Additive kinematic formulas for flag area measures

Judit Abardia-Evéquoz · Andreas Bernig

Received: 30 March 2020 / Revised: 26 April 2021 / Accepted: 13 August 2021 / Published online: 27 August 2021 © The Author(s) 2021

Abstract
We show the existence of additive kinematic formulas for general flag area measures, which generalizes a recent result by Wannerer. Building on previous work by the second named author, we introduce an algebraic framework to compute these formulas explicitly. This is carried out in detail in the case of the incomplete flag manifold consisting of all \((p + 1)\)-planes containing a unit vector.

Mathematics Subject Classification Primary 52A20 · 52B45; Secondary 52A39

Contents

1 Introduction ............................................ 1616
  1.1 Global and local kinematic formulas ........................................ 1616
  1.2 Results of the present paper .................................. 1618
2 Existence of kinematic formulas for smooth flag area measures ................. 1622
  2.1 Fiber integration ........................................ 1622
  2.2 Smooth flag area measures .................................. 1623
  2.3 Kinematic formulas ...................................... 1624
3 Dual flag area measures ...................................... 1627
4 Rotation measures ......................................... 1633
  4.1 Classification of rotation measures .................................... 1633
  4.2 Dual rotation measures .................................... 1635
5 Algebraic structure of FlagArea\((p)\).SO\((n)\),* ............................................. 1640
6 Bases for FlagArea\((p)\).SO\((n)\) and FlagArea\((p)\).SO\((n)\),* ...................... 1643

Communicated by Andreas Thom.

J. A. was supported by DFG Grant AB 584/1-2. A. B. was supported by DFG Grant BE 2484/5-2.

✉ Judit Abardia-Evéquoz
abardia@math.uni-frankfurt.de

Andreas Bernig
bernig@math.uni-frankfurt.de

1 Institut für Mathematik, Goethe-Universität Frankfurt am Main, Robert-Mayer-Str. 10, 60054 Frankfurt, Germany
1 Introduction

1.1 Global and local kinematic formulas

Let $V$ be a Euclidean vector space of dimension $n$ and unit sphere $S^{n-1}$. Let $\mathcal{K}(V)$ denote the space of compact convex subsets in $V$. A valuation is a finitely additive map on $\mathcal{K}(V)$, that is, a map $\mu : \mathcal{K}(V) \to A$, where $A$ is any abelian semigroup, and such that

$$\mu(K \cup L) + \mu(K \cap L) = \mu(K) + \mu(L),$$

whenever $K$, $L$, $K \cup L \in \mathcal{K}(V)$. If $A$ is a topological semigroup, then continuity of $\mu$ is understood with respect to the Hausdorff topology on $\mathcal{K}(V)$.

The intrinsic volumes $\mu_0, \ldots, \mu_n$ are examples of real valued valuations. They are continuous, translation invariant, and invariant under rotations. Hadwiger has shown that the space $\text{Val}^{\text{SO}(n)}$ of continuous, translation and rotation invariant valuations is spanned by the intrinsic volumes. If $G$ is a subgroup of $\text{SO}(n)$, then $\text{Val}^G$ (the space of continuous, translation invariant and $G$-invariant valuations) is finite-dimensional if and only if $G$ acts transitively on the unit sphere.

The classification of connected compact Lie groups $G$ acting transitively on some sphere is a topological problem which was solved by Montgomery-Samelson [33] and Borel [17]. There are six infinite lists

$$\text{SO}(n), \text{U}(n/2), \text{SU}(n/2), \text{Sp}(n/4), \text{Sp}(n/4) \cdot \text{U}(1), \text{Sp}(n/4) \cdot \text{Sp}(1),$$

and three exceptional groups

$$G_2, \text{Spin}(7), \text{Spin}(9).$$

For the sake of brevity, we will call a group from this list a transitive group. The computation of the dimension as well as an explicit geometric description of a basis of $\text{Val}^G$ in each of these cases is a challenging problem and many results have been obtained recently by various authors [2,5–7,10,14–16].

Many important constructions in convex geometry can be interpreted as valuations taking values in some abelian semigroup $A$ other than $\mathbb{R}$. Besides curvature and area measures (see below), we mention two other cases. If $A = (\mathcal{K}(V), +)$, where $+$ stands for the Minkowski sum, then $A$-valued valuations are called Minkowski valuations [23,32,38,39]. If $A = \text{Sym}^* V$, then $A$-valued valuations are called tensor valuations [13,18,25–27,29,31].

Federer’s curvature measures $C_0, \ldots, C_n$ are valuations with values in the space of signed measures on $V$. We refer to Schneider [36] for a classification result of these
Additive kinematic formulas. . .

curvature measures. Fu [21] and Bernig-Fu-Solanes [11] studied smooth curvature measures in a broader context. For a transitive group $G$, there are local kinematic formulas for translation and $G$-invariant smooth curvature measures. The case $G = \text{SO}(n)$ was considered by Federer, whereas the hermitian case $G = \text{U}(n/2)$ was described completely in [10–12].

The classical surface area measures $S_0, \ldots, S_{n-1}$ are valuations with values in the space of signed measures on the unit sphere. Additive kinematic formulas for surface area measures have been shown in [35]. Smooth area measures which are equivariant with respect to a transitive group $G$ were introduced by Wannerer [41,42], who proved the existence of local additive kinematic formulas and established such formulas in the hermitian case. Since these results are very influential for the present work, let us state them explicitly.

**Theorem 1.1** Let $G$ be a transitive group. Then the space $\text{Area}^G$ of smooth, $G$-invariant area measures is finite-dimensional. If $\Phi_1, \ldots, \Phi_N$ is a basis of $\text{Area}^G$, then there are local additive kinematic formulas

$$\int_G \Phi_i(K + gL, \kappa \cap g\lambda)dg = \sum c^i_{k,l} \Phi_k(K, \kappa) \Phi_l(L, \lambda),$$

where $K, L \in \mathcal{K}(V)$ and where $\kappa$ and $\lambda$ are Borel subsets of $S^{n-1}$.

The linear map

$$A : \text{Area}^G \to \text{Area}^G \otimes \text{Area}^G, \Phi_i \mapsto \sum c^i_{k,l} \Phi_k \otimes \Phi_l$$

is a cocommutative, coassociative coproduct. The transposed map $A^* : \text{Area}^{G,*} \otimes \text{Area}^{G,*} \to \text{Area}^{G,*}$ thus provides $\text{Area}^{G,*}$ with the structure of a commutative associative algebra.

In the case $G = \text{SO}(n)$, this algebra is isomorphic to $\mathbb{R}[t]/\langle t^n \rangle$. The case $G = \text{U}(n/2)$ is more involved. Using results from hermitian integral geometry [10] and from the theory of tensor valuations [13], Wannerer could write down this algebra in an explicit way.

**Theorem 1.2** The algebra $\text{Area}^{\text{U}(n/2),*}$ is isomorphic to

$$\mathbb{R}[s, t, v]/I_n,$$

where $I_n$ is the ideal generated by

$$f_{n/2+1}(s, t), f_{n/2+2}(s, t), p_{n/2}(s, t) - q_{n/2-1}(s, t)v, v^2$$

with

$$\log(1 + tx + sx^2) = \sum_{k=0}^{\infty} f_k(s, t)x^k$$

$\Box$ Springer
\[
\frac{1}{1 + tx + sx^2} = \sum_{k=0}^{\infty} p_k(s, t)x^k - \frac{1}{(1 + tx + sx^2)^2} = \sum_{k=0}^{\infty} q_k(s, t)x^k.
\]

Although it is possible to write down the local additive kinematic formulas for \( G = U(n/2) \) using this theorem, the result is not as explicit as one would like. In [8], the second named author has shown that the algebra structure on \( \text{Area}^{G,*} \) is induced from the algebra structure of a larger (infinite-dimensional) space \( \text{Area}^{*,sm} \) of smooth dual area measures and that the product in this algebra can be computed in some easy, algorithmic way. This has led to very explicit local additive kinematic formulas.

1.2 Results of the present paper

Let \( V \) be an oriented \( n \)-dimensional Euclidean vector space with unit sphere \( S^{n-1} \). We denote by \( \text{vol}_V \) the volume form. Let \( G \) be a subgroup of \( O(n) \) acting transitively on the sphere \( S^{n-1} \) and let \( \overline{G} : = G \rtimes V \).

Let \( H \) be a closed subgroup of \( G \cap O(n-1) \), where \( O(n-1) \subset O(n) \) is the stabilizer of the first basis vector. Then \( M : = G/H \) is a \( G \)-homogeneous manifold.

A smooth flag area measure is a translation invariant valuation with values in the space of signed measures on \( M = G/H \) which is given by a certain smooth differential form on \( V \times M \). We denote by \( \text{Area}_{G/H} \) the space of smooth flag area measures and by \( \text{Area}_{G/G/H} \) the subspace of smooth flag area measures which are equivariant with respect to the action, i.e.,

\[ \Phi(gK, g\kappa) = \Phi(K, \kappa), K \in \mathcal{K}(V), \kappa \in \mathcal{B}(M), g \in G. \]

We refer to Sect. 2 for the complete definition.

Our first two main theorems generalize [41, Corollary 3.1] and [8, Theorem 2], where the special case \( M = S^{n-1} \) was considered.

**Theorem 1** (Existence of local additive kinematic formulas) The space \( \text{Area}_{G/H} \) is finite-dimensional if and only if \( G \) acts transitively on the unit sphere. In this case, if \( \{\Phi_1, \ldots, \Phi_N\} \) is a basis of \( \text{Area}_{G/H} \), then there exist local additive kinematic formulas

\[
\int_G \Phi_i(K + gL, \kappa \cap g\lambda)dg = \sum_{k,l=1}^{N} c_{i,l}^{k} \Phi_k(K, \kappa)\Phi_l(L, \lambda),
\]

where \( \kappa, \lambda \) are Borel subsets of \( M \).

Examples:

(i) Let \( G \) be a subgroup of \( O(n) \) which acts transitively on \( S^{n-1} \). Let \( H = G \cap O(n-1) \) be the stabilizer of the action. Then \( M = S^{n-1} \) and the flag area
measures in this case are called area measures. The kinematic formulas in the case $G = O(n)$ are classical [35]. For more general $G$, Wannerer has shown the existence of kinematic formulas [41, Theorem 2.1] and our proof follows his arguments. Explicit formulas in the hermitian case $G = U(n)$ are contained in [8, 40, 41].

(ii) Let $G = SO(n)$, $H = S(O(p) \times O(q))$, $p + q = n - 1$. Then $M = \text{Flag}_{1,p+1}$ is the incomplete flag manifold consisting of pairs $(v, E)$ with $v \in S^{n-1}$, $E \in \text{Gr}_{p+1}(V)$. Some elements in the space $\text{FlagArea}^{(p), SO(n)} := \text{Area}^{G}_{G/H}$ were constructed using a Steiner type formula in [28], see also [24]. A complete description of this space was given in [1].

(iii) If $G \subset SO(n)$ and $H = \{1\}$, we also call the elements in $\text{Area}^{G}_{G/[1]}$ rotation measures. They will be studied in Sect. 4.

The local additive kinematic formulas can be encoded by the map

$$A : \text{Area}^{G}_{G/H} \to \text{Area}^{G}_{G/H} \otimes \text{Area}^{G}_{G/H}, \quad \Phi_i \mapsto \sum_{k,l} c_{k,l}^i \Phi_k \otimes \Phi_l,$$

which is a cocommutative, coassociative coproduct. Alternatively, the dual space $(\text{Area}^{G,*}_{G/H}, A^*)$ is a commutative, associative algebra.

We give an explicit construction and classification of rotation measures. Consider a smooth compact convex body and $x \in \partial K$. Let $v(x)$ be the outer normal vector at $x$. Given $g \in SO(n)$ with $ge_1 = v(x)$, the vectors $ge_2, \ldots, ge_n$ span $T_x \partial K$. The shape operator is the self-adjoint linear map $S_x := dv_x : T_x \partial K \to T_x \partial K$.

**Theorem 2** The space of rotation measures of degree $k$ is of dimension

$$\dim \text{Area}^{SO(n),*}_{k,SO(n)/[1]} = \frac{1}{n} \binom{n}{k} \binom{n}{k+1}.$$  

For each $0 \leq k \leq n - 1$ and for each $k$-tuples $I$, $J$ of distinct numbers from $\{2, \ldots, n\}$ with $|I| = |J| = k$ there exists a unique rotation measure $S_{I,J} \in \text{Area}^{SO(n)}_{SO(n)/[1],k}$ such that for every compact convex body with smooth boundary

$$S_{I,J}(K, f) = \int_{\partial K} \int_{g \in SO(n)} f(g) \det(\pi_{J^\perp} \circ S_x | V_{I^\perp} : V_{I^\perp} \to V_{J^\perp})dg \, d\mathcal{H}^{n-1}(x).$$  

Here $V_I = \text{span}\{ge_i, i \in I\}$, $V_J := \text{span}\{ge_j, j \in J\}$ are oriented $k$-dimensional subspaces of $T_x \partial K$, $\pi_{J^\perp} : T_x \partial K \to V_{J^\perp}$ is the orthogonal projection, and $d\mathcal{H}^{n-1}$ is the $(n-1)$-dimensional Hausdorff measure.

There are linear relations among these rotation measures: $S_{I,J}$ is antisymmetric in $I$ and antisymmetric in $J$. Moreover, given $I' = (i'_1, \ldots, i'_{k+1}) \subset \{2, \ldots, n\}$, $J' = (j'_1, \ldots, j'_{k+1}) \subset \{2, \ldots, n\}$ we have

$$\sum_{l=1}^{k+1} (-1)^l S_{[i'_1, \ldots, i'_{k-1}, j'_l, i'_{k+1}], [j'_1, \ldots, j'_{k-1}, j'_l, i'_1, \ldots, i'_{k+1}]} = 0.$$  

\[ \text{Springer} \]
The space $\text{Area}_{\text{SO}(n)/[1],k}$ of rotation measures is isomorphic to the quotient of the vector space spanned by the $S_{i,j}$ by the relations (2).

The next theorem describes algebraically the kinematic formulas for $\text{Area}_{G/H}$ for any closed subgroup $H \subset \text{SO}(n-1)$.

Let us write $S_{i,j} = S_{i_1,j_1}, S_{i_2,j_2}$ in the case $k = 1$. Then (2) translates to $S_{i,j} = S_{j,i}$. Hence the element $\frac{S_{i,j} + S_{j,i}}{2}$ belongs to $\text{Area}_{\text{SO}(n)/[1],1}$.

Recall that the volume of the special orthogonal group is given by

$$\text{vol}(\text{SO}(n)) = 2^{n-1} \frac{n(n+1)}{4} \prod_{i=1}^{n} \Gamma\left(\frac{i}{2}\right).$$

**Theorem 3** The map $x_{i,j} \mapsto -\text{vol}(\text{SO}(n)) \cdot \frac{S_{i,j} + S_{j,i}}{2}$ induces a graded algebra morphism

$$\mathbb{R}[X]/I \cong \text{Area}_{\text{SO}(n)/[1]}^*,$$

where $X := (x_{i,j})_{2 \leq i,j \leq n}$ and where $I \subset \mathbb{R}[X]$ is the ideal generated by

$$x_{i,j}x_{k,l} + x_{i,k}x_{j,l} + x_{i,l}x_{j,k}, \quad x_{i,j} - x_{j,i}.$$ 

If $H \subset \text{SO}(n-1)$ is a closed subgroup, then

$$\text{Area}_{\text{SO}(n)/H}^* \cong (\mathbb{R}[X]/I)^H,$$

with respect to the action $h^*X = h^t X h$.

In the important case of the incomplete flag manifold consisting of pairs $(v, E)$ with $\dim E = p+1$, $v \in E$, we write down the algebra structure more explicitly.

