Theory of acoustic surface plasmons

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I. INTRODUCTION

Since the early suggestion of Pines1 that low-energy plasmons with soundlike long-wavelength dispersion could be realized in the collective motion of a system of two types of electronic carriers, these modes have spurred over the years a remarkable interest and research activity.2 The possibility of having a longitudinal acoustic mode in a metal-insulator-semiconductor (MIS) structure was anticipated by Chaplik.3 Chaplik considered a simplified model in which a two-dimensional (2D) electron gas is separated from a semi-infinite three-dimensional (3D) metal. He found that the screening of valence electrons in the metal changes the 2D plasmon energy from its characteristic square-root wave-vector dependence to a linear dispersion, which was also discussed by Gumhalter4 in his study of transient interactions of surface-state electron-hole (e-h) pairs at surfaces.

Nevertheless, acoustic plasmons were only expected to exist for spatially separated plasmas, as pointed out by Das Sarma and Madhukar.5 The experimental realization of two-dimensionally confined and spatially separated multicomponent structures, such as quantum wells and heterostructures, provided suitable solid-state systems for the observation of acoustic plasmons.6 Acoustic plasma oscillations were then proposed as possible candidates to mediate the attractive interaction leading to the formation of Cooper pairs in high- Tc superconductors.7,8

Recently, Silkin et al.9 have shown that metal surfaces where a partially occupied quasi-2D surface-state band coexists in the same region of space with the underlying 3D continuum support a well-defined acoustic surface plasmon, which could not be explained within the original local model of Chaplik.3 This low-energy collective excitation exhibits linear dispersion at low wave vectors, and might therefore affect e-h and phonon dynamics near the Fermi level.10

In this paper, we present a model in which the screening of a semi-infinite 3D metal is incorporated into the description of electronic excitations in a 2D electron gas through the introduction of an effective 2D dielectric function. We find that the dynamical screening of valence electrons in the metal changes the 2D plasmon energy from its characteristic square-root behavior to a linear dispersion, not only in the case of a 2D sheet spatially separated from the semi-infinite metal, as anticipated by Chaplik,3 but also when the 2D sheet coexists in the same region of space with the underlying metal, as occurs in the real situation of surface states at a metal surface. Furthermore, our results indicate that it is the nonlocality of the 3D dynamical response which allows the formation of 2D electron-density acoustic oscillations at metal surfaces, since these oscillations would otherwise be completely screened by the surrounding 3D substrate. Unless stated otherwise, atomic units are used throughout, i.e., e2 =h=m_e=1.

II. THEORY

A variety of metal surfaces, such as Be(0001) and the (111) surfaces of the noble metals Cu, Ag, and Au, are known to support a partially occupied band of Shockley surface states with energies near the Fermi level.11 Since the wave function of these states is strongly localized near the surface and decays exponentially into the solid, they can be considered to form a 2D electron gas.

In order to describe the electronic excitations occurring within a surface-state band that is coupled with the underlying continuum of valence electrons in the metal, we consider a model in which surface-state electrons comprise a 2D electron gas at z=z_d (z denotes the coordinate normal to the
surface), while all other states of the metal comprise a 3D substrate consisting of a fixed uniform positive background (jellium) of density

\[ n_s(z) = \begin{cases} 
\bar{n}, & z \approx 0, \\
0, & \text{elsewhere},
\end{cases} \]  

(1)

plus a neutralizing inhomogeneous cloud of interacting electrons. The positive-background charge density \( \bar{n} \) is often expressed in terms of the 3D Wigner radius \( R_s^{3D} = (3/4\bar{n})^{1/3}/a_0 \), \( a_0 = 0.529 \) Å being the Bohr radius.

We consider the response of the interacting 2D and 3D electronic subsystems to an external potential \( \delta \phi_0(\mathbf{r}, \omega) \). According to time-dependent perturbation theory, keeping only terms of first order in the external perturbation, and Fourier transforming in two directions, the electron densities induced in the 2D and 3D subsystems are found to be

\[ \delta n_{2D}(z; q, \omega) = \delta(z - z_0)\chi_{2D}(q, \omega) \left[ \delta \phi_0(z; q, \omega) + \int dz' v(z, z'; q) \delta n_{3D}(z'; q, \omega) \right] \]  

(2)

and

\[ \delta n_{3D}(z; q, \omega) = \int dz' \chi_{3D}(z, z'; q, \omega) \left[ \delta \phi_0(z'; q, \omega) + \int dz'' v(z', z''; q) \delta n_{2D}(z''; q, \omega) \right] \]  

(3)

Here, \( q \) is the magnitude of the 2D wave vector parallel to the surface, \( \chi_{2D}(q, \omega) \) and \( \chi_{3D}(z, z'; q, \omega) \) are 2D and 3D interacting density response functions, respectively, \( \delta \phi_0(z; q, \omega) \) is the 2D Fourier transform of the external potential \( \delta \phi_0(\mathbf{r}, \omega) \), and \( v(z, z'; q) \) is the 2D Fourier transform of the bare Coulomb interaction

\[ v(z, z'; q) = v_q e^{-q|z-z'|}, \]  

(4)

with \( v_q = 2\pi/q \).

