SD-Access: Practical Experiences in Designing and Deploying Software Defined Enterprise Networks

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Abstract

Enterprise Networks, over the years, have become more and more complex trying to keep up with new requirements that challenge traditional solutions. Just to mention one out of many possible examples, technologies such as Virtual LANs (VLANs) struggle to address the scalability and operational requirements introduced by Internet of Things (IoT) use cases. To keep up with these challenges we have identified four main requirements that are common across modern enterprise networks: (i) scalable mobility, (ii) endpoint segmentation, (iii) simplified administration, and (iv) resource optimization. To address these challenges we designed SDA (Software Defined Access), a solution for modern enterprise networks that leverages Software-Defined Networking (SDN) and other state of the art techniques. In this paper we present the design, implementation and evaluation of SDA. Specifically, SDA: (i) leverages a combination of an overlay approach with an event-driven protocol (LISP) to dynamically adapt to traffic and mobility patterns while preserving resources, and (ii) enforces dynamic endpoint groups for scalable segmentation with low operational burden. We present our experience with deploying SDA in two real-life scenarios: an enterprise campus, and a large warehouse with mobile robots. Our evaluation shows that SDA, when compared with traditional enterprise networks, can (i) reduce overall data plane forwarding state up to 70% thanks to a reactive protocol using a centralized routing server, and (ii) reduce by an order of magnitude the handover delays in scenarios of massive mobility with respect to other approaches. Finally, we discuss lessons learned while deploying and operating SDA, and possible optimizations regarding the use of an event-driven protocol and group-based segmentation.

1 Introduction

Current Enterprise Networks (EN) present a high degree of complexity derived from their organic evolution. Traditional ENs are built in a three-tier structure: access, distribution and core, with each layer leveraging a distinct set of protocols. The access-distribution segment uses L2 technologies such as Virtual Local Area Networks (VLANs), Spanning Tree Protocol (STP), and VLAN Access Control Lists (ACLs). On the other hand, the distribution-core segment is usually L3 with a combination of Open Shortest Path First (OSPF), Multiprotocol Label Switching with Label Distribution Protocol (MPLS-LDP), and IP ACLs. This design varies from deployment to deployment, but the end result are complex networks that can be running up to tens of different protocols across hundreds of switches. This makes it hard to adapt to new requirements, such as isolating IoT devices or stretching L2 domains across distributed locations. Even if some of these challenges might have been addressed by technologies designed for service providers, such as Virtual Routing and Forwarding (VRF), given the high port density required in typical campus networks, adopting the same technologies in enterprise solutions is not cost effective.

Specifically, current ENs lack three key elements. First, scalable endpoint mobility across all the enterprise facilities, to address the ever-increasing amount of roaming devices. Usually this is handled via sending all wireless traffic through centralized Wireless LAN (WLAN) controllers, which limits scalability, and reduces bandwidth. Second, simple to operate segmentation. The most common forms of segmentation in ENs are VLANs or VRFs, which do not scale well and can be difficult to configure at scale. Another example are IP-based ACLs, that over time can easily become long and difficult to map to the original intent. Third, simplified operations. Network administrators might configure each router individually, and, as we mentioned previously, have to deal with a myriad of different protocols. Although there exist more modern solutions [1, 2] that satisfy some of these requirements, we believe that the state of the art does not deal with scale and dynamism in a cost-effective manner, i.e. without requiring large capital expenditures (CAPEX).

CAPEX plays, indeed, a very important role in the context of Enterprise Networks. First, because of brownfield deployments: typically, network administrators do not want to upgrade all of their switches for new features. Since these are usually legacy devices with
limited features, new network designs require a way to add new functionality without a forklift upgrade. Second, because deploying devices with reduced FIB size or CPU power decreases CAPEX but in turn means less powerful devices that require resource optimization.

In this paper we present the rationale, implementation, evaluation and experience matured in deploying SDA (Software Defined Access). Our objective with SDA was to design a solution that addressed the aforementioned requirements of modern EN. With this goal in mind, we leveraged a vast spectrum of research ideas, architectures and protocols produced by the community in the last decade \cite{23}, and integrated them in a practical and deployable solution. First, we leveraged network overlays as discussed in the Fabric architecture \cite{2}, in the form of the Locator/ID Separation Protocol (LISP \cite{23}). This offers three benefits; (i) we can upgrade existing deployments (brownfields) with minimal touch, (ii) their layer of indirection makes it easy to support L3 mobility, and (iii) they make segmentation with VRFs more scalable. Second, we applied the Software-Defined Networking (SDN) principle of centralized control to track endpoint location, and map endpoints to segmentation policies across the whole network. Finally, we chose a reactive protocol (LISP) to distribute network state to the data plane. In other words, we populate the switches forwarding tables only if required by the active traffic pattern. This reduces the overall switch requirements in terms of FIB size and CPU power which results in reduced CAPEX.

