Efficient computation of minimal perturbation sets in gene regulatory networks

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Research Topic: From structural to molecular systems biology: experimental and computational approaches to unravel mechanisms of kinase activity regulation in cancer and neurodegeneration

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In the last few decades, technological and experimental advancements have enabled a more precise understanding of the mode of action of drugs with respect to human cell signaling pathways and have positively influenced the design of new drug compounds. However, as the design of compounds has become increasingly target-specific, the overall effects of a drug on adjacent cellular signaling pathways remain difficult to predict because of the complexity of the interactions involved. Off-target effects of drugs are known to influence their efficacy and safety. Similarly, drugs which are more target-specific also suffer from lack of efficacy because their scope might be too limited in the context of cellular signaling. Even in situations where the signaling pathways targeted by a drug are known, the presence of point mutations in some of the components of the pathways can render a therapy ineffective in a considerable target subpopulation. Some of these issues can be addressed by predicting Minimal Intervention Sets (MIS) of elements of the signaling pathways that when perturbed give rise to a pre-defined cellular phenotype. These minimal gene perturbation sets can then be further used to screen a library of drug compounds in order to discover effective drug therapies. This manuscript describes algorithms that can be used to discover MIS in a gene regulatory network that can lead to a defined cellular phenotype. Algorithms are implemented in our Boolean modeling toolbox, GenYsis. The software binaries of GenYsis are available for download from http://www.vital-it.ch/software/genYsis/.

Keywords: boolean modeling, GRN, MIS, miRNA, algorithms, qualitative modeling, T-Helper, cancer pathways

1. INTRODUCTION

Advancements in high-throughput technologies have enabled biologists to measure the expression (or activity) of many genes simultaneously. By measuring and comparing the expression of genes in a normal vs. diseased cell phenotypes, biologists have been able to identify various key genes involved in disease pathways. However, predicting a set of genes in a disease is often not sufficient as it may not be possible to directly manipulate the expression of those genes using available drug compounds. This necessitates studying the interactions of genes that are known drug targets with respect to the genes (or proteins) that are implicated in high-throughput analysis of specific disease phenotypes. This observation has shifted the focus of computational and experimental tools from studying individual genes to understanding the underlying gene regulatory networks (GRNs) of biological processes. By modeling GRNs, one would like to gain a deeper understanding of how different cellular phenotypes arise from the same set of underlying genes and how a biological system can be forced to differentiate into a specific phenotype by manipulating the expression of a small set of genes/proteins in the underlying GRN.

Even with an improved understanding of the working of cellular signaling components and technological advancements in designing new drug compounds, it is often not possible to design drug compounds that specifically target only the desired genes/proteins with desired effectiveness. Some of these issues can also be addressed by predicting which elements of the GRNs have to be targeted in order to attain a pre-defined phenotype. The latter problem is formally referred to as Minimal Intervention Sets (MIS) problem in the literature (Karlebach and Shamir, 2010; Samaga et al., 2010). In an MIS problem, one would like to enumerate a list of possible sets of genes/proteins from a given GRN, which when perturbed, can give rise to the desired cellular phenotypes.

A GRN, such as the one in Figure 1A, can be modeled as a Boolean network using the mapping we have introduced earlier in Garg et al. (2009). In the Boolean modeling of a GRN, a node can exist in two expression states: low and high. These two expression states are represented by logic 0 and 1, respectively. A state of the network at a given time instant \( t \) is defined by the expression state of all the nodes at that instant of time. A state of the network evolves over time as defined by the underlying interactions.
A toy GRN representing interactions between a set of genes/proteins. Arrow-headed edges represent activation and circle-headed edges represent inhibiting interactions. (B) MIS patterns to push the systems into a steady state where $T = 1$. For every MIS vector there is at least one mutations that has to be present. The polarity of these mandatory mutations are indicated by red (knock-out) or blue (over-express) colors. In addition, compatible off-target mutations and their polarities (over-expression or knock-out) are also listed for every MIS vector. Genes corresponding to white color in an MIS vector indicate the mutations in these genes have no effect on the corresponding MIS vector. Genes corresponding to gray color in an MIS vector should not be perturbed in any polarity (either by knock-out or over-expression). Else the corresponding MIS vector may not be able to generate the desired steady state.
in the desired final steady state (Line 3 of Algorithm 1). These nodes with fixed polarities are referred to as the root nodes of the network.

