Sources of straylight in the post-focus imaging instrumentation of the Swedish 1-m Solar Telescope

M.G. Löfdahl\textsuperscript{1,2} and G.B. Scharmer\textsuperscript{1,2}

\textsuperscript{1} Institute for Solar Physics, Royal Swedish Academy of Sciences, Albanova University Center, 106 91 Stockholm, Sweden
\textsuperscript{2} Stockholm Observatory, Dept. of Astronomy, Stockholm University, Albanova University Center, 106 91 Stockholm, Sweden

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ABSTRACT

Context. Recently measured straylight point spread functions (PSFs) in Hinode/SOT make granulation contrast in observed data and synthetic magnetohydrodynamic (MHD) data consistent. Data from earthbound telescopes also need accurate correction for straylight and fixed optical aberrations.

Aims. We aim to develop a method for measuring straylight in the post-focus imaging optics of the Swedish 1-m Solar Telescope (SST).

Methods. We removed any influence from atmospheric turbulence and scattering by using an artificial target. We measured integrated straylight from three different sources in the same data: ghost images caused by reflections in the near-detector optics, PSFs corresponding to wavefront aberrations in the optics by using phase diversity, and extended scattering PSF wings of unknown origin by fitting to a number of different kernels. We performed the analysis separately in the red beam and the blue beam.

Results. Wavefront aberrations, which possibly originate in the bimorph mirror of the adaptive optics, are responsible for a wavelength-dependent straylight of 20–30% of the intensity in the form of PSFs with 90% of the energy contained within a radius of 0	extdegree. There are ghost images that contribute at the most a few percent of straylight. The fraction of other sources of scattered light from the post-focus instrumentation of the SST is only \(\sim 10^{-3}\) of the recorded intensity. This contribution has wide wings with a FWHM \(\sim 16''\) in the blue and \(\sim 34''\) in the red.

Conclusions. The present method seems to work well for separately estimating wavefront aberrations and the scattering kernel shape and fraction. Ghost images can be expected to remain at the same level for solar observations. The high-order wavefront aberrations possibly caused by the AO bimorph mirror dominate the measured straylight but are likely to change when imaging the Sun. We can therefore make no firm statements about the origin of straylight in SST data, but strongly suspect wavefront aberrations to be the dominant source.

Key words. Instrumentation: miscellaneous - Methods: observational - Techniques: image processing - Techniques: photometric - Telescopes

1. Introduction

For many years, there has been a discrepancy between the contrast in observed solar images and the corresponding images produced by magnetohydrodynamic (MHD) simulations. It was not clear whether compensation for straylight in the observations or missing physics in the simulations were at fault. This has now been resolved by measurements of the point spread function (PSF) in the Solar Optical Telescope (SOT) on the Hinode spacecraft (Wedemeyer-Böhm 2008) and comparison with artificial data (Wedemeyer-Böhm & Roupe van der Voort 2009). Scharmer et al. (2010) see their introduction for a full account of the problem recently initiated a project to measure the straylight sources on the optical table. We estimated the wavefront PSF by using phase diversity (PD; Gonsalves & Chidlaw 1979; Paxman et al. 1992; Löfdahl & Scharmer 1994) and fitted the remaining straylight to a scattering PSF. In particular, we were interested in the integrated fraction of scattered light in the image data and the width of the scattering kernel.

2. Imaging model

We model the image formation as

\[ g = f \ast s_\phi \ast s_K + d + n \]  

(1)

where \(g\) is a flat-fielded and dark-corrected data frame, \(f\) is the object, \(s_\phi\) is the point-spread function (PSF) of wavefront errors \(\phi\), \(s_K\) is a scattering PSF with extended wings, \(d\) represents
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Table 1: Scattering kernels

| Kernel name | Definition | FWHM |
|-------------|------------|------|
| Gauss       | $K_G(r; \sigma) \propto \exp(-r^2/(2\sigma^2))$ | $W_G = \sigma \cdot 2 \sqrt{2 \ln 2}$ |
| Lorentz     | $K_L(r; \gamma) \propto (1 + r^2/\gamma^2)^{-1}$ | $W_L = \gamma \cdot 2$ |
| Moffat      | $K_M(r; \alpha, \beta) \propto (1 + r^2/(\alpha^2\beta^2))^{-1}$ | $W_M = \alpha \cdot 2 \sqrt{2/\beta} - 1$ |
| Voigt       | $K_V(r; \sigma, \gamma) \propto K_G(r; \sigma) + K_L(r; \gamma)$ | $W_V \approx 0.5346W_L + \sqrt{0.2166W_L^2 + W_G^2}$ |

