A SIMPLE MODEL OF CHROMOSPHERIC EVAPORATION AND CONDENSATION DRIVEN CONDUCTIVELY IN A SOLAR FLARE

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ABSTRACT

Magnetic energy released in the corona by solar flares reaches the chromosphere where it drives characteristic upflows and downflows known as evaporation and condensation. These flows are studied here for the case where energy is transported to the chromosphere by thermal conduction. An analytic model is used to develop relations by which the density and velocity of each flow can be predicted from coronal parameters including the flare’s energy flux $F$. These relations are explored and refined using a series of numerical investigations in which the transition region (TR) is represented by a simplified density jump. The maximum evaporation velocity, for example, is well approximated by $v_e \approx 0.38(F/\rho_{\text{co}})^{1/3}$, where $\rho_{\text{co}}$ is the mass density of the pre-flare corona. This and the other relations are found to fit simulations using more realistic models of the TR both performed in this work, and taken from a variety of previously published investigations. These relations offer a novel and efficient means of simulating coronal reconnection without neglecting entirely the effects of evaporation.

Key word: Sun: flares

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1. INTRODUCTION

Solar flares are events in which large amounts of magnetic energy, stored in the coronal field, are rapidly converted to other forms. Many of the dramatic consequences of flares result less directly from the energy release than from the large mass of chromospheric material that is heated and driven upward in a process known as chromospheric evaporation (Canfield et al. 1980; Antonucci et al. 1999). Direct signatures of this process are observed in Doppler shifts of hot spectral lines (Antonucci & Dennis 1983; Zarro & Lemen 1988; Brosius & Phillips 2004; Milligan & Dennis 2009), but the tremendous increase in the emission measure of high-temperature plasma provides equally compelling, albeit indirect, evidence (Neupert 1968).

Since it was first proposed chromospheric evaporation has been investigated by numerical simulations solving one-dimensional gas-dynamic equations (Nagai 1980; Somov et al. 1981; Peres et al. 1982; McClymont & Canfield 1983). Some investigations introduce the flare energy as a beam of non-thermal electrons impacting the chromosphere (MacNeice et al. 1984; Fisher et al. 1985a, 1985b, 1985c), while others use an ad hoc heat source situated at the loop top, whose energy is carried to the chromosphere by thermal conduction (Cheng et al. 1983; MacNeice 1986). In both scenarios, beam-heated and conductive, chromospheric material is heated and driven upward at speeds comparable to, or exceeding, the local sound speed. In many simulations there is a downward flow, called chromospheric condensation, for which some spectroscopic observations provide separate evidence (Ichimoto & Kurokawa 1984; Brosius & Phillips 2004; Brosius 2009; Milligan & Dennis 2009).

It is generally believed that magnetic reconnection is ultimately responsible for releasing the coronal magnetic energy and thereby initiating a solar flare. The ad hoc energization invoked in one-dimensional gas-dynamic simulations mentioned above, either thermal or non-thermal, is thus intended to model reconnection. Emission of hard X-rays or microwaves from loop footpoints provide evidence of non-thermal electrons energizing the chromosphere. There are, however, flares in which substantial evaporation occurs in the absence of footpoint emission (Zarro & Lemen 1988; Longcope et al. 2010). In such cases the downward transport of reconnection energy can be attributed to thermal conduction. Moreover, even in those flares where it does occur, footpoint emission is observed to abate well before the flare’s energy release ends. Evaporation in the later stages of these flares is presumed to be driven by thermal conduction from the reconnection site at the loop tops. It has been proposed that the increased density resulting from chromospheric evaporation comes to inhibit the propagation of non-thermal beams, thereby causing the transition to conduction-driven evaporation (Liu et al. 2006).

Currently, we can hope to conduct theoretical studies of reconnection and evaporation together only for cases of conduction-driven evaporation. While theoretical models exists for non-thermal electron energization by turbulence (Benz & Smith 1987; Hamilton & Petrosian 1992; Miller et al. 1996; Park et al. 1997) and by steady electric fields (Litvinenko 1996), no such model includes the process of magnetic reconnection self-consistently. Instead, most large-scale models of flare-related magnetic reconnection have been formulated using resistive MHD: fluid equations lacking a non-thermal electron population (Forbes & Priest 1983; Mikic et al. 1988; Amari et al. 1996; Magara et al. 1996; Nishida et al. 2009; Birn et al. 2009). In fluid models of fast reconnection, magnetic energy is ultimately converted to kinetic energy of flows whose shocks produce heat (Petschek 1964; Soward 1982; Longcope et al. 2009), which is then carried by thermal conduction to the chromosphere where it drives evaporation (Forbes et al. 1989; Tsuneta 1996). Several investigations have succeeded in accommodating all these effects in a single, self-consistent simulation (Yokoyama & Shibata 1997, 1998; Chen et al. 1999a, 1999b).

Due to the numerical difficulties of resolving both the coronal reconnection, the solar transition region (TR) and the field-align thermal conduction between them, few investigations have followed those of Yokoyama & Shibata (1997) or Chen et al. (1999b) to simulate reconnection and evaporation together. Instead, the vast majority of theoretical investigations study...
magnetic reconnection in isolation, omitting the process of evaporation. This is primarily done to achieve better resolution of the coronal physics of reconnection. There is some evidence, however, that electron acceleration, and thus presumably reconnection, occurs at densities significantly enhanced by evaporation (Veronig & Brown 2004; Jiang et al. 2006; Guo et al. 2012) and even continuing to increase by ongoing evaporation (Liu et al. 2006). Thus it seems unrealistic to consider either process, reconnection or evaporation, in isolation. Moreover, many of the observational signatures with which reconnection models must ultimately make contact, such as X-ray and EUV light-curves or spectra, are direct effects of evaporation and only indirect effects of reconnection.

In place of a full, direct numerical simulation of both processes together, the effects of evaporation on coronal reconnection could be investigated using flows imposed in an otherwise coronal simulation. Doing so would, however, require a simplified relation between reconnection energy release and characteristics of the evaporation, such as density and flow velocity. Previous numerical studies of evaporation were generally not aimed at developing such a relation; fewer still sought one for conductively driven evaporation. Among the few investigations of this kind, Fisher (1987) and Brown & Emslie (1989) each offer different analytic models for evaporation from intense beam deposition. Fisher (1989) developed an analytic model for chromospheric condensation driven by either beam or conductive energy deposition. Fisher et al. (1984) presents a quantitative upper bound for the evaporation velocity in terms of evaporation temperature. The data provided in that work showed, however, actual evaporation speeds falling below this upper bound by as much as an order of magnitude. In fact, the data presented by Fisher et al. (1984) suggest a more useful relation might exist between evaporation velocity and flare energy flux for which they offer no explanation.