Algorithm 2 describes the GRN unrolling function UnrollGRN(). The function UnrollGRN() is called recursively starting from the root node (or target node) \( T \). The GRN is unrolled along a path until a duplicate node is found. At that instance, if all the input nodes to the duplicate node already exist on the unrolled path, then the duplicate node is assigned a new name (with the symbol “∼” over the original node name) and the unrolling process is terminated along this path. Otherwise, the duplicate node is further unrolled until the criteria for terminating the unrolling process is met. In each recursion, a set of nodes on the current path is maintained in the set of already unrolled nodes (labeled as \( aN \)). The current node being unrolled is added to set \( aN \) in Line 5 of Algorithm 2 and the input nodes (labeled as \( g \)) to the current node being unrolled (labeled as \( Sn \)) are checked for duplicacy in Line 7. If the input node \( g \) does not exist in the set \( aN \), then the UnrollGRN() process is repeated for that input node. In Lines 11–13, we check if any of the input nodes \( g \) to the node \( g \) does not belong to the set of duplicate nodes \( aN \), in which case the node \( g \) is further unrolled (Line 15). Otherwise the unrolling process is terminated along the current path by assigning the node ID corresponding to initial state nodes. The orgIndex vector maintains the index ID of all the nodes in the input GRN. The UnrollGRN() process returns a new node ID corresponding to unrolled node counterpart of original node \( S_n \). The new node IDs are generated by incrementing the counter corresponding to original set of nodes in the GRN in the vector indexCount (Line 18 of Algorithm 2). Vector indexCount maintains a count of the number of times a given node in the GRN is duplicated in the unrolling process, and helps ensuring that no two nodes have the same node ID in the unrolled GRN. The unrolled function with new unrolled node IDs corresponding to input nodes to node \( S_n \) and new index of \( S_n \) (i.e., outIndex) is generated in the function composeFunc() (described in Lines 24–30 of Algorithm 2). The composeFunc() duplicates the Boolean function describing the node \( S_n \) in the original GRN and renames the input and output node with new node IDs that are generated in the function UnrollGRN(). An offTargetIndex (in Line 20 of Algorithm 2) is a vector of the set of nodes that contains all nodes that lie in between the current node being unrolled \( S_n \) and the root node \( T \) of the unrolled GRN. The set of nodes in the offTargetIndex are used for specifying compatible off-targets corresponding to each MIS in Algorithm 3. The unrolled network generated by applying the UnrollGRN() function on the GRN in Figure 1A is shown in Figure 2A.

Once the input GRN is unrolled, Algorithm 1 generates the MIS vectors by recursively calling the function genMIS() starting from the unrolled index of target node \( T \) in Line 5 of Algorithm 1. The genMIS() is described in detail in Algorithm 3. The MIS vectors are generated by scanning the unrolled network from the root node (i.e., target node \( T \)) toward the leaf nodes. The function genMIS() is called recursively for the inputs of a given node (specified by currNode in Algorithm 3). The MIS vectors corresponding to input nodes are merged as described in the function mergeMIS(). The merged MIS vectors are combined with the new MIS vector which is generated for the given currNode using the function newMIS(). The mergeMIS() function as described in Algorithm 3, starts by setting Boolean variable flagOR to TRUE for Boolean input-output relationships that should be treated as an OR function (Lines 11–17). If the flagOR variable is TRUE, then the MIS vectors corresponding to input nodes to currNode are

![Figure 2](https://example.com/figure2.png)