Notes. All kernels are functions of the radial coordinate $r = (x^2 + y^2)^{1/2}$. They are normalized in the Fourier domain by division with the value in the origin. $K_M$ is from [Moffat (1969)]. The approximate expression for $W_V$ is given by [Olivero & Longbothum (1977)] and is claimed to be accurate to within a few %. 

| Hole | $x$ (mm) | $y$ (mm) | $\delta$ (mm) |
|------|---------|---------|---------------|
| A    | -2      | 0       | 1000          |
| B    | 0       | -2      | 250           |
| C    | 2       | 0       | 120           |
| D    | 0       | 0       | 60            |
| E    | 0       | 2       | 30            |
| F    | $\sqrt{2}$ | $\sqrt{2}$ | 20             |

Fig. 1: Straylight target drawing. Positions $(x, y)$ in mm, diameters ($\delta$) in $\mu$m with tolerances of 1–2 $\mu$m.

A residual dark level that was not subtracted properly in flat-fielding, and $n$ is additive Gaussian white noise. These quantities are all functions of the spatial coordinates $(x, y)$, suppressed when possible for compact notation. The symbol $\ast$ denotes convolution.

The scattering PSF, $s_K$, is modeled as:

$$s_K = c \delta + (1 - c) \cdot K \quad (2)$$

where $\delta$ is the Dirac delta function, $K$ is a convolution kernel equal to one of $K_M$, $K_L$, $K_G$, or $K_V$ as given in Table 1. Because it is part of the scattering PSF, we will refer to $K$ as a scattering kernel. Both the $\delta$ function and the kernels are normalized in the Fourier domain by division with the value in the origin. Owing to this normalization, $(1 - c)$ expresses the integrated fraction of this type of straylight.

### 3. Data

The data used in this experiment were collected with the SST (Scharmer et al., 2003a) on 29 May 2010 between 17:10 and 18:40 UT.

The primary optical system of the SST is a singlet lens with a focal length of 20.3 m at 460 nm and a 98-cm aperture. A mirror at the primary focus refracts the light to a Schupmann corrector, which forms an achromatic focus next to the primary focus. In this focal plane we placed an artificial target to isolate the opto-mechanical errors are introduced to save space: the angle to the beam of the Schupmann focus. The pupil diameter is 34 mm at this focal plane of the Schupmann focus. The pupil diameter is 34 mm at this location. There is a 35 mm diameter pupil stop at the DM. This defines the pupil for pinhole images. The reimaging lens then makes a F/46 beam parallel to the optical table. The light is then split by the 500 nm dichroic beamsplitter into a blue beam and a red beam. Both beams have several cameras behind different filters. Table 2 summarizes the cameras and setup parameters used for this experiment.

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In the blue beam one camera was nominally a “focus” camera and the other a defocused “diversity” camera of a PD pair. These two cameras and their beamsplitter were mounted on a common holder and could be moved together along the optical axis. This made it possible to generate additional focus diversities without changing the relative diversity between the wideband (WB) and PD cameras. The holder and its cameras are covered by a box that blocks light from directions other than the
beam. The relative rotation of the field in the WB and PD cameras was measured by comparing the grid patterns of the pinhole array images. The rotational misalignment is smaller than 0.1.

In the red beam we used a single camera that was also covered by a box to block external straylight. Here, we could only add diversities by moving the camera.

The AO was running in closed loop on the central pinhole (D) of the straylight target while the artificial target data were collected, so aberrations are assumed to be stable during the data collection. The telescope pointing was moving near disk center to average out the granularity structure as well as possible. Many exposures were collected at every position with all cameras, 3500 exposures in the blue and 10000 in the red, for the target data as well as for dark frames and flat fields. The high number of frames was necessary because we needed a high signal-to-noise ratio (SNR) to measure the very faint straylight far away from the pinholes. The target data were corrected for bias and gain variations. The corrected image $g_i$ is calculated as

$$g_i = (h_i - d)/(f - d), \tag{3}$$

where $h_i$ is the observed data frame, $d$ is the average dark frame, and $f$ is the average flat field image. To minimize the influence from solar features in the averaged flat-field images, the individual frames were collected while the telescope was circled over a quiet area near disk center and the DM produced random wavefronts.

