Quadratic BSDEs driven by a continuous martingale and applications to the utility maximization problem

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Abstract In this paper, we study a class of quadratic Backward Stochastic Differential Equations (BSDEs) which arises naturally in the utility maximization problem with portfolio constraints. We first establish existence and uniqueness of solutions for such BSDEs and we then give applications to the utility maximization problem. Three cases of utility functions: the exponential, power and logarithmic ones, will be discussed.

Keywords Backward Stochastic Differential Equations (BSDEs) · continuous filtration · quadratic growth · utility maximization · portfolio constraints.

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1 Introduction

In this paper, the problem under consideration consists in maximizing the expected utility of the terminal value of a portfolio under constraints. The main objective is to give the expression of the value process of the utility maximization problem with utility function $U$ and liability $B$, whose expression at time $t$ is

$$V_t^B(x) = \text{ess sup}_{\nu \in \mathcal{A}_t} \mathbb{E}_{\mathcal{F}_t} (U(X_{T}^\nu, t, x - B)).$$

(1.1)

In our model, $X_{T}^\nu, t, x$ is the terminal value of the wealth process associated with the strategy $\nu$ and equal to $x$ at time $t$ and the essential supremum is taken over all trading strategies $\nu$, which are defined on $[t, T]$ and take their values in an admissibility set denoted by $\mathcal{A}_t$. Since not any $\mathcal{F}_T$-measurable random variable $B$ is replicable by a strategy taking its values in $\mathcal{A}_t$, the financial market is incomplete. This problem provides further interests due to its connection with utility indifference valuation: in

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1 This study is part of my PhD thesis supervised by Professor Ying Hu and defended at the university of Rennes 1 (in France) in October 2007.
fact, the utility indifference price relates the two value processes $V^B$ and $V^0$. Introduced by Hodges and Neuberger (1989), the utility indifference selling price stands for the amount of money which makes the agent indifferent between selling or not selling the claim $B$.

Among previous studies of our problem, we refer to [2] and [18]. In the first, Becherer studies both the utility maximization problem and the notion of utility indifference valuation in a discontinuous setting, whereas, in the second paper, Mania and Schweizer consider the same problem in a continuous framework. As in these two papers and to solve the problem (1.1) in the case of non convex trading constraints, we rely on the dynamic programming methodology and on non linear BSDE theory. In the existing literature (see e.g. [3], [19] or [24]), the convex duality method is widely used to study the unconditional case of the problem, but in the aforementioned papers, the authors either suppose there is no constraints or they assume the convexity of the constraint set, which is an assumption we relax here. We rather use the first method to handle dynamically the problem and, for this approach, some major references are [12] and [18]. Our contribution consists in extending the dynamic method in a general continuous setting and in presence of constraints. This requires to establish existence and uniqueness results for solutions to specific quadratic BSDEs and then use these results to characterize both the value process expressed at time $t$ in (1.1) and the strategies attaining the supremum in this last expression.

The paper is structured as follows: Section 2 lays out the financial background and gives some preliminary tools and results about BSDEs. Then, the dynamic programming method is applied to derive an explicit BSDE. Section 3 investigates the existence and uniqueness results for solutions to the introduced BSDEs. In Section 4, applications to finance are developed and the expression of the value process is provided for three types of utility functions. Lengthy proofs are relegated to an appendix.

## 2 Statement of the problem and main results

### 2.1 The model and preliminaries

As usual, we consider $(\Omega, \mathcal{F}, P)$ a probability space equipped with a right-continuous and complete filtration $\mathcal{F} = (\mathcal{F}_t)$, and with a continuous $d$-dimensional local martingale $M$. Throughout this paper, all processes are considered on $[0, T]$, $T$ being a deterministic time and we denote by $Z \cdot M$ the stochastic integral of $Z$ w.r.t. $M$. We also assume that $\mathcal{F} = (\mathcal{F}_t)_{t \in [0, T]}$ is a continuous filtration: this means that any $\mathbb{R}$-valued (square integrable) $\mathcal{F}$-martingale $K$ is continuous and can be written

$$K = Z \cdot M + L,$$

with $Z$ a predictable $\mathbb{R}^d$-valued process and $L$ a (square integrable) $\mathbb{R}$-valued martingale strongly orthogonal to $M$ (i.e., for each $i$, $\langle M^i, L \rangle = 0$). For a given square integrable martingale $M$, the notation $\langle M \rangle$ stands for the quadratic variation process and the notation $| \cdot |_\infty$ stands for the norm in $L^\infty(\mathcal{F}_T)$ of any bounded $\mathcal{F}_T$- measurable random variable.

From the Galchouk-Kunita-Watanabe inequality, it follows that each component $d\langle M^i, M^j \rangle$ $(i, j \in \{1, \ldots, d\})$ is absolutely continuous with respect to $d\widetilde{C} = (\sum_i d\langle M^i \rangle)$. Hence, there exists an increasing and bounded process $C$ (for instance, we set: $C_t =$
arctan(\(\hat{C}_t\)), for all \(t\) such that \(\langle M \rangle\) can be written

\[d\langle M \rangle_s = m_s \hat{m}_s dC_s,\]

where \(m\) is a predictable process taking its values in \(\mathbb{R}^{d \times d}\) (this expression has been used in [8] in an analogous continuous framework). The notation \(\hat{m}_s^t\) stands for the transposed matrix and we also assume that, for any \(s\), the matrix \(m_s\hat{m}_s^t\) is invertible, \(\mathbb{P}\)-a.s.

The financial background To bring further motivations, we explain the financial context and, for this, we provide here all the definitions and common assumptions. We consider a financial market consisting in \(d + 1\) assets: one risk free asset with zero interest rate and \(d\) risky assets. We model the price process \(S\) of the \(d\) risky assets as a process satisfying

\[
\frac{dS_s}{S_s} = dM_s + dA_s, \quad \text{with: } \forall j \in \{1, \cdots, d\}, dA^j_s = \sum_{i=1}^{d} \lambda^i_s d\langle M^i, M^j \rangle_s, \tag{2.1}
\]

\((\langle M^i, M^j \rangle)_j\) standing for the \(i^{th}\) column of the \(\mathbb{R}^{d \times d}\) matrix-valued process \(\langle M \rangle\) and \(\lambda\) a \(\mathbb{R}^d\)-valued process satisfying

\[
(H_{\lambda}) \quad \exists a_\lambda > 0, \quad \int_0^T \lambda^t_s d\langle M \rangle_s \lambda_s = \int_0^T |m_s \lambda_s|^2 dC_s \leq a_\lambda, \quad \mathbb{P}\text{-a.s.} \tag{2.2}
\]

This definition is stronger than the usual structure condition, which only states:

\[
\int_0^T \lambda^t_s d\langle M \rangle_s \lambda_s < \infty, \quad \mathbb{P}\text{-a.s.} \text{ (we refer to [1] or [11] for this condition) and, in particular, it implies that } \mathcal{E}(-\lambda \cdot M) \text{ is a strict martingale density for the price process } S. \text{ In the financial application, we rely on } (H_{\lambda}) \text{ to use the precise a priori estimates given in Lemma 3.1 in Section 3.} \text{ We now state the definition of wealth process } X^\nu \text{ and of the associated self-financing and constrained trading strategy } \nu.

**Definition 2.1** A predictable \(\mathbb{R}^d\)-valued process \(\nu = (\nu_s)_{s \in [t,T]}\) is called a self-financing trading strategy if it satisfies

1. \(\nu_s \in \mathcal{C}, \mathbb{P}\text{-a.s. and for all } s, \mathcal{C} \text{ being the constraint set (closed and not necessarily convex set in } \mathbb{R}^d).\)

2. The wealth process \(X^\nu = X^{\nu,t,x}\) of an agent with strategy \(\nu\) and wealth \(x\) at time \(t\) is defined as follows

\[
\forall s \in [t,T], \quad X^\nu_s = x + \int_t^s \sum_{i=1}^{d} \frac{\nu^i_r}{S^i_r} dS^i_r, \tag{2.3}
\]

and it is in the space \(\mathcal{H}^2\) of semimartingales.

\(^2\) Both this decomposition already introduced in [7] and the assumption of almost sure invertibility of \(m_s\) for all \(s\), ensure that the no arbitrage property holds.
In this definition, each component $\nu^i$ of the trading strategy corresponds to the amount of money invested in the $i^{th}$ asset. Due to the presence of portfolio constraints, there does not necessarily exist a strategy $\nu$ (such that, for all $s$, $\nu_s \in C$) satisfying: $X_T^\nu = B$, for a given $\mathcal{F}_T$-contingent claim $B$. Hence, we are facing an incomplete market. The utility maximization problem aims at giving the expression of the value process defined at any time $t$ by (1.1) and at characterizing the set of optimal strategies, i.e. those achieving the esssup for the problem. In this study, we first consider the exponential utility maximization problem associated with the utility function: $U_\alpha(x) = -\exp(-\alpha x)$, with: $\alpha > 0$. Usually, the set of admissible trading strategies consists of all the strategies such that the wealth process is bounded from below. To solve the problem analogously to [12], we need to enlarge the set of admissible strategies to a new set denoted by $\mathcal{A}_t$.

**Definition 2.2** Let $C$ be the constraint set, which is such that: $0 \in C$. The set $\mathcal{A}_t$ of admissible strategies consists of all $d$-dimensional predictable processes: $\nu = (\nu_s)_{s \in [t,T]}$ satisfying: $\nu_s \in C$, $\mathbb{P}$-a.s. and for all $s$, $\mathbb{E}(\int_t^T |m_s \nu_s|^2 dC_s) < \infty$ and the uniform integrability of the family

$$\{\exp(-\alpha X^\nu_t) : \tau \mathcal{F} \text{-stopping time taking its values in } [t,T] \}.$$

This appears to be a restrictive condition on strategies and it implies that we have to justify the existence of one optimal strategy admissible in this sense.

**Preliminaries on quadratic BSDEs** We first provide the form of the one-dimensional BSDEs considered in the sequel

(Eq1) $Y_t = B + \int_t^T F(s,Y_s,Z_s)dC_s + \frac{\beta}{2} ((L)_T - (L)_t) - \int_t^T Z_s dM_s - \int_t^T dL_s.$

To refer to this BSDE, we use the notation BSDE($F, \beta, B$). Usually, a BSDE is characterized by two parameters: its terminal condition $B$ assumed here to be bounded, its generator $F = F(s,y,z)$, a $\mathcal{P} \times \mathcal{B}(\mathbb{R}) \times \mathcal{B}(\mathbb{R}^d)$-measurable function, continuous w.r.t. $(y,z)$ ($\mathcal{P}$ denotes the $\sigma$-field of all predictable sets of $[0,T] \times \Omega$ and $\mathcal{B}(\mathbb{R})$ the Borel field of $\mathbb{R}$). In our setting, we introduce another parameter $\beta$ which is assumed to be constant and a financial meaning for $\beta$ is given in next paragraph. We also impose precise growth conditions on the generator; in particular, we study existence under the assumption of quadratic growth w.r.t. $z$. One essential motivation of this study is that such quadratic BSDEs appear naturally when using the same dynamic method as in [12] to solve the problem (1.1). A solution of the BSDE($F, \beta, B$) is a triplet $(Y,Z,L)$ with $(L,M) = 0$ and such that: $\int_0^T |F(s,Y_s,Z_s)|dC_s < \infty$, $\mathbb{P}$-a.s., satisfying (Eq1) and defined on $S^\infty \times L^2(dM \otimes d\mathbb{P}) \times \mathcal{M}^2([0,T])$: $S^\infty$ consists of all bounded continuous processes, $L^2(dM \otimes d\mathbb{P})$ consists of all predictable processes $Z$ such that: $\mathbb{E}(\int_0^T |m_s Z_s|^2 dC_s) < \infty$, and $\mathcal{M}^2([0,T])$ consists of all real square integrable martingales of the filtration $\mathcal{F}$.

\[\text{Such BSDEs have been considered in [18], where the authors already deal with the utility maximization problem but, contrary to the present paper, they do not assume the presence of trading constraints.}\]
The stochastic exponential of a semimartingale \( K \) denoted by \( \mathcal{E}(K) \) is the unique process satisfying
\[
\mathcal{E}_t(K) = 1 + \int_0^t \mathcal{E}_s(K) dK_s.
\]
A process \( L \) is a BMO martingale if \( L \) is an \( \mathcal{F} \)-martingale and if there exists a constant \( c \) \((c > 0)\) such that, for any \( \mathcal{F} \)-stopping time \( \tau \),
\[
\mathbb{E}^{\mathcal{F}_\tau} ((L)_T - (L)_\tau) \leq c.
\]

**The dynamic method** In this part, we use the same dynamic method as in [12] to characterize the value process of the optimization problem in terms of the solution of a BSDE with parameters \((F^\alpha, \beta, B)\). The expressions of \( F^\alpha \) and \( \beta \) are obtained below in (2.5) by formal computations (these computations are justified in the last section of this paper).

