THE CRITICAL EXPONENT, THE HAUSDORFF DIMENSION OF THE LIMIT SET AND THE CONVEX CORE ENTROPY OF A KLEINIAN GROUP

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Abstract. In this paper we study the relationship between three numerical invariants associated to a Kleinian group, namely the critical exponent, the Hausdorff dimension of the limit set and the convex core entropy, which coincides with the upper box-counting dimension of the limit set. The Hausdorff dimension of the limit set is naturally bounded below by the critical exponent and above by the convex core entropy. We investigate when these inequalities become strict and when they are equalities.

1. Introduction and statement of results

In this paper we study the relationship between three numerical invariants associated to a Kleinian group, namely the critical exponent, the Hausdorff dimension of the limit set and the convex core entropy, which is shown here to coincide with the upper box-counting dimension, also referred to as upper Minkowski dimension, of the limit set. While the relationship between the first two has already been addressed in various ways, the convex core entropy of a Kleinian group is the new element in the picture. The convex core entropy \( h_c(\Lambda(G)) \) of a Kleinian group \( G \) acting on the unit ball \( \mathbb{B}^{n+1} \) is computed in a similar way to the volume entropy of the hyperbolic manifold given by \( G \), with the essential difference that one restricts the universal cover of the manifold, in this case simply hyperbolic space, to the \( \varepsilon \)-neighbourhood of the convex hull \( H(\Lambda(G)) \) of the limit set \( \Lambda(G) \) of \( G \). The name convex core entropy is owed to the fact that the lift of the convex core of a hyperbolic manifold to the universal cover is precisely the convex hull of the limit set of the underlying Kleinian group. The convex core entropy can also be written as the critical exponent \( \Delta(X) \) of an ‘extended Poincaré series’, given in terms of a uniformly distributed set \( X \) within \( H(\Lambda(G)) \). In this section we shall denote the above invariants simply by \( \delta, \dim_H, h_c \) and \( \dim_B \), respectively, when it is clear from the context what Kleinian group they are associated with. Also, \( \dim_B \) will refer to the box-counting dimension when it exists. The most general relationship between them, formulated as Theorem 3.5 in the main text, is the following.

Theorem 1. For any non-elementary Kleinian group we have

\[ \delta \leq \dim_H \leq h_c = \dim_B. \]

Here, only the last equality is new, while the middle inequality \( \dim_H \leq \dim_B \) is true in general and the first inequality is well-known as a consequence of Bishop and Jones [11]. Thus, the Hausdorff dimension of the limit set is naturally bounded.

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below and above by the critical exponent and the convex core entropy, respectively. The main goal of this paper is to investigate for what classes of Kleinian groups the above inequalities become strict and when they are equalities. For instance, in the case of non-elementary geometrically finite Kleinian groups, it is well-known that \( \delta = \dim_H \), and also that \( \dim_H = \dim_B \) (see Stratmann and Urbański [55]), thus making all four invariants coincide (Proposition 3.8). Moreover, when a Kleinian group is acting on the 3-dimensional hyperbolic space \( \mathbb{H}^3 \), Bishop [9, 10] has shown \( \delta = \dim_B \) if it is non-elementary and analytically finite and if its limit set has null 2-dimensional measure (see also [11]). The arguments in [10] use the so-called Whitney exponent of a closed set in the plane (see also [8] and [58]), which is related in spirit to our convex core entropy but is defined in the boundary of hyperbolic space, as opposed to the interior (see also our remark after Theorem 3.5). Taking the recent solution of the Ahlfors measure conjecture (which follows from the Tameness Conjecture proven in [1] and [16]) into consideration, the above results imply that all finitely generated non-elementary Kleinian groups acting on \( \mathbb{H}^3 \) satisfy \( \delta = \dim_B \).

We shall state partial results on characterising the occurrence of strict inequalities or equalities between the invariants from Theorem 1, and will also produce interesting classes of examples to further motivate conjectures emerging from such partial results.

The following result, formulated as Theorem 3.7, is the first natural observation on \( h_c \), and is reminiscent of the well-known fact that \( \delta \geq n/2 \) when the group contains a parabolic element of maximal rank \( n \).

**Theorem 2.** For any Kleinian group with the property that the convex hull of its limit set contains some horoball, we have \( h_c \geq n/2 \).

Another question that arises in connection with \( h_c \) is under what circumstances we have \( h_c < n \). Recall that the classical volume entropy of any \((n+1)\)-dimensional hyperbolic manifold is equal to \( n \), and thus \( h_c = n \) for any Kleinian group of the first kind (i.e. with the limit set being everything). This can also be seen by the equality in Theorem 1. We consider non-elementary Kleinian groups with the property that any point within the convex hull of their limit set is a bounded distance \( \ell \geq 0 \) away from the boundary of the convex hull; we call this property \( \ell \)-tight. Notice that the tightness condition also implies that the group is of the second kind (i.e. not of the first kind). It is satisfied for instance by any convex cocompact group of the second kind and any non-trivial normal subgroup thereof. Actually the tightness property can be relaxed in such a way that the resulting property is even true for any geometrically finite group of the second kind. We call such Kleinian groups geometrically tight. It has been shown in [38] that for geometrically tight groups the strict inequality \( \dim_H < n \) holds. Here, we show in Theorems 3.11 and 3.12 that the same holds for \( h_c = \dim_H \). Note that tightness implies porosity of the limit set, and hence it is natural to have some relation to \( \dim_B \).

**Theorem 3.** There is a constant \( s(n, \ell) < n \) depending only on \( n \) and \( \ell \) such that any Kleinian group with \( \ell \)-tight convex core satisfies \( h_c < s(n, \ell) \).

Next we investigate the question when \( \delta < \dim_H \). This question is particularly interesting, since it asks for what hyperbolic manifolds the recurrent dynamics within the convex core is smaller dimension-wise than the total dynamics. The interpretation of \( \delta \) as the dimension of recurrent dynamics is due to Bishop and Jones [11] who have shown that for all non-elementary Kleinian groups, \( \delta \) coincides
with the Hausdorff dimension of the conical limit set. Brooks has shown that for any convex cocompact Kleinian group satisfying $\delta > n/2$ and any of its non-trivial normal subgroups, the bottoms of the $L^2$-spectra coincide if and only if the quotient is amenable. Using this and the well-known correspondence between $\delta$ and the bottom of the $L^2$-spectrum, we can formulate the following result, stated as Theorem 4.4 in the text. In fact, a new proof of Brooks’ result by Stadlbauer shows that the assumption $\delta > n/2$ can be dropped.

**Theorem 4.** Let $G$ be a convex cocompact Kleinian group and $N$ some non-trivial normal subgroup. Then, $\delta(N) < h_c(\Lambda(N)) = \dim_H(\Lambda(N))$ precisely when $G/N$ is non-amenable.

In the context of our work, this constitutes a first instance where $\delta < \dim_H = h_c$. However, examples of Kleinian groups with $\delta < \dim_H$ were first given by Patterson (see also [24] for further discussion and references). Theorem 4 can be applied to a class of examples, also discussed in [24], where $G$ is a Schottky group and $N$ is a normal subgroup of $G$ so that $G/N$ is isomorphic to a Schottky subgroup $G_1$ of $G$ and to the isometry group of the manifold given by $N$. Therefore, assuming $G_1$ to be non-elementary and thus non-amenable ensures the existence of a dimension gap of the type $\delta < \dim_H = h_c$ for $N$. Since the non-amenability of $G_1$, that is, of its Cayley graph (which can be embedded in the convex core of the manifold associated to $N$ by taking suitable edge lengths) is essential in producing the dimension gap, it is natural to attempt a generalisation of Theorem 4 along the following lines (Conjecture 5.10). The main idea is that $N$ is not assumed to be a normal subgroup of some group $G$, so that the non-amenability condition is imposed on a discrete structure given by the pants decomposition of the hyperbolic surface given by $N$. This also means that, for this problem, we restrict our attention to the two-dimensional case. Formulating a similar conjecture in higher dimensions depends on finding a notion of manifold decomposition which is in some way analogous to the pants decomposition of a hyperbolic surface.

**Conjecture 1.** Let $S$ be a hyperbolic surface given by some Fuchsian group. Assume $S$ is of infinite type with strongly bounded geometry, and let $\mathcal{G}$ be the graph associated to some uniform pants decomposition of $S$. Then, $\delta < h_c$ if and only if $\mathcal{G}$ is non-amenable.

As usual, a pair of pants is a complete hyperbolic surface with geodesic boundary whose interior is homeomorphic to the complement of three points in the 2-sphere. A hyperbolic surface has strongly bounded geometry if it admits a pants decomposition such that the lengths of the decomposing closed geodesics are uniformly bounded away from 0 and $\infty$. Such a pants decomposition is called uniform. The graph $\mathcal{G}$ associated to a pants decomposition is defined naturally by letting the pants be vertices and connecting two vertices by an edge whenever the involved pants are adjacent. Due to the method of proof that we use, involving Cheeger constants of surfaces and isoperimetric constants of graphs, we can only partially address Conjecture 1 obtaining the following results stated as Theorem 5.1 and Theorem 5.2 further down. The assumptions are the same as in Conjecture 1.

**Theorem 5.** If $\mathcal{G}$ is uniformly strongly amenable, then all $\delta$, $\dim_H$ and $h_c$ are either equal to 1 or less than 1 at the same time.

**Theorem 6.** If $\mathcal{G}$ is non-amenable, then $\delta < 1$. 

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Uniform strong amenability is a stronger notion of amenability for graphs which coincides with the usual amenability for Cayley graphs of finitely generated groups (see Section 4 for more details). As a consequence of these two theorems, we obtain a partial answer to the problem posed in Conjecture 1. Under the assumptions of Conjecture 1 if $G'$ is homogeneous and $h_c = 1$, then $\delta < h_c = 1$ precisely when $G'$ is non-amenable. Here, a graph is called homogeneous if its automorphism group acts transitively. For homogeneous graphs all notions of amenability considered in Section 4 coincide, and again, Cayley graphs of finitely generated groups are homogeneous.

We provide further evidence for the validity of Conjecture 1 in the form of special classes of examples for which the statement of the conjecture holds. In Section 6 we provide examples of hyperbolic surfaces for which $\delta < h_c = 1$ and even $\delta < h_c < 1$. The fundamental piece of our construction is a pair of pants whose geodesic boundaries have sufficiently large length $\ell$, and suitably pasting copies of this one piece together makes tree-like hyperbolic surfaces. Then, as $\ell \to \infty$, the bottom of $L^2$-spectra of the surfaces tends to the maximum possible value, which implies that $\delta \to 1/2$, whereas the number of pairs of pants within distance $R$ of some base point remains bounded from below by $a^R$ for some universal constant $a$ larger than $1/2$. The last condition implies that $h_c \geq a$, and thus we get the difference between $\delta$ and $h_c$.

In order to attack Conjecture 1 in its full generality we expect that further developments of Kesten’s work [34] on random walks on graphs (see also [60]), as employed by Stadlbauer [53] to produce an alternative proof of Brooks’ theorem, will be more instrumental than attempting to modify Brooks’ initial approach. Progress in this direction has also been made in [30], where group-extended Markov systems are considered.

The last part of this paper is concerned with the question when $\dim H = h_c$. In light of the last equality of Theorem 1 this of course translates to the question when $\dim H = \dim B$, and thus $\dim H = \dim B$, since the first equality trivially implies the existence of the box-counting dimension. This question has already been addressed both in the general fractal geometric context and specifically for Kleinian groups. It is well-known that the two dimensions coincide for self-similar sets (see e.g. [23] or [41] for details). Often, equality holds when some degree of homogeneity of the considered set is ensured, or when it supports a sufficiently regular measure, in the sense that the measure of small balls is comparable to the radius raised to a certain power, which turns out to be the common value of the two dimensions (see [51], [61] and [41, Theorem 5.7]). For a sufficient condition for equality without control on the actual value of the dimension, see e.g. [22]. Another large class of examples is that of self-affine sets, for which the dimensions can differ [42], [36], [27], [32], [33], but coincide in a certain ‘generic’ sense [21], [7]. The situation for limit sets of Kleinian groups we have already briefly discussed after Theorem 1.

Here, however, we prefer the novel approach via the convex core entropy $h_c$ as it allows formulating a sufficient condition for the above equality within hyperbolic space, as opposed to the limit set itself. We introduce the bounded type condition for a uniformly distributed set $X$, stating that all cardinalities of intersections of $X$ with balls centred at points in $X$ are comparable, independently of centre and radius. As a weaker version of this condition, we also introduce the weakly bounded type condition by ignoring points of $X$ contained in a family of disjoint horoballs. Then
we develop a Patterson-Sullivan theory for uniformly distributed sets in convex hulls of closed sets in the boundary of hyperbolic space. This also includes a shadow lemma stated as Theorem 7.7 in the main text. These considerations enable us to prove the following result appearing as Theorem 7.8 later on.

**Theorem 7.** Let $\Lambda$ be a closed subset of $S^n$ and assume there is a uniformly distributed set $X$ of bounded type in the convex hull $H(\Lambda)$. Then the $\Delta(X)$-dimensional Hausdorff measure of $\Lambda$ is positive. In particular, $\dim_{H}(\Lambda) = h_{c}(\Lambda) = \dim_{B}(\Lambda)$.

Theorem 7 implies that any Kleinian group of bounded type, that is, with the property that the convex hull of its limit set admits a uniformly distributed set of bounded type, satisfies $\dim_{H}(\Lambda) = h_{c}(\Lambda) = \dim_{B}(\Lambda)$. As a consequence of Theorem 7 (see Corollary 7.9) we obtain that the Poincaré series $P^{s}(X, o) = \sum_{x \in X} e^{-sd(x, o)}$ for a uniformly distributed set $X$ of bounded type is also of divergence type, meaning that $P^{s}(X, o)$ diverges at the critical exponent $s = \Delta(X)$. This raises the natural question whether the divergence type of the Poincaré series for $X$ already implies $\dim_{H}(\Lambda) = h_{c}(\Lambda) = \dim_{B}(\Lambda)$. Note, the divergence type property of a uniformly distributed set $X$ in the convex hull of the limit set of some Kleinian group $G$ is not to be confused with the divergence type property of $G$ itself.

If the bounded type condition is relaxed to a weak version (Definition 7.10), then we show in Theorem 7.11 that the convex core entropy of the given closed set $\Lambda$ coincides with its packing dimension $\dim_{P}(\Lambda)$. In particular, any Kleinian group all of whose parabolic fixed points are bounded, and whose limit set gives a uniformly distributed set of weakly bounded type in its convex hull, satisfies the assumptions of Theorem 7.11 (see Corollary 7.12). Geometrically finite groups clearly fall into this category.

At this point it is perhaps useful to remark that Theorem 7 could also be obtained using ideas inspired by the way Bishop and Jones [11] showed that for non-elementary Kleinian groups $\delta$ equals the Hausdorff dimension of the conical limit set, perhaps with the additional subtlety that the group structure, which is essential in their argument, must be replaced with our bounded type condition or similar. However, we preferred the approach via the Patterson-Sullivan theory of uniformly distributed sets, as it constitutes a useful tool for further developments.

