THE HYPERDETERMINANT OF $3 \times 3 \times 2$ ARRAYS, AND
THE SIMPLEST INVARIANT OF $4 \times 4 \times 2$ ARRAYS

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Abstract. We use the representation theory of Lie algebras and computational linear algebra to obtain an explicit formula for the hyperdeterminant of a $3 \times 3 \times 2$ array: a homogeneous polynomial of degree 12 in 18 variables with 16749 monomials and 41 distinct integer coefficients; the monomials belong to 178 orbits under the action of $(S_3 \times S_3 \times S_2) \rtimes S_2$. We also obtain the simplest invariant for a $4 \times 4 \times 2$ array: a homogeneous polynomial of degree 8 in 32 variables with 14148 monomials and 13 distinct integer coefficients; the monomials belong to 28 orbits under $(S_4 \times S_4 \times S_2) \rtimes S_2$.

1. Preliminaries

The simple Lie algebra $\mathfrak{sl}_n(\mathbb{C})$ is the vector space of $n \times n$ complex matrices of trace 0 with the commutator product $[A, B] = AB - BA$. The Cartan subalgebra is spanned by $H_i = E_{i,i} - E_{i,i+1}$ and the simple root vectors are $U_i = E_{i,i} + 1$ where $i = 1, \ldots, n-1$; here $E_{ij}$ in the matrix unit with 1 in position $(i, j)$. The Cartan matrix $\Gamma = (\gamma_{ij})$ determines the brackets $[H_i, U_j]$:

$$[H_i, U_j] = \gamma_{ij} U_j, \quad \gamma_{ij} = \begin{cases} 2 & \text{if } i = j \\ -1 & \text{if } |i - j| = 1 \\ 0 & \text{if } |i - j| \geq 2 \end{cases}$$

We write $\gamma_i$ for the $i$-th row of $\Gamma$. The irreducible representation of $\mathfrak{sl}_n(\mathbb{C})$ on the vector space $\mathbb{C}^n$ is given by matrix-vector multiplication $A \cdot u = Au$. We define $\mathfrak{sl}_{pqr}(\mathbb{C}) = \mathfrak{sl}_p(\mathbb{C}) \oplus \mathfrak{sl}_q(\mathbb{C}) \oplus \mathfrak{sl}_r(\mathbb{C})$, $\mathbb{C}^{pqr} = \mathbb{C}^p \otimes \mathbb{C}^q \otimes \mathbb{C}^r$.

The semisimple Lie algebra $\mathfrak{sl}_{pqr}(\mathbb{C})$ acts irreducibly on the tensor product $\mathbb{C}^{pqr}$ by

$$\begin{align*}
(A, B, C) \cdot (u \otimes v \otimes w) &= (A \cdot u) \otimes v \otimes w + u \otimes (B \cdot v) \otimes w + u \otimes v \otimes (C \cdot w).
\end{align*}$$

The standard basis of simple tensors $x_{ijk} = x_i \otimes x_j \otimes x_k$ allows us to identify the elements of $\mathbb{C}^{pqr}$ with $p \times q \times r$ arrays (also called 3-dimensional matrices). The algebra $\mathbb{C}[x_{ijk}]$ of polynomial functions on $\mathbb{C}^{pqr}$ is graded by degree and generated by the subspace $\mathbb{C}^{pqr}$ of homogeneous elements of degree 1; here we identify $\mathbb{C}^{pqr}$ with its dual $(\mathbb{C}^{pqr})^*$. A basis for the homogeneous subspace of degree $d$ consists of the monomials with exponent arrays $E$ of nonnegative integers summing to $d$:

$$X = X(E) = \prod_{i,j,k} x_{ijk}^{e_{ijk}}, \quad E = (e_{ijk}),$$

The action of $\mathfrak{sl}_{pqr}(\mathbb{C})$ extends from $\mathbb{C}^{pqr}$ to $\mathbb{C}[x_{ijk}]$ by the derivation property,

$$D \cdot (fg) = (D \cdot f) g + f (D \cdot g), \quad D = (A, B, C).$$

Each homogeneous subspace is finite dimensional and hence completely reducible as a representation of $\mathfrak{sl}_{pqr}(\mathbb{C})$. The subalgebra of invariants is the direct sum of the
trivial 1-dimensional representations in each degree: the polynomials \( f \) such that \( D \cdot f = 0 \) for all \( D \in \mathfrak{sl}_{pqr}(\mathbb{C}) \). By elementary representation theory, it suffices to assume that \( H_i \cdot f = 0 \) and \( E_r \cdot f = 0 \) for all three summands of \( \mathfrak{sl}_{pqr}(\mathbb{C}) \). The results in the rest of this section are either standard or can be proved by straightforward calculation; a simpler example of this approach appears in Bremner [1]. We mention Humphreys [3] as a reference for Lie algebras and representation theory.

**Lemma 1.** The elements \( H_i^{(1)}, H_j^{(2)}, H_k^{(3)} \) in the summands \( \mathfrak{sl}_p(\mathbb{C}), \mathfrak{sl}_q(\mathbb{C}), \mathfrak{sl}_r(\mathbb{C}) \) act diagonally on monomials as the following linear differential operators:

\[
H_i^{(1)} \cdot X = \left( \frac{\partial}{\partial x_{i,j,k}} - \frac{\partial}{\partial x_{i+1,j,k}} \right) X = \left( \sum_{j,k} e_{i,j,k} - e_{i+1,j,k} \right) X \quad (1 \leq i \leq p-1),
\]

\[
H_j^{(2)} \cdot X = \left( \frac{\partial}{\partial x_{i,j,k}} - \frac{\partial}{\partial x_{i,j+1,k}} \right) X = \left( \sum_{i,k} e_{i,j,k} - e_{i,j+1,k} \right) X \quad (1 \leq j \leq q-1),
\]

\[
H_k^{(3)} \cdot X = \left( \frac{\partial}{\partial x_{i,j,k}} - \frac{\partial}{\partial x_{i,j,k+1}} \right) X = \left( \sum_{i,j} e_{i,j,k} - e_{i,j,k+1} \right) X \quad (1 \leq k \leq r-1).
\]

