The $q$-Dixon–Anderson integral and multi-dimensional $1\psi_1$ summations

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Abstract

The Dixon–Anderson integral is a multi-dimensional integral evaluation fundamental to the theory of the Selberg integral. The $1\psi_1$ summation is a bilateral generalization of the $q$-binomial theorem. It is shown that a $q$-generalization of the Dixon–Anderson integral, due to Evans, and multi-dimensional generalizations of the $1\psi_1$ summation, due to Milne and Gustafson, can be viewed as having a common origin in the theory of $q$-difference equations as expounded by Aomoto. Each is shown to be determined by a $q$-difference equation of rank one, and a certain asymptotic behavior. In calculating the latter, essential use is made of the concepts of truncation, regularization and connection formulae.

2010 Mathematical Subject Classification. Primary 33D05, 33D67, 33D70; Secondary 39A13

Keywords. Dixon–Anderson integral; Evans’s $q$-integral; Ramanujan’s $1\psi_1$ summation formula; Milne–Gustafson sum; Gustafson’s $A_n$ sum; Aomoto method; connection formulae;

1 Introduction

The Selberg integral is a multi-dimensional generalization of the Euler beta integral [42]. As surveyed in [18], after a dormant period of over thirty years since its discovery in the early 1940’s, it shot into prominence upon the realization of its relevance to random matrix theory, the combinatorics of root systems, and orthogonal polynomials in many variables, amongst other topics of contemporary interest. In 1991 Anderson [1] gave a new proof of the Selberg integral by deriving a certain recurrence in the number of integral variables $n$. At the heart of this proof was a further multi-dimensional integral

\[
\int_{x_n=x_{n-1}}^{x_n} \cdots \int_{x_2=x_1}^{x_2} \int_{x_1=x_0}^{x_1} \prod_{i=1}^{n} \prod_{j=0}^{n} |z_i - x_j|^{s_j-1} \prod_{1 \leq k < l \leq n} (z_l - z_k) \, dz_1 \, dz_2 \cdots \, dz_n
\]

\[
= \frac{\Gamma(s_0)\Gamma(s_1)\cdots\Gamma(s_n)}{\Gamma(s_0 + s_1 + \cdots + s_n)} \prod_{0 \leq i < j \leq n} (x_j - x_i)^{s_i + s_j - 1}. \tag{1.1}
\]

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For many years it was thought that (1.1) was itself a new gamma function evaluation of a multi-dimensional integral. However it was to transpire that (1.1) in fact was first derived in a paper of Dixon [15] written over eighty five years earlier (see [18] for the history of how Dixon’s paper was rediscovered in the modern era).

One line of research generated by the Selberg integral was the study of \( q \)-generalizations. Askey [11] conjectured the evaluation, in terms of \( q \)-gamma functions, of several multi-dimensional Jackson integrals which reduce to the Selberg integral in the limit \( q \to 1 \). Evans [16, 17] showed how two of these could be proved by adopting the strategy of Anderson. This of course required a \( q \)-generalization of (1.1). Evans [16, Theorem 1, (2.5), p.759] derived the sought \( q \)-generalization as

\[
\int_{x_n=x_{n-1}}^{x_n} \cdots \int_{z_2=x_1}^{x_2} \int_{z_1=x_0}^{x_1} \prod_{i=0}^{n-1} \prod_{j=1}^{n} (q z_i/x_j; q)_{s_j-1} \prod_{1 \leq k \leq l \leq n} (z_l - z_k) \, dqz_1 dqz_2 \cdots dqz_n
\]

\[
= \frac{\Gamma_q(s_0) \Gamma_q(s_1) \cdots \Gamma_q(s_n)}{\Gamma_q(s_0 + s_1 + \cdots + s_n)} \prod_{0 \leq i \leq j \leq n} x_j (x_i/x_j; q)_{s_j} (q x_j/x_i; q)_{s_i-1}. \tag{1.2}
\]

We will refer to (1.2) as the \( q \)-Dixon–Anderson integral.

Independent of the work of Anderson, Gustafson [21] invented the same strategy of using an auxiliary multi-dimensional integral (nowadays referred to as a type I \( q \)-hypergeometric integral) to prove a product of \( q \)-gamma functions evaluation of a different generalization of the Selberg integral (type II \( q \)-hypergeometric integral relating to the \( BC_n \) root system; the original Selberg integral relates to the \( A_{n-1} \) root system). To implement this strategy Gustafson had to formulate and prove an appropriate \( BC_n \) version of the \( q \)-Dixon–Anderson integral [22]. But this was prior to the work of Evans, so (1.2) was unknown. Rather the knowledge base of Gustafson included his earlier work [20], generalizing a result of Milne [34], to give the product form evaluation of the bilateral sum

\[
\sum_{y_1, \ldots, y_n = -\infty}^{\infty} \prod_{1 \leq i \leq j \leq n} \frac{(z_i q^{y_i} - z_j q^{y_j})}{z_i - z_j} \prod_{i, j = 1}^{n} \frac{(a_i z_j/z_i)^{y_i}}{(b_i z_j/z_i)^{y_j}}. \tag{1.3}
\]

As noted in [20], the case \( n = 1 \) of (1.3) is the definition of the \( 1/\psi_1 \) series, and thus the product form evaluation of (1.3) corresponds to a multi-dimensional generalization of the Ramanujan \( 1/\psi_1 \) summation theorem. We will refer to (1.3) as the Milne–Gustafson summation.

In this paper we will show that (1.2) and the product form evaluation of (1.3) are intimately related. The relationship is seen by seeking an explanation for the product expressions from the viewpoint of \( q \)-difference systems. One hint of a common underpinning comes from (1.2) and (1.3) both permitting generalizations involving Macdonald polynomials. Thus it was pointed out in [19] that the case \( s_0 = \cdots = s_n = s \) corresponds to Okounkov’s [37] integral formula for the Macdonald polynomials \( P_\kappa(x_0, \ldots, x_n; q, q^s) \) in the case \( \kappa = 0 \). On the other hand one viewpoint of (1.3) is as a multi-dimensional \( 1/\psi_1 \) summation associated to the root system \( A_{n-1} \) (see e.g. [36] and references therein), and such generalized hypergeometric function identities allow natural generalizations to include Macdonald polynomials [32, 12].

We remark that an elliptic analogue of the Milne–Gustafson summation is due to Kajihara–Noumi [31], and Rosengren [40, 41], independently. In these references a specialization of (1.3) is generalized to involve elliptic analogues of the \( q \)-products, and the resulting summation
is further more extended to an elliptic analogue of Kajihara’s $q$-transformation identity [30] between a summation over $n$ variables and a summation over $m$ variables. This gives another hint of a relationship between (1.2) and the product form evaluation of (1.3). Thus in the original paper of Dixon [15] the Dixon–Anderson integral (1.1) is generalized to a transformation identity between an $n$ and an $m$-dimensional multi-dimensional integral. And in proving a conjectured elliptic generalization of the Selberg integral due to van Diejen and Spiridonov [14], Rains [38] has proved a transformation identity between multi-dimensional elliptic integrals, which he has subsequently [39] shown permits under certain limiting operations a reduction to original transformation identity of Dixon.

We will discuss three multi-dimensional bilateral series,

(1) the Milne–Gustafson summation formula (Theorem 3.1),

(2) a multi-dimensional bilateral extension of Evans’s $q$-Dixon–Anderson integral (Theorem 4.1),

(3) the product expression for a slightly extended case of Gustafson’s $A_n$ sum contained in [20], itself generalizing the Milne–Gustafson summation (Theorem 5.2).

The sum of the case (1) connects the sums of (2) and (3) as a hub. As already mentioned, the aim of this paper is to give an explanation for the formulae of product expression of these sums from a view point of $q$-difference equations.

The method for proving these results is consistent with the concept introduced by Aomoto and Aomoto–Kato in the early 1990’s in the series of papers [3, 4, 5, 6, 7, 8, 9, 10]. Aomoto showed an isomorphism between a class of the Jackson integrals of hypergeometric type, which he called the $q$-analog de Rham cohomology [3, 4], and a class of theta functions, i.e., holomorphic functions possessing a quasi-periodicity [6, Theorem 1]. This isomorphism indicates that it is essential to analyze the class of holomorphic functions as a counterpart of that of the Jackson integrals in order to know the structure of $q$-hypergeometric functions, in particular, the meaning of known special formulae. In this paper the process to obtain the holomorphic functions through this isomorphism is called the regularization. When we fix a basis of the class of holomorphic functions as a linear space, an arbitrary function of the space can be expressed as a linear combination of the elements of the specific basis, which he called the connection formula [6, Theorem 3]. (As its simplest examples, Ramanujan’s $1 \psi_1$ summation formula and the $q$-Selberg integral [11, 23, 29, 16] have been explained. See [6, Examples 1, 2].) One way to choose a good basis is to fix it by its asymptotic behavior of a limiting process with respect to parameters included in the definition of the Jackson integral of hypergeometric type. And the asymptotic behavior can be calculated from the Jackson integrals possessing appropriate cycles which include their critical points. We call the process to fix the cycles the truncation. (These cycles are called the characteristic cycles [10] or the $\alpha$-stable or $\alpha$-unstable cycles [5] by Aomoto. The meaning of “$\alpha$” is mentioned in Section 3. The word truncation itself is first used by van Diejen in other context [13, 25].) The connection formula is also characterized as a formula showing that a multi-dimensional bilateral series as a general solution of the $q$-difference equation of the Jackson integrals with respect to parameters is expressed as a linear combination of multi-dimensional unilateral series as special solutions, each fixed by their asymptotic behaviors [5, Theorem (4.2)]. (We can see different examples of $q$-difference equations and the connection formulae from this paper in [26, 27, 28], and [28]
explains the Sears–Slater transformation for the very-well-poised $q$-hypergeometric series from the view point of this paper in the setting of $BC$ type symmetry.) We discuss three product formulae for the Jackson integrals corresponding to the sums of (1), (2) and (3) as a simple example of this concept.

This paper is organized as follows. After defining basic terminology in Section 2, we first show the product expression of the Milne–Gustafson sum using concepts of truncation, regularization and connection formulae in Section 3. Though the Milne–Gustafson sum can be obtained from our other two examples, we explain it individually, because the Milne–Gustafson sum has simpler structure than the other two, and it is instructive in outlining the concept of this paper. The subsequent two sections are devoted to explaining Evans’s $q$-Dixon–Anderson integral and Gustafson’s $A_n$ sum, respectively. The situation of these two cases looks a little more complex than the case of the Milne–Gustafson sum in their details, but still it is consistent with the outlines of the proofs for the product expressions of these sums. Specifically in section 4 we introduce a bilateral extension of Evans’s $q$-Dixon–Anderson integral and use the method of $q$-difference equations to deduce its product formula evaluation. In section 5, in order to understand the $q$-difference equations of Gustafson’s $A_n$ sum, we need to use an extension of the sum, though the difference of appearance is very slight. However, that hair’s-breadth extension is crucial from technical view point of this paper. In reading sections 3 to 5, a repetition of the main steps needed to implement the $q$-difference equation method will become apparent.

2 Definition of the Jackson integral

Throughout this paper, we fix $q$ as $0 < q < 1$ and use the symbols $(a)_\infty := \prod_{i=0}^{\infty} (1-q^i a)$ and $(a)_N := (a)_\infty / (q^N a)_\infty$. We define $\theta(a)$ by $\theta(a) := (a)_\infty (q/a)_\infty$, which satisfies

$$\theta(qa) = -\theta(a)/a.$$ (2.1)

Let $S_n$ be the symmetric group on $\{1, 2, \ldots, n\}$. For a function $f(z) = f(z_1, z_2, \ldots, z_n)$ on $(\mathbb{C}^*)^n$, we define action of the symmetric group $S_n$ on $f(z)$ by

$$(\sigma f)(z) := f(\sigma^{-1}(z)) = f(z_{\sigma(1)}, z_{\sigma(2)}, \ldots, z_{\sigma(n)}) \quad \text{for} \quad \sigma \in S_n.$$ We say that a function $f(z)$ on $(\mathbb{C}^*)^n$ is symmetric or skew-symmetric if $\sigma f(z) = f(z)$ or $\sigma f(z) = (\text{sgn} \sigma) f(z)$ for all $\sigma \in S_n$, respectively. We denote by $A f(z)$ the alternating sum over $S_n$ defined by

$$(Af)(z) := \sum_{\sigma \in S_n} (\text{sgn} \sigma) \sigma f(z),$$ (2.2)

which is skew-symmetric.

For $a, b \in \mathbb{C}$, we define

$$\int_a^b f(z)dz := \int_0^b f(z)dz - \int_0^a f(z)dz,$$ (2.3)

where

$$\int_0^a f(z)dz := (1-q) \sum_{\nu=0}^{\infty} f(aq^\nu)aq^\nu.$$


which is called the *Jackson integral*. As \( q \to 1 \), \( \int_{a}^{b} f(z) d_q z \to \int_{a}^{b} f(z) dz \) [2]. In this paper we basically use the Jackson integral of multiplicative measure as
\[
\int_{0}^{a} f(z) \frac{d_q z}{z} = (1 - q) \sum_{\nu = 0}^{\infty} f(aq^{\nu}).
\]

Let \( \mathbb{N} \) be the set of non-negative integers. For a function \( f(z) = f(z_1, \ldots, z_n) \) on \((\mathbb{C}^*)^n\) and an arbitrary point \( x = (x_1, \ldots, x_n) \in (\mathbb{C}^*)^n\), we define the multiple Jackson integral as
\[
\int_{0}^{x} f(z) \frac{d_q z_1}{z_1} \wedge \cdots \wedge \frac{d_q z_n}{z_n} := (1 - q)^n \sum_{(\nu_1, \ldots, \nu_n) \in \mathbb{N}^n} f(x_1 q^{\nu_1}, \ldots, x_n q^{\nu_n}). \tag{2.4}
\]

In this paper we use the multiple bilateral sum extending the above Jackson integral
\[
\int_{0}^{x} f(z) \frac{d_q z_1}{z_1} \wedge \cdots \wedge \frac{d_q z_n}{z_n} := (1 - q)^n \sum_{(\nu_1, \ldots, \nu_n) \in \mathbb{Z}^n} f(x_1 q^{\nu_1}, \ldots, x_n q^{\nu_n}), \tag{2.5}
\]

which we also call the *Jackson integral*. By definition the Jackson integral (2.5) is invariant under the shift \( x_i \rightarrow qx_i, 1 \leq i \leq n \). While we can consider the limit \( q \to 1 \) for the Jackson integral (2.4) defined over \( \mathbb{N}^n \), the Jackson integral (2.5) defined over \( \mathbb{Z}^n \) generally diverges if \( q \to 1 \). However, as we will see later, since the truncation of the Jackson integral (2.5) is corresponding to the sum (2.4) over \( \mathbb{N}^n \), if we need to consider the limit \( q \to 1 \), we switch from (2.5) to (2.4) by the process of the truncation.

