Early-Stage Planning of Switched-Capacitor Converters in a Heterogeneous Chip

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ABSTRACT The switched-capacitor converter (SCC) has been widely used for voltage regulation in multicore chips, where energy efficiency is the major concern. However, as the overhead to integrate SCCs in a chip is non-negligible, the SCCs could not be overused. Hence in this paper, we propose an early stage SCCs planning framework to obtain the SCC supply scheme together with the optimized Metal-Insulator-Metal (MIM) capacitance allocation and converter ratio selection for each SCC when the given number of SCCs is less than the number of cores. Besides, our method could also explore to find the best number of used SCCs for a given chip. The experiments show the results of our SCC planning methods.

INDEX TERMS Energy efficiency, switched-capacitor converter, multi-core, MIM capacitance.

I. INTRODUCTION

By fully exploiting the unique advantages of different types of cores (CPU, GPU, accelerators etc.), a state-of-art heterogeneous multi-core chip can achieve both powerful performance and high energy efficiency [1]–[6]. For example, the Apple A12 processor [5] has two high-performance CPU cores, four energy-efficient CPU cores, four GPU cores and eight neural engine cores; The Kirin 980 processor [6] has two high-performance CPU cores, two medium-performance CPU cores, four efficiency CPU cores, one GPU core and two neural processor cores. The heterogeneous chip is typically divided into several power domains [7], and each domain can be powered individually by the integrated on-chip voltage regulators such as switching-capacitor converters (SCCs) [8], [9], inductive switching regulators [7], [10] and LDOs [11], [12] (see Fig. 1 for an example).

Table 1 shows the comparison of different types of voltage regulators. The main problem with inductive switching regulator is that the inductor could not easily be integrated on the chip, and is usually manufactured on the package. The SCC has advantages such as wide output voltage, high energy conversion efficiency and high power density. Therefore, it has been widely studied and applied in recent processors [13]–[15].

Fig. 2 shows a 3:1 step-down SCC where a high input voltage could be converted to a lower output voltage by a series of flying capacitors $C_{sw}$ and switches $\phi_1/\phi_2$. During phase $\phi_1$, the flying capacitors $C_{sw}$ gets charged by the input power supply and delivers power to the output during phase $\phi_2$, where $\phi_1$ and $\phi_2$ are non-overlapping clock signals with...
TABLE 1. The comparison of different voltage regulators. "Step up/down" means output voltage is higher or lower than the input source voltage (i.e., Vdd).

| Electronic Element | LDO | Inductive Switching Regulator | SCC |
|--------------------|-----|-------------------------------|-----|
| Step Up/Down?      | No/Yes | No/Yes                       | Yes/Yes |
| On-chip Integration| Easy     | Hard                         | Easy |
| Design Complexity  | Low      | Low                         | High |
| Energy Efficiency  | Low      | High                        | High |

FIGURE 2. A 3:1 SCC and its output voltage ripple ΔV caused by the two-phase operation.

a frequency of $f_{sw}$. The charging and discharging behavior of the flying capacitors result in supply voltage ripple ΔV at the output. It should be mentioned that although only a 3:1 SCC is shown in this figure, other conversion ratios could be achieved with different topologies [16].

Energy conversion efficiency is critical for the SCC design [17]–[20]. A lot of prior works have investigated the optimization of the SCC design to achieve better energy efficiency, and have proposed techniques such as tuning the size of flying capacitors, operating frequency and switch width etc. [17], [21]–[26]. However, there are limited works on optimizing the energy efficiency of SCCs in a holistic way in a multi-core chip. In [9], the authors improve the overall energy efficiency of many-core system by dynamically adapting the switching frequency $f_{sw}$ of each SCC to the specific output load. The authors in [26] aim to not only achieve the highest energy efficiency but also suppress supply noise by optimizing the allocation of limited die area between flying capacitance and decoupling capacitance. In [19], the authors propose a system level efficiency model which characterizes the number, size and distribution of the SCCs, and they solve the optimization problem by mathematical optimization methods.

Although SCC is a promising technique for implementing fine-granularity power management in a multicore chip, we should not overuse the SCCs in a given chip since integrating the SCCs in a multicore chip needs the control circuit, the routing resource, the power consumption of clock signals, the chip area and so on [19]. On the other hand, in a heterogeneous multi-core chip, the cores with close voltage demands (i.e., their voltage demands slightly differ) are usually placed together in the physical layout [7]. This implies that theoretically the SCCs in a domain with higher voltage supply can also be shared by the cores in an adjacent domain with slightly lower voltage demand. In this way, we can potentially reduce the number of used SCCs for a given chip. Therefore, in our work, we will explore the best planning strategy of the SCCs in a heterogeneous chip.

More specifically, our work tries to optimize the energy efficiency of a SCC-powered heterogeneous chip from the following two important aspects:

- The SCC supply scheme.
- The capacitance allocation and ratio selection of SCCs.

The energy efficiency of the SCC is related to its switching capacitance and conversion ratio (see Section III). Recently Metal-Insulator-Metal (MIM) capacitors have been utilized as flying capacitors for SCCs [8], [18], [27] (see MIM capacitance in Fig. 1), and more than one conversion ratios are available for a SCC to supply for the loads where the ideal output voltage of the conver-

In Case 1 the SCC2 supplies Core2, Core3 and Core4 simultaneously, the output voltage of SCC2 should be no less than the maximal voltage demand among the three cores (i.e., leading to output 0.90V for all the three cores). Hence in Case 1 the Core2 and Core3 would have an over-supplied voltage which leads to extra power consumption, and the system would have an extra power loss (0.90-0.68)*0.10+(0.90-0.82)*0.30=0.046W (see Section IV-B for details). On the contrary, in Case 2 the extra power loss is (0.68-0.55)*0.08+(0.90-0.82)*0.30=0.0344W.