**Proposition 1.3** Let $p+q = n-1$, $G = \text{SO}(n)$, $H = S(\text{O}(p) \times \text{O}(q))$, $M = G/H = \text{Flag}_{1,p+1}$. If $p \neq \frac{n-1}{2}$, then there is a graded isomorphism

$$\text{FlagArea}_{(p),\text{SO}(n)}^* \cong \mathbb{R}[x, y]/(x^{p+1}, y^{q+1}),$$

where $\deg x = \deg y = 1$. If $p = q = \frac{n-1}{2}$, then there is a graded isomorphism

$$\text{FlagArea}_{(p),\text{SO}(n)}^* \cong \mathbb{R}[x, y, u]/\left(x^{p+1}, y^{p+1}, ux, uy, u^2 - (-1)^p \frac{p+1}{2^{2p}} x^p y^p\right),$$

where $\deg u = \frac{n-1}{2}$.

A basis of the space $\text{FlagArea}_{(p),\text{SO}(n)}^*$ consists of flag area measures $S_{k,l}^{(p),i}$, where $0 \leq k \leq n-1$, $0 \leq i \leq m_k$ (together with an additional flag area measure $S_{\frac{n-1}{2},l}^{(p),i}$ if

$\square$ Springer
If $p = q = \frac{n-1}{2}$, see [1]. The algebra structure given in the previous corollary translates into explicit kinematic formulas for these flag area measures.

Let $\omega_n$ denote the volume of the $(n - 1)$-dimensional unit sphere and let

$$c_{n,k,p,i} := \binom{n-1}{k}^{-1} \binom{m_k}{i}^{-1} \binom{|k-q|+m_k}{i}^{-1} \binom{n-1}{i},$$

as in [1]. For given $p, q, k$, we write $m_k := \min\{p, q, k, n-k-1\}$, $m'_k := \min\{p, k\}$ and define

$$C_{j,b,c}^{k,i} := (-1)^{b+c+m'_j+m'_{k-j}} \frac{c_{n,k,p,i}}{c_{n,j,p,b} c_{n,k-j,p,c}} \sum_{t=m'_k-m_k}^{m'-i} (-1)^i \binom{m'_k-t}{i}.$$ 

We do not know whether this expression can be simplified any further.

**Theorem 4** (Local additive kinematic formulas for flag area measures) Let $0 \leq p, k \leq n-1$, and $0 \leq i \leq m_k$. Then,

(i) If $(k, p) \neq (n-1, \frac{n-1}{2})$, $(\frac{n-1}{2}, \frac{n-1}{2})$, then

$$A_{1,p+1}^{SO(n)} \left(S_k^{(p),i}\right) = \frac{1}{\omega_n k} \sum_{j=0}^{m_k} \sum_{b=0}^{m'_{k-j}} \sum_{c=0}^{m'_{k-j}} C_{j,b,c}^{k,i} S_j^{(p),b} \otimes S_{k-j}^{(p),c},$$

(ii) If $(k, p) = (n-1, \frac{n-1}{2})$, then

$$A_{1,\frac{n+1}{2}}^{SO(n)} \left(S_{n-1}^{(\frac{n+1}{2}),0}\right) = \frac{1}{\omega_n} \sum_{j=0}^{\frac{n-1}{2}} \sum_{b=0}^{\frac{n-1}{2}} \sum_{c=0}^{\frac{n-1}{2}} C_{j,b,c}^{n-1, 0} S_j^{\left(\frac{n+1}{2}\right),b} \otimes S_{k-j}^{\left(\frac{n+1}{2}\right),c}$$

$$+ \frac{(-1)^n}{2^n \omega_n} \sum_{j=0}^{\frac{n-1}{2}} \sum_{b=0}^{\frac{n-1}{2}} \sum_{c=0}^{\frac{n-1}{2}} C_{j,b,c}^{n-1, 0} S_j^{\left(\frac{n+1}{2}\right),b} \otimes S_{k-j}^{\left(\frac{n+1}{2}\right),c},$$

(iii) If $(k, p) = (\frac{n-1}{2}, \frac{n-1}{2})$, then

$$A_{1,\frac{n+1}{2}}^{SO(n)} \left(S_{\frac{n+1}{2}}^{\left(\frac{n+1}{2}\right)}\right) = \frac{1}{\omega_n} \left(S_{\frac{n-1}{2}}^{\left(\frac{n+1}{2}\right)} \otimes S_0^{\left(\frac{n+1}{2}\right),0} + S_0^{\left(\frac{n+1}{2}\right),0} \otimes S_{\frac{n-1}{2}}^{\left(\frac{n+1}{2}\right)}\right).$$
2 Existence of kinematic formulas for smooth flag area measures

In this section we will introduce smooth area measures. Our definition will be justified by the existence of kinematic formulas for smooth area measures that will be shown in this section.

2.1 Fiber integration

We first collect some definitions and results from the theory of fiber bundles that will be used in the following.

Definition 2.1 Let \((E, \pi, B, F)\) be a fiber bundle, with \(B\) and \(E\) oriented manifolds and \(F\) compact with \(\text{dim } F = r\). The fiber integration or push-forward of a form \(\eta \in \Omega^{d+r}(E)\) is the form \(\pi_* \eta \in \Omega^d(B)\) such that

\[
\int_B \omega \wedge \pi_* \eta = \int_E \pi^* \omega \wedge \eta,
\]

for every differential form \(\omega \in \Omega^*(B)\) with compact support.

We then have the projection formula

\[
\pi_*(\pi^* \omega \wedge \eta) = \omega \wedge \pi_* \eta.
\]

We note that for the above definition of fiber integration, we follow the sign convention in [3], as in [1,41]. For another sign convention see, e.g., [4].

Lemma 2.2 [41, Equation (7)] Let \((E, \pi, B, F)\) be a fiber bundle, with \(B\) orientable and \(E\) oriented with the local product orientation. If \(N \subset B\) is a compact and oriented submanifold with \(\text{dim } N = n\) and \(\pi^{-1}(N) \subset E\) has the local product orientation, then, for every \(\omega \in \Omega^{n+r}(E)\) with fiber-compact support,

\[
\int_N \pi_* \omega = \int_{\pi^{-1}(N)} \omega.
\]

Lemma 2.3 [20, 4.3.2, 4.3.8] Let \(f : M \to N\) be a smooth and surjective map with \(M, N\) compact and oriented smooth manifolds with \(\text{dim } M = m\) and \(\text{dim } N = n\). Then \(f^{-1}(y)\) is an orientable smooth submanifold for almost every \(y \in N\). Let the orientation of \(M\) be given by a smooth \(m\)-vector field \(\xi\), and let the orientation of \(N\) be given by the smooth form \(dy \in \Omega^n(N)\). If the orientation of \(f^{-1}(y)\) is given by the smooth \((m-n)\)-vector field \(\xi \wedge f^* dy\) and if \(\mu\) denotes the measure given by \([[Y]] \wedge dy\), then

\[
\int_N \phi(y) \left( \int_{f^{-1}(y)} \omega \right) d\mu(y) = \int_M f^*(\varphi \wedge dy) \wedge \omega,
\]

for every continuous function \(\varphi : N \to \mathbb{R}\) and every \(\omega \in \Omega^{m-n}(M)\).
Lemma 2.4 [21] Let \((E, \pi, M, F)\) and \((E', \pi', M', F)\) be oriented fiber bundles with the same fiber \(F\). Assume that \(\overline{f} : E' \to E\) is a bundle map covering a smooth map \(f : M' \to M\) and that there exists an open cover \(\{U\}\) of \(M\) with local trivializations \(\varphi : \pi^{-1}(U) \to U \times F\) and \(\varphi' : \pi'^{-1}(f^{-1}(U)) \to f^{-1}(U) \times F\) compatible with the orientations of the bundle such that \(\varphi \circ \overline{f} = (f \times \text{id}_F) \circ \varphi'\), then

\[f^\ast \circ \pi^\ast = \pi'^\ast \circ \overline{f}^\ast.\]

2.2 Smooth flag area measures

Let us introduce our main object of study. Let \(e_1\) be the first standard vector in \(\mathbb{R}^n\) and let \(O(n-1)\) be its stabilizer. Let \(M := G/H\) be a homogeneous space, where \(G\) is a closed subgroup of \(O(n)\) and where \(H\) is a closed subgroup of \(G \cap O(n-1)\). Let \(\Pi : V \times M \to SV, (x, gH) \mapsto (x, ge_1)\), which is a fiber bundle. We let \(r\) denote the dimension of the fiber and \(m := n-1+r\).

**Definition 2.5** A translation invariant valuation \(\Phi\) with values in the space of signed measures on \(M\) is called a smooth flag area measure if there is a translation invariant differential form \(\omega \in \Omega^m(V \times M)\) such that for every \(f \in C^\infty(M)\) we have

\[\int_M fd\Phi(K, \cdot) = \int_{\text{nc}(K)} \Pi_\ast(f \omega),\]

where \(\text{nc}(K)\) denotes the normal cycle of \(K\). The space of smooth flag area measures is denoted by \(\text{Area}_{G/H}, \text{Area}_{G/H}^G\) denotes the subspace of smooth flag area measures equivariant under the action of \(G\) given by \((g\Phi)(K, f) = \Phi(g^{-1}K, g^*f)\).

**Definition 2.6** Let \(H_1 \subset H_2 \subset G\) be subgroups. Let \(\hat{\Pi} : V \times G/H_1 \to V \times G/H_2\) denote the projection map. The globalization map

\[\text{glob} : \text{Area}_{G/H_1} \to \text{Area}_{G/H_2}\]

is defined by

\[\int_{G/H_2} fd\text{glob} \Phi(K, \cdot) = \int_{G/H_1} \hat{\Pi}^\ast f d\Phi(K, \cdot), \quad f \in C^\infty(G/H_2).\]

**Lemma 2.7** Let \(\hat{\Phi} \in \text{Area}_{G/H_1}^G\) be represented by \(\hat{\omega}\). Then \(\text{glob} \hat{\Phi}\) is represented by \(\hat{\Pi}_\ast \hat{\omega}\).

**Proof** Let \(\Pi : V \times G/H_2 \to SV\) be the projection map. For \(f \in C^\infty(G/H_2)\) and \(K \in \mathcal{K}(V)\), we obtain, by using (3),
\[ \int_{G/H_2} f \, d \text{glob} \hat{\Phi}(K, \cdot) = \int_{G/H_1} \hat{\Pi}^* f \, d \hat{\Phi}(K, \cdot) \]
\[ = \int_{\text{nc}(K)} (\Pi \circ \hat{\Pi})_*(\hat{\Pi}^* f \cdot \hat{\omega}) \]
\[ = \int_{\text{nc}(K)} \Pi_*(f \cdot \hat{\Pi}_* \hat{\omega}). \]

Hence glob \( \hat{\Phi} \) is represented by the form \( \hat{\Pi}_* \hat{\omega} \).

The space \( \Omega^l(V \times M)^\text{tr} \) of translation invariant forms admits a filtration as follows. For \((x, gH) \in V \times M, 0 \leq j \leq l\), we define

\[ S^l,j_{x,gH} := \{ \phi \in \bigwedge^l T^*_{(x,gH)}(V \times M) : \forall v_1, \ldots, v_j \in T_{(x,gH)} \Pi^{-1}(\Pi(x, gH)), \phi(v_1, \ldots, v_j, -) = 0 \}, \]
\[ S^l,j := \{ \omega \in \Omega^l(V \times M)^\text{tr} : \forall (x, gH) \in V \times M, \omega|_{(x,gH)} \in S^l,j_{x,gH} \}, \]
\[ S^{*j} := \bigoplus_{l} S^l,j. \]

Then
\[ \Omega^l(V \times M)^\text{tr} = S^{l,r+1} \supset S^{l,r} \supset \ldots \supset S^{l,0} = \{0\}. \]

**Proposition 2.8** A form \( \tau \in \Omega^m(V \times M)^\text{tr} \) induces the trivial flag area measure if and only if

\[ \tau \in \langle \Pi^* \alpha, \Pi^* d\alpha, S^{m,r} \rangle. \]

**Proof** In the special case \( G = O(n), H = O(p) \times O(q) \), this was shown in [1, Theorem 2.3]. The proof can be easily adapted to the general case. \( \square \)

### 2.3 Kinematic formulas

If \( G \) is transitive, then the space of smooth flag area measures is a quotient of the finite-dimensional space \( \Omega^m(V \times M)^G \) and hence finite-dimensional itself. If \( G \) is not transitive, then \( \text{Val}^G \) is not finite-dimensional. Since we have a surjective map \( \text{glob} : \text{Area}^G_{G/H} \rightarrow \text{Val}^G, \dim \text{Area}^G_{G/H} = \infty \) as well in this case.

By using the definition of smooth flag area measures, we can restate the remaining part of Theorem 1 as follows.

**Theorem 2.9** Let \( G \) be transitive. Let \( \omega \in \Omega^m(V \times M)^\overline{G} \) and let \( \{ \omega_1, \ldots, \omega_N \} \) be a basis of \( \Omega^m(V \times M)^\overline{G} \). Then there exist constants \( c_{k,l} \) such that

\[ \int \int_{\text{nc}(K+gL)} \Pi_*(\varphi \cdot (g^{-1})^* \psi \cdot \omega) \, dg = \sum_{k,l} c_{k,l} \int_{\text{nc}(K)} \Pi_*(\varphi \omega_k) \int_{\text{nc}(L)} \Pi_*(\psi \omega_l). \]

\( \square \) Springer
where $\varphi, \psi \in C^\infty(M)$.

**Proof** (Proof of Theorem 2.9) We follow the ideas of Fu [21] and Wannerer [41]. We first assume that the convex bodies $K$ and $L$ have smooth boundaries and strictly positive Gauss curvature.

We define

$$E := \{(g, (x_i, p_i))_{i=1,2,3} \mid g \in G \times (V \times M)^3 : x_1 + g x_2 = x_3, p_1 = g p_2 = p_3\},$$

and the maps

$$p : E \rightarrow (V \times M) \times (V \times M)$$

$$(g, x_1, p_1, x_2, p_2, x_3, p_3) \mapsto ((x_1, p_1), (x_2, p_2)),$$

$$q : E \rightarrow G \times V \times M$$

$$(g, x_1, p_1, x_2, p_2, x_3, p_3) \mapsto (g, x_3, p_3).$$

We define $E'$ together with maps $p' : E' \rightarrow SV \times SV, q' : E' \rightarrow G \times SV$ in an analogous way, using $S^{n-1}$ instead of $M$. We then have a map

$$\Pi' : E \rightarrow E',$$

$$(g, (x_i, p_i)) \mapsto (g, \Pi(x_i, p_i)).$$

Let $q_1 : E \rightarrow G, q'_1 : E' \rightarrow G$ be the projections on the first factors. Let $\Pi_1, \Pi_2 : (V \times M) \times (V \times M) \rightarrow M$ be the projection maps onto the $M$-factors. Let $l_i : G \times V \times M \rightarrow M$ be defined by $l_1(g, x, p) := p, l_2(g, x, p) := g^{-1} p$. Then, $\Pi_i \circ p = l_i \circ q, i = 1, 2$ and we have the diagram

$$\begin{array}{ccc}
(V \times M) \times (V \times M) & \xleftarrow{p} & E \xrightarrow{q} G \times V \times M \\
\Pi \times \Pi & \downarrow & \Pi' \downarrow \text{id} \times \Pi \\
SV \times SV & \xleftarrow{p'} & E' \xrightarrow{q'} G \times SV \\
\downarrow q'_i & & \downarrow \\
G & & \\
\end{array}$$

Given $\tilde{h} \in \overline{G}$, we let $h$ be the part in $G$, that is, $h(x) = \tilde{h}(x) - \tilde{h}(0)$. The group $\overline{G} \times \overline{G}$ acts on $V \times M \times V \times M, E$, and $G \times V \times M$ as follows:

$$(\tilde{h}, \tilde{k}) \cdot (g, x_1, p_1, x_2, p_2, x_3, p_3) := (hgk^{-1}, \tilde{h}x_1, hp_1, \tilde{k}x_2, kp_2, \tilde{h}x_3, hp_3),$$

$$(\tilde{h}, \tilde{k}) \cdot (x_1, p_1, x_2, p_2) := (\tilde{h}x_1, hp_1, \tilde{k}x_2, kp_2),$$

$$(\tilde{h}, \tilde{k}) \cdot (g, x_3, p_3) := (hgk^{-1}, \tilde{h}x_3, hp_3).$$
The actions on $SV \times SV$, $E'$, and $G \times SV$ are defined analogously. Then the maps in the above diagram are $\tilde{G} \times \tilde{G}$-equivariant.

