Hidden Gauge Symmetry in Holomorphic Models

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Abstract

We study the effect of a hidden gauge symmetry on complex holomorphic systems. For this purpose, we show that intrinsically any holomorphic system has this gauge symmetry. We establish that this symmetry is related to the Cauchy-Riemann equations, in the sense that the associated constraint is a first class constraint only in the case that the potential be holomorphic. As a consequence of this gauge symmetry on the complex space, we can fix the gauge condition in several ways and project from the complex phase-space to real phase space. Different projections are gauge related on the complex phase-space but are not directly related on the real physical phase-space.

Keywords: phase-space Gauge Theories, Quantization of non-Hermitian systems

1. Introduction

In several instances, in physics it is natural to select complex variables to develop a theory. For example, in Conformal Field Theory in two dimensions the conformal transformations of the metric are equivalent to the Cauchy-Riemann equations for holomorphic functions. In this paper, we consider a generalization of this concept, in the sense that, we regard a system defined in the complex space and we show that this system possesses a gauge symmetry. This symmetry is trivial when is analyzed directly in the context of the complex variables \( z = x + iy \), because it says directly that the transformation is null \( \delta z = 0 \), then all the holomorphic functions are invariant under
these transformations. However, these transformations are not trivial if we consider that the real and imaginary part of $z$ are allowed to transform on the complex plane. We show that these transformations are gauge transformations generated by a first class constraint in the context of the Dirac’s canonical method. Then by selecting a gauge condition we can map our complex system to different real systems. The interesting point is that these systems are related by a gauge transformation on the complex phase-space.

In Quantum Mechanics one of the fundamental postulates is that every measurable physical quantity $A$ is described by an operator $A$ acting on the state space; and this operator is an observable. A common hypothesis is to select Hermitian operators, in order to obtain measurable or observable quantities. This postulate implies that if we want to get all the information of the system, we must consider a complete set of commuting observables. Moreover, it has been hypothesized that some systems do not necessarily satisfy this postulate. Examples of these cases are: non-Hermitian models [1, 2], with interesting applications as to generate entanglement in many-body systems [3]. The PT-symmetry [4, 5], with striking applications in optics [6, 7]. Also, we have theories with high order time derivatives as the Pais-Uhlenbeck model for particles [8, 9, 10] and Bernard-Duncan model for fields [11], noncommutative theories [12, 13], higher order derivative theories of gravity [14, 15] and complex theories of gravity [16].

There are several ways to address these models, for example when the Hermiticity is not available, it is natural to introduce a new kind of symmetry and in this way, the notion of PT-symmetry was introduced by Bender [4]. Furthermore, Ashtekar introduced a modification of the internal product, using the reality conditions, and this procedure also solves the problem in some cases [16]. Our approach is a generalization of the Ashtekar procedure, but written in a different way. Some years ago was shown that the reality conditions can be interpreted as second class constraints in the context of the Dirac’s method of canonical quantization [17], and then the internal product is given in terms of the measure of the path integral with second class constraints. The object of this paper is to explore further this idea. We find that in any holomorphic theory there is intrinsically a gauge symmetry and the second class constraints of the Ashtekar formalism correspond to a selection of the gauge condition of the symmetry. However, there are many additional consistent gauge conditions. By selecting a gauge condition we get a different real physical system that is gauge related to another real system by a complex gauge transformation to be performed on the extended complex
phase-space. In this form, we will show that using this gauge symmetry we can relate on the complex phase-space different real systems that are not related by a canonical transformation on the real phase-space. The work is organized as follows. In Sec. 2, we introduce the gauge symmetry and we show that is related to the Cauchy-Riemann equations. In Sec. 3 starting from the complex harmonic oscillator, and by using different gauges we obtain in the real physical space the potentials \( k/2x^2, \ ax^{-1}, \ bx^{-2} \) and \(-ax^{-1}\). In Sec. 4 we generalize our construction to the two-dimensional complex space and we show that the harmonic oscillator and the Kepler problem are gauge related. In Sec. 5 we quantize the system using path integrals. Section 6 is devoted to our conclusions.