**Definition 2.** The weight \( \Omega(X) \) of a monomial is the ordered list of \( p+q+r-3 \) integers consisting of its eigenvalues for \( H_i^{(1)}, H_j^{(2)}, H_k^{(3)} \):

\[
\Omega(X) = (\Omega_1, \Omega_2, \Omega_3) = (\omega_1, \ldots, \omega_{p+q+r}).
\]

The weight space \( W(d; \Omega) \) has a basis consisting of the monomials of degree \( d \) and weight \( \Omega \). The zero weight space in degree \( d \) is the space \( W(d; 0) \).

**Lemma 3.** A basis of \( W(d; 0) \) consists of the monomials \( X(E) \) whose exponent arrays \( E \) have entry sum \( d \) and satisfy the equal parallel slice property. That is, the following entry sums over 2-dimensional slices do not depend on \( i, j, k \) respectively:

\[
T_1(i) = \sum_{j,k} e_{i,j,k}, \quad T_2(j) = \sum_{i,k} e_{i,j,k}, \quad T_3(k) = \sum_{i,j} e_{i,j,k}.
\]

Hence the degree of an invariant polynomial is a multiple of \( \text{LCM}(p,q,r) \).

**Lemma 4.** The elements \( U_1^{(1)}, U_2^{(2)}, U_3^{(3)} \) in the summands \( \mathfrak{sl}_p(\mathbb{C}), \mathfrak{sl}_q(\mathbb{C}), \mathfrak{sl}_r(\mathbb{C}) \) act on monomials as the following linear differential operators:

\[
U_1^{(1)} = x_{i,j,k} \frac{\partial}{\partial x_{i+1,j,k}}, \quad U_2^{(2)} = x_{i,j,k} \frac{\partial}{\partial x_{i,j+1,k}}, \quad U_3^{(3)} = x_{i,j,k} \frac{\partial}{\partial x_{i,j,k+1}}.
\]

Hence we have the following formulas, where \( E', E'', E''' \) depend on \( i, j, k \) and are the same as \( E \) with the indicated exceptions:

\[
U_1^{(1)} \cdot X = \sum_{j,k} e_{i+1,j,k} X(E'), \quad \begin{cases} e_{i+1,j,k} = e_{i+1,j,k} - 1 \\ e_{i,j,k} = e_{i,j,k} + 1 \end{cases}
\]

\[
U_2^{(2)} \cdot X = \sum_{i,k} e_{i,j+1,k} X(E''), \quad \begin{cases} e_{i,j+1,k} = e_{i,j+1,k} - 1 \\ e_{i,j,k} = e_{i,j,k} + 1 \end{cases}
\]

\[
U_3^{(3)} \cdot X = \sum_{i,j} e_{i,j,k+1} X(E'''), \quad \begin{cases} e_{i,j,k+1} = e_{i,j,k+1} - 1 \\ e_{i,j,k} = e_{i,j,k} + 1 \end{cases}
\]
**Lemma 5.** In each degree $d$, the actions of $U_i^{(1)}$, $U_j^{(2)}$, $U_k^{(3)}$ induce linear maps from the zero weight space to higher weight spaces as follows:

\[
U_i^{(1)}: W(d; 0) \longrightarrow W(d; \Gamma_i, 0, 0), \\
U_j^{(2)}: W(d; 0) \longrightarrow W(d; 0, \Gamma_j, 0), \\
U_k^{(3)}: W(d; 0) \longrightarrow W(d; 0, 0, \Gamma_k).
\]

**Definition 6.** In degree $d$, the map $U(d)$ is the direct sum of all $U_i^{(1)}$, $U_j^{(2)}$, $U_k^{(3)}$:

\[
U(d): W(d; 0) \longrightarrow \bigoplus_i W(d; \Gamma_i, 0, 0) \oplus \bigoplus_j W(d; 0, \Gamma_j, 0) \oplus \bigoplus_k W(d; 0, 0, \Gamma_k).
\]

**Theorem 7.** In degree $d$, the invariant polynomials are the nullspace of $U(d)$.

We quote the following formula for the degree of the hyperdeterminant of a 3-dimensional array whose dimensions belong to the “sub-boundary” format.

**Lemma 8.** (Gelfand et al. [2], Corollary 3.8) The hyperdeterminant of an array of size $p \times q \times r$ where $p \geq q \geq r$ and $p = q + r - 2$ has degree

\[
2 \left( \frac{q + r - 2}{q - 1} \right) (q - 1)(r - 1).
\]

In particular, for $p = q$ and $r = 2$ we obtain $2p(p - 1)$.

We now specialize to $(p, q, r) = (3, 3, 2)$ until Section 4 in this case the hyper-determinant has degree 12.

**Definition 9.** Let $B(d; \Omega)$ be the set of all exponent arrays $E$ for monomials $X(E)$ of degree $d$ and weight $\Omega$. For $\Omega = 0$, we consider the symmetry group of $B(d; 0)$, which is the semidirect product $G = (S_3 \times S_3 \times S_2) \rtimes S_2$. The factors in the normal subgroup permute the slices in the three directions; the remaining $S_2$ transposes the first and second $S_3$.