Using Lemma 2.4 we obtain that $p_*q^*(dg \wedge \omega)$ is a $\tilde{G} \times \tilde{G}$-invariant form, i.e., an element of $\Omega^*(V \times M)^{\tilde{G}} \times \Omega^*(V \times M)^{\tilde{G}}$. The component of bidegree $(m, m)$ can be written as $\sum_{k,l} c_{k,l} \omega_k \wedge \omega_l$.

The normal cycle $K + gL$ is given by

$$nc(K + gL) = q_* \left[ (q'_1)^{-1}(g) \cap (p')^*(nc(K) \times nc(L)) \right].$$

Applying the pull-back $\Pi^*$, Lemma 2.4 yields

$$\Pi^* nc(K + gL) = \Pi^*(q'_1)_* \left[ (q'_1)^{-1}(g) \cap (p')^*(nc(K) \times nc(L)) \right]$$

$$= q_*(\Pi')^* \left[ (q'_1)^{-1}(g) \cap (p')^*(nc(K) \times nc(L)) \right]$$

$$= q_* \left[ q_1^{-1}(g) \cap (\Pi')^*(p')^*(nc(K) \times nc(L)) \right]$$

$$= q_* \left[ q_1^{-1}(g) \cap p^*(\Pi^* nc(K) \times \Pi^* nc(L)) \right].$$

We set $F := p^{-1}(\Pi^{-1} nc(K) \times \Pi^{-1} nc(L)) \subset E$.

Using the previous computation and Lemmas 2.2 and 2.3 (applied to $(q_1)|_F : F \to G$) we deduce that

$$\int_G \int_{nc(K+gL)} \Pi_*(\varphi \cdot (g^{-1})^* \psi \cdot \tau) dg = \int_G \int_{\Pi^{-1} nc(K+gL)} \varphi \cdot (g^{-1})^* \psi \cdot \tau dg$$

$$= \int_G \int_{q_1^{-1}(g) \cap F} q^*(\varphi \cdot (g^{-1})^* \psi) \tau dg$$

$$= \int_{F} q^*(\varphi \cdot (g^{-1})^* \psi \wedge \tau) \wedge dg$$

$$= \int_{\Pi^{-1}(nc(K)) \times \Pi^{-1}(nc(L))} p_* \left[ q^*(\varphi \cdot (g^{-1})^* \psi \cdot \tau) \wedge dg \right]$$

$$= \int_{\Pi^{-1}(nc(K)) \times \Pi^{-1}(nc(L))} p_* \left[ q^* l_1^* \varphi \cdot q^* l_2^* \psi \cdot q^* \tau \wedge dg \right]$$

$$= \int_{\Pi^{-1}(nc(K)) \times \Pi^{-1}(nc(L))} p_* \left[ p^* \Pi_1^* \varphi \cdot p^* \Pi_2^* \psi \cdot q^* \tau \wedge dg \right]$$

$$= \int_{\Pi^{-1}(nc(K)) \times \Pi^{-1}(nc(L))} \Pi_1^* \varphi \cdot \Pi_2^* \psi \cdot \left( \sum_{k,l} c_{k,l} \tau_k \wedge \tau_l \right)$$

$$= \sum_{k,l} c_{k,l} \int_{\Pi^{-1}(nc(K))} \varphi \tau_k \int_{\Pi^{-1}(nc(L))} \psi \tau_l$$
Additive kinematic formulas

\[ = \sum_{k,l} c_{k,l} \int_{nc(K)} \Pi_\ast(\varphi \tau_k) \int_{nc(L)} \Pi_\ast(\psi \tau_l). \]

The general case of not necessarily smooth convex bodies follows by approximation as in [41].

3 Dual flag area measures

In this section we introduce the notion of smooth dual flag area measure, which generalizes the notion of smooth dual area measure from [8]. Similarly to the case of dual area measures, we define a convolution product on the space of smooth dual area measures.

The space \( \Omega^n(V \times M)^{tr} \) of translation invariant forms is endowed with the usual Fréchet topology of uniform convergence on compact subsets of all partial derivatives and there is a surjection \( \Omega^n(V \times M)^{tr} \rightarrow \text{Area}_{G/H} \). We endow the latter space with the quotient topology and denote by \( \text{Area}^\ast_{G/H} \) the dual space to \( \text{Area}_{G/H} \).

Analogously to the case of area measures, we define a convolution product on a subspace of \( \Omega^2(V \times M)^{tr} \).

First, we introduce an operator on the space of differential forms on \( V \times M \) which will play the analogous role, and is defined analogously, to \( *_1 \) from [9] and [8]. We denote this operator again by \( *_1 \).

**Definition 3.1** The linear operator

\[ *_1 : \Omega^\ast(V \times M)^{tr} \rightarrow \Omega^\ast(V \times M)^{tr} \]

is given by

\[ *_1(\pi_1^\ast \tau_1 \wedge \pi_2^\ast \tau_2) = (-1)^{(n-k)\binom{n-k}{2}} \pi_1^\ast(*_1 \tau_1) \wedge \pi_2^\ast \tau_2, \]

where \( \tau_1 \in \bigwedge^k V, \tau_2 \in \Omega^\ast(M) \) and \( * : \bigwedge^k V \rightarrow \bigwedge^{n-k} V \) denotes the Hodge star operator (normalized in the usual way such that \( \tau \wedge *\tau = \|\tau\|^2 \text{vol}_V \)). Here \( \pi_1 : V \times M \rightarrow V \) and \( \pi_2 : V \times M \rightarrow M \) denote the natural projections.

**Lemma 3.2** The space

\[ \mathcal{J}^{n,tr} = \mathcal{J}^{n,tr}(V \times M) \]

\[ := \{ \tau \in \Omega^n(V \times M)^{tr} : \tau \in \mathcal{J}^{n,1}, \Pi^\ast \alpha \wedge \tau = 0, \Pi^\ast d\alpha \wedge \tau = 0 \} \]

is closed under the operation

\[ \tau \ast \tau' := *_1^{-1}(_1 \tau \wedge *_1 \tau'). \]
Proof Since \( *_1 \) does not affect the fiber of \( \Pi \), we have \( \tau \in \tilde{\mathfrak{g}}^{*,j} \) if and only if \( *_1 \tau \in \tilde{\mathfrak{g}}^{*,j} \). Moreover, if \( p_i \in \tilde{\mathfrak{g}}^{*,j_i} \), \( i = 1, 2 \), then \( \rho_1 \wedge \rho_2 \in \tilde{\mathfrak{g}}^{*,j_1+j_2-1} \). Hence, if \( \tau, \tau' \in \tilde{\mathfrak{g}}^{n,1} \), we have \( \tau \wedge \tau' \in \tilde{\mathfrak{g}}^{n,1} \).

The other two conditions can be proved as for the case of dual area measures (see [8]). \( \square \)

Definition 3.3 Let \( \tau \in \Omega^{2n-1+r} (V \times M)^{tr} \). Then \( (\pi_1)_\ast \tau \in \Omega^n (V)^{tr} \) is a multiple of the Lebesgue measure. We denote this multiple by \( \int \tau \).

Lemma 3.4 Let \( \mathcal{K} \subset \Omega^{n-1+r} (V \times M)^{tr} \) be the kernel from Prop. 2.8. The pairing

\[
J^{n,tr} \times \Omega^{n-1+r} (V \times M)^{tr} / \mathcal{K} \to \mathbb{R}, \quad (\tau, [\omega]) \mapsto \int \tau \wedge \omega
\]  

is well-defined and non-degenerate.

Proof We start with a simple fact from linear algebra. Let \( A, B \) be finite-dimensional vector spaces and \( \Phi : A \times B \to \mathbb{R} \) a non-degenerate pairing. Let \( K \subset B \) be a subspace and set

\[
A_K := \{ a \in A : \Phi(a, k) = 0 \quad \forall k \in K \}.
\]

Then the induced pairing

\[
A_K \times B/K \to \mathbb{R}, \quad (a, b + K) \mapsto \Phi(a, b)
\]

is well-defined and non-generate. Indeed, let \( L := \{ b \in B : \Phi(a, b) = 0 \quad \forall a \in A_K \} \). Obviously \( K \subset L \). Since \( \Phi \) is non-degenerate, we have \( \dim L = \dim B - \dim A_K = \dim A - (\dim A - \dim K) = \dim K \), hence \( K = L \).

Let \( A \) be the vector bundle over \( M \) whose fiber over a point \( gH \) is given by

\[
A_{gH} := \bigoplus_k \wedge^k T^*_g H M \otimes \wedge^{n-k} V^*.
\]

The smooth sections of \( A \) are the translation invariant \( n \)-forms on \( V \times M \). Let \( B \) be the vector bundle over \( M \) whose fiber over a point \( gH \) is given by

\[
B_{gH} := \bigoplus_l \wedge^l T^*_g H M \otimes \wedge^{n-1+r-l} V^*.
\]

The smooth sections of \( B \) are the translation invariant \( (n - 1 + r) \)-forms on \( V \times M \).

The natural pairing \( A_{gH} \times B_{gH} \to \wedge^{n-1+r} T^*_g H M \otimes \wedge^n V^* \cong \mathbb{R} \) between these spaces is obviously non-degenerate. Let \( \mathcal{K}_{gH} \subset B_{gH} \) be the subspace generated by \( \Pi^\ast \alpha, \Pi^\ast d\alpha \) and \( \mathfrak{s}^{n-1+r,r}_{x,gH} \) and \( A_{K,gH} \subset A_{gH} \) the annihilator of \( \mathcal{K}_{gH} \).

Varying \( gH \), we obtain a finite rank vector bundle \( A_K \to M \) whose smooth sections can be identified with \( J^{n,tr} \). From the linear algebra fact above it follows that the pairing (5) is non-degenerate in the fiber over each \( gH \in M \), which implies that it is non-degenerate. \( \square \)

Definition 3.5 A dual flag area measure \( L \in \text{Area}^{*}_G/H \) is called smooth if there exists \( \tau \in J^{n,tr} \) such that

\[
\langle L, \Phi \rangle = \int \tau \wedge \omega,
\]  

\( \odot \) Springer
whenever \( \omega \in \Omega^{n-1+r}(V \times M)^{tr} \) represents \( \Phi \in \text{Area}_{G/H} \). The space of smooth dual flag area measures is denoted by \( \text{Area}^{*,sm}_{G/H} \).

**Lemma 3.6** Let \( H_1 \subset H_2 \subset G \) be subgroups and \( \hat{\Pi} : V \times G/H_1 \to V \times G/H_2 \) the projection map. Let \( L \in \text{Area}^{*,G*}_{G/H_2} \) be represented by the form \( \tau \in \mathcal{J}^{n,ir}(V \times G/H_2) \). Then \( \text{glob}^* L \in \text{Area}^{*,G*}_{G/H_1} \) is represented by \( \hat{\Pi}^* \tau \in \mathcal{J}^{n,ir}(V \times G/H_1) \). In particular, \( \text{glob}^* \) is injective.

**Proof** By Lemma 2.7 and Definition 2.1, we have

\[
\langle \text{glob}^* L, \Phi \rangle = \langle L, \text{glob} \Phi \rangle = \int \tau \wedge \hat{\Pi}^* \hat{\omega} = \int \hat{\Pi}^* \tau \wedge \hat{\omega}.
\]

The group \( G \) acts on \( \text{Area}^{*,sm}_{G/H} \) in the natural way. The subspace of \( G \)-invariant elements is denoted by \( \text{Area}^{G*}_{G/H} \). The notation is justified by the following proposition.

**Proposition 3.7** Let \( G \) be transitive. Then

\[
\text{Area}^{G*}_{G/H} \cong \left( \text{Area}^{G}_{G/H} \right)^* ,
\]

in particular \( \dim \text{Area}^{G*}_{G/H} \) is finite-dimensional.

**Proof** By Lemma 3.4, the pairing

\[
(\bullet, \bullet) : \text{Area}^{*,sm}_{G/H} \times \text{Area}_{G/H} \to \mathbb{R}
\]

is non-degenerate. By averaging with respect to the Haar measure on \( G \), we obtain that the restriction

\[
(\bullet, \bullet) : \text{Area}^{G*}_{G/H} \times \text{Area}^{G}_{G/H} \to \mathbb{R}
\]

is non-degenerate. Since the second factor is finite-dimensional, the statement follows.

**Definition 3.8** Let \( L_1, L_2 \in \text{Area}^{*,sm}_{G/H} \) be represented by forms \( \tau_1, \tau_2 \in \mathcal{J}^{n,ir} \). Then we define \( L_1 \ast L_2 \in \text{Area}^{*,sm}_{G/H} \) as the smooth dual area measure represented by \( \tau_1 \ast \tau_2 = \ast^{-1}_1 (\ast_1 \tau_1 \wedge \ast_1 \tau_2) \in \mathcal{J}^{n,ir} \).

**Theorem 3.9** Let \( G \subset O(n) \) be a closed subgroup acting transitively on the unit sphere and \( H \subset G \cap O(n-1) \) be a closed subgroup. Then the following diagram commutes

\[
\begin{array}{ccc}
\text{Area}^{*,sm}_{G/H} \otimes \text{Area}^{*,sm}_{G/H} & \longrightarrow & \text{Area}^{*,sm}_{G/H} \\
q_G \otimes q_G & & q_G \\
\text{Area}^{G*}_{G/H} \otimes \text{Area}^{G*}_{G/H} & \longrightarrow & \text{Area}^{G*}_{G/H} \\
A^* & & \\
\end{array}
\]

\( \odot \) Springer
Here $q_G$ is the map transposed to the inclusion $\text{Area}^G_{G/H} \hookrightarrow \text{Area}^G_{G/H}$.

We need some preparation before proving the theorem.

**Proposition 3.10** Let $G$ be as in the theorem and let $(\Gamma, \rho)$ be a finite-dimensional $G$-module. The group $G$ acts on $\text{Val} \otimes \Gamma$ by $(g \mu)(K) := \rho(g)\mu(g^{-1}K)$. Then the space $(\text{Val} \otimes \Gamma)^G$ is finite-dimensional and contained in $(\text{Val}^{sm} \otimes \Gamma)^G$.

**Proof** Let $\mu \in (\text{Val} \otimes \Gamma)^G$. By Alesker’s irreducibility theorem [2] we may approximate $\mu$ by a sequence $\mu_i \in \text{Val}^{sm} \otimes \Gamma$. Averaging with respect to Haar measure on $G$ we find an approximating sequence $\tilde{\mu}_i \in (\text{Val}^{sm} \otimes \Gamma)^G$. But the latter space is finite-dimensional, since it is a quotient of the space of translation- and $G$-invariant, $\Gamma$-valued smooth differential forms, which is obviously finite-dimensional. It follows that $\mu$ belongs to $(\text{Val}^{sm} \otimes \Gamma)^G$. \hfill \Box

**Proposition 3.11** (Kinematic formulas for tensor valuations) Let $(\Gamma_i, \rho_i)$ be finite-dimensional $G$-modules. If $\mu_1, \ldots, \mu_k$ is a basis of $(\text{Val} \otimes \Gamma_1)^G$ and $\phi_1, \ldots, \phi_l$ is a basis of $(\text{Val} \otimes \Gamma_2)^G$, then for every $\tau \in (\text{Val} \otimes \Gamma_1 \otimes \Gamma_2)^G$ there are constants $c_{ij}^\tau$ such that

$$\int_G (\text{id} \otimes \rho_2(g^{-1}))\tau(K + gL)dg = \sum_{i,j} c_{ij}^\tau \mu_i(K) \otimes \phi_j(L).$$

We thus obtain a cocommutative coassociative coproduct

$$a^{\Gamma_1, \Gamma_2} : (\text{Val} \otimes \Gamma_1 \otimes \Gamma_2)^G \rightarrow (\text{Val} \otimes \Gamma_1)^G \otimes (\text{Val} \otimes \Gamma_2)^G.$$

**Proof** This follows from the usual Hadwiger argument, compare [13, Sect. 3.2] for a similar situation. \hfill \Box

**Definition 3.12** Let $(\Gamma_1, \rho_1), (\Gamma_2, \rho_2)$ be finite-dimensional $G$-modules. We define the convolution $c : (\text{Val} \otimes \Gamma_1)^G \otimes (\text{Val} \otimes \Gamma_2)^G \rightarrow (\text{Val} \otimes \Gamma_1 \otimes \Gamma_2)^G$ componentwise, i.e., $(\mu_1 \otimes f_1) \ast (\mu_2 \otimes f_2) := (\mu_1 \ast \mu_2) \otimes f_1 \otimes f_2$.

