Hydrodynamic Nambu brackets derived by geometric constraints

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Received 17 October 2014, revised 7 January 2015
Accepted for publication 26 January 2015
Published 12 February 2015

Abstract
A geometric approach to derive the Nambu brackets for ideal two-dimensional (2D) hydrodynamics is suggested. The derivation is based on two-forms with vanishing integrals in a periodic domain, and with resulting dynamics constrained by an orthogonality condition. As a result, 2D hydrodynamics with vorticity as dynamic variable emerges as a generic model, with conservation laws which can be interpreted as enstrophy and energy functionals. Generalized forms like surface quasi-geostrophy and fractional Poisson equations for the stream-function are also included as results from the derivation. The formalism is extended to a hydrodynamic system coupled to a second degree of freedom, with the Rayleigh–Bénard convection as an example. This system is reformulated in terms of constitutive conservation laws with two additive brackets which represent individual processes: a first representing inviscid 2D hydrodynamics, and a second representing the coupling between hydrodynamics and thermodynamics. The results can be used for the formulation of conservative numerical algorithms that can be employed, for example, for the study of fronts and singularities.

Keywords: 47.10.Df Hamiltonian formulations, 47.55.P-buoyancy-driven flows, convection, 47.32.-y vortex dynamics, rotating fluids, 92.10.-c physical oceanography, 92.60.-e properties and dynamics of the atmosphere, meteorology

1. Introduction

In a seminal article, Nambu [1] suggested an extension of Hamiltonian dynamics which is based on Liouville’s theorem and, differently from classical Hamiltonian mechanics, makes...
use of several conserved quantities. The additional conservation laws (CLs) can be considered as additional Hamiltonians and define manifolds whose intersections determine the trajectory in state space. In analogy to Poisson brackets in Hamiltonian mechanics, the resulting dynamics is determined by Nambu brackets [2]. As a first example, Nambu considered the Euler equations for a rotating solid body [1]. The approach has then been applied to a variety of finite-dimensional systems, ranging from the non-dissipative Lorenz equations [3] to the geometry of strange attractors in dissipative, chaotic systems [4]. For early examples of the derivation of the Nambu equations for different systems, see [5, 6].

The Nambu approach was extended from finite to infinite dimensional systems, and in particular to hydrodynamics, by Névir and Blender [7], who were able to determine the Nambu brackets corresponding to ideal hydrodynamics in two and three dimensions, with enstrophy and helicity as CLs which exist as a consequence of the particle relabeling symmetry [8]. An important finding was that a Nambu representation can be useful to construct numerical algorithms for the simulation of geophysical flows [9, 10]. The application of this approach in a global shallow water model revealed a distinct impact on energy and enstrophy spectra [11]. In the past years, several models of geophysical fluid dynamics have been rewritten in terms of Nambu brackets [12–16].

It should be noted that, apart for notable exceptions (e.g. [17]), the construction of the hydrodynamics Nambu brackets was mainly based on intuition and guessing. The aim of this study is thus to derive the Nambu brackets for hydrodynamics using a geometrical approach, which is based on replacing the Jacobian by a two-form based on the two CLs, as suggested for finite dimensional systems by [18]. While the examples here analysed have already been studied in the past, we report a novel way to systematically derive the hydrodynamics Nambu brackets. The method is introduced in section 2 for a physical system with three degrees of freedom and two CLs. In section 3, the geometrical approach is used to derive the Nambu bracket for two-dimensional (2D) hydrodynamics. The Nambu form for 2D hydrodynamics emerges when the dynamic variable is interpreted as vorticity, and the two CLs are the kinetic energy and the enstrophy. The resulting dynamics can be extended to the case of generalized Euler equations with a fractional Poisson operator for the stream-function. In section 4, the approach is extended to a coupled system with two degrees of freedom. Rayleigh–Bénard convection is discussed as an example. Finally, in section 5 the method is used to construct a Nambu representation of the coupled model in terms of constitutive conservation laws (CCLs), i.e. CLs which are conserved only in sub-systems.