2. Complex Theory for a First Order Theory

Let us consider a complex Lagrangian that is a function of the holomorphic coordinate \( z = x + iy \) and their velocities

\[
L(z, \dot{z}) = \frac{1}{2} \dot{z}^2 - V(z)
\]  

and we are assuming that the potential \( V(z) \) is a holomorphic function of \( z \), that is,

\[
\frac{dV}{d\bar{z}} = 0
\]  

Then, it is evident that the Lagrangian is invariant under the transformations

\[
x' = x + \lambda(t), \quad y' = y + i\lambda(t).
\]  

That leave \( z \) invariant, i.e. \( \delta z = 0 \). In consequence, from this point of view our system have a trivial symmetry. On the other hand, this symmetry is more useful if we decompose \( z \) in terms of real and imaginary parts. In this case, the Lagrangian is given by

\[
L(z, \dot{z}) = \frac{1}{2} \dot{x}^2 - \frac{1}{2} \dot{y}^2 + i\dot{x}\dot{y} - V_R(x, y) - iV_I(x, y).
\]  

The associated equations of motion of the above Lagrangian are not independent, since it is possible to divide them in real and imaginary parts and we get

\[
\ddot{x} + \frac{\partial V_R(x, y)}{\partial x} = 0, \quad \ddot{y} - \frac{\partial V_R(x, y)}{\partial y} = 0,
\]
where it is clear that $x$ and $y$ are real quantities. Now, we proceed to develop the canonical formulation of this theory using the variables $x$ and $y$. We select these variables, because in terms of holomorphic coordinates $z$, our symmetry is trivial in the sense we can not establish, any relation between the holomorphic and anti-holomorphic coordinates. The canonical momenta for the Lagrangian (1), are

$$ p_x := \frac{\partial L}{\partial \dot{x}} = \dot{x} + i\dot{y}, \quad p_y := \frac{\partial L}{\partial \dot{y}} = -\dot{y} + i\dot{x}. $$

(6)

Using these definitions, we obtain the primary constraint

$$ \Phi = 2p_\bar{z} = p_x + ip_y \approx 0, $$

(7)

where we introduce the weak equality symbol "≈" to emphasize that the quantity $\Phi$ is numerically restricted to be zero but does not identically vanish throughout phase space [18]. Following the usual definition of the canonical Hamiltonian in the phase-space

$$ H = \dot{x}p_x + \dot{y}p_y - L, $$

(8)

we observe that $H, L, p_x, p_y$ are complex quantities. Through the definition (8) we obtain the explicit total Hamiltonian

$$ H_T = \frac{p_\bar{z}^2}{2} + V(z) + \mu\Phi = \frac{1}{2}p_x^2 + V_R(x, y) + iV_I(x, y) + \mu\Phi, $$

(9)

where we add the primary constraint following the Dirac’s method [19]. The resulting equations of motion are

$$ \dot{x} = \{x, H_T\} = p_x + \mu, \quad \dot{y} = \{y, H_T\} = p_y + i\mu, $$

(10)

$$ \dot{p}_x = \{p_x, H_T\} = -\frac{\partial V}{\partial x}, \quad \dot{p}_y = \{p_y, H_T\} = -\frac{\partial V}{\partial y}. $$

(11)

Using equations (10) we observe that there is a gauge freedom since we have an arbitrary Lagrange multiplier. It is important to note that the temporal evolution is not necessarily a real quantity, so our real variables $x$ and $y$ under evolution could obtain an imaginary contribution.

In the following, we are going to evolve the primary constraint (7) and in this way we should understand what kind of constraint is, first or second class. The primary constraint $\Phi$ evolves as

$$ \dot{\Phi} = \{\Phi, H\} = -2\frac{dV(z)}{dz} \approx 0. $$

(12)
In the present case, we observe that the temporal evolution of $\Phi$ imposes
as a result the Cauchy-Riemann equations for $V(x, y)$ (see Eq. (2)). In
consequence if $V(x, y)$ holomorphic function we obtain that $\Phi$ is first class
constraint. Furthermore, there are no additional constraints and we will get
as a result that our reduced phase-space has therefore two degrees of freedom.
In the other hand, following the Dirac’s quantization method the physical
states are defined by imposing that the action of the first class constraint
over the states is equal to zero. In the coordinate representation this we will
imply
\[
\left(-i\hbar \frac{\partial}{\partial x} + \hbar \frac{\partial}{\partial y}\right) [G_R(x, y) + iG_I(x, y)] = 0,
\]
resulting the Cauchy-Riemann equations, if we decompose in real and imag-
inary parts. In this way, the Cauchy-Riemann equations appear in this for-
malism as an invariance under translations generated by the constraint. In
other words, we obtain that our theory is compatible with the Dirac’s for-
mulation [19, 18], but it must satisfy that the potential is a holomorph ic
function
\[
\hat{\Phi}V(x, y) = 0. \tag{14}
\]

Now, following the Dirac’s conjecture this constraint will be the gene-
erator of gauge transformation [19]. The transformations produced by the first class
constraint are
\[
\begin{align*}
\delta x &= \{x, \epsilon \Phi\} = \epsilon, & \delta y &= \{y, \epsilon \Phi\} = i\epsilon, \\
\delta p_x &= \{p_x, \epsilon \Phi\} = 0, & \delta p_y &= \{p_y, \epsilon \Phi\} = 0.
\end{align*} \tag{15}
\]

