Abstract: The reconstruction of charged particle trajectories is one of the most complex and CPU consuming parts of event processing in high energy experiments. At future hadron colliders such as the High-Luminosity Large Hadron Collider (HL-LHC) or the Future Circular Collider (FCC), the significantly increased number of simultaneous collisions will result in a much more challenging tracking environment. Concurrent algorithms exploiting modern computing architectures with many cores and accelerators are necessary to maintain and improve the tracking performance. Based on the tracking experience at LHC, the ACTS project is an attempt to encapsulate the current ATLAS software into a experiment-independent and framework-independent software designed for modern computing architectures. It provides a set of high-level track reconstruction tools which are agnostic to the details of the detection technologies and magnetic field configuration. The software has been fully tested for thread-safety to support parallel execution of the code and its data structures are optimized for vector operations to speed up linear algebra operations.

1 Introduction

The record-breaking data taking of the LHC in the second run (Run-2) between 2015 and 2018 provides chance for extraordinary exploration of the high-energy frontier. To greatly increase the sensitivity to new physics, the LHC will enter the HL-LHC \[ L = 7.5 \times 10^{34} \text{cm}^{-2}\text{s}^{-1}, \] era in 2026 with an instantaneous luminosity up to \( L = 7.5 \times 10^{34} \text{cm}^{-2}\text{s}^{-1} \), which corresponds to approximately 200 inelastic proton-proton collisions per beam crossing (pile-up). The greatly increased number of concurrent tracks from pile-up will put great pressure on CPU consumption at the LHC experiments. Highly-performant tracking software with concurrent algorithms exploiting modern computing architectures with many cores and accelerators have to be developed.

The A Common Tracking Software (ACTS) is an attempt to prepare a tracking toolkit for modern computing architectures and future colliders based on the ATLAS tracking experience with long term maintenance in mind. While the current ATLAS tracking software within the ATLAS software framework (Athena) has shown good overall performance at the LHC Run-1 and Run-2, many tracking components were not developed with a multi-threaded operation mode in mind during their design phase. The migration of Athena to multi-threaded Athena (AthenaMT) to adapt to the multi-core environment is on-going, which requires rewriting a significant amount of code in Athena. This makes the ACTS a possible alternative to the migration. It puts special emphasis on thread-safety in order to support an multi-threaded event processing and is designed to be independent of any event processing framework. ACTS also serves as an open-source platform for algorithm development for future track reconstruction.

With the advent of continuous integration (CI) techniques and git based code development, more emphasis can be put on the compilation state of the code. Hence, ACTS tries to minimise virtual interfaces and on the contrary enhances the use of compiler templating. The price of longer compilation time is hereby outweighed by generally fast code execution. Following this design
principles, ACTS uses C++ concept mechanisms rather than virtual interfaces in order to define code structures and modules.

ACTS is divided into two main components acts-core and acts-framework. The acts-core contains the detector-independent tracking toolkit. The acts-framework is a Gaudi inspired test framework, which can be used to run the continuous integration tests to ensure quality and thread-safety of the code. It allows a fast development and testing turn-around time, which is more flexible than the large software stacks of the LHC experiments. In addition to acts-core and acts-framework, the ACTS also includes a fast simulation component acts-fatras to simulate the trajectories of particles in detector with simplified material effects. For instance, input datasets used by various tracking algorithm development projects such as the Kaggle TrackML challenge and the HEP.TrkX project are provided by acts-fatras simulation with a prototype detector, i.e. the TrackML detector.

2 ACTS tracking components

At the time of writing, the current release of the acts-core is v0.10.04. The basic components needed for track reconstruction such as tracking geometry, tracking Event Data Model (EDM) and propagation engine are well-developed. Prototypes of algorithmic tracking tools including seed finding, track fitting and vertex reconstruction are implemented. The interface to support concurrent track reconstruction with multiple alignment constants, calibration constants or even magnetic field has been developed.

