Dynamical systems/Probability theory

Asymptotic description of stochastic neural networks. II. Characterization of the limit law

Description asymptotique de réseaux de neurones stochastiques. II. Caractérisation de la loi limite

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A B S T R A C T

We continue the development, started in [8], of the asymptotic description of certain stochastic neural networks. We use the Large Deviation Principle (LDP) and the good rate function $H$ announced there to prove that $H$ has a unique minimum $\mu_e$, a stationary measure on the set of trajectories $T^Z$. We characterize this measure by its two marginals, at time 0, and from time 1 to T. The second marginal is a stationary Gaussian measure. With an eye on applications, we show that its mean and covariance operator can be inductively computed. Finally, we use the LDP to establish various convergence results, averaged, and quenched.

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R É S U M É

Nous prolongeons le développement, commencé en [8], de la description asymptotique de certains réseaux de neurones stochastiques. Nous utilisons le principe de grandes déviations (PGD) et la bonne fonction de taux $H$ que nous y annoncions pour démontrer l’existence d’un unique minimum, $\mu_e$, de $H$, une mesure stationnaire sur l’ensemble $T^Z$ des trajectoires. Nous caractérisons cette mesure par ses deux marginales, à l’instant 0, et du temps 1 au temps T. La seconde marginales est une mesure gaussienne stationnaire. Avec un oeil sur les applications, nous montrons comment calculer de manière inductive sa moyenne et son opérateur de covariance. Nous montrons aussi comment utiliser le PGD pour établir des résultats de convergence en moyenne et presque sûrement.

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Version française abrégée

Après avoir rappelé dans la section 2 les notations et le modèle de réseaux de neurones utilisés dans [8], nous montrons dans la proposition 3.1 et le théorème 3.2 que la bonne fonction de taux $H$ du PGD annoncé dans cette publication admet
un minimum unique. Le théorème 3.2 fournit une méthode constructive de calcul effectif de la loi de ce minimum. Nous montrons enfin, dans la section 4, l’intérêt de ce minimum, qui apparaît comme la limite faible quand n → ∞ (le nombre de neurones tend vers l’infini) de la loi QVn du réseau moyenné par rapport aux poids synaptiques ; c’est un résultat en moyenne. Nous montrons aussi dans le corollaire 4.3 un résultat de convergence faible presque sûrement par rapport aux poids synaptiques, résultat intéressant d’un point de vue pratique, puisqu’il évite de prendre la moyenne par rapport à tous les réseaux. Le théorème 4.4 donne un résultat de convergence presque sûre de la mesure empirique vers le minimum de H.

1. Introduction

In [8] we started our asymptotic analysis of very large networks of neurons with correlated synaptic weights. We showed that the image Πn of the averaged law QVn through the empirical measure satisfied a large deviation principle with good rate function H. In the same article, we provided an analytical expression of this rate, which is a function of the spectral representation of certain Gaussian processes. In the next section, we recall some definitions given in [8].

2. Mathematical framework

We start by recalling the model of [8]. For some positive integer n > 0, we let Vn = {j ∈ Z : |j| ≤ n}, and |Vn| = 2n + 1. The finite-size neural network below is indexed by points in Vn. We work in discrete time, over times t ∈ {0, 1, . . . , T}, for some positive integer T. The state variable for each neuron is in R, and the path space is T = R Т+1. We equip T with the Euclidean topology, T secretion with the cylindrical topology, and denote the Borelian σ-algebra generated by this topology by B(T secretion).

The equation describing the time variation of the membrane potential Uj of the jth neuron writes:

\[ U^j_t = \gamma U^j_{t-1} + \sum_{i \in V_n} j^i_n f(U^i_{t-1}) + \theta^j + B^j_{t-1}, \quad U^j_0 = u^j_0, \quad j \in V_n, \quad t = 1, \ldots, T \]  

(1)

\( f : \mathbb{R} \to [0, 1] \) is a monotonically increasing Lipschitz continuous bijection. \( \gamma \) is in [0, 1) and determines the time scale of the intrinsic dynamics of the neurons. The \( B^j_t \)'s are i.i.d. Gaussian random variables distributed as \( \mathcal{N}(0, \sigma^2) \). They represent the fluctuations of the neurons’ membrane potentials. The \( \theta^j \)'s are i.i.d. as \( \mathcal{N}(\theta, \sigma^2) \). They are independent of the \( B^j_t \)’s and represent the current injected in the neurons. The \( u^j_0 \)’s are i.i.d. random variables each governed by the law \( \mu_1 \).

