Probabilistic phase space trajectory description for anomalous polymer dynamics

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Abstract

It has been recently shown that the phase space trajectories for the anomalous dynamics of a tagged monomer of a polymer—for single polymeric systems and phenomena such as phantom Rouse, self-avoiding Rouse, and Zimm ones, reptation, and translocation through a narrow pore in a membrane, as well as for many polymeric systems such as polymer melts in the entangled regime—are robustly described by the generalized Langevin equation. Here I show that the probability distribution of phase space trajectories for all of these classical anomalous dynamics for single polymers is that of a fractional Brownian motion (fBm), while the dynamics for polymer melts between the entangled regime and the eventual diffusive regime exhibits small but systematic deviations from that of a fBm.

In its terminal relaxation time \( \tau \), \( \tau \sim N^\kappa \), a polymer of length \( N \) displaces itself in space by its own size, which itself scales as \( \sim N^\xi \) [1, 2]. The values of \( \kappa \) and \( \xi \) vary from system to system. For example, for phantom (self-intersecting) polymers \( \xi = 1/2 \), and for self-avoiding polymers \( \xi = \nu \), with \( \nu = 3/4 \) in two dimensions and \( \approx 0.588 \) in three dimensions respectively. Similarly, for polymer dynamics in the absence of hydrodynamic interactions (Rouse [3, 4]) \( \kappa = 1 + 2\xi \), and polymer dynamics in a good solvent (Zimm [1, 2, 4, 5]) \( \kappa = 3\xi \). The above means, in the simplest case, that the mean square displacement (MSD) of a tagged monomer of a polymer must behave \( \sim t^{2\xi/\kappa} \) until time \( \tau \), and \( \sim t \) thereafter. Since \( 2\xi/\kappa \) is not necessarily unity, the dynamics of a tagged monomer in a polymer is anomalous until time \( \tau \), and the polymer’s diffusion coefficient scales \( \sim N^{2\xi - \kappa} \).

Starting from a microscopic description, there are two main approaches to model anomalous dynamics in stochastic systems [6]: (i) continuous time random walk (CTRW) [7] and the associated fractional Fokker–Planck equation (fFPE), providing a probabilistic description of phase space trajectories, and (ii) the generalized Langevin equation (GLE) [8], which describes individual phase space trajectories. Physical systems exhibiting anomalous dynamics, for which probabilistic description of phase space trajectories as well as description of individual trajectories can be obtained, are not only relatively rare, but also relating one description to the other often requires approximations [9]. Anyhow, given the ubiquity of anomalous dynamics in polymeric systems [1, 2], one would expect them to have been thoroughly examined from this perspective. To the best of my knowledge however, probabilistic description of phase space trajectories for anomalous polymer dynamics has only been considered for isolated cases such as the Rouse chain [10], and polymer translocation [11–15]: in [11, 12], an fFPE approach has been put forward, wherein a (power-law) waiting time before each move of the monomer in the pore is assumed to cause the anomalous dynamics. This approach is at odds with numerical studies by others [13], who report that, for the translocation of an infinite polymer, the probability distribution is Gaussian in space but with a width that scales anomalously in time. Further, the anomalous dynamics of translocation has been shown to match that of the fractional Brownian motion (fBm) [14, 15], which is also in contradiction with the fFPE approach.

