On Superfield Covariant Quantization in General Coordinates

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Abstract

We propose a natural extension of the BRST–antiBRST superfield covariant scheme in general coordinates. Thus, the coordinate dependence of the basic scalar and tensor fields of the formalism is extended from the base supermanifold to the complete set of superfield variables.

1 Introduction

The principle of extended BRST symmetry applied to general gauge theories has resulted in various schemes of covariant quantization \textsuperscript{1, 2, 3}. It turns out that these schemes can be combined within the formalism \textsuperscript{4, 5, 6}, which realizes the modified triplectic algebra \textsuperscript{3} in general coordinates. The differential operators $\Delta^a$, $V^a$, $U^a$ that form this algebra are constructed \textsuperscript{6} in terms of a nondegenerate antisymmetric tensor $\omega_{ij}$, a symmetric tensor $g_{ij}$ and a scalar $\rho$, defined on a supermanifold with a symmetric connection (Christoffel symbols). In Darboux coordinates, this supermanifold (base supermanifold) is parameterized by the fields and antifields $(\phi^A, \bar{\phi}^A)$ used in the quantization schemes \textsuperscript{1, 2, 3}. It proves possible to fulfill the relations of the modified triplectic algebra in case the tensor field $\omega_{ij}$ endows the base supermanifold with a symplectic structure respected by the symmetric connection (covariant derivative). In this respect, the base supermanifold can be viewed as a Fedosov supermanifold \textsuperscript{6}, which generalizes the notion of Fedosov manifolds \textsuperscript{7}. The properties of such supermanifolds have been recently studied in the papers \textsuperscript{8}.

In the original work \textsuperscript{4} on the modified triplectic quantization in general coordinates, the authors raised the problem of a superfield description of their formalism. This task calls for an extension of the geometric contents of \textsuperscript{4, 5, 6} to the complete set of variables of \textsuperscript{1, 2, 3}, which can be regarded as superfield components in a superspace with a pair of anticommuting coordinates \textsuperscript{9}. At present, two different approaches \textsuperscript{10, 11} to the mentioned problem have been proposed. In \textsuperscript{10}, a superfield description of $\Delta^a$, $V^a$, $U^a$ is suggested, using a covariant differentiation in terms of superfield variables. This formalism leaves intact the basic ingredients of \textsuperscript{4, 5, 6} as functions on the base supermanifold (accordingly interpreted as a Fedosov supermanifold). On the contrary, in \textsuperscript{11} it is proposed to extend the structure of a Fedosov supermanifold to the superfield case. It turns out, however, that the resulting Christoffel symbols \textsuperscript{11} cannot be regarded as connection coefficients having correct properties under coordinate transformations. Thus, the approach \textsuperscript{11} faces difficulties.

In this respect, the aim of the present work is to examine an alternative extension of the superfield approach \textsuperscript{10}. Namely, we consider extended counterparts of the fields $\omega_{ij}$, $g_{ij}$, $\rho$, defined on the complete supermanifold of variables \textsuperscript{11, 2, 3}, and realize the operators subject to the modified triplectic algebra in terms of such fields. In the limit when the coordinate dependence of the mentioned fields is restricted to the base supermanifold, one recovers the structure of a Fedosov supermanifold, and the present quantization scheme reduces to that of \textsuperscript{10}.

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2 Basic Objects

In this section, we recall the basic ingredients of \cite{10}, namely, the notion of a base supermanifold, the related construction of a \textit{triplectic supermanifold}, and its superfield formulation. In particular, we remind the basics of tensor analysis on supermanifolds (for details, see the monograph \cite{12} and papers \cite{6, 8}). We use DeWitt’s condensed notation \cite{13} and designations adopted in \cite{10}. Left-hand derivatives are denoted by \( \partial_i A = \partial A / \partial x^i \), and right-hand derivatives are labeled by the subscript “\( r \)”, with the corresponding notation \( A_{\bar r} = \partial A / \partial \bar x^r \). We assume that covariant derivatives, \( \nabla \), and other operators defined on tensor fields \textit{act from the right}: \( A \nabla \); besides, when necessary, the action of an operator from the right is indicated by an arrow: \( \overrightarrow{\nabla} \). The Grassmann parity of a quantity \( A \) is denoted by \( \epsilon (A) \).

2.1 Triplectic Supermanifold

Let us consider a supermanifold \( \mathcal{M}, \dim \mathcal{M} = N = 2n \), with local coordinates \((x^i, \theta^a)\), where the additional coordinates \( \theta^a \) are combined into \( \text{Sp}(2) \)-doublets (labeled by the index \( a = 1, 2 \)) and possess the Grassmann parity, \( \epsilon (\theta^a) = \epsilon_+ + 1 \), opposite to that of \( x^i \). We demand that the coordinates \( \theta^a \) transform as vectors under a change of coordinates on the supermanifold \( \mathcal{M} \), indeed,\(^1\)

\[
\bar{x}^i = \bar{x}^i(x), \quad \bar{\theta}^a = \theta^a \frac{\partial \bar{x}^i}{\partial x^j}.
\]