Combining Eqs. (2) and (3), we find

\[ \delta n_{2D}(z; q, \omega) = \delta(z - z_0)\chi_{eff}(q, \omega) \tilde{\delta}(z; q, \omega), \]  

(5)

where \( \chi_{eff}(q, \omega) = \frac{\chi_{2D}(q, \omega)}{1 - \chi_{2D}(q, \omega)[W(z_d, z_d'; q, \omega) - v_q]}, \) \( W(z_d, z_d'; q, \omega) \) being the so-called screened interaction

\[ W(z, z'; q, \omega) = v(z, z'; q) + \int dz_1 \int dz_2 \times v(z, z_1; q) \chi_{3D}(z_1, z_2; q, \omega) v(z_2, z'; q), \]  

(6)

and \( \tilde{\delta}(z; q, \omega) \) being the 2D Fourier transform of the total potential at \( z \) in the absence of the 2D sheet

\[ \tilde{\delta}(z; q, \omega) = \int dz'' \left[ \delta(z - z'') + \int dz'' v(z, z''; q) \right] \times \chi_{3D}(z', z''; q, \omega) \delta \phi_0(z''; q, \omega). \]  

(7)

Equation (5) suggests that the screening of the 3D subsystem can be incorporated into the description of the electron-density response at the 2D electron gas through the introduction of the effective density-response function of Eq. (6), whose poles should correspond to 2D electron-density oscillations.

Alternatively, we can focus on the 2D Fourier transform of the total potential at \( z \) in the presence of both 2D and 3D subsystems

\[ \phi(z; q, \omega) = \delta \phi_0(z; q, \omega) + \int dz' v(z, z'; q) \left[ \delta n_{2D}(z'; q, \omega) + \delta n_{3D}(z'; q, \omega) \right], \]  

(8)

which with the aid of Eqs. (3) and (8) can also be expressed in the following way:

\[ \phi(z; q, \omega) = \tilde{\delta}(z; q, \omega) + \int dz' W(z, z'; q, \omega) \delta n_{2D}(z'; q, \omega). \]  

(9)

Now we choose \( z = z_d \) and using Eq. (5) we write

\[ \phi(z_d; q, \omega) = [1 + W(z_d, z_d'; q, \omega) \chi_{eff}(q, \omega)] \tilde{\delta}(z_d; q, \omega), \]  

(10)

which allows one to introduce the effective inverse 2D dielectric function

\[ \varepsilon_{eff}^{-1}(q, \omega) = 1 + W(z_d, z_d'; q, \omega) \chi_{eff}(q, \omega). \]  

(11)

Since our aim is to investigate the occurrence of long-wavelength \( q \rightarrow 0 \) collective excitations, we can rely on the random-phase approximation (RPA),\(^\text{12}\) which is exact in the \( q \rightarrow 0 \) limit. In this approximation, the 2D and 3D interacting density-response functions are obtained as follows:

\[ \chi_{2D}(q, \omega) = \frac{\chi_{2D}^0(q, \omega)}{1 - \chi_{2D}^0(q, \omega)v_q}, \]  

(12)

and

\[ \chi_{3D}(z, z'; q, \omega) = \chi_{3D}^0(z, z'; q, \omega) + \int dz_1 \int dz_2 \times \chi_{3D}^0(z_1, z_2; q, \omega) v(z_1, z_2; q) \chi_{3D}(z_2, z'; q, \omega), \]  

(13)

where \( \chi_{2D}^0(q, \omega) \) and \( \chi_{3D}^0(z, z'; q, \omega) \) represent their noninteracting counterparts. An explicit expression for the 2D noninteracting density-response function \( \chi_{2D}^0(q, \omega) \) was reported by Stern.\(^\text{13}\) In order to derive explicit expressions for the 3D noninteracting density-response function \( \chi_{3D}^0(z, z'; q, \omega) \) one needs to rely on simple models, such as the hydrodynamical or infinite-barrier model, but accurate numerical calculations have been carried out\(^\text{14,15}\) from the knowledge of the eigen-
functions and eigenvalues of the Kohn-Sham Hamiltonian of density-functional theory (DFT).\textsuperscript{16}

Combining Eqs. (6), (12), and (13), one finds the RPA effective 2D dielectric function

$$\epsilon_{\text{eff}}(q, \omega) = 1 - W(z_d, z_d; q, \omega) \chi_{2D}^0(q, \omega).$$  \hfill (15)

The longitudinal modes of the 2D subsystem, or plasmons, are solutions of

$$\epsilon_{\text{eff}}(q, \omega) = 0. \hfill (16)$$

In the absence of the 3D subsystem, the 3D screened interaction $W(z, z'; q, \omega)$ reduces to the bare Coulomb interaction $v(z, z'; q)$, and the solution of Eq. (16) leads at long wavelengths to the well-known square-root wave-vector dependence of the 2D plasmon energy\textsuperscript{13}

$$\omega_{2D} = \frac{q_F}{\sqrt{m}} \sqrt{q}, \hfill (17)$$

$q_F$ and $m$ being the 2D Fermi momentum and 2D effective mass, respectively. The 2D Fermi velocity is simply

$$v_F = q_F/m.$$  \hfill (18)

In the presence of the 3D subsystem, the long-wavelength limit of the effective 2D dielectric function of Eq. (15) is found to have two zeros. One zero corresponds to a high-frequency ($\omega \gg v_F q$) oscillation in which both 2D and 3D electrons oscillate in phase with one another. The other mode corresponds to a low-frequency acoustic oscillation in which both 2D and 3D electrons oscillate out of phase.

