Regularity of solutions to the liquid crystals systems in $\mathbb{R}^2$ and $\mathbb{R}^3$

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Abstract
In this paper, we establish regularity and uniqueness for solutions to density dependent nematic liquid crystals systems. The results presented extend the regularity and uniqueness for constant density liquid crystals systems, obtained by Lin and Liu (1995 Commun. Pure Appl. Math. XLVIII 501–37).

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1. Introduction

The flows of nematic liquid crystals can be treated as slow moving particles where the fluid velocity and the alignment of the particles influence each other. The hydrodynamic theory of liquid crystals was established by Ericksen [7, 8] and Leslie [20, 21] in the 1960s. As Leslie points out in his 1968 paper: ‘liquid crystals are states of matter which are capable of flow, and in which the molecular arrangements give rise to a preferred direction’. In this paper, we consider the simplified model for the flow of nematic liquid crystals:

$$\begin{align*}
\rho_t + \nabla \cdot (\rho u) &= 0, \\
(\rho u)_t + \nabla \cdot (\rho u \otimes u) + \nabla p &= \Delta u - \nabla \cdot (\nabla d \otimes \nabla d) \\
d_t + u \cdot \nabla d &= \varphi - f(d) \\
\nabla \cdot u &= 0
\end{align*}$$

(1.1)

in $\Omega \times (0, T)$, where $\Omega$ is a domain in $\mathbb{R}^n$, $\rho : \Omega \times [0, T] \to \mathbb{R}$ is the fluid density, $p : \Omega \times [0, T] \to \mathbb{R}$ is the fluid pressure, $u : \Omega \times [0, T] \to \mathbb{R}^n$ is the fluid velocity and $d : \Omega \times [0, T] \to \mathbb{R}^n$ is the director field representing the alignment of the molecules, with $n = 2, 3$. The force term $\nabla d \otimes \nabla d$ in the equation of the conservation of momentum denotes the $3 \times 3$ matrix whose $ij$th entry is given by $\nabla_i d \cdot \nabla_j d$ for $1 \leq i, j \leq 3$. This force $\nabla d \otimes \nabla d$ is the stress tensor of the energy about the director field $d$, where the energy is given by

$$\frac{1}{2} \int_{\Omega} |\nabla d|^2 dx + \int_{\Omega} F(d)dx$$
and
\[ F(d) = \frac{1}{4\eta^2}(|d|^2 - 1)^2, \quad f(d) = \nabla F(d) = \frac{1}{\eta^2}(|d|^2 - 1)d. \]

In fact, \( F(d) \) is the penalty term of the Ginzburg–Landau approximation of the original free energy of the director field with unit length.

There is a vast literature on the hydrodynamic of the liquid crystal system. For background we list a few names, with no intention to be complete: [3–6, 9, 12–14, 22–24, 27]. Particularly, in [12, 27], the global weak existence of solutions to the flow of nematic liquid crystals was obtained for fluids with non-constant density. In light of the regularity results to the pure fluid system established in [2, 19] it is natural to ask if the regularity results in [22] can be extended to prove the regularity of the solutions for flows of nematic liquid crystals with non-constant fluid density.

In this paper, we extend the regularity and uniqueness results of Lin and Liu [22], which were obtained for density independent systems of nematic liquid crystals (LCD). The results obtained here establish regularity and uniqueness for solutions to density dependent LCD system.

Here we focus on the regularity of solutions to the flow of nematic liquid crystals satisfying the initial conditions:

\begin{align*}
\rho(x, 0) &= \rho_0(x), \quad 0 < M_1 \leq \rho_0(x) \leq M_2, \quad (1.2) \\
u(x, 0) &= u_0(x), \quad \nabla \cdot u_0 = 0, \quad u_0|_{\partial \Omega} = 0, \quad (1.3) \\
d(x, 0) &= d_0(x), \quad |d_0(x)| = 1, \quad (1.4)
\end{align*}

and the boundary conditions:

\begin{align*}
u(\cdot, t)|_{\partial \Omega} &= 0, \quad d(\cdot, t)|_{\partial \Omega} = d_0|_{\partial \Omega}. \quad (1.5)
\end{align*}

Existence of global weak solutions of (1.1), with the above specified data, has been established in [12, 27]. In fact, they have existence even without assuming the positive lower bound \( M_1 \). In [12, 27], to derive global weak solution, a viscosity term \( \epsilon \Delta \rho \) is added to regularize the first equation of system (1.1). This approach had been suggested in [25]. Our proof of regularity uses energy estimates introduced by Ladyzhenskaya on the approximate solutions. The added term in the second equation that results from the regularizing viscosity in the first equation in [25] contains the gradient of the fluid density. This term seems to create difficulties when it is used to establish the Ladyzhenskaya energy estimates for the approximate solution derived by the Galerkin method. Thus, in the appendix we sketch a proof of existence for the global weak solutions to system (1.1) without the introduction of the viscosity term for the density in the equation of the conservation of mass. In our case to obtain a classical solution we need to work with data that is more regular than the data used in [12, 27].

We obtain interior regularity with a relatively weak conditions on the initial data. For more regular data, we are able to obtain solutions which are regular up to the boundary. In the rest of the introduction we briefly describe our main results:

**Regularity in two dimensions.**

**Theorem 1.1.** Suppose that \( \Omega \) is a smooth bounded domain in \( \mathbb{R}^2 \). Let \( \rho_0, u_0 \) and \( d_0 \) satisfy (1.2)–(1.5). Suppose that \( \rho_0 \in C^1(\Omega), u_0 \in H^1(\Omega) \) and \( d_0 \in H^2(\Omega) \). Then, system (1.1) has a global classical solution \((\rho, u, d)\), that is, for all \( T > 0 \) and some \( \alpha \in (0, 1) \)

\[ u \in C^{1+\alpha/2,2}\alpha(0, T) \times \Omega, \]

\[ d \in C^{1+\alpha/2,2}\alpha(0, T) \times \Omega. \]
work in a rather different way. We keep the potentially small terms are based on those in [22], with interesting modifications. We use ideas of [22] making it too difficult. We first establish the Ladyzhenskaya energy estimate (2.19) and (2.20), similar to that in [22]. Then we apply the regularity result for transport equations in [2] to obtain the H"older continuity of the fluid density. Therefore theorem 1.1 follows from the Corollary 1.2.

Suppose in addition to the hypothesis in theorem 1.3 that Suppose that \( \rho \in C^1((0, T) \times \Omega) \) and \( d \in C^{1+\alpha/2,2+\alpha}(0, T) \times \Omega) \). Then system (1.1) has a classical solution \((\rho, u, d)\) in the time period \((0, T)\), for all \( T > 0 \). That is, for some \( \alpha \in (0, 1) \)

\[
\begin{align*}
\| u \|_{H^1(\Omega)}^2 + \| \nabla d \|_{H^1(\Omega)}^2 & \leq \epsilon_0, \\
\| \nabla p \|_{H^{1/2, 0}(\Omega)} & \leq \epsilon_0,
\end{align*}
\]

(1.6)

then system (1.1) has a classical solution \((\rho, u, d)\) in the time period \((0, T)\), for all \( T > 0 \). That is, for some \( \alpha \in (0, 1) \)

\[
\begin{align*}
\| u \|_{H^1(\Omega)} & \leq \epsilon_0, \\
\| \nabla p \|_{H^{1/2, 0}(\Omega)} & \leq \epsilon_0,
\end{align*}
\]

(1.7)

2. For general data, there exists a positive number \( \delta_0 = \delta_0(\rho_0, u_0, d_0) \) such that (1.7) holds in the interval \((0, T)\) for \( T \leq \delta_0 \).

**Corollary 1.4.** Suppose in addition to the hypothesis in theorem 1.3 that \( \rho_0 \in C^1(\Omega) \), \( u_0 \in C^{2+\alpha}(\Omega) \) and \( d_0 \in C^{2+\alpha}(\Omega) \), then the solution is regular up to the boundary for data small in the sense (1.6) or for large data and sufficiently short time.