We will state one of the key lemmas of this paper for deriving \( q \)-difference equations. For this let \( \Phi(z) \) be a symmetric function on \((\mathbb{C}^*)^n\) and for a function \( \varphi(z) \), define the function \( \nabla_i \varphi(z) \) (1 \( \leq i \leq n \)) by
\[
(\nabla_i \varphi)(z) := \varphi(z) - \frac{T_{z_i} \Phi(z)}{\Phi(z)} T_{z_i} \varphi(z), \tag{2.6}
\]
where \( T_{z_i} \) means the shift operator of \( z_i \to qz_i \), i.e., \( T_{z_i} f(\ldots, z_i, \ldots) = f(\ldots, qz_i, \ldots) \). We then have

**Lemma 2.1** For a meromorphic function \( \varphi(z) \) on \((\mathbb{C}^*)^n\), if the integral
\[
\int_{0}^{x} \varphi(z) \Phi(z) \frac{d_q z_1}{z_1} \wedge \cdots \wedge \frac{d_q z_n}{z_n}
\]
converges, then
\[
\int_{0}^{x} \varphi(z) \nabla_i \varphi(z) \frac{d_q z_1}{z_1} \wedge \cdots \wedge \frac{d_q z_n}{z_n} = 0. \tag{2.7}
\]
Moreover,
\[
\int_{0}^{x} \varphi(z) A \nabla_i \varphi(z) \frac{d_q z_1}{z_1} \wedge \cdots \wedge \frac{d_q z_n}{z_n} = 0, \tag{2.8}
\]
where \( A \) indicates the skew-symmetrization defined in (2.2).
Proof. From the definition (2.6) of \( \nabla_i \), (2.7) is equivalent to the statement
\[
\int_0^{\infty} \phi(z) \Phi(z) \frac{d_q z_1}{z_1} \land \cdots \land \frac{d_q z_n}{z_n} = \int_0^{\infty} T_{x_i} \phi(z) T_{z_i} \Phi(z) \frac{d_q z_1}{z_1} \land \cdots \land \frac{d_q z_n}{z_n},
\]
if the left-hand side converges. And this equation is just confirmed from the fact that the Jackson integral is invariant under the \( q \)-shift \( z_i \to q z_i (1 \leq i \leq n) \). Next we will confirm (2.8). Using \( \sigma \Phi(z) = \Phi(z) \), we have
\[
\Phi(z) \Delta_i \phi(z) = \Phi(z) \sum_{\sigma \in S_n} (\text{sgn } \sigma) \sigma(\nabla_i \phi)(z) = \sum_{\sigma \in S_n} (\text{sgn } \sigma) \sigma \Phi(z) \sigma(\nabla_i \phi)(z)
\]
so that we obtain
\[
\int_0^{\infty} \Phi(z) \Delta_i \phi(z) \frac{d_q z_1}{z_1} \land \cdots \land \frac{d_q z_n}{z_n} = \sum_{\sigma \in S_n} (\text{sgn } \sigma) \int_0^{\infty} \sigma \left( \Phi(z) \Delta_i \phi(z) \right) \frac{d_q z_1}{z_1} \land \cdots \land \frac{d_q z_n}{z_n}
\]
\[
= \sum_{\sigma \in S_n} (\text{sgn } \sigma) \int_0^{\sigma^{-1} \infty} \Phi(z) \Delta_i \phi(z) \frac{d_q z_1}{z_1} \land \cdots \land \frac{d_q z_n}{z_n} = \sum_{\sigma \in S_n} (\text{sgn } \sigma) \int_0^{\infty} \Phi(z) \Delta_i \phi(z) \frac{d_q z_1}{z_1} \land \cdots \land \frac{d_q z_n}{z_n},
\]
which vanishes from (2.7). □

3 Jackson integral of Milne–Gustafson type

In this section, we will explain the methods of this paper using the Milne–Gustafson summation formula.

3.1 Definitions and the result

Let \( a_1, \ldots, a_n, b_1, \ldots, b_n \) and \( \alpha \) be the complex numbers satisfying
\[
|q a_1^{-1} \cdots a_n^{-1} b_1^{-1} \cdots b_n^{-1}| < |q| < 1. \tag{3.1}
\]
Let \( \Phi(z) \) and \( \Delta(z) \) be the functions defined by
\[
\Phi(z) := (z_1 z_2 \cdots z_n)^{\alpha} \prod_{i=1}^{n} \prod_{j=1}^{n} \frac{(q a_j^{-1} z_i)}{(b_j z_i)} \tag{3.2}
\]
and
\[
\Delta(z) := \prod_{1 \leq i < j \leq n} (z_j - z_i). \tag{3.3}
\]

For \( x = (x_1, x_2, \ldots, x_n) \in (\mathbb{C}^*)^n \), we define the sum \( I(x) \) by
\[
I(x) := \int_0^{\infty} \Phi(z) \Delta(z) \frac{d_q z_1}{z_1} \land \cdots \land \frac{d_q z_n}{z_n}, \tag{3.4}
\]
which converges absolutely under the condition (3.1) (see [20, Lemma 3.19], [35, Lemma 2.5]). We call \( I(x) \) the Jackson integral of Milne–Gustafson type. By definition \( I(x) \) is skew-symmetric.
Theorem 3.1 (Milne–Gustafson [20, 34]) For an arbitrary \( x \in (\mathbb{C}^*)^n \), \( I(x) \) is evaluated as

\[
I(x) = (1 - q)^n \frac{\left( q^{\alpha} \prod_{i=1}^{n} (1 - q^{a_i - 1} b_i^{-1} z_i) \right)_{\infty}}{\left( q^{\alpha} \prod_{j=1}^{n} (1 - q^{1 - \alpha a_j^{-1} a_j^{-1} b_j^{-1} \cdot \cdot \cdot b_j^{-1})_{\infty} \right)_{\infty} \times \prod_{i=1}^{n} \prod_{j=1}^{n} \frac{\theta(q^{a_i x_i} z_i b_j)}{\theta(x_i b_j)}} \prod_{1 \leq i < j \leq n} x_j \theta(x_i, x_j).
\]

(3.5)

Remark. If \( n = 1 \), (3.5) coincides with Ramanujan’s \( 1 \psi_1 \) summation theorem. In this sense, (3.5) is a natural multi-dimensional extension of \( 1 \psi_1 \) sum. On the other hand, if \( q \to 1 \), the limiting formula of a special case of (3.5) coincides with the Dixon–Andersen integral (1.1) with \( x_0 = 0 \), as we will see in Remark after Corollary 3.4. In this sense, the Milne–Gustafson sum is a natural extension of both quantities.

The rest of this section is devoted to explaining the Milne–Gustafson summation formula (3.5) as a connection formula between solutions of a \( q \)-difference equation, and consequently this leads us to a simple proof.

3.2 \( q \)-difference equation with respect to \( \alpha \)

In this subsection we derive the \( q \)-difference equation with respect to \( \alpha \), which \( I(x) \) satisfies. We use \( I(\alpha; x) \) instead of \( I(x) \) to see the \( \alpha \) dependence.

Lemma 3.2 The recurrence relation for \( I(\alpha; x) \) is given by

\[
I(\alpha; x) = \frac{1 - q^{a_i x_i} a_i a_2 \cdot \cdot \cdot a_n b_1 b_2 \cdot \cdot \cdot b_n}{a_i a_2 \cdot \cdot \cdot a_n (1 - q^a)} I(\alpha + 1; x).
\]

(3.6)

Proof. Since the ratio \( T_{z_1} \Phi(z)/\Phi(z) \) is written as

\[
\frac{T_{z_1} \Phi(z)}{\Phi(z)} = q^\alpha \prod_{j=1}^{n} \frac{1 - b_j z_1}{1 - q a_j^{-1} z_1},
\]

if we put \( \varphi(z) = z_2^{-1} z_3^{-n-2} \cdot \cdot \cdot z_n \prod_{j=1}^{n} (1 - a_j^{-1} z_1) \), then, from (2.6) we have

\[
\nabla_1 \varphi(z) = z_2^{-1} z_3^{-n-2} \cdot \cdot \cdot z_n \left( \prod_{j=1}^{n} (1 - a_j^{-1} z_1) - q^\alpha \prod_{j=1}^{n} (1 - b_j z_1) \right),
\]

so that the skew-symmetrization of the above equation is given by

\[
\mathcal{A} \nabla_1 \varphi(z) = \left( (-1)^n (-1 - q^a) + (-1)^n \frac{1 - q^{a_1 a_2 \cdot \cdot \cdot a_n b_1 b_2 \cdot \cdot \cdot b_n}}{a_1 a_2 \cdot \cdot \cdot a_n} \right) \Delta(z).
\]

(3.7)

Since

\[
I(\alpha + 1; x) = \int_0^{x \infty} \frac{z_1 z_2 \cdot \cdot \cdot z_n \Phi(z) \Delta(z)}{z_1 \wedge \cdot \cdot \cdot \wedge z_n} \frac{d_1 z_1}{z_1} \wedge \cdot \cdot \cdot \wedge \frac{d_n z_n}{z_n},
\]

using (2.8) of Lemma 2.1 for (3.7), we obtain the relation (3.6). □
3.3 Truncation

For the special point \( x = a = (a_1, a_2, \ldots, a_n) \), we call \( I(a) \) the truncated Jackson integral of Milne–Gustafson type. By definition \( I(a) \) is a sum over \( \mathbb{N}^n \), while \( I(x) \) is generally the sum over the lattice \( \mathbb{Z}^n \). It has the advantage of simplifying the computation of the \( \alpha \to +\infty \) asymptotic behavior, as will be seen below. (The lattice \( \{ (x_1 q^a, \ldots, x_n q^a) \in (\mathbb{C}^*)^n ; (\nu_1, \ldots, \nu_n) \in \mathbb{Z}^n \} \) is called the \( q \)-cycle \([4]\) of \( I(x) \), while the set \( \{ (a_1 q^a, \ldots, a_n q^a) \in (\mathbb{C}^*)^n ; (\nu_1, \ldots, \nu_n) \in \mathbb{N}^n \} \) as the support of \( I(a) \) is called the \( \alpha \)-stable cycle in \([5, 10]\).)

**Lemma 3.3** The asymptotic behavior of \( I(\alpha + N; a) \) as \( N \to +\infty \) is given by

\[
I(\alpha + N; a) \sim (1 - q)^n (a_1 a_2 \cdots a_n)^{\alpha + N} \Delta(a) \prod_{i=1}^{\infty} \prod_{j=1}^{\infty} \frac{(qa_i/a_j)^\infty}{(a_i b_j)^\infty} (N \to +\infty). \tag{3.8}
\]

**Proof.** Since \( (q^{1+\nu_i}) = 0 \) if \( \nu_i < 0 \), by definition \( I(a) \) is written as

\[
I(\alpha + N; a) = (1 - q)^n \sum_{(\nu_1, \ldots, \nu_n) \in \mathbb{N}^n} (a_1 a_2 \cdots a_n q^{\nu_1 + \cdots + \nu_n})^{\alpha + N} \prod_{i=1}^{\infty} \prod_{j=1}^{\infty} \frac{(a_j^{-1} a_i q^{1+\nu_i})^\infty}{(b_j a_i q^{\nu_i})^\infty} \prod_{1 \leq i < j \leq n} (a_j q^{\nu_j} - a_i q^{\nu_i}),
\]

so that the leading term of the asymptotic behavior of \( I(\alpha + N; a) \) as \( N \to +\infty \) is given by the term corresponding to \( (\nu_1, \ldots, \nu_n) = (0, \ldots, 0) \) in the above sum, which is (3.8). □

From this lemma, with repeated use of Lemma 3.2, we immediately have

**Corollary 3.4** The truncated Jackson integral \( I(a) \) is expressed as

\[
I(a) = (1 - q)^n (a_1 a_2 \cdots a_n)^\alpha \frac{(q^a)^n (a_1 a_2 \cdots a_n b_1 b_2 \cdots b_n)^\infty}{(a_1 a_2 \cdots a_n)^N (q^a)^N} \prod_{1 \leq i < j \leq n} a_j \theta(a_i/a_j). \tag{3.9}
\]

**Proof.** By repeated use of the recurrence relation (3.6), we have

\[
I(\alpha; x) = \frac{(q^a a_1 a_2 \cdots a_n b_1 b_2 \cdots b_n)^N}{(a_1 a_2 \cdots a_n)^N (q^a)^N} I(\alpha + N; x).
\]

If we put \( x = a \) and take \( N \to +\infty \), we obtain

\[
I(\alpha; a) = \frac{(q^a a_1 a_2 \cdots a_n b_1 b_2 \cdots b_n)^N}{(q^a)^N} \lim_{N \to \infty} \frac{I(\alpha + N; a)}{(a_1 a_2 \cdots a_n)^N},
\]

which coincides with the right-hand side of (3.9) if we use (3.8). □

**Remark.** If \( n = 1 \), (3.9) coincides with the \( q \)-binomial theorem which is a special case of Ramanujan’s \( \psi_1 \) summation theorem. The truncated Jackson integral \( I(a) \) is the sum over \( \mathbb{N}^n \) by definition, and the definition of this case coincides with that of the ordinary Jackson integral explained by (2.4). Therefore we can consider the limiting case of (3.9) as \( q \to 1 \). If we substitute \( \alpha, a_j \) and \( b_j \) as \( \alpha \to s_0, a_j \to x_{j-1} \) and \( b_j \to q^{s_j-1}/x_{j-1} \), respectively, then (3.9) in the limit \( q \to 1 \) coincides with the Dixon–Anderson integral (1.1) with \( x_0 = 0 \).
3.4 Regularization and connection formulae

Let \( I(x) \) and \( h(x) \) be the functions defined by

\[
I(x) = \frac{I(x)}{h(x)}, \quad h(x) = (x_1x_2 \cdots x_n)^{a_1} \prod_{1 \leq i < j \leq n} x_j \theta(x_i/x_j) \prod_{i=1}^{n} \prod_{j=1}^{n} \theta(b_jx_i). \tag{3.10}
\]

We call \( I(x) \) the regularized Jackson integral of \( I(x) \). Since the trivial poles and zeros of \( I(x) \) are canceled out by multiplying together \( 1/h(x) \) and \( I(x) \), we have the following.

**Lemma 3.5** The regularization \( I(x) \) is holomorphic on \((\mathbb{C}^*)^n\) and symmetric.

**Proof.** From the expression (3.2) of \( \Phi(z) \) as integrand of (3.4), the function \( I(x) \) has the poles lying only in the set \( \{ x = (x_1, x_2, \ldots, x_n) \in (\mathbb{C}^*)^n : \prod_{i=1}^{n} \prod_{j=1}^{n} \theta(b_jx_i) \} \). Moreover \( I(x) \) is divisible by \( x_j \theta(x_i/x_j) \) because \( I(x) \) is skew-symmetric. We therefore obtain

\[
I(x) = I(x)h(x),
\]

where \( I(x) \) is some holomorphic function on \((\mathbb{C}^*)^n\). Since \( I(x) \) and \( h(x) \) are both skew-symmetric, \( I(x) \) is symmetric. \( \square \)

From (3.10) and the quasi-periodicity (2.1) of the theta function, we have

\[
\frac{T_{x_i}h(x)}{h(x)} = -q^a x_1 x_2 \cdots x_nb_1 b_2 \cdots b_n.
\]

And since \( I(x) \) is an invariant under the \( q \)-shift \( x_i \to qx_i \), the holomorphic function \( I(x) \) on \((\mathbb{C}^*)^n\) satisfies the \( q \)-difference equations

\[
T_{x_i}I(x) = -\frac{I(x)}{q^a x_1 x_2 \cdots x_nb_1 b_2 \cdots b_n}, \quad i = 1, 2, \ldots, n. \tag{3.11}
\]

Since the set of holomorphic functions on \((\mathbb{C}^*)^n\) satisfying (3.11) has the dimension 1 as a \( \mathbb{C} \)-linear space, we can take \( \theta(q^a x_1 x_2 \cdots x_nb_1 b_2 \cdots b_n) \) as a basis of the linear space. Thus \( I(x) \) is uniquely expressed as

\[
I(x) = C \theta(q^a x_1 x_2 \cdots x_nb_1 b_2 \cdots b_n), \tag{3.12}
\]

where \( C \) is some constant independent of \( x \).