The present work takes up the challenge of finding a simple relationship between flare energy release and the evaporation and condensation flows it generates. It adopts a purely fluid model, with energy transported by thermal conduction rather than energy beams. This is done firstly because, as explained above, fluid models remain the only kind that can provide a complete picture of flares from energy storage, to release, and to evaporation. A second advantage is to reduce the size of available parameter space. Non-thermal beams are characterized by an energy flux, a spectral index, and a lower-energy cutoff, and evaporation has been found to depend on all of these parameters (Fisher 1989). We show here that thermal energy transport is effectively characterized by a single parameter, the energy flux \( F \). This would in turn be determined by the amplitude (i.e., Mach number) of the shocks generating the heat, which depends in turn on the current sheet at which reconnection occurs (Longcope et al. 2009, 2010). The result of the present investigation is a set of simple relationships between \( F \) and the density and velocity of both chromospheric evaporation and chromospheric condensation. These relationships provide a very simple means of using spectroscopic observations of emission from the TR and chromosphere, to infer properties of magnetic reconnection in solar flares.

In order to facilitate the variation of parameters, this investigation uses a simplified model of the pre-flare TR. This is described, along with the governing dynamical equations, in the next section. Section 3 describes a typical numerical solution to these equations. This motivates a simplified analytical model, presented in the same section, and then compared to the numerical solution in detail. Section 4 present a large number of different numerical solutions spanning parameters. The analytical model is used to propose scaling relations which can be fit to the runs. Section 5 then applies these same scaling laws to simulations with more realistic TR and chromosphere treatments, including results from the literature. In nearly every case these results are found to conform reasonably well to the simple scaling laws.

2. THE MODEL

In this work, as in many previous investigations (Nagai 1980; Somov et al. 1981; Peres et al. 1982; MacNeice et al. 1984), evaporation is studied using one-dimensional gas-dynamic equations for evolution of the plasma along a static flux tube, parameterized by length \( \ell \). Equations for mass, momentum, and energy conservation in the flux tube of uniform cross section are

\[
\frac{\partial \rho}{\partial t} + \frac{\partial}{\partial \ell} (\rho v) = 0, \tag{1}
\]

\[
\rho \left( \frac{\partial v}{\partial t} + v \frac{\partial v}{\partial \ell} \right) = -\frac{\partial p}{\partial \ell} + \frac{\partial}{\partial \ell} \left( \frac{2}{3} \mu \frac{\partial v}{\partial \ell} \right) + \rho g_1, \tag{2}
\]

\[
c_v \rho \left( \frac{\partial T}{\partial t} + v \frac{\partial T}{\partial \ell} \right) = -p \frac{\partial v}{\partial \ell} + \frac{4}{3} \mu \left( \frac{\partial v}{\partial \ell} \right)^2 + \frac{\partial}{\partial \ell} \left( \kappa \frac{\partial T}{\partial \ell} \right) + \dot{Q}, \tag{3}
\]

where \( \rho \) and \( T \) are mass density and temperature, respectively, \( g_1 \) is the component of gravitational acceleration along the tube, and \( c_v \) is the specific heat, described below. The fluid moves along the flux tube at velocity \( v \). Heating and cooling due to the flare and radiative losses are included in the volumetric power \( \dot{Q} \) which is described in detail in the next sections. The total plasma pressure \( p \) is found using the ideal gas equation,

\[
p = \frac{k_a}{\bar{m}} \rho T, \tag{4}
\]

where \( k_a \) is Boltzmann’s constant and \( \bar{m} \) is the mean mass per particle.

Equations (1)–(3) are solved within a region spanning the corona and the chromosphere, over which varying states of ionization will occur. The focus is, however, on flare-driven flows which occur in plasmas heated to temperatures around or above \( 10^6 \) K, and for which the plasma is expected to be fully ionized. We therefore adopt the expedient measure of solving Equations (1)–(3) for a fully ionized plasma with coronal abundance, setting \( \bar{m} = 0.593 m_p \), where \( m_p \) is the proton mass, and taking the specific heat

\[
c_v = \frac{3 k_b}{2 \bar{m}}. \tag{5}
\]

The main way that ionization would affect our results would be by removing energy from the condensation shock (CS) through an additional contribution to \( c_v \). We discuss this in an appendix and show that such a contribution would have relatively minor effects on our results.

The thermal conductivity \( \kappa \) depends on temperature according to the classical Spitzer form (Braginskii 1965)

\[
\kappa = \kappa_0 T^{5/2}, \quad \kappa_0 = 10^{-6} \text{ erg cm}^{-1} \text{ s}^{-1} \text{ K}^{-7/2}. \tag{6}
\]
While this classical form can become inapplicable for extremely large heat fluxes, we have found that it applies to cases where heating occurs self-consistently through shocks (Guidoni & Longcope 2010; Longcope & Bradshaw 2010). In order to simplify our analysis we use it for all of our computations. The parallel component of dynamic viscosity \( \mu \) has a temperature dependence identical to classical conductivity, but is lower by a factor proportional to the Prandtl number \( \text{Pr} \),

\[
\mu = \text{Pr} \frac{\kappa}{c_s}.
\]

The Prandtl number in fully ionized plasma is \( \text{Pr} = 0.012 \), reflecting the very small electron-to-ion mass ratio. While it is, in some sense, much smaller than thermal conductivity, its effects are very important, especially in flares where \( T \) has increased by an order of magnitude (Peres & Reale 1993). Since they thermalize bulk kinetic energy, shocks cannot be modeled without viscosity. Nevertheless, some flare investigations in the literature do solve gas dynamic equations without viscosity (Cheng et al. 1983). To make closer contact with that work, and to sharpen the shocks for easier identification, we perform most runs using an artificially small value \( \text{Pr} = 10^{-4} \). To prevent under-resolution and maintain energy conservation, we place a lower bound on the viscosity

\[
\mu > 0.05 \rho c_s \Delta \ell,
\]

where \( \Delta \ell \) is the local grid spacing and \( c_s \) is the local sound speed. This bound is typically assumed in the regions of lowest \( T \), such as the pre-flare chromosphere.

Equations (1)–(3) are solved using a Lagrangian code similar to that described in Guidoni & Longcope (2010). In this new code the thermal conductivity term in Equation (3) is differenced implicitly to permit larger time steps even in the face of extremely high temperatures. In contrast to Guidoni & Longcope (2010), magnetic tension has been omitted from Equation (2) under the assumption that the flux tube is already in magnetostatic equilibrium. This omission removes magnetic reconnection as an explicit energy source. We follow, instead, the standard practice of replacing the omitted term with an ad hoc heating, without a corresponding force. In future work we will return to explore the effect of making this assumption compared to allowing reconnection to energize the flare loop legitimately.

2.1. The Initial Condition—a Simplified Transition Region

The initial condition for the model is a hydrostatic loop of total length \( L \), consisting of a coronal portion, TRs, and chromospheres at each footpoint. We add to the heating term, \( Q \), an ad hoc contribution, localized to the center of the loop (i.e., the loop top), to drive the evaporation and condensation via thermal conduction. The aim of this study is to characterize the evaporation and condensation as responses to the loop-top energy input. This characterization will depend, to some degree, on the pre-flare structure of the TR and chromosphere.