As for the description of individual trajectories for anomalous polymer dynamics, two recent papers [16, 17] show that without external forces, the motion of a tagged monomer of a polymer—for phantom and self-avoiding Rouse, Zimm, reptation, translocation, and polymer melts—is robustly
described by a unified GLE. The force \( \tilde{\phi}(t) \) experienced by
the tagged monomer is related to its velocity \( \tilde{v}(t) \) via
\[
\tilde{\phi}(t) = - \int_0^t dt' \mu(t-t')\tilde{v}(t') + \tilde{g}(t),
\]
where \( \mu(t) \) is the memory kernel, and the noise \( \tilde{g}(t) \) satisfies
\( \langle \tilde{g}(t) \rangle_0 = 0 \) and the fluctuation-dissipation theorem (FDT)
\( \langle g_\sigma(t)g_\lambda(t') \rangle = \kappa_\sigma T_\lambda \delta(t-t') \), where \( \sigma, \lambda = (x, y, z) \). Here \( \langle \cdot \rangle_0 \) denotes an average over the noise realizations, including
an average over equilibrium configurations of the polymers at \( t = 0^- \). Further, with \( \tilde{v}(t) \) responding to \( \tilde{\phi}(t) \) as \( \gamma \tilde{v}(t) = \tilde{\phi}(t) + \tilde{f}(t) \), where \( \gamma \) is the (effective) damping coefficient
for monomeric motion, and \( \tilde{f}(t) \) is a random force satisfying
\( \langle \tilde{f}(t) \rangle = 0 \) and the FDT \( \langle f_\sigma(t)f_\lambda(t') \rangle = 2\gamma \kappa_\sigma T_\lambda \delta(t-t') \), one has
\[
\tilde{v}(t) = \gamma^{-1} \left[ - \int_0^t dt' \mu(t-t')\tilde{v}(t') + \tilde{g}(t) + \tilde{f}(t) \right].
\]
In this formulation, \( \mu(t) \sim t^{-\alpha}e^{-t/\tau} \) for some \( 0 < \alpha < 1 \) (for a list, see table 1 of [17]). The FDT then ensures that the MSD \( \sim t^\alpha \) until time \( \tau \), and \( \sim \tau \) thereafter. This formulation also robustly yields the correct drift behavior of a tagged monomer under weak external forces [17], like the
Nernst–Einstein relation. The GLE (1) and (2), describing non-Markovian trajectories in phase space, demonstrate that there is no power-law waiting time (assumed in the modeling of translocation by the fFPE); instead, the anomalous dynamics stems from the fact that each move of the tagged monomer tends to be undone later.

Here I demonstrate that, with a \( \delta \)-function distribution in
3D space at \( t = 0 \), the probability distribution of a tagged
monomer for phantom Rouse, self-avoiding Rouse, Zimm, polymers in a \( \theta \)-solvent, reptation, and translocation in polymer melts in the entangled regime is given by
\[
P(\vec{r}, t|\vec{r}_0, 0) = e^{-\langle \vec{r}^2 \rangle_0^{1/2}/2\Delta(t)}/[2\pi \Delta(t)]^{3/2},
\]
with \( \Delta(t) = A t^\alpha e^{-t/\tau} + BN^{2\xi-\kappa}t \), where \( A \) and \( B \) are
two system parameters-dependent constants, and \( N^{2\xi-\kappa} \) is the scaling of the polymer’s diffusion coefficient with \( N \)
(for translocation, equation (3) holds only until the polymer disengages from the pore; see later), i.e. the anomalous dynamics of an infinite polymer is that of the fBm [18]. One should keep in mind that equation (3) is demonstrated here
for polymeric systems wherein the polymers are far away from any boundary (including translocation), as equation (3) cannot be reconciled with nontrivial boundary conditions. The GLE (1) and (2) and equation (3) thus provide a complete description (i.e. of individual trajectories as well as that of trajectory distribution in phase space) of anomalous dynamics in polymeric systems; as mentioned earlier, this is relatively rare for physical systems.

In fact, \( P(\vec{r}, t|\vec{r}_0, 0) \) for phantom Rouse, Zimm, polymers
in a \( \theta \)-solvent, and reptation can be obtained analytically, irrespective of the GLE description, thanks to the fact that their dynamics is described by that of the polymer’s fluctuation modes. For these systems, the location \( R_\alpha(t) \)
of monomer \( n \) can be expressed in terms of the mode amplitude \( \{ X_p(t) \} \)s for \( p = 0, 1, 2, \ldots \), as \( R_\alpha(t) = X_0(t) + \sum_{p=1}^\infty X_p(t) \cos(p\pi n/\eta) \) obeying the boundary condition that the polymer’s chain tension vanishes at the free ends, i.e. \( \partial R_\alpha(t)/\partial n|_{n=0} = \partial R_\alpha(t)/\partial n|_{n=N} = 0 \). As the \( \{ X_p(t) \} \)\s can be obtained by an inverse cosine transformation of the above, the polymer dynamics is simply reconstructed from the LE satisfied by each spatial component (denoted by \( \sigma \)) of the \( \{ X_p(t) \} \)\s [2]
\[
\gamma_p X_p(t) = -k_p X_p(t) + f_p(t),
\]
where the stochastic forces satisfy \( \langle f_p(t) \rangle = 0 \) and the
FDT \( \langle f_p(t)f_q(t') \rangle = 2\gamma_k \kappa_\sigma T_\lambda \delta(t-t') \). The list of \( \gamma_p \) and \( k_p \) values for these systems appear in table 1: note that the relaxation time \( \tau_p \) for the \( p \)th mode \( \tau_p = \gamma_p/k_p = c^{-1}p^{-\kappa} \) for \( p \neq 0 \); one can calculate \( c \) from the table.

