On orthogonal invariants in characteristic 2

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Abstract

Working over an algebraically closed base field \( k \) of characteristic 2, the ring of invariants \( R^G \) is studied, where \( G \) is the orthogonal group \( O(n) \) or the special orthogonal group \( SO(n) \), acting naturally on the coordinate ring \( R \) of the \( m \)-fold direct sum \( k^n \oplus \cdots \oplus k^n \) of the standard vector representation. It is proved for \( O(2) \), \( O(3) = SO(3) \), \( SO(4) \), and \( O(4) \), that there exists an \( m \)-linear invariant with \( m \) arbitrarily large, which is not expressible as a polynomial of invariants of lower degree. This is in sharp contrast with the uniform description of the ring of invariants valid in all other characteristics, and supports the conjecture that the same phenomena occur for all \( n \). For general even \( n \), new \( O(n) \)-invariants are constructed, which are not expressible as polynomials of the quadratic invariants. In contrast with these results, it is shown that rational invariants have a uniform description valid in all characteristics. Similarly, if \( m \leq n \), then \( R^{O(n)} \) is generated by the obvious invariants. For all \( n \), the algebra \( R^G \) is a finitely generated module over the subalgebra generated by the quadratic invariants, and for odd \( n \), the square of any \( SO(n) \)-invariant is a polynomial of the quadratic invariants. Finally we mention that for even \( n \), an \( n \)-linear \( SO(n) \)-invariant is given, which distinguishes between \( SO(n) \) and \( O(n) \) (just like the determinant in all characteristics different from 2).

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1 Preliminaries

1.1 The orthogonal group

Let \( k \) stand for an algebraically closed field of characteristic 2. Recall that the polar bilinear form \( \beta \) of a quadratic form \( q \) on a finite dimensional \( k \)-linear space is defined by

\[
\beta (v^{(1)}, v^{(2)}) \overset{\text{def}}{=} q(v^{(1)} + v^{(2)}) - q(v^{(1)}) - q(v^{(2)}).
\]

(1)

Note that \( \beta \) is an alternating bilinear form (which implies, but is not equivalent to, symmetry in characteristic 2). The quadratic form \( q \) is said to be non-degenerate if \( \beta(v, \cdot) = 0 \) and \( q(v) = 0 \) together imply \( v = 0 \).

Denote coordinates in \( k^n \) by \( x_1, \ldots, x_\nu, y_1, \ldots, y_\nu \) if \( n = 2\nu \) or by \( x_1, \ldots, x_\nu, y_1, \ldots, y_\nu, z \) if \( n = 2\nu + 1 \). The orthogonal group \( O(n) \) is the group of linear isomorphisms of \( k^n \) that leave the standard non-degenerate quadratic form

\[
q \overset{\text{def}}{=} x_1 y_1 + \cdots + x_\nu y_\nu \quad (n = 2\nu)
\]

resp.

\[
q \overset{\text{def}}{=} x_1 y_1 + \cdots + x_\nu y_\nu + z^2 \quad (n = 2\nu + 1)
\]

invariant. Of course they leave the polar form

\[
\beta (v^{(1)}, v^{(2)}) = x_1^{(1)} y_1^{(2)} + y_1^{(1)} x_1^{(2)} + \cdots + x_\nu^{(1)} y_\nu^{(2)} + y_\nu^{(1)} x_\nu^{(2)}
\]

(2)
of $q$ invariant as well. Note that up to base change, $q$ is the only non-degenerate quadratic form on $k^n$.

The form $\beta$ is non-degenerate if and only if $n$ is even. For $n = 2\nu + 1$,

$$\text{ker } \beta \overset{\text{def}}{=} \{ v : \beta(v, w) = 0 \text{ for all } w \}$$

is the $z$ axis.

The symplectic group $Sp(2\nu)$ is the group of linear isomorphisms of $k^{2\nu}$ that leave the standard symplectic form $\beta$ invariant. So $O(2\nu) \leq Sp(2\nu) \leq SL(2\nu)$. In fact $O(n) \leq SL(n)$ for all $n$. The algebraic group $O(n)$ is connected for odd $n$ and has two components for even $n$. For all $n$, the component containing the identity is the special orthogonal group $SO(n)$ (this can be taken as the definition of $SO(n)$). Thus, $SO(2\nu + 1) = O(2\nu + 1)$, whereas $SO(2\nu)$ is a subgroup of index 2 in $O(2\nu)$.

Call a vector $u$ non-singular if $q(u) \neq 0$. For a non-singular vector $u$, we write $T_u$ for the reflection defined by

$$T_u v \overset{\text{def}}{=} v - \frac{\beta(v, u)}{q(u)} u.$$ 

It is well known that $O(n)$ is generated by reflections, and $SO(n)$ is the set of elements that are expressible as a product of an even number of reflections.

For $n = 2\nu + 1$, each $A \in O(2\nu + 1)$ acts as the identity on the $z$ axis and acts symplectically on the factor space $k^{2\nu+1}/\text{ker } \beta$. This gives a homomorphism $\phi : O(2\nu + 1) \rightarrow Sp(2\nu)$ which is in fact an isomorphism (of groups, but not of algebraic groups). See [11] Theorem 11.9] for a proof.

### 1.2 Invariants

We write $R$ or $R_{n \times m}$ for the algebra of polynomials in the coordinates of the indeterminate $n$-dimensional vectors $v^{(1)}, \ldots, v^{(m)}$. We write $K$ or $K_{n \times m}$ for the field of rational functions. A $G$ in the superscript indicates the subalgebra (sub-field) formed by the functions invariant under the subgroup $G$ of $GL(n)$ acting on $m$-tuples of vectors in the obvious way. Let

$$Q^{(i)} \overset{\text{def}}{=} q \left(v^{(i)}\right) = \begin{cases} x_1^{(i)} y_1^{(i)} + \cdots + x_\nu^{(i)} y_\nu^{(i)} & \text{for } i = 1, \ldots, n \\ x_1^{(i)} y_1^{(i)} + \cdots + x_\nu^{(i)} y_\nu^{(i)} + z^{(i)} & \text{for } i = n+1, \ldots, 2n \end{cases}$$

$$B^{(ij)} \overset{\text{def}}{=} \beta \left(v^{(i)}, v^{(j)}\right) = x_1^{(i)} y_1^{(j)} + y_1^{(i)} x_1^{(j)} + \cdots + x_\nu^{(i)} y_\nu^{(j)} + y_\nu^{(i)} x_\nu^{(j)}.$$ 

Let

$$D^{(i_1, \ldots, i_n)} \overset{\text{def}}{=} \det \left[ v^{(i_1)}, \ldots, v^{(i_n)} \right]$$

be the determinant of the matrix that has $v^{(i_1)}, \ldots, v^{(i_n)}$ as its columns. Then $Q^{(i)}$, $B^{(ij)}$, $D^{(i_1, \ldots, i_n)}$ are multi-homogeneous elements of $R_{n \times m}^{O(n)}$.

(By the multi-degree of a monomial in the polynomial ring $R_{n \times m}$ we mean $\alpha = (\alpha^{(1)}, \ldots, \alpha^{(m)})$, where $\alpha^{(i)}$ is the total degree of the monomial in the variables belonging to $v^{(i)}$. The action of $O(n)$ preserves this multi-degree, therefore, $R_{n \times m}^{O(n)}$ is spanned by multi-homogeneous elements. A multi-homogeneous invariant of multi-degree $(1, \ldots, 1)$ will be called multi-linear.)
It is a classical fact that over a field of characteristic zero, the algebra \( R^{O(n)} \) is generated by the scalar products \( B^{ij} \) of the indeterminate vectors under consideration, and the algebra \( R^{SO(n)} \) is generated by the scalar products and the determinants. That is the so-called “first fundamental theorem” for the (special) orthogonal group; it has been discussed along with the analogous results for the other classical groups in Hermann Weyl’s work [12]. De Concini and Procesi [2] gave a characteristic free treatment to the subject, in particular, they proved that the first fundamental theorem for the (special) orthogonal group remains unchanged in odd characteristic. Concerning characteristic 2, Richman [8] proved later that the algebra \( R^G \) for the group \( G \) preserving the bilinear form \( x_1^{(1)}x_1^{(2)} + \cdots + x_n^{(1)}x_n^{(2)} \) is generated in degree 1 and 2. However, though this group preserves the quadratic form \( x_1^2 + \cdots + x_n^2 \), it is not the so-called ‘orthogonal group’ in characteristic 2: the quadratic form \( x_1^2 + \cdots + x_n^2 \) is the square of a linear form, hence is degenerate. So the question about vector invariants of the orthogonal group remains open in characteristic 2, when the behaviour of invariants turns out to be very much different, see Section 2.

2 Indecomposable invariants of high degree

The results in this section make the following conjecture plausible: for any fixed \( n \geq 2 \) (resp. \( n \geq 3 \)), there exist arbitrarily large values of \( m \) and \( m \)-linear invariants \( f_m \in R^{O(n)}_{n \times m} \) (resp. \( R^{SO(n)}_{n \times m} \)) such that \( f_m \) cannot be expressed as a polynomial in invariants of lower degree. We prove this for \( n \leq 4 \). The paper [3] contained a more sophisticated proof for the \( SO(4) \) case. It was first pointed out in this paper that special orthogonal invariants behave much different in characteristic 2.

In the general case, we have no proof of the conjecture, but in Subsection 2.4 we shall prove at least that the algebra \( R^{O(n)}_{n \times m} \) is not generated by the \( Q^{(i)} \) and \( B^{(ij)} \) if \( n \geq 2 \) and \( m \) is large enough (compared to \( n \)). This is obvious for odd \( n \), since if \( m \geq n \), then \( D^{(1-n)} \) is not expressible as a polynomial in the \( Q^{(i)} \) and \( B^{(ij)} \), but it is non-trivial for even \( n \).

2.1 The two-dimensional case

To treat the two-dimensional case, observe that the matrix

\[
A = \begin{pmatrix}
a_{11} & a_{12} \\
a_{21} & a_{22}
\end{pmatrix}
\]

is orthogonal if and only if

\[(a_{11}x + a_{12}y)(a_{21}x + a_{22}y) = xy,\]

that is, \( a_{11}a_{21} = a_{12}a_{22} = 0 \) and \( a_{11}a_{22} + a_{12}a_{21} = 1 \). So

\[O(2) = \left\{ \begin{pmatrix} a & 0 \\ 0 & 1/a \end{pmatrix} : a \in k^* \right\} \cup \left\{ \begin{pmatrix} 0 & a \\ 1/a & 0 \end{pmatrix} : a \in k^* \right\},\]

where the first of the two terms is \( SO(2) \).
Therefore, a polynomial is invariant under \( SO(2) \) if and only if all its terms have the same number of \( x \)'s and \( y \)'s. It follows that the algebra of \( SO(2) \)-invariant polynomials is generated by quadratic elements:

\[
R_2^{SO(2)} = k \left[ x^{(i)} y^{(j)} : i, j = 1, \ldots, m \right].
\]

That is not the case with \( O(2) \)-invariants. An \( SO(2) \)-invariant is \( O(2) \)-invariant exactly if it is invariant under \( \left( \begin{array}{cc} 0 & 1 \\ 1 & 0 \end{array} \right) \), that is, exactly if it is a linear combination over \( k \) of (multi-homogeneous) polynomials of the form

\[
x^{(i_1)} \cdots x^{(i_s)} y^{(j_1)} \cdots y^{(j_s)} = Q^{(i_1)} \cdots Q^{(i_s)}
\]

and

\[
x^{(i_1)} \cdots x^{(i_s)} y^{(j_1)} + y^{(i_1)} \cdots y^{(i_s)} x^{(j_1)} \cdots x^{(j_s)} \overset{\text{def}}{=} B^{(i_1, \ldots, i_s | j_1, \ldots, j_s)}.
\]

(Note that the new notation is in accordance with the notation \( B^{(ij)} \) introduced before.)

