Imaginary time D-branes to all orders

Oren Bergman and Shlomo S. Razamat

Department of Physics
Technion, Israel Institute of Technology
Haifa 32000, Israel
bergman, razamat@physics.technion.ac.il

ABSTRACT: Extending the work of Gaiotto, Itzhaki and Rastelli in hep-th/0304192, we derive a general prescription for computing amplitudes involving a periodic array of D-branes in imaginary time to arbitrary order. We use this prescription to show that closed string amplitudes with \( b \) boundaries are identical to closed string amplitudes with \( b \) additional insertions of a particular physical closed string state. We perform an explicit computation for the annulus, and argue on the basis of open and closed string field theory for higher order amplitudes. We also discuss possible subtleties in the prescription related to collisions of boundaries and insertions, and argue that they are harmless. This verifies the proposal that a periodic array of D-branes in imaginary time corresponds to a pure closed string background.

KEYWORDS: D-branes, S-branes, open/closed string duality.
1. Introduction

Open/closed string duality has been a powerful tool in understanding string theory and gauge theory. The most basic form of this relation originates from the dual descriptions of the vacuum cylinder amplitude, as a one-loop open string vacuum energy on one hand, and as a tree-level closed string exchange amplitude on the other. The AdS/CFT correspondence is another kind of open/closed string duality, whereby an open string theory on a collection of D-branes is dual to a closed string theory in some non-trivial geometry with fluxes. Recently, another type of open/closed string duality has been revealed. Gaiotto, Itzhaki and Rastelli have shown that closed string disk scattering amplitudes from a periodic array of D-branes in imaginary time are identical to purely closed string sphere amplitudes with an additional insertion of a particular physical closed string state [1]. This led to the proposal that an array of D-branes in imaginary time corresponds to a particular pure closed string background, and that
perhaps any configuration of D-branes which are localized in imaginary (or complex) time corresponds to some pure closed string background.

Arrays of D-branes in imaginary time arise in the study of unstable D-brane creation and evaporation \[2, 3, 4, 5, 6\], a process also known as a spacelike brane, or S-brane. An S-brane is described by adding to the flat space CFT the marginal boundary deformation

\[
\lambda \int dt \cosh(x_0(t)) .
\]  

(1.1)

This is related to the boundary sine-Gordon theory by a Wick rotation \(x_0 = ix\). In that case the deformation \(\lambda \int dt \cos(x(t))\) interpolates between a Neumann boundary condition at \(\lambda = 0\) and a Dirichlet boundary condition at \(\lambda = 1/2\) \[7, 8\]. The latter therefore corresponds to a periodic array of D-branes in \(x\). Upon Wick rotation we therefore formally get an array of D-branes in imaginary time when \(\lambda = 1/2\). This is a time-dependent background which describes the creation at \(x_0 = 0\), and immediate decay, of an unstable D-brane. It is therefore natural to expect that it can be described purely in terms of closed strings.

The authors of \[1\] derived a prescription for computing disk amplitudes for D-branes in imaginary time using a specific prescription for analytically continuing amplitudes for D-branes in real space. Applying this to the two-point (and more generally \(n\)-point) disk amplitude shows that the only contribution comes from the limit where the size of the boundary shrinks to a point, and that this corresponds to an additional insertion of a specific physical closed string state \(|W\rangle\). Assuming this holds for amplitudes with any number of boundaries, namely that the only contribution comes from the limit where all the boundaries shrink, and in that limit each boundary is replaced with an insertion of \(|W\rangle\), the insertion will exponentiate, implying that this is really a closed string background.

The aim of the present paper is to extend this result to higher order amplitudes, including an arbitrary number of boundaries and genus. We will show that any amplitude which involves a periodic array of D-branes in imaginary time is identical to a purely closed string amplitude where the boundaries are replaced by additional insertions of the same closed string state \(|W\rangle\). This will complete the verification of the proposal that the D-brane array corresponds to a pure closed string background.

Our paper is organized as follows. In section 2 we first review the prescription for calculating disk amplitudes for an array of D-branes in imaginary time presented in \[1\], and then generalize for amplitudes with any number of boundaries (in the Appendix we show how the prescription can be extended to an arbitrary configuration of imaginary branes). In section 3 we apply the general prescription to the two-point annulus ampli-
tude, and show that it is identical to the four-point sphere amplitude with two $|W\rangle$s. In section 4 we will address the question of additional contributions to the amplitude from collision singularities. We will argue that the prescription can be chosen in such a way that these additional singularities do not contribute. General amplitudes will be discussed in section 5, where, relying on formulations of closed and open/closed string field theory, we will show that an amplitude with $b$ boundaries and $n$ closed string insertions is identical to an amplitude with no boundaries and $n+b$ insertions.

