Research Article

An Analysis Method for Time-, Frequency-, and Energy-Domain Characteristics of Downhole Microseismic Signals and Its Application

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Based on SOS microseismic (MS) monitoring system of a certain mine, time-, frequency-, and energy-domain characteristics of MS signals are analyzed by comprehensively applying one-dimensional discrete Fourier transform (DFT) and one-dimensional discrete wavelet transform (DWT). The technology is employed to explore MS signals from incident and transmitted waves on the fault plane. The research results show that, within the time domain, the transmitted waves are found to have the rapidly reducing velocity and a few wave crests; within the frequency domain, the fault plane presents a low-pass filtering effect on incident waves; within the energy domain, the fault generally shows the vibration-attenuating effect on MS signals. The analysis method is used for the No. 3307 working face of a certain mine to realize the prediction on a buried fault in the middle part of the working face, and it is validated to have a favorable effect.

1. Introduction

Underground coal mines exhibit complex geological environment. The complex geological structures centered on faults not only influence the continuity of mine production, but also probably trigger some dynamic disasters such as fault-induced rockburst, which greatly threatens the safety production of coal mines [1, 2]. The time-, frequency-, and energy-domain curves of a microseismic (MS) signal, as the concomitant signal during the deformation and fracture of coal-rock mass, can indirectly reflect the generation, propagation, and attenuation processes of the signal.

It is widely known that the analysis based on vibration signal is used for detection of mechanical and electrical faults of the motor, and the change of generated vibration signals can help detect the type of fault [3–6], which can provide a reference for the MS effect analysis in underground coal mining. To date, numerous studies show that MS signals are subjected to local abrupt change or transition when going through a fault. Therefore, it is possible to predict a buried fault when excavating the unexposed working face by analyzing the population characteristics of MS signals in an area.

At the beginning of the century, Dou et al. [3–5] first introduced the SOS MS monitoring system in China to perform the precursor identification, and monitoring and early warning for rockburst, attaining numerous MS data. Based on signal analysis theory, Cai et al. [6] developed a series of software for postprocessing of MS signals. These studies provide equipment and software bases for analyzing the time-, frequency-, and energy-domain characteristics of MS signals; however, they focus on exploring the time-dependent law of MS signals. The frequency- and energy-dependent laws of MS signals are maturely applied in the geological exploration field, while their MS signal source generally needs to be actively activated. According to the research in a coalfield in Xinmi, Henan Province, China, Chen et al. [7] found that it is feasible to effectively improve the detection accuracy and efficiency of buried faults after eliminating the influence of high-frequency noises in vibration signals with the aid of the wavelet transform. Liu et al. [8] and Zhou et al. [9] explored the influence law of the
fault fracture zones with different depths and dips on propagation of Rayleigh waves. The research reveals the vibration-attenuating effect of faults on Rayleigh surface waves. Jia [10] also employed the technology for time- and frequency-domain characteristic analysis of Rayleigh waves to detect the buried faults.

At present, the signals measured by a MS monitoring instrument in underground coal mines of China are a group of discrete time-dependent signals; by connecting various points, the time-domain curve of MS signals can be drawn. Owing to the time-domain curve corresponding to an amplitude-time function, abundant time-dependent information is contained, while no any frequency-dependent information is included in the curve. The time-domain curve can be reconstructed by utilizing the discrete Fourier transform (DFT) and one-dimensional discrete wavelet transform (DWT). Furthermore, the accurate frequency-amplitude curve of MS signals is attained; however, the curve fails to reflect the change of the frequency of MS signals with time. With the development of the signal analysis technology, the time-frequency representation method of signals, that is, the method for representing signals through the joint function of time and frequency, has been applied to some extent [11–14]. On this basis, the frequency spectra are further transformed into energy spectra of MS signals, and thus the law of energy attenuation of MS signals in the propagation process can be obtained.

Therefore, the existing SOS MS monitoring system and monitored MS data during mining of the working faces of mines were applied. On this basis, the time- frequency-, and energy-domain characteristics of MS signals from incident and transmitted waves within the fault zone were separately analyzed by comprehensively using multiple signal analysis methods. It is expected to determine a quantified threshold to predict whether a fault exists or not, thus providing index reference for predicting the buried faults in working faces.