On the supermanifold \( \mathcal{M} \), one defines a tensor field of type \((n, m)\) and rank \( n + m \) as an object which in any local coordinate system \((x, \theta)\) is given by a set of functions \( T^{i_1 \ldots i_n}_{j_1 \ldots j_m}(x, \theta) \), with Grassmann parity \( \epsilon (T^{i_1 \ldots i_n}_{j_1 \ldots j_m}) = \epsilon (T) + \epsilon_{i_1} + \cdots + \epsilon_{i_n} + \epsilon_{j_1} + \cdots + \epsilon_{j_m} \), that transform under a change of coordinates \((x, \theta) \rightarrow (\bar{x}, \bar{\theta})\) as a tensor field, of the same rank and type, defined on the supermanifold \( \mathcal{M} \), namely,

\[
\bar{T}^{i_1 \ldots i_n}_{j_1 \ldots j_m} = T^{i_1 \ldots i_n}_{j_1 \ldots j_m} \left( \begin{array}{c}
\partial_{a} x^{k_1} \\
\partial_{a} x^{k_2} \\
\vdots \\
\partial_{a} x^{k_{m-1}} \\
\partial_{a} x^{k_m}
\end{array} \right) \left( \begin{array}{c}
\partial_{\bar{a}} \bar{x}^{l_1} \\
\partial_{\bar{a}} \bar{x}^{l_2} \\
\vdots \\
\partial_{\bar{a}} \bar{x}^{l_{n-1}} \\
\partial_{\bar{a}} \bar{x}^{l_n}
\end{array} \right) \left( \begin{array}{c}
\partial_{\bar{a}} \bar{x}^{l_1} \\
\partial_{\bar{a}} \bar{x}^{l_2} \\
\vdots \\
\partial_{\bar{a}} \bar{x}^{l_{n-1}} \\
\partial_{\bar{a}} \bar{x}^{l_n}
\end{array} \right) \left( \begin{array}{c}
\partial x^{j_1} \\
\partial x^{j_2} \\
\vdots \\
\partial x^{j_m}
\end{array} \right).
\]

Accordingly, a covariant derivative on \( \mathcal{M} \) is defined as an operation \( \nabla_i \) that maps a tensor field of type \((n, m)\) into a tensor field of type \((n, m + 1)\) and reduces to the usual derivative \( \partial_i / \partial x^i \) in a local Cartesian system on \( \mathcal{M} \). Explicitly, the operation \( \nabla_i \) has the form of a \( \theta \)-extension of the covariant derivative \( \nabla \) on the supermanifold \( \mathcal{M} \),

\[
\nabla_i^\mathcal{M} = \frac{\partial^\mathcal{M} T^{i_1 \ldots i_n}_{j_1 \ldots j_m}}{\partial \theta^a} \Gamma^k_m (\epsilon_k + \epsilon_m + 1).
\]

\[\text{(1)}\]

where \( \nabla_i^\mathcal{M} \) maps a tensor field \( T^{i_1 \ldots i_n}_{j_1 \ldots j_m}(x) \) of type \((n, m)\) into a tensor field of type \((n, m + 1)\) according to

\[
T^{i_1 \ldots i_n}_{j_1 \ldots j_m} \nabla^\mathcal{M}_k = T^{i_1 \ldots i_n}_{j_1 \ldots j_m} + \sum_{r=1}^{n+m} \epsilon_r + \epsilon_m \Gamma^i_k (\epsilon_r + \epsilon_m + 1) \left( \sum_{p=1}^{n+m} \epsilon_p \right) - \sum_{s=1}^{n+m} \epsilon_s \Gamma^i_k (\epsilon_s + 1).
\]

\[\text{(2)}\]

\(^1\text{In} \cite{6, 8, 10}, \text{the supermanifold} \mathcal{M} \text{is parameterized by coordinates} \((x^i, \theta^a)\), \text{where} \theta^a \text{transform as covectors}, \text{namely,} \quad \bar{\theta}^a = \theta^a \frac{\partial \bar{x}^i}{\partial x^j}. \text{Instead, in the paper} \cite{10} \text{the parameterization} \((x^i, \theta^a)\) \text{is used, since it is more convenient for a superfield formulation (see Subsection 2.2).}
In (1), (2), the functions \( M \Gamma^k_{ij}(x) \) are generalized Christoffel symbols (connection coefficients), having the transformation law

\[
M \Gamma^k_{ij} = (-1)^{\epsilon_i \epsilon_j} M \Gamma^k_{ji}.
\]

In case a local Cartesian system on \( M \) does exist, the connection coefficients \( M \Gamma^k_{ij}(x) \) possess the property of (generalized) symmetry:

\[
M \Gamma^k_{ij} = (-1)^{\epsilon_i \epsilon_j} M \Gamma^k_{ji}.
\]

With this in mind, the consideration will be restricted to symmetric connections.

Since \( x^i \) and \( \theta^{\alpha}_a \) are independent coordinates, expressions (1), (2) imply that the vectors \( \theta^{\alpha}_a \) are covariantly constant:

\[
\theta^{\alpha}_a \nabla_j = 0.
\]

From (1), (3), it follows that a (generalized) commutator \( [\nabla_i, \nabla_j] = \nabla_i \nabla_j - (-1)^{\epsilon_i \epsilon_j} \nabla_j \nabla_i \) acting on a scalar field \( T(x, \theta) \), can be written as

\[
T^M_{\nabla_i, \nabla_j} = (-1)^{\epsilon_m(\epsilon_n+1)} \frac{\partial T}{\partial \theta^m} \theta^m R^M_{n \, m} m_{ij},
\]

where \( R^i_{mjk}(x) \) is a curvature tensor on the supermanifold \( M \), defined by the action of a commutator of covariant derivatives \( \nabla_i \) on a vector field \( T^i(x) \) according to

\[
T^i_{\nabla_j, \nabla_k} = -(-1)^{\epsilon_m(\epsilon_n+1)} T^m R^i_{m \, jk}.
\]

The curvature tensor has the explicit form

\[
R^i_{mjk} = -\Gamma^i_{mj,k} + \Gamma^i_{mk,j} - \Gamma^i_{lj} \Gamma^l_{mk} (-1)^{\epsilon_i \epsilon_k} + \Gamma^i_{ij} \Gamma^l_{mk} (-1)^{\epsilon_i \epsilon_m} - \Gamma^i_{ij} \Gamma^l_{mk} (-1)^{\epsilon_k (\epsilon_m + \epsilon_l)},
\]

and obeys a property of (generalized) antisymmetry and a (super) Jacobi identity:

\[
R^i_{mjk} = -(-1)^{\epsilon_j \epsilon_k} R^i_{mkj}, \quad (-1)^{\epsilon_j \epsilon_l} R^i_{jkl} + \text{cycle} (j, k, l) \equiv 0.
\]

In what follows, we call \( M \) and \( \mathcal{M} \) the base and triplectic supermanifolds, respectively, and refer to \( \nabla_i \) as the triplectic covariant derivative.

