MOSAICS OF COMBINATORIAL DESIGNS

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Abstract. Looking at incidence matrices of $t$-$(v,k,\lambda)$ designs as $v \times b$ matrices with 2 possible entries, each of which indicates incidences of a $t$-design, we introduce the notion of a $c$-mosaic of designs, having the same number of points and blocks, as a matrix with $c$ different entries, such that each entry defines incidences of a design. In fact, a $v \times b$ matrix is decomposed in $c$ incidence matrices of designs, each denoted by a different colour, hence this decomposition might be seen as a tiling of a matrix with incidence matrices of designs as well. These mosaics have applications in experiment design when considering a simultaneous run of several different experiments. We have constructed infinite series of examples of mosaics and state some probably non-trivial open problems.

1. Introduction

A $t$-design with parameters $(v,k,\lambda)$ is a collection $\mathcal{B}$ of $k$-element subsets (blocks) of a $v$-element set $X$ (of points), such that every $t$-element subset of $X$ is contained in exactly $\lambda$ blocks. In such a case we speak sometimes of a $t$-$(v,k,\lambda)$ design.

It is known that $t$, $v$, $k$ and $\lambda$ must satisfy a number of more or less complicated (necessary) divisibility conditions whereas for $t \geq 2$ the existence of a $t$-design with parameters $(v,k,\lambda)$ is only known for particular cases which are not described by any general set of sufficient conditions.

A particularly convenient way to represent a design $\mathcal{B}$ is a binary $(v \times b)$-matrix, where $b$ is the number of blocks of the design and can be calculated as $b = \lambda \cdot \binom{v}{t}/\binom{k}{t}$. This matrix, also called the incidence matrix of $\mathcal{B}$, is labeled by the points in $X$ and the blocks of $\mathcal{B}$, and its entries give the value of the incidence, namely 1 for incident and 0 for non-incident. Each point of a $t$-design is incident with the same number of blocks, usually denoted by $r = \lambda \cdot \binom{v-1}{t-1}/\binom{k-1}{t-1}$.

The complement $\overline{\mathcal{B}}$ of a design $\mathcal{B}$ has the same point set $X$, while its blocks are complements of the blocks of $\mathcal{B}$. The complement of a $t$-design is a $t$-design as well. In particular, the complement of a 2-$(v,k,\lambda)$ design is a 2-$(v,v-k,b-2r+\lambda)$ design. Therefore, one can say that the entries equal to 1 in an incidence matrix indicate incidences of a design, while the 0’s indicate incidences of its complement.

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In the paper [2], dealing primarily with 1-designs, the notion of a coloured constant-composition design was thought of as a generalisation of this binary understanding of incidence in that the incidence matrix may be multi-valued (coloured) such that the set of subsets defined by every colour forms a design with its individual parameter set. A simple example for this was given in [2, example 1.3] and looks as follows.

**Example 1.1.** The matrix
\[
\begin{bmatrix}
2 & 3 & 3 & 1 & 3 & 1 & 1 \\
1 & 2 & 3 & 3 & 1 & 3 & 1 \\
1 & 1 & 2 & 3 & 3 & 1 & 3 \\
3 & 1 & 1 & 2 & 3 & 3 & 1 \\
1 & 3 & 1 & 1 & 2 & 3 & 3 \\
3 & 1 & 3 & 1 & 1 & 2 & 3 \\
3 & 3 & 1 & 3 & 1 & 1 & 2
\end{bmatrix}
\]

is the incidence matrix of a 3-coloured constant composition design in the sense of [2].

As a motivation for the work on the paper at hand, we observed that colours 1 and 3 each define a 2-design with parameters \((7, 3, 1)\) whereas colour 2 gives rise to the trivial 2-design with parameters \((7, 1, 0)\).

Indeed, all the \(v \times b\) incidences between the points of \(X\) and \(b\) copies of \(X\) itself can be partitioned in a mathematical constellation that might be best described by the expression:

\[
2-(7, 3, 1) \oplus 2-(7, 3, 1) \oplus 2-(7, 1, 0).
\]

It may get even clearer if we remark that the all-one matrix \(J\) of dimension \(v \times b\) can be written as a sum of the corresponding incidence matrices of mentioned 2-designs.

