The bends on a quantum waveguide and cross-products of Bessel functions

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Abstract

A detailed analysis of the wave-mode structure in a bend and its incorporation into a stable algorithm for calculation of the scattering matrix of the bend is presented. The calculations are based on the modal approach. The stability and precision of the algorithm is numerically and analytically analysed. The algorithm enables precise numerical calculations of scattering across the bend. The reflection is a purely quantum phenomenon and is discussed in more detail over a larger energy interval. The behaviour of the reflection is explained partially by a one-dimensional scattering model and heuristic calculations of the scattering matrix for narrow bends. In the same spirit, we explain the numerical results for the Wigner–Smith delay time in the bend.

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(Some figures in this article are in colour only in the electronic version)

1. Introduction

The wave propagation in bent waveguides has a long and rich history of research that dates back to Lord Rayleigh [1] and continues to the present days. Initially bends have been investigated in the framework of the electromagnetic theory, but more recently also quantum-mechanical aspects attracted a lot of attention. The bends are a popular subject of investigation because they are typical elements incorporated into designs of waveguides. The computation of their properties to sufficiently high precision seems to be a difficult problem in the regimes of high energies and high curvatures even today.

We are discussing a bend as a scatterer of non-relativistic quantum waves on a two-dimensional ideal straight waveguide as shown in figure 1. Such a structure is referred to as an open billiard. The past research of quantum aspects of bends can be separated into two branches. These are studies of bound states, their existence [2–4] and spectra [5] and the scattering properties, which are both reviewed in [6]. In order to describe quantum
phenomena over our open billiard several approaches have been used in the past: Green function approach [7], finite difference mesh calculations [8] and mode-matching techniques (MMT) using natural modes i.e. eigenfunctions of the Laplacian in the bend [5, 9–13] and other bases [14]. The work [5] is particularly interesting as it raises the question on how to stabilize the calculations and gives a MMT method that is stable, but unfortunately a bit ambiguous. The MMT based on natural modes is called the modal approach and is the main topic of discussion in the present paper. The modal approach looks the most promising to deal with bends because of its simplicity, power of interpretation and precision of results. But it also hides some problems that we examine here in detail.

Let us introduce the modal approach in our open billiard composed of a bend, with the inner radius \( r = q \) and the outer radius \( r = 1 \), and a straight waveguide of width \( a = 1 - q \) as shown in figure 1. The area of the billiard, denoted by \( \Omega \), can be separated into three sections: A—the left lead, B—the bend and C—the right lead. We are searching for the wavefunction \( \psi(\mathbf{r} \in \Omega) \), which solves the stationary Schrödinger (Helmholtz) equation on \( \Omega \) with Dirichlet boundary conditions reading

\[
-\Delta \psi(\mathbf{r}) = k^2 \psi(\mathbf{r}), \quad \psi|_{\mathbf{r} \in \partial \Omega} = 0, \tag{1}
\]

where \( E = k^2 \) is the energy and \( k \) is the corresponding wavenumber. The Helmholtz equation (1) is written in Cartesian coordinates \( \mathbf{r} = (x, y) \) in the asymptotic regions A and C as

\[
\left( \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) \psi = k^2 \psi, \quad \psi|_{y=0,1-q} = 0, \tag{2}
\]

and in polar coordinates \( \mathbf{r} = (r, \phi) \) across the bend B as

\[
\left( \frac{\partial^2}{\partial r^2} + \frac{1}{r} \frac{\partial}{\partial r} + \frac{1}{r^2} \frac{\partial^2}{\partial \phi^2} \right) \psi = k^2 \psi, \quad \psi|_{r=q,1} = 0. \tag{3}
\]

The modal approach suggests that we first solve Helmholtz equation (1) on each region of the open billiard separately. Thereby we obtain partial solutions called mode functions,
which are then used to describe the solution across the whole billiard. In the infinite straight waveguide and in the bend the mode functions are given by the ansätze \( \psi \propto u(y) \exp(\mathrm{i} gx) \) and \( \psi \propto U(r) \exp(\mathrm{i} \nu \phi) \), respectively. The ansätze in equations (2) and (3) give the following equations for the mode functions:

\[
\frac{d^2 u}{dy^2} + (k^2 - g^2) u = 0, \quad u|_{y=0,a} = 0, \quad y \in [0, a],
\]

\[
\frac{d^2 U}{dr^2} + \frac{1}{r} \frac{dU}{dr} + \left( k^2 - \frac{\nu^2}{r^2} \right) U = 0, \quad U|_{r=q,1} = 0, \quad r \in [q, 1],
\]

where \( a = 1 - q \) is the channel’s width and the scalars \( g, \mu \in \mathbb{C} \) are called mode numbers. Equations (4) and (5) have a discrete set of solutions i.e. the mode functions and the corresponding mode numbers, which we refer to as modes.

The modes in the straight waveguide and in the bend are denoted by pairs \((g_n, u_n(y))\) and \((\nu_p, U_p(r))\), respectively, where \( p, n \in \mathbb{N} \). The modes in the straight waveguide are explicitly written as

\[
k^2 = g_n^2 + \left( \frac{\pi n}{a} \right)^2, \quad u_n(x) = \sqrt{\frac{2}{a}} \sin \left( \frac{\pi n x}{a} \right),
\]

whereas modes in the bend are more complicated. They are discussed in section 2, where we also show that mode numbers are either real or imaginary. The mode functions \( u_n(y) \) and \( U_p(r) \) are then used in the bases of functions in which we expand waves over parts of the waveguide. The basis in the straight waveguide is given by

\[
e_{\pm}^\dagger(r) = u_n(y) \frac{\exp(\pm \mathrm{i} g_n x)}{\sqrt{g_n}},
\]

and in the bend by

\[
f_{\pm}^\dagger(r) = U_p(r) \frac{\exp(\pm \mathrm{i} \nu_p \phi)}{\sqrt{\nu_p}},
\]

where the sign \( \pm \) labels the two directions of phase (probability) flux propagation. We define the square-root of a complex number \( z = |z| \exp(\mathrm{i} \phi) \), \( \phi \in [0, 2\pi) \) as \( \sqrt{z} = |z|^{1/2} \exp(\mathrm{i} \phi/2) \). The basis functions are called wave modes or modes of the Laplacian. We distinguish two types of wave modes. The wave modes corresponding to real and imaginary mode numbers are called open modes or travelling waves and closed modes or decaying (evanescent) waves, respectively. The wavefunction \( \psi(r) \) (1) in the entire open billiard region \( \Omega \) is expressed in terms of the wave modes as

\[
\psi(r) = \sum_n a_n^+ e_n^+ (r) + a_n^- e_n^- (r), \quad r \in \Omega_A,
\]

\[
\psi(r) = \sum_p \lambda_p^+ f_p^+ (r) + \lambda_p^- f_p^- (r), \quad r \in \Omega_B,
\]

\[
\psi(r) = \sum_n b_n^+ e_n^+ (r) + b_n^- e_n^- (r), \quad r \in \Omega_C,
\]

where \( \Omega_{A,B,C} \) are regions corresponding to sections A, B and C, respectively. The expansion coefficients \( a_n^\pm, \lambda_p^\pm \) and \( b_n^\pm \) are determined by the condition that the wavefunction \( \psi(\vec{r}) \) is smooth everywhere in \( \Omega \), in particular on the boundaries between different regions \( \Omega_{A,B,C} \). The solution of the presented problem will be discussed in section 3.
This paper is organized as follows. In section 2, we present a detailed study of the mode structure in the bend, which is closely related to the work of Cochran [15–17]. In comparison to the work of others, ours is directed more towards the application of the mode structure to scattering calculations. In addition, we write explicit formulae for the mode functions in the bend, where we give special attention to the closed modes. In section 3, we outline a numerically stable MMT for calculation of the scattering matrix [18] of a single bend. The section 3 is concluded with the presentation of numerical results obtained by our method and compared to analytic estimates of the quantum transport properties of the bend. By considering the analogy between the quantum theory and EM theory we can connect our work to the EM wave propagation of longitudinal magnetic waves [9].

2. The cross-product of Bessel functions

In this section, we analyse the properties of the mode numbers and the corresponding mode functions for a given wavenumber \( k \) and inner radius \( q \). The mode functions in the bend \( U_p(r) \) are proportional to well-known cross-products of Bessel functions [15] of the first kind, \( J_\nu \), and Bessel functions of the second kind, \( Y_\nu \), [19] written as

\[
Z_\nu(k, r) = J_\nu(kr)Y_\nu(k) - Y_\nu(kr)J_\nu(k),
\]

or

\[
Z_{\nu,k}(r) = \frac{J_{-\nu}(kr)J_\nu(k) - J_\nu(kr)J_{-\nu}(k)}{\sin(\nu \pi)}, \quad \nu \notin \mathbb{Z},
\]

where the allowed values of mode numbers \( \nu \) are determined by the Dirichlet boundary conditions \( Z_\nu(q) = 0 \). In equation (13) we have used the relation \( Y_\nu(z) = (J_\nu(z) \cos(\nu \pi) - J_{-\nu}(z)) / \sin(\nu \pi) \) valid for orders \( \nu \notin \mathbb{Z} \). The understanding of the mode structure in the bend is essential for calculations of the scattering over our open billiard in the modal approach.

