SCREW INSTABILITY OF MAGNETIC FIELD AND GAMMA-RAY BURSTS IN TYPE Ib/c SUPERNOVAE

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ABSTRACT

A toy model of gamma-ray burst supernovae (GRB SNe) is discussed by considering the effects of the screw instability of the magnetic field in the black hole (BH) magnetosphere. The screw instability in the Blandford-Znajek (BZ) process (henceforth the SIBZ) can coexist with the screw instability in the magnetic coupling (MC) process (henceforth the SIMC). It turns out that both the SIBZ and SIMC occur inevitably, provided that the following parameters are greater than some critical values: (1) the BH spin, (2) the power-law index describing the magnetic field at the disk, and (3) the vertical height of the astrophysical load above the equatorial plane of the rotating BH. The features of several GRBs are well fitted. In our model the durations of the long GRBs depend on the evolution time of the half-opening angle. A small fraction of energy is extracted from the BH via the BZ process to power a GRB, while a large fraction of energy is extracted from the BH via the MC process to power an associated supernova. In addition, the variability timescales of tens of milliseconds in the light curves of the GRBs are fitted by two successive flares due to the SIBZ.

Subject headings: accretion, accretion disks — black hole physics — gamma rays: bursts — instabilities — magnetic fields — supernovae: general

1. INTRODUCTION

Recently, observations and theoretical considerations have linked long-duration GRBs with ultrabright Type Ib/c SNe (Galama et al. 1998, 2000; Bloom et al. 1999). The first candidate was provided by SN 1998bw and GRB 980425, and the recent HETE-2 burst GRB 030329 has greatly enhanced the confidence in this association (Stanek et al. 2003; Hjorth et al. 2003). Extremely high energy released in very short timescales suggests that GRBs involve the formation of a BH via a catastrophic stellar collapse event or possibly a neutron star merger, implying that an inner engine could be built on an accreting BH.

Among a variety of mechanisms of powering GRBs, the BZ process (Blandford & Znajek 1977) has the unique advantage of providing “clean” (free of baryonic contamination) energy by extracting rotating energy from a BH and transferring it in the form of Poynting flow in the outgoing energy flux (Lee et al. 2000; Li 2000c).

Not long ago, Brown et al. (2000) worked out a specific scenario for a GRB-SN connection. They argued that the GRB is powered by the BZ process and that the SN is powered by the MC process, which is regarded as one of the variants of the BZ process (Blandford 1999; van Putten 1999; Li 2000b, 2002; Wang et al. 2002). It is shown in Brown et al. (2000) that about $10^{52}$ ergs are available to power both a GRB and an SN. However, they failed to distinguish the fractions of the energy for these two objects.

More recently, van Putten and his collaborators (van Putten 2001; van Putten & Levinson 2003) worked out a poloidal topology for the open and closed magnetic field lines, in which the separatrix on the horizon is defined by a finite half-opening angle. The duration of a GRB is set by the lifetime of the rapidly splitting BH. They found that GRBs and SNe are powered by a small fraction of the BH spin energy. This result is consistent with observations, i.e., durations of GRBs of tens of seconds, true GRB energies distributed around $5 \times 10^{50}$ ergs (Frail et al. 2001), and aspherical SNe kinetic energies of $2 \times 10^{52}$ ergs (Hofflich et al. 1999).

Very recently, Lei et al. (2005) proposed a scenario for GRBs in Type Ib/c SNe, invoking the coexistence of the BZ and MC processes. In Lei et al. (2005) the GRB is powered by the BZ process and the associated SN is powered by the MC process. The overall timescale of the GRB is fitted by the duration of the open magnetic flux on the horizon.

Besides the feature of high energy released in very short durations, most GRBs are highly variable, showing very rapid variations in flux on a timescale much shorter than the overall duration of the burst. Variability on a timescale of milliseconds has been observed in some long bursts (Norris et al. 1996; McBreen et al. 2001; Nakar & Piran 2002). Unfortunately, the origin of the variations in the fluxes of GRBs remains unclear. In this paper we intend to discuss the mechanism for producing the variations in the fluxes of GRBs by virtue of the screw instability in the BH magnetosphere.

It is well known that magnetic field configurations with both poloidal and toroidal components can be screw unstable. According to the Kruskal-Shafranov criterion, the screw instability will occur if the toroidal magnetic field becomes so strong that the magnetic field line turns around itself once or more (Kadomtsev 1966; Bateman 1978).

Some authors have addressed the screw instabilities in the BH magnetosphere. Gruzinov (1999) argued that a magnetic field with a bunch of closed field lines connecting a Kerr BH with a disk can be screw unstable, resulting in the release of magnetic energy with the flares at the disk. Li (2000a) discussed the screw instability of the magnetic field in the BZ process, leading to a stringent upper bound to the BZ power. Wang et al. (2004, hereafter W04) studied the screw instability in the MC process. They concluded that this instability could occur at some place away from the inner edge of the disk, provided that the BH spin $a_s$ and the power-law index $n$ for the variation of the magnetic field on the disk are greater than some critical values.

