Research Article

Exact Solutions for (3 + 1)-Dimensional Potential-YTSF Equation and Discrete Kadomtsev-Petviashvili Equation

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1. Introduction

There has been considerable interest in seeking exact solutions to nonlinear differential or discrete equations. Since the exact solutions can help the physicists to well understand the mechanism of the complicated physical phenomena and dynamic processes modeled by these equations. In recent years, various approaches for constructing exact solutions are currently available such as inverse scattering transformation [1], Hirota direct method [2], the Bäcklund transformation [3], and algebra-geometric method [4–6].

Among vast exact solutions, linear superposition principle [7] and periodic or quasiperiodic wave solution [8] play a significant role in explaining the physical applications of these systems. The former method can be applied to exponential traveling waves of Hirota bilinear equations and is helpful in generating N-wave solutions to soliton equations, particularly those in higher dimensions. The latter is also called algebra-geometric solutions or finite gap solution; it is often obtained based on the inverse spectral theory and algebra-geometric method. The algebra-geometric theory, however, needs Lax pairs and is also involved in complicated analysis procedures on the Riemann surfaces. It is rather difficult to directly determine the characteristic parameters of waves, such as frequencies and phase shifts, for a function with given wave numbers and amplitudes. Based on the Hirota forms, Nakamura proposed a convenient way to find a kind of explicit quasiperiodic solution of nonlinear equations [9, 10]; it does not need any Lax pair and Riemann surface for the given nonlinear equation and is also able to find the explicit construction of multiperiodic wave solutions. Recently, Fan et al. [11–13] extended this method and gave a uniform approach to establish the periodic solutions of nonlinear differential and difference equations. However, there are only a few works [14, 15] available for constructing multiperiodic wave solutions of discrete equations, since more constraint equations need to be satisfied, but the parameters in the bilinear form of these discrete equations are insufficient; thus, it is difficult to construct multiperiodic wave solutions, even for two-periodic wave solution.

In this paper, we will mainly consider 3 + 1-dimensional potential-YTSF equation and discrete KP equation. First, we use a linear superposition principle to generate N-wave solutions of the former then use the above discussing method to construct quasiperiodic or periodic wave solutions of these two equations. In an appropriate limiting procedure, the soliton solutions are also obtained from the quasiperiodic solutions.
2. (3+1)-Dimensional Potential-YTSF Equation

(3 + 1)-Dimensional potential-YTSF equation, first introduced by Yu et al. [16], may be written as

\[-4u_{xx} + u_{xxxx} + 4u_{x}u_{xx} + 2u_{x}u_{zz} + 3u_{yy} = 0.\]  \hspace{1cm} (1)

The exact solitary-wave and periodic solutions have been addressed by means of the auto-Bäcklund transformation [17], the generalized projective Riccati equation method [18], the extended homoclinic test technique [19], and so on. Using the dependent variable transformation

\[\zeta = x + dz, \hspace{1cm} u = 2(\ln f)_{\zeta},\]  \hspace{1cm} (2)

we transform (1) to the bilinear form

\[-4D_{\zeta}D_{t} + dD_{\zeta}^{2} + 3D_{t}^{2} + c\] \[\times f \cdot f = 0,\]  \hspace{1cm} (3)

where \(d\) is an arbitrary positive constant and Hirota bilinear operators \(D_{\zeta}, D_{t},\) and \(D_{i}\) are defined by

\[D_{\zeta}^{m}D_{t}^{n} \equiv f (\zeta , t) \cdot g (\zeta , t) \]
\[= \left( \partial_{\zeta} - \partial_{\zeta}' \right)^{m} \left( \partial_{t} - \partial_{t}' \right)^{n} |_{\zeta = \xi, t = z},\] \hspace{3cm} (4)

which have a nice property when acting on exponential functions

\[D_{\zeta}^{m}D_{t}^{n} e^{n_{z}} \cdot e^{m_{t}} = (k_{1} - k_{2})^{m} (w_{1} - w_{2})^{n} \cdot e^{n_{z} + m_{t}},\] \hspace{3cm} (5)

with \(n_{j} = k_{j} \xi + l_{j} t + w_{j} t, j = 1, 2.\)