The \( j^i_n \)'s are the synaptic weights. \( j^i_n \) represents the strength with which the ‘presynaptic’ neuron \( j \) influences the ‘postsynaptic’ neuron \( i \). They arise from a stationary Gaussian random field specified by its mean and covariance function

\[ \mathbb{E}[j^i_n] = \frac{j}{|V_n|}, \quad \text{cov}(j^i_n j^k_n) = \frac{1}{|V_n|} \Lambda((k-i) \text{ mod } V_n, (l-j) \text{ mod } V_n). \]

\( \Lambda \) is positive definite, let \( \hat{\Lambda} \) be the corresponding (positive) Fourier transform. We make the technical assumption that the summation over both indices of the series \( (\Lambda(i,j))_{i,j \in \mathbb{Z}} \) is absolutely convergent to \( \Lambda^{\text{sum}} > 0 \). We write \( \Lambda^{\text{sum}} = \inf_{|k|,|l|} \Lambda_{\text{min}}(k,j) \) and assume that \( \Lambda^{\text{sum}}_{\text{min}} > 0 \).

We note \( j^n \) the \( |V_n| \times |V_n| \) matrix of the synaptic weights. \( j^n = (j^i_n)_{i,j \in V_n} \).

The process \((Y^j_t)\) defined by

\[ Y^j_t = \gamma Y^j_{t-1} + \bar{\theta} + B^j_{t-1}, \quad j \in V_n, \quad t = 1, \ldots, T, \quad Y^j_0 = u^j_0 \]

is stationary and independent. Writing \( v = \Psi(u) \), we define:

\[ \begin{cases} v_0 = \Psi_0(u) = u_0 \\ v_s = \Psi_s(u) = u_s - \gamma u_{s-1} - \bar{\theta}, \quad s = 1, \ldots, T. \end{cases} \]  

(2)

We extend \( \Psi \) to a mapping \( T^\mathbb{Z} \to T^\mathbb{Z} \) componentwise. We now introduce some more notation.

For some topological space \( \Omega \) equipped with its Borelian \( \sigma \)-algebra \( B(\Omega) \), we denote the set of all probability measures by \( \mathcal{M}(\Omega) \). We equip \( \mathcal{M}(\Omega) \) with the topology of weak convergence. For some \( \mu \in \mathcal{M}(T^\mathbb{Z}) \) governing a process \((X^i_j)_{i,j \in \mathbb{Z}}\), we let \( \mu^V_n \in \mathcal{M}(S^\mathbb{Z}_V) \) denote the marginal governing \((X^i_j)^{V_n}_{i,j \in \mathbb{Z}}\). For some \( \mu \in \mathcal{M}(T^\mathbb{Z}) \) governing a process \((X^i_j)_{i \in \mathbb{Z}}\), we let \( \mu^V_n \in \mathcal{M}(S^\mathbb{Z}_V) \) denote the marginal governing \((X^i_j)^{V_n}_{j \in \mathbb{Z}}\). For some \( X \in \mathcal{T} \) and \( 0 \leq a \leq b \leq T \), \( X_{a:b} \) denotes the \( b - a + 1 \)-dimensional subvector of \( X \). We let \( \mu_{a:b} \in \mathcal{M}(S^\mathbb{Z}_{a:b}) \) denote the marginal governing \((X^i_j)^{a:b}_{i,j \in \mathbb{Z}}\). For some \( j \in \mathbb{Z} \), let the shift operator \( S^j : T^\mathbb{Z} \to T^\mathbb{Z} \) be \( S^j(\omega)^j = \omega^{j+k} \). We let \( \mathcal{M}_S(T^\mathbb{Z}) \) be the set of all stationary probability measures \( \mu \) on \((T^\mathbb{Z}, B(T^\mathbb{Z}))\) such that for all \( j \in \mathbb{Z} \), \( \mu \circ (S^j)^{-1} = \mu \).

We next introduce the following definitions.

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1 We note \( \mathcal{N}_P(m, \Sigma) \) the law of the \( p \)-dimensional Gaussian variable with mean \( m \) and covariance matrix \( \Sigma \).
Definition 2.1. For each measure $\mu \in \mathcal{M}(T^V)$ or $\mathcal{M}_S(T^Z)$, we define $\hat{\mu}$ to be $\mu \circ \Psi^{-1}$.

