Heat transfer enhancement and reduction by polymer additives in turbulent Rayleigh Benard convection

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This letter confirms the existence of heat transfer enhancement (HTE) and reduction (HTR) in turbulent natural convection with polymer additives. HTE and HTR were numerically predicted by Benzi et al. (PRL, 104 024502, 2010) in homogenous turbulent convection, but experiments by Ahlers & Nikolaenko (PRL, 104 034503, 2010) in turbulent natural convection observed HTR only. Using direct numerical simulation of natural convection, the present study reconciles earlier numerical and experimental work on the basis of the dominant role of polymer length in the polymer dynamics in extensional flows.

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In the turbulence research community, high-molecular weight polymer additives are well known for their ability to reduce turbulent drag\cite{1,2}. Their effect on turbulent heat transport is far less documented, even though polymer solutions may be of interest in the management of heat transfer via turbulence control. A recent experimental study\cite{3} demonstrated that dilute solutions of polymers have the ability to produce heat transfer reduction (HTR). A direct numerical simulation, and shell polymer solutions may be of interest in the management of turbulent heat transport is far less documented, even though weight polymer additives are well known for their ability to the Newtonian solvent heat transfer under the same temperature conditions that lead to HTE or HTR.

Turbulent natural convection flows are simulated in a cartesian domain defined by the orthonormal vector base \( \mathbf{e}_x, \mathbf{e}_y, \mathbf{e}_z \) where \( x, y \) and \( z \) are the two horizontal directions and the vertical direction, respectively. The components of the velocity vector \( \mathbf{u} \) are \( u, v, \) and \( w \) and are normalized by the free-fall velocity, or convection velocity \( U_c = \sqrt{\alpha g H \Delta} \), where \( \alpha, \gamma, H \) and \( \Delta \) the fluid’s coefficient expansion, gravity, distance between the two no-slip, isothermal, horizontal walls, and the temperature difference between the bottom (hot) and top (cold) walls. In all simulations, \( H = 1 \) and \( \Delta = 1 \). The Rayleigh number, ratio of buoyancy forces to thermal and momentum diffusive forces, \( Ra = \alpha g H^3 \Delta / (\nu \kappa) \) is low, \( Ra = 10^3 \), yet within the turbulent regime. The kinematic viscosity and thermal diffusivity of the solvent are identified as \( \nu \) and \( \kappa \), respectively. The Prandtl number is also fixed, \( Pr = \nu / \kappa = 7 \) which is realistic for water. The Reynolds number based on \( U_c \) and \( H \) is therefore \( Re = Ra^{1/2} Pr^{-1/2} = 119 \). The flow is incompressible (\( \mathbf{\nabla} \cdot \mathbf{u} = 0 \)), periodic in horizontal directions and the buoyancy effect is simulated using the Boussinesq approximation, with the following transport equations for velocity, pressure \( p \) and temperature \( \theta \) and temperature fluctuations \( \theta’ \) around the hydrostatic temperature profile:

\[
\frac{\partial \mathbf{u}}{\partial t} + (\mathbf{u} \cdot \mathbf{\nabla})\mathbf{u} = -\mathbf{\nabla}p + \nu \mathbf{\nabla}^2 \mathbf{u} + \frac{1 - \beta}{Re} \mathbf{\nabla} \cdot \mathbf{T} \tag{1}
\]

\[
\frac{\partial \theta}{\partial t} + (\mathbf{u} \cdot \mathbf{\nabla})\theta = \frac{1}{Pr Re} \mathbf{\nabla}^2 \theta \tag{2}
\]

The parameter \( \beta \) is the ratio of solvent viscosity to the zero-shear viscosity of the polymer solution and affects both the viscous stress and polymer stress terms in Eq. (1). The polymer stress tensor \( \mathbf{T} \) is computed using the FENE-P (Finite Elastic Non-linear Extensibility-Peterlin) model:

\[
\mathbf{T} = \frac{1}{We} \left( C \frac{\mathbf{C}}{1 - \text{tr}(\mathbf{C})/L^2} - \mathbf{I} \right) \tag{3}
\]

where the tensor \( \mathbf{C} \) is the local conformation tensor of the polymer solution and \( \mathbf{I} \) is the unit tensor. The properties of the polymer solution are \( \beta \), the relaxation time,
Here based on the convection scales \( (We = λU_c/H) \) and the maximum polymer extension \( L \). The FENE-P model assumes that polymers may be represented by a pair of beads connected by a non-linear spring and defined by the end-to-end vector \( q \). The conformation tensor is the phase-average of the tensorial product of the end-to-end vector \( q \) with itself, \( C = (q ⊗ q) \) whose transport equation is

\[
\frac{∂C}{∂t} + (∂u ∇)C = C(∇u) + (∇u)^T C − T
\]  

(4)

On the lhs. of Eq. (4), the first two terms are responsible for the stretching of polymers by hydrodynamic forces, while the third term models the internal energy that tends to bring stretch polymers to their least energetic state (coiled). The FENE-P model has demonstrated its ability to capture the physics of polymer drag reduction\[2,5\]. In the present work, we make the further assumption that the thermal conductivity is independent of the polymer concentration, which should be reasonable within the dilute approximation.

