Higher-derivative mechanics with $\mathcal{N} = 2$

$l$-conformal Galilei supersymmetry

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Abstract

The analysis previously developed in [arXiv:1407.1438] is used to construct systems which hold invariant under $\mathcal{N} = 2$ $l$-conformal Galilei superalgebra. The models describe two different supersymmetric extensions of a free higher-derivative particle. Their Newton-Hooke counterparts are derived by applying appropriate coordinate transformations.

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1. Introduction

It is well-known that the Galilei algebra can be extended by the generators of dilatations and special conformal transformations in different ways. In general, the set of such extensions is called the $l$-conformal Galilei algebra [1]-[3], where $l$ is a positive integer or half-integer parameter. The so-called Schrödinger algebra [4] and the conformal Galilei algebra [5, 6] are the most popular instances which correspond to $l = 1/2$ and $l = 1$, respectively (see [6]-[35] and references therein).

In recent years, the $l$-conformal Galilei algebra for $l > 1$ has attracted much attention [31], [36]-[58]. This line of research includes the construction of dynamical realizations [41]-[48], [50, 53], [55]-[58], the investigation of supersymmetric extensions [38, 40, 49, 55], the analysis of central charges [36, 40, 49, 54]. Infinite-dimensional generalizations [36, 38, 54, 55], irreducible representations [37, 39, 52, 56], and twist deformations [51] have also been studied. To a large extent, this activity is motivated by the current study of the nonrelativistic version of the AdS/CFT-correspondence [59, 60].

If one changes the basis in the $l$-conformal Galilei algebra

$$K_{-1} \rightarrow K_{-1} \pm \frac{1}{R^2} K_1,$$

where $K_{-1}$ is the generator of time translations, $K_1$ is the generator of special conformal transformations, $\Lambda = \mp \frac{1}{R^2}$ is the nonrelativistic cosmological constant, one obtains the structure relations of the so-called $l$-conformal Newton-Hooke algebra [2, 3, 36]. This algebra is suitable for physical applications in Newton-Hooke spacetime, i.e. in nonrelativistic spacetime with cosmological attraction or repulsion [61]. Because the $l$-conformal Galilei algebra and the $l$-conformal Newton-Hooke algebra are isomorphic, one can speak about realizations of one and the same algebra in flat spacetime and in nonrelativistic spacetime with cosmological constant, respectively.

So far supersymmetric extensions of the $l$-conformal Galilei algebra have been investigated mostly for $l = 1/2$ and $l = 1$. It was shown that the Schrödinger supersymmetries manifest itself in nonrelativistic spin-1/2 particle [7], the nonrelativistic Chern-Simons matter system [8] and many-body mechanics [18, 22, 24, 30]. The systematic study of Schrödinger superalgebras was given in [9]. A relation with relativistic superconformal algebras and infinite-dimensional generalizations were studied in [15, 16, 34, 35] and [12], respectively. Various supersymmetric extensions of the conformal Galilei algebra were obtained in [23], [25]-[28], [33] by applying appropriate contraction procedures.

For arbitrary value of the parameter $l$, the $\mathcal{N} = 1$ and $\mathcal{N} = 2$ supersymmetric extensions of the $l$-conformal Galilei algebra were formulated in recent works [38], [40], [49], [55]. In particular, in [55] dynamical systems which hold invariant under the $\mathcal{N} = 1$ $l$-conformal Galilei superalgebra were constructed. Yet, the previous studies of $d = 1$, $\mathcal{N} = 4$ superconformal mechanics [62]-[69] indicate that the instance of $\mathcal{N} = 2$ is likely to be the maximal number of supersymmetries compatible with translation invariance of an interacting system. By this reason, it is natural to dwell on the dynamical realizations of the $\mathcal{N} = 2$ $l$-conformal Galilei superalgebra. The purpose of this work is thus to generalize the results obtained in our recent work [55] to the case of $\mathcal{N} = 2$.

We begin in Section 2 with a brief review of the $l$-conformal Galilei algebra and its
\( N = 2 \) supersymmetric extension and then construct dynamical realizations of such a superalgebra in a flat superspace. Associated mechanical systems in Newton-Hooke superspace are considered in Section 3. In Section 4 we summarize our results and discuss possible further developments. Some technical details regarding the derivation of an invariant action functional in Section 2 are presented in Appendix A.