The images collected in different focus positions were not recorded simultaneously and we took steps to ensure that tiny image movements did not violate the assumption that we made in PD processing, i.e. that there is a common object in all images after summation. In a first pass, the data frames $g_i$ were co-added in their original form. In a second pass, each exposure was aligned to the summed WB image at nominal focus (WB0 image) from the first pass (separately in blue and red) with sub-pixel precision through centroiding (center of mass) on one of the holes, and a new sum was formed. By using the same image as an alignment target, both the individual images in each sum and also the sums at different focus positions were well aligned.

In the remainder of this paper we will refer to these summed images simply as the images, corresponding to $g$ in Eq. (1). The WB0 images are shown in Fig. 3.

### 4. Straylight measurements

#### 4.1. Ghost images

Figure 3 shows a variety of weak duplicates of the pinhole images, commonly referred to as ghost images. The most significant ghost images are shifted by only a few arcseconds and appear to be at different focus positions. These contributions must come from reflections in the beam splitters and other optics within a few cm from the detector focus, and should therefore be present during ordinary observations of the Sun as well. There are many weaker contributions that appear to be mirror images in the blue and repetitions in the different taps of the red CCD, probably originating in the camera electronics.

The ghost images are not included in the image formation model of Eq. (1), but we can measure them here and then mask them in later processing. The strongest more or less in-focus ghosts are ≤ 1% in both the blue and red (measured on hole A).

#### 4.2. Wavefront aberrations

We estimated the wavefront error PSF, $s_p$, through PD with the MOMFBD C++ code of van Noort et al. (2005). We processed a subfield centered on the 20 µm straylight hole F. In the blue we used 256×256 pixels and in the red 128×128 pixels, the different sizes are necessary because of the difference in image scale. The top row of Fig. 4 shows the central part of this subfield. We can see directly that the chosen focus positions were not ideal. PD0 is very similar to WB− and PD+ to WB0 in the blue, so instead of six different diversity channels, we have in reality only four. The focus is somewhere between WB0 and WB+ in the red; it is probably preferable to have one channel close to the focal plane, to constrain the object estimation.

Careful pre-processing is easier with point-like targets than with extended scenes, which facilitates inversions. In particular, it is possible to fine-tune the intensity bias (dark level) correction, and then make sure the total energy is the same in all focus positions. Such refined dark-level correction was performed for the purpose of PD processing. First, all images in a PD set were normalized with respect to the average intensity in the inner part of the 1 mm target hole (A). We assumed this to be the best available measure of the intensity level, insensitive to the blurring of

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1. Because the target was repeatedly removed from the beam (when collecting flat fields) and inserted (when collecting target data), the mirror was alternately heated by the sunlight and allowed to cool again. Because these thermal variations cause changes in the mirror’s shape and stress, so the level to which the assumption is valid is difficult to predict.

2. The Sarno CAM1M100 CCD is organized in 2 by 8 taps (subfields), that are read out in parallel.

3. We are not aware of any studies about optimal distribution of several focus diversities.
the edge of the hole. The WB0 images, which were collected in nominal focus, we then subtracted a dark level measured as the peak (as defined by a Gaussian fit) of the histogram of image intensity within the PD processing subfield. This corrects for some of the straylight from hole A. For the data from other focus positions, we subtracted a dark level corresponding to the difference in median intensity over the entire frame (defining the dark level). Finally, the images were normalized to the same mean intensity within the PD processing subfield. This corrects for the peak (as defined by a Gaussian fit) of the histogram of image intensity in the central parts of target hole F.

In the PD processing the wavefronts were expanded in atmospheric Karhunen–Loève (KL) functions, expressed as linear combinations of Zernike polynomials (Roddier, 1990). These KL functions are ordered as the dominating Zernike polynomial in the notation of Noll (1976), and not by monotonically decreasing atmospheric variance. Although we were not measuring atmospheric wavefronts, we chose to use KL functions because bimorph mirrors naturally produce KL modes. We assumed that the alignment of the PD channels described in Sect. 3 is sufficient for PD processing, and accordingly did not include tilt coefficients in the fit. We defined $M$ as the index of the highest-order mode used, i.e., we used KL modes $4–M$.

