j(\gamma), \rho(\gamma)) \mid \gamma \in \Delta\} \).

We use the following structural results of discontinuous groups for the proof of Theorem 1.4.

Fact 4.2 ([10, Lemma 9.2]). Let \( \Gamma \) be a finitely generated discrete subgroup of \( G \) acting properly discontinuously on \( \text{AdS}^3 \). Then \( \Gamma \) is of either type (i) or (ii) as follows:

- type (i) \( \Gamma \) is of the form \( \Delta^{j,\rho} \) up to switching the two factors,
- type (ii) \( \Gamma \) is contained in a conjugate of \( \hat{G} \times \hat{G} \) or \( \hat{K} \times \hat{K} \).

A non-elementary discrete subgroup \( \Gamma \) of a connected linear real reductive Lie group \( L \) of real rank 1 is called convex cocompact if \( \Gamma \) acts cocompactly on the convex hull of its limit set in the Riemannian symmetric space associated to \( L \). For example, cocompact lattices and Schottky groups are convex cocompact. More generally, one may think of the notion of convex cocompactness of discontinuous groups for \( \text{AdS}^3 \):

Definition 4.3 ([10, Definition 9.1]). A discontinuous group \( \Gamma \) for \( \text{AdS}^3 \) is called convex cocompact if \( \Gamma \) is of the form \( \Delta^{j,\rho} \) up to finite index and switching the two factors, where \( \Delta \) is torsion-free and \( j(\Delta) \) is convex cocompact in \( \hat{G} \).

We note that a discontinuous group \( \Delta^{j,\rho} \) acts cocompactly on \( \text{AdS}^3 \) if and only if \( j(\Delta) \) is compact in \( \hat{G} \) because \( \Delta^{j,\rho} \) is isomorphic to \( j(\Delta) \) as abstract groups. By Fact 4.2, discontinuous groups acting cocompactly on \( \text{AdS}^3 \) are convex cocompact.
4.1 Proof of Theorem 1.4 for \( \Gamma \) of type (i)

In this subsection, we prove Theorem 1.4 for \( \Gamma \) of type (i). For this, we use the constant \( C_{\text{Lip}}(j, \rho) \) introduced by Kassel [8] and Guéritaud–Kassel [6], which quantifies the properness of the action of \( \Delta^{j, \rho} \) on \( \text{AdS}^3 \).

**Definition 4.4.** Let \( d_{\mathbb{H}^2} \) be the hyperbolic distance of the 2-dimensional hyperbolic space \( \mathbb{H}^2(\cong \cdot G/\cdot K) \). In Setting 4.1, we denote by \( C_{\text{Lip}}(j, \rho) \) the infimum of Lipschitz constants

\[
\text{Lip}(f) = \sup_{y \neq y'} \frac{d_{\mathbb{H}^2}(f(y), f(y'))}{d_{\mathbb{H}^2}(y, y')}
\]

of maps \( f : \mathbb{H}^2 \to \mathbb{H}^2 \) that are \((j, \rho)\)-equivariant.

The map \((j, \rho) \mapsto C_{\text{Lip}}(j, \rho)\) is continuous over the set of \((j, \rho) \in \text{Hom}(\Delta, \cdot G) \) such that \( j \) is injective and \( j(\Delta) \) is convex cocompact in \( \cdot G \) [6, Proposition 1.5].

**Fact 4.5 ([6, 8]).** Assume that \( \Delta \) is finitely generated. Then the action of \( \Delta^{j, \rho} \) on \( \text{AdS}^3 \) is properly discontinuous if and only if \( \min \{C_{\text{Lip}}(j, \rho), C_{\text{Lip}}(\rho, j)\} < 1 \).

**Remark 4.6.** In the setting of Fact 4.5, if \( C_{\text{Lip}}(\rho, j) < 1 \), then \( \rho \) is injective and discrete. Moreover, if \( j(\Delta) \) is convex cocompact, then so is \( \rho(\Delta) \).