2. Higher-derivative mechanics in flat superspace

The \( l \)-conformal Galilei algebra involves the generators \( K_{-1} \) and \( K_1 \) mentioned above, the generator of dilatations \( K_0 \), the set of vector generators \( C_i^{(n)} \) with \( n = 0, 1, \ldots, 2l \), and the generators of space rotations \( M_{ij} \). The non-vanishing structure relations in the algebra read

\[
[K_p, K_m] = (m - p) K_{p+m}, \quad [K_m, C_i^{(n)}] = (n - l(m + 1)) C_i^{(n+m)},
\]

\[
[M_{ij}, C_k^{(n)}] = \delta_{ik} C_j^{(n)} - \delta_{jk} C_i^{(n)}, \quad [M_{ij}, M_{ks}] = \delta_{ik} M_{js} + \delta_{js} M_{ik} - \delta_{is} M_{jk} - \delta_{jk} M_{is}. \tag{2}
\]

There are two types of \( N = 2 \) supersymmetric extensions of the \( l \)-conformal Galilei algebra [38, 49] which are called chiral and real. Apart from the generators considered above, both the superalgebras involve a pair of supersymmetry generators \( G_{-1/2}, \tilde{G}_{-1/2} \), the superconformal generators \( G_{1/2}, \tilde{G}_{1/2} \), the generator of \( U(1) \) \( R \)-symmetry transformations \( J \), the fermionic partners of the vector generators \( L_i^{(n)}, \tilde{L}_i^{(n)} \) with \( n = 0, 1, \ldots, 2l - 1 \), and the additional bosonic generators \( P_i^{(n)} \) with \( n = 0, 1, \ldots, 2l - 2\gamma \), where

\[
\gamma = \begin{cases} 
0, & \text{for chiral superalgebra;} \\
1, & \text{for real superalgebra.}
\end{cases} \tag{3}
\]

It should be noted that for the real \( N = 2 \) supersymmetric extension of the Schrödinger algebra the bosonic generators \( P_i^{(n)} \) are absent.

In addition to (2) the nonvanishing (anti)commutation relations of the \( N = 2 l \)-conformal Galilei superalgebra include

\[
\{G_r, G_s\} = 2iK_{r+s} + (-1)^{r+1/2}\delta_{r+s,0} J, \quad [J, C_i^{(n)}] = 2l(1 - \gamma) P_i^{(n)},
\]

\[
[G_r, C_i^{(n)}] = (n - 2l(r + 1/2)) L_i^{(n+r-1/2)}, \quad [J, L_i^{(n)}] = i(1 + 2l(1 - \gamma)) L_i^{(n)},
\]

\[
[G_r, C_i^{(n)}] = (n - 2l(r + 1/2)) \tilde{L}_i^{(n+r-1/2)}, \quad [J, \tilde{L}_i^{(n)}] = -i(1 + 2l(1 - \gamma)) \tilde{L}_i^{(n)},
\]

\[
[K_m, P_i^{(n)}] = (n - (l - \gamma)(m + 1)) P_i^{(n+m)}, \quad [J, P_i^{(n)}] = -2l(1 - \gamma) C_i^{(n)},
\]

\[
[K_m, L_i^{(n)}] = (n - (l - 1/2)(m + 1)) L_i^{(n+m)}, \quad [K_m, G_r] = (r - m/2) G_{m+r},
\]

\[
[K_m, \tilde{L}_i^{(n)}] = (n - (l - 1/2)(m + 1)) \tilde{L}_i^{(n+m)}, \quad [K_m, \tilde{G}_r] = (r - m/2) \tilde{G}_{m+r},
\]

\[
[G_r, P_i^{(n)}] = i\left(1 + (1 - \gamma)[n - 2l(r + 1/2) - 1]\right)L_i^{(n+r+\gamma-1/2)}, \quad [J, G_r] = i G_r, \tag{4}
\]

\[
[\tilde{G}_r, P_i^{(n)}] = -i\left(1 + (1 - \gamma)[n - 2l(r + 1/2) - 1]\right)\tilde{L}_i^{(n+r+\gamma-1/2)}, \quad [J, \tilde{G}_r] = -i \tilde{G}_r,
\]

\[
\{G_r, \tilde{L}_i^{(n)}\} = iC_i^{(n+r+1/2)} - \left(1 + \gamma[n - (2l - 1)(r + 1/2) - 1]\right)P_r^{(n-r+1/2)},
\]

\[
\{\tilde{G}_r, L_i^{(n)}\} = iC_i^{(n+r+1/2)} - \left(1 + \gamma[n - (2l - 1)(r + 1/2) - 1]\right)\tilde{P}_r^{(n-r+1/2)}.
\]
where $M$.

For integer $n$, (anti)commutators between the vector generators can be modified as follows:

\[
[M_{ij}, A_k^{(n)}] = \delta_{ik}A_j^{(n)} - \delta_{jk}A_i^{(n)}, \quad A_i^{(n)} = L_i^{(n)}, \quad \bar{L}_i^{(n)}, \quad P_i^{(n)}.
\]

The superalgebra (2), (4) admits a central extension. According to the results in [36, 40, 49], (anti)commutators between the vector generators can be modified as follows:

\[
[C_i^{(n)}, C_j^{(m)}] = (-1)^n n! m! \delta_{n+m,2l} \lambda_{ij} M, \quad \{L_i^{(n)}, \bar{L}_j^{(m)}\} = i(-1)^n n! m! \delta_{n+m,2l-1} \lambda_{ij} M, \quad \{P_i^{(n)}, P_j^{(m)}\} = (-1)^{n+\gamma} n! m! \delta_{n+m,2l-2} \lambda_{ij} M,
\]

where $M$ is a central charge and

\[
\lambda_{ij} = \begin{cases} 
\delta_{ij}, & i, j = 1, 2, \ldots, d, \quad \text{for half-integer } l; \\
\epsilon_{ij}, & i, j = 1, 2, \quad \text{for integer } l,
\end{cases}
\]

with $\epsilon_{12} = 1$.