### 2.2 Superfield Description

The complete set of variables arising in various quantization schemes (1, 2, 3) based on extended BRST symmetry can be presented as \( (\phi^A, \phi_A; \pi^A, \phi^{Aa}; \lambda^A, J_A) = (x^i, \theta^{\alpha}_a, y^i), \quad i = 1, 2, \ldots, N = 2n, \epsilon(x^i) = \epsilon(y^i) = \epsilon, \epsilon(\theta^{\alpha}_a) = \epsilon + 1 \). This set consists of the field-antifield variables \( (\phi^A, \phi_A, \phi^{Aa}), \pi^A, \lambda^A \), Lagrange multipliers \( (\lambda^A, \pi^A) \), and sources \( J_A \) to the fields. In the superfield formulation (9) of extended BRST symmetry, the variables \( (x^i, \theta^{\alpha}_a, y^i) \) are regarded as components of superfields \( z^i(\eta) \) in a superspace with Grassmann coordinates \( \eta_a \),

\[
z^i(\eta) = x^i + \eta^a \theta^{\alpha}_a + \eta^2 y^i, \quad \eta^2 \equiv \frac{1}{2} \eta_a \eta^a,
\]

where raising the \( Sp(2) \)-indices is performed with the help of the antisymmetric second-rank tensor \( \varepsilon^{ab} \), \( \varepsilon^{ab} \eta_b = \eta_a, \varepsilon^{[ab} \varepsilon_{cb]} = \delta^a_b \).

Let us identify the components \( (x^i, \theta^{\alpha}_a, y^i) \) with local coordinates on a supermanifold \( \mathcal{N} \), \( \text{dim } \mathcal{N} = 4N \), where the submanifold with coordinates \( (x^i, \theta^{\alpha}_a) \) is chosen as a triplectic supermanifold. At
the same time, we define the transformations of the additional coordinates \( y^i \), that accompany the transformations \((x, \theta) \rightarrow (\bar{x}, \bar{\theta})\), to be trivial:

\[
\bar{x}^i = \bar{x}^i(x), \quad \bar{\theta}^i_a = \theta^i_a \frac{\partial \bar{x}^i}{\partial x^i}, \quad \bar{y}^i = y^i.
\]

By analogy with the triplectic supermanifold \( \mathcal{M} \), a tensor field of type \((n, m)\) and rank \(n + m\) on the supermanifold \( \mathcal{N} \) is defined as an object which in any local coordinate system \((x, \theta, y)\) is given by a set of functions \( T^{i_1 \ldots i_n}_{j_1 \ldots j_m}(z) \) that transform as a tensor field on the base supermanifold \( M \). With this in mind, one can define on \( \mathcal{N} \) a superfield extension \( \mathcal{D}_i(\eta) \) of the triplectic covariant derivative \( \nabla_i \). Namely, one introduces \( \mathcal{D}_i(\eta) \) as an operation that maps a tensor field of type \((n, m)\) and reduces in a local Cartesian system on \( M \) to the superfield derivative\(^2\)

\[
\frac{\bar{\omega}}{\partial z^i(\eta)} = \frac{\omega}{\partial x^i} \eta^2 + \frac{\omega}{\partial \theta^a} \eta_a,
\]

defined with respect to variations \( \delta z^i(\eta) = \delta x^i + \eta^a \delta \theta^a \) induced by \((x, \theta, y) \rightarrow (\bar{x}, \bar{\theta}, \bar{y})\). The derivative \( \mathcal{D}_i(\eta) \) has the explicit form

\[
\bar{\mathcal{D}}_i(\eta) = \nabla_i \eta^2 + \frac{\partial}{\partial \theta^a} \eta_a,
\]

where each term of the \( \eta \)-expansion transforms as a covector with respect to \((x, \theta, y) \rightarrow (\bar{x}, \bar{\theta}, \bar{y})\).

Using \( \mathcal{D}_i(\eta) \), one can rewrite the equalities \((6)\), \((8)\) in the form

\[
\frac{\partial z^i}{\partial \eta^a} \mathcal{D}_j(\eta^a) = \delta^i_j \eta^a,
\]

and

\[
T \left[ \mathcal{D}_i(\eta^a), \mathcal{D}_j(\eta^b) \right] = (-1)^{\epsilon_m(\epsilon_n + 1)}(\eta^a)^2 (\eta^b)^2 \frac{\partial \epsilon}{\partial \eta^a} \frac{\partial z^{mn}}{\partial \eta^m} R^{n}_{mij},
\]

where \( T(z) \) is a scalar field, and \( R^{n}_{mij} \) is the curvature tensor \((3)\).

### 3 Extended Superfield Realization of (Modified) Triplelectic Algebra

In this section, we shall apply the above ingredients in order to construct an extended realization of the triplectic and modified triplectic algebras \([2, 3]\). To this end, we recall that the triplectic algebra \([2]\) is formed by two doublets of first- and second-order operators, \( \hat{V}^a \) and \( \hat{\Delta}^a \), respectively, having the Grassmann parity \( \epsilon(V^a) = \epsilon(\Delta^a) = 1 \) and obeying the relations

\[
\Delta^{a \Delta b} = 0, \quad V^{a \Delta b} = 0, \quad V^a \Delta^b + \Delta^b V^a = 0,
\]

whereas the modified triplelectic algebra \([3]\) involves an additional doublet of first-order operators \( \hat{U}^a \), \( \epsilon(U^a) = 1 \), and has the form

\[
\Delta^{a \Delta b} = 0, \quad V^{a \Delta b} = 0, \quad U^a U^b = 0, \quad V^a \Delta^b + \Delta^b V^a = 0, \quad U^a \Delta^b + U^b \Delta^a = 0, \quad U^a V^b + V^a U^b = 0.
\]

In \((2)\), \((10)\), the curly brackets stand for symmetrization with respect to the enclosed indices.