Finally, Section 8 is devoted to the bounded type condition which, as seen above, implies $\dim_{H} = h_{c} = \dim_{B}$ for Kleinian groups. The condition holds for groups of the first kind and for convex cocompact groups, but not for geometrically finite groups with parabolic elements. The weakly bounded type condition can be used for including these groups. We also observe that it is inherited to normal subgroups and that it is invariant under rough isometries. We propose the problem of asking whether it is even invariant under quasi-isometries. It is, however, possible to construct examples of groups of bounded type which are not contained in any of the above categories. This construction uses the work of Eskin, Fisher and Whyte [20] on the Diestel-Leader graph; there is a locally finite graph whose automorphism group acts transitively but which is not quasi-isometric to any Cayley graph of a finitely generated group. In fact, we expect a large class of geometrically infinite groups to have the (weakly) bounded type property (Conjecture 8.7).

**Conjecture 2.** A geometrically tight Kleinian group of divergence type is of weakly bounded type.
Thus, it may well be that Fuchsian groups with the tightness property form the first class of groups beyond those we could treat here, which will be shown to satisfy Conjecture 1 in its full generality.

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2. Preliminaries

Let \((\mathbb{B}^{n+1}, d)\), \(n \geq 1\), be the unit ball model of \((n+1)\)-dimensional hyperbolic space with the hyperbolic distance \(d\). Thus, the \(n\)-dimensional unit sphere \(S^n\) is the boundary at infinity of hyperbolic space. Let \(\text{vol}(\cdot)\) denote hyperbolic volume and \(A(\cdot)\) hyperbolic area. The hyperbolic metric also allows computing lengths \(\ell(\cdot)\) of curves in the usual way. Kleinian groups are discrete subgroups of the group of orientation preserving isometries of hyperbolic space. The quotient \(M = M_G = \mathbb{B}^{n+1}/G\) of \((n+1)\)-dimensional hyperbolic space through a torsion free Kleinian group, that is, a group without elliptic elements, is an \((n+1)\)-dimensional hyperbolic manifold. For ease of notation, we keep the notation \(d\) for the projected metric on \(M\). If \(n = 1\), then \(M\) is a hyperbolic surface and \(G\) is referred to as a Fuchsian group. If \(G\) is infinitely generated, we call the resulting hyperbolic surface of infinite type.

The limit set \(\Lambda(G)\) of a Kleinian group \(G\) is the set of accumulation points of an arbitrary \(G\)-orbit, and is a closed subset of \(S^n\). If \(\Lambda(G)\) consists of more than two points, then it is uncountable and perfect, and \(G\) is called non-elementary. Now let \(\Lambda\) be some closed subset of \(S^n\). The hyperbolic convex hull of the union of all geodesics both of whose end points are in \(\Lambda\) is called the convex hull of \(\Lambda\), and is denoted by \(H(\Lambda)\). For a positive constant \(\varepsilon > 0\), the \(\varepsilon\)-neighbourhood of \(H(\Lambda)\) is denoted by \(H_\varepsilon(\Lambda)\). When \(\Lambda = \Lambda(G)\) for some Kleinian group \(G\), the group acts discontinuously on the convex hull of \(\Lambda(G)\), and the quotient \(C(M_G) = H(\Lambda(G))/G\) is called the convex core of \(M_G = \mathbb{B}^{n+1}/G\). Equivalently, the convex core is the smallest convex subset of \(M_G\) containing all closed geodesics of \(M_G\). A non-elementary Kleinian group \(G\) is called convex cocompact if the convex core \(C(M_G)\) is compact, and geometrically finite if some \(\varepsilon\)-neighbourhood \(C_\varepsilon(M_G) = H_\varepsilon(\Lambda)/G\) of the convex core has finite hyperbolic volume.

A point \(\xi \in \Lambda(G)\) is a conical limit point of \(G\) if there exists a ball \(B\) in \(\mathbb{B}^{n+1}\) such that for every geodesic ray \(r\) towards \(\xi\) we have \(g(B) \cap r \neq \emptyset\) for infinitely many distinct \(g \in G\). The set of all conical limit points of \(G\) is called the conical limit set and is denoted by \(\Lambda_c(G)\).

A horoball is an \((n+1)\)-dimensional open ball in \(\mathbb{B}^{n+1}\) whose bounding sphere, called horosphere, is tangent to \(S^n\). If \(p\) is the fixed point of some parabolic element of the Kleinian group \(G\), then any horoball at \(p\) is invariant under the stabiliser \(\text{Stab}_G(p)\) of \(p\) in \(G\). Moreover, there is a horoball \(D_p\) at \(p\) so that \(D_p \cap g(D_p) = \emptyset\) for all \(g \in G \setminus \text{Stab}_G(p)\). Clearly, any other horoball contained in \(D_p\) also has this property. The projection of such a horoball \(D_p\) to \(M = \mathbb{B}^{n+1}/G\) is called a cusp neighbourhood. We can always find a cusp neighbourhood of volume one for each \(p\), which is called the canonical cusp neighbourhood. We say that \(p\) is a
bounded parabolic fixed point of $G$ if the intersection of $C(M)$ with $\partial D_p/\text{Stab}_G(p)$ is compact, where $\partial D_p$ denotes the bounding horosphere of $D_p$. A theorem of Beardon and Maskit [36] asserts that $G$ is geometrically finite if and only if its limit set is the disjoint union of $\Lambda_c(G)$ and the (at most countable) set of bounded parabolic fixed points.

For a Kleinian group $G$ and points $x, z \in \mathbb{B}^{n+1}$, the Poincaré series with exponent $s > 0$ is given by

$$P^s(Gx, z) = \sum_{g \in G} e^{-sd(g(x), z)}.$$  

The critical exponent $\delta = \delta(G)$ of $G$ is

$$\delta(G) = \inf \{ s > 0 : P^s(Gx, z) < \infty \} = \limsup_{R \to \infty} \frac{\log \#(B_R(z) \cap G(x))}{R},$$

where $B_R(z)$ is the hyperbolic ball of radius $R$ centred at $z$ and $\#(\cdot)$ denotes the cardinality of a set. By the triangle inequality, $\delta$ does not depend on the choice of $x, z \in \mathbb{B}^{n+1}$. If $G$ is non-elementary, then $0 < \delta \leq n$. Also, Roblin [49] showed that the above upper limit is in fact a limit. $G$ is called of convergence type if $P^s(Gx, z) < \infty$, and of divergence type otherwise.

A family of finite Borel measures $\{\mu_z\}_{z \in \mathbb{B}^{n+1}}$ on $\mathbb{S}^n$ is called $s$-conformal measure for $s > 0$ if $\{\mu_z\}$ are absolutely continuous to each other and, for each $z \in \mathbb{B}^{n+1}$ and $\xi \in \mathbb{S}^n$,

$$\frac{d\mu_z}{d\mu_0}(\xi) = k(z, \xi)^s,$$

where $k(z, \xi) = (1 - |z|^2)/|\xi - z|^2$ is the Poisson kernel and $o$ the origin in $\mathbb{B}^{n+1}$. Recall Patterson’s construction [44], [47] of $\delta$-conformal measures $\{\mu_z\}$ supported on the limit set $\Lambda(G)$ of a Kleinian group $G$, which satisfy $g^*\mu_{g(z)} = \mu_z$ for every $z \in \mathbb{B}^{n+1}$ and for every $g \in G$. This $G$-invariance property can be rephrased as follows: for every $g \in G$ and any measurable $A \subset \mathbb{S}^n$ we have

$$\mu_0(g(A)) = \int_A |g'(\xi)|^s d\mu_0(\xi).$$

Here, $|g'(\xi)|$ is the unique positive number called the linear stretching factor so that $g'(\xi)/|g'(\xi)|$ is orthogonal.

For further fundamentals on Kleinian groups and hyperbolic manifolds we refer the reader for instance to the books [5], [37], [48], [40], [31] and [43].

We assume familiarity with the notion of Hausdorff dimension and packing dimension of a set in $\mathbb{R}^n$. The latter is defined in a similar manner to the Hausdorff dimension, just using packings of disjoint balls centred in the given set instead of coverings of the set (for further details see [23] or [41]). We only recall that the upper box-counting dimension (also referred to as upper Minkowski dimension) of $\Lambda \subset \mathbb{R}^n$ is given by

$$\overline{\dim}_B(\Lambda) = \limsup_{\varepsilon \to 0} \frac{\log N_\varepsilon(\Lambda)}{-\log \varepsilon},$$

where $N_\varepsilon(\Lambda)$ is the smallest number of sets of diameter at most $\varepsilon$ that cover $\Lambda$, or the largest number of disjoint balls of radius $\varepsilon$ with centres in $\Lambda$. If the lower box-counting dimension $\underline{\dim}_B(\Lambda)$ of $\Lambda$, obtained by replacing the limit superior with a limit inferior in the above definition, coincides with $\overline{\dim}_B(\Lambda)$, then the box-counting
dimension (also called Minkowski dimension) of $\Lambda$ exists and is denoted $\dim_B(\Lambda)$ (see e.g. [23] for more details).

The upper box-counting dimension is related to the porosity of a set. We say that a subset $\Lambda \subseteq \mathbb{R}^n$ is $c$-porous if there is a constant $c > 0$ so that for each $x \in \Lambda$ and all $r > 0$ the ball $D_r(x)$ of centre $x$ and radius $r$ contains a point $y$ with the Euclidean distance $d_{\mathbb{R}^n}(y, \Lambda) \geq cr$. If $\Lambda$ is $c$-porous, then

$$\dim_B(\Lambda) \leq n - C_n c^n$$

for some constant $C_n > 0$ depending only on $n$ (see e.g. [35]).

As usual, the limsup set of a countable collection $(A_i)_{i \in \mathbb{N}}$ of sets consists of all points which lie in infinitely many member sets of the given collection:

$$\limsup \{ A_i : i \in \mathbb{N} \} = \{ x : x \in A_i \text{ for infinitely many } i \in \mathbb{N} \}.$$

A homeomorphism $f : X \to X$ of a metric space $(X, d)$ into itself is called a $K$-quasi-isometry if there exist constants $K \geq 1$ and $L \geq 0$ such that

$$\frac{1}{K} d(x, y) - L \leq d(f(x), f(y)) \leq K d(x, y) + L$$

for any $x, y \in X$. A $K$-quasi-isometry is called a rough isometry if $K = 1$.

3. Critical exponent, Hausdorff dimension and convex core entropy

For a compact Riemannian manifold $(X, g)$ the volume entropy is defined as

$$\lim_{R \to \infty} \log \text{vol}_g B_R(z)$$

where $B_R(z)$ is the ball of radius $R$ centred at some $z \in \tilde{X}$, with $\tilde{X}$ the universal cover of $X$, and $\text{vol}_g$ is the volume element induced by the Riemannian metric $g$. It is well-known that in this case the limit exists and is independent of the choice of $z \in \tilde{X}$. Also, it is clear that for any (not necessarily compact) hyperbolic manifold $\mathbb{B}^{n+1}/G$, with $G$ some Kleinian group, the volume entropy just equals $n$. In the context of our work it is, however, more useful to consider the following notion of volume entropy which takes into account the convex hull of the limit set $\Lambda(G)$ of $G$.

**Definition 3.1.** For a closed set $\Lambda$ in $\mathbb{S}^n$, we define the convex core entropy as

$$h_c(\Lambda) = \limsup_{R \to \infty} \frac{\log \text{vol}(B_R(z) \cap H_c(\Lambda))}{R},$$

where $B_R(z)$ is the ball of centre $z$ and radius $R$ in $\mathbb{B}^{n+1}$. For a hyperbolic manifold $M_G = \mathbb{B}^{n+1}/G$, we define the convex core entropy $h_c(M_G)$ to be $h_c(\Lambda(G))$.

The definition is independent of the choice of $z \in \mathbb{B}^{n+1}$ and of a positive constant $\varepsilon > 0$. The latter is seen from Proposition 3.4 below. The simplest reason why we need to take the $\varepsilon$-neighbourhood is that, in the degenerate case such as a Fuchsian group viewed as a Kleinian group, the volume of the convex hull is zero and there is no use considering its entropy. In the other case, by replacing $H_c(\Lambda)$ with $H(\Lambda)$, we can define the ‘exact’ convex core entropy, which is of course not greater than $h_c(\Lambda)$, but a priori we do not know whether they are equal or not. If $H(\Lambda)$ does not have any thin part such as a cusp or an arbitrarily narrow strait, then the two values are the same. From the definition, we also have that

$$0 \leq h_c(\Lambda) \leq h_c(\mathbb{S}^n) = n$$
for every closed set $\Lambda \subset \mathbb{S}^n$.

**Definition 3.2.** We call a discrete set $X = \{x_i\}_{i=1}^\infty$ in the convex hull $H(\Lambda) \subset \mathbb{B}^{n+1}$ **uniformly distributed** if the following two conditions are satisfied:

(i) There exists a constant $M < \infty$ such that, for every point $z \in H(\Lambda)$, there is some $x_i \in X$ such that $d(x_i, z) \leq M$;

(ii) There exists a constant $m > 0$ such that, any distinct points $x_i$ and $x_j$ in $X$ satisfy $d(x_i, x_j) \geq m$.

**Remark.** In any convex hull $H(\Lambda) \subset \mathbb{B}^{n+1}$, we can always choose some uniformly distributed set. For example, consider the orbits of several points under some cocompact Kleinian group acting on $\mathbb{B}^{n+1}$ (or on $\mathbb{B}^k \subset \mathbb{B}^{n+1}$ in the degenerate case) and take the intersection with $H(\Lambda)$. This gives uniformly distributed points in a thick part of $H(\Lambda)$. If we choose sufficiently many orbit points, they are distributed in a large portion of $H(\Lambda)$ and the rest of $H(\Lambda)$ is a thin part of simple structure. Then we can fill in points suitably ‘by hand’ in the thin part to obtain a uniformly distributed set in $H(\Lambda)$. In the upper half-space model $\mathbb{H}^{n+1}$, we may also use the set of dyadic points $\{c_k(m_1, \ldots, m_n)\}$ as in the proof of Theorem 3.5 below instead of the orbit points. We propose the problem of existence of uniformly distributed sets in the more general setting of metric spaces.

For a Kleinian group $G$ acting on $\mathbb{B}^{n+1}$, the critical exponent $\delta(G)$ is defined to be the infimum of all exponents $s > 0$ such that the Poincaré series $\sum_{g \in G} e^{-s d(g(x), z)}$ with $x, z \in \mathbb{B}^{n+1}$ converges. Similarly, we define the critical exponent for a uniformly distributed set as follows.

**Definition 3.3.** For a uniformly distributed set $X$, we define the Poincaré series with exponent $s > 0$ and reference point $z \in \mathbb{B}^{n+1}$ by

$$P^s(X, z) = \sum_{x \in X} e^{-s d(x, z)}.$$ 

The critical exponent for $X$ is

$$\Delta = \Delta(X) = \inf \{s > 0 \mid P^s(X, z) < \infty\}.$$ 

The Poincaré series for $X$ (or more simply $X$ itself) is of **convergence type** if $P^{\Delta}(X, z) < \infty$, and of **divergence type** otherwise.

As in the case of groups (see e.g. [43]), it is not too difficult to see that

$$\Delta(X) = \limsup_{R \to \infty} \frac{\log \#(B_R(z) \cap X)}{R}$$

for any $z \in \mathbb{B}^{n+1}$, where $\#(\cdot)$ denotes the cardinality of a set.

