ROBUST EXPONENTIAL ATTRACTORS FOR COLEMAN–GURTIN EQUATIONS WITH DYNAMIC BOUNDARY CONDITIONS POSSESSING MEMORY

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ABSTRACT. The well-posedness of a generalized Coleman–Gurtin equation equipped with dynamic boundary conditions with memory was recently established by the author with C.G. Gal. In this article we report advances concerning the asymptotic behavior and stability of this heat transfer model. For the model under consideration, we obtain a family of exponential attractors that is robust/Hölder continuous with respect to a perturbation parameter occurring in a singularly perturbed memory kernel. We show that the basin of attraction of these exponential attractors is the entire phase space. The existence of (finite dimensional) global attractors follows. The results are obtained by assuming the nonlinear terms defined on the interior of the domain and on the boundary satisfy standard dissipation assumptions. Also, we work under a crucial assumption that dictates the memory response in the interior of the domain matches that on the boundary.

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1. INTRODUCTION TO THE MODEL PROBLEM

In the framework of [23], let us only consider a thermodynamic process based on heat conduction. Suppose that a bounded domain Ω ⊂ R^n, n ≥ 1, is occupied by a body which may be inhomogeneous, but has a configuration constant in time. Thermodynamic processes taking place inside Ω, with sources also present at the boundary Γ, give rise to the following model for the temperature field u:

\[
\frac{\partial u}{\partial t} - \omega \Delta u - (1 - \omega) \int_0^\infty k(s) \Delta u(x, t - s) ds + f(u) + \alpha (1 - \omega) \int_0^\infty k(s) u(x, t - s) ds = 0,
\]

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in $\Omega \times (0, \infty)$, subject to the following boundary condition:

$$\begin{align*}
\partial_t u - \omega \Delta u + \omega \partial_n u + (1 - \omega) \int_0^\infty k(s) \partial_n u(x, t - s) \, ds \\
+ (1 - \omega) \int_0^\infty k(s)(-\Delta u + \beta)u(x, t - s) \, ds + g(u) = 0,
\end{align*}$$

(1.2)

on $\Gamma \times (0, \infty)$, for every $\alpha \geq 0$, $\beta \geq 0$, $\omega \in [0, 1)$, and where $k : [0, \infty) \to \mathbb{R}$ is a continuous nonnegative function, smooth on $(0, \infty)$, vanishing at infinity and satisfying the relation

$$\int_0^\infty k(s) \, ds = 1,$$

$\partial_n$ represents the normal derivative and $-\Delta$ is the Laplace-Beltrami operator. The cases $\omega = 0$ and $\omega > 0$ in (1.1) are usually referred as the Gurtin–Pipkin and the Coleman–Gurtin models, respectively. The literature contains a full treatment of equation (1.1) only in the case of standard boundary conditions (Dirichlet, Neumann and periodic boundary conditions). In light of new results and extensions for the phase field equations (see, e.g., [2] [16] and references therein), we must consider more general dynamic boundary conditions. In particular, we quote [22].

In most works, the equations are endowed with Neumann boundary conditions for both [unknowns] $u$ and $w$ (which means that the interface is orthogonal to the boundary and that there is no mass flux at the boundary) or with periodic boundary conditions. Now, recently, physicists have introduced the so-called dynamic boundary conditions, in the sense that the kinetics, i.e., $\partial_t u$, appears explicitly in the boundary conditions, in order to account for the interaction of the components with the walls for a confined system.

The derivation of (1.2) in the context of (1.1) can be derived in a similar fashion as in [15, 25] exploiting first and second laws of thermodynamics. Let $\omega \in [0, 1)$ be fixed. It is clear that if we (formally) choose $k = \delta_0$ (the Dirac mass at zero), equations (1.1), (1.2) turn into the following system:

$$\begin{align*}
\partial_t u - \Delta u + f(u) + \alpha(1 - \omega) u = 0, & \quad \text{in } \Omega \times (0, \infty), \\
\partial_t u - \Delta u + \partial_n u + g(u) + \beta(1 - \omega) u = 0, & \quad \text{on } \Gamma \times (0, \infty).
\end{align*}$$

(1.3), (1.4)

The latter has been investigated quite extensively recently in many contexts (i.e., phase-field systems, heat conduction with a source at $\Gamma$, Stefan problems, etc).

Now we define, for $\varepsilon \in (0, 1]$,

$$k_\varepsilon(s) = \frac{1}{\varepsilon} k \left( \frac{s}{\varepsilon} \right),$$

and we consider the same family of equations (1.1)-(1.2), replacing $k$ with $k_\varepsilon$. Thus, $k_\varepsilon \to \delta_0$ when $\varepsilon \to 0$. Our goal is to show in what sense does the system (1.1), (1.2) converge to (1.3), (1.4) as $\varepsilon \to 0$.

Such results seem to have begun with the hyperbolic relaxation of a Chaffee–Infante reaction diffusion equation in [25]. The motivation for such a hyperbolic relaxation is similar to the motivation for applying a memory relaxation; it alleviates the parabolic problems from the sometimes unwanted property of “infinite speed of propagation”. In [25], however, Hale and Raugel proved the existence of a family of global attractors that is upper-semicontinuous in the phase space. A global attractor is a unique compact invariant subset of the phase space that attracts all trajectories of the associated dynamical system, even at arbitrarily slow rates (cf. [29] and [36] Theorem 14.6). In a sense which will become clearer below, upper-semicontinuity guarantees the attractors to not “blow-up” as the perturbation parameter vanishes; i.e.,

$$\sup_{x \in A_\varepsilon} \inf_{y \in A_0} \|x - y\|_{X_\varepsilon} \to 0 \quad \text{as} \quad \varepsilon \to 0^+.$$
formal integration by parts into (1.1)-(1.2) yields

\[ \| S_\varepsilon(t)x - L S_0(t)\Pi x\|_{X_\varepsilon} \leq C \varepsilon^p, \]  

(1.5)

for all \( t \) in some interval, where \( x \in X_\varepsilon, S_\varepsilon(t) : X_\varepsilon \to X_\varepsilon \) and \( S_0(t) : X_0 \to X_0 \) are semigroups generated by the solutions of the perturbed problem and the limit problem, respectively, \( \Pi \) denotes a projection from \( X_\varepsilon \) onto \( X_0 \) and \( L \) is a “lift” from \( X_0 \) into \( X_\varepsilon \), and finally \( C, p > 0 \) are constants. Controlling this difference in a suitable norm is crucial to obtaining our continuity results (see (C5) in Proposition 3.24). The estimate \( \| \| \) means we can approximate the limit problem with the perturbation with control explicitly written in terms of the perturbation parameter. Usually such control is only exhibited on compact time intervals. Observe, a result of this type will ensure that for every problem of type (1.3)-(1.4), there is an “memory relaxation” of the form (1.1)-(1.2) close by in the sense that the difference of corresponding trajectories satisfies (1.5).

We carefully treat the following issues:

1: Well-posedness of the system comprising of equations (1.1)-(1.2) and (1.3)-(1.4).
2: Dissipation: the existence of bounded absorbing set, and a compact absorbing set, each of which is uniform with respect to the perturbation parameter \( \varepsilon \).
3: Stability: existence of a family of exponential attractors for each \( \varepsilon \in [0, 1] \) and an analysis of the continuity properties (robustness/Hölder) with respect to \( \varepsilon \).
4: The basin of attraction for each exponential attractor is the entire phase space, and in demonstrating this result we see that the semigroup of solution operators also admits a family of global attractors.

Concerning Issue 1, the well-posedness for a more general system, which includes the one above, was given recently by [17]. The relevant results from that work are cited below in Section 2. In this article we explore Issues 2, 3, and 4 in much more depth; in particular, the existence of an exponential attractor for each \( \varepsilon \in [0, 1] \), and the continuity of these attractors with respect to \( \varepsilon \).

As is now customary (cf. [3, 6, 7, 27]) we introduce the so-called integrated past history of \( u \), i.e., the auxiliary variable

\[ \eta^t(x, s) = \int_0^s u(x, t - y)dy, \]

for \( s, t > 0 \). Setting

\[ \mu(s) = -(1 - \omega)k^t(s), \]

formal integration by parts into (1.1)-(1.2) yields

\[ (1 - \omega) \int_0^\infty k_\varepsilon(s)\Delta u(x, t - s)ds = \int_0^\infty \mu_\varepsilon(s)\Delta \eta^t(x, s)ds, \]

\[ (1 - \omega) \int_0^\infty k_\varepsilon(s)u(x, t - s)ds = \int_0^\infty \mu_\varepsilon(s)\eta^t(x, s)ds, \]

\[ (1 - \omega) \int_0^\infty k_\varepsilon(s)\partial_n u(x, t - s)ds = \int_0^\infty \mu_\varepsilon(s)\partial_n \eta^t(x, s)ds, \]

and

\[ (1 - \omega) \int_0^\infty k_\varepsilon(s)(-\Delta \Gamma + \beta) u(x, t - s)ds = \int_0^\infty \mu_\varepsilon(s)(-\Delta \Gamma + \beta) \eta^t(x, s)ds. \]

where

\[ \mu_\varepsilon(s) = \frac{1}{\varepsilon^2} \mu \left( \frac{s}{\varepsilon} \right). \]

(1.6)
For each $\varepsilon \in (0, 1]$, the (perturbation) problem under consideration can now be stated.

**Problem $P_\varepsilon$.** Let $\alpha, \beta \geq 0$, and $\omega \in (0, 1)$. Find a function $(u, \eta)$ such that
\[
\partial_t u - \omega \Delta u - \int_0^\infty \mu_\varepsilon(s) \Delta \eta^\varepsilon(s) ds + \alpha \int_0^\infty \mu_\varepsilon(s) \eta^\varepsilon(s) ds + f(u) = 0
\]
in $\Omega \times (0, \infty)$, subject to the boundary conditions
\[
\partial_t u - \omega \Delta_\Gamma u + \omega \partial_\nu u + \int_0^\infty \mu_\varepsilon(s) \partial_t \eta^\varepsilon(s) ds + \int_0^\infty \mu_\varepsilon(s) (-\Delta_\Gamma + \beta) \eta^\varepsilon(s) ds + g(u) = 0
\]
on $\Gamma \times (0, \infty)$, and
\[
\partial_t \eta^\varepsilon(s) + \partial_s \eta^\varepsilon(s) = u(t) \quad \text{in} \quad \overline{\Omega} \times (0, \infty),
\]
with
\[
\eta^\varepsilon(0) = 0 \quad \text{in} \quad \overline{\Omega} \times (0, \infty),
\]
and the initial conditions
\[
u(0) = u_0 \quad \text{in} \quad \Omega, \quad u(0) = v_0 \quad \text{on} \quad \Gamma,
\]
\[
\eta^\varepsilon(0) = \eta_0 := \int_0^s u_0(x, -y) dy \quad \text{in} \quad \Omega, \quad \text{for} \quad s > 0,
\]
and
\[
\eta^\varepsilon(0) = \xi_0 := \int_0^s v_0(x, -y) dy \quad \text{on} \quad \Gamma, \quad \text{for} \quad s > 0.
\]

We will also discuss the problem corresponding to $\varepsilon = 0$. The results for this problem may already be found in works in parabolic equations and the Wentzell Laplacian (see [12, 13, 14]). The singular (limit) problem is

**Problem $P_0$.** Let $\alpha, \beta \geq 0$ and $\omega \in (0, 1)$. Find a function $u$ such that
\[
\partial_t u - \Delta u + f(u) + \alpha(1 - \omega)u = 0
\]
in $\Omega \times (0, \infty)$, subject to the boundary conditions
\[
\partial_t u - \Delta_\Gamma u + \partial_\nu u + g(u) + \beta(1 - \omega)u = 0
\]
on $\Gamma \times (0, \infty)$, with the initial conditions
\[
u(0) = u_0 \quad \text{in} \quad \Omega \quad \text{and} \quad u(0) = v_0 \quad \text{on} \quad \Gamma.
\]

Remark 1.1. It need not be the case that the boundary traces of $u_0$ and $\eta_0$ be equal to $v_0$ and $\xi_0$, respectively. Thus, we are solving a much more general problem in which equation (1.7) is interpreted as an evolution equation in the bulk $\Omega$ properly coupled with the equation (1.9) on the boundary $\Gamma$. Finally, from now on both $\eta_0$ and $\xi_0$ will be regarded as independent of the initial data $u_0$ and $v_0$. Indeed, below we will consider a more general problem with respect to the original one. This will require a rigorous notion of solution to Problem $P_\varepsilon$ (cf. Definitions 2.1, 2.4), hence we introduce the functional setting associated with this system.

Here below is the framework used to prove Hadamard well-posedness for Problem $P_\varepsilon$. Consider the space $X^2 := L^2(\overline{\Omega}, d\mu)$, where
\[
d\mu = dx|_{\Omega} \oplus d\sigma,
\]
where $dx$ denotes the Lebesgue measure on $\Omega$ and $d\sigma$ denotes the natural surface measure on $\Gamma$. It is easy to see that $X^2 = L^2(\Omega, dx) \oplus L^2(\Gamma, d\sigma)$ may be identified under the natural norm
\[
\|u\|_{X^2}^2 = \int_\Omega |u|^2 dx + \int_\Gamma |u|^2 d\sigma.
\]
Moreover, if we identify every $u \in C(\overline{\Omega})$ with $U = (u|_{\Omega}, u|_{\Gamma}) \in C(\Omega) \times C(\Gamma)$, we may also define $X^2$ to be the completion of $C(\overline{\Omega})$ in the norm $\| \cdot \|_{X^2}$. In general, any function $u \in X^2$ will be of the form $u = (u_1, u_2)$ with $u_1 \in L^2(\Omega, dx)$ and $u_2 \in L^2(\Gamma, d\sigma)$, and there need not be any connection between $u_1$ and $u_2$. From now on, the inner product in the Hilbert space $X^2$ will be denoted by $\langle \cdot, \cdot \rangle_{X^2}$. Hereafter, the spaces $L^2(\Omega, dx)$ and $L^2(\Gamma, d\sigma)$ will simply be denoted by $L^2(\Omega)$ and $L^2(\Gamma)$. 
Recall that the Dirichlet trace map \( \text{tr}_D : C^\infty(\overline{\Omega}) \rightarrow C^\infty(\Gamma) \), defined by \( \text{tr}_D(u) = u|\Gamma \) extends to a linear continuous operator \( \text{tr}_D : H^r(\Omega) \rightarrow H^{r-1/2}(\Gamma) \), for all \( r > 1/2 \), which is onto for \( 1/2 < r < 3/2 \). This map also possesses a bounded right inverse \( \text{tr}_D^{-1} : H^{r-1/2}(\Gamma) \rightarrow H^r(\Omega) \) such that \( \text{tr}_D(\text{tr}_D^{-1}\psi) = \psi \), for any \( \psi \in H^{r-1/2}(\Gamma) \). We can thus introduce the subspaces of \( H^r(\Omega) \times H^r(\Gamma) \),

\[
\mathcal{V}^r := \{(u, \psi) \in H^r(\Omega) \times H^r(\Gamma) : \text{tr}_D(u) = \psi\},
\]

for every \( r > 1/2 \), and note that we have the following dense and compact embeddings \( \mathcal{V}^{r_1} \hookrightarrow \mathcal{V}^{r_2} \), for any \( r_1 > r_2 > 1/2 \). Finally, we think of \( \mathcal{V}^1 \simeq H^1(\Omega) \oplus H^1(\Gamma) \) as the completion of \( C^1(\overline{\Omega}) \) in the norm

\[
||u||_{\mathcal{V}^r}^2 := \int_\Omega \left(|\nabla u|^2 + \alpha |u|^2\right) dx + \int_\Gamma \left(|\nabla \Gamma u|^2 + \beta |u|^2\right) d\sigma
\]

(or some other equivalent norm in \( H^1(\Omega) \times H^1(\Gamma) \)). Naturally, the norm on the space \( \mathcal{V}^r \) is defined as

\[
||u||_{\mathcal{V}^r}^2 := ||u||_{H^r(\Omega)}^2 + ||u||_{H^r(\Gamma)}^2.
\]

For \( U = (u, u|\Gamma) \in \mathcal{V}^1 \), let \( C_\Omega > 0 \) denote the best constant in which the Sobolev-Poincaré inequality holds

\[
||u - (u)|_L^{\infty}(\Omega) \leq C_\Omega ||\nabla u||_{L^\infty}(\Omega),
\]

for \( s \geq 1 \) (see [37 Lemma 3.1]). Here

\[
(u)_\Gamma := \frac{1}{|\Gamma|} \int_\Gamma u|_\Gamma d\sigma.
\]

Let us now introduce the spaces for the memory variable \( \eta \). For a nonnegative measurable function \( \theta \) defined on \( \mathbb{R}_+ \) and a real Hilbert space \( W \) (with inner product denoted by \( \langle \cdot, \cdot \rangle_W \)), let \( L^2_\mu(\mathbb{R}_+; W) \) be the Hilbert space of \( W \)-valued functions on \( \mathbb{R}_+ \), endowed with the following inner product

\[
\langle \phi_1, \phi_2 \rangle_{L^2_\mu(\mathbb{R}_+; W)} := \int_0^\infty \theta(s) \langle \phi_1(s), \phi_2(s) \rangle_W ds.
\]

Consequently, for \( r > 1/2 \) we set

\[
\mathcal{M}^r_\varepsilon := \begin{cases} 
L^2_\mu(\mathbb{R}_+, \mathcal{V}^r) & \text{for } \varepsilon \in (0, 1], \\
\{0\} & \text{when } \varepsilon = 0,
\end{cases}
\]

and when \( r = 0 \) set

\[
\mathcal{M}^0_\varepsilon := \begin{cases} 
L^2_\mu(\mathbb{R}_+, \mathcal{X}^2) & \text{for } \varepsilon \in (0, 1], \\
\{0\} & \text{when } \varepsilon = 0.
\end{cases}
\]