The proof of the regularity of the solution to system (1.1) in dimension three takes the same approach as in dimension two but is much more complicated. First in contrast to the cases of dimension two, we only obtain the Ladyzhenskaya energy estimates when either the initial data are small in the sense as described in (1.6) or \( T \) is small. Our calculations and estimates are based on those in [22], with interesting modifications. We use ideas of [22] making it work in a rather different way. We keep the potentially small terms \( \| u \|_{L^2} \) and \( \| \nabla d \|_{L^2} \) instead of throwing them away. This gives a more unified way to derive the Ladyzhenskaya energy estimates in the cases:

- of small data
- for short time.
After having the Ladyzhenskaya energy estimates, in contrast to the two-dimensional case, we do not have the Hölder continuity for the fluid density. Instead we observe that we have small oscillations of the density over small balls in $\Omega \times [0, T]$ provided that either the initial data are small or for short time. This turns out to be enough to carry out the frozen coefficient method to improve the regularity of the fluid velocity. We refer the reader to [19] for a reference of the frozen coefficient method. We give the idea of the method in appendix B. Our key lemma on the oscillation of the fluid density is as follows:

**Lemma 1.5.** Suppose that $\Omega$ is a smooth bounded domain in $\mathbb{R}^3$. Let $\rho_0, u_0$ and $d_0$ satisfy (1.2)–(1.5). Assume that $\rho_0 \in C^1(\overline{\Omega})$, $u_0 \in H^1(\Omega)$ and $d_0 \in H^2(\Omega)$. Suppose that $(\rho, u, d)$ is a weak solution to system (1.1) in theorem A.1. Let $t_1 \in (0, T)$ and $p \in \Omega$, define

$$A(p, t_1) = (B_{r_0}(p) \cap \Omega) \times ([t_1 - r_0, t_1 + r_0] \cap [0, T]).$$

Then, for any $\epsilon > 0$, there exists $\epsilon_0 > 0$ and $r_0 > 0$ such that for $p \in \Omega$ and all $T > 0$,

$$\sup_{(q, t_2) \in A(p, t_1)} |\rho(q, t_2) - \rho(p, t_1)| \leq \epsilon,$$  

(1.8)

provided that either

$$\|u_0\|_{H^1(\Omega)}^2 + \|\nabla d_0\|_{H^1(\Omega)}^2 \leq \epsilon_0 \quad \text{or} \quad T \leq \delta_0.$$

**Remark 1.6.** The interior regularity in theorems 1.1 and 1.3 is obtained by bootstrapping argument.

To close this section, we state the uniqueness of solution in the following sense,

**Theorem 1.7.** Let $(\rho, u, d)$ be the solution to system (1.1) and (1.2)–(1.5) obtained in corollary 1.2 for two dimensions or in corollary 1.4 for three dimensions. Let $(\bar{\rho}, \bar{u}, \bar{d})$ be a weak solution to system (1.1) with (1.2)–(1.5) satisfying the following energy inequalities:

$$\int_{\Omega} |\bar{d}|^2 \, dx \leq \int_{\Omega} |\rho_0|^2 \, dx,$$

$$\int_{\Omega} \frac{1}{2} \bar{\rho}|\bar{u}|^2 + \frac{1}{2}|\nabla \bar{d}|^2 + F(\bar{d}) \, dx + \int_0^T \int_{\Omega} |\nabla \bar{u}|^2 + |\Delta \bar{d} - f(\bar{d})|^2 \, dx \, dt \leq \int_{\Omega} \frac{1}{2} \rho_0 |u_0|^2 + \frac{1}{2}|\nabla d_0|^2 + F(d_0) \, dx.$$  

(1.10)

Then $(\rho, u, d) \equiv (\bar{\rho}, \bar{u}, \bar{d})$.

**Remark 1.8.** Note that the weak solutions established in [12, 27] satisfy the inequalities recorded above. Hence these solutions coincide with solutions we obtained in corollary 1.4 due to the uniqueness theorem 1.7.

2. **Classic solutions to nematic liquid crystals systems in $\mathbb{R}^2$**

In this section, we use the Ladyzhenskaya energy method [18] to show that $u \in L^\infty([0, T], H^1(\Omega)) \cap L^2([0, T], H^2(\Omega))$ and $d \in L^\infty([0, T], H^2(\Omega)) \cap L^2([0, T], H^3(\Omega))$. Then we apply a result from [2] to obtain the Hölder continuity of the density $\rho$. With the continuity of the density $\rho$ we apply the so-called frozen coefficient method to obtain higher regularities for $\rho, p, u, d$ by bootstrapping. The proof of the Ladyzhenskaya energy inequality is similar to that in [22]. The key inequalities used often in this paper are the following Gagliardo–Nirenberg inequality (see [10]):
Lemma 2.1 (Gagliardo–Nirenberg). If $Ω$ is a smooth bounded domain in $\mathbb{R}^n$, then

$$\|u\|^2_{L^2(Ω)} \leq C\|u\|^2_{L^2(Ω)}\|\nabla u\|_{L^2(Ω)}^2 + \|u\|^2_{L^2(Ω)},$$

(2.11)

when $n = 2$ and

$$\|u\|^2_{L^2(Ω)} \leq C\|u\|^2_{L^2(Ω)}\|\nabla u\|_{L^2(Ω)} + \|u\|^2_{L^2(Ω)}^2,$$

(2.12)

when $n = 3$. Moreover, if $u|_Ω = 0$, then

$$\|u\|^2_{L^2(Ω)} \leq C\|u\|^2_{L^2(Ω)}\|\nabla u\|_{L^2(Ω)},$$

(2.13)

when $n = 2$ and

$$\|u\|^2_{L^2(Ω)} \leq C\|u\|^2_{L^2(Ω)}\|\nabla u\|_{L^2(Ω)}^3,$$

(2.14)

when $n = 3$.

2.1. The $L^\infty(Ω^1)$ and $L^2(Ω^2)$ estimates of the velocity

Our strategy is the same as in [22]. We first establish the desired bounds for the Galerkin approximating solutions $(ρ_m, u_m, d_m)$ in the sequence that one has from the Galerkin method when proving the existence (see section 5 of the appendix in this paper). By passing to the weak limit we then obtain the desired bounds for the weak solution $(ρ, u, d)$. First we set

$$\Phi_m^2(t) = \|\nabla u_m\|^2_{L^2} + \|\nabla d_m\|^2_{L^2},$$

(2.15)

Then to show that $u^m \in L^\infty(Ω^1) \cap L^2(Ω^2)$ and $d^m \in L^\infty(Ω^2) \cap L^2(Ω^2)$ we calculate $\frac{d}{dt}\Phi_m^2$. Namely,

$$\frac{1}{2} \frac{d}{dt}\Phi_m^2(t) = \int_Ω \nabla u_m \cdot \nabla u_m^m \, dx + \int_Ω \nabla d_m \cdot \nabla d_m^m \, dx$$

$$= -\int_Ω \rho^m |u_m^m|^2 \, dx - \int_Ω |\nabla d_m^m|^2 \, dx$$

$$+ \int_Ω \nabla \Delta d_m \cdot \nabla (u_m \cdot \nabla d_m^m) - \Delta d_m \cdot \Delta (f(d_m)) \, dx$$

$$+ \int_Ω -\rho^m (u_m \cdot \nabla u_m^m) u_m^m - u_m^m \nabla d_m^m \, dx$$

$$= -\int_Ω \rho^m |u_m^m|^2 \, dx - \int_Ω |\nabla d_m^m|^2 \, dx$$

$$+ I + II + III + IV,$$

here we used equation (A.53). We find

$$I \leq \varepsilon \|\nabla d_m^m\|^2_{L^2} + C\|\nabla u_m^m\|^2_{L^2} \|\nabla d_m^m\|^2_{L^2} + C\|u_m^m\|^2_{L^2} + C\|u_m^m\|^2_{L^2},$$

$$\leq \varepsilon \|\nabla u_m^m\|^2_{L^2} + 2\varepsilon\|\nabla d_m^m\|^2_{L^2} + C\Phi_m^2 + C\Phi_m^4 + C\Phi_m^2 + C\Phi_m,$$

by the Gagliardo–Nirenberg inequality, the basic energy estimate (A.59) and the fact that

$$\|\nabla d_m^m\|_{L^2} \leq C\|\Delta d_m^m\|_{L^2} + |d_m^m|_{L^2}.$$

And similarly,

$$II \leq C\Phi_m^2 + C,$$

$$III \leq \varepsilon \|\nabla u_m^m\|^2_{L^2} + \varepsilon\|u_m^m\|^2_{L^2} + C\Phi_m^4 + C\Phi_m^2,$$

$$IV \leq \varepsilon \|\nabla d_m^m\|^2_{L^2} + \varepsilon\|u_m^m\|^2_{L^2} + C\Phi_m^4 + C\Phi_m^2.$$
Moreover, from equation (A.53), we have
\[ \| \triangle u_m \|_{L^2}^2 \leq 2 M_2 \| u_m^t \|_{L^2}^2 + 2 \| \nabla \Delta d_m \|_{L^2}^2 + C \Phi_m^4 + C \Phi_m^3 + C \Phi_m^2 \] (2.16)
and
\[ M_1 \| u_m^t \|_{L^2}^2 \leq 2 \| \Delta u_m \|_{L^2}^2 + 2 \| \nabla \Delta d_m \|_{L^2}^2 + C \Phi_m^4 + C \Phi_m^3 + C \Phi_m^2. \] (2.17)

