EQUILIBRIUM STATES FOR CENTER ISOMETRIES

PABLO D. CARRASCO 1 AND FEDERICO RODRIGUEZ-HERTZ 2

1 ICEx, UFMG, Belo Horizonte, Minas Gerais, Brazil BR31270-90
(pdcarrasco@gmail.com)

2 Department of Mathematics - Eberly College of Science, Penn State, State College,
Pennsylvania, USA PA 16802
(hertz@math.psu.edu)

(Received 24 August 2021; revised 26 April 2023; accepted 27 April 2023;
first published online 2 June 2023)

Abstract We develop a geometric method to establish the existence and uniqueness of equilibrium states associated to some Hölder potentials for center isometries (as are regular elements of Anosov actions), in particular, the entropy maximizing measure and the SRB measure. A characterization of equilibrium states in terms of their disintegrations along stable and unstable foliations is also given. Finally, we show that the resulting system is isomorphic to a Bernoulli scheme.

Contents

1 Introduction and Main Results 1296
2 Measures along foliations 1303
2.1. Families of quasi-invariant measures 1304
2.2. Quasi-invariant measures along leaves of foliations: the transverse measure 1307
3 Invariant measures for center isometries 1313
3.1. The conditional measures: potentials constant along the center and SRBs 1314
3.2. The equilibrium state 1317
3.3. Product structure and the Gibb’s property 1322
4 A characterization of equilibrium states 1326

P.D.C. is partially supported by FAPEMIG Universal APQ-02160-21.
F. R.-H. is partially supported by NSF grant DMS-1900778.

Keywords: Partially hyperbolic systems; Anosov actions; equilibrium states; conformal measures

2020 Mathematics subject classification: 37D35; 37D30

© The Author(s), 2023. Published by Cambridge University Press.
1. Introduction and Main Results

We will study some aspects of the thermodynamic formalism for maps related to higher rank Anosov actions. Let $M$ be a compact metric space and $f : M \to M$ be an homeomorphism. For $x \in M, \epsilon > 0, n \in \mathbb{N}$, we denote by $D(x, \epsilon)$ the open disc of center $x$ and radius $\epsilon$, and by $D(x, \epsilon, n)$ the open $(\epsilon, n)$-Bowen ball centered at $x$,

$$D(x, \epsilon, n) = \{ y \in M : d(f^j x, f^j y) < \epsilon, j = 0, \ldots, n-1 \}.$$ 

Recall that the topological pressure of the (continuous) potential $\varphi : M \to \mathbb{R}$ is given by

$$P_{\text{top}}(\varphi) = P_{\text{top}}(\varphi) := \lim_{\epsilon \to 0} \limsup_{n \to \infty} \frac{\log S(\epsilon, n)}{n},$$

where

$$S(\epsilon, n) = \inf \left\{ \sum_{x \in E} e^{S_n \varphi(x)} : M = \bigcup_{x \in E} D(x, \epsilon, n) \right\}, \quad S_n \varphi = \sum_{i=0}^{n-1} \varphi \circ f^i.$$ 

Denote by $\mathcal{P}_f(M)$ the set of $f$-invariant Borel probability measures on $M$. For $\nu \in \mathcal{P}_f(M)$, the pressure of $\varphi$ with respect to $\nu$ is

$$P_{\nu}(\varphi) := \nu(\varphi) + h_{\nu}(f).$$

**Theorem** (Variational Principle). It holds that

$$P_{\text{top}}(\varphi) = \sup_{\nu \in \mathcal{P}_f(M)} P_{\nu}(\varphi).$$

This classical theorem is due to Walters [50].

**Definition 1.1.** A measure $m \in \mathcal{P}_f(M)$ is an equilibrium state for the potential $\varphi$ if $P_{\text{top}}(\varphi) = P_m(\varphi)$.

The existence, uniqueness and general properties of equilibrium states are of utmost relevance in ergodic theory, and for the differentiable one in particular. Indeed, one of the most important theorems in smooth ergodic theory is the following.

**Theorem.** Let $M$ be a closed (that is, compact and without a boundary) manifold and consider a $C^1$ diffeomorphism $f : M \to M$ having a hyperbolic attractor $\Lambda$ (in particular,
Equilibrium states for center isometries

1297

Then, for every Hölder potential \( \varphi : \Lambda \rightarrow \mathbb{R} \), there exists a unique equilibrium state \( m_\varphi \) for \( f|\Lambda \). Furthermore, if \( f|\Lambda \) is topologically mixing, then the system \((f,m_\varphi)\) is metrically isomorphic to a Bernoulli shift.

As stated, this theorem is a culmination of the work of several authors. The existence and uniqueness are essentially due to Sinai, Ruelle and Bowen \cite{47},\cite{46},\cite{5}, while the Bernoulli property is mainly due to Ornstein and Weiss \cite{34}. See also \cite{4}.

In this work, we investigate the thermodynamic formalism for a generalization of the above systems, namely when we have an Anosov action instead of a single hyperbolic map. Let us recall that a differentiable action of a Lie Group on a compact Riemannian manifold \( \alpha : G \curvearrowright M \) is Anosov if the \( G \)-orbits of \( \alpha \) foliate \( M \) and there exists \( g \in G \) an Anosov element, i.e. there exist an \( \alpha(g) \)-invariant decomposition \( TM = E_s \oplus E^c \oplus E^u \) and \( C > 0, 0 < \lambda < 1 \) such that \( E^c_x = T_x(G \cdot x) \), and with respect to the metric on \( M \), it holds that

\[
\begin{align*}
\forall n \geq 0 & \quad \|D_x \alpha(g)^n(v)\| \leq C \lambda^n \|v\| \\
\forall n \leq 0 & \quad \|D_x \alpha(g)^n(v)\| \leq C \lambda^{-n} \|v\|.
\end{align*}
\]

In this case, it is possible to modify the metric to guarantee that \( \alpha(g) \) is an isometry when restricted to each \( G \)-orbit. Diffeomorphisms preserving a splitting with the above properties are called center isometries and will be our main focus. See the next section for the precise definition or the classical reference \cite{24} for further information about these systems.

Anosov flows (cf. \cite{1}) constitute the most well understood example of Anosov action, where an analogous theorem as the previous one holds \cite{4}. The proof relies on the existence of Markov partitions \cite{3}, which permit to represent these flows as suspension over a symbolic system; since this technology is unavailable for Anosov actions of rank \( \geq 2 \), we present a geometric construction of equilibrium states for that context. At this stage, however, we need to impose some condition on the potential (being constant along the orbits or being the geometrical potential associated to a regular element). Besides the fact that these cases include the most interesting types of potentials (corresponding to the entropy maximizing measure and the SRB), we also believe that the techniques developed are interesting on their own and may be applicable to more situations.

For a center isometry \( f \), the associated bundles \( E^s, E^u, E^c, E^{cs} = E^s \oplus E^c, E^{cu} = E^c \oplus E^u \) are integrable to continuous foliations with smooth leaves \( \mathcal{W}^s, \mathcal{W}^u, \mathcal{W}^c, \mathcal{W}^{cs}, \mathcal{W}^{cu} \) called the stable, unstable, center, center stable and center unstable foliations, respectively. If \( W \) is a leaf of one of these foliations, then the Riemannian metric of \( M \) induces a corresponding metric on \( M \), and we will consider \( W \) equipped with the topology induced by this distance. Our results require the assumption that \( \mathcal{W}^s, \mathcal{W}^u \) are minimal foliations, i.e. every one of their leaves is dense (this condition is implicit in the classical rank-one case cited above, due to the mixing hypothesis).

**Theorem A** (c-constant case). Let \( f : M \rightarrow M \) be a center isometry of class \( C^2 \) and \( \varphi : M \rightarrow \mathbb{R} \) a Hölder potential that is constant on center leaves. Assume that the stable and unstable foliations of \( f \) are minimal. Then, there exist \( m_\varphi \in \mathcal{P}r_f(M) \) and families
of measures \( \mu = \{ \mu_x \}_{x \in M} \), \( \mu^u = \{ \mu^u_x \}_{x \in M} \), \( \mu^s = \{ \mu^s_x \}_{x \in M} \), \( \mu^{cs} = \{ \mu^{cs}_x \}_{x \in M} \) satisfying the following.

1. The probability \( m_\varphi \) is the unique equilibrium state for the potential \( \varphi \).
2. For every \( x \in M \), the measure \( \mu^s_x \) is a Radon measure on \( W^s(x) \) which is positive on relatively open sets, and \( y \in W^s(x) \) implies \( \mu^s_x = \mu^s_y \).
3. It holds that for every \( x \in M \),
   (a) \( \mu^s_x = e^{\varphi_{top}(\varphi)} f_* \mu^s_x \) \( \in \{ u, cu \} \).
   (b) \( \mu^u_x = e^{-\varphi_{top}(\varphi)} f_* \mu^u_x \) \( \in \{ s, cs \} \).
4. If \( \xi \) is a measurable partition that refines the partition by unstable (stable) leaves, then the conditionals \( (m_\varphi)^\xi \) of \( m_\varphi \) are equivalent to \( \mu^u_x \) (resp. \( \mu^s_x \)) for \( m_\varphi \)-a.e. \( x \).
5. For every \( \epsilon > 0 \) sufficiently small and for every \( x \in M \), the measure \( m_\varphi \) has product structure with respect to the pairs \( \mu^u_x, \mu^{cs} \) and \( \mu^s_x, \mu^{cs} \), i.e. it is equivalent to \( \mu^u_x \times \mu^{cs} \) and to \( \mu^s_x \times \mu^{cs} \).
6. For every \( \epsilon > 0 \), there exist some positive constants \( a(\epsilon), b(\epsilon) \) satisfying, for every \( x \in M, n \geq 0 \),
\[
a(\epsilon) \leq \frac{m_\varphi(D(x,\epsilon,n))}{e^{S_{\varphi}(x) - nP_{top}(\varphi)}} \leq b(\epsilon).
\]

**Theorem A’ (SRB case).** Let \( f : M \to M \) be a center isometry of class \( C^2 \) and \( \varphi = -\log |\det Df|E^u| \). Assume that the unstable foliation of \( f \) is minimal and let \( \mu_x = \{ \mu^u_x \} \) be the family of Lebesgue measures on unstable leaves; that is, \( \mu^u_x \) is the volume on \( W^u(x) \) corresponding to the induced metric. Then, there exist \( m_\varphi \in \mathcal{P}_{\mathcal{R}}f(M) \) and a family of measures \( \mu^{cs} = \{ \mu^{cs}_x \}_{x \in M} \) satisfying the following.

1. The probability \( m_\varphi \) is the unique equilibrium state for the potential \( \varphi \).
2. For every \( x \in M \), the measure \( \mu^{cs}_x \) is a Radon measure on \( W^{cs}(x) \) which is positive on relatively open sets, and \( y \in W^{cs}(x) \) implies \( \mu^{cs}_x = \mu^{cs}_y \).
3. It holds that for every \( x \in M \),
   (a) \( \mu^{cs}_x = |\det Df|E^u|^{-1} f_* \mu^{cs}_x \).
   (b) \( \mu^u_x = |\det Df|E^u| \cdot f_* \mu^u_x \) (change of variables theorem).
4. If \( \xi \) is a measurable partition that refines the partition by unstable leaves, then the conditionals \( (m_\varphi)^\xi \) of \( m_\varphi \) are equivalent to \( \mu^u_x \)
5. For every \( \epsilon > 0 \) sufficiently small and for every \( x \in M \), the measure \( m_\varphi \) has product structure with respect to the pair \( \mu^u_x, \mu^{cs} \).
6. For every \( \epsilon > 0 \), there exist some positive constants \( a(\epsilon), b(\epsilon) \) satisfying, for every \( x \in M, n \geq 0 \),
\[
a(\epsilon) \leq \frac{m_\varphi(D(x,\epsilon,n))}{|\det Df(x)|E^u(f^n(x))} \leq b(\epsilon).
\]
Both theorems are similar, except that in **Theorem A’**, we cannot guarantee the existence of a family \( \mu^s = \{ \mu^s_x \}_{x \in M} \) on stable leaves satisfying the quasi-invariance.
property \( \mu^*_f = |\det Df| E^u_x|^{-1} \cdot f_* \mu^*_x \). We point out, however, that if we assume that also \( \mathcal{W}^s \) is minimal, then there exists a family \( \mu^{cu} = \{\mu^c_x\}_{x \in \mathcal{M}} \) satisfying the corresponding quasi-invariance. See below for more discussion on the existence of these families.

**Corollary A.** Let \( \alpha : G \curvearrowright \mathcal{M} \) be an Anosov action of class \( \mathcal{C}^2 \). Suppose that \( g \in G \) is an Anosov element such that its associated stable and unstable foliations are minimal and denote \( f = \alpha(g) \). Let \( \varphi : \mathcal{M} \to \mathbb{R} \) be a Hölder potential that is either constant along orbits of \( \alpha \) or the geometrical potential associated to \( f \). Then, there exist a unique equilibrium state \( m_\varphi \in \mathcal{P}_r f(\mathcal{M}) \) for \( \varphi \) and families of measures \( \mu^u = \{\mu^u_x\}_{x \in \mathcal{M}}, \mu^{cs} = \{\mu^{cs}_x\}_{x \in \mathcal{M}} \), satisfying the 1–6 of Theorem A.

In the rank-one case, the previous Theorem (Corollary) was established first by G. Margulis [32] for the entropy maximizing measure (\( \varphi \equiv 0 \)) and later by R. Bowen and D. Ruelle [7] for general potentials, except for 2,3 which appear to be new in this generality; the local product structure is due to N. Haydn [20] (see also [30]). The last item above is the so called Gibbs property. See [6] and [21]. The uniqueness of the equilibrium state is known from other works, for example [14] (see also below for the SRB case).

It is natural to inquire about the requirements imposed to the potentials. It turns out that, in general, families of measures satisfying the quasi-invariance property 3 of Theorems A, A’ may fail to exist.

**Theorem D.** There exists an analytic center isometry \( f : \mathcal{T}^3 \to \mathcal{T}^3 \) and a \( \mathcal{C}^\infty \) potential \( \varphi : \mathcal{T}^3 \to \mathbb{R} \) for which there is no family of measures \( \{\zeta^u_x\}_{x \in \mathcal{M}} \) satisfying

- \( f^{-1}_* \zeta^u_x = e^{\varphi - P_{top}(\varphi)} \zeta^u_x \);
- the measures depend continuously on the point \( x \).

Let us say a few words about the SRB case. The existence of SRB measures in the context with which we are working also follows from the general results in [37], while the uniqueness was initially proven by Dolgopyat in [16]. Nevertheless, the other parts of the theorem are new, and therefore, we are able to make a contribution to the study of SRB measures for partially hyperbolic systems in a setting that has not yet been explored thoroughly (i.e. zero Lyapunov exponents in the center direction).

At this point, we bring to the attention of the reader the following characterization of such measures: an invariant measure \( m \) is an SRB (that is, an equilibrium state for \( \varphi(x) = -\log |\det Df| E^u_x| \)) if and only if for every measurable partition subordinated to the unstable foliation, the conditional measures induced by \( m \) are absolutely continuous with respect to Lebesgue on the corresponding leaf. Here, we are able to give similar characterization for equilibrium states (that is, new even in the classical hyperbolic case); however, for certain non-uniformly interval expanding maps, there exist similar characterizations [15], [10]. We highlight that the result relies on the existence of a family of measures as given in Theorem A and could be applied under different hypotheses that guarantee such an existence. This is the case for time-one maps of (mixing) Anosov flows due to the results of Haydn cited above (see also Section 6), or for Anosov diffeomorphisms (where the condition of the potential being constant on center leaves is automatic).
Theorem B. Let \( f : M \to M \) be a \( C^2 \) center isometry and \( \varphi : M \to \mathbb{R} \) a Hölder potential. Suppose the existence of a family \( \mu^u = \{ \mu^u_x \}_{x \in M} \) satisfying 2,3 of Theorem A. For an \( f \)-invariant measure \( m \), the following conditions are equivalent.

1. \( m \) is an equilibrium state for \( \varphi \).
2. For every \( m \)-measurable partition \( \xi \) subordinated to \( \mathcal{W}^u \), the induced conditional measures are absolutely continuous with respect to \( \{ \mu^u_x \}_{x} \).

Furthermore, if there also exists a family \( \mu^s = \{ \mu^s_x \}_{x \in M} \) satisfying 2,3 of Theorem A, then conditions 1 and 2 are also equivalent to:

3. for every \( m \)-measurable partition \( \xi \) subordinated to \( \mathcal{W}^s \), the induced conditional measures are absolutely continuous with respect to \( \{ \mu^s_x \}_{x} \).

The last part is somewhat surprising in the SRB case (for systems where the stable measures exist, as mixing hyperbolic ones) because, in general, \( \mu^s_x \) will not be absolutely continuous with respect to Lebesgue; assuming the existence of Condition 3 is just Condition 2 for \( f^{-1} \).

Remark 1.1. More generally, in the previous theorem, instead of \( f \) being a center isometry, one can assume that for every \( f \)-invariant measure, the center Lyapunov exponents vanish. The proof is the same.

As a result, we get this new piece in the ergodic theory of Anosov flows (or diffeomorphisms).

Corollary B. Given a transitive Anosov flow \( \Phi = \{ f^t \}_t \) of class \( C^2 \) that is not a suspension, there exists a family \( \mu^u \in \text{Meas}(\mathcal{W}^u) \) satisfying the following: for any \( m \in \mathcal{P} r(M) \), if

1. \( m \) is \( f^t \)-invariant for some \( t \neq 0 \), and
2. \( m \) has conditionals absolutely continuous with respect to \( \mu^u \),

then \( m \) is the unique equilibrium state for the system \( (\Phi, \varphi) \).

Due to the uniqueness of the equilibrium state given in Theorems A, A', it follows from convexity of the pressure function that it is ergodic; however, this type of general argument does not yield any stronger metric property. Here, we will rely on the precise description that we have of the equilibrium state and employ geometrical methods to establish that, in fact, this measure is a Bernoulli measure. Again, the proof is written in more generality than what was assumed in the aforementioned theorems.

Theorem C. Let \( f : M \to M \) be a \( C^2 \) center isometry and \( \varphi : M \to \mathbb{R} \) a potential that is constant on center leaves, or the SRB potential. Suppose that the unstable foliation of \( f \) is minimal and let \( m_\varphi \) be the (ergodic) equilibrium state for \( (f, \varphi) \). Then, the system \( (f, m_\varphi) \) is metrically isomorphic to a Bernoulli shift.

In particular, if \( f : M \to M \) is conservative, then the volume is an Bernoulli measure for \( f \).
The methods developed in this article are of geometric flavor, and it is the hope of the authors that they can shed light on the theory of thermodynamic formalism for partially hyperbolic systems, which is still under development. Evidence of their efficacy appears in a companion article [13], where we establish new results in the ergodic theory of the classical rank-one case.

Comparison with other works

Other geometrical constructions exist in the literature, particularly the work of Climenhaga, Pesin and Zelerowicz [14], based on geometric measure theory, and the work of Spatzier and Vischer [49], studying compact extensions of Anosov systems. Our results have some intersection with the first cited work, but our methods are completely different and allow us to have more control over the equilibrium measures, particularly in terms of their conditional measures along the invariant foliations. Climenhaga et al. obtain the equilibrium state in some more general settings than the ones considered here. They construct families of measures $\mu^u$ as the ones described in Theorem A (that is, satisfying 2, 3, 4) and use them to construct a unique equilibrium state for the system satisfying 6. However, they do not seem to get much control on the transverse measures (the $\mu^{cs}_{x}$ in our theorems), and their existence is deduced only locally (disintegrating in small rectangles).

Our approach is different: we first construct the measures $\mu^{cs}_{x}$ globally and then use them to define the equilibrium measure in cases where a family $\mu^u$ satisfying 2, 3 of Theorem A exists. We remark that for the potentials considered in [14], we could use the existence of $\mu^u$, given their work to construct $m_{\varphi}$, and in particular, verify the hypotheses of Theorem B and perhaps Theorem C with some additional work (for the Bernoulli property, some knowledge on the unstable measures is required). The extra control on the transverse measure is used in [13] to deduce a strengthening of the Furstenberg-Marcus theorem on unique ergodicity of the unstable foliation of mixing Anosov flows.

In contrast, the precise characterization given in Theorem B for equilibrium states is (as far as we know) new in the literature. In addition, Theorem C establishes very fine statistical properties for the equilibrium state, using geometrical methods (julienne quasi-conformality) that probably could be used in other situations. It may be fruitful, for example, to analyze a possible synergy between these methods and the results of Climenhaga, Pesin and Zelerowicz.

We point out that in [31], it is also shown that the equilibrium measure built by [14] is Bernoulli. In this work, we present two proofs of the fact that the system is Kolmogorov. One proof is essentially the same as [31] (which is due to Ledrappier), and the other proof is a more geometrical one based on arguments developed by Pugh and Shub to study (stably) ergodicity of conservative partially hyperbolic maps. For the Bernoulliness, we adapt the method of Ornstein and Weiss. This is also the approach followed in Li and Wu’s work; however, the authors do not give all details and seem to leave some nonobvious parts for the reader to complete. Due to the importance of this theorem, we elaborate more on the proof.

Additional related work appears in the manuscript [11] by Buzzi, Fisher and Tahzibi, containing some results similar to ours for perturbations of time-one maps of Anosov flows in dimension three in the case of the entropy maximizing measure, and in the
recent preprint [2] by Bonthonneau, Guillarmou and Welch, studying SRB measures for the action, instead of a regular element, as in our case. The techniques in this last cited work are of the functional analytic type, and it seems that our approaches may be complementary. This remains as an interesting research line to be investigated.

**Systems verifying the hypotheses of the Theorems and related questions**

The conditions imposed on the potential $\varphi$, being constant on center leaves or equal to the geometrical potential, are used to guarantee the existence of the family $\mu^u$. As it can be seen using Theorem D, some additional assumptions are necessary, although at this stage, it is still not clear what those are.

**Question.** If $f : M \to M$ is a $C^2$ center isometry with minimal strong foliations and $\varphi : M \to \mathbb{R}$ is a Hölder potential, what are the conditions that guarantee the existence of a family $\mu^u$ satisfying 2, 3 of Theorem A?

In particular,

**Question.** Assume the hypotheses of Theorem A and, furthermore, that $f$ is accessible, meaning any bi-saturated set (that is, a set that is a union of both stable and unstable leaves). Does there exist a continuous family $\mu^u \in \text{Meas} (W^u)$ in this case?

We remark that the example given in the Appendix does not satisfy this condition, but only essential accessibility (any bi-saturated set by $W^u$, $W^s$ has Lebesgue measure either zero or one).

Requiring that $\varphi$ is constant on center leaves is usually a strong requirement because in several situations there exist dense center leaves, which forces $\varphi$ to be constant. Although this may be true, the constant zero potential corresponds to the entropy maximizing measure of the system which is undoubtedly important. However, there are several interesting cases without dense center leaves (for example, group extensions of hyperbolic systems), where the condition of constancy on center leaves includes an infinite dimensional space of potentials.

For the SRB potential, the existence of $\mu^u$ is automatic, and the study of the associated equilibrium state is paramount in smooth ergodic theory (including, for example, the conservative case). We emphasize, however, that given the existence of $\mu^u$, the results of this article can be applied. There are situations where this is the case. For example:

1. $f =$ time-one map of a mixing Anosov flow (see Section 6.1).
2. The potentials having the cs-Bowen property considered by Climenhaga, Pesin and Zelerowicz in [14] (cf. Lemma 3.16). This includes, in particular, the family of potentials $\varphi_t = -t \log \vert \det Df \vert |E^u|$.

This is the reason why we have written our results with more generality, with the hope that it could be used in other situations. Observe, for example, that in the first case, the family $\mu^s$ also exists, and therefore, by Theorem B, we get that the (unique) SRB measure is characterized by a family of measures on the stable (which are not absolutely continuous, unless the system is conservative).
The proof of Theorem B is based on the abstract methods used by Ledrappier and Young for the SRB measure, and in particular, apply also for systems whose Lyapunov exponents in the center direction are zero for every invariant measure. One is led to ask whether this can be extended in the non-uniformly hyperbolic setting, although this seems to be out of reach at the moment. Perhaps one could start with the following.

**Question.** Suppose that \( f : M \to M \) is a \( C^2 \) diffeomorphism and \( \varphi : M \to \mathbb{R} \) is a Hölder potential. Assume that the system \((f, \varphi)\) has a non-uniformly hyperbolic equilibrium state \( m_\varphi \) (in the sense of Pesin [35]). Construct a family of \( \{ \mu_x^u \}_{x \in M'} \) where \( m_\varphi(M') = 1 \), satisfying the quasi-invariance hypothesis 2 of Theorem A.

The fact that equilibrium states are determined by some families of measures on a dynamical structure (the invariant foliations) seems to indicate strong restrictions on the geometry of these measures. In Section 4, we establish the existence of a family of measures \( \{ \nu_x^u \}_{x \in M} \) on the unstable leaves such that if \( m \) is an invariant measure satisfying: given \( \xi \) a \( m \)-measurable partition subordinated to \( W^u \), the conditional measure of \( m \) on the atom \( \xi(x) \) is equal to \( \nu_x^u(\cdot | \xi(x)) \), for \( m \)-a.e.\( (x) \). Then, \( m \) is an equilibrium state of the system.

**Question.** Assume that \( f : M \to M \) is a \( C^2 \) center isometry and \( \varphi : M \to \mathbb{R} \) is a Hölder potential. Suppose the existence of a family \( \nu^u = \{ \nu_x^u \}_{x \in M} \) as explained above. If \( m \) is a (non-necessarily invariant) probability with conditionals given by \( \nu^u \), then is \( m \) an equilibrium state?

Even though this seems unlikely due to the lack of control in the transverse directions, we give a positive answer to this problem for codimension-one Anosov flows in [13].

**Organization of the rest of the article**

The rest of the paper is organized as follows. In Section 2, we develop general arguments to establish the existence of families of measures on foliations with prescribed invariance properties (conformality). These results are then used in Section 3 to construct the equilibrium state for a center isometry as in Theorem A. Then, in Section 4, we tackle the problem of the characterization of equilibrium states in terms of their conditional measures on stable/unstable leaves. Section 5 is devoted to the proof of the Bernoulli property of the considered system, and in the last Section, we include a discussion of the rank-one case (in particular, the proof of Corollary B), together with some questions. The proof of Theorem D is given in Section 7 (Appendix), since it can be read almost independently of the rest of the work (although Theorem A and Theorem B are used).