Definition 2.2. Let $E_2$ be the subset of $\mathcal{M}_S(T^Z)$ defined by
\[ E_2 = \{\mu \in \mathcal{M}_S(T^Z) \mid \mathbb{E}[\nu^0 \mid \|\nu^0\|^2 < \infty]\}. \]

Let $p_{n} : T^{V_n} \rightarrow T^{Z}$ be such that $p_{n}(\omega) = \omega^k \mod V_n$. Here, and throughout the paper, we take $k \mod V_n$ to be the element $l \in V_n$ such that $l = k \mod |V_n|$. Define the process-level empirical measure $\hat{\mu}_n : T^{V_n} \rightarrow \mathcal{M}_S(T^Z)$ as
\[ \hat{\mu}_n(\omega) = \frac{1}{|V_n|} \sum_{k \in V_n} \delta_{l_k} p_{n}(\omega), \]
where $\delta_{l_k}$ is the element of $\mathcal{M}(T^Z)$ which is the law of the solution to (1) conditioned on $J^n$. We let $Q^{V_n} = \mathbb{E}[^{|Q^{V_n}||J^n|}]$ be the law averaged with respect to the weights. Finally we introduce the image law in terms of which the principal results of this paper are formulated.

Definition 2.3. Let $I_n \in \mathcal{M}(\mathcal{M}_S(T^Z))$ be the image law of $Q^{V_n}$ through the function $\hat{\mu}_n : T^{V_n} \rightarrow \mathcal{M}_S(T^Z)$ defined by (3):
\[ I_n = Q^{V_n} \circ \hat{\mu}_n^{-1}. \]

3. Characterization of the unique minimum of the rate function

In [7], with each measure $\nu \in \mathcal{M}(T^Z)$ we associate the measure, noted $Q^{\nu}$ of $\mathcal{M}(T^Z)$ such that $Q^{\nu} = \mu_{\mathcal{I}} \otimes Q_{1T}^{\nu}$, where $Q_{1T}^{\nu}$ is a Gaussian measure on $T_{1T}^Z$ with spectral density $\sigma^2 \delta(\theta) + \tilde{K}^{\nu}(\theta)$ and mean $c^{\nu}$. The spectral density $\tilde{K}^{\nu}$ and mean $c^{\nu}$ are defined in [8]. We also define the rate function $H^{\nu}$, which uses a linear approximation of the functional $I^{\nu}$ defined in [7] and satisfies the relation $H^{\nu}(\mu) = H(\mu)$. We prove the following lemma in [7].

Lemma 3.1. For $\mu, \nu \in \mathcal{M}_S(T^Z)$, $H^{\nu}(\mu) = 0$ if and only if $\mu = Q^{\nu}$.

As stated in the following proposition, there exists a unique minimum $\mu_e$ of the rate function $H$. We provide explicit equations for $\mu_e$ which would facilitate its numerical simulation.

Proposition 3.1. There is a unique distribution $\mu_e \in \mathcal{M}_S(T^Z)$ which minimizes $H$. This distribution satisfies $H(\mu_e) = 0$, which is equivalent to $\mu_e = Q^{\mu_e}$.

Proof. The proof, which is found in [7], is an easy consequence of the explicit method we outline to actually calculate $\mu_e$ below in Theorem 3.2. \qed

