The Global Water Cycle Budget: A Chronological Review

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Received: 11 November 2020 / Accepted: 30 June 2021 / Published online: 19 August 2021
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Abstract
Like civilization and technology, our understanding of the global water cycle has been continuously evolving, and we have adapted our quantification methods to better exploit new technological resources. The accurate quantification of global water fluxes and storages is crucial in studying the global water cycle. These fluxes and storages physically interact with each other, are related through the water budget, and are constrained by it. First attempts to quantify them date back to the early 1900s, and during the past few decades, they have received an increasing research interest, which is reflected in the vast amount of data sources available nowadays. However, these data have not been comprehensive enough due to the high spatiotemporal variability of the global water cycle. Herein, we provide a comprehensive review of the chronological evolution of global water cycle quantification, the distinct data sources and methods used, and a critical assessment of their contribution to improving the spatiotemporal monitoring of the global water cycle. The chronology of global water cycle components shows that the uncertainty of flux estimates over oceans remains higher than that over land. Comparing the standard deviation and the interquartile range of the estimates from the 2000s onward with those from all the estimates (1905-2019), we can affirm that statistical variability has diminished in recent years. Moreover, the variability of ocean precipitation and evaporation estimates from the 2000 onward was reduced by more than 70% compared with earlier studies. These findings advocate that the consistency of global water cycle quantification has been improved.

Keywords Global water cycle · Water budget · Multi-source quantification

Abbreviations
CHIRPS Climate Hazards Group Infrared Precipitation with Station Data
CLM3 Community Land Model version 3

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CMORPH  Climate Prediction Center Morphing Method
CPC  Climate Prediction Center
CRU TS  University of East Anglia Climatic Research Unit Time-Series
CSR  Center for Space Research at University of Texas
CSU  Colorado State University
DMSP  Defense Meteorological Satellite Program
ECMWF  European Centre for Medium-Range Weather Forecasts
ERA  European Centre for Medium-Range Weather Forecasts Re-Analysis
GEWEX  Global Energy and Water Exchanges
GFZ  Deutschen GeoForschungsZentrum
GHP  Global Energy and Water Exchanges Hydrometeorology Panel
GLDAS  Global Land Data Assimilation System
GLEAM  Global Land Evaporation Amsterdam Model
GPCC  Global Precipitation Climatology Centre
GPM  Global Precipitation Climatology Project
GRACE  Gravity Recovery and Climate Experiment
GRDC  Global Runoff Data Centre
GRGS  Groupe de Recherche de Géodésie Spatiale
GWAVA  Global Water Availability Assessment
H08  Hanasaki 2008
HITESSEL  Land Surface Hydrology Tiled European Centre for Medium-Range Weather Forecasts Scheme for Surface Exchanges Over Land
JPL  Jet Propulsion Laboratories
JULES  Joint UK Land Environment Simulator
LPJmL  Lund-Potsdam-Jena Managed Land
MacPDM  Macro-scale Probability-Distributed Moisture
MATSIRO  Minimal Advanced Treatments of Surface Interaction and Runoff
MERRA  Modern-Era Retrospective Analysis for Research and Applications
MPI-HM  Max Planck Institute - Hydrology Model
MOD16  Moderate Resolution Imaging Spectroradiometer Global Evapotranspiration Project
MODIS  Moderate Resolution Imaging Spectroradiometer
NRL  Naval Research Laboratory
NTSG  Numerical Terradynamic Simulation Group
Orchidee  Organising Carbon and Hydrology in Dynamic Ecosystems
PGF  Princeton Global Forcing
PREC/L  Precipitation Reconstruction Over Land
SRB-CFSR-SEBS  Surface Radiation Budget - Climate Forecast System Reanalysis - Surface Energy Balance System
SRB-CFSR-PM  Surface Radiation Budget - Climate Forecast System Reanalysis - Penman-Monteith
SRB-CFSR-PT  Surface Radiation Budget - Climate Forecast System Reanalysis - Priestly-Taylor
SRB-PGF-PM  Surface Radiation Budget - Princeton Global Forcing - Penman-Monteith
SSM/I  Special Sensor Microwave Imager
SSMIS  Special Sensor Microwave Imager Sounder
1 Introduction

Water and its continuous circulation through its global cycle have played a fundamental role in sustaining life on Earth since its formation. The global water cycle is a complex phenomenon composed of several physicochemical processes such as condensation, evaporation, groundwater flow, infiltration, percolation, plant uptake, precipitation, run-off, sublimation, transpiration, and water vapor transport (Allan et al. 2020), coupled with anthropogenic interactions like water withdrawals and soil moisture use for livestock, crop irrigation, and forestry (Abbott et al. 2019). The longstanding representation of the global water cycle’s conceptual model has been limited to three variables, namely precipitation, evaporation and runoff. Recently, this coarse representation has been partitioned to include the aforementioned sub-processes and their feedbacks. Our understanding of the global water cycle has been evolving over the years, and the methods we use to quantify hydro-meteorological variables have adapted to exploit new technologies. Furthermore, the need to better estimate the components of the global water cycle has driven tailor-made technological developments as well (e.g., satellite instruments; Hildebrand et al. 2003; Levizzani and Cattani 2019).

Remote sensing data and model simulations complemented the traditional surface-based measurements and offered unprecedented coverage over previously inaccessible or unmonitored regions. Even though these advances provided vast data sources and aided to quantify water cycle components at multiple scales, their varying performances and uncertainties limit their applicability to global scale analyses (Brocca et al. 2019). Thus, the number of primary components used to quantify the global water cycle has not changed much. The most substantial differences that arose with the inclusion of satellite data are the decomposition of total evaporation into evaporation over oceans and evapotranspiration over land (Dickinson 1984), and the addition of total water storage (L’vovitch M, 1973). The above components represent the major inputs, outputs, and storage of the global water cycle. Hence, if we apply the mass conservation principle, we may write the water budget equation, which relates to these four components as follows.

\[ \Delta \text{TWS} = P - \text{ET} - Q \]  

(1)
where $\Delta TWS$ is the change in total water storage (as the sum of groundwater, soil moisture, and surface water such as river water, snow water, and water in lakes), $P$ is precipitation, $ET$ is evapotranspiration, and $Q$ is the net water transport. The rest of the global water cycle processes are, to some extent, encompassed in these four components (Bengtsson 2010). Inadvertently, aggregating global water cycle components to the most dominant ones also aggregates the underlying uncertainties of the minor components, which are overshadowed by the uncertainties of the major components with the available accuracy at the moment. Global water cycle quantification accuracy is further hindered by the inherent biases revealed in the first attempts to unify multiple data sources for a single component due to the vast heterogeneity of algorithms and data used (Hegerl et al. 2018).

Uncertainties in the quantification of global water cycle components are indispensable when attempting to close the water budget. We can express equation 1 as:

$$P - ET - Q - \Delta TWS = R$$

where $R$ is the budget residual, which in a closed budget equals to zero. Through the years, there have been various attempts to close the budget (Starr and Peixoto 1958; Willmott et al. 1985; Sheffield et al. 2009; Sahoo et al. 2011). They have used different data sources and methods to minimize the residual, but non-closure of the water budget still prevails. Alternatively, rather than using budget closure as the performance metric, some researchers prefer to look at runoff as a diagnostic flux to assess their results (Sheffield et al. 2009). Closing the water budget not only will improve our understanding of the global water cycle, but will necessarily lead to improvement of the accuracy of the data involved. Enhancing data accuracy is of critical importance for applications in climatology, hydrology, meteorology, and water resource management, to name a few.

To keep moving forward towards closure of the global water cycle, with more accurate data, it would be beneficial to assess previous achievements. Herein, we present a review of the chronological evolution of the paradigms regarding the global water cycle budget. We provide an in-depth recapitulation of the advancements in global water cycle quantification. In addition, we present a comparison between budgets reported in the literature, with highlights on the methods and data sources used. Using significant technological improvements as timeline reference milestones, we considered four epochs, namely Early Days of Hydrology, Model Simulations Period, Satellite Era, and Age of Big Data. Each epoch is characterized by its own accomplishments and challenges. Some of the latter were overcome in succeeding epochs and some prevailed up to the present. Despite data reaching unprecedented availability, detail, and coverage, the quest for robust quantification of the global water cycle remains.