In equilibrium models, the structure of the TR and chromosphere is determined by the interplay between heating, thermal conduction, and radiation. The relative magnitude of these competing effects can be estimated from the minimum value of the logarithmic differential emission measure (DEM), \( \xi = n_e^2 dz/d \ln T \), observed to be about \( \xi_{\text{min}} \sim 10^{17} \text{ cm}^{-3} \) at the TR temperature \( T_\text{r} \sim 10^5 \text{ K} \) (Dere 1982). The minimum DEM corresponds to conductive flux of

\[
|F_\text{c}| \simeq \frac{\kappa_0 \rho T_\text{r}^{3/2}}{4k^2} \xi_{\text{min}} = (4 \times 10^5 \text{ cm}^4 \text{ erg}^{-1}) \rho^2,
\]

where \( \rho \) is the equilibrium pressure at \( T_\text{r} \). Since active region loops have equilibrium pressures generally less than 10 erg cm\(^{-2}\) s\(^{-1}\), energy fluxes are of the order of 10\(^4\) erg cm\(^{-2}\) s\(^{-1}\) or less. Energy flux typically attributed to flares, above 10\(^6\) erg cm\(^{-2}\) s\(^{-1}\), completely overwhelms this. The most important factor determining the chromospheric response is therefore the distribution of mass, rather than the processes which created that mass distribution in the first place.

Motivated by the foregoing argument we wish to explore how different TR mass distributions affect the evaporative response to flare heating. Toward this end we perform a series of experiments initialized with an artificial TR, of set thickness \( \Delta_\ell \), separating perfectly uniform coronal and chromospheric plasmas (Brannon & Longcope 2014). In these experiments gravitational stratification is omitted \((g_1 = 0)\) so the equilibrium has uniform pressure \( p_0 \). Radiative losses are also omitted. Coronal plasma at uniform temperature \( T_{\text{co,0}} \) is maintained by heating functions at \( \ell = -\Delta_\ell \) and \( \ell = \Delta_\ell \). Temperature drops to a pre-set chromospheric level, \( T_{\text{ch,0}} \), across the TRs. This is maintained by cooling functions, at \( \ell = 0 \) and \( \ell = L \), equal and opposite to the heating functions. This construction is implemented by setting \( Q \) in equilibrium to

\[
H_{\text{eq}}(\ell) = A[S(\ell - \Delta_\ell) - S(\ell) + S(L - \Delta_\ell - \ell) - S(L - \ell)],
\]

where the heating and cooling are distributed over a distance 2\( w \) according to the shape function

\[
S(x) = \begin{cases} 
1 - (x/w - 1)^2, & 0 < x < 2w \\
0, & \text{otherwise}
\end{cases}
\]

centered at \( x = w \) and vanishing at \( x = 0 \). The coefficient \( A \) is chosen to obtain the desired temperature ratio, \( T_{\text{co,0}}/T_{\text{ch,0}} = R_\text{r} \), across each TR.

The initial condition is a static, isobaric equilibrium with \( \dot{Q} = H_{\text{eq}}(\ell) \). From Equation (3), we find the temperature distribution of the equilibrium

\[
T^{7/2}(\ell) = T_{\text{ch,0}}^{7/2} - \frac{7}{2} \kappa_0^{-1} \int_0^\ell d\ell' \int_0^{\ell'} d\ell'' H_{\text{eq}}(\ell'').
\]

An example, shown in Figure 1, has \( T_{\text{co,0}} = 2 \times 10^6 \text{ K} \), \( T_{\text{ch,0}} = 2 \times 10^4 \text{ K} \), \( \Delta_\ell = 3 \text{ Mm} \), and \( w = 0.75 \text{ Mm} \). The temperature changes only within the range, \( 0 < \ell < \Delta_\ell + w = 4.5 \text{ Mm} \), but mostly at the outside edge of the cooling function (i.e., the left side or the left TR);\(^1\) this point is used to define the total length of the loop. The flux between the heating and cooling sections is \( |F_\text{c}| \simeq 10^3 \text{ erg cm}^{-2} \text{ s}^{-1} \), which is slightly higher than in actual TRs, but still far below the flaring energy flux. This heat flux is lower than the free-streaming heat flux limit, \( F_\text{c}^{(8)} = (3/2)m_e n_e v_{\text{th,e}}^3 \) (Campbell 1984) by more than an order of magnitude throughout the TR.

The Lagrangian grid points are arranged to keep roughly constant mass between them. This has the effect of concentrating grid points in the chromosphere. The initial locations are shown along the bottom of the top panel of Figure 1.

\(^1\) Due to the artificial way we create it, we apply the term “transition region” (TR) to the entire region of artificial heating and cooling, even though the majority of this range has a very shallow temperature gradient, reminiscent of the corona.
2.2. Flare Heating

Flare energy release is modeled using a flat-topped ad hoc heating function centered at the loop top and extending a total distance of $\Delta f$,

$$H_f(\ell) = \begin{cases} \frac{F}{\Delta f/2}, & |\ell - L/2| < \Delta f/2 \smallskip \text{0, otherwise} \end{cases}$$

This is added to the equilibrium heating function, $\dot{Q} = H_{eq} + H_f$, to provide the term in Equation (3). That contribution is held fixed for the entire run.

Since the solution begins with a state which is in equilibrium with heating $H_{eq}$, the addition of $H_f$ has the effect of ramping the flare energy input instantaneously. In models where flare energy is released by fast magnetic reconnection the heating occurs at a slow shock which is generated by the retraction of the reconnected flux tube (Petschek 1964; Soward & Priest 1982). A particular flux tube passes the reconnection point in an instant and thereafter begins retracting (Longcope et al. 2009). It is therefore appropriate to replace this kind of self-consistent heating with an ad hoc heating term with an instantaneous turn-on. Since evaporation is the focus of this work, the heating term is never turned off.

The parameter $F$ defines the total energy flux delivered to one side of the loop, and ultimately to a single footpoint. This is one of the key parameters expected to dictate the chromospheric response. We perform runs for a range of parameters. The most significant variations occur for variations in energy flux $F$, loop length $L$, equilibrium values of pressure $p_0$ and TR temperature ratio $R_a = T_{co,0}/T_{ch,0}$.