More precisely, if $g = (\alpha, \beta, \gamma, \delta) \in G$, then we have:

\[
(\alpha \cdot E)_{i,j,k} = e_{\alpha(i),j,k}, \quad (\beta \cdot E)_{i,j,k} = e_{i,\beta(j),k}, \quad (\gamma \cdot E)_{i,j,k} = e_{i,j,\gamma(k)},
\]

\[
(\delta \cdot E)_{ijk} = \begin{cases} 
eq & \delta = \bigcirc \\ e_{ijk} & \delta = (12)
\end{cases}
\]

**Definition 10.** The flattening of an exponent array $E = (e_{ijk})$ is the ordered list obtained by applying lex order to the subscripts:

\[
\text{flat}(E) = [e_{111}, e_{112}, e_{121}, e_{122}, e_{131}, e_{132}, \ldots, e_{331}, e_{332}].
\]

The total order on exponent arrays is defined to be the lex order on flattens; that is, $E < E'$ for $\text{flat}(E) = [f_1, f_2, \ldots, f_{18}]$ and $\text{flat}(E') = [f'_1, f'_2, \ldots, f'_{18}]$ if and only if $f_i < f'_i$ where $i$ is the least index with $f_i \neq f'_i$. The matrix form of $E$ is:

\[
\begin{bmatrix}
  e_{111} & e_{112} & e_{131} & e_{112} & e_{122} & e_{132} \\
  e_{211} & e_{212} & e_{231} & e_{212} & e_{222} & e_{232} \\
  e_{311} & e_{312} & e_{331} & e_{312} & e_{322} & e_{332}
\end{bmatrix}
\]
2. Degree 6: no invariants

We show that there are no invariant polynomials in degree 6 for $3 \times 3 \times 2$ arrays. The next two results can be obtained easily with a computer algebra system.

Lemma 11. In degree 6 there are 288 exponent arrays $E$ for monomials $X(E)$ of weight zero, forming 8 orbits under the action of the symmetry group $G$. The sizes of these orbits, and their minimal representatives in matrix form, are:

- 36
  \[
  \begin{bmatrix}
  0 & 0 & 0 & 0 & 0 & 2 \\
  0 & 1 & 0 & 0 & 1 & 0 \\
  2 & 0 & 0 & 0 & 0 & 0 \\
  \end{bmatrix}
  \]
  \[
  \begin{bmatrix}
  0 & 0 & 0 & 0 & 0 & 2 \\
  0 & 1 & 0 & 0 & 1 & 0 \\
  1 & 0 & 0 & 0 & 0 & 0 \\
  \end{bmatrix}
  \]
- 72
  \[
  \begin{bmatrix}
  0 & 0 & 1 & 0 & 0 & 1 \\
  0 & 1 & 0 & 0 & 1 & 0 \\
  1 & 0 & 0 & 0 & 0 & 0 \\
  \end{bmatrix}
  \]
  \[
  \begin{bmatrix}
  0 & 1 & 0 & 0 & 1 & 0 \\
  1 & 0 & 0 & 0 & 0 & 0 \\
  \end{bmatrix}
  \]
- 6
  \[
  \begin{bmatrix}
  0 & 0 & 1 & 0 & 0 & 1 \\
  0 & 1 & 0 & 0 & 1 & 0 \\
  1 & 0 & 0 & 0 & 0 & 0 \\
  \end{bmatrix}
  \]
  \[
  \begin{bmatrix}
  0 & 0 & 1 & 0 & 0 & 1 \\
  1 & 0 & 0 & 0 & 0 & 0 \\
  \end{bmatrix}
  \]
- 36
  \[
  \begin{bmatrix}
  0 & 0 & 1 & 0 & 0 & 1 \\
  0 & 1 & 0 & 1 & 0 & 0 \\
  2 & 0 & 0 & 0 & 0 & 0 \\
  \end{bmatrix}
  \]
  \[
  \begin{bmatrix}
  0 & 0 & 1 & 0 & 0 & 1 \\
  1 & 0 & 0 & 0 & 0 & 0 \\
  \end{bmatrix}
  \]
- 18
  \[
  \begin{bmatrix}
  0 & 0 & 1 & 0 & 0 & 1 \\
  0 & 1 & 0 & 1 & 0 & 0 \\
  1 & 0 & 0 & 0 & 1 & 0 \\
  \end{bmatrix}
  \]
  \[
  \begin{bmatrix}
  0 & 0 & 1 & 0 & 0 & 1 \\
  1 & 0 & 0 & 0 & 1 & 0 \\
  \end{bmatrix}
  \]
- 36
  \[
  \begin{bmatrix}
  0 & 0 & 1 & 0 & 0 & 1 \\
  1 & 0 & 0 & 0 & 0 & 0 \\
  \end{bmatrix}
  \]
  \[
  \begin{bmatrix}
  0 & 0 & 1 & 0 & 0 & 1 \\
  1 & 0 & 0 & 0 & 0 & 0 \\
  \end{bmatrix}
  \]

Lemma 12. In degree 6 there are 204 exponent arrays $E$ for monomials $X(E)$ of each weight $[2, -1, 0, 0, 0], [-1, 2, 0, 0, 0], [0, 0, 2, -1, 0], [0, 0, -1, 2, 0]$, and 225 of weight $[0, 0, 0, 0, 2]$. The minimal representatives of these five sets are:

- 36
  \[
  \begin{bmatrix}
  0 & 0 & 0 & 0 & 0 & 2 \\
  0 & 1 & 0 & 0 & 1 & 0 \\
  2 & 0 & 0 & 0 & 0 & 0 \\
  \end{bmatrix}
  \]
  \[
  \begin{bmatrix}
  0 & 0 & 1 & 0 & 0 & 1 \\
  0 & 1 & 0 & 0 & 1 & 0 \\
  2 & 0 & 0 & 0 & 0 & 0 \\
  \end{bmatrix}
  \]
- 72
  \[
  \begin{bmatrix}
  0 & 0 & 0 & 0 & 0 & 2 \\
  0 & 1 & 0 & 0 & 1 & 0 \\
  1 & 0 & 0 & 0 & 0 & 0 \\
  \end{bmatrix}
  \]
  \[
  \begin{bmatrix}
  0 & 0 & 0 & 0 & 0 & 2 \\
  0 & 1 & 0 & 0 & 1 & 0 \\
  2 & 0 & 0 & 0 & 0 & 0 \\
  \end{bmatrix}
  \]
- 6
  \[
  \begin{bmatrix}
  0 & 0 & 0 & 0 & 0 & 2 \\
  0 & 1 & 0 & 0 & 1 & 0 \\
  1 & 0 & 0 & 0 & 0 & 0 \\
  \end{bmatrix}
  \]
  \[
  \begin{bmatrix}
  0 & 0 & 0 & 0 & 0 & 2 \\
  0 & 1 & 0 & 0 & 1 & 0 \\
  2 & 0 & 0 & 0 & 0 & 0 \\
  \end{bmatrix}
  \]

Proposition 13. There is no invariant polynomial in degree 6 for $3 \times 3 \times 2$ arrays.

Proof. We use the Maple package LinearAlgebra to create a zero matrix of size $513 \times 288$, consisting of a $288 \times 288$ upper block and a $225 \times 288$ lower block. The columns correspond to the ordered list of all weight zero monomials in degree 6. The rows of the lower block correspond to the ordered lists of higher weight monomials. We perform the following steps for each of the higher weights in the statement of Lemma 12 corresponding to the elements $U = U_1^{(1)}, U_2^{(1)}, U_1^{(2)}, U_2^{(2)}, U_1^{(3)}$:

1. For $j = 1, 2, \ldots, 288$ compute the action of $U$ on the $j$-th weight zero monomial, obtain a linear combination of higher weight monomials, and store the coefficients in the appropriate rows of the lower block.

2. Compute the row canonical form of the matrix using the Maple command ReducedRowEchelonForm; the lower block is now zero.

At the end of this computation, the nullspace contains the coefficient vectors of the invariant polynomials. During these five iterations, the rank of the matrix increases.
to 204, 277, 283, 286, 288; hence the nullspace is zero. (We emphasize that this computation was performed using rational arithmetic.)

3. Degree 12: the $3 \times 3 \times 2$ Hyperdeterminant

We show that there is a 1-dimensional space of invariant polynomials in degree 12. We obtain an explicit formula for a basis element which is (up to sign) the hyperdeterminant of a $3 \times 3 \times 2$ array in the sense of Gelfand et al. [2].

**Lemma 14.** Let $A$ be a matrix with entries in the ring $\mathbb{Z}$ of integers, let $r_0$ be its rank over the field $\mathbb{Q}$ of rational numbers, and let $r_p$ be its rank over the field $\mathbb{F}_p$ with $p$ elements. Then $r_p \leq r_0$ for every prime $p$. Hence the dimension of the nullspace of $A$ over $\mathbb{Q}$ is no larger than the dimension of the nullspace over $\mathbb{F}_p$.

**Proof.** The Smith normal form $S^{(0)} = (s^{(0)}_{ij})$ over $\mathbb{Q}$ satisfies $s^{(0)}_{ii} = 1$ for $1 \leq i \leq r_0$, other entries 0. Hence the Smith normal form $T = (t_{ij})$ over $\mathbb{Z}$ satisfies $t_{ii} \in \mathbb{Z}$, $t_{ii} > 0$ for $1 \leq i \leq r_0$, other entries 0. If $k \geq 0$ denotes the number of $t_{ii}$ which are divisible by $p$, then the Smith normal form $S^{(p)} = (s^{(p)}_{ij})$ over $\mathbb{F}_p$ satisfies $s^{(p)}_{ii} = 1$ for $1 \leq i \leq r_0 - k$, other entries 0. But clearly $S^{(p)}$ satisfies $s^{(p)}_{ii} = 1$ for $1 \leq i \leq r_p$, other entries 0. Hence $r_p = r_0 - k$. □

**Theorem 15.** An explicit formula for the $3 \times 3 \times 2$ hyperdeterminant is displayed in Tables 7–11: an irreducible polynomial of degree 12 in 18 variables with 16749 monomials and 41 distinct integer coefficients; the monomials belong to 178 orbits under the action of the symmetry group $(S_3 \times S_3 \times S_2) \rtimes S_2$.

**Proof.** The Maple code in Table 1 generates the 16749 exponent arrays for zero weight monomials in degree 12. (unflatten converts an array in list format to 3-dimensional table format.) The Maple code in Table 4 computes the orbits of the exponent arrays for the action of the symmetry group. (weightzeroindex does a binary search in the list of zero weight arrays; flatten converts an array in table format to list format.) The sizes and minimal representatives of the 178 orbits appear in Tables 7–11. The Maple code in Table 2 computes the exponent arrays of higher weight resulting from the action of the elements $U_1^{(1)}, U_2^{(1)}$; cases $U_1^{(2)}, U_2^{(2)}, U_1^{(3)}$ are similar. The action of these elements on each monomial of weight zero is stored in imagevectors. Each of the first four higher weights has 14442 monomials; the fifth has 15039 monomials.

