Classification of shift-symmetric Horndeski theories and hairy black holes

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No-hair theorems for scalar-tensor theories imply that the trivial scalar field configuration is the unique configuration around stationary black hole spacetimes. The most basic assumption in these theorems is that a constant scalar configuration is actually admissible. In this paper, we classify shift-symmetric Horndeski theories according to whether or not they admit the trivial scalar configuration as a solution and under which conditions. Local Lorentz symmetry and the presence of a linear coupling between the scalar field and Gauss-Bonnet invariant plays feature prominently in this classification. We then use the classification to show that any theory without linear Gauss-Bonnet coupling that respects local Lorentz symmetry admits all solutions of general relativity. We also study the scalar hair configuration around black hole spacetimes in theories where the linear Gauss-Bonnet coupling is present. We show that the scalar hair of the configuration is secondary, fixed by the regularity of the horizon, and is determined by the black hole horizon properties.

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I. INTRODUCTION

After more than 100 years since its introduction, general relativity (GR) is still the most successful theory describing gravitational interactions. Despite its mathematical simplicity and consistency with observations, many alternative theories have been proposed with motivations ranging from quantum gravity, cosmology and resolving dark matter and energy to testing Lorentz violation in the gravity sector. Any modification to GR (in $3 + 1$ dimensions), by Lovelock’s theorem [1,2], introduces new degrees of freedom. In this regard, scalar-tensor theories, which possess an additional scalar field, are perhaps the simplest alternatives to GR.

The new scalar degree of freedom could lead to intriguing phenomenology in black hole spacetimes. No-hair theorems [3–10] seem to suggest the opposite. They imply that, under certain assumptions regarding symmetries and asymptotics, the trivial configuration (vanishing scalar field) is the unique acceptable configuration in a black hole spacetime. However, no-hair theorems can be circumvented by relaxing these assumptions—notably allowing the scalar to be nonstationary—or by exploiting instabilities. This has lead to various scenarios for long-lived scalar hair [10–18].

Perhaps the most obvious way to find theories for which black holes have hair is to violate the most basic assumption of no-hair theorems: that a trivial configuration for the scalar is admissible in the first place for black hole spacetimes. Indeed, in Ref. [7] it was shown that static, spherically symmetric and asymptotically flat black holes cannot have hair in shift-symmetric scalar-tensor theories. Shift symmetry implies invariance under the transformation $\phi \to \phi + \text{const}$ and it can be thought of as the symmetry that prevents the scalar to acquire a mass from quantum corrections. Subsequently, it was pointed out in Ref. [8] that a linear coupling between a scalar and the Gauss-Bonnet invariant respects shift symmetry and at the same time leads to a contribution to the scalar’s field equation that depends only on the Gauss-Bonnet invariant.\textsuperscript{1} The latter does not vanish in black hole spacetimes; it sources the scalar and makes a constant scalar configuration inadmissible. It was further shown there that this is the only coupling term with this property, which at the same time allows for a constant scalar configuration in flat space (the Gauss-Bonnet invariant vanished). The latter is a requirement if one wants the theory to respect local Lorentz symmetry (LLS). The gradient of the scalar field $\nabla_a \phi$ picks a preferred direction at any point in spacetime. Hence, having a nontrivial gradient in flat space is a violation of LLS.

Let us now consider the implications of the results in Ref. [8] in terms of the shift-symmetric (SS) Horndeski theory [21–23]. This is the most general shift-symmetric scalar-tensor theory which leads to a second-order equation

\textsuperscript{1}Beyond the confines of shift symmetry, it was well known that a coupling between the scalar and the Gauss-Bonnet invariant leads to black hole hair [19,20].
of motion upon variation. The Lagrangian of the theory reads

\[ \mathcal{L} = \mathcal{L}_2 + \mathcal{L}_3 + \mathcal{L}_4 + \mathcal{L}_5, \]  

(1)

where

\[ \mathcal{L}_2 = G_2, \]

(2)

\[ \mathcal{L}_3 = -G_3 \Box \phi, \]