**Proposition 3.13** Let $(\Gamma, \rho)$ be a finite-dimensional $G$-module. The bilinear map

$$c : (\text{Val}_k \otimes \Gamma)^G \otimes (\text{Val}_{n-k} \otimes \Gamma^*)^G \rightarrow (\text{Val}_0 \otimes \Gamma \otimes \Gamma^*)^G \cong \text{Val}_0^G \cong \mathbb{R}$$

gives rise to an isomorphism $\hat{pd} : (\text{Val}_k \otimes \Gamma)^G \rightarrow (\text{Val}_{n-k}^* \otimes \Gamma)^G$, which is called Poincaré duality.

**Proof** The proof is a straightforward generalization of [41, Lemma 4.5]. \hfill \Box

We remark that there is another version of Poincaré duality which uses the Alesker product instead of the convolution. Following [41] we put a hat to distinguish between the two dualities.
**Proposition 3.14** Let $(\Gamma_1, \rho_1), (\Gamma_2, \rho_2)$ be finite-dimensional $G$-modules. Then the following diagram commutes

$$
\begin{array}{ccc}
(\text{Val} \otimes \Gamma_1 \otimes \Gamma_2)^G & \xrightarrow{a_{\Gamma_1, \Gamma_2}} & (\text{Val} \otimes \Gamma_1)^G \otimes (\text{Val} \otimes \Gamma_2)^G \\
\hat{\text{val}} & & \hat{\text{val}} \circ \hat{\text{pd}}
\end{array}
$$

Proof The proof is analogous to [41, Theorem 4.6].

**Definition 3.15** Let $\Gamma \subset C^\infty(G)$ be a finite-dimensional $G$-submodule. The map $M^\Gamma : \text{Area}_{G/\{1\}}^{G*} \rightarrow (\text{Val} \otimes \Gamma)^G$ such that

$$
\langle M^\Gamma \Phi(K), f \rangle = \Phi(K, f), \quad \Phi \in \text{Area}_{G/\{1\}}^{G*}, f \in \Gamma,
$$

is called *moment map*.

In the particular case $\Gamma = \text{Sym}^f V$, the moment map was already used in [41] and [8].

**Lemma 3.16** (i)

$$
\bigcap_{\Gamma} \ker M^\Gamma = \{0\},
$$

where the intersection is over all finite-dimensional subrepresentations of $C^\infty(G)$.

(ii) The linear span of the images of $(M^\Gamma)^* : (\text{Val}^* \otimes \Gamma)^G \rightarrow \text{Area}_{G/\{1\}}^{G*}$, where $\Gamma$ ranges over all finite-dimensional subrepresentations of $C^\infty(G)$, equals $\text{Area}_{G/\{1\}}^{G*}$.

Proof (i) Suppose that $M^\Gamma \Phi = 0$ for all $\Gamma$. This means that $\Phi(K, f) = 0$ for all $f \in \Gamma$ and all $\Gamma$. Since $\bigoplus_{\Gamma} \Gamma$ is a dense subspace of $C^\infty(G)$ by the theorem of Peter-Weyl [19], this implies that $\Phi(K, f) = 0$ for every $f \in C^\infty(G)$, hence $\Phi = 0$.

(ii) Let $\mathcal{H} \subset \text{Area}_{G/\{1\}}^{G*}$ be the linear span of the images of $(M^\Gamma)^*$. If $\mathcal{H} \neq \text{Area}_{G/\{1\}}^{G*}$, then we find some $0 \neq \Phi \in \text{Area}_{G/\{1\}}^{G*}$ with $\langle L, \Phi \rangle = 0$ for all $L \in \mathcal{H}$. But this implies that $\langle \mu, M^\Gamma \Phi \rangle = 0$ for all $\mu \in (\text{Val}^* \otimes \Gamma)^G$. By Poincaré duality, this means that $M^\Gamma \Phi = 0$ for all $\Gamma$, hence $\Phi = 0$ by (i). This is a contradiction. Hence $\mathcal{H} = \text{Area}_{G/\{1\}}^{G*}$.

Let $D : \Omega^{n-1}(SV) \rightarrow \Omega^n(SV)$ denote the Rumin operator [34].

**Lemma 3.17** Let $\Gamma \subset C^\infty(G)$ be a finite-dimensional $G$-submodule. If $\mu \in (\text{Val}_{n-k} \otimes \Gamma)^G$ is represented by $\eta = \sum_i \eta_i \otimes f_i$, $\eta_i \in \Omega^{n-1}(SV)^\text{tr}$, $f_i \in \Gamma$, then $(\hat{\text{pd}} \circ M^\Gamma)^* \mu \in \text{Area}_{G/\{1\}}^{G*}$ is represented by

$$
(-1)^k \sum_i f_i \Pi^* D \eta_i \in \Omega^n(M).
$$
Proof Let $\Phi \in \text{Area}_{G/\{1\}}^G$ be given by a form $\omega \in \Omega^m(V \times M)$ of bidegree $(k, m-k)$. Using [41, Proposition 4.2] we find

$$\langle (\hat{\rho} \circ M^\Gamma)^* \mu, \Phi \rangle = \langle \hat{\rho} \circ M^\Gamma \Phi, \mu \rangle = (-1)^k \sum_i \int D \eta_i \wedge \Pi_*(f_i \omega) = (-1)^k \sum_i f_i \Pi^* D \eta_i \wedge \omega.$$ 

\[ \square \]

Lemma 3.18 The additive kinematic formulas are compatible in the following sense. Let $\Gamma_1, \Gamma_2 \subset C^\infty(G)$ be finite-dimensional submodules and let $\Gamma_1 \cdot \Gamma_2$ be the (finite-dimensional) module generated by all $f_1 \cdot f_2$, $f_1 \in \Gamma_1$, $f_2 \in \Gamma_2$. Let $q : \Gamma_1 \otimes \Gamma_2 \to \Gamma_1 \cdot \Gamma_2$, $f_1 \otimes f_2 \mapsto f_1 \cdot f_2$ be the natural projection. Then the following diagram commutes

\[
\begin{array}{ccc}
\text{Area}_{G/\{1\}}^G & \xrightarrow{A} & \text{Area}_{G/\{1\}}^G \otimes \text{Area}_{G/\{1\}}^G \\
\downarrow M^{\Gamma_1 \cdot \Gamma_2} & & \downarrow M^{\Gamma_1} \otimes M^{\Gamma_2} \\
(\text{Val} \otimes (\Gamma_1 \cdot \Gamma_2)^*)^G & \xrightarrow{id \otimes q^*} & (\text{Val} \otimes \Gamma_1^*)^G \otimes (\text{Val} \otimes \Gamma_2^*)^G \\
\end{array}
\]

Proof Let $f_i \in \Gamma_i$, $i = 1, 2$. We compute

$$\left\langle \left[ a^{\Gamma_1, \Gamma_2} \circ (id \otimes q^*) \circ M^{\Gamma_1 \cdot \Gamma_2} \Phi \right](K, L), f_1 \otimes f_2 \right\rangle$$

$$= \int_G \langle (id \otimes \rho_2^*(g^{-1})) (q^* M^{\Gamma_1 \cdot \Gamma_2} \Phi(K + gL)), f_1 \otimes f_2 \rangle dg$$

$$= \int_G \langle M^{\Gamma_1 \cdot \Gamma_2} \Phi(K + gL), f_1 \cdot (g^{-1})^* f_2 \rangle dg$$

$$= \int_G \Phi(K + gL, f_1 \cdot (g^{-1})^* f_2) dg$$

$$= A(\Phi)(K, L, f_1, f_2)$$

$$= \langle (M^{\Gamma_1} \otimes M^{\Gamma_2}) \circ A(\Phi)(K, L), f_1 \otimes f_2 \rangle.$$

\[ \square \]

Proof of Theorem 3.9 We look first at rotation measures.

Let $\Gamma_1, \Gamma_2 \subset C^\infty(G)$ be two finite-dimensional $G$-submodules. Dualizing the above diagram yields the commutative diagram

\[ \square \]
Let $\mu_a \in (\text{Val}_{a-k_a} \otimes \Gamma_a)$ be represented by $\eta_a = \sum_i \eta_i^a \otimes f_i^a$ of bidegree $(n-k_a, k_a-1)$. Then $\mu_1 * \mu_2$ is represented by some $\eta \in \Omega^{n-1}(SV) \otimes \Gamma_1 \otimes \Gamma_2$ such that $D \eta = \sum_{i,j} (\star_1 D \eta_i^1 \wedge \star_1 D \eta_j^2) \otimes f_i^1 \otimes f_j^2$, which has bidegree $(n-k_1-k_2, k_1+k_2-1)$. It follows that

$$(-1)^{k_1+k_2} \Pi^*(D \eta) = \star_1 (\star_1 (-1)^{k_1} \Pi^* D \eta_1^1 \wedge \star_1 (-1)^{k_2} \Pi^* D \eta_2^2).$$

This means that if $L_1 \in \text{Area}_{G_{/H}}^\ast$ is in the image of $(\hat{\pi} \circ M_{\Gamma_1})^*$ and $L_2$ is in the image of $(\hat{\pi} \circ M_{\Gamma_2})^*$, then the formula to compute $L_1 * L_2$ is correct. Thus, by Lemma 3.16 the formula holds for all $L_1, L_2 \in \text{Area}_{G_{/H}}^\ast$.

In the general case, we have a commutative diagram

$$\begin{array}{ccc}
\text{Area}_{G_{/H}}^\ast & \xrightarrow{A} & \text{Area}_{G_{/H}}^\ast \otimes \text{Area}_{G_{/H}}^\ast \\
glob & & \downarrow \text{glob} \\
\text{Area}_{G_{/H}}^\ast & \xrightarrow{A} & \text{Area}_{G_{/H}}^\ast \otimes \text{Area}_{G_{/H}}^\ast
\end{array}$$

which gives us, by dualizing, a commutative diagram

$$\begin{array}{ccc}
\text{Area}_{G_{/H}}^\ast & \xleftarrow{\ast} & \text{Area}_{G_{/H}}^\ast \otimes \text{Area}_{G_{/H}}^\ast \\
glob^* & & \uparrow \text{glob}^* \\
\text{Area}_{G_{/H}}^\ast & \xleftarrow{\ast} & \text{Area}_{G_{/H}}^\ast \otimes \text{Area}_{G_{/H}}^\ast
\end{array}$$

Since glob$^*$ is injective, the statement follows from Lemma 3.6 and the fact that $\hat{\Pi}^*$ commutes with $\ast_1$. 

\section{Rotation measures}

In this section we consider rotation measures, i.e., the case $G := \text{SO}(n), H := \{1\}$ and prove Theorems 2 and 3.

\subsection{Classification of rotation measures}

\textbf{Proof of Theorem 2} In the first part of the proof, we follow [1, Sect. 3].
The Lie algebras of \( G, \bar{G} \) will be denoted by \( \mathfrak{g}, \mathfrak{g} \). The dimension of the fiber of \( \Pi : V \times G \to SV \) is given by \( r := \binom{n-1}{2} \). As above we set \( m := n - 1 + r \). By definition, a smooth flag area measure \( \Phi \in \text{Area}^k_{\text{SO}(n)/[1]} \) of degree \( k \) is represented by a translation invariant differential form \( \eta \in \Omega^{k,m-k}(V \times G) \). Since \( \Phi \) is \( G \)-invariant, we may assume by averaging over \( G \) that \( \eta \) is \( G \)-invariant, i.e., \( \eta \in \Omega^m(\bar{G}) \).

Let \( \sigma_i, i = 1, \ldots, n, \omega_{ij}, 1 \leq i \leq j \leq n \) denote the components of the Maurer-Cartan form of \( \bar{G} \). Then \( \sigma_i, 1 \leq i \leq n, \omega_{ij}, 1 \leq i < j \leq n \) span \( \mathfrak{g}^* \). We let \( X_i, 1 \leq i \leq n, X_{ij}, 1 \leq i < j \leq n \) denote the dual basis of \( \mathfrak{g} \). We let \( V_0 \) be the span of \( X_1 \); \( V_\sigma \) the span of \( X_i, 2 \leq i \leq n \); \( V_\omega \) be the span of the \( X_{1j}, 2 \leq j \leq n \); and \( U \) the span of the \( X_{ij}, 2 \leq i < j \leq n \). Schematically, the Lie algebra looks as follows:

\[
\tilde{\mathfrak{g}} = \begin{pmatrix} 0 & V_0 & 0 \\ V_\sigma & V_\omega & U \end{pmatrix}.
\]

Since \( \Pi^*\alpha = \sigma_1 \), the quotient of the space of \( \bar{G} \)-invariant forms of bidegree \((k, m-k)\) by multiples of \( \Pi^*\alpha \) is the space

\[
\Lambda^{k,m-k}(V_\sigma^* \oplus V_\omega^* \oplus U^*) \cong \Lambda^k V_\sigma^* \otimes \Lambda^{m-k}(V_\omega^* \oplus U^*) \\
\cong \Lambda^k V_\sigma^* \otimes \bigoplus_{i=0}^{m-k} \Lambda^{m-k-i} V_\omega^* \otimes \Lambda^i U^*.
\]

If \( \eta \) belongs to the sum of terms with \( i < \dim U^* = r \), then \( \eta \in \mathfrak{z}^{m,r} \) and hence induces the trivial flag area measure. We thus obtain that

\[
\Omega^{k,m-k}(\bar{G}) / \langle \Pi^*\alpha, \mathfrak{z}^{m,r} \rangle \cong \Lambda^k V_\sigma^* \otimes \Lambda^{n-1-k} V_\omega^*.
\]

Next, by Proposition 2.8, we have to factor out multiples of \( \Pi^*d\alpha \). By [30, Proposition 1.2.30], the multiplication map by \( d\alpha \) induces an injection

\[
\Lambda^{k-1} V_\sigma^* \otimes \Lambda^{n-2-k} V_\omega^* \hookrightarrow \Lambda^k V_\sigma^* \otimes \Lambda^{n-1-k} V_\omega^*
\]

is injective. Hence

\[
\text{Area}^k_{\text{SO}(n)/[1]} \cong \Omega^{k,m-k}(\bar{G}) / \langle \Pi^*\alpha, \Pi^*d\alpha, \mathfrak{z}^{m,r} \rangle \\
\cong (\Lambda^k V_\sigma^* \otimes \Lambda^{n-1-k} V_\omega^*) / (\Lambda^{k-1} V_\sigma^* \otimes \Lambda^{n-2-k} V_\omega^*).
\]

In particular,

\[
\dim \text{Area}^k_{\text{SO}(n)/[1]} = \binom{n-1}{k}^2 - \binom{n-1}{k-1}(n-1) = \frac{1}{n} \binom{n}{k} \binom{n}{k+1}.
\]

We now construct the rotation measures \( S_{I,J} \). Uniqueness follows from the fact that smooth convex bodies are dense in the space of all compact convex bodies. Let us prove
existence. Let \( I = (i_1, \ldots, i_k) \), \( J = (j_1, \ldots, j_k) \) and set \( I^c = \{2, \ldots, n\} \setminus I \), ordered in such a way that \( \text{sgn}(2, \ldots, n) = \text{sgn}(i_1, \ldots, i_k, i_1^c, \ldots, i_{n-k-1}^c) \) and similar for \( J^c \).