We must remark that this paper is not meant to introduce a novel architecture, but rather an account of our experience and lessons learned in designing, and deploying modern enterprise networks. We describe how we combine state of the art techniques to realize a practical solution, and the lessons that we have learnt when operating SDA. We detail our experience through two real-life deployments. First, a medium-sized enterprise campus network serving around 450 endpoints that includes fixed hosts, mobile hosts, application servers, IoT devices, etc. We show that in this scenario, our reactive protocol optimizes data plane state with a 70% reduction of FIB entries in the data plane compared to solutions that store all the state in all routers (e.g. BGP). Second, a large warehouse where hundreds of robots are moving at speed to fulfill shipping orders, such as those run by large on-line retailers. Here we evaluate the handover delay of 16,000 robots triggering 800 mobility events per second. Our solution achieves 5 times lower handover delay compared to existing approaches. Finally, we present our lessons learned from deploying SDA, such as reducing the initial connection delay due to the reactive protocol, coping with connectivity issues in the underlay or dealing with policy updates at scale.

2 Requirements and Design Decisions

This section delves deeper into the requirements of current ENs, explains limitations in the state of the art and discusses design decisions, summarized in table \ref{tab:requirements}.

**Resource optimization:** Routing protocols commonly found in enterprises, such as OSPF, IS-IS or BGP make it difficult to reduce the FIB space without losing granularity.\footnote{1} We approached this challenge by leveraging a reactive protocol (LISP in our implementation), rather than a proactive. Instead of pushing all routing entries beforehand to the routers, we only retrieve the necessary forwarding entries from a centralized server on-demand, and only for the routers that need them \cite{9,8}. We track endpoints by their IP address, so that routers download routes for the remote endpoints they need to reach, based on incoming traffic from local endpoints.

In addition, this reactive approach is helpful with mobility because we can reduce convergence time. This arises from the fact that a reactive approach reduces the churn generated by the location updates: we only notify the parties affected by a specific mobility event. We must remark that a reactive protocol presents several challenges, such as a potential initial delay for the establishment of flows (sec. 3.2.2), or detecting connectivity outages in the underlay (sec. 5) discusses our learnings in this space).

**Mobility:** the current trend of wireless first makes it critical to support a large amount of wireless endpoints. Traditionally, ENs handle mobility at L2 in a centralized way for both data plane and control plane. A gateway device (WLAN controller) acts as a sink for all traffic from all access points, performs access control, and re-injects it to the L3 network. This approach presents a serious scalability limitation because the gateway device becomes a bottleneck.\footnote{2} In addition, it creates triangular routing because all L3 traffic is forced to go to the gateway and then back to the actual destination. SDA tackles mobility at layer 3 using network overlays \cite{10,11}, specifically with the mobility features of LISP. We keep the wireless control plane centralized for authentication purposes, but we let packets coming from the access point to be directly routed to destination. This distributed data plane greatly increases scalability.

**Segmentation:** traditionally, the most common form of segmentation in enterprise networks are Virtual Local Area Networks (VLANs \cite{12}) and Virtual Routing and Forwarding tables (VRFs \cite{13}). Despite their simplicity, VLANs scope must be kept limited to prevent flooding of broadcast traffic or L2 forwarding loops, hence, they do not scale well. Regarding VRFs, they scale better than VLANs, but since each device has to be individually configured it is hard to implement global policies across the whole network. A direct consequence is that administration becomes too cumbersome as the number of VRFs increases. In addition, both of these approaches present similar limitations that make it hard to deal with mobility at scale.
Table 1: Summary of current state of the art, challenges, and design decisions

| Requirement     | Current Approach                          | Limitations                           | Our approach                  | Benefits                      |
|-----------------|-------------------------------------------|---------------------------------------|-------------------------------|-------------------------------|
| Resource efficiency | BGP and OSPF prefix aggregation         | Granularity                           | Traffic-driven route learning | Reduced CAPEX, device-level granularity |
| Mobility        | L2 centralized control and data plane     | Scalability, triangular routing       | L3 centralized control, distributed data plane | Increased scalability, optimized routing |
| Segmentation    | VLANs and VRFs                           | Scalability, network-wide policies    | Limited L2 stretching, 'centralized' VRFs | Increased scale with less resources |
| Simplified administration | VLAN and IP-based ACLs | Error-prone, no mobility | Group-based policies | Smaller ACLs, end-to-end enforcement |

SDA addresses these issues at different levels: for L2 segmentation \(^3\) \([14]\), we carefully stretch L2 domains (c.f. sec. 3.5). For L3, we still use VRFs, but map local VRFs to global virtual networks in order to handle L3 segmentation at scale. This way, network administrators only have to specify the virtual network for each endpoint \([6]\). Finally, we add a layer of indirection to ease administration, detailed in the next paragraph.