2. Geometry of Nambu mechanics in 3D

Consider a physical system with three degrees of freedom, \( X = (x_1, x_2, x_3) \) and two CLs, \( H = H(X) \) and \( C = C(X) \). Since \( H \) and \( C \) are invariant

\[
\frac{dH}{dt} = \nabla_X H \cdot \frac{dX}{dt} = 0, \tag{1}
\]

\[
\frac{dC}{dt} = \nabla_X C \cdot \frac{dX}{dt} = 0, \tag{2}
\]

where \( \nabla_X \) indicates the gradient operator in the \( X \) space. (1)–(2) are satisfied if the vector \( dX/dt \) is orthogonal to \( \nabla_X H \) and \( \nabla_X C \). An orthogonal vector can be constructed using the three-dimensional vector product.
\[
\frac{dX}{dt} = V_X C \times V_X H, \quad (3)
\]
which shows that the flow in phase space \(dX/dt\) is along the intersection of the manifolds defined by constant \(H\) and \(C\). Equation (3) is the canonical Nambu form

\[
\frac{dx_n}{dt} = \frac{\partial(x_n, C, H)}{\partial(x_1, x_2, x_3)}, \quad n = 1, 2, 3. \quad (4)
\]

Equation (4) can be rewritten using the anti-symmetric Levi-Civita symbol \(\varepsilon_{nij}\) as

\[
\frac{dx_n}{dt} = \varepsilon_{nij} \frac{\partial C}{\partial x_i} \frac{\partial H}{\partial x_j}, \quad n, i, j = 1, 2, 3. \quad (5)
\]

The dynamics of an arbitrary state space function \(F(X)\) is thus given by the canonical Nambu bracket

\[
\frac{\partial F}{\partial t} = \{F, C, H\}. \quad (6)
\]

Geometrically, the bracket is the volume of the parallelepiped

\[
\{F, C, H\} = V_X F \cdot V_X C \times V_X H. \quad (7)
\]

The conservation of \(H\) and \(C\) is obtained from (7), since the volume vanishes for \(F = H\) or \(F = C\).

As stated in the introduction, the Nambu bracket differ from the usual Poisson bracket for being defined on a phase space that can be odd dimensional and of higher dimensionality, i.e. of dimension \(n \geq 3\). If (7) is generalized as \(\{f_1, \ldots, f_n\}\), the bracket is a multilinear map

\[
\forall f_i (i = 1, \ldots, n) \in X, \text{ where } X \text{ is a smooth manifold}. \quad \text{Equation (8) satisfies the following properties:}
\]

- **Skew-symmetry**
  \[
  \{f_1, \ldots, f_n\} = (-1)^{\varepsilon(\sigma)} \{f_{\sigma_1}, \ldots, f_{\sigma_n}\}, \quad (9)
  \]
  where \(\varepsilon(\sigma)\) is the parity of a permutation \(\sigma\).

- **Leibniz Rule**
  \[
  \{f_1, \ldots, f_n\} = f_1 \{f_2, \ldots, f_n\} + \{f_1, f_2, \ldots, f_n\} f_1. \quad (10)
  \]

- **Fundamental Jacobi identity**
  \[
  \begin{align*}
  \{ \{f_1, \ldots, f_{n-1}, f_n\}, f_{n+1} \} &+ \{f_n, \{f_1, \ldots, f_{n-1}, f_{n+1}\}, f_{n+2} \} + \cdots + \{f_n, \ldots, f_{2n-2}, f_1, \ldots, f_{n-1}, f_{n+1}\} \\
  &= \{f_1, \ldots, f_{n-1}, \{f_n, \ldots, f_{2n-1}\}\}. \quad (11)
  \end{align*}
  \]

For more algebraic properties of Nambu brackets see [2]. Finally, it should be noted that, due to the multiple Hamiltonian structure of Nambu mechanics, Nambu systems have the property of possessing dynamical or hidden symmetries resulting in extra integrals of motion beyond those needed for complete integrability [5].
3. Hydrodynamics in 2D