Define \( S_{I,J} \) by the differential form

\[
\omega_{I,J} := \sigma_1 \wedge \cdots \wedge \sigma_k \wedge \omega_{j_1} \wedge \cdots \wedge \omega_{j_{n-k-1}} \wedge \rho \in \Omega^{k,m-k}(V \times \text{SO}(n)),
\]

where \( \rho \) is the volume form of the fiber of the map \( \text{SO}(n) \to S^{n-1} \), \( g \mapsto ge_1 \).

Let \( K \) be a smooth compact convex body with outer unit normal \( v : \partial K \to S^{n-1} \). Fix \( x \in \partial K \) and \( g \in \text{SO}(n) \) with \( ge_1 = v(x) \). Then \( ge_2, \ldots, ge_n \) form a positive orthonormal basis of \( T_x \partial K \). The vectors \( \omega_l := (ge_l, S_x(ge_l)) \in T_x \partial K \times T_x \partial K, l = 2, \ldots, n \) span \( T_{(x,v(x))} \text{nc}(K) \). Let \( \hat{w}_l \in T_{(x,g)}(V \times \text{SO}(n)) \) be any lift of \( w_l \), where \( g \) is in the fibre over \( v(x) \).

We have for \( 2 \leq i, j \leq n \)

\[
\sigma_i(\hat{w}_l) = \delta_{il}, \quad \omega_{J,j}(\hat{w}_l) = (ge_j, S(ge_l)).
\]

With \( \Sigma_k \) denoting the permutation group of \( k \) elements, we thus have

\[
\omega_{I,J}(\hat{w}_2, \ldots, \hat{w}_n, -) = \omega_{I,J}(\hat{w}_{i_1}, \ldots, \hat{w}_{i_k}, \hat{w}_{j_1}, \ldots, \hat{w}_{j_{n-k-1}}, -) = \sum_{\pi \in \Sigma_{n-k-1}} \text{sgn}(\pi)(ge_{\pi_1}^1, S(ge_{\pi_1}^1)) \cdots (ge_{\pi_{n-k-1}}^k, S(ge_{\pi_{n-k-1}}^k)) \cdot \rho
\]

\[
= \det(\pi_{J_{\perp}} \circ S_{x} |_{V_I^J} : V_I^J \to V_J^J) \cdot \rho,
\]

from which (1) follows.

By the definition of rotation measures (see Definition 3.5) and by Proposition 2.8, every rotation measure is a linear combination of the \( S_{I,J} \). The relations (2) and the last part of the statement are an immediate consequence of Proposition 2.8, since multiples of \( \Pi^*d\alpha \) induce the trivial rotation measure. \( \square \)

### 4.2 Dual rotation measures

Let us now study more carefully the space of dual rotation measures. By Definition 3.5, an element of \( \text{Area}_{\text{SO}(n)[1], k}^{\text{SO}(n)*} \) is represented by a form \( \tau \in \Omega^{n-k,k}(\tilde{G})^\ast \) such that \( \tau \in \mathfrak{s}^{n,1}, \Pi^*\alpha \wedge \tau = 0, \Pi^*d\alpha \wedge \tau = 0 \).

As above, we have

\[
\Omega^{n-k,k}(\tilde{G})^\ast \cong \Lambda^{n-k,k}(V_0^* \oplus V_\sigma^* \oplus V_\omega^* \oplus U^*)
\]

\[
\cong \bigoplus_{\epsilon=0,1} \Lambda^\epsilon V_0^* \otimes \Lambda^{n-k-\epsilon} V_\sigma^* \otimes \bigoplus_{i=0}^k \Lambda^{k-i} V_\omega^* \otimes \Lambda^i U^*.
\]

The condition \( \Pi^*\alpha \wedge \tau = 0 \) is satisfied for the part with \( \epsilon = 1 \) in this sum, and the condition \( \tau \in \mathfrak{s}^{n,1} \) is equivalent to \( i = 0 \). We are thus left with the space

\[
\Lambda^{n-k-1} V_\sigma^* \otimes \Lambda^k V_\omega^*.
\]
Multiplication by the symplectic form $d\alpha$ gives a surjection

$$L : \Lambda^{n-k-1} V^* \otimes \Lambda^k V^* \to \Lambda^{n-k} V^*_\omega \otimes \Lambda^{k+1} V^*_\omega,$$

and $\text{Area}_{SO(n)/\{1\}, k}$ is isomorphic to the kernel of this map.

Let us rewrite this in more invariant terms. Let $V^C = V^* \otimes \mathbb{C}$ stand for the complexification. The group $\text{SL}(n-1, \mathbb{C})$ acts on the set of bases of $V^C$, $V^C \otimes \mathbb{C}$ from the right in the natural way. If $Y = (Y_2, \ldots, Y_n)$ is a basis of $V^C$ and $g \in \text{SL}(n-1, \mathbb{C})$, then $(Yg)_i := \sum_{j=2}^n Y_j g_{ji}$. The corresponding right operation on $V^*_\omega, V^*_\omega \otimes \mathbb{C}$ is given by

$$g^* \sigma_i = \sum_{j=2}^n (g^{-1})_{ij} \sigma_j, \quad (8)$$

$$g^* \omega_{1i} = \sum_{j=2}^n \omega_{1j} a_{ji}. \quad (9)$$

As $\text{SL}(n-1, \mathbb{C})$-representations, we have $V^C = (V^C)^*$. The symplectic form is the canonic element of $\Lambda^2 (V^*_\omega \oplus (V^C)^*)$. The above map $L$ can then be rewritten as an $\text{SL}(n-1, \mathbb{C})$-equivariant surjection

$$L : \Lambda^{n-k-1} V^C \otimes \Lambda^k (V^C)^* \to \Lambda^{n-k} V^*_\omega \otimes \Lambda^{k+1} (V^C)^*.$$

We may $\text{SL}(n-1, \mathbb{C})$-equivariantly identify

$$\Lambda^{n-k-1} V^C \otimes \Lambda^k (V^C)^* \cong \Lambda^k (V^C)^* \otimes \Lambda^k (V^C)^*,$$

$$\Lambda^{n-k} V^C \otimes \Lambda^{k+1} (V^C)^* \cong \Lambda^{k-1} (V^C)^* \otimes \Lambda^{k+1} (V^C)^*,$$

and with this identification, the map $L : \Lambda^k (V^C)^* \otimes \Lambda^k (V^C)^* \to \Lambda^{k-1} (V^C)^* \otimes \Lambda^{k+1} (V^C)^*$ is given by

$$\tau_1 \wedge \cdots \wedge \tau_k \otimes \rho_1 \wedge \cdots \wedge \rho_k$$

$$\mapsto \sum_{i=1}^k (-1)^i \tau_1 \wedge \cdots \wedge \hat{\tau}_i \wedge \cdots \wedge \tau_k \otimes \rho_1 \wedge \cdots \wedge \rho_k \wedge \tau_i,$$

where $\tau_i, \rho_j \in (V^C)^*$.

Let $\mathcal{L}_k$ be the kernel of this map. It is well-known that $\mathcal{L}_k$ is an irreducible representation of $\text{SL}(n-1, \mathbb{C})$ [22, Exercise 15.30].

Let $\text{SL}(n-1, \mathbb{C})$ act on $X = (x_{ij})_{2 \leq i, j \leq n}$ (from the right) by $(g, X) \mapsto g^t X g$. Consider the algebra morphism defined by

$$\Psi : \mathbb{C}[X] \to \bigoplus_{k=0}^{n-1} \Lambda^k (V^C)^* \otimes \Lambda^k (V^C)^*, x_{ij} \mapsto \frac{1}{2} (\omega_{1i} \otimes \omega_{1j} + \omega_{1j} \otimes \omega_{1i}).$$
The product on the right hand side is given by the wedge products of the two factors. This is a commutative product that will be denoted by $\cdot$. We clearly have $\mathcal{L}_k \cdot \mathcal{L}_l \subset \mathcal{L}_{k+l}$.

$\Psi$ is equivariant by (9), and $\Psi(x_{ij}) \in \mathcal{L}_1$. Hence, $\Psi([X]_k) \subset \mathcal{L}_k$, where $[X]_k$ is the part of degree $k$. Since $\mathcal{L}_k$ is irreducible and the image is not trivial (consider $\Psi(x_{23} \ldots x_{2k,2k+1})$ if $k < n/2$ and $\Psi(x_{23}^2 \ldots)$ otherwise), we get a surjective map $\Psi : \mathbb{C}[X]_k \to \mathcal{L}_k \cong \text{Area}_{SO(n)^*}^{SO(n)^*(n/2)}$. Using Definition 3.8 we get a surjective algebra morphism $\Psi : \mathbb{C}[X] \to \text{Area}_{SO(n)^*}^{SO(n)^*(1)} \otimes \mathbb{C}$.

It is easy to check that $I \subset \ker \Psi$, hence we have a surjective map (denoted by the same letter)

$$\Psi : \mathbb{C}[X]/I \to \text{Area}_{SO(n)^*}^{SO(n)^*(1)} \otimes \mathbb{C}.$$ 

To finish the proof, we will compare the dimensions of both sides. We first need some relations in $\mathbb{C}[X]/I$.

**Lemma 4.1** Modulo $I$, we have the following equations.

(i) A monomial vanishes if some index is repeated three times, i.e., $x_{aa}x_{ab} = 0$, $x_{ab}x_{ab}x_{ab} = 0$ for all $a, b, b_1, b_2, b_3 \in \{2, \ldots, n\}$.

(ii) $\det(x_{ij})_{2 \leq i, j \leq n} = \frac{n!}{2^{n-1}} x_{22} \ldots x_{nn}$.

(iii) The elementary symmetric polynomials $E_i$ satisfy

$$E_i(x_{2,2}, \ldots, x_{n,n})E_j(x_{2,2}, \ldots, x_{n,n}) = \binom{i+j}{i} E_{i+j}(x_{2,2}, \ldots, x_{n,n}).$$

**Proof** (i) Easy exercise.

(ii) We prove this by induction over $n$, the case $n = 2$ being trivial.

Suppose that $n > 2$ and develop the determinant with respect to the last column:

$$\det(x_{ij})_{2 \leq i, j \leq n} = \sum_{l=2}^{n-1} (-1)^{l+n} x_{l,n} \det(x_{ij})_{2 \leq i \leq n, i \neq l} + x_{n,n} \det(x_{ij})_{2 \leq i, j \leq n-1}.$$

Now develop the determinant in the first summand with respect to the last row. We obtain some sum of terms containing the factor $x_{l,n}x_{nj}$, which equals $-\frac{1}{2} x_{n,n}x_{lj}$. We may thus replace the factor $x_{l,n}$ by $-\frac{1}{2} x_{n,n}$, and the last row of $(x_{ij})_{2 \leq i \leq n, i \neq l}^{2 \leq j \leq n-1}$ by $x_{l2}, \ldots, x_{ln-1}$, which is just the row which was deleted. Rearranging the rows (which gives us another sign $(-1)^{n-l+1}$) we find that

$$\det(x_{ij})_{2 \leq i, j \leq n} = \sum_{l=2}^{n-1} (-1)^{l+n} \left(-\frac{1}{2} \right) (-1)^{n-l+1} x_{n,n} \det(x_{ij})_{2 \leq i, j \leq n-1}$$

$$+ x_{n,n} \det(x_{ij})_{2 \leq i, j \leq n-1}$$

$$= \frac{n}{2} x_{n,n} \det(x_{ij})_{2 \leq i, j \leq n-1}.$$
(iii) By definition,
\[ E_i(x_{2,2}, \ldots, x_{n,n}) = \sum_{|I|=i} x_{a_1,a_1} \cdots x_{a_i,a_i}, \]
where \( I = (a_1, \ldots, a_i) \) runs over all ordered subsets of size \( i \) in \( \{2, \ldots, n\} \).
Since \( x_{a,a}^2 = 0 \) for each \( a \), we find that
\[ E_i(x_{2,2}, \ldots, x_{n,n}) E_j(x_{2,2}, \ldots, x_{n,n}) = \sum_{|I|=i, |J|=j} x_{a_1,a_1} \cdots x_{a_i,a_i} x_{b_1,b_1} \cdots x_{b_j,b_j} \]
\[ = \binom{i+j}{i} \sum_{|K|=i+j} x_{c_1,c_1} \cdots x_{c_{i+j},c_{i+j}} \]
\[ = \binom{i+j}{i} E_{i+j}(x_{2,2}, \ldots, x_{n,n}). \]
\[ \square \]

Lemma 4.2 The dimension of the degree \( k \)-part of the algebra
\[ \mathbb{C}[X]/I \]
is at most \( \frac{1}{n} \binom{n}{k} \binom{n}{k+1} \).

Proof Let us fix \( 0 \leq l \leq k \) and count the number of monomials with \( 2l \) indices appearing once and \((k-l)\) indices appearing twice.

There are \( \binom{n-1}{k-l} \) possibilities to choose the \((k-l)\) double indices among \( 1, \ldots, n-1 \).

Replacing \( x_{i_1j_1} x_{i_2j_2} \) by \( -\frac{1}{2} x_{i_1i_2} x_{j_1j_2} \), we may assume that such a double index \( i \) appears in a factor \( x_{ii} \).

From the remaining \((n-k+l-1)\) other indices we choose \( 2l \), which gives us \( \binom{n-k+l-1}{2l} \) possibilities. These \( 2l \) indices \( i_1, \ldots, i_{2l} \) will be put into pairs so that we form the product \( x_{i_1i_2} \cdots x_{i_{2l-1}i_{2l}} \).

However, we can use the relations to rule out some combinations. Arrange the \( 2l \) numbers \( i_1, \ldots, i_{2l} \) in a circle. If a monomial contains a factor \( x_{i_1i_2} x_{i_3i_4} \) such that the lines between \([i_1, i_2]\) and \([i_3, i_4]\) intersect, we may use the relation and replace this factor by \( x_{i_1i_2} x_{i_3i_4} = -x_{i_1i_3} x_{i_2i_4} - x_{i_1i_4} x_{i_2i_3} \). Note that \([i_1, i_3]\) and \([i_4, i_2]\) do not intersect and similarly \([i_1, i_4]\) and \([i_2, i_3]\) do not intersect. Continuing this way we may assume that none of the lines \([i_1, i_2], \ldots, [i_{2l-1}i_{2l}]\) do intersect. Basic combinatorics tells us that the number of such non-intersecting pairings is the Catalan number \( \frac{(2l)!}{(l+1)!l!} \).

Summarizing, we get that the dimension of the degree \( k \)-part of the algebra is bounded from above by
\[ \sum_{l=0}^{k} \binom{n-1}{k-l} \binom{n-k+l-1}{2l} \frac{(2l)!}{l!(l+1)!}. \]

It remains to see that this equals the expression given in the lemma. This can be seen by the following combinatorial argument.
Take a set of \( n \) numbered cards with both sides empty. Choose \( k \) among these cards and color the front side green. Independently of that, color the back side of \((k + 1)\) among the \( n \) cards red. The number of different colorings obtained in this way is \( \binom{n}{k} \binom{n}{k+1} \).