One can see from [21 Lemma 5.1] that for \( \varepsilon_1 \geq \varepsilon_2 > 0 \) and for fixed \( r = 0 \) or \( r > 1/2 \), there holds the continuous embedding \( \mathcal{M}^r_{\varepsilon_1} \hookrightarrow \mathcal{M}^r_{\varepsilon_2} \). As a matter of convenience, the inner-product in \( \mathcal{M}^r_{\varepsilon} \) is given by

\[
\left\langle \begin{pmatrix} \eta_1 \\ \xi_1 \end{pmatrix}, \begin{pmatrix} \eta_2 \\ \xi_2 \end{pmatrix} \right\rangle_{\mathcal{M}^r_{\varepsilon}} := \int_0^\infty \mu(s) \left( |\nabla \eta_1(s)|_{L^2(\Omega)}^2 + \alpha \langle \eta_1(s), \eta(s) \rangle_{L^2(\Omega)} \right) ds \\
+ \int_0^\infty \mu(s) \left( |\nabla \Gamma \xi_1(s)|_{L^2(\Gamma)}^2 + \beta \langle \xi_1(s), \xi(s) \rangle_{L^2(\Gamma)} \right) ds.
\]

When it is convenient, we will use the notation

\[
\mathcal{H}^0_{\varepsilon} := \mathcal{X}^2 \times \mathcal{M}^1_{\varepsilon} \quad \text{and} \quad \mathcal{H}^2_{\varepsilon} := \mathcal{V}^1 \times \mathcal{M}^2_{\varepsilon}.
\]

Each space is equipped with the corresponding “graph norm,” whose square is defined by, for all \( \varepsilon \in [0, 1] \) and \( (U, \Phi) \in \mathcal{H}^r_{\varepsilon}, i = 0, 1, \)

\[
|||U, \Phi|||^2_{\mathcal{H}^0_{\varepsilon}} := ||U||^2_{\mathcal{X}^2} + ||\Phi||^2_{\mathcal{M}^1_{\varepsilon}} \quad \text{and} \quad |||U, \Phi|||^2_{\mathcal{H}^2_{\varepsilon}} := ||U||^2_{\mathcal{V}^1} + ||\Phi||^2_{\mathcal{M}^2_{\varepsilon}}.
\]
For the kernel $\mu$, we take the following assumptions (cf. e.g. \[23, 21\]). Assume

$$\mu \in C^1(\mathbb{R}_+) \cap L^1(\mathbb{R}_+),$$ \hspace{1cm} (1.23)

$$\mu(s) \geq 0 \text{ for all } s \geq 0,$$ \hspace{1cm} (1.24)

$$\mu'(s) \leq 0 \text{ for all } s \geq 0,$$ \hspace{1cm} (1.25)

$$\mu'(s) + \delta \mu(s) \leq 0 \text{ for all } s \geq 0 \text{ and some } \delta > 0.$$ \hspace{1cm} (1.26)

The assumptions (1.23)-(1.25) are equivalent to assuming $k(s)$ be a bounded, positive, nonincreasing, convex function of class $C^2$. Moreover, assumption (1.26) guarantees exponential decay of the function $\mu(s)$ while allowing a singularity at $s = 0$. Assumptions (1.23)-(1.25) are used in the literature (see \[3, 7, 23, 27\] for example) to establish the existence and uniqueness of continuous global weak solutions to a system of equations similar to (1.7), (1.9), but with Dirichlet boundary conditions. In the literature, assumption (1.26) is used to obtain a bounded absorbing set for the associated semigroup of solution operators.

For each $\varepsilon \in (0, 1]$, define

$$D(T_\varepsilon) = \{ \Phi \in \mathcal{M}^1_\varepsilon : \partial_s \Phi \in \mathcal{M}^1_\varepsilon, \Phi(0) = 0 \}$$ \hspace{1cm} (1.27)

where (with an abuse of notation) $\partial_s \Phi$ is the distributional derivative of $\Phi$ and the equality $\Phi(0) = 0$ is meant in the following sense

$$\lim_{s \to 0} \| \Phi(s) \|_{\mathcal{X}^2} = 0.$$ \hspace{1cm}

Then define the linear (unbounded) operator $T_\varepsilon : D(T_\varepsilon) \to \mathcal{M}^1_\varepsilon$ by, for all $\Phi \in D(T_\varepsilon)$,

$$T_\varepsilon \Phi = -\frac{d}{ds} \Phi.$$ \hspace{1cm}

For each $t \in [0, T]$, the equation

$$\partial_t \Phi^t = T_\varepsilon \Phi^t + U(t)$$ \hspace{1cm} (1.28)

holds as an ODE in $\mathcal{M}^1_\varepsilon$ subject to the initial condition

$$\Phi^0 = \Phi_0 \in \mathcal{M}^1_\varepsilon.$$ \hspace{1cm} (1.29)

Concerning the solution to the IVP (1.28)-(1.29), we have the following proposition. The result is a generalization of [27, Theorem 3.1].

**Proposition 1.2.** For each $\varepsilon \in (0, 1]$, the operator $T_\varepsilon$ with domain $D(T_\varepsilon)$ is an infinitesimal generator of a strongly continuous semigroup of contractions on $\mathcal{M}^1_\varepsilon$, denoted $e^{T_\varepsilon t}$.

We now have (cf. e.g. [35, Corollary IV.2.2]).

**Corollary 1.3.** When $U \in L^1([0, T]; \mathcal{V}^1)$ for each $T > 0$, then, for every $\Phi_0 \in \mathcal{M}^1_\varepsilon$, the Cauchy problem

$$\begin{cases} 
\partial_t \Phi^t = T_\varepsilon \Phi^t + U(t), \quad \text{for } t > 0, \\
\Phi^0 = \Phi_0, 
\end{cases}$$ \hspace{1cm} (1.30)

has a unique solution $\Phi \in C([0, T]; \mathcal{M}^1_\varepsilon)$ which can be explicitly given as (cf. [7, Section 3.2] and [27, Section 3])

$$\Phi^t(s) = \begin{cases} 
\int_0^s U(t-y)dy, & \text{for } 0 < s \leq t, \\
\Phi_0(s-t) + \int_0^t U(t-y)dy, & \text{when } s > t.
\end{cases}$$ \hspace{1cm} (1.31)

(The interested reader can also see [7, Section 3], [23, pp. 346–347] and [27, Section 3] for more details concerning the case with static boundary conditions.)

Furthermore, we also know that, for each $\varepsilon \in (0, 1]$, $T_\varepsilon$ is the infinitesimal generator of a strongly continuous (the right-translation) semigroup of contractions on $\mathcal{M}^1_\varepsilon$ satisfying (1.32) below; in particular, $\text{Range}(I - T_\varepsilon) = \mathcal{M}^1_\varepsilon$.

Following (1.20), there is the useful inequality. (Also see [7, see equation (3.4)] and [27, Section 3, proof of Theorem].)
Corollary 1.4. There holds, for all $\Phi \in D(T_\varepsilon)$,

$$\langle T_\varepsilon \Phi, \Phi \rangle_{M^1_\varepsilon} \leq -\frac{\delta}{2\varepsilon} \|\Phi\|_{M^1_\varepsilon}^2.$$  \hspace{1cm} (1.32)

Even though the embedding $V^1 \hookrightarrow X^2$ is compact, it does not follow that the embedding $M^1_\varepsilon \hookrightarrow M^0_\varepsilon$ is also compact. Indeed, see [24] for a counterexample. Moreover, this means the embedding $H^1_\varepsilon \hookrightarrow H^0_\varepsilon$ is not compact. Such compactness between the “natural phase spaces” is essential to the construction of finite dimensional exponential attractors. To alleviate this issue we follow [7, 21] and define for any $\varepsilon \in (0, 1]$ the so-called tail function of $\Phi \in M^0_\varepsilon$ by, for all $\tau \geq 0$,

$$T_\varepsilon(\tau; \Phi) := \int_{(0,1/\varepsilon) \cup (\tau, \infty)} \varepsilon \mu_\varepsilon(s) \|\Phi(s)\|_{V_\varepsilon}^2 ds,$$

With this we set, for $\varepsilon \in (0, 1]$, 

$$K^2_\varepsilon := \{ \Phi \in M^1_\varepsilon : \partial_s \Phi \in M^0_\varepsilon, \Phi(0) = 0, \sup_{\tau \geq 1} T_\varepsilon(\tau; \Phi) < \infty \}.$$

The space $K^2_\varepsilon$ is Banach with the norm whose square is defined by

$$\|\Phi\|^2_{K^2_\varepsilon} := \|\Phi\|^2_{M^1_\varepsilon} + \varepsilon \|\partial_s \Phi\|^2_{M^0_\varepsilon} + \sup_{\tau \geq 1} \tau T_\varepsilon(\tau; \Phi).$$  \hspace{1cm} (1.33)

When $\varepsilon = 0$, we set $K^2_0 = \{0\}$. Importantly, for each $\varepsilon \in (0, 1]$, the embedding $K^2_\varepsilon \hookrightarrow M^1_\varepsilon$ is compact. (cf. [21] Proposition 5.4)). Hence, let us now also define the space

$$V^1_\varepsilon := V^1 \times K^2_\varepsilon,$$

and the desired compact embedding $V^1_\varepsilon \hookrightarrow H^0_\varepsilon$ holds. Again, each space is equipped with the corresponding graph norm whose square is defined by, for all $\varepsilon \in [0, 1]$ and $(U, \Phi) \in V^1_\varepsilon$,

$$\|(U, \Phi)\|^2_{V^1_\varepsilon} := \|U\|^2_{V^1} + \|\Phi\|^2_{K^2_\varepsilon}.$$

In regards to the system in Corollary 1.3 above, we will also call upon the following simple generalizations of [7] Lemmas 3.3, 3.4, and 3.6].

Lemma 1.5. Let $\varepsilon \in (0, 1]$ and $\Phi_0 \in D(T_\varepsilon)$. Assume there is $\rho > 0$ such that, for all $t \geq 0$, $\|U(t)\|_{V^1} \leq \rho$. Then for all $t \geq 0$,

$$\varepsilon \|T_\varepsilon \Phi_t\|^2_{M^1_\varepsilon} \leq \varepsilon e^{-\delta t} \|T_\varepsilon \Phi_0\|^2_{M^1_\varepsilon} + \rho^2 \|\mu\|_{L^1(\mathbb{R}^+)}.$$

Remark 1.6. The above result will also be needed later in the weaker space $M^0_\varepsilon$ (see Step 3 in the proof of Lemma 3.13). The result for the weaker space can be obtained by suitably transforming (1.30)-(1.31) and applying an appropriate bound on $U$.

Lemma 1.7. Let $\varepsilon \in (0, 1]$ and $\Phi_0 \in D(T_\varepsilon)$. Assume there is $\rho > 0$ such that, for all $t \geq 0$, $\|U(t)\|_{V^1} \leq \rho$. Then there is a constant $C > 0$ such that, for all $t \geq 0$,

$$\sup_{\tau \geq 1} \tau T_\varepsilon(\tau; \Phi_t) \leq 2(t + 2) e^{-\delta t} \sup_{\tau \geq 1} \tau T_\varepsilon(\tau; \Phi_0) + C \rho^2.$$

Finally, we give a version of Lemma 1.7 for compact intervals.

Lemma 1.8. Let $\varepsilon \in (0, 1]$, $T > 0$, and $\Phi_0 \in D(T_\varepsilon)$. Assume there is $\rho > 0$ such that

$$\int_0^T \|U(\tau)\|^2_{V^1} d\tau \leq \rho.$$

Then there is a positive constant $C(T)$ such that, for all $t \in [0, T]$,

$$\sup_{\tau \geq 1} \tau T_\varepsilon(\tau; \Phi_t) \leq C(T) \left( \rho + \sup_{\tau \geq 1} \tau T_\varepsilon(\tau; \Phi_0) \right).$$

We now discuss the linear operator associated with the model problem. In our case it is given by the following (note that in [7] Section 3.1] the basic tool is the Laplacian with Dirichlet boundary conditions; in our case, the analogue operator turns out to be the so-called “Wentzell” Laplace operator).
Proposition 1.9. Let $\Omega$ be a bounded open set of $\mathbb{R}^n$ with Lipschitz boundary $\Gamma$. For $\alpha, \beta \geq 0$, define the operator $A_{W}^{\alpha, \beta}$ on $\mathbb{X}^2$, by

$$A_{W}^{\alpha, \beta} := \begin{pmatrix} -\Delta + \alpha I & 0 \\ \partial_n & -\Delta + \beta I \end{pmatrix},$$

with

$$D\left(A_{W}^{\alpha, \beta}\right) := \left\{ U = (u_1, u_2)^{tr} \in \mathbb{V}^1 : -\Delta u_1 + \alpha u_1 \in L^2(\Omega), \partial_n u_1 - \Delta u_2 + \beta u_2 \in L^2(\Gamma) \right\}.$$

Then, $(A_{W}^{\alpha, \beta}, D(A_{W}^{\alpha, \beta}))$ is self-adjoint and nonnegative operator on $\mathbb{X}^2$ whenever $\alpha, \beta \geq 0$, and $A_{W}^{\alpha, \beta} > 0$ (is strictly positive) if either $\alpha > 0$ or $\beta > 0$. Moreover, the resolvent operator $(1 + A_{W}^{\alpha, \beta})^{-1} \in \mathcal{L}(\mathbb{X}^2)$ is compact. If the boundary $\Gamma$ is of class $C^2$, then $D(A_{W}^{\alpha, \beta}) = \mathbb{V}^2$ (see, e.g., [2, Theorem 2.3]). Indeed, for any $\alpha, \beta \geq 0$, the map $\Psi : U \mapsto A_{W}^{\alpha, \beta}U$, when viewed as a map from $\mathbb{V}^2$ into $\mathbb{X}^2 = L^2(\Omega) \times L^2(\Gamma)$, is an isomorphism, and there exists a positive constant $C_*$, independent of $U = (u, \psi)^{tr}$, such that

$$C_*^{-1}\|U\|_{\mathbb{V}^2} \leq \|\Psi(U)\|_{\mathbb{X}^2} \leq C_*\|U\|_{\mathbb{V}^2},$$

for all $U \in \mathbb{V}^2$ (cf. Lemma A.1).}

We can refer the reader to [1] for an extensive survey of recent results concerning the “Wentzell” Laplacian $A_{W}^{\alpha, \beta}$.

For the nonlinear terms, assume $f, g \in C^1(\mathbb{R})$ satisfy the growth assumptions: there exist positive constants $\ell_1$ and $\ell_2$, and $r_1, r_2 \in [1, \frac{5}{2})$ such that for all $s \in \mathbb{R}$,

$$|f'(s)| \leq \ell_1(1 + |s|^{r_1}),$$

$$|g'(s)| \leq \ell_2(1 + |s|^{r_2}).$$

We also assume there are positive constants $M_f$ and $M_g$ so that for all $s \in \mathbb{R}$,

$$f'(s) > -M_f,$$

$$g'(s) > -M_g.$$

Consequently, (1.39)- (1.40) imply there are $\kappa_i > 0$, $i = 1, 2, 3, 4$, so that for all $s \in \mathbb{R}$,

$$f(s)s \geq -\kappa_1 s^2 - \kappa_2,$$

$$g(s)s \geq -\kappa_3 s^2 - \kappa_4.$$  

Remark 1.10. Observe that here we do not allow for the critical polynomial growth exponent (of 5) which appears in several works with static boundary conditions (cf. e.g., [3, 7]). Indeed, in order for us to obtain a notion of strong solution (see Definition 2.4 below), the arguments in the proof of Theorem 2.6 do not allow for $r_i \geq \frac{5}{2}$, $i = 1, 2$.

We can follow [7, Section 4] or, more precisely [23, 24] to deduce the existence and uniqueness of weak solutions in the above class exploiting both semigroup methods and energy methods in the framework of a Galerkin scheme which can be constructed for problems with dynamic boundary conditions (see, e.g., [2, Theorem 2.3]).

Constants appearing below are independent of $\varepsilon$ and $\omega$, unless specified otherwise, but may depend on various structural parameters such as $\alpha, \beta$, $|\Omega|$, $|\Gamma|$, $\ell_f$ and $\ell_g$, and the constants may even change from line to line. We denote by $Q(\cdot)$ a generic monotonically increasing function. We will use $\|B\|_W := \sup_{\Gamma \in B} \|\mathcal{Y}\|_W$ to denote the “size” of the subset $B$ in the Banach space $W$.

2. Review of well-posedness and regularity

Here we provide some definitions and cite the relevant global well-posedness results concerning Problem $P_{\varepsilon}$. For the remainder of this article we choose to set $n = 3$, which is of course the most relevant physical dimension.

Below we will set $F : \mathbb{R}^2 \to \mathbb{R}^2$,

$$F(U) := \begin{pmatrix} f(u) \\ g(u) \end{pmatrix},$$

(2.1)
where \(\tilde{g}(s) := g(s) - \omega \beta s\), for \(s \in \mathbb{R}\). To offset \(\tilde{g}\), the term \(\omega \beta u\) will be incorporated in the operator \(A_{W}^{0,0}\) as \(A_{W}^{\beta,0}\).