To this end, we construct, for any strategy \( \nu \) and fixed \( t \), a process \( R^\nu = (R_{t,s}^\nu)_{s \geq t} \) such that, for all \( s \), \( R_{t,s}^\nu = U_\alpha(X_t^\nu - Y_s) \), with \( U_\alpha \) defined by: \( U_\alpha(\cdot) = -\exp(-\alpha \cdot) \), and such that the process \( Y \) solves the BSDE \((F^\alpha, \beta, B)\) of type (Eq1): the terminal condition is the contingent claim \( B \), and the parameters \( F^\alpha \) and \( \beta \) have to be determined. Besides, this family \((R^\nu)\) is such that
(i) \( R_{t,s}^\nu = U_\alpha(X_t^\nu - B) \), for any strategy \( \nu \),
(ii) \( R_{t,s}^\nu = U_\alpha(x - Y_t) \) \((x \) is assumed to be a constant\(^4\)).
(iii) \( R^\nu \) is a supermartingale for any strategy \( \nu, \nu \in \mathcal{A}_t \), and a martingale for a particular strategy \( \nu^*, \nu^* \in \mathcal{A}_t \).

We rely on the equation (2.3) defining \( X^\nu \) and on Itô’s formula to get
\[
X_t^\nu - Y_s = (x - Y_t) + \int_t^s (\nu_u - Z_u) dM_u - (L_s - L_t) + \int_t^s \beta (\langle L \rangle_s - \langle L \rangle_t) + \int_t^s (m_u \nu_u) (m_u \lambda_u) dC_u.
\]
Since, for all \( s \), \( R_{t,s}^\nu = -\exp(-\alpha(X_t^\nu - Y_s)) \) and using the notation: \( \mathcal{E}_{t,T}(K) = \frac{\mathcal{E}_T(K)}{\mathcal{E}_t(K)} \), for a given local martingale \( K \), we claim
\[
\exp\left(-\alpha(\int_t^T (\nu_s - Z_s) dM_s)\right) = \mathcal{E}_{t,T}(\alpha \nu - Z) \exp\left(\frac{\alpha^2}{2} \int_t^T \mathbb{K}^2 (\nu_s - Z_s) d\mathbb{K}_s\right), \quad \text{on the one hand},
\]
\[
\exp(\alpha (L_T - L_t)) = \mathcal{E}_{t,T}(\alpha L) \exp\left(\frac{\alpha^2}{2} (\langle L \rangle_T - \langle L \rangle_t)\right), \quad \text{on the other hand},
\]
which leads to the multiplicative decomposition
\[
R_{t,s}^\nu = -\exp\left(-\alpha(x - Y_t)\right) \mathcal{E}_{t,s}(\alpha(\nu - Z) \cdot M) \mathcal{E}_{t,s}(\alpha L) \exp(A_t^\nu - A_t^\nu).
\]

\(^4\) This dynamic method can be extended to any attainable wealth \( x \), i.e. any \( \mathcal{F}_t \)-measurable random variable such that: \( X_t^0 = x \), for at least one admissible strategy \( \nu \) defined on \([0, t]\).
Here, \( A^\nu \) is such that
\[
dA^\nu = \left( -\alpha F^\alpha (s, Z_s) - \alpha (m_s \nu_s)\' (m_s \lambda_s) + \frac{\alpha^2}{2} |m_s (\nu_s - Z_s)|^2 \right) dC_s
+ \left( \frac{\alpha^2 - \alpha \beta}{2} \right) d(L)_s.
\]

Since \( M \) and \( L \) are strongly orthogonal, we get
\[
E(-\alpha (\nu - Z) \cdot M) = E(-\alpha (\nu - Z) \cdot \alpha L) = E(-\alpha (\nu - Z) \cdot M + \alpha L).
\]

From (2.4), \( R^\nu \) is the product of a positive local martingale (as a continuous stochastic exponential of a local martingale) and a finite variation process. The process \( R^\nu \) being negative and relying on the multiplicative decomposition (2.4), the increasing property of \( A^\nu \) for all \( \nu \) yields the supermartingale property of \( R^\nu \) (the process \( R^\nu \) is a martingale for \( \nu \) satisfying: \( dA^\nu \equiv 0 \)). These two last conditions on the family \( (A^\nu) \) holding true for all \( \nu, \nu \in \mathcal{A}_t \), we get
\[
(\frac{\alpha^2}{2} - \alpha \beta) \cdot d(L)_s + \frac{\alpha^2}{2} \cdot d\langle L \rangle_s = 0 \quad \Rightarrow \quad (\beta = \alpha) \quad \text{and} \quad (m_s \nu_s)\' (m_s \lambda_s) + \frac{\alpha^2}{2} |m_s (\nu_s - Z_s)|^2 \geq 0.
\]

This leads to
\[
F^\alpha (s, z) = \inf_{\nu \in C} \left( \frac{\alpha}{2} |m_s (\nu - (z + \frac{\lambda_s}{\alpha}))|^2 \right) - (m_s z)\' (m_s \lambda_s) - \frac{1}{2\alpha} |m_s \lambda_s|^2. \quad \text{(2.5)}
\]

This method, explained for a fixed time \( t \), relies on the dynamic programming principle and could therefore be extended without any additional difficulty to any \( \mathcal{F} \)-stopping time \( \tau \).

2.2 Statement of the assumptions and main results

Assumptions

To study the existence for solutions of the BSDEs \((F, \beta, B)\) of type (Eq1), we assume in all the sequel the boundedness of the terminal condition \( B \). Moreover, we suppose that there exists a non negative predictable process \( \bar{\alpha} \) such that:
\[
\int_0^T \bar{\alpha}_s dC_s \leq a, \quad \text{for a strictly positive constant } a \quad \text{and three strictly positive constants} \quad b, \quad \gamma \quad \text{and} \quad C_1 \quad \text{such that one of the three following conditions holds}
\]
\[
(H_1) \quad |F(s, y, z)| \leq \bar{\alpha}_s + b\bar{\alpha}_s |y| + \gamma \frac{|m_s z|^2}{|\alpha|} \quad \text{with} \quad \gamma \geq |\beta| \quad \text{and} \quad \gamma \geq b,
\]
\[
(H'_1) \quad |F(s, y, z)| \leq \frac{\gamma}{2} |m_s z|^2,
\]
\[
(H''_1) \quad -C_1 (\bar{\alpha}_s + |m_s z|) \leq F(s, y, z) \leq \bar{\alpha}_s + \frac{\gamma}{2} |m_s z|^2.
\]

Remark 2.3 We give here some comments:
• Assumption \((H_1)\) is more general than the two other ones but we only require these two last assumptions to establish the existence result. We first reduce the assumption \((H_1)\) to \((H'_1)\) by a classical truncation procedure and we note that the additional
assumption in $\mathcal{H}_1''$ is that the lower bound has at most linear growth in $z$: this condition has already been used by [5] in the Brownian setting to justify the existence of a minimal solution. We rely on the same construction to prove our existence result.

- The quadratic BSDE introduced in Section 2.1 and of the form (Eq1) has for parameters: $F = F^\alpha$, $\beta = \alpha$ and $B$ ($B$ standing for the liability in the optimization problem (1.1)). In particular, the generator $F^\alpha$ given by (2.5) satisfies $\mathcal{H}_1$. In fact, we have

$$F^\alpha(s,z) \geq -(m_s z)'(m_s \lambda_s) - \frac{1}{2\alpha}|m_s \lambda_s|^2 \geq -|m_s z||m_s \lambda_s| - \frac{1}{2\alpha}|m_s \lambda_s|^2,$$

which leads to

$$F^\alpha(s,z) \geq -\left(\frac{\alpha}{2}|m_s z|^2 + \frac{1}{\alpha}|m_s \lambda_s|^2\right).$$

Defining $\bar{\alpha}$, for all $s$, by $\bar{\alpha}_s = \frac{1}{\alpha}|m_s \lambda_s|^2$, we claim that: $\int_0^T \bar{\alpha}_s dC_s \leq a$, $\mathbb{P}$-a.s., with the parameter $a$ depending on $\alpha$ and $\alpha_\lambda$ (this last constant is defined in equation (2.2)). Since $0$ is in $\mathcal{C}$, we get

$$F^\alpha(s,z) \leq \frac{\alpha}{2}|m_s z|^2.$$

- Even if we suppose that $F$ is Lipschitz w.r.t. $y$ and $z$, we cannot obtain directly existence and uniqueness result for a BSDE of type (Eq1), because of the presence of the additional term involving the quadratic variation process $\langle L \rangle$. This explains the introduction of another type of BSDEs denoted by (Eq2)

$$\begin{cases}
    dU_s = -g(s,U_s,V_s)dC_s + V_s dM_s + dN_s, \\
    U_T = e^{\beta B}.
\end{cases}$$

In the previous equation, $V \cdot M + N$ stands for the martingale part and $N$ is a $\mathbb{R}$-valued martingale orthogonal to $M$ (the presence of such a martingale $N$ is required, since $M$ does not enjoy the predictable representation property). In the sequel, we denote it by BSDE($g,e^{\beta B}$). This second type of BSDE is linked with the BSDE($F,\beta,B$) of type (Eq1) by using an exponential change of variable. Indeed, setting: $U = e^{\beta Y}$, this leads to

$$g(s,u,v) = \left(\beta u F(s, \frac{\ln(u)}{\beta}, \frac{v}{\beta u}) - \frac{1}{2\alpha}|m_s v|^2\right)1_{u>0}.$$
a constant $c_0$ such that
\begin{equation}
(H_2) \quad \begin{cases}
\forall z \in \mathbb{R}^d, \forall y^1, y^2 \in \mathbb{R}, \\
(y^1 - y^2)(F(s, y^1, z) - F(s, y^2, z)) \leq \mu|y^1 - y^2|^2, \\
\exists \theta \text{ s.t. } \int_0^T |m_s \theta_s|^2 dC_s \leq c_0, \forall y \in \mathbb{R}, \forall z^1, z^2 \in \mathbb{R}^d, \\
|F(s, y, z^1) - F(s, y, z^2)| \leq C_2(m_s \theta_s + |m_s z^1| + |m_s z^2|)|m_s(z^1 - z^2)|.
\end{cases}
\end{equation}

Remark 2.4 The first inequality in assumption $(H_2)$ corresponds to the monotonicity assumption (this assumption is given in [20]). The second assumption on the increments in the variable $z$ is a kind of local Lipschitz condition w.r.t $z$, which is similar to the one in [12]. We check that $(H_2)$ is satisfied by the generator $F^\alpha$ with: $C_2 = \frac{3}{2}$, $\theta \equiv \frac{4 |m_s \lambda|}{\alpha}$ and $\mu = 0$, since $F^\alpha$ is independent of $y$: indeed, for any $z^1, z^2$ in $\mathbb{R}^d$, we argue that the increments of $F^\alpha$ w.r.t. $z$ satisfy
\[
|F^\alpha(s, z^1) - F^\alpha(s, z^2)| \\
\leq \frac{\alpha}{2} \left( \text{dist}^2(m_s(z^1 + \frac{\lambda}{\alpha}), m_s C) - \text{dist}^2(m_s(z^2 + \frac{\lambda}{\alpha}), m_s C) \right) \\
+ | - (m_s z^1)'(m_s \lambda) + (m_s z^2)'(m_s \lambda)| \\
\leq \frac{\alpha}{2} |m_s(z^1 - z^2)|(|m_s z^1| + |m_s z^2| + 2 |m_s \lambda| \frac{1}{\alpha}) + |m_s(z^1 - z^2)||m_s \lambda|.
\]

Main results To obtain the existence and uniqueness results for solutions of BSDEs of type (Eq1), we establish the same results for BSDEs of type (Eq2). We now state the results which are justified in Section 3.

