A GENERALIZATION OF THE LOMNITZ LOGARITHM CREEP LAW VIA HADAMARD FRACTIONAL CALCULUS

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Abstract. We present a new approach based on linear integro-differential operators with logarithmic kernel related to the Hadamard fractional calculus in order to generalize, by a parameter $\nu \in (0, 1]$, the logarithmic creep law known in rheology as Lomnitz law (obtained for $\nu = 1$). We derive the constitutive stress-strain relation of this generalized model in a form that couples memory effects and time-varying viscosity. Then, based on the hereditary theory of linear viscoelasticity, we also derive the corresponding relaxation function by solving numerically a Volterra integral equation of the second kind. So doing we provide a full characterization of the new model both in creep and in relaxation representation, where the slow varying functions of logarithmic type play a fundamental role as required in processes of ultra slow kinetics.

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1. Introduction

In 1956 Lomnitz \cite{Lomnitz1956} introduced a logarithmic creep law to treat the creep behaviour of igneous rocks. The original Lomnitz creep law provides the strain response $\epsilon(t)$ to a constant stress $\sigma(t) = \sigma_0$ for $t \geq 0$ in the form

\begin{equation}
\epsilon(t) = \sigma_0 \frac{E_0}{E_0} \left[1 + q \ln(1 + t/\tau_0)\right], \quad t \geq 0,
\end{equation}

where $E_0$ is the shear modulus, $\tau_0 > 0$ is a characteristic time during which the transition from elastic to creep-type deformation occurs and $q$ is a positive non-dimensional constant. The logarithmic creep law suggested by Lomnitz on the basis of an empirical reasoning has found many applications in other papers of the same author \cite{Lomnitz1957, Lomnitz1958}.

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In 1958 Jeffreys [11] proposed a power law of creep, generalizing the Lomnitz logarithmic law to broaden the geophysical applications to fluid-like materials including igneous rocks. This generalized law, however, can be applied also to solid-like viscoelastic materials as shown in a revisited version in 1984 by Strick [35]. More recently, in 2012 Mainardi and Spada [23] have provided a full characterization of the rheological properties related to this general model thus including the original Lomnitz creep law.

We recall that in the linear theory of viscoelasticity, based on the hereditary theory by Volterra, a viscoelastic body is characterized by two distinct but interrelated material functions, causal in time (i.e. vanishing for $t < 0$): the creep compliance $J(t)$ (the strain response to a unit step of stress) and the relaxation modulus $G(t)$ (the stress response to a unit step of strain). For more details see e.g. the treatises by Christensen [5], Pipkin [28] and Mainardi [19].

By taking $J(0^+) = J_0 > 0$ so that $G(0^+) = G_0 = 1/J_0$, the body is assumed to exhibit a non vanishing instantaneous response both in the creep and in the relaxation tests. As a consequence, we find it convenient to introduce two non-dimensional quantities $\psi(t)$ and $\phi(t)$ as follows

$$J(t) = J_0[1 + \psi(t)] , \quad G(t) = G_0 \phi(t) ,$$

where $\psi(t)$ is a non-negative increasing function with $\psi(0) = 0$ and $\phi(t)$ is a non-negative decreasing function with $\phi(0) = 1$. Henceforth, $\psi(t)$ and $\phi(t)$ will be referred to as dimensionless creep function and relaxation function, respectively. Viscoelastic bodies can be distinguished in solid-like and fluid-like whether $J(+\infty)$ is finite or infinite so that $G(+\infty) = 1/J(+\infty)$ is non zero or zero, correspondingly.

It is quite common in linear viscoelasticity to require the existence of positive retardation and relaxation spectra for the material functions $J(t)$ and $G(t)$, as pointed out by Gross in his 1953 monograph on the mathematical structure of the theories of viscoelasticity [7]. This implies, as formerly proved in 1973 by Molinari [26] and revisited in 2005 by Hanyga [9], see also Mainardi’s book [19], that $J(t)$ and $G(t)$ turn out to be Bernstein and Completely Monotonic functions, respectively. For their mathematical properties the interested reader is referred to the excellent monograph by Schilling et al. [34].

