ROTUNDUS: TRIANGULATIONS, CHEBYSHEV POLYNOMIALS, AND PFAFFIANS

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Abstract. We introduce and study a cyclically invariant polynomial which is an analog of the classical tridiagonal determinant usually called the continuant. We prove that this polynomial can be calculated as the Pfaffian of a skew-symmetric matrix. We consider the corresponding Diophantine equation and prove an analog of a famous result due to Conway and Coxeter. We also observe that Chebyshev polynomials of the first kind arise as Pfaffians.

The tridiagonal determinant

\[ K_n(a_1, \ldots, a_n) := \det \begin{pmatrix} a_1 & 1 \\ 1 & a_2 & 1 \\ & \ddots & \ddots \\ & & 1 & a_{n-1} & 1 \\ & & & 1 & a_n \end{pmatrix} \]

is most often known as the continuant. It has a long and enchanting history. Let us mention a few of its many interesting properties.

a) The continuant was already known to Euler, although the notion of determinant was not in use in his time; see [5], Chapter 18. Indeed, continuants occur as both the numerator and the denominator of continued fractions:

\[ a_1 - \frac{1}{a_2 - \frac{1}{\ddots - \frac{1}{a_n}}} = \frac{K_n(a_1, \ldots, a_n)}{K_{n-1}(a_2, \ldots, a_n)}. \]

In the course of studying this formula Euler discovered a simple algorithm for calculating continuants, which we recall in Section 2. He went on to prove a series of identities involving them.

b) The matrix formula

\[ M_n := \begin{pmatrix} K_n(a_1, \ldots, a_n) & K_{n-1}(a_1, \ldots, a_{n-1}) \\ -K_{n-1}(a_2, \ldots, a_n) & -K_{n-2}(a_2, \ldots, a_{n-1}) \end{pmatrix} = \begin{pmatrix} a_1 & 1 \\ -1 & 0 \end{pmatrix} \cdots \begin{pmatrix} a_n & 1 \\ -1 & 0 \end{pmatrix} \]

puts continuants in the context of SL(2, \mathbb{R}), and even SL(2, \mathbb{Z}) when the \( a_i \) are integral.

c) Continuants are related to the spectral theory of difference equations. Indeed, they can be defined in terms of solutions of the linear difference equation

\[ V_{i-1} - a_i V_i + V_{i+1} = 0, \]

known as the discrete Sturm-Liouville, Hill, or Schrödinger equation: the initial conditions \((V_0, V_1) = (0, 1)\) give \(V_{n+1} = K_n(a_1, \ldots, a_n).\) If the sequence \((a_i)_{i \in \mathbb{Z}}\) is \(n\)-periodic, then the matrix \(M_n\) in (2) is the monodromy matrix of (3).
d) Continuants appeared in the work of Coxeter [3] as the values of frieze patterns (for a survey, see [7]). For \((a_i)\) n-periodic, Conway and Coxeter [2] considered the Diophantine system

\[
K_{n-2}(a_1, \ldots, a_{i+n-3}) = 1, \quad i \in \mathbb{Z}.
\]

(Of course, due to the periodicity there are only \(n\) distinct equations.) It can be shown that this system is equivalent to the condition that the monodromy matrix \(M_n\) of (3) is \(-\text{Id}\). Conway and Coxeter proved the beautiful theorem that every \textit{totally positive} \(n\)-periodic integer solution \((a_i)\) of this system corresponds to a triangulation of an \(n\)-gon. This implies in particular that such solutions are enumerated by the Catalan numbers. For details, see Section [4].

e) As discussed in [1], continuants have another property related to the Catalan numbers. Given any sequence \(a = (a_0, a_1, a_2, \ldots)\), there exists a unique sequence \(C = (C_0, C_1, C_2, \ldots)\) determined by the condition that the \textit{Hankel matrices}

\[
A_n := \begin{pmatrix}
C_0 & C_1 & \cdots & C_n \\
C_1 & C_2 & \cdots & C_{n+1} \\
\vdots & \vdots & \ddots & \vdots \\
C_n & C_{n+1} & \cdots & C_{2n}
\end{pmatrix}, \quad B_n := \begin{pmatrix}
C_1 & C_2 & \cdots & C_n \\
C_2 & C_3 & \cdots & C_{n+1} \\
\vdots & \vdots & \ddots & \vdots \\
C_n & C_{n+1} & \cdots & C_{2n-1}
\end{pmatrix}
\]

have determinants \(\det(A_n) = 1\) and \(\det(B_n) = K_{n+1}(a_0, \ldots, a_n)\). The sequence \(a = (1, 2, 2, \ldots)\) has \(K_{n+1}(1, 2, 2, \ldots, 2) = 1\) for all \(n > 0\) and determines the Catalan numbers.