**Simplified administration:** a direct consequence of using network primitives such as IP addresses or VLANs for segmentation and access control is operational complexity \([15]\). In other words, network administrators have to translate business intent into IP addresses and ACLs and backwards. In the long run, this approach does not scale, is error prone, and increases complexity.

To overcome this problem, we make use of the well-established group-based paradigm \([7, 16]\) to define ACLs between groups, instead of IP prefixes. First, the network operator defines a connectivity matrix among all groups. Then it adds endpoints to each group. On the network level, routers track each endpoint by its IP address and add a 16-bit tag representing its group, so they can enforce the connectivity rules in the matrix. The benefit is that network administration is radically simplified and common operations, such as IP address planning or ACL configurations can be automated.

We store this information in the control plane in two different servers, a routing server and a policy server. The policy server authenticates endpoints, assigns them a group and configures the data plane routers with the required group rules from the connectivity matrix. The routing server keeps track of all endpoints by their IP address and provides routes upon demand by the data plane.

On the data plane, the overlay routers - hereafter referred to as edge routers - enforce the connectivity matrix and route packets to the corresponding edge router. A special border router provides access to external networks. Finally, endpoints can roam freely across edge routers.

### 3.2 Control Plane

We based the control plane design on a database-focused approach similar to \([4]\), as opposed to more traditional designs \([15, 20]\). The control plane consists of two logically centralized servers: policy server and routing server. Table 2 presents a summary of all our control plane data.

#### 3.2.1 Control Plane Policy Server

We offer two degrees of segmentation: Virtual Networks (VN) and the group connectivity matrix. These group rules are independent for each VN. On one hand, VNs offer strong isolation at a 'macro' level. An example is a hospital network, where we want to isolate the doctors, guest and medical devices networks, we never expect them to be able to communicate each other. This is especially relevant to isolate legacy devices susceptible to attacks, e.g. an MRI machine running an outdated OS. In addition, it is a way to mitigate lateral spread attacks.

On the other hand, the group rules offer a 'micro' segmentation for finer grain control inside a VN. For example, this level of segmentation can separate different types of devices within a VN in Bring Your Own Device scenarios.

The policy server stores the connectivity rules from the connectivity matrix, and, for each endpoint: its

\(^3\)The reason for this separation is that usually the host on-boarding process needs both the endpoint credentials and group permissions, while the normal packet flow only needs the location mappings.
authentication data, and associated GroupId and VN. GroupId and VN are 16-bit and 24-bit identifiers, respectively. The authentication data is variable since we support different RADIUS-based authentication protocols [21], both with EAP or without. We use a specific protocol, Scalable-Group Tag eXchange Protocol (SXP [22]) to distribute the GroupIds and connectivity rules to edge routers. From the network perspective, VNs are mapped to isolated routing-switching domains, while GroupIds are inputs to group-based ACLs.

3.2.2 Control Plane Routing Server

The routing server stores the endpoint location, i.e. pairs of overlay-to-underlay IP addresses plus its associated VN. The overlay IP is the IP used by endpoints, while the underlay IP is the IP of the edge router serving this endpoint. The other edge routers encapsulate traffic for such endpoint towards the underlay IP. After a successful device onboarding (sec. 3.3.1), or upon detecting a mobility event, edge routers update the underlay location of an overlay IP address. Edge routers also retrieve this mapping when they receive a connection request to a particular device. We leverage the control plane aspects of the Locator/ID Separation Protocol (LISP, [23]).

In a nutshell, the LISP control plane offers two messages: Map Request, to retrieve the underlay address of an overlay endpoint, and Map Register, to update the location of an endpoint, i.e. the overlay to underlay mapping. This way, we can store in the data plane the overlay-to-underlay mappings that are required by the edge router to serve incoming traffic. In addition, the LISP control plane supports mobility, is well suited for SDN architectures [21], and accommodates different overlay address families apart from IP, e.g MAC addresses. This is especially helpful to support L2 services (sec. 3.5).

However, a drawback of using a reactive protocol such as LISP is the initial packet loss until the edge router downloads the route for a new destination. We have overcome this issue by installing a default route in all edge routers that points to the border router, and by synchronizing the routing state in the border with the information in the routing server (sync arrow in fig. [1]). This way, edge routers forward packets to the border until they finish the resolution process, during this time the border router forwards such packets to the destination. The border router is usually more powerful than edge routers in order to handle this extra load. Finally, some deployments may have more than one routing server or policy server for redundancy and load balancing.

