AN IMPROVED BOUND FOR THE RIGIDITY OF LINEARLY CONSTRAINED FRAMEWORKS

BILL JACKSON, ANTHONY NIXON, AND SHIN-ICHI TANIGAWA

ABSTRACT. We consider the problem of characterising the generic rigidity of bar-joint frameworks in $\mathbb{R}^d$ in which each vertex is constrained to lie in a given affine subspace. The special case when $d = 2$ was previously solved by I. Streinu and L. Theran in 2010 and the case when each vertex is constrained to lie in an affine subspace of dimension $t$, and $d \geq t(t-1)$ was solved by Cruickshank, Guler and the first two authors in 2019. We extend the latter result by showing that the given characterisation holds whenever $d \geq 2t$.

1. Introduction

A (bar-joint) framework $(G, p)$ in $\mathbb{R}^d$ is the combination of a simple graph $G = (V, E)$ and a realisation $p : V \rightarrow \mathbb{R}^d$. The framework $(G, p)$ is rigid if every edge-length preserving continuous motion of the vertices arises as a congruence of $\mathbb{R}^d$.

It is NP-hard to determine whether a given framework is rigid [1], but this problem becomes more tractable when one considers the generic behaviour. It is known that the rigidity of a generic framework $(G, p)$ in $\mathbb{R}^d$ depends only on the underlying graph $G$, see [2]. We say that $G$ is rigid in $\mathbb{R}^d$ if some (and hence every) generic realisation of $G$ in $\mathbb{R}^d$ is rigid. The problem of characterising graphs which are rigid in $\mathbb{R}^d$ has been solved for $d = 1, 2$ but is open for all $d \geq 3$.

We will consider the problem of characterising the generic rigidity of bar-joint frameworks in $\mathbb{R}^d$ with additional constraints that require some vertices to lie in given affine subspaces. We model the underlying incidence structure of such a framework as a looped simple graph $G = (V, E, L)$ where the vertex set $V$ represents the joints, the edge set $E$ represents the distance constraints between pairs of distinct vertices and the loop set $L$ represents the subspace constraints on individual vertices. We will distinguish between edges and loops throughout the paper, an edge will always have two distinct end-vertices and a loop will always have two identical end-vertices.

Motivated by potential applications in sensor network localisation and in mechanical engineering, rigidity has already been considered for bar-joint frameworks with various kinds of additional constraints [3, 6, 9, 10]. Following [3], we define a linearly constrained framework in $\mathbb{R}^d$ to be a triple $(G, p, q)$ where $G = (V, E, L)$ is a looped simple graph, $p : V \rightarrow \mathbb{R}^d$ and $q : L \rightarrow \mathbb{R}^d$. For $v_i \in V$ and $\ell_j \in L$ we put $p(v_i) = p_i$ and $q(\ell_j) = q_j$. The framework $(G, p)$ is generic if $(p, q)$ is algebraically independent over $\mathbb{Q}$.

An infinitesimal motion of $(G, p, q)$ is a map $\dot{p} : V \rightarrow \mathbb{R}^d$ satisfying the system of linear equations:

\begin{align}
(p_i - p_j) \cdot (\dot{p}_i - \dot{p}_j) &= 0 \quad \text{for all } v_i v_j \in E \\
q_j \cdot \dot{p}_i &= 0 \quad \text{for all incident pairs } v_i \in V \text{ and } \ell_j \in L.
\end{align}

Date: February 26, 2021.

2010 Mathematics Subject Classification. 52C25, 05C10 and 53A05.

Key words and phrases. rigidity, linearly constrained framework, pinned framework, count matroid.
The second constraint implies that the infinitesimal velocity of each \(v_i \in V\) is constrained to lie on the hyperplane through \(p_i\) with normal vector \(q_j\) for each loop \(\ell_j\) incident to \(v_i\).