2. Analysis Method for Time-, Frequency-, and Energy-Domain Characteristics of MS Signals

2.1. Transformation between Time- and Frequency-Domain Curves. Aiming at the characteristic that the measured MS signals appear as the time-amplitude curve, fast Fourier transform (FFT) allows the transformation between time- and frequency-domain information of MS signals. In essence, MS signals are decomposed into many sine waves and high-order harmonics with different frequencies consisting of the basis functions thereof. The basic form of Fourier transform is expressed as follows [15]:

\[ X(\omega) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(t) e^{-j\omega t} \, dt, \]

(1)

where \( X(t) \) refers to the function between the wave velocity and time history of MS signals by taking the time \( t \) as a variable; \( X(\omega) \) stands for the amplitude-frequency function by taking the angular frequency \( \omega \) of MS signals as a variable.

Moreover, the wave files are required to be a continuous function in FFT method, while the measured MS data in underground coal mines are stored as a group of arrays with the fixed frequency. Therefore, it is necessary to process the wave files by using the DDT [15]. The DDT delivers the same principle as the FFT method, while it also realizes the data discretization. The DDT method is expressed as

\[ X(e^{-j\omega}) = \sum_{n=-\infty}^{\infty} X(n)e^{-j\omega t_n}, \]

(2)

where \( X(n) \) and \( \omega \) separately represent the wave velocities of various data points and the angular frequency of MS signals.

2.2. Transformation between the Time-Domain and Time-Frequency Curves. However, due to hiding all time information in the transform process, the FFT method cannot show the change law of the frequency with time. Based on the one-dimensional DWT [15], it is possible to conduct the binary decomposition on MS signals; afterwards, the low-frequency parts are selected to conduct the transform at a half of the original scale. In this way, the high-resolution time information is attained at the high-frequency bands and high-resolution frequency information at the low-frequency bands of signals.

It is supposed that a MS signal \( X \) shows the length \( N \), and, therefore, the whole calculation process is completed within \( \log_2 N \) steps at most. Starting from original signals in the first step, two groups of parameters are generated: one group refers to the approximate signals \( cA_1 \) obtained using the low-pass filter, while the other group corresponds to the detailed signals \( cD_1 \) attained by applying the high-pass filter. The decomposition result of MS signals \( X(N) \) by employing the \( i \)-order DWT is expressed as follows:

\[ X(N) = cA_i + \sum_{j=1}^{i} cD_j, \]

(3)

where \( cA_i \) and \( cD_i \) separately denote the approximate and detailed coefficients of MS signals at nodes in the \( i \)-th sub-layer; moreover, the bandwidths of the MS signals at the \( i \)-th node can be separately expressed as follows:

\[ \omega(cA_i) = \omega(cD_i) = \frac{\omega}{2^i}. \]

(4)

The decomposition result of MS signals with the aid of the one-dimensional DWT is displayed in Figure 1.

According to the research results by Lin [13] and Zhao et al. [14], the db8 wavelet basis function is selected, which shows favorable adaptability in processing nonstationary vibration signals. The order of the wavelet decomposition equals 5.

2.3. Transformation between Frequency- and Energy-Domain Curves. The energy of MS signals, a kind of spherical wave, is generally calculated by applying the energy density method [1]. The MS energy \( W \) is defined as the known energy flux of seismic waves on the reference spherical surface, which is generated in the vibration process of the wave group \( s, \tau \):

\[ W = \int_{\text{sphere}} \frac{1}{2} \rho c \, ds, \]

where \( \rho \) is the mass density of the medium, \( c \) is the wave velocity, and \( ds \) is the area of the spherical surface.
The energy density of all measuring points is attained by calculating the sum of the densities of and waves in various groups. The energy density $\varepsilon (r)$ is calculated according to the following equation:

$$\varepsilon (r) = \frac{1}{2} \rho c v \tau \sum_{t=1}^{n} x_{i,k}^2 \tau_{ik},$$

where $\rho$, $c$, $v$, and $\tau$ denote the media density, propagation velocity of waves, amplitude of vibration velocity, and the duration of vibration of wave groups, with $i = P, S$ and $k = 1, 2, \ldots$.