3.3 Data Plane

The data plane presents two distinct routers (fig. [1]): edge and border.

**Edge Routers**: perform four key functions. First, they encapsulate and decapsulate traffic from and to endpoints, respectively. Second, provide inter-VN isolation (‘macro’ segmentation). We implement such segmentation with VRFs: LISP populates the VRF tables, and each entry has an associated GroupId. Third, they detect roaming endpoints and update their location in the routing server. And fourth, enforce group permissions from the connectivity matrix (‘micro’ segmentation).

**Border Routers**: perform the same functions as edge routers, with two exceptions. First, their FIB table is synchronized with the routing server. In other words, they don’t use a reactive protocol, rather they are subscribed to all route updates from the routing server [25]. Second, they have routes to other networks, e.g. Internet, datacenter. Because of this, border routers have more powerful CPU and larger FIB tables.

The data plane encapsulation leverages VXLAN with Group Identifier extension [26]. We chose this encapsulation over the native LISP data plane because of the need to encapsulate both L2 and L3 payloads (LISP supports L3 only). Additionally, in this VXLAN variant we can add the source GroupId in the group field (fig. [2]). Finally, the underlay is a network with plain IP connectivity that routes encapsulated packets between edge routers. The underlay routing is provided by either OSPF or IS-IS, we leverage MACsec [27] for packet integrity protection and confidentiality, and ECMP for redundancy [28].
the network plugs a device for the first time (onboarding) and the standard packet flow.

### 3.3.1 Host Onboarding

When an endpoint connects to the overlay, the edge router detects it and starts the authentication process with the policy server (step 1 in fig. 3). After a successful authentication, the edge router downloads the endpoint’s VN, GroupId, and associated connectivity rules from the policy server (step 2). Specifically, it downloads the rules where the endpoint’s group is the destination (c.f. sec. 5.3), stores locally the GroupId value, and associates it to the switch port where the endpoint is connected. Then it can assign an overlay IP address to the endpoint (step 4), obtained from a DHCP server (step 3). Finally, the edge router stores the location of the endpoint in the control plane, i.e. the underlay IP address of the destination overlay IP (step 3) pair in the database (step 4).

### 3.3.2 Packet Flow

On ingress, packets from endpoints are assigned their corresponding GroupId and VN (fig. 4 ingress edge router). The router knows these values from the onboarding process. Then, it does a VN + overlay destination IP lookup in the VRF table for that VN. If there is no match, it will query the control plane database. This query returns the underlay IP address of the destination overlay IP. Finally, the packet is encapsulated towards the corresponding edge router, carrying both VN and GroupId.

On egress, the destination edge router decapsulates the packet and injects it into a two-stage pipeline (fig. 4 egress edge router). First, it performs a VN + overlay destination IP lookup in the local VRF table corresponding to the VN in the packet. This query returns the output port and the associated destination GroupId. Each entry in the VRF has its associated GroupId, that is stored during the onboarding process. After authentication, the edge router creates an (Overlay IP, GroupId tag) association in the VRF table.

The second stage is an exact match lookup in an group-based ACL of (source GroupId, destination GroupId). This ACL enforces the aforementioned group rules. Finally, the router forwards the packet to the destination overlay IP address. We perform the policy enforcement on egress due to increased scalability (sec. 5.3).

### 3.4 Mobility Support

When an endpoint roams and attaches to a new edge router, the latter triggers the authentication process again, and registers the new location (Fig. 5 Step 1). After this registration, the control plane sends a message to the previous edge router instructing it to (i) pull the new location data (2,3), and (ii) forward all traffic for that particular endpoint to the new edge router. Hence, handover signaling is linear with the number of roaming endpoints, as opposed to proactive protocols, in which it also depends on the number of routers (sec. 4.3).

Additionally, we apply the event-driven approach to update edge routers storing stale entries. To this purpose, we use a specific data-triggered control plane message (Fig. 5): when the old edge router receives traffic for the roaming endpoint (1) it sends a control message to the source (2), instructing it to retrieve the new location (4). At the same time, the old destination router forwards this traffic to the new destination router (3).

Regarding signaling scalability, this method depends on traffic patterns: if the roaming endpoint is very popular, we will have to update a significant portion of edge routers. On the contrary, endpoints that receive traffic from few sources, require less signaling. The advantage of this technique is that it is triggered by traffic, in other words, the control plane doesn’t need to update all edge routers that have the stale location, but only those that require it. Finally, these control plane messages will be
staggered over time as traffic from different senders will arrive at different times, thus spreading the signaling load in time.

3.5 Support for L2 services

In enterprise scenarios, it is common that some devices or users require L2 connectivity. Common use-cases are some forms of load-balancing, certain IoT devices, and basic services such as DHCP or service discovery.

