End-to-End Synthetic Data Generation for Domain Adaptation of Question Answering Systems

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Abstract

We propose an end-to-end approach for synthetic QA data generation. Our model comprises a single transformer-based encoder-decoder network that is trained end-to-end to generate both answers and questions. In a nutshell, we feed a passage to the encoder and ask the decoder to generate a question and an answer token-by-token. The likelihood produced in the generation process is used as a filtering score, which avoids the need for a separate filtering model. Our generator is trained by fine-tuning a pretrained LM using maximum likelihood estimation. The experimental results indicate significant improvements in the domain adaptation of QA models outperforming current state-of-the-art methods.

1 Introduction

Improving question answering (QA) systems through automatically generated synthetic data is a long standing research goal (Mitkov and Ha, 2003; Rus et al., 2010). Although many past works have proposed different strategies for question generation, they have limited or no success in improving the downstream QA task (Du et al., 2017; Sun et al., 2018; Song et al., 2018; Klein and Nabi, 2019; Wang et al., 2020; Ma et al., 2020; Chen et al., 2020; Tuan et al., 2019).

Some recent approaches for synthetic QA data generation based on large pretrained language models (LM) have started to demonstrate success in improving the downstream Reading Comprehension (RC) task with automatically generated data (Alberti et al., 2019; Puri et al., 2020). However, these approaches typically consist of multi-stage systems that use three modules: span/answer detector, question generator and question filtering.

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Given an input passage, the span detector is responsible for extracting spans that will serve as answers for which questions will be generated. This module normally combines a pretrained QA model with handcrafted heuristics. The question generator is a large LM fine-tuned for the task of conditional generation of questions given passage and answer. The question filtering comprises another RC model that is used to score and filter the generated QA pairs. Each module of this synthetic data generation pipeline is trained/tuned separately and errors from one stage can propagate to the next stages. Additionally, each module is expensive to be computed because all use large transformer networks (Vaswani et al., 2017).

In this work, we propose an end-to-end approach for synthetic QA data generation. Our model comprises a single transformer-based encoder-decoder network that is trained end-to-end to generate both the answer and the question. In a nutshell, we feed a passage to the encoder and ask the decoder to generate the question and the answer token-by-token. The likelihood produced in the generation process is used as a filtering score, which avoids the need of a separate filtering model. Our generator is trained by fine-tuning a pretrained LM using maximum likelihood estimation (MLE). We use BART (Lewis et al., 2019) as the pretrained LM in our experiments.

We perform experiments with three different variations of our synthetic QA data generator: (1) AQGen, which generates first the answer then the question; (2) QAGen, which generates first the question then the answer; (3) QAGen Two-step (2S), which generates first the question, concatenates it to the passage, then generates the answer in a second pass through the same encoder-decoder.

We focus our empirical evaluation on the task of data augmentation for domain adaptation of reading comprehension (RC) models trained on...
SQuAD 1.1 dataset. We assess the effectiveness of our QA data generators for domain adaptation of four different target domain datasets: Natural Questions (NQ), BioASQ, NewsQA and DuoRC. We compare our results with recent work on domain adaptation for QA as well as with a three-stage synthetic data generator. QAGen performs better than AQGen and the baselines for all datasets, while QAGen2S provides the best results overall because it allows bidirectional attention between passage and question. For NQ dataset, QAGen2S improves the SQuAD baseline by more than 8 points in EM and more than 7 points in F1. For NewsQA and BioASQ the gains in EM are also above 4 points. Additionally, we also demonstrate that synthetically generated data by QAGen2S can improve the in-domain performance of both small and large RC models, leading to F1/EM improvements of 1/0.5 and 3/1/2.2 on RoBERTa-large and bert-base-uncased trained RC models on SQuAD dev.

The main contributions of this work can be summarized as follows: (1) we propose the first effective end-to-end approach for synthetic QA data generation; (2) our approach solves an important issue in previous methods for QA data generation: the detection of good spans. We show that span detection can be effectively solved as a generation task, just like question generation; (3) as it uses a single end-to-end model, our data generation pipeline is simpler, faster and more efficient; (4) we perform comprehensive experiments that demonstrate the effectiveness of our proposed approach for domain adaptation of QA systems.

2 End-to-End Model for Question and Answer Generation and Filtering

We model the problem of synthetic QA data generation as a conditional language modeling task. More specifically, we use an encoder-decoder (enc-dec) conditional LM as described in what follows.

2.1 Enc-Dec Conditional Language Models

Language modeling consists of learning the probability distribution $p(x)$ over variable-length token sequences $x = (x_1, x_2, ..., x_{|x|})$, where the tokens come from a fixed size vocabulary $V$. The training of LMs typically involves solving the task of predicting the next token based on past tokens. The distribution $p(x)$ can be represented by the conditional probability of the next token given the previous ones (Bengio et al., 2003):

$$ p(x) = \prod_{i=1}^{|x|} p(x_i|x_{<i}) $$

In the case of conditional LMs, the generation is conditioned on an additional context $c$:

$$ p(x|c) = \prod_{i=1}^{|x|} p(x_i|x_{<i}, c) $$

Transformer-based encoder-decoder conditional LMs (Lewis et al., 2019; Raffel et al., 2019) use bidirectional self-attention in the encoding step to create vector representations of the tokens in the context $c$. The decoding step generates the tokens of the sequence $x$ in an auto-regressive manner, while performing self-attention on previously generated tokens of $x$ and all the representations output by the encoder for $c$.

