Abstract—This paper presents the design and development of proof-of-concept Device-to-Device (D2D) Communication testbed. This testbed also seeks to address the design issues involved in the implementation of a D2D network in a realistic scenario. The performance of this testbed has been validated by emulating a Cellular network consisting of a Base Station (BTS) and many D2D devices in its proximity. The devices and the BTS coordinate and communicate with each other to select the optimum communication range, mode of communication and transmit parameters. Through the experimental results it has been shown that the proposed testbed has a communication radius of 120m and a D2D communication range of 62m with over 90% efficiency.

I. INTRODUCTION

Every natural calamity reminds us of our heavy dependence on infrastructure for information dissemination, and the need of easily deployable emergency communication services. In any catastrophic natural calamity, communication services are plagued by last mile connectivity issues and destruction of infrastructure. For instance, after Nepal earthquake [1] and Siachun earthquake in China [2], most of cellular infrastructure became inoperable within minutes.

This motivates the use of a cellular service that is minimally dependent on network infrastructure. D2D communication is one such service. In a typical D2D communication scenario, the user equipment (UE) within the D2D range exchange data directly through the D2D link circumventing the BTS, thus achieving high data rate, and low latency as compared to conventional cellular services. It also reduces the load on the network and provides robustness against infrastructure failures [3]. Additionally, inclusion of relays in D2D network enhances the capacity and coverage of networks [4].

Fig. 1. A Typical D2D Communication Scenario, With a Relay

II. EXPERIMENTAL SETUP

This section discusses the experimental setup of our testbed. Atmega328p [8] based microcontroller board was used for modeling user equipments (UEs) or devices. Separate transceivers were used for D2D and BTS-UE communication. CC2500 based transceiver [7] was used for D2D communication due to its high power efficiency and small communication range. Zigbee transceivers [6] were used for

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BTS-UE communication because of communication range and device addressing capability. The BTS was modeled using serial communication enabled software [9]. The presented testbed operates in the ISM bands of 2.4GHz. The Forward Error Correction (FEC) Coding feature was enabled to reduce the packet errors. With FEC the obtained data rate is 57.6 k Baud.

The BTS on the basis of Received Signal Strength Indicator (RSSI) value of packets decides the following:
(a) Whether D2D communication is feasible.
(b) If (a) is true, then whether it should take place through a direct link or through a relay.

III. EXPERIMENTAL RESULTS AND ANALYSIS

This section describes the experimental results and analyses for D2D testbed. To test BTS-UE link, we have transmitted 50 packets from different distances and have accounted the RSSI value of each packet, which gives us an estimate of the communication range and efficiency of the link:

A. RSSI vs Distance: As the distance between the BTS and UE increases, the RSSI value decreases and the variance of RSSI increases. It is primarily due to the path loss in the wireless channel and decreasing SNR at larger distances. The RSSI value is used to estimate the approximate distance between the BTS and UE within the cell. Based on this model, the BTS can predict the possibility of D2D communication between different devices by setting a threshold RSSI value.

B. Efficiency vs Distance: Similar to experimental results obtained in [11] we observed that as RSSI decreases the packet drop count increases. Results from Fig. 3. helped us estimate the cell radius, and the range of D2D communication with/without relay. From the data collected, we conclude the cell radius is approximately 120m which caters to an area of 0.045km² with an efficiency threshold of 85%. We also observed that the D2D range without relay which was 30m with efficiency threshold of 90% got extended by almost twice to 62m when relays were incorporated. Additionally, a steeper drop in packet efficiency in case of D2D without relay was observed as compared to the case of D2D with relay. Here, efficiency is: \((\text{Number of packets received correctly}/\text{Number of packets transmitted}) \times 100\).

C. Power Consumption metric

| Power Consumption (D2D Feature ON) | 385.2mW |
|-----------------------------------|---------|
| Power Consumption (D2D Feature OFF) | 234mW   |
| Active time (D2D Feature ON)      | 13.75hr |
| Standby-time (D2D Feature Off)    | 22.64hr |

Table 1. Power consumption and Operation time metric of testbed in various operation modes

Table 1. shows the power consumption of modules with in both modes i.e., with D2D feature ON and OFF. Standby times were measure using a 5.3Wh 3.6V battery as reference.

IV. CONCLUSIONS

An experimental testbed for D2D communication was designed and implemented using IEEE802.15.4 and 2.4 GHz RF Transceivers. The results and analysis indicate that the testbed is highly scalable and can be implemented in a real world scenario by following a similar approach. Highly portable architecture of this testbed enables it to be readily deployed in a disaster stricken area to provide immediate communication services. The range of the testbed can be further extended by incorporating more devices, large power amplifiers and powerful antennas. By using sophisticated algorithms and Software Defined Radio platforms the concepts of network coding and cognitive radio networks can be applied to make the system more advanced and secure.

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