The Schrödinger equation with spatial white noise potential

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Abstract

We consider the linear and nonlinear Schrödinger equation with a spatial white noise as a potential over the two dimensional torus. We prove existence and uniqueness of solutions to an initial value problem for suitable initial data. Our construction is based on a change of unknown originally used in [13] and conserved quantities.

Keywords: nonlinear Schrödinger equation; spatial white noise; renormalization.

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1 Introduction

In this work we study a linear or nonlinear Schrödinger equation on a periodic domain with a random potential given by a spatial white noise in dimension 2. This equation is important for various purposes. In the linear case, it is used to study Anderson localisation. It is a complex version of the famous PAM model. In the nonlinear case, it describes the evolution of nonlinear dispersive waves in a totally disorder medium (see for instance [9], [12] and the references therein).

If $u$ denotes the unknown, the equation is given by:

$$i\frac{du}{dt} = \Delta u + \lambda |u|^2 u + u\xi, \quad x \in \mathbb{T}^2, \quad t \geq 0,$$

where $\mathbb{T}^2$ denotes the two dimensional torus, identified with $[0, 2\pi]^2$, and $\xi$ is a real-valued spatial white noise. Of course, $\lambda = 0$ for the linear equation. A positive $\lambda$ corresponds to the focusing case and $\lambda < 0$ to the defocusing case. For simplicity, we take $\lambda = \pm 1$ in the nonlinear case. The qualitative properties of the solutions are completely different in these two cases.

We are here interested in the question of existence and uniqueness of solutions. This is a preliminary but important step before studying other phenomena, such as solitary waves.

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waves, blow up phenomena or Anderson localisation. The main difficulty is due to the presence of the rough potential. Recall that in dimension 2, a white noise has a negative regularity which is strictly less than \(-1\). In the parabolic case (i.e. replace \(i\frac{du}{dt}\) by \(\frac{Du}{dt}\)) renormalized solutions were recently constructed in [13]. However, their argument relies strongly on the strong regularising properties of the heat semigroup which are not available for the Schrödinger equation. Some smoothing properties for the Schrödinger equation are known when it is set on the plane. For instance in [6], section 2.5, it is shown that localized initial data yield smooth solutions. Further results are mentioned in Remark 2.7.8 of the same book. See also [8, 14, 16, 18] for further results as well as [4, 17] for deterministic nonlinear smoothing in the euclidean setting. In the periodic case, considered here however, similar linear smoothing results do not hold. Some deterministic nonlinear smoothing hold for the cubic NLS on the one dimensional torus (see [10, 11, 15]), but there is no such deterministic smoothing for the quintic or higher, and it is believed not to hold in dimensions bigger than 2 regardless of the nonlinearity.

Instead of using regularising estimates for the Schrödinger semigroup we rely on the Hamiltonian structure of the equation and its conserved quantities. We use the same transformation introduced in [13]. On the level of this transformed equation, the conservation of mass and energy gives enough control to construct solutions taking values in almost \(H^2(T^2)\), the standard Sobolev space of functions with derivatives up to order 2 in \(L^2(T^2)\). Inverting the transformation this yields solutions in almost \(H^1(T^2)\). This is rather surprising since the regularity is comparable to what is obtained in the parabolic case, when strong smoothing properties are available. However, we have to assume more structure on the initial datum than is needed in the parabolic case: On the level of the transformed equation the initial datum has to have \(H^2(T^2)\) regularity, which translates to the assumption that the initial datum for the original equation is the product of an \(H^2(T^2)\) function and a explicit function of regularity almost \(H^1(T^2)\) which depends on the specific realisation of the noise \(\xi\). This may be surprising at a first glance but, remembering that the domain of the linear operator appearing in the equation is random ((1)), this is in fact natural.

As in the parabolic case, a renormalization is necessary and at the level of the original equation, the renormalized equation rewrites formally:

\[
i\frac{du}{dt} = \Delta u + \lambda |u|^2 u + u(\xi - \infty), \ x \in T^2, \ t \geq 0.
\]

The transformation \(u \to e^{i\xi t} u\) transforms the original equation into the renormalized one. Therefore, the renormalization amounts to renormalize only the phase. A similar remark was made in [3] in a related but different context.

We first consider the linear equation, \(\lambda = 0\). In this way the ideas can be explained in a simpler setting. We use a transformation introduced in [13] in the parabolic case, it transforms the equation into a less singular one. Conservation of the \(L^2(T^2)\) and \(H^1(T^2)\) norm imply some bounds in these spaces, but these are not yet sufficient to construct a solution. We then use conservation of the \(L^2(T^2)\) norm of the time derivative to get bounds in \(H^2\) on the transformed equation with a smoothed noise. The bound explodes when the smoothing disappears but thanks to an idea reminiscent of interpolation theory we show that this implies uniform \(H^{1/2}, \gamma < 2\), bounds on the smoothed solutions. This bound is sufficient to prove that they converge to a solution of our transformed equation. Going back to the original equation yields a solution in \(H^1\).

For \(\lambda < 0\), we obtain global solutions for any initial data satisfying some smoothness assumptions. For \(\lambda > 0\), as in the deterministic case, we need a smallness assumption on the initial data. The ideas are similar but the estimates are more delicate.

We could of course consider the equation with a more general nonlinearity: \(|u|^{2\sigma} u\) with \(\sigma \leq 1\). For \(\sigma < 1\), no restriction on the size of the initial data is required for \(\lambda > 0\).
Another easy generalization is to consider a general bounded domain and Dirichlet boundary conditions, as long as they are sufficiently smooth and the properties of the Green function of the Laplace operator are sufficiently good so that Lemma 2.1 below holds.

The study of the linear equation is closely related to the understanding of the Schrödinger operator with white noise potential. This is the subject of a recent very interesting article by Allez and Chouk ([1]) where the paracontrolled calculus is used to study the domain and spectrum of this operator. It is not clear how this can be used for the nonlinear equation.

Notation

We use the classical $L^p = L^p(T^2)$ spaces for $p \in [1, \infty]$, as well as the $L^2$ based Sobolev spaces $H^s = H^s(T^2)$ for $s \in \mathbb{R}$ and the Besov spaces $B^s_{p,q} = B^s_{p,q}(T^2)$, for $s \in \mathbb{R}$, $p,q \in [1,\infty]$. These are defined in terms of Fourier series and Littlewood-Paley theory (see [2]). Recall that for $s > \frac{2}{p}$ the space $B^s_{p,q}(T^2)$ embeds into $L^\infty(T^2)$.

Throughout the article, $c$ denotes a constant which may change from one line to the next. Also, we use a small parameter $0 < \varepsilon < e^{-1}$ and $K_\varepsilon$ is a random constant which can also change but such that $E(K_\varepsilon)$ is uniformly bounded in $\varepsilon$ for all $p$. Similarly, for $0 < \varepsilon_1, \varepsilon_2 < e^{-1}$, the random constant $K_{\varepsilon_1, \varepsilon_2}$ may depend on $\varepsilon_1, \varepsilon_2$ but $E(K_{\varepsilon_1, \varepsilon_2})$ is uniformly bounded in $\varepsilon_1, \varepsilon_2$ for all $p$.

2 Preliminaries

We consider the following nonlinear Schrödinger equation in dimension 2 on the torus, that is periodic boundary conditions are assumed, for the complex-valued unknown $u = u(x,t)$:

$$
\frac{idu}{dt} = \Delta u + \lambda |u|^2 u + u\xi, \; x \in T^2, \; t \geq 0.
$$

(2.1)

It is supplemented with initial data

$$
u(x,0) = u_0(x), \; x \in T^2.
$$

We need to choose the initial data of special form which depends on the realisation of the noise $\xi$. This will be made precise below. In the focusing case $\lambda > 0$ we need an extra assumption on the size of $\|u_0\|_{L^2}$ which has be small enough (see (4.3) below).

The potential $\xi$ is random and is a real valued spatial white noise on $T^2$. For simplicity, we assume that it has a zero spatial average. The general case could be recovered by adding an additional Gaussian random potential which is constant in space. This would not change the analysis below.

