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Adaptive self-organization in the embryo: its importance to adult anatomy and to tissue engineering

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Abstract

The anatomy of healthy humans shows much minor variation, and twin-studies reveal at least some of this variation cannot be explained genetically. A plausible explanation is that fine-scale anatomy is not specified directly in a genetic programme, but emerges from self-organizing behaviours of cells that, for example, place a new capillary where it happens to be needed to prevent local hypoxia. Self-organizing behaviour can be identified by manipulating growing tissues (e.g. putting them under a spatial constraint) and observing an adaptive change that conserves the character of the normal tissue while altering its precise anatomy. Self-organization can be practically useful in tissue engineering but it is limited; generally, it is good for producing realistic small-scale anatomy but large-scale features will be missing. This is because self-organizing organoids miss critical symmetry-breaking influences present in the embryo: simulating these artificially, for example, with local signal sources, makes anatomy realistic even at large scales. A growing understanding of the mechanisms of self-organization is now allowing synthetic biologists to take their first tentative steps towards constructing artificial multicellular systems that spontaneously organize themselves into patterns, which may soon be extended into three-dimensional shapes.

Key words: mini-organ; organoid; symmetry; symmetry-breaking; synthetic biology; synthetic morphology.

Introduction: the paradox of anatomical variation

One of the first things that medical students learn of human anatomy, usually to their frustration, is that its details are surprisingly variable. Blood vessels can vary in route and number (Dăescu et al. 2012; Bertrand et al. 2014; Silva et al. 2014; Marco-Clement et al. 2016; Tomaszewski et al. 2017), innervation of the same structure can differ between individuals (Matejcík, 2010; Henry et al. 2016; Wolf et al. 2016), the number of bones in the cranium can vary due to occasional appearance of wormian (intrasutural) bones (Hess, 1946; Ghosh et al. 2017), and there are many more examples of unpredictable anatomy in anatomical and surgical literature. Some of these differences may be specified genetically, but studies of monozygotic twins have demonstrated that histogenesis can vary even when driven by exactly the same ‘genetic programme’. This fact even finds application in the forensic sciences; while the ‘DNA fingerprints’ of monozygotic twins are the same, their literal fingerprints are readily distinguishable (Srihari et al. 2008; Kücken & Champod, 2013). Palatal rugae also differ between monozygotic twins (Herrera et al. 2017), while patterns of cortical gyrification and dentition can, but do not always, do so (Townsend et al. 2005; Kates et al. 2009).

In this review, I will consider possible sources of this variation, with a particular focus on processes of self-organization that produce anatomies that are predictable in terms of overall statistical properties but not in terms of fine detail. The review will then consider practical uses for this self-organization, and current limitations.

Anatomical variation that cannot be explained genetically is traditionally accounted for in terms of environmental influences or developmental errors. Environmental differences can be largely discounted for anatomical features that arise during foetal development, especially between identical twins, although it is possible that the precise site of placental implantation into the uterus might affect a limited number of things. This leaves error – the notion that variation arises through inaccurate following of the genetically specified developmental programme. A simple error theory, however, runs into a problem: it is in the nature of embryonic development that the morphogenetic events of each stage build on the results of events at previous stages.
Errors would therefore be cumulative and, if each event were directly programme-driven, even a perfectly executed second mechanism could go badly wrong if it followed an earlier error. In this system, for example, a ‘perfectly’ positioned artery, in terms of textbook diagrams, would fail to bring blood to an organ if the organ’s rudiment had been placed atypically through a previous error. If every stage of embryonic development was as variable as adult anatomy, and all events ran directly to a genetic programme, one would expect development of a complex body to degenerate into a chaos of collisions and missed connections. Yet it does not: that is a paradox for anyone who regards development as the direct following a set of instructions in a genetic programme.