Theorem 2.5 Existence: Considering the BSDE $F, \beta, B$ and assuming both that the generator $F$ satisfies $(H_1)$ and that the terminal condition $B$ is bounded, there exists a solution $(Y, Z, L)$ in $S^\infty \times L^2(dM \otimes d\mathbb{P}) \times \mathcal{M}^2([0, T])$ of the BSDE.

Theorem 2.6 Uniqueness: For all BSDEs $F, \beta, B$ of type (Eq1) such that the generator $F$ satisfies both $(H_1)$ and $(H_2)$ and such that the terminal condition is bounded, there exists a unique solution $(Y, Z, L)$ in $S^\infty \times L^2(dM \otimes d\mathbb{P}) \times \mathcal{M}^2([0, T])$.

Theorem 2.7 Comparison: Considering two BSDEs of the form (Eq1) given by $(F^1, \beta, \xi^1)$ and $(F^2, \beta, \xi^2)$ where $F^1$ and $F^2$ satisfy $(H_1)$ and $(H_2)$ and assuming furthermore that $(Y^1, Z^1, L^1)$ and $(Y^2, Z^2, L^2)$ are respective solutions of each BSDE such that
\[
(\xi^1 \leq \xi^2 \quad \text{and} \quad F^1(s, Y^1_s, Z^1_s) \leq F^2(s, Y^2_s, Z^2_s)), \quad \mathbb{P}\text{-a.s. and for all } s,
\]
then, we have: $Y^1_s \leq Y^2_s$, $\mathbb{P}$-a.s. and for all $s$.

We only prove results for the two first theorems, since, without additional difficulty, we check that the comparison result given in Theorem 2.7 holds: to prove this, we proceed with a linearization of the generator similar as the one in Section 3.2: this consists in applying the Itô-Tanaka formula to the adapted and bounded process: $\tilde{Y}^{1, 2} = \exp(2\mu C)|Y^{1, 2} - \alpha|^2$ and in rewriting the same proof.
3 Results about quadratic BSDEs

3.1 A priori estimates

In this part, we obtain precise a priori estimates for solutions of the BSDEs of type (Eq1). Referring to previous studies on quadratic BSDEs (such as in [5] or [16]), these estimates are the starting point of the proof of the main existence result.

To prove these estimates, we assume the existence of a solution $(Y, Z, L)$ of the BSDE$(F, \beta, B)$ such that $F$ satisfies $(H_1)$ and we proceed analogously to [5]. However, since the authors work with a brownian filtration, we have to generalize their method to our setting.

**Lemma 3.1** Considering a BSDE of type (Eq1) given by $(F, \beta, B)$ and assuming both boundedness of $B$ and condition $(H_1)$ for $F$, we can give explicitly in terms of the parameters $\gamma$, $a$, $b$ (given in $(H_1)$) and $|B|_{\infty}$ the three constants $c$, $C$, $C'$ such that, for any solution $(Y, Z, L)$ in $S^\infty \times L^2(d(M) \otimes d\P) \times \M^2([0, T])$,

1. $\P$-a.s. and for all $t$, $c \leq Y_t \leq C$,
2. for any $\mathcal{F}$-stopping time $\tau$, $\E^\tau \left( \int_\tau^T |m_s Z_s|^2 dC_s + \langle L \rangle_T - \langle L \rangle_\tau \right) \leq C'$.

**Proof** By definition, the solution $(Y, Z, L)$ belongs to $S^\infty \times L^2(d(M) \otimes d\P) \times \M^2([0, T])$ and our first objective is to explicit both a lower and an upper bound for $Y$. Setting first: $\bar{a} = \frac{e^{\bar{a}_s} - 1}{b}$, we aim at proving

$$\forall t, \quad \exp(\gamma|Y_t|) \leq \exp \left( \gamma (\bar{a} + |B|_{\infty} e^{\bar{a}_s}) \right).$$

(3.1)

For this and for fixed $t$, we introduce $H = (U(s, |Y_s|))$ such that

$$\forall s \geq t, \quad H_s = U(s, |Y_s|) = \exp \left( \gamma \left( \frac{\exp \left( \int_t^s b\bar{a}_u dC_u \right) - 1}{b} \right) + \gamma |Y_s| \exp \left( \int_t^s b\bar{a}_u dC_u \right) \right),$$

and satisfying: $U(t, |Y_t|) = e^{\gamma|Y_t|}$. Applying Itô’s formula to the process $H$, we justify that it is a local submartingale: to this end, we prove that the predictable with bounded variation process $A$ in the canonical decomposition of the semimartingale $H$ is increasing. For sake of clarity, we first apply the Itô-Tanaka formula to $|Y|$

$$d|Y_s| = -\text{sign}(Y_s) F(s, Y_s, Z_s) dC_s - \text{sign}(Y_s) \frac{\beta}{2} d\langle L \rangle_s + d\ell_s$$

$$+ \text{sign}(Y_s) (Z_s dM_s + dL_s),$$

$\ell$ being the local time of $Y$. Now, Itô’s formula leads to the following expression of $A$

$$\exp \left( - \int_t^s b\bar{a}_u dC_u \right) dA_s =$$

$$H_s \left( \gamma \bar{a}_s - \gamma \text{sign}(Y_s) F(s, Y_s, Z_s) + \gamma b\bar{a}_s |Y_s| + \frac{\beta}{2} \int_t^s b\bar{a}_u dC_u |m_s Z_s|^2 \right) dC_s$$

$$+ H_s \gamma d\ell_s + H_s \gamma \left( \frac{\beta}{2} \exp \left( \int_t^s b\bar{a}_u dC_u \right) - \text{sign}(Y_s) \frac{\beta}{2} d\langle L \rangle_s \right).$$

Using assumption $(H_1)$ and the inequalities: $|\beta| \leq \alpha$ and $\bar{a} \geq 0$, we get that the process $A$ is increasing. Hence, $H$ is a local submartingale and we conclude relying on a
standard localization procedure: i.e., there exists a sequence \((\tau_k)\) of increasing stopping times, converging to \(T\) and taking values in \([t,T]\) and such that \((U(s,\tau_k),|Y_{s,\tau_k}|)\) is a submartingale. This entails

\[ e^{\gamma Y_t} = U(t,|Y_t|) \leq E(U(T \wedge \tau_k,|Y_{T,\tau_k}|)|\mathcal{F}_t). \]

Applying the bounded convergence theorem to \((E(U(T \wedge \tau_k,|Y_{T,\tau_k}|)|\mathcal{F}_t))_k\) and letting \(k\) tend to infinity, we obtain

\[ e^{\gamma |Y_t|} \leq E(U(T,|Y_T|)|\mathcal{F}_t), \]

which gives (3.1). Hence, assertion (i) of lemma 3.1 is satisfied with

\[ C = (\tilde{a} + |B|_\infty e^{ba}) \text{ and } c = -(\tilde{a} + |B|_\infty e^{ba}). \]

To prove assertion (ii), we apply Itô’s formula to the bounded process: \(\tilde{\psi}(Y) = \psi_\gamma(Y + |c|)\), with \(\psi_\gamma\) such that

\[ \psi_\gamma(x) = \frac{e^{\gamma x} - 1 - \gamma x}{\gamma^2}. \]

Such a function satisfies

\[ \psi_\gamma'(x) \geq 0, \text{ if } x \geq 0, \quad \text{and} \quad -\gamma \psi_\gamma' + \psi_\gamma'' = 1, \quad (3.2) \]

and since \(c\) is the lower bound of \(Y\), we have: \(Y + |c| \geq 0\, \mathbb{P}\text{-a.s.}\) We now consider an arbitrary stopping time \(\tau\) of \((\mathcal{F}_t)_{t \in [0,T]}\). Taking the conditional expectation with respect to \(\mathcal{F}_\tau\) in Itô’s formula between \(\tau\) and \(T\), we get

\[
\begin{align*}
\tilde{\psi}(Y_\tau) - & E^{\mathcal{F}_\tau}(\tilde{\psi}(Y_T)) \\
= & -E^{\mathcal{F}_\tau} \left( \int_{\tau}^{T} \tilde{\psi}'(Y_s)(-F(s,Y_s,Z_s)dC_s - \frac{\beta}{2}d(L)_s) \right) \\
& - E^{\mathcal{F}_\tau} \left( \int_{\tau}^{T} \tilde{\psi}'(Y_s)(Z_s dM_s + d(L)_s) \right) - E^{\mathcal{F}_\tau} \left( \int_{\tau}^{T} \tilde{\psi}''(Y_s) \left( |m_s Z_s|^2 dC_s + d(L)_s \right) \right).
\end{align*}
\]

Since \(Z \cdot M\) and \(L\) are square integrable martingales and \(\tilde{\psi}'(Y)\) is a bounded process, the conditional expectation of the terms of the second line in the right-hand side vanishes. Using both the upper bound on \(F\) in (H.1) and simple computations, we obtain

\[
\begin{align*}
\tilde{\psi}(Y_\tau) - & E^{\mathcal{F}_\tau}(\tilde{\psi}(Y_T)) \\
\leq & E^{\mathcal{F}_\tau} \int_{\tau}^{T} \tilde{\psi}'(Y_s)\left(\alpha_s Z_s dC_s \right) \\
& + E^{\mathcal{F}_\tau} \int_{\tau}^{T} \left( \frac{\beta}{2} \tilde{\psi}' - \frac{1}{2} \tilde{\psi}'' \right)(Y_s) d(L)_s \\
& + E^{\mathcal{F}_\tau} \int_{\tau}^{T} \left( \frac{\gamma}{2} \tilde{\psi}' - \frac{1}{2} \tilde{\psi}'' \right)(Y_s) |m_s Z_s|^2 dC_s.
\end{align*}
\]

Using the properties of \(\psi_\gamma\) given by (3.2) and the fact that: \(\gamma \geq |\beta|\), we get

\[ \left( \frac{1}{2} \psi'' - \frac{\beta}{2} \psi' \right)(Y_s) \geq \left( \frac{1}{2} \psi'' - \gamma \psi' \right)(Y_s) = \frac{1}{2} \mathbb{P}\text{-a.s.} \quad \text{and for all } s. \]

Putting in the left-hand side of Itô’s formula applied to \(\tilde{\psi}(Y)\) the two last terms, it follows from the two last inequalities
\begin{align*}
&\frac{1}{2} \mathbb{E}^F \left( \int_\tau^T |m_s Z_s|^2 dC_s + \langle (L)_T - (L)_\tau \rangle \right) \\
&\leq \mathbb{E}^F \left( \int_\tau^T \left( \frac{1}{2} \psi'' - \frac{\gamma}{2} \psi' \right) |Y_s|^2 \, dC_s + \int_\tau^T \left( \frac{1}{2} \psi'' - \frac{\beta}{2} \psi' \right) |Y_s| \, d\langle L \rangle_s \right) \\
&\leq 2|\psi(Y)|_{S^\infty} + |\psi'(Y)|_{S^\infty} \int_0^\tau (\bar{\alpha}_s (1 + b |Y|_{S^\infty}) \, dC_s.
\end{align*}

and using the integrability assumption on \( \bar{\alpha} \) given in section 2.2, we get the existence of a constant \( C \) such as in assertion (ii), Lemma 3.1: this constant is independent of the stopping time \( \tau \) and depends only on the parameters \( a, b, \gamma \) and \( |B|_{\infty} \).

\[ \blacksquare \]