At high frequencies, where $\omega \gg v_F q$, the long-wavelength limit of the 2D density-response function $\chi_{2D}^0(q, \omega)$ is known to be

$$\lim_{q \to 0} \chi_{2D}^0(q, \omega \gg v_F q) = \frac{1}{\pi} \frac{\omega_{2D}^2}{\omega^2}.$$  \hfill (19)

On the other hand, when the 2D sheet is located either far inside or far outside the metal surface, the long-wavelength limit of the 3D screened interaction $W(z_d, z_d; q, \omega)$ takes the form

$$\lim_{q \to 0} W(z_d, z_d; q, \omega \gg v_F q) = v_F q \frac{\omega^2}{\omega_{p,s}^2 - \omega^2}, \hfill (20)$$

where $\omega_{p,s}$ represents either the bulk-plasmon frequency $\omega_p = \sqrt{4 \pi n}$ or the conventional surface-plasmon energy $\omega_s = \omega_F / \sqrt{2}$.\textsuperscript{17} Depending on whether the 2D sheet is located inside or outside the solid. Introduction of Eqs. (18) and (19) into Eqs. (15) and (16) yields a high-frequency mode at

$$\omega^2 = \omega_{p,s}^2 + \omega_{2D}^2.$$  \hfill (21)

At low frequencies, we seek for an acoustic 2D plasmon energy that in the long-wavelength limit takes the form

$$\omega = \alpha v_F q.$$  \hfill (22)

An inspection of Eqs. (15), (22), and (23) indicates that for a low-energy acoustic oscillation to occur the quantity $I(z_d)$ must be different from zero. In that case, the long-wavelength limit of the effective 2D dielectric function of Eq. (15) has indeed a zero corresponding to a low-frequency oscillation of energy given by Eq. (21) with

$$\alpha = \sqrt{1 + \frac{(I(z_d))^2}{\pi(\pi + 2I(z_d))}}.$$  \hfill (24)

In the following, we investigate the impact of the 3D screening on the actual wave-vector dependence of the low-energy 2D collective excitation. We first consider the two limiting cases in which the 2D sheet is located far inside and far outside the solid surface, and we then carry out self-consistent calculations of the 3D screened interaction $W(z, z'; q, \omega)$, which will allow us to obtain plasmon dispersions for arbitrary locations of the 2D sheet.

A. 2D sheet far inside the metal surface

In the case of a 2D sheet that is located far inside the material surface, the 3D subsystem can safely be assumed to exhibit translational invariance in all directions, i.e., the screened interaction $W(z_d, z_d; q, \omega)$ entering Eq. (15) can be easily obtained from the knowledge of the interacting density-response function $\chi_{2D}^0(k, \omega)$ of a uniform 3D electron gas, as follows:

$$W(z_d, z_d; q, \omega) = 2 \int \frac{dk}{k^2} \epsilon_{3D}^{-1}(k, \omega),$$ \hfill (25)

where $k = \sqrt{q^2 + q_z^2}$ is the magnitude of a 3D wave vector and $\epsilon_{3D}^{-1}(k, \omega)$ is the inverse dielectric function of a uniform 3D electron gas

$$\epsilon_{3D}^{-1}(k, \omega) = 1 + \frac{4 \pi}{k^2} \chi_{3D}^0(k, \omega).$$ \hfill (26)

In the RPA,

$$\chi_{3D}^0(k, \omega) = 1 - \frac{4 \pi}{k^2} \chi_{3D}^0(k, \omega),$$ \hfill (27)

$\chi_{3D}^0(k, \omega)$ being the noninteracting density-response function first obtained by Lindhard.\textsuperscript{18}

1. Local 3D response

If one characterizes the 3D uniform electron gas by a local dielectric function $\epsilon_{3D}(\omega)$, then Eq. (25) yields

$$W_{\text{local}}(z_d, z_d; q, \omega) = v_F \epsilon_{3D}^{-1}(\omega).$$ \hfill (28)

In a 3D gas of free electrons, $\epsilon_{3D}(\omega)$ takes the Drude form
which yields

$$\lim_{q \to 0} W_{\text{local}}(z_d, z_d; q, \alpha \nu_F q) = 0.$$  

This means that in a local picture of the 3D response the characteristic collective oscillations of the 2D electron gas would be completely screened by the surrounding 3D substrate and no low-energy acoustic mode would exist.\(^19\)

### 2. Hydrodynamic 3D response

Dispersion effects of the 3D subsystem can be incorporated approximately in a hydrodynamic model. In this approximation, the dielectric function of a 3D uniform electron gas is found to be\(^18\)

$$\varepsilon_{3D}(k, \omega) = 1 - \frac{\omega_p^2}{\omega^2 - \beta^2 k^2},$$  

where \(\beta = \sqrt{1/3} k_F\) represents the speed of propagation of hydrodynamic disturbances in the electron system,\(^20\) and \(k_F\) is the 3D Fermi momentum.