**Remark.** For the orbit $X = Gz$ of a Kleinian group $G$, Roblin [49] proved that the above limit superior is actually the limit. One can ask what condition ensures that this is also the case for our $\Delta(X)$ as well as for the convex core entropy $h_c(\Lambda)$. Later, in Theorem 3.5, we will see that $h_c(\Lambda)$ coincides with the upper box-counting dimension $\dim_b(\Lambda)$. Thus the problem is transferred to asking when $\dim_b(\Lambda)$ is equal to the lower box-counting dimension $\dim_b(\Lambda)$.

**Proposition 3.4.** Given a closed set $\Lambda \subset \mathbb{S}^n$, we have that

$$h_c(\Lambda) = \Delta(X)$$

for any uniformly distributed set $X$ in the convex hull $H(\Lambda)$.
Proof. By the definition of uniformly distributed set, we see that the union of all hyperbolic (closed) balls $B_{M+\varepsilon}(x_i)$ of radius $M+\varepsilon$ centred at $x_i \in X$ covers the $\varepsilon$-neighbourhood $H_c(\Lambda)$ of the convex hull. Hence we have

$$\text{vol}(B_R(z) \cap H_c(\Lambda)) \leq \text{vol}(B_{M+\varepsilon}) \cdot \#(B_R(z) \cap X),$$

where $B_{M+\varepsilon}$ denotes any hyperbolic ball of radius $M+\varepsilon$. This gives the inequality $h_c(\Lambda) \leq \Delta(X)$.

On the other hand, to show the converse inequality, we set $m' = \min\{m/2, \varepsilon\}$ and take the hyperbolic (open) ball $B_{m'}(x_i)$ centred at $x_i \in X$ with radius $m'$. Then $B_m(x_i)$ is contained in $H_c(\Lambda)$ and does not intersect any ball of the same radius centred at some other point in $X$. From this observation, we see that

$$\text{vol}(B_{R+m'}(z) \cap H_c(\Lambda)) \geq \text{vol}(B_{m'} \cdot \#(B_R(z) \cap X),$$

where $B_{m'}$ denotes any hyperbolic ball of radius $m'$. This yields $h_c(\Lambda) \geq \Delta(X)$, and hence $h_c(\Lambda) = \Delta(X)$. \qed

For a convex cocompact Kleinian group $G$, we can take the orbit $G(z)$ of some $z \in H(\Lambda(G))$ as a uniformly distributed set $X$ in the convex hull of the limit set $\Lambda(G)$. In this case, $\Delta(X) = \delta(G)$, and hence $h_c(\Lambda(G)) = \delta(G)$ by the above proposition. We can extend this statement to geometrically finite Kleinian groups as is seen later.

Basic inequalities for our numerical invariants are the following.

**Theorem 3.5.** For any closed set $\Lambda \subset S^n$ we have

$$\dim_H(\Lambda) \leq \dim_B(\Lambda) = h_c(\Lambda).$$

When $\Lambda = \Lambda(G)$ is the limit set of some non-elementary Kleinian group $G$, we have that

$$\delta(G) \leq \dim_H(\Lambda(G)) \leq \dim_B(\Lambda(G)) = h_c(\Lambda(G)).$$

**Proof.** We prove that the convex core entropy $h_c(\Lambda)$ of $\Lambda$ coincides with its upper box-counting dimension $\dim_B(\Lambda)$, thus rendering the first inequality of the theorem trivial (see e.g. [23]). Let $\Lambda (\neq S^n)$ be a closed subset of $S^n$. By using the upper half-space model $\mathbb{H}^{n+1}$ for hyperbolic space, we may assume that $\Lambda$ is a compact subset of $\mathbb{R}^n$. A uniformly distributed set $X$ in the convex hull $H(\Lambda)$ can be given as follows. For each $(m_1, \ldots, m_n) \in \mathbb{Z}^n$ and each $k \in \mathbb{Z}$, we define the following dyadic square of size $2^{-k}$ in $\mathbb{R}^n$ and a cuboid over it in $\mathbb{H}^{n+1}$ together with its 'upper centre':

$$I_k(m_1, \ldots, m_n) = \left[\frac{m_1}{2^k}, \frac{m_1+1}{2^k}\right] \times \cdots \times \left[\frac{m_n}{2^k}, \frac{m_n+1}{2^k}\right] \subset \mathbb{R}^n;$$

$$\tilde{I}_k(m_1, \ldots, m_n) = \left[\frac{m_1}{2^k}, \frac{m_1+1}{2^k}\right] \times \cdots \times \left[\frac{m_n}{2^k}, \frac{m_n+1}{2^k}\right] \times \left[\frac{1}{2^{k+1}}, \frac{1}{2^k}\right] \subset \mathbb{H}^{n+1};$$

$$c_k(m_1, \ldots, m_n) = \left(\frac{m_1+1/2}{2^k}, \ldots, \frac{m_n+1/2}{2^k}\right) \in \mathbb{H}^{n+1}.$$  

If $H(\Lambda) \cap \tilde{I}_k(m_1, \ldots, m_n) \neq \emptyset$, then we choose the nearest point

$$x_k(m_1, \ldots, m_n) \in H(\Lambda) \cap \tilde{I}_k(m_1, \ldots, m_n)$$

to the upper-centre $c_k(m_1, \ldots, m_n)$. Set

$$X = \{x_k(m_1, \ldots, m_n) \mid k \in \mathbb{Z}, (m_1, \ldots, m_n) \in \mathbb{Z}^n\}.$$
We see that $X$ is a uniformly distributed set in $H(\Lambda)$, except for the eventuality that there is a cluster of points $x_k(m_1, \ldots, m_n)$ in a thin part of $H(\Lambda)$ that are very close to each other. If this is the case, we only have to select one such point from each cluster as a member of $X$ and remove the rest in order to make $X$ uniformly distributed.

For a fixed integer $k$, let $N_k(\Lambda)$ be the number of dyadic squares $\{I_k(m_1, \ldots, m_n)\}$ that intersect $\Lambda$. Then the upper box-counting dimension of $\Lambda$ is given by

$$\dim_B(\Lambda) = \limsup_{k \to \infty} \frac{\log N_k(\Lambda)}{k \log 2}$$

(see e.g. [23, Chapter 3]).

The convex core entropy is defined by

$$h_c(\Lambda) = \limsup_{R \to \infty} \frac{\log \text{vol} (B_R(z) \cap H_\epsilon(\Lambda))}{R},$$

where $B_R(z)$ is the ball of centre $z$ and radius $R$ in $\mathbb{H}^{n+1}$. Here we may replace the point $z$ with any compact subset $Z$ of $\mathbb{H}^{n+1}$ to obtain the same quantity. We consider $Z = W \times \{\tau\} \subset \mathbb{H}^{n+1}$, where $W \subset \mathbb{R}^n$ is a sufficiently large closed ball containing $\Lambda$, and $\tau > 0$ is sufficiently large, that is, above the highest $(n+1)$-th coordinate of $H_\epsilon(\Lambda)$. By using the fact that the distance between $Z$ and $W \times \{2^{-k}\}$ is comparable to $k \log 2$, we obtain

$$h_c(\Lambda) = \limsup_{k \to \infty} \frac{\log \text{vol} (\mathbb{R}^n \times [2^{-k}, \infty) \cap H_\epsilon(\Lambda))}{k \log 2}.$$

The latter equality always holds in the case of exponential growth. Also, in general, the limit superior with respect to the continuous variable $R \to \infty$ is greater than or equal to that with respect to the discrete sequence $k \to \infty$, but here they coincide due to this particular property of exponential growth.

Let $N_k(X)$ denote the number of elements of the uniformly distributed set $X$ that are in $\mathbb{R}^n \times [2^{-(k+1)}, 2^{-k}]$. Then, $\text{vol} (\mathbb{R}^n \times [2^{-(k+1)}, 2^{-k}] \cap H_\epsilon(\Lambda))$ is comparable with $N_k(\Lambda)$ and hence

$$h_c(\Lambda) = \limsup_{k \to \infty} \frac{\log N_k(X)}{k \log 2}.$$

Next, we compare $N_k(\Lambda)$ with $N_k(X)$. For every point $x_k(m_1, \ldots, m_n) \in X$, there is some $I_k(m_1', \ldots, m_n')$ intersecting $\Lambda$ with $|m_i - m_i'| \leq 1$ ($i = 1, \ldots, n$). Conversely, for every square $I_k(m_1, \ldots, m_n)$ intersecting $\Lambda$, there is some point $x_k(m_1', \ldots, m_n') \in X$ with $|m_i - m_i'| \leq 1$ ($i = 1, \ldots, n$). This shows that

$$3^{-n}N_k(\Lambda) \leq N_k(X) \leq 3^n N_k(\Lambda),$$

and hence

$$h_c(\Lambda) = \dim_B(\Lambda).$$

Finally, in the case that $\Lambda = \Lambda(G)$ for some non-elementary Kleinian group $G$, the additional inequality stated in the theorem follows from the theorem of Bishop and Jones [11] asserting that $\delta(G) = \dim_H(\Lambda_c(G)).$
Remark. Another exponent of similar flavour related to the upper box-counting dimension has been introduced by Bishop [9]. For any closed set \( \Lambda \subset \mathbb{S}^n \), which we may assume to be contained in \( \mathbb{R}^n \), consider a Whitney decomposition \( \mathcal{Q} \) of the complement \( \mathbb{R}^n \setminus \Lambda \), which consists of dyadic cubes \( \{ Q_i \}_{i \in \mathbb{N}} \) of disjoint interior whose diameters are comparable to the distance to \( \Lambda \). Then the Whitney exponent \( \Delta_{\text{Whit}}(Q) \) is defined to be the critical exponent of the series \( \sum_{i \in \mathbb{N}} \text{diam}(Q_i)^s \), and is independent of the choice of the Whitney decomposition \( \mathcal{Q} \). Then \( \Delta_{\text{Whit}}(Q) \leq \dim_B(\Lambda) \) in general and \( \Delta_{\text{Whit}}(Q) = \dim_B(\Lambda) \) if \( \Lambda \) has null \( n \)-dimensional measure. This is a generalisation of a similar result due to Tricot [58] for the 1-dimensional case.

The volume entropy on a horoball can be considered similarly to the convex core entropy as follows.

**Lemma 3.6.** Let \( D \) be some horoball in \( \mathbb{B}^{n+1} \) and \( B_R(z) \) the ball of radius \( R > 0 \) centred at some \( z \in \mathbb{B}^{n+1} \). Then

\[
\lim_{R \to \infty} \frac{\log \text{vol}(B_R(z) \cap D)}{R} = \frac{n}{2}.
\]

**Proof.** We will show the statement in the upper half-space model

\( \mathbb{H}^{n+1} = \{ (x, y) \mid x \in \mathbb{R}^n, y > 0 \} \)

of hyperbolic space. We may assume that \( D = \{ y \geq 1 \} \) and \( z = (0, 1) \). Then the intersection of \( B_z(R) \) with the boundary \( \partial D = \{ y = 1 \} \) is the ball of Euclidean radius \( \sqrt{2(cosh R - 1)} \). From this, we see that the volume of the \( c \)-neighbourhood of \( \partial D \) in \( B_z(R) \) for some \( c > 0 \) is comparable with \( \exp(nR/2) \), and hence

\[
\liminf_{R \to \infty} \frac{\log \text{vol}(B_R(z) \cap D)}{R} \geq \frac{n}{2}.
\]

On the other hand, \( B_R(z) \cap D \) is contained in a region

\[ E = \{ (x, y) \in \mathbb{H}^{n+1} \mid |x| \leq \sqrt{(\cosh R - 1)/2} (y + 1), 1 \leq y \leq e^R \}, \]

and \( \text{vol}(E) \) is bounded by

\[
\left( \frac{\cosh R - 1}{2} \right)^{\frac{n}{2}} \int_1^{e^R} \frac{(y + 1)^n}{y^{n+1}} dy \leq \exp(nR/2).
\]

This gives

\[
\limsup_{R \to \infty} \frac{\log \text{vol}(B_R(z) \cap D)}{R} \leq \frac{n}{2},
\]

and hence the assertion follows. \( \square \)

**Remark.** The volume of \( B_R(z) \cap D \) is explicitly given by the definite integral

\[
\frac{\pi^{\frac{n}{2}}}{\Gamma(\frac{n}{2} + 1)} \int_1^{e^R} \frac{(-y^2 + 2y \cosh R - 1)^{\frac{n}{2}}}{y^{n+1}} dy.
\]

In the case where \( n = 1 \), this is equal to

\[
2 \cosh R \left( \frac{\pi}{2} - \arctan \sqrt{\frac{\cosh R - 1}{2}} \right) + 2 \sqrt{2(\cosh R - 1)} - 2 \left( \frac{\pi}{2} + \arctan \sqrt{\frac{\cosh R - 1}{2}} \right).
\]
In the general case, this can be represented by using hypergeometric series.

As a direct consequence of Lemma 3.6 we obtain the following.

**Theorem 3.7.** If the convex hull \( H(\Lambda) \) of a closed set \( \Lambda \subset \mathbb{S}^n \) contains a horoball, then \( h_c(\Lambda) \geq n/2 \). In particular, for any Kleinian group \( G \) acting on \( \mathbb{B}^{n+1} \) with the property that the convex hull of its limit set contains a horoball, we have

\[
h_c(\Lambda(G)) \geq \frac{n}{2}.
\]

**Remark.** The above condition on the convex hull is trivially satisfied for non-elementary Kleinian groups \( G \) with parabolic elements of maximal rank \( n \). In that case, it is well-known [4] that the critical exponent \( \delta(G) \) is strictly greater than \( n/2 \), and we recover the statement of Theorem 3.7 since \( h_c(\Lambda(G)) \geq \delta(G) > n/2 \) by Theorem 3.5.

Note that there is a canonical way of putting a uniformly distributed set on a horoball. See Cannon and Cooper [17] for literature. For instance, in the horoball \( D = \{ (x, y) \mid x \in \mathbb{R}^n, y \geq 1 \} \) of the upper half-space model \( \mathbb{H}^{n+1} \) as above, we can define

\[
X_D = \bigcup_{k \in \mathbb{N} \cup \{0\}} ((2^k \mathbb{Z})^n, 2^k)
\]
to be a uniformly distributed set.

Using this uniformly distributed set on a horoball, it is not too difficult to show that for a geometrically finite Kleinian group the convex core entropy coincides with the critical exponent. However, this can be immediately deduced from Theorems 3.5 and 3.6 and Stratmann and Urbaniški’s result [55] that the Hausdorff, packing and box-counting dimensions of the limit set of a geometrically finite Kleinian group are coincident and agree with the critical exponent.

**Proposition 3.8.** For a non-elementary geometrically finite Kleinian group \( G \), we have that

\[
\delta(G) = \dim_H(\Lambda(G)) = \dim_B(\Lambda(G)) = h_c(\Lambda(G)).
\]
$G$ has the limit set of zero area if $\Lambda(G) \neq S^2$ and $\delta(G) = 2$ if $\Lambda(G) = S^2$. In summary, we have the following theorem obtained by piecing together results from [9], [10], [55], [11], [1] and [16].

**Theorem 3.9.** For a non-elementary analytically finite Kleinian group $G$ acting on $\mathbb{H}^3$, we have that

$$\dim_H(\Lambda(G)) = \dim_B(\Lambda(G)) = h_c(\Lambda(G)).$$

In addition, if $G$ is finitely generated or if the 2-dimensional measure of $\Lambda(G)$ is zero, then $\delta(G)$ coincides with these quantities.

