COMPLEXITY OF VILLAMAYOR’S ALGORITHM
IN THE NON EXCEPTIONAL MONOMIAL CASE

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Abstract

We study monomial ideals, always locally given by a monomial, like a reasonable first step to estimate in general the number of monoidal transformations of Villamayor’s algorithm of resolution of singularities. The resolution of a monomial ideal < X^{a_1}_1 · · · X^{a_n}_n > is interesting due to its identification with the particular toric problem < Z^c - Z^{a_1}_1 · · · Z^{a_n}_n >.

In the special case, when all the exponents ai are greater than or equal to the critical value c, we construct the largest branch of the resolution tree which provides an upper bound involving partial sums of Catalan numbers. This case will be called “minimal codimensional case”. Partial sums of Catalan numbers (starting 1, 2, 5, . . . ) are 1, 3, 8, 22, . . . These partial sums are well known in Combinatorics and count the number of paths starting from the root in all ordered trees with n + 1 edges. Catalan numbers appear in many combinatorial problems, counting the number of ways to insert n pairs of parenthesis in a word of n + 1 letters, plane trees with n + 1 vertices, . . .

The non minimal case, when there exists some exponent ai smaller than c, will be called “case of higher codimension”. In this case, still unresolved, we give an example to state the foremost troubles.

Computation of examples has been helpful in both cases to study the behaviour of the resolution invariant. Computations have been made in Singular (see [5]) using the desing package by G. Bodnár and J. Schicho, see [4].

1 Introduction

The existence of resolution of singularities in arbitrary dimension over a field of characteristic zero was solved by Hironaka in his famous paper [9]. Later on, different constructive proofs have been given, among others, by Villamayor [13], Bierstone-Milman [1], Encinas-Villamayor [6], Encinas-Hauser [5] and Wodarczyk [14].

This paper is devoted to study the complexity of Villamayor’s algorithm of resolution of singularities. This algorithm appears originally in [13] and we will use the presentation given in [6]. In this paper, the authors introduce a class of objects called basic objects \( B = (W, (J, c), E) \) where \( W \) is a regular ambient space over a field \( k \) of characteristic zero, \( J \subset O_W \) is a sheaf of ideals, \( c \) is an integer and \( E \) is a set of smooth hypersurfaces in \( W \) having only normal crossings. That is, they consider the ideal \( J \) together with a positive integer \( c \), or critical value defining the singular locus \( \text{Sing}(J, c) = \{ \xi \in W | \text{ord}_\xi(J) \geq c \} \), where \( \text{ord}_\xi(J) \) is the order of \( J \) in a point \( \xi \).

Let \( W \overset{\pi}{\rightarrow} W' \) be the monoidal transformation with center \( Z \subset \text{Sing}(J, c) \), \( \pi^{-1}(Z) = Y' \) is the exceptional divisor. Let \( \xi \) be the generic point of \( Z \), \( \text{ord}_\xi(J) = \theta \), the total transform of \( J \) in \( W' \) satisfies \( J O_{W'} = I(Y')^\theta \cdot J' \) where \( J' \) is the weak transform of \( J \), (see [6] for details).

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A transformation of a basic object \((W, (J, c), E) \leftarrow (W', (J', c), E')\) is defined by a monoidal transformation \(W \leftarrow W'\) and defining \(J' = I(Y')^{b-c} \cdot J\), the controlled transform of \(J\).

A sequence of transformations of basic objects

\[
(W, (J, c), E) \leftarrow (W^{(1)}, (J^{(1)}, c), E^{(1)}) \leftarrow \cdots \leftarrow (W^{(N)}, (J^{(N)}, c), E^{(N)})
\]

is a resolution of \((W, (J, c), E)\) if \(\text{Sing}(J^{(N)}, c) = \emptyset\).

**Remark 1.1.** Superscripts \((k)\) in basic objects will denote the \(k\)-stage of the resolution process. Subscripts \(i\) will always denote the dimension of the ambient space \(W_i^{(k)}\).

Villamayor’s algorithm provides a log-resolution in characteristic zero. A log-resolution of \(J\) is a sequence of monoidal transformations at regular centers as \([1]\) such that each center has normal crossings with the exceptional divisors \(E^{(i)}\), and the total transform of \(J\) in \(W^{(N)}\) is of the form

\[
J\mathcal{O}_{W^{(N)}} = I(H_1)^{b_1} \cdot \cdots \cdot I(H_N)^{b_N}
\]

with \(b_i \in \mathbb{N}\) for all \(1 \leq i \leq N\) and \(E^{(N)} = \{H_1, \ldots, H_N\}\).

In \([2]\) it is shown that algorithmic principalization of ideals reduces to algorithmic resolution of basic objects. That is, starting with \(c = \max \operatorname{ord}(J)\), the maximal order of \(J\), we obtain a resolution of \((W, (J, c), E)\) as \([1]\). At this step \(\max \operatorname{ord}(J^{(N)}) = c^{(N)} < c\). If \(c^{(N)} > 1\), we continue resolving \((W^{(N)}(J^{(N)}), c^{(N)}), E^{(N)}(J^{(N)})\) and so on, until have \(\max \operatorname{ord}(J^{(N)}) = c^{(N)} = 1\). Finally, a resolution of \((W, (J^{(N)}), (1), E^{(N)}))\) provides a log-resolution of \(J^{(N)}\), and therefore a log-resolution of \(J\).

In \([3]\) it is also shown that algorithmic principalization of ideals leads to embedded desingularization of varieties. That is, given a closed subscheme \(X \subset W\), the algorithmic principalization of the ideal \(I(X)\) provides an embedded desingularization of \(X\). See also \([7]\) for more details.

A key point in the definition of the algorithm is to use induction on the dimension of the ambient space \(W\) to define an upper-semi-continuous function \(t\). The set of points where this function attains its maximal value, \(\max t\), is a regular closed set, and defines a regular center for the next monoidal transformation.

A resolution of the basic object \((W, (J, c), E)\) is achieved by a sequence of monoidal transformations as in \([1]\), with centers \(\max t^{(k)}(\theta)\) for \(0 \leq k \leq N - 1\). That is, the sequence of monoidal transformations is defined by taking successively the center defined by the upper-semi-continuous function. The algorithm stops at some stage because the maximal value of the function \(t\) drops after monoidal transformations, that is, \(\max t^{(0)} > \max t^{(1)} > \cdots > \max t^{(N-1)}\).

This function \(t\) will be the resolution invariant. We shall work with the invariant defined in \([3]\), using the language of mobiles developed in \([5]\). We remind briefly the main notions.

Let \(J \subset \mathcal{O}_W\) be an ideal defining a singular algebraic set \(X \subset W\). The ideal \(J\) factors into \(J = M \cdot I\), with \(M\) the ideal defining a normal crossing divisors, and \(I\) some ideal still unresolved.