With the above, \( P(\vec{r}, t|\vec{r}_0, 0) \) is calculated as follows. For fixed \( \{ X_p^{(0)} \} \)s that correspond to the position \( \vec{r}_0 \) of the tagged monomer at \( t = 0 \), one determines the probability \( P(\vec{r}, t|\vec{r}_0^{(0)}, 0) \) from equation (4). One then obtains \( P(\vec{r}, t|\vec{r}_0, 0) \) by integrating over all values of \( \{ X_p(t) \} \)\s that correspond to the position \( \vec{r} \) of the tagged monomer at time \( t \), taking into account the equilibrium distribution of the \( \{ X_p^{(0)} \} \)\s. With the tagged monomer being the middle monomer, this calculation, demonstrating equation (3) for phantom Rouse, Zimm, polymers in a \( \theta \)-solvent, and reptation are detailed in appendix A: therein it is seen that (cf equations (A.13)–(A.17))
\[
\Delta(t) \sim \int_0^\infty dp/k_p (1 - e^{-t/\tau_p}),
\]
i.e. the exponent of \( \Delta(t) \) in time is determined by the integral in equation (5). The corresponding scalings of \( \Delta(t) \) are summarized in table 2. Further, based on [19], I note that one can construct an effective equation (4) also for self-avoiding polymers, with \( p \)-independent \( \gamma_0 \) and \( \gamma_{p \neq 0} \), and \( p \sim p_{l+2}^{*2} \).

The corresponding scaling behavior for \( \Delta(t) \), also calculated in appendix A, is listed in table 2, and is verified by simulations in figure 1.

It is interesting to note here that the mode expansion technique to establish equation (3) for the systems of table 1 implies that equation (3) is a simple consequence of the physical connectivity of the polymer chain.

The expansion of the monomer co-ordinates into polymer’s fluctuation modes also provides an insight into how, given the GLE (1) and (2), one may expect \( P(\mathbf{r}, t|\mathbf{r}_0, 0) \) to be Gaussian. For example, consider an ensemble \( \mathcal{E} \) of polymers, at equilibrium at \( t = 0 \), with a given velocity history of the middle monomer between times 0 and \( t \). For this ensemble, if \( [\mathbf{g}(t) + \mathbf{f}(t)] \) can be shown to be Gaussian, then the displacements of the middle monomer in an infinitesimal time between \( t \) and \( (t + dt) \) is Gaussian distributed about the mean \( -\gamma^{-1} \int_0^t dt' \mu(t - t') \mathbf{v}(t') \), since \( \mathbf{v}(t) \) is proportional to \( [\mathbf{g}(t) + \mathbf{f}(t)] \). Such (infinitesimal) Gaussian displacements, accumulated over time, would then mean that \( P(\mathbf{r}_\sigma, t|\mathbf{r}_0, 0) \) has to be Gaussian.