Among all the wonderful properties of the continuant, there is one which might be considered a flaw: it is not invariant under cyclic permutations of its arguments. Indeed, the polynomials

\[K_n(a_1, \ldots, a_n), \quad K_n(a_n, a_1, \ldots, a_{n-1}), \quad \ldots, \quad K_n(a_2, \ldots, a_n, a_1)\]

are all different. At times this can be inconvenient. For instance, in considering the Conway-Coxeter system [4], one has to deal with \(n\) equations.

In this note, we introduce a cyclically invariant version of continuants.

\[K_n(a_1, \ldots, a_n) := K_n(a_1, \ldots, a_n) - K_{n-2}(a_2, \ldots, a_{n-1}).\]

\[1\] Conway and Coxeter called such a solution a quiddity.
At order 5 one has relation of $R$ with $K$ clearly the second term on the right side of (5) contains precisely all those terms in the modified algorithm. This is an immediate consequence of Euler’s algorithm, given in Section 2 below.

It turns out that the rotundus is the Pfaffian of a very simple skew-symmetric matrix of size 2

Proposition 1. $R_n$ is cyclically invariant: $R_n(a_1, \ldots, a_n) = R_n(a_n, a_1, \ldots, a_{n-1})$.

Proof. This is an immediate consequence of Euler’s algorithm, given in Section 2 below.

In light of this proposition, we suggest the Latin term rotundus as a name for $R_n$. We will show that several properties of the rotundus are, in fact, more sophisticated versions of analogous properties of the continuant $K_n$. For instance, in Section 3 we calculate $R_n$ as a Pfaffian. Speaking “philosophically”, the relation of $R_n$ and $K_n$ is similar to that of the Chebyshev polynomials of the first and second kinds: see Section 5.

2. The cyclic Euler algorithm

Euler’s algorithm for calculating the continuant $K_n(a_1, \ldots, a_n)$ is as follows: start with the full product $a_1 \ldots a_n$ and successively replace all the adjacent pairs $a_i a_{i+1}$ by $-1$ in all possible ways. For example,

$$K_3(a_1, a_2, a_3) = a_1 a_2 a_3 - a_1 a_3 a_2 - a_2 a_3 a_1 = a_1 a_2 a_3 - a_1 - a_3,$$

$$K_4(a_1, a_2, a_3, a_4) = a_1 a_2 a_3 a_4 - a_1 a_2 a_4 a_3 - a_1 a_3 a_4 a_2 + a_1 a_2 a_3 a_4 + a_1 a_3 a_4 a_2 + a_1 a_4 a_3 a_2 = a_1 a_2 a_3 a_4 - a_1 - a_3 - a_4 + 1.$$

It follows directly from (5) that the rotundus is calculated by nearly the same rule. The only difference is that the variables are ordered cyclically, so the pair $a_n a_1$ is considered adjacent. For example,

$$R_3(a_1, a_2, a_3) = a_1 a_2 a_3 - a_1 a_3 a_2 - a_2 a_3 a_1 = a_1 a_2 a_3 - a_1 - a_3,$$

$$R_4(a_1, a_2, a_3, a_4) = a_1 a_2 a_3 a_4 - a_1 a_2 a_4 a_3 - a_1 a_3 a_4 a_2 + a_1 a_2 a_3 a_4 + a_1 a_3 a_4 a_2 + a_1 a_4 a_3 a_2 = a_1 a_2 a_3 a_4 - a_1 - a_3 - a_4 + 2.$$

At order 5 one has

$$R_5(a_1, a_2, a_3, a_4, a_5) = a_1 a_2 a_3 a_4 a_5 - a_1 a_3 a_4 a_5 - a_1 a_2 a_3 a_4 a_5 - a_1 a_2 a_3 a_4 a_5 + a_1 a_2 a_3 a_4 a_5.$$

Clearly the second term on the right side of (5) contains precisely all those terms in the modified algorithm with $a_n a_1$ removed. We refer to this procedure as the “cyclic Euler algorithm”.

