Validation and application of the lattice Boltzmann algorithm for a turbulent immiscible Rayleigh-Taylor system

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We develop a multicomponent lattice Boltzmann (LB) model for the 2D Rayleigh–Taylor turbulence with a Shan-Chen pseudopotential implemented on GPUs. In the immiscible case this method is able to accurately overcome the inherent numerical complexity caused by the complicated structure of the interface that appears in the fully developed turbulent regime. Accuracy of the LB model is tested both for early and late stages of instability. For the developed turbulent motion we analyze the balance between different terms describing variations of the kinetic and potential energies. Then, we analyze the role of interface in the energy balance, and also the effects of the vorticity induced by the interface in the energy dissipation. Statistical properties are compared for miscible and immiscible flows. Our results can also be considered as a first validation step to extend the application of LB model to 3D immiscible Rayleigh-Taylor turbulence.

1. Introduction

When a heavier fluid is suspended atop a lighter fluid, the so-called Rayleigh–Taylor (RT) instability can develop, which eventually leads to a mixing layer with a turbulent motion called Rayleigh-Taylor turbulence. Physical experiments of the RT instability have been challenging due to the difficulty of sustaining an unstable density stratification necessary to set up the appropriate initial conditions for the instability [1, 2, 3, 4, 5].

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Despite this limitation, considerable advances in numerical simulations of the Rayleigh-Taylor instability have been verified in the last decades, specially in the context of the systems with miscible fluids [6, 7, 8, 9, 10, 11, 12]. Fewer works have been dedicated to the immiscible 2D viscous case [1, 13, 14, 15, 16, 17, 18, 19, 20], and most of them are devoted to early stages of the instability with little information about the state of developed turbulence. Only recently, the 2D immiscible RT instability was simulated for high Reynolds numbers [17, 18, 21, 22, 23]. To the best of our knowledge, only [21] simulated a statistically homogeneous fully developed turbulent mixing layer compatible with classical phenomenological theories for immiscible RT turbulence [6, 24]. One of the reasons for this is the highly complicated pattern formed by the interfaces that appear in the immiscible case, originating high gradients and singularities in the solutions. This is a source of challenging numerical instabilities in many numerical methods for multicomponent fluids. To the best of our knowledge, only recently the energy budget for miscible case was analyzed [11], and no analysis of the immiscible case have been reported in the scientific literature.

In this article, we investigate the immiscible RT turbulence using numerical simulations based on the multicomponent lattice-Boltzmann method with Shan-Chen pseudopotential model [25, 26, 27]. This method is able to accurately overcome the inherent numerical complexity caused by the structure of the interface that appears in the fully developed turbulent regime [1, 13, 28]. This method, similarly to other lattice Boltzmann methods, also admits parallel implementations in many situations, which is very important for statistical analyses that require a substantial number of simulations. We run several simulations of the RT turbulence (at least 10 simulations for each experiment presented in this article) in parallel on GPUs using CUDA with a computational grid of resolution $10^4 \times 5.000$. It is important to emphasize that some other diffuse interface methods may also be able to treat the same complex interfacial phenomena described in this article, see [20, 29, 30, 31, 32] for a recent discussion.

In the present article, we perform a number of numerical tests justifying validity of the LB model for the RT instability. We analyse the energy budget in the RT flows with the emphasis on the effects of interface and dissipation, and comparing the results with the miscible RT system. We verify that non-isotropic contributions to the stress tensor due to variations of order parameter are small in the miscible case. In the immiscible flow, these contributions grow in time following the increase of the interface length, but remain small compared to buoyancy and viscous contributions. Also, numerical anisotropy of the Shan-Chen force generates spurious currents [33, 34] within thin diffuse interfaces, which do not affect most of our measurements but may interfere in the results for enstrophy. We note that, in the companion article [21], we apply the proposed numerical scheme for the investigation of the long-time behavior of RT systems and verify a series of phenomenological predictions.

