The Traill island model for lemming dynamics, how it compares to Fennoscandian vole dynamics models, and a proposed simplification

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Abstract

The Traill island model of Gilg et al. (2003) is a landmark attempt at mechanistic modelling of the cyclic population dynamics of rodents, focusing on a high Arctic community. It models the dynamics of one prey, the collared lemming, and four predators: the stoat, the Arctic fox, the long-tailed skua and the snowy owl. In the present short note, we first summarize how the model works in light of theory on seasonally forced predator-prey systems, with a focus on the temporal dynamics of predation rates. We show notably how the impact of generalist predation, which is able here to initiate population declines, differs slightly from that of generalist predation in other mechanistic models of rodent-mustelid interactions such as Turchin & Hanski (1997). We then provide a low-dimensional approximation with a single generalist predator compartment that mimics the essential features of the Traill island model: cycle periodicity, amplitude, shape, as well as generalist-induced declines. This simpler model should be broadly applicable to model other lemming populations that predominantly grow under the snow during the winter period. Matlab computer codes for Gilg et al. (2003), its two-dimensional approximation, as well as alternative lemming population dynamics models are provided.

Keywords: lemmings, voles, population cycles, predator-prey models, tundra ecosystems
The Gilg, Hanski & Sittler (2003) model for Arctic lemmings

The predator-prey community in Gilg et al. (2003) is constituted of one prey species, the collared lemming (*Dicrostonyx groenlandicus*), and its four predators: the stoat (*Mustela erminea*), the Arctic fox (*Alopex lagopus*), the long-tailed skua (*Stercorarius longicaudus*) and the snowy owl (*Bubo scandiacus*). The basic structure of the model is that of a coupled system of nonlinear differential equations for the lemming and stoat populations (present year-round and all years), with time-varying terms. The time-varying part of the model results largely from avian and fox predation on lemmings, which happens only in the summer, in addition to a heightened intrinsic population growth of lemmings in winter. Finally, another forcing term comes from the stoat reproduction, which is modelled as a discontinuous burst, the stoat population being multiplied by $(1 + v)$ every year in the spring. The model here is slightly reformulated to make its mathematical structure more apparent. The lemming population dynamics are described by

$$\frac{dN}{dt} = r(t)N - \Gamma(N, N', t) - \frac{cN^2P}{D^2 + N^2}.$$  \hspace{1cm} (1)

For convenience, we will count time in unit of years, and define the variable $t_{\text{mod}} = t \equiv 1$, hence $t_{\text{mod}}$ is time of year between 0 and 1. A key variable is $N'$, the lemming density at snowmelt:

$$t_{\text{mod}} < t_{\text{snowmelt}}, \quad N' = N(t) \& r(t) = r_w$$

$$t_{\text{mod}} > t_{\text{snowmelt}}, \quad N' = N(t_{\text{snowmelt}}) \& r(t) = r_s$$  \hspace{1cm} (2)

$N'$ can be thought of as a perceived lemming density by generalist and nomadic predators upon their seasonal arrival to the system, that introduces a short time delay in summer in the model (decisions made by the predators are conditional to $N'$). The generalist predation term $\Gamma(N, N', t)$ is exactly zero in winter, and changes during the summer as a function of settlement and reproduction schedules of the various predators. The stoat density $P$ has dynamics of the form

$$\frac{dP}{dt} = -(d_h + \Delta(N)(d_l - d_h))P$$  \hspace{1cm} (3)

with $d_h$ the maximum stoat death rate and $d_l$ the minimum death rate, and $\Delta(N)$ a sigmoid function between 0 and 1, that makes the dynamics switch between the two mortality rates according to the formula $\Delta(N) = 1/2 + \arctan(b(N - D))/\pi$. In other words, there is a higher predator death rate when there is no food. The stoat compartment is additionally subjected to an interruption and modification of the state
variable, i.e., each year at time $t_{\text{stoat}}$ the integration stops and the predator density switches from $P$ to $P(1 + v)$ where $v$ is the number of offsprings (the youngs are assumed to be equivalents to adults).