**Proposition 2.1**  
(i) Assume that the indices \( i_1, \ldots, i_s, j_1, \ldots, j_s \) are all different. Then the \( O(2) \)-invariant \( B^{(i_1, \ldots, i_s | j_1, \ldots, j_s)} \) is not expressible as a polynomial in invariants of lower degree.

(ii) Assume that each of the indices \( 1, \ldots, m \) occurs among the indices \( i_1, \ldots, i_s, j_1, \ldots, j_s \) the same number of times as it occurs among the indices \( i'_1, \ldots, i'_s, j'_1, \ldots, j'_s \). Then the multi-homogeneous \( O(2) \)-invariant \( B^{(i_1, \ldots, i_s | j_1, \ldots, j_s)} + B^{(i'_1, \ldots, i'_s | j'_1, \ldots, j'_s)} \) (if non-zero) is expressible as the product of two \( B \)'s of lower degree.

(iii) Assume that the indices \( i_1, \ldots, i_s, j_1, \ldots, j_s \) are not all different. Then the \( O(2) \)-invariant \( B^{(i_1, \ldots, i_s | j_1, \ldots, j_s)} \) is expressible as a polynomial in invariants of lower degree.

**Proof.** (i) Let \( \alpha \) denote the multi-degree of \( B^{(i_1, \ldots, i_s | j_1, \ldots, j_s)} \). So \( \alpha^{(i)} = 1 \) if \( i \) is one of the indices \( i_1, \ldots, i_s, j_1, \ldots, j_s \); and \( \alpha^{(i)} = 0 \) otherwise.

We only need to prove that \( B^{(i_1, \ldots, i_s | j_1, \ldots, j_s)} \) is not expressible as a linear combination of products with two factors each, each factor being of lower multi-degree and being either some \( B \) or some product of \( Q \)'s. Note that such a product (of two factors) is always multi-homogeneous: its multi-degree is \( \alpha \) if and only if both factors are \( B \)'s (of lower multi-degree) with no repetition of indices and with \( \{ i_1, \ldots, i_s, j_1, \ldots, j_s \} \) as the disjoint union of the two index-sets. But such a product is always the sum of two \( B \)'s of multi-degree \( \alpha \). Therefore, any linear combination of such products, when expressed as a linear combination of the \( B \)'s of multi-degree \( \alpha \), gives rise to coefficients that add up to zero. The statement follows.

(ii) The assumption can be formulated by writing \( I + J = I' + J' \) for the multi-sets \( I = \{ i_1, \ldots, i_s \}, J = \{ j_1, \ldots, j_s \}, I' = \{ i'_1, \ldots, i'_s \}, \) and \( J' = \{ j'_1, \ldots, j'_s \} \). It follows that \( I = E + G, J = F + H, I' = E + H, \) and \( J' = F + G \) with suitable multi-sets \( E, F, G, \) and \( H \). That implies \( |E| = |F|, |G| = |H|, \) and

\[
B^{(E|F)} B^{(G|H)} = B^{(E+G|F+H)} + B^{(E+H|F+G)} = B^{(I|J)} + B^{(I'|J')}.
\]

(iii) Using (ii), we may assume \( i_1 = j_1 \). Then

\[
B^{(i_1, \ldots, i_s | j_1, \ldots, j_s)} = Q^{(i_1)} B^{(i_2, \ldots, i_s | j_2, \ldots, j_s)}.
\]
The following theorem is an easy consequence.

**Theorem 2.2**  
(i) The algebra $R^{O(2)}_{2 \times m}$ is generated by the invariants
\[
Q^{(i)} \quad \text{and} \quad B^{(i_1, \ldots, i_s| j_1, \ldots, j_s)},
\]
where $1 \leq i \leq m$ and $1 \leq i_1 < \cdots < i_s < j_1 < \cdots < j_s \leq m$, respectively.

(ii) The system of generators in (i) is minimal. Indeed, any system of multi-homogeneous generators of the algebra $R^{O(2)}_{2 \times m}$ must contain the invariants $Q^{(i)}$ (possibly multiplied by non-zero constants), and must contain invariants of multi-degree $\alpha$ for all 0-1 sequences $\alpha = (\alpha^{(1)}, \ldots, \alpha^{(m)})$ that contain an even number of 1’s.

2.2 The three-dimensional case

Let us interpret $k^3$ as $\mathfrak{sl}(2)$ via
\[
v = \begin{pmatrix} x \\ y \\ z \end{pmatrix} \leftrightarrow \begin{pmatrix} z & x \\ y & z \end{pmatrix} = V.
\]
Then $q(v) = xy + z^2 = \det V$. So, for any $T \in SL(2),$ 
\[
\text{Ad } T : \mathfrak{sl}(2) \to \mathfrak{sl}(2), \quad V \mapsto TVT^{-1}
\]
is orthogonal. It is easily seen that every orthogonal transformation is of this form. So, for $i_1, \ldots, i_s \in \{1, \ldots, m\},$ the polynomial
\[
T_{r^{(i_1, \ldots, i_s)}} \overset{\text{def}}{=} \text{Tr}(V^{(i_1)} \cdots V^{(i_s)})
\]
is $O(3)$-invariant: $T_{r^{(i_1, \ldots, i_s)}} \in R^{O(3)}_{3 \times m}$.

**Proposition 2.3** If the indices $i_1, \ldots, i_s$ are all different, then $T_{r^{(i_1, \ldots, i_s)}}$ is not expressible as a polynomial in $O(3)$-invariants of lower degree.

**Proof.** We may assume $s = m$ and $i_1 = 1, \ldots, i_s = s$. We first assume that $s$ is even; say, $s = 2\sigma$.

If we replace every occurrence of all the variables $z^{(i)}$ in an $O(3)$-invariant by zero, then we get an $O(2)$-invariant, since $A \oplus 1 \in O(3)$ if $A \in O(2)$. The degree is unchanged or decreased. Therefore, it suffices to prove that the $O(2)$-invariant
\[
T_{r^{(1, \ldots, 2\sigma)}} \mid_{z=0} = \text{Tr} \left( \begin{pmatrix} 0 & x^{(1)} \\ y^{(1)} & 0 \end{pmatrix} \begin{pmatrix} 0 & x^{(2)} \\ y^{(2)} & 0 \end{pmatrix} \cdots \begin{pmatrix} 0 & x^{(2\sigma-1)} \\ y^{(2\sigma-1)} & 0 \end{pmatrix} \begin{pmatrix} 0 & x^{(2\sigma)} \\ y^{(2\sigma)} & 0 \end{pmatrix} \right) = \text{Tr} \left( \begin{pmatrix} x^{(1)} & y^{(2)} \\ y^{(1)} & x^{(2)} \end{pmatrix} \cdots \begin{pmatrix} x^{(2\sigma-1)} & y^{(2\sigma)} \\ y^{(2\sigma-1)} & x^{(2\sigma)} \end{pmatrix} \right) = B^{(1,3,\ldots, 2\sigma-1|2,4,\ldots, 2\sigma)}
\]
is not expressible as a polynomial in $O(2)$-invariants of lower degree. That was the statement of Proposition 2.1(i).
Assume now that \( s \) is odd. Assume indirectly that

\[
Tr^{(1,\ldots,s)} = \sum_j a_j b_j,
\]

where \( a_j, b_j \in R^{O(3)} \) are multi-homogeneous invariants of strictly positive degree. We may assume that \( a_j b_j \) is \( s \)-linear for all \( j \). Denote by \( \pi : R_{3\times s} \to R_{3\times (s-1)} \) the algebra homomorphism induced by the embedding \( \mathfrak{sl}(2)^{m-1} \to \mathfrak{sl}(2)^m \), \((V^{(1)}, \ldots, V^{(s-1)}) \mapsto (V^{(1)}, \ldots, V^{(s-1)}, I)\), where \( I \) stands for the identity matrix. Obviously, \( \pi \) maps a multi-homogeneous polynomial of multi-degree \((\alpha_1, \ldots, \alpha_{s-1}, \alpha_s)\) to a multi-homogeneous polynomial of multi-degree \((\alpha_1, \ldots, \alpha_{s-1})\). Since \( I \) is fixed by the \( SL(2) \)-action, we have that \( \pi(R^{O(3)}_{3\times s}) \subseteq R^{O(3)}_{3\times (s-1)} \). Applying the map \( \pi \) to (4) we get that \( Tr^{(1,\ldots,s-1)} = \sum \pi(a_j) \pi(b_j) \). The degree of \( a_j \) and \( b_j \) is at least 2 for all \( j \), hence each \( \pi(a_j) \) and each \( \pi(b_j) \) is either zero or a homogeneous \( O(3) \)-invariant of positive degree. Therefore, \( Tr^{(1,\ldots,s-1)} \) can be expressed by invariants of lower degree. But \( s - 1 \) is even, so this contradicts what we have already proven.

\[\Box\]

**Theorem 2.4** A minimal system of generators of \( R_{3\times m}^{O(3)} \) is

\[
\{Q^{(j)}, \ Tr^{(i_1,\ldots,i_s)} \mid 1 \leq j \leq m; \ 2 \leq s \leq m; \ 1 \leq i_1 < \cdots < i_s \leq m\}.
\]