The paper is organized as follows. Section 2 describes details of the lattice Boltzmann model. In the section 3, we study the evolution of the kinetic and potential energies of the systems, comparing miscible and immiscible systems side by side. In the subsection (a), we analyze the influence of the interface in the energy balance for the immiscible Rayleigh-Taylor flows, by calculating the total energy of the interface and showing connections with different terms in the kinetic energy variations. Some differences due to the energy necessary to form the interfaces are expected [35, 36, 37, 38], which also lead to an extra generation of the vorticity [39, 40]. To investigate such possibility, we calculate numerically the energy of the interface and we compare with the energy flux due to the Korteweg stress tensor [37, 41]. The generation of vorticity at the interface is investigated by analyzing the evolution of the enstrophy in the subsection (b). We also analyze the existence of critical points in the transition to turbulent regimes in the immiscible case by studying the evolution of the density profiles in the final part of the subsection (a). We summarize the results in the Conclusion.
2. Lattice Boltzmann model

In this section, we describe the two-component lattice Boltzmann method for simulating immiscible and miscible Rayleigh-Taylor systems in Boussinesq approximation; we refer to [25, 26] and specially [21] for more details. In this method, spatial coordinates and time take values on the lattice with spacings \( \Delta x \) and \( \Delta t \), and the system is described by the interactions between two species of particles, A and B. Considering the so-called D2Q9 scheme, each particle is allowed to have nine velocities \( c_0, \ldots, c_8 \). These velocities are given by the vectors \((0,0), (\pm c, 0), (0, \pm c)\) and \((\pm c, \pm c)\) with \( \epsilon = \Delta x/\Delta t \), such that a particle either stays at the same or moves to a neighboring lattice point in a single time step. The system is described by the functions \( f_i^s(x, t) \) determining the number of particles of component \( s = A \) or \( B \) and velocity \( c_i \) at a given point and time. The densities of each component and common velocity of the fluid are defined as

\[
\rho_s(x, t) = \sum_i f_i^s(x, t), \quad u(x, t) = \frac{\sum_i f_i^s(x, t)c_i/\tau_s}{\sum_s \rho_s(x, t)/\tau_s},
\]

where \( s = A, B \) and \( i = 0, \ldots, 8 \). The total density is given by the sum \( \rho = \rho_A + \rho_B \).

The evolution is governed by the lattice-Boltzmann equations with the Bhatnagar-Gross-Krook collision term [26]

\[
f_i^s(x + c_i \Delta t, t + \Delta t) - f_i^s(x, t) = -\frac{1}{\tau_s} \left[ f_i^s(x, t) - f_i^{s(eq)}(\rho_s, u + \tau_s F_s/\rho_s) \right],
\]

where \( \tau_s \) and \( F_s \) are the relaxation time and the forcing term for component \( s \), respectively. The right-hand side in (2.2) describes the relaxation towards the local equilibrium distribution

\[
f_i^{s(eq)}(\rho_s, u') = \rho_s w_i \left( 1 + \frac{3c_i \cdot u'}{c^2} + \frac{9(c_i \cdot u')^2}{2c^4} - \frac{3u' \cdot u'}{2c^2} \right), \quad u' = u + \frac{\tau_s F_s}{\rho_s},
\]

with the lattice sound speed \( c_s = c/\sqrt{3} \) and constant weights \( w_i \). These weights are expressed through velocity components \( c_i = (c_i^1, c_i^2) \) by the conditions

\[
\sum_i w_i c_i^a c_i^b = c_s^2 \delta_{ab}, \quad \sum_i w_i c_i^a c_i^b c_i^c c_i^d = c_s^4 \left( \delta_{ab}\delta_{cd} + \delta_{ad}\delta_{bc} + \delta_{ac}\delta_{bd} \right) \quad \text{for } a, b, c, d = 1, 2,
\]

where \( \delta_{ab} \) is the Kronecker delta.