Eqs. (1,4) are solved using finite differences on a staggered grid, following\[6\]. The code has been validated against existing databases of turbulent channel flows and natural convection simulations\[6\]. All simulations are performed in a computational domain of dimensions \( 8H × 8H × H \) and resolution \( 128 × 128 × 129 \). The Newtonian, HTE= +10% \( (L = 25, \ We = 10) \), and HTR= −30% were repeated on domains with twice the spatial resolution and also doubled lateral dimensions with virtually no change in heat transfer.

In Fig. 1 several simulations were used to map the heat transfer response of a wide range of relaxation time \( 0.1 ≤ We ≤ 45 \), and polymer lengths \( L = 10, 25, 50, 100 \) with a few additional simulations for \( L = 15, 20, 30, 40 \) at \( We = 10 \) and \( L = 25, 40 \) at \( We = 40 \). Simulations at higher \( We \) were found to require smaller time and space resolutions and will be discussed in subsequent publications. As predicted by the shell model of Benzi et al.\[3\], HTE is observed at low \( We \) for nearly all polymer lengths (except for \( L = 100 \)), yet the present simulated enhancement (HTE= +12% for \( L = 25 \) and \( We = 10 \)) is much more modest than the maximum observed in Benzi et al.’s shell model of homogenous convection, \( Nu/Nu_s ≈ 6 \), or their DNS where \( Nu/Nu_s ≈ 2.4 \) with \( L = 30 \). The absence of walls appears therefore to magnify the HTE ability of viscoelastic thermal convection flows. Fig. 1 also highlights the critical role of the polymer length on the heat transfer performance. Long polymers, \( L ≥ 50 \), show hardly any HTE. For the range of \( We \) considered, the short polymer simulations show a decrease of the HTE effect, yet do not reach HTR for the range of considered \( We \). The two HTR flows exhibit a power-law behavior at high \( We \), with \( Nu ∝ We^{−0.1} \) and \( We^{−0.2} \), for \( L = 50 \) and 100, respectively. Although this result indicates a dependence of the power law exponent in \( L \), the limited available data does not allow for a definitive conclusion. Combining the shell model and the scaling theory of Grossmann and Lohse\[7\], Benzi et al.\[3\] predicted the HTR behavior to \( Nu ∝ We^{−1} \). Since the shell model prediction were performed at much higher Rayleigh numbers, it may be assumed that Benzi’s work may describe an asymptotic behavior of HTR.

The topological differences between Newtonian, HTE and HTR flows are depicted in Fig. 2. The shape of convection cells is identified by the ridges observed in an instantaneous isotherm at \( θ = 0.85 \). For the Newtonian flow, these ridges are highlighted by contours of \( λ^* = max|λ_{ir}\|, λ_{ir} \) is the real part of the eigenvalues of the velocity gradient tensor \( ∇u \). Terrapon et al.\[9\] introduced \( λ^* \) as a measure of the ability of turbulent flows to stretch polymer molecules. It should be noted that regions of large \( λ^* \) are also regions or uni- or biaxial-extensional flows\[10\]. For viscoelastic flows, the isotherm is colored by the local polymer stretch, calculated as \( tr(C)/L^2 \). The topology of convection cells is dramatically modified by the presence of the polymers, with the emergence of highly organized convection cells. The typical horizontal length scale of convection cells is measured using the first negative minimum of the radial correlation function of vertical velocity fluctuations in planes parallel to the walls (not shown). This length scale drops from 3.2 in the Newtonian flow to 0.87 in the HTR flow and 0.7 in the HTE flow. The structure of regions of rotation-dominated flows is shown by positive isosurfaces of the second invariant \( Q \) of the velocity gradient tensor\[8\]. The \( Q \)-criterion is sensitive to the intensity of vortices and is adjusted to identify vortical structures in the core of the Newtonian flows with \( Q = 0.1 \), arising from shear layer instability in plumes. Such small scales vortices are absent in the HTE flow, and, with a much lower threshold \( Q = 0.01 \), the structure of convection cells is isolated. The vertical slice of polymer stretch contours shown in Fig. 2 indicates sustained stretching over most of the plumes’ vertical extent. The absence of core tur-
instability at large $We$ and $L$, which is the likely cause of the observed small scales. Since the initial study suggests that this instability is not a major component of the HTR mechanism, this matter will be discussed in a future publication. Lastly, Fig. 2 shows much lower polymer stretch in the boundary layers of HTE convection cells than HTR.