Introducing Eq. (31) into Eq. (25), one finds

$$\lim_{q \to 0} W(z_d, z_d; q, \alpha \nu_F q) = 2 \pi \beta \omega_p,$$

which yields the following simple expression for the acoustic coefficient of Eq. (24):

$$\alpha = \sqrt{1 + \frac{4 \beta^2 \omega_p^2}{\omega^2}},$$  

### 3. Full 3D response

We have carried out numerical calculations of the RPA effective dielectric function of Eq. (15), by using the full \(\chi_{2D}(q, \omega)\) and \(\chi_{3D}(k, \omega)\) density-response functions, and choosing the electron-density parameters \(r_{s2D}^3 = 3.14\) and \(r_{s3D}^3 = 1.87\) corresponding to the (0001) surface of Be.\(^21\)

The results we have obtained with \(q = 0.01 a_0^{-1}\) and \(q = 0.1 a_0^{-1}\) are displayed in Figs. 1(a) and 1(b), respectively. We observe that at energies below the upper edge \(\omega_p = \nu_F q + q^2/(2m)\) (vertical dashed line) of the 2D \(e-h\) pair continuum (where 2D \(e-h\) pairs can be excited) the real part of the effective dielectric function is nearly constant and the imaginary part is large, as would occur in the absence of the 3D substrate. At energies above \(\omega_p\) momentum and energy conservation prevents 2D \(e-h\) pairs from being produced, and Im \(\varepsilon_{\text{eff}}(q, \omega)\) is very small.

Collective excitations are related to a zero of Re \(\varepsilon_{\text{eff}}(q, \omega)\) in a region where Im \(\varepsilon_{\text{eff}}(q, \omega)\) is small and lead, therefore, to a maximum in the energy-loss function Im[\(-\varepsilon_{\text{eff}}^{-1}(q, \omega)\)].\(^22\) In the absence of the 3D substrate, a 2D plasmon would occur at \(\omega_{2D} = 1.22\) eV for \(q = 0.01 a_0^{-1}\) and \(\omega_{2D} = 3.99\) eV for \(q = 0.1 a_0^{-1}\). However, Fig. 1 shows that in the presence of the 3D substrate a well-defined low-energy acoustic plasmon occurs, the sound velocity being just over the 2D Fermi velocity \(\nu_F\). The small width of the plasmon peak is entirely due to plasmon decay into \(e-h\) pairs of the 3D substrate.

We have carried out calculations of the effective 2D dielectric function of Eq. (15) for a variety of 2D and 3D electron densities, and we have found that a well-defined acoustic plasmon of energy \(\omega = \alpha \nu_F q\) is always present for 2D wave vectors up to a maximum value of \(q - q_F\) where the acoustic-plasmon dispersion merges with \(\omega_q\). The coefficient \(\alpha\) that we have obtained from the zeros in Eq. (16) is represented by stars in Fig. 2 versus the 3D Wigner radius \(r_{s3D}\), together with the prediction of Eq. (24) as obtained with the computed RPA value of \(I(z_d = -\infty)\) (solid line) and the hydrodynamic prediction of Eq. (33) (dotted line). Figure 2 shows that Eq. (33) is a good representation of the linear dispersion of this low-energy plasmon, especially at the highest 3D electron densities. Figure 2 also shows that for low electron densities the hydrodynamic prediction is too small, which is due to the fact that at low densities the long-wavelength limit of the 3D screened interaction is underestimated in this approximation.

### B. 2D sheet far outside the metal surface

In the case of a 2D sheet that is located far outside the metal surface, where the 3D electron density is negligible, the 3D screened interaction of Eq. (7) at \(z = z' = z_d\) takes the form

$$W(z_d, z_d; q, \omega) = v_q [1 - e^{-2 q z_d} g(q, \omega)],$$  

where \(g(q, \omega)\) is the so-called surface-response function of the 3D subsystem

$$g(q, \omega) = -v_q \int dz \int dz' e^{i(z + z')} \chi_{3D}(z_1, z_2; q, \omega).$$  

### 1. Local 3D response

In the simplest possible model of a metal surface, one characterizes the 3D substrate at \(z \leq 0\) by a local dielectric function which jumps discontinuously at the surface from \(\varepsilon_{3D}(\omega)\) inside the metal \((z \leq 0)\) to zero outside \((z > 0)\). Within this model,\(^23\)

$$g_{\text{local}}(q, \omega) = \frac{\varepsilon_{3D}(\omega) - 1}{\varepsilon_{3D}(\omega) + 1},$$

which is precisely the long-wavelength limit of the actual surface-response function.

At low frequencies, where \(\varepsilon_{3D}(\omega)\) is large [see Eq. (29)] and \(g_{\text{local}}(q, \omega) \to 1\), Eq. (34) yields

$$\lim_{q \to 0} W_{\text{local}}(z_d, z_d; q, \alpha \nu_F q) = 4 \pi z_d.$$  

Introducing Eq. (37) into Eq. (24), one finds
For large values of the distance \( z_d \) between the 2D sheet and the metal surface, one can write
\[
\alpha = \sqrt{1 + \frac{16z_d^2}{1 + 8z_d^2}}. \quad (38)
\]
which is the result first obtained by Chaplik\(^3\) by using the Drude-like 2D density-response function of Eq. (18).

