Algebraic structures on parallel M2-branes

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Abstract

In the course of closing supersymmetry on parallel M2 branes up to a gauge transformation, following the suggestion in [hep-th/0611108] of incorporating a gauge field which only has topological degrees of freedom, we are led to assume a certain algebraic structure for the low energy theory supposedly living on parallel M2 branes.
1 Introduction

The low-energy theory living on a single M2 brane was derived in [1], [2]. This theory can also be derived from the Yang-Mills action living on a single D2 brane by dualizing one of the scalar fields [3].

In this Letter we investigate the ‘non-abelian’ generalization of this M2 brane theory, much inspired by the work of Bagger and Lambert [4]. More specifically, we ask what requirements come from supersymmetry. Our starting point is to assume that supersymmetry can be realized on some kind of ‘fields’ with the usual Lorentz index structure. We do not need to know much about the internal structure to be able to analyze the supersymmetry transformations. All we in essence need, is usual gamma matrix algebra.

We put non-abelian in quotation marks because the fields will not take values in the adjoint representation of a non-abelian Lie algebra. We also put the word ‘fields’ in quotation marks because it is not clear that these would be just ordinary fields. Perhaps they are ‘non-abelian loops’.

We thus assume there are some kind of non-commuting ‘fields’ that take values in some algebra, and that there are certain ways of multiplying together such fields to get a new element in the algebra. We also require that these fields are such that they reduce to the ordinary eight scalar fields plus their supersymmetric partners in the abelian case.

Dimensional analysis suggests there is in the supersymmetry variations, products of two as well as of three fields. It is of course desirable that all products of our fields are such that they close on some internal algebra. The way we do that is by making the minimal assumption that there is a multiplication of two fields which belong to some set of fields, that we denote as \( \mathcal{A} \), such that the product is in some set \( \mathcal{B} \) that need not be the same as \( \mathcal{A} \), though a product of three elements in \( \mathcal{A} \) must yield back an element in \( \mathcal{A} \). We introduce three different kinds of multiplications to be used according to whether the elements being multiplied belong to \( \mathcal{A} \) or \( \mathcal{B} \). Then we see what requirements closure of the supersymmetry transformations impose on these various multiplications.

We end this Letter by proposing a rather explicit, though maybe drastic, way of realizing these multiplication operations. For this construction we abandon the concept of ordinary fields and instead assume the fields are loops in transverse space.

2 The abelian cases

The abelian super Yang-Mills SUSY transformations can be derived by dimensionally reducing \( 1 + 9 \) dimensional super Yang-Mills to \( 1 + 2 \) dimensions. The ten-dimensional spinor is Majorana-Weyl,

\[ \Gamma^{(10)} \chi = \chi \]  

Since we wish to prepare the ground for an up-lift to M-theory, it is desirable to look for an embedding of \( SO(1, 9) \) into \( SO(1, 10) \) in which \( \Gamma^{(10)} \) is the eleventh gamma matrix. We denote the gamma matrices as \( \Gamma^M (M = 0, ..., 9, 10) \). In

\footnote{Since the gauge field would be in the adjoint, all other fields would also be in the adjoint due to supersymmetry.}
M-theory, the spinor can obviously just be Majorana. But the presence of an $M2$ brane breaks the Lorentz symmetry as $SO(1,10) \rightarrow SO(1,2) \times SO(8)$, and we can have a Weyl spinor of $SO(8)$. Let us denote by

$$\Gamma = \Gamma^{3..9(10)}$$

the chirality matrix of $SO(8)$. Half the supersymmetry is broken by the $M2$ brane. Let us choose a convention where the unbroken supersymmetry parameters are Weyl

$$\Gamma \epsilon = \epsilon$$

The broken supersymmetries gets manifested as goldstinos,

$$\Gamma \psi = -\psi$$

living on the world-volume of the $M2$ brane. The broken translations become eight goldstone scalar fields, $\phi^A$ on the $M2$ brane. The unbroken supersymmetries relate the bosonic and fermions degrees of freedom. The Yang-Mills supersymmetry transformations, written in terms of such spinors, is given by

$$\delta \phi^a = i \bar{\epsilon} \Gamma^a \psi$$
$$\delta F_{\mu\nu} = -2i \bar{\epsilon} \Gamma_{(10)} \partial_{(10)} \psi$$
$$\delta \psi = \frac{1}{2} F_{\mu\nu} \Gamma^{\mu\nu} \Gamma^{(10)} \epsilon + \partial_{\mu} \phi^a \Gamma^a \Gamma \epsilon$$

Let us now dualize the gauge field to a scalar field

$$\partial_\mu \phi^{(10)} = \frac{R}{2} \epsilon_{\mu\nu\rho} F^{\nu\rho}$$

We then get (if we also replace $\phi^a$ by the reduced field $R\phi^a$ and $\psi$ by the reduced field $R\psi$ respectively)

$$\delta \psi = \partial_\mu \phi^{(10)} \Gamma^\mu \Gamma^{(10)} \epsilon + \partial_{\mu} \phi^a \Gamma^a \Gamma \epsilon$$

and

$$\delta \partial_\mu \phi^{(10)} = 2i \bar{\epsilon} \Gamma_{\mu\nu} \Gamma^{(10)} \partial^\nu \psi$$