3.2 The uniqueness result

**Proof** The key idea of this proof is to proceed by linearization and to justify as in [12] the use of Girsanov’s theorem. Let \((Y^1, Z^1, L^1)\) and \((Y^2, Z^2, L^2)\) be two solutions of the BSDE\((F, \beta, B)\) with \( F \) satisfying both \((H_1)\) and \((H_2)\) and \( B \) bounded. We define \( Y'^{1,2} \) by: \( Y'^{1,2} = Y^1 - Y^2 \) (\( Z'^{1,2} \) and \( L'^{1,2} \) are defined similarly) and we consider the nonnegative and bounded semimartingale \((Y'^{1,2})\) defined by: \( Y'^{1,2}_t = e^{2\mu t} |Y^{1,2}_t|^2 \). We then use Itô’s formula

\[ d\tilde{Y}_s^{1,2} = 2\mu \tilde{Y}_s^{1,2} \, dC_s + e^{2\mu t} 2Y_s^{1,2} \, dY_s^{1,2} + \frac{1}{2} e^{2\mu t} 2d(Y'^{1,2})_s. \]

Since \( Y^1 \) and \( Y^2 \) are solutions of the BSDE\((F, \beta, B)\), we have

\[ dY_s^{1,2} = - (F(s, Y^1_s, Z^1_s) - F(s, Y^2_s, Z^2_s)) \, dC_s - \frac{\beta}{2} d\left( \langle L^1 \rangle_s - \langle L^2 \rangle_s \right) + dK_s, \]

with: \( K = Z^{1,2} \cdot M + L^{1,2}, \) which stands for the martingale part. Hence, considering Itô’s formula between \( t \) and an arbitrary \( \mathcal{F} \)-stopping time \( \tau (\tau \geq t) \), we get

\[ \begin{align*}
\tilde{Y}_t^{1,2} - \tilde{Y}_\tau^{1,2} &= - \left( \int_t^\tau 2\mu \tilde{Y}_s^{1,2} \, dC_s \\
&\quad + \int_t^\tau e^{2\mu s} 2Y_s^{1,2} (F(s, Y_s^1, Z_s^1) - F(s, Y_s^2, Z_s^2)) \, dC_s \\
&\quad + \int_t^\tau e^{2\mu s} 2Y_s^{1,2} \frac{\beta}{2} d\left( \langle L^1 \rangle_s - \langle L^2 \rangle_s \right) \\
&\quad - \int_\tau^\tau e^{2\mu s} 2Y_s^{1,2} (Z_s^{1,2} \, dM_s + dL_s^{1,2}) \\
&\quad - \int_\tau^\tau e^{2\mu s} \frac{1}{2} 2d(Y'^{1,2})_s \right) \\
&\leq 0.
\end{align*} \]

The generator \( F \) satisfying \((H_2)\), it follows

\[ 2Y_s^{1,2} (F(s, Y_s^1, Z_s^1) - F(s, Y_s^2, Z_s^2)) \leq 2\mu |Y_s^{1,2}|^2 + 2Y_s^{1,2} (m_s \kappa_s + (m_s Z_s^{1,2})), \]

where \( m_s \kappa_s \) is a constant depending on the parameters \( a, b, \gamma \) and \( |B|_{\infty} \).
where the $\mathbb{R}^d$-valued process $\kappa$ is defined as follows

$$\begin{align*}
\kappa_s &= \begin{cases} 
(F(s,Y^1_s,Z^1_s) - F(s,Y^2_s,Z^2_s))(Z^{1,2}_s), & \text{if } |m_s Z^{1,2}_s| \neq 0, \\
0, & \text{otherwise.}
\end{cases}
\end{align*}$$

We introduce a new process $A$

$$A_s = 2Y^{1,2}_s \left( F^1(s,Y^1_s,Z^1_s) - F^2(s,Y^2_s,Z^2_s) - \left( 2\mu Y^{1,2}_s \right)^2 + 2Y^{1,2}_s (m_s \kappa) (m_s Z^{1,2}_s) \right).$$

This process being almost surely non positive, we obtain

$$\tilde{Y}^{1,2}_t - \tilde{Y}^{1,2}_r = \int_r^t A_s dC_s - \int_r^t e^{2\mu C} \frac{1}{2} 2d(Y^{1,2})_s$$

$$+ \int_r^t 2Y^{1,2}_s e^{2\mu C} (m_s \kappa) (m_s Z^{1,2}_s) dC_s$$

$$+ \int_r^t 2Y^{1,2}_s e^{2\mu C} \beta \frac{1}{2} d(L^{1,2}, L^1 + L^2)_s$$

$$- \int_r^t 2e^{2\mu C} Y^{1,2}_s Z^{1,2}_s dM_s - \int_r^t 2e^{2\mu C} Y^{1,2}_s d\tilde{H}^{1,2}.$$ 

We then consider the stochastic integrals

$$\tilde{N} = \left( 2e^{2\mu C} Y^{1,2} \right) : M \quad \text{and} \quad \tilde{N} = \kappa : M, \quad \text{on the one hand},$$

$$\tilde{L} = \left( 2Y^{1,2} e^{2\mu C} \right) : L^{1,2} \quad \text{and} \quad \tilde{L} = \frac{\beta}{2} (L^1 + L^2), \quad \text{on the other hand},$$

From (H2), we deduce

$$\exists C > 0, \quad |m_s \kappa| \leq C \left( |m_s \theta| + |m_s Z^1_s| + |m_s Z^2_s| \right).$$

Using both the assertion (ii) in Lemma 3.1 and the assumption on $\theta$ given by (H2), we get: $\kappa : M + \frac{\beta}{2} (L^1 + L^2)$ is a BMO martingale and referring then to [14], $\mathcal{E}(\kappa : M + \frac{\beta}{2} (L^1 + L^2))$ is a true martingale. Defining $\mathbb{Q}$ such that: $\frac{d\mathbb{Q}}{d\mathbb{P}} = \mathcal{E}(\kappa : M + \frac{\beta}{2} (L^1 + L^2))$, Girsanov’s theorem entails that: $K = \tilde{N} + \tilde{L} - (\tilde{N} + L, \kappa : M + \frac{\beta}{2} (L^1 + L^2))$, is a local martingale under $\mathbb{Q}$; this implies the existence of a sequence $(\tau^k)$ converging to $T$ such that each $\tau^k$ may be assumed greater than $t$ and such that $K_{\wedge \tau^k}$ is a martingale. Hence, between $t = t \wedge \tau^k$ and $\tau^k$, the adapted process $\tilde{Y}$ satisfies

$$\tilde{Y}^{1,2}_t = \tilde{Y}^{1,2}_{\tau^k} + \int_{\tau^k}^t A_s dC_s + (K_{\tau^k} - K_t).$$

Taking the conditional expectation w.r.t $\mathcal{F}_t$ under $\mathbb{Q}$ in that last equality and using the martingale property of $K_{\wedge \tau^k}$, we get

$$\tilde{Y}^{1,2}_t \leq \mathbb{E}^{\mathbb{Q}} \left( \tilde{Y}^{1,2}_{\tau^k} | \mathcal{F}_t \right). \quad (3.3)$$

As in the proof of Lemma 3.1 on page 9, the use of the bounded convergence theorem in the right-hand side of (3.3) entails

$$\tilde{Y}^{1,2}_t \leq \lim_{k \to \infty} \mathbb{E}^{\mathbb{Q}} \left( \tilde{Y}^{1,2}_{\tau^k} | \mathcal{F}_t \right) = 0.$$
Hence, it implies
\[ \forall t, \; \tilde{Y}_{t}^{1,2} \leq 0 \quad \text{Q-a.s.} \quad \text{(and P-a.s., because of the equivalence of P and Q)}, \]
which ends the proof (\( \tilde{Y}_{t}^{1,2} \) being a non-negative adapted process).

\[ \square \]

3.3 Existence

3.3.1 Main steps of the proof of Theorem 2.5

In this part and to prove the existence result (Theorem 2.5), we proceed with three main steps.

In a first step, we prove that, to solve a BSDE of type (Eq1) under assumption \((H_1)\), it suffices to solve the same BSDE under a simpler assumption \((H'_1)\).

In a second step, we introduce an intermediate BSDE of the form (Eq2) and we establish a one-to-one correspondence between the existence of a solution of a BSDE of the form (Eq1) and one of the form (Eq2).

The third and last step consists in constructing a solution of the BSDE of the form (Eq2) when its generator \(g\) satisfies \((H'_1)\) and in establishing a “monotone stability” result analogous to the one given in [16].

**Step 1: Truncation in \(y\)** We rely on the a priori estimates given in Lemma 3.1 to strengthen the assumption on the generator and obtain precise estimates for an intermediate BSDE. More precisely, we show that it is sufficient to study existence under the simpler assumption \((H'_1)\) (instead of \((H_1)\))

\[ (H'_1) \quad \exists \bar{a} \geq 0, \; \int_{0}^{T} \bar{a}_{s} dC_{s} \leq a (a > 0), \; \text{such that } |F(s,y,z)| \leq \bar{a}_{s} + \frac{\gamma}{2} |m_s z|^2. \]

Assuming that we have a solution of the BSDE(\(F,\beta,B\)) of type (Eq1) under assumption \((H'_1)\) on \(F\), we deduce the existence of a solution of this BSDE under \((H_1)\). For this, we define \(K\) by:

\[ K = |c| + |C|, \quad \text{with } c \text{ and } C \text{ the two constants given in assertion (i) in Lemma 3.1 and we introduce} \]

\[ \left\{ \begin{array}{l}
    dY^K_s = -F^K(s,Y^K_s,Z^K_s) dC_s - \frac{\beta}{2} d[L^K]_s + Z^K_s dM_s + dL^K_s, \\
    Y^K_T = B,
  \end{array} \right. \]

where the generator \(F^K\) and the truncation function \(\rho_K\) are respectively defined by:

\[ F^K(s,y,z) = F(s,\rho_K(y),z) \text{ and} \]

\[ \rho_K(y) = \begin{cases} 
    -K & \text{if } y < -K, \\
    y & \text{if } |y| \leq K, \\
    K & \text{if } y > K.
  \end{cases} \]

Hence, we have

\[ \forall y \in \mathbb{R}, \; z \in \mathbb{R}^d, \; |F^K(s,y,z)| \leq \bar{a}_{s}(1 + b(|\rho_K(y)|) + \frac{\gamma}{2} |m_s z|^2. \]
Since: $|ρ_K(γ)| \leq |γ|$, $F^K$ satisfies again $(H_1)$ with the same parameters as $F$. Using Lemma 3.1, $K$ is an upper bound of $Y^K$ in $S^\infty$, for any solution $(Y^K, Z^K, L^K)$ of BSDE($F^K$, $β$, $B$). Besides, if we replace $α$ by: $\tilde{α} = (1 + bK)$, $F^K$ satisfies $(H'_1)$. Due to the initial assumption, there exists a solution denoted by $(Y^K, Z^K, L^K)$ of BSDE($F^K$, $β$, $B$). Since: $|Y^K| \leq K$, $F^K$ and $F$ coincide along the trajectories of this solution and hence, $(Y^K, Z^K, L^K)$ is a solution of BSDE($F$, $β$, $B$) with $F$ satisfying $(H_1)$.

