Empirical validation and proof of added value of MUSICA’s tropospheric δD remote sensing products

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Abstract. The project MUSICA (MUlti-platform remote Sensing of Isotopologues for investigating the Cycle of Atmospheric water) integrates tropospheric water vapour isotopologue remote sensing and in situ observations. This paper presents a first empirical validation of MUSICA’s H₂O and δD remote sensing products, generated from ground-based FTIR (Fourier transform infrared), spectrometer and space-based IASI (infrared atmospheric sounding interferometer) observation. The study is made in the area of the Canary Islands in the subtropical northern Atlantic. As reference we use well calibrated in situ measurements made aboard an aircraft (between 200 and 6800 m a.s.l.) by the dedicated ISOWAT instrument and on the island of Tenerife at two different altitudes (at Izaña, 2370 m a.s.l., and at Teide, 3550 m a.s.l.) by two commercial Picarro L2120-i water isotopologue analysers.

The comparison to the ISOWAT profile measurements shows that the remote sensors can well capture the variations in the water vapour isotopologues, and the scatter with respect to the in situ references suggests a δD random uncertainty for the FTIR product of much better than 45‰ in the lower troposphere and of about 15‰ for the middle troposphere. For the middle tropospheric IASI δD product the study suggests a respective uncertainty of about 15‰. In both remote sensing data sets we find a positive δD bias of 30–70‰.

Complementing H₂O observations with δD data allows moisture transport studies that are not possible with H₂O observations alone. We are able to qualitatively demonstrate the added value of the MUSICA δD remote sensing data. We document that the δD–H₂O curves obtained from the different in situ and remote sensing data sets (ISOWAT, Picarro at Izaña and Teide, FTIR, and IASI) consistently identify two different moisture transport pathways to the subtropical north eastern Atlantic free troposphere.

1 Introduction

The water cycle (continuous evaporation, transport and condensation of water) is closely linked to the global energy and radiation budgets and has thus fundamental importance for climate on global as well as regional scales. Understanding the different, strongly coupled, and often competing processes that comprise the tropospheric water cycle is of prime importance for reliable climate projections. Since different water cycle processes differently affect the isotopic composition of atmospheric water, respective measurements are potentially very useful for tropospheric water cycle research. For instance, they can help to investigate cloud processes (Webster and Heymsfield, 2003; Schmidt et al., 2005), rain recycling and evapotranspiration (Worden et al., 2007), or the processes that control upper tropospheric humidity (Risi et al., 2012).
In the following, we express $\text{H}_2^{16}\text{O}$ and $\text{HD}^{16}\text{O}$ as $\text{H}_2\text{O}$ and $\text{HDO}$, respectively; and $\text{HDO}^{16}\text{O}/\text{H}_2^{16}\text{O}$ in the $\delta$-notation (with the Vienna standard mean ocean water, VSMOW = $3.1152 \times 10^{-4}$, Craig, 1961):

$$\delta \text{D} = \frac{\text{HD}^{16}\text{O}/\text{H}_2^{16}\text{O}}{\text{VSMOW}} - 1. \tag{1}$$

Tropospheric water isotopologue data obtained by space- and ground-based remote sensing techniques are particularly useful, since they can be produced continuously and at global scale. Schneider et al. (2012) present tropospheric $\text{H}_2\text{O}$ and $\delta$D remotely sensed from the ground at 10 globally distributed FTIR (Fourier transform infrared) stations of the NDACC (Network for the Detection of Atmospheric Composition Change, http://www.acd.ucar.edu/irwg/). Space-based remote sensing observations of tropospheric $\delta$D are possible by thermal nadir sensors (Worden et al., 2006; Schneider and Hase, 2011; Lacour et al., 2012) and sensors detecting reflected solar light in the near infrared (Frankenberg et al., 2009, 2013; Boesch et al., 2013).

While there have been efforts for theoretically assessing the quality of the remotely sensed $\delta$D products (e.g. Schneider et al., 2006b; Worden et al., 2006; Schneider and Hase, 2011; Lacour et al., 2012; Schneider et al., 2012; Boesch et al., 2013), so far no rigorous empirical quality assessment has been presented. The few existing studies consist of very few indirect comparisons (Worden et al., 2011) or use a $\delta$D reference that itself is not comprehensively validated (Schneider and Hase, 2011; Boesch et al., 2013). This situation is rather unsatisfactory: since $\delta$D remote sensing measurements are very difficult and the nature of the data is very complex, there is urgent need to support the theoretical quality assessment studies by elaborated empirical validation exercises.

In this context the objective of our paper is to empirically document the quality and prove the scientific value of tropospheric water vapour isotopologue remote sensing products for investigating moisture transport pathways. To do so we use tropospheric $\delta$D reference data obtained by continuously calibrated in situ instruments. The study is made for the Izaña observatory and the surroundings of the island of Tenerife, where tropospheric water isotopologues have been measured in coincidence from different platforms and by different techniques: (1) since 1999 by ground-based FTIR remote sensing within NDACC, (2) since 2007 by space-based remote sensing using IASI aboard METOP, (3) since 2012/2013 by commercial Picarro in situ instruments from ground at two different altitudes, and (4) in July 2013 during six aircraft profile measurements using the dedicated ISOWAT in situ instrument. All these data have been generated within the project MUSICA (www.imk-asf.kit.edu/english/musica). The Izaña observatory and the surroundings of Tenerife comprise the principal water vapour isotopologue reference area of MUSICA and allow a first empirical validation with dedicated aircraft campaign data as well as with long-term data sets. We are not aware of any other site where free tropospheric water vapour isotopologue observations have been made continuously and simultaneously by so many different observational techniques.

Section 2 briefly presents the in situ observations that we use as reference. In Sect. 3 we briefly describe the investigated ground- and space-based remote sensing data. In Sects. 4 and 5 the inter-comparisons are shown and discussed. Section 6 resumes the study.

2 The in situ reference observations

Compared to the remote sensing measurements, the in situ techniques have the great advantage that they can be continuously calibrated against an isotopologue standard. In the following we briefly describe the in situ instruments as operated in the Tenerife area.

2.1 Aircraft-based ISOWAT

The ISOWAT instrument is a tunable diode laser spectrometer specifically designed for the use aboard research aircraft (Dyroff et al., 2010). The first prototype has been successfully used within the project CARIBIC (Civil Aircraft for the Regular Investigation of the atmosphere Based on an Instrument Container, http://www.caribic-atmospheric.com/). For the validation campaign, a second prototype of ISOWAT was installed aboard a CASA C-212 aircraft of INTA (Instituto Nacional de Técnica Aeroespacial, http://www.inta.es/).

ISOWAT measures $\delta$D in water vapour by means of laser-absorption spectroscopy. Ambient air is extracted from the atmosphere and is pumped through a multi-reflection measurement cell. The beam of a diode laser is guided into the cell where it is reflected back and forth between two mirrors to form an optical path of 32 m. The emission wavelength of the laser is continuously tuned across individually resolved absorption lines of the $\text{H}_2^{16}\text{O}$ and $\text{HD}^{16}\text{O}$ isotopologues at a frequency of 10 Hz. Absorption spectra are averaged over 1 s, which defines the maximum temporal resolution of the measurements.