**Proof.** The group \( SL(2) \) acts on \( \mathfrak{gl}(2) \), the space of \( 2 \times 2 \) matrices, by conjugation. Denote by \( \mathfrak{gl}(2)^m \) (resp. \( \mathfrak{sl}(2)^m \)) the \( m \)-fold direct sum of copies of \( \mathfrak{gl}(2) \) (resp. \( \mathfrak{sl}(2) \)), endowed with the diagonal \( SL(2) \)-action. Denote by \( P \) the coordinate ring of \( \mathfrak{gl}(2)^m \), and recall that \( R \) is the coordinate ring of \( \mathfrak{sl}(2)^m \). Restriction of functions from \( \mathfrak{gl}(2)^m \) to \( \mathfrak{sl}(2)^m \) induces a surjective algebra homomorphism \( \varphi : P \to R \). Clearly we have \( \varphi(P^{SL(2)}) \subseteq R^{O(3)} \). Now \((\mathfrak{gl}(2)^m, \mathfrak{sl}(2)^m)\) is a good pair of \( SL(2) \)-varieties in the sense of [4]. This follows for example from [4] Proposition 1.3b], since \( \mathfrak{sl}(2)^m \) is an \( m \)-codimensional linear subspace in the good variety \( \mathfrak{gl}(2)^m \), defined as the zero locus of \( m \) linear \( SL(2) \)-invariants on \( \mathfrak{gl}(2)^m \), hence \( \mathfrak{sl}(2)^m \) is a good complete intersection in \( \mathfrak{gl}(2)^m \). As a consequence of general properties of modules with good filtrations (cf. [4]) we get that the restriction of \( \varphi \) to the ring of invariants \( P^{SL(2)} \) is surjective onto \( R^{O(3)} \). In particular, a generating system of \( P^{SL(2)} \) is mapped to a generating system of \( R^{O(3)} \). Using the result of [5], a minimal system of generators of \( P^{SL(2)} \) was determined in [4]. This is mapped by \( \varphi \) to the generating system of \( R^{O(3)} \) stated in our theorem. So the only thing left to show is that the above generating system is minimal. Since it consists of multi-homogeneous elements with pairwise different multi-degree, it is sufficient to prove that none of them can be expressed by invariants of strictly lower degree. This is clear for \( Q^{(j)} \), and this is the content of Proposition 2.3 for \( Tr^{(i_1,\ldots,i_s)} \). \[\Box\]

**2.3 The four-dimensional case**

To treat the four-dimensional case, we interpret \( k^4 \) as \( \mathfrak{gl}(2) \) via

\[
v = \begin{pmatrix} x_1 \\ x_2 \\ y_1 \\ y_2 \end{pmatrix} \leftrightarrow \begin{pmatrix} x_1 & x_2 \\ y_1 & y_2 \end{pmatrix} = V.
\]
Then \( q(v) = x_1 y_1 + x_2 y_2 = \det V \). So, for any \( S, T \in SL(2) \), the transformation
\[
\mathfrak{gl}(2) \to \mathfrak{gl}(2), \quad V \mapsto SVT^{-1}
\]
is orthogonal. We get a homomorphism \( \varphi : SL(2) \times SL(2) \to O(4) \) which is easily seen to be injective; its image is a six-dimensional irreducible subgroup of \( O(4) \), so it must be \( SO(4) \). This interpretation of \( SO(4) \) was used in [3] to show that the algebra \( R_{4 \times m}^{SO(4)} \) is not generated by its elements of degree \(< m – 1 \). A simpler proof can be given by means of the following construction.

Let \( i_1, \ldots, i_s; j_1, \ldots, j_s \in \{1 \ldots m\} \). The determinant
\[
\begin{vmatrix}
V^{(i_1)} & V^{(j_1)} & V^{(j_2)} & \cdots & V^{(j_{s-1})} & V^{(j_s)} \\
V^{(i_2)} & \cdots & \cdots & \cdots & \cdots & \cdots \\
\vdots & \cdots & \cdots & \cdots & \cdots & \cdots \\
V^{(i_s)} & \cdots & \cdots & \cdots & \cdots & \cdots \\
\end{vmatrix}
\]
is \( SO(4) \)-invariant. Assume that the indices \( i_1, \ldots, i_s; j_1, \ldots, j_s \) are all different. The 2s-linear component of the above determinant is also invariant, denote it by
\[
F = F^{(i_1, \ldots, i_s | j_1 \ldots j_s)} \in R_{4 \times m}^{SO(4)}.
\]

**Proposition 2.5** If the indices \( i_1, \ldots, i_s; j_1, \ldots, j_s \in \{1, \ldots, m\} \) are all different, then \( F^{(i_1, \ldots, i_s | j_1 \ldots j_s)} \) is not expressible as a polynomial in \( SO(4) \)-invariants of lower degree.

**Proof.** If we replace every occurrence of all the variables \( x_2^{(i)} \) and \( y_2^{(i)} \) in an \( SO(4) \)-invariant by zero, then we get an \( O(2) \)-invariant, since if \( A \in O(2) \) then \( A \oplus \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \) and \( A \oplus \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \) are both in \( O(4) \) (where \( A \) acts on the \( x_1, y_1 \) coordinate plane) and one of them must be in \( SO(4) \). The degree is unchanged or decreased. Therefore, it suffices to prove that the \( O(2) \)-invariant
\[
F^{(i_1, \ldots, i_s | j_1 \ldots j_s)} \bigg|_{x_2=y_2=0}
\]
is not expressible as a polynomial in \( O(2) \)-invariants of degree \(< 2s \). That is the 2s-linear component of the determinant
\[
\begin{vmatrix}
x^{(i_1)} & x^{(j_1)} & y^{(i_1)} & y^{(j_1)} & x^{(j_2)} & y^{(i_2)} & y^{(j_2)} & \cdots & \cdots & x^{(i_s)} & x^{(j_s)} & y^{(i_s)} & y^{(j_s)} \\
x^{(i_2)} & \cdots & \cdots & \cdots & \cdots & \cdots & \cdots & \cdots & \cdots & \cdots & \cdots & \cdots \\\n\vdots & \cdots & \cdots & \cdots & \cdots & \cdots & \cdots & \cdots & \cdots & \cdots & \cdots & \cdots \\\nx^{(i_s)} & \cdots & \cdots & \cdots & \cdots & \cdots & \cdots & \cdots & \cdots & \cdots & \cdots & \cdots \\\ny^{(j_1)} & \cdots & \cdots & \cdots & \cdots & \cdots & \cdots & \cdots & \cdots & \cdots & \cdots & \cdots \\\ny^{(j_2)} & \cdots & \cdots & \cdots & \cdots & \cdots & \cdots & \cdots & \cdots & \cdots & \cdots & \cdots \\\n\vdots & \cdots & \cdots & \cdots & \cdots & \cdots & \cdots & \cdots & \cdots & \cdots & \cdots & \cdots \\
y^{(j_s)} & \cdots & \cdots & \cdots & \cdots & \cdots & \cdots & \cdots & \cdots & \cdots & \cdots & \cdots \\
\end{vmatrix}
\]
which is nothing but \( B^{(i_1, \ldots, i_s | j_1 \ldots j_s)} \). The statement follows from Proposition 2.1(i). □
Corollary 2.6 Any system of multi-homogeneous generators of the algebra $R_{4 \times m}^{SO(4)}$ must contain the invariants $Q^{(i)}$ (possibly multiplied by non-zero constants), and must contain invariants of multi-degree $\alpha$ for all 0-1 sequences $\alpha = (\alpha^{(1)}, \ldots, \alpha^{(m)})$ that contain an even number of 1’s.

To treat the full orthogonal group $O(4)$, consider the sum

$$G = G^{(i_1, \ldots, i_s | j_1, \ldots, j_s)} = F^{(i_1, \ldots, i_s | j_1, \ldots, j_s)} + \sigma F^{(i_1, \ldots, i_s | j_1, \ldots, j_s)},$$

where $\sigma$ represents the coset $O(4) \setminus SO(4)$. Obviously, $G$ is invariant under $O(4)$.

Proposition 2.7 If the indices $i_1, \ldots, i_s; j_1, \ldots, j_s \in \{1, \ldots, m\}$ are all different, then $G^{(i_1, \ldots, i_s | j_1, \ldots, j_s)}$ is not expressible as a polynomial in $O(4)$-invariants of degree less than $2s - 2$.

Proof. The substitution

$$x_2^{(i_t)} = y_2^{(i_t)} = 0 \quad (t = 1, \ldots, s),$$

$$x_2^{(j_t)} = y_2^{(j_t)} = 0 \quad (t = 1, \ldots, s - 2),$$

$$V^{(j_{s-1})} = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}, \quad V^{(j_s)} = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$$

turns any $O(4)$-invariant into an $O(2)$-invariant, since we may embed $O(2)$ into $O(4)$ by identifying $A \in O(2)$ with $A \oplus \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \in O(4)$ (where $A$ acts on the $x_1, y_1$ coordinate plane), and the subspace of $k^{4 \times m}$ defined by the above equations is stable under $O(2)$. The degree is unchanged or decreased. Therefore, it suffices to prove that the $O(2)$-invariant that $G$ turns into is not expressible as a polynomial in $O(2)$-invariants of degree $< 2s - 2$. Now $F$ turns into the $(2s - 2)$-linear component of the determinant

$$\begin{vmatrix} x^{(i_1)} & \cdots & y^{(i_1)} & \cdots \\ x^{(i_2)} & \cdots & y^{(i_2)} & \cdots \\ \vdots & \ddots & \vdots & \vdots \\ x^{(i_{s-1})} & \cdots & y^{(i_{s-1})} & 1 \\ 0 & 1 & 0 & y^{(i_s)} \\ 0 & 0 & y^{(i_s)} & x^{(i_s)} \end{vmatrix},$$

which is nothing but $x^{(i_1)}x^{(i_2)} \cdots x^{(i_{s-1})}y^{(i_s)}y^{(j_1)} \cdots y^{(j_{s-2})}$. Since the representative $\sigma : x_1 \leftrightarrow y_1$ of $O(4) \setminus SO(4)$ commutes with the substitution under consideration, $\sigma F$ is turned into $y^{(i_1)}y^{(i_2)} \cdots y^{(i_{s-1})}x^{(i_s)}x^{(j_1)} \cdots x^{(j_{s-2})}$ and therefore $G$ is turned into $B^{(i_1, i_2, \ldots, i_{s-1} | j_1, j_2, \ldots, j_{s-2})}$. The statement follows from Proposition 2.1(i). \qed
2.4 The even-dimensional case

We turn to the even-dimensional case in general. To a monomial depending on the vectors $v^{(1)}, \ldots, v^{(m)}$ in a multi-linear fashion we shall associate the $2 \times \nu$ matrix

$$
\begin{pmatrix}
\sigma_1 & \cdots & \sigma_\nu \\
\tau_1 & \cdots & \tau_\nu
\end{pmatrix}
$$

called the type of the monomial, whose entry $\sigma_t$ is the number of occurrences of $x_t$ as a factor of the monomial, and $\tau_t$ is the number of occurrences of $y_t$. So

$$m = \sigma_1 + \tau_1 + \cdots + \sigma_\nu + \tau_\nu.$$

Lemma 2.8 Denote by $p$ the sum of all monomials that depend on the two-dimensional vectors $v^{(1)}, \ldots, v^{(6)}$ in a sextilinear fashion and have type $\begin{pmatrix} 3 \\ 3 \end{pmatrix}$. Then $p$ is a unimodular invariant: $p \in R_{2 \times 6}^{SL(2)}$.

Proof. Invariance under

$$
\begin{pmatrix}
c & 1 \\
1/c & c
\end{pmatrix}
(c \in k^*)
$$

is obvious as all terms in $p$ are invariant. It suffices to check invariance under

$$
A_c = \begin{pmatrix} 1 & c \\ c & 1 \end{pmatrix}
$$

and

$$
A_c^T = \begin{pmatrix} 1 & c \\ c & 1 \end{pmatrix}
$$

($c \in k$).