In order to mathematically appreciate the Gaussian behavior of \( [\mathbf{g}(t) + \mathbf{f}(t)] \), one needs to recall the physics behind the anomalous dynamics for these systems [16, 17]: a move of the middle monomer creates a local strain by altering the polymer’s chain tension locally (equation (1)). In response to this strain, in subsequent times there is an enhanced chance, for the monomer, to undo the move (equation (2)). This physics is best represented by discretizing the movement of the middle monomer in time for the ensemble \( \mathcal{E} \) [17], e.g., \( v(t) = \sum_m \delta r_m \delta(t - t_i) \) for some \( m \), and \( t_0 = 0 \) by choice. In between these moves the middle monomer remains stationary, i.e., the dynamics of the polymer is given by those of the mode amplitudes \( \{\mathbf{Y}_p(t)s\} \), with the monomer locations \( \mathbf{r}_h(t) \) relative to the middle monomer expressed as \( \mathbf{r}_h(t) = 4 \sum_p \mathbf{Y}_p(t) \sin \frac{\pi (2p + 1)}{N} t \tau_{2p+1} \Theta(n - N/2) - 4 \sum_p \mathbf{Y}_p(t) \sin \frac{\pi (2p + 1)}{N} t \tau_{2p+1} \Theta(N/2 - n) \) for \( p = 0, 1, 2, \ldots \) (the superscripts for \( \mathbf{Y} \) correspond to the right and the left halves of the polymer). The \( \{\mathbf{Y}_p(t)s\} \)s are obtained from \( \{\mathbf{r}_h(t)s\} \)s via the inverse sine transform, and are readily shown to satisfy the boundary condition that the chain tension vanishes at the open ends of the polymer. Through this formulation, the polymer’s chain tension at the middle monomer, expressed in terms of the \( \{\mathbf{Y}_p(t)s\} \), changes discretely at \( \{t_i\} \), while in between, the relaxation of the chain tension gives rise to the memory kernel of equation (1). To work this out for all systems of table 1, one needs to re-perform, as applicable, the pre-averaging approximation in terms of the \( \{\mathbf{Y}_p(t)s\} \), which is a cumbersome task. For the sake of simplicity, I therefore only consider the phantom Rouse case here. For this system, in times \( t_i < t < t_{i+1} \), the \( \{\mathbf{Y}_p(t)s\} \)s for each half independently obey the LE [17]

\[
\gamma_p \frac{\partial \mathbf{Y}_p}{\partial t} = -q_p \mathbf{Y}_p(t) + \mathbf{\bar{h}}_p(t),
\]

with \( q_p = 2N\gamma_p, q_p = 6\sigma^2 k_B T(2p + 1)^2/N, \tau_{2p+1} = \gamma_p/q_p, \), \( \{\mathbf{h}_p(t)\} = \gamma_p k_B T \delta(t - t_i) \bar{\delta}_{p2} \). Then \( \mathbf{g}(t) \) in equations (1) and (2) is given by (see equation (19) of [17])

\[
\mathbf{g}(t) = 4 \sum_p \frac{\pi (2p + 1)}{N} \left\{ e^{-t/\tau_{2p+1}} \left[ \mathbf{\bar{Y}}_p(t) (0^+) + \mathbf{\bar{Y}}_p(t) (0^-) \right] + \frac{1}{\gamma_p} \int_0^t dt' e^{-(t-t')/\tau_{2p+1}} \left[ \mathbf{\bar{h}}_p(t')(t') + \mathbf{\bar{h}}_p(t')(t') \right] \right\}.
\]

With \( \mathbf{f}(t), \{\mathbf{h}_p(t)s\}, \{\mathbf{Y}_p(0^+)s\} \)s being Gaussian distributed with zero mean (from equations (2) and (7)), \( [\mathbf{g}(t) + \mathbf{f}(t)] \) also has to be Gaussian.