2.1.\textit{N} Exponential Wave Solutions. Let us consider the special case \(c = 0\) in (3) and introduce \(\textit{N}\)-wave testing function

\[f = \sum_{j=1}^{N} e_{j} f_{j} = \sum_{j=1}^{N} e^{e_{j}(k_{j} \xi + l_{j} t + w_{j} t)}, \hspace{1cm} 1 \leq j \leq N,\] \hspace{3cm} (6)

where \(e_{j}, k_{j}, l_{j},\) and \(w_{j}\) are arbitrary constants. Substituting (6) into (3) and using (5) give

\[\sum_{j=1}^{N} e_{j} f_{j} \cdot f_{j} = 0.\] \hspace{3cm} (7)

If the following condition

\[-4(k_{j} - k_{j}) (w_{j} - w_{j}) + d(k_{j} - k_{j})^{4} + 3(l_{j} - l_{j})^{2},\] \hspace{3cm} (8)

is satisfied, then any linear combination of the \(\textit{N}\) exponential wave solutions \(e^{n_{j}}, 1 \leq j \leq \textit{N}\) solves (3). By inspection, a solution to (8) is

\[w_{j} = dk_{j}^{2}; \hspace{1cm} l_{j} = \pm \sqrt{d}k_{j}^{2}, \hspace{1cm} 1 \leq j \leq \textit{N}.\] \hspace{3cm} (9)

Therefore, (1) has the following \(\textit{N}\)-wave solution

\[u = 2(\ln f)_{\zeta},\] \hspace{3cm} (10)

\[f = \sum_{j=1}^{N} e_{j} f_{j} = \sum_{j=1}^{N} e^{e_{j}(k_{j} \xi + l_{j} t + w_{j} t)} e^{d(k_{j} \xi + l_{j} t + w_{j} t)^{2}},\] \hspace{3cm} (11)

where \(e_{j}, k_{j}\) are arbitrary constants. Especially assume that \(e_{1} = e_{2} = e_{3} = 1, k_{1} = -k_{2},\) and \(k_{3} = 0\) in (10); then, we get

\[u = 2(\ln f)_{\zeta} = 2k_{j} \sinh \left( k_{j} (x + dz) + dk_{j} t \right) e^{d(k_{j} \xi + l_{j} t + w_{j} t)^{2}},\] \hspace{3cm} (11)

2.2. Quasiperiodic Solutions. The Riemann theta functions of genus one [20] are defined by

\[\Theta_{1} (\xi, \tau) = - i \sum_{m=\infty}^{\infty} (-1)^{m} e^{m \xi (2m+1) + m \tau (m+(1/2))^{2}},\] \hspace{3cm} (12)

\[\Theta_{2} (\xi, \tau) = \sum_{m=\infty}^{\infty} e^{m \xi (2m+1) + m \tau (m+(1/2))^{2}},\] \hspace{3cm} (13)

\[\Theta_{3} (\xi, \tau) = \sum_{m=\infty}^{\infty} e^{2m \xi \tau + m \tau^{2}},\] \hspace{3cm} (14)

\[\Theta_{4} (\xi, \tau) = \sum_{m=\infty}^{\infty} (-1)^{m} e^{2m \xi \tau + m \tau^{2}},\] \hspace{3cm} (15)

respectively, where \(\xi = k_{j} \xi + l_{j} t + w_{j} t.\) Letting \(\Theta_{i} (x) = \Theta_{i}(x, \tau)\) \((k = 1, 2, 3, 4)\) and using the identities

\[\Theta_{3} (x + y) \Theta_{3} (x - y) \Theta_{2}^{2} (0)\]
\[= \Theta_{3}^{2} (x) \Theta_{3}^{2} (y) + \Theta_{3}^{2} (x) \Theta_{3}^{2} (y),\] \hspace{3cm} (16)

\[\Theta_{4} (x + y) \Theta_{4} (x - y) \Theta_{2}^{2} (0)\]
\[= \Theta_{4}^{2} (x) \Theta_{4}^{2} (y) + \Theta_{4}^{2} (x) \Theta_{4}^{2} (y),\] \hspace{3cm} (17)

we can obtain the Hirota derivatives of \(\Theta_{i}(x), \Theta_{i}(x):\)

