Convex geodesic bicombings and hyperbolicity

Dominic Descombes & Urs Lang

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Abstract

A geodesic bicombing on a metric space selects for every pair of points a geodesic connecting them. We prove existence and uniqueness results for geodesic bicombings satisfying different convexity conditions. In combination with recent work by the second author on injective hulls, this shows that every word hyperbolic group acts geometrically on a proper, finite dimensional space \( X \) with a unique (hence equivariant) convex geodesic bicombing of the strongest type. Furthermore, the Gromov boundary of \( X \) is a \( \mathbb{Z} \)-set in the closure of \( X \), and the latter is a metrizable absolute retract, in analogy with the Bestvina–Mess theorem on the Rips complex.

1 Introduction

By a geodesic bicombing \( \sigma \) on a metric space \((X,d)\) we mean a map

\[
\sigma: X \times X \times [0,1] \rightarrow X
\]

that selects for every pair \((x,y) \in X \times X\) a constant speed geodesic \( \sigma_{xy} := \sigma(x,y,\cdot) \) from \( x \) to \( y \) (that is, \( d(\sigma_{xy}(t),\sigma_{xy}(t')) = |t-t'|d(x,y) \) for all \( t,t' \in [0,1] \), and \( \sigma_{xy}(0) = x, \sigma_{xy}(1) = y \)). We are interested in geodesic bicombings satisfying one of the following two conditions, each of which implies that \( \sigma \) is continuous and, hence, \( X \) is contractible. We call \( \sigma \) convex if

\[
\text{the function } t \mapsto d(\sigma_{xy}(t),\sigma_{x'y'}(t)) \text{ is convex on } [0,1] \tag{1.1}
\]

for all \( x,y,x',y' \in X \), and we say that \( \sigma \) is conical if

\[
d(\sigma_{xy}(t),\sigma_{x'y'}(t)) \leq (1-t)d(x,x') + td(y,y') \text{ for all } t \in [0,1] \tag{1.2}
\]

and \( x,y,x',y' \in X \). Obviously every convex geodesic bicombing is conical, but the reverse implication does not hold in general (see Example 2.2). For this, in order to pass condition (1.2) to subsegments, one would need to know in addition that \( \sigma \) is consistent in the sense that

\[
\sigma_{pq}(\lambda) = \sigma_{xy}((1-\lambda)s + \lambda t) \tag{1.3}
\]
whenever \(x, y \in X\), \(0 \leq s \leq t \leq 1\), \(p := \sigma_{xy}(s)\), \(q := \sigma_{xy}(t)\), and \(\lambda \in [0, 1]\). Thus, every conical and consistent geodesic bicombing is convex. Furthermore, we will say that \(\sigma\) is reversible if
\[
\sigma_{xy}(t) = \sigma_{yx}(1 - t) \quad \text{for all } t \in [0, 1]
\] (1.4)
and \(x, y \in X\). This property is not imposed here but will be obtained at no extra cost later. Basic examples of convex geodesic bicombings are given by the linear geodesics \(\sigma_{xy}(t) := (1 - t)x + ty\) in a linearly convex subset \(X\) of a normed space or by the unique geodesics \(\sigma_{xy} : [0, 1] \to X\) in a CAT(0) space [2, 4] or a Busemann space [11, 20] (where \(t \mapsto d(\sigma(t), \tau(t))\) is convex for every pair of geodesics \(\sigma, \tau : [0, 1] \to X\)). An additional source of conical geodesic bicombings is the fact that this weaker notion behaves well under 1-Lipschitz retractions (see Lemma 2.1). Consistent and reversible geodesic bicombings have also been employed in [13, 10].

In view of the primary examples, the existence of a convex or conical geodesic bicombing on a metric space may be regarded as a weak (but non-coarse) global nonpositive curvature condition. One thus arrives at the following hierarchy of properties (A) \(\Rightarrow\) (B) \(\Rightarrow\) (C) \(\Rightarrow\) (D) \(\Rightarrow\) (E) for a geodesic metric space \(X\):

(A) \(X\) is a CAT(0) space;
(B) \(X\) is a Busemann space;
(C) \(X\) admits a convex and consistent geodesic bicombing;
(D) \(X\) admits a convex geodesic bicombing;
(E) \(X\) admits a conical geodesic bicombing.

Clearly, if \(X\) is uniquely geodesic, then (E) \(\Rightarrow\) (B). When \(X\) is a normed real vector space, (A) holds if and only if the norm is induced by an inner product ([4, Proposition II.1.14]), (B) holds if and only if the norm is strictly convex ([20, Proposition 8.1.6]), and (C) is always satisfied. In the general case, (C) is stable under limit operations, whereas (B) is not (compare Sect. 10 in [17]). It is unclear whether (E) \(\Rightarrow\) (D) and (D) \(\Rightarrow\) (C) without further conditions. One of the purposes of this paper is to establish these implications under suitable assumptions, and to address questions of uniqueness. Our first result refers to (E) and (D).

1.1 Theorem. Let \(X\) be a proper metric space with a conical geodesic bicombing. Then \(X\) also admits a convex geodesic bicombing.

The idea of the proof is to resort to a discretized convexity condition and then to gradually decrease the parameter of discreteness by the “cat’s cradle” construction from [1]. The passage from (D) to (C) appears to be more subtle. We first observe that the linear segments \(t \mapsto (1 - t)x + ty\) in an arbitrary normed
space $X$ may be characterized as the curves $\gamma: [0, 1] \to X$ with the property that $t \mapsto d(z, \gamma(t))$ is convex on $[0, 1]$ for every $z \in X$ (see Theorem 3.3). We therefore term curves with this property straight (in a metric space $X$). Since the geodesics of a convex bicombing are necessarily straight, the above observation shows that normed spaces have no such bicombing other than the linear one. By contrast, there are instances of non-linear straight geodesics in compact convex subspaces of normed spaces as well as multiple convex geodesic bicombings in compact metric spaces (see Examples 3.4 and 3.5). Nevertheless, we prove a strong uniqueness property of straight curves (Proposition 4.3) in spaces satisfying a certain finite dimensionality assumption, introduced by Dress in [7] and explained further below. This gives the following result regarding items (D) and (C).

1.2 Theorem. Let $X$ be a metric space of finite combinatorial dimension in the sense of Dress, or with the property that every bounded subset has finite combinatorial dimension. Suppose that $X$ possesses a convex geodesic bicombing $\sigma$. Then $\sigma$ is consistent, reversible, and unique, that is, $\sigma$ is the only convex geodesic bicombing on $X$.

Our interest in Theorems 1.1 and 1.2 comes from the fact that property (E) holds in particular for all absolute 1-Lipschitz retracts $X$. (To see this, embed $X$ isometrically into $\ell_\infty(X)$ and retract the linear geodesics to $X$; compare again Lemma 2.1). These correspond to the injective objects in the category of metric spaces and 1-Lipschitz maps: $X$ is injective if for every isometric inclusion $A \subset B$ of metric spaces and every 1-Lipschitz map $f: A \to X$ there exists a 1-Lipschitz extension $\bar{f}: B \to X$ of $f$. Basic examples include the real line, all $\ell_\infty$ spaces, and all metric ($\mathbb{R}$-)trees. Furthermore, by a 50-year-old result of Isbell [14], every metric space $X$ possesses an essentially unique injective hull $E(X)$. This yields a compact metric space if $X$ is compact and a finite polyhedral complex with $\ell_\infty$ metrics on the cells in case $X$ is finite. Isbell’s explicit construction was rediscovered and further explored by Dress [7], who gave it the name tight span. The combinatorial dimension $\dim_{\text{comb}}(X)$ of a general metric space $X$ is the supremum of the dimensions of the polyhedral complexes $E(Y)$ for all finite subspaces $Y$ of $X$. In case $X$ is already injective, every such $E(Y)$ embeds isometrically into $X$, so $\dim_{\text{comb}}(X)$ is bounded by the supremum of the topological dimensions of compact subsets of $X$. Dress also gave a characterization of the condition $\dim_{\text{comb}} \leq n$ in terms of a $2(n + 1)$-point inequality. We restate his result in Theorem 4.1 and provide a streamlined proof in an appendix to this paper.

In [18], the second author proved that if $\Gamma$ is a Gromov hyperbolic group, endowed with the word metric with respect to some finite generating set, then the injective hull $E(\Gamma)$ is a proper, finite-dimensional polyhedral complex with finitely many isometry types of cells, isometric to polytopes in $\ell_\infty$ spaces, and $\Gamma$ acts properly and cocompactly on $E(\Gamma)$ by cellular isometries. Furthermore, after barycentric subdivision, the resulting simplicial $\Gamma$-complex is a model for the classifying space $E\Gamma$ for proper actions. Since $X = E(\Gamma)$ satisfies property (E),
Theorems 1.1 and 1.2 together now show that $E(\Gamma)$ possesses a convex geodesic bicombing that is consistent, reversible, and unique, hence equivariant with respect to the full isometry group of $E(\Gamma)$. (The existence of an equivariant conical geodesic bicombing on $E(\Gamma)$ was known before, see Proposition 3.8 in [18], but the proof of that fact did not give any indication on the consistency and uniqueness of the bicombing.) In particular, the following holds.

1.3 **Theorem.** Every word hyperbolic group $\Gamma$ acts properly and cocompactly by isometries on a proper, finite-dimensional metric space $X$ with a convex geodesic bicombing that is furthermore consistent, reversible, and unique, hence equivariant with respect to the isometry group of $X$.