Formally equation (2.1) has two invariant quantities. Given a solution $u$ of (2.1), the mass:

$$
N(u(t)) = \int_{T^2} |u(x, t)|^2 dx
$$

is constant in time as well as the energy:

$$
H(u(t)) = \int_{T^2} \frac{1}{2} |\nabla u(x, t)|^2 - \frac{\lambda}{4} |u(x, t)|^4 - \frac{1}{2} \xi(x)|u(x, t)|^2 dx.
$$

This is formal because the noise $\xi$ is very rough. In dimension 1, the noise has regularity $-1/2^-$ and belongs to $B^\alpha_{\infty, \infty}$ for any $\alpha < -1/2$, therefore the product $\xi |u|^2$ can be defined rigorously for $u \in H^1$ and this provides a bound in $H^1$. Existence and uniqueness through regularization of the noise and a compactness argument can then be obtained.
In dimension 2, the noise lives in any space with regularity $-1^-$, that is any regularity strictly less than $-1$, and the solution is not expected to be sufficiently smooth to compensate this. In fact, the product is almost well defined for $u \in H^1$ and we are in a situation similar to the two dimensional nonlinear heat equation with spatial white noise (i.e. the two dimensional continuous parabolic Anderson model). We expect that a renormalization is necessary.

Inspired by [13], we introduce:

$$ Y = \Delta^{-1} \xi $$

(note that this is well defined since we consider a zero average noise, we choose $Y$ also with a zero average) and $v = u e^Y$. Then the equation for $v$ reads

$$ \frac{d}{dt} v = \Delta v - 2 \nabla v \cdot \nabla Y + v |\nabla Y|^2 + \lambda v |v|^2 v e^{-2Y}. \quad (2.2) $$

The random field $Y$ has regularity $1^-$ and $\nabla Y$ is of regularity $0^-$. Thus this transformation has lowered the roughness of the most irregular term on the right hand side. At this point it is easier to see why we need a renormalization: the term $|\nabla Y|^2$ is not well defined since $\nabla Y$ is not a function. However, the roughness is mild here and it has been known for long that up to renormalization by a log divergent constant this square term can be defined in the second order Wiener chaos based on $\xi$.

Let us be more precise. Let $\rho_\varepsilon = \varepsilon^{-2} \rho(\varepsilon \cdot)$ be a compactly supported smooth mollifier and consider the smooth noise $\xi_\varepsilon = \rho_\varepsilon * \xi$. We denote by $Y_\varepsilon = \Delta^{-1} \xi_\varepsilon$. Then it is proved in [13] that for every $\kappa > 0$, $\xi$ belongs almost surely to $B^{1-\kappa}_{-\infty, \infty}$ and, as $\varepsilon \to 0$, $\xi_\varepsilon$ converges in probability to $\xi$ in $B^{1-\kappa}_{-\infty, \infty}$.

Also, denoting by

$$ C_\varepsilon = E(\|\nabla Y_\varepsilon\|^2) $$

the quantity $\|\nabla Y_\varepsilon\|^2 := \|\nabla Y_\varepsilon\|^2 - C_\varepsilon$ converges in $L^p(\Omega; B^{\kappa}_{-\infty, \infty})$ for any $p \geq 1$, $\kappa > 0$ to a random variable $\|\nabla Y\|^2$: in the second Wiener chaos associated to $\xi$. It is easy to see that $C_\varepsilon$ goes to $\infty$ as $|\ln \varepsilon|$ as $\varepsilon \to \infty$:

$$ E(\|\nabla Y_\varepsilon\|^2) \sim K_0 |\ln \varepsilon| $$

for some $K_0 > 0$. By stationarity this quantity does not depend on $x \in T^2$.

This discussion is summarised in the following Lemma whose proof can be found in [13, Lemma 1.1 and Proposition 1.3] in the more difficult case of the space variable in $\mathbb{R}^2$.

**Lemma 2.1.** For $1 \geq \kappa' > \kappa'' > 0$ and any $p \geq 1$, there exist a constant $c$ independent of $\varepsilon$ such that:

$$ \left[ E \left( \| Y_\varepsilon - Y \|_{B^{\kappa'}_{-\infty, \infty}}^p \right) \right]^{\frac{1}{p}} \leq c \varepsilon^{\kappa'' - \frac{2}{p}} $$

and

$$ \left[ E \left( \| \nabla Y_\varepsilon \|^2 : \| \nabla Y \|^2 : \| \nabla Y \|^2 \|_{B^{\kappa''}_{-\infty, \infty}}^p \right) \right]^{\frac{1}{p}} \leq c \varepsilon^{\kappa'' - \frac{2}{p}}. $$

**Remark 2.2.** Using the monotonicity of stochastic $L^p$ norms in $p$, one can drop the exponent $-\frac{2}{p}$ in the right hand side. We state the result in this way because this is the bound that one actually proves. Below, we use this bound with $\kappa'' - \frac{2}{p} = \frac{s'}{2}$.

Note that for $s < \tilde{s}$, $p, r \geq 1$, we have $B^s_{-\infty, \infty} \subset B^s_{p, r}$. Thus, bounds in the latter Besov spaces follow.
Instead of solving equation (2.2) for \(v_\varepsilon\), we consider:

\[
i \frac{dv_\varepsilon}{dt} = \Delta v_\varepsilon - 2\nabla v_\varepsilon \cdot \nabla Y_\varepsilon + v_\varepsilon : |\nabla Y_\varepsilon|^2 + \lambda |v_\varepsilon|^2 v_\varepsilon e^{-2Y_\varepsilon} \tag{2.3}
\]

and setting \(u_\varepsilon = v_\varepsilon e^{-Y_\varepsilon}:\)

\[
i \frac{du_\varepsilon}{dt} = \Delta u_\varepsilon + \lambda |u_\varepsilon|^2 u_\varepsilon + u_\varepsilon(\xi - C_\varepsilon), \quad x \in \mathbb{T}^2, \quad t \geq 0. \tag{2.4}
\]

Since \(Y_\varepsilon\) is smooth, it is classical to prove that these equations have a unique global solution in \(C([0, T]; H^k)\) for any \(T > 0\) for an initial data in \(H^k, \ k = 1, 2\), provided the \(L^2\) norm is small for \(\lambda > 0\) (see for instance [6], Section 3.6). More details are given in Section 4.

The mass and energy are transformed into the two following quantities which are invariant under the dynamics for \(v_\varepsilon:\)

\[
\tilde{N}_\varepsilon(v_\varepsilon(t)) = \int_{\mathbb{T}^2} |v_\varepsilon(x, t)|^2 e^{-2Y_\varepsilon(x)} dx
\]

and

\[
\tilde{H}_\varepsilon(v_\varepsilon(t)) = \int_{\mathbb{T}^2} \left( \frac{1}{2} |\nabla v_\varepsilon(x, t)|^2 + \frac{1}{2} |v_\varepsilon|^2 \right) - \frac{\lambda}{4} |v_\varepsilon(x, t)|^4 e^{-2Y_\varepsilon(x)} e^{-2Y_\varepsilon(x)} dx.
\]

Since the most irregular term: \(|\nabla Y_\varepsilon|^2\) here is not as rough as \(\xi\), this transformed energy is a much better quantity than the original one. It is possible to give a meaning to it for \(\varepsilon = 0\) and use it to get bounds in \(H^1\).

Below, we use the following simple results.