2 Chronicle

2.1 Early Days of Hydrology

Studies of the global water cycle are as old as hydrology. In classical Greece, Plato and Aristotle philosophized that groundwater might be the component responsible for circulating water resources by connecting rivers and lakes. However, Marcus Vitruvius is most commonly credited to be the first one to conceptualize the water cycle. In the first century BCE, Vitruvius proposed a philosophical description of the water cycle that placed precipitation instead of groundwater as a critical component of water transport (Pollio 1648).
Vitruvius planted a seed that would later lead both, yet independently, during the sixteenth century, Leonardo da Vinci and Bernard Palissy into describing a water cycle with three principal components: precipitation, evaporation, and runoff (Palissy 1580; Pfister et al. 2009). Therefore, equation 1 was originally formulated as:

\[ P - E = Q \]

where \( P \) is precipitation, \( E \) is evaporation, and \( Q \) is the runoff or exceeding precipitation. With this theoretical formulation, the scientific community ventured into quantifying the above components during the seventeenth century. Pierre Perrault and Edmund Halley were among the pioneers that supplemented experimental science to hydrology with their research on catchment precipitation and evaporation, respectively (Brutsaert 2005). John Dalton was the first to quantify all three above-listed components for England and Wales, providing a comprehensive quantification of a water cycle and not just a single component of it (Dalton 1799).

With catchment scale quantification achieved, the next step was to aim for global-scale quantification. During the next years and up to the end of the 1960s, numerous studies, mainly coming from Germany and Russia, attempted to quantify the global water cycle. Baumgartner and Reichel (1972) surveyed the literature on global water cycle.

### Table 1 Modified from Baumgartner and Reichel (1972) to exclude incomplete rows

| Author             | \( P_L \) | ET  | \( Q \) | \( P_O \) | \( E \) | \( P_{TOT} \) | \( E_{TOT} \) |
|--------------------|----------|-----|--------|----------|-------|------------|------------|
| Brückner (1905)    | 122      | 97  | 25     | 359      | 384   | 481        | 481        |
| Fritzsche (1906)   | 112      | 81  | 31     | 353      | 384   | 465        | 465        |
| Schmidt (1915)     | 112      | 81  | 31     | 242      | 273   | 354        | 354        |
| Wüst (1922)        | 112      | 75  | 37     | 267      | 304   | 379        | 379        |
| Cherubim (1931)    | 112      | 75  | 37     | 334      | 371   | 446        | 446        |
| Meinardus (1934)   | 99       | 62  | 37     | 412      | 449   | 511        | 511        |
| Halbfaß (1934)     | 100      | 52  | 48     | 410      | 458   | 510        | 510        |
| Wüst and Defant (1936) | 99   | 62  | 37     | 297      | 334   | 396        | 396        |
| Wundt (1938)       | 99       | 62  | 37     | 346      | 383   | 445        | 445        |
| L’vovitch M, (1945)| 107      | 71  | 36     | 412      | 448   | 519        | 519        |
| Möller (1951)      | 99       | 62  | 37     | \( \leq 324 \) | \( \leq 361 \) | \( \leq 423 \) | \( \leq 423 \) |
| Reichel (1952)     | 100      | 70  | 30     | 315      | 345   | 415        | 415        |
| Wüst et al. (1954) | 100      | 73  | 27     | 324      | 351   | 424        | 424        |
| Budyko (1955)      | 100      | 66  | 34-38  | 370      | 408   | 470        | 474        |
| Albrecht (1960)    | 100      | 67  | 33     | 378      | 411   | 478        | 478        |
| Budyko (1963)      | 107      | 61  | 46-48  | 404      | 452   | 512        | 513        |
| Mira (1964)        | 108      | 72  | 36     | 412      | 448   | 520        | 520        |
| Nace (1968)        | 100      | 69  | 31     | 319      | 350   | 419        | 419        |
| Kessler (1968)     | 100      | 60  | 40     | 410      | 450   | 510        | 510        |
| Mather (1969)      | 106      | 69  | 37     | 382      | 419   | 488        | 488        |
| L’vovitch (1970)   | 109      | 72  | 37     | 411      | 448   | 520        | 520        |
| Budyko (1970)      | 107      | 64  | 43     | 412      | 455   | 519        | 519        |

All the fluxes are in \( 10^3 \) km\(^3\)/year. \( P_L \) is precipitation overland, ET is evapotranspiration overland, \( Q \) is runoff, \( P_O \) is precipitation over oceans, \( E \) is evaporation over oceans, \( P_{TOT} \) is total global precipitation, and \( E_{TOT} \) is total global evaporation.
quantification during the 1900s and added their findings to the previous compilation by Reichel (1952), accounting for over 40 studies (Table 1). Over land, precipitation range between \((99 \text{ to } 122) \times 10^3 \, \text{km}^3/\text{year}\), evapotranspiration range between \((52 \text{ to } 97) \times 10^3 \, \text{km}^3/\text{year}\), and runoff range between \((25 \text{ to } 48) \times 10^3 \, \text{km}^3/\text{year}\). Over oceans, precipitation and evaporation range between \((242 \text{ to } 412) \times 10^3 \, \text{km}^3/\text{year}\) and \((273 \text{ to } 458) \times 10^3 \, \text{km}^3/\text{year}\), respectively. Note that evaporation and evapotranspiration have the most extensive ranges, presumably, because these values were derived from other measurements since, at the time, it was not possible to obtain direct observations. Even so, several reported fluxes are similar, if not identical, which may be caused by the fact that despite using different approximations or formulations, the initial data set used was the same. Over land precipitation estimates were derived from gauge and chart data, runoff estimates were derived from the river measurements by Marcinek (1964), and evaporation estimates were computed as the difference between precipitation and runoff. Over oceans, heat balance maps, and climatological data for fixed locations constituted evaporation estimates, runoff is the same as overland because of atmospheric water balance (Rasmussen 1970), and precipitation estimates were the difference between evaporation and runoff.

Due to the high variability in time and space of global water cycle components, ground station reports were not representative of the surrounding areas. Besides, it has been typical for developing countries not to possess a ground station network dense enough to monitor global water cycle components in those regions (Willmott et al. 1994). Aware of the above, Baumgartner and Reichel (1972) introduced very strong yet somewhat arbitrary correction assumptions, and estimated the errors based on the biggest difference between the values compiled on their survey. Considering that the precipitation measured by rain gauges is smaller than the amount reaching the surface and there are different zonal climatic conditions overland, the authors suggest three different options to correct precipitation underestimation. They pointed out that the scenario selected is the most probable, yet no explanation is provided towards why that is. Correcting precipitation overland has a ripple effect because it is used to compute runoff, which is then used to compute precipitation over the oceans. Based on their assumptions, they report the quantification of the global water cycle had been achieved within a margin of ten percent relative error.

A decade later, Willmott et al. (1985) presented the first study with sufficient spatial coverage. Their study was based on temperature and precipitation observational data records from 13,332 globally distributed stations, and estimated terrestrial snow-cover, soil moisture, and evapotranspiration. Their work extended on previous regional studies over Africa (Mather 1962), Asia excluding U.S.S.R. (Mather 1963a), U.S.S.R. (Mather 1963b), Australia, New Zealand, and Oceania (Mather 1963c), Europe (Mather 1964a), North America excluding USA (Mather 1964b), USA (Mather 1964c), and South America (Mather 1965). The above cumulatively used only 8,565 stations from the same network Willmott et al. (1985) used on their study. Still, they had to use empirical equations and a revised version of the potential evapotranspiration method of Thornthwaite (1948) in order to derive snow-cover, soil moisture, and evapotranspiration from the temperature and precipitation observational data available. Willmott et al. (1985) did not report single values as annual averages, but presented their results in maps where it could be seen that annual mean evapotranspiration is approximately \(173 \times 10^3 \, \text{km}^3/\text{year}\) over continental regions near the equator, \(43 \times 10^3 \, \text{km}^3/\text{year}\) towards the poles, and below \(43 \times 10^3 \, \text{km}^3/\text{year}\) across the Sahara, Arabia and Central Asia. Nonetheless, we know now, technological limitations and the lack of data sources place the findings of the above discussed studies in a best-guess scenario only.
2.2 Model Simulations Period