During the campaign ISOWAT was calibrated before and after each flight performing measurements of a known isotope standard. The standard was provided by a custom-designed bubbler system that was used to humidify dry synthetic air to $\delta$D of about $-130\%e$ at humidity ranging from about 200 to > 25000 ppmv. One of the key strengths of ISOWAT is its in-flight calibration. While substantial calibration measurements were performed on the ground, we perform in-flight calibrations in order to confirm the instrumental performance during the flight. The in-flight calibration source provided a known isotope standard at a humidity of 3000–5000 ppmv. Thereby, ambient air was first dried (< 5 ppmv) in a cartridge containing a molecular sieve. The
Figure 1. $H_2O$ (left panel) and $\delta D$ profiles (right panel) as measured by ISOWAT above the subtropical Atlantic close to Tenerife between 10:00 and 13:00 UT on 6 days at the end of July 2013. The depicted data are 10 m vertical averages. For comparison we also depict the a priori profiles used for the MUSICA NDACC/FTIR and METOP/IASI remote sensing retrievals (grey dashed lines).

dry air was then humidified in a small temperature-stabilized bubbler system. Calibrations were performed 2–5 times per flight at varying altitudes in order to check the performance of ISOWAT under all environmental conditions. By combining the ground-based and in-flight calibration measurements we were able to provide a robust accuracy estimate for the ISOWAT in-flight data. For the majority of conditions encountered, ISOWAT provided profile measurements with an accuracy for $\delta D$ of about 10‰. Below 2000 ppmv the accuracy increases and can exceed 35‰ for a humidity below 500 ppmv.

The ISOWAT humidity data are calibrated against a commercial hygrometer (Edge Tech model Dew Master). We estimate a precision and accuracy of about 4‰.

ISOWAT measures the isotopologues with a temporal resolution of 1 s. This translates to a horizontal spatial resolution of about 80 m depending on the aircraft velocity. During the MUSICA campaign, profile flights consisted in a relatively fast ascent followed by a slower descent with intermediate level flights at certain selected altitudes and we achieved an average vertical resolution of about 1.2 m. The good temporal resolution of ISOWAT allows observing the rather sharp vertical gradients encountered during the flights (see Fig. 1).

For a more detailed report about the aircraft campaign, the ISOWAT measurements, and the calibration procedures please refer to Dyroff et al. (2015).

2.2 Surface-based Picarro

Similar to ISOWAT, the Picarro water isotopologue analysers work with a tunable diode laser. The laser light enters a cavity filled with the air mass to be analysed. The absorption signal of the air mass is determined by the ring-down time of the laser light intensity. In order to get an absorption spectrum the ring-down time is measured for different laser frequencies between 7183.5 and 7184 cm$^{-1}$. For more details see the Picarro website (http://www.picarro.com).

In March 2012 we installed a Picarro L2120-i water isotopologue analyser at the Izaña Observatory at 2370 m a.s.l. The measured $H_2O$ and $\delta D$ time series is depicted in the left graphs of Fig. 2. In June 2013 we installed an additional Picarro L2120-i analyser at a small observatory located close to the cable car summit station of the Teide mountain (at 3550 m a.s.l.). The Teide $H_2O$ and $\delta D$ time series is depicted in the right graphs of Fig. 2. We only depict data measured during the second half of each night (between midnight and 1 hour after sunrise). By this measure we avoid that the measurements are affected by local upslope flow, which can bring boundary layer air to the mountain observatories. The measurement gaps are due to instrumental problems when the instruments were sent to the manufacturer for repair. The time series document that the atmospheric water vapour fields are rather variable already on hourly timescales.

The $\delta D$ calibration procedure for the Picarro instruments is based on a standard delivery module (SDM). It consists of two syringe pumps and allows injecting two different standards into the vaporizer where a constant dry air flow sustains immediate vaporization of the liquid in the air stream (for more details see also Aemisegger et al., 2012). The calibration is made every 8 h. It uses two different $\delta D$ standards (at $-142.2$ and $-245.3\text{‰}$) that are analysed by the instrument at three different humidity levels covering the typical humidity range at Izaña and at Teide (during summer).

The precision of our 0.6 Hz measurements was 13.5 and 2.2‰ at 500 and 4500 ppmv, respectively. This noise almost completely averages out in the 10 min averages (our final data product). The random uncertainty of the individual calibrations (performed every 8 h) was 0.5 and 0.2‰ at 500 and 4500 ppmv, respectively, which also averages out on longer timescales. Systematic uncertainties of the used standard
water and uncorrected humidity dependence were 1.7 and 0.7 ‰ at 500 and 4500 ppmv, respectively.

Our Picarro humidity data are calibrated with respect to humidity data measured by standard meteorological sensors. The humidity values measured by the Picarro and the meteorological sensors are very strongly correlated and for the calibrated data we estimate a precision and accuracy of better than 2 %.

A more detailed description of the MUSICA Picarro in situ measurements at Tenerife island is the subject of a dedicated paper, which is currently in preparation.

3 The investigated remote sensing products

The characteristics of the water vapour isotopologue remote sensing products are rather complex. Schneider et al. (2012) introduce a proxy state concept that allows for reasonably characterizing the interesting products, namely humidity (or H$_2$O) and δD (or HDO/H$_2$O). They identify two product types. Product type 1 is a vertical H$_2$O profile and product type 2 is for isotopologue studies. Product type 2 provides H$_2$O and δD data that are representative for the same air mass and assures that the δD product is optimally independent on H$_2$O. In the following we use this proxy state concept for briefly discussing the characteristics of the MUSICA remote sensing products that are available for the area of Tenerife island.

3.1 Ground-based NDACC/FTIR

Ground-based FTIR remote sensing measurements have been performed at Izaña since 1999 (e.g. García et al., 2012). The experiment is situated in its own measurement laboratory (a shipping container equipped with electricity, air-conditioning, internet, etc.) and just about 50 m away from the Observatory’s main building. Typically we measure on about 2–3 days per week. The number of measurement days is mainly limited by manpower, which is needed for operating the instrument. Ground-based FTIR systems measure high-resolution mid-infrared solar absorption spectra. The spectra contain absorption signatures of many different atmospheric trace gases. Therefore, the technique can simultaneously monitor many different atmospheric trace gases. Continuous developments of sophisticated retrieval algorithms allow also the retrieval of tropospheric water vapour isotopologues (for retrieval details please refer to Schneider et al., 2006b, 2010b).

Using the measured spectra for estimating the atmospheric trace gas distributions is generally an ill-posed problem. For this purpose the solution state is constraint towards an a priori state. The H$_2$O and δD a priori values applied for the isotopologue retrievals are depicted in Fig. 1 as grey line. The MUSICA FTIR retrieval works with several spectral microwindows between 2655 and 3025 cm$^{-1}$ and with HITRAN 2008 (Rothman et al., 2009) spectroscopic parameters, and the H$_2$O and HDO parameters have been adjusted for speed-dependent Voigt line shapes (Schneider et al., 2011), which affects pressure broadening parameters but also line intensities. For H$_2$O the adjustment has been made taking coincident H$_2$O profile observations as the reference. For HDO the adjustment is more uncertain, since the atmospheric HDO state was calculated from the measured H$_2$O state assuming standard δD profiles (there were no HDO measurements available).