As a matter of fact, we are able to immediately generalise this basic idea to any prime power \(v \equiv 3 \pmod{4}\) using quadratic residues and non-residues in \(GF(v)\), forming developments of the Paley difference sets in the additive groups of \(GF(v)\), so that we clearly and constructively obtain 3-valued incidence matrices describing decompositions of the form:

\[
2-\left(\frac{v-1}{2}, \frac{v-3}{4}\right) \oplus 2-\left(\frac{v-1}{2}, \frac{v-3}{4}\right) \oplus 2-(v, 1, 0).
\]

Specifically, for \(v = 31\), we have the example

\[
2-(31, 15, 7) \oplus 2-(31, 15, 7) \oplus 2-(31, 1, 0),
\]

and we ask, if, particularly for \(v = b = 31\), there exist other decompositions of this kind.

Purely arithmetically, we may think of

\[
2-(31, 15, 7) \oplus 2-(31, 10, 3) \oplus 2-(31, 6, 1),
\]

however, so far, we have not been able to provide an example of a 3-valued incidence matrix giving rise to this decomposition.

This paper is devoted to developing a formalisation of the general idea underlying these thoughts. To the best of our knowledge, there has not been any approach to
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2. Main Definition and Necessary Conditions

Let us recapitulate the main notion introduced in the previous section. We can take the all-one matrix of dimensions $v \times b$ and try to write it as a sum of incidence matrices of $t$-designs:

$$J = M_1 + M_2 + \cdots + M_c,$$

where $M_j$'s are incident matrices of designs $B_j$. Since the complement of a design is a design again, this equation is equivalent to the next one:

$$\overline{M_i} = M_1 + M_2 + \cdots + M_{i-1} + M_{i+1} + \cdots + M_c.$$

If we look at the last expression structurally, we see that we have decomposed every block of the design $B_i$ into $c - 1$ differently coloured subblocks in the way that every set of $b$ subblocks of the same colour constitutes a design. This fact justifies the way we have written down our constellations:

(1) \[ t - (v, v, b) = t_1 - (v, k_1, \lambda_1) \oplus t_2 - (v, k_2, \lambda_2) \oplus \cdots \oplus t_c - (v, k_c, \lambda_c), \]

or equivalently

(2) \[ t_i - (v, k_i, \lambda_i) = t_1 - (v, k_1, \lambda_1) \oplus t_2 - (v, k_2, \lambda_2) \oplus \cdots \oplus t_{i-1} - (v, k_{i-1}, \lambda_{i-1}) \]

\[ \oplus t_{i+1} - (v, k_{i+1}, \lambda_{i+1}) \oplus \cdots \oplus t_c - (v, k_c, \lambda_c). \]

We would like to point out that it is more natural and elegant to look at this decomposition on the level of incidence matrices.

**Definition 2.1.** Let $c$ be a positive integer and let $B_i$ be designs with parameters $t_i - (v, k_i, \lambda_i)$, $i = 1, \ldots, c$ with the same number of points $v$ and blocks $b$. A $c$-mosaic of designs $B_1, B_2, \ldots, B_c$ is a $(v \times b)$ matrix $M = [m_{pq}]$, $m_{pq} \in \{l_1, l_2, \ldots, l_c\}$ for which holds that matrices $M_i$ defined as

$$[M_i]_{pq} = \begin{cases} 1, & m_{pq} = l_i \\ 0, & \text{otherwise} \end{cases}$$

are incidence matrices of designs $B_i$.

Since there are a lot of parameters to be mentioned, we find it most convenient to denote a $c$-mosaic of designs with given parameters in the way as written in equations (1) and (2).

**Remark 2.2.** The prerequisites of this definition lead, presented more explicitly, to the following facts:

(1) The integrality conditions for each parameter set $t_i - (v, k_i, \lambda_i)$ are satisfied.

(2) \[ b = \lambda_1 \binom{\nu}{\nu_1} = \lambda_2 \binom{\nu}{\nu_2} = \cdots = \lambda_c \binom{\nu}{\nu_c} \]

**Remark 2.3.** If $M$ is a $c$-mosaic of designs with parameters given above, then it holds:

(1) \[ k_1 + k_2 + \cdots + k_c = v, \]

(2) \[ r_1 + r_2 + \cdots + r_c = b. \]
Conditions listed in the two remarks above form necessary conditions for the existence of a $c$-mosaic of designs. We are not aware of any further necessary conditions to be satisfied.