The forcing terms \( F_s = F_s^{ff} + F_s^{fb} + F_s^{ex} \) contain three parts describing the fluid-fluid interaction, the fluid-boundary interaction and the external forces. The first is given by the Shan-Chen inter-molecular force as

\[
F_s^{ff}(x, t) = -G_{AB} \rho_A(x, t) \sum_i w_i \rho_s(x + c_i \Delta t, t) c_i,
\]

with \( s' = B \) and \( s = A \) or vice versa. The choice of the pseudopotential function in (2.5) is dictated by simplicity: this is the simplest choice allowing phase segregation when the two fluids interact via repulsive interactions. Of course, other choices are possible, with different impacts on the overall stability [42]. Function (2.5) describes a system without self-interaction, where the coupling constant \( G_{AB} \) controls the interaction between components \( A \) and \( B \). The interaction between fluid and boundary is given by

\[
F_s^{fb}(x, t) = -G_{sb} \rho_s(x, t) \sum_i w_i S(x + c_i \Delta t) c_i,
\]

where \( S(x) \) is the indicator equal to unity at boundary nodes and vanishing otherwise. The parameters \( G_{Ab} \) and \( G_{Bb} \) control interactions between fluid components and solid boundary; they relate to contact angles of fluids in the mixture. External forces are introduced as

\[
F_A^{ex} = -\rho_A \bar{g} e_y, \quad F_B^{ex} = \rho_B \bar{g} e_y,
\]

which yield the buoyancy forces in Boussinesq approximation, as we will see below.
Solutions of this model approximate, in the continuum limit, the coupled Navier-Stokes and Cahn–Hilliard equations \[26, 28, 43\] given by

\[
\rho \left( \frac{\partial \mathbf{u}}{\partial t} + (\mathbf{u} \cdot \nabla) \mathbf{u} \right) = -\nabla \cdot \mathbf{P} + \nabla \cdot \left[ \eta \nabla \mathbf{u} + \eta \nabla (\nabla \cdot \mathbf{u}) \right] - \phi \kappa \nabla \phi + \mathbf{f},
\]

\[
\nabla \cdot \mathbf{u} = 0,
\]

\[
\frac{\partial \phi}{\partial t} + \nabla \cdot (\phi \mathbf{u}) = \nabla \cdot [\mathbf{M} \nabla \mu]
\]

for the velocity field \( \mathbf{u}(x, t) \), the total density \( \rho(x, t) \) and the order parameter \( \phi(x, t) = \rho_A - \rho_B \).

Here \( \eta \) is dynamic viscosity, \( \mu \) is the chemical potential and \( \mathbf{M} \) is the mobility coefficient. With \( \mathbf{P} \) being the momentum-flux tensor

\[
\mathbf{P} = p_b \mathbf{I} + \mathbf{P}^K + \mathbf{K}^{(\tau)},
\]

where

\[
p_b = \frac{c_s^4 \rho + \frac{G_{AB} c_s^2}{4} (\rho^2 - \phi^2)},
\]

\[
\mathbf{P}^K = \left[ -\kappa \phi \Delta \phi - \frac{\kappa}{2} |\nabla \phi|^2 \right] \mathbf{I} + \kappa \nabla \phi \otimes \nabla \phi,
\]

\[
\mathbf{K}^{(\tau)} = \frac{c_s^4 \Delta t \rho A B}{\rho} \left( \tau - \frac{1}{2} \right) \left( \frac{\nabla P_A}{\rho_A} - \frac{\nabla P_B}{\rho_B} \right) \otimes \left( \frac{\nabla P_A}{\rho_A} - \frac{\nabla P_B}{\rho_B} \right),
\]

with the coefficient \( \kappa = \frac{c_s^4 G_{AB}}{4} \) for the Shan-Chen method. The part \( \mathbf{P}^k \) is called the Korteweg stress tensor \[41, 44, 45\], \( p_b \) denotes the pressure in the bulk regions and \( \mathbf{K}^{(\tau)} \) is an extra spurious \( \tau \)-dependent contribution, which is small for \( \tau \) close to 1/2 and for small variations of the total densities of the system. Explicit expressions for the chemical potential \( \mu \) and the mobility coefficient can be found in \[28\], such expressions are not used in this article. Notice that Equations (2.9)-(2.10) are obtained via the Chapman-Enskog expansion \[25, 26\] assuming that fields vary smoothly in time and space. In such limit the forcing implementation (2.3) introduces spurious non-Galilean invariant terms. In practice, especially when dealing with numerical simulations developing sharp gradients in space and time, hydrodynamic consistency checks are needed (see Fig. 3).