2.2 Question-Answer Generation

In the case of end-to-end synthetic data generation for QA, we need to model the joint conditional distribution $p(a, q|c)$, where the input context $c$ is a passage, $q$ is a question and $a$ is the correct answer, which is a span in $c$. Our approach to model $p(a, q|c)$ involves fine-tuning a pretrained Enc-Dec conditional LM using a training set $D = \{ (c^1, q^1, a^1), (c^2, q^2, a^2), ..., (c^{|D|}, q^{|D|}, a^{|D|}) \}$. We train the Enc-Dec with parameters $\theta$ through maximum likelihood estimation (MLE) by minimizing the negative log-likelihood over $D$:

$$ \mathcal{L}(D) = -\sum_{i=1}^{|D|} \log p_{\theta}(a^i, q^i|c^i) $$

We can have different variations of the generator depending on how we place the items in the output sequence: answer-question or question-answer. This difference in the ordering is crucial because it defines which part is conditioned on the other. Based on this observation, we propose three variations of our generative model:

AQGen: this model generates answer and question jointly given the input context: $(q, a) \sim p(a, q|c)$. During sampling, the answer tokens are generated, which are followed by question tokens. This makes the generation of the question conditioned on both input context (through attention on the encoder) and answer (through self-attention in the decoder). Fig. 1 depicts this model.
QAGen: this model generates question and answer jointly given the input passage: \((q, a) \sim p(a, q|c)\). During sampling, the question tokens are generated, which are followed by answer tokens. This makes the generation of the answer conditioned on both input context (through attention on the encoder) and question (through self-attention in the decoder). Fig. 2 depicts this model.

QAGen Two-Step (2S): this model performs question generation and answer generation in two separate passes over the Enc-Dec LM. First, the question is generated given the input context \(q \sim p(q|c)\), (Step 1). Next, the question is concatenated with the passage and both are given to the encoder-decoder that generates the answer \(a \sim p(a|q, c)\), (Step 2). QAGen 2S sampling approach is illustrated in Fig. 3. This model uses a single Enc-Dec LM that is trained with samples of both \(p(q|c)\) and \(p(a|q, c)\). We use control codes \(<q>\) and \(<a>\) to inform the decoder whether to generate a question or an answer, respectively.

2.3 Decoding

A natural choice for decoding with conditional neural LMs is beam search. However, our preliminary experiments with beam search showed a lack of diversity and a high repetition of generated question-answer pairs. Generating diverse question-answer pairs is crucial to the performance of downstream RC models. Particularly, diversity of answer spans ensures that various parts of the passage are used, and different question types are generated. We use a variant of nucleus sampling (Holtzman et al., 2019), where we pick top \(k\) tokens, and within top \(k\), we pick tokens that comprise top 95% probability mass. We set \(k\) to 20 in our experiments. We refer to this setting as Topk+Nucleus. This decoding was used in QAGen, AQGen, and question sampling step in QAGen2S. The answer generation of QAGen2S was performed by greedy decoding. We discard generated \((q, a)\) pairs whose answers do not occur in the input passage, as non-extractive QA is outside the scope of this work. We observed between 10% to 15% of samples being dropped because of this issue.

2.4 Filtering

Recent work have used the round-trip filtering method (Alberti et al., 2019; Puri et al., 2020) to prune the synthetic QA set and improve data quality. This method consists of two steps: (1) using an RC model to provide answers to the generated questions; (2) dropping the QA pairs for which the answer of the RC model does not match the span detected answer. While round-trip filtering has shown to be effective, it is not the most efficient approach because it involves the application of an RC system over the whole set of generated data. Additionally, there might exist cases that are difficult for the filtering model, but in fact are of high quality.

We propose using the likelihood of the generated question-answers as a measure to perform filtering and address the efficiency issue, as it avoids the use of an RC model for filtering. We argue that such a likelihood score, albeit noisy, is an indicator of whether a generated question-answer is high quality for training a downstream RC model. We refer to this approach as LM filtering. Essentially, given an input passage, we sample \(n\) different QA pairs, rank them according to decreasing order of
Lymph node status has major prognostic importance in colorectal cancer and greater precision in the diagnosis of lymph node metastases should provide better prognostic and therapeutic guidance. Keratin 20 (K20) gene expression has been used as a marker of lymph node metastases, but the evidence for this remains circumstantial. This study has therefore sought to determine K20 specificity and to correlate K20 expression with mutan K-RAS expression, in order to provide direct evidence that K20 expression in lymph nodes of colorectal cancer patients genuinely reflects metastatic disease. Specificity of K20 expression was established against a range of tissue types and 289 lymph nodes from 41 non-cancer control patients. K20 expression was restricted to gastrointestinal epithelia and was only present in one of the 289 control lymph nodes, giving a calculated specificity of 97.6% (95% confidence limits: 87.1-99.9%).