**2. Measures along foliations**

For \( r \geq 1 \), we denote by \( \mathcal{D}iff^r(M) \) the group of \( C^r \) diffeomorphisms of a manifold \( M \). Let \( f \in \mathcal{D}iff^r(M) \) and \( \mu \) be an \( f \)-invariant measure. Recall that (see [45]) given a \( \mu \)-measurable partition \( \xi \) of \( M \), we can disintegrate \( \mu \) in a family of conditional probabilities \( \{ \mu_x^\xi \}_{x \in M'} \) with \( \mu(M') = 1 \) such that for every \( f \in L^1(M, \mu) \), the conditional expectation
of $f$ in $\mathcal{B}_\xi$, the $\sigma$-algebra generated by $\xi$, is given by

$$\mathbb{E}_\mu(f|\mathcal{B}_\xi) = \int f d\mu_x^\xi, \quad x \in M'.$$

Furthermore, if $\xi$ is countably generated (that is, $\xi = \bigvee_n \xi_n$ with $\xi_n$ finite partition for every $n \in \mathbb{N}$), then for $x, y \in M'$, if $y$ belongs to the atom of $\xi$ containing $x$, then $\mu_x^\xi = \mu_y^\xi$. In this case, denote by $M_\xi = M/\xi$ the space of atoms of $\xi$ and consider $\pi_\xi : M \to M_\xi$, $\pi_\xi(x) = \xi(x)$, the atom that contains $x$ (this map is well-defined $\mu$-a.e.).

We equip $M_\xi$ with the $\sigma$-algebra induced by $\pi_\xi$ and consider the transverse measure $\mu = (\pi_\xi)\mu$. The considerations above imply, in particular, that if $\xi$ is countably generated, then $\eta = \xi(x) \mapsto \mu_\eta^\xi := \mu_x^\xi$ defines a measurable function from $M_\xi$ to the set of Borel probabilities on $M$, and furthermore,

$$A \in \mathcal{B}_M \Rightarrow \mu(A) = \int_{M_\xi} \mu_\eta^\xi(A) \mu_\xi(\mathrm{d}\eta).$$

This shows that $\mu$ is completely determined provided that we know $\mu_\xi$ and $\{\mu_\eta^\xi\}_{\eta \in M_\xi}$.

Our interest, however, is constructing a particular $f$-invariant measure $\mu$ (the equilibrium state); for this, we will argue backwards and construct first the transverse measure and the conditionals. Of course, this presents several technical difficulties, mainly because we do not have the partition $\xi$, and there is not a well-defined notion of what it means to be $\mu$-measurable.

A way to circumvent this problem is using some (continuous) invariant structure of $f$ to define the partition. In the next part, we present a general construction that allows us to build families of measures satisfying certain (quasi-)invariant properties.

The core of our construction in this part is inspired by the work of G. Margulis [32], who considered (mixing) Anosov flows and the trivial potential $\varphi \equiv 0$.

### 2.1. Families of quasi-invariant measures

Let $X$ be a locally compact metric space and $f : X \to X$ a bi-measurable map. From now on, by a measure on $X$, we mean a Radon measure and denote the set of such measures by $\mathcal{R} \circ \mathcal{d}(X)$. The set of continuous functions with compact support on $X$ is denoted by $\mathcal{C}_c(X)$. The set $\mathcal{C}_c(X)$ is equipped with the uniform topology, while $\mathcal{R} \circ \mathcal{d}(X)$ is equipped with the vague one.

**Notation:** If $\phi$ is measurable, we write $f\phi := \phi \circ f$. If $\mu \in \mathcal{R} \circ \mathcal{d}(X)$, the measure $f\mu = f_*\mu$ is the unique measure $\nu$ such that

$$\forall \phi \in \mathcal{C}_c(X), \quad \int f\phi \mathrm{d}\mu = \int \phi \mathrm{d}\nu.$$

With the above, it is direct to verify that for $\mu, \nu \in \mathcal{R} \circ \mathcal{d}(X)$, $\mu = \rho \nu$, it holds that $f\mu = f^{-1}\rho f\nu$. Recall that $\mu \in \mathcal{R} \circ \mathcal{d}(X)$ is quasi-invariant if $f^{-1}\mu \sim \mu$; in this case, we can write $f^{-1}\mu = h_\mu \mu$, where $h_\mu = \frac{df^{-1}}{d\mu} \mu$. Similarly, $f^{-n}\mu = h_\mu^{(n)} \mu$.

---

1From now on, we omit the $*$ in push forwards.
As it can be deduced directly from the uniqueness of the Radon-Nikodym derivative, the family \( \{ h^{(n)} \}_{n \in \mathbb{Z}} \) is a multiplicative cocycle over \( f \) with generator \( h \).

**Multiplicative cocycles.** A family \( \{ h^{(n)} : X \to \mathbb{R}_{\geq 0} \}_{n \in \mathbb{Z}} \) is a multiplicative cocycle over \( f \) if

\[
\forall n, m \in \mathbb{Z}, x \in M \Rightarrow h^{(n+m)}(x) = h^{(n)}(f^m x) \cdot h^{(m)}(x).
\]

Given \( h : X \to \mathbb{R}_{>0} \), it generates a multiplicative cocycle over \( f \) (and in this case, we call \( h \) the generator of the cocycle) by defining

\[
h^{(n)}(x) = \begin{cases} 
\prod_{k=0}^{n-1} h(f^k x) & k > 0 \\
1 & k = 0 \\
\prod_{k=1}^{-n} h^{-1}(f^k x) & k < 0.
\end{cases}
\]

Observe that if \( \{ h^{(n)} \}_{n \in \mathbb{Z}} \) is a positive multiplicative cocycle over \( f \) (with generator \( h \)), then \( \{ a^{(n)} := \log h^{(n)} \}_{n \in \mathbb{Z}} \) is an additive cocycle (with generator \( \log h \)):

\[
\forall n, m \in \mathbb{Z}, x \in M \Rightarrow a^{(n+m)}(x) = a^{(n)}(f^m x) + a^{(m)}(x).
\]

It will be useful to introduce the following.

**Definition 2.1.** Let \( M, \Lambda \) be sets. We say that \( M \) is a bundle over \( \Lambda \) if can be written as

\[
M = \bigsqcup_{i \in \Lambda} M_i
\]

where \( M_i \) is a locally compact metric space, for every \( i \in \Lambda \). We say that \( f : M \to M \) is a bundle isomorphism if there exists a bijection \( q : \Lambda \to \Lambda \) such that \( f|_{M_i} : M_i \to M_{q(i)} \) is a homeomorphism, for every \( i \in \Lambda \).

**Remark 2.1.** In the definition above we are not assuming, a priori, any topology on \( M \), and therefore, we do not require any global continuity for bundle morphisms. In the cases of interest, \( M \) will be manifold and each \( M_i \) an immersed (but not necessarily embedded) sub-manifold.

For example, if \( M \) is a (Riemannian) manifold and \( \mathcal{F} = \{ W(x) \}_{x \in M} \) a foliation on \( M \) with smooth leaves, then the metric on \( M \) induces corresponding metrics, which in turn define a natural topology on each leaf, and we can write \( M = \bigsqcup_{L \in \Lambda} L \), where \( \Lambda = M/\mathcal{F} \). Thus, \( M \) is a bundle over \( \Lambda \). Furthermore, if \( f : M \to M \) is a diffeomorphism and \( \mathcal{F} \) is \( f \)-invariant, then \( f \) induces a bijection \( q : \Lambda \to \Lambda, q(L) = f(L) \), and thus, \( f \) is a bundle equivalence.

Consider the bundles over \( \Lambda \) given as

\[
\text{Con} := \bigsqcup_{i \in \Lambda} C_c(M_i)
\]

\[
\text{Rad} := \bigsqcup_{i \in \Lambda} \mathcal{R}ad(M_i)
\]
and consider also the space of sections of Rad,
\[ \text{Meas} := \{ \nu : \Lambda \to \text{Rad} : \nu_i := \nu(i) \in \mathcal{R} \circ d(M_i) \forall \ i \in \Lambda \}. \]

The natural topology of Meas is the weak topology determined by Con; it is a locally convex topology. Let \( \text{Con}^+ := \{ \phi \in \text{Con}, \phi \geq 0, \phi \not\equiv 0 \} \).

**Lemma 2.2.** Suppose that \( \mathcal{A} \subset \text{Meas} \) satisfies
1. for every \( \psi \in \text{Con} \), there exists \( c(\psi) > 0 \) with the property that for every \( \mu \in \mathcal{A}, \mu(\psi) \leq c(\psi) \).
2. For every \( \psi \in \text{Con}^+ \), there exists \( d(\psi) > 0 \) with the property that for every \( \mu \in \mathcal{A}, \mu(\psi) \geq d(\psi) \).

Then, \( \text{cl} \mathcal{A} \subset \text{Meas} \) is compact, and furthermore, it does not contain the zero section.

**Proof.** This is a direct consequence of Tychonoff’s theorem. \( \square \)

From now on, we assume that \( f \) is a bundle equivalence.

**Definition 2.2.** \( \nu \in \text{Meas} \) is quasi-invariant if for every \( i \in \Lambda \), \( f^{-1} \nu_{qi} \sim \nu_i \) with positive continuous Radon-Nikodym derivative \( \rho_i = \frac{df^{-1} \nu_{qi}}{d\nu_i} \). In this case, \( \rho : M \to \mathbb{R}_{>0} \) given by \( \rho|_{M_i} = \rho_i \) will be called the Jacobian of \( \nu \).

One verifies directly that if \( \nu \) is quasi-invariant, then \( \rho \) generates a (multiplicative) cocycle over \( q \), and we write \( \tilde{\rho} = \log \rho \) for the corresponding additive cocycle.

Now suppose that \( \varphi : M \to \mathbb{R} \) is a function such that its restriction to each \( M_i \) is continuous for each \( i \), and \( \nu \in \text{Meas} \) is quasi-invariant: we are interested in finding \( \mu \in \text{Meas} \) quasi-invariant with Jacobian \( e^{-\varphi} \). Consider \( \nu^n = e^{S_n \varphi} \cdot f^{-n} \nu_i \), i.e.

\[ \nu^n_i = e^{S_n \varphi} \cdot f^{-n} \nu_{q^n(i)} = e^{S_n \varphi + S_n \tilde{\rho}} \cdot \nu_i \] (2.1)

and let \( \mathcal{C}^+ \) be the positive cone generated by \( \{ \nu^n \}_{n \geq 0} \),

\[ \mathcal{C}^+ = \left\{ \sum_{j=1}^{k} a_j \nu^{n_j} : a_j \geq 0, k \in \mathbb{N} \right\}. \] (2.2)

**Theorem 2.3.** Suppose that \( M = \bigsqcup_{i \in \Lambda} M_i \) is a bundle over \( \Lambda \), \( f : M \to M \) is a bundle equivalence, \( \varphi : M \to \mathbb{R} \) is a function such that its restriction to each \( M_i \) is continuous, and \( \nu \in \text{Meas} \) is quasi-invariant. Assume that \( \{ \nu^n = e^{S_n \varphi} \cdot f^{-n} \nu \}_{n \geq 0} \) satisfies:

- if \( \phi \in \text{Con}^+ \), then \( \nu^n(\phi) > 0 \) for all \( n \).
- Given \( \phi, \psi \in \text{Con} \) with \( \phi \not\equiv 0 \) non-negative, there exists \( e(\phi, \psi) > 0 \) such that for every \( n \geq 0 \), it holds that

\[ \frac{\nu^n(\psi)}{\nu^n(\phi)} \leq e(\phi, \psi). \]

Then, there exist \( P \in \mathbb{R} \) and a quasi-invariant \( \mu \in \mathcal{C}^+ \) with Jacobian \( e^{P - \varphi} \). Moreover, \( \mu \) has full support on each \( M_i \).
Proof. Define $S : \text{Meas} \rightarrow \text{Meas}$ by

$$S(\mu)_i = e^{\varphi} \cdot f^{-1}\mu_{q(i)}.$$ 

Then, $S$ is continuous and sends $C^+$ to itself. We compute

$$S(\nu^n)_i = e^{\varphi} \cdot f^{-1}\nu^n_{q(i)} = e^{\varphi} \cdot f^{-1}(e^{S_n \varphi} f^{-n} \nu_{q^n+1}(i)) = e^{S_n \varphi \circ f} \cdot f^{-n-1} \nu_{q^n+1} = \nu^{n+1}_i. \tag{2.3}$$

Fix a non-negative, non-identically zero function $\phi_0 \in \text{Con}$ and let $\hat{\nu}^n := \frac{\nu^n}{\nu(\phi_0)}$; consider the set

$$X = \text{cl}\left\{ \sum_{i=1}^k a_i \hat{\nu}^{n_i} : a_i \geq 0, k \in \mathbb{N}, \sum_{i=1}^k a_i = 1 \right\} \tag{2.4}$$

$$= \text{cl}\{ \nu \in C^+ : \nu(\phi_0) = 1 \}. \tag{2.5}$$

By Lemma 2.2 and the assumed hypotheses, $X$ is a compact convex subset of $\text{Meas}$, and by Equation (2.3), the normalized operator $S\nu := S\nu(\phi_0)$ sends $X$ to itself. Hence, by the Schauder-Tychonoff fix point theorem, there exists $\mu \in X$ such that $S(\mu) = \mu$. In other words, $\psi \in \text{Con}$ implies

$$\mu_{q(i)}(\psi \circ f^{-1}e^{\varphi \circ f^{-1}}) = e^P \cdot \mu_i(\psi) \quad (\Rightarrow f^{-1}\mu_{q(i)} = e^{P-\varphi} \cdot \mu_i), \tag{2.6}$$

where $e^P = S\mu(\psi_0) > 0$.

Observe that if $\psi \in \text{Con}$ is non-negative and non-identically zero, then for some constant $c(\psi) > 0$, it holds that $\hat{\nu}^n(\psi) > 0$ for all $n \geq 0$, and thus, the same is valid for $\mu$. Therefore, $\mu$ has full support on each $M_i$, and the proof of the Theorem is complete. \hfill \square

2.2. Quasi-invariant measures along leaves of foliations: the transverse measure

We will now apply the construction of the previous part to the following setting.

H-1 $M$ is a compact (closed) smooth Riemannian manifold, and $\mathcal{F} = \{F(x)\}_{x \in M}$ is continuous foliations with smooth leaves. We consider the bundle structure of $M = \bigsqcup_{F \in \Lambda} F$ over $\Lambda = M/\mathcal{F}$ and denote $\text{Con}(\mathcal{F}), \text{Meas}(\mathcal{F})$ the corresponding associated bundles.

H-2 $f$ is a diffeomorphism of $M$ of differentiability class $C^2$.

H-3 $\mathcal{F}$ is $f$-invariant; the induced map by $f$ on $\Lambda$ is denoted by $q$.

H-4 There exists a complementary continuous foliation $\mathcal{G} = \{G(x)\}_{x \in M}$ of $\mathcal{F}$ with smooth leaves, and such that

(a) $\mathcal{G}$ is minimal: each leaf $G(x)$ is dense.

(b) $\mathcal{G}$ is $f$-invariant.

(c) $\mathcal{G}$ is contracting under $f$: if $d_{\mathcal{G}}$ denotes the intrinsic distance (on the corresponding leaf of $\mathcal{G}$), we have

$$\forall x, y \in M, y \in G(x) \Rightarrow d_{\mathcal{G}}(fx, fy) \leq \lambda d_{\mathcal{G}}(x, y)$$

for some $0 < \lambda < 1$. 


The idea is that if $B$ is a foliated box corresponding to $F$, we will use the (measurable) partition $F|B$ to play the role of the quotient space where we define our transverse measure. The existence of a complementary contracting foliation is used (crucially) to ensure the compactness property necessary for Lemma 2.2.

**Notation:** If $A \subset M, \epsilon > 0$, let

$$G(A, \epsilon) := \{ y \in M : \exists x \in A / d_G(x, y) < \epsilon \},$$

and if $A = \{ x \}$, we write $G(x, \epsilon) = G(\{ x \}, \epsilon)$.

**Definition 2.3.** Let $\delta > 0$.

1. Two relatively compact sets $A_1 \subset F_{i_1}, A_2 \subset F_{i_2}$ are $\delta$-equivalent if there exists a holonomy transport (Poincaré map) $\text{hol}^G: F_{i_1} \to F_{i_2}$ induced by $G$ satisfying:
   (a) $\text{hol}^G|A_1$ is a homeomorphism of $A_1$ onto $A_2$.
   (b) For every $x \in A_1, \text{hol}^G(x) \in G(x, \delta)$.

2. Two functions $\psi_1, \psi_2 \in \text{Con}(\mathcal{F})$ are $\delta$-equivalent if $\text{supp}(\psi_1)$ is $\delta$-equivalent to $\text{supp}(\psi_2)$, and for every $x \in \text{supp}(\psi_1), \psi_2(\text{hol}^G(x)) = \psi_1(x)$. Here, $\text{supp}$ denotes the support of the corresponding continuous function, while $\text{hol}^G$ is the holonomy map connecting $\text{supp}(\psi_1)$ with $\text{supp}(\psi_2)$.

Observe that given $\psi \in \text{Con}(\mathcal{F}), \delta > 0$, there exists $\gamma = \gamma(\psi, \delta) > 0$ such that if $x \in G(\text{supp}(\psi), \gamma)$, then

- the transverse foliation defines an homeomorphism onto its image $\text{hol}^G|: \text{supp}(\psi) \to F(x)$.
- $\psi_{F(x)} := \psi \circ \text{hol}^G$ is continuous, of compact support, and $\delta$-equivalent to $\psi$.

We seek to find a quasi-invariant $\nu \in \text{Meas}(\mathcal{F})$ with regular Radon-Nikodym derivative. A natural class is obtained by fixing a Riemannian metric on $M$ and considering $\text{Leb} \in \text{Meas}(\mathcal{F})$ given by

$$F \in \Lambda \Rightarrow \text{Leb}_F = \text{induced Lebesgue measure on the leaf } F.$$  

By the basic change of variables theorem, $\text{Leb}$ is quasi-invariant and its Jacobian is $\rho_F = |\det Df|F|$. Due to compactness of $M$, we have that

$$\rho$$

is uniformly bounded from below: $\rho(x) \geq C_\rho > 0 \forall x \in M$,

and since $f \in \text{Diff}^{1+\alpha}(M)$, we get that $\rho$ (and therefore, $\tilde{\rho} = \log \rho$) is $\alpha$-Hölder.

**Remark 2.4.** In the abstract definition of Jacobian given before, we did not consider the variation of this function for points in different fibers of $M$. Note, however, that in the hypotheses of this part, the globally defined map $\rho : M \to \mathbb{R}_{>0}$ is continuous. Furthermore, if $T\mathcal{F}$ is Hölder (something common in applications), then $\rho$ is globally Hölder as well.

We will use the minimality of $G$ to compare sets (functions) defined on different leaves of $\mathcal{F}$. It is necessary, however, to control how families of measures $\nu = \{ \nu_F \}_{F \in \mathcal{F}}$ vary with
the transverse holonomy given by $\mathcal{G}$. By transversality between $\mathcal{F}$ and $\mathcal{G}$ and compactness of $M$, it holds that given $\delta_0 > 0$, there exists $\delta_1 > 0$, so that for every $x, y \in M, y \in G(x, \delta_0)$,

$$F(y, \delta_1)$$ is $\delta_0$-equivalent to some subset of $F(x)$.

**Definition 2.4.** $\nu \in \text{Meas}(\mathcal{F})$ is absolutely continuous if for every (locally defined) holonomy transport $\text{hol}_G^\mathcal{F}: F_{i_1} \to F_{i_2}$, $\text{hol}_G^\mathcal{F}_i \sim \nu_{F_{i_2}}$. It is strongly absolutely continuous if there exist $\delta_0 > 0$ and $J : \{(x, y, z) \in M \times M \times M, y \in G(x, \delta_0), z \in F(y, \delta_1)\} \to \mathbb{R}$ continuous such that if $B = F(y, \delta_1), A = \text{hol}_G^\mathcal{F}(B) \subset F(x)$, then

$$\text{hol}_G^\mathcal{F}_i \nu_{F_{i_1}}|A = J(x, y, \cdot)\nu_{F_{i_1}}|B.$$

**Proposition 2.4.1.** Leb is strongly absolutely continuous.

**Proof.** This result is classical by now and relies on the contracting behavior of $\mathcal{G}$ together with the fact of $f$ being of class $C^{1+\alpha}, \alpha > 0$. See [40].

For strongly absolutely continuous sections, we have the following.

**Proposition 2.4.2.** Assume that $\nu$ is strongly absolutely continuous and of full support on every $F \in \mathcal{F}$. Then, given $\epsilon > 0$, there exists $\delta > 0$ such that for every $\psi_1, \psi_2 \in \text{Con}(\mathcal{F})$ that are $\delta$-equivalent and non-identically zero, it holds that

$$\left| \int \psi_1 d\nu_{F_{i_1}} - \int \psi_2 d\nu_{F_{i_2}} \right| < \delta \int |\psi_1| d\nu_{F_{i_1}}.$$  

**Proof.** We start by noting that since $\nu$ is strongly absolutely continuous, given $\epsilon > 0$, there exists $\delta$ such that if $A, B$ are $\delta$-equivalent (with nontrivial measure), then

$$\left| \frac{\nu(A)}{\nu(B)} - 1 \right| < \epsilon. \quad (2.7)$$

The remaining part of the argument is explained in [32]; for convenience of the reader, we repeat it here.

**Claim.** Given $\epsilon > 0$, there exists $\delta > 0$ such that for every $\psi_1, \psi_2 \in \text{Con}(\mathcal{F})$ that are $\delta$-equivalent, non-identically zero and non-negative, it holds that

$$\left| 1 - \frac{\int \psi_2 d\nu_{F_{i_2}}}{\int \psi_1 d\nu_{F_{i_1}}} \right| < \delta.$$  

**Proof.** Given $\epsilon > 0$, let $\delta > 0$, as above, and consider $\psi_1, \psi_2$ under the hypotheses of the claim. Let $A \subset F_{i_1}, B \subset F_{i_2}$ be the supports of $\psi_1, \psi_2$. Then, by the Radon-Nikodym theorem, we can write

$$\int \psi_1 d\nu_{F_{i_1}} = \int \psi_2 \cdot j d\nu_{F_{i_2}},$$

where, by (2.7), $|1 - j(z)| < \delta$ for every $z \in B$. Using that $\psi_1, \psi_2$ are non-negative, we deduce

$$(1 - \delta) \cdot \int \psi_2 d\nu_{F_{i_2}} \leq \int \psi_1 d\nu_{F_{i_1}} \leq (1 + \delta) \cdot \int \psi_2 d\nu_{F_{i_2}}$$

which implies the claim. 

\[\square\]
Given \(\psi_1, \psi_2 \in \text{Con}(F)\) that are \(\delta\)-equivalent and non-identically zero, we decompose into their positive and negative parts, \(\psi_1 = \psi_1^+ - \psi_1^-, \psi_2 = \psi_2^+ - \psi_2^-\), and use the previous claim:

\[
\left| \int \psi_1 \, d\nu_{F_1} - \int \psi_2 \, d\nu_{F_2} \right| \leq \left| \int \psi_1^+ \, d\nu_{F_1} - \int \psi_1^+ \, d\nu_{F_2} \right| + \left| \int \psi_2^+ \, d\nu_{F_1} - \int \psi_2^+ \, d\nu_{F_2} \right| \\
\leq \delta \left| \psi_1^+ \, d\nu_{F_1} + \delta \left| \psi_1^- \, d\nu_{F_1} - \psi_1^- \, d\nu_{F_2} \right| = \delta \int |\psi_1| \, d\nu_{F_1}.
\]

The proof is complete. \(\square\)

In what follows, we will be interested in quasi-invariant sections \(\nu \in \text{Meas}(F)\). We introduce the following definition.

**Definition 2.5.** We say that \(\nu \in \text{Meas}(F)\) is appropriate for \(f\) if it satisfies:

1. is strongly absolutely continuous,
2. for every leaf \(F \in F\), \(\nu_F\) has full support,
3. is quasi-invariant with Hölder Jacobian.

**Remark 2.5.** It follows by Proposition 2.4.1 that Leb is appropriate.

Fix \(\nu \in \text{Meas}(F)\) appropriate for \(f\) and consider \(\varphi : M \to \mathbb{R}\) a Hölder continuous potential. Let \(\rho\) be the Jacobian of \(\nu\), \(\hat{\rho} = \log \rho\) and \(\hat{\varphi} = \varphi + \hat{\rho}\); this is a \((C_{\hat{\varphi}}, \theta)\)-Hölder function. For \(n \in \mathbb{N}\), take \(\nu^n = e^{S_n \hat{\varphi}} \cdot f^{-n} \nu = e^{S_n \hat{\varphi}} \nu\) (cf. Equation (2.1)).

**Lemma 2.6.** There exists a constant \(D_1 > 0\) and \(\ell : \mathbb{R}_{>0} \to \mathbb{R}_{>0}\) with the following property. For every \(\delta > 0\), if \(\psi_1, \psi_2 \in \text{Con}^+\) are \(\delta\)-equivalent and \(n \geq 0\), then it holds that

\[
\nu^n(\psi_1) \leq \ell(\delta) \cdot e^{D_1 \delta^\theta} \nu^n(\psi_2).
\]

Furthermore, \(\ell(\delta) \xrightarrow{\delta \to 0} 1\).

**Proof.** Define \(D_1 := C_{\hat{\varphi}} \sum_{i=0}^{\infty} \lambda^i\); since \(\lambda < 1\), \(D < +\infty\). Assume that \(\psi_1, \psi_2\) are \(\delta\)-equivalent, \(\psi_2 \circ \text{hol}^G = \psi_1\). Observe that for every \(x \in \text{supp}(\psi_1)\), for every \(n \geq 0\), it holds that

\[
|S_n \hat{\varphi}(\text{hol}^G x) - S_n \hat{\varphi}(x)| \leq \sum_{i=0}^{\infty} C_{\hat{\varphi}} \cdot d_G(f^i \text{hol}^G x, f^i x)^\theta \leq D_1 \delta^\theta.
\]

It then follows that

\[
\nu^n(\psi_1) = \int e^{S_n \hat{\varphi}} \psi_2 \circ \text{hol}^G \, d\nu = \int e^{S_n \hat{\varphi} - S_n \hat{\varphi} \circ \text{hol}^G} \psi_2 \circ \text{hol}^G e^{S_n \hat{\varphi} \circ \text{hol}^G} \, d\nu \\
\leq e^{D_1 \delta^\theta} \int \psi_2 e^{S_n \hat{\varphi}} \, d\text{hol}^G \nu \leq \ell(\delta) e^{D_1 \delta^\theta} \nu^n(\psi_2),
\]

where \(\ell\) is an upper bound of \(\frac{d\text{hol}^G \nu}{d\nu}\), and therefore converges to 1 as \(\delta \to 0\). \(\square\)
Lemma 2.7. Let $A_1 \subset F_{i_1}, A_2 \subset F_{i_2}$ be relatively open and pre-compact. Then, there exist $\hat{\epsilon}(A_1, A_2) > 0$ such that for every $n \geq 0$, it holds that

$$\frac{1}{\hat{\epsilon}(A_1, A_2)} \leq \frac{\nu^n(A_1)}{\nu^n(A_2)} \leq \hat{\epsilon}(A_1, A_2).$$

Proof. Let us start noting that since $G$ is minimal (on $M$ compact), we have the following property: for any $A \subset F, F \in F$ there exist $\delta(A), r(A) > 0$ such that for every $x \in M$, one can find $B_x \subset A$ that is $\delta(A)$-equivalent to $F(x, r(A))$.