We choose \( \Delta x = \Delta t = 1 \) (considered as lattice-Boltzmann units) in the rectangular domain of horizontal size \( L_x = 10^4 \) and vertical size \( L_y = L_x/2 \). Periodic boundary conditions are assumed in the horizontal direction with the solid bottom and top boundaries. The bounce-back relation \[26, 46\] is used for the distribution function \( f_i^T(x, t) \) at the solid boundaries for modeling the no-slip condition. The relaxation time \( \tau = 0.53 \) is chosen for both components, providing the kinetic viscosity \( \nu = c_s^2 (\tau - 1/2) = 0.01 \). For small fluid velocities (small lattice Mach numbers) \( |\mathbf{u}| \ll c_s \), the flow can be assumed incompressible. We consider pure densities of both fluid components equal to 1.10 and the gravity parameter \( g = 9 \times 10^{-3} \). This gravity value is sufficient to overcome the effects of surface tension without generating significant fluctuations in total density. Since changes of the total density due to pressure variations and mixing are small, we approximate \( \rho(x, t) \approx \rho_0 \) by a constant.

The coupling constant \( G_{AB} \) has a critical value with the immiscible (two phase) flow for stronger couplings and miscible (single phase) flow for weaker couplings. For our immiscible and miscible models we select \( G_{AB} = 0.1381 \) and \( G_{AB} = 0.0805 \), respectively. In the interactions with the boundaries we use neutral wetting, i.e., \( G_{ab} = G_{bk} = 0 \), to minimize the influence of the boundaries in the simulations. In the immiscible model, two phases are separated by a diffuse interface having a width of approximately \( l_{int} \approx 3 \) grid nodes. This model approximates the Boussinesq system for the immiscible RT systems \[21\] considered at scales much larger than \( l_{int} \) with the surface tension \( \sigma = 0.0059 \) obtained from pressure measurements for large bubbles. Similarly, one recovers the miscible Boussinesq approximation for the miscible RT systems \[21\] in the continuous limit for small gradients of the order parameter. The diffusion coefficient can...
be estimated roughly as $D \simeq c_s^2 \left[ (\tau - 1/2) - \rho \tau G_{AB}/2 \right] = 0.002 \ [43, 47]$. For simulations in this paper, we initialize the flow by using an equilibrium immiscible configuration and adding a small random (white-noise) deformation to the interface with an amplitude of 4 grid points. In this equilibrium configuration, the first phase consists primarily of component $A$ with about 9% of component $B$, and vice versa for the second phase.

The simulations are implemented on GPUs of the model NVIDIA Tesla V100 PCIe 32 GB. This helps to accumulate suitable statistics with a reasonable amount of time. Specifically, we consider ensembles with at least 10 simulations. Every simulation takes around 10 hours to perform 90,000 time steps, which is enough to obtain fully developed mixing layers for miscible and immiscible RT systems. The same simulation using sequential codes in CPUs takes a few days. For further quantitative descriptions on the GPU codes in use we refer to [48, 49, 50]. In [48] some performance measurements for soft flows under periodic shear indicate a GPU/ CPU speed up ranging from 2 to 12 for grids from $128 \times 128$ to $1024 \times 1024$. A bigger difference is expected for bigger grids.

3. Results and discussion

We first develop the equation for the kinetic and potential energies of the system. Then, we study the evolution of such energies for the immiscible and miscible RT system using numerical data from the Shan-Chen multicomponent method. The results for the density and velocity fields are shown in the Figures 1 and 2 for the immiscible and miscible cases, respectively. In this figures, we can observe that after an initial linear growth the perturbations develop into nonlinear mushroom-like structures evolving further to the fully developed turbulent mixing layer. The important difference between the immiscible and miscible cases can be seen at small scales. The immiscible Rayleigh-Taylor turbulence leads to the formation of emulsion-like state with a multitude of small bubbles. The miscible Rayleigh-Taylor turbulence develops sharp gradients leading to enhanced diffusion at small scales.

We analyse the potential and kinetic energies of the RT systems defined as [1]

$$E_p = \tilde{g} \langle y \phi \rangle, \quad E_k = \left\langle \frac{\rho |u|^2}{2} \right\rangle,$$

(3.1)

where the averages are calculated in a subdomain obtained by cutting the 10 rows closest to the top and the 10 rows closest to the bottom of the original computational domain, to avoid complications with the boundaries. This means that the subdomain has the size $D = 10,000 \times 4,980$. The time derivatives and differential operators are calculated numerically by using centered finite difference schemes.