To proceed we must use the equation of motion

$$\Gamma^\nu \partial_\nu \psi = 0$$

Then we can use $\Gamma_{\mu\nu} = -\eta_{\mu\nu} + \Gamma_\mu \Gamma_\nu$, and write this as

$$\delta \partial_{\mu} \phi^{(10)} = 2i \bar{\epsilon} \Gamma^{(10)} \partial_{\mu} \psi$$

This corresponds to equating $\phi^{(10)}$ with the dual gauge potential. The integral of a dual potential over a closed loop is well-defined only modulo $2\pi$, and since we are in three dimensions, the dual potential is a zero-form and integration of a zero-form should mean evaluation of that zero form at a point, suggesting this scalar would be compact,

$$\phi^{(10)} \sim \phi^{(10)} + 2\pi R.$$
This way we have reached the \( SO(8) \) covariant SUSY transformations of an M2 brane,

\[
\begin{align*}
\delta \phi^A &= i \bar{\epsilon} \Gamma^A \psi \\
\delta \psi &= \partial_\mu \phi^A \Gamma^\mu \Gamma_A \epsilon
\end{align*}
\]  

(12)

In conformal four-dimensional Yang-Mills theory we have the length dimensions

\[
(A_\mu, \phi^a, \psi, \epsilon) = (-1, -1, -\frac{3}{2}, \frac{1}{2})
\]  

(13)

Reduction to three dimensions, does not change these dimensions. But we rather get a dimensionful coupling constant.

The theory living on an M2 brane is conformal. So the fields acquire the length dimensions

\[
(A_\mu, \phi^A, \psi, \epsilon) = \left(-1, -\frac{1}{2}, -1, \frac{1}{2}\right)
\]  

(14)

Intuitively one may perhaps think of this as that the Goldstone modes get their length-dimensions increased by \( \frac{1}{2} \) as a result of an integration over one compact transverse dimension.\(^3\) But the gauge field does not. It will become even more apparent that the gauge field is to be treated very differently from the scalars and fermions when we turn to the non-abelian case. As we will see, the gauge field will be much like an ordinary field, taking values in an algebra \( B \) that closes on itself, while the scalars and fermions will belong to a different set \( A \) that is like the square root of \( B \).

### 3 Non-abelian generalization

We will assume the algebra is a semi-direct product of two distinct sets, that we denote as \( A \) and \( B \) respectively. We introduce three different kinds of products,

\[
\begin{align*}
\langle \cdot, \cdot \rangle & : A \times A \to B \\
(\cdot, \cdot) & : A \times B \to A \\
[\cdot, \cdot] & : B \times B \to B
\end{align*}
\]  

(15)

We get the familiar algebraic structure of Yang-Mills theory if we assume that \( A = B \) is an ordinary Lie algebra, and that all these multiplications are identical.

We will assume the products have the following properties

\[
\begin{align*}
\langle \alpha, \beta \rangle &= -\langle \beta, \alpha \rangle \\
(A, a) &= \varepsilon(\alpha, A) \\
[A, B] &= -[B, A],
\end{align*}
\]  

(16)

the ‘associative’ property

\[
(\alpha, \langle \beta, \gamma \rangle) = \varepsilon(\langle \alpha, \beta \rangle, \gamma)
\]  

(17)

\(^3\)The Einstein metric (or the M-theory metric) \( G \) is related to the string metric \( g \) by the Weyl rescaling \( g = G/R \) where \( R \) is the radius of the M-theory circle as measured by the Einstein metric. In the string metric a transverse dimension has length dimension 1, and scalars on the D-brane are rescaled by one power of \( \alpha' \) so as to get dimension \( -1 \). In Einstein metric transverse dimension gets dimension \( 1/2 \) and scalars on the brane get dimension \( -1/2 \).
though we let $\varepsilon$ be an arbitrary sign factor for the time being. We also assume these products are subject to the following Jacobi identities,

$$\langle (A, \alpha), \beta \rangle - \langle (A, \beta), \alpha \rangle = [A, \langle \alpha, \beta \rangle]$$  (18)  

$$((\alpha, A), B) - ((\alpha, B), A) = -\varepsilon(\alpha, [A, B])$$  (19)  

$$[[A, B], C] - [[A, C], B] = [A, [B, C]].$$  (20)

These will, among other things, be crucial when verifying that the gauge transformations close into a gauge algebra, and when verifying equations of motion are gauge invariant.

