We are interested in studying multidimensional hyperbolic equations with nonlocal integral and Neumann or nonclassical conditions. For the approximate solution of this problem first and second order of accuracy difference schemes are presented. Stability estimates for the solution of these difference schemes are established. Some numerical examples illustrating applicability of these methods to hyperbolic problems are given.

1. Introduction

In the last decades, for the development of numerical methods and theory of solutions of the hyperbolic problems with nonlocal integral, Neumann and nonclassical conditions have been an important research topic in many natural phenomena. Solutions of this type of hyperbolic problems were investigated in [1–13]. These problems were studied in various directions: qualitative properties of solutions, spectral problems, various statements of boundary value problems, and numerical investigations.

For example, in [5] the nonlocal boundary value problem
\[ \frac{d^2 u(t)}{dt^2} + A u(t) = f(t), \quad 0 \leq t \leq 1, \]
\[ u(0) = \sum_{r=1}^{n} \alpha_r u(\lambda_r) + \varphi, \quad u_t(0) = \sum_{r=1}^{n} \beta_r u_t(\lambda_r) + \psi, \quad (1) \]
was investigated. The stability estimates for the solution of the problem were established. The first order of accuracy difference schemes for the approximate solution of this problem was presented. The stability estimates for the solution of these difference schemes were established. Theoretical statements were supported by numerical examples.

The well-posedness of the Cauchy problem, Goursat problem, and boundary value problem for multidimensional hyperbolic equations have been studied extensively in a large cycle of papers (see, e.g., [14–21] and the references therein).

Actually, in paper [14], the Goursat problem for a linear multidimensional hyperbolic equation was investigated. Uniqueness of the solution and weak solvability of the Goursat problem were established.

In paper [15], the existence or nonexistence of global solutions of a multidimensional version of the first Darboux problem for wave equations with power nonlinearity in the conic domain was investigated.

In [16, 17], the solvability of an initial-boundary value problem for second order linear hyperbolic equations with a condition on the lateral boundary connecting the values of the solution or the conormal derivative of the solution with the values of some integral operator of the solution was studied. The existence and uniqueness theorems for regular solutions were proved.

In [18–20], the difference schemes for multidimensional hyperbolic equations were investigated. These methods were stable under the inequalities and contain the connection between the grid step sizes of time and space variables.

In [21], the authors develop a finite difference method (FDM) for a multidimensional coupled system of nonlinear parabolic and hyperbolic equations and prove the existence,
stability, and uniqueness of its solution by a set of theorems. Finally, the proposed method was illustrated by a number of numerical experiments.

The study of difference schemes for hyperbolic equations with nonlocal conditions without using any necessary condition concerning the grid step sizes is of great interest. Such a difference scheme for solving the initial-value problem for abstract hyperbolic equations was studied for the first time in [22]. In the present paper, the following multidimensional hyperbolic equation

\[
\frac{\partial^2 u(t, x)}{\partial t^2} - \sum_{r=1}^{m} (a_r(x) u_{x_r})_{x_r} + \sigma u(t, x) = f(t, x),
\]

\(x = (x_1, \ldots, x_m) \in \Omega, \quad 0 < t < 1,
\]

with nonlocal integral

\[
u(0, x) = \int_{0}^{1} \alpha(\rho) u(\rho, x) d\rho + \varphi(x), \quad x \in \overline{\Omega},
\]

\[
u_t(0, x) = \int_{0}^{1} \beta(\rho) u_t(\rho, x) d\rho + \psi(x), \quad x \in \overline{\Omega},
\]

and Neumann

\[
\frac{\partial u(t, x)}{\partial \mathbf{n}} \Big|_{S_1} = 0
\]

or nonclassical conditions

\[
u(t, x) \Big|_{S_1} = 0,
\]

\[
\frac{\partial u(t, x)}{\partial \mathbf{n}} \Big|_{S_2} = 0, \quad 0 \leq t \leq 1,
\]

under the assumption

\[
1 + \int_{0}^{1} \alpha(s) \beta(s) ds > \int_{0}^{1} (|\alpha(s)| + |\beta(s)|) ds
\]

is considered. Here, \(\Omega\) is the unit open cube in the \(m\)-dimensional Euclidean space \(\mathbb{R}^m\) with boundary \(S = S_1 \cup S_2, \overline{\Omega} = \Omega \cup S, a_r(x) (x \in \Omega), \varphi(x), \psi(x) (x \in \overline{\Omega}),\) and \(f(t, x) (t \in (0, 1), x \in \Omega)\) are given smooth functions, and \(a_r(x) \geq a > 0.\) \(\mathbf{n}\) is the normal vector to \(\Omega.\)

The first and second order of accuracy difference schemes for multidimensional hyperbolic problem (2) are presented. The schemes are shown to be absolutely stable. It is naturally seen that the second order difference schemes are much more advantageous than the first order ones.

2. Stability of First Order of Accuracy Difference Scheme

For approximately solving problem (2), first order of accuracy difference scheme

\[
\tau^{-2} (u_{k+1} - 2u_k + u_{k-1}) + A u_{k+1} = f_k, \quad f_k = f(t_{k+1}),
\]

\(t_{k+1} = (k + 1) \tau, \quad 1 \leq k \leq N - 1, \quad N \tau = 1,
\]

\([u_0 = \sum_{j=1}^{N} \alpha(t_j) u_j \tau + \varphi, \quad \nu(t_0, x) = \sum_{j=1}^{N} \beta(t_j) (u_j - u_{j-1}) + \psi,
\]

\(I + \tau^2 A) \tau^{-1} (u_1 - u_0) = \sum_{j=1}^{N} \beta(t_j) (u_j - u_{j-1}) + \psi
\]

is considered. A study of discretization of the nonlocal boundary value problem also permits one to include general difference schemes in applications, if differential operator in space variables \(A\) is replaced by difference operator \(A h\) that acts in a Hilbert space and is uniformly self-adjoint positive definite in \(h\) for \(0 < h \leq h_0.\)

The stability estimates of solution of difference scheme (7) are established under the assumption

\[
1 > \sum_{j=1}^{N} |\alpha(t_j)| + \tau \sum_{j=1}^{N} |\beta(t_j)| \tau + \sum_{j=1}^{N} |\alpha(t_j)| \tau + \sum_{j=1}^{N} |\beta(t_j)| \tau.
\]

Lemma 1. The following estimates hold [23]:

\[
\|R\|_{H^{-H}} \leq 1, \quad \|\tilde{R}\|_{H^{-H}} \leq 1,
\]

\[
\|R \tilde{R}^{-1}\|_{H^{-H}} \leq 1, \quad \|R \tilde{R}^{-1}\|_{H^{-H}} \leq 1,
\]

\[
\|\tau A^{1/2} R\|_{H^{-H}} \leq 1, \quad \|\tau A^{1/2} \tilde{R}\|_{H^{-H}} \leq 1,
\]

where

\[
R = (I + i \tau A^{1/2})^{-1}, \quad \tilde{R} = (I - i \tau A^{1/2})^{-1}.
\]

Lemma 2. The operator

\[
T = I + \sum_{j=1}^{N} \beta(t_j) \tau^2 R^{2} (R^{j} + \tilde{R}^{j})
\]

\[
- \sum_{j=1}^{N} \alpha(t_j) \tau^2 [R^{j+1} - \tilde{R}^{j+1}]
\]

\[
- \sum_{j=1}^{N} \alpha(t_j) \tau^{N} \beta(t_j) \tau (R \tilde{R})^{j+2}
\]
has an inverse

\[ T^{-1} = \left\{ I + \sum_{j=1}^{N} \beta(t_j) \frac{\tau}{2} R^2 \left( R^t + \tilde{R}^t \right) \right\}^{-1} \]

\[ - \sum_{j=1}^{N} \alpha(t_j) \frac{\tau}{2} \left[ R^{t-1} - \tilde{R}^{t-1} \right] \]

\[ - \sum_{j=1}^{N} \alpha(t_j) \frac{\tau}{2} \sum_{j=1}^{N} \beta(t_j) \tau (\tilde{R}^t)^{i-2} \]

and the following estimate is satisfied:

\[ \| T^{-1} \|_{H \rightarrow H} \leq (1) \times \left( 1 - \sum_{j=1}^{N} |\alpha(t_j)| \frac{\tau}{2} \sum_{j=1}^{N} |\beta(t_j)| \tau \right) \]

\[ - \sum_{j=1}^{N} |\beta(t_j)| \tau - \sum_{j=1}^{N} |\alpha(t_j)| \tau \]

\[ \| T^{-1} \|_{H \rightarrow H} \]

\[ \leq 1 - \sum_{j=1}^{N} |\alpha(t_j)| \frac{\tau}{2} \sum_{j=1}^{N} |\beta(t_j)| \tau \]

\[ \| T^{-1} \|_{H \rightarrow H} \}

\[ \| T^{-1} \|_{H \rightarrow H} \]

\[ \left( I + \tau^2 A \right) \tau^{-1} \left( u_1 - u_0 \right) = \omega, \]