A second paradox comes from the observation that the functional tissue elements (alveoli, islets, glomeruli, capillaries, etc.) of large and small mammals are of similar size (linear dimensions differing by no more than a factor of 3 or so); the organs of large mammals simply contain more of them, typically around 1000 times more in human than in mouse. That means thousands of times more items to be properly positioned, yet the genomes of humans and mice are of similar size, at about 3 Gigabases, containing about 19 000 protein-coding genes (International Human Genome Sequencing Consortium, 2001; Chinwalla et al. 2002; Euskirchen et al. 2014). The similar sizes, and the fact that there are far fewer genes than body structures, challenge the idea of genes specifying anatomy in any direct way.

A solution to the paradox, a solution that has been written about many times before (Turing, 1953; Meinhardt & Gierer, 2000; Davies, 2005; Bozorgmehr, 2014), although it has not succeeded in expunging the idea of anatomical features being under direct genetic control (‘a gene for’ a specific anatomical feature), is to view anatomy as emerging from a complex interaction of cells that use communication to organize themselves according to the conditions in which they actually find themselves. Understanding the basis of this adaptive self-organization is therefore critical for understanding development, for understanding how variation arises, and for explaining how it can do so harmlessly. It also promises to offer valuable new approaches to tissue engineering.

Adaptive self-organization: constancy and change

The principles of adaptive self-organization in development can be illustrated by the well-known system that adapts the anatomy of capillary systems to the tissue that must be served. Tissue cells produce a transcription factor, Hif-1α, that is unstable in the presence of oxygen (Maxwell et al. 1999; Cockman et al. 2000). Hif-1α, when it survives, drives transcription of vascular endothelial growth factor (VEGF; Liu et al. 1995; Forsythe et al. 1996), and VEGF diffuses away and acts as an inducer of capillary sprouting and a chemoattractant for the new sprouts (Millauer et al. 1993; Yu & Sato, 1999). The effect of this is that the capillary system automatically grows and adapts to serve the needs of growing tissues that experience hypoxia by out-growing their existing capillary supply. The amino acid sequences of the protein machines that underly this system are of course specified by genes, but the vascular anatomy that emerges from the action of those machines is not (see Davies, 2005, for more detailed discussion).

The mechanism for adaptive capillary formation described above relies on negative feedback of a type seen in many examples of physiological homeostasis (thermostat, glucostat, etc.: see Romanovsky, 2007; Röder et al. 2016 for recent reviews). The main difference is that, whereas conventional homeostatic systems have evolved to resist change, self-organizing ones have evolved to accommodate and to drive change. When a tissue grows and acquires new capillaries, it changes quickly; what is conserved is not the physical anatomy but rather the abstract architecture of the tissue. In this case, the relevant architecture can be described in terms of density of capillaries. In the cases presented below, it can be described in terms of the relationship between different cell types at the ends of a branching tree or of the connections between different types of tubules. The concept of conserved architectures extends beyond anatomy and can be applied, for example, to proportions of stem and differentiated cell types in a population or to the energy fluxes through different metabolic pathways (Schilling et al. 1999; Rodríguez-Brenes et al. 2013; Lavington et al. 2014; Batsivari et al. 2017).

Self-organizing processes operate through a very wide range of organization levels, in both embryonic and adult lives. They are seen at the subcellular level in the assembly of macromolecular complexes (Misteli, 2001; Kurakin, 2005; Karsenti, 2008; Gordon et al. 2012), at the level of cell populations and tissues (Green et al. 2004; Takeichi, 2011), and extend even beyond the individual organism to populations (De Palo et al. 2007; Hölldobler & Wilson, 2008) and ecosystems (Braakman et al. 2017). The rest of this review will, however, be restricted to the level of histogenesis.