2.1. The properties of mode numbers

The set of mode numbers at a given wavenumber \( k \in \mathbb{R}, k > 0 \) and inner radius \( q \in (0, 1) \) is denoted by \( M_{k,q} = \{ \nu \in \mathbb{C} : Z_{\nu,k}(q) = 0 \} \). The functions \( Z_{\nu,k}(r) \) are even \( Z_{-\nu,k}(r) = Z_{\nu,k}(r) \) and analytic in the order \( \nu \) [16]. These properties yield the following symmetry of the set of mode numbers:

\[
M_{k,q} = -M_{k,q}, \quad M_{k,q}^* = M_{k,q}.
\]

In addition we conclude that mode numbers are either purely real or purely imaginary

\[
M_{k,q} \subset \mathbb{R} \cup i\mathbb{R}.
\]

The number of real modes is finite, whereas the number of imaginary modes is infinite at a finite wavenumber \( k \). The proof of the later is given in appendix A. The properties (14) and (15) enable a decomposition of \( M_{k,q} \) into two disjoint subsets of mode numbers laying on the positive \( M_{k,q,+} \) and the negative \( M_{k,q,-} \) real and imaginary axes:

\[
M_{k,q,+} = \{ \nu \in M_{k,q} : \text{Re } \nu \geq 0 \text{ or Im } \nu \geq 0 \},
\]

\[
M_{k,q,-} = \{ \nu \in M_{k,q} : \text{Re } \nu < 0 \text{ or Im } \nu < 0 \} \subseteq -M_{k,q,+}.
\]

It easy to see that \( M_{k,q} = M_{k,q,+} \cup M_{k,q,-} \). We call \( \text{Re}[M_{k,q,+}] \) and \( \text{Im}[M_{k,q,+}] \) the set of real modes and imaginary modes, respectively. The number of real modes in the bend
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$N_b = \text{card} \Re \{ \mathcal{M}_{k,q,r} \}$ is equal or one more than the number of real modes in the straight waveguide $N_s = \lfloor ka/\pi \rfloor$:

$$0 \leq N_b - N_s \leq 1.$$  \hfill (18)

where $\lfloor x \rfloor$ denotes the largest integer smaller than $x$. Taking into account the analyticity of $Z_{\nu,k}(r)$ in the order $\nu$ and in the wavenumber $k$ [16] we find that $N_b$ can be computed in the semi-classical limit, for $q \neq 0$, as

$$N_b = \left\lfloor \frac{ka}{\pi} + \frac{a}{8\pi qk} + O(k^{-2}) \right\rfloor,$$  \hfill (19)

and $N_s$ is asymptotically, as $k \to \infty$, close to $N_b$. Expressions (18) and (19) are explained in Appendix B. The asymptotic form of $Z_{\nu,k}(r)$ in the order parameter [20] reads as

$$Z_{\nu,k}(r) = \frac{1}{\pi^\nu} [r^\nu O(1) - r^{-\nu} O(1)], \quad |\nu| \gg 1.$$  \hfill (20)

From equation (20) we learn that $Z_{\nu,k}(q)$ diverges exponentially with increasing order parameter as $O(q^{-|\nu|})$ and oscillates along the imaginary axis. This bounds real mode numbers $\Re \{ \mathcal{M}_{k,q,r} \}$ from above and indicates that there is an infinite number of almost periodic imaginary mode numbers.

The mode numbers $\nu \in \mathcal{M}_{k,q}$ and consequently the mode functions can be obtained only numerically. We use different approximations of mode numbers to improve their numerical computation. By using the Debye approximation of Bessel functions for imaginary orders $\nu = i\gamma (\gamma \in \mathbb{R})$ valid for $\gamma^2 + (qk)^2 \gg 1$ and the Dirichlet condition $Z_{\nu,k}(q) = 0$ we obtain the following relation:

$$\sqrt{\gamma^2 + k^2} - \sqrt{\gamma^2 + (qk)^2} + \gamma \log \left[ \frac{q + \sqrt{\gamma^2 + k^2}}{\gamma + \sqrt{\gamma^2 + (qk)^2}} \right] = \pi n, \quad n \in \mathbb{N}.$$  \hfill (21)

The solution of equation (21) in variable $\gamma \gg k$ represents an asymptotic approximation of imaginary mode numbers $\nu_n = i\gamma_n$ and is written as

$$\gamma_n = \frac{\pi n}{\log q} - \frac{(ka)^2}{4\pi n} + O(n^{-3}), \quad n \gg 1.$$  \hfill (22)

The first term in equation (22) is already well known and can also be obtained from equation (20), see [15]. The divergence of $Z_{\nu,k}(q)$ for $\nu \to \infty$ makes the finding of high real mode numbers, especially at large $k$, extremely difficult. We stabilize the search by using an analytic approximation of the highest real mode number $\nu_{\max}(k, q) = \max \{ \nu : Z_{\nu,k}(q) = 0 \}$ for $q$ sufficiently far away from 0. This is achieved by using the asymptotic expansion of Bessel functions [19] in the transitional regime yielding

$$\nu_{\max}(k, q) = k - \frac{k}{2} \left[ a_0 + a_1 \exp \left( -\frac{2^2}{3} \frac{a_0^2}{k} \right) \right] + O(k^{-5}),$$  \hfill (23)

where

$$a_1 = -\frac{\text{Bi}(-a_0)}{2\text{Ai}(-a_0)} \doteq 0.323685, \quad a_0 \doteq 2.3381074.$$  \hfill (24)

The constant $a_0$ is the negative first zero of the Airy function, $\text{Ai}(-a_0) = 0$. The exact implicit formula $Z_{\nu,k}(q) = 0$ for mode numbers at given $k$ and $q \neq 0$ has an interesting simple first-order approximation reading

$$\left( \frac{k}{k_0(n, q)} \right)^2 - \left( \frac{\nu \log q}{\pi n} \right)^2 \approx 1,$$  \hfill (25)
which is asymptotically exact in two independent limits: $\nu = \text{fixed}, k \to \infty$, and $k = \text{fixed}, |\nu| \to \infty$. The relation (25) represents a useful approximation of mode numbers and is to our knowledge a new uniform approximation of modes in a bend. The expression $k_0(n, q)$ is the $n$th zero of $Z_{n,k}(q)$, which can be easily found numerically. In the limit of large $n$, where we can use $k_0(n, q) \approx \pi n/a$, the relation (25) is simplified to

$$(ka)^2 - (\nu \log q)^2 \approx (\pi n)^2.$$  

(26)

The validity of this formula is illustrated in figure 2, where we compare mode numbers obtained from the approximate relation (26) with the exact ones. The highest real mode $\nu_{\text{max}}$ for small wavenumbers $k < \nu$ can be approximated using equation (25) as

$$\nu_{\text{max}}(k, q) \approx \frac{\pi}{|\log q|} \sqrt{\left(\frac{k}{k_0(1, q)}\right)^2 - 1}.$$  

(27)

In practical applications, it is important that below the wavenumber $k_{\text{low}}(q) = k_0(1, q)$ there are no real modes. In wide bends with $q \approx 0$, one can expand the cross-product of Bessel functions around $q = 0$ and obtain the formula

$$k_{\text{low}}(q) = b_0 + b_1 \frac{1}{|\log q|} + O(q^2),$$  

(28)

where $b_0$ is the smallest zero of the Bessel function $J_0(x)$, $J_0(b_0) = 0$, and

$$b_0 = 2.404 \, 825 \, 558, \quad b_1 = -\frac{\pi Y_0(b_0)}{2J_0(b_0)} \approx 1.542 \, 889 \, 74.$$  

(29)

In narrow bends, where $a = 1 - q \to 0$, we can use standard stationary perturbation theory [21], see equation (B.2) in appendix B, to approximate $k_{\text{low}}(q)$. By introducing the matrix elements

$$V_{nm} = -\frac{1}{2} \int_0^1 \sin(\pi nx) \sin(\pi mx) \frac{dx}{(x + \gamma)^2}, \quad \gamma = \frac{q}{1 - q},$$  

(30)

we can express the lowest wavenumber as

$$k_{\text{low}}(q) = \frac{\pi}{a} \left[ 1 + \frac{1}{\pi^2} V_{11} + \frac{1}{\pi^2} \sum_{l>1} \frac{|V_{li}|^2}{1 - l^2} + O(|V|^3) \right]^{1/2}.$$  

(31)
Formula (31) has a simple first-order expansion in \( a = 1 - q \)

\[
k_{\text{low}}(q) = \frac{\pi}{a} - \frac{a}{8\pi} + O(a^2). \tag{32}
\]

From expression (32) we learn that the lowest wavenumber at which real modes exist increases with increasing \( q \) and converges to \( \frac{\pi}{a} \).

### 2.2. Numerical evaluation of mode functions in a bend

The mode functions in the bend at a given wavenumber \( k \) and inner radius \( q \) are proportional to cross-products of Bessel functions \( Z_{\nu,k}(r) \) (12), where the order parameter \( \nu \) takes values from the set \( \mathcal{M}_{k,q} \). Because of the symmetry \( Z_{-\nu,k}(r) = Z_{\nu,k}(r) \), we only consider mode numbers from the set \( \mathcal{M}_{k,q,+} = \{ \nu_n : \nu_n^2 > \nu_{n+1}^2, n \in \mathbb{N} \} \), which are ordered by decreasing square. To illustrate the basic properties of mode functions, we plot in figure 3 the functions
For real and first few imaginary mode numbers for \( q = 0 \) and some low wavenumber \( k \). We see that the first mode function \( Z_{\nu,1}(r) \) has no zeroes on the interval \( r \in (q, 1) \) and each consecutive mode function has one additional zero. In the following, we present formulae and numerical recipes for stable calculation of mode functions, where we assume that the mode numbers are given.

The Bessel functions for real orders are well implemented in the currently available numerical libraries, i.e. SLATEC [22]. From the definitions of Bessel functions it is not unexpected that we encounter problems at evaluating \( Z_{\nu,k}(r) \) for large wavenumbers \( k \gg 1 \) and high real orders \( \nu \gg 1 \). In order to overcome these problems we apply the stable forward recursions in the order parameter [19] written as

\[
p_{\mu+1} = p_{\mu-1} - 2\mu(xq_{\mu} + yr_{\mu}), \quad (33)
\]

\[
q_{\mu+1} = (2\mu(\mu + 1)x^2 - 1)r_{\mu} + 2\mu(\mu + 1)xyq_{\mu} - (\mu + 1)yq_{\mu-1} + \mu x p_{\mu}, \quad (34)
\]

\[
r_{\mu+1} = (2\mu(\mu + 1)x^2 - 1)q_{\mu} + 2\mu(\mu + 1)xyr_{\mu} - (\mu + 1)r_{\mu-1} - \mu y p_{\mu}, \quad (35)
\]

where we write \( x = (kr)^{-1} \) and \( y = k^{-1} \) and define the following symbols:

\[
p_{\mu} = J_{\mu}(kr)Y_{\mu}(k) - J_{\mu}(k)Y_{\mu}(kr), \quad (36)
\]

\[
q_{\mu} = J_{\mu}(kr)Y'_{\mu}(k) - J'_{\mu}(k)Y_{\mu}(kr), \quad (37)
\]

\[
r_{\mu} = J'_{\mu}(kr)Y_{\mu}(k) - J_{\mu}(k)Y'_{\mu}(kr). \quad (38)
\]