Therefore, we arrive at
\[ \frac{d}{dt} \Phi_1(t) + \| \nabla u_m \|_{L^2}^2 + \| \nabla \Delta d_m \|_{L^2}^2 \leq C \Phi_m(t) + C, \] (2.18)
which implies, as in [22], again in the light of the basic energy inequality (A.59),
\[ \Phi_1(t) \leq (\Phi_1(0)^2 + C) e^{CT+C} \int_0^T \| \nabla u_m \|_{L^2}^2 \, dt + \int_0^T \| \nabla \Delta d_m \|_{L^2}^2 \, dt \leq C. \] (2.19)

Hence we have obtained:

**Theorem 2.2.** Let \( \Omega \) be a smooth bounded domain in \( \mathbb{R}^2 \) and the initial data \( (\rho_0, u_0, d_0) \) satisfy the conditions of theorem 1.1. Suppose that \( \Phi_1(0)^2 = \| \nabla u_0 \|_{L^2}^2 + \| \Delta d_0 \|_{L^2}^2 < \infty \). Then there exists a constant \( C \) such that the approximating solutions \( (\rho_m, u_m, d_m) \) of the system (1.1) obtained in theorem A.1 satisfies
\[ \| \nabla u_m \|_{L^2}^2 + \| \nabla \Delta d_m \|_{L^2}^2 \leq e^{CT+C} \] (2.20)
for all \( t \in [0, T] \) and
\[ \int_0^T \| \nabla u_m \|_{L^2}^2 \, dt + \int_0^T \| \nabla \Delta d_m \|_{L^2}^2 \, dt \leq C. \] (2.21)

From the last theorem it follows that

**Corollary 2.3.** Under the same hypothesis of last theorem, there exists a solution \( (\rho, u, d) \) to (1.1) which satisfies the energy inequalities
\[ \| \nabla u \|_{L^2}^2 + \| \Delta d \|_{L^2}^2 \leq e^{CT+C} \] (2.22)
for all \( t \in [0, T] \) and
\[ \int_0^T \| \nabla u \|_{L^2}^2 \, dt + \int_0^T \| \nabla \Delta d \|_{L^2}^2 \, dt \leq C. \] (2.23)

**Proof.** It follows by extracting a subsequence of the Galerkin approximations \( (\rho_m, u_m, d_m) \) and passing to the limit.

### 2.2. Hölder continuity of the fluid density

Next we recall a regularity lemma for the transport equation from [2] to obtain Hölder continuity for the fluid density \( \rho \).

**Lemma 2.4 ([2]).** Suppose that \( u \in L^\infty([0, T], H^1(\Omega)) \cap L^2([0, T], H^2(\Omega)) \). And suppose that
\[ \rho_0 + u \cdot \nabla \rho = 0 \]
in \( \Omega \times (0, T) \). Assume that \( \rho(0) \in C^1(\Omega) \) and that \( \Omega \subset \mathbb{R}^2 \) is smooth and bounded. Then \( \rho \in C^\alpha(\Omega \times [0, T]) \) for some \( \alpha \in (0, 1) \) which depends only on the initial data, \( T \) and \( \Omega \).
2.3. Proof of theorem 1.1

The proof is more or less standard, particularly after the work in [2]. We sketch a proof here for completeness. Rewrite the third equation in (1.1) as
\[ d_t - \Delta d = -u \cdot \nabla d - f(d). \]  
(2.23)

It yields from the basic energy inequality (A.51) and estimate (2.19) that
\[ u \cdot \nabla d \in L^\infty(0, T; L^r(\Omega)), \quad \text{for any } r \in [1, \infty). \]

Then due to standard estimates of solutions to parabolic equations (see [1, 17]), from equation (2.23) we have
\[ d \in W^{1,r}(\Omega^2), \quad \text{for any } r, s \in [1, \infty), \]
which implies that
\[ d \in C^{1,1}([0, T] \times \Omega) \]  
(2.24)

for any \( \alpha \in (0, 1) \). Now we go to the second equation in (1.1) and use the above estimates for \( d \) to improve the estimate on \( u \) via the frozen coefficient method [19], after we have the Hölder continuity for the fluid density \( \rho \), as done in [2] to derive that
\[ u \in W^{1,p}(\Omega^2), \]
for some \( q > 1 \) and any \( p > 1 \). Therefore we have
\[ u \in C^{1/2,a}([0, T] \times \Omega). \]

Next going back to the third equation in (1.1), by the standard Hölder estimates for parabolic equations (see [17] theorem 5.1 in chapter VII) we have
\[ d \in C^{1+\frac{2}{2a}}(0, T) \times \Omega), \]
for some \( a \in (0, 1) \). Therefore we are able to go back to the second equation in (1.1), again via the frozen coefficient method [19], to derive that
\[ u \in C^{1+\frac{2}{2a}}((0, T) \times \Omega). \]

Finally, \( \rho \in C^1((0, T) \times \Omega) \) follows from the regularity of \( u \) and the regularity of the pressure \( p \) follows easily from the regularity of \((\rho, u, d)\) similarly as in [2]. □

Remark 2.5. By bootstrapping argument, we can obtain higher regularity.

Proof of corollary 1.2 follows by Krylov’s theorem 10.3.3 in [15], which for convenience of reader, we recall here [15].

Theorem 2.6. For any \( h \in C^{a/2,a}((0, T) \times \Omega) \) and boundary \( g \in C^{1+a/2,2a}((0, T) \times \Omega) \) there exists a unique function \( u \in C^{1+a/2,2a}((0, T) \times \Omega) \) satisfying the equation \( Lu - u_t = h \) in \( (0, T) \times \Omega \) and equal \( g \) on boundary of \((0, T) \times \Omega\).

We apply this to both the second and third equation in (1.1). Applying to the second equation, \( h = u \cdot \nabla u + f(d) \), \( g = d_0 \) and \( L = \Delta \). Applying to the third equation, \( h = u \cdot \nabla u + \nabla p + \nabla \cdot (\nabla d \otimes \nabla d) \), \( g = 0 \) and \( L = \Delta \). Proceeding as in the last theorem yields \( h \in C^{a/2,a}((0, T) \times \Omega) \) for both equations. On the boundary of \( \Omega \), \( u = 0 \), \( d = d_0 \) and \( d_0 \in C^{2a}(\Omega) \) by hypothesis. Hence the conclusion of the corollary follows.
3. Classical solution to nematic liquid crystals system in 3D

In this section, we consider the solutions of (1.1) for $\Omega \in \mathbb{R}^3$ a bounded domain. We establish regularity in two cases:
- global regularity with small initial data;
- short time regularity.

First we adopt the idea from [22] to derive the Ladyzhenskaya energy estimates. In contrast to the cases of dimension two, we will only obtain the Ladyzhenskaya energy estimates for the above two cases as in [22]. Our calculations and estimates are similar to those in [22], with interesting modifications. After having the Ladyzhenskaya energy estimates, unlike the case of dimension two, we will not have Hölder continuity for the fluid density right away. Instead, we observe that we can have the oscillation of the density over small balls in $\Omega \times [0,T]$ to be small, provided that either the initial data are small or we work for short time, which turns out to be enough to carry out the frozen coefficient method to improve the regularity of the fluid velocity.

3.1. Ladyzhenskaya energy estimates

Our derivation of the Ladyzhenskaya energy estimates in [22] in dimension three is rather an interesting modification of the original Ladyzhenskaya’s argument for the pure fluid systems. In [22] for the argument to work, it needs either the viscosity for the fluid to be very large or the time to be very short. We use the same idea, but, instead we assume the initial data to be small or the time to be short while the viscosity of the fluid is a fixed constant. For the convenience of the arguments in our context, without loss of generality we take the constant to be 1. Let us set as before:

$$\Phi^2_m(t) = \| \nabla u^m \|^2_{L^2} + \| \Delta d^m \|^2_{L^2}. \quad (3.25)$$

Then, as in the previous section, we will first derive the Ladyzhenskaya energy estimates for the Galerkin approximate solutions $(\rho^m, u^m, d^m)$ and pass to the weak limit to obtain the Ladyzhenskaya energy estimates for the weak solutions $(\rho, u, d)$ to system (1.1) as desired.