**Figure 2**: (A) Unrolled GRN when the node \( T \) has a fixed polarity in steady states. The labels 0 and 1 next to node labels represent polarity propagated from the root node \( T = 1 \) to the leaf nodes in the unrolled networks. (B) Propagation of MIS patterns through an AND gate. (C) Propagation of MIS patterns through an OR gate.
merged using the MIS_OR function (as described in Algorithm 4). Otherwise the input MIS vectors are merged using the MIS_AND function. The newMIS() function, generates a new MIS vector for the currNode. It returns a Boolean vector of length six times the number of number of nodes in the original GRN. The Boolean vector can be divided into three fragments of equal number of bits. The first fragment stores the information corresponding to offTargetIndex nodes, the second fragment stores the information of nodes that should have a specific initial state (i.e., nodes with the symbol “∼”), and the last fragment stores the information regarding the nodes that should be perturbed (i.e., over-expressed or knocked-out). Figure 2A shows the polarity of each node in the unrolled GRN as a result of applying the genMIS() function on the unrolled network.

The MIS_OR() and MIS_AND() are the core functions of our MIS algorithm and ensure minimal and non-conflict properties of generated MIS vectors. Functions MIS_OR() and MIS_AND() merge the list of MIS vectors in a Boolean OR or AND manner as described in Algorithm 4. The MIS_OR() function checks for setwise containment of an MIS vector from one input list in another input list (Lines 5 and 7) and maintains the minimal property of generated MIS vectors by dropping MIS patterns that are not minimal in Lines 6 and 8 of Algorithm 4. The MIS_AND() function, checks for conflict between the MIS vectors in two input lists (Lines 23–25). Before merging any two MIS vectors, it checks if the resulting MIS vector would give rise to a conflicting perturbations (i.e., the same node over-expressed in one input MIS and knocked-out in the other MIS). Any such MIS vectors are dropped from the merged list of two input MIS vectors. Small examples further demonstrating the MIS_AND() and MIS_OR() functions are described in Figures 2B,C, respectively. In Figure 2B, the MIS pattern at the input node E1, which requires two perturbations involving over-expression of node B and knock-down of node Q is dropped from the merged MIS list at the output, as it is not a minimal pattern and can be replaced by the minimal MIS at the input node B1, which only requires one perturbation involving over-expression of node B.

Function genMIS() in Line 5 of Algorithm 1 returns minimal perturbation sets obtained by traversing the unrolled GRN. However, presence of feedback loops may prevent some of these MIS patterns from generating the desired steady state in actual simulations. Therefore, in order to ensure that the generated MIS can indeed give rise to desired steady state, we simulate the generated MIS patterns using the the function simulateMIS(), which essentially uses the Algorithm we developed in Garg et al. (2008) to model gene perturbations and checks if the resulting steady state are indeed the ones that are expected from the comp_MIS() function. The simulateMIS() function also checks for minimality of generated MIS patterns. These two additional steps, ensure that the list of MIS patterns resulting from comp_MIS() are indeed a minimal list of perturbed genes that can push the system into a desired cellular phenotype.

3. RESULTS
We show the application of our algorithms on T-Helper cell and Growth vs. Apoptosis gene regulatory networks.

3.1. T-HELPER GRN
We have previously demonstrated existence of three steady states in a Boolean model of the T-helper GRN [Figures 3A,B, (Garg et al., 2008)]. These three steady states correspond to molecular profiles observed in Th0, Th1, and Th2 cells, which can be distinguished at the molecular level by their pattern of cytokine secretion that play a central role in cell mediated immunity (Th1 cells) and humoral responses (Th2 cells).