In order to support such services, but avoid sending broadcast traffic to the entire network, our implementation leverages four elements: (i) VLANs (limited to the edge router ports), (ii) indexing endpoints by MAC address in the Routing Server (in addition to IP address), (iii) storing overlay IP to MAC pairs in the routing server, and (iv) deployment of L2 gateways in edge routers.

4 Evaluation

We have implemented SDA in a commercially available line of routers, leveraging the protocols mentioned previously: LISP [23], RADIUS [21], and Scalable-Group Tag eXchange Protocol [22] for the control plane, and VXLAN [29] for the data plane. We have deployed our implementation in two different real-life scenarios: two campus networks with 150 and 450 endpoints, and a large warehouse (partially emulated) with massive mobility serving 16,000 emulated endpoints. Table 3 presents a summary of their characteristics.

We evaluated three key elements of SDA: first, the response of the routing server under stressful conditions, because it is critical in the process of establishing data flows. Second, quantifying the state optimization in the data plane due to the edge-border design. And third, assess the difference between an proactive and a reactive protocol in face of massive mobility events.

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A significant amount of applications rely on broadcast domains, e.g. Apple Bonjour

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| Deployment | # Border Routers | # Edge Routers | Number of endpoints |
|------------|------------------|---------------|---------------------|
| Building A | 1                | 7             | 150                 |
| Building B | 2                | 6             | 450                 |
| Warehouse  | 2                | 200           | 16,000 (emulated)   |

The combination of these four elements helps us to provide scalable L2 connectivity: first, VLANs limit broadcast domains; second, MAC address indexing locates endpoints of the same VLAN that are in different edge routers. Finally, L2 gateways absorb broadcast traffic and convert it to unicast: for instance, they capture ARP requests and perform a lookup in the routing server to find the MAC associated to the IP in the ARP request. Then they use this MAC to replace the broadcast MAC in the ARP request, creating a unicast L2 message. This message is injected in the L2 pipeline, which will use the MAC-to-underlay IP to encapsulate the request to the intended L2 MAC.
4.1 Routing Server Scalability

The routing server is a critical part of the design, because it allows establishing communication between any pair of endpoints. Because of this, we evaluated its performance depending on the number of routes and queries per second.

To this end, we setup a routing server implemented in a commercial virtual router with 8 GB RAM, 8 vCPU, on top of a virtualization platform with an 8-core 2.1 GHz processor. We measured the delay to answer route requests and route updates with a script running in a local machine that sent 800 queries per second. We repeated the experiment for different number of routes configured in the routing server. Each query requested or updated a different route, in order to avoid optimizations due to intermediate caches. We consider the network delay negligible. Figures 7a and 7b present boxplots of the time required to answer an IPv4 route request and a route update, respectively, for four different number of configured routes in the routing server. The values are relative to the minimum delay of a routing server with only one route.

We can see that the delay is not dependent on the number of routes. Since this architecture is designed to store network state hierarchically, it makes it easy to implement the routing server with a Patricia Trie. The delay of this data structure depends on the number of bits of the keys, not the number of elements [30]. Based on the data collected for this particular test, an equivalent deployment using a similar setup should scale to at least 3k endpoints without noticeable performance degradation. Each endpoint requires registering 3 routes (IPv4, IPv6 and MAC addresses), then 10k / 3 = ∼3k.

We chose to send 800 queries/s to the server since it is the peak requirement in the massive mobility scenario (sec. 4.3). We consider this a highly loaded server, however, in case we needed to increase such figure, the architecture scales horizontally and can deploy more routing servers. Then, we load balance across edge routers by grouping them and pointing each group to a different routing server for the route requests, and perform route updates on all servers.

Using the same routing server as before, we repeated the previous experiment but for different number of queries/s. Figure 7c presents boxplots of the delay to answer IPv4 route requests for four different number of queries per second to the routing server. The values are relative to the minimum delay of all samples. Assuming a mobility pattern similar to the warehouse scenario (sec. 4.3) with 800 moves/s and that each move triggers 2 queries to the routing server, we conclude that the routing server could support this use case (800*2 = 1600 queries/s).

4.2 State Reduction

In order to quantify the state reduction due to the reactive protocol, we counted the number of overlay-to-underlay IPv4 mappings in the FIB of the edge and border routers. We setup a VM that collected this data hourly from the router CLI. The routers were in two separate buildings (A and B), with three floors each, and providing network connectivity to between 200 and 500 users. Table 4 provides additional details about each deployment, and Fig. 8 shows the network topology. The control plane of border routers has a 4-core 2.4GHz, x86 CPU with 16 GB RAM, and edge routers a 4-core 1.8 GHZ, x86 CPU with 8 GB RAM. Both of them use a custom ASIC for the data plane. The border-to-edge links are 10 Gbps and the edge-to-AP 1 Gbps.