Identifying adaptive self-organization

There are two broad approaches for identifying instances of adaptive self-organization, one directly experimental and the other theoretical. The practical one typically begins with observation of a developmental phenomenon that seems to show variation and adaptation either naturally or in an experimental system. These experimental systems can be very simple. To take one example, many organ rudiments (e.g. lung, salivary gland, mammary gland, prostate, kidney) can be removed from a mouse embryo and cultured on a filter at a gas-medium interface (Trowell, 1954; Jainchill et al. 1964). Such cultures grow very flat compared with the natural organs, typically only a few tens of microns
thick, yet their internal tissues form in a way usually
described as ‘organotypic’: epithelial trees are still tree-like
and mesenchymal tissue surrounds them in a way that
reflects its organization in vivo. The ability of tissues that
should form very three-dimensional organs to form flat but
‘realistic’ versions of their normal selves is a promising indi-
cation that a process of adaptive self-organization is at
work. The ability of a tissue to mitigate the effects of a per-
turbation such as cut-and-paste removal and grafting of its
components is another indication (Fig. 1).

Given that epithelial trees in organs show evidence of
self-organization, questions arise about how the system
organizes itself so that some cells initiate new branches
and others do not, and so that branches spread out rather
than tangle. An indication that even cells that are not ini-
tiating branches can do so can be gained by removing the
branches from a ‘stalk’, for example the presumptive
ureter of a mouse ureter-collecting duct tree, placing the
stalk in appropriate mesenchyme and observing that it
now initiates branching (Sweeney et al. 2008). It can also
be gained from the observation that epithelial cysts in
Matrigel, even clonal ones made from mouse cell lines,
will produce branching trees, some cells being branch
leaders and others remaining behind although all began
exactly the same (Montesano et al. 1991; Tai et al. 2013).
To find out why cells that can branch might nevertheless
refrain from doing so, Nelson et al. (2006) cultured popu-
lations of mouse mammary epithelial cells in shaped wells
in gelled matrix, and used matrix invasion as a proxy for
branching. They found that cells at the extremities of long
rectangular wells would be invasive but those towards the
middle of the rectangle would not. This invasive beha-


![Diagram](image.png)

**Fig. 1** Practical approaches to seek evidence for adaptive self-organization. Simple manipulations, such as constraining the physical shape of a tis-


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suggested a model in which cells secrete a substance,
probably TGFβ, which inhibits invasion. In an epithelial
tree, such a system would ensure that, once a branch has
started to form, cells at its tip would be running away
from the inhibitor secreted by the tree so would remain
highly invasive while those left behind near the branch
site would experience an even higher concentration of
inhibitor, as it accumulates in ‘bays’ nearly surrounded by
cells secreting it. These cells will remain non-invasive
(Fig. 2a).

While the Nelson hypothesis described above is powerful,

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signalling. Given that BMP7 and its receptor are both made by branches, these observations have suggested a model in which the tree self-organizes by each branch growing in the direction of least BMP7, and therefore avoids growing backwards towards itself or growing towards other branches that are secreting their own BMP7 (Fig. 2b; Davies et al. 2014). In (b), the depth of grey indicates calculated concentrations of BMP7.

In the kidney, the tips of growing branches are surrounded by a population of mesenchymal stem cells, the ‘cap mesenchyme’ (Schreiner, 1902; Reinhoff, 1922). At least in mouse, this population depends on BMP7 and FGF9 signalling from the tip for its continued maintenance (Barak et al. 2012; Muthukrishnan et al. 2015) and, when a tip divides and its daughters become separated by new stalk, only the cap cells that surround the diverging tips retain the cap phenotype and the space between them becomes occupied by a newly sprouting blood vessel (Munro, 2017). Caps do not divide in this way when they are induced chemically in pure mesenchyme (Davies & Garrod, 1995; Kuure et al. 2007). The vessels seem to find themselves there by growing up the stalks of the developing tree (Munro, 2017). These two facts illustrate something else common in self-organizing systems: one tissue type, in this case ureteric bud, may be a primary organizer of space, while other entities such as the cap and the blood vessels take their cues from it.

The kidneys (and other organs) show many other examples of self-organization in their development, including the control of stem cell replacement vs. differentiation, the polarization of epithelia, the organization of blood vessels to serve tissues that secrete chemoattractants such as VEGF, etc. In general, these have been identified by a combination of perturbing the system to show adaptation, identifying ligand-receptor pairs that might mediate organization, and perturbing their expression pattern to show the expected effect on patterning of the organ. These experimental steps may proceed in a different order, possible signalling molecules being identified first, for example, but the net effect on understanding is the same.