\section*{2. Nonlocal 3D response}

An inspection of Eq. (34) shows that the long-wavelength limit of the screened interaction \( W(z_d, z_d'; q, \omega) \) is dictated not only by the local \((q=0)\) surface-response function \( g_{\text{local}}(q, \omega) \) but also by the leading correction in \( q \) of the actual nonlocal \( g(q, \omega) \). Feibelman showed that up to first order in an expansion in powers of \( q \), the surface-response function of a jellium surface can be written as\(^24\)
\[
g(q, \omega) = \frac{\epsilon_{\text{3D}}(\omega)}{\epsilon_{\text{3D}}(\omega) + 1} \left[ 1 + 2q d_\perp(\omega) \frac{\epsilon_{\text{3D}}(\omega)}{\epsilon_{\text{3D}}(\omega) + 1} \right] + O(q^2), \quad (40)
\]
compute the noninteracting density-response function, which in the static limit for a jellium slab. We first assume that the 3D electron density-response function. To ensure that our slab calculations, and find explicit expressions for the surface-functions, and then introduce a double-cosine Fourier representation for functions occurring in Eq. (24) remains unchanged, as this shows that the acoustic-plasmon sound velocity derived from the knowledge of the self-consistent electron-density parameters \( r_s^{2D} = 3.14 \) and \( r_s^{3D} = 1.87 \) corresponding to Be(0001).

The results we have obtained for a 2D sheet located at \( z_d = \lambda_F \) are displayed in Figs. 3(a) (with \( q = 0.01a_0^{-1} \)) and 3(b) (with \( q = 0.1a_0^{-1} \)), \( \lambda_F = 2\pi/k_F \) being the 3D Fermi wavelength. Figure 3 clearly shows that in the presence of the 3D substrate a well-defined low-energy acoustic plasmon occurs, the sound velocity being close to that predicted by Eq. (43) with \( d_\perp(0) = 0.2\lambda_F \) (vertical long-dashed lines). The actual plasmon energy is smaller than predicted by Eq. (43), especially at the shortest wavelengths (\( q = 0.1a_0^{-1} \)), simply due to the bending of the plasmon dispersion as a function of \( q \) (see Fig. 7 below).

C. 2D sheet at an arbitrary location

1. Hydrodynamic 3D response

An explicit expression for the screened interaction \( W(z, z'; q, \omega) \) of Eq. (7) can be obtained in a hydrodynamic model in which the 3D electron density is assumed to change abruptly at the surface from \( \bar{n} \) inside the metal to zero outside. After writing and linearizing the basic hydrodynamic equations, i.e., the continuity and the Bernoulli equation, we find

\[
\lim_{q \to 0} W(z_d, z_d'; q, \omega \tau q) = \begin{cases} 
2\pi\beta & \omega \tau > 0, z_d \approx 0, \\
4\pi\epsilon_d & \omega \tau = 0, z_d \approx 0, \\
0 & \omega \tau < 0, z_d > 0,
\end{cases}
\]

which combined with Eq. (24) yields an explicit expression for the acoustic coefficient \( \alpha \). We note that in a local description of the electronic response of the solid surface (\( \beta = 0 \)) the 3D screened interaction \( W(z_d, z_d'; q, \omega \tau q) \) is zero inside the

\[
g(q, \omega) = 1 + 2qd_\perp(0).
\]

The frequency-dependent \( d_\perp(0) \) function occurring in Eq. (40) represents the centroid of the induced 3D charge density, which in the static limit (\( \omega = 0 \)) reduces to the image plane of an external point charge.

Using Eq. (41), we find the actual long-wavelength limit of Eq. (34):

\[
\lim_{q \to 0} W(z_d, z_d; q, \omega \tau q) = 4\pi[z_d - d_\perp(0)],
\]

which combined with Eq. (24) yields

\[
\alpha = \sqrt{1 + \frac{16(z_d - d_\perp(0))^2}{1 + 8(z_d - d_\perp(0))}}.
\]

This shows that the acoustic-plasmon sound velocity derived from the local model [see Eq. (38)] remains unchanged, as long as \( z_d \) is replaced by the coordinate of the 2D sheet relative to the position of the image plane.

3. Full 3D response

In order to compute the full RPA surface-response function of Eq. (35), we follow the method described in Ref. 14 for a jellium slab. We first assume that the 3D electron density vanishes at a distance \( z_0 \) from either jellium edge, and compute the noninteracting density-response function \( \chi^0_{3D}(z, z'; q, \omega) \) from the knowledge of the self-consistent Kohn-Sham wave functions and energies of DFT, which we obtain in the local-density approximation (LDA). We then introduce a double-cosine Fourier representation for both the noninteracting and the interacting density-response functions, and find explicit expressions for the surface-response function in terms of the Fourier coefficients of the density-response function. To ensure that our slab calculations are a faithful representation of the actual surface-response function of a semiinfinite 3D system, we follow the extrapolation procedure described in Ref. 28.
solid ($z_d \leq 0$) and $4\pi z_d$ outside ($z_d > 0$). This shows that in the 2D long-wavelength limit ($q \to 0$) the nonlocality of the 3D response is only present inside the solid ($z_d \leq 0$), where finite values of the 3D momentum $k$ are possible.