In consequence, we get
\[
\delta z = \{z, \Phi\} = 0, \tag{17}
\]
in agreement with the transformations (3). From a pragmatic point of view
$z$ and $p_z$ are Dirac’s observables with null variation, but it implies a more
complicated structure if we take in account the variation of the real and
imaginary part of $z$. In this framework and if we pay attention to the equa-
tions (10), it is necessary to impose a gauge condition in order to obtain a
real reduced phase-space. Then according to the gauge condition that we
choose we can obtain a different real theory. The interesting point is that
all these real theories are connected by a complex gauge transformation in the original extended phase-space. In fact, the equations of motion that we get from the Hamiltonian formulation are complex quantities obtained for the real and imaginary parts. Furthermore, the phase-space is wider than the configuration space since $\mu$ exists in this formulation, and it is possible to choose as a real quantity either $\delta x$ or $\delta y$. For the purpose of applying a method that is not trivial using this mathematical structure, we must propose a gauge condition on the real or imaginary part of $z$ in such way that the resulting theory be real and in consequence the imaginary degrees of freedom be eliminated. Furthermore, this will produce that the components, real and imaginary, interact with each other and send information from one side to the other. In addition, the procedure is not forcing us to fix the gauge symmetry for the Hamiltonian in a specific way and the gauge condition is selected according to the real model that we wish to build. It shares a common origin with the Ashtekar’s complex models based on the reality conditions and the imposition of the gauge condition is equivalent to the introduction of the internal product [20]. However, the reality conditions are a single way to select a gauge condition. Whereas, there are a lot of ways to remove this freedom in the complex systems so we get to a Hermitian system.

The next step is to determine the Lagrange multiplier $\mu$ [10], using the gauge condition $\gamma(x, y)$. The canonical evolution of this condition gives us

$$\dot{\gamma} = \{\gamma, H_T\} = \{\gamma, H + \mu\Phi\} = \{\gamma, H\} + \mu\{\gamma, \Phi\} \approx 0,$$

then

$$\mu \approx -\frac{\{\gamma, H\}}{\{\gamma, \Phi\}} = -\frac{p_x \frac{\partial \gamma}{\partial x}}{\left(\frac{\partial \gamma}{\partial x} + i\frac{\partial \gamma}{\partial y}\right)}.$$

This implies for the equations of motion the following expressions

$$\dot{x} = [1 - \frac{\partial \gamma}{\partial x} + i\frac{\partial \gamma}{\partial y}] p_x, \quad \dot{y} = -i \frac{p_x \frac{\partial \gamma}{\partial x}}{\left(\frac{\partial \gamma}{\partial x} + i\frac{\partial \gamma}{\partial y}\right)},$$

$$\dot{p}_x = \{p_x, H_T\} = -\frac{\partial V_R(x, y)}{\partial x} - i\frac{\partial V_I(x, y)}{\partial x},$$

$$\dot{p}_y = \{p_y, H_T\} = -\frac{\partial V_R(x, y)}{\partial y} - i\frac{\partial V_I(x, y)}{\partial y}.$$

Now, assume that the gauge condition is of the form

$$\gamma_1 = y - ig_1(x) \approx 0.$$
and it determines a concrete value for \( \mu \)

\[
\mu_1 \approx \frac{\{(y - ig_1(x)), H\}}{\{(y - ig_1(x)), \Phi\}} = - \frac{p_x \frac{\partial g_1(x)}{\partial x}}{(\frac{\partial g_1(x)}{\partial x} - 1)},
\]

(23)

with the resulting equations of motion for the reduced phase-space,

\[
\dot{x} = [1 - \frac{\partial g_1(x)}{\partial x} (\frac{\partial g_1(x)}{\partial x} - 1)]p_x,
\]

(24)

\[
\dot{p}_x = \{p_x, H_T\} = - \frac{\partial V_R(x, ig_1)}{\partial x} - i \frac{\partial V_I(x, ig_1)}{\partial x},
\]

Now, if the potential is a power series in \( z \) then

\[ V(z) = az^n = V_R(x, y) + iV_I(x, y) \]

(25)

for \( n \) even or odd, we get

\[
V_R(x, y) \sim x^m y^l \quad V_I(x, y) \sim x^i y^j
\]

(26)

with \( n \) even, \((m, l)\) are even and \((i, j)\) are odd. In the case that \( n \) is odd, we get that \((m, j)\) are odd and \((l, i)\) are even. Then by Eq. (24) the evolution of \( p_x \) is real and the gauge condition (22) projects correctly. So, \( x \) and \( p_x \) are real quantities and they don’t leave the real space, with the evolution. Furthermore, using this procedure the imaginary part in the potential contributes to the real part through the gauge condition.