As pointed out e.g. in [19], the relaxation modulus $G(t)$ can be derived from the corresponding creep compliance $J(t)$ through the Volterra integral equation of the second kind

$$G(t) = \frac{1}{J_0} - \frac{1}{J_0} \int_0^t dt' \int_0^t dt'' G(t - t') G(t' - t'') ;$$
as a consequence, the dimensionless relaxation function $\phi(t)$ obeys the Volterra integral equation

$$
\phi(t) = 1 - \int_0^t \frac{d\psi}{dt} \phi(t - t') dt'.
$$

Mainardi and Spada in [23] have shown, both analytically and numerically, that the relaxation function corresponding to the Lomnitz creep law decays in time as the slow varying function $1/\ln t$.

Quite recently Pandey and Holm [27] have discussed the meaning of the empirical Lomnitz logarithmic law in the framework of time-dependent non-Newtonian rheology, where the stress-strain relation is

$$
\sigma(t) = \eta(t) \dot{\epsilon}(t), \quad t \geq 0,
$$

where $\eta(t) > 0$ represents a time-dependent viscosity coefficient. In particular, they have shown that the stress-strain equation leading to the Lomnitz law is

$$
\frac{q}{E_0} \sigma(t) = \left(1 + \frac{t}{\tau_0}\right) \dot{\epsilon}(t), \quad t \geq 0,
$$

so that the time evolution of viscosity is represented by the differential operator

$$
\hat{O}_1^t := \left(1 + \frac{t}{\tau_0}\right) \frac{d}{dt}.
$$

The starting point of Pandey and Holm [27] is a spring-dashpot viscoelastic model (of Maxwell type) with viscosity varying linearly in time that provides a relaxation function decaying in time to zero as a negative power law. We note that the stress-strain relation (1.6) indeed yields the Lomnitz creep law (1.1) for constant stress $\sigma(t) = \sigma_0$, but the power law for the relaxation function is not compatible with its ultra-slow decay of logarithmic type derived by by Mainardi and Spada in [23] in the framework of the linear theory of viscoelasticity as solution of the Volterra integral equation (1.3).

In Geophysics there exists another approach to derive the Lomnitz creep law: it is due to Scheidegger [32, 33], who in 1970 proposed a non-linear stress-strain relation that reads

$$
\dot{\sigma}(t) = 2\eta \ddot{\epsilon}(t) + \beta \dot{\epsilon}^2(t),
$$

where $\eta$ is the (constant) viscosity and $\beta$ a creep factor. The integration of this differential equation for a step input of stress $\sigma(t) = \sigma_0$ for $t \geq 0$ leads to the Lomnitz creep law (1.1) provided that $2\eta/\beta = q\sigma_0/E_0$ and $\tau_0$ is a suitable time constant of integration. This non-linear approach, however, even if justified by the author for some effects related to energy dissipation in rocks, has not found
a validation in the literature up to nowadays. Furthermore, no investigation for the relaxation of stress under constant strain has been considered.

The above discussion implies that in order to justify the Lomnitz creep law we have (at least, to our knowledge) three possible ways: the standard one based on the linear hereditary Volterra theory, the approach with non constant viscosity followed by Pandey and Holm [27] and the non-linear approach proposed by Scheidegger.

In this paper, starting with the Pandey and Holm [27] approach, we set up an iterative operational method based on operator (1.7) which leads to the generalized Lomnitz law

\[ \epsilon(t) = \frac{\sigma_0}{E_0} \left[ 1 + q \ln^\nu \left( 1 + \frac{t}{\tau_0} \right) \right] \frac{\Gamma(1+\nu)}{\Gamma(1+\nu)}, \quad 0 < \nu \leq 1, \quad t \geq 0. \]

We will then derive the corresponding relaxation function of this law by solving the related Volterra integral equation. An interesting outcome of our analysis is that the resulting rheological model considers both a time varying viscosity and the memory effects required by the hereditary theory of linear viscoelasticity.

We first give some mathematical preliminaries in the next Section and then in Section 3 we explain the meaning of our approach. In Section 4 we discuss the implications of our work and finally conclusions are drawn in Section 5.

For readers’ convenience we add two appendices. In Appendix A we recall the essentials of the Hadamard fractional calculus on which our operational approach is based. In Appendix B we outline the numerical method adopted to solve the Volterra integral equation satisfied by the relaxation function of our generalized model.