3. THE SIMULATIONS

Figure 2 shows the solution for a flux tube of length $L = 53$ Mm, pressure $p_0 = 1.0$ erg cm$^{-3}$, subjected to a flare energy flux $F = 3.5 \times 10^{10}$ erg cm$^{-2}$ s$^{-1}$, distributed over $\Delta f = 10$ Mm. Its initial TR was the same as seen in Figure 1. The heating produces an evolution resembling those reported in many previous simulations of this kind (Cheng et al. 1983; Emslie & Nagai 1985). The temperature within the heated region (between the vertical dashed lines) rises rapidly. At the same time, thermal conduction creates fronts moving rapidly in both directions. By $t = 1.5$ s these fronts have reached the TRs and the loop top temperature slows its rise. After $t = 2.0$ s the apex temperature has achieved a steady state of $T_a = 3.7 \times 10^7$ K. After that the temperature profile changes very little over the bulk of the loop. The heat flux $F$ is being delivered to the chromosphere where it generates evaporation flow.

The loop’s DEM undergoes a characteristic evolution during as the conduction front travels to the TR and initiates evaporation. Figure 3 shows the logarithmic DEM, $\xi(T) = n_e^2 d\ell/d\ln T$, throughout the evolution depicted in Figure 2. The initial DEM has a sharp peak at the coronal temperature ($T = 2 \times 10^6$ K) and a sloping TR below. (The simplified TR creates a minimum $\min(\xi) \simeq 3 \times 10^{27}$ cm$^{-5}$, slightly higher, and at higher temperature, than a real TR.) The conduction front shifts the emission from the coronal peak into an increasing slope up to the flare peak at $T \simeq 3 \times 10^7$, making no change to the TR which has not yet been disturbed. As the conduction front crosses the TR, over the times $1.3 \leq t \leq 1.5$ s, the DEM below the corona is rapidly eroded away; a steep drop reaches $T = 7 \times 10^5$ K and $T = 2 \times 10^5$ K at $t = 1.3$ and 1.4 s, respectively. This emission
Figure 2. Evolution of temperature under a flare energy flux of $F = 3.5 \times 10^{10}$ erg cm$^{-2}$ s$^{-1}$. The left panel shows $T(\ell)$ at a sequence of times between $t = 0$ and $t = 3.5$ s. The apex temperature, $T(L/2)$, is indicated by a diamond. Vertical dashed lines show the region, extending $\Delta \ell = 10$ Mm, over which the flare heating is applied. The right panel shows the continuous evolution of the apex temperature over time. Diamonds correspond to the same times whose profiles are shown in the left panel. The dashed curves shows the apex temperature predicted by Equation (23).

Figure 3. Logarithmic DEM evolving during the initial phases shown in Figure 2. The curves follow a sequence progressing from low to high around $T \simeq 3 \times 10^6$ K, matching the times listed from low to high along the left.

(A color version of this figure is available in the online journal.)

is piled into a peak around $3 \times 10^6$ K. At later times the TR has been thinned enough that $\xi \simeq 3 \times 10^{27}$ cm$^{-5}$, and the peak at $3 \times 10^6$ K grows by evaporation.

The evaporation phase begins once the conduction front has reached the TR and the peak coronal temperature has plateaued: by about $t = 2.0$ s in the present case. Figure 4 shows details of this phase from $t = 3.5$ s when the conduction front has penetrated 1.0 Mm into the chromosphere. This penetration occurs at the head of the conduction front which takes the form of a downward propagating shock of extremely high Mach number: the pressure jumps by a factor 480 and the density jump, a factor of 3.85, is nearly 4, the maximum value permitted by Rankine Hugoniot relations. The post-shock material is downflowing at $v_c \simeq -370$ km s$^{-1}$, in a chromospheric condensation (Fisher et al. 1985a); we henceforth refer to this shock as the CS. An upward propagating shock, the evaporation shock (ES), has reached $\ell = 1.5$ Mm by this time. The density there jumps by a factor slightly greater than four and the peak velocity is $v_e = +750$ km s$^{-1}$. The shock is well defined because we have used the anomalous Prandtl number $Pr = 10^{-4}$. Between these two shocks lies a rarefaction wave (RW) over which the velocity changes continuously between downflow and upflow, and the density increases by a factor close to 100.
Figure 4. Structure of the evaporation flow at the last time shown in Figure 2. The right column shows the entire left side of the flux tube and the left column shows the region around the TR. The rows show, from top to bottom, pressure, velocity, temperature, and electron density. The dotted curve shows the initial profiles of temperature and density (initial pressure and velocity are both uniform).

3.1. An Analytic Model of the Evaporation

The foregoing simulation suggests a simple model for the evaporation. The conduction front overtakes the TR rapidly enough that the entire region is raised to a uniform temperature, $T^*$, before any dynamical response can occur. The TR then functions as an initial pressure discontinuity whose subsequent evolution is an isothermal Riemann problem. Since the TR is now at uniform temperature, the pressure ratio across the jump matches the density ratio which is inversely related to the temperature ratio across the pre-flare TR,

$$\frac{p_{ch}}{p_{co}} = \frac{\rho_{ch,0}}{\rho_{co,0}} = R_{tr}.$$  \hspace{1cm} (14)

Under isothermal dynamics, the initial pressure jump decomposes into a shock and a RW (Fabbro et al. 1985). If the initial jump is thin enough the RW will be self-similar (Landau & Lifshitz 1959; Fabbro et al. 1985)

$$v(\ell, t) = \frac{\ell}{t} + a,$$  \hspace{1cm} (15)

$$\rho(\ell, t) = \rho_0 \exp \left( -\frac{\ell}{at} \right) = \rho_0 \exp \left( 1 - \frac{v}{a} \right),$$  \hspace{1cm} (16)

where $a = \sqrt{p/\rho} = \sqrt{k_B T_*/m}$ is the isothermal sound speed and $\rho_0$ is a constant determined from the surrounding solution.

In the complete solution, illustrated in Figure 5, the left edge is the CS, which heats the plasma to its uniform temperature of $T_*$, with (adiabatic) sound speed $c_{s,*} = \sqrt{5/3}a$. Because the CS has an extremely high Mach number it increases the density to $4\rho_{ch,0} = 4R_{tr} \rho_{co,0}$. The post-shock flow speed for a hypersonic shock propagating into stationary plasma is

$$v_c = -\frac{3}{\sqrt{5}} c_{s,*} = -\sqrt{3} a,$$  \hspace{1cm} (17)

directed downward ($v_c < 0$). This is the condensation velocity, lying at the left-hand edge of the RW and labeled A in Figure 5. Applying these two conditions to point A allows $\rho_0$ to be eliminated from Equation (16)

$$\frac{\rho(\ell, t)}{\rho_{co,0}} = 4R_{tr} \exp \left( -\sqrt{3} - \frac{v}{a} \right).$$  \hspace{1cm} (18)

The ES propagates into the stationary coronal plasma to the right. In the reference frame of the ES, the coronal material is flowing leftward with isothermal Mach number, $M_{tr}^{(0)}$. Because it is an isothermal shock the post-shock flow, in the ES reference frame, has isothermal Mach number $1/M_{tr}^{(0)}$. In the non-moving reference frame, the evaporation flows at velocity $v_c$ to the right, while the pre-shock material is stationary. The velocity difference between pre-shock and post-shock velocities
is independent of reference frame so

$$\frac{v_e}{a} = M_{es}^{(it)} - \frac{1}{M_{es}^{(it)}}.$$  \hspace{1cm} (19)