**Step 2: an intermediate BSDE** To establish the one-to-one correspondence, we first assume the existence of a solution $(Y, Z, L)$ of BSDE($F, β, B$) with $F$ satisfying $(H'_1)$ and we set: $U = e^{βY}$. Using Itô's formula, we check that $U$ solves a BSDE of the type (Eq2) and that the expression of the generator $g$ is given by

$$g(s, u, v) = \left(βuF(s, \frac{ln(u)}{β}, \frac{v}{βu}) - \frac{1}{2β}|m_s v|^2\right) 1_{u > 0}. \quad (3.4)$$

A solution of the BSDE($g, e^{βB}$) of type (Eq2) is given by the triplet $(U, V, N)$ such that: $U_s = e^{βY_s}$, $V_s = βU_s Z_s$ and $N = βU \cdot L$. Our aim is to prove that the converse is true: i.e. if we can solve the BSDE($g, e^{βB}$) of type (Eq2) under the assumption $(H'_1)$ on $g$, then we obtain a solution of the BSDE($F, β, B$) of type (Eq1) by setting

$$Y = \frac{ln(U)}{β}, \quad Z = \frac{V}{βU}, \quad \text{and} \quad L = \frac{1}{βU} \cdot N. \quad (3.5)$$

To achieve this, we give precise estimates of $U$ in $S^\infty$ for any solution $(U, V, N)$ of the BSDE($g, e^{βB}$) of type (Eq2). Due to the singularity of the expression (3.4) of $g$ with respect to $u$, we first rely on a truncation argument and for this, we introduce a new generator $G$

$$G(s, u, v) = βρ_{c^2}(u)F\left(s, \frac{ln(u \vee e^1)}{β}, \frac{v}{β(u \vee e^1)}\right) - \frac{1}{2β(u \vee e^1)}|m_s v|^2. $$

The two positive constants $c^1$ and $c^2$ are defined later and the function $ρ_{c^2}$ is the same as in the first step. Since $F$ satisfies $(H'_1)$ and since: $ρ_{c^2}(u) \leq c^2$, we obtain that $G$ also satisfies $(H'_1)$. Hence, for any positive constants $c^1$ and $c^2$, there exists a solution of the BSDE($G, e^{βB}$) of type (Eq2). We denote it $(U^{c_1}, c^2, V^{c_1}, c^2, N^{c_1}, c^2)$. Thanks to the estimates

$$|G(s, u, v)| \leq βρ_{c^2}(u)(α_s + \frac{γ|m_s v|^2}{2|c|^2}) + \frac{|m_s v|^2}{2c^2} \leq βα_s |u| + \frac{γ}{2} |m_s v|^2,$$

we obtain that $G$ satisfies $(H_1)$ with the parameters $a, b$ and $γ$ defined by

$$a = \int_0^T |βα_s dC_s, \quad b = 1, \quad γ = \tilde{γ}.$$
Defining \( c^2 \) by: \( c^2 = \epsilon - 1 + |\beta|_{\infty}^2 \), this provides an upper bound independent of \( \gamma \). To prove the existence of a strictly positive lower bound, we consider a solution \( (U, V, N) \) of the BSDE\((g, e\beta B)\) and we introduce the adapted process \( \Psi(U) \) for all \( t \) by:

\[
\Psi(U_t) = e^{-\int_0^t \hat{\beta}_s dC_s} U_t
\]

(we check that: \( \hat{\beta} = |\beta| \text{sign}(U_s) \), satisfies: \( \int_0^T |\hat{\beta}_s| dC_s \leq a, \quad \mathbb{P}\)-a.s.). Applying then Itô’s formula to \( \Psi(U) \) between \( t \) and \( T \), we get

\[
\Psi(U_t) - \Psi(U_T) = \int_t^T (e^{-\int_s^t \hat{\beta}_u dC_u} (G(s, U_s, V_s) + \hat{\beta}_s U_s)) dC_s - \int_t^T e^{-\int_s^t \hat{\beta}_u dC_u} (V_s dM_s + dN_s).
\]

(3.6)

with the process \( A \) such that: \( A_s = G(s, U_s, V_s) + (\hat{\beta}_s U_s + \frac{1}{2} |m_s V_s|^2) \), which is almost surely positive. Since \( -\frac{1}{2} (V \cdot M) \) is a BMO martingale (thanks to (ii) in Lemma 3.1), we introduce a probability measure by defining: \( \tilde{\mathbb{Q}} = \mathbb{E}(-\frac{1}{2} V \cdot M) \). The Girsanov’s transform \( \tilde{M} \) of \( M: \tilde{M} = M + \frac{1}{2} (V \cdot M, M) \), is a local martingale under \( \tilde{\mathbb{Q}} \) and it follows that \( \Psi(U) \) is the sum of a local martingale (under \( \tilde{\mathbb{Q}} \)) and an increasing process: relying on the standard localization procedure and on the boundeness assumption on \( \Psi(U) \), we conclude

\[
\Psi(U_t) \geq \mathbb{E}^{\tilde{\mathbb{Q}}} (\Psi(U_T) | \mathcal{F}_t).
\]

Hence, \( U_t \geq \mathbb{E}^{\mathbb{Q}} (\inf_U U_T) e^{-\int_0^T \hat{\beta}_s dC_s} |\mathcal{F}_t| \), and if \( c^1 \) is defined by: \( c^1 = e^{-|\beta|_{\infty} t} \), it is a lower bound of \( U \). For these choices of \( c^1, c^2 \), the generator \( G \) satisfies \((H_1)\) and, for any solution \( (U, V, N) \),

\[
c^1 \leq U_s \leq c^2, \quad \mathbb{P}\text{-a.s. and for all } s.
\]

Since: \( G(s, U_s, V_s) = g(s, U_s, V_s) \mathbb{P}\)-a.s. and for all \( s, (U, V, N) \) is a solution of the BSDE\((g, e\beta B)\). The process \( U \) being strictly positive and bounded, we can define \( (Y, Z, L) \) by (3.5) and applying Itô’s formula to \( \log(U) \), we check that \( (Y, Z, L) \) is a solution of the BSDE\((F, \beta, B)\).

**Step 3: Approximation** To prove the existence of a solution of the BSDE\((F, \beta, B)\) of type (Eq1) under \((H_1)\), the above two steps show that it is sufficient to prove the existence of a solution of the BSDE\((g, e\beta B)\) of type (Eq2). Assuming here that \( F \) satisfies \((H_1)\), Step 2 entails that we only need to prove existence for the second type of BSDE under assumption \((H_1)\) on \( g \). Analogously to [16], we construct an approximating sequence \( (U^n, V^n, N^n) \) satisfying

- these triplets are solutions of the BSDEs\((g^n, e\beta B)\),
- the sequence \( (g^n) \) is increasing and converges, \( \mathbb{P}\)-a.s. and for all \( s, to g (g : (y, z) \rightarrow g(s, y, z)) \).

From now and for the remaining of Section 3.3.1, we suppose

**Assumption 1:** The generator \( g \) satisfies \((H_1')\).

(3.6)
We then proceed by defining \( g^n \) by inf-convolution
\[
g^n(s,u,v) = \inf_{\tilde{u}, \tilde{v}} \left( g(s, \tilde{u}, \tilde{v}) + n|s- \tilde{u}| + n|u- \tilde{v}| \right).
\]
Such a \( g^n \) is well defined and globally Lipschitz continuous, which means
\[
\forall u^1, u^2, v^1, v^2, \quad |g^n(s, u^1, v^1) - g^n(s, u^2, v^2)| \leq n(|m_s (v^1 - v^2)| + |u^1 - u^2|).
\]
Since \( g^n \) is increasing and converges, \( \mathbb{P} \)-a.s. and for all \( s \), to \( g : (u,v) \to g_s(u,v) \) which is continuous w.r.t. \( (u,v) \), Dini’s theorem implies that the convergence is uniform over compact sets. Besides, using that: \( g^n \leq g \), we obtain
\[
\sup_n |g^n(s,0,0)| \leq \bar{\alpha}_s.
\]

The existence of a unique solution \( (U^n, V^n, N^n) \) of the BSDEs given by \( (g^n, \epsilon^n B) \) in \( S^2 \times L^2(d(M) \otimes d\mathbb{P}) \times M^2([0,T]) \) follows from (3.7) and (3.8) (a detailed proof of this existence result can be found in [8] where it is obtained in a general continuous setting). Furthermore, applying Theorem 2.7 for these BSDEs of type (Eq2) and using that \( (g^n)_n \) is increasing, we get: \( U^n \leq U^{n+1} \). The following result entails that, for all \( n, U^n \) is in \( S^\infty \).

**Proposition 3.2** Let \( (U^n, V^n, N^n) \) be a solution in \( S^2 \times L^2(d(M) \otimes d\mathbb{P}) \times M^2([0,T]) \) of a BSDE of the type (Eq2) given by the parameters \((g^n, B)\), with a generator \( g^n \) \( L_n \)-Lipschitz and a terminal condition \( B \) bounded, we have
\[
\exists K(L_n,T) > 0, \forall t, |U^n|^2 \leq K(L_n,T) \mathbb{E} \left( |\tilde{B}|_{\infty}^2 + (\int_t^T |g^n(s,0,0)|dC_s)^2 |\mathcal{F}_t \right).
\]

The proof, relegated to the appendix, is adapted from the results given in Proposition 2.1 in [4]. Relying on (3.8) and on the assumption on \( \bar{\alpha} \), Proposition 3.2 implies that \( U^n \) is in \( S^\infty \). Furthermore, since each generator \( g^n \) satisfies the assumption \( (H_1^n) \) (and hence \( (H_1) \) with the same parameters), assertion (i) in Lemma 3.1 ensures that \( (U^n) \) is uniformly bounded in \( S^\infty \).

**Step 4: Convergence of the approximation** To prove the convergence of the solutions of the BSDEs\((g^n, \epsilon^n B)\) under Assumption 1 (see (3.6)), we introduce the triplet \((\tilde{U}, \tilde{V}, \tilde{N})\) as being the limit (in a specific sense) of \((U^n, V^n, N^n)\). \((U^n)\) being increasing, we set:
\[
\tilde{U}_s = \lim_n \frac{U^n_s}{U^n_s}, \mathbb{P} \text{-a.s. for all } s.\text{ Any generator } g^n \text{ satisfying } (H_1^n), \text{ and hence } (H_1) \text{ with the same parameters, the estimate (ii) in Lemma 3.1 holds true for each term of } (V^n)_s \text{ and } (N^n)_s \text{ (uniformly in } n). \text{ As bounded sequences of Hilbert spaces, there exist subsequences of } (V^n) \text{ and } (N^n) \text{ such that: } V^n \overset{w}{\to} \bar{V} \text{ (in } L^2(d(M) \otimes d\mathbb{P})) \text{, and: } N^n \overset{w}{\to} \bar{N}_T \text{ in } L^2(\Omega, \mathcal{F}_T, \mathbb{P}). \text{ This implies the weak convergence in } L^2(\Omega, \mathcal{F}_T, \mathbb{P}) \text{ of } N^n \text{ to } \bar{N}_T, \text{ if we define } \bar{N}_T \text{ by: } \bar{N}_T = \mathbb{E}^{\mathbb{P}}(\bar{N}_T). \text{ However, to justify the passage to the limit}
\]

\[5\]  The space \( S^2 \) consists of all continuous processes \( U \) such that: \( \mathbb{E} \left( \sup_{t \in [0,T]} |U_t|^2 \right) < \infty.\]
in the BSDEs given by \((g^n, e^\beta B^n)\), we need the strong convergence of \((V^n)\), eventually along a subsequence, to \(V\) in \(L^2(dM \otimes dP)\) (resp. \((N^n)\) to \(N\) in \(\mathcal{M}^2([0,T])\)). We give one essential result (similar to the stability result in [16]) which is the key ingredient in the last step of the proof of Theorem 2.5.

**Lemma 3.3** Let \((g^n)\) and \((\tilde{B}^n)\) be two sequences associated with the BSDEs\((g^n, \tilde{B}^n)\) of type \((\text{Eq2})\) and satisfying
- \(\mathcal{P}\)-a.s. and for all \(s\), \((g^n : (u,v) \to g^n(s,u,v))\) converges increasingly w.r.t. \(n\) and uniformly on the compact sets of \(\mathbb{R} \times \mathbb{R}^d\) to \(g : (u,v) \to g(s,u,v)\) (\(g\) is continuous w.r.t. \((u,v)\)).
- \((\tilde{B}^n)\) is a uniformly bounded sequence of \(\mathcal{F}_T\)-measurable random variables, which converges almost surely to \(\tilde{B}\) and increasingly w.r.t. \(n\).

If there exists one solution \((U^n, V^n, N^n)\) of the BSDEs given by \((g^n, \tilde{B}^n)\) such that the sequence \((U^n)_n\) is increasing, then the sequence \((U^n, V^n, N^n)\) converges to \((\tilde{U}, \tilde{V}, \tilde{N})\) in the following sense

\[ \mathbb{E} \left( \sup_{t \in [0,T]} |U^n_t - \tilde{U}_t| \right) \to 0, \text{ as } n \to \infty, \]

\[ \mathbb{E} \left( \int_0^T |m_s(\tilde{V}_s - V^n_s)|^2 dC_s + |N^n_T - N^n_T|^2 \right) \to 0, \text{ as } n \to \infty. \]

and the triplet \((\tilde{U}, \tilde{V}, \tilde{N})\) solves the BSDE\((g, \tilde{B})\) of type \((\text{Eq2})\).