The initial conditions for the recursion, at low orders, are calculated using standard routines and the expressions for the derivatives of Bessel functions by relation valid for any Cylindrical function:

\[
C'_{\nu} = (C_{\nu} - 1 - C_{\nu} + 1) / \nu. \quad (40)
\]

\[
P_{\nu}(z) = 1 - \frac{(\mu - 1)(\mu - 9)}{2!(8z)^2} + \frac{(\mu - 1)(\mu - 9)(\mu - 25)(\mu - 49)}{4!(8z)^4} + \ldots \quad (40)
\]

and

\[
Q_{\nu}(z) = \frac{\mu - 1}{8z} - \frac{(\mu - 1)(\mu - 9)(\mu - 25)}{3!(8z)^3} + \ldots, \quad \mu = 4\nu^2, \quad (41)
\]

which we sum up to \( t_{\text{max}} = \lfloor \nu/2 \rfloor + 1 \) terms. There is another difficulty occurring at high wavenumbers, which cannot be corrected. The first few real modes \( \nu_{p} \in M_{k,q,+} \) scale linearly with the wavenumber \( k \) and functions \( Z_{\nu,k}(r) \) diverge with increasing order \( \nu \). Consequently, the values \( Z_{\nu,k}(q) \) are exponentially sensitive on the precision of the first few mode numbers \( \nu_{p} \):

\[
|Z_{\nu_{p+1},k}(q)| \sim q^{-\nu_{p}} \sinh(|\log q|\delta v). \quad (42)
\]

This problem cannot be solved completely, but only partially corrected by manually setting the values of \( Z_{\nu,k}(r) \) to zero around the inner radius. This can be done without any real loss of precision, because the mode functions are localized near to the outer radius. In practice we calculate the left-hand side of equation (42) in a finite range arithmetic \([-m, m]\) with the
maximal number \( m \) (e.g. \( m \approx 10^{308} \) in double precision). By considering that together with the known property \( \nu_{\text{max}} \sim k \) (23), we find that in practice our modal approach breaks down above some wavenumber \( k_{\text{break}} \sim \log m / |\log q| \) and consequently bounding the number of open modes in our numerical analysis below

\[
N_{0, \text{break}} \sim \frac{a \log m}{\pi |\log q|}.
\]

where we used the relation \( N_{0} \sim ka/\pi \) valid for narrow bends and high wavenumbers.

The numerical evaluation of \( Z_{\nu, k}(r) \) at imaginary orders \( \nu \in i\mathbb{R} \) is almost unsupported in currently available numerical libraries. Therefore, we have developed procedures for their evaluation ourselves and give here a summary of our work. For each regime of order parameters \( \nu = iy \) and wavenumbers \( k \), we use a different strategy to evaluate \( Z_{iy, k}(r) \) in order to achieve an optimal precision control and a CPU time consumption. The formula for the cross-products of Bessel functions (12) takes for imaginary orders a simple form

\[
Z_{iy, k}(r) = \frac{2}{\sinh(\pi y)} \text{Im}\{J_{iy}(k)J_{iy}^*(kr)\}.
\]

At small wavenumbers \( k \) or more generally for \( k \ll y \), we use the Taylor expansion of the Bessel function [19] and rewrite equation (44) into

\[
Z_{iy, k}(r) = \frac{2}{\pi y} \text{Im}\{r^{-iy}u_{iy}(k)u_{iy}^*(kr)\},
\]

where we use the series

\[
u_{\nu}(z) = \sum_{l=0}^{\infty} \frac{(-1)^l}{l!(\nu+1, \nu+l+1)} z^{2l+1}, \quad (x, y) = \frac{\Gamma(y)}{\Gamma(x)}.
\]

The series (46) is summed up to the index \( l_{\text{max}} = \lfloor \sqrt{z^2/\epsilon} + |\nu|^{2/4} \rfloor \), where \( \epsilon \) is the desired accuracy of the expression.

At higher wavenumbers \( k \) and orders \( y \ll k \) we combine the backwards recursion valid for Cylindrical functions

\[
a_{l-1}(z) = \frac{2(l+iy)}{z} a_{l}(z) - a_{l+1}(z),
\]

with an appropriate normalization formula for \( a_{l}(z) \) [19] and thereby obtain an expression for \( u_{iy, k}(r) \) (45) given by

\[
u_{iy}(z) = a_{0}(z) \left[ \sum_{l=0}^{\infty} \frac{(2l+z)(1+z, l+z)}{l!} a_{2l}(z) \right]^{-1}.
\]

The terms \( a_{2l} \) in the series (48) are given with the recursion (47) started at the index \( l_{\text{max}} = 2[(x+1)/2] \) with initial conditions \( a_{l_{\text{max}}} = \epsilon \) and \( a_{l_{\text{max}}+1} = 0 \), where the constant \( \epsilon \) is the smallest number supported by the CPU architecture and \( x \) is determined by the equation:

\[
|\log \epsilon| - 1 + \frac{1}{2} \log(1+y^2) - y \arctan y = \frac{1}{2} x \log(x^2+y^2) - x \left( \log \frac{z}{2} + 1 \right) - x \arctan \frac{y}{x}.
\]

The later equation (49) is meaningful only if the right side is positive, yielding that presented approach with the iteration formula is valid only for orders \( y \) below some value scaling as \( O(|\log \epsilon|) \). By increasing the wavenumber \( k \) further up and keeping orders small \( y \ll k \) we can use the Hankel approximation (39) with the order parameter \( \nu = iy \). The asymptotic
series (40) and (41) in expression (39) are summed at least up to $l_{\text{max}} = \lfloor z/2 + \sqrt{z^2 - y^2}/2 \rfloor$ terms. At large enough wavenumbers $k$ and imaginary orders $y > k$ we can make use of the Debye approximation of Bessel functions [23] and write

$$Z_{\nu}(k, r) = \frac{2 \text{Im} \left\{ G(\alpha, \xi) G^*(\beta, \zeta) \exp \left\{ i \left[ \xi - \zeta - y \left( \text{arcsinh} \frac{\sqrt{\xi}}{k} - \text{arcsinh} \frac{\sqrt{\zeta}}{kr} \right) \right] \right\} \right\}}{(1 - \exp(-2\pi y)) \sqrt{\xi \zeta}}, \quad (50)$$

with substitutions

$$\xi = \sqrt{y^2 + k^2}, \quad \zeta = \sqrt{y^2 + (kr)^2}, \quad \alpha^{-1} = 1 + \frac{k^2}{y^2}, \quad \beta^{-1} = 1 + \frac{(kr)^2}{y^2}. \quad (51)$$

Expression $G(x, y)$ in formula (50) is given in the form of an asymptotic series

$$G(x, y) = \sum_{m=0}^{\infty} \frac{(-i)^m v_m(x)}{y^m}, \quad (52)$$

where polynomials $v_m(t)$ are generated by the following recursion

$$v_{k+1}(t) = \frac{1}{2} (1-t)(kv_k(t) + 2tv'_k(t)) + \frac{1}{16} t^{6/5} \int_0^t (1-5\tau) \tau^{-6/5} v_k(\tau) \, d\tau. \quad (53)$$

The first few $v_m(t)$ read as

$$v_0(t) = 1, \quad v_1(t) = \frac{1}{8} - \frac{5}{24} t, \quad v_2(t) = \frac{3}{128} - \frac{77}{3456} t + \frac{385}{3456} t^2. \quad \ldots \quad (54)$$

Formulae (39), (45), (48) and (50) enable a stable high precision calculation of the mode functions in the bend at imaginary mode numbers.

### 2.3. The overlap of mode functions in different geometries

The main ingredient in the modal description of the scattering are the overlap integrals of the mode functions in the straight waveguide and in the bend. These overlap integrals ‘tell’ about the compatibility of both scattering regions and are discussed in the following.

The cross products of Bessel functions with order parameter $\nu \in \mathcal{M}_{k,q,+}$ at given wavenumber $k$ and inner radius $q$ form a set of functions

$$Z_{k,q} = \{ Z_{\nu,k}(r) : \nu \in \mathcal{M}_{k,q,+}, r \in [q, 1] \}, \quad (55)$$

which is complete in $L^2[q, 1]$ and orthogonal w.r.t. the weight function $w(r) = r^{-1}$. The later is derived in appendix A. The orthogonality relation for $Z_{v,k} \in Z_{k,q}$ reads [24]

$$\int_q^1 dr \, w(r) Z_{\nu,k}(r) Z_{\mu,k}(r) = \delta_{\nu,\mu} \frac{k}{2
u} \left[ Z_{\nu+1,k}(1) \frac{\partial Z_{\nu,k}}{\partial \nu} (1) - q Z_{\nu+1,k}(q) \frac{\partial Z_{\nu,k}}{\partial \nu} (q) \right]. \quad (56)$$

The line separating the bend and the straight waveguide will be called the cross-section of our open billiard. On the cross-section, we define two different scalar products denoted by $(\cdot, \cdot)$ and $\langle \cdot, \cdot \rangle$, and written as

$$(a, b) = \int_q^1 dr \frac{a(r)b(r)}{r}, \quad \langle a, b \rangle = \int_0^a dy \, a(y)b(y). \quad (57)$$

Let us now introduce modes at some fixed wavenumber $k$ and inner radius $q$ for different regions of the open billiard. In the bend, mode numbers $\nu_p$ and normalized mode functions $U_p(r)$ read as

$$\nu_p \in \mathcal{M}_{k,q,+}, \quad U_p(r) = \frac{Z_{\nu_p,k}(r)}{\sqrt{\left( Z_{\nu_p,k}, Z_{\nu_p,k} \right)}}, \quad p \in \mathbb{N}, \quad (58)$$
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where we order the mode numbers so that \( v_p^2 > v_{p+1}^2 \), and in the straight leads connected to the bend we have mode numbers \( g_n \) and mode functions \( u_n(x) \) defined by

\[
  g_n = \sqrt{k^2 - \left( \frac{\pi n}{a} \right)^2}, \quad u_n(y) = \sqrt{\frac{2}{d}} \sin \left( \frac{\pi}{a} ny \right), \quad n \in \mathbb{N}.
\]