The averaging kernel is an important output of the retrieval. It describes the response of the retrieval on actual
The a posteriori correction significantly reduces the vertical resolution of the retrieved $\delta$D state (compare upper left graphs between type 1 and type 2 panels). This sensitivity reduction is mandatory in order to assure that the $\delta$D product is representative for the same air mass as the $\delta$O product (compare upper left and bottom right graphs in the type 2 panels). This sensitivity dependency of the retrieved $\delta$D on humidity, i.e. the cross-dependency on humidity (compare the bottom left graphs between the type 1 and type 2 panels).

The Izaña FTIR product type 2 offers a degree of freedom for the signal (DOFS, trace of the averaging kernel matrix quantifying the retrieval’s independency on the a priori assumptions) for $\delta$H$_2$O and $\delta$D of typically 1.75. The lower tropospheric kernels have an FWHM (full width at half maximum) of about 2 km and the middle tropospheric kernels a FWHM of about 5–6 km. In Schneider et al. (2012) the lower and middle tropospheric random uncertainty has been estimated to be smaller than 2 % for $\delta$H$_2$O and 25 % for $\delta$D, respectively, whereby measurement noise, spectral baseline uncertainties, and assumed tropospheric a priori temperature are the leading error sources. The systematic uncertainty can reach 10 % for $\delta$H$_2$O and 150 % for $\delta$D. It is dominated by uncertainties in the spectroscopic parameters (intensity and pressure broadening). The a posteriori correction method reduces the $\delta$D cross-dependency on humidity to less than 10–15 %.

### 3.2 Space-based METOP/IASI

IASI is a Fourier transform spectrometer flown aboard the METOP satellites. It combines high temporal, horizontal, and spectral resolution (covers the whole globe twice a day, measures nadir pixels with a diameter of only 12 km, and records thermal radiation between 645 and 2760 cm$^{-1}$ with a
resolution of 0.5 cm\(^{-1}\). IASI measurements are assured until 2020 on three different METOP satellites, whereby the first two are already in orbit: MetOp-A has been launched in October 2006, MetOp-B in September 2012. For our study we consider spectra measured by the IASI instruments aboard both satellites. Each IASI instrument has two Tenerife overpasses a day (about 10:30 and 22:30 UT). For MUSICA we work so far only with overpasses that observe clear sky scenes. We use very strict cloud-screening conditions and therefore work with only about 10% of all possible overpass spectra.

The retrieval uses the spectral window between 1190 and 1400 cm\(^{-1}\) and HITRAN 2008 (Rothman et al., 2009) spectroscopic line parameters. The applied a priori values are the same as for the FTIR retrievals and are depicted in Fig. 1 as grey line. Schneider and Hase (2011) present our IASI retrieval algorithm as well as a first theoretical error assessment of the respective H\(_2\)O and \(\delta\)D products.

The left panel of graphs in Fig. 4 shows typical averaging kernels for the product type 1 \([\text{H}_2\text{O}, \delta\text{D}]\)-state of MUSICA IASI retrievals corresponding to spectra measured over the subtropical northern Atlantic. Product type 1 offers vertical H\(_2\)O profiles with the FWHM of the kernels of about 2 km in the lower and middle troposphere and 3 km in the upper troposphere (see upper left graph in type 1 panel of Fig. 4 and Schneider and Hase, 2011; Wiegele et al., 2014, for more a more detailed characterization). The MUSICA product type 1 IASI H\(_2\)O profiles are empirically validated in Schneider and Hase (2011) by comparison to meteorological radiosondes, ground-based FTIR, and the EUMET-SAT METOP/IASI product and in Wiegele et al. (2014) by comparison to ground-based FTIR at three different locations (polar, mid-latitudinal and subtropical) and a further validation of this type 1 product is not the subject of this paper.

Interesting for isotopologue studies is product type 2 which shall be further investigated in this paper. The respective \([\text{H}_2\text{O}, \delta\text{D}]\)-state kernels are depicted in the right panel of graphs in Fig. 4. The sensitivity is typically limited to between 2 and 8 km altitude, with a maximum in the middle troposphere around 4–5 km. The random uncertainty for type 2 H\(_2\)O and \(\delta\)D is estimated to be about 5% and 20‰, respectively, whereby measurement noise, surface emissivity, assumed tropospheric a priori temperature, and unrecognized thin elevated clouds are the leading error sources. The systematic uncertainty is very likely dominated by errors in the spectroscopic line parameters and can reach 2–5% for H\(_2\)O in the case of a 2–5% error in the line intensity parameter. For \(\delta\)D the systematic uncertainty can reach 50‰ in the case of inconsistencies of 5% between the spectroscopic intensity parameters of H\(_2\)O and HDO. Despite the a posteriori correction there remains a \(\delta\)D cross-dependency on humidity, which can cause an additional \(\delta\)D uncertainty of 30–50‰ (Wiegele et al., 2014).
Remote sensing data do not represent a single altitude. Instead they reflect the atmospheric situation as averaged out over a range of different altitudes (the kind of averaging is documented by the averaging kernels of Figs. 3 and 4). Such data can only be quantitatively compared to reference data that are available as vertical profiles. Here we compare the NDACC/FTIR and METOP/IASI products (product type 2, see Schneider et al., 2012) to the in situ profiles as measured by ISOWAT between 200 and 6800 m a.s.l.

For a quantitative comparison we have to adjust the vertically highly resolved ISOWAT profiles (\(x_{IW}\) as depicted in Fig. 1) to the modest vertical resolution of the remote sensing profiles. For this purpose we first perform a smoothing towards the altitude grid of the remote sensing retrieval’s forward model. It can be described by \(M_{x_{IW}}\), whereby \(M\) is a \(v \times w\) matrix with \(v\) and \(w\) being the numbers of the grid points of the forward model and of the vertically highly resolved ISOWAT profile, respectively. This smoothing works in a way that assures a conservation of the partial columns between two forward model grid points (i.e. the respective partial columns are very similar, before and after the smoothing process). In a second step we convolve \(M_{x_{IW}}\) with the remote sensing averaging kernel \(A\):

\[
\hat{x}_{IW} = \hat{A} (M_{x_{IW}} - x_a) + x_a. \tag{2}
\]

Here \(x_a\) is the a priori profile used by the remote sensing retrieval. When using the \(\{\text{H}_2\text{O}, \delta\text{D}\}\)-proxy state averaging kernels as depicted in Figs. 3 and 4 we have to make sure that \(M_{x_{IW}}\) in Eq. (2) is in the \(\{\text{H}_2\text{O}, \delta\text{D}\}\)-proxy state. The result of this convolution is an ISOWAT profile (\(\hat{x}_{IW}\)) with the same vertical resolution as the remote sensing profile. In the following we will use the “hat”-index for marking parameters or amounts that are retrieved from measured spectra or obtained by convolution calculations according to Eq. (2).