By induction on the dimension of \(W\), we will have this decomposition at every dimension from \(n\) to 1, that is \(J_i = M_i \cdot I_i\), for \(n \geq i \geq 1\), are defined in local flags \(W_n \supseteq W_{n-1} \supseteq \cdots \supseteq W_i \supseteq \cdots \supseteq W_1\), where each \(J_i, M_i, I_i \in \mathcal{O}_W\), are in dimension \(i\). There is a critical value \(c_{i+1}\) at each dimension \(i\), \((c_{n+1} = c)\), see \([5]\) for details. All the basic objects \((W_i(\cdot, (J_i, c_{i+1}), E_i))\), for \(n \geq i \geq 1\), will be resolved during the process of the algorithm.

Let \(E\) be the exceptional divisor of previous monoidal transformations, and consider \(E = \bigcup_{i=1}^{n} E_i\) where \(E_i\) applies to dimension \(i\). Obviously, we start with \(E = \emptyset\).

For any point \(\xi \in \text{Sing}(J, c)\), the function \(t\) will have \(n\) coordinates, with lexicographical order, and it will be one of the following three types:

\[
\begin{align*}
(a) & \quad t(\xi) = (t_n(\xi), t_{n-1}(\xi), \ldots, t_{n-r}(\xi), \infty, \infty, \ldots, \infty) \\
(b) & \quad t(\xi) = (t_n(\xi), t_{n-1}(\xi), \ldots, t_{n-r}(\xi), \Gamma(\xi), \infty, \ldots, \infty) \quad \text{with } t_i = \left[ \frac{\theta_i}{c_{i+1}}, m_i \right] \\
(c) & \quad t(\xi) = (t_n(\xi), t_{n-1}(\xi), \ldots, t_{n-r}(\xi), \ldots, t_1(\xi))
\end{align*}
\]
where $\theta_i = \text{ord}_{\xi}(I_i)$, $m_i$ is the number of exceptional divisors in $E_i$, and $\Gamma$ is the resolution function corresponding to the so-called monomial case, following the notation of [6], pages 165–166. We will recall the definition of $\Gamma$ in equation (3).

For simplicity, let assume that we start with a polynomial ring, $W = \text{Spec}(k[X_1, \ldots, X_n])$. In $\mathcal{O}_W = k[X_1, \ldots, X_n]$ the ideal $J$ is locally given by a monomial with respect to a regular system of parameters

$$J = \langle X_1^{a_1} \cdots X_n^{a_n} \rangle \subset \mathcal{O}_W$$

with $a_i \in \mathbb{N}$, for $i = 1, \ldots, n$.

Note that, in this situation, the center of the next monoidal transformation is combinatorial, it is a linear combination of $X_1, \ldots, X_n$. And this is also true after monoidal transformations, since Villamayor’s algorithm applied to a monomial ideal provides always combinatorial centers, and after a monoidal transformation in a combinatorial center we obtain again a monomial ideal.

So, at any stage of the resolution process, $W = \bigcup_i U_i$, where $U_i \cong \mathbb{A}^n_k$. Thereafter, we shall work locally, so we will assume that $W$ is an affine space.

To resolve the toric hypersurface $\{f = 0\} = \{Z^c - X_1^{a_1} \cdots X_n^{a_n} = 0\}$ we note that its singular locus $\text{Sing}(f, c)$ is always included in $\{Z = 0\}$, so we argue by induction on the dimension and reduce to the case where the corresponding ideal $J$ is of the form

$$J = \langle X_1^{a_1} \cdots X_n^{a_n} \rangle \subset \mathcal{O}_W$$

with $1 \leq a_1 \leq a_2 \leq \ldots \leq a_n$, $\sum_{i=1}^n a_i = d$, $d \geq c$, (3)

where $c$ is the critical value. If $a_i = 0$ for some $i$, then we may assume $\text{dim}(W) < n$.

After a monoidal transformation, we always consider the controlled transform of $J$ with respect to $c$, $J' = I(Y')^{-c} \cdot J'$ where $J'$ is the total transform of $J$ and $Y'$ denotes the new exceptional divisor. For the toric problem $J = \langle Z^c - X_1^{a_1} \cdots X_n^{a_n} \rangle$, taking the origin as center of the next monoidal transformation, at the $i$-th chart:

$$J^i = \langle Z^c \cdot X_i^c - X_1^{a_1} \cdots X_i^{d_i} \cdots X_n^{a_n} \rangle = \langle X_i^c \cdot (Z^c - X_1^{a_1} \cdots X_i^{d_i} \cdots X_n^{a_n}) \rangle,$$

and we can only factorize $c$ times the exceptional divisor.

Remark 1.2. We will denote as $i$-th chart the chart where we divide by $X_i$. When the center of the monoidal transformation is the origin, this monoidal transformation is expressed:

$$\begin{align*}
\mathbb{Z} & \to \mathbb{Z} \oplus \mathbb{Z} \oplus \frac{X_1}{X_i} \oplus \cdots \oplus \frac{X_{i-1}}{X_i} \oplus \frac{X_{i+1}}{X_i} \oplus \cdots \oplus \frac{X_n}{X_i} \\
Z & \to Z' \oplus \frac{X_i}{X_i} \\
X_i & \to \frac{X_i}{X_i} \\
X_j & \to \frac{X_j}{X_i} \text{ for } j \neq i
\end{align*}$$

where $\mathbb{Z} = \{Z, X_1, \ldots, X_n, \frac{Z}{X_i}, \frac{X_1}{X_i}, \ldots, \frac{X_{i-1}}{X_i}, \frac{X_{i+1}}{X_i}, \ldots, \frac{X_n}{X_i}\}$ is isomorphic to $\mathbb{Z} = \{Z, X_i, \frac{Z}{X_i}, \frac{X_1}{X_i}, \ldots, \frac{X_{i-1}}{X_i}, \frac{X_{i+1}}{X_i}, \ldots, \frac{X_n}{X_i}\}$. For simplicity, we will denote each $\frac{X_j}{X_i}$ again as $X_j$, and $\frac{Z}{X_i}$ as $Z$.

So we will apply the resolution algorithm to the basic object $(W, (J, c), \emptyset)$ for $J = \langle X_1^{a_1} \cdots X_n^{a_n} \rangle$, which is already a monomial ideal, but it is not necessarily supported on the exceptional divisors.

## 2 Monomial case (exceptional monomial)

The monomial case is a special case in which $J$ is a “monomial ideal” given locally by a monomial that can be expressed in terms of the exceptional divisors. This case arises after several monoidal transformations.
This means that we have a basic object \((W, (J, c), E)\) where \(J\) is locally defined by one monomial supported on the hypersurfaces in \(E\). In this case, the ideal \(J\) factors into \(J = M \cdot I\) with \(J = M\) and \(I = 1\). We can also call it exceptional monomial.