It is of course not obvious these assumptions are consistent with each other. Either one may try and look for inconsistencies in any of the Jacobi identities and the other assumptions. But there appears to be a simpler way of checking consistency of these assumptions. Namely by noting there is an explicit, finite-dimensional realization of this algebra. We then take as $A$ the set of gamma matrices $\gamma^i$ in four dimensions (as suggested by scalar fields taking values in a fuzzy three sphere, [7]), and as $B$ the set of $\gamma^{ij}$. We then define the products as $\langle \gamma^i, \gamma^j \rangle = [\gamma^i, \gamma^j] \in A$, $((\gamma^i, \gamma^j), \gamma^k) = -\varepsilon(\gamma^i, \gamma^{jk}) \in A$ and $[\gamma^{ij}, \gamma^{kl}] = [\gamma^i, [\gamma^j, \gamma^k]] \in B$. In the right-hand sides, the brackets denote usual commutators.

We note that $[\cdot, \cdot] : B \to B$ follow as a consequence of the Lorentz algebra. One may also verify that the associativity property and the Jacobi identities are satisfied. It is clear though, that this realization, nor any fuzzy three-sphere generalization of the gamma-matrices, can reasonably contain all information of the gauge group that is supposed to appear when we reduce to D2 branes. So we should look for a larger realization of this algebra.

We introduce a gauge covariant derivative $D_\mu = \partial_\mu + A_\mu$ as usual. Acting with this derivative on an element in either $A$ or $B$, we should get back an element in the same set. Taking two derivatives we should still end up with an element in the same set as we started with. Hence $D_\mu$ should be an operator in $B$. In particular we must take $A_\mu \in B$.

Gauge variations act as

$$\delta_\Lambda A_\mu = -\varepsilon D_\mu \Lambda$$  

$$\delta_\Lambda \phi^A = (\phi^A, \Lambda)$$  

$$\delta_\Lambda \psi = (\psi, \Lambda)$$  (21)

and they form a closed gauge algebra. To see that, we compute

$$[\delta_{\Lambda'}, \delta_\Lambda] A_\mu = -\varepsilon ([\delta_{\Lambda'}, A_\mu, \Lambda] - [\delta_\Lambda A_\mu, \Lambda'])$$  

$$= [D_{\mu} \Lambda', \Lambda] - [D_{\mu} \Lambda, \Lambda'] = D_{\mu} [\Lambda', \Lambda],$$  (22)

and

$$[\delta_{\Lambda'}, \delta_\Lambda] \phi = ((\phi, \Lambda'), \Lambda) - ((\phi, \Lambda), \Lambda')$$  

$$= -\varepsilon (\phi, [\Lambda', \Lambda])$$  (23)

from which we deduce the gauge algebra

$$[\delta_{\Lambda'}, \delta_\Lambda] = -\varepsilon \delta_{[\Lambda', \Lambda]}.$$  (24)
The strange sign factor in the gauge variation is necessary in order for \(D_\mu \phi\) to transform covariantly,

\[
\begin{align*}
\delta_\Lambda (D_\mu \phi) &= (\delta_\Lambda A_\mu, \phi) + D_\mu \delta_\Lambda \phi \\
&= -\varepsilon (D_\mu \Lambda, \phi) + D_\mu (\phi, \Lambda) \\
&= (D_\mu \phi, \Lambda).
\end{align*}
\] (25)

Just as in the abelian case, we would like to dualize the Yang-Mills gauge field into a scalar field to get the theory on M2 branes. However this is unlikely the whole story in the non-abelian case – it seems not possible to derive the M2 brane theory this way. When we dualize the Yang-Mills gauge field it should mean it does no longer enter our equations after dualization. That suggests we should dualize the gauge field as follows,

\[
D_\mu^{NEW} \phi^{(10)} = \frac{R}{2} \epsilon^{\mu \nu \rho} F^{\nu \rho}_{OLD}
\] (26)

We do not want the Yang-Mills gauge field to occur at anywhere after dualization, so we have introduced a new gauge field that enters in the covariant derivative on the left-hand side.

In the sequel we drop the subscript \(NEW\), it always being understood that we use the new flat gauge field. It seems very unlikely we get the M2 theory by dualizing the Yang-Mills gauge field like this, but nevertheless we find this dualization useful.

The most general ansatz for the supersymmetry transformations, consistent with \(SO(1, 2) \times SO(8)\) symmetry and dimensional analysis, appears to be

\[
\begin{align*}
\delta \phi^A &= i \bar{\psi} \Gamma^A \psi \\
\delta A_\mu^A &= i \bar{\psi} \Gamma_\mu \Gamma^A \langle \psi, \phi^A \rangle \\
\delta \psi &= \gamma \Gamma^A D_\mu \phi^A + \beta \Gamma_{ABC} \epsilon \langle \phi^A, \langle \phi^B, \phi^C \rangle \rangle
\end{align*}
\] (27)

for some numerical coefficients \(\alpha, \beta, \gamma\), to be determined.