According to the above equation, it can be found that the MS signal energy is directly proportional to the square of the amplitude. Therefore, the energy distribution of MS signals can be expressed by using the relative energy. In the frequency-domain curve, if the MS signals are partitioned into $n$ frequency bands, the relative energy within the $i$th frequency band can be expressed as follows:

$$E_i = \int_{0}^{T} (U \cdot n)dS,$$

where $E_i$ denotes the energy of MS signals at the $S_i$th frequency band, and $x_{i,k}$ ($i = 1, 2, \ldots, n, k = 1, 2, \ldots m$; $m$ refers to the number of discrete points of MS signals) represents the amplitude at the $k$th sampling point within the $i$th frequency band of MS signals.

The total energy of MS signals can be expressed as follows:

$$E = \sum_{i=1}^{n} E_i,$$

where $E$ and $E_i$ represent the total energy of MS signals and the energy at the $S_i$th frequency band of MS signals.

Thus, the relative energy density in the $i$th frequency band can be shown as follows:

$$\lambda = \frac{E_i}{E} \times 100\%,$$

where $E_i$ and $E$ denote the total energy of MS signals and the energy at the $S_i$th frequency band of MS signals, respectively.

**2.4. The Method for Comprehensively Analyzing the Time-, Frequency-, and Energy-Domain Characteristics.** The MS signals recorded by using the SOS MS monitoring instrument are taken as examples. The main steps of the analysis method for time-, frequency-, and energy-domain characteristics of MS signals are summarized as follows: (1) the effective downhole MS signals are monitored by using the SOS MS monitoring instrument, and then data are stored; (2) the MS signals are extracted, and a time window is selected to attain the slices of MS signals with a reasonable length based on the time window; (3) the low-pass filtering is conducted on MS signals to eliminate the noise interference factors such as downhole mechanical equipment; (4) the time-amplitude curve (that is, time-domain curve) of MS signals is drawn and analyzed; (5) the programming is performed by utilizing MATLAB software, and the time-domain curve is subjected to DDT according to Nyquist sampling frequency to draw and then analyze the frequency-amplitude curve (that is, frequency-domain curve) of MS signals; (6) the time-domain curve is subjected to DWT by applying the wavelet analysis toolbox of MATLAB software to draw and analyze the time-frequency curve of MS signals; (7) the time, frequency, and energy data obtained through the aforementioned processing are normalized, and the time-, frequency-, and energy-domain characteristic curves of MS signals are drawn and analyzed by applying the three-dimensional drawing function of the MATLAB software. The method for comprehensively analyzing the time-, frequency-, and energy-domain characteristics is presented in Figure 2.

For MS signals from underground coal mines, the seismic waves synchronously experience reflection and transmission due to being influenced by the interfacial dynamic effect at the interface when waves from the seismic source propagate to the structural plane such as faults. The incident and reflected wave surfaces of the same seismic wave, as well as different types of seismic wave surfaces, are superposed, which causes the abrupt change of the spectra of the transmitted waves. It is mainly shown as changes of the time, frequency, and energy spectra of the transmitted waves. Owing to the fact that vibration lasts for a short time, and the seismic source is close to the observation station, it is difficult to attain the hidden law of MS signals through the conventional observation. Based on the method for comprehensively analyzing the time-, frequency-, and energy-domain characteristics, it is feasible to partially enlarge different characteristics of MS signals. By analyzing the abrupt change of time and frequency spectra and energy dissipation of MS signals, it is possible to predict the positions of large-scale structural planes within areas.

**3. Examples for Analyzing the Time-, Frequency-, and Energy-Domain Characteristics of MS Signals**

**3.1. Engineering Background.** All data were taken from the SOS MS monitoring system of a certain coal mine in Shandong Province, China. The mined No. 3 coal seam of...
Select the time window with a reasonable length

The effective MS signals monitored by SOS

Low-pass filtering of selected MS signals

Drawing and analyzing time-amplitude and time-domain curve

DDT transfer

DWT transfer

Normalizing the information: time, frequency, and energy

Figure 2: The scheme of the proposed analysis method for MS signals.

the No. 3307 working face of the coal mine shows an average dip of 8°, and faults are developed in the working face. The F1 normal fault (∠60° H: 23 m) has been explored during the excavation. A total of three groups of seismic geophones were distributed within the working face, in which 1# and 2# seismic geophones were distributed in the intake airway at the footwall of the F1 fault, and the 3# geophone was distributed in the haulage gateway at the hanging wall of the F1 fault. According to the MS monitoring law of the working face, the population waveform characteristics of the measured MS signals abruptly varied when the working face was mined to the position about 60 m in front of the open-off cut. Moreover, MS events generally intensively appeared in the area 10~60 m in front of the working face. Considering this, the area 70~120 m in front of the open-off cut was mainly monitored, and the monitoring was constantly performed during the mining of the working face. The condition of the working face is displayed in Figure 3.