The central extension (5) allows one to obtain a realization of all the scalar generators as well as the generators of space rotations in terms of the quadratic combinations of the vector generators [40, 49]

\[
K_n = \sum_{k=0}^{2l} \sigma_{k,0} c^{(2l-k)} c^{(k+n)} + 2l \sum_{k=0}^{2l-1} \sigma_{k,1} L^{(2l-k-1)} L^{(k+n)} + (-1)^{2l-2\gamma} \sum_{k=0}^{2l-2\gamma} \sigma_{k,2} P^{(2l-2\gamma-k)} P^{(k+n)},
\]

\[
G_r = 2 \sum_{k=0}^{2l} \sigma_{k,0} c^{(2l-k+r+1/2)} + i(1 - \gamma [(2l-1)(r-1/2) + k]) P^{(2l-k+r+1/2-\gamma)} L^{(k-1)},
\]

\[
\bar{G}_r = 2 \sum_{k=0}^{2l} \sigma_{k,0} c^{(2l-k+r+1/2)} - i(1 - \gamma [(2l-1)(r-1/2) + k]) P^{(2l-k+r+1/2-\gamma)} L^{(k-1)},
\]

\[
J = \frac{2l - 2l\gamma + 1}{2} \sum_{k=0}^{2l-1} \nu_{k,1} (L^{(2l-k-1)} L^{(k)} - L^{(2l-k-1)} L^{(k)}) + 2l(1 - \gamma) \sum_{k=0}^{2l} \nu_{k,0} c^{(2l-k)} P^{(k)},
\]

\[
M_{ij} = \sum_{k=0}^{2l} \nu_{k,0} c_i^{(2l-k)} c_j^{(k)} + (-1)^{2l-2\gamma} \sum_{k=0}^{2l} \nu_{k,2} P_i^{(2l-2\gamma-k)} P_j^{(k)} + i \sum_{k=0}^{2l-1} \nu_{k,1} L_i^{(2l-k-1)} L_j^{(k)} + i \sum_{k=0}^{2l-1} \nu_{k,1} \bar{L}_i^{(2l-k-1)} \bar{L}_j^{(k)}.
\]

For integer $l$ the generator of spatial rotations has the form\(^1\)

\[
M_{12} = -\sum_{k=0}^{2l} \frac{\nu_{k,0}}{2} c_i^{(2l-k)} c_i^{(k)} - i \sum_{k=0}^{2l-1} \nu_{k,1} L_i^{(2l-k-1)} \bar{L}_i^{(k)} - (-1)^{2l-2\gamma} \sum_{k=0}^{2l-2\gamma} \frac{\nu_{k,2}}{2} P_i^{(2l-2\gamma-k)} P_i^{(k)},
\]

where we denoted

\[
\sigma_{k,s}^n = \frac{1}{2} (k - (l - s/2)(n + 1)) \nu_{k,s}, \quad \nu_{k,s} = \frac{(-1)^{2l-k-s}}{M k!(2l - k - s)!}.
\]

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\(^{1}\)Throughout the work the summation over repeated spatial indices is understood.
In (7) above the bold style letters refer to the product of vector generators \( AB = \lambda_{ij} A_i B_j \).

In order to construct a dynamical realization of the superalgebra (2), (4), (5), we adopt the strategy suggested in \([55]\). As the first step, we construct a system which possesses the vector integrals of motion satisfying the relations (5) under some graded Poisson bracket. This can be done by applying the conventional method of nonlinear realizations \([70, 71]\) to vector integrals of motion satisfying the relations (5) under some graded Poisson bracket.

It is straightforward to verify that the vector integrals of motion (11) obey the structure relations (12) with \( M = 1 \).

This action describes a free \( \mathcal{N} = 2 \) higher-derivative superparticle whose configuration space degrees of freedom involve the bosonic coordinates \( x_i \), the fermionic coordinates \( \psi_i \) and \( \bar{\psi}_i \), and extra bosonic coordinates \( z_i \). The bosonic limit of (9) has been recently studied in \([41]-[42], [44]-[46]\). Some technical details regarding the derivation of this action are gathered in Appendix A.