In this paper we attempt to combine the screw instability of the magnetic field with the coexistence of the BZ and MC processes. To facilitate the description henceforth, we refer to the screw instability of the magnetic field occurring in the BZ and

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MC processes as the SIBZ and SIMC, respectively. It is shown that both the SIBZ and SIMC can occur, provided that the following parameters are greater than some critical values: (1) the BH spin, (2) the power-law index describing the variation of the magnetic field at the disk, and (3) the vertical height of the astrophysical load above the equatorial plane of the Kerr BH.

The features of several GRB SNe are well fitted in our model. (1) The overall duration of the GRBs is fitted by the evolution of the half-opening angles. (2) The true energies of several GRBs are fitted by the energy extracted in the BZ process, and the energies of associated SNe are fitted by the energy transferred in the MC process. (3) The variability timescales of tens of milliseconds in the light curves of several GRBs are fitted by two successive flares due to the SIBZ.

This paper is organized as follows. In §2 we derive a criterion for the SIBZ based on the Kruskal-Shafranov criterion and some simplified assumptions on the remote load. In §3 we discuss the timescale and energy extraction from a Kerr BH in the context of the suspended accretion state. In §4 we propose a scenario for the origin of the variation in the light curves of GRBs based on the flares arising from the SIBZ. Finally, in §5 we summarize the main results and discuss some issues related to our model. Throughout this paper the geometric units \( G = c = 1 \) are used.

2. SCREW INSTABILITY IN BLACK HOLE MAGNETOSPHERE

In W04 the criterion for the SIMC is derived based on the following points: (1) the Kruskal-Shafranov criterion, (2) the mapping relation between the angular coordinate on the BH horizon and the radial coordinate on the disk, and (3) the calculations of the poloidal and toroidal components of the magnetic field at the disk. The criterion for the SIBZ can be derived in an analogous way. However, the BZ process involves unknown astrophysical loads, to which both the mapping relation and the calculations for the poloidal and toroidal components of the magnetic field are related. In order to work out an analytical model we present the following simplified assumptions.

1. The magnetosphere anchored in a Kerr BH and its surrounding disk is described in Boyer-Lindquist coordinates, in which the poloidal and toroidal components of the magnetic field are related. In order to work out an analytical model we present the following simplified assumptions.

\[
\Sigma^2 = (r^2 + a^2)^2 - a^2 \Delta \sin^2 \theta, \quad \rho^2 = r^2 + a^2 \cos^2 \theta, \quad \Delta = r^2 + a^2 - 2Mr, \quad \varpi = \left( \frac{\Sigma}{\rho} \right) \sin \theta, \quad \alpha = \frac{\rho \sqrt{\Delta}}{\Sigma}.
\]

2. The remote load is axisymmetric, being located evenly in a plane with some height above the disk. In Figure 1 the open magnetic field lines connect the BH horizon with the load. The symbols \( L_{\text{MC}} \) and \( H_c \) represent the critical field line and the height of the remote load above the equatorial plane for the occurrence of the SIBZ, respectively.

3. In Figure 1 the radius \( r_s \) is the critical radius of the SIMC, which is determined by the criterion for the screw instability given in W04,

\[
\left( \frac{2\pi \varpi_D}{L_{\text{MC}}} \right) B_D^p < 1.
\]

In equation (2) \( L_{\text{MC}} \) is the critical length of the poloidal field line for the SIMC, \( B_D^p \) and \( B_D^t \) are the poloidal and toroidal components of the magnetic field on the disk, respectively, and \( \varpi_D \) is the cylindrical radius on the disk, which reads

\[
\varpi_D = \frac{\Sigma_D}{\rho_D} = \sqrt{2} \frac{1}{\chi_{\text{ms}}} \left( 1 + a^2 \xi s \chi_{\text{ms}}^{-1} + \chi_{\text{ms}}^{-2} \right) \chi_{\text{ms}}^{-1},
\]

where \( \chi_{\text{ms}} \equiv (r_{\text{ms}}/M)^{1/2} \) is defined by Novikov & Thorne (1973) in terms of the radius of the innermost stable circular orbit.