Some parameters of the MS monitoring system applied in the No. 3307 working face are shown as follows: 16 seismic geophones were used to sample signals at 8000 groups of points at the sampling frequency of 500 Hz, with the time of recording signals for 16 s.

3.2. Comparison of the Time- and Frequency-Domain Curves of the Incident and Transmitted Waves. The MS event occurring at 10:57:53 a.m. on October 10, 2015, is used as an example. At first, the MS data measured by the 16 groups of geophones are screened to attain the signals measured by geophones 1#, 2#, and 3#. Afterwards, the signals are partially enlarged, and the slices within the time window of 4 s are drawn. The enlarged MS signals are smoothed through the low-pass filtering based on the MATLAB software. The time-domain curves of smoothed signals in three groups of channels are drawn, as shown in Figure 4.

Obviously, it can be seen from Figure 4 that the time-domain curve in the 2# channel shows different characteristics than those in the 1# and 3# channels. As shown in Figure 3, if the F1 fault is taken as the boundary, the 1# and 2# geophones are distributed in front of the F1 fault, which are used to monitor the incident waves; the 3# geophone lies in the rear of the F1 fault, which is applied to monitor the transmitted waves. In addition, considering that the distances of the intensively monitored area to the 2# and 3# geophones are approximated, the data in 2# and 3# channels are separately selected for comparison and analysis. The relationship curves v(t) between the particle vibration velocities in the two channels and time are drawn, as shown in Figure 5.

(a) Relationship curve between the velocity of incident waves and time

(b) Relationship curve between the velocity of transmitted waves and time

By comparing curves, it can be seen that the peak velocity of incident waves is $4.37 \times 10^{-4}$ m/s, with a low reduction rate of wave velocity, and there are about 30 wave crests. Moreover, P wave first motion is clearly found, and vibration lasts for about 1 s; the peak velocity of the transmitted waves equals $6.27 \times 10^{-4}$ m/s, showing a large reduction rate of the wave velocity, and about 10 wave crests appear. In addition, the coda waves are developed, and P wave first motion is hard to be identified due to the interference of high-frequency signals. In this case, the duration of the vibration is about 3 s.

The digital signals of the incident and transmitted waves are imported into the MATLAB software. By performing the programming based on Equation (2), the measured signals are subjected to DDT, and then the frequency-amplitude distribution curves of incident and transmitted waves are drawn, as shown in Figure 6.

Owing to the fact that the sampling frequency of seismic geophones is 500 Hz, the Nyquist sampling frequency is determined as 250 Hz according to the sampling theorem. Not any amplitude information is contained within the frequency band of 200~250 Hz. For convenience of analysis, the MS signals in the frequency band of 0~200 Hz are analyzed, in which 0~60, 60~120, and 120~250 Hz are separately defined as low-, middle-, and high-frequency bands.

Through analysis, it is found that (1) the frequencies of incident and transmitted waves are mainly found within the frequency band of 0~160 Hz, in which the dominant frequency of the incident waves mainly appears in the middle- and low-frequency bands of 0~120 Hz; by contrast, the main frequency of the transmitted waves is transferred from high- to low-frequency bands, and their dominant frequency corresponds to a low-frequency band of 0~20 Hz. It indicates that the presence of the fault blocks the middle- and high-frequency vibration signals and some low-frequency vibration signals (20~120 Hz) of incident waves, showing a low-pass filtering effect on incident waves; (2) within the dominant frequency bands, the incident waves deliver the
uniformly distributed frequencies, and their frequency spectra show significant multipeak characteristics; as for the transmitted waves, the frequency is mainly found to be about 2 Hz, and the frequency spectra exhibit the sharp single-peak characteristic.