The density jump across the isothermal shock is $\rho_e/\rho_{co,0} = [M_{es}^{(it)}]^2$. The right-hand edge of the RW, labeled B in Figure 5, must match the conditions of the ES described above. Applying these conditions to Equation (18) yields the relation

$$[M_{es}^{(it)}]^2 = 4R_{tr} \exp\left(-\sqrt{3} - M_{es}^{(it)} + \frac{1}{M_{es}^{(it)}}\right),$$

which must be satisfied by $M_{es}^{(it)}$. Figure 6 shows the solution for a range of TR density ratios $R_{tr}$. Diamonds follow an empirical fit

$$M_{es}^{(it)} \simeq 2.670 + 1.209 \log(R_{tr}/100) [1 + 0.126 \log(R_{tr}/100)].$$

Due to its logarithmic dependence on $R_{tr}$ the isothermal Mach number of the ES falls within the narrow range between 2.5 and 3.5 for most reasonable assumptions above the pre-flare TR.

This model can be compared to an upper bound obtained by Fisher et al. (1984). They used the isothermal momentum equation under the assumption that the entire pressure drop matched the pre-flare values, and the kinetic energy in the condensation was ignorable. By doing so, they obtained the upper bound on the evaporation velocity,

$$v_{icm} = \sqrt{(6/5) \ln R_{tr} c_{s,\ast}} = \sqrt{2 \ln R_{tr} a}.$$  \hspace{1cm} (22)

This is plotted as a dashed line in Figure 6. The discrepancies are due to the different assumptions used in the two derivations.

3.2. Modeling the Simulation

Figure 7 shows the numerical solution from Figure 4, at a somewhat later time ($t = 6.5$ s), plotted in the same manner as the sketch in Figure 5. Because the solution includes viscosity, albeit artificially low, the ES is somewhat broadened. The CS satisfies the structure assumed in the simplified model: $\rho_c = 4R_{tr}\rho_{co,0}$ and $v_c = -\sqrt{3}a$. Its actual location, plotted with a square, lies almost on top of this theoretical one, marked with a triangle in the right column of Figure 7. The ES also conforms to the assumption of an isothermal shock, marked by a dotted curve in the right column.

The actual RW does not, however, conform to the self-similar, isothermal structure. The velocity is not linear with distance, and the density is not exponential. The path between squares, in the right column of Figure 7, falls off the isothermal model.
Figure 6. Isothermal Mach number of the evaporation shock, $M^{(it)}_{es}$, as a function of $R_t$, satisfying Equation (20). Diamonds follow the empirical fit, Equation (21). The dashed curve shows the upper bound, Equation (22), derived by Fisher et al. (1984).

Figure 7. Solutions from Figure 4, at later time $t = 6.25$ s, plotted in the same manner as Figure 6. Velocity is scaled to the local isothermal sound speed, $a$, and density to the pre-flare coronal value $\rho_{co,0}$. Vertical dotted lines in the upper right panel show the boundaries of the RW and the ES. The right column plots the scaled velocity against normalized density. Dotted curves show the relation for an isothermal shock, and the dash dotted line shows the equation for an isothermal, self-similar RW, namely, Equation (18). A triangle in the right panels shows the theoretical point in density-velocity space where a hypersonic condensation shock would fall.

shown by dash-dotted lines. It is temperature variation along the RW that causes its track to fall beneath the isothermal (dash-dotted) one in the lower right. This curve intersects the shock curve at a point of lower density and lower velocity. Thus the prediction of the isothermal model, i.e., Equation (20), provides an upper bound on the isothermal Mach number of the actual shock. For this case with $R_t = 100$, the isothermal model predicts $M^{(it)}_{es} = 2.67$, and thus $\rho_c/\rho_{co,0} = (2.67)^2 = 7.13$ and $v_c/a = 2.67 - (2.67)^{-1} = 2.30$. The actual values, 4.69 and 1.50, respectively, fall below those values. The isothermal Mach
number of this shock, $M_{\text{es}}^{(i)} = \sqrt{4.69} = 2.16$, lower than the prediction from Equation (20). This is the effect of temperature variation along the RW.

At higher values of heat flux $F$ the evaporation/condensation structure becomes more isothermal owing to the larger conductivity at higher temperatures. A solution of this kind, shown in Figure 8, has a RW falling closer to the isothermal model (dash-dotted curve). At these higher fluxes, however, the RW begins to affect the CS, and the latter departs from the assumption of a hypersonic shock, as evident in the separation between square and triangle in the right column of plots. The density behind the CS is lower than $4\rho_{\text{ch},0}$, and the velocity greater than $-\sqrt{3}a$. We discuss in the next section the level of energy flux required to produce this departure from the analytic model.

The analytic model breaks down for different reasons in the opposite limit of very small energy fluxes. In this case, the conduction fronts move very slowly from the loop top. In one case (not shown) with $F = 10^9$ erg cm$^{-2}$ s$^{-1}$, the steady-evaporation phase is achieved only after 30 s compared to 2 s, in Figure 2. The loop-top heating also drives flows downward, as evident on the right column of Figure 4. When the conduction front arrives late, this flow impinges on the evaporation flow. The result is a departure from the analytic model of Figure 5, and a systematically low evaporation flow.

Using the physical viscosity, characterized by $Pr = 0.012$, provides a more realistic, but less clear picture of the evaporation process. Figure 9 shows the results of making this change to the simulation discussed above. The larger viscosity spreads the ES considerably, causing it to overlap with the RW. As a result, the phase space curve of the ES deviates from the isothermal curve (dotted) by veering toward the RW curve (dash-dotted). The point of maximum velocity is adopted at the point separating these two structures, now largely merged. This occurs at a lower velocity ($v_c/a = 1.20$) and higher density ($\rho_c/\rho_{\text{co},0} = 6.30$) than in the case with a well-defined ES. In addition, the ES continues expanding, causing these values to change with time. We therefore continue using the anomalously low value, $Pr = 10^{-4}$ to obtain clear values. We recognize that these values will differ from those with physical viscosity in the manner just described.

4. SCALING OF THE EVAPORATION

4.1. Variation in Flare and Loop Parameters

We next explore how the structure of the evaporation and condensation varies with parameters. Twenty-eight different simulations are performed with different values of $L$, $F$, $p_0$, and $R_{\text{tr}}$. Loop lengths range from 9 to 86 Mm, fluxes from $10^9$ to $10^{12}$ erg cm$^{-2}$ s$^{-1}$, initial pressures from 0.3 to $3.0 \rho_{\text{gc}}$, and $R_{\text{tr}}$ from 40 to 100. For simplicity we hold fixed the TR structure by keeping the values $\Delta_{\text{tr}} = 3$ Mm, $w = 750$ km; the chromosphere is kept at $T_{\text{ch},0} = 20,000$ K, but the corona is at $T_{\text{co},0} = R_{\text{tr}} T_{\text{ch},0}$ which varies as $R_{\text{tr}}$ is varied. The heating profile was also kept fixed with $\Delta_{\text{fl}} = 10$ Mm. Each simulation was run past the time the apex temperature plateaued at $T_{\text{fl}}$. At that point, the shocks, ES and CS, were identified and characterized.