2. INTEGRO-DIFFERENTIAL OPERATORS WITH LOGARITHMIC KERNELS

In the recent paper by Beghin, Garra and Macci [2], an integro-differential operator with logarithmic kernel has been introduced in the context of correlated fractional negative binomial processes in statistics. Using their notation, the time-evolution operator \( \hat{O}_\nu^t \) acting on a sufficiently well-behaved function \( f(t) \) is defined as

\[
\hat{O}_\nu^t f(t) := \frac{1}{\Gamma(n-\nu)} \times \\
\int_{t}^{\infty} \ln^{n-1-\nu} \left( \frac{a + bt}{a + b\tau} \right) \left[ \left( \frac{a}{b} + \tau \frac{d}{d\tau} \right)^n f(\tau) \right] \frac{b}{a + b\tau} d\tau,
\]

for \( n - 1 < \nu < n \in \mathbb{N}, \ 0 < a \leq 1 \) and \( b > 0 \).
A relevant property of this operator is given by the following result

\begin{equation}
\hat{O}_\nu^t \ln^\beta (a + bt) = \frac{\Gamma(\beta + 1)}{\Gamma(\beta + 1 - \nu)} \ln^{\beta - \nu} (a + bt)
\end{equation}

for \( \nu \in (0, 1) \) and \( \beta > -1 \setminus \{0\} \), see [2], pag. 1057 for the details. Moreover we have that \( \hat{O}_\nu^t \text{ const.} = 0 \). We refer to the Appendix A for a short survey about fractional-type operators with logarithmic kernel, starting from the so-called Hadamard fractional calculus.

In analogy with the classical theory of fractional calculus (see e.g. the monograph by Kilbas, Srivastava and Trujillo [13]), we introduce the integral operator with logarithmic kernel acting on a sufficiently well-behaved function \( f(t) \) as

\begin{equation}
\hat{I}_\alpha^t f(t) := \frac{1}{\Gamma(\alpha)} \int_{1-a}^t \ln^{\alpha - 1} \left( \frac{a + bt}{a + b\tau} \right) f(\tau) \frac{b}{a + b\tau} d\tau, \quad \alpha > 0,
\end{equation}

so that we recognize

\begin{equation}
\hat{O}_\nu^t f(t) = \hat{I}_{1-\nu}^t \left[ \left( \frac{a}{b} + t \frac{d}{dt} \right)^n f(t) \right], \quad n - 1 < \nu < n, \quad n \in \mathbb{N}.
\end{equation}

Therefore, recalling the definition (1.7) for the operator \( \hat{O}_1^t \) with \( \tau_0 = 1 \) and taking \( \nu \in (0, 1) \), \( a = b = 1 \) in the above equation, we obtain

\begin{equation}
\hat{O}_\nu^t f(t) = \hat{I}_{1-\nu}^t \left[ \left( 1 + t \frac{d}{dt} \right)^n f(t) \right] = \hat{I}_{1-\nu}^t \hat{O}_1^t f(t), \quad 0 < \nu < 1.
\end{equation}

We also observe that, by using the property (2.2), it can be proved that the composed Mittag-Leffler function

\begin{equation}
E_{\nu,1}(-\ln^{\nu} (1 + t)) = \sum_{k=0}^{\infty} \frac{(-\ln^{\nu} (1 + t))^k}{\Gamma(\nu k + 1)}
\end{equation}

is an eigenfunction of the operator \( \hat{O}_\nu^t \). Once again we find the Mittag-Leffler functions, that are known to play a central role in the theory of fractional differential equations, see e.g. the recent monograph by Gorenflo et al [6]. As a matter of fact, the composition of the classical Mittag-Leffler function with the power of a logarithmic function decays as a power of the logarithmic function. This behaviour can be interesting in the framework the so-called \textit{ultra-slow kinetics} that includes phenomena of strong anomalous relaxation and diffusion and related stochastic processes. On this respect, the interested reader may refer to the seminal paper of 1983 by Sinai [31] and then, e.g. to Chechkin et al. [3], Metzler and Klafter [25], Mainardi et al. [20, 21] and more recently to Wen Chen et al. [4].
We can observe that, heuristically, the integro-differential operator $\hat{O}_t^\nu$ can be obtained by means of a time-change $t \to \left(\frac{a}{b} + t\right)$ starting from the definition of the Caputo fractional derivative. We also note that the operator $\hat{O}_t^\nu$ can be considered as a sort of fractional counterpart of the differential operator $\hat{O}_t^1$ appearing in the stress-strain equation governing the original Lomnitz’s law, see Eq. (1.6). Moreover, we remark that for $\nu = 0$ and $b = 1$ the operator $\hat{O}_t^\nu$ coincides with the regularized Hadamard fractional derivative (see Appendix A, [10] and [2] for more details).