\[ \begin{align*}
\tau^{-2} (u_{k+1} - u_k) + A u_{k+1} &= f_k , \\
f_k &= f(t_{k+1}) , \quad t_{k+1} = (k + 1) \tau , \\
1 \leq k &\leq N - 1, \quad N \tau = 1 , \\
u_0 &= \mu , \\
u_1 &= \mu + \tau R \tilde{R} \omega ,
\end{align*} \]

\[ u_k = \frac{1}{2} \left[ R^{k-1} + \tilde{R}^{k-1} \right] \mu + \left( R - \tilde{R} \right)^{-1} \tau \left( R^{k} - \tilde{R}^{k} \right) \omega \]

\[ \sum_{s=1}^{k-1} \frac{\tau}{2i} A^{-1/2} \left[ R^{k-s} - \tilde{R}^{k-s} \right] f_s , \quad 2 \leq k \leq N , \]

were obtained in [22]. Applying formula (20) and nonlocal boundary conditions in (7), we can write formula for \( \mu \) and \( \omega \)

\[ \mu = T^{-1} \left[ \left[ \alpha \left( \tau \right) + \sum_{j=1}^{N} \alpha(t_j) \right] \tau \right. \]

\[ \times \sum_{s=1}^{i-1} \frac{\tau}{2i} A^{-1/2} \left[ R^{i-s} - \tilde{R}^{i-s} \right] f_s + \phi \]

\[ \left. \times \left[ I + \sum_{j=1}^{N} \beta(t_j) \frac{\tau}{2} R \tilde{R} \left( R^t + \tilde{R}^t \right) \right] \right\]
\[
+ \sum_{j=1}^{N} \alpha(t_j) \tau^2 (R - \bar{R})^{-1} (R^j - \bar{R}^j) \\
\times \frac{1}{2} \sum_{s=1}^{N} \left[ R^{j-s} - \bar{R}^{j-s} \right] f_s \\
- \sum_{j=1}^{N} \beta(t_j) \frac{\tau}{2l} (R - \bar{R}) A^{-1/2} f_{j-1} + \psi \\
\omega = T^{-1} \left\{ \left[ I - \sum_{j=1}^{N} \alpha(t_j) \frac{\tau}{2} \left[ R^{j-1} - \bar{R}^{j-1} \right] \right] \right. \\
\left. \times \left[ \left[ \beta(\tau) + \beta(2\tau) + \sum_{j=3}^{N} \beta(t_j) \right] \right. \\
\times \frac{\tau^2}{2} \sum_{s=1}^{N} \left[ R^{j-s} - \bar{R}^{j-s} \right] f_s \\
- \sum_{j=1}^{N} \beta(t_j) \frac{\tau}{2l} (R - \bar{R}) A^{-1/2} f_{j-1} + \psi \right\} \\
+ \sum_{j=1}^{N} \beta(t_j) \frac{\tau}{2} A^{1/2} \left[ R^{j-1} - \bar{R}^{j-1} \right] \\
\times \left[ \left[ \alpha(\tau) + \sum_{j=2}^{N} \alpha(t_j) \right] \right. \\
\left. \times \frac{\tau}{2l} A^{-1/2} \left[ R^{j-s} - \bar{R}^{j-s} \right] f_s - \varphi \right\}. \\
\]

Hence, for the solution of nonlocal boundary value problem (7) we have formulas (20), (21), and (22).

Second, let us investigate stability of difference scheme (7). In [22], for the solution of (19) stability estimates

\[
\max_{0 \leq k \leq N} \| u_k \|_{H^2} \leq M \left\{ \sum_{s=1}^{N-1} \| A^{-1/2} f_s \|_{H^2} + \| A^{-1/2} \varphi \|_{H^2} \right\}, \\
\max_{1 \leq k \leq N} \| r^{-1} (u_k - u_{k-1}) \|_{H^2} + \max_{0 \leq k \leq N} \| A^{1/2} u_k \|_{H^2} \\
\leq M \left\{ \sum_{s=1}^{N-1} \| f_s \|_{H^2} + \| \varphi \|_{H^2} + \| A^{1/2} \varphi \|_{H^2} \right\}, \\
\max_{1 \leq k \leq N} \| r^{-1} (u_k - u_{k-1}) \|_{H^2} + \max_{0 \leq k \leq N} \| A^{1/2} u_k \|_{H^2} \\
\leq M \left\{ \sum_{s=1}^{N-1} \| f_s \|_{H^2} + \| \varphi \|_{H^2} + \| A^{1/2} \varphi \|_{H^2} \right\}. \\
\]

Using the triangle inequality, formula (27), and estimates (9), it follows that

\[
\| A^{-1/2} \varphi \|_{H^2} \leq M \left\{ \sum_{j=1}^{N-1} \| A^{-1/2} f_s \|_{H^2} + \| A^{-1/2} \psi \|_{H^2} + \| \varphi \|_{H^2} \right\}. \\
\]

So, estimate (16) follows from estimates (23), (26), and (28). Second, applying \( A^{1/2} \) to formula (21) and using estimates (9), we get estimate

\[
\| A^{1/2} \varphi \|_{H^2} \leq M \left\{ \sum_{j=1}^{N-1} \| f_j \|_{H^2} + \| \varphi \|_{H^2} + \| A^{1/2} \varphi \|_{H^2} \right\}. \\
\]
By using formula (22) and estimates (9), we obtain

\[
\|ω\|_H \leq M \left\{ \sum_{j=1}^{N-1} \|f_j\|_H \tau + \|ψ\|_H + \left\| A^{1/2} \varphi \right\|_H \right\}. 
\]

(30)

Using estimates (24), (29), and (30), we obtain estimate (17) for the solution of (7). Third, applying \( A \) to formula (21) and using Abel’s formula, we can write formula for \( A\mu \)

\[
A\mu = T^{-1} \left\{ \left[ \alpha(\tau) + \sum_{j=1}^{N-1} \alpha(t_j) \right] \tau 
\right. 

\times \left[ \sum_{s=2}^{j-1} \frac{1}{2} \left[ R_{j-s}^i - R_{j-s}^i \right] (f_s - f_{s-1}) 
\right.

\left. + \left( R_{j-s}^i - R_{j-s}^i \right) f_1 - (R - R) f_{j-1} + A\varphi \right\] 

\times \left[ I + \sum_{j=1}^{N} \beta(t_j) \frac{\tau}{2} 2R \left( R^i + R^i \right) \right] 

\times \left[ \alpha(t) \right. 

\times \left[ \sum_{s=2}^{j-1} \frac{1}{2} \left[ R_{j-s}^i - R_{j-s}^i \right] (f_s - f_{s-1}) 
\right.

\left. + \left( R_{j-s}^i - R_{j-s}^i \right) f_1 - (R - R) f_{j-2} \right. 

\left. + \sum_{j=1}^{N} \beta(t_j) f_{j-1} + A^{1/2} \psi \right\} 

\left. \right\} \right]. \]

(33)

It follows from formula (31) and estimates (9) that

\[
\left\| A^{1/2} \omega \right\|_H \leq M \left\{ \sum_{s=2}^{N-1} \left\| f_s - f_{s-1} \right\|_H + \left\| f_1 \right\|_H + \left\| A^{1/2} \psi \right\|_H + \left\| A\varphi \right\|_H \right\}. 
\]

(32)

Applying \( A^{1/2} \) to formula (22) and using Abel’s formula, we get

\[
A^{1/2} \omega = T^{-1} \left\{ \left[ I - \sum_{j=1}^{N} \alpha(t_j) \frac{\tau}{2} \left( R_{j-s}^i - R_{j-s}^i \right) \right] \right\} \right\} \right]. \]

(34)

Thus, estimate (18) follows from estimates (23), (32), and (34). This is the end of the proof of Theorem 3.

3. Stability of Second Order of Accuracy Difference Scheme

Now, we consider the second order accuracy difference scheme for approximate solution of boundary value problem (2)

\[
\tau^{-2} (u_{k+1} - 2u_k + u_{k-1}) + \frac{1}{2} A u_k + \frac{1}{4} A (u_{k+1} + u_{k-1}) = f_k, 
\]

\[
f_k = f(t_k), \quad t_k = k\tau, \quad 1 \leq k \leq N - 1, \quad N\tau = 1, 
\]

\[
u_0 = \sum_{j=1}^{N} \alpha(t_j) \frac{\tau}{2} \left[ \frac{u_j + u_{j-1}}{2} \right] \tau + \varphi, 
\]
The stability of solutions of this difference scheme is investigated under the assumption

\[
1 > \sum_{j=1}^{N} |\alpha(j - \frac{T}{2})| R + \sum_{j=1}^{N} |\beta(j - \frac{T}{2})| R
+ \sum_{j=1}^{N} |\alpha(j - \frac{T}{2})| \sum_{j=1}^{N} |\beta(j - \frac{T}{2})| R.
\]  

Lemma 4. The following estimates hold [23]:

\[
\left\| (I \pm i \tau A^{1/2})^{-1} \right\|_{H-H} \leq 1,
\]

\[
\| R \|_{H-H} \leq 1, \quad \| \bar{R} \|_{H-H} \leq 1, \quad \| R \|_{H-H} \leq 1,
\]

where

\[
R = \left( I - \frac{i \tau A^{1/2}}{2} \right) \left( I + \frac{i \tau A^{1/2}}{2} \right)^{-1},
\]

\[
R = \left( I + \frac{i \tau A^{1/2}}{2} \right) \left( I - \frac{i \tau A^{1/2}}{2} \right)^{-1}.
\]