Again, using $u^m|_{\partial\Omega} = d^m|_{\partial\Omega} = 0$, and $\Delta d^m|_{\partial\Omega} = 0$, by integration by parts, it still follows that

$$\frac{1}{2} \frac{d}{dt} \Phi^2_m(t) = \int_{\Omega} \nabla u^m \cdot \nabla u^m \, dx + \int_{\Omega} \Delta d^m \cdot \Delta d^m \, dx = -\int_{\Omega} \rho^m |u^m|^2 \, dx - \int_{\Omega} |\nabla \Delta d^m|^2 \, dx$$

$$+ \int_{\Omega} \nabla \Delta d^m \cdot \nabla (u^m \cdot \nabla d^m) - \Delta d^m \cdot \Delta (f(d^m)) \, dx$$

$$+ \int_{\Omega} -\rho^m (u^m \cdot \nabla u^m) u^m - u^m \nabla d^m \Delta d^m \, dx$$

$$= -\int_{\Omega} \rho^m |u^m|^2 \, dx - \int_{\Omega} |\nabla \Delta d^m|^2 \, dx + I + II + III + IV.$$

We will proceed the same way as we did in dimension two except the Gagliardo–Nirenberg inequality is different in dimension three from that in dimension two. More importantly we will keep the terms $\| u^m \|_{L^2}$ and $\| \nabla d^m \|_{L^2}$ whenever necessary. We may derive

$$I \leq \epsilon \| \Delta u^m \|^2_{L^2} + \epsilon \| \nabla \Delta d^m \|^2_{L^2} + (\| u^m \|_{L^2} + \| \nabla d^m \|_{L^2})(C \Phi^8_m + C),$$

$$II \leq C \Phi^8_m + C \| \nabla d^m \|_{L^2},$$

$$III \leq \epsilon \| u^m \|^2_{L^2} + \epsilon \| \Delta u^m \|^2_{L^2} + C \| u^m \|^2_{L^2} \Phi^8_m + C \Phi^2_m.$$
and
\[ IV \leq \varepsilon \|u_m\|^2_{L^2} + \varepsilon \|\nabla \Delta u_m\|^2_{L^2} + C \|\nabla d_m\|^2_{L^2} + C \|\nabla d_m\|^2_{L^2}. \]

To relate \(\Delta u_m\) back to \(u_m\), from equation (A.53), we have that
\[ \|\Delta u_m\|^2_{L^2} \leq 2 M_1 \|u_m\|^2_{L^2} + 2 \|\nabla d_m\|^2_{L^2} + \|u_m\|^2_{L^2} + \|d_m\|^2_{L^2}. \]
and
\[ M_1 \|u_m\|^2_{L^2} \leq 2 \|\Delta u_m\|^2_{L^2} + 2 \|\nabla d_m\|^2_{L^2} + \|u_m\|^2_{L^2} + \|d_m\|^2_{L^2}. \]

Therefore we arrive at
\[ \|\Delta u_m\|^2_{L^2} + \|\nabla d_m\|^2_{L^2} + \frac{d}{dt} \Phi_m \leq C \Phi_m + \|u_m\|^2_{l^2} + \|\nabla d_m\|^2_{L^2}. \]

Set
\[ \Phi_m^2 = \Phi_m^2 + \|u_m\|^2_{L^2} + \|\nabla d_m\|^2_{L^2} \]
and observe that
\[ \frac{d}{dt} \Phi_m^2 \leq (C + C \|u_m\|^2_{L^2} + \|\nabla d_m\|^2_{L^2}) \Phi_m^2. \] (3.26)

or set
\[ \Phi_m^2 = \Phi_m^2 + \|u_m\|^2_{L^2} + \|\nabla d_m\|^2_{L^2} + 1 \]
we have
\[ \frac{d}{dt} \Phi_m^2 \leq C \Phi_m^2. \] (3.27)

It is clear from (3.27) one can prove the Ladyzhenskaya energy estimates when \(T\) is small. To obtain the Ladyzhenskaya energy estimates for small initial data we will use an idea similar to that in [22]. Suppose that
\[ \|u_0\|^2_{H^1} + \|d_0\|^2_{H^2} = \theta_0. \]
Recall that by the basic energy estimate we have
\[ \|u_m\|^2_{L^2} + \|\nabla d_m\|^2_{L^2} \leq \|u_0\|^2_{H^1} + \|d_0\|^2_{H^2} \leq \theta_0. \]

Then we claim that, if \(\theta_0\) is so small that
\[ C \theta_0 (4e^{C+1} \theta_0)^3 \leq 1, \] (3.28)
then
\[ \Phi_m^2 \leq 4e^{C+1} \theta_0, \]
for all \(t\). First we prove the claim for \(t \in [0, 1]\). Assume otherwise, there must be \(t_0 \in (0, 1)\) such that
\[ \Phi_m^2 (t_0) = 4e^{C+1} \theta_0 \] (3.29)
and
\[ \Phi_m^2 (t) \leq 4e^{C+1} \theta_0 \]
for all \(t \in (0, t_0]\). Therefore, from (3.26), by the choice of \(\theta_0\) in (3.28), we have
\[ \frac{d}{dt} \Phi_m^2 \leq (C + 1) \Phi_m^2 \]
for all \(t \in (0, \theta_0)\) and \(\Phi_m^2 (0) \leq 2\theta_0\), which implies that
\[ \Phi_m^2 (t_0) \leq e^{C+1} \Phi_m^2 (0) \leq 2e^{C+1} \theta_0 \]
and thus contradicts (3.29). For $t > 1$, we simply observe, as in [22], that the basic energy inequality (A.51)
\[
\int_{t-1}^{t} \Phi_m^2(t) \, dt \leq 2\theta_0
\]
implies that there is $t_0 \in (t-1, t)$ such that
\[
\Phi_m^2(t_0) \leq 2\theta_0.
\]
Then one may repeat the above argument to conclude that
\[
\Phi_m^2(t) \leq 4e^{C+1}\theta_0.
\]
As in the case of two dimension, passing to the limit the existence of weak solutions will follow from the uniform estimates we have obtained. This weak solution satisfies

**Theorem 3.1.** Suppose that $\Omega$ is a smooth bounded domain in $\mathbb{R}^3$. Let $\rho_0$, $u_0$ and $d_0$ satisfy (1.2)-(1.5). Assume that
\[
\|u_0\|_{H^1} + \|d_0\|_{H^2} < \infty.
\]
Let $(\rho, u, d)$ be a weak solution to system (1.1) with data $(\rho_0, u_0, d_0)$. There is $\epsilon_0 > 0$ such that if
\[
\|u_0\|_{H^1} + \|d_0\|_{H^2} \leq \epsilon_0,
\]
then
\[
\|\nabla u\|_{L^2}^2 + \|\Delta d\|_{L^2}^2 + \int_0^T (\|\Delta u\|_{L^2}^2 + \|\nabla \Delta d\|_{L^2}^2) \, dt \leq C(\|u_0\|_{H^1} + \|d_0\|_{H^2})
\]
(3.30)
holds for any positive $T$. For data with no smallness condition there is a $\delta_0$ depending on the data such that (3.30) holds for all $T \leq \delta_0$.

3.2. Oscillation of the fluid density

In this subsection, we show that the oscillation of the density $\rho$ over sufficiently small space time balls can be made as small as necessary. This estimate follows by the estimate on $u$ from the Ladyzhenskaya energy estimates obtained in the previous subsection. For convenience of the readers we restate lemma 1.5.

**Lemma 3.2.** Suppose that $\Omega$ is a smooth bounded domain in $\mathbb{R}^3$. Let $\rho_0$, $u_0$ and $d_0$ satisfy (1.2)-(1.5). Assume that $\rho_0 \in C^1(\bar{\Omega})$, $u_0 \in H^1(\Omega)$ and $d_0 \in H^2(\Omega)$. Suppose that $(\rho, u, d)$ is a weak solution to system (1.1) constructed in theorem A.1 (see the appendix). Let $t_1 \in (0, T)$ and $p \in \Omega$, define
\[
A_{(p,t_1)} = (B_{r_0}(p) \cap \Omega) \times ([t_1 - r_0, t_1 + r_0] \cap [0, T]).
\]
Then, for any $\epsilon > 0$, there exists $\epsilon_0 > 0$ and $r_0 > 0$ such that for $p \in \Omega$ and all $T > 0$,
\[
\sup_{(q,t_2) \in A_{(p,t_1)}} |\rho(q,t_2) - \rho(p,t_1)| \leq \epsilon,
\]
provided that either
\[
\|u_0\|_{H^1(\Omega)}^2 + \|\nabla d_0\|_{H^2(\Omega)}^2 \leq \epsilon_0 \quad \text{or} \quad T \leq \delta_0.
\]
For reasonably regular velocity we may solve (3.31) by the method of characteristics. Due to Osgood theorem \[29\], since \( u \in H^2 \) for almost all \( t \in [0, T] \) and in light of the Ladyzhenskaya energy estimates in theorem 3.1, there is a unique solution to the Cauchy problem corresponding to (3.31) by finding trajectories of the liquid particles

\[
\frac{dy}{d\tau} = u(y, \tau), \quad y|_{\tau=t} = x; \quad x \in \Omega, \quad t \in (0, T)
\]

and defining

\[
\rho(x, t) = \rho_0(y(0, x, t)).
\]