The *rigidity matrix* \(R(G, p, q)\) of the linearly constrained framework \((G, p, q)\) is the matrix of coefficients of this system of equations for the unknowns \(\dot{p}\). Thus \(R(G, p, q)\) is a \((|E| + |L|) \times d|V|\) matrix, in which: the row indexed by an edge \(v_iv_j \in E\) has \(p(u) - p(v)\) and \(p(v) - p(u)\) in the \(d\) columns indexed by \(v_i\) and \(v_j\), respectively and zeros elsewhere; the row indexed by a loop \(\ell_j = v_iv_i \in L\) has \(q_j\) in the \(d\) columns indexed by \(v_i\) and \(v_j\) elsewhere. The \(|E| \times d|V|\) sub-matrix consisting of the rows indexed by \(E\) is the *bar-joint rigidity matrix* \(R(G - L, p)\) of the bar-joint framework \((G - L, p)\).

The framework \((G, p, q)\) is *infinitesimally rigid* if its only infinitesimal motion is \(\dot{p} = 0\), or equivalently if rank \(R(G, p, q) = d|V|\). We say that the looped simple graph \(G\) is *rigid* in \(\mathbb{R}^d\) if rank \(R(G, p, q) = d|V|\) for some realisation \((G, p, q)\) in \(\mathbb{R}^d\), or equivalently if rank \(R(G, p, q) = d|V|\) for all generic realisations \((G, p, q)\) i.e. all realisations for which \((p, q)\) is algebraically independent over \(\mathbb{Q}\). Streinu and Theran [10] gave a complete characterisation of looped simple graphs which are rigid in \(\mathbb{R}^2\). Cruickshank et al. [3] extended their characterisation to higher dimensions for graphs in which each vertex is incident to sufficiently many loops. We need to introduce some terminology to describe this result.

Given a looped simple graph \(G = (V, E, L)\) and \(X \subseteq V\) let \(i(X)\) denote the number of edges and loops in the subgraph of \(G\) induced by \(X\). We say that \(G\) is \(k\)-sparse for some integer \(k \geq 1\), if \(i(X) \leq k|X|\) for all \(X \subseteq V\) and that \(G\) is \(k\)-tight if it is a \(k\)-sparse graph with \(|E \cup L| = k|V|\). Let \(G^{[k]}\) denote the graph obtained from \(G\) by adding \(k\) new loops at every vertex. The following conjecture is posed in [3].

**Conjecture 1.1** ([3]). Suppose \(G\) is a looped simple graph and \(d, t\) are positive integers with \(d \geq 2t\). Then \(G^{[d-t]}\) can be realised as an infinitesimally rigid linearly constrained framework in \(\mathbb{R}^d\) if and only if \(G\) has a \(t\)-tight looped simple spanning subgraph.

The main result of [3] verifies Conjecture 1.1 in the case when \(d \geq \max\{2t, t(t - 1)\}\). Our main result, Theorem 3.2 below, verifies Conjecture 1.1 completely and, in addition, extends the characterisation to the case when \(d = 2t - 1\).

### 2. PINNED INDEPENDENCE

Let \(G = (V, E)\) be a simple graph and \(P \subseteq V\). We will consider infinitesimal motions \(\dot{p}\) of a \(d\)-dimensional bar-joint framework \((G, p)\) in which the vertices in \(P\) are pinned i.e. \(\dot{p}(v) = 0\) for all \(v \in P\). Let \(R^{pin}(G, P, p)\) denote the submatrix obtained from the rigidity matrix \(R(G, p)\) by deleting the \(d\)-tuples of columns corresponding to vertices of \(P\). We say that \((G, P)\) is *pinned independent* in \(\mathbb{R}^d\) if the rows of \(R^{pin}(G, P, p)\) are linearly independent for any generic \(p\).

A graph \(G'\) is said to be obtained from another graph \(G\) by a *0-extension* if \(G = G' - v\) for a vertex \(v \in V(G')\) with \(d_{G'}(v) = d\), or a *1-extension* if \(G = G' - v + xy\) for a vertex \(v \in V(G')\) with \(d_{G'}(v) = d + 1\) and \(x, y \in N(v)\). We can use standard proof techniques to show that 0-extension and 1-extension preserve pinned independence, see for example [9].

