INSTABILITY OF THE SOLITARY WAVE SOLUTIONS FOR THE 
GENERALIZED DERIVATIVE NONLINEAR SCHRÖDINGER 
eQUATION IN THE CRITICAL FREQUENCY CASE

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ABSTRACT. We study the stability theory of solitary wave solutions for the generalized derivative nonlinear Schrödinger equation

\[ i\partial_t u + \partial_x^2 u + i|u|^{2\sigma}\partial_x u = 0. \]

The equation has a two-parameter family of solitary wave solutions of the form

\[ \phi_{\omega,c}(x) = \varphi_{\omega,c}(x) \exp \left\{ i\frac{c}{2}x - \frac{i}{2\sigma + 2} \int_{-\infty}^x \varphi_{\omega,c}^2(y) \, dy \right\}. \]

Here \( \varphi_{\omega,c} \) is some real-valued function. It was proved in [29] that the solitary wave solutions are stable if \( -2\sqrt{\omega} < c < 2z_0\sqrt{\omega} \), and unstable if \( 2z_0\sqrt{\omega} < c < 2\sqrt{\omega} \) for some \( z_0 \in (0, 1) \). We prove the instability at the borderline case \( c = 2z_0\sqrt{\omega} \) for \( 1 < \sigma < 2 \), improving the previous results in [7] where \( 3/2 < \sigma < 2 \).

1. Introduction

In this paper, we study the stability theory of the solitary wave solutions for the generalized derivative nonlinear Schrödinger equation:

\[ i\partial_t u + \partial_x^2 u + i|u|^{2\sigma}\partial_x u = 0, \quad t \in \mathbb{R}, \quad x \in \mathbb{R} \quad (1.1) \]

for \( \sigma > 0 \). It describes an Alfvén wave and appears in plasma physics, nonlinear optics, and so on (see [33, 34]). In the case of \( \sigma = 1 \), by a suitable gauge transformation, (1.1) is transformed to the standard derivative nonlinear Schrödinger equation:

\[ i\partial_t u + \partial_x^2 u + i\partial_x(|u|^2 u) = 0. \quad (1.2) \]

This equation (1.2) was widely studied. The local well-posedness was proved by Hayashi and Ozawa [18, 19] in the energy space \( H^1(\mathbb{R}) \) and by Guo and Tan [11] in the smooth space. In the paper of [18], the authors proved the global well-posedness in the energy space when the initial data \( u_0 \) satisfies the mass condition \( \|u_0\|_{L^2} < \sqrt{2\pi} \). This condition seems natural for global well-posedness in view of the mass critical nonlinear Schrödinger equation and generalized KdV equation, as it ensures an priori estimate of \( H^1 \)-norm from mass and energy conservations. However, recently, the third author extended the condition to \( \|u_0\|_{L^2} < 2\sqrt{\pi} \) in [45, 46], in which the key ingredient in the proof is the use of the momentum conservation. A simplified proof was later given by the first and third authors in their paper [15], where the global well-posedness in \( H^{3/2}(\mathbb{R}) \) was also proved under the same mass constraint. The problems

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for large mass are still unclear at the moment. In [6], Fukaya, Hayashi and Inui constructed a class of large global solution with high oscillation. In the papers of Cher, Simpson and Sulem [3], Jenkins, Liu, Perry, Sulem [22, 27, 25, 26], Pelinovsky and Shimabukuro [38, 39], the authors constructed a class of global solution by using the inverse scattering method. On the long-time behavior and modified scattering theory, see [8] and references therein. On the low regularity theory, see [1, 4, 5, 9, 10, 14, 21, 35, 36, 30, 41, 42] and the reference therein.

In the case of \( \sigma \neq 1 \), the Cauchy problems of (1.1) have been investigated by many researchers. In the case of \( \sigma > 1 \), local well-posedness in energy spaces \( H^1(\mathbb{R}) \) was studied by Hayashi and Ozawa [20] for any \( \sigma > 1 \), by Hao [16] in \( H^{1/2}(\mathbb{R}) \) for any \( \sigma > \frac{5}{2} \), and by Santos [40] in \( H^{1/2}(\mathbb{R}) \) for any \( \sigma > \frac{1}{2} \) and small data. In the case of \( 0 < \sigma < \frac{1}{2} \), local well-posedness in the some weighted spaces was studied by Linares, Ponce and Santos [28]. Note that in this case, the nonlinear term is not regular enough, appropriate construction of the working space is needed to handle nonlinearity. Global well-posedness was studied in [6, 20, 32]. In particular, in the case of \( 0 < \sigma < 1 \) the global existence (without uniqueness) of the solution in \( H^1(\mathbb{R}) \) was shown by Hayashi and Ozawa [20]; while in the case of \( \sigma > 1 \), the global well-posedness of the solution in \( H^1(\mathbb{R}) \) was shown by Hayashi and Ozawa [6, 32] with some suitable size restriction on the initial datum.

Also, the stability theory was widely studied. The equation (1.1) has a two-parameter family of solitary waves,

\[
    u_{\omega,c}(t) = e^{i\omega t} \phi_{\omega,c}(x - ct),
\]

where \( \phi_{\omega,c} \) is the solution of

\[
    \phi_{\omega,c}(x) = \varphi_{\omega,c}(x) \exp \left\{ \frac{c}{2} x - \frac{i}{2\sigma + 2} \int_{-\infty}^{x} \varphi_{\omega,c}(y) dy \right\},
\]

(1.3)

and

\[
    \varphi_{\omega,c}(x) = \left\{ \frac{2\sqrt{\omega} \cosh(\sigma \sqrt{4\omega - c^2} x) - c}{2\sigma \sqrt{\omega} \cosh(\sigma \sqrt{4\omega - c^2} x) - c} \right\}^{1/\sigma}.
\]

Note that \( \phi_{\omega,c} \) is the solution of

\[
    -\partial_x^2 \phi + \omega \phi + ci\partial_x \phi - i|\phi|^{2\sigma} \partial_x \phi = 0.
\]

(1.4)

When \( \sigma = 1 \), Colin and Ohta [2] proved the stability of the soliton waves when \( c^2 < 4\omega \), see also Guo and Wu [12] for previous result in the case of \( c > 0 \). The endpoint case \( c^2 = 4\omega, c > 0 \) was studied in [23]. Further, Le Coz and Wu [24], Miao, Tang and Xu [31] proved the stability of the multi-solitary wave solutions. A consequence of these results are a class of the arbitrary large global solutions. Note that the equation (1.3) can be solved when \( 4\omega < c^2, c \in \mathbb{R} \) or \( 4\omega = c^2, c > 0 \).

In the case of \( 0 < \sigma < 1 \), Liu, Simpson and Sulem [29] proved that the solitary wave solution \( u_{\omega,c} \) is stable for any \(-2\sqrt{\omega} < c < 2\sqrt{\omega}\), Guo [13] further proved the stability of the solitary wave solutions in the endpoint case \( 0 < c = 2\sqrt{\omega} \). In the case of \( \sigma \geq 2 \), the solitary wave solution \( u_{\omega,c} \) is unstable for any \(-2\sqrt{\omega} < c < 2\sqrt{\omega}\).
The case \(1 < \sigma < 2\) is more complicated. It was proved by Liu, Simpson and Sulem \([29]\) that there exists \(z_0(\sigma) \in (0, 1)\), which solves the equation \(F_\sigma(z) = 0\) with
\[
F_\sigma(z) = (\sigma - 1)^2 \left[ \int_0^\infty (\cosh y - z)^{-1} dy \right]^2 - \left[ \int_0^\infty (\cosh y - z)^{-\frac{1}{2}} (z \cosh y - 1) dy \right]^2,
\]
such that when \(-2\sqrt{\omega} < c < 2z_0\sqrt{\omega}\), the solitary wave solution \(u_{\omega,c}\) is unstable and when \(2z_0\sqrt{\omega} < c < 2\sqrt{\omega}\). See also Tang and Xu \([43]\) for the stability of the sum of two solitary waves. Further, Fukaya \([7]\) proved that the solitary waves solution is unstable when \(\frac{3}{2} \leq \sigma < 2\), \(c = 2z_0\sqrt{\omega}\). After the work, the stability theory of the solitary waves solution when \(1 < \sigma < \frac{3}{2}\), \(c = 2z_0\sqrt{\omega}\) is the only unknown case. In this paper, we aim to solve this left case.

Before stating our theorem, we adopt some notations. For \(\varepsilon > 0\), we define
\[
U_\varepsilon(\phi_{\omega,c}) = \{ u \in H^1(\mathbb{R}) : \inf_{(\theta,y) \in \mathbb{R}^2} \| u - e^{i\theta}\phi_{\omega,c}(-y) \|_{H^1} < \varepsilon \}.
\]

**Definition 1.** We say that the solitary wave solution \(u_{\omega,c}\) of (1.1) is stable if for any \(\varepsilon > 0\) there exists \(\delta > 0\) such that if \(u_0 \in U_\delta(\phi_{\omega,c})\), then the solution \(u(t)\) of (1.1) with \(u(0) = u_0\) exists for all \(t > 0\), and \(u(t) \in U_\varepsilon(\phi_{\omega,c})\) for all \(t > 0\). Otherwise, \(u_{\omega,c}\) is said to be unstable.

The main result in the present paper is

**Theorem 1.** Let \(1 < \sigma < 2\) and \(z_0 = z_0(\sigma) \in (-1, 1)\) satisfy \(F_\sigma(z_0) = 0\). Then the solitary wave solutions \(e^{i\omega t}\phi_{\omega,c}(x - ct)\) of (1.1) is unstable if \(c = 2z_0\sqrt{\omega}\).

In this paper, we use the same ideas as in [47]. It relies on the modulation theory and construction of the virial identities. Compared to [7], the idea is to utilize virial identities to replace the Lyapunov functional, to obtain the lower bound on modulations. This can be used to avoid the requirement of the high-order regularities of the energy. However, the construction in the present paper is much more delicate, due to the complicated structure of the equation.

This paper is organized as follows. In Section 2, we give the definitions of some important functionals and some useful lemmas. In Section 3, we obtain the modulation result and show the coercivity for the second variation. In Section 4, we prove the main theorem.

**Remark 1.** We note that the same result in Theorem 1 was obtained independently by Miao-Tang-Xu in [44] (appear on arXiv on March 20, 2018) by different method. They used the third derivative of the energy around the solitary wave.

## 2. Preliminaries

### 2.1. Notations.

We use \(A \lesssim B\) or \(A = O(B)\) to denote an estimate of the form \(A \leq CB\) for some constant \(C > 0\). Similarly, we will write \(A \sim B\) to mean \(A \lesssim B\) and \(B \lesssim A\). And we denote \(\dot{f} = \partial_t f\).

For \(u, v \in L^2(\mathbb{R}) = L^2(\mathbb{R}, \mathbb{C})\), we define
\[
\langle u, v \rangle = \text{Re} \int_\mathbb{R} u(x)\overline{v(x)} \, dx.
\]
and regard $L^2(\mathbb{R})$ as a real Hilbert space.

For a function $f(x)$, its $L^q$-norm $\|f\|_{L^q} = \left(\int_{\mathbb{R}} |f(x)|^q dx \right)^{\frac{1}{q}}$ and its $H^1$-norm $\|f\|_{H^1} = (\|f\|_{L^2}^2 + \|\partial_x f\|_{L^2}^2)^{\frac{1}{2}}$.

2.2. Conservation laws. The solution $u(t)$ of (1.1) satisfies three conservation laws, 

\[ E(u(t)) = E(u_0), \quad P(u(t)) = P(u_0), \quad M(u(t)) = M(u_0) \]

for all $t \in [0, T_{\text{max}})$, where $T_{\text{max}}$ denotes the maximal existence time of $u(t)$, and

\[
E(u) = \frac{1}{2} \|\partial_x u\|_{L^2}^2 - \frac{1}{2(\sigma + 1)} \text{Im} \int_{\mathbb{R}} |u|^{2\sigma} u \overline{\partial_x u} dx,
\]

\[
P(u) = \frac{1}{2} (i \partial_x u, u)_{L^2} = \frac{1}{2} \text{Im} \int_{\mathbb{R}} u \partial_x u dx,
\]

\[
M(u) = \frac{1}{2} \|u\|_{L^2}^2.
\]

2.3. Some functionals. From the definitions of $E$, $P$ and $M$, we have

\[ E'(u) = -\partial_x^2 u - i|u|^{2\sigma} \partial_x u, \]

\[ P'(u) = i\partial_x u, \]

\[ M'(u) = u. \]

Let

\[ S_{\omega,c}(u) = E(u) + \omega M(u) + cP(u), \]

then we have

\[ S_{\omega,c}'(u) = E'(u) + \omega M'(u) + cP'(u) \]

\[ = -\partial_x^2 u - i|u|^{2\sigma} \partial_x u + \omega u + ic\partial_x u. \quad (2.1) \]

Hence, (1.4) is equivalent to $S_{\omega,c}'(\phi) = 0$. Hence for the solution $\phi_{\omega,c}$ to (1.4), we have

\[ S_{\omega,c}'(\phi_{\omega,c}) = 0. \quad (2.2) \]

Moreover, by (2.1), we obtain

\[
S_{\omega,c}''(\phi_{\omega,c}) f = -\partial_x^2 f + \omega f + ic\partial_x f - i\sigma |\phi_{\omega,c}|^{2\sigma - 2} \overline{\phi_{\omega,c}} \partial_x \phi_{\omega,c} f \\
- i\sigma |\phi_{\omega,c}|^{2\sigma - 2} \phi_{\omega,c} \partial_x \phi_{\omega,c} f - i|\phi_{\omega,c}|^{2\sigma} \partial_x f. \quad (2.3)
\]

2.4. Useful Lemma. In this subsection, we give some lemmas which are useful in the following sections. First, we have following formulas.

