DETERMINING MODES FOR THE SURFACE QUASI-GEOSTROPHIC EQUATION

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ABSTRACT. We introduce a determining wavenumber for the surface quasi-geostrophic (SQG) equation defined for each individual trajectory and then study its dependence on the force. While in the subcritical and critical cases this wavenumber has a uniform upper bound, it may blow up when the equation is supercritical. A bound on the determining wavenumber provides determining modes, which in some sense measure the number of degrees of freedom of the flow, or resolution needed to describe a solution to the SQG equation.

KEY WORDS: Surface quasi-geostrophic equation, determining modes, global attractor, De Giorgi method.
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1. INTRODUCTION

In this paper we introduce a determining wavenumber $\Lambda_\theta(t)$ for the forced surface quasi-geostrophic (SQG) equation

\[
\frac{\partial \theta}{\partial t} + u \cdot \nabla \theta + \nu \Lambda^\alpha \theta = f,
\]

\[
u = R^\perp \theta,
\]

on the torus $\mathbb{T}^2 = [0, L]^2$, where $0 < \alpha < 2$, $\nu > 0$, $\Lambda = \sqrt{-\Delta}$ is the Zygmund operator, and $R^\perp \theta = \Lambda^{-1}(-\partial_2 \theta, \partial_1 \theta)$.

The scalar function $\theta$ represents the potential temperature and the vector function $u$ represents the fluid velocity. The initial data $\theta(0) \in L^2(\mathbb{T}^2)$ and the force $f \in L^p(\mathbb{T}^2)$ for some $p > 2/\alpha$ are assumed to have zero average.

The wavenumber $\Lambda_\theta(t)$ is defined solely based on the structure of the equation, but not on the force, regularity properties, or any known bounds on the solution. We prove that if two complete weak solutions $\theta_1, \theta_2 \in L^\infty((-\infty, \infty); L^2)$ (i.e., lying on the global attractor) coincide on frequencies below $\max\{\Lambda_{\theta_1}, \Lambda_{\theta_2}\}$, then $\theta_1 \equiv \theta_2$. While in the subcritical and critical cases this wavenumber has uniform upper bounds, it may blow up when the equation is supercritical. A bound on $\Lambda_\theta$ immediately provides determining modes, which in some sense measure the number of degrees of freedom of the flow, or resolution needed to describe a solution to the SQG equation.

The first result of finite dimensionality of a flow was obtained by Foias and Prodi for the 2D Navier-Stokes equations (NSE) in [24], where it was shown that low modes control high modes asymptotically as time goes to infinity. Then an explicit estimate on the number of determining modes was obtained by Foias, Manley, Temam, and Treve in [23], and improved by Jones and Titi in [30]. A related result, the finite dimensionality of the global

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attractor of the 2D NSE, was first proved by Foias and Temam in [25] (see Constantin, Foias, and Temam [12] for the best available bound). See also [11, 21, 22, 26, 27] and references therein for more results in this direction.

Equation (1.1) with \( \alpha = 1 \) describes the evolution of the surface temperature field in a rapidly rotating and stably stratified fluid with potential velocity [13]. Being applicable in atmosphere and oceanography, this model is also very interesting from the mathematical point of view. Indeed, the behavior of solutions to (1.1) with \( \kappa = 0 \) in 2D and the behavior of potentially singular solutions to the Euler’s equation in 3D have been found similar both analytically and numerically (see [9, 13, 17, 33] and the references therein). Since \( L^\infty \), the highest controlled norm, is critical when \( \alpha = 1 \), equation (1.1) is referred as supercritical, critical and subcritical SQG for \( 0 < \alpha < 1 \), \( \alpha = 1 \) and \( \alpha > 1 \) respectively.

The global regularity problem of the critical SQG equation has been very challenging due to the balance of the nonlinear term and the dissipative term (1.1). This problem is resolved now, with several different proofs and their adaptations to the case of a smooth force available [2, 15, 16, 28, 31, 32].

The long time behavior of solutions to the critical SQG equations have been studied in [6, 10, 14, 15, 20, 34, 35]. The first result on the existence of an attractor was obtained recently by Constantin, Tarfulea, and Vicol in [15], where the authors studied the long time dynamics of regular solutions of the forced critical SQG using the nonlinear maximal principle [16]. With the assumption that the force \( f \in L^\infty(T^2) \cap H^1(T^2) \) and the initial data in \( H^1(T^2) \), the authors proved the existence of a compact attractor, which is a global attractor in the classical sense in \( H^s \) for \( s \in (1, 3/2) \), and it attracts all the points (but not bounded sets) in \( H^1 \). Moreover, the authors proved that the attractor has a finite box-counting dimension.

Later, Cheskidov and Dai [6] proved that the critical SQG equation (1.1) with \( \alpha = 1 \) possesses a global attractor in \( L^2(T^2) \), provided the force \( f \) is solely in \( L^p \) for \( p > 2 \). As the first step, it is established that for any initial data in \( L^2 \) a weak (viscosity) solution is bounded in \( L^\infty \) on any interval \([t_0, \infty), t_0 > 0 \). The main tool is an application of the De Giorgi iteration method to the forced critical SQG as it was done by Caffarelli and Vasseur in [2] in the unforced case. This is the only part that requires the force to be in \( L^p \) for some \( p > 2 \). Second, in the spirit of [5], the Littlewood-Paley decomposition technique is used to show that bounded weak solutions have zero energy flux and hence satisfy the energy equality. The energy equality immediately implies the continuity of weak solutions in \( L^2 \).

In the third step, an abstract framework of evolutionary systems introduced by Cheskidov and Foias [7] was followed to show the existence of a weak global attractor. Finally, with all the above ingredients at hand, an abstract result established by Cheskidov in [4] was applied to prove that the weak global attractor is in fact a strongly compact strong global attractor.

In a very recent paper [10], Constantin, Coti Zelati, and Vicol showed that the \( H^1 \) attractor obtained in [15] is indeed a global attractor in the classical sense, i.e., it attracts bounded sets in \( H^1 \). The main ingredient here is an estimate of a \( C^\alpha \) norm of a solution in terms of the \( L^\infty \) norms of the solution and the force, which was done using the Constantin-Vicol nonlinear maximal principle [16]. Since the \( L^\infty \) is known to be bounded thanks to the De Giorgi iteration method, this automatically gives an absorbing ball in \( C^\alpha \), which in turn implies the existence of absorbing balls in \( H^1 \) and \( H^{3/2} \), and hence asymptotic compactness in \( H^1 \). This results in the existence of the \( H^1 \) global attractor.

In this paper we start with introducing a time-dependent determining wavenumber \( \Lambda_\theta(t) \) defined for each individual trajectory \( \theta(t) \) and then study its dependence on \( \alpha \) and \( f \). Given
a weak solution \( \theta(t) \) of the SQG equation, we define
\[
A_{\theta,r}(t) = \min \{ \lambda_q : \lambda_q^{1-\alpha} \| \theta_q \|_r < c_{\alpha,r} \nu, \quad \text{for} \quad r \in I_{\alpha} \}
\]
for \( r \in I_{\alpha} \). Here \( \lambda_q = \frac{q}{p} \), \( \theta_q = \Delta q \theta \) is the Littlewood-Paley projection of \( \theta \) (see Section 2), and
\[
c_{\alpha,r} = \begin{cases} \frac{c_0}{\alpha^2 (r+1)^2} \left( 1 - 2\frac{\alpha - 2}{\alpha - 1} \frac{\alpha^{\frac{\alpha-1}{2}}}{\alpha^{\frac{\alpha-1}{2}}} \right) \frac{1}{2} & , \quad 0 < \alpha \leq 1, \\ c_0 (\alpha - 1)^2 \left( 1 - 2\frac{\alpha - 2}{\alpha - 1} \frac{\alpha^{\frac{\alpha-1}{2}}}{\alpha^{\frac{\alpha-1}{2}}} \right) & , \quad 1 < \alpha < 2, \\ \end{cases}
\]
for some absolute adimensional constant \( c_0 \). Actually, the unit for \( c_0 \) is \( [c_0] = [\theta]/[\nu] \), but the SQG equation (1.1) is written so that \( \theta \) and \( \nu \) have the same unit.

The first part in the definition of \( A \) resembles the dissipation wavenumber introduced by Cheskidov and Shvydkoy in [8] for the 3D Navier-Stokes equation, also defined in terms of a critical norm, but \( L^\infty \) based, i.e., the smallest one. In [8] it was shown that in some sense the linear term is dominant above that wavenumber. More precisely, it is enough to control a weak solution of the 3D Navier-Stokes equations in the inertial range, i.e., below the dissipation wavenumber, in order to ensure regularity. The dissipation wavenumber was also adapted to the supercritical SQG by Dai in [19], where the smallest critical norm was used as well.

Clearly, the determining wavenumber is much more restrictive than the dissipation wavenumber. First, a larger critical norm appears in the first condition of the definition of \( A_{\theta,r} \). Second, \( A_{\theta,r} \) not only controls high modes, but also low modes, as can be seen in the second condition. From the mathematical point of view, this is due to the fact that there are more terms to control and less cancellations in this setting.

In the first part of the paper we show that \( A \) is indeed a determining wavenumber.