We use the Maple package LinearAlgebra[Modular] to create a zero matrix of size 31788 × 16749, consisting of a 16749 × 16749 upper block and a 15039 × 16749 lower block. The columns correspond to the ordered list of all zero weight monomials in degree 12. The rows of the lower block correspond to the ordered lists of higher weight monomials. Following the same algorithm as in the proof of Proposition 13, we use modular arithmetic with $p = 1009$ to compute the nullspace of the matrix; see the Maple code in Table 5 for $U_1^{(1)}, U_2^{(1)}$ (other cases similar). (higherweightindex does a binary search in the list of higher weight arrays.) Modular arithmetic is essential in order to control memory usage for such a large matrix. The five higher weights give cumulative ranks 14442, 16673, 16727, 16744, 16748; thus the nullspace is 1-dimensional. Using symmetric representatives modulo $p$, there are 41 distinct coefficients in the canonical basis vector, and we verify that the coefficients are constant on orbits. The coefficients, their multiplicities, and the corresponding orbits are displayed in Table 6.
Our last task is to verify this result in characteristic 0. By Lemma 14 we know that the dimension of the nullspace over \( \mathbb{Q} \) is at most 1. We create an ordered list of lists, \texttt{orbitlist}, containing the indices of weight zero monomials in each orbit, and an ordered list, \texttt{invariant}, of the coefficients as a function of the orbit index. We use integer arithmetic to confirm that the elements \( U_1^{(1)}, U_2^{(1)}, U_1^{(2)}, U_2^{(2)}, U_1^{(3)} \) annihilate the basis vector of the nullspace. See Table 12 for \( U_1^{(1)}, U_2^{(1)} \); the other cases are similar. (\texttt{compress} collects terms with equal monomials.) In each case the final result is the empty list, and this completes the proof. \( \square \)

4. THE SIMPLEST INVARIANT OF A \( 4 \times 4 \times 2 \) ARRAY

Similar computations give the following result. (This invariant is not the hyperdeterminant, which has degree 24 by Lemma 8.)

**Theorem 16.** Every homogeneous invariant polynomial in the entries of a \( 4 \times 4 \times 2 \) array has degree a multiple of 4. In degree 0 there is only the trivial invariant 1, in degree 4 there are no invariants, and in degree 8 there is a 1-dimensional space of invariants. A basis of the invariants in degree 8 consists of the polynomial displayed in Table 13 which has 32 variables, 1,4148 monomials, and 13 distinct integer coefficients constant on 28 orbits under the action of \((S_4 \times S_4 \times S_2) \rtimes S_2\).

In principle this method could also be used to study the invariants of degree 12 for a \( 4 \times 4 \times 2 \) array, but in this case there are 677232 monomials of weight zero.

**Acknowledgement**

The author was supported by a Discovery Grant from NSERC, the Natural Sciences and Engineering Research Council of Canada.

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\( \text{N := 12;} \)
\( \text{weightzero := {};} \)
\( \text{for e[1] from 0 to N/3 do} \)
\( \text{for e[2] from 0 to N/3-e[1] do} \)
\( \text{for e[3] from 0 to N/3-add(e[p],p=1..2) do} \)
\( \text{for e[4] from 0 to N/3-add(e[p],p=1..3) do} \)
\( \text{for e[5] from 0 to N/3-add(e[p],p=1..4) do} \)
\( \text{e[6] := N/3-add(e[p],p=1..5):} \)
\( \text{for e[7] from 0 to N/3 do} \)
\( \text{for e[8] from 0 to N/3-e[7] do} \)
\( \text{for e[9] from 0 to N/3-add(e[p],p=7..8) do} \)
\( \text{for e[10] from 0 to N/3-add(e[p],p=7..9) do} \)
\( \text{for e[11] from 0 to N/3-add(e[p],p=7..10) do} \)
\( \text{e[12] := N/3-add(e[p],p=7..11);} \)
\( \text{for e[13] from 0 to N/3 do} \)
\( \text{for e[14] from 0 to N/3-e[13] do} \)
\( \text{for e[15] from 0 to N/3-add(e[p],p=13..14) do} \)
\( \text{for e[16] from 0 to N/3-add(e[p],p=13..15) do} \)
\( \text{for e[17] from 0 to N/3-add(e[p],p=13..16) do} \)
\( \text{e[18] := N/3-add(e[p],p=13..17);} \)
\( \text{ee := unflatten( \{seq(e[p],p=1..18)\}):} \)
\( \text{i sums := \{seq(add(add(ee[i,j,k],k=1..2),j=1..3),i=1..3)\}:} \)
\( \text{j sums := \{seq(add(add(ee[i,j,k],k=1..2),i=1..3),j=1..3)\}:} \)
\( \text{k sums := \{seq(add(add(ee[i,j,k],j=1..3),i=1..3),k=1..2)\}:} \)
\( \text{if nops(i sums)=1 and nops(j sums)=1 and nops(k sums)=1 then} \)
\( \text{weightzero := weightzero union \{[seq(e[p],p=1..18)]\}} \)
\( \text{fi} \)
\( \text{od od od od od od od od od od od od od od od od od od od od:} \)

**Table 1.** Maple code to generate exponent arrays of weight zero

\( \text{higherweight := table();} \)
\( \text{imagevectors := table();} \)
\( \text{for m to 2 do} \)
\( \text{higherweight[1,m] := {};} \)
\( \text{for n to nops(weightzero) do} \)
\( \text{x := unflatten( weightzero[n] );} \)
\( \text{imagevectors[1,m,n] := [];} \)
\( \text{for j to 3 do for k to 2 do} \)
\( \text{if x[m+1,j,k] >= 1 then} \)
\( \text{xx := copy(x): xx[m+1,j,k] := xx[m+1,j,k] - 1;} \)
\( \text{xx[m,j,k] := xx[m,j,k] + 1: xx := flatten( xx );} \)
\( \text{higherweight[1,m] := higherweight[1,m] union \{xx\};} \)
\( \text{imagevectors[1,m,n] :=} \)
\( \text{[op(imagevectors[1,m,n])], [x[m+1,j,k], xx]]} \)
\( \text{fi} \)
\( \text{od od od od od:} \)