In a last part of the paper, we discuss the asymptotic geometry of complete metric spaces $X$ with a convex and consistent geodesic bicombing $\sigma$. We define the geometric boundary $\partial_\sigma X$ in terms of geodesic rays consistent with $\sigma$, and we equip $\overline{X}_\sigma = X \cup \partial_\sigma X$ with a natural metrizable topology akin to the cone topology in the case of CAT(0) spaces. In view of Theorem 1.3 this unifies and generalizes the respective constructions for CAT(0) or Busemann spaces and for hyperbolic groups. By virtue of the bicombing one can then give a rather direct proof of the following result on $\overline{X}_\sigma$. Recall that a metrizable space is an absolute retract if it is a retract of every metrizable space containing it as a closed subspace.

1.4 **Theorem.** Let $X$ be a complete metric space with a convex and consistent geodesic bicombing $\sigma$. Then $\overline{X}_\sigma$ is contractible, locally contractible, and an absolute retract. Moreover, $\partial_\sigma X$ is a Z-set in $\overline{X}_\sigma$, that is, for every open set $U$ in $\overline{X}_\sigma$ the inclusion $U \setminus \partial_\sigma X \hookrightarrow U$ is a homotopy equivalence.

Note that we do not assume $X$ to be proper or finite dimensional. Bestvina and Mess [3] proved the analogous result for the Gromov closure $\overline{P(\Gamma)}$ of the (contractible) Rips complex of a hyperbolic group $\Gamma$. Theorem 1.3 and Theorem 1.4 together thus provide an alternative to their result, which has a number of important applications (see Corollaries 1.3 and 1.4 in [3]).

2 From conical to convex bicombings

In this section, we first discuss some simple properties and examples of conical geodesic bicombings, as defined in (1.2), then we prove Theorem 1.1.

2.1 **Lemma.** Let $\overline{X}$ be a metric space with a conical geodesic bicombing $\overline{\sigma}$. If $\pi: \overline{X} \to X$ is a 1-Lipschitz retraction onto some subspace $X$ of $\overline{X}$, then $\sigma := \pi \circ \overline{\sigma}|_{X \times X \times [0,1]}$ defines a conical geodesic bicombing on $X$.

**Proof.** Note that since $\pi$ is a 1-Lipschitz retraction, $\sigma$ is indeed a geodesic bicombing on $X$. Furthermore, since $\pi$ is 1-Lipschitz and $\overline{\sigma}$ is conical, we have

$$d(\sigma_{xy}(t), \sigma_{x'y'}(t)) \leq d(\overline{\sigma}_{xy}(t), \overline{\sigma}_{x'y'}(t)) \leq (1 - t) d(x, x') + t d(y, y')$$

for all $t \in [0,1]$ and $x, y, x', y' \in X$, so $\sigma$ is conical as well. 

\hfill \square
As mentioned earlier, a direct consequence of this lemma is that all injective metric spaces (or absolute 1-Lipschitz retracts) admit conical geodesic bicombings.

An equally simple application gives an example of a conical geodesic bicombing that is not convex.

2.2 Example. Consider the set $X$ of all $(u,v) \in \mathbb{R}^2$ with $|u| \leq 2$ and $b(u) := |u| - 1 \leq v \leq |b(u)|$, endowed with the metric induced by the $\ell_\infty$ norm on $\mathbb{R}^2$.

Note that this is a geodesic metric space. With respect to this metric, the vertical retraction $\pi$ from the triangle $\bar{X} := \{(u,v) : b(u) \leq v \leq 1\}$ onto $X$ that maps $(u,v)$ to $(u, \min\{v, |b(u)|\})$ is 1-Lipschitz. The linear geodesic bicombing $\bar{\sigma}$ on $\bar{X}$, defined by $\bar{\sigma}_{xy}(t) := (1 - t)x + ty$, is convex. By Lemma 2.1 $\sigma := \pi \circ \bar{\sigma}|_{\bar{X} \times \bar{X} \times [0,1]}$ defines a conical geodesic bicombing on $X$. For $x = (-2,1)$ and $y = (2,1)$, we have $\sigma_{xy}(1/4) = (-1,0)$, $\sigma_{xy}(3/4) = (1,0)$, and $\sigma_{xy}(1/2) = (0,1)$. Hence, for $z = (0,-1)$, the function $t \mapsto ||\sigma_{xy}(t) - \sigma_{z,1}(t)||_\infty = ||\sigma_{xy}(t) - z||_\infty$ is clearly not convex.

We now define a relaxed notion of convexity that will be useful for the proof of Theorem 1.1. We say that a geodesic bicombing $\sigma$ on a metric space $X$ is $1/n$-discretely convex if, for all $x, y, x', y' \in X$, the convexity condition

$$d(\sigma_{xy}(s), \sigma_{x'y'}(s)) \leq \frac{t - s}{t - r} d(\sigma_{xy}(r), \sigma_{x'y'}(r)) + \frac{s - r}{t - r} d(\sigma_{xy}(t), \sigma_{x'y'}(t))$$

holds whenever the three numbers $r < s < t$ belong to $[0,1] \cap (1/n)\mathbb{Z}$. To check this condition it clearly suffices to verify the “local” inequality

$$2d(\sigma_{xy}(s), \sigma_{x'y'}(s)) \leq d(\sigma_{xy}(s - 1/n), \sigma_{x'y'}(s - 1/n)) + d(\sigma_{xy}(s + 1/n), \sigma_{x'y'}(s + 1/n))$$

for all $s \in (0,1) \cap (1/n)\mathbb{Z}$. Note that every conical geodesic bicombing is $1/2$-discretely convex.

2.3 Proposition. Suppose that $X$ is a complete metric space with a geodesic bicombing $\sigma$ that is conical and $1/n$-discretely convex for some integer $n \geq 2$. Then $X$ also admits a geodesic bicombing that is conical and $1/(2n - 1)$-discretely convex.

Proof. Set $m := 2n - 1$. To construct the desired new bicombing $\tilde{\sigma}$, fix $x$ and $y$ and define the sequences $p_i$ and $q_i$ recursively as $q_0 := \sigma_{xy}(n/m)$ and

$$p_i := \sigma_{xq_{i-1}}(1 - 1/n), \quad q_i := \sigma_{pq_i}(1/n), \quad \text{for } i \geq 1.$$

Since $\sigma$ is conical, we get the inequalities

$$d(p_i, p_{i+1}) \leq (1 - 1/n) d(q_{i-1}, q_i),$$

$$d(q_i, q_{i+1}) \leq (1 - 1/n) d(p_i, p_{i+1}).$$
It follows that \( p_i \) and \( q_i \) are Cauchy sequences, so \( p_i \to p \) and \( q_i \to q \). Then \( \sigma_{xq_i} \to \sigma_{xq} \) and \( \sigma_{p,y} \to \sigma_{py} \) uniformly, again because \( \sigma \) is conical. Note that \( p = \sigma_{xq}(1-1/n) \) and \( q = \sigma_{py}(1/n) \); we can thus define \( \tilde{\sigma}_{xy}(s) \) for \( s \in [0,1] \cap (1/m)\mathbb{Z} \) so that

\[
\tilde{\sigma}_{xy}(s) = \begin{cases} 
\sigma_{xq}(m/n)s & \text{if } s \leq n/m, \\
\sigma_{py}(m/n)s - (n - 1)/n & \text{if } s \geq (n - 1)/m.
\end{cases}
\]  

(2.1)

To declare \( \tilde{\sigma}_{xy} \) on all of \([0,1] \), we connect any pair of consecutive points \( x' := \tilde{\sigma}_{xy}(s) \) and \( y' := \tilde{\sigma}_{xy}(s+1/m) \), where \( s \in [0,1] \cap (1/m)\mathbb{Z} \), by the geodesic \( t \mapsto \sigma_{x'y'}(m(t - s)) \) for \( t \in [s, s + 1/m] \).

Now if \( p', q' \) and \( \tilde{\sigma}_{x'y'} \) result from the same construction for two points \( x' \) and \( y' \), we want to show that for \( s \in (0,1) \cap (1/m)\mathbb{Z} \) we have

\[
2d(\tilde{\sigma}_{xy}(s), \tilde{\sigma}_{x'y'}(s)) \leq d(\tilde{\sigma}_{xy}(s - 1/m), \tilde{\sigma}_{x'y'}(s - 1/m)) + d(\tilde{\sigma}_{xy}(s + 1/m), \tilde{\sigma}_{x'y'}(s + 1/m)).
\]

In view of (2.1) this corresponds to the inequality

\[
2d(\tau(t), \tau'(t)) \leq d(\tau(t - 1/n), \tau'(t - 1/n)) + d(\tau(t + 1/n), \tau'(t + 1/n))
\]

where \( \tau = \sigma_{xq}, \tau' = \sigma_{x'q'}, t = (m/n)s \) if \( s \leq (n - 1)/m \) and \( \tau = \sigma_{py}, \tau' = \sigma_{y'p}', t = (m/n)s - (n - 1)/n \) if \( s \geq n/m \). However, these inequalities hold since \( \sigma \) is \( 1/n \)-discretely convex. This shows that \( \tilde{\sigma} \) is \( 1/m \)-discretely convex. Now it follows easily from the construction that \( \tilde{\sigma} \) is also conical.

\[ \square \]

From this result, we now obtain Theorem 1.1 by an application of the Arzelà–Ascoli theorem, which requires \( X \) to be proper. We do not know whether the implication (E) \( \Rightarrow \) (D) holds in general without this assumption.