3.3. Comparison of Time-Frequency Curves of Incident and Transmitted Waves. The fifth-order DWT is separately conducted on MS signals from incident and transmitted waves to attain the approximate and detailed coefficients of two MS signals, as shown in Figure 7.
According to the above decomposition results, $d_1$ refers to the part with the highest frequency in the detailed coefficient of MS signals, with a small amplitude, low energy, and high discreteness, which is not suitable to be used as the quantified threshold. Therefore, it is not intensively analyzed. In the decomposition results, the main energy of MS signals is mainly found in wavelet decomposed signals $d_2$, $d_3$, $d_4$, and $d_5$. By observing the waveform graph, it can be seen that P wave first motions of four waveforms $d_3$, $d_4$, $d_5$, and $a_5$ are clearly observed. The onset amplitudes of the four wavelet decomposed signals of incident and transmitted waves are compared with their corresponding maximum amplitudes, and the change laws of the onset amplitudes and maximum amplitudes are shown in Figure 8.

The above analysis results show that (1), among wavelets at different frequency bands, the onset amplitude of incident waves is logarithmically correlated with the frequency band of wavelets. The lower the frequency band, the smaller the onset amplitude of wavelets; (2) the onset amplitudes of transmitted waves at the high- and middle-frequency bands are also logarithmically correlated with the frequency band of wavelets; however, the wavelet presents obviously abrupt change in the amplitude at the low-frequency band $a_5$. The onset amplitude of the transmitted wave is 14.47 times that of the incident wave at the frequency band $a_5$, far larger than those of the wavelets at the other frequency bands; (3) the maximum amplitudes of incident waves are relatively discrete, while those of transmitted waves regularly increase only at the frequency band $d_5$; (4) comparatively speaking, the increment of the onset amplitude of the wavelet at the frequency band $a_5$ is more suitable to be used as the quantified threshold to measure the influence of faults on the energy in MS signals.

The DWT result is calculated by performing programming based on MATLAB software, and nephograms of time-frequency characteristics of MS signals from incident and transmitted waves are separately drawn, as shown in Figure 9.

By observing the nephograms, it can be seen that (1), along the timeline, the vibrations of incident and transmitted waves at the dominant frequency band last for about 0.8 and 0.4 s, respectively; the time window of the dominant frequency band of incident waves is narrower than that of the transmitted waves; (2) along the frequency axis, the main vibration frequency band of transmitted waves narrows relative to that of incident waves, showing the transfer of the dominant frequency band from the middle- to low-frequency bands.

### 3.4. Comparison of Energy-Domain Curves of Incident and Transmitted Waves

According to the directly proportional relationship between the energy and the square of amplitude of MS signals, it is feasible to characterize the energy distribution of MS signals at different frequency bands with the aid of the relative energy density. The frequency-amplitude curve of MS signals in Figure 6 is segmented at first, in which the frequency band of $0 \sim 160$ Hz is divided into eight sections ($S_1 \sim S_8$).

According to Equations (7)–(9), the energy density distributions of incident and transmitted waves at different frequency bands are separately calculated, as shown in Tables 1 and 2. The corresponding energy density distribution curves are drawn, as shown in Figure 10.

According to the above analysis, the energy of incident waves mainly concentrates in the frequency band of $20 \sim 80$ Hz, at which the energy accounts for about 67.96% of the total waveform energy. The high-frequency components of transmitted waves significantly reduce, so the energy at the high-frequency band dramatically declines. The waveform energy is mainly found at the low-frequency band of $0 \sim 20$ Hz, at which the energy takes up 97.33% of the total waveform energy.

According to results obtained through DDT and DWT and the above analysis results, the time, frequency, and energy data are normalized by utilizing the MATLAB software. The three-dimensional graphs of time-, frequency-, and energy-domain characteristics of incident and transmitted waves are separately shown in Figure 11.

By comparing the above graphs, it can be found that (1) the energy of MS signals varies in the leap pattern with time. Globally, the energy of incident waves with high density is
Figure 7: The results of one-dimensional discrete wavelet decomposition of incident and transmitted waves. (a) The result of wavelet decomposition of incident waves. (b) The result of wavelet decomposition of transmitted waves.