3. Pfaffians

Recall that the determinant of a skew-symmetric matrix $\Omega$ is the square of a certain polynomial in its entries, known as the Pfaffian:

$$\det(\Omega) =: \text{pf}(\Omega)^2.$$ 

It turns out that the rotundus is the Pfaffian of a very simple skew-symmetric matrix of size $2n \times 2n$:  

$$\begin{bmatrix}
-1 & 1 & 0 & \cdots & 0 \\
1 & -1 & 1 & \cdots & 0 \\
0 & 1 & -1 & \cdots & 0 \\
\vdots & \vdots & \vdots & \ddots & \vdots \\
0 & 0 & 0 & \cdots & -1
\end{bmatrix}.$$
Theorem 1. One has

\[
\begin{vmatrix}
1 & a_1 & 1 & & & \\
& 1 & a_2 & 1 & & \\
& & \ddots & \ddots & \ddots & \\
& & & 1 & a_n & \\
-1 & -a_1 & -1 & & & \\
& -1 & \ddots & \ddots & & \\
& & & -1 & & \\
& & & & -1 & -a_n & -1
\end{vmatrix} = R_n(a_1, \ldots, a_n)^2.
\]

This formula may be understood as an analog of (1). It is entertaining to prove the cyclic symmetry of the determinant directly by conjugating by the appropriate permutation matrices.

Example. One can easily check directly that

\[
\begin{vmatrix}
0 & 0 & 1 & a_1 & 1 & 0 \\
0 & 0 & 0 & 1 & a_2 & 1 \\
-1 & 0 & 0 & 0 & 1 & a_3 \\
-a_1 & -1 & 0 & 0 & 0 & 1 \\
-1 & -a_2 & -1 & 0 & 0 & 0 \\
0 & -1 & -a_3 & -1 & 0 & 0
\end{vmatrix} = a_1a_2a_3 - a_1 - a_2 - a_3.
\]

Remark. Surprisingly, symmetric matrices of the same form are also related to the rotundus:

\[
\begin{vmatrix}
1 & a_1 & 1 & & & \\
& 1 & a_2 & 1 & & \\
& & \ddots & \ddots & \ddots & \\
& & & 1 & a_n & \\
a_1 & 1 & & & & \\
& \ddots & \ddots & & & \\
& & & \ddots & & \\
& & & & 1 & \\
& & & & & 1
\end{vmatrix} = (-1)^n(R_n(a_1, \ldots, a_n)^2 - 4).
\]

Proof of Theorem 1. Regard the matrix in (6) as a $2 \times 2$ block matrix with $n \times n$ entries. As such, it has the form

\[
\begin{pmatrix}
E & C \\
-C & E
\end{pmatrix},
\]

where $C$ is the tridiagonal continuant matrix in (1), and $E$ is the skew-symmetric matrix with a 1 in the upper right corner, a $-1$ in the lower left corner, and all other entries zero.

It clarifies the situation to prove a more general result. Given any $n \times n$ matrix $A$, let us write $A_{\text{mid}}$ for the $(n-2) \times (n-2)$ matrix obtained from $A$ by removing its “perimeter”: its first and last rows and
columns. We will prove that for any scalars $x$ and $y$,
\begin{equation}
\det \begin{pmatrix} xE & A \\ -A & yE \end{pmatrix} = (\det(A) - xy \det(A_{\text{mid}}))^2.
\end{equation}

Taking $x$ and $y$ to be 1 and $A$ to be $C$, then gives the theorem.

Write $B$ for the matrix in (7). Clearly $\det(B)$ is quadratic in both $x$ and $y$, and it is a perfect square because $B$ is skew-symmetric. Consequently it must take the form
\begin{equation}
\det(B) = (\Delta_0 + x \Delta_x + y \Delta_y + xy \Delta_{xy})^2
\end{equation}
for some polynomials $\Delta_0$, $\Delta_x$, $\Delta_y$, and $\Delta_{xy}$ in the entries of $A$, which are determined up to a single overall choice of sign. Observe that
\begin{equation}
\det(B) = \det \begin{pmatrix} 0 & -\text{Id} \\ \text{Id} & 0 \end{pmatrix} \begin{pmatrix} xE & A \\ -A & yE \end{pmatrix} = \det \begin{pmatrix} A & -yE \\ xE & A \end{pmatrix}.
\end{equation}
Therefore if either $x$ or $y$ is zero, $\det(B) = \det(A)^2$. Hence $\Delta_x = \Delta_y = 0$, and we may take $\Delta_0 = \det(A)$.