**Proof of Theorem 1.1** Starting from the given conical geodesic bicombing \( \sigma^1 := \sigma \), we construct, by means of Proposition 2.3, a sequence of conical geodesic bicombings \( \sigma^k \) on \( X \) such that \( \sigma^k \) is \( 1/n_k \)-discretely convex, where \( n_k = 2 \) and \( n_{k+1} = 2n_k - 1 \). This collection of maps \( \sigma^k \) is equicontinuous on every bounded set, and for every fixed \((x, y, t)\) in the separable domain \( X \times X \times [0, 1] \), the sequence \( \sigma^k_{x'y'}(t) \) remains in a compact subset of \( X \). One may thus extract a subsequence \( \sigma^{k(l)} \) that converges uniformly on every compact set to a map \( \tilde{\sigma} \), which is clearly a geodesic bicombing. Convexity

\[
d(\tilde{\sigma}_{xy}(s), \tilde{\sigma}_{x'y'}(s)) \leq \frac{t - s}{t - r} d(\tilde{\sigma}_{xy}(r), \tilde{\sigma}_{x'y'}(r)) + \frac{s - r}{t - r} d(\tilde{\sigma}_{xy}(t), \tilde{\sigma}_{x'y'}(t)),
\]

where \( r < s < t \), follows from the corresponding inequality for \( \sigma^{k(l)}_{xy}, \sigma^{k(l)}_{x'y'} \) and \( r_l < s_l < t_l \) by choosing these numbers in \([0,1] \cap (1/n_{k(l)})\mathbb{Z} \) such that \( r_l \to r, s_l \to s, \) and \( t_l \to t \).

\[ \square \]

The following observation will be used in Example 3.5.
2.4 Remark. Let $\sigma$ be a concial geodesic bicombing on the proper metric space $X$, and suppose that for some pair of points $x, y$ the consistency condition $\sigma_{x'y'}(\lambda) = \sigma_{xy}((1 - \lambda)s + \lambda t)$ holds for all $0 \leq s \leq t \leq 1$ and $\lambda \in [0, 1]$, where $x' := \sigma_{xy}(s)$ and $y' := \sigma_{xy}(t)$. Then it is easily seen that $\sigma_{xy}$ as well as all positively oriented subsegments are unaltered by the procedure in the above proof. In other words, the resulting convex bicombing $\bar{\sigma}$ satisfies $\bar{\sigma}_{x'y'} = \sigma_{x'y'}$ for all $x', y'$ as above, in particular $\bar{\sigma}_{xy} = \sigma_{xy}$.

3 Straight curves

Whereas the preceding section dealt with the existence of convex bicombings, we now turn to the question of uniqueness. First we consider a property every geodesic from a convex bicombing necessarily shares.

Let $X$ be a metric space. We call a curve $\gamma : [a, b] \to X$ straight (or a straight segment) if for every $z \in X$ the function $d_z \circ \gamma$ is convex, where $d_z = d(z, \cdot)$. In particular, for fixed $s, t \in [a, b]$, taking $z := \gamma(s)$ one gets the inequality

$$d(\gamma(s), \gamma((1 - \lambda)s + \lambda t)) \leq \lambda d(\gamma(s), \gamma(t))$$

for all $\lambda \in [0, 1]$, whereas for $z := \gamma(t)$ one obtains

$$d(\gamma((1 - \lambda)s + \lambda t), \gamma(t)) \leq (1 - \lambda) d(\gamma(s), \gamma(t))$$

for all $\lambda \in [0, 1]$.

By taking the sum of these two inequalities one sees that straight curves are geodesics (of constant speed). The terminology is further justified by Theorem 3.3 below. In the proof of this result as well as in Example 3.5 we use Isbell’s injective hull construction [14], which we first recall (see [18] for a more detailed exposition).

Given a metric space $X$, consider the vector space $\mathbb{R}^X$ of arbitrary real valued functions on $X$ and put

$$\Delta(X) := \{f \in \mathbb{R}^X : f(x) + f(y) \geq d(x, y) \text{ for all } x, y \in X\}.$$

Call $f \in \Delta(X)$ extremal if there is no $g \leq f$ in $\Delta(X)$ distinct from $f$. The set $E(X)$ of extremal functions is equivalently described as

$$E(X) = \{f \in \mathbb{R}^X : f(x) = \sup_{y \in X} (d(x, y) - f(y)) \text{ for all } x \in X\},$$

and it is easily seen that $E(X)$ is a subset of

$$\Delta_1(X) := \{f \in \Delta(X) : f \text{ is 1-Lipschitz}\}.$$

Note that a function $f \in \mathbb{R}^X$ belongs to $\Delta_1(X)$ if and only if

$$\|f - d_x\|_\infty = f(x)$$

for all $x \in X$. (3.1)
The metric \((f, g) \mapsto \|f - g\|_\infty\) on \(\Delta_1(X)\) is thus finite, as \(\|f - g\|_\infty \leq \|f - d_x\|_\infty + \|g - d_x\|_\infty = f(x) + g(x)\) for any \(x \in X\). The set \(E(X) \subset \Delta_1(X)\) is equipped with the induced metric, and one has the canonical isometric embedding
\[
e: X \to E(X), \quad e(x) = d_x.
\]

Isbell showed that \((e, E(X))\) is indeed an injective hull of \(X\). That is, \(E(X)\) is an injective metric space, and every isometric embedding of \(X\) into another injective metric space factors through \(e\).

Returning to straight curves, we first observe that this property persists when we pass from \(X\) to \(E(X)\).

**3.1 Lemma.** Let \(\gamma: [a, b] \to X\) be a straight curve in some metric space \(X\). Regarding \(X\) as a subspace of its injective hull \(E(X)\) we then have that \(\gamma\) is also straight in \(E(X)\).

**Proof.** By (3.1), the distance from an element \(f \in E(X)\) to a point \(x \in X \subset E(X)\) equals \(f(x)\). So we need to show that the function \(f \circ \gamma\) is convex. Given \(x := \gamma(s)\), \(y := \gamma(t)\), and \(w := \gamma((1 - \lambda)s + \lambda t)\), where \(\lambda \in [0, 1]\), let \(\varepsilon > 0\) and choose (using the extremality of \(f\)) a point \(v \in X\) such that \(f(v) + f(w) \leq d(v, w) + \varepsilon\). Since \(\gamma\) is straight in \(X\), we have
\[
d(v, w) \leq (1 - \lambda)d(v, x) + \lambda d(v, y).
\]
Furthermore, \(d(v, x) \leq f(v) + f(x)\) and \(d(v, y) \leq f(v) + f(y)\). Combining these inequalities we get
\[
f(v) + f(w) \leq f(v) + (1 - \lambda)f(x) + \lambda f(y) + \varepsilon.
\]
Since \(\varepsilon\) was arbitrary, this gives \(f(w) \leq (1 - \lambda)f(x) + \lambda f(y)\), as desired. 

Now let \(X = V\) be a normed real vector space. Isbell [15] and Rao [21] (see also [6]) showed that then the injective hull \(E(V)\) has a Banach space structure with respect to which the isometric embedding \(e: V \to E(V)\) is linear. Since \(E(V)\) is injective, collections of balls in \(E(V)\) have the binary intersection property, so the Banach space \(E(V)\) is also injective in the linear category by [19]. Then a theorem of Nachbin, Goodner, and Kelley [16] implies that \(E(V)\) is isometrically isomorphic to the space \(C(M)\) of continuous functions, with the supremum norm, on some extremely disconnected compact Hausdorff space \(M\). Summarizing, we may thus view \(V\) as a linear subspace of \(C(M)\), where \(M\) is such that \(E(V) \cong C(M)\). This fact will be used below.

As usual, we call a curve \(\gamma: [a, b] \to V\) in a vector space \(V\) linear if it is of the form \(t \mapsto p + ty\) for some \(p, y \in V\). This is obviously a local property.