It is now clear why we required the Eqs (16), (17). We then find that

\[
\langle \phi^A, \langle \phi^B, \phi^C \rangle \rangle = \epsilon^2 \langle \phi^B, \langle \phi^C, \phi^A \rangle \rangle
\]

and

\[
\begin{align*}
\langle \phi^A, \langle \phi^B, \phi^C \rangle \rangle &= \epsilon (\langle \phi^A, \phi^B \rangle, \phi^C) \\
&= -\epsilon (\langle \phi^B, \phi^A \rangle, \phi^C) \\
&= -\epsilon^2 (\phi^B, \langle \phi^A, \phi^C \rangle)
\end{align*}
\] (28)

We now see that we can get the symmetries of \(\Gamma_{ABC}\) if and only if \(\epsilon^2 = 1\).

We notice that the field strength is absent in the variation of the fermions. If we assume the action for the gauge field being the Chern-Simons action \([5]\), then we should get source terms which are bilinears in the fermionic field when varying the gauge field in the gauge covariant derivatives. So the gauge field strength need not vanish, despite it contains no local physical degrees of freedom.

There appears to be no way of incorporating the field strength in \(\delta \psi\) consistent with dimensional analysis.

As in the abelian case, the term

\[
D_\mu \phi^{(10)} \Gamma^{(10)} \epsilon
\] (29)

arose from dualizing the corresponding term

\[
F_{\mu \nu} \Gamma^{\mu \nu} \Gamma^{(10)} \epsilon
\] (30)
in Yang-Mills theory. If we take the viewpoint that the gauge field is new, its transformation rule can not be derived from Yang-Mills theory. But dimensional analysis suggests this form. If we take the viewpoint that it is the flat piece of the Yang-Mills connection, it becomes suggestive that it does indeed reduce to the transformation rule of a gauge field if we compactify $\phi^{(10)}$.

Let us now turn to the issue of closure of supersymmetry.

### 3.1 The scalars

We begin by the scalars. We have

$$[\delta_\eta, \delta_\epsilon] \phi^A = \frac{-2i\gamma_\epsilon \Gamma^\mu \eta D_\mu \phi^A}{+ 6\beta i \epsilon \Gamma_{BCD} \eta (\phi^A, \langle \phi^B, \phi^C \rangle)}$$  \hspace{1cm} (31)

Since we have assumed that our brackets have a cyclic property, we can write the result as

$$[\delta_\eta, \delta_\epsilon] \phi^A = \frac{-2i\gamma_\epsilon \Gamma^\mu \eta D_\mu \phi^A + (\phi^A, \Lambda)}{+(\phi^A, \Lambda)}$$ \hspace{1cm} (32)

Here

$$\Lambda = 6i\beta \epsilon \Gamma_{AB} \eta (\phi^A, \phi^B)$$ \hspace{1cm} (33)

should be given the interpretation of a gauge parameter.

### 3.2 The gauge field

We compute

$$\alpha^{-1} \delta_\eta \delta_\epsilon A_\mu = i\epsilon \Gamma_\mu \Gamma_A (\delta_\eta \psi, \phi^A) + i\epsilon \Gamma_\mu \Gamma_A (\psi, \delta_\eta \phi^A)$$

$$= i\gamma \epsilon \Gamma_\mu \Gamma_A (\phi^A, \phi^A)$$

$$+ i\beta \epsilon \Gamma_\mu \Gamma_A \Gamma_{BCD} \eta (\phi^B, \langle \phi^C, \phi^D \rangle), \phi^A)$$

$$- \epsilon \Gamma_\mu \Gamma_A \psi \bar{\eta} \psi$$ \hspace{1cm} (34)

We note that, by applying the Jacobi identity,

$$\varepsilon ([\phi^A, \langle \phi^B, \phi^C \rangle], \phi^D)$$

$$= \varepsilon ([\phi^B, \phi^C], \phi^D)$$

$$= \varepsilon (\phi^A, \phi^B, \phi^C, \phi^D) = 0.$$ \hspace{1cm} (35)

Applying a Fierz rearrangement on the last term, we now get (on-shell)

$$[\delta_\eta, \delta_\epsilon] A_\mu = -2i\epsilon (\epsilon \Gamma^\epsilon \eta) F_{\kappa \mu} + D_\mu \Lambda$$ \hspace{1cm} (36)

We thus assume the equation of motion

$$F_{\mu \nu} = \alpha \epsilon_{\mu \nu \rho} (D^\rho \phi^A, \phi_A) + \frac{i \alpha}{2} \langle \bar{\psi}, \Gamma_{\mu \nu} \psi \rangle$$ \hspace{1cm} (37)

and the gauge parameter

$$\Lambda = i\alpha \epsilon \Gamma_{AB} \eta (\phi^A, \phi^B).$$ \hspace{1cm} (38)
3.3 The fermions

