EXPLICIT BOUNDS ON INTEGRALS OF EIGENFUNCTIONS
OVER CURVES IN SURFACES OF NONPOSITIVE
CURVATURE

by
Emmett Lyons Wyman

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Abstract

Let \((M,g)\) be a compact Riemannian surface with nonpositive sectional curvature and let \(\gamma\) be a closed geodesic in \(M\). Let \(e_\lambda\) be an \(L^2\)-normalized eigenfunction of the Laplace-Beltrami operator \(\Delta_g\) with \(-\Delta_g e_\lambda = \lambda^2 e_\lambda\). Sogge, Xi, and Zhang [12] showed using the Gauss-Bonnet theorem that

\[
\int_\gamma e_\lambda \, ds = O((\log \lambda)^{-1/2}),
\]

an improvement over the general \(O(1)\) bound. Conjectures by Reznikov [9] suggest, among other things, the same bounds should hold over a wider variety of curves \(\gamma\). We use a combination of methods from [12] and other geometric tools which we develop in Chapter 3 to show this integral enjoys the same decay over a wide variety of curves, where \(M\) has *nonpositive* sectional curvature. These are the curves \(\gamma\) whose geodesic curvature avoids, pointwise, the geodesic curvature of circles of infinite radius tangent to \(\gamma\).

Primary Reader: Professor Christopher Sogge (Advisor)

Secondary Readers: Professor Mauro Maggioni, Assistant Professor Hang Xu, Assistant Professor Fei Lu, Professor Paul Dagdigian, Professor Dan Naiman, Assistant Professor Petar Maksimovic.
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Introduction

1.1 Background

Throughout, we let \((M, g)\) be a compact, boundaryless, 2-dimensional Riemannian manifold, we let \(\Delta_g\) denote the Laplace-Beltrami operator

\[
\Delta_g = |g|^{-1/2} \sum_{j,k} \partial_j (g^{ij} |g|^{1/2} \partial_k)
\]

with respect to the metric \(g\), and we denote by \(e_\lambda\) an \(L^2\)-normalized eigenfunction \(\Delta_g\) with corresponding eigenvalue \(\lambda\), i.e.

\[
\Delta_g e_\lambda = -\lambda^2 e_\lambda \quad \text{and} \quad \|e_\lambda\|_{L^2(M)} = 1.
\]

The original problem of bounding geodesic period integrals arose from the spectral theory of automorphic forms with the question: How do the Fourier coefficients of an eigenfunction restricted to a geodesic behave in a compact hyperbolic surface? The problem for the constant coefficient was simultaneously and independently addressed by Good [6] and Hejhal [7], who showed that

\[
\int_\gamma e_\lambda \, ds = O(1).
\]

(1.1.1)

if \(M\) is a compact hyperbolic surface and \(\gamma\) is a closed geodesic in \(M\). In fact, this bound holds if we integrate \(e_\lambda\) against any fixed periodic exponential function over \(\gamma\).

Good and Hejhal’s bound was later extended to the general Riemannian setting by Zelditch [15]
who provided the following powerful result. Let $M$ be any $n$-dimensional, compact, Riemannian manifold without boundary. Let $e_j$ for $j = 1, 2, \ldots$ comprise a Hilbert basis of eigenfunctions with corresponding eigenvalues $\lambda_j$. If $\Sigma$ is a $d$-dimensional submanifold in $M$ and $d\sigma$ is a smooth, compactly supported multiple of the surface measure on $\Sigma$, then Zelditch provides a Kuznecov asymptotic formula,

$$\sum_{\lambda_j \leq \lambda} \left| \int_{\Sigma} e_j \, d\sigma \right|^2 \sim \lambda^{n-d} + O(\lambda^{n-d-1}) \quad (1.1.2)$$

where the implicit constant in front of the main term is nonzero provided $d\sigma$ is nonnegative and not identically zero. As a consequence, we have

$$\sum_{\lambda_j \in [\lambda, \lambda+1]} \left| \int_{\Sigma} e_j \, d\sigma \right|^2 = O(\lambda^{n-d-1}).$$

Taking the $n = 2, d = 1$ case provides Good and Hejhal’s $O(1)$ bound\(^1\) regardless of hypotheses on the curvature of $M$ or $\gamma$.

In \cite{9}, Reznikov demonstrates the bound (1.1.1) for both periodic geodesics and circles in hyperbolic surfaces, and goes further to conjecture the following.

**Conjecture 1.1 (Reznikov).** Let $M$ be a compact hyperbolic surface and $\gamma$ a closed geodesic or circle in $M$. Then,

$$\int_{\gamma} e_\lambda \, ds = O(\lambda^{-1/2+\varepsilon})$$

for all $\varepsilon > 0$.

The first improvement\(^2\) towards Reznikov’s conjecture is due to Chen and Sogge\cite{4}, who obtained an improved bound

$$\int_{\gamma} e_\lambda \, ds = o(1) \quad (1.1.3)$$

for geodesics in compact surfaces with (not necessarily constant) negative curvature. Their strategy involved a lift to the universal cover, the Hadamard parametrix to write the relevant quantity as an oscillatory integral with a geometric phase function, and the Gauss-Bonnet theorem to show that critical points of the phase function are isolated. They conclude with the method of stationary phase. Recently Sogge, Xi, and Zhang\cite{12} improved this bound further to $O((\log \lambda)^{-1/2})$ while also allowing the sectional curvature of $M$ to vanish of finite order.

\(^1\)Zelditch’s Kuznecov formula also tells us that generic eigenfunctions satisfy much better bounds. One can use an extraction argument to show that if $R(\lambda) \to \infty$, there exists a density 1 subsequence of eigenfunctions for which the left hand side of (1.1.1) is $O(R(\lambda) \lambda^{-d/2})$, or $O(R(\lambda) \lambda^{-1/2})$ in the case of a curve.

\(^2\)Reznikov’s conjectured bound, or any polynomial improvement to the bound of (1.1.1) for that matter, seems to be inaccessible with standard techniques. But, it does hold for circles in the flat torus as we will see in section 1.3.
Following Chen and Sogge’s strategy, the author [14] used Jacobi fields to show the little-$o$ bound (1.1.3) of [4] holds in the broader scenario where $M$ has nonpositive sectional curvature and the geodesic curvature of $\gamma$ avoids that of circles of infinite radius tangent to $\gamma$. As a corollary, integrals of eigenfunctions over both geodesics and circles in hyperbolic manifolds enjoy Chen and Sogge’s $o(1)$ bound. Following Sogge, Xi, and Zhang’s example, we improve this to $O((\log \lambda)^{-1/2})$ decay under the same hypotheses of [14], albeit without the weakened sectional curvature hypotheses of [12].

1.2 Statement of Results

We require some notation to state our main result. If $\gamma$ is a curve in $M$, we denote by $\kappa_\gamma(t)$ the geodesic curvature of $\gamma$ at $t$, i.e.

$$
\kappa_\gamma(t) = \frac{1}{|\gamma'(t)|} \left| \frac{D}{dt} \frac{\gamma'(t)}{|\gamma'(t)|} \right|,
$$

where $D/dt$ is the covariant derivative in the parameter $t$. For fixed $p \in M$ and $v \in T_p M$, we denote by $v^\perp$ a choice of vector in $T_p M$ for which $|v^\perp| = |v|$ and $\langle v^\perp, v \rangle = 0$. We denote by $S_p M$ the unit-length vectors in $T_p M$, and we denote the bundle of such vectors by $SM$, the unit sphere bundle over $M$.

To state our main result, we need a function $k$ on the unit sphere bundle of $M$ representing a “critical geodesic curvature” which we assume $\kappa_\gamma$ avoids to obtain decay of the integral in (1.1.1).

**Definition 1.2.** Fix $p \in M$ and $v \in S_p M$ and let $t \mapsto \zeta(t)$ the unit speed geodesic with $\zeta(0) = p$ and $\zeta'(0) = v$. Let $J$ be a Jacobi field along $\zeta$ satisfying

$$
J(0) = \zeta'(0)^\perp.
$$

We let $k(v)$ denote the unique number such that

$$
|J(r)| = O(1) \quad \text{for } r \leq 0
$$

if $J$ satisfies the additional initial condition

$$
\frac{D}{dr} J(0) = k(v) J(0).
$$

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Figure 1.1: A Jacobi Field $J$ satisfying Definition 1.2. $k$ is equal to the geodesic curvature of the limiting circle on the right.

$k$ is a well-defined, continuous function on $SM$ by [14, Proposition 4.1], though we include the proof here as Proposition 3.3 for completeness. The geometric meaning of $k$ is clearer after a lift to the universal cover. By the theorem of Hadamard, we identify the universal cover of $M$ with $(\mathbb{R}^2, \tilde{g})$, where $\tilde{g}$ is the pullback of the metric tensor $g$ through the covering map. If $p \in M$ and $\tilde{p} \in \mathbb{R}^2$ a lift of $p$ through the covering map, and $v \in S_p M$ and $\tilde{v} \in S_{\tilde{p}} \mathbb{R}^2$ the lift of $v$, the argument in Proposition 3.3 reveals $k(v)$ to be the limiting curvature of the circle at $\tilde{p}$ with center taken to infinity along the geodesic ray in direction $-\tilde{v}$ (see Figure 1.1). In the flat case, $k \equiv 0$. If $M$ is a hyperbolic surface with sectional curvature $-1$, part (2) of Lemma 3.4 tells us $k \equiv 1$, the curvature of a horocycle in the hyperbolic plane. Our main result is as follows.

