Determination of pore compressibility and geological reserves using a new form of the flowing material balance method

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ABSTRACT

Pore compressibility is an important parameter in reservoir engineering. However, its variation from laboratory core analysis or logging data can be large. Moreover, laboratory core analysis cannot identify the influence of macroscopic fractures on pore compressibility. The geological reserves obtained with the commonly used flowing material balance (FMB) method are significantly impacted by the accuracy of the pore compressibility. Therefore, a new form of the FMB method is proposed in this study which can determine the pore compressibility and geological reserves at the same time. For gas wells, the new method uses the material balance equation and the FMB equation including the pore compressibility. For oil wells, new forms of the material balance equation and the FMB equation were established which have the same form as the corresponding equations for gas wells. A new linear expression of the material balance equation is employed for the analysis. Simulation results indicate that the new method can provide more precise predictions of both the pore compressibility and the geological reserves. Furthermore, the new method also considers the influence of formation fractures because it uses well production data. Sensitivity analysis indicates that the error in the pore compressibility has a significant influence on the determination of the geological reserves.

1. Introduction

Pore compressibility is the change in rock pore volume with varying pore pressure, and it is a fundamental parameter of the flow equations for porous media. Pore compressibility is used in well testing, rate transient analysis, material balance, and reservoir simulations (Iwere et al., 2002; Haynes et al., 2008; Tønnesen and Miskimins, 2011; Lan et al., 2017). In 1953, Hall (1953) developed an empirical chart for pore compressibility with porosity from experimental results of limestone and sandstone cores. Later, the compressibility of different types of sandstone, carbonate, and consolidated and unconsolidated rocks was also investigated (Newman, 1973; Pauget et al., 2002; Jalalah, 2006a, 2006b; Zaki et al., 1995; Chertov and Suarez-Rivera, 2014; Oliveira et al., 2016).

It has been determined that pore compressibility is influenced by the stress state, stress path (Von Gonten and Choudhary, 1969; Lachance and Andersen, 1983; Hettema et al., 2000; Yi et al., 2005; Carvajal et al., 2010), and fluid properties (Carles and Lapointe, 2005). In addition to the direct measurement method for pore compressibility, many indirect evaluation methods have also been proposed which relate the pore compressibility to other mechanical parameters (Sampath, 1982; Zimmerman, 1991; Bai et al., 2010; Saxena, 2011; Hettema et al., 2013; Zeng and Wang, 2017). Using these methods, pore compressibility can be evaluated from core analysis or logging data (Khatckshian, 1996; Seehong et al., 2001; Wofl et al., 2005; Oliveira et al., 2014). Several other evaluation methods have also been proposed. For example, Ling et al. (2014) and He et al. (2016) developed a method to determine pore compressibility through permeability experiments. Siddiqui et al. (2010) used computed tomography (CT) scanning to evaluate the pore compressibility.

At this point, pore compressibility is mainly investigated using core analysis, empirical equations, and logging data. However, the experimental determination of compressibility faces the problem of heterogeneity, and cores cannot reflect the influence of macroscopic fractures. Although logging data describes a larger sample of the reservoir, it still only represents the properties of the volume near the well. To obtain a parameter that reflects the average property of the well drainage volume, a new evaluation method for pore compressibility is needed. The

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feedback control methods can be used to investigate the spatial variation of reservoir state and properties, but the algorithms are complicated (Narasingam et al., 2018; Siddhamshetty and Kwon, 2018).

Production data reflects the average properties of the well drainage volume, and it is an important input parameter for the flowing material balance (FMB) method that is commonly used to evaluate geological reserves. In fact, this method obtains the product of geological reserves and pore compressibility by linear fitting, in which the pore compressibility plays an important role. Therefore, the pore compressibility is critical for accurate evaluation of geological reserves (see section 5.1 for details). In this study, a new method to determine the pore compressibility is proposed based on the FMB method in order to obtain more accurate evaluation of geological reserves.