**Theorem 2.1.** Let \(J \subset \mathcal{O}_W\) be a monomial ideal as in equation [3]. Let \(E = \{H_1, \ldots, H_n\}\), with \(H_i = V(X_i)\), be a normal crossing divisor. Then an upper bound for the number of monoidal transformations to resolve \((W, (J, c), E)\) is given by

\[
\frac{d - c + \gcd(a_1, \ldots, a_n, c)}{\gcd(a_1, \ldots, a_n, c)}.
\]

**Proof.** We may assume that the greatest common divisor of the exponents \(a_i\) and the critical value \(c\) is equal to 1, because both the simplified problem and the original problem have the same singular locus. That is, if \(\gcd(a_1, \ldots, a_n, c) = k\) then \(d = k \cdot d_1\), \(c = k \cdot c_1\), \(a_i = k \cdot b_i\) for all \(1 \leq i \leq n\) and \(\gcd(b_1, \ldots, b_n, c_1) = 1\). The ideal \(J\) can be written as \(J = (J_1)^k\) where \(J_1 = \langle X_1^{b_1} \cdot \ldots \cdot X_n^{b_n} \rangle\) therefore

\[\text{Sing}(J, c) = \{\xi \in X \mid \text{ord}_\xi((J_1)^k) \geq k \cdot c_1\} = \{\xi \in X \mid \text{ord}_\xi(J_1) \geq c_1\} = \text{Sing}(J_1, c_1),\]

where \(X\) is the algebraic set defined by \(J\).

For a point \(\xi \in \mathbb{A}^n\), \(\Gamma(\xi) = (\Gamma_1(\xi), \Gamma_2(\xi), \Gamma_3(\xi))\) where

\[
\begin{align*}
\Gamma_1(\xi) &= \min\{p \mid \exists i_1, \ldots, i_p, a_{i_1}(\xi) + \cdots + a_{i_p}(\xi) \geq c, \ \xi \in H_{i_1} \cap \cdots \cap H_{i_p}\}, \\
\Gamma_2(\xi) &= \max\left\{\frac{a_{i_1}(\xi) + \cdots + a_{i_p}(\xi)}{c} \mid p = \Gamma_1(\xi), \ \xi \in H_{i_1} \cap \cdots \cap H_{i_p}\right\}, \\
\Gamma_3(\xi) &= \max\{(i_1, \ldots, i_p, 0, \ldots, 0) \in \mathbb{Z}^n \mid \Gamma_2(\xi) = \frac{a_{i_1}(\xi) + \cdots + a_{i_p}(\xi)}{c}, \ \xi \in H_{i_1} \cap \cdots \cap H_{i_p}\}
\end{align*}
\]

with lexicographical order in \(\mathbb{Z}^n\).

The center \(Z\) of the next monoidal transformation is given by the set of points where \(\Gamma\) attains its maximal value. It is easy to see that \(Z = \bigcap_{i=\lfloor n/2 \rfloor} H_i\).

So at the \(j\)-th chart, the exponent of \(X_j\) after the monoidal transformation is \((\sum_{i=n-r+1}^n a_i) - c\) and

\[
\left(\sum_{i=n-r+1}^n a_i\right) - c < \min_{n-r+1 \leq i \leq n} a_i = a_{n-r+1}
\]

because \(\sum_{i=n-r+2}^n a_i < c\) by construction of the center \(Z\).

This shows that the order of the ideal drops after each monoidal transformation by at least one, so in the worst case, we need \(d - (c - 1)\) monoidal transformations to obtain an order lower than \(c\).

**Remark 2.2.** Note that it is necessary to consider the monomial case. On one hand, this case may appear in dimension \(n\), and also in lower dimensions, \(n - 1, \ldots, 1\), when we resolve any basic object \((W, (J, c), E)\) (where \(J\) is any ideal). So we need to resolve the monomial case in order to obtain a resolution of the original basic object \((W, (J, c), E)\).

On the other hand, the algorithm of resolution leads to the monomial case, since given any ideal \(J\), the algorithm provides a log-resolution of \(J\). And it is necessary to continue to a resolution within the monomial case.

**Remark 2.3.** The bound in theorem [2.1] is reached only for the following values of \(c\):

\[1, a_n + \ldots + a_j + 1 \text{ for } n \geq j \geq 2, d.\]

For these values of \(c\), the order of the ideal drops after each monoidal transformation exactly by one.
• If $c = 1$, the monoidal transformation is an isomorphism. The exponent of $X_n$ after the monoidal transformation is $a_n - 1$.

• If $c = a_n + \ldots + a_j + 1$, for $n \geq j \geq 2$, the center of the monoidal transformation is $Z = \cap_{i=j}^{n} H_i$. At the $l$-th chart, for $n \geq l \geq j - 1$, the exponent of $X_l$ after the monoidal transformation is $(\sum_{i=j-1}^{n} a_i) - c = (\sum_{i=j}^{n} a_i) - (\sum_{i=j}^{n} a_i) - 1 = a_{j-1} - 1$.

In particular, at the $(j-1)$-th chart, the exponent of $X_{j-1}$ after the monoidal transformation has dropped exactly by one.

• If $c = d$, we finish after only one monoidal transformation.

Remark 2.4. If $\gcd(a_1, \ldots, a_n, c) = k > 1$, then the bound of the theorem 2.1 is $(d - c + k)/k$. As $(d - c + k)/k < d - c + 1$, we can use in practice the bound for the case $\gcd(a_1, \ldots, a_n, c) = 1$.

3 Case of one monomial

To construct an upper bound for the number of monoidal transformations needed to resolve the basic object $(W, (J, c), E = \emptyset)$, where $J$ is locally defined by a unique monomial, we estimate the number of monoidal transformations needed to obtain $(W', (J', c), E')$, a transformation of the original basic object, with $J' = M'$ (an exceptional monomial), and then apply theorem 2.1. In order to use theorem 2.1 we need an estimation of the order of $M'$. This estimation will be valid at any stage of the resolution process.

Lemma 3.1. Let $(W, (J, c), \emptyset)$ be a basic object where $J$ is a monomial ideal as in equation (3). Let $J = M \cdot I$ be the factorization of $J$, where $M = 1$, because of $E = \emptyset$, and $J = I$. After $N$ monoidal transformations we have $(W^{(N)}, (J^{(N)}, c), E^{(N)})$. Let $\xi \in W^{(N)}$ be a point. Then

$$ord_\xi(M^{(N)}) \leq (2^N - 1)(d - c)$$

where $ord_\xi(M^{(N)})$ denotes the order at $\xi$ of $M^{(N)}$, the (exceptional) monomial part of $J^{(N)}$.

Proof. It follows by induction on $N$:

• that if $N = 1$, $ord_\xi(M^{(1)}) = d - c$.

At the beginning, the first center defined by this algorithm is always the origin, so at the $i$-th chart:

$$J^{(1)} = M^{(1)} \cdot I^{(1)} = < X_1^{d-c} > \cdot < X_1^{a_1} \cdot \ldots \cdot X_n^{a_n} >$$

with $E^{(1)} = \{H_i\}$, where $H_i = V(X_i)$.