**Lemma 2.1.** Let \((G, P)\) be pinned independent and let \((G', P)\) be obtained from \(G\) by a 0-extension or a 1-extension. Then \((G', P)\) is pinned independent.

We can use this lemma to obtain a sufficient condition for pinned independence. A looped simple graph is said to be *\(K_k\)-free* if it has no subgraph isomorphic to the complete graph \(K_k\).
Lemma 2.2. Let $G = (V, E)$ be a simple graph with $P \subseteq V$ and $d \geq 2$ be an integer. Construct a looped simple graph $G'$ from $G$ by adding $d$ loops to each vertex of $P$ and $\lfloor \frac{d}{2} \rfloor$ loops to each vertex of $V - P$. Suppose that $G'$ is $d$-sparse and $K_{d+2}$-free. Then $(G, P)$ is pinned independent in $\mathbb{R}^d$.

Note that if $d$ is even then the $d$-sparsity of $G'$ implies that $G'$ is $K_{d+2}$-free. Hence this assumption is only needed when $d$ is odd.

**Proof.** We prove the lemma by induction on $|V|$. The conclusion is trivial if $V = P$ or $|V| = 1$ so we may suppose not. Moreover we may assume $G$ is connected since the lemma holds for $G$ if and only if it holds for each connected component of $G$. Let $H$ be the graph obtained from $G'$ by deleting $\lfloor \frac{d}{2} \rfloor$ loops from every vertex. Then $H$ is $\lfloor \frac{d}{2} \rfloor$-sparse and hence the minimum degree of $H$ is at most $d + 1$. Furthermore, if the minimum degree of $H$ is equal to $d + 1$, then $d$ is odd, $H$ is $(d + 1)$-regular, $H$ has no loops, and hence $P = \emptyset$.

Let $v$ be a vertex of minimum degree in $H$. Since each vertex in $P$ has degree at least $d + 1$ in $H$ (by the connectivity of $G$), $v \in V - P$. Then $(G - v)' = G' - v$ satisfies the hypotheses of the lemma and hence $(G - v, P)$ is pinned independent in $\mathbb{R}^d$ by induction. If $d_H(v) \leq d$, then $G$ can obtained from $G - v$ by a 0-extension and Lemma 2.1 implies that $(G, P)$ is pinned independent. Hence we may suppose that $d_H(v) = d + 1$. As noted above, this implies that $d$ is odd, $H$ is $(d + 1)$-regular and $P = \emptyset$. This gives $H = G$ and $G$ is $(d + 1)$-regular.

We will show that $G - v + xy$ satisfies the hypotheses of the lemma for two non-adjacent neighbours $x, y$ of $v$ in $G$. Since $P = \emptyset$, this is equivalent to showing that $G - v + xy$ is $\frac{d+1}{2}$-sparse and has no $K_{d+2}$-subgraph. Since $G$ is $K_{d+2}$-free, we may choose $x, y \in N(v)$ such that $xy \notin E$. Since $G$ is connected and $(d + 1)$-regular, we have $i(X) < \frac{d+1}{2} |X|$ for all $X \subseteq V$ and hence $G - v + xy$ is $\frac{d+1}{2}$-sparse. Suppose $G - v + xy$ contains a subgraph $K$ isomorphic to $K_{d+2}$. Then $x, y \in V(K)$. Choose $z \in N(v) - \{x, y\}$. The fact that $G$ is $(d+1)$-regular implies that $z \notin V(K)$, $N(x) \cap N(z) = \{v\}$ and $xz \notin E$. We can now deduce that $G - v + xz$ is $\frac{d+1}{2}$-sparse and has no $K_{d+2}$-subgraph.