In addition to the KL parametrization of the unknown wavefront, we also estimated the (Zernike) focus diversities with respect to the WB0 images, starting from the same data positions. Because the WB and PD cameras sit on a common mount and are therefore moved together, a single additional focus shift had to be determined when the three images from the PD camera were added. The diversities estimated with different $M$ vary by no more than a few tenths of a mm and we used the values estimated with $M = 210$ for both $M$ used here. The nominal and estimated diversities are shown in Table 3.

The magnitudes of the estimated diversities are all lower than their nominal values. This could be caused by a mismatch in the image formation model. We used the diameter of the ordinary telescope pupil, re-imaged on the bimorph mirror. In reality, there is diffraction in the pinhole, making the re-imaged pupil slightly fuzzy. The 7 mm defocus of the PD camera is particularly underestimated. This may be because of a mistake in the setup, so this camera was in fact defocused by less than 7 mm. These estimates confirm that the diversity setting of the PD camera was not very different from the step size of the ($-, 0, +$) positions.

Along with the observed images, $g$, in Fig. 4, we also show the recreated images, $\tilde{g} = \hat{f} * \hat{g}$, based on the PD estimates $\hat{f}$ and $\hat{g}$, for different $M$. An inspection of these images clearly shows that the PSFs must be satisfactorily estimated, particularly in the blue $M = 231$ case.

The estimated wavefront phases without focus are shown in Table 4. The $M = 231$ estimates in the blue and red show similarities, although the red wavefronts are less well resolved than the blue wavefronts because of the smaller subfields used and...
possibly because of the smaller number of images with different diversities. They both have two bright rings and a dark gradient at perimeter. Both rings have brighter bumps at approximately the same positions. Particularly in the blue wavefront, the pattern resembles that of the electrodes on the bimorph mirror. The $M = 36$ wavefront estimates are much less resolved. Some similarities to the 231-estimates can be seen along the outer bright ring. However, with the smaller $M$, the KL functions apparently cannot represent the inner ring pattern visible in the $M = 231$ wavefront estimates.

The RMS values of the estimated wavefronts are listed in Table 3. The WB camera in the "0" position was out of focus by approximately 0.1 rad in the blue and 0.5 rad in the red. To make the RMS comparable between beams, we also show the RMS after subtracting the best-fit focus contribution as well as calculated for a common wavelength, 500 nm. This makes the 231-estimates in red and blue agree, $\sigma_{500} = 0.085 \pm 0.003$ waves. The 36 and 231-estimates do not agree in either beam. We are more confident in the blue 231-results because 1) the results agree between blue and red, 2) the details in the wavefront are the solution converged to when $M$ is increased in increments from 36 to 231, and 3) the solution give estimated PSFs that recreate the observed data well, see particularly the large-diversity images in Fig. 4. The Strehl ratio for this solution (see Table 3) is 0.66 in the blue. Taking the two 231 solutions in red and blue together we obtain a Strehl ratio of $75 \pm 2\%$ at 500 nm after removing the focus error.

Instrumental contributions to the wavefronts can in principle be estimated and corrected in solar data with the normal MOMFBD image restoration, except that we usually use 36 modes, far less than 231. The instrumental high-order modes are not included in the $r_0$ measurements of the wide-field wavefront sensor so they are also not dealt with in the high-order compensation of Schärmer et al. (2010). They are therefore an independent contribution to the lowered contrast in our solar images.

In Fig. 5 we show the enclosed PSF energy as a function of the radial coordinate. The enclosed energies for $s_0$ and $s_8$ reach 90% at $r = 0\farcs17$ and $0\farcs62$, respectively, in the blue and at $0\farcs27$ and $0\farcs55$ in the red.

### 4.3. Extended wings

We attempted to fit a scattering PSF with extended wings to the WB0 images shown in Fig. 3. We preferred to use the 1 mm hole A, because it transmits more light than the other holes and therefore has better SNR in the far wings. To remove the pollution from the other holes and from the ghost images, we defined binary masks to be used when fitting, see Fig. 2.

The Strehl ratio is the observed peak of the PSF divided by the peak of the theoretical PSF for a perfect imaging system.

For the WB0 images used for fitting the straylight model, the second-pass sums were corrected for a pattern of stripes running in the $y$ direction. This correction was made by subtracting from all rows a smoothed version of the mean of rows 1–10. The average of this correction was $\sim 10^{-4}$ in the blue and almost $\sim 10^{-4}$ in the red, representing a correction of the dark level similar to the levels corrected in the previous section. (Fig. 5 shows the images after this step.) For this step the images were also normalized with respect to the average intensity in the inner part of the 1 mm hole (A).