The modes with real and imaginary mode numbers are called open and closed modes, respectively. The number of open modes in some geometry is denoted by \( N_o \). The overlap integrals of mode functions are given by

\[
  A_{np} = \langle u_n, U_p \rangle, \quad B_{np} = (u_n, U_p),
\]

where we use the relation \( r = q + y \) between the coordinates. In figure 4, we show a density plot of the matrix elements, in log scale, namely \( \log |A_{np}| \) and \( \log |B_{np}| \), at two values of inner radii with the same number of open modes \( N_o \) in both geometries. We see that the matrices \( A_{np} \) and \( B_{np} \) have a similar form for all \( q \) and \( k \). This is starting at small indices with a wide area of high values of matrix elements that squeezes to almost a single intensified point at \( n, p \approx N_o \) again spreading in a triangular shape with increasing indices. The parameter \( q \) has a strong influence on the shape of the area with high intensities in \( A \) and \( B \). In the case of small values of \( q \) in contrast to larger \( q \), the area of high values in matrices \( A \) and \( B \) covers almost the whole open–open block of indices and with crossing of the narrowing at \( n, p \approx N_o \) spreads faster with increasing indices. The shape of matrices \( A \) and \( B \) is similar therefore in the following we only show results for the matrix \( A_{np} \). We found numerically that the area of high intensities in matrices \( A \) and \( B \) scales with the number of open modes \( N_o \) as

**Figure 4.** Density plots of the matrix elements \( \log |A_{np}| \) (top-row) and \( \log |B_{np}| \) (bottom-row) for \( q = 0.2 \) (left) and \( q = 0.9 \) (right) as indicated in the figure. The number of open modes is \( N_o = 100 \) and the number of all considered modes is \( N = 300 \).
$A_{np}, B_{np} \sim F(n/N_o, p/N_o)$, where $F$ is some a well-behaved function. We demonstrate this by plotting the matrix elements $|A_{np}|$ in relative indices $n/N_o$ and $p/N_o$ for different numbers of open modes $N_o$ shown in figure 5. In addition, we find numerical evidence that intensities of matrix elements $A_{np}$ and $B_{np}$ in the region of open modes and in the region of closed modes scale differently with $N_o$

open modes: $|A_{np}|, |B_{np}| \lesssim \frac{1}{\sqrt{N_o}} F_{\text{max}} \left( \frac{n}{N_o}, \frac{p}{N_o} \right)$,  

closed modes: $|A_{np}|, |B_{np}| \lesssim \frac{1}{N_o^2} F_{\text{min}} \left( \frac{n}{N_o}, \frac{p}{N_o} \right)$,  

where $F_{\text{max}}$ and $F_{\text{tail}}$ are some well-behaved functions. Taking into account these phenomenological findings enables a better precision control of scattering calculations. In figure 6, we see that $F_{\text{max}}$ is an envelope function for maximal values of $N_o^\frac{1}{2}|A_{np}|$ and that $F_{\text{min}}$ can be chosen to fit the tails of $N_o^\frac{1}{2}|A_{np}|$. We prove the scaling relation (62) by using an asymptotic approximation of the mode function in the bend

$$U_p(r) = \sqrt{\frac{2}{|\log q|}} \sin \left( \frac{\pi p}{\log q} \log r \right), \quad p \gg 1,$$

which yields the following asymptotic behaviour of matrix elements

$$A_{np} \approx \frac{6}{\pi^2 (1-q)^2} (q^2 (-1)^p + (-1)^{p+1}) n p^{-3} + O(p^{-5}) \quad n = \text{fixed}, \quad p \to \infty,$$

$$A_{np} \approx \frac{2}{\pi^2} \frac{1-q}{|\log q|^2} (q^{-2} (-1)^{p+1} + (-1)^{n}) n p^{-3} + O(n^{-3}) \quad p = \text{fixed} \gg 1, \quad n \to \infty,$$

The off-diagonal diagonal elements $A_{np}$ and $B_{np}$ decay algebraically with increasing index. The pre-factor of the decay is decreasing with increasing $q$ and is singular at $q = 0$. This means that for large enough $q$ it is possible to approximately express the open modes of the bend solely in terms of open modes of the straight waveguide and vice versa, as indicated by the relation (61).
From the definition of matrix elements $A_{np}$ and $B_{np}$ (60), and completeness of the mode functions at given $k$ and $q$, it follows that $A$ and $B$ are transition matrices between the sets of mode functions in different regions,

$$u_n(x) = \sum_{p \in N} B_{np} U_p(r), \quad U_p(r) = \sum_{n \in N} A_{np} u_n(x),$$

yielding the relation

$$A B^T = A^T B = id.$$  \tag{67}

In practice, we work with finite sets of modes, where the identity (67) cannot hold exactly. In figure 7, we plot $A B^T$ for different inner radii $q$ and fixed $N_o = 100$. The mismatch from the identity (67) on some sub-set of indices starting at the origin $n = 1$, or $p = 1$, increases with decreasing inner radius $q$. This means that the numerical calculation of scattering for smaller $q$ should be less accurate at finite dimensions. The discrepancy between $A B^T$ and the identity on (truncated) finite-dimensional spaces is strongly non-uniform in indices. Before going into practical aspects of this problem, we examine the convergence of matrix elements $(A B^T)_{nm}$ to $\delta_{nm}$ with increasing number of all considered modes $N = N_o + N_c$ at fixed $N_o$, where $N_c$ is the number of closed modes. An example of such convergence is shown in figure 8. The convergence proceeds by the standard scenario, where the agreement between $(A B^T)_{np}$ and $\delta_{np}$ propagates block-wise from low to higher indices with increasing $N$. The propagation is slow due to the triangular shaped area of high intensities in the closed–closed modes block of $A$ and $B$. The speed of propagation of accuracy to higher indices increases with increasing inner radius $q$.

The SVD decompositions [25] of matrices $A$ and $B$ is useful for improving and stabilising the scattering calculations and will be used in the next section. From definitions of transition matrices (60) and completeness of mode functions we obtain

$$(A A^T)_{nn'} = (u_n, r u_{n'}), \quad (A^T A)_{pp'} = (U_p, r U_{p'}),$$

$$\quad (B B^T)_{nn'} = (u_n, r^{-1} u_{n'}), \quad (B^T B)_{pp'} = (U_p, r^{-1} U_{p'}),$$

which we use to bound the image

$$\frac{\|A a\|}{\|a\|} \in [q^{-1}, 1], \quad \frac{\|B a\|}{\|a\|} \in [1, q^{-1}] \quad \text{for} \quad \|a\| \neq 0.$$  \tag{70}
Figure 7. Density plot of matrix elements \( \log_{10} |(AB^T)_{nm} - \delta_{nm}| \) for \( q = 0.2, 0.6 \) and \( 0.9 \) (from left to right). On the abscissa and ordinate we plot indices \( n \) and \( m \), respectively. The number of open modes is \( N_o = 100 \) and the total number of modes is 300.

Figure 8. Density plot of matrix elements \( \log_{10} |(AB^T)_{nm} - \delta_{nm}| \) for different numbers of closed modes \( N_c = 1, 100 \) and \( 500 \), as indicated in the figure, at inner radius \( q = 0.2 \) and \( N_o = 100 \) open modes. The labels on the abscissa and the ordinate are matrix indices \( n \) and \( m \), respectively.

These results together with \( AB^T = \text{id} \) can be used to determine the form of the SVD decomposition
\[
A = U \Sigma V^T, \quad B = U \Sigma^{-1} V^T, \quad \Sigma = \text{diag}\{\sigma_i \in [\sqrt{q}, 1], i \in \mathbb{N}\},
\]
where \( U \) and \( V \) are orthogonal matrices. We show here an example of the SVD decomposition of finite-dimensional matrices \( A \) and \( B \) at \( q = 0.2 \) and \( N_o = 100 \). In figure 9, we show singular values and in figure 10 we show density plots of the corresponding matrices \( U \) and \( V \), where the inner indices are ordered by decreasing magnitude of singular values. We see that the relative dimension of the space, which violates the bounds of singular values \( (70) \), converges with increasing space dimension \( N = N_o + N_c \), where \( N_c \) is the number of imaginary modes. In the presented case \( q = 0.2 \) the relative dimension is around 20\%. It is important to see that vectors in \( V \) and \( U \) corresponding to singular values, which violate the bounds, have nonzero components only at closed modes. We conclude that due to a finite-dimensional
representation of matrices $A$ and $B$ we have deviations from the infinitely dimensional case only at high laying decaying modes that span a space of almost fixed relative dimension for some value of $q$.

3. The scattering across a bend

In this section, we solve the on-shell scattering of a non-relativistic particle across our open billiard using the modal approach, initiated in the introduction. The scattering is discussed at fixed wavenumber $k$ and inner radius $q$. The control of the precision of scattering calculations is studied in detail. In the second part of this section, we investigate some interesting physical scattering properties of the bend.