**3.2 Proposition.** Let \(M\) be a compact Hausdorff space, and let \(\gamma: [a, b] \to O\) be a curve in an open subset \(O\) of \(C(M)\). Then \(\gamma\) is straight (in \(O\) with the induced metric) if and only if it is linear.
Proof. Clearly every linear curve is straight. For the other direction, we assume that \( \gamma: [0,1] \rightarrow O \) is a straight curve from 0 to \( y \), where \( \|y\|_\infty = l \), and the closed 2l-neighborhood of \( \gamma([0,1]) \) is contained in \( O \). We have to show that the two functions \( \gamma(\lambda) \) and \( \lambda y \) agree for every \( \lambda \in (0,1) \). So fix \( \lambda \in (0,1) \) as well as \( m \in M \). For an arbitrary \( \varepsilon > 0 \), choose an open neighborhood \( U \) of \( m \) such that

\[
|\gamma(\lambda)(m') - \gamma(\lambda)(m)| < \varepsilon/2, \quad |y(m') - y(m)| < \varepsilon/2
\]

for all \( m' \in U \). By Urysohn’s lemma there is a nonnegative function \( \phi \in C(M) \) with \( \phi|_{M\setminus U} \equiv 0 \) and \( \|\phi\|_\infty = 2l \). Put \( z_\pm := \gamma(\lambda) \pm \phi \) and note that these are elements of \( O \). Since \( \gamma \) is straight,

\[
2l = \|z_\pm - \gamma(\lambda)\|_\infty \leq (1 - \lambda)\|z_\pm\|_\infty + \lambda\|z_\pm - y\|_\infty. \tag{3.2}
\]

Now if \( f \in C(M) \) is a function satisfying \( \|f\|_\infty \leq l \) as well as \( f(m') < f(m) + \varepsilon \) for all \( m' \in U \), then \( (f + \phi)|U < 2l + f(m) + \varepsilon \). (Note that \( \|f\|_\infty \leq l \) since \( \gamma \) is a geodesic from 0 to \( y \).) Together with (3.2), this shows that

\[
\gamma(\lambda)(m) - \lambda y(m) + \varepsilon \geq 0.
\]

Similarly, for \( f = -\gamma(\lambda) \) and \( f = y - \gamma(\lambda) \) we obtain \( \|z_-\|_\infty \leq 2l - \gamma(\lambda)(m) + \varepsilon \) and \( \|z_- - y\|_\infty \leq 2l + y(m) - \gamma(\lambda)(m) + \varepsilon \), respectively, which gives

\[
\lambda y(m) - \gamma(\lambda)(m) + \varepsilon \geq 0.
\]

Letting \( \varepsilon \to 0 \) we conclude that \( \gamma(\lambda)(m) = \lambda y(m) \), ending the proof as \( \lambda \) and \( m \) were arbitrary.

Combining these results we obtain the desired characterization of linear geodesics in normed spaces.

3.3 Theorem. A straight curve in an arbitrary normed space \( V \) is linear. Hence the bicombing of linear geodesics is the only convex bicombing on \( V \).

Proof. As mentioned above, we can regard the normed space \( V \) as being a linear subspace of its injective hull \( E(V) \), and we have \( E(V) \cong C(M) \) for some compact Hausdorff space \( M \). Now straight curves in \( V \) are straight in \( C(M) \) by Lemma 3.1 and linear by Proposition 3.2.

One may ask whether this holds more generally for linearly convex subsets of normed spaces. The answer turns out to be negative.
3.4 Example. Consider the Banach space \( \ell_\infty([0, 1]) \) of bounded real valued functions on \([0, 1]\), equipped with the supremum norm. The subset

\[
C := \{ f \in \ell_\infty([0, 1]) : f(0) + f(1) = 1, f \text{ is convex, and } f \in \Delta_1([0, 1]) \}
\]

is compact and linearly convex. Hence there is the convex bicombing of linear geodesics in \( C \). But there are more straight segments: the curve \( \gamma : [0, 1] \to C, \gamma(t) = d_{\ell_1} \), is non-linear, and by (3.1) we have \( t \mapsto \|f - \gamma(t)\|_\infty = f(t) \) for every \( f \in C \), which is a convex function by the definition of \( C \).

We conclude this section with an example of a compact metric space that admits at least two distinct convex geodesic bicombings.

3.5 Example. Consider two geodesics \( \alpha, \beta : [0, 1] \to \ell_\infty([0, 1]) \) from \( d_0 \) to \( d_1 \): the linear geodesic \( \alpha(s) = (1-s)d_0 + sd_1 \), and the Kuratowski embedding \( \beta(t) = d_{\ell_1} \) of \([0, 1]\). Let \( B \subset \ell_\infty([0, 1]) \) be the bigon composed of these two geodesic segments. By (3.1) we have

\[
\|\alpha(s) - \beta(t)\|_\infty = \alpha(s)(t) = s + t - 2st.
\]

(3.3)

Since this last term is symmetric in \( s \) and \( t \), there is an isometric involution \( \iota : B \to B \) that interchanges \( \alpha \) and \( \beta \). Furthermore, as \( \ell_\infty([0, 1]) \) is injective, we can embed the injective hull \( E(B) \) of \( B \) into \( \ell_\infty([0, 1]) \) (and identify it with its image), so that \( B \subset E(B) \subset \ell_\infty([0, 1]) \). Now \( E(B) \) is not linearly convex in \( \ell_\infty([0, 1]) \), but by retracting the linear geodesics with endpoints in \( E(B) \) to \( E(B) \) we obtain a conical geodesic bicombing \( \sigma \) on \( E(B) \) (compare Lemma 2.1). Note that since \( \alpha \) was already linear, we have \( \sigma_{d_0d_1} = \alpha \). Note further that \( E(B) \) is compact, because \( B \) is compact. Theorem 1.1 then yields a convex bicombing \( \bar{\sigma} \) which, by Remark 2.4, still satisfies \( \bar{\sigma}_{d_0d_1} = \alpha \). Finally, the involution \( \iota \) extends uniquely to an isometry \( I \) of \( E(B) \) (see, for instance, Proposition 3.7 in [18]). Mapping \( \bar{\sigma} \) by \( I \) we get a convex bicombing \( \bar{\tau} \) on \( E(B) \) with \( \bar{\tau}_{d_0d_1} = \beta \), distinct from \( \bar{\sigma} \).

4 Combinatorial dimension

The example just described contrasts with Theorem 1.2 which we will prove in this section. First we discuss the structure of injective hulls of finite metric spaces and the notion of combinatorial dimension in more detail.

Let \( X \) be a finite metric space, with \(|X| = n \geq 1\), say. The set \( \Delta(X) \subset \mathbb{R}^X \cong \mathbb{R}^n \) is an unbounded polyhedral domain, determined by the finitely many linear inequalities \( f(x) + f(y) \geq d(x, y) \) for \( x, y \in X \) (in particular \( f \geq 0 \)). As \( X \) is finite, a function \( f \in \Delta(X) \) is extremal if and only if for every \( x \in X \) there exists a point \( y \in X \) such that \( f(x) + f(y) = d(x, y) \). So the injective hull is a polyhedral subcomplex of \( \partial \Delta(X) \) of dimension at most \( n/2 \). (It is not difficult to see that \( E(X) \) consists precisely of the bounded faces of \( \partial \Delta(X) \).) For \( n \leq 5 \), the
various possible combinatorial types of $E(X)$ are depicted in Sect. 1 of [7] (where $\Delta(X)$ and $E(X)$ are denoted $P_X$ and $T_X$, respectively). To describe the structure of $E(X)$ further, one may assign to every $f \in E(X)$ the undirected graph with vertex set $X$ and edge set

$$A(f) = \{ \{x, y\} : x, y \in X, f(x) + f(y) = d(x, y) \}.$$ 

Note that this graph has no isolated vertices (because $f$ is extremal), but may be disconnected, and there is a loop $\{x, x\}$ if and only if $f(x) = 0$, which occurs if and only if $f = d_x$ (by (4.1)). Call a set $A$ of unordered pairs of (possibly equal) points in $X$ admissible if there exists an $f \in E(X)$ with $A(f) = A$, and denote by $\mathcal{A}(X)$ the collection of admissible sets. The family of polyhedral faces of $E(X)$ is then given by $\{P(A)\}_{A \in \mathcal{A}(X)}$, where

$$P(A) = \{ f \in \Delta(X) : A \subset A(f) \},$$

and where $P(A')$ is a face of $P(A)$ if and only if $A \subset A'$. We define the rank $\text{rk}(A)$ of $A$ as the dimension of $P(A)$. This number can be read off as follows. If $f, g$ are two elements of $P(A)$, then $f(x) + f(y) = d(x, y) = g(x) + g(y)$ for $\{x, y\} \in A$, so $f(y) - g(y) = -(f(x) - g(x))$. Thus the difference $f - g$ has alternating sign along all edge paths in the graph $(X, A)$. It follows that there is either no or exactly one degree of freedom for the values of $f \in P(A)$ on every connected component of $(X, A)$, depending on whether or not the component contains a cycle of odd length. We call such components (viewed as subsets of $X$) odd or even $A$-components, respectively. The rank $\text{rk}(A) = \dim(P(A))$ is then precisely the number of even $A$-components of $X$. (Here we have adopted the notation from [13], whereas [7] uses $\mathcal{X}_f = \{(x, y) \in X \times X : f(x) + f(y) = d(x, y)\}$ in place of $A(f)$.)

Now let again $X$ be a general metric space. We recall that the combinatorial dimension of $X$, introduced by Dress, is the possibly infinite number

$$\dim_{\text{comb}}(X) = \sup \{ \dim(E(Y)) : Y \subset X, |Y| < \infty \},$$

see Theorem 9’ on p. 380 in [7]. This theorem contains in particular a characterization of the inequality $\dim_{\text{comb}}(X) \leq n$ in terms of a $2(n + 1)$-point inequality, which may be rephrased as follows.

4.1 Theorem (Dress). Let $X$ be a metric space, and let $n \geq 1$ be an integer. The inequality $\dim_{\text{comb}}(X) \leq n$ holds if and only if for every set $Z \subset X$ with $|Z| = 2(n + 1)$ and every fixed point free involution $i : Z \to Z$ there exists a fixed point free bijection $j : Z \to Z$ distinct from $i$ such that

$$\sum_{z \in Z} d(z, i(z)) \leq \sum_{z \in Z} d(z, j(z)).$$  (4.1)
The case \( n = 1 \) corresponds to the much simpler fact that \( \dim_{\text{comb}}(X) \leq 1 \) if and only if \( X \) is 0-hyperbolic in the sense of Gromov \[11\] or tree-like in the terminology of \[7\], that is, for every quadruple of points \( x, x', y, y' \in X \),

\[
d(x, x') + d(y, y') \leq \max\{d(x, y) + d(x', y'), d(x, y') + d(x', y)\}.
\]

Theorem 4.1 follows from more general considerations in Sect. (5.3) of \[7\]. For convenience, we provide a streamlined and somewhat simplified argument in an appendix. However, this result will not be used in the present paper.