• We assume that the result holds for $N = m - 1$.

$$J^{(m-1)} = M^{(m-1)} \cdot I^{(m-1)} = < X_{i_1}^{b_1} \cdot \ldots \cdot X_{i_s}^{b_s} > \cdot < X_{i_{s+1}}^{a_{s+1}} \cdot \ldots \cdot X_n^{a_n} >$$

with $\sum_{i=1}^{s} b_i = d'$. By inductive hypothesis, after $m - 1$ monoidal transformations, the maximal order $d'$ of the (exceptional) monomial part $M^{(m-1)}$ satisfies

$$d' \leq (2^{m-1} - 1)(d - c).$$

For $N = m$, there are two possibilities:

1. If $\max \ ord(I^{(m-1)}) = \sum_{j=s+1}^{n} a_{i_j} \geq c$ then the center of the next monoidal transformation contains only variables appearing in $I^{(m-1)}$. 

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2. If \( \text{max ord}(I^{(m-1)}) = \sum_{j=s+1}^{n} a_{ij} < c \) then the center of the next monoidal transformation contains variables appearing in \( I^{(m-1)} \) and also variables appearing in \( M^{(m-1)} \).

**Case 1:**

If the center of the monoidal transformation is as small as possible, that is \( Z = \cap_{j=s+1}^{n} V(X_{ij}) \), at the \( i \)-th chart,

\[
J^{(m)} = M^{(m)} \cdot I^{(m)} = \langle X_{i_{1j}}^{b_{1}} \cdots X_{i_{sj}}^{b_{s}} \cdot X_{i}^{d-\sum_{j=1}^{s} a_{ij} - c} \rangle < X_{i_{s+1}}^{a_{s+1}} \cdots X_{i_{n}}^{a_{n}} > .
\]

The exponent of \( X_{ij} \), \( d - \sum_{j=1}^{s} a_{ij} - c = \sum_{j=s+1}^{n} a_{ij} - c \) is as big as possible, so this is the worst case, because the increase in the order of the exceptional monomial part after the monoidal transformation will be greater than that for another centers.

The highest order of \( M^{(m)} \) is

\[
\sum_{i=1}^{s} b_{i} + d - \sum_{j=1}^{s} a_{ij} - c = d' + d - c - \sum_{j=1}^{s} a_{ij} \leq d' + d - c,
\]

so by inductive hypothesis

\[
d' + d - c \leq (2^{m-1} - 1)(d - c) + d - c = 2^{m-1}(d - c) \leq (2^{m} - 1)(d - c).
\]

**Case 2:**

- At the \( ij \)-th chart, for \( 1 \leq j \leq s \)

\[
J^{(m)} = M^{(m)} \cdot I^{(m)} = \langle X_{i_{1j}}^{b_{1}} \cdots X_{i_{sj}}^{b_{s}} \cdot X_{i}^{\square} \rangle < X_{i_{s+1}}^{a_{s+1}} \cdots X_{i_{n}}^{a_{n}} > .
\]

- At the \( i \)-th chart, for \( s + 1 \leq i \leq n \)

\[
J^{(m)} = M^{(m)} \cdot I^{(m)} = \langle X_{i_{1}}^{b_{1}} \cdots X_{i_{s}}^{b_{s}} \cdot X_{i_{i}}^{\square} \rangle < X_{i_{s+1}}^{a_{s+1}} \cdots X_{i_{n}}^{a_{n}} > .
\]

As above, if we are in the worst case, when the center of the monoidal transformation is as small as possible, that is, the center is a point,

\[
\square = \Delta = d' + d - \sum_{j=1}^{s} a_{ij} - c .
\]

Therefore in both cases the highest order of \( M^{(m)} \) satisfies

\[
\leq 2d' + d - c \leq 2(2^{m-1} - 1)(d - c) + d - c = (2^{m} - 1)(d - c) .
\]

\[\square\]

**Remark 3.2.** Due to its general character, this bound is large and far from being optimal.

**Remark 3.3.** The ideals \( M_{i} \) are supported on a normal crossing divisors \( D_{i} \). Recall that their transformations after monoidal transformations, in the neighborhood of a point \( \xi \in W_{i} \), are

\[
D'_{i} = \begin{cases} 
D_{i}^* + (\theta_{i} - c_{i+1}) \cdot Y' & \text{if } (t'_{n}(\xi'), \ldots, t'_{s+1}(\xi') = (t_{n}(\xi), \ldots, t_{s+1}(\xi)) \in \text{other case} \\
\emptyset & n \geq i \geq 1,
\end{cases}
\]

where \( D_{i}^* \) denotes the pull-back of \( D_{i} \) by the monoidal transformation \( \pi \), \( Y' \) denotes the new exceptional divisor, the point \( \xi' \in W_{i} \) satisfies \( \pi(\xi') = \xi \), \( t_{i} = \text{ord}_{\xi}(I_{i}) \) and \( c_{i+1} \) is the corresponding critical value.
In what follows we will define the ideals $J_{i-1}$, $n \geq i > 1$. We need some auxiliary definitions: the companion ideals $P_i$ and the composition ideals $K_i$, see [5] for details. 

We construct the companion ideals to ensure that $Sing(P_i, \theta_i) \subset Sing(J_i, c_{i+1})$,

$$P_i = \begin{cases} I_i & \text{if } \theta_i \geq c_{i+1} \\ I_i + M^{-1}_{i+1} & \text{if } 0 < \theta_i < c_{i+1} \end{cases}$$

where $\xi \in \mathbb{A}^n_k$ is a point, $\theta_i = ord_{\xi}(I_i)$ and $c_{i+1}$ is the corresponding critical value.

Let $J_i = M_i \cdot I_i$ be the factorization of an ideal $J_i$ in $W_i$, where $M_i, I_i$ are ideals in $W_i$ in the neighborhood of a point $\xi \in \mathbb{A}^n_k$. Let $E_i$ be a normal crossing divisor in $\mathbb{A}^n_k$.

The composition ideal $K_i$ in $W_i$ of the product $J_i = M_i \cdot I_i$, with respect to a control $c_{i+1}$, is

$$K_i = \begin{cases} P_i \cdot I_{W_i}(E_i \cap W_i) & \text{if } I_i \neq 1, \\ 1 & \text{if } I_i = 1. \end{cases}$$

The critical value for the following step of induction on the dimension is $c_i = ord_{\xi}(K_i)$.

The construction of the composition ideal $K_i$ ensures normal crossing with the exceptional divisor $E_i$.

We say that an ideal $K$ is **bold regular** if $K = <X^a>$, $K \in k[X]$, $a \in \mathbb{N}$.