The generalist predation rate can be decomposed into 3 separate terms corresponding to the different predators (both for adults and juveniles, the latter being counted in “adult equivalents”). It is a function of time through the predator densities:

$$
\Gamma(N, N', t) = \frac{W_f N^2 (P_f(t) + P_{yf}(t))}{D_f^2 + N(t)^2} + \frac{W_o N(t)^2 (P_o(t) + P_{yo}(t))}{D_o^2 + N(t)^2} + \frac{W_l N(t)^4 (P_l(t) + P_{yl}(t))}{D_l^4 + N(t)^4}.
$$

The numerical response of the predators (and hence, the seasonal variation in generalist predation pressure) is fully described in Table 1.

| Predator | Adults (when present) | Youths x Growth youns | Arrival date | Leaving date | Birth date |
|----------|-----------------------|-----------------------|--------------|--------------|------------|
| Fox      | $P_f = b_f N^2$       | $P_{yf}(t) = \frac{b_f N^2}{1 + e^{-0.365 (t_0 - t_{ofa})}}$ | $t_{ofa} = 0.52$ | $t_{fa} = 1.0$ | $t_{snowmelt} = 0.65$ |
| Owl      | $P_o = \frac{b_o (N' - 2)}{1 + N'}$ | $P_{yo}(t) = \frac{b_o (N' - 2)}{1 + e^{-0.365 (t_0 - t_{ofa})}}$ | $t_{ofa} = 0.52$ | $t_{ofa} = 0.94$ | $t_{birth owl} = 0.67$ |
| LT skua  | $P_l = 0.02$          | $P_{yl}(t) = \frac{b_l N^2}{1 + e^{-0.454 (t_0 - t_{ofa})}}$ | $t_{fa} = 0.62$ | $t_{la} = 0.81$ | $t_{snowmelt} = 0.72$ |

Table 1: Numerical responses of generalists. The density of adults in the first column apply only during the period between the arrival and leaving dates mentioned in the 4th and 5th columns. The density of youngs is conditional on that of the adults being positive, and will be non-zero after the birth date. $P_o = 0$ whenever $N' < 2$. Note, for comparison, that the time of stoat reproduction is $t_{\text{stoat}} = 0.69$. $t_{ofa} = \text{arrival time for the owl and fox}$, $t_{fa} = \text{arrival time for the long-tailed skua}$, $t_{ofa} = \text{arrival time for the fox}$, $t_{ofa} = \text{arrival time for the owl}$, $t_{la} = \text{leaving time for the long-tailed skua}$. 


Figure 1: **Predator abundances** over time in the Gilg et al. (2003) model for the reference parameter set with all predators present.

This seasonal and large mortality (≈ 80 to 90% of lemming individuals are eaten by skuas and owls over the summer in peak years\(^1\)) is in effect *equivalent to a very large seasonal perturbation*, mirroring theoretical results that show the oscillation-generating effects of such seasonal perturbations (Rinaldi et al., 1993; King and Schaffer, 2001; Taylor et al., 2012). Simulations of another, simplified Lemming-Stoat-Skua (LSS) model\(^2\) adapting the framework of Turchin and Hanski (1997) to reduce the model complexity of the Gilg et al. (2003) model, show that the 95% upper quantile of lemming values can be increased by a factor of about 1.3 in case of seasonal rather than constant generalist predation. Hence seasonal generalist predation, together with other sources of seasonality (e.g., in birth rates, Taylor et al., 2013), can increase the potential for high-amplitude oscillations. Our LSS model does confirm, however, that increases in the *average* quantity of generalists \((G)\) such as skuas decreases cycle amplitude and periodicity like shown in Turchin and Hanski (1997).

The Gilg et al. (2003) model without mustelids, but with generalist predators, can exhibit 2-year population cycles for some parameter values (Fig. 3), and this is largely due to the recruitment of juveniles foxes at the end of the year. We initially spotted this because of a typo in Gilg et al. (2003)’s Supplementary

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\(^1\)computed for a few peaks with the model

\(^2\)which assumes that all generalist predators behave like skuas
Figure 2: **Population cycles and predation rates** in the Gilg et al. (2003) model, in logarithmic scale. Parameters for lemming and stoats: \( r_W = 5, r_S = 0.8, v = 4.0, c = 1000, D = 0.08, N_{crit} = D, d_I = 0.1, d_h = 4, b = 25. \) Lemming density is given in individuals per ha.
Figure 3: **2-year population cycles (and transients) in the Gilg et al. (2003) model without mustelids.** Parameters for lemming growth: $r_W = 4$, $r_S = 0.8$, $v = 4.0$, $c = 1000$, $D = 0.1$, $N_{crit} = D$, $d_l = 0.1$, $d_h = 4$, $b = 25$. The maximum number of owls has been multiplied by two.