Finally, in this section, we introduce a class of convex hulls $H(\Lambda)$ in hyperbolic space $\mathbb{H}^{n+1}$ such that the convex core entropy $h_c(\Lambda)$ is strictly less than $n$.

**Definition 3.10.** We say that a convex hull $H(\Lambda)$ in $\mathbb{H}^{n+1}$ is $\ell$-tight (or just tight in brief) if every point $z \in H(\Lambda)$ is within distance $\ell \geq 0$ from the boundary $\partial H(\Lambda)$. Also $H(\Lambda)$ is weakly $\ell$-tight if there exist mutually disjoint horoballs $\{D_p\}_{p \in \Phi}$ with the set of tangency points $\Phi \subset S^n$ such that every point $z \in H(\Lambda) \setminus \bigcup_{p \in \Phi} D_p$ is within distance $\ell$ from $\partial H(\Lambda)$.

As first natural examples of Kleinian groups with the weak tightness property we have all non-trivial normal subgroups of geometrically finite groups of the second kind. For a Kleinian group $G$ acting on $\mathbb{H}^{n+1}$, generalising an argument of Tukia [59] for geometrically finite groups, it was proven in [38] that, if the convex hull $H(\Lambda(G))$ of the limit set of $G$ is weakly tight, then the Hausdorff dimension $\dim_H(\Lambda(G))$ is strictly less than $n$. In [34], $G$ is called geometrically tight if $H(\Lambda(G))$ is weakly tight. By essentially the same arguments, we can show that the convex core entropy $h_c(\Lambda(G))$ is strictly less than $n$ also in this case. Actually, this fact is independent of group actions and valid in general for an arbitrary convex hull with the tightness property.

**Theorem 3.11.** If a convex hull $H(\Lambda)$ in $\mathbb{H}^{n+1}$ is weakly $\ell$-tight, then

$$h_c(\Lambda) \leq s(n, \ell) < n,$$

where $s(n, \ell)$ is some constant depending only on $n$ and $\ell$. In particular, if a Kleinian group $G$ is geometrically tight, then $h_c(\Lambda(G)) < n$.

**Proof.** By transferring $H(\Lambda)$ and $\Lambda$ to the upper-half plane model $\mathbb{H}^{n+1}$ of hyperbolic space together with its boundary $\mathbb{H}^n \cup \{\infty\}$, we can assume that $\Lambda$ is a bounded subset of $\mathbb{R}^n$. For a Euclidean cube $Q$ in $\mathbb{R}^n$, we denote by $\overline{Q}$ the Euclidean cube in $\mathbb{H}^{n+1}$ having $Q$ as the lower face. Also $d(Q)$ denotes its side length and $x(Q) \in \mathbb{H}^{n+1}$ the centre of the upper face of $Q$.

Assume that $H(\Lambda)$ is weakly $\ell$-tight. It is shown in [38] that we can choose the following family $L_m = \{Q_{m,i}\}_{i \in \mathbb{N}}$ of cubes $Q_m = Q_{m,i}$ for each $m \in \mathbb{N}$. For every fixed $m$, all cubes $Q_{m,i} \in L_m$ have mutually disjoint interior and intersect $\Lambda$. Also the union $\bigcup Q_m$ taken over all $Q_m \in L_m$ covers all of $\Lambda$ except the set $\Phi$ of tangency points of the horoballs $\{D_p\}_{p \in \Phi}$ which appear in the definition of weak tightness for $H(\Lambda)$. Each cube $Q_m \in L_m$ contains smaller cubes $Q_{m+1} \in L_{m+1}$ that satisfy the following properties. Here we denote the family of these cubes $Q_{m+1}$ contained in a given $Q_m$ by $L_{m+1}(Q_m)$.

- For every point $z$ on the boundary $\partial H(\Lambda)$, there is a upper centre $x(Q_m)$ of some $Q_m \in L_m$, $m \in \mathbb{N}$, within a uniformly bounded distance of $z$. 

There exist positive constants \( s = s(n, \ell) < n \) and \( c < 1 \) depending only on \( n \) and \( \ell \) such that
\[
\sum_{Q_{m+1} \in \mathcal{L}_{m+1}(Q_m)} d(Q_{m+1})^s \leq c d(Q_m)^s
\]
for each \( Q_m \in \mathcal{L}_m \) and every \( m \in \mathbb{N} \).

Note that the first property above is not explicitly written down in [38] but it is clear from the construction.

We choose a point \( x_m \in H(\Lambda) \) for each \( Q_m \) that is closest to \( x(Q_m) \). Let \( X' \) be the union of all such points \( x_m \) taken over all \( Q_m \in \mathcal{L}_m \) for all \( m \in \mathbb{N} \). Then \( X' \) is uniformly distributed everywhere in some neighbourhood of \( \partial H(\Lambda) \) apart from the union of \( \{D_p\}_{p \in \mathcal{P}} \). For each horoball \( D = D_p \), we put a canonical set of points \( X_{D'} \) in a uniformly distributed manner into \( D' = D \cap H(\Lambda) \). Then the union of \( X' \) and \( X_{D'} \) for all horoballs defines a uniformly distributed set \( X \) in \( H(\Lambda) \) due to its weak tightness.

In each \( X_{D'} \), we take the nearest point \( x_{D'} \) to a given base point \( o \in \mathbb{H}^{n+1} \). By elementary hyperbolic geometry, we see that there is a constant \( a > 0 \) independent of \( D' \) such that
\[
d(x, o) + a \geq d(x, x_{D'}) + d(x_{D'}, o)
\]
is satisfied for every \( x \in X_{D'} \). This yields
\[
P^s(X_{D'}, o) = \sum_{x \in X_{D'}} e^{-sd(x, o)} \leq \sum_{x \in X_{D'}} e^{-s(d(x, x_{D'}) + d(x_{D'}, o) - a)} = e^{sa} e^{-sd(x_{D'}, o)} P^s(X_{D'}, x_{D'}).
\]
For the sake of simplicity, we may assume that \( X' \) contains each \( x_{D'} \) by enlarging \( X' \). Then we have
\[
P^s(X, o) \leq e^{sa} P^s(X', o) \cdot P^s(X_{D'}, x_{D'}),
\]
where \( D \) can be chosen arbitrarily from \( \{D_p\} \). Using this inequality and Lemma 3.6 we have \( h_c(\Lambda) = \Delta(X) \leq \max\{\Delta(X'), n/2\} \), where \( \Delta(X') \) is the critical exponent defined for \( X' \) instead of \( X \).

In order to estimate \( \Delta(X') \), we use the second property of \( \mathcal{L}_m = \{Q_m\} \) as above. It is well-known that the hyperbolic distance \( d(o, x_m) \) can be estimated by using the Euclidean distance from \( x(Q_m) \) to the boundary \( \mathbb{R}^n \). In particular, there is a uniform constant \( C > 0 \) such that \( e^{-d(o, x_m)} \leq C d(Q_m) \). Then, for \( s = s(n, \ell) \), we have
\[
P^s(X', o) \leq C^n \sum_{m \in \mathbb{N}} \sum_{Q_m \in \mathcal{L}_m} d(Q_m)^s \leq C^n \sum_{m \in \mathbb{N}} c^m < \infty,
\]
which shows that \( \Delta(X') \leq s(n, \ell) < n \).

In the case where \( H(\Lambda) \) is \( \ell \)-tight without negligible horoballs, we can obtain a better estimate of the convex core entropy \( h_c(\Lambda) \) in terms of \( \ell \). This is done by using the coincidence of \( h_c(\Lambda) \) with the upper box-counting dimension \( \overline{\dim}_B(\Lambda) \) and estimating the porosity constant for \( \Lambda \) in terms of \( \ell \). Then the upper estimate of \( \overline{\dim}_B(\Lambda) \) in terms of the porosity constant yields the result. One may think that the above theorem can also be obtained in this way, by using the relation between \( \overline{\dim}_B(\Lambda) \) and the so-called mean porosity introduced in [35], but it seems
that sets $\Lambda$ for which $H(\Lambda)$ is weakly tight are not necessarily mean porous as in the definition, so the known estimate cannot be applied directly.

**Theorem 3.12.** If the convex hull $H(\Lambda) \subset \mathbb{H}^{n+1}$ of a closed set $\Lambda \subset S^n$ is $\ell$-tight, then

$$h_c(\Lambda) = \dim_B(\Lambda) \leq n - C e^{-2n\ell},$$

where $C > 0$ is a constant depending only on $n$.

**Proof.** We again use the upper half-space model $\mathbb{H}^{n+1}$ and assume that $\Lambda$ is a closed set of $\mathbb{R}^n \cup \{\infty\}$ containing $\infty$ and set $\Lambda' = \Lambda - \{\infty\} \subset \mathbb{R}^n$. We will show that, if $H(\Lambda)$ is $\ell$-tight, then $\Lambda'$ is $c$-porous for $c = 2 e^{-2\ell}$. Then by the well-known estimate of the upper box-counting dimension

$$\dim_B(\Lambda') \leq n - C c^n$$

and by Theorem 3.12 we have the required inequality.

Suppose to the contrary that $\Lambda'$ is not $c$-porous for $c = 2 e^{-2\ell}$. Then there are $x \in \Lambda'$ and $r > 0$ such that every point $y$ in the Euclidean ball $D_r(x) \subset \mathbb{R}^n$ satisfies $d_{\mathbb{R}^n}(y, \Lambda') < cr$. It is easy to see that $D_r(x) \times [cr, \infty) \subset \mathbb{H}^{n+1}$ is contained in the convex hull $H(\Lambda)$, and in particular the Euclidean ball $\tilde{D}_r(z) \subset \mathbb{H}^{n+1}$ of centre $z = (x, cr + r)$ is in $H(\Lambda)$. Since the hyperbolic radius of $\tilde{D}_r(z)$ is $\frac{1}{2} \log(1 + 2/c)$, the hyperbolic centre $z_0 \in H(\Lambda)$ of $\tilde{D}_r(z)$ satisfies

$$d(z_0, \partial H(\Lambda)) \geq \frac{1}{2} \log \left(1 + \frac{2}{c}\right) > \frac{1}{2} \log \frac{2}{c} = \ell.$$ 

This implies that $H(\Lambda)$ is not $\ell$-tight, which proves the claim. \qed

4. Amenability of pants decompositions

We define amenability of graphs and then apply this concept to a certain type of decomposition of a hyperbolic surface. A graph $\mathcal{G} = (V, E)$ consists of the set $V$ of vertices and the set $E$ of edges that connect vertices in $V$. A subgraph $K = (V', E')$ of $\mathcal{G}$ is a graph with $V' \subset V$ and $E' \subset E$ such that every edge in $E'$ connects vertices in $V'$. The boundary $\partial K$ of a subgraph $K = (V', E')$ is the subset $V''$ of vertices in $V'$ that are connected to a vertex in $V \setminus V'$ by an edge in $E$.

**Definition 4.1.** A connected graph $\mathcal{G} = (V, E)$ is called amenable if

$$\inf_K \frac{\vert \partial K \vert}{\vert K \vert} = 0,$$

where the infimum is taken over all finite connected subgraphs $K$. Moreover, $\mathcal{G}$ is called strongly amenable if

$$\lim_{m \to \infty} \inf_{K(m)} \frac{\vert \partial K^{(m)} \vert}{\vert K^{(m)} \vert} = 0,$$

where the infimum is taken over all finite connected subgraphs $K^{(m)}$ with $\vert K^{(m)} \vert \leq m$ and $v \in K^{(m)}$ for some fixed vertex $v \in V$. Finally, $\mathcal{G}$ is defined to be uniformly strongly amenable if the above convergence as $m \to \infty$ is uniform independently of the choice of $v \in V$. 
For more details on the notion of amenability see e.g. [13], [62]. For amenability of graphs see e.g. [60] and the appendix in [28]. Note that a graph is assumed to be simple in some cases but our graph defined later can contain a loop edge at a vertex and double edges between two vertices. However, as far as our arguments are concerned, these edges do not cause problems. If necessary, we may add virtual vertices at the middle of all edges to make the graph simple.

Remark. As a direct consequence of the definition, a graph is non-amenable if and only if
\[ \sup_K \frac{|K|}{|\partial K|} < \infty, \]
where the supremum is again taken over all finite connected subgraphs $K$.

We say that a finitely generated group $G$ is (non-) amenable if the Cayley graph of $G$ with respect to some generating set $A$ is (non-) amenable. This definition is independent of the choice of the generating set $A$. Strong amenability and uniformly strong amenability of $G$ are defined in the same way. However, since $G$ is homogeneous in the sense that $G$ acts on the vertices of its Cayley graph transitively, we see that these concepts of amenability are all the same for finitely generated groups.

A normal covering $M_2 \to M_1$ is called amenable if its covering transformation group, which is isomorphic to the quotient group $\pi_1(M_1)/\pi_1(M_2)$, is amenable.

The following theorem is due to Brooks [14]. Here, $\lambda_0$ denotes the bottom of the $L^2$-spectrum of a Riemannian manifold. Note that, for a covering $M_2 \to M_1$, the inequality $\lambda_0(M_1) \leq \lambda_0(M_2)$ is always satisfied.

**Theorem 4.2** (Brooks [14]). Let $M_1$ be a $(n+1)$-dimensional hyperbolic manifold given by a convex cocompact Kleinian group with $\lambda_0(M_1) < n^2/4$, and let $M_2$ be a normal cover of $M_1$. Then the covering $M_2 \to M_1$ is amenable if and only if $\lambda_0(M_2) = \lambda_0(M_1)$.

Recently, Stadlbauer [53] gave a new proof of Brooks’ theorem by developing further ideas of Kesten [34] on random walks on graphs, which allows one to drop the assumption $\lambda_0(M_1) < n^2/4$.

We also have the well-known correspondence between $\lambda_0$ and $\delta$ given by the following theorem.

**Theorem 4.3** (Elstrodt [19], Patterson [44], Sullivan [57]). For any Kleinian group $G$ and $M_G = \mathbb{B}^{n+1}/G$ we have
\[ \lambda_0(M_G) = \begin{cases} \frac{1}{4} n^2, & \text{if } \delta(G) \leq \frac{1}{4} n \\ \delta(G)(n - \delta(G)), & \text{if } \delta(G) \geq \frac{1}{4} n. \end{cases} \]

Note that the less intricate implication in Brooks’ theorem, namely that amenability implies equality of critical exponents, has been recovered and even generalised using different methods by Roblin [50] and Sharp [52]. The above results enable us to prove the following theorem.

**Theorem 4.4.** If $N$ is a non-trivial normal subgroup of a convex cocompact Kleinian group $G$, then
\[ \dim_H(\Lambda(N)) = h_c(\Lambda(N)). \]
Furthermore,

\[ G/N : \text{non-amenable} \iff \delta(N) < \dim_H(\Lambda(N)). \]

**Proof.** We deduce the first statement from \( \Lambda(N) = \Lambda(G) \) and \( \dim_H(\Lambda(G)) = \delta(G) = \Delta(X) \), where \( X \) is chosen to be some \( G \)-orbit in \( H(\Lambda(G)) \), together with Proposition 3.4. The second statement follows from Brooks’ theorem (Theorem 4.2), enhanced by Stadlbauer [53]. □

As an illustration of the situation in Theorem 4.4 we give the following class of examples of Kleinian groups whose critical exponent is strictly smaller than the Hausdorff dimension of their limit set (see also [24]).