**Table 1:** Samples of generated question-answer pairs using QAGen2S model for four target domains. The generated answers and answer-only scores for QAGen and QAGen2S be-

**LM score and pick the top m samples.** This is similar to the sample-and-rerank approach suggested by Holtzman et al. (2019) and Adiwardana et al. (2020). Formally, for QAGen and QAGen2S, we use the score:

$$LM \text{ score } = \sum_{i=1}^{N_a} \log p(a^i|c, q)$$

And for AQGen:

$$LM \text{ score } = \sum_{i=1}^{N_a} \log p(a^i|c) + \sum_{i=1}^{N_q} \log p(q^i|c, a)$$

Where $N_q$ and $N_a$ indicate the lengths of generated question and answer, respectively. We use answer-only scores for QAGen and QAGen2S because question quality would have a dominant effect on LM scores since questions are usually longer than answers. Additionally, using answer-only scores when conditioned on the generated question is more suitable for the RC tasks because it better mimics the score of a downstream RC model, which is answer centric. With AQGen, we use both answer and question LM scores, as answer generation is not conditioned on the question. We use likelihood summation instead of averaging because experiments showed that the former works slightly better. Further details included in Appendix B.3. We speculate this is due to average pooling encouraging longer question-answers, which could be of lower quality than shorter question-answer pairs.
3 Related Work

Question generation (QG) has been extensively studied from the early heuristic-based methods (Mitkov and Ha, 2003; Rus et al., 2010) to the recent neural-base approaches. However, most work (Du et al., 2017; Sun et al., 2018; Zhao et al., 2018; Kumar et al., 2019; Wang et al., 2020; Ma et al., 2020; Tuan et al., 2019; Chen et al., 2020) only takes QG as a stand-alone task, and evaluates the quality of generated questions with either automatic metrics such as BLEU, or human evaluation. Tang et al. (2017), Duan et al. (2017) and Sachan and Xing (2018) verified that generated questions can improve the downstream answer sentence selection tasks. Song et al. (2018) and Klein and Nabi (2019) leveraged QG to augment the training set for machine reading comprehend tasks. However, they only got improvement when only a small amount of human labeled data is available. Recently, with the help of large pre-trained language models, Alberti et al. (2019) and Puri et al. (2020) have been able to improve the performance of RC models using generated questions. However, they need two extra BERT models to identify high-quality answer spans, and filter out low-quality question-answer pairs. Lee et al. (2020) follow a similar approach while using InfoMax Hierarchical Conditional VAEs. Nishida et al. (2019) showed improvements by fine-tuning the language model on the target domains.

4 Experimental Setup and Results

4.1 Datasets

We used SQuAD 1.1 dataset (Rajpurkar et al., 2016) to train the generative models as well as in-domain supervised data for the downstream RC task in this work. We used the default train and dev splits, which contain 87,599 and 10,570 (q, a) pairs, respectively.

Similar to (Nishida et al., 2019), we selected the following four datasets as target domains:

**Natural Questions** (Kwiatkowski et al., 2019), which consist of Google search questions and the annotated answers from Wikipedia. We used MRQA Shared Task (Fisch et al., 2019) preprocessed training and dev sets, which consist of 104,071 and 12,836 (q, a) pairs, respectively. The training set passages were used as the unlabeled target domain corpus, while the evaluations were performed on the dev set.

**NewsQA** (Hermann et al., 2015), which consists of question and answer pairs from CNN news articles. We used the dev set from the MRQA Shared Task, which removes unanswerable questions and those without annotator agreement. We prefer this version as we focus only on the generation of answerable questions. The dev set consists of 4,212 (q, a) pairs. Passages from CNN/Daily Mail corpus of Hermann et al. (2015) are used as unlabeled target domain corpus.

**BioASQ** (Tsatsaronis et al., 2015): we employed MRQA shared task version of BioASQ, which consists of a dev set with 1,504 samples. We collected PubMed abstracts to use as target domain unlabeled passages.

**DuoRC** (Saha et al., 2018) contains question-answer pairs from movie plots which are extracted from both Wikipedia and IMDB. ParaphraseRC task of DuoRC dataset was used in our evaluations, consisting of 13,111 pairs. We crawled IMDB movie plots to use as the unlabeled target domain corpus.

4.2 Experimental Setup

We used Pytorch (Paszke et al., 2019) and Transformers (Wolf et al., 2019) to develop the models and perform experiments. Generative models are trained on SQuAD 1.1 for 5 epochs, and the best model is selected based on the cross entropy loss on the SQuAD dev set. AdamW (Loshchilov and Hutter, 2017) optimizer with learning rate of $3 \times 10^{-5}$ is employed.

For RC model training, we use `bert-base-uncased` model (Devlin et al., 2018). AdamW optimizer is used with learning rate of $3 \times 10^{-5}$ and batch size 24 for 2 epochs without linear warmup. We set maximum sequence length 384 with document stride 128. SQuAD 1.1 dev set is used to select the best model during training. As a baseline for QA data generation, we implemented a three-stage pipeline similar to the state-of-the-art approach of Puri et al. (2020). We call this baseline **QGen**, which generates a question given a passage and extracted span, $q \sim p(q|a, c)$. The span detection module consists of `bert-base-uncased` fine-tuned on SQuAD 1.1 passage and spans, where the start and end classification heads are trained to perform span detection. For QGen, we experimented with sampling top 5 spans and generating two questions per each, as suggested by (Puri et al., 2020), as
well as sampling top 10 spans and generating one question per each. Our results showed the latter outperforming the former. Henceforth, we used this configuration in our evaluations.

We trained QGen models on both BART-Large and GPT2-Medium (Radford et al., 2019), which have an equivalent number of parameters, 406M (BART) vs 350M (GPT2), and evaluated BLEU score of the generated question w.r.t. the ground truth question on the SQuAD dev set. BART and GPT2 achieved 21.29 and 18.31 BLEU, respectively. We believe the bi-directional encoding in BART is superior to uni-directional encoding in GPT2. Hence, we used BART for the rest of the experiments.