2. General Prescription

2.1 Review of the disk case

We begin with a brief review of the prescription for the disk amplitudes [1]. If $\tilde{A}$ is a disk amplitude of closed strings with a single D-brane located at a spatial position $x=0$, then the amplitude with a periodic array at $x=(n+1/2)a$ is given by

$$\tilde{S}(P) = \sum_{n=-\infty}^{\infty} \tilde{A}(P)e^{i(n+1/2)aP} = \tilde{A}(P) \sum_{n=-\infty}^{\infty} (-1)^n 2\pi \delta(Pa - 2\pi n),$$

(2.1)

where we have suppressed all the kinematic variables except the total momentum in the $x$ direction $P$. The amplitude for an array of D-branes in imaginary time is then defined by the Wick rotation $x \rightarrow -ix^0$ and $P \rightarrow iE$, with $x^0$ and $E$ real. This gives

$$S(E) = \tilde{A}(iE) \sum_{n=-\infty}^{\infty} (-1)^n 2\pi \delta(iEa - 2\pi n).$$

(2.2)

Naively this vanishes, however $\tilde{A}(iE)$ may blow up for some values of $E$ and yield a non-zero result. One has to provide a prescription for computing this quantity, which is essentially a prescription for performing the analytic continuation from real space to imaginary time. The prescription given in [1] is as follows. Consider the Fourier transform of the original amplitude

$$\tilde{G}(x) = \int_{-\infty}^{\infty} dP e^{iPx} \tilde{A}(P) \sum_{n=-\infty}^{\infty} (-1)^n 2\pi \delta(Pa - 2\pi n).$$

(2.3)

Using the residue theorem this can be written as

$$\tilde{G}(x) = \frac{1}{2i} \oint_{C} dP e^{iPx} \frac{\tilde{A}(P)}{\sin(aP/2)},$$

(2.4)
where the contour $C$ is shown in figure 1. An assumption is then made that $\tilde{A}(P)$ is an analytic function, with poles or cuts only along the imaginary $P$ axis. The contour $C$ can therefore be deformed to a contour $C'$, which implies that

$$S(E) = \frac{\text{Disc}_E[\tilde{A}(iE)]}{2 \sinh(aE/2)},$$

(2.5)

where

$$\text{Disc}_E[f(E)] \equiv -i[f(E + i\epsilon) - f(E - i\epsilon)].$$

(2.6)

The above prescription was then applied to the two-point disk amplitude. We repeat the computation in the boundary state approach, since that is the one which is easiest to generalize to higher order. This amplitude has a single modulus, which in the parameterization of $[1]$ corresponds to the radius of the boundary $\rho$. The disk corresponds to $|z| \geq \rho$, and the two insertions are fixed at $z = 1$ and $z = \infty$. The amplitude is therefore given by

$$\tilde{A}(p_1, p_2) = \int_0^1 \frac{d\rho}{\rho} \langle 0 | V(p_1; \infty) V(p_2; 1) (b_0 + \tilde{b}_0) \rho^{L_0 + \tilde{L}_0} | \tilde{B} \rangle,$$

(2.7)

where $|\tilde{B}\rangle$ is a boundary state at radius 1 corresponding to a D-brane located at $x = 0$, and the operator $\rho^{L_0 + \tilde{L}_0}$ propagates the boundary state from radius 1 to radius $\rho \leq 1$. Inserting a complete set of closed string states and integrating over $\rho$ gives

$$\tilde{A}(p_1, p_2) = \int dk \sum_i \langle 0 | V(p_1; \infty) V(p_2; 1) | k, i \rangle \frac{1}{\frac{k^2}{2} + 2l_i} \langle k, i | (b_0 + \tilde{b}_0) | \tilde{B} \rangle,$$

(2.8)

where $l_i$ is the level of the state $|k, i\rangle$. Applying the prescription (2.5) then gives the three-point sphere amplitude

$$S(p_1, p_2) = \langle 0 | V(p_1; \infty) V(p_2; 1) | W_E \rangle,$$

(2.9)

where $|W_E\rangle$ is a physical (ghost number two) closed string state defined in terms of the Wick-rotated boundary state

$$|W_E\rangle \equiv \int dk \sum_i |k, i\rangle \frac{\delta(k^2/2 + 2l_i)}{2 \sinh(Ea/2)} (b_0 + \tilde{b}_0) | B \rangle = \frac{\delta(L_0 + \tilde{L}_0)}{2 \sinh(Ea/2)} (b_0 + \tilde{b}_0) | B \rangle.$$

(2.10)

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1The boundary state itself is not a physical state since it has ghost number 3.
2.2 Any number of boundaries

Consider now an amplitude with \( b \) boundaries. Here we need to take into account the possibility of associating different boundaries to different D-branes in the spatial array. Denote by \( \tilde{A}_{n_1...n_b} \) the amplitude with the first boundary on the \( n_1 \)th brane, the second on the \( n_2 \)th brane, etc. The total amplitude is then given by

\[
\tilde{S} = \frac{1}{b!} \sum_{\{n_j\}} \tilde{A}_{n_1...n_b} . \tag{2.11}
\]