Figure 8: Comparison of the change laws of the onset amplitude and maximum amplitude of incident and transmitted waves. (a) The change law of the onset amplitude of the wavelets at different frequency bands. (b) The change law of the maximum amplitude of the wavelets at different frequency bands.
continuously distributed, and the energy is absent only in few frequency bands. The energy of transmitted waves in many vibration frequency bands is lost at the timeline. By discretizing and calculating the curved surface, it can be attained that, at the frequency axis, the energy density of transmitted waves at the low-frequency band of 0 ∼ 60Hz is about 84.7%, while that at the middle-frequency band of 60 ∼ 120Hz is about 6.43%; the energy density at the high-frequency band nearly equals 0. It generally shows the vibration-attenuating effect of faults on MS signals. (2) Locally, the energy of transmitted waves is higher than that of incident waves in some areas, which indicates that faults deliver a vibration-increasing effect on vibration waves in some periods and frequency bands.

### 3.5. Engineering Verification

According to the above principle, the three-dimensional distribution graphs of time-, frequency-, and energy-domain characteristics of the MS event occurring at 10:57:53 a.m. on October 10, 2015, in the channels 1#, 2#, and 3# are separately drawn. For convenience of comparison, their time-energy profiles are analyzed, as shown in Figure 12.

As shown in Figure 12, the energy distribution laws in the three channels present an obvious difference: the energy spectra in 1# and 3# channels are distributed in a relatively similar fashion, which greatly differs from that in the 2# channel. The energy density of transmitted waves at the low-frequency band of 0 ∼ 60 Hz is about 84.7%, while that at the middle-frequency band of 60 ∼ 120 Hz is about 6.43%; the energy density at the high-frequency band nearly equals 0. It generally shows the vibration-attenuating effect of faults on MS signals. (2) Locally, the energy of transmitted waves is higher than that of incident waves within some areas, which indicates that faults deliver a vibration-increasing effect on vibration waves in some periods and frequency bands.

### Table 1: The energy density distribution of incident waves at different frequency bands.

| Frequency band (Hz) | S1  | S2  | S3  | S4  | S5  | S6  | S7  | S8  |
|---------------------|-----|-----|-----|-----|-----|-----|-----|-----|
| 0–20                | 0.0008 | 0.0020 | 0.0013 | 0.0014 | 0.0011 | 0.0003 | 0.0000 | 0.0000 |
| Relative energy     | 11.48 | 28.75 | 18.78 | 20.43 | 15.84 | 4.54 | 0.16 | 0.02 |
| Energy density (%)  | 30   | 50   | 70   | 90   | 110  | 130  | 150  | 170  |

### Table 2: The energy density distribution of transmitted waves at different frequency bands.

| Frequency band (Hz) | S1  | S2  | S3  | S4  | S5  | S6  | S7  | S8  |
|---------------------|-----|-----|-----|-----|-----|-----|-----|-----|
| 0–20                | 0.0911 | 0.0010 | 0.0006 | 0.0002 | 0.0004 | 0.0001 | 0.0001 | 0.0000 |
| Relative energy     | 97.33 | 1.11 | 0.66 | 0.23 | 0.43 | 0.14 | 0.10 | 0.00 |
| Energy density (%)  | 30   | 50   | 70   | 90   | 110  | 130  | 150  | 170  |
channel. According to the actual condition of the working face, the geophones 1# and 2# are both located in front of the F1 fault, so data collected thereby should show the energy distribution characteristics of incident waves; however, the energy distribution characteristic of data collected by the geophone 1# is similar to that of geophone 3#, showing the energy characteristics of transmitted waves. On this basis, it is inferred that a large-scale structural plane is probably present between the monitored area and the geophone 1#. Also, the amplitude-frequency and time-frequency distribution are extract, as shown in Figures 13 and 14. It can be seen that the amplitude-frequency and time-frequency distribution laws are similar to those of the energy distribution.

Afterwards, the buried fault F2 was exposed in the mining process of the working face, which practically verifies the aforementioned analysis results. The position of the measured buried fault F2 is displayed in Figure 15.