However the method described above is meaningful, if the power series of \( V(z) \) is multiplied by a real constant but if we have an imaginary constant in front of \( V(z) \) the method does not work. In order to confront this case, we need a new gauge condition

\[ \gamma_2 = x - ig_2(y) \approx 0. \]

(27)

Now, the real quantities will be \( y, p_y, \dot{p}_y \) and \( L, H \). We obtain a similar situation to (20) and (21) as in the case of \( \gamma_1 \). Also we can select another kind of gauge conditions as

\[ y = ix + ig_1(x) + ig_2(x)p_x + ig_2(x)p_x^2 \]

(28)

In this case, we must look at real solutions to the momentum \( p_x \) in terms of velocities. For this specific example, the second order action gets a term
with a velocity dependent metric. Then by selecting an appropriated gauge condition we will get a map from the complex phase-space to the real physical space. Now, if we want to quantize the real theory we can follow two paths, first we can compute the corresponding Dirac’s brackets for the variables on the reduced phase-space and promote these brackets to commutators. The second procedure is to build the measure of the path integral using the Senjanovic procedure [21]. In the next sections, we will describe by several examples how the procedure works specifically.

3. Complex Harmonic Oscillator and gauge related systems

In order to describe how the procedure introduced works explicitly, we select the harmonic oscillator. First, we consider a complex extension of the ordinary Lagrangian, given by

\[ L = \frac{1}{2} \dot{z}^2 - \frac{\omega^2}{2} z^2 \]  

(29)

where \( z \) is a complex variable that is separated into real and imaginary parts

\[ z = x + iy. \]  

(30)

The Lagrangian in terms of these variables is

\[ L(x,y) = \frac{1}{2} \dot{x}^2 - \frac{1}{2} \dot{y}^2 + i \dot{x} \dot{y} - \frac{\omega^2}{2} x^2 + \frac{\omega^2}{2} y^2 - i \omega^2 x y \]  

(31)

and we obtain the momenta

\[ p_x = \dot{x} + i \dot{y}, \]  

(32)

\[ p_y = -\dot{y} + i \dot{x}. \]  

(33)

We observe that these momenta are not independent, then generate the primary constraint

\[ \Phi_0 = p_x + i p_y \approx 0. \]  

(34)

The next step is to obtain the canonical Hamiltonian

\[ H_0 = \dot{x} p_x + \dot{y} p_y - L(x,y), \]  

(35)

and the total Hamiltonian will be

\[ H_T = \frac{1}{2} p_x^2 + \frac{\omega^2}{2} x^2 - \frac{\omega^2}{2} y^2 + i \omega^2 x y + \mu_0 \Phi_0. \]  

(36)
On the other hand, the Poisson brackets are
\[ \{x, p_x\} = 1, \quad \{y, p_y\} = 1. \quad (37) \]

Now, the evolution of the constraint (34) give us
\[ \{\Phi_0, H_T\} = 0, \quad (38) \]
resulting that \( \Phi_0 \) is a complex first class constraint.

The gauge transformations induced by this constraint on the phase-space are
\[ \delta x = \{x, \mu \Phi_0\} = \mu, \quad \delta y = \{y, \mu \Phi_0\} = i\mu, \quad (39) \]
\[ \delta p_x = \{p_x, \epsilon^0 \Phi_0\} = 0, \quad \delta p_y = \{p_y, \epsilon^0 \Phi_0\} = 0. \quad (40) \]

Here we observe that for \( \mu \) real, the gauge transformation over the real variable \( y \) induces an imaginary part, then this part can influence the real part of the Lagrangian and in this form to modify the dynamics of the real system. As a simple example, we choose the gauge condition that leads to the usual Hermitian structure
\[ \gamma_0 = y \approx 0. \quad (41) \]

The Lagrange multiplier is obtained through Dirac’s method and we get
\[ \dot{\gamma}_0 = \{\gamma_0, H_T\} = \mu^0 \{\gamma_0, \Phi_0\} = i\mu^0 \approx 0, \quad (42) \]

The equations of motion from (10) and (11) yield
\[ \dot{x} = \{x, H_T\} = p_x + \mu^0, \quad \dot{p}_x = \{p_x, H_T\} = -\omega^2 x + i\omega^2 \gamma_0. \quad (43) \]