2. FMB method

2.1. FMB equation for gas wells

The FMB equation for gas reservoirs used in this study is very similar to that reported in the literature; however, the proposed FMB equation for oil reservoirs is quite different from that in the literature. For completeness of the discussion and to facilitate understanding of the FMB equation for oil reservoirs proposed in this paper, the derivation of the FMB equation for gas reservoirs is also presented in detail. In the literature, pore compressibility and irreducible water saturation are neglected in the FMB equation for gas reservoirs (Matter and McNeil, 1998; Sun, 2015). In this study, an equation considering the pore compressibility is derived. For a closed dry gas reservoir with irreducible water, the material balance equation is as follows (Dake, 2004):

\[
\frac{dG_B}{dt} = (G - G_e)B_g + GB_e \left( \frac{C_w S_{wi} + C_i}{1 - S_{wi}} \right) \frac{dp}{dt}
\]

where

\[G = \frac{G_p B_g}{B_e - B_g} + B_e \left( \frac{C_w S_{wi} + C_i}{1 - S_{wi}} \right) \frac{dp}{dt}
\]

where

\[B_e = \frac{p_e Z_e T}{p_{e,sc} T_{e,sc}} \quad B_g = \frac{p_g Z_g T}{p_{g,sc} T_{e,sc}} \]

in which \(T\) is the formation temperature (K), \(T_{e,sc}\) is the temperature at the standard condition (K), \(p_{e,sc}\) is the pressure at the standard condition (MPa), \(Z_g\) is the gas deviation factor, \(Z_e\) is the initial formation pressure, \(p_i\) is the formation pressure (MPa), and the subscript \(sc\) indicates the standard condition.

The effective compressibility is defined as follows:

\[C_i = \frac{C_w S_{wi} + C_i}{1 - S_{wi}}
\]

Eq. (5) reflects the effect of the compressibility of irreducible water, and it would be the pore compressibility when there is no water. Substituting Eqs. (4) and (5) into Eq. (3), the following expression can be obtained:

\[\frac{1 - \frac{C_e}{G} B_e}{Z_i} = \frac{P}{Z} (1 - C_i \frac{dp}{dt})
\]

Taking the derivative of the two sides of Eq. (6) with respect to time yields the following:

\[q = -\frac{G Z_p}{Z_p} \left[ C_e \left( 1 - \frac{C_e}{G} \frac{dp}{dt} \right) + C_i \right] \frac{dp}{dt} = -\frac{G Z_p}{Z_p} \left( 1 - S_{wi} \right) C_i \frac{dp}{dt}
\]

where \(q\) is the gas production rate (m³/s), \(t\) is the time (s), \(C_e\) is the gas compressibility (MPa⁻¹), and \(p\) is the gas density (kg/m³). The total compressibility is expressed as follows:

\[C_i = C_w S_{wi} + C_j (1 - S_{wi}) - C_e (C_w S_{wi} + C_j) \frac{dp}{dt}
\]

The gas compressibility can be expressed as follows:

\[C_e = \frac{1}{\rho} \frac{dp}{dt} = \frac{ZRT}{pM_g} \frac{dp}{dt} = Z \frac{d}{p} \left( \frac{P}{Z} \right)
\]

The following real gas state equation is used in Eq. (9):

\[\rho = \frac{pM_g}{ZRT}
\]

where \(M_g\) is the gas molecular molar mass (kg/mol), and \(R\) is the universal gas constant, 8.314 J/(mol·K).

The normalized pseudo-pressure can be defined as follows:

\[P_i = \left( \frac{\mu_i Z_i}{P} \right) \int^t_0 \frac{P}{\mu_i Z_i} \frac{dp}{dt} \]

where \(\mu_k\) is the gas viscosity (Pas).