3.1. The scattering matrix of a bend

The scattering matrix $S$ [18] is a linear mapping between the incoming and outgoing ‘waves’ with respect to our scatterer. We reorganize the expansion coefficients of the wavefunction over different regions (9), (10), (11) into the incoming contributions denoted as $v_{\text{in}} = (a_1^1, a_2^1, \ldots, b_1^1, b_2^1, \ldots)$ and outgoing contributions $v_{\text{out}} = (a_1^2, a_2^2, \ldots, b_1^2, b_2^2, \ldots)$. Then the scattering matrix $S$ can be defined as

$$S v_{\text{in}} = v_{\text{out}}. \quad (72)$$

The $S$-matrix in our case has a simple symmetric block form

$$S = \begin{bmatrix} R & T \\ T & R \end{bmatrix}, \quad (73)$$

with $R$ and $T$ being the reflection and the transmission matrix, respectively. By reordering of rows and columns in $S$ so that the matrix elements concerning open (subscript o) and closed (subscript c) modes are separated and grouped together we obtain the matrix $\mathcal{S}$, reading

$$S \rightarrow \mathcal{S} = \begin{bmatrix} S_{oo} & S_{oc} \\ S_{co} & S_{cc} \end{bmatrix}. \quad (74)$$

We find that blocks of matrix $\mathcal{S}$ (74) obey the generalized unitarity [26] defined by the following relations
Figure 10. Density plots of matrix elements $|U_{nm}|$ (left) and $|V_{nm}|$ (right) of the SVD decomposition of matrices $A$ (top row) and $B$ (bottom row) at inner radius $q = 0.2$ with $N_o = 100$ open and $N_c = 100$ closed modes. Labels on the abscissa and the ordinate are indices $n$ and $m$, respectively.

\[
S_{oo} S_{oo}^\dagger = S_{oo}^\dagger S_{oo} = \text{id}, \quad (75)
\]
\[
i S_{oo} S_{co}^\dagger = S_{oc}, \quad (76)
\]
\[
i S_{oc}^\dagger S_{oo} = S_{co}, \quad (77)
\]
\[
i S_{oc} S_{co}^\dagger = i S_{oc}^\dagger S_{oc} = S_{cc} - S_{cc}^\dagger. \quad (78)
\]

Relations (75)–(78) result from the probability current conservation, which is also equivalent to the condition $A B^T = \text{id}$. Due to the time-reversal symmetry of the physical problem the scattering matrices $S$ and $S^\dagger$ are symmetric

\[
S^T = S, \quad S^{\dagger T} = S. \quad (79)
\]

The block symmetry of the scattering matrix (73) simplifies its calculation. We may consider individual incoming waves $e_n^+$ represented by the following wavefunction ansatz

\[
\psi(r) = e_n^+(r) + \sum_m e_m^-(r) R_{mn}, \quad r \in \Omega_A. \quad (80)
\]
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\[ \psi(r) = \sum_p f_p^+(r) \Lambda_{pm}^+ + f_p^-(r) \Lambda_{pm}^-, \quad r \in \Omega_B, \]  
\[ \psi(r) = \sum_m e_m^+(r) T_{mn}, \quad r \in \Omega_C. \]

The continuity of \( \psi(r) \) and its normal derivative on the connecting cross-sections between regions \( \Omega_{A,B,C} \) determines the matrix elements \( R_{mn}, T_{mn} \) and \( \Lambda_{pm}^\pm \) and yields the following system of matrix equations

\[ \text{id} + R = M(\Lambda^+ + \Lambda^-), \quad T = M(\mathcal{F} \Lambda^+ + \mathcal{F}^{-1} \Lambda^-), \]  
\[ \text{id} - R = N(\Lambda^+ - \Lambda^-), \quad T = N(\mathcal{F} \Lambda^+ - \mathcal{F}^{-1} \Lambda^-), \]

which we write using diagonal matrices \( V = \text{diag}\{v_n\}_{n \in \mathbb{N}}, G = \text{diag}\{g_n\}_{n \in \mathbb{N}} \) and \( \mathcal{F} = \exp(iV) \), and transition matrices \( A \) and \( B \) (60). The elimination of matrices \( \Lambda^\pm \) from equations (83) and (84) yields the blocks of the scattering matrix \( S \), reading

\[ T = (C - \mathcal{F} D C^{-1} \mathcal{F} D)^{-1} \mathcal{F} (C - DC^{-1} D), \]  
\[ R = (C - \mathcal{F} D C^{-1} \mathcal{F} D)^{-1} (\mathcal{F} DC^{-1} \mathcal{F} C - D), \]

that we express by using the following auxiliary matrices

\[ C = M^{-1} + N^{-1} = V^\frac{1}{2} B^T G^{-\frac{1}{2}} + V^{-\frac{1}{2}} A^T G^\frac{1}{2}, \]  
\[ D = M^{-1} - N^{-1} = V^\frac{1}{2} B^T G^{-\frac{1}{2}} - V^{-\frac{1}{2}} A^T G^\frac{1}{2}, \]

where we take into account the relation \( AB^T = \text{id} \). The presented form of the matrix \( T \) (86) and \( R \) (87) is chosen in order to increase its numerical stability i.e. minimizing the use of inverses and avoiding direct computation of \( \mathcal{F}^{-1} \).

### 3.2. Numerically stable scheme for scattering matrix calculation

A bend on a straight waveguide is a paradigmatic example for testing numerical schemes and ideas on how to accurately calculate the scattering matrix. In particular, the high curvature case \( q \to 0 \) turns to be highly non-trivial. Here we give a simple and stable procedure to obtain the scattering matrix with a clear precision control for practically all curvatures.

The scattering across a bend of angle \( \beta \) and inner radius \( q \) back to asymptotic region at some wavenumber \( k \) is described by the scattering matrix \( S(\beta) \) (73), which is composed of the reflection matrix \( R(\beta) \) (87) and the transmission matrix \( T(\beta) \) (86). In practice, we work with finite-dimensional matrix approximations, denoted by \( R_N(\beta), T_N(\beta) \in \mathbb{C}^{N \times N}, S_N(\beta) \in \mathbb{C}^{2N \times 2N}, A_N, B_N \in \mathbb{R}^{N \times N} \), (90)

where \( N \geq N_0 \) is the number of modes used in the asymptotic regions. The main objective is to construct these finite-dimensional matrices \( R_N(\beta) \) and \( T_N(\beta) \) so that

(i) calculations are numerically stable and precise,
(ii) \( S_N(\beta) \) satisfies the time reversal symmetry (79) and the generalized unitarity relation (75)–(77),
(iii) the sub-block of $R_N(\beta)$ and $T_N(\beta)$ of dimension $N' \in (N_0, N]$ is calculated with controllable accuracy, where $N_0 = \lfloor ka/\pi \rfloor$ is the number of open modes in the asymptotic region.

The recipe to achieve these assumptions may be separated into two parts. In the first part, we cure the numerical instability caused by the maximal element $r(\beta) = \exp(\beta_{vN})$ in $F_N(\beta)$, which are exponentially diverging with increasing $N$. This is achieved by separating the bend into $2^n$ identical subsections of angle $\beta' = 2^{-n_0} \beta$ so that $r(\beta') \epsilon_{num} \approx 1$, where $\epsilon_{num}$ is the numerical precision e.g. $\epsilon_{num} = 2^{-52}$ in double precision floating point arithmetic. The number $n_0$ is calculated as

$$n_0 = \max \left\{ 0, 1 + \left\lfloor \log_2 \left( \frac{\log \epsilon_{num}}{\beta_{vN}} \right) \right\rfloor \right\}.$$  \hspace{1cm} (91)

The scattering matrix $S_N(\beta')$ of a small subsection of the bend can be calculated in a very stable way and up to a high precision. By concatenating scattering matrices of subsections together with the recursion

$$S_N(2^{-m+1}\beta) = S_N(2^{-m}\beta) \odot S_N(2^{-m}\beta).$$ \hspace{1cm} (92)

we obtain the scattering matrix of the whole bend $S_N(\beta)$. The symbol $\odot$ denotes the operation for concatenating scattering matrices associated with scatterers on the waveguide and is defined in appendix C.

In the second part, we are discussing the problem that $S_N(\beta')$ diverges with increasing $N$, which is due to violation of the identity $AB^T = \text{id}$ (67) for finite truncated transition matrices $A_N$ and $B_N$. We eliminate the problem by deforming $A_N$ and $B_N$ so that they are non-singular and exactly fulfill the condition $A_N B_N^T = \text{id}$. We make the SVD decomposition of the truncated matrix $A_N = U_N \Sigma_N V_N^T$, modify its singular values $\Sigma_N = \text{diag}\{\sigma_i\}_{i=1}^N$ to $\tilde{\Sigma}_N = \text{diag}\{\tilde{\sigma}_i\}_{i=1}^N$ so that they fit in the bounds obtained for infinitely dimensional case (71)

$$\tilde{\sigma}_i = \begin{cases} \sigma_i : \sigma_i \in [q^{-\frac{1}{2}}, 1] \\ \sigma^* : \text{otherwise} \end{cases},$$  \hspace{1cm} (93)

and again generate both matrices

$$\tilde{A}_N = U_N \tilde{\Sigma}_N V_N^T, \hspace{1cm} \tilde{B}_N = U_N \tilde{\Sigma}_N^{-1} V_N^T.$$ \hspace{1cm} (94)

The same procedure can also be done using SVD decomposition of the matrix $B_N$ as a base for generation of both deformed matrices $\tilde{A}_N$ and $\tilde{B}_N$. The value of $\sigma^* > 0$ can be chosen arbitrarily, but the most elegant choice is $\sigma^* = 1$. By using matrices $\tilde{A}_N$ and $\tilde{B}_N$ (94) instead of $A_N$ and $B_N$ in $S_N(\beta')$ and consequently in $S_N(\beta)$ these become generalized unitary with a well-behaved and physically precise limit $N \to \infty$ at least on the sub-space of dimension $N'$.

We first check this by discussing the precision of transition between the modes in the bend and in the straight waveguide on the sub-space of dimension $N' < N$. The error of transition from the asymptotic region (infinite waveguide) into the bend is quantified by

$$\epsilon_{a\to b}(N, N') = \max_{n, m \in L} \left| \langle u_n | \sum_{p=1}^N |U_p\rangle (U_p) - \text{id} \right| |u_m\rangle = \max_{n, m \in L} \left| \sum_{p=1}^N A_{np} B_{mp} - \delta_{nm} \right|.$$ \hspace{1cm} (95)

and for transition in the opposite direction by

$$\epsilon_{b\to a}(N, N') = \max_{p, r \in L} \left| \langle U_p | \sum_{n=1}^N |u_n\rangle (u_n) - \text{id} \right| |U_r\rangle = \max_{p, r \in L} \left| \sum_{n=1}^N A_{nr} B_{mp} - \delta_{pr} \right|.$$ \hspace{1cm} (96)

with $L = \{1, 2, \ldots, N'\}$. The introduced transition errors (95) and (96) measure the violation of the identity $AB^T = \text{id}$ on the subspace $N'$, when working with the finite number of modes $N$. 