In terms of the boundary-momentum-space amplitude \( \tilde{A}(k_1, \ldots, k_b) \) this becomes

\[
\tilde{S} = \frac{1}{b!} \sum_{\{n_j\}} \int \prod_{j=1}^{b} [dk_j \, e^{iak_j(n_j+1/2)}] \tilde{A}(k_1, \ldots, k_b) \delta \left( \sum_{j=1}^{b} k_j - P \right) \\
= \frac{1}{b!} \int \prod_{j=1}^{b} dk_j \, \tilde{S}(k_1, \ldots, k_b) \delta \left( \sum_{j=1}^{b} k_j - P \right) , \tag{2.12}
\]

where \( P \) is the total momentum in the direction of the array, and

\[
\tilde{S}(k_1, \ldots, k_b) = \tilde{A}(k_1, \ldots, k_b) \prod_{j=1}^{b} \sum_{n_j = -\infty}^{\infty} (\frac{1}{2\pi})^2 \delta(k_j a - 2\pi n_j) . \tag{2.13}
\]
For $b = 1$ this reduces to the disk amplitude (2.1). Consider the Fourier transform of this expression with respect to the boundary momentum $k_1$,

$$
\tilde{G}(x, k_2, \ldots, k_b) = \int dk_1 e^{ik_1 x} \tilde{\mathcal{S}}(k_1, \ldots, k_b)
= \frac{1}{2i} \oint_C dk_1 e^{ik_1 x} \tilde{A}(k_1, \ldots, k_b) \prod_{j=2}^{b} \sum_{n_j=-\infty}^{\infty} 2\pi \delta(k_j a - 2\pi n_j). \quad (2.14)
$$

As before, we would like to deform the contour to $C'$. Unlike the single boundary case however, we cannot assume that $\tilde{A}(k_1, \ldots, k_b)$ has singularities only along the imaginary $k_1$ axis. Generically it will have singularities also along a finite number of lines parallel to the imaginary axis. Schematically, these arise from terms of the form

$$\frac{1}{(k_1 - q)^2 + a^2},$$

where $q$ is some combination of the other boundary momenta. The deformed contour will then contain a number of contours like $C'$. Upon Fourier transforming back we obtain an expression for $\tilde{S}(k_1, \ldots, k_b)$ in terms of the contour integrals. However, since we are interested in the Wick-rotated amplitude with $k_1 = iE_1$ and $E_1$ real, only the contour on the imaginary axis contributes, and the result is

$$
\tilde{S}(iE_1, k_2, \ldots, k_b) = \frac{\text{Disc}_{E_1} \tilde{A}(iE_1, k_2, \ldots, k_M)}{2 \sinh(aE_1/2)} \prod_{j=2}^{b} \sum_{n_j=-\infty}^{\infty} 2\pi \delta(k_j a - 2\pi n_j). \quad (2.15)
$$

Repeating this procedure for the rest of the boundary momenta $k_2, \ldots, k_b$ we obtain

$$
S(E_1, \ldots, E_b) = \frac{\text{Disc}_{E_1} [\text{Disc}_{E_2} [\ldots \text{Disc}_{E_b} [\tilde{\mathcal{S}}(iE_1, \ldots, iE_b)]]]}{\prod_{j=1}^{b} 2 \sinh(aE_j/2)}. \quad (2.16)
$$

The total amplitude is then given by

$$
S(E) = \frac{1}{b!} \int \left[ \prod_{i=1}^{b} dE_i \right] \delta \left( \sum_{k=1}^{b} E_i - E \right) S(E_1, \ldots, E_b), \quad (2.17)
$$

where $E = -iP$ is the total energy. This will be our prescription for calculating amplitudes off a periodic array of D-branes in imaginary time. For more general brane configurations see Appendix A. The prescription of [1] is recovered by setting $b = 1$. 


Figure 2: (a) The usual parametrization of the annulus, and (b) the new parametrization of the annulus.

3. Annulus two-point amplitude

Let us now apply our prescription to the two-point annulus amplitude. We first need to choose a convenient parameterization of the annulus. Consider the usual parameterization of the annulus (Fig. 2a): the external radius is 1, the internal radius is \( \rho \), one insertion is located on the real axis (using rotational symmetry) at \( r \), and the other is located at \( z \). The modulus \( \rho \) satisfies \( 0 \leq \rho \leq r \leq 1 \). We would like to integrate over the radii and fix as many insertions as possible. Consider then the transformation \( z \to z/r \). This fixes the position of the first insertion at 1, and gives

\[
\rho_{\text{out}} = \frac{1}{r}, \quad \rho_{\text{in}} = \frac{\rho}{r}, \quad z' = \frac{z}{r}
\]  

(3.1)

for the external radius, internal radius, and position of the second insertion, respectively (Fig. 2b). These are the (four) real moduli of the annulus with two insertions. The radii satisfy \( 1 \leq \rho_{\text{out}} \leq \infty \) and \( 0 \leq \rho_{\text{in}} \leq 1 \). The amplitude is then given by

\[
\tilde{A}(p_1, p_2) = \int d^2 z' \int_0^1 \frac{d\rho_{\text{in}}}{\rho_{\text{in}}} \int_1^\infty \frac{d\rho_{\text{out}}}{\rho_{\text{out}}} \langle \tilde{B}|\rho_{\text{out}}^{-L_0-L_a}(b_0 + \tilde{b}_0)V_1(p_1; 1, 1)V_2(p_2; z', \bar{z}') (b_0 + \tilde{b}_0)\rho_{\text{in}}^{L_0+L_a} |\tilde{B}\rangle,
\]  