We now turn to the fermions:

\[
[\delta_\eta, \delta_\epsilon] \psi = i\gamma^\mu \Gamma_A (\epsilon \bar{\eta} - \eta \bar{\epsilon}) \Gamma^A D_\mu \psi \\
+ i\alpha \Gamma^A \Gamma_B (\psi, \phi^B) \Gamma_\mu (\psi, \phi^A) \\
+ 3i\beta \Gamma_{ABC} (\epsilon \bar{\eta} - \eta \bar{\epsilon}) \Gamma^A (\psi, \langle \phi^B, \phi^C \rangle) 
\] (39)

We now use Eq (17) and a Fierz rearrangement, derived in the appendix. We then get

\[
[\delta_\eta, \delta_\epsilon] \psi = -2i\gamma_1 (\epsilon \bar{\eta} D_\epsilon \psi \\
+ i(\epsilon \bar{\eta}) \Gamma^\mu \left( \gamma \Gamma^\mu D_\mu \psi + \frac{9}{4} \beta - \frac{1}{8} \alpha \epsilon \right) \Gamma_{AB} (\psi, \phi^A, \phi^B) \\
+ \frac{1}{4} i(\epsilon \bar{\eta} \Gamma^\mu \Gamma^\nu \Gamma^\rho \Gamma^\sigma \Gamma^A \Gamma^B \Gamma^C \Gamma_D \Gamma^E \Gamma^F \Gamma^G \Gamma^H \Gamma^I \Gamma^J \Gamma^K \Gamma^L \Gamma^M \Gamma^N \Gamma^O \Gamma^P \Gamma^Q \Gamma^R \Gamma^S \Gamma^T \Gamma^U \Gamma^V \Gamma^W \Gamma^X \Gamma^Y \Gamma^Z \Gamma^\Lambda) \\
- \frac{1}{16} i(\epsilon \bar{\eta} \Gamma^\mu \Gamma^\nu \Gamma^\rho \Gamma^\sigma \Gamma^A \Gamma^B \Gamma^C \Gamma_D \Gamma^E \Gamma^F \Gamma^G \Gamma^H \Gamma^I \Gamma^J \Gamma^K \Gamma^L \Gamma^M \Gamma^N \Gamma^O \Gamma^P \Gamma^Q \Gamma^R \Gamma^S \Gamma^T \Gamma^U \Gamma^V \Gamma^W \Gamma^X \Gamma^Y \Gamma^Z \Gamma^\Lambda) \\
\] (40)

We now see that, by choosing

\[
6\beta - \alpha \gamma = 0 \\
6\beta + \alpha \epsilon = 0 
\] (41)

(The first equation is required from coupling the scalar to the gauge field) we get closure on the fermionic equation of motion

\[
\Gamma^\mu D_\mu \psi + \frac{\alpha}{2} \Gamma_{AB} (\psi, \langle \phi^A, \phi^B \rangle) = 0. 
\] (42)

That is, on-shell,

\[
[\delta_\eta, \delta_\epsilon] \psi = -2i\gamma_1 (\epsilon \bar{\eta} D_\epsilon \psi + (\psi, \Lambda). 
\] (43)

The gauge parameter \( \Lambda = -i\alpha \epsilon (\epsilon \bar{\eta}) \langle \phi^A, \phi^B \rangle \) here, coincides with earlier expressions for the gauge parameter in Eqs (33) and (38) by means of Eq (41).

The gauge invariance of the fermionic equation follows from repeated use of Jacobi identities as follows,

\[
\delta (\psi, \langle \phi^A, \phi^B \rangle) = ((\psi, \Lambda), \langle \phi^A, \phi^B \rangle) \\
+ (\psi, \langle \phi^A, \phi^B \rangle) + (\psi, \langle \phi^A, \langle \phi^B, \Lambda \rangle \rangle) \\
= ((\psi, \Lambda), \langle \phi^A, \phi^B \rangle) + \epsilon (\psi, [\Lambda, \langle \phi^A, \phi^B \rangle]) \\
= ((\psi, \langle \phi^A, \phi^B \rangle), \Lambda). 
\] (44)

We can make a supersymmetry variation of the fermionic equation of motion and get corresponding bosonic equations of motion. Among these, we in particular find the constraint equation Eq (37).

\[\text{I am grateful to Ulf Gran for checking the various gamma matrix identities in Eq (78) using the computer program GAMMA [10], and for actually localizing the term in the second of these identities that was missing in previous versions of this paper. This missing term is the reason I failed to show on-shell closure in previous versions of this paper.}\]
Making a field redefinition

\[ \phi^A \rightarrow \frac{1}{\sqrt{\alpha}} \phi^A \]

\[ \psi \rightarrow \frac{1}{\sqrt{\alpha}} \psi \]

(45)

the \( \alpha \)'s drop out in the supersymmetry variations,

\[ \delta \phi^A = i \bar{\epsilon} \Gamma^A \psi \]

\[ \delta A^\mu = i \bar{\epsilon} \Gamma^A \langle \psi, A \rangle \]

\[ \delta \psi = -\epsilon \Gamma^\mu A^\epsilon D^\epsilon A \phi^A - \frac{\epsilon}{6} \Gamma_{ABC} \epsilon (\phi^A, \langle \phi^B, \phi^C \rangle) \]

(46)

and also from the equations of motion. There is no continuous parameter in this theory if the gauge field fixes the overall normalization of the action. Supersymmetry does not tell us which sign \( \epsilon = \pm 1 \) to choose. We do not know what will eventually determine this sign.