FIGURE 3. Two cases of SCC supply schemes would lead to different efficiency, which motivates us to propose a smart supply scheme.
TABLE 2. Different capacitance allocation and ratio selection would leads different efficiency (Vdd=1.2V).

| #SC  | Case 1 | Case 2 |
|------|--------|--------|
|      | Csw(nF) | Ratio  | η       | Csw(nF) | Ratio  | η       |
| SC1  | 7       | 2.1    | 75.3%   | SC1     | 3.2    | 81.9%   |
| SC2  | 6       | 4.3    |         | SC2     | 9      | 1.1     |

sion ratio is greater than the demanded voltage. Table 2 shows two cases with different capacitance allocation and conversion ratios for SCCs in Fig. 3. We can see that the energy efficiency is different. Since different capacitance and ratio in each SCC would lead to different power loss with the given SCC loss mechanism (see Section III), capacitance allocation and ratio selection would have effect on the energy efficiency. Hence, given a supply scheme we also need to optimize the capacitance allocation and conversion ratio of the SCCs to improve the efficiency.

Motivated by the aforementioned observations, in this work, we propose an early stage SCCs planning framework to improve the energy efficiency of the multi-core chips when the number of SCCs is less than the number of cores. It is noticed that when the number of SCC equals to the number of cores, each SCC could be used to supply the power for one core by converting the global voltage to a specific demand voltage of the core. In this way, a finest power management is achieved. However, the overhead associated with integrated SCCs (such as control circuit, routing resource) is non-negligible [19]. As a result, if there is limited budget to integrate SCCs, we should integrate less number of SCCs (i.e., the number of SCC is less than the number of cores). The pros in this scenario are that we could reduce the overhead of integrating SCCs, while the cons are that some cores with different demand voltages are supplied by the same SCC outputting the higher demand voltage of cores, there would be some extra power loss due to the over-supply of some cores. And we also provide a method to guide how many SCCs should be used to get the highest efficiency for the system.

The rest of this paper is organized as follows. We formulate the problem in Section II. In Section III, we introduce the basic loss mechanism of SCCs. Then the proposed SCC planning framework - SCC supply scheme and SCC optimization are introduced in Section IV. We then show the experimental results in Section VI. Finally, we make conclusions in Section VII.

In Case 1, the MIM capacitance allocated in each SCC (Csw) is proportional to the area of the cores this SCC supplied, and the selected ratio is the one whose no-load output voltage is minimal but larger than the demand of the supplied cores. According to the SCC loss equation (see Section III-A), the loss would be \( P_{\text{cond}} = P_{\text{acc}} + P_{\text{sw}} = (e_1 \cdot C_{\text{sw,acc}} + \frac{e_2}{C_{\text{sw,acc}}}) + (e_1 \cdot C_{\text{sw,acc}} + \frac{e_2}{C_{\text{sw,acc}}}) \) where \( e_1 \) and \( e_2 \) are the ratio-determined parameters. From this equation, we could see that the ratio-determined parameters would significantly affect the loss model, and after given these \( e_1 \) and \( e_2 \), the capacitance allocated in each SCC would also affect the efficiency. In this situation, the MIM capacitance allocated and the selected ratios in each SCC in Case 1 may not lead to the minimal loss. As a contrast, the MIM capacitance allocation and ratio selection with our proposed method (introduced in Section IV-C) would have a higher efficiency.

II. PROBLEM FORMULATION

In the literature [7], Intel has proposed the one regulator per core scheme to achieve the finest power management for a given chip. However, considering the overhead associated with distributing a large number of regulators over the chip, in this work, we focus on the scenario that the available SCCs are typically limited (less than the number of cores).

The problem can be formulated as follows: Given

1) the layout of a \( M \)-core heterogeneous chip, 2) the minimal supply voltage and maximal demand current of each core, 3) the available number of SCCs \( \hat{M} (1 \leq \hat{M} < M) \), 4) the total MIM capacitance for the flying capacitors of SCCs and 5) the available ratios for one SCC, our work attempts to maximize the overall energy efficiency of the power supply system by finding

1) the best supply scheme for a specified \( \hat{M} \) SCCs, together with 2) the amount of flying capacitance and the conversion ratio of each of the \( \hat{M} \) SCCs.

In our work, we also explore the number \( \hat{M} (1 \leq \hat{M} < M) \) to find the best number of SCCs for the given \( M \)-core chip.

It’s noticed that as the MIM capacitors are designed and used as the flying capacitors in SCCs, works like [18], [28] have studied the design techniques to optimize the performance and quality of MIM capacitors, such as optimizing the ESR (i.e., Equivalent Series Resistance). Hence, we don’t take the ESR issue into consideration in this paper. Instead, we use the optimal parameter like frequency shown in [18] to significantly reduce the ESR’s effect on the MIM capacitors.

III. ANALYSIS OF THE INHERENT POWER LOSSES OF SCCs

In this section, we will briefly introduce and analyse the loss mechanism of SCCs, and then further discuss the ratios and flying capacitance used in SCCs.