**Remark 3.4** The “stability” result stated in Lemma 3.3 holds also for the solution of the BSDE\((F, \beta, B)\) of type \((\text{Eq1})\) (this results from the correspondence established in the second step).

We relegate to subsection 3.3.2 the technical point in the proof of Lemma 3.3, i.e. the strong convergence in their respective Hilbert spaces of the sequences \((V^n)\) and \((N^n)\). Assuming this, we prove the existence of a solution for BSDE\((g, \tilde{B})\) by justifying the passage to the limit in the BSDEs\((g^n, \tilde{B}^n)\)

\[ U^n_t = \tilde{B}^n + \int_t^T g^n(s,U^n_s,V^n_s)dC_s - \int_t^T V^n_s dM_s - (N^n_T - N^n_T). \]

To this end, we check that, \(\mathcal{P}\)-a.s. and for all \(t\),
(i) \(V^n \to \tilde{V}\) (in \(L^2(dM \otimes dP)\)), as \(n \to \infty\),
(ii) \(N^n \to \tilde{N}\) (in \(\mathcal{M}^2([0,T])\)), as \(n \to \infty\),
(iii) \(\mathbb{E} \left( \int_0^T |g^n(s,U^n_s,V^n_s) - g(s, \tilde{U}_s, \tilde{V}_s)| dC_s \right) \to 0, \text{ as } n \to \infty. \)

Assertions (i) and (ii) are consequences of the strong convergence of the sequences \((V^n)\) (resp. \((N^n)\)) in \(L^2(dM \times dP)\) (resp. in \(\mathcal{M}^2([0,T])\)). To prove (iii), we justify the convergence in \(L^1(dC \otimes dP)\) using the two following results:
- The convergence in \(dC_s \otimes dP\)-measure of \((m_sV^n_s)\) and \((U^n_s)\) (at least along proper subsequences) and the properties of \((g^n)\), which ensure the convergence of \((g^n(s,U^n_s,V^n_s))\) to \(g(s, \tilde{U}_s, \tilde{V}_s)\) in \(dC_s \otimes dP\)-measure.
- The uniform integrability of the family \((g^n(s,U^n_s,V^n_s))\) resulting from the estimates of \(g^n\) given by \((H'_1)\) and from the fact that \(\langle mV^n \rangle^2\) is a uniformly integrable sequence, since it is strongly convergent in \(L^1(dC \times dP)\).
Passing to the limit as \( n \) goes to \( \infty \), we get that the triplet \((\tilde{U}, \tilde{V}, \tilde{N})\) is a solution of the BSDE\((g, e^{B\beta})\).

To obtain a solution of the BSDE\((F, \beta, B)\), we rely on the results of the two first steps and we set \((\tilde{Y}, \tilde{Z}, \tilde{L})\) using the formula \((3.5)\).

\[
\square
\]

Now, we relax Assumption 1 given by \((3.6)\): i.e., we proceed with the case when \( g \) only satisfies \((H'_1)\). In this case, the lower bound is no more Lipschitz and, for the procedure, we refer once again to \([5]\): the idea consists in using two successive approximations. For this, we define \((g^{n,p})\) as follows

\[
g^{n,p}(s, u, v) = \text{ess inf}_{u',v'} \left( g^{n,p}(s, u', v') + n|m_s(v - v')| + n|u - u'| \right)
\]

which is increasing w.r.t. \( n \) and decreasing w.r.t. \( p \). The entire proof can be rewritten by passing to the limit as \( n \) goes to \( \infty \) (\( p \) being fixed) and then as \( p \) goes to \( \infty \).

### 3.3.2 Proof of the “stability” result in Lemma 3.3

Following the same method as in \([16]\), we establish the strong convergence of the sequences \((V^n)_n\) and \((N^n)_n\) to \(\tilde{V}\) and \(\tilde{N}\) (this requires the a priori estimates established in Lemma 1 for the solutions of the BSDEs given by \((g^n, \tilde{B}^n)\)). We first introduce the nonnegative semimartingale: \(\Phi_L(U^n - U^p) = (\Phi_L(U^n,p))_{n \geq p}\), with \(\Phi_L\) such that

\[
\Phi_L(x) = e^{Lx} - Lx - \frac{1}{L^2}.
\]

This function \(\Phi_L\) satisfies: \(\Phi_L \geq 0\), \(\Phi_L(0) = 0\), \(\Phi''_L - L\Phi'_L = 1\), \(\Phi'_L(x) \geq 0\) and \(\Phi'_L(x) \geq 1\), if \( x \geq 0 \). Since \(V^n,p\), \(M\) and \(N^n,p\) are square integrable martingales, their expectations are constant. Applying Itô’s formula to \(\Phi_L(U^n,p)\) between 0 and \(T\), we get

\[
\begin{align*}
\mathbb{E}\Phi_L(U^n_0) - \mathbb{E}\Phi_L(U^n_T) &= \mathbb{E} \int_0^T (\Phi'_L(U^n_s,p)(g^n(s, U^n_s, V^n_s) - g^p(s, U^p_s, V^p_s))))dC_s \\
&\quad - \mathbb{E} \int_0^T \Phi''_L(U^n_s,p)|m_s(V^n_s)|^2dC_s - \mathbb{E} \int_0^T \Phi'_L(U^n_s,p)d\langle N^n,p\rangle_s.
\end{align*}
\]

Then, since both \(g^n\) and \(g^p\) satisfy \((H'_1)\) with the same parameters,

\[
|g^n(s, U^n_s, V^n_s) - g^p(s, U^p_s, V^p_s)|
\]

\[
\leq 2\tilde{a} + \frac{\gamma}{2}|m_s(V^n_s)|^2 + \frac{\gamma}{2}|m_s(V^p_s)|^2
\]

\[
\leq 2\tilde{a} + \frac{3\gamma}{2}(|m_s(V^n_s)|^2 + |m_s(V^p_s - \bar{V}_s)|^2 + |m_s\bar{V}_s|^2) + \gamma(|m_s(V^p_s - \bar{V}_s)|^2 + |m_s\bar{V}_s|^2)
\]

\[
\leq 2\tilde{a} + \frac{3\gamma}{2}(|m_s(V^n_s)|^2 + \frac{5\gamma}{2}(|m_s(V^p_s - \bar{V}_s)|^2 + |m_s\bar{V}_s|^2)).
\]
The two last inequalities result from the convexity of: \( z \rightarrow |z|^2 \). Using these estimates and transferring both
\[
\mathbb{E} \left( \int_0^T \frac{\Phi''_L}{2} (U_s^{n,p}) m_s(V_s^{n,p})^2 \, dC_s \right) \quad \text{and} \quad \mathbb{E} \left( \int_0^T \frac{\Phi'_L(U_s^{n,p})}{2} 3\gamma |m_s(V_s^{n,p})|^2 \, dC_s \right),
\]
in the left-hand side of Itô’s formula applied to \( \Phi_L(U_s^{n,p}) \), we obtain
\[
\mathbb{E} \Phi_L(U_0^{n,p}) + \frac{1}{2} \mathbb{E} \left( |N_s^{n,p}|^2 \right) + \mathbb{E} \left( \int_0^T \left( \frac{\Phi''_L}{2} - \frac{3\gamma}{2} \Phi'_L \right) (U_s^{n,p}) m_s(V_s^{n,p})^2 \, dC_s \right)
\leq \mathbb{E} \Phi_L(\tilde{B}^n - \tilde{B}^p) + \mathbb{E} \left( \int_0^T \frac{\Phi'_L(U_s^{n,p})}{2} \left( 2\alpha_s + \frac{5\gamma}{2} (|m_s(V_s^p - \tilde{V}_s)|^2 + |m_s\tilde{V}_s|^2) \right) \, dC_s \right). \tag{**}
\]
Setting: \( L = 8\gamma \), and using the definition (3.10), we check
\[
\Phi''_L - 8\gamma \Phi'_L = 1, \tag{3.11}
\]
which entails the positiveness of the last term of the left-hand side. Then, thanks to the weak convergence of \((V^n)\) to \(\tilde{V}\) (and of \((N^n)\) to \(\tilde{N}\)) and the convexity of: \( z \rightarrow |z|^2 \), we have
\[
\liminf_{n \to \infty} \mathbb{E} \left( \int_0^T \left( \frac{\Phi''_L}{2} - \frac{3\gamma}{2} \Phi'_L \right) (U_s^{n,p}) m_s(V_s^{n,p})^2 \, dC_s \right) \geq \mathbb{E} \left( \int_0^T \frac{\Phi'_L(U_s^{n,p})}{2} (\tilde{U}_s - U_s^p) (|m_s(\tilde{V}_s - V_s^p)|^2) \, dC_s \right). \tag{3.12}
\]
Similarly, we get
\[
\liminf_{n \to \infty} \mathbb{E} \left( |N_T^{n,p}|^2 \right) \geq \mathbb{E} \left( |\tilde{N}_T - N_T^p|^2 \right). \tag{3.13}
\]
Using the almost sure convergence of the increasing sequence \((U^n)\) to \(\tilde{U}\), the dominated convergence theorem yields
\[
\Phi'_L(U_s^{n,p}) \left( \frac{5\gamma}{2} (|m_s(\tilde{V}_s - V_s^p)|^2 + |m_s\tilde{V}_s|^2) + 2\alpha_s \right) \leq \Phi_L(\tilde{U}_s - U_s^p) \left( \frac{5\gamma}{2} (|m_s(\tilde{V}_s - V_s^p)|^2 + |m_s\tilde{V}_s|^2) + 2\alpha_s \right), \tag{3.14}
\]
which holds uniformly in \( n \). Besides, the process in the right-hand side of (3.14) is integrable w.r.t. \( dC_s \), as a product of a bounded process and a sum of integrable processes. To obtain a lower bound of the left-hand side of inequality (**), we use both (3.12) and (3.13). Then, for the right-hand side of (**), we rely on (3.14) and on the almost sure and increasing convergence of \((\tilde{B}^n)\) to \(\tilde{B}\) to get
\[ \mathbb{E}[\Phi_L(U_0 - U_0^p) + \frac{1}{2} \mathbb{E}(|N_T - N_T^p|^2)] \\
+ \mathbb{E} \int_0^T ((\Phi_L^\prime - \frac{3\gamma}{2}\phi_L)(\bar{U}_s - U_0^p)\bar{m}_s(\bar{V}_s - V_0^p)^2) dC_s \\
\leq \mathbb{E}\left(\Phi_L(\bar{B} - \bar{B}^p) + \int_0^T \Phi_L^\prime(\bar{U}_s - U_0^p)(\frac{5\gamma}{2}m_s(\bar{V}_s - V_0^p)^2 + 2\bar{\alpha}_s + 5\gamma m_s\bar{V}_s^2) dC_s\right). \]

Transferring now \( \mathbb{E}(\int_0^T \Phi_L^\prime(\bar{U}_s - U_0^p)\frac{5\gamma}{2}m_s(\bar{V}_s - V_0^p)^2 dC_s) \) in the left-hand side of this inequality and using properties of \( \Phi_L \) and, in particular, (3.11), we obtain

\[ \mathbb{E} \left(\Phi_L(\bar{B} - \bar{B}^p) + \frac{1}{2} \mathbb{E} \left( \int_0^T |m_s(\bar{V}_s - V_0^p)|^2 dC_s + |N_T - N_T^p|^2 \right) \right) \leq \mathbb{E} \left(\Phi_L(\bar{B} - \bar{B}^p) + \int_0^T \Phi_L^\prime(\bar{U}_s - U_0^p)(2\bar{\alpha}_s + 5\gamma m_s\bar{V}_s^2) dC_s\right). \]

Thanks to the convergence of \( (\bar{U}_s - U_0^p) \) to 0 (holding true \( \mathbb{P} \)-a.s. and for all \( s \)) and since \( |m\bar{V}|^2 \) and \( \bar{\alpha} \) are in \( L^1(dC \otimes d\mathbb{P}) \), the dominated convergence theorem entails the convergence of the right-hand side to 0. Taking the limit sup over \( p \) in the left-hand side, it yields

\[ \lim_{p \to \infty} \sup \mathbb{E} \left( \frac{1}{2} \mathbb{E} \left( \int_0^T |m_s(\bar{V}_s - V_0^p)|^2 dC_s + |N_T - N_T^p|^2 \right) \right) \leq 0, \]

which ends the proof.