The detector geometry description is necessary for track propagation and material effects integration during track reconstruction. Since track reconstruction with an accurate detector description as used in full detector simulation could require large CPU time consumption, an abstraction of the detector geometry, i.e. tracking geometry, is used in track reconstruction in ATLAS tracking software. In the ACTS, the same concept of TrackingGeometry is used for track reconstruction. The Surface is the most fundamental geometrical object and could be extended to Layers and Volumes. The ACTS TrackingGeometry can be built from various geometry description such as the ATLAS GeoModel description and the DD4Hep modelling. An abstract DetectorElementBase class will help rebuild the connection between the full detector geometry description and the tracking geometry. ACTS TrackingGeometry supports various sub-detector such as the Silicon tracker, Calorimeter and Muon Chambers.

The trajectory of a charged particle in magnetic field can be described with a set of track parameters such as space coordinates and the momentum at that space point. ACTS also includes an additional time parameter per track to support timing detectors. Inheriting from the base class TrackParameters with the parameter set \((\text{loc}_1, \text{loc}_2, \phi, \theta, p, t)\), the SingleBoundParameters and SingleCurvilinearParameters are used to describe a single component trajectory in the local frame of a detector surface and in the curvilinear frame, respectively. To support the multi-component fitter such as Gaussian-Sum-Filter (GSF) which describes the non-Gaussian energy loss of electron as a weighted sum of several Gaussian distributions, a multi-component trajectory is described by MultivariantBoundParameters and MultivariantCurvilinearParameters.

To propagate initial track parameters throughout the detector, a highly-flexible Propagator is developed with the main task of integrating the motion of the particle governed by the Lorentz force in a magnetic field to the transport of track parameters. The Propagator is designed to be templated on a Stepper and a Navigator to support user-defined integration of particle motions and the tracking geometry. The adaptive Runge-Kutta-Nyström method is used as the primary integration method in ACTS. The propagate call of the Propagator also has a highly-templated
design to allow for propagation with various EDMs for track parameters and surfaces, and user-defined options including the execution of a list of actions, i.e. Actors at each integration step, and abort conditions Aborters. Material effects could be included by adding a MaterialInteractor in the Actor.

2.1 Track finding and fitting

After the detector-dependent measurement objects such as clusters or drift circles are formed from the detector response, track reconstruction uses local or global pattern recognition algorithms to identify the group of measurement objects that stem from the same particle. The local pattern recognition method usually starts with the seed finding process to search for combinations of measurement objects (typically doublets or triplets) originating from the same particle trajectory and provide an initial estimation of direction of the trajectory. Starting from the reconstructed seeds, a combinatorial Kalman filter technique is used to build all trajectory candidates in parallel by progressively adding other measurements along track propagation. In this approach, track fitting is integrated with track finding in the sentset that track parameters are updated using Kalman filter technique during the propagation.

Inspired by the seed finder in ATLAS tracking software, ACTS implements a detector-independent Seedfinder to build seeds from triplets of SpacePoints (created from either a single two-dimensional measurement, or a combination of two one-dimensional measurements): starting from a (middle) SpacePoint, SpacePoint closer (inner) or further (outer) to the SpacePoint are searched for within a window in the azimuthal angle. The inner SpacePoints and outer SpacePoints are then checked with the middle SpacePoint to form a triplet by comparing their polar angle. The selection for both the inner (outer) SpacePoint and the triplet are motivated by the helix model of track trajectory in an assumed homogeneous magnetic field: a circle in the transverse plane and a linear trajectory along the beam direction. Highly configurable selection criteria are applied to ensure both the purity and efficiency of the seeds by taking care of various properties such as potential minimum transverse momentum of the tracks, measurement errors, and region of interest for seed finding.