In simple terms, General Circulation Models (GCMs) are a set of theoretical and empirical mathematical expressions that attempt to simulate climate’s physical processes. They could be an atmospheric GCM, an oceanic GCM, or a coupled GCM. The first atmospheric GCM was introduced by Norman Phillips (1956), and it opened the door to new opportunities for global water cycle quantification (McGuffie and Henderson-Sellers 2001). Not long after, towards the end of the 1960s, the National Oceanic and Atmospheric Administration Geophysical Fluid Dynamics Laboratory developed the first coupled GCM (Manabe 1969). The basic structure of a GCM can be seen in Fig. 1. The GCM spatial domain is composed of 3D cells, whose horizontal grid is typically formed by latitude and longitude, and pressure levels determine the cell height. The number of physical processes considered and the complexity to which they are represented have continuously improved since the introduction of GCMs. Today’s models further account for terrestrial vegetation and the carbon cycle with an explicit representation of biogeochemical processes—such models are referred to as Earth System Models or ESMs (Flato 2011; Collins et al. 2013; Hurrell et al. 2013; Flato et al. 2014; Otto-Bliesner et al. 2016).

Model simulations were initially driven exclusively by ground observations. Later on, satellite remote sensing, model reanalysis data sets, or different combinations of them were assimilated. Hydrological models revolutionized the quantification of the global water cycle by providing regular gridded data with global coverage as well as constant time steps. On top of that, both statistical and dynamical downscaling of GCMs and ESMs have evolved over the past decades to enable more reliable estimates (Tapiador et al. 2020). For example, the most recent release of the European Centre for Medium Range Weather Forecasts Reanalysis product (ERA-5), which is a reanalysis based on the European Centre for Medium-Range Weather Forecasts’ Integrated Forecasting System (ECMWF’s IFS) weather model, provides a 30 km global coverage with 137 atmospheric pressure levels.
capped at 80 km with uncertainty ranges reported at each level (Hersbach et al. 2020). Despite the exponential growth in computing power efficiency, many fundamental processes like radiative transfer, convection initiation, hydrometeor phase change, and cloud microphysics that occur between the sub-kilometer scale and the microscale (i.e., nine orders of magnitude less than current model resolutions) are parameterized, as they cannot be resolved at the model resolution. On that account, while GCMs and ESMs provide global coverage of water cycle components, their spatial and temporal resolution is still relatively coarse, hindering validation attempts.

Model simulations further changed global water cycle quantification by providing more robust formulations towards the estimation of evapotranspiration. The bucket model developed by Budyko (1961) was implemented for the evapotranspiration scheme used in the first coupled GCM (Manabe 1969). This scheme oversimplified the physical processes surrounding evapotranspiration (Fig. 2); nevertheless, its results were not significantly different from much more complex formulations attempted in contemporaneous GCMs (Carson 1982). In the aforementioned scheme, evapotranspiration depends on potential evaporation, soil water content, field capacity (defined as the amount of soil moisture or water content held in the soil after excess water has drained away and the rate of downward movement has decreased), and water holding capacity (Carson 1982). Federer et al. (1996) compared five surface-independent and four surface-dependent potential evapotranspiration approximation schemes in models, and their results suggest that, at that time, none of the methods significantly differ from each other for most surface types. Still, the authors point out that the Penman-Monteith (Monteith and Unsworth 2013) and Shuttleworth & Wallace (Shuttleworth and Wallace 1985) methods might pose as the most comprehensive for global-scale analysis, a hypothesis that was later confirmed for Penman-Monteith (Wang and Dickinson 2012).

Fig. 2 Schematic of the Budyko bucket model implemented by Manabe (1969). The model represents a single layer soil reservoir with a defined maximum field water capacity of 15 cm from which soil water evaporates at a rate proportional to the remaining water content.
Table 2  Modified from Haddeland et al. (2011)

| Model name | Model time step | Meteorological forcing variables | ET scheme | Reference(s) |
|------------|-----------------|----------------------------------|-----------|--------------|
| GWAVA      | Daily           | \( P, T, W, q, \text{LW}_{\text{net}}, \text{SW}, \text{SP} \) | Penman-Monteith | Meigh et al. (1999) |
| H08        | 6h              | \( \text{RR, S, T, W, q, LW, SW, SP} \) | Bulk formula | Hanasaki et al. (2008) |
| HTESSSEL   | 1h              | \( \text{RR, S, T, W, q, LW, SW, SP} \) | Penman-Monteith | Balsamo et al. (2009) |
| JULES      | 1h              | \( \text{RR, S, T, W, q, LW, SW, SP} \) | Penman-Monteith | Cox et al. (1999), Essery et al. (2003) |
| LPJmL      | Daily           | \( P, T, \text{LW}_{\text{net}}, \text{SW} \) | Priestley-Taylor | Bondeau et al. (2007), Rost et al. (2008) |
| MacPDM     | Daily           | \( P, T, W, q, \text{LW}_{\text{net}}, \text{SW} \) | Penman-Monteith | Arnell (1999), Gosling and Arnell (2011) |
| MATSIRO    | 1h              | \( \text{RR, S, T, W, q, LW, SW, SP} \) | Bulk formula | Takata et al. (2003), Koirala (2010) |
| MPI-HM     | Daily           | \( P, T \) | Thornthwaite | Hagemann and Dümenil (1997), Hagemann and Gates (2003) |
| Orchidee   | 15 min          | \( \text{RR, S, T, W, q, SW, LW, SP} \) | Bulk formula | de Rosnay and Polcher (1998) |
| VIC        | Daily/3h        | \( P, T_{\text{max}}, T_{\text{min}}, W, q, \text{LW, SW, SP} \) | Penman-Monteith | Liang et al. (1994) |
| WaterGAP   | Daily           | \( P, T, \text{LW}_{\text{net}}, \text{SW} \) | Priestley-Taylor | Alcamo et al. (2003) |

LW is downward longwave radiation flux, \( \text{LW}_{\text{net}} \) is net longwave radiation flux, \( P \) is precipitation (rain or snow distinguished in the model), \( q \) is specific humidity, \( \text{RR} \) is rainfall rate, \( S \) is snowfall rate, \( \text{SW} \) is downward shortwave radiation flux, \( \text{SP} \) is surface pressure, \( T \) is air temperature, \( T_{\text{max}} \) is maximum daily air temperature, \( T_{\text{min}} \) is minimum daily air temperature, and \( W \) is wind speed. Bulk formula: Bulk transfer coefficients are used when calculating the turbulent heat fluxes.
The coupled GCM introduced by Manabe (1969) simulated average values of $93.4 \times 10^3$ km$^3$/year overland precipitation, $69.5 \times 10^3$ km$^3$/year evapotranspiration, $23.9 \times 10^3$ km$^3$/year runoff, $359.3 \times 10^3$ km$^3$/year over ocean precipitation, and $429 \times 10^3$ km$^3$/year evaporation. In recent years, Haddeland et al. (2011) compared 11 model simulations for the period 1985-1999 (Table 2). Observation-based data for global precipitation overland had an average value of $126 \times 10^3$ km$^3$/year, simulated evapotranspiration, and runoff mean values range between $(60$ to $85) \times 10^3$ km$^3$/year and $(42$ to $66) \times 10^3$ km$^3$/year, respectively. Note that Manabe’s evapotranspiration estimate is the only flux within the values reported by Haddeland et al. (2011). Besides, the later estimates are within the range for annual averages reported by Baumgartner and Reichel (1972), hinting that despite the substantial uncertainties and approximations, the values reported in the previous period were not that far from the current ones.

Model simulations did represent a new data source with seeming advantages over observations like the ability to generate global coverage data and perhaps more revolutionary to forecast, predict, and project. Nevertheless, once again, the scientific community relied heavily on observational data because it was crucial for model calibration and validation. Consequently, this novel opportunity to research global water cycle variability and its response to global warming further stressed the need for better observation-based measurements and more accurate quantification of the cycle components.