**Lemma 3.6 (connection formula)** For an arbitrary \( x, y \in (\mathbb{C}^*)^n \), the connection formula between \( I(x) \) and \( I(y) \) is written as

\[
I(x) = \frac{\theta(q^a x_1 x_2 \cdots x_nb_1 b_2 \cdots b_n)}{\theta(q^a y_1 y_2 \cdots y_nb_1 b_2 \cdots b_n)} I(y). \tag{3.13}
\]

In particular, if we set \( y = a \in (\mathbb{C}^*)^n \), then

\[
I(x) = \frac{\theta(q^a x_1 x_2 \cdots x_nb_1 b_2 \cdots b_n)}{\theta(q^a a_1 a_2 \cdots a_nb_1 b_2 \cdots b_n)} I(a). \tag{3.14}
\]
Remark. If we switch the symbols from $\mathcal{I}(x)$ to $I(x)$, we have

$$I(x) = \frac{h(x)\theta(q^a x_1 x_2 \cdots x_n b_1 b_2 \cdots b_n)}{h(y)\theta(q^a y_1 y_2 \cdots y_n b_1 b_2 \cdots b_n)} I(y).$$

In particular, if we set $y = a$ in the above equation, we obtain

$$I(x) = \frac{h(x)\theta(q^a x_1 x_2 \cdots x_n b_1 b_2 \cdots b_n)}{h(a)\theta(q^a a_1 a_2 \cdots a_n b_1 b_2 \cdots b_n)} I(a),$$

which is also the connection formula between a solution $I(x)$ of the $q$-difference equation (3.6) and the special solution $I(a)$ fixed by its asymptotic behavior (3.8) as $\alpha \to +\infty$. In addition, its connection coefficient is written as a ratio of theta functions (i.e., that of $q$-gamma functions), and is of course invariant under the shift $\alpha \to \alpha + 1$. Using the evaluation (3.9) of $I(a)$, the connection formula (3.15) exactly coincides with (3.5) for the Milne–Gustafson sum.

Using (3.9), the constant $C$ in (3.12) is also calculated explicitly as

$$C = \frac{I(a)}{h(a)\theta(q^a a_1 a_2 \cdots a_n b_1 b_2 \cdots b_n)} = \frac{(1 - q)^n(q^n_\infty \prod_{i=1}^n (q a_i^{-1} b_j^{-1})_\infty)}{(q^\alpha)_\infty (q^{1 - \alpha} a_1^{-1} b_1^{-1} \cdots a_n^{-1} b_n^{-1})_\infty}. \quad (3.16)$$

From (3.12) we therefore obtain

Proposition 3.7 For an arbitrary $x \in (\mathbb{C}^*)^n$, $\mathcal{I}(x)$ is expressed as

$$\mathcal{I}(x) = (1 - q)^n (q^n_\infty \prod_{i=1}^n (q a_i^{-1} b_j^{-1})_\infty) \theta(q^\alpha x_1 \cdots x_n b_1 \cdots b_n). \quad (3.17)$$

Since (3.5) is equivalent to (3.17), the Milne–Gustafson summation formula as the expression (3.17) gives the isomorphism between the sets of $I(x)$ and of theta functions defined by (3.11).

If we set

$$\beta := 1 - \alpha_1 - \cdots - \alpha_n - \beta_1 - \cdots - \beta_n - \alpha, \quad (3.18)$$

where $\alpha_i$ and $\beta_i$ are given by $a_i = q^{\alpha_i}$, $b_i = q^{\beta_i}$, after rearrangement, the formula (3.17) is also expressed as the following Macdonald-type sum, whose value is given by an $x$-independent constant [33, 13, 24].

Proposition 3.8 Under the condition $a_1 \cdots a_n b_1 \cdots b_n q^{a+\beta} = q$,

$$\int_0^{x_\infty} \frac{\prod_{i=1}^n (q a_i^{-1} z_i)_\infty (q b_j^{-1} z_i)_\infty}{(q^\alpha a_1 \cdots a_n z_1^{-1} \cdots z_n^{-1}) (q^\alpha b_1 \cdots b_n z_1 \cdots z_n) \prod_{1 \leq i < j \leq n} (q z_i / z_j)_\infty (q z_j / z_i)_\infty} \times d_q z_1 \wedge \cdots \wedge d_q z_n = \frac{(1 - q)^n (q^n_\infty \prod_{i=1}^n (q a_i^{-1} b_i^{-1})_\infty)}{(q^\alpha)_\infty (q^{\beta})_\infty}, \quad (3.19)$$

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Proof. Since $h(x)\theta(q^n x_1 \cdots x_n b_1 \cdots b_n)$ is invariant under the $q$-shift $x_i \rightarrow qx_i$, from (3.12), we have

$$\int_0^\infty \Phi(z) \Delta(z) \frac{d_q z_1}{z_1} \wedge \cdots \wedge \frac{d_q z_n}{z_n} = C,$$

so that

$$\int_0^\infty \prod_{i=1}^n \prod_{j=1}^n (qa_j^{-1} z_i)_0 (qb_j^{-1} z_i)_0 \prod_{1 \leq i < j \leq n} (qz_i/z_j)_0 \prod_{1 \leq i < j \leq n} (qz_i/z_j)_0 \frac{d_q z_1}{z_1} \wedge \cdots \wedge \frac{d_q z_n}{z_n} = C,$$

which is rewritten as (3.19) using (3.16) under the condition (3.18). □

As a corollary, it is confirmed that the following identity for a contour integral is equivalent to the formula (3.19) of the special case $x = a \in \mathbb{C}^n$.

**Corollary 3.9** Let $\mathbb{T}^n$ be the the direct product of the unit circle, i.e., $\mathbb{T}^n := \{(z_1, \ldots, z_n) \in \mathbb{C}^n ; |z_i| = 1\}$. Suppose that $|a_i| < 1$, $|b_i| < 1$ ($i = 1, \ldots, n$) and $a_1 \cdots a_n b_1 \cdots b_n q^{a+b} = q$. Then

$$\left(\frac{1}{2\pi i\sqrt{-1}}\right)^n \frac{1}{n!} \int_{\mathbb{T}^n} \frac{(q^a a_1 \cdots a_n z_1^{-1} \cdots z_n^{-1})_0 (q^b b_1 \cdots b_n z_1 \cdots z_n)_0}{\prod_{i=1}^n \prod_{j=1}^n (a_i z_j^{-1})_0 (b_i z_j)_0} \prod_{1 \leq i < j \leq n} (z_i/z_j)_0 (z_j/z_i)_0 \frac{dz_1}{z_1} \cdots \frac{dz_n}{z_n} = \frac{(q^{1-a})_0 (q^{1-b})_0}{(q)_0 \prod_{i=1}^n \prod_{j=1}^n (a_i b_j)_0}.$$

**Proof.** By residue calculation using (3.19) of the case $x = a \in \mathbb{C}^n$. □

### 3.5 Dual expression of the Jackson integral $I(x)$

For an arbitrary $x = (x_1, x_2, \ldots, x_n) \in (\mathbb{C}^*)^n$ we specify $x^{-1}$ as

$$x^{-1} := (x_1^{-1}, x_2^{-1}, \ldots, x_n^{-1}) \in (\mathbb{C}^*)^n.$$

(3.20)

For the point $b = (b_1, b_2, \ldots, b_n) \in (\mathbb{C}^*)^n$, if we set $y = b^{-1}$ in the connection formula (3.13), then we obtain the expression

$$\mathcal{I}(x) = \frac{\theta(q^a x_1 x_2 \cdots x_n b_1 b_2 \cdots b_n)}{\theta(q^n)} \mathcal{I}(b^{-1}).$$

(3.21)

Since $x = b^{-1}$ is a pole of the function $I(x)$ by definition, $I(b^{-1})$ no longer makes sense. However, the regularization $\mathcal{I}(b^{-1})$ appearing on the right-hand side of (3.21) still has meaning as a special value of a holomorphic function. We will show a way to realize the regularization $\mathcal{I}(b^{-1})$ as a computable object by another Jackson integral. For this purpose, let $\Phi(z)$ and $\Delta(z)$ be the functions specified by

$$\Phi(z) := (z_1 z_2 \cdots z_n)^{1-\alpha_1-\cdots-\alpha_n-\beta_1-\cdots-\beta_n-\alpha} \prod_{i=1}^n \prod_{j=1}^n (q b_j^{-1} z_i)_0 (a_j z_i)_0.$$

(3.22)
where $\alpha_i$ and $\beta_i$ are given by $a_i = q^{\alpha_i}, b_i = q^{\beta_i},$ and

$$\Delta(z) := \prod_{1 \leq i < j \leq n} (z_i - z_j).$$

(3.23)

For $x = (x_1, x_2, \ldots, x_n) \in (\mathbb{C}^*)^n,$ we define the sum $\bar{I}(x)$ by

$$\bar{I}(x) := \int_0^{x \cdot \infty} \Phi(z) \Delta(z) \frac{d_q z_1}{z_1} \wedge \cdots \wedge \frac{d_q z_n}{z_n},$$

(3.24)

which converges under the condition (3.1). We call $\bar{I}(x)$ the dual Jackson integral of $I(x),$ and call $\bar{I}(b)$ its truncation. (The sum $I(x)$ transforms to its dual $\bar{I}(x)$ up to sign if we interchange the parameters as

$$\alpha \leftrightarrow \beta \quad \text{and} \quad a_i \leftrightarrow b_i \ (i = 1, \ldots, n),$$

(3.25)

where $\beta$ is specified by (3.18).) We also define the regularization $\bar{\mathcal{I}}(x)$ of $\bar{I}(x)$ as

$$\bar{\mathcal{I}}(x) := \frac{\bar{I}(x)}{h(x)}, \quad \text{where} \quad h(x) = (x_1 x_2 \cdots x_n)^{1-\alpha_1 - \cdots - \alpha_n - \beta_1 - \cdots - \beta_n - \alpha} \prod_{1 \leq i < j \leq n} x_i \theta(x_j/x_i) / \prod_{i=1}^n \prod_{j=1}^n \theta(a_j x_i).$$

(3.26)

In the same manner as Lemma 3.5, we can confirm that the function $\bar{\mathcal{I}}(x)$ is also holomorphic and symmetric.

**Lemma 3.10 (reflection equation)** The connection between $I(x)$ and $\bar{I}(x)$ is

$$I(x) = \frac{h(x)}{h(x^{-1})} \bar{I}(x^{-1}), \quad \text{where} \quad \frac{h(x)}{h(x^{-1})} = \prod_{i=1}^n \prod_{j=1}^n x_i^{1-\alpha_j - \beta_j} \theta(q a_j^{-1} x_i) / \theta(b_j x_i),$$

(3.27)

where $x^{-1}$ is specified as in (3.20). In other words, the relation between $\mathcal{I}(x)$ and $\bar{\mathcal{I}}(x)$ is

$$\mathcal{I}(x) = \bar{\mathcal{I}}(x^{-1}).$$

(3.28)

**Proof.** From the definitions (3.10) and (3.26) the ratio $h(x)/\bar{h}(x^{-1})$ is written as in (3.27).

Since $\Delta(z) = (z_1 z_2 \cdots z_n)^{n-1} \Delta(z^{-1}),$ from (3.2), (3.3), (3.22) and (3.23), we have

$$\Phi(z) \Delta(z) = \frac{h(z)}{h(z^{-1})} \Phi(z^{-1}) \Delta(z^{-1}).$$

(3.29)

Also since $h(z)/\bar{h}(z^{-1})$ is invariant under the shift $z_i \rightarrow q z_i,$ by the definitions (3.4) and (3.24) of $I(x)$ and $\bar{I}(x),$ the connection (3.27) between $I(x)$ and its dual $\bar{I}(x)$ is derived from (3.29). □

We use $\bar{I}(\alpha; x)$ instead of $\bar{I}(x)$ to see the $\alpha$ dependence. From (3.27), the recurrence relation for $\bar{I}(\alpha; x)$ is completely the same as (3.6) of $I(\alpha; x)$.

**Lemma 3.11** The function $\bar{I}(\alpha; x)$ also satisfies the recurrence relation (3.6) of $I(\alpha; x),$ and is rewritten as

$$\bar{I}(\alpha; x) = \frac{1 - q^{1-\alpha}}{b_1 b_2 \cdots b_n (1 - q^{-\alpha} a_1^{-1} a_2^{-1} \cdots a_n^{-1} b_1 \cdots b_n)} \bar{I}(\alpha - 1; x).$$

(3.30)
Corollary 3.12  The asymptotic behavior of \( \bar{I}(\alpha - N; b) \) as \( N \to +\infty \) is written as
\[
\bar{I}(\alpha - N; b) \sim (1 - q)^n (b_1 \cdots b_n)^{1 - \alpha_1 - \cdots - \alpha_n - \beta_1 - \cdots - \beta_n - \alpha + N} \\
\times \Delta(b) \prod_{i=1}^{n} \prod_{j=1}^{n} (qb_i/b_j)_{\infty} (N \to +\infty). \tag{3.31}
\]
Moreover, by repeated use of (3.30), the truncated Jackson integral \( \check{I}(b) \) is written as
\[
\check{I}(b) = \frac{(1 - q)^n (b_1 \cdots b_n)^{1 - \alpha_1 - \cdots - \alpha_n - \beta_1 - \cdots - \beta_n - \alpha}(q_{\infty}^{1-a})_{\infty}}{(q^{1-a_1} \cdots q^{1-b_1^{1} \cdots b_n^{1}})_{\infty} \prod_{i=1}^{n} \prod_{j=1}^{n} (a_i b_j)^{\infty}} \prod_{1 \leq i < j \leq n} b_i \theta(b_j/b_i). \tag{3.32}
\]

Proof. Using Lemma 3.11, the arguments are completely parallel to Lemma 3.3 and Corollary 3.4. Actually, if we substitute \( a_j, b_j \) and \( \alpha \) in \( \Phi(z) \) of (3.2) by \( a_j \to b_j, b_j \to a_j \) and \( \alpha \to \beta = 1 - \alpha_1 - \cdots - \alpha_n - \beta_1 - \cdots - \beta_n - \alpha \), respectively, then \( \Phi(z) \) transforms to \( \check{\Phi}(z) \) in (3.22), so that we obtain the same result as Corollary 3.4 with these substitutions. \( \square \)

From (3.13) and (3.28), for \( x, y \in (\mathbb{C}^\ast)^n \) we have the connection formula between \( \mathcal{I}(x) \) and \( \check{\mathcal{I}}(y) \) as
\[
\mathcal{I}(x) = \frac{\theta(q^\alpha x_1 x_2 \cdots x_n b_1 b_2 \cdots b_n)}{\theta(q^\alpha y_1 y_2 \cdots y_n b_1 b_2 \cdots b_n)} \check{\mathcal{I}}(y).
\]
In particular, if \( y = b \), then we have
\[
\mathcal{I}(x) = \frac{\theta(q^\alpha x_1 x_2 \cdots x_n b_1 b_2 \cdots b_n)}{\theta(q^\alpha)} \check{\mathcal{I}}(b).
\]
If we switch the symbols from \( \mathcal{I}(x) \) and \( \check{\mathcal{I}}(b) \) to \( I(x) \) and \( \check{I}(b) \), respectively, then we obtain
\[
I(x) = \frac{h(x) \theta(q^\alpha a_1 a_2 \cdots a_n b_1 b_2 \cdots b_n)}{h(b) \theta(q^\alpha)} \check{I}(b). \tag{3.33}
\]
We once again obtain the connection formula between a solution \( I(x) \) of the \( q \)-difference equation (3.6) and the special solution \( \check{I}(b) \) fixed by its asymptotic behavior (3.31) as \( \alpha \to -\infty \), as a counterpart of the formula (3.15) of the case \( \alpha \to +\infty \).

The connection formula (3.33) with (3.32) is also another expression for the Milne–Gustafson sum, like the formula (3.15).

Remark. As we have seen above, we used the integrand \( \check{\Phi}(z) \) instead of \( \Phi(z) \), which coincides with \( \check{\Phi}(z) \) up to the \( q \)-periodic factor \( h(z)/h(z^{-1}) \), and used the set \( \{b_1 q^{\alpha_1}, \ldots, b_n q^{\alpha_n}\} \in \mathbb{C}^\ast \) for the argument of the \( q \)-difference equation (3.6).
(C∗)n; (ν1, . . . , νn) ∈ Nn} as the “(−α)-stable cycle” for the dual integral Ĩ(x) when we construct a special solution Ĩ(b) expressed by (Jackson) integral representation for the q-difference equation (3.6) as α → −∞. In the classical setting, this process is usually done by taking an imaginary cycle without changing the integrand Φ(z) under the ordinary integral representation. In the q-analog setting Aomoto and Aomoto–Kato used the integral representation without changing the integrand Φ(z), but instead, they adopted the residue sum on the set \{((b−1q−ν1), . . . , b−1q−νn) ∈ (C∗)n; (ν1, . . . , νn) ∈ Nn\} of poles of I(x). They call this cycle the α-unstable cycle [5, 10] of I(x) for the parameter α. To carry out this process is called the regularization in their original paper [3]. We hope our slight changes of terminology does not bring confusion to the reader.