By symmetry, it is sufficient to deal with $A_c$. The transformed polynomial

$$
p_c(v^{(1)}, \ldots, v^{(6)}) = p(A_cv^{(1)}, \ldots, A_cv^{(6)})
$$

is a linear combination of sextilinear monomials whose type $\begin{pmatrix} \sigma \\ \tau \end{pmatrix}$ (where $\sigma + \tau = 6$) satisfies the inequality $\sigma \leq 3 \leq \tau$. The coefficient of such a monomial is $c^{\sigma-3}\binom{\tau}{3}$. That is 1 if $\tau = 3$ and zero otherwise. So $p_c = p$. \qed

Let $m \geq 2(3\nu - 1)$, and denote by $f \in R_{2\nu \times 2(3
\nu - 1)} \leq R_{2\nu \times m}$ the sum of all monomials that depend in a multi-linear fashion on the first $2(3\nu - 1)$ indeterminate vectors (and do not involve the rest), and the two rows of whose type coincide, each row being a permutation of $(2, 3, 3, \ldots, 3)$ (one 2 and $(\nu - 1)$ 3’s).

Theorem 2.9 (i) The polynomial $f$ is an orthogonal invariant.

(ii) The polynomial $f$ is not expressible as a polynomial in the $Q^{(i)}$ and $B^{(ij)}$.

Proof. (i) Let $A^{-T}$ denote the inverse transpose of the matrix $A$. It suffices to check invariance under the subgroup formed by transformations of the form

$$
\hat{A} = \begin{pmatrix} A & A^{-T} \\ A^{-T} & A \end{pmatrix}
$$

($A \in GL(\nu)$)
and under the reflection $x_1 \leftrightarrow y_1$, as these generate $O(2\nu)$. (This follows easily from the fact that $O(2\nu)$ is generated by reflections. Indeed, $x_1 \leftrightarrow y_1$ can be turned into an arbitrary reflection via conjugation by some $\hat{A}$, since $\{\hat{A} \mid A \in GL(\nu)\}$ acts transitively on $\{v \in k^n \mid q(v) = 1\}$.)

Invariance under $x_1 \leftrightarrow y_1$ is obvious as the terms in $f$ simply undergo a permutation (of order 2). Now look at $\hat{A}$. We may restrict $A$ to a system of generators of $GL(\nu)$.

Invariance under

$$\hat{A}_{i,c} : x_i \mapsto cx_i, \quad y_i \mapsto c^{-1}y_i \quad (i \in \{1, \ldots, m\}, \ c \in k^*)$$

is obvious as each term in $f$ is invariant.

By symmetry, it suffices to check invariance under

$$\hat{A}_c : x_1 \mapsto x_1 + cx_2, \quad y_2 \mapsto cy_1 + y_2 \quad (c \in k).$$

To this end, write $f$ as $f = g + h$ where $g$ is the sum of those terms in $f$ that have only 3’s in the first two columns of their types, and $h$ is the sum of the other terms.

We use the above lemma to prove that $g$ is in fact invariant not just under $\hat{A}_c$, but under both of the transformations $x_1 \mapsto x_1 + cx_2$ and $y_2 \mapsto cy_1 + y_2$. By symmetry, it is sufficient to deal with $x_1 \mapsto x_1 + cx_2$. Let us break $g$ up into sub-sums in the following way. Two terms shall be in the same sub-sum if and only if the six vector variables whose $x_1$ or $x_2$ coordinate is involved are the same for the two terms, and each of the other $2(3\nu - 1) - 6$ vector variables involved is involved in the two terms via the same coordinate. Each sub-sum will then consist of $\binom{6}{3}$ terms whose sum is invariant under $x_1 \mapsto x_1 + cx_2$ by the above lemma.

We are left with the task of proving that $h$ is invariant under $\hat{A}_c$. To this end, let us break $h$ up into sub-sums in the following way. Two terms shall be in the same sub-sum if and only if the ten vector variables whose $x_1, x_2, y_1$ or $y_2$ coordinate is involved are the same for the two terms, and each of the other $2(3\nu - 1) - 10$ vector variables involved is involved in the two terms via the same coordinate. Each sub-sum will then consist of $2^{10}\binom{5}{2}$ terms whose sum is invariant under $\hat{A}_c$, as we shall now check. In other words, we have to check that the sum $r$ of all monomials that depend in a decilinear fashion on the four-dimensional vectors $v^{(1)}, \ldots, v^{(10)}$ and have type $\binom{2}{2} \binom{3}{3}$ or $\binom{3}{3} \binom{2}{2}$ is invariant under $\hat{A}_c$. The transformed polynomial

$$r_c (v^{(1)}, \ldots, v^{(10)}) = r \left( \hat{A}_c v^{(1)}, \ldots, \hat{A}_c v^{(10)} \right)$$

is a linear combination of decilinear monomials whose type $\left( \begin{array}{cc} \sigma_1 & \sigma_2 \\ \tau_1 & \tau_2 \end{array} \right)$ satisfies $\sigma_1 + \sigma_2 = \tau_1 + \tau_2 = 5$. The coefficient of such a monomial is

$$c^{\sigma_2 - 3 + \tau_1 - 2} \binom{\sigma_2}{3} \binom{\tau_1}{2} + c^{\tau_1 - 3 + \sigma_2 - 2} \binom{\tau_1}{3} \binom{\sigma_2}{2} = c^{\sigma_2 + \tau_1 - 5} \left( \binom{\sigma_2}{3} \binom{\tau_1}{2} + \binom{\tau_1}{3} \binom{\sigma_2}{2} \right).$$

That is 1 if $\{\tau_1, \sigma_2\} = \{2, 3\}$ and zero otherwise. So $r_c = r$. 

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(ii) Since \( f \) is multi-linear, the only way for the proposition to be false would be if \( f \) were a polynomial in the \( B^{(ij)} \). So it suffices to show that \( f \) is not a symplectic invariant. We show that it is not invariant under the symplectic transformation

\[ T : x_1 \mapsto x_1 + y_1. \]

Write \( f \) as \( f = \tilde{g} + \tilde{h} \) where \( \tilde{g} \) is the sum of those terms in \( f \) that have three \( x_1 \)'s and three \( y_1 \)'s among their factors, and \( \tilde{h} \) is the sum of those that have two \( x_1 \)'s and two \( y_1 \)'s. Lemma 2.8 tells us that \( \tilde{g} \) is invariant under \( T \). On the other hand, we show that \( \tilde{h} \) is not. It suffices to show that the sum of all monomials that depend on the two-dimensional vectors \( v^{(1)}, \ldots, v^{(4)} \) in a quadrilinear fashion and have type \( \binom{2}{2} \) is not invariant. That is clear since the coefficient of the monomial \( x^{(1)} y^{(2)} y^{(3)} y^{(4)} \) will be \( 1 + 1 + 1 = 3 \) after applying \( T \).

\[ \square \]

Remark 2.10 Replacing the pair \((3, 2)\) in the construction of \( f \) by \((2^t - 1, 2^t - 2)\), where \( t \) is an arbitrary natural number, we get a multi-linear orthogonal invariant in \( 2((2^t - 1)\nu - 1) \) vector variables. For \( t > 1 \), the resulting invariant is not a polynomial of the quadratic invariants.

### 3 Two remarks

#### 3.1 On the odd-dimensional case

As a contrast to the previous section, we prove the following theorem. It is a consequence of the first fundamental theorem for the symplectic group \( Sp(2\nu) \), which holds in its usual form in any characteristic (including 2), as was proved in [2, Section 6]. Using our notation, the first fundamental theorem for the symplectic group in characteristic 2 says that the algebra \( R^{Sp(2\nu)}_{2\nu \times \nu} \) is generated by the \( B^{(ij)} \).

**Theorem 3.1** The invariant \( f \in R^{O(2\nu+1)}_{(2\nu+1)\times \nu} \) is expressible as a polynomial in the \( Q^{(i)} \) and \( B^{(ij)} \) if and only if the variables \( z^{(1)}, \ldots, z^{(m)} \) occur in \( f \) only with even exponents.

For example, if \( f \) is the square of a (polynomial) invariant, then \( f \) is expressible as a polynomial in the \( Q^{(i)} \) and \( B^{(ij)} \).

**Proof.** “Only if” is trivial; we prove “if”. The proof relies on the relationship between \( O(2\nu + 1) \) and \( Sp(2\nu) \) that was described in Subsection 2.2 the subalgebra of \( R \) generated by the \( x \) and \( y \) variables is stable with respect to the action of \( O(2\nu + 1) \), and this action can be identified with the natural action of \( Sp(2\nu) \) on \( R_{(2\nu)\times \nu} \).

Assume hypothesis. View \( f \) as a polynomial in the variables \( z^{(i)} \), and consider a term

\[ \left(z^{(1)}\right)^{2\alpha_1} \cdots \left(z^{(m)}\right)^{2\alpha_m} p \left(x_1^{(1)}, \ldots, x_\nu^{(1)}, y_1^{(1)}, \ldots, y_\nu^{(1)}, \ldots, x_1^{(m)}, \ldots, x_\nu^{(m)}, y_1^{(m)}, \ldots, y_\nu^{(m)}\right) \]

of highest degree in \( f \). Then \( p \) must be invariant under \( Sp(2\nu) \), and the first fundamental theorem for the symplectic group [2] says that \( p \) must be expressible as a polynomial in the \( B^{(ij)} \).
Replace $f$ by the polynomial
$$f_1 = f - Q^{(1)} \alpha_1 \cdots Q^{(m)} \alpha_m p.$$ If $f_1$ is expressible in the desired form, then so is $f$. Of course, $f_1$ is again $O(2\nu + 1)$-invariant, the $z^{(i)}$ occur with even exponents only, and a highest-degree term of $f$ has disappeared. The new terms in $f_1$ are of lower degree. Iterating this procedure, we arrive at the polynomial 0 after a finite number of steps. □

3.2 $SO(2\nu)$ versus $O(2\nu)$

Concerning the even-dimensional case, it is not completely trivial that $R_{2\nu \times m}^{SO(2\nu)} \neq R_{2\nu \times m}^{O(2\nu)}$ ($m \geq 2\nu$). An easy proof is possible using a general theorem of Rosenlicht [9, Theorem 2] and the fact that $SO(2\nu)$ is a perfect group (i.e., is generated by commutators of its elements). We now give an explicit construction of a $2\nu$-linear polynomial in $R_{2\nu \times 2\nu}$ that is invariant under $SO(2\nu)$ but not under $O(2\nu)$ – just like the determinant in any characteristic different from 2.

We write $SO(2\nu, \mathbb{C})$ for the special orthogonal group defined over the complex field by the quadratic form $q = x_1 y_1 + \cdots + x_{\nu} y_{\nu}$. (We continue to write $SO(2\nu)$ for the group defined over the field $k$ of characteristic 2.) The polar form $\beta$ of $q$ is given by the same formulas (1) and (2) of Subsection 1.1 as over the field $k$.

Lemma 3.2 If the polynomial $f$ in the coordinates of the indeterminate $2\nu$-dimensional vectors $v^{(1)}, \ldots, v^{(m)}$ has integer coefficients and is invariant under $SO(2\nu, \mathbb{C})$, then – when viewed as a polynomial over $k$ – it is invariant under $SO(2\nu)$.