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Table 2. Systems of table 1 and their \( \Delta(t) \)-behavior. Note that the scaling exponent of \( \Delta(t) \) with time, in each case, is given by \( 2\xi/\kappa \), as noted in the first paragraph of the paper.

| System                  | \( \Delta(t) \)                           |
|------------------------|-------------------------------------------|
| Phantom Rouse          | \( \sim t^{1/3} \) until \( t \) and \( \sim t \) thereafter |
| Zimm (phantom) and polymer in a \( \theta \)-solvent | \( \sim t^{1/3} \) until \( t \) and \( \sim t \) thereafter |
| Zimm (self-avoiding)   | \( \sim t^{1/3} \) until \( t \) and \( \sim t \) thereafter |
| Repetition (curvilinear co-ordinate) | \( \sim t^{1/3} \) until \( t \) and \( \sim t \) thereafter |
| Self-avoiding Rouse    | \( \sim t^{1/2} \) until \( t \) and \( \sim t \) thereafter |

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Figure 1. Equation (3) for self-avoiding Rouse polymers (\( N = 400 \)): model details can be found in appendix B. Left: second moment \( m_2(t) = \sum_{(r)} [(r(t) - r(0))^2]^{1/2} \) of the distribution (3), scales as \( t^{1/2} \sim \tau \) until \( t \), and \( \sim t \) thereafter. Right: \( m_2(t) \) against \( m_2(t) = \sum_{(r)} [(r(t) - r(0))^2]^{1/2} \). Solid (red) line passing through the data points: \( m_2(t) = [m_2(t)/3]^{1/2} \)--note that \( m_2(t) = 3[m_2(t)/3]^{2} \) for a Gaussian distribution. Data obtained from a time-series of 200 000 consecutive snapshots, separated by 400 time units each, of 256 different polymers.
Thus, to summarize so far, having expanded the monomer co-ordinates in polymer’s fluctuation modes, I have shown that $P(\vec{r}, t|\vec{r}_0, 0)$ for phantom Rouse, Zimm, polymers in a $\theta$-solvent, reptation and self-avoiding Rouse is Gaussian; and have illustrated, for the specific case of phantom Rouse, that Gaussianity of $P(\vec{r}, t|\vec{r}_0, 0)$ is expected from the GLE (1) and (2) since the noise term $\{\dot{\vec{g}}(t) + \dot{f}(t)\}$ is Gaussian. Unfortunately however, the mode expansion does not work as simply for translocation (for which, the tagged monomer is in the one within the pore at time $t$, i.e. it does not even have a fixed index) nor for polymer melt. Neither can Gaussianity of $\{\dot{\vec{g}}(t) + \dot{f}(t)\}$ be shown, and therefore, one has to rely on computer simulations. The data for the melt are presented in figure 2(a): simulations are performed at overall monomer density unity; the simulation details, the same as those of [17] where the GLE has been shown to describe the dynamics of the middle monomer of a tagged polymer in the entangled regime, can be found in appendix B. Following reptation theory for polymer melts, one expects the second moment $m_2(t)$ to behave $\sim t^{1/4}$ in the entangled regime, which starts around time $\sim 10^5$ for this model; in this regime an effective exponent 0.27 is found (the solid (red) line passing through the data points in the left graph). While the right graph is consistent with equation (3) in the entangled regime, between the entangled regime and the eventual diffusive regime, $P(\vec{r}, t|\vec{r}_0, 0)$ does deviate very slightly, and systematically, from (3), indicating that the noise term $\{\dot{\vec{g}}(t) + \dot{f}(t)\}$ is not Gaussian during this time.

The data for unbiased translocation are presented in figure 2(b) (see model details in appendix B). The monomer number within the pore at time $t$ is denoted by $s(t)$. Polymers are equilibrated with $s(0) = N/2$. Here $m_2(t) \sim t^{1/(4(1+2\nu))} \approx t^{0.75}$, and should cross over to diffusive behavior, as predicted in [20], although the crossover is slow: at long times polymers start disengaging from the pore, corresponding to the flattening of $m_2(t)$ (the turquoise points in the left graph), hence the true diffusive behavior can only be observed for very long polymers. Nevertheless, equation (3) is verified cleanly up to the point when all polymers remain threaded in the pore: this behavior is in agreement with [13, 14] (albeit they report an anomalous exponent different from $1/(1+\nu)/(1+2\nu)$), and contradicts [12], reaffirming that fFPE is not applicable for polymer translocation.

Finally, I note that the drift of a tagged monomer due to a weak external force $\vec{F}$ (i.e. in the linear response regime), is given by $e^\alpha \vec{F}$ until time $\tau$ and $\vec{F}$ thereafter, where $\alpha$ is the anomalous exponent. Describing this requires a simple extension of equation (3).