4. The angle \( \theta_3 \) in Figure 1 is the half-opening angle of the magnetic flux tube on the horizon, which is related by the mapping relation between the angular coordinate on the BH horizon and the radial coordinate on the disk as follows (Wang et al. 2003):

\[
\cos \theta - \cos \theta_3 = \int_1^\xi G(a_s; \xi, n) d\xi,
\]

where

\[
G(a_s; \xi, n) = \frac{\xi^{1-n} a^2 \chi_{\text{ms}}^{-2}}{\chi_{\text{ms}}^{-1} + \chi_{\text{ms}}^{-2} a^2 \xi s + a^2 \chi_{\text{ms}}^{-1} a^2 \xi s}.
\]

In equations (4) and (5), \( \xi \equiv r/r_{\text{ms}} \) is defined as a radial parameter in terms of \( r_{\text{ms}} \), and \( n \) is a power-law index for the variation of the poloidal magnetic field at the disk, i.e.,

\[
B_D^p \propto \xi^{-n}.
\]

5. The suspended accretion state is assumed due to the transfer of angular momentum from the BH to the disk (van Putten & Ostriker 2001).
Analogous to equation (2), the criterion for the SIBZ can be expressed as

\[ \left( \frac{2\pi R}{L_{BZ}} \right) \frac{B_{L}^{p}}{B_{L}^{T}} < 1, \]  

(7)

where \( L_{BZ} \) is the critical length of the poloidal field line for the SIBZ, \( B_{L}^{p} \) and \( B_{L}^{T} \) are the poloidal and toroidal components of the magnetic field on the remote load, respectively, and \( R \) is the cylindrical radius of the remote load with respect to the symmetric axis of the BH.

The toroidal field component \( B_{L}^{T} \) can be expressed by Ampère’s law,

\[ B_{L}^{T} = \frac{2I_{L}}{R}, \]  

(8)

where \( I_{L} \) is the electric current flowing in the loop \( KMM'K' \) in Figure 1, which reads

\[ I_{L} = \sqrt{\frac{P_{BZ}}{Z_{L}}}. \]  

(9)

The quantities \( P_{BZ} \) and \( Z_{L} \) in equation (9) are the BZ power and the load resistance, respectively. The BZ power has been derived in Wang et al. (2002) as

\[ \frac{P_{BZ}}{P_{0}} = 2d^{2} \int_{0}^{\theta_{s}} k(1 - k) \sin^{3}\theta d\theta \]  

(10)

where \( q \equiv (1 - a^{2})^{1/2} \) is a parameter depending on the BH spin, and \( k \equiv \Omega_{B}/\Omega_{H} \) is the ratio of the angular velocity of the field lines to that of the BH horizon. The quantity \( P_{0} \) is defined as

\[ P_{0} \equiv (B_{H}^{p})^{2}M^{2} \approx 6.59 \times 10^{50} \times B_{15}^{2}(M/M_{\odot})^{2} \text{ ergs s}^{-1}, \]  

(11)

where \( B_{15} \) represents the magnetic field at the BH horizon in terms of \( 10^{15} \) G.

MT82 argued in a speculative way that the ratio \( k \) will be regulated to about 0.5 by the BZ process itself, which corresponds to the optimal BZ power with impedance matching. Taking impedance matching into account, we have the remote load resistance equal to the horizon resistance, and they read

\[ \Delta Z_{L} = \Delta Z_{H} = R_{H} \frac{\rho_{H} \, d\theta}{2\pi \varpi_{H}}, \]  

(12)

where \( R_{H} = 4\pi = 377 \) ohms is the surface resistivity of the BH horizon (MT82). Thus, we have \( Z_{L} \) and \( Z_{H} \) expressed as

\[ Z_{L} = Z_{H} = \int_{0}^{\theta_{s}} R_{H} \frac{\rho_{H} \, d\theta}{2\pi \varpi_{H}} = \int_{0}^{\theta_{s}} 2\rho_{H} \, d\theta/\varpi_{H}. \]  

(13)

Incorporating equations (8)–(13), we can calculate \( B_{L}^{p} \) in terms of the cylindrical radius \( R \). On the other hand, the poloidal magnetic field \( B_{L}^{p} \) at the radius \( R \) of the load can be determined by the conservation of the magnetic flux, i.e.,

\[ B_{L}^{p} 2\pi \varpi_{H} \rho_{H} \, d\theta = B_{L}^{T} 2\pi R \, dR. \]  

(14)

From equation (14) we have

\[ B_{L}^{p} = \frac{B_{L}^{T} \varpi_{H} \rho_{H}}{R} \, d\theta/\, dR. \]  

(15)
Assuming that the height of the planar load above the equatorial plane of the Kerr BH is \( H \), we have an approximate relation between the angle \( \theta \) and the radius \( R \),

\[
\tan \theta = R/H.
\]

(16)

Substituting equation (16) into equation (15), we have

\[
B_L^\perp = \frac{B_H^\perp \sin \theta S \cos^2 \theta}{HR}.
\]

(17)

Incorporating equations (8) and (17) with criterion (7), we have

\[
\frac{\pi B_H^\perp \sin \theta S \cos^2 \theta S}{H \sqrt{P_{BZ}/Z_L}} < 1,
\]