It seems likely a supersymmetric action can be derived from the equations of motion one gets by making supersymmetry variation of the fermionic equation of motion, or simply by making a suitable ansatz. I have not yet worked out all the details, but it is clear that for the gauge field there is a Chern-Simons term plus the couplings to scalars and fermions via gauge covariant derivatives in their kinetic terms. Also there is a sixtic scalar interaction term of the form \( (\phi^A, \langle \phi^B, \phi^C \rangle)(\phi_A, \langle \phi_B, \phi_C \rangle) \). This is very similar to a term that was proposed in this action in \[7\], and in fact it become identical to it if we specify that \( \epsilon = 1 \) and let \( (, ) \) be an ordinary commutator and \( (, ) \) and ordinary anti-commutator. More work is needed before we can tell how to realize our algebra with such multiplication operations though. At this stage it is not clear which sign of \( \epsilon \) one should choose. It is likely though that the sign of \( \epsilon \) will get determined when one has the supersymmetric action. If then \( \epsilon \) multiplies some kinetic term, demanding positive kinetic energy will fix the sign of \( \epsilon \).

One may of course wonder how it is possible to get a parity violating Chern-Simons theory at the conformal fixed point, when the action on parallel D2-branes is parity invariant. Another issue is what the level of this Chern-Simons theory would be. These questions were originally raised in \[5\], where it was also proven that no Chern-Simons theory in three dimensions with \( N = 8 \) supersymmetry exists! Have we done something impossible then? The answer is no, since that proof relied on an ordinary Lie algebra structure of the gauge group. In this Letter we have demonstrated that one has to go outside a Lie algebra in order to be able to close supersymmetry on-shell.

4 Speculations on an infinite-dimensional realization of the algebra

Motivated by my earlier work on the M5 brane where I have introduced fields defined on loops \( C^\mu(s) \) in the world volume of the M5 brane, I would now like to suggest that the scalar fields are non-abelian versions of such loops, that is,

\[ \phi^A(s) \]

(47)
parametrized by $s \in [0, 2\pi]$. This describes a (non-abelian or matrix valued) loop in transverse space to the M2 brane, and will depend on a point $x^\mu$ in the M2 brane in the usual fashion, just like any ordinary local field. That is, we have the following dependence on $s$ and $x$ of our non-abelian loops: $\phi^A(s,x)$. Though we will not always display the explicit $x$-dependence.

We then suggest that the two-bracket is given by

$$\langle \phi, \varphi \rangle = \int ds \left( \phi(s)\dot{\varphi}(s) - \varphi(s)\dot{\phi}(s) \right)$$

(48)

for any non-abelian loops $\phi$ and $\varphi$. They may even be fermionic loops. A strange feature of the two-bracket is to be that it does not vanish even if the loops did not take values in a matrix algebra (that is, even if they were abelian), despite

$$\langle \phi, \varphi \rangle = -\langle \varphi, \phi \rangle.$$  

(49)

This non-vanishing is because the two-bracket is not an ordinary commutator.

Supersymmetry suggest the fermions are non-abelian loops $\psi(s)$ in the fermionic part of superspace. The gauge field carries no physical degrees of freedom, and we see no reason to let this depend on $s$, so we assume that the gauge field is just an ordinary (flat) gauge field $A_\mu(x)$.

5 Reduction from M2’s to D2’s

We reduce by taking point-like loops (whatever that means)

$$\phi^A(s) = \phi^A$$

(50)

except the winding loops, which can not shrink due to their topological obstruction. We take them to be minimal, that is, if $\phi^{(10)}$ is a compact (transverse) dimension with radius $R$, then we take

$$\phi^{(10)}(s) = Rs$$

(51)

We have no idea how these fields behave in their internal spaces. How to reduce from a field in $\phi^A(s) \in A$, to a field $\phi^a$ that takes its values in the adjoint representation in an ordinary Lie algebra associated to the gauge group of the associated Yang-Mills theory, is to us a mystery.