**Step 1.** Fix a time \( t \in [0, T] \). Let \( x_1 \) and \( x_2 \) be two arbitrary points from \( \Omega \) satisfying \(|x_1 - x_2| \leq d < 1\). For any \( \tau \in (0, t) \), assume

\[
y_1 = y(\tau, x_1, t), \quad y_2 = y(\tau, x_2, t),
\]

then the difference \( z(\tau) = y_1 - y_2 \) is the solution to the Cauchy problem

\[
\frac{dz}{d\tau} = u(y_1, \tau) - u(y_2, \tau), \quad z|_{\tau=t} = x_1 - x_2.
\]

For \( 0 \leq \alpha \leq 1/2 \), by a standard Sobolev embedding theorem in \( \Omega \), we have

\[
\frac{d|z|}{d\tau} \leq C\|u(\tau)\|_{H^2(\Omega)}|z|^\alpha, \quad \tau \in (0, t).
\]

Integrating from \( \tau \) to \( t \),

\[
|z|^{1-\alpha} \leq |x_1 - x_2|^{1-\alpha} + C T^{1/2} \|u\|_{L^2(0, T; H^2(\Omega))}.
\]

As a consequence of theorem 3.1, we know that \(|z|\) is as small as needed provided that \(|x_1 - x_2|\) and \(\|u_0\|_{H^1} + \|d_0\|_{H^2}\) are small or \( T \) is small. Therefore

\[
|\rho(x_1, t) - \rho(x_2, t)| = |\rho_0(y(0, x_1, t)) - \rho_0(y(0, x_2, t))| \leq C|z|
\]

is as small as one wants provided that \(|x_1 - x_2|\) and \(\|u_0\|_{H^1} + \|d_0\|_{H^2}\) are small or \( T \) is small.

**Step 2.** Fix a point \( x \in \Omega \). Let \( t_1, t_2 \in [0, T] \) arbitrary, let

\[
y_1 = y(\tau, x, t_1), \quad y_2 = y(\tau, x, t_2).
\]

Assume that \( x' = y_2|_{\tau=t_1} \). Then due to uniqueness, the integral curve \( y_2(\tau) \) can be considered as a solution to the Cauchy problem

\[
\frac{dy_2}{d\tau} = u(y_2, \tau), \quad y_2|_{\tau=t_1} = x'
\]

with initial data at \( \tau = t_1 \). Hence, the difference \( z(\tau) = y_1 - y_2 \) is the solution of the Cauchy problem

\[
\frac{dz}{d\tau} = u(y_1, \tau) - u(y_2, \tau), \quad z|_{\tau=t_1} = x - x'.
\]

By the definition of \( x' \), we have

\[
|z|^{1-\alpha} \leq |x_1 - x_2|^{1-\alpha} + C \frac{\|u\|_{H^2(\Omega)}}{\tau_1 - \tau_2}.
\]

Therefore, again due to a standard Sobolev embedding theorem,

\[
|\rho(x) - \rho(x')| \leq \int_{t_1}^{t_2} \|u(s, x, t_2)\| ds \leq C \int_{t_1}^{t_2} \|u\|_{H^2(\Omega)} ds \leq C \|u\|_{L^2(0, T; H^2(\Omega))} |t_1 - t_2|^{1/2}.
\]
By step 1, we conclude that
\[
|\rho(x, t_1) - \rho(x, t_2)| = |\rho_0(y(0, x, t_1)) - \rho_0(y(0, x, t_2))| = |\rho_0(y(0, x, t_1)) - \rho_0(y(0, x', t_1))|
\]
is as small as needed provided that \(|t_1 - t_2|\) and \(\|u_0\|_{H^1} + \|d_0\|_{H^2}\) are small or \(T\) is small. This completes the proof of the lemma.

3.3. Proof of theorem 1.3

In this subsection, we complete the proof of theorem 1.3. This is done by combining theorem 3.1, lemma 1.5 from the previous subsections, the frozen coefficient technique applied to \(L^q(L^q)\) estimates, Hölder estimates and a bootstrapping argument between the three equations of system (1.1).

In the appendix we briefly describe the frozen coefficient method. For simplicity, we show how the method works for the density dependent NSE and obtain the estimate for \(L^q\) space with \(q > \sqrt{3}\). We apply now this method to our approximating solutions \((\rho^m, u^m, d^m)\). These solutions for each \(m\) satisfy the conclusion of theorem 1.3. We now show that the estimates are uniformly in \(m\) applying the frozen coefficient method, in which case we let \(q = 2\). That allows us to pass to the limit \((\rho, u, d)\) and obtain (1.7) for weak solutions. We now show briefly the steps to yield the necessary uniform bound.

Here to simplify the notation we denote the approximating solutions by \((\rho, u, d)\). We notice first that since
\[
u \in L^\infty(0, T; L^6(\Omega)), \quad \nabla d \in L^\infty(0, T; L^6(\Omega)),
\]
we have
\[
u \cdot \nabla d \in L^\infty(0, T; L^3(\Omega)).
\]
By standard parabolic estimates on the third equation in (1.1) (see [1, 17]), we have
\[
d \in W^{1, p}(W^{2, 3}),
\]
for all \(1 < p < \infty\), which implies that \(\nabla d \in L^\infty(0, T; L^q(\Omega))\) for any \(q \in (1, \infty)\). Thus, we have
\[
u \cdot \nabla d \in L^\infty(0, T; L^q(\Omega)), \quad \forall q \in (1, 6).
\]
Applying the same standard parabolic estimate on the third equation in (1.1) yields
\[
d \in W^{1, p}(W^{2, q}), \quad \forall p \in (1, \infty) \quad \text{and} \quad q \in (1, 6),
\]
which implies that \(d \in C^{\alpha/2, 1+\alpha}([0, T] \times \bar{\Omega})\) for some \(\alpha \in (0, 1)\) and
\[
\nabla d \Delta d \in L^\infty(0, T; L^q(\Omega)), \quad \forall q \in (1, 6).
\]
In the second equation of (1.1), the estimates for the conservation of momentum with constant density can be extended to the non-constant density cases when lemma 1.5 is available. This is done via the frozen coefficient method.

We know that
\[
u \cdot \nabla u \in L^\infty(0, T; L^2(\Omega)).
\]
Now we apply the frozen coefficient method using the oscillation estimates for the density (lemma 1.5) to yield
\[
u \in W^{1, p}(W^{2, 3/2}), \quad \forall p \in (1, \infty)
\]
Thus \( u \in L^\infty(0, T; W^{1,3}(\Omega)) \) and \( u \cdot \nabla u \in L^\infty(0, T; L^2(\Omega)) \). Repeating the above argument yields
\[
\forall p \in (1, \infty), \quad u \in W^{1,p}(W^{2,3}),
\]
from where it follows that \( u \in C^\alpha(\Omega \times [0, T]) \).

Back to the third equation in (1.1), we conclude that
\[
d \in C^{1+\alpha, 2+\alpha}((0, T) \times \Omega)
\]
for some \( \alpha \in (0, 1) \) via the standard Hölder estimates for parabolic equations (see [17, chapter VII]). From here the argument for the pure fluid systems works with no further significant modifications. This completes the proof of theorem 1.3.

**Proof of corollary 1.4.** Follows by Krylov’s theorem [16] just as in the case of two dimensions.

### 4. Uniqueness of solution

In this section we establish theorem 1.7. For the LCD system with constant density, Lin and Liu [22] proved that the solution \((u, d)\) is unique provided \( u \in L^\infty(0, T; H^1) \) and \( d \in L^\infty(0, T; H^2) \). The idea is to calculate the energy law satisfied by the difference of two solutions and establish a Gronwall’s inequality. In our case, to calculate the energy law of the difference of two solutions it has some extra terms involving the density. Hence the estimates are more involved requiring additional bounds on the strong solution \((\rho, u, d)\) to yield a Gronwall’s inequality. In 2D, we need
\[
\nabla \rho, \nabla u \in L^\infty((0, T) \times \Omega), \quad u, u \cdot \nabla u \in L^\infty(0, T; L^q(\Omega)), \quad q > 2. \tag{4.36}
\]

In 3D, we need
\[
\nabla \rho, \nabla u \in L^\infty((0, T) \times \Omega), \quad u, u \cdot \nabla u \in L^\infty(0, T; L^3(\Omega)). \tag{4.37}
\]

With the assumption on data, \( \rho_0 \in C^1(\bar{\Omega}), u_0 \in C^{2+\alpha}(\bar{\Omega}) \) and \( d_0 \in C^{2+\alpha}(\bar{\Omega}) \), the solution \((\rho, u, d)\) from corollary 1.2 or corollary 1.4 satisfies (4.36) or (4.37), respectively.