An analogous statement and proof holds for the groups $O(n, \mathbb{C})$ and $O(n)$ instead of $SO(2\nu, \mathbb{C})$ and $SO(2\nu)$.

Proof. For a vector $u \in \mathbb{C}^{2\nu}$ or $u \in k^{2\nu}$, $q(u) \neq 0$, we write $T_u$ for the reflection in the hyperplane orthogonal to $u$:
$$T_u v^{\text{def}} = v - \frac{\beta(v, u)}{q(u)} u.$$ Being invariant under $SO(2\nu, \mathbb{C})$ or $SO(2\nu)$ means being invariant under the product of any two reflections:
$$f(T_u T_w v^{(1)}, \ldots, T_u T_w v^{(m)}) = f(v^{(1)}, \ldots, v^{(m)})$$ for $u, w \in \mathbb{C}^{2\nu}$ or $u, w \in k^{2\nu}$, $q(u)q(w) \neq 0$. Coefficients of both sides may be viewed as rational functions with coefficients in $\mathbb{Z}$ or $\mathbb{Z}/(2)$ of the vector variables $u$ and $w$, and $SO$-invariance of $f$ boils down to formal equality of pairs of such rational functions. Since formal equality over $\mathbb{Z}$ implies that over $\mathbb{Z}/(2)$, the lemma is proved. □

We shall use the symbol $*$ to mean any one of the two letters $x$ and $y$. 13
Proposition 3.3 Consider the $2\nu$-linear polynomial
\[ \sum B^{(i_1 i_2)} B^{(i_3 i_4)} \ldots B^{(i_{2\nu-1} i_{2\nu})} \]
with integer coefficients, where the $B$’s are defined by (3) over \( \mathbb{Z} \), and the sum is extended over those permutations $i_1, \ldots, i_{2\nu}$ of the indices $1, \ldots, 2\nu$ that satisfy $i_1 < i_2$, $i_3 < i_4$, $\ldots$, $i_{2\nu-1} < i_{2\nu}$ and $i_1 < i_3 < \cdots < i_{2\nu-1}$. The coefficient of the monomial $*^{(1)}_{j_1} \cdots *^{(2\nu)}_{j_{2\nu}}$ is 1 if $j_1, \ldots, j_{2\nu}$ is a permutation of $x_1, \ldots, x_{\nu}, y_1, \ldots, y_{\nu}$ and is even otherwise.

Proof. The product
\[ B^{(i_1 i_2)} B^{(i_3 i_4)} \ldots B^{(i_{2\nu-1} i_{2\nu})} \]
is the sum of those monomials $*^{(1)}_{j_1} \cdots *^{(2\nu)}_{j_{2\nu}}$ that satisfy $j_1 = j_{i_2}$, $j_3 = j_{i_4}$, $\ldots$, $j_{i_{2\nu-1}} = j_{i_{2\nu}}$ and have an $x$ and a $y$ corresponding to each of these pairs of indices. So the sum we are looking at is a linear combination of those $2\nu$-linear monomials that have the same number – say, $\tau_t$ – of $x_i$’s and $y_i$’s among their factors, for each value of $t$. The coefficient of such a monomial is $\tau_1! \cdots \tau_{\nu}!$, since a monomial occurs as many times as its factors can be grouped into pairs of the form \( \{x_t, y_t\} \). That coefficient is 1 if $\tau_1 = \cdots = \tau_{\nu} = 1$ and even otherwise. \( \square \)

Subtract the determinant $D^{(1 \ldots (2\nu))}$ from the above sum (considering both to be defined over \( \mathbb{Z} \)). The result is a polynomial with even coefficients, denote it by $2\Delta$.

Theorem 3.4 The polynomial $\Delta$, viewed as a polynomial over $k$, is invariant under $SO(2\nu)$ but not under $O(2\nu)$.

Proof. Invariance under $SO(2\nu)$ follows from Lemma 3.2 as $\Delta$ is invariant under $SO(2\nu, \mathbb{C})$.

Let $*^{(1)}_{j_1} \cdots *^{(2\nu)}_{j_{2\nu}}$ be a permutation of $x_1, \ldots, x_{\nu}, y_1, \ldots, y_{\nu}$. By Proposition 3.3, the coefficient of the monomial $*^{(1)}_{j_1} \cdots *^{(2\nu)}_{j_{2\nu}}$ in the polynomial $\Delta$ is 0 if the permutation is even and is 1 if it is odd. It follows that $\Delta$ is not invariant under the reflection $x_1 \leftrightarrow y_1$ (not even if viewed over $k$), since this transforms the monomials corresponding to odd permutations into those corresponding to even ones. \( \square \)

4 Separation of orbits

The results in this section are analogous to those for characteristic different from 2. The proofs use Witt’s theorem [11, Theorem 7.4], standard facts concerning reductive groups, and basic algebraic geometry.

Let us introduce the notation
\[ A = A_{n \times m} = k \left[ Q^{(i)}, B^{(ij)} : 1 \leq i \leq m, 1 \leq i < j \leq m \right]. \]

Note that we have shown in Subsection 2.4 that $A \neq R^{O(n)}$ for even $n$ and large $m$. The same is obvious for odd $n$ and $m \geq n$ as $D^{(1 \ldots n)} \in R^{O(n)} \setminus A$. 

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4.1 The null-cone

Recall that the null-cone corresponding to a graded algebra of polynomials is defined to be the locus of common zeros of its homogeneous elements of positive degree.

**Theorem 4.1** The null-cones corresponding to the three algebras

\[ R^{SO(n)}_{n \times m} \geq R^{O(n)}_{n \times m} \geq A_{n \times m} \]

are the same.

**Proof.** Suppose that the point \( (v^{(1)}, \ldots, v^{(m)}) \) belongs to the null-cone of \( A \); that is, the vectors \( v^{(1)}, \ldots, v^{(m)} \) satisfy the equations \( Q^{(i)} = 0 \) and \( B^{(ij)} = 0 \). The subspace they span is then totally singular (i.e., has \( q \equiv 0 \)). Let \( W \) be a maximal totally singular subspace containing them. It follows from Witt’s theorem that the dimension of \( W \) is \( \nu = \left\lfloor \frac{n}{2} \right\rfloor \), and that there exists a maximal totally singular subspace \( W_1 \) such that

\[ k^n = W \oplus W_1 \oplus \ker \beta. \]

For \( 0 \neq t \in k \), let \( A_t \in O(n) \) stand for the special orthogonal transformation that multiplies vectors in \( W \) by \( t \), vectors in \( W_1 \) by \( 1/t \), and vectors in \( \ker \beta \) by 1. Any \( f \in R^{SO(n)}_{n \times m} \) is invariant under \( A_t \), so

\[ f\left(tv^{(1)}, \ldots, tv^{(m)}\right) = f\left(v^{(1)}, \ldots, v^{(m)}\right). \]

This holds for arbitrary \( t \neq 0 \), so it must also hold for \( t = 0 \). This means that the point \( (v^{(1)}, \ldots, v^{(m)}) \) is contained in the null-cone of \( R^{SO(n)} \). \( \square \)

**Corollary 4.2** The algebras \( R^{O(n)} \) and \( R^{SO(n)} \) are finitely generated as \( A \)-modules.

**Proof.** Let \( G \) stand for \( O(n) \) or \( SO(n) \). Then \( G \) is a reductive algebraic group, so Nagata’s theorem [7, Theorem 3.4] says that \( R^G \) is finitely generated as an algebra.

Consider a homogeneous element \( h \in R^G \). By Theorem 4.1 and Nullstellensatz, \( h \) has a power in the ideal of \( R \) generated by the \( Q^{(i)} \) and the \( B^{(ij)} \). It follows by [7, Lemma 3.4.2] that \( h \) has a power in the ideal of \( R^G \) generated by the \( Q^{(i)} \) and the \( B^{(ij)} \).

Applying that to each element \( h \) of a finite system of homogeneous generators of the algebra \( R^G \) shows that the ideal of \( R^G \) generated by the \( Q^{(i)} \) and the \( B^{(ij)} \) contains all elements of \( R^G \) that are homogeneous of high enough degree. So \( R^G \), as an \( A \)-module, is generated by elements of degree lower than some number \( d \). These form a finite-dimensional vector space, so a finite number of them will suffice. \( \square \)

4.2 Algebro-geometric lemmas

We recall some well-known facts from algebraic geometry. The word ‘variety’ below stands for an irreducible affine algebraic variety over \( k \) (the characteristic of \( k \) is 2 in our applications, but the following general statements are valid if \( k \) is an arbitrary algebraically closed field). Write \( K[X] \) for the algebra of polynomial functions on \( X \), and write \( K(X) \)
for the field of rational functions on $X$. Let $f : X \to Y$ be a dominant morphism of varieties. Then the comorphism $f^*$ identifies $K(Y)$ with the subfield $f^*K(Y)$ of $K(X)$. The morphism $f$ is said to be separable, if $K(X) \geq f^*K(Y)$ is a separable field extension. We need the following criterion for separability, see for example [1, (17.3) Theorem]: The morphism $f$ is separable if and only if there is a non-singular point $x$ on $X$ such that $f(x)$ is non-singular in $Y$, and the differential $d_xf : T_x X \to T_{f(x)} Y$ at $x$ is surjective.

Lemma 4.3 Let $f : X \to Y$ be a dominant, separable morphism of varieties. Suppose that $h$ is a rational function on $X$, such that for some non-empty Zariski open subset $U$ of $X$, the restriction $h|_U$ is constant along the fibers of $f|_U$. Then $h$ is the pull-back of a rational function on $Y$, that is, $h \in f^*K(Y)$.

Proof. Take a principal affine open subset $V$ in $X$, where $h|_V$ is regular, and $h|_V$ is constant along the fibers of $f|_V$. Then $h$ is purely inseparable over $f^*K(Y)$ by [1, (18.2) Proposition, p.78]; that is, $h^p$ is contained in $f^*K(Y)$ for some natural number $s$. Thus $h$ itself is contained in $f^*K(Y)$, because $f$ is separable by our assumption. □

More can be said when $Y$ is normal. See for example [1, (18.3), p.79]:

Lemma 4.4 Let $f : X \to Y$ be a surjective morphism of varieties, and assume that $Y$ is normal. Suppose that $h$ is a polynomial function on $X$, such that $h$ is the pull-back of a rational function on $Y$, i.e. $h$ is contained in $f^*K(Y)$. Then $h$ is the pull-back of a polynomial function on $Y$, that is, $h \in f^*K[Y]$.

Proof. See for example [1 (18.3), p.79], and note that since we are dealing with affine varieties, ‘regular functions’ in the sense of [1] (i.e. everywhere defined rational functions) are the same as ‘polynomial functions’. □

4.3 Rational invariants

We now look at the field $K^{O(n)}$, which is much easier to deal with than the algebra $R^{O(n)}$. Note that $K^{O(n)}$ is the fraction field of $R^{O(n)}$ (this follows easily from the fact that $SO(n)$ is perfect).