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Appendix A. Derivation of equation (3) for the middle monomer for phantom Rouse, Zimm, polymers in a $\theta$-solvent, reptation, and self-avoiding Rouse polymers

I tag the middle monomer of the polymer, and here I obtain equation (3) for its dynamics.

I start with the Langevin equation (3) describing the evolution of the $p$th mode amplitude ($p = 0, 1, 2, \ldots$), namely,

$$\gamma_p \frac{X_{pq}(t)}{\dot{\theta}_t} = -k_p \Theta_{pq}(t) + \phi_p(t),$$

(A.1)

with $\langle \phi_{pq} \rangle = 0$ and the FDT $\langle \phi_p(t) \phi_p(t') \rangle = 2\gamma_p k_B T \delta(t - t') \gamma_p \delta_{pq}$. As noted in table 1, equation (A.1) can be derived for phantom Rouse, Zimm, polymers in a $\theta$-solvent and reptation. A straightforward result that follows from equation (A.1) is that

$$\langle X_{pq}(t)X_{pq}(t') \rangle = \delta_{pq} \gamma_p (k_B T/k_p) e^{-k_p \gamma_p |t-t'|/\gamma_p},$$

(A.2)
where $\tau_p$ is the relaxation time of the $p$th mode ($p \neq 0$) for the polymer. When equation (A.2) is combined with the corresponding time correlation function for mode amplitudes for self-avoiding polymers [19], namely $\langle \tilde{X}_p(t) \cdot \tilde{X}_q(t') \rangle \propto N^{2p} p^{-(1+2q)} e^{-t/\tau_p}$, one can formulate an effective equation (4) with both $\gamma_p$ and $\gamma_{p\neq0}$ independent of $p$, and $k_p \sim p^{-(1+2q)}$ (this implies that for a self-avoiding polymer $\tau_p \sim (N/p)^{1+2q}$). Given this, I will henceforth use equation (A.1) also for self-avoiding Rouse polymers.

The Fokker–Planck equation for the probability $P(X_{po}, t)$ that corresponds to the LE is given by [22]

$$\frac{\partial P(X_{po}, t)}{\partial t} = \frac{k_p}{\gamma_p} \frac{\partial}{\partial X_{po}} [X_{po} P(X_{po}, t)]$$

$$+ \frac{k_B T}{\gamma_p} \frac{\partial^2 P(X_{po}, t)}{\partial X_{po}^2},$$

(A.3)

where $a_p = k_B T / k_p$ for $p \neq 0$, and $a_0 = k_B T / \gamma_0$.

The solution of equation (A.3), with the initial condition that $P(X_{po}, 0) = \delta(X_{po} - X_{po}^0)$, is obtained as follows.

(i) For $p = 0$, $k_p = 0$ i.e., (A.3) is a simple diffusion equation. Its solution is given by [21]

$$P(X_{po}, t) = \frac{1}{\sqrt{2\pi a_{0} t}} \exp \left[ - \frac{(X_{po} - X_{po}^0)^2}{2a_{0} t} \right].$$

(A.4)

(ii) For $p \neq 0$, equation (A.3) can be verified by direct substitution of its solution

$$P(X_{po}, t) = \frac{1}{\sqrt{2\pi a_{p}(1 - e^{-2t/\tau_p})}}$$

$$\times \exp \left[ - \frac{(X_{po} - X_{po}^0 e^{-t/\tau_p})^2}{2a_{p}(1 - e^{-2t/\tau_p})} \right].$$

(A.5)

Next, as noted above equation (4), in terms of the mode amplitudes, the location of the middle monomer ($n = N/2$) at any time $t$ is given by

$$\bar{r}(t) = \tilde{X}_0(t) + 2 \sum_{p=1}^{N/2} \tilde{X}_p(t) \cos \frac{p\pi}{2}.$$ 

(A.6)