Material (which has been corrected in Gilg et al., 2009 and did not affect Gilg et al., 2003’s simulations) where the max density of owls $b_0$ had been multiplied by two. Two-year population cycles do not appear for the standard parameter set of Gilg et al. (2003), but it is easy to imagine that for a slightly different predator composition at another study site, such short-term fluctuations might become possible.

On the other hand, removing the skua population in the differential equations model leads to a blow-up (unstable oscillations diverging away from the attractor). Therefore, our interpretation of the cycles in the model of Gilg et al. (2003) is that:

1. Long-tailed skuas keep the lemming cycle within bounds through predation during the summer and generate, together with owls, strong seasonal forcing. Their influence is therefore two-fold: (a) their generalist predation tends to keep lemmings in check but (b) the fact that such predation is seasonal contributes to the population cycling.

2. The slightly delayed reproductive response of foxes can for some parameter sets create a short-period (2-year) cycle in absence of mustelids.

3. Stoats generate an eventually unstable lemming-stoat oscillation, which is transformed into a more
sustainable attractor by generalists (skuas in particular).

Our conclusion is therefore that both ‘generalists’ such as skuas/owls/foxes and specialists such as mustelids contribute to some degree to generating collared lemming fluctuations in the Traill Island model. These considerations open up new challenges in defining the precise role of generalist (or nomadic specialists) versus resident specialist predators.

**Comparison to the vole-weasel model of Turchin and Hanski (1997)**

The model of Turchin and Hanski (1997) can be written

\[
\frac{dN}{dt} = rN \left(1 - \frac{N}{K}\right) - \frac{GN^2}{C^2 + N^2} \left(\frac{aNP}{D + N}\right) \tag{5}
\]

\[
\frac{dP}{dt} = sP \left(1 - \frac{P}{N}\right) \tag{6}
\]

Adding seasonality and adimensionalizing, we arrive at

\[
\frac{dn}{dt} = r(1 - e \sin(2\pi t))n - rn^2 - \frac{gn^2}{h^2 + n^2} - \frac{an}{n + d} \tag{7}
\]

\[
\frac{dp}{dt} = s(1 - e \sin(2\pi t))p - sp^2/n \tag{8}
\]

with possibly a small noise term on all parameters, so that each parameter $\Pi_t$ is transformed once a year into $\Pi_t(1 + \sigma \epsilon_t)$, $\epsilon_t \sim \mathcal{N}(0, 1)$. This models reproduces the Fennoscandian gradient when $G$ is increased from South to North. We use here the parameters $r = 6$, $e = 1.0$, $K = 150.0$, $s = 1.25$, $C = 600.0$, $D = 6.0$, $Q = 40.0$, $G = 60.0$, $H = 15$, $\sigma = 0$. See Taylor et al. (2013) for a recent investigation of the possible effects of changes in seasonality over the gradient on cycle periodicity and amplitude.

In Fig. 4 below we illustrate the time series of weasel and vole densities as well as the total amount killed per unit time for specialists or generalists, which shows that specialist predation is larger than generalist predation during vole population declines.
Figure 4: Densities and predation rates in a modified version of the Turchin & Hanski (1997) model, where we additionally allowed generalist predation rates to vary seasonally. Voles still reproduce better in summer than winter, which counteracts the increased predation levels in summer.

By contrast, the model that we adapted for modelling Greenland lemmings using the same model framework shows a slightly different kind of dynamics.