The following equations follow immediately from the existence of a $c$-mosaic:

\begin{align*}
M_1 + M_2 + \cdots + M_c &= J_{v,b} \\
l_1M_1 + l_2M_2 + \cdots + l_cM_c &= M
\end{align*}

Example 2.4. (a) The matrix of order $v$

\[
M = \begin{bmatrix}
1 & 2 & 3 & \cdots & v-1 & v \\
v & 1 & 2 & \cdots & v-2 & v-1 \\
v-1 & v & 1 & \cdots & v-3 & v-2 \\
\vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\
2 & 3 & 4 & \cdots & v & 1
\end{bmatrix}
\]

is a trivial $v$-mosaic of designs with parameters $2-(v,1,0)$.

(b) Incidence matrices of a $t$-design and its complement, coloured in any two different colours, define a $2$-mosaic.

(c) The previously mentioned decomposition consisting of two Hadamard $2$-designs on $v$ points and a the trivial $2-(v,1,0)$ design define a $3$-mosaic.

3. Further Constructions of Mosaics

The next obvious question for our investigation was to find non-trivial mosaics of designs. In particular, we have concentrated on $2$-designs, and how they can be composed together in such a mosaic. Before presenting a general theorem, we will show, how we tackled this problem given the example of affine planes.

Example 3.1. (a) The incidence matrix of an affine plane of order $3$, i.e. the $2$-design with parameters $(9,3,1)$, is a $(9 \times 12)$-matrix. Clearly, $3$ copies of such planes satisfy the necessary conditions and we come up with the following $3$-mosaic.

\[
\begin{bmatrix}
1 & 1 & 2 & 3 & 3 & 3 & 1 & 2 & 2 & 3 & 1 \\
1 & 3 & 1 & 2 & 3 & 2 & 3 & 1 & 2 & 1 & 2 \\
1 & 2 & 3 & 1 & 3 & 1 & 2 & 3 & 2 & 3 & 1 \\
2 & 1 & 2 & 3 & 1 & 2 & 3 & 1 & 3 & 3 & 1 \\
2 & 3 & 1 & 2 & 1 & 1 & 2 & 3 & 3 & 2 & 3 \\
2 & 2 & 3 & 1 & 1 & 3 & 1 & 2 & 3 & 1 & 2 \\
3 & 1 & 2 & 3 & 2 & 1 & 2 & 3 & 1 & 1 & 2 \\
3 & 3 & 1 & 2 & 2 & 3 & 1 & 2 & 1 & 3 & 1 \\
3 & 2 & 3 & 1 & 2 & 2 & 3 & 1 & 1 & 2 & 3
\end{bmatrix}
\]

In our notation, this is a $3$-mosaic given by

$2-(9,9,12) = 2-(9,3,1) \oplus 2-(9,3,1) \oplus 2-(9,3,1)$. 
(b) Being able to follow the same pattern, here is a \((16 \times 20)\)-matrix representing a 4-mosaic of 4 copies of the affine plane of order 4:

\[
\begin{pmatrix}
0 & 0 & 1 & 2 & 3 & 1 & 0 & 1 & 2 & 3 & 2 & 0 & 1 & 2 & 3 & 3 & 0 & 1 & 2 & 3 \\
0 & 1 & 0 & 3 & 2 & 1 & 1 & 0 & 3 & 2 & 2 & 1 & 0 & 3 & 2 & 3 & 1 & 0 & 3 & 2 \\
0 & 2 & 3 & 0 & 1 & 1 & 2 & 3 & 0 & 1 & 2 & 3 & 0 & 1 & 2 & 3 & 0 & 1 & 2 & 3 \\
0 & 3 & 2 & 1 & 0 & 1 & 3 & 2 & 1 & 0 & 2 & 3 & 1 & 0 & 3 & 2 & 1 & 0 & 3 & 2
\end{pmatrix}
\]