3.1. Geometric derivation of the Nambu bracket

Consider a 2D continuous system with the dynamic variable $\zeta$ and the two conserved functionals $H = H[\zeta]$ and $E = E[\zeta]$. The conservation of $H$ and $E$ yields

\[
\frac{dH}{dt} = \int H_t \frac{\delta H}{\delta \zeta} dA = 0, \tag{12}
\]

\[
\frac{dE}{dt} = \int E_t \frac{\delta E}{\delta \zeta} dA = 0, \tag{13}
\]

where $H_t = \delta H / \delta \zeta$ and $E_t = \delta E / \delta \zeta$ are the functional derivatives of $H$ and $E$ with respect to $\zeta$, and $dA = dx_1 dx_2$ is an area element. In analogy to the 3D state space considered in section 2, the sums (1)–(2) are replaced by the integrals in the $(x_1, x_2)$ plane. In (12)–(13), the CLs are constraints for the time evolution of $\zeta$ and can be interpreted as an orthogonality condition for $E$ and $H$ with respect to $\partial H / \partial t$.

To construct dynamics which satisfies these orthogonality relations, we use differential forms (see, e.g., [19]). Consider a 2-form $\wedge$ for arbitrary functions $f$ and $g$, which is exact, so that $df \wedge dg = d(f \wedge dg)$. The integral of the 2-form thus vanishes in a periodic domain

\[
\int df \wedge dg = 0. \tag{14}
\]

Equation (14) yields

\[
\int f df \wedge dg = 0 \quad \text{and} \quad \int g df \wedge dg = 0, \tag{15}
\]

which shows that $f$ and $g$ are orthogonal to the 2-form $df \wedge dg$. With the identifications $f = H$, $g = E$, (12)–(13) suggests

\[
\frac{\delta H}{\delta \zeta} dA = df \wedge dg = J(f, g) dx_1 \wedge dx_2, \tag{16}
\]

where $J$ is the Jacobian $J(f, g) = f_{\zeta} g_{x_2} - f_{x_2} g_{\zeta}$ with the subscripts indicating partial derivatives. The orthogonality constraint (16) yields

\[
\frac{\delta H}{\delta \zeta} = J(H, E), \tag{17}
\]

which is the Nambu representation of 2D hydrodynamics [7]. Arbitrary functionals $F[\zeta]$ evolve according to

\[
\frac{\delta F}{\delta \zeta} = \{F, E, H\}, \tag{18}
\]

with the Nambu bracket

\[
\{F, E, H\} = -\int F J(E, H) dA. \tag{19}
\]

The bracket (19) is anti-symmetric and cyclic, $\{F, E, H\} = \{E, H, F\} = \{H, F, E\}$, since

\[
\int df \wedge dg = \int g dh \wedge df = \int h df \wedge dg.
\]

A non-canonical Hamiltonian formulation is obtained by evaluating the functional derivative $E$. This yields a Poisson bracket

\[
\{F, E, H\} = -\int F J(E, H) dA.
\]
with the Casimir functional $E$.

### 3.2. Physical Interpretation of the CLs $H$ and $E$

The dynamics derived so far is not based on a physical interpretation of the two CLs $H$ and $E$. Consider a 2D, non-divergent flow $(u, v)$ in the $(x, y)$ plane, derived from the stream-function $\psi$ that satisfies $u = -\partial_y \psi, \; v = \partial_x \psi$. With the vorticity

$$\zeta = \frac{\partial v}{\partial x} - \frac{\partial u}{\partial y} = \nabla^2 \psi, \quad (21)$$

the first CL is the kinetic energy

$$H = \frac{1}{2} \int (u^2 + v^2) \, dA. \quad (22)$$

For periodic boundary conditions

$$H = -\frac{1}{2} \int \zeta \psi \, dA, \quad (23)$$

and the functional derivative is

$$\frac{\delta H}{\delta \zeta} = -\psi. \quad (24)$$

The kinetic energy $H$ plays thus a unique role in hydrodynamics since it is responsible for the advection in Eulerian flows through the functional derivative with respect to $\zeta$.