Therefore, Theorem 1.4 for \( \Gamma \) of type (i) reduces to the following:

**Theorem 4.7.** In Setting 4.1, we assume that \( \Delta \) is finitely generated and that \( C_{\text{Lip}}(j, \rho) < 1 \). Then there exists a constant \( \mu_1 > 0 \) independent of \( j, \rho \) and \( \Delta \) such that for any \( m, k \in \mathbb{N} \) with \( m > 3^k \mu_1 (1 - C_{\text{Lip}}(j, \rho))^{-2} \),

\[
N_{\Delta^{j, \rho}}(\cdot \text{AdS}^3)(\lambda_m) \geq k.
\]

For the proof of Theorem 4.7, we need two results from Kassel–Kobayashi [10] applied to our setting \( G = \cdot G \times \cdot G \). If a discontinuous group \( \Gamma \) satisfies the assumption of Fact 4.8 below, then it is ((1 − \( \alpha \))/2, 0)-sharp in the sense of [10, Definition 4.2]. Hence we get the following by applying [10, Lemma 4.6.4]:

**Fact 4.8 ([10]).** Let \( \Gamma \subset G \) be a discontinuous group for \( \text{AdS}^3 \). We assume that there exists \( 0 \leq \alpha < 1 \) such that \( \|\gamma_2\| \leq \alpha \|\gamma_1\| \) or \( \|\gamma_1\| \leq \alpha \|\gamma_2\| \) for any \((\gamma_1, \gamma_2) \in \Gamma \). Then there exists \( c > 0 \) independent of \( \alpha \) and \( \Gamma \) such that for any \( x \in \text{AdS}^3 \) and any \( R > 0 \),

\[
N_{\Gamma}(x, R) \leq \#(\Gamma \cap K)e^{8R(1-\alpha)^{-1}}.
\]

The following theorem traces back to the Kazhdan–Margulis theorem for discrete subgroups of semisimple groups.

**Fact 4.9 ([10, Proposition 8.14]).** There exists a constant \( r > 0 \) satisfying the following property: for any discrete subgroup \( \cdot \Gamma \) of \( \cdot G \), there exists \( \cdot g \in \cdot G \) such that \( \|\gamma\| \geq r \) for all \( \gamma \in \cdot g^{-1} \cdot \Gamma \cdot g \setminus \{\cdot E\} \).

In the following, we use the upper half plane model \( \{z = x + \sqrt{-1}y \in \mathbb{C} \mid \text{Im } z > 0\} \) equipped with the metric tensor \( ds^2 = (dx^2 + dy^2)/y^2 \) for the hyperbolic space \( \mathbb{H}^2 \). Then \( \|\gamma\| \) is equal to the hyperbolic distance \( d_{\mathbb{H}^2}(\cdot g\sqrt{-1}, \cdot \Gamma \cdot g) \) for \( \cdot g \in \text{AdS}^3(\cong \cdot G \) (see, e.g., [6, equation (A.1)]).
Proof of Theorem 4.7. The idea of the proof is similar to [10, Theorem 9.9], however, we give a proof for the sake of completeness. By Fact 4.9, replacing \( j \) by some conjugate under \( G \), we may assume \( |j(\gamma)| \geq r \) for any \( \gamma \in \Delta \setminus \{ E \} \). In particular, \( \Gamma \cap K = \{ E \} \) for such \( j \) and for any \( \rho \). We fix \( \delta > 0 \) such that
\[
\alpha := C_{\text{Lip}}(j, \rho) + \delta < 1.
\]
Then, replacing \( \rho \) by some conjugate under \( G \), we may assume
\[
\|\rho(\gamma)\| \leq \alpha \|j(\gamma)\| \quad \text{for any } \gamma \in \Delta.
\] (4.1)
Indeed, by Definition 4.4, there exists a \((j, \rho)\)-equivariant map \( f_\delta : \mathbb{H}^2 \to \mathbb{H}^2 \) satisfying \( \text{Lip}(f_\delta) < \alpha \). We take \( g_\delta \in G \) such that \( g_\delta \sqrt{-1} = f_\delta(\sqrt{-1}) \). Then, for any \( \gamma \in \Delta \), we have
\[
\|g_\delta^{-1}(\gamma)g_\delta\| = d_{\mathbb{H}^2}(f_\delta(\sqrt{-1}), \rho(\gamma)\delta(\sqrt{-1})) < \alpha d_{\mathbb{H}^2}(\sqrt{-1}, j(\gamma)\sqrt{-1}) = \alpha \|j(\gamma)\|.
\]
Hence (4.1) holds by replacing \( \rho \) with \( g_\delta^{-1}\rho(\cdot)g_\delta \), and therefore we get
\[
N_\Gamma(x, R) \leq c e^{8R(1 - (C_{\text{Lip}}(j, \rho) + \delta))^{-1}}
\]
by Fact 4.8. Then the constant \( \varepsilon_\Gamma \) in (2.10) has the following lower bound:
\[
3\varepsilon_\Gamma = \inf_{\gamma \in \Delta \setminus \{ E \}} |j(\gamma)| - \inf_{\gamma \in \Delta \setminus \{ E \}} \|\rho(\gamma)\| \geq \inf_{\gamma \in \Delta \setminus \{ E \}} (1 - \alpha) \|j(\gamma)\| \geq r(1 - \alpha).
\]
Note that \( \log \cosh t = O(t^2) \) as \( t \to 0 \). By the explicit description (3.1) of \( m_\Gamma(k) \), Theorem 4.7 follows from Proposition 3.2.