3. A generalization of the Lomnitz law

We here consider a generalization of the Lomnitz stress-strain relation (1.6) where the operator $\hat{O}_t^1$ in (1.7) is replaced by the integro-differential operator $\hat{O}_t^\nu$ defined in (2.1) by taking $a = b = 1$. Note that we have taken for the sake of simplicity and without loss of generality $\tau_0 = 1$.

This means that we are considering a generalized rheology with memory effects and time-varying viscosity, based on the following stress-strain relation

\[
\frac{q}{E_0} \sigma(t) = \hat{O}_t^\nu \epsilon(t)
\]

\[
= \frac{1}{\Gamma(1 - \nu)} \int_0^t \ln^{-\nu} \left(\frac{1 + t}{1 + \tau}\right) \left[ \left(1 + \tau \right) \frac{d}{d\tau} \epsilon(\tau) \right] \frac{1}{1 + \tau} d\tau
\]

with $\nu \in (0, 1)$, $t \geq 0$.

By using property (2.2), we obtain that the solution of this generalized fractional equation, setting $\sigma(t) = \sigma_0$, is

\[
\epsilon(t) = \sigma_0 \frac{E_0}{q} \left[ 1 + q \ln^{\nu} \left(\frac{1 + t}{\Gamma(1 + \nu)}\right) \right], \quad 0 < \nu \leq 1, \quad t \geq 0,
\]

which represents our generalized Lomnitz creep law.

The corresponding non-dimensional creep function for this model is

\[
\psi_\nu(t) = q \ln^{\nu} \left(\frac{1 + t}{\Gamma(1 + \nu)}\right), \quad 0 < \nu \leq 1, \quad t \geq 0,
\]

so that the rate of creep is

\[
\dot{\psi}_\nu(t) = q \nu \ln^{\nu-1} \left(\frac{1 + t}{\Gamma(1 + \nu)}\right) \frac{1}{1 + t}, \quad 0 < \nu \leq 1, \quad t \geq 0.
\]
Therefore, in view of (1.3), the dimensionless relaxation function \( \phi_{\nu}(t) \) corresponding to our generalized Lomnitz creep law obeys the integral equation

\[
(3.5) \quad \phi_{\nu}(t) = 1 - \frac{q \nu}{\Gamma(1+\nu)} \int_0^t \frac{\ln^{\nu-1}(1+t')}{1+t'} \phi_{\nu}(t-t') \, dt', \quad 0 < \nu \leq 1, \quad t \geq 0,
\]

that is a Volterra integral equation of the second kind with logarithmic kernel if \( 0 < \nu < 1 \) as expected. Of course for \( \nu = 1 \) the case of the Lomnitz model is recovered, already investigated by Mainardi and Spada [23].

Figures 1 and 2 show the evolution of the dimensionless creep function \( \psi_{\nu}(t) \) and of the relaxation function \( \phi_{\nu}(t) \) corresponding to the generalised Lomnitz model, for various values of parameter \( \nu \). From Figure 1, we observe that the effect of decreasing the value of \( \nu \) is that of increasing the initial steepness of the creep function and of decreasing its subsequent rate of variation. This behaviour stems from the analytical expression for the rate of creep given by Eq. (3.4), valid for any value of time. From Figure 2, a similar sensitivity to the value of \( \nu \) is observed for the relaxation function, although no closed-form expression is available to corroborate this finding. However, the results in Figures 1 and 2 are both in agreement with the asymptotic representations given below.

![Figure 1](image.png)

**Figure 1.** The dimensionless creep function \( \psi_{\nu}(t) \) of the generalised Lomnitz model for \( \nu = 0.25, 0.50, 0.75, 1 \) depicted versus time: (a) linear scale, (b) logarithmic scale.