Lemma 5. Suppose that assumption (36) holds. Then, the operator

\[
T = I - \left\{ \alpha \left( \frac{T}{2} \right) + \left[ \alpha \left( \frac{T}{2} \right) + \alpha \left( \frac{3T}{2} \right) \right] \frac{R + \bar{R}}{2} \right\}
\]

\[
+ \alpha \left( \frac{3T}{2} \right) \frac{R + \bar{R}}{2} \right\}
\]

\[
+ \sum_{j=3}^{N} \alpha(j - \frac{T}{2}) \frac{R^j + \bar{R}^j + \bar{R}^{-j} + R^{-j}}{2} \frac{T}{2}
\]

\[
- \left\{ \beta \left( \frac{T}{2} \right) - \beta \left( \frac{3T}{2} \right) \right\} \left( \frac{R + \bar{R}}{2} \right)
\]

\[
+ \beta \left( \frac{3T}{2} \right) \frac{R + \bar{R}}{2} \right\}
\]

\[
+ A^{-1/2} \sum_{j=3}^{N} \beta(j - \frac{T}{2}) \frac{R^j - \bar{R}^j + \bar{R}^{-j} + R^{-j}}{2} \frac{T}{2}
\]

has an inverse \(T^{-1}\) and the following estimate is satisfied:

\[
\| T^{-1} \|_{H-H} \leq \left\| \left[ 1 - \sum_{j=1}^{N} |\alpha(j - \frac{T}{2})| R + \sum_{j=1}^{N} |\beta(j - \frac{T}{2})| R \right]^{-1} \right\|
\]

\[
- \sum_{j=1}^{N} |\beta(j - \frac{T}{2})| R - \sum_{j=1}^{N} |\alpha(j - \frac{T}{2})| R
\]

\[
\geq 1 - \left\{ \alpha \left( \frac{3T}{2} \right) + \left[ \alpha \left( \frac{T}{2} \right) + \alpha \left( \frac{3T}{2} \right) \right] \right\} \frac{R + \bar{R}}{2} \| H-H \|
\]
Let \( \phi \in D(A) \), \( \psi \in D(A^{1/2}) \), and assumption (36) hold. For the solution of difference scheme (3) the following stability estimates

\[
\max_{0 \leq k \leq N} \| u_k \|_H \leq M \left\{ \sum_{s=0}^{N-1} \| A^{-1/2} f_s \|_H \tau + \| A^{-1/2} \psi \|_H + \| \phi \|_H \right\},
\]

\[
\max_{1 \leq k \leq N} \| r^{-1} (u_k - u_{k-1}) \|_H + \max_{0 \leq k \leq N} \| A^{1/2} u_k \|_H \leq M \left\{ \sum_{s=0}^{N-1} \| f_s \|_H \tau + \| A^{1/2} \psi \|_H + \| \psi \|_H \right\},
\]

\[
\max_{1 \leq k \leq N-1} \| r^{-2} (u_{k+1} - 2u_k + u_{k-1}) \|_H + \max_{1 \leq k \leq N} \| A u_k + u_{k-1} \|_H \leq M \left\{ \sum_{s=1}^{N-1} \| f_s - f_{s-1} \|_H + \| f_0 \|_H + \| A^{1/2} \psi \|_H + \| A \phi \|_H \right\}
\]

are valid, where \( M \) is independent of \( f_s \), \( 0 \leq s \leq N - 1 \), and \( \phi \), \( \psi \).
Proof. We obtain formula for the solution of difference scheme (3). For the solution of difference scheme

\[
\tau^{-2}(u_{k+1} - 2u_k + u_{k-1}) + \frac{1}{2}Au_k + \frac{1}{4}A(u_{k+1} + u_{k-1}) = f_k,
\]

\[
f_k = f(t_k), \quad t_k = k\tau, \quad 1 \leq k \leq N - 1, \quad N\tau = 1,
\]

\[
u_0 = \mu, \quad \left(I + \frac{\tau^2 A}{4}\right)^{-1}(u_1 - u_0) + \frac{\tau}{2}(Au_0 - f_0) = \omega,
\]

(45)

the following formulas

\[
u_0 = \mu,
\]

\[
u_1 = \left(I + \frac{\tau^2 A}{4}\right)^{-1}\left((I - \frac{\tau^2 A}{4})\mu + \tau\omega + \frac{\tau}{2}f_0\right),
\]

\[
u_k = \frac{1}{2}[R^k + \tilde{R}^k]\mu + \frac{1}{2A^{1/2}}[R^k - \tilde{R}^k]\left(\omega + \frac{\tau}{2}f_0\right) - \sum_{j=3}^{k-1}A^{-1/2}[R^{k-j} - \tilde{R}^{k-j}]f_j, \quad 2 \leq k \leq N,
\]

(46)

were obtained in [22]. Applying formula (46) and nonlocal boundary conditions in (3), we obtain formulas

\[
u = T^{-1}\left\{I - \left[\beta\left(\frac{\tau}{2}\right) - \beta\left(\frac{3\tau}{2}\right)\right]\left(I + \frac{\tau^2 A}{4}\right)^{-1}\tau
\]

\[+ \beta\left(\frac{3\tau}{2}\right)iA^{-1/2}\frac{R^2 - \tilde{R}^2}{2}
\]

\[+ \sum_{j=3}^{N}\beta(t_j - \frac{\tau}{2})iA^{-1/2}
\]

\[\times \frac{R^i - \tilde{R}^{i} + \tilde{R}^{i-1} - R^{i-1}}{2i}\right]\right]\right]\right]\right]\right],
\]

\[
\times \left\{\left[\alpha\left(\frac{\tau}{2}\right) + \alpha\left(\frac{3\tau}{2}\right) + \alpha\left(\frac{3\tau}{2}\right)A^{-1/2}\frac{R^2 - \tilde{R}^2}{2i}\right)
\]

\[+ \alpha\left(\frac{3\tau}{2}\right)\left(\frac{R^2 + \tilde{R}^2}{2}\right)
\]

\[+ \sum_{j=3}^{N}\alpha(t_j - \frac{\tau}{2})A^{-1/2}
\]

\[\times \frac{R^i - \tilde{R}^i + R^{i-1} - \tilde{R}^{i-1}}{2i}\right]^2f_0
\]

\[- \alpha\left(\frac{3\tau}{2}\right)\frac{\tau^2}{2i}A^{-1/2}(R - \tilde{R})f_1 - \sum_{j=3}^{N}\alpha(t_j - \frac{\tau}{2})\frac{\tau}{2}
\]

\[
\times \left[\sum_{s=1}^{j-2}A^{-1/2}\left[R^{i-s} - R^{i-s} + R^{i-s-1} - \tilde{R}^{i-s-1}\right]f_s
\]

\[+ \frac{\tau}{2i}R - \tilde{R} f_{j-1}\right]\right\} + \varphi\right]\right]\right],
\]

(47)

\[
\omega = T^{-1}\left\{I - \left[\alpha\left(\frac{\tau}{2}\right) + \alpha\left(\frac{3\tau}{2}\right) + \alpha\left(\frac{3\tau}{2}\right)\right]\left(R + \tilde{R}\right)
\]

\[+ \alpha\left(\frac{3\tau}{2}\right)\left(\frac{R^2 + \tilde{R}^2}{2}\right)
\]

\[+ \sum_{j=3}^{N}\alpha(t_j - \frac{\tau}{2})\frac{R^i + R^{i+1} + \tilde{R}^{i+1} - \tilde{R}^{i+1}}{2i}\right]f_0 \right\}
\]

\[
\times \left\{\left[\beta\left(\frac{\tau}{2}\right) - \beta\left(\frac{3\tau}{2}\right)\right]\left(I + \frac{\tau^2 A}{4}\right)^{-1}\tau
\]

\[+ \frac{\tau}{2i}R - \tilde{R} f_{j-1}\right]\right\} + \varphi\right]\right]\right],
\]

(47)
\[
+ \sum_{j=3}^{N} \beta \left( t_j - \frac{\tau}{2} \right) R^{-1/2} f_0 \\
\times \frac{R^i - \overline{R}^i + \overline{R}^{i-1} - R^{i-1}}{2} \\
+ \left\{ i \tau R^{-1/2} \frac{R - \overline{R}}{2} \\
\times \left[ \beta \left( \frac{3\tau}{2} \right) f_i + \sum_{j=3}^{N} \beta \left( t_j - \frac{\tau}{2} \right) f_{j-1} \right] \\
+ i \tau R^{-1/2} \sum_{j=3}^{N} \beta \left( t_j - \frac{\tau}{2} \right) \right\} f_s + \psi
\]

Hence, for the solution of nonlocal boundary value problem (3) we have formulas (46), (47), and (48).