The second CL is the enstrophy

$$E = \frac{1}{2} \int \zeta^2 \, dA, \quad (25)$$

so that

$$\frac{\delta E}{\delta \zeta} = \zeta. \quad (26)$$

Using (24) and (26), (17) yields

$$\frac{\partial \zeta}{\partial t} = -J(\psi, \zeta). \quad (27)$$

It should be noted that due to the Lagrangian conservation of $\zeta$, the system conserves arbitrary functionals $E_h = \int h(\zeta) \, dA$. As noted by [7], (27) can be rewritten in terms of any Casimir $E_h$, given an opportune rescaling of the 2D Jacobian.

The Nambu bracket (19), derived for the Euler equation, holds also for generalized Euler equations in which the stream-function $\psi$ is linked to an active tracer $\zeta$ by a fractional Poisson equation [20, 21]

$$\zeta = \psi^\alpha. \quad (28)$$

In (28), the parameter $\alpha$ defines the degree of smoothing. While for $\alpha = 2$, (28) implies the 2D Euler equation, for $\alpha = 1$ a physical model is given by a stratified and rotating flow in a semi-infinite three-dimensional domain with nonlinear advection of potential temperature at one of the boundaries and vanishing potential vorticity in the interior [22, 23]. The so-obtained dynamics is called surface quasi-geostrophic approximation. If the horizontal
coordinates are a Legendre transform of the physical coordinates \((x, y)\) which follow the flow, and neglecting an arising nonlinear term, the surface semi-geostrophic approximation is obtained [24]. Other cases physically realizable include the case with negative exponent \(\alpha = -2\), which corresponds to the limit of the large-scale quasi-geostrophic dynamics [25], and the case \(\alpha = 3\) which represents a rotating shallow flow, which is the limit of a mantle convection model [26]. Other values of \(\alpha\) can be used for the study of systems characterized by different degrees of locality of the resulting turbulence [27]. Noticeably, all the models defined by (28) have the same Nambu bracket (19) and CLs, with the only difference in the physical meaning of the CLs.

4. Geometry of coupled continuous systems

4.1. Nambu bracket for a system with two degrees of freedom

Consider now a system with two degrees of freedom \(\zeta\) and \(\mu\). Two generic CLs are considered: the first is the total energy, given by the sum of the kinetic energy and a potential energy which is a functional of \(\mu\) only

\[
H = -\frac{1}{2} \int \zeta \psi \, dA + P[\mu].
\]

(29)

The second CL is a bilinear coupling of vorticity to the second degree of freedom \(\mu\)

\[
C = \int \zeta \mu \, dA.
\]

(30)

The time derivatives of the two CLs are

\[
\frac{dH}{dt} = \int \left[ H_\zeta \frac{\partial \zeta}{\partial t} + H_\mu \frac{\partial \mu}{\partial t} \right] dA = 0,
\]

(31)

\[
\frac{dC}{dt} = \int \left[ C_\zeta \frac{\partial \zeta}{\partial t} + C_\mu \frac{\partial \mu}{\partial t} \right] dA = 0.
\]

(32)

The advection of vorticity \(\zeta\) by the flow \(\psi\) can be written as

\[
\frac{\partial \zeta}{\partial t} \, dx \wedge dy = dH_\zeta \wedge dC_\mu.
\]

(33)

With this term the first part of the integral in (31) vanishes. The advection of \(\mu\) is represented by

\[
\frac{\partial \mu}{\partial t} \, dx \wedge dy = -dC_\zeta \wedge dH_\zeta.
\]

(34)

To satisfy \(dH/dt = 0\), an additional term \(Z\) is necessary in \(\partial \zeta /\partial t\), so that

\[
\frac{\partial \zeta}{\partial t} \, dx \wedge dy = dH_\zeta \wedge dC_\mu + Z.
\]

(35)

With (34) and (35), and the identities

\[
\int d\left( C_\mu C_\zeta \right) \wedge dH_\zeta = 0 \quad \text{and} \quad \int d\left( H_\mu H_\zeta \right) \wedge dC_\zeta = 0,
\]