By induction $G - v + xz$ is (pinned) independent in $\mathbb{R}^d$. Since $G$ is obtained from $G - v + xz$ by a 1-extension, $G$ is (pinned) independent by Lemma 2.1. This completes the proof. \qed

3. Linearity constrained rigidity

Let $(K_{n}^{[d+1]}, p, q)$ be a generic $d$-dimensional realization of the complete graph on $n$ vertices with $d + 1$ loops on each vertex. Since each edge/loop of $K_{n}^{[d+1]}$ is associated with a row of $R(K_{n}^{[d+1]}, p, q)$, we can define a matroid on the union of the edge set and the loop set of $K_{n}^{[d+1]}$ by the linear independence of the row vectors of $R(K_{n}^{[d+1]}, p, q)$. This matroid is called the generic linearly constrained rigidity matroid $\mathcal{R}_{d,n}$. A looped simple graph $G = (V, E, L)$ with $n$ vertices is said to be an $\mathcal{R}_{d}$-circuit if $E \cup L$ is a circuit in $\mathcal{R}_{d,n}$.

We first derive a rather surprising result concerning the infinitesimal motions of an arbitrary linearly constrained framework in $\mathbb{R}^d$.

**Lemma 3.1.** Let $(G, p, q)$ be a generic linearly constrained framework in $\mathbb{R}^d$. Suppose that $v$ is a vertex of $G$ and rank $R(G, p, q) = \text{rank} R(G - \ell, p, q)$ for some loop $\ell$ incident to $v$. Then $\dot{p}(v) = 0$ for every infinitesimal motion $\dot{p}$ of $(G, p, q)$.

**Proof.** Let $G = (V, E, L)$. We proceed by induction on $|E|$. The hypothesis that rank$(G, p, q) = \text{rank}(G - \ell, p, q)$ implies that $\ell$ is contained in some $\mathcal{R}_{d}$-circuit $C$ in $G$. If $C \neq G$ then we can apply induction to $(C, p|_{V(C)}, q|_{V(C)})$ to deduce that $\dot{p}(v) = 0$. Hence we may suppose
If $v$ is incident with $d$ loops then $v$ is fixed in every infinitesimal motion of $(G, p, q)$ so we may suppose $v$ is incident to at most $d - 1$ loops. Since $G$ is a $\mathcal{R}_d$-circuit, this implies that $v$ is incident to an edge $e \in E$.

Let $G^+$ be the looped simple graph obtained from $G$ by adding a new loop $\ell^*$ at $v$ and put $G^* = G^+ - \ell$. Then $G$ and $G^*$ are isomorphic so are both $\mathcal{R}_d$-circuits in the linearly constrained rigidity matroid of $G^+$. Since $e$ is a common edge of $G$ and $G^*$, we can apply the matroid circuit exchange axiom to deduce that there exists a third $\mathcal{R}_d$-circuit $G' \subseteq G^+ - e$. Since $G$ and $G^*$ are $\mathcal{R}_d$-circuits, $\ell$ and $\ell^*$ are both loops in $G'$. Since $|E(G')| < |E|$, we can apply induction to deduce that $v$ is fixed in every infinitesimal motion of any generic realisation $(G', p', q')$ of $G'$. Since $G'$ is a $\mathcal{R}_d$-circuit and $\ell^* \in L(G')$, the space of infinitesimal motions of $(G', p', q')$ and $(G' - \ell^*, p', q'|_{L(G')-\ell^*})$ are the same and hence $v$ is fixed in every infinitesimal motion of any generic realisation of $G' - \ell^*$. Since $G' - \ell^* \subseteq G$, the same conclusion holds for $G$.

We next use Lemmas 2.2 and 3.1 to characterise independence for generic linearly constrained frameworks in $\mathbb{R}^d$ when each vertex is incident with sufficiently many loops.

Theorem 3.2. Suppose $d \geq 2$ is an integer and $G = (V, E, L)$ is a looped simple graph with the property that every vertex of $G$ is incident with at least $\left\lceil \frac{d}{2} \right\rceil$ loops. Then $G$ is independent in $\mathbb{R}^d$ if and only if $G$ is $d$-sparse and $K_{d+2}$-free.