(3.2)

Inserting complete sets of states, and integrating over the radii gives

\[
\tilde{A}(p_1, p_2) = \int dk_1dk_2 \tilde{A}(k_1, k_2; p_1, p_2),
\]  

(3.3)
where
\[ \tilde{A}(k_1, k_2; p_1, p_2) = \sum_{i,j} \int d^2 z' \langle \tilde{B}|(b_0 + \tilde{b}_0)|k_1, i\rangle \langle k_1, i| \frac{1}{k_1^2 + 2l_i} \]

\[ V_1(p_1; 1, 1)V_2(p_2; z', \bar{z}') \frac{1}{k_2^2 + 2l_j}|k_2, j\rangle\langle k_2, j|\tilde{B} \rangle. \]

This is the amplitude corresponding to boundary momenta \( k_1 \) and \( k_2 \), to which we will apply our general prescription (2.16). It is apparent that this amplitude has poles on the imaginary \( k_1 \) and \( k_2 \) axes, which will contribute to the discontinuities. Additional singularities can arise from the integral over \( z' \), but as we shall argue in the next section, their contribution can be neglected in (2.16). We therefore obtain for the total amplitude

\[ S(p_1, p_2) = \frac{1}{2} \int dE_1 \int d^2 z' \langle W_{E_1}|V_1(p_1; 1, 1)V_2(p_2; z', \bar{z}')|W_{E-E_1} \rangle. \]

As anticipated, we obtain the amplitude for four closed string states on the sphere. We can also express this as

\[ S(p_1, p_2) = \frac{1}{2}\langle W(\infty, \infty)V_1(p_1; 1, 1)V_2(p_2; z', \bar{z}')W(0, 0) \rangle, \]

where \( W(z, \bar{z}) \) is the vertex operator corresponding to the state \( \int dE|W_E \rangle \).

4. Collisions of boundaries and insertions

Before we generalize this result to higher orders, let us turn our attention to the possible contributions of other singularities. Amplitudes with boundaries and bulk insertions can have four types of singularities, arising respectively from a shrinking boundary, the collision of two vertex operators, the collision of a vertex operator and a shrinking boundary and the collision of two shrinking boundaries. The singularities are all poles, and are associated with the emission of an on-shell closed string. In the previous section we assumed that only the shrinking-boundary singularities contribute to the discontinuity in the annulus amplitude. In the next section we will assume that the same holds for the discontinuity of a general amplitude. This is a crucial condition for producing the correct closed string amplitudes. Here we will show that it is actually implied by the choice of analytic continuation.

Consider first a shrinking-boundary singularity. Apart from analytic factors, the amplitude with a shrinking boundary is basically of the form

\[ \tilde{A}_B(k) = \frac{1}{k^2 + m^2}, \]
where $k$ is the momentum of the shrinking boundary. This amplitude was used as an illustration of a disk amplitude in [1]. Their strategy for computing the amplitude for an array of D-branes in imaginary time was to Fourier-transform to position space, sum over an array of D-branes in space, analytically continue to imaginary time and finally transform back to momentum (energy) space. In position space we get

$$\tilde{G}_B(x) = \int dk e^{ikx} \tilde{A}_B(k) = \frac{\pi}{m} e^{-m|x|}.$$  \hfill (4.2)

Summing over the array then gives

$$\tilde{G}_{B,\text{array}}(x) = \frac{\pi}{m} \sum_{n=-\infty}^{\infty} e^{-m|x+an+\frac{1}{2}a|} = \frac{\pi}{m} f(mx) \frac{\sinh(ma/2)}{\sinh(ma/2)},$$  \hfill (4.3)

where the function $f(mx)$ is defined as $\cosh(mx)$ for $-\frac{1}{2}a \leq x \leq \frac{1}{2}a$, and is periodic with period $a$. This expression is not analytic, however it is analytic within each period. A natural prescription for analytically continuing it to the imaginary axis is to focus on the branch around the origin, i.e. $f(mx) = \cosh(mx)$ for all $x$, in which case

$$G_{B,\text{array}}(x^0) = \frac{\pi}{m} \frac{\cos(mx^0)}{\sinh(ma/2)},$$  \hfill (4.4)

and in momentum space

$$S_B(E) = \frac{\pi}{2m \sinh(ma/2)} [\delta(E-m) + \delta(E+m)] = \frac{\pi \delta(E^2 - m^2)}{\sinh(ma/2)}. \hfill (4.5)$$

This agrees precisely with the general prescription (2.16) applied to (4.1).