The ISOWAT profiles are limited to 200–6800 m altitude, whereas the FTIR and IASI remote sensing instruments are also sensitive to altitudes above 7000 m (and IASI is also very weakly sensitive for altitudes below 200 m). For the comparison study we extend the ISOWAT profiles above the aircraft’s ceiling altitude by the values we use as a priori for the remote sensing retrievals (the a priori values are the same for FTIR and IASI and depicted as grey dashed line in Fig. 1). Below 200 m altitude we use the values as measured during the first 100 m of available aircraft data.

### 4 Assessing random uncertainty and bias

When comparing two atmospheric measurements we have to take care that the different instruments detect the same (or at least very similar) air masses. Large differences in the vertical resolution can be accounted for by Eq. (2). In addition we have to be aware that ISOWAT measures the profile aboard a descending and ascending aircraft. Each flight, i.e. each ISOWAT profile measurement, takes about 3 hours and is made over the ocean (see flight tracks of Fig. 5). This is in contrast to the FTIR remote sensing measurements, which need only about 10 min and are made at Izaña observatory at 2370 m a.s.l. on a mountain ridge of an island. It is well documented (e.g. Rodríguez et al., 2009) that the immediate surroundings of the island at this altitude are affected by mixing from the marine boundary layer (MBL). This mixing is mostly thermally driven: it is weak during the night and starts increasing during the morning hours and the air mass measured at or very close to the island becomes more and more affected by the MBL. At the end of the morning this air mass is not well representative for the situation encountered at the same altitude over the ocean.

For this study we compare the ISOWAT profile with the FTIR data obtained from the spectra measured in the morning with a solar elevation angle of 30°. This elevation assures that the FTIR has good sensitivity (absorption pathes are short enough and water vapour lines are not too heavily saturated) and it occurs only about 2:30 h after sunrise, when the influence of the MBL on the immediate surroundings of the island is still moderate.

In Fig. 6 we compare the \(\text{H}_2\text{O}\) measurements. The data are depicted as difference to the a priori, i.e. we discuss here the variability that is actually introduced by the remote sensing measurement and observed by ISOWAT. Here and in the
following we calculate the H$_2$O differences as differences between the logarithms of the H$_2$O concentrations. Since $\Delta \ln X \approx \Delta X / X$, we can interpret these differences between the logarithms of the H$_2$O concentrations as relative differences. The graphs also show the predicted uncertainties for the lower and middle troposphere and for dry (day 130730) and humid conditions (day 130731). The respective error bars are hardly discernible, since the H$_2$O errors are only a few percent. Please note that the uncertainties as shown in the central graph take into account the assumption of climatologic a priori values for altitudes above the aircraft’s ceiling altitude (no measurements!), which is the reason for the relative large uncertainty as estimated for the middle troposphere for the ISOW AT data smoothed by the FTIR kernels.

The comparison between the left and the central panels of Fig. 6 gives insight into the vertical structures that can be resolved by the remote sensing measurements. The profiles depicted in the central and the right panels represent the same vertical structures and their comparison allows conclusions about the quality of the remote sensing data.

For this purpose we statistically analyse the differences between the remote sensing product ($\tilde{x}_{RS}$) and the convolved ISOW AT product ($\tilde{x}_{IW}$, see Eq. 2). We determine the mean difference $\bar{b}_{DIFF}$ from the $n$ numbers of coincidences:

$$\bar{b}_{DIFF} = \frac{1}{n} \sum_{i=1}^{n} (\tilde{x}_{RS,i} - \tilde{x}_{IW,i})$$  \hspace{1cm} (3)$$

and the standard deviation of the differences (the scatter between both data sets):

$$\sigma_{DIFF} = \sqrt{\frac{1}{n-1} \sum_{i=1}^{n} (\tilde{x}_{RS,i} - \tilde{x}_{IW,i} - \bar{b}_{DIFF})^2}.$$  \hspace{1cm} (4)

Furthermore, we calculate the typical/mean scatter as predicted from the combined uncertainties of the remote sensing and the convolved ISOW AT data, $\epsilon_{RS}$ and $\epsilon_{IW}$, respectively:

$$\hat{\epsilon}_{DIFF} = \frac{1}{n} \sum_{i=1}^{n} \sqrt{\epsilon_{RS,i}^2 + \epsilon_{IW,i}^2}.$$  \hspace{1cm} (5)

For comparison we also calculate a parameter, which is the scatter in the convolved ISOW AT data:

$$\hat{\epsilon}_{IW} = \frac{1}{n} \sum_{i=1}^{n} (\tilde{x}_{IW,i} - \tilde{\mu}_{IW})^2$$  \hspace{1cm} (6)

whereby $\tilde{\mu}_{IW} = \frac{1}{n} \sum_{i=1}^{n} \tilde{x}_{IW,i}$. The $\hat{\epsilon}_{IW}$ parameter informs about the random uncertainty of the water vapour state when no measurements are available (a priori uncertainty).

The values that result from these calculations for the comparison of FTIR and ISOW AT H$_2$O data are depicted in Fig. 7. In the left graph, the scatter between FTIR and ISOW AT (parameter $\hat{\epsilon}_{DIFF}$ according to Eq. 4) is shown as black triangles, together with the predicted scatter ($\hat{\epsilon}_{DIFF}$ according to Eq. (5), red dashed line). We observe a scatter of about 28 and 20 % for the lower and middle troposphere, respectively. In the lower troposphere the observed scatter is significantly larger than the scatter predicted from the combined uncertainties, which might be caused by the fact that the two instruments observe similar, but not the same air masses. The large inhomogeneity in the tropospheric water vapour fields becomes clearly visible in Fig. 1 (spatial inhomogeneity) and Fig. 2 (temporal inhomogeneity). In this context the observed scatter has to be interpreted as a rather conservative empirical estimation of the FTIR’s random uncertainty. The blue solid line depicts the scatter between the six ISOW AT profiles when smoothed with the FTIR kernels.
Eqs. (3) and (4), respectively). Red area: the predicted uncertainty range (calculated as $\hat{\epsilon}_{\text{DIFF}}$/sqrt(n-1)).

Figure 7. Left graph, assessment of the random uncertainty. Black symbols: the FTIR-ISOWAT scatter ($\hat{\epsilon}_{\text{DIFF}}$ value according to Eq. 4). Red dashed line: the predicted scatter ($\hat{\epsilon}_{\text{DIFF}}$ value according to Eq. 5). Blue solid line: the scatter in the convolved ISOWAT data ($\hat{\epsilon}_{\text{IW}}$ value according to Eq. 6). Blue dashed line: the uncertainty in the not convolved ISOWAT data ($\epsilon_{\text{IW}}$). Right graph, assessment of the bias. Black symbols and error bars: the FTIR-ISOWAT mean difference and standard error of the mean ($\hat{\delta}_{\text{DIFF}}$ and $\hat{\epsilon}_{\text{DIFF}}$/sqrt(n-1) values according to Eqs. (3) and (4), respectively). Red area: the predicted uncertainty range (calculated as $\hat{\epsilon}_{\text{DIFF}}$/sqrt(n-1)).

