The Strength of Multi-row Aggregation Cuts for Sign-pattern Integer Programs

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Abstract

In this paper, we study the strength of aggregation cuts for sign-pattern integer programs (IPs). Sign-pattern IPs are a generalization of packing IPs and are of the form \( \{x \in \mathbb{Z}^n_+ \mid Ax \leq b\} \) where for a given column \( j \), \( A_{ij} \) is either non-negative for all \( i \) or non-positive for all \( i \). Our first result is that the aggregation closure for such sign-pattern IPs can be 2-approximated by the original 1-row closure. This generalizes a result for packing IPs from [11]. On the other hand, unlike in the case of packing IPs, we show that the multi-row aggregation closure cannot be well approximated by the original multi-row closure. Therefore for these classes of integer programs general aggregated multi-row cutting planes can perform significantly better than just looking at cuts from multiple original constraints.

1 Introduction

In a recent paper [11], Bodur et al. studied the strength of aggregation cuts. An aggregation cut is obtained as follows: (i) By suitably weighing and adding the constraints of a given integer programming (IP) formulation, one can obtain a relaxation which is defined by a single constraint together with variable bounds. (ii) All the valid inequalities for the integer hull of this knapsack-like set are called as aggregation cuts. The set obtained by adding all such aggregation cuts (for all possible aggregations) is called the aggregation closure. Such cuts are commonly used in practice by state-of-the-art solvers [23, 24, 22, 19, 17] and also have been studied in theory [19, 2, 14]. A very special subclass of the aggregation cuts are the cuts obtained from original constraints of the formulation as the knapsack-like relaxation (i.e. no aggregation at all). The weaker closure obtained from such cuts is called as the original 1-row closure [11]. The paper [11] shows that for packing and covering IPs, the aggregation closure can be 2-approximated by the original 1-row closure. In contrast, they show that for general IPs, the aggregation closure can be arbitrarily stronger than the original 1-row closure.

The aggregation cuts are obtained based on our ability to generate valid inequalities for feasible sets described by one non-trivial constraint and variable bounds. Recently there has a
large body of work on multi-row cuts, for example [14, 16, 18, 13, 12, 8, 9, 15, 3]. Also see
the review articles [21, 7, 6] and analysis of strength of these cuts [5, 4, 10]. Therefore, it is
natural to consider the notion of multi-row aggregation cuts. Essentially by using \( k \) different
set of weights on the constraints of the problem one can produce a relaxation that involves
\( k \) constraints together with variable bounds. We call the valid inequalities for the integer
hull of such relaxations as \( k \)-row or multi-row aggregation cuts. Analogous to the case of
aggregation cuts, we can also define the notion of \( k \)-row aggregation closure and the original
\( k \)-row closure [11] (i.e. generate cuts from all relaxations described by \( k \) constraints from the IP
formulation). The results in [11] can be used to show that for packing and covering IPs the \( k \)-row
aggregation closure can be approximated by the original \( k \)-row closure within a multiplicative
factor that depends only on \( k \). (We obtain sharper bounds for the case of \( k = 2 \) in this paper.)

For packing and covering IPs all the coefficients of all the variables in all the constraints
have the same sign. Therefore when we aggregate constraints we are not able to “cancel”
variables, i.e., the support of an aggregated constraint is exactly equal to the union of supports
of the original constraints used for the aggregation. A natural conjecture for the fact that the
aggregation closure (resp. multi-row aggregation closure) is well approximated by the original
1-row closure (resp. original multi-row closure) for packing and covering problems, is the fact
that such cancellations do not occur for these problems. Indeed one of the key ideas used to
obtain good candidate aggregations in the procedure described in [19] is to use aggregations
that maximize the chances of cancellation. Also see [2], which discusses the strength of split
cuts obtained from aggregations that create cancelations.

In order to study the effect of cancellations, we study the strength of aggregation closures
vis-à-vis original row closures for sign-pattern IPs. A sign-pattern IP is a problem of the form
\( \{x \in \mathbb{Z}_+^n \mid Ax \leq b\} \) where a given variable has exactly the same sign in every constraint, i.e. for
a given column \( j \), \( A_{ij} \) is either non-negative for all rows \( i \) or non-positive for all rows \( i \). Thus
aggregations do not create cancellations.

