Limiting Absorption Principle and Well-Posedness for the Time-Harmonic Maxwell Equations with Anisotropic Sign-Changing Coefficients

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Abstract: We study the limiting absorption principle and the well-posedness of Maxwell equations with anisotropic sign-changing coefficients in the time-harmonic domain. The starting point of the analysis is to obtain Cauchy problems associated with two Maxwell systems using a change of variables. We then derive a priori estimates for these Cauchy problems using two different approaches. The Fourier approach involves the complementing conditions for the Cauchy problems associated with two elliptic equations, which were studied in a general setting by Agmon, Douglis, and Nirenberg. The variational approach explores the variational structure of the Cauchy problems of the Maxwell equations. As a result, we obtain general conditions on the coefficients for which the limiting absorption principle and the well-posedness hold. Moreover, these new conditions are of a local character and easy to check. Our work is motivated by and provides general sufficient criteria for the stability of electromagnetic fields in the context of negative-index metamaterials.

Contents

1. Introduction ........................................ 146
2. Statement of the Main Results ...................... 147
3. Fourier Approach for the Cauchy Problems ........ 152
   3.1 Preliminaries .................................. 152
   3.2 Proof of Theorem 2.1 ......................... 157
4. Variational Approach for the Cauchy Problems .... 159
   4.1 Some useful lemmas ......................... 159
   4.2 Proof of Theorem 2.2 ....................... 169
   4.3 Some applications of Theorem 2.2 ........... 172
A. Proof of Proposition 3.1 ......................... 174
1. Introduction

Negative-index metamaterials are artificial structures whose refractive index has a negative value over some frequency range. Their existence was postulated by Veselago in 1964 [35] and confirmed experimentally by Shelby, Smith, and Schultz in 2001 [33]. Negative-index metamaterial research has been a very active topic of investigation not only because of potentially interesting applications, but also because of challenges involved in understanding their peculiar properties due to the sign-changing coefficients in the equations modeling the phenomena.

In this paper, we study the stability of electromagnetic fields in the context of negative-index metamaterials from a mathematical point of view. More precisely, we study the limiting absorption principle and the well-posedness of Maxwell equations with anisotropic sign-changing coefficients in the time-harmonic domain. Let $D$ be an open, bounded subset of $\mathbb{R}^3$ of class $C^1$ and let $\varepsilon^+, \mu^+$ be defined in $\mathbb{R}^3 \setminus \bar{D}$, and $\varepsilon^-, \mu^-$ be defined in $D$ such that $\varepsilon^+, \mu^+, -\varepsilon^-, \mu^-$ are real, symmetric, uniformly elliptic matrix-valued functions. Set, for $\delta \geq 0$,

$$
(\varepsilon_\delta, \mu_\delta) = \begin{cases} 
(\varepsilon^+, \mu^+) & \text{in } \mathbb{R}^3 \setminus \bar{D}, \\
(\varepsilon^- + i\delta I, \mu^- + i\delta I) & \text{in } D.
\end{cases}
$$

(1.1)

Here and in what follows, $I$ denotes the $(3 \times 3)$ identity matrix and $\bar{D}$ denotes the closure of $D$. We also denote $B_R$ the open ball in $\mathbb{R}^3$ centered at the origin and of radius $R > 0$. We assume as usual that for some $R_0 > 0$, $D \subset B_{R_0}$, $(\varepsilon^+, \mu^+) = (I, I)$ in $\mathbb{R}^3 \setminus B_{R_0}$, and

$$
\varepsilon^+, \mu^+, \varepsilon^-, \mu^- \text{ are piecewise } C^1.
$$

(1.2)

Given $\delta > 0$ and $J \in [L^2(\mathbb{R}^3)]^3$ with compact support, let $(E_\delta, H_\delta) \in [H_{\text{loc}}(\text{curl}, \mathbb{R}^3)]^2$ be the unique radiating solution of the Maxwell equations

$$
\begin{cases}
\nabla \times E_\delta = i\omega \mu_\delta H & \text{in } \mathbb{R}^3, \\
\nabla \times H_\delta = -i\omega \varepsilon_\delta E + J & \text{in } \mathbb{R}^3.
\end{cases}
$$

(1.3)

Physically, $\varepsilon_\delta$ and $\mu_\delta$ describe the permittivity and the permeability of the considered medium, $\omega$ is the frequency, $D$ is a plasmonic structure of negative-index metamaterials and $i\delta I$ describes its loss, and $J$ is the density of charge.