**Theorem 1.1.** Let \( \alpha \in (0,2) \) and \( \theta_1(t) \) and \( \theta_2(t) \) be weak solutions of the SQG equation (1.1). Let \( A(t) = \max \{ A_{\theta_1,r}(t), A_{\theta_2,r}(t) \} \) for some \( r \in I_{\alpha} \). If
\[
\theta_1(t)_{\leq A(t)} = \theta_2(t)_{\leq A(t)}, \quad \forall t > 0,
\]
then
\[
\lim_{t \to \infty} \| \theta_1(t) - \theta_2(t) \|_{B^l_{1,1}} = 0,
\]
where \( l = \alpha (r + 1)/2 \) when \( \alpha \in (0,1] \), and \( l = 2\alpha/(\alpha - 1) \) when \( \alpha \in (1,2) \).

Moreover, if \( \theta_1(t) \) and \( \theta_2(t) \) are two complete (ancient) bounded in \( L^2 \) viscosity solutions, i.e., \( \theta_1, \theta_2 \in L^\infty((-\infty,\infty); L^2) \), and
\[
\theta_1(t)_{\leq A(t)} = \theta_2(t)_{\leq A(t)}, \quad \forall t < T,
\]
for some \( T \in (-\infty,\infty) \), then
\[
\theta_1(t) = \theta_2(t), \quad \forall t < T.
\]

Note that the second part of the theorem implies that for any solutions \( \theta_1(t), \theta_2(t) \) on the attractor \( \mathcal{A} \), we have \( \theta_1 \equiv \theta_2 \) provided \( (\theta_1)_{\leq A} \equiv (\theta_2)_{\leq A} \), where
\[
\mathcal{A} = \{ \theta(0) : \theta(t) \text{ is a complete bounded solution, i.e., } \theta \in L^\infty((-\infty,\infty); L^2) \}.\]
In [6], Cheskidov and Dai proved that $\mathcal{A}$ is a compact global attractor in the classical sense when $\alpha = 1$. It uniformly attracts bounded sets in $L^2$, it is the minimal closed attracting set, and it is the $L^2$-omega limit of the absorbing ball $B_{L^2}$. Clearly, this holds in the subcritical case $\alpha > 1$ as well where we also have all the ingredients to apply the framework of evolutionary systems [4]. However, in the supercritical case $\alpha < 1$, we only know the existence of a weak global attractor at this point.

In the second part of the paper, using the De Giorgi iteration method, we extend the $L^\infty$ estimate in [6] to the whole range $\alpha > 0$. This argument requires the force $f$ to be in $L^p$ for some $p > 2/\alpha$ and implies

\begin{equation}
\|\theta\|_\infty \lesssim \|f\|_p^{\nu}, \quad \forall \theta \in \mathcal{A}.
\end{equation}

Note that this estimate holds for all $\alpha > 0$, and it explains the choice of the space $B^0_{l,l}$ in Theorem 1.1. Indeed, thanks to the Littlewood-Paley Theorem or simply the interpolation $\|\theta\|_{B^0_{l,l}} \lesssim \|\theta(t)\|^{1-\frac{2}{l}}\|\theta\|^{\frac{2}{l}}_{L^2}$, the $B^0_{l,l}$ norm of a viscosity solution is bounded on the global attractor. Thus, one can take a limit as the initial time goes to $-\infty$ and show that the difference between two solutions that coincide below $\Lambda$ is zero. On the other hand, the $B^0_{l,l}$ norm enjoys a better estimate than the $L^l$ norm.

Using the $L^\infty$ estimate (1.4) in the subcritical case $\alpha \in (1, 2)$ we show that for some $r$

\begin{equation*}
\Lambda_{\theta,r} \lesssim \left( \frac{\|f\|_2}{(\alpha - 1)^2 \nu^2} \right)^{\frac{1}{\alpha - 1}},
\end{equation*}

for large enough $t$ (or when $\theta \in \mathcal{A}$). Here we took $p = 2$ for simplicity. This gives the following bound on the number of determining modes $N$:

\begin{equation*}
N \lesssim \left( \frac{\|f\|_2^2}{(\alpha - 1)^2 \nu^2} \right)^{\frac{1}{\alpha - 1}}.
\end{equation*}

In the critical case $\alpha = 1$, the $L^\infty$ estimate clearly is not enough to obtain a bound on $\Lambda$. However, combining it with the Hölder estimate $\|\theta(t)\|_{C^h} \lesssim \|\theta(0)\|_\infty + \|f\|_\infty$ for some small $h$ and large $t$, obtained by Constantin, Coti Zelati and Vicol in [10], we show that there exists $r$ such that

\begin{equation*}
\Lambda_{\theta,r} \lesssim \left( \frac{\|f\|_\infty^{\nu}}{\nu^2} \right)^{\frac{1}{\nu^2}},
\end{equation*}

for $t$ large enough, provided $\theta(0) \in H^1$. Extending this estimate to solutions with $L^2$ initial data is an open problem.

2. Preliminaries

2.1. Notations. We denote by $A \lesssim B$ an estimate of the form $A \leq CB$ with some absolute constant $C$, and by $A \sim B$ an estimate of the form $C_1 B \leq A \leq C_2 B$ with some absolute constants $C_1$, $C_2$. We write $\| \cdot \|_p = \| \cdot \|_{L^p}$, and $(\cdot, \cdot)$ stands for the $L^2$-inner product.
2.2. **Littlewood-Paley decomposition.** The techniques presented in this paper rely strongly on the Littlewood-Paley decomposition, which we recall here briefly. For a more detailed description on this theory we refer readers to the books by Bahouri, Chemin and Danchin [1], and Grafakos [29].

Denote $\lambda_q = \frac{2^q}{L}$ for integers $q$. A nonnegative radial function $\chi \in C_0^\infty(\mathbb{R}^n)$ is chosen such that

\[
\chi(\xi) = \begin{cases} 
1, & \text{for } |\xi| \leq \frac{3}{4} \\
0, & \text{for } |\xi| \geq 1.
\end{cases}
\]

Let

\[
\varphi(\xi) = \chi(\xi/2) - \chi(\xi)
\]

and

\[
\varphi_q(\xi) = \begin{cases} 
\varphi(2^{-q}\xi), & \text{for } q \geq 0, \\
\chi(\xi), & \text{for } q = -1.
\end{cases}
\]

For a tempered distribution vector field $u$ we define its Littlewood-Paley projection $u_q$ in the following way:

\[
h_q = \sum_{k \in \mathbb{Z}^n} \varphi_q(k)e^{i\frac{2\pi}{L}k \cdot x}
\]

\[
u_q := \Delta_q u = \sum_{k \in \mathbb{Z}^n} \hat{u}_k \varphi_q(k)e^{i\frac{2\pi}{L}k \cdot x} = \frac{1}{L^2} \int_{\mathbb{R}^n} h_q(y)u(x - y)dy, \quad q \geq -1,
\]

where $\hat{u}_k$ is the $k$th Fourier coefficient of $u$. Then

\[
u = \sum_{q=-1}^{\infty} \nu_q
\]

in the sense of distributions. To simplify the notation, we denote

\[u_{\leq Q} = \sum_{q=-1}^{Q} \nu_q, \quad u_{(Q,R]} = \sum_{p=Q+1}^{R} \nu_p, \quad \tilde{u}_q = \sum_{|p-q| \leq 1} \nu_p.
\]

We will also use the Besov $B_{l,l}^0$ norm defined as

\[
\|u\|_{B_{l,l}^0} = \left( \sum_{q=-1}^{\infty} \|\nu_q\|_l^l \right)^{\frac{1}{l}}.
\]

The following inequalities will be used throughout the paper:

**Lemma 2.1.** (Bernstein’s inequality) Let $n$ be the space dimension and $r \geq s \geq 1$. Then for all tempered distributions $u$,

\[
\|u_q\|_r \leq \lambda_q^{n(\frac{1}{r} - \frac{1}{s})} \|u_q\|_s.
\]

**Lemma 2.2.** Assume $2 < l \leq \infty$ and $0 \leq \alpha \leq 2$. Then

\[
l \int |u_q \Lambda^\alpha u_q| |u_q|^{l-2} \, dx \geq \lambda_q^\alpha \|u_q\|_l^l.
\]