A. THE LOSS MECHANISM OF THE SCCS

The switched-capacitor converter would have several inherent losses when delivers energy from the input side to the output side. These non-negligible power losses include switching loss caused by charging flying capacitance, conduction loss caused by driving these switches and load power loss caused by the output voltage ripple. Each kind of the losses could be seen in Fig. 4, and all of these are explained in the work of [17], [19] and [22]. Our problem formulation in Section IV-C are based on these loss mechanisms. The detailed formulation of these loss mechanisms are introduced in the following.

1) Conduction loss. For a specific SCC topology, when the switches are turned on and the charge would be transferred to the flying capacitors through the switches, and part of the power will be dissipated in the switches [19] as

\[
P_{\text{cond}} = \frac{M_{\text{sw}} I_{\text{out}}^2 R_{\text{on}}}{\sigma \gamma C_{\text{sw,sw}}}
\]  

(1)

Here, \( M_{\text{sw}} \) is the parameter that related with the topology, \( I_{\text{out}} \) is the load current of a SCC and \( R_{\text{on}} \) is the equivalent resistance density of a switch when it is on. \( \sigma \) is a fitting
parameter and $\gamma$ is a topology-dependent parameter. $f_{sw}$ is the switching frequency of the SCC.

(2) Gate-drive loss. When the switches are turned on or off, the gate capacitors of these transistors would be charged or discharged. The energy lost here in each cycle [17] is

$$P_{\text{gate}} = N_{\text{phase}} \cdot N_{sw} \cdot (C_{\text{gate}} \cdot W_{sw}) \cdot V_{dd}^2.$$ 

Since $W_{SW}$ is the cumulative width of switches that are turned ON/OFF in this period, it is also proportional to the frequency $f_{sw}$ and could be written as [19] $W_{sw} = \sigma \gamma f_{sw} C_{sw}/N_{\text{phase}}$. As a result, the gate-drive loss is proportional to $f_{sw}^2$.

Hence we have the gate-drive loss

$$P_{\text{gate}} = N_{sw} f_{sw}^2 V_{dd}^2 C_{\text{gate}} \sigma \gamma C_{sw}$$  \hspace{1cm} (2)

where $N_{sw}$ represents the number of switches in a SCC and $C_{\text{gate}}$ is the per-unit-width gate capacitance of the switches.

(3) Load power loss. Due to the voltage ripple of the SCC output voltage, the load power loss [19] is

$$P_{\text{load}} = \frac{1}{2} I_{\text{out}} \Delta V.$$ 

Since the load current of a SCC can be expressed as $I_{\text{out}} = M_{\text{topo}} \cdot f_{sw} \cdot C_{sw} \cdot N_{\text{phase}} \cdot \Delta V$, we could have

$$\Delta V = \frac{I_{\text{out}}}{M_{\text{topo}} f_{sw} N_{\text{phase}} C_{sw}}$$  \hspace{1cm} (3)

where $M_{\text{topo}}$ is topology-dependent and $N_{\text{phase}}$ is the number of interleaving stage in a SCC. Finally, the load power loss could be written as

$$P_{\text{load}} = \frac{I_{\text{out}}^2}{2 M_{\text{topo}} f_{sw} N_{\text{phase}} C_{sw}}$$  \hspace{1cm} (4)

As a result, the inherent power loss of one SCC is

$$P_{SCC} = P_{\text{cond}} + P_{\text{gate}} + P_{\text{load}} = \epsilon_1 \cdot C_{sw} + \epsilon_2$$  \hspace{1cm} (5)

where

$$\epsilon_1 = N_{sw} f_{sw}^2 C_{\text{gate}} \sigma \gamma V_{dd}^2$$  \hspace{1cm} (6)

and

$$\epsilon_2 = I_{\text{out}}^2 \left( \frac{1}{2 M_{\text{topo}} N_{\text{phase}} f_{sw}} + \frac{M_{sw} R_{\text{on}}}{\sigma \gamma f_{sw}} \right)$$  \hspace{1cm} (7)

Here the parameters are divided into three types. 1) Non topology-dependent parameters: $f_{sw}$, $R_{\text{on}}$, $C_{\text{gate}}$, $N_{\text{phase}}$, $V_{dd}$, and $\sigma$, 2) topology-dependent parameters: $N_{sw}$, $M_{\text{topo}}$, $M_{sw}$, and $\gamma$, 3) other parameters: $I_{\text{out}}$ and $C_{sw}$. These parameters show that the power loss is related with the topology of SCCs, such as the switches represented by the parameters of $N_{sw}$ and $W_{sw}$ and the flying capacitors represented by the parameter of $C_{sw}$.

As non topology-dependent parameters such as $f_{sw}$ (see Table 5 in Section VI) are fixed and the load information $I_{\text{out}}$ is also known, we can see the loss mechanisms are only related with the flying capacitance $C_{sw}$ and the topology-dependent parameters (see Table 3) of SCCs.

As a result, two issues (flying capacitance and conversion ratio) could be optimized to improve the conversion efficiency of the SCCs.

### B. THE MIM CAPACITANCE USED IN SCCS

In fully integrated switching-capacitor converters, the flying capacitors could be implemented by the baseline MOS capacitors [29], deep trench capacitors [30], Metal-Oxide-Metal (MOM) capacitors [20] and Metal-Isolator-Metal (MIM) capacitors [8].