The variations of potential and kinetic energies, obtained from (2.8)–(2.10), are given by

$$\partial_t E_p = \langle u \cdot \tilde{g} e_y \rangle,$$

(3.2)

$$\partial_t E_k = - \langle u \cdot (\nabla \cdot P) \rangle + \left\langle u \cdot \left( \nabla \cdot \left( \eta \nabla u + \eta \nabla u^T \right) \right) \right\rangle - \langle u \cdot \tilde{g} e_y \rangle.$$

(3.3)

We can see three different contributions to the kinetic energy variation:

- Contribution of the momentum-flux tensor: $- \langle u \cdot (\nabla \cdot P) \rangle$.
- Contribution of the viscous term: $\left\langle u \cdot \left( \nabla \cdot \left( \eta \nabla u + \eta \nabla u^T \right) \right) \right\rangle$.
- Contribution of the buoyancy term: $\langle u \cdot \tilde{g} e_y \rangle$.
Figure 1. Mixing layer of the immiscible Rayleigh-Taylor turbulence. Upper set of pictures describes the density field, where the yellow color represents a heavier phase and the brown color corresponds to a lighter phase. The lower set of pictures describes the absolute value of velocity, with lighter colors corresponding to larger velocities. Small pictures show zooms into the small region (marked in the center of the main panel) for three different times. These times correspond to the initial linear growth, formation of nonlinear mushroom-like structures at intermediate times, and fully developed turbulent mixing at larger times. Simulations are performed on the grids $10,000 \times 5,000$ in lattice-Boltzmann units.
Figure 2. Same plots as in Fig. 1 but now for the miscible Rayleigh-Taylor turbulence.
The potential and kinetic energies are shown in Figs. 3(a, b), where we compare the averages and standard deviations using 10 simulations obtained for immiscible and miscible flows. The kinetic energy grows faster in the miscible case. In Figs. 3(c, d), we verify the balance (3.3) for immiscible and miscible systems. These graphs demonstrate a good agreement confirming that the solutions for the order parameter \( \phi \) and the velocity field \( \mathbf{u} \) obtained by the Shan-Chen multicomponent method satisfy accurately the coupled Navier-Stokes and Cahn–Hilliard system (2.8)–(2.10).

In Figs. 3(e, f) we present separately the contribution of each term in (3.4) to the kinetic energy balance. One can see that the difference between the immiscible and miscible flows in the growth of kinetic energy in Fig. 3(b) is associated mainly with the terms \( \nabla \cdot \mathbf{P} \) and \( \nabla \cdot (\eta \nabla \mathbf{u} + \eta \nabla \mathbf{u}^T) \). Here, the first term describes the contribution of the momentum flux tensor responsible for the process of the lattice-Boltzmann algorithm [25]. A significant difference between miscible and immiscible flows is related to the Korteweg stress tensor \( \mathbf{P}^K \) presented in Fig. 4(b). Below we explain that this difference represents the portion of kinetic energy which is converted into the energy of interface.

(a) Energy of the interface

In this subsection, we show that the energy flux \( \langle \nabla \cdot \mathbf{P} \cdot \mathbf{u} \rangle \) due to the Korteweg stress tensor is directly connected with the variation of the total energy of the interface defined as the product between the total length \( \mathcal{L} \) of the interface and the surface tension \( \gamma \).

Points of the moving interface \( \Gamma(t) \) for an immiscible binary mixture are commonly given by the equation \( \phi(x, t) = 0 \).