For a proof of Lemma 2.2 see [3][18].
2.3. Bony’s paraproduct and commutator. Bony’s paraproduct formula will be used to decompose the nonlinear term. First, note that
\[ u \cdot \nabla v = \sum_{p} u_{p-2} \cdot \nabla v_{p} + \sum_{p} u_{p} \cdot \nabla v_{p-2} + \sum_{p} \sum_{|p-p'| \leq 1} u_{p} \cdot \nabla v_{p'}. \]
Due to (2.5) we have \( \varphi(\xi) = 0 \) when \( |\xi| \leq 3/4 \) or \( |\xi| \geq 2 \), and hence
\[ (f_{q} g_{q-2})_{\geq q} = 0, \quad (f_{q} g_{q-3})_{\leq q-2} = 0, \quad (f_{q} g_{q+1})_{\geq q+3} = 0, \]
for tempered distributions \( f \) and \( g \). Therefore,
\[ \Delta_q (u \cdot \nabla v) = \sum_{q-1 \leq p \leq q+2} \Delta_q (u_{p-2} \cdot \nabla v_{p}) + \sum_{q-1 \leq p \leq q+2} \Delta_q (u_{p} \cdot \nabla v_{p}) \]
\[ + \sum_{p \geq q-2} \sum_{|p-p'| \leq 1} \Delta_q (u_{p} \cdot \nabla v_{p'}). \]
It is usually sufficient to use a weaker form of this formula:
\[ \Delta_q (u \cdot \nabla v) = \sum_{|q-p| \leq 2} \Delta_q (u_{p-2} \cdot \nabla v_{p}) + \sum_{|q-p| \leq 2} \Delta_q (u_{p} \cdot \nabla v_{p}) \]
\[ + \sum_{p \geq q-2} \Delta_q (u_{p} \cdot \nabla v_{p}). \]
We will also use the notation of the commutator
\[ (\Delta_q, u_{p-2} \cdot \nabla) v_{p} := \Delta_q (u_{p-2} \cdot \nabla v_{p}) - u_{p-2} \cdot \nabla \Delta_q v_{p}. \]
By definition of \( \Delta_q \) we have
\[ [\Delta_q, u_{p-2} \cdot \nabla] v_{p} = \int_{\mathbb{T}^{2}} h_{q}(x - y) (u_{p-2}(y) - u_{p-2}(x)) \nabla v_{p}(y) \, dy \]
\[ = \int_{\mathbb{T}^{2}} \nabla h_{q}(x - y) (u_{p-2}(y) - u_{p-2}(x)) v_{p}(y) \, dy, \]
where we used integration by parts and the fact that \( \text{div} u_{p-2} = 0 \). Thus, by Young’s inequality, for any \( r > 1 \),
\[ \| [\Delta_q, u_{p-2} \cdot \nabla] v_{p} \|_{r} \lesssim \| \nabla u_{p-2} \|_{\infty} \| v_{p} \|_{r} \int_{\mathbb{T}^{2}} |z| \| \nabla h_{q}(z) \| \, dz \]
\[ \lesssim \| \nabla u_{p-2} \|_{\infty} \| v_{p} \|_{r}. \]

3. Proof of the first part of Theorem 1.1

Now we are ready to prove our first main result, which holds for all weak solutions of the SQG equation, even the ones that might not satisfy the energy inequality.

**Definition 3.1.** A weak solution to (1.1) is a function \( \theta \in C_{w}([0, T]; L^{2}([T^{2}]), \text{zero spatial average that satisfies (1.1) in a distributional sense. That is, for any } \phi \in C_{0}^{\infty}([T^{2} \times (0, T)), \)
\[ - \int_{0}^{T} (\theta, \phi_{t}) dt - \int_{0}^{T} (\theta, \nabla \phi) dt + \nu \int_{0}^{T} (\Lambda^{\frac{p}{2}} \theta, \Lambda^{\frac{p}{2}} \phi) dt = (\theta_{0}, \phi(0, 0)) + \int_{0}^{T} (f, \phi) dt. \]
Theorem 3.2. Let $\alpha \in (0, 2)$, and $\theta_1(t), \theta_2(t)$ be weak solutions of the SQG equation (1.1). Let $\Lambda(t) = \max\{A_{\theta_1,r}(t), A_{\theta_2,r}(t)\}$ for some $r \in I_\alpha$. Let

\[
\Lambda(t) = \max\{\Lambda_{\theta_1}(t), r(t), \Lambda_{\theta_2}(t), r(t)\}
\]

for some $r \in I_\alpha$. Let

\[
l = \begin{cases} 
\frac{\alpha(r + 1)}{2}, & 0 < \alpha \leq 1, \\
\frac{2\alpha}{\alpha - 1}, & 1 < \alpha < 2.
\end{cases}
\]

If

\[
\theta_1(t) \leq \Lambda(t) = \theta_2(t) \leq \Lambda(t), \quad \forall t \in (T_1, T_2),
\]

then

\[
\|\theta_1(t) - \theta_2(t)\|_{B^{l}_{\alpha}} \leq \|\theta_1(t_0) - \theta_2(t_0)\|_{B^{l}_{\alpha}} e^{-\frac{\nu}{\Lambda_{\alpha/l}}(t-t_0)}, \quad \forall T_1 \leq t_0 \leq t \leq T_2,
\]

where $c$ is an absolute constant.

Proof. Denote $u_1 = R^\perp \theta_1$ and $u_2 = R^\perp \theta_2$. Let $w = \theta_1 - \theta_2$, which satisfies the equation

\[
w_t + u_1 \cdot \nabla w + \nu \Lambda^\alpha w + R^\perp w \cdot \nabla \theta_2 = 0
\]

in the sense of distributions. By our assumption $w \leq \Lambda(t) = 0$ for $t \in (T_1, T_2)$. Recall that

\[
I_\alpha = \begin{cases} 
\left(\frac{4}{\alpha} - 1, \infty\right), & 0 < \alpha \leq 1, \\
\left(\frac{2\alpha}{\alpha - 1}, \frac{4}{\alpha} - 1\right), & 1 < \alpha < 2.
\end{cases}
\]

Combining $r \in I_\alpha$ with (3.8) one can verify that the conditions

\[
2 \leq l \leq r < \frac{2l}{\alpha}, \quad \frac{2r}{r + \frac{\alpha}{l}} > \alpha - 1, \quad 1 + \frac{2}{r} - \frac{\alpha}{l} > 0
\]

are satisfied. These inequalities will be used throughout the proof.

Projecting equation (3.11) onto the $q$-th shell, multiplying it by $l w_q |w_q|^{l-2}$, integrating, adding up for all $q \geq -1$, and applying Lemma 2.2 yields

\[
\|w(t)\|_{B^{l}_{\alpha}}^l - \|w(t_0)\|_{B^{l}_{\alpha}}^l + C \nu \int_{t_0}^t \|\Lambda^\alpha w\|_{B^{l}_{\alpha}}^l \, d\tau \leq
\]

\[
- \int_{t_0}^t l \sum_{q \geq -1} \int_{\mathbb{R}^3} \Delta_q (R^\perp w \cdot \nabla \theta_2) w_q |w_q|^{l-2} \, dx \, d\tau
\]

\[
- \int_{t_0}^t l \sum_{q \geq -1} \int_{\mathbb{R}^3} \Delta_q (u_1 \cdot \nabla w) w_q |w_q|^{l-2} \, dx \, d\tau
\]

\[
= \int_{t_0}^t I \, d\tau + \int_{t_0}^t J \, d\tau,
\]

(3.13)
for all \( T_1 \leq t_0 \leq t \leq T_2 \). Using Bony’s paraproduct mentioned in Subsection 2.3, \( I \) is decomposed as

\[
I = - l \sum_{q \geq -1} \sum_{|q-p| \leq 2} \int_{\mathbb{R}^3} \Delta_q \left( R^{\frac{1}{l}} w_{\leq p-2} \cdot \nabla (\theta_2)_p \right) w_q |w_q|^{l-2} \, dx
- l \sum_{q \geq -1} \sum_{|q-p| \leq 2} \int_{\mathbb{R}^3} \Delta_q \left( R^{\frac{1}{l}} w_p \cdot \nabla (\theta_2)_{\leq p-2} \right) w_q |w_q|^{l-2} \, dx
- l \sum_{q \geq -1} \sum_{p \geq q-2} \int_{\mathbb{R}^3} \Delta_q \left( R^{\frac{1}{l}} \tilde{w}_p \cdot \nabla (\theta_2)_p \right) w_q |w_q|^{l-2} \, dx
= I_1 + I_2 + I_3.
\]

These terms are estimated as follows. First, recall \( w_{\leq \Lambda(t)} = 0 \). Let \( Q(t) \) be such that \( \Lambda(t) = 2^Q(t)/L \). Since \( r \geq l \), we can choose \( m \) so that \( \frac{1}{r} + \frac{1}{m} + \frac{l-1}{m} = 1 \). Changing the order of summations and using Hölder’s inequality, we infer

\[
|I_1| \leq l \sum_{q > Q} \sum_{|q-p| \leq 2} \int_{\mathbb{R}^3} |\Delta_q \left( R^{\frac{1}{l}} w_{\leq p-2} \cdot \nabla (\theta_2)_p \right) w_q| |w_q|^{l-2} \, dx
= l \sum_{p > Q+2} \sum_{|q-p| \leq 2} \int_{\mathbb{R}^3} |\Delta_q \left( R^{\frac{1}{l}} w_{\leq p-2} \cdot \nabla (\theta_2)_p \right) w_q| |w_q|^{l-2} \, dx
\lesssim l \sum_{p > Q+2} \lambda_p \| (\theta_2)_p \|_r \sum_{|q-p| \leq 2} \sum_{q > Q} \| w_q \|_l^{l-1} \sum_{p' \leq p-2} \| R^{\frac{1}{l}} w_{p'} \|_m.
\]