Now use the following schematic diagram of $B$ to envision the coefficient of $x^2 y^2$ in its determinant:
\begin{equation}
B = \begin{pmatrix} \begin{pmatrix} \begin{pmatrix} x & A \\ y & \end{pmatrix} \end{pmatrix} \\ \begin{pmatrix} -x \\ -A \end{pmatrix} \\ \begin{pmatrix} y & \end{pmatrix} \end{pmatrix}
\end{equation}
It becomes clear that this coefficient is $\det(A_{\text{mid}})^2$, and so $\Delta_{xy}$ must be one of $\pm \det(A_{\text{mid}})$. The sign is negative, because $B$ is singular when $x = y = 1$ and $B = \text{Id}$: its first and last columns sum to 0.

**Comment.** Theorem 1 arises naturally in symplectic geometry. Consider a “projective $2n$-gon” in $(2n - 2)$-dimensional symplectic space, i.e., a cyclically ordered configuration of $2n$ lines, satisfying the strong “Lagrangian condition” that every set of $n - 1$ consecutive lines generates a Lagrangian subspace. It turns out that the moduli space of such configurations is precisely the hypersurface where the rotundus vanishes. The matrix in (6) enters the picture as the Gram matrix of the symplectic form evaluated on a certain normalized choice of points on the lines of the configuration.

These geometric considerations are more technical and will be treated elsewhere. In this note we restrict ourselves to combinatorial properties of the rotundus which seem interesting and deserving of further study.

4. **Centrally symmetric triangulations**

Here we investigate the Diophantine equation
\begin{equation}
R_n(a_1, \ldots, a_n) = 0.
\end{equation}
We will show that it is an analog of the Coxeter-Conway system [1]. However, thanks to its cyclic invariance, one does not need a system: a single equation contains complete information.

Let us first explain the classical Conway-Coxeter theorem [2]. An $n$-periodic solution $(a_i)_{i \in \mathbb{Z}}$ of the system (1) is called *totally positive* if
\begin{equation}
K_{j-i+1}(a_i, a_{i+1}, \ldots, a_j) > 0 \text{ for } j-i < n-3.
\end{equation}
Total positivity is one of the central notions of algebraic combinatorics. The theorem is a beautiful combinatorial interpretation of the totally positive solutions of (1). Given a triangulation of a (regular) $n$-gon, let $a_i$ be the number of triangles adjacent to the $i^{th}$ vertex. This yields an $n$-periodic sequence of positive integers $(a_i)_{i \in \mathbb{Z}}$. The content of the theorem is that these sequences are solutions of (1), they are totally positive, and every totally positive solution of (1) arises in this way.
Theorem. [2] Totally positive integer solutions of (4) correspond to triangulations of the \( n \)-gon.

For different proofs of this theorem, see [6, 8].

Example. Up to cyclic permutation, the only totally positive 5-periodic integer solution of the system

\[
\begin{pmatrix}
 a_i & 1 & 0 \\
 1 & a_{i+1} & 1 \\
 0 & 1 & a_{i+2}
\end{pmatrix} = 1, \quad 1 \leq i \leq 5,
\]

is given by \((a_1, a_2, a_3, a_4, a_5) = (1, 3, 1, 2, 2)\). It corresponds to the only triangulation of the pentagon:

![Pentagon Triangulation](image)

The label of each vertex is the number of triangles adjacent to it.

We now turn to the rotundus system (8). As usual, extend \((a_1, \ldots, a_n)\) to an \(n\)-periodic sequence \((a_i)_{i \in \mathbb{Z}}\). By analogy with (4), solutions of (8) are said to be totally positive if they satisfy (9) for all \(j - i \leq n\). Such solutions are described by the following theorem.

**Theorem 2.** Every totally positive integer solution of (8) corresponds to a centrally symmetric triangulation of a \(2n\)-gon.

Example. Consider the following centrally symmetric triangulations of the decagon:

![Decagon Triangulations](image)

Totally positive solutions from triangulations.