The goals of this paper are to derive general conditions on $(\varepsilon_0, \mu_0)$ for which $(E_\delta, H_\delta)$ are bounded and to characterize its limit. The corresponding scalar version of Maxwell equations in the frequency regime is the Helmholtz equation. The well-posedness of the Helmholtz equation with sign-changing coefficients has been studied intensively, with the initial investigations initiated by Costabel and Stephan [9]. Later, the well-posedness and the Fredholm character were investigated using the integral method [32] and the $T$-coercivity method [5, 7] (and the references therein). Recently, one of the authors [22] obtained general results on the limiting absorption principle and the well-posedness for the Helmholtz equation. His approach is based on a priori estimates using Fourier and variational approaches for Cauchy problems associated with two elliptic equations derived naturally in this context. The use of the Cauchy problems in the context of the Helmholtz equations with sign-changing coefficients originally appeared in [18]. The theory behind the Helmholtz equations is now almost complete and is the state-of-the-art in this area.

There is very little in the mathematical literature about the stability of the (full) Maxwell equations with sign-changing coefficients. The only known work in this direction that could help us is due to Bonnet-Ben Dhia, Chesnel, and Ciarlet [6] using the
T-coercivity method. They considered a bounded setting with isotropic coefficients and obtained the well posedness outside a discrete set of ω under requirements on ε and μ of a non-local nature, which is generally difficult to check. The goal of this paper is to fill this gap by developing the approach in [22] for the Maxwell equations. The idea is first to obtain the Cauchy problems associated with two Maxwell systems via a change of variables and then to derive a priori estimates for these Cauchy problems. Two approaches are proposed to obtain these estimates. The Fourier approach involves the complementing conditions for Cauchy problems associated with two elliptic equations, which were studied in more general setting by Agmon, Douglis, and Nirenberg [2]. The variational approach explores the variational structure of the Cauchy problems. In comparison with the acoustic setting [22], new ideas are required to handle the complex structure of the Maxwell equations and to be able to apply the theory on complementing conditions for elliptic systems. In particular, various forms of the Poincaré lemma and the Helmholtz decomposition are used with a suitable implementation of local charts to avoid imposing topological conditions. As a result, we obtain very general conditions on the (anisotropic) coefficients to ensure the well-posedness and the limiting absorption principle. Moreover, these new conditions are local and easy to check. For example, the well-posedness and the limiting absorption principle hold under the condition (i) (ε+, −ε−) and (μ+, −μ−) are smooth near the interface ∂D and both satisfy the complementary condition on the interface (Theorem 2.1 and Corollary 2.1), or (ii) ε and μ are isotropic near the interface and |ε+ + ε−| and |μ+ + μ−| are away from 0 there (Theorem 2.2 and Corollary 4.1), or (iii) ε+, −ε−, μ+, μ− are equal to I near the interface and the interface is (strictly) convex (Corollary 4.2).

Our work thus provides general sufficient criteria for the stability of electromagnetic fields in the context of negative-index metamaterials in the electromagnetic setting. This work also clarifies the role of the complementary conditions considered in [24] in ensuring the resonance associated with negative-index metamaterials appeared in their various applications, such as superlensing [24] and cloaking [25, 27], in the electromagnetic setting. Previous mathematical works on applications of negative-index metamaterials, such as superlensing, cloaking using complementary media, cloaking via anomalous localized resonance for a source or for an object, can be found in [3, 13, 14, 16, 19–21, 23, 26–28, 31], respectively, and the references therein.