The second equation says that the time evolution for \( p_x \) is real. However, \( \gamma_0 \) must be a good gauge condition and this implies that together with the constraint (34), must be a set of second class constraints \( \chi_a = (\Phi_0, \gamma_0) \). The matrix \( C_{ab} = \{\chi_a, \chi_b\} \) for the constraints is
\[ C_{ab} = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}. \quad (44) \]

with determinant
\[ \det (C_{ab}) = -1. \quad (45) \]
Then, the gauge condition $\gamma_0$ implies for the momentum

$$p_x = \dot{x} + i\dot{\gamma}_0 \approx p_{xR}, \quad (46)$$

that it is a real quantity. The Hamiltonian (36) is reduced to

$$H_{HO} = \frac{1}{2}p_{xR}^2 + \frac{\omega^2}{2}x^2. \quad (47)$$

and the corresponding Lagrangian is the usual one

$$L_{HO} = \frac{1}{2}\dot{x}^2 - \frac{\omega^2}{2}x^2. \quad (48)$$

So in this way, we get the real harmonic oscillator. Indeed, by fixing the gauge condition (41) we recover the real harmonic oscillator. Another alternative way to fix the gauge condition is

$$\gamma_1 = y - ix + iU_1 \frac{\dot{x}}{2U_{\frac{1}{2}}(x)} \approx 0, \quad (49)$$

$$\{\Phi, \gamma_1\} = -\frac{i}{2U_{\frac{1}{2}}(x)}\partial_x U(x). \quad (50)$$

We use this particular form of the gauge condition to get an interesting form for the Hamiltonian in the reduced phase space (see Eq. (55)). Now, we get the set of second class constraints $\chi_{1a} = (\Phi_0, \gamma_1)$, with the corresponding matrix of second class constraints given by

$$\mathbf{A}_{ab} = \begin{pmatrix} 0 & -\frac{i}{2U_{\frac{1}{2}}(x)}\partial_x U(x) \\ \frac{i}{2U_{\frac{1}{2}}(x)}\partial_x U(x) & 0 \end{pmatrix}. \quad (51)$$

and the inverse matrix yields

$$\mathbf{A}^{ab} = \begin{pmatrix} 0 & -2\frac{i}{\partial_x U(x)}U_{\frac{1}{2}}(x) \\ 2\frac{i}{\partial_x U(x)}U_{\frac{1}{2}}(x) & 0 \end{pmatrix}. \quad (52)$$

The associated determinant is

$$\det \mathbf{A}_{ab} = -\frac{[\partial_x U(x)]^2}{4U(x)}. \quad (53)$$

We observe here, that the gauge (49) must be accessible, this means that given any set of canonical variables there must exist a gauge transformation
that maps the given set onto a set that satisfies (49). Furthermore, the condition (49) must fix the gauge completely and that is the case only if the determinant (53) is different from zero. If the determinant vanishes in some point, the gauge condition is not defined globally and we have a Gribov obstruction [22, 23]. If this is not the case, the corresponding Dirac’s bracket is

\[ \{x, p_x\}^* = \frac{2U^\frac{1}{2}(x)}{\partial_x U(x)}, \]  

we note that this gauge condition generates a non-canonical transformation. The Hamiltonian in the reduced phase space is

\[ H_R = \frac{1}{2}p_x^2 + \frac{\omega^2}{2}U(x), \]  

and we obtain that the action in the reduced space is

\[ S_{1R} = \int dt \left[ \frac{\partial_x U(x)}{2U^\frac{1}{2}(x)} \dot{x} p_x - H_R \right], \]  

From the variation with respect to \( p_x \) we can get the momentum in terms of the velocities

\[ p_x = \left[ \frac{\partial_x U(x)}{2U^\frac{1}{2}(x)} \right] \dot{x}, \]  

that it is consistent with the expression (24). In consequence the action in the configuration space is

\[ S_{1R} = \int dt \left( \frac{\partial_x U}{2U^\frac{1}{2}} \right)^2 \left[ \frac{1}{2} \dot{x}^2 - \omega^2 \frac{2U^2}{(\partial_x U)^2} \right]. \]  

For the Lagrange’s multiplier we get

\[ \mu_1 = p_x \left[ 1 - \frac{2U^\frac{1}{2}(x)}{\partial_x U(x)} \right] = \left[ \frac{\partial_x U(x)}{2U^\frac{1}{2}(x)} - 1 \right] \dot{x}, \]  

Note that if we assume that the gauge condition (49) is infinitesimal related to the gauge condition (41), the associated gauge transformation that related one system with the other is

\[ \bar{x} = x - i\delta \gamma \{x, \Phi\}, \quad \bar{x} = U^\frac{1}{2}(x), \]  

11
where
\[ \delta \gamma = \gamma_1 - \gamma_0 \]  
with the objective of replacing $\bar{x}$ with $x$ in (48) to obtain (58).