The other singularities, corresponding to the collision of insertions and shrinking boundaries, arise when the sum of the momenta of the two colliding elements is on-shell for some closed string state. Thus amplitudes with two colliding insertions, a colliding insertion and shrinking boundary and two colliding shrinking boundaries are respectively of the qualitative form

$$\tilde{A}_{VV}(p_1, p_2) = \frac{1}{(p_1 + p_2)^2 + m^2}$$  \hfill (4.6)

$$\tilde{A}_{VB}(k, p) = \frac{1}{k^2 + m^2} \frac{1}{(k + p)^2 + m^2}$$  \hfill (4.7)

$$\tilde{A}_{BB}(k_1, k_2) = \frac{1}{k_1^2 + m_1^2} \frac{1}{k_2^2 + m_2^2} \frac{1}{(k_1 + k_2)^2 + m^2}.$$  \hfill (4.8)

In the case of the annulus two-point amplitude, for example, there is a singularity of the first type when $z' \to 1$ and $(p_1 + p_2)^2$ is on-shell, and a singularity of the second type
when \( \rho_{\text{in}} \to 0, z' \to 0 \) and \((p_1 + k_1)^2 \) is on-shell (and another when \( \rho_{\text{out}} \to \infty, z' \to \infty \) and \((p_1 + k_2)^2 \) is on-shell). Boundary-boundary singularities will arise when there are more boundaries. As explained in [1], the poles coming from collisions of vertex operator insertions (4.6) are harmless, since one can always define the amplitude by analytically continuing the external momenta \( p_i \) off-shell away from the singularity. The same argument does not work for the boundary momenta \( k_j \), since the amplitude contains an integral over all their possible values. We therefore need a different argument for the insertion-boundary and boundary-boundary poles.\(^2\)

Let us compute directly the amplitudes for D-branes in imaginary time derived from (4.7) and (4.8) using the same strategy as above. In both cases there are poles from shrinking boundaries and poles from collisions. We will show that only the former contribute in our prescription. In position space we get

\[
\tilde{G}_{VB}(x) = \frac{\pi}{2mm'} \int_{-\infty}^{\infty} dy e^{-m'|y|-ipy} e^{-m|x-y|} \tag{4.9}
\]

\[
\tilde{G}_{BB}(x_1, x_2) = \frac{\pi^2}{2m_1m_2m} \int_{-\infty}^{\infty} dy e^{-m_1|y-x_1|} e^{-m_2|y-x_2|} e^{-m|y|}. \tag{4.10}
\]

Summing over the array then gives

\[
\tilde{G}_{VB,\text{array}}(x) = \frac{\pi}{2mm'} \int_{-\infty}^{\infty} dy e^{-m'|y|-ipy} \frac{f(m(x-y))}{\sinh(ma/2)} \tag{4.11}
\]

\[
\tilde{G}_{BB,\text{array}}(x_1, x_2) = \frac{\pi^2}{2m_1m_2m} \int_{-\infty}^{\infty} dy \frac{f(m_1(y-x_1))}{\sinh(m_1a/2)} \frac{f(m_2(y-x_2))}{\sinh(m_2a/2)} e^{-m|y|}, \tag{4.12}
\]

where \( f \) is the same periodic function as before. We need to specify again how to analytically continue \( f \) to the imaginary axis. The most natural choice is to use the same prescription as before, namely to replace \( f(m(x-y)) \) with \( \cosh(m(x-y)) \) in both (4.11) and (4.12). Wick rotating and then transforming back to momentum space we finally get

\[
S_{VB}(E) = \frac{\pi \delta(E^2 - m^2)}{\sinh(ma/2)} \frac{1}{(E - ip)^2 - m^2} \tag{4.13}
\]

\[
S_{BB}(E_1, E_2) = \frac{\pi \delta(E_1^2 - m_1^2)}{\sinh(m_1a/2)} \frac{\pi \delta(E_2^2 - m_2^2)}{\sinh(m_2a/2)} \frac{1}{(E_1 + E_2)^2 - m^2}, \tag{4.14}
\]

in complete agreement with our assertion that the general prescription (2.16) receives contributions only from shrinking boundaries.\(^2\)

\(^2\)For the special case of the disk, the insertion-boundary pole is harmless for the same reason as above. Momentum conservation implies that if \( p_1 + k \) is on-shell, then so is the sum of all the other external momenta \( \sum_{i=2}^{n} p_i \), and the latter can be analytically continued off-shell in the amplitude.
The generalization to an arbitrary number of colliding vertices and shrinking boundaries is straightforward. The singular part of the amplitude is

\[
\prod_{j=1}^{b} \frac{1}{k_j^2 + m_j^2} \frac{1}{(\sum_{i=j}^{b} k_j + \sum_{i=1}^{n} p_i)^2 + m^2},
\]  

(4.15)

which gives

\[
\frac{\pi^b}{2m} \prod_{j=1}^{b} m_j \int_{-\infty}^{\infty} dy \prod_{j=1}^{b} \frac{f(m_j(y - x_j))}{\sinh(m_j a/2)} e^{-m|y| - iy \sum p_i},
\]  

(4.16)

for the position space amplitude of the array. Applying the same prescription gives

\[
\prod_{j=1}^{b} \pi \delta(E_j^2 - m_j^2) \frac{1}{\sinh(m_j a/2)} \frac{1}{(\sum_{j=1}^{b} E_j)^2 - m^2},
\]  

(4.17)

which is precisely what one would get by computing the discontinuities of (4.15) from the shrinking boundaries.

In summary, only the poles coming from boundaries shrinking to points contribute in our prescription (2.16). The other poles remain in the resulting amplitudes, e.g. (4.17), as they should for closed string amplitudes.