**Table 2.** Maple code to generate exponent arrays of higher weight
groupaction := proc( g, x )
local a, b, c, d, gx, i, j, k, x0, x1, x2, x3:
a,b,c,d := op( g ): x0 := unflatten( x ):
for i to 3 do for j to 3 do for k to 2 do
x1[ a[i], j, k ] := x0[ i, j, k ] od od od:
for i to 3 do for j to 3 do for k to 2 do
x2[ i, b[j], k ] := x1[ i, j, k ] od od od:
for i to 3 do for j to 3 do for k to 2 do
x3[ i, j, c[k] ] := x2[ i, j, k ] od od od:
if d = [1,2] then gx := x3 else
for i to 3 do for j to 3 do for k to 2 do
gx[ i, j, k ] := x3[ j, i, k ] od od od fi:
RETURN( flatten(gx) )
end:

Table 3. Maple code for action of symmetry group

S2 := combinat[permute](2): S3 := combinat[permute](3):
G := [seq(seq(seq(seq([a,b,c,d],d in S2),c in S2),b in S3),a in S3)]:
o := 0: orbitlist := []: indexlist := [seq(j,j=1..nops(weightzero))]:
while indexlist <> [] do
  o := o + 1: x := weightzero[indexlist[1]]: orbit := {}:
  for g in G do
    gx := groupaction( g, x ):
    j := weightzeroindex( gx, 1, nops(weightzero) ):
    orbit := orbit union { j }
  od:
  orbitlist := [ op(orbitlist), sort(convert(orbit,list)) ]:
  indexlist := sort(convert(convert(indexlist,set) minus orbit,list))
od:

Table 4. Maple code to compute orbits of exponent arrays

with( LinearAlgebra[Modular] ): PRIME := 1009:
bigcol := nops(weightzero):
bigrow := bigcol + nops(higherweight[3,1]):
bigmat := Create( PRIME, bigrow, bigcol, integer[] ):
for m to 2 do
  for j to bigcol do
    for cx in imagevectors[1,m,j] do
      c,x := op(cx):
      i := higherweightindex( x, 1, m, 1, nops(higherweight[1,m]) ):
      bigmat[bigcol+i,j] := ( bigmat[bigcol+i,j] + c ) mod PRIME
    od:
  RowReduce(PRIME,bigmat,bigrow,bigcol,bigcol,0,0,'bigrank',0,0,true)
od:
MatBasis( PRIME, bigmat, bigrank, true ):

Table 5. Maple code to fill and reduce representation matrix
| coef | mult | orbits                  |
|------|------|-------------------------|
| −104 | 18   | 153                     |
| −68  | 36   | 150                     |
| −62  | 36   | 100                     |
| −38  | 36   | 92                      |
| −36  | 72   | 171                     |
| −34  | 144  | 86                      |
| −32  | 72   | 175                     |
| −30  | 24   | 173, 178                |
| −27  | 12   | 146                     |
| −26  | 252  | 89, 134, 141, 147       |
| −24  | 168  | 85, 93, 144             |
| −22  | 288  | 108, 164                |
| −20  | 432  | 71, 121, 129            |
| −18  | 144  | 111                     |
| −16  | 369  | 28, 39, 158, 174        |
| −12  | 648  | 32, 95, 97, 130, 136    |
| −10  | 1116 | 9, 17, 58, 60, 79, 82, 101, 102, 118, 127, 137 |
| −8   | 1098 | 13, 21, 27, 42, 45, 48, 50, 64, 73, 160, 165 |
| −6   | 942  | 14, 19, 56, 65, 72, 76, 90, 94, 132 |
| −4   | 1224 | 20, 26, 35, 46, 47, 54, 106, 154, 156, 159, 166 |
| −2   | 1224 | 2, 3, 6, 36, 37, 53, 55, 57, 91, 155, 162, 170 |
| 1    | 216  | 1, 5, 114, 122          |
| 2    | 1656 | 10, 16, 22, 30, 33, 34, 41, 67, 68, 83, 87, 96, 104, 138 |
| 4    | 1332 | 4, 8, 12, 18, 29, 38, 40, 62, 77, 78, 84, 115, 116, 117, 123, 124, 125, 126, 143 |
| 6    | 972  | 11, 24, 31, 43, 44, 63, 99, 110, 168 |
| 8    | 540  | 7, 15, 66, 119, 128     |
| 10   | 612  | 25, 51, 52, 105, 169, 177 |
| 12   | 288  | 107, 109, 172           |
| 16   | 648  | 69, 70, 80, 120, 140, 148 |
| 18   | 792  | 61, 81, 88, 112, 133, 139, 142, 145 |
| 20   | 252  | 23, 49, 59              |
| 22   | 288  | 75, 131                 |
| 24   | 144  | 161                     |
| 26   | 144  | 113, 157                |
| 30   | 72   | 135                     |
| 36   | 150  | 74, 98, 151, 152        |
| 38   | 72   | 167                     |
| 44   | 72   | 149                     |
| 50   | 72   | 103                     |
| 54   | 36   | 163                     |
| 76   | 36   | 176                     |