Using equation (A.6), I obtain, upon averaging over all possible initial states of the polymer at $t = 0$,

$$P(r_\sigma, t|r_{0\sigma}, 0) = \prod_{p=0}^{\infty} \int_{-\infty}^{\infty} dX_{po}^0 P_{eq}(X_{po}^0)$$

$$\times \delta \left[ r_{0\sigma} - \left( X_{po}^0 + 2 \sum_{q=1}^{\infty} X_{po}^0 \cos \frac{q\pi}{2} \right) \right]$$

$$\times \int_{-\infty}^{\infty} dX_{po} P(X_{po}, t)$$

$$\times \delta \left[ r_\sigma - \left( X_{po} + 2 \sum_{q=1}^{\infty} X_{po} \cos \frac{q\pi}{2} \right) \right].$$

(A.7)

where $P_{eq}(X)$ is the equilibrium probability of $X$, i.e. a Gaussian, obtained by taking $t \to \infty$ limit of equation (A.5).

At this stage, because of the $\delta$-functions in equation (A.7), it is easiest to Fourier transform $P(r_\sigma, t|r_{0\sigma}, 0)$, defined as

$$\tilde{P}_{k, k':t} = \frac{1}{2\pi} \int d\sigma \, dE_{0\sigma} \, e^{i(kr_\sigma + k' r_{0\sigma})} \int_{-\infty}^{\infty} dX_{po} P_{eq}(X_{po})$$

$$\times e^{-i(kr_\sigma + k' r_{0\sigma})} \tilde{P}_{k, k':t} = \int_{-\infty}^{\infty} dX_{po} P(X_{po}, t) e^{-ik(r_\sigma + k' r_{0\sigma})} \cos \frac{q\pi}{2}.$$ 

(A.8)

which reduces equation (A.7) to

$$2\pi e^{-i(kr_\sigma + k' r_{0\sigma})} \tilde{P}_{k, k':t} = \prod_{p=0}^{\infty} \int_{-\infty}^{\infty} dX \, dE_{0\sigma} P_{eq}(X_{po})$$

$$\times e^{-i(kr_\sigma + k' r_{0\sigma})} \tilde{P}_{k, k':t} = \prod_{p=0}^{\infty} \int_{-\infty}^{\infty} dX \, dE_{0\sigma} P_{eq}(X_{po})$$

$$\times \int_{-\infty}^{\infty} dX_{po} P(X_{po}, t) e^{-ikr_\sigma - k' r_{0\sigma}} \cos \frac{q\pi}{2}.$$ 

At this point, in order to follow through the calculation of $\tilde{P}_{k, k':t}$, I need the two following integrals:

(i) for $p = 0$:

$$\int_{-\infty}^{\infty} dX_{po} \frac{1}{\sqrt{2\pi a_{0} t}} \exp \left[ - \frac{(X_{po} - X_{po}^0)^2}{2a_{0} t} - ik' X_{po} \right]$$

$$= e^{-iK^0 e^{-t/\tau_p} k'}. \quad \text{(A.10)}$$

(ii) for $p \neq 0$:

$$\int_{-\infty}^{\infty} dX_{po} \frac{1}{\sqrt{2\pi a_{p}(1 - e^{-2t/\tau_p})}}$$

$$\times \exp \left[ - \frac{(X_{po} - X_{po}^0 e^{-t/\tau_p})^2}{2a_{p}(1 - e^{-2t/\tau_p})} - 2ik' X_{po} \cos \frac{p\pi}{2} \right]$$

$$= e^{-2K^0 e^{-t/\tau_p} k' \cos(p\pi/2) - 2a_{p}(1 - e^{-2t/\tau_p}) k'^2 \cos(p\pi/2)}. \quad \text{(A.11)}$$

Using (i) and (ii), I now integrate over $X_{po}^0$ (i.e. the location of the center-of-mass of the polymer) with a uniform probability density measure yielding $\sqrt{2\pi} \delta(k + k')$, which leads me to

$$P(r_\sigma, t|r_{0\sigma}, 0) \propto \delta(k + k')$$

$$= e^{-2K^0 e^{-t/\tau_p} k' \cos(p\pi/2) - 2a_{p}(1 - e^{-2t/\tau_p}) k'^2 \cos(p\pi/2)}.$$

(A.12)

$P_{k, k':t} \propto \delta(k + k')$ implies that $P(r_\sigma, t|r_{0\sigma}, 0)$ is a function of $(r_\sigma - r_{0\sigma})$.