Figure 8. As Fig. 6, but for $\delta D$. Here the error bars are clearly discernible.

(\(\hat{\delta}_{\text{IW}}\) values according to Eq. 6). It is much larger than the scatter in the difference with the FTIR profiles meaning that the FTIR well follows the ISOWAT reference, which confirms previous empirical validation exercises made for H$_2$O (e.g. Schneider et al., 2006a; Schneider and Hase, 2009; Schneider et al., 2010a). Please note that the depicted red dashed line represents the combined uncertainty of the convolved ISOWAT data and the FTIR data. The pure ISOWAT uncertainty (uncertainty of ISOWAT if not convolved with the FTIR kernel, $\epsilon_{\text{IW}}$) is much smaller and depicted as blue dashed line.

The mean difference between FTIR and ISOWAT and the respective standard error of the mean ($\hat{\delta}_{\text{DIFF}}$ and $\hat{\epsilon}_{\text{DIFF}}$/sqrt(n-1), according to Eqs. (3) and (4), respectively) are shown in the right graph of Fig. 7 as black triangles and error bars. The red area depicted around the zero line indicates the zone where a bias might be observed accidently due to the combined random uncertainties of ISOWAT and FTIR (this area is calculated as $\hat{\epsilon}_{\text{DIFF}}$/sqrt(n-1), see Eq. 5). The observed differences overlap well with this area meaning that we cannot observe a significant bias between the FTIR and the ISOWAT data.

The coincident $\delta D$ profiles are shown in Fig. 8. Here the predicted uncertainties are clearly discernible. The results of the statistical analysis of the $\delta D$ comparison are presented in Fig. 9. In the left graph we observe a scatter ($\hat{\delta}_{\text{DIFF}}$) of about 45 and 15 ‰ for the lower and middle troposphere, respectively, which can be interpreted as a conservative empirical estimation of the FTIR’s random uncertainty. In the middle troposphere this observed scatter is clearly smaller than the predicted one ($\hat{\epsilon}_{\text{DIFF}}$) indicating that our theoretical ISOWAT and/or FTIR error estimations might be too conservative. In particular the ISOWAT estimates are rather conservative since we assumed that on a single day all $\delta D$ errors
that occur at different altitudes and during ascent and descent are fully correlated. Allowing for δD errors that are not fully correlated (for instance positive errors at 2 km altitude and negative errors at 5 km altitude) would strongly decrease the error as estimated for the ISOWAT data, since through the convolution with the kernel a large part of the error would cancel out. The comparison of the observed scatter with the blue solid line (scatter between the six convolved ISOWAT profiles, $\hat{\delta}\text{H}_2\text{O}$) demonstrates that the FTIR δD product well captures the atmospheric variations as seen by the ISOWAT reference data.

The right graph of Fig. 9 reveals a clear systematic difference between the FTIR and the ISOWAT δD data.

At and above 3 km altitude this difference lies outside the zone where a bias might be observed accidentally due to the combined random uncertainties of ISOWAT and FTIR (red area calculated according to Eq. 5), meaning that we are able to detect a significant bias. It is about 25‰ in the lower troposphere and 70‰ in the middle troposphere.

In Fig. 10 we show a correlation plot for the H$_2$O and δD data as observed in the middle troposphere (altitude of 5 km) by ISOWAT and FTIR. This plot can serve as a summary of the comparison exercise: (1) H$_2$O and δD signals are similarly observed by both instruments (good correlation), (2) there is no significant difference between the H$_2$O data, and (3) there is a significant positive bias in the FTIR δD data.

4.2 METOP/IASI

The black squares and diamonds in Fig. 5 show all the IASI-A and IASI-B pixels for morning overpasses that have been declared cloud free (according to EUMETSAT level 2 data) within a 250 km $\times$ 250 km area around the aircraft’s flight tracks. In order to assure that IASI and ISOWAT observe
similar air masses we only work with IASI observations that are made not further away than 50 km from the typical location of the aircraft. This yields 13 coincidences (three for IASI-A and ten for IASI-B) made on four different days: 130724, 130725, 130730, and 130731. The respective pixels are marked by the filled squares and diamonds in Fig. 5 (the different colours are for the different days).

IASI can hardly measure the vertical distribution of $\delta D$ (see right panel of Fig. 4). For this reason we can limit the validation exercise to a single altitude level where IASI has typically good sensitivity. This is the case for the altitude of 5 km, which typically represents the atmospheric situation between 2 and 8 km altitude.

Figure 11 shows the same as Fig. 10 but for the IASI instead of the FTIR data. It depicts the correlation between the ISOWAT data (convolved with IASI kernels) and the IASI data.

For $\text{H}_2\text{O}$ the data group nicely around the $1:1$ diagonal. For three of the five IASI observations on day 130731 the agreement is unusually poor. These data points are marked by black edges and they correspond to the one IASI-A pixel and the two IASI-B pixels marked by the black edges in Fig. 5. The reason for their relatively poor agreement is that for these coincidences the two IASI and ISOWAT instruments observe different air masses. For more details see Appendix A. For $\delta D$ we observe a good correlation but there is a significant systematic difference. All the IASI data show rather consistently about 60% less HDO depletion than ISOWAT and this bias is outside the predicted uncertainty range, i.e. it is significant. In this context it is interesting that for the FTIR data we observe a similar systematic difference, which confirms the work of Schneider and Hase (2011) and Wiegele et al. (2014), where no systematic differences between IASI and FTIR are reported.

The good correlations as seen in Fig. 11 demonstrate that IASI can well capture the variations of the middle tropospheric water vapour isotopologues. In order to document this quantitatively, we compare the scatter observed in the difference between IASI and ISOWAT with the scatter observed in the ISOWAT profiles as well as with the scatter predicted from our ISOWAT and IASI uncertainty estimations. These scatter values are collected in Table 1. First, we see that the scatter in the IASI $-\text{ISOWAT}$ difference (the value $\sigma_{\text{DIFF}}$ according to Eq. 4) is much smaller than the scatter in the convolved ISOWAT data (the value $\sigma_{\text{IW}}$ according to Eq. 6), i.e. IASI well tracks the $\text{H}_2\text{O}$ and $\delta D$ variations as observed by ISOWAT. From the $\sigma_{\text{DIFF}}$ values we empirically assess an IASI random uncertainty of better than $6\%$ for $\text{H}_2\text{O}$ and about $13\%$ for $\delta D$. For the latter the value is not larger than the combined estimated errors of the convolved ISOWAT and the IASI $\delta D$ data ($\epsilon_{\text{DIFF}}$ according to Eq. 5), which is also about $13\%$. Since ISOWAT and IASI actually do not detect the same air mass, part of the observed scatter should be due to the observation of a different air mass. Consequently our combined uncertainty estimations are very likely too conservative, which might be explained by the aforementioned conservative ISOWAT uncertainty assumption (assumption of fully correlated errors).