Then using the definition of \( \Lambda_{\theta,r} \), Young’s inequality, Jensen’s inequality and the fact that \( \| R^{\frac{1}{l}} w_q \|_l \lesssim \| w_q \|_l \), we obtain

\[
|I_1| \lesssim c_{\alpha,r} l \sum_{p > Q+2} \lambda_p^{\alpha - \frac{2}{l}} \sum_{|q-p| \leq 2} \| w_q \|_l^{l-1} \sum_{p' \leq p-2} \lambda_{p'}^{\frac{2}{l} - \frac{2}{r}} \| R^{\frac{1}{l}} w_{p'} \|_l
\lesssim c_{\alpha,r} l \sum_{p > Q} \lambda_p^{\alpha - \frac{2}{l}} \| w_p \|_l^{l-1} \sum_{p' \leq p-2} \lambda_{p'}^{\frac{2}{l} - \frac{2}{r}} \| R^{\frac{1}{l}} w_{p'} \|_l
\lesssim c_{\alpha,r} l \sum_{p > Q} \lambda_p^{\alpha \theta} \| w_p \|_l^{l-1} \sum_{p' \leq p-2} \lambda_{p'}^{\frac{2}{l} - \frac{2}{r}} \| R^{\frac{1}{l}} w_{p'} \|_l \lambda_{p'}^{\alpha \theta - \frac{2}{r}}
\lesssim c_{\alpha,r} l \sum_{p > Q} \lambda_p^{\alpha \theta} \| w_p \|_l + c_{\alpha,r} l \sum_{p > Q} \left( \sum_{p' \leq p-2} \lambda_{p'}^{\frac{2}{l} - \frac{2}{r}} \| R^{\frac{1}{l}} w_{p'} \|_l \lambda_{p'}^{\alpha \theta - \frac{2}{r}} \right)^l
\lesssim c_{\alpha,r} l \left( 1 - 2^{\frac{2}{l} - \frac{2}{r}} \right)^{-1} \sum_{q > Q} \lambda_q^{\alpha \theta} \| w_q \|_l.
\]
where we needed \( r < 2l/\alpha \) in order to apply Jensen’s inequality at the last step. For \( I_2 \) we first change the order of summations and decompose it into two parts:

\[
|I_2| \leq l \sum_{p > Q} \sum_{q > Q} \left| \int_{R^3} \left| \Delta_q (R^+ w_p \cdot \nabla (\theta_2)_{p \leq p - 2}) w_q \right| |w_q|^{l-2} \, dx \right|
\]

\[
\leq l \sum_{p > Q} \sum_{q > Q} \left| \int_{R^3} \left| \Delta_q (R^+ w_p \cdot \nabla (\theta_2)_{q \leq Q}) w_q \right| |w_q|^{l-2} \, dx \right|
\]

\[
+ l \sum_{p > Q+2} \sum_{q > Q} \left| \int_{R^3} \left| \Delta_q (R^+ w_p \cdot \nabla (\theta_2)_{(Q,p - 2)}) w_q \right| |w_q|^{l-2} \, dx \right|
\]

\[
eq I_{21} + I_{22}.
\]

Using Hölder’s inequality, definition of \( \Lambda_{\theta,r} \), and Young’s inequality for the first term, we obtain

\[
I_{21} \lesssim l \sum_{p > Q} \sum_{q > Q} \| \nabla (\theta_2) \|_Q \| R^+ w_p \|_l \| w_q \|_l^{l-1}
\]
Since $r \geq l \geq 2$, we can choose $m$ so that $\frac{1}{r} + \frac{1}{m} + \frac{1}{l} = 1$. To estimate $I_3$ we first integrate by parts, change the order of summations, and use Hölder’s inequality:

$$|I_3| \leq \sum_{p > Q} \sum_{q > Q} \sum_{p > Q} \int_{\mathbb{R}^3} |\Delta_q (R^l \tilde{w}_p (\theta_2)_p) \nabla (w_q |w_q|^{l-2})| \, dx$$

$$\leq \sum_{p > Q} \sum_{q > Q} \sum_{p > Q} \int_{\mathbb{R}^3} |\Delta_q (R^l \tilde{w}_p (\theta_2)_p) \nabla w_q| |w_q|^{l-2} \, dx$$

$$\leq \sum_{p > Q} \sum_{q > Q} \sum_{p > Q} \int_{\mathbb{R}^3} |\Delta_q (R^l \tilde{w}_Q (\theta_2)_Q) \nabla w_q| |w_q|^{l-2} \, dx$$

$$+ \sum_{p > Q} \sum_{q > Q} \sum_{p > Q} \int_{\mathbb{R}^3} |\Delta_q (R^l \tilde{w}_p (\theta_2)_p) \nabla \nabla w_q| |w_q|^{l-2} \, dx$$

Then using definition of $\Lambda_{\theta_2, r}$ and Jensen’s inequality, we get

$$|I_3| \lesssim c_{\alpha, r} \nu l^2 \sum_{p > Q} \lambda_p^{1-\frac{2}{r}} \|R^l \tilde{w}_p\|_l \sum_{q < p \leq p+2} \lambda_q^{1+(l-1)\frac{\alpha}{r} - \frac{2}{r} - \frac{2}{r}} \|w_q\|_{l}^{l-1}$$

$$+ c_{\alpha, r} \nu l^2 \sum_{q < Q \leq Q+2} \lambda_q^{1-1} \|w_q\|_l \sum_{q < p \leq p+2} \lambda_q \|w_q\|_{l}^{l-1}$$

$$\lesssim c_{\alpha, r} \nu l^2 \sum_{p > Q} \lambda_p^{\frac{\alpha}{r}} \|w_p\|_l \sum_{q < p \leq p+2} \lambda_q^{\frac{\alpha}{r} - a - 1} \|w_q\|_{l}^{l-1} \lambda_q^{\frac{\alpha}{r} - \frac{2}{r} - \frac{2}{r}}$$

$$+ c_{\alpha, r} \nu l^2 \sum_{Q < q \leq Q+2} \lambda_q^{\frac{\alpha}{r}} \|w_q\|_l$$

$$\lesssim c_{\alpha, r} \nu l^2 \left(1 - 2^{\frac{\alpha}{r} - \frac{2}{r} - \frac{2}{r}}\right)^{-\frac{1}{l}} \sum_{q < Q} \lambda_q^\alpha \|w_q\|_l$$

were we used $\frac{\alpha}{r} + \frac{\alpha}{r} > \alpha - 1$. Therefore, we have

$$|I| \lesssim c_{\alpha, r} \nu l^2 \left[\left(1 - 2^{\frac{\alpha}{r} - \frac{2}{r}}\right)^{-l} + \left(1 - 2^{\alpha - 1 - \frac{2}{r} - \frac{2}{r}}\right)^{-\frac{1}{l}} \sum_{q > Q} \lambda_q^\alpha \|w_q\|_l^{l}\right]$$

(3.14) $\lesssim c_{\alpha, r} \nu l^2 \left(1 - 2^{\frac{\alpha}{r} - \frac{2}{r}}\right)^{-l} \sum_{q > Q} \lambda_q^\alpha \|w_q\|_l^{l}$

due to the choice of the parameters $l$ and $r$ as in (3.8) and (3.12).
Thus, the term $u_1 \leq q - 2$ can be estimated as $J_1 + J_2 + J_3$. Thanks to (2.7), $J_1$ can be decomposed as

\[
J_1 = \int_{\mathbb{R}^3} \sum_{q \geq 1} \sum_{|q - p| \leq 2} \Delta_q ((u_1)_{|p - 2} \cdot \nabla) w_p |w_q|^2 \, dx
\]

Using the commutator notation (2.6), where we used the fact that $\sum_{|p - q| \leq 2} \Delta_q w_p = w_q$. Notice that we have $J_{12} = 0$, since $\text{div} (u_1_{|q - 2} = 0$. Thanks to (2.7),

$$|||\Delta_q, (u_1)_{|p - 2} \cdot \nabla|w_p||_i \lesssim |||\nabla (u_1)_{|p - 2}||_\infty ||w_p||_i.$$  

Thus, the term $J_{11}$ can be estimated as

$$|J_{11}| \leq \int_{\mathbb{R}^3} \sum_{q > Q} \sum_{|q - p| \leq 2} \Delta_q ((u_1)_{|p - 2} \cdot \nabla) w_p |w_q|^2 \, dx$$

$$\leq \int_{\mathbb{R}^3} \sum_{q > Q} \sum_{|q - p| \leq 2} |\Delta_q (u_1)_{|q} \cdot \nabla|w_p||_i |w_q||_i^2 \, dx$$

$$\leq \int_{\mathbb{R}^3} \sum_{q > Q} \sum_{|q - p| \leq 2} \|\nabla (u_1)_{|q}||_\infty |w_p||_i |w_q||_i^2 \, dx$$

$$+ \int_{\mathbb{R}^3} \sum_{q > Q} \sum_{|q - p| \leq 2} \|\nabla (u_1)_{|q}||_\infty |w_p||_i |w_q||_i^2 \, dx$$

$$= J_{11} + J_{12}.$$  

For the first term we use Hölder’s and Bernstein’s inequalities,

$$J_{11} \lesssim \int_{\mathbb{R}^3} \sum_{q > Q} \sum_{|q - p| \leq 2} \sum_{Q < p' \leq q} \lambda_{p'}^2 ||(u_1)_{p'}||_\infty |w_p||_i |w_q||_i^2 \, dx$$

$$\lesssim \int_{\mathbb{R}^3} \sum_{q > Q} \sum_{|q - p| \leq 2} \sum_{Q < p' \leq q} \lambda_{p'}^{1 + \frac{2}{p'}} ||(u_1)_{p'}||_i |w_p||_i |w_q||_i^2 \, dx$$.
and then the fact that $\|u_1\|_r \lesssim \|\theta_1\|_r$, definition of $A_{\rho_1, r}$ to get

$$J_{111} \lesssim c_{\alpha, r} \nu l \sum_{q > Q} \sum_{|q-p| \leq 2} \sum_{p > Q} \|w_p\|_l \|w_q\|_l^{\nu-1} \sum_{Q < p' \leq q} \lambda_{p'}^\alpha$$

$$\lesssim c_{\alpha, r} \nu l \sum_{q > Q} \|w_q\|_l^\nu \sum_{Q < p' \leq q} \lambda_{p'}^\alpha$$

$$\lesssim c_{\alpha, r} \nu l \sum_{q > Q} \|w_q\|_l^\nu \sum_{Q < p' \leq q} \lambda_{p'}^\alpha$$

$$\lesssim c_{\alpha, r} \nu l \sum_{q > Q} \lambda_{Q}^\alpha \|w_q\|_l^{\nu-1}$$

