DIFFUSION DETERMINES THE COMPACT MANIFOLD

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Abstract. We provide a short proof for the theorem that two compact Riemannian manifolds are isometric if and only there exists an order isomorphism which intertwines between the heat semigroups on the manifolds.

1. Introduction. Two years before the publication of Kac’s famous paper [Kac] Can one hear the shape of a drum Milnor [Mil] gave a counterexample showing that one cannot hear the shape of a compact Riemannian manifold. Milnor presented two non-isometric 16-dimensional Riemannian manifolds for which the associated Laplace–Beltrami operators have the same spectrum, i.e. are isospectral. The latter is equivalent with the existence of a unitary operator $U$ which intertwines the heat semigroups on the compact manifolds. The heat semigroups are positive, which means that they map positive functions (i.e. positive heat) to positive functions on the $L^2$-spaces of the compact manifolds. In this paper we replace the unitary operator by an order isomorphism, i.e. a linear bijective mapping $U$ such that $U\varphi \geq 0$ if and only if $\varphi \geq 0$. Then we show that the manifolds are indeed isometric. This may be interpreted in the following way. The heat semigroups are positive, which means that positive functions (heat densities) are mapped to positive functions. The orbit corresponding to a positive initial value describes the propagation of the heat density, i.e. the diffusion. Thus to say that an order isomorphism intertwines between two heat semigroups means that the positive orbits are mapped to positive orbits. So our result may be rephrased by saying that diffusion determines the compact manifold. For open connected subsets of $\mathbb{R}^d$ satisfying a weak smoothness condition Arendt [Are2] proved that diffusion determines the body (see also [Are1]). In a recent paper [ABE] this

2010 Mathematics Subject Classification: 58J53, 35P05, 47F05, 35R30.
The paper is in final form and no version of it will be published elsewhere.

DOI: 10.4064/bc112-0-1
was extended to connected Riemannian manifolds satisfying the same smoothness condition. Every compact connected Riemannian manifold satisfies this smoothness condition.

The aim of this paper is to give a direct and short proof that diffusion determines every chart \((V, x)\) where

\[
H^1(M) = \{ \varphi \in L_2(M) : \varphi \circ x^{-1} \in H^1(x(V)) \text{ for every chart } (V, x) \}.
\]

If \(\varphi \in H^1(M)\) and \((V, x)\) is a chart on \(M\) then set \(\frac{\partial}{\partial x^i} \varphi = (D_i(\varphi \circ x^{-1})) \circ x \in L_2(V)\), where \(D_i\) denotes the partial derivative in \(\mathbb{R}^d\). Moreover, for all \(\varphi, \psi \in H^1(M)\) there exists a unique element \(\nabla \varphi : \nabla \psi \in L_1(M)\) such that

\[
\nabla \varphi \cdot \nabla \psi \bigg|_V = \sum_{i,j=1}^d g^{ij} \left( \frac{\partial}{\partial x^i} \varphi \right) \left( \frac{\partial}{\partial x^j} \psi \right)
\]

for every chart \((V, x)\) on \(M\). Set \(|\nabla \varphi| = (\nabla \varphi : \nabla \varphi)^{1/2}\). We provide \(H^1(M)\) with the norm \(\varphi \mapsto (|\nabla \varphi|^2 + |\nabla \varphi|^2)^{1/2}\). Then \(H^1(M)\) is a Hilbert space. Define the bilinear form \(a : H^1(M) \times H^1(M) \to \mathbb{R}\) by \(a(\varphi, \psi) = \int V \nabla \varphi \cdot \nabla \psi\). Then \(a\) is a closed and positive form in \(L_2(M)\). The Laplace–Beltrami operator \(\Delta\) on \(M\) is the negative of the associated self-adjoint operator. If \((V, x)\) is a chart on \(M\) then

\[
\Delta \varphi = \sum_{i,j=1}^d \frac{1}{\sqrt{g}} \frac{\partial}{\partial x^i} g^{ij} \sqrt{g} \frac{\partial}{\partial x^j} \varphi
\]

