Green Measures for Markov Processes

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Abstract

In this paper we study Green measures of certain classes of Markov processes. In particular Brownian motion and processes with jump generators with different tails. The Green measures are represented as a sum of a singular and a regular part given in terms of the jump generator. The main technical question is to find a bound for the regular part.

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1 Introduction

Let $X(t), t \geq 0$ be a time homogeneous Markov process in $\mathbb{R}^d$ starting from the point $x \in \mathbb{R}^d$. For a function $f : \mathbb{R}^d \to \mathbb{R}$ we consider the following heuristic object

$$V(f, x) = \int_0^\infty E_x[f(X(t))]dt.$$ 

If this quantity exists then $V(f, x)$ is called the potential for the function $f$. The notions of potentials is well known in probability theory, see e.g., [1, 11].

The existence of the potential $V(f, x)$ is a difficult question and the class of admissible $f$ shall be analyzed for each process separately. An alternative approach is based on the use of the generator $L$ of the process $X$. Namely, the potential $V(f, x)$ may be constructed as the solution to the following equation:

$$-LV = f.$$ 

Of course, there appear a technical problem of the characterization of the domain for the inverse generator $L^{-1}$. For a general Markov process we can not characterize this domain.

In the analogy with the PDE framework, we would like to have a representation

$$V(t, x) = \int_{\mathbb{R}^d} f(y)G(x, dy),$$ 

where $G(x, dy)$ is a measure on $\mathbb{R}^d$. This measure is nothing but the fundamental solution to the considered equation and traditionally may be called the Green measure for the operator $L$. Our aim is to study Green measures for certain classes of Markov processes. We stress again that the concepts of...
potentials and Green measures are related in the same manner as the notions of solutions and fundamental solutions to the corresponding equations.

In this paper we discuss general notion of Green measures for Markov processes and consider particular examples of such processes for which the existence and properties of Green measures may be analyzed.

2 General Framework

We will consider time homogeneous Markov processes $X(t)$, $t \geq 0$ in $\mathbb{R}^d$, see for example [1, 3, 10, 11]. A standard way to define a Markov process is to give the probability $P_t(x, B)$ of the transition from the point $x \in \mathbb{R}^d$ to the Borel set $B \subset \mathbb{R}^d$ in the time $t > 0$. In some cases we may have

$$P_t(x, B) = \int_B p_t(x, y) \, dy,$$

where $p_t(x, y)$ is the density of the transition probability (heat kernel), that is, $P_t(x, dy) = p_t(x, y) \, dy$. The function

$$g(x, y) := \int_0^\infty p_t(x, y) \, dt$$

is called the Green function, although the integral here may diverge. The existence of the Green function for a given process or transition probability, even for simple classes of Markov processes, is not always guaranteed, see examples below. Nevertheless, Green functions for different classes of Markov processes are well known in probability theory, see, e.g., [2, 4] and references therein.

As an alternative we introduce the Green measure by

$$G(x, dy) := \int_0^\infty P_t(x, dy) \, dt, \quad x \in \mathbb{R}^d,$$

assuming the existence of this object as a Radon measure on $\mathbb{R}^d$. Then we would have $G(x, dy) = g(x, y) \, dy$. The aim of this paper is to show how to define and study Green measures for certain particular Markov processes in $\mathbb{R}^d$.  

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Let us be more precise. We can start with a Markov semigroup $T(t), t \geq 0$, that is, a family of linear operators in a Banach space $E$. As $E$, we may use bounded measurable functions $B(\mathbb{R}^d)$, bounded continuous functions $C_b(\mathbb{R}^d)$ or Lebesgue spaces $L^p(\mathbb{R}^d), p \geq 1$ depending on each particular case. This family of operators satisfy the following properties:

(i) $T(t) \in \mathcal{L}(E), t \geq 0$,

(ii) $T(0) = 1$,

(iii) $\lim_{t \to 0^+} T(t)f = f, \quad f \in E$,

(iv) $T(t+s) = T(t)T(s)$,

(v) $\forall f \geq 0 \quad T(t)f \geq 0$.

The semigroup is conservative if

(vi) $T(t)1 = 1$.