Henceforth, we report the asymptotic representations of the non-dimensional creep and relaxation functions taking \( q = \tau_0 = 1 \) for \( 0 < \nu \leq 1 \) for \( t \to 0^+ \) and \( t \to +\infty \). For \( \psi_{\nu}(t) \) these representations are directly obtained from its analytical expression given by Eq. (1.9). For \( \phi_{\nu}(t) \) the corresponding representations are properly derived from the relation between the Laplace transforms \( \tilde{\phi}_{\nu}(s) \) and \( \tilde{\psi}_{\nu}(s) \) that, by virtue of the Volterra integral equation...
Figure 2. The dimensionless relaxation function $\phi_\nu(t)$ of the generalized Lomnitz model for $\nu = 0.25, 0.50, 0.75, 1$ depicted versus time: (a) linear scale, (b) logarithmic scale.

Hence we get

$$\psi_\nu(t) \sim \begin{cases} \frac{t^\nu}{\Gamma(1 + \nu)}, & t \to 0^+, \\ \ln t^\nu/\Gamma(1 + \nu), & t \to +\infty, \end{cases}$$

and

$$\phi_\nu(t) \sim \begin{cases} 1 - \frac{t^\nu}{\Gamma(1 + \nu)}, & t \to 0^+, \\ \frac{\Gamma(1 + \nu)}{\ln t^\nu}, & t \to +\infty. \end{cases}$$

These asymptotic representations have been checked to fit with sufficiently good approximation the numerical results in suitable ranges of time.

4. DISCUSSION

The applications of fractional rheologies in rock-physics is nowadays widely accepted, on the basis of empirical validations and rigorous theoretical models (see e.g. [24] and the references therein). Fractional models have the great advantage to take into account memory effects in relaxation processes, providing a more realistic picture of the physical mechanisms involved in rock-physics. The logarithmic Lomnitz creep law is essentially phenomenological, but a complete viscoelastic characterization has been recently provided in [23]. In view of the relevance of memory effects in relaxation processes, the advantage of our approach lies in a generalization of the Lomnitz law by considering an integro-differential counterpart of the stress-strain relation governing the original logarithmic creep law. This mathematical explorative model is based on
the application of Hadamard-like fractional operators with logarithmic kernel. This choice is based on a physical reasoning: in this case the memory kernel should follow the logarithmic-type time of relaxation. The resulting generalized law has a simple form where the effect of memory is clearly parametrized by the real order $\nu$ appearing in (1.9). For the sake of completeness we have fully characterised this model, studying the corresponding relaxation function. The advantage of this generalization is to introduce a physical parameter $\nu$ in the model that allows to consider memory effects in the relaxation process and to find a better agreement with experimental data. Although the mathematical model is apparently more complicated, it is, in our view, useful to explore the physical applications of fractional Hadamard-like operators with logarithmic kernels. Hence, the main outcomes of our proposal are the following: to consider memory effects in logarithmic-type relaxation models and to start the study on the applications of the Hadamard-like operator (2.1) in the classical equations of mathematical physics. This can be particularly useful in the analysis of diffusive equations related to ultra-slow processes.

5. Conclusions

We have presented a new approach based on linear integro-differential operators with logarithmic kernel related to the Hadamard fractional calculus in order to generalize by a parameter $\nu \in (0,1]$ the Lomnitz creep law. For this generalized model we have derived the constitutive stress-strain relation in a form coupling memory effects and time-varying viscosity and also we have evaluated numerically the corresponding relaxation function. Finally, we note that the results obtained in this paper may be useful for fitting experimental data in rheology of real materials that exhibit responses in creep and relaxation varying slower than those of the Lomnitz model. We are thus confident to have found a suitable application of the Hadamard operators in the interrelated fields of fractional calculus and ultra-slow kinetics.