To rewrite the action (56) in more conventional way we introduce the reparametrization

\[ \frac{d\tau}{dt} = [\frac{4U}{(\partial_x U)^2}] \],

then the action (56) is transformed to

\[ S = \int d\tau \left[ \frac{1}{2}(x')^2 - \frac{\omega^2}{8} (\partial_x U)^2 \right]. \]

for the above action, the new momentum is

\[ p_{x'} = x' = (\frac{dt}{d\tau}) \dot{x} = \frac{(\partial_x U)^2}{4U} \dot{x} = \frac{\partial_x U}{2U^{1/2}} p_x, \]

and we get the trivial symplectic structure

\[ \{ x, p_{x'} \}^* = \{ x, \frac{\partial_x U}{2U^{1/2}} p_x \}^* = 1, \]

The new Hamiltonian with this reparametrization is

\[ H_{x'} = \frac{1}{2} p_{x'}^2 + \frac{\omega^2}{8} (\partial_x U)^2. \]

So, it is possible to establish a relationship, by means of a gauge transformation, between the harmonic oscillator and a system with arbitrary potential given by $V(x) = \frac{\omega^2}{8} (\partial_x U)^2$ in one dimension.

If we consider that $U(x) = 2\sqrt{8}x^{1/2}$ where it is noted that the domain of the function is $(0, \infty)$. Then the reduced Hamiltonian for this $U(x)$ is

\[ H_C = \frac{1}{2} p_{x'}^2 + \frac{\omega^2}{x}. \]

Here $\omega$ is an electrical charge, in particular we are thinking in an electron-electron system.
On the other hand, we can also find a mapping from the complex Harmonic Oscillator to a Lagrangian that is invariant under the conformal group \[24\] and resulting a gauge transformation between this conformal Lagrangian and the real harmonic oscillator. If we choose \(U = \log |x|\) and using (63) we have

\[
S = \int d\tau [\frac{1}{2} (x')^2 - \frac{\omega^2}{8} \frac{1}{x^2}],
\]

that is conformal invariant. The Hamiltonian corresponding using (66) is

\[
H_x' = \frac{1}{2} p_{x'}^2 + \frac{\omega^2}{8} \frac{1}{x^2}.
\]

In this way we establish a transformation between the real Harmonic oscillator model and the conformal action (68). Furthermore, we may also think in a central potential with a negative charge so it is necessary to establish another gauge condition

\[
\gamma_{-1} = x + iy - iU^\frac{1}{2}(y) \approx 0,
\]

\[
\{ \Phi, \gamma_{-1} \} = -\frac{1}{2U^\frac{1}{2}} \partial_y U(y),
\]

In this case the Dirac’s bracket is

\[
\{ y, p_y \}^* = \frac{2U^\frac{1}{2}(y)}{\partial_y U(y)},
\]

and the resulting momentum generated by this condition is

\[
p_y = -\frac{\partial_y U(y)}{2U^\frac{1}{2}(y)} \dot{y}.
\]

The action associated to the gauge condition (70) will be

\[
S_{2R} = \int dt \left( \frac{\partial_y U}{2U^\frac{1}{2}} \right)^2 \left[ -\frac{1}{2} \dot{y}^2 - \omega^2 \frac{2U^2}{(\partial_y U)^2} \right],
\]

and as previously was done, we need a new parameterization

\[
\left( \frac{d\tau}{dt} \right) = -\frac{4U}{(\partial_y U)^2}
\]
resulting a new action from (74). Now using $U(y) = 2\sqrt{8y^2}$ we obtain

$$S = \int d\tau \left[ \frac{1}{2} (y')^2 + \frac{\omega^2}{y} \right].$$

(76)

So, the new momentum will be

$$p_y' = y' = (\frac{dt}{d\tau}) \dot{y} = -\frac{(\partial_y U(y))^2}{4U(y)} \dot{y} = \frac{\partial_y U}{2U^2} p_y;$$

(77)

and finally we will get the Hamiltonian with opposite sign

$$H_C = \frac{1}{2} p_y'^2 - \frac{\omega^2}{y}$$

(78)

wherewith, we establish the mapping for this central potential with opposite sign. In the next section we will show that our idea can be extended to a systems with more degrees of freedom and that our transformation is related to a non-canonical mapping in two dimensions.

4. Two dimensional case

We now describe our strategy for a system with more degrees of freedom. Specifically, we consider a two dimensional case and we find a gauge transformation between the harmonic oscillator and a central field.