When we applied our MIS algorithm on the GRN of Figure 3A, it reported 22 MIS patterns that can drive the Th0 steady state into Th1 steady state. Out of these 22 MIS patterns, 8...
patterns (Figure 3C) do not have any pre-requisite on initial state of the network and can lead to Th1 steady state independently of the initial state of the network. The remaining 14 MIS (Figure 3D) would lead to Th1 steady state only if the network is initially in the Th0 state. It is interesting to note that all the MIS patterns are composed of either a single or at most two simultaneous perturbations. Most of the gene perturbation combinations among the 14 MIS patterns in Figure 3D are well-known gene perturbations for biasing the T-Helper cellular differentiation toward Th1 cell types and have been used as target for well-known drug molecules to enhance immune response. The existing methods to find MIS patterns, which do not take into account initial state of the network, will only be able to identify 8 MIS patterns listed in Figure 3C. All these 8 MIS patterns require either T-bet over-expression or GATA3 knock-down in combination with few other perturbations. However, both T-bet and GATA3 are known to be difficult to target using drug compounds and can only be suppressed or activated by using siRNAs or through indirect stimulation of upstream cytokines (Weigmann and Neurath, 2002; Usui et al., 2003; Liberman et al., 2009, 2012; Chou et al., 2010). More interesting perturbations identified by the remaining 14 MIS patterns in Figure 3D highlight the importance of considering initial state of the GRN in the algorithms presented in this manuscript.

The Th1 cells produce IFNg as their signature cytokine secretion profile. Secreted IFNg can bind to its receptor IFNgR present on the Th1 cell surface leading to activation of signaling pathways involved in Th1 cell differentiation and maintenance of Th1 state (Novelli et al., 1997; Murphy and Reiner, 2002). The MIS patterns, MISInit 8 and 9, in Figure 3D represent over-expression of IFNg or IFNgR, respectively, that are required for differentiation of Th0 cells to Th1 phenotype. The MIS pattern MISInit 3 represents activation of T cell receptor (TCR) through external ligands, which can lead to transcriptional expression of various cytokines involved in T cell differentiation. The remaining MIS patterns represent other well-known modes of differentiating Th0 to Th1 cell types either through production of IFNg in T helper cells or by activating proteins downstream of IFNg signaling (Mendoza, 2005; Mendoza and Xenarios, 2006). These modes of activation include expression of external ligands such as IL-18, IL-12, and IFN-b (MISInit 5, 11 and 14), or by directly stimulating their target receptors IL-18R, IL-12R, and IFN-bR (MISInit 6, 1 and 12), increased expression of intermediate Kinases IRAK and JAK1 (MISInit 7 and 10), or by expressing transcription factors STAT1, STAT4, or NFAT (MISInit 13, 2 and 4). The compatible off-target perturbations in the MIS patterns listed in Figure 3D, are mostly related to down-regulating the expression of ligands and other proteins involved in maintenance of Th2 cell type, and differentiation of Th0 to Th2 cell types (Mendoza, 2005; Mendoza and Xenarios, 2006).

3.2. GROWTH vs. APOPTOSIS GRN
We identified key proteins that are known to play a crucial role in maintaining the balance between growth and apoptosis signals in the cancer pathways. We then constructed the GRN representing interactions between these proteins by identifying experimentally validated functions defining these interactions from the literature. Boolean formulation of these interactions are summarized in the GRN in Figure 4A and literature evidence supporting these interactions are listed in Supplementary Table 1. The GRN can be divided among four modules—PI3K, AKT, p53, and mTORC1—to represent four sub-networks that are mostly comprised of linear paths (or no feedback loops). These four modules interact with each other through positive and negative interactions giving rise to multiple feedback loops in the resulting GRN. As a result of these feedback loops, the GRN in Figure 4A gives rise to four Boolean attractors when simulated using our Boolean modeling toolbox genYsis (Garg et al., 2008). Both the attractors show oscillating apoptosis and growth signals demonstrating the ability of the pathway to self-regulate the cellular growth. Figure 4B shows the average growth and apoptosis signals in these attractors. An equal distribution of states displaying high growth and high apoptosis in these Boolean attractors highlight the balance maintained by the feedback loops in the constructed GRN.