Table 6. Coefficients, multiplicities, and corresponding orbits
| coef | representative | size | #  | coef | representative | size | #  |
|------|----------------|------|----|------|----------------|------|----|
| 1    | [0 0 0 0 0 0] | 36   | 1  | -2   | [0 0 0 0 0 0] | 36   | 4  |
| -2   | [0 0 0 0 0 0] | 144  | 3  | 4    | [0 0 0 0 0 0] | 36   | 4  |
| 1    | [0 2 0 2 0 0] | 72   | 5  | -2   | [0 2 0 2 0 0] | 72   | 6  |
| 8    | [0 0 0 0 0 0] | 36   | 7  | 4    | [0 0 0 0 0 0] | 72   | 8  |
| -10  | [0 0 0 0 0 0] | 36   | 9  | 2    | [0 0 0 0 0 0] | 36   | 10 |
| 6    | [0 0 0 0 0 0] | 144  | 11 | 4    | [0 0 0 0 0 0] | 72   | 12 |
| -8   | [0 0 0 0 0 0] | 72   | 13 | -6   | [0 0 0 0 0 0] | 144  | 14 |
| 8    | [0 0 0 0 0 0] | 72   | 15 | 2    | [0 0 0 0 0 0] | 72   | 16 |
| -10  | [0 0 0 0 0 0] | 72   | 17 | 4    | [0 0 0 0 0 0] | 72   | 18 |
| -6   | [0 0 0 0 0 0] | 6    | 19 | -4   | [0 0 0 0 0 0] | 72   | 20 |
| -8   | [0 0 0 0 0 0] | 72   | 21 | 2    | [0 0 0 0 0 0] | 72   | 22 |
| 20   | [0 0 0 0 0 0] | 36   | 23 | 6    | [0 0 0 0 0 0] | 36   | 24 |
| 10   | [0 0 0 0 0 0] | 36   | 25 | -4   | [0 0 0 0 0 0] | 72   | 26 |
| -8   | [0 0 0 0 0 0] | 18   | 27 | -16  | [0 0 0 0 0 0] | 9    | 28 |
| 4    | [0 0 0 0 0 0] | 72   | 29 | 2    | [0 0 0 0 0 0] | 144  | 30 |
| 6    | [0 0 0 0 0 0] | 144  | 31 | -12  | [0 0 0 0 0 0] | 144  | 32 |
| 2    | [0 0 0 0 0 0] | 144  | 33 | 2    | [0 0 0 0 0 0] | 144  | 34 |
| -4   | [0 0 0 0 0 0] | 72   | 35 | -2   | [0 0 0 0 0 0] | 144  | 36 |
| -2   | [0 0 0 0 0 0] | 144  | 37 | 4    | [0 0 0 0 0 0] | 36   | 38 |
| -16  | [0 0 0 0 0 0] | 144  | 39 | 4    | [0 0 0 0 0 0] | 72   | 40 |

Table 7. The $3 \times 3 \times 2$ hyperdeterminant, orbits 1 to 40
| coef | representative size | # | coef | representative size | # |
|------|---------------------|---|------|---------------------|---|
| 2    | 144 41             |   | -8   | 72 42               |   |
| 6    | 144 43             |   | 6    | 144 44              |   |
| -8   | 144 45             |   | -4   | 144 46              |   |
| -4   | 144 47             |   | -8   | 144 48              |   |
| 20   | 144 49             |   | -8   | 144 50              |   |
| 10   | 144 51             | 10| -6   | 144 52              |   |
| -2   | 144 55             |   | 6    | 144 56              |   |
| -2   | 144 57             |   | -10  | 144 58              |   |
| 20   | 144 59             | -10| -10  | 144 60              |   |
| 18   | 144 61             |   | 4    | 144 62              |   |
| 6    | 144 63             |   | -8   | 144 64              |   |
| -6   | 144 65             |   | 8    | 144 66              |   |
| 2    | 144 67             |   | 2    | 144 68              |   |
| 16   | 144 69             |   | 16   | 144 70              |   |
| -20  | 144 71             |   | -6   | 144 72              |   |
| -8   | 144 73             |   | 36   | 144 74              |   |
| 22   | 144 75             |   | -6   | 144 76              |   |
| 4    | 144 77             |   | 4    | 144 78              |   |
| -10  | 144 79             |   | 16   | 144 80              |   |

Table 8. The $3 \times 3 \times 2$ hyperdeterminant, orbits 41 to 80
| coef | representative | size | #   | coef | representative | size | #   |
|------|----------------|------|-----|------|----------------|------|-----|
| 18   | 0 0 1 0 1 2      | 144  | 81  | -10  | 0 0 1 0 1 2      | 144  | 82  |
| 2    | 0 0 1 0 1 2      | 144  | 83  | 4    | 0 0 1 0 1 2      | 144  | 84  |
| -24  | 0 0 1 0 1 2      | 72   | 85  | -34  | 0 0 1 0 1 2      | 144  | 86  |
| 2    | 0 0 1 0 1 2      | 144  | 87  | 18   | 0 0 1 0 1 2      | 144  | 88  |
| -26  | 0 0 1 0 1 2      | 72   | 89  | -6   | 0 0 1 0 1 2      | 144  | 90  |
| -2   | 0 0 1 0 1 2      | 72   | 91  | -38  | 0 0 1 0 1 2      | 144  | 92  |
| -24  | 0 0 1 0 1 2      | 24   | 93  | -6   | 0 0 1 0 1 2      | 144  | 94  |
| -12  | 0 0 1 0 1 2      | 144  | 95  | 2    | 0 0 1 0 1 2      | 144  | 96  |
| -12  | 0 0 1 0 1 2      | 144  | 97  | 36   | 0 0 1 0 1 2      | 144  | 98  |
| 6    | 0 0 1 0 1 2      | 72   | 99  | -62  | 0 0 1 0 1 2      | 144  | 100 |
| -10  | 0 0 1 0 1 2      | 144  | 101 | -10  | 0 0 1 0 1 2      | 144  | 102 |
| 50   | 0 0 1 0 1 2      | 72   | 103 | 2    | 0 0 1 0 1 2      | 144  | 104 |
| 10   | 0 0 1 0 1 2      | 144  | 105 | -4   | 0 0 1 0 1 2      | 144  | 106 |
| 12   | 0 0 1 0 1 2      | 144  | 107 | -22  | 0 0 1 0 1 2      | 144  | 108 |
| 12   | 0 0 1 0 1 2      | 72   | 109 | 6    | 0 0 1 0 1 2      | 144  | 110 |
| -18  | 0 0 1 0 1 2      | 144  | 111 | 18   | 0 0 1 0 1 2      | 144  | 112 |
| 26   | 0 0 1 0 1 2      | 72   | 113 | 1    | 0 0 1 0 1 2      | 144  | 114 |
| 4    | 0 0 1 0 1 2      | 72   | 115 | 4    | 0 0 1 0 1 2      | 144  | 116 |
| 4    | 0 0 1 0 1 2      | 72   | 117 | -10  | 0 0 1 0 1 2      | 144  | 118 |
| 8    | 0 0 1 0 1 2      | 144  | 119 | 16   | 0 0 1 0 1 2      | 144  | 120 |