for all \(\varphi \in C_c^\infty(V)\). Let \(S\) be the semigroup on \(L_2(M)\) generated by \(\Delta\) and let \(p \in [1, \infty)\). By the Beurling–Deny criteria the operator \(S_t|_{L_2(M) \cap L_p(M)}\) extends to a positive contraction operator on \(L_p(M)\) for all \(t > 0\). Moreover, \(S(t)\) is a \(C_0\)-semigroup. Since the semigroup \(S\) has a smooth kernel satisfying Gaussian bounds ([Sal, Theorem 5.4.12]), it follows that \(S_tC(M) \subset C(M)\) and \(S|_{C(M)}\) is a \(C_0\)-semigroup on \(C(M)\).

If \((M_1, g_1)\) and \((M_2, g_2)\) are two compact Riemannian manifolds then a map \(\tau : M_1 \to M_2\) is called an isometry if it is a \(C^\infty\)-diffeomorphism and

\[
g_2|_{\tau(p)}(\tau_*(v), \tau_*(w)) = g_1|_p(v, w)
\]

for all \(p \in M_1\) and \(v, w \in T_p M_1\). The Riemannian manifolds \((M_1, g_1)\) and \((M_2, g_2)\) are called isometric if there exists an isometry from \(M_1\) onto \(M_2\). If \(\tau : M_1 \to M_2\) is an isometry and \(p \in [1, \infty]\) then \(\varphi \circ \tau \in L_p(M_1)\) and

\[
\|\varphi \circ \tau\|_{L_p(M_1)} = \|\varphi\|_{L_p(M_2)}
\]

for all \(\varphi \in L_p(M_2)\).

A linear operator \(U : E \to F\) between two Riesz spaces is said to be a lattice homomorphism if

\[
U(\varphi \wedge \psi) = (U \varphi) \wedge (U \psi)
\]

for all \(\varphi, \psi \in E\). For alternative equivalent definitions see [AlB, Theorem 7.2]. Each lattice homomorphism \(U\) is positive, i.e. \(\varphi \geq 0\) implies \(U \varphi \geq 0\). An order isomorphism
$U: E \to F$ is a bijective mapping such that $U\varphi \geq 0$ if and only if $\varphi \geq 0$. Equivalently, $U$ is an order isomorphism if and only if $U$ is a bijective lattice homomorphism. Then also $U^{-1}$ is an order isomorphism. Recall also that each positive operator between $L_p$-spaces, or from $C(M_1)$ into $C(M_2)$ where $M_1$ and $M_2$ are compact Hausdorff spaces, is continuous by [AlB, Theorem 12.3].

The main theorem of this paper is the following.

**Theorem 1.1.** Let $(M_1, g_1)$ and $(M_2, g_2)$ be two compact Riemannian manifolds. Let $p \in [1, \infty)$. For all $j \in \{1, 2\}$ let $\Delta_j$ be the Laplace–Beltrami operator on $M_j$ and let $S^{(j)}$ and $T^{(j)}$ be the associated semigroups on $L_p(M_j)$ and $C(M_j)$. Then the following three conditions are equivalent.

I. $(M_1, g_1)$ and $(M_2, g_2)$ are isometric.

II. There exists an order isomorphism $U : L_p(M_1) \to L_p(M_2)$ such that

$$US^{(1)}_t = S^{(2)}_t U$$

for all $t > 0$.

III. There exists an order isomorphism $U : C(M_1) \to C(M_2)$ such that

$$UT^{(1)}_t = T^{(2)}_t U$$

for all $t > 0$.

Moreover, if the manifolds are connected and if $U$ is an order isomorphism as in Condition II or III then there exist $c > 0$ and a (surjective) isometry $\tau : M_2 \to M_1$ such that $U\varphi = c\varphi \circ \tau$ for all $\varphi \in L_p(M_1)$.