Start again with a set of \( n \) numbered cards with both sides empty and fix a number \( 0 \leq l \leq k \). Choose one of the cards and declare it to be 1-colored (the color will be fixed later). Among the remaining \((n - 1)\) cards, choose \( (k - l) \) and color the front side green and the back side red. Among the remaining \((n - k + l - 1)\) cards, choose \( 2l \) and declare them to be 1-colored. Among the \((2l + 1)\) 1-colored cards, we color \( l \) in green and \((l + 1)\) in red. In this way, we obtain all colorings with precisely \((k - l)\) two-colored cards, such that \( k \) are green and \((k + 1)\) are red. However, each of these colorings is counted \((2l + 1)\) times, since any of the \((2l + 1)\) 1-colored cards can be chosen as the first card to begin with. The total number of colorings is therefore

\[
\sum_{l=0}^{k} \binom{n-1}{k-l} \binom{n-k+l-1}{2l} \frac{1}{2l+1}.
\]

\[\square\]

**End of the proof of Theorem 3** Since \( \Psi : \mathbb{C}[X]/I \to \text{Area}_{SO(n)*}^{\text{SO}(n)/[1]} \otimes \mathbb{C} \) is surjective and the dimension on the left hand side is not larger than the dimension on the right hand side, the map must be a bijection and the upper bound for the dimension from Lemma 4.2 is attained. Obviously, the algebra isomorphism \( \Psi \) induces an algebra isomorphism (denoted by the same letter)

\[\Psi : \mathbb{R}[X]/I \to \text{Area}_{SO(n)*}^{\text{SO}(n)/[1]} .\]

Let us compute the image of \( x_{i,j} \). Note that \( x_{i,j} \) corresponds to the dual rotation measure given by the form \( \tau := *_{1}^{-1} \left( \sigma_{i} \wedge \omega_{j,1} + \sigma_{j} \wedge \omega_{i,1} \right) \). We compute

\[\Psi_{1}^{-1} (\sigma_{i} \wedge \omega_{j,1}) = *^{-1} \sigma_{i} \wedge \omega_{j,1} = (-1)^{n} \sigma_{1} \wedge \sigma_{1}^{c} \wedge \cdots \wedge \sigma_{l-n}^{c} \wedge \omega_{j,1},\]

and hence

\[\Psi_{1}^{-1} (\sigma_{i} \wedge \omega_{j,1}) \wedge \omega_{[i..j]} = (-1)^{n} \sigma_{1} \wedge \sigma_{1}^{c} \wedge \cdots \wedge \sigma_{l-n}^{c} \wedge \omega_{j,1} \wedge \sigma_{i} \wedge \omega_{j,1} \wedge \sigma_{i} \wedge \sigma_{j} \wedge \omega_{j,1} \wedge \sigma_{j} \wedge \omega_{j,1} \wedge \rho \]

\[= - \sigma_{1} \wedge \cdots \wedge \sigma_{n} \wedge \omega_{2,1} \wedge \cdots \wedge \omega_{n,1} \wedge \rho .\]

It follows that

\[\langle \Psi (x_{i,j}), S_{i,i} \rangle = - \text{vol}(\text{SO}(n)),\]

\[\langle \Psi (x_{i,j}), S_{i,j} \rangle = \langle \Psi (x_{i,j}), S_{j,i} \rangle = - \frac{1}{2} \text{vol}(\text{SO}(n)), i \neq j .\]

In both cases, it follows that \( \Psi (x_{ij}) = - \text{vol}(\text{SO}(n)) \cdot \frac{S_{i,j}^{*} + S_{j,i}^{*}}{2} .\)

\[\square\]

**Remark 4.3** In the following, we will identify an element of \( \mathbb{R}[X]/I \) with its image under \( \Psi \) in \( \text{Area}_{SO(n)*}^{\text{SO}(n)/[1]} \).
Corollary 4.4 Let $H \subset SO(n-1)$ be a closed subgroup. Then the image of the transposed globalization map $\text{glob}^* : \text{Area}_{SO(n)}^* \to \text{Area}_{SO(n)}/(1) \cong \mathbb{R}[X]/I$ is the subalgebra of $\mathbb{R}[X]/I$ consisting of all invariants under $H$ with respect to the right action $h^*X = h^tXh$.

**Proof** The statement follows directly by recalling that the inclusion $\text{glob}^*$ preserves the algebra structure of both spaces and is $H$-equivariant. \qed

**Examples** We consider the case of area measures, i.e., $H = SO(n-1)$. By Corollary 4.4, $\text{Area}_{SO(n)}^* := \text{Area}_{SO(n)}/SO(n-1)$ is the subalgebra of $\mathbb{R}[X]/I$ consisting of all invariants under $H$ with respect to the right action $h^*X = h^tXh$, $h \in SO(n-1)$. Since $h^t = h^{-1}$, these invariants contain the elementary symmetric functions of $X$. By Lemma 4.1(ii), they can be written as rescalings of the elementary symmetric functions of the diagonal elements $x_{ii}$, $2 \leq i \leq n$.

The linear map $\Xi : \mathbb{R}[t] \to (\mathbb{R}[X]/I)^H$, $t^i \mapsto i!E_i(x_2,2, \ldots, x_{n,n})$ induces by Lemma 4.1 an injective algebra morphism

$$\Xi : \mathbb{R}[t]/\langle t^n \rangle \to (\mathbb{R}[X]/I)^H = \text{Area}_{SO(n)}^*.$$ 

Since the dimensions on both sides agree, this map is an algebra isomorphism. Hence,

$$\text{Area}_{SO(n)}^* \cong \mathbb{R}[t]/\langle t^n \rangle,$$

which is of course well-known.

The additive kinematic formulas are given by

$$A(S_i) = \frac{1}{\omega_n} \sum_{k+l=i} \binom{i}{k} S_k \otimes S_l,$$

see [13], or Schneider [37, Theorem 4.4.6]. It follows that

$$S_k^* \cdot S_l^* = \frac{1}{\omega_n} \binom{k+l}{k} S_{k+l}^*.$$ 

Clearly $t$ is mapped to some multiple $cS_1^*$. We will see later that $c = \omega_n$. Then $t^k$ is mapped to $\omega_n k!S_k^*$, as can be shown by induction over $k$.

5 Algebraic structure of FlagArea$^{(p),SO(n)}_*$

The aim in this section is to prove Proposition 1.3. Recall first that $\sigma_i$, $\omega_{ij}$ are the coordinates of the Maurer–Cartan form of $SO(n)$. The volume form of the unit sphere is $\omega_2 \wedge \cdots \wedge \omega_n$. We have the structure equations

$$d\sigma_i = -\sum_{j=1}^n \omega_{ij} \wedge \sigma_j, \quad d\omega_{ij} = -\sum_{k=1}^n \omega_{ik} \wedge \omega_{kj}.$$
Unwinding the definitions in Sect. 4, we have

\[ x_{ij} = \frac{1}{2} (\sigma_i \wedge \omega_j + \sigma_j \wedge \omega_i); \]

in particular \( x_{ii} = \sigma_i \wedge \omega_i \).

**Proof of Proposition 1.3** Recall that \( \text{Flag}_{1,p+1} \cong \text{SO}(n)/H \) with \( H = \text{SO}(p) \times \text{O}(q) \). By Corollary 4.4, \( \text{glob}^* \) maps \( \text{FlagArea}^{(p)}_{\text{SO}(n)}, \star \) bijectively to the algebra of \( H \)-invariant elements in \( \mathbb{R}[X]/I \), where the action is given by \( h^*X := h'Xh = h^{-1}Xh \).

Assume first that \( p \neq q \). We claim that the linear map

\[ \mathfrak{E} : \mathbb{R}[x, y] \to (\mathbb{R}[X]/I)^H, \]

which sends \( x^i y^j \) to \( i!E_i(x_{2,2}, \ldots, x_{p+1,p+1}) j!E_j(x_{p+2,p+2}, \ldots, x_{n,n}) \) is an algebra morphism.

It is clear that the image of each monomial is \( H \)-invariant. The compatibility with the product follows from Lemma 4.1.

Obviously, \( x^{p+1}, y^{q+1} \in \ker \mathfrak{E} \), hence there is an induced algebra morphism

\[ \tilde{\mathfrak{E}} : \mathbb{R}[x, y]/\langle x^{p+1}, y^{q+1} \rangle \to (\mathbb{R}[X]/I)^H. \tag{11} \]

We claim that this map is injective. To do so, introduce a bigrading on \( (\mathbb{R}[X]/I)^H \) by declaring that

\[
\deg x_{ab} = \begin{cases} (1, 0) & 2 \leq a, b \leq p + 1 \\ (\frac{1}{2}, \frac{1}{2}) & 2 \leq a \leq p + 1, p + 2 \leq b \leq n \\ (\frac{1}{2}, \frac{1}{2}) & 2 \leq b \leq p + 1, p + 2 \leq a \leq n \\ (0, 1) & p + 2 \leq a, b \leq n. \end{cases}
\]

It is easily checked that the ideal \( I \) is bigraded, so we indeed have a bigrading on the quotient. The image of \( x^i y^j, 0 \leq i \leq p, 0 \leq j \leq q \) is of bidegree \( (i, j) \). To prove injectivity of \( \tilde{\mathfrak{E}} \), it is therefore enough to prove that \( \tilde{\mathfrak{E}}(x^i y^j) \neq 0 \) for \( 0 \leq i \leq p, 0 \leq j \leq q \). But \( \tilde{\mathfrak{E}}(x^i y^j) \) corresponds to the form

\[ i!E_i(\sigma_2 \wedge \omega_2, \ldots, \sigma_{p+1} \wedge \omega_{p+1}) j!E_j(\sigma_{p+2} \wedge \omega_{p+2}, \ldots, \sigma_n \wedge \omega_n), \tag{12} \]

which is obviously non-zero.

To conclude the proof that \( \tilde{\mathfrak{E}} \) is an algebra isomorphism, it is enough to compare dimensions. The dimension of the \( k \)-homogeneous part of the left hand side is the number of monomials \( x^i y^j \) with \( i + j = k, 0 \leq i \leq p, 0 \leq j \leq q \), which is easily computed as \( \min\{p, q, k, n-k-1\} + 1 \). The \( k \)-homogeneous part on the right hand side is isomorphic to \( \text{FlagArea}^{(p)}_{\text{SO}(n)}, \star \), which is isomorphic to \( \left( \text{FlagArea}^{(p)}_{k, \text{SO}(n)} \right)^* \) by Proposition 3.7. By [1, Theorem 4] its dimension is \( \min\{p, q, k, n-k-1\} \).
Let us now consider the case $p = q$. The above proof goes through word by word, except that $\dim \text{FlagArea}_{k}^{(p), \text{SO}(n)} = \min \{p, q, k, n - k - 1\} + 2$ if $k = p = q$. We define

$$\Xi : \mathbb{R}[x, y, u] \rightarrow (\mathbb{R}[X]/I)^{H},$$

similarly as above, with

$$\Xi(u) := \det(x_{ij})_{2 \leq i \leq p + 1, p + 2 \leq j \leq n}.$$

By Lemma 4.1, we have $\Xi(xu) = \Xi(yu) = 0$. More precisely, each monomial in the development of the determinant contains each index at least once, while each term in $x$ (resp. $y$) contains each index twice.

We next compute $\Xi(u^{2})$ by using $x_{ai} x_{aj} = -\frac{1}{2} x_{aa} x_{ij}$, which is a consequence of Lemma 4.1.

$$\Xi(u^{2}) = \left( \sum_{\sigma \in \Sigma_{p}} \text{sgn}^{\prime}(\sigma) x_{2, \sigma(p+2)} \cdots x_{p+1, \sigma(n)} \right) \left( \sum_{\pi \in \Sigma_{p}} \text{sgn}^{\prime}(\pi) x_{2, \pi(p+2)} \cdots x_{p+1, \pi(n)} \right)$$

$$= \left( -\frac{1}{2} \right)^{p} x_{2,2} \cdots x_{p+1, p+1} \sum_{\sigma, \pi \in \Sigma_{p}} \text{sgn}^{\prime}(\sigma) \text{sgn}^{\prime}(\pi) x_{\sigma(p+2)} \cdots x_{\sigma(n)} \pi(n)$$

$$= \left( -\frac{1}{2} \right)^{p} x_{2,2} \cdots x_{p+1, p+1} ! \sum_{\pi \in \Sigma_{p}} \text{sgn}^{\prime}(\pi) x_{p+2, \pi(p+2)} \cdots x_{n, \pi(n)}$$

$$= \left( -\frac{1}{2} \right)^{p} p! E_{p}(x_{2,2}, \ldots, x_{p+1, p+1}) \det(x_{i,j})_{p + 2 \leq i, j \leq n}$$

$$= \left( -\frac{1}{2} \right)^{p} p! E_{p}(x_{2,2}, \ldots, x_{p+1, p+1}) \frac{(p + 1)!}{2^{2p}} E_{p}(x_{p+2, p+2}, \ldots, x_{n, n})$$

$$= (-1)^{p} \frac{(p + 1)!}{2^{2p}} \Xi(x^{p} y^{p}).$$

It follows that there is an induced algebra morphism

$$\tilde{\Xi} : \mathbb{R}[x, y, u]/\langle x^{p+1}, y^{p+1}, xu, yu, u^{2} - (-1)^{p} \frac{(p + 1)!}{2^{2p}} x^{p} y^{p} \rangle \rightarrow (\mathbb{R}[X]/I)^{H}.$$  

We argue as above to prove that $\tilde{\Xi}$ is injective. However, if $p$ is even, there are two elements whose images under $\tilde{\Xi}$ are of bidegree $(\frac{p}{2}, \frac{p}{2})$, namely $x^{\frac{p}{2}} y^{\frac{p}{2}}$ and $u$. We show that the images of these elements are linearly independent.

Let $\{X_{i}\}_{2 \leq i \leq p+1}$ be the dual basis to $\{\sigma_{i}\}_{2 \leq i \leq p+1}$ and let $\{X_{i,1}\}_{p+2 \leq i \leq n}$ be the dual basis to $\{\omega_{i,1}\}_{p+2 \leq i \leq n}$. By (12), the form corresponding to $\tilde{\Xi}(x^{\frac{p}{2}} y^{\frac{p}{2}})$ is non-zero but vanishes evaluated at $(X_{2}, \ldots, X_{p+1}, X_{p+2}, \ldots, X_{n,1})$. For the associated form to $\tilde{\Xi}(u)$, we have

$$\det \left( \frac{1}{2} (\sigma_{i} \wedge \omega_{j,1} + \sigma_{j} \wedge \omega_{i,1}) \right)_{2 \leq i \leq p+1, p+2 \leq j \leq n} (X_{2}, \ldots, X_{p+1}, X_{p+2}, \ldots, X_{n,1})$$

$\tilde{\Xi}$ Springer
We first recall the bases of FlagArea

In the following, \(0 \leq p \leq n - 1\), \(q := n - p - 1\), \(m_k := \min\{p, q, k, n - k - 1\}\).

### 6.1 Bases for FlagArea\(^{(p), SO(n)}\)

We first recall the bases of FlagArea\(^{(p), SO(n)}\) introduced in [1].

For \(\max\{0, k - q\} \leq a \leq \min\{k, p\}\), \(\hat{\eta}_{k,a} \in \Omega^{n-1}(\bigtimes_{\Phi_1} V)\) is defined as the coefficient of \(\alpha^a \beta^{k-a}\) in the expansion of

\[
\hat{\eta}_{a,\beta} := \bigwedge_{i=2}^{p+1} (\alpha \sigma_i + \omega_{i,1}) \bigwedge_{j=p+2}^{n} (\beta \sigma_j + \omega_{j,1}).
\]

(13)

In the case \(2p = 2k = n - 1\) we set

\[
\hat{\eta}_{\text{ex}} := \sigma_{p+2} \wedge \cdots \wedge \sigma_n \wedge \omega_{p+2,1} \wedge \cdots \wedge \omega_{n,1} \in \Omega^{n-1}(\bigtimes_{\Phi_1} V).
\]

(14)

We denote

\[
\hat{\omega}_{k,a} := \frac{\omega_n}{\text{vol}}(\bigtimes_{\Phi_1} V) \hat{\eta}_{k,a} \wedge \rho \in \Omega^m(\bigtimes_{\Phi_1} V),
\]

\[
\max\{0, k - q\} \leq a \leq \min\{k, p\},
\]

(15)

and, if \(n\) is odd and \(2p = n - 1\),

\[
\hat{\omega}_{\text{ex}} := \frac{\omega_n}{\text{vol}}\hat{\eta}_{\text{ex}} \wedge \rho \in \Omega^m(\bigtimes_{\Phi_1} V).
\]

(16)

Here \(\rho\) denotes the volume form of the fiber of the map \(\Pi : V \times Flag_{1,p+1} \to V \times S^{n-1}\).

We remark that the factor in the definition of \(\hat{\omega}_{k,a}\) does not appear explicitly in [1], but implicitly by the fact that the volume form on the fiber should be normalized to volume 1 (see [1, Corollary 4.6]).