4.3 Synthetic Data Generation
For each of the unlabeled target domain corpora, we randomly selected 100,000 passages to perform synthetic data generation. Passages shorter than 100 tokens were discarded. Selected ones were truncated to maximum length of 550 tokens. We removed the passages that existed in the dev sets.

Question-answer generation with AQGen, QAGen, and QAGen2S is performed using Topk+Nucleus, as discussed in Sec. 2.3. For each passage, 10 samples are generated. Unless otherwise mentioned, LM filtering is applied by sorting the 10 samples of each passage according to LM scores as detailed in Sec. 2.4, and the top 5 samples are selected. The number of synthetically generated pairs is between 860k to 890k without filtering and 480k to 500k after LM filtering. Tab. 1 shows generated question-answer pairs from four target domain (see Appendix for more examples). We can observe that the generative model is able to generate question answer pairs even from raw HTML input that corresponds to a table. The rendered table can be seen in Tab. 12 (Appendix C.3). Considering the fact that the training data of the generative model does not include any HTML input, this further demonstrates the robustness and efficacy of our proposed approach.

4.4 Domain Adaptation Results
Tab. 2 shows the results of domain adaptation experiments. Each experiment was performed by training the RC model on the synthetic data generated on the target domain corpus. We refer to the dataset to which the downstream model is being adapted as the target domain. Source domain indicates the supervised training dataset (SQuAD).

We also performed experiments by using both Synthetic + SQuAD1.1 data. Our QGen and QA-Gen2S models outperform by wide margins the baseline models trained on SQuAD 1.1 only, as well as unsupervised domain adaptation approaches (UDA) suggested by Nishida et al. (2019) and Lee et al. (2020). Additionally, QGen and QAGen2S significantly outperforms QGen, our implementation of the three-stage pipeline of Puri et al. (2020).

Even though our SQuAD 1.1 baselines are generally higher than both Nishida et al. (2019) and Lee et al. (2020), our best model achieves more point-wise improvements in all of the target domain datasets, except with BioASQ, where Nishida et al. (2019) observe 4.3 points in EM versus 4 points with ours, and 4.2 points in F1 versus 2.2 with ours.

Comparing LM and round-trip filtering when applied to the best performing model, QAGen2S, we can observe that the LM filtering approach (Sec. 2.4) is more effective than round-trip filtering in BioASQ and DuoRC target domains. It barely underperforms (∼1 point) in F1 and EM in the other two domains. This demonstrates the efficacy of the suggested filtering approach, which also simplifies the question-answer generation pipeline.

The highest (EM/F1) domain adaptation gains seen with BioASQ (4/2.2) and DuoRC (1.2/1.1) are smaller than those with Natural Questions (8.5/7.5) and NewsQA (5.5/4.5). We postulate this is due to two reasons: Firstly, both BioASQ and DuoRC domains are more dissimilar to the source domain, SQuAD, compared to NewsQA and Natural Questions; Secondly, BioASQ and DuoRC are more difficult datasets. Comparing our results with supervised target domain training of DuoRC, we observe that with using only synthetic data outperforms the DuoRC training set, which consists of 39144 pairs. While our domain adaptation methods show substantial gains with NewsQA and Natural Questions domain, there is still room for improvements to match the performance of supervised target domain training (last row in Tab. 2).

While results in Tab. 2 suggest that generating synthetic QA data from target domain text leads to significant gains on the target domain dev set, one can argue whether it is essential to generate synthetic data from the corpus matching the target dev set’s domain to achieve good performance. Hence, we performed cross-domain experiments to check this argument. Tab. 3 shows the performance
### Table 2: Domain adaptation results for different methods. **Bold** cells indicate the best performing model on each of the target domain dev sets, excluding supervised target domain training results.

| Model                  | fine-tune Data | NQ | NewsQA | BioASQ | DuoRC |
|------------------------|----------------|----|--------|--------|-------|
| SQuAD 1.1 Nishida et al. (2019) | SQuAD           | 44.4 | 57.5  | 35.2 | 50.7 | 41.1 | 53.6 | 24.5 | 33.0 |
| UDA Nishida et al. (2019) | SQuAD           | 43.8 | 56.7  | 35.9 | 51.4 | 45.4 | 57.8 | 25.5 | 34.1 |
| SQuAD 1.1 Lee et al. (2020) | SQuAD+Synthetic | 42.7 | 57.2  |      |      |      |      |      |      |
| SQuAD 1.1 Nishida et al. (2019) | Synthetic       | 44.6 | 58.9  | 29.5 | 50.6 | 44.5 | 50.6 | 28.5 | 34.2 |
| Our SQuAD 1.1            | Synthetic       | 48.0 | 61.7  | 36.0 | 53.7 | 53.7 | 53.7 | 28.5 | 34.2 |
| QGen + round-trip filtering | + SQuAD          | 49.0 | 62.6  | 39.6 | 55.2 | 49.0 | 54.1 | 29.3 | 34.0 |
| AQGen (ours) + LM filtering | Synthetic       | 47.8 | 61.2  | 38.5 | 54.0 | 38.5 | 49.0 | 29.3 | 33.7 |
| QAGen (ours) + LM filtering | + SQuAD         | 49.0 | 62.6  | 39.6 | 55.2 | 49.0 | 54.1 | 29.3 | 34.0 |
| QAGen2S (ours) + LM filtering | Synthetic       | 32.6 | 56.0  | 33.0 | 50.3 | 32.6 | 56.0 | 25.5 | 34.1 |
| QAGen2S (ours) + SQuAD   | Synthetic       | 50.3 | 65.5  | 43.5 | 57.9 | 48.0 | 58.3 | 30.0 | 36.5 |
| All 4 data sources      |               | 53.3 | 66.4  | 45.6 | 60.7 | 45.6 | 60.7 | 29.4 | 35.2 |