We characterize the unique measure $\mu_e$ such that $\mu_e = Q^{\mu_e}$ in terms of its image $\hat{\mu}_e$. This characterization allows one to directly numerically calculate $\mu_e$, since $\mu_e$ is Gaussian. The problem becomes that of defining the latest entries (in time) of $K^{\mu_e}$ and $c^{\mu_e}$ in terms of previous ones. Hence we characterize $\mu_e$ recursively (in time), by providing a method of determining $\mu_{e,1-1}$ in terms of $\mu_{e,0}$. Let $K_{e,1-1}$ be the $(t - 1) \times (s - 1)$ submatrix of $K^{\mu_e}$ composed of the rows from times 1 to $t - 1$ and the columns from times 1 to $s - 1$. Let the measure $\mu_{e,0} \in \mathcal{M}(T_{0,T})$ be given by
\[
\mu_{e,0} (dv_0) = \mu_I(dv_0) \otimes N_t((\mu_e, c^{\mu_e}), \sigma^2 I_t) \, dy^{v_0}_{1,t},
\]
and $\mu^{(1)}_{e,0,0,0} \in \mathcal{M}(T_{0,0} \times T_{0,0})$ be given by
\[
\mu^{(1)}_{e,0,0,0} (dv_{0,0}) = \mu_I(dv_{0,0}) \otimes \mu_I(dv_{0,0}) \\
\otimes N_{s+t_s}((\mu_e, c^{\mu_e}), \sigma^2 I_{t,s} + K^{\mu_e,(0,0)}_{s,t,s}) \, dy^{v}_{1,t} \, dy^{v}_{1,s},
\]
where
\[
K^{\mu_e,(0,0)}_{s,t,s} = \begin{bmatrix} K^{\mu_e,0}_{s,t,s} & K^{\mu_e,1}_{s,t,s} & K^{\mu_e,0}_{s,t,s} \\
K^{\mu_e,1}_{s,t,s} & K^{\mu_e,2}_{s,t,s} & K^{\mu_e,1}_{s,t,s} \\
K^{\mu_e,0}_{s,t,s} & K^{\mu_e,1}_{s,t,s} & K^{\mu_e,0}_{s,t,s} \end{bmatrix},
\]
and the $\dagger$ sign represents the transpose of a matrix or a vector. Observe that $\{c^{\mu_e}_s, K^{\mu_e}_{s,s} \mid s \in [1, T]\}$ are sufficient to characterize $\hat{\mu}_e$, since a Gaussian is entirely characterized by its mean and covariance. Furthermore, $\{\mu_{e,0,0,0,0} \mid 0 \leq l \leq 2\}$
are sufficient to characterize $\mu_{\epsilon, t}$, because a Gaussian law is uniquely characterized by its pairwise marginals. Therefore the following theorem is sufficient for the inductive calculation of $\mu_{\epsilon}$.

**Theorem 3.2.** We may characterize $\mu_{\epsilon}$ inductively as follows. Initially $\mu_{\epsilon, 0} = \mu_{0}^2$. Given that we have a complete characterization of $[\mu_{\epsilon, (0, l, 0, t)} : l \in \mathbb{Z}]$, we may characterize $[\mu_{\epsilon, (0, l, 0, t)} : l \in \mathbb{Z}]$ according to the following identities. For $s \in [1, t]$,

$$c_{s}^{\epsilon} = \int f(\Phi^{-1}(v)_{s-1})\mu_{0, s-1}^{\epsilon} \, dv.$$  

(4)

For $1 \leq r, s \leq t$, $K_{rs}^{\epsilon, k} = \theta_{k} I_{T}^{r} + \sum_{l=-\infty}^{\infty} A(k, l)M_{rs}^{\epsilon}$. Here, for $p = \max(r - 1, s - 1)$,

$$M_{rs}^{\epsilon} = \int f(\Phi^{-1}(v)_{r-1}) \times f(\Phi^{-1}(v)_{s-1})\mu_{r, p}^{\epsilon} \, dv,$$

(5)

and for $l \neq 0$

$$M_{rs}^{\epsilon, l} = \int f(\Phi^{-1}(v)_{r-1}) \times f(\Phi^{-1}(v)_{s-1})\mu_{r, p}^{\epsilon, l} \, dv \, dv.$$  

(6)

**Remark 1.** From a practical point of view the $s$-dimensional integral in (4) and the $(r, s)$-dimensional integral in (5) can be reduced by a change of variable to at most two dimensions. Similarly, the $(r + s)$-dimensional integral in (6) can be reduced to at most four dimensions.

**Remark 2.** If we make the biologically realistic assumption that the synaptic weights are not correlated beyond a certain correlation distance $d \geq 0$, $A(k, l) = 0$ if $k$ or $l$ does not belong to $V_{d}$ it is seen that the matrices $K_{rs}^{\epsilon, k}$ are 0 as soon as $k \notin V_{d}$: thus in this case the asymptotic description of the network of neurons is sparse.

4. Convergence results

We use the Large Deviation Principle proved in [8,7] to establish convergence results for the measures $\Delta^{n}$, $Q^{V_{n}}$ and $Q^{V_{n}}(J^{n})$.