5. General amplitudes

A sphere amplitude with \( b \) boundaries and \( n \) closed string vertices has \( 3b \) boundary moduli and \( 2n \) closed string moduli. The CKVs of the sphere can be used to fix the positions of three boundaries, leaving integrations over the remaining \( b - 3 \) complex boundary positions, \( b \) boundary radii and \( n \) complex positions of the vertices. The dimensionality of the moduli space is the same as for an \( (n + b) \)-punctured sphere with additional integrations over the boundary sizes. More generally, a genus \( g \) amplitude with \( n \) closed string vertices and \( b \) boundaries has \((6g - 6 + 2n + 2b)\) real moduli, which is the same same as a genus \( g \) amplitude with \( n + b \) vertices and no boundaries plus the extra boundary size integrals.

We have shown that the general prescription for computing any amplitude involving an array of D-branes in imaginary time (2.16) receives a contribution only in the limit where all the boundaries have a vanishing size. To see that this corresponds precisely to a closed string amplitude we still need to show that the moduli space of the resulting punctured Riemann surface is covered completely and without overlap. In other words we require a slicing of the moduli space of punctured Riemann surfaces with boundaries,
and a slicing of the moduli space of punctured Riemann surfaces without boundaries, such that the former reduces to the latter when all the boundaries shrink. Such slicings have been constructed by Zwiebach in the context of closed string field theory [9], and open/closed string field theory [10]. We will use these to demonstrate the above reduction. Let us first review (very) briefly Zwiebach’s results.

5.1 Zwiebach’s closed and open/closed SFTs

String field theory can be viewed as a set of vertices, which can be used to build any string amplitude using Feynman rules. One of the main difficulties in doing this for the closed string (covariantly) is the need to cover the moduli space of every diagram completely and exactly once. This problem was solved by Zwiebach for the purely closed bosonic string in [9]. The closed string vertices \( \langle V_{g,n} \rangle \) are defined in terms of regions of the moduli space \( V_{g,n} \) satisfying two properties. The first is that every diagram formed with the vertices has a minimal area metric, subject to the constraint that every non-contractible closed curve on it has length greater than or equal to \( 2\pi \). This implies that every point in the moduli space is covered at most once. It also implies that the vertices have stubs of length \( \pi \). In addition, the vertices satisfy recursion relations, which can be expressed concisely as

\[
\partial V + \frac{1}{2} \{ V, V \} + \hbar \Delta V = 0 , \tag{5.1}
\]

where \( V \) represents the formal sum of the vertices \( V_{g,n} \). The operation \( \{ , \} \) corresponds to sewing two punctures located on different vertices, \( \Delta \) corresponds to sewing two punctures on the the same vertex, and \( \partial \) is the boundary operator. The specific relation for the moduli space of a given topology \( \mathcal{M}_{g,n} \) is recovered by considering all terms of the same topology. This relation guarantees that every point in the moduli space is covered. For example, for the four-punctured sphere one gets

\[
\partial V_{0,4} + \frac{1}{2} \{ V_{0,3}, V_{0,3} \} = 0 . \tag{5.2}
\]

This shows that the four-punctured sphere is covered fully and without overlap by four regions, corresponding to the three diagrams formed by two 3-string vertices and a propagator, and the 4-string vertex.

In [10] it was shown how to extend this framework to open and closed string field theory. One defines string vertices which include \( b \) boundaries and \( m \) boundary insertions, \( \gamma_{g,n}^{b,m} \), using the same properties as above, where the definitions of the anti-bracket and \( \Delta \) are extended to incorporate the sewing of open string vertices as well. The purely closed string vertices are then the same as before, namely \( \gamma_{g,n}^{0,0} = V_{g,n} \).
5.2 General amplitudes of imaginary-time D-branes

Consider a genus $g$ amplitude with $n$ closed string insertions and $b$ boundaries (and no open string insertions). What we are trying to show is that if the boundaries correspond to an array of D-branes in imaginary time, this amplitude is identical to a genus $g$ amplitude with $n + b$ insertions and no boundaries. Qualitatively they are the same, since the general prescription picks out the limit of vanishing boundaries, and our arguments in section 4 show that other limits do not contribute. However one still needs to show that the closed string moduli space is properly covered in this limit.

The moduli space of the amplitude with boundaries is divided into several regions, each corresponding to a different diagram built from vertices with boundaries and propagators. In particular, there exists a region of the moduli space in which the diagram is built by connecting $b$ string-boundary vertices $\mathcal{V}_{0,1}^{1,0}$ to the genus $g$ $(n + b)$-string vertex $\mathcal{V}_{g,n+b}^{0,0}$ using $b$ propagators. The region corresponds to varying the length of each propagator from zero to infinity. When a particular propagator has zero length we get the stitch $\{\mathcal{V}_{0,1}^{1,0}, \mathcal{V}_{g,n+b}^{0,0}\}$, which matches on to the boundary of the region built with $\mathcal{V}_{g,n+b-1}^{1,0}$. The limit in which all the propagators have infinite length corresponds to the diagram where all the boundaries have zero size. As we argued in the previous section, this is the only relevant part of the amplitude for the general prescription. The above region is therefore the only relevant region, and since $\mathcal{V}_{g,n+b}^{0,0} = \mathcal{V}_{g,n+b}$ we conclude that the slicing of the closed string moduli space is correctly recovered.