**Example 4.5.** Let \( G_0 \) and \( G_1 \) be two non-elementary convex cocompact Kleinian groups acting on \( \mathbb{H}^{n+1} \) with (open) fundamental domains \( F_0, F_1 \) respectively, such that \( F_0^c \cap F_1^c = \emptyset \). For simplicity, we assume that \( G_0 \) is freely generated by \( g_1, \ldots, g_k \). With \( G = G_0 \ast G_1 \), let \( \varphi : G \rightarrow G_1 \) denote the canonical group homomorphism, and define \( N := \ker(\varphi) \). Clearly,

\[ N = \langle hg_ih^{-1} : i = 1, \ldots, k, h \in G_1 \rangle, \]

and \( N \) is the normal subgroup of \( G \) generated by \( G_0 \) in \( G \). It follows that \( G/N \) is isomorphic to \( G_1 \). Observe now that \( G/N \) contains a free subgroup on two generators, and therefore \( G/N \) is not amenable. Hence, applying the theorem above, it follows that \( \delta(N) < \dim_H(\Lambda(N)) \).

In what follows, we restrict ourselves to 2-dimensional hyperbolic surfaces and consider the amenability of objects which do not necessarily originate from normal coverings.

**Definition 4.6.** A pair of pants is a complete hyperbolic surface with geodesic boundary whose interior is homeomorphic to the complement of three points in the 2-sphere.

Note that a pair of pants can contain cuspidal regions. Also, a connected hyperbolic surface with geodesic boundary is a pair of pants if and only if all of its simple closed geodesics are boundary components. Thus, pairs of pants are exactly those hyperbolic surfaces with geodesic boundary which cannot be further simplified by cutting along simple closed geodesics.

The following definition contains an existence statement which is formulated and proven in [3] and [29, Theorem 3.6.2].

**Definition 4.7.** Every connected, not simply connected hyperbolic surface \( S \) has a pants decomposition \( \mathcal{P} \) obtained as follows. There exists a family of mutually disjoint simple closed geodesics \( M \) on \( S \) such that if \( \overline{M} \) denotes the closure of \( M \) in \( S \) (viewed as a subset of \( S \)), then the closure of each connected component of \( S \setminus \overline{M} \) is isometric to either

1. a pair of pants (thus the term pants decomposition),
2. a half annulus \( \{ z \in \mathbb{C} : 1 \leq |z| < R \} \) in \( \{ z \in \mathbb{C} : 1/R < |z| < R \} \), for some \( 1 < R < \infty \), endowed with the corresponding hyperbolic metric, or
3. a closed half plane in \( \mathbb{H}^2 \) with the hyperbolic metric.

\( \mathcal{P} \) is the family of all pairs of pants (components of type (1)), which is in the convex core \( C(S) \) of \( S \).
For details on the pants decomposition of a hyperbolic surface we refer the reader for instance to [29, Sections 3.5 and 3.6].

**Remark.** Pants decompositions are not unique as can be easily seen already for the simple example of a compact surface of genus 2.

**Definition 4.8.** For a pants decomposition \( P \) of the hyperbolic surface \( S \), the associated graph \( G = G(P) \) is defined to be the graph whose vertices are given by the pairs of pants in \( P \) and which has edges between pairs of pants whenever these are adjacent via some boundary simple closed geodesic. We endow the graph \( G(P) \) with the usual metric \( d_P \) in which edges have length 1.

**Remark.** A pair of pants can be adjacent to itself, and two pairs of pants can be adjacent via two distinct simple closed geodesics. In other words, the graph \( G(P) \) can contain loop edges at some vertices and double edges between vertices.

**Definition 4.9.** We say that \( S \) has strongly bounded geometry if \( S \) admits a pants decomposition \( P \) such that there are constants \( C \geq c > 0 \) with the property that the lengths of geodesic boundary components of each pair of pants possibly containing a cusp are bounded from above by \( C \) and from below by \( c \). We call such \( P \) uniform pants decomposition.

**Theorem 4.10.** Let \( S \) be a hyperbolic surface with strongly bounded geometry and \( P \) a uniform pants decomposition of \( S \). If \( G \) is the graph associated to \( P \), then \( G \) is quasi-isometric to the convex core \( C(S) \) without the union of all canonical cusp neighbourhoods. In particular, if \( G \) and \( G' \) are graphs associated to different uniform pants decompositions of \( S \), then \( G \) and \( G' \) are quasi-isometric.

**Proof.** The second statement follows directly from the first. The proof of the first statement is a standard argument which we give for the sake of completeness. Let \( x \) and \( y \) be points in \( C(S) \) without the union of all canonical cusp neighbourhoods, and let \( \gamma \) be the shortest geodesic path connecting them. Then \( \gamma \) decomposes into geodesic paths \( \gamma_i = \gamma \cap P_i, \ i \in \{1, \ldots, n\} \), where the \( P_i \) are the pairs of pants from \( P \) met by \( \gamma \). Since \( P \) is a uniform pants decomposition, it is not difficult to see that there exist constants \( C' \geq c' > 0 \) depending only on \( P \) so that

\[
c' \leq \ell(\gamma_i) \leq C', \ i \in \{1, \ldots, n\}.
\]

Since \( d(x, y) = \ell(\gamma) = \sum_{i=1}^{n} \ell(\gamma_i) \) we thus obtain

\[
c' d_P(P_1, P_n) - 2c' \leq d(x, y) \leq C' n.
\]

Now let \( n_{\text{min}} \) be the minimal number of pants in \( P \) that must be crossed by some geodesic segment of length \( d(x, y) \). Then we clearly have \( n_{\text{min}} \geq d(x, y)/C' \) and thus

\[
n \leq \frac{d(x, y)}{c'} \leq \frac{C'}{c'} n_{\text{min}} \leq \frac{C'}{c'} d_P(P_1, P_n).
\]

Therefore,

\[
d(x, y) \leq C' n \leq \frac{(C')^2}{c'} d_P(P_1, P_n),
\]

which finishes the proof. \( \square \)

By using [60, Theorem 4.7], which essentially ensures the invariance of amenability under quasi-isometries, we obtain the following corollary as a direct consequence of Theorem 4.10.
**Corollary 4.11.** If $S$ is a hyperbolic surface with strongly bounded geometry, and if $\mathcal{G}$ and $\mathcal{G}'$ are graphs associated to different uniform pants decompositions of $S$, then

$$\mathcal{G} : \text{amenable} \iff \mathcal{G}' : \text{amenable}.$$  

**Remark.** Given a hyperbolic surface $S = \mathbb{B}/G$ with strongly bounded geometry, and a uniform pants decomposition $\mathcal{P}$ of $S$, one can produce a uniformly distributed set $X$ in $H(\Lambda(G))$ in the following way: First, choose a point in each pair of pants of $\mathcal{P}$ and take the lifts of all such points to $H(\Lambda(G))$; secondly, in each horoball $D$ that is a lift of a cusp neighbourhood of $S$, we take the set of points $X_D$ canonically as in Section 3.

**Remark.** If $N$ is a non-trivial normal subgroup of a convex cocompact Fuchsian group $G$ acting on $\mathbb{B}^2$ so that the normal cover $S = \mathbb{B}^2/N$ preserves the structure of a pants decomposition $\mathcal{P}$ of $\mathbb{B}^2/G$, then $S$ has strongly bounded geometry, and, by Theorem 4.10, the graph $\mathcal{G}(\mathcal{P})$ associated to $\mathcal{P}$ is quasi-isometric to the Cayley graph of $G/N$.

## 5. Amenability and the Dimension Gap

In this section, we continue to investigate hyperbolic surfaces $S = \mathbb{B}^{n+1}/G$ with strongly bounded geometry and prove the following two theorems. They provide partial information on the relationship between amenability of the graph $\mathcal{G} = \mathcal{G}(\mathcal{P})$ associated to a uniform pants decomposition $\mathcal{P}$ and gaps between the three quantities $\delta(G)$, $\text{dim}_H(\Lambda(G))$ and $h_c(\Lambda(G))$.

**Theorem 5.1.** Let $S$ be a hyperbolic surface given by the Fuchsian group $G$. Assume $S$ is of infinite type with strongly bounded geometry. Let $\mathcal{G}$ be the graph associated to a uniform pants decomposition $\mathcal{P}$ of $S$. If $\mathcal{G}$ is uniformly strongly amenable, then all $\delta(G)$, $\text{dim}_H(\Lambda(G))$ and $h_c(\Lambda(G))$ are either equal to 1 or less than 1 at the same time.

**Theorem 5.2.** Let $S$ be a hyperbolic surface given by the Fuchsian group $G$. Assume $S$ is of infinite type with strongly bounded geometry. Let $\mathcal{G}$ be the graph associated to a uniform pants decomposition $\mathcal{P}$ of $S$. If $\mathcal{G}$ is non-amenable, then $\delta(G) < 1$.

In order to prove Theorems 5.1 and 5.2 we shall need some prerequisites.

**Definition 5.3.** The isoperimetric constant or Cheeger constant of a hyperbolic surface $S$ is defined as

$$h(S) = \sup_W \frac{A(W)}{\ell(\partial W)},$$

where the supremum is taken over all relatively compact domains $W \subset S$ with smooth boundary $\partial W$. Here, $A(W)$ denotes the hyperbolic area of $A$ and $\ell(\partial W)$ the hyperbolic length of the boundary.

**Remark.** Cheeger’s constant satisfies $h(S) \geq 1$ for any hyperbolic surface $S$. See [2] for a proof not relying on Theorems 4.3 and 5.4.

Fundamental estimates of $\lambda_0(S)$ in terms of $h(S)$ are given as follows by Cheeger [18] and Buser [15].
Theorem 5.4. For every hyperbolic surface $S$ we have
\[
\frac{1}{4h(S)^4} \leq h_0(S) \leq \frac{B}{h(S)}
\]
for some universal constant $B > 0$.

Definition 5.5. A geodesic domain $W^*$ in the hyperbolic surface $S$ is a domain of finite area so that $\partial W^*$ consists of finitely many simple closed geodesics; define the isoperimetric constant given by such domains as
\[
h^*(S) = \sup_{W^*} \frac{A(W^*)}{\ell(\partial W^*)},
\]
where the supremum is taken over all geodesic domains $W^*$ in $S$.

By definition, a geodesic domain $W^*$ in $S$ does not contain any funnels (i.e. half annuli in (2) of Definition 4.7) of $S$. Also, geodesic domains are not necessarily relatively compact, as they may contain cusps. Nonetheless, we have the following estimate, which is essentially a direct consequence of the definitions and [26] and [39, Theorem 7].

Proposition 5.6. Let $S$ be a hyperbolic surface of infinite type. Then,
\[
h^*(S) \leq h(S) \leq h^*(S) + 1.
\]

Definition 5.7. Let $S$ be a hyperbolic surface of infinite type with strongly bounded geometry, and $\mathcal{P}$ some uniform pants decomposition of $S$. Set
\[
h^\mathcal{P}(S) = \sup_{W^2} \frac{A(W^2)}{\ell(\partial W^2)},
\]
where the supremum is taken over all finite connected unions $W^2$ of pants from the pants decomposition $\mathcal{P}$.

Lemma 5.8. Let $S$ be a hyperbolic surface of infinite type with strongly bounded geometry, and $\mathcal{P}$ some uniform pants decomposition of $S$. Then there is a constant $b = b(\mathcal{P}) > 0$ so that
\[
h^*(S) \leq b h^\mathcal{P}(S).
\]

Proof. Take an arbitrary geodesic domain $W^*$ in $S$. For this $W^*$, let $W^2$ be the finite connected union of pants from $\mathcal{P}$ that consists of all pants having non-empty intersection with $W^*$. Since $W^* \subset W^2$, we have $A(W^*) \leq A(W^2)$. On the other hand, we compare $\ell(\partial W^*)$ with $\ell(\partial W^2)$ by considering the number of pants in $W^2$ intersecting $\partial W^*$. Let $n \geq 1$ be this number. There is a constant $a = a(\mathcal{P}) > 0$ such that every simple closed geodesic in $S$ has at least one piece of length greater than or equal to $a$ in common with any pair of pants from $\mathcal{P}$ it intersects. It follows that $\ell(\partial W^*) \geq an$. To each pair of pants in $W^2$ intersecting $\partial W^*$, there correspond at most two boundary components of $\partial W^2$, and the length of each boundary component is bounded from above by $C = C(\mathcal{P})$, which is the constant in the strongly bounded geometry condition. Hence $\ell(\partial W^2) \leq 2nC$. Therefore we have
\[
\frac{A(W^*)}{\ell(\partial W^*)} \leq \frac{A(W^2)}{an} \leq \frac{2C A(W^2)}{a \ell(\partial W^2)}.
\]
By setting $b = 2C/a$ and taking the supremum over all such $W^*$ and $W^2$, we obtain the required inequality. \qed
We are now in the position to prove Theorems 5.1 and 5.2.

**Proof of Theorem 5.1.** We consider the case where the convex hull $H(\Lambda(G))$ of the limit set of $G$ is weakly tight. This means that there exists a constant $\ell \geq 0$ such that every point $z$ in the convex core $C(S)$ except in the canonical cusp neighbourhoods is within distance $\ell$ from the boundary $\partial C(S)$. If this is satisfied, then Theorem 3.11 asserts that $h_c(\Lambda(G)) < 1$. Since $\delta(G) \leq \dim_H(\Lambda(G)) \leq h_c(\Lambda(G))$ by Theorem 3.3, these quantities are all less than 1 in this case.

Conversely, assume that the above condition is not satisfied. We will prove that $\delta(G) = 1$ in this case. Then we also have $\dim_H(\Lambda(G)) = h_c(\Lambda(G)) = 1$ and the proof is complete. By our assumption, we have a sequence of points $z_i$ in $C(S)$ without the union of canonical cusp neighbourhoods such that the distance from $z_i$ to $\partial C(S)$ tends to $\infty$ as $i \to \infty$.

Let $v_i$ be the vertex of the graph $G$ corresponding to the pair of pants that contains $z_i$. Uniformly strong amenability of $G$ implies that, for any $\varepsilon > 0$, there exist a positive integer $m$ and, for each $i$, a finite connected subgraph $K_i^{(m)}$ with $v_i \in K_i^{(m)}$ and $|K_i^{(m)}| \leq m$, such that

$$\frac{|\partial K_i^{(m)}|}{|K_i^{(m)}|} < \varepsilon.$$

Let $W_i^z$ be a finite connected union of the pants from $\mathcal{P}$ corresponding to the subgraph $K_i^{(m)}$. Note that $W_i^z$ contains $z_i$ and $W_i^z$ consists of at most $m$ pants from $\mathcal{P}$. Uniformity of the pants decomposition $\mathcal{P}$ implies that each pair of pants in $\mathcal{P}$ has a bounded diameter except for canonical cusp neighbourhoods. Hence the diameters of the $W_i^z$ without canonical cusp neighbourhoods are uniformly bounded independently of $i$. Since the distance from $z_i$ to $\partial C(S)$ tends to $\infty$ as $i \to \infty$, the subsurfaces $W_i^z$ are contained in the interior of $C(S)$ for all sufficiently large $i$.