**Lemma 2.3.** For any \(\kappa \in (0, 1)\) and any \(p \geq 1\), there exists a constant independent on \(\varepsilon\) such that:

\[
\left[ \mathbb{E} \left( \|e^{-2Y_\varepsilon} - e^{-2Y}\|_{B^{1-\kappa}_{\infty, \infty}}^p \right) \right]^{\frac{1}{p}} \leq c \varepsilon^{\frac{2}{5}}.
\]

**Proof.** Since \(B^{1-\kappa}_{\infty, \infty}\) is equal to the Hölder space \(C^{1-\kappa}(\mathbb{T}^2)\) we have:

\[
\|e^{-2Y_\varepsilon} - e^{-2Y}\|_{B^{1-\kappa}_{\infty, \infty}} = \|e^{-2Y} (e^{-2(Y_\varepsilon - Y)} - 1)\|_{B^{1-\kappa}_{\infty, \infty}} \leq \|e^{-2Y}\|_{B^{1-\kappa}_{\infty, \infty}} \|e^{-2(Y_\varepsilon - Y)} - 1\|_{B^{1-\kappa}_{\infty, \infty}}.
\]

Then we write:

\[
\|e^{-2Y}\|_{B^{1-\kappa}_{\infty, \infty}} \leq 2 \|e^{-2Y}\|_{L^\infty} \|Y\|_{B^{1-\kappa}_{\infty, \infty}} + \|e^{-2Y}\|_{L^\infty},
\]

\[
\|e^{-2(Y_\varepsilon - Y)} - 1\|_{B^{1-\kappa}_{\infty, \infty}} \leq 2 \|e^{-2Y}\|_{L^\infty} \|e^{-2Y}\|_{L^\infty} \|Y_\varepsilon - Y\|_{B^{1-\kappa}_{\infty, \infty}}.
\]

The result follows by Hölder inequality, Lemma 2.1 (in the form of Remark 2.2 with \(\kappa'' = \kappa\)) and Gaussianity to bound exponential moments of \(Y\) and \(Y_\varepsilon\).

**Lemma 2.4.** There exists a constant \(c\) independent of \(\varepsilon\) such that:

\[
\mathbb{E} (\|\nabla Y_\varepsilon\|_{L^4}^4) \leq c |\ln \varepsilon|^2
\]

and

\[
\mathbb{E} (\|\nabla Y_\varepsilon\|_{L^2}^2 : \|\Delta\varepsilon\|) \leq c(|\ln \varepsilon|)^4.
\]

**Proof.** It suffices to write:

\[
\mathbb{E} \left( \int_{\mathbb{T}^2} |\nabla Y_\varepsilon(x)|^4 dx \right) = \int_{\mathbb{T}^2} \mathbb{E} \left( |\nabla Y_\varepsilon(x)|^4 \right) dx = 12\pi^2 C_2.
\]

Similarly:

\[
\mathbb{E} \left( \int_{\mathbb{T}^2} |\nabla Y_\varepsilon(x)|^2 : |\Delta\varepsilon|^4 dx \right) = \mathbb{E} \left( \int_{\mathbb{T}^2} (|\nabla Y_\varepsilon(x)|^2 - C_2)^4 dx \right) = 51\pi C_2^4.
\]
3 The linear case

In this section, we start with the linear case: \( \lambda = 0 \). Then the equation for \( \psi \) reads

\[
i \frac{d \psi}{dt} = \Delta \psi - 2\nabla \psi \cdot \nabla \epsilon + \psi : |\nabla \epsilon|^2.
\] (3.1)

There exists a unique solution in \( C([0,T]; H^2) \) if \( \psi(0) \in H^2 \). Indeed, for \( \epsilon > 0 \), \( Y_\epsilon \) is smooth so that \( u_{\epsilon,0} = v_0 e^{-Y_\epsilon} \) is also in \( H^2 \). Existence and uniqueness of a global solution in \( C([0,T]; H^2) \cap C^1([0,T]; L^2) \) of

\[
i \frac{d u_\epsilon}{dt} = \Delta u_\epsilon + \epsilon (\xi_\epsilon - C_\epsilon), \quad \epsilon \geq 0, \quad u_\epsilon(0) = u_{\epsilon,0},
\] (3.2)

is easy to prove, for instance by a fixed point argument on a mild form of the equation. Recall that \( (e^{i t \Delta}) \) is a strongly continuous group of isometries on any \( H^s \). This mild solution satisfies (3.1) as an inequality in \( L^2 \), see for instance [7], chapter 4. Setting \( v_\epsilon = u_{\epsilon,\epsilon} e^{Y_\epsilon} \) gives a solution in \( C([0,T]; H^2) \cap C^1([0,T]; L^2) \) to (3.1). Uniqueness of \( u_\epsilon \) implies uniqueness of \( v_\epsilon \). In fact, the same argument gives a unique solution in \( C([0,T]; H^{k+2}) \cap C^1([0,T]; H^k) \) if \( v_\epsilon(0) \in H^k \), \( k \in \mathbb{N} \).

We take the initial data

\[ v_\epsilon(0) = v_0 = u_0 e^Y \]

and assume below that it belongs to \( H^2 \). Note that this gives an initial data depending on \( \epsilon \) for \( u_\epsilon \) for (3.2), but we recover the good initial data at the limit \( \epsilon \to 0 \).

The mass and energy of a solution are now:

\[ N_\epsilon(v_\epsilon(t)) = \int_{\mathbb{T}^2} |v_\epsilon(x,t)|^2 e^{-2Y_\epsilon(x)} dx \]

and

\[ H_\epsilon(v_\epsilon(t)) = \int_{\mathbb{T}^2} \left( \frac{1}{2} |\nabla v_\epsilon(x,t)|^2 + \frac{1}{2} |v_\epsilon|^2 : |\nabla Y_\epsilon|^2 \right) e^{-2Y_\epsilon(x)} dx. \]

They are constant in time under the evolution (3.1). This follows from standard computations. Since the solution is in \( C([0,T]; H^2) \cap C^1([0,T]; L^2) \), these can be done rigorously. For instance, thanks to this property we have:

\[
\frac{d}{dt} \int_{\mathbb{T}^2} \frac{1}{2} |\nabla v_\epsilon(x,t)|^2 e^{-2Y_\epsilon(x)} dx = Re \int_{\mathbb{T}^2} \Delta v_\epsilon(x,t) \frac{d v_\epsilon}{dt} e^{-2Y_\epsilon(x)} dx.
\]

Since \( Y_\epsilon \) converges in \( B^{1,-\kappa}_{\infty,\infty} \) for any \( \kappa > 0 \) as \( \epsilon \) tends to zero, we see that the mass gives a uniform bound in \( L^2 \) on \( v_\epsilon \). More precisely:

\[
\|v_\epsilon(t)\|_{L^2}^2 \leq \|e^{2Y_\epsilon}\|_{L^\infty} \|e^{-2Y_\epsilon}\|_{L^\infty} \|v_0\|_{L^2}^2 = K_\epsilon \|v_0\|_{L^2}^2
\] (3.3)

with

\[
K_\epsilon = \|e^{2Y_\epsilon}\|_{L^\infty} \|e^{-2Y_\epsilon}\|_{L^\infty}. \]

(3.4)

The energy enables us to get a bound on the gradient.

**Proposition 3.1.** Let \( \kappa \in (0, 1/2) \), there exists a random constant \( K_\epsilon \) bounded in \( L^p(\Omega) \) with respect to \( \epsilon \) for any \( p \geq 1 \) such that if \( v_0 \in H^1 \):

\[
\int_{\mathbb{T}^2} |\nabla v_\epsilon(x,t)|^2 dx \leq K_\epsilon \left( H_\epsilon(v_0) + \|v_0\|_{L^2}^2 \right).
\]

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Proof. Since $B^{\infty}_{\infty,2}$ is in duality with $B^{1}_{1,2}$ we deduce by the standard multiplication rule in Besov spaces (see e.g. [2], Section 2.8.1)
\[
\left| \int_{T^2} |v_\varepsilon|^2 : |
abla Y_\varepsilon|^2 : dx \right| \leq \|v_\varepsilon\|_{B^{1}_{1,2}} \|\nabla Y_\varepsilon\|_{B^{\infty}_{\infty,2}} \leq K_\varepsilon \|v_\varepsilon\|_{B^{1}_{1,2}} \leq K_\varepsilon \|v_\varepsilon\|_{B^{2}_{2,2}}.
\]

Then we note that $\|v_\varepsilon\|_{B^{2}_{2,2}} = \|v_\varepsilon\|_{H^\kappa}$ so that by interpolation
\[
\left| \int_{T^2} |v_\varepsilon|^2 : |
abla Y_\varepsilon|^2 : dx \right| \leq K_\varepsilon \|v_\varepsilon\|_{2}^{2(1-\kappa)} \|v_\varepsilon\|_{H^\kappa}.
\]