(18)

where the relation \( \sin \theta_S = R/L_{BZ} \) is used. Criterion (18) implies that the SIBZ will occur, provided that the height of the load is greater than the critical height, i.e., \( H > H_c \), and we have

\[
h_c \equiv \frac{H_c}{M} = \frac{\pi B_H^\perp \sin \theta S \cos^2 \theta S}{M \sqrt{P_{BZ}/Z_L}}.
\]

(19)

As argued in W04 the angle \( \theta_S \) can be determined by the criterion for the SIMC with the mapping relation between the BH horizon and the disk, and it is a function of the BH spin \( a_\ast \) and the power-law index \( n \), i.e., \( \theta_S(a_\ast, n) \). Inspecting equations (1), (10), and (19), we find that \( h_c \) is a dimensionless parameter also depending on the parameters \( a_\ast \) and \( n \), i.e., \( h_c = h_c(a_\ast, n) \). By using equations (2) and (19) we have the contours of \( \theta_S(a_\ast, n) \) and \( h_c(a_\ast, n) \) in \( a_\ast-n \) parameter space as shown in Figure 2.

Inspecting Figure 2, we find the following features of the contours:

1. The values of \( \theta_S \) increase and those of \( h_c \) decrease with increasing \( n \) for the given BH spin \( a_\ast \).
2. The values of \( \theta_S \) increase and those of \( h_c \) decrease with increasing \( a_\ast \) for the given \( n \).
3. Both the SIMC and SIBZ will occur, provided that the parameters \( a_\ast \) and \( n \) in which both \( \theta_S > 0 \) and \( h_c > 100 \) are constrained. Thus, the occurrence of the SIMC and SIBZ is guaranteed by the value ranges of \( a_\ast \) and \( n \) in the shaded region.

3. TIMESCALE OF A GAMMA-RAY BURST

AND ENERGY EXTRACTION FROM

A ROTATING BLACK HOLE

There are several scenarios for invoking the BZ process for powering GRBs, and the main differences among these scenarios lie in the environment of a spinning BH and the approaches to the duration of a GRB. These scenarios are outlined as follows.

Model I.—In Lee et al. (2000) the energy is extracted magnetically from a rotating BH without a disk, and the duration of the GRB is estimated as the time needed for extracting all the rotational energy of the central BH via the BZ process.

Model II.—Here it is argued that the energy is extracted magnetically from a rotating BH with a transient disk, and the duration of the GRB is estimated as the time it takes for the disk to plunge into the BH (Lee & Kim 2002; Wang et al. 2002).

Model III.—In Li (2000c) the energy is extracted magnetically from a rotating BH with a stationary torus in a state of suspended accretion, and the duration of the GRB is estimated as the time needed for extracting all the rotational energy of the central BH via the BZ process.

Model IV.—In Brown et al. (2000) the energy is extracted magnetically from a rotating BH with a nonstationary disk in a state of suspended accretion, and the duration of the GRB is determined by the presence of the disk.

Model V.—In van Putten & Levinson (2003) the energy is extracted magnetically from a rotating BH with a torus in a state of suspended accretion, and the duration of the GRB is determined by the instability of the disk.

Model VI.—In Lei et al. (2005) the energy is extracted magnetically from a rotating BH with a thin disk in a state of suspended accretion, and the duration of the GRB is determined by the lifetime of the half-opening angle.

This model.—It is a modified version of model VI in which the effects of the SIMC and SIBZ are taken into account. Compared with model VI some features and advantages are given as follows:

1. The magnetic field configuration in model VI is built based on the conservation of the closed magnetic flux connecting the BH with the disk with precedence over open magnetic flux, resulting in closed field lines connecting the half-opening angle \( \theta_{BZ} \) at the horizon with the disk extending to infinity. In this model, however, the closed field lines are confined by the SIMC within a region of a limited radius \( r_S \) (about a few Schwarzschild radii, as shown in Table 4), which is consistent with the collapsar model of GRB SNe.

2. As argued in § 4, the variability timescales of the light curves of GRBs are modulated by two successive flares due to the SIBZ.