For the MOS capacitor, it has large parasitics which will significantly reduce the efficiency of SCC [29] and the leakage issue of MOS capacitor is also serious [31]. The deep trench capacitor is implemented by dry-etching macro pores in silicon and filling the pores with the dielectric and electrode [32]. This technique is not part of baseline CMOS, which leads to much more additional masks and costs [20]. The MOM capacitor (typical density $1.5fF/\mu m^2@65nm$ [33]) is fabricated by the lower metal layers on the chip, resulting in heavy capacitive coupling to the substrate [34]. On the contrary, the MIM capacitor (typical density $1.6fF/\mu m^2@65nm$ [33]) is fabricated between one upper metal layer and one additional metal layer above it, resulting in small capacitive coupling to the substrate [34]. Although the combined capacitors such as MIM and MOS capacitors [13], [35] are used together as flying capacitors in SCCs, in recent high-end processor chips [8], [18], [27] the MIM capacitors are widely used in the SCCs.

As the global resource, the MIM capacitance existing in the top metal layers are shared by all the SCCs in the chip (see Fig. 1). Hence, in our SCC planning method, we should better allocate the MIM capacitance to maximize the total conversion efficiency of SCCs.
In this section, we would show how to do the SCC planning and how to select for the efficiency of all SCCs. As shown in Table 3 and Table 5 we can have a ratio 2:1 is employed to supply to one core, using the parameters in Equation (3). And consequently, this SCC is very large (see Equation (3)). Hence we need to wisely merge the SCCs into M groups with each group supplied by an individual SCC, so that the total extra power loss of each group $P_{\text{extra}} = \sum_{m=1}^{M} P_{\text{extra}}^m$ is minimized to get the highest energy efficiency.

(2) We also need to optimize the flying capacitance and selected ratio for each SCC to minimize the total power loss of each individual SCC $P_{\text{total}}^m = \sum_{l} P_{l}^m$, where $P_{l}^m$ is the power loss of the $m$-th SCC (see Equation (5)).

So our SCC planning tries to minimize these two kind of losses.

**B. STEP 1: GROUPING THE CORES**

It is reasonable that only the cores/groups having a neighbor relationship could be merged into one group, and then can be supplied by one SCC. Hence it is not easy to minimize $P_{\text{total}} = \sum_{m=1}^{M} P_{\text{extra}}^m$ (see Equation (8)) because the physically adjacent location of cores in each group would be the constraint. Therefore we would introduce our greedy approaches (two strategies) to merge the cores into $M$ groups with inducing a decent $P_{\text{total}}$. Our grouping method is similar to the hierarchical/agglomerative clustering methods in unsupervised learning [36], [37].

We could treat each group as one core, and it has a minimum supply voltage $V_{\text{in}}^m = \max(V_1^l, V_2^l, \ldots, V_L^l)$ and the maximum demand current

$$I_{\text{group}}^m = \sum_{l \in \text{Group } m} I_{l}^m$$

In order to represent the adjacent relationship among the cores/groups on a chip and the extra power loss induced by the merging of two adjacent cores/groups, we could use an adjacency graph where the connected nodes $x$ and $y$ represent the adjacency cores/groups, and the weight $w_{x,y}$ between nodes $x$ and $y$ represents the induced extra power loss if these two cores/groups merge. According to Equation (8), the $w_{x,y}$ could be written as

$$w_{x,y} = \begin{cases} (V_{\text{group}}^x - V_{\text{group}}^y) \times I_{\text{group}}^x, & V_{\text{group}}^x > V_{\text{group}}^y \\ (V_{\text{group}}^y - V_{\text{group}}^x) \times I_{\text{group}}^y, & V_{\text{group}}^x \leq V_{\text{group}}^y \end{cases}$$

**C. THE CONVERSION RATIOS OF THE SCC**

As shown in Table 3, different conversion ratios could output different no-load voltages. Since there exists voltage ripple in the output of SCCs (see Equation 3), the voltage acquired by the core loads, $V_{\text{in}} - \Delta V$, should be no less than the minimal supply voltage of the core, $V_{\text{core}}$.

Generally speaking, we choose a ratio for one SCC according to the minimal supply voltage of the load, which is shown in Fig. 5 (the Vdd is 1.2V here). However, when the demand voltage is slightly less than 0.6V (for example, 0.58V) and we choose the ratio 2:1, the output voltage ripple of the SCC $\Delta V$ is allowed up to $V_{\text{in}} - V_{\text{core}} = 0.02V$. This would lead to that the demand amount of flying capacitance $C_{\text{fly}}$ for this SCC is very large (see Equation (3)). And consequently, the power loss is huge (see Equation (5)), resulting in low conversion efficiency. For instance, if one SCC with the ratio 2:1 is employed to supply to one core, using the parameters in Table 3 and Table 5 we can have $e_1 = 7.08 * e + 5$ and $e_2 = 9.13 * e - 12$ in Equation 5. When the demand voltage is 0.588V, the demand capacitance is at least 2.1nF (see Equation (16)) and the loss increases to 5.9mW. However when the demand voltage is 0.598V, the demand capacitance is at least 12.5nF and the loss increases to 9.6mW. What’s more, as the MIM capacitance is global resource, the MIM capacitance used in other SCCs would decrease. On the other hand, perhaps the ratio 3:2 is better to achieve high efficiency.

Hence we could set an overlap region whose demand voltage is slightly less than 0.6V (and also other $V_{\text{in}}$s such as 0.8V, 0.9V...). In these regions, we should determine which ratio is better to select for the efficiency of all SCCs.

**IV. PLANNING METHODS OF SCCS**

In this section, we would show how to do the SCC planning to achieve better power efficiency at early design stage of the chip, when the $M$ cores system are supplied by less number of SCCs (i.e., $\hat{M}$). Here we study two steps: 1) The SCC supply scheme (i.e., mapping relationship between SCCs and cores), when $\hat{M}$ SCCs supply energy to the $M$ cores, 2) The MIM capacitance allocation and conversion ratio selection of the $\hat{M}$ SCCs. Besides, we also provide the guidance of how many SCCs should be used to achieve the minimum overall loss.

