Online Dispatch of Shared Energy Storage with Remote Renewable Generations

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Abstract. The sustained penetration of wind and solar generation is conducive to alleviating the energy crisis and environmental pollution. However, the finite capacity of transmission corridor limits the delivery of remote renewables and leads to curtailment. Energy storage plays an important role in renewables accommodation and improving equipment utilization, and shared energy storage can magnify the benefits through a temporal and spatial complementary. This paper proposes an online dispatch approach of energy storage shared by multiple renewable plants. The uncertainty and non-anticipativity issue are addressed via a two-stage decision-making process. The day-ahead scheduling determines the allowable energy and power levels of shared energy storage; the real-time online dispatch decides the wait-and-see strategies of charging and discharging power based on a single-period optimization model constrained by the pre-scheduled bounds. The case study verifies the effectiveness of the proposed method.

1 Instruction

In response to the worldwide challenges of energy crisis and environmental pollution, renewable energy represented by wind and photovoltaic (PV) power is developing rapidly in recent years. In China, the installed capacity of renewable generation has surged to 4000 GW by 2020 and is projected to be increased to 12 billion kW by 2030. Although the penetration of renewable energy accelerates grid decarbonization and promotes society's sustainable development, the inherent volatility and stochasticity of renewables bring huge challenges to power system dispatch. Moreover, the unbalanced geographical distribution and the insufficient capacity of supporting transmission channels result in massive resource abandonment. Energy storage is a flexible resource to compensate for the mismatch of renewables and load demand and mitigate the curtailment [1].

Motivated by the success of sharing economy, shared energy storage is attracting increasing attention. Considering the high cost and low utilization ratio of energy storage in individual frameworks, shared energy storage exploits the temporal and spatial demand complementary of different users and brings about cost reduction [2]. The shared energy storage can be implemented on the demand-side or generation side. The day-ahead operation of shared energy storage with PV power producers is studied in [3], and the sensitivity-based allocation ratio is adopted for profit distribution. In [4], a combinatorial auction mechanism is induced to the allocation of residential shared energy storage, wherein the capacity, energy storage level, charging and discharging power are taken as multi-sources to be auctioned. [5] pays attention to the electricity losses during the sharing process and develops a hierarchical capacity planning approach for community-level shared batteries. Taking into account the price uncertainty, [6] proposes a sharing strategy of energy storage with two users based on a robust optimization model. Based on the equilibrium approach, [7] presents a pricing and dispatch strategy of a residential system with shared energy storage and multiple consumers.

Considering the randomness and limited predictability of renewables, numerous methods have been proposed for the optimal dispatch of energy storage with renewable energy. Stochastic optimization [8] and robust optimization [9] are classical approaches to address the uncertainty issues, and both methods are formulated based on offline data, such as forecast and historical data while ignoring the non-anticipativity effect. However, the uncertainty is observed period by period and may not be realized as anticipated, thus the anticipative schedules generated by conventional two-stage stochastic/robust optimization may be infeasible in practical operation [10]. To guarantee the causality of decision-making, the scheduling strategy is supposed to be independent of future information.

To resolve the uncertainty and non-anticipatively issues of shared energy storage dispatching with renewable generations, this paper proposes an online dispatch method, which is composed of two stages of decision-making. The day-ahead dispatch pre-schedules...
the allowable state-of-charge (SoC) ranges of shared energy storage; the real-time scheduling determines the wait-and-see decisions of charging and discharging power based on a single-period optimization model constrained by the pre-prespecified bounds without any future information.

The remainder of the paper is organized as follows. Section 2 presents the online dispatch framework of the shared energy storage with renewable plants and establishes the models of non-anticipative day-ahead scheduling and online dispatch. The case study is analyzed in Section 4 and conclusions are drawn in Section 5.

2 Problem Formulation

2.1 Online dispatch framework

The structure of an integrated system with renewables and shared energy storage is shown in Fig. 1. The renewables, including wind power and photovoltaic power, are sold to the grid through the transmission line. Considering the fluctuation of renewable outputs, curtailing takes place in abundant scenarios due to line capacity limitation, and the under-utilization of devices results from insufficient outputs. The energy storage is shared by the solar plants and wind plants to cope with uncertainty and smooth the output.

![Fig.1 System structure.](image)

**Fig.1 System structure.**

In the day-ahead stage, the allowable SoC ranges and the permitted charging/discharging level of shared energy storage is determined based on a rough prediction of the renewable outputs; in the real-time stage, the scheduling moves on hour by hour, and the strategy is determined by a single-period optimization problem with the prespecified bounds after observing the real output of renewables. The online dispatch framework is displayed as follows.