We express $A(W_i^z)$ and $\ell(\partial W_i^z)$ by using $|K_i^{(m)}|$ and $|\partial K_i^{(m)}|$ for a sufficiently large $i$. It is easy to see that $A(W_i^z) = 2\pi |K_i^{(m)}|$. By the fact that $W_i^z$ is contained in the interior of $C(S)$, the pairs of pants in $W_i^z$ which correspond to elements of $\partial K_i^{(m)}$ are the only ones contributing to $\partial W_i^z$, and have at most two boundary curves in $\partial W_i^z$, that is, the number of the boundary components of $\partial W_i^z$ is bounded by $2|\partial K_i^{(m)}|$. Hence

$$\frac{A(W_i^z)}{\ell(\partial W_i^z)} \geq \frac{2\pi |K_i^{(m)}|}{2C|\partial K_i^{(m)}|} > \frac{\pi}{C\varepsilon}.$$

However, since $\varepsilon$ can be taken arbitrarily small, this estimate actually implies that $h(S) = \infty$. Then, by Theorems 4.3 and 5.4, we conclude that $\delta(G) = 1$. □

**Proof of Theorem 5.2.** For the uniform pants decomposition $\mathcal{P}$ of $S$, we consider some finite connected union $W^z$ of pants from $\mathcal{P}$. Also, for the graph $G$ associated to $\mathcal{P}$, let $K$ be the subgraph of $G$ associated to $W^z$. Note that $K$ is connected and, by definition of $G$, no pairs of pants are discarded while constructing $K$ from $W^z$. The area $A(W^z)$ is given by $2\pi |K|$.

The pairs of pants in $W^z$ which correspond to elements of $\partial K$ have at least one boundary curve in $\partial W^z$. Also, note that pairs of pants that produce loop edges at vertices in $K$ do not contribute to $\partial W^z$, for the corresponding vertices of $K$ cannot
be in \( \partial K \). Therefore, the fact that \( P \) is a uniform pants decomposition implies

\[
\ell(\partial W) \geq c|\partial K|.
\]

But \( \mathcal{G} \) was assumed to be non-amenable, and we conclude that

\[
h^P(S) \leq \frac{2\pi}{c} \sup_K \frac{|K|}{|\partial K|} < \infty,
\]

where the supremum is taken over all finite connected subgraphs \( K \) of \( \mathcal{G} \). By Proposition 5.6 and Lemma 5.8 it now follows that

\[
h(S) \leq h^*(S) + 1 \leq b \ h^P(S) + 1 \leq \frac{2\pi b}{c} \sup_K \frac{|K|}{|\partial K|} + 1 < \infty.
\]

Finally, Theorem 5.4 implies that \( \lambda_0 > 0 \). Employing Theorem 4.3 this finishes the proof. \( \square \)

We have the following corollary to both Theorems 5.1 and 5.2.

**Corollary 5.9.** Let \( S \) be a hyperbolic surface given by the Fuchsian group \( G \). Assume that \( S \) is of infinite type with strongly bounded geometry. Let \( \mathcal{G} \) be the graph associated to some uniform pants decomposition \( P \) of \( S \). Assume that \( h_c(\Lambda(G)) = 1 \) and \( \mathcal{G} \) is homogeneous. Then

\[\mathcal{G} : \text{non-amenable} \iff \delta(G) < 1.\]

When \( G \) is a non-trivial normal subgroup of a cocompact Fuchsian group, Theorem 4.4 provides a similar consequence. However, in Corollary 5.9 we have only to assume that the graph \( \mathcal{G} \) is homogeneous, which is weaker than the condition that \( S \) itself admits the covering group action.

**Remark.** Amenability of graphs is preserved by quasi-isometries (see e.g. [60, Theorem 4.7]). If \( \mathcal{G} \) is ‘quasi-homogeneous’ in the sense that any vertex of \( \mathcal{G} \) is mapped to a fixed vertex by a uniform quasi-isometry, then Corollary 5.9 is still true under this weaker assumption on \( \mathcal{G} \).

Motivated by the statements of Theorem 4.2 and Corollary 5.9 we formulate the following conjecture.

**Conjecture 5.10.** Let \( S \) be a hyperbolic surface of infinite type having strongly bounded geometry, and assume \( S = \mathbb{B}^2/G \), with \( G \) a Fuchsian group. Let \( \mathcal{G} \) be the graph associated to some uniform pants decomposition \( P \) of \( S \). Then

\[\mathcal{G} : \text{non-amenable} \iff \delta(G) < h_c(\Lambda(G)).\]

**Remark.** Our further strategy, pursued in Sections 7 and 8 will be to provide a condition under which \( \dim_H(\Lambda(G)) = h_c(\Lambda(G)) \) holds, in which case \( \delta(G) < \dim_H(\Lambda(G)) \) would follow from the above conjecture.

**Remark.** Formulating the above statements in higher dimensions depends on defining a higher dimensional analogue to the pants decomposition of a hyperbolic surface.
6. Examples of dimension gap

In this section, we will illustrate two examples of a surface $S = \mathbb{B}^2/G$ for which the condition $\delta(G) < h_c(\Lambda(G))$ is satisfied. In these examples, the graph associated to some uniform pants decomposition of $S$ is non-amenable. Thus, these examples may serve as an evidence for the conjecture raised in the previous section.

The building block for our Riemann surface will be a pair of pants $P_t$ all of whose boundary geodesics $a_1$, $a_2$ and $a_3$ have the same length $\ell > 0$. Let $H_\ell$ be the symmetric half of $P_t$, which is the right-angled hexagon having the sides $a_1^+$, $a_2^+$ and $a_3^+$ of length $\ell/2$. Let $o$ be the centre of $H_\ell$ and $r(\ell) > 0$ be the distance between $o$ and the midpoint of $a_i^+$ ($i = 1, 2, 3$). Then, a simple calculation using hyperbolic trigonometry yields that

$$r(\ell) = \arccosh \sqrt{\frac{4\sinh^2(\ell/4) + 1}{3\sinh^2(\ell/4)}}.$$

In particular, $r(\ell)$ is a decreasing function of $\ell$ and

$$\lim_{\ell \to \infty} r(\ell) = \arccosh \frac{2}{\sqrt{3}} = \frac{\log 3}{2} \approx 0.55.$$

Example 6.1. Take the pair of pants $P_t$ and glue a funnel (half annulus) along $a_1^+$ and two other pants $P_t$ along $a_2^+$ and $a_3^+$ without twist, that is, in such a way that their symmetric axes meet and their half hexagons $H_\ell$ are connected. The resulting surface has four boundary components and we glue four other pants $P_t$ along them in the same manner. Continuing this process, we obtain a hyperbolic surface $S$ of infinite type which has one boundary component at infinity. Let $G$ be a Fuchsian group such that $S = \mathbb{B}^2/G$.

We choose the midpoints of the sides of all right-angled hexagons $H_\ell$ in $S$ and denote the set of all such midpoints by $\hat{X} \subset C(S)$. Let $X$ be the inverse image of $\hat{X}$ under the projection $\mathbb{B}^2 \to S$. Then, clearly, $X$ is a uniformly distributed set in the convex hull $H(\Lambda(G))$ of the limit set of $G$, and Proposition 3.4 states that the convex core entropy $h_c(\Lambda(G))$ is given by $\Delta(X)$.

We will estimate this $\Delta(X)$. Let $x_0 \in X$ be a point such that its projection $\hat{x}_0 \in \hat{X}$ is the midpoint of the side on $\partial C(S)$ facing the boundary at infinity of $S$. The number of points in $\hat{X}$ within distance $2n r(\ell)$ from $\hat{x}_0$ can be estimated as $\#(\hat{X} \cap B_{2n r(\ell)}(\hat{x}_0)) \geq 2^n$ for every $n \geq 0$. Hence we have

$$\Delta(X) = \limsup_{R \to \infty} \frac{\log \#(X \cap B_R(x_0))}{R} \geq \limsup_{n \to \infty} \frac{\log \#(\hat{X} \cap B_{2n r(\ell)}(\hat{x}_0))}{2n r(\ell)} \geq \lim_{n \to \infty} \frac{\log(2^n)}{2n r(\ell)} = \frac{\log 2}{2 r(\ell)}.$$

Since $\log 2 \approx 0.69$, we see that $h_c(\Lambda(G)) > 1/2$ for all sufficiently large $\ell$.

On the other hand, we will estimate $\delta(G)$ by using the isoperimetric constant $h^P(S)$ for the pants decomposition $P$ trivially obtained from the construction of $S$. Let $W^\ell$ be an arbitrary connected finite (not single) union of pants from $P$. Then the number of components of $\partial W^\ell$ is always greater than the number of pants in
W^2. Hence
\[ h^P(S) = \sup_{W^2} \frac{A(W^2)}{\ell(W^2)} \leq \frac{2\pi}{\ell}. \]

By Proposition 5.6 and Lemma 5.8, we have
\[ (1 \leq h(S) \leq h^*(S) + 1 \leq bh^P(S) + 1 = \frac{2b\pi}{\ell} + 1, \]
where \( b = b(P) > 0 \) is a constant depending on \( P \). As \( \ell \) tends to infinity, \( h(S) \to 1 \), and thus \( \lambda_0(S) \to 1/4 \) by Theorem 5.4. Therefore, \( \delta(G) \to 1/2 \) by Theorem 4.3. Hence, for all sufficiently large \( \ell \), we have the strict inequality \( \delta(G) < h_c(\Lambda(G)) \).

In the above example, the convex core entropy \( h_c(\Lambda(G)) \) is actually equal to one in spite of the fact that the above arguments cannot produce this value. This is because \( \dim_H(\Lambda(G)) \leq h_c(\Lambda(G)) \) by Theorem 3.5 and \( \dim_H(\Lambda(G)) = 1 \) by [38, Theorem 2]. (Actually the 1-dimensional Hausdorff measure of \( \Lambda(G) \) is positive in this case.) On the other hand, since the graph associated to the uniform pants decomposition \( P \) is non-amenable, Theorem 5.2 yields \( \delta(G) < 1 \). Thus,
\[ \delta(G) < 1 = \dim_H(\Lambda(G)) = h_c(\Lambda(G)) \]
for this example, which also shows that the assumption of amenability is necessary in the statement of Theorem 5.1.

In what follows, we give another example of a situation where \( \delta(G) < h_c(\Lambda(G)) \), with \( h_c(\Lambda(G)) \) being strictly less than one, for which we also get control on the Hausdorff dimension of the limit set, in the sense that \( \dim_H(\Lambda(G)) < 1 \).

**Example 6.2.** We first take the same surface \( S \) as in Example 6.1 but then we cut off some of the pants in the following way. Let \( G \) be the graph associated with the pants decomposition of \( S \). This is a binary tree which is rooted at the vertex \( v_0 \) corresponding to the pair of pants that contains \( \hat{x}_0 \), and which branches into two edges at every vertex (the valency is three at every vertex except \( v_0 \)). There are four vertices at depth 2 from \( v_0 \). We remove one of the four vertices and the edge just terminating at this vertex as well as the subtree rooted at this vertex. By this surgery, there remain 3 vertices at depth 2 from \( v_0 \). We repeat the same process beginning from the three \( v_2 \), namely, remove one of the four vertices at depth 2 from each \( v_2 \). Thus there remain 9 vertices at depth 4 from \( v_0 \). We continue this surgery inductively to obtain a new graph \( G' \). Then we rebuild a hyperbolic surface \( S' \) from \( G' \) by replacing each vertex of \( G' \) with the pair of pants \( P_\ell \) and by attaching funnels to the boundary components resulting from this cut-off process. Let \( G' \) be a Fuchsian group such that \( S' = \mathbb{H}^2/G' \).

Let \( \hat{X}' \subset C(S') \) be the set of all midpoints of the sides as before and let \( X' \) be the inverse image of \( \hat{X} \) under the projection \( \mathbb{H}^2 \to S' \). Taking the base points \( x_0 \in X' \) and \( \hat{x}_0 \in \hat{X}' \) for the associated Poincaré series, we estimate \( \Delta(X') \). Let \( d(\ell) \) be the distance between the midpoints of any two distinct sides of \( H_\ell \), which thus satisfies \( d(\ell) \leq 2r(\ell) \). By the construction of \( S' \), we have \( \#(\hat{X} \cap B_{2n} d(\ell)(\hat{x}_0)) \geq 3^n \) for every
\textbf{Patterson measures for uniformly distributed sets}

Fix a uniformly distributed set \( X \) in the convex hull \( H(\Lambda) \subset \mathbb{B}^{n+1} \) of a closed set \( \Lambda \subset \mathbb{S}^n \). For any exponent \( s \) greater than \( \Delta = \Delta(X) \) and for any \( z \in \mathbb{B}^{n+1} \), we consider the purely atomic measure \( \mu_s^z \) on \( \mathbb{B}^{n+1} \) given by

\[
\mu_s^z = \frac{1}{P^s(X,o)} \sum_{x \in X} e^{-sd(x,z)} \mathbf{1}_x.
\]

Here, \( o \) is the origin of \( \mathbb{B}^{n+1} \) and \( \mathbf{1}_x \) is the point mass at \( x \). The total mass \( \sigma(\mu_s^z) \) of \( \mu_s^z \) is \( P^s(X,z)/P^s(X,o) \). Since \( \sigma(\mu_o^z) = 1 \), we have

\[
e^{-sd(z,o)} \leq \sigma(\mu_s^z) \leq e^{sd(z,o)}.
\]

For the moment, we impose the following assumption on the divergence of the Poincaré series at the exponent \( \Delta \):

\[
\lim_{r \to \infty} \frac{\log \#(X' \cap B(x))}{R} = \infty.
\]

We say that (the Poincaré series for) \( X \) is of \textit{divergence type} if this condition is satisfied. Later, we will see that this is automatically satisfied for the Poincaré series for a uniformly distributed set \( X \) of \textit{bounded type} defined below (see Corollary 7.9).

Similar to the usual Patterson construction of conformal measures on \( \mathbb{S}^n \), we take a decreasing sequence of exponents \( \{s_j\} \) with \( \lim_{j \to \infty} s_j = \Delta \). Then, passing to a subsequence if necessary, we have a weak-* limit of the sequence of purely atomic measures \( \{\mu_{s_j}^z\} \) on the compact topological space \( \overline{\mathbb{B}^{n+1}} = \mathbb{B}^{n+1} \cup \mathbb{S}^n \), which
we denote by \( \mu_z \). Note that this may be depending on the choice of the sequence of exponents \( \{ s_j \} \), but we expect that \( \mu_z \) is uniquely determined independently of \( \{ s_j \} \). It is well-known that when \( X \) is the orbit of a convex cocompact Kleinian group, this uniqueness holds. Although we cannot assume uniqueness of \( \mu_z \) for uniformly distributed sets in general, it is easy to see that if \( \mu^{s_j}_\circ \) has a weak-* limit \( \mu_\circ \) for \( z = \circ \), then \( \mu^{s_j}_z \) has a weak-* limit \( \mu_z \) for every \( z \in \mathbb{B}^{n+1} \) by the same sequence of exponents \( \{ s_j \} \). Hence, whenever we consider a family of measures \( \{ \mu_z \}_{z \in \mathbb{B}^{n+1}} \), we always regard them as the weak-* limits for the same sequence \( \{ s_j \} \). We call \( \{ \mu_z \}_{z \in \mathbb{B}^{n+1}} \) a Patterson measure for the uniformly distributed set \( X \) in the convex hull \( H(\Lambda) \).