**Theorem 4.1.** $\Delta^{n}$ converges weakly to $\delta_{\mu_{\epsilon}}$, i.e., for all $\Phi \in C_{b}(\mathcal{M}_{S}(T^{Z}))$,

$$\lim_{n \to \infty} \int_{\Delta^{n}} \Phi(\hat{\mu}_{n}(u)) \, Q^{V_{n}}(du) = \Phi(\mu_{\epsilon}).$$

Similarly,

$$\lim_{n \to \infty} \int_{\Delta^{n}} \Phi(\hat{\mu}_{n}(u)) \, Q^{V_{n}}(J^{n})(du) = \Phi(\mu_{\epsilon}) \quad J \text{ almost surely}.$$  

**Proof.** The proof of the first result follows directly from the existence of an LDP for the measure $\Delta^{n}$, see Theorem 3.1 in [8], and is a straightforward adaptation of the one in [10, Theorem 2.5.1]. The proof of the second result uses the same method, making use of Theorem 4.2 below. □

We can in fact obtain the following quenched convergence analogue of the usual lower bound inequality in the definition of a Large Deviation Principle.

**Theorem 4.2.** For each closed set $F$ of $\mathcal{M}_{S}(T^{Z})$ and for almost all $J$:

$$\lim_{n \to \infty} \frac{1}{|\Delta^{n}|} \log \left[ Q^{V_{n}}(J^{n})^{\alpha_{n}} \cap S_{n}^{-1} \right] \leq \inf_{\mu \in F} H(\mu).$$

**Proof.** The proof is a combination of Tchebyshev’s inequality and of the Borel–Cantelli lemma and is an adaptation of the one in [10, Theorem 2.5.4, Corollary 2.5.6]. □

We define $\tilde{Q}^{V_{n}}(J^{n}) = \frac{1}{|\Delta^{n}|} \sum_{j \in V_{n}} Q^{V_{n}}(J^{n}) \circ S^{-n}$, where we recall the shift operator $S$. Clearly $\tilde{Q}^{V_{n}}(J^{n})$ is in $\mathcal{M}_{S}(T^{V_{n}})$. We define $\tilde{Q}^{V_{n}}$ to be the expectation of $\tilde{Q}^{V_{n}}(J^{n})$, with respect to the synaptic weights $J$. 
Corollary 4.3. Fix m and let n > m. For almost every J and all h ∈ C_b(T_{V_m}),

\[
\lim_{n \to \infty} \int_{T_{V_m}} h(u) \tilde{Q}^{V_m}(J^n)(du) = \int_{T_{V_m}} h(u) \mu_e^{V_m}(du),
\]

\[
\lim_{n \to \infty} \int_{T_{V_m}} h(u) Q^{V_m}(J^n)(du) = \int_{T_{V_m}} h(u) \mu_e^{V_m}(du).
\]

That is, the V_m^{th} marginals \(\tilde{Q}^{V_m}(J^n)\) and \(Q^{V_m}(J^n)\) of respectively \(\hat{Q}^{V_m}(J^n)\) and \(\hat{Q}^{V_m}\) converge weakly to \(\mu_e^{V_m}\) as \(n \to \infty\).

Proof. It is sufficient to apply Theorem 4.1 in the case where \(\Phi\) in \(C_b(M_S(T^{Z}))\) is defined by

\[\Phi(\mu) = \int_{T^{V_m}} h d\mu^{V_m}\]

and to use the fact that \(Q^{V_m}, \tilde{Q}^{V_m}(J^n) \in M_S(T^{V_m})\). \(\square\)

We now prove the following ergodic-type theorem. We may represent the ambient probability space by \(\Omega\), where \(\omega \in \Omega\) is such that \(\omega = (J_i, B_i, u_i^n)\), where \(i, j \in Z\) and \(0 \leq t \leq T - 1\), recall (1). We denote the probability measure governing \(\omega\) by \(\Psi\). Let \(u^{(n)}(\omega) \in T^{V_n}\) be defined by (1). As an aside, we may then understand \(Q^{V_n}(J^n)\) to be the conditional law of \(\Psi\) on \(u^{(n)}(\omega)\), for a given \(J^n\).

Theorem 4.4. Fix m > 0 and let h ∈ C_b(T_{V_m}). For \(u^{(n)}(\omega) \in T^{V_n}\) (where \(n > m\)) \(\Psi\) almost surely,

\[
\lim_{n \to \infty} \frac{1}{|V_n|} \sum_{j \in V_n} h(\pi^{V_m} S^j u^{(n)}(\omega))) = \int_{T_{V_m}} h(u) d\mu^{V_m}(u).
\]  

(7)

where \(\pi^{V_m}\) is the projection onto \(V_m\). Hence \(\hat{\mu}_n(u^{(n)}(\omega))\) converges \(\Psi\)-almost-surely to \(\mu_e\).