2. Statement of the Main Results

The starting point of our analysis is to obtain Cauchy problems associated with two Maxwell systems using a change of variables. A central point of the analysis is then to derive a priori estimates for these Cauchy problems. We first use a Fourier approach involving the theory of complementing conditions as developed by Agmon, Douglis, and Nirenberg [2]. Given a unit vector e ∈ R3, denote

\[ \mathbb{R}^3_{e,+} = \left\{ x \in \mathbb{R}^3; \langle x, e \rangle > 0 \right\} \quad \text{and} \quad \mathbb{R}^3_{e,0} = \left\{ x \in \mathbb{R}^3; \langle x, e \rangle = 0 \right\}. \]

Here and in what follows, \( \langle \cdot, \cdot \rangle \) denotes the standard scalar product in \( \mathbb{R}^3 \) or \( \mathbb{C}^3 \). The definition of the complementing condition for the Cauchy problem of two elliptic equations is as follows

**Definition 2.1** (Agmon et al. [2]). Two constant, positive, symmetric matrices \( A_1 \) and \( A_2 \) are said to satisfy the (Cauchy) complementing boundary condition with respect to
direction \( e \in \partial B_1 \) if and only if for all \( \xi \in \mathbb{R}^3_{e,0}[0] \), the only solution \((u_1(x), u_2(x))\) of the form \( (e^{i(y,\xi)} v_1(t), e^{i(y,\xi)} v_2(t)) \) with \( x = y + te \) where \( t = \langle x, e \rangle \), of the following system
\[
\begin{align*}
div(A_1 \nabla u_1) &= div(A_2 \nabla u_2) = 0 \text{ in } \mathbb{R}^3_{e,0}, \\
u_1 &= u_2 \text{ and } A_1 \nabla u_1 \cdot e = A_2 \nabla u_2 \cdot e \text{ on } \mathbb{R}^3_{e,0},
\end{align*}
\]
that is bounded in \( \mathbb{R}^3_{e,0} \) is \((0, 0)\).

**Remark 2.1.** Agmon et al. [2] (see also [1]) considered the complementing conditions for a general elliptic system and derived properties for them. The special case given in the above definition found a particular interest in the context of the Helmholtz equations with sign-changing coefficients (see [22]).

Denote
\[ \Gamma = \partial D, \]
and, for \( \tau > 0 \), set
\[ D_\tau = \left\{ x \in D; \text{dist}(x, \Gamma) < \tau \right\} \quad \text{and} \quad D_{-\tau} = \left\{ x \in \mathbb{R}^3 \setminus \bar{D}; \text{dist}(x, \Gamma) < \tau \right\}. \]

For the Fourier approach, we prove the following result:

**Theorem 2.1.** Let \( 0 < \delta < 1, J \in [L^2(\mathbb{R}^3)]^3 \) with supp \( J \subseteq B_{R_0} \), and let \((E_{\delta}, H_{\delta}) \in [H^1_{\text{loc}}(\text{curl}, \mathbb{R}^3)]^2 \) be the unique radiating solution of \((1.3)\). Assume that \( \epsilon^+, \mu^+ \in C^1(D_{-\tau}), \epsilon^-, \mu^- \in C^1(D_{\tau}) \) for some \( \tau > 0 \), and \((\epsilon^+, -\epsilon^-)(x) \) and \((\mu^+, -\mu^-)(x) \) satisfy the (Cauchy) complementing conditions with respect to the unit normal vector \( v(x) \) for all \( x \in \Gamma \). Then
\[
\| (E_{\delta}, H_{\delta}) \|_{L^2(B_{R})} \leq CR \| J \|_{L^2(\mathbb{R}^3)} \quad \forall \ R > 0, \tag{2.1}
\]
for some positive constant \( C_R \) independent of \( \delta \) and \( J \). Moreover, \((E_{\delta}, H_{\delta})\) converges to \((E_0, H_0)\) strongly in \([L^2_{\text{loc}}(\mathbb{R}^3)]^6\) as \( \delta \to 0 \), where \((E_0, H_0) \in [H^1_{\text{loc}}(\text{curl}, \mathbb{R}^3)]^2 \) is the unique radiating solution of \((1.3)\) with \( \delta = 0 \). As a consequence, we have
\[
\| (E_0, H_0) \|_{L^2(B_{R})} \leq CR \| J \|_{L^2(\mathbb{R}^3)} \quad \forall \ R > 0. \tag{2.2}
\]

