Linear Scaling Solution of the Time-Dependent Self-Consistent-Field Equations

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A new approach to solving the Time-Dependent Self-Consistent-Field equations is developed based on the double quotient formulation of Tsiper [J. Phys. B, 34 L401 (2001)]. Dual channel, quasi-independent non-linear optimization of these quotients is found to yield convergence rates approaching those of the best case (single channel) Tamm-Dancoff approximation. This formulation is variational with respect to matrix truncation, admitting linear scaling solution of the matrix-eigenvalue problem, which is demonstrated for bulk excitons in the polyphenylene vinylene oligomer and the (4,3) carbon nanotube segment.

The Time-Dependent Self-Consistent-Field equations together with models that include some portion of the Hartree-Fock (HF) exchange admit control over the range of self-interaction in the optical response and are related to new models of electron correlation based on the Random Phase Approximation (RPA), as shown by Tamar and Udagawa [17] and extended by Narita and Shibuya with second order optimization of the quotients based on the Hermitian matrix $G$ to position and momentum. This picture avoids the imbalance between superoperator and functional notation is of reduced dimensionality in the MO representation.

Several TD-SCF eigensolvers are based on the oscillator picture

$$\begin{pmatrix} A & B \\ -B & -A \end{pmatrix} \begin{pmatrix} X \\ Y \end{pmatrix} = \omega \begin{pmatrix} X \\ Y \end{pmatrix},$$

where $A$ and $B$ are Hermitian blocks corresponding to $4^{th}$ order tensors spanning transitions between occupied and virtual sub-spaces, $\omega$ is the real excitation energy and $\vec{\omega} = (\vec{X}, \vec{Y})$ is the corresponding transition density. By construction, the MO representation allows strict separation between the dyadic particle-hole ($ph$) and hole-particle ($hp$) solutions, $X^T$ and $Y^T$, for which specialized algorithms exist. Nevertheless, convergence of the naive $J$-symmetric problem is typically much slower than the corresponding Hermitian Tamm-Dancoff approximation (TDA), $A^T X = \omega X$, which is of reduced dimensionality in the MO representation.

Recent efforts have focused on addressing the problem of dimensionality by employing linear scaling methods that reduce the cost of $L[\vec{v}]$ within Density Functional Theory (DFT) to $O(N)$. However, this remains an open problem for the Hartree-Fock (HF) exchange, an ingredient in models that account for charge transfer in the dynamic and static response, including the Random Phase Approximation (RPA) at the pure HF level of theory. Likewise, scaling of the TD-SCF eigenproblem remains formidable due to associated costs of linear algebra, even when using powerful Krylov subspace methods. Underscoring this challenge, one of the most successful approaches to linear scaling TD-DFT avoids the matrix eigenproblem entirely through explicit time-evolution, this decay leads to sparse matrices and $O(N^{2/3})$ complexity at.

Linear scaling matrix methods exploit quantum locality, manifest in approximate exponential decay of matrix elements expressed in a well posed, local basis; with the dropping of small elements below a threshold, $\tau_{mix}$, this decay leads to sparse matrices and $O(N)$ complexity at the forfeit of full precision. Likewise, linear scaling methods for computing the HF exchange employ an advanced form of direct SCF, exploiting this decay with $\tau_{mix}$.
An alternative is Rayleigh Quotient Iteration (RQI), which poses the eigenproblem as non-linear optimization and is variational with respect to matrix perturbation. TINC found that matrix perturbation (a truncation proxy) disrupts convergence of Krylov solvers with slow convergence, i.e. Lanczos and Arnoldi for the RPA, but has less impact on solvers with rapid convergence, i.e. generically for the TDA or Davidson for the RPA. Relative to semi-empirical Hamiltonians, the impact of incompleteness on subspace iteration may be amplified with first principles models and large basis sets (ill-conditioning).

This framework provides the freedom to work in any orthogonal representation, and to switch between transition density and oscillator duals with minimal cost.

QUIRQI is given in Algorithm 1. It begins with a guess for the transition density, which is then split into its dual (lines 2-3). The choice of initial guess is discussed later. Lines 4-24 consist of the non-linear conjugate gradient optimization of the nearly independent channels: In each step, the flow of information proceeds from optimization of the duals to builds involving the density and back to the duals in a merge-annihilate-truncate-build-split-truncate (MATBST) sequence. For the variables \( v \), \( p \) and \( q \) this sequence is comprised by lines 22-23 and 5-7, and lines 15-19 for the corresponding conjugate gradients \( h_v \), \( h_p \) and \( h_q \). Truncation is carried out with the filter operation as described in Ref. [11], with cost and error determined by the matrix threshold \( \tau_{\text{max}} \).