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Appendix A. Hadamard Fractional Calculus and More General Integro-Differential Operators with Logarithmic Kernel

According to the literature, there are many different definitions of fractional-type derivatives, motivated by the specific mathematical or physical problems under consideration. One of these definitions was introduced by Hadamard [8] in 1892 and, although not so frequently used in applications, it is generally mentioned in classical reference books on fractional calculus (e.g. [29], Section 18.3). The Hadamard fractional derivative essentially corresponds to the fractional power of the operator $\delta = (t \frac{d}{dt})$ and therefore can be obtained from the well-known Riemann-Liouville fractional derivative, by taking the change of variable $t \to \ln t$. The Hadamard fractional calculus is now gaining more interest in the mathematical literature (see for example [30] and references therein), while, as far as we know, few applications in mathematical-physics have been studied. For a survey about this topic, we refer to the textbooks [13] and [29] and to the review paper of Kilbas [12].

We first recall the definition of the Hadamard fractional integral

$$ (J^\nu_a f)(t) = \frac{1}{\Gamma(\nu)} \int_a^t \left( \ln \frac{t}{\tau} \right)^{\nu-1} f(\tau) \frac{d\tau}{\tau}, \quad 0 \leq a < t < b \leq \infty. $$

The left-sided Hadamard fractional derivative of order $\nu \geq 0$ is

$$ (D^\nu_a f)(t) = \delta^n (J^{n-\nu}_a f)(t) = \frac{1}{\Gamma(n-\nu)} \left( t \frac{d}{dt} \right)^n \int_a^t \left( \ln \frac{t}{\tau} \right)^{n-\nu-1} f(\tau) \frac{d\tau}{\tau}, $$

where $n = [\nu] + 1$ and $[\nu]$ is the integer-part of $\nu$.

In the recent paper [10], the Caputo-like regularization of the Hadamard derivatives was introduced as follows

$$ (CD^\nu_a f)(t) = (D^\nu_a f)(t) = (D^\nu_a f)(t) - \sum_{k=0}^{n-1} \frac{\delta^k f(a)}{k!} \left( \ln \left( \frac{t}{a} \right) \right)^k, $$

that is equivalent to commute the operator $\delta^n$ with the Hadamard fractional integral (see [10], Theorem 1). Therefore, the Caputo-like Hadamard derivative is

- for $\nu \notin \mathbb{N}$

$$ (CD^\nu_a f)(t) = J^{n-\nu}_a (\delta^n f)(t) = \frac{1}{\Gamma(n-\nu)} \int_a^t \left( \ln \frac{t}{\tau} \right)^{n-\nu-1} \left[ \left( \tau \frac{d}{d\tau} \right)^n f(\tau) \right] \frac{d\tau}{\tau} $$
for $\nu \in \mathbb{N}$

\[(A.5) \quad (CD_a^n f)(t) = \delta^n f(t) = \left( \frac{d}{dt} \right)^n f(t).\]

In analogy with this theory, in the recent paper by Beghin et al [2], the authors considered in a probabilistic framework the Caputo-like counterpart of the fractional power of the operator $\hat{O}_t = \left[ \left( \frac{a}{b} + t \right) \frac{d}{dt} \right]$. Observe that in the special case $a = 0$, we obtain again the Caputo-like regularization of the Hadamard derivative.

In analogy with the Hadamard derivative, this integro-differential operator can be formally obtained starting from the Caputo derivative by taking the change of variable $t \rightarrow \ln \left( \frac{a}{b} + t \right)$ with the advantage to avoid the singularity for $t = 0$.

The integro-differential operator considered in [2] is defined:

- if $\nu \notin \mathbb{N}$ as

\[(A.6) \quad \hat{O}_\nu f(t) = \frac{1}{\Gamma(n - \nu)} \int_{\frac{a}{b}}^{t} \ln^{n-1-\nu} \left( \frac{a + bt}{a + b\tau} \right) \hat{O}_n f(\tau) \frac{b}{a + b\tau} d\tau,\]

- if $\nu \in \mathbb{N}$ as

\[(A.7) \quad \hat{O}_\nu f(t) = \left( \hat{O}_1 \right)^n f(t).\]

Some basic results about this operator with logarithmic kernel have been investigated by Beghin et al. in [2] but a full mathematical analysis about the correct functional setting is still missing. On the other hand, as the authors have just suggested in that paper, integro-differential operators with logarithmic kernels can have also potential applications in physics.