![Fig.2 Online dispatch framework.](image)

**Fig.2 Online dispatch framework.**

2.2 Non-anticipative day-ahead scheduling

The uncertainty of accessible renewable outputs is described via the following box set.

$$ U^m = \left\{ p_i^{ox} | p_i^{ox} \in [p_i^{ox}, p_i^{ox}] \forall i,t \right\} $$

(1)

where the subscript i is the index of renewable plant, and subscript t is the index of time slot. $p_i^{ox}$ is the uncertain output of each renewable plant, $p_i^{ox}$ and $p_i^{ox}$ are the predicted lower and upper bounds. The minimal possible total output $p_i^{ox}$ can be calculated by $\sum_i p_i^{ox}$, and the maximal possible total output $p_i^{ox}$ equals $\sum_i p_i^{ox}$, where I is the number of renewable plants. Then, the uncertainty of total renewable output $p_i^{ox}$ can be judged by

$$ U^{ox} = \left\{ p_i^{ox} | p_i^{ox} \leq p_i^{ox} \leq p_i^{ox} \forall t \right\} $$

(2)

Consider the curtailment of renewables, the uncertainty set of real accommodated renewables is adjusted by

$$ U^c = \left\{ p_i^{ox} | \min \left\{ p_i^{ox} - h_i, p_i^{ox} \right\} \leq p_i^{ox} - p_i^{ox} \forall t \right\} $$

(3)

where $h_i$ is the curtailment level, and is determined in the day-ahead scheduling. Two vertex scenarios denoted by S1 and S2 are picked from the uncertainty realizations:

$$ p_{i, S1}^{ox} = p_i^{ox} - h_i \forall t $$

(4)

which represents the maximal renewable output ;

$$ p_{i, S2}^{ox} = \min \left\{ p_i^{ox} - h_i, p_i^{ox} \right\} \forall t $$

(5)

which represents the minimal renewable output. The day-ahead dispatch problem is formulated as follows.

$$ \max \sum_{i=1}^{I} \sum_{t=1}^{T} \omega_t \left( \tilde{p}_i^{ox} - p_i^{ox} + p_i^{ox} \right) $$

(6a)

s.t. $\forall i.t.$

$$ p_i^{ox} \leq p_i^{ox} \leq p_i^{ox} \forall i.t.s $$

(6b)

$$ \tilde{p}_i^{ox} = \min \left\{ p_i^{ox} - h_i, p_i^{ox} \right\} \forall i.t.s $$

(6c)

$$ 0 \leq h_i \leq p_i^{ox} $$

(6d)

$$ p_i^{min} \leq p_i^{min} \leq p_i^{min} \forall i.t.s $$

(6e)

$$ p_i^{max} \leq p_i^{max} \leq p_i^{max} \forall i.t.s $$

(6f)

$$ E_i^{min} = E_i^{min} - p_i^{min} + \eta_{i}^{min} \forall i.t $$

(6g)

$$ E_i^{max} = E_i^{max} - p_i^{min} + \eta_{i}^{min} \forall i.t $$

(6h)

where $C_i$ is the electricity price, $\omega_t$ is the weighting factor of the selected scenario and the subscript $s \in \{S1,S2\}$ represents the index of scenario, $\tilde{p}_i^{ox}$ is the actual total output of renewable plants, $p_i^{ox}$ and $p_i^{ox}$ are the charging and discharging power of shared energy storage. Binary variables $\mu_i$ and $\mu_i$ denote the
charging and discharging status of shared energy storage. The auxiliary variables $p_{i,c}^\text{min}$ and $p_{i,d}^\text{max}$ are the allowable lower and upper bounds of charging power, $p_{i,c}^\text{min}$ and $p_{i,d}^\text{max}$ denote the permitted discharging level, $E_{c}^\text{min}$ and $E_{d}^\text{max}$ give the safe ranges of SoC. The parameter $p^\text{f}$ is the transmission line capacity and $\alpha^\text{e}$ is the minimal load rate, $\eta^c$ and $\eta^d$ are the charging and discharging efficiencies, $E$ and $\overline{E}$ are the physical lower and upper bounds of SoC, $\overline{p}^c$, $\overline{p}^d$ and $\overline{p}$ give the physical ranges of charging and discharging power, respectively. The objective (6a) is to maximize the weighted sum of generating income. Constraint (6b) gives the transmission line capacity constraint and the minimal load rate restrictions. Constraint (6c)-(6d) describe the real renewable output under each selected scenario considering the curtailment level. Expressions (6e)-(6k) are non-anticipative constraints of shared energy storage that enforce the all-scenario feasible of the charging and discharging strategies. Constraint (6l) forbids simultaneous charging and discharging. The minimal value expression in (6c) can be transmitted to an equivalent mixed-linear formulation as follows.