(3)

\[ \mathcal{L}_4 = G_4 R + G_{4X} [(\Box \phi)^2 - (\nabla_a \phi \nabla_b \phi)^2], \]

(4)

\[ \mathcal{L}_5 = G_5 G_{ab} \nabla^a \nabla^b \phi \]

(5)

\[ -\frac{1}{6} G_{5X} [(\Box \phi)^3 - 3 \Box \phi (\nabla_a \nabla_b \phi)^2 + 2 (\nabla_a \nabla_b \phi)^3], \]

(6)

\[ X = -\frac{1}{2} \nabla_a \phi \nabla^a \phi \text{ and } G_{ix} = \partial X G_i. \]  

These theories admit \( \phi = 0 \) solutions for the scalar and hence all of the solutions of GR.

Class 2.—SS Horndeski theories which are not in class 1 but satisfying

\[ \lim_{g \to 0} \mathcal{E}_\phi[\phi = 0, g] = 0, \]

(10)

where \( \eta_{ab} \) is the Minkowski metric. These theories do not admit \( \phi = 0 \) solutions and hence they do not share GR solutions in general. However, they have Minkowski spacetime as a solution, and this solution is smoothly connected to other solutions.

Following the discussion in the introduction regarding Lorentz symmetry, theories in classes 1 and 2 respect LLS, while class 3 theories are Lorentz violating. Before ending this section, let us mention an important result regarding the scalar field equation of motion which we use extensively in the following sections. By virtue of shift symmetry, the theory acquires a Noether's current \( J^a \) associated to the shift symmetry which is given explicitly by

\[ J^a = G_2 X J^a_{(2,1)} + G_{3X} J^a_{(3,1)} + G_{4X} J^a_{(4,1)} + G_{4XX} J^a_{(4,2)} + G_{5X} J^a_{(5,1)} + G_{5XX} J^a_{(5,2)}, \]

(11)

where

\[ J^a_{(2,1)} = -\nabla^a \phi \]

(12)

\[ J^a_{(3,1)} = \nabla^a \phi \Box \phi - \nabla^a \nabla^b \phi \nabla_b \phi, \]

(13)
This is to ensure that the solution. In order to make use of the scaling properties in the GR branch is dynamically disconnected from any other smoothly. In other words, we disregard theories in which the equation of motion for the scalar field can be thought of as the conservation of the Noether’s current, namely

\[
\mathcal{E}_\phi[\phi, g] = -\nabla_a J^a. \tag{18}
\]

Inspecting carefully the terms in the current shows that they have a specific scaling dimension with \( \phi, J^a_\phi/|\phi| = \beta^a J^a_\phi[\phi] \), where

\[
\begin{align*}
  n_{(2,1)} &= 1, & n_{(3,1)} &= 2, \\
  n_{(4,1)} &= 1, & n_{(4,2)} &= 3, \\
  n_{(5,1)} &= 2, & n_{(5,2)} &= 4. \tag{19}
\end{align*}
\]

We will use this scaling property in the next sections.

### A. Class 1: Theories with GR solutions

In this section, we derive the conditions on the \( G_i \)’s for a theory to be in class 1. We impose the defining condition of the class as follows:

\[
0 = \mathcal{E}_\phi[\phi = 0, g] = \lim_{\epsilon \to 0} \mathcal{E}_\phi[\epsilon \hat{\phi}, g] \quad \forall \ g, \tag{20}
\]

where \( \hat{\phi} \) can be any differentiable field configuration. This is to ensure that the \( \phi = 0 \) solution can be reached smoothly. In other words, we disregard theories in which the GR branch is dynamically disconnected from any other solution. In order to make use of the scaling properties in Eq. (19), we define the following functions:

\[
\begin{align*}
  F_{(2,1)}(X) &= |X|^{1/2}G_{2X}, & F_{(3,1)}(X) &= XG_{3X}, \\
  F_{(4,1)}(X) &= |X|^{1/2}G_{4X}, & F_{(4,2)}(X) &= |X|^{3/2}G_{4XX}, \\
  F_{(5,1)}(X) &= XG_{3X}, & F_{(5,2)}(X) &= X^2G_{5XX} \tag{21}
\end{align*}
\]