Alternatively, the screened interaction $W(z, z^*; q, \omega)$ can be obtained within a specular-reflection model (SRM) or, equivalently, a classical infinite-barrier model (CIBM) of the surface, which have the virtue of describing the 3D screened interaction in terms of the bulk dielectric function $\varepsilon_{3D}(k, \omega)$ of a 3D uniform (and infinite) electron gas (see Appendix). If this bulk dielectric function is chosen to be the hydrodynamic dielectric function of Eq. (31), then these models yield Eq. (44). A more accurate description of the bulk dielectric function $\varepsilon_{3D}(k, \omega)$ yields a result that still coincides with that of Eq. (44) outside the surface ($z_d > 0$), though small differences may arise at $z_d < 0$.

When the 2D sheet is located far inside the metal ($z_d \ll 0$), Eq. (44) yields the hydrodynamic asymptotic behavior dictated by Eq. (32), and the SRM combined with the RPA bulk dielectric function yields the correct RPA asymptotic behavior. However, these hydrodynamic and specular-reflection models, which are both based on the assumption that the 3D electron density drops abruptly to zero at the surface, fail to reproduce the correct asymptotic behavior outside the surface [see Eq. (42)]. This is due to the fact that the leading correction in $q$ of the surface-response function $g(q, \omega)$ is governed by the spill out of the electron density into the vacuum, which is not present in these models.

FIG. 3. As in Fig. 1, but now for a 2D sheet that is located at one 3D Fermi wavelength outside the metal surface ($z_d = \lambda_d$). The long-dashed vertical lines here represent the plasmon energy $\omega = a_0 q$ predicted by Eq. (43) with $d = 0.2 \lambda_F$. For real frequencies, a 2D sheet that is located at $z_d = \lambda_F$ exhibits a plasmon peak that at $q = 0.01 a_0^{-1}$ is extremely sharp (as $z_d \to \infty$ the plasmon peak becomes a delta function); hence, in the calculations presented in this figure we have replaced the energy $\omega$ by a complex quantity $\omega + i \eta$ with (a) $\eta = 0.05$ eV for $q = 0.01 a_0^{-1}$ and (b) $\eta = 0$ for $q = 0.1 a_0^{-1}$.
2. Full 3D response

For an arbitrary location of the 2D sheet we need to compute the full screened interaction \( W(z_d,z_d';q,\omega) \) of Eq. (7). To calculate this quantity we consider a jellium slab, as we did to obtain the surface-response function \( g(q,\omega) \), and we find explicit expressions in terms of the Fourier coefficients of the interacting density-response function,\(^{27}\) which we compute in the RPA [see Eq. (14)] from the knowledge of the LDA eigenvalues and eigenfunctions of the Kohn-Sham Hamiltonian of DFT.

In Fig. 4, the long-wavelength limit \( I(z_d) \) of the screened interaction \( W(z_d,z_d';q,\omega) \) [see Eq. (23)] is displayed versus \( z_d \). The solid line represents the full self-consistent RPA interaction, whereas the dotted line represents the result obtained from the RPA bulk screened interaction of Eq. (25). The horizontal dashed line represents the result obtained from the RPA bulk screened interaction of Eq. (25). The 3D Wigner radius has been taken to be \( r_s^{3D} = 1.87 \).

\( I(z_d) \) the occurrence of acoustic surface plasmons is originated by a combination of the nonlocality of the 3D response and the spill out of the 3D electron density into the vacuum.

\( I(z_d) \) for the effective dielectric function of Eq. (15) (with \( q = 0.01a_0^{-1} \) [Fig. 5(a)] and \( q = 0.1a_0^{-1} \) [Fig. 5(b)]) by using the full 2D noninteracting density-response function \( \chi_{2D}(q,\omega) \) and the self-consistent RPA screened interaction \( W(z_d,z_d';q,\omega) \), with electron-density parameters \( r_s^{3D} = 3.14 \) and \( r_s^{2D} = 1.87 \) corresponding to Be(0001). In these figures the 2D sheet has been taken to be located at \( z_d = 0 \), as approximately occurs with the quasi-2D surface-state band in Be(0001). For comparison, also shown in these figures are the results we have obtained for the energy-loss function when the 2D sheet is located inside the metal at \( z_d = -\lambda_F \) and outside the metal at \( z_d = \lambda_F/2 \) and \( z_d = \lambda_F \).

An inspection of Fig. 5 shows that (i) the results we have obtained for \( z_d = -\lambda_F \) and \( z_d = \lambda_F \) are exactly reproduced by the limiting Eqs. (25) and (34) appropriate for a 2D sheet far inside and far outside the metal surface, respectively, and (ii) in the actual situation where the 2D surface-state band is located very near the jellium positive background edge \( (z_d = 0) \), a well-defined low-energy acoustic plasmon occurs, the sound velocity being very close to the limiting case of a 2D sheet far inside the metal surface and being, therefore, just above \( \omega_0 \). This is in agreement with the recent prediction that in a real metal surface where a partially occupied quasi-2D surface-state band coexists in the same region of space with the underlying 3D continuum an acoustic surface plasmon should occur at energies just above the upper edge of the 2D \( e-h \) pair continuum.\(^{5}\)