“Pooled generalists” model (aka Lemming - Stoat - Skua model)

Because there are very many parameters in Gilg et al. (2003) (26 in Table S1 and S2 from the original paper, plus potentially 10 dates from Table 1 of this article), we constructed a simplified model to compare its behaviour to Turchin and Hanski (1997). The model assumes that all generalists behave like the skua (the more abundant generalist, with numbers that only depend on the season and not on other species densities). It also assumes that the numerical response has the more simplified Leslie-type form of Turchin and Hanski (1997), which allows to formulate a smooth model. The LSS model uses a winter indicator variable $W(t) = \frac{1}{2}(1 + \cos(2\pi t))$. The time $t = 0$ is in January, so that $W = 1$ in full winter, 0 in full summer. The full differential equation model then writes
\[
\frac{dN}{dt} = r_{\text{min}}N + (r_{\text{max}} - r_{\text{min}})W(t)N - r_{\text{max}} \frac{N^2}{K} - \frac{G(1 - W(t))N^4}{H^4 + N^4} - \frac{CN^2P}{D^2 + N^2}
\]

(9)

\[
\frac{dP}{dt} = sP \left(1 - \frac{P}{N}\right)
\]

(10)

Parameters used in Fig. 5 are tailored to the Greenland Traill island case study: \(r_{\text{max}} = 6, r_{\text{min}} = 0.5, K = 500, G = 50, H = 2, C = 1000, D = 0.1, s = 1.75, Q = 100\). Because the carrying capacity \(K\) in absence of predation was absent in the Traill island model, it is here set to a large value, but it is notable that the LSS model can also work without. The functional response exponents have been taken in accordance to Gilg et al. (2003) and are all sigmoid (Type III), in contrast to the more classical choice of type II response for specialists and type III for generalists in Turchin and Hanski (1997).

Simulating this model, Fig 5 below, we see that the predation by generalists in summer is much higher than that of the specialist (note the logarithmic scale), in constrast to Turchin and Hanski (1997). We also see very clearly that generalists clearly initiate the lemming declines, by “cropping off” the lemming peaks.

Figure 5: “Pooled generalists” LSS model simulation. See text for parameter values.
A cautionary tale on cycle shape in mechanistic models

It has been proposed that cycle shape can be a proxy for cycle causation (Turchin et al., 2000). We offer a different view here. A difficulty with the numerous mechanistic mathematical models available to model rodent cycles is that they tend to produce cycles with correct periodicity and amplitude, but with shapes often different from that of the data. In other words, mechanistic models with empirically estimated parameters might not fit all the details of the cycle very well. For example, in Korpimäki et al. (2002, Fig. 4) the mechanistic predation model consistently produces cycles that rank in the right side of Royama’s triangle, where delayed density-dependence generates the crashes after a plateau at high density (Royama, 1992). However, the data shows often faster crashes, ranking on the left side of the triangle (Fig. 4 in their paper). Conversely, the model in Gilg et al. (2003) cited above tends to produce fast crashes in just one year while the data show crashes occurring over one or two years. This is arguably an undesirable property of the model (Oksanen et al., 2008), which incidentally refutes the claims of Turchin et al. (2000) that “prey peaks” have a rounded shape. The models by Korpimäki et al. (2002) and Gilg et al. (2003) therefore seem to be equally good at describing periodicity and amplitude of the time series, but equally limited to reproduce cycle shape. With rich datasets (e.g. >100 data points in this context), it might be possible to find the most likely models just based on cycle shape, but given the limited data available here (∼25 years with no spatial replication, which is common in many such study sites), such endeavours may be a little premature. Mechanistic mathematical models may be best interpreted as illustrating what is possible, rather than what is actually happening in real populations. Although in some cases, it may be possible to at least rank different scenarios based on very contrasted models and multiple model diagnostics (Kendall et al., 2005).

Code availability

Computer codes have been deposited at Zenodo as part of our release of lemming population cycles models (Barraquand and Henden, 2020) with DOI:10.5281/zenodo.4271833. These are additionally available at https://github.com/fbarraquand/lemmingCycles_ODEmodels. The repository includes of course code for the original Traill island model, codes to simulate the Turchin & Hanski (1997) model with/without seasonal generalist predation, as well as our proposed LSS simplification of the model with 9 parameters. The repository also includes features not used here, such as a stochastic (SDE) version of the Traill island model, various models considered in Turchin and Batzli (2001) for lemming-plant interactions, and a host-parasite model of an interaction with unknown parasite, whose main purpose is to elicit caution regarding inferring cycle causation without hard data on all main parameters of an interaction.

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This remark may very well apply to numerous other mechanistic models for cyclic populations.
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