Our study reveals interesting results. On the one hand we are able to show that the ag-
grgregation closure for such sign-pattern IPs is 2-approximated by the original 1-row closure,
supporting the conjecture that non-cancellation implies that aggregation is less effective. On
the other hand, unlike packing and covering IPs, the multi-row aggregation closure cannot be
well approximated by the original multi-row closure. So for these classes of problems, multi-row
cuts may do significantly better than single-row cuts, especially those obtained by aggregation.

The structure of the rest of the paper is as follows. In Section 2 we provide formal definitions
and statements of our results. In Section 3 we present the proofs for our results.

2 Definitions and statement of results

2.1 Definitions

For an integer \( n \), we use the notation \( [n] \) to describe the set \( \{1, \ldots, n\} \) and for \( k \leq n \) non-
negative integer, we use the notation \( \binom{[n]}{k} \) to describe all subsets of \( [n] \) of size \( k \). For \( i \in [n] \), we
denote by \( e_i \) the \( i^{th} \) vector of the standard basis of \( \mathbb{R}^n \). The convex hull of a set \( S \) is denoted
as \( \text{conv}(S) \). For a set \( S \subset \mathbb{R}^n \) and a positive scalar \( \alpha \) we define \( \alpha S := \{\alpha u \mid u \in S\} \). We use
\( P^I \) to denote the convex hull of integer feasible solutions of \( P \) (i.e. the integer hull of \( P \)). For
a given linear objective function, we let \( z^{LP}, z^{IP} \) denote the optimal objective function over \( P \)
and \( P^I \) respectively.

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2.1.1 Sign-pattern IPs

**Definition 1.** Let \( n \) be an integer, let \( J^+, J^- \subset [n] \) such that \( J^+ \cap J^- = \emptyset \) and \( J^+ \cup J^- = [n] \). We call a polyhedron \( P \), a \((J^+, J^-)\) sign-pattern polyhedron if it is of the form

\[
P = \left\{ x \in \mathbb{R}^n_+ \mid \sum_{j \in J^+} A_{ij} x_j - \sum_{j \in J^-} A_{ij} x_j \leq b_i \quad \forall i \in [m] \right\},
\]

where \( A_{ij}, b_i \geq 0, \forall i \in [m], \forall j \in [n] \). Additionally, we require \( A_{ij} \leq b_i \forall j \in J^+, \forall i \in [m] \).

Through out this paper, whenever we refer to a packing polyhedron or a covering polyhedron, we make a similar assumption on the coefficients defining the polyhedron, i.e., if \( P := \{ x \in \mathbb{R}^n_+ | Ax \leq b \} \) is a packing (resp. \( P := \{ x \in \mathbb{R}^n_+ | Ax \geq b \} \) is a covering) polyhedron we assume \( A_{ij} \leq b_i \) for all \( i \in [2], j \in [n] \). Also we assume that all data is rational.

**Definition 2.** Given two polyhedra \( P \) and \( Q \) contained in \( \mathbb{R}^n_+ \) such that \( P \supseteq Q \supseteq \{0\} \), and a positive scalar \( \alpha \geq 1 \), we say that \( P \) is an \( \alpha \)-approximation of \( Q \) if \( P \subset \alpha Q \).

**Remark 1.** Let \( P \supseteq Q \supseteq \{0\} \). Suppose we are maximizing a linear objective over \( P \) and \( Q \) and let the optimal objective function over \( P \) and \( Q \) be \( z^P \) and \( z^Q \) respectively. Then \( P \) being an \( \alpha \)-approximation of \( Q \) implies that either \( z^P = z^Q = \infty \) or \( z^P \geq z^Q \geq \frac{1}{\alpha} \cdot z^P \). Therefore, in order to show \( P \) is not an \( \alpha \)-approximation of \( Q \), all we need to do is to establish that there is a linear objective such that \( z^P, z^Q < \infty \) and \( z^Q < \frac{1}{\alpha} \cdot z^P \).

**Remark 2.** Definition 2 does not hold for covering polyhedron. We will refer to \( \alpha \)-approximation results for covering polyhedron for comparison. Given two covering polyhedra \( P \) and \( Q \) such that \( P \supseteq Q \), and a positive scalar \( \alpha \geq 1 \), we say that \( P \) is an \( \alpha \)-approximation of \( Q \) if \( P \subset \frac{1}{\alpha} Q \). This is equivalent to saying that if we are minimizing a non-negative linear function over \( P \) and \( Q \) (and the optimal objective function over \( P \) and \( Q \) are \( z^P \) and \( z^Q \) respectively), then \( z^P \leq z^Q \leq \alpha \cdot z^P \).