Proof. Our proof is an adaptation of [10]. We may suppose without loss of generality that \(\int_{T^{V_m}} h(u) d\mu_e^{V_m}(u) = 0\). For \(p > 1\) let

\[F_p = \left\{ \mu \in M_S(T^{Z}) \mid \int_{T_{V_m}} h(u) \mu^{V_m}(du) \geq \frac{1}{p} \right\}.
\]

Since \(\mu_e \notin F_p\), but it is the unique zero of \(H\), it follows that \(\inf_{F_p} H = m > 0\). Thus by Theorem 3.1 in [8], there exists an \(n_0\), such that for all \(n > n_0\),

\[Q^{V_n}(\hat{\mu}_n \in F_p) \leq \exp(-m|V_n|).
\]

However

\[\Psi(\omega \mid \hat{\mu}_n(u^{(n)}(\omega)) \in F_p) = Q^{V_n}(u \mid \hat{\mu}_n(u) \in F_p).
\]

Thus

\[\sum_{n=0}^{\infty} \Psi(\omega \mid \hat{\mu}_n(u^{(n)}(\omega)) \in F_p) < \infty.
\]

We may thus conclude from the Borel–Cantelli lemma that \(\Psi\) almost surely, for every \(\omega \in \Omega\), there exists \(n_p\) such that for all \(n \geq n_p\),

\[
\frac{1}{|V_n|} \sum_{j \in V_n} h(\pi^{V_m} S^j u^{(n)}(\omega))) \leq \frac{1}{p}.
\]

This yields (7) because \(p\) is arbitrary. The convergence of \(\hat{\mu}_n(u^{(n)}(\omega))\) is a direct consequence of (7), since this means that each of the \(V_m^{th}\) marginals converge. \(\square\)
5. Possible extensions and conclusion

This result can be straightforwardly extended to the case when the noise is correlated but stationary Gaussian, that is \( \text{cov}(B_s^j, B_t^k) \) is some function of \( s, t \) and \( (k - j) \), see [6]. It can also be easily extended to the case that the initial distribution is correlated, but the spatial correlation satisfies a certain “mixing principle”, which enforces a sufficiently rapid decay [4].

The hypothesis that the synaptic weights are Gaussian is somewhat unrealistic from the biological viewpoint. In his PhD thesis [10], Moynot has obtained some preliminary results in the case of uncorrelated weights. We think that this is also a promising avenue. Moynot again, in his thesis, has extended the uncorrelated weights case, to include two populations with different (Gaussian) statistics for each population. This is also an important practical problem in neuroscience. Finally, the extension of Moynot’s result to the correlated case would probably constitute a low hanging fruit.

It would be of interest to compare our LDP with other analyses of the rate of convergence of neural networks to their limits as the size asymptotes to infinity. This includes the system-size expansion of Bressloff [1], the path-integral formulation of Buice and Cowan [2] and the systematic expansion of the moments by (amongst others) [9,5,3].

In recent years there has been a lot of effort to mathematically justify neural-field models, through some sort of asymptotic analysis of finite-size neural networks. Many, if not most, of these models assume/prove some sort of thermodynamic limit, whereby if one isolates a particular population of neurons in a localized area of space, they are found to fire increasingly asynchronously as the number in the population asymptotes to infinity. Indeed this was the result of Moynot and Samuelides. However, our results imply that there are system-wide correlations between the neurons, even in the asymptotic limit. The key reason why we do not have propagation of chaos is that the Radon–Nikodym derivative \( \frac{d\mu_N}{d\mu_{indep}} \) of the average laws in [8, Proposition 2.4] cannot be tensored into \( N \) i.i.d. processes, whereas the simpler assumptions on the weight function \( \Lambda \) in Moynot and Samuelides allow the Radon–Nikodym derivative to be tensored. A very important implication of our result is that the mean-field behavior is insufficient to characterize the behavior of a population. Our limit process \( \mu_N \) is system-wide and ergodic. Our work challenges the assumption held by some that one cannot have a ‘concise’ macroscopic description of a neural network without an assumption of asynchronicity at the local population level.

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2 We noted in the introduction that this is termed propagation of chaos by some.