### Table 3: Cross domain experiments using QAGen2S as the generative model. **Underlined** cells indicate best EM/F1 value for each of the target domain dev sets (column-wise) and individual target domain corpus.

| Target Domain Corpus | fine-tune Data | NQ | NewsQA | BioASQ | DuoRC | SQuAD |
|----------------------|----------------|----|--------|--------|-------|-------|
| SQuAD 1.1            | SQuAD          | 44.6 | 58.9  | 39.5 | 50.6 | 28.5 | 34.2 | 80.8 | 88.2 |
| Natural Questions    | Synthetic      | 52.6 | 65.6  | 40.4 | 55.3 | 27.8 | 33.3 | 79.9 | 86.8 |
| CNN/DM               | + SQuAD        | 52.0 | 65.7  | 40.4 | 55.3 | 27.8 | 33.3 | 79.9 | 86.8 |
| PubMed               | Synthetic      | 48.8 | 61.7  | 37.7 | 55.6 | 26.7 | 32.0 | 78.6 | 85.6 |
| IMDB                 | + SQuAD        | 48.8 | 61.7  | 37.7 | 55.6 | 26.7 | 32.0 | 78.6 | 85.6 |
| All 4 data sources   | Synthetic      | 53.3 | 66.3  | 43.6 | 56.3 | 29.1 | 34.7 | 82.7 | 89.0 |

### 4.5 Comparison of AQGen, QAGen and QAGen2S models

Comparing our proposed LM filtering-based models in Tab. 2, we propose the following explanations: (1) QAGen2S and QAGen outperform AQGen because generating answers conditioned on the question results in better spans, which is crucial in the training of the downstream RC task. Generated answer spans not conditioned on questions could include spurious tokens, or be a partial span. (2) QAGen2S outperforms QAGen because including the generated question in the bidirectional encoder allows cross attention between the passage and generated question, which results in even more accurate answer generation. Comparing the performance when only synthetic question-answer pairs are employed versus adding SQuAD training pairs, we can observe that the addition of labeled data results in marginal gains. This becomes even more evident for the best performing data generators. In fact, in some cases, adding SQuAD data degrades EM, such as QAGen2S + LM filtering with Natural on every target domain dev set of RC models fine-tuned on synthetic data of different target domain corpora. We can see that diagonal elements, which have same domain of dev set and target corpus, show either the best performance (underlined results) or are within a narrow margin of top EM/F1 scores. Therefore, the most effective strategy is achieved when the passages used in the generation of synthetic samples are from the same domain as the target, which is expected in a domain adaptation method. Additionally, we trained an RC model with the synthetic data from all the four domains (last two rows in Tab. 3). This produced our best F1 results for all datasets, indicating that mixing synthetic data from different domains is beneficial for the QA task. Tab. 3 also shows EM/F1 scores of the cross-domain RC models on SQuAD 1.1 dev set. We can see that using synthetic data from any of the four domains significantly improved the performance for SQuAD. In particular, when training the RC model with data from all domains + SQuAD training data (last row), there is a large gain in both EM (3.8) and F1 (2.7).
Questions and NewsQA.

### 4.6 Ablation Studies

#### Sampling Design Choices

Tab. 4 shows a comparison between beam search and Topk+Nucleus sampling with different number of samples (5, 10, and 20). The results indicate that beam search underperforms Topk+Nucleus. We attribute this to the lack of diversity in the generated samples using beam search. We observed that beam search tends to select fewer distinct spans, compared to Topk+Nucleus, and generates minor variations of the same question. Appendix C.1 examines this issue.

When training the RC model we only used the top 5 samples based on LM score per each passage. We can observe that sampling 10 pairs per document leads to the best EM/F1 on the target domain. By sampling many QA pairs per passage, we increase the chance of generating good samples. However, if we sample too many qa pairs the top ranked ones might be too similar. Therefore, we used sample size of 10 in this work since a higher sample size incurs higher computation cost while not showing improvements.

#### LM Filtering

We argue that using LM filtering, as discussed in section 2.4, results in improvements in the target domain downstream RC models by enhancing the quality of the generated \((q, a)\) pairs. Results in Tab. 5 indicate that in the majority of the experiments using LM filtering leads to improved F1/EM metrics. AQAgen benefits the most from LM filtering as it generates data with lower quality than the other two models. Tables 10 and 12 in the Appendix show examples of QA pairs and their LM scores.

Fig. 4 shows experimental results when varying the number of \((q, a)\) pairs selected per passage. We chose the value of 5 as this configuration outperforms other values overall. A high value is more likely to allow undesired pairs, while a low value might discard plenty of high quality samples.