4.2 Proof of Theorem 1.4 for \( \Gamma \) of type (ii)

In this subsection, we prove Theorem 1.4 for the case where \( \Gamma \) is standard. For this, we use the following fact by Kobayashi [17] and Kassel [9] applied to our AdS\(^3\) setting, which gives the stability for properness under any small deformation of standard convex cocompact discontinuous groups.

Fact 4.10 ([9, Theorem 1.4]). Let \( \Gamma \) be a convex cocompact discrete subgroup of \( G \times K \). Then for any \( \alpha, \beta > 0 \), there exists a neighborhood \( W \subset \text{Hom}(\Gamma, G) \) of the natural inclusion \( \Gamma \subset G \) such that for any \( \varphi \in W \),
\[
|\varphi(\mu(\gamma)) - \mu(\gamma)| \leq \begin{cases} 
\alpha |\mu(\gamma)| & \text{if } \gamma \in \Gamma \setminus K, \\
\beta & \text{if } \gamma \in \Gamma \cap K,
\end{cases}
\]
where \( \mu(g_1, g_2) := (\|g_1\|, \|g_2\|) \in \mathbb{R}^2 \) for \( (g_1, g_2) \in G, \| \cdot \| \) is given in Definition 2.1, and \( |(x_1, x_2)| := \sqrt{x_1^2 + x_2^2} \) for \( (x_1, x_2) \in \mathbb{R}^2 \).

We introduce the following terminology for the estimate of the discrete spectrum since a discontinuous group \( \Gamma \) is not necessarily torsion-free. Let \( \text{pr}_j : G = G \times G \to G \) be the \( j \)-th projection \( (j = 1, 2) \). In the following definition, we assume that \( \text{pr}_2(\Gamma) \) is bounded. Then the group \( \Gamma_1 := \text{ker}(\text{pr}_1 | \Gamma) \) is cyclic since \( \Gamma_1 \) is a discrete subgroup of a conjugate of the product group \( \{ E \} \times K (\cong \mathbb{R}/\mathbb{Z}) \).

Definition 4.11. A discrete subgroup \( \Gamma \) of \( G \) is said to be standard of class \( n \) if \( \text{pr}_2(\Gamma) \) is bounded and the cyclic group \( \Gamma_1 = \text{ker}(\text{pr}_1 | \Gamma) \) is of order \( n \).
Remark 4.12.

(1) If $\Gamma$ is torsion-free, then it is of class 1.

(2) If $\text{pr}_2(\Gamma)$ is bounded for a discrete subgroup $\Gamma$ of $G$, then the group $\text{pr}_1(\Gamma)$ is discrete in $\check{G}$. Moreover, if $\Gamma$ is of class 1, then it is of the form $\Delta^j\rho$ such that $\Delta = \text{pr}_1(\Gamma)$ and $C_{\text{Lip}}(j, \rho) = 0$.