2.1.2 Closures

Given a polyhedron \( P \), we are interested in cuts for the pure integer set \( P \cap \mathbb{Z}^n \).

**Definition 3.** For \( P = \{ x \geq 0 \mid Ax \leq b \} \), where \( A \in \mathbb{R}^{m \times n}, k \geq 1 \) integer, and \( \lambda_1, \ldots, \lambda_k \in \mathbb{R}^n_+ \), let

\[
P(\lambda_1, \ldots, \lambda_k) := \{ x \geq 0 \mid \lambda_1 Ax \leq \lambda_1 b, \ldots, \lambda_k Ax \leq \lambda_k b \}.
\]

\[
P^I(\lambda_1, \ldots, \lambda_k) := \text{conv} \left( \{ x \in \mathbb{Z}^n_+ \mid \lambda_1 Ax \leq \lambda_1 b, \ldots, \lambda_k Ax \leq \lambda_k b \} \right).
\]

**Definition 4** (Closures). Given a polyhedron \( P = \{ x \in \mathbb{R}^n_+ \mid Ax \leq b \} \), where \( A \in \mathbb{R}^{m \times n} \), we define its aggregation closure \( A(P) \) as

\[
A(P) = \bigcap_{\lambda \in \mathbb{R}^n_+} P^I(\lambda).
\]

We can generalize the aggregation-closure to consider simultaneously \( k \) aggregations, where \( k \in \mathbb{Z} \) and \( k \geq 1 \). More precisely, for a polyhedron \( P \) the \( k \)-aggregation closure is defined as

\[
A_k(P) := \bigcap_{\lambda_1, \ldots, \lambda_k \in \mathbb{R}^n_+} P^I(\lambda_1, \ldots, \lambda_k).
\]
Similarly, the original 1-row closure $1 \mathcal{A}(P)$ is defined as

$$1 \mathcal{A}(P) := \bigcap_{i \in [m]} P^I(e_i).$$

We can generalize the original 1-row closure, to the original $k$-row closure $k \mathcal{A}(P)$. More precisely, for a polyhedron $P$ the original $k$-row closure is defined as

$$k \mathcal{A}(P) := \bigcap_{\{i_1, \ldots, i_k\} \in \binom{[m]}{k}} P^I(e_{i_1}, \ldots, e_{i_k}).$$

Given a linear objective function, we let $z^\mathcal{A}$, $z^{k \mathcal{A}}$, $z^{1 \mathcal{A}}(P)$, and $z^{k \mathcal{A}}(P)$ be the optimal objective function over $\mathcal{A}$, $\mathcal{A}_k$, $1 \mathcal{A}(P)$ and $k \mathcal{A}(P)$ respectively.

2.2 Statement of results

The first result compares the aggregation closure with the LP relaxation of a $(J^+, J^-)$ sign-pattern polyhedron.

**Theorem 1.** For a $(J^+, J^-)$ sign-pattern polyhedron $P$, we have that $\mathcal{A}(P)$ can be 2-approximated by $P$, and thus by $1 \mathcal{A}(P)$.

This result generalizes the result obtained in [11] for the case of packing IPs. Since the ratio of 2 is already known to be tight for the case of packing instances [11], the result of Theorem 1 is tight.

Next we show that, in general, for $(J^+, J^-)$ sign-pattern IPs, the aggregation-closure does not do a good job at approximating the 2-aggregation closure.

**Theorem 2.** There is a family of $(J^+, J^-)$ sign-pattern polyhedra for which $\mathcal{A}$ is an arbitrarily bad approximation to $A_2$, i.e. for each $\alpha > 1$, there is a $(J^+, J^-)$ sign-pattern polyhedron $P$ such that $\mathcal{A}(P)$ is not an $\alpha$-approximation of $A_2(P)$. In contrast, if $P$ is a packing (resp. covering) polyhedron, then $\mathcal{A}(P) \subseteq 3(A_2(P))$ (resp. $\mathcal{A}(P) \subseteq \frac{1}{2\alpha}(A_2(P))$).

The previous result shows that for non-trivial $(J^+, J^-)$ sign-pattern polyhedra, using multiple row cuts can have significant benefits over one row cuts. This is different than for the case of packing/covering problems (where the improvement is bounded).

The next result shows that the aggregation-closure considering simultaneously 2 aggregations ($A_2$) can be arbitrarily stronger than the original 2-row closure ($2 \mathcal{A}$).