![Figure 11. As Fig. 10, but for correlation between ISOWAT data (here smoothed with IASI kernels, i.e. this ISOWAT data are different to the ISOWAT data as depicted in Fig. 10) and IASI data for 5 km altitude. Three $\text{H}_2\text{O}$ outliers on day 130731 (blue triangles) are marked by black edges. For clarity the error bars are only given for one observation per day and on day 130731 in addition for one of the three outliers.](image)

### Table 1. Scatter values as obtained from IASI and ISOWAT coincidences that fulfil our coincidence criteria (presents the same as the left panels of Figs. 7 and 9, but for IASI instead of FTIR and at 5 km altitude only). Predicted: combined ISOWAT and IASI estimated uncertainties ($\epsilon_{\text{DIFF}}$): IASI $-\text{ISOWAT}$: scatter as observed in the difference between ISOWAT and IASI ($\sigma_{\text{DIFF}}$): ISOWAT: scatter as observed in the ISOWAT data ($\sigma_{\text{IW}}$). The values in parenthesis are for calculations without considering the three outliers on 130731.

|          | $\text{H}_2\text{O}$ [%] | $\delta D$ [%] |
|----------|--------------------------|----------------|
| Predicted ($\epsilon_{\text{DIFF}}$) | 9.9 (8.5)            | 13.2 (12.3)    |
| IASI $-\text{ISOWAT}$ ($\sigma_{\text{DIFF}}$) | 16.0 (6.0)           | 12.0 (13.2)    |
| ISOWAT $\sigma_{\text{IW}}$ | 29.9 (34.4)           | 37.1 (36.7)    |
4.3 Bias in the remote sensing data

When comparing the remote sensing and ISOWAT H2O data we find a systematic difference of up to 10%. However, the mean difference is clearly smaller than the respective standard error of the mean, making this empirical bias estimation statistically insignificant (see black triangles and error bars in the right panel of Fig. 7). Since the lower/middle tropospheric H2O fields are temporally and spatially very variable (variability in the range of 50–150%), it is difficult to identify a bias in the H2O remote sensing product using a limited number of nearby in situ reference observations.

Tropospheric δD variability is in the range of 50–150‰ and a remote sensing δD bias of a similar magnitude might be detected even by using a small number of coinciding reference measurements. In fact the bias we observe between the few ISOWAT reference data and our remote sensing δD product is statistically significant. It is between 10 and 70‰ for the FTIR (see right panels in Figs. 9 and 10) and about 60‰ for the IASI data (see right panel of Fig. 11). Wiegele et al. (2014) found consistency between a large amount of IASI and FTIR data obtained at three rather different locations (subtropics, mid-latitudes and Arctic), which suggests that the biases are similar and stable for a wide range of different locations. However, in order to investigate the consistency of the bias for different locations more quantitatively further ISOWAT profile measurements at different sites and during different seasons would be desirable.

5 Proofing the added value of δD

5.1 The added value of δD observations

In Fig. 12 we plot all the in situ data that have been measured so far in the lower or middle troposphere within the project MUSICA. These data represent different altitudes and two different locations (subtropics and mid-latitudes). We observe a strong correlation between the logarithm of H2O concentrations and δD (for linear correlation we get an R2 of about 80%), which suggests that δD and H2O contain similar information thereby relativizing the results as presented in Sect. 4: in Fig. 9 and Table 1 we show that the remote sensing measurements can correctly detect a large part of the actual δD variations. However, we do not show if the remote sensing δD measurements are precise enough for detecting the small part of the lower/middle tropospheric δD variations that are complementary to H2O.

In this context, we have to be aware that the remote sensing retrievals provide δD data that are slightly dependent on the atmospheric H2O state (see the bottom left graphs in the type 1 and 2 panels of Figs. 3 and 4), meaning that the remote sensing δD data might be correlated to the in situ δD data only via its dependency on H2O and not because δD is correctly retrieved. The fact that in Sect. 4 we convolve the in situ reference data with the remote sensing averaging kernels further increases this risk of misinterpreting the δD remote sensing data quality: by convolving the in situ data with the averaging kernels we create a δD in situ reference that has a similar dependency on H2O as the remote sensing data and the good correlation between the remote sensing and the convolved in situ δD data might partly be a result of the convolution calculations according to Eq. (2).

For these reasons it is rather important to complement the quantitative validation exercises as shown in Sect. 4 by a qualitative study demonstrating that the δD remote sensing measurements add new information to the H2O remote sensing data. This added value of δD can be examined by analysing δD–H2O diagrams (we face a two-dimensional validation problem!). We have to demonstrate that our combined δD/H2O remote sensing products are really useful for studying atmospheric moisture transport processes.

In this section we work with pure in situ data (not convolved with the remote sensing averaging kernels). This does not allow a quantitative study, but it ensures that our in situ reference remains completely independent from the remote sensing data.

5.2 Dehydration via condensation versus vertical mixing from the boundary layer

The downwelling branch of the Hadley circulation plays a dominating role for the free troposphere (FT) of the subtropics. It is responsible for a strong subsidence inversion layer which hinders mixing of planetary boundary layer (PBL) air into the FT. Under such situation the FT air mass is transported from higher latitudes and/or higher altitudes...
(Galewsky et al., 2005; Barnes and Hartmann, 2010; Cuevas et al., 2013).

In addition, the summertime FT of the northern subtropical Atlantic is frequently affected by air masses that are advected from the African continent (e.g. Prospero et al., 2002; Rodríguez et al., 2011; Andrey et al., 2014). At that time of the year there are strong and extended heat lows over the African continent at 20–35°N. These heat lows modify the transport pathways to the FT and enable mixing from the PBL to the FT (e.g. Valero et al., 1992).

These two different transport pathways can be observed at our reference site (island of Tenerife and surroundings), and we can use these circumstances for validating the added value of the δD signal and for demonstrating the usefulness of the remote sensing data for studying atmospheric moisture transport processes.

5.2.1 Aerosol data as proxy for transport pathways

Saharan dust aerosols measured in the FT around Tenerife can be used for identifying an air mass that has experienced vertical transport over the African continent. This shall be demonstrated by Fig. 13, which shows that at Izaña and in summer high aerosol concentrations (PM$_{10}$ > 25 µg m$^{-3}$) are clearly correlated to air masses that have been advected from the African continent. The PM$_{10}$ aerosol data show the aerosol mass concentration considering all particles with aerodynamic diameter smaller than 10 µm, and at Izaña, PM$_{10}$ is, by far, dominated by Saharan dust particles (Rodríguez et al., 2011). For the calculation of the backward trajectories we use HYSPLIT (Hybrid Single-Particle Lagrangian Integrated Trajectory – some examples and explanations of the HYSPLIT calculations are given in Cuevas et al., 2013).

In the following we use low aerosol concentrations as proxy for an FT air mass that has been mainly transported from higher latitudes and/or higher altitudes (clean conditions, no vertical mixing from the PBL to the FT). High aerosol concentrations are our proxy for air masses influenced by vertical mixing over the African continent (dust conditions). We investigate the isotopologue data measured by the different instruments under the different conditions. For each instrument we need aerosol data that are representative for a similar air mass as the isotopologue data.