It follows
\[
\int_{T^2} |\nabla v_\varepsilon(x,t)|^2 \, dx \leq K_\varepsilon H(v_\varepsilon(t)) + K_\varepsilon \|v_\varepsilon(t)\|_{L^2}^{2(1-\kappa)} \|v_\varepsilon(t)\|_{H^\kappa}^2
\]
\[
\leq K_\varepsilon \tilde{H}_\varepsilon(v_0) + K_\varepsilon \|v_\varepsilon(t)\|_{L^2}^2 + K_\varepsilon \|v_\varepsilon(t)\|_{L^2}^{2(1-\kappa)} \|\nabla v_\varepsilon\|_{L^2}^2
\]
\[
\leq K_\varepsilon \tilde{H}_\varepsilon(v_0) + K_\varepsilon \|v_0\|_{L^2}^2 + \frac{1}{2} \|\nabla v_\varepsilon\|_{L^2}^2
\]

and hence, by absorbing the last term in the left hand side,
\[
\int_{T^2} |\nabla v_\varepsilon(x,t)|^2 \, dx \leq K_\varepsilon \left( \tilde{H}_\varepsilon(v_0) + \|v_0\|_{L^2}^2 \right).
\]

Since $\tilde{H}_\varepsilon(v_0)$ is bounded for $v_0 \in H^1$, we obtain a (random) bound on $v_\varepsilon$ in $H^1$ using similar arguments as above.

**Corollary 3.2.** There exists a random constant $K_\varepsilon$ bounded in $L^p(\Omega)$ with respect to $\varepsilon$ for any $p \geq 1$ such for any $v_0 \in H^1$:
\[
\|v_\varepsilon\|_{H^1} \leq K_\varepsilon \|v_0\|_{H^1}, \quad t \geq 0.
\]

Unfortunately, this regularity is not sufficient to control the product $\nabla v_\varepsilon \cdot \nabla Y_\varepsilon$ on the right hand side of (3.1). The next observation is that, $w_\varepsilon = \frac{dw_\varepsilon}{dt}$ is formally a solution of:
\[
dt^\varepsilon \frac{dw_\varepsilon}{dt} = \Delta w_\varepsilon - 2\nabla w_\varepsilon \cdot \nabla Y_\varepsilon + w_\varepsilon : |\nabla Y_\varepsilon|^2 ; \quad (3.5)
\]

and since $w_\varepsilon$ satisfies the same equation as $v_\varepsilon$, it has the same invariant quantities. We use in particular the mass:
\[
\tilde{N}(w_\varepsilon(t)) = \tilde{N}(w_\varepsilon(0)).
\]

Hence:
\[
\|w_\varepsilon(t)\|_{L^2}^2 \leq K_\varepsilon \tilde{N}(w_\varepsilon(0)) \leq K_\varepsilon \|w_\varepsilon(0)\|_{L^2}^2. \quad (3.6)
\]

This formal argument can be justified as follows. We take a sequence $(v_{\varepsilon,\eta}(0))_{\eta > 0}$ in $H^4$ which converges to $v_\varepsilon(0)$ in $H^2$. Then, as noted above, the corresponding solution $v_{\varepsilon,\eta}$ of (3.2) lives in $C([0,T]; H^4) \cap C^1([0,T], H^2)$ and converges to $v_\varepsilon$ in $C([0,T]; H^2) \cap C^1([0,T], L^2)$. The argument above holds for $w_{\varepsilon,\eta} = \frac{dw_{\varepsilon,\eta}}{dt}$ and
\[
\|w_{\varepsilon,\eta}(t)\|_{L^2}^2 \leq K_\varepsilon \tilde{N}(w_{\varepsilon,\eta}(0)) \leq K_\varepsilon \|w_{\varepsilon,\eta}(0)\|_{L^2}^2.
\]

Letting $\eta \to 0$, we obtain that (3.6) is true under the assumption that $v_0 \in H^2$.

**Proposition 3.3.** There exists a random constant $K_\varepsilon$ bounded in $L^p(\Omega)$ with respect to $\varepsilon$ for any $p \geq 1$ such that if $v_0 \in H^2$:
\[
\|v_\varepsilon\|_{H^2} \leq c K_\varepsilon \left( \|v_0\|_{H^2} + \|v_0\|_{L^2} \ln \varepsilon \right)^2.
\]

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Proof. From (3.1), we have:

\[ w_\varepsilon(0) = -i(\Delta v_0 - 2\nabla v_0 \cdot \nabla Y_\varepsilon + v_0 : |\nabla Y_\varepsilon|^2) , \]

so that, thanks to the embedding \( H^{1/2} \subset L^4 \),

\[ \|w_\varepsilon(0)\|_{L^2} \leq c \left( \|v_0\|_{H^2} + \|v_0\|_{H^{3/2}} \|\nabla Y_\varepsilon\|_{L^4} + \|v_0\|_{H^{1/2}} : |\nabla Y_\varepsilon|^2 : L^4 \right) . \]

By interpolation we deduce:

\[
\|w_\varepsilon(t)\|_{L^2} \leq c \left( \|v_0\|_{H^2} + \|v_0\|_{L^4} \|\nabla Y_\varepsilon\|_{L^4} + \|v_0\|_{L^4} \|\nabla Y_\varepsilon \|_{L^2} + \|v_0\|_{L^2} \|: |\nabla Y_\varepsilon|^2 : L^2 \right) \\
\leq c \left( \|v_0\|_{H^2} + \|v_0\|_{L^2} \|\nabla Y_\varepsilon\|_{L^2} + \|v_0\|_{L^2} : |\nabla Y_\varepsilon|^2 : L^2 \right) \\
\leq c \left( \|v_0\|_{H^2} + K_\varepsilon \|v_0\|_{L^2} \|\nabla Y_\varepsilon\|_{L^2} \ln \varepsilon \right) ,
\]

where:

\[ K_\varepsilon = \|\nabla Y_\varepsilon\|_{L^2} \ln \varepsilon \|\nabla Y_\varepsilon\|_{L^2}^2 + \|: |\nabla Y_\varepsilon|^2 : L^2 \| \ln \varepsilon \|_{L^2}^2 . \]

By Lemma 2.4 and gaussianity, we know that the moments of this random variable are bounded with respect to \( \varepsilon \).

It follows

\[ \|w_\varepsilon(t)\|_{L^2} \leq K_\varepsilon \left( \|v_0\|_{H^2} + \|v_0\|_{L^2} \|\nabla Y_\varepsilon\|_{L^2} \ln \varepsilon \right) . \]

This in turn allows us to control \( \|v_\varepsilon\|_{H^2} \). Indeed, from (3.1),

\[ \|\Delta v_\varepsilon\|_{L^2} \leq \|w_\varepsilon(t)\|_{L^2} + 2\|\nabla v_\varepsilon \cdot \nabla Y_\varepsilon\|_{L^2} + \|v_\varepsilon : |\nabla Y_\varepsilon|^2 : L^2 \|
\]

and by similar arguments as above

\[ \|\Delta v_\varepsilon\|_{L^2} \leq \|w_\varepsilon(t)\|_{L^2} + \frac{1}{2} \|\Delta v_\varepsilon\|_{L^2} + cK_\varepsilon \|v_\varepsilon(t)\|_{L^2} \ln \varepsilon \|_{L^2}^2 
\]

and finally

\[ \|\Delta v_\varepsilon\|_{L^2} \leq K_\varepsilon \left( \|v_0\|_{H^2} + \|v_0\|_{L^2} \ln \varepsilon \right) . \]

The result follows thanks to (3.3).
Theorem 3.6. Let us first prove pathwise uniqueness. Since the equation is linear, this amounts
\[ \|v\|_{V^1} \leq c\|v_0\|_{H^1} \quad (\|v\|_{H^\kappa} + \|v_0\|_{H^\kappa}) \|e^{-2Y_1}\|_{B_{-\kappa}^x}. \]