**Lemma 1.** Let $1 < \sigma < 2$ and $(\omega, c) \in \mathbb{R}^2$ satisfy $c^2 < 4\omega$, we have

\[ S_{\omega,c}''(\phi_{\omega,c}) = -2\sigma i|\phi_{\omega,c}|^{2\sigma} \partial_x \phi_{\omega,c}, \quad (2.4) \]

\[ S_{\omega,c}''(i\partial_x \phi_{\omega,c}) = -2\sigma \omega |\phi_{\omega,c}|^{2\sigma} \phi_{\omega,c}. \]
Proof. First, using (2.2) and (2.3), we get

\[
S''_{\omega,c}(\phi_{\omega,c}) = -\frac{\partial^2 \phi_{\omega,c}}{\partial x^2} + 2\sigma |\phi_{\omega,c}|^{2\sigma - 2} |\phi_{\omega,c}|^2 \frac{\partial \phi_{\omega,c}}{\partial x} + i\sigma |\phi_{\omega,c}| + i\sigma |\phi_{\omega,c}|^2 \frac{\partial \phi_{\omega,c}}{\partial x} - i|\phi_{\omega,c}|^2 \frac{\partial^2 \phi_{\omega,c}}{\partial x^2}.
\]

Similarly, using (2.2) and (2.3), we obtain

\[
S''_{\omega,c}(\phi_{\omega,c})(i\frac{\partial \phi_{\omega,c}}{\partial x}) = i\frac{\partial \phi_{\omega,c}}{\partial x} \left[ -\frac{\partial^2 \phi_{\omega,c}}{\partial x^2} + 2\sigma \sigma |\phi_{\omega,c}|^{2\sigma - 2} |\phi_{\omega,c}|^2 \frac{\partial \phi_{\omega,c}}{\partial x} + i\sigma |\phi_{\omega,c}|^2 \frac{\partial \phi_{\omega,c}}{\partial x} - i|\phi_{\omega,c}|^2 \frac{\partial^2 \phi_{\omega,c}}{\partial x^2} \right] = -2\sigma i|\phi_{\omega,c}|^2 \frac{\partial \phi_{\omega,c}}{\partial x}.
\]

This concludes the proof of Lemma 1. □

Let

\[
J(u) = \text{Im} \int_{\mathbb{R}} |u|^{2\sigma} \overline{\frac{\partial u}{\partial x}} u dx.
\]

Then we have

\[
J'(u) = 2(\sigma + 1)i|u|^{2\sigma} \frac{\partial u}{\partial x}.
\]

Moreover, we have the following lemma.

Lemma 2. Let \(1 < \sigma < 2\) and \((\omega, c) \in \mathbb{R}^2\) satisfy \(c^2 < 4\omega\), then

\[
||\partial_x \phi_{\omega,c}||_{L^2}^2 = \omega ||\phi_{\omega,c}||_{L^2}^2.
\]

Moreover,

\[
J(\phi_{\omega,c}) = 4\omega M(\phi_{\omega,c}) + 2cP(\phi_{\omega,c}),
\]

\[
\frac{\sigma - 1}{\sigma + 1} J(\phi_{\omega,c}) = 2cP(\phi_{\omega,c}) + 4E(\phi_{\omega,c}),
\]

and

\[
J'(\phi_{\omega,c}) = -\frac{\sigma + 1}{\sigma} S''_{\omega,c}(\phi_{\omega,c}) \phi_{\omega,c}.
\]

Proof. From the equation \(S'_{\omega,c}(\phi_{\omega,c}) = 0\), by producing with \(\overline{x \frac{\partial \phi_{\omega,c}}{\partial x}}\) and \(\overline{\phi_{\omega,c}}\) respectively, and taking the real part, we obtain

\[
||\partial_x \phi_{\omega,c}||_{L^2}^2 = \omega ||\phi_{\omega,c}||_{L^2}^2,
\]

and

\[
||\partial_x \phi_{\omega,c}||_{L^2}^2 + \omega ||\phi_{\omega,c}||_{L^2}^2 + c \text{Im} \int_{\mathbb{R}} \phi_{\omega,c} \overline{\frac{\partial \phi_{\omega,c}}{\partial x}} dx - J(\phi_{\omega,c}) = 0.
\]

Therefore, we have

\[
J(\phi_{\omega,c}) = 4\omega M(\phi_{\omega,c}) + 2cP(\phi_{\omega,c}).
\]
Combining the definition of $E$ and \eqref{2.6}, we have

$$E(\phi_{\omega,c}) = \frac{1}{2} \| \partial_x \phi_{\omega,c} \|_{L^2}^2 - \frac{1}{2(\sigma + 1)} \text{Im} \int_{\mathbb{R}} |u|^{2\sigma} u \bar{\partial_x u} \, dx$$

$$= \omega M(\phi_{\omega,c}) - \frac{1}{2(\sigma + 1)} J(\phi_{\omega,c}).$$

Then, we get

$$\omega M(\phi_{\omega,c}) = E(\phi_{\omega,c}) + \frac{1}{2(\sigma + 1)} J(\phi_{\omega,c}).$$

Hence, we obtain

$$J(\phi_{\omega,c}) = 4 \left[ E(\phi_{\omega,c}) + \frac{1}{2(\sigma + 1)} J(\phi_{\omega,c}) \right] + 2 c P(\phi_{\omega,c})$$

$$= 2 c P(\phi_{\omega,c}) + 4 E(\phi_{\omega,c}) + \frac{2}{\sigma + 1} J(\phi_{\omega,c}).$$

That is,

$$\frac{\sigma - 1}{\sigma + 1} J(\phi_{\omega,c}) = 2 c P(\phi_{\omega,c}) + 4 E(\phi_{\omega,c}).$$

Moreover, from \eqref{2.4} and \eqref{2.5}, we have

$$J'(\phi_{\omega,c}) = 2(\sigma + 1) i |\phi_{\omega,c}|^{2\sigma} \partial_x \phi_{\omega,c}$$

$$= - \frac{\sigma + 1}{\sigma} S''_{\omega,c}(\phi_{\omega,c}) \phi_{\omega,c}.$$

This completes the proof. \hfill \Box

**Lemma 3.** Let $1 < \sigma < 2$ and $(\omega, c) \in \mathbb{R}^2$ satisfy $c^2 < 4\omega$, then

$$\| \phi_{\omega,c} \|_{L^{2\sigma + 2}}^2 = 4(\sigma + 1) \left[ \frac{c}{2} M(\phi_{\omega,c}) + P(\phi_{\omega,c}) \right],$$

and

$$\partial_c M(\phi_{\omega,c}) = \partial_\omega P(\phi_{\omega,c}), \quad \partial_\omega P(\phi_{\omega,c}) = \omega \partial_c M(\phi_{\omega,c}).$$

**Proof.** The details are given in Appendix. \hfill \Box

For any $(\omega, c) \in \mathbb{R}^2$ satisfying $c^2 < 4\omega$, we define a function $d(\omega, c)$ by

$$d(\omega, c) = S_{\omega,c}(\phi_{\omega,c}).$$

Thus, we have

$$d'(\omega, c) = \left( \partial_\omega d(\omega, c), \partial_c d(\omega, c) \right) = \left( M(\phi_{\omega,c}), P(\phi_{\omega,c}) \right),$$

and the Hessian matrix $d''(\omega, c)$ of $d(\omega, c)$ is given by

$$d''(\omega, c) = \begin{bmatrix} \partial_{\omega\omega} d(\omega, c) & \partial_{\omega c} d(\omega, c) \\ \partial_{c\omega} d(\omega, c) & \partial_{cc} d(\omega, c) \end{bmatrix} = \begin{bmatrix} \partial_\omega M(\phi_{\omega,c}) & \partial_\omega P(\phi_{\omega,c}) \\ \partial_c M(\phi_{\omega,c}) & \partial_c P(\phi_{\omega,c}) \end{bmatrix}.$$

For general exponents $1 < \sigma < 2$, Liu, Simpson and Sulem \cite{29} proved that $z_0$ is the unique solution of $\det[d''(\omega, c)] = 0$. 
Let \((\mu, \nu)\) to be the eigenvector associated to zero eigenvalue of the Hessian matrix \(d''(\omega, c)\). Since zero is the simple eigenvalue, \((\mu, \nu)\) is unique up to a constant. That is,

\[
\begin{align*}
\mu \partial_\omega M(\phi_{\omega, c}) + \nu \partial_c P(\phi_{\omega, c}) &= 0, \\
\mu \partial_c M(\phi_{\omega, c}) + \nu \partial_\omega P(\phi_{\omega, c}) &= 0.
\end{align*}
\tag{2.11}
\]

Together with \(\partial_c M(\phi_{\omega, c}) = \partial_\omega P(\phi_{\omega, c})\), (2.11) is equivalent to

\[
\begin{align*}
\mu \partial_\omega M(\phi_{\omega, c}) + \nu \partial_c M(\phi_{\omega, c}) &= 0, \\
\mu \partial_\omega P(\phi_{\omega, c}) + \nu \partial_c P(\phi_{\omega, c}) &= 0.
\end{align*}
\tag{2.12}
\]

Now we have the following lemma.

**Lemma 4.** Let \(1 < \sigma < 2\) and \((\omega, c) \in \mathbb{R}^2\) satisfy \(c = 2z_0 \sqrt{\omega}\), then

\[P(\phi_{\omega, c}) = a_0 M(\phi_{\omega, c}), \quad \frac{\mu}{\nu} = \sqrt{\omega},\]

where \(a_0 = (\sigma - 1) \sqrt{\omega} > 0\). Moreover, there exists \(\kappa_0 > 0\), such that

\[
\begin{align*}
\mu^2 \partial_\omega M(\phi_{\omega, c}) + 2\mu \nu \partial_{\omega c} M(\phi_{\omega, c}) + \nu^2 \partial_{cc} M(\phi_{\omega, c}) &= \kappa_0 z_0, \\
\mu^2 \partial_\omega P(\phi_{\omega, c}) + 2\mu \nu \partial_{\omega c} P(\phi_{\omega, c}) + \nu^2 \partial_{cc} P(\phi_{\omega, c}) &= -\kappa_0 \sqrt{\omega}.
\end{align*}
\tag{2.13}
\]

**Proof.** The proof of Lemma 4 is postponed to Appendix. 

For convenience, we denote the quality \(Q_{\mu, \nu}\) to be:

\[Q_{\mu, \nu}(f) = \mu M(f) + \nu P(f)\]

Moreover, we denote \(\psi, \tilde{\psi}\) as

\[\psi = \partial_\lambda \phi_{\omega, c} + \lambda \mu, c + \lambda \nu \big|_{\lambda = 0} = \mu \partial_\omega \phi_{\omega, c} + \nu \partial_c \phi_{\omega, c}, \quad \tilde{\psi} = \frac{1}{2} \partial_\lambda^2 \phi_{\omega, c} + \lambda \mu, c + \lambda \nu \big|_{\lambda = 0}\]

**Lemma 5.** Let \(1 < \sigma < 2\). If \(c = 2z_0 \sqrt{\omega}\), then

\[
\langle M'(\phi_{\omega, c}), \psi \rangle = \langle P'(\phi_{\omega, c}), \psi \rangle = 0, \tag{2.15}
\]

and

\[
S''_{\omega, c}(\phi_{\omega, c}) \psi = -Q_{\mu, \nu}(\phi_{\omega, c}), \quad \langle S''_{\omega, c}(\phi_{\omega, c}) \psi, \psi \rangle = 0. \tag{2.16}
\]