Using the second-order operators \( \Delta^a \), one can define a pair of bilinear operations \(( , )^a\),

\[
(F, G)^a = (-1)^{\epsilon(G)}(FG) \Delta^a - (-1)^{\epsilon(G)}(F \Delta^a) G - F(G \Delta^a),
\]

which form a set of antibrackets, similar to those introduced in the \(Sp(2)\)-covariant formalism \([1]\). Thus, the operations \(( , )^a\), possess the Grassmann parity \( \epsilon((F, G)^a) = \epsilon(F) + \epsilon(G) + 1 \) and obey the symmetry property

\[
(F, G)^a = -(-1)^{\epsilon(G) + 1}(\epsilon(F) + 1)(G, F)^a,
\]

\(^2\)As usual, we assume that \( \delta T(z) = \int d^2 \eta \frac{\delta \mathcal{D}_i}{\delta z^i(\eta)} \delta z^i(\eta) \) and \( \int d^2 \eta = \int d^2 \eta \eta^a = 0, \int d^2 \eta \eta^a \eta^b = \delta^{ab} \).
as well as the Leibniz rules

\[(F,GH)^a = (F,G)^a H + (F,H)^a G(-1)^\epsilon(G)\epsilon(H),\]
\[(F,G)^{[a}D^{b]} = (F,GD^{[a}b) - (FD^{[a},G)^b(-1)^\epsilon(G), \quad D^a \equiv \{\Delta^a, U^a, V^a\}\]

and the Jacobi identity

\[(F,(G,H)^{[a})^{b]}(-1)^{(\epsilon(F)+1)(\epsilon(H)+1)} + \text{cycle}(F,G,H) \equiv 0.\]

In general coordinates, the operators [9], [10] and the antibrackets [11] can be constructed [6, 10]
in terms of a scalar \(\rho(x)\) and tensor \(\omega_{ij}(x), g_{ij}(x)\) fields defined on the base supermanifold \(M\). At the same time, within the superfield description [10] the objects \(\rho, \omega_{ij}, g_{ij}\) are formally identified with fields \(\mathcal{R}, \Omega_{ij}, G_{ij}\) on the larger supermanifold \(\mathcal{N}\). In contrast to [10], we shall present a superfield realization of [9], [11] in terms of extended counterparts of \(\rho, \omega_{ij}, g_{ij}\), inherently defined on \(\mathcal{N}\). The corresponding quantization procedure then follows the approach [10].

### 3.1 Extended Realization

Let us equip the supermanifold \(\mathcal{N}\) with an even scalar field \(\mathcal{R}(z)\), as well as with even tensor fields \(G_{ij}(z)\) and \(\Omega_{ij}(z)\), the latter having the inverse\(^3\) \(\Omega^{ij}(z)\), \(\epsilon(G_{ij}) = \epsilon(\Omega_{ij}) = \epsilon(\Omega^{ij}) = \epsilon_i + \epsilon_j,\)

\[
\Omega_{ik}\Omega^{kj}(-1)^{\epsilon_i} = \delta^i_j, \quad \Omega^{ik}\Omega_{kj}(-1)^{\epsilon_k} = \delta^j_k.
\]

We demand that the fields \(G_{ij}(z)\) and \(\Omega_{ij}(z)\) obey the following properties of generalized (anti)symmetry:

\[G_{ij} = (-1)^{\epsilon_i\epsilon_j}G_{ji}, \quad \Omega_{ij} = -(\epsilon_i\epsilon_j)\Omega_{ji} \iff \Omega^{ij} = -(\epsilon_i\epsilon_j)\Omega^{ji}.
\]

At the same time, we require that \(\Omega_{ij}(z)\) and \(\Omega^{ij}(z)\) be covariantly constant with respect to the superfield derivative \(D_1(\eta)\), namely,

\[
\Omega_{ij}D_k = 0 \iff \Omega^{ij}D_k = 0.
\]

Using the fields \(\mathcal{R}(z), \Omega^{ij}(z)\) and the derivative \(D_1(\eta)\), one can construct a superfield \(Sp(2)\)-doublet \(\Delta^a\) of odd second-order differential operators, acting as scalars on the supermanifold \(\mathcal{N}\),

\[
\hat{\Delta}^a = \int d^2\eta \eta^2 \frac{\partial}{\partial \eta^a} \left( D_i + \frac{1}{2}(\mathcal{R} \delta_i^j) \right),
\]

where \(D^i(\eta)\) is a superfield derivative,

\[
\hat{D}^i = D_i \hat{\Omega}^{ji} \iff \hat{D}^i = D^i \hat{\Omega}_{ji}(-1)^{\epsilon_j},
\]

which transforms as a vector on \(\mathcal{N}\). In accordance with [11], the operators [16] generate a doublet of superfield bracket operations:

\[
(F,G)^a = -\int d^2\eta \eta^2 \frac{\partial}{\partial \eta^a} \left( (FD)^i \frac{\partial}{\partial \eta_i} \right)(-1)^{\epsilon_i\epsilon(G)} - (\epsilon(F)+1)(\epsilon(G)+1)(F \leftrightarrow G).
\]