By the results of \[18\], every proper metric space with integer valued metric that is discretely geodesic and \( \delta \)-hyperbolic has finite combinatorial dimension. By contrast, the unit circle \( S \) in the Euclidean plane with either the induced (chordal) or the induced inner metric satisfies \( \dim_{\text{comb}}(S) = \infty \), as is seen by looking at the constant extremal function \( f = \text{diam}(S)/2 \), restricted to the vertices of a regular \( 2n \)-gon. Similarly, the metric bigon \( B \) constructed in Example 3.5 has \( \dim_{\text{comb}}(B) = \infty \); consider the function \( f \) defined by \( f(\alpha(s)) = f(\beta(1-s)) = ||\alpha(s) - \beta(1-s)||/2 \) for \( s \in [0,1] \). Among the finite dimensional normed spaces, only those with a polyhedral norm have finite combinatorial dimension, equal to the number of pairs of opposite facets of the unit ball.

The following proposition is the key observation for the proof of Theorem 1.2.

We denote by \( B(x, r) \) the closed ball of radius \( r \) at \( x \).

### 4.2 Proposition

Let \( X \) be a metric space of finite combinatorial dimension. Then for every pair of points \( x_0, y_0 \in X \) there exists a \( \delta > 0 \) such that

\[
d(x_0, y_0) + d(x, y) \leq d(x_0, y) + d(x_0, y_0)
\]

for all pairs of points \( x \in B(x_0, \delta) \) and \( y \in B(y_0, \delta) \).

**Proof.** When \( x_0 = y_0 \), the triangle inequality in \( X \) gives the result. Now assume that \( x_0 \neq y_0 \). Denote by \( \mathcal{F} \) the collection of all real valued functions with finite support \( \text{spt}(f) \subset X \) such that \( f \in \text{E}(\text{spt}(f)), x_0, y_0 \in \text{spt}(f), \) and \( \{x_0, y_0\} \in A(f) \), that is,

\[
f(x_0) + f(y_0) = d(x_0, y_0).
\]

Since \( \dim_{\text{comb}}(X) < \infty \), there exist an integer \( n \) and a function \( f \in \mathcal{F} \) such that \( \text{rk}(A(g)) \leq n = \text{rk}(A(f)) \) for all \( g \in \mathcal{F} \). Since \( x_0 \neq y_0 \), we have \( n \geq 1 \), thus \( f > 0 \). By restricting \( f \) to a smaller set if necessary, we can arrange that \( A(f) \) is the collection of \( n \) disjoint pairs \( \{x_0, y_0\}, \{x_1, y_1\}, \ldots, \{x_{n-1}, y_{n-1}\} \). There exists a \( \delta > 0 \) such that for all \( v \in \{x_0, y_0\} \) and \( w \in \{x_1, y_1, \ldots, x_{n-1}, y_{n-1}\} \) we have \( d(v, w) > \delta \), \( f(v) \geq \delta \), and

\[
f(v) + f(w) \geq d(v, w) + 2\delta.
\]

Note that \( d(x_0, y_0) = f(x_0) + f(y_0) \geq 2\delta \). Let \( x \in B(x_0, \delta) \) and \( y \in B(y_0, \delta) \). If \( x = x_0 \) or \( y = y_0 \) or \( x = y \), the desired inequality holds. So assume that
Now suppose that \( s \neq x \neq y \neq y_0 \). Then \( x, y, x_0, y_0, \ldots, x_{n-1}, y_{n-1} \) are pairwise distinct. Put 
\[ a := d(x, y_0) - f(y_0) \quad \text{and} \quad b := d(x_0, y) - f(x_0). \]
We have
\[
a \geq d(x_0, y_0) - d(x, x_0) - f(y_0) = f(x_0) - d(x, x_0) \geq f(x_0) - \delta,
b \geq d(x_0, y_0) - d(y, y_0) - f(x_0) = f(y_0) - d(y, y_0) \geq f(y_0) - \delta.
\]
(4.3)
Since \( f(x_0), f(y_0) \geq \delta \), this gives in particular \( a, b \geq 0 \) and hence
\[
a + f(x_0) \geq \delta \geq d(x, x_0),
b + f(y_0) \geq \delta \geq d(y, y_0).
\]
(4.4)
Furthermore, for every \( w \in \{x_1, y_1, \ldots, x_{n-1}, y_{n-1}\} \), combining (4.3) and (4.2) we obtain
\[
a + f(w) \geq f(x_0) + f(w) - \delta \geq d(x_0, w) + \delta \geq d(x, w),
b + f(w) \geq f(y_0) + f(w) - \delta \geq d(y_0, w) + \delta \geq d(y, w).
\]
(4.5)
Now, in the case that \( a + b < d(x, y) \), we could define a function \( g \) with finite support by putting \( g(w) := f(w) \) for \( w \in \{x_0, y_0, \ldots, x_{n-1}, y_{n-1}\} \) and by choosing \( g(x) > a \) and \( g(y) > b \) such that \( g(x) + g(y) = d(x, y) \). In view of (4.4) and (4.5), this function would satisfy
\[
A(g) = \{\{x_0, y_0\}, \ldots, \{x_{n-1}, y_{n-1}\}, \{x, y\}\},
\]
so that \( g \in \mathcal{F} \) and \( \text{rk}(A(g)) = n + 1 \), in contradiction to the maximality of \( n \). We conclude that \( d(x, y) \leq a + b = d(x, y_0) + d(x_0, y) - d(x_0, y_0) \). \( \square \)

4.3 Proposition. Suppose that \( X \) is a metric space of finite combinatorial dimension, and \( \alpha, \beta : [0,1] \rightarrow X \) are two straight curves. Then the function \( s \mapsto d(\alpha(s), \beta(s)) \) is convex on \([0,1] \). In particular, every pair of points in \( X \) is joined by at most one straight segment, up to reparametrization.

Proof. For \( s, t \in [0,1] \), put \( h(s, t) := d(\alpha(s), \beta(t)) \). Fix \( s_0 \in (0,1) \). Then it follows from Proposition 4.2 that there exists an \( \varepsilon > 0 \) such that \([s_0 - \varepsilon, s_0 + \varepsilon] \subset [0,1] \) and, for all \( s, t \in [s_0 - \varepsilon, s_0 + \varepsilon] \),
\[
h(s_0, s_0) + h(s, t) \leq h(s, s_0) + h(s_0, t).
\]
(4.6)
Now suppose that \( s_0 - \varepsilon \leq s < s_0 < t \leq s_0 + \varepsilon \), and let \( \lambda \in (0,1) \) be such that \( s_0 = (1-\lambda)s + \lambda t \). Since \( h(s, \cdot) \) and \( h(\cdot, t) \) are convex functions on \([0,1] \), we have
\[
h(s, s_0) \leq (1-\lambda) h(s, s) + \lambda h(s, t),
h(s_0, t) \leq (1-\lambda) h(s, t) + \lambda h(t, t).
\]
(4.7)
Combining (4.6) and (4.7) we conclude that

\[ h(s_0, s_0) \leq (1 - \lambda) h(s, s) + \lambda h(t, t). \]

Note that this holds whenever \( s_0 - \varepsilon \leq s < s_0 < t \leq s_0 + \varepsilon \) and \( s_0 = (1 - \lambda)s + \lambda t \), where \( \varepsilon > 0 \) depends on \( s_0 \). Since \( s \mapsto h(s, s) = d(\alpha(s), \beta(s)) \) is continuous on \([0, 1]\), it follows easily that this function is convex. □

Theorem 1.2 is an immediate corollary of Proposition 4.3. Note that a convex (or conical) geodesic bicombing \( \sigma \) can be restricted to any ball \( B = B(z, r) \) because \( \sigma \)-convex \( x, y \in B \) implies \( \sigma_{xy}([0, 1]) \subset B \).

5 Boundary at infinity

We now consider a complete metric space \( X \) with a convex and consistent (equivalently, conical and consistent) geodesic bicombing. Note that completeness is no restriction, as any conical bicombing may be extended to the completion of the underlying space. We define the geometric boundary and the closure of \( X \) by means of geodesic rays that are consistent with the given bicombing, and we equip the closure with a simple explicit metric. (Some general references for the analogous constructions in the case of CAT(0) spaces or Gromov hyperbolic spaces are [2, 4, 5, 11].) Then we prove Theorem 1.4.

By a ray in \( X \) we mean an isometric embedding of \( \mathbb{R} := [0, \infty) \). Two rays \( \xi, \eta \) in \( X \) are asymptotic if the function \( t \mapsto d(\xi(t), \eta(t)) \) is bounded or, equivalently, the Hausdorff distance between the images of \( \xi \) and \( \eta \) is finite. In the presence of a convex and consistent bicombing \( \sigma \) on \( X \) we call a ray \( \xi : \mathbb{R} \to X \) a \( \sigma \)-ray if

\[ \xi(((1 - \lambda)s + \lambda t) = \sigma_{xy}(\lambda) \]

whenever \( 0 \leq s \leq t \), \( x := \xi(s) \), \( y := \xi(t) \), and \( \lambda \in [0, 1] \). It follows that for any two \( \sigma \)-rays \( \xi, \eta \) the map \( t \mapsto d(\xi(a + \alpha t), \eta(b + \beta t)) \) is convex on \( \mathbb{R} \) for all \( a, \alpha, b, \beta \geq 0 \).