and currents

\[
\begin{align*}
  J^a_{(4,1)} &= 2G^{ab}\nabla_b \phi, & J^a_{(4,2)} &= |X|^{-1/2}J^a_{(4,1)}, \quad J^a_{(5,1)} &= X^{-1}J^a_{(5,1)}, \\
  J^a_{(5,2)} &= X^{-2}J^a_{(5,2)} \tag{22}
\end{align*}
\]

and rewrite the Noether’s current as

\[
\begin{align*}
  J^a &= F_{(2,1)}J^a_{(2,1)} + F_{(3,1)}J^a_{(3,1)} \\
  &= F_{(4,1)}J^a_{(4,1)} + F_{(4,2)}J^a_{(4,2)}, & J^a(5,1) &= F_{(5,1)}J^a_{(5,1)} + F_{(5,2)}J^a_{(5,2)}. \tag{23}
\end{align*}
\]

The scalings are designed such that the new currents \( J^a \)’s are scale invariant \( j^a_\epsilon[\epsilon \hat{\phi}, g] = j^a_\epsilon [\hat{\phi}, g] ; \) the \( \epsilon \) dependence is now encoded in \( F_i \). In particular, the behavior of \( F_i(X) \) close to \( X = 0 \) is crucial for \( \epsilon \to 0 \) limit. If \( F_i \) functions are such that \( F_i(X = 0) = 0 \), then the current \( J^a \) vanishes as \( \epsilon \to 0 \). Thus the equation of motion is satisfied. As a result, \( F_i(X = 0) = 0 \) are sufficient conditions for a theory to belong to class 1. In what follows, we show that \( F_i(X = 0) = 0 \) are necessary as well.

According to our definition, a theory is in class 1 if for all spacetime metrics \( g_{ab} \)

\[
\lim_{\epsilon \to 0} \mathcal{E}_\phi[\epsilon \hat{\phi}, g] = 0. \tag{24}
\]

Let us restrict ourselves to static spherically symmetric field configuration \( \hat{\phi} \) and metric and choose the metric to be infinitesimally close to the flat metric:

\[
g_{ab}dx^a dx^b = -(1 + \epsilon_1 h(r))dt^2 + \frac{dr^2}{1 + \epsilon_2 f(r)} + r^2 d\Omega^2. \tag{25}
\]

where \( \epsilon_1 \) and \( \epsilon_2 \) are small numbers. With staticity, spherical symmetry and smoothness at the center, the scalar field equation of motion reduces to \( J^a = 0 \); thus, we require

\[
\lim_{\epsilon \to 0} J^a[\epsilon \hat{\phi}, g] = 0. \tag{26}
\]

Imposing the above to hold in any order of \( \epsilon_1 \) and \( \epsilon_2 \), we get at \( X = 0 \)

\[
\epsilon_1^0 \epsilon_2^0 \text{ order: } F_{(2,1)} = F_{(3,1)} = F_{(4,2)} = 0, \tag{27}
\]

\( \epsilon_1 \) and \( \epsilon_2 \) order: \( F_{(4,1)} = 0, F_{(5,1)} = -F_{(5,2)}, \tag{28} \)

\( \epsilon_1 \epsilon_2 \) order: \( 5F_{(5,1)} + 4F_{(5,2)} = 0. \tag{29} \)

The combination of the above conditions yields

\[
F_i(X = 0) = 0. \tag{30}
\]
Equation (30) is derived by restricting the metric to be static, spherically symmetric and close to flat spacetime; thus, it constitutes a set of necessary conditions for Eq. (20) to hold. Combining this with the previous result, we have shown that $F_i(X = 0) = 0$ is a set of necessary and sufficient conditions for a theory to be in class 1. In particular, this means that Eq. (26) is satisfied to all orders in $e_1$ and $e_2$.

On a final note we should mention that all $F_i(X = 0)$, if not divergent, are not independent since they are related through their definitions as derivatives of $G_i$ functions. In particular,

$$F_{(4,2)}(X = 0) = -\frac{1}{2} F_{(4,1)}(X = 0),$$
$$F_{(5,1)}(X = 0) = -F_{(5,2)}(X = 0). \quad (31)$$

### B. Class 2: Theories with Minkowski solution

So far, we have focused on theories which admit $\phi = 0$ as a solution on any background spacetime metric. Now, we turn our attention to class 2 theories which do not satisfy this property and only admit the trivial solution on a flat spacetime.