By relative compactness of $\text{cl} A_1$, the closure of $A_1$ inside $F_{i_1}$, it follows that $\text{cl} A_1 \subset \bigcup_i^n F(x_j, r(A_2))$, where each plaque $F(x_j, r(A_2))$ is $\delta(A_2)$-equivalent to some $B_j \subset A_2$.

Fix two of these sets $E_1 = F(x_j, r(A_2)), E_2 = B_j$ and denote by $\text{hol}^G$ the holonomy transport such that $\mathbb{1}_{E_1} = \mathbb{1}_{E_2} \circ \text{hol}^G$. By regularity of $\nu_{F_{i_2}}$ we can find a non-decreasing sequence $(\phi_k)_k \subset C_c(F_{i_2})$ satisfying

1. $k \in \mathbb{N} \Rightarrow 0 \leq \phi_k \leq 1, \text{supp}(\phi_k) \subset \text{cl} A_2$.
2. $\lim_{k \to \infty} \phi_k(x) = \mathbb{1}_{A_2}(x)$.
3. $\nu^n(A) = \lim_k \uparrow \nu^n(\phi_k)$.

Define $\psi_k = \phi_k \circ \text{hol}^G$ and apply the previous lemma to deduce that for every $n$,

$$\frac{\nu^n(E_1)}{\nu^n(E_2)} = \frac{\lim_k \nu^n(\psi_k)}{\sup_k \nu^n(\phi_k)} \leq \frac{\sup_k \psi_k}{\phi_k} \leq \ell(\delta(A_2)) e^{D_1 \delta(A_2)^\rho} := e_0.$$ 

Therefore,

$$\frac{\nu^n(A_1)}{\nu^n(A_2)} \leq \frac{\nu^n(F(x_j, r(A_2)))}{\nu^n(A_2)} \leq m \cdot \max_j \frac{\nu^n(F(x_j, r(A_2)))}{\nu^n(B_j)} \leq m \cdot e_0.$$ 

From here, the conclusion follows. \hfill $\Box$

Corollary 2.8. Fix $\psi \in \text{Con}^+(F)$. Then, for every $\phi \in \text{Con}(F)$, there exists $\hat{\epsilon}(\phi, \psi) > 0$ such that for every $n \geq 0$, it holds that

$$\frac{\nu^n(\phi)}{\nu^n(\psi)} \leq \hat{\epsilon}(\phi, \psi).$$

Proof. This is essentially Lemma 2.4 of [32]. For $r > 0$, let $A_r := \psi^{-1}(r, \infty)$ and note that since $\psi \in \text{Con}$ is non-negative and non-identically zero, there exists $r > 0$ such that $A_r$ is relatively open and pre-compact inside the leaf of $F$ that contains $\text{supp}(\psi)$. Take $A$ open, relatively compact containing $\text{supp}(\phi)$ and use the previous Lemma to deduce

$$\frac{\nu^n(\phi)}{\nu^n(\psi)} < \frac{\|\phi\|_\infty \cdot \nu^n(A)}{r \cdot \nu^n(A_r)} < \frac{\|\phi\|_\infty}{r} \hat{\epsilon}(A, A_r).$$

We have thus shown that in the assumed conditions $H - 1$ to $H - 4$, there exists an appropriate $\nu$ (Remark 2.5), and therefore, by Corollary 2.8, we get that the hypotheses
of Theorem 2.3 are satisfied. Thus, we conclude the existence of \( P \in \mathbb{R} \) and \( \mu \in \text{Meas}(F) \) such that

1. \( \mu \) is in the closure of the positive cone generated by \( \{ \nu^n \}_{n \geq 0} \) (and thus has full support on each leaf of \( F \)),
2. \( \mu \) is quasi-invariant, with Jacobian \( e^{P - \varphi} \).

**Strong absolute continuity of the quasi-invariant section.** It turns out that the quasi-invariance of \( \mu \) implies that it is strongly absolutely continuous. We keep working with \( \nu, \mu \) as in previous part; that is,

- \( \nu \) is appropriate for \( f \),
- \( \mu \) is quasi-invariant with Jacobian \( e^{P - \varphi} \) and in the closure of the positive cone generated by \( \{ \nu^n \}_{n \geq 0} \).

Denote for \( x \in M \), \( \mu_x = \mu_{F(x)} \). By quasi-invariance, we get

\[
\forall n \in \mathbb{N}, \quad f^{-n} \mu_{f^n x} = e^{nP - n\varphi} \mu_x. \tag{2.8}
\]

**Lemma 2.9.** Given \( \epsilon > 0 \), there exists \( \delta > 0 \) such that for every \( \psi_1, \psi_2 \in \text{Con}^+ \) that are \( \delta \)-equivalent, then

\[
\left| \frac{\mu(\psi_1)}{\mu(\psi_2)} - 1 \right| < \epsilon.
\]

**Proof.** By Lemma 2.6, for every \( n \in \mathbb{N} \), we have \( \hat{\varphi}^n(\psi_1) \leq \ell(\delta) \cdot e^{D_1 \delta^2} \hat{\varphi}^n(\psi_2) \); the inequality extends to convex combinations of \( \{ \hat{\varphi}^n \} \) and therefore, to elements of \( \mathcal{X} \) (cf. Equation (2.4)). In particular, \( \mu \) satisfies the claim. \( \square \)

We now fix \( x_0, y_0 \) in the same leaf of \( G \) and consider \( \text{hol}^G : A(x_0) \subset F(x_0) \rightarrow B(y_0) \subset F(y_0) \) the corresponding Poincaré map. For \( x \in A(x_0) \), define

\[
\text{Jac}(x) = \prod_{j=0}^{\infty} \frac{e^{\varphi f^j(x)}}{e^{\varphi f^j(x)}} = \lim_n e^{S_n \varphi(\text{hol}^G x) - S_n \varphi(x)}. \tag{2.9}
\]

Since \( \varphi \) is Hölder and \( G \) is contracting, the previous formula defines a continuous function \( \text{Jac} : A(x_0) \rightarrow \mathbb{R} \).

**Proposition 2.9.1.** It holds that \( (\text{hol}^G)^{-1} \mu_{y_0} = \text{Jac} \cdot \mu_{x_0} \).

**Proof.** Denote \( h = \text{hol}^G \), and for \( n \geq 0 \), let \( h_n \) be the Poincaré map defined on a neighborhood of \( f^n x \) inside \( f^n(A(x_0)) \). As \( f \) preserves \( F, G \), \( h = f^{-n} \circ h_n \circ f^n \) and therefore,

\[
h^{-1}_{y_0} \mu_{y_0} = (f^{-n} \circ h^{-1}_n) e^{S_n \varphi f^{-n} - nP} \mu_{f^n y_0} = f^{-n} \left( e^{S_n \varphi_{f^n x_0} - nP} h^{-1}_n \mu_{f^n y_0} \right) \]
\[
= f^{-n} \left( e^{S_n \varphi_{f^n x_0} - nP} (\mu_{f^n x_0} + (h^{-1}_n \mu_{f^n y_0} - \mu_{f^n x_0})) \right) \]
\[
= e^{S_n \varphi_{f^n x_0} - S_n \varphi} \mu_{x_0} + f^{-n} e^{S_n \varphi_{f^n x_0} - nP} (h^{-1}_n \mu_{f^n y_0} - \mu_{f^n x_0}).
\]
By the lemma above, given $\epsilon > 0$, there exists $n_0$ such that for $n \geq n_0$, it holds: for any $\psi \in \text{Con}^+$ supported in $f^n(A(x_0))$, 
\[ |h_n^{-1} \mu f^n y_0(\psi) - \mu f^n x_0(\psi)| < \epsilon h_n^{-1} \mu f^n y_0(\psi), \]
which in turn implies
\[ |f - n e^{S_n \varphi \circ f^{-n} - n P}(h_n^{-1} \mu f^n y_0 - \mu f^n x_0)(\psi \circ f^n)| < \epsilon \mu f^n y_0(\psi \circ h_n^{-1} e^{S_n \varphi \circ f^{-n} - n P}) = \epsilon h_n^{-1} \mu y_0(\psi \circ f^n). \]
Thus, we can write $h_n^{-1} \mu y_0 = J_n \cdot \mu x_0 + u_n$, where $u_n$ converges to zero in the vague topology, and $\{J_n\}_n$ is a sequence of continuous functions that converges uniformly to Jac. This concludes the proof.

**Remark 2.10.** Using that $\mathcal{G}$ is contracting under $f$ and $\varphi$ is Hölder, one verifies directly that $\|\text{Jac} - 1\|_{C^0} \underset{y_0 \to x_0}{\longrightarrow} 0$.

### 3. Invariant measures for center isometries

We will use the previous construction in the case when $f$ is a center isometry. For convenience of the reader, we recall the definition and some basic facts below.

**Definition 3.1.** Let $M$ be a closed manifold. A diffeomorphism $f \in \text{Diff}^r(M), r \geq 1$ is a center isometry if there exists a continuous splitting of the tangent bundle of the form
\[ TM = E^s \oplus E^c \oplus E^u, \]
where both bundles $E^s, E^u$ are nontrivial, a (continuous) Riemannian metric $\|\cdot\|$ on $M$ and a constant $0 < \lambda < 1$ such that

1. All bundles $E^s, E^c, E^u$ are $Df$-invariant.
2. For every $x \in M$, for every unit vector $v^* \in E^s_x, * = s, c, u$,
\[ \|D_x f(v^*)\| = 1 \]
\[ \|D_x f^n(v^s)\|, \|D_x f^{-1}(v^u)\| < \lambda. \]

Center isometries are a subclass of the so called Partially Hyperbolic Systems. From their theory, we need the following.

**Theorem 3.1.** If $f \in \text{Diff}^r(M)$ is a center isometry, then the bundles $E^s, E^u, E^c$, $E^{cs} = E^c \oplus E^s, E^{cu} = E^c \oplus E^u$ are (uniquely) integrable to continuous foliations $\mathcal{W}^s = \{W^s(m)\}_{x \in M}, \mathcal{W}^u = \{W^u(m)\}_{x \in M}, \mathcal{W}^c = \{W^c(m)\}_{x \in M}, \mathcal{W}^{cs} = \{W^{cs}(m)\}_{x \in M}, \mathcal{W}^{cu} = \{W^{cu}(m)\}_{x \in M}$ respectively called the stable, unstable, center, center stable and center unstable foliations, whose leaves are $C^r$ immersed submanifolds. Moreover, leaves of $\mathcal{W}^{cs}$ are saturated by leaves of $\mathcal{W}^s, \mathcal{W}^c$, and leaves of $\mathcal{W}^{cu}$ are saturated by leaves of $\mathcal{W}^u, \mathcal{W}^c$.

**Proof.** Integrability of the bundles $E^s, E^u$ is consequence of the classical Stable Manifold theorem (see, for example, Theorem 4.1 in [36]), while the rest of the assertions can be deduced from Theorem 7.5 in [23].

\[ \square \]
Standing hypotheses for the rest of the section: $f: M \to M$ is center isometry of class $C^2$ and $\varphi: M \to \mathbb{R}$ is a Hölder potential. The metric in $M$ is assumed to make $E^s, E^c, E^u$ mutually perpendicular. Both foliations $W^s, W^u$ are minimal.

We will apply the results of Section 2: take $\mathcal{F} = W^{cu}, \mathcal{G} = W^s$, $\nu = \text{Leb}$, the Lebesgue measure on leaves of $W^{cu}$. By the $C^2$ hypothesis on $f$ and Proposition 2.4.1, $\nu$ is appropriate for $f$, and since $W^s$ is minimal, we are in the setting discussed in Section 2.2. Therefore, the conclusion of Corollary 2.8 is valid. Then, Theorem 2.3 allows us to deduce the existence of an appropriate $\mu^{cu} \in \text{Meas}(W^{cu})$ for $f$, with Jacobian $e^{P-\varphi}$ for some $P \in \mathbb{R}$. Finally by Proposition 2.9.1, $\mu$ is strongly absolutely continuous (therefore appropriate for $f$). We summarize this in the Proposition below.

**Proposition 3.1.1.** There exists a section $\mu^{cu} = \mu^{cu}_\varphi \in \text{Meas}(W^{cu})$ and $P \in \mathbb{R}$ such that:

1. For every $\psi \in \text{Con}^+(W^{cu})$, it holds that $\mu^{cu}(\psi) > 0$.
2. For every $x \in M$, $f^{-1}\mu^{cu}_f = e^{P-\varphi}\mu^{cu}_x$.
3. If $\text{hol}^s = \text{hol}^s_{x_0, y_0}: A(x_0) \subset W^{cu}(x_0) \to B(y_0) \subset W^{cu}(y_0)$ is the Poincaré map determined by the stable holonomy that sends $x_0$ to $y_0$, then
   \[(\text{hol}^s)^{-1}\mu^{cu}_{y_0} = \text{Jac}^{s}_{x_0, y_0} \cdot \mu^{cu}_{x_0},\]
   where
   \[
   \text{Jac}^{s}_{x_0, y_0}(x) = \prod_{j=0}^{\infty} \frac{e^{\varphi f^j(\text{hol}^s(x))}}{e^{\varphi f^j(x)}}. \tag{3.1}
   \]

Note that $f^{-1}$ is also a center isometry whose stable foliation coincides with the unstable of $f$, and likewise its unstable foliation coincides with the stable of $f$. By applying the previous arguments to $f^{-1}$ and the potential $\varphi \circ f^{-1}$, we conclude the following.

**Proposition 3.1.2.** There exist $\mu^{cs} = \mu^{cs}_\varphi \in \text{Meas}(W^{cs})$ and $P' \in \mathbb{R}$ such that:

1. For every $\psi \in \text{Con}^+(W^{cs})$, it holds that $\mu^{cs}(\psi) > 0$.
2. For every $x \in M$, $f^{-1}\mu^{cs}_f = e^{\varphi - P'}\mu^{cs}_x$.
3. If $\text{hol}^u = \text{hol}^u_{x_0, y_0}: A(x_0) \subset W^{cs}(x_0) \to B(y_0) \subset W^{cs}(y_0)$ is the Poincaré map determined by the unstable holonomy that sends $x_0$ to $y_0$, then
   \[(\text{hol}^u)^{-1}\mu^{cs}_{y_0} = \text{Jac}^{u}_{x_0, y_0} \cdot \mu^{cs}_{x_0},\]
   where
   \[
   \text{Jac}^{u}_{x_0, y_0}(x) = \prod_{j=1}^{\infty} \frac{e^{\varphi f^{-j}(\text{hol}^u(x))}}{e^{\varphi f^{-j}(x)}}. \tag{3.2}
   \]

### 3.1. The conditional measures: potentials constant along the center and SRBs

We are interested in constructing $\mu^u \in \text{Meas}(W^u)$ satisfying analogous properties as $\mu^{cu}$. Our previous construction, however, does not apply in this case since the transverse

---

2This can always be achieved by passing to an equivalent metric.
fibration to $W^u$ is not contracting. To bypass this problem, we assume some condition on $\varphi$, namely that it is either

- constant on center leaves (c-constant case), or
- $\varphi = -\log \det Df|E^u$ (SRB case).

In the SRB case, we define

$$\mu^u_x = \text{Lebesgue measure on } W^u(x)$$

by the change of variables theorem $f^{-1}\mu^u_x = \det Df|E^u \cdot \mu^u_x = e^{-\varphi} \mu^u_x$. For the c-constant case, one deduces by compactness of $M$ the existence of some $c_{cen} > 0$ such that for every $x \in M$, there is a well-defined projection $\pi^c_x : W^c(W^u(x), c_{cen}) \to W^u(x)$ by sliding along local center plaques. Given $x$, we define a measure on $W^u(x)$ by setting

$$\mu^u_x = \pi^c_x \cdot \mu^c_x.$$  (3.3)

Note that $\mu^u \in \text{Meas}(W^u)$ is quasi-invariant with Jacobian $e^{P-\varphi}$; indeed, by using that $\varphi$ is constant on center leaves and that $f$ is an isometry on these, we deduce

$$f^{-1}\mu^u_x = f^{-1}\pi^c_x \cdot \mu^c_x = \pi^c_x e^{P-\varphi} \mu^c_x = e^{P-\varphi} \pi^c_x \cdot \mu^c_x.$$  (3.4)

Arguing with $\mu^{cs}$ instead of $\mu^{cu}$, we can analogously construct a family of measures $\mu^s = \{\mu^s_x\}_{x \in M}$ on stable leaves. An important case of c-constant potential is when $\varphi \equiv 0$; in this case, we denote $m^* \in \text{Meas}(F^*)$, $* \in \{s,u,cs,cu\}$ the corresponding sections.

**Definition 3.2.** $m^*$ are the Margulis measures on $F^*$.

It follows that

$$f^{-1}m^{cu}_x = e^h m^{cu}_x$$  (3.5)

and

$$f^{-1}m^u_x = e^h m^u_x$$  (3.6)

for some $h \in \mathbb{R}$.

**Proposition 3.1.3.**

1. $m^{cu}$ ($m^{cs}$) is invariant under hol* holonomy (respectively, holu holonomy).

2. The constant $h$ is positive.

**Proof.** By part 3 of Proposition 3.1.1, it holds that $\text{Jac}_{x_0, y_0}^s = 1$, thus implying the first part.

Recall the construction of $m^{cu}$ on page 13, with $\nu = \text{Leb}$ and $\nu^n = f^{-n}\nu$ and a fixed normalized $\psi_0 \in \text{Con}^+(W^{cu})$.

Thus, we have for every $n \geq 0$,

$$f^{-1}\nu^n(\psi_0) \geq \min\{\det Df|E^{cu}\} \nu^n(\psi_0) \Rightarrow f^{-1}\nu^n(\psi_0) \geq \min\{\det Df|E^{cu}\}. $$

This implies the same inequality for every member of $\mathcal{X}$, and in particular,

$$e^h = m^{cu}(\psi_0 \circ f^{-1}) \geq \min\{\det Df|E^{cu}\} > 1.$$  \(\square\)
Remark 3.2. The reader can perceive that, in principle, $h$ (and $P, P'$) depend on $\psi_0$. We will show in the next section that $h = h_{top}(f)$ and $P = P' = P_{top}(\phi)$.

We return to the general case; we will use the family $\{\mu^u_x\}_x$ to define some new measures $\{\nu^u_x\}_x$ that will serve as conditional measures on local unstable manifolds for the equilibrium state.

For each $x \in M, y \in W^u(x)$, let

$\Delta^u_x(y) := \prod_{k=1}^{\infty} \frac{e^{\varphi \circ f^{-k}(y)}}{e^{\varphi \circ f^{-k}(x)}}, \quad (3.7)$

and note that $\Delta^u_x : W^u(x) \to \mathbb{R}$ is continuous. Define

$\nu^u_x = \Delta^u_x \mu^u_x. \quad (3.8)$

One verifies easily that $\nu^u_x$ is a Radon measure on $W^u(x)$ which is positive on open sets, and furthermore,

$\frac{f^{-1} \nu^u_x}{\nu^u_y} = \Delta^u_y \circ f \cdot f^{-1} \mu^u_x = \Delta^u_y \circ f \cdot e^{P-\varphi} \mu^u_x = e^{P-\varphi} \nu^u_x. \quad (3.9)$

For $y \in W^u(x)$, we have $\nu^u_y = c(y, x) \cdot \nu^u_x$ with $c(y, x) > 0$. Hence, $\{\nu^u_y\}_{y \in W^u(x)}$ defines a projective class of measures $[\nu^u_x]$. In particular, if $\xi$ is a $\mu^u_x$-measurable partition subordinated to $W^u$, we have that the probability measures

$\nu^\xi_x := \nu^u_x(\cdot | \xi(x)) \quad (3.10)$

satisfy $\nu^\xi_x = \nu^\xi_y$ for $y \in \xi(x)$.

Before moving on, we establish the following lemma that will allow us to compare different unstable measures. Let $\epsilon > 0$ be so that any set of diameter less than $2\epsilon$ is contained in a foliation chart of $W^u$ and consider the compact space

$N = \{(x_0, y_0, z) \in M^3 : y_0 \in \text{cl} W^u(x_0, \epsilon/2), z \in \text{cl} W^c(x_0, \epsilon/2)\}.$

For $(x_0, y_0, z) \in N$, define

$T_{x_0, y_0}(z) = \prod_{k=1}^{+\infty} \frac{e^{\varphi \circ f^{-k}(\text{hol}^u_{x_0, y_0}(z))}}{e^{\varphi \circ f^{-k}(z)}}. \quad (3.11)$

Lemma 3.3. It holds that:

1. the constant $c(y, x)$ converges uniformly to 1 as $y \to x$, and
2. $T : N \to \mathbb{R}$ is (uniformly) continuous.

Proof. The first follows directly since $c(y, x) = \Delta^u_y(x)$. For the second, for every $k \geq 0$, consider the continuous function $T_k : N \to \mathbb{R}$ defined as

$T_k(x_0, y_0, z) = \sum_{i=1}^{k} \varphi \circ f^{-i}(\text{hol}^u_{x_0, y_0}(z)) - \varphi \circ f^{-i}(z)$
and note that by the Weierstrass’ test, $T_k$ converges uniformly to
\[ \sum_{k=1}^{+\infty} \varphi \circ f^{-k}(\text{hol}_{x_0,y_0}^u z) - \varphi \circ f^{-k}(z), \]
which implies that $\log T$ is continuous. Thus, $T$ is continuous.

### 3.2. The equilibrium state

It is seldom the case that for a given invariant measure $\mu$ for $f$, the partition by unstable manifolds is $\mu$-measurable. Therefore, we will have to work in sets $B$ where $W^u|B$ defines a sufficiently nice partition. Since we are trying to use the family $\{\mu_{x}^{cs}\}_{x \in M}$ as a substitute for the transverse measure of the equilibrium state, we will have to deal with the technical difficulty of having to show coherence between different choices $B,B'$; this will be bypassed using our control on the behavior of $\{\mu_{x}^{cs}\}_{x \in M}$ under unstable (local) holonomies. We will now make some geometrical preparations to deal with this problem.

**Dynamical boxes.** To take advantage of the local product structure between $W^c$ and $W^u$, we introduce some new notation. Due to the fact that the invariant bundles are mutually perpendicular, there exists $c_{\text{ips}}>0$ such that for any $0<\epsilon \leq c_{\text{ips}}$ it holds that for every $x,y \in M, d(x,y) < \epsilon$ implies
\[
\#W^s(x,2\epsilon) \cap W^{cu}(y,2\epsilon) = 1 \tag{3.12}
\]
\[
\#W^u(x,2\epsilon) \cap W^{cs}(y,2\epsilon) = 1. \tag{3.13}
\]

**Definition 3.3.** For $0<\epsilon \leq c_{\text{ips}}$ and $x \in M$, we consider the sets
\[
P^{cs}(x,\epsilon) := W^c(W^s(x,\epsilon),\epsilon) \tag{3.14}
\]
\[
P^{cu}(x,\epsilon) := W^c(W^u(x,\epsilon),\epsilon) \tag{3.15}
\]
\[
B(x,\epsilon) := \bigcup_{y \in W^c(x,\epsilon)} \text{hol}_{x,y}^u(P^{cs}(x,\epsilon)) \tag{3.16}
\]
where $\text{hol}_{x,y}^u: W^{cs}(x) \to W^{cs}(y)$ is the locally defined Poincaré map sending $x$ to $y$.

Sets $B(x,\epsilon)$ constructed in this fashion will be referred to as *dynamical boxes*, while $\text{hol}_{x,y}^u(P^{cs}(x,\epsilon))$ will be referred to as the *cs*-plaques of $B(x,\epsilon)$.

Shrinking $c_{\text{ips}}$, if necessary, can guarantee also that for $0<\epsilon \leq c_{\text{ips}}$, for every $x,x' \in M$,
\begin{itemize}
  \item $P^{cu}(x,\epsilon) \cap P^{cu}(x',\epsilon) \neq \emptyset \Rightarrow P^{cu}(x,\epsilon) \cap P^{cu}(x',\epsilon) \subset P^{cu}(x'',3\epsilon)$ for some $x'' \in M$.
  \item $B(x,\epsilon) \cap B(x',\epsilon) \neq \emptyset \Rightarrow B(x,\epsilon) \cap B(x',\epsilon) \subset B(x'',5\epsilon)$ for some $x'' \in M$.
\end{itemize}

To understand better the structure of dynamical boxes, we note the following.

**Lemma 3.4.** Fix $x \in M$ and for $y \in W^s(y)$, consider the locally defined holonomy $\text{hol}_x^s: W^{cu}(x) \to W^{cu}(y)$. Then, $\text{hol}_x^s$ sends center leaves into center leaves and $\text{hol}_x^s|W^c(x)$ is an isometry (similar for unstable holonomies).
Figure 1. Comparison between $P^{cu}(x,\epsilon)$, $P^{cu}(y,\epsilon)$ for $y \in W^s(x)$. The stable holonomy sends each center plaque $W^c(x',\epsilon) \in P^{cu}(x,\epsilon)$ to a center plaque $W^c(y',\epsilon) \in P^{cu}(y,\epsilon)$, but the image of unstable plaques in $P^{cu}(x,\epsilon)$ are only Hölder submanifolds in $P^{cu}(y,\epsilon)$. Nevertheless, $\text{hol}^s_{x,y}(W^u(x,\epsilon)) \to W^u(x,\epsilon)$ in the $C^0$ topology as $y \to x$.

**Proof.** Let $\delta > 0$ be sufficiently small so that $\text{hol}^s_{x,y}: A = W^{cu}(x,\delta) \to B \subset W^{cu}(y)$ is a well-defined homeomorphism. Since $f$ preserves $W^{cu}, W^c, W^s$, it follows that

$$\text{hol}^s_{x,y} = f^{-n} \circ \text{hol}^s_{f^n x, f^n y} \circ f^n \quad \forall n \geq 0$$

where $\text{hol}^s_{f^n x, f^n y}: f^n(A) \to f^n(B) \subset W^c(f^n y)$. Using that $f|W^c$ is an isometry and $f|W^u$ expands distances, it follows that $\text{hol}^s$ sends $W^c(x,\delta)$ to $W^c(y)$ and that the differentiable map $\text{hol}^s_{f^n x, f^n y}|W^c(f^n x)$ uniformly approaches the identity for large $n$, hence the claim.

We remark that, in general, $\text{hol}^s$ does not send $W^u$ to itself. See Figure 1.