The geometric boundary \( \partial_\sigma X \) is the set of equivalence classes of mutually asymptotic \( \sigma \)-rays in \( X \), and we write \( \bar{X}_\sigma := X \cup \partial_\sigma X \).

For a unified treatment of the two parts of \( \bar{X}_\sigma \) it is convenient to associate with every pair \( (o, x) \in X \times X \) the eventually constant curve \( g_{ox} : \mathbb{R} \to X \),

\[ g_{ox}(t) := \begin{cases} 
\sigma_{ox}(t/d(o, x)) & \text{if } 0 \leq t < d(o, x), \\
x & \text{if } t \geq d(o, x). 
\end{cases} \quad (5.1) \]

As a preliminary remark we note that for any basepoint \( o \in X \) and \( r \in \mathbb{R} \), the radial retraction \( \phi_r : X \to B(o, r) \) defined by \( \phi_r(x) := g_{ox}(r) \) satisfies

\[ d(\phi_r(x), \phi_r(y)) \leq \frac{2r}{d(o, x)} d(x, y) \quad (5.2) \]
whenever \( d(o, x) \geq d(o, y) \) and \( d(o, x) > r \). To see this, let \( s := r/d(o, x) \) and \( y' := \sigma_{oy}(s) \). We have \( \phi_r(x) = \sigma_{ox}(s) \), and since \( \sigma \) is conical, \( d(\phi_r(x), y') \leq s \ d(x, y) \). Furthermore, \( d(y', \phi_r(y)) = d(o, \phi_r(y)) - d(o, y') \leq d(o, \phi_r(x)) - d(o, y') \leq d(\phi_r(x), y') \) and so \( d(\phi_r(x),\phi_r(y)) \leq d(\phi_r(x), y') + d(y', \phi_r(y)) \leq 2s \ d(x, y) \). In particular, \( \phi_r \) is \( 2 \)-Lipschitz. The constant \( 2 \) is optimal, as one can see by looking at the space \( \ell^2_\infty \) with 0 as the basepoint, the map \( \phi_1 \), and the points \((1,1), (1+\varepsilon, 1-\varepsilon)\). In order to prove that for every pair \((o, \bar{x}) \in X \times \partial_o X \) there is a \( \sigma \)-ray issuing from \( o \) and representing the class \( \bar{x} \), we shall need the following estimate (compare Lemma II.8.3 in [4] for the case of CAT(0) spaces).

**5.1 Lemma.** Let \( X \) be a metric space with a convex and consistent geodesic bicombing \( \sigma \), and let \( o, p \in X \). Then for any \( \sigma \)-ray \( \xi \) with \( \xi(0) = p \) we have

\[
d(\varrho_{ox}(t), \varrho_{oy}(t)) \leq \frac{2t \ d(o, p)}{T - d(o, p)}
\]

whenever \( T > 2d(o, p) \), \( x, y \in \xi((T, \infty)) \), and \( 0 \leq t \leq T - 2d(o, p) \).

**Proof.** Assume \( d(o, x) \leq d(o, y) \) and let \( s := d(p, x)/d(p, y) \) and \( y' := \sigma_{oy}(s) \). Since \( \xi \) is a \( \sigma \)-ray, we have \( x = \sigma_{py}(s) \). As \( \sigma \) is conical,

\[
d(x, y') \leq (1 - s) \ d(p, o) \leq d(o, p).
\]

(5.3)

Now \( d(o, x) \geq d(p, x) - d(o, p) \geq T - d(o, p) \) and so \( d(o, y') \geq d(o, x) - d(x, y') \geq T - 2d(o, p) \). Hence, for \( 0 \leq t \leq T - 2d(o, p) \), we have \( \phi_t(x) = \varrho_{ox}(t) \) and \( \phi_t(y') = \varrho_{oy}(t) \), and (5.2) gives the result.

The next result now follows by a standard procedure.

**5.2 Proposition.** Let \( X \) be a complete metric space with a convex and consistent geodesic bicombing \( \sigma \). Then for every pair \((o, \bar{x}) \in X \times \partial_o X \) there is a unique \( \sigma \)-ray \( \varrho_{ox} \) with \( \varrho_{ox}(0) = o \) that represents the class \( \bar{x} \). Furthermore, if \( r \geq 0 \) and \( x = \varrho_{ox}(r) \), then \( \varrho_{ox}(t) = \varrho_{ox}(r + t) \) for all \( t \in \mathbb{R}_+ \).

**Proof.** Let \( \xi \) be a \( \sigma \)-ray in the class \( \bar{x} \), and let \( p := \xi(0) \). For \( n = 1, 2, \ldots \), put \( \varrho_n := \varrho_{ox}(n) \). It follows from the preceding lemma that for every fixed \( t \geq 0 \) the sequence \( \varrho_n(t) \) is Cauchy. In the limit one obtains a \( \sigma \)-ray \( \varrho_{ox} \) issuing from \( o \). As in (5.3), we have \( d(\xi(t), \varrho_{ox}[t \ d(o, \xi(n))/n]) \leq d(o, p) \) for \( 0 \leq t \leq n \), hence \( d(\xi(t), \varrho_{ox}(t)) \leq d(o, p) \) for all \( t \geq 0 \). In particular, \( \varrho_{ox} \) is asymptotic to \( \xi \). Finally, if \( \bar{q}' \) is another \( \sigma \)-ray issuing from \( o \) and asymptotic to \( \xi \), then \( t \rightarrow d(\varrho_{ox}(t), \bar{q}'(t)) \) is a non-negative, bounded, convex function on \( \mathbb{R}_+ \) that vanishes at 0, so \( \varrho' = \varrho_{ox} \).

From this uniqueness property, the last assertion of the proposition is clear.

A natural topology on \( X_\sigma = X \cup \partial_o X \) may be described in different ways. First we fix a basepoint \( o \in X \) and consider the set

\[
\mathcal{R}_{\sigma, o} := \{ \varrho_{ox} : \bar{x} \in X_\sigma \} = \{ \varrho_{ox} : x \in X \} \cup \{ \varrho_{ox} : \bar{x} \in \partial_o X \}
\]
of generalized $\sigma$-rays based at $o$, given by (5.1) and Proposition 5.2. We equip $\overline{\mathcal{R}}_{\sigma,o}$ with the topology of uniform convergence on compact subsets of $\mathbb{R}_{+}$. Clearly $\overline{\mathcal{R}}_{\sigma,o}$ is compact if and only if $X$ is proper, as a consequence of the Arzelà-Ascoli theorem. The topology of $\overline{\mathcal{R}}_{\sigma,o}$ agrees, under canonical identification, with the cone topology on $\overline{X}_{\sigma}$, a basis of which is given by the sets

$$U_{o}(\bar{x}, t, \varepsilon) := \{ \bar{y} \in \overline{X}_{\sigma} : d(\varrho_{o\bar{x}}(t), \varrho_{o\bar{y}}(t)) < \varepsilon \} \quad (5.4)$$

for $\bar{x} \in \overline{X}_{\sigma}$ and $t, \varepsilon > 0$. Note that since $\varphi_{r}$ is 2-Lipschitz, we have

$$d(\varrho_{o\bar{x}}(r), \varrho_{o\bar{y}}(r)) \leq 2 d(\varrho_{o\bar{x}}(t), \varrho_{o\bar{y}}(t)) \quad \text{for all } r \in [0, t]. \quad (5.5)$$

Note also that $U_{o}(x, t, \varepsilon)$ is just the open ball $U(x, \varepsilon)$ in case $t \geq d(o, x) + \varepsilon$. It follows readily from the following lemma that this topology on $\overline{X}_{\sigma}$ is independent of the choice of basepoint $o$.

5.3 Lemma. Given $o \in X$, $\bar{x} \in \partial_{o}X$, $\varepsilon, t > 0$, and $p \in X$, there exists $T > 0$ such that $U_{p}(\bar{x}, \varepsilon/4, T) \subset U_{o}(\bar{x}, \varepsilon, t)$.