The action (9) is invariant under the transformations

\[
\delta x_i = \sum_{n=0}^{2l} a_i^{(n)} t^n, \quad \delta \bar{\psi}_i = \sum_{n=0}^{2l-1} \bar{\xi}_i^{(n)} t^n, \quad \delta \psi_i = \sum_{n=0}^{2l-1} \xi_i^{(n)} t^n, \quad \delta z_i = \sum_{n=0}^{2l-2\gamma} b_i^{(n)} t^n,
\]

which yield the following integrals of motion:

\[
C_i^{(n)} = \lambda_{ij} \sum_{k=0}^{n} \frac{(-1)^{k+1} n!}{(n-k)!} t^{n-k} x_j^{(2l-k)}, \quad L_i^{(n)} = i\lambda_{ij} \sum_{k=0}^{n} \frac{(-1)^k n!}{(n-k)!} t^{n-k} \psi_j^{(2l-k-1)},
\]

\[
\bar{L}_i^{(n)} = i\lambda_{ij} \sum_{k=0}^{n} \frac{(-1)^{k+1} n!}{(n-k)!} t^{n-k} \bar{\psi}_j^{(2l-k-1)}, \quad P_i^{(n)} = \lambda_{ij} \sum_{k=0}^{n} \frac{(-1)^k n!}{(n-k)!} t^{n-k} z_j^{(2l-2\gamma-k)},
\]

where \( f^{(n)}(t) \equiv \frac{d^n f(t)}{dt^n} \), \( f^{(0)}(t) \equiv f(t) \).

At the next step, let us introduce the graded Poisson bracket

\[
[A, B] = \lambda_{ij} \left( \sum_{n=0}^{2l} (-1)^n \frac{\partial A}{\partial x_i^{(2l-n)}} \frac{\partial B}{\partial x_j} - i \sum_{n=0}^{2l-1} (-1)^n \frac{\partial A}{\partial \psi_i^{(n)}} \frac{\partial B}{\partial \psi_j^{(2l-n-1)}} - i \sum_{n=0}^{2l-1} (-1)^n \frac{\partial A}{\partial \bar{\psi}_i^{(n)}} \frac{\partial B}{\partial \bar{\psi}_j} + \sum_{n=0}^{2l-2\gamma} (-1)^{n+\gamma} \frac{\partial A}{\partial z_i^{(n)}} \frac{\partial B}{\partial z_j^{(2l-2\gamma-n)}} \right).
\]

This can be viewed as an \( \mathcal{N} = 2 \) generalization of the bracket considered recently in \([55]\).

It is straightforward to verify that the vector integrals of motion (11) obey the structure relations (12) with \( M = 1 \). Therefore the expressions (7) and (8) provide further integrals of motion which together with (11) form a representation of the \( \mathcal{N} = 2 \) \( l \)-conformal Galilei superalgebra (2), (4), (5). Symmetry transformations of the action functional (9) which correspond to the integrals (7), (8) read

\[
K_n : \quad \delta t = t^{n+1} a_n, \quad \delta x_i = l(n+1) t^n a_n x_i, \quad \delta \psi_i = (l-1/2)(n+1) t^n a_n \psi_i,
\]

\[
\delta \bar{\psi}_i = (l-1/2)(n+1) t^n a_n \bar{\psi}_i, \quad \delta z_i = (l-\gamma)(n+1) t^n a_n z_i;
\]

\[
G_{-\frac{1}{2}} : \quad \delta x_i = i \psi_i \alpha_{-\frac{1}{2}}, \quad \delta z_i = -\psi_i^{(\gamma)} \alpha_{-\frac{1}{2}}, \quad \delta \bar{\psi}_i = (x_i^{(1)} + iz_i^{(1-\gamma)}) \alpha_{-\frac{1}{2}}.
\]
\[ G_{-\frac{1}{2}} : \quad \delta x_i = i\overline{\psi}_i \alpha_{-\frac{1}{2}}, \quad \delta z_i = \overline{\psi}^{(\gamma)}_i \alpha_{-\frac{1}{2}}, \quad \delta \psi_i = (x_i^{(1)} - iz_i^{(1-\gamma)})\alpha_{-\frac{1}{2}}; \]
\[ G_{\frac{1}{2}} : \quad \delta x_i = it\psi_i \alpha_{\frac{1}{2}}, \quad \delta z_i = (-t\psi_i^{(\gamma)} + (2l - 1)\gamma \psi_i)\alpha_{\frac{1}{2}}, \]
\[ \delta \overline{\psi}_i = (tx_i^{(1)} - 2lx_i + itz_i^{(1-\gamma)} - 2il(1 - \gamma)z_i)\alpha_{\frac{1}{2}}; \]
\[ G_{-\frac{1}{2}} : \quad \delta x_i = it\overline{\psi}_i \alpha_{-\frac{1}{2}}, \quad \delta z_i = (t\overline{\psi}^{(\gamma)}_i - (2l - 1)\gamma \overline{\psi}_i)\alpha_{-\frac{1}{2}}, \]
\[ \delta \psi_i = (tx_i^{(1)} - 2lx_i - itz_i^{(1-\gamma)} + 2il(1 - \gamma)z_i)\alpha_{-\frac{1}{2}}; \]
\[ J : \quad \delta x_i = 2l(1 - \gamma)\nu z_i, \quad \delta z_i = -2l(1 - \gamma)\nu x_i, \quad \delta \overline{\psi}_i = -i(2l - 2l\gamma + 1)\nu \overline{\psi}_i, \]
\[ \delta \psi_i = i(2l - 2l\gamma + 1)\nu \psi_i, \]
\[ M_{ij} : \quad \delta x_i = w_{ij} x_j, \quad \delta \psi_i = w_{ij} \psi_j, \quad \delta \overline{\psi}_i = w_{ij} \overline{\psi}_j, \quad \delta z_i = w_{ij} z_j, \quad (w_{ij} = -w_{ji}). \]

Thus, a free higher-derivative superparticle (9) provides a dynamical realization of the \( \mathcal{N} = 2 \) \( l \)-conformal Galilei superalgebra (2), (4), (5). It should be remembered that the bosonic generators \( P_i^{(n)} \) and the coordinates \( z_i^{(n)} \) must be discarded for the case of the real \( \mathcal{N} = 2 \) Schrödinger superalgebra.