The implications I $\Rightarrow$ II and I $\Rightarrow$ III are an easy consequence of (I).

**2. Proof of Theorem 1.1.** The first part in the proof of Theorem 1.1 is the observation that $C^\infty$-functions are invariant under intertwining operators.

**Lemma 2.1.** Let $(M_1, g_1)$ and $(M_2, g_2)$ be two compact Riemannian manifolds. Let $p \in [1, \infty)$. For all $j \in \{1, 2\}$ let $\Delta_j$ be the Laplace–Beltrami operator on $M_j$ and let $S^{(j)}$ and $T^{(j)}$ be the associated semigroups on $L_p(M_j)$ and $C(M_j)$. Let either $U : L_p(M_1) \to L_p(M_2)$ be an order isomorphism such that

$$US^{(1)}_t = S^{(2)}_t U$$

for all $t > 0$, or $U : C(M_1) \to C(M_2)$ be an order isomorphism such that

$$UT^{(1)}_t = T^{(2)}_t U$$

for all $t > 0$. Then

(i) $UC^\infty(M_1) = C^\infty(M_2)$.

(ii) $U\varphi \geq 0$ if and only if $\varphi \geq 0$, for all $\varphi \in C^\infty(M_1)$.

(iii) $(U\varphi)(U\psi) = 0$ for all $\varphi, \psi \in C^\infty(M_1)$ with $\varphi \psi = 0$.

(iv) $\Delta_2 U\varphi = U\Delta_1 \varphi$ for all $\varphi \in C^\infty(M_1)$.
Proof. Suppose $U$ is an order isomorphism from $C(M_1)$ onto $C(M_2)$. Let $H_j$ be the generator of $T(j)$ for all $j \in \{1, 2\}$. If $\varphi \in D(H_1)$ then it follows from (2) that
\[
\frac{1}{t}(I - T_t^{(2)})U\varphi = \frac{1}{t}U(I - T_t^{(1)})\varphi
\]
for all $t > 0$. Since $U$ is continuous one deduces that $U\varphi \in D(H^{(2)})$. So $UD(H_1) \subset D(H_2)$ and $H_2U\varphi = UH_1\varphi$ for all $\varphi \in D(H_1)$. Similarly $U^{-1}D(H_2) \subset D(H_1)$ and therefore $UD(H_1) = D(H_2)$. Hence by iteration $U\cap_{n=1}^{\infty} D(H_1^n) = \cap_{n=1}^{\infty} D(H_2^n)$. But $C^\infty(M_j) = \cap_{n=1}^{\infty} D(H_j^n)$ for all $j \in \{1, 2\}$ by elliptic regularity. Here we use that the manifolds are compact. This shows (i) and (iv). Property (ii) follows since $\varphi\psi = 0$ and non-zero. So by Lemma 2.2 there exist $\psi \\in C(M_1)$ and $\varphi\psi = 0$ then $\varphi \wedge \psi = 0$ and $|U\varphi| \wedge |U\psi| = U|\varphi| \wedge U|\psi| = U(|\varphi| \wedge |\psi|) = 0$. Therefore $|U\varphi(U\psi)| = |U\varphi| |U\psi| = 0$ and $(U\varphi)(U\psi) = 0$. This implies Property (iii).

The proof on the $L_p$-spaces is similar. ■

The next lemma is a $C^\infty$-version of the Riesz representation theorem (cf. [EvG Corollary 1.8.1]).

Lemma 2.2. Let $M$ be a compact Riemannian manifold and $F : C^\infty(M) \to \mathbb{R}$ a positive linear functional such that
\[
F(\varphi)F(\psi) = 0 \text{ for all } \varphi, \psi \in C^\infty(M) \text{ with } \varphi\psi = 0. \tag{3}
\]
Then there exist $c \in [0, \infty)$ and $p \in M$ such that $F(\varphi) = c\varphi(p)$ for all $\varphi \in C^\infty(M)$.