4 Applications to finance

In this section, we study the problem (1.1) stated in the introduction for three types of utility functions.

4.1 The case of the exponential utility

**Theorem 4.1** \( \bullet \) For any fixed \( t \), the value process given at time \( t \) by \( V_t^B \) can be expressed in terms of the unique solution \((Y, Z, L)\) of BSDE of type (Eq1) given by \((F^\alpha, \beta, B)\)

\[ V_t^B(x) = U_\alpha(x - Y_t). \]  

(4.1)

The constant \( \beta \) corresponds to the risk-aversion parameter \( \alpha \), \( B \) is the contingent claim and \( F^\alpha \) is the generator, whose expression is given by

\[ F^\alpha(s, z) = \inf_{\nu \in C} \left( \frac{\alpha}{2} \left( m_s(\nu - (z + \frac{\lambda_s}{\alpha}))^2 \right) - (m_s z) \left( m_s \lambda_s \right) \right) \frac{1}{2\alpha} \left|m_s \lambda_s \right|^2. \]
• There exists an optimal strategy: \( \nu^* = (\nu^*_s)_{s \in [t, T]} \) such that: \( \nu^* \in \mathcal{A}_t \), and satisfying, \( \mathbb{P} \)-a.s. and for all \( s \),

\[
\nu^*_s \in \text{argmin}_{\nu \in \mathbb{C}} |m_s(\nu - (Z_s + \frac{\lambda_s}{\alpha}))|^2. \tag{4.2}
\]

• Extending the definition of \( V^B_t (x) \) to an arbitrary stopping time \( \tau \), we set

\[
V^B_t (x) = \text{esssup}_\nu \mathbb{E}^{\mathcal{F}_\tau} \left( U_\alpha(x + \int_\tau^T \nu^*_u \frac{dS^u}{S^u} - B) \right).
\]

where, in this expression, all trading strategies \( \nu \) are defined on \([\tau, T]\). Then, for any \( \tau \),

\[
V^B_\tau(x) = U_\alpha(x - Y_\tau) = R^{\nu^*}_\tau,
\]

and we recover the formulation of the dynamic programming principle

\[
\forall \ \tau, \ \sigma \leq \tau, \ \mathcal{F}\text{-stopping times,} \quad V^B_\tau(x) = \mathbb{E}^{\mathcal{F}_\tau} (V^B_\sigma(X^{\nu^*}_{\sigma}, \tau, x)). \tag{4.3}
\]

Remark 4.2 To give sense to the expression \( V^B_\tau(X^{\nu^*}_{\tau}, \tau, x) \), we refer to the footnote given at the bottom of page 5: indeed and by definition, \( X^{\nu^*}_{\tau}, \tau, x = x + \int_\tau^\tau \nu^*_u \frac{dS^u}{S^u} \), is an attainable wealth at time \( \sigma \), when starting from \( x \) at time \( \tau \).

Proof To prove (4.1), we rely on the results obtained in Section 3 to claim the existence of a unique solution \((Y, Z, U)\) of the BSDE\((F^\alpha, A, B)\). Then, using the expression of \( R^\nu = U_\alpha(X^\nu - Y) \) obtained in the last paragraph of Section 2.1, we write

\[
\forall \ s \in [t, T], \quad R^\nu_s = R^\nu_\tau \tilde{M}^\nu_s \exp(A^\nu_s - A^\nu_\tau),
\]

with: \( \tilde{M}^\nu_s = \mathcal{E}_{t,s}(-\alpha(\nu - Z)_t \cdot M + \alpha L) \). Since the continuous stochastic exponential is a positive local martingale and since: \( A^\nu \geq 0 \), there exists a sequence of stopping time \( (\tau_n) \) such that \( (R^\nu_{\tau_n}) \) is a supermartingale (for each \( \nu \)), which entails

\[
\forall \ s, \ t \leq s \leq T, \ \forall \ A \in \mathcal{F}_t, \quad \mathbb{E}(R^\nu_{s \wedge \tau_n} 1_A) \leq \mathbb{E}(R^\nu_s 1_A).
\]

Using the definition of admissibility and the boundedness of \( Y \), we obtain the uniform integrability of \( (R^\nu_{s \wedge \tau_n}) \) and \( (R^\nu_{s \wedge \tau_n}) \). Passing to the limit, we get: \( \mathbb{E}(R^\nu_s 1_A) \leq \mathbb{E}(R^\nu_s 1_A) \), which entails the supermartingale property of \( R^\nu \), as soon as: \( \nu \in \mathcal{A}_t \). This supermartingale property and the relation: \( R^\nu_\tau = U_\alpha(x - Y_\tau) \), imply

\[
V^B_\tau(x) = \text{ess sup}_{\nu \in \mathcal{A}_t} \mathbb{E}^{\mathcal{F}_\tau} (U_\alpha(X^{\nu^*}_{\tau}, \tau, x - B) \leq U_\alpha(x - Y_\tau).
\]

Now, to obtain the equality (4.1), we focus on the second point of Theorem 4.1. Since: \( z \rightarrow F^\alpha(s, z) \) is a continuous functional of \( z \), which tends to \( +\infty \), as \( |z| \) goes to \( \infty \), the infimum in the expression of \( F^\alpha \) exists. Furthermore, relying on the same selection argument as in lemma 11 in [12] and thanks to the continuity of the functional and the predictability of the processes \( \lambda \) and \( Z \), there exists a measurable choice of \( \nu^*_s \) satisfying (4.2), i.e. \( A^{\nu^*} \equiv 0 \). To check that: \( \nu^* \in \mathcal{A}_t \), we argue that, from the choice of \( \nu^* \) given in Theorem 4.1 and since 0 is in \( \mathbb{C} \),

\[
\forall s \in [0, T], \quad |m_s(\nu^*_s - (Z_s + \frac{\lambda_s}{\alpha}))| \leq |m_s(Z_s + \frac{\lambda_s}{\alpha})|.
\]
Since $|m_s(\nu^* - Z_s)| \leq |m_s(\nu^* - (Z_s + \frac{\lambda}{\nu^*}))| + |m_s \frac{\lambda}{\nu^*}$, we obtain a control of $|m(\nu^* - Z)|$ depending only on the processes $Z$ and $\lambda$. Hence and thanks to Kazamaki’s criterion (see [14]), $E(-\alpha(\nu^* - Z) \cdot M)$ is a true martingale. The process $R_{\nu^*}$, such that, for all $s, s \geq t$

$$R_{\nu^*}^t = -e^{-\alpha(x - Y_t)} E_{t,s}(-\alpha(\nu^* - Z) \cdot M + \alpha L),$$

is a true martingale, which implies that: $\nu^* \in A_t$ and the equality (4.1).

To recover the dynamic programming principle, we define the $\mathcal{F}_\tau$-measurable random variable $V_{B_\tau}(x)$ the same way as $V_{B_t}(x)$ and for any $\mathcal{F}$-stopping time $\tau$. The same procedure as the one used to prove (4.1) entails

$$V_{\tau}^B(x) = U_{\alpha}(x - Y_\tau) = U_{\alpha}(X_{\tau,\tau,x} - Y_\tau) = R_{\nu^*}^\tau.$$

Applying the optional sampling theorem between $\tau$ and $\sigma$ to the martingale $R_{\nu^*}$ defined by: $R_{\nu^*}^s = U_{\alpha}(X_{\nu^*,\tau,x} - Y)$, we get (4.3).

\[\square\]

4.2 Power and logarithmic utilities

As in [12], we introduce two other types of utility functions:

- The first one is the power utility, defined for all real $\gamma, \gamma \in ]0, 1[$, by: $U_\gamma(x) = \frac{1}{\gamma} x^\gamma$ ($\gamma$ being fixed, we write $U^1$ instead of $U_\gamma$).

- The second one is the logarithmic utility, given by: $U^2(x) = \ln(x)$.

Contrary to the exponential case, we have to impose that the wealth process is positive. We focus our attention to the case where there is no liability any more (i.e. $B \equiv 0$, in the problem (1.1)). In this context, a constrained trading strategy is a $\mathbb{R}^d$-dimensional process $\rho$, which takes its values in the constraint set $C$ and such that, for each $i$, $\rho^i$ stands for the part of the wealth invested in stock $i$. The discounted price process $S$ is again assumed to satisfy (2.1) and we denote by: $X^\rho = X^{\rho,\tau,x}$, the wealth process associated with the strategy $\rho$ and such that: $X^\rho_t = x$. Its expression for any $s, s \in [t, T]$, is

$$X^\rho_s = x + \int_t^s X_u^\rho \rho_u \frac{dS_u}{S_u} = x + \int_t^s X_u^\rho \rho_u dM_u + \int_t^s X_u^\rho \rho_u d\langle M \rangle_u \lambda_u.$$

The decomposition of the price process $S$ is the same as in Section 1.2 and, in particular, $\lambda$ is a predictable $\mathbb{R}^d$-valued process. For each case, we give in subsections 4.2.1 and 4.2.2 a definition of the admissibility set for trading strategies (this set is always denoted by $A_t$). Denoting by $U$ the utility function, we are going to characterize the value process associated to the utility maximization problem with liability equal to zero; this process is defined at time $t$ by

$$V_t(x) = \text{ess sup}_{\rho, \rho \in A_t} E^{\mathcal{F}_t}(U(x + \int_t^T X_u^\rho \rho_u \frac{dS_u}{S_u})).$$

(4.4)
4.2.1 The power utility case

Definition 4.3 The set of admissible strategies $\mathcal{A}_t$ consists of all $d$-dimensional predictable processes $\rho = (\rho_s)_{s \in [t,T]}$ such that: $\rho_s \in \mathcal{C}$ ($\mathbb{P}$-a.s. and for all $s$) as well as

$$
\int_t^T \rho_s' d(M)_s \rho_s = \int_t^T |m_s \rho_s|^2 dC_s < \infty, \; \mathbb{P} \text{- a.s.}
$$

This condition entails that the stochastic exponential $\mathcal{E}(\rho \cdot M)$ is a continuous local martingale. We can now solve the problem (4.4) for the power utility function $U^1$.

Theorem 4.4 Let $V^1_t$ be the value process associated with the problem (4.4) and having for utility function: $U = U^1$.