(36)
equation (31) becomes
\[
\frac{dH}{dt} = \int H_\zeta (dH_\zeta \wedge dC_\mu + Z) dA + \int H_\mu dH_\zeta \wedge dC_\zeta dA = 0, \tag{37}
\]
which requires that
\[
Z = -dC_\zeta \wedge dH_\mu. \tag{38}
\]
Using this \(Z\)-term, the derivatives \(dH/dt\) and \(dC/dt\) vanish, and we have finally
\[
\frac{\partial \zeta}{\partial t} dy \wedge dx = -dC_\mu \wedge dH_\zeta - dC_\zeta \wedge dH_\mu. \tag{39}
\]
Notice that the additional \(Z\) term does not contribute to \(dC/dt\). This is a direct consequence of Nambu mechanics having the property of possessing hidden symmetries resulting in extra integrals of motion. Using the forms obtained for \(\partial \zeta/\partial t\) and \(\partial \mu/\partial t\), we can define a Nambu bracket for an arbitrary functional \(F[\zeta, \mu]\) by including the corresponding functional derivatives \(F_\mu\) and \(F_\zeta\)
\[
\frac{dF}{dt} = \{F, C, H\} \tag{40}
\]
\[
\{F, C, H\} = -\int \left[ F_\mu dC_\zeta \wedge dH_\zeta + F_\zeta dC_\mu \wedge dH_\mu + F_\zeta dC_\mu \wedge dH_\zeta \right]. \tag{41}
\]
As noted by [12], this Nambu bracket is the continuous analogue of the Nambu bracket for the heavy top, for which the fundamental Jacobi identity is known to be satisfied.

4.2. Example: Rayleigh–Bénard convection

To demonstrate how the method can be applied in a practical context, the Rayleigh–Bénard convection is used as an example. The system has two dynamic variables, \(\zeta\) and \(\mu\), the first being the vorticity and the second representing a vertical temperature anomaly that interacts with the convective motion. The dynamic equations are [12]
\[
\frac{\partial \zeta}{\partial t} = J(\zeta, \psi) + \frac{\partial \mu}{\partial x}, \tag{42}
\]
\[
\frac{\partial \mu}{\partial t} = J(\mu, \psi) + \frac{\partial \psi}{\partial x}, \tag{43}
\]
where \(\psi\) is the stream-function for the non-divergent flow \((u, v)\) in the vertically oriented \(x\)--\(y\)-plane, \(u = -\partial \psi/\partial y, \ v = \partial \psi/\partial x\). The two CLs are
\[
H = -\int \left( \frac{1}{2} \zeta \psi + \mu v \right) dx dy, \tag{44}
\]
\[
C = \int \zeta (\mu - y) dx dy, \tag{45}
\]
where \(H\) is the total energy (kinetic and potential) and \(C\) is based on Kelvin’s circulation theorem.

The dynamic equations for an arbitrary functional \(F[\zeta, \mu]\) can be obtained by the Nambu bracket (41) (see also [12, 15]). This example shows that the geometric approach based on orthogonality conditions (31)–(32) yields a rather simple and straightforward method to construct the Nambu bracket.
5. Constitutive conservation laws

Following an idea already included in the original paper by Nambu [1], CCLs have been introduced in Nambu dynamics by [14]. The corresponding brackets have been classified by [15] as Nambu brackets of type II. The main idea is the partitioning of a physical system into sub-systems, with CLs satisfied in the sub-system only. For the coupled system introduced in section 4, this means that $H$ and $C$ are conserved, but the dynamics is written in terms of two functionals which replace $C$ and are not conserved in the complete system. The resulting dynamics is split into two brackets: a first bracket, which uses enstrophy $E$ and energy $H$ and corresponds to 2D-hydrodynamics, without contributions from the buoyancy. The second bracket uses total energy $H$ and a CL $B$, which is based on the thermodynamics of the system only. The system is decomposed by the dependencies $E = E[\zeta]$ and $B = B[\mu]$. It is convenient to use quadratic integrals

$$E = \frac{1}{2} \int \zeta^2 \, dA, \quad B = \frac{1}{2} \int \mu^2 \, dA.$$  \hspace{1cm} (46)

Notice that $B$ defined here differs from the total buoyancy used by [15]. The overarching role of the total energy $H$ is expressed by $H = H[\zeta, \mu]$, which combines kinetic and potential energy. It should be noted that the energy $H$ remains in all brackets.