Using the fields \(G_{ij}(z)\) and \(\Omega_{ij}(z)\), one can also equip the supermanifold \(\mathcal{N}\) with the superfield objects \(S_0\) and \(S_{ab}\)

\[
S_0 = \frac{1}{2} \int d^2\eta \eta^2 \frac{\partial}{\partial \eta^a} G_{ij} \frac{\partial}{\partial \eta^b} z^i, \quad \epsilon(S_0) = 0,
\]
\[
S_{ab} = -\frac{1}{6} \int d^2\eta \eta^2 \frac{\partial}{\partial \eta^a} \Omega_{ij} \frac{\partial}{\partial \eta^b} z^j, \quad \epsilon(S_{ab}) = 0,
\]

\(^3\)In the supersymmetric case, the contraction rules for tensor indices, as well as the definition of a nondegenerate tensor, can be found in the monograph [12] and papers [6, 8].
invariant under local coordinate transformations, $\tilde{S}_0 = S_0$, $\tilde{S}_{ab} = S_{ab}$. Here, $S_0$ is an $Sp(2)$-scalar, whereas $S_{ab}$ is an $Sp(2)$-tensor, symmetric with respect to its indices, $S_{ab} = S_{ba}$.

Using $S_0$, $S_{ab}$ and the bracket operations $(\cdot, \cdot)^a$, we define the $Sp(2)$-doublets of first-order odd differential operators $V^a$ and $U^a$

$$
\tilde{V}^a = (\cdot, S_0)^b = -\frac{1}{2} \int d^2\eta \eta^2 \frac{\partial^2 \tilde{D}^i}{\partial \eta^2} \frac{\partial \tilde{z}^i}{\partial \eta^b},
$$

$$
\tilde{U}^a = (\cdot, S_0)^a = \int d^2\eta \eta^2 \left\{ \frac{\partial \tilde{D}^i}{\partial \eta^2} \left[ G_{ij} \frac{\partial \tilde{z}^j}{\partial \eta^a} (-1)^{\epsilon_i} + \frac{1}{2} \frac{\partial \tilde{z}^i}{\partial \eta^a} \frac{\partial (G_{jk} \tilde{D}^i)}{\partial \eta^b} (-1)^{\epsilon_i \epsilon_k} \right] \right\} + \frac{1}{2} \frac{\partial \tilde{D}^i}{\partial \eta^a} \frac{\partial \tilde{z}^i}{\partial \eta^b} \left[ G_{jk} \frac{\partial \tilde{D}^i}{\partial \eta^a} \frac{\partial \tilde{z}^k}{\partial \eta^b} (-1)^{\epsilon_i \epsilon_k} + \right. \left. \frac{1}{2} \frac{\partial \tilde{z}^i}{\partial \eta^b} \frac{\partial (G_{jk} \tilde{D}^i)}{\partial \eta^a} (-1)^{\epsilon_i \epsilon_k+1} \right].
$$

(19)

(20)

The objects in (16–19) are formally identical with those arising in [10]. At the same time, the doublet of first-order operators (20) is an extension of its counterpart from [10]; namely, it contains an extra term with the expression $\frac{\partial}{\partial \eta^a}(G_{ij} \tilde{D}^k)$, related to the additional variables present in $G_{ij}$.

By straightforward calculations (see Appendix A), taking into account the expressions (16), (19) for $\Delta^a$, $V^a$ and the properties (7), (8) of derivatives $\tilde{D}_i(\eta)$, one can show that the triplectic algebra (9) is fulfilled if the scalar field $R(z)$ is chosen as

$$
R = -\log \text{sdet } (\Omega^{ij}),
$$

while the tensor fields $\Omega_{ij}(z)$ and $\Omega^{ij}(z)$ obey the Jacobi identities

$$
\frac{\partial^2 \Omega_{ij}}{\partial z^k} (-1)^{\epsilon_i \epsilon_k} + \text{cycle } (i,j,k) = 0 \Leftrightarrow \Omega^{il} \frac{\partial \Omega^{jk}}{\partial z^i} (-1)^{\epsilon_i \epsilon_k} + \text{cycle } (i,j,k) = 0,
$$

(22)

and the curvature tensor (5) of the base supermanifold $M$ is zero:

$$
\frac{M}{R^{ijkl}} = 0.
$$

(23)

Now that the triplectic algebra (9) and the related antibrackets (10) have been explicitly constructed, the Leibniz rules (12) and the Jacobi identity (13) are obviously fulfilled.

Due to (9), in order to complete the construction of the modified triplectic algebra (10), it remains to ensure the fulfillment of the relations involving the operators $U^a$. In this respect, the definition (20), namely, $\tilde{U}^a = (\cdot, S_0)^a$, as well as the Leibniz rules (12) and the Jacobi identity (13), imply that the modified triplectic algebra (10) holds true in case the function $S_0$ is subject to

$$(S_0, S_0)^a = 0, \ S_0 V^a = 0, \ S_0 \Delta^a = 0.
$$

(24)

We note that a solution of these equations can be found (see Appendix B) in the class of covariantly constant tensor fields $G_{ij}(z)$ with a subsidiary condition:

$$
G_{ij} \tilde{D}^k = 0, \ G_{ij} \frac{\partial \Omega^{jk}}{\partial z^k} (-1)^{k} = 0.
$$

(25)

The geometric interpretation of equalities (22) will be given in the following subsection, with allowance for (15), (23). As far as conditions (25) are concerned, we do not need to restrict the consideration to this special case of solutions to (24); namely, in what follows we merely assume that equations (24) are fulfilled.