Table 9. The $3 \times 3 \times 2$ hyperdeterminant, orbits 81 to 120
| coef | representative | size | # | coef | representative | size | # |
|------|----------------|------|---|------|----------------|------|---|
| −20  | 0 0 0 0 0 2 2 2 | 144  | 121 | 1    | 0 0 0 0 0 2 2 2 | 36   | 122 |
| 4    | 0 0 0 0 0 2 2 2 | 36   | 123 | 4    | 0 0 0 0 0 2 2 2 | 72   | 124 |
| 4    | 0 0 0 0 0 2 2 2 | 36   | 125 | 4    | 0 0 0 0 0 2 2 2 | 36   | 126 |
| −10  | 0 2 0 1 0 1 0 0 2 | 72   | 127 | 8    | 0 0 0 0 0 2 2 2 | 144  | 128 |
| −20  | 0 0 1 0 0 2 1 1 | 144  | 129 | −12  | 0 0 0 0 0 2 2 2 | 72   | 130 |
| 22   | 0 0 0 0 0 2 2 2 | 144  | 131 | −6   | 0 0 0 0 0 2 2 2 | 144  | 132 |
| 18   | 0 0 0 0 0 2 2 2 | 72   | 133 | −26  | 0 0 0 0 0 2 2 2 | 72   | 134 |
| 30   | 0 0 0 0 0 2 2 2 | 72   | 135 | −12  | 0 0 0 0 0 2 2 2 | 144  | 136 |
| −10  | 0 0 0 0 0 2 2 2 | 144  | 137 | 2    | 0 0 0 0 0 2 2 2 | 144  | 138 |
| 18   | 0 0 0 0 0 2 2 2 | 144  | 139 | 16   | 0 0 0 0 0 2 2 2 | 144  | 140 |
| −26  | 0 0 0 0 0 2 2 2 | 36   | 141 | 18   | 0 0 0 0 0 2 2 2 | 36   | 142 |
| 4    | 0 0 0 0 0 2 2 2 | 72   | 143 | −24  | 0 0 0 0 0 2 2 2 | 72   | 144 |
| 18   | 0 0 0 0 0 2 2 2 | 72   | 145 | −27  | 0 0 0 0 0 2 2 2 | 12   | 146 |
| −26  | 0 0 0 0 0 2 2 2 | 72   | 147 | 16   | 0 0 0 0 0 2 2 2 | 36   | 148 |
| 44   | 0 0 0 0 0 2 2 2 | 72   | 149 | −68  | 0 0 0 0 0 2 2 2 | 36   | 150 |
| 36   | 0 0 0 0 0 2 2 2 | 6    | 151 | 36   | 0 0 0 0 0 2 2 2 | 36   | 152 |
| −104 | 0 0 0 0 0 2 2 2 | 18   | 153 | −4   | 0 0 0 0 0 2 2 2 | 72   | 154 |
| −2   | 0 0 0 0 0 2 2 2 | 144  | 155 | −4   | 0 0 0 0 0 2 2 2 | 144  | 156 |
| 26   | 0 0 0 0 0 2 2 2 | 72   | 157 | −16  | 0 0 0 0 0 2 2 2 | 144  | 158 |
| −4   | 0 0 0 0 0 2 2 2 | 72   | 159 | −8   | 0 0 0 0 0 2 2 2 | 72   | 160 |

Table 10. The $3 \times 3 \times 2$ hyperdeterminant, orbits 121 to 160
result := []:
for o to nops(invariant) do
    c := invariant[o][1]:
    for i in orbitlist[o] do
        x := unflatten(weightzero[i]):
        for j to 3 do for k to 2 do
            if x[2,j,k] >= 1 then
                xx := copy(x):
                xx[2,j,k] := xx[2,j,k] - 1:
                xx[1,j,k] := xx[1,j,k] + 1:
                result := [ op(result), [ c*x[2,j,k], flatten(xx) ] ]
            fi
        od
    od:
result := compress( result )
od:

Table 12. Maple code to verify results with integer arithmetic
| representative | size | #  | representative | size | #  |
|----------------|------|----|----------------|------|----|
| 1              | 144  | 1  | -2             | 144  | 2  |
| -1             | 288  | 3  | 1              | 1152 | 4  |
| -2             | 576  | 5  | 3              | 288  | 6  |
| 2              | 1152 | 7  | 2              | 576  | 8  |
| -3             | 1152 | 9  | 6              | 24   | 10 |
| 2              | 288  | 11 | -8             | 144  | 12 |
| -1             | 1152 | 13 | -1             | 576  | 14 |
| 9              | 192  | 4  | 1              | 36   | 16 |
| -1             | 576  | 17 | 4              | 144  | 18 |
| 4              | 144  | 19 | -6             | 288  | 20 |
| -2             | 576  | 21 | -2             | 576  | 22 |
| 3              | 1152 | 23 | 3              | 1152 | 24 |
| -2             | 1152 | 25 | -2             | 288  | 26 |
| 14             | 72   | 27 | -12            | 144  | 28 |

Table 13. The simplest invariant of a $4 \times 4 \times 2$ array