**Proof.** By (2.12), we get

\[
\begin{align*}
\langle M'(\phi_{\omega, c}), \mu \partial_\omega \phi_{\omega, c} + \nu \partial_c \phi_{\omega, c} \rangle &= 0, \\
\langle P'(\phi_{\omega, c}), \mu \partial_\omega \phi_{\omega, c} + \nu \partial_c \phi_{\omega, c} \rangle &= 0,
\end{align*}
\]

that is,

\[
\langle M'(\phi_{\omega, c}), \psi \rangle = \langle P'(\phi_{\omega, c}), \psi \rangle = 0.
\]

From (2.11), we have

\[
\begin{align*}
\langle \mu M'(\phi_{\omega, c}) + \nu P'(\phi_{\omega, c}), \partial_\omega \phi_{\omega, c} \rangle &= 0, \\
\langle \mu M'(\phi_{\omega, c}) + \nu P'(\phi_{\omega, c}), \partial_c \phi_{\omega, c} \rangle &= 0.
\end{align*}
\]
Therefore, we have
\[ \langle Q_{\mu,\nu}'(\phi_{\omega,c}), \psi \rangle = 0.\]

On the other hand, differentiating \( S'_{\omega+\lambda\mu, c+\lambda\nu}(\phi_{\omega+\lambda\mu, c+\lambda\nu}) = 0 \) with respect to \( \lambda = 0 \), we have
\[
S''_{\omega+\lambda\mu, c+\lambda\nu}(\phi_{\omega+\lambda\mu, c+\lambda\nu}) \partial_{\lambda} \phi_{\omega+\lambda\mu, c+\lambda\nu} \bigg|_{\lambda=0} = - \left[ \mu M'(\phi_{\omega+\lambda\mu, c+\lambda\nu}) + \nu P'(\phi_{\omega+\lambda\mu, c+\lambda\nu}) \right] \bigg|_{\lambda=0}.
\]
That is
\[
S''_{\omega, c}(\phi_{\omega,c}) \psi = - Q_{\mu,\nu}'(\phi_{\omega,c}).
\]
Thus, we have
\[
\langle S''_{\omega, c}(\phi_{\omega,c}) \psi, \psi \rangle = - \langle Q_{\mu,\nu}'(\phi_{\omega,c}), \psi \rangle = 0.
\]
This proves the lemma. \(\square\)

**Lemma 6.** Let \( 1 < \sigma < 2 \). If \( c = 2z_0\sqrt{\omega} \), then
\[
\langle J'(\phi_{\omega,c}), \psi \rangle = 4\mu M(\phi_{\omega,c}) + 2\nu P(\phi_{\omega,c}) \neq 0.
\]

**Proof.** Note that \( \psi = \partial_{\lambda} \phi_{\omega+\lambda\mu, c+\lambda\nu} \big|_{\lambda=0} \), using (2.7), we can write
\[
\langle J'(\phi_{\omega,c}), \psi \rangle = \partial_{\lambda} J(\phi_{\omega+\lambda\mu, c+\lambda\nu}) \big|_{\lambda=0} = \partial_{\lambda} \left[ 4(\omega + \lambda\mu) M(\phi_{\omega+\lambda\mu, c+\lambda\nu}) + 2(c + \lambda\nu) P(\phi_{\omega+\lambda\mu, c+\lambda\nu}) \right] \bigg|_{\lambda=0} = 4\mu M(\phi_{\omega,c}) + 2\nu P(\phi_{\omega,c}) + \langle M'(\phi_{\omega,c}), \partial_{\lambda} \phi_{\omega+\lambda\mu, c+\lambda\nu} \big|_{\lambda=0} \rangle.
\]
When \( c = 2z_0\sqrt{\omega} \), together with (2.13), we obtain
\[
\langle J'(\phi_{\omega,c}), \psi \rangle = 4\mu M(\phi_{\omega,c}) + 2\nu P(\phi_{\omega,c}) + \langle M'(\phi_{\omega,c}), \psi \rangle + \langle P'(\phi_{\omega,c}), \psi \rangle = 4\mu M(\phi_{\omega,c}) + 2\nu P(\phi_{\omega,c}).
\]
Using Lemma 4, we find
\[ 4\mu M(\phi_{\omega,c}) + 2\nu P(\phi_{\omega,c}) = \nu(4\sqrt{\omega} + 2a_0) M(\phi_{\omega,c}) \neq 0. \]
Hence, \( \langle J'(\phi_{\omega,c}), \psi \rangle \neq 0 \). This finishes the proof. \(\square\)

### 3. Modulation and the coercivity property

**Proposition 1.** There exists \( \delta_0 > 0 \), such that for any \( \delta \in (0, \delta_0) \), \( u \in U_{\delta}(\phi_{\omega,c}) \), the following properties is verified. There exist \( C^1 \)-functions
\[
(\theta, y, \lambda) : U_{\delta}(\phi_{\omega,c}) \to \mathbb{R} \times \mathbb{R} \times \mathbb{R}^+,
\]
such that if we define \( \varepsilon(t) \) by
\[
\varepsilon(t) = e^{-i\theta(t)} u(t, \cdot + y(t)) - \phi_{\omega+\lambda(t), \mu(t), c+\lambda(t), \nu(t)}, \tag{3.1}
\]
then \( \varepsilon \) satisfies the following orthogonality conditions for any \( t \in \mathbb{R} \),
\[
\langle \varepsilon, i\phi_{\omega+\lambda(t), c+\lambda(t), \nu(t)} \rangle = \langle \varepsilon, \partial_{\lambda} \phi_{\omega+\lambda(t), c+\lambda(t), \nu(t)} \rangle = \langle \varepsilon, J'(\phi_{\omega+\lambda(t), c+\lambda(t), \nu(t)}) \rangle = 0.
\]
Moreover,
\[
\langle S''_{\omega, c+\lambda(t), \nu(t)}(\phi_{\omega+\lambda(t), c+\lambda(t), \nu(t)}) \varepsilon, \varepsilon \rangle \gtrsim \|\varepsilon\|_{H^2(\mathbb{R})}^2. \tag{3.2}
\]
Thus, we can get

Therefore, the implicit function theorem implies that there exists \( \delta \) such that \( F(\theta, y, \lambda) = 0 \), such that, moreover, we have the following decomposition,

\[
\epsilon \mapsto F(\theta, y, \lambda) = a_1 \phi_{\omega,c} + a_2 \partial_x \phi_{\omega,c} + h_1,
\]

with

\[
\langle h_1, g_{-1} \rangle = \langle h_1, i \phi_{\omega,c} \rangle = \langle h_1, \partial_x \phi_{\omega,c} \rangle = 0,
\]

and

\[
\langle S''_{\omega,c}(\phi_{\omega,c}) h_1, h_1 \rangle \gtrsim \| h_1 \|^2_{H^1(\mathbb{R})}.
\]

**Proof.** The proof of the proposition can be split into the following three steps.

Step 1, modulation for fixed time. Fixing \( t \in \mathbb{R} \), let \( \overline{F}(\theta, y, \lambda; u) = (F_1, F_2, F_3) \) with

\[
F_1(\theta, y, \lambda; u) = \langle \epsilon, i \phi_{\omega+\lambda \mu_c+c+\lambda \nu} \rangle,
F_2(\theta, y, \lambda; u) = \langle \epsilon, \partial_x \phi_{\omega+\lambda \mu_c+c+\lambda \nu} \rangle,
F_3(\theta, y, \lambda; u) = \langle \epsilon, J'(\phi_{\omega+\lambda \mu_c+c+\lambda \nu}) \rangle.
\]

Note that

\[
\partial_x \epsilon \big|_{(0,0,0;\phi_{\omega,c})} = -i \phi_{\omega,c}; \quad \partial_y \epsilon \big|_{(0,0,0;\phi_{\omega,c})} = \partial_x \phi_{\omega,c}; \quad \partial_\lambda \epsilon \big|_{(0,0,0;\phi_{\omega,c})} = -\psi.
\]

Then, the Jacobian matrix of the derivative of the function \((\theta, y, \lambda; u) \mapsto \overline{F}\) with respect to \((\theta, y, \lambda)\) is as follows.

\[
D \overline{F} \bigg|_{(0,0,0;\phi_{\omega,c})} = \begin{pmatrix}
\partial_\theta F_1 & \partial_\theta F_2 & \partial_\theta F_3 \\
\partial_y F_1 & \partial_y F_2 & \partial_y F_3 \\
\partial_\lambda F_1 & \partial_\lambda F_2 & \partial_\lambda F_3
\end{pmatrix}
\]

\[
= \begin{pmatrix}
-\| \phi_{\omega,c} \|^2_{L^2} & -2P(\phi_{\omega,c}) & -\langle \psi, i \phi_{\omega,c} \rangle \\
2P(\phi_{\omega,c}) & \| \partial_x \phi_{\omega,c} \|^2_{L^2} & -\langle \psi, \partial_x \phi_{\omega,c} \rangle \\
0 & 0 & -\langle J'(\phi_{\omega,c}), \psi \rangle
\end{pmatrix}.
\]

Thus, we can get

\[
\det \left( D \overline{F} \right) \bigg|_{(0,0,0;\phi_{\omega,c})} = 4\sigma (2 - \sigma) \omega [M(\phi_{\omega,c})]^2 \langle J'(\phi_{\omega,c}), \psi \rangle.
\]

From Lemma \( \Box \) we have

\[
\det \left( D \overline{F} \right) \bigg|_{(0,0,0;\phi_{\omega,c})} \neq 0.
\]

Therefore, the implicit function theorem implies that there exists \( \delta_0 > 0 \), such that for any \( \delta \in (0, \delta_0) \), \( u \in U_\delta(\phi_{\omega,c}) \), the following properties is verified. There exist continuity functions

\[
(\theta, y, \lambda) : U_\delta(\phi_{\omega,c}) \to \mathbb{R} \times \mathbb{R} \times \mathbb{R}^+,
\]

such that \( F_j(\theta, y, \lambda; u) = 0 \), \( j = 1, 2, 3 \).

Step 2, the regularity of the parameters in time. The parameters \((\theta, y, \lambda) \in C^1_t\) can be followed from the regularization arguments.

Step 3, the coercivity property of \( S''_{\omega,c}(\phi_{\omega,c}) \). From \( [29] \) Theorem 3.1, we obtain that \( S''_{\omega,c}(\phi_{\omega,c}) \) has exactly one negative eigenvalue. Hence there exists only one \( \lambda_{-1} < 0 \), such that

\[
S''_{\omega,c}(\phi_{\omega,c}) g_{-1} = \lambda_{-1} g_{-1}, \quad \| g_{-1} \|_{L^2} = 1.
\]

Moreover, we have the following decomposition,

\[
\epsilon = a_{-1} g_{-1} + a_1 i \phi_{\omega,c} + a_2 \partial_x \phi_{\omega,c} + h_1,
\]

with

\[
\langle h_1, g_{-1} \rangle = \langle h_1, i \phi_{\omega,c} \rangle = \langle h_1, \partial_x \phi_{\omega,c} \rangle = 0,
\]

and

\[
\langle S''_{\omega,c}(\phi_{\omega,c}) h_1, h_1 \rangle \gtrsim \| h_1 \|^2_{H^1(\mathbb{R})}.
\]
Since \( \langle \varepsilon, i \phi_{\omega,c} \rangle = \langle \varepsilon, \partial_x \phi_{\omega,c} \rangle = 0 \), we have \( a_1 = a_2 = 0 \). Then, we can write
\[
\varepsilon = a_{-1}g_{-1} + h_1.
\]

Next, using (2.9), we have
\[
J'(\phi_{\omega,c}) = S''_{\omega,c}(\phi_{\omega,c})(-\frac{\sigma + 1}{\sigma} \phi_{\omega,c}).
\]

For convenience, we put
\[
h = -\frac{\sigma + 1}{\sigma} \phi_{\omega,c}.
\]

Note that \( \langle h, i \phi_{\omega,c} \rangle = \langle h, \partial_x \phi_{\omega,c} \rangle = 0 \), we can also write that
\[
h = b_{-1}g_{-1} + h_2
\]
with
\[
\langle h_2, g_{-1} \rangle = \langle h_2, i \phi_{\omega,c} \rangle = \langle h_2, \partial_x \phi_{\omega,c} \rangle = 0,
\]
and
\[
\langle S''_{\omega,c}(\phi_{\omega,c})h_2, h_2 \rangle \gtrsim \|h_2\|_{H^1(\mathbb{R})}^2.
\]

For simplicity, we denote
\[
\gamma = -\langle S''_{\omega,c}(\phi_{\omega,c})h, h \rangle = -\langle J'(\phi_{\omega,c}), h \rangle = \frac{2(\sigma + 1)^2}{\sigma} J(\phi_{\omega,c}).
\]

Then, from (2.7) and Lemma 4, we know \( \gamma > 0 \).