In addition to experimental approaches, a theoretical method for detecting self-organization has been suggested. The topologies of systems that are known to arise by bottom-up self-organization rather than top-down control are characterized by power-laws. Examples include the Internet, the air transport network, the meanderings of a river and the forking of lightning (reviewed by Turcotte & Rundle, 2002). Many biological systems that are assumed to have arisen by bottom-up, evolutionary processes rather than centralized control, such as protein networks and metabolic networks, also show power-law topologies (e.g. a log plot of the number of proteins that interact with a particular protein, vs. the number of proteins with that number of...
interactions, plots as a descending straight line). Several authors have therefore suggested that self-organization in development might be identified by seeking power-law topologies (Kurakin, 2005; Tiraihi et al. 2011). Some features of systems known, through experiment, to self-organize do show power-law behaviour: imaging the anatomy of a branching epithelial or vascular tree using voxels of a range of dimensions, assessing the fraction of voxels containing at least some of the tree in each case, and log-plotting the occupancy vs. voxel size yields a power-law line, at least until the voxels become smaller than the smallest tubules (see Fig. 3 for an illustration of this method).

There are, however, problems with the approach. The idea that, if something shows a power-law, top-down control must be rejected, is unsound. Many structures produced entirely predictably by very precise top-down mechanisms can also follow power-laws. An example is Cantor dust: to produce this, draw a line 1 m long, erase the middle third, now erase the middle third from the two lines you have left, and so on ad infinitum: a log plot of the length of line vs. the number of lines at that length yields a power-law. There is nothing self-organizing about the generation of Cantor dust – it is done by an external agent following precise rules to the letter: this fact alone should caution against assuming that power-law structures must arise by self-organization. Also, the association between power-laws and self-organization in biological systems often has circular character: we do not actually know how protein and metabolic networks with their power-laws evolved, we just assume that they used only bottom-up processes and so use this association to bolster the power-law-implies-bottom-up relationship. Finally, and practically, it is difficult to know what to measure in an embryo to get the data that can be tested for a power-law, without falling into the trap of data-dredging until a straight line is found. This approach to identifying self-organization should therefore be used only with great caution.

Putting self-organization to practical use

One of the ways in which basic anatomical and embryological knowledge can be used for practical purposes is in

Fig. 3 A theoretical approach to seek evidence for self-organization, by seeking fractal geometry, which is alleged to be associated with self-organizing systems (but see main text for cautionary notes). The subject of this illustration is a lightning bolt, shown black-on-white for clarity, and analysed in two dimensions. The object is viewed under grids of increasing resolution, and in each case the number of squares containing any part of the subject is counted. A graph is then plotted of the log of the number of squares occupied vs. the log of the proportion of the grid occupied by a single square. Fractal structures yield a straight descending line (the gradient of which is related to the fractal dimension): this graph was generated from the image shown. Exactly the same idea can be applied to 3D data (with cubes rather than squares).
guiding tissue engineering, the attempt to turn progenitor cells into functional tissues. Most current approaches to tissue engineering involve the engineer placing cells where they are needed for the final structure, either by making a hydrogel scaffold and seeding it with cells (Hockaday et al. 2012) or by bio-printing suspended cells into a defined 3D shape (Nishiyama et al. 2009; Möller et al. 2017). These approaches have proved effective for tissues such as cartilage that involve only a few cell types, that are relatively homogenous and that are matrix-rich. Tissues such as kidney, which contain dozens of cell types that must be in a very precise arrangement pose more of a problem, especially when it is borne in mind that small faults in the physical relationships of their cells, for example the failure of podocyte foot process interdigitation, can be the reason that someone’s kidneys fail in the first place (reviewed by Ranganathan, 2016). At least with current technologies, 3D printing of a kidney is quite impractical. Can self-organization provide a more effective alternative?