We modeled the impact of two well-known cancer mutations in genes p53 and TSC2 on the attractors of GRN in Figure 4A. The p53 gene is one of the most frequently mutated genes in human cancers (Bourdon, 2007; Vousden and Lane, 2007). The p53 mutation leads to constitutive inhibition of its functionality and suppresses apoptosis signals, leading to uncontrolled cell growth or proliferation. Our simulation results also capture this effect of p53 mutation, wherein the average apoptosis signals in the attractor states decreases to 0 and growth signals stay high as compared to attractors in wild-type GRN (Figure 4B). We also modeled the impact of mTORC1 and PI3K inhibition (representing the affect of drug compounds such as Rapamycin and Wortmannin, respectively) on restoring the balance of growth vs. apoptosis in the presence of p53 mutation (Figure 4B). From the simulation results in Figure 4B, it is clear that while PI3K inhibition can balance the p53 mutation by completely suppressing growth signals, mTORC1 inhibition can only moderately decrease the constitutive growth signals resulting from p53 mutations. This can be attributed to PI3K inhibitor acting upstream of mTORC1 in order to block all the three distinct pathways leading to cell division and protein production (Welsh et al., 1997; Mendez et al., 2001; Liang et al., 2003). On the contrary, in the presence of mutation in TSC2 gene (leading to loss of function of TSC2 and high growth vs. apoptosis signals in attractor states), simulation results show that growth signals cannot be regulated with PI3K inhibitors (Figure 4B). However, mTORC1 inhibitor can counter the effect of TSC2 mutation by restoring the growth signals to low level of wild-type steady state levels. It has been shown in the experiments that cells treated with PI3K inhibitors show improved apoptosis response in a TSC2 expression dependent manner (Kob et al., 2005). On the other hand, greatly elevated mTORC1 signaling has been reported in the presence of TSC2 mutation, which can be restored with mTORC1 inhibitors (Kim et al., 2011).

Having established a confidence in our constructed GRN for modeling the balance between growth and apoptosis signals in cancer pathways, we next computed MIS patterns that can force the dynamics of the network to constitutive high growth and constitutive low apoptosis signals. Our algorithm reported a total of 54 MIS patterns, none of which requires the system to be in a specific initial state (Figure 4C). Most of the perturbations
(over-expression or knock-out) defined by these MIS patterns are well-known mutations in cancer cells. Most of the MIS patterns listed in Figure 4C require two or more simultaneous perturbations, highlighting that highly malignant cell phenotypes often comprise of multiple mutations. For example, MIS patterns that contain either p53 or TSC mutations also require mutations in other parts of the pathway to push the system into desired steady state. This observation is also supported from the simulation results in Figure 4B, where these mutations alone cannot give rise to constitutively high growth and low apoptosis signals in steady states. Another perturbation vector given by MIS 19 represents the over-activated AKT protein, which may explain a well-known mutation in AKT that leads to hyper-phosphorylated form of AKT in cancer cells.

We next screened these MIS patterns against a database of miRNA and their target gene pairs in human genome, which we compiled using four different miRNA target prediction algorithms [miRANDA (John et al., 2004), TargetScan (Lewis et al., 2005), mirDB (Wang and El Naqa, 2008) and RNA22 (Miranda et al., 2006)] to predict miRNA-target pairs and combined these with experimentally validated pairs [TarBase, (Papadopoulos et al., 2009)]. In silico miRNA target prediction algorithms suffer high rates of type I and type II errors (Watanabe et al., 2007; Zhang and Verbeek, 2010). Therefore, in order to increase the quality of the predictions we considered only those predictions that were supported by at least two different prediction algorithms, or were experimentally validated. We restricted the application of our algorithm to 464 miRNA cancer type pairs that were collected from different experimental studies in literature and have been shown to be disregulated (either up-regulated or down-regulated) in various different human cancers or cancer cell lines (Sinha et al., 2008).