Theorem 4.5 (i) The field $K^{O(2\nu)}_{2\nu \times m}$ is generated by the algebraically independent invariants

$$Q^{(i)} \quad (1 \leq i \leq \min(m, 2\nu))$$

and

$$B^{(ij)} \quad (1 \leq i < j \leq m, \ i \leq 2\nu).$$

(ii) For $m < 2\nu$ we have $K^{SO(2\nu)}_{2\nu \times m} = K^{O(2\nu)}_{2\nu \times m}$. For $m \geq 2\nu$, the field $K^{SO(2\nu)}_{2\nu \times m}$ is a quadratic extension of $K^{O(2\nu)}_{2\nu \times m}$, generated for example by the invariant $\Delta$ constructed in Theorem 3.4.
(iii) The field $K_{O(2ν+1) \times m}$ is generated by the algebraically independent invariants

$$Q^{(i)} \quad (1 \leq i \leq \min(m, 2ν)),$$

$$B^{(ij)} \quad (1 \leq i < j \leq m, \quad i \leq 2ν),$$

and

$$D^{(1, \ldots, 2ν, l)} \quad (2ν + 1 \leq l \leq m).$$

The description in (ii) of $K_{O(2ν) \times 2ν \times m}$ for $m \geq 2ν$ will be made complete in Theorem 4.14 where we determine the quadratic polynomial over $K_{O(2ν) \times 2ν \times m}$ that $Δ$ satisfies.

Note that the theorem is valid in any characteristic. In any characteristic different from 2, the third statement remains valid if $SO(2ν + 1)$ is replaced by $O(2ν + 1)$ and $D^{(1, \ldots, 2ν, l)}$ is replaced by $B^{(2ν+1|l)}$. The proof given below, appropriately modified, goes through.

The proof is via the following propositions.

**Proposition 4.6** Let $m$ be any positive integer, and let $(β^{(ij)})$ be any alternating $m \times m$ matrix of rank $r \leq n$. Then there exist vectors $u^{(1)}, \ldots, u^{(m)} \in k^n$ with

$$β(u^{(i)}, u^{(j)}) = β^{(ij)} \quad (i, j = 1, \ldots, m).$$

**Proof.** It is well known that $(β^{(ij)})$ is cogredient to $J \oplus 0 = \begin{pmatrix} 0 & I \\ I & 0 \end{pmatrix} \oplus 0$ with $J$ of size $r \times r$ (so $r$ is always even). The proposition obviously holds for the latter matrix, and the general case follows by base change. □

**Proposition 4.7** Let $m \leq n$. Let $(β^{(ij)})$ be any $m \times m$ alternating matrix, and let $q^{(1)}, \ldots, q^{(m)} \in k$. Then there exist vectors $v^{(1)}, \ldots, v^{(m)} \in k^n$ with

$$β(v^{(i)}, v^{(j)}) = β^{(ij)} \quad (i, j = 1, \ldots, m)$$

and

$$q(v^{(i)}) = q^{(i)} \quad (i = 1, \ldots, m).$$

**Proof.** As always, we set $ν = \lceil n/2 \rceil$. Choose vectors $u^{(1)}, \ldots, u^{(m)} \in k^{2ν}$ as in the previous proposition.

Consider $n = 2ν + 1$ first. Note that the standard quadratic form $q$ is onto $k$ on any line parallel to ker $β$ (the $z$-axis). Therefore, there exist vectors $v^{(i)} \in k^{2ν+1}$ that are mapped to the $u^{(i)}$ by the projection

$$k^{2ν+1} \to k^{2ν+1}/\ker β = k^{2ν}$$

and have $q(v^{(i)}) = q^{(i)}$.

Now let $n = 2ν$. First suppose that $m = n$ and $u^{(1)}, \ldots, u^{(m)}$ is a basis of $k^n$. Define a new quadratic form $q^*$ by the formula

$$q^*(\sum_{i=1}^{m} λ_i u^{(i)}) = \sum_{i=1}^{m} λ_i^2 q^{(i)} + \sum_{1 \leq i < j \leq m} λ_i λ_j β^{(ij)}. $$
Let $\beta^*$ stand for the polar form of $q^*$. Then

$$\beta^*(u^{(i)}, u^{(j)}) = q^*(u^{(i)} + u^{(j)}) - q^*(u^{(i)}) - q^*(u^{(j)}) = \beta(u^{(i)}, u^{(j)})$$

therefore, $\beta^* \equiv \beta$. It follows that $q^*$ is non-degenerate. Since $k$ is algebraically closed, all non-degenerate quadratic forms are equivalent. So there is a linear isomorphism $A : k^n \to k^n$ such that $q(Au) = q^*(u)$ for all $u \in k^n$. It of course follows that

$$\beta(Au', Au'') = \beta^*(u', u'') = \beta(u', u'')$$

for all $u', u'' \in k^n$ (that is, $A \in Sp(n)$). Define $v^{(i)} = Au^{(i)}$ ($i = 1, \ldots, m$). Then

$$\beta(v^{(i)}, v^{(j)}) = \beta(u^{(i)}, u^{(j)}) = \beta^{(ij)}$$

and

$$q(v^{(i)}) = q^*(u^{(i)}) = q^{(i)},$$

i. e., $v^{(1)}, \ldots, v^{(m)}$ have the desired properties.

Suppose finally that $n = 2\nu$ but $u^{(1)}, \ldots, u^{(m)}$ do not span $k^n$. Choose some vector $0 \neq u^{(0)} \in \langle u^{(1)}, \ldots, u^{(m)} \rangle^\perp$. Choose a linear function $f : k^n \to k$ with $f(u^{(0)}) \neq 0$. Define the new quadratic form $q^*$ by the formula

$$q^* = q + \lambda f^2,$$

with some $\lambda \in k$ that gives $q^*(u^{(0)}) \neq 0$. The quadratic form $f^2$ has 0 as its polar form, so $q^*$ has $\beta$. It follows that $q^*$ is non-degenerate. We therefore have a linear isomorphism $A : k^n \to k^n$ such that $q(Au) = q^*(u)$ for all $u \in k^n$. Of course $A \in Sp(n)$. The vectors $Au^{(i)}$ have

$$\beta(Au^{(i)}, Au^{(j)}) = \beta(u^{(i)}, u^{(j)}) = \beta^{(ij)}.$$ 

Note also that $Au^{(0)} \in \langle Au^{(1)}, \ldots, Au^{(m)} \rangle^\perp$ and $q(Au^{(0)}) \neq 0$. The latter ensures that $q$ is onto $k$ on any line parallel to $kAu^{(0)}$. So there are vectors $v^{(i)} \in Au^{(i)} + kAu^{(0)}$ with $q(v^{(i)}) = q^{(i)}$. They have all desired properties. \hfill \Box

We shall need the following consequence of Witt’s theorem.

**Proposition 4.8** (i) For $n = 2\nu$ and arbitrary $m$, there exists a non-empty open set $U \subset k^{n \times m}$ with the following property: if

$$\left( v^{(1)}', \ldots, v^{(m)}' \right) \in U \text{ and } \left( v^{(1)}'', \ldots, v^{(m)}'' \right) \in U$$

satisfy

$$Q^{(i)'} = Q^{(i)''} \quad (1 \leq i \leq 2\nu),$$

$$B^{(ij)'} = B^{(ij)''} \quad (1 \leq i < j \leq m, \quad i \leq 2\nu),$$

then there is an orthogonal transformation $A$ such that $Av^{(i)'} = v^{(i)''}$ for every $1 \leq i \leq m$. 

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(ii) When \( m < n = 2\nu \), the assertion (i) holds with \( A \) taken from the special orthogonal group \( \text{SO}(2\nu) \).

(iii) For \( n = 2\nu + 1 \) and arbitrary \( m \), there exists a non-empty open set \( U \subset k^{n \times m} \) with the following property: if

\[
\left( v^{(1)}', \ldots, v^{(m)'} \right) \in U \text{ and } \left( v^{(1)}'', \ldots, v^{(m)''} \right) \in U
\]

satisfy

\[
Q^{(i)'} = Q^{(i)''} \quad (1 \leq i \leq 2\nu),
B^{(ij)'} = B^{(ij)''} \quad (1 \leq i < j \leq m, \ i \leq 2\nu),
D^{(1,\ldots,2\nu,l)'} = D^{(1,\ldots,2\nu,l)''} \quad (2\nu + 1 \leq l \leq m),
\]

then there is an orthogonal transformation \( A \) such that \( Av^{(i)'} = v^{(i)''} \) for every \( 1 \leq i \leq m \).

Proof. For (i) and (iii), an \( m \)-tuple of vectors shall be contained in \( U \) exactly if the images of the first \( \min(m, 2\nu) \) vectors are linearly independent in \( k^{n} \setminus \ker \beta \). Those first \( \min(m, 2\nu) \) vectors will always span a subspace \( W \) with \( W \cap \ker \beta = 0 \). If

\[
\left( v^{(1)}', \ldots, v^{(m)'} \right) \in U \text{ and } \left( v^{(1)}'', \ldots, v^{(m)''} \right) \in U
\]

satisfy the conditions stated in the proposition, then Witt’s theorem provides \( A \in O(n) \) with

\[
Av^{(i)'} = v^{(i)''} \quad (i = 1, \ldots, \min(m, 2\nu)).
\]

If \( m > 2\nu \), we need to show that this equality also holds for \( 2\nu < i \leq m \).

(i) As \( \beta \) is non-degenerate and \( v^{(1)''}, \ldots, v^{(2\nu)''} \) is a basis of \( k^{2\nu} \), it suffices to show that

\[
\beta \left( v^{(i)''}, Av^{(j)'} \right) = \beta \left( v^{(i)''}, v^{(j)''} \right)
\]

for \( 1 \leq j \leq m \) and \( 1 \leq i \leq 2\nu \). This is equivalent to

\[
\beta \left( Av^{(i)'}, Av^{(j)'} \right) = \beta \left( v^{(i)''}, v^{(j)''} \right),
\]

which follows from the orthogonality of \( A \).

(iii) Equality (5) is proved as above, and shows that \( Av^{(j)'} \) and \( v^{(j)''} \) can differ only in their \( z \) coordinates. Equality of the \( z \) coordinates will follow from

\[
\det \left[ v^{(1)''}, \ldots, v^{(2\nu)''}, Av^{(j)'} \right] = \det \left[ v^{(1)''}, \ldots, v^{(2\nu)''}, v^{(j)''} \right], \tag{6}
\]

since expanding both determinants by the last column gives the same terms except for the term containing the \( z \) coordinate of the last vector with the same non-vanishing \( 2\nu \times 2\nu \) minor as its coefficient on both sides.
Equality (6) is equivalent to
\[
\det \left[ Av^{(1)}', \ldots, Av^{(2\nu)}', Av^{(j)}' \right] = \det \left[ v^{(1)}', \ldots, v^{(2\nu)}', v^{(j)}' \right],
\]
which follows from orthogonality of \( A \).