Proof. Let $\varphi \in C^\infty(M)$. Then $\|\varphi\|_\infty \mathbf{1} - \varphi \geq 0$, so it follows from positivity that $F(\varphi) \leq F(\mathbf{1}) \|\varphi\|_\infty$. Since $C^\infty(M)$ is dense in $C(M)$ one can extend $F$ to a continuous linear function from $C(M)$ into $\mathbb{R}$. This extension is again positive since positive functions in $C(M)$ can be approximated uniformly by positive functions in $C^\infty(M)$. By the Riesz representation theorem there exists a unique Radon measure $\mu$ on $M$ such that $F(\varphi) = \int \varphi \, d\mu$ for all $\varphi \in C^\infty(M)$. Then it follows from (3) that $\mu$ is a point measure. Hence there exist $p \in M$ and $c \in [0, \infty)$ such that $F(\varphi) = c\varphi(p)$ for all $\varphi \in C^\infty(M)$. ■

Proposition 2.3. Let $(M_1, g_1)$ and $(M_2, g_2)$ be two compact Riemannian manifolds. Suppose there exists a linear bijection $U : C^\infty(M_1) \to C^\infty(M_2)$ such that

(i) $U\varphi \geq 0$ if and only if $\varphi \geq 0$, for all $\varphi \in C^\infty(M_1)$.

(ii) $(U\varphi)(U\psi) = 0$ if and only if $\varphi\psi = 0$, for all $\varphi, \psi \in C^\infty(M_1)$.

(iii) $\Delta_2 U\varphi = U\Delta_1 \varphi$ for all $\varphi \in C^\infty(M_1)$.

Then the Riemannian manifolds $(M_1, g_1)$ and $(M_2, g_2)$ are isometric.

Proof. Let $q \in M_2$. Then the map $\varphi \mapsto (U\varphi)(q)$ from $C^\infty(M_1)$ into $\mathbb{R}$ is linear, positive and non-zero. So by Lemma 2.2 there exist $\tau(q) \in M_1$ and $h(q) \in (0, \infty)$ such that
\[
(U\varphi)(q) = h(q)\varphi(\tau(q)) \tag{4}
\]
for all $\varphi \in C^\infty(M_1)$. So one obtains functions $\tau : M_2 \to M_1$ and $h : M_2 \to (0, \infty)$. Similarly, there exist $\tilde{\tau} : M_1 \to M_2$ and $\tilde{h} : M_1 \to (0, \infty)$ such that $(U^{-1}\psi)(p) = \tilde{h}(p)\psi(\tilde{\tau}(p))$ for all $\psi \in C^\infty(M_2)$ and $p \in M_1$. Then $\varphi(p) = \tilde{h}(p)h(\tilde{\tau}(p))\varphi(\tau(\tilde{\tau}(p)))$ for all $\varphi \in C^\infty(M_1)$ and $p \in M_1$. Choosing $\varphi = \mathbf{1}$ gives $\tilde{h}(p)h(\tilde{\tau}(p)) = 1$. Hence $\varphi = \varphi \circ \tau \circ \tilde{\tau}$ for all $\varphi \in C^\infty(M_1)$ and $\tau \circ \tilde{\tau} = I$. Similarly $\tilde{\tau} \circ \tau = I$ and $\tau$ is a bijection.
Choosing again \( \varphi = 1 \) in (4) gives \( h = U 1 \in C^\infty(M_2) \). Hence \( \varphi \circ \tau = h^{-1} U \varphi \in C^\infty(M_2) \) for all \( \varphi \in C^\infty(M_1) \) and \( \tau \) is a \( C^\infty \)-function. Thus \( \tau \) is a \( C^\infty \)-diffeomorphism and the two manifolds have the same dimension. Let \( d = \dim M_1 = \dim M_2 \).