Finally, construct the junior ideal $J_{i-1}$

$$J_{i-1} = \begin{cases} Coeff_{V}(K_i) & \text{if } K_i \text{ is not bold regular or 1} \\ 1 & \text{otherwise} \end{cases}$$

where $V$ is a hypersurface of maximal contact in $W_i$ (see [5] page 830) and $Coeff_{V}(K_i)$ is the coefficient ideal of $K_i$ in $V$ (see [5] page 829). The junior ideal $J_{i-1}$ is an ideal in this suitable hypersurface $V$ of dimension $i - 1$.

If $\frac{a}{c} \geq 1$ we are in the first case of equation (5), $\frac{\theta_{n-1}}{c_{n-1}} = \frac{\theta_{n-2}}{c_{n-2}} = \ldots = \frac{\theta_j}{c_{j+1}} = 1$ and $t_j = \ldots = t_1 = \infty$ for $n - 1 \geq j \geq 1$, because $D_{n-1} = \ldots = D_1 = \emptyset$ and $P_i = I_i$, and hence $J_{i-1}$ is always given by a unique monomial.

**Remark 3.4.** For an ideal $J = <X_1^{a_1} \ldots X_n^{a_n}>$ as in equation (3), if we assume $a_n \geq a_{n-1} \geq \ldots \geq a_1 \geq c$, then at every stage $\frac{\theta_{n}}{c_n} \geq 1$, so we are always in the previous situation. The singular locus of $(J, c)$ is always a union of hypersurfaces $\cup_{r=1}^{n-1} \{X_i = 0\}$, $1 \leq r \leq n$, and the center of the next monoidal transformation will be the intersection of some of these hypersurfaces. So we will call this case the **minimal codimensional case**.

**Remark 3.5.** If there exists some $a_{i_0} < c$, at a certain stage of the resolution process it may occur $\frac{\theta_{i_0}}{c_{i_0}} < 1$. Then we are in the second case of equation (5), the (exceptional) monomial part $M_n$ can appear in some $J_j$ for $n - 1 \geq j \geq 1$, and $\frac{\theta_{i_0}}{c_{i_0}}$ can be much greater than 1, which increases the number of monoidal transformations. Now its singular locus is a union of intersections of hypersurfaces of the type $\cup_{j \geq 1} \{X_i = 0\} \cap \ldots \cap \{X_i = 0\}$. This is the **higher codimensional case**.

### 4 Bound in the minimal codimensional case

**Remark 4.1.** From now on, we always look to the points where the function $t$, defined in (2), is maximal. So the following results concerning the behavior of the function $t$ always affect the points where it reaches its maximal value.


Proposition 4.2. Let \((W, (J, c), E)\) be a basic object where \(J\) is a monomial ideal as in equation \(\mathcal{M}\), with \(a_i \geq c\) for all \(1 \leq i \leq n\). We can factor \(J = J_n = M_n \cdot I_n\), and after \(r - 1\) monoidal transformations, \(J_{n}^{(r-1)} = M_{n}^{(r-1)} \cdot I_{n}^{(r-1)}\). Let \(\xi \in W^{(r-1)}\) be a point where \(\text{ord}_\xi (I_{n}^{(r-1)}) = \theta_n^r\). After each monoidal transformation \(\pi\), the resolution function in a neighbourhood of \(\xi'\), where \(\pi(\xi') = \xi\) and \(\text{ord}_\xi (I_{n}^{(r)}) = \theta_n^r < \theta_n\), is of the form

\[
\left(\frac{\left[d - \sum_{j=1}^{s} a_{ij}\right]}{c}, [1, 0], \ldots, [1, 0]\right)
\]

for some \(1 \leq s \leq n - 1\).

Proof. After monoidal transformations,

\[
J_{n}^{(r)} = M_{n}^{(r)} \cdot I_{n}^{(r)} = \langle X_{n_{1}}^{b_{1}}, \ldots, X_{n_{s}}^{b_{s}} \rangle \
\]

with \(d - \sum_{j=1}^{s} a_{ij} = \sum_{j=s+1}^{n} a_{ij} \geq c\) then, \(P_{n}^{(r)} = I_{n}^{(r)}\) and the (exceptional) monomial part does not appear in \(J_{n}^{(r)}\) for all \(n \geq l \geq 1\).

We have \(\theta_n^r \neq \theta_n\), then \(E_{n}^{(r)} = Y' + |E|\) and \(m_n = s\), we count all the exceptional divisors of the previous steps and the new one. There are no exceptional divisors in lower dimension because \(E_{n-1}^{(r)} = (Y' + |E|) - E_{n}^{(r)} = 0\) and, in a similar way, we obtain \(E_{l}^{(r)} = 0\) for all \(n - 1 \geq l \geq 1\).

The normal crossing divisors \(D_{i}^{(r)} = 0\) for all \(n - 1 \geq i \geq 1\), so the corresponding ideals \(M_{n-1}^{(r)} = \ldots = M_{1}^{(r)} = 1\). In particular, \(M_{n}^{(r)} = 1\), hence

\[
c_{n} = \text{ord}_\xi (K_{n}^{(r)}) = \text{ord}_\xi (\text{Coeff}(K_{n}^{(r)})) = \text{ord}_\xi (J_{n-1}^{(r)}) = \text{ord}_\xi (I_{n}^{(r)}) = 0_{n-1}
\]

with \(\xi' \in W^{(r)}\) such that \(\pi(\xi') = \xi\), because \(\text{ord} (\text{Coeff}(K)) = \text{ord}(K)\) when \(K\) is a monomial ideal, therefore \(\frac{\theta_n^r}{c_n} = 1\). By the same argument we obtain \(\frac{\theta_n^{r-1}}{c_{n-1}} = \ldots = \frac{\theta_2^r}{c_2} = 1\).

Remark 4.3. After each monoidal transformation, the exceptional divisors at each dimension are:

\[
E_{j}^r = \left\{
\begin{array}{ll}
E_{j}^r & \text{if } (\theta_{n}^{r}(\xi'), \ldots, \theta_{j+1}^{r}(\xi')) = (t_n(\xi), \ldots, t_{j+1}(\xi)) \text{ and } \theta_j = \theta_j^r \\
(Y' + (E_{1} \cup \ldots \cup E_{n})) - (E_{n} + \ldots + E_{j+1}) & \text{in other case}
\end{array}
\right.
\]

for \(n > j \geq 1\), where \(E_{j}^r\) denotes the strict transform of \(E_{j}\) by the monoidal transformation \(\pi\), \(Y'\) denotes the new exceptional divisor, the point \(\xi' \in W_{j}^{r}\) satisfies \(\pi(\xi') = \xi\), \(\theta_j^r = \text{ord}_\xi (I_{j})\) and \(\theta_j = \text{ord}_\xi (I_{j})\). We denote \(|E| = E_{1} \cup \ldots \cup E_{n}\).