The second term is estimated in a similar way:

$$J_{112} \lesssim l \sum_{q > Q} \sum_{|q-p| \leq 2} \sum_{p > Q} \lambda_{p'}^\nu \|(u_1)_{p'}\|_\infty \|w_p\|_l \|w_q\|_l^{\nu-1}$$

$$\lesssim l \sum_{q > Q} \sum_{|q-p| \leq 2} \sum_{p > Q} \lambda_{p'}^\nu \|(\theta_1)_{p'}\|_\infty \|w_p\|_l \|w_q\|_l^{\nu-1}$$

$$\lesssim c_{\alpha, r} \nu l \sum_{q > Q} \sum_{|q-p| \leq 2} \lambda_{Q}^\nu \|w_p\|_l \|w_q\|_l^{\nu-1}$$

$$\lesssim c_{\alpha, r} \nu l \sum_{q > Q} \lambda_{Q}^\nu \|w_q\|_l^\nu$$

To estimate $J_{13}$, we start with splitting the summation

$$|J_{13}| \leq l \sum_{q > Q} \sum_{|q-p| \leq 2} \int_{\mathbb{R}^3} |((u_1)_{p'} \leq p-2 - (u_1)_{q-2}) \cdot \nabla \Delta_q w_p| \|w_q\|^{\nu-1} \, dx$$

$$\lesssim l \sum_{q > Q} \sum_{|q-p| \leq 2} \int_{\mathbb{R}^3} |(u_1)_{p'}| \|\nabla \Delta_q w_p| \|w_q\|^{\nu-1} \, dx$$

$$\leq l \sum_{q > Q} \sum_{|q-p| \leq 2} \int_{\mathbb{R}^3} |(u_1)_{q-3} \cdot \nabla \Delta_q w_p| \|w_q\|^{\nu-1} \, dx$$

$$+ l \sum_{q > Q} \sum_{|q-p| \leq 2} \sum_{p' > Q} \int_{\mathbb{R}^3} |(u_1)_{p'}| \|\nabla \Delta_q w_p| \|w_q\|^{\nu-1} \, dx$$

$$\equiv J_{131} + J_{132}.$$
followed by definition of $A_{q_1, r}$ and Jensen’s inequality.

\[
J_{131} \lesssim c_{\alpha, r} \nu l \sum_{q > Q} \lambda_q^{\alpha-1} \| w_q \|_l^{l-1} \sum_{|q-p| \leq 2} \sum_{p > Q} \lambda_p \| w_p \|_l
\]

\[
\lesssim c_{\alpha, r} \nu l \sum_{q > Q} \lambda_q^{\alpha-1} \| w_q \|_l^{l-1} \sum_{|q-p| \leq 2} \sum_{p > Q} \lambda_p \| w_p \|_l \lambda_{p-l}^{-\frac{r}{2}}
\]

\[
\lesssim c_{\alpha, r} \nu l \sum_{q > Q} \lambda_q^{\alpha-1} \| w_q \|_l^{l} \sum_{|q-p| \leq 2} \sum_{p > Q} \lambda_p \| w_p \|_l \lambda_{p-l}^{-\frac{r}{2}}
\]

\[
\lesssim c_{\alpha, r} \nu l \sum_{q > Q} \lambda_q^{\alpha-1} \| w_q \|_l.
\]

Since $r \geq l$ we can choose $m$ so that $\frac{1}{m} + \frac{1}{r} + \frac{l-1}{l} = 1$, and estimate the second term as

\[
J_{132} \lesssim I \sum_{q > Q} \| w_q \|_l^{l-1} \sum_{|q-p| \leq 2} \sum_{p > Q} \lambda_p \| w_p \|_m \sum_{q-3 \leq p' \leq q} (u_1)_{p'} \| w_{p'} \|_r
\]

\[
\lesssim c_{\alpha, r} \nu l \sum_{q > Q} \| w_q \|_l^{l-1} \sum_{|q-p| \leq 2} \sum_{p > Q} \lambda_p^{1+\frac{2}{m}} \| w_p \|_l \sum_{q-3 \leq p' \leq q} \lambda_p^{\alpha-1-\frac{r}{2}}
\]

\[
\lesssim c_{\alpha, r} \nu l \sum_{q > Q} \lambda_q^{1+\frac{2}{m}} \| w_q \|_l \sum_{q-3 \leq p' \leq q} \lambda_p^{\alpha-1-\frac{r}{2}}
\]

\[
\lesssim c_{\alpha, r} \nu l \sum_{q > Q} \lambda_q^{\alpha-1} \| w_q \|_l \sum_{q-3 \leq p' \leq q} \lambda_{p'-q}^{\alpha-1-\frac{r}{2}}
\]

\[
\lesssim c_{\alpha, r} \nu l \sum_{q > Q} \lambda_q^{\alpha} \| w_q \|_l.
\]

Again choosing $m$ such that $\frac{1}{r} + \frac{1}{m} + \frac{l-1}{l} = 1$ and using Hölder’s inequality, we obtain

\[
|J_2| \leq I \sum_{q > Q} \| w_q \|_l \sum_{|q-p| \leq 2} \int_{\mathbb{R}^3} |\Delta_q ((u_1)_p \cdot \nabla w_{p-2})| |w_q|^{l-1} \, dx
\]

\[
\leq I \sum_{p > Q+2} \sum_{|q-p| \leq 2} \int_{\mathbb{R}^3} |\Delta_q ((u_1)_p \cdot \nabla w_{p-2})| |w_q|^{l-1} \, dx
\]

\[
\lesssim I \sum_{p > Q+2} \| (u_1)_p \|_r \sum_{|q-p| \leq 2} \| w_q \|_l^{l-1} \sum_{p' \leq q} \lambda_{p'} \| w_{p'} \|_m.
\]
Now we use definition of $A_{q,r}$ and Jensen’s inequality to conclude that

$$|J_2| \lesssim c_{o,r} \nu l \sum_{l > Q+1} \lambda^{l-\frac{q}{r}} \sum_{\nu > Q} \lambda^{\frac{q}{r}-1} \sum_{p' \leq q} \lambda^{\frac{q}{r}+\frac{2}{m}-\frac{q}{r}} w_{p'} \|w_{p'}\|_m$$

$$\lesssim c_{o,r} \nu l \sum_{l > Q} \lambda^{\frac{q}{r}-\frac{q}{r}} \sum_{p' \leq q} \lambda^{\frac{q}{r}+\frac{2}{m}-\frac{q}{r}} w_{p'} \|w_{p'}\|_l$$

$$\lesssim c_{o,r} \nu l \sum_{l > Q} \lambda^{\frac{q}{r}-\frac{q}{r}} \sum_{p' \leq q} \lambda^{\frac{q}{r}+\frac{2}{m}-\frac{q}{r}} w_{p'} \|w_{p'}\|_l$$

$$\lesssim c_{o,r} \nu l \left(1 - 2^{\frac{q}{r}-\frac{q}{r}}\right)^{-l} \sum_{l > Q} \lambda^{\frac{q}{r}} w_{q,l}^l,$$

where we used $1 + \frac{q}{r} - \frac{q}{r} > 0$. Finally, observe that $J_3$ enjoys the same estimate as $J_2$ due to the fact that $\|\lambda_{t+1}\|_{\nu r} \lesssim \|\lambda_t\|_{\nu r}$ for any $r_1 \in (1, \infty)$. Thus

$$|J| \lesssim c_{o,r} \nu \gamma^2 \left(1 - 2^{\frac{q}{r}-\frac{q}{r}}\right)^{-l} \sum_{l > Q} \lambda^{\frac{q}{r}} w_{q,l}^l,$$

(3.15)

where $\gamma$ and $\lambda_q$ yield

$$\|w(t)\|_{B^{l,q}_{p,l}} - \|w(t_0)\|_{B^{l,q}_{p,l}} \leq \int_{t_0}^t \left(-C\nu \|\Lambda^{l,q} w\|_{B^{l,q}_{p,l}} + C_1 c_{o,r} \nu \gamma^2 \left(1 - 2^{\frac{q}{r}-\frac{q}{r}}\right)^{-l} \sum_{l > Q} \lambda^{\frac{q}{r}} w_{q,l}^l \right) d\tau,$$

for some absolute constants $C$ and $C_1$. Recall that

$$l = \begin{cases} \frac{\alpha(r + 1)}{2} & 0 < \alpha \leq 1, \\ \frac{\alpha}{\alpha - 1} & 1 < \alpha < 2, \end{cases} \quad c_{o,r} = \begin{cases} \frac{c_0}{\alpha^2 (r + 1)^2} \left(1 - 2^{\frac{q}{r}-\frac{q}{r}}\right)^{-l} & 0 < \alpha \leq 1, \\ \frac{c_0 (\alpha - 1)^2}{\alpha (\alpha - 1)^2} \left(1 - 2^{\frac{q}{r}-\frac{q}{r}}\right)^{-l} & 1 < \alpha < 2. \end{cases}$$

Hence, choosing $c_0 = \frac{C}{\alpha_2 c_1}$, we arrive at

$$\|w(t)\|_{B^{l,q}_{p,l}} - \|w(t_0)\|_{B^{l,q}_{p,l}} \leq -\frac{C\nu}{2} \int_{t_0}^t \|\Lambda^{l,q} w\|_{B^{l,q}_{p,l}} d\tau \lesssim -\lambda_0 \nu \int_{t_0}^t \|w\|_{B^{l,q}_{p,l}} d\tau$$

for all $T_1 \leq t_0 \leq t \leq T_2$. Combining it with Grönwall’s inequalities gives the desired result.