4 Jackson integral of Dixon–Anderson type

In this section we use q-difference equations to show a proof of Evans’s summation formula for q-Dixon–Anderson integral introducing a multi-dimensional bilateral extension of his sum, which we call the Jackson integral of Dixon–Anderson type. In addition, as a limiting case, the Milne–Gustafson summation formula is deduced from it. In this sense, the Jackson integral of Dixon–Anderson type as a q-analog of the integral (1.1) can also be regarded as a natural multi-variable extension of Ramanujan’s 1ψ1 sum.

4.1 Definitions and the results

Let a1, a2, . . . , an+1, b1, b2, . . . , bn+1 be the complex numbers satisfying

\[ q < |a_1a_2 \cdots a_{n+1}b_1b_2 \cdots b_{n+1}|. \]  \hspace{1cm} (4.1)

Let Φ(z) be specified by

\[ Φ(z) := z_1z_2 \cdots z_n \prod_{i=1}^{n+1} \frac{(qa_jz_i)_{∞}}{(b_jz_i)_{∞}}, \]  \hspace{1cm} (4.2)

cf. (3.2)) and let ∆(z) be specified by (3.3). For \( x = (x_1, x_2, \ldots, x_n) \in (C^*)^n \), we define the sum \( J(x) \) by

\[ J(x) := \int_0^{x_{∞}} Φ(z) \Delta(z) \frac{dz_1}{z_1} \wedge \cdots \wedge \frac{dz_n}{z_n}, \]  \hspace{1cm} (4.3)

which converges absolutely under the condition (4.1) (cf. [20, Lemma 3.19], [35, Lemma 2.5]). We call \( J(x) \) the Jackson integral of Dixon–Anderson type. By definition \( J(x) \) is skew-symmetric.

For an arbitrary point \((x_1, x_2, . . . , x_{n+1}) \in (C^*)^{n+1}\), we set the point \((\tilde{x}_i)\) of \((C^*)^n\) by

\[ (\tilde{x}_i) := (x_1, . . . , x_{i-1}, x_{i+1}, . . . , x_{n+1}) \in (C^*)^n \quad \text{for} \quad i = 1, 2, . . . , n + 1. \]

The main result of this section is the following:
Theorem 4.1 For the function $J(x)$ on $(\mathbb{C}^*)^n$ as a sum over $\mathbb{Z}^n$,
\[
\sum_{i=1}^{n+1}(-1)^{i-1}J(\tilde{x}_i) = C_0 \frac{\theta(x_1x_2 \cdots x_{n+1}b_1b_2 \cdots b_{n+1})}{\prod_{i=1}^{n+1} \prod_{j=1}^{n+1} \theta(x_ib_j)} \prod_{1 \leq i < j \leq n+1} x_j \theta(x_i/x_j),
\] (4.4)
where $C_0$ is a constant independent of $(x_1, x_2, \ldots, x_{n+1}) \in (\mathbb{C}^*)^{n+1}$, which is explicitly written as
\[
C_0 = (1-q)^n (q^n a_0 \cdots a_{n+1} b_1 b_2 \cdots b_{n+1}) \prod_{1 \leq i < j \leq n+1} a_j \theta(a_i/a_j).
\] (4.5)

Proof. From the denominator of integrand (4.2), we see the poles of $J(x)$ are included in the set of zero points of $\prod_{i=1}^{n+1} \prod_{j=1}^{n+1} \theta(x_ib_j)$. Since the sum $\sum_{i=1}^{n+1}(-1)^{i-1}J(\tilde{x}_i)$ is skew-symmetric with respect to the permutation of $\{x_1, x_2, \ldots, x_{n+1}\}$, it is divisible by $\prod_{1 \leq i < j \leq n+1} x_j \theta(x_i/x_j)$. We therefore obtain
\[
\sum_{i=1}^{n+1}(-1)^{i-1}J(\tilde{x}_i) = f(x) \frac{\prod_{1 \leq i < j \leq n+1} x_j \theta(x_i/x_j)}{\prod_{i=1}^{n+1} \prod_{j=1}^{n+1} \theta(x_ib_j)},
\] (4.6)
where $f(x) = f(x_1, x_2, \ldots, x_{n+1})$ is some holomorphic function on $(\mathbb{C}^*)^{n+1}$. Since the left-hand side of (4.6) is an invariant under the $q$-shift $x_i \rightarrow qx_i$, taking account of the quasi-periodicity (2.1) of the function on the right-hand of (4.6), we have that the holomorphic function $f(x)$ must satisfy
\[
T_{x_i} f(z) = -\frac{f(x)}{x_1x_2 \cdots x_{n+1}b_1b_2 \cdots b_{n+1}} \quad \text{for} \quad i = 1, 2, \ldots, n+1.
\]
This equation has the unique holomorphic solution up to constant, and is written as
\[
f(x) = C_0 \theta(x_1x_2 \cdots x_{n+1}b_1b_2 \cdots b_{n+1}),
\]
where $C_0$ is some constant independent of $x_1, x_2, \ldots, x_{n+1}$. Therefore we obtain the expression (4.4). The explicit evaluation of the constant $C_0$ in (4.5) will be given in Subsection 4.5. □

We call $J(\tilde{a}_i)$ ($i = 1, 2, \ldots, n+1$) the truncated Jackson integral, which is defined as a sum over $\mathbb{N}^n$. As a special case of Theorem 4.1, we immediately have the following:

Corollary 4.2 (Evans [16]) The truncated Jackson integral $J(\tilde{a}_i)$ satisfies
\[
\sum_{i=1}^{n+1}(-1)^{i-1}J(\tilde{a}_i) = (1-q)^n (q^n a_0 \cdots a_{n-1}b_1 b_2 \cdots b_{n+1}) \prod_{1 \leq i < j \leq n+1} a_j \theta(a_i/a_j).
\] (4.7)

Remark. If we substitute $a_j$ and $b_j$ as $a_j \rightarrow x_{j-1}$ and $b_j \rightarrow q^{s_j-1}x_{j-1}$, respectively, then (4.7) is directly rewritten by the ordinary iterated Jackson integral (2.3) according to
\[
\int_{x_n=x_{n-1}}^{x_n} \cdots \int_{x_2=x_1}^{x_2} \int_{x_1=x_0}^{x_1} \prod_{j=0}^{n} (q^{s_j}z_j/x_j)_{\infty} \Delta(z) d_q z_1 d_q z_2 \cdots d_q z_n = (1-q)^n \prod_{0 \leq i < j \leq n} \frac{x_j \theta(x_i/x_j)}{(x_iq^{s_j}/x_j)_{\infty}(x_jq^{s_i}/x_i)_{\infty}},
\] (4.8)
which exactly coincides with the formula (1.2) established by Evans. Since (4.8) is already proved in [16], logically speaking, the constant $C_0$ of (4.4) in Theorem 4.1 can conversely be evaluated as (4.5) if we use (4.7), which is equivalent to (4.8), after putting $(z_1, \ldots, z_{n+1}) = (a_1, \ldots, a_{n+1})$ on the equation (4.4). The argument in [16] to prove (4.8) was done under the restriction on $s_i$ as positive integers. As is already pointed out in [16], by analytic continuation $s_i$ can be considered as complex numbers after proving (4.8) in the setting $s_i$ are integers. But here we prefer to start without restrictions on the parameters being integers, and we would like to choose another way for the evaluation of $C_0$ in keeping with our viewpoint. Our method then is based on regarding $J(x)$ as a solution of $q$-difference equations fixed by its asymptotic behavior. Thus, in this paper, (4.7) is consequently obtained as a corollary via Theorem 4.1.

The rest of subsections are mainly devoted to the evaluation of the constant $C_0$ as (4.5) in Theorem 4.1, which we will see in Subsection 4.5. In addition, considering the dual expression $\bar{J}(x)$ of the integral $J(x)$, we can regard the Jackson integral of Milne–Gustafson type as a limiting case of that of Dixon–Anderson type. (Consequently, we have a proof of the Milne–Gustafson sum again using the Jackson integral of Dixon–Anderson type, see Corollary 4.7.) In this sense, the Jackson integral of Dixon–Anderson type as a $q$-analog of the integral (1.1) can also be regarded as a natural multi-dimensional extension of Ramanujan’s $1\psi_1$ sum.

For the above purposes we first state the $q$-difference equations for the regularization and the dual expression of $J(x)$.

### 4.2 $q$-difference equations

Let $\Phi(z)$ be specified by

$$
\bar{\Phi}(z) := (z_1z_2 \cdots z_n)^{1-\alpha_1-\cdots-\alpha_{n+1}-\beta_1-\cdots-\beta_{n+1}} \prod_{i=1}^{n+1} \prod_{j=1}^{n+1} \frac{(q b_j z_i)^{\infty}}{(a_j z_i)^{\infty}},
$$

(cf. (3.22)) where $\alpha_i$ and $\beta_i$ are given by $a_i = q^{\alpha_i}, b_i = q^{\beta_i}$, and let $\bar{\Delta}(z)$ be specified by (3.23). For $x = (x_1, x_2, \ldots, x_n) \in (C^*)^n$, we define the sum $\bar{J}(x)$ by

$$
\bar{J}(x) := \int_0^{X^\infty} \bar{\Phi}(z) \bar{\Delta}(z) \frac{d_q z_1}{z_1} \wedge \cdots \wedge \frac{d_q z_n}{z_n},
$$

which converges under the condition (4.1). We call $\bar{J}(x)$ the dual Jackson integral of $J(x)$. By definition $\bar{J}(x)$ is skew-symmetric. For the specific points

$$
x = (\hat{b}_i) = (b_1, \ldots, b_{i-1}, b_{i+1}, \ldots, b_{n+1}) \in (C^*)^n, \quad i = 1, 2, \ldots, n + 1,
$$

we call $\bar{J}(\hat{b}_i)$ the truncated Jackson integral, which is defined as a sum over $N^n$.

Let $J(x)$ and $h(x)$ be the functions defined by

$$
J(x) := \frac{J(x)}{h(x)}, \quad \text{where} \quad h(x) = x_1 x_2 \cdots x_n \prod_{1 \leq i < j \leq n} x_j \theta(x_i/x_j) \prod_{i=1}^{n+1} \prod_{j=1}^{n+1} \theta(b_j x_i),
$$

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which we call the regularization of $J(x)$. We also define the regularization $\tilde{J}(x)$ of $\tilde{J}(x)$ according to

$$\tilde{J}(x) := \frac{\tilde{J}(x)}{h(x)}, \quad \text{where} \quad \tilde{h}(x) = (x_1 x_2 \cdots x_n)^{1-\alpha_1-\cdots-\alpha_{n+1}-\beta_1-\cdots-\beta_{n+1}} \prod_{1 \leq i < j \leq n} x_i \theta(x_j/x_i) \prod_{i=1}^{n+1} \prod_{j=1}^{n+1} \theta(a_j x_i).$$

(4.12)

Since the trivial poles and zeros of $J(x)$ are canceled out by multiplying together $1/h(x)$ and $\tilde{J}(x)$, the function $J(x)$ is holomorphic on $\mathbb{C}^*$, and $\tilde{J}(x)$ is symmetric. In the same manner, the function $\tilde{J}(x)$ is also holomorphic and symmetric.

**Lemma 4.3 (reflection equation)** The connection between $J(x)$ and $\tilde{J}(x)$ is

$$J(x) = \frac{h(x)}{\tilde{h}(x^{-1})} \tilde{J}(x^{-1}), \quad \text{where} \quad \frac{h(x)}{\tilde{h}(x^{-1})} = \prod_{i=1}^{n+1} \prod_{j=1}^{n+1} x_i^{1-\alpha_j-\beta_j} \theta(qa_j^{-1} x_i) \theta(b_j x_i),$$

(4.13)

where $x^{-1}$ is specified as in (3.20). In other words, the relation between $J(x)$ and $\tilde{J}(x)$ is

$$J(x) = \tilde{J}(x^{-1}).$$

(4.14)

**Proof.** The proof is the same as that of Lemma 3.10 in Section 3. □

We now state the $q$-difference equations for $\tilde{J}(x)$ or $\tilde{J}(x)$ under the setting $x = (\tilde{b}_i), i = 1, 2, \ldots, n+1$.

**Proposition 4.4** Suppose $x = (\tilde{b}_i), i = 1, 2, \ldots, n+1$. Then the recurrence relations for $\tilde{J}(x)$ are given by

$$T_{a_j} \tilde{J}(x) = (-a_j)^n \prod_{i=1}^{n+1} (1 - b_i^{-1} a_j^{-1}) \tilde{J}(x) \quad \text{and} \quad T_{b_j} \tilde{J}(x) = (-b_j^{-1})^n \prod_{i=1}^{n+1} (1 - a_i b_j) \tilde{J}(x)$$

(4.15)

for $j = 1, 2, \ldots, n+1$. The recurrence relations for $\tilde{J}(x)$ are given by

$$T_{a_j} \tilde{J}(x) = \prod_{i=1}^{n+1} (1 - b_i^{-1} a_j^{-1}) \tilde{J}(x) \quad \text{and} \quad T_{b_j} \tilde{J}(x) = \prod_{i=1}^{n+1} (1 - a_i b_j^{-1}) \tilde{J}(x).$$

(4.16)

for $j = 1, 2, \ldots, n+1$.

The rest of this subsection is devoted to the proof of the above proposition. Let $e(c; z)$ be the symmetric polynomial of degree $n$ defined by

$$e(c; z) := \prod_{i=1}^{n} (1 - c^{-1} z_i),$$

(4.17)

which has a property that $e(c; z)$ vanishes for $z_i = c$. 