This question has been explored by obtaining renogenic stem cells by disaggregating the presumptive kidney region of E11.5 mouse embryos, re-aggregating them by centrifugation, and assessing their ability to re-organize in culture (Unbekandt & Davies, 2010). Provided they were protected from apoptosis by the inclusion of a Rho kinase (ROCK) inhibitor for the first 24 h of culture, the random mix of cells underwent a phase transition: the epithelial (ureteric bud) cells coalesced to form clumps that polarized into cysts then elongated into branching tubules, while the mesenchymal cells near these tubules underwent mesenchymal-to-epithelial transition to form nephrons in a manner similar to that seen in vivo. This morphogenesis was accompanied by cell differentiation, with markers of each tubular segment being detectable by immunostaining and reverse transcription-polymerase chain reaction. Functional tests of active proximal tubule organic anion and cation transport were positive, with both transporter expression and drug sensitivity data confirming that the normal channels were being used (Lawrence et al. 2015). Furthermore, transplantation of these rudiments into immune-deficient rat recipients resulted in their being vascularized and forming glomeruli capable of passing traces of fluorescent albumen from the blood into the urinary space, from which it was then recovered by proximal tubule cells (Xinaris et al. 2012).

**Limits to the self-organization approach: the need for induced symmetry-breaking**

The renal organoids described above contain appropriate cell types, and they have normal micro-scale anatomy in the sense of having tubular, segmented nephrons connected to collecting duct tubules. A high-magnification image of one might well be mistaken for a foetal kidney, but a low-power could not, because the larger scale structure of a normal kidney is entirely missing and the organoid is symmetrical (in the sense of being the same everywhere with no special places or directions: Fig. 4a). There is no proper cortex-medulla division, nephrons are not orientsed with respect to any axis, there are no loops of Henle and the collecting duct system appears as a series of scattered tubules and treelets instead of one connected tree ramifying from a ureter ‘trunk’. This latter point is the most critical, because normal renal anatomy is organized primarily by the development of the ureteric bud/collection duct tree. In an embryo, the ureteric bud enters the kidney-forming area (metanephrogenic mesenchyme) from the outside as one single tube entering at one place, breaking the symmetry of the system. Can the limited success of self-organization in the organoid be explained by its being too symmetrical?

This idea was addressed by Geneva et al. (2011), who designed a serial-reaggregation experiment. The first aggregation proceeded exactly as in the Unbekandt system described above. The second took one ureteric bud/collection duct tubule from the first aggregation and combined it with mesenchymal stem cells from the renogenic area of a second embryo, but not with any more ureteric bud cells. In this second aggregate, the ureteric bud/collection duct system grew and a single, coherent tree, with nephrons aligning to it properly (Fig. 4b). In the best culture system developed so far (Chang & Davies, 2012), the rudiments developed distinct medullary and cortical zones, and loops of Henle were seen to extend from the cortex to the medulla and back, as they should.

This engineered kidney was much more realistic than the simple organoid, but the collecting duct tree, while coherent, was symmetrical with no unique ureter to lead urine away. In normal development, the ureteric bud crosses a zone of peri-Wolffian mesenchyme on its way from its point of emergence from the Wolffian duct to its invasion of the metanephrogenic mesenchyme in which it ramifies to make the collecting duct. The part of the bud that remains in the peri-Wolffian mesenchyme becomes the ureter, perhaps because of the different signalling environment of this mesenchyme. This raised the possibility that the ureteric bud in the serial-reaggregates produced a collecting duct tree that lacked a ureter because the in vivo asymmetry of the system, with one zone of the ureteric bud in peri-Wolffian mesenchyme, was missing. To test this idea, we have recently transplanted a piece of peri-Wolffian mesenchyme next to just one tubule of the growing tree in a serial re-aggregate, and showed that this tubule ceases to branch and instead expresses the ureter marker, uroplakin (unpublished data presented in the 2016 Anatomical Society December meeting). The symmetry-breaking conversion of one tubule of the tree into a ureter-like uroplakin-positive, unbranched tube can also be driven by local application of a bead.
soaked in a defined growth factor normally produced by that mesenchyme. This example illustrates a general approach for improving the performance of organoid production by self-organizing systems. Self-organization is powerful but, in the absence of symmetry-breaking influences that are present in normal development, it is unlikely to produce correct large-scale anatomy. Judicious, local application of symmetry-breaking signals (e.g. the bead above) or techniques (e.g. the use of serial reaggregation to force the system to begin with a single epithelium) may be used to add critical missing information to a self-organizing system and transform its output from being a mere organoid to being a mini-organ. The general idea should be equally applicable to other types of organoid.