**Proof of theorem 1.7.** First recall that the solution \((\rho, u, d)\) from theorems 1.1 and 1.3 satisfies energy equality:
\[
\int_\Omega \frac{1}{2} |u|^2 + \frac{1}{2} |\nabla d|^2 + F(d) \, dx + \int_0^T \int_\Omega |\nabla u|^2 + |\Delta d - f(d)|^2 \, dx \, dt \\
= \int_\Omega \frac{1}{2} \rho_0 |u_0|^2 + \frac{1}{2} |\nabla d_0|^2 + F(d_0) \, dx. \tag{4.38}
\]
The density \( \rho \) is the strong solution of the transport equation, hence it satisfies that
\[
\int_\Omega \rho^2 \, dx = \int_\Omega \rho_0^2 \, dx.
\]

On the other hand side, \( \tilde{\rho} \) is a weak solution of the transport equation and \( M_1 \leq \tilde{\rho} \leq M_2 \). We have by hypothesis that
\[
\int_\Omega \tilde{\rho}^2 \, dx \leq \int_\Omega \rho_0^2 \, dx. \tag{4.39}
\]
Thus,
\[
\frac{1}{2} \int_\Omega |\rho - \tilde{\rho}|^2 \, dx = \frac{1}{2} \int_\Omega \rho^2 \, dx + \frac{1}{2} \int_\Omega \tilde{\rho}^2 \, dx - \int_\Omega \rho \tilde{\rho} \, dx
\]
\[
\leq \int_\Omega \rho_0^2 \, dx - \int_\Omega \rho \tilde{\rho} \, dx. \tag{4.40}
\]
Since $\rho \in C^1([0, T] \times \tilde{\Omega})$, we can take $\rho$ as a test function. Thus, multiplying

$$\tilde{\rho}_t + \tilde{u} \cdot \nabla \tilde{\rho} = 0$$

by $\rho$ and integrating by parts yields

$$\int_{\Omega} \rho_0^2 \, dx - \int_{\Omega} \rho \tilde{\rho} \, dx = - \int_0^t \int_{\Omega} \tilde{\rho} \rho_t \, dx \, dt - \int_0^t \int_{\Omega} (\tilde{u} \cdot \nabla \rho) \tilde{\rho} \, dx \, dt$$

$$= \int_0^t \int_{\Omega} (u \cdot \nabla \rho) \rho_t \, dx \, dt - \int_0^t \int_{\Omega} (\tilde{u} \cdot \nabla \rho) \tilde{\rho} \, dx \, dt. \quad (4.41)$$

Here we used again that $\rho$ is a classical solution of the transport equation. Substituting equality (4.41) in (4.40) gives

$$\frac{1}{2} \int_{\Omega} |\rho - \tilde{\rho}|^2 \, dx \leq \int_0^t \int_{\Omega} \tilde{\rho} (u - \tilde{u}) \nabla \rho \, dx \, dt$$

$$= \int_0^t \int_{\Omega} (\rho - \tilde{\rho}) (u - \tilde{u}) \nabla \rho \, dx \, dt. \quad (4.42)$$

Next, calculate the following terms:

$$\frac{1}{2} \int_{\Omega} \tilde{\rho} |u - \tilde{u}|^2 \, dx + \frac{1}{2} \int_{\Omega} |\nabla d - \nabla \tilde{d}|^2 \, dx$$

$$\leq - \int_0^t \int_{\Omega} |\Delta u - \Delta \tilde{u}|^2 \, dx \, dt - \int_0^t \int_{\Omega} |\Delta d - \Delta \tilde{d}|^2 \, dx \, dt$$

$$+ \frac{1}{2} \int_{\Omega} (\tilde{\rho} - \rho) |u|^2 \, dx - \int_{\Omega} \tilde{\rho} u \otimes \tilde{u} - \rho_0 |u_0|^2 \, dx - \int_{\Omega} \nabla d \otimes \nabla \tilde{d} - |\nabla d_0|^2 \, dx$$

$$- \int_{\Omega} F(d) \, dx - \int_{\Omega} F(\tilde{d}) \, dx + 2 \int_{\Omega} F(d_0) \, dx - \int_0^t \int_{\Omega} |f(d)|^2 \, dx \, dt$$

$$- \int_{\Omega} \int_{\Omega} \int_{\Omega} \nabla u \cdot \nabla \tilde{u} \, dx \, dt - 2 \int_{\Omega} \int_{\Omega} \int_{\Omega} \Delta u \cdot \Delta \tilde{d} \, dx \, dt$$

$$+ 2 \int_{\Omega} \int_{\Omega} \Delta d \cdot f(d) \, dx \, dt + 2 \int_{\Omega} \int_{\Omega} \Delta \tilde{d} \cdot f(\tilde{d}) \, dx \, dt. \quad (4.43)$$

Since $u, d \in C^{1+\epsilon/2, 2+\epsilon} ([0, T] \times \tilde{\Omega})$, we can take $u, d$ as test functions for the weak solution $\tilde{u}, \tilde{d}$. Thus, it follows that

$$\int_{\Omega} \tilde{\rho} u \otimes \tilde{u} - \rho_0 |u_0|^2 \, dx = \int_0^t \int_{\Omega} \tilde{\rho} \tilde{u} \, dx \, dt + \int_0^t \int_{\Omega} \tilde{\rho} (\tilde{u} \cdot \nabla u) \, dx \, dt$$

$$- \int_0^t \int_{\Omega} \tilde{\rho} (\tilde{u} \cdot \nabla u) \, dx \, dt - \int_0^t \int_{\Omega} \tilde{\rho} (\tilde{u} \cdot \nabla u) \, dx \, dt. \quad (4.44)$$
Indeed, formally, to obtain (4.44), we multiply equation
\[
(\bar{\rho} \ddot{u}) + \nabla (\bar{\rho} \nabla \ddot{u}) + \nabla \bar{\rho} = \Delta \ddot{u} - \nabla \cdot (\nabla \bar{d} \otimes \nabla \bar{d})
\]
by \(u\) and integrate by parts. To obtain (4.45), we multiply equation
\[
\dot{d} + \bar{u} \cdot \nabla \bar{d} = \Delta \bar{d} - f(\bar{d})
\]
by \(\Delta d\) and integrate by parts.

Substitute (4.44) and (4.45) in (4.43). Add (4.42) combined with the equalities in equations (1.1), yields
\[
\frac{1}{2} \int_{\Omega} |\rho - \tilde{\rho}|^2 \, dx + \frac{1}{2} \int_{\Omega} \tilde{\rho} |u - \bar{u}|^2 \, dx + \frac{1}{2} \int_{\Omega} |\nabla d - \bar{d}|^2 \, dx
\leq - \int_{0}^{T} \int_{\Omega} |\nabla u - \nabla \bar{u}|^2 \, dx \, dt - \int_{0}^{T} \int_{\Omega} |\Delta d - \Delta \bar{d}|^2 \, dx \, dt
+ \int_{0}^{T} \int_{\Omega} \tilde{\rho} |(\tilde{\rho} - \rho)(u - \bar{u})\nabla \rho| \, dx \, dt - \int_{0}^{T} \int_{\Omega} \tilde{\rho} \nabla u |u - \bar{u}|^2 \, dx \, dt
+ \int_{0}^{T} \int_{\Omega} \tilde{\rho} |(\tilde{\rho} - \rho)(u - \bar{u})(u + u \cdot \nabla u)| \, dx \, dt
+ \int_{0}^{T} \int_{\Omega} u |(\nabla d - \nabla \bar{d})(\Delta d - \Delta \bar{d})| \, dx \, dt
- \int_{0}^{T} \int_{\Omega} (u - \bar{u}) (\nabla d - \nabla \bar{d}) |\Delta d\Delta \bar{d}| \, dx \, dt + \int_{0}^{T} \int_{\Omega} (\Delta d - \Delta \bar{d})(f(d) - f(\bar{d})) \, dx \, dt.
\]  
(4.46)