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Lemma 4.5 If we put \( \varphi(z) \) as
\[
\varphi(z) = z_1^{-1} \prod_{i=1}^{n+1} (b_i - z_1) \times \prod_{1 \leq j < k \leq n} (z_k - b_j),
\]
then \( A\nabla_1 \varphi(z) \) is expanded as
\[
A\nabla_1 \varphi(z) = \left( c_0 + c_1 \frac{e(b_1; z)}{z_1 z_2 \cdots z_n} \right) \Delta(z),
\]
where the constants \( c_0 \) and \( c_1 \) are given by
\[
c_0 = -b_1^{-1} a_1^{-1} \cdots a_n^{-1} \prod_{i=1}^{n+1} (1 - a_i b_1), \quad c_1 = (-b_1)^n a_1^{-1} \cdots a_n^{-1} (1 - \prod_{i=1}^{n+1} a_i b_1).
\]

**Proof.** From (4.9), the ratio \( \frac{T_{z_1} \bar{\Phi}(z)}{\Phi(z)} \) is written as
\[
\frac{T_{z_1} \bar{\Phi}(z)}{\Phi(z)} = q \prod_{j=1}^{n+1} \frac{a_j - z_1}{b_j - q z_1}.
\]
From (2.6), for the function \( \varphi(z) \) defined in (4.18) we have
\[
\nabla_1 \varphi(z) = z_1^{-1} \left( \prod_{i=1}^{n+1} (b_i - z_1) - \prod_{i=1}^{n+1} (a_i^{-1} - z_1) \right) \prod_{1 \leq j < k \leq n} (z_k - b_j) = \frac{\varphi'(z)}{z_1 z_2 \cdots z_n}
\]
where
\[
\varphi'(z) = \left( \prod_{i=1}^{n+1} (b_i - z_1) - \prod_{i=1}^{n+1} (a_i^{-1} - z_1) \right) z_2 z_3 \cdots z_n \prod_{1 \leq j < k \leq n} (z_k - b_j).
\]
Since \( A\nabla_1 \varphi(z) = A\varphi'(z)/z_1 z_2 \cdots z_n \), for the purpose of proving (4.19) it suffices to show that
\[
A\varphi'(z) = (c_0 z_1 z_2 \cdots z_n + c_1 e(b_1; z)) \Delta(z).
\]
Taking account of the degree of \( \varphi'(z) \) as a polynomial of \( z \), we can expand the skew-symmetrization \( A\varphi'(z) \) as
\[
A\varphi'(z) = \left( c_0 z_1 z_2 \cdots z_n + \sum_{i=1}^{n} c_i e(b_i; z) \right) \Delta(z),
\]
where the coefficients \( c_i \) \( (i = 0, 1, \ldots, n) \) are some constants. Here we will confirm that \( c_i \) vanishes if \( i \geq 2 \), and \( c_0 \) and \( c_1 \) are evaluated as (4.20).
First we take \( z_1 = b_1, z_2 = b_2, \ldots, z_n = b_n \). Then, from (4.21) and (4.23) with the vanishing property of \( e(b_i; z) \), we have two ways of expression of \( A\varphi'(z) \),
\[
A\varphi'(a) = -\prod_{i=1}^{n+1} (a_i^{-1} - b_1) \times b_2 b_3 \cdots b_n \Delta(z) = c_0 b_1 b_2 \cdots b_n \Delta(z).
\]
Thus we obtain $$c_0 = -b_1^{-1} \prod_{i=1}^{n+1} (a_i^{-1} - b_1) = -b_1^{-1} a_1^{-1} \cdots a_{n+1}^{-1} \prod_{i=1}^{n+1} (1 - a_i b_1).$$

Next we take $$z_1 = b_1, z_2 = b_2, \ldots, z_{n-1} = b_{n-1}$$ and $$z_n \notin \{ b_1, b_2, \ldots, b_{n+1} \}.$$ Then, from (4.23) and the vanishing property of $$e(a_i; z),$$ we have

$$\mathcal{A} \varphi'(z) = (c_0 b_1 b_2 \cdots b_{n-1} z_n + c_n e(b_n; z)) \Delta(z). \quad (4.24)$$

On the other hand, from (4.21), we have

$$\mathcal{A} \varphi'(z) = - \prod_{i=1}^{n+1} (a_i^{-1} - b_1) \times b_2 b_3 \cdots b_{n-1} z_n \Delta(z) = c_0 b_1 b_2 \cdots b_{n-1} z_n \Delta(z). \quad (4.25)$$

Comparing (4.24) and (4.25), we obtain $$c_n = 0.$$ In the same manner, by symmetry of $$\mathcal{A} \varphi'(z)$$ of $$\varphi'(z)$$ in (4.21), we also obtain $$c_i = 0$$ if $$i \geq 2.$$ Thus we obtain the expansion (4.22).

Lastly, we suppose $$z_1 = 0$$ and $$z_2 = b_2, \ldots, z_n = b_n$$ to determine $$c_1$$ in (4.22). Then we have

$$\mathcal{A} \varphi'(z) = c_1 (-b_1^{-1})^n b_2 b_3 \cdots b_n \prod_{1 \leq j < k \leq n} (b_k - b_j). \quad (4.26)$$

On the other hand, from (4.21), we have

$$\mathcal{A} \varphi'(z) = \left( \prod_{i=1}^{n+1} b_i - \prod_{i=1}^{n+1} a_i^{-1} \right) b_2 b_3 \cdots b_n \prod_{1 \leq j < k \leq n} (b_k - b_j). \quad (4.27)$$

Comparing (4.26) with (4.27), we obtain $$c_1$$ as is expressed in (4.20). \(\square\)

**Proof of Proposition 4.4.** We will prove (4.15) for $$T_{b_1}$$ first. Without loss of generality, it suffices to show that

$$T_{b_1} \tilde{J}(x) = (-b_1^{-1})^n \frac{\prod_{i=1}^{n+1} (1 - a_i b_1)}{1 - \prod_{i=1}^{n+1} a_i b_1} \tilde{J}(x). \quad (4.28)$$

Since we have $$T_{b_1} \Phi(z)/\Phi(z) = \prod_{i=1}^{n} (1 - a_i^{-1} z_i)/z_i = e(a_1; z)/z_1 \cdots z_n$$ by definition, $$T_{b_1} \tilde{J}(x)$$ is expressed by

$$T_{b_1} \tilde{J}(x) = \int_0^{\infty} e(b_1; z) \Phi(z) \Delta(z) \frac{dz_1}{z_1} \wedge \cdots \wedge \frac{dz_n}{z_n}.$$ 

Here we temporarily assume the condition $$1 < |a_1 a_2 \cdots a_{n+1} b_1 b_2 \cdots b_{n+1}|$$ on parameters. Then, under the condition $$x = (\tilde{b}_i), i = 1, 2, \ldots, n+1,$$ the truncated Jackson integral

$$\int_0^{\infty} \varphi(z) \Phi(z) \frac{dz_1}{z_1} \wedge \cdots \wedge \frac{dz_n}{z_n}$$

where $$\varphi(z)$$ is defined by (4.18) converges absolutely. Therefore, applying (2.8) in Lemma 2.1 to the fact (4.19) in Lemma 4.5, we obtain the relation

$$c_0 \tilde{J}(x) + c_1 T_{b_1} \tilde{J}(x) = 0,$$

where $$c_0$$ and $$c_1$$ are given in (4.20). This relation coincides with (4.28). Once we obtain (4.28), the restriction on parameters can be removed by analytic continuation.
Next we will show the \( q \)-difference equation (4.15) for \( T_{a_1} \), of the case \( j = 1 \) in the same manner as above. Since we have \( T_{a_1} \Phi(z)/\Phi(z) = \prod_{i=1}^{n}(1-a_1 z_i)/z_i = e(a_1^{-1}; z)/z_1 z_2 \cdots z_n \), \( T_{a_1} \bar{J}(x) \) is expressed by
\[
T_{a_1} \bar{J}(x) = \int_0^{x_{\infty}} \frac{e(a_1^{-1}; z) \bar{\Phi}(z) \Delta(z)}{z_1 z_2 \cdots z_n} \frac{dz_1}{z_1} \cdots \frac{dz_n}{z_n}.
\]

Here if we exchange \( b_i \) with \( a_i^{-1} \) \((i = 1, 2, \ldots, n + 1)\) in the above proof of (4.28) including that of Lemma 4.5, the way of argument is completely symmetric for this exchange. Therefore (4.15) for \( T_{a_1} \) is obtained exchanging \( b_i \) with \( a_i^{-1} \) on the coefficient of (4.28).

From the expression (4.12) of \( \bar{h}(x) \), under the condition \( x = (\widehat{b}_i) \), \( i = 1, 2, \ldots, n + 1 \), \( \bar{h}(x) \) satisfies
\[
T_{a_j} \bar{h}(x) = (-a_j)^n \bar{h}(x) \quad \text{and} \quad T_{b_j} \bar{h}(x) = \frac{b_j}{b_1 b_2 \cdots b_{n+1}} \bar{h}(x) \quad (j = 1, 2, \ldots, n + 1).
\]

Since \( \bar{J}(x) = \bar{J}(x)/\bar{h}(x) \), from the above equations and (4.15), we therefore obtain (4.16).

\[ \square \]

### 4.3 Evaluation of the truncated Jackson integral

The main result of this subsection is the evaluation of the regularization of the truncated Jackson integral using the \( q \)-difference equations (4.16) in Proposition 4.4 and its asymptotic behavior for the special direction of parameters.

**Theorem 4.6** For \( x = (\widehat{b}_i) \), \( i = 1, 2, \ldots, n + 1 \), the regularized Jackson integral \( \bar{J}(x) \) is evaluated as
\[
\bar{J}(\widehat{b}_i) = (1-q)^n \frac{\Phi_{\infty}(q^n \prod_{k=1}^{n+1}(qa_j^{-1} b^{-1}_k)_{\infty})}{(qa_1^{-1} \cdots a_1^{-1} b_b^{-1} \cdots b_{n+1}^{-1})_{\infty}}.
\]

**Proof.** Without loss of generality, it suffices to show (4.29) in the case \( x = (\widehat{b}_{n+1}) \), i.e., the case \( x = b = (b_1, \ldots, b_n) \in (\mathbb{C}^*)^n \). We denote by \( C \) the right-hand side of (4.29). Then it is immediate to confirm that \( C \) as a function of \( a_j \) and \( b_j \) satisfies the same \( q \)-difference equations as (4.16) of \( \bar{J}(b) \). Therefore the ratio \( \bar{J}(b)/C \) is invariant under the \( q \)-shift with respect to \( a_j \) and \( b_j \).

Next, for an integer \( N \), let \( T^N \) be the \( q \)-shift operator for a special direction defined as
\[
T^N : a_i \to q^{-nN} a_i \quad (i = 1, 2, \ldots, n + 1); \quad b_j \to q^{(n+1)N} b_j \quad (j = 1, 2, \ldots, n); \quad b_{n+1} \to q^{-nN} b_{n+1}.
\]

Then, by definition \( T^N \bar{J}(b) \) is written as
\[
T^N \bar{J}(b) = (1-q)^n \sum_{(\nu_1, \ldots, \nu_n) \in \mathbb{N}^n} (b_1 b_2 \cdots b_n q^{\nu_1 + \cdots + \nu_n + n(n+1)N})_{1-\alpha_1-\cdots-\alpha_n+1-\beta_1-\cdots-\beta_{n+1}+nN} \times \prod_{i=1}^{n} \left( \frac{(b_n^{-1} b_1 q^{1+\nu_1+(2n+1)N})_{\infty}}{(a_n^{-1} b(q^{\nu_n+N})_{\infty}} \right) \prod_{j=1}^{n} \left( \frac{(b_j^{-1} b_1 q^{1+\nu_j})_{\infty}}{(a_j b q^{\nu_j+N})_{\infty}} \right) \prod_{1 \leq i < j \leq n} q^{(\alpha_j+1)N} (b_i q^{\nu_i} - b_j q^{\nu_j}),
\]

\[ \]
On the other hand, from (4.12), \( \bar{\nu} \) term corresponding to (4.12) is also invariant under the \( q \)-shift with respect to \( a_j \) and \( b_j \). Thus \( \bar{\nu} \) is given by the product formula (3.32) for the Milne–Gustafson sum \( \bar{\nu} \). Therefore, comparing (4.30) with (4.31), we obtain

\[
\frac{\bar{\nu}}{C} = \frac{T^N \bar{\nu}(b)}{T^N \bar{h}(b)C} = \lim_{N \to +\infty} \frac{T^N \bar{\nu}(b)}{T^N \bar{h}(b)C} = \lim_{N \to +\infty} \frac{a^{-1} \cdots a^{-1} b^{-1} \cdots b^{-1} q^{1+2nN}}{\prod_{i=1}^{n+1} (a_i^{-1} b_{n+1}^{-1} q^{1+2nN})} = 1,
\]

and thus \( \bar{\nu} = C \). \( \square \)

### 4.4 A remark on the relation between \( \bar{\nu}(b) \) and \( \bar{I}(b) \)

As an application of the \( q \)-difference equations (4.15) for \( \bar{\nu}(x) \), we can show that the product formula (3.32) for the Milne–Gustafson sum \( \bar{I}(b) \) in Corollary 3.12 (or (3.9) of \( I(a) \) in Corollary 3.4 by their duality (3.25) of parameters) is a special case of (4.29) in Theorem 4.6. This indicates a way to prove the Milne–Gustafson summation formula from the product formula of the Jackson integral of Dixon–Anderson type.
Corollary 4.7 For $b = (b_1, b_2, \ldots, b_n)$, the truncated Jackson integral $\bar{J}(b)$ of Dixon–Anderson type is expressed as

$$\bar{J}(b) = \bar{I}(b) \prod_{i=1}^{n} \frac{(qa_i^{-1}b_{n+1})_{\infty}}{(b_i a_{n+1})_{\infty}}, \quad (4.32)$$

where $\bar{I}(b)$ is the truncated Jackson integral of Milne–Gustafson type defined by (3.24) with the setting $\alpha = \alpha_{n+1} + \beta_{n+1}$. In particular, $\bar{I}(b)$ is expressed as (3.32) in Corollary 3.12.

Remark. From (4.32), $\bar{I}(b)$ is a limiting case of $\bar{J}(b)$ with the $q$-shift $a_{n+1} \rightarrow q^N a_{n+1}$ and $b_{n+1} \rightarrow q^{-N} b_{n+1}$ $(N \rightarrow +\infty)$. Conversely, the product formula (4.29) of $\bar{J}(b)$ in Theorem 4.6 is reconstructed from the product formula (3.32) of $\bar{I}(b)$ via the connection (4.32).

Proof. From (4.15) the recurrence relation of $\bar{J}(b)$ with respect to the $q$-shift $a_{n+1} \rightarrow qa_{n+1}$ and $b_{n+1} \rightarrow q^{-1} b_{n+1}$ is written as

$$\bar{J}(b) = T_{b_{n+1}}^{-1} T_{a_{n+1}} \bar{J}(b) \times \prod_{i=1}^{n} \frac{1 - qa_i^{-1} b_{n+1}^{-1}}{1 - b_i a_{n+1}}.$$ 

By repeated use of this equation we have

$$\bar{J}(b) = T_{b_{n+1}}^{-N} T_{a_{n+1}}^{-N} \bar{J}(b) \times \prod_{i=1}^{n} \frac{(qa_i^{-1}b_{n+1})_{N}}{(b_i a_{n+1})_{N}} = \lim_{N \rightarrow \infty} \frac{T_{b_{n+1}}^{-N} T_{a_{n+1}}^{-N} \bar{J}(b) \times \prod_{i=1}^{n} (qa_i^{-1}b_{n+1})_{\infty}}{(b_i a_{n+1})_{\infty}}. \quad (4.33)$$

Moreover, by definition

$$\lim_{N \rightarrow \infty} \frac{T_{b_{n+1}}^{-N} T_{a_{n+1}}^{-N} \bar{J}(b) \times \prod_{i=1}^{n} (qa_i^{-1}b_{n+1})_{\infty}}{(b_i a_{n+1})_{\infty}} = (1 - q)^n \sum_{(\nu_1, \ldots, \nu_n) \in \mathbb{N}^n} (b_1 b_2 \cdots b_n q^{\nu_1 + \cdots + \nu_n}) (1 - \alpha_1 - \cdots - \alpha_{n+1} - \beta_1 - \cdots - \beta_{n+1})$$

$$\times \prod_{i=1}^{n} \frac{(b_{n+1}^{-1} b_i q^{1+\nu_i+N})_{\infty}}{(a_{n+1} b_i q^{\nu_i+N})_{\infty}} \prod_{j=1}^{n} \frac{(b_j^{-1} b_i q^{1+\nu_j})_{\infty}}{(a_j b_i q^{\nu_j})_{\infty}} \prod_{1 \leq i < j \leq n} (b_i q^{\nu_i} - b_j q^{\nu_j}). \quad (4.34)$$

which exactly coincides with the definition of $\bar{I}(b)$ under the setting $\alpha = \alpha_{n+1} + \beta_{n+1}$. From (4.33) and (4.34), we therefore obtain (4.32).
Next, using (4.32), (4.11) and (4.29) of Theorem 4.6, the sum $\bar{I}(b)$ is conversely calculated as

$$
\bar{I}(b) = \prod_{i=1}^{n} \frac{(b_i a_{n+1})_\infty}{(q a_i^{-1} b_{n+1})_\infty} \bar{J}(b) = \prod_{i=1}^{n} \frac{(b_i a_{n+1})_\infty}{(q a_i^{-1} b_{n+1})_\infty} \bar{J}(b) \bar{h}(b)
$$

$$
= \prod_{i=1}^{n} \frac{(b_i a_{n+1})_\infty}{(q a_i^{-1} b_{n+1})_\infty} \times (1 - q)^n \frac{(q)_n}{(q)_\infty} \prod_{i=1}^{n+1} \prod_{j=1}^{n+1} \frac{(q a_i^{-1} b_j^{-1})_\infty}{(q a_i^{-1} b_{n+1}^{-1})_\infty} \prod_{i=1}^{n} \prod_{j=1}^{n+1} \frac{(a_i b_j)_\infty}{(a_i b_{n+1})_\infty} \prod_{1 \leq i < j \leq n} b_i \theta(b_j/b_i),
$$

which exactly coincides with (3.32) of Corollary 3.12 under the setting $\alpha = \alpha_{n+1} + \beta_{n+1}$. □