Then, by Proposition 3.3 and interpolation:
\[ \|v\|_{H^{1+\kappa}} \leq c\|v_0\|_{H^2}^{(1+\kappa)/2}\|v_0\|_{L^2}^{(1-\kappa)/2} \leq K\|v_0\|_{H^2} + \|v_0\|_{L^2} |\ln\varepsilon_2|^2(1+\kappa)/2\|v_0\|_{L^2}^{(1-\kappa)/2} \]
and, by Corollary 3.2, for \( i = 1, 2 \)
\[ \|v\|_{H^\kappa} \leq \|v_0\|_{H^\kappa} \|v_0\|_{L^2}^{1-\kappa} \leq K\|v_0\|_{H^2} \|v_0\|_{L^2}^{1-\kappa}/2 \leq K\|v_0\|_{H^2} \|v_0\|_{L^2}^{1-\kappa}/2. \]

It follows
\[ \|v\|_{V^1} \leq K\|v_0\|_{H^2} \|v_0\|_{L^2}^{1-\kappa}/2 \leq K\|v_0\|_{H^2} \|v_0\|_{L^2}^{1-\kappa}/2. \]

The second term is bounded by the same quantity and we deduce:
\[ \frac{1}{2} \frac{d}{dt} \int_{T^2} |r(x,t)|^2 e^{-2Y_1(x)} dx \]
\[ \leq K\|e^{-2Y_1}\|_{B_{-\kappa}^x} \|v_0\|_{L^2}^{(1-\kappa)/2}(\|v_0\|_{H^2} + \|v_0\|_{L^2} |\ln\varepsilon_2|^2)^{1+\kappa}/2 \]
\[ \times \left( \|\nabla(Y_1 - Y_2)\|_{B_{-\kappa}^x}^2 + : |\nabla Y_1|^2 : - : |\nabla Y_2|^2 : B_{-\kappa}^x \right). \]

The result follows from integration in time and Lemma 2.1. For instance, we have:
\[ \|\nabla(Y_1 - Y_2)\|_{B_{-\kappa}^x} \leq c\|\nabla(Y_1 - Y_2)\|_{B_{-\kappa}^x}^{(1-\kappa)/2} \leq c\|Y_1 - Y_2\|_{B_{-\kappa}^x}^{(1-\kappa)/2} \leq K_1, \]
thanks to Lemma 2.1 with \( \kappa' = \frac{7\kappa}{8}, \kappa'' = \frac{3\kappa}{4} \) and \( p = \frac{8}{\kappa}. \)

By interpolation, we deduce from Proposition 3.3 and 3.4 the following result.

Corollary 3.5. Let \( \varepsilon_2 > \varepsilon_1 > 0 \) then for \( \kappa \in (0, 1], \gamma \in [0, 2], p \geq 1 \) there exists a random constant \( K_{\varepsilon_1, \varepsilon_2} \) bounded in \( L^p(\Omega) \) with respect to \( \varepsilon_1, \varepsilon_2 \) for any \( p \geq 1 \) such that if \( v_0 \in H^2 \):
\[ \sup_{t \in [0,T]} \|v_1(t) - v_2(t)\|_{H^\gamma} \leq K_{\varepsilon_1, \varepsilon_2}^{\frac{\gamma}{2}} \|v_1 - v_2\|_{B_{-\kappa}^x}^{1-\frac{\gamma}{2}} \leq K_{\varepsilon_1, \varepsilon_2}^{\frac{\gamma}{2}}. \]

We are now ready to state and prove the main result of this section.

Theorem 3.6. Assume that \( v_0 = v_0 \in L^p(\Omega; H^2) \) for some \( p > 1 \). For any \( T \geq 0 \), \( q < p, \gamma \in (1, 2) \), when \( \varepsilon \to 0 \), the solution \( v \) of (3.1) satisfying \( v(0) = v_0 \) converges in \( L^q(\Omega; C([0,T]; H^\gamma)) \) to \( v \) which is the unique solution to
\[ \frac{dv}{dt} = \Delta v - 2 \nabla v \cdot \nabla Y + v : |\nabla Y|^2 \quad \text{in } C([0,T]; H^{\gamma-2}) \]

in \( C([0,T]; H^\gamma) \) such that \( v(0) = v_0 \). Here, by solution, we mean that (3.8) holds as an equality in \( C([0,T]; H^{\gamma-2}) \).

Proof. Let us first prove pathwise uniqueness. Since the equation is linear, this amounts
to prove that a solution with \( v(0) = 0 \) is 0. Let us consider such a solution and write:
\[ \int_{T^2} |v(x,t)|^2 e^{-2Y(x)} dx = \lim_{\varepsilon \to 0} \int_{T^2} |v(x,t)|^2 e^{-2Y_1(x)} dx \]
as can be seen from Lemma 2.1. Then, $v \in C([0,T];H^\gamma)$ implies that $\frac{dv}{dt} \in C([0,T];H^{\gamma-2})$ and we may differentiate for $\varepsilon > 0$:

$$\frac{d}{dt} \int_{\mathbb{T}^2} |v(x,t)|^2 e^{-2Y_\varepsilon(x)} \, dx = 2 \frac{dv}{dt} \cdot ve^{-2Y_\varepsilon} = -2(i\Delta v - 2i\nabla v \cdot \nabla Y + iv : |\nabla Y|^2; ve^{-2Y_\varepsilon})$$

where $(\cdot, \cdot)$ has to be understood as the duality between $H^{\gamma-2}$ and $H^{2-\gamma}$. Note that $2 - \gamma \leq \gamma$. Recall that:

$$(i\Delta v - 2i\nabla v \cdot \nabla Y + iv : |\nabla Y|^2; ve^{-2Y_\varepsilon}) = 0,$$

and deduce:

$$\frac{d}{dt} \int_{\mathbb{T}^2} |v(x,t)|^2 e^{-2Y_\varepsilon(x)} \, dx = (-2i\nabla v \cdot \nabla(Y - Y_\varepsilon) + iv(\cdot |\nabla Y|^2; -; |\nabla Y|^2; ve^{-2Y_\varepsilon}).$$

We then repeat the estimate of the proof of Proposition 3.4 but estimate the $H^{1+\kappa}$ norm by the $H^{\gamma}$ norm and obtain

$$\| \frac{d}{dt} \int_{\mathbb{T}^2} |v(x,t)|^2 e^{-2Y_\varepsilon(x)} \, dx \| \leq K_\varepsilon e^{\gamma_\varepsilon}.$$  

The random constant $K_\varepsilon$ depends on the norm of $v_1, v_2$ in $C([0,T];H^\gamma)$ and on $Y_\varepsilon$. We take $\varepsilon = 2^{-k}$. By Lemma 2.1 and Borel-Cantelli, we know that $\sup_k K_{2^{-k}} < \infty$ a.s. Integrating in time and letting $k \to \infty$, we get $\int_{\mathbb{T}^2} |v(x,t)|^2 e^{-2Y_\varepsilon(x)} \, dx = 0$.

Now let $\varepsilon_k = 2^{-k}$, Corollary 3.5 implies that $(v_{\varepsilon_k})$ is Cauchy in $L^q(\Omega; C([0,T];H^\gamma))$. It is not difficult to prove that the limit $v$ is a solution of (3.8) and

$$E \left( \sup_{t \in [0,T]} \| v_{\varepsilon_k}(t) \|_{H^\gamma}^q \right) \leq c E \left( \| v_0 \|_{H^2}^p \right)^{q/p},$$

$$E \left( \sup_{t \in [0,T]} \| v(t) \|_{H^\gamma}^q \right) \leq c E \left( \| v_0 \|_{H^2}^p \right)^{q/p}.$$  

Let $\varepsilon > 0$ and $k$ such that $\varepsilon_k < \varepsilon$. By interpolation, with $\gamma' = \gamma < 2$,

$$\sup_{t \in [0,T]} \| v_{\varepsilon_k}(t) - v_{\varepsilon_k}(t) \|_{H^\gamma} \leq c \sup_{t \in [0,T]} \| v_{\varepsilon_k}(t) \|_{L^2}^{2(1-\gamma'/\gamma)} \sup_{t \in [0,T]} \| v_{\varepsilon_k}(t) - v_{\varepsilon_k}(t) \|_{H^\gamma}^{2\gamma'/\gamma} \leq c \sup_{t \in [0,T]} \| v_{\varepsilon_k}(t) \|_{L^2}^{2(1-\gamma'/\gamma)} \sup_{t \in [0,T]} \| v_{\varepsilon_k}(t) \|_{H^\gamma}^{2\gamma'/\gamma}.$$  

By Proposition 3.4, Proposition 3.3 and the above inequality, we deduce:

$$E \left( \sup_{t \in [0,T]} \| v_{\varepsilon_k}(t) - v_{\varepsilon_k}(t) \|_{H^\gamma}^q \right) \leq c \varepsilon^{\gamma/2} \| v_0 \|_{H^2}^{\gamma/p}. $$

Letting $k \to \infty$, we deduce that the whole family $(v_{\varepsilon_k})_{\varepsilon > 0}$ converges to $v$ in $L^q(\Omega; C([0,T];H^\gamma))$. It remains to let $\varepsilon \to 0$ in each term of (3.1) to prove that $v$ is a solution.