**Definition 2.1.** Let \(\varepsilon \in (0, 1]\), \(\omega \in (0, 1)\) and \(T > 0\). Given \(U_{0} = (u_{0}, v_{0})^{tr} \in X^{2}\) and \(\Phi_{0} = (\eta_{0}, \xi_{0})^{tr} \in \mathcal{M}_{1}^{2}\), the pair \((u(t), v(t))^{tr} = (\Phi^{t})^{tr}\) satisfying
\[
U \in L^{\infty}([0, T]; X^{2}) \cap L^{2}([0, T]; V^{1}),
\]
\[
u \in L^{\infty}(\Omega \times [0, T]),
\]
\[
u \in L^{\infty}(\Gamma \times [0, T]),
\]
\[
\Phi \in L^{\infty}([0, T]; \mathcal{M}_{1}^{2}),
\]
\[
\frac{\partial}{\partial t} U \in L^{2}([0, T]; (V^{1})^{*} \oplus \left(L^{2}(\Omega \times [0, T]) \times L^{2}(\Gamma \times [0, T])\right),
\]
\[
\frac{\partial}{\partial t} \Phi \in L^{2}([0, T]; H^{-1}(\mathbb{R}^{+}; V^{1})),
\]
is said to be a weak solution to Problem \(P_{\varepsilon}\) if, \(v(t) = u_{\mid \Gamma}(t)\) and \(\xi^{t} = \eta_{\mid \Gamma}^{t}\), for almost all \(t \in [0, T]\), and for all \(\Xi = (\xi, \eta^{tr})^{tr} \in V^{1} \cap (L^{2}(\Omega) \times L^{2}(\Gamma))\), \(\Pi = (\rho, \nu^{tr})^{tr} \in \mathcal{M}_{1}^{2}\), and for almost all \(t \in [0, T]\), there holds,
\[
(\frac{\partial}{\partial t} U(t), \Xi)_{X^{2}} + \omega(A_{W}^{0,\beta} U(t), \Xi)_{X^{2}} + \langle \Phi^{t}, \Xi \rangle_{\mathcal{M}_{1}^{2}} + (F(U(t)), \Xi)_{X^{2}} = 0,
\]
\[
(\frac{\partial}{\partial t} \Phi^{t}, \Pi)_{\mathcal{M}_{1}^{2}} = \langle T_{\varepsilon} \Phi^{t}, \Pi \rangle_{\mathcal{M}_{1}^{2}} + \langle U(t), \Pi \rangle_{\mathcal{M}_{1}^{2}},
\]
in addition,
\[
U(0) = U_{0} \quad \text{and} \quad \Phi^{0} = \Phi_{0}.
\]
The function \([0, T] \ni t \mapsto (U(t), \Phi^{t})\) is called a global weak solution if it is a weak solution for every \(T > 0\).

**Remark 2.2.** When we have a weak solution to Problem \(P_{\varepsilon}\), the above restrictions \(u_{\mid \Gamma}(t)\) and \(\eta_{\mid \Gamma}^{t}\) are well-defined by virtue of the Dirichlet trace map, \(\text{tr}_{D} : H^{1}(\Omega) \rightarrow H^{1/2}(\Gamma)\). However, this is not necessarily the case for \(\partial_{t} U\).

**Remark 2.3.** The continuity properties \(U \in C([0, T]; X^{2})\) follow from the classical embedding (cf. e.g. [38, Lemma 5.51]),
\[
\{x \in L^{2}([0, T]; V), \ \partial_{t} x \in L^{2}([0, T]; V')\} \hookrightarrow C([0, T]; H),
\]
where \(H\) and \(V\) are reflexive Banach spaces with continuous embeddings \(V \hookrightarrow H \hookrightarrow V'\), the injection \(V \hookrightarrow H\) being compact.

**Definition 2.4.** The pair \((u(t), v(t))^{tr} = (\Phi^{t})^{tr}\) is called a (global) strong solution of Problem \(P_{\varepsilon}\), if it is a weak solution in the sense of Definition 2.1 and if it satisfies the following regularity properties:
\[
U \in L^{\infty}([0, \infty); V^{1}) \cap L^{2}([0, \infty); V^{2}),
\]
\[
\Phi \in L^{\infty}([0, \infty); \mathcal{M}_{1}^{2}),
\]
\[
\frac{\partial}{\partial t} U \in L^{\infty}([0, \infty); X^{2}) \cap L^{2}([0, \infty); V^{1}),
\]
\[
\frac{\partial}{\partial t} \Phi \in L^{\infty}([0, \infty); \mathcal{M}_{1}^{2}).
\]
Thereupon, \((U(t), \Phi^{t})\) satisfies the equations \((2.8)-(2.9)\) almost everywhere, i.e., is a strong solution.

**Theorem 2.5** (Weak solutions). Assume \((1.22)-(1.23)\) and \((1.37)-(1.40)\) hold. For each \(\varepsilon \in (0, 1]\), \(\omega \in (0, 1)\) and \(T > 0\), and for any \(U_{0} = (u_{0}, v_{0})^{tr} \in X^{2}\) and \(\Phi_{0} = (\eta_{0}, \xi_{0})^{tr} \in \mathcal{M}_{1}^{2}\), there exists a unique (global) weak solution to Problem \(P_{\varepsilon}\) in the sense of Definition 2.1 which depends continuously on the initial data in the following way; there exists a constant \(C > 0\), independent of \(U_{i}, \Phi_{i}, i = 1, 2,\) and \(T > 0\) in which, for all \(t \in [0, T]\), there holds
\[
\|U_{1}(t) - U_{2}(t)\|_{X^{2}} + \|\Phi_{1}^{t} - \Phi_{2}^{t}\|_{\mathcal{M}_{1}^{2}} \leq \left(\|U_{1}(0) - U_{2}(0)\|_{X^{2}} + \|\Phi_{1}^{t} - \Phi_{2}^{t}\|_{\mathcal{M}_{1}^{2}}\right)e^{Ct}.
\]

**Proof.** Cf. [17, Theorem 3.8] for existence and [17, Proposition 3.10] for \((2.15)\). \(\square\)

We conclude the preliminary results for Problem \(P_{\varepsilon}\) with the following...
Theorem 2.6 (Strong solutions). Assume \((1.23)-(1.25)\) and \((1.37)-(1.40)\) hold. For each \(\varepsilon \in (0,1]\), \(\omega \in (0,1)\), and \(T > 0\), and for any \(U_0 = (u_0,v_0)^T \in \mathbb{V}^1\) and \(\Phi_0 = (\eta_0,\xi_0)^T \in \mathcal{M}^2\), there exists a unique (global) strong solution to Problem \(P_{\varepsilon}\) in the sense of Definition 2.4.

Proof. Cf. [17, Theorem 3.11]. \(\square\)

Here we recall some important aspects and relevant results for Problem \(P_0\). The interested reader can also see [13] for further details.

Definition 2.7. Let \(\omega \in (0,1)\) and \(T > 0\). Given \(U_0 = (u_0,v_0)^T \in \mathbb{X}^2\), the pair \(U(t) = (u(t),v(t))^T\) satisfying

\[
U \in L^\infty([0,T];\mathbb{X}^2) \cap L^2([0,T];\mathbb{V}^1),
\]

\[
u \in L^{r_1}(\Omega \times [0,T]),
\]

\[
v \in L^{r_2}(\Gamma \times [0,T]),
\]

\[
\partial_t U \in L^2([0,T];(\mathbb{V}^1)^* \oplus (L^{r_1}(\Omega \times [0,T]) \times L^{r_2}(\Gamma \times [0,T]))),
\]

is said to be a weak solution to Problem \(P_0\) if, \(v(t) = u_{\varepsilon T}(t)\) for almost all \(t \in [0,T]\), and for all \(\Xi = (\zeta,\zeta_T)^T \in \mathbb{V}^1 \cap (L^{r_1}(\Omega) \times L^{r_2}(\Gamma))\), and for almost all \(t \in [0,T]\), there holds,

\[
(\partial_t U(t),\Xi)_{\mathbb{X}^2} + \omega(\Lambda_0^0 U(t),\Xi)_{\mathbb{X}^2} + (F(U(t)),\Xi)_{\mathbb{X}^2} = 0,
\]

with,

\[
U(0) = U_0.
\]

The function \([0,T] \ni t \mapsto U(t)\) is called a global weak solution if it is a weak solution for every \(T > 0\).

We remind the reader of Remark 2.2 on the issue of traces.

We conclude this section with the following.

Theorem 2.8 (Weak solutions). Assume \((1.37)-(1.40)\) hold. For each \(\omega \in (0,1)\) and \(T > 0\), and for any \(U_0 = (u_0,v_0)^T \in \mathbb{X}^2\), there exists a unique (global) weak solution to Problem \(P_0\) in the sense of Definition 2.7, which depends continuously on the initial data as follows: there exists a constant \(C > 0\), independent of \(U_1\) and \(U_2\), and \(T > 0\) in which, for all \(t \in [0,T]\), there holds

\[
\|U_1(t) - U_2(t)\|_{\mathbb{X}^2} \leq \|U_1(0) - U_2(0)\|_{\mathbb{X}^2} e^{Ct}.
\]

Proof. Cf. [13, Theorem 2.2]. \(\square\)

3. Asymptotic behavior and attractors

3.1. Preliminary estimates. Concerning Problem \(P_{\varepsilon}\) and following directly from Theorem 2.6, we have the first preliminary result for this section.

Corollary 3.1. Problem \(P_{\varepsilon}\) defines a (nonlinear) strongly continuous semigroup \(S_{\varepsilon}(t)\) on the phase space \(\mathcal{H}_{0}^{\varepsilon} = \mathbb{X}^2 \times \mathcal{M}^1\) by

\[
S_{\varepsilon}(t)\Upsilon_0 := (U(t),\Phi^t),
\]

where \(\Upsilon_0 = (U_0,\Phi_0) \in \mathcal{H}_{0}^{\varepsilon}\) and \((U(t),\Phi^t)\) is the unique solution to Problem \(P_{\varepsilon}\). The semigroup is Lipschitz continuous on \(\mathcal{H}_{0}^{\varepsilon}\) via the continuous dependence estimate \((2.14)\).

The next preliminary result concerns a uniform bound on the weak solutions. This result follows from an estimate which proves the existence of a bounded absorbing set for the semigroup of solution operators. This result provides a basic but important first step in showing the associated dynamical system is dissipative (cf. e.g. \([1, 39]\)). It is important to note that throughout the remainder of this article, whereby we are now concerned with the asymptotic behavior of the solutions to Problem \(P_{\varepsilon}\) and Problem \(P_0\),

\(A1\): we will assume that \([120]\) holds.

Additionally, we introduce a smallness criteria for certain parameters relating to the linear operator \(\Lambda_0^{\alpha,\beta}\) and the nonlinear map \(F\).
A2: Smallness criteria: Fix \( \varepsilon \in (0,1) \) and \( \omega \in (0,1) \). Denote by \( C_{\mathcal{P}} \) the positive constant that arises from the embedding \( \mathcal{V}^1 \hookrightarrow \mathcal{X}^2 \); i.e., \( \|U\|_{\mathcal{X}^2} \leq C_{\mathcal{P}} \|U\|_{\mathcal{V}^1} \). The smallness criteria is that \( \kappa_1, \kappa_3, \beta > 0 \) (cf. (1.34) and (1.41)-(1.42)) satisfy

\[
\max\{\kappa_1, \kappa_3 + \beta\} < \omega C_{\mathcal{P}}^{-1}.
\]  

(3.1)

As a final note, we remind the reader that all formal multiplication below can be rigorously justified using the Galerkin procedure developed in the proof of Theorem 2.3 of [17].

Lemma 3.2. Let \( \varepsilon \in (0,1) \) and \( \omega \in (0,1) \). In addition to the assumptions of Theorem 2.3, assume (1.26) holds and that \( \kappa_1, \kappa_3, \beta > 0 \) satisfy (3.7). For all \( R > 0 \) and \( \Upsilon_0 = (U_0, \Phi_0) \in \mathcal{H}^0 \) with \( \|\Upsilon_0\|_{\mathcal{H}^0} \leq R \) for all \( \varepsilon \in (0,1) \), there exist positive constants \( \nu_0 = \nu_0(\omega, C_{\mathcal{P}}, \kappa_1, \kappa_3, \beta, \delta) \) and \( P_0 = P_0(\kappa_2, \kappa_4, \nu_0) \), and there is a positive monotonically increasing function \( Q(\cdot) \) each independent of \( \varepsilon \), in which, for all \( t \geq 0 \),

\[
\|(U(t), \Phi^t)\|_{\mathcal{H}^0}^2 \leq Q(R)e^{-\nu_0 t} + P_0.
\]  

Moreover, the set

\[
\mathcal{B}_\varepsilon^0 := \{(U, \Phi) \in \mathcal{H}^0 : \|(U, \Phi)\|_{\mathcal{H}^0} \leq \sqrt{P_0 + 1}\}.
\]  

is absorbing and positively invariant for the semigroup \( S_t \).

Proof. Let \( \varepsilon \in (0,1) \) and \( \omega \in (0,1) \). Let \( \Upsilon_0 = (U_0, \Phi_0) \in \mathcal{H}^0 = \mathcal{X}^2 \times \mathcal{M}_\varepsilon^1 \). From the equations (2.8) and (2.9), we take the corresponding weak solution \( \Xi = U(t) \) and \( \Pi(s) = \Phi^t(s) \). We then obtain the identities

\[
\langle \partial_t U, U \rangle_{\mathcal{X}^2} + \omega \langle A_{W}^{0,\beta} U, U \rangle_{\mathcal{X}^2} + \langle \Phi^t, U \rangle_{\mathcal{M}_\varepsilon^1} + \langle F(U), U \rangle_{\mathcal{X}^2} = 0,
\]  

(3.4)

and

\[
\langle \partial_t \Phi^t, \Phi^t \rangle_{\mathcal{M}_\varepsilon^1} = \langle T_\varepsilon \Phi^t, \Phi^t \rangle_{\mathcal{M}_\varepsilon^1} + \langle U, \Phi^t \rangle_{\mathcal{M}_\varepsilon^1}.
\]  

(3.5)

Observe,

\[
\langle \partial_t U, U \rangle_{\mathcal{X}^2} = \frac{1}{2} \frac{d}{dt} \|U\|_{\mathcal{X}^2}^2,
\]  

(3.6)

and

\[
\langle A_{W}^{0,\beta} U, U \rangle_{\mathcal{X}^2} = \|\nabla u\|_{L^2(\Omega)}^2 + \|\nabla_\Gamma u\|_{L^2(\Gamma)}^2 + \beta \|u\|_{L^2(\Gamma)}^2.
\]  

(3.7)

and

\[
\langle \partial_t \Phi^t, \Phi^t \rangle_{\mathcal{M}_\varepsilon^1} = \frac{1}{2} \frac{d}{dt} \|\Phi^t\|_{\mathcal{M}_\varepsilon^1}^2.
\]  

(3.8)

Combining (3.4)-(3.8) produces the differential identity, which holds for almost all \( t \geq 0 \),

\[
\frac{1}{2} \frac{d}{dt} \left\{ \|U\|_{\mathcal{X}^2}^2 + \|\Phi^t\|_{\mathcal{M}_\varepsilon^1}^2 \right\}
\]  

(3.9)

\[
+ \omega \left( \|\nabla u\|_{L^2(\Omega)}^2 + \|\nabla_\Gamma u\|_{L^2(\Gamma)}^2 + \beta \|u\|_{L^2(\Gamma)}^2 \right)
\]  

- \langle T_\varepsilon \Phi^t, \Phi^t \rangle_{\mathcal{M}_\varepsilon^1} + \langle F(U), U \rangle_{\mathcal{X}^2} = 0.

Because of assumption (1.26), we may directly apply (1.32) from Corollary 1.4 i.e.,

\[
- \langle T_\varepsilon \Phi^t, \Phi^t \rangle_{\mathcal{M}_\varepsilon^1} \geq \frac{\delta}{2\varepsilon} \|\Phi^t\|_{\mathcal{M}_\varepsilon^1}^2.
\]  

(3.10)

With (1.41) and (1.42), we know

\[
\langle F(U), U \rangle_{\mathcal{X}^2} \geq -\kappa_1 \|u\|_{L^2(\Omega)}^2 - (\kappa_3 + \omega \beta) \|u\|_{L^2(\Gamma)}^2 - (\kappa_2 + \kappa_4)
\]  

(3.11)

\[
\geq -\kappa_1 \|u\|_{L^2(\Omega)}^2 - (\kappa_3 + \beta) \|u\|_{L^2(\Gamma)}^2 - (\kappa_2 + \kappa_4)
\]  

\[
= -C_F \|U\|_{\mathcal{X}^2}^2 - (\kappa_2 + \kappa_4),
\]  

where \( C_F := \max\{\kappa_1, \kappa_3 + \beta\} \). Finally, due the embedding \( \mathcal{V}^1 \hookrightarrow \mathcal{X}^2 \), we have

\[
C_{\mathcal{P}}^{-1} \|U\|_{\mathcal{X}^2} \leq \|U\|_{\mathcal{V}^1}.
\]  

(3.12)
for some \( C_{\Omega} > 0 \). Hence, \ref{3.10} \text{-} \ref{3.12} yields the differential inequality (minimizing the left-hand side by setting \( \varepsilon = 1 \)),

\[
\begin{align*}
\frac{d}{dt} \left\{ \|U\|_{X^2}^2 + \|\Phi^t\|_{M^1_\varepsilon}^2 \right\} \\
+ 2 \left( \omega C_{\Omega}^{-1} - C_F \right) \|U\|_{X^2}^2 + \delta \|\Phi^t\|_{M^1_\varepsilon}^2 \\
\leq 2 (\kappa_2 + \kappa_4).
\end{align*}
\]

Thus we arrive at the differential inequality, which holds for almost all \( \tilde{t} \),

\[
\frac{d}{d\tilde{t}} \left\{ \|U\|_{X^2}^2 + \|\Phi^{\tilde{t}}\|_{M^1_\varepsilon}^2 \right\} + m_0 \left( \|U\|_{X^2}^2 + \|\Phi^{\tilde{t}}\|_{M^1_\varepsilon}^2 \right) \\
\leq C.
\]

where \( m_0 := \min\{2(\omega C_{\Omega}^{-1} - C_F), \delta \} > 0 \), and \( C > 0 \) depends only on \( \kappa_2 \) and \( \kappa_4 \). (The absolute continuity of the mapping \( t \mapsto \|U(t)\|_{X^2}^2 + \|\Phi^t\|_{M^1_\varepsilon}^2 \) can be established as in \ref{3.2}, Lemma III.1.1, for example.) After applying a suitable Grönwall inequality, the estimate \ref{3.2} follows with \( \nu_0 = m_0 \) and \( P_0 = \frac{C}{m_0} \); indeed, \ref{3.13} yields, for all \( t \geq 0 \),

\[
\|U(t)\|_{X^2}^2 + \|\Phi^t\|_{M^1_\varepsilon}^2 \\
\leq e^{-m_0 t} \left( \|U_0\|_{X^2}^2 + \|\Phi_0\|_{M^1_\varepsilon}^2 \right) + P_0.
\]

Now we see \ref{3.2} holds for any \( R > 0 \) and \( \Upsilon_0 = (U_0, \Phi_0) \in \mathcal{H}^0 \) such that \( \|\Upsilon_0\|_{\mathcal{H}^0} \leq R \) for all \( \varepsilon \in (0, 1] \).