The material balance pseudo-time is defined as follows:

\[t_{mb} = \frac{\left( \mu_i Z_i \right) \int^t_0 \frac{P}{\mu_i Z_i} \frac{dp}{dt}}{q}
\]

Substituting Eq. (7) and the normalized pseudo-pressure definition in Eq. (11) into the MB pseudo-time definition in Eq. (12) yields the following:

\[t_{mb} = \frac{G}{q(1 - S_{wi})} \left( \frac{\mu_i Z_i}{P} \right) \int^t_0 \frac{P}{\mu_i Z_i} \frac{dp}{dt} = \frac{GC_i}{q(1 - S_{wi})} \left( \rho_i - p_i \right)
\]

That is:

\[\frac{P_i - P_{e,sc}}{q} = \frac{t_{mb}(1 - S_{wi})}{GC_i}
\]

Considering the formation irreducible water, the continuity equation describing the flow in porous media for gas reservoir is as follows:

\[\frac{\partial (\phi \rho \phi_e)}{\partial t} + V (\rho V) = 0
\]

where

\[\phi_e = \phi [1 - S_{wi} - (C_w S_{wi} + C_i) \Delta p]
\]

\[V = -\frac{K_v}{\phi_e}
\]

in which \(\phi_e\) is the effective porosity (%), \(V\) is the flow velocity in porous media (m/s), \(K_v\) is the permeability (m²), and \(\phi_e\) is the initial porosity (%).

Substituting Eqs. (10) and (17) into Eq. (15) yields the following:

\[V \left( \frac{pM_g}{ZRT \mu_i} \right) = \frac{\partial}{\partial t} \left( \phi \frac{pM_g}{ZRT} \right)
\]

Assuming the formation is isothermal, Eq. (18) becomes

\[V \left( \frac{p M_g Z_i}{ZRT \mu_i} \right) = \frac{\partial}{\partial t} \left( \phi \frac{p M_g}{Z} \right)
\]

Assuming the permeability, \(K\), is constant, and using the definition of normalized pseudo-pressure in Eq. (11), the left side of Eq. (19) becomes
Using Eq. (10) and the definitions of the total compressibility in Eq. (8), the normalized pseudo-pressure in Eq. (11), and the material balance pseudo-time in Eq. (12), the right side of Eq. (19) can be expressed as follows:

\[
\frac{\partial \frac{p}{Z}}{\partial t} = \frac{\partial \frac{p}{Z}}{\partial t} = \frac{\partial \frac{p}{Z}}{\partial t} = \frac{\partial \frac{p}{Z}}{\partial t} \tag{20}
\]

Using Eqs. (20) and (21), Eq. (19) can be written as follows:

\[
V^3 p^3 = \left( \frac{\phi \mu C_i}{K} \right) \beta_{p} \frac{\partial \rho}{\partial \phi} \tag{22}
\]

Equation (22) has the same form as the seepage equation for a weak compressible fluid. For a gas well with a constant production rate, when the reservoir is in pseudo-steady state, the following expression can be applied (Sun, 2015):

\[
\frac{p}{q} = \left( \frac{\phi \mu C_i}{K} \right) \beta_{p} = \left( \frac{\phi \mu C_i}{K} \right) \beta_{p} \tag{23}
\]

where \(p\) is the bottom hole pressure (MPa), \(p\) is the reservoir pressure (m), \(A\) is the reservoir area (m²), \(C_o\) is the shape factor (Dietz, 1965), \(r\) is Euler's constant, \(r_e\) is the effective well radius (m), \(r_w\) is the well radius (m), and \(s\) is the skin factor.

Using Eqs. (14) and (23) yields the following:

\[
\frac{p}{q} = \left( \frac{\phi \mu C_i}{K} \right) \beta_{p} \beta_{p} \tag{24}
\]

Equation (24) is the gas well FMB equation considering the pore compressibility.

### 2.2. FMB equation for oil wells

Pore compressibility cannot be determined by the conventional FMB method for oil wells owing to the oversimplification in the common material balance equation, i.e., assuming the oil formation volume factor is constant. When the oil formation volume factor is variable, a new form of the material balance equation and the FMB equation thus need to be established.

For a closed unsaturated oil reservoir without producing water, it holds that (Dake, 1978):

\[
\frac{p}{q} = \left( \frac{\phi \mu C_i}{K} \right) \beta_{p} \beta_{p} \tag{25}
\]

where \(p\) is the oil initially in place (m³), \(N_i\) is the cumulative producing gas (m³), \(B_i\) is the original oil formation volume factor (m³/m³), \(B_i\) is the oil formation volume factor (m³/m³), \(N_o\) is the cumulative oil production (m³), \(\Delta p = p_i - p_{i-1}\) is the formation pressure drop (MPa).