At \(n = 5\), one easily checks that the values

\((5, 2, 2, 2, 1), \quad (4, 3, 1, 3, 1), \quad (4, 2, 1, 4, 1),\)

of \((a_1, a_2, a_3, a_4, a_5)\) obtained from these triangulations are indeed totally positive solutions of (8).

**Proof of Theorem 2.** We deduce the result directly from the Conway-Coxeter theorem. Recall that (8) is the zero-trace condition for the matrix \(M_n\) in (2). In light of the obvious fact that this matrix has determinant 1, (8) is equivalent to the condition that \(M_n\) have eigenvalues \(\pm i\), or in other words, \(M_n^2 = -\text{Id}\).

This implies that the “double” \(2n\)-tuple \((a_1, \ldots, a_n, a_1, \ldots, a_n)\) is a solution of the Conway-Coxeter system of order \(2n - 2\). By the Conway-Coxeter theorem, this \(2n\)-tuple must be given by a triangulation of a \(2n\)-gon. This triangulation is clearly centrally symmetric.

To prove the converse, one needs the fact that (10) implies

\[K_{n-1}(a_i, \ldots, a_{i+n-2}) = 0, \quad K_n(a_i, \ldots, a_{i+n-1}) = -1.\]

Indeed, this holds because the matrices \(M_{n-1}\) and \(M_n\) have determinant 1. Given a centrally symmetric triangulation of a \(2n\)-gon, i.e., a totally positive solution of the Conway-Coxeter system of order \(2n - 2\), we have shown that \(M_{2n} = M_n^2 = -\text{Id}\). Hence the result. \(\square\)
Chebyshev polynomials of the second kind: series are usually denoted by $T_n$ of polynomials, called the Chebyshev polynomials of the first and second kinds, respectively. These two satisfying the recurrence $P_{n+1}(x) = 2xP_n(x) - P_{n-1}(x)$. The two sets of “initial conditions” $P_0(x) = 1$, $P_1(x) = x$ and $P_0(x) = 1$, $P_1(x) = 2x$ lead to two series of polynomials, called the Chebyshev polynomials of the first and second kinds, respectively. These two series are usually denoted by $T_n(x)$ and $U_n(x)$. They start as follows:

- $T_0(x) = 1$, $U_0(x) = 1$,
- $T_1(x) = x$, $U_1(x) = 2x$,
- $T_2(x) = 2x^2 - 1$, $U_2(x) = 4x^2 - 1$,
- $T_3(x) = 4x^3 - 3x$, $U_3(x) = 8x^3 - 4x$,
- $T_4(x) = 8x^4 - 8x^2 + 1$, $U_4(x) = 16x^4 - 12x^2 + 1$,

... 

It is well known that substituting $a_1 = a_2 = \cdots = a_n = 2x$ into the continuant $K_n$ gives precisely the Chebyshev polynomials of the second kind:

$$U_n\left(\frac{x}{2}\right) = K_n(x, \ldots, x).$$

As may be seen for example in [1], this determinantal expression is useful in combinatorics. A similar expression for the Chebyshev polynomials of the first kind appears to be missing.

Applying our results, we obtain the “Pfaffian formula”

$$T_n\left(\frac{x}{2}\right) = \frac{1}{2} R_n(x, \ldots, x) = \frac{1}{2} \text{pf} \begin{pmatrix} 1 & x & 1 \\ 1 & x & 1 \\ \vdots & \vdots & \vdots \\ -1 & -1 & 1 \\ -x & -1 & 1 \\ -1 & \ddots & \ddots \\ \vdots & \ddots & \ddots \\ -1 & \ddots & \ddots \\ -1 & -1 & -1 \end{pmatrix},$$

the matrix being of size $2n \times 2n$. This is an immediate corollary of Theorem [1] together with the well-known (and obvious) relation between the polynomials of first and second kind:

$$T_n(x) = \frac{1}{2} (U_n(x) - U_{n-2}(x)).$$

We did not find (10) in the literature.
Applying (2) and (5), we have also the “trace formula”

\[ T_n \left( \frac{x}{2} \right) = \frac{1}{2} \text{tr} \left( \begin{pmatrix} x & 1 \\ -1 & 0 \end{pmatrix} \begin{pmatrix} x & 1 \\ -1 & 0 \end{pmatrix} \cdots \begin{pmatrix} x & 1 \\ -1 & 0 \end{pmatrix} \right). \]

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