The peak apex temperature, $T_{\text{fl}}$, is achieved when the flare energy flux balances the power driving the evaporation. The heat flux reaching the evaporating plasma, at lower temperature, will be $\sim k_0 T_\text{fl}^{7/2}/L$. Equating this with the input flux yields an
expected scaling

$$T_{fl} = C_T (FL/\kappa_0)^{2/7}, \quad (23)$$

where $C_T$ is a dimensionless constant. The same form is given in the Appendix of Fisher (1989). The left panel of Figure 10 shows $T_{fl}$ for the 28 runs (plusses) versus the product $FL$, where $L$ is the full loop length. The dashed line shows Equation (23) with $C_T = 1.46$, found from a fit to all 28 runs.

According to the analytic model of Section 3.1, the isothermal Mach number of the ES, $M_{es}^{(it)}$, depends only on the pre-flare chromospheric/coronal density ratio $R_u$ (and on that only logarithmically). Application to an actual solution showed, however, that temperature gradient within the RW led to a slightly lower value of $M_{es}^{(it)}$. For the cases of small viscosity, however, the ES is a simple isothermal shock and therefore its density enhancement is

$$R_{es} = \frac{\rho_e}{\rho_{co,0}} = \left(M_{es}^{(it)}\right)^2. \quad (24)$$

This will have an upper bound dependent on $R_u$, and a value depending on other factors responsible for the temperature variation within the RW. Figure 10 shows that the observed ES density enhancement, $R_{es}$, is ordered by the quantity, $F/p_0^{5/2}$, identified using multivariate regression to the 28 plusses. An empirical relation,

$$R_{es} = \frac{1}{2} \ln \left(\frac{F}{p_0^{5/2}/C_M}\right) + 7.13, \quad (25)$$

lies near, and slightly above, much of the data, where $C_M = 2.8 \times 10^{12}$ erg$^{-3/2}$ cm$^{-9/2}$ s$^{-1}$. Expression (21) predicts that the upper bound to the density enhancement of, $R_{es} = (2.67)^2 = 7.13$. The empirical fit, Equation (25), would exceed the maximum for $F p_0^{5/2} > C_M$. This value is above the point where the analytic model becomes untenable due to the reduction in Mach number of the CS, as shown in Figure 8.

The analytic solution shown in Figure 5 has a total kinetic energy (per unit area)

$$E_K = \int \frac{1}{2} \rho v^2 \, d\ell = \frac{1}{2} \rho_{co,0} a^3 \int \frac{\rho(\tilde{\ell})}{\rho_{co,0}} (M_{es}^{(it)}(\tilde{\ell}))^2 d\tilde{\ell}, \quad (26)$$

where $\tilde{\ell} = \ell/\alpha t$ is the similarity variable of the solution, and $M_{es}^{(it)} = v/a$ is the scaled velocity plotted in the figure. The integral in the final expression depends on the scaled analytic solution and therefore on $M_{es}^{(it)}$ only. Assuming the flare energy flux, $F$, exactly balances this energy requirement (i.e., $F = dE_K/dt$), the isothermal sound speed within the evaporation flow is

$$a \sim (F/\rho_{co,0})^{1/3}. \quad (27)$$

If we neglect the logarithmic dependence of $M_{es}^{(it)}$, the evaporation flow speed will scale in the same manner

$$v_e = C_e (F/\rho_{co,0})^{1/3}. \quad (28)$$

The best fit to the 28 plusses, shown in Figure 11, is for $C_e = 0.38$. The points at the very left and very right of the range trend below this fit. The explanation may be the departure from the analytic model at high and low fluxes, described briefly in Section 3.2.
Figure 10. Flare temperature $T_f$ (left) and ES density enhancement ratio $R_{es}$ (right) of flare simulations. The plusses are the runs with artificial TR described in Section 4. Other symbols show runs with more realistic TR treatments from the literature and this work, as described in Section 5. The left panel shows $T_f$, in Kelvin, vs. $FL$ (in units of $10^{20}$ erg cm$^{-1}$ s$^{-1}$), with a dashed line showing Equation (23). The right panel shows $R_{es}$ vs. $F^{5/2}$ (in units of $10^8$ erg$^{-3/2}$ cm$^{-9/2}$ s$^{-1}$), and the dashed line shows relation (25).

Figure 11. Velocity of the evaporation (left) and condensation (right) from flare simulations, plotted in km s$^{-1}$. The plusses are the runs with artificial TR described in Section 4. Other symbols show runs with more realistic TR treatments from the literature and this work, as described in Section 5. The left panel shows $v_e$ vs. $F/\rho_{co,0}$ (in $10^{24}$ cm$^3$ s$^{-3}$), with a dashed line showing Equation (28). The right panel shows $v_c$ vs. $F/\rho_{ch,0}$ (in $10^{24}$ cm$^3$ s$^{-3}$), with a dashed line showing Equation (29). The dotted line shows the scaling derived by Fisher (1989), and reproduced here as Equation (30).

Fisher (1989) estimates the height of the pressure peak separating evaporation from condensation to scale as $p_e \sim (F^2 \rho_{co,0})^{1/3}$ (see also Fisher et al. 2012). While he does not go on to estimate the evaporation flow speed we can take the additional step of identifying the sound speed within the evaporation as $a \sim \sqrt{p_e/\rho_{co,0}}$ to obtain a scaling identical to Equation (27). While Fisher’s logic differs from that following Equation (26) above, both produce the same scaling, as would simple dimensional analysis (Fisher 1989).

It is noteworthy that we found CSs in every run, including those of the smallest flare energy fluxes. Thermal conduction therefore differs from non-thermal deposition, which generates condensation only when the flux exceeds a threshold $F_{thr}$. This threshold is found to be between $F_{thr} = 3 \times 10^9$ and $3 \times 10^{11}$ erg cm$^{-2}$ s$^{-1}$ depending on pre-flare pressure and the beam’s spectral properties (Fisher 1989). Non-thermal energy fluxes below the threshold produce gentle evaporation, in which there is little observable condensation. Fluxes above...
Figure 12. Evaporation flows at $t = 4 \text{ s}$ from runs with different TR models. Velocity $v$ in km s$^{-1}$ (left column) and the electron density $n_e$ (right column) are plotted for each run, but the $x$ axis is shifted to line up the plots. Except for $w$ and $\Delta t$, all have the same parameters as those in Figure 4. The top row (a) shows that same run, with $w = 3 \text{ Mm}$ and $\Delta t = 0.75 \text{ Mm}$. The next two rows have $w = 3 \text{ Mm}$ and $\Delta t = 0.25 \text{ Mm}$ (b), and $w = 1 \text{ Mm}$ and $\Delta t = 0.25 \text{ Mm}$ (c). The bottom row (d) is the same as (a) but with a specific heat $c_v$ modified to simulate ionization, as explained in the Appendix. Dotted lines in the left column repeat the velocity profile for row (a) for reference.