3. Associated mechanics in Newton-Hooke superspace

Inspired by the results in [55], let us introduce an analogue of Niederer’s coordinate transformations [72] which link dynamical realizations of \( \mathcal{N} = 2 \) \( l \)-conformal Galilei superalgebra in flat superspace to those in Newton-Hooke superspace. For the case of a negative cosmological constant we set

\[ t' = R \tan(t/R), \quad x'_i(t') = x_i(t)/\cos^2(t/R), \quad \psi'_i(t') = \psi_i(t)/\cos^{2l-1}(t/R), \]
\[ \overline{\psi}^\prime_i(t') = \overline{\psi}_i(t)/\cos^{2l-1}(t/R), \quad z'_i(t') = z_i(t)/\cos^{2l-2\gamma}(t/R). \] (14)

For half-integer \( l \) implementation of (14) in (9) results in the action functional

\[ S = \frac{1}{2} \int dt \left( x_i \prod_{k=1}^{l+\frac{1}{2}} \left( \frac{d^2}{dt^2} + \frac{(2k - 1)^2}{R^2} \right) x_i - i\psi_i \prod_{k=1}^{l-\frac{1}{2}} \left( \frac{d^2}{dt^2} + \frac{(2k)^2}{R^2} \right) \overline{\psi}_i - \right. \]
\[ \left. - i\overline{\psi}_i \prod_{k=1}^{l-\frac{1}{2}} \left( \frac{d^2}{dt^2} + \frac{(2k)^2}{R^2} \right) \overline{\psi}_i + (-1)^{\gamma} z_i \prod_{k=1}^{l-\gamma+\frac{1}{2}} \left( \frac{d^2}{dt^2} + \frac{(2k - 1)^2}{R^2} \right) z_i \right) \] (15)

while for integer \( l \) one has

\[ S = \frac{1}{2} \int dt \epsilon_{ij} \left( x_i \prod_{k=1}^{l} \left( \frac{d^2}{dt^2} + \frac{(2k)^2}{R^2} \right) x_j - i\psi_i \prod_{k=1}^{l} \left( \frac{d^2}{dt^2} + \frac{(2k - 1)^2}{R^2} \right) \overline{\psi}_j - \right. \]
\[ \left. - i\overline{\psi}_i \prod_{k=1}^{l} \left( \frac{d^2}{dt^2} + \frac{(2k - 1)^2}{R^2} \right) \overline{\psi}_j + (-1)^{\gamma} z_i \prod_{k=1}^{l-\gamma} \left( \frac{d^2}{dt^2} + \frac{(2k)^2}{R^2} \right) \dot{z}_j \right) \] (16)

5
These actions describe $\mathcal{N} = 2$ supersymmetric generalizations of the so-called Pais-Uhlenbeck oscillator [73] (for a review see also [74]) for a particular choice of its frequencies. Recently the bosonic limit of the models (15) and (16) has been extensively studied in [48], [53], [57, 58].

The coordinate transformations (14) allow one to readily obtain symmetry transformations and associated integrals of motion from the expressions (10), (11), (13) and (7). For example, the application of (14) to (10) yields

$$\delta x_i = \sum_{n=0}^{2l-1} a_i^{(n)} R^n \sin^n \frac{t}{R} \cos^{2l-n-1} \frac{t}{R}, \quad \delta \bar{\psi}_i = \sum_{n=0}^{2l-1} \bar{\xi}_i^{(n)} R^n \sin^n \frac{t}{R} \cos^{2l-n-1} \frac{t}{R},$$

$$\delta \psi_i = \sum_{n=0}^{2l-1} \xi_i^{(n)} R^n \sin^n \frac{t}{R} \cos^{2l-n-1} \frac{t}{R}, \quad \delta z_i = \sum_{n=0}^{2l-1} b_i^{(n)} R^n \sin^n \frac{t}{R} \cos^{2l-2\gamma-n} \frac{t}{R}. \quad (17)$$