In the definition of class 2 in Eq. (10), we require the limit $g_{ab} \to \eta_{ab}$ to exclude theories that have $\phi = 0$ solution on flat spacetime when this solution cannot be reached smoothly. Intuitively, Eq. (10) requires that, starting from a perturbed flat metric and then damping the perturbations, there is always a solution to the scalar field equation of motion which is continuously connected to $\phi = 0$.

Considering a static spherically symmetric metric and taking the limit to the flat metric in Eq. (10), similar to our argument in the previous section, we get the following necessary conditions at $X = 0$:

$$F_{(2,1)} = F_{(3,1)} = F_{(4,2)} = 0,$$
$$F_{(4,1)}, F_{(5,1)}, \text{ and } F_{(5,2)} \text{ are finite and at least one nonzero.} \quad (32)$$

As we mentioned earlier, the values of $F_i$’s at $X = 0$ are not all independent. In fact, using Eq. (31) yields

$$F_{(4,1)}(X = 0) = 0,$$
$$F_{(5,1)}(X = 0) = -F_{(5,2)}(X = 0) \neq 0. \quad (33)$$

As a result, the only nonzero values among $F_i(X = 0)$ are the ones coming from $G_5$.

In the derivation above, we have only considered the limit to the flat metric through spherical perturbations; hence, the above constitute a set of necessary conditions at this point. In the next section, we show that they are also sufficient condition for class 2. Moreover, we discuss how class 2 and class 1 theories are related.

### C. Relation between class 1 and 2

Let us consider a class 2 theory with Lagrangian $\mathcal{L}$. By the argument in the previous section, we know Eqs. (32) and (33) must hold.

Now let us define

$$F_{(5,1)}(X) = c + \tilde{F}(X), \quad (34)$$

where $c = F_{(5,1)}(X = 0)$; thus, $\tilde{F}(X = 0) = 0$. Using the definition of $F_{(5,1)}$ in terms of $G_5$, this gives

$$G_5 = c \ln |X| + \int X \tilde{F}(X') \frac{dX'}{X'} = c \ln |X| + \tilde{G}_5, \quad (35)$$

where

$$\tilde{G}_5 = \int X \tilde{F}(X') \frac{dX'}{X'}, \quad (36)$$

satisfying $X G_{5X} = 0$ at $X = 0$.

By substituting $G_5$ from Eq. (35) in Lagrangian $\mathcal{L}$, the $\ln |X|$ contribution turns into a linear Gauss-Bonnet coupling term, and we get

$$\mathcal{L} = \tilde{\mathcal{L}} - \frac{c}{4} \phi \mathcal{G}, \quad (37)$$

where $\tilde{\mathcal{L}}$ is a Lagrangian with $G_5$ in $\mathcal{L}$ replaced by $\tilde{G}_5$.

Note that $\tilde{\mathcal{L}}$ satisfies Eq. (30) and, thus, it belongs to class 1. Consequently, we have proven that the Lagrangian of any class 2 theory is a linear Gauss-Bonnet coupling plus a class 1 theory Lagrangian.

This result further proves that Eqs. (32) and (33) are sufficient conditions for class 2 condition Eq. (10). In order to see this, consider the equation of motion derived from Eq. (37) which reads

$$\mathcal{E}_\phi[\phi, g] = \tilde{\mathcal{E}}_\phi[\phi, g] - \frac{c}{4} \mathcal{G}, \quad (38)$$

$\tilde{\mathcal{E}}_\phi$ is the equation of motion derived from $\tilde{\mathcal{L}}$ and satisfies $\tilde{\mathcal{E}}_\phi[\phi = 0, g] = 0$, as it belongs to class 1. As a result,

$$\mathcal{E}_\phi[\phi = 0, g] = -\frac{c}{4} \mathcal{G}, \quad (39)$$

which clearly satisfies Eq. (10).