**Theorem 3.** There is a family of $(J^+, J^-)$ sign-pattern polyhedra with 4 constraints for which $2 \mathcal{A}$ is an arbitrarily bad approximation to $A_2$, i.e. for each $\alpha > 1$, there is a $(J^+, J^-)$ sign-pattern polyhedron $P$ such that $2 \mathcal{A}(P)$ is not an $\alpha$-approximation of $A_2(P)$. In contrast, if $P$ is a packing (resp. covering) polyhedron, then $2 \mathcal{A}(P) \subseteq 3(A_2(P))$ (resp. $2 \mathcal{A}(P) \subseteq \frac{1}{2\alpha}(A_2(P))$).

The previous results establish the comparison between the sets $1 \mathcal{A}(P)$ and $\mathcal{A}(P)$, $\mathcal{A}(P)$ and $A_2(P)$, and $2 \mathcal{A}(P)$ and $A_2(P)$. These results are presented in Table I.
Table 1: Upper bound (lower bound for covering case) on $\alpha$ for various containment relations; $m$ is the number of constraints.

| $A(P) \subset \alpha A(P)$ | $A(P) \subset \alpha A_2(P)$ | $A(P) \subset \alpha A_2(P)$ |
|-----------------------------|-------------------------------|-------------------------------|
| $\alpha \leq 2$ ($[11]$)   | $\alpha \leq 3$ if $m \geq 2$ | $\alpha \leq 3$ if $m \geq 2$ |
| $\alpha \geq \frac{1}{2} ([11])$ | $\alpha \geq \frac{1}{2.5}$ if $m \geq 2$ | $\alpha \leq \infty$ if $m \geq 2$ |
| $\alpha \leq \infty$ if $m \geq 2$ | $\alpha \leq \infty$ if $m \geq 2$ | $\alpha \leq \infty$ if $m \geq 2$ |

### 3 Proofs

#### 3.1 Proof of Theorem 1

First, we need some general properties for $(J^+, J^-)$ sign-pattern LPs.

**Proposition 1.** Consider a $(J^+, J^-)$ sign-pattern polyhedron defined by one non-trivial constraint $P = \{ x \geq 0 \mid \sum_{j \in J^+} a_j x_j - \sum_{j \in J^-} a_j x_j \leq b \}$ and let $c$ be a vector with the same sign-pattern, i.e. $c_j \geq 0$ $\forall j \in J^+$ and $c_j \leq 0$ $\forall j \in J^-$. Then:

1. $z^{LP} = \max_{x \in P} c^T x$ is bounded if and only if $\max_{j \in J^+} \frac{c_j}{a_j} \leq \min_{j \in J^-} \frac{-c_j}{a_j}$.

2. If $z^{LP}$ is bounded, then there exists an optimal solution $x^{LP}$ such that $x^{LP}_j = b/a_j$ for $j \in \arg\max_{j \in J^+} c_j/a_j$ and $x^{LP}_k = 0$ for $k \in [n]\{j\}$.

3. If $z^{LP}$ is bounded, then $z^{LP} \leq 2z^{IP}$, where $z^{IP} = \max_{x \in P^I} c^T x$.

**Proof.** Clearly $0 \in P$, thus the $(J^+, J^-)$ sign-pattern LP cannot be infeasible. Consider its dual

$$\min \{by \mid a_jy \geq c_j \forall j \in J^+, a_jy \leq -c_j \forall j \in J^-, y \geq 0\},$$

which is feasible if and only if $\max_{j \in J^+} \frac{c_j}{a_j} \leq \min_{j \in J^-} \frac{-c_j}{a_j}$.

If $z^{LP}$ is bounded, then there exists an optimal solution that is an extreme point. Since the problem is defined by a single non-trivial constraint, each extreme point can have at most one non-zero coefficient, thus a maximizer $x^{LP}$ over the set of extreme points must be of the form $x^{LP}_j = b/a_j \geq 1$ for some $j^* \in J^+$ and $x^{LP}_k = 0 \forall j \in [n]\{j^*\}$.

Clearly $[x^{LP}] \in P^I$, thus $\frac{z^{LP}}{z^{IP}} \leq \frac{b/a_{j^*}}{[b/a_{j^*}]}$. Finally, since $P$ is a $(J^+, J^-)$ sign-pattern polyhedron $b/a_{j^*} \geq 1$ and thus $\frac{z^{LP}}{z^{IP}} \leq 2$.  