Let \( \Omega \) be an open set of \( \mathbb{R}^3 \). Given \((u_n) \subseteq L^2_{\text{loc}}(\Omega) \) and \( u \in L^2_{\text{loc}}(\Omega) \), one says that \( u_n \) converges to \( u \) in \( L^2_{\text{loc}}(\Omega) \) if \( u_n \) converges to \( u \) in \( L^2(K) \) for every compact subset \( K \) of \( \Omega \). Recall that, for \( \omega > 0 \), a solution \((E, H) \in [H^1_{\text{loc}}(\text{curl}, \mathbb{R}^3 \setminus B_R)]^2 \), for some \( R > 0 \), of the Maxwell equations
\[
\begin{align*}
\nabla \times E &= i\omega H \quad \text{in } \mathbb{R}^3 \setminus B_R, \\
\nabla \times H &= -i\omega E \quad \text{in } \mathbb{R}^3 \setminus B_R,
\end{align*}
\]
is called radiating if it satisfies one of the (Silver-Müller) radiation conditions
\[
H \times x - |x|E = O(1/|x|) \quad \text{or} \quad E \times x + |x|H = O(1/|x|) \quad \text{as } |x| \to +\infty.
\]
Here and in what follows, for \( \alpha \in \mathbb{R} \), \( O(|x|^\alpha) \) denotes a quantity whose norm is bounded by \( C|x|^\alpha \) for some constant \( C > 0 \). One also denotes
\[
H(\text{curl}, \Omega) = \left\{ u \in [L^2(\Omega)]^3; \nabla \times u \in [L^2(\Omega)]^3 \right\},
\]
Proposition 3.1, whose proof is given in the appendix. Proposition 2.1 below). The optimality of the complementing conditions is discussed in
is new, and its discovery makes the required conditions on
to the pair of permittivity and permeability. To the best of our knowledge, this insight
conditions for the Cauchy problems associated with two elliptic equations corresponding
Cauchy problem associated with two Maxwell systems follows from the complementing
of tools and results, such as Poincaré’s lemma, the Helmholtz decomposition for both
electric and magnetic fields, the analysis on the complementing conditions and duality
arguments. From the analysis, we derive that the complementing conditions for the Cauchy problem associated with two Maxwell systems follows from the complementing
conditions for the Cauchy problems associated with two elliptic equations corresponding
to the pair of permittivity and permeability. To the best of our knowledge, this insight
is new, and its discovery makes the required conditions on $\epsilon$ and $\mu$ easy to check (see
Proposition 2.1 below). The optimality of the complementing conditions is discussed in
Proposition 3.1, whose proof is given in the appendix.

To check the complementing condition, one can use its following algebraic charac-
terization (see [22, Proposition 1]).

**Proposition 2.1.** Let $e \in \partial B_1$, and let $A_1$ and $A_2$ be two constant, positive, symmetric matrices. Then $A_1$ and $A_2$ satisfy the (Cauchy) complementing condition with respect to $e$ if and only if

$$\langle A_2 e, e \rangle \langle A_2 \xi, \xi \rangle - \langle A_2 e, \xi \rangle^2 \neq \langle A_1 e, e \rangle \langle A_1 \xi, \xi \rangle - \langle A_1 e, \xi \rangle^2 \quad \forall \xi \in \mathbb{R}^3_{\epsilon,0} \setminus \{0\}.$$ 

In particular, if $A_2 > A_1$, then $A_1$ and $A_2$ satisfy the complementing condition with respect to $e$.