Now, let us investigate the stability of difference scheme (3). In [22], for the solution of (45) the following stability estimates

\[
\max_{0 \leq k \leq N} \| u_k \|_H \leq M \left\{ \sum_{s=0}^{N-1} \| A^{-1/2} f_s \|_H \tau + \| A^{-1/2} \omega \|_H + \| \mu \|_H \right\},
\]

\[
\max_{1 \leq k \leq N} \| r^{-1} (u_k - u_{k-1}) \|_H + \max_{1 \leq k \leq N} \| A^{1/2} u_k \|_H \leq M \left\{ \sum_{s=0}^{N-1} \| f_s - f_{s-1} \|_H + \| f_0 \|_H + \| A^{1/2} \omega \|_H + \| A \mu \|_H \right\}
\]

were established. Now, from formula (47) and estimates (37) it follows that

\[
\| \mu \|_H \leq M \left\{ \sum_{s=0}^{N-1} \| A^{-1/2} f_s \|_H \tau + \| A^{-1/2} \psi \|_H + \| \varphi \|_H \right\}
\]

Applying $A^{-1/2}$ to formula (48), we get

\[
A^{-1/2} \omega = T^{-1} \left\{ \left[ I - \left[ \alpha \left( \frac{\tau}{2} \right) + \alpha \left( \frac{3\tau}{2} \right) \right] \left( \frac{R + \overline{R}}{2} \right) \right] \\
\times \left[ \frac{\tau^2}{4} f_0 \right] \\
+ \alpha \left( \frac{3\tau}{2} \right) \frac{\tau^2}{4i} \langle R - \overline{R} \rangle f_i \\
- \sum_{j=3}^{N} \alpha \left( t_j - \frac{\tau}{2} \right) \frac{\tau}{2}
\right\}
\]
\[
\times \left\{ \left[ \beta \left( \frac{\tau}{2} \right) - \beta \left( 3\frac{\tau}{2} \right) \right] \frac{\tau^2}{2} \left( I + \frac{\tau^2 A}{4} \right)^{-1} + \frac{\tau}{2} i A^{-1/2} \beta \left( 3\frac{\tau}{2} \right) \frac{R^2 - \bar{R}^2}{2} + \sum_{j=3}^{N} \beta \left( t_j - \frac{\tau}{2} \right) i A^{-1/2} \times \frac{R^j - \bar{R}^j + R^{j-1} - \bar{R}^{j-1}}{2} \right\} A^{-1/2} f_0 \\
+ i \tau A^{-1/2} \frac{R - \bar{R}}{2} \times \left\{ \beta \left( 3\frac{\tau}{2} \right) A^{-1/2} f_1 + \sum_{j=3}^{N} \beta \left( t_j - \frac{\tau}{2} \right) A^{-1/2} f_{j-1} \right\} \\
+ \sum_{j=3}^{N} \beta \left( t_j - \frac{\tau}{2} \right) \frac{\tau^2}{2} \beta \left( \frac{t_j}{4} \frac{\tau}{2} \right) i A^{-1/2} \times \frac{R^j - \bar{R}^j + R^{j-1} - \bar{R}^{j-1}}{2} \right\} A^{-1/2} f_0 \\
- \sum_{j=3}^{N} \alpha \left( t_j - \frac{\tau}{2} \right) \frac{\tau^2}{4i} (R - \bar{R}) f_{j-1} \\
- \sum_{j=3}^{N} \alpha \left( t_j - \frac{\tau}{2} \right) \frac{\tau}{2} \times \sum_{s=1}^{j-2} \left\{ \left[ \beta \left( 3\frac{\tau}{2} \right) A^{-1/2} f_s + \sum_{j=3}^{N} \beta \left( t_j - \frac{\tau}{2} \right) A^{-1/2} f_{j-s} \right] \right\} A^{-1/2} f_s \\
\right\}
\]
\[- \sum_{j=3}^{N} \alpha(t_j - \tau) \frac{\tau}{2} \]
\[\times \sum_{s=1}^{j-2} \left[R^{j-s} - \bar{R}^{j-s} + R^{j-s-1} - \bar{R}^{j-s-1}\right] f_s \right) \}
\[+ \left[ \alpha \left( \frac{3\tau}{2} \right) + \alpha \left( \frac{3\tau}{2} \right) \right] \left\{ \frac{\tau}{2} \left( I + \frac{\tau^2 A}{4} \right)^{-1} \right\} f_0 \]
\[+ \frac{i\tau A^{-1/2}}{2} \beta \left( \frac{3\tau}{2} \right) \frac{R^2 - \bar{R}^2}{2} \]
\[+ \sum_{j=3}^{N} \beta(t_j - \tau) \frac{\tau}{2} A^{-1/2} \]
\[\times \frac{R^j - \bar{R}^j + R^{j-1} - \bar{R}^{j-1}}{2i} \right\} f_0 \]
\[+ \left[ \beta \left( \frac{3\tau}{2} \right) f_1 + \sum_{j=3}^{N} \beta(t_j - \tau) f_{j-1} \right] \]
\[+ \frac{i\tau A^{-1/2} N}{2} \beta \left( \frac{3\tau}{2} \right) \]
\[\times \sum_{s=1}^{j-2} \left[R^{j-s} - \bar{R}^{j-s} + R^{j-s-1} - \bar{R}^{j-s-1}\right] = T^{-1} \left\{ I - \left[ \beta \left( \frac{\tau}{2} \right) - \beta \left( \frac{3\tau}{2} \right) \right] \left( I + \frac{\tau^2 A}{4} \right)^{-1} \right\} \]
\[+ \beta \left( \frac{3\tau}{2} \right) x A^{-1/2} \frac{R^2 - \bar{R}^2}{2} \]
\[+ \sum_{j=3}^{N} \beta \left( t_j - \frac{\tau}{2} \right) A^{-1/2} \]
\[\times \frac{R^j - \bar{R}^j + R^{j-1} - \bar{R}^{j-1}}{2i} \right\} f_0 \]
\[- \alpha \left( \frac{3\tau}{2} \right) x \frac{\tau^2}{4i} A^{1/2} (R - \bar{R}) f_1 \]
\[- \sum_{j=3}^{N} \alpha \left( t_j - \frac{\tau}{2} \right) \frac{\tau}{4} A^{1/2} (R - \bar{R}) f_{j-1} + A\varphi \]
\[- \sum_{j=3}^{N} \alpha \left( t_j - \frac{\tau}{2} \right) \frac{\tau}{4} \]
\[\times \left[ \sum_{s=1}^{j-2} \left( I - i\tau A^{1/2} \frac{R^j - \bar{R}^j}{2} \right) \right] f_0 \]
\[+ 2f_{j-2} \right\} \]
\[\|A^{1/2} \mu\|_H \leq M \left\{ \sum_{s=0}^{N-1} \|f_s\|_H \tau + \|\varphi\|_H + \|A^{1/2} \varphi\|_H \right\}. \quad (56) \]

Using formula (48), the triangle inequality, and estimates (37), we obtain
\[\|\omega\|_H \leq M \left\{ \sum_{s=0}^{N-1} \|f_s\|_H \tau + \|\varphi\|_H + \|A^{1/2} \varphi\|_H \right\}. \quad (57) \]
\[
\times \left[\sum_{s=1}^{j-2} \left[ \left( I - \frac{i\tau A^{1/2}}{2} \right) R^{j-s} - \left( I - \frac{i\tau A^{1/2}}{2} \right) R^{j-s} \right] f_s - f_{s-1} + \left( I + \frac{i\tau A^{1/2}}{2} \right) ̂R^{j-s} \right] f_0 \right] + \sum_{j=3}^{N} \beta \left( t_j - \frac{\tau}{2} \right) \frac{\tau}{4} \times \left[ \sum_{s=1}^{j-2} \left[ \left( I - \frac{i\tau A^{1/2}}{2} \right) R^{j-s} + \left( I + \frac{i\tau A^{1/2}}{2} \right) ̂R^{j-s} \right] f_0 \right] - 2f_{j-2} \right] \right).
\]
\[
\times \left\{ \left[ \beta \left( \frac{\tau}{2} \right) - \beta \left( \frac{3\tau}{2} \right) \right] \left( I + \frac{\tau^2 A}{4} \right)^{-1}
+ \frac{\tau}{2} i \beta \left( \frac{3\tau}{2} \right) \times \frac{R^2 - \bar{R}^2}{2}
+ \sum_{j=3}^{N} \beta \left( t_j - \frac{\tau}{2} \right) i \times \frac{R^j - \bar{R}^j + \bar{R}^{j-1} - R^{j-1}}{2} \right\} f_0
+ \frac{i}{2} \left[ \beta \left( \frac{3\tau}{2} \right) f_1
+ \sum_{j=3}^{N} \beta \left( t_j - \frac{\tau}{2} \right) f_{j-1} \right] + A^{1/2} \psi
\]
\]
Using the triangle inequality and estimates (37), we obtain
\[
\|A^{1/2} \omega\|_{H^2} 
\leq M \left\{ \sum_{s=1}^{N-1} \|f_s - f_{s+1}\|_{H^2} + \|f_0\|_{H^2} + \|A^{1/2} \psi\|_{H^2} + \|A \phi\|_{H^2} \right\}.
\]
(61)

As a result, estimate (44) follows from estimates (50), (59), and (61). Theorem 6 is proved.