Finally, I now need to evaluate the discrete sum in the exponent of equation (A.12). Having noticed that $\cos(q\pi/2) = 0$ for odd $q$-values and $\cos^2(q\pi/2) = 1$ for even $q$-values, the sum can be converted into an integral; thereafter the inverse Fourier transform from $k$ to $(r_\sigma - r_{0\sigma})$ leads to equation (3), with the behavior of $\Delta(t)$ presented in table 2. With the corresponding scaling of $\gamma_p$, and $\tau_p = \gamma_p / k_p$ for phantom Rouse, Zimm, polymers in a theta-solvent, reptation, and self-avoiding Rouse polymers (see table 1), these integrals are listed below. Note that in equations (A.13)–(A.17) I omit constants in converting the discrete sums to integrals.
Rubinstein's reptation model [23] for a single reptating polymer, is made possible via a lattice polymer model, based on Over the past years, a highly efficient simulation approach to Appendix B. Simulation details

hops can be along the contour of the polymer, thus explicitly single monomer hops to neighboring lattice sites. These lattice site is one less than the number of monomers occupying monomers. The number of stored lengths within any given string are located either in the same, or in neighboring lattice sites. The polymers are self-avoiding: multiple occupation of lattice sites is not allowed, except for a set of adjacent monomers. The number of stored lengths within any given site is one less than the number of monomers occupying that site. The polymers move through a sequence of random single monomer hops to neighboring lattice sites. These hops can be along the contour of the polymer, thus explicitly providing reptation dynamics. They can also change the contour ‘sideways’, providing Rouse dynamics. Each kind of movement is attempted with a statistical rate of unity, which defines the unit of time. This model has been used before to simulate the diffusion and exchange of polymers in an equilibrated layer of adsorbed polymers [25], dynamics self-avoiding Rouse polymers [19], polymer translocation under a variety of circumstances [15, 20, 26], and the dynamics of polymer adsorption [27].

The same model has been used for the polymer melt simulations (here the polymers are both self- and mutually avoiding) for a system of size $60^3$ with an overall monomer density unity per lattice site. Due to the possibility that adjacent monomers belonging to the same polymer can occupy the same site, overall approximately 40% of the sites typically remain empty.

Initial thermalizations were performed as follows. Completely crumpled up polymers are placed in lattice sites at random. The system is then brought to equilibrium by letting it evolve up to $10^6$ units of time, with a combination of random intermediate redistribution of stored lengths within each polymer. Additional details on the melt simulations can be found in [17].

Appendix B. Simulation details

Over the past years, a highly efficient simulation approach to polymer dynamics has been developed in our group. This is made possible via a lattice polymer model, based on Rubinstein’s reptation model [23] for a single reptating polymer, with the addition of sideways moves (Rouse dynamics). A detailed description of this model, its computationally efficient implementation and a study of some of its properties and applications can be found in [24].

In this model, each polymer is represented by a sequential string of monomers, living on a face-centered-cubic lattice with periodic boundary conditions in all three spatial directions. Hydrodynamic interactions between the monomers are not taken into account in this model. Monomers adjacent in the string are located either in the same, or in neighboring lattice sites. The polymers are self-avoiding: multiple occupation of lattice sites is not allowed, except for a set of adjacent monomers. The number of stored lengths within any given lattice site is one less than the number of monomers occupying that site. The polymers move through a sequence of random single monomer hops to neighboring lattice sites. These hops can be along the contour of the polymer, thus explicitly providing reptation dynamics. They can also change the contour ‘sideways’, providing Rouse dynamics. Each kind of movement is attempted with a statistical rate of unity, which defines the unit of time. This model has been used before to simulate the diffusion and exchange of polymers in an equilibrated layer of adsorbed polymers [25], dynamics self-avoiding Rouse polymers [19], polymer translocation under a variety of circumstances [15, 20, 26], and the dynamics of polymer adsorption [27].

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