**Corollary 3.5.** For every $0 < \epsilon \leq c_{ips}$ and $x \in M$, it holds that

$$B(x,\epsilon) = \bigcup_{y \in W^s(x,\epsilon)} \text{hol}^s_{y,x}(P^{cu}(x,\epsilon)),$$

where $\text{hol}^s_{x,y}: W^{cu}(x) \to W^{cu}(y)$ is the locally defined Poincaré map sending $x$ to $y$.

**Proof.** This is a direct consequence of Lemma 3.4 above, plus the fact that $W^c$ subfoliates $W^{cu}, W^{cs}$.

In view of this Corollary, sets $\text{hol}^s_{x,y}(P^{cu}(x,\epsilon))$ will be referred to as the $cu$-plaques of $B(x,\epsilon)$. Another consequence is the following.
**Corollary 3.6.** For every $0 < \epsilon \leq c_{ps}$ and $x \in M$, $B(x, \epsilon) \subset M$ is open.

**Proof.** Fix $x \in M, \epsilon > 0$ and define $b : W^c(x, \epsilon) \times W^s(x, \epsilon) \to W^c(x)$ by

$$b(y, z) = W^s(y, 2\epsilon) \cap W^c(z, 2\epsilon).$$

This map is continuous, injective and by Lemma 3.4, $\mathcal{H}(b) = P^c(x, \epsilon)$. The invariance of domain theorem now implies that $P^c(x, \epsilon)$ is an open subset of $W^c(x)$.

Analogously, define $\tilde{b} : P^c(x, \epsilon) \times W^u(x, \epsilon) \to M$,

$$\tilde{b}(y, z) = \text{hol}_{x, z}^u (y);$$

$\tilde{b}$ is continuous, injective and, by definition, $B(x, \epsilon) = \mathcal{H}(\tilde{b})$. Another application of the invariance of domain theorem implies that $B(x, \epsilon)$ is open.

**The equilibrium state.** We now construct the equilibrium state. Fix $B = B(x, 0, \epsilon)$ a dynamical box with $0 < \epsilon < c_{ps}/2$. By the choice of $\epsilon$, the set $W^u(x, B) = W^u(x, 2\epsilon) \cap B$ consists of a unique unstable plaque. Similar considerations hold for the other foliations.

If $W$ is a $cs$-plaque of $B$ and $x \in B$, denote $x_w = W^u(x, B) \cap W$. For $U \subset B$ open sub-box, define the function $\alpha^U_{W, B} : W \to \mathbb{R}$ by

$$\alpha^U_{W, B}(w) = \nu^u_w(U \cap W^u(w, B)).$$

(3.17)

**Lemma 3.7.** $\alpha^U_{W, B}$ is upper semi-continuous, and hence, measurable.

**Proof.** The SRB case is direct, so we will consider only when $\varphi$ is constant along center leaves.

We use the following notation: for $\gamma > 0$ and $C$ contained in a $cu$-plaque $Z \subset B$, we write

$$\text{Col}_\gamma(C) := \{ y \in Z : \exists y' \in C \text{ s.t. } d_{W^c}(y, y') < \gamma \}.$$ 

Consider a sequence $(y_m)_m \subset W$, $y_m \underset{m \to \infty}{\longrightarrow} y$. Let

$$A = W^u(y, B) \cap U,$$

$$A_m = W^u(y_m, B) \cap U.$$ 

By definition of $\mu^u_y$ (3.3), $\mu^u_y(A) = \mu^c_y(W^c(A, c_{cen}))$, and since $\mu^c_y$ is a Radon measure,

$$\mu^u_y(A) = \inf_{\gamma > 0} \mu^c_y(\text{Col}_\gamma(W^c(A, c_{cen}))).$$ 

Similar considerations apply to $\mu^u_{y_m}(A_m)$ and to the measures $\nu^u_y, \nu^u_{y_m}$; in particular, if

$$A_\gamma = \text{Col}_\gamma(W^c(A, c_{cen}) \cap W^u(y)),$$

then $A_\gamma$ is an open neighborhood of $A$ inside $W^u(y)$, and

$$\nu^u_y(A) = \inf_{\gamma > 0} \int_{W^c(A, c_{cen})} \Delta^u_y \circ \pi^c_y d\mu^c_y.$$
Fix $0 < \gamma < \epsilon_{ps} - \epsilon_{cen}$. By Lemma 3.3, the function $y' \mapsto \Delta_{y_w}(y')$ is positive and uniformly continuous on $B$. Hence, given $\tau > 0$, there exists $0 < \rho < \tau$ such that $y' \in B$, $d(y, y') < \rho \Rightarrow |\Delta_{y_w}(y)\Delta_{y_w}(y') - 1| < \tau$. Due to continuity of the unstable and center unstable foliations, there exists $0 < \rho' < \rho$ so that if $y' \in B, d(y, y') < \rho'$, then

- the local stable holonomy between $W^{cu}(y', c_{cen} + \gamma)$ and $W^{cu}(y)$ is well-defined, with $\text{Jac}^s_{y,y'}(z) < 1 + \tau$, for every $z \in \text{hol}^s_{y,y'}(W^{cu}(y, c_{cen} + \gamma))$ (cf. Remark 2.10).
- $W^c(W^u(y', B) \cap U, c_{cen})$ is $\rho$-equivalent to some subset $E_{y'} \subset \text{Col}_\gamma(W^c(A, c_{cen}))$.

Using continuity of the product of functions, we can further assume

- $|\Delta^u_{y} \circ \pi^c_y \circ \text{hol}^s_{y,y'}(z) - \Delta^u_{y} \circ \pi^c_y(z)| < \tau$ for every $z \in E_{y'}$.

Take $m_0$ so that $m \geq m_0$ implies $d(y_m, y) < \rho'$ and write $E_m = E_{y_m}$,

$$g_m := \text{hol}^s_{y_m,y} : E_m \to W^c(A_m, c_{cen}).$$

Then,

$$\nu^u_{y_m}(A_m) = \int_{W^c(A_m, c_{cen})} \Delta^u_{y_m} \circ \pi^c_{y_m} \, d\mu^c_{y_m} = \int_{g_m(E_m)} \Delta^u_{y_m} \circ \pi^c_{y_m} \, d\mu^c_{y_m}$$

$$= \int_{E_m} \Delta^u_{y_m} \circ \pi^c_{y_m} \circ g_m \cdot \text{Jac}^s_{y,y_m} \, d\mu^c_y \leq (1 + \tau) \int_{E_m} \Delta^u_{y_m} \circ \pi^c_{y_m} \circ g_m \, d\mu^c_y$$

$$< (1 + \tau) \left( \int_{E_m} \Delta^u_{y} \circ \pi^c_y \, d\mu^c_y + \tau \cdot \mu^c_y(E_m) \right)$$

$$\leq (1 + \tau) \left( \int_{W^c(A_{\gamma}, c_{cen})} \Delta^u_{y} \circ \pi^c_y \, d\mu^c_y + \tau \cdot \mu^c_y(\text{Col}_\gamma(W^c(A, c_{cen})) \right).$$

Hence,

$$\limsup_m \alpha^U_{W, B}(y_m) = \limsup_m \nu^u_{y_m}(A_m)$$

$$\leq (1 + \tau) \left( \int_{W^c(A_{\gamma}, c_{cen})} \Delta^u_{y} \circ \pi^c_y \, d\mu^c_y + \tau \cdot \mu^c_y(\text{Col}_\gamma(W^c(A, c_{cen})) \right).$$

Taking limit as $\tau \to 0$, we obtain

$$\limsup_m \alpha^U_{W, B}(y_m) \leq \int_{W^c(A_{\gamma}, c_{cen})} \Delta^u_{y} \circ \pi^c_y \, d\mu^c_y$$

which in turn implies

$$\limsup_m \alpha^U_{W, B}(y_m) \leq \inf_{\gamma > 0} \int_{W^c(A_{\gamma}, c_{cen})} \Delta^u_{y} \circ \pi^c_y \, d\mu^c_y = \alpha^U_{W, B}(y),$$

as we wanted to show. \(\square\)
Standard arguments of measure theory, together with the previous Lemma, permit us to define a Borel measure $m^{W,B}$ on $B$ by the condition

$$U \subset B \text{ open sub-box } \Rightarrow m^{W,B}(U) := \int \alpha^{U}_{W,B}(w) \mu^{cs}_{w_0}(dw),$$

where $w_0 \in W$.

Let $W'$ be another cs-plaque of $W^{cs}|B$ and consider $\text{hol}^{u}_{w_0,w_0'} : W \to W'$ the corresponding Poincaré map. Fix $U \subset B$ open, and to simplify the notation, write $U^{u}_{w} := U \cap W^{u}(w,B)$. We compute

$$m^{W',B}(U) = \int_{W'} \nu_{w}^{u}(U^{u}_{w}) \mu^{cs}_{w_0}(dw') = \int_{W} \nu_{\text{hol}^{u}_{w_0,w_0'}(w)}^{u}(U^{u}_{\text{hol}^{u}_{w_0,w_0'}(w)}) \text{Jac}^{u}_{w_0,w_0'}(w) \mu^{cs}_{w_0}(dw)$$

$$= \int_{W} \left( \nu_{\text{hol}^{u}_{w_0,w_0'}(w)}^{u}(U^{u}_{w}) \prod_{k=1}^{+\infty} \frac{e^{\varphi k \text{hol}^{u}_{w_0,w_0'}(w)}}{e^{\varphi k (w)}} \right) \mu^{cs}_{w_0}(dw)$$

$$= \int_{W} \nu_{w}^{u}(U_{w}) \mu^{cs}_{w_0}(dw) = m^{W,B}(U).$$

Hence, $m^{W',B} = m^{W,B}$; we write $m^B = m^{W,B}$ for any plaque $W \in W^{cs}|B$. The following is now clear.

**Lemma 3.8.** Consider $0 < \epsilon < \epsilon' < \frac{c_{\text{cov}}}{2}$ and $x,x' \in M$ such that $B = B(x,\epsilon) \subset B(x',\epsilon')$. Then, $m^B = m^{B'}|B$.

Take a finite covering $\mathcal{B} = \{B_{1} = B(x_{1},c_{\text{cov}}),\ldots,B_{R} = B(x_{R},c_{\text{cov}})\}$ of $M$ with $0 < c_{\text{cov}} < \frac{c_{\text{cov}}}{2}$ and define the measure $m$ by the condition: $A \subset B_{i}$ is Borel $\Rightarrow m(A) := m^{B_{i}}(A)$. If $A \subset B_{i} \cap B_{j}$, then by our choice of $c_{\text{cov}}$, there exists $x \in M$ with $A \subset B(x,\epsilon_0)$. Thus, by the previous lemma, $m^{B_{i}}(A) = m^{B_{j}}(A)$. Hence, $m$ is a well-defined Borel measure on $M$. With no loss of generality, we assume further that for every $i$, there exists $x'_{i}$ such that $f(B_{i}) \subset B(x'_{i},c_{\text{ips}})$.

**Proposition 3.8.1.** The measure $m$ is $f$-invariant.

**Proof.** Fix $m^{B_{i}} = m^{W_{i},B_{i}}$, let $B' = B(x'_{i},c_{\text{ips}})$ so that $f(B_{i}) \subset B(x'_{i},c_{\text{ips}})$ and denote $W'$ the cs-plaque of $B'$ containing $f(W_{i})$. Consider also $U \subset f(B_{i})$ as an open sub-box of $B'$. Then, $f^{-1}U \subset B_{i}$ is an open sub-box, and for $w \in B_{i}$, $(f^{-1}U)^{u}_{w} = f^{-1}(U^{u}_{f_{w}})$. Therefore,

$$fm^{W_{i},B_{i}}(U) = m^{W_{i},B_{i}}(f^{-1}U) = \int_{W_{i}} \nu_{w}^{u}(f^{-1}U^{u}_{f_{w}}) \mu^{cs}_{w_0}(dw).$$

The quasi-invariance of $\nu_{w}^{u}(f^{-1}U^{u}_{f_{w}})$, formula (3.9) permits us to write

$$\nu_{w}^{u}(f^{-1}(U^{u}_{f_{w}})) = e^{\varphi(w)-P} \nu_{f_{w}}^{u}(U^{u}_{f_{w}}).$$

Thus,

$$fm^{W_{i},B_{i}}(U) = \int_{W_{i}} e^{\varphi(w)-P} \nu_{f_{w}}^{u}(U^{u}_{f_{w}}) \mu^{cs}_{w_0}(dw) = e^{-P} \int_{W_{i}} e^{\alpha^{W',U}(f_{w})\varphi(w)} \mu^{cs}_{w_0}(dw).$$
which by 2. of Proposition 3.1.2, can be written as
\[ e^{P' - P} \int f W' U (z) \mu_{f w_0}^{cs} (dz) = e^{P' - P} \int W' \alpha W' U (z) \mu_{f w_0}^{cs} (dz) = e^{P' - P} m^{W', B'} (U), \]
where in the last equality we have used that \( U \subset f (B_i) \). Since \( U \) is an arbitrary open sub-box, we have proven that \( f m^{W_i, B_i} = e^{P' - P} m^{W', B'} \). This implies \( f m = e^{P' - P} m \). The measure \( m \) is finite on compact sets and \( f M = M \). Thus, \( P = P' \) and \( m \) is \( f \)-invariant. □

**Corollary 3.9.** It holds that \( P = P' \).

**Definition 3.4.** We denote \( m_\varphi \) the probability measure \( \frac{m}{m (M)} \).

**Remark 3.10.** Assuming that existence of \( \{ \mu_s^x \}_{x \in M} \) satisfying \( f^{-1} \mu^x_s = e^{P' - P} \mu^x_s \) (for example, in the \( c \)-constant case), we can argue similarly and construct another invariant measure \( \tilde{m}_\varphi \) which is given locally as
\[ \tilde{m}_\varphi (U) = \int _V \nu_v^s (U_v) \mu_{z_0}^{cu} (dv), \]
where \( V \) is a \( cu \)-plaque of some dynamical box containing \( U, z_0 \in V \).

**Convention:** The family \( \mathcal{B} = \{ B_1, \ldots B_R \} \), together with corresponding center stable plaques \( W_1, \ldots W_R \), is considered to be fixed.

Directly from the construction, we get:

**Corollary 3.11.** If \( \xi \) is a \( m_\varphi \)-measurable partition subordinated to \( W^u \), then for \( m_\varphi \)-almost every \( x \), it holds that
\[ (m_\varphi)_x^\xi = \frac{\nu_v^u (| \xi (x) |)}{\nu_x^u (\xi (x))}. \]
Assuming the existence of \( \tilde{m}_\varphi \), similarly we get that if \( \xi \) is a \( \tilde{m}_\varphi \)-measurable partition subordinated to \( W^s \), then for \( \tilde{m}_\varphi \)-almost every \( x \), it holds that
\[ (\tilde{m}_\varphi)_x^\xi = \frac{\nu_v^s (| \xi (x) |)}{\nu_x^s (\xi (x))}. \]

**Remark 3.12.** We will prove later that \( m_\varphi = \tilde{m}_\varphi \), provided that these exist.

### 3.3. Product structure and the Gibb’s property

We start establishing the following.

**Proposition 3.12.1** (Product structure of \( m_\varphi \)). There exists \( 0 < c_{psm} \leq c_{cov} \) such that for every \( 0 < \epsilon \leq c_{psm} \), there exists \( c (\epsilon) > 0 \) satisfying for every \( x \in M \),
\[ \frac{1}{c} \leq \frac{m_\varphi (B (x, \epsilon))}{\mu_x^u (W^u (x, B (x, \epsilon))) \cdot \mu_x^s (P^{cs} (x, \epsilon))} \leq c. \]

The proof follows directly by the definition of \( m_\varphi \) with the following lemma.
Lemma 3.13. There exists $0 < c_{psm} \leq c_{cov}$ such that for $0 < \epsilon \leq c_{psm}$, we can find $c(\epsilon) > 0$ such that for all $x,x' \in M$, the following holds.

\[
(\ast) \quad c(\epsilon)^{-1} \leq \frac{\mu_x^{cu}(W^{cu}(x,\epsilon))}{\mu_x^{cu}(W^{cu}(x',\epsilon))} \leq \frac{\mu^{cs}_x(W^{cs}(x,\epsilon))}{\mu^{cs}_x(W^{cs}(x',\epsilon))} \leq c(\epsilon)
\]

\[
(\ast\ast) \quad c(\epsilon)^{-1} \leq \frac{\mu_x^{u}(W^{u}(x,\epsilon))}{\mu_x^{u}(W^{u}(x',\epsilon))} \leq c(\epsilon)
\]

\[
(\ast\ast\ast) \quad c(\epsilon)^{-1} \leq \frac{\nu_x^{u}(W^{u}(x,\epsilon))}{\nu_x^{u}(W^{u}(x',\epsilon))} \leq c(\epsilon)
\]

Proof. Let $c_{psm}$ be the Lebesgue number associated to the covering $\mathcal{B}$. We start with $(\ast)$; it suffices to consider the first set of inequalities. Since $\mu_x^{cu}$ is a Radon measure of full support, we have the following: for $\epsilon > 0$ fixed, there exists $\gamma > 0$ and $c_0(x,\epsilon) > 0$ such that

\[
x' \in W^{cu}(x,\gamma) \Rightarrow c_0(\epsilon,x)^{-1} \leq \frac{\mu_x^{cu}(W^{cu}(x,\epsilon))}{\mu_x^{cu}(W^{cu}(x',\epsilon))} \leq c_0(\epsilon,x).
\]

By Lemma 3.3, it is no loss of generality to assume that the same holds for $x' \in D(x,\gamma)$, and hence, due to the compactness of $M$, we get a uniform $c(\epsilon)$ independent of $x$.

For $(\ast\ast)$, the claim is immediate for the SRB case, so we just need to consider when $\varphi$ is constant along centrals, but this follows from as in the previous part since $\mu_x^{u}(A) = \mu_x^{cu}(W^{c}(A,c_{cov}))$.

Finally, $(\ast\ast\ast)$ is consequence of $(\ast\ast)$, together with Lemma 3.3. \hfill \Box

Remark 3.14. Arguing similarly and redefining $c, c_{psm}$ if necessary, we can guarantee that for every $x \in M$,

\[
\frac{1}{c(\epsilon)} \leq \frac{\tilde{m}_{\varphi}(B(x,\epsilon))}{\mu_x^{s}(W^{s}(x,B(x,\epsilon)))} \cdot \frac{\mu_x^{cu}(P^{cu}(x,\epsilon))}{\mu_x^{cu}(W^{cu}(x,\epsilon))} \leq c(\epsilon).
\]

Next, we establish a Gibbs’s type property for $m_{\varphi}$ (resp. $\tilde{m}_{\varphi}$) that will allow us to show that it is an equilibrium state for the potential $\varphi$. By reducing $c_{psm}$ if necessary, we can assume that for every $0 < \epsilon < c_{psm}$, for every $\epsilon$-ball $D \subset M$, the distance between $x,y \in D$ is given by

\[
d(x,y) = \inf\{\text{length}(\alpha) : \alpha : [0,1] \to D \text{ piecewise } C^1, \alpha(0) = x, \alpha(1) = y, \alpha' \in E^* = s,c,u\}.
\]

With this metric and using that $f$ is a center isometry, we have

\[
D^{u}(x,\epsilon,n) = D(x,\epsilon,n)|W^{u}(x) = f^{-n}W^{u}(f^{n}x,\epsilon)
\]

\[
D(x,\epsilon,n) = \bigcup_{y \in W^{cs}(x,\epsilon)} D^{u}(y,\epsilon,n).
\]

(3.18)

We note the following classical remark.

Lemma 3.15. Given $\epsilon > 0$, there exists $K(\epsilon) > 0$ with the property that for every $x,y \in M, n \geq 0$, it holds that
1. \( y \in D^u(x, \epsilon, n) \Rightarrow |S_n \varphi(x) - S_n \varphi(y)| < K. \)

2. \( y \in D(x, \epsilon, n) \Rightarrow |S_n \varphi(x) - S_n \varphi(y)| < nK. \) If \( \varphi \) is constant on central leaves, then
\( y \in D(x, \epsilon, n) \Rightarrow |S_n \varphi(x) - S_n \varphi(y)| < K. \)

Moreover, \( K(\epsilon) \to 0 \) as \( \epsilon \to 0. \)

**Proof.** We will prove only the second part, as the arguments for the first are included in the proof of this case. Let \( y_n := W^s(y, \epsilon) \cap f^{-n}W^{cu}(f^n x, \epsilon). \) Points in the same stable leaf are exponentially contracted and \( \varphi \) is Hölder. Thus,
\[
|S_n \varphi(x) - S_n \varphi(y)| \leq |S_n \varphi(x) - S_n \varphi(y_n)| + C_1(\epsilon)
\]
for some constant \( C_1(\epsilon) \) that converges to zero as \( \epsilon \) tends to zero. Since \( f^n y_n \in W^{cu}(f^n x, \epsilon), \) the point \( z_n := W^u(f^n y, \epsilon) \cap W^c(f^n x, \epsilon) \) is well-defined. Observe then that the distance \( d(f^{-j} z_n, f^{-n} y_n) \) is exponentially contracted under \( f^{-1}, \) and thus, for some other similar constant \( C_2(\epsilon), \) we have
\[
|S_n \varphi(x) - S_n \varphi(y)| \leq |S_n \varphi(x) - S_n \varphi(f^{-n} z_n)| + C_2(\epsilon).
\]

Since \( f \) is a center isometry and \( \varphi \) is Hölder, it follows that
\[
|S_n \varphi(x) - S_n \varphi(f^{-n} z_n)| = 0 \quad \text{c-constant case}.
\]

\[
|S_n \varphi(x) - S_n \varphi(f^{-n} z_n)| \leq C_\varphi n \epsilon^0 := C_3(\epsilon) \quad \text{in general.}
\]

Defining \( K(\epsilon) := C_1(\epsilon) + C_2(\epsilon) + C_3(\epsilon), \) we finish the proof. \( \square \)

Therefore, in general, the Birkhoff’s sums for points in the same \((\epsilon, n)\)-Bowen ball differ by a factor that grows linearly with \( n. \) This is not that convenient; to circumvent this, the authors in [14] work with a type of potential that satisfies for sufficiently small \( \epsilon, \)
\[
\exists Q_\varphi > 0 : \forall x, y \in M, y \in W^{cs}(x, \epsilon), \forall n \in \mathbb{N} \Rightarrow |S_n \varphi(x) - S_n \varphi(y)| < Q_\varphi.
\]

They call this the \textbf{cs-Bowen property for} \( \varphi, \) and they prove that the geometric potential satisfies this condition. In fact, inspection of their arguments shows that the following holds.

**Lemma 3.16.** If \( \mu^u \) is strongly absolutely continuous\(^3\), then \( \varphi \) satisfies the cs-Bowen property.

In particular, the geometrical potential satisfies the cs-Bowen property.

**Proof.** The proof is similar to the proof of Theorem 5.2 of the above cited article. For convenience of the reader, we rephrase these arguments in our setting.

Since \( \mu^u \) is strongly absolutely continuous, given \( \tau > 0, \) there exists \( \rho > 0 \) so that for every \( x, y \in M, \) it holds that if \( A \subset W^u(x), B \subset W^u(y) \) are \( \rho \)-equivalent, then \( h|\mu^u_x|\mu^u_y|B = J(x, y, \cdot) \mu^u_y|A, \) and \( |J(x, y, z) - 1| < \tau \) for every \( z \in A. \) Take \( \epsilon > 0 \) sufficiently small so that \( y \in W^{cs}(x, \rho/2) \) implies that \( W^u(y, \epsilon) \) is \( \rho \)-equivalent to some subset of \( W^u(x). \) Recalling that \( D^u(y, \epsilon, n) = f^{-n}W^u(f^n y, \epsilon) \) and since \( f \) is a center isometry, it follows that if \( y \in W^{cs}(x, \rho/2), \) then for every \( n \geq 0, D^u(y, \epsilon, n) \) is \( \rho \)-equivalent to some subset of \( J(x, \epsilon, n) \subset W^u(x, \rho/2) \).
The last claim follows from Lemmas 3.15 and 3.16. \qed
We are ready to show that $m_\varphi$ is an equilibrium state.

**Proposition 3.18.1.** It holds that $P = P_{\text{top}}(\varphi) = P_{\mu_\varphi}(\varphi)$.

**Proof.** Fix $0 < \epsilon < c_{psm}$ small. By the previous Corollary, and since $m_\varphi$ is invariant, one has

$$\frac{\log d(\epsilon)}{n} - K(\epsilon) \leq P - (\int \log m_\varphi(D(x,\epsilon,n)) \, dm_\varphi + \int \varphi \, dm_\varphi) \leq \frac{\log d(\epsilon)}{n} + K(\epsilon)$$

which, by the Brin-Katok formula \cite{BrinKatok}, gives

$$- K(\epsilon) \leq P - (h_{m_\varphi}(f; A) + \int \varphi \, dm_\varphi) \leq K(\epsilon) \Rightarrow P_{m_\varphi}(\varphi) = P.$$ 

Next, we consider a maximally $(n,2\epsilon)$-separated set $E_n$: then, for $\{D(x,\epsilon,n)\}_{x \in E_n}$ are pairwise disjoint and $M = \bigcup_{x \in E_n} D(x,2\epsilon,n)$. Take $A^n = \{A^n_x : x \in E_n\}$ partition by Borel sets so that for every $x \in E_n$, $D(x,\epsilon,n) \subset A^n_x \subset D(x,2\epsilon,n)$, and compute\footnote{Recall the definition of $S(\epsilon,2)$ on page 2.}

$$S(2\epsilon,n) \leq \sum_{x \in E_n} e^{S_n \varphi(x)} \leq \sum_{x \in E_n} m_\varphi(D(x,\epsilon,n)) e^{nP + nK(\epsilon)} \leq e^{nP + nK(\epsilon)} \sum_{x \in E_n} m_\varphi(A^n_x).$$

It follows that $P_{\text{top}}(\varphi) \leq P$, and therefore, by the variational principle, that $P = P_{\text{top}}(\varphi) = P_{m_\varphi}(f)$. \hfill \qed

**Remark 3.19.** The Gibbs property given in Corollary 3.18 is presented in more generality than needed. Still, since the theory is still under development, there is perhaps some value in presenting the property in this form. In particular, it shows that the presence of the linear term $nK(\epsilon)$ instead of $K(\epsilon)$ is enough to establish Proposition 3.18.1.

Since $P = 0$ by construction in the SRB case, we get:

**Corollary 3.20.** If $m_{SRB}$ is the measure associated to $\varphi = - \log \det Df|E^u$, then $P_{m_{SRB}}(f) = 0$.

### 4. A characterization of equilibrium states

The aim of this section is to characterize equilibrium states in terms of their conditional measures along strong unstable leaves, similar to the case of SRB measures, where they are characterized by the property of their conditionals being absolutely continuous with respect to Lebesgue measures along unstables. We will rely on the seminal work of Ledrappier-Young \cite{LedrappierYoung}.