**Proposition 2.** Consider a $(J^+, J^-)$ sign-pattern polyhedron $P$, then $P^I$ is also a $(J^+, J^-)$ sign-pattern polyhedron.
Proof. First, since $P$ is a $(J^+, J^-)$ sign-pattern polyhedron, $0, e_1, \ldots, e_n \in P$, then $P^I$ is a non-empty full-dimensional polyhedron. We show that for every non-trivial facet $ax \leq b$ (that is facets other than $x_j \geq 0$), we must have $a_j \geq 0$ for $j \in J^+$ and $a_j \leq 0$ for $j \in J^-$. 

For $j \in J^-$. Note that the recession cone of $P^I$ is the same as the recession cone of $P$. Then for every facet $ax \leq b$ we have $a_j \leq 0$ for $j \in J^-$ (otherwise $e_j$ would not be in the recession cone of $P^I$).

For $j \in J^+$, assume that there exists a facet $ax \leq b$ s.t. $a_j < 0$. Consider $a' = a - a_j e_j$ (we zero out the $j$-th component), if $a'x \leq b$ is valid, it corresponds to a stronger non-trivial constraint than $ax \leq b$. In order to show that it is valid, assume that there exists $x \in P \cap \mathbb{Z}^n$ s.t. $a'x > b$. Note that $x_j \geq 1$ (since otherwise $a'x = ax \leq b$). Consider $x' = x - x_j e_j$ (clearly $x' \in P \cap \mathbb{Z}^n$), then $b < a'x = ax' \leq b$, a contradiction. 

**Proposition 3.** Let $P$ be a $(J^+, J^-)$ sign-pattern polyhedron defined by one constraint, then $P \subset 2P^I$.

Proof. Assume by contradiction that there exists $x' \in \frac{1}{2}P$ s.t. $x' \notin P^I$. Since $P^I$ is a $(J^+, J^-)$ sign-pattern polyhedron, each non-trivial facet-defining inequality $ax \leq b$ satisfies $a_j \geq 0 \forall j \in J^+$ and $a_j \leq 0 \forall j \in J^-$. Since $x' \notin P^I$, for one of these facets, we have: $ax' > b$. Now, if we consider $a$ as an objective: $\max_{x \in P} ax \leq b$ and thus defines a bounded problem. Since the IP is feasible and bounded and $P$ is defined by rational data, the LP is also bounded (see [20]). Hence by Proposition 1 $ax' \leq \frac{1}{2}z^{LP} \leq z^I \leq b$ a contradiction.

**Observation 1.** Let $\{S_i\}_{i \in I}$ be a collection of subsets in $\mathbb{R}^n$ and let $\alpha \in \mathbb{R}_+$. Then $\alpha (\cap_{i \in I} S_i) = \cap_{i \in I} \alpha (S_i)$.

Now, we prove Theorem 1.

Proof. By definition, we have that $P \subset P(\lambda), \forall \lambda \in \mathbb{R}_+^m$. Since $P(\lambda)$ corresponds to a $(J^+, J^-)$ sign-pattern polyhedron defined by one constraint, by Proposition 3 we have that $P(\lambda) \subset 2P^I(\lambda)$. Then taking intersection over all $\lambda \in \mathbb{R}_+^m$ and by Observation 1 we have

$$P \subset \bigcap_{\lambda \in \mathbb{R}_+^m} P(\lambda) \subset \bigcap_{\lambda \in \mathbb{R}_+^m} 2P^I(\lambda) = 2 \bigcap_{\lambda \in \mathbb{R}_+^m} P^I(\lambda) = 2A(P).$$

Since $1A(P)$ is contained in $P$, we have that $1A(P)$ is a 2-approximation of $A(P)$.

### 3.2 Proof of Theorem 2

In order to prove the first part of Theorem 2 consider the following family of $(J^+, J^-)$ sign-pattern polyhedra and $M \geq 2$ integer

$$\begin{align*}
\max \quad & x_1 - (M-1)x_2 \\
\text{s.t.} \quad & x_1 - M(M-1)x_2 \leq 1 \\
& x_1 \leq M + 1 \\
& x_1, x_2 \geq 0.
\end{align*}$$

(1)