### 4.5 Evaluation of the constant $C_0$

In this subsection we will evaluate the constant $C_0$ in (4.4) of Theorem 4.1. From the expression (4.4), the constant $C_0$ is conversely written as the sum of functions,

$$
C_0 = \sum_{k=1}^{n+1} (-1)^k g_k(x_1, x_2, \ldots, x_{n+1}), \quad (4.35)
$$

where

$$
g_k(x_1, x_2, \ldots, x_{n+1}) := J(\tilde{x}_k) \frac{\prod_{i=1}^{n+1} \prod_{j=1}^{n+1} \theta(x_i b_j)}{\theta(x_1 x_2 \cdots x_{n+1} b_1 b_2 \cdots b_{n+1}) \prod_{1 \leq i < j \leq n+1} x_j \theta(x_i / x_j)}.
$$

Using (4.11) and (4.14), we have

$$
g_k(x_1, x_2, \ldots, x_{n+1}) = \frac{\bar{J}(\tilde{x}_k^{-1}) h(\tilde{x}_k) \prod_{i=1}^{n+1} \prod_{j=1}^{n+1} \theta(x_i b_j)}{\theta(x_1 x_2 \cdots x_{n+1} b_1 b_2 \cdots b_{n+1}) \prod_{1 \leq i < j \leq n+1} x_j \theta(x_i / x_j)}
$$

$$
= \frac{\bar{J}(\tilde{x}_k^{-1}) x_1 x_{k-1} x_{k+1} \cdots x_n x_{n+1} \prod_{j=1}^{n+1} \theta(x_k b_j)}{\theta(x_1 x_2 \cdots x_{n+1} b_1 b_2 \cdots b_{n+1}) \prod_{i=1}^{k-1} x_i \theta(x_i / x_k) \prod_{j=k+1}^{n+1} x_j \theta(x_k / x_j)}
$$

$$
= (-1)^{k-1} \frac{\bar{J}(\tilde{x}_k^{-1})}{\theta(x_1 x_2 \cdots x_{n+1} b_1 b_2 \cdots b_{n+1}) \prod_{1 \leq i \leq n+1} \theta(x_i / x_i)} \frac{\theta(x_k b_k)}{\prod_{i \neq k} \theta(x_k / x_i)}
$$

Using this and (4.35) shows

$$
C_0 = \sum_{k=1}^{n+1} \frac{\bar{J}(\tilde{x}_k^{-1})}{\theta(x_1 x_2 \cdots x_{n+1} b_1 b_2 \cdots b_{n+1})} \frac{\theta(x_k b_k)}{\prod_{1 \leq i \leq n+1} \theta(x_k / x_i)}. \quad (4.36)
$$

Since $C_0$ is a constant independent of $(x_1, x_2, \ldots, x_{n+1})$, it suffices to calculate the right-hand side of (4.36) in the specific case

$$
x_1 = b_1^{-1}, x_2 = b_2^{-1}, \ldots, x_n = b_n^{-1} \quad \text{and} \quad x_{n+1} \notin \{b_1^{-1}, b_2^{-1}, \ldots, b_n^{-1}\}.
$$
We now impose this condition. Noting \( \theta(x_kb_k) = 0 \) if \( k \neq n + 1 \) we see from (4.36) that

\[
C_0 = \mathcal{J}(\hat{b}_{n+1}) \frac{\theta(x_{n+1}b_{n+1})}{\theta(b_1^{-1}b_2^{-1} \cdots b_n^{-1}x_{n+1}b_1b_2 \cdots b_{n+1})} \prod_{i=1}^{n} \frac{\theta(x_{n+1}b_i)}{\theta(x_{n+1}/b_i^{-1})} = \mathcal{J}(\hat{b}_{n+1}).
\]

Since \( \mathcal{J}(\hat{b}_{n+1}) \) has already evaluated as (4.29) in Theorem 4.6, we obtain \( C_0 \) as is expressed in (4.5) of Theorem 4.1. \( \square \)

\section{Jackson integral of Gustafson’s \( A_n \)-type}

In this section we show a proof for the product formula of Gustafson’s \( A_n \) sum introducing a slight extension of it. As is pointed out in [20], the Milne–Gustafson sum \( I(x) \) can also be deduced from Gustafson’s \( A_n \) sum.

\subsection{Definitions and results}

Let \( a_i, b_i \) (1 \( \leq i \leq n + 1 \)) and \( d \) be complex numbers in \( \mathbb{C}^* \). In this section we define \( \Phi(z) \) and \( \Delta(z) \) by

\[
\Phi(z) := \prod_{i=1}^{n+1} (q a_j^{-1} z_i)_0, \quad \Delta(z) := \prod_{1 \leq i < j \leq n+1} (z_j - z_i), \quad (5.1)
\]

under the condition

\[
z_1 z_2 \cdots z_{n+1} = d. \quad (5.2)
\]

(The functions \( \Phi(z) \) and \( \Delta(z) \) are regarded as a function on \( (\mathbb{C}^*)^n \) of \( n \) variables putting \( z_{n+1} = d z_1^{-1} \cdots z_n^{-1} \) into the definition (5.1).) For \( x = (x_1, x_2, \ldots, x_n) \in (\mathbb{C}^*)^n \), we define the sum \( K(x) \) by

\[
K(x) := \int_0^{x_\infty} \Phi(z) \Delta(z) \frac{d_q z_1}{z_1} \wedge \cdots \wedge \frac{d_q z_n}{z_n}, \quad (5.3)
\]

which converges absolutely under the condition

\[
q < |a_1 a_2 \cdots a_{n+1} b_1 b_2 \cdots b_{n+1}|.
\]

(See [20, Lemma 3.19].) We call \( K(x) \) the \textit{Jackson integral of Gustafson’s \( A_n \)-type}. In particular, for given arbitrary \( c_1, c_2, \ldots, c_n \in \mathbb{C}^* \), if we set \( d \) in (5.2) as \( d = c_1 c_2 \cdots c_n \), then the sum \( K(c) \) for \( c = (c_1, c_2, \ldots, c_n) \in (\mathbb{C}^*)^n \) is completely equivalent to Gustafson’s \( A_n \) sum defined in [20], which will be stated as Corollary 5.3. If we set \( x = (a_1, a_2, \ldots, a_n) \) on (5.3), then we call \( K(a) \) the \textit{truncated Jackson integral}. For an arbitrary \( x = (x_1, x_2, \ldots, x_n) \in (\mathbb{C}^*)^n \) we define the function \( h(x) \) by

\[
h(x) := (-1)^n \frac{\prod_{1 \leq i < j \leq n} x_j \theta(x_i/x_j)}{\prod_{i=1}^{n+1} \theta(b_j x_i)} \frac{\prod_{i=1}^{n} x_i \theta(d x_1^{-1} \cdots x_n^{-1}/x_i)}{\prod_{j=1}^{n+1} \theta(b_j d x_1^{-1} \cdots x_n^{-1})}. \quad (5.4)
\]

We remark that, if we denote by \( x_{n+1} \) the combination of variables \( d x_1^{-1} x_2^{-1} \cdots x_n^{-1} \), then \( h(x) \) is expressed as

\[
h(x) = \frac{\prod_{1 \leq i < j \leq n+1} x_j \theta(x_i/x_j)}{\prod_{i=1}^{n+1} \theta(b_j x_i)}. \quad (5.5)
\]
We define the regularization $\mathcal{K}(x)$ of the sum $K(x)$ by $\mathcal{K}(x) := K(x)/h(x)$. Since $h(x)$ is invariant under the $q$-shift $x_i \to qx_i (1 \leq i \leq n)$, the regularization $\mathcal{K}(x)$ is also expressed as

$$\mathcal{K}(x) = \frac{K(x)}{h(x)} = \int_0^{\infty} \frac{\Phi(z) \Delta(z)}{h(z)} \frac{dz_1}{z_1} \cdots \frac{dz_n}{z_n},$$

so that, for $x = (x_1, x_2, \ldots, x_n) \in (\mathbb{C}^*)^n$ we have a Macdonald-type sum expression (recall (3.19)) of the regularization $\mathcal{K}(x)$ as

$$\mathcal{K}(x) = \int_0^{\infty} \prod_{i=1}^{n+1} \prod_{j=1}^{n+1} (q a_j^{-1} z_i) (q b_j^{-1} z_i)^{-1} d_q z_1 \wedge \cdots \wedge d_q z_n,$$

where the variable $z_{n+1}$ in the integrand satisfy the condition (5.2) by definition.

**Lemma 5.1** The $q$-periodic function $\mathcal{K}(x)$ is holomorphic on $(\mathbb{C}^*)^n$, and is consequently a constant independent of $x \in (\mathbb{C}^*)^n$.

**Remark.** As we will see in Lemma 5.5 below, $\mathcal{K}(x)$ satisfies the $q$-difference system of rank 1, which is independent of $x \in (\mathbb{C}^*)^n$. We regard the connection coefficient between a general solution $\mathcal{K}(x)$ of the system and a special solution $\mathcal{K}(a)$ as 1, i.e.,

$$\mathcal{K}(x) = \mathcal{K}(a),$$

for an arbitrary $x \in (\mathbb{C}^*)^n$, which is just the statement of Lemma 5.1. In the same way, for $b^{-1}$ as specified in (3.20) we can also consider the equation $\mathcal{K}(x) = \mathcal{K}(b^{-1})$ as a connection formula.

**Proof.** We temporarily write $x_{n+1} = dx_1 x_2^{-1} \cdots x_{n-1}^{-1}$. From the expression (5.6), the function $\mathcal{K}(x)$ has the poles lying only in the set $\{x = (x_1, x_2, \ldots, x_n) \in (\mathbb{C}^*)^n; \prod_{1 \leq i < j \leq n+1} \theta(x_i/x_j)\}$, $\mathcal{K}(x)$ is written as

$$\mathcal{K}(x) = \frac{f(x)}{\prod_{1 \leq i < j \leq n+1} x_j \theta(x_i/x_j)}$$

where $f(x)$ is some holomorphic function on $(\mathbb{C}^*)^n$. Since $\mathcal{K}(x)$ and $\prod_{1 \leq i < j \leq n+1} x_j \theta(x_i/x_j)$ are symmetric and skew-symmetric for permutation of $x_1, x_2, \ldots, x_{n+1}$, respectively, the holomorphic function $f(x)$ is skew-symmetric. Thus $f(x)$ vanishes if $x_i = x_j$. This means that $f(x)$ is divisible by $x_j \theta(x_i/x_j)$. Since the holomorphic function $f(x)$ is divisible by $\prod_{1 \leq i < j \leq n+1} x_j \theta(x_i/x_j)$, from the expression (5.8), $\mathcal{K}(x)$ is holomorphic function on $(\mathbb{C}^*)^n$. By definition of Jackson integrals, the holomorphic function $\mathcal{K}(x)$ is invariant under the $q$-shift $x_i \to qx_i (1 \leq i \leq n)$. Therefore $\mathcal{K}(x)$ is a constant independent of $x$. □

The aim of this section is the evaluation of $\mathcal{K}(x)$ as a constant. The main theorem is stated as follows:

**Theorem 5.2** For an arbitrary $x = (x_1, x_2, \ldots, x_n) \in (\mathbb{C}^*)^n$, the regularization $\mathcal{K}(x)$ is a constant independent of $x$, which is expressed as

$$\mathcal{K}(x) = (1 - q)^n \frac{(q a_1^{-1} \cdots a_{n+1}^{-1} d) (q b_1^{-1} \cdots b_{n+1}^{-1} d^{-1})}{(q a_1^{-1} \cdots a_{n+1} b_1^{-1} \cdots b_{n+1}^{-1})} \prod_{i=1}^{n+1} \prod_{j=1}^{n+1} (q a_i^{-1} b_j^{-1}).$$


In other words, from the expression \( K(x) = \mathcal{K}(x)h(x) \), the sum \( K(x) \) is expressed as

\[
K(x) = (1 - q)^n (q a_1^{-1} \cdots a_{n+1}^{-1} d)_{\infty} (q b_1^{-1} \cdots b_{n+1}^{-1} d^{-1})_{\infty} \prod_{i=1}^{n+1} \prod_{j=1}^{n+1} (q a_i^{-1} b_j^{-1})_{\infty} \\
\times (-1)^n \prod_{1 \leq i < j \leq n} x_i \theta(x_i/x_j) \prod_{i=1}^{n} x_i \theta(dx_1^{-1} \cdots x_n^{-1}/x_i) \prod_{j=1}^{n+1} \theta(b_j dx_1^{-1} \cdots x_n^{-1}).
\]  
(5.10)

Proof. Using (5.7), the evaluation of \( \mathcal{K}(x) \) is deduced from the special case \( \mathcal{K}(a) \) of \( a = (a_1, a_2, \cdots, a_n) \in (\mathbb{C}^*)^n \), which will be shown in Lemma 5.4 below. We will also mention another way to evaluate \( \mathcal{K}(x) \) in Subsection 5.3. □

In particular,

**Corollary 5.3 (Gustafson [20])** For given arbitrary \( c_1, c_2, \cdots, c_{n+1} \in \mathbb{C}^* \), set \( d = c_1 c_2 \cdots c_{n+1} \). Then the sum \( K(c) \) for \( c = (c_1, c_2, \cdots, c_n) \in (\mathbb{C}^*)^n \) is expressed as

\[
K(c) = (1 - q)^n (q a_1^{-1} \cdots a_{n+1}^{-1} c_1 \cdots c_{n+1})_{\infty} (q b_1^{-1} \cdots b_{n+1}^{-1} c_1 \cdots c_{n+1})_{\infty} \\
\times \prod_{i=1}^{n+1} \prod_{j=1}^{n+1} (q a_i^{-1} b_j^{-1})_{\infty} \prod_{1 \leq i < j \leq n+1} c_i \theta(c_i/c_j) \prod_{n+1 \leq j \leq n+1} c_j \theta(c_j),
\]  
(5.11)

which exactly coincides with the product expression of Gustafson’s \( A_n \) sum.

Proof. Using (5.5), this formula obtained from (5.10). □

Remark 1. As is pointed out in Gustafson’s original paper [20, p.1593], the Milne–Gustafson sum \( I(z) \) discussed in Section 3 is immediately deduced from Gustafson’s \( A_n \) sum \( K(c) \). In this sense, Gustafson’s \( A_n \) sum is regarded as an extension of the Milne–Gustafson sum.

Remark 2. Under the setting \( d = c_1 c_2 \cdots c_{n+1} \), the expression (5.10) of \( K(x) \) for an arbitrary \( x = (x_1, x_2, \cdots, x_n) \in (\mathbb{C}^*)^n \) contains (5.11) of \( K(c) \) for \( c = (c_1, c_2, \cdots, c_n) \in (\mathbb{C}^*)^n \). In this sense, \( K(x) \) is regarded as an extension of Gustafson’s \( A_n \) sum \( K(c) \), though the difference of appearance is very slight. However, technically speaking, it is crucial to distinguish \( c \) and \( x \) in the above setting for the proof, as we will see in Lemma 5.7, which is a key for deriving the \( q \)-difference equations of \( K(x) \).

Though the following lemma is a special case of Theorem 5.2, from the fact (5.7), logically it suffices to evaluate \( \mathcal{K}(a) \) instead of proving Theorem 5.2.