A binary representation of hole A was generated by thresholding the WB0 image at 50% of the maximum intensity and removing contributions from the other holes. Artificial images were then made by convolving this binary image with the appropriate PSFs.

Figure 7 shows an azimuthal average (taking the mask into account) of hole A, zoomed in on the hole perimeter. (The zoom makes a discrepancy in image scale of about 1% apparent.) We show the artificial hole convolved with three different PSFs and the observed hole. The artificial image made with PD estimated $s_8$ match the observed data very well in the blue. Comparing with the diffraction limited image, it is obvious that we need to model the wavefront PSF to isolate other sources of straylight. The match is fairly good also in the red but the near wings are overestimated. The two PD estimated PSFs ($M = 36$ and $M = 231$, resp.) give almost indistinguishable results for this purpose. The straylight we will try to model with the scattering PSF, $s_0$, is the component that shows up at $r \geq 5\farcs8$ in the blue and $r \geq 6\farcs2$ in the red.

We now fitted Eqs. (1) and (2) to the data, using the $M = 231$ estimates of $s_0$ as fixed contributions from the wavefronts. We used the Levenberg–Marquardt algorithm as implemented in...
the MPFIT package for IDL (More
Markwardt 2002). In practice we fitted with two parameters \( c_1 \) and \( c_2 \) substituted for \( c \) and \((1-c)\) in Eq. (2) to allow for normalization differences in real and artificial data. We then report \( c = c_1/(c_1 + c_2) \) as the result of the fit.

The results of the fits are shown in Fig. 8 and in Table 3. With any of the kernels we get \( c > 0.99 \) in both beams, which appears to be a very robust result by the agreement between the different fits. In the blue we get 0.2–0.4% scattered light and in the red 0.1–0.4%.

The \( d \) parameter is returned with low values, on the order of \( 10^{-5} \). This indicates that the subtraction of the average top rows worked well as a dark correction refinement. Note that in the red, outside the signal-dominated radii, there is just noise, seemingly around zero. In the blue there seems to be a remaining uncorrected dark level that is not modeled by the \( d \) fit parameter. This could be caused by a geometrical asymmetry, e.g., by insufficient masking of the other holes or a dark-level gradient. It does not seem to ruin the fits.

We have less confidence in the details of the red fits than in the blue fits because the artificial image based on \( s_\phi \) overestimates the core of the PSF, see the right panel of Fig. 8. However, it is apparent from Fig. 8 that there is less straylight in the red than in the blue. Comparison of the observed red data (black in the red plots) with the observed blue data (gray) reveals a factor of \(~3\) difference. This would favor the lower estimate of 0.1% in the red and make the Lorentz kernel fit less believable.

In the blue the fit with a Gaussian kernel seems to fail at large radii. It also has the largest FWHM, \(~20''\). The Lorentzian kernel follows the signal dominated geometrical better than the other kernels but the Voigt and Moffat kernels give similar results. These all have FWHM \( 13'' \sim -16'' \). In the red the Lorentzian kernel differs from the other kernels by giving a larger FWHM. While the Moffat kernel \( \beta \) is estimated with a very high value, which is compensated for by an \( \alpha \) that is also very large, and the Voigt kernel is almost degenerated to a Gaussian, the latter three kernels agree on a FWHM of \( 34'' \). We conclude that the Voigt and Moffat kernels, by virtue of their two fit parameters, are better able to represent the true shape of the extended wings. Using their results, we estimate the FWHM to \( 16'' \) in the blue and \( 34'' \) in the red.

There are noticeable residuals at \( 10'' \pm \) a few arcsec in the fits shown in Fig. 8. Particularly in the red, where this feature corresponds to 36% of the total intensity! Because of the log scale, this residual looks much lower in the blue but the corresponding error in the blue is in fact 15%. This may sound alarming but it appears this is needed to cancel fitting errors within the hole and at the hole perimeter. There are several possible reasons for the bad fits at small radii. There are small imperfections in the shape of the hole that could cause diffraction. The 50% threshold does not necessarily produce a binary representation of the hole with a correct size. The thickness of the metal foil may cause reflections in the interior walls of the hole. There are remaining variations in intensity of unknown origin within the hole. Particularly in the red, the PD estimated \( s_\phi \) does not fit the core of the PSF. Owing to the truncation of the wavefront expansion, the estimated \( s_\phi \) may also under-represent the near wings of the PSFs. Thermal relaxation may cause variations in the \( s_\phi \) errors around the hole perimeter during the data collection. Despite the limited accuracy at small radii, the residuals for the extended wings at larger radii are low and we believe the kernel fits can be trusted because the 2D fitting is dominated by the larger areas where the radii are large.