**Theorem 1.3.** Let $(M,g)$ be a compact, boundaryless, 2-dimensional Riemannian manifold with nonpositive sectional curvature. Let $b$ be a smooth, compactly supported function on $\mathbb{R}$ and $\gamma$ be a unit-speed curve in $M$ parametrized on an interval containing the support of $b$. Then,

$$\sum_{\lambda_j \in [\lambda, \lambda + (\log \lambda)^{-1}]} \left[ \int b(s) e_j(\gamma(s)) \, ds \right]^2 = O((\log \lambda)^{-1}) \tag{1.2.4}$$

provided that

$$\kappa_\gamma(s) \neq k(\gamma'(s)) \quad \text{and} \quad \kappa_\gamma(s) \neq k(-\gamma'(s)) \tag{1.2.5}$$

for each $s \in \text{supp} b$.

We obtain our desired bound as an immediate corollary to Theorem 1.3.
Theorem 1.4. Let $M$, $b$, and $\gamma$ be as in Theorem 1.3 with $\gamma$ satisfying (1.2.5). Then,

$$\int b(s)e_\lambda(\gamma(s))\,ds = O((\log \lambda)^{-1/2}).$$  (1.2.6)

To prove Theorem 1.3, we follow Sogge, Xi, and Zhang’s argument in [12] to reduce the problem to an oscillatory integral with a geometric phase function. We then exploit properties of the curvature of circles of increasing radius to obtain bounds on the Hessian of the phase function, and conclude with a stationary phase argument.

There are a couple useful corollaries to Theorem 1.3 which are worth pointing out. We will find by part (2) of Lemma 3.4 that if the sectional curvature $K$ is bounded by

$$0 \geq K_0 \geq K \geq K_1$$

for some nonpositive constants $K_0$ and $K_1$, then

$$\sqrt{-K_0} \leq k \leq \sqrt{-K_1}.$$

This yields an easy criterion for determining $\gamma$ which satisfy the hypotheses (1.2.5) of Theorem 1.3.

Corollary 1.5. Let $M$, $b$, and $\gamma$ be as in Theorem 1.3, and suppose the sectional curvature $K$ of $M$ is bounded as above. If

$$\kappa_\gamma(s) < \sqrt{-K_0} \quad \text{or} \quad \kappa_\gamma(s) > \sqrt{-K_1}$$

for all $s \in \text{supp} b$, then (1.2.4) and hence (1.2.6) hold.

If the sectional curvature of $M$ is strictly negative, we can take $K_0 > 0$. The corollary then implies the main result in [12] for geodesics, minus the weakened hypotheses which allow $K$ to vanish of finite order. If $\gamma$ is a geodesic circle, we can say something else.

Corollary 1.6. Let $M$ and $b$ be as in Theorem 1.3, let the sectional curvature $K$ be bounded between $K_0$ and $K_1$ be as above, and let $\gamma$ be a unit-speed geodesic circle of radius $r > 0$. Then, (1.2.4) and hence (1.2.6) hold provided

$$r < \frac{1}{2\sqrt{-K_0}} \log \left( \frac{\sqrt{-K_1} + \sqrt{-K_0}}{\sqrt{-K_1} - \sqrt{-K_0}} \right) \quad \text{in the case } 0 > K_0 > K_1,$$

$$r < \frac{1}{\sqrt{-K_1}} \quad \text{in the case } 0 = K_0 > K_1,$$
or for all r in the case where the sectional curvature is constant.

This corollary follows directly from the previous corollary, part (3) of Lemma 3.4, and the fact that the inverse of the hyperbolic cotangent function is

\[
\text{arccoth}(x) = \frac{1}{2} \log \left( \frac{x + 1}{x - 1} \right).
\]

1.3 Examples

There are a couple model settings – the round sphere and the flat torus – which help to illustrate the necessity of the hypotheses of Theorem 1.3. In what follows, \( \gamma \) will always be a unit speed curve and \( b \) will be a smooth, nonnegative, compactly supported function on \( \mathbb{R} \).

Example 1.7 (The Sphere). We require our manifold have nonpositive sectional curvature in order to construct \( k \) in Definition 1.2, but one may ask anyway if it is possible to impose some conditions on a curve in a positively curved manifold so that we obtain some decay like (1.2.6). We are able to give a negative answer to this question by considering the standard sphere \( S^2 \). The key ideas here are Zelditch’s Kuznecov formula (1.1.2) and the fact that all of the eigenfunctions \( \lambda \) are of the form

\[
\lambda = \sqrt{k(k+1)} \quad \text{for some } k = 0, 1, 2, \ldots.
\]

(See [10, Section 3.4] or [8, Theorem 3.1].)

Let \( e_j \) be an orthonormal basis of eigenfunctions on \( S^2 \). For each distinct eigenvalue \( \lambda \), construct a new eigenfunction \( e_\lambda \) by

\[
e_\lambda = \frac{\sum_{\lambda_j = \lambda} \left( \int b(s)e_j(\gamma(s)) \, ds \right) e_j}{\left( \sum_{\lambda_j = \lambda} \left| \int b(s)e_j(\gamma(s)) \, ds \right|^2 \right)^{1/2}}.
\]

Note that \( e_\lambda \) is \( L^2 \)-normalized and that

\[
\int b(s)e_\lambda(\gamma(s)) \, ds = \left( \sum_{\lambda_j = \lambda} \left| \int b(s)e_j(\gamma(s)) \, ds \right|^2 \right)^{1/2}.
\]
By (1.1.2) and the assumption that $b$ is nonnegative, there exists some large constant $c$ so that

$$\sum_{\lambda_j \in [\lambda, \lambda + c]} \left| \int b(s)e_j(\gamma(s)) \, ds \right|^2 \geq 1.$$ 

However, there are at most $c$ distinct eigenvalues in the interval $[\lambda, \lambda + c]$. Hence, every interval of length $c$ has an eigenvalue $\lambda$ for which

$$\int b(s)e_\lambda(\gamma(s)) \, ds \geq 1/c.$$ 

Hence, there is no version of Theorem 1.4 which will hold on the sphere.

Example 1.8 (The Torus). Let $\mathbb{T}^2 = \mathbb{R}^2/2\pi\mathbb{Z}^2$ denote the flat torus. As noted before, $k \equiv 0$ and every curve $\gamma$ with nonvanishing geodesic curvature satisfies the hypotheses (1.2.5) of Theorem 1.3. Suppose $\gamma$ is one such curve parametrized by arc-length. Let $e_\lambda$ be any $L^2$-normalized eigenfunction on $\mathbb{T}^2$. Note

$$e_\lambda(x) = \sum_{m \in \mathbb{Z}^2 \atop |m| = \lambda} a_m e^{im \cdot x}$$

for some coefficients $a_m$ satisfying

$$\sum_{m \in \mathbb{Z}^2 \atop |m| = \lambda} |a_m|^2 = \frac{1}{(2\pi)^2}.$$

By Cauchy-Schwartz,

$$\left| \int b(s)e_\lambda(\gamma(s)) \, ds \right| = \left| \sum_{m \in \mathbb{Z}^2 \atop |m| = \lambda} a_m \int b(s)e^{im \cdot \gamma(s)} \, ds \right| \leq \frac{1}{2\pi} \# \{m \in \mathbb{Z}^2 : |m| = \lambda \}^{1/2} \sup_{|m| = \lambda} \left| \int b(s)e^{im \cdot \gamma(s)} \, ds \right|.$$ 

Divisor bounds for Gaussian integers yields an essentially sharp estimate

$$\# \{m \in \mathbb{Z}^2 : |m| = \lambda \} = O(\lambda^\varepsilon)$$

for all $\varepsilon > 0$, while a standard stationary phase argument yields a sharp uniform bound of $O(\lambda^{-1/2})$ on the integral. Hence,

$$\int b(s)e_\lambda(\gamma(s)) \, ds = O(\lambda^{-1/2+\varepsilon}),$$

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which is much better than the bound (1.2.6) in Theorem 1.4. This example can be seen to be sharp by taking \( \gamma \) to be a circle, \( b \equiv 1 \), and \( a_m \) constant over \( |m| = \lambda \).

It is worth remarking that, again using standard stationary phase arguments, we obtain a polynomial improvement over the bound (1.2.6) even if the geodesic curvature of \( \gamma \) were to vanish of finite order. However, problems occur when \( \gamma \) contains a line segment. If \( \gamma \) is a line segment in \( \mathbb{T}^2 \), we may construct a sequence of exponentials which are essentially constant on \( \gamma \). We select a sequence \( m_k \) on the integer lattice with \( |m_k| \to \infty \) whose distance \( |m_k \cdot \gamma'(s)| \) from the space of normal vectors to \( \gamma \) in \( \mathbb{R}^2 \) vanishes in the limit. Then,

\[
\left| \int b(s)e^{im_k \cdot \gamma(s)} \, ds \right| \to \left| \int b(s) \, ds \right|,
\]

and the conclusion of Theorem 1.4 does not hold.

In the example for the torus above, we demonstrate the bound

\[
\int b(s)e_{\lambda}(\gamma(s)) \, ds = O(1)
\]  

(1.3.1)

cannot be improved if \( \gamma \) is a geodesic segment. The analogous situation on a compact hyperbolic surface is when \( \gamma \) is a segment of a horocycle. It is natural to ask if this \( O(1) \) bound is still sharp. The answer is: probably not. Assuming the quantum unique ergodicity conjecture, any sequence of eigenfunctions on a compact hyperbolic surface is quantum ergodic. Recently, Canzani, Galkowski, and Toth \[3\] showed that if \( e_{\lambda} \) is a quantum ergodic sequence of eigenfunctions, the integral in (1.3.1) is necessarily \( o(1) \) for all smooth curves \( \gamma \). On the other hand, if one can construct a sequence of eigenfunctions saturating (1.3.1) for some horocycle \( \gamma \), one will have provided a negative answer to the quantum unique ergodicity conjecture.
A Standard Reduction

We employ a standard strategy to reduce the bound in Theorem 1.3 to one involving a sum over the deck transformations in the universal cover of oscillatory integrals with some geometric phase function. Our presentation of this reduction is only superficially different from [4] and [12]. The idea to lift the problem to the universal cover originally appeared in Bérard’s celebrated paper [1] in which he obtained a log improvement to the bound on the remainder term of the sharp Weyl law for compact manifolds with nonpositive sectional curvature. Other elements of this reduction, including uniformizing the sum in Theorem 1.3 over a Schwartz-class function and writing the result as some integral against the kernel of the half-wave operator, are very standard and appear across many results in global harmonic analysis (see for example [2, 13, 1, 4, 12] and [11, 10] for further reading).