### 4 The nonlinear equation

We now study the nonlinear equation (2.2) and consider its approximation (2.3) with initial condition $v_\varepsilon(0) = v_\varepsilon = v_0 e^{\varepsilon}$.

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and assume below that it belongs to $H^2$. Using the same argument as in [5], we can prove existence of a solution to (2.4) in $C([0,T^*); H^2) \cap C^1([0,T^*); L^2)$ where $T^*$ is the maximal time of existence. It is either infinite or finite and in the latter case the $H^2$ norm blows up. This implies local existence and uniqueness for (2.3). Proposition 4.2 below shows that, under condition 4.2, the $H^2$ norm is bounded on finite time intervals and thus implies that $T^* = \infty$.

Again the solution is sufficiently regular to justify the computations yielding conservation of the mass and energy.

The mass gives a uniform bound in $L^2$ on $v_\varepsilon$:

$$
\|v_\varepsilon(t)\|_{L^2} \leq K_\varepsilon \|v_0\|_{L^2}^2.
$$

(4.1)

The estimate on the $H^1$ norm using the energy is similar to the linear case. Recall that the energy is given by:

$$
\tilde{H}_\varepsilon(v_\varepsilon(t)) = \int_{\mathbb{T}^2} \left( \frac{1}{2} |\nabla v_\varepsilon(x,t)|^2 + \frac{1}{2} |v_\varepsilon(x,t)|^2 : |\nabla Y_\varepsilon|^2 + \frac{\lambda}{4} |v_\varepsilon(x,t)|^4 e^{-2Y_\varepsilon(x)} \right) e^{-2Y_\varepsilon(x)} dx
$$

and it can be checked that for all $t \geq 0$ we have $\tilde{H}_\varepsilon(v_\varepsilon(t)) = \tilde{H}_\varepsilon(v_0)$.

**Proposition 4.1.** There exists a constant $K_\varepsilon$ bounded in $L^p(\Omega)$ for any $p \geq 1$ such that if $v_0 \in H^1$ and

$$
\|e^{-2Y_\varepsilon}\|_{L^\infty} \|e^{2Y_\varepsilon}\|_{L^\infty} \leq 1
$$

if $\lambda = 1$ (4.2)

then

$$
\|v_\varepsilon(t)\|_{H^1} \leq K_\varepsilon \left( \|v_0\|_{H^1}^2 + \|v_0\|_{L^2}^2 \|v_0\|_{H^1} \right).
$$

Moreover, the sequence $(k_\varepsilon) = (k_{2-\varepsilon})$ is bounded almost surely, i.e. $\sup_k K_{2-\varepsilon}$ is almost surely finite.

**Proof.** We proceed as in the proof of Proposition 3.1. We first have

$$
\int_{\mathbb{T}^2} v_\varepsilon^2 : |\nabla Y_\varepsilon|^2 : dx \leq K_\varepsilon \|v_\varepsilon\|_{L^2}^{2(1-\varepsilon)} \|v_\varepsilon\|_{H^1}^{2\varepsilon}
$$

and

$$
\int_{\mathbb{T}^2} |\nabla v_\varepsilon(x,t)|^2 dx
\leq K_\varepsilon \tilde{H}_\varepsilon(v_\varepsilon(t)) + K_\varepsilon \|v_\varepsilon(t)\|_{L^2}^{2(1-\varepsilon)} \|v_\varepsilon(t)\|_{H^1}^{2\varepsilon} + \frac{\lambda}{4} \int_{\mathbb{T}^2} |v_\varepsilon(x,t)|^4 e^{-2Y_\varepsilon(x)} e^{-2Y_\varepsilon(x)} dx
\leq K_\varepsilon \tilde{H}_\varepsilon(v_0) + K_\varepsilon \|v_0\|_{L^2}^2 + \frac{1}{2} \|\nabla v_\varepsilon\|_{L^2}^2 + \frac{\lambda}{4} \int_{\mathbb{T}^2} |v_\varepsilon(x,t)|^4 e^{-2Y_\varepsilon(x)} e^{-2Y_\varepsilon(x)} dx.
$$

For $\lambda = -1$, the result follows after dropping the last term and using

$$
\int_{\mathbb{T}^2} |v_\varepsilon(x,0)|^4 e^{-4Y_\varepsilon(x)} dx \leq K_\varepsilon \|v_0\|_{L^4}^4 \leq K_\varepsilon \|v_0\|_{H^{1/2}}^4 \leq K_\varepsilon \|v_0\|_{L^2}^4 \|v_0\|_{H^1}^2,
$$

thanks to the Sobolev embedding $H^{1/2} \subset L^4$ and interpolation.

For $\lambda = 1$, Gagliardo-Nirenberg inequality (see for instance [5] for a simple proof with the constant 1/2 used below):

$$
\int_{\mathbb{T}^2} |v_\varepsilon(x,t)|^4 e^{-4Y_\varepsilon(x)} dx \leq \|e^{-2Y_\varepsilon}\|_{L^\infty} \int_{\mathbb{T}^2} |v_\varepsilon(x,t)|^4 dx
\leq \frac{1}{2} \|e^{-2Y_\varepsilon}\|_{L^\infty} \int_{\mathbb{T}^2} |v_\varepsilon(x,t)|^2 dx \int_{\mathbb{T}^2} |\nabla v_\varepsilon(x,t)|^2 dx
\leq \frac{1}{2} \|e^{-2Y_\varepsilon}\|_{L^\infty} \|e^{2Y_\varepsilon}\|_{L^\infty} \|v_0\|_{L^2}^2 \int_{\mathbb{T}^2} |\nabla v_\varepsilon(x,t)|^2 dx,
$$

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where we have made use of \( \| v_\varepsilon(t) \|_{L^2}^2 \leq \| e^{2Y_\varepsilon} \|_{L^\infty} \| e^{-2Y_\varepsilon} \|_{L^\infty} \| v_0 \|_{L^2}^2 \) according to (3.3).

The result follows easily under assumption (4.2).

The constant \( K_\varepsilon \) is a polynomial in \( \| : |\nabla Y_\varepsilon|^2 : \|_{B^{1,\infty}_{\varepsilon}} \| e^{-2Y_\varepsilon} \|_{L^\infty} \) and \( \| e^{2Y_\varepsilon} \|_{L^{\infty}} \).

By Lemma 2.1 and Lemma 2.3 and Borel-Cantelli, we know that \( : |\nabla Y_{2-k}|^2 : \) and \( Y_{2-k} \) converge almost surely in \( B^{-\infty}_{\varepsilon} \) and \( B^{1,\infty}_{\varepsilon} \) so that \( K_\varepsilon \) is indeed bounded almost surely.

We now proceed with the \( H^2 \) bound.

**Proposition 4.2.** There exists a random constants \( K_\varepsilon \) bounded in \( L^p(\Omega) \) with respect to \( \varepsilon \) for any \( p \geq 1 \) such that if \( v_0 = u_0 e^{-Y} \in H^2 \) and (4.2) holds:

\[
\| v_\varepsilon(t) \|_{H^2} \leq c K_\varepsilon \left( 1 + \| v_0 \|_{H^2} + \| v_0 \|_{L^2} \right) \exp \left( K_\varepsilon \left( \| v_0 \|_{H^2} + \| v_0 \|_{L^2} \right) \right). 
\]

Moreover \( K_\varepsilon = K_{2-k} \) is bounded almost surely.