Figure 3: A general amplitude with boundaries introduced via closed string boundary vertices.

3The string-boundary vertex corresponds to the boundary state $|B\rangle$. 
The only thing which remains to be shown is that the $b$ additional insertions correspond to the state $|W\rangle$. To this end we will compute the contribution of the above region to the amplitude explicitly, and then apply the prescription (2.16). Let us denote the positions of the closed string insertions by $z_i$, the positions of the boundaries by $\zeta_j$, and their radii by $\rho_i$. The lengths of the propagators correspond to the radii of the boundaries: infinite length corresponds to zero radius, and zero length to some maximal radius $\rho_i^{\text{max}}$. The amplitude is therefore given by (we omit the ghosts for the sake of clarity)

$$
\tilde{A}_{g,n}^{b_0}(p_1, \ldots, p_n) = \langle V_{g,n+b}^{0,0} \prod_{i=1}^{n} |V_i(p_i; z_i, \bar{z}_i)\rangle \prod_{j=1}^{b} \int_{0}^{\rho_j^{\text{max}}} \frac{d\rho_j}{\rho_j} \frac{L_j^{(j)} + \tilde{L}_j^{(j)}}{L_0^{(b)} + \tilde{L}_0^{(b)}} |B_j(\zeta_j, \bar{\zeta}_j)\rangle. \quad (5.3)
$$

The integrals over the position and genus moduli are included in the closed string vertex $\langle V_{g,n+b}^{0,0} \rangle$. The range of integration of each radius will depend in general on all the other moduli. However, as we shall see, our result is independent of the details of this dependence. Performing the $\rho_b$ integral gives

$$
\tilde{A}_{g,n}^{b_0}(p_1, \ldots, p_n) =
\langle V_{g,n+b}^{0,0} \prod_{i=1}^{n} |V_i(p_i; z_i, \bar{z}_i)\rangle \prod_{j=1}^{b-1} \int_{0}^{\rho_j^{\text{max}}} \frac{d\rho_j}{\rho_j} \frac{L_j^{(j)} + \tilde{L}_j^{(j)}}{L_0^{(b)} + \tilde{L}_0^{(b)}} |B_j(\zeta_j, \bar{\zeta}_j)\rangle \delta(L_0^{(b)} + \tilde{L}_0^{(b)}) |B_b(\zeta_b, \bar{\zeta}_b)\rangle. \quad (5.4)
$$

Inserting a complete set of momentum states for the $b$th boundary, and computing the discontinuity with respect to $E_b$ then gives

$$
-2\pi \langle V_{g,n+b}^{0,0} \prod_{i=1}^{n} |V_i(p_i; z_i, \bar{z}_i)\rangle \prod_{j=1}^{b-1} \int_{0}^{\rho_j^{\text{max}}} \frac{d\rho_j}{\rho_j} \frac{L_j^{(j)} + \tilde{L}_j^{(j)}}{L_0^{(b)} + \tilde{L}_0^{(b)}} |B_j(\zeta_j, \bar{\zeta}_j)\rangle \delta(L_0^{(b)} + \tilde{L}_0^{(b)}) |B_b(\zeta_b, \bar{\zeta}_b)\rangle = 0. \quad (5.5)
$$

That the result is independent of $\rho_b^{\text{max}}$ follows from $\text{Disc}(\rho^E/E) = -2\pi \rho^E \delta(E) = -2\pi \delta(E)$. Repeating this procedure for the remaining radii we obtain

$$
(-2\pi)^b \langle V_{g,n+b}^{0,0} \prod_{i=1}^{n} |V_i(p_i; z_i, \bar{z}_i)\rangle \prod_{j=1}^{b} \delta(L_0^{(j)} + \tilde{L}_0^{(j)}) |B_j(\zeta_j, \bar{\zeta}_j)\rangle, \quad (5.6)
$$

The total amplitude which follows from (2.16) and (2.17) is therefore given by

$$
S(p_1, \ldots, p_n) = \frac{1}{b!} \langle V_{g,n+b}^{0,0} \prod_{i=1}^{n} |V_i(p_i; z_i, \bar{z}_i)\rangle \prod_{j=1}^{b-1} \int dE_j |W_{E_j}\rangle |W_{E - \sum_{j=1}^{b-1} E_j}\rangle, \quad (5.7)
$$
where $E$ is the total energy of the closed string insertions. This can also be expressed as

$$S(p_1, \ldots, p_n) = \frac{1}{b!} \int_{V_{g,n+b}} \langle \prod_{i=1}^{n} V_i(p_i; z_i, \bar{z}_i) \prod_{j=1}^{b} W(\zeta_j, \bar{\zeta}_j) \rangle .$$

(5.8)

So any amplitude with $b$ boundaries corresponding to an array of D-branes in imaginary time is identical to an amplitude without boundaries, but with $b$ additional insertions of the physical closed string state $|W\rangle$. The $1/b!$ combinatoric factor ensures that the amplitudes exponentiate properly to give a macroscopic closed string background.