![Effect of number of QAs selected per passage in LM filtering. QAGen2S model is used for generation. The likelihood score of the generated answer is used to sort the generated question answer pairs decreasingly.](image)

Table 5: Comparison of using LM filtering versus no filtering. Bold values indicate best performance on each target domain for each model (per rows separated by sold lines).

| Model                          | F1 Data | NQ       | BioASQ   |
|-------------------------------|---------|----------|----------|
| AQGen w/o filter. Synth.      | 46.93   | 60.71    | 41.49    | 53.59    |
| + SQ                          | 46.84   | 61.00    | 41.36    | 53.84    |
| AQGen + LM filter. Synth.     | 47.80   | 67.29    | 49.34    | 52.71    |
| + SQ                          | 49.04   | 62.56    | 42.89    | 54.90    |
| QAGen w/o filter. Synth.      | 50.01   | 63.10    | 45.74    | 55.06    |
| + SQ                          | 50.01   | 63.10    | 45.74    | 55.06    |
| QAGen2S w/o filter. Synth.    | 47.12   | 62.61    | 46.88    | 58.92    |
| + SQ                          | 46.73   | 62.63    | 47.41    | 59.33    |
| QAGen2S + LM filter. Synth.   | 52.54   | 67.55    | 48.30    | 55.73    |
| + SQ                          | 52.03   | 65.70    | 46.74    | 57.76    |

Correlation between LM and F1 Scores

In this work, we proposed using the LM score of the generated samples as a surrogate to round-trip filtering. We postulate that the LM score correlates with the F1 score used in round-trip filtering. To more thoroughly examine this, we devised an experiment where we sorted the generated samples by their answer LM scores, divided them into contiguous buckets each with 200 samples, and calculated the average F1 score of the samples in each bucket. Fig. 5 shows the results of this experiment. As we can see, there exists a strong correlation between the two scores.
While the correlation looks promising, a challenge with using the LM score is that it is relatively noisy. For example, to use the LM score to get only samples whose F1 scores are 1, a very high threshold needs to be set, forcing the vast majority of samples to be dropped. Future work can explore how to reduce this noise.

Impact of Synthetic Dataset Size

In Fig. 6, we present plots that correlate synthetic dataset size (in # of passages) and RC model performance (EM/F1). We can see that with increasing the number of generated \((q,a)\) pairs (5 pairs per passage), RC model performance improves. Such correlation is more evident when not using the SQuAD training data. This is expected as with added supervised training samples, there would be less need for a large number of synthetic samples.

4.7 Experiments with Large QA Models

The downstream RC models presented in previous sections were based on fine-tuning BERT-base model, which has 110 million parameters. In this section, we assess the efficacy of our proposed domain adaptation approach on a higher capacity transformer as the RC model. For these experiments, we chose pretrained RoBERTa-large (Liu et al., 2019) model from transformers library (Wolf et al., 2019), which has 355 million parameters. Tab. 6 displays the domain adaptation results on the NQ domain using QAGen2S generated samples. It also includes performance on the source domain dev set. Although the SQuAD 1.1 baselines (first row), is significantly higher than those with BERT-base in Tab. 2, EM/F1 gains of 5.8/3.4 are achieved on the target domain. 1/0.5 gains in EM/F1 are observed in SQuAD 1.1 dev set. These results demonstrate that our proposed end-to-end synthetic data generation approach is capable of achieving substantial gains even on state-of-the-art RC baselines such as RoBERTa-large.

| Model                       | FT Data  | SQuAD L1 | NQ   |
|-----------------------------|----------|----------|------|
| SQuAD 1.1 (SQ)             | SQ       | 86.43    | 93.18|
| QAGen2S w/o filter.        | Synth.   | 85.39    | 92.13|
| QAGen2S + LM filter.       | + SQ     | 86.23    | 93.19|
| QAGen2S + RT filter.       | Synth.   | 85.77    | 92.07|
| QAGen2S + RT filter.       | + SQ     | 86.75    | 93.50|

Table 6: Source and target domain performance with RoBERTa-large as downstream RC model.

5 Conclusions

We presented a novel end-to-end approach to generate question-answer pairs by using a single transformer-based model. Our experiments showed that by proper decoding, significant improvements in domain adaptation of RC models can be achieved. We concluded that using LM filtering improves the quality of synthetic question-answer pairs; however, there is still a gap with round-trip filtering with some of the target domains. Improving LM-score-based filtering is a future direction of our work.

While we were able to generate diverse, high quality and challenging synthetic samples on the target domains, the types of the questions produced still were limited to those of SQuAD, since the generative models were trained on SQuAD. It would be interesting to explore how one can adapt the generative models to the target domain questions.
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A Additional Details Regarding the Datasets Used

**SQuAD 1.1** dataset is used to train the generative models as well as in-domain supervised data for the downstream RC task. We use the default train and dev splits, which contain 87,599 and 10,570 \((q,a)\) pairs, respectively. SQuAD 1.1 questions exhibit high lexical overlap with answers, since annotators were presented with passages and extracted answers when creating questions.

**Natural Questions** dataset consists of Google search questions, the Wikipedia pages from top 5 search results, and the corresponding annotated answers. This dataset and SQuAD are both derived from Wikipedia pages, however, questions from Natural Questions have considerably less ngram overlap with annotated answers compared to those from SQuAD. Also different from SQuAD, Natural Questions dataset contains passages with HTML tables and tags. We use MRQA Shared Task preprocessed training and dev sets, which consist of 104,071 and 12,836 \((q,a)\) pairs, respectively. We utilize training set passages as the target domain (unlabeled) corpus, while preforming evaluations on the dev set.