\[D_{x}^{2} \Theta_{3} (x) \cdot \Theta_{3} (x) = \delta_{x}^{2} \Theta_{3} (x + y) \Theta_{3} (x - y) |_{y=0}\]
\[= b_{3} \Theta_{3}^{2} (x) + b_{2} \Theta_{3}^{2} (x),\] \hspace{3cm} (18)

\[D_{x}^{2} \Theta_{3} (x) \cdot \Theta_{3} (x) = \delta_{x}^{2} \Theta_{3} (x + y) \Theta_{3} (x - y) |_{y=0}\]
\[= c_{3} \Theta_{3}^{2} (x) + c_{2} \Theta_{3}^{2} (x),\] \hspace{3cm} (19)

\[D_{x}^{2} \Theta_{4} (x) \cdot \Theta_{4} (x) = \delta_{x}^{2} \Theta_{4} (x + y) \Theta_{4} (x - y) |_{y=0}\]
\[= b_{2} \Theta_{4}^{2} (x) - b_{1} \Theta_{3}^{2} (x),\] \hspace{3cm} (20)

\[D_{x}^{2} \Theta_{4} (x) \cdot \Theta_{4} (x) = \delta_{x}^{2} \Theta_{3} (x + y) \Theta_{3} (x - y) |_{y=0}\]
\[= c_{2} \Theta_{4}^{2} (x) - c_{1} \Theta_{3}^{2} (x),\] \hspace{3cm} (21)
where
\[
\begin{align*}
b_1 &= 2\Theta_3'(0)\Theta_2^2(0), & b_2 &= 2\Theta_4''(0)\Theta_2(0), \\
b_3 &= 2\left(\Theta_3''(0)\Theta_4(0) + \Theta_4''(0)\Theta_3(0)\right), & b_4 &= 2\Theta_3(0)\Theta_2(0), \\
c_1 &= 2b_1(b_2 + b_3), & c_2 &= \frac{3}{2}b_2^2 + b_4.
\end{align*}
\] (15)

Next, we will calculate analytically the quasiperiodic solutions using the Hirota derivatives in (14).

**Case 1.** In the bilinear equation (3), we suppose \( f(x, y, z, t) \) to be
\[
f(x, y, z, t) = \Theta_3(\xi), \quad \xi = k_1\xi + l_1y + w_1t,
\]
where \( k_1, l_1, \) and \( w_1 \) are arbitrary constants. Substituting (16) into (3) and setting the coefficients of the terms \( \Theta_3^2(\xi), \Theta_3^4(\xi) \) to be zero, we obtain a system of algebraic equations
\[
\begin{align*}
-4k_1w_1 + 3l_1^2 b_2 + d k_1^4 c_2 + c &= 0, \\
4k_1w_1 - 3l_1^2 b_1 - d k_1^4 c_1 &= 0.
\end{align*}
\] (17)

Solving (17), we find
\[
\begin{align*}
w_1 &= \frac{3l_1^2 b_1 + d k_1^4 c_1}{4k_1 b_1}, \\
c &= -\left(3l_1^2 b_2 + dk_1^4 c_1\right) + \frac{b_2}{b_1}\left(3l_1^2 b_1 + d k_1^4 c_1\right),
\end{align*}
\] (18)

where \( b_1, b_2, \) and \( c_1, c_2 \) are given by (15). We have thus constructed a kind of quasiperiodic solution for (1)
\[
u = 2\ln(\Theta_3(k_1\xi + l_1z + w_1t)).
\] (19)

In the following, we further analyze the asymptotic property of (19).

**Proposition 1.** If the vector \((w_2, c)^T\) is given by (18) and supposing \(\xi' = 2\pi i\xi + n_1r, k' = 2\pi i k, \) and \( 1\text{Im}r \to \infty, \) then one has
\[
f = \Theta_3(\xi) = 1 + e^{2\pi i k} + e^{-2\pi i k}
\]
\[
+ e^{4\pi i k} + e^{-4\pi i k} + \cdots
\]
\[
= 1 + e^{i\xi'} + e^{2\pi i k}e^{-i\xi'} + e^{2\pi i k} + \cdots
\]
\[
= 1 + e^{i\xi'}, \quad \text{as} \ 1\text{Im}r \to \infty.
\] (20)

From (2), one gets the solution of (1) as follows:
\[
u = 2(\ln f)_\xi' \to \frac{4\pi i e^{i\xi'}}{1 + e^{i\xi'}} = k' \sec \left(\frac{\xi'}{2}\right).
\] (21)