Using Eq. (4), Eq. (25) can be written as follows:

\[
\frac{1}{B_i} (1 - C_i \Delta p) = \frac{1}{B_i} \left( \frac{1}{1 - S_{wi}} \right) \tag{26}
\]

This equation has the same form as the gas reservoir material balance in Eq. (6). Taking the derivative of both sides of Eq. (26) with respect to time yields the following expression:

\[
\frac{1}{B_i} \left( \frac{1}{1 - C_i \Delta p} \right) \left( 1 - \frac{\Delta p}{B_i} \right) = \frac{1}{B_i} \left( \frac{1}{1 - C_i \Delta p} \right) \tag{27}
\]

The right side of Eq. (27) can be expressed as follows:

\[
\frac{1}{B_i} \left( \frac{1}{1 - C_i \Delta p} \right) \left( 1 - \frac{\Delta p}{B_i} \right) = \frac{1}{B_i} \left( \frac{1}{1 - C_i \Delta p} \right) \tag{28}
\]

Therefore, Eq. (27) can be written as the following:

\[
q = - \frac{dN_o}{dt} \left( \frac{1}{N_o} \right) \left( \frac{1}{1 - S_{wi}} \right) \tag{29}
\]

where \(C_i^* = (1 - S_{wi}) C_i - (C_o S_{wi} + C_f) C_f \Delta p + C_o S_{wi} + C_f \)

For oil reservoirs, using Eq. (16), the first term of the continuity equation in Eq. (15) becomes the following:

\[
\frac{d \rho_{p}}{dt} = \frac{\rho_{p}}{K} \frac{d \rho_{p}}{dt} \tag{30}
\]

The second term of the continuity equation given in Eq. (15) is as follows:

\[
V \left( \frac{\rho V}{p} \right) = \frac{1}{K} \frac{d \rho_{p}}{dt} \left( \frac{1}{\rho_{p}} \right) \tag{31}
\]

The normalized pseudo-pressure for oil wells is defined as follows:

\[
p_{p}^* = \frac{p_{p} K}{B_i \rho_{p}} \frac{1}{B_i \rho_{p}} \tag{32}
\]

The material balance pseudo-time for oil wells is defined as:

\[
t_{p}^* = \frac{\rho_{p} C_i^*}{q} \frac{1}{B_i \rho_{p}} \tag{33}
\]

Using Eqs. (31)–(34), the governing equation of the flow in porous media for oil wells is as follows:

\[
V^3 p_{p}^* = \left( \frac{\phi \mu C_i^*}{K} \right) \beta_{p} \beta_{p} \tag{35}
\]

Equation (35) has the same form as Eq. (22), while Eq. (26) has the same form as Eq. (6). Therefore, the same form of the FMB equation as in Section 2.1 can be obtained.

### 3. Evaluation method for pore compressibility and geological reserves

#### 3.1. Proposed new method

When the total compressibility and initial water saturation is known, the gas initially in place (GiHP) can be determined by linear regression using the FMB equations. If the pore compressibility is unknown, it cannot be directly obtained with the commonly used equations. As the FMB equations for oil and gas wells have the same form, the gas well equation is taken as an example. The following are first defined:

\[
\varphi = \frac{p_i}{p_i} \tag{36}
\]

\[
X_{G} = \varphi G_{p} Y_{p} = \frac{1 - \varphi}{\varphi \Delta p} \tag{37}
\]

Then, Eq. (6) can be written as follows:
For oil wells, only a geological reserve needs to be assumed. For the new method, both the FMB equations for oil and gas wells need to assume a geological reserve and pore compressibility, and these two parameters are iteratively solved for simultaneously. Furthermore, the conventional FMB equation for oil wells uses pressure and time, while the new method uses pseudo-pressure and material balance pseudo-time. Another small difference is that the conventional FMB equations do not explicitly consider water saturation.