4.2. Variation in TR

In order to provide maximum flexibility, a simplified TR model has been used under the presupposition that the detailed TR structure does not affect the evaporation or condensation. Figure 12 shows that this presupposition is warranted. Velocity and density are shown at $t = 4 \text{ s}$ from solutions with different TR structures. The thickness of the TR is varied from $w = 1 \text{ Mm}$ to $w = 3 \text{ Mm}$. The size of the heat sources range from $\Delta t = 0.25 \text{ Mm}$ to $\Delta t = 0.75 \text{ Mm}$. It is evident that the resulting flow structure is insensitive to the structure of the initial TR.

5. APPLICATION TO MORE REALISTIC SIMULATIONS

The foregoing considered simulations with an artificial TR in order to fully explore the dependence of evaporation on parameters. In cases with more realistic TRs these parameters cannot be varied independently. The results derived above do, however, apply to these cases.

5.1. Simulation with Radiation

We use the same code to perform runs with a more realistic TR by including radiation and gravitational stratification. The heating function in this case is

$$\dot{Q} = -n_e^2 \Lambda(T) + H_{\text{eq}}(\ell) + H_0(\ell),$$

where $n_e = 0.874 \rho/m_p$ is the electron number density assuming complete ionization. The radiative loss function $\Lambda(T)$ is a piece-wise power-law fit to the output of CHIANTI 7.1 with coronal abundances (Landi et al. 2013; Dere et al. 1997). We make this function monotonic, $\Lambda \sim T^{1.66}$, over the range $19,000 \text{ K} < T < 78,700 \text{ K}$. This omits a peak at $T \simeq 20,000 \text{ K}$, due to silicon which would make the lowest temperature regions susceptible to radiative instabilities. For $T < 19,000 \text{ K}$ we set
$\Lambda = 0$ in order to prevent any thermal instability in the isothermal chromosphere. The equilibrium heating, $H_{\text{eq}}(\ell)$, is taken to be uniform except in the chromospheric layer, where it is set to exactly balance the radiative losses in equilibrium. In order to produce a stratified chromosphere, we take $g_{\text{par}} = \pm 274 \text{ m s}^{-2}$ within the chromosphere only.

The initial state is taken to be an equilibrium for heating $Q = -n_e^2 \Lambda + H_{\text{eq}}$ with specified peak temperature $T_{\text{eq},0} = 2 \times 10^6$ K, a chromosphere at $T_{\text{ch},0} = 20,000$ K, and (full) loop length $L = 60$ Mm. Following the arguments of Rosner et al. (1978), specifying these parameters fixes the equilibrium heating, and coronal pressure, to be $H_{\text{eq}} = 1.3 \times 10^{-3}$ erg cm$^{-3}$ s$^{-1}$ and $p_0 = 0.65$ erg cm$^{-3}$. We add the flare heating profile $H_{\text{f}}$ from Equation (13), with $F = 3.4 \times 10^6$ and $10^6$ erg cm$^{-2}$ s$^{-1}$ in separate runs. The characteristics of the resulting evaporation and condensation, plotted as $\times$’s in Figures 10 and 11, fall very close to those of runs with artificial TRs. Notably, the radiative losses decreased the flare temperature (by about 25% below Equation (23) in both cases), and the ES density enhancement (by about 10% below Equation (25) in both cases); radiative losses left the evaporation velocity within 8% of relation (28). This corroborates our assumption that radiative losses do not make significant contributions to the rapid evolution of flare evaporation, at least when it is driven by conduction.

### 5.2. Simulations in the Literature

Numerous simulations of conductively driven flaring loops have been reported in the literature. Each of these used a different code, implementing different aspects of the relevant physics. Evaporation and condensations characteristics from some notable simulation reports are given in Table 1 and plotted as various symbols on Figures 10 and 11. These lie near enough to the dashed lines to be considered to be adequately predicted by relations described in previous section.

Peres & Reale (1993) used the Palermo-Harvard numerical code (Peres et al. 1982) to perform several simulations aimed at exploring the effects of viscosity on evaporation. Two sets of these runs, named run 1 and run 2, use a steady ad hoc heating source, localized to the loop top. Theirs had a 10 Mm wide Gaussian profile in place of the flat-topped function of Equation (13). The flaring energy flux,

$$F = \int_{0}^{L/2} H_{\text{f}}(\ell) d\ell,$$

is $F = 6.3 \times 10^6$ (run 1) and $6.3 \times 10^{10}$ erg cm$^{-2}$ s$^{-1}$ (run 2) in their two cases. Their initial condition was an equilibrium, subject to optically thin radiative losses, and gravity. The semi-circular loop had a full length of $L = 38$ Mm, temperature and pressure $T = 3 \times 10^6$ K, and $p_0 = 6$ erg cm$^{-3}$, at the loop apex. Their simulation solved single-fluid hydrodynamic equations with temperature-dependent ionization of hydrogen.

Figure 13, reproduced from Peres & Reale (1993), shows the time evolution of run 1 done with zero viscosity. The ES, propagating upward until after $t = 40$ s, is seen clearly due to the low viscosity. The curves from $t = 30$ s are used to deduce properties of the shock, including pre-shock and post-shock density, $n_1$ and $n_2$, and evaporation velocity $v_e$. The values found are listed in Table 1 and plotted as diamonds in Figures 10 and 11. Peres & Reale (1993) report, in a table, $T_{\text{shock}} = 4.2 \times 10^7$ and $v_e = 750$ km s$^{-1}$ for run 2. Since they provide no plot analogous to our Figure 13 for that run, however, we could not deduce $R_e$ or $v_e$.

One of the earliest simulations of a flaring loop was done by Cheng et al. (1983) using the NRL Dynamic Flux Tube Model (Boris et al. 1980). This code solves quasi-neutral gas dynamics equations for a fully ionized plasma with distinct electron and ion temperatures. There is no viscosity. The electrons are heated directly by an ad hoc source with a Gaussian profile with full width $2$ Mm. The heating is increased linearly with time so that the energy flux, defined according to Equation (32), is $F = (4 \times 10^6$ erg cm$^{-2}$ s$^{-1}$). The tube is quite short, with full length $L = 10$ Mm between the chromospheric feet of the semi-circular loop. The state at $t = 4.95$ s, shown in their Figures 4 and 6, clearly shows an ES structure from which we deduce shock properties. We list these values in Table 1 and plot them as squares in Figures 10 and 11.