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52 in double precision floating point arithmetic.
It is expected and supported by our numerical studies that the errors vanish in the limit $N \to \infty$ at fixed $N'$ and other parameters. In figure 11, we show transition errors as a function of $N$ at a fixed $N'$ for two values of $N_o$. The errors decrease with increasing $N_c$ down to a certain plateau, which is determined by the precision of mode functions. The most problematic in the precision are the highest few open modes in the bend. A conservative estimate for the plateau is around $10^{-8}$. The transition errors (95) and (96) increase with decreasing $q$ indicating that we need more modes to achieve equally small error as for higher $q$. We did not find any analytic approximation for transition errors. Therefore we numerically estimate the minimal dimension of the functional space $N_t = N_c + N_o$ needed for transition errors to be smaller than some $\varepsilon$, defined as

$$N_t(N', \varepsilon) = \min\{N : \varepsilon_{s \to b}(N, N') < \varepsilon \text{ and } \varepsilon_{b \to s}(N, N') < \varepsilon\},$$

(97)

where $N' = N'_c + N_o$ is the dimension of the observed sub-space. In our numerical analysis we set $\varepsilon \approx 10^{-7}$. We check the convergence of $R_N(\beta)$ and $T_N(\beta)$ with increasing $N$ on some fixed sub-space of dimension $N' < N$. The matrices $R_N$ and $T_N$ are calculated using the method of dividing the bend into sub-sections together with deforming the transition matrices. The convergence is measured through the relative difference of matrices at subsequent changes of the dimension $N$

$$\varepsilon_R(N, N') = \frac{\|R_{N+1}(\beta) - R_N(\beta)\|_N}{\|R_N(\beta)\|_N},$$

$$\varepsilon_T(N, N') = \frac{\|T_{N+1}(\beta) - T_N(\beta)\|_N}{\|T_N(\beta)\|_N},$$

(98)

where we introduce a matrix norm $\|A\|_M = \max_{i,j \in [1,M]} |A_{ij}|$ on the sub-space of the dimension $M$. Expressions (98) give upper bounds for the deviations of matrices from their asymptotic forms

$$\|R_\infty(\beta) - R_N(\beta)\|_{N'} \leq C_1(N') \sum_{M=N+1}^{\infty} \varepsilon_R(M, N'),$$

(99)
The measures of convergence $\varepsilon_R(T_{N_0} + N_c, N_0 + 10)$ (top, bottom) as functions of $N_c$ for $N_0 = 10, 100$ (left, right) at various inner radii $q$ as indicated in the figure. The bend is of angle $\beta = \pi$.

Figure 12. The measures of convergence $\varepsilon_R(T_{N_0} + N_c, N_0 + 10)$ (top, bottom) as functions of $N_c$ for $N_0 = 10, 100$ (left, right) at various inner radii $q$ as indicated in the figure. The bend is of angle $\beta = \pi$.

\[ \|T_\infty(\beta) - T_N(\beta)\|_{\infty} \leq C_2(N') \sum_{M=N+1}^{\infty} \varepsilon_T(M, N'), \tag{100} \]

with expressions $C_1(N') = \max_{N' \geq N'} \|R_N(\beta)\|_{N'}$ and $C_2(N') = \max_{N' \geq N'} \|T_N(\beta)\|_{N'}$, which are of the order of magnitude 1. We have numerically studied quantities $\varepsilon_R(T, N)$ as functions of $N$ at fixed $N'$ and the results are shown in figure 12. In the case $N' = N_0$, we are talking about open–open block of the scattering matrix, which is sometimes called the semi-quantal approximation [27]. We see that $\varepsilon_R$ and $\varepsilon_T$ decrease with increasing total number of modes $N = N_0 + N_c$ in a similar fashion as transition errors down to some plateau around $10^{-12}$. The plateau is almost equal to the machine precision, which is surprisingly better than the transition errors.

The presented method for the calculation of the scattering matrix and its accuracy control works well for all $q > 0$. Nevertheless, a treatment of high curvature cases $q \to 0$ are difficult as we need to consider a large number of closed modes to reach a sufficient precision of the scattering matrix. However, this is feasible to achieve by our method in a stable and controlled way.

3.3. Quantum transport across the bend

The scattering matrix of the open billiard describes the stationary quantum transport of a particle over the bend. We discuss here the most important and obvious measures of the transport, which are the reflection probability and the Wigner–Smith delay time. Since the classical particle cannot scatter back [28] we are particularly interested in the reflection probability as a genuine quantum (wave) property. This is a measure of quantum tunnelling between the two classically invariant components of the phase space corresponding to right
and left going waves. The scattering of an incoming Gaussian ray over the bend is illustrated in figure 13. The ray follows the classical trajectories, but as it is of finite width, its parts are scattered differently when hitting the curved wall. The parts of the ray travel different lengths and interfere among themselves.

We are discussing the scattering over the bend at some fixed wavenumber \( k \) and inner radius \( q \). The scattering properties are contained in the transmission matrix \( T \) (86) and the reflection matrix \( R \) (87). The wavefunction over the asymptotic region is described in \( N \) modes, where \( N \geq N_0 = \lfloor ka/\pi \rfloor \). We consider an incoming wave coming to the bend from the left side written in the asymptotic region as

\[
\psi_{\text{in}}(r) = \sum_{n=1}^{N} a_n e^{i n \theta}(r). \tag{101}
\]

By introducing a vector of complex coefficients \( a = \{a_n\}_{n=1}^{N_0} \) we can write the transmitted and reflected probability flux, \( j_T \) and \( j_R \) respectively, in an elegant form

\[
j_R = a^\dagger \Pi a, \quad j_T = a^\dagger \Sigma a, \quad j_0 = a^\dagger a = j_R + j_T, \tag{102}
\]

where we introduce matrices \( \Pi \) and \( \Sigma \) calculated from open–open mode blocks of \( R \) and \( T \):

\[
\Pi = R_{00}^\dagger R_{00}, \quad \Sigma = T_{00}^\dagger T_{00}, \quad \text{where} \quad \Pi + \Sigma = \text{id}. \tag{103}
\]

The average transport properties are given by the first and the second moment of the probability currents \( j_R, j_T \) averaged over an ensemble of incoming states \( a \). The ensemble represents states (vectors \( a \)) uniformly distributed over the \( 2N \)-dimensional sphere of radius \( j_0 \) [18, 29]. The average probability currents are given by

\[
\langle j_R \rangle = \frac{\langle j_R \rangle a}{j_0} = \frac{1}{N_0} \text{tr}(\Pi), \quad T = 1 - R, \tag{104}
\]

and the standard deviations of probability currents (giving fluctuations within an ensemble) are written as

\[
\sigma_R^2 = \left( \frac{\langle j_R \rangle - (\langle j_R \rangle a)^2}{j_0^2} \right) a = \frac{1}{N_0 + 1} \left[ \frac{\text{tr}(\Pi^2)}{N_0} - R^2 \right] = \sigma_T^2. \tag{105}
\]

In the following, we thus discuss the average reflection \( R \) and the dispersion of reflection \( \sigma_R^2 \). An approximation of the transmission matrix \( T \) can be determined from the semi-classical
calculations, whereas for the reflection matrix $R$ it cannot, as the reflection in the bend is a purely quantum phenomenon. The gross structure of matrices $R$ and $T$, similarly as of matrices $A$ and $B$, does not change significantly with increasing wavenumber $k$. In figure 14, we show the density plot of matrices $R$ and $T$ with $N_o = 100$ open modes. The high probabilities in the matrix $T$ have a classical correspondence, which is revealed through the calculation of the classical scattering matrix $T_{\text{class}}$ [30]. Both, the classical and the quantum transmission matrices feature similar patterns, but due to the quantum interference, we cannot establish a clear correspondence. In the matrix $T$, we have a large area of high values so we can expect that transmission probability of individual modes should be high. It is important to note that the area in the reflection matrix of high intensity is concentrated around the last open mode with the index $N_o$.

At the so-called resonant wavenumbers $k_m = \frac{\pi}{a} m$ ($m \in \mathbb{N}$) a new open mode appears in the asymptotic region and causes a strong increase in the reflection matrix elements at open modes with high indices. This is demonstrated in figure 15, where we show the scattering matrices $R$ and $T$ around the highest open mode calculated at $k \approx k_{100}$ and at $q = 0.6$. The changes are centred around the index $N_o$ and significantly influence the average transport.

In order to clarify the contributions to the total reflection we plot in figure 16 the reflection probability of individual modes $\Pi_{kn}$ for wavenumbers near and far from the resonance. We see that the highest open mode has the strongest reflection and the reflection probability of ‘all’ modes increases at resonant wavenumbers $k = k_{N_o}$. In particular the reflection of highest open mode is almost perfect $\Pi_{N_o,N_o} \approx 1$. In the vicinity of the resonance, we could effectively approximate the average reflection as $R \approx \Pi_{N_o,N_o}/N_o$ (see figure 17). The resonant wavenumbers $k_{N_o}$ are important markers for anomalously strong reflection. This is illustrated in figure 17, where we plot the average reflection $R$ as a function of the wavenumber around $k = k_{100}$. We see the average reflection $R$ has a strong sharp maximum at resonant wavenumbers and decreases in an irregular oscillating manner with increasing wavenumber until crossing the next resonant wavenumber. The frequency of irregular oscillations increases with increasing wavenumber. From numerical results we see that $R$ decreases with increasing $q$. In narrow channels $a \to 0$ at large wavenumbers we showed with a perturbative approach (see appendix D) that

\begin{figure}  
\centering  
\includegraphics[width=\textwidth]{figure14.png}  
\caption{The density plot of the scattering matrices $\log_{10} |(R_N)_{nm}|$ and $\log_{10} |(T_N)_{nm}|$ and the classical analogue of the later $\log_{10} |(T_{\text{class}})_{nm}|$ calculated at inner radius $q = 0.6$, wavenumber $k = 100.5 \frac{\pi}{a}$ and with the total number of modes $N = 150$.}  
\end{figure}
The density plots of the reflection matrix \( \log_{10} |R_{nm}| \) and the transmission matrix \( \log_{10} |T_{nm}| \) around the point \((n, m) = (N_0, N_0)\) at wavenumbers \(k = (100 - 10^{-3}) \frac{\pi}{a}\) (before), \(k = 100\frac{\pi}{a}\) (in the middle) and \(k = (100 + 10^{-3}) \frac{\pi}{a}\) (after the resonance). The solid lines denote indices \(n = N_0\) and \(m = N_0\).

\[ R \sim a^2 N_0, \quad (106) \]

which is confirmed numerically. The resonant behaviour around the resonant wavenumber can be partially explained by neglecting all open modes except that with the highest index \(N_0\). Such system can be treated as an independent 1d scatterer \((d = 1)\) with the reflection and transmission matrix elements reading

\[ R_{1d} = \frac{-\sin (\beta \nu N_0)}{\sin (\beta \nu N_0 + i \mu)}, \quad T_{1d} = \frac{\sin (i \mu)}{\sin (\beta \nu N_0 + i \mu)}, \quad (107) \]

with the phase shift
\[ \mu = 2 \arctanh (K), \quad K = \frac{R_{N_r}N_s}{V_{N_r}B_{N_r}N_s} \in [0, 1]. \] (108)

At \( k = k_{N_r} \), the mode number \( s_{N_r} \approx \mu_{N_s} \) and the phase shift \( \mu_{N_s} \) become zero yielding a perfect reflection in a 1d scattering model, \( R_{1d} = -1 \) and \( T_{1d} = 0 \). This treatment is meaningful, because the matrices \( A \) and \( B \) are approximately diagonal at \((N_{r}, N_{s})\) with an algebraic decay of matrix elements when we move away from the diagonal. If the modes were strictly independent we would have \( \Pi_{N_{r},N_{s}} = \| R_{1d} \|^2 \), but the algebraic tails in matrices \( A \) and \( B \) make this solution to hold only as a rough approximation as can be seen in figure 17.