In this paper, for two $(3 \times 3)$ matrices $A$ and $B$, the notation $A > B$ means that
$\langle Ax, x \rangle > \langle Bx, x \rangle$ for all $x \in \mathbb{R}^3 \setminus \{0\}$. A similar convention is used for $A \geq B$. As a direct consequence of Theorem 2.1 and Proposition 2.1, one obtains

**Corollary 2.1.** Let $0 < \delta < 1$, $J \in [L^2(\mathbb{R}^3)]^3$ with $\text{supp } J \subset B_{R_0}$, and let $(E_\delta, H_\delta) \in [H_{\text{local}}(\text{curl, } \mathbb{R}^3)]^2$ be the unique radiating solution of (1.3). Assume that $\epsilon^+, \mu^+ \in C^1(\bar{D}_-\tau)$ and $\epsilon^-, \mu^- \in C^1(\bar{D}_\tau)$ for some $\tau > 0$, and for each connected compo-
nent of $\Gamma$,

$$\left(\epsilon^+ \geq -\epsilon^- + cI \quad \text{or} \quad -\epsilon^- \geq \epsilon^+ + cI\right),$$

and

$$\left(\mu^+ \geq -\mu^- + cI \quad \text{or} \quad -\mu^- \geq \mu^+ + cI\right),$$

for some $c > 0$. Then

$$\| (E_\delta, H_\delta) \|_{L^2(\mathbb{R}^3)} \leq C_R \| J \|_{L^2(\mathbb{R}^3)} \quad \forall \ R > 0,$$

for some positive constant $C_R$ independent of $\delta$ and $J$. Moreover, $(E_\delta, H_\delta)$ converges to
$(E_0, H_0)$ strongly in $[L^2_{\text{local}}(\mathbb{R}^3)]^6$ as $\delta \to 0$, where $(E_0, H_0) \in [H_{\text{local}}(\text{curl, } \mathbb{R}^3)]^2$ is the
unique radiating solution of (1.3) with $\delta = 0$. As a consequence, we have

$$\| (E_0, H_0) \|_{L^2(\mathbb{R}^3)} \leq C_R \| J \|_{L^2(\mathbb{R}^3)} \quad \forall \ R > 0.$$
Theorem 2.1 (see also its consequence Corollary 2.1) provides very general conditions for ensuring the well-posedness and the validity of the limiting absorption principle. One does not require that $\epsilon^+ + \epsilon^-$ and $\mu^+ + \mu^-$ have the same sign on $\Gamma$. This was previously out of reach.

Our next approach for addressing the Cauchy problems is a variational one. To this end, we first introduce some notations.

**Definition 2.2.** Let $\tau > 0$ and $U$ be a smooth, open subset of $\mathbb{R}^3$ such that $\bar{U} \subset D$. A transformation $F : D \setminus \bar{U} \rightarrow D_{-\tau}$ is said to be a reflection through $\Gamma$ if and only if $F$ is a diffeomorphism and $F(x) = x$ on $\Gamma$.

Here and in what follows, when we mention a diffeomorphism $F : \Omega \rightarrow \Omega'$ for two open subsets $\Omega$ and $\Omega'$ of $\mathbb{R}^3$, we mean that $F$ is a diffeomorphism, $F \in C^1(\Omega)$, and $F^{-1} \in C^1(\Omega')$. For a diffeomorphism $F$ from $\Omega$ to $\Omega'$, for a matrix $A$ defined in $\Omega$, and for a vector field $E$ defined in $\Omega$, denote

$$F_*A(x') = \frac{\nabla F(x)A(x)\nabla F^T(x)}{J(x)} \quad \text{and} \quad F_*E(x') = \nabla F^{-T}(x)E(x),$$

with $x = F^{-1}(x')$ and $J(x) = \det \nabla F(x)$. For a vector field $J$ defined in $\Omega$, we set

$$T_*J(x') = \frac{\nabla F(x)J(x)}{J(x)}.$$

In what follows, $d_{\partial \Omega}$ denotes the distance function to $\partial \Omega$ for an open, bounded subset $\Omega$ of $\mathbb{R}^3$, i.e.,

$$d_{\partial \Omega}(x) := \min \left\{|y - x|; y \in \partial \Omega\right\} \text{ for } x \in \mathbb{R}^3.$$