Moreover, we have
\[
\begin{align*}
\langle S''_{\omega,c}(\phi_{\omega,c})\varepsilon, \varepsilon \rangle &= \lambda_{-1}a_{-1}^2 + \langle S''_{\omega,c}(\phi_{\omega,c})h_1, h_1 \rangle, \\
\langle S''_{\omega,c}(\phi_{\omega,c})h, h \rangle &= \lambda_{-1}b_{-1}^2 + \langle S''_{\omega,c}(\phi_{\omega,c})h_2, h_2 \rangle = -\gamma < 0.
\end{align*}
\]

According to the orthogonality condition \( \langle \varepsilon, J'(\phi_{\omega,c}) \rangle = 0 \) and some direct computations, we have
\[
\lambda_{-1}a_{-1}b_{-1} + \langle S''_{\omega,c}(\phi_{\omega,c})h_1, h_2 \rangle = 0.
\]

Together with (3.3), (3.4), (3.5) and the Cauchy-Schwartz inequality, we obtain that
\[
-\lambda_{-1}a_{-1}^2 = \frac{\lambda_{-1}a_{-1}^2b_{-1}}{-\lambda_{-1}b_{-1}^2} = \frac{\langle S''_{\omega,c}(\phi_{\omega,c})h_1, h_2 \rangle^2}{\gamma + \langle S''_{\omega,c}(\phi_{\omega,c})h_2, h_2 \rangle} \leq \frac{\langle S''_{\omega,c}(\phi_{\omega,c})h_1, h_1 \rangle \langle S''_{\omega,c}(\phi_{\omega,c})h_2, h_2 \rangle}{\gamma + \langle S''_{\omega,c}(\phi_{\omega,c})h_2, h_2 \rangle}.
\]

Thus, we get
\[
\langle S''_{\omega,c}(\phi_{\omega,c})\varepsilon, \varepsilon \rangle \geq -\frac{\langle S''_{\omega,c}(\phi_{\omega,c})h_1, h_1 \rangle \langle S''_{\omega,c}(\phi_{\omega,c})h_2, h_2 \rangle}{\gamma + \langle S''_{\omega,c}(\phi_{\omega,c})h_2, h_2 \rangle} + \langle S''_{\omega,c}(\phi_{\omega,c})h_1, h_1 \rangle
\]
\[
= \frac{\gamma}{\gamma + \langle S''_{\omega,c}(\phi_{\omega,c})h_2, h_2 \rangle} \langle S''_{\omega,c}(\phi_{\omega,c})h_1, h_1 \rangle
\]
\[
\gtrsim \|h_1\|_{H^1(\mathbb{R})}^2.
\]

By (3.6) and Hölder’s inequality, we have
\[
a_{-1}^2 \lesssim \|h_1\|_{H^1(\mathbb{R})}^2.
\]
Hence, by $\varepsilon = a_{-1}g_{-1} + h_1$, we have

$$\|\varepsilon\|^2_{L^2} \lesssim a_{-1}^2 + \|h_1\|^2_{H^1(\mathbb{R})} \lesssim h_1^2.$$  
Since,

$$\langle S''_{\omega,c}(\phi_{\omega,c})\varepsilon,\varepsilon\rangle \gtrsim \|h_1\|^2_{H^1(\mathbb{R})} \gtrsim \|\varepsilon\|^2_{L^2}.$$  
From the definition of $S''_{\omega,c}(\phi_{\omega,c})$ in (2.3), we have

$$\|\varepsilon\|^2_{H^1} \lesssim \langle S''_{\omega,c}(\phi_{\omega,c})\varepsilon,\varepsilon\rangle + \|\varepsilon\|^2_{L^2}.$$  
Therefore, we get that

$$\langle S''_{\omega,c}(\phi_{\omega,c})\varepsilon,\varepsilon\rangle \gtrsim \|\varepsilon\|^2_{H^1(\mathbb{R})}.$$  
This finishes the proof of the proposition. \qed

**Lemma 7.** There exists $C_{\omega,c} \in \mathbb{R}$, such that

$$\dot{y} - c - \lambda \nu = C_{\omega,c}\lambda + \langle S''_{\omega,c}(\phi_{\omega,c}), \frac{-a_0\phi_{\omega,c} + i\partial_x\phi_{\omega,c}}{2(a_0^2 - \omega)M(\phi_{\omega,c})}, \varepsilon \rangle + O(\lambda\|\varepsilon\|_{H^1(\mathbb{R})} + \|\varepsilon\|^2_{H^1(\mathbb{R})}),$$  

(3.7)

and

$$\dot{\theta} - \omega - \lambda \mu = O(\|\varepsilon\|_{H^1(\mathbb{R})}), \quad \dot{\lambda} = O(\|\varepsilon\|_{H^1(\mathbb{R})})$$  

(3.8)

Here the parameters $\theta$, $y$, $\lambda$ are given by Proposition 4.

**Proof.** Now, we consider the dynamic of the parameters. From (3.1), we have

$$u = e^{i\theta(t)}(\phi_{\omega + \lambda(t)\mu,c + \lambda(t)\nu} + \varepsilon(t))(x - y(t)).$$  
Using (1.1), we obtain

$$i\dot{\varepsilon} = (\theta - \omega - \lambda \nu)(\phi_{\omega + \lambda \mu,c + \lambda \nu} + \varepsilon) - (\dot{y} - c - \lambda \nu)(i\partial_x \phi_{\omega + \lambda \mu,c + \lambda \nu} + i\partial_x \varepsilon)$$

$$+ \dot{\lambda} \cdot \partial_x \phi_{\omega + \lambda \mu,c + \lambda \nu} = S''_{\omega,c}(\phi_{\omega,c})\varepsilon + O(\lambda\varepsilon + \varepsilon^2),$$  

(3.9)

where $O(\varepsilon)$ is a functional of $\varepsilon$ with the order equal or more than one.

First, the equation (3.9) producing with $-a_0\phi_{\omega + \lambda \mu,c + \lambda \nu} + i\partial_x \phi_{\omega + \lambda \mu,c + \lambda \nu}$, we get

$$- (\dot{\theta} - \omega - \lambda \mu)\left[ -2a_0M(\phi_{\omega + \lambda \mu,c + \lambda \nu}) + 2P(\phi_{\omega + \lambda \mu,c + \lambda \nu}) + O(\|\varepsilon\|_{H^1(\mathbb{R})}) \right]$$

$$- (\dot{y} - c - \lambda \nu)\left[ -2a_0P(\phi_{\omega + \lambda \mu,c + \lambda \nu}) + \|\partial_x \phi_{\omega + \lambda \mu,c + \lambda \nu}\|^2_{L^2} + O(\|\varepsilon\|_{H^1(\mathbb{R})}) \right]$$

$$+ \dot{\lambda}\left[ i\partial_x \phi_{\omega + \lambda \mu,c + \lambda \nu} - a_0\phi_{\omega + \lambda \mu,c + \lambda \nu} + i\partial_x \phi_{\omega + \lambda \mu,c + \lambda \nu} - (\varepsilon, i\partial_x \phi_{\omega + \lambda \mu,c + \lambda \nu} + \partial_x \phi_{\omega + \lambda \mu,c + \lambda \nu}) \right] = \langle S''_{\omega,c}(\phi_{\omega,c}), (-a_0\phi_{\omega + \lambda \mu,c + \lambda \nu} + i\partial_x \phi_{\omega + \lambda \mu,c + \lambda \nu}), \varepsilon \rangle + O(\lambda\|\varepsilon\|_{H^1(\mathbb{R})} + \|\varepsilon\|^2_{H^1(\mathbb{R})})$$

By a direct expansion, we have

$$\phi_{\omega + \lambda \mu,c + \lambda \nu} - \psi + O(\lambda^2),$$  

(3.10)

and

$$\partial_x \phi_{\omega + \lambda \mu,c + \lambda \nu} = \psi + O(\lambda).$$

Moreover, together with (2.15), we have

$$M(\phi_{\omega + \lambda \mu,c + \lambda \nu}) = M(\phi_{\omega,c}) + \lambda M'(\phi_{\omega,c}), \psi) + O(\lambda^2) = M(\phi_{\omega,c}) + O(\lambda^2),$$

$$P(\phi_{\omega + \lambda \mu,c + \lambda \nu}) = P(\phi_{\omega,c}) + \lambda P'(\phi_{\omega,c}), \psi) + O(\lambda^2) = P(\phi_{\omega,c}) + O(\lambda^2).$$

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From (2.6), we get
\[ \| \partial_x \phi_{\omega + \lambda \mu, c + \lambda \nu} \|^2_{L^2} = (\omega + \lambda \mu) \| \phi_{\omega + \lambda \mu, c + \lambda \nu} \|^2_{L^2} = 2 \omega M(\phi_{\omega, c}) + O(\lambda). \]

We collect the above computations and obtain
\[ - (\dot{\theta} - \omega - \lambda \mu) [ - 2 a_0 M(\phi_{\omega, c}) + 2 P(\phi_{\omega, c}) + O(\lambda^2 + \| \varepsilon \|_{H^1(\mathbb{R})}) ] \]
\[ - (\dot{y} - c - \lambda \nu) [ - 2 a_0 P(\phi_{\omega, c}) + 2 \omega M(\phi_{\omega, c}) + O(\lambda + \| \varepsilon \|_{H^1(\mathbb{R})}) ] \]
\[ + \lambda \langle i \psi, - a_0 \phi_{\omega, c} + i \partial_x \phi_{\omega, c} \rangle + O(\lambda + \| \varepsilon \|_{H^1(\mathbb{R})}) \]
\[ = \langle S''_{\omega, c}(\phi_{\omega, c})(- a_0 \phi_{\omega, c} + i \partial_x \phi_{\omega, c} + O(\lambda)), \varepsilon \rangle + O(\lambda \| \varepsilon \|_{H^1(\mathbb{R})} + \| \varepsilon \|^2_{H^1(\mathbb{R})}). \]

By Lemma 4, we know that
\[ - a_0 M(\phi_{\omega, c}) + P(\phi_{\omega, c}) = 0, \quad - a_0 P(\phi_{\omega, c}) + \omega M(\phi_{\omega, c}) = (\omega - a_0^2) M(\phi_{\omega, c}) \neq 0. \]

Then, we get
\[ - (\dot{\theta} - \omega - \lambda \mu) [ O(\lambda^2 + \| \varepsilon \|_{H^1(\mathbb{R})}) ] \]
\[ - (\dot{y} - c - \lambda \nu) [ 2(\omega - a_0^2) M(\phi_{\omega, c}) + O(\lambda + \| \varepsilon \|_{H^1(\mathbb{R})}) ] \]
\[ + \lambda \langle i \psi, - a_0 \phi_{\omega, c} + i \partial_x \phi_{\omega, c} \rangle + O(\lambda + \| \varepsilon \|_{H^1(\mathbb{R})}) \]
\[ = \langle S''_{\omega, c}(\phi_{\omega, c})(- a_0 \phi_{\omega, c} + i \partial_x \phi_{\omega, c}), \varepsilon \rangle + O(\lambda \| \varepsilon \|_{H^1(\mathbb{R})} + \| \varepsilon \|^2_{H^1(\mathbb{R})}). \] (3.11)

Next, producing with \( \phi_{\omega + \lambda \mu, c + \lambda \nu} \) in the equation (3.9) and treating as above, we have
\begin{align*}
- (\dot{\theta} - \omega - \lambda \mu) [ O(\lambda^2 + \| \varepsilon \|_{H^1(\mathbb{R})}) ] \\
- (\dot{y} - c - \lambda \nu) [ 2(\omega - a_0^2) M(\phi_{\omega, c}) + O(\lambda + \| \varepsilon \|_{H^1(\mathbb{R})}) ] \\
+ \lambda \langle i \psi, \phi_{\omega, c} \rangle + O(\lambda + \| \varepsilon \|_{H^1(\mathbb{R})}) \\
= O(\| \varepsilon \|_{H^1(\mathbb{R})}).
\end{align*} (3.12)

Finally, producing with \( i J'(\phi_{\omega + \lambda \mu, c + \lambda \nu}) \) in the equation (3.9) and treating as above, we obtain
\begin{align*}
- (\dot{\theta} - \omega - \lambda \mu) [ \langle J'(\phi_{\omega, c}), - i \phi_{\omega, c} \rangle + O(\lambda + \| \varepsilon \|_{H^1(\mathbb{R})}) ] \\
- (\dot{y} - c - \lambda \nu) [ \langle J'(\phi_{\omega, c}), \partial_x \phi_{\omega, c} \rangle + O(\lambda + \| \varepsilon \|_{H^1(\mathbb{R})}) ] \\
+ \lambda \langle J'(\phi_{\omega, c}), \psi \rangle + O(\lambda + \| \varepsilon \|_{H^1(\mathbb{R})}) \\
= O(\| \varepsilon \|_{H^1(\mathbb{R})}).
\end{align*} (3.13)