Let $r > 0$ be the constant in Fact 4.9. For an integer $n \geq 2$, we define a positive number $\eta_n$ by

$$
cosh \eta_n := 1 + 2\left( \sinh \frac{r}{4} \sin \frac{\pi}{n} \right)^2.
$$

We get the following by easy computations:

**Lemma 4.13.** By an abuse of notation, we regard $k(\theta), a(t)$ in (2.2) as elements of $\check{G} = \text{PSL}(2, \mathbb{R})$. Then

$$
\left\| \text{a}(\frac{r}{8})^{-1} k\left(\frac{j \pi}{n}\right) \text{a}(\frac{r}{8}) \right\| \geq \eta_n \quad \text{for} \quad j = 1, \ldots, n - 1.
$$

We give a uniform estimate of $\varepsilon_{\Gamma}$ in (2.10) and $N_{\Gamma}(x, R)$ in (2.8) for standard discrete subgroups $\Gamma$ of class $n$ after taking a conjugation of $\Gamma$.

**Lemma 4.14.** Let $\Gamma$ be a standard discrete subgroup of class $n \geq 2$. There exists $g \in G$ such that $\varepsilon_{g^{-1}\Gamma g} \geq \min\{\eta_n/3, r/6\}$ and $N_{g^{-1}\Gamma g}(x, R) < \varepsilon e^{16R}$ for any $x \in \text{AdS}^3$ and any $R > 0$.

**Proof.** Let $\Gamma_1 = \ker(\text{pr}_1|_\Gamma)$ as in Definition 4.11. Since $\Gamma$ is of class $n$, the group $\text{pr}_2(\Gamma_1)$ is generated by $k(\pi/n) \in \check{G} = \text{PSL}(2, \mathbb{R})$. We take $\check{g} \in \check{G}$ in Fact 4.9 applied to $\check{\Gamma} = \text{pr}_1(\Gamma)$ and set $g := (\check{g}, a(r/8)) \in G$. Replacing $\Gamma$ by $g^{-1}\Gamma g$, we get $\|\gamma_1\| \geq r$ for $(\gamma_1, \gamma_2) \in \Gamma \setminus \Gamma_1$ by Fact 4.9 and $\|\gamma_2\| \geq \eta_n$ for $(\gamma_1, \gamma_2) \in \Gamma \setminus \{E\}$ by Lemma 4.13. Moreover, if $(\gamma_1, \gamma_2) \in \Gamma$, then $\|\gamma_2\| = \|a(r/8)^{-1}ka(r/8)\|$ for some $k \in K$, hence $\|\gamma_2\| \leq r/2$ because $\|g_1g_2\| \leq \|g_1\| + \|g_2\|$ for $g_1, g_2 \in \check{G}$ and since $\|a(t)\| = 2t$ for $t \geq 0$ and $\|k\| = 0$ for $k \in \check{K}$. To summarize,

$$
\begin{cases}
\|\gamma_2\| \leq \frac{r}{2} \leq \frac{\|\gamma_2\|}{2} & \text{if} \quad (\gamma_1, \gamma_2) \in \Gamma \setminus \Gamma_1, \\
\|\gamma_2\| \geq \eta_n & \text{if} \quad (\gamma_1, \gamma_2) \in \Gamma \setminus \{E\}. 
\end{cases}
$$

Then $\varepsilon_{\Gamma} \geq \min\{\eta_n/3, r/6\}$ and $\Gamma \cap K = \{E\}$. Moreover, $\|\gamma_1\| \leq \|\gamma_2\|/2$ or $\|\gamma_2\| \leq \|\gamma_1\|/2$ for any $(\gamma_1, \gamma_2) \in \Gamma$ and thus $N_{\Gamma}(x, R) < \varepsilon e^{16R}$ for any $x \in \text{AdS}^3$ and any $R > 0$ by Fact 4.8. \qed