4. Gas and oil reservoir cases

4.1. Gas reservoir case

An example of the production data for a gas well is simulated in this section. The simulation method is presented in the appendix. The simulation parameters are listed in Table 2. The actual GIIP calculated using the volume method is \( G = \phi(1-S_{wi})h_B \rho_f = 1.373 \times 10^9 \text{ m}^3 \). The simulated results are shown in Fig. 2.

Assuming the pore compressibility \( G_i = 1.0 \times 10^{-3} \text{ MPa}^{-1} \), and the GIIP \( G = 3.0 \times 10^7 \text{ m}^3 \), the normalized pseudo-pressure and material balance pseudo-time were calculated using the simulated production data. This data was then fitted with the line \( \Delta p_p/q - (1-S_{wi})h_{ca} \) and the results are shown in Fig. 3. Next, the computed \( b_{p,ca} \) was used to calculate the average formation pressure, after which \( (1-\phi)/\phi \Delta p_p \) and \( G_x/\phi \Delta p_p \) were computed and fitted, as shown in Fig. 4. The results are \( C_e = 2.59 \times 10^{-3} \text{ MPa}^{-1} \) and \( G = 1.368 \times 10^8 \text{ m}^3 \). Using Eq. (5), the pore compressibility \( C_i = 2.02 \times 10^{-2} \text{ MPa}^{-1} \). The calculations in the first iteration are listed in Table 3. The results show that the GIIP and pore compressibility computed by the proposed new method are close to the actual values. If more accurate results are required, the iterations can be continued. If a pore compressibility \( C_i = 1.0 \times 10^{-3} \text{ MPa}^{-1} \) is used, the resulting GIIP calculated using the conventional method is \( 1.733 \times 10^9 \text{ m}^3 \), which represents an error of 26.2%.

4.2. Oil reservoir case

An example of the production data for an oil well is simulated in this section. The simulation parameters are listed in Table 4. The actual oil initially in place (OIIP) calculated with the volume method is \( N = \phi(1-S_{wi})h_B \rho_f = 1.003 \times 10^8 \text{ m}^3 \). The simulated results are shown in Fig. 5.

Assuming a pore compressibility \( C_i = 5.0 \times 10^{-4} \text{ MPa}^{-1} \) and an OIIP \( N = 2.0 \times 10^9 \text{ m}^3 \), the normalized pseudo-pressure and material balance pseudo-time were calculated using the simulated production data. This data was then fitted with the line \( \Delta p_p/q - (1-S_{wi})h_{ca} \) and the results are shown in Fig. 6. Next, the computed \( b_{p,ca} \) was used to calculate the average formation pressure, after which \( (1-\phi)/\phi \Delta p_p \) and \( N/\phi \Delta p_p \) were then computed and fitted, as shown in Fig. 7. The results are \( C_e = 1.36 \times 10^{-3} \text{ MPa}^{-1} \), and \( N = 1.004 \times 10^8 \text{ m}^3 \). Using Eq. (5), the pore compressibility \( C_i = 1.003 \times 10^{-3} \text{ MPa}^{-1} \). The first iteration calculation results are listed in Table 5, and demonstrate that the OIIP and pore compressibility computed using the proposed new method are close to the actual values. If more accurate results are required, the iterations can be continued. If a pore compressibility \( C_i = 5.0 \times 10^{-3} \text{ MPa}^{-1} \) is used, the resulting OIIP calculated using the conventional method is \( 1.23 \times 10^8 \text{ m}^3 \), which represents an error of 22.8%.

As it can be seen from the above cases, the proposed method has high computational efficiency. Although it is not mathematically proved that the method can obtain a global optimum, experience and geological knowledge are beneficial for giving appropriate initial values. When the guess value is far from the true one, the pseudo-steady state segment becomes a curve. These can help to get reasonable values in practice.