**A. OVERVIEW OF THE SCC PLANNING**

In order to plan $\hat{M}$ SCCs ($1 \leq \hat{M} < M$) to supply energy to the $M$ cores, we would merge the cores into $\hat{M}$ groups with each group supplied by an individual SCC. Hence two kinds of loss are shown and introduced in details in the followings.

1) Assume the Group $\hat{m}$ has $L$ cores, these cores have the minimum supply voltage $V_{\text{in}}^1, V_{\text{in}}^2, \ldots, V_{\text{in}}^L$ respectively. As this group is supplied by one SCC, it would have an minimum supply voltage $V_{\text{group}}^\hat{m} = \max(V_{\text{in}}^1, V_{\text{in}}^2, \ldots, V_{\text{in}}^L)$. Hence many cores here would have an higher supply voltage which is not necessary and this leads to the extra power loss

$$P_{\text{extra}}^\hat{m} = \sum_{l=1}^{\hat{M}} I_{l}^\hat{m}(V_{\text{group}}^\hat{m} - V_{\text{core}}^l)$$

where the $I_{l}^\hat{m}$ is the maximum current demand of core $l$. Hence we need to wisely merge the $M$ cores into $\hat{M}$ groups with each group supplied by an individual SCC, so that the total extra power loss of each group $P_{\text{total}} = \sum_{m=1}^{M} P_{\text{extra}}^m$ is minimized to get the highest energy efficiency.
the graph is to iteratively merge the nodes until the number of nodes in a maximum demand current. We could follow the loop below

\[ M \] grams. After we get the adjacent graph (we could obtain this adjacent graph by using the V oronoi dia-

above graphs the labeled weight is the smallest weight). with the smallest weight in the graph to merge (assuming in each of the groups connected with the smallest weight to merge. Hence

\[ \text{FIGURE 6. The layout of a 4-core chip and its adjacency graph representing the neighbor relationship.} \]

For example, to represent the neighbor relationship in a multicore chip, we could obtain this adjacent graph by using the Voronoi dia-

grams. After we get the adjacent graph (M nodes), each node would represent one core with a minimum supply voltage and a maximum demand current. We could follow the loop below to iteratively merge the nodes until the number of nodes in the graph is \( \hat{M} \).

1. Find the smallest weight \( W_{x,y} \) in the adjacency graph. Merge the node \( x \) and node \( y \) into a new node \( x_\text{topo} \), and calculate \((V_{x,y}^\text{group}, I_{x,y}^\text{group})\) (see Equation (9) and (10)) respectively).

2. Update the weights connected to the original node \( x \) and \( y \) with Equation (11). Then a new adjacency graph is generated.

3. Goto 1, until the number of nodes in the adjacent graph is \( \hat{M} \).

Given the layout of all the cores in a multicore chip, we could calculate the total induced extra power loss with Equation (8),

\[ P_{\text{extra}}^\text{total} = \sum_{m=1}^{\hat{M}} P_{\text{extra}}^m = \sum_{m=1}^{\hat{M}} \sum_{l=1}^L I_{\text{core}}^l (V_{\text{group}}^m - V_{\text{core}}^l) \tag{12} \]

\[ C. \text{STEP 2: OPTIMIZING THE SCCS} \]

When the cores are merged in \( \hat{M} \) groups, we treat each group as one core with a minimum supply voltage \( V_{\text{group}}^m \) and a maximum demand current \( I_{\text{group}}^m \) (see Equation (9) and (10)). Given the load information of these cores, the total available MIM capacitance for SCCs and optional ratios for one SCC, The problem is to optimize the capacitance allocation and ratio selection for the \( \hat{M} \) SCCs to get better energy efficiency. In this section, we conduct our method to optimize the capacitance allocation and ratio selection for each SCC to achieve the minimal power loss of all SCCs, \( P_{\text{extra}}^\text{total} \).

We could use \( x(m, n) \), a binary-variable, to indicate whether the \( n \)-th ratio is used in the \( m \)-th SCC. According to Equation (5), the total power loss of all SCCs would be

\[ P_{\text{scc}}^\text{total} = \sum_{m=1}^{\hat{M}} \sum_{n=1}^{N} x(m, n) \cdot (e_{1}^m \cdot n + e_{2}^m \cdot n + \frac{e_{3}^m \cdot n}{C_{\text{sw}}^m}) \tag{13} \]

where \( \hat{M} \) and \( N \) are the number of SCCs and the number of optional ratios. And \( e_{1}^m \cdot n, e_{2}^m \cdot n \) is the value of \( e_{1}(e_{2}) \) in the power loss model of the \( m \)-th SCC, when the \( n \)-th ratio of the \( m \)-th SCC is used. So we would minimize the objective function of Equation (13).