The smooth flag area measure associated to the form \(\hat{\omega}_{k,a}\) (resp. \(\hat{\omega}_{\text{ex}}\)) is denoted by \(\Phi_{k,a} \in \text{FlagArea}^{(p), SO(n)}\) (resp. \(\Phi_{\text{ex}}\)) and is defined for \(0 \leq p, k \leq n - 1\), \(\max\{0, k - q\} \leq a \leq \min\{p, k\}\).

Another basis for FlagArea\(^{(p), SO(n)}\) was given in [1]. This basis contains the elements \(S_k^{(p)}\) in FlagArea\(^{(p), SO(n)}\) previously introduced in [24]. The smooth flag area
measures of this basis are denoted by $S_{k}^{(p),i}$ and defined, for $0 \leq p, k \leq n - 1$, $0 \leq i \leq m_k$, as

$$S_{k}^{(p),i} = c_{n,k,p,i} \sum_{a=\min\{p,k\}-m_k}^{\min\{p,k\}-i} \left( \begin{array}{c} \min\{p,k\} - a \\ i \end{array} \right) \Phi_{k,a},$$

where

$$c_{n,k,p,i} = \binom{n-1}{k}^{-1} \binom{m_k}{i}^{-1} \binom{|k - q| + m_k}{i}^{-1} \binom{n-1}{i}.$$

For the exceptional case $2p = 2k = n - 1$, the following notation is used:

$$\tilde{S}_{\frac{n-1}{2}}^{\frac{n-1}{2}} = \Phi_{ex}.$$

For the indicated ranges, both sets $\{S_{k}^{(p),i}\}$ and $\{\Phi_{k,a}\}$ constitute a basis of FlagArea$^{(p),O(n)}$ and the sets $\{S_{k}^{(p),i}, \tilde{S}_{\frac{n-1}{2}}^{\frac{n-1}{2}}\}$ and $\{\Phi_{k,a}, \Phi_{ex}\}$ a basis of FlagArea$^{(p),SO(n)}$. A straightforward computation shows that the inverse relation is given as follows.

**Lemma 6.1**

$$\Phi_{j,a} = \sum_{s=\min\{p,j\}-a}^{\min\{p,q,j,n-j-1\}} (-1)^{a+s}\binom{m_k}{s} \binom{s}{j} c_{n,j,p,s} \binom{n-1}{i} S_{j,s}^{(p),s}.$$

**Lemma 6.2** Let $\text{glob} : \text{FlagArea}^{(p),SO(n)} \to \text{Area}^{SO(n)}$ be the globalization map. Then

$$\text{glob} S_{k}^{(p),i} = S_{k},$$

$$\text{glob} \Phi_{k,a} = \left( \begin{array}{c} q \\ k-a \end{array} \right) \left( \begin{array}{c} p \\ a \end{array} \right) S_{k}.$$

**Proof** The first equation was shown in [1, Theorem 3]. The second equation can be deduced from the first one and Lemma 6.1.

**6.2 Bases for FlagArea$^{(p),SO(n),*}$**

**Corollary 6.3** The dual bases are related by

$$\Phi_{k,a}^{*} = \sum_{i=0}^{\min\{k,n-k-1,p,q\}} c_{n,k,p,i} \left( \begin{array}{c} \min\{k,p\} - a \\ i \end{array} \right) S_{k}^{(p),i,*},$$

\[ Springer\]
\[ S_k^{(p),i,*} = c_{n,k,p,i}^{-1} \sum_{a=\min[p,k]-i}^{\min[p,k]} (-1)^{a+\min[p,k]+i} \left( \frac{i}{\min[p,k] - a} \right) \Phi_{k,a}^* . \]

Let us introduce another basis of FlagArea\((p),SO(n),*\). For \(\max\{0, k - q\} \leq a \leq \min\{k, p\}\), we define \(\tilde{\tau}_{k,a} \in \mathcal{J}^{n,fr}\) by

\[
\tilde{\tau}_{k,a} := \ast_1^{-1} E_a(x_{22}, \ldots, x_{p+1,p+1}) E_{k-a}(x_{p+2,p+2}, \ldots, x_{n,n}).
\]

(18)

Let \(\tilde{\Phi}_{k,a}^*\) be the element in FlagArea\((p),SO(n),*\) given by \(\tilde{\tau}_{k,a}\). If \((k, p) \neq (\frac{n-1}{2}, \frac{n-1}{2})\), the elements of \(\{\tilde{\Phi}_{k,a}^*\}_{\max\{0, k-q\} \leq a \leq \min\{p,k\}}\) constitute a basis of FlagArea\((p),SO(n),*\) by [1, Theorem 4].

In the exceptional case \(2p = 2k = n - 1\), we define

\[
\tilde{\tau}_{ex} := \ast_1^{-1} \det(x_{ij})_{2 \leq i \leq p+1, \quad p+2 \leq j \leq n} \in \mathcal{J}^{n,fr}.
\]

The smooth dual flag area measure associated to the form \(\tilde{\tau}_{ex}\) will be denoted by \(\tilde{\Phi}_{ex}^*\). For \(2p = 2k = n - 1\), the elements of \(\{\tilde{\Phi}_{k,a}^*\}_{0 \leq a \leq k}\) together with \(\tilde{\Phi}_{ex}^*\) constitute a basis of FlagArea\((p),SO(n),*\). This follows again from [1, Theorem 4] and the fact that \(\tilde{\tau}_{ex} \wedge \tilde{\tau}_{ex} \neq 0\) but \(\tilde{\tau}_{k,a} \wedge \tilde{\tau}_{ex} = 0\).

The following lemma expresses the elements of the dual basis of \(\{\Phi_{k,a}\} \cup \{\Phi_{ex}\}\) and \(\{S_k^{(p),i,*}\}\) in the algebra given in Proposition 1.3.

**Lemma 6.4** (i) For \(0 \leq k \leq n - 1\) and \(\max\{0, k - q\} \leq a \leq \min\{p, k\}\)

\[ \Phi_{k,a}^* = \frac{1}{\omega_n} \binom{q}{k-a}^{-1} \binom{p}{a}^{-1} \frac{1}{a!(k-a)!} x^a y^{k-a}. \]

(ii) For \(0 \leq k \leq n - 1\) and \(0 \leq i \leq \min\{p, q, k, n - k - 1\}\),

\[ S_k^{(p),i,*} = \frac{(-1)^{i+\min[p,k]}}{\omega_n c_{n,k,p,i} p!} \sum_{a=\min[p,k]-i}^{\min[p,k]} (-1)^a \frac{1}{a!(k-a)!} \binom{i}{\min[p,k] - a} \binom{q}{k-a}^{-1} \binom{p}{a}^{-1} x^a y^{k-a}. \]

(iii) If \(2p = 2k = n - 1\), then

\[ \Phi_{ex}^* = \frac{(-1)^p}{\omega_n p!} u. \]

**Proof** (i) Let

\[ \tilde{\tau}_{\alpha,\beta} := \ast_1^{-1} \sum_{i=0}^{p} \omega_i^{p-i} E_i(\sigma_2 \wedge \omega_2, \ldots, \sigma_{p+1} \wedge \omega_{p+1}) \]

Springer
\[
\sum_{j=0}^{q} \beta^{q-j} E_j(\sigma_{p+2} \wedge \omega_{p+2,1}, \ldots, \sigma_n \wedge \omega_{n,1})
\]
\[
= \sigma_1 \wedge \bigwedge_{i=2}^{p+1} (\alpha \sigma_i + \omega_{i,1}) \wedge \bigwedge_{j=p+2}^{n} (\beta \sigma_j + \omega_{j,1}),
\]
(19)

where the second equation follows from [9, Eq. (47)]. Then the coefficient of \(\alpha^p \beta^q \beta^a \beta^{q-k+a}\) in \(\tilde{t}_{a, \beta}\) is \(\tilde{t}_{k,a}\).

Let \(k, a\) be fixed. We first compute \(\langle \tilde{\Phi}_{i,b}^*, \Phi_{k,a}\rangle\) for fixed indices \(l, b\) by using the expansions in (13) and (19). For \(\alpha, \beta, \tilde{\alpha}, \tilde{\beta} \in \mathbb{R}\), one can easily check that

\[
\tilde{t}_{a, \beta} \wedge \tilde{t}_{\tilde{\alpha}, \tilde{\beta}} = (\alpha + \tilde{\alpha})^{p} (\beta + \tilde{\beta})^{n-p-1} \sigma_1 \wedge \cdots \wedge \sigma_n \wedge \omega_{2,1} \wedge \cdots \wedge \omega_{n,1}.
\]

Since \(\tilde{t}_{k,a} \wedge \tilde{t}_{l,b}\) is the coefficient of \(\alpha^a \beta^{k-a} \tilde{\alpha}^p \tilde{\beta}^{n-l-1-p+b}\) in this expression, we find that \(\tilde{t}_{k,a} \wedge \tilde{t}_{l,b} = 0\) if \(b \neq a\) or \(l \neq k\). In the case \(b = a\) and \(l = k\), we have, by Definition 3.5,

\[
\langle \tilde{\Phi}_{k,a}^*, \Phi_{k,a}\rangle = \frac{\omega_n}{\text{vol(Flag}_{1,p+1})} \int \tilde{t}_{k,a} \wedge \tilde{t}_{k,a} \wedge \rho = \frac{\omega_n}{\text{vol(Flag}_{1,p+1})} \left( \frac{p}{a} \right) \left( \frac{n-p-1}{k-a} \right) \int \sigma_1 \wedge \cdots \wedge \sigma_n \wedge \omega_{2,1} \wedge \cdots \wedge \omega_{n,1} \wedge \rho
\]

Hence,

\[
\Phi_{k,a}^* = \frac{1}{\omega_n} \left( \frac{q}{k-a} \right)^{-1} \left( \frac{p}{a} \right)^{-1} \tilde{\Phi}_{k,a}^*.
\]
(20)

The statement now follows from the fact that \(\tilde{\Phi}_{k,a}^* = \frac{x^a y^{k-a}}{a! (k-a)!}\), which is a consequence of Lemma 4.1(iii).

(ii) This follows from Corollary 6.3 and (i).

(iii) We first show that

\[
\Phi_{ex}^* = \frac{(-1)^p}{\omega_n} \Phi_{ex}^*,
\]

which follows from

\[
\langle \tilde{\Phi}_{ex}^*, \Phi_{ex}\rangle = \frac{\omega_n}{\text{vol(Flag}_{1,p+1})} \int \tilde{t}_{ex} \wedge \sigma_{p+2} \wedge \cdots \wedge \sigma_n \wedge \omega_{p+2,1} \wedge \cdots \wedge \omega_{n,1}
\]
\[
= \frac{\omega_n}{\text{vol(Flag}_{1,p+1})} (-1)^{\left( \frac{p}{2} \right)} p! \int \sigma_{p+2} \wedge \cdots \wedge \sigma_n \wedge \omega_{2,1} \wedge \cdots \wedge \omega_{p+1,1}
\]
\[
\wedge \sigma_{p+2} \wedge \cdots \wedge \sigma_n \wedge \omega_{p+2,1} \wedge \cdots \wedge \omega_{n,1} \wedge \rho
\]

\(\square\) Springer
Additive kinematic formulas

\[ \omega_n \text{vol}(\text{Flag}_{1,p+1}) p! \int \sigma_1 \wedge \cdots \wedge \sigma_{p+1} \wedge \omega_{2,1} \wedge \cdots \wedge \omega_{p+1,1} \wedge \sigma_{p+2} \wedge \cdots \wedge \sigma_n \wedge \omega_{p+2,1} \wedge \cdots \wedge \omega_{n,1} \wedge \rho \]

\[ = \omega_n \text{vol}(\text{Flag}_{1,p+1}) (-1)^p p! \int \sigma_1 \wedge \cdots \wedge \sigma_n \wedge \omega_{2,1} \wedge \cdots \wedge \omega_{n,1} \wedge \rho \]

\[ = (-1)^p p! \omega_n. \]

The proof is finished by noting that \( \tilde{\Phi}^*_{ex} = u. \)

The globalization map \( \text{glob} : \text{FlagArea}^{(p),SO(n)} \to \text{Area}^{SO(n)} \) induces an algebra morphism \( \text{glob}^* : \text{Area}^{SO(n),*} \to \text{FlagArea}^{(p),SO(n),*} \). In terms of the algebraic descriptions it is given as \( t \mapsto x + y \). This follows from Lemma 3.6 since \( t \) is mapped to

\[ \sum E_{1}(x_{22}, \ldots, x_{nn}) \sum E_{1}(x_{p+2,p+2}, \ldots, x_{nn}) \]

By Lemma 6.4 and (17) we thus have

\[ \langle t, S_1 \rangle = \langle t, \text{glob}^*(t), S_1(p,0) \rangle = \langle x + y, S_1(p,0) \rangle = \left( \omega_n (p \Phi^*_{1,1} + q \Phi^*_{1,0}), \frac{1}{n-1} (\Phi_{1,0} + \Phi_{1,1}) \right) = \omega_n, \]

which implies that \( t = \omega_n S_1^*. \) Hence the constant \( c \) from the end of Sect. 4 equals \( \omega_n \).

7 Explicit additive kinematic formulas

The aim in this section is to obtain explicit additive kinematic formulas for \( \text{FlagArea}^{(p),SO(n)} \). We denote by

\[ A^G_{1,p+1} : \text{FlagArea}^{(p),G} \to \text{FlagArea}^{(p),G} \otimes \text{FlagArea}^{(p),G} \]

the additive kinematic operator for flag area measures in \( \text{FlagArea}^{(p),G} \) with \( G \) either \( O(n) \) or \( SO(n) \).

Theorem 7.1

(i) For \( 0 \leq k \leq n - 1 \) and \( \max\{0, k - q\} \leq a \leq \min\{p, k\} \), the additive kinematic formulas for \( O(n) \) are given by

\[ A^{O(n)}_{1,p+1}(\Phi_{k,a}) = \frac{1}{\omega_n} \sum_{j=0}^{k} \sum_{b=\max(0,j-k+a)}^{\min\{a,j\}} c^{k,a}_{j,b} \Phi_{j,b} \otimes \Phi_{k-j,a-b}, \]

where

\[ c^{k,a}_{j,b} = \binom{q}{j-b}^{-1} \binom{p}{b}^{-1} \binom{q-k+j+a-b}{j-b} \binom{p-a+b}{b}. \]
The additive kinematic formulas for \( \text{SO}(n) \) are given as follows. If \((k, p) \neq (n - 1, \frac{n - 1}{2})\), then

\[
A^{\text{SO}(n)}_{1, p+1}(\Phi_{k,a}) = A^{\text{O}(n)}_{1, p+1}(\Phi_{k,a}).
\]

If \(k = 2p = n - 1\), then

\[
A^{\text{SO}(n)}_{1, p+1}(\Phi_{n-1, \frac{n-1}{2}}) = A^{\text{O}(n)}_{1, p+1}(\Phi_{n-1, \frac{n-1}{2}}) + \frac{(-1)^p (p + 1)}{2^p \omega_n} \Phi_{\text{ex}} \otimes \Phi_{\text{ex}},
\]

and

\[
A^{\text{SO}(n)}_{1, p+1}(\Phi_{\text{ex}}) = \frac{1}{\omega_n} \left( \Phi_{\text{ex}} \otimes \Phi_{0,0} + \Phi_{0,0} \otimes \Phi_{\text{ex}} \right).
\]

**Proof** (i) Using the algebraic structure of \( \text{FlagArea}^{(p), \text{O}(n)} \) and Theorem 3.9 we compute the coefficient \( c^{k,a}_{j,b,l,c} \) of \( \Phi_{j,b} \otimes \Phi_{l,c} \) in \( A^{\text{O}(n)}_{1, p+1}(\Phi_{k,a}) \) as

\[
c^{k,a}_{j,b,l,c} = \left\{ A^{\text{O}(n)}_{1, p+1}(\Phi_{k,a}), \Phi^*_{j,b} \otimes \Phi^*_{l,c} \right\} = \left\{ \Phi_{k,a}, A^{\text{O}(n),*}_{1, p+1}(\Phi^*_{j,b} \otimes \Phi^*_{l,c}) \right\} = \langle \Phi_{k,a}, \Phi^*_{j,b} \cdot \Phi^*_{l,c} \rangle.
\]

We have

\[
\Phi^*_{j,b} \cdot \Phi^*_{l,c} = \frac{1}{\omega_n^2} \left( \begin{array}{c} q \\ j - b \\ \end{array} \right)^{-1} \left( \begin{array}{c} p \\ b \\ \end{array} \right)^{-1} \left( \begin{array}{c} q \\ l - c \\ \end{array} \right)^{-1} \left( \begin{array}{c} p \\ c \\ \end{array} \right)^{-1} \frac{1}{b!(j - b)!c!(l - c)!} x^b y^{j - b} z^c y^{l - c} = \frac{1}{\omega_n} \left( \begin{array}{c} q \\ j - b \\ \end{array} \right)^{-1} \left( \begin{array}{c} p \\ b \\ \end{array} \right)^{-1} \left( \begin{array}{c} q \\ l - c \\ \end{array} \right)^{-1} \left( \begin{array}{c} p \\ c \\ \end{array} \right)^{-1} \frac{1}{b+c} \left( \begin{array}{c} j + l - b - c \\ \end{array} \right) \left( \begin{array}{c} q \\ j - b \\ \end{array} \right) \left( \begin{array}{c} p \\ b + c \\ \end{array} \right) \Phi^*_{j+l,b+c}.\]

It follows that \( c^{k,a}_{j,b,l,c} \) equals zero unless \( k = j + l \) and \( a = b + c \) and the result follows.