The bold entries in part (b) of the previous example shows how \(GF(4)\) can be used in order to describe the decomposition. Let

\[
A := \begin{bmatrix}
0 & 1 & 2 & 3 \\
1 & 0 & 3 & 2 \\
2 & 3 & 0 & 1 \\
3 & 2 & 1 & 0
\end{bmatrix}
\quad \text{and} \quad
M := \begin{bmatrix}
0 & 0 & 0 & 0 \\
0 & 1 & 2 & 3 \\
0 & 2 & 3 & 1 \\
0 & 3 & 1 & 2
\end{bmatrix}
\]

denote the addition and multiplication table of \(GF(4)\). Then, up to column rearrangements, the above matrix can be written as:

\[
\begin{bmatrix}
m_{0,0} + A & m_{0,1} + A & m_{0,2} + A & m_{0,3} + A \\
m_{1,0} + A & m_{1,1} + A & m_{1,2} + A & m_{1,3} + A \\
m_{2,0} + A & m_{2,1} + A & m_{2,2} + A & m_{2,3} + A \\
m_{3,0} + A & m_{3,1} + A & m_{3,2} + A & m_{3,3} + A
\end{bmatrix}
\begin{bmatrix}
a_{0,0} J_{4,1} & a_{0,1} J_{4,1} & a_{0,2} J_{4,1} & a_{0,3} J_{4,1} \\
a_{1,0} J_{4,1} & a_{1,1} J_{4,1} & a_{1,2} J_{4,1} & a_{1,3} J_{4,1} \\
a_{2,0} J_{4,1} & a_{2,1} J_{4,1} & a_{2,2} J_{4,1} & a_{2,3} J_{4,1} \\
a_{3,0} J_{4,1} & a_{3,1} J_{4,1} & a_{3,2} J_{4,1} & a_{3,3} J_{4,1}
\end{bmatrix}
\]

where \(J_{4,1}\) denotes the all-1-column of length 4. In fact, it is clear that this mosaic allows a "chained" tactical decomposition (see [3]) of all copies of affine planes involved in this construction.

**Theorem 3.2.** Let \(F\) be the field with \(q\) elements. Then there is a \(q\)-mosaic of affine planes of order \(q\):

\[
2 \cdot (q^2, q^2, q^2 + q) = 2 \cdot (q^2, q, 1) \oplus \cdots \oplus 2 \cdot (q^2, q, 1).
\]

**Proof.** Let \(A\) and \(M\) denote the operation tables (matrices) of the additive and multiplicative groups of \(F\) respectively. Then the desired \(q\)-mosaic is described and represented as a matrix of dimensions \(q^2 \times (q^2 + q)\) by the simple formula:

\[
[M \otimes J_{q,q} + J_{q,q} \otimes A | A \otimes J_{q,1}]
\]

Here \(\otimes\) denotes the Kronecker product of matrices, and \(J_{q,q}\) is the all-1 matrix of size \(q \times q\). Now it is an easy task to verify that each element of \(F\) (representing here a colour) appears in each row \(q + 1\) times and in each column \(q\) times and
that it appears in two different rows in the same columns just once at the same time. □

3.1. Mosaics of Resolvable Designs. We present a general construction for creating \( v_k \)-mosaics out of identical copies of a resolvable \( t-(v, k, \lambda) \) design, i.e.

\[
t-(v, v, b) = \bigoplus_{i=1}^{v_k} t-(v, k, \lambda).
\]

**Definition 3.3.** A design \( \mathcal{B} \) on a set \( X \) is called resolvable if there exists a partition of the set of blocks \( \mathcal{B} \) into so called parallel classes, such that every parallel class itself is a partition of the set of points \( X \).

We note that for a resolvable \( t-(v, k, \lambda) \) design the number of parallel classes is \( r \) and each class contains \( v_k \) blocks.

Among the many examples of resolvable designs, affine planes and Kirkman triple systems are the most prominent ones.

**Theorem 3.4.** Let \( D \) be the incidence matrix of a resolvable \( t-(v, k, \lambda) \) design, where the columns have been arranged by parallel classes. Let \( L \) be a latin square of order \( \frac{v}{k} \) with entries \( l_1, \ldots, l_{\frac{v}{k}} \). Then \( M := D (I_p \otimes L) \) is a \( \frac{v}{k} \)-mosaic.