Figure 9 shows the average number of FIB entries for the border and edge routers, for both buildings, and for three different weeks. We can see that, on average edge routers store less FIB entries than border routers: in building A edge routers carry only about 30% of the FIB entries on the border routers, while in building B this figure is as low as 6%. Table 5 presents also averages of FIB entries for border and edge routers for a period of 5 weeks. We can also see reductions in FIB entries, even if we calculate separate averages for day and nighttime. We can conclude that the reactive approach helps in optimizing data plane state, while the border router absorbs the convergence delay of the route resolution.

It is also worth mentioning that the usage pattern of the FIB table on border routers shows a common daily and weekly pattern: during daytime in working week days routers host more routes than during nighttime and over weekends. This is due to the fact that the border router is always up to date with the information in the routing server regarding the endpoints in the deployment. Thus, the number of entries in the border router follows closely the presence of authenticated users in the network (i.e. users in the office). In contrast, edge routers cache routes learned on demand and may retain them during longer periods, even when users have left the office. We can clearly see this in building A (Fig. 9 top row), where edge routers seem to keep their routes for most of the time between workdays, but eventually clear they caches during weekend. On the other hand, this effect is less noticeable in building B, where edge routers follow the daytime/nighttime routine more closely. The reason behind this could be nighttime traffic patterns: when some endpoints leave the office at night, the remaining ones may initiate communication with those that left, that will trigger a route resolution with a negative result, and thereby deleting that FIB entry.

|                      | Bldg. A | Bldg. B |
|----------------------|---------|---------|
| Border Routers       | 1       | 2       |
| Edge Routers         | 7       | 6       |
| Floors               | 3       | 3       |
| AP* per floor        | 40      | 40      |
| Total AP             | 120     | 120     |
| AP* per edge         | ~20     | 20      |
Figure 7: Routing Server Performance Evaluation.

(a) Boxplot (95%) of the delay of 10k route requests for four different number of configured routes. Relative values to a routing server with 1 route.

(b) Boxplot (95%) of the delay of 10k route updates for four different number of configured routes. Relative values to a routing server with 1 route.

(c) Boxplot (95%) of the delay of route requests for four different number of queries per second. Values are relative to the minimum of all.

Finally, another relevant aspect of building B is a substantial amount of end-hosts that are permanently connected to the network and do not follow the day/night routine. Examples of such end-hosts are desktops and IoT devices (VoIP phones, cameras) that do not necessarily move with the users.

4.3 Massive Mobility Events

In this experiment we focus on the handover delay of large mobility events for a reactive and proactive protocol. We recreated in the lab the specifications of a real life deployment, a large warehouse with hundreds of robots continuously roaming across WiFi access points. Figure 10 presents the topology: a commercial border router (4-core 1.8GHz CPU, 8 GB RAM for the control plane and custom ASIC in the data plane) and 198 edge routers emulated with a commercial traffic generator. The border router had an embedded routing server.

We configured the traffic generator to: (i) create unidirectional UDP traffic from the 200 edge routers towards the border router (yellow arrow in fig. 10), (ii) send 1500 bytes packets from 16,000 emulated hosts, and (iii) generate 800 mobility events per second by changing the attachment port of the end hosts between the two physical edge routers. We selected this amount of mobility events because in the real-life scenario, around 5% of the endpoints change their attachment point every second.

We measured the convergence time as the handover delay, i.e. the time since the emulated host is detached until traffic is restored after it attaches to the new edge router. In order to compare both proactive and on-demand approaches, we measured the handover delay in the same topology, but with two different control plane configurations: BGP as the proactive, and LISP as the reactive. In the BGP case we used a centralized route-reflector in the edge router to distribute route updates.

Figure 11 plots the CDF of the handover delay for BGP and LISP. All values are normalized to the minimum convergence time observed during the measurement process. We can see that the proactive solution takes around 10 times more to converge than the reactive one. The reason is that the proactive approach replicates the network update to all 200 edge routers, while the on-demand approach follows traffic patterns and only updates edge routers that have active traffic to roaming hosts.