The existence of the bounded set \( \mathcal{B}_0^\varepsilon \) in \( \mathcal{H}_\varepsilon^0 \) that is absorbing and positively invariant for \( \mathcal{S}_\varepsilon(t) \) follows from \ref{3.13} (cf. e.g. \ref{3.1} Proposition 2.64]). Given any nonempty bounded subset \( B \) in \( \mathcal{H}_\varepsilon^0 \setminus \mathcal{B}_0^\varepsilon \), then we have that \( \mathcal{S}_\varepsilon(t)B \subseteq \mathcal{B}_0^\varepsilon \), in \( \mathcal{H}_\varepsilon^0 \), for all \( t \geq t_0 \) where

\[
t_0 \geq \frac{1}{m_0} \ln \left( \|B\|_{\mathcal{H}^0_{\varepsilon}}^2 \right).
\]

(Observe, \( t_0 > 0 \) because \( \|B\|_{\mathcal{H}^0_{\varepsilon}} > 1 \).) This finishes the proof. \( \square \)

\textbf{Corollary 3.3.} From \ref{3.3} it follows that for each \( \varepsilon \in (0, 1] \) and \( \omega \in (0, 1) \), any weak solution \( (U(t), \Phi^t) \) to Problem \( \mathcal{P}_\varepsilon \), according to Definition \ref{2.1}, is bounded uniformly in \( t \). Indeed, for all \( \Upsilon_0 \in \mathcal{H}_\varepsilon^0 \),

\[
\limsup_{t \to +\infty}\|\mathcal{S}_\varepsilon(t)\Upsilon_0\|_{\mathcal{H}^0_{\varepsilon}} \leq \bar{P}_0,
\]

where \( \bar{P}_0 \) depends on \( P_0 \) and the initial datum.

\textbf{Corollary 3.4.} Problem \( \mathcal{P}_\varepsilon \) defines a (nonlinear) strongly continuous semigroup \( \mathcal{S}_\varepsilon(t) \) on the phase space \( \mathcal{H}_\varepsilon^0 = X^2 \times M^1_\varepsilon \) by

\[
\mathcal{S}_\varepsilon(t)\Upsilon_0 := (U(t), \Phi^t),
\]

where \( \Upsilon_0 = (U_0, \Phi_0) \in \mathcal{H}_\varepsilon^0 \) and \( (U(t), \Phi^t) \) is the unique solution to Problem \( \mathcal{P}_\varepsilon \). The semigroup is Lipschitz continuous on \( \mathcal{H}_\varepsilon^0 \) via the continuous dependence estimate \ref{2.14}.

\textbf{Remark 3.5.} Thanks to the uniformity of the above estimates with respect to the perturbation parameter \( \varepsilon \), it is easy to see that there exists a bounded absorbing set \( \mathcal{B}_0^\varepsilon \) for the semigroup \( \mathcal{S}_0 : \mathcal{H}_\varepsilon^0 = X^2 \to X^2 \) generated by the weak solutions of Problem \( \mathcal{P}_0 \). Moreover, we also easily see that Problem \( \mathcal{P}_0 \) defines a semigroup \( \mathcal{S}_0(t) : \mathcal{H}_0^0 = X^2 \to X^2 \) by \( \mathcal{S}_0(t)U_0 := U(t) \). (See the references mentioned above for further details.)
3.2. Exponential attractors. Exponential attractors (sometimes called inertial sets) are positively invariant sets possessing finite fractal dimension that attract bounded subsets of their basin of attraction exponentially fast. This section will focus on the existence of exponential attractors. The existence of an exponential attractor depends on certain properties of the semigroup; namely, the smoothing property for the difference of any two trajectories and the existence of a more regular bounded absorbing set in the phase space (see e.g. [3, 20] and in particular [21]). The basin of attraction will be discussed in the next section.

The main result of this section is the following.

**Theorem 3.6.** For each $\varepsilon \in [0, 1]$ and $\omega \in (0, 1)$, the dynamical system $(S_\varepsilon, \mathcal{H}_\varepsilon^0)$ associated with Problem $P_\varepsilon$ admits an exponential attractor $\mathcal{M}_\varepsilon$ compact in $\mathcal{H}_\varepsilon^0$, and bounded in $\mathcal{V}_1^\varepsilon$. Moreover, there hold:

(i) For each $t \geq 0$, $S_\varepsilon(t)\mathcal{M}_\varepsilon \subseteq \mathcal{M}_\varepsilon$.

(ii) The fractal dimension of $\mathcal{M}_\varepsilon$ with respect to the metric $\mathcal{H}_\varepsilon^0$ is finite, uniformly in $\varepsilon$; namely,

$$\dim_F (\mathcal{M}_\varepsilon, \mathcal{H}_\varepsilon^0) \leq C < \infty,$$

for some positive constant $C$ independent of $\varepsilon$.

(iii) There exist $\varrho > 0$ and a positive nondecreasing function $Q$ such that, for all $t \geq 0$,

$$\text{dist}_{\mathcal{H}_\varepsilon^0}(S_\varepsilon(t)\mathcal{B}, \mathcal{M}_\varepsilon) \leq Q(\|\mathcal{B}\|_{\mathcal{H}_\varepsilon^0})e^{-\varrho t},$$

for every nonempty bounded subset $\mathcal{B}$ of $\mathcal{H}_\varepsilon^0$.

**Remark 3.7.** Above, the fractal dimension of $\mathcal{M}_\varepsilon$ in $\mathcal{H}_\varepsilon^0$ is given by

$$\dim_F (\mathcal{M}_\varepsilon, \mathcal{H}_\varepsilon^0) := \limsup_{r \to 0} \frac{\ln \mu_{\mathcal{H}_\varepsilon^0}(\mathcal{M}_\varepsilon, r)}{-\ln r} < \infty$$

where $\mu_{\mathcal{H}_\varepsilon^0}(\mathcal{X}, r)$ denotes the minimum number of $r$-balls from $\mathcal{H}_\varepsilon^0$ required to cover $\mathcal{X}$.

The proof of Theorem 3.6 follows from the application of an abstract result reported here for our problem (see e.g. [3, 21]; cf. also Remark 3.10 below).

**Proposition 3.8.** Let $(S_\varepsilon, \mathcal{H}_\varepsilon^0)$ be a dynamical system for each $\varepsilon \in [0, 1]$. Assume the following hypotheses hold:

(C1) There exists a bounded absorbing set $\mathcal{B}_\varepsilon^1 \subseteq \mathcal{V}_1^\varepsilon$ which is positively invariant for $S_\varepsilon(t)$. More precisely, there exists a time $t_1 > 0$, uniform in $\varepsilon$, such that

$$S_\varepsilon(t)\mathcal{B}_\varepsilon^1 \subseteq \mathcal{B}_\varepsilon^1$$

for all $t \geq t_1$ where $\mathcal{B}_\varepsilon^1$ is endowed with the topology of $\mathcal{H}_\varepsilon^0$.

(C2) There is $t^* \geq t_1$ such that the map $S_\varepsilon(t^*)$ admits the decomposition, for each $\varepsilon \in (0, 1]$ and for all $\mathcal{Y}_0, \Xi_0 \in \mathcal{B}_\varepsilon^1$,

$$S_\varepsilon(t^*)\mathcal{Y}_0 - S_\varepsilon(t^*)\Xi_0 = L_\varepsilon(\mathcal{Y}_0, \Xi_0) + R_\varepsilon(\mathcal{Y}_0, \Xi_0)$$

where, for some constants $\alpha^* \in (0, \frac{1}{4})$ and $\Lambda^* = \Lambda^*(\Omega, t^*, \omega) \geq 0$, the following hold:

$$\|L_\varepsilon(\mathcal{Y}_0, \Xi_0)\|_{\mathcal{H}_\varepsilon^0} \leq \alpha^* \|\mathcal{Y}_0 - \Xi_0\|_{\mathcal{H}_\varepsilon^0}$$

and

$$\|R_\varepsilon(\mathcal{Y}_0, \Xi_0)\|_{\mathcal{V}_1^\varepsilon} \leq \Lambda^* \|\mathcal{Y}_0 - \Xi_0\|_{\mathcal{H}_\varepsilon^0}.$$  \hspace{1cm} (3.17)

(C3) The map

$$(t, \mathcal{Y}) \mapsto S_\varepsilon(t)\mathcal{Y} : [t^*, 2t^*] \times \mathcal{B}_\varepsilon^1 \to \mathcal{B}_\varepsilon^1$$

is Lipschitz continuous on $\mathcal{B}_\varepsilon^1$ in the topology of $\mathcal{H}_\varepsilon^0$.

Then, $(S_\varepsilon, \mathcal{H}_\varepsilon^0)$ possesses an exponential attractor $\mathcal{M}_\varepsilon$ in $\mathcal{B}_\varepsilon^1$.

We now prove the hypotheses of Proposition 3.8 and we again remind the reader that for the remainder of the article, we assume that the smallness criteria (3.1) holds, in addition to the assumption (1.26). We begin with the perturbation Problem $P_\varepsilon$. The results for the singular Problem $P_0$ will follow.
Lemma 3.9. Condition (C1) holds for each $\varepsilon \in (0, 1]$ and $\omega \in (0, 1)$. Moreover, for all $R > 0$ and $\Upsilon_0 = (U_0, \Phi_0) \in \mathcal{V}^1 = \mathcal{V} \times \mathcal{K}^2$ with $\|\Upsilon_0\|_{\mathcal{V}^1} \leq R$ for all $\varepsilon \in (0, 1]$, there exists a positive constant $P_1 = P_1(\nu_1, \bar{P}_0)$ and a positive monotonically increasing function $Q(\cdot)$, each independent of $\varepsilon$, such that, for all $t \geq 0$,

$$\| (U(t), \Phi^t) \|_{\mathcal{V}^1}^2 \leq Q(R)e^{-\min\{\delta, 1\}t} (t + 1) + 2P_1. \tag{3.19}$$

Proof. Let $\varepsilon \in (0, 1], \omega \in (0, 1)$ and $\Upsilon_0 = (U_0, \Phi_0) \in \mathcal{V}^1 = \mathcal{V} \times \mathcal{K}^2$. For all $s, t \geq 0$, let $Z(t) = A^\omega_{\Upsilon, \Theta}(U(t))$ and $\Theta^t(s) = A^\omega_{\Upsilon, \Theta}(s)$. In equations (2.8), (2.9), take $\Xi = Z(t)$ and $\Pi = \Theta^t(s)$. Proceeding as in [17 proof of Theorem 3.11] (however, this time we are able to enjoy the uniform bounds (2.11)), we obtain the identities,

$$\langle \partial_t U, Z \rangle_{\mathcal{X}_2} + \omega \left\langle A^\omega_{\Upsilon, \Theta} U, Z \right\rangle_{\mathcal{X}_2} + \left\langle \Phi^t, Z \right\rangle_{\mathcal{M}_t^\omega} + \left\langle F(U), Z \right\rangle_{\mathcal{X}_2} = 0, \tag{3.20}$$

and

$$\left\langle \partial_t \Phi^t, \Theta^t \right\rangle_{\mathcal{M}_t^\omega} = \left\langle T_e \Phi^t, \Theta^t \right\rangle_{\mathcal{M}_t^\omega} + \left\langle U, \Theta^t \right\rangle_{\mathcal{M}_t^\omega}. \tag{3.21}$$

These two identities may be combined together after we observe that, from the definition of the product given in (1.22),

$$\left\langle \Phi^t, Z \right\rangle_{\mathcal{M}_t^\omega} = \int_0^\infty \mu_\varepsilon(s) \left\langle \Phi^t(s), Z \right\rangle_{\mathcal{V}^1} ds \tag{3.22}$$

and

$$\int_0^\infty \mu_\varepsilon(s) \left\langle A^\omega_{\Upsilon, \Theta} U, A^\omega_{\Upsilon, \Theta} \right\rangle_{\mathcal{X}_2} ds = \int_0^\infty \mu_\varepsilon(s) \left\langle \Theta^t(s), A^\omega_{\Upsilon, \Theta} U \right\rangle_{\mathcal{X}_2} ds \tag{3.23}$$

Next we write

$$\left\langle \partial_t U, Z \right\rangle_{\mathcal{X}_2} = \left\langle \partial_t U, A^\omega_{\Upsilon, \Theta} U \right\rangle_{\mathcal{X}_2} \tag{3.24}$$

and

$$\omega \left\langle A^\omega_{\Upsilon, \Theta} U, Z \right\rangle_{\mathcal{X}_2} = \omega \left( \langle \nabla u, \nabla z \rangle_{L^2(\Omega)} + \langle \nabla r u, \nabla r z \rangle_{L^2(\Gamma)} + \beta (v, z)_{L^2(\Gamma)} \right) \tag{3.25}$$

for all $t \geq 0$.\]
and
\[
\langle \partial_t \Phi^t, \Theta^t \rangle_{M_2^t} = \int_0^\infty \mu_\varepsilon(s) \langle \partial_t \Phi^t(s), \Theta^t(s) \rangle_{\mathcal{V}_1} \, ds
\]  
(3.26)

Combining (3.23) to (3.26) brings us to the differential identity, which holds for almost all \( t \geq 0 \),
\[
\frac{1}{2} \frac{d}{dt} \left\{ \| U \|_{\mathcal{V}_1}^2 + \| \Theta^t \|_{M_2^t}^2 \right\}
+ \omega \| Z \|_{\mathcal{X}_2}^2 - \langle T \Phi^t, \Theta^t \rangle_{M_2^t} + \langle F(U), Z \rangle_{\mathcal{X}_2}
= \omega \alpha \langle u, z \rangle_{L^2(\Omega)}.
\]  
(3.27)

With assumption (1.26) we are able to estimate the following
\[
\langle T \Phi^t, \Theta^t \rangle_{M_2^t} = \int_0^\infty \mu_\varepsilon(s) \langle T \Phi^t(s), \Theta^t(s) \rangle_{\mathcal{V}_1} \, ds
\]  
(3.28)

Multiplying the nonlinear term by \( Z \) in \( \mathcal{X}_2 \) produces, with an application of integration by parts,
\[
\langle F(U), Z \rangle_{\mathcal{X}_2} = \int_\Omega f(u) (-\Delta u + \alpha u) \, dx + \int_\Gamma \tilde{g}(u) (-\Delta_{\Gamma} u + \partial_n u + \beta u) \, d\sigma
\]  
(3.29)