Recall that the regular solution \((\rho, u, \bar{d})\) satisfies (4.36) in 2D and (4.37) in 3D. By Hölder and Gagliardo–Nirenberg inequalities on the right-hand side of (4.46), it follows that
\[
\frac{1}{2} \int_{\Omega} |\rho(t) - \tilde{\rho}(t)|^2 \, dx + \tilde{\rho}(t) |u(t) - \bar{u}(t)|^2 + |\nabla d(t) - \nabla \bar{d}(t)|^2 \, dx
\leq C \int_{0}^{T} \int_{\Omega} |\rho - \tilde{\rho}|^2 + |u - \bar{u}|^2 + |\nabla d - \bar{d}|^2 \, dx \, dt.
\]  
(4.47)

To handle the last integral in (4.46), we used the fact that \(|\bar{d}|, |\Delta \bar{d}| \leq 1\) and hence \(|f(d) - f(\bar{d})| \leq C|d - \bar{d}|\) by the definition of \(f(d)\). Thus,
\[
\int_{0}^{T} \int_{\Omega} |f(d) - f(\bar{d})|^2 \, dx \, dt \leq C \int_{0}^{T} \int_{\Omega} |d - \bar{d}|^2 \, dx \, dt \leq C \int_{0}^{T} \int_{\Omega} |\nabla d - \nabla \bar{d}|^2 \, dx \, dt
\]
where the constant \(C\) depends on space domain \(\Omega\) not on time \(T\), and \(C\) depends on the dimension of the space.

Using the lower bound of \(\tilde{\rho} \geq M_{1} > 0\), and Gronwall’s inequality to (4.47) yields
\[
\frac{1}{2} \int_{\Omega} |\rho(0) - \tilde{\rho}(0)|^2 + \tilde{\rho}(0) |u(0) - \bar{u}(0)|^2 + |\nabla d(0) - \nabla \bar{d}(0)|^2 \, dx \, dt
\leq \int_{\Omega} |\rho(0) - \tilde{\rho}(0)|^2 + \tilde{\rho}(0) |u(0) - \bar{u}(0)|^2 + |\nabla d(0) - \nabla \bar{d}(0)|^2 \, dx \, dt
\]
\[= 0\]
for all \( t > 0 \) which implies
\[
\tilde{\rho} - \rho = \tilde{u} - u = \tilde{d} - d = 0.
\]
This completes the proof of theorem 1.7.

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Appendix A. Existence of weak solutions

In this appendix, we sketch an existence theorem for Galerkin approximations. As mentioned in the introduction, the existence of global weak solutions to the flow of nematic liquid crystals has been established in [27] and in [12] for non-constant fluid density. Unfortunately the Ladyzhenskaya energy estimates do not seem to work for the Galerkin approximate solutions constructed in [27] and in [12]. The Galerkin approximate solutions constructed here will possess the Ladyzhenskaya energy estimates. When the initial fluid density has a positive lower bound, we are able to derive estimates on \( u_m \) and \( d_m \) so that we can employ the compactness lemma of Lions–Aubin. Since the Galerkin method has been widely used for fluid systems as well as on the system of liquid crystals we will be brief (see [2, 12, 22, 27]).

A.1. Galerkin approximate solutions

We construct a sequence of Galerkin approximating solutions that are uniformly bounded. These are the solutions used in sections 2 and 3. The bounds obtained there through the Ladyzhenskaya method yield a subsequence that will converge to the classical solution.

Let us first state the existence theorem for global weak solutions:

**Theorem A.1.** Assume that \( u_0 \in L^2(\Omega) \) and \( d_0 \in H^1(\Omega) \) with \( d_0|_{\partial\Omega} \in H^{3/2}(\Omega) \). System (1.1) with initial boundary conditions (1.2)–(1.5) has a weak solution \( (\rho^m, u^m, d^m) \) for each \( m = 1, 2, 3, \ldots \) satisfying, for all \( T \in (0, \infty) \),
\[
0 < M_1 \leq \rho^m \leq M_2,
\]
\[
u^m \in L^2(0, T; H^1_0(\Omega)) \cap L^\infty(0, T; L^2(\Omega)),
\]
\[
d^m \in L^2(0, T; H^2(\Omega)) \cap L^\infty(0, T; H^1(\Omega)),
\]
\[|d^m| \leq 1,
\]
and the energy inequality
\[
\int_{\Omega} (|\Delta d^m - f(d^m)|^2 + |\nabla u^m|^2) \, dx + \frac{d}{dt} \int_{\Omega} \left( \frac{1}{2} \rho |u^m|^2 + \frac{1}{2} |\nabla d^m|^2 + F(d^m) \right) \, dx \leq 0.
\]

**Proof.** Let
\[
\mathcal{H}(\Omega) = \text{closure of } \{ f \in C_0^\infty(\Omega, \mathbb{R}^3) : \nabla \cdot f = 0 \} \text{ in } L^2(\Omega, \mathbb{R}^3)
\]
and \( \{ \phi_i \}_{i=1}^\infty \) be an orthonormal basis of \( \mathcal{H} \) and satisfying
\[
-\Delta \phi_i + \nabla P = \lambda_i \phi_i \text{ in } \Omega,
\]
\[
\phi_i = 0 \text{ on } \partial \Omega
\]
for \( i = 1, 2, \ldots \). Here \( 0 < \lambda_1 \leq \lambda_2 \leq \cdots \leq \lambda_n \leq \cdots \) with \( \lambda_i \to \infty \). In other words, we choose an orthonormal basis of \( \mathcal{H} \) which consists of the eigenfunctions of Stokes operator on \( \Omega \) with vanishing Dirichlet boundary condition (see [31]). Let
\[
P_m : \mathcal{H} \to \mathcal{H}_m = \text{span}\{\phi_1, \ldots, \phi_m\}
\]
be the orthonormal projection. We seek approximate solutions \((\rho^m, u^m, d^m)\) with \( u^m \in \mathcal{H}_m \) satisfy the following equations:
\[
\rho^m_t + u^m \cdot \nabla \rho^m = 0, \quad \rho^m(x, 0) = \rho_0(x),
\]
\[
P_m \left( \rho^m \frac{\partial}{\partial t} u^m \right) = P_m (\Delta u^m - \rho^m u^m \cdot \nabla u^m - \nabla \cdot (\nabla d^m \otimes \nabla d^m)),
\]
\[
d^m_t + u^m \cdot \nabla d^m = \Delta d^m - f(d^m),
\]
\[
u m(x, 0) = P_m \nu_0(x), \quad d^m(x, 0) = d_0(x), \quad d^m(x, t) \mid_{\partial \Omega} = d_0(x) \mid_{\partial \Omega}.
\]
Let
\[
u m(x, t) = \sum_{i=1}^m g_i^m(t) \nu_i(x),
\]
with \( g_i^m(t) \in C^1[0, T] \). Hence (A.53) is equivalent to the following system of ordinary differential equations:
\[
\sum_{i=1}^m A_i^{m/j}(t) \frac{d}{dt} g_i^m(t) = - \sum_{i,k} B_{i,k}^{m/j}(t) g_i^m(t) g_k^m(t) - \sum_{i=1}^m C_i^{m/j}(t) g_i^m(t) + D_i^{m/j}(t),
\]
for \( j = 1, 2, \ldots, m \),
where
\[
A_i^{m/j}(t) = \int_\Omega \rho^m(t) \nu_i(x) \nu_j(x) dx,
\]
\[
B_{i,k}^{m/j}(t) = \int_\Omega \rho^m(t) \nu_i(x) \cdot \nabla \nu_k(x) \nu_j(x) dx,
\]
\[
C_i^{m/j}(t) = \int_\Omega \nabla \nu_i(x) \cdot \nabla \nu_j(x) dx,
\]
\[
D_i^{m/j}(t) = \int_\Omega \sum_{k,l} \left( \frac{\partial}{\partial x_k} d^m \cdot \frac{\partial}{\partial x_l} d^m \right) \frac{\partial}{\partial x_l} \nu_i^j(x) dx.
\]
Here \( \nu_i^j(x) \) is the \( k \)th component of the vector \( \nu_j(x) \). And
\[
u m(\cdot, 0) = \sum_{i=1}^m g_i^m(0) \nu_i(x), \quad \text{where } g_i^m(0) = \int_\Omega \nu_0(x) \nu_i(x) dx.
\]

To complete the proof, we need the following lemma.