**Proof.** We see that every \( v \times \frac{v}{k} \) submatrix containing one full parallel class is multiplied by a copy of the latin square \( L \). Since every value \( l_1, \ldots, l_{\frac{v}{k}} \) appears exactly once in every column of \( L \), every column of \( M \) contains every block of a parallel class, each block multiplied by a different \( l_i \). Since these columns form a parallel class they completely partition the set of points while having disjoint support, therefore completely covering the column without overlapping each other. Furthermore every \( l_i \) appears exactly once in every row of \( (I_r \otimes L) \), therefore every block of the original design is contained in every design of the mosaic, which shows that each design is an exact copy of the original resolvable design. □

**Example 3.5.** A \( 2-(15, 3, 1) \) resolvable design arranged by parallel classes.

\[
D := \begin{bmatrix}
1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 & 0 \\
0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 1 & 0 & 0 & 0 & 1 \\
0 & 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 \\
0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 & 0 \\
0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 \\
0 & 0 & 0 & 0 & 1 & 1 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 1 & 0 & 0 & 0 \\
1 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\
0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 \\
0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 \\
0 & 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 \\
0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 & 1 & 1 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 1 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 & 0 & 1 & 1 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 & 0 \\
0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 \\
0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 \\
0 & 0 & 0 & 0 & 1 & 1 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 1 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 & 0 & 1 & 1 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 & 0 \\
0 & 0 & 0 & 0 & 1 & 1 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 1 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 & 0 & 1 & 1 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 & 0 \\
0 & 0 & 0 & 0 & 1 & 1 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 1 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 & 0 & 1 & 1 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 & 0 \\
0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 \\
0 & 0 & 0 & 0 & 1 & 1 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 1 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 & 0 & 1 & 1 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 & 0 \\
0 & 0 & 0 & 0 & 1 & 1 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 1 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 & 0 & 1 & 1 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 & 0 \\
0 & 0 & 0 & 0 & 1 & 1 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 1 & 0 & 0 & 0.
\]
We choose a simple cyclic shift for the latin square

\[
L := \begin{bmatrix}
1 & 5 & 4 & 3 & 2 \\
2 & 1 & 5 & 4 & 3 \\
3 & 2 & 1 & 5 & 4 \\
4 & 3 & 2 & 1 & 5 \\
5 & 4 & 3 & 2 & 1 \\
\end{bmatrix}
\]

and calculate the incidence matrix of a mosaic as 

\[
M := D(I_5 \otimes L).
\]

The earlier examples on affine planes can be constructed in this fashion as well.

4. Applications of Mosaics

Combinatorial design theory has its roots in the design of experiments, arranging test subjects in suitable test groups, or arranging players in a tournament. Assume \(v\) players and a game that needs exactly \(k\) participants, then using a \(t-(v, k, \lambda)\) design ensures that when playing \(b\) games every subset of \(t\) subjects play together exactly \(\lambda\) times. Resolvable designs have been very useful, since they allow for a parallelization of test runs that are in the same parallel class.

With games and experiments it is quite often the case that a parallelization in this manner is not possible, either because only one gameboard is at hand or it is required for the test to be supervised by the same person to ensure consistency. In this case a mosaic can be used to parallelize several different games/tests, each with its own required number of players \(k_i\), on the same set of subjects. Assume a mosaic of the form

\[
t_1 - (v, k_1, \lambda_1) \oplus \cdots \oplus t_c - (v, k_c, \lambda_c)
\]

then every column of the mosaic partitions the different players onto the different games, while preserving the properties of the designs used in the mosaic.
Furthermore, applications of designs in distributed storage systems (DSS) have recently been discussed in several papers under the notion Fractional Repetition Codes (FRC). For more information, see [4] and its bibliography. It is conceivable that mosaics will provide novel features to these systems, as they will contribute to parallelisation and thus increased efficiency.

Conclusion

In this paper we have introduced the notion of a mosaic to the theory of combinatorial designs. Mosaics may be thought of as tilings of the ambient space of a design with disjoint copies of this design or otherwise with disjoint blocks of designs with different parameters.

Beside the rather immediate constructions of infinite families of mosaics derived from resolvable designs, we have a few open problems: How can mosaics be derived from non-resolvable designs? How can the concrete open case after example 1.1 (before the second section of this paper) be tackled?

These questions, along with the question, how a mosaic may be defined in the theory of designs over $\mathrm{GF}(q)$, will be addressed in forthcoming papers.

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