The main features of the above models of GRBs are summarized in Table 1. In model VI the duration of a GRB is regarded as the lifetime of the half-opening angle \( \theta_{BZ} \), which is based on the evolution of the rotating BH. The same procedure can be applied to this model, except that the angle \( \theta_{BZ} \) is replaced by \( \theta_S \) arising from the SIMC. It is found that the

| Model     | BZ Process | MC Process | Surrounded by | Objects | Half-Opening Angle | Variability |
|-----------|------------|------------|---------------|---------|--------------------|-------------|
| I…………… | Yes        | No         | No disk       | GRB     | No                 | No          |
| II…………… | Yes        | No         | Transient disk| GRB     | No                 | No          |
| III…………… | Yes        | No         | Torus         | GRB     | No                 | No          |
| IV…………… | Yes        | Yes        | Disk          | GRB/SN  | Yes                | No          |
| V…………… | Yes        | Yes        | Torus         | GRB/SN  | Yes                | No          |
| VI…………… | Yes        | Yes        | Disk          | GRB/SN  | Yes                | No          |
| This model | Yes        | Yes        | Disk          | GRB/SN  | Yes                | Yes         |
The fractions of extracted energy from a rotating BH via the BZ and MC processes are defined, respectively, as \( f_{\text{BZ}} \) and \( f_{\text{MC}} \), and they read

\[
f_{\text{BZ}} = \frac{E_{\text{BZ}}}{E_{\text{BZ}} + E_{\text{MC}}}, \quad f_{\text{MC}} = \frac{E_{\text{MC}}}{E_{\text{BZ}} + E_{\text{MC}}},
\]

where \( E_{\text{BZ}} \) and \( E_{\text{MC}} \) are the energies extracted in the BZ and MC processes, respectively:

\[
E_{\text{BZ}} = \int_0^{t_{\text{BZ}}} P_{\text{BZ}} \, dt, \quad E_{\text{MC}} = \int_0^{t_{\text{MC}}} P_{\text{MC}} \, dt.
\]

In equation (21), \( t_{\text{BZ}} \) is defined as the lifetime of the angle \( \theta_S \), which can be calculated by the same procedure as given in Lei et al. (2005). The MC power in equation (21) is expressed as (W04)

\[
\frac{P_{\text{MC}}}{P_0} = 2a_s^2 \int_{\theta_S}^{\beta} \frac{\beta(1 - \beta) \sin^3 \theta \, d\theta}{2 - (1 - \eta) \sin^2 \theta},
\]

where the parameter \( \beta = \Omega_e/\Omega_H = \Omega_D/\Omega_H \) is the ratio of the angular velocity of the magnetic field lines to that of the BH.

In model VI the BH spin \( a_s^{\text{GRB}} \) corresponds to the time when the half-opening angle \( \theta_{\text{BZ}} = 0 \) and the BZ power \( P_{\text{BZ}} = 0 \), while \( a_s^{\text{SN}} \) corresponds to the MC power \( P_{\text{MC}} = 0 \). In this model, \( a_s^{\text{GRB}} \) and \( a_s^{\text{SN}} \) have the same meanings as given in model VI, except that \( \theta_{\text{BZ}} \) is replaced by \( \theta_S \).

In Table 3 the values of \( a_s^{\text{GRB}}, f_{\text{BZ}}, \) and \( f_{\text{MC}} \) fitted to five GRBs invoking model VI and this model are shown in the left and right subcolumns, respectively.

Inspecting the data in the left and right subcolumns of Tables 2 and 3, we find that \( f_{\text{BZ}} \) and \( f_{\text{MC}} \) in this model are greater and less than their counterparts in model VI, respectively. This result arises from the effects of the SIMC and SIBZ. The half-opening angle \( \theta_S \) in this model is greater than the half-opening angle \( \theta_{\text{BZ}} \) in model VI, as argued in W04.

4. AN EXPLANATION OF VARIABILITIES IN GAMMA-RAY BURST LIGHT CURVES

As is well known, the bursts are divided into long and short bursts according to their \( T_{90} \) values. Most GRBs are highly variable, showing 100% variations in flux on a timescale much shorter than the overall duration of the burst. The bursts seem to be composed of individual pulses, with a pulse being the "building block" of the overall light curve. The variability timescale \( \delta t \) is much shorter than the GRB duration \( T_{90} \); the former is more than a factor of \( 10^4 \) smaller than the latter (Piran 2004). However, the origin of the variability in the light curves of GRBs remains unclear.

In this paper, we combine the variability with the screw instability of the magnetic field in the BH magnetosphere and suggest that the variability could be fitted by a series of flares arising from the SIBZ, which accompanies the release of the energy of the toroidal magnetic field.

An equivalent circuit \( MLL'M' \) for the SIBZ is shown in Figure 4a, which consists of two adjacent magnetic surfaces \( MM' \) and \( LL' \) connecting the BH horizon and the remote load. An inductor is introduced in the equivalent circuit by considering that the toroidal magnetic field threads the loop \( MLL'M' \), and the inductor is represented by the symbol \( \Delta L \) in Figure 4a.
The inductance $\Delta L$ in the circuit is defined by

$$\Delta L = \frac{\Delta \Psi^T}{I_L},$$

where $I_L$ is given by equation (9) and $\Delta \Psi^T$ is the flux of the toroidal magnetic field threading the circuit. The flux $\Delta \Psi^T$ can be integrated over the loop $MLL'M'$ as follows:

$$\Delta \Psi^T = \oint_{\text{loop}} B^T \sqrt{g_{rr} g_{\theta \theta}} \, dr \, d\theta,$$

where the toroidal magnetic field measured by “zero-angular-momentum observers” is

$$B^T = 2I_L/(\alpha \omega),$$

where $\alpha$ is the lapse function defined in equation (1) (MT82).