**Hypotheses of this section:** $f : M \to M$ is a $C^2$ center isometry, $\varphi : M \to \mathbb{R}$ is a Hölder potential, and there is a family of measures $\mu^u$ satisfying 2,3 of Theorem A for $\varphi$.

Of course, the existence of such families is guaranteed only on some cases (for example, when $\varphi$ is either constant along centrals or $\varphi = - \log |\det Df|E^u|$), but since the arguments
that we will present only depend on this existence, there is value in writing this part abstractly.

Let \( m \in \mathcal{P} \) and \( \nu^* \in \text{Meas}(\mathcal{F}^*) \), \(* = s,u\). We say that \( m \) has conditionals equivalent to \( \nu^* \) along \( \mathcal{F}^* \) if for every \( m \)-measurable partition \( \xi \) subordinated to the (possibly non-measurable partition) \( \mathcal{F}^* \), it holds that \( m\xi \sim \nu^* \) for \( \mu\text{-a.e.}(x) \). See [45] for a discussion of measurable partitions and conditional measures.

Define
\[
\mathcal{P}(M,\mu^u) = \{ m \in \mathcal{P}(M) : m \text{ has conditionals equivalent to } \mu^u \} \tag{4.1}
\]
\[
\mathcal{P}_f(M,\mu^u) = \mathcal{P}(M,\mu^u) \cap \mathcal{P}_f(M). \tag{4.2}
\]

We will prove the following.

**Theorem 4.1.** The set \( \mathcal{P}_f(M,\mu^u) \) coincides with the set of equilibrium states for \( \varphi \).

**Remark 4.2.** Implicit in the statement of the above theorem is the existence of at least one equilibrium state for \((f,\varphi)\). For center isometries, this is automatic: \( f \) is what is called \( h \)-expansive. Thus, by [33], the function \( m \in \mathcal{P}_f(M) \to h_m(f) \) is upper semi-continuous and therefore has a maximum. Note, however, that this abstract method does not give any information about the equilibrium state besides its existence.

**Increasing partitions**

A \( m \)-measurable partition \( \xi \) is called increasing if it refines its image \((f\xi < \xi)\). If \( \xi \) is a partition, recall that we denote by \( \mathcal{B}_\xi(M) \) the sub-\( \sigma \) algebra of \( \mathcal{B}_M \) that consists of \( \xi \)-saturated sets. The mesh of \( \xi \) is the supremum of \( \{ \text{diam}(A) : A \in \xi \} \).

**Definition 4.1.** We call a measurable partition \( \xi \) a SLY partition if it is increasing, subordinated to \( \mathcal{W}^u \) and furthermore, for \( m\text{-a.e.}(x) \in M \), the atom \( \xi(x) \) contains a neighborhood of \( x \) inside \( \mathcal{W}^u(x) \).

In our restricted setting, a SLY partition automatically satisfies the following additional properties:

1. \( \bigvee_{n \geq 0} f^{-n} \xi = \mathcal{B}_M \).
2. \( \bigwedge_{n \geq 0} f^n \xi = \mathcal{B}^u \)

where \( \mathcal{B}^u \) is the \( \sigma \)-algebra of \( \mathcal{W}^u \) saturated sets. A key result is the following.

**Theorem 4.3.** There exist SLY partitions of arbitrarily small mesh. If \( \xi \) is a SLY partition, then
\[
h_m(f) = h_m(f,\xi) = h_m(f^{-1}\xi|\xi).
\]

The existence part is essentially due to Sinai [47] (compare Section 3 in [28] and Lemma 2.4.2 in [29], where the construction is done in more generality). The second part is a deep result of Ledrappier and Young (Corollary 5.3 in [29]). We remark that although in this last article the result is presented for ergodic measures, it extends easily to non-ergodic ones by using the ergodic decomposition. We have tacitly used that the strong unstable
manifolds coincide with the Pesin’s unstable manifolds, as consequence of the fact that
\( f \) does not have any positive Lyapunov exponents along center directions, independently
of the measure.

### 4.1. Equilibrium states have conditionals equivalent to \( \mu^u \)

Now, we fix \( \xi \) a SLY partition for the measure \( m \) and denote by \( m_x = m^\xi_x \) the conditional
measure of \( m \) on \( \xi(x) \). The main result of [29] admits the following generalization in our
setting.

**Theorem 4.4.** If \( m \) is any equilibrium state corresponding to \( (f, \varphi) \), then
\( m_x \sim \mu^u_x \) on \( \xi(x) \) for \( m\text{-a.e.}(x) \).

To give a self-contained presentation, we include the complete proof instead of just
citing the relevant parts of Ledrappier-Young’s work. Assume for the moment that the
conclusion of the theorem was true. Then, for \( m\text{-a.e.}(x) \), we have
\[
dm_x = \rho_x \, d\mu^u_x,
\]
where \( \rho_x \) is a non-negative function such that \( \int \rho_x \, d\mu^u_x = 1 \). Using that the partition \( \xi \) is measurable, we can assemble all \( \{\rho_x\} \) into one measurable function \( \rho : M \to \mathbb{R} \). Since \( m \in \mathcal{P}r_f(M) \), we have
\[
f m_x^{-1} \xi = m_x f^{-1} \xi = m^\xi_x \quad \text{m-a.e.} (x).
\]
However, \( f^{-1} \xi > \xi \). Thus, for any \( A \in \mathcal{B}_M \), we can write
\[
\frac{1}{m_x(f^{-1} \xi(x))} \int_{A \cap f^{-1} \xi(x)} \rho_x \, d\mu^u_x = \frac{1}{m_x(f^{-1} \xi(x))} m_x(A \cap f^{-1} \xi(x)) = m_x f^{-1} \xi(A)
\]
\[
= m_x(f A \cap \xi(f x)) = \int_{f(A \cap f^{-1} \xi(x))} \rho_x \, d\mu^u_x = \int_{A \cap f^{-1} \xi(x)} \rho \circ f e^{P-\varphi} \, d\mu^u_x.
\]
Hence, by uniqueness of the conditional measures \( m\text{-a.e.}(x) \), it holds that
\[
\frac{\rho(y)}{m_x(f^{-1} \xi(x))} = \rho(f y) \cdot e^{P-\varphi(y)} \quad \text{for } \mu_x\text{-a.e.}(y) \in f^{-1} \xi(x).
\]
As the denominator appearing in the previous equation is \( f^{-1} \xi \)- measurable, we finally
conclude that the function
\[
x \mapsto \frac{\rho(x)}{\rho(f^{-1} x)} e^{P-\varphi(f^{-1} x)}
\]
is \( \xi \) - measurable (i.e. constant on the atoms of \( \xi \)). By a simple inductive argument, one
is led to conclude that \( \rho \) satisfies
\[
y \in \xi(x) \Rightarrow \frac{\rho(y)}{\rho(x)} = \prod_{k=1}^{\infty} e^{\varphi \circ f^{-k} (y)} = \Delta^u_x(y). \quad (4.3)
\]

**Lemma 4.5.** For every \( x \in M \), the function \( W^u(x) \ni y \mapsto \log \Delta^u_x(y) \) is locally Lipschitz
and therefore uniformly bounded away from 0 and \( \infty \) on the atom \( \xi(x) \).
The proof is straightforward using that for every \( x \in M \), the set \( W^u(x) \) is an immersed submanifold and the fact that \( \varphi \) is globally Hölder.

From (4.3), we deduce that \( \rho \) should have the form

\[
\rho(y) = \frac{\Delta^u_x(y)}{L(x)}, \quad y \in \xi(x)
\]

with \( L(x) = \int_{\xi(x)} \Delta^u_x(y) d\mu^u_x(y) \).

We now define a measure \( \tilde{m} \) by requiring \( \tilde{m} = m \) on \( B_\xi \) and such its conditionals on \( \xi \) are given by \( d \tilde{m} = \Delta^u_x L(x) d \mu_x = \rho d \mu_x \) (cf. (3.10)). The proof of Theorem 4.4 will be achieved by establishing that \( m = \tilde{m} \), and for this, it suffices to show that \( m = \tilde{m} \) on every \( B_{f^{-n} \xi}, n \geq 0 \), since the previous \( \sigma \) - algebras generate \( \mathcal{B}_M \).

We start by noticing the following: for \( q(x) = \tilde{m}_x(f^{-1} \xi(x)) \), we have

\[
q(x) = \frac{1}{L(x)} \int_{f^{-1} \xi(f(x))} \Delta_x(f^{-1} f y) \frac{e^{P-\varphi(y)}}{e^{P-\varphi(f^{-1} f y)}} d\mu^u_x = \frac{1}{L(x)} \int_{\xi(f(x))} J^u_x(f^{-1} z) e^{\varphi(f^{-1} z)-P} d\mu^u_x(z) = \frac{L(f x)}{L(x)} e^{\varphi(x)-P} \leq 1.
\]

Thus, \( \frac{L(f x)}{L(x)} \leq e^{P-\varphi(x)} \Rightarrow \log \frac{L(f x)}{L(x)} \leq P - \varphi(x) \), and therefore, \( \max \{ \log \frac{L(f x)}{L(x)} \} \) is in \( L^1(m) \). A classic lemma of measure theory (cf. Proposition 2.2 in [28]) then implies

\[
\int \log \frac{L(f x)}{L(x)} dm = 0 \Rightarrow \int -\log q(x) dm(x) = P - \int \varphi dm.
\]

We have shown the following.

**Lemma 4.6.** It holds that

\[
P - \int \varphi dm = \int -\log \tilde{m}_x(f^{-1} \xi(x)) dm(x) = \int -\log \left( \int_{f^{-1} \xi(x)} \rho(y) d\mu^u_x(y) \right) dm(x).
\]

By definition, the measures \( m \) and \( \tilde{m} \) coincide on \( B_\eta \); to prove that these two measures coincide, it suffices to establish that \( m \) and \( \tilde{m} \) coincide on \( B_{f^{-1} \xi} \) provided that \( m \) is an equilibrium state, and argue by induction.

Denote by \( g_{f^{-1} \xi} = \frac{dm}{\tilde{m}_x} \big|_{B_{f^{-1} \xi}} \), and observe that since the partition \( f^{-1} \xi \) restricted to each atom \( \xi(x) \) is countable, we have for \( m \)-a.e.\( (x) \)

\[
g_{f^{-1} \xi}(x) = \frac{\tilde{m}_x(f^{-1} \xi(x))}{m_x(f^{-1} \xi(x))}.
\]

To prove that \( m = \tilde{m} \) on \( B_{f^{-1} \xi} \), we will show that \( g_{f^{-1} \xi}(x) \equiv 1 \) for \( m \)-a.e.\( (x) \). Observe that for \( m \)-a.e.\( (x) \), one has \( m_x(f^{-1} \xi(x)) > 0 \). Hence, the function \( g_{f^{-1} \xi}(x) \) is well-defined for \( m \)-a.e.\( (x) \), but not necessarily for \( \tilde{m} \)-a.e.\( (x) \). This point is not emphasized in [29], and some minor extra considerations are required to complete the argument\(^5\). For the sake of exactness, we will be precise in what follows.

\(^5\)This was remarked some time ago by the second author in some private notes.
For an atom $\xi(x)$, we write $f^{-1}\xi|\xi(x) = \{A_j^x\}_{j=1}^\infty$. We compute
\[
\int_{\xi(x)} g_{f^{-1}\xi}(y) \, dm(x)(y) = \int_{\xi(x)} \frac{\hat{m}_y(f^{-1}\xi(y))}{\hat{m}_x(f^{-1}\xi(y))} \, dm_x(y) = \int_{\xi(x)} \frac{\hat{m}_x(f^{-1}\xi(y))}{\hat{m}_x(f^{-1}\xi(y))} \, dm_x(y)
\]
\[
= \sum_{j=1}^\infty \int_{A_j^x} \frac{\hat{m}_x(A_j^x)}{\hat{m}_x(A_j^x)} \, dm_x(y) = \sum_{j=1}^\infty \hat{m}_x(A_j^x) \leq \sum_{j=1}^\infty \hat{m}_x(A_j^x) = \hat{m}_x(x) = 1 \tag{4.5}
\]
\[
\Rightarrow \int g_{f^{-1}\xi}(x) \, dm(x) \leq 1. \tag{4.6}
\]

Now, we use our hypothesis that $m$ is an equilibrium state: by Theorem 4.3 and Lemma 4.6,
\[
\int -\log \hat{m}_x(f^{-1}\xi(x)) \, dm(x) = H_m(f^{-1}\xi|\xi) = P - \int \varphi \, dm = \int -\log \hat{m}_x(f^{-1}\xi(x)) \, dm(x)
\]
and thus, $\iint g_{f^{-1}\xi}(x) \, dm(x) = 0$. Using Jensen’s inequality and (4.6), we conclude
\[
0 = \int \log g_{f^{-1}\xi}(x) \, dm(x) \leq \log \int g_{f^{-1}\xi}(x) \, dm(x) \leq \log 1 = 0.
\]

Strict convexity of the logarithm function then implies
\[
g_{f^{-1}\xi}(x) = 1 \quad \text{m-a.e.}
\]

We conclude that the chain of inequalities appearing are equalities, and in particular, for equation (4.5). As a result, we have $\mu_x(A_j^x) > 0 \Rightarrow \hat{m}_x(A_j^x) > 0$, and this in turn implies that m-a.e.(x). It holds that $m_x = \hat{m}_x$ on $f^{-1}\xi|\xi(x)$ since these measures coincide on all the atoms and not only on the ones of $m_x$ positive measure. Consequently, $m = \hat{m}$ on $B_{f^{-1}\xi}$, and this finishes the general inductive step necessary to prove Theorem 4.4.

**Corollary 4.7.** Suppose that $m \in \mathcal{P}_{r_f}(M)$ is an equilibrium state for the potential $\varphi$ and $\xi$ is a SLY partition as above. Then, for m-a.e.(x), the conditional measures of $m$ with respect to $\xi$ are given by
\[
\hat{m}_x^\xi = \hat{m}_x = \frac{\Delta_x^u}{L(x)} \mu_x^u |\xi(x) \quad L(x) = \int_{\xi(x)} \Delta_x^u \, d\mu_x^u.
\]

In particular, the disintegration can be extended to every leaf of $\mathcal{W}^u$ and $m \in \mathcal{P}_{r_f}(M, \mu^u)$.

We remark that above we only used the existence of an equilibrium state with conditionals satisfying the quasi-invariance condition 3 of Theorem A.

### 4.2. Conditional measures determine equilibrium states

We are interested now in the following converse of Theorem 4.4.

**Theorem 4.8.** Let $m \in \mathcal{P}_{r_f}(M)$ and assume that with respect to some SLY partition $\xi$, we have that $m_x << \mu_x^u$ for m-a.e.(x). Then, m is an equilibrium state.
Equilibrium states for center isometries

Proof. The proof uses similar techniques to the ones used above and is based in [28]. Consider $\xi$ a SLY partition for $m$ and define the measure $\hat{m}$ on $M$ by requiring that for $A \subset M$ Borel,

$$\hat{m}(A) = \int \mu^u_x(A \cap \xi(x)) \, dm(x). \tag{4.7}$$

Observe that $\hat{m}$ is not necessarily finite, but only $\sigma$-finite. By hypothesis, $dm_x = \rho \, d\mu_x$. Thus, $m << \hat{m}$, and moreover, $m$-a.e. ($x$). It holds that

$$\frac{dm}{d\hat{m}} = \rho \, m$-a.e. ($x$) \tag{4.8}$$

(see Proposition 4.1 in [28]). Note that

$$m_x(f^{-1}\xi(x)) = \frac{\rho \circ f(x)}{\rho(x)} \, \phi(x) - P.$$

Finally, we compute

$$0 \leq h_m(f) = H(f^{-1}\xi | \xi) = \int -\log m_x(f^{-1}\xi(x)) \, dm(x)$$

$$= P - \int \varphi \, dm + \int -\log \frac{\rho \circ f(x)}{\rho(x)} \, dm(x)$$

and since $\varphi$ is integrable (bounded), the function $-\log \frac{\rho \circ f}{\rho}$ is integrable as well. Using again Proposition 2.2 of [28], we conclude that $\log \frac{\rho \circ f}{\rho}$ has zero integral. Hence,

$$h_m(f) = P - \int \varphi \, dm$$

and $m$ is an equilibrium state. The proof is complete. 

Joining Theorems 4.4 and 4.8, we get Theorem 4.1. Below we list some of its consequences.

Corollary 4.9. Assume also the existence of a family $\mu^s$ satisfying 2.3 of Theorem A for $\varphi$. If $m$ is an equilibrium state, then $m$ has conditionals equivalent to $\mu^s, \mu^u$.

Proof. The set of equilibrium states for $f$ coincides with the one for $f^{-1}$. 

Remark 4.10. The corollary above does not require uniqueness of the equilibrium state.

Since the measures $\mu^u_x$ are positive on relative open sets, Proposition 4.1 in [26] implies:

Corollary 4.11. For every equilibrium state $m$ for $\varphi$, it holds that $h_m(f) > 0$.

Finally, we note that the previous theorem gives another proof of the fact that $m_\varphi$ is an equilibrium state (and $P$ is the topological pressure), as the conditionals of $m_\varphi$ are absolutely continuous with respect to $\mu^u$; see Corollary 3.11.
5. Kolmogorov and Bernoulli properties

The aim of this section is to establish the Bernoulli property for equilibrium states. Again, our arguments are written in some more generality than the context in which we have been working, and in particular, most of them do not require uniqueness of the equilibrium state (at least under very mild additional hypotheses), using that \( m_\varphi = \tilde{m}_\varphi \) instead.

For the remaining part of this section, \( f : M \to M \) is a center isometry of class \( C^2 \), \( \varphi \) is a H"older potential, and \( m_\varphi = \tilde{m}_\varphi \) are the equilibrium states of the system \((f,\varphi)\) constructed in Section 3.

5.1. Kolmogorov processes

We will prove first that \((f,m_\varphi)\) has the Kolmogorov property, and in particular, it is mixing of all orders. For this, we give two proofs. The first, which works without any extra assumptions, consists of verifying that our system satisfies the hypotheses of an abstract theorem due to Ledrappier [27]. This argument does require uniqueness of the equilibrium state for the considered potentials, which is known from [14].

The second proof is more geometrical and is based on the methods originally developed by Grayson, Pugh and Shub for establishing the stable ergodicity of the time-one map of the geodesic flow on manifolds of constant sectional curvature [19]. In this reasoning, we use \( m_\varphi = \tilde{m}_\varphi \) and ergodicity instead of uniqueness of the equilibrium state, but we require an extra technical assumption, namely the so called accessibility property, which is a common hypothesis for these types of arguments. Nonetheless, we think that there is value in giving this more geometrical proof, with the hope that it could be applied to equilibrium states of other systems, particularly because the first method seems ad hoc to our setting.

**Completely positive entropy.** Let \( T : M \to M \) be a homeomorphism of the compact metric space \( M \), fix \( m \in \mathcal{P}r_T(M) \) and denote \( \text{Pin}(T,m) \) the Pinsker \( \sigma \)-algebra of the system, i.e. the \( \sigma \)-algebra generated by \[
\{ \xi \text{ countable measurable partition of } M : H_m(\xi) < \infty, h_m(T;\xi) = 0 \}.
\]

We use the following characterization of Kolmogorov systems, although the reader may want to take it as the definition of the Kolmogorov property.

**Theorem 5.1** (Rohlin-Sinai). The system \((T,m)\) has the Kolmogorov property if and only if \( \text{Pin}(T,m) = \{ \emptyset, M \} \mod 0 \).

To conclude that \((f,m_\varphi)\) is a Kolmogorov system, we use the results of [27]. We give some definitions in order of making our presentation self-contained.

**Definition 5.1.** We say that a map \( T : M \to M \) of a compact metric space is weakly expansive\(^6\) if for every compact metric space \( N \) and continuous map \( S : N \to N \), the map
\[
\mathcal{P}r_{T \times S}(M \times N) \ni m \to h_m(T \times S) - h_{\pi_N m}(S) \in \mathbb{R}
\]
is upper semi-continuous.

\(^{6}\)The terminology “weakly expansive” has several meanings in the literature. In this work, we are only concerned with the one given in this page.
Equilibrium states for center isometries

If $T : M \rightarrow M$ is $h$-expansive, then it is weakly expansive; see page 266 in [27] and [33]. It follows that if $f$ is a center isometry, then it is weakly expansive.

**Theorem 5.2** (Ledrappier). Suppose that $T : M \rightarrow M$ is weakly expansive and $\varphi : M \rightarrow \mathbb{R}$ is continuous. Let $R : M \times M \rightarrow M \times M$ be the product map of $T$ with itself and denote $\Phi : M \times M \rightarrow \mathbb{R}$ the function $\Phi(x,y) = \varphi(x) + \varphi(y)$. If $(R, \Phi)$ has a unique equilibrium state, then $(T, \varphi)$ has a unique equilibrium state $m$, and $(T, m)$ is Kolmogorov.

We apply the above theorem to $T = f$; note that $R = (f, f) : M \times M \rightarrow M \times M$ is a center isometry of class $C^2$ with invariant decomposition

$$E_R^\sigma \approx E_f^\sigma \oplus E_f^\sigma \subset TM \oplus TM \approx T(M \times M), \quad \sigma \in \{s, c, u, cs, cu\}.$$ 

Moreover, by unique integrability of the stable, center and unstable foliations in center isometries (cf. the references given in the proof of Theorem 3.1), it follows that for every $(x, y) \in M \times M$,

$$W_R^\sigma(x, y) = W_f^\sigma(x) \times W_f^\sigma(y).$$

We deduce that $\mathcal{F}_R^s, \mathcal{F}_R^u$ are minimal. Next, we consider $\varphi : M \rightarrow \mathbb{R}$ a Hölder potential and $\Phi = (\varphi, \varphi)$. Then, $\Phi$ is clearly Hölder with respect to the distance $d((x, y), (x', y')) = \max\{d(x, y), d(x', y')\}$ on $M \times M$. Observe:

1. If $\varphi$ is constant along center leaves of $f$, then $\Phi$ is constant along center leaves of $R$.
2. If $\varphi = -\log |\det Df| E^u|$, then

$$\Phi = -\log |\det Df| E^u| - \log |\det Df| E^s| = -\log |DR| E^u_R|.$$

In both cases, the system $(R, \Phi)$ satisfies the hypotheses of Theorem A and therefore has a unique equilibrium state. Hence, by Theorem 5.2, $(f, m_\varphi)$ is Kolmogorov.

**Remark 5.3.** In the recent paper [12], the authors use a similar approach to show the $K$-property of equilibrium states associated to Hölder potentials, where the underlying dynamics are given by the geodesic flow of a (closed) rank-one manifold.

**Juliennes and Equilibrium States.** Now, we give a second, more geometrical, proof of the fact that $(f, m_\varphi)$ is Kolmogorov. We will rely heavily on the technology developed in [41] and its subsequent refinements. As a guide, we use the general lines of Section 4 in [22]. In this part, we work in the conditions described at the beginning of the section, but we do not require uniqueness of the equilibrium state, nor its ergodicity, and only that $m_\varphi = \tilde{m}_\varphi$ (or even more generally, it is enough to assume that these measures are equivalent to each other, with uniformly bounded Radon-Nikodym derivatives).

We say that a subset $X \subset M$ is $s$-saturated ($u$-saturated) if it consists of whole stable (respectively, unstable) leaves. If it is both $s$- and $u$-saturated, we say that it is bi-saturated. Given a point $x \in M$, its accessibility class $ACC(x)$ is the smallest bi-saturated set containing $x$. Analogously, we say that $X \subset M$ is $m$-essentially $s$-saturated ($u$-saturated) if there exists a $s$-saturated ($u$-saturated) Borel set $X_0$ so that $m(X \Delta X_0) = 0$. By [29], we have:
Theorem 5.4 (Ledrappier-Young). Let \( f : M \to M \) be a \( C^2 \) partially hyperbolic diffeomorphism preserving a Borel measure \( m \). Assume that \( f \) is a center isometry (or more generally, that all Lyapunov exponents corresponding to vectors in the center direction are zero). If \( X \in \Pi_{\phi}(f, m) \), then \( X \) is both \( m \)-essentially \( s \)-saturated and \( m \)-essentially \( u \)-saturated.

What we will show is that if \( X \in \mathcal{B}_M \) is \( m \phi \)-essentially \( s \)-saturated, then it coincides almost everywhere with a \( s \)-saturated set \( \mathcal{D}(X; f^{scu}) \). After that, we will establish that if \( X \) is both \( m \phi \)-essentially \( s \)-saturated and \( m \phi \)-essentially \( u \)-saturated, there is equality \( \mathcal{D}(X; f^{scu}) = \mathcal{D}(X; f^{ucs}) \). Hence, under these hypotheses, \( X \) coincides with a bi-saturated set. If we knew that any bi-saturated set is either empty or the whole manifold, then we would be able to deduce, by the previous theorem, that \( \Pi_{\phi}(f, m) \) is trivial, and therefore, the system \((f, m_{\phi})\) is Kolmogorov. Lack of nontrivial bi-saturated sets is a common hypothesis in the theory.

Definition 5.2. The map \( f \) is accessible (or has the accessibility property) if there exists \( x \) so that ACC\((x) = M \).

The script of this proof was developed by Pugh and Shub as part of their program to establish stable ergodicity of (conservative) partially hyperbolic systems. In our case, however, we do not have as much control for the equilibrium measure as one has for volume; therefore, additional work is required. As a remark for the reader versed in Pugh-Shub’s program, we point out that \( m \phi \)-essential accessibility\(^7\) seems inadequate for our purposes since in principle, we do not know the equilibrium measure. We do not know whether in the context of Theorem A the system \((f, m_{\phi})\) is always \( m_{\phi} \)-essentially accessible or not.

For now, we do not assume accessibility, but we do assume that \( m \) is positive on open sets.

Definition 5.3. We say that the family \( \mathcal{E} = \{ \{ E_n(x) \} \}_{n \in \mathbb{N}} \) is a regular Vitali\(^8\) basis if for every \( x \in M \), the family \( \{ E_n(x) \} \) is a local basis of neighborhoods at \( x \) such that

1. each \( E_n(x) \) is a Borel set.
2. \( \lim_{n \to \infty} \text{diam}(E_n(x)) = 0 \).

The regular basis is said to be closed if each \( E_n(x) \) is closed set, and it is decreasing if \( E_n(x) \supset E_{n+1}(x) \), for all \( x \in M, n \in \mathbb{N} \).

Definition 5.4. Let \( \mathcal{E} \) be a regular Vitali basis and \( X \in \mathcal{B}_M \). We say that \( x \in M \) is a \( \mathcal{E} \)-density point of \( X \) if

\[
\lim_{n \to \infty} \frac{m(X \cap E_n(x))}{m(E_n(x))} = 1.
\]

We denote by \( \mathcal{D}(X; \mathcal{E}) \) the set of \( \mathcal{E} \)-density points of \( X \).