### 3.2 Quantization Rules

Having constructed an explicit realization of the differential operators $\Delta^a$, $V^a$, $U^a$ and antibrackets $(\cdot, \cdot)^a$, we are in a position to set up a quantization procedure. This procedure repeats the BRST–antiBRST superfield covariant scheme in general coordinates [10] and has the same features. Thus, the vacuum functional is defined as

$$
Z = \int dz D_0 \exp\{(i/\hbar)[W + X + \alpha S_0]\},
$$

(26)
In this respect, we note that \( \Delta^a \) in the case of [10]. We also observe that, due to the subsidiary condition (23), the Fedosov supermanifold [6, 8], i.e., an extension of Fedosov manifolds [7, 14] to a supersymmetric case.

\[ \omega \text{ constancy of the even differential two-form} \]

with the properties

\[ \mathcal{V}^{(a \mathcal{V}^b)} = 0, \quad \mathcal{U}^{(a \mathcal{U}^b)} = 0, \quad \mathcal{V}^{(a \mathcal{U}^b)} + \mathcal{U}^{(a \mathcal{V}^b)} = 0, \]

that hold true for arbitrary values of the constant parameters \( \alpha, \beta, \gamma \), which implies that the operators \( \Delta^a, \mathcal{V}^a, \mathcal{U}^a \) also realize the modified triplectic algebra.

The integrand of (26) is invariant under extended BRST transformations, with the generators

\[ \delta^a = (\cdot, W - X)^a + \mathcal{V}^a - \mathcal{U}^a, \]

which implies the independence of the vacuum functional (26) from a choice of the gauge-fixing function \( X \) (for arbitrary \( \alpha, \beta, \gamma \)).

Let us establish the relation between [10] and the present quantization scheme in more detail. To this end, we introduce the notation

\[ \Omega_{ij}(z) \equiv \omega_{ij}(x, \theta, y), \quad G_{ij}(z) \equiv g_{ij}(x, \theta, y), \quad \mathcal{R}(z) \equiv \rho(x, \theta, y), \]

and examine the special case \( \omega_{ij}(x), g_{ij}(x) \), which, in view of (21), implies \( \rho(x) \), so that all the fields \( \omega_{ij}, g_{ij}, \rho \) are restricted to the base supermanifold \( M \), as in the case of [10].

From (15) and (22), it follows that \( \omega_{ij}(x) \) and its inverse \( \omega^{ij}(x) \) are subject to

\[ \omega_{ij}^M\nabla_k = 0 \Leftrightarrow \omega^{ij}\nabla_k = 0, \]

\[ \omega_{ij,k}(-1)^{\epsilon_i \epsilon_k} + \text{cycle (i, j, k)} \equiv 0 \Leftrightarrow \omega^{ij} \partial_i \omega^{jk}(-1)^{\epsilon_i \epsilon_k} + \text{cycle (i, j, k)} \equiv 0, \]

and, therefore, \( \omega_{ij}(x) \) and \( \omega^{ij}(x) \) are identified with the antisymmetric fields of [10]. Geometrically, (20) implies that \( \omega_{ij}(x) \) and \( \omega^{ij}(x) \) provide the base supermanifold \( M \) with an even symplectic structure and with a Poisson bracket, respectively [6]. At the same time, (29) ensures the covariant constancy of the even differential two-form \( \omega = \omega_{ij}dx^j \wedge dx^i \), so that \( M \) is interpreted as an even Fedosov supermanifold [6 S], i.e., an extension of Fedosov manifolds [7] [14] to a supersymmetric case. We also observe that, due to the subsidiary condition (23), the Fedosov supermanifold \( M \) is flat, as in the case of [10].

For the fields \( \omega_{ij}(x), g_{ij}(x) \), equalities (16) - (21) and (28) imply that the functions \( S_0, \mathcal{D}_0, \) the operators \( \Delta^a, V^a, U^a \) and the antibrackets \( \{\cdot,\cdot\}^a \) are reduced to the corresponding ingredients of [10]. In this respect, we note that \( U^a \) are reduced to their counterparts of [10] due to the equality

\[ \frac{1}{2}(W, W)^a + W\mathcal{V}^a = i\hbar \Delta^a, \quad \frac{1}{2}(X, X)^a + X\mathcal{U}^a = i\hbar \Delta^a. \]
4 Conclusion

We have presented a natural extension of the recently proposed BRST–antiBRST superfield covariant scheme in general coordinates [10]. Thus, the coordinate dependence of the basic ingredients of [10], being the scalar ρ and tensor ω_{ij}, g_{ij} fields, has been extended to the complete set of supervariables used in that formalism. In terms of the extended fields, R, Ω_{ij}, G_{ij}, we have explicitly realized the differential operators Δ^a, V^a, U^a, subject to the modified triplectic algebra, and constructed the related antibracket operations (, )^a. The corresponding quantization procedure follows [10] and has the same general features. Thus, the formalism contains free parameters (α, β, γ), whose arbitrary choice yields a gauge-independent vacuum functional and, consequently, a gauge-independent S-matrix [15]. In the limit when the extended fields R, Ω_{ij}, G_{ij} are reduced to the original ingredients of [10], namely, ρ, ω_{ij}, g_{ij}, the present quantization scheme becomes identical with the approach [10], and, therefore, reproduces (for a specific choice of the parameters α, β, γ) in Darboux coordinates [6] [10] the previously known schemes [11] [2] [3] of covariant BRST–antiBRST quantization. It appears interesting to combine the considerations of the present work with the ideas of the recent paper [11], which suggests enlarging the structure of a Fedosov supermanifold to the case of superfield variables. Such an opportunity, however, is impeded by the problem of a consistent superfield extension of connection coefficients [11].