**Lemma 5.4** For the special point \( x = a = (a_1, a_2, \cdots, a_n) \), the truncation \( \mathcal{K}(a) \) is expressed as

\[
\mathcal{K}(a) = (1 - q)^n (q a_1^{-1} \cdots a_{n+1}^{-1} d)_{\infty} (q b_1^{-1} \cdots b_{n+1}^{-1} d^{-1})_{\infty} \prod_{i=1}^{n+1} \prod_{j=1}^{n+1} (q a_i^{-1} b_j^{-1})_{\infty}.
\]  
(5.12)

Proof. Subsection 5.4 will be devoted to the proof of this lemma, computing the asymptotic behavior of the truncated Jackson integral \( \mathcal{K}(a) \). □
In this subsection we show the explicit. Notice that $a_{n+1}$ fixed in the definition of $\Phi(z)$ does not necessarily satisfy the relation $d = a_1a_2 \cdots a_{n+1}$. Thus in general, $h(a)$ does not coincide with

$$\frac{\prod_{1 \leq i < j \leq n+1} a_j \theta(a_i/a_j)}{\prod_{i=1}^{n+1} \prod_{j=1}^{n+1} \theta(a_i b_j)},$$

(5.13)

and the correct expression of $h(a)$ follows by definition as

$$h(a) = (-1)^n \frac{\prod_{1 \leq i < j \leq n} a_j \theta(a_i/a_j)}{\prod_{i=1}^{n} \prod_{j=1}^{n+1} \theta(b_j a_i)} \frac{\prod_{i=1}^{n} a_i \theta(da_i^{-1} \cdots a_n^{-1}/a_i)}{\prod_{j=1}^{n+1} \theta(b_j da_i^{-1} \cdots a_n^{-1})},$$

(5.14)

which will be used later. However, if we set $d = a_1a_2 \cdots a_{n+1}$, (i.e., set $c = a$ in Corollary 5.3) then $h(a)$ is written as (5.13), so that $K(a) = K(a)h(a)$ is written more simply as

$$K(a) = (1-q)^n \frac{(q)_{\infty} \prod_{1 \leq i < j \leq n+1} a_j \theta(a_i/a_j)}{\prod_{i=1}^{n} \prod_{j=1}^{n+1} (a_i b_j)_{\infty}},$$

which is referred as Milne’s fundamental theorem of $U(n)$ series [34] in [40, (2.2) p.421].

### 5.2 $q$-difference equations

In this subsection we show the $q$-difference equations for $K(x)$ with respect to parameters explicitly.

**Lemma 5.5** The recurrence relations for $K(x)$ are given by

$$T_{a_j}K(x) = K(x) \frac{1 - d \prod_{i=1}^{n+1} a_i^{-1} \prod_{i=1}^{n+1} (1 - b_i^{-1} a_i^{-1})}{1 - \prod_{i=1}^{n+1} a_i^{-1} b_i^{-1} \prod_{i=1}^{n+1} (1 - a_i b_j)},$$

(5.15)

$$T_{b_j}K(x) = K(x) \frac{1 - d \prod_{i=1}^{n+1} b_i \prod_{i=1}^{n+1} (1 - a_i b_j)}{1 - \prod_{i=1}^{n+1} a_i b_i \prod_{i=1}^{n+1} (1 - a_i b_j)},$$

(5.16)

for $j = 1, 2, \ldots, n+1$. The recurrence relations for $K(x)$ are given by

$$T_{a_j}K(x) = K(x) \frac{1 - d \prod_{i=1}^{n+1} a_i^{-1} \prod_{i=1}^{n+1} (1 - b_i^{-1} a_i^{-1})}{1 - \prod_{i=1}^{n+1} a_i^{-1} b_i^{-1} \prod_{i=1}^{n+1} (1 - a_i b_j)},$$

(5.17)

$$T_{b_j}K(x) = K(x) \frac{1 - d \prod_{i=1}^{n+1} b_i \prod_{i=1}^{n+1} (1 - a_i b_j)}{1 - \prod_{i=1}^{n+1} a_i b_i \prod_{i=1}^{n+1} (1 - a_i b_j)},$$

(5.18)

for $j = 1, 2, \ldots, n+1$.

The rest of this subsection is devoted to proving the above $q$-difference equations. Before proving Lemma 5.5, we will show two lemmas. In this section, $\Phi(z)$ in (5.1) is considered under the restriction (5.2). Involving this restriction, we need a slight change of the basic lemma (Lemma 2.1) to Lemma 5.6 stated below in order to suit the setting of this section.
For a function \( \varphi(z) \) of \( z = (z_1, z_2, \ldots, z_n) \in (\mathbb{C}^*)^n \), let \( \nabla_{i,j} \varphi(z) \) \((1 \leq i, j \leq n + 1)\) be the functions defined by

\[
(\nabla_{i,j} \varphi)(z) := \varphi(z) - \frac{T_{z_j}^{-1} T_{z_i} \Phi(z)}{\Phi(z)} T_{z_j}^{-1} T_{z_i} \varphi(z),
\]

(5.19)

where \( T_{z_j}^{-1} T_{z_i} \) indicates the shift operator with respect to \( z_i \to q z_i \) and \( z_j \to q^{-1} z_j \) together.

(Since we regard \( \Phi(z) \) given by (5.1) as a function of \( z = (z_1, z_2, \ldots, z_n) \in (\mathbb{C}^*)^n \) under the condition \( z_{n+1} = d z_1^{-1} z_2^{-1} \cdots z_n^{-1} \), if we consider the individual shift \( z_i \to q z_i \) \((1 \leq i \leq n)\), then the shift \( z_{n+1} \to q^{-1} z_{n+1} \) occurs automatically. We formally write the shift of this situation by the symbol \( T_{z_i}^{-1} T_{z_{n+1}} \) instead of \( T_{z_i} \) for our convenience. In the same way, we use the symbol \( T_{z_i}^{-1} T_{z_{n+1}} \) instead of \( T_{z_i}^{-1} \).

In this section we use the symbol \( \mathcal{A} \) as the skew-symmetrization with respect to \( S_{n+1} \) on \( n + 1 \) variables \( z_1, z_2, \ldots, z_{n+1} \), i.e., \( \mathcal{A} f(z) = \sum_{\sigma \in S_{n+1}} (\text{sgn} \sigma) \sigma f(z) \). Then we have

**Lemma 5.6** For a function \( \varphi(z) \) of \( z = (z_1, z_2, \ldots, z_n) \in (\mathbb{C}^*)^n \),

\[
\int_0^{x\infty} \Phi(z) \nabla_{i,j} \varphi(z) \frac{d_q z_1}{z_1} \wedge \cdots \wedge \frac{d_q z_n}{z_n} = 0 \quad (1 \leq i, j \leq n + 1),
\]

(5.20)

if the integral converges. Moreover, for a function \( \varphi(z) = \varphi(z_1, z_2, \ldots, z_{n+1}) \) with \( z_{n+1} = d z_1^{-1} z_2^{-1} \cdots z_n^{-1} \),

\[
\int_0^{x\infty} \Phi(z) \mathcal{A} \nabla_{i,j} \varphi(z) \frac{d_q z_1}{z_1} \wedge \cdots \wedge \frac{d_q z_n}{z_n} = 0.
\]

(5.21)

**Proof.** If \( i = n + 1 \) or \( j = n + 1 \), then \( T_{z_i}^{-1} T_{z_{n+1}} = T_{z_i}^{-1} \) or \( T_{z_{n+1}}^{-1} T_{z_i} = T_{z_i}^{-1} \), respectively, so that we can confirm (5.20) in the same way as (2.7) in Lemma 2.1. While if \( i \neq n + 1 \) and \( j \neq n + 1 \), then from the definition (5.19) of \( \nabla_{i,j} \), (5.20) is equivalent to

\[
\int_0^{x\infty} \varphi(z) \Phi(z) \frac{d_q z_1}{z_1} \wedge \cdots \wedge \frac{d_q z_n}{z_n} = \int_0^{x\infty} T_{z_i}^{-1} T_{z_j} \Phi(z) T_{z_i}^{-1} T_{z_j} \Phi(z) \frac{d_q z_1}{z_1} \wedge \cdots \wedge \frac{d_q z_n}{z_n},
\]

which is just confirmed from the fact that the Jackson integral is invariant under the \( q \)-shift \( z_i \to q z_i \) \((1 \leq i \leq n)\). Next we will confirm (5.21). For \( \varphi(z) = \varphi(z_1, z_2, \ldots, z_{n+1}) \), we have

\[
\Phi(z) \mathcal{A} \nabla_{i,j} \varphi(z) = \Phi(z) \sum_{\sigma \in S_{n+1}} (\text{sgn} \sigma) \sigma \nabla_{i,j} \varphi(z) = \sum_{\sigma \in S_{n+1}} (\text{sgn} \sigma) \Phi(z) \nabla_{\sigma(i), \sigma(j)} \varphi(z),
\]

and thus

\[
\int_0^{x\infty} \Phi(z) \mathcal{A} \nabla_{i,j} \varphi(z) \frac{d_q z_1}{z_1} \wedge \cdots \wedge \frac{d_q z_n}{z_n}
\]

\[
= \sum_{\sigma \in S_{n+1}} (\text{sgn} \sigma) \int_0^{x\infty} \Phi(z) \nabla_{\sigma(i), \sigma(j)} \varphi(z) \frac{d_q z_1}{z_1} \wedge \cdots \wedge \frac{d_q z_n}{z_n}.
\]

Since \( \sigma \varphi(z) \) is also a function on \((\mathbb{C}^*)^n\) under the condition \( z_{n+1} = d z_1^{-1} z_2^{-1} \cdots z_n^{-1} \), using (5.20), we see all terms in the right-hand side of the above equation are equal to 0. \( \square \)
For $c \in \mathbb{C}^*$ and $z = (z_1, z_2, \ldots, z_{n+1}) \in (\mathbb{C}^*)^{n+1}$ we denote $e(c; z)$ the symmetric polynomial of degree $n + 1$ defined by

$$e(c; z) := \prod_{i=1}^{n+1} (1 - c^{-1}z_i),$$

(cf. (4.17)) which has a property that $e(c; z)$ vanishes if $z_i = c$ for some $i = 1, 2, \ldots, n + 1$.

**Lemma 5.7** If we put $\varphi(z)$ as

$$\varphi(z) = \prod_{i=1}^{n+1} (1 - a_i^{-1}z_1)(1 - b_i z_{n+1}) \times z_2 \cdots z_n \prod_{1 \leq j < k \leq n} (z_k - a_j), \quad (5.22)$$

then $\mathcal{A} \nabla_{1,n+1}\varphi(z) \left( = 2\mathcal{A}\varphi(z) \right)$ is expanded as

$$\mathcal{A} \nabla_{1,n+1}\varphi(z) = \left( c_0 e_0(z) + c_1 e(a_1; z) \right) \Delta(z), \quad (5.23)$$

where the function $e_0(z)$ is defined by

$$e_0(z) := 1 - z_1 z_2 \cdots z_{n+1} a_1^{-1} a_2^{-1} \cdots a_{n+1}^{-1}$$

and the constants $c_0$ and $c_1$ are given by

$$c_0 = (-1)^{n+1} 2 a_1^{-1} b_1 \cdots b_{n+1} \prod_{i=1}^{n+1} (1 - a_i^{-1} b_i^{-1}), \quad c_1 = (-1)^n 2 a_1 b_1 \cdots b_{n+1} (1 - \prod_{i=1}^{n+1} a_i^{-1} b_i^{-1}). \quad (5.24)$$

In particular, under the condition $z_1 z_2 \cdots z_{n+1} = d$, the function $e_0(z)$ is a constant and then

$$c'_0 := c_0 e_0(z) = (-1)^{n+1} 2 a_1^{-1} b_1 \cdots b_{n+1} (1 - d a_1^{-1} a_2^{-1} \cdots a_{n+1}^{-1}) \prod_{i=1}^{n+1} (1 - a_i^{-1} b_i^{-1}). \quad (5.25)$$

**Proof.** Since the ratio $T_{z_{n+1}}^{-1} T_{z_1} \Phi(z)/\Phi(z)$ is written as

$$\frac{T_{z_{n+1}}^{-1} T_{z_1} \Phi(z)}{\Phi(z)} = \prod_{j=1}^{n+1} \frac{(1 - b_j z_1)(1 - a_j^{-1} z_{n+1})}{(1 - q a_j^{-1} z_1)(1 - q^{-1} b_j z_{n+1})},$$

for $\varphi(z)$ given by (5.22), using (5.19) gives

$$\nabla_{1,n+1}\varphi(z) = \left( \prod_{i=1}^{n+1} (1 - a_i^{-1} z_1)(1 - b_i z_{n+1}) - \prod_{i=1}^{n+1} (1 - b_i z_1)(1 - a_i^{-1} z_{n+1}) \right) \times z_2 \cdots z_n \prod_{1 \leq j < k \leq n} (z_k - a_j). \quad (5.26)$$

Let us use $\nabla$ instead of $\nabla_{1,n+1}$ for abbreviation. Taking account of the degree of $\nabla \varphi(z)$ as a polynomial of $z$, we can expand the skew-symmetrization $\mathcal{A} \nabla \varphi(z)$ as

$$\mathcal{A} \nabla \varphi(z) = \left( c_0 e_0(z) + \sum_{i=1}^{n} c_i e(a_i; z) + c_{n+1} e(b_{n+1}^{-1}; z) \right) \Delta(z), \quad (5.27)$$
where the coefficients \( c_i \) \((i = 0, 1, \ldots, n)\) are some constants. Here we will confirm that \( c_i \) vanishes if \( i \geq 2 \), and \( c_0 \) and \( c_1 \) are evaluated as (5.24).

First we take \( z_1 = a_1, z_2 = a_2, \ldots, z_n = a_n \) and \( z_{n+1} = b_{n+1}^{-1} \). Then, from (5.27) with the vanishing property of \( e(a_i; z) \), we have \( \mathcal{A}_n \varphi(z) \) as

\[
\mathcal{A}_n \varphi(z) = c_0 e_0(z) \Delta(z) = c_0 \left( 1 - a_{n+1}^{-1} b_{n+1}^{-1} \right) \prod_{1 \leq j < k \leq n} (a_k - a_j) \prod_{i=1}^{n} \left( a_i^{-1} b_{n+1}^{-1} - a_i \right)
\]

\[= (-1)^n c_0 a_1 \cdots a_{n+1} \prod_{i=1}^{n+1} \left( 1 - a_i^{-1} b_{n+1}^{-1} \right) \prod_{1 \leq j < k \leq n} (a_k - a_j). \tag{5.28}\]

On the other hand, from (5.26), we have

\[
\mathcal{A}_n \varphi(z) = -2 \prod_{i=1}^{n+1} \left( 1 - b_i a_1 \right) \left( 1 - a_i^{-1} b_{n+1}^{-1} \right) \times a_2 \cdots a_n \prod_{1 \leq j < k \leq n} (a_k - a_j). \tag{5.29}\]

Comparing (5.28) with (5.29), we obtain \( c_0 \) in the expression (5.24).

Next we take \( z_1 = a_1, z_2 = a_2, \ldots, z_n = a_n \) and \( z_{n+1} \not\in \{a_1, a_2, \ldots, a_n, b_{n+1}^{-1} \} \). Then, from (5.27) and the vanishing property of \( e(a_i; z) \), we have

\[
\mathcal{A}_n \varphi(z) = \left( c_0 e_0(z) + c_{n+1} e\left( b_{n+1}^{-1}; z \right) \right) \Delta(z). \tag{5.30}\]

On the other hand, from (5.26) and (5.29), we have

\[
\mathcal{A}_n \varphi(z) = -2 \prod_{i=1}^{n+1} \left( 1 - b_i a_1 \right) \left( 1 - a_i^{-1} z_{n+1} \right) \times a_2 \cdots a_n \prod_{1 \leq j < k \leq n} (a_k - a_j) = c_0 e_0(z) \Delta(z). \tag{5.31}\]

Comparing (5.30) and (5.31), we obtain \( c_{n+1} = 0 \).

Third we take \( z_1 = a_1, z_2 = a_2, \ldots, z_n = a_{n-1}, z_n \not\in \{a_1, a_2, \ldots, a_{n-1}, b_{n+1}^{-1} \} \) and \( z_{n+1} = b_{n+1}^{-1} \).