5. Discussion

The wavefront aberrations are quite significant, corresponding to a Strehl ratio of \(~75\%\). The structure of the estimated wavefronts (\( M = 231 \)) with their 6- and 12-fold symmetries suggests that the bimorph mirror of the SST AO is responsible. Wavefront aberrations originating in the instrumentation will be at least partly corrected for by our standard MOMFBD image restoration. Part of the wavefront aberrations came from modes of higher order than we normally include in this processing and it is unclear how much of this would be corrected for. With the point-like object used here, the magnitude of the estimated wavefront strongly depends on the number of included modes, \( M \). However, as shown by Scharmer et al. (2010), when the object is solar granulation, the MFBD/PD-type problem is less constrained and an estimated low-order wavefront tends to also represent the blurring caused by the higher-order modes that are not included.

The aberrations give stray light that is mostly contained in the first diffraction rings of \( s_\phi \), 90% of the energy is within a radius of \( 0.6'' \) (see Fig. 9). The origin of this surprisingly high level of wavefront errors is unknown. One possible source is the mounting of the 1 mm thick deformable mirror, which is
Fig. 9: Fit results, angular averages of the masked images, centered on the 1 mm hole. Beam and $M$ as noted in the plot legends. Black: observed image; gray (in the red plots): blue observed image; brown: binary image convolved with $s_\theta$ estimated with $M = 231$; Other colors: binary image convolved with $s_\theta$ as well as $s_K$ fitted with kernels as listed.

Table 5: Scattering kernel fit results

| $M$ | Kernel  | $c$  | Kernel parameters | FWHM | $\chi^2$ | $c$  | Kernel parameters | FWHM | $\chi^2$ |
|-----|---------|-----|-------------------|------|---------|-----|-------------------|------|---------|
| 36  | Gauss   | 99.8| $\sigma = 8.31$  | 197/6| 0.0143  | 99.9| $\sigma = 13.74$ | 32/4 | 0.0595  |
| 36  | Lorentz | 99.6| $\gamma = 6.61$ | 137/2| 0.0142  | 99.7| $\gamma = 17.78$| 35/6 | 0.0595  |
| 36  | Moffat  | 99.7| $\alpha = 9.03$ | $\beta = 1.36$ | 147/7| 0.0142  | 99.9| $\alpha = 416.03$| $\beta = 458.67$ | 32/4 | 0.0595  |
| 36  | Voigt   | 99.7| $\sigma = 3.98$ | $\gamma = 4.23$ | 147/7| 0.0141  | 99.9| $\sigma = 13.64$ | $\gamma = 0.0008$ | 32/1 | 0.0595  |
| 231 | Gauss   | 99.8| $\sigma = 8.77$ | 207/6| 0.0148  | 99.9| $\sigma = 14.61$ | 34/4 | 0.0593  |
| 231 | Lorentz | 99.6| $\gamma = 7.38$ | 148/7| 0.0147  | 99.6| $\gamma = 19.83$| 39/7 | 0.0593  |
| 231 | Moffat  | 99.7| $\alpha = 11.04$| $\beta = 1.56$ | 16/5  | 0.0147  | 99.9| $\alpha = 524.28$| $\beta = 644.53$ | 34/4 | 0.0593  |
| 231 | Voigt   | 99.7| $\sigma = 4.59$ | $\gamma = 4.26$ | 16/1  | 0.0147  | 99.9| $\sigma = 14.39$ | $\gamma = 0.0008$| 33/9 | 0.0593  |

Notes. $M$ is the max KL index used in PD. The parameters $\alpha$, $\gamma$, and $\sigma$ are in units of arcsec, while $\beta$ is dimensionless. The $c$ parameter is the percentage of the intensity that is not contained within the far wings.

clamped between two O-rings with the tension adjusted manually by 12 screws. Another possibility is high-order aberrations induced by a large focus error imposed on the mirror.