4. Application

The discretization of hyperbolic equation (2) with Neumann and integral or nonclassical and integral boundary conditions is carried out in two steps. First, let us define the grid sets
\[
\Omega_h = \{ x = x_r = (h_1 r_1, \ldots, h_m r_m) \in \mathbb{R}^m : r = (r_1, \ldots, r_m) \}
\]
\[
0 \leq r_j \leq N_j, \quad h_j N_j = 1, \quad j = 1, \ldots, m
\]
\[
\Omega_h = \Omega_h \cap \mathbb{R}^m, \quad S_h = \Omega_h \cap \mathbb{R}^m.
\]

We introduce the Banach space \( L_{2h} = L_2(\Omega_h) \) of the grid functions
\[
\varphi_h(x) = \{ \varphi (h_1 r_1, \ldots, h_m r_m) \}
\]
defined on \( \Omega_h \), equipped with the norm
\[
\|\varphi_h\|_{L_2(\Omega_h)} = \left( \sum_{x \in \Omega_h} \|\varphi_h(x)\|^2_{L_2(\Omega_h)} \right)^{1/2}.
\]
(64)

To the differential operator \( A^x \) generated by (2), we assign the difference operator \( A_h^x \) by the formula
\[
A_h^x u_h^x = -\sum_{r=1}^{m} (a_r(x) u_h^{r+1})_{x,r} + \sigma u_h^x(x)
\]
(65)
acting in the space of grid functions \( u_h^x(x) \), satisfying the condition \( D^h u_h^x(x) = 0 \) for all \( x \in \Omega_h \) or \( u_h^x(x) = 0 \) and \( D^h u_h^x(x) = 0 \) for \( x \in \Omega_h \) and \( D^h u_h^x(x) = 0 \) for \( x \in \Omega_h \). \( D^h u_h^x \) is the approximation of \( (\partial u / \partial n) \). It is known that \( A_h^x \) is a self-adjoint positive definite operator in \( L_2(\Omega_h) \). With the help of \( A_h^x \), we arrive at the nonlocal boundary value problem
\[
\frac{d^2 v^h(t,x)}{dt^2} + A_h^x v^h(t,x) = f^h(t,x), \quad 0 < t < 1, \quad x \in \Omega_h,
\]
\[
v^h(0,x) = \int_0^1 \alpha(\rho) v^h(\rho,x) d\rho + \varphi^h(x), \quad x \in \Omega_h,
\]
\[
\frac{dv^h(0,x)}{dt} = \int_0^1 \beta(\rho) \frac{dv^h(\rho,x)}{dt} d\rho + \psi^h(x), \quad x \in \Omega_h
\]
(66)
for an infinite system of ordinary differential equations.

Second, we replace problem (66) by the difference scheme
\[
u_{k+1}^h(x) - 2u_k^h(x) + u_{k-1}^h(x) + A_h^x u_{k+1}^h(x) = f_{k+1}^h(x),
\]
\[
f_{k+1}^h(x) = f^h(t_{k+1},x), \quad t_{k+1} = (k + 1) \tau,
\]
\[
1 \leq k \leq N - 1, \quad N \tau = 1, \quad x \in \Omega_h,
\]
\[
u_0^h(x) = \sum_{m=1}^{N} \alpha(t_m) u_m^h(x) \tau + \tilde{f}^h(x), \quad x \in \Omega_h,
\]
\[
(t + \tau^2 A_h^x) (u_1^h(x) - u_0^h(x)) \tau^{-1}
\]
\[
= \sum_{j=1}^{N} \beta(\rho_j) [u_j^h(x) - u_{j-1}^h(x)] + \psi^h(x), \quad x \in \Omega_h
\]
(67)
of the first order accuracy in \( t \). For the stability of first order of accuracy difference scheme, the following theorem is presented.

**Theorem 7.** Let \( \tau \) and \( h \) be sufficiently small numbers. Then, the solutions of difference scheme (67) satisfy the following stability estimates:
\[
\max_{0 \leq s \leq N} \|u_s^h\|_{L_{2h}} + \max_{1 \leq k \leq N-1} \|r^{-1} (u_k^h - u_{k-1}^h)\|_{L_{2h}} + \max_{0 \leq s \leq N} \|u_s^h\|_{L_{2h}}
\]
\[
\leq M_1 \left[ \max_{1 \leq k \leq N-1} \|f_k^h\|_{L_{2h}} + \|\varphi_h^0\|_{L_{2h}} + \|\psi_h^0\|_{L_{2h}} \right],
\]
\[
\max_{1 \leq k \leq N-1} \|r^{-2} (u_{k+1}^h - 2u_k^h + u_{k-1}^h)\|_{L_{2h}} + \max_{1 \leq k \leq N-1} \|u_s^h\|_{L_{2h}}
\]
\[
\leq M_1 \left[ \|f_1^h\|_{L_{2h}} + \max_{1 \leq k \leq N-1} \|r^{-1} (f_k^h - f_{k-1}^h)\|_{L_{2h}} + \|\varphi_h^0\|_{L_{2h}} + \|\psi_h^0\|_{L_{2h}} \right].
\]
(68)

Here, \( M_1 \) is independent of \( h, \varphi_h^0(x), \psi_h^0(x) \), and \( f_i^h(x), 1 \leq k < N \).

The proof of Theorem 7 is based on the symmetry property of difference operator \( A_h^x \) defined by formula (65) and on the following theorem on coercivity inequality of the elliptic difference problem.

**Theorem 8.** For the solutions of the elliptic difference problem
\[
A_h^x u_h^x(x) = \omega_h^x(x), \quad x \in \Omega_h, \quad D^h u_h^x(x) = 0, \quad x \in S_h
\]
or \( u_h^x(x) = 0, \quad x \in S_{1h}, \quad D^h u_h^x(x) = 0, \quad x \in S_{2h}
\]
(69)
the following coercivity inequality holds [23]:

\[ \sum_{r=1}^{m} \| u_{k,r}^h \|_{L^{2h}} \leq M \| \omega^h \|_{L^{2h}}. \] (70)

In addition, the second order of accuracy difference scheme

\[ \tau^2 [u_{k+1}^h (x) - 2u_k^h (x) + u_{k-1}^h (x)] \]

\[ + \frac{1}{2} A^x_h u_k^h (x) + \frac{1}{4} A^x_h [u_{k+1}^h (x) + u_k^h (x)] = f_k^h (x), \]

\[ x \in \Omega_h, \quad f_k^h = f_k^h (t_k, x), \]

\[ t_k = k \tau, \quad 1 \leq k \leq N - 1, \quad N \tau = 1, \]

\[ u_0^h (x) = \sum_{j=1}^{N} \alpha \left( \rho_j - \frac{\tau}{2} \right) \left[ u_j^h (x) + u_{j-1}^h (x) \right] \frac{\tau}{2} \]

\[ + \varphi^h (x), \quad x \in \Omega_h, \]

\[ \left( I + \frac{\tau^2 A^x_h}{2} \right) \tau^{-1} [u_1^h (x) - u_0^h (x)] \]

\[ - \frac{\tau}{2} \left[ f_0^h (x) - A^x_h u_0^h (x) \right] \]

\[ = \sum_{j=1}^{N} \beta \left( \rho_j - \frac{\tau}{2} \right) \left[ u_j^h (x) - u_{j-1}^h (x) \right] + \psi^h (x), \]

\[ f_0^h = f^h (0, x), \quad f_N^h = f^h (1, x), \quad x \in \Omega_h, \] (71)

for approximately solving hyperbolic equation (2) with nonlocal integral and Neumann or nonclassical conditions is presented. The following theorem on the stability of (71) is obtained.

**Theorem 9.** Let \( \tau \) and \( h \) be sufficiently small numbers. Then, the solution of difference scheme (71) satisfies the following stability estimates:

\[
\max_{0 \leq k \leq N} \| u_k^h \|_{L^{2h}} + \max_{1 \leq k \leq N} \| f_k^h - f_{k-1}^h \|_{L^{2h}} \leq M_1 \]

\[
\sum_{r=1}^{m} \| u_{k,r}^h \|_{L^{2h}} \leq M_2 \| \omega^h \|_{L^{2h}}. \]

\[
\max_{0 \leq k \leq N} \left( \sum_{r=1}^{m} \| u_{k,r}^h \|_{L^{2h}} \right) + \max_{1 \leq k \leq N} \| f_k^h - f_{k-1}^h \|_{L^{2h}} \]

\[
\leq M_2 \left[ \| f_0^h \|_{L^{2h}} + \max_{1 \leq k \leq N} \| f_k^h - f_{k-1}^h \|_{L^{2h}} \right]. \]

Here, \( M_2 \) does not depend on \( \tau, h, \varphi^h (x) \), and \( f_k^h, 0 \leq k \leq N-1 \).

The proof of Theorem 9 is based on the symmetry property of difference operator \( A^x_h \) defined by formula (65) and on Theorem 8 on coercivity inequality of elliptic difference problem (69).