As the fault was not explored during the excavation of the No. 3307 working face, the area was not identified at high rockburst risk and subjected to targeted measures when performing region division of the working face according to the rockburst risk. As a result, high-energy mine tremors frequently occurred during the mining of the working face. If the presence of the existing fault had been predicted through the analysis technology for time-, frequency-, and energy-domain characteristics, it is possible to manage the area as a zone with high rockburst risk, thus avoiding the occurrence of potential fault-induced rockburst.

4. Discussion

The question arises as to whether the aforementioned analysis method for time-, frequency-, and energy-domain characteristics of MS signals could be used to predict the buried faults in underground working faces. Such a method could take full advantage of the SOS MS monitoring system in rock burst coal mines. The advantages of the method are as follows: (1) a single frequency component pulse physical model of vibration wave with Fourier spectrum characteristics is established. The model shows that when the pulse wave with Fourier spectrum passes through the nonlinear joint surface, its waveform changes, and its corresponding spectrum will be modified due to absorption. (2) Discrete Fourier transform (FFT) is used to analyze the incident wave and transmission wave of fault plane. The results show that the nonlinear joint plane shields the high-frequency signal and part of the low-frequency signal of incident wave and acts as a low-pass filter for incident wave. The attenuation range of high-frequency signal is much larger than that of low-frequency signal. (3) One-dimensional discrete wavelet transform (DWT) is applied to incident wave and transmission wave in fault plane. It is pointed out that the abnormal amplitude increment of a5 wavelet P wave in low-frequency band of transmission wave is more suitable than S-wave to measure the influence of fault on seismic wave propagation. (4) The time-frequency characteristic nephogram and time-energy density distribution diagram of incident wave and transmission wave are calculated and drawn by MATLAB programming, and the “isolation” effect of fault surface on incident wave energy is explained. (5) The application of this technology to the detection of hidden faults in a deep working face can predict a small hidden fault in the middle of the working face. Through the pressure relief work in advance, the potential risk of fault burst can be avoided. However, it is definitely promising to develop an optimization scheme for the detection of buried fault, but depending on the implementation, the resulting method will probably be more complex and time consuming computationally, as a large number of field examples are needed for verification. Despite these remarks, this idea has the potential to deliver interesting results.
Figure 12: The relative energy-time distributions of the MS event in three channels. (a) Channel 1#. (b) Channel 2#. (c) Channel 3#.

Figure 13: The relative amplitude-frequency distributions of the MS event in three channels.
Figure 14: The relative time-frequency distributions of the MS event in three channels. (a) 1#. (b) 2#. (c) 3#.

Figure 15: Planar graph of the position of the buried fault F2.
5. Conclusions

(1) The transformation between time- and frequency-domain curves of MS signals is realized by using the DDT, while that between the time-domain and time-frequency curves of MS signals is achieved through DWT; moreover, the relative energy density representation method is employed to realize the transformation between the frequency- and energy-domain curves. Eventually, the change laws of the frequency and energy distributions of MS signals with time are attained by utilizing the analysis method for time-, frequency-, and energy-domain characteristics of MS signals.

(2) Through research, the differences of time-, frequency-, and energy-domain characteristic curves of incident and transmitted waves of the fault plane are obtained. The differences are mainly shown as follows: within the time domain, the transmitted waves present rapidly decreasing velocity and a few wave crests; within the frequency domain, the structural plane blocks the high-frequency signals and some low- and middle-frequency (20–120 Hz) signals of incident waves, playing a low-pass filtering effect on incident waves. The vibration frequency of transmitted waves mainly occurs in the low-frequency band; within the energy domain, the fault generally delivers a vibration-attenuating effect on MS signals, while it still shows a vibration-increasing effect on MS signals within several time periods. The onset amplitude of the wavelet at the frequency band 5 is more suitable for being used as the quantified threshold to measure the influence of the fault on propagation of MS signals.

(3) The comprehensive analysis method for time-, frequency-, and energy-domain characteristics of MS signals is applied in a certain working face, and it can predict a buried fault in the middle part of the working face, so it is verified to have a favorable effect. However, considering the complexity of downhole geological structures and nonrepeatability of the case, how to establish a quantitative identification index for a structural plane based on MS signals that is applicable for all mines also needs plenty of data accumulation and remains to be further explored.

Data Availability

Some or all data, models, or code generated or used during the study are available from the corresponding author upon request.

Conflicts of Interest

The authors declare that they have no conflicts of interest.

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