Proof. To prove the necessity we suppose that $G$ is independent in $\mathbb{R}^d$. Then every subgraph $G' = (V', E', L')$ of $G$ is independent in $\mathbb{R}^d$. This implies that $|E' \cup L'| \leq d|V'|$ (since the rows of $R(G', p', q')$ are linearly independent for any generic realisation $(G', p', q')$ of $G'$), and $G' \neq K_{d+2}$ (since $K_{d+2}$ is dependent as a bar-joint framework in $\mathbb{R}^d$). Hence $G$ is $d$-sparse and $K_{d+2}$-free.

To prove sufficiency, we suppose that $G$ is $d$-sparse and $K_{d+2}$-free. We show that $G$ is independent in $\mathbb{R}^d$ by induction on $|V| + |E|$. The cases when $|V| = 1$ and when $G$ is disconnected are straightforward so we assume that $|V| \geq 2$ and $G$ is connected.

We next consider the case when $G$ has a $d$-tight proper subgraph $H$, where $H$ is said to be proper if it is connected and $1 < |V(H)| < |V|$. (Note that each connected component of a disconnected graph is a $d$-tight proper subgraph.) The hypothesis that $G$ is $d$-sparse implies that $H$ is a proper subgraph of $G$ so every vertex of $H$ is incident with at least $\left\lceil \frac{d}{2} \right\rceil$ loops. We can now use induction to deduce that $H$ is minimally rigid. Construct a new graph $G'$ from $G$ by replacing $H$ with another $d$-tight subgraph $H'$ on the same vertex set which has $d$ loops at each vertex and no edges. It is not difficult to see that replacing the $d$-tight subgraph $H$ by the $d$-tight subgraph $H'$ preserves $d$-sparsity and does not create a copy of $K_{d+2}$, so $G'$ satisfies the hypotheses of the theorem. Furthermore, since $H$ is a connected graph on at least two vertices, $H$ contains at least one edge and hence we can apply induction to deduce that $G'$ is independent in $\mathbb{R}^d$. Since replacing the minimally rigid subgraph $H'$ of $G'$ by the minimally rigid subgraph $H$ will not change independence$^1$, $G$ is independent in $\mathbb{R}^d$.

It remains to consider the case when $G$ has no $d$-tight proper subgraph. We assume, for a contradiction, that $G$ is not independent in $\mathbb{R}^d$. Then $G$ has a subgraph $C$ which is an $\mathcal{R}_d$-circuit. We next use the same trick as in the proof of Lemma 3.1 to show that every vertex of $C$ which is incident to a loop in $C$ must be incident to $d$ loops in $G$.

Suppose $v$ is incident to a loop $\ell$ in $C$, but not incident to $d$ loops in $G$. Let $G^+$ be the looped simple graph obtained from $G$ by adding a new loop $\ell^*$ at $v$, and let $C^* = C - \ell + \ell^*$.

\*1This follows because $(G, p)$ and $(G', p)$ will have the same space of infinitesimal motions for any generic $p$, since both $H$ and $H'$ will constrain every infinitesimal motion to be zero on $V(H) = V(H')$.,
We can show, as in the proof of Lemma 3.1, that there exists an \( \mathcal{R}_d \)-circuit \( C' \subset C \cup C^* \subset G^+ \) which does not contain a given edge \( e \) incident to \( v \) in \( C \). The assumptions that \( G \) has no \( d \)-tight proper subgraph and \( v \) is not incident to \( d \) loops in \( G \) imply that \( G^+ - e \) is \( d \)-sparse. Since \( G^+ - e \) is \( K_{d+2} \)-free, has at least \( \lfloor \frac{d}{2} \rfloor \) loops at each vertex and has fewer edges than \( G \), we may apply induction to deduce that \( G^+ - e \) is independent in \( \mathbb{R}^d \). This contradicts the fact that \( G^+ - e \) contains the \( \mathcal{R}_d \)-circuit \( C' \). Hence, every vertex of \( G \) which is incident to a loop in \( C \) must be incident to \( d \) loops in \( G \).