**Case 2.** Assume \( f(x, y, z, t) \) in (3) to be
\[
f(x, y, z, t) = \Theta_4(\xi), \quad \xi = k_2\xi + l_2y + w_2t,
\]
where \( k_1, l_1, \) and \( w_1 \) are arbitrary constants. Setting the coefficients of the terms \( \Theta_4^2(\xi), \Theta_4^4(\xi) \) to be zero, we have
\[
\begin{align*}
(4k_2w_2 - 3l_2^2) b_2 - d k_2^4 c_1 &= 0, \\
(-4k_2w_2 + 3l_2^2) b_2 + d k_2^4 c_2 + c &= 0.
\end{align*}
\] (23)

Solving (23) yields
\[
\begin{align*}
w_2 &= \frac{3l_2^2 b_2 + d k_2^4 c_1}{4k_2 b_1}, \\
c &= -(3l_2^2 b_2 + d k_2^4 c_1) + \frac{b_2}{b_1}\left(3l_2^2 b_1 + d k_2^4 c_1\right),
\end{align*}
\] (24)

where \( b_1, b_2, \) and \( c_1, c_2 \) are given by (15). Thus, the second kind of quasiperiodic solution of (1) is constructed as follows:
\[
u = 2\ln(\Theta_4(k_2\xi + l_2z + w_2t))_\xi'.
\] (25)

**Proposition 2.** If the vector \((w_2, c)^T\) is given by (24) and supposing \(\xi' = 2\pi i\xi + n_1r, k' = 2\pi i k, \) and \( 1\text{Im}r \to \infty, \) then one has
\[
f = \Theta_4(\xi) = 1 - e^{-2\pi i k}e^{2\pi i k}
\]
\[
+ e^{2\pi i k} + e^{-2\pi i k} + \cdots
\]
\[
= 1 - e^{-i\xi'} + e^{2\pi i k} - e^{i\xi'} + \cdots
\]
\[
= 1 - e^{i\xi'}, \quad \text{as} \ 1\text{Im}r \to \infty.
\] (26)

Using the variable transformation (2), one gets the solution of (1) as follows:
\[
u = 2(\ln f)_\xi' \to \frac{4k\pi i e^{i\xi'}}{1 - e^{i\xi'}} = -k' \sec \left(\frac{\xi'}{2}\right).
\] (27)

### 3. Discrete KP Equation

The discrete analogue of KP equation [21, 22] (or a two-dimensional analogue of the discrete KdV equation) is
\[
\begin{align*}
\nabla_1 u + v &= \chi V_{x} E_{yj} u, \\
\nabla_1 u + v &= \frac{E_{yj} - E_{y} E_{xj} v}{\delta y \left(1 + E_{yj} u\right)},
\end{align*}
\] (28)

where \( u \) and \( v \) are functions of \( x, y, \) and \( t, \chi \) is a constant, \( \nabla \) and \( E \) are the difference and shift operators defined by
\[
\begin{align*}
\nabla_x f(z) &= \frac{1}{\delta z} \left[ f\left(z + \frac{\delta z}{2}\right) - f\left(z - \frac{\delta z}{2}\right)\right], \\
E_x f(z) &= f\left(z \pm \frac{\delta z}{2}\right).
\end{align*}
\] (29)
In fact, using the dependent variable transformation

\[ n = a \left( \frac{x}{\delta x} + \frac{y}{\delta y} \right), \]
\[ l = b \left( \frac{y}{\delta y} + \frac{t}{\delta t} \right), \]
\[ m = -c \left( \frac{x}{\delta x} + \frac{t}{\delta t} \right), \]

and substituting (30) into (28), we have the bilinear form of discrete KP equation as follows:

\[ a(b - c) \zeta_{mnab}^{m+c} + b(c - a) \zeta_{mnab}^{m-c} + c(a - b) \zeta_{mnab}^{m+c} = 0, \tag{31} \]

where \( a, b, \) and \( c \) are the difference intervals for independent variables \( n, l, \) and \( m, \) respectively. Some operator solutions of (31) have been addressed by the transformation groups methods \([23, 24]\). This famous three-dimensional difference equation is interesting and important because it is emerging in the context of quantum integrable systems \([25, 26]\) as the model-independent functional relations for eigenvalues of quantum transfer matrices. Moreover, some typical soliton equations can be obtained by performing a scaling continuum limit for appropriate combinations of parameters and variables, such as continuous Korteweg-de Vries (KdV) equation, KP equation, two-dimensional Toda lattice (2DTL) equation, Sine-Gordon (SG) equation, and Benjamin-Ono equation.