The semigroup $T(t), t \geq 0$ is associated with a Markov process $\{X(t), t \geq 0 \mid P_x, x \in \mathbb{R}^d\}$ if

$$(T(t)f)(x) = E^x[f(X(t))] = \int_{\mathbb{R}^d} f(y)P_t(x, dy), \quad f \in E.$$ 

The transition probabilities may be constructed from the semigroup by choosing $f = 1_A, A \in \mathcal{B}(\mathbb{R}^d)$, that is,

$$P_t(x, A) = (T(t)1_A)(x).$$

Now we introduce the resolvent of the Markov semigroup $T(t), t \geq 0$. Let $\lambda > 0$ be given. The $\lambda$-resolvent of the Markov semigroup is the linear operator $R_\lambda : E \longrightarrow E$ defined by

$$(R_\lambda f)(x) := \int_0^\infty e^{-\lambda t}(T(t)f)(x)\, dt = \int_0^\infty e^{-\lambda t}\int_{\mathbb{R}^d} f(y)P_t(x, dy)\, dt,$$

for any $f \in E$ and $x \in \mathbb{R}^d$.

Denote by $\mathcal{B}_b(\mathbb{R}^d)$ the family of bounded Borel sets in $\mathbb{R}^d$ and $C_0(\mathbb{R}^d)$ the space of continuous functions with compact support.
Definition 2.1. The Green measure for a Markov process \( X(t), t \geq 0 \) with transition probability \( P_t(x, B) \) is defined by

\[
\mathcal{G}(x, B) := \int_0^\infty P_t(x, B) \, dt, \quad B \in \mathcal{B}_b(\mathbb{R}^d),
\]

or

\[
\int_{\mathbb{R}^d} f(y) \mathcal{G}(x, dy) = \int_0^\infty f(y) P_t(x, dy) \, dt, \quad f \in C_0(\mathbb{R}^d)
\]

whenever these integrals exist.

The Markov generator is a characteristic of a Markov semigroup. More precisely, we have the following definition.

Definition 2.2. We set

\[
D(L) := \left\{ f \in E \middle| \frac{T(t)f - f}{t} \text{ converges in } E \text{ when } t \to 0^+ \right\}
\]

and for every \( f \in D(L), x \in \mathbb{R}^d \)

\[
(Lf)(x) := \lim_{t \to 0^+} \frac{(T(t)f)(x) - f(x)}{t}.
\]

Then \( D(L) \) (the domain of \( L \)) is a linear subspace of \( E \) and \( L : D(L) \to E \) is a linear operator called the generator of the semigroup \( T(t), t \geq 0 \).

There are several known properties of the generator \( L \) and we have the full description of the Markov generators via so-called maximum principle, see, e.g., [2, 4].

From the relation between semigroup and generator we have

\[
E^x \left[ \int_0^\infty f(X(t)) \, dt \right] = \int_{\mathbb{R}^d} f(y) \mathcal{G}(x, dy) = -(L^{-1}f)(x) = \int_0^\infty (T(t)f)(x) \, dt
\]

for every \( f \in C_0(\mathbb{R}^d) \). Because any Radon measure defines a generalized function, then we may write

\[
\mathcal{G}(x, dy) = g(x, y) \, dy,
\]
where \( g(x, \cdot) \in D'(\mathbb{R}^d) \) is a positive generalized function for all \( x \in \mathbb{R}^d \). In view of (2.1) the Green measure is the fundamental solution corresponding to the operator \( L \). Note that the existence and regularity of this fundamental solution produces a description of admissible Markov processes for which the Green measure exists. In Section 4 we present some examples and show the existence of the Green measure under the assumption \( d \geq 3 \). This moment is one more demonstration on the essential influence of the dimension of the phase space on the properties of Markov processes.

### 3 Jump Generators and Green Measures

Let \( a : \mathbb{R}^d \rightarrow \mathbb{R} \) be a fixed kernel with the following properties:

1. Symmetric, \( a(-x) = a(x) \), for every \( x \in \mathbb{R}^d \).
2. Positive and bounded, \( a \geq 0 \), \( a \in C_b(\mathbb{R}^d) \).
3. Integrable
   \[
   \int_{\mathbb{R}^d} a(y) \, dy = 1.
   \]

Consider the generator \( L \) defined on \( E \) (as mentioned above) by

\[
(Lf)(x) = \int_{\mathbb{R}^d} a(x-y)[f(y) - f(x)] \, dy = (a * f)(x) - f(x), \quad x \in \mathbb{R}^d.
\]

In particular, \( L^* = L \) in \( L^2(\mathbb{R}^d) \) and \( L \) is a bounded linear operator in all \( L^p(\mathbb{R}^d) \), \( p \geq 1 \). We call this operator the jump generator with jump kernel \( a \). The corresponding Markov process is of a pure jump type and is known in stochastic as compound Poisson process, see [12].