### III. Black Hole Solutions of Class 2

So far, we have been working out the classification of SS Horndeski theories, and we have shown that class 2 theories

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2 Note that Lagrangian $\tilde{\mathcal{L}}$ is linear in terms of $G_i$’s.
are closely related to the ones in class 1. The scalar field for class 2 theories must have a nontrivial configuration on curved spacetimes, and this means that their black hole solutions must have hair (this generalizes the logic of Ref. [8] to all theories in class 2). We study the behavior of the scalar hair in black hole spacetimes for class 2 theories in this section.

It has been shown that for a canonical massless scalar field with linear Gauss-Bonnet coupling [corresponding to $\mathcal{L} = X$ in Eq. (37)], the scalar hair of the black hole is secondary for stationary axisymmetric [26] (static, spherically symmetric [27,28]) black holes. In this section, we generalize this result to a wider class of theories with linear Gauss-Bonnet coupling.

The first case that we consider is a static, spherically symmetric spacetime and scalar field. The advantage in this case is that we do not put any restriction on the theory and asymptotics of the black hole. The proof applies to all class 1 and class 2 theories, i.e., to all non-Lorentz breaking theories.

Then, we consider the case of a stationary, asymptotically flat black hole spacetime and stationary scalar field, without assuming extra spacetime symmetries. In this case, we assume that the dominant contribution to the kinetic term of the Lagrangian in the weak field limit is the canonical kinetic term. Essentially, this means that all corrections to the canonical kinetic term are higher-order field contributions, that are relevant when the scalar field is strong. Let us place this condition in the context of a class 2 theory with Lagrangian $\mathcal{L}$. As we have shown, $\mathcal{L}$ can be expressed as

$$\mathcal{L} = \tilde{\mathcal{L}} + \alpha \phi \mathcal{G},$$

(40)

where $\tilde{\mathcal{L}}$ (with $\tilde{\mathcal{G}}$ functions) is in class 1 and $\alpha \neq 0$. Hence, our condition regarding the weak field dominance of the canonical kinetic term implies that the dominant term to the Noether’s current $J^\alpha$ (of $\tilde{\mathcal{L}}$) at infinity is $-\nabla^\alpha \phi$. Finally, we assume (for technical reasons of the proof) that the surface gravity of the Killing horizon is constant.

In both cases discussed above, and with the assumptions listed, we prove that the scalar charge is secondary.

### A. Spherical black holes

Consider a static spherically symmetric black hole with the following metric:

$$g_{ab}dx^a dx^b = -h(r) dt^2 + \frac{dr^2}{f(r)} + r^2 d\Omega^2,$$

(41)

and a horizon at $r = r_H$ given by $f(r_H) = h(r_H) = 0$. For a static spherically symmetric spacetime

$$\mathcal{G} = \nabla_a \mathcal{G}^a, \quad \mathcal{G}^a = (0, \mathcal{G}^r, 0, 0), \quad \mathcal{G}^r = \frac{4(f - 1) f h'}{r^2 h}. \quad (42)$$

$J^a = \tilde{J}^a - \alpha \mathcal{G}^a$ satisfies the symmetries of the spacetime. Hence the only nontrivial component of $J^a$ in the coordinates defined by Eq. (41) is $J^r$. Explicitly solving $\nabla_a J^a = 0$, we get

$$J^r = C \frac{f}{r^2 \sqrt{h}}. \quad (43)$$

where $C$ is a constant. Thus, we have

$$C \frac{f}{r^2 \sqrt{h}} = J^r - \alpha \frac{4(f - 1) f h'}{r^2 h}. \quad (44)$$

The explicit form of $J^r$ is given by [24]

$$J^r = -f \phi' \tilde{G}_{22} + f^2 (\phi')^2 \frac{rfh' + 4h}{2rh} \tilde{G}_{32}$$

$$+ f \phi' \frac{2hf - 2h + 2rfh'}{r^2 h} \tilde{G}_{42}$$

$$- 2f^3 (\phi')^3 \frac{rh'}{r^2 h} \tilde{G}_{44}$$

$$+ f^2 (\phi')^2 h' \frac{1 - 3f}{2r^2 h} \tilde{G}_{52} + f^4 (\phi')^4 \frac{h'}{2r^2 h} \tilde{G}_{55}. \quad (45)$$