\[
\begin{align*}
\bar{p}_{i,c}^c &= \min\{p_{i,c}^\text{max} - h_i, \forall t \} \\
\bar{p}_{i,c}^c &\leq \bar{p}_{i,c}^c - h_i, \forall t \\
\bar{p}_{i,d}^c &\geq \bar{p}_{i,c}^c - h_i - \bar{p}_{i,d}^\text{min} (1 - z_i^1), \forall t \\
\bar{p}_{i,c}^c &\leq \bar{p}_{i,d}^c - \bar{p}_{i,c}^\text{max} (1 - z_i^2), \forall t \\
\bar{z}_i^1, \bar{z}_i^2 &\in \{0, 1\}, \bar{z}_i^1 + \bar{z}_i^2 = 1, \forall t
\end{align*}
\]

where $z_i^1$ and $z_i^2$ are induced binary variables.

### 2.3 Online dispatch

In the real-time dispatch stage, after observing the real accessible total output of renewables $p_i^\text{c}$, the scheduling of shared energy storage is determined based on the following model.

\[
\begin{align*}
\max \quad & C_i \left( \bar{p}_{i,c}^c - p_{i,c}^c + p_{i,d}^d \right) \\
\text{s.t.} \quad & \alpha^p \leq \bar{p}_{i,c}^c - p_{i,c}^c + p_{i,d}^d \leq p^\text{f} \quad (8a) \\
& \bar{p}_{i,c}^c = \min\{p_{i,c}^\text{max} - h_i, \bar{p}_{i,c}^c \} \quad (8b) \\
& 0 \leq h_i \leq \bar{p}_{i,d}^c \quad (8c) \\
& p_{i,c}^\text{min} \leq p_{i,c}^c \leq p_{i,c}^\text{max} \quad (8d) \\
& p_{i,d}^\text{min} \leq p_{i,d}^d \leq p_{i,d}^\text{max} \quad (8e)
\end{align*}
\]

where $p_{i,c}^\text{min}$ and $p_{i,d}^\text{max}$ represent the permitted charging ranges determined in the day-ahead stage, $p_{i,c}^\text{max}$ and $p_{i,d}^\text{max}$ are the pre-specified allowable discharging range, and they are the optimal solution to problem (6). It can be proved that if the non-anticipative day-ahead scheduling problem (6) has feasible solutions, then there must be at least one feasible scheduling strategy for the real-time dispatch under all the uncertainty realizations that reside in the pre-specified sets (1) [10-11]. Different from the models of multi-period dispatch with energy storage, the time-coupling SoC constraints are relaxed, but the bounds of SoC will not be violated under any uncertainty realizations due to the pre-defined bounds of charging/discharging power and SoC level. Moreover, the real-time decision-making only depends on the current observations and requires no predictions, which meets online dispatch requirements.

### 3 Case study

Case studies are carried out on an integrated system with 2 wind plants whose capacities are both 400 MW, a 400 MW solar plant, and a shared energy storage with the capacity of 200 MW/600 MWh. Other system parameters are listed in Table 1. and the predicted renewable output is plotted in Fig.3. All the tests are implemented via Matlab 2016a and Gurobi 9.1.1.

| Parameters | Value (unit) | Parameters | Value (unit) |
|------------|-------------|------------|-------------|
| $\alpha^e$ | 0.5         | $p^f$      | 600 MW      |
| $\eta^c$   | 0.95        | $\eta^d$   | 0.95        |
| $E$        | 30 MWh      | $\overline{E}$ | 600 MWh |
| $p^c$      | 50 MW       | $p^d$      | 200 MW      |
| $p^c$      | 50 MW       | $\overline{p}$ | 200 MW |
| $C_i$      | 0.8 yuan/MWh| $E_0$      | 180 MWh     |

Fig.3 Prediction of renewable output intervals.
The observed renewable output and the power delivery through the transmission line in the real-time stage are shown in Fig. 6. In periods 11-15, the accessible renewable output exceeds the transmission line capacity, thus part of the surplus is used to charge the shared energy storage and the residual energy is abandoned which is represented by the shadow area in Fig. 6, leading to 257.3 MWh renewable curtailment. In periods 17-21, the actual total renewable output below the required minimum load, and the vacancy is compensated by the discharging power.

4 Conclusion

This paper explores the online dispatch of a renewable-storage integrated system where a central energy storage is shared by multiple renewable plants. The proposed method guarantees that the total power exported via the transmission line satisfies the requirement on the utilization rate of transmission capacity, regardless of the hourly unfolding real renewable output. Case study shows that the SoC of the shared energy storage is constrained by two additional bounds, implying that the SoC can vary within a subrange of its physical ranges.
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