In figure 18, we study measures of reflection \( \mathcal{R} \) and \( \sigma_{R} \) over a larger range of wavenumbers \( k \). From figure 18(a), we see that \( \mathcal{R} \) strongly oscillates with peaks at resonant wavenumber \( k_{r} \) and its upper bound decreases proportionally to \( k^{-1} \), as predicted. The numerical results in figure 18(b) indicate that \( \sigma_{R} < \mathcal{R} \) and \( \mathcal{R} \sim \sigma_{R} \) as \( k \) goes to infinity. To get rid of oscillations and get an overall average behaviour of \( \mathcal{R} \) and \( \sigma_{R} \) we calculate their cumulative integrals.

**Figure 17.** Reflection a bend of an angle \( \beta = \pi \) as a function of the wavenumber \( k \) in the region of a reflection resonance \( k = 10^{1.5} \). In (a) we show the average reflection measure for different values of \( q \) (indicated in the figure), while in (b) we show a zoom-in around the resonance and compare the average reflection and its standard deviation with the reflection in the last open mode (inset shows even a more very narrow region of the resonance).

**Figure 18.** The average reflection \( \mathcal{R} \) and the relative deviation of reflection \( \sigma_{R} \) over a larger interval of wavenumbers \( k \) at \( q = 0.6 \).
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Figure 19. The integral of the average reflection $R$ and deviation $\sigma_R$ over larger interval of wavenumbers $k$ of a bend with a radius $q = 0.6$ and an angle $\beta = \pi$. The inserted lines are $f_1(k) = 0.01113 + 0.01022 \log k$ and $f_2(k) = -0.01553 + 0.006924 \log k$.

with respect to the wavenumber. The results are shown in figure 19 and yield the following dependence:

$$
\int_{k_0}^{k} R \, dk \propto \int_{k_0}^{k} \sigma_R \, dk = O(\log(k)).
$$

(109)

This indicates together with previous conclusions that the reflection measures, averaged over small wavenumber ranges, indeed scale as

$$
R \sim \sigma_R = O(k^{-1}), \quad k \to \infty.
$$

(110)

It seems that this relation (110) is valid for an arbitrary inner radius $q$ and represents a new and very useful information for the study of waveguides and general billiards that include bends.

Another insight into the scattering properties gives the Wigner–Smith delay time $\tau_{ws}$ [31, 32], which is the quantum analogue of the geometric length travelled by a wave. In the semi-classical limit, where we could apply geometric optics, $\tau_{ws}$ is equal to the average geometric length of classical trajectories over the open billiard. By using the Hermitian variant of the lifetime matrix

$$
Q = S_{oo} \frac{dS_{oo}}{dk},
$$

(111)

the Wigner–Smith delay time is defined as

$$
\tau_{ws} = \frac{1}{2N_0} \text{tr} \{ Q \} = \frac{1}{N_0} \text{tr} \left\{ R_{oo}^l \frac{dR_{oo}}{dk} \right\} + \frac{1}{N_0} \text{tr} \left\{ T_{oo}^l \frac{dT_{oo}}{dk} \right\},
$$

(112)

where we have used block symmetries of our matrix $S$ (73). $\tau_{ws}$ can be thought of as an average delay time corresponding to particular modes, which are defined as

$$
\tau_{ws}^n = \frac{1}{N_0} \sum_{m=1}^{N_0} \text{Im} \left\{ \left[ R_{oo}^l \right]_{nm} \left[ R_{oo}^l \right]_{mn} + \left[ T_{oo}^l \right]_{nm} \left[ T_{oo}^l \right]_{mn} \right\},
$$

(113)

with derivative defined as $(\bullet)' = d/dk$. Numerical results shown in figure 20 point to a similar dependence of Wigner–Smith delay time $\tau_{ws}$ on the wavenumber $k$ as the average reflection $R$, just the oscillations are smoothed out. The time $\tau_{ws}$ strongly increases near the resonance wavenumber $k = k_{N_0}$ due to intense changes in the scattering matrices $R$ and $T$ in the area
around the index of the newly open mode. Qualitatively we can explain the singular behaviour by treating the highest open mode in the resonance regions within a 1d scattering model in which the delay time is given by

$$\tau_{ws}^{1d} = \text{Im}\{T_{1d}^*T_{1d} + R_{1d}^*R_{1d}\} = \frac{\beta \sinh(2\mu)\nu_p' - \sin(2\beta\nu_p)\mu'}{\cosh(2\mu) - \cos(2\beta\nu_p)}.$$  \hspace{1cm} (114)

The first term in the numerator of equation (114) corresponds to the transmission and the second term to the reflection. By slowly increasing the wavenumber across the region of the resonance, we can note three different regimes: before, in the vicinity and after the resonant wavenumber. Slightly before the resonance $k < k_{N_o}$, a new real mode appears in the bend (see formula (B.5)) making the propagation across the bend very slow. From formula (114), we learn that this results in a large transmission time and consequently in a large time delay $\tau_{ws}^{1d}$. In the instance of crossing the reflection resonance a new mode appears in the straight waveguide, which causes a square-root singularity $\tau_{ws}^{1d} \sim (k - k_{N_o})^{-\frac{1}{2}}$ for $k > k_{N_o}$ and its sign is determined by $2\beta\nu_{N_o}$. This reflection term has a short-scale influence to the behaviour of the time delay and can enhance or reduce its size. Obviously, this is a very non-classical situation. By going further away from the resonance wavenumbers the reflection contribution to the time delay is levelled by an increasing transmission term due to a very slow propagation of the mode in the asymptotic region, which again increases the transition time. So we can experience one or two peaks of the time delay in the vicinity of the reflection resonance. Away from the reflection resonance the time delay drops even below the classical time. The latter we assume is due to reflection phenomena which reduces the classically expected phase shift.

The presented 1d scattering model has only an instructive purpose and does not represent any useful quantitative approximation, similarly as was the case in the discussion of the reflection.

4. Conclusions

We present mathematical, numerical and physical backgrounds of the non-relativistic 2D scattering of a quantum particle on a circular bend connected to infinite straight waveguides. We discuss mathematical properties and derive numerical recipes for accurate and reliable calculation of the mode functions and the corresponding mode numbers in a bend. We take
a special care of closed (evanescent) modes in the bend. The obtained modal structure and its properties are incorporated in a robust and stable numerical scheme for computing the scattering matrix with a controllable precision. Our numerical apparatus is applied to the study of transport properties. We focus mainly on the reflection, which is a purely quantum (wave) phenomenon since the back-reflection of classical rays is not possible. Our study is particularly focused on the possibility of investigating the (semi-classical) regime of very large wavenumbers. Some of the obtained physical properties of the scattering problem can be explained analytically. In addition, we present results on the Wigner–Smith delay in the bend. The obtained transport properties can be useful in discussing and predicting properties of open billiards (or waveguides) composed of arbitrary combination of bends and straight segments.

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Appendix A. The symmetry of mode numbers

We prove the symmetry (15), by changing the variable \( r = e^{-x} \) and transforming the Bessel equation (3) and the corresponding boundary condition into the equation

\[
\frac{d^2 Z}{dx^2} + (k^2 e^{-2x} - \nu^2) Z = 0, \quad Z|_{x=0, \log q} = 0,
\]

which can be interpreted as a one-dimensional quantum-mechanical eigenvalue problem, with the Hamiltonian \( \hat{H} \) and potential \( V' \):

\[
\hat{H} Z = -\nu^2 Z, \quad \hat{H} = -\frac{d^2}{dx^2} + V'(x), \quad V'(x) = \begin{cases} -k^2 e^{-2x}; & x \in [0, -\log q] \\ \infty; & \text{elsewhere}. \end{cases}
\]

Because the Hamiltonian \( \hat{H} \) is a Hermitian operator, the eigenvalues are real \( -\nu^2 \in \mathbb{R} \) yielding \( \nu \in \mathbb{R} \cup i\mathbb{R} \). From the form of the potential \( V'(x) \), depicted in figure A1, we see that there are only a finite number of real mode numbers \( \nu^2 > 0 \) and an infinite number of imaginary mode numbers \( \nu^2 < 0 \). The independent solutions of equation (A.2) are orthogonal with respect to the measure \( dx = r^{-1} dr \) and so the weight function between mode functions \( U_p(r) \) in the bend is \( w(r) = r^{-1} \).