### 2.3 Satellite Era

Shortly after the introduction of climate models (Phillips 1956), the Television Infra-red Observation Satellite (TIROS-1 or TIROS-A) became the first weather satellite successfully launched in 1960, and so it began the satellite era (NOAA 1987). Barnes and Bowley (1968) proved the effectiveness of satellite observations in hydrology when they published their findings on snow cover mapping over the Missouri and Upper Mississippi River basins. Thereafter, several satellite missions made it into orbit, among the most notable, we may mention the National Aeronautics and Space Administration (NASA) Earth Observing System (EOS) missions. Based on their orbits, satellites could be grouped into two major groups, either geosynchronous orbit (GEO) or polar orbit. Many of the satellites involved in the EOS missions have a nearly polar orbit. Polar-orbit satellites move around the Earth in a Sun-synchronous orbit so that the overpass occurs at the same local time every day, taking around 100 minutes to complete an orbit. These satellites overpass the equator at the same local solar time each day. Satellite sensors could be active or passive, and it is not uncommon for both to be onboard the same satellite. For example, the Tropical Rainfall Measuring Mission (TRMM) Microwave Imager (TMI), a passive sensor, and the Precipitation Radar (PR), an active sensor, were onboard the TRMM satellite. Regarding satellites and missions of particular interest for global water cycle quantification, we have the TRMM (Huffman et al. 2007) and the Global Precipitation Measurement (GPM) (Huffman et al. 2015) for precipitation, the Moderate Resolution Imaging Spectroradiometer (MODIS) for evapotranspiration (Mu et al. 2011), and the Gravity Recovery and Climate Experiment (GRACE) for total water storage (Tapley et al. 2004). There is no specific instrument nor mission dedicated solely to runoff yet (Hong et al. 2007). However, runoff could be derived from other satellite observations, for instance, TRMM precipitation (Huffman et al. 2007), and MODIS land cover (Friedl et al. 2002) using the Natural Resources Conservation Service (NRCS) runoff curve number method (Cronshay 1986; Burges et al. 1998).
Satellite observations complemented the traditional surface measurements and offered unprecedented observational coverage on a global scale (McCabe et al. 2017). The Defense Meteorological Satellite Program (DMSP) near-polar orbiting satellites have been key providers of data over the oceans since 1987 (Dubach and Ng 1988). Onboard their satellites, the most notable instruments are the Special Sensor Microwave Imager (SSM/I) (Hollinger 1991) and its successor, the Special Sensor Microwave Imager Sounder (SSMIS) (Kunkee et al. 2008). These passive microwave radiometers provide measurements used to derive data on surface wind speed, atmospheric water vapor, cloud liquid water, and rain rate, which are critical to quantifying the global water cycle (Robertson et al. 2014). Furthermore, various present-day models and reanalysis products assimilate satellite observations (Van Dijk et al. 2011). Nonetheless, like for GCMs, ground observations are crucial for satellite data validation. Notwithstanding, the number of ground stations worldwide has been declining since the 1970s (Walker et al. 2016). It was not before Trenberth et al. (2007) that the availability of observational and modeled data to quantify the global water cycle was exploited. A year prior, Oki and Kanae (2006) presented a quantitative synthesis of the global water cycle. Instead of estimating the budget, they made a compilation of individual studies to stress the importance of global water cycle quantification and further assessment to manage renewable freshwater resources properly. This concern has been in the minds of the scientific community for quite some time now (Falkenmark and Lindh 1974). The budget assessments by Trenberth et al. and Oki & Kanae are held in high regard and are often used as a sort of validation reference (Rodell et al. 2015).

Oki and Kanae (2006) addressed the availability of renewable freshwater resources for human consumption within the global water cycle. The authors stressed that freshwater availability would be better assessed by fluxes than by storages because water is a circulating resource. Also, given the high variability of the water cycle in time and space, water stress is not a problem of how much water is available but a matter of when and where it is available (Postel et al. 1996). To better represent their research, they synthesized previous estimates of global water cycle fluxes and storages (Korzoun (1978), Shiklomanov (1998), Dirmeyer et al. (2006), and Oki (2006)). By doing so, they also presented a much more comprehensive mean state of the global water cycle. Their results showed overland precipitation of $111 \times 10^3 \text{ km}^3/\text{year}$, evapotranspiration of $65.5 \times 10^3 \text{ km}^3/\text{year}$, and runoff of $45.5 \times 10^3 \text{ km}^3/\text{year}$. Moreover, precipitation is divided into rainfall and snowfall, plus the fluxes are allocated to different terrains or land uses. Over oceans, precipitation was $391 \times 10^3 \text{ km}^3/\text{year}$ and evaporation was $436.5 \times 10^3 \text{ km}^3/\text{year}$.

Trenberth et al. (2007) used different data sources to quantify the global water cycle and its components. Three data sets were selected for precipitation, the Global Precipitation Climatology Project (GPCP v2; Adler et al. 2003), the University of East Anglia Climatic Research Unit time-series (CRU TS 2.1; Mitchell and Jones 2005), and the Precipitation REConstruction over Land (PREC/L; Chen et al. 2002). Evapotranspiration was simulated using the Community Land Model version 3 (CLM3; Bonan et al. 2002; Qian et al. 2004), which was forced using a combined PREC/L and GPCP precipitation data set. Surface plus subsurface runoff was derived from two climatic water balance estimates (evapotranspiration minus precipitation), the first from the European Centre for Medium Range Weather Forecasts Reanalysis 45 year product (ERA40; Uppala et al. 2005) using the methods described by Trenberth and Guillemot (1998), and the second using evapotranspiration from CLM3 and GPCP precipitation. Additionally, the authors relied on previous work for some components of the global water cycle like surface runoff (Dai and Trenberth 2002), ice volumes (Houghton et al. 2001), soil moisture (Webb et al. 1993), and groundwater (Schlesinger 2005). It was common for prior studies to cite values that, in
return, cite another and so on. Unlike them, the authors documented, and traced back as far as possible, the origins of the values used. They reported $113 \times 10^3 \text{ km}^3/\text{year}$ overland precipitation, $73 \times 10^3 \text{ km}^3/\text{year}$ evapotranspiration, $40 \times 10^3 \text{ km}^3/\text{year}$ runoff, $373 \times 10^3 \text{ km}^3/\text{year}$ over ocean precipitation, and $413 \times 10^3 \text{ km}^3/\text{year}$ evaporation.

It is important to note that satellite data records are recently of sufficient time frame lengths and with methods “mature” enough to develop meaningful global water cycle climatology records that can provide information on its components mean state and variability (Schlosser and Houser 2007; Robertson et al. 2014). Exploiting the increasing availability and maturity of satellite products, Sheffield et al. (2009) addressed the feasibility of closing the water budget, relying solely on satellite-based products. They combined the TRMM Multi-satellite Precipitation Analysis (TMPA; Huffman et al. 2007) and the Climate Prediction Center morphing method (CMORPH; Joyce et al. 2004) products for precipitation, the University of Colorado GRACE time series (CSR RL04; Wahr et al. 1998) for total water storage, and they derived evapotranspiration from Aqua satellite data using the Penman-Monteith revised formulation proposed by Mu et al. (2007). Then they evaluated their findings over the Mississippi River basin comparing their runoff estimates, computed as the budget residual, with ground observations. Their results indicate that the data products selected do not close the budget because the computed runoff is greatly overestimated compared to ground measurements. The authors suggest that further improvement of satellite-based products may reduce the residual and suggest multi-source data merging as a complementary means to achieve budget closure.

### 2.4 Age of Big Data

In this day and age, we have transitioned from minimal data coverage and sources into a widely heterogeneous abundance. In contrast to the continuous decline in the number of ground stations, satellite-based and model-derived data products have proliferated. However, while some components of the global water cycle have multiple products to choose from (e.g., precipitation), others do not (e.g., total water storage). Some products assimilate or calibrate against ground station data to improve their performance (Rudolf and Schneider 2005); others implemented machine learning processing to do so (Hong et al. 2004). It is not uncommon to find performance comparisons between products in the literature, evincing large differences in the magnitude and the variability of the estimates (e.g., as much as 300 mm/year difference between precipitation data sets; Sun et al. 2018). In their global comparison of 30 data sets at multiple spatiotemporal scales, Sun et al. (2018) found that, in general, variability from reanalysis data sets is more substantial than that from other data sources. Conversely, we can see that no single data set performs the best in all regions and at all scales. Aware of that fact, some studies did not look for the best individual data set, but the best combination of data sets towards budget closure of the water cycle over one (Azarderakhsh et al. 2011) or multiple basins (Lorenz et al. 2014). It should be pointed out that the above studies’ success metric was not budget closure itself, but validation versus in situ runoff instead.