We now find that for instance a term like

$$\Gamma_A \int (\psi(s)\dot{\phi}^A(s) - \phi^A(s)\dot{\psi}(s))$$

(52)

reduces to

$$\Gamma^{(10)} \int ds \left( \psi R - Rs\dot{\psi}(s) \right) = \Gamma^{(10)} R \int ds \frac{d}{ds}(s\psi(s)) = \Gamma^{(10)} R \psi$$

(53)

where thus

$$\psi(s) = \psi$$

(54)

is taken to be a point-like loopino. Hence we find that the supersymmetry variation

$$\delta A_\mu = i\Gamma_\mu \Gamma_A \langle \psi, \phi^A \rangle$$

(55)
of super Yang-Mills, where we rescale $\phi^a \to R\phi^a$ and $\psi \to R\psi$. Likewise,
\[
\delta \psi = \Gamma^\mu \Gamma_A D_\mu \phi^A + \frac{1}{6} \Gamma_{ABC} \epsilon(\phi^A, \langle \phi^R, \phi^C \rangle)
\] (57)
reduces to
\[
R\delta \psi = R\Gamma^\mu \Gamma_{(10)} D_\mu \phi^{(10)} + R\Gamma^\mu \Gamma_A D_\mu \phi^A + \frac{R}{2} \Gamma_{ab} \Gamma_{(10)} \epsilon[\phi^a, \phi^b].
\] (58)
This is almost the supersymmetry variation one has in Yang-Mills, apart from
the field strength term. But this term we can also get by including point-like
loops in addition to the winding loops. It seems likely one should really sum
over all loops in some kind of path-integral. Then one should try to understand
why only the minimal loops give the important contributions. Of course this
presentation is rather vague. At the time of this writing, no known way to
reduce from membrane theory to Yang-Mills theory is known. The purpose of
this presentation is to give some idea of how this could work, not to give a final
answer to that question.

Since one wants to have translational invariance\footnote{We study rigid translations of the loops, so $v^A1$ does not depend on $s$.}
\[
\phi^A(s) \to \phi^A(s) + v^A1
\] (59)
it has been suggested the three-bracket should be a Nambu bracket \cite{3}, \cite{9}, \cite{7}. That would work nicely since 1 commutes with everything and translational in-
variance would get restored, though these papers are concerned with a reduction
of the M2 brane theory to a fuzzy three sphere \cite{6}.

If the field is really a loop that winds the compact dimension, then $\langle \phi, \phi \rangle$ is
invariant under translations. But for a different reason than that 1 commutes
with everything. It is invariant under translations because
\[
\int ds \dot{\phi}(s) = 0
\] (60)
when integrated along a closed loop.

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GAMMA.
A Gamma matrix identities

In 11 dimensions, the dimension of the spinor is $2^5 = 32$. Since $2^{11} = 2^5 \cdot 2^5$, we get two copies of $32 \times 32$ matrices if we sum from 0 to 11. So we should just sum from 0 to 5 in

$$
\epsilon \bar{\eta} = \sum_{n=0}^{5} c_n \bar{\eta} \Gamma_{M_1 \ldots M_n} \epsilon \Gamma^{M_1 \ldots M_n} 
$$

(61)

Making the split $11 = 3 + 8$, we find a basis

$$
1, \Gamma^A, \Gamma^{AB}, \ldots
$$

(62)

which constitute $2^8 \cdot 8 = 2^{10}$ linearly independent matrices, as suitable for a basis of $32 \times 32$ matrices.

If $\epsilon$ is Weyl,

$$
\Gamma \epsilon = \epsilon
$$

(63)

then we have just even numbers of $\Gamma^A$ matrices,

$$
\epsilon \bar{\eta} = \sum_p c_p \bar{\eta} \Gamma_{A_1 A_2 \ldots A_p} \epsilon \Gamma^{A_1 A_2 \ldots A_p} + \sum_p d_p \bar{\eta} \Gamma_{\mu} \Gamma_{A_1 A_2 \ldots A_p} \epsilon \Gamma^{\mu} \Gamma^{A_1 A_2 \ldots A_p}
$$

(64)

We may let $p = 0, 1, \ldots, 4$ if we also include $\Gamma$ since

$$
\Gamma_{A_1 \ldots A_p} = \frac{1}{(8-p)!} \epsilon_{A_1 \ldots A_p A_{p+1} \ldots A_8} \Gamma^{A_{p+1} \ldots A_8}
$$

(65)

We find that

$$
\bar{\epsilon} \Gamma_{A_1 A_2 \ldots A_p} \eta - \bar{\eta} \Gamma_{A_1 A_2 \ldots A_p} \epsilon = \bar{\epsilon} \Gamma_{A_1 A_2 \ldots A_p} \eta \left( 1 - (-1)^{\frac{p+1}{2}} \right)
$$

$$
\bar{\epsilon} \Gamma_{\mu} \Gamma_{A_1 A_2 \ldots A_p} \eta - \bar{\eta} \Gamma_{\mu} \Gamma_{A_1 A_2 \ldots A_p} \epsilon = \bar{\epsilon} \Gamma_{\mu} \Gamma_{A_1 A_2 \ldots A_p} \eta \left( 1 + (-1)^{\frac{p+1}{2}} \right)
$$

(66)

which, together with the Weyl property, means that the only non-vanishing combinations are

$$
\bar{\epsilon} \Gamma^{AB} \eta - \bar{\eta} \Gamma^{AB} \epsilon,
\bar{\epsilon} \Gamma_{\mu} \eta - \bar{\eta} \Gamma_{\mu} \epsilon,
\bar{\epsilon} \Gamma_{\mu} \Gamma_{ABCD} \eta - \bar{\eta} \Gamma_{\mu} \Gamma_{ABCD} \eta.
$$