Since the geometric shapes of the magnetic surfaces are unknown, we assume that the surfaces are formed by rotating the two radial segments $MM'$ and $LL'$, which span the angle $\Delta \theta$ as shown in Figure 4b. Thus the flux $\Delta \Psi^T$ can be calculated easily by integrating over the region $MLL'M'$. Incorporating equations (23)–(25), we obtain $\Delta L$ as follows:

$$\Delta L = 2 \csc \theta \Delta \theta \int_{r_{\text{H}}}^{r_{\text{H}}/M} \rho^2 \, d\rho \int_{\Delta}^{r_{\text{ad}}} \left(\frac{\rho^2}{r^2 + a^2} \cos^2 \theta_S\right) \, dr,$$

where $\tilde{r}$ is defined as $\tilde{r} \equiv r/M$.

Although the detailed process of the SIBZ is still unclear, we suggest that the energy release in one SIBZ event is roughly divided into two stages: the processes of releasing and retrieving magnetic energy. The two processes can be simulated as the corresponding processes in the equivalent $R-L$ circuit. A detailed analysis is given as follows.

In the first stage, the energy of the toroidal magnetic field is released as soon as the SIBZ occurs, being dissipated on the load and plasma fluid in the way analogous to a discharging process in an equivalent $R-L$ circuit. The equation governing the discharging process in the $R-L$ circuit is

$$\Delta L \frac{dI^P}{dt} + (\Delta Z_{\text{plasm}} + \Delta Z_L)I^P = 0,$$

where $\Delta Z_{\text{plasm}}$ is the resistance of the plasma fluid in the BH magnetosphere.

At the second stage, the energy of the toroidal magnetic field is recovered due to the rotation of the BH, and the process of retrieving the magnetic energy is modulated by a charging process in an equivalent $R-L$ circuit. The equation governing the charging process in the $R-L$ circuit is

$$\Delta L \frac{dI^P}{dt} + (\Delta Z_{\text{H}} + \Delta Z_L)I^P = \Delta E_H.$$

In equations (27) and (28), $\Delta L$ is the inductance in the circuit $MLL'M'$ and $\Delta Z_{\text{plasm}}$ is the resistance of the plasma in the BH magnetosphere.
Fig. 4.—(a) An equivalent R-L circuit consisting of two magnetic surfaces, $MM'$ and $LL'$, which connect the BH horizon and the remote load; (b) a simplified configuration of the poloidal magnetic field corresponding to the equivalent R-L circuit.

| GRB      | Parameters | $a_*$ | $n$  | $r_s$ | $h_*$ | $T_{90}$ (s) | Variability Timescale (ms) |
|----------|------------|-------|------|-------|-------|--------------|-----------------------------|
|          |            |       |      |       |       |              | $\delta t_{III}$ $\delta t_{II}$ $\delta t_{I}$ |
| 970508...| 0.9        | 3.46  | 5.96 | 87.71 | 15    | 13.42        | 26.84 40.25                |
| 990712...| 0.9        | 3.54  | 6.45 | 85.56 | 30    | 13.23        | 26.46 39.68                |
| 991208...| 0.9        | 3.55  | 6.52 | 87.71 | 39.84 | 13.42        | 26.83 40.25                |
| 991216...| 0.9        | 3.58  | 6.77 | 87.70 | 7.51  | 13.42        | 26.83 40.25                |
| 021211...| 0.9        | 3.42  | 5.77 | 59.32 | 13.3  | 10.90        | 21.80 32.70                |

Note.—The quantity $r_s \equiv r_s/M$ is the critical dimensionless radius for the SIMC.
have BH magnetosphere. Incorporating equations (12) and (26), we have
\[
\frac{\Delta L}{\Delta Z_H} = \left(9.85 \times 10^{-6} \text{ s}\right) \frac{(M/M_\odot)}{2 - (1 - q) \sin^2 \theta_S} \\
\times \int_{(1+q)}^{\beta_{\text{miz}}/M} \frac{r^2 + a_z^2 \cos^2 \theta_S}{(r^2 + a_z^2 - 2\beta r)} \, d\beta.
\]  
(29)

Combining the initial conditions in the first and second stages, we have the solutions of equations (27) and (28) as follows:
\[
P_{\text{disch}}^p = P_{\text{initial}}^p e^{-t/\tau_1},
\]
(30)
\[
P_{\text{ch}}^p = P_{\text{steady}}^p \left(-e^{-t/\tau_2}\right).
\]
(31)