- Its expression is

$$
V^1_t(x) = \frac{x^\gamma}{\gamma} \exp(Y_t).
$$

In this expression, $(Y,Z,L)$ stands for the unique solution of the BSDE$(f^1,1,0)$ of type (Eq1)

$$
Y_t = 0 - \int_t^T f^1(s,Z_s) dC_s + \int_t^T \frac{1}{2} d(L)_s - \int_t^T Z_s dM_s - (L_T - L_t),
$$

the process $L$ is a real-valued martingale strongly orthogonal to $M$ and the expression of the generator $f^1$ is given by

$$
f^1(s,z) = \inf_{\rho, \rho' \in \mathcal{C}} \frac{\gamma(1-\gamma)}{2} \left( m_s(\rho - \frac{z + \lambda_s}{1 - \gamma})^2 \right) - \frac{\gamma(1-\gamma)}{2} |m_s(z + \lambda_s)|^2 - \frac{1}{2} |m_s|^2. \tag{4.5}
$$

- There exists an optimal strategy $\rho^*_t$ satisfying, $\mathbb{P}$-a.s. and for all $s$,

$$
(\rho^*_t)(s) \in \arg \min_{\rho, \rho' \in \mathcal{C}} |m_s(\rho - \frac{Z_s + \lambda_s}{1 - \gamma})|^2. \tag{4.6}
$$

Remark 4.5 The expression of the optimal strategy $\rho^*$ is already known in the brownian setting and when there is no trading constraints: in that case, the wealth process $X^\pi$ satisfies

$$
dX^\pi_s = rX^\pi_t ds + X^\pi_t \left( \sigma_s \pi_s dW_s + (\mu - r) \pi_s ds \right). \tag{4.7}
$$

In the elementary case of constant coefficients in (4.7), the optimal proportion is equal to $\frac{\mu - r}{\sigma^2}$. (this result can be found in [6] or also in the seminal paper of [15]). In [25], the author generalizes those previous results assuming that the price process is a geometric brownian motion and assuming that there exists an additional asset, which is driven by another brownian motion correlated to the first one: in that case, the explicit formula for the optimal strategy incorporates the effect of the correlation factor.
Proof. We just give a sketch of the proof, which is similar to the one given in the exponential case and relies on the same dynamic method as in [12]. To this end, we define the process $R_\rho^s$ for all $s, s \in [t, T]$ by:

$$R_\rho^s = X_\rho^s \exp(Y^s),$$

and since $Y$ is solution of the BSDE($f_1^1, 1_2^2, 0$), simple computations leads to

$$R_\rho^s = R_\rho^t 1_{t,s}(\gamma \rho + Z) \cdot M + L) \exp(\tilde{A}_\rho^s - \tilde{A}_\rho^t),$$

where the process $\tilde{A}_\rho^s$ is such that

$$\tilde{A}_\rho^s = \int_0^s (f_1^1(u, Z_u) + \gamma |m_u Z_u|^2 + \frac{\gamma(\gamma - 1)}{2} |m_u \rho_u|^2 + \gamma (m_u \rho_u) (m_u (Z_u + \lambda_u)))dC_u.$$
Remark 4.8 As in the power utility case, we recover the expression of the optimal proportion in the brownian setting. Assuming that the coefficients \( \mu, \sigma \) and \( r \) are constants, this proportion is equal to: \( \rho^* \equiv \frac{\mu-r}{\sigma^2} \).

Proof The wealth process \( X^\rho \) satisfies again

\[
X^\rho_s = x + \int_0^s X^\rho_u \rho_u dM_u + \int_0^s X^\rho_u (m_u \rho_u)' (m_u \lambda_u) dC_u.
\]

Now, using both Itô’s formula and the assumption that \( Y \) solves a BSDE of type (Eq2), it yields

\[
R^\rho_s = \ln(X^\rho_s) + Y_s = \ln(x) + Y_t + \int_t^s ((\rho_u + Z_u) dM_u + dL_u) + A^{\rho^2}_s(s) - A^{\rho^2}_s(t),
\]

where the process \( A^{\rho^2}_s \) is such that

\[
A^{\rho^2}_s(s) = \int_0^s \left( f^2(u) - \frac{1}{2} |m_u \rho_u|^2 + (m_u \rho_u)' (m_u \lambda_u) \right) dC_u.
\]

From the definition of \( f^2 \), we obtain: \( A^{\rho^2}_s \leq 0 \), and we deduce:

- \( \ln(X^\rho) + Y \) is a supermartingale, for any \( \rho \) such that \( \rho \in A^t \).

If, besides, \( \rho^2 \) satisfies (4.9) then: \( A^{\rho^2}_s = 0 \) and hence: \( |m(\rho^2 - \lambda)| \leq |m\lambda| \). The assumption \( (H\lambda) \) on \( \lambda \) implying the uniform integrability of \( R^{\rho^2} \), we can claim

- \( \ln(X^{\rho^2}) + Y \) is a martingale.

Such a strategy \( \rho^2 \) is optimal and applying the optional sampling theorem to \( R^{\rho^2} \), we get

\[
V_{\rho^2}(x) = \mathbb{E}^{\mathbb{F}^i} (R^{\rho^2}_{T^i}) = R^{\rho^2}_t = \ln(x) + Y_t.
\]

\( \Box \)

5 Conclusion

In this paper, we have solved the utility maximization problem by characterizing both the value process and the optimal strategies: the novelty of our study is that we have used a dynamic method in the context of a general (and non necessarily Brownian) filtration and in presence of portfolio constraints. This last assumption entails that the introduced BSDEs have quadratic growth.

Since we are not in the Brownian setting, the first part of our work consists in justifying new existence and uniqueness results for solutions of a specific type of quadratic BSDEs. This study leads to an expression of the value process in terms of a solution of a BSDE of the previous type. Relying on the dynamic principle, we are able to characterize this value process for three cases of utility functions. This type of BSDE has already been studied in a particular case in [18] in connection with the notion of indifference utility price. However, one of the main differences in [18] is that no constraints are imposed on the portfolio. Furthermore and contrary to our setting, they refer to duality methods. Our study depends heavily on the assumption that the filtration is continuous and we hope to study the case when jumps are allowed. Another perspective is to study the connection with the problem of utility indifference pricing.

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6 Appendix: proof of proposition 3.2

Contrary to lemma 3.1, where the process $Y$ is supposed to be in $S^\infty$, in this proposition, the process $U^n$ is only assumed to be in $S^2$. First, we apply Itô’s formula to $(e^{\Gamma C_t} |U^n_t|^2)$, $\Gamma$ being a non negative constant
\begin{equation}
\begin{aligned}
\frac{d(e^{\Gamma C_t} |U^n_t|^2)}{dt} &= e^{\Gamma C_t} |U^n_t|^2 dC_t + e^{\Gamma C_t} (2U^n_t dU^n_t + d(U^n_t)), \\
\end{aligned}
\end{equation}

(6.1)
with
\[2U^n_t dU^n_t + d\langle U^n \rangle_t = -2U^n_t g^n(t, U^n_t, V^n_t) dC_t + |m_t V^n_t|^2 dC_t + d\langle N^n \rangle_t \]
\[\quad + 2U^n_t (V^n_t M_t + dN^n_t).\]

Since \((U^n, V^n, N^n)\) is in \(S^2 \times L^2(d\langle M \rangle \times d\mathbb{P}) \times M^2([0, T])\), it follows that the process \(K\) defined by
\[K_s = \int_0^s 2e^{RC_u} U^n_u (V^n_u dM_u + dN^n_u),\]
(6.2)
is a true martingale. We now fix \(t \in [0, T]\) and we rewrite Itô’s formula (6.1) between \(s\) \((t \leq s \leq T)\) and \(T\)
\[e^{RC_t} |U^n_s|^2 - e^{RC_T} |U^n_T|^2 = \int_s^T e^{RC_u} U^n_u (\Gamma U^n_u + m_u V^n_u)^2 dC_u \]
\[\quad - \int_s^T e^{RC_u} (|m_u V^n_u|^2 dC_u + d\langle N^n \rangle_u) - (K_T - K_s).\]

Relying on the Lipschitz property of the generator \(g^n\), we get
\[2|U^n_u|^2 g^n(u, U^n_u, V^n_u) \leq 2|U^n_u|^2 |g^n(u, 0, 0)| + 2L_n (|U^n_u|^2 + |U^n_u||m_u V^n_u|),\]
and using the inequality: \(2L_n |ab| \leq (2L_n)^2 a^2 + \frac{1}{2} b^2\), we obtain
\[2L_n |U^n_u||m_u V^n_u| \leq 2(2L_n) |U^n_u|^2 + \frac{1}{2} |m_u V^n_u|^2.\]

Combining these two last inequalities, setting: \(\Gamma = 2((L_n)^2 + L_n)\), and taking the expectation w.r.t \(\mathcal{F}_t\) in Itô’s formula applied to \(e^{RC_t} |U^n_t|^2\) between \(t\) and \(T\), it yields
\[e^{RC_t} |U^n_t|^2 \leq \mathbb{E} \left( e^{RC_T} |U^n_T|^2 |\mathcal{F}_t \right) \]
\[\quad + \mathbb{E} \left( \int_t^T e^{RC_u} (2|U^n_u|^2 |g^n(u, 0, 0)| + \frac{1}{2} |m_u V^n_u|^2) dC_u |\mathcal{F}_t \right) \]
\[\quad - \mathbb{E} \left( \int_t^T e^{RC_u} (|m_u V^n_u|^2 dC_u + d\langle N^n \rangle_u) |\mathcal{F}_t \right).\]

This leads to
\[\mathbb{E} \left( \int_t^T e^{RC_u} (|m_u V^n_u|^2 dC_u + d\langle N \rangle_u) |\mathcal{F}_t \right) \]
\[\quad \leq 2 \left( \mathbb{E} \left( e^{RC_T} |U^n_T|^2 \right) + 2 \int_t^T e^{RC_u} |U^n_u|^2 |g^n(u, 0, 0)| dC_u |\mathcal{F}_t \right).\]
(6.3)
We come back to Itô’s formula (6.1) for the process $e^{ΓC_s |U^n_s|^2}$ between $s$ and $T$. Taking the supremum over $s (s \in [t, T])$, it follows
\[
\begin{align*}
sup_{t \leq s \leq T} e^{ΓC_s |U^n_s|^2} & \leq e^{ΓC_T |U^n_T|^2} \\
+ 2 \int_t^T e^{ΓC_u |g^n(u, 0, 0)|dC_u} + sup_{t \leq s \leq T} |K_T - K_s|.
\end{align*}
\]
Applying the Burkholder-Davis-Gundy inequality to the supremum of the square integrable martingale $K$ and the relation: $C a b \leq C^2 a^2 + \frac{1}{2} b^2$, we deduce the existence of a constant $C$ such that
\[
\begin{align*}
& \mathbb{E}\left(\sup_{t \leq s \leq T} e^{ΓC_s |U^n_s|^2} |F_t\right) \leq \mathbb{E}\left(e^{ΓC_T |U^n_T|^2} + 2 \int_t^T e^{ΓC_u |g^n(u, 0, 0)|dC_u} |F_t\right) \\
& \quad + \frac{C^2}{2} \mathbb{E}\left(\int_t^T e^{ΓC_u |m_u V^n_u|^2 dC_u + d(N)_u} |F_t\right) + \frac{1}{2} \mathbb{E}\left(\sup_{t \leq s \leq T} e^{ΓC_s |U^n_s|^2} |F_t\right),
\end{align*}
\]
where the constant $C$ is generic and may vary from line to line. Combining this last inequality with (6.3), we deduce
\[
\begin{align*}
& \mathbb{E}\left(\sup_{t \leq s \leq T} e^{ΓC_s |U^n_s|^2} |F_t\right) \leq \mathbb{E}\left(e^{ΓC_T |U^n_T|^2} + \int_t^T e^{ΓC_u |g^n(u, 0, 0)|dC_u} |F_t\right) \\
& \quad + \frac{C^2}{2} \mathbb{E}\left(\int_t^T e^{ΓC_u |m_u V^n_u|^2 dC_u + d(N)_u} |F_t\right) + \frac{1}{2} \mathbb{E}\left(\sup_{t \leq s \leq T} e^{ΓC_s |U^n_s|^2} |F_t\right).
\end{align*}
\]
To obtain the desired relation, we use a last estimate of the last term in the right-hand side of the previous inequality
\[
\begin{align*}
& C \mathbb{E}\left(\int_t^T e^{ΓC_u |g^n(u, 0, 0)|dC_u} |F_t\right) \\
& \leq \frac{1}{2} \mathbb{E}\left(\sup_{t \leq s \leq T} e^{ΓC_s |U^n_s|^2} |F_t\right) + \frac{C^2}{2} \mathbb{E}\left(\left(\int_t^T e^{ΓC_u |g^n(u, 0, 0)|dC_u}\right)^2 |F_t\right).
\end{align*}
\]
We can now claim that the relation (3.9) given in proposition 3.2 holds true, using that
\[
e^{ΓC_s |U^n_s|^2} \leq \mathbb{E}\left(\sup_{t \leq s \leq T} e^{ΓC_s |U^n_s|^2} |F_t\right).
\]
To deduce the boundedness of $U^n$ in $S^\infty$, we use the two following properties: on the one hand, $|g^n(u, 0, 0)| \leq \bar{α}_u$, with the process $\bar{α}$ satisfying: $\int_0^T \bar{α}_s dC_s \leq a < \infty$, $\mathbb{P}$-a.s. and, on the other hand and for all $n$, the random variable $U^n_T = e^{βB}$ is bounded.

□