**Lemma A.2.** There exists a weak solution \((\rho^m, u^m, d^m)\) to the problem (A.52)–(A.55) in \( Q_T = \Omega \times [0, T] \), for any \( T \in (0, \infty) \), satisfying
\[
M_1 \leq \rho^m \leq M_2,
\]
\[
u m \in L^\infty(0, T; L^2(\Omega)) \cap L^2(0, T; H^1),
\]
\[
d^m \in L^\infty(0, T; H^1) \cap L^2(0, T; H^2), \quad |d^m| \leq 1.
\]
Moreover, \((\rho^m, u^m, d^m)\) is smooth in the interior of \( Q_T \) and satisfies the energy equality,
\[
\int_\Omega |\nabla u^m|^2 + |\Delta d^m - f(d^m)|^2 dx + \frac{d}{dt} \int_\Omega \left( \frac{1}{2} |\rho^m|^2 + |\nabla d^m|^2 + F(d^m) \right) dx = 0.
\]
The proof of this lemma is based on an application of the Leray–Schauder fixed point theorem. Let $v^m = \sum_{i=1}^{m} h_i^m \phi_i \in C^1(0, T; \mathcal{H}_m)$. For each $m$ let $\rho^m$ be a solution to

$$\rho + v^m \cdot \nabla \rho = 0 \quad (A.60)$$

with initial condition $\rho(\cdot, 0) = \rho_0$. Let $d^m$ be a solution to

$$d_t + v^m \cdot \nabla d = \Delta d - f(d)$$

with initial condition $d(\cdot, 0) = d_0$ and boundary condition $d(x, t) = d_0(x)$. The reason the transport equation (A.60) is solvable for $v^m \in C^1(0, T; \mathcal{H}_m)$ is due to the regularity of the eigenfunctions of the Stokes operators (see [18, 31]). Let $u^m = \sum_{i=1}^{m} g_i^m \phi_i \in C^1(0, T; \mathcal{H}_m)$ be the solution of the system of linear equations

$$\sum_{i=1}^{m} A^{mij}_i(t) \frac{d}{dt} g_i^m(t) = -\sum_{i,k} B^{mij}_i(t) h_i^m(t) g_k^m(t) - \sum_{i=1}^{m} C^j_i g_i^m(t) + D^{mij}_i(t).$$

This system of linear equations is solvable because the eigenvalues of matrix of the coefficients $A^{mij}_i(t)$ are bounded from below, since

$$A^{mij}_i \gamma_i \gamma_j \geq M_1 \int_{\Omega} |\psi|^2 \, dx \quad \text{where} \quad \psi = \sum_{i=1}^{m} \gamma_i \phi_i. \quad (A.61)$$

Thus we constructed a mapping $M$ with $M(v^m) = u^m$. The energy estimate (A.59) is the key which allows one to apply Leray–Schauder fixed point theorem for $M$.

Remark A.3. We know that from the estimates obtained in sections 2 and 3, we can pass to the limit and conclude that there exists $(\rho, u, d)$ such that, taking subsequence if necessary,

$$\rho^m \rightharpoonup \rho \text{ in } L^p(\Omega \times [0, T]) \text{ for any } p \in (1, \infty),$$

$$u^m \rightharpoonup u \text{ weakly in } C(0, T; H^1) \text{ and strongly in } C(0, T; L^2),$$

$$d^m \rightharpoonup d \text{ weakly in } L^2(0, T; H^2) \text{ and strongly in } L^2(0, T; H^1).$$

It follows easily from the above convergences that indeed $(\rho, u, d)$ is a weak solution to system (1.1).

Appendix B. The frozen coefficient method

For completeness, in this section, we recall an application of the frozen coefficient method by considering the following problem (for more detail see [19])

$$\rho v_t - \Delta v + \rho v \cdot \nabla v + \nabla p = f,$$

$$\nabla \cdot v = 0, \quad v(0) = 0, \quad v|_{\partial \Omega} = 0, \quad (B.62)$$

in the domain $\Omega \times (0, T)$. Here $\rho$ is a given function in $\Omega \times (0, T)$ satisfying

$$0 < M_1 \leq \rho \leq M_2, \quad (B.63)$$

$$|\nabla \rho| \leq M_3, \quad |\rho_t| \leq M_4 \quad (B.64)$$

(the derivatives of $\rho$ may be the generalized ones). And $f$ is a given function in $L^q(\Omega \times (0, T))$ for $q > \sqrt{3}$. 


The frozen coefficient method is now used to prove the following lemma,

**Lemma B.1.** If \( v \in W^{1,q}(W^{2,q}(\Omega)) \) and \( \nabla p \in L^q(\Omega \times (0,T)) \) is a solution of problem (B.62), then for an appropriate constant a depending on \( q, |\Omega|, M_1, M_2, M_3 \) and \( M_4 \)

\[
\|v_t\|_{L^q} + \|\Delta v\|_{L^q} + \|\nabla p\|_{L^q} \leq C(\|f\|_{L^q} + \|v\|_{L^q}), \tag{B.65}
\]

where \( L^q \) denotes the norm in \( L^q(\Omega \times (0,T)) \), the constant \( C \) depends on \( q, |\Omega|, M_1, M_2, M_3 \) and \( M_4 \).

**Proof.** Let \( \zeta^k_\lambda(x) \) be the set of non-negative functions in \( C^2(\mathbb{R}^n) \) depending on the parameter \( \lambda \in (0,1) \), forming a partition of unity in \( \Omega \):

\[
1 = \sum_{k=1}^{N_\lambda} \zeta^k_\lambda(x), \quad x \in \Omega
\]

with

\[
\text{supp} \zeta^k_\lambda(x) \subset \Omega^k_\lambda
\]

where the subdomains \( \Omega^k_\lambda \) form a covering of \( \Omega \) which satisfy the following properties:

1. the diameters of \( \Omega^k_\lambda \) do not exceed \( \lambda \);
2. there is a fixed number \( l \) such that the multiplicity of the covering of \( \Omega \) by the subdomains \( \Omega^k_\lambda \) is \( \leq l \);
3. \( \sum_{k=1}^{N_\lambda} (\zeta^k_\lambda(x))^q \geq \mu > 0, \forall x \in \Omega \);
4. \( |D^\beta \zeta^k_\lambda(x)| \leq c\lambda^{-|\beta|}, |\beta| = 1, 2, \forall x \in \Omega \).

For simplicity, we consider the case when \( \rho \) is independent of \( t \). Fix \( x_k \in \Omega^k_\lambda \), for each \( k = 1, 2, ..., N_\lambda \), the vector \( v_k(x, t) = v(x,t)\zeta^k_\lambda(x) \) and the function \( p_k(x, t) = p(x,t)\zeta^k_\lambda(x) \) are solutions in \( \Omega \times (0,T) \) (in the same spaces as \( v \) and \( p \)) to the problem

\[
\begin{align*}
\rho(x_k)v_t - \Delta v_k + \nabla p_k &= f\zeta^k_\lambda(x) + [\rho(x_k) - \rho(x)]v_k - \rho(x)v_k \cdot \nabla v_k + g_k(x, t), \\
\nabla \cdot v_k &= v \cdot \nabla \zeta^k_\lambda(x), \quad v_k(0) = 0, \quad v_k|_{\partial \Omega} = 0,
\end{align*}
\tag{B.66}
\]

where

\[
g_k(x, t) = -2\sum_{i=1}^{N_\lambda} v_{\zeta^i_k}v - v\Delta \zeta^k_\lambda + p\nabla \zeta^k_\lambda + \rho(x)[v\zeta^k_\lambda(v \cdot \nabla \zeta^k_\lambda) + (\zeta^k_\lambda - 1)v \cdot \nabla v] .
\]

Assuming the right-hand side of the first equation in (B.66) is the ‘free term’, making use of the results of lemma 2.2 in [19], we have the estimate for \( v_k, p_k \)

\[
\|v_k\|_{L^q} + \|\Delta v_k\|_{L^q} + \|\nabla p_k\|_{L^q} \leq C_1(\|f\|_{L^q} + \max_{x \in \Omega^k_\lambda} |\rho(x_k) - \rho(x)|\|v_k\|_{L^q} + \|v_k \cdot \nabla v_k\|_{L^q} + \|g_k\|_{L^q}). \tag{B.67}
\]

where constant \( C_1 \) depends on \( M_2 \). Since \( \max_{x \in \Omega^k_\lambda} |\rho(x_k) - \rho(x)| \leq M_3 \lambda \), and the properties of \( \zeta^k_\lambda \), we are able to derive estimate (B.65) from (B.67), by choosing appropriately \( \lambda = (1 + M_3)^{-1}\min\{1, (2C_1)^{-1}\} \) and applying the general Gagliardo–Nirenberg inequality (see [2]).

**Remark B.2.** As seen in this simple example once we have the bound on the small oscillations the desired estimate follows.


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