Several analytic properties of the jump generator \( L \) were studied recently, see for example [5, 9, 8]. Here we recall some of these properties necessary in what follows.

Because \( L \) is a convolution operator, it is natural to apply Fourier transform to study it.

At first notice that, due to the symmetry of the kernel \( a \), its Fourier image is given by
\[ \hat{a}(k) = \int_{\mathbb{R}^d} e^{-i(k,y)} a(y) \, dy = \int_{\mathbb{R}^d} \cos((k, y)) a(y) \, dy. \]

Then, it is easy to see that
\[
\hat{a}(0) = 1, \quad \hat{a}(k) < 1, \quad k \neq 0,
\]
\[ \hat{a}(k) \to 0, \quad k \to \infty. \]

On the other hand, the Fourier image \( L \) is the multiplication operator by
\[ \hat{L}(k) = \hat{a}(k) - 1 \]
that is the symbol of \( L \).

We make the following assumptions on the kernel \( a \).

\((H)\) The jump kernel \( a \) is such that \( \hat{a} \in L^1(\mathbb{R}^d) \) and has finite second moment, that is,
\[ \int_{\mathbb{R}^d} |x|^2 a(x) \, dx < \infty. \]

Denote by \( G_\lambda(x, y), \ x, y \in \mathbb{R}^d, \ \lambda \in (0, \infty) \) the resolvent kernel of \( R_\lambda(L) = (\lambda - L)^{-1} \). This kernel admits the representation
\[ G_\lambda(x, y) = \frac{1}{1 + \lambda} \left( \delta(x - y) + G_\lambda(x - y) \right), \quad \lambda \in (0, \infty), \]
with
\[ G_\lambda(x) = \sum_{k=1}^{\infty} \frac{a_k(x)}{(1 + \lambda)^k}, \quad (3.1) \]
where \( a_k(x) = a^{*k}(x) \) is the \( k \)-fold convolution of the kernel \( a \). Notice that the resolvent kernel \( G_\lambda(x, y) \) has a singular part, \( \delta(x - y) \) and a regular part \( G_\lambda(x - y) \). The Green function, as a generalized function, has the form
\[ G_0(x) = \delta(x) + G_0(x). \]

The transition probability density \( p(t, x) \) in terms of Fourier transform has representation
\[ p(t, x) = \frac{1}{(2\pi)^d} \int_{\mathbb{R}^d} e^{i(k, x) + t(\hat{a}(k) - 1)} \, dk. \]
and for the resolvent kernel

\[ G_\lambda(x, y) = -(L - \lambda)^{-1}(x, y), \]

holds

\[ G_\lambda(x - y) = \frac{1}{(2\pi)^d} \int_{\mathbb{R}^d} \frac{e^{i(k, x-y)}}{1-\hat{a}(k) + \lambda} \, dk. \]

For a regularization of the last expression we write

\[ \frac{1}{1-\hat{a}(k) + \lambda} = \frac{1}{1+\lambda} + \frac{\hat{a}(k)}{(1+\lambda)(1-\hat{a}(k) + \lambda)}. \]

Then for operators we have

\[ G_\lambda = \frac{1}{1+\lambda} + G_\lambda \]

or in terms of kernels

\[ G_\lambda(x - y) = \frac{1}{(2\pi)^d} \int_{\mathbb{R}^d} e^{i(k, x-y)} \frac{\hat{a}(k)}{(1+\lambda)(1-\hat{a}(k) + \lambda)} \, dk. \]

We summarize our considerations. The study the resolvent kernel (Green kernel) is reduced to the analysis of the regular part \( G_0(x) \), that is,

\[ G_0(x) = \sum_{k=1}^{\infty} a_k(x), \quad a_k(x) = a^k(x), \]

where \( a_k(x) \) is the \( k \)-fold convolution of the kernel \( a \). The Fourier representation for \( G_0 \) is given by

\[ G_0(x) = \frac{1}{(2\pi)^d} \int_{\mathbb{R}^d} e^{i(k, x)} \frac{\hat{a}(k)}{1-\hat{a}(k)} \, dk. \]