---

\(^7\)The map \( f \) is \( m \)-essentially accessible if any bi-saturated set has measure zero or one.

\(^8\)More general definitions of Vitali bases (not regular) are available in the literature (cf. [41]). The definition presented here is enough for our purposes.
In particular, density points for the basis \( \{ D(x, \frac{1}{2^n}) \}_n \) will be called \( B-L \) density points\(^9\). It is standard that for any Borel set \( X \), \( m \)-almost every point of \( X \) is a \( B-L \) density point of \( X \). In the case when \( m \) is a volume, the concept of \( m \)-essential accessibility is a natural assumption because there is a well-defined reference class of measures, and by the discussion above, one can prove the Kolmogorov property establishing that for any \( X \subset M \) which is both \( m \)-essentially \( s \) and \( u \)-saturated, the set of its \( B-L \) density points is bi-saturated. This is the approach followed in [22].

However, for \( \varphi \)-equilibrium measures, we do not have as much control on the properties as one has for volumes, and in particular, we do not know how to control \( B-L \) density points. Instead, we will work with density points corresponding to some dynamical defined Vitali bases called \textit{juliennes}, and show first that under our hypotheses,

1. any \( X \in \mathcal{B}_M \) coincides \( m \)-almost everywhere with the set of its julienne density points.
2. If \( X \) is \( m \)-essentially \( s \)-saturated, then the set of its julienne density points is \( s \)-saturated.

\textbf{Convention:} From now on, we specialize in the case \( m = \tilde{m}_\varphi \).

For some simplifications in the notation we choose to work with \( \tilde{m}_\varphi \), that is, with the construction of an equilibrium measure using \( cu \)-transversals explained in Remark 3.10. As we previously noted, the properties of \( \tilde{m}_\varphi \) are completely analogous to the ones of \( m_\varphi \), and we will refer directly to them without further clarification. Until Proposition 5.14.1, we will not use the equality \( m_\varphi = \tilde{m}_\varphi \).

Some finer control in the local holonomies is now required, specifically that they are Hölder continuous. See Theorem A of [42].

\textbf{Theorem 5.5} (Pugh-Shub-Wilkinson). \textit{There exists} \( C_H > 0, \theta \in (0,1) \) \textit{such that for every} \( x, y, z \in M \) \textit{with} \( y \in W^s(x, \frac{c_{cu}x}{2}), z \in W^u(x, \frac{c_{cu}x}{2}) \), the \textit{locally defined holonomy maps} \( \text{hol}_{y,x}^u : W^c(x) \to W^c(y), \text{hol}_{z,x}^s : W^c(x) \to W^c(y) \) \textit{are} \( (C_H, \theta) \)-Hölder.

Choose numbers \( 0 < \varepsilon < \frac{c_{cu}x}{2}, 0 < \sigma < 1 \) such that \( d(x, y) < \varepsilon \Rightarrow B(y, \varepsilon) \subset B(x, \frac{c_{cu}x}{2}), \lambda^\theta < \sigma \) and define the \( u,s,c,cu,cs,ucs,scu \)-juliennes as

\[
J_n^u(x) := f^{-n}(W^u(f^n x, \varepsilon)) \\
J_n^s(x) := f^n(W^s(f^{-n} x, \varepsilon)) \\
B_n^c(x) := W^c(x; \sigma^n \varepsilon) \\
J_n^{cu}(x) := \bigcup_{y \in B_n(x)} J_n^u(y) \\
J_n^{cs}(x) := \bigcup_{y \in B_n(x)} J_n^s(y)
\]

\(^9B-L \) stands for Besicovitch-Lebesgue.
\[ J_{n}^{ucs}(x) := \bigcup_{y \in J_{n}^{cs}(x)} J_{n}^{u}(y) \]
\[ J_{n}^{scu}(x) := \bigcup_{y \in J_{n}^{cs}(x)} J_{n}^{s}(y). \]

**Remark 5.6.** The definition of juliennes for general partially hyperbolic maps is more involved since no a priori knowledge of the action of \( f \) on the center direction is assumed. In our case, the fact that \( f \) is a center isometry simplifies all the definitions.

By Corollary 3.18, we obtain:

**Lemma 5.7.** There exist constants \( c_1(\varepsilon), c_2(\varepsilon) > 0 \) such that for every \( x \in M \), it holds that
\[ c_1 \leq \frac{\nu_{n}(J_{n}^{s}(x))}{e^{S_{n}\varphi \circ f^{-n}(x)} - n P} \leq c_2. \]

From now on, we omit the reference of the constants with respect to \( \varepsilon \), which is considered to be fixed and small with respect to \( \frac{\nu_{c}}{2} \). We then have the following.

**Corollary 5.8.** There exist \( L_1, L_2 > 0 \) such that for every \( x \in M \), for every \( n \geq 0 \), it holds that \( y, z \in J_{n}^{cu}(x) \) implies
\[ L_1 \leq \frac{\nu_{n}(J_{n}^{s}(y))}{\nu_{n}(J_{n}^{s}(z))} \leq L_2. \]

**Proof.** Arguing as in the proof of Lemma 3.15, we deduce the existence of some \( K' > 0 \) such that for every \( x \in M \) and \( n \geq 0 \),
\[ y, z \in J_{n}^{cu}(x) \Rightarrow |S_{n}\varphi \circ f^{-n}y - S_{n}\varphi \circ f^{-n}z| < K'; \]
this relies on the fact that the central size of \( J^{cu} \) is exponentially small. The claimed property follows now from the previous lemma. \( \square \)

Using the above and the product structure of \( m \) (Proposition 3.12.1), we deduce the following.

**Corollary 5.9.** There exist \( L_3(\varepsilon), L_4(\varepsilon) > 0 \) such that for every \( x \in M \), for every \( n \geq 0 \), it holds that
\[ L_3 \leq \frac{m(J_{n}^{scu}(x))}{\mu_{x}(J_{n}^{s}(x)) \cdot \mu_{x}^{cu}(J_{n}^{cu}(x))} \leq L_4. \]

The key property of juliennes is that they behave in a controlled manner under holonomies.

**Proposition 5.9.1.** There exist \( k \geq 1, n_0 \in \mathbb{N} \) satisfying: for every \( x, x' \in M, x' \in W^{s}(x, \varepsilon), n \geq n_0 \), the corresponding stable holonomy \( \text{hol}^{s} : W^{cu}(x, c_{ip}) \rightarrow W^{cu}(x', c_{ip}) \) satisfies
\[ J_{n+k}^{cu}(x') \subset \text{hol}^{s}(J_{n}^{cu}(x)) \subset J_{n-k}^{cu}(x'). \]
This is completely analogous to Proposition B.8 of [22]. As our juliennes differ from the ones used in that work, we present the proof.

**Proof.** Take \( z \in B_n^c(x), y \in J_{n+k}^u(z) \): then, \( d(z,x) \leq \sigma^n \varepsilon \) and \( d(f^n y, f^n z) < \varepsilon \). Therefore, \( d(y, z) < \lambda^n \varepsilon \) (recall that \( \max_{x \in M} \{ \| D_x f | E^u_x \|, \| D_x f^{-1} | E^u_x \| \} < \lambda < 1 \)). If \( z' = \text{hol}^u(z), y' = \text{hol}^u(y) \), then for \( n \) sufficiently large \( d(x, z), d(x, y) < \varepsilon \).

\[
\begin{align*}
& a) \quad d(z', z) < 2 \varepsilon, d(y', y) < 2 \varepsilon, \text{ because } d(x, x') < \varepsilon, \\
& b) \quad d(f^n y', f^n z') \leq d(f^n y', f^n y) + d(f^n y, f^n z) + d(f^n z, f^n z') \leq \\
& \quad \lambda^n (d(y,y') + d(z,z')) + d(f^n y, f^n z) \leq \lambda^n (2 \varepsilon) + \varepsilon < 2 \varepsilon.
\end{align*}
\]

Define \( w' \) so that \( f^n w' = W^n(f^n y', 4 \varepsilon) \cap W^c(f^n z', 4 \varepsilon) \): it follows that \( w' = W^n(y', c_{t_p}) \cap W^c(z', c_{t_p}) = W^n(y', c_{t_p}) \cap W^c(x', c_{t_p}) \).

The above implies at once that there exists \( k \geq 1 \) independent of \( x \) such that if \( n-k \geq n_0 \), \( y' \in J_{n-k}^u(w') \). However, since \( d(y, z) < \lambda^n \varepsilon \), by Theorem 5.5, we get

\[
d(z', y') \leq C_H \varepsilon^\theta \lambda^{n_0} \Rightarrow d(z', w') \leq 2C_H \varepsilon^\theta \lambda^{n_0}.
\]

Using Lemma 3.4, we get

\[
d(x', w') \leq d(x, z) + d(z', w') < \sigma^n \varepsilon + 2C_H \varepsilon^\theta \lambda^{n_0} = \sigma^{-k}(\sigma^k(1 + 2C_H \varepsilon^\theta)) \varepsilon.
\]

Thus, if \( k \) is sufficiently large, \( d(x', w') < \sigma^{-k} \varepsilon \), and \( w' \in B_{n-k}(x') \). This shows that \( y' = \text{hol}^u(y) \in J_{n-k}^u(x') \) and finishes the proof of the second inclusion. The first one is obtained similarly by using \((\text{hol}^u)^{-1}\).

Now we can establish a central proposition.

**Proposition 5.9.2.** If \( X \) is m-essentially s-saturated, then the set of its \( \mathcal{J}^{scu} \)-density points is s-saturated.

For the proof, we will employ the following Lemma.

**Lemma 5.10.** Let \( X_s \) be an s-saturated set and \( x \in M \). Then,

\[
\lim_{n \to \infty} \frac{m(X_s \cap J_{n}^{scu}(x))}{m(J_{n}^{scu}(x))} = 1 \Leftrightarrow \lim_{n \to \infty} \frac{\mu_x^{cu}(X_s \cap J_{n}^{cu}(x))}{\mu_x^{cu}(J_{n}^{cu}(x))} = 1.
\]

The proof is not too hard and is a direct consequence of Corollary 5.9. We omit the proof and refer the reader to Proposition 2.7 of [9], where a completely analogous statement is proven.

**Proof.** Consider \( X_s \) an s-saturated set such that \( m(X \Delta X_s) = 0 \). Let \( x \) be a \( \mathcal{J}^{scu} \)-density point of \( X \) and let \( \text{hol}^u \) be a (local) stable holonomy sending \( x \) to \( y \). Using the previous proposition, we deduce

\[
\mu_y^{cu}(\text{hol}^u(J_{n+k}^{cu}(x) \cap X_s)) \leq \mu_y^{cu}(J_{n}^{scu}(y) \cap X_s) \leq \mu_y^{cu}(\text{hol}^u(J_{n-k}^{cu}(x) \cap X_s)),
\]

Equilibrium states for center isometries 1337
and since at this scale \((\text{hol})^{-1}\mu_{\mathcal{cu}}^y\) is uniformly comparable to \(\mu_{\mathcal{cu}}^x\), we have

\[
1 = \lim_{n \to \infty} \frac{m(X \cap J_n^{scu}(x))}{m(J_n^{scu}(x))} = \lim_{n \to \infty} \frac{\mu_{\mathcal{cu}}^y(X \cap J_n^{cu}(x))}{\mu_{\mathcal{cu}}^y(J_n^{cu}(x))} = \lim_{n \to \infty} \frac{\mu_{\mathcal{cu}}^y(\text{hol}^s(X \cap J_n^{cu}(x)))}{\mu_{\mathcal{cu}}^y(\text{hol}^s(J_n^{cu}(x)))}
\]

\[
= \lim_{n \to \infty} \frac{\mu_{\mathcal{cu}}^x(X \cap J_n^{cu}(y))}{\mu_{\mathcal{cu}}^x(J_n^{cu}(y))} = \lim_{n \to \infty} \frac{m(X \cap J_n^{scu}(y))}{m(J_n^{scu}(y))},
\]

i.e. \(y\) is also a point of \(\mathcal{f}^{scu}\)-density of \(X\).

We will show now that any measurable \(X\) coincides m-almost everywhere with \(\mathcal{D}(X; \mathcal{f}^{scu})\).

**Definition 5.5.** Let \(m \in \mathcal{P}_r(M)\) be positive on open sets and nonatomic. A regular Vitali basis \(\mathcal{E}\) is m-engulfing if there exists \(L > 0\) with the following property: for every \(x \in M, n \in \mathbb{N}\) there exists a closed set \(\hat{E}_n(x)\) such that

1. \(E_n(x) \subset \hat{E}_n(x)\) and \(m(\hat{E}_n(x)) \leq L \cdot m(E_n(x))\).
2. If \(n' \geq n, y \in M\) and \(E_{n'}(y) \cap E_n(x) \neq \emptyset\) then \(E_{n'}(y) \subset \hat{E}_n(x)\).
3. Given \(N_0\) there exists \(\delta > 0\) such that \(m(\text{cl} E_n(x)) < \delta\) implies \(n \geq N_0\).

**Theorem 5.11.** If \(\mathcal{E}\) is a closed m-engulfing basis, then for every \(X \in \mathcal{B}_M\) the set of its \(\mathcal{E}\)-density points coincide almost everywhere with \(X\).

**Proof.** This is proven in [41], Theorem 3.1. See also the discussion after Corollary 3.2 in that article.

Note the following.

**Lemma 5.12.** There exist \(n_l, l \in \mathbb{N}\) so that for every \(x \in M, n - l \geq n_l\) implies

\[
J_n^{scu}(y) \cap J_n^{scu}(x) \neq \emptyset \Rightarrow \text{cl} J_n^{scu}(y) \subset J_{n-l}^{cu}(x).
\]

**Proof.** Observe that \(J_n^{scu}(y) \cap J_n^{scu}(x) \neq \emptyset\) implies \(J_n^{scu}(y) \subset D(x, 2\varepsilon(2\lambda^n + \sigma^n))\); we consider \(n \geq n_0\) so that \(2\varepsilon(2\lambda^n + \sigma^n) < \frac{\delta}{4}\). Using Proposition 5.9.1, one readily deduces the existence of \(n_1 \geq n_0\) and \(k\) satisfying, for \(n - k \geq n_1\),

\[
\text{hol}^s(J_n^{cu}(y)) \subset J_{n-k}^{cu}(x);
\]

observe that the distance \(d(\text{hol}^s(w), w)\) for \(w \in J_n^{cu}(y)\) is smaller than \(4\varepsilon(2\lambda^n + \sigma^n)\). From here follows the claim.

The lemma above implies, in particular, that the density points of the bases \(\mathcal{f}^{scu}\) and \(\text{cl} \mathcal{f}^{scu} = \{\text{cl} J_n^{cu}(x) : x \in M\}\) coincide. Since the latter is a closed basis, we will be able to apply Theorem 5.11 and deduce that for any measurable set \(X\), \(\mathcal{D}(X; \mathcal{f}^{scu})\) coincides m-almost everywhere with \(X\). Of course, we need to check that \(\text{cl} \mathcal{f}^{scu}\), or equivalently \(\mathcal{f}^{scu}\), is m-engulfing.

**Remark 5.13.** The measure \(\hat{m}_\varphi\) is nonatomic. Under the hypothesis of ergodicity, this is directly from Corollary 4.11. Without this hypothesis, it can be deduced from Theorem C and Proposition 4.1 in [26] because \(\mu_{\mathcal{cu}}^x\) has full support in \(W^s(x)\), for every \(x \in M\).
**Proposition 5.13.1.** \( \mathcal{J}^{\text{scu}} \) is m-engulfing.

**Proof.** Consider \( l, n_l \) as in the previous lemma. Arguing as in Corollary 5.8, we deduce the existence of \( D = D(l) > 0 \) such that for every \( n - l \geq n_l, x \in M \),

\[
\frac{\mu^x(J^{\text{cu}}_{n-l}(x))}{\mu^x(J^{\text{cu}}_n(x))} \leq D.
\]

Define then \( \hat{J}^{\text{scu}}_n(x) := \text{cl} J^{\text{scu}}_{n-l}(x) \) and observe that due to Corollary 5.9 and the inequality above, one can deduce the existence of \( \hat{D} > 0 \) such that

\[
m(\hat{J}^{\text{scu}}_n(x)) \leq \hat{D} \cdot m(J^{\text{ucu}}_n(x)).
\]

This, together with Lemma 5.12, implies the m-engulfing property for \( \mathcal{J}^{\text{scu}} \). \( \square \)

The following is now clear.

**Corollary 5.14.** Every measurable set \( X \) coincides m-almost everywhere with \( \mathcal{D}(X; \mathcal{J}^{\text{scu}}) \).

We have thus established that if \( X \) is m-essentially \( s \)-saturated, then it coincides almost everywhere with the \( s \)-saturated set \( \mathcal{D}(X; \mathcal{J}^{\text{scu}}) \). Interchanging \( f \) by \( f^{-1} \) and \( \hat{m}_\varphi \) by \( m_\varphi \), we deduce that if \( X \) is m-essentially \( u \)-saturated, then it coincides almost everywhere with the \( u \)-saturated set \( \mathcal{D}(X; \mathcal{J}^{\text{ucu}}) \). To continue our reasoning, we now establish:

**Proposition 5.14.1.** Assume that \( m_\varphi = \hat{m}_\varphi \). Then, for any measurable set \( X \), \( \mathcal{D}(X; \mathcal{J}^{\text{scu}}) = \mathcal{D}(X; \mathcal{J}^{\text{ucu}}) \).

The proof uses the following elementary lemma (cf. Proposition B.9 in [22]).

**Lemma 5.15.** Let \( m \) be a Borel probability measure on \( M \) and suppose that \( \mathcal{E}^1 = \{ \{ E^1_n(x) \}_{n \in \mathbb{N}} \}_{x \in M}, \mathcal{E}^2 = \{ \{ E^2_n(x) \}_{n \in \mathbb{N}} \}_{x \in M} \) are decreasing regular Vitali bases. Suppose that there exist \( l \in \mathbb{N}, D = D(l) > 0 \) such that for every \( x \in M \),

\[
E^1_{n+l}(x) \subset E^2_n(x) \subset E^1_{n-l}(x) \quad \frac{m(E^1_{n+l}(x))}{m(E^2_n(x))} \geq D.
\]

Then, for every measurable \( X \subset M \), it holds that \( \mathcal{D}(X; \mathcal{E}^1) = \mathcal{D}(X; \mathcal{E}^2) \).

**Proof.** The core of the proof is to establish the existence of \( l, n_l \in \mathbb{N} \) such that for every \( x \in M, n - l \geq n_l \), it holds that

\[
J^{\text{scu}}_{n+l}(x) \subset J^{\text{ucu}}_n(x) \subset J^{\text{scu}}_{n-l}(x).
\]

Take \( y \in J^{\text{ucu}}_n(x) \): consider \( z, w \) such that \( y \in J^{\text{s}}_n(z), z \in J^{\text{s}}_n(w), w \in B^{l}_{n+l}(x) \) and let \( y' = \text{hol}^s(y) \in W^{\text{cu}}_n(x, c_{1/\varepsilon}) \). Arguing as in the proof of Proposition 5.9.1, we obtain

\[
d(z, w) \leq \varepsilon x^n \Rightarrow d(y, y') \leq C_H \varepsilon^\theta x^{n \theta}.
\]

Hence,

\[
d(f^n y', f^n w) \leq \varepsilon(1 + \lambda^n) + C_H (\varepsilon)^\theta x^{n \theta} \leq 2\varepsilon
\]
if $n$ is sufficiently large. We conclude that if $y'' = W^c(x,2\varepsilon) \cap W^u(y',2\varepsilon)$, then for sufficiently large $k$ and $n \geq k$,

$$d(y',y''),d(y'',w) \leq \sigma^{n-k} \Rightarrow y' \in J^u_{n-k}(y''),y'' \in B_{\sigma^{n-k}}(w'),$$

and thus, for some $l > k,n \geq l$, it holds that $y' \in J^\text{cu}_{n-l}(x)$ and finally $y \in J^{\text{scu}}_{n-l}(x)$. The other inclusion is similar.

To finish, we note that for a given $l$, and since $m = \tilde{m}_\varphi = m_\varphi$,

$$\frac{m(J^\text{ucu}_{n+l}(x))}{m(J^\text{ucu}_{n-l}(x))}$$

is uniformly bounded from below in $x,n$, because $\mathcal{F}^{\text{ucs}}$ is $m$-engulfing (cf. Proposition 5.13.1).

\[\square\]

**Corollary 5.16.** Assume that $m_\varphi = \tilde{m}_\varphi$. If $X$ is $m$-essentially $s$- and $u$- saturated, then $X$ coincides $m$-almost everywhere with the bi-saturated set $\mathcal{D}(X) = \mathcal{D}(X;\mathcal{F}^{\text{scu}}) = \mathcal{D}(X;\mathcal{F}^{\text{ucs}})$.

This allows us to conclude the Kolmogorov property.

**Theorem 5.17.** Assume that $m_\varphi = \tilde{m}_\varphi$ and either

1. $f$ is accessible, or
2. for every $x$, the transverse measure of $\mu^\text{cu}_x | W^u(W^c(x,c_{lps}),c_{lps})$ on $W^c(x,c_{lps})$ is Lebesgue (induced by the Riemannian metric).

Then, the system $(f,\tilde{m}_\varphi)$ is Kolmogorov.

**Proof.** Assuming accessibility, the proof follows from our previous discussion: if $X \in \text{Pin}(f,m)$ has positive measure then $X$ coincides $m$-almost everywhere with a bi-saturated set $\mathcal{D}(X)$, which has to be equal to $M$. Therefore, $m(X) = 1$ and $\text{Pin}(f,m)$ is trivial.

Alternatively, assume the second condition. Let $X \in \text{Pin}(f,m)$ be of positive measure as before and consider $\mathcal{D}(X)$; by changing $X$ by $\mathcal{D}(X)$, it is no loss of generality to assume that $X$ is bi-saturated. Take $x \in \mathcal{D}(X)$ and let $Y = M \setminus X$. By Lemma 5.10, it follows that there exists $n_0$ so that for $n \geq n_0$,

$$\mu^\text{cu}_x (Y \cap J^\text{cu}_n(x)) < \frac{1}{4} \mu^\text{cu}_x (J^\text{cu}_n(x)).$$

If $x' \in W^s(x)$, we get, since $Y$ is bi-saturated and the fact that $\text{hol}^*_{x',x}$ maps isometrically $B^c_{\sigma^n}(x)$ to $B^c_{\sigma^n}(x')$ (Lemma 3.4),

$$J^\text{cu}_n(x') \cap Y = \bigcup_{y \in Y \cap B^c_{\sigma^n}(x')} J^s_n(u).$$

Using that the corresponding transverse measures of $\mu^\text{cu}_x,\mu^\text{cu}_x$ on $B^c_{\sigma^n}(x),B^c_{\sigma^n}(x')$ are Lebesgue, we thus get

$$\frac{\mu^\text{cu}_x(Y \cap J^\text{cu}_n(x'))}{\mu^\text{cu}_x(J^\text{cu}_n(x'))} = \frac{\mu^\text{cu}_x(Y \cap J^\text{cu}_n(x))}{\mu^\text{cu}_x(J^\text{cu}_n(x))} < \frac{1}{4}.$$
Equilibrium states for center isometries

for every \( n \geq n_0 \). We remark that we have not compared the sizes of \( J^s_n(y) \) and \( J^t_n(\text{hol}_{x',x}^s(y)) \) for points \( y \in B_{c_n}^s(x) \) since the stable distance between \( x,x' \) could be large.

Now, by minimality of \( W^s(x) \), again using that the transverse measure of \( \mu^{cu}_y|W^{cu}(y,\varepsilon) \) is Lebesgue and that \( Y \) is bi-saturated, we deduce that for every \( y \in M \),

\[
\frac{\mu^{cu}_y(Y \cap J^{cu}_n(y))}{\mu^{cu}_y(J^{cu}_n(y))} \leq \frac{1}{4}.
\]

This implies that \( \emptyset(Y) = 0 \), and therefore, \( m(X) = 1 \). As in first part, we deduce that \((f,m_\varphi)\) is Kolmogorov.

\[\square\]

**Remark 5.18.** See Section 6.2 for a discussion on the second possible hypothesis in the previous theorem.

5.2. Bernoulli processes

Here, we establish that \((f,\tilde{m}_\varphi)\) is isomorphic to a Bernoulli shift when \( \varphi \) is either constant on center leaves (which includes the case when \( \tilde{m}_\varphi \) is the entropy maximizing measure) of the SRB potential. The hypotheses of Theorem A are assumed, in particular, \( m_\varphi = \tilde{m}_\varphi \); therefore, \((f,\tilde{m}_\varphi)\) is a Kolmogorov system. We rely heavily on the machinery developed by D. Ornstein and B. Weiss to establish the similar statement for the case where \( f \) is the time-one map of an Anosov flow and \( m_\varphi \) is the Lebesgue measure [34] (see also [44]). For the sake of completeness, we repeat here the main concepts and arguments from that work that we will use. Nonetheless, some familiarity with the Ornstein and Weiss article is desirable to follow this section.

Throughout this part, all probability spaces are standard, and all partitions of them are considered to be finite and ordered. If \( P \) is a partition, its \( i \)-th atom will be denoted \( P_i \). For partitions \( P,P' \) of the probability space \((X,B_X,m)\) having the same number \( k \) of atoms, its partition distance is defined as

\[
|P - P'| := \sum_{i=1}^k m(P_i \triangle P'_i).
\]

**Definition 5.6.** Let \( \{P_j\}_{1}^{n},\{Q_j\}_{1}^{n} \) be sequences of partitions of the probability spaces \((X,B_X,m_X),(Y,B_Y,m_Y)\) having the same number of atoms. Then, its \( \bar{d} \)-distance is

\[
\bar{d}(\{P_j\}_{1}^{n},\{Q_j\}_{1}^{n}) := \inf_{g_1,g_2} \frac{1}{n} \sum_{j=1}^{n} |g_1P_j - g_2Q_j|,
\]

where \( g_1,g_2 \) are isomorphisms between \( X,Y \) and some fixed Lebesgue space \((Z,B_Z,m_Z)\) (say, the interval).

To clarify the the meaning of this definition, we observe the following. Given a partition \( P \) of \( X \) and \( x \in X \), the \( P \)-name of \( x \) is simply the atom where it is contained. Similarly, for a sequence of partitions \( \{P_j\}_{1}^{n} \) having the same number of elements, the \( \{P_j\}_{1}^{n} \)-name of \( x \in X \) is the \( n \)-tuple \((P_{j_1}(x),\ldots,P_{j_n}(x))\) such that \( x \in \cap_{k=1}^{n} P_{j_k}(x) \). It is...
straightforward to verify that for partitions $P,P'$ of $X$, the partition distance $|P - P'|$ is simply (twice) the expected value of the function $g_{P,P'} : X \to \{0,1\}$ such that

$$g_{P,P'}(x) = 1 \iff \text{the } P,P' \text{ names of } x \text{ are different}.$$  

Consequently, we have that $d((P_j)^n_1, (Q_j)^n_1) \leq r$ if and only if there is a way to recode simultaneously $(P_j)^n_1, (Q_j)^n_1$ such that the average of the expected value of points having different $n$-names with respect to the encoding is less than or equal to $r$. The following definition and lemma give an important tool to estimate the size of the $d$ distance between two sequences of partitions.