3.1. The Solutions in Terms of One-Theta Function. Suppose that

\[ \Theta_i(\xi, \tau) = \Theta_i(\xi - \alpha, \tau) \]

where

\[ \xi = k_1 n + k_2 l + k_3 m + \frac{k_1 a + k_2 b + k_3 c}{2} \tag{33} \]

\( k_1, k_2, \) and \( k_3 \) are arbitrary constants, and \( \Theta_i(\xi, \tau) \) is defined by (12). Similarly, we can obtain

\[ \zeta_{mnab}^{m+c} = \Theta_i(\xi + \alpha, \tau), \]
\[ \zeta_{mnab}^{m-c} = \Theta_i(\xi - \alpha, \tau), \]
\[ \zeta_{mnab}^{m-c} = \Theta_i(\xi - \beta, \tau), \]
\[ \zeta_{mnab}^{m+c} = \Theta_i(\xi + \beta, \tau), \tag{34} \]
\[ \zeta_{mnab}^{m+c} = \Theta_i(\xi - \gamma, \tau), \]
\[ \zeta_{mnab}^{m+c} = \Theta_i(\xi + \gamma, \tau), \]

with

\[ \alpha = \frac{k_1 b + k_3 c - k_1 a}{2}, \]
\[ \beta = \frac{k_1 a + k_2 c - k_2 b}{2}, \]
\[ \gamma = \frac{k_1 a + k_2 b - k_3 c}{2}. \tag{35} \]

Substituting (34) into (31) and using the following identities of the theta functions

\[ \Theta_1(x + y) \Theta_1(x - y) = \Theta_2^2(0) \left[ \Theta_1^2(x) \Theta_2^2(y) - \Theta_2^2(x) \Theta_1^2(y) \right], \]
\[ \Theta_2(x + y) \Theta_2(x - y) = \Theta_2^2(0) \left[ \Theta_1^2(x) \Theta_2^2(y) - \Theta_2^2(x) \Theta_1^2(y) \right], \]
\[ \Theta_3(x + y) \Theta_3(x - y) = \Theta_2^2(0) \left[ \Theta_1^2(x) \Theta_3^2(y) + \Theta_3^2(x) \Theta_1^2(y) \right], \]
\[ \Theta_4(x + y) \Theta_4(x - y) = \Theta_2^2(0) \left[ \Theta_1^2(x) \Theta_4^2(y) + \Theta_4^2(x) \Theta_1^2(y) \right], \tag{36} \]

yield

\[ a(b - c) \Theta_1^2(\alpha) + b(c - a) \Theta_1^2(\beta) + c(a - b) \Theta_1^2(y) = 0, \]

when \( i = 1, 2; \)

\[ a(b - c) \Theta_2^2(\alpha) + b(c - a) \Theta_2^2(\beta) + c(a - b) \Theta_2^2(y) = 0, \]

when \( i = 3, 4. \tag{37} \]

Here, we use \( \Theta_i(\xi) = \Theta_i(\xi, \tau) \) for simplicity. From (37), we can find that if \( \alpha = \beta = \gamma, \) that is, \( k_1 a = k_2 b = k_3 c, \) which follows from (35), then (31) holds. In virtue of the variable
transformation (30), the solution of (28) is expressed by one-theta function as follows:

\[
u = \left( \Theta_1 \left[ k_1 \left( n + \frac{a}{b} l + \frac{a}{c} m \right) \right] \times \Theta_1 \left[ k_1 \left( n + \frac{a}{b} l + \frac{a}{c} m \right) + 2k_1a \right] \right) \times \left( \Theta_1 \left[ k_1 \left( n + \frac{a}{b} l + \frac{a}{c} m \right) + 3k_1a \right] \times \Theta_1 \left[ k_1 \left( n + \frac{a}{b} l + \frac{a}{c} m \right) + k_1a \right] \right) \times \left( \Theta_1 \left[ k_1 \left( n + \frac{a}{b} l + \frac{a}{c} m \right) + 2k_1a \right] \times \Theta_1 \left[ k_1 \left( n + \frac{a}{b} l + \frac{a}{c} m \right) + k_1a \right] \right) = 0
\]