6. Conclusions

We have generalized the prescription for computing closed string amplitudes in the background of an array of D-branes in imaginary time to arbitrary order, and used it to show that an amplitude with $b$ boundaries is identical to an amplitude without boundaries and with $b$ additional insertions of a particular physical closed string state $|W\rangle$. Summing over the boundaries then corresponds to an insertion of $\exp \int d^2z W(z, \bar{z})$, which corresponds to a closed string background.

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A. A pair of branes in imaginary time

The simplest configuration of branes in imaginary time which corresponds to a real closed string background consists of two D-branes located at $x_0 = \pm ia [I]$. The line of argument is similar to the one used in the array case. We start with the amplitude for a pair of D-branes at $x = \pm a$ in real space

$$\tilde{S}(P) = \frac{1}{b!} \int \prod_{j=1}^{b} dk_j \left( e^{ia k_j} + e^{-ia k_j} \right) \tilde{A}(k_1, \ldots, k_b) \delta \left( \sum_{j=1}^{b} k_j - P \right) .$$

(A.1)

Let us concentrate on the contribution of the brane at $x = a$, i.e. the term with $e^{ia k_j}$. The contribution of the other brane will be similar, and we will add it in later. We can

---

We will suppress the external momenta and indices in this section.
assume that $a > 0$ without loss of generality. Fourier transforming the integrand with respect to $k_1$ gives

$$
\tilde{G}(x, k_2, \ldots) = \int_{-\infty}^{\infty} dk_1 e^{ik_1x} \tilde{A}(k_1, \ldots, k_b) \prod_{j=1}^{b} e^{iak_j}.
$$

(A.2)

The $k_1$ integration contour can be closed by an infinite semi-circle from above for $x + a > 0$, and from below for $x + a < 0$ (Fig. 4). Assuming, as before, that the only singularities of $\tilde{A}(k_1, \ldots)$ are on the imaginary $k_1$ axis, we deform the contour to $C'_{\pm}$ (Fig. 5). Back in momentum space we then get

$$
\tilde{S}(k_1, \ldots, k_b) = \int_{-\infty}^{\infty} dx \tilde{G}(x, k_2, \ldots) e^{-ik_1x}
= \int_{-\infty}^{-a} dx \int^{c'_{-}} dk e^{-i(k_1-k)x} e^{iak} \prod_{j=2}^{b} e^{iak_j} \tilde{A}(k, k_2, \ldots, k_b)
+ \int_{-a}^{\infty} dx \int^{c'_{+}} dk e^{-i(k_1-k)x} e^{iak} \prod_{j=2}^{b} e^{iak_j} \tilde{A}(k, k_2, \ldots, k_b).
$$

(A.3)
Using\(^5\)

\[
\int_c^\infty \, dx \, e^{iwx} = \begin{cases} 
\delta(w) & \text{for } c < 0 \\
0 & \text{for } c > 0 
\end{cases}
\]  \hspace{1cm} (A.4)

we obtain (after the Wick rotation)

\[ S(E_1, \ldots, k_b) = \Theta(E_1) e^{-[aE_1]} \prod_{j=2}^b e^{iak_j} \text{Disc}_{E_1} \tilde{A}(iE_1, k_2, \ldots, k_b) . \]  \hspace{1cm} (A.5)

For the brane at \( x = -a \) we replace \( e^{iak_j} \) with \( e^{-iak_j} \) in (A.3), and exchange the contours \( C'_+ \) and \( C'_- \). The net result is to change \( \Theta(E_1) \) to \( -\Theta(-E_1) \) above. Repeating the procedure for the other boundary momenta, and adding the contribution of the other brane, gives

\[ S(E) = \frac{1}{b!} \int \prod_{j=1}^b dE_j \, S(E_1, \ldots, E_b) \, \delta \left( \sum_{k=1}^M E_i - E \right) , \]  \hspace{1cm} (A.6)

where \( E = -iP \) and

\[ S(E_1, \ldots, E_b) = \prod_{j=1}^b \text{sign}(E_j) e^{-[aE_j]} \text{Disc}_{E_b} [...] \text{Disc}_{E_1} \tilde{A}(iE_1, \ldots, iE_b)] ... \]  \hspace{1cm} (A.7)

\(^5\)We define the \( x \) integrals as \( \int_a^\infty dx \, e^{iwx} = \lim_{n \to \infty} \int_a^{a + \frac{2\pi n}{w}} dx \, e^{iwx} \). This vanishes unless \( \omega = 0 \). Furthermore \( \int_{-\infty}^{\infty} d\omega \int_a^\infty dx \, e^{ixw} = \int_a^\infty dx \, \delta(x) \), which vanishes for \( a > 0 \) and is 1 for \( a < 0 \). This implies the above result.

\textbf{Figure 5:} The two deformed contours for \( x + a > 0 \) and \( x + a < 0 \)
For $b = 1$ this reduces to the result in [1]. One can also reproduce the result for the periodic array (2.16) by summing over an infinite number of pairs.

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