The paradigm of quantifying the global water cycle is steadily shifting from identifying the best data source per water cycle component into developing the best way to merge data from various sources to complement each other. Various integration methodologies have emerged, among the most widely used ones are: Bayesian model averaging, constrained linear regression, neural networks, optimal interpolation, and simple weighting (Bishop 1995; Hoeting et al. 1999; Rodgers 2000; Aires et al. 2004). Also, post-processing closure
methodologies, which distributed the budget residual $R$ among the components based on each component’s uncertainties, explored Monte Carlo applications and Kalman filter variations (Pan and Wood 2006; Munier and Aires 2018). Specifics vary from method to method, but, in general, combining different data sets consists of three steps. These steps are an initial assessment of the products to be combined, followed by the integration of the products, and finally, budget closure post-processing.

Data integration is not a new concept nor the methods mentioned above, but its implementation altogether with closure constraints into the quantification of the water cycle is. Sahoo et al. (2011) used 16 data sets (eight for precipitation, six for evapotranspiration, one for runoff, and one for total water storage) applying simple weighting integration over ten basins across the globe, determining water cycle budget non-closure between 5 – 25%. Likewise, Pan et al. (2012) used eight data sets (four for precipitation, two for evapotranspiration, one for runoff, and one for total water storage) in 32 different basins. The authors focused on describing the uncertainty contribution of each component rather than focusing on budget closure, and found that, in general, most of the closure error comes from evapotranspiration.

To date, only a few studies have adopted multi-source data integration at the global scale (Rodell et al. 2015; Zhang et al. 2016; Munier and Aires 2018). The differences between studies and their results reside either on the data sets selected or in the post-processing. Rodell et al. (2015), using six data sets (one for precipitation, three for evapotranspiration, one for runoff, and one for total water storage; Table 3), reported a non-closure residual of less than 10%. The authors adopted the variational data assimilation algorithm of L’Ecuyer and Stephens (2002) and adjusted it to optimize the global water cycle budget closure at the annual scale. They reported $(116.5 \pm 5.1) \times 10^3 \text{ km}^3/\text{year}$ overland precipitation, $(70.6 \pm 5.0) \times 10^3 \text{ km}^3/\text{year}$ evapotranspiration, $(45.9 \pm 4.4) \times 10^3 \text{ km}^3/\text{year}$ runoff, $(403.5 \pm 22.2) \times 10^3 \text{ km}^3/\text{year}$ over ocean precipitation, and $(449.5 \pm 22.2) \times 10^3 \text{ km}^3/\text{year}$ evaporation. Note that the estimates reported by Oki and Kanae (2006) and Trenberth et al. (2011) lie within the above findings with the only two exceptions of overland precipitation from Oki and Kanae (2006) and runoff from Trenberth et al. (2011).

Zhang et al. (2016), using 14 data sets (five for precipitation, six for evapotranspiration, one for runoff, and two for total water storage; Table 4), assessed the effect of different data sources in the estimation of the water cycle and its budget closure. By removing/replacing in situ observations, reanalysis products, model simulations, or satellite products before data integration, the authors observed that removing non-satellite sources worsens

| Table 3 | Compiled from Rodell et al. (2015). $P$ is precipitation, ET is evapotranspiration, $Q$ is runoff, and $\Delta TWS$ is changes in total water storage |
|---------|----------------------------------------------------------------------------------------------------------------------------------|
| Data source | Variable | Reference(s) |
| GPCP v2.2 | $P$ | Adler et al. (2003); Huffman et al. (2009) |
| Princeton ET | ET | Vinukollu et al. (2011b) |
| MERRA and MERRA-Land | ET | Rienecker et al. (2011); Bosilovich et al. (2011); Reichle (2012) |
| GLDAS | ET | Rodell et al. (2004) |
| University of Washington runoff | $Q$ | Clark et al. (2015) |
| CSR RL05 | $\Delta TWS$ | Chambers and Bonin (2012); Johnson and Chambers (2013); Tapley et al. (2004) |
closure errors. Furthermore, as for satellite data sets, they indicate that budget closure error depends on the use of satellite-only data sets or satellite-gauge combined data sets. Regardless of the combination of data sets, the budget could not be closed and, thus, a constrained Kalman filter was used, as developed by Sahoo et al. (2011). They reported a non-closure residual that ranges between $7.6 - 10.4\%$ when using satellite products that lack gauge-based corrections, which is reduced to $4.2 - 9.0\%$ when using gauge-corrected satellite products.

Munier and Aires (2018) integrated 12 data sets (four for precipitation, three for evapotranspiration, one for runoff, and four for total water storage; Table 5) over 11 basins to test a budget closure correction model. The authors define the Calibration Index for Closure (CIC), which depends on the values of precipitation minus evapotranspiration ($P - ET$) and the Normalized Difference Vegetation Index (NDVI), and based on the CIC values,

### Table 4

Modified from Zhang et al. (2016). $P$ is precipitation, ET is evapotranspiration, $Q$ is runoff, and TWS is total water storage.

| Data source | Variable | Reference(s) |
|-------------|----------|--------------|
| CSU         | $P$      | Bytheway and Kummerow (2013) |
| PGF         | $P$      | Sheffield et al. (2006) |
| CHIRPS      | $P$      | Funk et al. (2014) |
| GPCC(v6)    | $P$      | Schneider et al. (2014) |
| TMPA-RT     | $P$      | Huffman et al. (2007, 2010) |
| SRB-PGF-PM  | ET       | Vinukollu et al. (2011a) |
| VIC         | ET       | Sheffield and Wood (2007) |
| ERA-interim | ET       | Simmons (2006) |
| MERRA       | ET       | Rienecker et al. (2011) |
| GLEAM       | ET       | Gonzalez Miralles et al. (2011) |
| SRB-CFSR-SEBS | ET   | Vinukollu et al. (2011a) |
| SRB-CFSR-PM | ET       | Vinukollu et al. (2011a) |
| SRB-CFSR-PT | ET       | Vinukollu et al. (2011a) |
| VIC         | $Q$      | Sheffield and Wood (2007) |
| VIC         | TWS      | Sheffield and Wood (2007) |
| GRACE       | TWS      | Landerer and Swenson (2012) |

### Table 5

Modified from Munier and Aires (2018). $P$ is precipitation, ET is evapotranspiration, $Q$ is runoff, and $\Delta$TWS is total water storage change.

| Data source | Variable | Reference(s) |
|-------------|----------|--------------|
| TMPA        | $P$      | Huffman et al. (2007) |
| CMORPH      | $P$      | Joyce et al. (2004) |
| NRL         | $P$      | Turk et al. (2010) |
| GPCP        | $P$      | Adler et al. (2003) |
| GLEAM       | ET       | Gonzalez Miralles et al. (2011) |
| MOD16       | ET       | Mu et al. (2007) |
| NTSG        | ET       | Zhang et al. (2010) |
| GRDC        | $Q$      | http://www.grdc.sr.unh.edu/ |
| CSR         | $\Delta$TWS | http://www2.csr.utexas.edu/grace/ |
| GFZ         | $\Delta$TWS | ftp://isdcftp.gfz-potsdam.de/grace/ |
| JPL         | $\Delta$TWS | https://grace.jpl.nasa.gov/data/get-data/ |
| GRGS        | $\Delta$TWS | https://grace.obs-mip.fr/ |
assigned the basins into one of four classes. Then the closure correction model is calibrated to each basin using the corresponding CIC class, and it optimizes budget closure for the fluxes one at the time. While no absolute values are reported, the authors describe how this novel method reduced non-closure residuals by 26% of the value it would have using constrained Kalman filter post-processing.