And we have the constraints:

1) each of the \( \hat{M} \) SCCs would only choose one conversion ratio, that’s

\[ \sum_{n=1}^{N} x(m, n) = 1, \quad \forall m = 1, 2, \ldots, \hat{M} \tag{14} \]

2) the MIM capacitance used in each SCC as flying capacitance would have a total amount, which should be no more than the total MIM capacitance \( C_{\text{total}} \). So we have

\[ \sum_{m=1}^{\hat{M}} C_{\text{sw}}^m \leq C_{\text{total}} \tag{15} \]

3) besides, according to Equation (3) and Section III-C, the output voltage ripple of the \( m \)-th SCC, \( \Delta V_{\text{group}}^m \), should not exceed the maximal allowed ripple of this core group, \( \Delta V_{\text{max}}^m \), the total available no-load voltage \( V_{\text{nl}} \), (for example, the SCC with ratio 2:1 would output no-load voltage 1/2*VDD), and the received voltage of the core is \( V_{\text{core}}^m - \Delta V \), where \( \Delta V \) is the voltage ripple. If the received voltage of the core \( V_{\text{nl}} - \Delta V \) is less than the demand voltage of the core \( V_{\text{core}} \), this would lead to malfunction of the cells in this core. As a result, the maximum allowed voltage ripple is

\[ \Delta V_{\text{max}} = V_{\text{nl}} - V_{\text{core}} \geq \Delta V = \frac{\text{lag}}{M_{\text{topo}} \cdot f_{\text{sw}} \cdot N_{\text{phase}} \cdot C_{\text{sw}}^m} \]

\[ (\text{see Equation (3))}. \]

This could lead to a lower bound of each \( C_{\text{sw}}^m \), since

\[ V_{\text{group}}^m - V_{\text{core}}^m \geq \frac{I_{\text{group}}^m}{M_{\text{topo}} \cdot f_{\text{sw}} \cdot N_{\text{phase}} \cdot C_{\text{sw}}^m} \tag{16} \]
where \( \hat{m} = 1, 2, \ldots, \hat{M} \) and hence \( \hat{M} \) constraints here.

Notice \( V_{nl}^{\hat{m},n} \) here is the output voltage of the \( \hat{m} \)-th SCC, when it uses the \( n \)-th ratio.

Obviously this is a MINLP (i.e., Mixed-Integer Nonlinear Programming) problem since we have continuous variables \( C_{sw}^m \), binary variables \( x_{\hat{m},n} \) and non-linear terms in the objective function. Although there are many solvers such as IBM Cplex [38] could directly be used to solve the problem, the problem is still hard to get its optimal result in a suitable period of time, especially when the size of the problem is still hard to get its optimal result in a suitable period of time.

**Algorithm 1** Early-stage planning of SCCs

```plaintext
1: Input: the layout of \( M \) cores, the minimum supply voltage and maximum current of \( m - th \) core \((V_{core}^m, I_{core}^m)\), the number of SCCs \( \hat{M} \).
2: Output: the supplied cores in each of the \( \hat{M} \) SCCs, the capacitance \( C_{opt}^m \) and the ratio \( r^m \) for each SCC.
3: // Step1: Grouping the cores
4: Generate the adjacency graph \( G \)
5: while the number of nodes in \( G > \hat{M} \) do
6:   Find the smallest weight \( W_{x,y} \) in \( G \), and merge the nodes \( x \) and \( y \) into new node \( x_y \)
7:   Calculate the minimum supply voltage and maximum demand current \((V_{x,y}, I_{x,y})\) with Equation (9) and (10).
8: end while
9: // Step2: Optimizing the SCCs
10: Formulate the power loss optimization as a MINLP problem (Equation (13) (14) (15) and (16)).
11: According to the demand voltages of each core group, get the \( K \) ratio combinations (sub-problems).
12: for \( k = 1 \) to \( K \) do
13:   get a case of optimal total power loss \( P_{total,k} \), and the corresponding MIM capacitance \( C_{sw}^m \) and conversion ratio \( r^m \), \( \hat{m} = 1, 2, \ldots, \hat{M} \).
14: end for
15: get the case of \( C_{sw}^\hat{m} \) and \( r^\hat{m} \), \( \hat{m} = 1, 2, \ldots, \hat{M} \), which is corresponding to the minimal total power loss \( P_{total} \). \( = \min \{ P_{total,k} \} \).
```

V. THE OPTIMAL NUMBER OF THE SCCS

As introduced in [19], the authors use a penalty term for the power loss of control circuit and the power consumption of clock signals. Here, we also use a penalty term for the power loss overhead of integrating the SCCs since integrating the SCCs in a multicore chip needs the control circuit, the routing resource (including the supply routing resource), the power consumption of clock signals, the chip area and so on. It’s reasonable that the overhead to integrate one SCC could be evaluated as a constant loss \( P_0 \) (as the penalty). With the increase of the number of SCCs, the overhead to integrate more SCCs \( \hat{M} \ast P_0 \) would increase, while the power loss \( P_{extra} + P_{total} \) would generally decrease because of finer power management. The overall loss with \( \hat{M} \) SCCs is

\[
P_{total} = P_{total,extra}(\hat{M}) + P_{total}(\hat{M}) + \hat{M} \ast P_0
\]

where \( \hat{M} \) is the number of used SCCs in the chip.

By varying the number of SCC \( \hat{M} \) from \( M \) to \( 1 \), we could get the overall loss with the aforesaid techniques at every

As a conclusion of this solution for the SCCs planning, **Algorithm 1** shows the the framework of the early-stage SCC planning method.