The initial complex model is given by the Lagrangian

$$L(z_1, z_2) = \frac{1}{2} \dot{z}_1^2 + \frac{1}{2} \dot{z}_2^2 - \frac{\omega_1^2}{2} z_1^2 - \frac{\omega_2^2}{2} z_2^2$$

(79)

with $z_1 = x + iy$ and $z_2 = u + iv$. From, the above Lagrangian we get the momenta

$$p_x = \dot{x} + i\dot{y}, \quad p_y = -\dot{y} + i\dot{x},$$

$$p_u = \dot{u} + i\dot{v}, \quad p_v = -\dot{v} + i\dot{u},$$

(80)

resulting into two first class constraints

$$\Phi_0 = p_x + ip_y \approx 0,$$

$$\Phi_1 = p_u + ip_v \approx 0.$$
In consequence it is necessary to include two gauge conditions

\begin{align*}
\gamma_0 &= x + iy - iU_1^\frac{1}{2}(y, v) \approx 0, \\
\gamma_1 &= u + iv - iU_1^\frac{1}{2}(y, v) \approx 0.
\end{align*}

The full set of second class constraints will be \( \chi_A = (\Phi_0, \gamma_0, \Phi_1, \gamma_1) \), with the matrix of second class constraints \( C_{AB} = \{\chi_A, \chi_B\} \) given by

\begin{equation}
C_{AB} = \begin{pmatrix}
0 & -\frac{1}{2} \partial_y U_1^\frac{1}{2} & 0 & -\frac{1}{2} \partial_y U_1^\frac{1}{2} \\
\frac{1}{2} \partial_y U_1^\frac{1}{2} & 0 & \frac{1}{2} \partial_v U_1^\frac{1}{2} & 0 \\
0 & -\frac{1}{2} \partial_v U_1^\frac{1}{2} & 0 & -\frac{1}{2} \partial_v U_1^\frac{1}{2} \\
\frac{1}{2} \partial_v U_1^\frac{1}{2} & 0 & \frac{1}{2} \partial_u U_1^\frac{1}{2} & 0
\end{pmatrix}.
\end{equation}

and the corresponding determinant

\begin{equation}
\det C_{AB} = \left[ \left( \partial_y U_1^\frac{1}{2} \partial_v U_1^\frac{1}{2} - \partial_y U_1^\frac{1}{2} \partial_v U_1^\frac{1}{2} \right)^2 \right] \neq 0.
\end{equation}

The total Hamiltonian for this case results

\begin{equation}
H_T(y, v) = -\frac{1}{2} p_y^2 - \frac{1}{2} p_v^2 + \frac{\omega_1^2}{2} r^2 - \frac{\omega_2^2}{2} y^2 + i\omega_1^2 xy
\end{equation}

\begin{equation}
-\frac{1}{2} p_r^2 + \frac{\omega_1^2}{2} u^2 - \frac{\omega_2^2}{2} v^2 + i\omega_2^2 uv + \mu^0 \Phi_0 + \mu^1 \Phi_1.
\end{equation}

In the reduced space the momenta are determined by

\begin{equation}
\begin{align*}
p_y &= -\frac{d}{dt}(U_1^\frac{1}{2}), \\
p_v &= -\frac{d}{dt}(U_1^\frac{1}{2}).
\end{align*}
\end{equation}

In the same way we can apply in (85), the constraints (81) and the gauge conditions (82) resulting

\begin{equation}
H_R = -\frac{1}{2} p_y^2 - \frac{1}{2} p_v^2 + \frac{\omega_1^2}{2} U(y, v) + \frac{\omega_2^2}{2} U(y, v),
\end{equation}

By selecting the variables \( r^2 = y^2 + v^2 \) and \( y = r \cos(\theta) \) and \( v = r \sin(\theta) \) the reduced Lagrangian is

\begin{equation}
L_R = -\frac{1}{2} \left[ \left( \frac{dU_1^\frac{1}{2}}{dt} \right)^2 + \left( \frac{dU_1^\frac{1}{2}}{dt} \right)^2 \right] - \frac{\omega_1^2}{2} U(r, \theta) - \frac{\omega_2^2}{2} U(r, \theta)
\end{equation}
Now by choosing equal frequencies $\omega_1 = \omega_2$ and with the potential given by

\[
U = \frac{y}{r^\beta} = r^{1-\beta} \cos(\theta), \quad U = \frac{v}{r^\beta} = r^{1-\beta} \sin(\theta).
\]

(89)

We obtain for the determinant of the constraint algebra the following expression

\[
\det | C_{AB} | = \frac{(2\beta y^2 + 2\beta v^2 - 1)^2}{(y^2 + v^2)^{4\beta}},
\]

(90)

and the reduced phase-space action is

\[
S_R = \int dt \left[ -\frac{1}{2} r^{2-2\beta} \dot{r}^2 - \frac{(1-\beta)^2}{2} r^{-2\beta} \dot{\theta}^2 - \frac{\omega_1^2}{2} r^{2(1-\beta)} \right].
\]