Note that the only integral solutions are $(0, 0)$, $(1, 0)$ and $(\bar{x}_1, \bar{x}_2)$, where $\bar{x}_1, \bar{x}_2 \in \mathbb{Z}_+, \bar{x}_1 \leq M + 1$ and $\bar{x}_2 \geq 1$. Therefore, $z^{IP} = 2$ and corresponds to $(M + 1, 1)$. Additionally, $z^{LP} = M$ since the feasible point $(M + 1, \frac{1}{M-1})$ achieves that objective value and by multiplying the first
constraint by \( \frac{1}{M} \), multiplying the second constraint by \( \frac{M-1}{M} \) and addition them we obtain the valid inequality: \( x_1 - (M - 1) x_2 \leq M \). Thus, in this case we have that: \( \frac{z_{LP}}{z_{IP}} = \frac{M}{2} \). Trivially, since we have only two constraints \( A_2(P) = P_I \). Now, we present our proof of the first part of Theorem 2.

**Proof.** It follows from Theorem 1 that for any \((J^+, J^-)\) **sign-pattern** polyhedron \( \frac{z_{LP}}{z_{IP}} \in [1, 2] \). For the family of \((J^+, J^-)\) **sign-pattern** polyhedra we have that \( z_{IP} = z_{A^2} \) and therefore

\[
\frac{z^A}{z_{A^2}} = \frac{z_{LP}}{z_{IP}} \cdot \frac{z^A}{z_{LP}} \geq \frac{M}{2}.
\]

Since \( M \) can be arbitrarily large, \( A(P) \) cannot be an \( \alpha \)-approximation of \( A_2(P) \) for any finite value of \( \alpha \). \( \square \)

In order to prove the second part of Theorem 2 we need the following result regarding packing and covering integer programs.

**Proposition 4.** Let \( P := \{ x \in \mathbb{R}_+^n | Ax \leq b \} \) be a packing (resp. \( P := \{ x \in \mathbb{R}_+^n | Ax \geq b \} \) be a covering) polyhedron defined by two non-trivial constraints, i.e. \( A \in \mathbb{R}^{2 \times n} \), satisfying the property \( A_{ij} \leq b_i \) for all \( i \in [2], j \in [n] \). Then \( P \subseteq 3P_I \) (resp. \( P \subseteq \frac{1}{2} P_I \)).

A proof of Proposition 4 is presented in the Appendix. Now we present a proof of the second part of Theorem 2.

**Proof.** Let \( P \) be a packing polyhedron. We have that

\[
A(P) = \bigcap_{\lambda_1 \in \mathbb{R}_+^m} P_I(\lambda_1) \subset \bigcap_{\lambda_1 \in \mathbb{R}_+^m} P(\lambda_1) \subset \bigcap_{\lambda_1, \lambda_2 \in \mathbb{R}_+^m} P(\lambda_1, \lambda_2) \subset 3 \bigcap_{\lambda_1, \lambda_2 \in \mathbb{R}_+^m} P_I(\lambda_1, \lambda_2) = 3A_2(P),
\]

where the third containment follows from Proposition 4.

Using Proposition 4 the proof of the covering case is the similar to the packing case. \( \square \)

### 3.3 Proof of Theorem 3

In order to prove the first part of Theorem 3 we introduce the following family of instances. For \( M \geq 2 \) an even integer:

\[
\begin{align*}
\max \quad & x_1 - \frac{M}{2} x_2 - \frac{M}{2} x_3 - \frac{M}{2} x_4 \\
\text{s.t.} \quad & x_1 - M x_2 - M x_3 \leq 1 \\
& x_1 - M x_2 \quad \leq M x_4 \leq 1 \\
& x_1 \quad - M x_3 - M x_4 \leq 1 \\
& x_1 \quad \leq M + 1 \\
& x_1, x_2, x_3, x_4 \geq 0.
\end{align*}
\]

It is not difficult to verify that \( z_{IP} = 1 \). The point \((1, 0, 0, 0)\) has value 1 and for any feasible solution such that \( x_1 \geq 2 \), we must have \( x_2 + x_3 + x_4 \geq 2 \) (from constraints (3) – (5)) thus the objective function value in this case is at most 1. Additionally, \( z_{LP} = \frac{M}{2} + 1 \) since the feasible point \((M + 1, \frac{1}{2}, \frac{1}{2}, \frac{1}{2})\) achieves that objective value and by aggregating constraints (3) – (6) and dividing by 4, we obtain the valid inequality: \( x_1 - \frac{M}{2} x_2 - \frac{M}{2} x_3 - \frac{M}{2} x_4 \leq \frac{M}{4} + 1 \).