**Definition 5.7.** A measurable map $g : (X,m_X) \to (Y,m_Y)$ is said to be $\epsilon$-measure preserving if there exists $\mathcal{E}x(g) \subset X$ such that $\mu_X(\mathcal{E}x(g)) < \epsilon$ and with the property that $A \subset X \setminus \mathcal{E}x(g)$ implies

$$\frac{|\mu_Y(g(A))|}{\mu_X(A)} - 1 < \epsilon.$$  

In this case, $\mathcal{E}x(g)$ is the exceptional set of $g$.

**Lemma 5.19.** Let $\{P_j\}^n_1, \{Q_j\}^n_1$ be partitions of the probability spaces $(X,\mathcal{B}_X, m_X)$, $(Y,\mathcal{B}_Y, m_Y)$ having the same number of atoms and assume that there exists $g : (X,m_X) \to (Y,m_Y)$-measure preserving with exceptional set $\mathcal{E}x(g)$ such that

$$x \notin \mathcal{E}x(g) \Rightarrow \frac{1}{n} \#\{1 \leq j \leq n : P_j - \text{name of } x \neq Q_j - \text{name of } gx\} \leq \epsilon.$$  

Then, $d((P_j)^n_1, (Q_j)^n_1) \leq 16\epsilon$.

See Lemma 1.3 in [34] for the proof. We will usually apply the previous lemma with $Y \subset X$ a subspace, where $m_Y := m_X(\cdot|Y)$ and $Q_j = P_j|Y$.

The following definition and theorem are central for what follows.

**Definition 5.8.** Let $f : (X,\mathcal{B}_X, m_X) \to (X,\mathcal{B}_X, m_X)$ be an automorphism and $P$ a finite partition of $X$. We say that $P$ is very weak Bernoullian (VWB)\(^{10}\) if, given $\epsilon > 0$, there exists $N_0$ such that for all $N' \geq N \geq N_0$, there exists a family of atoms $\mathcal{G} \subset \bigvee_{1}^{N}, f^{-1}P$ satisfying

- $m_X(\mathcal{G}) > 1 - \epsilon$;
- for $n \geq 0$, it holds that $A \in G \Rightarrow d((f^jP)^n_1, (f^jP |A)^n_1) \leq \epsilon$.

**Theorem 5.20** (Ornstein). Let $f : (X,\mathcal{B}_X, m_X) \to (X,\mathcal{B}_X, m_X)$ be an automorphism.

1. If $P$ is VWB, then $(X,\bigvee_{1}^{\infty}, f^nP, m_X)$ is isomorphic to a Bernoulli shift.
2. Suppose that there exists an increasing family of $f$-invariant $\sigma$-algebras $\{A_n\}^\infty_{n=1}$ satisfying:

\(^{10}\)In [34], the VWB condition is defined with the roles of past and future interchanged. This, however, is a minor difference since if a system is Bernoulli, then its inverse is Bernoulli as well.
Equilibrium states for center isometries

(a) $A_n \nsubseteq B_X$.

(b) For every $n$, $(X,A_n,m_X)$ is isomorphic to a Bernoulli shift. Then, $(X,B_X,m_X)$ is isomorphic to a Bernoulli shift.

From now on, we will specialize in our case of interest $(X,B_X,m_X) = (M,B_M,m = \tilde{m}_\varphi)$. The idea is to show that there exist VWB partitions of arbitrarily small diameter and use the previous theorem to conclude that the process $(f,\tilde{m}_\varphi)$ is Bernoulli. We fix a family of dynamical boxes $\mathcal{V} = \{V_i\}_{i=1}^R$ together with their corresponding $cu$-transversals $\{W_i\}_{i=1}^R$ (see Remark 3.10) and define $\tilde{m}_\varphi$ using these families.

Remark 5.21. In the SRB, we will work with $f^{-1}$ instead of $f$; that is, we will prove that the system $(f^{-1},\tilde{m}_\varphi)$ is Bernoulli, which in turn implies that $(f,\tilde{m}_\varphi)$ is Bernoulli. This is made to guarantee that we have control on the stable measures. Of course, one can argue directly with $(f,m_\varphi)$, but the notation becomes heavier.

Consider a partition $\mathcal{P}$ such that each atom $P \in \mathcal{P}$ is a proper set with diameter smaller than the Lebesgue number of $\{V_i\}_{i=1}^R$, and furthermore, its boundary $\partial P_i$ is piecewise differentiable. Clearly, there exist such partitions of arbitrarily small diameter, and thus, it is enough to prove that $\mathcal{P}$ as above is VWB.

Definition 5.9. Let $A,B \subset M$ with $B$ a dynamical box. We say that $x \in A \cap B$ is a point of $(s−)$tubular intersection if the stable plaque of $B$ containing $x$ is completely contained in $A \cap B$. If every point of $A$ is a point of tubular intersection with $B$, we say that $A$ is a $s$-band.

Lemma 5.22. Let $C$ be a dynamical box and $\delta > 0$. Then, there exists $N_1$ such that for all $N' > N \geq N_1$, one can find $\mathcal{H} \subset \bigvee_{N}^{N'} f^{-n} \mathcal{P}$ with $m(\bigcup_{H \in \mathcal{H}} H) \geq 1 - \delta$ satisfying that if $A \in \mathcal{H}$, there exists $E \subset A$ with the properties

1. $m(E | A) \geq 1 - \delta$.
2. $E \cap C$ is a $s$-band.

Compare Lemma 2.1 in [34]. Note that, in general, the disintegration of $m$ into local stable manifolds is much worse than the case considered by Ornstein and Weiss (where $m$ is Lebesgue).

Proof. Define the set

$$\mathcal{H} := \left\{ x : \lim_{n \to \infty} \frac{S_n \varphi(x)}{n} = \int \varphi \, dm \right\}.$$ 

The system $(f,m)$ is ergodic and $\varphi$ is continuous. Thus, $\mathcal{H}$ is a full measure $s$-saturated set in $M$. By Egoroff’s theorem, we can find $\mathcal{H}_0 \subset \mathcal{H}$ with $m(\mathcal{H}_0) \geq 1 - \delta^2 / 4$, where the above convergence is uniform. Hence, there exists $N_0$ such that for all $N \geq N_0$, for all $x \in \mathcal{H}_0$, it holds that

$$S_n \varphi(x) - nP = S_n \varphi(x) - n\left( \int \varphi \, dm + h_m(f) \right) < -\frac{n h_m(f)}{2}.$$
(recall that $h_m(f) > 0$ by Corollary 4.11). Let $\zeta := \max\{\text{diam}W^s(x,C) : x \in C\}$, and for $n \geq N_1$, define

$$B_n = \bigcup_i \{x \in C \cap f^{-n}P_i : x \text{ is not of tubular intersection}\} = \bigcup_i \{x \in f^nC \cap P_i : x \text{ is not of tubular intersection}\}.$$ 

As $f^nC$ is a dynamical box, $B_n \subset \bigcup_i \bigcup_{x \in \partial P_i} f^nW^s(f^{-n}x,\zeta)$. Now by formula (3.9), Lemma 3.13 and the fact that $H_0$ is $s$-saturated, we deduce the existence of a constant $d = d(\zeta) > 0$ such that

$$\forall x \in \partial P_i \cap H_0, \quad \nu^s_{x_w}(f^nW^s(f^{-n}x,\zeta)) \leq e^{S_n\varphi(x_w) - nP} \leq e^{-n\frac{h_m(f)}{2}},$$

where $P_i \subset V_1 = V(P_i) \subset V$ and $x_w = W^s(x,V_i) \cap W_i$, $W_i = W^c_u(z_i,V_i)$, being the chosen $cu$-transversal of $V_i$.

It follows that

$$m(B_n \cap H_0) \leq \#P \cdot \sup_i \mu^c_u(W_i) \cdot d e^{-n\frac{h_m(f)}{2}} \leq d e^{-n\frac{h_m(f)}{2}}.$$

Define $B := \bigcup_{N_1}^\infty B_n$, where $N_1 > N_0$ is such that $m(B \cap H_0) < \frac{\delta^2}{T}$.

**Claim 1:** For all $N' > N \geq N_1$, there exists $\mathcal{H}_1 \subset \bigvee_{N} f^{-n}P$ such that $m(\bigcup A \not\in \mathcal{H}_1 A) \leq \frac{\delta}{2}$ and $A \in \mathcal{H}_1 \Rightarrow m(M \setminus H_0 | A) < \frac{\delta}{2}$.

Otherwise, $m(M \setminus H_0 | A) \geq \frac{\delta^2}{T}$, contradicting the choice of $H_0$.

**Claim 2:** For all $N' > N \geq N_1$, there exists $\mathcal{H}_2 \subset \bigvee_{N} f^{-n}P$ such that $m(\bigcup A \not\in \mathcal{H}_2 A) \leq \frac{\delta}{2}$ and $A \in \mathcal{H}_2 \Rightarrow m(B \cap H_0 | A) < \frac{\delta}{2}$.

Otherwise, $m(B \cap H_0) \geq \frac{\delta^2}{T}$, contradicting the definition of $B$.

Let $\mathcal{H} = \mathcal{H}_1 \cap \mathcal{H}_2$. Then, $m(\bigcup A \not\in \mathcal{H} A) \geq 1 - \delta$ and for $A \in \mathcal{H}$, the existence of the $s$-band $E \subset A$ satisfying the conclusion of the lemma is easily deduced from the above two claims.

Since $(f,m)$ has the Kolmogorov property, we have the following.

**Lemma 5.23.** Let $C$ be a dynamical box and $\delta > 0$. Then, there exists $N_2 \geq N_1$ such that for any $N' \geq N \geq N_2$, there exists $\mathcal{G} \subset \bigvee_{N} f^{-n}P$ satisfying

- $m(\bigcup A \not\in \mathcal{G} A) \geq 1 - \delta$;
- $A \in \mathcal{G} \Rightarrow |m(C | A) - m(C)| < \delta$.

Until now, we did not make explicit assumptions for the potentials. The conclusion of the lemma below, a refinement of Proposition 3.1.2 for the conditional measures on $W^s$, seems to require to some extra control on the potential, and in particular, on the stable measures.

**Lemma 5.24.** If $\varphi \equiv 0$ or $\varphi = -\log |\det Df| E^u|$, then given $\epsilon > 0$, there exists $\delta > 0$ so that for every $x, y \in \mathcal{E}$, if $A \subset W^s(x, \frac{\epsilon_{\varphi(x)}}{4}), B \subset W^s(y, \frac{\epsilon_{\varphi(y)}}{4})$ are $\delta$—equivalent relatively open and pre-compact sets, then

$$\left| \frac{\nu^s_y(A)}{\nu^s_y(B)} - 1 \right| < \epsilon.$$
**Proof.** In the SRB case, we interchange $f$ and $f^{-1}$ as explained in Remark 5.21, and then the $\nu^s_x$ are smooth volumes on the leaves. Hence, the conclusion of the Lemma follows. Therefore, we only consider the case when $\varphi$ is constant on center leaves. Due to Lemma 3.3, it is enough to prove the same property for the measures $\mu^s_x$ instead of the $\nu^s_x$.

Recall that

$$\mu^s_x = \pi^c_x \mu^s_x,$$

where $\pi^c_x : W^c(W^s(x),c_{cen}) \to W^s(x)$ is the projection collapsing center plaques, $0 < c_{cen} < \frac{c_{lps}}{4}$. By the local product structure of the foliations, if $0 < \delta < \frac{c_{lps}}{4}$, then it follows that for every $x, y \in M$, if $A \subset W^s(x, \frac{c_{lps}}{4}), B \subset W^s(y, \frac{c_{lps}}{4})$ are $\delta$-equivalent, then

$$\text{hol}^u(W^c(B, c_{cen} - \delta)) \subset W^c(A, c_{cen}) \subset \text{hol}^u(W^c(B, c_{cen} + \delta)),$$

where $\text{hol}^u : W^{cs}(y, c_{lps}) \to W^{cs}(x)$ is the local holonomy by unstable leaves and $d(\text{hol}^u(z), z) \leq 2\delta$ for every $z \in W^c(B, c_{cen} + \delta)$. Now, applying part 3 of Proposition 3.1.1, we get the result. \[\square\]

We are ready to prove the analogue of the Main Lemma of [34] (compare Lemma 8.5 in [35]).

**Proposition 5.24.1.** Given $\delta > 0$, there exists $\rho > 0$ such that if $C$ is a dynamical box with diameter less than $\rho$ and $E \subset C$ is a $s$-band, then there exists a bijection $\theta : E \to C$ such that

1. $\theta m(\cdot | E)$ is equivalent to $m(\cdot | C)$, with Jacobian $J(x)$ satisfying $|J(x)| < \delta$, for every $x \in C$.
2. For all $n \geq 0, x \in E$, it holds that $d(f^{-n}x, f^{-n}\theta(x)) \leq \delta$.

**Proof.** Consider $\rho > 0$ smaller than the Lebesgue number of the covering $\{V_i\}_{i=1}^R$. If $C$ is a dynamical box with diam$C \leq \rho$, then it is contained in some $V = V_i$. Hence, using Lemma 3.8, it is no loss of generality to assume $C = V$. We thus can write

$$C = \bigcup_{y \in W^s(x_0, \epsilon)} \text{hol}^s_{y,x_0}(W), W = Pu(x_0, \epsilon)$$

for some $x_0 \in M, \epsilon > 0$ (cf. Corollary 3.5). Observe that if $E \subset C$ is an $s$-band, then

$$m(A | E) = \frac{1}{m(E)} \int_W \frac{\nu^u_{\theta}(W^s(w) \cap A)}{\nu^u_{\theta}(W^s(w,C))} \, d\mu^u_x w.$$

Fix $E \subset C$ an $s$-band and let $\theta_{x_0} : W \cap E \to W$ be a bijective map that sends $\mu^u_{x_0}|W \cap E$ to $\mu^u_x|W$. For $x \in E$, define $\theta(x) = \text{hol}^s_{x,x_0} \circ \theta_{x_0} \circ \text{hol}^s_{x_0,x}(x)$: $\theta$ preserves $cu$-plaques of $C$; therefore, $d(f^{-n}x, f^{-n}\theta(x)) \leq \rho$ for every $n \geq 0$. Since $E$ is an $s$-band, $\theta$ is bijective (and clearly measurable).

For every $w \in W$, $\theta \nu^u_{\theta}(\cdot | W^s(w,C))$ is sent to a measure $\tilde{\nu}^u_{\theta_{x_0}(w)}$ which, due to the previous Lemma, is uniformly comparable with $\nu^u_{\theta_{x_0}(w)}(\cdot | W^s(\theta_{x_0}(w),C))$. From this, the statement follows easily. \[\square\]

Now, we can apply Lemma 2.3 of [34] to obtain the following.
Lemma 5.25. Let $\epsilon, \delta > 0$ be given. Then, there exists $N$ with the property that for all $N' \geq N$, one can find $\mathcal{G} \subset \bigvee_{N}^{N'} f^{-n}P, E \subset M$ and $\theta : E \to M$ satisfying

1. $m(\cup_{A \in \mathcal{G}} A) \geq 1 - \epsilon$;
2. $\theta$ is a bijective onto $\epsilon$-measure preserving map from $(E, m(\cdot | E))$ to $(M, m)$;
3. for $A \in \mathcal{G}$, then $\theta(E \cap A) = A$ and
   (a) $m(E \cap A | A) \geq 1 - \epsilon$;
   (b) for all $n \geq 0, x \in E \cap A$ it holds that $d(f^{-n}x, f^{-n}(\theta(x))) \leq \delta$.

For convenience of the reader, we spell the proof.

Proof. Consider $0 < \rho$ corresponding to $\delta$ in the previous proposition. Using Besicovitch covering lemma we construct a partition $\{U_0, U_1, \ldots, U_l\}$ such that

1. for $1 \leq j \leq l$ the set $U_j$ is a dynamical box of diameter less than $\rho$.
2. $m(U_0) \leq \frac{\epsilon}{10}$.

Then using Lemmas 5.22 and 5.23 we deduce that there exists $N$ such that for all $N' \geq N$ we can find $\mathcal{G} \subset \bigvee_{N'}^{N} f^{-n}P$ with $m(\cup_{A \in \mathcal{G}} A) \geq 1 - \epsilon$ and such that for $A \in \mathcal{G}, 1 \leq j \leq l$ there exists $E_A \subset A$ of relative measure bigger than $1 - \epsilon$ with the properties:

1. $\sum_{j} |m(E_A | U_j) - m(B_j)| < \epsilon$.
2. $E_A \cap U_j$ is a $s$-band for $1 \leq j \leq l$, $E_A \cap U_0 = \emptyset$.

We let $E := \bigcup_{A \in \mathcal{G}} E_A \cup U_0$. Finally we use the previous proposition in each $E_A \cap U_j$, and by defining $\theta | U_0$ as the identity we get $\theta : E \to M$ satisfying the conclusion of the lemma.

Now we finish the proof.

Theorem 5.26. The partition $P$ is VWB.

Proof. Let $\epsilon > 0$ be given. If $E \subset M$ and $j \in \mathbb{N}$, then for every $x \in M$,

$$x \in \text{atom } A \text{ of } f^{j}P | E \iff f^{-j}x \in \text{atom } f^{-j}A \text{ of } P,$$

and similarly for the partition $f^{j}P$. It follows that for every $n \in \mathbb{N}, x \in E$, the $\{f^{j}P | E\}_{j=0}^{n}$- and $\{f^{j}P | E\}_{j=0}^{n}$-names are determined by the atoms of $P$ that the finite sequence $\{f^{-j}x\}_{j=0}^{n}$ visits.

Take $\epsilon = \frac{\delta}{64}$ and apply the previous Lemma with $\epsilon, \delta$, where $\delta$ is chosen as follows. Since all atoms $A \in \mathcal{P}$ have (piecewise) smooth boundaries by disregarding some additional atoms in $\mathcal{G} \subset \bigvee_{N}^{N'} f^{-n}P$, we can modify the $\epsilon$-measure preserving map $\theta : (E, m(\cdot | E)) \to (M, m)$ that we constructed to some other $2\epsilon$-measure preserving map $\theta' : (E', m(\cdot | E')) \to (M, m)$ such that

$$x \not\in \mathcal{G}x(\theta') \Rightarrow \forall n, \frac{1}{n} \# \{1 \leq j \leq n : P - \text{name of } x \neq P - \text{name of } \theta(x)\} \leq 2\epsilon.$$

To see this, note that points $x, y$ such that $d(x, y) < \delta$ and $x, y$ are in different atoms of $P$, necessarily are in $N_{\delta} = \bigcup_{i} N_{\delta}(\partial P_{i})$, where $N_{\delta}(\partial P_{i})$ denotes the $\delta$-tubular neighborhood
of \( \partial P_i \); since \( \partial P_i \) is piecewise-smooth, this \( \delta \)-neighborhood is contained in the union of finitely many \( \delta \)-neighborhoods of smooth codimension one manifolds of zero \( m \)-measure. From here, the claim follows, as one can choose \( \delta \) so that \( m(N_\delta) \) is arbitrarily small.

If \( A \in \mathcal{G} \subset \bigvee_{N'} f^{-n} P \), then by applying Lemma 5.19, we conclude that for all \( n \geq 0 \), it holds that

\[
\mathcal{D}((f^j P)^n_1, (f^j P | A)^n_1) \leq \mathcal{D}((f^j P)^n_1, (f^j P | E)^n_1) + \mathcal{D}((f^j P | E)^n_1, (f^j P | A)^n_1) \leq 16(2\varepsilon + 2\varepsilon) < \varepsilon.
\]

Hence, \( P \) is VWB.

Theorems 5.26 and 5.20 imply Theorem C.

6. Applications and concluding remarks

In this last section, we apply our results, particularly of Section 4, to the rank-one case. We finish with some questions.

6.1. Hyperbolic flows

Let \( \Phi = (f^t)_{t \in \mathbb{R}} \) be an Anosov flow with invariant splitting \( TM = E^s \oplus E^c \oplus E^u \), where \( E^c \) is generated by tangents to flow direction. If this flow is transitive, there is a dichotomy:

1. \( \Phi \) is a suspension of an Anosov diffeomorphism, and therefore, \( M \) is a fiber bundle over \( S^1 \), with fibers transverse to the flow line, or
2. both \( W^s, W^u \) are minimal foliations.

See [38]. In what follows, we will focus in this last case.

For Anosov flows, the powerful of symbolic representations is available [3, 43]. With this, one can establish the following.

**Proposition 6.0.1.** Given a Hölder potential \( \varphi : M \to \mathbb{R} \), there exists \( \mu^u \in \text{Meas}(W^u) \) satisfying:

a) \( \mu^u_x \) has full support inside \( W^u(x) \), and is nonatomic.

b) \( \forall t \in \mathbb{R}, x \in M \), \( f^{-t} \mu^u_{f^t(x)} = e^{P_{\text{top}}(\varphi) t - \int_0^t \varphi(f^s(\cdot)) ds} \mu^u_x \).

c) The map \( \mu^u : x \to \mu^u_x \) is weakly continuous in the following sense: given \( y \in W^u(x, \varepsilon_0) \) and \( \text{hol}_{y,x}^u : W^u(y) \to W^u(x) \) the locally defined Poincaré map, it follows that for any \( A \subset W^u(x) \) relatively open and pre-compact, it holds that

\[
\mu^u_y(\text{hol}_{y,x}^u(A)) \xrightarrow{y \to x} \mu^u_x(A).
\]

Moreover, the convergence is uniform in \( x \).

**Proof.** The construction is due to N. Haydn [20], based in the original construction of Gibbs measures from Sinai [48]. Details are given in the Appendix of the paper of M. Pollicot and C. Waldken [39]. Part c) is not explicitly stated by Haydn, who only states (a stronger version of) this fact for holonomies corresponding to the strong stable foliation, although it clearly follows from this and part b).
Let \( f = f_1 \) the time-one map. Given \( \varphi \), we denote \( \tilde{\varphi} \) its average along flow lines \( \tilde{\varphi}(x) = \int_0^1 \varphi(f^k x) \, dt \). Observe that by the above proposition, the family of measures \( \mu^u = \{ \mu^u_x \}_{x \in M} \) satisfies the same conditions as the measures along unstables that we constructed in Section 3.1. Therefore, all our construction goes through and we can determine an equilibrium state \( m_{\tilde{\varphi}} \) for the system \( (f, \tilde{\varphi}) \) having conditionals along unstables given by the family \( \mu^u \). We now relate \( m_{\tilde{\varphi}} \) and the equilibrium states for the flow.

Denote by \( \mathcal{P}_r(M) = \cap_{t \in \mathbb{R}} \mathcal{P}_{f_t}(M) \) the set of invariant measures for the flow. The topological pressure of the system \( (\Phi, \varphi) \) is given by the variational principle ([50], Corollary 4.12)

\[
P_{\text{top}}(\Phi, \varphi) = \sup_{\nu \in \mathcal{P}_r(M)} \{ h_\nu(\Phi_1) + \int \varphi \, d\nu \},
\]

and the definition of equilibrium state for this system is clear. In what follows, we will write \( \mathcal{C}_q(f, \varphi) \) for the set of equilibrium measures of \( (f, \varphi) \), and analogously, \( \mathcal{C}_q(\Phi, \varphi) \) denotes the set of equilibrium states for \( (\Phi, \varphi) \). Clearly, \( \mathcal{C}_q(\Phi, \varphi) \subset \mathcal{C}_q(f, \varphi) \), and although in principle these sets can be different, it is known that

\[
P_{\text{top}}(\Phi, \varphi) = P_{\text{top}}(f, \tilde{\varphi}).
\]

However, using the previous line, it is direct to check that \( P_{\text{top}}(\Phi, \varphi) = P_{\text{top}}(f, \tilde{\varphi}) \).

Therefore, it follows that

\[
\mathcal{C}_q(\Phi, \varphi) = \{ \mu \in \mathcal{P}_r(M) : h_\mu(f) + \int \tilde{\varphi} \, d\mu \} \subset \mathcal{C}_q(f, \tilde{\varphi}).
\]

**Proposition 6.0.2.** If \( \Phi \) is a transitive Anosov flow, then the sets \( \mathcal{C}_q(\Phi, \varphi) \) and \( \mathcal{C}_q(f, \tilde{\varphi}) \) coincide. Therefore, \( \mathcal{C}_q(f, \tilde{\varphi}) = \{ m_{\tilde{\varphi}} \} \).

**Proof.** Let \( A(t, x) = \int_0^1 \varphi(\Phi_t x) \, ds \); then, \( A : M \times \mathbb{R} \rightarrow \mathbb{R} \) is an additive cocycle over \( \Phi \) \( A(t + s, x) = A(t, \Phi_s x) + A(s, x) \) and \( A(1, x) = \tilde{\varphi} \). For transitive hyperbolic flows, it is known (cf. [7]) that \( \mathcal{C}_q(\Phi, \varphi) = \{ \mu \} \), and in particular, \( \mu \) is ergodic for the flow (in fact, \( (\Phi, \mu) \) is a Bernoulli flow). Fix any \( m \in \mathcal{C}_q(f, \tilde{\varphi}) \) and note that since \( f \) and \( f^s \) commute, \( f^s m \in \mathcal{C}_q(f, \tilde{\varphi}) \).

Now, the cocycle property tells us that

\[
A(1 + s, x) = A(1, f^s(x)) + A(s, x) = A(s, f(x)) + A(1, x)
\]

\[
\Rightarrow \tilde{\varphi} \circ f^s(x) - \tilde{\varphi}(x) = A(1, f^s(x)) - A(1, x) = A(s, f(x)) - A(s, x)
\]

and \( \tilde{\varphi} \circ f^s \) is cohomologous to \( \tilde{\varphi} \), i.e. its difference is of the form \( k(f(x)) - k(x) \) for some \( k \) (that in this case is Hölder). It is simple to check that cohomologous potentials have the same equilibrium states; Therefore, \( f^s m \in \mathcal{C}_q(f, \tilde{\varphi}) \). The measure \( \tilde{\mu} = \int_0^1 f^s m \) is invariant under the flow and an equilibrium state for \( (f, \tilde{\varphi}) \). Hence, \( \tilde{\mu} = \mu \). Since \( \mu \) is ergodic for the map \( f = f_1 \) \( ((\Phi, \mu) \) is mixing; thus, clearly \( (f, \mu) \) is mixing), we deduce that

\[
f^s m = \mu \quad \forall s \in [0, 1]
\]

and, in particular, \( m = \mu \). \( \square \)
The above, together with Theorem B, implies Corollary B. In the article [13], Corollary B is used to investigate further properties of the horocyclic flow, as uniqueness of quasi-invariant measures.