Using (3.11), (3.12), (3.13) and Lemma 5, we obtain
\[ \dot{y} - c - \lambda \nu = C_{\omega, c} \dot{\lambda} + \langle S''_{\omega, c}(\phi_{\omega, c}) \frac{- a_0 \phi_{\omega, c} + i \partial_x \phi_{\omega, c}}{2(a_0^2 - \omega) M(\phi_{\omega, c})}, \varepsilon \rangle + O(\lambda \| \varepsilon \|_{H^1(\mathbb{R})} + \| \varepsilon \|^2_{H^1(\mathbb{R})}), \]

and
\[ \dot{\theta} - \omega - \lambda \mu = O(\| \varepsilon \|_{H^1(\mathbb{R})}), \quad \dot{\lambda} = O(\| \varepsilon \|_{H^1(\mathbb{R})}). \]

Here
\[ C_{\omega, c} = \frac{-1}{2(a_0^2 - \omega) M(\phi_{\omega, c})} \langle i \psi, - a_0 \phi_{\omega, c} + i \partial_x \phi_{\omega, c} \rangle. \]

This completes the proof.
4. Instability of the Solitary Wave Solutions

4.1. Virial Estimates. To prove the main theorem, first, we need the localized virial identities.

Lemma 8. Let \( \varphi \in C^\infty(\mathbb{R}) \), then

\[
\frac{d}{dt} \int_{\mathbb{R}} \varphi |u|^2 \, dx = -2 \text{Im} \int_{\mathbb{R}} \varphi' \overline{\partial_x u} u \, dx + \frac{1}{\sigma + 1} \int_{\mathbb{R}} \varphi' |u|^{2\sigma + 2} \, dx,
\]

\[
\frac{d}{dt} \int_{\mathbb{R}} \varphi \text{Im}(u \overline{\partial_x u}) = -2 \int_{\mathbb{R}} \varphi' |\partial_x u|^2 \, dx + \frac{1}{2} \int_{\mathbb{R}} \varphi''' |u|^2 \, dx + \text{Im} \int_{\mathbb{R}} \varphi' |u|^{2\sigma} \overline{\partial_x u}.
\]

Proof. Combining the equation (1.1) and integration by parts, we have

\[
\frac{d}{dt} \int_{\mathbb{R}} \varphi |u|^2 \, dx = 2 \text{Re} \int_{\mathbb{R}} \varphi \partial_t u \, \overline{u}
\]

\[
= 2 \text{Re} \int_{\mathbb{R}} \varphi(i \partial_x^2 u - |u|^{2\sigma} \partial_x u) \overline{u}
\]

\[
= -2 \text{Re} \int_{\mathbb{R}} i \varphi' \partial_x u \overline{u} \, dx + \frac{1}{\sigma + 1} \text{Re} \int_{\mathbb{R}} \varphi |u|^{2\sigma + 2} \, dx
\]

By the same way, we obtain

\[
\frac{d}{dt} \int_{\mathbb{R}} \varphi \text{Im}(u \overline{\partial_x u}) = \text{Im} \int_{\mathbb{R}} \varphi \partial_t u \overline{\partial_x u} \, dx + \text{Im} \int_{\mathbb{R}} \varphi u \overline{\partial_x u} \, dx
\]

\[
= 2 \text{Im} \int_{\mathbb{R}} \varphi \partial_t u \overline{\partial_x u} \, dx + \text{Im} \int_{\mathbb{R}} \varphi' \partial_t u \overline{u} \, dx
\]

\[
= 2 \text{Im} \int_{\mathbb{R}} \varphi(i \partial_x^2 u - |u|^{2\sigma} \partial_x u) \overline{\partial_x u} \, dx + \text{Im} \int_{\mathbb{R}} \varphi'(i \partial_x^2 u - |u|^{2\sigma} \partial_x u) \overline{u} \, dx
\]

\[
= -2 \int_{\mathbb{R}} \varphi' |\partial_x u|^2 \, dx + \frac{1}{2} \int_{\mathbb{R}} \varphi''' |u|^2 \, dx + \text{Im} \int_{\mathbb{R}} \varphi' |u|^{2\sigma} \overline{\partial_x u}.
\]

This proves the lemma. \( \square \)

Now we define \( \varphi_R \in C^\infty(\mathbb{R}) \) satisfying

\[
\varphi_R(x) = \begin{cases} 
  x, & |x| \leq R, \\
  2R, & |x| \geq 2R,
\end{cases}
\]

and \( 0 \leq |\varphi'_R| \leq 1 \) for any \( x \in \mathbb{R} \). Moreover, we denote

\[
I_1(t) = \int_{\mathbb{R}} \varphi_R(x - y(t)) |u|^2 \, dx,
\]

\[
I_2(t) = \int_{\mathbb{R}} \varphi_R(x - y(t)) \text{Im}(u \overline{\partial_x u}) \, dx.
\]
To prove the main theorem, we define the key functional $I(t)$ as

$$ I(t) = -\sqrt{\omega}I_1(t) + I_2(t) + \tilde{C}_{\omega,c}\lambda, $$

where $\tilde{C}_{\omega,c} = 2C_{\omega,c}(M(\phi_{\omega,c}) + P(\phi_{\omega,c}))$.

Hence, by Lemma 8 we can obtain the following localized virial estimates.

**Lemma 9.** Assume that

$$ u = e^{i\theta(t)}(\phi_{\omega+c,\mu+c+\lambda(t)} + \varepsilon(t))(x - y(t)), $$

with the parameters obey the estimates in Lemma 7. Then the following estimates hold:

$$ I_1'(t) = -2C_{\omega,c}\dot{\lambda}M(\phi_{\omega,c}) - 2c[M(u_0) - M(\phi_{\omega,c})] - 4[P(u_0) - P(\phi_{\omega,c})] $$

$$ - \frac{\sigma - 1}{\sigma(2 - \sigma)\omega} \mathcal{S}_{\omega,c}(\phi_{\omega,c})(\sqrt{\omega}\phi_{\omega,c} - i\partial_x\phi_{\omega,c}, \varepsilon) + \frac{1}{2(\sigma + 1)} \lambda^2 \frac{d^2}{d\lambda^2} \|\phi_{\omega+c,\mu+c+\lambda}\|_{L^{2\sigma+2}}^2 \bigg|_{\lambda=0} $$

$$ + O(\lambda\|\varepsilon\|_{H^1(\mathbb{R})} + \|\varepsilon\|_{H^1(\mathbb{R})}^2 + \frac{1}{R}) + O(\lambda^2), $$

and

$$ I_2'(t) = -2C_{\omega,c}\dot{\lambda}P(\phi_{\omega,c}) - 2[P(u_0) - P(\phi_{\omega,c})] - 4[E(u_0) - E(\phi_{\omega,c})] $$

$$ - \frac{\sigma - 1}{\sigma(2 - \sigma)\omega} \mathcal{S}_{\omega,c}(\phi_{\omega,c})(\sqrt{\omega}\phi_{\omega,c} - i\partial_x\phi_{\omega,c}, \varepsilon) + \frac{1}{2(\sigma + 1)} \lambda^2 \frac{d^2}{d\lambda^2} J(\phi_{\omega+c,\mu+c+\lambda}) \bigg|_{\lambda=0} $$

$$ + O(\lambda\|\varepsilon\|_{H^1(\mathbb{R})} + \|\varepsilon\|_{H^1(\mathbb{R})}^2 + \frac{1}{R}) + O(\lambda^2). $$

**Proof.** By Lemma 8 and some direct computation, we have the following formulas.

$$ I_1'(t) = -\dot{y} \int_{\mathbb{R}} \varphi'_R(x - y(t))|u|^2 - 2\text{Im} \int_{\mathbb{R}} \varphi'_R(x - y(t))u\overline{\partial_x u}dx + \frac{1}{\sigma + 1} \int_{\mathbb{R}} \varphi'_R(x - y(t))|u|^{2\sigma+2}dx, $$

$$ I_2'(t) = -\dot{y} \int_{\mathbb{R}} \varphi'_R(x - y(t))\text{Im}(u\overline{\partial_x u})dx - \int_{\mathbb{R}} \varphi'_R(x - y(t))[2|\partial_x u|^2 - \text{Im}(|u|^{2\sigma}u\overline{\partial_x u})]dx $$

$$ + \frac{1}{2} \int_{\mathbb{R}} \varphi''_R(x - y(t))|u|^2dx. $$

First, with the definitions of $M$ and $P$ yields

$$ I_1'(t) = -2\dot{y}M(u) - 2\dot{y} \int_{\mathbb{R}} [\varphi'_R(x - y(t)) - 1]|u|^2dx - 4P(u) - 2\text{Im} \int_{\mathbb{R}} [\varphi'_R(x - y(t)) - 1]u\overline{\partial_x u}dx $$

$$ + \frac{1}{\sigma + 1} \|u\|_{L^{2\sigma+2}}^{2\sigma+2} + \frac{1}{\sigma + 1} \int_{\mathbb{R}} [\varphi'_R(x - y(t)) - 1]|u|^{2\sigma+2}dx $$

$$ = -2(\dot{y} - c - \lambda\nu)M(u) - 2(c + \lambda\nu)M(u) - 4P(u) + \frac{1}{\sigma + 1} \|u\|_{L^{2\sigma+2}}^{2\sigma+2} $$

$$ + O\left( \int_{\mathbb{R}} [\varphi'_R(x - y(t)) - 1](\dot{y}|u|^2 + \text{Im}(u\overline{\partial_x u}) + |u|^{2\sigma+2})dx \right). $$

In fact, supp[$\varphi'_R(x - y(t)) - 1$] $\subset \{x : |x - y(t)| \geq R\}, \ 0 \leq |\varphi'_R| \leq 1$. From Lemma 7 we know that $|\dot{y}| \lesssim 1$. Then, after using (1.1) and the exponential decaying of
\[ \phi_{\omega + \lambda \mu, c + \lambda \nu}, \] we have

\[
\int_{\mathbb{R}} \left[ \varphi'_{\mathbb{R}}(x - y(t)) - 1 \right] (\dot{y} | u|^2 + \text{Im}(u \overline{\partial_x u}) + |u|^{2\sigma + 2}) \, dx 
\]

\[
\leq \int_{|x - y(t)| \geq R} \left[ |\phi_{\omega + \lambda \mu, c + \lambda \nu}|^2 + |\partial_x^2 \phi_{\omega + \lambda \mu, c + \lambda \nu}|^2 + |\varepsilon|^2 + |\partial_x \varepsilon|^2 + |\varepsilon|^{2\sigma + 2} \right] 
\]

\[
= O(\|\varepsilon\|_{H^1(\mathbb{R})}^2 + \frac{1}{R}).
\]  

(M.3)

Mergering (3.7) and (1.3) into (4.2), we obtain

\[
I_1'(t) = -2[C_{\omega, c} \lambda + \langle S''_{\omega, c}(\phi_{\omega, c}) - a_0 \phi_{\omega, c} + i \partial_x \phi_{\omega, c}, \varepsilon \rangle + O(\lambda \|\varepsilon\|_{H^1(\mathbb{R})} + \|\varepsilon\|_{H^1(\mathbb{R})}^2) \rangle M(u)
\]

\[
- 2(c + \lambda \nu) M(u) - 4P(u) + \frac{1}{\sigma + 1} \|u\|_{L^{2\sigma + 2}}^{2\sigma + 2} + O\left(\|\varepsilon\|_{H^1(\mathbb{R})}^2 + \frac{1}{R}\right).
\]

Now, using (2.15), (3.10) and (4.1), we get

\[
M(u) = M(\phi_{\omega, c}) + \langle M'(\phi_{\omega, c}), \varepsilon \rangle + O(\lambda \|\varepsilon\|_{H^1(\mathbb{R})} + \|\varepsilon\|_{H^1(\mathbb{R})}^2),
\]

and

\[
P(u) = P(\phi_{\omega, c}) + \langle P'(\phi_{\omega, c}), \varepsilon \rangle + O(\lambda \|\varepsilon\|_{H^1(\mathbb{R})} + \|\varepsilon\|_{H^1(\mathbb{R})}^2).
\]