Directly from (1.39) and (1.40), we see that there holds,
\[
\int_\Omega f'(u) |\nabla u|^2 \, dx + \int_\Gamma \tilde{g}'(u) |\nabla_{\Gamma} u|^2 \, d\sigma \geq -M_f \| \nabla u \|^2_{L^2(\Omega)} - M_g \| \nabla_{\Gamma} u \|^2_{L^2(\Gamma)},
\]  
(3.30)
and from (3.11), (3.12), we obtain,
\[
\alpha \int_{\Omega} f(u) \, dx + \beta \int_{\Gamma} g(u) \, u \, d\sigma = \alpha \int_{\Omega} f(u) \, ds + \beta \int_{\Gamma} g(u) \, u \, d\sigma - \int_{\Gamma} \omega \beta^2 u^2 \, d\sigma \\
\geq -\alpha \kappa_1 \|u\|_{L^2(\Omega)}^2 - \alpha \kappa_2 - \beta \kappa_3 \|u\|_{L^2(\Gamma)}^2 - \beta \kappa_4 - \omega \beta^2 \|u\|_{L^2(\Gamma)}^2 \\
\geq -C \left( \|U\|_{L^2}^2 + 1 \right),
\]
for some constant $C > 0$, independent of $t$. For the last term in (3.31) we recall (17). Proof of Theorem 3.11]. Due to the assumptions (1.37)-(1.38) it suffices to bound integrals of the form, for some $r \leq \frac{5}{4}$,
\[
I := \int_{\Gamma} u^{r+1} \partial_n u \, d\sigma.
\]
Indeed, thanks to the trace and regularity embeddings, for all $\omega \in (0, 1)$ and for some $C_\omega \sim \frac{\omega}{2} > 0$,
\[
I \leq \|\partial_n u\|_{H^{1/2}(\Gamma)} \|u^{r+1}\|_{H^{-1/2}(\Gamma)} \\
\leq \frac{\omega}{4} \|u\|_{H^2(\Omega)}^2 + C_\omega \|u^{r+1}\|_{H^{-1/2}(\Gamma)}^2.
\]
To bound the last term in (3.32) we will employ the Sobolev embeddings (recall $\Gamma$ is two-dimensional) $H^{1/2}(\Gamma) \hookrightarrow L^4(\Gamma)$ and $H^1(\Gamma) \hookrightarrow L^s(\Gamma)$, for any $s \in (\frac{4}{3}, \infty)$. Then, by employing some basic Hölder inequalities
\[
\|u^{r+1}\|_{H^{-1/2}(\Gamma)}^2 = \sup_{\psi \in H^{1/2}(\Gamma)} \|u^{r+1}\|_{H^{1/2}(\Gamma)} \|\psi\|_{H^{1/2}(\Gamma)} \|\psi\|_{H^{1/2}(\Gamma)} = 1 \\
\leq \sup_{\psi \in H^{1/2}(\Gamma)} \|\psi\|_{H^1(\Gamma)}^2 \|u\|_{L^s(\Gamma)}^2 \\
\leq C \|u\|_{H^1(\Gamma)}^2 \|u\|_{L^s(\Gamma)}^2,
\]
for some positive constant $C$ and for sufficiently large $s \in (\frac{4}{3}, \infty)$, where $\bar{s} := 4s / (3s - 4) > 4/3$. Next we exploit the interpolation inequality
\[
\|u\|_{L^\infty(\Gamma)} \leq C \|u\|_{H^2(\Gamma)}^{1/2r} \|u\|_{L^2(\Gamma)}^{1-1/2r},
\]
provided that $r = 1 + 2/\bar{s} < 5/2$, where we further infer from (3.33) that
\[
\|u^{r+1}\|_{H^{-1/2}(\Gamma)}^2 \leq C \|u\|_{H^1(\Gamma)}^2 \|u\|_{H^2(\Gamma)}^2 \|u\|_{L^2(\Gamma)}^{2r-1} \\
\leq \eta \|u\|_{H^2(\Gamma)}^2 + C_\eta \|u\|_{H^1(\Gamma)}^2 \left( \|u\|_{H^1(\Gamma)}^2 \|u\|_{L^2(\Gamma)}^{2(2r-1)} \right),
\]
for any $\eta \in (0, 1]$. Inserting (3.34) into (3.32) and choosing a sufficiently small $\eta = \omega/C_\omega$, by virtue of (1.36), we easily deduce
\[
I \leq \frac{\omega}{4} \|Z\|_{X^2}^2 + C_\omega \|u\|_{H^1(\Gamma)}^2 \left( \|u\|_{H^1(\Gamma)}^2 \|u\|_{L^2(\Gamma)}^{2(2r-1)} \right).
\]
Together, (3.30) + (3.35) provide the following bound on (3.29) for all $\omega > 0$, and for some positive constants $C$ and $C_\omega \sim \frac{\omega}{2}$,
\[
\langle F(U), Z \rangle_{X^2} \geq -C \left( \|U\|_{X^2}^2 + 1 \right) - \frac{\omega}{4} \|Z\|_{X^2}^2 \\
- C_\omega \|u\|_{H^1(\Gamma)}^2 \left( \|u\|_{H^1(\Gamma)}^2 \|u\|_{L^2(\Gamma)}^{2(2r-1)} \right).
\]
Also with Young’s inequality,
\[
\omega \alpha \langle u, z \rangle_{L^2(\Omega)} \leq \omega \alpha^2 \|u\|_{L^2(\Omega)}^2 + \frac{\omega}{4} \|z\|_{L^2(\Omega)}^2 \\
\leq \omega \alpha^2 \|u\|_{L^2(\Omega)}^2 + \frac{\omega}{4} \|Z\|_{X^2}^2.
\]
Applying the estimates (3.28), (3.36) and (3.37) to (3.24), we arrive at the differential inequality, which holds for almost all \( t \geq 0 \), and for \( 0 < r < \frac{3}{2} \),

\[
\begin{aligned}
\frac{d}{dt} \left\{ \|U\|_{V^1}^2 + \|\Theta^t\|_{M^0}^2 \right\} &+ \omega \|Z\|_{X^2}^2 + \delta \|\Theta^t\|_{M^0}^2 \\
&\leq C \left( \|U\|_{X^2}^2 + 1 \right) + C_\omega \|u\|_{H^1(\Gamma)}^2 \left( \|U\|_{L^2(\Gamma)}^{2(2r-1)} \right).
\end{aligned}
\]

(3.38)

On the left-hand side, we estimate the term \( \omega \|Z\|_{X^2}^2 \) using

\[
\|U\|_{V^1}^2 = \langle U, A_W^\alpha \beta U \rangle_{X^2} = \langle U, Z \rangle_{X^2} \leq C_\omega \|U\|_{X^2}^2 + \omega \|Z\|_{X^2}^2.
\]

(3.39)

Finally, with (3.39) and the uniform bounds (3.16), we now obtain from (3.38), with \( m_1 := \min \{1, \delta \} > 0 \),

\[
\frac{d}{dt} \left\{ \|U\|_{V^1}^2 + \|\Theta^t\|_{M^0}^2 \right\} + m_1 \left( \|U\|_{V^1}^2 + \|\Theta^t\|_{M^0}^2 \right) \leq C_\omega \left( 1 + \|u\|_{H^1(\Gamma)}^2 \right) \left( \|U\|_{V^1}^2 + \|\Theta^t\|_{M^0}^2 \right) + C,
\]

where \( C_\omega > 0 \) depends on \( \bar{P}_0 \) from (3.16). Now from (3.39), we immediately find the following dissipation integral

\[
\omega \int_t^{t+1} \|U(\tau)\|_{V^1}^2 \, d\tau \leq C,
\]

(3.41)

and we may apply a Grönwall-type inequality (see e.g. Proposition A.3 below) to (3.40). We also recall (3.16) yields, for some \( C_* > 0 \),

\[
C_*^{-1} \|\Phi^t\|_{V^2}^2 \leq \|A_W^\alpha \beta \Phi^t\|_{M^0}^2 = \|\Theta^t\|_{M^0}^2 \leq C_* \|\Phi^t\|_{V^1}^2.
\]

(3.42)

Hence, there are constants \( M_1 \geq 1 \) and \( P_1 > 0 \), both uniform in \( t \), such that for all \( t \geq 0 \), (3.40) produces, for all \( t \geq 0 \),

\[
\begin{aligned}
\|U(t)\|_{V^1}^2 + \|\Phi^t\|_{M^0}^2 &\leq M_1 e^{-m_1 t} \left( \|U_0\|_{V^1}^2 + \|\Phi_0\|_{M^0}^2 \right) + P_1 \\
&\leq M_1 Re^{-m_1 t} + P_1,
\end{aligned}
\]

(3.43)

where the last inequality follows because \( \|\Phi_0\|_{M^0} \leq \|\Phi_0\|_{X^2} \leq R \).

To show (3.19) holds we need to control the last two terms of the norm (3.33). First, it is easy to see from (3.43) that for all \( t \geq 0 \)

\[
\|U(t)\|_{V^1}^2 \leq \|U(t)\|_{V^1}^2 + \|\Phi^t\|_{M^0}^2 \leq M_1 R + P_1.
\]

Then the conclusions of Lemmas 1.5 and 1.7 given above now take the form

\[
\varepsilon \|T_\varepsilon \Phi^t\|_{M^0}^2 + \sup_{\tau \geq 0} \tau T_\varepsilon(\tau; \Phi^t) \\
\leq e^{-\delta t} \left( \varepsilon \|T_\varepsilon \Phi_0\|_{M^0}^2 + 2 \sup_{\tau \geq 1} \tau T_\varepsilon(\tau; \Phi_0) (t+2) \right) + M_1 Re^{-m_1 t} + P_1 \\
\leq e^{-m_1 t} \left( R(M_1 + 1) + Q(R) (t + 1) \right) + P_1 \\
\leq Q(R)e^{-m_1 t} (t + 1) + P_1.
\]

(3.44)

Together, the estimates (3.43) and (3.44) show that (3.19) holds.
The existence of a bounded set $B_{ε}^1$ in $V_{ε}^1$ that is absorbing and positively invariant for $S_{ε}(t)$ follows from (3.19). Indeed, define

$$B_{ε}^1 := \{(U, Φ) ∈ V_{ε}^1 : \|(U, Φ)\|_{V_{ε}^1} ≤ \sqrt{2P_{1} + 1}\}.$$ 

Then, given any nonempty bounded subset $B$ in $H_{ε}^0 \setminus B_{ε}^1$, and after possibly enlarging the radius of $B_{ε}^1$ in $H_{ε}^0$ due to the embedding $V_{ε}^1 ⊆ H_{ε}^0$, we have that $S_{ε}(t)B ⊆ B_{ε}^1$, in $H_{ε}^0$, for all $t ≥ t_1$ where $t_1 = t_1(R) ≥ 0$ is such that there holds

$$e^{-\min\{δ, 1\}t_1} (t_1 + 1) ≤ \frac{1}{Q(R)}.$$ 

(3.45)

This establishes (C1) and completes the proof when $ε ∈ (0, 1]$.

The following result refers to the strong solutions developed in [17] Theorem 3.11] (see Theorem 2.6 above) whose initial data is now taken in $V_{ε}^1 ⊆ H_{ε}^0$.

**Corollary 3.10.** For all $Γ = (U_0, Φ_0) ∈ H_{ε}^0 = V^1 × M_{ε}^2$, it follows that any strong solution $(U(t), Φ^t)$ to Problem $P_{ε}$ is bounded, uniformly in $t$ and $ε$; indeed, thanks to (3.19) there is a constant $P_1 > 0$, depending on the bound $P_1$ and the initial datum, but independent of $t$ and $ε$, in which,

$$\limsup_{t → +∞} \|S_{ε}(t)(U_0, Φ_0)\|_{V_{ε}^1} ≤ P_1.$$ 

(3.46)

We can now give a decay estimate for $Φ^t$ in $M_{ε}^1$.

**Lemma 3.11.** There holds, for all $ε ∈ (0, 1]$, $ω ∈ (0, 1)$, $Γ_0 = (U_0, Φ_0) ∈ V_{ε}^1$, and for all $t ≥ 0$,

$$\|Φ^t\|_{M_{ε}^1}^2 ≤ \|Φ_0\|_{M_{ε}^1}^2 e^{-σt/2ε} + C(P_0)ε.$$ 

(3.47)

**Proof.** Let $ε ∈ (0, 1]$, $ω ∈ (0, 1)$ and $Γ_0 = (U_0, Φ_0) ∈ H_{ε}^0$. As in the proof of Lemma 3.2 take $Π = Φ^t(s)$ in equation (3.4) to obtain

$$\int_0^∞ \mu_ε(s) \left⟨ \partial_s Φ^t(s), A_{ω}^{α, β} Φ^t(s) \right⟩_{X^2} ds = \int_0^∞ \mu_ε(s) \left⟨ T_ε Φ^t(s), A_{ω}^{α, β} Φ^t(s) \right⟩_{X^2} ds + \int_0^∞ \mu_ε(s) \left⟨ U, A_{ω}^{α, β} Φ^t(s) \right⟩_{X^2} ds.$$ 

Combining (3.2), (3.5), (3.8), and (3.10), we obtain

$$\frac{1}{2} \frac{d}{dt} \|Φ^t\|_{M_{ε}^1}^2 + \frac{δ}{2ε} \|Φ^t\|_{M_{ε}^1}^2 ≤ \left⟨ U, Φ^t(0) \right⟩_{H^2}.$$ 

(3.48)

Estimating the product on the right-hand side with Young’s inequality,

$$\left⟨ U, Φ^t(0) \right⟩_{H^2} = \int_0^∞ \mu_ε(s) \left⟨ U, Φ^t(s) \right⟩_{V^1} ds \leq \int_0^∞ \mu_ε(s) \|U\|_{V^1} \|Φ^t\|_{V^1} ds \leq \|U\|_{V^1} \|Φ^t\|_{M_{ε}^1} \leq \frac{1}{δ} \|U\|_{V^1}^2 + \frac{δ}{4ε} \|Φ^t\|_{M_{ε}^1}^2.$$ 

(3.49)

we combine (3.48) and (3.49) to find that, for almost all $t ≥ 0$,

$$\frac{d}{dt} \|Φ^t\|_{M_{ε}^1}^2 + \frac{δ}{2ε} \|Φ^t\|_{M_{ε}^1}^2 ≤ \frac{1}{δ} \|U\|_{V^1}^2.$$ 

(3.50)

Thus, applying a Grönwall type inequality whereby integrating (3.50) over the interval $(0, t)$, recalling the uniform bound (3.49), produces (3.47).

**Corollary 3.12.** From Lemma 3.11 we obtain the limit, for each $t > 0$ fixed,

$$\lim_{ε → 0} \|Φ^t\|_{M_{ε}^1} = 0.$$ 

(3.51)
In addition, since \( e^{-\delta t/2e} < e^{-\delta t/2} e^{\delta t/2} < e^{\delta T/2} \) for all \( \varepsilon \in (0, 1] \) and for all \( t \) in the compact interval \([0, T]\), for some \( T > 0 \), then inequality (3.47) is estimated by,
\[
\|\Phi_t^e\|_{M_t^\varepsilon}^2 \leq \max \{ \|\Phi_0\|_{M_t^\varepsilon}, C(\bar{P}_0) \} \left( e^{\delta T/2} + \varepsilon \right).
\]

Define the constants \( \Lambda_0 = \max \{ \|\Phi_0\|_{M_T^\varepsilon}, e^{-\delta \varepsilon t/2}, C(\bar{P}_0) \} \) and \( p_0 = \min \{ \frac{\delta T}{T}, \frac{1}{2} \} \). Then, for all \( \varepsilon \in (0, 1] \) and for all \( t \in [0, T] \), there holds,
\[
\|\Phi_t^e\|_{M_t^\varepsilon} \leq \Lambda_0 e^{p_0}.
\]

We now go on to establish the next condition of Proposition 3.8.

**Lemma 3.13.** Condition (C2) holds for each \( \varepsilon \in (0, 1] \) and \( \omega \in (0, 1) \). The constants \( t^* \) and \( \ell^* \) depend on \( \omega, \delta \) and the constant due to the embedding \( \mathcal{V}^1 \hookrightarrow \mathcal{X}^2 \).

**Proof.** Let \( \varepsilon \in (0, 1] \) and \( \omega \in (0, 1) \). Let \( Y_0 = (U_0, \Phi_0), Z_0 = (V_0, \Psi_0) \in B^1 \). Define the pair of trajectories, for \( t \geq 0 \), \( Y(t) = S_t(t) Y_0 = (U(t), \Phi^t) \) and \( Z(t) = S_t(t) Z_0 = (V(t), \Psi^t) \). For each \( t \geq 0 \), decompose the difference \( \Delta(t) := Y(t) - Z(t) \) with \( \Delta_0 := Y_0 - Z_0 \) as follows:
\[
\Delta(t) = \bar{Y}(t) + \bar{Z}(t)
\]
where \( \bar{Y}(t) = (\bar{V}(t), \bar{\Phi}^t) \) and \( \bar{Z}(t) = (\bar{W}(t), \bar{\Phi}^t) \) are solutions of the problems:
\[
\begin{align*}
\frac{\partial}{\partial t} \bar{V}(t) + \omega A_W^0 \bar{V}(t) + \int_0^\infty \mu_\varepsilon(s) A_W^0 \bar{\Phi}^t(s)ds &= 0, \\
\frac{\partial}{\partial t} \bar{\Phi}^t(s) + T_\varepsilon \bar{\Phi}^t(s) + \bar{V}(t), \\
\bar{Y}(0) &= Y_0 - Z_0,
\end{align*}
\]
and
\[
\begin{align*}
\frac{\partial}{\partial t} \bar{W}(t) + \omega A_W^0 \bar{W}(t) + \int_0^\infty \mu_\varepsilon(s) A_W^0 \bar{\Theta}^t(s)ds + F(U(t)) - F(V(t)) &= 0, \\
\frac{\partial}{\partial t} \bar{\Theta}^t(s) &= T_\varepsilon \bar{\Theta}^t(s) + W(t), \\
\bar{Z}(0) &= 0.
\end{align*}
\]

**Step 1.** (Proof of (3.17).) By estimating along the usual lines, after multiplying (3.52) by \( \bar{V} \) in \( \mathcal{X}^2 \) and multiplying equation (3.52) by \( A_W^0 \bar{\Phi}^t \) in \( M_0^\varepsilon = L^2_{M_0^\varepsilon}(\mathbb{R}^+; \mathcal{X}^2) \), we easily obtain the differential inequality,
\[
\frac{1}{2} \frac{d}{dt} \left( \|\bar{V}\|_{\mathcal{X}^2}^2 + \|\bar{\Phi}^t\|_{M_0^\varepsilon}^2 \right) + C_{\mathcal{T}^2} \omega \|\bar{V}\|_{\mathcal{X}^2}^2 + \frac{\delta}{2} \|\bar{\Phi}^t\|_{M_0^\varepsilon}^2 \leq 0,
\]
where the constant \( C_{\mathcal{T}^2} > 0 \) is due to the embedding \( \mathcal{V}^1 \hookrightarrow \mathcal{X}^2 \); i.e., \( \|\bar{V}\|_{\mathcal{X}^2}^2 \leq C_{\mathcal{T}^2} \|\bar{V}\|_{\mathcal{V}^1}^2 \). Set \( m_2 := \min(2C_{\mathcal{T}^2} \omega, \delta) > 0 \). Thus, \( (3.53) \) becomes, for almost all \( t \geq 0 \),
\[
\frac{d}{dt} \left( \|\bar{V}\|_{\mathcal{X}^2}^2 + \|\bar{\Phi}^t\|_{M_0^\varepsilon}^2 \right) + m_2 \left( \|\bar{V}\|_{\mathcal{X}^2}^2 + \|\bar{\Phi}^t\|_{M_0^\varepsilon}^2 \right) \leq 0.
\]
After applying a Grönwall inequality, we have that for all \( t \geq 0 \),
\[
\left( \|\bar{V}(t), \bar{\Phi}^t\|_{M_0^\varepsilon} \right) \leq \left( \|\bar{\Delta}_0\|_{M_0^\varepsilon} e^{m_2 t/2}.
\]
Set \( t^* := \max\{t_1, \frac{2}{m_2} \ln 4\} \) (recall \( t_1 \) was defined in (3.45) in the proof of Lemma 3.9). Then, for all \( t \geq t^* \), \( (3.17) \) holds with \( L = \bar{Y}(t^*) = (\bar{V}(t^*), \bar{\Phi}^{t^*}) \), and
\[
\ell^* = e^{-m_2 t^*/2} < \frac{1}{2}.
\]
Before we show that \( (3.19) \) holds, we need to establish a crucial bound.