Let us double check the constants in this formula. Clearly the additive kinematic formulas commute with the globalization map \( \text{glob} : \text{FlagArea}^{(p), \text{O}(n)} \rightarrow \text{Area}^{\text{O}(n)} \). By Lemma 6.2, \( \text{glob} \otimes \text{glob} \) applied to the right hand side gives

\[
\frac{1}{\omega_n} \sum_{j=0}^{k} \sum_{b=\max(0,j-k+a)}^{\min(a,j)} c^{k,a}_{j,b} \text{glob} \Phi_{j,b} \otimes \text{glob} \Phi_{k-j,a-b}
\]

\( \square \) Springer
Additive kinematic formulas...

\[\begin{align*}
1649 &= \frac{1}{\omega_n} \sum_{j=0}^{k} \sum_{b=\max(0, j-k+a)}^{a, j} c_{j,b}^{k,a} \left( \begin{array}{c} q \\ j-b \end{array} \right) \left( \begin{array}{c} p \\ b \end{array} \right) S_j \otimes \left( \begin{array}{c} q \\ k-j-a+b \end{array} \right) \left( \begin{array}{c} p \\ a-b \end{array} \right) S_{k-j} \\
1649 &= \frac{1}{\omega_n} \sum_{j=0}^{k} \sum_{b=\max(0, j-k+a)}^{a, j} \left( \begin{array}{c} q-k+j+a-b \\ j-b \end{array} \right) \left( \begin{array}{c} p-a+b \\ b \end{array} \right) \left( \begin{array}{c} q \\ k-j-a+b \end{array} \right) \left( \begin{array}{c} p \\ a-b \end{array} \right) S_j \otimes S_{k-j} \\
1649 &= \frac{1}{\omega_n} \sum_{j=0}^{k} \sum_{b=\max(0, j-k+a)}^{a, j} \left( \begin{array}{c} a \\ b \end{array} \right) \left( \begin{array}{c} k-a \\ j-b \end{array} \right) S_j \otimes S_{k-j} \\
1649 &= \frac{1}{\omega_n} \left( \begin{array}{c} q \\ k-a \end{array} \right) \left( \begin{array}{c} p \\ a \end{array} \right) \sum_{j=0}^{k} \left( \begin{array}{c} k \\ j \end{array} \right) S_j \otimes S_{k-j}.
\end{align*}\]

The globalization of the left hand side in the kinematic formula is \(\left( \begin{array}{c} q-k+a \\ p-a \end{array} \right) A(S_k)\), which equals the globalization of the right hand side by (10).

(ii) For the proof of additive kinematic formulas for SO(n), we first observe that the above argument remains the same unless we are in the exceptional case \(2p = k = n-1\). In this case, it remains to compute the coefficient \(\langle \Phi_1^{SO(n)}, 1, p+1, \Phi_{n-1, \frac{p}{2}}, \Phi_{ex} \otimes \Phi_{ex}^* \rangle\). For that, we compute

\[\begin{align*}
(\Phi_{ex}^*)^2 &= \frac{1}{\omega_n^2 p!^2} u^2 \\
&= (-1)^p (p+1) \frac{\omega_n^2 2^p p!^2}{(q-k+1)} \\
&= (-1)^p (p+1) \frac{\Phi_n^*}{2^p \omega_n} \Phi_{n-1, \frac{p-1}{2}}
\end{align*}\]

from which the result follows.

Finally, the additive kinematic formula for \(\Phi_{ex}\) has to be a linear combination of \(\Phi_{ex} \otimes \Phi_{k,0}, \Phi_{k,0} \otimes \Phi_{ex}\) and the formula follows directly.

\[\square\]

**Corollary 7.2** Let \(0 \leq p \leq n - k - 1\) and consider the flag area measures \(S_k^{(p)}\) introduced in [24]. Then,

\[A_{1, p+1}^{SO(n)}(S_k^{(p)}) = \frac{1}{\omega_{n-p}} \sum_{j=0}^{k} \left( \begin{array}{c} k \\ j \end{array} \right) S_j^{(p)} \otimes S_{k-j}^{(p)}.
\]

**Proof** This follows from the case \(a = 0\) in Theorem 7.1, since

\[S_k^{(p)} = \frac{\omega_{n-p}}{\omega_n} S_k^{(p), \min[k,p]} = \frac{\omega_{n-p}}{\omega_n} \left( \begin{array}{c} q \\ k \end{array} \right)^{-1} \Phi_{k,0}
\]

by [1, Theorem 3] and by (17). \[\square\]
Proof of Theorem 4  By the previous results, it suffices to compute $A_{O(n)}^{0(n)}$. Indeed, for $2p = n - 1$, by definition $S_{\frac{n-1}{2}}^{n-1} = \Phi_{ex}$ and $\Phi_{n-1, \frac{n-1}{2}} = S_{n-1}^{(p),0}$, hence $A_{O(n)}^{0(n)}$ can be directly deduced from $A_{1, p+1}^{0(n)}$ and Theorem 7.1.

By proceeding as in Theorem 7.1, we have that the coefficient of $S_j^{(p),b} \otimes S_l^{(p),c}$ in $A_{1, p+1}^{0(n)}(S_k^{(p),i})$ is given by

$$\langle S_k^{(p),i}, S_j^{(p),b}, S_l^{(p),c} \rangle.$$ 

Let

$$S_k^{(p),i,*} = \sum_{a=m_k-i}^{m_k} K_{k,i,a} x^a y^{k-a}$$

with $K_{k,i,a}$ the constant given in Lemma 6.4(ii) and let

$$x^a y^{k-a} = \tilde{K}_{k,a} \Phi_{k,a}^*$$

with $\tilde{K}_{k,a}$ the constant obtained from Lemma 6.4(i).

Using the defined constants and (17), we have

$$\langle S_k^{(p),i}, S_j^{(p),b,*}, S_l^{(p),c,*} \rangle = \left( S_k^{(p),i}, \sum_{s=m_j-b}^{m_j} \sum_{r=m_l-c}^{m_l} K_{j,b,s} K_{l,c,r} \tilde{K}_{j+l,s+r} \Phi_{j+l,r+s}^* \right)$$

$$= \sum_{t=m_k-b}^{m_k} \sum_{s=m_j-b}^{m_j} \sum_{r=m_l-c}^{m_l} c_{n,k,p,i} \left( m_k - t \right) K_{j,b,s} K_{l,c,r} \tilde{K}_{j+l,s+r} \left( \Phi_{k,t}, \Phi_{j+l,r+s}^* \right).$$

Hence, the coefficient of $S_j^{(p),b} \otimes S_l^{(p),c}$ in $A_{1, p+1}^{0(n)}(S_k^{(p),i})$ is zero unless $k = j + l$ and $t = s + r$ and the result follows by substituting the constants and taking into account the possible range for $t$, $s$ and $r$. \[\square\]

Acknowledgements  We thank Thomas Wannerer for useful comments on a first draft of this paper and the anonymous referee for many useful remarks.

Funding  Open Access funding enabled and organized by Projekt DEAL.

Data Availability  Data sharing not applicable to this article as no datasets were generated or analysed during the current study.

Declarations  

Conflict of interest  On behalf of all authors, the corresponding author states that there is no conflict of interest.
Open Access  This article is licensed under a Creative Commons Attribution 4.0 International License, which permits use, sharing, adaptation, distribution and reproduction in any medium or format, as long as you give appropriate credit to the original author(s) and the source, provide a link to the Creative Commons licence, and indicate if changes were made. The images or other third party material in this article are included in the article’s Creative Commons licence, unless indicated otherwise in a credit line to the material. If material is not included in the article’s Creative Commons licence and your intended use is not permitted by statutory regulation or exceeds the permitted use, you will need to obtain permission directly from the copyright holder. To view a copy of this licence, visit http://creativecommons.org/licenses/by/4.0/.

References

1. Abardia-Evéquoz, J., Bernig, A., Dann, S.: Flag area measures. Mathematika 65(4), 958–989 (2019)
2. Alesker, S.: Description of translation invariant valuations on convex sets with solution of P. McMullen’s conjecture. Geom. Funct. Anal. 11(2), 244–272 (2001)
3. Álvarez Paiva, J.C., Fernandes, E.: Gelfand transforms and Crofton formulas. Selecta Math. (N.S.) 13(3), 369–390 (2007)
4. Berline, N., Getzler, E., Vergne, M.: Heat kernels and Dirac operators. In: Grundlehren Text Editions. Springer-Verlag, Berlin (2004) (Corrected reprint of the 1992 original)
5. Bernig, A.: A Hadwiger type theorem for the special unitary group. Geom. Funct. Anal. 19, 356–372 (2009)
6. Bernig, A.: Integral geometry under $G_2$ and Spin$(7)$. Israel J. Math. 184, 301–316 (2011)
7. Bernig, A.: Invariant valuations on quaternionic vector spaces. J. Inst. Math. Jussieu 11, 467–499 (2012)
8. Bernig, A.: Dual area measures and local additive kinematic formulas. Geom. Dedicata 203(1), 85–110 (2019)
9. Bernig, A., Fu, J.H.G.: Convolution of convex valuations. Geom. Dedicata 123, 153–169 (2006)
10. Bernig, A., Fu, J.H.G.: Hermitian integral geometry. Ann. Math. 173, 907–945 (2011)
11. Bernig, A., Fu, J.H.G., Solanes, G.: Integral geometry of complex space forms. Geom. Funct. Anal. 24(2), 403–492 (2014)
12. Bernig, A., Fu, J.H.G., Solanes, G.: Dual curvature measures in Hermitian integral geometry. In: Analytic aspects of convexity, volume 25 of Springer INdAM Ser., pages 1–17. Springer, Cham (2018)
13. Bernig, A., Hug, D.: Kinematic formulas for tensor valuations. J. Reine Angew. Math. 736, 141–191 (2018)
14. Bernig, A., Solanes, G.: Classification of invariant valuations on the quaternionic plane. J. Funct. Anal. 267, 2933–2961 (2014)
15. Bernig, A., Solanes, G.: Kinematic formulas on the quaternionic plane. Proc. Lond. Math. Soc. (3) 115(4), 725–762 (2017)
16. Bernig, A., Voide, F.: Spin-invariant valuations on the octonionic plane. Israel J. Math. 214(2), 831–855 (2016)
17. Borel, A.: Some remarks about Lie groups transitive on spheres and tori. Bull. Am. Math. Soc. 55, 580–587 (1949)
18. Böröczky, K.J., Domokos, M., Solanes, G.: Dimension of the space of unitary equivariant translation invariant tensor valuations. J. Funct. Anal. 280(4), 108862 (2021)
19. Bröcker, T., Tammo T. D.: Representations of compact Lie groups, volume 98 of Graduate Texts in Mathematics. Springer-Verlag, New York (1995) (Translated from the German manuscript, Corrected reprint of the 1985 translation)
20. Federer, H.: Geometric measure theory. Die Grundlehren der mathematischen Wissenschaften, Band 153. Springer, New York Inc., New York (1969)
21. Fu, J.H.G.: Kinematic formulas in integral geometry. Indiana Univ. Math. J. 39(4), 1115–1154 (1990)
22. Fulton, W., Harris, J.: Representation theory. A first course. Graduate Texts in Mathematics. 129. New York etc.: Springer, xv, 551 p., 144 ill. (1991)
23. Haberl, C.: Minkowski valuations intertwining with the special linear group. J. Eur. Math. Soc. (JEMS) 14(5), 1565–1597 (2012)
24. Hinderer, W., Hug, D., Weil, W.: Extensions of translation invariant valuations on polytopes. Mathematika 61(1), 236–258 (2015)
25. Hug, D., Schneider, R.: Local tensor valuations. Geom. Funct. Anal. 24(5), 1516–1564 (2014)
26. Hug, D., Schneider, R., Schuster, R.: The space of isometry covariant tensor valuations. Algebra i Analiz 19(1), 194–224 (2007)
27. Hug, D., Schneider, R., Schuster, R.: Integral geometry of tensor valuations. Adv. Appl. Math. 41(4), 482–509 (2008)
28. Hug, D., Türk, I., Weil, W.: Flag measures for convex bodies. In: Asymptotic geometric analysis, volume 68 of Fields Inst. Commun., pages 145–187. Springer, New York (2013)
29. Hug, D., Weis, J.A.: Crofton formulae for tensor-valued curvature measures. In: Tensor valuations and their applications in stochastic geometry and imaging, volume 2177 of Lecture Notes in Math., pages 111–156. Springer, Cham (2017)
30. Huybrechts, D.: Complex Geometry. Universitext, pp. xii+309. Springer, Berlin (2005)
31. Kiderlen, M., Eva B., Vedel J. (eds.): Tensor Valuations and Their Applications in Stochastic Geometry and Imaging. Springer Lecture notes in mathematics (2017)
32. Ludwig, M.: Minkowski valuations. Trans. Am. Math. Soc. 357(10), 4191–4213 (2005). (electronic)
33. Montgomery, D., Samelson, H.: Transformation groups of spheres. Ann. Math. 2(44), 454–470 (1943)
34. Rumin, M.: Differential forms on contact manifolds. (Formes différentielles sur les variétés de contact). J. Differ. Geom. 39(2), 281–330 (1994)
35. Schneider, R.: Kinematische Berührmaße für konvexe Körper und Integralrelationen für Oberflächenmaße. Math. Ann. 218(3), 253–267 (1975)
36. Schneider, R.: Curvature measures of convex bodies. Ann. Mat. Pura Appl. 4(116), 101–134 (1978)
37. Schneider, R.: Convex bodies: the Brunn–Minkowski theory, vol. 151 of Encyclopedia of Mathematics and its Applications. Cambridge University Press, Cambridge (2014)
38. Schuster, F., Wannerer, T.: Minkowski valuations and generalized valuations. J. Eur. Math. Soc. (JEMS) 20(8), 1851–1884 (2018)
39. Schuster, F.E., Wannerer, T.: GL(n) contravariant Minkowski valuations. Trans. Am. Math. Soc. 364(2), 815–826 (2012)
40. Solanes, G.: Contact measures in isotropic spaces. Adv. Math. 317, 645–664 (2017)
41. Wannerer, T.: Integral geometry of unitary area measures. Adv. Math. 263, 1–44 (2014)
42. Wannerer, T.: The module of unitarily invariant area measures. J. Differ. Geom. 96(1), 141–182 (2014)

Publisher’s Note Springer Nature remains neutral with regard to jurisdictional claims in published maps and institutional affiliations.