The associated conserved vector charges obey the structure relations (5) under the graded Poisson bracket which is obtained from (12) with the help of (14) (see also a related discussion in [55]). The graded bracket enables one to automatically produce additional integrals of motion. In particular, taking into account (1) and the following the redefinition:

$$G_{-\frac{1}{2}} \rightarrow G_{-\frac{1}{2}} + \frac{i}{R} \bar{G}_{\frac{1}{2}}, \quad \bar{G}_{-\frac{1}{2}} \rightarrow \bar{G}_{-\frac{1}{2}} - \frac{i}{R} G_{\frac{1}{2}}, \quad (18)$$

one finds the infinitesimal symmetry transformations of the form

$$K_0: \quad \delta t = \frac{R}{2} \sin \frac{2t}{R} a_0, \quad \delta x_i = l \cos \frac{2t}{R} x_i a_0, \quad \delta \bar{\psi}_i = \left(l - \frac{1}{2}\right) \cos \frac{2t}{R} \psi_i a_0, \quad \delta \psi_i = \left(l - \frac{1}{2}\right) \cos \frac{2t}{R} \psi_i a_0,$$

$$K_1: \quad \delta t = R^2 \sin^2 \frac{t}{R} a_1, \quad \delta x_i = l R \sin \frac{2t}{R} x_i a_1, \quad \delta \bar{\psi}_i = \left(l - \frac{1}{2}\right) R \sin \frac{2t}{R} \bar{\psi}_i a_1, \quad \delta \psi_i = \left(l - \frac{1}{2}\right) R \sin \frac{2t}{R} \psi_i a_1,$$

$$G_{-\frac{1}{2}}: \quad \delta x_i = i e^{\frac{\bar{\alpha}}{2}} \bar{\psi}_i \alpha_{-\frac{1}{2}}, \quad \delta z_i = e^{\frac{\bar{\alpha}}{2}} \left(-\psi_i^{(1-\gamma)} + \frac{2l-1}{R} \gamma \bar{\psi}_i\right) \alpha_{-\frac{1}{2}},$$

$$\delta \bar{\psi}_i = \frac{e^{\frac{\bar{\alpha}}{2}}}{R} \left(x_i^{(1)} - \frac{2il}{R} x_i + i z_i^{(1-\gamma)} + \frac{2l(1-\gamma)}{R} z_i\right) \alpha_{-\frac{1}{2}},$$

$$\bar{G}_{-\frac{1}{2}}: \quad \delta x_i = i e^{-\frac{\bar{\alpha}}{2}} \bar{\psi}_i \alpha_{-\frac{1}{2}}, \quad \delta z_i = e^{-\frac{\bar{\alpha}}{2}} \left(-\psi_i^{(1-\gamma)} + \frac{2l-1}{R} \gamma \bar{\psi}_i\right) \bar{\alpha}_{-\frac{1}{2}},$$

$$\delta \psi_i = e^{-\frac{\bar{\alpha}}{2}} \left(x_i^{(1)} + \frac{2il}{R} x_i - i z_i^{(1-\gamma)} + \frac{2l(1-\gamma)}{R} z_i\right) \bar{\alpha}_{-\frac{1}{2}},$$

$$G_{\frac{1}{2}}: \quad \delta x_i = l \cos \frac{t}{R} x_i \psi_{\frac{1}{2}}, \quad \delta z_i = \left(-l \sin \frac{t}{R} \psi_{\frac{1}{2}}^{(1-\gamma)} + \frac{2l-1}{R} \gamma \cos \frac{t}{R} \psi_{\frac{1}{2}}\right) \alpha_{\frac{1}{2}},$$

$$\delta \bar{\psi}_i = \left(l \sin \frac{t}{R} x_i^{(1)} - 2l \cos \frac{t}{R} x_i + l R \sin \frac{t}{R} z_i^{(1-\gamma)} - 2il(1-\gamma) \cos \frac{t}{R} z_i\right) \alpha_{\frac{1}{2}};$$
$G_{\frac{1}{2}}: \quad \delta x_i = i R \sin \frac{t}{R} \bar{\psi}_i \bar{\alpha}_{\frac{1}{2}}, \quad \delta z_i = \left( R \sin \frac{t}{R} \bar{\psi}_i^{(\gamma)} - (2l - 1) \gamma \cos \frac{t}{R} \bar{\psi}_i \right) \bar{\alpha}_{\frac{1}{2}},$

$\delta \psi_i = \left( R \sin \frac{t}{R} \bar{x}_i^{(1)} - 2l \cos \frac{t}{R} \bar{x}_i - i R \sin \frac{t}{R} \bar{z}_i^{(1-\gamma)} + 2il(1-\gamma) \cos \frac{t}{R} \bar{z}_i \right) \bar{\alpha}_{\frac{1}{2}}.$

Transformations associated with $K_{-1}, J, M_{ij}$ hold the same form as in (11).

For the case of a positive cosmological constant Niederer-like transformations can be obtained from (14) by a formal change $R \rightarrow iR$. Note that the flat space limit $R \rightarrow \infty$ reproduces the model (9).

4. Conclusion

To summarize, in this paper we have constructed the simplest dynamical realizations of $\mathcal{N} = 2$ $l$-conformal Galilei superalgebra in flat superspace and in Newton-Hooke superspace. In the latter case the model can be interpreted as an $\mathcal{N} = 2$ supersymmetric extension of the Pais-Uhlenbeck oscillator for a particular choice of its frequencies. Coordinate transformations which link the models have been constructed.