Transcription of the well-tested Combinatorial Kalman Filter (CKF) in ATLAS tracking software to ACTS design taking advantage of the high-performant ACTS KalmanFilter is planned. The ACTS KalmanFilter is designed to be independent of the EDM for tracks and allow for user-defined methods for filtering, smoothing, re-calibration of measurements using updated information from the track fitting and rejection of outlier measurements (measurements which are selected as incompatible with the track hypothesis). To record the track fitting results with the KalmanFilter, a flexible TrackState class is used to contain various information relevant with fitting on a specific detector surface including measurements (uncalibrated and calibrated), fitted parameters (predicted, filtered and smoothed), fit quality, propagation length and a TrackStateFlag as an interpreter of the TrackState, e.g. whether the TrackState is an outlier or not. The KalmanFilter can be included in the Actors of a propagation call. To validate the performance of the KalmanFilter, track fitting for truth trajectories generated with acts-fatras is performed. Figure 1 shows the almost 100% fitting efficiency (the fraction of truth trajectories that are processed for smoothing) of KalmanFilter studied from a sample of 10000 muons with the TrackML detector simulated with acts-fatras. Figure 2 shows the distributions of the pulls of track parameters for 10000 muons generated with momentum direction $\eta = 0$. All the distributions are Gaussian with a width close to 1, which indicates that errors of track parameters in the KalmanFilter are correctly estimated.

ACTS also includes a GaussianSumFilter prototype. The multi-component MultiStepper and
MultiMaterialInteractor are implemented. Development of multi-component MultiUpdater and MultiSmoother is in progress. Tools for vertex reconstruction [16] including IterativeVertexFinder and MultiAdaptiveVertexFitter prototype have been implemented in ACTS as well.

Figure 1: ACTS KalmanFilter efficiency as a function of eta (left) and pT (right) for a sample of 10000 muons generated with acts-fatras with the TrackML detector.

Figure 2: Distributions of pull values of the track parameters for a sample of 10000 muons with $\eta = 0$ generated with acts-fatras with the TrackML detector.

2.2 Alignment and calibration

ACTS is designed for full parallel execution. Contextual data, i.e. detector alignment, calibration data, detector or magnetic field status are handled with context or payload objects that guarantee to provide access to the correct conditions in memory in a concurrent environment. An AlgorithmContext which includes a GeometryContext object, a CalibrationContext object and a MagneticFieldContext object has been implemented to support on-the-fly alignment,
calibration and magnetic field. The concept of GeometryContext has been demonstrated by running the propagation test with event-dependent alignment constants in flight. The concept of CalibrationContext using detector data has been successfully used in ATLAS. Implementation of a contextual calibration tool to apply additional calibration correction to the original measurement by importing the calibration tool used in ATLAS tracking software is planned.

3 Integration of ACTS to AthenaMT

ACTS is designed to have no dependence on a particular experiment framework. A plugin mechanism is used in ACTS where necessary to allow interfacing experiment software.

Work is on-going to integrate ACTS in AthenaMT. After building an ACTS TrackingGeometry for a specific ATLAS sub-detector, ACTS can run the test of propagation of particles through the geometry. The tracking geometry for the current ATLAS Inner Detector (ID) and Calorimeter in AthenaMT has been translated to ACTS TrackingGeometry and tested for particle propagation. Implementation of ACTS TrackingGeometry for the ATLAS Muon Spectrometer is planned.

The ACTS seed finder has been tested for single particle and the result have been validated with the ATLAS seed finder. It has also been tested for multi-threaded execution in AthenaMT. Track fitting with ACTS KalmanFilter and GaussianSumFilter, and vertex reconstruction with ACTS IterativeVertexFinder and MultiAdaptiveVertexFitter with trajectories through the ATLAS detectors are planned once prototypes of those fitters are complete and well validated.

4 Summary

The large increase in track multiplicity at future colliders needs tracking software of high performance with ability to exploit parallel architectures. The ACTS project aims to provide a framework-independent and detector-independent tracking toolkit tested for strict thread-safety to support multi-threaded event processing. It is actively developed with collaboration across a range of experiments.

Tracking components including tracking geometry, EDM, propagator, seed finder are well developed. The prototype of tracking deliverables for seed finding, track fitting and vertex reconstruction are available with performance in validation. Planned future developments will focus on implementation of tools for track finding and contextual re-calibration and alignment.

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