**Theorem 4.15.** There exists a constant $\mu_n > 0$ depending only on $n$ such that for any convex cocompact standard discrete subgroup $\Gamma$ of class $n$ and any $m, k \in \mathbb{N}$ with $m > 3^k \mu_n$,

$$
\tilde{N}_{\Gamma, \text{AdS}^3}(\lambda_m) \geq k.
$$

**Proof.** If $n = 1$, then this follows from Theorem 4.7 since convex cocompact discontinuous groups are finitely generated, hence we assume that $n \geq 2$. In this case, we shall prove that $\Gamma$ and its small deformation are standard of class $n$. When $n \geq 2$, the group $\Gamma_1 = \ker(\text{pr}_1|_\Gamma)$ is a cyclic group of order $n$. By Fact 4.9, replacing $\Gamma$ by some conjugate under $\check{G} \times \{E\}$, we may and do assume $\|\gamma_1\| \geq r$ for any $(\gamma_1, \gamma_2) \in \Gamma \setminus \Gamma_1$. By Fact 4.10, there exists a neighborhood $W$ of the natural inclusion $\Gamma \subset G$ such that for any $\varphi \in W$, the restriction of $\varphi$ to the finite subgroup $\Gamma_1$ is injective and the inequalities

$$
\begin{cases}
\|\varphi_1(\gamma)\| \geq \frac{1}{2}r, \quad \|\varphi_2(\gamma)\| \leq \frac{1}{2}\|\varphi_1(\gamma)\| & \text{if} \quad \gamma \in \Gamma \setminus \Gamma_1, \\
|\mu(\varphi(\gamma))| < \frac{1}{2}r & \text{if} \quad \gamma \in \Gamma_1
\end{cases}
$$

hold where $\varphi_i = \text{pr}_i \circ \varphi$ for $i = 1, 2$. Then $\varphi$ is injective and discrete.
We claim $\varphi_1(\Gamma_1)$ is trivial. Indeed, if there exists $\gamma \in \Gamma_1 \setminus \{E\}$ such that $\varphi_1(\gamma) \neq \gamma E$, then the normalizer of $\varphi(\Gamma_1)$ in $G$ is contained in $K_1 \times G$, where $K_1$ is the maximal compact subgroup of $\Gamma_1$. Hence $\varphi(\Gamma) \subset K_1 \times G$. By the inequalities (4.2), $\varphi(\Gamma)$ is finite, hence $\Gamma$ is also finite. This contradicts the assumption that $\Gamma$ is non-elementary. Thus $\varphi_1(\Gamma_1)$ is trivial and $\varphi_2(\Gamma_1)$ is non-trivial. Hence the normalizer of $\varphi(\Gamma_1)$ in $G$ is contained in $K_1 \times G$, where $K_2$ is the maximal compact subgroup of $G$ containing $\varphi_2(\Gamma_1)$. Therefore $\text{pr}_2(\varphi(\Gamma))$ is bounded. Moreover $\varphi(\Gamma_1) = \varphi(\Gamma_1)$ by the inequalities (4.2), hence the discrete subgroup $\varphi(\Gamma)$ is standard of class $n$. By the explicit description (3.1) of $m(\Gamma)$ and Lemma 4.14, Theorem 4.15 follows from Proposition 3.2.

Remark 4.16. In the above proof, we have shown that a convex cocompact standard discrete subgroup $\Gamma$ of class $n \geq 2$ and its small deformation are standard of class $n$. Therefore we obtain a stronger result that

$$\tilde{N}_{\Gamma \setminus \text{AdS}^3}(\lambda_m) = \infty$$

for any convex cocompact standard discrete subgroup $\Gamma$ of class $n \geq 2$ and any integer $m > 3\mu_n$ if the following statement holds: $N_{\Gamma \setminus \text{AdS}^3}(\lambda_m) = \infty$ for any standard discrete subgroup $\Gamma$ and any $m \in \mathbb{N}$ such that $N_{\Gamma \setminus \text{AdS}^3}(\lambda_m) \geq 1$. The latter statement is discussed in [13] by using discretely decomposable blanching laws of unitary representations (cf. [11]).

Thus the proof of Theorem 1.4 is completed.

Acknowledgements

The author would like to express his sincere gratitude to Professor Toshiyuki Kobayashi whose suggestions led him to study the multiplicities of $L^2$-eigenvalues for anti-de Sitter manifolds. He also would like to show his appreciation to Dr. Hiroyoshi Tamori whose comments led him to an explicit description of $m(C,a,\varepsilon,s)$ in Lemma 3.3. Thanks are also due to the anonymous referees for their helpful comments to improve the paper. This work was supported by JSPS KAKENHI Grant Number 18J20157 and the Program for Leading Graduate Schools, MEXT, Japan.

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