Proof. It follows from Lemma 5.1 and the construction of the ray $\varrho_{o\bar{x}}$ in Proposition 5.2 that if $T$ is chosen sufficiently large, depending on $d(o, p)$ and $\varepsilon, t$, and if $x := \varrho_{p\bar{x}}(T)$, then

$$d(\varrho_{o\bar{x}}(t), \varrho_{o\bar{y}}(t)) \leq \varepsilon/4. \quad \text{Likewise, for any point } \bar{y} \in \overline{X}_{\sigma}, \text{ if } y := \varrho_{o\bar{y}}(T) \text{ and } d(p, y) \text{ is large enough, then}$$

$$d(\varrho_{o\bar{x}}(t), \varrho_{o\bar{y}}(t)) \leq \varepsilon/4. \quad \text{Now if } \bar{y} \in U_{p}(\bar{x}, \varepsilon/4), \text{ that is, } d(x, y) < \varepsilon/4, \text{ then}$$

$$d(\varrho_{o\bar{x}}(t), \varrho_{o\bar{y}}(t)) \leq 2 d(x, y) < \varepsilon/2 \quad \text{by (5.2), provided } d(o, x), d(o, y) > t. \text{ We conclude that } d(\varrho_{o\bar{x}}(t), \varrho_{o\bar{y}}(t)) < \varepsilon \text{ and thus } \bar{y} \in U_{o}(\bar{x}, t, \varepsilon) \text{ for sufficiently large } T. \quad \square$$

Next we equip $\overline{X}_{\sigma}$ with the metric defined by

$$D_{o}(\bar{x}, \bar{y}) := \int_{0}^{\infty} d(\varrho_{o\bar{x}}(s), \varrho_{o\bar{y}}(s)) e^{-s} \, ds \quad (5.6)$$

(compare Sect. 8.3.B in [11]). We have $D_{o}(o, \bar{x}) \leq 1$, with equality if and only if $\bar{x} \in \partial_{o}X$. For $d(\varrho_{o\bar{x}}(t), \varrho_{o\bar{y}}(t)) = a$, (5.6) yields

$$\int_{t}^{\infty} \frac{a}{2} e^{-s} \, ds \leq D_{o}(\bar{x}, \bar{y}) \leq \int_{0}^{t} 2a e^{-s} \, ds + \int_{t}^{\infty} 2s e^{-s} \, ds,$$

and it follows easily from these estimates that the metric (5.6) induces the cone topology. Observe also that if $d(o, x) = R$ and $y = \varphi_{r}(x)$ for some $0 \leq r \leq R$, then

$$D_{o}(x, y) = \int_{r}^{R} (s - r) e^{-s} \, ds + \int_{R}^{\infty} (R - r) e^{-s} \, ds = e^{-r} - e^{-R}. $$
In particular, for any σ-ray ξ issuing from o, the curve \( \lambda \mapsto \xi(-\log(1 - \lambda)) \), \( \lambda \in [0, 1) \), is a unit speed geodesic with respect to \( D_o \). Accordingly, for \( \lambda \in [0, 1] \), we define the radial retraction \( \psi_\lambda: \overline{X}_\sigma \to B_{D_o}(o, \lambda) = \{ \bar{y}: D_o(o, \bar{y}) \leq \lambda \} \) such that \( \psi_1 = \text{id} \) and \( \psi_\lambda(x) := \varrho_{o\bar{x}}(t) \) for \( \lambda < 1 \) and \( t := -\log(1 - \lambda) \). In this latter case, the generalized ray \( \varrho_{o\bar{x}} \) with endpoint \( x := \psi_\lambda(x) \) agrees with \( \varphi_t \circ \varrho_{o\bar{x}} \), and since \( \varphi_t \) is 2-Lipschitz we obtain

\[
D_o(\psi_\lambda(x), \psi_\lambda(y)) = \int_0^\infty d(\varphi_t(\varrho_{o\bar{x}}(s)), \varphi_t(\varrho_{o\bar{y}}(s))) e^{-s} ds \leq 2 D_o(x, \bar{y}) \quad (5.7)
\]

for all \( x, \bar{y} \in \overline{X}_\sigma \). Thus \( \psi_\lambda \) is 2-Lipschitz with respect to \( D_o \). Finally, we note that if \( \bar{x} \in \overline{X}_\sigma \) and \( \lambda, \mu \in [0, 1] \), then clearly

\[
D_o(\psi_\lambda(x), \psi_\mu(x)) \leq |\lambda - \mu|, \quad (5.8)
\]

with equality when \( D_o(o, \bar{x}) \geq \max\{\lambda, \mu\} \). Now we turn to the result stated in the introduction.

**Proof of Theorem 1.4.** The map \( (x, \lambda) \mapsto \psi_{1-\lambda}(x) \) is continuous on \( \overline{X}_\sigma \times [0, 1] \) by (5.7) and (5.8) and contracts \( \overline{X}_\sigma \) to \( o \), so \( \overline{X}_\sigma \) is contractible.

To show that \( \overline{X}_\sigma \) is locally contractible, we prove that in fact each of the sets \( U_o(x, t, \varepsilon) \) for \( x \in \overline{X}_\sigma \) and \( t, \varepsilon > 0 \) (see (5.4)) is contractible. The same map as above, but restricted to \( U_o(x, t, \varepsilon) \times [0, e^{-t}] \), contracts \( U_o(x, t, \varepsilon) \) to the subset \( U(\varrho_{o\bar{x}}(t), \varepsilon) \cap B(o, t) \), which as an intersection of balls is \( \sigma \)-convex and hence itself contractible.

To prove that \( \partial_o X \) is a \( Z \)-set in \( \overline{X}_\sigma \), let an open set \( U \) in \( \overline{X}_\sigma \) be given, and assume that \( U \neq \emptyset, \overline{X}_\sigma \). We want to find a homotopy \( h: U \times [0, 1] \to U \) from the identity on \( U \) to a map into \( U \setminus \partial_o X \) such that the restriction of \( h \) to \( (U \setminus \partial_o X) \times [0, 1] \) takes values in \( U \setminus \partial_o X \). To this end, we note that the function \( \mu: U \to \mathbb{R} \) defined by

\[
\mu(x) := D_o(o, x) - \frac{1}{2} \inf\{D_o(x, \bar{y}) : \bar{y} \in \overline{X}_\sigma \setminus U\}
\]

is Lipschitz continuous with respect to \( D_o \) and satisfies \( \mu(x) < D_o(o, x) \) for all \( x \in U \) because \( U \) is open. It is then easy to see that \( h(x, \lambda) := \psi_{\max\{1-\lambda, \mu(x)\}}(x) \) serves the purpose.

It remains to show that \( \overline{X}_\sigma \) is an AR (absolute retract). In case \( X \) has finite topological dimension, we have

\[
\dim(\overline{X}_\sigma) = \dim(X) < \infty.
\]

Indeed, for every \( \varepsilon \in (0, 1) \), any open covering of the \( D_o \)-ball \( B_{D_o}(o, 1 - \varepsilon) \) with mesh \( \leq \varepsilon \) gives rise, via \( \psi_{1-\varepsilon}^{-1} \), to an open covering of \( \overline{X}_\sigma \) with mesh \( \leq 3\varepsilon \) and the same multiplicity (see, for instance, [5] for the definitions). It is then a standard result that contractible and locally contractible metrizable spaces of finite
dimension are absolute retracts (see [8]). However, finite dimension is not needed.
Every metric space \( X \) with a conical geodesic bicombing is strictly equiconnected,
as defined in [12], so \( X \) is an AR by Theorem 4 in that paper (see also [9]). Now,
by Corollary 6.6.7 in [22] (a result attributed to O. Hanner and S. Lefschetz),
\( \overline{X}_\sigma \) is an ANR (absolute neighborhood retract) as it contains \( X \) as a homotopy
dense subset; alternatively, one can give a short direct argument along the lines of
Lemma 1.4 in [23]. Thus \( \overline{X}_\sigma \) is a contractible ANR or, equivalently, an AR (see
Corollary 6.2.9 in [22]).

As a concluding remark we note that, presumably, the spaces \( \partial \sigma X \) and \( X_{\sigma} \)
depend on the choice of \( \sigma \). However, if \( X \) is a complete (not necessarily proper)
Gromov hyperbolic space with a convex and consistent bicombing \( \sigma \), then
\( X_{\sigma} \) is independent of \( \sigma \) and furthermore \( \partial \sigma X \) agrees with the boundary \( \partial \infty X \) defined in
terms of sequences converging to infinity. Indeed, a modification of Lemma 5.1 and
Proposition 5.2 first shows that for every ray \( \xi \) in \( X \) there is a \( \sigma \)-ray asymptotic
to \( \xi \) and issuing from the same point. As in the proof of Lemma 5.3 one can then
conclude that distinct bicombings yield homeomorphic boundaries.

**Appendix: Proof of Theorem 4.1**

We use the notation from Sect. 4.

First we show the “if” direction. Let \( Y \subset X \) be a finite set. If \( |Y| \leq 2n+1 \), the
dimension of \( E(Y) \) is at most \( n \). Now suppose that \( |Y| \geq 2n+2 \), \( f \in E(Y) \), and
\( Z \subset Y \) is a set with \( |Z| = 2n+2 \) and with a fixed point free involution \( i: Z \to Z \)
such that \( \{z, i(z)\} \in A(f) \) for every \( z \in Z \). By assumption, there exists a fixed
point free bijection \( j: Z \to Z \) such that \( j \neq i \) and

\[
\sum_{z \in Z} d(z, i(z)) \leq \sum_{z \in Z} d(z, j(z)).
\]

Since \( f(z) + f(i(z)) = d(z, i(z)) \) and \( d(z, j(z)) \leq f(z) + f(j(z)) \), this gives

\[
\sum_{z \in Z} f(z) + f(i(z)) \leq \sum_{z \in Z} f(z) + f(j(z)).
\]

However, since both \( i \) and \( j \) are bijections, these two sums agree, so each of
the inequalities \( d(z, j(z)) \leq f(z) + f(j(z)) \) must in fact be an equality, that is,
\( \{z, j(z)\} \in A(f) \). There is at least one \( z \in Z \) such that \( j(z) \neq i(z) \), so the graph
with vertex set \( Z \) and edge set \( \bigcup_{z \in Z} \{\{z, i(z)\}, \{z, j(z)\}\} \) has at most \( n \) connected
components. As this holds for every \( Z \) and \( i \) as above, we conclude that also the
graph \( (Y, A(f)) \) has no more than \( n \) components. Since \( f \in E(Y) \) was arbitrary,
this shows that the dimension of \( E(Y) \) is less than or equal to \( n \).