Moreover,

\[
\|u\|_{L^{2\sigma + 2}}^{2\sigma + 2} = \|\phi_{\omega, c}\|_{L^{2\sigma + 2}}^{2\sigma + 2} + 2(\sigma + 1) \lambda \|\phi_{\omega, c}\|_{L^{2\sigma + 2}}^{2\sigma} \phi_{\omega, c}, \psi \rangle + 2(\sigma + 1) \langle \phi_{\omega, c}, \varepsilon \rangle + 2(\sigma + 1) \langle |\phi_{\omega, c}|^{2\sigma} \phi_{\omega, c}, \varepsilon \rangle
\]

\[
+ \frac{1}{2} \lambda^2 \frac{d^2}{d\lambda^2} \|\phi_{\omega + \lambda \mu, c + \lambda \nu}\|_{L^{2\sigma + 2}}^{2\sigma + 2} \bigg|_{\lambda = 0} + O(\lambda \|\varepsilon\|_{H^1(\mathbb{R})} + \|\varepsilon\|_{H^1(\mathbb{R})}^2) + o(\lambda^2),
\]

and

\[
J(u) = J(\phi_{\omega, c}) + \lambda \langle J'(\phi_{\omega, c}), \psi \rangle + \frac{1}{2} \lambda^2 \frac{d^2}{d\lambda^2} J(\phi_{\omega + \lambda \mu, c + \lambda \nu}) \bigg|_{\lambda = 0}
\]

\[
+ \frac{\sigma - 1}{\sigma + 1} \langle J'(\phi_{\omega, c}), \varepsilon \rangle + O(\lambda \|\varepsilon\|_{H^1(\mathbb{R})} + \|\varepsilon\|_{H^1(\mathbb{R})}^2) + o(\lambda^2).
\]

(4.7)

Combinig (4.4) and (4.6) yields

\[
I_1'(t) = -2C_{\omega, c} \lambda M(\phi_{\omega, c}) - 2c M(u) - 2\lambda \nu M(\phi_{\omega, c}) - 4P(u) + \frac{1}{\sigma + 1} \|\phi_{\omega, c}\|_{L^{2\sigma + 2}}^{2\sigma + 2}
\]

\[
+ \left\langle - S''_{\omega, c}(\phi_{\omega, c}) - a_0 \phi_{\omega, c} + i \partial_x \phi_{\omega, c}, a_0^2 - \omega \right\rangle + 2|\phi_{\omega, c}|^{2\sigma} \phi_{\omega, c}, \psi \rangle + 2\lambda \langle |\phi_{\omega, c}|^{2\sigma} \phi_{\omega, c}, \varepsilon \rangle
\]

\[
+ \frac{1}{2(\sigma + 1)} \lambda^2 \frac{d^2}{d\lambda^2} \|\phi_{\omega + \lambda \mu, c + \lambda \nu}\|_{L^{2\sigma + 2}}^{2\sigma + 2} \bigg|_{\lambda = 0} + O(\lambda \|\varepsilon\|_{H^1(\mathbb{R})} + \|\varepsilon\|_{H^1(\mathbb{R})}^2) + \frac{1}{R} + o(\lambda^2).
\]

From the conservation laws and (2.10), we get

\[
I_1'(t) = -2C_{\omega, c} \lambda M(\phi_{\omega, c}) - 2c M(u_0) - 4P(u_0) - 2\lambda \nu M(\phi_{\omega, c}) + 2c M(\phi_{\omega, c}) + 4P(\phi_{\omega, c})
\]

\[
+ \left\langle - S''_{\omega, c}(\phi_{\omega, c}) - a_0 \phi_{\omega, c} + i \partial_x \phi_{\omega, c}, a_0^2 - \omega \right\rangle + 2|\phi_{\omega, c}|^{2\sigma} \phi_{\omega, c}, \psi \rangle + 2\lambda \langle |\phi_{\omega, c}|^{2\sigma} \phi_{\omega, c}, \varepsilon \rangle
\]

\[
+ \frac{1}{2(\sigma + 1)} \lambda^2 \frac{d^2}{d\lambda^2} \|\phi_{\omega + \lambda \mu, c + \lambda \nu}\|_{L^{2\sigma + 2}}^{2\sigma + 2} \bigg|_{\lambda = 0} + O(\lambda \|\varepsilon\|_{H^1(\mathbb{R})} + \|\varepsilon\|_{H^1(\mathbb{R})}^2) + \frac{1}{R} + o(\lambda^2).
\]
Observe that
\[
\langle |\phi_{\omega,c}|^{2\sigma} \phi_{\omega,c}, \psi \rangle = \frac{1}{2(\sigma + 1)} \partial_\lambda \left( \|\phi_{\omega+\lambda \mu,c+\lambda \nu}\|_{L^2}^{2\sigma+2} \right) \bigg|_{\lambda = 0}.
\]
Moreover, using the equality (2.10) again yields
\[
\langle |\phi_{\omega,c}|^{2\sigma} \phi_{\omega,c}, \psi \rangle = \frac{1}{2(\sigma + 1)} \partial_\lambda \left( 4(\sigma + 1) \left( \frac{c + \lambda \nu}{2} M(\phi_{\omega+\lambda \mu,c+\lambda \nu}) + P(\phi_{\omega+\lambda \mu,c+\lambda \nu}) \right) \right) \bigg|_{\lambda = 0}.
\]
Using Lemma 5 again, we obtain that
\[
\langle |\phi_{\omega,c}|^{2\sigma} \phi_{\omega,c}, \psi \rangle = \nu M(\phi_{\omega,c}).
\]
By Lemma 1, we have
\[
-S''(\phi_{\omega,c}) \frac{-a_0 \Phi_{\omega,c} + i \partial_x \Phi_{\omega,c}}{a_0^2 - \omega} + 2|\phi_{\omega,c}|^{2\sigma} \phi_{\omega,c} = -\frac{\sigma - 1}{\sigma(2 - \sigma)\omega} S''(\phi_{\omega,c}) \left( \sqrt{\omega} \Phi_{\omega,c} - i \partial_x \Phi_{\omega,c} \right).
\]
Finally, we collect the above equalities and obtain
\[
I'_1(t) = -2C_{\omega,c} \lambda M(\phi_{\omega,c}) - 2c [M(u_0) - M(\phi_{\omega,c})] - 4 [P(u_0) - P(\phi_{\omega,c})]
\]
\[
- \frac{\sigma - 1}{\sigma(2 - \sigma)\omega} \left( S''(\phi_{\omega,c}) \left( \sqrt{\omega} \Phi_{\omega,c} - i \partial_x \Phi_{\omega,c} \right), \varepsilon \right) + \frac{1}{2(\sigma + 1)} \lambda^2 \frac{d^2}{d\lambda^2} \|\phi_{\omega+\lambda \mu,c+\lambda \nu}\|_{L^2}^{2\sigma+2} \bigg|_{\lambda = 0}
\]
\[
+ O(\lambda \varepsilon \|H^1(\mathbb{R})\| + \|\varepsilon\|_{H^1(\mathbb{R})}^2 + \frac{1}{R}) + o(\lambda^2).
\]
Similarly, from the definitions of $P$, $E$ and $J$, we have
\[
I'_2(t) = -2\dot{y} P(u) - 4E(u) + \frac{\sigma - 1}{\sigma + 1} J(u)
\]
\[
- \dot{y} \int_{\mathbb{R}} [\varphi'_R(x - y(t)) - 1] [\text{Im}(u \overline{\partial_x u}) - 2|\partial_x u|^2 + \text{Im}|u|^{2\sigma} \overline{\partial_x u}] dx
\]
\[
= -2(\dot{y} - c - \lambda \nu) P(u) - 2(c + \lambda \nu) P(u) - 4E(u) + \frac{\sigma - 1}{\sigma + 1} J(u) + O(\|\varepsilon\|_{H^1(\mathbb{R})}^2 + \frac{1}{R}).
\]
Using (3.7), we get
\[
I''_2(t) = -2 \left[ C_{\omega,c} \lambda + \left( S''(\phi_{\omega,c}) \frac{-a_0 \Phi_{\omega,c} + i \partial_x \Phi_{\omega,c}}{a_0^2 - \omega} \right) \right] P(u)
\]
\[
- 2(c + \lambda \nu) P(u) - 4E(u) + \frac{\sigma - 1}{\sigma + 1} J(u) + O(\|\varepsilon\|_{H^1(\mathbb{R})}^2 + \frac{1}{R}).
\]
Combining (4.5) and (4.7), we obtain
\[
I'_2(t) = -2C_{\omega,c} \lambda P(\phi_{\omega,c}) - 2c P(u) - 2\lambda \nu P(\phi_{\omega,c}) - 4E(u) + \frac{\sigma - 1}{\sigma + 1} J(\phi_{\omega,c})
\]
\[
- P(\phi_{\omega,c}) \left( S''(\phi_{\omega,c}) \frac{-a_0 \Phi_{\omega,c} + i \partial_x \Phi_{\omega,c}}{a_0^2 - \omega}, \varepsilon \right) + \frac{\sigma - 1}{\sigma + 1} \langle J'(\phi_{\omega,c}), \psi \rangle
\]
\[
+ \frac{\sigma - 1}{\sigma + 1} \lambda \langle J'(\phi_{\omega,c}), \psi \rangle + \frac{\sigma - 1}{2(\sigma + 1)} \lambda^2 \frac{d^2}{d\lambda^2} J(\phi_{\omega+\lambda \mu,c+\lambda \nu}) \bigg|_{\lambda = 0}
\]
\[
+ O(\lambda \varepsilon \|H^1(\mathbb{R})\| + \|\varepsilon\|_{H^1(\mathbb{R})}^2 + \frac{1}{R}) + o(\lambda^2).
\]
Using (2.7), (2.8), (2.9), Lemma 4 and the conservation laws, we have

\[ I_2'(t) = -2C_{\omega,c}\dot{\lambda} P(\phi_{\omega,c}) - 2c[P(u_0) - P(\phi_{\omega,c})] - 4[E(u_0) - E(\phi_{\omega,c})] \]

\[ - \frac{\sigma - 1}{\sigma(2 - \sigma)}\sqrt{\omega} \langle S'_{\omega,c}(\phi_{\omega,c})(\sqrt{\omega}\phi_{\omega,c} - i\partial_x \phi_{\omega,c}), \varepsilon \rangle + \frac{\sigma - 1}{2(\sigma + 1)} \lambda^2 \frac{d^2}{d\lambda^2} J(\phi_{\omega,\lambda\mu,c+\lambda\nu}) \bigg|_{\lambda=0} \]

\[ + O(\lambda\|\varepsilon\|_{H^1(\mathbb{R})} + \|\varepsilon\|^2_{H^1(\mathbb{R})} + \frac{1}{R}) + o(\lambda^2). \]

This completes the proof of the lemma.

According to Lemma 9, we have following result.

**Lemma 10.** Under the assumptions of Lemma 9, we have

\[ I'(t) = A(u_0) + B(\lambda) + O(\lambda\|\varepsilon\|_{H^1(\mathbb{R})} + \|\varepsilon\|^2_{H^1(\mathbb{R})} + \frac{1}{R}) + o(\lambda^2), \]

with \( A(u_0), B(\lambda) \) verifying

\[ A(u_0) = (2c\sqrt{\omega} + 4\omega)[(M(u_0) - M(\phi_{\omega,c})) + (4\sqrt{\omega} - 2c)[P(u_0) - P(\phi_{\omega,c})] \]

\[ - 4[S_{\omega,c}(u_0) - S_{\omega,c}(\phi_{\omega,c})], \]

and

\[ B(\lambda) = b_1 \lambda^2, \]

for some \( b_1 > 0. \)

**Remark 2.** The form of \( I(t) \) removes the linear term of \( \varepsilon \) in \( I'(t). \)

**Proof of Lemma 10.** From the definition of \( I(t) \), we have

\[ I'(t) = -\sqrt{\omega}I_1'(t) + I_2'(t) + \widetilde{C}_{\omega,c}\dot{\lambda}. \]

By Lemma 4 we obtain

\[ I'(t) = \sqrt{\omega}[2c(M(u_0) - M(\phi_{\omega,c})) + 4(P(u_0) - P(\phi_{\omega,c}))] \]

\[ - 2c[P(u_0) - P(\phi_{\omega,c})] - 4[E(u_0) - E(\phi_{\omega,c})] \]

\[ + \frac{1}{2(\sigma + 1)} \frac{d^2}{d\lambda^2} \left[ - \sqrt{\omega}\|\phi_{\omega,\lambda\mu,c+\lambda\nu}\|^2_{L^{2\sigma+2}} + (\sigma - 1)J(\phi_{\omega,\lambda\mu,c+\lambda\nu}) \right] \bigg|_{\lambda=0} \]

\[ + O(\lambda\|\varepsilon\|_{H^1(\mathbb{R})} + \|\varepsilon\|^2_{H^1(\mathbb{R})} + \frac{1}{R}) + o(\lambda^2). \]