Clearly, Theorem 3.2 implies the first part of Theorem 1.1. To prove the second part, we need to introduce viscosity solutions and show that the global attractor for such solutions is bounded in $L^\infty$. 


4. $L^\infty$ ESTIMATES

The goal of this section is to obtain an explicit $L^\infty$ bound on viscosity solutions to (1.1) when the force $f$ is in $L^p$ for some $p > 2/\alpha$.

A weak solution $\theta(t)$ on $[0, T]$ is called a viscosity solution if there exist sequences $\epsilon_n \to 0$ and $\theta_n(t)$ satisfying

$$\frac{\partial \theta_n}{\partial t} + u_n \cdot \nabla \theta_n + \nabla^\alpha \Lambda \theta_n + \epsilon_n \Delta \theta_n = f, \quad u_n = R^L \theta_n,$$

(4.16)

such that $\theta_n \to \theta$ in $C_w([0, T]; L^2)$. Standard arguments imply that for any initial data $\theta_0 \in L^2$ there exists a viscosity solution $\theta(t)$ of (1.1) on $[0, \infty)$ with $\theta(0) = \theta_0$ (see [13], for example). The solution $\theta(t)$ may enjoy some regularity depending on the force, but this is not needed for our argument.

In the case of $\alpha = 1$ and zero force, Caffarelli and Vasseur derived a level set energy inequality using a harmonic extension [2]. Here we sketch a modification of the proof from [6] extended to all $\alpha > 0$.

**Lemma 4.1.** Let $\alpha > 0$ and $\theta(t)$ be a viscosity solution to (1.1) on $[0, T]$ with $\theta(0) \in L^2$. Then for every $\lambda \in \mathbb{R}$ it satisfies the level set energy inequality

$$\frac{1}{2} \| \theta(t) \|_2^2 + \nu \int_{0}^{t} \| \Lambda^{2/\alpha} \theta(t) \|_2^2 \, dt \leq \frac{1}{2} \| \theta(t_1) \|_2^2 + \int_{0}^{t} \int_{\mathbb{T}^2} f \theta \, dx \, dt,$$

(4.17)

for all $t_1 \in [t, T]$ and a.e. $t_1 \in [0, T]$. Here $\theta_\lambda = (\theta - \lambda)_+$ or $\theta_\lambda = (\theta + \lambda)_-.$

**Proof.** We only show a priori estimates. It is clear how to pass to the limit in (4.16) as $\epsilon \to 0$. Denote $\varphi(\theta) = (\theta - \lambda)_+$. Note that $\varphi$ is Lipschitz and $\varphi'(\theta) \varphi(\theta) = \varphi(\theta)$.

Multiplying the first equation of (1.1) by $\varphi'(\theta) \varphi(\theta)$ and integrating over $\mathbb{T}^2$ yields

$$\frac{1}{2} \frac{d}{dt} \int_{\mathbb{T}^2} \varphi^2(\theta) \, dx + \int_{\mathbb{T}^2} \nabla \cdot \left( \frac{1}{2} \varphi^2(\theta) u \right) \, dx$$

$$+ \nu \int_{\mathbb{T}^2} \Lambda^{2/\alpha} \varphi(\theta) \, dx = \int_{\mathbb{T}^2} f \varphi(\theta) \, dx.$$ \hspace{1cm} (4.18)

Let $f, g \in C^\infty(\mathbb{T}^2)$ such that $g(x) = (f(x) - \lambda)_+$. Then one can easily verify that

$$(f(x) - f(y))(g(x) - g(y)) \geq (g(x) - g(y))^2.$$ \hspace{1cm} \text{Now, by Fubini’s Theorem,} \hspace{1cm}

$$\sum_{j \in \mathbb{Z}^2} \int_{\mathbb{T}^2} PV. \int_{\mathbb{T}^2} \frac{f(x) - f(y)}{|x - y + L_j|^{2+\alpha}} g(x) \, dy \, dx =$$

$$\sum_{j \in \mathbb{Z}^2} \int_{\mathbb{T}^2} PV. \int_{\mathbb{T}^2} \frac{f(y) - f(x)}{|x - y + L_j|^{2+\alpha}} g(y) \, dy \, dx.$$ \hspace{1cm} \text{Note that (see [18])}

$$\Lambda^\alpha = \frac{\epsilon_0 \tau}{2} \sum_{j \in \mathbb{Z}^2} PV. \int_{\mathbb{T}^2} \frac{f(x) - f(y)}{|x - y + L_j|^{2+\alpha}} \, dy.$$
Lemma 4.2. Let \( p > 2 \) since the integral \( \alpha \) is defined in [2] in the unforced case. Now we can use De Giorgi iteration to obtain explicit bounds on the \( \sup_{t \in [0, \infty)} \| \theta(t) \|_{L^\infty} \). Here we extend the proof in [6] to cover the whole range \( \alpha > 0 \).

Now we can use De Giorgi iteration to obtain explicit bounds on the \( L^\infty \) norm. For \( \alpha = 1 \) this was done in [2] in the unforced case \( f = 0 \), and similarly in [6] for \( f \notin L^p \), \( p > 2 \). Here we extend the proof in [6] to cover the whole range \( \alpha > 0 \).

Lemma 4.2. Let \( \alpha \in (0, \infty) \) and \( \theta \) be a viscosity solution of (4.1) on \( [0, \infty) \) with \( \theta(0) \in L^2 \) and \( f \in L^p(\mathbb{T}^2) \) for some \( p \in (2, \alpha, \infty) \). Then, for every \( t > 0 \),

\[
\| \theta(t) \|_{L^\infty} \lesssim \begin{cases} 
\frac{\| \theta(0) \|_2}{(\nu t)^{\frac{\alpha-2}{2}}} + \left( \frac{\| f \|_p}{\nu} \right)^{\frac{p-2}{p-\alpha}} \| \theta(0) \|_2^{\frac{p-2}{p-\alpha}}, & p < \infty, \\
\frac{\| \theta(0) \|_2}{(\nu t)^{\frac{\alpha-2}{2}}} + \left( \frac{\| f \|_\infty}{\nu} \right)^{\frac{1}{p}} \| \theta(0) \|_2^{\frac{1}{p}}, & p = \infty.
\end{cases}
\]

Proof. Consider the levels

\[ \lambda_k = M(1 - 2^{-k}) \]

for some \( M \) to be determined later, and denote the truncated function

\[ \theta_k = (\theta - \lambda_k)^+ \]

Fix \( t_0 > 0 \). Let \( T_k = t_0(1 - 2^{-k}) \) and define the energy levels as:

\[ U_k = \sup_{t \geq T_k} \| \theta_k(t) \|_2^2 + 2\nu \int_{T_k}^\infty \| \Lambda^2 \theta_k(t) \|_2^2 \, dt. \]

We take \( \tilde{\theta} = \theta_k \) and \( t_1 = s \in (T_{k-1}, T_k), t_2 = t > T_k \) in the truncated energy inequality (4.17). Then taking \( t_1 = s, t_2 = T > t \), adding the two inequalities, taking \( \limsup \) in \( T \) and then \( \sup \) in \( t \) gives

\[ U_k \leq 2\| \theta_k(s) \|_2^2 + 2 \int_{T_{k-1}}^{T_k} f(x)\theta_k(x, \tau) \, dx \, d\tau, \]
for a.a. \( s \in (T_{k-1}, T_k) \). Taking the average in \( s \) on \([T_{k-1}, T_k]\) yields

\[
U_k \leq \frac{1}{t_0} \int_{T_{k-1}}^{T_k} \int_{T^2} \theta_k^2(s) dx ds + 2 \int_{T_{k-1}}^{T_k} \int_{T^2} |f(x)\theta_k(x,t)| dx dt. \tag{4.20}
\]

By an interpolation inequality between \( L^\infty(L^2) \) and \( L^2(H^\alpha) \), we have that

\[
\|\theta_k\|_{L^{2+\alpha}(T^2 \times [T_k, \infty))} \leq C \frac{U_k^{2+\alpha}}{\nu}, \tag{4.21}
\]

where \( C \) is a constant independent of \( \nu \) and \( k \).