Lessons for synthetic biology

The systems discussed so far in this article are the products of natural evolution, operating either in their normal developmental context or in artificial organoids. They are beginning to be joined by synthetic biological systems engineered to perform developmental tasks such as patterning, differentiation and morphogenesis using genetic modules that have been designed rather than evolved. Ideas for this were set out by a range of authors (Sia et al. 2007; Teague et al. 2016) a few years ago in a range of journals (including this one; Davies, 2008) and some systems have now become a reality, many in prokaryotes but some in mammalian systems as well (see Davies, 2017 for a recent review).
Commentators such as Bozorgmehr (2014) have pointed out that the most interesting and effective approaches to synthetic development would be those that produce cell behaviours leading to self-organization and the emergence of coherent large-scale structures. Some progress has been made in this direction by constructing a patterning system in which randomly mixed cells organize themselves into patches somewhat reminiscent of animal coat markings (Cachat et al. 2016). The system makes use of adhesions-mediated phase separation. Many decades ago, Steinberg aggregated together cells of different types and showed that they would sort out, apparently with the most adhesive inside and the least adhesive outside (Steinberg, 1963); more recently he used cells engineered to express different levels of the same cadherin to show that this sorting really was predictable on the grounds of adhesion alone (Foty & Steinberg, 2005). Steinberg’s systems used small numbers of cells with much freedom to move, and the phase separation could easily run to completion as it does, for example, in a beaker containing oil and water. We reasoned that, in a more constrained system, phase separation would tend to be trapped in local energy minima in which cells separate somewhat to form patches but these patches cannot easily coalesce without cells invading patches of the other cell type, which would increase the contact area between different cell types and be energetically unfavourable. The rich patterns caused by constrained phase separation of oil and water in a very shallow puddle are examples of this effect. Engineering non-adhesive cells to express either E- or P-cadherin on command, making a random mix of those cells, and then inducing cadherin expression, resulted in the formation of patches or spots (depending on the ratios of the E- and P-cadherin expressing cells; Cachat et al. 2016).

Patterning is only the first stage: what needs to be done now is to couple patterning to the subsequent activation of distinct morphogenetic behaviours in the different patches/lines/spots of cells so that, as in natural development, patterning is the prelude to the creation of physical structure. Possible simple morphogenetic effectors, for first proof-of-concept experiments, might be apoptosis of one type of cell (e.g. those in patches, to leave a net) or apical constriction to deform a cell sheet into a corrugated structure.

Feedback of a different kind: implications for basic research

So far in this article, the limitations of self-organization have been considered only negatively, as a problem for tissue engineers wanting to use self-organization to make organoids. Examples were given of how large-scale features were missing from self-organized organoids because a critical symmetry-breaking influence, present in natural embryonic development, was missing and had to be replaced by artificial manipulation. These limitations can be very helpful, however, in the context of basic research, for each failure of realism in a self-organizing organoid points to the necessity of a feature of natural embryogenesis that would normally provide information. Comparison of development in embryonic organ rudiments and organoids can lead an experimenter to rapid identification of the influences that normally shape organ-scale anatomy. Finding these will increase our understanding of normal development and, perhaps, identify very specific regulators of organ-scale anatomy for which small evolutionary change might have a major effect on resulting morphology.

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