**Step 2.** (A preliminary bound for \( \bar{W} \) and \( \bar{\Theta}^t \).) We claim, for each \( 0 < T < \infty \), there holds
\[
\bar{W} \in L^\infty([0, T]; \mathcal{X}^2) \cap L^2([0, T]; \mathcal{V}^1),
\]
\[
\bar{\Theta}^t \in L^\infty([0, T]; M_t^\varepsilon).
\]
To show this, we multiply equation (3.53) by $\hat{W}$ in $\mathcal{X}^2$ and multiply equation (3.54) by $A_{W}^{\alpha,\beta} \hat{\Theta}^t$ in $\mathcal{M}^0_t$. Summing the resulting two identities produces,

\[
\frac{1}{2} \frac{d}{dt} \left( \left\| \hat{W} \right\|_{\mathcal{X}^2}^2 + \left\| \hat{\Theta}^t \right\|_{\mathcal{M}^t_1}^2 \right) + \omega \left( A_{W}^{0,0} \hat{W}, \hat{W} \right)_{\mathcal{X}^2} - \left( T_e \hat{\Theta}^t, \hat{\Theta}^t \right)_{\mathcal{M}^t_1} + \left( F(U) - F(V), \hat{W} \right)_{\mathcal{X}^2} = 0. \tag{3.58}
\]

The first of the three products above can be re-written, using the definition of the $\mathcal{V}^1$ norm (see (1.18)), as

\[
\omega \left( A_{W}^{0,0} \hat{W}, \hat{W} \right)_{\mathcal{X}^2} = \omega \left( A_{W}^{0,0} \hat{W}, \hat{W} \right)_{\mathcal{X}^2} - \omega \alpha (\hat{w}, \hat{w})_{L^2(\Omega)} = \omega \left( \left\| \nabla \hat{w} \right\|_{L^2(\Omega)}^2 + \left\| \nabla^\Gamma \hat{w} \right\|_{L^2(\Gamma)}^2 + \beta \left\| \hat{w} \right\|_{L^2(\Gamma)}^2 \right) + \omega \alpha (\hat{w}, \hat{w})_{L^2(\Omega)}.
\]

As with the above estimate (3.52), we have

\[
\left( T_e \hat{\Theta}^t, \hat{\Theta}^t \right)_{\mathcal{M}^t_1} - \frac{\delta}{2} \left\| \hat{\Theta}^t \right\|_{\mathcal{M}^t_1}^2 \leq -\frac{\omega}{2} \left\| \hat{\Theta}^t \right\|_{\mathcal{M}^t_1}^2.
\]

Using assumptions (1.37) and (1.38), with data in the bounded set $\mathcal{B}_{\varepsilon}^1$ and the uniform bound (3.10), we now estimate the nonlinear terms as follows

\[
\left( f(u) - f(v), \hat{w} \right)_{L^2(\Omega)} \leq \left\| f(u) - f(v) \right\|_{L^6(\Omega)} \left\| \hat{w} \right\|_{L^6(\Omega)} \leq \left\| f(u) - f(v) \right\|_{L^{5/3,6}(\Omega)} \left\| \hat{w} \right\|_{L^6(\Omega)} \leq r_1 \left\| u - v \right\|_{L^6(\Omega)} \left( 1 + \left\| u - v \right\|_{L^{3,1/2}(\Omega)} \right) \left\| \hat{w} \right\|_{L^6(\Omega)} \leq C \left\| \hat{w} \right\|_{H^1(\Omega)},
\]

where $C = C(t_1, \Omega, \bar{P}_0, r_1) > 0$ and the last inequality follows from the fact that $H^1(\Omega) \hookrightarrow L^6(\Omega)$ and $H^1(\Omega) \hookrightarrow L^{3,1/2}(\Omega)$ because $1 \leq r_1 < \frac{3}{2}$. Similarly for $\bar{g}$ (here the estimate is easier because $H^1(\Gamma) \hookrightarrow L^p(\Gamma)$ for $1 \leq p < \infty$ as $\Gamma$ is two dimensional),

\[
\left( \bar{g}(u) - \bar{g}(v), \hat{w} \right)_{L^2(\Gamma)} \leq C \left\| \hat{w} \right\|_{H^1(\Gamma)}.
\]

Thus, (3.61) and (3.62) show that

\[
\left( \left\| \nabla \hat{w} \right\|_{L^2(\Omega)}^2 + \left\| \nabla^\Gamma \hat{w} \right\|_{L^2(\Gamma)}^2 + \beta \left\| \hat{w} \right\|_{L^2(\Gamma)}^2 \right) + \delta \left\| \hat{\Theta}^t \right\|_{\mathcal{M}^t_1}^2 \leq C_w \left\| \hat{w} \right\|_{\mathcal{H}^2_0}^2 + \omega \left\| \hat{W} \right\|_{\mathcal{V}^1}^2,
\]

where $C_w \sim \frac{C}{2}$. Together (3.58)–(3.59) yields the differential inequality, which holds for almost all $t \geq 0$,

\[
\frac{d}{dt} \left( \left\| \hat{W} \right\|_{\mathcal{X}^2}^2 + \left\| \hat{\Theta}^t \right\|_{\mathcal{M}^t_1}^2 \right) + \omega \left( \left\| \nabla \hat{w} \right\|_{L^2(\Omega)}^2 + \left\| \nabla^\Gamma \hat{w} \right\|_{L^2(\Gamma)}^2 + \beta \left\| \hat{w} \right\|_{L^2(\Gamma)}^2 \right) + \delta \left\| \hat{\Theta}^t \right\|_{\mathcal{M}^t_1}^2 \leq C_w \left\| \hat{w} \right\|_{\mathcal{H}^2_0}^2.
\]

Now integrating (3.63) with respect to $t$ in $[0, T]$, for some fixed $0 < T < \infty$, we obtain

\[
\left\| \hat{W}(t) \right\|_{\mathcal{X}^2}^2 + \left\| \hat{\Theta}^t \right\|_{\mathcal{M}^t_1}^2 + \int_0^T \left( \omega \left( \left\| \nabla \hat{w}(\tau) \right\|_{L^2(\Omega)}^2 + \left\| \nabla^\Gamma \hat{w}(\tau) \right\|_{L^2(\Gamma)}^2 + \beta \left\| \hat{w}(\tau) \right\|_{L^2(\Gamma)}^2 \right) + \delta \left\| \hat{\Theta}^\tau \right\|_{\mathcal{M}^\tau_1}^2 \right) d\tau \leq C_w \left\| \hat{w} \right\|_{\mathcal{H}^2_0}^2 T.
\]

Using (3.65), we easily deduce the claim (3.56)–(3.57).
Step 3. (Proof of (3.18).) We begin by multiplying equation (3.53) by $K = A^\alpha_\omega^\beta \hat{W}$ in $\mathbb{X}^2$, then, after applying $A^\alpha_\omega^\beta$ to equation (3.53), we multiply the result by $\Lambda^t = A^\alpha_\omega^\beta \hat{\Theta}^t$ in $\mathcal{M}^0_\mu = L^2(\mathbb{R}^+; \mathbb{X}^2)$. This leaves us with the two identities,

$$
\left\langle \partial_t \hat{W}, K \right\rangle_{\mathbb{X}^2} + \omega \left\langle A^\alpha_\omega^\beta \hat{W}, K \right\rangle_{\mathbb{X}^2} + \left\langle A^\alpha_\omega^\beta \hat{\Theta}^t, K \right\rangle_{\mathcal{M}^0_\mu} + (F(U) - F(V), K)_{\mathbb{X}^2} = 0.
$$

(3.66)

and

$$
\left\langle \partial_t A^\alpha_\omega^\beta \hat{\Theta}^t, \Lambda^t \right\rangle_{\mathcal{M}^0_\mu} = \left\langle A^\alpha_\omega^\beta T \hat{\Theta}^t, \Lambda^t \right\rangle_{\mathcal{M}^0_\mu} + \left\langle A^\alpha_\omega^\beta \hat{W}, \Lambda^t \right\rangle_{\mathcal{M}^0_\mu}.
$$

(3.67)

Observe,

$$
\left\langle A^\alpha_\omega^\beta \hat{\Theta}^t, K \right\rangle_{\mathcal{M}^0_\mu} = \left\langle \Lambda^t, A^\alpha_\omega^\beta \hat{W} \right\rangle_{\mathcal{M}^0_\mu}.
$$

(3.68)

Hence, combining (3.66) and (3.67) through (3.68),

$$
\left\langle \partial_t \hat{W}, K \right\rangle_{\mathbb{X}^2} + \omega \left\langle A^\alpha_\omega^\beta \hat{W}, K \right\rangle_{\mathbb{X}^2} + \left\langle \partial_t A^\alpha_\omega^\beta \hat{\Theta}^t, \Lambda^t \right\rangle_{\mathcal{M}^0_\mu} - \left\langle A^\alpha_\omega^\beta T \hat{\Theta}^t, \Lambda^t \right\rangle_{\mathcal{M}^0_\mu} + (F(U) - F(V), K)_{\mathbb{X}^2} = 0.
$$

(3.69)

The first three products can be re-written as follows,

$$
\left\langle \partial_t \hat{W}, K \right\rangle_{\mathbb{X}^2} = \left\langle \partial_t \hat{W}, A^\alpha_\omega^\beta \hat{W} \right\rangle_{\mathbb{X}^2} = \left\langle \partial_t \hat{W}, \hat{W} \right\rangle_{\mathbb{X}^2} = \frac{1}{2} \frac{d}{dt} \| \hat{W} \|_{\mathbb{X}^2}^2.
$$

(3.70)

$$
\omega \left\langle A^\alpha_\omega^\beta \hat{W}, K \right\rangle_{\mathbb{X}^2} = \omega \left\langle A^\alpha_\omega^\beta \hat{W}, K \right\rangle_{\mathbb{X}^2} - \omega \alpha \langle \hat{w}, k \rangle_{L^2(\Omega)} = \omega \| K \|_{\mathbb{X}^2}^2 - \omega \alpha \langle \hat{w}, k \rangle_{L^2(\Omega)},
$$

(3.71)

and

$$
\left\langle \partial_t A^\alpha_\omega^\beta \hat{\Theta}^t, \Lambda^t \right\rangle_{\mathcal{M}^0_\mu} = \left\langle \partial_t \Lambda^t, \Lambda^t \right\rangle_{\mathcal{M}^0_\mu} = \frac{1}{2} \frac{d}{dt} \| \Lambda^t \|_{\mathcal{M}^0_\mu}^2.
$$

(3.72)

Inserting (3.70)–(3.72) into (3.69) gives us the differential identity,

$$
\frac{1}{2} \frac{d}{dt} \left\{ \| \hat{W} \|_{\mathbb{X}^2}^2 + \| \Lambda^t \|_{\mathcal{M}^0_\mu}^2 \right\} + \omega \| K \|_{\mathbb{X}^2}^2 - \left\langle T \hat{\Theta}^t, \Lambda^t \right\rangle_{\mathcal{M}^0_\mu} + (F(U) - F(V), K)_{\mathbb{X}^2} = \omega \alpha \langle \hat{w}, k \rangle_{L^2(\Omega)}.
$$

(3.73)

Similar to (3.28), we estimate

$$
\left\langle A^\alpha_\omega^\beta T \hat{\Theta}^t, \Lambda^t \right\rangle_{\mathcal{M}^0_\mu} \leq - \frac{\delta}{2} \| \Lambda^t \|_{\mathcal{M}^0_\mu}^2,
$$

(3.74)

and in a similar fashion to (3.63), we find

$$
\| (F(U) - F(V), K)_{\mathbb{X}^2} \| \leq C_\omega \| \hat{W} \|_{\mathbb{X}^2}^2 + \frac{\omega}{4} \| K \|_{\mathbb{X}^2}^2,
$$

(3.75)

where $C_\omega \sim \frac{\omega}{\omega}$. We also estimate

$$
\omega \alpha \langle \hat{w}, k \rangle_{L^2(\Omega)} \leq \omega \alpha^2 \| \hat{W} \|_{\mathbb{X}^2}^2 + \frac{\omega}{4} \| K \|_{\mathbb{X}^2}^2.
$$

(3.76)
Thus, letting $T \leq R$ and secondly, by applying the weak form of Lemma 1.5 (see Remark 1.6), we find that for all third terms from the left-hand side of (3.78), the following bound follows easily with Grönwall’s inequality

$$\begin{align*}
\text{Now integrating } (3.77) \text{ with respect to } t \text{ in } [0, T], \text{ for some fixed } 0 < T < \infty, \text{ we obtain}
\|\tilde{W}(t)\|_{V^1}^2 + \|A^t\|^2_{M^2_0} + \int_0^t \left( \omega \|A^0_\epsilon \tilde{W}(\tau)\|_{X^2}^2 + \delta \|A^\tau\|_{M^2_0}^2 \right) d\tau \\
\leq C \|\tilde{W}(0)\|_{X^2}^2 + C\omega \|\tilde{\Sigma}_0\|_{H^0_0}^2 T,
\end{align*}
$$

where the right-hand side of the inequality makes sense thanks to (3.56). Now omitting the second and third terms from the left-hand side of (3.78), the following bound follows easily with Grönwall’s inequality

$$\begin{align*}
\|\tilde{W}(t)\|_{V^1}^2 &\leq C\omega \|\tilde{\Sigma}_0\|_{H^0_0}^2 T e^{\alpha T},
\end{align*}
$$

and with this

$$\|A^t\|_{M^2_0}^2 \leq C\omega \|\tilde{\Sigma}_0\|_{H^0_0}^2 T e^{\alpha T},$$

also follows.

In order to obtain the desired bound from (3.79) and (3.80), first recall that there is $C_* > 0$ (cf. (1.36)) such that

$$\|A^t\|_{M^2_0}^2 = \|A^0_\epsilon \tilde{\Theta}^t\|_{M^2_0}^2 \geq C_*^{-1} \|\tilde{\Theta}^t\|_{M^2_0}^2.$$

Thus, letting $T = t^*$ (from Step 1), we obtain, for some positive monotonically increasing function $M_2(\cdot)$,

$$\|\left(\tilde{W}(t^*), \tilde{\Theta}^t\right)\|_{H^1_0} \leq M_2(t^*) \|\tilde{\Sigma}_0\|_{H^0_0}.$$

Now it suffices to show that for some positive constant $C(T)$, there holds for all $t \in [0, T]$,

$$\|\tilde{\Theta}^t\|_{X^2}^2 \leq C(T) \|\tilde{\Sigma}_0\|_{H^0_0}^2.$$

First, we see that with an application of Lemma 1.5 with (3.79) and (3.80) there holds, for all $t \in [0, T]$,

$$\sup_{\tau \geq 1} \tau T_\epsilon(\tau; \tilde{\Theta}^t) \leq C(T) \|\tilde{\Sigma}_0\|_{H^0_0}^2,$$

and secondly, by applying the weak form of Lemma 1.5 (see Remark 1.4), we find that for all $t \in [0, T]$,

$$\epsilon \|T_{\epsilon} \Phi^t\|_{M^2_0}^2 \leq C(T) \|\tilde{\Sigma}_0\|_{H^0_0}^2.$$

Together (3.83)-(3.84) establish (3.82). Therefore, inequality (3.18) now follows with $R = \Xi(t^*) = \left(\tilde{W}(t^*), \tilde{\Theta}^t\right)$ and $\varphi^* = M_2(t^*) \geq 0$ (for a suitably updated function $M_2$). This finishes the proof of (C2).

**Lemma 3.14.** Condition (C3) holds for each $\epsilon \in (0, 1]$ and $\omega \in (0, 1)$.

**Proof.** Let $\epsilon \in (0, 1]$ and $\omega \in (0, 1)$. Let $R > 0$ and $\Upsilon_0 = (U_0, \Phi_0) \in V_\epsilon^1$ where $\|\Upsilon_0\|_{V_\epsilon^1} \leq R$. Directly from (3.40), there holds,

$$\|\mathcal{S}_\epsilon(t) \Upsilon_0\|_{V_\epsilon^1} \leq \bar{P}_1,$$

but where now the size of the initial data, $R$, depends on the size of $B^1_\epsilon$. Hence, on the compact interval $[t^*, 2t^*]$, the map $t \mapsto S(t)\Upsilon_0$ is Lipschitz continuous for each fixed $\Upsilon_0 \in B^1_\epsilon$. This means there is a constant $L = L(t^*) > 0$ such that

$$\|\mathcal{S}_\epsilon(t_1) \Upsilon_0 - \mathcal{S}_\epsilon(t_2) \Upsilon_0\|_{H^0_0} \leq L |t_1 - t_2|.$$

Together with the continuous dependence estimate (2.15), (C3) follows. \qed
Remark 3.15. According to Proposition 3.8, for each \( \varepsilon \in (0, 1] \), the semigroup \( \mathcal{S}_\varepsilon(t) : \mathcal{H}_0^0 \rightarrow \mathcal{H}_0^0 \) possesses an exponential attractor, \( \mathfrak{M}_\varepsilon \subset \mathcal{B}_1^1 \), which attracts bounded subsets of \( \mathcal{B}_1^1 \) exponentially fast (in the topology of \( \mathcal{H}_0^0 \)). Moreover, in light of the results in this section—which are uniform in the perturbation parameter \( \varepsilon \)—we now simply accept the corresponding results for the simpler limit Problem \( P_0 \). In this setting we use the notation for the compact absorbing set \( \mathcal{B}_1^0 \) and the exponential attractor \( \mathfrak{M}_0 \) admitted by the semigroup \( S_0(t) : \mathcal{H}_0^0 = \mathbb{R}^2 \rightarrow \mathbb{R}^2 \).