![Fig. 1. Workflow of the proposed new FMB method.](image-url)
5. Discussion

5.1. Influence of pore compressibility

If the pore compressibility is not accurate, the geological reserve determined using the FMB method will not be accurate either. Based on the parameters for the examples in Section 4, the error in the geological reserve with the pore compressibility error is analyzed in Figs. 8–11 under different formation pressures, temperatures, pore compressibilities, and irreducible water saturations. The pore compressibility ratio is defined as the ratio of the pore compressibility used in the FMB method to the actual pore compressibility. The results show that the influence of the pore compressibility error on the geological reserve increases with the initial formation pressure, irreducible water saturation, and pore compressibility, and decreases with the formation temperature. The formation temperature and irreducible water saturation have little impact on the error in the geological reserves. If the pore compressibility differs from the actual value by an order of magnitude, an error of approximately 20–80% in the geological reserves may result.
Therefore, the pore compressibility has a significant impact on the geological reserves obtained using the FMB method, particularly when the formation pressure is very high. Because the oil compressibility is small relative to the gas compressibility, and is closer to the pore compressibility, the pore compressibility has a more significant influence on the evaluated geological reserves of oil reservoirs.

### Table 3
First iteration of the computation for the gas reservoir.

| Assumption | $C_i (\text{MPa}^{-1})$ | $G (\text{m}^3)$ | $b_{i,\text{ps}} (\text{Pa}/(\text{m}^3/\text{d}))$ | $C_r (\text{MPa}^{-1})$ | Iteration results |
|------------|-------------------------|------------------|---------------------|------------------------|-------------------|
| $1.0 \times 10^{-3}$ | $3.0 \times 10^9$ | 6.5274 | 2.76 | $2.59 \times 10^{-3}$ | $2.02 \times 10^{-3}$ | $1.368 \times 10^9$ |

### Table 4
Oil reservoir simulation parameters.

| Reservoir parameter | Value |
|---------------------|-------|
| Reservoir thickness (m) | 20 |
| Permeability (mD) | 10 |
| Initial pressure (MPa) | 30 |
| Irreducible water saturation | 0.2 |
| Porosity | 10% |
| Formation thickness (m) | 60 |
| Skin factor | 0 |
| Well radius (m) | 0.1 |
| Pore compressibility (MPa$^{-1}$) | $1.0 \times 10^{-3}$ |
| Formation water specific volume | 1.008 |
| OIIP (m$^3$) | $1.003 \times 10^6$ |

### 5.2. Applicability

In the derivation, the permeability is assumed to be constant, but this assumption is unnecessary in practical. The second term on the right side of Eq. (24) is determined by the material balance equation and is not affected by changes in permeability. The first item on the right side is determined by the permeability of the reservoir, the reservoir geometry shape and the location of the well. The specific form would be obtained based on the permeability spatial distribution. However, as it can be seen from the workflow in Fig. 1, the specific expression of $b_{i,\text{ps}}$ is not required. Therefore, the proposed method is also applicable to cases with spatial variation of permeability. However, it should be pointed out that the pore compressibility obtained in this method is the average within the well drainage volume.

The new method is proposed for the single-phase flow of dry gas reservoirs and unsaturated oil reservoirs that do not produce water. Only the elastic expansion and rock pore compaction are considered as driving mechanisms. In practice, oil or gas well production may be a multiphase flow, e.g., a water/oil flow, water/gas flow, or oil/gas flow. Actual reservoir production may also have other driving mechanisms, such as water drive, dissolved gas drive, and gas top drive. For weak consolidated rocks, rock compaction is strong, and the formation permeability will change significantly with a decrease in pressure. Here, a constant permeability is assumed during the production process. Hence, the proposed method is only applicable for analysis of a short production period of consolidated reservoirs. Therefore, there is still a need to develop additional methods that are suitable for these situations.
6. Conclusions

Pore compressibility determined by core analysis and logging data is poorly representative, and thus cannot reflect the overall reservoir properties. This uncertainty in the pore compressibility can result in significant error in the evaluation of geological reserves using the FMB equation. In this paper, a new FMB equation considering pore compressibility was established for gas wells. For oil wells, the commonly used material balance equation and FMB equation were transformed into the same form as these for gas wells. Based on the FMB method, a new linear regression equation for the material balance equation was proposed, which can be used to obtain the geological reserves and pore compressibility at the same time. The results of simulated example cases indicate that the proposed method can provide more accurate values for the geological reserve and pore compressibility. Impact factor analyses indicate that the error in the pore compressibility has a significant influence on the geological reserve calculated using the FMB method.