Note that

\[
\theta_{k-1} \geq 2^{-k} M \quad \text{on} \quad \{(x,t) : \theta_k(x,t) > 0\},
\]

and hence

\[
1_{\{\theta_k > 0\}} \leq \frac{2^{k+1}}{M \alpha} \theta_k^{-1}. \]

Therefore, using the fact that \( \theta_k \leq \theta_{k-1} \) and (4.21), we have

\[
\begin{aligned}
\frac{2^{k+1}}{t_0} & \int_{T_{k-1}}^{T_k} \int_{T^2} \theta_k^2(x,s) dx ds \\
\leq \frac{2^{k+1}}{t_0} & \int_{T_{k-1}}^{T_k} \int_{T^2} \theta_{k-1}^2(x,s) 1_{\{\theta_k > 0\}} dx ds \\
\leq \frac{2^{2k+1}}{t_0 M^2} & \int_{T_{k-1}}^{T_k} \int_{T^2} \theta_{k-1}^{2+\alpha} dx ds \\
& \leq C \frac{2^{2k+1}}{\nu t_0 M^2} U_{k-1}^{2+\alpha},
\end{aligned}
\tag{4.22}
\]

On the other hand, since \( f \in L^p(T^2) \) with \( p > \frac{2}{\alpha} \), we obtain, for \( p' = \frac{p}{p-1} \) (or \( p' = 1 \) when \( p = \infty \)),

\[
\int_{T_{k-1}}^{T_k} \int_{T^2} |f(x)\theta_k(t)| dx dt
\leq \|f\|_p \left( \int_{T_{k-1}}^{T_k} \left( \int_{T^2} |\theta_k|^{p'} dx \right)^{1/p'} dt \right)
\leq \|f\|_p \left( \int_{T_{k-1}}^{T_k} \left( \int_{T^2} |\theta_k|^{2+\alpha} 1_{\{\theta_k > 0\}} dx \right)^{1/p'} dt \right)
\leq \|f\|_p \left( \frac{2^{k(2/p' + \alpha - 1)}}{M^{2/p' + \alpha - 1}} \int_{T_{k-1}}^{T_k} \left( \int_{T^2} |\theta_{k-1}|^{2+\alpha} dx \right)^{1/p'} dt \right)
\leq \|f\|_p \left( \frac{2^{k(2/p' + \alpha - 1)}}{M^{2/p' + \alpha - 1}} \sup_{t \geq T_{k-1}} \left( \int_{T^2} |\theta_{k-1}|^2 dx \right)^{2 - \frac{2}{p'} + \frac{\alpha}{p'}} \int_{T_{k-1}}^{T_k} \left( \int_{T^2} |\theta_{k-1}|^{2+\alpha} dx \right)^{2+\alpha} dt \right)
\leq \|f\|_p \left( \frac{2^{k(2/p' + \alpha - 1)}}{\nu M^{2/p' + \alpha - 1}} U_{k-1}^{1+(2-2p'+p'\alpha)/2p'} \right).
\]

Note that \( (2 - 2p' + p'\alpha)/2p' > 0 \), since \( p > 2/\alpha \). Combining (4.20), (4.22) and (4.23) yields

\[
U_k \leq C \frac{2^{2k+1}}{\nu t_0 M^2} U_{k-1}^{2+\alpha/2} + C \|f\|_p \frac{2^{k(2/p' + \alpha - 1)}}{\nu M^{2/p' + \alpha - 1}} U_{k-1}^{1+(2-2p'+p'\alpha)/(2p')} \tag{4.24}
\]
with a constant $C$ independent of $k$. We claim that for a large enough $M$, the above nonlinear iteration inequality implies that $U_k$ converges to 0 as $k \to \infty$. Thus $\theta(t_0) \leq M$ for almost all $x$. The same argument applied to $\theta_k = (\theta + \lambda_k)_-$ also gives a lower bound.

To prove the above claim (and automatically get an explicit expression for $M$ in terms of $t_0$ and $U_0$), first note that $\theta \leq 0$ almost everywhere if $U_0 = 0$. Assume now $U_0 > 0$. Denote $\delta = (2 - 2\rho' + \rho'\alpha)/(2\rho')$. Note that $0 < \delta < \alpha/2$. Define $V_k = \eta_k U_k$ with $\eta_k = 2^m \nu_k$. We choose

$$m = \max\{4, \frac{2 + \rho'(\alpha - 1)}{\rho'\delta}\}, \quad \eta_0 = \frac{1}{2U_0},$$

$$M = \frac{(4C)^{\frac{1}{\nu}} 2^{m(1+\rho')}(2U_0)^{\frac{1}{\nu}}}{(\nu_0)^{1/\alpha}} + \left(\frac{2C\nu^2}{\nu} \frac{\|f\|_{L^p}}{\nu}\right)^{\frac{\rho'}{\rho' - \alpha - 1}} (2U_0)^{\frac{\rho'}{\rho' - \alpha - 1}}$$

$$\sim U_0^\frac{1}{\nu} (\nu_0)^{-\frac{1}{\alpha}} + \left(\frac{\|f\|_{L^p}}{\nu}\right)^{\frac{\rho'}{\rho' - \alpha - 1}} (U_0)^{\frac{\rho'}{\rho' - \alpha - 1}}.$$}

Based on the choice of the parameters $m, M, \eta_0$, one can verify that

$$C\eta_k \|f\|_{L^{\rho' + \alpha - 1}} U_k^{1+\delta} \leq \frac{1}{2} \eta_k^{-1/\alpha} U_k^{1+\delta}, \quad k \geq 1;$$

It follows from (4.23) that

$$V_k = \eta_k U_k \leq C\eta_k \frac{\nu_0^{1+\alpha/2}}{\nu M^{1+\alpha/2}} U_k^{1+\alpha/2} + C\eta_k \|f\|_{L^{\rho' + \alpha - 1}} U_k^{1+\delta} \leq \frac{1}{2} \eta_k^{-1/\alpha} U_k^{1+\delta} + \frac{1}{2} \eta_k^{-1} U_k^{1+\delta} = \frac{1}{2} V_k + \frac{1}{2} V_k^{1+\delta},$$

for all $k \geq 1$. We also have $V_0 = \eta_0 U_0 < 1/2$. Recalling that $0 < \delta < \alpha/2$, we arrive at

$$V_k \leq V_k^{1+\delta}, \quad k \geq 1.$$

It implies that $V_k \to 0$ and hence $U_k \to 0$ as $k \to \infty$. The estimate (4.19) follows from (4.25).

\end{proof}

5. Global attractor and bounds on the determining wavenumber

5.1. Global attractor. Thanks to the energy inequality, we have

$$\|\theta(t)\|_2^2 \leq \|\theta(0)\|_2^2 e^{-\nu(2\pi \lambda_0)^n t} + \frac{\|A^{-\frac{\nu}{2}} f\|_2^2}{\nu^2 (2\pi \lambda_0)^n} \left(1 - e^{-\nu(2\pi \lambda_0)^n t}\right), \quad t > 0,$$

where $\lambda_0 = 2^q/L$ as before. Denote

$$B_{L^2} = \{ \theta \in L^2 : \|\theta\|_2 \leq R_2 \}, \quad R_2 = \frac{\|A^{-\frac{\nu}{2}} f\|_2}{\nu \lambda_0^{n/2}}.$$

Then for any solution $\theta(t)$ there exists time $t_{L^2}$ that depends only on $\|\theta(0)\|_2$, such that

$$\theta(t) \in B_{L^2}, \quad \forall t \geq t_{L^2}.$$
So the set \( B_{L^2} \) is an absorbing ball in \( L^2 \). Moreover, there is a global attractor \( A \subset B_{L^2} \),

\[
A = \{ \theta(0) : \theta(t) \text{ is a complete bounded trajectory, i.e., } \theta \in L^\infty((-\infty, \infty); L^2) \}.
\]

In [6], in the critical case \( \alpha = 1 \), we proved that \( A \) is a compact global attractor in the classical sense. It uniformly attracts bounded sets in \( L^2 \), it is the minimal closed attracting set, and it is the \( L^2 \)-omega limit of the absorbing ball \( B_{L^2} \). This was done using the De Georgi iteration method to obtain \( L^2 \) continuity of solutions (which is automatically true in the subcritical case \( \alpha > 1 \)), and applying the framework of evolution systems in [4]. With all the ingredients at hand, the framework [4] gives the existence of the global attractor in the subcritical case as well. However, in the critical case \( \alpha < 1 \), we only know the existence of a weak global attractor at this point.

We also proved that the global attractor \( A \) is bounded in \( L^\infty \). More precisely, let

\[
B_{L^\infty} = \left\{ \theta \in B_{L^2} : \| \theta \|_\infty \leq \left( \frac{\| f \|_\nu}{\nu} \right)^{\frac{p}{p+\nu}} \| \theta \|_2^{\frac{p}{p+\nu}} \right\},
\]

where

\[
R_\infty \sim \left( \frac{\| f \|_\nu}{\nu} \right)^{\frac{p}{p+\nu}} \left( \frac{\| \Lambda^{-\alpha/2} f \|_2}{\nu \lambda_0^{\alpha/2}} \right)^{\frac{p+\nu-2}{p+\nu}} \leq \lambda_0^{1-\alpha - \frac{2-\alpha}{p+\nu-2}} \frac{\| f \|_\nu}{\nu}.
\]

Lemma 4.2 implies that

\[
A \subset B_{L^\infty}.
\]

Moreover, for any solution \( \theta(t) \) there exists time \( t_{L^\infty} \) that depends only on \( \| \theta(0) \|_2 \), such that

\[
\theta(t) \in B_{L^\infty}, \quad \forall t \geq t_{L^\infty}.
\]

So \( B_{L^\infty} \) is an absorbing set.

5.2. **Proof of the second part of Theorem 1.1** For a viscosity solution \( \theta(t) \) on the global attractor, i.e., such that \( \theta \in L^\infty((-\infty, \infty); L^2) \), we have

\[
\| \theta(t) \|_{B_{1,1}^0} \leq \| \theta(t) \|_{L^\infty}^{1-\frac{2}{p}} \| \theta(t) \|_2^{\frac{2}{p}} \leq R_1^{1-\frac{2}{p}} R_2^2,
\]

for all \( t \). Hence, fixing \( t \) in (5.10) and taking a limit as \( t_0 \) goes to \(-\infty\), we obtain the desired result. \( \square \)

In the following two subsections we will derive explicit bounds on \( A_\theta \) for solutions \( \theta \) in the absorbing set \( B_{L^\infty} \).