If a given miRNA targets a gene identified as over-expressed in an MIS pattern, then we define the polarity of dis-regulation of that miRNA as down-regulated. Similarly, a given miRNA is said to be up-regulated if its target gene is knocked-down in the MIS pattern. When disregulation of only a single miRNA is assumed to lead to cancerous behavior (i.e., only looking at MIS patterns with all knock-down genes or all over-expressed genes), our algorithm predicts 33 up-regulated and 20 down-regulated miRNAs. The predicted miRNAs, their polarity, corresponding cancer types and supporting MIS patterns are listed in Supplementary Table 2. Out of these predicted miRNAs, 38 miRNAs were found to have the same polarity as has been seen in published experimental results and 15 predicted miRNAs did not match the polarity observed in published experiments (Sinha et al., 2008). However, we believe that the small list of miRNA with mismatched polarity may arise from the fact that two or more miRNA may be simultaneously perturbed in the cancer types studied in published results and require analyzing the effect of disregulation in more than one miRNA along with our list of MIS patterns.
Algorithm 1: Algorithm for generating all MIS vectors

```plaintext
1 comp_MIS(G, T, outPol)
2 begin
3    targetIndex = unrollGRN(G, T, uG)
4    MIS = genMIS(uG, polarity, targetIndex)
5    MISim = simulateMIS(MIS, G, T)
6    return MISim
7 end
```

Algorithm 2: Algorithm for unrolling the GRN.

```plaintext
1 UnrollGRN(G(V, f), aN, S_n, uG)
2 begin
3    for i = 1 to |V| do
4       newIndex[i] = -1
5       // Add S_n to visited nodes on current path
6    aN = aN U S_n
7    for g in Inp(S_n) do
8       // Check if Node g is already unrolled
9       if g not in aN then
10          flagUnroll = 0
11          // Check if all inputs to Node g are
12          for g in Inp(g) do
13             if g not in aN then
14                flagUnroll = 1
15       if flagUnroll = 1 then
16          newIndex[g] = UnrollGRN(G, aN, g)
17          else
18             newIndex[g] = origIndex[g]
19       outIndex = indexCount[S_n] + 1
20       composeFunc(G, S_n, newIndex[], outIndex, uG)
21       aN = aN U S_n
22       // Return new node corresponding to S_n
23       return outIndex
24    end
25 end
```

Algorithm 3: Algorithm for generating MIS vectors

```plaintext
1 genMIS(uG, currNode, polarity)
2 begin
3    MISim = mergeMIS(uG, currNode, polarity)
4    MIScurr = newMIS(uG, currNode, polarity)
5    MISout = MIS-OR(MIScurr, MISim)
6    return MISout
7 end
8 mergeMIS(uG, currNode, polarity)
9 begin
10    flagOR = 0
11    if polarity[currNode] = 1 then
12       if Bool_func(currNode, uG) is of type OR then
13          flagOR = 1
14       else
15          // For output 1 treat as AND gate
16       else if polarity[currNode] = 0 then
17          if Bool_func(currNode, uG) is of type AND then
18             // For output 0 treat as OR gate
19             flagOR = 1
20       if flagOR = 1 then
21          MISout = initMISVector(0)
22          for g in InpNodes(Bool_func(currNode, uG)) do
23             polarity[g] = polarity[currNode]
24             MIStmp = genMIS(uG, g, polarity)
25             MISout = MIS-OR(MISout, MIStmp)
26          else
27             MISout = initMISVector(1)
28             for g in InpNodes(Bool_func(currNode, uG)) do
29                polarity[g] = polarity[currNode]
30                MIStmp = genMIS(uG, g, polarity)
31                MISout = MIS-AND(MISout, MIStmp)
32          end
33          return MISout
34       newMIS(uG, currNode, polarity)
35 begin
36       currNodeIndex = origIndex[currNode]
37       MIStmp = initMISVector(1)
38       if currNode = initial_state_node then
39          index = 4
40       else
41          index = 2
42       if polarity[currNode] = 0 then
43          MIStmp[index * currNodeIndex] = 0
44       else
45          MIStmp[index * currNodeIndex + 1] = 0
46       for g in offTargetIndex[currNode] do
47          nodeIndex = origIndex[g]
48       if polarity[g] = 0 then
49          MIStmp[6 * nodeIndex] = 0
50       else
51          MIStmp[6 * nodeIndex + 1] = 0
52          return MIStmp
53    end
```