2.1 Uniformization and the Half-Wave Operator

Let $e_j$ for $j = 0, 1, 2, \ldots$ be a Hilbert basis of eigenfunctions with corresponding eigenvalues $\lambda_j$. To prove Theorem 1.3, it suffices to show

$$\sum_j \chi(T(\lambda_j - \lambda)) \left| \int b(s)e_j(\gamma(s)) \, ds \right|^2 \lesssim T^{-1} + e^{CT\lambda^{-1/2}} \tag{2.1.1}$$

where $\chi$ is a nonnegative, Schwartz-class function on $\mathbb{R}$ with $\chi(0) = 1$ and supp$\hat{\chi} \subset [-1, 1]$, and where

$$T = c \log \lambda \tag{2.1.2}$$
for some appropriately small positive constant $c$. Using a partition of unity, we write $b$ as a sum

$$b = \sum_k b_k$$

of smooth, compactly supported functions with small support. By Cauchy-Schwarz, the left hand side of (2.1.1) is bounded by the total number of $b_k$ in the sum times

$$\sum_k \sum_j \chi(T(\lambda_j - \lambda)) \left| \int b_k(s)e_j(\gamma(s)) \, ds \right|^2.$$

Hence, it suffices to prove (2.1.1) where $b$ has small support. After expanding the integral in (2.1.1), the left hand side of (2.1.1) is

$$\sum_j \chi(T(\lambda_j - \lambda)) \iint b(s)b(t)e_j(\gamma(s))\overline{e_j(\gamma(t))} \, ds \, dt$$

$$= \frac{1}{2\pi} \sum_j \iint b(s)b(t)\hat{\chi}(\tau)e^{i\tau T(\lambda_j - \lambda)}e_j(\gamma(s))\overline{e_j(\gamma(t))} \, ds \, dt \, d\tau$$

$$= \frac{1}{2\pi T} \sum_j \iint b(s)b(t)\hat{\chi}(\tau/T)e^{i\tau(\lambda_j - \lambda)}e_j(\gamma(s))\overline{e_j(\gamma(t))} \, ds \, dt \, d\tau$$

$$= \frac{1}{2\pi T} \iint b(s)b(t)\hat{\chi}(\tau/T)e^{-i\lambda\tau}e^{i\tau \sqrt{-\Delta_g}(\gamma(s), \gamma(t))} \, d\tau \, ds \, dt$$

where the second line follows from the Fourier inversion formula, the third by a change of variables, and the fourth by writing out the kernel

$$e^{i\tau \sqrt{-\Delta_g}(x, y)} = \sum_j e^{i\tau \lambda_j}e_j(x)\overline{e_j(y)}$$

of the half-wave operator $e^{it \sqrt{-\Delta_g}}$. Hence, (2.1.1) will follow from

$$\left| \iint b(s)b(t)\hat{\chi}(\tau/T)e^{-i\lambda\tau}e^{i\tau \sqrt{-\Delta_g}(\gamma(s), \gamma(t))} \, d\tau \, ds \, dt \right| \lesssim 1 + e^{CT\lambda^{-1/2}}.$$

To simplify things, we scale the metric so that the injectivity radius of $M$ is at least 10. Moreover, after perhaps restricting the support of $b$, we ensure that

$$\sup_{s,t \in \text{supp} b} d_g(\gamma(s), \gamma(t)) \leq 1 \quad (2.1.3)$$
where \(d_g\) is the distance function with respect to the metric \(g\). Now we let \(\beta \in C_0^\infty(\mathbb{R})\) be a smooth cutoff function so that \(\beta(\tau) = 1\) for \(|\tau| \leq 2\) and \(\beta(\tau) = 0\) for \(|\tau| \geq 4\). We begin by showing

\[
\left| \int \int b(s)b(t)\beta(\tau) \hat{\chi}(\tau/T)e^{-i\lambda \tau} e^{\tau \sqrt{-\Delta_g}(\gamma(s), \gamma(t))} ds \, dt \right| \lesssim 1. \tag{2.1.4}
\]

As argued in [4] and [12], we have by the proof of Lemma 5.1.3 in [11] that

\[
\int \beta(\tau) \hat{\chi}(\tau/T)e^{-i\lambda \tau} e^{\tau \sqrt{-\Delta_g}(x, y)} d\tau = \lambda^{1/2} \sum_{\pm} a_{\pm}(T, \lambda; d_g(x, y)) e^{\pm i\lambda d_g(x, y)} + O(1)
\]

where the amplitude \(a_{\pm}\) satisfies bounds

\[
\left| \frac{d^j}{dr^j} a_{\pm}(T, \lambda; r) \right| \leq C_j r^{-j-1/2} \quad \text{if } r \geq \lambda^{-1}, T \geq 1 \tag{2.1.5}
\]

and

\[
|a_{\pm}(T, \lambda; r)| \leq C \lambda^{1/2} \quad \text{if } r \leq \lambda^{-1}, T \geq 1. \tag{2.1.6}
\]

Hence (2.1.4) would follow from

\[
\sum_{\pm} \left| \int \int b(s)b(t) a_{\pm}(T, \lambda; |r|) e^{\pm i\lambda |r|} ds \, dt \right| \lesssim \lambda^{-1/2}. \tag{2.1.7}
\]

We let

\[r(s, t) = \text{sgn}(s - t) d_g(\gamma(s), \gamma(t))\]

and if necessary restrict the support of \(b\) so that the map

\[(s, t) \mapsto (s, r(s, t))\]

is a diffeomorphism on supp\(b \times \text{supp} b\). By a change of coordinates, we write the integral in (2.1.7) as

\[
\int \int \tilde{b}(s, r) a_{\pm}(T, \lambda; |r|) e^{\pm i\lambda |r|} ds \, dr
= \int \int_{|r| \leq \lambda^{-1}} + \int \int_{|r| \geq \lambda^{-1}} \tilde{b}(s, r) a_{\pm}(T, \lambda; |r|) e^{\pm i\lambda |r|} ds \, dr.
\]

where \(\tilde{b}(s, r) \, ds \, dr = b(s)b(t) \, ds \, dt\) where \(r = r(s, t)\). The \(|r| \leq \lambda^{-1}\) part is \(O(\lambda^{-1/2})\) by (2.1.6). The same bound holds for the \(|r| \geq \lambda^{-1}\) part after integrating by parts in \(r\) once and applying (2.1.5).
(2.1.4) follows.

2.2 Lift to the Universal Cover

What remains is to show

$$\left| \iiint b(s)b(t)(1 - \beta(\tau))\hat{\chi}(\tau/T)e^{-i\lambda\tau}e^{i\tau\sqrt{-\Delta_y}}(\gamma(s), \gamma(t)) \, ds \, dt \, d\tau \right| \lesssim 1 + e^{CT\lambda^{-1/2}}.$$  

(2.2.1)

As in [4] and [12], we want to lift the kernel $e^{i\tau\sqrt{-\Delta_y}(x, y)}$ to the universal cover of $M$, but we also want to make use of Huygen’s principle afterwards. So before we lift, we will rephrase the bound above using the kernel $\cos(\tau \sqrt{-\Delta_y})$ instead of $e^{i\tau\sqrt{-\Delta_y}}$. By Euler’s formula,

$$e^{i\tau\sqrt{-\Delta_y}} = 2\cos(\tau \sqrt{-\Delta_y}) - e^{-i\tau\sqrt{-\Delta_y}},$$

the contribution of the $e^{-i\tau\sqrt{-\Delta_y}}$ term to (2.2.1) is

$$\left| \iiint b(s)b(t)(1 - \beta(\tau))\hat{\chi}(\tau/T)e^{-i\lambda\tau}e^{-i\tau\sqrt{-\Delta_y}}(\gamma(s), \gamma(t)) \, ds \, dt \, d\tau \right|$$

$$= \sum_j \left| \iiint (1 - \beta(\tau))\hat{\chi}(\tau/T)e^{-i(\lambda_j + \lambda)\tau}e_j(\gamma(s))\overline{e_j(\gamma(t))} \, ds \, dt \, d\tau \right|$$

$$= 2\pi \sum_j \Phi_T(\lambda_j + \lambda) \left| \int b(s)b(t)e_j(\gamma(s))\overline{e_j(\gamma(t))} \, ds \, dt \right|$$

where $\Phi_T(\tau) = (1 - \beta(\tau))\hat{\chi}(\tau/T)$. By integration by parts,

$$\Phi_T(\lambda) = O(\lambda^{-N}) \quad \text{for all } N \in \mathbb{N}.$$  

Hence,

$$2\pi \left| \sum_j \Phi_T(\lambda_j + \lambda) \left| \int b(s)b(t)e_j(\gamma(s))\overline{e_j(\gamma(t))} \, ds \, dt \right| \right|$$

$$\leq 2\pi \sum_j |\Phi_T(\lambda_j + \lambda)| \left| \int b(s)e_j(\gamma(s)) \, ds \right|^2$$

$$= O(\lambda^{-N}),$$
where in the last line we invoke the standard \( O(1) \) bound on the integral. Hence, it suffices to show
\[
\left| \int \int \int b(s)b(t)(1 - \beta(\tau))\hat{\chi}(\tau/T)e^{-i\lambda \tau} \cos(\tau \sqrt{-\Delta_g})(\gamma(s), \gamma(t)) \, d\tau \, ds \, dt \right| \\
\lesssim 1 + e^{CT} \lambda^{-1/2}.
\] (2.2.2)