(ii) We impose an additional condition on points of \( U \): the orthogonal subspace to the subspace spanned by the components of an \( m \)-tuple \((m < 2\nu)\) in \( U \) should contain a non-singular vector. It is easy to see that \( U \) still contains a non-empty Zariski open subset in \( k^{2\nu \times m} \). Indeed, when \( m = 2\nu - 1 \), the orthogonal subspace to the subspace spanned by the linearly independent components of an \( m \)-tuple \( v \in k^{2\nu \times m} \) is spanned by a vector whose coordinates are \( m \times m \) minors of \( v \), therefore the condition that this vector is non-singular is expressed as the non-vanishing of a polynomial function on \( k^{2\nu \times m} \). \( U \) is clearly non-empty; for example, a basis of the subspace orthogonal to some non-singular vector is contained in \( U \). To handle the case \( m < 2\nu - 1 \) as well, note that the image of a non-empty Zariski open subset of \( k^{2\nu \times (2\nu-1)} \) under the projection map onto \( k^{2\nu \times m} \) contains a non-empty open subset of \( k^{2\nu \times m} \).

Now take from \( U \) the \( m \)-tuples \( v', v'' \) satisfying the conditions stated in the proposition. By Witt’s theorem we have \( A \in O(2\nu) \) with \( Av' = v'' \). There is a non-singular vector \( u \) orthogonal to the subspace spanned by the components of \( v' \). The reflection \( T_u \) fixes \( v' \). So both \( A \) and \( AT_u \) map \( v' \) to \( v'' \), and one of them is contained in \( SO(2\nu) \).

Proof of Theorem 4.5

(i) and (iii): Write \( f \) for the regular map defined on \( k^{n \times m} \) that has the invariants in the theorem as its coordinates. For \( m \leq 2\nu \), Proposition 4.7 shows that \( f \) is surjective. If \( m \geq 2\nu \), \( f \) is still dominant, for if we prescribe values \( q^{(i)} \), \( \beta^{(ij)} \) and (in the odd-dimensional case) \( d^{(1, \ldots, 2\nu)} \) with \( \det (\beta^{(ij)})^{2\nu}_{i,j=1} \neq 0 \), then the vectors \( v^{(1)} \), \( \ldots, v^{(2\nu)} \) provided by Proposition 4.7 will give a basis in \( k^n / \ker \beta = k^{2\nu} \), and this ensures the existence of \( v^{(2\nu+1)} \), \( \ldots, v^{(m)} \) such that the coordinates of \( f \) take the prescribed values on the \( m \)-tuple \( v^{(1)}, \ldots, v^{(m)} \). This proves algebraic independence of the invariants in the theorem.

We now show that \( f \) is separable. Consider the point \((e^{(1)}, \ldots, e^{(m)})\) in \( k^{n \times m} \) given by the first \( \min(m, 2\nu) \) vectors of the standard basis of \( k^n \) and \( m - \min(m, 2\nu) \) zero vectors. We claim that the differential of \( f \) at this point is onto. The partial derivatives are as follows.
\[
\frac{\partial Q^{(i)}}{\partial x^{(i)}_t} = y^{(i)}_t, \quad \frac{\partial Q^{(i)}}{\partial y^{(i)}_t} = x^{(i)}_t, \tag{7}
\]
all other partials of \( Q^{(i)} \) being zero. So the \( n \times m \) matrix formed by the partials of \( Q^{(i)} \) has \( e^{(i)} \) with \( x \) and \( y \) coordinates interchanged as its \( i \)th column, all other columns being zero. Also,
\[
\frac{\partial B^{(ij)}}{\partial x^{(i)}_t} = y^{(j)}_t, \quad \frac{\partial B^{(ij)}}{\partial y^{(i)}_t} = x^{(j)}_t, \quad \frac{\partial B^{(ij)}}{\partial x^{(j)}_t} = y^{(i)}_t, \quad \frac{\partial B^{(ij)}}{\partial y^{(j)}_t} = x^{(i)}_t, \tag{8}
\]
all other partials of \( B^{(ij)} \) being zero. So the \( n \times m \) matrix formed by the partials of \( B^{(ij)} \) has \( e^{(i)} \) with \( x \) and \( y \) coordinates interchanged as its \( j \)th column and has \( e^{(j)} \) with \( x \) and
y coordinates interchanged as its ith column, all other columns being zero. We easily see that all these n × m matrices are linearly independent. Our claim follows in the even-dimensional case; in the odd-dimensional case we observe that these (2ν + 1) × m matrices have nothing but zeros in their last lines, so it suffices to prove that the last lines of the (2ν + 1) × m matrices formed by the partials of the D^{(1,...,2ν,l)} are linearly independent. This is obvious, since

\[ \frac{\partial D^{(1,...,2ν,l)}}{\partial z^{(l')}} = δ^{(l)}_{(l')} \]

for 2ν + 1 ≤ l, l' ≤ m.

Now let h ∈ K^{O(n)}_{n×m} (considered as a function on k^{n×m}). Then h is constant along the orbits of O(n), so Proposition 4.8 shows that h is constant along the fibers of f (at least on some non-empty open set). By Lemma 4.3, h is the pull-back of a rational function.

(ii) When m < 2ν, the same argument as above works: h ∈ K^{SO(2ν)}_{2ν×m} is constant along the fibers of f defined above by Proposition 4.8 (ii), so by Lemma 4.3, h is a rational function in the Q(i), B^{(ij)}.

For the case m ≥ 2ν, note that K^{O(2ν)} is the fixed point set of the two-element group O(2ν)/SO(2ν) acting on K^{SO(2ν)}, hence the degree of the field extension K^{SO(2ν)} | K^{O(2ν)} is 1 or 2. By Theorem 3.4, it must be a quadratic extension generated by ∆.

4.4 The case m ≤ n

The results of this section show that the conjectured exotic orthogonal invariants can appear only if the number of vector variables is sufficiently large, namely, if m > n.

Theorem 4.9 Let n = 2ν or n = 2ν + 1, and let m ≤ 2ν. Then the algebra R^{O(n)}_{n×m} is generated by the \( \binom{m+1}{n} \) algebraically independent invariants Q^{(i)} and B^{(ij)}. When m < 2ν = n, we have R^{SO(2ν)}_{2ν×m} = R^{O(2ν)}_{2ν×m}.

Proof. Let f : k^{n×m} → k^{\binom{m+1}{n}} stand for the regular map that has the Q^{(i)} and B^{(ij)} as its coordinates. Choose any h ∈ R^{O(n)}_{n×m} (or h ∈ R^{SO(2ν)}_{2ν×m} when m < 2ν). Theorem 4.3 says that h is the pull-back of a rational function. But h is a polynomial, and Proposition 4.7 says that f is surjective. By Lemma 4.4, h is the pull-back of a polynomial function. □

Theorem 4.10 Let m = n = 2ν + 1. Let D stand for D^{(1-n)}. Then the algebra R^{O(n)}_{n×m} is generated by the \( \binom{n+1}{2} + 1 \) invariants Q^{(i)}, B^{(ij)} and D, the ideal of algebraic relations between whom is generated by the single element G defined as

\[
G = D^2 - \frac{1}{2} \begin{vmatrix} 2Q^{(1)} & B^{(12)} & \cdots & B^{(1n)} \\ B^{(21)} & 2Q^{(2)} & \cdots & B^{(2n)} \\ \vdots & \vdots & \ddots & \vdots \\ B^{(n1)} & B^{(n2)} & \cdots & 2Q^{(n)} \end{vmatrix}.
\]

(See Proposition 4.11 for the meaning of 1/2 here.)
We break the proof up into several propositions.

**Proposition 4.11** The determinant in the definition of $G$, when interpreted as a polynomial over $\mathbb{Z}$ in the variables $Q^{(i)}$ and $B^{(ij)}$, has even coefficients. So $G$ is defined as a polynomial over $\mathbb{Z}$ and a fortiori over $k$.

*Proof.* Each expansion term in the determinant either has a factor from the diagonal and therefore has an even coefficient, or is a product of off-diagonal entries and can be paired with the transposed term (note that $B^{(ij)} = B^{(ji)}$).

**Proposition 4.12** The polynomials $Q^{(i)}$, $B^{(ij)}$ and $D$ satisfy the relation

$$(-1)^\nu D^2 - \frac{1}{2} \begin{vmatrix} 2Q^{(1)} & B^{(12)} & \cdots & B^{(1n)} \\ B^{(21)} & 2Q^{(2)} & \cdots & B^{(2n)} \\ \vdots & \vdots & \ddots & \vdots \\ B^{(n1)} & B^{(n2)} & \cdots & 2Q^{(n)} \end{vmatrix} = 0$$

over $\mathbb{Z}$ and a fortiori over $k$.

*Proof.* Working over $\mathbb{Q}$, the matrix of the polar form $\beta$ of the quadratic form

$$q = x_1 y_1 + \cdots + x_\nu y_\nu + z^2$$

is

$$M = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \oplus \cdots \oplus \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \oplus (2).$$

For arbitrary $V \in \mathbb{Q}^{n \times n}$ with $i$th column $v^{(i)}$, we have

$$V^T M V = (\beta (v^{(i)}, v^{(j)}))_{i,j=1}^n.$$

Taking determinants gives

$$(-1)^\nu \cdot 2 \cdot (\det V)^2 = \det (\beta (v^{(i)}, v^{(j)}))_{i,j=1}^n.$$

The proposition follows, since $\beta (v^{(i)}, v^{(i)}) = 2q (v^{(i)})$.

The following proposition deals with the hypersurface $\{ G = 0 \}$ in the affine space $k^{(n+1)}$, with coordinates denoted by $Q^{(i)}$, $B^{(ij)}$, $D$ ($1 \leq i \leq n$, $1 \leq j < l \leq n$).

**Proposition 4.13** The hypersurface $\{ G = 0 \}$ in $k^{(n+1)}$ is normal.

*Proof.* A hypersurface $H$ (the zero locus of a single polynomial in an affine space) is normal if and only if the set of singular points has codimension $\geq 2$ in $H$; this follows for example from Seidenberg’s criterion for normality [10, Theorem 3], together with Macaulay’s unmixedness theorem (cf. [6, Theorem 17.6]).

Write $G$ as

$$G = D^2 - (Q^{(1)} F^{(1)} + \cdots + Q^{(n)} F^{(n)} + F^{(0)}),$$

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where $F^{(i)}$ is the $i$th principal $(n - 1) \times (n - 1)$ minor of the matrix

$$
\begin{pmatrix}
2Q^{(1)} & B^{(12)} & \cdots & B^{(1n)} \\
B^{(21)} & 2Q^{(2)} & \cdots & B^{(2n)} \\
\vdots & \vdots & \ddots & \vdots \\
B^{(n1)} & B^{(n2)} & \cdots & 2Q^{(n)}
\end{pmatrix},
$$

and $F^{(0)}$ is the sum of those terms in the determinant of this matrix that have no factor from the diagonal, and have at least $\nu + 1$ factors from above the diagonal.