FIGURE 5 | Algorithms for computing the MIS patterns given a Boolean GRN and the profile of desired steady states.
4. DISCUSSION

In this manuscript, we have presented an efficient approach to generate a list of minimal sets of gene perturbations that can push the dynamics of GRN into a specific steady state (representing a given cellular phenotype). Our algorithm for computing MIS patterns follows a branch and bound approach, where the unrolled network is scanned for MIS patterns in a depth-first manner. If the network being simulated has many feedback loops, then the current implementation of Algorithms proposed in this manuscript may be inefficient due to the large size of the unrolled network (Supplementary Table 3). However, the unrolled network can be scanned for MIS patterns in an efficient manner by a parallel implementation of the function genMIS(). The algorithms proposed here can be useful in various experimental settings where one would like to enumerate multiple options to regulate the dynamics of GRNs. We demonstrate one such application of our algorithm with respect to T-Helper GRN. The T-helper GRN shown in Figure 3A has been previously shown to effectively model the precursor Th0 cells and effector Th1 and Th2 cells (Mendoza and Xenarios, 2006). Understanding the molecular mechanisms that regulate the differentiation process from Th0 toward either Th1 or Th2 is very important, since an immune response biased toward the Th1 phenotype result in the appearance of autoimmune diseases, and an enhanced Th2 response can originate allergic reactions (Murphy and Reiner, 2002; Agnello et al., 2003). We previously demonstrated how one can efficiently simulate the effect of gene perturbations in the T-Helper GRN (Garg et al., 2008, 2009). However, it would be of utmost interest to generate a list of possible perturbations that can transition a cell from one steady state to another. For example, MIS patterns required to transition a cell from Th0 to Th1 cell state would indicate different possible treatments to stimulate the auto-immune response of the body. The MIS patterns generated by our algorithm captures some of the well-known perturbations that have been experimentally validated to differentiate T-Helper cells into Th1 phenotype. Gene expression levels can often exist at more than two expression states. The algorithms proposed here can be extended to multiple expression levels of nodes (such as Low/Medium/High) by encoding them into Boolean rules (Garg et al., 2007).

The GRN presented here for modeling the growth vs. apoptosis signals in cancer pathways, consists of various feedback loops that ensures the balance between the growth and apoptosis pathways. It is a well-accepted fact that mutations leading to permanent loss or gain of function of genes in the feedback loops of signaling pathways can disregulate the delicate balance between pro-growth and pro-apoptopic cellular signals. If these mutations are in a favor of pro-growth or anti-apoptosis signals, then a cell is said to have a pre-disposition toward uncontrolled growth (and hence proliferation). In such a scenario, a cell (carrying mutations) undergoes uncontrolled proliferation and can subsequently lead to the formation of tumors. Most cancer therapies either try to restore the normal expression of mutated genes directly or counteract the impact of mutated genes by targeting other genes (or proteins) in the pathway. Understanding how different genes (and proteins) regulate each other in these pathways is therefore of major interest in the development of treatments for various cancers. Here, we show how the impact of such mutations can be studied with respect to our proposed GRN by modeling p53 and TSC mutations. In Figure 4B, differential response of therapies targeting PI3K and mTORC1 nodes in the presence of p53 and TSC mutations indicate the importance of taking into account gene mutations when deciding upon the drug therapies. Whereas, only single mutations are simulated in Figure 4B, in a real world scenario, multiple mutations can be present simultaneously. In such a scenario, activity of multiple genes/proteins may have to be targeted for the drug therapy to be effective. Such compatible sets of genes/proteins which would be suitable for

![Algorithm 4: Algorithm for combining list of MIS vectors.](image-url)
manipulation by one or more drug compounds can be quickly discovered by enumerating all MIS vectors of a GRN. Here, we demonstrate one such application by listing MIS vectors that can lead to high growth and low apoptosis signals in steady state of GRN of Figure 4A.