The CLs for $H$ and $C$ are the same as in (31)–(32). To proceed with the determination of the Nambu bracket, the functional derivatives of $C$ are substituted by derivatives of $E$ and $B$

$$C_\zeta = B_\mu, \quad C_\mu = E_\zeta.$$  \hspace{1cm} (47)

thus the dynamical equations read as

$$\frac{\partial \zeta}{\partial t} dx \wedge dy = dH_\zeta \wedge dE_\zeta - dB_\mu \wedge dH_\mu,$$  \hspace{1cm} (48)

$$\frac{\partial \mu}{\partial t} dx \wedge dy = dH_\zeta \wedge dB_\mu.$$  \hspace{1cm} (49)

Using (48)–(49), one can formulate the tendency of an arbitrary functional $F[\zeta, \mu]$

$$\frac{dF}{dt} = - \int F_\zeta dE_\zeta \wedge dH_\zeta - \int F_\zeta dB_\mu \wedge dH_\mu - \int F_\mu dB_\mu \wedge dH_\zeta.$$  \hspace{1cm} (50)

The first term is the 2D bracket for incompressible hydrodynamics, which involves only $\zeta$-derivatives (19)

$$\left\{ F, E, H \right\}_\zeta \zeta = - \int F_\zeta dE_\zeta \wedge dH_\zeta,$$  \hspace{1cm} (51)

with the enstrophy $E$ and the energy $H$. The second bracket is

$$\left\{ F, B, H \right\}_\mu \mu = - \int F_\zeta dB_\mu \wedge dH_\mu - \int F_\mu dB_\mu \wedge dH_\zeta.$$  \hspace{1cm} (52)

The dynamics is split into two brackets with the CCLs $E$ and $B$, so that

$$\frac{dF}{dt} = \left\{ F, E, H \right\}_\zeta \zeta + \left\{ F, B, H \right\}_\mu \mu.$$  \hspace{1cm} (53)

In the classification introduced by [15], this is a Nambu bracket of type II. If buoyancy is neglected this decomposition yields a representation of the coupled system in terms of only 2D-hydrodynamics.
6. Summary

In this study, Nambu systems with two CLs are reconsidered. For three degrees of freedom, the standard Nambu form is derived by a pure geometric approach in three-dimensional space, with the resulting dynamics given as a flow along the intersection of the two manifolds determined by the conserved quantities. This approach is quite general, since it uses only CLs and their dependencies on the dynamic variable and does not need prior specification of the dynamic equations that are used.

This geometric approach is transferred to a continuous system in 2D with two CLs. The derivation is based on two-forms with vanishing integrals in a periodic domain. Similar to the finite dimensional case, the resulting dynamics is constrained by an orthogonality condition. The result is a Nambu bracket which appears in 2D hydrodynamics when the dynamic variable is the vorticity and the functional derivatives of the two CLs are the vorticity and the stream-function of the flow. This suggests an analogy in the geometry of the hydrodynamics equations and the equation for a Nambu triplet with finite degrees of freedom. The Nambu bracket holds its form also for the generalized Euler equation, which is defined by a fractional Poisson equation for the stream-function and an active scalar. Generalized Euler equations are interesting for the study of the formation of fronts and singularities [28]; conservative numerical algorithms based on the Nambu bracket [9] can thus be useful to avoid spurious accumulation or dissipation of energy and enstrophy.

Finally, a coupled system with two degrees of freedom is considered to demonstrate a further application of the method presented here. The model is analogous to Rayleigh–Bénard convection with vorticity and a temperature anomaly as dynamic variables. The approach is extended to construct a Nambu type II formulation using constitutive CLs. In the Rayleigh–Bénard example, the method yields two brackets: a first representing inviscid 2D hydrodynamics, and a second representing the coupling between hydrodynamics and thermodynamics. In the brackets the Hamiltonian is present in all terms and allows for a non-canonical Hamiltonian description of the system.

Acknowledgments

The authors would like to thank two anonymous reviewers for insightful comments and suggestions.

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