In particular,

$$\frac{\partial G}{\partial Q^{(i)}} = F^{(i)} \quad (i = 1, \ldots, n).$$

We claim that the locus of common zeros of $G$, $F^{(1)}$ and $F^{(n)}$ is of codimension 3 in $k^{(n+1)+1}$. Equivalently, the locus of common zeros of $F^{(1)}$ and $F^{(n)}$ is of codimension 2 in the hyperplane $\{D = 0\}$. (To see the equivalence note that projection from the direction of the $D$ coordinate axis onto the coordinate hyperplane $\{D = 0\}$ maps the hypersurface $\{G = 0\}$ bijectively onto the hyperplane $\{D = 0\}$.) The polynomials $F^{(1)}$ and $F^{(n)}$ depend only on the variables $B^{(ij)}$, and their vanishing on a common hypersurface in the affine space $\{D = 0\}$ would mean having the defining polynomial of that hypersurface as a common factor. Therefore it suffices to show that $F^{(1)}$ and $F^{(n)}$ have no common factors as polynomials in the $B^{(ij)}$. To this end, we impose the order

$$B^{(12)} > B^{(23)} > \cdots > B^{(n-2|n-1)} > B^{(n-1|n)} >$$

$$> B^{(13)} > \cdots > B^{(n-3|n-1)} > B^{(n-2|n)} >$$

$$> \cdots >$$

$$> B^{(1|n-1)} > B^{(2|n)} >$$

$$> B^{(1|n)}$$

on the variables and the corresponding lexicographic order on the monomials. Then the leading monomial of $F^{(1)}$ is $(B^{(23)} B^{(45)} \cdots B^{(n-1|n)})^2$, and the leading monomial of $F^{(n)}$ is $(B^{(12)} B^{(34)} \cdots B^{(n-2|n-1)})^2$. The leading monomials have no common factors, hence $F^{(1)}$ and $F^{(n)}$ have no common factors. So the locus of common zeros of $G$, $F^{(1)}$ and $F^{(n)}$ is of codimension 3. The singular locus of $\{G = 0\}$ is contained in that locus, so it has codimension $\geq 2$ in $\{G = 0\}$, which is therefore normal. \qed

**Proof of Theorem 4.10** Consider the map

$$f : k^{nxn} \to k^{(n+1)+1}$$

that has the $Q^{(i)}$, the $B^{(ij)}$, and $D$ as its coordinates. It follows from Propositions 4.12 and 4.14 that the image of $f$ is the hypersurface $\{G = 0\}$ (we need that the characteristic is 2, so the values of the $Q^{(i)}$ and the $B^{(ij)}$ determine the value of $D$ on $\{G = 0\}$).

Choose any $h \in R^{O(n)}_{nxn}$. Theorem 4.15 says that $h$ is the pull-back of a rational function on $\{G = 0\}$. But $h$ is a polynomial, so, by Lemma 4.14 and Proposition 4.13, $h$ is the
pull-back of a polynomial.

We now turn to the description of the algebra of special orthogonal invariants in the case \( m = n = 2\nu \). We shall write \( \sum B B \cdots B \) for the \( 2\nu \)-linear \( O(2\nu, \mathbb{C}) \)-invariant
\[
\sum B^{(i_1 i_2)} B^{(i_3 i_4)} \cdots B^{(i_{2\nu-1} i_{2\nu})}
\]
defined over \( \mathbb{Z} \) that was proved in Proposition 3.3 to agree with \( D = D^{(1 \cdots (2\nu))} \) modulo 2.

**Theorem 4.14** Let \( m = n = 2\nu \). Let \( \Delta \) stand for the \( SO(2\nu) \)-invariant constructed in Theorem 3.4. Then the algebra \( R_{SSO(n)} \) is generated by the \((\nu+1) + 1\) invariants \( Q^{(i)}, B^{(ij)} \) and \( \Delta \), the ideal of algebraic relations between whom is generated by the single element \( \Gamma \) defined as

\[
\Gamma = \Delta^2 - \Delta \sum B B \cdots B + \frac{1}{4} \begin{pmatrix}
2Q^{(1)} & B^{(12)} & \cdots & B^{(1n)} \\
B^{(21)} & 2Q^{(2)} & \cdots & B^{(2n)} \\
\vdots & \vdots & \ddots & \vdots \\
B^{(n1)} & B^{(n2)} & \cdots & 2Q^{(n)}
\end{pmatrix}.
\]

(See the proof for the meaning of 1/4 here.)

**Proof.** The proof is rather similar to that of Theorem 4.10. Write \( L \) for the expression
\[
\left( \sum B B \cdots B \right)^2 - (-1)^\nu
\]
so \( L \) is a polynomial of \( Q^{(i)}, B^{(ij)} \) with integral coefficients.

First interpret \( Q^{(i)}, B^{(ij)}, \Delta \) as polynomials over \( \mathbb{Z} \) in the \( x, y \) variables. Recall that \( \Delta \) was defined over \( \mathbb{Z} \) by
\[
\Delta = \frac{1}{2} \left( \sum B B \cdots B - D \right),
\]
where \( D = D^{(1 \cdots (2\nu))} \). Set
\[
\bar{\Delta} = \frac{1}{2} \left( \sum B B \cdots B + D \right).
\]
It is a polynomial with integral coefficients in the \( x, y \) variables by Proposition 3.3 hence so is
\[
\Delta \bar{\Delta} = \frac{1}{4} \left( \left( \sum B B \cdots B \right)^2 - D^2 \right) = \frac{1}{4} L
\]
(the second equality is proved in the same manner as Proposition 4.12). Note that \( \Delta + \bar{\Delta} = \sum B B \cdots B \). It follows that \( Q^{(i)}, B^{(ij)}, \Delta \) (considered as polynomials over \( \mathbb{Z} \) in the \( x, y \) variables) satisfy the relation
\[
\Delta^2 - \Delta \sum B B \cdots B + L/4 = 0.
\]
We claim that the coefficients of \( L \) are divisible by four, so \( L/4 \) is a polynomial in the variables \( Q^{(i)}, B^{(ij)} \) with integer coefficients. Indeed, multiply the relation \( \Delta \Delta = L/4 \) by 4 and consider it modulo 2: the left hand side becomes zero, so we obtain on the right hand side an algebraic relation over \( k \) holding between \( Q^{(i)}, B^{(ij)} \) (defined over \( k \)). But \( Q^{(i)}, B^{(ij)} \) are algebraically independent in \( R_{n \times m}^{SO(n)} \) by Theorem 4.5, so this relation must be trivial. This means that all coefficients of \( L \) (as a polynomial in the \( Q^{(i)}, B^{(ij)} \)) are even. Taking now the relation \( 2\Delta \Delta = L/2 \) modulo 2 and repeating the same argument we obtain our claim. So \( \mathfrak{M} \) is an algebraic relation with integral coefficients holding between \( Q^{(i)}, B^{(ij)}, \Delta \) (considered as polynomials over \( \mathbb{Z} \) in the \( x, y \) variables).

It follows immediately that \( \mathfrak{M} \) makes sense and holds as a relation over \( k \); that is, the relation \( \Gamma = 0 \) makes sense and holds in \( R_{n \times m}^{SO(n)} \).

Consider now the map
\[
f : k^{n \times n} \to k^{(n+1)/2 + 1}
\]
that has the \( Q^{(i)} \), the \( B^{(ij)} \), and \( \Delta \) as its coordinates. It follows from the relation \( \Gamma = 0 \) and Proposition 4.7 that the image of \( f \) is the hypersurface \( \{ \Gamma = 0 \} \) in \( k^{(n+1)/2 + 1} \). (For surjectivity, we also need that the coset \( O(2\nu) \setminus SO(2\nu) \) interchanges \( \Delta \) and \( \bar{\Delta} \), so a point \( (Q, B, \Delta) \) is in the image of \( f \) if and only if \( (Q, B, \bar{\Delta}) \) is in the image of \( f \).) Choose any \( h \in R_{n \times m}^{SO(n)} \). Theorem 4.5 says that \( h \) is the pull-back of a rational function on the hypersurface \( \{ \Gamma = 0 \} \). But \( h \) is a polynomial, so, by Lemma 4.4 and Proposition 4.15 below, \( h \) is the pull-back of a polynomial. \( \square \)

**Proposition 4.15** Consider the affine space \( k^{(n+1)/2 + 1} \), with coordinates denoted by \( Q^{(i)}, B^{(ij)}, \Delta \) \((1 \leq i \leq n, 1 \leq j \leq l \leq n)\). Then the hypersurface \( \{ \Gamma = 0 \} \) in \( k^{(n+1)/2 + 1} \) is normal.

**Proof.** Just as in Proposition 4.13, it suffices to prove that the singular locus has codimension \( \geq 2 \) in the hypersurface.

Calculate
\[
\frac{\partial \Gamma}{\partial \Delta} = \sum B B \cdots B
\]
and
\[
\frac{\partial \Gamma}{\partial Q^{(n)}} = \frac{1}{2} \begin{vmatrix}
2Q^{(1)} & B^{(12)} & \cdots & B^{(1[n-1])} \\
B^{(21)} & 2Q^{(2)} & \cdots & B^{(2[n-1])} \\
\vdots & \vdots & \ddots & \vdots \\
B^{(n-1[1])} & B^{(n-1[2])} & \cdots & 2Q^{(n-1)}
\end{vmatrix} = Q^{(1)}F^{(1)} + \cdots + Q^{(n-1)}F^{(n-1)} + F^{(0)},
\]
where \( F^{(i)} \) is the \( i \)th principal \((n-2) \times (n-2)\) minor of the last determinant for \( i = 1, \ldots, n-1 \), and \( F^{(0)} \) also depends only on the \( B^{(ij)} \).

We claim that the locus of common zeros of \( \Gamma, \partial \Gamma/\partial \Delta \) and \( \partial \Gamma/\partial Q^{(n)} \) is of codimension 3 in \( k^{(n+1)/2 + 1} \). Equivalently, the locus of common zeros of \( \partial \Gamma/\partial \Delta \) and \( \partial \Gamma/\partial Q^{(n)} \) is of codimension 2 in the hyperplane \( \{ \Delta = 0 \} \). It suffices to show that \( \partial \Gamma/\partial \Delta \) and \( \partial \Gamma/\partial Q^{(n)} \) have no common factors as polynomials in the \( Q^{(i)} \) and the \( B^{(ij)} \). As \( \partial \Gamma/\partial \Delta \) depends only on the \( B^{(ij)} \), so will any common factor, but then, in order to divide \( \partial \Gamma/\partial Q^{(n)} \), it must divide each \( F^{(i)} \). But we have shown in the proof of Proposition 4.13 that \( F^{(1)} \) and \( F^{(n-1)} \)}
(there denoted by $F^{(1)}$ and $F^{(n)}$ since $n$ there was odd and the $F$’s were $(n - 1) \times (n - 1)$ minors of an $n \times n$ matrix) have no common factors. So the locus of common zeros of $\Gamma$, $\partial \Gamma / \partial \Delta$ and $\partial \Gamma / \partial Q^{(n)}$ is of codimension 3. The singular locus of $\{ \Gamma = 0 \}$ is contained in that locus, so it has codimension $\geq 2$ in $\{ \Gamma = 0 \}$, which therefore is normal. □

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