(67)

and we get

$$
\epsilon \bar{\eta} - \eta \bar{\epsilon} = a \bar{\epsilon} \Gamma_{AB} \eta \Gamma^{AB} (1 + \Gamma) + b \bar{\epsilon} \Gamma_{\mu} \eta \Gamma^{\mu} (1 + \Gamma) + c \bar{\epsilon} \Gamma_{ABCD} \eta \Gamma^{ABCD}
$$

(68)

We also find that

$$
\bar{\psi} \Gamma_{A_1 \ldots A_p} \psi \sim 1 + (-1)^{\frac{p(p+1)}{2}}
$$
\[ \bar{\psi}\Gamma_{\mu}\Gamma_{A_1\ldots A_p}\psi \sim 1 - (-1)^{\frac{p(p-1)}{2}} \]  

(69)

so, if \( \psi \) is anti-Weyl, the only non-vanishing bilinears are

\[ \bar{\psi}\psi, \quad \bar{\psi}\Gamma_{ABCD}\psi, \quad \bar{\psi}\Gamma_{\mu}\Gamma_{AB}\psi. \]  

(70)

For \( \psi \) taking values in an algebra \( A \), we find an additional minus sign (due to the antisymmetry of the bracket \( \langle \ldots \rangle \)) and so the above will instead be the vanishing fermionic bilinears.

For the numerical factors, we need

\[ \delta_{A_1\ldots A_p}^{A_1\ldots A_p} = \binom{8}{p} \frac{8!}{(8-p)!} \]  

from which we get

\[ \text{tr} \left( \Gamma_{A_1\ldots A_p}^{A_1\ldots A_p} \right) = (-1)^{\frac{p(p-1)}{2}} p! (\text{tr} \mathbf{1}) \delta_{A_1\ldots A_p}^{A_1\ldots A_p} \]  

(72)

Here \( \text{tr} \mathbf{1} = 2^5 = 32 \).

Now we get the Fierz identity

\[ e\bar{\eta} - \eta \bar{\epsilon} = \frac{1}{16} \left[ (2\epsilon\Gamma_{\mu}\eta\Gamma^{\mu} - \epsilon\Gamma_{AB}\eta\Gamma^{AB}) \frac{1}{2} (1 + \Gamma) \right. \]

\[ \left. - \frac{1}{24} \epsilon\Gamma_{ABCD}\eta\Gamma^{ABCD} \right] \]  

(73)

If we let \( \Gamma^{M_k} \) be some completely antisymmetrized product of gammas, then

\[ \epsilon\Gamma^{M_1\ldots M_n}\eta - \bar{\eta}\Gamma^{M_1\ldots M_n}\epsilon = \bar{\epsilon} \left( \Gamma^{M_1\ldots M_n} - e\Gamma^{M_1\ldots M_n} \right) \eta \]  

(74)

where \( e \) is the product of the signs relating \( \Gamma^{M_k} \) to its transpose. For \( M_k \) being single indices, we have

\[ \Gamma^{M_1\ldots M_k} = e_k C \Gamma^{M_1\ldots M_k} C^{-1} \]  

(75)

with sign factor

\[ e_k = (-1)^{\frac{k(k+1)}{2}} \]  

(76)

So for instance, we get

\[ \bar{\epsilon}\Gamma^{A}\Gamma_{CDE}\eta - \bar{\eta}\Gamma^{A}\Gamma_{CDE}\epsilon = \bar{\epsilon}\{\Gamma^{A}\Gamma_{CDE}\}\eta \]

\[ = 6\delta_{[C_E}^{[A} \epsilon\Gamma_{DE]}\eta \]

with sign factor

\[ e_k = (-1)^{\frac{k(k+1)}{2}} \]  

(76)

Some gamma matrix identities,

\[ \{\Gamma^{A}, \Gamma_{CDE}\} = 6\delta_{[C_E}^{[A} \Gamma_{DE]} \]

\[ \Gamma_{ABC}\Gamma^{EF}\Gamma_{C} = 2\Gamma^{EF}\Gamma_{AB} - 8\delta_{A}^{[E} \Gamma^{F]}\Gamma_{B} - 32\delta_{[A}^{[E} \Gamma_{B]}^{F]} \]

\[ \Gamma_{A}\Gamma^{EF}\Gamma_{B} = \Gamma^{EF}\Gamma_{AB} + 4\delta_{[A}^{[E} \Gamma_{B]}^{F]} \]

\[ \Gamma_{ABC}\Gamma^{EFHG}\Gamma_{C} = -2\Gamma_{[A}^{[E}\Gamma^{FHG]}\Gamma_{B]} \]

\[ \Gamma_{A}\Gamma^{EFGH}\Gamma_{A} = 0 \]  

(78)
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