Remark 3 (see [27]). If \( \xi_m = \Theta_3 (\xi - (3k_1a/2), \tau) \) is a solution of (31), then \( R_0 ((n/a) + (l/b) + (m/c)) R_1(n/a) R_2(l/b) R_3(m/c) \Theta_3 (\xi - (3k_1a/2), \tau) \) is a solution too, where \( R_i, (i = 0, 1, 2, 3) \), are arbitrary functions.

Proposition 5. The Riemann theta function \( \Theta_3 (\xi, \tau) \) defined by (12) has the periodic properties

\[
\Theta_3 (\xi + 1 + \tau, \tau) = \exp (-2im\xi - i\pi \tau) \Theta_3 (\xi, \tau)
\]

So, the meromorphic functions \( F(\xi, \tau) \) defined by

(I) \( F(\xi, \tau) = \frac{\Theta_3 (\xi, \tau)}{\Theta_3 (\xi + h, \tau)} \), \( \forall h \xi \in C \)

(II) \( F(\xi, \tau) = \frac{\Theta_3 (\xi, \tau)}{\Theta_3 (\xi + 2h, \tau)} \), \( \forall h \xi \in C \)

are all double periodic functions with two fundamental periods 1 and \( \tau \). Because the other three Riemann theta functions in (12) are the deformations of \( \Theta_3 (\xi, \tau) \), they can be proved to be periodic in a similar way.

Proof. By using definition \( \Theta_3 (\xi, \tau) \) in (12), it is easy to see that

\[
\Theta_3 (\xi + 1 + \tau, \tau) = \sum_{m=\infty}^{\infty} e^{2mni(\xi + 1 + \tau + m\pi \tau)}
\]

\[
= e^{-2\pi i \tau} \Theta_3 (\xi, \tau)
\]

(42)

\[
\Theta_3 (\xi + h + 1 + \tau, \tau) = \sum_{m=\infty}^{\infty} e^{2mni(\xi + h + 1 + \tau + m\pi \tau)}
\]

\[
= e^{-2\pi i (\xi + h)} \Theta_3 (\xi + h, \tau)
\]

Therefore, in both (I) and (II) cases, it holds that

\[
F(\xi + 1 + \tau, \tau) = F(\xi, \tau), \xi \in C
\]

That is to say, (38) is periodic wave solution of (28).

3.2. The Solutions in Terms of Two-Theta Function. In order to look for its solutions in terms of two-theta functions, we suppose

\[
\xi_{m+c(1/2)} = \Theta_3 (\xi, \tau_1) \Theta_3 (\xi, \tau_2)
\]

\[
= \Theta_3 \left( k_1 n + k_2 l + k_3 m + \frac{k_1 a + k_2 b + k_3 c}{2}, \tau_1 \right)
\]

\[
\times \Theta_3 \left( k_1 n + k_2 l + k_3 m + \frac{k_1 a + k_2 b + k_3 c}{2}, \tau_2 \right),
\]

\( \forall i, j = 1, 2, 3, 4 \).

Therefore,

\[
\xi_{m+\alpha J}^{\text{nm}} = \Theta_3 (\xi - \alpha, \tau_1) \Theta_3 (\xi - \alpha, \tau_2)
\]

\[
\xi_{n+\beta J}^{\text{nm}} = \Theta_3 (\xi + \beta, \tau_1) \Theta_3 (\xi + \beta, \tau_2)
\]

\[
\xi_{n+\gamma J}^{\text{nm}} = \Theta_3 (\xi - \gamma, \tau_1) \Theta_3 (\xi - \gamma, \tau_2)
\]

\[
\xi_{n+\delta J}^{\text{nm}} = \Theta_3 (\xi + \delta, \tau_1) \Theta_3 (\xi + \delta, \tau_2)
\]

where \( \alpha, \beta, \gamma, \delta \) are the same as in (35).