Here is the last application of these ideas.

Corollary 6.1. Suppose that $\zeta^{cs} \in \text{Meas}(\mathcal{W}^{cs})$ is such that for every $x \in M$, $f^{-1} \zeta^{cs}_{fx} = e^{P'} \zeta^{cs}_x$, where $P' \in \mathbb{R}$. Then, $\zeta^{cs} = \mu^{cs}$ and $P' = P_{top}(\varphi)$.

Proof. The quasi-invariance condition in the hypotheses permits us to compute the Jacobian of $\zeta^{cs}$ with respect to the unstable holonomy, and this coincides with the Jacobian of $\mu^{cs}$. We can thus use $\zeta^{cs}$ instead of $\mu^{cs}$ and construct a probability $m$ that is an equilibrium state for $(f, \tilde{\varphi})$ (cf. Section 3.2). Therefore, it is the unique equilibrium state for $(\Phi, \varphi)$. Using the local product structure, one gets that $\zeta^{cs} = \mu^{cs}$. \hfill \Box

6.2. Epilogue

We finish our article with some questions and considerations. In this part, the standing hypotheses are $f: M \to M$ is a $C^2$ center isometry with minimal stable and unstable foliations, $\varphi: M \to \mathbb{R}$ a Hölder potential.

Question. Assume the existence of an equilibrium state $m_\varphi$ for $(f, \varphi)$ and families of measures $\mu^u, \mu^s$ satisfying the quasi-invariance condition 3 of Theorem A. Does it follow the uniqueness of the equilibrium state?

This question has eluded us for some time, and for the time being the only cases where uniqueness is known are potentials similar to the ones treated in this article. The proofs are obtained by methods that do not rely on this property. Maybe one can start from the following.

Question. Assume that the existence conclusions of Theorem A are valid, together with the ergodicity of $m_\varphi, \tilde{m}_\varphi$. Is the case that $m_\varphi = \tilde{m}_\varphi$?

Since these measures are ergodic, it would suffice to establish that they are not singular with respect to each other. Here is example of such a situation.

Claim. Assume that $\varphi$ is constant on center leaves and suppose that the center disintegration of the measures $\mu^u, \mu^s$ is Lebesgue, meaning that for every $x$, the disintegration of $\mu^u_x$ on $P^u(x, c_{ips})$ by local center manifolds is given by absolutely continuous measures with uniformly bounded (independently of $x$) Jacobians, and likewise for $\mu^s_x$ on $P^s(x, c_{ips})$. Then, $m_\varphi = \tilde{m}_\varphi$.

Proof. It suffices to establish that $\tilde{m}_\varphi << m_\varphi$. During the proof, we will denote $a \sim b$ to indicate that the quotient $a/b$ is bounded above and below, with constants independent of $\epsilon$. Using the Proposition 3.12.1 and the remark after it, we get

$$
\sup_{0 < \epsilon < c_{psm}} \frac{\tilde{m}_\varphi(B(x, \epsilon))}{m_\varphi(B(x, \epsilon))} \leq D \cdot \sup_{0 < \epsilon < c_{psm}} \frac{\mu^u_x(B^u(x, \epsilon)) \cdot \mu^u_x(P^u(x, \epsilon))}{\mu^s_x(B^s(x, \epsilon)) \cdot \mu^s_x(P^s(x, \epsilon))}.
$$
where \( D \) does not depend on \( x \). Recalling the definition of \( \mu^c_x, \mu^u_x \) in the \( c \)-constant case Equation (3.3) and since \( \mu^c_x \) has Lebesgue disintegration,

\[
\frac{\mu^c_x(W^s(x,\epsilon))}{\mu^c_x(P^c(x,\epsilon))} \sim \left( \frac{c_{cen}}{\epsilon} \right)^c,
\]

and likewise,

\[
\frac{\mu^u_x(P^c(x,\epsilon))}{\mu^u_x(W^u(x,\epsilon))} \sim \left( \frac{\epsilon}{c_{cen}} \right)^c.
\]

We conclude that there exists some constant \( \tilde{D} > 0 \) such that for every \( x \in M \), it holds that

\[
\sup_{0 < \epsilon < c_{psm}} \frac{\tilde{m}_\varphi(B(x,\epsilon))}{m_\varphi(B(x,\epsilon))} \leq \tilde{D}.
\]

This implies that \( \tilde{m}_\varphi \ll m_\varphi \) and \( \frac{\partial \tilde{m}_\varphi}{\partial m_\varphi}(x) \leq \tilde{D} \) for \( m_\varphi \)-a.e. \( (x) \), as consequence of the standard Lebesgue differentiation theorem for Borel measures. To check the absolute continuity, assume that \( m_\varphi(A) = 0 \) and let \( r > 0 \) be arbitrary. Take a sequence of dynamical boxes \( \{B(x_k,\epsilon_k)\}_{k \in \mathbb{N}} \) satisfying

1. \( A \subset \bigcup_{k \geq 0} B(x_k,\epsilon_k) \),
2. \( \sum_{k=0}^{\infty} m_\varphi(B(x_k,\epsilon_k)) < \frac{r}{D} \).

Then,

\[
\tilde{m}_\varphi(A) \leq \sum_{k=0}^{\infty} \tilde{m}_\varphi(B(x_k,\epsilon_k)) \leq \tilde{D} \sum_{k=0}^{\infty} m_\varphi(B(x_k,\epsilon_k)) < r,
\]

and since \( r > 0 \) is arbitrary, \( \tilde{m}_\varphi(A) = 0 \).

The conditional measures of \( \mu^c_x \) and \( \mu^u_x \) along centrals seem to contain some important information about the equilibrium state. We can thus ask the following.

**Question.** When are the center conditional measures of \( \mu^c_x \) and \( \mu^u_x \) absolutely continuous?

One possible tool to answer the previous question is using the construction of Section 2 as in the following example.

**Example 6.2.** For \( x \in M \), denote by \( \lambda^c_x \) the normalized Lebesgue measure on \( W^c(x, \epsilon_c) \). Assume that \( E^c \) is differentiable and that \( \varphi \) is \( c \)-constant.

**Claim.** For every \( x \in M \), the conditional measures of \( \mu^c_x | P^c(x, \epsilon_c) \) with respect to the center foliation are given by \( \{\lambda^c_y\}_{y \in W^c(x)} \).

In particular, the disintegration is defined everywhere. The situation is similar for \( \mu^u_x \). To see this, fix \( x \in M \), \( 0 < \epsilon \leq \epsilon_c \) and let \( B = P^c(x, \epsilon) \). For \( n \geq 0 \), let \( B_n = f^n(B) \) and note that since \( f \) is a center isometry, then \( \forall y \in B_n \) the map \( f^{-n} : W^c(y, B_n) \rightarrow W^c(f^{-n}y, B) \) is an isometry with respect to the induced metric. As \( W^c \) is differentiable,
the disintegration of the Lebesgue measure \( \nu|B_n = \text{Leb}^c|B_n \) along center plaques is given by \( \{\lambda^c_y\}_{y \in B_n} \). Therefore, for \( \nu_n = f^{-n}\nu|B_n \), its disintegration is given by \( \{f^{-n}\lambda^c_y\}_{y \in B_n} = \{\lambda^c_z\}_{z \in B}. \) This, in turn, implies that the center disintegration of \( \nu^n = e^{S_n\varphi}f^{-n}\nu \) is given by

\[
(v^n)^c_y = \frac{e^{S_n\varphi}}{e^{S_n\varphi}d(v^n)_y}(v_n)^c_y = (v_n)^c_y = \lambda^c_y.
\]

From this, it follows that every section \( \nu \in \mathcal{X} (2.4) \), in particular \( \mu^c_u \), has the same disintegration, proving our claim.

**Question.** What are, in general, the disintegrations of \( \mu^c_u \) and \( \mu^u \) along center leaves?

Similarly, we can inquire about the transverse measures of \( \mu^u \) on (local) center leaves. For the geometrical proof of the Kolmogorov property Theorem 5.17, we noted that a sufficient condition would be establishing that these measures are Lebesgue. We suspect that this is always the case.

**Question.** Is it true that the transverse (normalized) measures of

\[
\mu^c_u|W^u(W^c(x,c_{ips}),c_{ips}),
\]

\[
\mu^c_s|W^s(W^c(x,c_{ips}),c_{ips})
\]

are equal \( \lambda^c_x \)?

### 7. Appendix: Proof of Theorem D

Let \( A: \mathbb{T}^2 \to \mathbb{T}^2 \) be a linear Anosov map and consider \( f: \mathbb{T}^2 \times \mathbb{T}^2 \to \mathbb{T}^4 \) the group extension of \( A \) given by

\[
f(x,\theta_1,\theta_2) = (A \cdot x, \theta_1 + \alpha_1k(x), \theta_2 + \alpha_2k(x)),
\]

where \( k: \mathbb{T}^2 \to \mathbb{T} \) is analytic, not cohomologous to constant, and \( (\alpha_1,\alpha_2) \) is a Liouville vector (see below). Then, \( f \) is a conservative analytic center isometry with a center bundle parallel to the vertical fibers \( \{0\} \times \mathbb{R}^2 \). This example was considered by Dolgopyat [17] in other contexts. Due to a result of Katok, Theorem 1 in [25], this map is a \( K \)-automorphism; therefore, its unstable foliation \( W^u \) is ergodic.

**Lemma 7.1.** \( W^u \) is minimal.

**Proof.** Let \( e^u \) be a unit vector in \( \mathbb{T}^2 \) generating the unstable bundle of \( A \) and consider the linear flow \( \psi^u_t: \mathbb{T}^2 \to \mathbb{T}^2 \), \( \psi^u_t(x) = x + t \cdot e^u \). The unstable foliations of \( A \) are the orbits of \( \psi^u \), and it holds that

\[
A\psi^u_t(x) = \psi^u_{\lambda t}(Ax),
\]

where \( \lambda > 1 \) is the unstable eigenvalue of \( A \). It is not hard to verify that the unstable foliation of \( f \) is the orbit foliation of the flow \( \tilde{\psi}^u_t: \mathbb{T}^4 \to \mathbb{T}^4 \) given by

\[
\tilde{\psi}^u_t(x,\theta_1,\theta_2) = (\psi^u_t(x), \theta_1 + \alpha_1l_t(x), \theta + \alpha_2l_t(x)),
\]

where \( l_t(x) = \sum_{n=1}^\infty k(A^{-n}x) - k(A^{-n}\psi^u_n(x)) = \sum_{n=1}^\infty k(A^{-n}x) - k(A^{-n}x + \frac{t}{\lambda}e^u) \); since \( k \) is differentiable, the previous series is convergent. In particular, \( \tilde{\psi}^u \) is conservative.
The flow $\psi^u$ is uniquely ergodic, with Leb being its invariant measure. Therefore, by a classical result due to Furstenberg, either $\psi^u_t$ is uniquely ergodic (and therefore minimal, since it preserves $\mu = \text{Leb} \times d\theta_1 \times d\theta_2$) or any $\hat{\psi}^u_t$ ergodic invariant measure has atomic disintegration along the partition given by the vertical tori (i.e. the center foliation of $f$). See Theorem 4.1 in [18]. The latter possibility is prohibited by Katok’s result, as $\hat{\psi}^u_t$ is ergodic with respect to Lebesgue.

The vector $(\alpha_1, \alpha_2)$ is chosen so that $\frac{\alpha_1}{\alpha_2} \not\in \mathbb{Q}$, and that for every $n \in \mathbb{N}$, there exists $m_{n,1}, m_{n,2} \in \mathbb{N}$ such that

- $|\alpha_1 m_{n,1} + \alpha_2 m_{n,2}| < 1 m_{n,1} 2^n$;
- $m_{n,2} \geq m_{n,1} > n$.

Denote $d_n(x, \theta_1, \theta_2) = \exp(2\pi i ((\theta_1, \theta_2), (m_{n,1}, m_{n,2})))$; then, $d_n : \mathbb{T}^4 \to \mathbb{T}$ satisfies

$$d_n(f(x, \theta_1, \theta_2)) = \exp(2\pi i ((\theta_1 + \alpha_1 k(x), \theta_2 + \alpha_2 k(x)), (m_{n,1}, m_{n,2}))) = \exp(2\pi i k(x) ((\alpha_1, \alpha_2), (m_{n,1}, m_{n,2}))) \cdot d_n(x, \theta_1, \theta_2).$$

Define $\varphi : M \to \mathbb{R}$ by

$$\varphi(x, \theta_1, \theta_2) = \sum_{n \geq 0} d_n(f(x, \theta_1, \theta_2)) - d_n(x, \theta_1, \theta_2) = \sum_n \left( \exp \left( 2\pi i k(x) ((\alpha_1, \alpha_2), (m_{n,1}, m_{n,2})) \right) - 1 \right) d_n(x, \theta_1, \theta_2).$$

Observe that $\varphi$ is the $C^\infty$ limit of coboundaries; therefore, $\mathcal{E}q(f, \varphi) = \mathcal{E}q(f, 0)$. It is clear, however, that the Lebesgue measure in $\mathbb{T}^4$ maximizes entropy.

Assume that there exists a family of measures $\zeta^u = \{\zeta^u_L : L \in \mathcal{W}^u\}$ satisfying the quasi-invariance condition $f^{-1}\zeta^u_L = e^{\mathcal{R}(\varphi) - h_{top}(f)} \zeta^u_L$ and depending continuously on the point. Then, by Theorem B, one would have

$$\zeta^u_L = e^{\omega_L} \cdot m^u_L,$$

where $m^u_L$ is the corresponding Margulis measure on $L$, and $\omega_L : L \to \mathbb{R}_{>0}$ is continuous. We would thus get

$$e^{\mathcal{R}(\varphi) - h_{top}(f) + \omega_L} m^u_L = f^{-1}(e^{\omega_L} \cdot m^u_L) = e^{\omega_L \circ f - h_{top}(f)} m^u_L,$$

and hence, $\mathcal{R}(\varphi) = \omega_L \circ f - \omega$. (because the Margulis measures have full support). If $k(0) = 0$, then $L_0 = W^u(0)$ is fixed, and this gives, for $\omega = \omega_{L_0}$,

$$\mathcal{R}(\varphi) = \omega \circ f - \omega \text{ on } L_0.$$ 

Since the family $\{\omega_{W^u(x)}\}_x$ depends continuously on $x$ (the $m^u$ are essentially the Lebesgue measure), $\omega$ extends continuously to $M$, thus implying that $\mathcal{R}(\varphi)$ is cohomologous to the zero function, with continuous transfer function. Likewise, the situation is similar for $\mathfrak{S}(\varphi)$; thus, there would exist $\phi : M \to \mathbb{C}$ continuous so that $\varphi = \phi \circ f - \phi$.

We can use Fourier expansion to find $\phi$; for $x \in \mathbb{T}^2$, we consider $\varphi(x, \cdot, \\cdot) : \mathbb{T}^2 \to \mathbb{R}$. If $(n_1, n_2) \in \mathbb{Z}^2$, we denote by

$$e_{(n_1, n_2)}(\theta_1, \theta_2) = \exp(2\pi i ((n_1, n_2), (\theta_1, \theta_2)))$$
the corresponding element of the Fourier basis. Note that $d_n(x,\theta_1,\theta_2) = e_{(m_1,1,m_2)}(\theta_1,\theta_2)$. We compute
\[
\varphi(x, \cdot, \cdot) = \sum_n (e_{(m_1,1,m_2)}(k(x)\alpha_1,k(x)\alpha_2) - 1) \cdot e_{(m_1,1,m_2)}
\]
\[
\phi(x, \cdot, \cdot) = \sum_{(n_1,n_2)} a_{(n_1,n_2)}(x) \cdot e_{(n_1,n_2)}
\]
where $a_n : \mathbb{T}^2 \to \mathbb{C}$ is continuous, and
\[
\varphi(x, \cdot, \cdot) = \phi(f(x, \cdot, \cdot)) - \phi(x, \cdot, \cdot)
\]
\[
= \sum_{(n_1,n_2)} \left( a_{(n_1,n_2)}(Ax) \cdot e_{(n_1,n_2)}((k(x)\alpha_1,k(x)\alpha_2)) - a_{(n_1,n_2)}(x) \right) \cdot e_{(n_1,n_2)}
\]
\[
\Rightarrow \begin{cases} 
(\text{I}) & a_{(n_1,n_2)}(Ax) \cdot e_{(n_1,n_2)}((k(x)\alpha_1,k(x)\alpha_2)) = a_{(n_1,n_2)}(x) \quad (n_1,n_2) \neq (m_1,1,m_2) \\
(\text{II}) & a_{(m_1,1,m_2)}(Ax - 1) \cdot e_{(m_1,1,m_2)}((k(x)\alpha_1,k(x)\alpha_2)) = a_{(m_1,1,m_2)}(x) - 1
\end{cases}
\]
From (I), we get that if $(n_1,n_2) \neq (m_1,1,m_2)$, then $|a_{(n_1,n_2)}(Ax)| = |a_{(n_1,n_2)}(x)|$; since $A$ is topologically transitive, $|a_{(n_1,n_2)}(x)| = c_{(n_1,n_2)} \in \mathbb{R}$ constant. It follows that $c_{(n_1,n_2)} \cdot e_{(n_1,n_2)}((k(x)\alpha_1,k(x)\alpha_2)) = c_{(n_1,n_2)}$ for every $x$, and this implies that $c_{(n_1,n_2)} = 0$ (because $k(x)$ is not constant). We argue similarly for (II): fixed pair $(m_1,1,m_2)$, the function $x \mapsto |a_{(m_1,1,m_2)}(x) - 1|$ has to be constant and therefore is the zero function. It follows that $a_{(m_1,1,m_2)}(x) = 1$ for every $x$. Putting together (I),(II), we get that
\[
\phi = \sum_n d_n = \sum_{(m_1,1,m_2)} e_{(m_1,1,m_2)}.
\]

This is a contradiction, due to the Riemann-Lebesgue lemma. We have shown that our assumption on the existence of families of measures $\zeta^u$ (and the corresponding one for $\Im(\varphi)$) is incorrect, thus establishing Theorem D.

**Remark 7.2.** We have used a complex valued potential to simplify the computations, but clearly the same argument can be adapted using one real valued potential, by employing the Fourier basis of $\mathbb{T}^2$ that consists of products of sines and cosines.

**Acknowledgements.** We are very thankful to the referee for her/his careful reading of the manuscript, giving several thoughtful suggestions, bringing to our attention some references and pointing out errors in the original version of this work.

The first author would like to thank the hospitality of the Penn State Math department, where this project was initiated.

**Competing Interest.** None.

**References**

[1] D. Anosov, Geodesic flows on closed Riemannian manifolds of negative curvature, *Proc. Steklov Math. Inst.* 90 (1967), 1–235.

[2] Y. Bonthonneau, C. Guillarmou and T. Weich, SRB measures for Anosov actions, Preprint, Arxiv:2103.12127.
[3] R. Bowen, Symbolic dynamics for hyperbolic flows, *Am. J. Math.* **95**(2) (1973), 429–460.
[4] R. Bowen, Bernoulli equilibrium states for axiom A diffeomorphisms, *Math. Syst. Theory* **8**(4) (1974a), 289–294.
[5] R. Bowen, Some systems with unique equilibrium states, *Math. Syst. Theory* **8**(3) (1974b), 193–202.
[6] R. Bowen, *Equilibrium States and the Ergodic Theory of Anosov Diffeomorphisms* (Lect. Notes in Math.) vol. **470** (Springer Verlag, 2008).
[7] R. Bowen and D. Ruelle, The ergodic theory of Axiom A flows, *Invent. Math.* **29** (1975), 181–202.
[8] M. Brin and A. Katok, On local entropy, *Proc. Conf. in Dyn. Sys, Rio de Janeiro* (Lecture Notes in Mathematics), vol. **1007** (Springer, 1983), 30–38.
[9] K. Burns and A. Wilkinson, On the ergodicity of partially hyperbolic systems, *Ann. Math.* **171** (2010), 451–489.
[10] J. Buzzi, Thermodynamical formalism for piecewise invertible maps: Absolutely continuous invariant measures as equilibrium states, in A. Katok, R. de la Llave, Y. Pesin and H. Weiss (eds.) *Smooth Ergodic Theory and Its Applications* (Proceedings of Symposia in Pure Mathematics) vol. **69** (American Mathematical Society, 2001), 749–783.
[11] J. Buzzi, T. Fisher and A. Tahzibi, A dichotomy for measures of maximal entropy near time-one maps of transitive Anosov flows, *Ann. Scient. Ec. Norm. Sup.* **55**(4) (2021), 969–1002.
[12] B. Call and D. J. Thompson, Equilibrium states for self-products of flows and the mixing properties of rank 1 geodesic flows, *J. London Math. Soc.* **105**(2) (2022), 794–824.
[13] P. D. Carrasco and F. Rodriguez-Hertz, Contributions to the ergodic theory of hyperbolic flows: unique ergodicity for quasi-invariant measures and equilibrium states for the time-one map, To appear in *Isr. J. Math.* (2022).
[14] V. Climenhaga, Y. Pesin and A. Zelerowicz, Equilibrium measures for some partially hyperbolic systems, *J. Mod. Dyn.* **16**(0) (2020), 155–205.
[15] M. Denker, G. Keller and M. Urbanski, On the uniqueness of equilibrium states for piecewise monotone mappings, *Stud. Math.* **1**(97) (1985), 27–36.
[16] D. Dolgopyat, Lectures on U-Gibbs states, *Lecture notes* (2001).
[17] D. Dolgopyat, Livsic theory for compact group extensions of hyperbolic systems, *Moscow Mathematical Journal* **5**(1) (2005), 55–66.
[18] H. Furstenberg, Strict ergodicity and transformation of the torus, *Am. J. Math.* **83**(4) (1961), 573.
[19] M. Grayson, C. Pugh and M. Shub, Stably ergodic diffeomorphisms, *Ann. Math.* **140**(2) (1994), 295–329.
[20] N. Haydn, *Canonical product structure of equilibrium states*, Random Comput. Dynam. (1994).
[21] N. T. A. Haydn and D. Ruelle, Equivalence of Gibbs and equilibrium states for homeomorphisms satisfying expansiveness and specification, *Comm. Math. Phys.* **148**(1) (1992), 155–167.
[22] F. R. Hertz, M. A. R. Hertz and R. Ures, Accessibility and stable ergodicity for partially hyperbolic diffeomorphisms with 1D-center bundle, *Invent. Math.* **172** (2008), 353–381.
[23] F. R. Hertz, M. R. Hertz and R. Ures, A survey of partially hyperbolic dynamics, in G. Forni, M. Lyubich, C. Pugh and M. Shub (eds.) *Partially Hyperbolic Dynamics, Laminations and Teichmüller Flow* (Fields Institute Communications) vol. **51** (American Mathematical Society, 2007), 35–88.
[24] M. Hirsch, C. Pugh and M. Shub, *Invariant Manifolds* (Lect. Notes in Math.) vol. **583** (Springer Verlag, 1977).
Equilibrium states for center isometries

[25] A. Katok, Smooth non-Bernoulli K-automorphisms, Invent. Math. 61(3) (1980), 291–299.
[26] A. Katok and R. J. Spatzier, Invariant measures for higher-rank hyperbolic abelian actions, Ergod. Theor. Dyn. Syst. 16(4) (1996), 751–778.
[27] F. Ledrappier, Mesures d’équilibre d’entropie complètement positive, in Systèmes dynamiques II - Varsovie (Astérisque) no. 50 (Société mathématique de France, 1977).
[28] F. Ledrappier and J. M. Strelcyn, A proof of the estimation from below in Pesin’s entropy formula, Ergod. Theor. Dyn. Syst. 2 (1982), 203–219.
[29] F. Ledrappier and L.-S. Young, The metric entropy of diffeomorphisms. I. Characterization of measures satisfying Pesin’s entropy formula, Ann. Math. 122 (1985), 509–539.
[30] R. Leplaideur, Local product structure for equilibrium states, Trans. Amer. Math. Soc. 352(4) (2000), 1889–1912.
[31] X. Li and W. Wu, Bernoulli property of equilibrium states for certain partially hyperbolic diffeomorphisms, J. Dyn. Differ. Equ. (2021).
[32] G. A. Margulis, On Some Aspects of the Theory of Anosov Systems (Springer, 2004).
[33] M. Misiurewicz, Topological conditional entropy, Stud. Math. 55(2) (1976), 175–200.
[34] D. Ornstein and B. Weiss, Geodesic flows are Bernoullian, Isr. J. Math. 14(2) (1973), 184–198.
[35] Y. Pesin, Characteristic Lyapunov exponents, and smooth ergodic theory, Russian Math. Surveys 32(4) (1977), 55–114.
[36] Y. Pesin, Lectures on Partial Hyperbolicity and Stable Ergodicity (Zurich Lectures in Advanced Mathematics) (European Mathematical Society, 2004).
[37] Y. B. Pesin and Y. G. Sinai, Gibbs measures for partially hyperbolic attractors, Ergod. Theor. Dyn. Syst. 2(3–4) (1982).
[38] J. Plante, Anosov flows, Am. J. Math. 94 (1972), 729–754.
[39] M. Pollicott and C. P. Walkden, Livsic theorems for connected Lie groups, Trans. Amer. Math. Soc. 353(7) (2001), 2879–2895.
[40] C. Pugh and M. Shub, Ergodicity of Anosov actions, Invent. Math. 15 (1972), 1–23.
[41] C. Pugh and M. Shub, Stable ergodicity and julienne quasi-conformality, Journal of the European Mathematical Society 2(1) (2000), 1–52.
[42] C. Pugh, M. Shub and A. Wilkinson, Hölder foliations, Duke Math. J. 86(3) (1997), 17–546.
[43] M. Ratner, Markov partitions for anosov flows on n-dimensional manifolds, Isr. J. Math. 15(1) (1973), 92–114.
[44] M. Ratner, Anosov flows with Gibbs measures are also Bernoullian, Isr. J. Math. 17(4) (1974), 380–391.
[45] V. Rohlin, On the Fundamental Ideas of Measure Theory, Transl. Amer. Math. Soc. 10 (1962), 1–52.
[46] D. Ruelle, A measure associated with Axiom-A attractors, Am. J. Math. 98(3) (1976), 619.
[47] Y. Sinai, Markov partitions and C-diffeomorphisms, Funct. Anal. Appl. 2(1) (1968), 61–82.
[48] Y. G. Sinai, Gibbs measures in ergodic theory, Russ. Math. Surv. 27(4) (1972), 21–69.
[49] R. Spatzier and D. Vischer, Equilibrium measures for certain isometric extensions of Anosov systems, Ergod. Theor. Dyn. Syst. 38(3) (2016), 1154–1167.
[50] P. Walters, A variational principle for the pressure of continuous transformations, Am. J. Math. 97(4) (1975), 937.