Now we are ready to lift to the universal cover. Since \( M \) has nonpositive sectional curvature, we identify its universal cover with \((\mathbb{R}^2, \tilde{g})\) where \( \tilde{g} \) is the pullback of the metric tensor \( g \) through the covering map. Fix \( \tilde{f} \in C^\infty_0(\mathbb{R}^2) \) and define \( f \in C^\infty(M) \) by
\[
f(x) = \sum_{\alpha \in \Gamma} \tilde{f} \circ \alpha(\tilde{x})
\]
where \( \Gamma \) is the set of deck transformation associated with the covering map and \( \tilde{x} \) is a lift of \( x \) to \( \mathbb{R}^2 \). Now if \( \tilde{u}(t, x) \) satisfies the wave equation
\[
\partial_t^2 \tilde{u} - \Delta_{\tilde{g}} \tilde{u} = 0
\]
with initial data
\[
\tilde{u}(0, \tilde{x}) = \tilde{f}(\tilde{x}) \quad \text{and} \quad \partial_t \tilde{u}(0, \tilde{x}) = 0,
\]
then
\[
u(t, x) = \sum_{\alpha \in \Gamma} \tilde{u}(t, \alpha(\tilde{x}))
\]
satisfies the wave equation in \( M \) with respect to the metric \( g \) with initial data
\[
u(0, x) = f(x) \quad \text{and} \quad \partial_t \nu(0, x) = 0.
\]

Hence,
\[
\cos(\tau \sqrt{-\Delta_g})f(x) = \sum_{\alpha \in \Gamma} \cos(\tau \sqrt{-\Delta_g}) \tilde{f}(\alpha(\tilde{x})),
\]
from which we obtain the relationship

$$\cos(\tau \sqrt{-\Delta g})(x, y) = \sum_{a \in \Gamma} \cos(\tau \sqrt{-\Delta \tilde{g}})(a(\tilde{x}), \tilde{y})$$

between the kernels. Using this identity, we will have the bound (2.2.2) if we can show

$$\sum_{a \in \Gamma} \left| \int \int b(s)b(t)K_{T,\lambda}(\tilde{\gamma}_\alpha(s), \tilde{\gamma}(t)) \, ds \, dt \right| \lesssim 1 + e^{C T \lambda^{-1/2}}$$

(2.2.3)

where $\tilde{\gamma}$ is a lift of $\gamma$ to the universal cover, $\tilde{\gamma}_\alpha$ is shorthand for $\alpha \circ \tilde{\gamma}$, and

$$K_{T,\lambda}(x, y) = \int (1 - \beta(\tau))\tilde{\chi}(\tau/T) e^{-i\lambda \tau} \cos(\tau \sqrt{-\Delta \tilde{g}})(x, y) \, d\tau.$$

Proposition 5.1 in [12] stated below, gives a crucial characterization of the kernel $K_{T,\lambda}$.

**Proposition 2.1** (Sogge, Xi, Zhang). If $d_{\tilde{g}}(x, y) \geq 1$ and $\lambda \gg 1$ we can write

$$K_{T,\lambda}(x, y) = \lambda^{1/2} \sum_{\pm} a_{\pm}(T, \lambda; x, y)e^{\pm i \lambda d_{\tilde{g}}(x, y)} + R_{T,\lambda}(x, y),$$

where

$$|a_{\pm}(T, \lambda; x, y)| \leq C,$$  \hspace{1cm} (2.2.4)

and if $N = 1, 2, \ldots$ is fixed

$$\Delta_x^N a_{\pm}(T, \lambda; x, y) = O(e^{C N d_{\tilde{g}}(x, y)})$$  \hspace{1cm} (2.2.5)

and

$$\Delta_y^N a_{\pm}(T, \lambda; x, y) = O(e^{C N d_{\tilde{g}}(x, y)}),$$  \hspace{1cm} (2.2.6)

where $\Delta_x$ and $\Delta_y$ denote the operator $\Delta_{\tilde{g}}$ acting in the $x$ and $y$ variables, respectively. Additionally, if the constant $c > 0$ in (2.1.2) is small enough,

$$R_{T,\lambda}(x, y) = O(\lambda^{-1}) \quad \text{if } d_{\tilde{g}}(x, y) \geq 1$$  \hspace{1cm} (2.2.7)

and

$$K_{T,\lambda}(x, y) = O(\lambda^{-1}) \quad \text{if } d_{\tilde{g}}(x, y) \leq 1.$$  \hspace{1cm} (2.2.8)

By (2.2.8), the contribution of the identity term to the sum in (2.2.3) is $O(\lambda^{-1})$, better than we

---

1Sogge, Xi, and Zhang [12] prove this proposition using the Hadamard parametrix as it appears in Bérard [1].
need. Hence we need only check that
\[
\sum_{\alpha \in \Gamma \setminus I} \left| \iint b(s)b(t)K_{T,\lambda}(\tilde{\gamma}_\alpha(s), \tilde{\gamma}(t)) \, ds \, dt \right| \lesssim 1 + e^{CT} \lambda^{-1/2}. \tag{2.2.9}
\]
where \( I \) denotes the identity element in \( \Gamma \). By Huygen’s principle and since \( \text{supp} \hat{\chi} \subset [-1, 1] \), the kernel \( K_{T,\lambda} \) is supported on \( d_\delta(x, y) \leq T \), and so the sum in (2.2.9) is finite. In fact, by volume comparison with the plane of constant curvature, there are \( O(e^{CT}) \) many terms in the sum. Since the injectivity radius of \( M \) is at least 10, (2.1.3) implies \( d_\delta(\tilde{\gamma}_\alpha(s), \tilde{\gamma}(t)) \geq 8 \) for \( s, t \in \text{supp} b \) if \( \alpha \neq I \).

Hence by (2.2.7),
\[
\sum_{\alpha \neq I} \left| \iint b(s)b(t)R_{T,\lambda}(\tilde{\gamma}_\alpha(s), \tilde{\gamma}(t)) \, ds \, dt \right| \lesssim \lambda^{-1} e^{CT},
\]
again satisfying better bounds than required. Hence, it suffices to show
\[
\lambda^{1/2} \sum_{\alpha \neq I} \left| \iint b(s)b(t)a_\pm(T, \lambda; \tilde{\gamma}_\alpha(s), \tilde{\gamma}(t))e^{\pm i \lambda \phi_\alpha(s, t)} \, ds \, dt \right| \lesssim 1 + e^{CT} \lambda^{-1/2} \tag{2.2.10}
\]
where \( \phi_\alpha(s, t) = d_\delta(\tilde{\gamma}_\alpha(s), \tilde{\gamma}(t)) \), for those finitely many \( \alpha \neq I \) over which the sum (2.2.9) is supported.

We approach the bound (2.2.10) by splitting the sum into two parts. After perhaps smoothly extending \( \gamma \) past its endpoints, the continuity of \( k \) allows us to select an open interval \( \mathcal{I} \) containing \( \text{supp} b \) on which the curvature hypotheses (1.2.5) are satisfied. We fix a constant \( R \) independent of \( T \) and \( \lambda \) to be determined later, and let
\[
A = \{ \alpha \in \Gamma : \inf_{s, t \in \mathcal{I}} d_\delta(\tilde{\gamma}_\alpha(s), \tilde{\gamma}(t)) \leq R \}. \tag{2.2.11}
\]
We will have the bound (2.2.10) if we can prove the following respective medium- and large- time bounds.

**Proposition 2.2.** For any \( \alpha \in \Gamma \setminus I \), there exists a constant \( C_\alpha \) such that
\[
\left| \iint b(s)b(t)a_\pm(T, \lambda; \tilde{\gamma}_\alpha(s), \tilde{\gamma}(t))e^{\pm i \lambda \phi_\alpha(s, t)} \, ds \, dt \right| \leq C_\alpha \lambda^{-1/2}
\]
for \( \lambda > 1 \).

**Proposition 2.3.** There exists a constant \( C \) independent of \( T \) and \( \lambda \) such that for every \( \alpha \in \Gamma \setminus A \)
with \( \inf_{s,t \in I} \phi_{\alpha}(s, t) \leq T \),

\[
\left| \int \int b(s)b(t)a_{\pm}(T, \lambda; \tilde{\gamma}_{\alpha}(s), \tilde{\gamma}(t))e^{\pm i\lambda \phi_{\alpha}(s, t)} \, ds \, dt \right| \leq Ce^{CT} \lambda^{-1}
\]

Since \( A \) has a fixed number of terms, Proposition 2.2 implies that the contribution of the set \( A \) to the sum to (2.2.10) is \( O(1) \). Moreover because \( K_{T,\lambda}(x, y) \) vanishes for \( d_{\tilde{g}}(x, y) > T \), we need only consider the terms \( \alpha \in \Gamma \setminus A \) such that \( \phi_{\alpha}(s, t) \leq T \) for some \( s, t \in \text{supp} b \). As noted earlier, there are \( O(e^{CT}) \) many such terms, and so Proposition 2.3 tells us the contribution of the set \( \Gamma \setminus A \) to the sum in (2.2.10) is \( O(e^{CT} \lambda^{-1/2}) \), as desired. To prove Propositions 2.2 and 2.3, we will use the geometric tools from [14] to obtain bounds on the derivatives of \( \phi_{\alpha} \) and then apply stationary phase.
Geometric Tools

To prove Propositions 2.2 and 2.3, we will need bounds on the derivatives of the phase function $\phi_\alpha$ for $\alpha \neq I$. In section 3.1, we bound the mixed partial derivative $\partial_s \partial_t \phi_\alpha$ and compute $\partial^2_s \phi_\alpha$ and $\partial^2_t \phi_\alpha$ in terms of the curvature of $\gamma$ and the curvature of circles. We prove Proposition 2.2 using these tools and the method of stationary phase.