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A Tripletic Algebra

Let us examine the algebra of the differential operators Δ^a and V^a, as acting on scalars defined on the supermanifold N. Using the expressions [11], [2], [3], the properties [4], [5], and the definitions [10], [10], we obtain

\begin{align*}
\Delta^a (\Delta^b) &= - \int d^2 \eta' d^2 \eta'' \left\{ A_{ij} (\eta', \eta'') \frac{\partial D^i j}{\partial \eta'_a} \frac{\partial D^i}{\partial \eta'_b} + \frac{1}{2} \frac{\partial D^i}{\partial \eta'^a} \epsilon^{c[a} \left[ B^i_{bj} (\eta', \eta'') \frac{\partial D^j}{\partial \eta'^2} \frac{\partial D^j}{\partial \eta'^2} + \frac{\partial D^j}{\partial \eta'^2} B^i_{bj} (\eta', \eta'') \right] \\
&- \frac{1}{2} \epsilon^{b[a} \frac{\partial D^j}{\partial \eta'^a} \left[ B_{ij} (\eta', \eta'') - (-1)^{\epsilon_i \epsilon_j} B_{ji} (\eta', \eta'') \right] + \frac{1}{2} \frac{\partial D^i}{\partial \eta'^a} \left( \frac{\partial (RD_j)}{\partial \eta'^2} \right) \right\} \eta'^a \eta'^b,
\end{align*}

\begin{align*}
V^a (V^b) &= - \frac{1}{4} \int d^2 \eta' d^2 \eta'' A_{ij} (\eta', \eta'') \frac{\partial D^i j}{\partial \eta'^a} \frac{\partial D^i}{\partial \eta'^b} \eta'^a \eta'^b,
\end{align*}

\begin{align*}
2 \left( \Delta^a V^b + V^b \Delta^a \right) &= - \int d^2 \eta' d^2 \eta'' \left\{ A_{ij} (\eta', \eta'') \left( \frac{1}{2} \epsilon^{ab} \Omega^{ij} + \frac{\partial D^i}{\partial \eta'^a} \frac{\partial D^j}{\partial \eta'^b} \right) \right. \\
&+ \epsilon^{ab} \frac{\partial D^i}{\partial \eta'^2} \frac{\partial}{\partial \eta'^2} \left[ \frac{\partial (R \Delta_j)}{\partial \eta' a} \right] + \frac{1}{2} \Omega^{ij} \left( \frac{\partial (RD_j)}{\partial \eta'^2} \right) \left( -1 \right)^{\epsilon_j} \\
&- \frac{\partial D^i}{\partial \eta'^a} \left( \frac{1}{2} B_{ij} (\eta', \eta'') - M^{k}_{ij,k} \left( -1 \right)^{\epsilon_i \epsilon_k} \right) \left( \frac{\partial D^i}{\partial \eta'^a} \right) \eta'^a \eta'^b, \\
&\left. + \Gamma^{l}_{ij} \Gamma^{k}_{ik} \left( -1 \right)^{\epsilon_j (\epsilon_i + \epsilon_k) + \epsilon_k (\epsilon_i + 1)} \right\} \eta'^a \eta'^b,
\end{align*}

with the following notation:

\begin{align*}
A_{ij} (\eta', \eta'') &= \frac{\partial}{\partial \eta'^a} \frac{\partial}{\partial \eta'^2} \left[ D_i (\eta'), D_j (\eta'') \right], \quad B_{ij} (\eta', \eta'') &= \frac{\partial (RD_j)}{\partial \eta'^2} \frac{\partial D^i}{\partial \eta'^a}, \quad B_{ij} (\eta', \eta'') = \frac{\partial (RD_i)}{\partial \eta'^2} \frac{\partial D^i}{\partial \eta'^a}.
\end{align*}

We now subject the function R (z) to the equations

\begin{align*}
\left( \frac{\partial (R \Delta_j)}{\partial \eta' a} \right) \left( -1 \right)^{\epsilon_j} = 0,
\end{align*}
which, in view of (14), are equivalent to
\[
\frac{\partial_{r} \mathcal{R}}{\partial z^{i}(\eta)} = 2 \frac{\partial_{r} \Omega^{jk}}{\partial z^{k}(\eta)} \Omega_{ij}(-1)^{\epsilon_{j}+\epsilon_{k}}.
\]

To solve these equations, we use the consequence of the Jacobi identities (22)
\[
\Omega_{kj} \frac{\partial}{\partial z^{i}(\eta)} \Omega^{jk} + 2 \frac{\partial_{r} \Omega^{jk}}{\partial z^{k}(\eta)} \Omega_{ji}(-1)^{\epsilon_{j}+\epsilon_{k}} = 0,
\]
and obtain the equality
\[
\frac{\partial_{r} \mathcal{R}}{\partial z^{i}(\eta)} = -\Omega_{kj} \frac{\partial}{\partial z^{i}(\eta)} \Omega^{jk}.
\]

(A.4)

Thus, the function \( \mathcal{R}(z) \) can be chosen as
\[
\mathcal{R} = -\log \det (\Omega^{ij}),
\]
since its variation has the form
\[
\delta \mathcal{R} = -\log \det (\Omega^{ij} + \delta \Omega^{ij}) + \log \det (\Omega^{ij}) = -\log \det \left( \delta \Omega^{ij} + (-1)^{\epsilon_{i}} \Omega_{ik} \delta \Omega^{kj} \right)
\]
\[
= -\text{str} \left[ (-1)^{\epsilon_{i}} \Omega_{ik} \delta \Omega^{kj} \right] = -\Omega_{ij} \delta \Omega^{ij}.
\]

(A.5)

From (1), (6), (15) and (A.5), it follows that
\[
\mathcal{R} D_{i} (\eta) = \frac{\partial_{r} \mathcal{R}}{\partial \eta^{i}} = \Omega_{jk} \frac{\partial_{r} (\Omega^{k}_{j} D_{i})}{\partial \eta^{k}} \frac{\partial z^{m}}{\partial \eta^{a}} \Omega^{m}_{i} \Omega_{ij}(-1)^{\epsilon_{m}(\epsilon_{i}+1)} = 0.
\]