Emslie & Nagai (1985) simulate a flaring loop energized by either a beam of non-thermal electrons or a direct ad hoc heating. They use the code reported in Nagai (1980) solving single-fluid
equations with temperature-dependent ionization of hydrogen, viscosity, and a sophisticated treatment of thermal conduction. The case with ad hoc heating, applicable to our present study, has a loop-top Gaussian profile of full width 4.8 Mm, which ramps up linearly as \( F = (6.7 \times 10^8 \text{ erg cm}^{-2} \text{s}^{-2}) t \). With a total length \( L = 22 \text{ Mm} \), their semi-circular loop is twice as long as that of Cheng et al. (1983). From their Figures 7 and 8, showing the state of the simulation, we can deduce the properties of the shock at \( t = 10 \) and 20 s. These values are Table 1 and plotted as triangles in Figures 10 and 11.

Finally, MacNeice (1986) performed a simulation with very high spatial resolution of a flare heated by a loop-top Gaussian profile (7 Mm wide) with constant heat flux \( F = 10^9 \text{ erg cm}^{-2} \text{s}^{-1} \). His Figure 7 shows the state of the simulation at a set of times. We use the latest time shown \( (t = 13.75 \text{ s}) \) to deduce properties of the evaporation which are plotted as pentagons in Figures 10 and 11. This very low evaporation velocity appears to follow the departing trend attributed above to a low energy flux.

6. DISCUSSION

The foregoing has used simplified numerical experiments to study the process of conduction-driven chromospheric evaporation and condensation. This led to an analytic model which followed from the simplified scenario of the thermal conduction front leaving the density jump of the initial TR at a uniform temperature. The analytic solution of this isothermal Riemann problem, depicted in Figure 5, predicts an ES whose Mach number, and thus density jump, depends only on the temperature. The analytic solution and condensation. This led to an analytic model which followed from the simplified scenario of the thermal conduction front leaving the density jump of the initial TR at a uniform temperature. The analytic solution of this isothermal Riemann problem, depicted in Figure 5, predicts an ES whose Mach number, and thus density jump, depends only on the temperature. The analytic solution and condensation. This led to an analytic model which followed from the simplified scenario of the thermal conduction front leaving the density jump of the initial TR at a uniform temperature. The analytic solution of this isothermal Riemann problem, depicted in Figure 5, predicts an ES whose Mach number, and thus density jump, depends only on the temperature.
for example, by reconnection-generated shocks. Future work is aimed at verifying this as well as investigating the effect that evaporation has on the reconnection and its shocks.

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APPENDIX
NEGLIGENCE EFFECT OF IONIZATION

The foregoing shows how energy input from an ad hoc source, standing in for flare reconnection, heats and accelerates plasma from the chromosphere. In order to simplify the model, complete ionization was assumed, even of the chromospheric plasma. This assumption leads to an over-estimate of the final temperature achieved, $T_f$, since the energy required to achieve full ionization would reduce the amount available for heating and acceleration. This under-estimate is, however, relatively small and neglecting it leads to a relatively small error.

To estimate the magnitude of the error we consider only that portion of the specific energy, $\varepsilon_{\text{ion}} = c_v^{(i)} T_v$, required by the condensation shock (CS) to heat the material from its initial chromospheric state. Here $c_v^{(i)} = (3/2) k_f / \rho m$ is the specific heat when fully ionized, and the initial temperature is set to zero since $T_v \gg T_{ch0}$. Had that same specific energy, $\varepsilon_{\text{ion}}$, been devoted to both heating and ionizing the plasma, the final temperature achieved would be lower by $\Delta T_{\text{ion}} = \varepsilon_{\text{ion}} / c_v^{(i)}$, where $\varepsilon_{\text{ion}}$ is the energy required to fully ionize a unit mass of chromospheric plasma. The energy required to heat the extra electrons is already accounted for by using $c_v^{(i)}$ for the specific heat throughout the ionization process.

We estimate the ionization energy using the fairly conservative approach of considering only hydrogen and helium, whose mass fractions we denote $X = 0.74$ and $Y = 0.25$, respectively, but counting the energy required to ionize both from purely neutral ground states. The ionization energy under this scenario is

$$\varepsilon_{\text{ion}} = X \frac{\chi_x}{m_p} + Y \frac{\chi_h}{4m_p} = \frac{15.1 \text{ eV}}{m_p},$$

where the energy to fully ionize an atom from its neutral ground state is $\chi_x = 13.6$ eV for hydrogen and $\chi_h = 24.6 + 54.4 = 79$ eV for helium. The energy removed by ionization thus lowers the final temperature of the CS by

$$\Delta T_{\text{ion}} = \frac{\varepsilon_{\text{ion}}}{c_v^{(i)}} = \frac{2}{3 m_p} \frac{15.1 \text{ eV}}{\chi_n} = 69,000 \text{ K.}$$

Since the final temperature of the CS is well over $2 \times 10^6$ K in the simplified runs, the error from neglecting ionization is less than 5%.

To test the foregoing assertion we run a numerical experiment with a specific heat designed to remove energy similar to ionization. The simulation solves Equations (1)–(3) as before except with specific heat

$$c_v(T) = c_v^{(i)} + \varepsilon_{\text{ion}} f(T) = c_v^{(i)} \left[1 + \Delta T_{\text{ion}} f(T) \right],$$

with $\Delta T_{\text{ion}}$ given by Equation (A2). The function $f(T)$ expresses the distribution of ionization temperatures and is defined to integrate to unity. It should peak at temperatures where each species is being predominately ionized. Motivated by the description above, however, we use a simple version

$$f(T) = \frac{1}{\sigma_T} \text{sech}^2 \left(\frac{T - T_0}{\sigma_T} \right),$$

with a single peak of width $\sigma_T = 80,000$ K centered at $T_0 = 250,000$ K. This removes all energy attributable to ionization, i.e., $\varepsilon_{\text{ion}}$, as the plasma is raised from its chromospheric temperature, $T_{ch0} = 20,000$ K to the CS temperature $> 10^8$ K. The function is designed to do this gradually enough to be easily resolved by the simulation.

Aside from replacing Equation (5), where $c_v = c_v^{(i)}$, with the modified form in Equation (A3), the simulation is exactly the one performed for Figure 4, with $L = 53$ Mm, $F = 3.5 \times 10^{10}$. The result, plotted along the bottom row (d) of Figure 12 is virtually indistinguishable from the case with $c_v = c_v^{(i)}$. To produce any noticeable effect it is necessary to artificially raise the ionization energy, $\varepsilon_{\text{ion}}$, by a factor of ten. Doing so raises the density in the immediate vicinity of the CS, but otherwise leaves the solution unchanged. The conclusion is that ionization, had it been legitimately included, would not have had an appreciable effect on the evaporation or condensation flows we have studied here.

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