When the curvature radius is large with respect to the interface thickness, we have the following relations [38, 41, 51, 52, 53]

\[
\int_{\Omega} (\nabla \cdot \mathbf{P}^K) \cdot \mathbf{u} \, dx = -\kappa \int_{\Omega} \phi \nabla(\Delta \phi) \cdot \mathbf{u} \, dx \simeq -\kappa \int_{\Omega} |\nabla \phi|^2 K \frac{\nabla \phi}{|\nabla \phi|} \cdot \mathbf{u} \, dx \\
= -\int_{\Gamma(t)} \gamma K (\mathbf{n} \cdot \mathbf{u}) ds,
\]

where \( \mathbf{n} = \frac{\nabla \phi}{|\nabla \phi|} \) and is the normal field on \( \Gamma(t) \), \( K = -\nabla \cdot \mathbf{n} \) [54] is the scalar curvature and \( \mathbf{P}^K \) is given by (2.13). Using the total length equation described in [55], it can be shown that the left-hand-side in (3.6) can be rewritten in a such way that

\[
\langle (\nabla \cdot \mathbf{P}^K) \cdot \mathbf{u} \rangle \simeq \frac{1}{\mathcal{L}} \frac{d(\mathcal{L} \gamma)}{dt},
\]

where \( \mathcal{L} \) is the total length of the interface between two phases. This formula implies that the energy flux due to the Korteweg stress tensor (2.13) corresponds directly to the variation of the energy of the interface. We studied the flux \( \langle (\nabla \cdot \mathbf{P}^K) \cdot \mathbf{u} \rangle \) for miscible and immiscible RT flows in Figs. 4(b, d). In Fig. 4(d) we verify the relation (3.7) showing that the difference in miscible and immiscible flows is associated with the energy of the interface. The energy of the interface is calculated as the product of the surface tension \( \gamma \) and the total length of the interface \( \mathcal{L} \).
Figure 3. (a) Evolution of the potential energy $E_p$ for miscible and immiscible flows. (b) Evolution of the kinetic energy $E_k$ for miscible and immiscible flows. Verification of the kinetic energy balance for immiscible (c) and miscible (d) flows. Components of the kinetic energy variation (3.3) for immiscible (e) and miscible (f) flows. The shaded regions indicate standard deviations.

The latter is calculated by the Cauchy-Crofton formula [56, 57] with the result shown in Fig. 4(c). A small difference between the two curves in Fig. 4(d) can be attributed to the diffuse interface assumption in the lattice-Boltzmann algorithm and to high values of curvatures in the late stages of the immiscible Rayleigh-Taylor turbulence.
Figure 4. (a) Comparison between the energy flux due to the bulk pressure and spurious term. (b) Comparison between the energy flux due to the Korteweg stresses. (c) Evolution of the total length. (d) Comparison between the energy flux due to the Korteweg stresses and the right hand side of (3.7) indicated as the variation of the energy of the interface. The shaded regions indicate standard deviations.

The graphs in Fig. 4(d) mark a transition to a new regime starting at times close to $t = 30,000$, at which the variation of interface energy attains a local maximum. We argue that this transition indicates the moment when the interface becomes disconnected generating small drops and large disconnected clusters. This behavior is clearly seen in Fig. 5, where we plot the density profiles at four different times. These figures show the process of how the interface becomes disconnected after $t = 30,000$. A similar phenomenon was observed in [58] for the one-dimensional convective Cahn-Hilliard equation.

(b) Viscous dissipation and enstrophy

As follows from Figs. 3(e, f), the most significant distinction between immiscible and miscible flows is related to the viscous dissipation function $\mathbf{u} \cdot (\nabla \cdot (\eta \nabla \mathbf{u} + \eta \nabla \mathbf{u}^T))$, whose mean value appears in the kinetic energy balance (3.3). We now analyze the statistics of viscous dissipation, exploring its connection with the enstrophy of the system. The enstrophy is defined as $\Omega = \frac{1}{2} \int \omega^2 dx$, where $\omega = \nabla \times \mathbf{u}$ is a scalar vorticity of two-dimensional flow. Neglecting the density variation, we have [59]

$$
\left\langle \mathbf{u} \cdot \left( \nabla \cdot (\eta \nabla \mathbf{u} + \eta \nabla \mathbf{u}^T) \right) \right\rangle = \eta \left\langle \mathbf{u} \cdot \nabla^2 \mathbf{u} \right\rangle = -\eta \left\langle |\nabla \times \mathbf{u}|^2 \right\rangle = -\frac{2\eta}{D} \Omega.
$$

(3.8)
Figure 5. Evolution of the interface profile for times close to the local maximum for the total interface energy; see also Fig. 4(d). For time $t = 30,000$ the interface has only one component, while in the next few times the first topology changes take place leading to the first drops and large disconnected clusters.