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Appendix. Simulation method

For simplicity, only an oil or gas reservoir with a circular boundary and a centered wellbore is considered. The oil production can be described by the governing equations in a cylindrical coordinate system as follows:

\[ \frac{C_r^2 \phi}{B_o} \frac{\partial p}{\partial t} = \frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{k}{\mu_o} \frac{\partial p}{\partial r} \right) \]  
(A-1)

The initial condition is as follows:

\[ p(r, 0) = p_i \]  
(A-2)

The interior boundary condition is defined as follows:

\[ 2 \pi r_n \frac{k}{\mu_o} \frac{\partial p}{\partial r} \bigg|_{r=r_n} = C \frac{\partial p}{\partial t} + B_o q \]  
(A-3)

The outer boundary condition is given by the following:

\[ \frac{\partial p}{\partial r} \bigg|_{r=r_o} = 0 \]  
(A-4)

In addition:

\[ p|_{t=n} = p_i + \frac{q \mu_o B_o}{2 \pi h} \]  
(A-5)

where C is the wellbore storage coefficient (m³/Pa). For gas reservoirs, C₀, B₀, and µ₀ are replaced with Cᵣ, Bᵣ, and µᵣ, respectively, in the above formulae.

If \( r = r_i e^s \), the governing equation in Eq. (A-1) and boundary conditions in Eqs. (A-3) to (A-5) can be rewritten, respectively, as follows:

\[ r_i^2 e^{2s} \frac{C_r^2 \phi}{B_o} \frac{\partial p}{\partial t} = \frac{1}{\partial x} \left( \frac{k}{\mu_o} \frac{\partial p}{\partial x} \right) \]  
(A-6)

\[ 2 \pi r_i h k \frac{\partial p}{\partial x} \bigg|_{x=0} = C \frac{\partial p}{\partial t} + B_o q \]  
(A-7)

\[ \frac{\partial p}{\partial x} \bigg|_{x=\ln(r_i/r_o)} = 0 \]  
(A-8)

For convenience, the following are defined:

\[ A = r_i^2 e^{2s} \frac{C_r^2 \phi}{B_o}, B = \frac{k}{r_i \mu_o}, E = \frac{2 \pi r_i h k}{r_i e^{2s} \mu_o} \]  
(A-9)

Dividing the reservoir into N segments along the radial direction, and taking the equidistant grid \( \Delta x = \ln(r_i/r_o)/N \), Eqs. (A-6)–(A-8) can be discretized into the following forms, respectively:

\[ A_i \left( \frac{P_{i+1}^{(n+1)} - P_i^{(n+1)}}{\Delta t} \right) = \frac{1}{\Delta x} \left( B_i^o \left( \frac{P_{i+1}^{(n+1)} - P_j^{(n+1)}}{\Delta x_j / 2} - \frac{P_{i+1}^{(n+1)} - P_{i-1}^{(n+1)}}{\Delta x_{i-1} / 2} \right) \right) \]  
(A-10)

\[ E_i \left( \frac{P_{i+1}^{(n+1)} - P_i^{(n+1)}}{\Delta X_0} \right) = C \phi \left( \frac{P_{i+1}^{(n)} - P_i^{(n)}}{\Delta t} \right) + B_o q^{(n)} \]  
(A-11)

\[ \frac{P_{N+1}^{(n+1)} - P_{N}^{(n+1)}}{\Delta X_N} = 0 \]  
(A-12)

where \( \Delta t \) is the time step, superscript \( n \) denotes the \( n \)th time step, and \( s \) denotes the \( s \)th iteration of a time step. Because the coefficients \( A, B, C, \) and \( E \) are all functions of pressure, and the difference equations are nonlinear, in order to linearly solve the difference equation, the values of the \( s \)th iterative step are used for \( A, B, C \) and \( E \) in the \( (s+1) \)th iteration of each time step. Thus, the difference equations can be solved iteratively.

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