Let \( H = C - L(C) \) be the underlying simple graph of \( C \) and \( P \) be the set of all vertices in \( C \) which are incident to at least one loop in \( C \). Let \( H' \) be obtained from \( H \) by adding \( d \) loops at each vertex in \( P \) and \( \lfloor \frac{d}{2} \rfloor \) loops at each vertex of \( V(C) \setminus P \). Then \( H' \) is a subgraph of \( G \) so is \( d \)-sparse and \( K_{d+2} \)-free. We can now use Lemma 2.2 to deduce that \( (H, P) \) is pinned independent in \( \mathbb{R}^d \) so \( R_{pin}(H, P, p) \) has linearly independent rows for any generic \( p \). We now compare \( R_{pin}(H, P, p) \) and \( R(C, p, q) \), for some generic \( q \). Since \( P \) is the set of vertices of \( C \) which are incident with a loop in \( C \), \( R(C, p, q) \) has the block structure

\[
\begin{bmatrix}
P & \quad & V(C) \setminus P \\
E(C) & \ast & R_{pin}(H, P, p) \\
L(C) & \ast & 0
\end{bmatrix}.
\]

The row independence of \( R_{pin}(H, P, p) \) now implies that every linear combination of the rows of \( R(C, p, q) \) which sums to zero will have zero coefficients for the rows indexed by \( E(C) \). This contradicts the fact that \( C \) is an \( \mathcal{R}_d \)-circuit.

Theorem 3.2 can be restated as a characterisation of rigidity.

**Theorem 3.3.** Suppose \( d \geq 2 \) is an integer and \( G \) is a looped simple graph with the property that every vertex of \( G \) is incident with at least \( \lfloor \frac{d}{2} \rfloor \) loops. Then \( G \) is rigid in \( \mathbb{R}^d \) if and only if \( G \) has a spanning, \( d \)-tight, \( K_{d+2} \)-free subgraph \( H \) with the property that every vertex of \( H \) is incident with at least \( \lfloor \frac{d}{2} \rfloor + 2 \) loops.

**Proof.** If \( G \) has a spanning subgraph \( H \) with the properties listed in the theorem then \( H \) will be rigid in \( \mathbb{R}^d \) by Theorem 3.2. On the other hand, if \( G \) is rigid in \( \mathbb{R}^d \), then we can choose an independent spanning subgraph \( H' \) of \( G \) with no edges and \( \lfloor \frac{d}{2} \rfloor \) loops at each vertex, and then extend \( H' \) to a minimally rigid spanning subgraph \( H \) of \( G \). Then \( H \) will be independent and rigid so will be \( d \)-tight and \( K_{d+2} \)-free.

\[\square\]

4. **Open questions**

We close by mentioning two further problems for linearly constrained frameworks in \( \mathbb{R}^d \) which are solved for \( d = 2 \) but open when \( d \geq 3 \).

1. The characterisation of rigidity for generic linear constrained frameworks in \( \mathbb{R}^2 \) was extended in [4, 6] by allowing the linear constraints to be non-generic. It would be of interest to extend Theorem 3.3 in the same way. Notice that non-generic linear constraints arise naturally when considering rigidity for frameworks in \( \mathbb{R}^d \) under the additional constraint that the vertices should lie on a smooth algebraic variety \( V \). The case when \( V \) is 2-dimensional, \( d = 3 \) and the loops constrain \( G \) to lie on \( V \) was considered in [7, 8].