(91)

Using a new selection of time

\[
\left( \frac{d\tau}{dt} \right) = r^{2\beta}, \quad \dot{\tilde{A}} = \frac{dA}{d\tau},
\]

(92)

and the following change of variables

\[
\tilde{\theta} = \frac{1}{(1-\beta)} \theta, \quad \tilde{r} = (1-\beta) r, \quad \omega_1^2 = \tilde{\omega}_1^2 (1-\beta)^2 (1-2\beta)
\]

(93)

we will get the action

\[
\tilde{S}_R = \int d\tau \left[ -\frac{1}{2} \tilde{r}^{2\beta} \dot{\tilde{r}}^2 - \frac{1}{2} \tilde{r}^2 - \frac{\tilde{\omega}_1^2}{2} \tilde{r}^{2(1-2\beta)} \right]
\]

(94)

with Hamiltonian

\[
\tilde{H}_R = \frac{1}{2} (p_{r}^2 + p_{\tilde{\theta}}^2) - \frac{\tilde{\omega}_1^2}{2} \tilde{r}^{2(1-2\beta)},
\]

(95)

we observe that for $\beta = \frac{3}{2}$, this Hamiltonian is reduced to the Kepler central problem. So in this way we have shown that our formalism also works for systems in more dimensions. In next section we establish how to quantize these systems using path integrals.
5. Path Integral for the Complex Harmonic Oscillator

In order to establish the respective quantum mechanics of our complex theories using path integrals we employ the Senjanovic’s method, that allows to quantize systems with second class constraints [21]. As an example, we consider the complex harmonic oscillator (29), with gauge condition $\gamma_1$ in the path integral, and we introduce the notation

$$\xi^a = (x, y), \quad \rho_a = (p_x, p_y),$$

$$\tau_a = (\Phi, \gamma_1)$$

(96)

(97)

where $\xi^a$ includes the real and imaginary parts of $z$, and $\rho_a$ is in principle a complex quantity. After that we obtain the measure of the path integral that includes first class constraint and gauge condition and it is

$$D\Xi = D\xi^a D\rho_a \det \{ \tau_A, \tau_B \} \delta(\tau_C)$$

(98)

and the total path integral is

$$Z = \int D\Xi \exp\left[ i \int dt (\dot{x}p_x + \dot{y}p_y - H_T) \right].$$

(99)

If we eliminate $(y, p_y)$, by means of the delta functionals $\delta(\tau_C)$ we will get

$$Z_R = \int DxDp_x \prod_i \frac{2U^{\frac{1}{2}}(x_i)}{\partial_x V(x_i)} \left| - \frac{i}{2U^{\frac{1}{2}}} \partial_x U(x_i) \right|$$

$$\exp\left[ i \int dt \left( \frac{\partial_x U(x)}{2U^{\frac{1}{2}}(x)} \dot{x}p_x - H_R \right) \right].$$

(100)

or using the reparametrization (62) we obtain

$$Z_C = \int DxDp_{x'} \exp\left[ i \int d\tau (\dot{x}p_{x'} - H_{x'}) \right].$$

(101)

with the Hamiltonian $H_{x'}$ given by (66). In this way, by integrate variables $y, p_y$ using the constraint and gauge condition, we obtain a real path integral. It is necessary to mention that the complex number don’t have ordering, but we use temporal partitions as a way to order.
6. Conclusions

In this letter, we have shown that there exists in any complex holomorphic system a hidden gauge symmetry. This symmetry allows us to map the complex system to several real systems, depending on the gauge condition used. By means of the Dirac’s method and the Cauchy-Riemann structure, we handle the complex theories establishing a relationship with real systems using the gauge symmetry. In this context, the selection of Hermitian variables, reality conditions [20], or \( \mathcal{PT} \) symmetry [5], can be seen as gauge conditions for the first class constraints.

The procedure established can be summarized as follows: First, we start with a complex holomorphic model. As a second step, it is separated in real and imaginary parts. As a third step, we found primary constraints for the complex momenta and they evolve correctly in the complex theory, because of the Cauchy-Riemann equations. As a fourth step, the Hamiltonian is obtained. Finally, we propose gauge conditions as Hermitian conditions and check the degrees of freedom. Then we have a set of second class constraints and we can quantize this system directly using the path integral. For different gauge choices, we can get several real systems that are not related by a canonical transformation in the real phase space but these systems are related by a gauge transformation in the complex phase space. This situation is in some sense analogous to the two time physics of Bars [25], where in the extended phase space physical systems as the free particle and the harmonic oscillator are gauge related. The analysis can also be extended to arbitrary complex dimensions and for systems with high order derivative theories as the Pais-Uhlenbeck model [26].

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