The Tsiper functional is the sum of dual quotients \( \omega_p \) and \( \omega_q \), determined at line 8, followed by the gradients \( g_p \) and \( g_q \) computed at line 9. After the first cycle, the corresponding relative error \( e_{\text{rel}} \) (10) and maximum matrix element of the gradient \( g_{\text{max}} \) (11) are computed and used as an exit criterion at line 4, along with non-variational behavior \( \omega > \omega_{\text{old}} \).

Next, the Polak-Ribiere variant of non-linear conjugate gradients yields the search direction in each channel, \( h_p \) and \( h_q \) (12-14). The action of \( L[\cdot] \) on to \( h_p \) and \( h_q \) is then computed, again with a MATBST sequence (15-19), followed by a self-consistent dual channel line search at line 20, as described below. With steps \( \lambda_p \) and \( \lambda_q \) in hand, minimizing updates are taken along each conjugate direction (22), and the cycle repeats with the MATBST sequence spanning lines 21-23 and 5-7.

Optimization of the Tsiper functional \( \omega[\lambda_p, \lambda_q] \equiv \int d^3x \langle \psi | H - \omega \rho | \psi \rangle \)
Algorithm 1 QUIRQI

1: procedure QUIRQI(ω, v)
2:   guess v
3:   p = f_v (w), q = f_w (w)
4:   while ε_y > ε and gmax > γ and ω < ω_{old} do
5:     L[v] = [F, v] + [G[v], P]
6:     L[p] = f_w (L[v]), L[q] = f_v (L[v])
7:     filter (L[p], L[q], τ_{nxt})
8:     ω_p = (ω_p, ω_p) = (ω_p, ω_p)
9:     g_p = [q + L[p]] = [q + L[q]]
10:    ω_{rel} = max \{ |g_p|_{ij}, |g_p|_{ij} \}
11:    g_{max} = max \{ |g_p|_{ij}, |g_p|_{ij} \}
12:    β_p = \frac{(g_{p_{old}} - g_p)}{(g_{p_{old}} - g_p)}
13:    ω_{old} = ω, g_{p_{old}} = g_p, g_{q_{old}} = g_q
14:    h_p ← g_p + β_p h_p, h_q ← g_q + β_q h_q
15:    h_v = f_h (h_p, h_q), h_v ← f_v (h_v)
16:    filter (h_p, h_q, τ_{nxt})
17:    L_{h_1} = [F, h_1] + [G[h_1], P]
18:    L_{h_2} = f_w (L_{h_1}), L_{h_2} = f_v (L_{h_1})
19:    filter (L_{h_1}, L_{h_2}, τ_{nxt})
20:    {λ_p, λ_q} = argmin \{ ω | p + λ_p h_p, q + λ_q h_q \}
21:    p ← p + λ_p h_p, q ← q + λ_q h_q
22:    v ← f_v (p, q), v ← f_v (v)
23:    filter (p, q, v, τ_{nxt})
24: end while
25: end procedure

$$\omega [p + \lambda_p h_p, q + \lambda_q h_q]$$ involves a two dimensional line-search (line 20) corresponding to minimization of

$$\omega [\lambda_p, \lambda_q] = \frac{A_p + \lambda_p B_p [\phi - C_p C_p] + A_q + \lambda_q B_q [\phi - C_q C_q]}{R_{pq} + \lambda_p S_{pq} + \lambda_q T_{pq} + \lambda_p \lambda_q U_{pq}}$$

with coupling entering through terms in the denominator such as \( U_{pq} = \langle h_p, h_q \rangle \). A minimum in Eq. (3) can be found quickly to high precision by alternately substituting one-dimensional solutions one into the other until self-consistency is reached. This semi-analytic approach starts with a rough guess at the pair \{λ_p, λ_q\} (eg. found by a coarse scan) followed by iterative substitution, where for example the p-channel update is

$$\lambda_p \left\{ \left[ (2 C_p R_{pq} + 2 C_p \lambda_p S_{pq})^2 - 4 (C_p T_{pq} + C_p \lambda_q U_{pq}) \right] \ight.$$  

$$\left. [B_p R_{pq} + B_p \lambda_p S_{pq} - (A_p + A_q + B_p \lambda_q + C_p \lambda_q^3) T_{pq} - (A_q \lambda_p + A_q \lambda_q + B_q \lambda_q^3 + C_q \lambda_q^3) U_{pq}] \right \}^{1/2}$$

$$- 2 C_p R_{pq} - 2 C_p \lambda_q S_{pq} \right \} / [2 C_p (T_{pq} + \lambda_q U_{pq})],$$

with an analogous update for the q-channel obtained by swapping subscripts. As the solution decouples \( S_{pq}, T_{pq} \) and \( U_{pq} \) become small the steps are found independently.