**NewsQA** consists of question and answer pairs from CNN news articles. We use the dev set from the MRQA Shared Task, which removes unanswerable questions and those without annotator agreement. We believe this version better suits our work, as we focus only on generation of answerable questions. The train and dev sets consists of 74,160 and 4,212 samples, respectively. Passages from CNN/Daily Mail corpus are used as target domain passages.

**BioASQ** challenge is a competition on semantic indexing and question answering tasks based on annotated PubMed documents. As with the previous dataset, we employ MRQA shared task version of BioASQ, which consists of a dev set with 1,504 pairs. We collected PubMed abstracts to use as target domain passages. Being from Biomedical domain, BioASQ makes a clear domain shift from other datasets.

**DuoRC** contains question answer pairs from movie plots which are extracted from both Wikipedia and IMDB. This dataset has been developed to have question and answer pairs with minimal lexical overlap, which makes it more challenging. ParaphraseRC task of DuoRC dataset is used in our evaluations. Training and dev sets include 39,144 and 13,111 pairs, respectively. We crawled IMDB movie plots to use as the target domain unlabeled corpus. The dataset has been developed by selecting the same movie plot from both sources, and generating question from one source and selecting the answer from the other. This approach has resulted in question and answer pairs with minimal lexical overlap.

All of the validation sets of the aforementioned out-of-domain tasks are identical to those used by Nishida et al., except DuoRC, where we use MRQA shared task formatted DuoRC dev set.

B Additional Ablation Studies

**B.1 Performance on SQuAD 1.1 with Different Filtering Approaches**

While the performance of the RC models on the target domains is important, weak performance on the source domain could inhibit the use of our proposed methods in applications that require strong performance in both source and target domains. Tab. 7 shows EM/F1 scores of the bert-base-uncased RC models trained with synthetic data generated from the IMDB corpus on SQuAD 1.1 dev set. We can observe that adding synthetic samples to the SQuAD training set always improves the performance on the dev set compared to using the SQuAD training set only. In fact, with QAGen2S, impressive 3.1(EM)/2.2(F1) gains are achieved. Synthetic only samples from the same model outperform the SQuAD baseline. Similar to previous domain adaptation results, we observe that QAGen2S outperforms QAGen, and QAGen exceeds AQGen.

**B.2 Comparison of Using Filtering vs. No Filtering**

Tab. 8 presents comprehensive results of using LM filtering over all the of the target domains. We can observe that the arguments made in Sec. 4.7 hold for NewsQA and DuoRC as well.

**B.3 Impact of Language Model Score Pooling**

To aggregate the LM scores of a given question-answer pair, one can use either sum or average of the token scores, as defined in Sec. 2.4. We experimented with both options and summarized the results in Tab. 9 for QAGen and AQGen models. We can observe that using summation generally outperforms averaging. We speculate this is because average pooling encourages longer question-
answer pairs, which are more likely to consist of incorrect samples. By using summation, shorter question-answer pairs would be more likely to be selected during LM filtering.

C Examples of Generated Samples

C.1 Illustration of Answer LM Score

Tab. 10 presents unfiltered question-answer pairs and associated answer LM scores generated from a randomly selected Natural Questions corpus using the QAGen2S model. As can be seen from Topk+Nucleus decoded samples, the last two generated samples are incorrect and would be filtered out using the LM filtering approach that is used in this work. The last sample, which consists of an answer that is entirely irrelevant to its question, has a considerably lower answer LM score than the rest of the samples.

With beam search, due to the high number of repetitions, the scores are close. While beam search generates samples with high likelihood, due to the lack of diversity, as evident here, the performance of the trained RC models on such synthetic samples underperforms those of Topk+Nucleus.

C.2 Comparison of Generated Samples by AQGen, QAGen and QAGen2S

Tab. 11 presents unfiltered question-answers pairs generated using each of our proposed models on a randomly selected passage from CNN/Daily Mail corpus. We can observe that generated samples using AQGen have lower quality than the other two models. Also, the selected spans are repetitive. Only 3 out of the 6 properly generated samples are correct question-answer pairs. Comparing QAGen and QAGen2S samples, we can observe that QAGen2S generates more diverse and longer answer spans. In this example, we can see that more repeated spans are generated by QAGen than QAGen2S.

While the Topk+Nucleus sampling approach improves the diversity of generated question-answer pairs, we can still see repetitions and incorrect pairs. We believe using the LM score filtering, the vast majority of incorrect pairs are discarded. However, this also means there is room for improving the generative models.

C.3 Question Answers from Table

The Natural Questions dataset includes HTML formatted passages. We noticed that some of them
Table 9: Comparison of using average versus summation of LM scores when doing LM filtering. **Bold** values indicate the best performance on each target domain for each model (per rows separated by solid lines).

| Model | LM Pooling | fine-tune Data | NQ EM F1 | NewsQA EM F1 | BioASQ EM F1 | DuoRC EM F1 |
|-------|------------|----------------|----------|--------------|--------------|-------------|
| AQGen - Sum | Synthetic + SQuAD | + SQuAD | 49.04 | 62.56 | 39.62 | 56.89 | 42.89 | 54.90 | 27.88 | 34.40 |
| AQGen - Avg | Synthetic + SQuAD | + SQuAD | 45.03 | 59.87 | 35.21 | 53.08 | 40.88 | 53.74 | 26.7 | 33.26 |
| QAGen - Sum | Synthetic + SQuAD | + SQuAD | 50.01 | 63.10 | 40.06 | 59.20 | 45.74 | 55.06 | 29.91 | 35.82 |
| QAGen - Avg | Synthetic + SQuAD | + SQuAD | 50.18 | 63.71 | 42.76 | 58.65 | 42.15 | 52.21 | 29.01 | 35.05 |