In this work we made the first step towards investigating mechanical systems exhibiting $\mathcal{N} = 2$ $l$-conformal Galilei supersymmetry. We hope that further developments will demonstrate advantages of supersymmetric $l$-conformal theories. The first issue to mention is that the integrals of motion $K_{-1}, G_{\frac{1}{2}}$ and $\bar{G}_{\frac{1}{2}}$ for the models (15) and (16) obey the structure relations

$$\{G_{\frac{1}{2}}, \bar{G}_{\frac{1}{2}}\} = 2i \left( H - \frac{1}{R} J \right), \quad [H, G_{\frac{1}{2}}] = i \frac{R}{J} G_{\frac{1}{2}}, \quad [H, \bar{G}_{\frac{1}{2}}] = -i \frac{R}{J} \bar{G}_{\frac{1}{2}}.$$

It would be interesting to modify the realizations constructed above so as to bring the structure relations to the standard form. This issue will be studied elsewhere. Another interesting problem to tackle is to construct dynamical realizations of $\mathcal{N} = 2$ $l$-conformal Galilei superalgebra without higher-derivatives. It is also worth generalizing the results in [11], [29] to incorporate $\mathcal{N} = 2$ supersymmetry. Investigation of $l$-conformal Galilei superalgebras for $\mathcal{N} > 2$ and construction of their dynamical realizations may potentially raise many interesting issues. In this context it would be interesting to construct $l$-conformal extensions of the systems obtained recently in [75] and the superparticles with rigidity in [76, 77].

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Appendix A. Higher-derivative superparticle action from nonlinear realization

Let us apply the method of nonlinear realizations [70, 71] to the subalgebra which is formed by the generator of time translations together with all the vector generators and the
central charge $M$. The left multiplication by a subgroup element
\[ e^{aK_1}e^{n(n)}C_i^{(n)}e^{i\epsilon_i^{(n)}L_i^{(n)}+i\epsilon_i^{(n)}L_i^{(n)}}e^{b_i^{(n)}P_i^{(n)}}e^{\phi M} \]
determines the action on the space
\[ G = e^{tK_1}e^{n(n)}C_i^{(n)}e^{i\psi_i^{(n)}L_i^{(n)}+i\tilde{\psi}_i^{(n)}L_i^{(n)}}e^{z_i^{(n)}P_i^{(n)}}e^{\varphi M} \]
parameterized by the even $t$, $x_i^{(n)}$, $z_i^{(n)}$, $\varphi$, and odd $\psi_i^{(n)}$, $\tilde{\psi}_i^{(n)}$ coordinates. Infinitesimal coordinate transformations which correspond to this action read
\[
\begin{align*}
\delta x_i^{(n)} &= \sum_{k=0}^{2l} \frac{(-1)^{n+k}}{n!(k-n)!} t^{k-n} a_i^{(k)}, & \delta \psi_i^{(n)} &= \sum_{k=n}^{2l-1} \frac{(-1)^{n+k}}{n!(k-n)!} t^{k-n} \xi_i^{(k)}, \\
\delta \tilde{\psi}_i^{(n)} &= \sum_{k=n}^{2l-1} \frac{(-1)^{n+k}}{n!(k-n)!} t^{k-n} \bar{\xi}_i^{(k)}, & \delta z_i^{(n)} &= \sum_{k=n}^{2l-2\gamma} \frac{(-1)^{n+k}}{n!(k-n)!} t^{k-n} b_i^{(k)}, \\
\delta t &= a, & \delta \varphi &= \phi + \sum_{k=0}^{2l-1} \sum_{n=0}^{2l} \psi_{i,0}^{n} t^{k-n} a_i^{(k)} \lambda_{ij} \psi_j^{(2l-n)} + i \sum_{k=0}^{2l-1} \sum_{n=0}^{2l-1} \psi_{i,1}^{n} t^{k-n} \xi_i^{(k)} \lambda_{ij} \tilde{\psi}_j^{(2l-n-1)} + \\
&+ i \sum_{k=0}^{2l-1} \sum_{n=0}^{2l-1} \psi_{i,1}^{n} t^{k-n} \bar{\xi}_i^{(k)} \lambda_{ij} \tilde{\psi}_j^{(2l-n-1)} + (-1)^{\gamma} \sum_{k=0}^{2l-2\gamma} \sum_{n=0}^{2l-2\gamma} \psi_{i,2\gamma}^{n} t^{k-n} b_i^{(k)} \lambda_{ij} z_j^{(2l-2\gamma-n)},
\end{align*}
\]
where we denoted
\[ v_{n,s}^{k} = (-1)^{k} \frac{k!(2l-n-s)!}{2(k-n)!}. \]
The generators of these transformations form the subalgebra of $\mathcal{N} = 2$ $l$-conformal Galilei superalgebra (2), (4), (5) which involve $K_1$, $C_i^{(n)}$, $L_i^{(n)}$, $L_i^{(n)}$, $P_i^{(n)}$ and $M$.