In section 3.2, we verify that $k$ in Definition 1.2 is well-defined, continuous, and nonnegative. We then show that both $k$ as a function along a geodesic and the curvature of geodesic circles of increasing radius satisfy the same ordinary differential equation. From this we deduce some key properties and relationships between $k$ and the curvature of circles of large radius. This allows us to provide some very useful bounds on the pure second derivatives of $\phi_\alpha$ at large enough distances, and to deduce Corollaries 1.5 and 1.6 from Theorem 1.3. [5] is the principal reference for the geometric arguments which follow.

3.1 The Second Derivatives of the Phase Function

Let $F : I \times I \times \mathbb{R} \to \mathbb{R}^2$ be the smooth map to the universal cover defined so that $r \mapsto F(s, t, r)$ is the unique constant-speed geodesic with $F(s, t, 0) = \tilde{\gamma}(t)$ and $F(s, t, 1) = \gamma_\alpha(s)$. If $\partial_s$, $\partial_t$, and $\partial_r$ are the coordinate vector fields living in the domain of $F$, then the Lie brackets $[\partial_s, \partial_t]$, $[\partial_s, \partial_r]$ and $[\partial_t, \partial_r]$ all vanish. Hence,

$$\frac{D}{ds} \partial_t F - \frac{D}{dt} \partial_s F = [\partial_s F, \partial_t F] = [F_s \partial_s, F_t \partial_t] = F_s [\partial_s, \partial_t] = 0 \quad (3.1.1)$$
and
\[ \frac{D}{ds} \partial_s F - \frac{D}{dr} \partial_r F = 0 \quad \text{and} \quad \frac{D}{dt} \partial_t F - \frac{D}{dr} \partial_r F = 0 \] (3.1.2)
similarly. Now,
\[ \phi_\alpha^2(s, t) = \int_0^1 |\partial_r F(s, t, r)|^2 dr, \]
and taking a derivative in \( s \) yields
\begin{align*}
\phi_\alpha(s, t) \partial_s \phi_\alpha(s, t) &= \int_0^1 \left( \frac{D}{ds} \partial_r F(s, t, r), \partial_r F(s, t, r) \right) dr \\
&= \int_0^1 \partial_r \langle \partial_s F(s, t, r), \partial_r F(s, t, r) \rangle dr \\
&= \langle \tilde{\gamma}_\alpha'(s), \partial_r F(s, t, 1) \rangle \\
&= \langle \tilde{\gamma}_\alpha'(s), \partial_r F(s, t, 1) \rangle (3.1.3)
\end{align*}
where the second line follows from (3.1.2) and the geodesic equation \( \frac{D}{dr} \partial_r F = 0 \), and the third line from the fundamental theorem of calculus and the observation that \( \partial_s F(s, t, 0) = 0 \). Moreover, since the curves \( \tilde{\gamma} \) and \( \tilde{\gamma}_\alpha \) are disjoint, \( \phi_\alpha \) is nonvanishing. We then have the following fact (also noted in [4] and [12]): \( \partial_r \phi_\alpha(s, t) \) vanishes if and only if \( \tilde{\gamma}_\alpha \) is perpendicular to the geodesic adjoining \( \tilde{\gamma}_\alpha(s) \) and \( \tilde{\gamma}(t) \), and similarly if \( \partial_t \phi_\alpha \) vanishes. The gradient \( \nabla \phi_\alpha(s, t) \) vanishes if and only if \( \tilde{\gamma} \) and \( \tilde{\gamma}_\alpha \) are both perpendicular to the geodesic adjoining \( \tilde{\gamma}_\alpha(s) \) and \( \tilde{\gamma}(t) \).

Now we compute the mixed partial derivative \( \partial_s \partial_t \phi_\alpha \). Taking a derivative in \( t \) of (3.1.3) yields
\[ \partial_s \phi_\alpha(s, t) \partial_t \phi_\alpha(s, t) + \phi_\alpha(s, t) \partial_t \partial_s \phi_\alpha(s, t) = \langle \tilde{\gamma}_\alpha'(s), \partial_r F(s, t, 1) \rangle \] (3.1.4)
We claim that
\[ \left| \frac{D}{dr} \partial_s F(s, t, 1) \right| \leq 1, \] (3.1.5)
which, along with the observation that \( |\tilde{\gamma}_\alpha'|, |\partial_s \phi_\alpha|, \) and \( |\partial_t \phi_\alpha| \) are all bounded above by \( 1 \), yields the following bound.

**Lemma 3.1.**
\[ |\partial_s \partial_t \phi_\alpha| \leq 2 \phi_\alpha^{-1}. \]

**Proof.** In light of (3.1.4), it suffices only to verify our claim (3.1.5). For fixed \( s \) and \( t \) we write \( \partial_s F \) as the sum of parallel and perpendicular parts
\[ \partial_s F = f(r) \partial_r F + h(r) \partial_r F^\perp. \]
Now,

\[ 1 = |\partial_s F(s, t, 0)|^2 = f(0)^2 + h(0)^2, \]

and since \( \frac{D}{dt} \partial_s F = 0 \) (and indeed also \( \frac{D}{dt} \partial_s F^\perp = 0 \)), it suffices to show that

\[ f'(1) = -f(0) \quad \text{and} \quad |h'(1)| \leq |h(0)|. \]  \hspace{1cm} (3.1.6)

Since \( f \partial_s F \) and \( h \partial_s F^\perp \) are parallel and perpendicular Jacobi fields along \( r \mapsto F(s, t, r) \), respectively, we have

\[ f'' = 0, \]

from which the first part of (3.1.6) follows, and

\[ h'' + \tilde{K} h = 0 \]

where \( \tilde{K} = \tilde{K}(F(s, t, r)) \) is the sectional curvature of \((\mathbb{R}^2, \tilde{g})\). We assume without loss of generality by our choice of \( F^\perp \) that \( h(0) \geq 0 \). Since \( \tilde{K} \leq 0 \), \( h \) vanishes uniquely at 1, and so \( h(r) > 0 \) for \( 0 < r < 1 \). Again since \( \tilde{K} \leq 0 \), \( h \) is convex on \([0, 1]\). In particular,

\[ 0 \leq h(r) \leq h(0)(1 - r), \]

so

\[ 0 \geq h'(1) \geq -h(0), \]

from which we obtain the second part of (3.1.6). \( \square \)

Now we compute \( \partial_s^2 \phi_\alpha \). Fix \( t_0 \) and let \( r \mapsto \zeta(s, r) \) denote the unit speed geodesic with \( \zeta(s, 0) = \tilde{\gamma}(t_0) \) and \( \zeta(s, \phi_\alpha(s, t_0)) = \tilde{\gamma}_\alpha(s) \). To avoid ambiguity in the notation, we fix \( s_0 \) and let \( r_0 = \phi_\alpha(s_0, t_0) \), and compute \( \partial_s^2 \phi_\alpha(s_0, t_0) \). By (3.1.3),

\[ \partial_s \phi_\alpha(s, t_0) = \langle \tilde{\gamma}'_\alpha(s), \partial_r \zeta(s, \phi_\alpha(s, t_0)) \rangle. \]

Differentiating in \( s \) yields

\[ \partial_s^2 \phi_\alpha(s_0, t_0) = \left\langle \frac{D}{ds} \tilde{\gamma}'_\alpha(s_0), \partial_r \zeta(s_0, r_0) \right\rangle + \left\langle \tilde{\gamma}'_\alpha(s_0), \frac{D}{ds} \bigg|_{s=s_0} \partial_r \zeta(s, \phi(s, t_0)) \right\rangle. \]  \hspace{1cm} (3.1.7)

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Figure 3.1: \( \tilde{\gamma} \) and \( \tilde{\gamma}_\alpha \) (solid) and the angle \( \theta \) between \( \tilde{\gamma}_\alpha \) and a geodesic circle (dashed) with center on \( \tilde{\gamma} \).

Now

\[
\frac{D}{ds} \mid_{s=s_0} \partial_r \zeta(s, \phi(s, t_0)) = \frac{D}{ds} \partial_r \zeta(s_0, r_0) + \partial_s \phi(s_0, t_0) \frac{D}{dr} \partial_r \zeta(s_0, r_0).
\]

The second term on the right vanishes since \( r \mapsto \zeta(s, r) \) is a geodesic. The curve \( s \mapsto \zeta(s, r_0) \) is a geodesic circle of radius \( r_0 \). Hence, \( \partial_r \zeta \) and \( \partial_s \zeta \) are perpendicular by Gauss’ lemma. Since in addition \( |\partial_r \zeta| = 1 \), there exists a scalar \( \kappa \) such that

\[
\frac{D}{ds} \partial_r \zeta = \kappa \partial_s \zeta. \tag{3.1.8}
\]

In fact, \( \kappa(s_0, r_0) \) is the geodesic curvature of the circle \( s \mapsto \zeta(s, r_0) \) at \( s = s_0 \). Hence, we write (3.1.7) as

\[
\partial_s^2 \phi(s_0, t_0) = \left\langle \frac{D}{ds} \tilde{\zeta}'_\alpha(s_0), \partial_r \zeta(s_0, r_0) \right\rangle + \kappa(s_0, r_0) \langle \tilde{\zeta}'_\alpha(s_0), \partial_s \zeta(s_0, r_0) \rangle. \tag{3.1.9}
\]

Let \( \theta \in [0, \pi/2] \) denote the angle of intersection between the curve \( \tilde{\gamma}_\alpha \) and the circle \( s \mapsto \zeta(s, r_0) \) (see Figure 3.1). We have

\[
\tilde{\zeta}'_\alpha(s_0) = \frac{\partial}{\partial s} \bigg|_{s=s_0} \zeta(s, \phi(s, t_0)) = \partial_s \zeta(s_0, r_0) + \partial_s \phi(s_0, t_0) \partial_r \zeta(s_0, r_0),
\]

and since \( \partial_r \zeta \) and \( \partial_s \zeta \) are perpendicular,

\[
\langle \tilde{\zeta}'_\alpha(s_0), \partial_s \zeta(s_0, r_0) \rangle = |\partial_s \zeta(s_0, r_0)|^2 = \cos^2(\theta).
\]
Lemma 3.2. Let $\theta$ and $\kappa$ be as above. Then,

$$\partial^2_t \phi_{\alpha}(s_0, t_0) = \cos(\theta)(\pm \kappa_r(s_0) + \cos(\theta)\kappa(s_0, r_0)),$$

(3.1.10)

where $\pm$ matches the sign of $\langle \frac{D}{ds} \tilde{\gamma}_{\alpha}', \partial_r \zeta \rangle$. The analogous computation holds for $\partial^2_s \phi_{\alpha}$.