Appendix B. The number of modes in the straight and the bent waveguide

We discuss the number of open modes \( N_b(k, q) = \text{card} \{ \mathcal{M}_{k,q} \text{+} \} \) in the bend and its deviation from the number of modes in the straight waveguide \( N_s = \lfloor ka/\pi \rfloor \). The mode numbers in \( \mathcal{M}_{k,q} \) continuously slide with increasing \( k \) and fixed \( q \) from the imaginary to the real axis by crossing the point \( \nu = 0 \). This dynamics is depicted in figure 2. This means that \( N_b(k, q) \) is equal to the number of zeros \( x \) of \( Z_{0,x}(q) \) up to the value \( k \)

\[
N_b(k, q) = \text{card} \{ \mathcal{M}_{k,q} \text{+} \} = \text{card} \{ x \leq k : Z_{0,x}(q) = 0 \}.
\]
By using substitutions $U = r^{-\frac{1}{2}} \varphi$ and $r = q + ax$ the mode problem in the bend (5) is in the case $\nu = 0$ transformed into a 1d stationary Schrödinger equation ($\gamma = q/(1 - q)$)

$$-\frac{d^2 \varphi}{dx^2} + V(x) \varphi = e \varphi, \quad V(x) = -[2(x + \gamma)]^{-2}, \quad x \in [0, 1],$$

with the eigenenergy denoted by $e = (ka)^2$. The discrete set of eigenenergies is ordered as $e_{n+1} > e_n, n \in \mathbb{N}$. By setting $V = 0$ in expression (B.2) we obtain the mode problem for appropriately rescaled straight waveguide. In the eigen-energies in this case se $(\pi n)^2, n \in \mathbb{N}$. Then taking into account the (empirical) fact $e_n \leq (\pi n)^2 < e_{n+1}$ we can conclude

$$0 \leq N_b(k, q) - N_s(k, q) \leq 1, \quad \forall q \in (0, 1).$$

This means that at certain $k$ and $q$ we can have in the bend one open mode more, but not less than in the straight waveguide. In the semi-classical limit $k \to \infty$ the eigenenergies $e_n$ can be obtained using the Debye approximation valid for $qk \gg 1$. In this way we get a relation between the eigenvalues $e$ and its counting number $N_b$

$$2\pi N_b = (4k^2 + 1)^{\frac{1}{2}} - (4(qk)^2 + 1)^{\frac{1}{2}} - \arctan((4k^2 + 1)^{-\frac{1}{2}}) + \arctan((4(qk)^2 + 1)^{-\frac{1}{2}}),$$

which yields with asymptotic expansion in $k$ the expression

$$N_b(k, q) = \frac{ka}{\pi} + \frac{a(1 + q)}{64\pi (qk)^2} + O(a(qk)^{-3}).$$

We see that $N_b$ and $N_s$ are close to each other for high wavenumber and not too small inner radius $q$.

Appendix C. The method of concatenating scattering matrices

Here we outline a method to concatenate the scattering matrices [33] associated with scatterers on sectioned waveguides. Let us assume to have two scatterers labelled by A and B and with scattering matrices $S_A$ and $S_B$, respectively.

$$S_{A,B} = \begin{bmatrix} t_{L,A,B}^L & r_{R,A,B}^L \\ t_{L,A,B}^R & r_{R,A,B}^R \end{bmatrix} \in \mathbb{C}^{2N \times 2N}. \quad (C.1)$$

By combining both scatterers A and B in the order AB we build a ‘larger’ scatterer with the scattering matrix $S$. The matrix $S$ is calculated from matrices $S_{A,B}$ by a nonlinear operation $\odot : \mathbb{C}^{2N \times 2N} \times \mathbb{C}^{2N \times 2N} \to \mathbb{C}^{2N \times 2N}$ defined as

$$S = S_A \odot S_B = \begin{bmatrix} t_L^L & r_R^L \\ t_L^R & r_R^R \end{bmatrix} \in \mathbb{C}^{2N \times 2N}, \quad (C.2)$$
which explicitly reads
\[
\begin{align*}
\rho^L &= r^L_A + i t^L_A R L^{-1} L^R, & \sigma^L &= t^L_A L^{-1} R^L, \quad (C.3) \\
\rho^R &= r^R_A + i t^R_A R L^{-1} L^R, & \sigma^R &= t^R_A L^{-1} R^L, \quad (C.4)
\end{align*}
\]
where we define \( L = 1 - r^A_A L^R \) and \( L^R = 1 - r^A_A L^R \). Note that a bend on a straight waveguide can be treated as a scatterer. By combining bends of angles \( \gamma' \) and \( \delta' \) with scattering matrices \( S(\gamma') \) and \( S(\delta') \), respectively, we get a bend of angle \( \gamma' + \delta' \) with the scattering matrix \( S(\gamma' + \delta') \).

The latter matrix can be obtained from matrices \( S(\gamma') \) and \( S(\delta') \) by the formula
\[
S(\gamma' + \delta') = S(\gamma') \otimes S(\delta') = S(\delta') \otimes S(\gamma'). \quad (C.5)
\]

**Appendix D. Perturbative calculation of the scattering matrix for narrow bent waveguide**

We present a semi-classical approximation, for \( k \gg 1 \), of a scattering matrix corresponding to a single bend on a straight waveguide of width \( a \), as one shown in figure 1. Here we are discussing only narrow channels \( a \ll 1 \), where the influence of closed modes on the scattering diminishes. Therefore closed modes are neglected in our calculations. We are working at wavenumbers \( k \), where in all regions of the open billiard the number of open modes is equal. This enables us to write the reflection and the transmission matrix in the following simpler form
\[
R = -[C + i S]^{-1} (C - i S), \quad T = 2[C + i S]^{-1}, \quad (D.1)
\]
where we use the diagonal matrices \( C = \text{Re}[\mathcal{F}] \), \( S = \text{Im}[\mathcal{F}] \) and \( G = \text{diag}[\xi_n] \) to express the introduced matrices
\[
\begin{align*}
C_{\pm} &= G^{\frac{1}{2}} A C B^T G^{-\frac{1}{2}} \pm G^{-\frac{1}{2}} B C A^T G^{\frac{1}{2}}, \quad (D.2) \\
S_{\pm} &= G^{\frac{1}{2}} A S A^T G^{-\frac{1}{2}} \pm G^{-\frac{1}{2}} B S B^T G^{\frac{1}{2}}. \quad (D.3)
\end{align*}
\]

We proceed by rescaling the variables to dimensionless form by the following substitutions
\[
y = a \xi, \quad r = q + a\xi, \quad \kappa = a k, \quad h_n = a g_n = \sqrt{\kappa^2 - (\pi n)^2}, \quad v_p = a v_p, \quad (D.4)
\]
with a new transverse coordinate \( \xi \in [0, 1] \), and geometric properties being described by the parameter \( a = a/q \ll 1 \). The transition matrices are then expressed as
\[
\begin{align*}
A_{np} &= q^\frac{1}{2} Q_{np}, & Q_{np} &= \frac{\int_0^1 d\xi \ b_n(\xi) \phi_p(\xi) (1 + \alpha \xi)^{-\frac{1}{2}}}{\sqrt{\int_0^1 \phi_p(\xi)^2 (1 + \alpha \xi)^{-2}}}, \quad (D.5) \\
B_{np} &= q^{-\frac{1}{2}} P_{np}, & P_{np} &= \frac{\int_0^1 d\xi \ b_n(\xi) \phi_p(\xi) (1 + \alpha \xi)^{-\frac{1}{2}}}{\sqrt{\int_0^1 \phi_p(\xi)^2 (1 + \alpha \xi)^{-2}}}, \quad (D.6)
\end{align*}
\]
with \( b_n(\xi) = \sqrt{2} \sin(\pi n \xi) \). The eigenpairs \((v_p, \phi_p(\xi))\) are defined by the following differential equation and the boundary condition:
\[
\frac{d^2 \phi_p}{d\xi^2} + \left( \kappa^2 - v_p^2 - \alpha^2 \right) \phi_p = 0, \quad \phi_p(0) = \phi_p(1) = 0. \quad (D.7)
\]
We can easily recognize that the solutions of equation (D.7) converge in the limit \( \alpha \to 0 \) to \( v_p = h_p \) and \( \phi_p(\xi) = h_p(\xi) \). We assume that the solutions can be expanded in a power series of variable \( \alpha \). The eigenpairs can then be obtained using the standard perturbation theory with the perturbation parameter \( \alpha \). The rescaled modes are written as

\[
v_p^2 = h_p^2 \left[ 1 + \alpha + \alpha^2 \left( \frac{1}{3} - \frac{1}{2(\pi p)^2} \right) \right] + \alpha^2 \left( \frac{1}{4} + O(h_p^4) \right) + O(\alpha^3),
\]

and the rescaled mode functions read as

\[
\phi_p(\xi) = \sum_n V_{np} b_n(\xi), \quad V_{np} = \delta_{np} + \alpha \frac{8 \pi n p h_p^2}{\pi^2(n^2 - p^2)} \delta_{np} + O(\alpha^2),
\]

where we use the symbol \( \delta_{p,odd} = (1: n \text{ is odd}; 0: \text{otherwise}) \). By plugging the mode functions \( \phi_p(\xi) \) into transition matrices \( Q \) (D.5) and \( P \) (D.6) we obtain

\[
Q_{np} = \delta_{np} + \alpha \left( F_{np} + \frac{1}{4} \delta_{np} \right) + O(\alpha^2),
\]

\[
P_{np} = \delta_{np} - \alpha \left( F_{np} + \frac{1}{4} \delta_{np} \right) + O(\alpha^2),
\]

\[
F_{np} = \frac{8 \pi n p}{\pi^2(n^2 - p^2)} \left( \frac{h_p^2}{\pi^2(n^2 - p^2)} - \frac{1}{4} \right) \delta_{np}.
\]

Note that the rescaled transition matrices \( Q \) and \( P \) satisfy the known identity \( Q P^T = P Q^T = id \). We insert the expressions for \( Q \) (D.10) and \( P \) (D.11) back into \( S_\pm \) (D.3) and \( C_\pm \) (D.2) and write the reflection and the transmission matrix as

\[
R = -\frac{\alpha}{2} \mathcal{F} \left[ H^{-\frac{1}{2}}(F, C) + i(F S)^{\frac{1}{2}} H^{-\frac{1}{2}}(F, C) + i(F T S) H^{-\frac{1}{2}} \right] + O(\alpha^2),
\]

\[
T = \mathcal{F} - \frac{\alpha}{2} \mathcal{F} \left[ H^{-\frac{1}{2}}(F, F) H^{-\frac{1}{2}} + H^{-\frac{1}{2}}(F, F) H^{-\frac{1}{2}} \right] + O(\alpha^2),
\]

where we have introduced the symbol \( (A)^{\frac{1}{2}} = A + A^T \) and the diagonal matrix \( H = \text{diag}(h_n)_{n=1}^{N_0} \). The approximations of the reflection matrix \( R \) (D.13) and the transmission matrix \( T \) (D.14) are valid far away from the resonant condition \( ak = \pi n \), because we assumed that \( |g_{nm}| > \alpha \) for all \( m \leq N_0 \). We conclude that the strength of reflection scales as \( R \sim \alpha^2 \) and that narrow channels can be treated as perturbed straight waveguides.

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