We also demonstrate an example of how the MIS patterns generated by our algorithm could be used to predict miRNAs which, when over or under-expressed, could lead to a cancerous phenotype of cells. Aberrant expression of miRNAs is known to play a major role in the development of cancers due to their importance in various biological processes such as cellular proliferation and apoptosis (Subramanian and Steer, 2010; Yu et al., 2010). However, despite much interest in this area, the mechanism of action of miRNAs in disease remains largely unknown. The current view is that miRNAs have evolved to coordinate regulate cellular processes; thus, whilst the number of miRNAs is relatively small compared to the number of genes (~<1000 in humans, (Griffiths-Jones et al., 2008)), complex regulation mechanisms can be achieved through the combined actions of multiple miRNAs acting in a temporal and spatial manner. In our analysis, of 53 miRNAs predicted to influence the cancerous phenotype, 38 (~71%) show the same polarity as published data, demonstrating the potential of this approach. It remains to be seen whether the remaining 15 predicted miRNAs that do not show the same polarity as published data, have an impact on defining the cancerous phenotype.

In addition to applications shown in this manuscript, such as discovering minimal functional mutations in a disease phenotype and screening drug compound library, one can use the MIS vectors to guide experimental setups. Normally, in the absence of information of MIS patterns, one would have to try all possible combinations \(3^N\) of \(N\) different perturbations (compounds or treatments) of genes/proteins in a given signaling pathway, which can quickly lead to a large number of experiments for even a modestly large GRN. Even when number of simultaneous perturbations to test are restricted to two, it becomes unfeasible to perform all possible two-combinations of available compounds. In such a scenario, MIS patterns generated by our algorithm can be very useful. The number of MIS patterns that can lead to a desired steady state can be significantly smaller than the number of all possible perturbations as has been seen from the application of our algorithm on the T-Helper and Apoptosis vs. Growth GRNs (Figures 3, 4 and Supplementary Table 3). Generating such MIS patterns algorithmically using an approach presented here can therefore reduce both the number of simulations and experiments required, and can provide model-driven insight into which subsets of genes should be knocked-down and over-expressed to obtain a desired cellular phenotype.

ACKNOWLEDGMENTS

Abhishek Garg and Kartik Mohanram developed the algorithm to compute MIS patterns, Abhishek Garg and Julien Dorier performed simulations, Abhishek Garg and Alessandro Di Cara performed the literature survey and compiled the GRN for growth vs. apoptosis model, Gwendoline Degueurce, and Mark Ilberson wrote the code and compiled the list of miRNAs and their target genes, Abhishek Garg and Ioannis Xenarios wrote the manuscript and designed the study.

FUNDING

European Commission FP6 project ENFIN (Experimental Network for Functional INtegration -LSHG-CT-2005-518254). Computations were performed at the Vital-IT Center of the Swiss Institute of Bioinformatics. Swiss Federal Government through the Federal Office of Education Science and Innovation (SERI) Postdoc Fellowship (RPF) Program for Julien Dorier.

SUPPLEMENTAL MATERIAL

The Supplementary Material for this article can be found online at: http://www.frontiersin.org/10.3389/fphys.2013.00361/abstract

Supplementary Table 1 | List of Boolean interactions in the Growth vs. Apoptosis GRN along with supporting references.

Supplementary Table 2 | List of predicted miRNA with matching (and mis-matching) polarity, Cancer types, and supporting MIS IDs.

Supplementary Table 3 | Simulation results of computing MIS patterns on Random Networks of varying complexities.

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Conflict of Interest Statement: The authors declare that the research was conducted in the absence of any commercial or financial relationships that could be construed as a potential conflict of interest.

Received: 14 August 2013; paper pending published: 31 August 2013; accepted: 22 November 2013; published online: 17 December 2013.

Citation: Garg A, Mohanram K, Di Cara A, Degueure G, Ibberson M, Dorier J and Xenarios I (2013) Efficient computation of minimal perturbation sets in gene regulatory networks. Front. Physiol. 4:361. doi: 10.3389/fphys.2013.00361

This article was submitted to Systems Biology, a section of the journal Frontiers in Physiology.

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