It follows from Property (iii) that
\[
\Delta_2(h \cdot (\varphi \circ \tau)) = h \cdot ((\Delta_1 \varphi) \circ \tau)
\]
(5) for all \( \varphi \in C^\infty(M_1) \). Let \( q \in M_2 \). There exists a chart \((V, x)\) on \( M_1 \) such that \( \tau(q) \in V \) and \( x(\tau(q)) = 0 \). Let \( \Omega \subset M_1 \) be open such that \( \tau(q) \in \Omega \subset \overline{\Omega} \subset V \). Let \( \lambda_1, \ldots, \lambda_d \in \mathbb{R} \). For all \( t > 0 \) there exists a \( \varphi_t \in C^\infty(M_1) \) such that
\[
\varphi_t|\Omega = \exp\left(t \sum_{k=1}^{d} \lambda_k x^k\right)|\Omega.
\]
Since
\[
\Delta_1 = \sum_{i,j=1}^{d} \frac{1}{\sqrt{g_1}} \frac{\partial}{\partial x^i} g_{ij}^1 \sqrt{g_1} \frac{\partial}{\partial x^j}
\]
on \( V \) it follows that
\[
\Delta_1 \varphi_t = \sum_{i,j=1}^{d} t^2 g_{ij}^1 \lambda_i \lambda_j \varphi_t - t \lambda_i \frac{\varphi_t}{\sqrt{g_1}} \frac{\partial}{\partial x^i} (g_{ij}^1 \sqrt{g_1})
\]
on \( \Omega \). Hence
\[
\lim_{t \to \infty} t^{-2}(h \cdot ((\Delta_1 \varphi_t) \circ \tau)) \vert q = h(q) \sum_{i,j=1}^{d} g_{ij}^1(\tau(q)) \lambda_i \lambda_j.
\]
Next, \( \tau^{-1}(V), y \) is a chart on \( M_2 \), where \( y = x \circ \tau \). Then it follows similarly that
\[
\lim_{t \to \infty} t^{-2}(\Delta_2(h \cdot (\varphi_t \circ \tau))) \vert q = h(q) \sum_{i,j=1}^{d} g_{ij}^2(\tau(q)) \lambda_i \lambda_j.
\]
But then (5) gives
\[
\sum_{i,j=1}^{d} g_{ij}^1(\tau(q)) \lambda_i \lambda_j = \sum_{i,j=1}^{d} g_{ij}^2(q) \lambda_i \lambda_j
\]
for all \( \lambda_1, \ldots, \lambda_d \in \mathbb{R} \) and \( (g_{ij}^1 \circ \tau) \vert q = g_{ij}^2(q) \) for all \( i, j \in \{1, \ldots, d\} \). Hence \( g_{1ij}|_{\tau(q)} = g_{2ij}|_{\tau(q)} \). In particular,
\[
g_{1}|_{\tau(q)}\left( \frac{\partial}{\partial x^i}, \frac{\partial}{\partial x^j} \right) = g_{2}|_{\tau(q)}\left( \frac{\partial}{\partial y^i}, \frac{\partial}{\partial y^j} \right) = g_{2}|_{q}\left( (\tau^{-1})_* \frac{\partial}{\partial x^i}, (\tau^{-1})_* \frac{\partial}{\partial x^j} \right)
\]
for all \( i, j \in \{1, \ldots, d\} \). Hence \( \tau \) is an isometry from \((M_2, g_2)\) onto \((M_1, g_1)\). ■
Now the implications $I \Rightarrow I$ and $III \Rightarrow I$ in Theorem 1.1 follow easily from Lemma 2.1 and Proposition 2.3. Substituting $\varphi = 1$ in (5) gives $\Delta_2 h = 0$ in the proof of Proposition 2.3. If $M_2$ is connected this implies that $h$ is constant. Then the last part in Theorem 1.1 is obvious.

Acknowledgements. The second named author is most grateful for the hospitality extended to him during a fruitful stay at the University of Ulm. He wishes to thank the University of Ulm for financial support. Part of this work is supported by the Marsden Fund Council from Government funding, administered by the Royal Society of New Zealand.

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