Remark 3.16. In order to show that the attraction property (iii) in Theorem 3.6 also holds—that is, in order to show that the basin of attraction of \( \mathfrak{M}_\varepsilon \) is all of \( \mathcal{H}_0^0 \)—we appeal to the transitivity of the exponential attraction in Proposition A.2 and Theorem 3.17 below.

3.3. Basin of attraction (and global attractors). The main result in this section has two purposes: primary, per the above remark, it will help us show that the exponential attractors we seek attract every bounded subset in \( \mathcal{H}_0^0 \) (not just \( \mathcal{B}_1^1 \)). This property is sometimes not obvious because of the difficulties using spaces involving memory (we refer the reader to Section 1 of this article and to the rate of attraction of \( \mathcal{B}_1^1 \) as found in Lemma 3.9). However, we overcome this problem, partly, by proving a condition on the solution semigroup \( \mathcal{S}_\varepsilon \) that is also essential for the existence of global attractors (also called a universal attractors); we refer to the asymptotic compactness/regularizing of \( \mathcal{S}_\varepsilon \), which happens to occur in our case with an exponential rate. Together, the asymptotic compactness of \( \mathcal{S}_\varepsilon \) (Theorem 3.17 below) and the existence of an absorbing set in \( \mathcal{H}_0^0 \) (Lemma 3.2) will guarantee the existence of a global attractor that is compact in \( \mathcal{H}_0^0 \) and bounded in \( \mathcal{V}_1^2 \).

Theorem 3.17. For each \( \varepsilon \in [0, 1] \), there is a positive constant \( \varrho_1 \) and a monotonically increasing function \( Q(\cdot) \) in which for every nonempty bounded subset \( B \) of \( \mathcal{H}_0^0 \) there holds, for all \( t \geq 0 \),

\[
\text{dist}_{\mathcal{H}_0^0}(\mathcal{S}_\varepsilon(t)B, \mathcal{B}_1^1) \leq Q(\|B\|_{\mathcal{H}_0^0})e^{-\varrho_1 t}.
\]

Proof. Because of the smoothing properties of the associated with the Wentzell parabolic Problem \( P_0 \) (cf. \[13\]), we limit ourselves to the case when \( \varepsilon \in (0, 1] \).

Let \( \varepsilon \in (0, 1] \) and \( B \) be a nonempty bounded subset of \( \mathcal{H}_0^1 \). By recalling Lemma 3.2 we already know that there is a bounded absorbing set that is exponentially attracting in \( \mathcal{H}_0^0 \), i.e., for all \( t \geq 0 \) there holds

\[
\text{dist}_{\mathcal{H}_0^0}(\mathcal{S}_\varepsilon(t)B, \mathcal{B}_1^0) \leq Q(\|B\|_{\mathcal{H}_0^0})e^{-\varrho_0 t},
\]

so owing once again to the transitivity of exponential attraction (cf. Proposition A.2 below) it suffices to show that, for all \( t \geq 0 \),

\[
\text{dist}_{\mathcal{H}_0^0}(\mathcal{S}_\varepsilon(t)\mathcal{B}_1^0, \mathcal{B}_1^1) \leq Q(\mathcal{P}_0) e^{-\varrho_0 t},
\]

for some positive constant \( \varrho_0 \) and for some positive monotonically increasing function \( Q(\cdot) \), each independent of \( \varepsilon \). (Recall from \[3.3\] that \( \mathcal{P}_0 = \sqrt{\mathcal{P}_0 + 1} \) is the radius of \( \mathcal{B}_1^1 \).)

To prove \( (3.85) \), the idea is to show that for each \( \varepsilon \in (0, 1] \) and for each \( \mathcal{Y}_0 \in \mathcal{H}_0^1 \) we can decompose the semigroup

\[
\mathcal{S}_\varepsilon(t)\mathcal{Y}_0 = \mathcal{Z}_\varepsilon(t)\mathcal{Y}_0 + \mathcal{K}_\varepsilon(t)\mathcal{Y}_0
\]

where the operators \( \mathcal{Z}_\varepsilon \) are uniformly (exponentially) decaying to zero and \( \mathcal{K}_\varepsilon \) are uniformly compact (bounded in \( \mathcal{V}_1^2 \)) for large \( t \). This is done in the following lemmas. \( \square \)

The following decomposition and subsequently more general lemmas, as we will allow the datum to belong to any bounded subset of the phase space \( \mathcal{H}_0^0 \), can be seen to follow \[7\] Theorem 6.10—Lemma 6.12 with obvious changes to account for the dynamic boundary conditions with memory. Hence, we will limit the proofs to sketches of the most important details.

First, choose a constant \( M_F > 0 \), based on \[1.39\], \[1.40\], and \[2.1\], so that the map defined by, for all \( s \in \mathbb{R} \),

\[
F_0(s) := F(s) + M_F s,
\]

satisfies, for every \( s \in \mathbb{R} \),

\[
F_0'(s) \geq \begin{pmatrix} 0 \\ 0 \end{pmatrix},
\]

\[ (3.86) \]
Next, let $\Upsilon_0 = (U_0, \Phi_0) \in \mathcal{H}_0^\varepsilon$. Then rewrite Problem $P_\varepsilon$ into the system of equations in $(V, \Psi)$ and $(W, \Theta)$, where $(V, \Psi) + (W, \Theta) = (U, \Phi)$,

$$
\begin{aligned}
\begin{cases}
\partial_t V(t) + \omega A_W^{0,\beta} V(t) + \int_0^\infty \mu_\varepsilon(s) A_W^{a,b} \Psi(t) ds + F_0(U(t)) - F_0(W(t)) = 0, \\
\partial_t \Psi(t) = T_\varepsilon \Psi(t) + V(t), \\
(V(0), \Psi^0) = \Upsilon_0,
\end{cases}
\end{aligned}
$$

(3.87)

and

$$
\begin{aligned}
\begin{cases}
\partial_t W(t) + \omega A_W^{0,\beta} W(t) + \int_0^\infty \mu_\varepsilon(s) A_W^{a,b} \Theta(t) ds + F_0(W(t)) - M_F U(t) = 0, \\
\partial_t \Theta(t) = T_\varepsilon \Theta(t) + W(t), \\
(W(0), \Theta^0) = 0.
\end{cases}
\end{aligned}
$$

(3.88)

In view of Lemmas 3.18 and 3.19 below, we define the one-parameter family of maps, $K_\varepsilon(t) : \mathcal{H}_0^\varepsilon \to \mathcal{H}_0^\varepsilon$, by

$$
K_\varepsilon(t) \Upsilon_0 := (W(t), \Theta^t),
$$

where $(W, \Theta)$ is a solution of (3.88). With such $(W, \Theta)$, we may define a second function $(V, \Psi)$ as the solution of (3.87). Through the dependence of $(V, \Psi)$ on $(W, \Theta)$ and $(U(0), \Phi^0) = \Upsilon_0$, the solution of (3.87) defines a one-parameter family of maps, $Z_\varepsilon(t) : \mathcal{H}_0^\varepsilon \to \mathcal{H}_0^\varepsilon$, defined by

$$
Z_\varepsilon(t) \Upsilon_0 := (V(t), \Psi^t).
$$

Notice that if $(V, \Psi)$ and $(W, \Theta)$ are solutions to (3.87) and (3.88), respectively, then the function $(U(t), \Phi^t) := (V(t), \Psi^t) + (W(t), \Theta^t)$ is a solution to Problem $P_\varepsilon$.

The next result shows that the operators $Z_\varepsilon$ are uniformly decaying to zero in $\mathcal{H}_\varepsilon$.

**Lemma 3.18.** For each $\varepsilon \in (0, 1]$ and $\Upsilon_0 = (U_0, \Phi_0) \in \mathcal{H}_0^\varepsilon$, there exists a unique global weak solution $(V, \Psi) \in C([0, \infty); \mathcal{H}_0^\varepsilon)$ to problem (3.87). Moreover, given $R > 0$, then for all $\Upsilon_0 \in \mathcal{H}_0^\varepsilon$ with $\|\Upsilon_0\|_{\mathcal{H}_0^\varepsilon} \leq R$ for all $\varepsilon \in (0, 1]$, there exists $\nu_0' > 0$, independent of $\varepsilon$, such that, for all $t \geq 0$,

$$
\|Z_\varepsilon(t) \Upsilon_0\|_{\mathcal{H}_0^\varepsilon} \leq Q(R) e^{-\nu_0't}.
$$

(3.89)

**Proof.** The existence of a global weak solution to (3.87) follows as the proof of [18, Theorem 2.3]. It remains to show that (3.89) holds.

The proof is very similar to the proof of Lemma 3.2 save that the assumptions (1.39) - (1.40) become crucial. Indeed, the constant $C$ on the right-hand side of (3.13) vanishes because nonlinear terms now satisfy the bound

$$
\langle F_0(U) - F_0(W), V \rangle_{\mathcal{H}_0^\varepsilon} \geq 0
$$

as here $V = U - W$ and (3.86) holds. \hfill \Box

The following lemma establishes the uniform compactness of the operators $K_\varepsilon$.

**Lemma 3.19.** For each $\varepsilon \in (0, 1]$ and $\Upsilon_0 = (U_0, \Phi_0) \in \mathcal{H}_0^\varepsilon$, there exists a unique global weak solution $(W, \Theta) \in C([0, \infty); \mathcal{H}_0^\varepsilon)$ to problem (3.88). Moreover, given $R > 0$, then for all $\Upsilon_0 \in \mathcal{H}_0^\varepsilon$ with $\|\Upsilon_0\|_{\mathcal{H}_0^\varepsilon} \leq R$ for all $\varepsilon \in (0, 1]$, there holds for all $t \geq 0$,

$$
\|K_\varepsilon(t) \Upsilon_0\|_{\mathcal{H}_0^\varepsilon} \leq Q(R),
$$

Furthermore, the operators $K_\varepsilon$ are uniformly compact in $\mathcal{H}_0^\varepsilon$.

**Proof.** Again, in light of [18, Theorem 2.3], it remains to show that the operators $K_\varepsilon$ are uniformly compact in $\mathcal{H}_0^\varepsilon$.

This time we appeal to Lemma 3.9 whereby only trivial changes are required in the proof in order to show Lemma 3.19 holds. \hfill \Box

**Remark 3.20.** These results—with datum contained to the absorbing set $B_0^\varepsilon$—complete the proof of Theorem 3.17. Consequently, the existence of a (finite dimensional) global attractor $A_\varepsilon, \varepsilon \in (0, 1]$, for $S_\varepsilon$ follows.
Theorem 3.21. For each \( \varepsilon \in (0,1] \), the semigroup \( \mathcal{S}_\varepsilon \) admits a unique global attractor
\[
\mathcal{A}_\varepsilon = \omega(B^0_\varepsilon) := \bigcap_{s \geq 0} \bigcup_{t \geq s} \mathcal{S}_\varepsilon(t)B^0_\varepsilon
\]
in \( \mathcal{H}_\varepsilon^0 \). Moreover, the following hold:
1. For each \( t \geq 0 \), \( \mathcal{S}_\varepsilon(t)\mathcal{A}_\varepsilon = \mathcal{A}_\varepsilon \), and
2. For every nonempty bounded subset \( B \) of \( \mathcal{H}_\varepsilon^0 \),
\[
\lim_{t \to \infty} \text{dist}_{\mathcal{H}_\varepsilon^0}(\mathcal{S}_\varepsilon(t)B, \mathcal{A}_\varepsilon) = 0. \tag{3.90}
\]
3. The global attractor \( \mathcal{A}_\varepsilon \) is bounded in \( \mathcal{V}_\varepsilon^1 \) (hence, compact in \( \mathcal{H}_\varepsilon^0 \)) and trajectories on \( \mathcal{A}_\varepsilon \) are strong solutions (in the sense of Definitions 2.3)
4. The fractal dimension is bounded, uniformly in \( \varepsilon \), i.e.,
\[
\text{dim}_F(\mathcal{A}_\varepsilon, \mathcal{H}_\varepsilon^0) \leq \text{dim}_F(\mathcal{M}_\varepsilon, \mathcal{H}_\varepsilon^0) \leq C < \infty,
\]
for some constant \( C > 0 \) independent of \( \varepsilon \).

Proof. The existence and boundedness of the global attractor for Problem \( P_0 \) can be found in [12, Theorem 2.3] and the references therein. Thus, it suffices to show the result for the perturbation Problem \( P_\varepsilon \), with \( \varepsilon \in (0,1] \). By referring to the standard literature (cf. e.g. [1, 39]) and Lemma 3.2, Lemma 3.9, and Theorem 3.17, the proof is complete. \( \square \)

3.4. Robustness and Hölder continuity of the exponential attractors. What remains in this section is to show that the family of exponential attractors is robust, or Hölder continuous with respect to the perturbation parameter \( \varepsilon \). As a preliminary step, we follow, for example [6, see p. 177] among others, and define the so-called canonical extension map, \( \mathcal{E} : \mathcal{X}^2 \to \mathcal{M}_\varepsilon \), by
\[
\mathcal{E}(U) = 0. \tag{3.91}
\]
With this, define the lift mapping, \( \mathcal{L} : \mathcal{X}^2 \to \mathcal{H}_\varepsilon^0 \), by
\[
\mathcal{L}(U) = (U, \mathcal{E}(U)) = (U, 0). \tag{3.92}
\]

Theorem 3.22. Let the assumptions of Theorem 3.1 be satisfied. For each \( \varepsilon \), the semigroup of solution operators, \( \mathcal{S}_\varepsilon(t) \) admits an exponential attractor \( \mathcal{M}_\varepsilon \) in which the family of compact sets \( \{\mathcal{M}_\varepsilon\}_{\varepsilon \in [0,1]} \) defined by
\[
\mathcal{M}_\varepsilon := \left\{ \begin{array}{ll}
\mathcal{L}\mathcal{M}_0 & \text{for } \varepsilon = 0 \\
\mathcal{M}_\varepsilon & \text{for } \varepsilon \in (0, 1]
\end{array} \right. \tag{3.93}
\]
is Hölder continuous for every \( \varepsilon \in [0,1] \), i.e., there exist constants \( \Lambda > 0 \), \( \tau \in (0,0.1/2] \) independent of \( \varepsilon \), such that, for every \( 0 \leq \varepsilon_2 < \varepsilon_1 \leq 1 \), the symmetric Hausdorff distance satisfies
\[
\text{dist}_{\mathcal{H}_\varepsilon^0}(\mathcal{M}_{\varepsilon_1}, \mathcal{M}_{\varepsilon_2}) \leq \Lambda(\varepsilon_1 - \varepsilon_2)^\tau. \tag{3.94}
\]

Remark 3.23. The symmetric Hausdorff distance between two subsets \( A, B \) of a Banach space \( \mathcal{X} \) is defined as
\[
\text{dist}_{\mathcal{X}}^\text{sym}(A, B) := \max \{\text{dist}_{\mathcal{X}}(A, B), \text{dist}_{\mathcal{X}}(B, A)\}. \nonumber
\]
More precisely, the condition given in (3.93) implies the family of attractors is both upper- and lower-semicontinuous (thus, continuous) at each value of the perturbation parameter \( \varepsilon \in [0,1] \).

In order to prove Theorem 3.22 we will develop the main assumptions of the abstract results found in the seminal works [20, 21]. As in Proposition 3.8 above, the assumptions suited specifically for our needs appear in [21] (H2) and (H3) of Theorem A.2.

As above, the number \( L > 0 \) shown below is used to denote the (local) Lipschitz constant of the mapping \( F : \mathcal{Y}^1 \to \mathcal{X}^2 \).

Proposition 3.24. Let the assumptions of Proposition 3.8 be satisfied. In addition, assume the following:
(C4) The canonical extension map \( \mathcal{E}|_{\mathcal{R}_0^0} : \mathcal{X}^2 \to \mathcal{H}_\varepsilon^0 \) given by (3.97) is Lipschitz continuous.
(C5) There is a constant \( \Lambda_1 = \Lambda_1(L, \Omega, t^*) > 0 \) such that, for all \( t \in [t^*, 2t^*] \) and for all \( \Upsilon_0 = (U_0, \Phi_0) \in B_\varepsilon^1 \),
\[
\|S_\varepsilon(t)\Upsilon_0 - \mathcal{L}S_\varepsilon(t)\mathbb{P}\Upsilon_0\|_{\mathcal{H}_\varepsilon^0} \leq \Lambda_1 \sqrt{\varepsilon}.
\]
Here, \( \mathbb{P} : \mathcal{H}_\varepsilon^0 \to \mathcal{H}_\varepsilon^0 \) denotes the projection defined by, for all \( \Upsilon = (U, \Phi) \in \mathcal{H}_\varepsilon^0 \),
\[
\mathbb{P}\Upsilon = U.
\]

(C6) There is a constant \( \Lambda_2 = \Lambda_2(L, \Omega, t^*) > 0 \) such that, for all \( t \in [t^*, 2t^*] \), \( \Upsilon_0 = (U_0, \Phi_0) \in B_\varepsilon^1 \subset \mathcal{H}_\varepsilon^1 \) and, for all \( 0 < \varepsilon_2 < \varepsilon_1 \leq 1 \),
\[
\|S_{\varepsilon_1}(t)\Upsilon_0 - S_{\varepsilon_2}(t)\Upsilon_0\|_{\mathcal{H}_\varepsilon^0} \leq \Lambda_2 (\varepsilon_1 - \varepsilon_2)^{1/2}.
\]

Then, the family of exponential attractors \((\mathcal{M}_\varepsilon)_{\varepsilon \in [0, 1]}\) is Hölder continuous for every \( \varepsilon \in [0, 1] \) in the sense of Theorem 3.23.

Remark 3.25. The condition (C6) below does not appear in [7], but rather we now borrow [21, (H7) of Theorem 4.4], cf. also [52, (P4) of Theorem 2.1].