We finally observe that Hadamard derivatives and their generalizations can be considered as particular, but interesting cases of fractional derivatives of a function with respect to another function, a topic considered in the book [13] (section 2.5, pp. 99-105). This approach to fractional calculus is poorly known in the mathematical-physics literature; however, quite recently, Almeida [1] has studied the regularized Caputo version.

**APPENDIX B. NUMERICAL APPROACH**

Here we present a numerical scheme adopted to solve the Volterra Integral Equation satisfied by our relaxation function $\phi_\nu(t)$ that we re-write henceforth
for the sake of convenience by setting $q = 1$, that is

\[(B.1) \quad \phi_{\nu}(t) = 1 - \frac{\nu}{\Gamma(1 + \nu)} \int_0^t \frac{\ln^{\nu-1}(1 + t')}{1 + t'} \phi_{\nu}(t - t') \, dt'.\]

**B.1. Definitions.** Our equation can be rewritten as

\[(B.2) \quad \phi_{\nu}(t) = 1 - \gamma \int_0^t K_{\nu}(t - \tau) \phi_{\nu}(\tau) \, d\tau,
\]

where the Kernel is

\[(B.3) \quad K_{\nu}(x) = \frac{\ln^{\nu-1}(1 + x)}{1 + x} = \frac{1}{\nu} \frac{d}{dx} \ln^\nu(1 + x),\]

and the constant $\gamma$ reads

\[(B.4) \quad \gamma \equiv \frac{\nu}{\Gamma(1 + \nu)}.\]

**B.2. Discretization.** In the following, we employ the Euler’s product integration, proposed for the first time by Young in [36] and described e.g. in the 1985 monograph by Linz [14]. In particular, we take advantage of the numerical scheme used in 1995 by Mainardi et al. [22] to deal the weakly singular Volterra equation with power law kernel for the generalized Basset problem for a sphere accelerating in a viscous fluid, see also the 1997 survey by Mainardi [18]. Here, however, the weak singularity of the kernel is of logarithmic type, that induces more restrictions on the efficiency of the method.

The integration interval $(0, t)$ is subdivided into $n$ equal intervals of width $\delta t \equiv h \ll 1$:

\[(B.5) \quad t_j = jh, \quad j = 0, 1, 2, \ldots, n,
\]

which allows to write our Volterra equation in a piecewise manner:

\[(B.6) \quad \phi_{\nu}(t_n) = 1 - \gamma \sum_{j=0}^{n-1} \int_{t_j}^{t_{j+1}} K_{\nu}(t_n - \tau) \phi_{\nu}(\tau) \, d\tau.
\]

We now assume a linear piecewise form for the function $\phi_{\nu}(t)$, that is $\phi_{\nu}(t) = \phi_j$ for $t_j \leq t < t_{j+1}$, which provides

\[(B.7) \quad \phi_n = 1 - \gamma \sum_{j=0}^{n-1} \phi_j \int_{t_j}^{t_{j+1}} K_{\nu}(t_n - \tau) \, d\tau,
\]
where $\phi_n$ is the approximation for $\phi(t_n)$. But

$$
\int_{t_j}^{t_{j+1}} K_\nu(t_n - \tau) d\tau = \int_{t_n-t_{j+1}}^{t_n-t_j} K_\nu(x) dx = \int_{(n-(j+1))h}^{(n-j)h} K_\nu(x) dx
$$

(B.8)  

\[
= \int_{(n-(j+1))h}^{(n-j)h} \frac{\ln^{\nu-1}(1 + x)}{1 + x} dx = \frac{1}{\nu} \ln^{\nu}(1 + x)\left|_{(n-j)h}^{(n-j+1)h}\right.
\]

\[
= \frac{\ln^{\nu}(1 + (n-j)h) - \ln^{\nu}(1 + (n-(j+1))h)}{\nu}.
\]

Hence

(B.9)  

$$
\phi_\nu(t_n) = 1 - \gamma \sum_{j=0}^{n-1} \Omega_{n-j} \phi_j,
$$

with

(B.10)  

$$
\Omega_n = \frac{\ln^{\nu}(1 + nh) - \ln^{\nu}(1 + (n-1)h)}{\nu}.
$$

Equations (B.9) and (B.10) have been implemented in a Fortran program. The results are depicted in the Figures 1 and 2 in the body of the paper.

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