Another important observation is that the variance of the handover delay is consistently higher in the proactive approach than the reactive. This is due to the fact that the reactive architecture selectively updates only routers that are actively sending traffic to the end-host that moved, while the proactive approach updates edge routers randomly, i.e. not by their need for such update. These results show that SDA’s reactive approach can be beneficial in stressed environments such as automated

Table 5: Average number of FIB entries for a 5 week period, for day work hours (9 am to 19 pm), and nighttime.

| Router | Period | Building |
|--------|--------|----------|
|        |        | A        | B        |
| Border | All    | 50       | 291      |
|        | Day    | 85       | 362      |
|        | Night  | 19       | 227      |
| Edge   | All    | 42       | 34       |
|        | Day    | 47       | 42       |
|        | Night  | 38       | 27       |
| Decrease (All) | 16%    | 88%      |

Figure 8: Campus Network Topology (underlay routers not shown for clarity).
warehouses or large gatherings with highly mobile end-hosts.

5 Lessons Learnt

In this section we summarize several challenges and our learnings from implementing and deploying SDA in enterprise networks.

5.1 Underlay Connectivity Issues

In order for the overlay to work, there needs to be underlay connectivity. However, it is possible that an edge router fails or that an underlay IP changes, interrupting normal traffic flow. It can be challenging for the overlay to know the state of the underlay without explicit probing. To cope with these situations, edge routers monitor the address announcements of the underlay routing protocol (IS-IS or OSPF) to know about their reachability to underlay IP addresses of the other edge routers.

This way, when they detect a connectivity outage, they update their local forwarding table deleting such route and falling back to the default route to the border, until a new edge router registers the overlay address in the routing server.

5.2 Edge Routers Rebooting

One issue that can happen is a forwarding loop between the edge and border router. Assume the network is forwarding traffic, and an edge router reboots. It will start with an empty FIB for the overlay entries. When it receives traffic for one of its former endpoints, it will use the default route and forward it back to the border router, since it does not know yet its endpoints. The border router will forward this traffic to the rebooted router according to its current information, creating a forwarding loop.

Although this loop is transient and disappears once the edge router detects its endpoints, we rely on two mechanisms in such situation. First, since the edge router will not announce its underlay IP address through the underlay routing protocol while rebooting,
the tracking of the connectivity state of the underlay IP address that the other edge routers perform will remove the routes to the rebooting edge router. Second, the rebooting router will not recognize the incoming traffic, so it will send the data plane message we mentioned in sec. 3.3 to the originating edge router. This will trigger a refresh in the overlay FIB entries of the sending edge router.

5.3 Selecting the Policy Enforcement Point

In this section we discuss a bandwidth vs. network state trade-off related to the deployment of group policies. We can save bandwidth by enforcing policies on ingress (because we don’t forward traffic that will be dropped on egress), or data plane state by enforcing them on egress. On egress we save data plane state because we only need policies for the local destination groups of the endpoints that are attached to a particular edge router, as opposed to ingress, which would need policies for all possible destination groups. Taking this into account, we chose to enforce policies on egress to reduce overall state in the data plane.

In order to quantify the wasted bandwidth due to enforcing on egress, we analyzed the packet drops due to group-based ACLs in a real-life deployment leveraging egress-based policy enforcement. This deployment is a medium-large enterprise network with a campus and a few branches. For our analysis, we looked at three different devices in this deployment, a branch router, an edge device in the campus, and a VPN gateway. Combined, these three devices were serving around 11,000 endpoints during the period we monitored them. Figure 12 presents the permille of dropped traffic for the period of 5 days. We can see that in the worst case the drop rate is extremely low: 2 out of each 10k packets. The VPN router has a significantly larger amount of drops than the other routers due to the fact that it receives all the traffic from remote users, which present a different usage pattern from the users in the office.

Since this deployment performs the policy enforcement on egress, we expected a significant percentage of drops. Surprisingly, we discovered that after a new policy is applied, there is a transient period with an increase in drops, but when endpoints (which are usually humans) realize they cannot access this particular destination, they stop requesting it. Hence, the operational experience in the most common enterprise use cases shows that enforcing policies on egress does not impact significantly the amount of wasted bandwidth.

An additional benefit of enforcing on egress is a simplification of signalling. When a group rule is updated, it is necessary to notify all the affected edge routers. However, this is not easy in our design, because requests to the control plane are only triggered by data plane events. For example, consider that the policy check is implemented on ingress and that the edge router has already learned the GroupId associated to a particular destination (fig. 13 top part). Now suppose that the group associated to this destination endpoint is updated, the ingress router has no way to know it. Hence, we need a way to signal this change.

On the contrary, if the policy is enforced on egress, the (Overlay IP, GroupId) pair in the VRF is automatically updated, because the modification of endpoint data automatically triggers the authentication process again. In other words, on egress the (Overlay IP, GroupId) pair is always up to date because it is linked to the endpoints connected to that edge router. This way, we can avoid implementing an extra signaling mechanism, and the associated complexity.