Case 1. If \( i = 1, j = 2 \), we substitute (45) into (31) to get

\[
a(b - c) \Theta_1 (\xi - \alpha, \tau_1) \Theta_2 (\xi - \alpha, \tau_2)
\]

\[
\times \Theta_1 (\xi + \alpha, \tau_1) \Theta_2 (\xi + \alpha, \tau_2) + b(c - a)
\]

\[
\times \Theta_1 (\xi - \beta, \tau_1) \Theta_2 (\xi - \beta, \tau_2) \Theta_3 (\xi + \beta, \tau_1)
\]

\[
\times \Theta_2 (\xi + \beta, \tau_2) + c(a - b) \Theta_1 (\xi - \gamma, \tau_1)
\]

\[
\times \Theta_2 (\xi - \gamma, \tau_2) \Theta_3 (\xi + \gamma, \tau_1) \Theta_3 (\xi + \gamma, \tau_2) = 0.
\]
By using the first two identities of the theta functions (36), the above equation is equivalent to

\[
\Theta_1^2(\xi, \tau) \Theta_2^2(\xi, \tau) \left[ \epsilon_1 \Theta_2^2(\alpha, \tau) \Theta_2^2(\alpha, \tau) \right]
+ \epsilon_2 \Theta_2^2(\beta, \tau) \Theta_2^2(\beta, \tau)
+ \epsilon_3 \Theta_2^2(\gamma, \tau) \Theta_2^2(\gamma, \tau) \right]
\]

\[
- \Theta_1^2(\xi, \tau) \Theta_2^2(\xi, \tau) \left[ \epsilon_1 \Theta_2^2(\alpha, \tau) \Theta_2^2(\alpha, \tau) \right]
+ \epsilon_2 \Theta_2^2(\beta, \tau) \Theta_2^2(\beta, \tau)
+ \epsilon_3 \Theta_2^2(\gamma, \tau) \Theta_2^2(\gamma, \tau) \right]
\]

\[
+ \Theta_2^2(\xi, \tau) \Theta_2^2(\xi, \tau) \left[ \epsilon_1 \Theta_2^2(\alpha, \tau) \Theta_2^2(\alpha, \tau) \right]
+ \epsilon_2 \Theta_2^2(\beta, \tau) \Theta_2^2(\beta, \tau)
+ \epsilon_3 \Theta_2^2(\gamma, \tau) \Theta_2^2(\gamma, \tau) \right] = 0.
\]

(47)

Therefore,

\[
\epsilon_1 \Theta_2^2(\alpha, \tau) \Theta_2^2(\alpha, \tau) + \epsilon_2 \Theta_2^2(\beta, \tau) \Theta_2^2(\beta, \tau)
+ \epsilon_3 \Theta_2^2(\gamma, \tau) \Theta_2^2(\gamma, \tau) = 0,
\]

(48)

Here, \(\epsilon_1 = a(b - c), \epsilon_2 = b(c - a), \) and \(\epsilon_3 = c(a - b).\) To get special solutions of (48), we can assume that \(\alpha = \beta = \gamma;\) that is, \(k_1 a = k_2 b = k_3 c.\) From the variable transformation (30), the solution of (28) in terms of two-theta functions are

\[
u = \left( \Theta_1 \left[ k_1 \left( n + \frac{a l + a m}{b c} \right), \tau_1 \right] \times \Theta_2 \left[ k_1 \left( n + \frac{a l + a m}{b c} \right), \tau_2 \right] \right)
\]

\[
\times \Theta_1 \left[ k_1 \left( n + \frac{a l + a m}{b c} \right) + 2k_1 a, \tau_1 \right]
\]

\[
\times \Theta_2 \left[ k_1 \left( n + \frac{a l + a m}{b c} \right) + 2k_1 a, \tau_2 \right).
\]

(49)

Case 2. If \(i = 2, j = 3\) and substituting (45) into (31), then we are led to

\[
a(b - c) \Theta_2(\xi - \alpha, \tau_1) \Theta_3(\xi - \alpha, \tau_2) \Theta_2(\xi + \alpha, \tau_1)
\]

\[
\times \Theta_1 \left[ k_1 \left( n + \frac{a l + a m}{b c} \right), \tau_1 \right]
\]

\[
\times \Theta_2 \left[ k_1 \left( n + \frac{a l + a m}{b c} \right), \tau_2 \right]
\]

\[
\times \Theta_1 \left[ k_1 \left( n + \frac{a l + a m}{b c} + 3k_1 a, \tau_1 \right) \right]
\]

\[
\times \Theta_2 \left[ k_1 \left( n + \frac{a l + a m}{b c} + 3k_1 a, \tau_2 \right) \right]
\]

\[
\times \left( \Theta_1^2\left[ k_1 \left( n + \frac{a l}{b} + \frac{a m}{c} \right) + k_1 a, \tau_1 \right] \right)^{-1} - 1,
\]