**5. Numerical Examples**

In this section, we apply finite difference schemes (67) and (71) to three examples which are one-dimensional hyperbolic equation with nonlocal and nonclassical conditions.

**Example 10.** The nonlocal boundary value problem

\[
\frac{\partial^2 u (t, x)}{\partial t^2} - (1 + x) \frac{\partial^2 u (t, x)}{\partial x^2} - u_x (t, x) + u (t, x)
\]

\[
= f (t, x),
\]

\[
f (t, x) = [(x + 2 \cos x - \sin x) (e^t - 1 - t) + e^t \cos x, \quad 0 < t < 1, \quad 0 < x < \pi,
\]

\[
u (0, x) = \int_0^1 e^{-s} u (s, x) ds + \varphi (x),
\]

\[
\varphi (x) = (1 - 3e^{-1}) \cos x,
\]

\[
u_l (0, x) = \int_0^1 e^{-s} u_l (s, x) ds + \psi (x),
\]

\[
\psi (x) = -e^{-1} \cos x,
\]

\[
0 \leq x \leq \pi,
\]

\[
u (t, 0) = u (t, \pi) = 0, \quad 0 \leq t \leq 1,
\] (73)

for one-dimensional hyperbolic equation with variable coefficients is considered. The exact solution of this problem is

\[
u (t, x) = (e^t - 1 - t) \cos x. \] (74)
First, we obtain the first order of accuracy difference scheme

\[
\frac{u_n^{k+1} - u_n^k + u_n^{k-1}}{2h} - \left(1 + x_n^2\right) \frac{u_n^{k+1} - 2u_n^k + u_n^{k-1}}{h^2} = f\left(t_{k+1}, x_n\right),
\]

\[
f\left(t_{k+1}, x_n\right) = \left(\left(x_n + 2\right) \cos x_n - \sin x_n\right) \times \left(e^{\delta_{k+1}} - 1 - t_{k+1}\right) + e^{\delta_{k+1}} \cos x_n,
\]

\[N \tau = 1, \quad M \tau = \pi, \quad 1 \leq n \leq M - 1, \quad M = \pi.
\]

\[
u_0^k - \sum_{k=1}^N e^{-\tau^k} \tau u_k^k = \varphi(x_n), \quad t_k = k \tau, \quad 1 \leq k \leq N - 1,
\]

\[
\varphi(x_n) = \left(1 - 3e^{-t}\right) \cos x_n, \quad 0 \leq n \leq M,
\]

\[
u_1^k - u_0^k - \sum_{k=1}^N e^{-\tau^k} \left(u_k^k - u_{k-1}^k\right) = \psi(x_n),
\]

\[
\psi(x_n) = -e^{-t} \cos x_n, \quad 0 \leq n \leq M - 1,
\]

\[
u_0^k = u_1^k, \quad u_M^k = u_{M-1}^k, \quad 0 \leq k \leq N.
\]

(75)

The system can be written in the matrix form

\[
A_n u_{n+1} + B_n u_n + C_n u_{n-1} = D f_n, \quad 1 \leq n \leq M - 1,
\]

\[
u_0 = u_1, \quad u_M = u_{M-1}.
\]

(76)

Here,

\[
A_n = \begin{bmatrix}
0 & 0 & 0 & 0 & \cdots & 0 & 0 \\
0 & e_n & 0 & 0 & \cdots & 0 & 0 \\
0 & 0 & e_{n-1} & 0 & \cdots & 0 & 0 \\
\vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\
0 & 0 & 0 & 0 & \cdots & e_1 & 0 \\
0 & 0 & 0 & 0 & \cdots & 0 & e_n \\
0 & 0 & 0 & 0 & \cdots & 0 & 0
\end{bmatrix}_{(N+1) \times (N+1)},
\]

\[
B_n = \begin{bmatrix}
1 & -e^{-\tau} & -e^{-2\tau} & \cdots & -e^{-N\tau} & -e^{-N\tau} \\
b & c & d_n & \cdots & 0 & 0 \\
0 & b & c & \cdots & 0 & 0 \\
0 & 0 & b & \cdots & 0 & 0 \\
\vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\
0 & 0 & 0 & \cdots & d_n & 0 \\
0 & 0 & 0 & \cdots & c & d_n \\
0 & 0 & 0 & \cdots & 0 & a_n \\
0 & 0 & 0 & \cdots & 0 & 0 \\
\end{bmatrix}_{(N+1) \times (N+1)}.
\]

\[
C_n = \begin{bmatrix}
0 & 0 & 0 & 0 & \cdots & 0 & 0 \\
0 & e_n & 0 & 0 & \cdots & 0 & 0 \\
0 & 0 & e_{n-1} & 0 & \cdots & 0 & 0 \\
\vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\
0 & 0 & 0 & 0 & \cdots & e_1 & 0 \\
0 & 0 & 0 & 0 & \cdots & 0 & e_n \\
0 & 0 & 0 & 0 & \cdots & 0 & 0
\end{bmatrix},
\]

\[
f_n = \begin{bmatrix}
f_0^N \\
f_1^N \\
f_2^N \\
\vdots \\
f_N^N
\end{bmatrix}_{(N+1) \times 1},
\]

\[
f_n^k = f\left(t_{k+1}, x_n\right) = \left(\left(x_n + 2\right) \cos x_n - \sin x_n\right) \times \left(e^{\delta_{k+1}} - 1 - t_{k+1}\right) + e^{\delta_{k+1}} \cos x_n, \quad 0 \leq n \leq M,
\]

\[
f_n^0 = \left(1 - 3e^{-t}\right) \cos x_n, \quad 0 \leq n \leq M,
\]

(77)

Here, \(D = I_{N+1}\) is the identity matrix.

Consider

\[
U_s = \begin{bmatrix}
u_0^s \\
u_1^s \\
u_2^s \\
\vdots \\
u_N^s
\end{bmatrix}_{(N+1) \times 1}, \quad s = n - 1, n, n + 1.
\]

(78)

This type system was used by [24] for difference equations.

For the solution of matrix equation (76), we will use modified Gauss elimination method. We seek a solution of the matrix equation by the following form:

\[
u_n = a_n u_{n+1} + b_{n+1}, \quad n = M - 1, \ldots, 2, 1,
\]

(79)
where \( u_M = (I - \alpha_M)^{-1}\beta_M, \alpha_j (j = 1, \ldots, M - 1) \) are \((N + 1) \times (N + 1)\) square matrices and \( \beta_j (j = 1, \ldots, M - 1) \) are \((N + 1) \times 1\) column matrices. \( \alpha_1 \) is identity and \( \beta_1 \) is zero matrices, and

\[
\alpha_{n+1} = -(B_n + C_n\alpha_n)^{-1}A_n, \\
\beta_{n+1} = (B_n + C_n\alpha_n)^{-1}(D_n\varphi_n - C_n\beta_n).
\]

Second, applying formulas

\[
\begin{align*}
\frac{2u(0) - 5u(h) + 4u(2h) - u(3h)}{h^2} - u''(0) &= O(h^2), \\
\frac{2u(\pi) - 5u(\pi - h) + 4u(\pi - 2h) - u(\pi - 3h)}{h^2} - u''(\pi) &= O(h^2)
\end{align*}
\]

and using the second order of accuracy implicit difference scheme (71), we get second order of accuracy difference scheme

\[
\begin{align*}
\frac{u^{k+1}_n - 2u^k_n + u^{k-1}_n}{\tau^2} + (1 + x_n) \\
\times \left[ \frac{u^{k-1}_n - 2u^{k-1}_n + u^{k-1}_n}{4h^2} - \frac{u^{k-1}_n - 2u^{k-1}_n + u^{k-1}_n}{2h^2} \\
- \frac{u^{k-1}_n - 2u^{k-1}_n + u^{k-1}_n}{4h^2} + \frac{u^{k-1}_n - 2u^{k-1}_n + u^{k-1}_n}{2h^2} \\
- \frac{u^{k-1}_n - 2u^{k-1}_n + u^{k-1}_n}{4h^2} + \frac{u^{k-1}_n - 2u^{k-1}_n + u^{k-1}_n}{2h^2} \\
+ 1 - \frac{u^{k+1}_n - u^{k-1}_n}{4} + \frac{u^{k+1}_n - u^{k-1}_n}{4} &= f^k_n,
\end{align*}
\]

\[
f^k_n = [(x_n + 2) \cos x_n + \sin x_n] (e^{h \tau} - 1 - t_k) + e^{k \tau} \cos x_n,
\]

\[
Mh = \pi, \quad x_n = nh, \quad 1 \leq n \leq M - 1, \quad N\tau = 1, \quad 1 \leq k \leq N - 1,
\]

\[
u^0_n = \sum_{k=1}^{N} \frac{N}{2} \left[ e^{-k \tau} u^k_n + e^{(k-1) \tau} u^{k-1}_n \right] + \varphi(x_n),
\]

\[
\psi(x_n) = (1 - 3e^{-\tau}) \cos x_n, \quad 0 \leq n \leq M,
\]