**Proof.** As in Section 3, we set \( w_\varepsilon = \frac{dv_\varepsilon}{dt} \) which now satisfies:

\[
\frac{d}{dt} v_\varepsilon = \Delta v_\varepsilon - 2\nabla v_\varepsilon \cdot \nabla Y_\varepsilon + w_\varepsilon : |\nabla Y_\varepsilon|^2 + \lambda \left( |v_\varepsilon|^4 + 2 \Re (v_\varepsilon \bar{w}_\varepsilon) v_\varepsilon \right) e^{-2Y_\varepsilon}.
\]

From (2.3), we have:

\[
w_\varepsilon(0) = -i(\Delta v_0 - 2\nabla v_0 \cdot \nabla Y_\varepsilon + v_0 : |\nabla Y_\varepsilon|^2 + |v_0|^4) + \lambda |v_0|^2 v_0 e^{-2Y_\varepsilon},
\]

and as in Proposition 3.3 and using the embedding \( H^1 \subset L^6 \):

\[
\| w_\varepsilon(0) \|_{L^2} \leq c \| v_0 \|_{H^2} + \| v_0 \|_{L^2} \left( \| |\nabla Y_\varepsilon|^4 \|_{L^1} + \| |\nabla Y_\varepsilon|^2 \|_{L^4} \right) \exp \left( K_\varepsilon \left( \| v_0 \|_{H^2} + \| v_0 \|_{L^2} \right) \right).
\]

By Lemma 2.4:

\[
P\left( \| |\nabla Y_\varepsilon|^4 \|_{L^1} + \| |\nabla Y_\varepsilon|^2 \|_{L^4} \geq |\ln \varepsilon|^4 \right) \leq c |\ln \varepsilon|^{-2}
\]

it follows that:

\[
\| w_\varepsilon(0) \|_{L^2} \leq c \| v_0 \|_{H^2} + K_\varepsilon \| v_0 \|_{L^2} \ln |\varepsilon| + K_\varepsilon \| v_0 \|_{H^1}.
\]

with \( K_\varepsilon \) having all moments finite and such that \( K_{2-k} \) is almost finite by Borel-Cantelli. We have taken \( |\ln \varepsilon| \) instead of \( |\ln \varepsilon|^2 \) in the estimate above in order to have this latter property. Recall that \( Y_{2-k} \) converges a.s. in \( L^\infty \).

We do not have preservation of the \( L^2 \) norm but:

\[
\frac{1}{2} \int_{T^2} |w_\varepsilon(x,t)|^2 e^{-2Y_\varepsilon(x)} dx = 2\lambda \int_{T^2} \Re (v_\varepsilon(x,t) \bar{w}_\varepsilon(x,t)) |Im(v_\varepsilon(x,t) \bar{w}_\varepsilon(x,t))| e^{-4Y_\varepsilon(x)} dx
\]

\[
\leq K_\varepsilon \| v_\varepsilon(t) \|_{L^\infty}^2 \int_{T^2} |w_\varepsilon(x,t)|^2 e^{-2Y_\varepsilon(x)} dx
\]

\[
\leq K_\varepsilon \| v_\varepsilon(t) \|_{H^1}^2 (1 + \ln(1 + \| v_\varepsilon(t) \|_{H^2})) \int_{T^2} |w_\varepsilon(x,t)|^2 e^{-2Y_\varepsilon(x)} dx
\]

\[
\leq K_\varepsilon \left( \| v_0 \|_{H^2}^2 + \| v_0 \|_{L^2}^2 \right) (1 + \ln(1 + \| v_\varepsilon(t) \|_{H^2})) \int_{T^2} |w_\varepsilon(x,t)|^2 e^{-2Y_\varepsilon(x)} dx
\]

thanks to the Brezis-Gallouet inequality (5.4) and to Proposition 4.1.

This computation is not rigorous. We proceed as in the linear case to justify it. We take a sequence of smooth initial data, say in \( H^4 \). In this case, using Theorem 5.4.1 in [6], we know that the solution is sufficiently regular to do the computations above. This
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Theorem 4.3. Assume that $v_0 = u_0 e^Y \in H^2$ and
\[
\|e^{-2Y}\|_{L^\infty} \|e^{2Y}\|_{L^\infty} \|v_0\|_{L^2} < 1 \text{ if } \lambda = 1.
\] (4.3)

For any $T \geq 0$, $p \geq 1$, $\gamma \in (1, 2)$, when $\varepsilon \to 0$, the solution $v_\varepsilon$ of (2.3) satisfying $v_\varepsilon(0) = v_0$ converges in probability in $C([0, T]; H^\gamma)$ to $v$ which is the unique solution to
\[
 i \frac{dv}{dt} = \Delta v - 2 \nabla v \cdot \nabla Y + v : |\nabla Y|^2 : + \lambda |v|^2 e^{-2Y}
\] (4.4)
with paths in $C([0, T]; H^\gamma)$ such that $v(0) = v_0$. 

The result follows.

We see that this $H^2$ bound is not as good as in the linear case. Due to the double exponential, we do not have moments here. However, this is sufficient to prove existence and uniqueness. We now state the main result of this section.

Theorem 4.3. Assume that $v_0 = u_0 e^Y \in H^2$ and
\[
\|e^{-2Y}\|_{L^\infty} \|e^{2Y}\|_{L^\infty} \|v_0\|_{L^2} < 1 \text{ if } \lambda = 1.
\] (4.3)

For any $T \geq 0$, $p \geq 1$, $\gamma \in (1, 2)$, when $\varepsilon \to 0$, the solution $v_\varepsilon$ of (2.3) satisfying $v_\varepsilon(0) = v_0$ converges in probability in $C([0, T]; H^\gamma)$ to $v$ which is the unique solution to
\[
 i \frac{dv}{dt} = \Delta v - 2 \nabla v \cdot \nabla Y + v : |\nabla Y|^2 : + \lambda |v|^2 e^{-2Y}
\] (4.4)
with paths in $C([0, T]; H^\gamma)$ such that $v(0) = v_0$. 

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Proof. Pathwise uniqueness is proved as in the linear case. Let $v_1$, $v_2$ be two solutions of (4.4) with paths in $C([0, T]; H^1)$ and starting with the same initial data. We set $r = v_1 - v_2$ which satisfies

$$\frac{dr}{dt} = \Delta r - 2\nabla r \cdot \nabla Y + r : |\nabla Y|^2 : + \lambda(|v_1|^2v_1 - |v_2|^2v_2)e^{-2Y}.$$  

The following computation can be done thanks to the regularity of $v_1$ and $v_2$:

$$\frac{d}{dt} \int_{T^2} |r(x, t)|^2 e^{-2Y_r(x)} \, dx = 2(\frac{dr}{dt}, r e^{-2Y_r})$$

$$= -2i(\Delta r - 2i\nabla r \cdot \nabla Y + ir : |\nabla Y|^2 : + \lambda(|v_1|^2v_1 - |v_2|^2v_2)e^{-2Y_r}, re^{-2Y_r})$$

$$\leq (-2i\nabla r \cdot \nabla (Y - Y_r) + i r : |\nabla Y|^2 : - \lambda(|v_1|^2v_1 - |v_2|^2v_2)e^{-2Y_r}, re^{-2Y_r}).$$

After similar manipulations as above:

$$\frac{d}{dt} \int_{T^2} |r(x, t)|^2 e^{-2Y_r(x)} \, dx \leq K_\varepsilon (e^{\alpha/2} + \int_{T^2} |r(x, t)|^2 e^{-2Y_r(x)} \, dx)$$

with $K_\varepsilon$ such that $\sup_{\varepsilon} K_{\varepsilon, k} < \infty$ a.s. It remains to use Gronwall Lemma, take $\varepsilon = 2^{-k}$ and let $k \to \infty$ to conclude that $r = 0$ a.s.

Under assumption (4.3), we know that (4.2) holds for $\varepsilon$ small enough. Thus we may use Propositions 4.1 and 4.2.