In the above-mentioned studies, there is a methodological consensus to use simple weighting when integrating data from various sources. This is in good agreement with Aires (2014) who compared the performance of different integration methods, and reported that simple weighting is the most suitable one. Simple weighting offers a straightforward formulation, and more elaborate methods do not offer enough improvement on results to justify the increased complexity they carry along. The assumption for the simple weighting method is that the errors associated with the different products are Gaussian (zero-mean) and independent. However, there might be cases that this assumption may not hold, especially for gauge-based data products, and the dependence among products will cause an underestimation of the error associated with the integrated data set. The combined data set for a given component of the global water cycle ($P$, $ET$, $Q$, or $\Delta TWS$) is equal to:

$$x = \sum_{i=1}^{n} w_i x_i$$

(4)

where $x$ is the combined data set for the single component of the global water cycle being integrated, $x_1$, $x_2$, $x_3$, ..., $x_n$ are the different products considered, $w_i$ is the associated weight of product $x_i$ and is defined as:

$$w_i = \frac{(\bar{x} - x_i)^{-2}}{\sum_{j=1}^{n} (\bar{x} - x_j)^{-2}}$$

(5)

where $\bar{x}$ is the arithmetic mean of the $n$ data products considered, and $(\bar{x} - x_i)^2$ is defined as the error variance. That is to say, the weight associated to each product is proportional to the inverse of its error variance. Finally, the error associated to the combined data set $x$ is:

$$e_x = \frac{1}{\sum_{i=1}^{n} (\bar{x} - x_i)^{-2}}$$

(6)

### 3 Status Quo et Verisimile Futurum

It might have been noticed that the chronology of global water cycle quantification does not follow a linear timeline. The epochs started at different points in time without replacing the one before. Each epoch did not only continue to develop, but just like global water cycle components, they interacted with each other in a feedback loop. A convergence point is the fact that model simulations and satellite-based measurements depend upon ground observations either for validation or calibration. The latest epoch, the age of big data, does not intend to merge all the previous into one, but to exploit the various data sources stemming from them to generate the most accurate estimates possible. Therefore, we should keep working on the continuous improvement of ground measurements, model simulations, and satellite observations, which will inherently improve their integration. Abbott et al. (2019) provided one of the most recent descriptions of the global water cycle. Analogously to
Oki and Kanae (2006), the authors did not quantify the global water cycle components themselves but synthesized data from the literature. The authors did not aim to quantify the components of the global water cycle but to assess its correct representation. To do so, they compiled over 464 diagrams (e.g., Fig. 3) and estimates from over 80 studies. Human interaction was absent in approximately 85% of the diagrams, highlighting the omission of the non-negligible anthropogenic component of the water cycle. In addition, the authors stress the necessity to represent seasonal and interannual variability of the global water cycle fluxes and storages in diagrams because the general understanding of temporal variability of the global water cycle is absent in the collective consciousness (Cardak 2009). Within the studies, not all of them reported estimates for all components of the global water cycle. The synthesis resulted in the following estimates: overland precipitation $110 \times 10^3 \text{ km}^3/\text{year}$, evapotranspiration $69 \times 10^3 \text{ km}^3/\text{year}$, and runoff $46 \times 10^3 \text{ km}^3/\text{year}$; over oceans, precipitation $380 \times 10^3 \text{ km}^3/\text{year}$ and evaporation $420 \times 10^3 \text{ km}^3/\text{year}$.

Herein, building upon the previous compendium done by Baumgartner and Reichel (1972), we surveyed the recent literature, and to the best of our knowledge, compiled all the different estimates of global water cycle components available in peer review journals that at least report the average annual fluxes for the terrestrial or oceanic water cycle (Table 6). Since 2010 it has become more common for studies to address only the terrestrial water cycle (e.g., Van der Ent et al. 2010; Haddeland et al. 2011; Jasechko et al. 2013; Zhang et al. 2018). On the other hand, ocean salinity measurements are being exploited to study the oceanic branch of the water cycle (Durack 2015), yet there are very few studies focusing solely on the oceanic water cycle (e.g., Syed et al. 2010; Robertson et al. 2014; Gutenstein et al. 2021). Inspecting the chronology of global water cycle flux annual average estimates over land and over oceans, it is safe to state that uncertainty estimates associated with fluxes over oceans is higher than that over land (Figs. 4(a) and 4(b)). Comparing...
the standard deviation and the interquartile range of the estimates from Oki (1999) onward with the ones from all the estimates (1905-2019), we can affirm that variability has diminished in recent years (Figs. 4(c) and 4(d)). Moreover, the variability of ocean precipitation and evaporation was reduced by more than 70%. These findings advocate that the consistency of the estimates has been improved.

Despite our survey compiling estimates available in the literature rather than presenting a more “traditional” estimates’ time series, we observe an increasing trend in the global water cycle fluxes annual average as the year of publication progresses (Fig. 5). We should remark that the years listed correspond to the publication date and do not necessarily reflect on the data sets’ reference period used by the authors therein. Hence, our observations are of qualitative and not quantitative character. An increasing trend in global water cycle fluxes, commonly referred to as intensification, is often attributed to global warming; however, the processes that drive the global water cycle’s response are yet to be fully understood (Allan et al. 2020). Take note that these estimates are global and do not describe changes in the water cycle at different smaller scales. On top of that, we should not assess these results conclusively because most studies used different data sources and different

| Author                   | \(P_L\) | ET  | Q   | \(P_O\) | E   | \(P_{TOT}\) | \(E_{TOT}\) |
|--------------------------|--------|-----|-----|--------|-----|------------|------------|
| Manabe (1969)            | 93.4   | 69.5| 23.9| 359.3  | 429 | 452.7      | 498.5      |
| Baumgartner and Reichel (1972) | 100   | 65  | 35  | 383    | 418 | 483        | 483        |
| Falkenmark and Lindh (1974) | 114   | 73  | 41  | 412    | 453 | 526        | 526        |
| Speidel and Agnew (1982)  | 111    | 71  | 39.7| 385    | 425 | 496        | 496        |
| NRC (1986)                | 107    | 71  | 36  | 398    | 434 | 505        | 505        |
| Van der Leeden (1990)     | 100    | 70  | 39.6| 320    | 350 | 420        | 420        |
| Gleick (1993)             | 119    | 72  | 47  | 458    | 505 | 577        | 577        |
| Schmitt (1995)            | 110.4  | 69.4| 41  | 384.7  | 425.7| 495.1      | 495.1      |
| Shiklomanov (1998)        | 119    | 74.2| 42.7| 458    | 502.8| 577        | 577        |
| Oki (1999)                | 115    | 75  | 40  | 391    | 431 | 506        | 506        |
| Oki and Kanae (2006)      | 111    | 65.5| 45.5| 391    | 436.5| 502        | 502        |
| Schlosser and Houser (2007)| 103.5 | 63  | 40.5| 376    | 417 | 479.5      | 480        |
| Trenberth et al. (2007)   | 113    | 73  | 40  | 373    | 413 | 486        | 486        |
| Lim and Roderick (2009)   | 113    | 78.8| 34.1| 417.7  | 451.8| 530.7      | 530.8      |
| Syed et al. (2010)        |        |     |     |        |     | 36.1       | 409.2      |
| Van der Ent et al. (2010) | 117    | 82  | 35  |        |     |            |            |
| Chapin III et al. (2011)  | 110    | 71  | 40  | 385    | 425 | 495        | 496        |
| Haddeland et al. (2011)   | 126    | 72.5| 54  |        |     |            |            |
| Trenberth et al. (2011)   | 114    | 74  | 40  | 386    | 426 | 500        | 500        |
| Jasechko et al. (2013)    | 110    | 72.7| 37.3|        |     |            |            |
| Durack (2015)             | 110.4  | 85.1| 39.4| 384.7  | 410 | 495.1      | 495.1      |
| Rodell et al. (2015)      | 116.5  | 70.6| 45.9| 403.5  | 449.5| 520        | 520.1      |
| Schneider et al. (2017)   | 117.6  | 71.8| 45.8| 386    | 431.8| 503.6      | 503.6      |
| Zhang et al. (2018)       | 114.7  | 68  | 46.6|        |     |            |            |
| Abbott et al. (2019)      | 110    | 69  | 46  | 380    | 420 | 490        | 489        |
Fig. 4 Probability density distribution of global water cycle fluxes from Tables 1 and 6. The dashed line represents the mean value of each flux. (a) Overland fluxes where $P$ is precipitation, $ET$ is evapotranspiration, and $Q$ is runoff. (b) Over ocean fluxes where $P$ is precipitation and $E$ is evaporation. (c) Same as (a) but only for Table 6. (d) Same as (b) but only for Table 6.