Then, from (5.27) and the vanishing property of \( e(a_i; z) \), we have

\[
\mathcal{A}_n \varphi(z) = \left( c_0 e_0(z) + c_n e(a_n; z) \right) \Delta(z). \tag{5.32}\]

On the other hand, from (5.26), we have

\[
\mathcal{A}_n \varphi(z) = c_0 e_0(z) \Delta(z). \tag{5.33}\]

Comparing (5.32) and (5.33), we obtain \( c_n = 0 \). In the same manner, by symmetry of \( \mathcal{A}_n \varphi(z) \) of \( \nabla \varphi(z) \) in (5.26), we also obtain \( c_i = 0 \) if \( i \geq 2 \). Thus we obtain the expansion (5.23).

Lastly, we take \((z_1, z_2, \ldots, z_{n+1}) = (b_1^{-1}, b_2^{-1}, \ldots, b_{n+1}^{-1}) = b^{-1}\). From (5.26), we have \( \mathcal{A}_n \varphi(b^{-1}) = 0 \). On the other hand, from (5.27), we have

\[
\mathcal{A}_n \varphi(z) = \left( c_0 e_0(b^{-1}) + c_1 e(a_1; b^{-1}) \right) \Delta(z)
\]

so that

\[
c_1 = -c_0 \frac{e_0(b^{-1})}{e(a_1, b^{-1})} = (-1)^n 2a_1^n b_1 \cdots b_{n+1} (1 - \prod_{i=1}^{n+1} a_i^{-1} b_i^{-1}).
\]
which is what we want to show. □

**Proof of Lemma 5.5.** We will prove (5.15) for $T_{a_j}$ first. Without loss of generality, it suffices to show that

$$T_{a_1}K(x) = K(x) \frac{1 - d}{1 - \prod_{i=1}^{n+1} a_i^{-1} b_i^{-1}} \prod_{i=1}^{n+1} (1 - b_i^{-1} a_i^{-1}).$$

(5.34)

Since we have $T_{a_1} \Phi(z)/\Phi(z) = \prod_{i=1}^{n+1} (1 - a_i^{-1} z_i) = e(a_1; z)$ by definition, $T_{a_1} K(z)$ is expressed by

$$T_{a_1}K(x) = \int_0^x e(a_1; z) \Phi(z) \Delta(z) \frac{d_q z_1}{z_1} \wedge \cdots \wedge \frac{d_q z_n}{z_n}.$$

Applying (5.21) in Lemma 5.6 to the fact (5.23) in Lemma 5.7, we obtain the relation

$$c'_0 K(z) + c_0 T_{a_1} K(z) = 0,$$

where $c_1$ and $c_0'$ are given in (5.24) and (5.25). This relation coincides with (5.34).

Next we will show the $q$-difference equation (5.16) for $T_{b_j}$ of the case $j = 1$ as the same manner as above. Since we have $T_{b_1} \Phi(z)/\Phi(z) = \prod_{i=1}^{n+1} (1 - b_1 z_i) = e(b_1^{-1}; z)$, $T_{b_1} K(z)$ is expressed by

$$T_{b_1}K(x) = \int_0^x e(b_1^{-1}; z) \Phi(z) \Delta(z) \frac{d_q z_1}{z_1} \wedge \cdots \wedge \frac{d_q z_n}{z_n}.$$

Here if we exchange $a_i$ with $b_i^{-1}$ ($i = 1, 2, \ldots, n + 1$) in the above proof of (5.34) including that of Lemma 5.7, the way of argument is completely symmetric for this exchange. Therefore (5.16) for $T_{b_1}$ is obtained exchanging $a_i$ with $b_i^{-1}$ on the coefficient of (5.34).

Lastly we will confirm the $q$-difference equations (5.17) and (5.18) for $\mathcal{K}(x)$. From (5.4), we have

$$T_{a_j} h(z) = h(z) \quad \text{and} \quad T_{b_j} h(z) = d(-b_j)^{n+1} h(z).$$

We therefore obtain (5.17) and (5.18) from (5.15) and (5.16), respectively, using the above equations. □

### 5.3 A remark on a relation to the Macdonald identity for $A_n^{(1)}$

We can use the recurrence relations (5.17) and (5.18) directly to the regularization $\mathcal{K}(z)$ for its evaluation. Actually, we can immediately obtain Theorem 5.2 as a corollary of Lemma 5.5.

**Corollary 5.8** The sum $\mathcal{K}(x)$ (expressed as (5.6)) can be written

$$\mathcal{K}(x) = \mathcal{K}_0(x) \left( \frac{q a_1^{-1} \cdots a_n^{-1} d}{q b_1^{-1} \cdots b_{n+1}^{-1} d} \right) \prod_{i=1}^{n+1} \prod_{j=1}^{n+1} \left( q a_i^{-1} b_j^{-1} \right).$$

(5.35)

where $\mathcal{K}_0(x)$ is the Jackson integral defined by

$$\mathcal{K}_0(x) := \int_0^x \frac{1}{\prod_{1 \leq i < j \leq n+1} (q z_i / z_j) \prod_{j=1}^{n+1} (q z_j / z_i) \frac{d_q z_1}{z_1} \wedge \cdots \wedge \frac{d_q z_n}{z_n}}.$$

(5.36)

We remark that $\mathcal{K}_0(x)$ satisfies the Macdonald identity for $A_n^{(1)}$ proved by Milne (straightforward rewrite of [34, Theorem 1.58]), i.e.,

$$\mathcal{K}_0(x) = (1 - q)^n(q)^n.$$
Proof. Let $T^N$ be the $q$-shift operator with respect to $a_i \rightarrow q^{-N}a_i$ and $b_i \rightarrow q^{-N}b_i$ ($i = 1, 2, \ldots, n + 1$). If we set $C$ the right-hand side of (5.35) without factor $K_0(x)$, then we have $T^N C \rightarrow 1 \ (N \rightarrow +\infty)$. From (5.17) and (5.18), $K(x)$ and $C$ satisfy the same recurrence relations, so that the ratio $\frac{K(x)}{C}$ is invariant under the $q$-shift $T^N$. Therefore we obtain

$$
\frac{K(x)}{C} = T^N \frac{K(x)}{C} = \lim_{N \rightarrow +\infty} T^N \frac{K(x)}{T^N C} = \lim_{N \rightarrow +\infty} T^N \frac{K(x)}{C},
$$

where

$$
\lim_{N \rightarrow +\infty} T^N K(x) = \lim_{N \rightarrow +\infty} \int_0^{\infty} \prod_{i=1}^{n+1} \frac{(q^{a_j}z_{i+1})_\infty (q^{b_j}z_i)_\infty}{(a_j z_{n+1})_\infty} \frac{dz_i}{z_i},
$$

which coincides with (5.36) of $K_0(x)$. □

Though (5.35) of Corollary 5.8 shows the connection between $K(x)$ and $K_0(x)$, it is not our intention to evaluate $K(x)$ via this connection using the Macdonald identity. In keeping with our viewpoint our aim is to evaluate $K(a)$ directly calculating the asymptotic behavior of the truncated Jackson integral.

### 5.4 Asymptotic behavior (Proof of Lemma 5.4)

In this subsection we will give a proof for Lemma 5.4. In order to calculate $K(a)$, we deform $\Phi(z)$ to $\tilde{\Phi}(z)$ according to

$$
\Phi(z) = k(z)\tilde{\Phi}(z),
$$

where

$$
k(z) := \prod_{j=1}^{n+1} z^{-\alpha_j-\beta_j} \frac{\theta(qa_j^{-1}z_{n+1})}{\theta(b_j z_{n+1})} = \prod_{j=1}^{n+1} \frac{\theta(a_jd^{-1}z_1z_2\cdots z_n)}{(d^{-1}z_1z_2\cdots z_n)^{1-\alpha_j-\beta_j} \theta(qb_j)\theta(d^{-1}z_1z_2\cdots z_n)}
$$

and

$$
\tilde{\Phi}(z) := (z_{n+1}^{-1})^{n+1-\alpha_1-\cdots-\alpha_{n+1}-\beta_1-\cdots-\beta_{n+1}}
\times \prod_{i=1}^{n} \prod_{j=1}^{n+1} \frac{(qa_j^{-1}z_i)_\infty}{(b_j z_i)_\infty} \times \prod_{j=1}^{n+1} \frac{(qb_j^{-1}z_{n+1})_\infty}{(a_j z_{n+1})_\infty}
\times \prod_{i=1}^{n} \prod_{j=1}^{n+1} \frac{(qa_j^{-1}z_i)_\infty}{(b_j z_i)_\infty} \times \prod_{j=1}^{n+1} \frac{(qb_j^{-1}d^{-1}z_1\cdots z_n)_\infty}{(a_j d^{-1}z_1\cdots z_n)_\infty}.
$$

Here $\alpha_i$ and $\beta_i$ are given by $a_i = q^{\alpha_i}, b_i = q^{\beta_i}$. Then we define the Jackson integral $\tilde{K}(x)$ by

$$
\tilde{K}(x) := \int_0^{\infty} \tilde{\Phi}(z) \Delta(z) \frac{dz_1}{z_1} \cdots \frac{dz_n}{z_n}.
$$

Since $k(z)$ is invariant under the $q$-shift $z_i \rightarrow qz_i$, from (5.37) and (5.40), we have

$$
K(x) = k(x)\tilde{K}(x).
$$
We will calculate the asymptotic behavior of $\tilde{K}(x)$ instead of $K(x)$ when $x = a$. Since $\Delta(z)$ is written as

$$\Delta(z) = \prod_{i=1}^{n}(z_{n+1} - z_i) \prod_{1 \leq j < k \leq n}(z_k - z_j) = \prod_{i=1}^{n} \frac{1 - z_i(d^{-1}z_1 \cdots z_n)}{d^{-1}z_1 \cdots z_n} \prod_{1 \leq j < k \leq n}(z_k - z_j),$$

from (5.39), we have

$$\Phi(z)\Delta(z) = (d^{-1}z_1z_2 \cdots z_n)^{1-\alpha_1-\cdots-\alpha_{n+1}-\beta_1-\cdots-\beta_{n+1}} \prod_{1 \leq j < k \leq n}(z_k - z_j)$$

$$\times \prod_{i=1}^{n} \left(1 - \frac{z_i}{d} z_1z_2 \cdots z_n \right) \prod_{j=1}^{n+1} \left(\frac{qa_j^{-1}z_i}{b_j z_i}\right) \times \prod_{j=1}^{n+1} \left(qb_j^{-1}d^{-1}z_1 \cdots z_n\right).$$

For an integer $N$, let $T^N$ be the $q$-shift operator for a special direction,

$$T^N : b_i \rightarrow q^{-nN}b_i \ (i = 1, 2, \ldots, n + 1); \quad a_j \rightarrow q^{(n+1)N}a_j \ (j = 1, 2, \ldots, n); \quad a_{n+1} \rightarrow q^{-nN}a_{n+1}.$$  

Then, by definition $T^N\tilde{K}(a)$ is written explicitly as

$$T^N\tilde{K}(a) = (1 - q^n) \sum_{(\nu_1, \ldots, \nu_n) \in N^n} (d^{-1}a_1a_2 \cdots a_n q^{\nu_1 + \cdots + \nu_n + n(n+1)N})^{-\alpha_1-\cdots-\alpha_{n+1}-\beta_1-\cdots-\beta_{n+1}+nN}$$

$$\times \prod_{i=1}^{n} \left(1 - \frac{a_i q^{\nu_i}}{d} a_1a_2 \cdots a_n q^{\nu_1 + \cdots + \nu_n + (n+1)2N}\right) \prod_{j=1}^{n+1} \left(\frac{a_{n+1}^{-1}a_i q^{1+\nu_i+(n+1)N}}{b_{n+1}a_i q^{\nu_i+N}}\right) \prod_{j=1}^{n+1} \left(qb_j^{-1}d^{-1}z_1 \cdots z_n\right)$$

$$\times \prod_{1 \leq i < j \leq n} q^{(n+1)N}(a_j a_i^{-1} - a_i q^{\nu_i}),$$

so that the leading term of the asymptotic behavior of $T^N\tilde{K}(a)$ as $N \rightarrow +\infty$ is given by the term corresponding to $(\nu_1, \ldots, \nu_n) = (0, \ldots, 0)$ in the above sum, i.e.,

$$T^N\tilde{K}(a) \sim (1 - q^n) (d^{-1}a_1a_2 \cdots a_n q^{n(n+1)N})^{1-\alpha_1-\cdots-\alpha_{n+1}-\beta_1-\cdots-\beta_{n+1}+nN}$$

$$\times \prod_{i=1}^{n} \prod_{j=1}^{n+1} (qa_j^{-1}a_i) \prod_{1 \leq i < j \leq n} q^{(n+1)N}(a_j - a_i)$$

$$= (d^{-1}a_1a_2 \cdots a_n q^{n(n+1)N})^{1-\alpha_1-\cdots-\alpha_{n+1}-\beta_1-\cdots-\beta_{n+1}+nN}$$

$$\times (1 - q^n) q^n \prod_{1 \leq i < j \leq n} q^{(n+1)N}a_j \theta(a_i/a_j) \quad (N \rightarrow +\infty). \quad (5.42)$$

On the other hand, if we set $C$ as the right-hand side of (5.12) of Lemma 5.4, then we have from (5.14) and (5.38)

$$\frac{h(a)C}{k(a)} = (d^{-1}a_1a_2 \cdots a_n)^{1-\alpha_1-\cdots-\alpha_{n+1}-\beta_1-\cdots-\beta_{n+1}} \prod_{1 \leq i < j \leq n} a_j \theta(a_i/a_j)$$

$$\times \frac{(1 - q^n) q^n (qb_1^{-1} \cdots b_{n+1}^{-1}d^{-1}) \prod_{j=1}^{n+1} (qa_j^{-1}) \prod_{j=1}^{n+1} (qb_j^{-1})}{(a_1 \cdots a_{n+1}d^{-1}) (qa_1^{-1} \cdots a_{n+1}b_1^{-1} \cdots b_{n+1}^{-1}) \prod_{i=1}^{n+1} (b_i a_i)},$$

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and thus
\[ T^N \frac{h(a) C}{k(a)} = \left(d^{-1} a_1 a_2 \cdots a_n q^{n(n+1)N} \right)^{1-\alpha_1 - \cdots - \alpha_{n+1} - \beta_1 - \cdots - \beta_{n+1} + nN} \prod_{1 \leq i < j \leq n} q^{(n+1)N} a_j \theta(a_i/a_j) \]
\[ \times \left(1 - q\right)^n \left( q^n b_1^{-1} \cdots b_{n+1}^{-1} d^{-1} q^{1+n(n+1)N} \right)_{\infty} \prod_{j=1}^{n+1} (a_{n+1}^{-1} b_j^{-1} q^{1+2nN})_{\infty} \prod_{i=1}^{n} \prod_{j=1}^{n+1} (b_j a_i q^N)_{\infty}. \] (5.43)

Since \( K(a) \) and \( C \) satisfy the same recurrence relations with respect to \( a_i \) and \( b_i \), the ratio \( \frac{K(a)}{C} \) is invariant under the \( q \)-shift \( T^N \). From (5.42) and (5.43), we therefore obtain
\[
\frac{K(a)}{C} = T^N \frac{\tilde{K}(a)}{C} = \lim_{N \to +\infty} \frac{T^N \tilde{K}(a)}{T^N h(a) C/k(a)} = \lim_{N \to +\infty} \frac{T^N \tilde{K}(a)}{T^N h(a) C/k(a)}
\]
\[ = \lim_{N \to +\infty} \frac{(a_1 \cdots a_{n+1} d^{-1} q^{n^2 N})_{\infty} (a_1^{-1} \cdots a_{n+1}^{-1} b_1^{-1} \cdots b_{n+1}^{-1} q^{1+nN})_{\infty} \prod_{i=1}^{n} \prod_{j=1}^{n+1} (b_j a_i q^N)_{\infty}}{(b_1^{-1} \cdots b_{n+1}^{-1} d^{-1} q^{1+n(n+1)N})_{\infty} \prod_{j=1}^{n+1} (a_{n+1}^{-1} b_j^{-1} q^{1+2nN})_{\infty}}
\]
\[ = 1,
\]
which completes the proof of Lemma 5.4. \( \square \)

Acknowledgements
This work was supported by the Australian Research Council and JSPS KAKENHI Grant Number 25400118.

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