We take $\varepsilon_2 > \varepsilon_1 > 0$, set $r = v_{\varepsilon_1} - v_{\varepsilon_2}$ and write:

$$\frac{dr}{dt} = \Delta r - 2\nabla r \cdot \nabla Y_{\varepsilon_1} + r : |\nabla Y_{\varepsilon_1}|^2 : -2\nabla v_{\varepsilon_2} \cdot \nabla (Y_{\varepsilon_1} - Y_{\varepsilon_2}) + v_{\varepsilon_2} : (|\nabla Y_{\varepsilon_1}|^2 : - : |\nabla Y_{\varepsilon_2}|^2)$$

$$+ \lambda (|v_{\varepsilon_1}|^2v_{\varepsilon_1} - |v_{\varepsilon_2}|^2v_{\varepsilon_2})e^{-2Y_{\varepsilon_1}} + \lambda (|v_{\varepsilon_2}|^2v_{\varepsilon_2} - |v_{\varepsilon_1}|^2v_{\varepsilon_1})e^{-2Y_{\varepsilon_2}}. $$

By the same arguments as in Section 3 and standard estimates we obtain:

$$\frac{1}{2} \frac{d}{dt} \int_{T^2} |r(x, t)|^2 e^{-2Y_{\varepsilon_1}(x)} \, dx$$

$$\leq c ||e^{-2Y_{\varepsilon_1}} ||_{B_{2,\infty}^1} \|v_{\varepsilon_1}(t)||_{H^{1,\infty}} (\|v_{\varepsilon_1}(t)||_{H^1} + \|v_{\varepsilon_2}(t)||_{H^1})$$

$$\times (\|\nabla (Y_{\varepsilon_1} - Y_{\varepsilon_2})\|_{B_{2,\infty}^1} + \|: |\nabla Y_{\varepsilon_1}|^2 : - : |\nabla Y_{\varepsilon_2}|^2 \|_{B_{2,\infty}^1})$$

$$+ K_{\varepsilon_1} (\|v_{\varepsilon_1}\|_{L^\infty} + \|v_{\varepsilon_2}\|_{L^\infty}) \|v_{\varepsilon_1}\|_{L^\infty} \int_{T^2} |r(x, t)|^2 e^{-2Y_{\varepsilon_1}(x)} \, dx$$

$$+ K_{\varepsilon_1} ||v_{\varepsilon_2}||_{L^2}^2 (\|v_{\varepsilon_1}\|_{L^2} + \|v_{\varepsilon_2}\|_{L^2}) ||e^{-2Y_{\varepsilon_1}} - e^{-2Y_{\varepsilon_2}}||_{L^2}$$

$$\leq K_{\varepsilon_1, \varepsilon_2} \|v_{\varepsilon_2}\|_{H^1} (1 + \ln(1 + \|v_{\varepsilon_1}\|_{H^2})) \|v_{\varepsilon_1}\|_{H^1} (1 + \ln(1 + \|v_{\varepsilon_1}\|_{H^2}) + \ln(1 + \|v_{\varepsilon_2}\|_{H^2}))$$

$$\times \int_{T^2} |r(x, t)|^2 e^{-2Y_{\varepsilon_1}(x)} \, dx$$

$$+ K_{\varepsilon_1, \varepsilon_2} \|v_{\varepsilon_2}\|_{H^1}^2 (1 + \ln(1 + \|v_{\varepsilon_1}\|_{H^2}))^{3/2} \|v_{\varepsilon_1}\|_{L^2} + \|v_{\varepsilon_2}\|_{L^2}) \varepsilon_2^{\kappa},$$

by the Brezis-Gallouet inequality. We have used for $\kappa \in (0, 1)$:

$$\|e^{-2Y_{\varepsilon_1}} - e^{-2Y_{\varepsilon_2}}\|_{L^2} \leq 2 \|Y_{\varepsilon_1} - Y_{\varepsilon_2}\|_{L^3} (\|e^{-2Y_{\varepsilon_1}}\|_{L^\infty} + \|e^{-2Y_{\varepsilon_2}}\|_{L^\infty})$$

$$\leq c \|\varepsilon_2\|_{\kappa} \|Y\|_{B_{2,\infty}^1} (\|e^{-2Y_{\varepsilon_1}}\|_{L^\infty} + \|e^{-2Y_{\varepsilon_2}}\|_{L^\infty})$$

$$\leq K_{\varepsilon_1, \varepsilon_2} \|\varepsilon_2\|_{\kappa}^{\kappa}.$$
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Again, the constants $K_{\varepsilon_1}, K_{\varepsilon_1, \varepsilon_2}$ above have all moments bounded independently of $\varepsilon_1, \varepsilon_2$ are almost surely bounded in $k$ for $\varepsilon_1 = 2^{-(k+1)}, \varepsilon_2 = 2^{-k}$.

We deduce from Gronwall’s Lemma:
\[
\ln \|r\|_{L^2} \leq K_{\varepsilon_1, \varepsilon_2} P(v_0)(1 + \ln P(v_0) + \ln |\ln \varepsilon|) \exp(K_{\varepsilon_1, \varepsilon_2} P(v_0)t) + \kappa \exp(K_{\varepsilon_1, \varepsilon_2} P(v_0)t)(\ln K_{\varepsilon_1, \varepsilon_2} + \ln P(v_0) + \ln |\ln \varepsilon|) - \frac{\kappa}{2} |\ln \varepsilon|,
\]
where $P(v_0)$ denotes a polynomial in $\|v_0\|_{H^2}$. By interpolation, we have
\[
\ln \|r\|_{H^\gamma} \leq c + (1 - \frac{\gamma}{2}) \ln \|r\|_{L^2} + \frac{\gamma}{2} \ln \|r\|_{H^2}
\]
so that a similar estimate holds for $\ln \|r\|_{H^\gamma}, \gamma < 2$.

The constants $K_{\varepsilon_1, \varepsilon_2}$ are bounded almost surely when $\varepsilon_1 = 2^{-(k+1)}, \varepsilon_2 = 2^{-k}$ so that
\[
\|v_2^{1-(k+1)} - v_2^{-k}\|_{H^\gamma} \leq C(v_0)|\ln 2^{-(k+1)}|C(v_0)\frac{2}{\gamma}(k+1),
\]
where now $C(v_0)$ is a random constant depending on $\|v_0\|_{H^2}$. It follows that $v_2^{-k}$ is Cauchy in $C([0, T], H^\gamma)$.

Finally, we reproduce the estimate above for $\|v_2(t) - v_2^{-k}\|_{L^2}$ but bound $\|v_2^{-k}\|_{L^2}$ by $\|v^{-k}\|_{H^\gamma}$ instead of using Brezis-Gallouet inequality. We obtain:
\[
\ln \|v_2(t) - v_2^{-k}\|_{L^2} \leq \tilde{K}_{\varepsilon_1, \varepsilon_2} P(v_0)(1 + \ln P(v_0) + \ln |\ln \varepsilon|) \exp(\tilde{K}_{\varepsilon_1, \varepsilon_2} P(v_0)t) + \kappa \exp(\tilde{K}_{\varepsilon_1, \varepsilon_2} P(v_0)t)(\ln \tilde{K}_{\varepsilon_1, \varepsilon_2} + \ln P(v_0) + \ln |\ln \varepsilon|) - \frac{\kappa}{2} |\ln \varepsilon|,
\]
where $\tilde{K}_{\varepsilon_1, \varepsilon_2}$ are constants with moments bounded independently on $\varepsilon$ and $k$. Again, a similar bound holds for the $H^\gamma$ norm thanks to an interpolation argument. Letting $k \to \infty$ yields:
\[
\ln \|v_2(t) - v\|_{L^2} \leq \tilde{K}_2 P(v_0)(1 + \ln P(v_0) + \ln |\ln \varepsilon|) \exp(\tilde{K}_2 P(v_0)t) + \kappa \exp(\tilde{K}_2 P(v_0)t)(\ln \tilde{K}_2 + \ln P(v_0) + \ln |\ln \varepsilon|) - \frac{\kappa}{2} |\ln \varepsilon|,
\]
where again $\tilde{K}_2$ are constants with bounded moments.

The conclusion follows. \hfill \Box

Remark 4.4. Condition (4.3) is probably not optimal. It can easily be weakened to $\lambda K_2^2 K_{1, \varepsilon} \|v_0\|_{L^2} < 2$, but this is probably not optimal either.

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