In equations (30) and (31), \(P_{\text{initial}}^p\) and \(P_{\text{steady}}^p\) are the initial and steady currents, respectively, while \(P_{\text{disch}}^p\) and \(P_{\text{ch}}^p\) represent the discharging and charging currents, respectively. The characteristic timescales in equations (30) and (31) are given respectively by \(\tau_1\) and \(\tau_2\), and they read
\[
\tau_1 \equiv \frac{\Delta L}{(\Delta Z_{\text{plsm}} + \Delta Z_L)},
\]
(32)
\[
\tau_2 \equiv \frac{\Delta L}{(\Delta Z_H + \Delta Z_L)}.
\]
(33)

From equations (32) and (33) we have the ratio of \(\tau_1\) to \(\tau_2\) given by
\[
\tau_1/\tau_2 = 2\Delta Z_H/(\Delta Z_{\text{plsm}} + \Delta Z_H),
\]
(34)
where \(\Delta Z_H = \Delta Z_L\) is used in deriving equation (34).

In contrast to a disk plasma of perfect conductivity, the resistance \(\Delta Z_{\text{plsm}}\) cannot be neglected based on the following considerations:

1. The plasma fluid becomes very tenuous after leaving the inner edge of the disk, augmenting significantly the resistance due to an increasing radial velocity onto the BH.
2. The conductivity of the plasma fluid is highly anisotropic; i.e., the conductivity in the cross-field direction is greatly impeded by the presence of the strong magnetic threading of the BH (Punsly 2001).

Although the value of \(\Delta Z_{\text{plsm}}\) is unknown, we can estimate roughly the variability timescales of GRBs by combining equation (34) with different cases given as follows:

Case I.—\(\Delta Z_{\text{plsm}} \gg \Delta Z_H\) leads to \(\tau_1 \ll \tau_2\), and the timescale of two successive flares arising from the SIBZ is dominated by \(\tau_2\).

Case II.—\(\Delta Z_{\text{plsm}} \approx \Delta Z_H\) leads to \(\tau_1 \approx \tau_2\), and the timescale of two successive flares arising from the SIBZ is about \(2\tau_2\).

Case III.—\(\Delta Z_{\text{plsm}} \ll \Delta Z_H\) leads to \(\tau_1 \approx 2\tau_2\), and the timescale of two successive flares arising from the SIBZ is about \(3\tau_2\).

Therefore the variability timescales are insensitive to the values of the unknown \(\Delta Z_{\text{plsm}}\). From equation (31) we obtain that the charging current attains 99.3% of \(I_{\text{steady}}\) in the relax time \(t_{\text{relax}} = 5\tau_2\), implying the recovery of the toroidal magnetic field, and the variability timescales of GRBs can be estimated as follows:
\[
(\delta t)_1 \equiv (t_{\text{SIBZ}})_1 \approx 5\tau_2, \quad \text{for} \quad \Delta Z_{\text{plsm}} \gg \Delta Z_H,
\]
(35)
\[
(\delta t)_2 \equiv (t_{\text{SIBZ}})_2 \approx 10\tau_2, \quad \text{for} \quad \Delta Z_{\text{plsm}} \approx \Delta Z_H,
\]
(36)
\[
(\delta t)_3 \equiv (t_{\text{SIBZ}})_3 \approx 15\tau_2, \quad \text{for} \quad \Delta Z_{\text{plsm}} \ll \Delta Z_H.
\]
(37)

In case I we have \(\tau_1 \ll \tau_2\), implying that the magnetic energy is released much more rapidly in the first stage compared with the time for the recovery of the magnetic energy in the second stage. Thus case I seems more consistent with the features of the light curves, i.e., that an individual pulse has a fast rise, exponential

![Fig. 5.—Curves of (\delta t) vs. \(a_*\) with \(n = 3.54\), 3.55, and 3.58 for (a) GRB 990712, (b) GRB 991208, and (c) GRB 991216, respectively.](image)
decay (FRED) profile, with an average rise-to-decay ratio of 1:3 (Norris et al. 1996).

By using equations (29), (33), and (35)–(37), we have the variability timescales in the light curves of four GRBs in the three different cases, as shown in Table 4. In addition, we obtain the curves of \( \delta t_1 \) versus \( a_1 \) with fixed values of \( n \) for GRB 990712, GRB 991208, and GRB 021216, as shown in Figure 5.

Inspecting Table 4, we find that the variability timescales of tens of milliseconds in the light curves of GRBs can be modulated by the two successive flares due to the SIBZ, which accompany the BZ process in powering the GRBs. We also find that the variability timescales of the four GRBs are generally 3 orders of magnitude less than the corresponding durations \( t_{90} \), which are consistent with the observations.