Hence, after the first monoidal transformation, since \(\theta_n^r < \theta_n\) we have \(E_{n}^r = Y'\) and \(E_{n-1}^r = \ldots = E_{1}^r = 0\). After the second monoidal transformation, at the chart where \(\theta_n^r = \theta_n\), we obtain \(E_{n-1}^r = (E_{n}^r) = \emptyset\), \(E_{n-1}^r = Y''\), and \(E_{n-2}^r = \ldots = E_{1}^r = \emptyset\) and so on. We call this phenomena propagation because every exceptional divisor appears in the resolution function \(t\) firstly in dimension \(n\), then in dimension \(n - 1, n - 2\), and so on.

Definition 4.4. We will call propagation, \(p(i,j)\), for \(1 \leq i \leq j - 1\), \(1 \leq j \leq n\), to the number of monoidal transformations needed to eliminate \(i\) exceptional divisors in dimension \(j\), when we remain constant \((t_n, t_{n-1}, \ldots, t_{j+1})\) and \(\theta_j\), and there are no exceptional divisors in lower dimensions \(j - 1, \ldots, 1\). That is, passing from the stage

\[
([\theta_n, m_n], \ldots, [\theta_{j+1}, m_{j+1}], \theta_j, [1, 0], \ldots, [1, 0])
\]

to the stage

\[
([\theta_n, m_n], \ldots, [\theta_{j+1}, m_{j+1}], \theta_j, [1, 0], \ldots, [1, 0], \infty, \ldots, \infty).
\]
Lemma 4.5. Propagation Lemma Let \((W, (J_c), E)\) be a basic object where \(J\) is a monomial ideal as in equation (3) with \(a_i \geq c\) for all \(1 \leq i \leq n\). Let \(p(i, j)\) be the propagation of \(i\) exceptional divisors in dimension \(j\) in the resolution process of \((W, (J_c), E)\).

Then, for all \(1 \leq j \leq n\),

\[
p(i, j) = \begin{cases} 
  i + \sum_{k=1}^{i} p(k, j-1) & \text{if } 0 \leq i \leq j - 1 \\
  0 & \text{if } i = j 
\end{cases}
\]

(8)

Proof.  

- If there are \(i\) exceptional divisors in dimension \(i\), \(K_{i+1}\) is bold regular, \(t_i = \infty\) then \(p(i, i) = 0\). We can not propagate these \(i\) exceptional divisors at this stage of the resolution process.

If there are \(s\) exceptional divisors at this step of the resolution process, then there are \(n - s\) variables in \(I_n\). On the other hand, from dimension \(n\) to dimension \(i + 1\) there are \(s - i\) exceptional divisors.

When we construct \(J_{n-1}, \ldots, J_{i+1}\), add to the corresponding composition ideal \(K_j\) the variables in \(I_W (E_j \cap W_j)\), so in these dimensions there are \((n - s) + (s - i) = n - i\) variables.

When we make induction on the dimension, at each step lose one variable, so in \(n - i - 1\) steps obtain that \(K_{i+1}\), that corresponds to the \(n - (n - i - 1) = i + 1\) position, is bold regular. And the variables appearing in these \(i\) exceptional divisors do not appear in the center of the next monoidal transformation.

- By induction on the dimension:

  - If \(j = 1\), \(p(1, 1) = 0\) by the previous argument.

  - If \(j = 2\), \(p(1, 2) = 1\) because when we propagate 1 exceptional divisor from dimension 2 to dimension 1, \(K'_{2}\) is bold regular.

\[
([\theta_n, m_n], \ldots, [\theta_2, 1], [1, 0]) \quad \downarrow \chi, \quad \quad ([\theta_n, m_n], \ldots, [\theta_2, 0], \infty)
\]

Then \(p(1, 2) = 1 = 1 + 0 = 1 + p(1, 1)\).

- We assume that the result holds for \(j \leq s - 1\). For \(j = s\):

\[
\begin{align*}
([\theta_n, m_n], \ldots, [\theta_s+1, m_s+1], [\theta_s, i], [1, 0], \ldots, [1, 0]) & \\
\begin{array}{c}
\downarrow \\
\downarrow \\
\downarrow
\end{array}
& \\
([\theta_n, m_n], \ldots, [\theta_s+1, m_s+1], [\theta_s, i-1], [1, 1], [1, 0], \ldots, [1, 0]) \\
\vdots \\
p(1, s-1) & \\
([\theta_n, m_n], \ldots, [\theta_s+1, m_s+1], [\theta_s, i-1], [1, 0], \ldots, [1, 0], \infty) & \\
\downarrow & \\
([\theta_n, m_n], \ldots, [\theta_s+1, m_s+1], [\theta_s, i-2], [1, 2], [1, 0], \ldots, [1, 0])
\end{align*}
\]

We want \([\theta_n, m_n] \ldots [\theta_{s+1}, m_{s+1}]\) and \(\theta_s\) remain constant. So after the first monoidal transformation look to some suitable chart where \(m_s = i\) drops. As \(m_s\) drops then \(m_{s-1} = i - (i - 1) = 1\) and propagate this exceptional divisor in dimension \(s - 1\), making
$p(1, s - 1)$ monoidal transformations. Otherwise, to keep $([\theta_n, m_n] \ldots [\theta_{s+1}, m_{s+1}])$ and $\theta_s$ constant, the only possibility is to look to a suitable chart where $m_s$ drops from $i - 1$ to $i - 2$. But in this case this would provide the same resolution function that appears after the propagation. As we want to construct the largest possible sequence of monoidal transformations, we follow the propagation phenomenon as above.

After more monoidal transformations:

\[
\begin{array}{c}
\vdots \\
p(2, s - 1) \\
\vdots \\
\vdots \\
([\theta_n, m_n], \ldots, [\theta_{s+1}, m_{s+1}], [\theta_s, 1], [1, 0], \ldots, [1, 0], \infty, \ldots, \infty) \\
\downarrow \\
([\theta_n, m_n], \ldots, [\theta_{s+1}, m_{s+1}], [\theta_s, 0], [1, i], [1, 0], \ldots, [1, 0])
\end{array}
\]

Then, for $1 \leq i \leq s - 1$,

\[
p(i, s) = 1 + p(1, s - 1) + 1 + p(2, s - 1) + \cdots + 1 + p(i, s - 1)
\]

with $p(l, s - 1), 1 \leq l \leq i$, defined by the induction hypothesis.

**Remark 4.6.** Computation of examples in Singular with *desing* package has been useful to state this behaviour of the exceptional divisors after monoidal transformations. The implementation of this package is based on the results appearing in [3].

**Theorem 4.7.** Let $(W, (J, c), \emptyset)$ be a basic object where $J$ is a monomial ideal as in equation (3) with $a_i \geq c$ for all $1 \leq i \leq n$. Then, the resolution function corresponding to $(W, (J, c), \emptyset)$ drops after monoidal transformations in the following form:
At this stage, $a_i \geq c$ by hypothesis, so the center of the next monoidal transformation is $\{X_i = 0\}$, and then we obtain an exceptional monomial.

Proof. It follows by the propagation lemma and the fact that each time that $\theta_n$ drops

$E' = Y' + |E|^\nu \neq \emptyset$, and $E'_i = (Y' + |E|^\nu) - (E'_n + \cdots + E'_{i+1}) = \emptyset$ for all $n - 1 \geq i \geq 1$.