Then let us construct the left-invariant Maurer-Cartan one-forms
\[ G^{-1}dG = \omega_{K_1} + \omega_{C_i}^{(n)}C_i^{(n)} + i \omega_{L_i}^{(n)}L_i^{(n)} + i \omega_{L_i}^{(n)}L_i^{(n)} + \omega_{P_i}^{(n)}P_i^{(n)} + \omega_M^{(n)}M, \]
where\(^2\)
\[
\begin{align*}
\omega_{C_i}^{(n)} &= dx_i^{(n)} + (n+1)x_i^{(n+1)}dt, & \omega_{L_i}^{(n)} &= d\psi_i^{(n)} + (n+1)\psi_i^{(n+1)}dt, \\
\omega_{L_i}^{(n)} &= d\bar{\psi}_i^{(n)} + (n+1)\bar{\psi}_i^{(n+1)}dt, & \omega_{P_i}^{(n)} &= dz_i^{(n)} + (n+1)z_i^{(n+1)}dt, \\
\omega_K &= dt, & \omega_M &= d\varphi + \sum_{n=0}^{2l} v_{n,0}^{n} \omega_{C_i}^{(n)} \lambda_{ij} x_j^{(2l-n)} + i \sum_{n=0}^{2l-1} v_{n,1}^{n} \omega_{L_i}^{(n)} \lambda_{ij} \tilde{\psi}_j^{(2l-n-1)} + \\
&+ i \sum_{n=0}^{2l-1} v_{n,1}^{n} \omega_{L_i}^{(n)} \lambda_{ij} \tilde{\psi}_j^{(2l-n-1)} + (-1)^{\gamma} \sum_{n=0}^{2l-2\gamma} v_{n,2\gamma}^{n} \omega_{P_i}^{(n)} \lambda_{ij} z_j^{(2l-2\gamma-n)},
\end{align*}
\]
\(^2\)By definition $x_i^{(2l+1)} = \psi_i^{(2l)} = \tilde{\psi}_i^{(2l)} = z_i^{(2l-2\gamma+1)} = 0$. 

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By construction, these forms are invariant under all the transformations (A1).

Some degrees of freedom can be reduced by setting some of the one-forms to vanish [78]. If we take \( t \) to be a temporal coordinate, then the restrictions
\[
\omega^{(n)}_{C,i} = 0, \quad \omega^{(n)}_{L,i} = 0, \quad \omega^{(n)}_{\bar{L},i} = 0, \quad \omega^{(n)}_{P,i} = 0,
\]
will provide constraints
\[
y^{(n)}_i = \frac{(-1)^n}{n!} \frac{d^n y^{(0)}_i}{dt^n}, \quad y^{(n)}_i = x^{(n)}_i, \quad \psi^{(n)}_i, \quad \bar{\psi}^{(n)}_i, \quad z^{(n)}_i,
\]

as well as the equations of motion for the dynamical variables
\[
x^{(n)}_i \equiv x^{(0)}_i, \quad \psi^{(n)}_i \equiv \psi^{(0)}_i, \quad \bar{\psi}^{(n)}_i \equiv \bar{\psi}^{(0)}_i, \quad z^{(n)}_i \equiv z^{(0)}_i,
\]

\[
\frac{d^{2l+1}x^{(n)}_i}{dt^{2l+1}} = 0, \quad \frac{d^{2l}\psi^{(n)}_i}{dt^{2l}} = 0, \quad \frac{d^{2l}\bar{\psi}^{(n)}_i}{dt^{2l}} = 0, \quad \frac{d^{2l-2\gamma+1}z^{(n)}_i}{dt^{2l-2\gamma+1}} = 0.
\]

The action functional which corresponds to these equations has the form
\[
S = \frac{1}{2} \int dt \lambda_{ij} \left( x^{(n)}_i \frac{d^{2l+1}x^{(n)}_j}{dt^{2l+1}} - i\psi^{(n)}_i \frac{d^{2l}\psi^{(n)}_j}{dt^{2l}} - i\bar{\psi}^{(n)}_i \frac{d^{2l}\bar{\psi}^{(n)}_j}{dt^{2l}} + (-1)^\gamma z^{(n)}_i \frac{d^{2l-2\gamma+1}z^{(n)}_j}{dt^{2l-2\gamma+1}} \right).
\]

This can be obtained from the one-form \( \omega_M \) by taking into account (A2). In accord with (A1) this action is invariant under the transformations
\[
\delta t = a, \quad \delta x^{(n)}_i = \sum_{n=0}^{2l} \tilde{\alpha}^{(n)}_i t^n, \quad \delta \psi^{(n)}_i = \sum_{n=0}^{2l-1} \tilde{\zeta}^{(n)}_i t^n, \quad \delta \bar{\psi}^{(n)}_i = \sum_{n=0}^{2l-1} \tilde{\bar{\zeta}}^{(n)}_i t^n, \quad \delta z^{(n)}_i = \sum_{n=0}^{2l-2\gamma} \tilde{b}^{(n)}_i t^n,
\]

where \( \tilde{\alpha}^{(n)}_i = (-1)^n \alpha^{(n)}_i \) and \( \alpha^{(n)}_i = \{a^{(n)}_i, \xi^{(n)}_i, \tilde{\xi}^{(n)}_i, b^{(n)}_i\} \).

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