Now we prove the other implication. Suppose that \( Z \subset X \) is a set with
\( |Z| = 2n+2 \), and \( i: Z \to Z \) is a fixed point free involution. Let \( Z_2 \) denote
the set of all subsets of cardinality two of \( Z \). The involution \( i \) selects a subset
\[ Z_i := \{ \{ z, i(z) \} : z \in Z \} \] of \( Z_2 \) of \( n + 1 \) disjoint pairs. For every function \( h: Z \to \mathbb{R} \) we consider the set \( W(h) \) of all \( w: Z_2 \to \mathbb{R} \) such that \( w \leq 0 \) on \( Z_i \), \( w \geq 0 \) on \( Z_2 \setminus Z_i \), and

\[ \sum_{z' \in Z \setminus \{ z \}} w(\{ z, z' \}) = h(z) \]

for all \( z \in Z \). First we observe that if \( z \in Z \), and if \( \{ x, y \} \in Z_i \) is chosen such that \( z \notin \{ x, y \} \), then the function \( w_{z,\{ x, y \}} := (\delta_{\{ x, z \}} + \delta_{\{ y, z \}} - \delta_{\{ x, y \}})/2 \) on \( Z_2 \) belongs to \( W(\delta_z) \), and \( w_{i(z),\{ x, y \}} - \delta_{\{ z, i(z) \}} \) is in \( W(-\delta_z) \). It follows that \( W(h) \) is non-empty for every \( h: Z \to \mathbb{R} \). Put

\[ \mu(h) := \sup\{ w : w \in W(h) \}, \quad S(w) := \sum_{\{ x, y \} \in Z_2} w(\{ x, y \})d(x, y); \]

note that \( \mu(h) > -\infty \) but possibly \( \mu(h) = \infty \). For \( w_{z,\{ x, y \}} \) as above we have \( S(w_{z,\{ x, y \}}) \geq 0 \) by the triangle inequality, thus \( \mu(\delta_z) \geq 0 \) for all \( z \in Z \). Furthermore, since \( 0 \in W(0) \), also \( \mu(0) \geq 0 \). In fact, if \( w \in W(0) \), then \( \lambda w \in W(0) \) for all \( \lambda \geq 0 \), so we have either \( \mu(0) = 0 \) or \( \mu(0) = \infty \).

In case \( \mu(0) = \infty \), choose \( w \in W(0) \) with \( S(w) > 0 \) such that no \( w' \in W(0) \) with \( S(w') \) has strictly smaller support. It follows that every nonzero \( w \in W(0) \) with support \( \text{spt}(w) \subset \text{spt}(w) \) satisfies \( S(v) > 0 \), for if \( \lambda > 0 \) is the maximal number with the property that \( |\lambda w| \leq |w| \), then \( v' := w - \lambda v \) belongs to \( W(0) \) and \( \text{spt}(v') \) is a strict subset of \( \text{spt}(w) \), so \( S(v') \leq 0 \) and \( \lambda S(v) = S(w) - S(v') > 0 \). (In fact \( \lambda v = w \), because \( v' \neq 0 \) would likewise imply \( S(v') > 0 \).) Since for fixed \( z \) the sum of the weights \( w(\{ z, z' \}) \) is zero, it is not difficult to see that there exist pairwise distinct points \( z_0, z_1, \ldots, z_l \), each \( k \geq 1 \), such that \( w(\{ z_k, i(z_k) \}) < 0 < w(\{ i(z_k), z_{k+1} \}) \) for \( k = 0, \ldots, l \), where \( z_{l+1} := z_0 \). Then the function

\[ v := \sum_{k=0}^{l} -\delta_{\{ z_k, i(z_k) \}} + \delta_{\{ i(z_k), z_{k+1} \}} \]

on \( Z_2 \) belongs to \( W(0) \), and \( \text{spt}(v) \subset \text{spt}(w) \). Hence \( S(v) > 0 \). This means that

\[ \sum_{k=0}^{l} d(z_k, i(z_k)) < \sum_{k=0}^{l} d(i(z_k), z_{k+1}). \]

The points \( i(z_0), \ldots, i(z_l) \) are distinct, so there is a well-defined map \( j: Z \to Z \) such that \( j(i(z_k)) = z_{k+1} \) for \( k = 0, \ldots, l \) and \( j(z) = i(z) \) otherwise. Note that \( j \) is fixed point free since \( \{ i(z_k), z_{k+1} \} \in Z_2 \) and \( i(z) \neq z \) for all \( z \in Z \). Furthermore, \( j \) is injective because \( i \) is injective, \( z_0, \ldots, z_l \) are distinct, and \( j(z) = i(z) = z_k \) would imply \( j(z) = j(i(z_k)) = z_{k+1} \neq z_k \). Now it is clear that \( [4.1] \) holds, even with strict inequality. Note that this part of the proof does not use the assumption \( \dim_{\text{omb}}(X) \leq n \).

It remains to consider the case \( \mu(0) = 0 \). Let \( h, h' \in \mathbb{R}^Z \). For all \( w \in W(h) \) and \( w' \in W(h') \) we have \( w + w' \in W(h + h') \), therefore

\[ \mu(h) + \mu(h') \leq \mu(h + h'). \]
in particular $\mu(h) \leq \mu(0) - \mu(-h) = -\mu(-h) < \infty$. Put 
\[
\nu(h) := \frac{\mu(h) - \mu(-h)}{2}.
\]
We have $\mu(h) - \mu(-h') \geq \mu(h + h')$ and $\mu(h') - \mu(-h) \geq \mu(h + h')$, so 
\[
\nu(h) + \nu(h') \geq \mu(h + h').
\]
We have already observed that $\mu(\delta_z) \geq 0$ for all $z \in Z$, hence $-\mu(\delta_z) \geq 0$ and $\nu(\delta_z) \geq 0$. If $\{x, y\} \in Z_2 \setminus Z_i$, then $\delta_{\{x, y\}} \in W(\delta_x + \delta_y)$, thus 
\[
\nu(\delta_x) + \nu(\delta_y) \geq \mu(\delta_x + \delta_y) \geq d(x, y).
\]
Similarly, if $\{x, y\} \in Z_i$, then $-\delta_{\{x, y\}} \in W(-\delta_x - \delta_y)$, hence 
\[
\nu(-\delta_x) + \nu(-\delta_y) \geq \mu(-\delta_x - \delta_y) \geq -d(x, y)
\]
and so $\nu(\delta_x) + \nu(\delta_y) = -\nu(-\delta_x) - \nu(-\delta_y) \leq d(x, y)$. Now it is clear that there exists a function $f \in \mathbb{R}^{Z}$ such that $f(z) \geq \nu(\delta_z)$ for all $z \in Z$ and $f(x) + f(y) = d(x, y)$ for all $\{x, y\} \in Z_i$. Hence, $f \in \Delta(Z)$ and $Z_i \subset A(f)$, so in fact $f \in E(Z)$. Since $\dim_{\text{comb}}(X) \leq n$ by assumption, we have $\text{rk}(A(f)) \leq n$, and there is no loss of generality in assuming that there is no $g \in E(Z)$ with $Z_i \subset A(g)$ and $\text{rk}(A(g)) > \text{rk}(A(f))$. Since $Z$ has at most $n$ even $A(f)$-components, some such component $Z'$ contains more than one of the $n + 1$ edges in $Z_i$. Note that $i$ maps $Z'$ onto $Z'$. We claim that for every $z' \in Z'$ there is a $z'' \in Z' \setminus \{z', i(z')\}$ such that $\{z', z''\} \in A(f)$. If, to the contrary, there were a $z' \in Z'$ with no such $z''$, we could choose $g \in \mathbb{R}^{Z}$ such that $f(z') > g(z') > d(z', z) - f(z)$ and $g(z) = f(z)$ for all $z \in Z \setminus \{z', i(z')\}$, and $g(i(z')) = d(z', i(z')) - g(z')$. This function would satisfy $\text{rk}(A(g)) > \text{rk}(A(f))$ and $Z_i \subset A(g)$, in contradiction to the assumption on $f$. It follows easily that there exist $z_0, z_1, \ldots, z_l \in Z'$, with $l \geq 1$, such that $\{z_0, i(z_0)\}, \ldots, \{z_l, i(z_l)\}$ are pairwise disjoint and $\{i(z_k), z_{k+1}\} \in A(f)$ for $k = 0, \ldots, l$, where $z_{l+1} = z_0$. Now 
\[
\sum_{k=0}^{l} d(z_k, i(z_k)) = \sum_{k=0}^{l} f(z_k) + f(i(z_k)) = \sum_{k=0}^{l} d(i(z_k), z_{k+1}).
\]
Putting $j(i(z_k)) = z_{k+1}$ and $j(z_{k+1}) = i(z_k)$ for $k = 0, \ldots, l$ and $j(z) = i(z)$ otherwise, we get a fixed point free involution $j : Z \to Z$ distinct from $i$ such that (4.1) holds with equality.

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D. Descombes (dominic.descombes@math.ethz.ch),
U. Lang (urs.lang@math.ethz.ch),
Department of Mathematics, ETH Zurich, 8092 Zurich, Switzerland