[Scharmer et al. (2011)] see the supporting online material) compared umbra intensity and granulation contrast in 630 nm SST data to data from SOT/Hinode and inferred a 50% straylight level with a small FWHM of less than 2", consistent with this straylight originating from aberrations. However, the aberrations measured here can only account for about 1/3 of the 50% straylight and would have to be stronger by a factor 2 than those measured here to fully explain the contrast in the observed granulation data.

Our best estimate of the scattering PSF, $s_K$, is that it generates only 0.3% straylight in the blue (~397 nm) and 0.1% in the red (~630 nm). In our best fits, the FWHM of the scattering kernel $K$ is ~16" in the blue and ~34" in the red, using the Voigt and Moffat kernels. The Gauss and Lorentz kernel fits give similar results.
It is common to truncate the wings of the scattering kernels at some radius but our fits work well without truncation, possibly because we are including the dark level \( d \) in the fit. We cannot exclude that some pollution from the holes \( B \sim F \) influenced the \( s_k \) fits. A better straylight target should have only the 1 mm hole and the smallest hole.

After the ordinary dark-current calibrations, which consist of a subtraction of an average dark frame, the dark level was manipulated in various ways. For PD processing, we estimated and subtracted \( \sim 10^{-8} \) of the intensity in hole A from the subfield containing hole F, measured basically as the modal value within the PD processing subfield. Before the straylight kernel fitting, we also subtracted on the order of \( \sim 10^{-9} \) based on the top 10 rows of pixels. Because the kernel fitting involved a dark level, \( d \), which was estimated to \( \sim 10^{-6} \), we can be reasonably sure that the standard dark-correction is correct to the \( 10^{-4} \) level. However, this is insignificant in comparison with the ghost images, the most significant of which could be measured to \( \sim 1\% \) of the hole A intensity. Consequently, we have to allow for an additive component at the \( \sim 10^{-2} \) level, which is not modeled by the scattering kernels.

6. Conclusions

We have proposed a procedure for measuring the amount of straylight in the SST post-focus instrumentation and applied it to one wavelength in the blue beam and one wavelength in the red beam. The strength of the method is that we simultaneously measured wavefront aberrations (with phase diversity methods) and “conventional” scattered light from the same data. Thus, we were able to separate these two sources of straylight.

The dominant contributions to straylight are high-order aberrations, causing a reduction of the Strehl ratio. The estimated Strehl ratio at 390, 500 and 630 nm is 66%, 75%, and 82%, resp., corresponding to integrated straylight within a radius of \( \sim 0.6 \) on the order of 34%, 25%, and 18%, resp. The second most important source of straylight is multiple weak, out-of-focus ghost images. The combined effect of these is difficult to estimate but most likely contributes less than a few percent at all wavelengths. The smallest contribution measured is from “conventional” straylight in the form of a PSF with very wide wings (16" in the blue, 34" in the red), this is estimated to contribute 0.3% in the blue beam and 0.1% in the red.

The wavefront contribution could potentially be higher when observing the Sun because of the heat that affects the mirror. Considering the small number of optical surfaces and the high optical quality of the SST telescope optics, other main contributions to the lowered contrast most likely are of atmospheric origin. This could come partly from uncorrected high-order wavefront aberrations, as discussed by Schärmer et al. (2010), and partly from scattering by dust particles in the Earth’s atmosphere.

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Note added in proof In October 2011 we were upgrading the wavefront sensor of the SST AO system. We found that switching off the mirror voltages results in a change in the science focus by approximately 9 cm along the optical axis. Due to limited electrode resolution, deformable mirrors cannot produce even low-order modes perfectly. When such a large focus has to be compensated for, there are therefore unavoidable high-order wavefront errors. We have simulated our setup and calculated the wavefront phase corresponding to the difference between a 9 cm defocus and the approximate focus produced by the mirror in order to compensate for it. The resulting RMS wavefront is 0.14 waves at 500 nm and the corresponding Strehl ratio is 0.48. This is even worse than the effects reported in Table 1 by a factor 1.6 in RMS wavefront.

We note again that these measurements (and simulations) are not directly comparable to solar observations. Nevertheless, this effect may well contribute by a significant amount to the loss of contrast in SST data. The SST optical setup will be modified to take into account when we install our new 85-electrode deformable mirror during the summer or fall of 2012. Before that, we will also try to compensate for the effect by introducing a corresponding focus change in the Schupmann system.

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