Fig. 5 Chronological estimates of global water cycle fluxes over land in $10^3 \text{km}^3/\text{year}$. $P$ is precipitation, $ET$ is evapotranspiration, and $Q$ is runoff. The years listed correspond to the publication date and do not necessarily reflect the data sets’ reference period used by the authors.
methods at different development stages, as discussed in the previous section. For example, if we were to look only at Table 6 entries in Fig. 6 (from Baumgartner and Reichel (1972) onward), we would not be able to clearly discriminate a trend from the variability present.

**Fig. 6** Chronological estimates of global water cycle fluxes over oceans in $10^4$ km$^3$/year. $P$ is precipitation and $E$ is evaporation. The years listed correspond to the publication date and do not necessarily reflect the data sets’ reference period used by the authors.

**Fig. 7** Chronological estimates of the evaporative index. This is defined as the ratio between evapotranspiration and precipitation overland ($ET/P$). The years listed correspond to the publication date and do not necessarily reflect the data sets’ reference period used by the authors.
in those estimates. Moreover, suppose we were to omit the estimates reported between Van der Leeden (1990) and Shiklomanov (1998), there seem to be minor oscillations around an overall flat trend, attesting the narrative is dependent on the data being observed. Latch onto the ratio between evapotranspiration and precipitation over land, also known as the Evaporative Index ($\text{ET}/P$; Fig. 7), and it is interesting to see how, despite some clear multi-annual oscillations, there seems to be no sharp trend. The Evaporative Index is the fraction of available water consumed by evapotranspiration (Budyko 1974), and assuming no significant change in total water storage, its residual ($1 - \text{ET}/P$) could be inferred as the fraction that turns into available freshwater. This, at least on paper, would suggest global freshwater availability has not diminished on average.

Through the previous sections, we have described how our understanding of the global water cycle has been evolving over the years as we exploit novel technologies and methods to quantify the components of the global water cycle more accurately. Accordingly, to assess future changes in the global water cycle and its response to global warming, we should study both past shifts documented in observational records and possible changes predicted by model simulations. While there are inherent fluctuations in the global water cycle, some of them are driven by natural phenomena like variations in the Sun and volcanic eruptions (e.g., the year without a summer; Stommel and Stommel 1979), and anthropogenic activities. The latter exerts a continuously increasing influence directly via interference with land surface and water consumption, and indirectly via greenhouse gases and aerosols emissions (Abbott et al. 2019). The nature of the driver and the spatial scale they exercise domain over alter key water cycle characteristics, e.g., precipitation frequency, intensity, or duration (Pendergrass and Hartmann 2014).

Concurrently, model simulations predicted that global mean precipitation would rise in response to CO$_2$ doubling (Mitchell et al. 1987). The relationship between climate and water cycle caught the attention of both climatic and hydrological communities (Chahine 1992b; Loaiciga et al. 1996). Models and the relationship between climate and water cycle are continuously evaluated in the Assessment Reports of the Intergovernmental Panel on Climate Change (IPCC; Collins et al. 2013; Flato et al. 2014). The Clausius–Clapeyron expression for the saturation vapor pressure establishes that at temperatures typical of the lower troposphere, the water holding capacity increases by about 7% for each 1K increase in temperature. It is safe to assume that an increase in lower-tropospheric water vapor will lead to a chain reaction affecting the entire global water cycle. The poorly understood response of the global water cycle resulted in two main hypotheses: the “changing character of precipitation” and the “dry gets drier, wet gets wetter”. The former shows that the increase in global mean precipitation will be unevenly distributed in precipitation events (Trenberth et al. 2003). Heavy or extreme rainfall will become more frequent, while light or moderate precipitation will decline. The latter suggests that the increased vertical gradient of atmospheric water vapor would offset atmospheric wind convergence in the tropics making wet regions wetter and dry regions drier (Roderick et al. 2014). Both hypotheses are today under vigorous debate (Held and Soden 2006; Seager et al. 2010; O’Gorman and Muller 2010; Greve et al. 2014; Roderick et al. 2014; Byrne and O’Gorman 2015; Kumar et al. 2015; Salzmann 2016; Skliris et al. 2016; Wang et al. 2017; Markonis et al. 2019; Allan et al. 2020).

Global precipitation and evapotranspiration, however, are further associated with Earth’s energy budget rather than the Clausius–Clapeyron equation (O’Gorman et al. 2012; Roderick et al. 2014). Model simulations report that in response to global warming, global precipitation and evapotranspiration, independently of climate forcing, would increase constrained by Earth’s energy budget to an expected rate between 2-3%/K (Samset et al. 2018).
Precipitation’s response to global warming, also known as apparent hydrological sensitivity, comprises a fast reaction proportional to radiative forcings and a slow temperature-dependent response to the radiative forcings (Bala et al. 2010). Across multiple model simulations, precipitation increases with global warming are generally suppressed over land compared to the global mean (0.8-2.4%/K vs. 2.3-2.7%/K), a behavior partly expected due to limitations on moisture convergence product of the more significant warming over land than oceans (Richardson et al. 2018). Considering that global precipitation’s response to global warming is slower than the response of atmospheric water vapor, atmospheric water vapor lifetime must increase to reconcile these different response rates (Hodnebrog et al. 2019). By doing so, regional characteristics of precipitation such as seasonal duration, frequency, and intensity are altered (Pendergrass 2018).

As atmospheric water vapor content increases and its lifetime prolongs, the increased horizontal moisture transport induces an intensification of precipitation minus evapotranspiration patterns. Over the continents, precipitation minus evapotranspiration is positive and accounts for the freshwater flux from the atmosphere to the surface, whereas over the ocean, precipitation minus evaporation is negative and represents the freshwater flux from the oceans to the atmosphere. In dry regions, where evapotranspiration is constrained by water availability, changes in precipitation minus evapotranspiration will be mainly credited to precipitation changes (Roderick et al. 2014). Precipitation minus evapotranspiration over land can be negative during dry seasons or extended drought periods (Kumar et al. 2015). Given that evapotranspiration is a compound flux of evaporation and transpiration, the response of vegetation to global warming and increased CO₂ concentrations in the atmosphere will also determine the characteristics of regional precipitation minus evapotranspiration patterns. Besides, over land, we cannot neglect anthropogenic activities like irrigation, land-use change, deforestation, urbanization, and water withdrawals, among others that directly alter precipitation minus evapotranspiration regimes. On this account, we can expect several factors like topography, atmospheric circulation, anthropogenic tampering, and vegetation response to generate different and complex water cycle responses to global warming.

4 Discussion and Conclusions

Early attempts to quantify the global water cycle date back to the early 1900s (Brückner 1905). To date, despite tremendous advances in terms of data and technology, accuracy regarding the components of the global water cycle has not increased accordingly. Ultimately, unquantified uncertainties on remote sensing satellite products (Sheffield et al. 2009), limitations of climate model simulations (Trenberth et al. 2011), short and heterogeneous observational data records (Schneider et al. 2017), and the natural fluctuations of water cycle components Markonis et al. (2018) keep the understanding of the global water cycle ambiguous and human contribution unattributed. Within the twenty-first century, the paradigm of quantifying the global water cycle has been shifting from identifying the best data source per water cycle component into developing the best way to integrate data from various sources (Aires 2014). Therefore, proper statistical tools for uncertainty quantification (Papalexiou 2018), robust downscaling/disaggregation (Papalexiou et al. 2018), along with analysis over multiple scales (Hanel et al. 2017; Markonis et al. 2021) are required.