We denote

\[ A(u_0) = \sqrt{\omega}[2c(M(u_0) - M(\phi_{\omega,c})) + 4(P(u_0) - P(\phi_{\omega,c}))] \]

\[ - 2c[P(u_0) - P(\phi_{\omega,c})] - 4[E(u_0) - E(\phi_{\omega,c})], \]

and

\[ B(\lambda) = \frac{1}{2(\sigma + 1)} \frac{d^2}{d\lambda^2} \left[ - \sqrt{\omega}\|\phi_{\omega,\lambda\mu,c+\lambda\nu}\|^2_{L^{2\sigma+2}} + (\sigma - 1)J(\phi_{\omega,\lambda\mu,c+\lambda\nu}) \right] \bigg|_{\lambda=0}. \]

Then, we have

\[ I'(t) = A(u_0) + B(\lambda) + O(\lambda\|\varepsilon\|_{H^1(\mathbb{R})} + \|\varepsilon\|^2_{H^1(\mathbb{R})} + \frac{1}{R}) + o(\lambda^2). \]
By the definition of $S_{\omega,c}$, we have
\[A(u_0) = (2c\sqrt{\omega} + 4\omega)(M(u_0) - M(\phi_{\omega,c})) + (4\sqrt{\omega} - 2c)[P(u_0) - P(\phi_{\omega,c})]
- 4[S_{\omega,c}(u_0) - S_{\omega,c}(\phi_{\omega,c})].\]

Now we consider $B(\lambda)$. Observe, from (2.7) and (2.10), that
\[-\sqrt{\omega}\|\phi_{\omega+c,\lambda,\omega+c,\lambda}\|^2_{L^2} + (\sigma - 1)J(\phi_{\omega+c,\lambda,\omega+c,\lambda})
- \sqrt{\omega} \cdot 4(\sigma + 1)[c + \lambda\nu]M(\phi_{\omega+c,\lambda,\omega+c,\lambda}) + P(\phi_{\omega+c,\lambda,\omega+c,\lambda})
+ (\sigma - 1)[4(\omega + \lambda\mu)M(\phi_{\omega+c,\lambda,\omega+c,\lambda}) + 2(c + \lambda\nu)P(\phi_{\omega+c,\lambda,\omega+c,\lambda})]
= [4\omega(\sigma - 1) - 2c\sqrt{\omega}(\sigma + 1)]M(\phi_{\omega+c,\lambda,\omega+c,\lambda}) + [2c(\sigma - 1) - 4\sqrt{\omega}(\sigma + 1)]P(\phi_{\omega+c,\lambda,\omega+c,\lambda})
+ [4\mu(\sigma - 1) - 2\nu\sqrt{\omega}(\sigma + 1)]\lambda M(\phi_{\omega+c,\lambda,\omega+c,\lambda}) + 2\lambda\nu P(\phi_{\omega+c,\lambda,\omega+c,\lambda}).\]

Next, using (2.13) and (2.14), we calculate the terms above separately:
\[\frac{d^2}{d\lambda^2}M(\phi_{\omega+c,\lambda,\omega+c,\lambda})\bigg|_{\lambda=0} = \mu^2\partial_{\omega\omega}M(\phi_{\omega,c}) + 2\mu\nu\partial_{\omega\lambda}M(\phi_{\omega,c}) + \nu^2\partial_{\lambda\lambda}M(\phi_{\omega,c}) = \kappa_0 z_0,\]
\[\frac{d^2}{d\lambda^2}P(\phi_{\omega+c,\lambda,\omega+c,\lambda})\bigg|_{\lambda=0} = \mu^2\partial_{\omega\omega}P(\phi_{\omega,c}) + 2\mu\nu\partial_{\omega\lambda}P(\phi_{\omega,c}) + \nu^2\partial_{\lambda\lambda}P(\phi_{\omega,c}) = -\kappa_0 \sqrt{\omega}.\]

Finally, together with (2.15), and the three estimates above, we get
\[\frac{1}{2(\sigma + 1)}\left\|\phi_{\omega+c,\lambda,\omega+c,\lambda}\right\|^2_{L^2} + (\sigma - 1)J(\phi_{\omega+c,\lambda,\omega+c,\lambda})\bigg|_{\lambda=0}
\cdot \left[2\omega(\sigma - 1) - \sqrt{\omega}(\sigma + 1)\right]\left\|\frac{d^2}{d\lambda^2}M(\phi_{\omega+c,\lambda,\omega+c,\lambda})\right\|_{\lambda=0}
\cdot \left[2\omega(\sigma - 1) - \sqrt{\omega}(\sigma + 1)\right]\left\|\frac{d^2}{d\lambda^2}P(\phi_{\omega+c,\lambda,\omega+c,\lambda})\right\|_{\lambda=0}
\cdot \left[2\omega(\sigma - 1) - \sqrt{\omega}(\sigma + 1)\right]\cdot \kappa_0 z_0
\cdot \left[2\omega(\sigma - 1) - \sqrt{\omega}(\sigma + 1)\right]\cdot -\kappa_0 \sqrt{\omega}
\cdot \frac{2\kappa_0 \sqrt{\omega}(1 - z_0^2)}{2}.
\]

Let $b_1 = 2\kappa_0 \sqrt{\omega}(1 - z_0^2)$, then $b_1 > 0$. Hence, we obtain that
\[B(\lambda) = b_1 \lambda^2.\]

This concludes the proof of Lemma 10. □

4.2. Proof of Theorem 1. Now we give the proof of Theorem 1. Suppose that $e^{iat}\phi_{\omega,c}(x - ct)$ of (1.1) is stable. Choose
\[u_0 = \phi_{\omega,c} + \delta_1(-a_0\phi_{\omega,c} + i\partial_x\phi_{\omega,c}), \quad \delta_1 > 0.\]
Here $\delta_1$ is small enough such that $u_0 \in U_\delta(\phi_{\omega,c})$ which is given by Proposition 1.

Let $u$ be the corresponding solution of (1.1) with the initial data $u_0$. Then, we can write
\[u = e^{i\theta}(\phi_{\omega+c,\lambda,\omega+c,\lambda} + \varepsilon)(x - y),\]
with $(\theta, y, \lambda)$ obtained in Proposition 1 and $|\lambda| \ll 1$. 

---

**Comment:** The text contains a detailed mathematical proof, including definitions, theorems, and calculations, relevant to a specific mathematical problem. It involves differential equations, stability analysis, and proofs of propositions and lemmas. The notation and concepts are typical of advanced mathematical research, particularly in the field of dynamical systems or partial differential equations. The proof concludes with a statement that $\lambda$ is small enough and concludes with a mathematical expression that relates to the initial conditions and the stability of solutions. The proof is complete with a final assertion that $B(\lambda) = b_1 \lambda^2$. This indicates a successful proof of the theorem in question, as indicated by the □ symbol, signifying the end of the proof.
Lemma 11. There exists $b_2 > 0$, such that

$$A(u_0) \geq b_2 \delta_1.$$ 

Proof. Recalling that $c = 2z_0 \sqrt{\omega}$, $a_0 = (\sigma - 1) \sqrt{\omega}$ and the choose of $u_0$, we have

$$M(u_0) - M(\phi_{\omega,c}) = \delta_1 (M'(\phi_{\omega,c}), -a_0 \phi_{\omega,c} + i \partial_x \phi_{\omega,c}) + o(\delta_1)$$

$$= \delta_1 [-2a_0 M(\phi_{\omega,c}) + 2P(\phi_{\omega,c})] + o(\delta_1)$$

$$= o(\delta_1), \quad (4.8)$$

and

$$P(u_0) - P(\phi_{\omega,c}) = \delta_1 (P'(\phi_{\omega,c}), -a_0 \phi_{\omega,c} + i \partial_x \phi_{\omega,c}) + o(\delta_1)$$

$$= 2(\omega - a_0^2) M(\phi_{\omega,c}) \delta_1 + o(\delta_1)$$

$$= 2\omega \sigma (2 - \sigma) M(\phi_{\omega,c}) \delta_1 + o(\delta_1). \quad (4.9)$$

Moreover, using $S'_{\omega,c}(\phi_{\omega,c}) = 0$, we get

$$S_{\omega,c}(u_0) - S_{\omega,c}(\phi_{\omega,c}) = \delta_1 (S'_{\omega,c}(\phi_{\omega,c}), -a_0 \phi_{\omega,c} + i \partial_x \phi_{\omega,c}) + o(\delta_1)$$

$$= o(\delta_1). \quad (4.10)$$

Now, we collect the above computations and obtain

$$A(u_0) = (2c \sqrt{\omega} + 4\omega) \cdot o(\delta_1) + (4 \sqrt{\omega} - 2c) \cdot 2\omega \sigma (2 - \sigma) M(\phi_{\omega,c}) \delta_1 + o(\delta_1) - 4 \cdot o(\delta_1)$$

$$= 8\omega \sqrt{\omega} \sigma (2 - \sigma) M(\phi_{\omega,c}) \delta_1 + o(\delta_1)$$

$$\geq b_2 \delta_1,$$

where choose $b_2 = 4\omega \sqrt{\omega} \sigma (2 - \sigma) M(\phi_{\omega,c}) > 0$. This proves the lemma. $\square$

We further give the estimate on $\|\varepsilon\|_{H^1(\mathbb{R})}^2$.

Lemma 12. Let $\varepsilon$ be defined in (3.1), there exists $b_3 > 0$, then

$$\|\varepsilon\|_{H^1(\mathbb{R})}^2 \leq b_3 \lambda \delta_1.$$ 

Proof. Without loss of generality, we may assume that $\nu > 0$. From the conservation laws, we have

$$S_{\omega+\lambda \mu, c+\lambda \nu}(u_0) = S_{\omega+\lambda \mu, c+\lambda \nu}(u)$$

$$= S_{\omega+\lambda \mu, c+\lambda \nu}(\phi_{\omega+\lambda \mu, c+\lambda \nu}) + \frac{1}{2} (S''_{\omega+\lambda \mu, c+\lambda \nu}(\phi_{\omega+\lambda \mu, c+\lambda \nu}) \varepsilon, \varepsilon) + o(\|\varepsilon\|_{H^1(\mathbb{R})}^2).$$

Combining (2.2) and Lemma 3 yields

$$S_{\omega+\lambda \mu, c+\lambda \nu}(\phi_{\omega+\lambda \mu, c+\lambda \nu}) = S_{\omega+\lambda \mu, c+\lambda \nu}(\phi_{\omega,c}) + \lambda (S''_{\omega+\lambda \mu, c+\lambda \nu}(\phi_{\omega,c}), \psi)$$

$$+ \frac{1}{2} \lambda^2 (S''_{\omega+\lambda \mu, c+\lambda \nu}(\phi_{\omega,c}), \psi, \psi) + o(\lambda^2)$$

$$= S_{\omega+\lambda \mu, c+\lambda \nu}(\phi_{\omega,c}) + \lambda (S''_{\omega,c}(\phi_{\omega,c}), \psi) + \lambda \mu (M'(\phi_{\omega,c}), \psi)$$

$$+ \lambda \nu (P'(\phi_{\omega,c}), \psi) + \frac{1}{2} \lambda^2 (S''_{\omega,c}(\phi_{\omega,c}), \psi, \psi) + o(\lambda^2)$$

$$= S_{\omega+\lambda \mu, c+\lambda \nu}(\phi_{\omega,c}) + o(\lambda^2).$$
Then, we have

\[ S_{\omega + \lambda, \mu, c + \lambda v}(u_0) = S_{\omega, \lambda, \mu, c + \lambda v}(\phi_{\omega, c}) + \frac{1}{2} \langle S''_{\omega + \lambda, \mu, c + \lambda v}(\phi_{\omega, \lambda, \mu, c + \lambda v}) \varepsilon, \varepsilon \rangle + o(\lambda^2 + \| \varepsilon \|^2_{H^1(\mathbb{R})}) . \]

Together with (4.8), (4.9) and (4.10), we have

\[ S_{\omega, \lambda, \mu, c + \lambda v}(u_0) - S_{\omega, \lambda, \mu, c + \lambda v}(\phi_{\omega, c}) = 2\nu \omega \sigma (2 - \sigma) M(\phi_{\omega, c}) \lambda \delta_1 + o(\delta_1) . \]

Therefore, by (3.2), (3.8) and (4.11), there exists \( C > 0 \), such that

\[ \| \varepsilon \|^2_{H^1(\mathbb{R})} \leq C \langle S''_{\omega, \lambda, \mu, c + \lambda v}(\phi_{\omega, \lambda, \mu, c + \lambda v}) \varepsilon, \varepsilon \rangle \]

\[ = C \left[ S_{\omega, \lambda, \mu, c + \lambda v}(u_0) - S_{\omega, \lambda, \mu, c + \lambda v}(\phi_{\omega, c}) \right] + o(\lambda^2 + \| \varepsilon \|^2_{H^1(\mathbb{R})}) \]

\[ = 2C \nu \omega \sigma (2 - \sigma) M(\phi_{\omega, c}) \lambda \delta_1 + o(\delta_1) + o(\lambda^2 + \| \varepsilon \|^2_{H^1(\mathbb{R})}) \]

\[ \leq 2b_3 \lambda \delta_1 + o(\| \varepsilon \|^2_{H^1(\mathbb{R})}) , \]

where \( b_3 = 2C \nu \omega \sigma (2 - \sigma) M(\phi_{\omega, c}) > 0 \). Then we obtain

\[ \| \varepsilon \|^2_{H^1(\mathbb{R})} \leq b_3 \lambda \delta_1 . \]

This completes the proof. \( \square \)

**Proof of Theorem 1.** On the one hand, we note that from the definition of \( I(t) \), we have the time uniform boundedness of \( I(t) \). That is, if \( |\lambda| \ll 1 \), then

\[ \sup_{t \in \mathbb{R}} I(t) \lesssim R(\| \phi_{\omega, c} \|^2_{H^1(\mathbb{R})} + 1) . \] (4.12)

On the other hand, using (3.8) and Lemmas 10, 11 we get

\[ I'(t) = A(u_0) + B(\lambda) + O(\lambda \| \varepsilon \|^2_{H^1(\mathbb{R})} + \| \varepsilon \|^2_{H^1(\mathbb{R})} + \frac{1}{R}) + o(\lambda^2) \]

\[ \geq b_2 \delta_1 + b_1 \lambda^2 + O\left( \| \varepsilon \|^2_{H^1(\mathbb{R})} + \frac{1}{R} \right) + o(\lambda^2) \]

\[ \geq \frac{1}{2} b_2 \delta_1 + \frac{1}{2} b_1 \lambda^2 + O\left( \| \varepsilon \|^2_{H^1(\mathbb{R})} \right) , \]

where choosing \( R \geq 10(b_2 \delta_1)^{-1} \).