\[
\begin{align*}
\frac{u^0_n - u^0_0}{\tau} &- \frac{\tau}{4} (1 + x_n) \\
&\times \left[ \frac{u^1_{n-1} - u^1_{n-1} + u^1_{n-1}}{h^2} + \frac{u^0_{n+1} - u^0_{n-1}}{h^2} \\
+ \frac{\tau}{2} \left[ - \frac{u^0_{n+1} - u^0_{n-1}}{4h} - \frac{u^0_{n+1} - u^0_{n-1}}{4h} \\
+ \frac{\tau}{4} [u^0_n + u^0_n] - \frac{\tau}{4} f^0_n \\
+ \sum_{k=1}^{N} e^{-k \tau + \tau/2} [u^k_n + u^{k-1}_n] + \psi(x_n) \right], \quad 1 \leq n \leq M - 1,
\end{align*}
\]

\[
\psi(x_n) = -e^{-1} \cos x_n, \quad 0 \leq n \leq M,
\]

\[
u^0_n - u^0_0 = h^2 \left[ \frac{2u^0_n - 5u^1_n + 4u^2_n - u^3_n}{\tau^2} + u^0_n - \varphi^0_n \right]
\]

\[
u^N_n - u^0_0 = h^2 \left[ \frac{2u^N_n - 5u^N_n + 4u^{N-1}_n - u^{N-2}_n}{\tau^2} + u^N_n - \varphi^0_n \right]
\]

\[
u^k_n - u^0_0 = \frac{h^2}{2} \left[ \frac{u^{k+1}_n - 2u^k_n + u^{k-1}_n}{h^2} + u^0_n - \varphi^0_n \right], \quad 1 \leq k \leq N - 1,
\]

for the approximate solutions of nonlocal boundary value problem (73). We have again \((N + 1) \times (N + 1)\) system of linear equations. We can write the system as a matrix equation (76). Here,

\[
E_n = \begin{bmatrix}
0 & 0 & 0 & 0 & \cdots & 0 & 0 & 0 \\
0 & 2a_n & a_n & 0 & \cdots & 0 & 0 & 0 \\
0 & a_n & 2a_n & a_n & \cdots & 0 & 0 & 0 \\
\vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \vdots \\
0 & 0 & 0 & \cdots & a_n & 2a_n & a_n & 0 \\
w_n & w_n & 0 & \cdots & 0 & 0 & 0 & 0
\end{bmatrix}^{(N+1)\times(N+1)}
\]
\[ F_n = \begin{bmatrix}
1 - \frac{\tau}{2} & -\tau e^{-\tau} & -\tau e^{-2\tau} & -\tau e^{-3\tau} & \ldots & -\tau e^{-(N-1)\tau} & -\frac{\tau}{2} e^{-N\tau} \\
b_n & d_n & b_n & 0 & \ldots & 0 & 0 \\
0 & b_n & d_n & b_n & \ldots & 0 & 0 \\
\vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\
0 & 0 & 0 & 0 & \ldots & d_n & b_n \\
0 & 0 & 0 & 0 & \ldots & d_n & b_n \\
y_n & t_n & \lambda e^{-3\tau/2} & \lambda e^{-5\tau/2} & \ldots & \lambda e^{-(2N-3)\tau/2} & -e^{-N\tau+(\tau/2)} \\
\end{bmatrix}_{(N+1)\times(N+1)}, \]

\[ G_n = \begin{bmatrix}
0 & 0 & 0 & 0 & \ldots & 0 & 0 & 0 \\
c_n & 2c_n & c_n & 0 & \ldots & 0 & 0 & 0 \\
0 & c_n & 2c_n & c_n & \ldots & 0 & 0 & 0 \\
\vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots \\
0 & 0 & 0 & 0 & \ldots & c_n & 2c_n & c_n \\
z_n & z_n & 0 & 0 & \ldots & 0 & 0 & 0 \\
\end{bmatrix}_{(N+1)\times(N+1)}, \]

\[ a_n = -\frac{(1+x_n)}{4h^2} - \frac{1}{8h}, \quad b_n = \frac{1}{\tau^2} + \frac{1}{2h^2} + \frac{1}{4}, \]

\[ c_n = -\frac{(1+x_n)}{4h^2} + \frac{1}{8h}, \quad d_n = -\frac{2}{\tau^2} + \frac{1}{2h^2} + \frac{1}{2}, \]

\[ y_n = -\frac{1}{\tau} + \frac{\tau}{4} + \frac{(1+x_n)}{2h^2} + e^{-\tau/2}, \]

\[ t_n = \frac{1}{\tau} + \frac{\tau}{4} + \frac{(1+x_n)}{2h^2} + (e^{-\tau} - 1) e^{-\tau/2}, \]

\[ w_n = -\frac{\tau^2}{4h} - \frac{(1+x_n)}{2h^2}, \quad z_n = \frac{\tau^2}{4h} - \frac{(1+x_n)}{2h^2}, \quad \lambda = (e^{-\tau} - 1) \]

\[ f_n = \begin{bmatrix}
f_n^0 \\
f_n^1 \\
\vdots \\
f_n^N \\
\end{bmatrix}_{(N+1)\times1}, \]

\[ f_n^k = f(t_k, x_n) = [(x_n + 2) \cos x_n - \sin x_n] \times (e^{t_k} - 1 - t_k) + e^{t_k} \cos x_n, \quad 1 \leq k \leq N - 1, \]

\[ f_n^0 = (1 - 3e^{-1}) \cos x_n, \quad 0 \leq n \leq M, \]

\[ f_n^N = -e^{-1} \cos x_n, \quad 0 \leq n \leq M, \]

\[ T = \begin{bmatrix}
\lambda_1 & \lambda_2 & \lambda_3 & \lambda_4 & 0 & 0 & \ldots & 0 & 0 & 0 & 0 & 0 \\
a & b & a & 0 & 0 & \ldots & 0 & 0 & 0 & 0 & 0 \\
0 & a & b & a & 0 & \ldots & 0 & 0 & 0 & 0 & 0 \\
\vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\
0 & 0 & 0 & 0 & \ldots & 0 & a & b & a & 0 \\
0 & 0 & 0 & 0 & \ldots & 0 & a & b & a & 0 \\
0 & 0 & 0 & 0 & \ldots & 0 & \lambda_4 & \lambda_3 & \lambda_2 & \lambda_1 \\
\end{bmatrix}_{(N+1)\times(N+1)}.
\[ a = \frac{-h}{2 \tau^2}, \quad b = \frac{-1}{h} + \frac{h}{\tau^2} - \frac{h}{2}, \]

\[ \lambda_1 = \frac{-1}{h} - \frac{h}{2} \left( \frac{2}{\tau^2} + 1 \right), \quad \lambda_2 = \frac{5}{2 \tau^2}, \quad \lambda_3 = -\frac{2h}{\tau^2}, \quad \lambda_4 = \frac{h}{2 \tau^2}, \]

\[ D = I_{N+1}, \quad U_s = \begin{bmatrix} u_0 \\ u_1 \\ \vdots \\ u_N \end{bmatrix}^{(N+1) \times 1}, \quad s = n - 1, n, n + 1. \]

(83)

For the solution of the matrix equation (76), we used the same algorithm as in the first order of accuracy difference scheme. Here, \( u_M = (\alpha_{M-1} \alpha_M - 4 \alpha_M + 3 I)^{-1} (4 \beta_M - \alpha_{M-1} \beta_M - \beta_{M-1}) \),

\[ \alpha_1 = T^{-1} \left( \frac{-1}{2} I \right), \quad \beta_1 = T^{-1} \varphi_0^k, \quad 0 \leq k \leq N. \] (84)

**Example II.** The nonlocal boundary value problem

\[ \frac{\partial^2 u(t, x)}{\partial t^2} - (1 + x) \frac{\partial^2 u(t, x)}{\partial x^2} - u_x(t, x) + u(t, x) = f(t, x), \]

\( f(t, x) = [(x + 2) \cos x + \sin x - 1] \left( \frac{e^t}{2} - 1 - t \right) \]

\[ + e^t \cos x - 1, \quad 0 < t < 1, \quad 0 < x < \pi, \]

\( u(0, x) = \int_0^1 e^{-s} u(s, x) ds + \varphi(x), \]

\( \varphi(x) = (1 - 3e^{-1}) \cos x - 1, \quad 0 \leq x \leq \pi, \)

\( u(t, 0) = u_t(t, \pi) = 0, \quad 0 \leq t \leq 1, \)

is considered. Here, we use the same procedure as in the first example. The exact solution of this problem is

\[ u(t, x) = \left( \frac{e^t}{2} - 1 - t \right) \cos x - 1. \] (85)

(86)

Using the same manner, we can construct first order of accuracy difference scheme and it can be written in the matrix form

\[ A_n u_{n+1} + B_n u_n + C_n u_{n-1} = D f_n, \quad 1 \leq n \leq M - 1, \]

\[ u_0 = 0, \quad u_M = u_{M-1}. \] (87)

Here, matrices \( A_n, B_n, C_n, \) and \( D \) are given in the previous example, and

\[ f_n = \begin{bmatrix} f_0^N \\ f_1^N \\ \vdots \\ f_M^N \end{bmatrix}^{(N+1) \times 1}, \]