The quest for accurate global water cycle quantification gave birth to the Global Energy and Water Exchanges (GEWEX) project. The GEWEX project, formerly known as the...
Global Energy and Water Cycle Experiment, started in 1990 and is dedicated to studying the Earth’s water and energy cycles (Chahine 1992a). GEWEX established a channel for international research collaboration through different panels, meetings, and projects. Among the most renowned outcomes, we could mention the work of Trenberth et al. (2007), which we further discussed in Sect. 2.3. Speaking of data sets and modeling improvements, GEWEX overlooks eight continental-scale experiments, GEWEX Americas Prediction Project (GAPP; Lawford 1999), Baltic Sea Experiment (BALTEx; Raschke et al. 1998, 2001), GEWEX Asian Monsoon Experiment (GAME; Yasunari 1994), Large Scale Biosphere Atmosphere Experiment in Amazonia (LBA; Marengo 2005), Mackenzie GEWEX Study (MAGS; Stewart et al. 1998), La Plata Basin (LPB; Cavalcanti et al. 2015), The African Monsoon Multidisciplinary Analysis (AMMA; Redelsperger et al. 2006), and Murray-Darling Basin (MDB; Evans and McCabe 2010). Other than the logistic and political criteria, these sites were selected in order to collect data from different climate regimes to assess the global water cycle in a representative manner. The collaborative effort of the international teams involved improved the understanding of regional water balance and feedback processes. The data resulting from the continental-scale experiments are publicly available. Thus, they indirectly started to set up a scientific framework to quantify the global water cycle and close its budget; the latter was obtained within a 10% non-closure tolerance.

As a rule of thumb, ground observations are regarded as the closest measurements to the actual values. However, it is evident that ground observations suffer from systematic errors, mainly because of different environmental and meteorological conditions. For example, the precipitation phase, evaporation from the gauge, and wind drift induce precipitation undercatch on rain gauges (Fuchs et al. 2001). The scientific community is aware that good quality ground observations data represent a cornerstone to quantify the global water cycle, yet we are still unable to deploy a homogeneously distributed global network. Spatial coverage of the Global Precipitation Climatology Centre (GPCC), currently the most comprehensive gauge network available, represents only about 1% of the Earth’s surface (assuming no overlap of a 5 km radius per gauge) (Kidd et al. 2017). One of the main reasons behind the struggle to deploy a comprehensive network is that ground stations, and ergo observational data records, are extremely geopolitically dependent (Kibler et al. 2014). In addition, deploying dense monitoring networks unavoidably imply high operational and maintenance costs and spatial requirements (Saltikoff et al. 2017). Consequently, in many developing countries, ground observational records, if available, tend to have multiple temporal discontinuities or non-standardized data quality check protocols (Walker et al. 2016). Different techniques have been used to fill spatiotemporal gaps in observational records. Reconstructing these time series could be achieved using several tools that could be grouped in the following, self-contained infilling (Kemp et al. 1983; Pappas et al. 2014), spatial interpolation (Shepard 1968; Young 1992; Eischeid et al. 1995, 2000), quantile mapping (Simolo et al. 2010; Newman et al. 2015, 2019; Devi et al. 2019), and machine learning methods (Dastorani et al. 2010; Wambua et al. 2016). On a different front, there is an opportunity to use data from amateur networks and the internet of things (i.e., big data with large uncertainty) to enhance spatial coverage and spatiotemporal resolution of traditional ground stations via crowdsourcing and the internet. Needless to say, appropriate validation and quality control procedures must be adopted and implemented to fully exploit the potential to provide a valuable source of high spatiotemporal resolution real-time data (Muller et al. 2015). As of now, however, the lack of adequate ground-based data and station networks still hampers our ability to monitor the water cycle robustly.
Model simulations can generate past climate, current climate, and climate projections data. Moreover, they are capable to switch anthropogenic forcing on precipitation on and off, while the decoupling of natural and anthropogenic forcing remains a challenge on observational data (Allen and Ingram 2002). However, compared to observational data, various characteristics of global water cycle fluxes, and precipitation, in particular, hold uncertainty (Prein and Pendergrass 2019). The simulated projections’ temporal length appears to influence precipitation trends, e.g., variability in precipitation estimates are indistinguishable from the noise of internal variability in 20-year or longer runs (Hawkins et al. 2016). Specifications differ from model to model, but in general, recycling of moisture is too large, and the lifetime of moisture is too short across most models, inducing premature precipitation (Trenberth et al. 2011). Also, inaccurate convective parameterizations evidenced that models overestimate precipitation frequency and underestimate its intensity (Trenberth et al. 2017). Analysis focusing on convective precipitation highlighted that its model representation is strongly dependent on the model depiction of cloud microphysics and cloud spatiotemporal variability (Zhao et al. 2016). There is a threefold spread in mean precipitation change with global temperature ($1 - 3\% K^{-1}$), and model simulations showed that there is a correlation between an increase in precipitation extremes and an increase in model resolution, precipitation extremes at the same time showed an anticorrelation with changes in light-moderate precipitation (Thackeray et al. 2018). Furthermore, both the spread and magnitude of change in extreme precipitation vastly exceed those of mean precipitation ($4 - 10\% K^{-1}$) (Kharin et al. 2013). Last but not least, despite the known link between the energy and water global cycles, solar dimming and brightening (the effect of aerosols) are not well represented or sometimes not even considered at all in models; thus, model simulations fail to reproduce variability in the global water cycle intensity (Wild and Liepert 2010).

Satellite remote sensing observations, like models, are limited by their design. Both the orbit they follow and the instrument type (i.e., active or passive) influence global water cycle components’ monitoring. The satellite’s orbit would delimit its spatiotemporal resolution or coverage. In general, a satellite with high spatial resolution comes with coarse temporal resolution and vice-versa, and high spatiotemporal resolution comes with limited coverage. It has been shown that estimates from active sensors can considerably vary from passive sensor ones, yet they complement each other (Petković and Kummerow 2017). In addition, similarly to ground observations, satellite remote sensing has to deal with different meteorological conditions. For instance, satellite-based global water cycle estimates accuracy is affected by cloud-top reflectance and thermal radiance, making uncertainty larger during the winter or in dry climates (Kummerow et al. 2004). While satellites can monitor the water cycle at the global scale and cover regions inaccessible by ground stations, they still have to tackle the problems involved in complex topography regions. In some cases, the relative biases reach as much as 300% for precipitation estimates (Fekete et al. 2004). Further complications arise from the unique spatiotemporal characteristics of different remotely sensed global water cycle components, making it impossible to assess the water budget without some sort of prior downscaling or integration (Sheffield et al. 2018). E.g., TMPA’s precipitation at 25 km every three hours (Huffman et al. 2007), MODIS’ evapotranspiration at 1 km daily (Mu et al. 2007), and GRACE’s total water storage at $\sim 500$ km every 30 days (Tapley et al. 2004). Despite all the issues mentioned above, satellite products continue to be the most widely used sources to monitor global water cycle components due to their comprehensive spatial coverage.

It is clear that no global water cycle data source is without fail, and in some cases, one data source strengths cover for other weaknesses. It is typical for satellite-based measurements and model simulations to use ground-based data for validation, calibration, and
enhancement purposes. Along the same line, model simulations additionally assimilate satellite-based observations for the above plus for reanalysis. In contrast to the top-down estimation approach used in satellite remote sensing, a bottom-up approach, referred to as reverse hydrology, has been recently proposed (Ciabatta et al. 2020). A physically based selection of surface explanatory variables, like soil moisture, vegetation cover, and topography, is expected to preserve process dynamics and interlinkages within data sets that remain unresolved in conventional statistical downscaling bias-correction methods (Wehbe et al. 2020). It is of utmost importance that the research community strives to improve ground observations, model simulations, and satellite remote sensing measurements individually because more accurate and robust individual data sources will subsequently refine the outcome of multi-source integration. Hence, a three-way integration of satellite remote sensing, model reanalysis, and ground-based measurements, as discussed in Sect. 2.4, is widely acknowledged as the current best practice, particularly when leveraging machine learning tools to handle large data sets.

Acknowledgements This work was supported by the Faculty of Environmental Sciences, Czech University of Life Sciences Prague internal Grant 2020B0001 “A multiscale framework for data analysis of global precipitation”. The data compiled herein and the R code for the figures are publicly available at https://github.com/MiRoVaGo/chronology_gwc.

Declarations

Conflict of interest The authors declare that they have no conflict of interest.

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