Remark 4.8. Following the propagation in the previous way provides the largest branch in the resolution tree, because in other case, for example after the first monoidal transformation

looking to some chart $j$ with $j \neq i$ we obtain an invariant which will appear later in the resolution process, after the propagation $p(1, n)$.

Corollary 4.9. Let $(W, (J, c), \emptyset)$ be a basic object where $J$ is a monomial ideal as in equation (3) with $a_i \geq c$ for all $1 \leq i \leq n$. Therefore the number of monoidal transformations needed to transform $J$ into an exceptional monomial is at most

$$1 + p(1, n) + 1 + p(2, n) + \cdots + 1 + p(n - 1, n) + 1 = n + \sum_{j=1}^{n-1} p(j, n).$$

Remark 4.10. In this case we always have $\theta_n \geq c$, so $Sing(J, c) \neq \emptyset$ at every stage of the resolution process. Therefore, in the resolution tree, the branch of theorem 4.7 effectively appears, and it is the largest, hence (9) is exactly the number of monoidal transformations to obtain $J' = M'$. 11
Proposition 4.11. Let \((W, (J, c), \emptyset)\) be a basic object where \(J\) is a monomial ideal as in equation with \(a_i \geq c\) for all \(1 \leq i \leq n\). Then the previous sum of propagations is a partial sum of Catalan numbers.

\[
n + \sum_{j=1}^{n-1} p(j, n) = \sum_{j=1}^{n} C_j \text{ where } C_j = \left\{ \frac{1}{j+1} \binom{2j}{j} \right\} \text{ are Catalan numbers.}
\]

Proof. (1) Extend \(p\) to arbitrary dimension:

\[
n + \sum_{j=1}^{n-1} p(j, n) = p(n, n+1).
\]

Because of the form of the recurrence equation defining \(p(i, j)\), and the fact that \(p(n, n) = 0\) by definition, it follows that

\[
p(n, n+1) = n + \sum_{j=1}^{n} p(j, n) = n + \sum_{j=1}^{n-1} p(j, n). \tag{10}
\]

(2) Solve the recurrence equation defining \(p(i, j)\):

(a) We transform the recurrence equation \((8)\), defining \(p(i, j)\) for \(0 \leq i \leq j\) and \(1 \leq j \leq n\), to another recurrence equation defined for every \(i, j \geq 0\):

By sending the pair \((i, j)\) to the pair \((i, j-i)\) we extend the recurrence to \(i, j \geq 0\), that is, we consider

\[
\tilde{p}(i, j) = p(i, i+j)
\]

then \(p(i, j) = \tilde{p}(i, j-i)\). As \(p(i, j)\) is defined for \(0 \leq i \leq j\) then \(\tilde{p}(i, j)\) is defined for \(0 \leq i \leq i+j\) for every \(i, j \geq 0\).

(b) Note that

\[
\tilde{p}(i, j) - \tilde{p}(i-1, j+1) = p(i, i+j) - p(i-1, i+j)
\]

\[
= i + \sum_{k=1}^{i} p(k, i+j-1) - (i-1) - \sum_{k=1}^{i-1} p(k, i+j-1) = p(i, i+j-1) + 1 = \tilde{p}(i, j-1) + 1.
\]

Therefore, we have the following recurrence equation involving \(\tilde{p}(i, j)\)

\[
\begin{cases}
\tilde{p}(i, j) = 1 + \tilde{p}(i-1, j+1) + \tilde{p}(i, j-1) & \text{for } i, j \geq 1 \\
\tilde{p}(0, j) = \tilde{p}(i, 0) = 0
\end{cases} \tag{11}
\]

Take \(r(i, j) = p(i, i+j) + 1 = \tilde{p}(i, j) + 1\) and replace \(\tilde{p}(i, j)\) with \(r(i, j)\) in the equation \((11)\). It follows the auxiliary recurrence equation:

\[
\begin{cases}
\ r(i, j) = r(i-1, j+1) + r(i, j-1) & \text{for } i, j \geq 1 \\
r(0, j) = r(0, j) + 1 = 1, \ r(i, 0) = r(i, 0) + 1 = 1
\end{cases} \tag{12}
\]

(c) Resolving the auxiliary recurrence equation \((12)\) by generating functions:

Define \(r_{i,j} := r(i, j)\) and the generating functions

\[
R(x, y) = \sum_{i,j \geq 0} r_{i,j} x^i y^j \in \mathbb{C}[[x, y]], \quad R_s(x, y) = \sum_{i,j \geq 1} r_{i,j} x^{i-1} y^{j-1} \in \mathbb{C}[[x, y]].
\]
Therefore, which defines an equation of the form

\[ R_s(x, y) = \sum_{i,j \geq 1} r_{i-1,j+1} x^{i-1} y^{j-1} + \sum_{i,j \geq 1} r_{i,j-1} x^{i-1} y^{j-1} \]

\[ = \sum_{i \geq 0, j \geq 1} r_{i,j+1} x^i y^{j-1} + \frac{1}{y} \sum_{i \geq 1,j \geq 0} r_{i,j} x^i y^j \]

\[ = \frac{1}{y} \sum_{i \geq 0,j \geq 1} r_{i,j} x^i y^j + \frac{1}{y} \left[ \sum_{i \geq 1} r_{i,0} x^i + \sum_{i \geq 1,j \geq 1} r_{i,j} x^i y^j \right] \]

\[ = \frac{1}{y} \sum_{i \geq 1} r_{0,j} y^j + xy R_s(x, y) - y \sum_{i \geq 0} r_{i,1} x^i \]

\[ = \frac{1}{y} \left[ \frac{1}{1-x} + xy R_s(x, y) - y \sum_{i \geq 0} r_{i,1} x^i \right] + \frac{1}{y} \left[ \frac{1}{1-x} + y R_s(x, y) \right] \]

\[ = \frac{1}{y(1-y)} + \frac{1}{y} R_s(x, y) - \frac{1}{y} \sum_{i \geq 0} r_{i,1} x^i + \frac{1}{1-x} + y R_s(x, y). \]

Then

\[ \left( 1 - y - \frac{x}{y} \right) R_s(x, y) = \frac{1}{y(1-y)} + \frac{1}{1-x} - \frac{1}{y} \sum_{i \geq 0} r_{i,1} x^i \]

multiplying the equality by \( y \) we have

\[ (y - y^2 - x) R_s(x, y) = \frac{1}{1-y} + \frac{y}{1-x} - \sum_{i \geq 0} r_{i,1} x^i \]

\[ = \frac{1}{1-y} + \frac{y}{1-x} - r_{0,1} - \sum_{i \geq 1} r_{i,1} x^i = \frac{y}{1-y} + \frac{y}{1-x} - \sum_{i \geq 1} r_{i,1} x^i. \]

Therefore

\[ (y - y^2 - x) R_s(x, y) = \frac{y}{1-y} + \frac{y}{1-x} - \sum_{i \geq 1} r_{i,1} x^i \]

which defines an equation of the form

\[ Q(x, y) R_s(x, y) = K(x, y) - U(x). \]

Now apply the kernel method used in [2], algebraic case 4.3:

If \( Q(x, y) = 0 \) then \( y = \frac{1 + \sqrt{1-4x}}{2} \). We take the solution passing through the origin, \( y = \frac{1 + \sqrt{1-4x}}{2} \) and \( y = xC(x) \) where \( C(x) \) is the generating function of Catalan numbers.