With Lemma 3.2 in hand, we turn our attention to the proof of Proposition 2.2.

Proof of Proposition 2.2. Since $A$ is fixed and finite, we may restrict the support of $b$ without worrying about doing so uniformly over elements of $A$. Fix $\alpha \in A \setminus I$. Let $D$ denote the diagonal of $I \times I$. We claim that

$$D \subset \{ \partial^2_t \phi_{\alpha} \neq 0 \} \cup \{ \partial^2_s \phi_{\alpha} \neq 0 \} \cup \{ \nabla \phi_{\alpha} \neq 0 \}$$

(3.1.11)

Provided our claim holds, we take the support of $b$ small enough so that $\text{supp} b \times \text{supp} b$ lies entirely in one of the three open sets above. If $\text{supp} b \times \text{supp} b$ lies in one of the first two sets, the proposition follows by stationary phase [11, Theorem 1.1.1] in the appropriate variable. If $\text{supp} b \times \text{supp} b$ is contained in the third set, then the proposition follows from nonstationary phase [11, Lemma 0.4.7].

To prove (3.1.11), we suppose $s_0 = t_0$ and $\nabla \phi_{\alpha}(s_0, t_0) = 0$ and $\partial^2_s \phi_{\alpha}(s_0, t_0) = 0$ and show that $\partial^2_t \phi_{\alpha}(s_0, t_0) \neq 0$. By (3.1.10),

$$0 = \pm \kappa_r(s_0) + \kappa(s_0, r_0)$$

where $r_0 = \phi_{\alpha}(s_0, t_0)$. This tells us $\pm$ must take the negative sign, and that $\tilde{\gamma}_{\alpha}$ is curved “towards” $\tilde{\gamma}(t_0)$. This means that $\tilde{\gamma}$ must be curved “away” from $\tilde{\gamma}_{\alpha}(s_0)$, since otherwise the midpoint of the geodesic connecting $\tilde{\gamma}(t_0)$ and $\tilde{\gamma}_{\alpha}(s_0)$ would be fixed by the deck transformation $\alpha$ (see Figure 3.2). Hence $\partial^2_t \phi_{\alpha}(s_0, t_0) > 0$ by the analogous computation to (3.1.10).

3.2 Curvature of circles

Fix $t_0$ and let $\kappa$ be as in (3.1.8). To apply (3.1.10) in any useful way, we need to know something about the function $\kappa(s, r)$, the curvature of a geodesic circle of radius $r$ centered $\tilde{\gamma}(t_0)$, and how it relates to $k$. Before this, though, we verify Definition 1.2.

Proposition 3.3. The function $k : SM \to \mathbb{R}$ in Definition 1.2 is well-defined, continuous, and nonnegative.
Figure 3.2: Impossible (top) and possible (bottom) configurations of a normal geodesic adjoining $\tilde{\gamma}(t_0)$ and $\tilde{\gamma}_\alpha(s_0)$ at $t_0 = s_0$.

**Proof.** Let $\zeta$ and $J$ be as in Definition 1.2. By properties of Jacobi fields, $k(v)$ is independent of the choice of direction of $J(0)$, and so we fix one. Since both $J(0)$ and $\frac{D}{dr} J(0)$ are perpendicular to $\zeta'(0)$,

$$\langle J(r), \zeta'(r) \rangle = 0 \quad \text{for all } r.$$

We write

$$J(r) = h(r) w(r)$$

where $w(r)$ is the vector at $\zeta(r)$ obtained through a parallel transport of $J(0)$ and where $h$ satisfies

$$h'' + Kh = 0 \quad \text{and} \quad h(0) = 1. \quad (3.2.1)$$

Here $K = K(\zeta(r))$ is the sectional curvature at $\zeta(r)$. It suffices to show the existence and uniqueness of such an $h$ with

$$|h(r)| \leq C \quad \text{for } r \leq 0 \quad (3.2.3)$$

and afterwards set $k(v) = h'(0)$. Note $k(v)$ is necessarily nonnegative since otherwise (3.2.3) would break by convexity. The difference of two such functions $h_1$ and $h_2$ satisfies (3.2.1) and (3.2.3) and $(h_1 - h_2)'(0) = 0$. If $(h_1 - h_2)'(0) \neq 0$, then $(h_1 - h_2)(r)$ is unbounded for $r \leq 0$ by convexity. Hence, $h_1 = h_2$ identically. This proves uniqueness.
To prove existence, we construct a bounded \( h \) as a limit. For all \( s > 0 \), let \( h_s \) denote the unique function satisfying (3.2.1), (3.2.2), and \( h_s(-s) = 0 \). We set

\[
h_{\infty} = \lim_{s \to \infty} h_s = h_1 + \int_1^{\infty} \partial_s h_s \, ds. \tag{3.2.4}
\]

We will show

\[
|\partial_s h_s(r)| \leq -\frac{r}{s^2} \quad \text{for } r \leq 0, \tag{3.2.5}
\]

which guarantees uniform convergence of (3.2.4) for \( r \) in compact sets, whence \( h_{\infty} \) satisfies (3.2.1) by regularity. Moreover for \( r \leq 0 \),

\[
h_{\infty}(r) = \int_{-r}^{\infty} \partial_s h_s(r) \, ds \leq 1
\]

which is stronger than required. We now prove (3.2.5). \( h_s \) vanishes uniquely at \(-s\) since \( K \leq 0 \). Hence, \( h_s \geq 0 \) and so \( h_s'' \geq 0 \) on \([-s, 0]\). Since \( h_s(0) = 1 \) and \( h_s(-s) = 0 \),

\[
0 \leq h_s(r) \leq \left( 1 + \frac{r}{s} \right) \quad \text{for } -s \leq r \leq 0
\]

by convexity. We conclude that

\[
0 < h'_s(-s) \leq \frac{1}{s}
\]

by writing \( h'_s(-s) \) using the limit definition of the derivative and applying the previous inequality. Since \( h_s(-s) = 0 \) for all \( s > 0 \),

\[
0 = \frac{d}{ds} h_s(-s) = -h'_s(-s) + \partial_s h_s(-s)
\]

whence

\[
0 < \partial_s h_s(-s) \leq \frac{1}{s}. \tag{3.2.6}
\]

\( \partial_s h_s \) satisfies (3.2.1) with initial data \( \partial_s h_s(0) = 0 \). Since \( \partial_s h_s(-s) > 0 \), a similar convexity argument yields

\[
0 < \partial_s h_s(r) \leq -\partial_s h_s(-s) \frac{r}{s} \quad \text{for } -s \leq r < 0.
\]

(3.2.5) follows from the above inequality and (3.2.6).

Finally, we show \( k \) is continuous on \( SM \). To do so, we show that \( k \) is continuous on every continuous path \( t \mapsto v(t) \) in \( SM \). If \( r \mapsto \zeta(t, r) \) is the geodesic with \( \partial_r \zeta(t, 0) = v(t) \), we let \( h_{\infty}(t, r) \)
and $h_r(t, r)$ be as constructed above along the geodesic $r \mapsto \zeta(t, r)$. In the limit as $t \to 0$, the sectional curvature $K(\zeta(t, r))$ converges to $K(\zeta(0, r))$ uniformly for $r$ in a compact set. Combined with (3.2.1), we have for any $\varepsilon > 0$ and $s > 0$ a $\delta > 0$ such that

$$|h_s(t, r) - h_s(0, r)| < \frac{\varepsilon}{3} \quad \text{for} \quad -s \leq r \leq 0$$

if $|t| < \delta$. Moreover if $r$ lies in some compact set, by (3.2.5) and the fundamental theorem of calculus, there exists $s > 0$ large enough such that

$$|h_\infty(t, r) - h_s(t, r)| < \frac{\varepsilon}{3}$$

independently of $t$. Putting these bounds together, we have

$$|h_\infty(t, r) - h_\infty(0, r)| 
\leq |h_\infty(t, r) - h_s(t, r)| + |h_s(t, r) - h_s(0, r)| + |h_s(0, r) - h_\infty(0, r)| < \varepsilon,$$

i.e. $h_\infty(t, r) \to h_\infty(0, r)$ uniformly for $r$ in a compact set. By regularity, $\partial_r h(t, r) \to \partial_r h(0, r)$ as $t \to 0$, and in particular $k(v(t)) \to k(v(0))$. \hfill $\square$

Let $\tilde{k}$ denote the function on $S\mathbb{R}^2$ for which $\tilde{k}(\tilde{v}) = k(v)$ wherever $\tilde{v} \in S\mathbb{R}^2$ is a lift of $v \in SM$. Since the covering map is a local isometry, $\tilde{k}$ satisfies Definition 1.2 where $M$ in the definition is replaced with the universal cover. Furthermore, we can loosen Definition 1.2 a little bit. Let $v$, $\zeta$, and $J$ be as in Definition 1.2 except with $M$ replaced by the universal cover. If $|J(0)|$ is allowed to be any positive number, we have

$$\tilde{k}(v) = \frac{|Dv J(0)|}{|J(0)|}.$$ 

Since $J$ is a perpendicular Jacobi field along $\zeta$,

$$J(r) = h(r)w(r)$$

where $w$ is a unit normal vector field along $\zeta$ and $h$ satisfies

$$h''(r) + \tilde{K}(\zeta(r))h(r) = 0.$$
We conclude that
\[ \dot{k}(\zeta'(r)) = \frac{|\frac{d}{dr}J(r)|}{|J(r)|} = \frac{h'(r)}{h(r)} \text{ for all } r \geq 0. \]

It follows
\[ \frac{d}{dr} \dot{k}(\zeta'(r)) = \frac{h''(r)}{h(r)} - \frac{h'(r)^2}{h(r)^2} = -\ddot{K}(\zeta(r)) - \dot{k}(\zeta'(r))^2. \] (3.2.7)

Note by the same argument for (3.1.1),
\[ \frac{D}{ds} \partial_r \zeta = \frac{D}{dr} \partial_s \zeta. \]

This and (3.1.8) yields
\[ \frac{D^2}{dr^2} \partial_s \zeta = \frac{D}{dr} (\kappa \partial_s \zeta) = \partial_r \kappa \partial_s \zeta + \kappa \frac{D}{dr} \partial_s \zeta = \left( \partial_r \kappa + \kappa^2 \right) \partial_s \zeta \]
where \( \kappa \) is the geodesic curvature of the circle \( s \mapsto \zeta(s, r) \) with center at \( \tilde{\gamma}(t_0) \) and radius \( r \) as before.