The sound velocity \( v_s(\omega=v_F q) \) of the acoustic plasmon that is visible in Fig. 5 is displayed in Fig. 6 versus the location \( z_d \) of the 2D sheet relative to the jellium edge, as obtained from our full RPA self-consistent calculation of the 2D dielectric function of Eq. (15) (open circles), together with the sound velocity \( v_s = v_F \) obtained from Eq. (43) with \( d_F(0) = 0.2a_F \) (dotted line) and the 2D sheet is located inside the metal surface, the sound velocity nicely
converges with the RPA bulk calculation from Eq. (25) (horizontal short-dashed line). When the 2D sheet is located outside the metal surface, the sound velocity converges with the limiting value $a_{\text{F}}$ obtained from Eq. (43) and $d_{\perp}(0) = 0.2 \lambda_{\text{F}}$. For comparison, also shown in this figure is the result we have obtained from Eq. (24) by using the actual RPA $I(z_d)$ screened interaction (thick solid line) and from the hydrodynamic Eq. (44). These calculations clearly show that Eq. (24) accurately reproduces the dispersion of acoustic surface plasmons, as long as the long-wavelength limit $I(z_d)$ of the screened interaction is described self-consistently with full inclusion of the electronic selvage structure at the surface.

The sound velocity of Fig. 6 (open circles) has been obtained from the effective 2D dielectric function at very low 2D momenta, where the energy of the acoustic plasmon is linear in $q$. The behavior of this plasmon energy as a function of the 2D momentum $q$ is displayed in Fig. 7, with the 2D sheet chosen to be located far inside the solid (thick dotted line), at $z_d=0$ (open circles), at $z_d=\lambda_{\text{F}}$ (solid line), and infinitely far outside the solid (solid circles). The upper edge of the 2D $e$-$h$ pair continuum is represented by a thick dashed line, showing that in the real situation where the 2D sheet is located near the jellium edge the energy of the acoustic surface plasmon (open circles) is just outside the 2D $e$-$h$ pair continuum for all momenta under study.
III. SUMMARY AND CONCLUSIONS

The partially occupied band of Shockley surface states in a variety of metal surfaces is known to form a quasi-2D electron gas that is immersed in a semiinfinite 3D gas of valence electrons. In order to describe the impact of the dynamical screening of the semi-infinite 3D continuum on the electronic excitations at the 2D electron gas of Shockley surface states, we have presented a model in which the dynamical screening of 3D valence electrons is incorporated through the introduction of an effective 2D dielectric function.

We have considered the two limiting cases in which the 2D sheet is located far inside and far outside the metal surface. In both cases, the dynamical screening of the valence electrons in the metal is found to change the 2D plasmon energy from its characteristic square-root behavior to a linear dispersion, the sound velocity being proportional to the Fermi momentum of the 2D gas. As this collective oscillation occurs in a region of 2D momentum space where 2D e-h pairs cannot be produced, this is a well-defined acoustic plasmon. The finite width of the plasmon peak is due to a small probability for the plasmon to decay into e-h pairs of the 3D substrate.

We have shown explicitly that when the 2D sheet coexists in the same region of space with the underlying 3D continuum the origin of acoustic surface plasmons, which have been overlooked over the years, is dictated by a combination of the nonlocality of the 3D response and the spill out of the 3D electron density into the vacuum, both providing incomplete screening of the 2D electron-density oscillations.

We have carried out self-consistent DFT calculations of the dynamical density-response function of the 3D system of valence electrons, and we have found that a well-defined acoustic surface plasmon exists for all possible locations of the 2D sheet relative to the metal surface. The energy dispersion of this acoustic surface plasmon is slightly higher than the energy dispersion of the acoustic plasmon occurring in a 2D sheet that is taken to be located far inside the solid (thick dotted line), at \( z_d = 0 \) (open circles), at \( z_d = \lambda_F \) (solid line), and infinitely far outside the metal (solid circles). The thick dashed line represents the upper edge \( \omega_{u} = u_{F} q + q^2/(2m) \) of the 2D e-h pair continuum. The thin dotted line represents the 2D plasmon energy \( \omega_{2D} \) dictated by Eq. (17), which is accurate at long wavelengths \( (q \rightarrow 0) \). The thick dashed line represents the 2D plasmon energy \( \sqrt{\omega_{2D}^2 + 3u_{F}^2 q^2/4} \) that is obtained after an expansion of \( \sqrt{\omega_{2D}^2 + 3u_{F}^2 q^2/4} \) in powers of \( u_{F} q/\omega \). 2D and 3D electron densities have been taken to be those corresponding to the Wigner radii \( r_{2D} = 3.14 \) and \( r_{3D} = 1.87 \), respectively. The 2D effective mass has been taken to be \( m = 1 \).

![Image 6](image6.png)

**FIG. 6.** The open circles represent the sound velocity \( u_{s} (\omega = u_{F} q) \) of the low-energy acoustic plasmon that is visible in Fig. 5 versus the location \( z_d \) of the 2D sheet with respect to the jellium edge. The horizontal short-dashed line represents the result we have obtained from the limiting Eq. (25) appropriate for a 2D sheet far inside the metal. The dotted line represents the result we have obtained from the limiting Eq. (43) with \( d_z = 0.2 \lambda_F \), which is appropriate for a 2D sheet far outside the metal. The long-wavelength limit \( u_{F} \) of the upper edge \( \omega_{u}/q \) of the 2D e-h pair continuum is represented by a horizontal long-dashed line. The thick and thin solid lines represent the results obtained from Eq. (24) by using the actual RPA \( I(z_d) \) and the hydrodynamic Eq. (44), respectively. 2D and 3D electron densities have been taken to be those corresponding to the Wigner radii \( r_{2D} = 3.14 \) and \( r_{3D} = 1.87 \), respectively. The 2D effective mass has been taken to be \( m = 1 \).