**Proposition 7.1.** Let \( \{ \mu_z \}_{z \in \mathbb{B}^{n+1}} \) be a Patterson measure for a uniformly distributed set \( X \) in the convex hull \( H(\Lambda) \) of a closed set \( \Lambda \subset \mathbb{S}^n \). Then the following properties are satisfied:

1. The support of each \( \mu_z \) is in \( \Lambda \);
2. The measures \( \{ \mu_z \} \) are absolutely continuous to each other and the Radon-Nikodym derivative satisfies
   \[
   \frac{d\mu_z}{d\mu_\circ}(\xi) = k(z, \xi)^\Delta
   \]
   for any \( z \in \mathbb{B}^{n+1} \) and for any \( \xi \in \Lambda \). Here \( k(z, \xi) = (1 - |z|^2)/|\xi - z|^2 \) is the Poisson kernel and \( \Delta = \Delta(X) \).

This proposition says that the Patterson measure \( \{ \mu_z \}_{z \in \mathbb{B}^{n+1}} \) is a \( \Delta \)-conformal measure that is supported on \( \Lambda \). A proof can be obtained in a similar manner to the case of Patterson measures for Kleinian groups.

The total mass of \( \mu_z \) is given by
\[
\sigma(\mu_z) = \lim_{j \to \infty} \sigma(\mu^{s_j}_z) = \lim_{j \to \infty} \frac{P^{s_j}(X, z)}{P^{s_j}(X, \circ)}.
\]
Then, for every \( z \in \mathbb{B}^{n+1} \),
\[
e^{-\Delta d(z, \circ)} \leq \sigma(\mu_z) \leq e^{\Delta d(z, \circ)}.
\]

**Definition 7.2.** We say that a uniformly distributed set \( X \) is of bounded type if there exists a constant \( \rho \geq 1 \) such that
\[
\frac{|X \cap B_R(x)|}{|X \cap B_R(\circ)|} \leq \rho
\]
for every \( x \in X \) and for every \( R > 0 \). Here we assume that the origin \( \circ \in \mathbb{B}^{n+1} \) belongs to \( X \).

When \( X \) is the orbit of a convex cocompact Kleinian group, \( X \) is clearly of bounded type. This is not the case for a uniformly distributed set \( X \) in the convex hull of a geometrically finite group with parabolic elements. Hence, it is useful to adapt the bounded type condition in such a way that it also covers geometrically finite Kleinian groups. This will be done later in this section.

It is easy to see that, if \( X \) is of bounded type, then \( P^s(X, x)/P^s(X, \circ) \leq \rho \) for every \( x \in X \) and every \( s > \Delta(X) \), and hence
\[
\limsup_{s \searrow \Delta} \frac{P^s(X, x)}{P^s(X, \circ)} \leq \rho.
\]
This is also true for every $x$ in $H(\Lambda)$ by replacing $\rho$ with $K = \rho e^{\Delta M}$, where $M > 0$ is the constant in the definition of uniform distribution. Then, by an elementary observation in hyperbolic geometry, we see that the total mass $\sigma(\mu_z)$ of the Patterson measure $\mu_z$ is uniformly bounded by $K$ for every $z \in \mathbb{B}^{n+1}$.

We will now deal with the situation that the Poincaré series of $X$ converges at the exponent $\Delta$. We shall introduce a Patterson function and a modified Poincaré series to construct a Patterson measure $\mu_z$, as in the case of the ordinary Poincaré series for Kleinian groups (see for instance [25]).

**Definition 7.3.** For a uniformly distributed set $X$, a continuous, non-decreasing function $h : (0, \infty) \to (0, \infty)$ is called a *Patterson function* (or sometimes *slowly varying function*) if the following conditions are satisfied:

1. The modified Poincaré series
   \[ P_h^s(X, z) = \sum_{x \in X} h(d(x, z)) e^{-sd(x, z)} \]
   converges for $s > \Delta(X)$ and diverges for $s \leq \Delta(X)$;

2. For every $\varepsilon > 0$, there exists a constant $r_0 > 0$ such that $h(t + r) \leq e^{\varepsilon t} h(r)$ for all $r \geq r_0$ and $t > 0$;

3. There exists a constant $C > 0$ such that $h(r + t) \leq C h(r) h(t)$ for all $r > 0$ and $t > 0$.

The same proof as in the case of orbits of Kleinian groups shows that a Patterson function exists for any uniformly distributed set $X$. Notice that, if $P^\Delta(X, z) = \infty$, then the constant function $h(t) \equiv 1$ can be a Patterson function for $X$. Hence, by the same construction using the modified Poincaré series instead of the ordinary one, we have a $\Delta$-conformal measure $\{\mu_z\}_{z \in \mathbb{B}^{n+1}}$ supported on $\Lambda$, which we again call a Patterson measure for $X$.

**Proposition 7.4.** Assume that the uniformly distributed set $X$ is of bounded type. Then there exists a Patterson function $h$ for $X$ and a constant $\rho \geq 1$ such that the modified Poincaré series satisfies

\[ \frac{P_h^s(X, x)}{P_h^s(X, o)} \leq \rho \]

for every $x \in X$ and for every $s > \Delta(X)$.

**Proof.** Since $X = \{x_i\}_{i \in \mathbb{N}}$ is of bounded type, there is by definition a constant $\rho \geq 1$ such that $\#(X \cap B_R(x)) \leq \rho \#(X \cap B_R(o))$ for every $x \in X$ and for every $R > 0$. This implies that

\[ \sum_{d(x_i, x) \leq R} h(d(x_i, x)) e^{-sd(x_i, x)} \leq \rho \sum_{d(x_j, o) \leq R} h(d(x_j, o)) e^{-sd(x_j, o)} \]

for every $R > 0$. Taking the limit as $R \to \infty$, we have the desired estimate. \qed

By the same argument as before, we see from Proposition 7.4 that, if $X$ is of bounded type, then the total mass $\sigma(\mu_z)$ of the Patterson measure $\mu_z$ for $X$ is uniformly bounded by $K$ independently of $z \in \mathbb{B}^{n+1}$.

**Proposition 7.5.** The Patterson measure $\mu_z$ for $X$ has no atom in $\Lambda$ if $X$ is of bounded type.
Proof. If $\mu_z$ has an atom at $\xi \in \Lambda$, then 
$$\sigma(\mu_z) \geq \mu_z(\{\xi\}) = k(z, \xi)^\Delta \mu_o(\{\xi\}),$$
and this diverges to $\infty$ when $z \in \mathbb{B}^{n+1}$ tends to $\xi$ radially. However, this contradicts the fact that the total mass $\sigma(\mu_z)$ is uniformly bounded. \hfill $\square$

One of the very useful properties of Patterson measures for groups is given by the so-called Sullivan shadow lemma. In our case we obtain a partial result, which will be sufficient for further considerations.

**Definition 7.6.** For a point $x \in \mathbb{B}^{n+1}$ different from the origin $o$, the antipodal point $x^* \in S^n$ is the end point of the geodesic ray from $x$ passing through $o$. Let $B(x, \ell)$ be a hyperbolic ball with the centre $x$ and radius $\ell > 0$. The shadow $S(x, \ell)$ of the ball $B(x, \ell)$ is the set of points $y \in S^n$ so that the geodesic from $x^*$ to $y$ intersects $B(x, \ell)$.

The diameter of a shadow $S(x, \ell)$ is measured using the spherical distance on $S^n$ and is denoted by $\text{diam} S(x, \ell)$. In the case of the orbits of Kleinian groups, the shadow lemma asserts that the Patterson measure of a shadow and the $\Delta$-power of its diameter are comparable. In our case, we have a similar statement as follows.

**Theorem 7.7.** Let $X$ be a uniformly distributed set of bounded type and $\mu_z$ the Patterson measure for $X$ with uniformly bounded total mass $\sigma(\mu_z) \leq K$. Fix a radius $\ell > 0$. Then there exists a constant $A > 0$ depending only on $K$ and $\ell$ such that the diameter of a shadow $S(x, \ell)$ for any $x \in X \setminus \{o\}$ satisfies

$$A (\text{diam} S(x, \ell))^\Delta \geq \mu_o(S(x, \ell)).$$

Proof. Let $\gamma_x$ be a conformal automorphism of $\mathbb{B}^{n+1}$ that sends $x$ to $o$. Its linear stretching factor $|\gamma_x'(\xi)|$ at $\xi \in S^n$ coincides with the Poisson kernel $k(x, \xi)$. We will estimate $|\gamma_x'(\xi)|$ on $S(x, \ell)$. For any $\xi \in S(x, \ell)$, set $\eta = \gamma_x(\xi)$. Then

$$|\gamma_x'(\xi)| = \left| \frac{1}{(\gamma_x^{-1})'(\eta)} \right| = \frac{|\eta - \gamma_x(o)|^2}{1 - |\gamma_x(o)|^2} = \frac{|\eta - \gamma_x(o)|^2}{1 - |x|^2}. $$

Here we have constants $a > 0$ and $b > 0$ depending only on $\ell$ such that

$$1 - |x|^2 \leq a \text{ diam} S(x, \ell) \quad \text{and} \quad |\eta - \gamma_x(o)|^2 \geq b$$

for any $\eta$ in $\gamma_x(S(x, \ell))$. Therefore,

$$k(x, \xi) = |\gamma_x'(\xi)| \geq \frac{b}{a \text{ diam} S(x, \ell)},$$

and hence

$$K \geq \sigma(\mu_z) \geq \int_{S(x, \ell)} d\mu_z(\xi) = \int_{S(x, \ell)} k(x, \xi)^\Delta d\mu_o(\xi) \geq \left( \frac{b}{a} \right)^\Delta \frac{\mu_o(S(x, \ell))}{(\text{diam} S(x, \ell))^\Delta}. $$

By taking $A = K(a/b)^\Delta$, we obtain the assertion. \hfill $\square$
Employing the shadow lemma (Theorem 7.7) and condition (i) of the definition of uniformly distributed sets, we can obtain the lower estimate of the Hausdorff dimension of \( \Lambda \) by the critical exponent \( \Delta = \Delta(\mathcal{X}) \). This is a generalisation of the corresponding result for the Hausdorff dimension of limit sets of convex cocompact Kleinian groups.

**Theorem 7.8.** Let \( \Lambda \) be a closed subset on \( \mathbb{S}^n \) and assume that there is a uniformly distributed set \( \mathcal{X} \) of bounded type in the convex hull \( H(\Lambda) \). Then the \( \Delta \)-dimensional Hausdorff measure of \( \Lambda \) is positive. In particular, \( \dim_H(\Lambda) \geq \Delta(\mathcal{X}) \), and hence we have that \( \dim_H(\Lambda) = \Delta(\mathcal{X}) = h_c(\Lambda) = \dim_B(\Lambda) \).

**Proof.** By usual arguments (see Nicholls [43, Section 4.6]) relying on Theorem 7.7, the \( \Delta \)-dimensional Hausdorff measure \( m \) satisfies \( m(\Lambda) \geq c \mu_o(\Lambda) \) for some constant \( c > 0 \). Since \( \mu_o(\Lambda) > 0 \), we have that \( m(\Lambda) > 0 \). This implies that \( \dim_H(\Lambda) \geq \Delta(\mathcal{X}) \). By Theorem 3.5 and Proposition 3.4, we conclude \( \dim_H(\Lambda) = \Delta(\mathcal{X}) = h_c(\Lambda) = \dim_B(\Lambda) \). Thus, \( \dim_B(\Lambda) \) exists and equals all of these invariants. \( \square \)

**Remark.** We have relied on the shadow lemma (Theorem 7.7) in order to show Theorem 7.8. An alternative proof may be possible by using the arguments in Bishop and Jones [11] which give \( \dim_H(\Lambda(G)) = \delta(G) \) for any non-elementary Kleinian group \( G \). However, these arguments require some degree of homogeneity of \( \mathcal{X} \) and it is not easy to deduce this only from the bounded type condition for \( \mathcal{X} \). In other words, it is only the number of points in \( \mathcal{X} \) within some distance from some point \( x \in X \) which is controlled by the bounded type condition, whereas all 'geometric characteristics' (i.e. both distance and direction) of \( \mathcal{X} \) viewed from \( x \in X \) must be almost the same in order to apply Bishop and Jones’ arguments.

From Theorem 7.8, we see that the bounded type property implies the divergence type property of the Poincaré series for a uniformly distributed set \( \mathcal{X} \).

**Corollary 7.9.** Any uniformly distributed set \( \mathcal{X} \) of bounded type in \( H(\Lambda) \) satisfies \( P^\Delta(X, o) = \infty \) for \( \Delta = \Delta(\mathcal{X}) \).

**Proof.** For \( X = \{x_i\}_{i \in \mathbb{N}} \), take the shadows \( S(x_i, \ell) \subset \mathbb{S}^n \), \( i \in \mathbb{N} \), of Euclidean diameter comparable to \( e^{-d(x_i, o)} \) with constant of comparability only depending on \( \ell \). Since

\[
\Lambda = \limsup\{S(x_i, \ell) : i \in \mathbb{N}\},
\]

the convergence of \( P^\Delta(X, o) \) implies, by means of the Borel-Cantelli lemma, that the \( \Delta \)-dimensional Hausdorff measure \( m(\Lambda) \) of \( \Lambda \) is zero. However, Theorem 7.8 gives \( m(\Lambda) > 0 \). This shows that \( P^\Delta(X, o) \) diverges. \( \square \)

Conversely, one may ask whether the divergence type property of the Poincaré series for \( \mathcal{X} \) implies \( \dim_H(\Lambda) = h_c(\Lambda) = \dim_B(\Lambda) \). There are closed sets \( \Lambda \subset \mathbb{S}^n \) such that \( \dim_H(\Lambda) < \dim_B(\Lambda) \), for example those given by McMullen [42]. This tells us that, by Theorem 7.8, not all closed sets \( \Lambda \subset \mathbb{S}^n \) necessarily contain a uniformly distributed set \( \mathcal{X} \) of bounded type in their convex hull \( H(\Lambda) \).

In the remainder of this section, we shall attempt to extend the above arguments to the case where \( H(\Lambda) \) contains horoballs. When \( \Lambda = \Lambda(G) \) is the limit set of some Kleinian group \( G \), this occurs mainly in the case where \( G \) has parabolic elements and \( H(\Lambda(G)) \neq \mathbb{B}^{n+1} \) contains no uniformly distributed set of bounded type. However, we want to include, say, the limit set of a geometrically finite Kleinian
group with parabolics in the category of ‘preferred’ closed sets. Hence we weaken
the definition of the bounded type condition in the following way.

**Definition 7.10.** We say that a uniformly distributed set \( X \) is of **weakly bounded type** if there exist a constant \( \rho \geq 1 \) and a family of mutually disjoint horoballs \( \{D_p\}_{p \in \Phi} \) in \( \mathbb{B}^{n+1} \) with set of tangency points \( \Phi \subset S^n \) such that

\[
\frac{\#(X \cap B_R(x))}{\#(X \cap B_R(o))} \leq \rho
\]

for every \( x \in X' \) and for every \( R > 0 \). Here \( X' = X \cap (\mathbb{B}^{n+1} \setminus \bigcup_{p \in \Phi} D_p) \) and we assume that the origin \( o \in \mathbb{B}^{n+1} \) belongs to \( X' \).

Under this assumption, we can also conclude that the Poincaré series for the uniformly distributed set \( X \) is of divergence type if the corresponding Patterson measure has no atom on the set \( \Phi \) of tangency points of horoballs. In this case, we are led to consider the packing dimension \( \dim_P(\Lambda) \) of \( \Lambda \) instead of the Hausdorff dimension.