5.4 Updating Policies

In our deployment experience, we found an interesting trade-off when updating policies: it can be more scalable (i.e. less signaling) moving users to different groups rather than directly updating the group-based ACLs. Indeed, this trade-off depends on the distribution of endpoints within groups of each particular deployment, i.e. few groups with large amounts of endpoints vs. high number of groups with few endpoints each. Thus, it is not always the case that changing the endpoint’s group is more scalable, but here we present two examples form our experience:

Acquisitions: in case of an acquisition, the new employees are progressively moved through different groups until they get the same group as regular employees. The reverse also holds, when part of a company is
sold, their users are moved to a group that is associated with more restrictive policies.

Service insertion: it is common that traffic has to go through middleboxes, e.g. a firewall or a WAN optimizer. In some deployments, the SDA operators decide to update the group from the packets so that devices in the service chain decide whether to apply a policy or not. In other words, instead of applying different policies across the path for the same group, they change the group along the way so that different policies are applied across this same path.

6 Related Work

6.1 SDN Pioneering Work

Ethane [1], one of the first SDN designs, presents numerous similarities with our proposal: it also targets enterprise networks, presents a similar architecture with a centralized controller, and supports incremental deployment. However, Ethane specifically focuses on three key elements, mostly around the control plane: (i) providing network access control, (ii) a rich high-level policy language, and (iii) controller design and fault-tolerance. Conversely, in this paper we pay more attention to data plane related aspects such as network isolation and resource efficiency.

Campus networks also motivated the inception of OpenFlow [17], that champions the decoupling of data plane and control plane, gives a strong focus to the interface between the router and the controller and defines and approach to implementing rich policies on capable switches. SDA in its turn gives more emphasis to ability to support scalability in heterogeneous environments with devices with different capabilities.

Finally, SANE [31] offers a simple, high-level policy interface like the one used by SDA, but SANE tackles the problem in the border between L2 and L3 and does not trust the data plane routers.

6.2 BeyondCorp and Zero Trust Networks

In terms of securing the enterprise network, a closely related work is Beyond Corp [32], also known as the Zero Trust model. Like SDA, Beyond Corp focuses on access control between network endpoints, with an especial emphasis on user-to-server connections. On the other hand, it should be noted that networking improvements (e.g. seamless mobility, etc) are not in the scope of BeyondCorp and therefore this section only discusses how SDA relates to BeyondCorp in terms of enterprise security.

BeyondCorp offers a solid approach to build secure enterprise networks by means of keeping healthy endpoints and directing traffic through access proxies. By doing so, BeyondCorp presents a security model that is agnostic to the underlying networking infrastructure. While this is a reasonable approach in certain scenarios, in our operational experience, we have found certain enterprise requirements that are hard to meet with a BeyondCorp-only approach. First, while BeyondCorp protects the access to the enterprise network, its focus is on protecting the access to enterprise applications at layer 7. However, it is not always possible to redirect traffic through the proxies (e.g. L2 traffic). Second, despite enterprise efforts around building healthy fleets of devices, the reality we observe is that insecure devices are still present in typical enterprise networks (even more due to the explosion of different IoT devices). These endpoints make the BeyondCorp approach harder to implement and, in many cases, secure on-boarding and admission still need to be performed by the network infrastructure. Third, with only a BeyondCorp security model the overall network performance could be degraded by malicious actors attempting to get access (even if unsuccessful) or explicitly looking to disrupt the network operation. SDA operates lower in the stack and not only protects the connection of devices to the network but also the network infrastructure itself. We believe that SDA complements BeyondCorp and the combination of both could contribute to strengthen the overall security of an enterprise network.

6.3 Other Related Work

Software Resolved Networks [2] also leverages a reactive protocol (DNS extensions) and a centralized database, but requires involving endpoints when resolving routes, and allows a wider range of policies than our proposal.

Other proposals for enterprise networks center their work on specific elements of an enterprise network, such as ACL configurations [15], systematic design of VLANs and ACL placement [13] or incremental SDN deployment [34].

7 Conclusion

This paper presents SDA, a solution designed for modern enterprise networks. The main goal of the architecture is supporting emerging requirements, with a strong focus on mobility, segmentation, and incremental deployment. At the same time, it provides scalability and optimizes data plane resources for heterogeneous environments with devices of diverse capabilities.

SDA leverages common practices in networking (centralized control, network overlays) and makes use of a reactive approach to distribute network information and support mobility. Experimental results show that, when compared with traditional approaches, SDA exceeds a 70% reduction in the overall forwarding state used by the network. Also, in very large deployments that need to deal with massive mobility events, network convergence is an order of magnitude faster than the status quo. For all these reasons we believe that SDA is a proper choice to address the unique requirements of modern enterprise networks that include scalable mobility, end-to-end segmentation, simplified administration, and overall resource optimization.
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