Assuming regularity of the scalar field at the horizon, i.e., $\phi'(r_H)$ is finite, one can see that $J^r(r_H) = 0$ (in the next section, we will see the generalization of this result beyond spherical symmetry). As a result, evaluating Eq. (44) at $r = r_H$ fixes the constant $C$:

$$C = 4\alpha \sqrt{f'(r_H) h'(r_H) \text{sgn}(f'(r_H))}. \quad (46)$$

Substituting this value back in (44), we get

$$J^r = \frac{4\alpha}{r^2} \sqrt{\frac{f}{h}} \left[ f'(r_H) h'(r_H) \text{sgn}(f'(r_H)) \right. $$

$$+ (f - 1) \left. \sqrt{\frac{f}{h}} \right]. \quad (47)$$

The important fact about this equation is that the right-hand side depends only on the geometry and hence $J^r$ is completely fixed by the spacetime.

The explicit form of $J^r$ in Eq. (45) shows that it depends on the scalar field only through $\phi'$. In other words, combining Eqs. (47) and (45) yields an algebraic equation for $\phi'$ in terms of geometrical quantities. This means that the scalar field configuration is completely fixed by the geometry. Hence, the scalar hair is secondary and we have proven the desired result. Note that in the above proof we...
did not use any restriction on the theory apart from not being Lorentz violating (i.e., not belonging in class 3).

In general, Eq. (47) possesses multiple solutions for $\phi'$ even when $\alpha = 0$. Treating the $\tilde{G}_i$’s as polynomial functions in $X$, we can rearrange Eq. (47) in the following format:

$$\sum_{n=2}^{m} \alpha_n A_n(r) \phi'' - f \phi' + \alpha A_0(r) = 0,$$

(48)

where $\alpha A_0(r)$ comes from the Gauss-Bonnet term [rhs of Eq. (47)] and the $\alpha_n A_n(r)$ terms originate from $\tilde{X}$, with $n$ controlled by the choice of the $\tilde{G}_i$. We have assumed here that the canonical kinetic term is present and this gives the $f \phi'$ contribution. This polynomial equation can have multiple real roots. However, not all these roots will correspond to physically relevant solutions.

To see this, first set $\alpha_n = 0$, in which case one gets the unique (known) solution $\phi' = \alpha A_0(r)/f$. When $\alpha_n \neq 0$ this solution will receive corrections that vanish as $\alpha_n \rightarrow 0$ and the limit is smooth. More branches of solutions can also arise now, but these solutions are not expected to have a smooth limit as $\alpha_n \neq 0$ and hence they are not continuously connected with the only branch that exists for $\alpha_n = 0$. Moreover, it is not clear whether any of these new solutions will have the correct asymptotic behavior or whether they correspond to regular solutions of the whole theory (here only the scalar equation is considered). This behavior persists for $\alpha = 0$, in which case $\alpha_n = 0$ leads to the GR solution $\phi' = 0$.

It is also worth pointing out that, for a spacetime with multiple horizons, $f'(r_H)$ changes sign on successive horizons. Hence, the values of $C$ calculated on different horizons (to ensure the regularity of $\phi$) cannot match. This means that the scalar field is singular on at least one of the horizons in such a spacetime. For example, spherically symmetric black holes with de Sitter asymptotics are expected to be singular. This agrees with the results and conclusions obtained numerically in [29,30].

B. Stationary black holes

Now, let us present the proof for stationary black holes. The proof goes beyond spherical symmetry and uses only stationarity of the black hole spacetime. However, it is restricted to a subclass of theories in classes 1 and 2, as we have explained earlier.