On the other hand since \( \partial_s \zeta \) is a perpendicular Jacobi field along \( r \mapsto \zeta(s, r) \),
\[ \frac{D^2}{dr^2} \partial_s \zeta = -\tilde{K} \partial_s \zeta. \]

Putting these together, we obtain
\[ \partial_r \kappa + \kappa^2 + \tilde{K} = 0, \] (3.2.8)
the same differential equation that \( k \) satisfies in (3.2.7). As a consequence, we deduce the following facts.

**Lemma 3.4.** Let \( r \mapsto \zeta(r) \) be a unit-speed geodesic in \((\mathbb{R}^2, \tilde{g})\) and \( \kappa(r) \) the geodesic curvature at \( \zeta(r) \) of the circle of radius \( r \) with center at \( \zeta(0) \). Moreover, suppose \( 0 \geq \tilde{K}_0 \geq K \geq \tilde{K}_1 \) for some constants \( \tilde{K}_0 \) and \( \tilde{K}_1 \). The following are true.

1. \( 0 < \kappa(r) - \dot{k}(\partial_r \zeta(r)) \leq r^{-1} \) for all \( r > 0 \).

2. \( \sqrt{-\tilde{K}_0} \leq \dot{k}(v) \leq \sqrt{-\tilde{K}_1} \) for all \( v \in S \tilde{M} \).

3. For \( r > 0 \),
\[ \kappa(r) \geq \begin{cases} \sqrt{-\tilde{K}_0} \coth(\sqrt{-\tilde{K}_0} r) & \text{if } \tilde{K}_0 < 0, \\ 1/r & \text{if } \tilde{K}_0 = 0. \end{cases} \]
Proof. (1) Since both $\kappa$ and $\tilde{k}$ satisfy (3.2.8), the difference $\kappa - \tilde{k}$ satisfies
\[
\partial_r (\kappa - \tilde{k}) = -(\kappa^2 - \tilde{k}^2).
\]
(3.2.9)

Since $\kappa(r)$ is large for small $r$, we can easily guarantee that $\kappa(r_0) > \tilde{k}(\zeta'(r))$ for $0 < r \ll 1$. Now $\kappa$ and $\tilde{k}$ are smooth for $r > 0$, and since $\kappa - \tilde{k} = 0$ is an equilibrium of (3.2.9), we have that
\[
\kappa(r) - \tilde{k}(\zeta'(r)) > 0 \quad \text{for all } r > 0.
\]
Hence we rephrase (3.2.9) and obtain
\[
\partial_r (\kappa - \tilde{k}) = -\frac{\kappa + \tilde{k}}{\kappa - \tilde{k}} (\kappa - \tilde{k})^2 \leq - (\kappa - \tilde{k})^2,
\]
the inequality a consequence of the fact that $\kappa > \tilde{k}$. We then have by comparison
\[
\kappa(r) - \tilde{k}(\zeta'(r)) \leq r^{-1},
\]
as desired.

(2) $\tilde{k}$ is nonnegative and bounded by Proposition 3.3 and the compactness of $M$. Suppose $\tilde{k}(\zeta'(0)) < \sqrt{-K_0}$. By (3.2.7)
\[
\partial_r \tilde{k}(\zeta'(r)) > 0 \quad \text{wherever} \quad \tilde{k}(\zeta'(r)) < \sqrt{-K_0},
\]
and hence
\[
\tilde{k}(\zeta'(r)) < \sqrt{-K_0} \quad \text{for all } r < 0.
\]
We conclude that $\partial_r \tilde{k}(\zeta'(r))$ is positive and bounded away from 0 for $r < 0$, and hence $\tilde{k}(\zeta'(r))$ is eventually negative if $r$ is negative enough, a contradiction. Hence, $\tilde{k}(\zeta'(0)) \geq \sqrt{-K_0}$. A similar argument shows $\tilde{k}(\zeta'(r))$ is unbounded for $r < 0$ if $\tilde{k}(\zeta'(0)) > \sqrt{-K_1}$, which supplies the right side of the inequality.

(3) Geometric considerations show $\kappa$ has initial data
\[
\lim_{r \to 0} r \kappa(r) = 1. \tag{3.2.10}
\]
Now,
\[ \kappa'(r) \geq -K_0 - \kappa(r)^2 \quad \text{for } r > 0, \]
and part (3) follows from comparison with the ordinary differential equation \( u' = -K_0 - u^2 \) with the initial data (3.2.10) and an elementary computation.

We now use the computation (3.1.10) of \( \partial_s^2 \phi_\alpha \) and Lemma 3.4 to prove some uniform bounds on the derivatives of \( \phi_\alpha \) to be used in the proof of Proposition 2.3. Recall \( I \) is some open interval containing the support of \( b \) on which \( \gamma \) satisfies the hypotheses (1.2.5) of Theorem 1.3.

**Lemma 3.5.** Suppose
\[
|\kappa_\gamma(s) - \kappa(s, \phi_\alpha(s, t))| > \varepsilon \quad \text{for all } s, t \in I
\]
for some \( \varepsilon > 0 \). Then there exist positive constants \( \delta \) and \( \eta \) independent of \( \alpha \) such that if the diameter of \( I \) is less than \( \delta \) and \( \partial_s \phi_\alpha \) is nonvanishing on \( I \times I \), then
\[
|\partial_s \phi_\alpha(s, t)| \geq \eta \quad \text{for } s, t \in \text{supp} b.
\]

On the other hand if \( \partial_s \phi_\alpha(s_0, t_0) = 0 \) for some \( s_0, t_0 \in I \), then
\[
|\partial_s^2 \phi_\alpha(s, t)| \geq \varepsilon/4 \quad \text{for } s, t \in I.
\]
This result holds similarly for derivatives in \( t \).

**Proof.** The curvature of any geodesic circle in \( (\mathbb{R}^2, \tilde{g}) \) with radius at least 1 is bounded uniformly by Lemma 3.4 and the fact that \( \tilde{k} \) is bounded. Hence, we select a global constant \( C \) so that
\[
\sup_{s \in I} \kappa_\gamma(s) + \sup_{s,t \in I} \kappa(s, \phi_\alpha(s, t)) \leq C \quad \text{for all } \alpha \neq I
\]
where \( \kappa(s, \phi_\alpha(s, t)) \) is the curvature of the circle at \( \tilde{\gamma}_\alpha(s) \), with center at \( \tilde{\gamma}(t) \) and radius \( \phi_\alpha(s, t) \) as per (3.1.8). Set
\[
\eta' = \min \left( \frac{1}{2}, \frac{\varepsilon}{2C} \right).
\]

Our first claim is that
\[
|\partial_s^2 \phi_\alpha| \geq \varepsilon/4 \quad \text{if } |\partial_s \phi_\alpha| \leq \eta'.
\]
Note first
\[ \sin(\theta) = |\partial_s \phi_\alpha(s, t_0)| \]
(see Figure 3.1), then if \(|\partial_s \phi_\alpha(s, t_0)| \leq \eta'\),
\[ \cos(\theta) \geq \sqrt{1 - \eta'^2} \geq 1 - \varepsilon/2C. \]

Since \(\eta' \leq 1/2\), we have that \(\cos(\theta) \geq 1/2\) by default. Hence,
\[ |\partial^2_s \phi_\alpha| \geq \frac{1}{2} |\pm \kappa_\gamma + \cos(\theta)\kappa| \]
\[ = \frac{1}{2} |\pm \kappa_\gamma + \kappa - (1 - \cos(\theta))\kappa| \]
\[ \geq \frac{1}{2} |\kappa_\gamma - \kappa| - \frac{1}{2} |1 - \cos(\theta)||\kappa| \]
\[ \geq \frac{1}{2} \varepsilon - \frac{1}{2} C\varepsilon \]
\[ = \frac{\varepsilon}{4}, \]
proving our claim.