(A.6)

Then, due to (2), (6), (15) and (A.4), one obtains
\[
\frac{1}{2} \frac{\partial (\mathcal{R} D_{i})}{\partial \eta^{m}} = -\frac{1}{2} \Omega_{jk} \frac{\partial}{\partial \eta^{j}} \left\{ \Omega^{k}_{j} D_{i} - \eta^{2} \left[ \frac{\partial_{r} (\Omega^{k}_{j} D_{m})}{\partial \eta^{k}} \frac{\partial z^{m}}{\partial \eta^{a}} \Omega^{m}_{i} \Omega_{ij}(-1)^{\epsilon_{m}(\epsilon_{i}+1)} - \Omega_{mj} M^{j m}(-1)^{\epsilon_{m}(\epsilon_{i}+1)} - \Omega_{mj} M^{j m}(-1)^{\epsilon_{m}(\epsilon_{i}+1)} \right] \right\} = M^{j i} (-1)^{\epsilon_{j}}.
\]

(A.7)

In view of (A.2), the properties (A.6) and (A.7) imply
\[
B^{i}_{ij} (\eta', \eta'') \eta^{i j} = 0, \quad B_{ij} (\eta', \eta'') - (-1)^{\epsilon_{i} \epsilon_{j}} B_{ji} (\eta', \eta'') = 0,
\]
\[
B_{ij} (\eta', \eta'') = 2 \left( M^{k}_{i j} - M^{k}_{i j} \right) (-1)^{\epsilon_{k}}.
\]

(A.8)

Now, with the help of (3), (A.3) and (A.6)–(A.8), the expressions for \( \Delta^{a} A^{b} \) and \( \Delta^{a} V^{b} + V^{b} \Delta^{a} \) in (A.1) can be written as follows:
\[
\Delta^{a} A^{b} = - \int d^{2} \eta' d^{2} \eta'' A_{ij} (\eta', \eta'') \frac{\partial_{r} D^{j}}{\partial \eta''^{m}} \frac{\partial D^{i}}{\partial \eta^{m}} \eta^{i j} \eta^{m} \eta^{m},
\]
\[
2 \left( \Delta^{a} V^{b} + V^{b} \Delta^{a} \right) = - \int d^{2} \eta' d^{2} \eta'' A_{ij} (\eta', \eta'') \left( \frac{1}{2} \frac{\partial_{r} D^{i}}{\partial \eta''^{m}} \frac{\partial z^{j}}{\partial \eta^{m}} \right) \eta^{i j} \eta^{m},
\]
\[
+ \int d^{2} \eta' d^{2} \eta'' \frac{\partial D^{i}}{\partial \eta''^{m}} \frac{\partial D^{j}}{\partial \eta^{m}} \frac{\partial z^{k}}{\partial \eta^{i j}} \eta^{i j} \eta^{m} (-1)^{\epsilon_{k}(\epsilon_{i}+1)}.
\]

(A.9)

We remind that the commutator of derivatives \( D_{i} (\eta) \), acting on scalars defined on the supermanifold \( \mathcal{N} \), is given by (8). Then, due to (A.1) and (A.9), we can see that if the base supermanifold \( M \) is chosen to be flat, \( M^{i}_{jk} = 0 \), the supermanifold \( \mathcal{N} \) admits an explicit realization of the triplectic algebra (9). As a consequence, the bracket operations (17) obey the properties (12) and (13), so that these operations can be interpreted as extended antibrackets.
B Modified Triplectic Algebra

Let us establish conditions that ensure the fulfillment of equations (24). To this end, we recall that
the function \( S_0 \) has the form (18), whereas the operators \( \Delta^a, V^a \) and antibrackets \( (, )^a \) are
given by (16), (17), (19). Using the properties (7), (8) of derivatives \( D_i(\eta) \), we obtain

\[
(S_0, S_0)^a = \int d^2\eta' d^2\eta'' \frac{\partial z^i}{\partial \eta'^b} \left( G_{ij}D^k(\eta') \right) \frac{\partial z^j}{\partial \eta''^a} \eta'^2 \eta''^2 \left( -1 \right)^{\varepsilon_k(\varepsilon_j+1)},
\]

\[
S_0V^a = \frac{1}{4} \int d^2\eta' d^2\eta'' \frac{\partial z^i}{\partial \eta'^b} \left( G_{ij}D^k(\eta') \right) \frac{\partial z^j}{\partial \eta''^a} \eta'^2 \eta''^2 \left( -1 \right)^{\varepsilon_j \varepsilon_k},
\]

\[
S_0\Delta^a = \int d^2\eta' d^2\eta'' \left\{ \frac{\partial z^i}{\partial \eta'^b} \frac{\partial}{\partial \eta''^a} \left[ \left( G_{ij}D^k(\eta') \right) + \frac{1}{2} G_{ij} \left( RD^j \right) \right] + \frac{1}{2} \frac{\partial z^i}{\partial \eta'^b} \frac{\partial}{\partial \eta''^a} \left[ \omega_k + \frac{1}{2} \left( RD_k \right) \right] \right\} \eta'^2 \eta''^2.
\]

Next, imposing the condition of covariance \( G_{ij}D_k = 0 \) (equivalent to \( G_{ij}D^k = 0 \)) and the subsidiary
condition \( G_{ij} \left( RD^j \right) = 0 \),
we can see that the right-hand sides in (B.1) turn to zero. The above equality (B.2) is formally
identical to a subsidiary condition used in [10], and, due to (A.4), (A.6), is equivalent to

\[
G_{ij} \frac{\partial \Omega^{jk}}{\partial z^k} \left( -1 \right)^k = 0.
\]

Hence, the conditions [25] provide an example of solutions to equations (24) which ensure the fulfill-
ment of the modified triplectic algebra [10].

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