Relation (3.8) is verified for our LB simulations in Figs. 6(a, b). These two figures also demonstrate a significant difference in the evolution of the viscous dissipation between immiscible and miscible flows.

It is apparent from Fig. 6(a), that the values of the enstrophy are considerably larger for the immiscible flow. We now argue that this difference can be attributed to the flow in a small neighborhood of the interface. Figure 6(c) shows the dissipation function for the immiscible flow; it corresponds to a small area of $667 \times 467$ lattice points marked by the rectangle in the center of Fig. 1 and amplified in its right small panel corresponding to $t = 83,000$. Visually, it is clear that a considerable part of high dissipation is concentrated near the interface. For comparison, we present the dissipation function for the miscible case in Fig. 6(d), which corresponds to a small area from Fig. 2. In the miscible case, the dissipation is more dispersed and its amplitude is roughly half (notice the difference of color scales).

Part of the dissipation may have a numerical origin coming from spurious currents of the lattice Boltzmann method. However, the experiments in [21, 51] suggest that this numerical contribution is not large enough to account for all the vorticity generated by the interface, once typical values of spurious vorticity are same order or smaller than the values of the vorticity for the miscible case [25, 51].
Figure 6. Comparison between the evolution of the total enstrophy and the evolution of the dissipation function $u \cdot (\nabla \cdot (\eta \nabla u + \eta \nabla u^T))$ for (a) immiscible and (b) miscible flows; shaded regions indicate standard deviations. Example of dissipation function for (c) immiscible and (d) miscible flows at $t = 83,000$ corresponding to the final time in Figs. 1 and 2.

4. Conclusion

We have presented a high resolution study of the developed immiscible RT turbulence in 2D using the Shan-Chen multicomponent method. Through an appropriate choice of parameters, forcing scheme and initial configuration, we developed a LB model for simulating the immiscible and miscible RT systems in Boussinesq approximation. The simulation of the Shan-Chen multicomponent method in GPUs made it possible to collect a robust set of statistics, allowing direct verifications of phenomenological predictions for the RT turbulence [21].

With the numerical results provided by the Shan-Chen model, we analyzed the energy budget of the RT turbulence. The verification of the energy balance shows the good accuracy of the solutions provided by the Shan-Chen model in solving the coupled Navier-Stokes and Cahn–Hilliard equations. In this analysis we found that the potential energy statistics are similar between immiscible and miscible flows. Significant differences were found in the statistics of kinetic energy. Analyzing the components of the kinetic energy variations, we found that the differences are associated with the momentum flux tensor and the viscous dissipation. We show that the flux due to the Korteweg stress tensor corresponds to the variation of the total length of the interface, calculated numerically by the Cauchy-Crofton formula. We show indications that the interface acts as a source of vorticity, which can explain a significant part of the difference in the viscous dissipation statistics verified between immiscible and miscible flows. The results for the miscible case are in line with the current studies about energy balance found in the scientific literature [11].
Analyzing the variation of the total interface energy, we verify the existence of a bifurcation point in the transition to turbulence. It is associated with the onset of topological changes in the interface between fluid phases. Before the critical point the interface has only one component, while after the critical point the interface is disconnected. This process is characterized by the appearance of drops and isolated clusters evolving later to the emulsion-like mixed turbulent state. Regarding future works, the extension of the numerical procedures presented in this article for the three-dimensional immiscible Rayleigh-Taylor turbulence, which is a more suitable configuration for experimental procedures, is an ongoing research. Such extension of the present GPU code can be a non-trivial task. This extension may also be achieved by using some other lattice Boltzmann methods based on phase field models or the color gradient method, as in the works [19, 20, 30, 32], where the algorithms are employed in conjunction with MRT or central moments based algorithms.

Data Accessibility. More information about the statistical analysis exposed in this article can be found in the thesis [51]. The files for the energy budget analysis and some examples of velocity and density fields used in the article can be accessed in a data set via the following link: https://doi.org/10.5061/dryad.4mw6m908p.

Authors’ Contributions. All authors contributed to the paper.

Competing Interests. The authors declare that they have no competing interests.

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