For \( d \geq 3 \) this integral exists for all \( x \in \mathbb{R}^d \) that follows from the integrable singularity of \( (1 - \hat{a}(k))^{-1} \) at \( k = 0 \). The latter is the consequence of our assumptions on \( a(x) \).
4 Particular Models

The main technical question is to obtain a bound for the $k$-fold convolution $a_k(x)$ in $k$ and $x$ together for the analysis of the properties of $G_0(x)$. From stochastic point of view, $a_k(x)$ is the density of sum of $k$ i.i.d. random variables with distribution density $a(x)$. Unfortunately, we can not find in the literature any general result in this direction. There are several particular classes of jump kernels for which we shall expect such kind of results, see [8].

1. Exponential tails or light tails. That is, the kernel $a(x)$ satisfies the upper bound

$$a(x) \leq Ce^{-\delta|x|}, \quad \delta > 0.$$ 

2. Moderate tails. In this case the asymptotic of $a(x)$ and $x \to \infty$ is given by

$$a(x) \sim \frac{C}{|x|^{d+\gamma}}, \quad \gamma > 2. \quad (4.1)$$

3. Heavy tails. The kernel $a(x)$ has an asymptotic similar to (4.1) with $\gamma \in (0, 2)$, that is,

$$a(x) \sim \frac{C}{|x|^{d+\gamma}}, \quad \gamma \in (0, 2).$$

In both cases the exponential tails and moderate tails, the kernel $a(x)$ has second moment. On the other hand, the case of heavy tails the second moment of $a(x)$ does not exists.

Below we consider two examples of kernels $a(x)$ and show the bound for the regular part of the resolvent kernel $G_0(x)$.

4.1 Gauss Kernels

Assume that the jump kernels $a(x)$ has the following form:

$$a(x) = C \exp \left(-\frac{b|x|^2}{2}\right), \quad C, b > 0. \quad (4.2)$$

Proposition 4.1. If the jump kernel $a(x)$ be given by (4.2) and $d \geq 3$, then holds

$$G_0(x) \leq C_1 \exp \left(-\frac{b|x|^2}{4}\right).$$
Proof. By a direct calculation we find

\[ a_k(x) = \frac{C}{k^{d/2}} \exp \left( -\frac{b|x|^2}{2k} \right) \]

with \( C = C(b, d) \). Therefore for \( d \geq 3 \) we obtain

\[
G_0(x) = \sum_{k=1}^{\infty} a_k(x) = C \sum_{k=1}^{\infty} \frac{1}{k^{d/2}} \exp \left( -\frac{b|x|^2}{2k} \right)
\]

\[
= C \sum_{k=1}^{\infty} \sum_{n=0}^{\infty} \frac{1}{k^{d/2}n!} \left( -\frac{b|x|^2}{2k} \right)^n
\]

\[
= C \sum_{n=0}^{\infty} \left( \sum_{k=1}^{\infty} \frac{1}{k^{d/2+n}} \right) \frac{1}{n!} \left( -\frac{b|x|^2}{2} \right)^n.
\]

As the series \( \sum_{k=1}^{\infty} \frac{1}{k^{d/2+n}} = \zeta(d/2 + n) \leq \zeta(3/2) \) for \( d/2 + n > 1 \Leftrightarrow d \geq 3 \), where \( \zeta(s), s > 1 \) is the Riemann zeta function, then we obtain

\[
G_0(x) \leq C \zeta(3/2) \sum_{n=0}^{\infty} \frac{1}{n!} \left( -\frac{b|x|^2}{2} \right)^n = C_1 \exp \left( -\frac{b|x|^2}{2} \right).
\]

\( \square \)

4.2 Exponential Tails

Now we investigate the case when the jump kernel \( a(x) \) has exponential tails, that is,

\[
a(x) \leq C \exp(-\delta |x|), \quad \delta > 0.
\]  

(4.3)

Proposition 4.2. If the jump kernel \( a(x) \) satisfies (4.3) and \( d \geq 3 \), then there exist \( A, B > 0 \) such that the bound for \( G_0(x) \) holds

\[
G_0(x) \leq A \exp(-B|x|).
\]