QUIRQI has been implemented in FreeON [2], which employs the linear scaling Coulomb and Hartree-Fock exchange kernels QCTC and ONX with cost and accuracy controlled by the two-electron screening threshold \( \tau_{se} \). N-scaling solution of the QUIRQI matrix equations is achieved with the sparse approximate matrix-matrix multiply (SpAMM), with cost and accuracy determined by the drop tolerance \( \tau_{nxt} \). All calculations were carried out with version 4.3 of the gcc/gfortran compiler under version 8.04 of the Ubuntu Linux distribution and run on a fully loaded 2GHz AMD Quad Opteron 8350.

For systems studied to date, QUIRQI is found to converge monotonically with rates comparable to the TDA as shown in Fig. [1]. Based on the comparative performance presented by TINC, the TDA rate of convergence appears to be a lower bound for RPA solvers. In addition to the convergence rate, performance is strongly determined by the initial guess. The following results have been obtained using the polarization response density along the polymer axis [19], which can be computed in \( O(N) \) by Perturbed Projection [20]. Also, a relative precision of 4 digits in the excitation energy is targeted with the convergence parameters \( \epsilon = 10^{-4} \) and \( \gamma = 10^{-3} \), with exit from the optimization loop on violation of monotonic convergence (\( \omega > \omega_{old} \)) due to precision limitations associated with linear scaling approximations.

In Fig. [2] linear scaling and convergence to the bulk limit are demonstrated for a series of polyethylene vinylene (PPV) oligomers at the RHF/6-31G** level of theory for the threshold combinations \{ \( \tau_{nxt}, \tau_{se} \) \} = \{ 10^{-4}, 10^{-5} \} and \{ 10^{-5}, 10^{-6} \}. Significantly more conservative thresholds have been used for the Coulomb sums, which incur only minor cost. Convergence is reached in 24 - 25 iterations, with the cost of Coulomb summation via QCTC comparable to the cost of SpAMM(\( \tau_{nxt} \) = 10^{-4}). In Fig. [3] linear scaling and convergence to the bulk limit are demonstrated for a series of (4,3) carbon nanotube segments at the RHF/3-21G level of theory for the same threshold combinations, again with convergence achieved in about 24-25 cycles. In both cases, tightening the pair \{ \( \tau_{nxt}, \tau_{se} \) \} leads to a systematically improved result. While the \{ 10^{-4}, 10^{-5} \} thresholds that work well for PPV lead to a non-monotone behavior with respect to extent for the nanotube series, dropping one more decade to \{ 10^{-5}, 10^{-6} \} leads to a sharply improved behavior. Dropping thresholds further to \{ 10^{-6}, 10^{-7} \} yields identical results to within the convergence criteria (~four digits) across the series, also scaling with \( N \) but at roughly twice the cost.

These results demonstrate that QUIRQI can achieve both systematic error control and linear scaling in solution of the RPA eigenproblem for systems with extended conjugation. Relative to PPV, the greater numerical sensitivity encountered with the nanotube series is consistent with the ground state problem, where a smaller band gap and greater atomic connectivity typically demand tighter thresholds.

QUIRQI exploits decoupling of the Tsipper functional into nearly independent, pseudo-Hermitian quotients.
leading to aggressive convergence rates equivalent to the fully Hermitian TDA, while remaining variational with respect to matrix truncation ($\tau_{\text{mtx}}$). However, QUIRQI is not variational with respect to the screening parameter $\tau_{2e}$. It can be systematically improved by tightening $\tau_{2e}$ though, due to rigorous error bounds based on the Schwartz inequality. These properties present opportunities for more precise error control as suggested by Rubensson, Rudberg and Salek. Further, these properties are expected to hold even for the most general SCF models, with the only difference being an increasingly localized transition density matrix and larger cost prefactor with an increasing DFT component. Finally, a variational approach allows considerable flexibility in the path to solution, as errors due to approximation can be overcome by optimization, offering opportunities for single precision GPU acceleration, variable thresholding, incremental Fock builds as well as extrapolation techniques.

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