Moreover, combining Lemme 12 yields

\[ I'(t) \geq \frac{1}{4} b_2 \delta_1 + \frac{1}{2} b_1 \lambda^2 > 0 , \]

when \( |\lambda| \ll 1 \).

This implies that \( I(t) \to +\infty \) when \( t \to +\infty \), which is contradicted with (4.12). Hence we prove the instability of the solitary wave solutions \( e^{i\omega t} \phi_{\omega, c}(x - ct) \) of (1.1). This completes the proof of Theorem 1. \( \square \)
Appendix: Proof of Lemma 3 and Lemma 4

Throughout this section, let \(1 < \sigma < 2\) and \(z_0 = z_0(\sigma) \in (-1, 1)\) satisfy \(F_\sigma(z_0) = 0\).

Now we adopt some notations from [29]. More precisely, for any \((\omega, c) \in \mathbb{R}^2\) satisfying \(c^2 < 4\omega\), we denote
\[
\kappa = \sqrt{4\omega - c^2} > 0, \quad \tilde{\kappa} = 2^{\frac{1}{\sigma} - 2} \sigma^{-1} (1 + \sigma)^{\frac{1}{2} - \frac{2}{\sigma} - 2\omega - \frac{1}{2}}, \quad f(\omega, c) = \frac{(\sigma + 1)\kappa^2}{2\sqrt{\omega}},
\]
\[
h(x; \sigma; \omega, c) = \cosh(\sigma \kappa x) - \frac{c}{2\sqrt{\omega}}, \quad \alpha_n = \int_0^\infty \frac{h}{2^n} \, dx, \, n \in \mathbb{Z}^+.
\]

Proof of Lemma 3. For any \((\omega, c) \in \mathbb{R}^2\) satisfy \(c^2 < 4\omega\), by (1.3), we have
\[
\partial_x \phi_{\omega,c}(x) = e^{i\theta} \left[ (i\frac{c}{2} - i\frac{\varphi_{2\sigma,c}}{2\sigma + 2}) \varphi_{\omega,c} + \partial_x \varphi_{\omega,c} \right].
\]
Therefore, we have
\[
P(\phi_{\omega,c}) = \frac{1}{2} \text{Im} \int_\mathbb{R} \phi_{\omega,c} \partial_x \phi_{\omega,c} \, dx
\]
\[
= \frac{1}{2} \text{Im} \int_\mathbb{R} \left[ (i\frac{c}{2} - i\frac{\varphi_{2\sigma,c}}{2\sigma + 2}) \varphi_{\omega,c}^2 \right] \, dx
\]
\[
= - \frac{c}{4} \| \varphi_{\omega,c} \|_{L^2}^2 + \frac{1}{4(\sigma + 1)} \| \varphi_{\omega,c} \|_{L^{2\sigma+2}}^{2\sigma+2}.
\]
Finally, we obtain
\[
\| \varphi_{\omega,c} \|^2_{L^{2\sigma+2}} = 4(\sigma + 1) \left[ \frac{c}{2} M(\phi_{\omega,c}) + P(\phi_{\omega,c}) \right].
\]

According to [29] Appendix Lemma A.3, we have that
\[
\partial_{\omega} M(\phi_{\omega,c}) = \partial_c P(\phi_{\omega,c}), \quad \partial_c P(\phi_{\omega,c}) = \omega \partial_{\omega} M(\phi_{\omega,c}).
\]
This completes the proof. \(\square\)

Now, we focus on the critical case \(c = 2z_0\sqrt{\omega}\).

Proof of Lemma 4. From [29] Lemma 4.2, \(\det[d''(\omega, c)] = 0\) is equivalent to
\[
[(\sigma - 1) \sqrt{\omega} M(\phi_{\omega,c})]^2 = P(\phi_{\omega,c})^2.
\]
When \(c = 2z_0\sqrt{\omega}\), we have \(P(\phi_{\omega,c}) > 0\). Indeed, if \(P(\phi_{\omega,c}) < 0\), since \(\frac{P(\phi_{\omega,c})}{M(\phi_{\omega,c})} \to +\infty\), where \(c \to -2\sqrt{\omega}\). Then there exist two solutions \(c_1 = c_1(\sqrt{\omega}), c_2 = c_2(\sqrt{\omega})\), such that
\[
\left| \frac{P(\phi_{\omega,c})}{M(\phi_{\omega,c})} \right| = (\sigma - 1) \sqrt{\omega}.
\]
This contradicts the fact that \(z_0\) is the unique solution of \(\det[d''(\omega, c)] = 0\). Hence,
\[
P(\phi_{\omega,c}) > 0, \quad P(\phi_{\omega,c}) = (\sigma - 1) \sqrt{\omega} M(\phi_{\omega,c}).
\]
From [29] Appendix (A.2) Lemmas A.1 and A.2, we know that \( M(\phi_{\omega,c}) = f_{\omega}^{1/2} \alpha_0 \) and \( P(\phi_{\omega,c}) = \frac{1}{4\sqrt{\omega}} f_{\omega}^{1/2} (-2\omega^{1/2} c \alpha_0 + \kappa^2 \alpha_1) \). Since \( P(\phi_{\omega,c}) > 0 \), then we have

\[ \kappa^2 \alpha_1 > 2\omega^{1/2} c \alpha_0. \]

Together with [29] Appendix Lemma A.3, we obtain

\[ \partial_\omega M(\phi_{\omega,c}) \approx \kappa^{-1} [ -8(\sigma - 1) \omega^{1/2} \alpha_0 + c(2\omega^{1/2} c \alpha_0 - \kappa^2 \alpha_1) ] < 0, \]
\[ \partial_\omega P(\phi_{\omega,c}) = 2\kappa [2c \omega^{1/2} \alpha_0 (\sigma - 1) - 2c \omega^{1/2} \alpha_0 + \kappa^2 \alpha_1] > 0. \]

On the one hand, by \( \partial_c P(\phi_{\omega,c}) = \omega \partial_\omega M(\phi_{\omega,c}) \) and \( \partial_\omega P(\phi_{\omega,c}) = \partial_\omega M(\phi_{\omega,c}) \), we have

\[ \frac{\mu}{\nu} = -\frac{\partial_c M(\phi_{\omega,c})}{\partial_\omega M(\phi_{\omega,c})} = -\frac{\partial_\omega P(\phi_{\omega,c})}{\partial_\omega M(\phi_{\omega,c})} > 0. \]

On the other hand,

\[ \frac{\mu}{\nu} = -\frac{\partial_\omega P(\phi_{\omega,c})}{\partial_\omega M(\phi_{\omega,c})} = -\frac{\omega \partial_\omega M(\phi_{\omega,c})}{\partial_\omega P(\phi_{\omega,c})}. \]

Hence, combining with above, we get

\[ \left( \frac{\mu}{\nu} \right)^2 = -\frac{\partial_\omega P(\phi_{\omega,c})}{\partial_\omega M(\phi_{\omega,c})} \cdot -\frac{\omega \partial_\omega M(\phi_{\omega,c})}{\partial_\omega P(\phi_{\omega,c})} = \omega. \]

Then we obtain

\[ \frac{\mu}{\nu} = \sqrt{\omega}. \]

Differentiating \( M(\phi_{\omega,c}) \) and \( P(\phi_{\omega,c}) \) with respect to \( \omega \) and \( c \), we have the following relations:

\[ \partial_{\omega\omega} M(\phi_{\omega,c}) = \frac{1}{\omega} (\partial_{\omega c} P(\phi_{\omega,c}) - \partial_\omega M(\phi_{\omega,c})), \]
\[ \partial_{\omega c} M(\phi_{\omega,c}) = \partial_{\omega\omega} P(\phi_{\omega,c}), \]
\[ \partial_{cc} M(\phi_{\omega,c}) = \partial_{\omega c} P(\phi_{\omega,c}), \]
\[ \partial_{cc} P(\phi_{\omega,c}) = \omega \partial_{\omega\omega} P(\phi_{\omega,c}). \]

Since \( \partial_\omega P(\phi_{\omega,c}) = \sqrt{\omega} \partial_\omega M(\phi_{\omega,c}) \), we obtain \((z_0^2 - 1) \alpha_1 = (1 - z_0 - \sigma) \alpha_0\). From [4] Appendix Lemma 10, we have

\[ \partial_\omega M(\phi_{\omega,c}) = 8\sqrt{\omega} \kappa \alpha_0 (z_0^2 - \sigma + 1) + 8\sqrt{\omega} \kappa \alpha_1 z_0 (z_0^2 - 1) = 8\sqrt{\omega} \kappa \alpha_0 (1 - \sigma)(1 + z_0), \]
\[ 2\sqrt{\omega} \partial_{\omega\omega} P(\phi_{\omega,c}) + 2\partial_\omega P(\phi_{\omega,c}) - \frac{1}{2} \partial_\omega M(\phi_{\omega,c}) = -4\sqrt{\omega} \kappa \alpha_0 (1 - \sigma)(1 + z_0), \]

and

\[ \mu^2 \partial_{\omega\omega} P(\phi_{\omega,c}) + 2\mu \nu \partial_{\omega c} P(\phi_{\omega,c}) + \nu^2 \partial_{cc} P(\phi_{\omega,c}) = -8\nu^2 \omega \kappa \alpha_0 (\sigma - 1). \]

Moreover, we have

\[ \mu^2 \partial_{\omega\omega} M(\phi_{\omega,c}) + 2\mu \nu \partial_{\omega c} M(\phi_{\omega,c}) + \nu^2 \partial_{cc} M(\phi_{\omega,c}) \]
\[ = \nu^2 [\omega \partial_{\omega\omega} M(\phi_{\omega,c}) + 2\sqrt{\omega} \partial_{\omega c} M(\phi_{\omega,c}) + \partial_{cc} M(\phi_{\omega,c})] \]
\[ = \nu^2 [-\partial_\omega M(\phi_{\omega,c}) + \partial_{cc} M(\phi_{\omega,c}) + 2\sqrt{\omega} \partial_{\omega\omega} P(\phi_{\omega,c})] \]
\[ = \nu^2 [2\sqrt{\omega} \partial_{\omega\omega} P(\phi_{\omega,c}) + 2\partial_{\omega c} P(\phi_{\omega,c}) - \frac{1}{2} \partial_\omega M(\phi_{\omega,c}) - \frac{1}{2} \partial_\omega M(\phi_{\omega,c})] \]
\[ = \nu^2 [-4\sqrt{\omega} \kappa \alpha_0 (\sigma - 1)(1 - z_0) + 4\sqrt{\omega} \kappa \alpha_0 (1 - \sigma)(z_0 + 1)] \]
\[ = 8\nu^2 \sqrt{\omega} \kappa \alpha_0 (\sigma - 1) z_0. \]
Take $\kappa_0 = 8\nu^2 \sqrt{\omega \kappa_0 \alpha_0 (\sigma - 1)}$, then $\kappa_0 > 0$. This concludes the proof of Lemma 4. □

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SOLITARY WAVE SOLUTIONS FOR DNLS

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