Table 10: Samples of generated question-answers pairs using QAGen2S model from Natural Questions passages with their LM scores. Sum of answer likelihood scores is used to sort the pairs decreasingly. The generated answers are shown in **bold**.

| Passage: | <P> The United States is estimated to have a population of 327,589,916 as of April 23, 2018, making it the third most populous country in the world. It is very urbanized, with 81% residing in cities and suburbs as of 2014 (the worldwide urban rate is 54%). California and Texas are the most populous states, as the mean center of U.S. population has consistently shifted westward and southward. New York City is the most populous city in the United States. <P> |
| Topic: Nucleus | Q: As of April 23, 2018, what is the estimated population of the US? | A: 327,589,916 | LM score: -0.00577 |
| Q: What is the population of the United States? | A: 327,589,916 | LM score: -0.00707 |
| Q: What is the most populous city in the United States? | A: New York City | LM score: -0.04131 |
| Q: Where do 81 percent of Americans live? | A: cities and suburbs | LM score: -0.05560 |
| Q: Where does the United States rank among most populous countries on the planet? | A: third | LM score: -0.07449 |
| Q: How much of the US’s population is concentrated in the metropolitan areas of the country? | A: 81% | LM score: -0.09509 |
| Q: What two cities have the highest populations in America? | A: California and Texas | LM score: -0.18128 |
| Q: What country is considered the most populous? | A: third | LM score: -1.85929 |

Table 10: Samples of generated question-answers pairs using QAGen2S model from Natural Questions passages with their LM scores. Sum of answer likelihood scores is used to sort the pairs decreasingly. The generated answers are shown in **bold**.

| Passage: | <P> The United States is estimated to have a population of 327,589,916 as of April 23, 2018, making it the third most populous country in the world. It is very urbanized, with 81% residing in cities and suburbs as of 2014 (the worldwide urban rate is 54%). California and Texas are the most populous states, as the mean center of U.S. population has consistently shifted westward and southward. New York City is the most populous city in the United States. <P> |
| Topic: Nucleus | Q: As of April 23, 2018, what is the estimated population of the US? | A: 327,589,916 | LM score: -0.00577 |
| Q: As of April 23, 2018, what was the population of the United States? | A: 327,589,916 | LM score: -0.00529 |
| Q: As of April 23, 2018, how many people live in the United States? | A: 327,589,916 | LM score: -0.00618 |
| Q: How many people live in the United States? | A: 327,589,916 | LM score: -0.0132 |
| Q: What is the population of the United States? | A: 327,589,916 | LM score: -0.0135 |

D Training and Platform Details

All of the experiments in this work were performed on Amazon EC2 instances. We employed p3.8xlarge, p3.16xlarge, and p3dn.24xlarge GPU instances. In the training of the generative models, warmup was set to 10% of total training steps. We used a batch size of 24. Each epoch took 2 to 3 hours on 3 GPUs. We observed that usually, the best model is achieved within the first two epochs.

The RC models with Synthetic+SQuAD samples were trained by combining synthetic samples and SQuAD training set and randomly shuffling them. Each epoch of training took 2 to 12 hours, depending on the average length of target domain passages on 1 GPU.

All of the hyperparameters of both generative and RC downstream models were fixed. We only performed hyperparameter tuning on those mentioned in the paper.
Fifteen people have now died after consuming cantaloupe contaminated with the listeria monocytogenes bacteria, the Centers for Disease Control and Prevention said Friday. At least 84 people in 19 states have become ill with the bacteria, the agency said. And the number of illnesses could still grow, added the CDC, citing reporting lags and how the disease can develop slowly in some people. On Tuesday, the CDC was reporting 13 deaths and 72 illnesses in what was already then the deadliest food-borne illness outbreak in the United States since 1998. Five people have died in New Mexico from eating the tainted cantaloupes, the CDC said. Three people died in Colorado, two in Texas and one each in Kansas, Maryland, Missouri, Nebraska and Oklahoma. Illnesses have also been reported in Alabama, Arkansas, California, Illinois, Indiana, Montana, North Dakota, Virginia, West Virginia, Wisconsin and Wyoming. What you need to know about Listeria. Most of those who fell ill are more than 60 years old, the CDC said. Doctors also are closely monitoring the pregnancies of two women who ate contaminated cantaloupe, with the agency noting that listeriosis can cause miscarriages and stillbirths. Older adults and people with compromised immune systems are also especially susceptible. Public health investigators have traced the source of the bacteria to a farm in Granada, Colorado. Food Poisoning 101. The grower, Jensen Farms, issued a recall for its Rocky Ford-brand cantaloupes on September 14. By now, the cantaloupes should all be off store shelves, the CDC said. The agency warned that people should not eat Rocky Ford cantaloupes, even if they have eaten part of one and have not yet fallen ill. It also said that consumers should be wary of eating any cantaloupes if they don’t know where they came from. How to keep your food safe.
Table 12: Generated samples using QAGen2S model from a Natural Questions passage consisting of a table. Sum of answer likelihood scores are chosen to sort the pairs decreasingly.