(50)

From the identities of the theta functions (36), the last equation is changed into

\[
\Theta_1^2(\xi, \tau_1) \Theta_2^2(\xi, \tau_2) \left[ \epsilon_1 \Theta_2^2(\alpha, \tau_1) \Theta_2^2(\alpha, \tau_2) \right]
+ \epsilon_2 \Theta_2^2(\beta, \tau_1) \Theta_2^2(\beta, \tau_2)
+ \epsilon_3 \Theta_2^2(\gamma, \tau_1) \Theta_2^2(\gamma, \tau_2) \right] = 0.
\]

(51)

Here, \(\epsilon_1 = a(b - c), \epsilon_2 = b(c - a), \) and \(\epsilon_3 = c(a - b).\)
\[
- \Theta^2_1(\xi, \tau_1) \Theta^2_1(\xi, \tau_2) \left[ e_1 \Theta^2_1(\alpha, \tau_1) \Theta^2_1(\alpha, \tau_2) + e_2 \Theta^2_1(\beta, \tau_1) \Theta^2_1(\beta, \tau_2) + e_3 \Theta^2_1(\gamma, \tau_1) \Theta^2_1(\gamma, \tau_2) \right] = 0.
\]
\[
\text{(51)}
\]

Therefore,
\[
\begin{align*}
&\frac{1}{3} \Theta^2_1(\alpha, \tau_1) \Theta^2_1(\alpha, \tau_2) + e_2 \Theta^2_1(\beta, \tau_1) \Theta^2_1(\beta, \tau_2) + e_3 \Theta^2_1(\gamma, \tau_1) \Theta^2_1(\gamma, \tau_2) = 0, \\
&\frac{1}{3} \Theta^2_1(\gamma, \tau_1) \Theta^2_1(\gamma, \tau_2) = \frac{1}{3} (\Theta^2_1(\alpha, \tau_1) + \Theta^2_1(\beta, \tau_1)).
\end{align*}
\]
\[
\frac{1}{3} \Theta^2_1(\gamma, \tau_1) \Theta^2_1(\gamma, \tau_2) = \Theta^2_1(\alpha, \tau_1) + \Theta^2_1(\beta, \tau_1).
\]
\[
\text{(52)}
\]

with \(e_1 = a(b - c), e_2 = b(c - a), \) and \(e_3 = c(a - b).\) To get the special solutions of (52), we can assume that \(\alpha = \beta = \gamma;\) that is, \(k_1 a = k_2 b = k_3 c.\) From the variable transformation (30), the solution of (28) in terms of two-theta functions are
\[
\begin{align*}
u = 1 - &\frac{1}{2} \left[ \Theta^2_2 \left( k_1 \left( n + \frac{a}{b} l + \frac{a}{c} m \right), \tau_1 \right) \times \Theta_3 \left( k_1 \left( n + \frac{a}{b} l + \frac{a}{c} m \right), \tau_2 \right) \\
&\times \Theta_2 \left( k_1 \left( n + \frac{a}{b} l + \frac{a}{c} m \right) + 3k_1 a, \tau_1 \right) \\
&\times \Theta_3 \left( k_1 \left( n + \frac{a}{b} l + \frac{a}{c} m \right) + 3k_1 a, \tau_2 \right) \right)^{-1},
\end{align*}
\]
\[
\text{(53)}
\]

\section{Conclusion}

In this paper, based on the Riemann theta functions, a lucid and straightforward generalization of the Hirota-Riemann method is presented to explicitly construct some kinds of quasi-periodic wave solutions for (3 + 1)-dimensional potential-YTSF equation and discrete KP equation. This method is also suitable for other more general nonlinear evolution equations in mathematical physics. Moreover, for the (3+1)-dimensional potential-YTSF equation, we not only use linear superposition principle to generate N-wave solutions but also analyze the quasi-periodic wave solutions that tend to the soliton solutions under a small amplitude limit.

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