Proof. It was shown in [8] that

\[
an_n(x) \leq C n^{-d/2} \exp(-c \min(|x|, |x|^2/n)).
\]

This implies the following bound for \( a_n(x) \)

\[
an_n(x) \leq C n^{-d/2} \left( \exp(-c|x|) + \exp(-c|x|^2/n) \right).
\]
Hence, it is simple to obtain the bound for $G_0(x)$, namely for $d \geq 3$

$$G_0(x) = \sum_{n=1}^{\infty} a_n(x) \leq C_1 \exp(-c_1|x|) + C_2 \exp(-c_2|x|^2)$$

$$\leq A \exp(-B|x|).$$

4.3 Brownian Motion

Let us consider another concrete example of a Markov process. Namely, denote $B(t)$, $t \geq 0$ the Brownian motion in $\mathbb{R}^d$. The generator of this process is the Laplace operator $\Delta$ considered in a proper Banach space $E$. As above we are interested in studying the expectation of the random variable

$$Y(f) = \int_0^\infty f(B(t)) \, dt$$

for certain class of functions $f : \mathbb{R}^d \to \mathbb{R}$. To this end, we introduce the following class of functions

$$CL(\mathbb{R}^d) = \{ f : \mathbb{R}^d \to \mathbb{R} : f \text{ is continuous, bounded and belongs to } L_1(\mathbb{R}^d) \}.$$

It is a Banach space with the norm $\|f\|_{CL} := \|f\|_{\infty} + \|f\|_1$, where $\| \cdot \|_{\infty}$ is the supremum norm and $\| \cdot \|_1$ is the norm in $L_1(\mathbb{R}^d)$.

**Proposition 4.3.** Let $d \geq 3$ be given. The Green measure of Brownian motion is

$$G(x, dy) = G_0(x - y) \, dy = \frac{C(d)}{|x - y|^{d-2}} \, dy.$$

**Proof.** Note that due to (2.1) we have

$$E^x[Y(f)] = -\Delta^{-1} f(x) = \int_{\mathbb{R}^d} C(d) \frac{f(y)}{|x - y|^{d-2}} \, dy.$$
Then
\[ \left| \int_{\mathbb{R}^d} \frac{f(y)}{|x-y|^{d-2}} \, dy \right| \leq \left| \int_{|x-y| \leq 1} \frac{f(y)}{|x-y|^{d-2}} \, dy \right| + \left| \int_{|x-y| > 1} \frac{f(y)}{|x-y|^{d-2}} \, dy \right| \leq C_1 \|f\|_{\infty} + C_2 \|f\|_{L_1(\mathbb{R}^d)} \leq C \|f\|_{CL}, \]
where we have used the local integrability in $y$ of $|x-y|^{2-d}$. It means that every function from $CL(\mathbb{R}^d)$ is integrable with respect to the Green measure. \hfill \Box

**Remark 4.4.** In a forthcoming paper we will investigate the additive functionals for time change Markov processes. More precisely, let $X(t)$, $t \geq 0$ be a Markov process in $\mathbb{R}^d$ with generator $L$ and denote by $\mu_t(dx)$ the marginal distribution of $X(t)$. That is, $\mu_t$ is the solution of the Fokker-Planck equation
\[ \frac{\partial \mu_t}{\partial t} = L^* \mu_t. \]
In addition, Assume that an inverse subordinator $E(t)$, $t \geq 0$ is given and consider random time change
\[ Y(t) := X(E(t)), \quad t \geq 0. \]
It is known that the marginal distribution $\nu_t$ of $Y(t)$ holds a subordination formula, see [7]
\[ \nu_t(dx) = \int_0^\infty D_t(\tau) \mu_t(dx) \, d\tau, \]
where $D_t(\tau)$ is the density distribution of $E(t)$. If $P_t(x, dy)$ is the transition probability of $X(t)$, then the Green measure of $Y(t)$ is (heuristically) given by
\[ G(x, dy) = \int_0^\infty \int_0^\infty P_t(x, dy) G_t(\tau) \, d\tau \, dt. \]
But it is not hard to see that this definition leads to a contradiction and it has to be modified. More precisely, it has to be renormalized in such a way...
that then we are able to study the integral functionals

\[\int_{0}^{\infty} f(Y(t)) \, dt\]

for a proper class of functions \(f : \mathbb{R}^d \rightarrow \mathbb{R}\). For the details, see [6].

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