Now, the proof of the first part of Theorem 3
Proof. We show that for the family of instances $\{2\} - \{6\}$, $\frac{z(z - 4)}{z} = \frac{M}{4} + 1$ and thus $2 \cdot A$ can be an arbitrarily bad approximation of $A_2$.

First, we show that $z^{2 \cdot A} = \frac{M}{4} + 1$ by showing that the optimal point for the LP relaxation is also feasible for $2 \cdot A$. To conclude the proof, we show that $z^{A_2} = z^{LP}$ by providing an upper bound on $z^{A_2}$ coming from a particular selection of multipliers.

In the case of $2 \cdot A$, we verify that $(x, y_1, y_2, y_3) = (M + 1, \frac{1}{2}, \frac{1}{2}, \frac{1}{2})$ is in $P^I(e_i, e_i)$, where $K := \{e_i, e_i\}$ corresponds to an arbitrary selection of two constraints, i.e. any $K \in \binom{4}{2}$. Let $S^\prime_K$ be those variables with negative coefficients that are present in the inequalities in $K$. If constraint $\{j\}$ is in $K$, let $l$ denote the smallest index in $S^\prime_K$. Otherwise, let $l$ denote the index of the variable (out of $\{x_2, x_3, x_4\}$) that is present in both constraints $\{e_i, e_i\}$ (note that there must always be one such index). Then it can be verified that the points $(M + 1, 0, 0, 0) + e_i^\top$ and $(M + 1, 1, 1, 1) - e_i^\top$ are in $P^I(e_i, e_i)$ and so is the midpoint $(M + 1, \frac{1}{2}, \frac{1}{2}, \frac{1}{2})$. The latter point has value: $M + 1 - \frac{M}{2} = \frac{M}{4} + 1$, thus, in terms of objective function value, $2 \cdot A$ does not provide any extra improvement when compared to the LP relaxation.

Now, we show that $z^{A_2} = 1$. Since $P^I \subset A_2(P)$, we have that $z^{A_2} \geq 1$, and by the definition of $A_2$, we have that $z^{A_2} \leq z^{P^I(\lambda, \mu)}$ $\forall \lambda, \mu \in \mathbb{R}_+^d$. Consider $\hat{\lambda} = (1, 1, 0, 0), \hat{\mu} = (0, 0, 1, 1)$ and $c^\top = (1, -\frac{M}{2}, -\frac{M}{2}, -\frac{M}{2})$, then the problem $\max \{c^\top x : x \in P^I(\hat{\lambda}, \hat{\mu})\}$ corresponds to

$$\begin{align*}
\max \quad & x_1 - \frac{M}{2} x_2 - \frac{M}{2} x_3 - \frac{M}{2} x_4 \\
\text{s.t.} \quad & 2x_1 - 2M x_2 - M x_3 - M x_4 \leq 2 \\
& 2x_1 - M x_3 - M x_4 \leq M + 2 \\
& x_1, x_2, x_3, x_4 \in \mathbb{Z}_+.
\end{align*}$$

Note that $x_3$ and $x_4$ have the same coefficients in the objective and in every constraint, thus by dropping $x_4$ and rearranging the constraints we obtain a problem with the same optimal objective function value

$$\begin{align*}
\max \quad & x_1 - \frac{M}{2} x_2 - \frac{M}{2} x_3 \\
\text{s.t.} \quad & x_1 \leq 1 + M x_2 + \frac{M}{2} x_3 \\
& x_1 \leq 1 + \frac{M}{2} + \frac{M}{2} x_3 \\
& x_1, x_2, x_3 \in \mathbb{Z}_+.
\end{align*}$$

Now, a simple case analysis (below) for each value of $x_1$, shows that $z^{P^I(\hat{\lambda}, \hat{\mu})} = 1$. Let $z$ denote the best objective function value for each case:

- Case $(x_1 = 0)$: it is easy to see that $z \leq 0$.
- Case $(x_1 = 1)$: it is easy to see that $z \leq 1$ (in fact, it is equal to 1 when $x_2 = x_3 = 0$).
- Case $(2 \leq x_1 \leq \frac{M}{2} + 1)$: note that in this case the first constraint forces either $x_2$ or $x_3$ to be at least one. Thus $z \leq \frac{M}{2} + 1 - \frac{M}{2} = 1$.
- Case $(k \frac{M}{2} + 2 \leq x_1 \leq (k + 1) \frac{M}{2} + 1$, for $k \geq 1$ integer): similar to the previous case. Now, since $x_1 \geq k \frac{M}{2} + 2$, the second constraint forces $x_3 \geq k$, this together with the first constraint forces $x_2 + x_3 \geq k + 1$. Then, $z \leq (k + 1) \frac{M}{2} + 1 - \frac{M}{2} - k \frac{M}{2} = 1$.