![Image 7](image7.png)

**FIG. 7.** Dispersion of the acoustic plasmon occurring in a 2D sheet that is taken to be located far inside the solid (thick dotted line), at \( z_d = 0 \) (open circles), at \( z_d = \lambda_F \) (solid line), and infinitely far outside the metal (solid circles). The thick dashed line represents the upper edge \( \omega_{u} = u_{F} q + q^2/(2m) \) of the 2D e-h pair continuum. The thin dotted line represents the 2D plasmon energy \( \omega_{2D} \) dictated by Eq. (17), which is accurate at long wavelengths \( (q \rightarrow 0) \). The thick dashed line represents the 2D plasmon energy \( \sqrt{\omega_{2D}^2 + 3u_{F}^2 q^2/4} \) that is obtained after an expansion of \( \sqrt{\omega_{2D}^2 + 3u_{F}^2 q^2/4} \) in powers of \( u_{F} q/\omega \). 2D and 3D electron densities have been taken to be those corresponding to the Wigner radii \( r_{2D} = 3.14 \) and \( r_{3D} = 1.87 \), respectively. The 2D effective mass has been taken to be \( m = 1 \).
energy of the collective excitation that has recently been predicted to exist at real metal surfaces where a quasi-2D surface-state band coexists with the underlying 3D continuum.33 Small differences between the plasmon energies obtained here and those reported previously9 are due to the absence in the present model of transitions between 2D and 3D states.

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APPENDIX: SPECULAR-REFLECTION MODEL OF THE 3D RESPONSE

Either by assuming that electrons are specularly reflected at the surface (SRM)29 or by invoking the so-called classical infinite-barrier model (CIBM) of a jellium surface,30,31 one finds

\[
W(z_d, z_d'; q, \omega) = v d \left\{ \begin{array}{ll}
1 - e^{-2q z_d} [1 - \epsilon_s(0, q; \omega)] + [1 + \epsilon_s(0, q; \omega)], & z_d \geq 0, \\
\epsilon_s(0, q; \omega) + \epsilon_s(2q z_d, q; \omega) - 2\epsilon_s^2(z_d, q; \omega)/[\epsilon_s(0, q; \omega) + 1], & \text{elsewhere},
\end{array} \right.
\]

where \( k = \sqrt{q^2 + q_z^2} \) is a 3D momentum and

\[
\epsilon_s(z; q, \omega) = \frac{q}{\pi} \int_{-\infty}^{+\infty} dq_z e^{i q z} \epsilon_{3D}(k, \omega),
\]

\( \epsilon_{3D}(q, \omega) \) being the dielectric function of a uniform (and infinite) 3D electron gas.

If the 3D dielectric function \( \epsilon_{3D}(q, \omega) \) is chosen to be the hydrodynamic dielectric function of Eq. (31), then one finds

\[
\epsilon_s(z; q, \omega) = \frac{1}{\omega^2 - \omega_p^2/\sqrt{\beta^2 q^2 + \omega_p^2}} e^{-q/\beta},
\]

which in combination with Eq. (A1) yields Eq. (44).

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On Be(0001), an occupied surface state with a binding energy of 2.8 eV at \( \Gamma \) exists in the \( \Gamma_4^+ - \Gamma_4^- \) bulk band gap. This surface state disperses with momentum parallel to the surface, thereby forming a surface-state band with a 2D Fermi energy \( \varepsilon_F = 2.8 \text{ eV} \). If one takes, for simplicity, the effective mass of surface-state electrons to be equal to the free-electron mass, the 2D Fermi momentum \( q_f \) and Wigner radius \( r_{2D} = \frac{\sqrt{2}}{q_f a_0} \) are found to be \( q_f = 0.45 a_0^{-1} \) and \( r_{2D} = 3.14 \), respectively. On the other hand, Be has two valence electrons per atom, which yields an average 3D electron density \( \bar{n} \) corresponding to the 3D Wigner radius \( r_{3D} = 1.87 \).

The energy-loss function \( \text{Im}[\varepsilon_{\text{eff}}^{-1}(q, \omega)] \) is not necessarily positive definite and may not give the true absorptive response of the combined 2D and 3D systems; however, its resonant structure is a true reflection of the modes of the system.

\( z_0 \) is chosen sufficiently large for the physical results to be insensitive to the precise value employed.

We use the Perdew-Wang [J. P. Perdew and Y. Wang, Phys. Rev. B 46, 12947 (1992)] parametrization of the Ceperley-Alder xc energy of the homogeneous electron gas [D. Ceperley and B. J. Alder, Phys. Rev. Lett. 45, 566 (1980)].

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The image-plane coordinate \( d_{1}(0) = 0.2 \lambda_F \) has been chosen in such a way that Eq. (42) reproduces the asymptotic behaviour of the full RPA calculation represented in Fig. 4 by a thick solid line.

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