From Figure 5 we find that the curves of \( \delta t_1 \) versus \( a_1 \) are almost the same, increasing linearly in a rather small slope with decreasing \( a_1 \). The values of \( \delta t_1 \) remains less than 20 ms during the occurrence of the SIBZ for these GRBs.

5. DISCUSSION

5.1. Mechanism for the Recurrent Occurrence of SIBZ

In this paper we discuss the possibility of the modulations of the SIBZ on the light curves of GRBs. One of the puzzles is, what mechanism leads to the recurrent occurrence of the SIBZ and prevents the magnetic field from settling to a screw-stable configuration?

As argued in MT82, the BH magnetosphere consists of a series of magnetic surfaces connecting the horizon with the loads, and the total electric current \( I \) flowing downward through an \( m \)-loop is proportional to the toroidal magnetic field \( B_T \) by Ampère’s law. It is argued that these magnetic surfaces can be regarded as an equivalent circuit, in which each loop consists of two adjacent magnetic surfaces (Wang et al. 2002). The total electric current flowing downward through an \( m \)-loop is exactly equal to the algebraic sum of the poloidal currents flowing in the loops (Wang et al. 2003).

As shown in Figure 1, the critical magnetic surface (CMS) for the SIBZ is represented by the critical line \( M' \). According to criterion (7), only the toroidal magnetic field outside the CMS is depressed by the SIBZ, while the toroidal and poloidal components of the magnetic field within the CMS are little affected. On the other hand, the poloidal magnetic field outside the CMS still exists in spite of the occurrence of the SIBZ, and the toroidal magnetic field outside the CMS will be recovered because of the twist of the poloidal magnetic field arising from the rotation of the BH. So, the rotation of the BH is the main mechanism for the recurrent occurrence of the SIBZ in the BH magnetosphere.

5.2. Rotation Period of the BH and Timescales of Recovery of Toroidal Magnetic Fields

If we take the BH mass as \( 10 M_{\odot} \), the rotation period of the BH is only \( \sim 1 \) ms for the BH spin required by the criterion for the SIBZ. This result implies that toroidal magnetic fields cannot be recovered in one period of a rotating BH. How can we explain the discrepancy between BH rotation and the timescales required for recovery of the toroidal fields?

In spite of the lack of detailed knowledge of the screw instability, it is helpful to imagine the magnetic field line as an elastic string. The rotating BH always twists the field line, while the field line tries to untwist itself. Once the toroidal component of the magnetic field is strong enough to satisfy the criterion, the screw instability will occur, just as a twisted elastic string releases its energy under appropriate conditions. In our model we simulate the process of twisting the field line as a transient process of accumulating magnetic energy in the inductor \( \Delta L \). In the equivalent \( R-L \) circuit, which corresponds to the increase of the toroidal magnetic field, and the variability timescales of tens of milliseconds in the light curves of several GRBs are fitted as the time interval between two successive flares due to the SIBZ. Thus the threshold of the toroidal magnetic field (magnetic energy) cannot be recovered in only one rotation of BH, just as a threshold of twisting more than one turn is required for an elastic string to release its energy.

5.3. An Explanation for GRBs with XRFs and XRRs

Recently, much attention has been paid to the issue of X-ray flashes (XRFs), X-ray-rich gamma-ray bursts (XRRs), and GRBs, since \textit{HETE-2} provided strong evidence that the properties of these three kinds of bursts form a continuum and therefore that these objects are probably the same phenomenon (Lamb et al. 2004a, 2004b, 2005). The observations from \textit{HETE-2} motivate some authors to seek a unified model of these bursts. The most competitive unified models of these bursts are the off-axis jet model (Yamazaki et al. 2002; Lamb et al. 2005) and the two-component jet model (Berger et al. 2003; Huang et al. 2004), in which XRFs, XRRs, and GRBs arise from differences in the viewing angles. Unfortunately, a detailed discussion on producing different viewing angles for XRFs, XRRs, and GRBs was not given in the above works.

Our argument on the SIBZ and SIMC may be helpful in understanding this issue. It is believed that a disk is probably surrounded by a high-temperature corona analogous to the solar corona (Liang & Price 1977; Haardt & Maraschi 1991; Zhang et al. 2000). Very recently, some authors have argued that coronal heating in some stars, including the Sun, is probably related to the dissipation of currents and that very strong X-ray emissions arise from the variation of magnetic fields (Galsgaard & Parnell 2004; Peter et al. 2004). Analogously, if the corona exists above the disk in our model, we expect that it might be heated by the induced currents due to the SIMC and SIBZ. Therefore a very strong X-ray emission would be produced to form XRFs or XRRs.

Although our model may be too simplified and idealized with respect to the real situation, it provides a possible scenario for the occurrence of the screw instability in the BH magnetosphere, and it may be helpful in understanding some astrophysical observations. We hope to improve our model by combining more observations in the future.

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