For ISOWAT we use the $V_{10}$ aerosol data observed in situ during the flights. The $V_{10}$ aerosol data is the aerosol volume concentration considering particles with a diameter smaller than 10 µm. The vertical resolution of these measurements is 100 m. The ISOWAT data are much higher resolved. We calculate 100 m averages from the ISOWAT data in order to make them representative for the same layers as the aerosol data. An air mass with $V_{10}$ < 1 mm$^3$ cm$^{-3}$ is defined as a clean air mass and an air mass with $V_{10}$ > 10 mm$^3$ cm$^{-3}$ is defined as dust air mass. For more details on the aircraft aerosol data see Appendix B and Fig. B1.

The Izaña Picarro data are paired with Izaña’s PM$_{10}$ in situ aerosol measurements. As definition for clean conditions we use PM$_{10}$ < 2 µg m$^{-3}$ and for dust conditions PM$_{10}$ > 25 µg m$^{-3}$. More information about these data is given in Appendix B (Fig. B2). We only work with nighttime data (observed between midnight to 1 hour after sunrise). Thereby we can minimize the risk of data affected by local mixing between the MBL and the FT.

At Teide there are no continuous in situ aerosol observations and we pair the Teide Picarro data with the Izaña AERONET (http://aeronet.gsfc.nasa.gov) remote sensing data. The AERONET photometers analyse the direct sunlight and report the aerosol optical depth (AOD) for the whole atmosphere above Izaña, i.e. they are reasonably representative for the altitudes around Teide. For an AOD value at 500 nm below 2 × 10$^{-2}$ we assume clean conditions and above 5 × 10$^{-2}$ dust conditions. In order to avoid that the Picarro observations are affected by local vertical mixing we only work with nighttime data (as for the Izaña Picarro we only use data obtained between midnight and one our after sunrise). Note that we have to interpolate to AERONET data during the nighttime, since the AERONET photometer observations work with direct sunlight.

Izaña’s ground-based FTIR remote sensing system has the capability to resolve the first few kilometres above Izaña. The Izaña AERONET data are representative for similar air masses and can be used for classifying the FTIR data. We use the same threshold levels as for the classification of the Teide Picarro data.

For the classification of the IASI data we also use Izaña’s AERONET data. However, we have to consider that IASI is most sensitive at around 5 km altitude, i.e. an altitude significantly above the location of the Izaña AERONET photometer. In order to have a reasonable proxy for aerosol amounts around 5 km altitude we work with higher AOD threshold values. We use a value below 5 × 10$^{-2}$ for clean conditions and above $1 \times 10^{-1}$ for dust conditions.

A brief overview of the Izaña AERONET data is given in Appendix B (Fig. B3).
5.2.2 Identifying the transport pathways in the water vapour isotopologue data

Figure 14 shows the $\delta$D–H$_2$O plots for the different in situ instruments (from the top to the bottom: ISOWAT, Picarro at Izaña, and Picarro at Teide). The plot is made with the whole data set as shown in Figs. 1 and 2, i.e. it uses among others the 10 min averaged nighttime data measured almost continuously between March 2012 and October 2014. Grey dots represent all measurements. The blue dots (left panels) represent the observations made for clean conditions, i.e. when there is weak/no influence from the African continent. The red dots (right panels) are for observations made for dust conditions, i.e. when the air mass is clearly affected by vertical mixing over Africa.

The top graphs show the ISOWAT data together with simulated $\delta$D–H$_2$O curves. The magenta lines represents values that occur for mixing of two air masses: a humid air mass with MBL values (H$_2$O: 25 000 ppmv; $\delta$D[1] = −80‰ and H$_2$O[2] = 900 ppmv; $\delta$D[2] = −430‰). Second for mixing between H$_2$O[1] = 25 000 ppmv; $\delta$D[1] = −80‰ and H$_2$O[2] = 200 ppmv; $\delta$D[2] = −610‰. The cyan line represents a Rayleigh distillation curve for an initial atmospheric temperature of 25 °C, a relative humidity at the surface of 80 %, and an averaged thermodynamic profile. Rayleigh distillation means that all water that condenses during the transport pathway is immediately removed from the air mass. There is a strong correlation between the ISOWAT water vapour isotopologue data and the aerosol proxy: (1) when vertical mixing over Africa is clearly discernible in the aerosol data, the
ISOWAT δD data group around a mixing line. (2) When the aerosol data reveal no significant vertical mixing over Africa the δD data approximate towards a Rayleigh distillation line (blue dots and cyan line in the top graphs of Fig. 14).

These different transport pathways are also well observed in the in situ isotopologue data sets as collected continuously by the two Picarro at Izaña and Teide. In particular the Picarro at Teide, which is less affected by the local airflows on the island’s mountains, provides very distinct isotopologue fingerprints for the two different situations. The good consistency between the different in situ reference data sets makes this finding very robust.

Figure 15 shows the respective δD–H₂O plots for the MUSICA’s remote sensing data (ground-based FTIR, and IASI). These data are representative for several years. We work with FTIR data measured between 2005 and 2014 and we use IASI-A and IASI-B data measured between October 2007 and the end of July 2013. If compared to the in situ data of Fig. 14 we can again observe the positive bias in the remote sensing δD values. However, the interesting point here is that the δD–H₂O distribution in the remote sensing data sets reveals the different transport pathways similarly to the in situ data sets. This proves that the MUSICA FTIR and IASI δD remote sensing data add scientifically useful information to the respective H₂O measurement and can give valuable insight into tropospheric moisture transport pathways.

A more profound scientific examination of these different transport regimes is out of the scope of this technical validation paper and shall be addressed in an extra paper which is currently in preparation.

6 Conclusions

Global remote sensing of tropospheric δD in addition to H₂O can open up novel opportunities for tropospheric water cycle research. However, the interesting signal of the added value of δD is small. Its detection by remote sensing techniques is a difficult task and prior to a scientific application of the data, their characteristics and uncertainties should be well understood. In this context Schneider et al. (2012) and Wiegele et al. (2014) show detailed feasibility and error assessment studies for MUSICA’s NDACC/FTIR and METOP/IASI water vapour isotopologue products. In this paper those efforts are complemented by an empirical validation exercise taking high-quality in situ measurements as the reference. The study is made in the surroundings of the Canary Islands in the subtropical northern Atlantic.

For a quantitative validation of the random uncertainty and the bias of the remote sensing data we need in situ observations of well-resolved vertical profiles. During an aircraft campaign in July 2013 we produce six of such profiles using the dedicated aircraft instrument ISOWAT, whose extensive pre-, post-, and in-flight calibration modes ensure data of high quality and a very high vertical resolution. With this unprecedented data set and based on the scatter between the coincident ISOWAT and remote sensing observations we can empirically assess the random uncertainty of the NDACC/FTIR δD product to be smaller than 45 and 15 ‰ for the lower and middle troposphere, respectively. For the middle tropospheric METOP/IASI δD product we assess a value of 13 ‰. For the bias assessment we examine systematic dif-
ferences with respect to ISOWAT and find that there is a systematic positive difference of about 30–70 ‰, which is similarly observed for the NDACC/FTIR and the METOP/IASI δD product. For global and more reliable bias and empirical uncertainty estimations we need more reference profiles measured at a variety of globally representative sites (currently we only have six coinciding reference profiles for one single location).