The proof of the second part of Theorem 3 is very similar to the proof of the second part of Theorem 2 and therefore we do not present it here.

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Proof of Proposition 4

Proof. The result for the case of packing polyhedron is shown in [11]. We prove the result for the case of covering polyhedron. Consider the LP relaxation:

\[
\begin{align*}
\max & \quad \sum_{j=1}^{n} c_j x_j \\
\text{s.t.} & \quad \sum_{j=1}^{n} a_{1j} x_j \geq b_1 \\
& \quad \sum_{j=1}^{n} a_{2j} x_j \geq b_2 \\
& \quad x_j \geq 0 \quad \forall j \in [n].
\end{align*}
\]

In the LP optimal solution \( x^* \), at most 2 variables are non-zero. If only one variable is positive, then it is easy to verify the result by rounding up this solution to produce a IP feasible solution. Therefore, without loss of generality, let \( x^*_1 > 0 \) and \( x^*_2 > 0 \). Let \( y^* \) be an optimal dual solution. By strong duality and complimentary slackness, we have:

\[
\begin{align*}
b_1 y^*_1 + b_2 y^*_2 &= c_1 x^*_1 + c_2 x^*_2 \tag{7} \\
A_{11} y^*_1 + A_{21} y^*_2 &= c_1 \tag{8} \\
A_{12} y^*_1 + A_{22} y^*_2 &= c_2. \tag{9}
\end{align*}
\]

We consider six cases:

1. \( x^*_1 \geq 1, x^*_2 \geq 1 \): Clearly \( ([x^*_1], [x^*_2], 0) \) is IP feasible. It is clear that \( \frac{c_1[x^*_1] + c_2[x^*_2]}{c_1 x^*_1 + c_2 x^*_2} \leq 2 \).

2. \( 0.4 \leq x^*_1 < 1, x^*_2 \geq 1 \): Again, \( ([x^*_1], [x^*_2], 0) \) is IP feasible.

\[
\frac{c_1[x^*_1] + c_2[x^*_2]}{c_1 x^*_1 + c_2 x^*_2} \leq \max \left\{ \frac{c_1}{c_1 x^*_1}, \frac{c_2}{c_2 x^*_2} \right\} \leq \max\{2.5, 2\} = 2.5
\]

3. \( x^*_1 \geq 1, 0.4 \leq x^*_2 < 1 \): Same as above.

4. \( x^*_1 < 0.4, x^*_2 \geq 1 \): Since \( A_{1i} \leq b \) for \( i \in [2] \), we have that \( A_{12} x^*_2 \geq b_1(1 - x^*_1) \) for \( i \in [2] \) and therefore \( (0, \left\lfloor \frac{x^*_2}{1 - x^*_1} \right\rfloor, 0) \) is IP feasible. Now note that

\[
\frac{c_2}{c_2 x^*_2} \leq \left\lfloor \frac{(5/3) \cdot x^*_2}{x^*_2} \right\rfloor < \begin{cases} 2 & 1 \leq x^*_2 \leq 6/5 \\ 2.5 & 6/5 < x^*_2 \leq 9/5 \\ 5/3 + \frac{1}{x^*_2} \leq 20/9 & x^*_2 \geq 9/5 \end{cases}
\]

5. \( x^*_1 \geq 1, x^*_2 < 0.4 \): Same as above.

6. \( x^*_1 < 1, x^*_2 < 1 \): In this case,

\[
\frac{c_1[x^*_1] + c_2[x^*_2]}{c_1 x^*_1 + c_2 x^*_2} = \frac{c_1}{c_1 x^*_1 + c_2 x^*_2} + \frac{c_2}{c_1 x^*_1 + c_2 x^*_2} \leq \frac{A_{11} y^*_1 + A_{21} y^*_2}{b_1 y^*_1 + b_2 y^*_2} + \frac{A_{12} y^*_1 + A_{22} y^*_2}{b_1 y^*_1 + b_2 y^*_2} \quad (\text{using } (7), (8), (9))
\]

\[
\leq 2,
\]

where the last inequality follows from the fact that \( A_{ij} \leq b_i \) for \( i \in [2], j \in [2] \).

\[\square\]