**Algorithm 1 Early-stage planning of SCCs**

1. Input: the layout of \( M \) cores, the minimum supply voltage and maximum current of \( m - th \) core \((V_{core}^m, I_{core}^m)\), the number of SCCs \( \hat{M} \).
2. Output: the supplied cores in each of the \( \hat{M} \) SCCs, the capacitance \( C_{opt}^m \) and the ratio \( r^m \) for each SCC.
3: // Step1: Grouping the cores
4: Generate the adjacency graph \( G \)
5: while the number of nodes in \( G > \hat{M} \) do
6:   Find the smallest weight \( W_{x,y} \) in \( G \), and merge the nodes \( x \) and \( y \) into new node \( x_y \)
7:   Calculate the minimum supply voltage and maximum demand current \((V_{x,y}, I_{x,y})\) with Equation (9) and (10).
8: end while
9: // Step2: Optimizing the SCCs
10: Formulate the power loss optimization as a MINLP problem (Equation (13) (14) (15) and (16)).
11: According to the demand voltages of each core group, get the \( K \) ratio combinations (sub-problems).
12: for \( k = 1 \) to \( K \) do
13:   get a case of optimal total power loss \( P_{total,k} \), and the corresponding MIM capacitance \( C_{sw}^m \) and conversion ratio \( r^m \), \( \hat{m} = 1, 2, \ldots, \hat{M} \).
14: end for
15: get the case of \( C_{sw}^\hat{m} \) and \( r^\hat{m} \), \( \hat{m} = 1, 2, \ldots, \hat{M} \), which is corresponding to the minimal total power loss \( P_{total} \). \( = \min \{ P_{total,k} \} \).
granularity of SCCs. And the optimal number of SCC $\hat{M}_{opt}$ is the one with the minimal overall loss. Therefore one could explore the number $\hat{M}$ to find the best number of used SCCs which achieves the minimal overall loss.

It’s noticed that the optimal number of SCCs is closely related with the layout information of cores in the chips. For the Equation (18), the layout information would affect the term $P_{\text{total\;extra}}(\hat{M})$ and $P_{\text{total\;scc}}(\hat{M})$. Therefore, we couldn’t directly figure out the optimal number of SCCs at one time. Instead, we could use the method that by varying the number of SCCs, we can get the loss information and finally achieve the optimal number of SCCs.

VI. EXPERIMENTAL RESULTS

In this section, we would present the results of our SCC planning work.

Heterogeneous multicore benchmarks, including 4-core, 8-core and 16-core, are tested. The loads information in each core of our benchmarks are obtained from a reasonable scaling of the value in [19] and are shown in Table 4. We assume that firstly the cores in [19] are in many types (such as Cortex-A72@ 0.78V/@ 0.82V [41], DSP@ 0.55V [42]), and the current information could be achieved by the system-level simulators GEM5 [43] and McPAT [44] which simulate the hardware behavior and get the power information [45]. Then the aspect ratios of these cores could be customized [46]. The layouts of cores in the three chips are shown in Fig. 9 and simpler versions of such heterogeneous chips could be seen on today’s market [47]. The layouts of these three multicore chips are fixed patterns. And the Algorithm 1 in Section IV-D can be applied to any benchmarks as long as the layouts of cores, the minimum supply voltage and maximum current and the available number of SCCs are given. As introduced in Section II, by given enough information, we can easily formulate the problem and apply the optimization algorithm. And the results vary with the layouts of cores in different benchmarks.

The parameters of SCCs used in the experiments have been listed in Table 5. And the CVX [40] is used to solve the convex problems.

A. RESULTS OF THE SCC PLANNING

1) THE CORE GROUPING

With our grouping method, the cores in a chip could be in several groups. Fig. 10 shows two strategies used to group the cores, and the respective obtained extra power loss.

Strategy 1: The proposed grouping strategy in Section IV-B.

Strategy 2: Differing from strategy 1, here we simply merge two adjacent cores/groups which have the most similar supply voltage at each time. Hence we replace the weight in Equation (11) with $W_{x, y} = |V_{\text{group}}^{x} - V_{\text{group}}^{y}|$.

We can see that as the number of groups (i.e., $\hat{M}$) varies from $M$ to 1, the extra power loss would increase. This is because with less SCCs the power management would be coarser, and more power could be wasted as there are more mismatches between the core demand voltage and the SCC output voltage. And we also see that our strategy 1 is better than strategy 2 since it comes out with less extra power loss in most cases (Notice that when the case $\hat{M} = 1$, both grouping strategies would result in only one group that includes all cores, leading to same extra power loss. What’s more, since there are some homogeneous cores in this chip, both grouping strategies would put these cores together first, leading to no extra power loss at $\hat{M} = 6$ or 7).
2) THE SCC OPTIMIZATION

In this section, we would show the obtained power loss of all SCCs when optimizing the MIM capacitance allocation and ratio selection. To show the effectiveness of our optimization, we also show the obtained power loss when we do not optimize the capacitance or ratio. We show power loss results of 4 SCCs in the 4-core chip without and with optimization in Table 6. In the w/o method, we allocate the capacitance to each SCC according to

1: the percentage of core area supplied by this SCC,
2: the percentage of core current supplied by this SCC.

And then we select the ratio according to the demand voltage without considering the overlap voltage regions (see Fig. 5). We mark this two methods as w/o optimizing SCCs _1 and w/o optimizing SCCs _2, respectively. It can be seen that our method could allocate the capacitance wisely and also select better ratios in some SCCs, which totally significantly reduce the total power loss of SCCs.

3) RESULTS OF THE WHOLE FRAMEWORK

In our work, we propose the SCC planning framework to obtain better power efficiency when the given number of SC converters is less than the number of cores in chip. In this part, we would show the planning results and the obtained power efficiency when the given number of SC converters varies from M to 1. To the best of our knowledge, there is no literature to explore the supply method where the used number of SCCs is less than the number of cores. Three methods stated in the following to implement the SCC planning framework, which include the general ideas if one would use less number of SCCs to supply the power for the cores, are shown as the comparisons in the results.