Fig. 3 plots the vertical distributions of the rms of temperature, horizontal and streamwise velocity fluctuations. The respective thickness of the momentum $δ_u$ and thermal $δ_θ$ boundary layers is estimated by the altitude of the maxima of $u_{rms}$ and $θ_{rms}$. Newtonian and HTE temperature and vertical velocity fluctuations are very close, especially in the boundary layer region. The main difference is observed in the horizontal velocity, with a reduction of $δ_u$ ($δ_u^{HTE} ≈ 0.12 < δ_0 ≈ 0.14 < δ_u^{Newt} ≈ 0.18$) and a reduction of velocity magnitude. The HTR flow significantly departs from the Newtonian flow for all quantities shown in Fig. 3. The momentum thickness in HTR and HTE flows leads to convection cell-driven flows which is reflected in the fact that $w_{rms} ≈ 2 \times u_{rms}$, or the intensity of plume velocity fluctuations are the sum of velocity fluctuations in the boundary layers of two adjacent convection cells.

Fig. 4 relates the heat flux $(wθ)_z = κΔ/H(Nu − 1)$ to the elastic energy $\langle ε^p \rangle_z = (u \cdot ((1−β)/Ra \nabla \cdot T))_z$, where $\langle \cdot \rangle_z$ denotes the averaging over time and homogenous direction at altitude $z$. Following Grossmann & Lohse [7], the focus of the discussion is the relation:

$$\frac{v^3}{H}(Nu − 1)RaPr^{−2} = \langle ε^u \rangle_V + \langle ε^p \rangle_V − \langle ε^θ \rangle_V$$

where $ε^u$ is the TKE dissipation rate, $\langle \cdot \rangle_V$ the averaging
over time and the entire flow volume, and the subscripts \(bl\) and \(pl\) denotes the respective contribution of boundary layers and plumes. For clarity, Fig. 4 plots only \(-\langle \varepsilon_p \rangle_{bl} \), \(-\langle \varepsilon_p \rangle_{pl} \), calculated from the horizontal and vertical contributions of \(\varepsilon_p\). In the HTE flow, the volume average of the plume elastic energy, \(-\langle \varepsilon_p \rangle_{V} = 0.86\) dominates that of boundary layers \(-\langle \varepsilon_p \rangle_{V} = 0.17\). The HTR flow shows the inverse behavior with \(-\langle \varepsilon_p \rangle_{V} = 0.32\) and \(-\langle \varepsilon_p \rangle_{V} = 0.46\). The explanation for the different distribution of elastic energy is first found in plumes. The Newtonian flow, via contours of \(\lambda^*\), shows that the base of plumes hosts the largest extensional velocity gradients, and polymeric fluids indeed exhibit the most stretch in these regions (Fig. 2). As polymers travel in the plume, the velocity gradient drops rapidly, similar to the relaxation of a stretched polymer arising from the sudden cancellation of an extensional flow studied by Doyle et al.\[12\]. These authors demonstrated that the first normal stress decreases at a rate of \(L^2 \sqrt{\tau} / t\). Replacing time by travel distance in the plume, this decay rate can be observed in the vertical slice of the contours of \(\tau(C) / L^2\) of Fig. 2, showing much more rapid relaxation in HTR than HTE. Short polymers are therefore able to sustain larger contributions over longer plume lengths. The second difference is the significant stretch in boundary layers at HTR, while almost negligible at HTE. The negative (positive) elastic contribution of \(-\langle \varepsilon_p \rangle_{bl} \) for \(z/H + 1/2 > 0.01\) is the result of a large increase of extensional viscosity driven by accelerating fluid in this region. Below the extensional region, boundary layers are shear dominated and thus experience the effect of shear thinning as shown by positive (negative) elastic contribution of \(-\langle \varepsilon_p \rangle_{bl} \). Extensional viscosity for a FENE-P fluid increases dramatically with increasing \(L\) and \(Ra\[13\], which leads to the reduction of horizontal velocity fluctuations in the HTR flow (Fig. 3).

In conclusion, the commonality in the present HTE and HTR flows is the absence of core turbulence, which implies that both flows are driven by convection cells alone. The present HTE simulations and the homogeneous convection simulations of Benzi et al.\[4\] demonstrate that the interactions of polymers with plumes is inherently of HTE nature for short polymer length. Long polymers, via extensional viscosity in boundary layers and rapid relaxation in plumes, cause HTR as observed in Ahlers & Nikolaenko\[3\]’s experiment with high molecular weight polymers at much higher Rayleigh numbers. The extrapolation of the proposed models to high Reynolds number should be valid on the basis that polymers have been shown to reduce turbulence intensity and mixing in free shear\[14\] and isotropic\[15\] turbulence, which should be the dominant flow patterns in core turbulence of natural convection at high \(Ra\).

Acknowledgments

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