5.3. **The subcritical case** \( \alpha > 1 \). In this case \( A_{\theta,r} \) is a determining wavenumber for all \( r \in (\frac{\alpha q}{\alpha-1}, \frac{1}{\alpha-1}) \). When \( r = \frac{\alpha q}{\alpha-1} \), our estimates blow up. Nevertheless, we are able to pass to a limit as \( r \to \frac{1}{\alpha-1} =: r_0 \) and show that \( A_{\theta,r} \leq A_\theta \) for some \( r < r_0 \), where

\[
A_\theta(t) = \min \{ \lambda_q : \lambda_q^2 \| \theta_p \|_p \leq c_{\alpha,r} \| \theta \|_\infty < \lambda_q^{\alpha} \sum_{p \leq q} \lambda_p \| \theta_p \|_\infty \}
\]

thanks to the following observation.
Lemma 5.1. Let \( \alpha > 1 \). There exists a function \( r(M) \in (\frac{2\alpha}{\alpha - 1}, \frac{\lambda_0}{\beta}) \), such that
\[
A_{\theta, r(M)}(t) \leq A_{\theta}(t), \quad t \in [T_1, T_2],
\]
provided
\[
\|\theta\|_{L^\infty((\mathbb{T} \times [T_1, T_2]))} < M.
\]

Proof. We will choose \( r > 2\alpha/(\alpha - 1) > 2 \), in which case \( \|\theta_p\|_r < LM \), where \( L \) is the size of the torus. Now since \( \alpha - 1 - 2/r > 0 \) we have that
\[
\|\theta_p\|_r < LM < c_{\alpha, r}\lambda_p^{\alpha - 1 - \frac{2}{r}}
\]
for
\[
\lambda_p > \left( \frac{LM}{c_{\alpha, r}\nu} \right)^{\frac{1}{\alpha - 1}} =: N(r).
\]
If \( A_{\theta} \geq N(r) \) then we are done since the first condition in the definition of \( A_{\theta, r} \) is satisfied above \( N(r) \). Otherwise, for \( \lambda_p \in (A_{\theta}, N(r)) \) we have
\[
\lambda_p^{\frac{2}{r} - \frac{2}{\alpha}} < N(r)^{\frac{2}{r} - \frac{2}{\alpha}} \to 1 \quad \text{as} \quad r \to r_0, \quad \text{with} \quad r_0 = \frac{4}{\alpha - 1},
\]
and
\[
\lambda_p^{\frac{1 - \alpha + \frac{2}{r}}{r}} \|\theta_p\|_{r_0} < \frac{1}{2} c_{\alpha, r}\nu.
\]
One can verify that \( \lim_{r \to r_0} N(r)^{\frac{2}{r} - \frac{2}{\alpha}} = 1 \). Therefore
\[
\lambda_p^{1 - \alpha + \frac{2}{r}} \|\theta_p\|_r < \frac{3}{2} \lambda_p^{1 - \alpha + \frac{2}{r}} \|\theta_p\|_{r_0}
\]
\[
= \frac{3}{2} \lambda_p^{1 - \alpha} \|\theta_p\|_{r_0} \lambda_p^{\frac{2}{r} - \frac{2}{\alpha}}
\]
\[
< \frac{3}{2} c_{\alpha, r}\nu N(r)^{\frac{2}{r} - \frac{2}{\alpha}}
\]
\[
< c_{\alpha, r}\nu,
\]
provided \( r_0 - r \) is small enough, which means \( \lambda_p > A_{\theta, r} \). This concludes the proof. \( \square \)

We will now estimate \( A_{\theta} \) for \( \theta \in B_{L^\infty} \). To verify the first condition in the definition of \( A_{\theta} \) we note that
\[
\|\theta_p\|_{\frac{r}{r - 1}} \leq \lambda_p^{1 - \frac{2}{r}} \|\theta_p\|_{\frac{r}{r - 1}} \leq \lambda_p^{1 - \frac{2}{r}} R_\infty < \frac{1}{2} \lambda_p^{\frac{2}{r} - \frac{2}{\alpha}} c_0\nu(\alpha - 1)^2,
\]
provided \( \lambda_p > \lambda_0^{-1} \left( \frac{2R_\infty}{(\alpha - 1)^2 c_0\nu} \right)^{\frac{1}{\alpha - 1}} \).

For the second condition we estimate
\[
\sum_{\rho \leq q} \lambda_p \|\theta_p\|_\rho \leq 2 \lambda_q R_\infty < \lambda_q^2 c_0\nu(\alpha - 1)^2;
\]
provided \( \lambda_q > \left( \frac{2R_\infty}{(\alpha - 1)^2 c_0\nu} \right)^{\frac{1}{\alpha - 1}} \).

Therefore,
\[
(5.27) \quad A_{\theta} \leq \max \left\{ \lambda_p^{-1} \left( \frac{2R_\infty}{(\alpha - 1)^2 c_0\nu} \right)^{\frac{2}{\alpha - 1}}, \left( \frac{2R_\infty}{(\alpha - 1)^2 c_0\nu} \right)^{\frac{1}{\alpha - 1}} \right\},
\]
which is finite when \( \alpha > 1 \). Clearly, when the force is large enough, the first term in \( 5.27 \) dominates and
\[
A_{\theta} \leq \lambda_0^{-1} \left( \frac{2R_\infty}{(\alpha - 1)^2 c_0\nu} \right)^{\frac{1}{\alpha - 1}}.
\]
When $f \in L^2$, (5.26) gives
\[ R_\infty \sim \left( \frac{\|f\|_2}{\nu} \right)^{\frac{1}{\alpha}} \left( \frac{\|\Lambda^{-\alpha/2} f\|_2}{\nu \lambda_0^{\alpha/2}} \right)^{\frac{\alpha-1}{\alpha}} \leq \lambda_0^{1-\alpha} \left( \frac{\|f\|_2}{\nu} \right). \]

Therefore
\[ A_\theta \lesssim L^3 \left( \frac{\|f\|_2}{(\alpha - 1)^2 \nu^2} \right)^{\frac{\alpha}{\alpha-1}}. \]

5.4. The critical case $\alpha = 1$. In this section we consider the critical case $\alpha = 1$ assuming that $f \in L^\infty \cap H^1$ and the initial data $\theta(0) \in H^1$. In this case it is known that there exists a global solution $\theta \in C((0, \infty); H^1) \cap L_{loc}^1((0, \infty); H^{3/2})$. Moreover,
\[ \|\theta(t)\|_{C^0} \leq \|\theta(t_0)\|_{\infty} + \frac{\|f\|_{\infty}}{\nu}, \quad \forall t \geq t_0 + \frac{3}{2(1-h)}, \]
where $h = \min \left\{ \frac{c_1 \|\theta(0)\|_{\infty} + c_2 \|f\|_{\infty}^{1/\nu}}{\nu}, \frac{1}{4} \right\}$ (see Theorem 4.2 and (4.19) in [10]). We will not keep track of the length $L$ in this subsection in order not to overwhelm the estimates. Since $f \in L^\infty$, the radius of $B_{L, \infty}$ in (5.26) becomes $R_\infty \sim \|f\|_{\infty}$. So when $t$ is large enough we have $\|\theta(t)\|_{C^0} \leq R_{C^0} \sim \|f\|_{\infty}$. Now we will estimate the determining wavenumber
\[ A_{\theta, r}(t) = \min \left\{ \lambda_q : \lambda_q \|\theta_p\|_r < \frac{2c_0 \nu}{(r + 1)^2} \forall p > q, \quad \text{and} \quad \lambda_q \sum_{p \leq q} \lambda_p \|\theta_p\|_\infty < \frac{c_0 \nu}{(r + 1)^2} \lambda_q^{\frac{1}{\nu}} \right\}, \]
where $r > 3$ and $c_0$ is an absolute constant. Regarding the first condition, note that
\[ \|\theta_p\|_r \leq \|\theta_p\|_\infty \leq \lambda_p^{-h} R_{C^0} < \frac{2c_0 \nu}{(r + 1)^2} \lambda_p^{-\frac{1}{\nu}}, \]
provided
\[ \lambda_p \geq \left( \frac{(r + 1)^2}{2c_0 \nu} R_{C^0} \right)^{\frac{1}{1-\nu}}, \quad \text{and} \quad h > \frac{2}{r}. \]

As for the second condition,
\[ \sum_{p \leq q} \lambda_p \|\theta_p\|_\infty \leq 2 \lambda_q^{1-h} R_{C^0} < \frac{c_0 \nu}{(r + 1)^2} \lambda_q \]
provided
\[ \lambda_q > \left( \frac{2(r + 1)^2}{c_0 \nu} R_{C^0} \right)^{\frac{1}{\nu}} \]

Therefore,
\[ A_{\theta, r} \leq \max \left\{ \left( \frac{(r + 1)^2}{2c_0 \nu} R_{C^0} \right)^{\frac{1}{1-\nu}}, \left( \frac{2(r + 1)^2}{c_0 \nu} R_{C^0} \right)^{\frac{1}{\nu}} \right\}. \]

Since $h \lesssim \frac{r^2}{\|f\|_{\infty}}$ and $R_{C^0} \sim \frac{\|f\|_{\infty}}{\nu}$, we obtain
\[ A_{\theta, r} \lesssim \left( \frac{\|f\|_{\infty}}{\nu^2} \right)^{\frac{c_0 \|f\|_{\infty}}{\nu}}, \]
for some absolute (depending on $L$) constant $c$ and some large enough $r$. 
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