(0) Ours: we use the proposed grouping strategy and the SCC optimization technique both described in Section IV.

(1) Method 1: we do not use the proposed grouping strategy (but strategy 2 in Section VI-A.1 instead) and use the SCC optimization technique.

(2) Method 2: we do not use the proposed grouping strategy (but strategy 2 in Section VI-A.1 instead) and do not use the SCC optimization technique (w/o optimizing SCCs _2 in Section VI-A.2 instead).

Let us see the 4-core benchmark as an example firstly. If the given number of SC converters \( \hat{M} \) is 3, the results of our SCC planning framework are shown in Table 7. We can see with our methods the supply schemes and optimized capacitance and ratios could be obtained for better efficiency of the chip.

The energy efficiency of the chip with three planning methods are shown in Fig. 11 respectively. We can see the energy efficiency with our method is slightly higher than that with Method 1, and more higher than that with Method 2. Besides, it could be seen that as the the given number of SCCs in the 4-core benchmark varies from 1 to 4, the energy efficiency of the chip with our method could be improved since more SCCs would lead to a finer power management. On the contrary, as Method 2 does not use the SCC optimization technique, the more SCCs are given, the more unreasonable capacitance allocation would occur and the worse efficiency would appear.

The energy efficiency of the 8-core and 16-core benchmarks with our methods are shown in Fig. 12 and Fig. 13, respectively. It is noticed that the energy efficiency would stay the same when the number of SCCs nears \( \hat{M} \). This is because there are many identical cores (i.e., homogeneous) in the heterogeneous chip, and it would not induce any more \( P_{\text{total extra}} \) or \( P_{\text{total scc}} \) when two identical cores are merged into one group and supplied by one SCC.

B. THE BEST NUMBER OF SCCS

Our method also provides the way to find the best number of SCCs, which could lead to the minimal overall power
TABLE 6. Optimizing the four-SCC case of the four-core benchmark. Here * stands for the selected ratio among the possible candidates with our optimization.

| #SC | w/o optimizing SCs | w/o optimizing SCs_2 | w/ optimizing SCs |
|-----|--------------------|-----------------------|------------------|
|     | C_{total} (nF) | C_{optim} (mW) | C_{optim} (nF) | C_{optim} (mW) | C_{optim} (nF) | C_{optim} (mW) |
| SC1 | 5 | 2:1 | 5.08 | 1.25 | 2:1 | 8.17 | 1.04 | 2:1* | 3:2 | 9.47 |
| SC2 | 2 | 3:2 | 15.32 | 1.57 | 3:2 | 18.95 | 1.85 | 3:2 | 16.41 |
| SC3 | 3 | 4:3 | 145.62 | 4.70 | 4:3 | 94.61 | 4.67 | 4:3 | 37.37 |
| SC4 | 3 | 1:1 | 77.90 | 5.48 | 1:1 | 43.31 | 5.44 | 1:1 | 43.59 |

\[ \hat{M} \times P_0 \] would increase, as the number of the SCC grows. As a result, when two SC converters are used, we would obtain the minimal overall loss.

TABLE 7. When the 4-core chip is supplied with three SCCs, our SCC planning methods could obtain smart supply schemes and optimized capacitance and ratios for each SCC.

| #SCC | Supplied cores | Cap (nF) | ratio (%) | Ours | Cap (nF) | ratio (%) | Method 1 | Cap (nF) | ratio (%) | Method 2 | Cap (nF) | ratio (%) | Method 2_2 |
|------|----------------|----------|-----------|------|----------|-----------|----------|----------|-----------|----------|----------|-----------|-----------|
| SCC1 | core1, core2 | 3.22 | 3.2 | 84.4 | core1 | 1.04 | 2:1 | core1 | 5 | 2:1 | core1 | 1.25 | 2.1 |
| SCC2 | core3 | 4.51 | 1:1 | 83.7 | core2 | 1.85 | 3:2 | core2 | 2 | 3:2 | core2 | 1.57 | 3.2 |
| SCC3 | core4 | 5.27 | 1:1 | 83.6 | core3, core4 | 10.11 | 1:1 | core3, core4 | 6 | 1:1 | core3, core4 | 10.18 | 1:1 |

FIGURE 13. 16-core benchmark: efficiency vs convert number.

FIGURE 14. The tradeoff between power loss and the constant loss (i.e., the penalty of using SCCs) in eight-core benchmark, and result in finding a minimal overall loss.

FIGURE 15. The tradeoff between power loss and the constant loss (i.e., the penalty of using SCCs) in four-core benchmark, and result in finding a minimal overall loss.

FIGURE 16. The tradeoff between power loss and the constant loss (i.e., the penalty of using SCCs) in sixteen-core benchmark, and result in finding a minimal overall loss.
The similar trend is also observed in 4-core and 8-core benchmarks, and the results are shown in Fig. 15 and Fig. 16 respectively. We can see that the optimal numbers of SC converter for 4-core and 16-core benchmarks are 1 and 3 respectively.

VII. CONCLUSION

As the overhead of integrating SCCs in a chip is non-negligible and the SCCs could not be overused. In this paper, for better energy efficiency we propose an early stage planning framework of SCCs to obtain the SCC supply scheme together with the optimized MIM capacitance allocation and converter ratio selection for each SCC when the given number of SCCs is less than the number of cores. Besides, our method could also explore to find the best number of used SCCs for a given chip. The experiments show the results of our SCC planning methods.

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