The quantitative comparison to the ISOWAT data does not demonstrate whether the remote sensing δD data is complementary to the remote sensing H2O data. Such complementarity has to be investigated by δD–H2O plots. For these plots we need a large number of data points, thus they are hardly possible by means of only six ISOWAT profiles. Instead we use all the data available from the different instruments since 2005 and pair them with aerosol data that we use as proxy for classifying situations of different moisture pathways. We are able to demonstrate that all the instruments involved in our study (ISOWAT, Picarro at Izaña and Teide, NDACC/FTIR, and METOP/IASI) are able to consistently identify two different free tropospheric water vapour transport pathways. Transport from the PBL via vertical mixing can be identified by isotopologue data that approximate a mixing line on the δD-H2O surface. Such mixing lines occur in all data sets primarily in the presence of large aerosol amounts, which serve as proxy for large scale vertical mixing over the African continent. In contrast, if there are small aerosol amounts we observe primarily δD–H2O curves that approximate a Rayleigh curve, meaning that the respective air masses have been dried by condensation. This is in agreement with a strong inversion layer that hinders mixing from the PBL and prevailing moisture transport from higher latitudes and altitudes.

Our study proves that the MUSICA H2O and δD remote sensing data are a reliable tool for water vapour isotopologue studies. However, we have to be aware that there is very likely a bias in the δD values. For a better understanding of this bias further research on the spectroscopic line parameters as well as more high-quality aircraft profiles and thus further campaigns and validation efforts would be desirable.

We would like to propose using the approaches as presented in this paper, in Schneider et al. (2012), and in Wiegele et al. (2014) as guideline for best practice when validating water vapour isotopologue remote sensing data sets.
Appendix A: Discussion of day 130731

On day 130731 there are five IASI observations that fulfil our temporal and spatial coincidence criteria. The respective IASI pixels are depicted in Fig. 5 in magenta as filled symbols. Square symbols are for IASI-A pixels and diamonds are for IASI-B pixels. They group at two different locations. The first group (two IASI-A pixels) is located west of the aircraft’s flight track and the second group (one IASI-A pixel and two IASI-B pixels) is located southeast of the flight track. The latter pixels are marked by black edges. The magenta symbols as shown in Fig. 11 have the same marking. The three data points where the ISOWAT versus IASI agreement for H$_2$O is poor belong to the marked pixels (left panel of Fig. 11), i.e. to the observation made southeast of the flight track. There is consistency between the IASI-A observation and the two IASI-B observations, but all three observations are in disagreement with the ISOWAT observation. Such outliers are not seen in the ISOWAT versus IASI plot for δD (right panel of Fig. 11). There all five IASI observations on day 130731 agree well with the ISOWAT observations.

The issue can be understood by a look at Fig. A1. It shows MODIS (Moderate Resolution Imaging Spectroradiometer) images for the Canary Islands on the three consecutive days between day 130730 and 130801. On day 130730 (left image) the air is rather clean, which is the typical situation for an air mass travelling from the Atlantic northwest of the islands. In contrast, on day 130801 (right image) there is a lot of dust in the air, indicating that the free tropospheric air mass over the Canaries has its origin in the boundary layer over the Sahara desert (located just a few hundred kilometres east of the islands). Day 130731, when we observe the H$_2$O outliers, is a transition day. During this day the Sahara boundary layer air mass is mixing with the free tropospheric Atlantic air mass. The central panel of Fig. A1 documents that there is a strong gradient in the dust concentration from southeast of ISOWAT’s flight track – where the air has mainly the dust-laden Saharan characteristics – to west of the flight track – where the air is still rather clean.

The two groups of IASI pixels on day 130731 are located in areas with different atmospheric situations. West of ISOWAT’s flight track the mixing between dry and clean air with humid and dust-laden air has just begun, meaning that H$_2$O started to increase and δD has strongly increased (during a mixing from dry to humid δD is rapidly determined by the humid end member, see also mixing lines in Figs. 12, 14, and 15). Southeast of the flight track the mixing process is already more advanced and the air mass has almost the characteristics of the humid mixing end member, i.e. both H$_2$O and δD are strongly increased.

The three outliers as seen in Fig. 11 are due to spatial inhomogeneities in the atmospheric water vapour state on day 130731. We show that the high temporal and spatial resolution of IASI allows resolving these inhomogeneities and that IASI-A and IASI-B can observe the responsible moisture transport pathway in a consistent manner.
Figure A1. Images for the Canary Islands on three consecutive days (130730, 130731, and 130801). Images are daily composites of data of the Moderate Resolution Imaging Spectroradiometer (MODIS) aboard the NASA Terra and Aqua satellites. Source: https://earthdata.nasa.gov/labs/worldview/.
Appendix B: The aerosol data sets

The INTA aerosol instrument provides the aerosol number density for different particle sizes, whereby different particle sizes ranging from 0.5 to 50 µm diameter can be distinguished. From these data we calculate the aerosol volume concentration for all the aerosols with a diameter smaller than 10 µm (this volume concentration is called $V_{10}$), whereby we assume spherical aerosols. The respective data measured during the six flights above the boundary layer (above 1500 m a.s.l.) are plotted in Fig. B1. Please note that there are many occasions with $V_{10} = 0$ µm$^3$ cm$^{-3}$ (aerosol number density below the detection limit) that are not visible in the graph.

The Izaña PM$_{10}$ data are hourly averaged mass concentration data and given as aerosol mass per air volume. Figure B2 shows the 2012–2014 time series. The mass concentrations are determined from the continuously measured aerosol size distributions (applying the instrument APS, TSI™, model 3321). First the aerosol volume concentrations ($V_{10}$) are calculated. From $V_{10}$ the mass concentration (PM$_{10}$) is obtained by using an empirically estimated aerosol effective density using the methods described by Rodríguez et al. (2012). This density estimation consists in correlating the measured aerosol volume concentrations to mass concentrations measured by the gravimetric method. For the gravimetric method PM$_{10}$ aerosols are collected in microfibre quartz filters. This collection needs several hours and requires a careful treatment of the filters, hence the gravimetric method cannot be performed continuously. The Izaña programme for in situ aerosol characterization was audited by the World Calibration Centre for Aerosol Physics (WCCAP; Institute for Tropospheric Research, Leipzig) in November 2006. For more details on these PM$_{10}$ data please refer to Rodríguez et al. (2011).

The Aerosol Robotic Network (AERONET) provides atmospheric aerosol properties at several wavelengths (Holben et al., 1998). The Cimel CE-318 sun photometer is the standard instrument in the network. It measures direct sun irradiance (every 15 min) with a $1.2^\circ$ full field of view that is used to compute aerosol optical depth (AOD) for each wavelength available on each photometer type. Three quality levels of AERONET data are available: level 1.0 (real time raw data), level 1.5 (real time cloud screened data), and level 2.0 (quality assured data). Figure B3 shows the time series of AOD at 500 nm as measured at the Izaña observatory.
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