Set
\[ \delta = \frac{\eta'}{2\sqrt{2}(1 + C^2)^{1/2}}. \]

By (3.1.10),
\[ |\partial^2_s \phi_\alpha| \leq C. \]

Moreover by Lemma 3.1, the fact that \(\mathcal{I}\) has diameter at most 1, and that the injectivity radius is at least 10, we have
\[ |\partial_t \partial_s \phi_\alpha(s, t)| \leq 1. \]

Hence for any \((s, t)\) and \((s_0, t_0)\) in \(\mathcal{I} \times \mathcal{I}\),
\[ |\partial_s \phi_\alpha(s, t) - \partial_s \phi_\alpha(s_0, t_0)| \leq (1 + C^2)^{1/2}|(s, t) - (s_0, t_0)| \leq \frac{\eta'}{2} \]
since the diameter of \(\mathcal{I} \times \mathcal{I}\) is no greater than \(\sqrt{2}\delta\). In particular if \(\partial_s \phi_\alpha(s_0, t_0) = 0\), then
\[ |\partial_s \phi_\alpha(s, t)| \leq \eta'/2 \quad \text{for all } s, t \in \mathcal{I} \]
and so \(|\partial^2_s \phi_\alpha(s, t)| \geq \varepsilon/4\) by our claim.
Now suppose $|\partial_s \phi_\alpha(s,t)| > 0$ for all $s,t \in \mathcal{I}$. In the case that $|\partial_s \phi_\alpha(s_0,t_0)| \leq \eta'/2$ for some $s_0,t_0 \in \mathcal{I}$, $|\partial_s \phi_\alpha(s,t)| \leq \eta'$ for all $s,t \in \mathcal{I}$, and hence $\partial_s \phi_\alpha(s,t)$ is monotonic in $s$, and so $\partial_s \phi_\alpha$ is smallest near an endpoint of $\mathcal{I}$. Since supp$b$ is closed and $\mathcal{I}$ open, the distance $d(\text{supp} b, \mathcal{I}^c)$ from supp$b$ to the complement of $\mathcal{I}$ is positive. Hence,

$$|\partial_s \phi(s,t)| \geq d(\text{supp} b, \mathcal{I}^c)\varepsilon/4 > 0.$$  

The proof is complete after setting

$$\eta = \min(\eta'/2, d(\text{supp} b, \mathcal{I}^c)\varepsilon/4).$$

\qed
Proof of Proposition 2.3

We now have all of the tools we need to prove Proposition 2.3, and hence conclude the proof of Theorem 1.3. By our hypotheses (1.2.5) on the curvature of $\gamma$, and since $k$ is continuous, we restrict the support of $b$ and also the interval $I$ so that

$$\inf_{s,t \in I} |\kappa(\gamma)(t) - k(\pm \gamma'(s))| > 2\varepsilon$$

for some small $\varepsilon > 0$. We first require $R$ in (2.2.11) be at least as large as $16\varepsilon^{-1}$ so that, by Lemma 3.1,

$$\sup_{t,s \in I} |\partial_t \partial_s \phi(\alpha)(s,t)| \leq \varepsilon/8 \quad \text{if } \alpha \in \Gamma \setminus A. \quad (4.0.1)$$

Let $\zeta$ be the map from $I \times I \times \mathbb{R}$ into the universal cover of $M$ so that $r \mapsto \zeta(s, t, r)$ be the unit-speed geodesic with $\zeta(s, t, 0) = \tilde{\gamma}(t)$ and $\zeta(s, t, \phi(\alpha)(s, t)) = \tilde{\gamma}_\alpha(s)$. Moreover let $\kappa(s, t)$ denote the curvature at $\tilde{\gamma}_\alpha(s)$ of the circle with center $\tilde{\gamma}(t)$ and radius $\phi(\alpha)(s, t)$ (see Figure 3.1). By Lemma 3.4 and our requirement that $R > 16\varepsilon^{-1}$,

$$|\kappa(s, t) - \hat{k}(\partial_r \zeta(s, t, \phi(\alpha)(s, t)))| < \varepsilon.$$ 

Hence,

$$|\kappa(s, t) - \kappa_{\gamma}(t)| > \varepsilon \quad \text{for } s, t \in I. \quad (4.0.2)$$

To summarize, we need to show

$$\left| \iint a(s, t) e^{\pm i \lambda \phi(\alpha)(s, t)} \, ds \, dt \right| \leq C e^{CT} \lambda^{-1} \quad (4.0.3)$$
where $C$ is independent of $\alpha$, and where for simplicity we have written

$$a(s, t) = b(s, t) a_{\pm}(T, \lambda; \tilde{\gamma}(s), \tilde{\gamma}(t)).$$

Considering (4.0.2), we restrict the diameter of $I$ to be less than the $\delta$ in Lemma 3.5. If $|\partial_s \phi_\alpha| > 0$ on $I \times I$, $|\partial_s \phi_\alpha| \geq \eta$ on $\text{supp} b \times \text{supp} b$ for some $\eta > 0$ independent of $\alpha$. Then we integrate by parts to write the integral in (4.0.3) as

$$\frac{1}{\pm i \lambda} \int \int \partial_s \left( \frac{a(s, t)}{\partial_s \phi_\alpha(s, t)} \right) e^{\pm i \lambda \phi_\alpha(s, t)} ds dt.$$

Now

$$|\partial_s a(s, t)| \lesssim e^{CT}$$

by (2.2.4) and (2.2.5), and since $|\partial_s \phi_\alpha| > \eta$, we have

$$\partial_s \left( \frac{a}{\partial_t \phi_\alpha} \right) \leq Ce^{CT},$$

from which the desired bound follows. We obtain the desired bound similarly if $\partial_t \phi_\alpha$ does not vanish in $I \times I$.

By Lemma 3.5, all that is left is the case that $\nabla \phi_\alpha$ vanishes at exactly one point $(s_0, t_0) \in I \times I$. By a translation, we assume without loss of generality that $(s_0, t_0) = (0, 0)$. In this case,

$$|\partial_s^2 \phi_\alpha| \geq \varepsilon/4 \quad \text{and} \quad |\partial_t^2 \phi_\alpha| \geq \varepsilon/4$$

(4.0.5)

on $I \times I$. We use a careful stationary phase argument to obtain (4.0.3). By (4.0.1) and (4.0.5),

$$\left| \begin{array}{cc} \partial_s^2 \phi_\alpha & \partial_s \partial_t \phi_\alpha \\ \partial_s \partial_t \phi_\alpha & \partial_t^2 \phi_\alpha \end{array} \right| \xi \geq c' |\xi| \quad \text{for all} \ \xi \in \mathbb{R}^2$$

for some positive constant $c'$ depending only on $\varepsilon$. Hence by the mean value theorem,

$$|\nabla \phi(s, t)| \geq c' |(s, t)| \quad \text{for all} \ s, t \in I.$$

(4.0.6)

Let $\psi \in C_0^\infty(\mathbb{R}^2)$ with $\psi(s, t) = 1$ for $|(s, t)| \leq 1/2$ and $\psi(s, t) = 0$ for $|(s, t)| \geq 1$. We write the
integral in (4.0.3) as the sum of respective parts

\[ I + II = \int \int \psi(\lambda^{1/2}s, \lambda^{1/2}t)a(s, t)e^{\pm i\lambda\phi_\alpha(s, t)} \, ds \, dt + \int \int (1 - \psi(\lambda^{1/2}s, \lambda^{1/2}t))a(s, t)e^{\pm i\lambda\phi_\alpha(s, t)} \, ds \, dt. \]

We have trivially

\[ |I| \leq Ce^{CT}\lambda^{-1}, \]

and so it suffices to bound \(II\). We define an operator

\[ L = \frac{\nabla \phi}{\pm i|\nabla \phi|^2} \cdot \nabla \]

with adjoint

\[ L^*f = -\frac{1}{\pm i\lambda} \left[ \partial_s \left( \frac{\partial_s \phi_\alpha}{|\nabla \phi_\alpha|^2} f \right) + \partial_t \left( \frac{\partial_t \phi_\alpha}{|\nabla \phi_\alpha|^2} f \right) \right]. \]

Then since

\[ Le^{\pm i\lambda\phi_\alpha} = e^{\pm i\lambda\phi_\alpha}, \]

we write

\[ II = \int \int (1 - \psi(\lambda^{1/2}s, \lambda^{1/2}t))a(s, t)Le^{\pm i\lambda\phi_\alpha(s, t)} \, ds \, dt = \int \int L^*[(1 - \psi(\lambda^{1/2}s, \lambda^{1/2}t))a(s, t)]e^{\pm i\lambda\phi_\alpha(s, t)} \, ds \, dt. \]

Firstly,

\[ \left| \partial_t \left( \frac{\partial_s \phi_\alpha}{|\nabla \phi_\alpha|^2} \right) \right| \leq C|\nabla \phi_\alpha|^{-2} \leq C|(s, t)|^{-2}. \]

since the first and second derivatives of \( \phi_\alpha \) are bounded by a constant uniform for \( \alpha \neq I \), as established by Lemma 3.1 and the proof of Lemma 3.5. Secondly,

\[ \left| \partial_s(1 - \psi(\lambda^{1/2}s, \lambda^{1/2}t)) \right| \leq \lambda^{1/2}|\partial_s \psi(\lambda^{1/2}s, \lambda^{1/2}t)| \leq C|(s, t)|^{-1}. \]

All bounds hold similarly for the derivative in \( t \). Hence by (4.0.4),

\[ |L^*[(1 - \psi(\lambda^{1/2}s, \lambda^{1/2}t))a(s, t)]| \lesssim e^{CT}\lambda^{-1}|(s, t)|^{-2} \]
and so using polar coordinates,

\[ |II| \lesssim e^{CT} \lambda^{-1} \int_{\lambda^{-1/2}}^{\text{diam } I \times I} r^{-2} r \, dr \lesssim e^{CT} \lambda^{-1} \log \lambda. \]

By (2.1.2), we absorb log \( \lambda \) into \( e^{CT} \) and obtain the desired bound.
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Curriculum Vitae

Emmett Lyons Wyman was born April 4th, 1991 in Rochester, New York.

He graduated from The University of Rochester with a BA Honors with Highest Distinction in Mathematics in May 2013, and received the Arthur S. Gale Memorial Prize for the highest performing graduating senior in mathematics.

In 2013, Wyman enrolled in Johns Hopkins University’s doctoral mathematics program. He completed his dissertation under the guidance of Christopher Sogge at Johns Hopkins University and defended on March 14th, 2018. During his time at Johns Hopkins, he wrote and submitted three manuscripts for publication and spoke on his results at the American Mathematical Society Special Session in Global Harmonic Analysis at the University of Central Florida September 2017. He had instructed a number of courses and received the Professor Joel Dean Award for extraordinary performance in undergraduate teaching.