2. A linearly constrained frameworks \((G, p, q)\) in \( \mathbb{R}^d \) is **globally rigid** if it is the only realisation of \( G \) in \( \mathbb{R}^d \) which satisfies the same distance and linear constraints as \((G, p, q)\). It was proved in [5] that a linearly constrained framework \((G, p, q)\) in \( \mathbb{R}^2 \) is globally rigid if and only if every connected component \( H \) of \( G \) is either a single vertex with at least 2 loops, or is redundantly rigid (i.e. \( H - f \) is rigid in \( \mathbb{R}^2 \) for all edges and loops \( f \) of \( H \)) and
'2-balanced'. It seems likely that this result can be extended to higher dimensional linearly constrained frameworks when each vertex is incident to sufficiently many linear constraints. More precisely we conjecture that, if \((G, p, q)\) is a generic linearly constrained framework with at least two vertices in \(\mathbb{R}^d\) and every vertex of \(G\) is incident with at least \(\lfloor \frac{d}{2} \rfloor\) loops, then \((G, p, q)\) is globally rigid if and only if every connected component of \(G\) is either a single vertex with at least \(d\) loops, or is redundantly rigid in \(\mathbb{R}^d\). (The necessary condition from [5] that \(G\) should be ‘\(d\)-balanced’ follows from the assumption that every vertex of \(G\) is incident with at least \(\lfloor \frac{d}{2} \rfloor\) loops.)

**Acknowledgements.** We would like to thank the Heilbronn Institute for Mathematical Research for providing partial financial support for this research and the referee for their careful reading and helpful comments on the submitted version of this paper. The third author was supported by JST ERATO Grant Number JPMJER1903 and JSPS KAKENHI Grant Number JP18K11155.

**REFERENCES**

[1] T. Abbott, Generalizations of Kempe’s universality theorem, Master’s thesis, Massachusetts Institute of Technology (2008).

[2] L. Asimow and B. Roth, The rigidity of graphs, Transactions of the American Mathematical Society, 245 (1978) 279–289.

[3] J. Cruickshank, H. Guler, B. Jackson and A. Nixon, Rigidity of linearly constrained frameworks, International Mathematics Research Notices, 2020:12 (2020) 3824–3840.

[4] Y. Eftekhari, B. Jackson, A. Nixon, B. Schulze, S. Tanigawa and W. Whiteley, Point-hyperplane frameworks, slider joints, and rigidity preserving transformations, Journal of Combinatorial Theory: Series B, 135 (2019) 44–74.

[5] H. Guler, B. Jackson and A. Nixon, Global rigidity of 2-dimensional linearly constrained frameworks, International Mathematics Research Notices, rnaa157, available online, https://doi.org/10.1093/imrn/rnaa157, 2020

[6] N. Katoh and S. Tanigawa, Rooted-tree decompositions with matroid constraints and the infinitesimal rigidity of frameworks with boundaries, SIAM Journal on Discrete Mathematics, 27:1 (2013) 155–185.

[7] A. Nixon, J. Owen and S. Power, Rigidity of frameworks supported on surfaces, SIAM Journal on Discrete Mathematics 26 (2012), no. 4, 1733–1757.

[8] A. Nixon, J. Owen and S. Power, A characterization of generically rigid frameworks on surfaces of revolution, SIAM Journal on Discrete Mathematics 28 (2014), no. 4, 2008–2028.

[9] B. Servatius, O. Shai, and W. Whiteley, Combinatorial characterization of the Assur graphs from engineering, European Journal of Combinatorics, 31 (2010) 1091–1104.

[10] I. Streinu and L. Theran, Slider-pinning rigidity: a Maxwell-Laman-type theorem, Discrete and Computational Geometry, 44 (2010) 812–837.

School of Mathematical Sciences, Queen Mary University of London, Mile End Road, London, E1 4NS, U.K.

E-mail address: b.jackson@qmul.ac.uk

Department of Mathematics and Statistics, Lancaster University, Lancaster, LA1 4YF, U.K.

E-mail address: a.nixon@lancaster.ac.uk

Department of Mathematical Informatics, Graduate School of Information Science and Technology, University of Tokyo, 7-3-1 Hongo, Bunkyo-ku, 113-8656, Tokyo, Japan

E-mail address: tanigawa@mist.i.u-tokyo.ac.jp