On the other hand, \( Q(x, y) = 0 \) gives \( K(x, xC(x)) = U(x) \),

\[ K(x, y) = \frac{y}{1-y} + \frac{y}{1-x} = \frac{-y^2 + y - x + 1}{(1-x)(1-y)} - 1 \]
so $K(x, xC(x)) = \frac{1}{(1-x)(1-xC(x))} - 1$ and using $\frac{1}{1-xC(x)} = C(x)$ we have

$$U(x) = \frac{C(x)}{1-x} - 1.$$  

Making some calculations and using that $R(x, y)$ satisfies

$$R(x, y) = xyR_s(x, y) + \sum_{j \geq 0} r_{0,j} y^j + \sum_{i \geq 0} r_{i,0} x^i - r_{0,0}$$

we obtain the generating function of $r(i, j)$

$$R(x, y) = \frac{xyC(x) + x - y}{(y^2 - y + x)(1-x)}.$$  

(3) Compute the generating function of the sequence $p(n, n+1)$:

The coefficient of $y$ in $R(x, y)$ is just $\sum_{i \geq 0} r_{i,1} x^i$ then

$$\sum_{i \geq 0} r_{i,1} x^i = \frac{\partial R(x, y)}{\partial y} \bigg|_{y=0} = \frac{C(x)}{1-x}$$

is the generating function of the elements in the first column.

If $C(x)$ is the generating function of $C_n$ then the convolution product $C(x) \cdot \frac{1}{1-x}$ is the generating function of $\sum_{k=0}^n C_k = S_n$ therefore

$$r_{n,1} = \sum_{k=0}^n C_k.$$  

As $r(n, 1) = p(n, n+1) + 1$ then $p(n, n+1) = r(n, 1) - 1 = \sum_{k=0}^n C_k - 1$, as $C_0 = 1$ we have

$$p(n, n+1) = \sum_{k=1}^n C_k$$

where $C_k$ are Catalan numbers.  

See [12] for more details about Catalan numbers and the web page [11] for further details about their partial sums.

**Theorem 4.12.** Let $(W, (J, c), \emptyset)$ be a basic object where $J$ is a monomial ideal as in equation (3) with $a_i \geq c$ for all $1 \leq i \leq n$. Then the number of monoidal transformations required to resolve $(W, (J, c), \emptyset)$ is at most

$$\sum_{j=1}^n C_j + (2\sum_{j=1}^n C_j - 1)(d - c) - c + 1$$

where $C_j$ are Catalan numbers.

**Proof.** It follows by theorem 2.1, lemma 3.1 and proposition 4.11.
Table 1: Values of the bound

| n  | ∑_j=1^n C_j | global bound          |
|----|-------------|-----------------------|
| 1  | 1           | 1 + (d − c) − c + 1   |
| 2  | 3           | 3 + 7(d − c) − c + 1  |
| 3  | 8           | 8 + 255(d − c) − c + 1| 
| 4  | 22          | 22 + 4194303(d − c) − c + 1 |

**Example 4.13.** The following table shows some values of the bound for any monomial ideal J as in equation (3) with a_i ≥ c for all 1 ≤ i ≤ n.

**Remark 4.14.** Note that, as a consequence of proposition 4.11, the number of monoidal transformations needed to transform J into an exceptional monomial only depends on n, the dimension of the ambient space.

**Corollary 4.15.** Let J = < Z^c − X_1^{a_1}, . . . , X_n^{a_n} > ⊂ k[X_1, . . . , X_n, Z] be a toric ideal with a_i ≥ c for all 1 ≤ i ≤ n. Then the number of monoidal transformations needed to resolve (k_{n+1}, (J, c), θ) is at most

$$\sum_{j=1}^n C_j + (2\sum_{j=1}^n C_j - 1)(d - c) - c + 1$$

where C_j are Catalan numbers and d = \sum_{i=1}^n a_i.

5 Higher codimensional case

In the minimal codimensional case, the way in which the invariant drops essentially depends on the number of accumulated exceptional divisors. Because the first components of the invariant, θ_n, . . . , θ_1, defined in equation (2), only depend on the order of the ideals I_n, . . . , I_1. Recall that, for each J_i, we use the ideal M_i (see remark 3.3), to define the ideal I_i.

But in this case the first components of the invariant play an important role. They can also depend on the order of the (exceptional) monomial part M_n, see remark 3.5. So they may increase suddenly when some θ_j is given by the order of the ideal M_n. We will call this situation the higher codimensional case in dimension j.

Note that after some monoidal transformations, we can obtain a new higher codimensional case in another dimension.

So, we must compute the number of monoidal transformations while θ_n ≥ c, with a suitable sum of propagations. Then, estimate the number of monoidal transformations needed to get the higher codimensional case in dimension 1, and use the known estimation for the order of M_n to give an upper bound for the number of monoidal transformations needed to get the following higher codimensional case inside this one (if it is possible). Afterward, estimate the number of monoidal transformations needed to get the higher codimensional case in dimension 2, and so on.

Hence, it has not been possible to obtain a bound for this case in the same way as above, due to the complications of the combinatorial problem, that perform that we can not know what branch is the largest in the resolution tree (to obtain an exceptional monomial).

Furthermore, if we could find such bound, the large number of potential cases we expect, suggests that this bound would be very huge, even to estimate only the number of monoidal transformations needed to obtain an exceptional monomial.
**Example 5.1.** If we consider the basic object $(W, (J, c), \emptyset) = (\mathbb{A}^3_k, (X_1^2X_2X_3, 4), \emptyset)$, there exists a branch of height 15 to obtain $J' = M'$ or $\text{Sing}(J', c) = \emptyset$. So, in dimension 3, we need a bound greater than or equal to 15 for a higher codimensional case, in front of the 8 monoidal transformations needed for a minimal codimensional case.

**Remark 5.2.** In any case, both theorem 2.1 and lemma 3.1 are valid also in the higher codimensional case. So the open problem is to find a bound $C$ to obtain an exceptional monomial, to construct a global bound of the form

$$C + (2^C - 1)(d - c) - c + 1.$$  

**Remark 5.3.** For $n = 2$ the higher codimensional case appears only in dimension 1 and making some calculations we obtain $C = 3$, that gives the same bound as in the minimal codimensional case. This bound can be improved by studying the different branches.

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