\( f_n^{k+1} = f(t_{k+1}, x_n) = [(x + 2) \cos x + \sin x - 1] \]

\[ \times \left( \frac{e^t}{2} - 1 - t \right) + e^t \cos x - 1, \quad 1 \leq k \leq N - 1, \]

\( f_0^N = (1 - 3e^{-1}) \cos x - 1, \quad 0 \leq n \leq M, \)

\( f_M^N = -e^{-1} \cos x - 1, \quad 0 \leq n \leq M. \) (88)

For the solution of matrix equation (87), we will use modified Gauss elimination method. We seek a solution of the matrix equation by the following form:

\[ u_n = \alpha_{n+1} u_{n+1} + \beta_{n+1}, \quad n = M - 1, \ldots, 2, 1, \] (89)

where \( u_M = (I - \alpha_M)^{-1} \beta_M, \alpha_j \) \((j = 1, \ldots, M - 1)\) are \((N + 1) \times (N + 1)\) square matrices and \( \beta_j \) \((j = 1, \ldots, M - 1)\) are \((N+1)\times 1\) column matrices. \( \alpha_1 \) and \( \beta_1 \) are zero matrices, and

\[ \alpha_{n+1} = -(B_n + C_n \alpha_n)^{-1} A_n, \]

\[ \beta_{n+1} = (B_n + C_n \alpha_n)^{-1} (D_n \varphi_n - C_n \beta_n), \]

\[ n = 1, 2, 3, \ldots, M - 1. \] (90)

By using the second order of accuracy implicit difference scheme (71), we can write the matrix form

\[ E_n u_{n+1} + F_n u_n + G_n u_{n-1} = D f_n, \quad 1 \leq n \leq M - 1, \]

\[ u_0 = 0, \quad u_{M-2} - 4u_{M-1} + 3u_M = 0. \] (91)
Here, matrices $E_n$, $F_n$, $G_n$, and $D$ are given in the previous example, and also $f_n$ is given in the first order accuracy difference scheme. For the solution of the matrix equation (91), we used the same algorithm as in the first order of accuracy difference scheme, where $u_M = (\alpha M - \alpha M - 4\alpha M + 3I)^{-1}(4\beta M - \alpha M - \beta M - \beta M - 1)e$, $\alpha$ and $\beta$ are zero matrices.

**Example 12.** In this example, the nonlocal boundary value problem

$$\frac{d^2 u(t, x)}{dt^2} - (1 + x) \frac{d^2 u(t, x)}{dx^2} - u_x (t, x) + u(t, x) = f(t, x),$$

$$f(t, x) = [(x + 2) \cos x + \sin x + 1] (e^{-t} - 1)$$

$$+ e^{-t} (\cos x + 1), \quad 0 < t < 1, \ 0 < x < \pi,$$

$$u(0, x) = \int_0^1 e^{-t} u(s, x) ds + \varphi(x),$$

$$\varphi(x) = (1 - 3e^{-1}) (\cos x + 1),$$

$$u_t(0, x) = \int_0^1 e^{-t} u_t(s, x) ds + \psi(x),$$

$$\psi(x) = -e^{-1} (\cos x + 1),$$

$$u_x (t, 0) = u(t, \pi) = 0, \quad 0 \leq t \leq 1, \ 0 \leq x \leq \pi,$$

for one-dimensional hyperbolic equation is considered. The exact solution of this problem is

$$u(t, x) = (e^{-t} - 1) (\cos x + 1).$$

First, we use the first order of accuracy implicit difference scheme (67) for the approximate solutions of nonlocal boundary value problem (92) and we obtain the matrix equation

$$A_n u_{n+1} + B_n u_n + C_n u_{n-1} = D f_n, \quad 1 \leq n \leq M - 1,$$

$$u_M = \vec{0}, \quad u_1 = u_2.$$  

Here, matrices $A_n$, $B_n$, $C_n$, and $D$ are the same as in the first example, and

$$f_n = \begin{bmatrix} f_0^N \\ f_1^N \\ f_2^N \\ \vdots \\ f_{n-1}^N \\ f_n^N \end{bmatrix},$$

$$f_n^{k+1} = f(t_{k+1}, x_n) = [(x + 2) \cos x + \sin x + 1]$$

$$\times (e^{-t} - 1) + e^{-t} (\cos x + 1), \quad 1 \leq k \leq N - 1,$$

$$f_n^0 = (1 - 3e^{-1}) (\cos x + 1), \quad 0 \leq n \leq M,$$

$$f_n^N = -e^{-1} (\cos x + 1), \quad 0 \leq n \leq M.$$  

(95)

For the solution of matrix equation (94), we will use modified Gauss elimination method. We seek a solution of the matrix equation by the following form:

$$u_n = \alpha_{n+1} u_{n+1} + \beta_{n+1}, \quad n = M - 1, \ldots, 2, 1,$$

where $u_M = \vec{0}, \alpha_1$ is identity and $\beta_1$ is zero matrices, and

$$\alpha_{n+1} = -(B_n + C_n \alpha_n)^{-1} A_n,$$

$$\beta_{n+1} = (B_n + C_n \alpha_n)^{-1} (D_n \varphi_n + C_n \beta_n),$$

$$n = 1, 2, 3, \ldots, M - 1.$$

Second, for the approximate solutions of nonlocal boundary value problem (92), we use second order of accuracy difference scheme (71) and the formulas

$$3u_k^k - 4u_k^k + u_{k-1}^k = 0, \quad 1 \leq k \leq N - 1,$$

$$10u_0^k - 15u_k^k + 6u_{k-1}^k - u_{k-2}^k = 0, \quad 1 \leq k \leq N - 1,$$

$$2u_{M-1}^k - 5u_{M-2}^k + 4u_{M-3}^k - u_{M-4}^k = 0, \quad 1 \leq k \leq N - 1,$$

$$u_M^k = 0, \quad 1 \leq k \leq N - 1.$$  

(98)

The system can be written in the following matrix form:

$$P_n u_{n+2} + E_n u_{n+1} + F_n u_n$$

$$+ G_n u_{n-1} + R_n u_{n-2} = D f_n,$$

$$u_2 - 4u_1 + 3u_0 = \vec{0},$$

$$10u_0^k - 15u_k^k + 6u_{k-1}^k - u_{k-2}^k = \vec{0},$$

$$u_M^k = \vec{0}, \quad 2 \leq n \leq M - 2.$$  

(99)

Here, $P_n$ and $R_n$ are zero matrices and $E_n$, $F_n$, $G_n$, and $D$ are given in the first example, and also $f_n$ is given in the first order accuracy difference scheme. For the solution of matrix equation (99), we will use modified Gauss elimination method. We seek a solution of the matrix equation in the following form:

$$u_n = \alpha_{n+1} u_{n+1} + \beta_{n+1} u_{n+2} + \varphi_{n+1}, \quad n = M - 2, \ldots, 1,$$

$$u_{M-1} = (I - \frac{4}{5} \alpha_{M-1} + \frac{1}{5} \beta_{M-1})^{-1}$$

$$\times \left( \frac{4}{5} \varphi_{M-1} + \frac{4}{5} \gamma_{M-2} \varphi_{M-2} - \frac{1}{5} \beta_{M-2} \right),$$

$$u_M = \vec{0}.$$  

(100)
where $\alpha_j, \beta_j$ are $(N+1) \times (N+1)$ square matrices and $\gamma_n (j = 1, \ldots, M)$ are $(N+1) \times 1$ column matrices defined by

$$T_n = F_n + G_n \alpha_n + R (\beta_{n-1} + \alpha_{n-1} \alpha_n),$$
$$\alpha_{n+1} = -(T_n)^{-1} (E_n + G_n \beta_n + R \alpha_{n-1} \alpha_n),$$
$$\beta_{n+1} = (T_n)^{-1} P_n,$$
$$\gamma_{n+1} = (T_n)^{-1} (Df_n - G_n \gamma_n - R_n (\alpha_{n-1} \gamma_n + \gamma_{n-1})).$$

(101)

Using formulas (100) and (101), we can compute $U_n, 1 \leq k \leq M - 1$.

Now, let us give the results of numerical analysis. The numerical solutions are recorded for different values of $N = M$, and $u(t_k, x_n)$ represents the exact solution, and $u_h^n$ represents the numerical solution at $(t_k, x_n)$. For their comparison, the errors are computed by

$$E_N^M = \max_{1 \leq k \leq N-1, 1 \leq n \leq M-1} |u(t_k, x_n) - u_h^n|.$$  (102)

Thus, the results given in Tables 1, 2, and 3 show that the second order of accuracy difference scheme (71) is more accurate comparing with the first order of accuracy difference scheme (67).

6. Conclusion

In this paper, we presented first and second order stable difference schemes for solving the second order multidimensional hyperbolic equation with nonlocal integral and Neumann or nonclassical boundary conditions. Stability of the difference schemes do not depend on any additional condition between $h$ and $\tau$. The numerical results given in the previous sections demonstrate the efficiency and good accuracy of these schemes. Finally we would like to mention that this technique can be applied to get the highest order stable difference schemes.

Conflict of Interests

The authors declare that there is no conflict of interests regarding the publication of this paper.

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