Lemma 3.26. Condition (C4) holds.

Proof. Based on the definition of \( \mathcal{E} \) given in [3.91], the result is vacuously true. \( \square \)

The following lemma proves condition (C5) of Proposition 3.24. It shows that the difference between the semigroups \( S_\varepsilon(t) \) and the lifted limit semigroup \( \mathcal{L}S_\varepsilon(t) \) in \( \mathcal{H}_\varepsilon^0 \), on finite time intervals, is of order \( \varepsilon^{1/2} \).

Lemma 3.27. Let \( T > 0 \). For all \( \varepsilon \in (0, 1] \), \( \omega \in (0, 1] \) and \( \Upsilon_0 = (U_0, \Phi_0) \in \mathcal{H}_\varepsilon^0 \) such that \( \|\Upsilon_0\|_{\mathcal{H}_\varepsilon^0} \leq R \)
for all \( \varepsilon \in (0, 1] \), there exists a positive constant \( C(T) \), independent of \( \varepsilon \), but depending on \( \omega \) and \( T \), in which, for all \( t \geq 0 \),
\[
\|S_\varepsilon(t)\Upsilon_0 - \mathcal{L}S_\varepsilon(t)\mathbb{P}\Upsilon_0\|_{\mathcal{H}_\varepsilon^0} \leq C(T)\varepsilon^{1/2}.
\]

Proof. Let \( \hat{\Upsilon}(t) = (\hat{U}(t), \hat{\Phi}(t)) \) denote the solution of Problem \( P_\varepsilon \) corresponding to the initial data \( \Upsilon_0 = (U_0, \Phi_0) \in B_\varepsilon^1 \) and let \( U(t) \) denote the solution of Problem \( P_0 \) corresponding to the initial data \( \mathbb{P}\Upsilon_0 = U_0 \in B_\varepsilon^1 \). With the solution \( U(t) \), define the function \( \Phi(t) \) by the solution to the Cauchy problem,
\[
\begin{cases}
\partial_t \Phi = T_{\varepsilon}\Phi(t) + U(t) \\
\Phi(0) = \Phi_0 - \mathbb{P}\Upsilon_0 = M_\varepsilon^0.
\end{cases}
\]

(3.98)

With the (unique) solution to (3.98) (cf. Corollary 1.13), define \( \hat{\Upsilon}(t) := (U(t), \Phi(t)) \) for all \( t \geq 0 \). Let
\[
\hat{\Delta}(t) = (Z(t), \Theta(t)) := \hat{\Upsilon}(t) - \Upsilon(t) = (\hat{U}(t), \hat{\Phi}(t)) - (U(t), \Phi(t)) = (\hat{U}(t) - U(t), \hat{\Phi}(t) - \Phi(t));
\]

hence, \( \hat{\Delta}(t) = (Z(t), \Theta(t)) \) satisfies the system
\[
\begin{cases}
\partial_t Z(t) + \omega \Lambda_{W}^{0, \beta} Z(t) + \int_0^t \mu_\varepsilon(s) \Lambda_{W}^{\alpha, \beta} \Theta(s) ds + F(\hat{U}(t)) - F(U(t)) = -\int_0^t \mu_\varepsilon(s) \Lambda_{W}^{\alpha, \beta} \Phi'(s) ds, \\
\partial_t \Theta(s) = T_{\varepsilon}\Theta(t) + Z(t), \\
(Z(0), \Theta(0)) = 0.
\end{cases}
\]

(3.99)

Multiply (3.99) 1 by \( Z \) in \( \mathcal{X}^2 \) and (3.99) 2 by \( \Lambda_{W}^{\alpha, \beta} \Theta(t) \) in \( L_{\mu_\varepsilon}(\mathbb{R}_+; \mathcal{X}^2) \), summing the resulting identities and estimating as in the above arguments, it is not hard to see that there holds, for almost all \( t \geq 0 \),
\[
\frac{1}{2} \frac{d}{dt} \left\{ \|Z\|^2_{\mathcal{X}^2} + \|\Theta\|^2_{M_\varepsilon^1} \right\} + \omega \|Z\|^2_{\mathcal{V}_1} + \frac{\delta}{2\varepsilon} \|\Theta\|^2_{M_\varepsilon^1} \leq -\left\langle F(\hat{U}) - F(U), Z \right\rangle_{\mathcal{X}^2} + \omega \alpha \|z\|^2_{L^2(\Omega)} - \int_0^t \mu_\varepsilon(s) \left\langle \Lambda_{W}^{\alpha, \beta} \Phi'(s), Z \right\rangle_{\mathcal{X}^2} ds.
\]

(3.100)

Recall, with (3.99) we obtain,
\[
-\left\langle F(\hat{U}) - F(U), Z \right\rangle_{\mathcal{X}^2} \leq M_F \|Z\|^2_{\mathcal{X}^2}.
\]

(3.101)
For the remaining term on the right-hand side, we apply the definition of the norm and Young’s inequality to find,

\[ -\int_0^\infty \mu_\varepsilon(s) \left( A_\varepsilon^\alpha \beta \Phi^t(s), Z \right)_{X_\varepsilon^2} \, ds = -\int_0^\infty \mu_\varepsilon(s) \left( \Phi^t(s), Z \right)_{Y_1} \, ds \leq \|Z\|_{Y_1} \|\Phi^t\|_{M^t_1} \leq \omega \|Z\|_{Y_1}^2 + \frac{1}{4\omega} \|\Phi^t\|_{M^t_1}^2. \]

Recall that, by (3.17), there holds for all \( t \geq 0 \),

\[ \|\Phi^t\|_{M^t_1}^2 \leq \|\Phi^0\|_{M^t_1}^2 e^{-\delta t/2\varepsilon} + C\varepsilon, \]  

(3.102)

where \( C > 0 \) depends on the bound \( \overline{P}_0 \), but is uniform in \( \varepsilon \) and \( t \). Collecting (3.100)-(3.102) yields,

\[ \frac{d}{dt} \left\{ \|Z\|_{X_2}^2 + \|\Theta^t\|_{M^t_1}^2 \right\} + \delta \|\Theta^t\|_{M^t_1}^2 \leq 2\left( \omega\alpha + M_F \right) \|Z\|_{X_2}^2 + C\varepsilon \|Z\|_{X_2}^2 + C\varepsilon \left( \|\Phi^0\|_{M^t_1}^2 e^{-\delta t/2\varepsilon} + \varepsilon \right). \]  

(3.103)

Integrating (3.103) with respect to \( t \) on the interval \([0, T]\), for \( T > 0 \), and then applying the initial conditions (3.100), as well as the uniform bound (3.100), we have,

\[ \|Z(t)\|_{X_2}^2 + \|\Theta^t\|_{M^t_1}^2 \leq \int_0^T C\|Z(\tau)\|_{X_2}^2 \, d\tau + C(T)\varepsilon. \]  

(3.104)

Next we seek an appropriate bound on the term with \( Z \). It follows from (3.104) and Gronwall’s inequality that there holds, for all \( t \geq 0 \) and for all \( \varepsilon \in (0, 1] \),

\[ \|Z(t)\|_{X_2}^2 \leq C(T)\varepsilon, \]  

(3.105)

where \( C > 0 \) depends on \( \omega \), \( \delta \), and of course \( T \), but not \( \varepsilon \).

Returning to (3.104), we now see that there holds, for all \( t \in [\sqrt{\varepsilon}, T] \) and for all \( \varepsilon \in (0, 1] \),

\[ \| (Z(t), \Theta^t) \|_{H^2_\varepsilon}^2 \leq C(T)\varepsilon. \]  

(3.106)

Therefore (3.97) follows. This finishes the proof. \( \square \)

We will establish the Hölder continuity with the following lemma. With regard to [21], in particular, hypothesis (H7) of Theorem 4.4 there, we do not perform an \( \varepsilon \)-scaling of the memory variable.

**Lemma 3.28.** *(Condition (C6)) holds.*

**Proof.** Assume \( 0 < \varepsilon_2 < \varepsilon_1 \leq 1 \). Let \( \Upsilon_0 = (U_0, \Phi^0) \in B^1_\varepsilon \). Let \( \Upsilon(t) = (U(t), \Phi^t) \) denote the solution of Problem \( P_{\varepsilon_1} \) corresponding to the initial datum \( \Upsilon_0 \) and let \( \tilde{\Upsilon}(t) = (\tilde{U}(t), \tilde{\Phi}^t) \) denote the solution Problem \( P_{\varepsilon_2} \) corresponding to the same initial datum \( \Upsilon_0 \). Let

\[ \tilde{\Delta}(t) = (\tilde{Z}(t), \tilde{\Theta}^t) := \tilde{\Upsilon}(t) - \tilde{\Upsilon}(t) \]

\[ = (\tilde{U}(t), \tilde{\Phi}^t) - (\tilde{U}(t), \tilde{\Phi}^t) \]

\[ = (\tilde{U}(t) - \tilde{U}(t), \tilde{\Phi}^t - \tilde{\Phi}^t). \]

\[ \begin{align*}
\partial_t \tilde{Z} + \omega A^0_\varepsilon \tilde{Z} + \int_0^\infty \mu_\varepsilon(s) A^\alpha_\varepsilon \beta \tilde{\Theta}^t(s) ds + F(\tilde{U}) - F(\tilde{V}) &= \int_0^\infty (\mu_\varepsilon(s) - \mu_\varepsilon(s)) A^\alpha_\varepsilon \beta \tilde{\Phi}^t(s) ds \\
\partial_\varepsilon \tilde{\Theta}^t(s) &= T_{\varepsilon_2} \tilde{\Theta}^t(s) + \tilde{Z}(t) \\
\tilde{Z}(0) &= 0, \quad \tilde{\Theta}^0 = 0.
\end{align*} \]  

(3.107)

Observe, by the definition of \( T_\varepsilon \), \((T_{\varepsilon_1} - T_{\varepsilon_2}) \tilde{\Phi}^t(s) = 0 \). We proceed in the usual fashion by multiplying (3.107)_1 by \( \tilde{Z} \) in \( X_\varepsilon^2 \), and multiplying equation (3.107)_2 by \( A_\varepsilon^\alpha \beta \tilde{\Theta}^t \) in \( L_{\mu_\varepsilon_2}(\mathbb{R}_+; X_\varepsilon^2) \), summing the results,
we arrive at the identity,

\[
\frac{1}{2} \frac{d}{dt} \left\{ \| \vec{Z} \|^2_{\mathcal{X}^2} + \| \vec{\Theta} \|^2_{\mathcal{M}^0_{\tau_1}} \right\} + \\
+ \omega \| \vec{Z} \|^2_{\mathcal{Y}_2} - \int_0^\infty \mu_{\varepsilon_1}(s) \left\langle T_{\varepsilon_1} \vec{\Theta}(s), A_W^{\alpha, \beta} \vec{\Theta}(s) \right\rangle_{\mathcal{X}^2} \, ds \\
= \int_0^\infty (\mu_{\varepsilon_2}(s) - \mu_{\varepsilon_1}(s)) \left\langle \vec{\Psi}(s), \vec{Z}(t) \right\rangle_{\mathcal{X}^2} \, ds + \\
- \left\langle F \left( \vec{U} \right) - F \left( \vec{V} \right), \vec{Z} \right\rangle_{\mathcal{X}^2} + \omega \alpha \| \vec{z} \|^2_{L^2(\Omega)}.
\]  

(3.108)

We estimate from here along the usual lines to obtain, for almost all \( t \geq 0 \),

\[
- \int_0^\infty \mu_{\varepsilon_1}(s) \left\langle T_{\varepsilon_1} \vec{\Theta}(s), A_W^{\alpha, \beta} \vec{\Theta}(s) \right\rangle_{\mathcal{X}^2} \, ds \leq \frac{\delta}{2\varepsilon_1} \| \vec{\Theta} \|^2_{\mathcal{M}^1_{\tau_1}}.
\]  

(3.109)

We know there is a constant \( M_F > 0 \) in which,

\[
- \left\langle F \left( \vec{U} \right) - F \left( \vec{V} \right), \vec{Z} \right\rangle_{\mathcal{X}^2} \leq M_2 \| \vec{Z} \|^2_{\mathcal{X}^2},
\]  

(3.110)

and finally, with the fact that \( \vec{\Psi} \) is uniformly bounded on \( B_{\varepsilon_1} \),

\[
\int_0^\infty (\mu_{\varepsilon_2}(s) - \mu_{\varepsilon_1}(s)) \left\langle \vec{\Psi}(s), \vec{Z}(t) \right\rangle_{\mathcal{X}^2} \, ds = \frac{\varepsilon_1 - \varepsilon_2}{\varepsilon_1 \varepsilon_2} \int_0^\infty \mu_{\varepsilon_1}(s) \left\langle \vec{\Psi}(s), \vec{Z}(t) \right\rangle_{\mathcal{X}^2} \, ds \\
\leq C \frac{\varepsilon_1 - \varepsilon_2}{\varepsilon_2} \| \vec{Z} \|^2_{\mathcal{X}^2} \| \vec{\Psi} \|^2_{\mathcal{M}^1_{\tau_1}} \\
\leq \frac{\varepsilon_1 - \varepsilon_2}{\varepsilon_2} Q(R_1) + \frac{1}{2} \| \vec{Z} \|^2_{\mathcal{X}^2},
\]  

(3.111)

where \( R_1 > 0 \) is the radius of the absorbing set \( B_{\varepsilon_1} \). After applying (3.109)–(3.111), we obtain the differential inequality,

\[
\frac{d}{dt} \left\{ \| \vec{Z} \|^2_{\mathcal{X}^2} + \| \vec{\Theta} \|^2_{\mathcal{M}^1_{\tau_1}} \right\} \leq 2 \left( M_2 + \omega + 1 \right) \| \vec{Z} \|^2_{\mathcal{X}^2} + C \| \vec{\Theta} \|^2_{\mathcal{M}^1_{\tau_1}} + \frac{\varepsilon_1 - \varepsilon_2}{\varepsilon_2} Q(R_1),
\]  

(3.112)

where \( M_3 := \max \{ 2(M_2 + \omega + 1), C \} > 0 \). We now integrate (3.112) with respect to \( t \) over \([0, T]\) which in turn yields the Gronwall-type estimate, for all \( t \in [0, T] \)

\[
\left\| \left( \vec{Z}(t), \vec{\Theta}(t) \right) \right\|_{\mathcal{H}^0_{\tau_1}} \leq \sqrt{\frac{\varepsilon_1 - \varepsilon_2}{\varepsilon_2} Q(R_1) \left( e^{M_3 T} - 1 \right)}.
\]

Therefore, (3.106) follows. \( \square \)

Remark 3.29. In conclusion, by Theorem 3.22 the semigroup \( \mathcal{S}_\varepsilon \) generated by the solutions of Problem \( P_\varepsilon \) admits a robust family of exponential attractors \( (\mathcal{M}_\varepsilon)_{\varepsilon \in [0, 1]} \) in \( \mathcal{H}^0_{\tau_1} \), Hölder continuous at each \( \varepsilon \in [0, 1] \).

APPENDIX A.

For the reader’s convenience we report some important results that are needed in the article.

The following lemma is from [15] Lemma 2.2. It is in the spirit of the \( H^s \)-elliptic regularity estimate that can be found in [30] Theorem II.5.1.

**Lemma A.1.** Consider the linear boundary value problem,

\[
\begin{cases}
- \Delta u + \alpha u = \psi_1 & \text{in } \Omega, \\
- \Delta_{\Gamma} u + \partial_n u + \beta u = \psi_2 & \text{on } \Gamma.
\end{cases}
\]  

(3.20)

If \((\psi_1, \psi_2)^T \in H^s(\Omega) \times H^s(\Gamma), s \geq 0 \) and \( s + \frac{1}{2} \notin \mathbb{N} \), then the following estimate holds for some constant \( C > 0 \),

\[
\| u \|_{H^{s+2}(\Omega)} + \| u \|_{H^{s+2}(\Gamma)} \leq C \left( \| \psi_1 \|_{H^s(\Omega)} + \| \psi_2 \|_{H^s(\Gamma)} \right).
\]  

(3.21)

The following result is the so-called transitivity property of exponential attraction from [10] Theorem 5.1).
Proposition A.2. Let \((X, d)\) be a metric space and let \(S_t\) be a semigroup acting on this space such that
\[
d(S_t x_1, S_t x_2) \leq C e^{Kt} d(x_1, x_2),
\]
for appropriate constants \(C\) and \(K\). Assume that there exists three subsets \(U_1, U_2, U_3 \subset X\) such that
\[
dist_X(S_t U_1, U_2) \leq C_1 e^{-\alpha t}, \quad \text{dist}_X(S_t U_2, U_3) \leq C_2 e^{-\alpha_2 t}.
\]
Then
\[
dist_X(S_t U_1, U_3) \leq C' e^{-\alpha' t},
\]
where \(C' = CC_1 + C_2\) and \(\alpha' = \frac{\alpha_1 \alpha_2}{K + \alpha_1 + \alpha_2}\).

The following statement refers to a frequently used Grönwall-type inequality that is useful when working with dissipation arguments. We also refer the reader to [5, Lemma 2.1], [26, Lemma 2.2], [33, Lemma 5].

Proposition A.3. Let \(\Lambda : \mathbb{R}_+ \rightarrow \mathbb{R}_+\) be an absolutely continuous function satisfying
\[
\frac{d}{dt} \Lambda(t) + 2\eta \Lambda(t) \leq h(t) \Lambda(t) + k,
\]
where \(\eta > 0\), \(k \geq 0\) and \(\int_s^t h(\tau) d\tau \leq \eta(t-s) + m\), for all \(t \geq s \geq 0\) and some \(m \geq 0\). Then, for all \(t \geq 0\),
\[
\Lambda(t) \leq \Lambda(0) e^{m} e^{-\eta t} + \frac{ke^m}{\eta}.
\]

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