**Theorem 7.11.** Suppose that a uniformly distributed set \( X \) in the convex hull of \( \Lambda \subset S^n \) is of weakly bounded type and the Patterson measure \( \mu_z \) for \( X \) has no atom on the tangency points \( p \in \Phi \subset S^n \) of the horoballs \( \{D_p\}_{p \in \Phi} \) appearing in the definition of weak boundedness. Then the packing dimension \( \dim_P(\Lambda) \) of \( \Lambda \) coincides with \( \Delta(X) = h_c(\Lambda) = \overline{\dim_B}(\Lambda) \). Moreover, \( P^\Delta(X,o) = \infty \) for \( \Delta = \Delta(X) \).

**Proof.** Since the Patterson measure \( \mu_z \) has no atom on any \( p \in \Phi \), we have \( \mu_{o}(\Lambda') > 0 \) for \( \Lambda' = \Lambda \setminus \Phi \). Using Theorem 7.7 for \( X' = X \cap (\mathbb{B}^{n+1} \setminus \bigcup_{p \in \Phi} D_p) \) and applying the same argument as in Sullivan [56], we see that the \( \Delta \)-dimensional packing measure \( \nu \) satisfies \( \nu(\Lambda') \geq c \mu_o(\Lambda') \) for some constant \( c > 0 \). Hence \( \nu(\Lambda) > 0 \), which implies that \( \dim_P(\Lambda) \geq \Delta(X) = h_c(\Lambda) \). On the other hand, since the packing dimension \( \dim_P(\Lambda) \) is always less than or equal to the upper box-counting dimension \( \overline{\dim_B}(\Lambda) \), we have \( \dim_P(\Lambda) = h_c(\Lambda) \).

The proof of the latter statement is carried out similarly to Corollary 7.9 by using \( X' = \{x_i\}_{i \in \mathbb{N}} \) instead of \( X \). Namely, take the shadow \( S(x_i, \ell) \subset S^n \) of Euclidean diameter comparable to \( e^{-d(x_i, o)} \) for each \( i \), and represent \( \Lambda' = \limsup\{S(x_i, \ell) : i \in \mathbb{N}\} \). By the Borel-Cantelli lemma, the convergence \( P^\Delta(X', o) \leq P^\Delta(X, o) < \infty \) implies that \( \nu(\Lambda') = 0 \). Hence \( \nu(\Lambda') > 0 \) yields \( P^\Delta(X,o) = \infty \).

A sufficient condition for the Patterson measure to have no atom on \( \Phi \) can be easily given in the usual way when \( \Lambda \) is the limit set of some Kleinian group.

**Corollary 7.12.** Let \( G \) be a non-elementary Kleinian group acting on \( \mathbb{H}^{n+1} \) all of whose parabolic fixed points are bounded. If a uniformly distributed set \( X \) in \( H(\Lambda(G)) \) is of weakly bounded type for the set \( \Phi \) of all parabolic fixed points of \( G \), then \( \dim_P(\Lambda(G)) = \Delta(X) \) and \( P^\Delta(X,o) = \infty \).

**Proof.** We can choose \( X' = X \cap (\mathbb{B}^{n+1} \setminus \bigcup_{p \in \Phi} D_p) \) invariant under \( G \). Then, a similar argument as in the case of Patterson measures defined by an orbit of \( G \) gives that the Patterson measure \( \mu'_p \) for \( X' \) has no atom on the bounded parabolic fixed points of \( G \). The statement therefore follows from the proof of the previous theorem.
Remark. It is known that, if $\dim_B(\Lambda \cap U) = \dim_B(\Lambda)$ for every open set $U \subset \mathbb{S}^n$ that intersects $\Lambda$, then $\dim_P(\Lambda) = \dim_B(\Lambda)$ (see e.g. Falconer [23, Corollary 3.9]). This also yields the first assertion of the above corollary.

8. Kleinian groups of bounded type

For a Kleinian group $G$ acting on $\mathbb{B}^{n+1}$, we consider the problem whether there is a uniformly distributed set $X$ of bounded type in the convex hull $H(\Lambda(G))$ of the limit set $\Lambda(G) \subset \mathbb{S}^n$. When this is the case, we say that the Kleinian group $G$ is of bounded type. If $G$ is of bounded type, then $\dim_H(\Lambda(G)) = \dim_B(\Lambda(G)) = \dim_P(\Lambda(G))$ by Theorem 7.8. Any convex cocompact Kleinian group $G$ is of bounded type because the orbit $X$ of any point in $H(\Lambda(G))$ is a $G$-invariant uniformly distributed set, and in particular of bounded type.

First, we show that the bounded type property is inherited to normal subgroups.

**Proposition 8.1.** If $G$ is a non-trivial normal subgroup of a convex cocompact Kleinian group $\hat{G}$, then $G$ is of bounded type. More generally, any non-trivial normal subgroup $G$ of a Kleinian group $\hat{G}$ of bounded type is also of bounded type.

**Proof.** Let $X$ be a uniformly distributed set of bounded type for $\Lambda(\hat{G})$ satisfying by definition

$$\#(X \cap B_R(x)) \leq \rho$$

for every $x \in X$ and for every $R > 0$, we consider $X' = f(X)$, which may not be in the convex hull $H(\Lambda(G'))$ of $G'$. By composing, if necessary, with another rough-isometric automorphism $G'$ onto itself, we may assume that $X'$ is a uniformly distributed set for $\Lambda(G)$ satisfying by definition

$$\frac{\#(X \cap B_R(x))}{\#(X \cap B_R(o))} \leq \rho$$

for every $x \in X$ and for every $R > 0$, we consider $X' = f(X)$, which may not be in the convex hull $H(\Lambda(G'))$ of $G'$. By composing, if necessary, with another rough-isometric automorphism $G'$ onto itself, we may assume that $X'$ is a uniformly distributed set for $\Lambda(G)$. □

Next, we investigate if certain deformations of Kleinian groups preserve the bounded type property. Recall that a homeomorphism $f : \mathbb{B}^{n+1} \to \mathbb{B}^{n+1}$ is a $K$-quasi-isometry for $K \geq 1$ if there is a constant $L \geq 0$ such that

$$\frac{1}{K}d(x, y) - L \leq d(f(x), f(y)) \leq Kd(x, y) + L$$

for any $x$ and $y$ in $\mathbb{B}^{n+1}$. Also, a 1-quasi-isometry is referred to as a rough isometry.

**Proposition 8.2.** Let $G'$ be a rough-isometric deformation of a Kleinian group $G$ of bounded type. Then $G'$ is also of bounded type.

**Proof.** Assume that $G'$ is obtained from $G$ by a rough-isometric automorphism $f : \mathbb{B}^{n+1} \to \mathbb{B}^{n+1}$ such that $G' = fGf^{-1}$. Given a uniformly distributed set $X$ of bounded type for $\Lambda(G)$ satisfying by definition

$$\frac{\#(X \cap B_R(x))}{\#(X \cap B_R(o))} \leq \rho$$

for every $x \in X$ and for every $R > 0$, we consider $X' = f(X)$, which may not be in the convex hull $H(\Lambda(G'))$ of $G'$. By composing, if necessary, with another rough-isometric automorphism $G'$ onto itself, we may assume that $X'$ is a uniformly distributed set in $H(\Lambda(G'))$. Since $f$ satisfies

$$d(x, y) - L \leq d(f(x), f(y)) \leq d(x, y) + L$$

for some $L \geq 0$, we have

$$\#(f(X) \cap B_R(f(x))) \leq \#(X \cap B_{R+L}(x));$$

$$\#(f(X) \cap B_R(f(o))) \geq \#(X \cap B_{R-L}(o)).$$
This implies that
\[
\frac{\#(f(X) \cap B_R(f(x)))}{\#(f(X) \cap B_R(fo))} \leq \frac{\#(X \cap B_{R+L}(x))}{\#(X \cap B_{R-L}(o))}
= \frac{\#(X \cap B_{R+L}(x))}{\#(X \cap B_{R+L}(o))} \cdot \frac{\#(X \cap B_{R-L}(o))}{\#(X \cap B_{R-L}(x))} \leq \rho c e^{2Ln}
\]
for some constant \( c > 0 \), which shows that \( X' = f(X) \) is of bounded type. \( \square \)

This observation leads us to the following problem.

**Problem 8.3.** Let \( G' \) be a quasi-isometric deformation of a Kleinian group \( G \) of bounded type. Is then \( G' \) also of bounded type?

So far, we have seen that the following classes of Kleinian groups \( G \) are of bounded type and hence satisfy \( \dim_H(\Lambda(G)) = h_c(\Lambda(G)) = \dim_B(\Lambda(G)) \):

1. Kleinian groups of the first kind \( (\Lambda(G) = S^n) \);
2. Convex cocompact Kleinian groups;
3. non-trivial normal subgroups of Kleinian groups of bounded type;
4. rough-isometric deformations of Kleinian groups of bounded type.

In what follows, we exhibit an example which does not belong to the above classes but still is of bounded type.

The construction of this example is based on the following theorem describing properties of the Diestel-Leader graph \( DL(m,n) \) for \( m, n \geq 2 \) and \( m \neq n \), which is proved by Eskin, Fisher and Whyte [20].

**Theorem 8.4.** There exists a locally finite graph \( G = (V,E) \) such that the group of isometries of \( G \) acts transitively on the vertex set \( V \) but \( G \) is not quasi-isometric to the Cayley graph of any finitely generated group.

We also need the following result, which is given by a similar argument to Proposition 8.2.

**Proposition 8.5.** Let \( X \) be a uniformly distributed set in the convex hull \( H(\Lambda) \) of a closed set \( \Lambda \subset S^n \). Assume that there exists a uniform constant \( L \geq 0 \) such that, for any two points \( x_1 \) and \( x_2 \) in \( X \), there is a rough-isometric automorphism \( f \) of \( B^{n+1} \) with additive constant \( L \) satisfying \( f(X) = X \) and \( f(x_1) = x_2 \). Then \( X \) is of bounded type.

**Proof.** For any two points \( x_1 \) and \( x_2 \) in \( X \), we have
\[
\#(X \cap B_R(x_2)) \leq \#(X \cap B_{R+L}(x_1)),
\]
and hence
\[
\frac{\#(X \cap B_R(x_2))}{\#(X \cap B_R(x_1))} \leq \frac{\#(X \cap B_{R+L}(x_1))}{\#(X \cap B_R(x_1))} \leq \rho c e^{Ln},
\]
where \( \rho \geq 1 \) and \( c > 0 \) are the same constants as in the proof of Proposition 8.2. This implies that \( X \) is of bounded type. \( \square \)

**Example 8.6.** We take a graph \( G \) as in Theorem 8.4 and let \( k \) be the valency of each vertex of \( G \). Consider a hyperbolic surface \( Q \) with \( k + 1 \) geodesic boundary components that is homeomorphic to a \((k+1)\)-holed sphere. One boundary component of \( Q \) is reserved for gluing a funnel (half annulus) and the other \( k \) components...
are used for the following construction tracing $\mathcal{G}$. Put a copy of $Q$ on each vertex of $\mathcal{G}$ and fit them together according to the structure of $\mathcal{G}$ by gluing adjacent geodesic boundaries of $Q$. The resulting hyperbolic surface is denoted by $S$. It is easy to see that $\mathcal{G}$ and the convex core $C(S)$ of $S$ are quasi-isometric to each other.

We first show that $S$ is not quasi-isometric to any normal cover of any convex compact surface, that is, a hyperbolic surface given by a convex cocompact Fuchsian group. Suppose to the contrary that $S$ is quasi-isometric to a normal cover $\Sigma$ of a convex compact surface $\hat{\Sigma}$. It follows that the convex cores $C(S)$ and $C(\Sigma)$ are quasi-isometric. Then $C(\Sigma)$ is quasi-isometric to the Cayley graph of the covering group isomorphic to $\pi_1(\hat{\Sigma})/\pi_1(\Sigma)$. Since $\pi_1(\hat{\Sigma})$ is finitely generated, so is $\pi_1(\hat{\Sigma})/\pi_1(\Sigma)$. This implies that $\mathcal{G}$ is quasi-isometric to the Cayley graph of a finitely generated group, which contradicts Theorem 8.4.

Represent $S = \mathbb{B}^2/G$ by a Fuchsian group $G$. Choose a point $\hat{x}$ in each $Q$ and let $X$ be the set of all such points $\hat{x}$ in $C(S)$. Then, define $X$ as the inverse image of $X$ under the universal cover $\mathbb{B}^2 \to S$, which is thus a uniformly distributed set in the convex hull $H(\Lambda(G))$. We will prove that there is a uniform constant $L \geq 0$ such that, for any two points $x_1$ and $x_2$ in $X$, there is a rough-isometry $f: \mathbb{B}^2 \to \mathbb{B}^2$ with additive constant $L$ satisfying $f(x_1) = x_2$. $f(X) = X$ and $fGf^{-1} = G$. Then, by Proposition 8.3, we see that $X$ is of bounded type, and hence $G$ is of bounded type. If $x_1$ and $x_2$ project to the same point in $X$ by the universal cover, then $f$ can be taken as an element of the covering group, which is an isometry of $\mathbb{B}^2$. Hence we may assume that $x_1$ and $x_2$ project to distinct points $\hat{x}_1$ and $\hat{x}_2$ in $\hat{X}$.

Let $v_1$ and $v_2$ be the vertices of $\mathcal{G}$ corresponding to $\hat{x}_1$ and $\hat{x}_2$ respectively. Since there is an isometry $\sigma$ of $\mathcal{G}$ sending $v_1$ to $v_2$, we can take a piecewise isometry $\hat{f}_v$ of $S$ preserving the structure of the union of $Q$ and mapping $\hat{x}_1$ to $\hat{x}_2$. Then we modify $\hat{f}_v$ to an automorphism $\hat{f} : S \to S$ so that the action on $\mathcal{G}$ induced by $\hat{f}$ is the same as $\sigma$. Actually, on each $Q \subset S$ associated with a vertex $v \in \mathcal{G}$ with the adjacent edges $\{e_1, \ldots, e_k\}$, the difference between $\sigma$ and $\hat{f}_v$ appears as a permutation of the set of edges $\{e_1, \ldots, e_k\}$. Hence we have only to modify $f_v$ to $\hat{f}$ on each $Q$ according to the permutation. Since the number of such permutations is finite, there is a uniform constant $K \geq 1$ such that the modified map $\hat{f}$ can be chosen as a $K$-quasi-isometry on each $Q$. We can find similar arguments in Bonfert-Taylor et al. [12]. Since the action on $\mathcal{G}$ induced by $\hat{f}$ is isometric, we see that such $\hat{f}$ is a rough-isometry with an additive constant $L$ depending only on $S$ and $K$. Lifting $\hat{f}$ to $\mathbb{B}^2$, we obtain the required rough-isometry $f$.

Although the above construction might give the impression that only some special Kleinian groups beside the ones in the previous list are of bounded type, we expect that there are a large number of such groups. We formulate our expectation as follows. Note that, if we want to allow a Kleinian group to have parabolic elements, we have to replace the bounded type condition with the weakly bounded type condition given in Definition 7.10. (A Kleinian group is of weakly bounded type if it has this property.)

**Conjecture 8.7.** If the convex hull $H(\Lambda(G))$ of the limit set of a Kleinian group $G$ of divergence type has the (weak) tightness property, then $G$ is of (weakly) bounded type.
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