Consider a generic stationary asymptotically flat black hole spacetime with a Killing vector $\xi^a$ and Killing horizon $\mathcal{H}$. The equation of motion from Lagrangian (40) reads

$$\nabla_a \tilde{J}^a = \alpha \nabla_a \tilde{G}^a,$$

(49)

where $\tilde{J}^a$ is the Noether’s current associated with $\tilde{L}$ and $\nabla_a \tilde{G}^a = \tilde{G}$. Integrating above in a spacetime region bounded by the Killing horizon of the black hole ($\mathcal{H}$), infinity ($\infty$) and two (partial) Cauchy hypersurfaces ($C_1$ and $C_2$), we get

$$\int_{\mathcal{H}} n_a \tilde{J}^a + \int_\infty n_a \tilde{J}^a = \alpha \int_{\mathcal{H}} n_a \tilde{G}^a + \alpha \int_{\infty} n_a \tilde{G}^a,$$

(50)

where $n_a$ is the normal to the boundary. Note that the integrals over $C_1$ and $C_2$ (by isometry) cancel each other.

On the Killing horizon $n_a = \xi_a$ and

$$\xi_a \tilde{J}^a = 0,$$

(51)

provided that the scalar field is regular, static and $\mathcal{H}$ has constant surface gravity [31]. Moreover,

$$\int_{\infty} n_a \tilde{G}^a = 0$$

(52)

for asymptotically flat spacetimes. Consequently,

$$\int_{\mathcal{H}} n_a \tilde{J}^a = \alpha \int_{\mathcal{H}} n_a \tilde{G}^a.$$  

(53)

The left-hand side of the above gives the scalar charge of the black hole. In order to see this, consider “$1/r^3$” expansion of the scalar field near infinity:

$$\phi = \frac{C}{r} + \mathcal{O}(1/r^3).$$

(54)

Substituting this expansion in the Noether’s current (and imposing asymptotic flatness), we get

$$\int_{\infty} n_a \tilde{J}^a = 4\pi C.$$  

(55)

Note that in the above the only nonvanishing contribution is from $-\nabla^a \phi$ by the restriction we imposed on the theory that the canonical kinetic terms dominates in a weak field. Substituting this back in Eq. (53) yields

$$4\pi C = \alpha \int_{\mathcal{H}} n_a \tilde{G}^a.$$  

(56)

The right-hand side of the above is a purely geometrical quantity. As a result, the scalar charge is fixed by the geometry; i.e., the scalar charge of the black hole is secondary. This generalizes the proof presented in Ref. [26] beyond axisymmetry and to a wider class of theories within SS Horndeski; the charge of the scalar field is fixed by the properties of the horizon.

Equation (56) holds for $\alpha = 0$, corresponding to class 1 theories too. In this case, we conclude that

$$C = 0.$$  

(57)
In other words, the scalar charge of a hairy solution (if exists) of class 1 theories vanishes, and the asymptotic falloff of the scalar field is faster than $1/r$.

We finish this section by the following observation. If the spacetime possesses multiple horizons, we expect Eq. (56) to hold on each horizon. As a result (if $a \neq 0$),

$$\int_{H_i} n_a G^i = \int_{H_i} n_a G^i. \tag{58}$$

This is a very restrictive condition on the spacetime geometry. In particular, the scalar field cannot remain regular if the above does not hold. As we have shown in the previous section, the above cannot hold for static spherically symmetric black holes. Equation (58) indicates that stationary black holes with multiple horizons (within theories we considered in this section) are also irregular at least on one of the horizons.

**IV. SUMMARY AND CONCLUSION**

In this paper, we have presented a classification of shift-symmetric Horndeski theories that could be useful in various applications. We argued that Horndeski theories can be split in three classes: (i) theories that admit all of the spacetimes of GR with a constant scalar configuration; (ii) theories do not belong to the previous class but that admit flat space with constant scalar; (iii) theories in which the scalar has to be nontrivial in flat space or do not admit flat space with constant scalar configuration; (iii) theories in which the scalar charge for these hairy black holes is fixed by the regularity of the horizon and is determined by the horizon properties.

Our result underscore the important role that a linear coupling between the scalar field and Gauss-Bonnet term plays for black holes and complement the earlier results of Refs. [8, 24]. This is the unique interaction term that forces a Lorentz-invariant theory within the shift-symmetric Horndeski class to have hairy black hole solutions.

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