The main result in this direction is

**Theorem 2.2.** Let $0 < \delta < 1$, $\tau > 0$, $J \in [L^2(\mathbb{R}^3)]^3$ with supp $J \subset B_{R_0}$, and let $(E_\delta, H_\delta) \in [H_{\text{loc}}(\text{curl}, \mathbb{R}^3)]^2$ be the unique radiating solution of (1.3). Assume that there exist a smooth open subset $U$ of $\mathbb{R}^3$ with $\bar{U} \subset D$ and a reflection $F$ through $\Gamma$ from $D \setminus \bar{U}$ onto $D_{-\tau}$ such that, with the notations

$$(\epsilon, \mu) = (\hat{\epsilon}^+, \hat{\mu}^+) \text{ in } D_{-\tau} \quad \text{and} \quad (\hat{\epsilon}, \hat{\mu}) = (F_*\epsilon^-, F_*\mu^-) \text{ in } D_{-\tau},$$

for each connected component $O$ of $D_{-\tau}$,

$$(\hat{\epsilon} - \epsilon \geq cd_1^{\alpha_1} I \text{ in } O \quad \text{or} \quad \epsilon - \hat{\epsilon} \geq cd_1^{\alpha_1} I \text{ in } O)$$

and

$$(\hat{\mu} - \mu \geq cd_1^{\alpha_2} I \text{ in } O \quad \text{or} \quad \mu - \hat{\mu} \geq cd_1^{\alpha_2} I \text{ in } O),$$

for some $0 \leq \alpha_1, \alpha_2 < 2$ and for some positive constant $c$. In the case $\alpha_1 + \alpha_2 > 0$ in $O$, additionally assume that

$$\text{supp } J \cap (O \cup F^{-1}(O)) = \emptyset.$$

Set, in $D_{-\tau}$,

$$\hat{E}_\delta = F_*E_\delta \quad \text{and} \quad \hat{H}_\delta = F_*H_\delta.$$
and additionally assume that \( D \) is of class \( C^2 \). Then, for all \( R > 0 \) and for all open set \( V \) containing \( \Gamma \),

\[
\int_{B_R \setminus V} |(E_\delta, H_\delta)|^2 + \int_{D_{-\tau}} |(\langle \varepsilon - \hat{\varepsilon} \rangle E_\delta, E_\delta)| + |(\langle \mu - \hat{\mu} \rangle H_\delta, H_\delta)| \]

\[
+ \int_{D_{-\tau}} |(E_\delta - \hat{E}_\delta, H_\delta - \hat{H}_\delta)|^2 \leq C \| J \|_{L^2(\mathbb{R}^3)}^2,
\]

for some positive constant \( C = C_{R,V} \) independent of \( \delta \) and \( J \). Moreover, for any sequence \( (\delta_n) \) converging to 0, up to a subsequence, \( (E_{\delta_n}, H_{\delta_n}) \) converges to \((E_0, H_0)\) strongly in \([L^2_{\text{loc}}(\mathbb{R}^3 \setminus \Gamma)]^6 \) as \( n \to +\infty \), where \((E_0, H_0) \in [H_{\text{loc}}(\text{curl}, \mathbb{R}^3 \setminus \Gamma)]^2 \) satisfies (2.3) with \( \delta = 0 \) and is a radiating solution of (1.3) with \( \delta = 0 \). In the case \( \alpha_1 = \alpha_2 = 0 \) for all connected components of \( D_{-\tau} \), the convergence holds in \([L^2_{\text{loc}}(\mathbb{R}^3)]^6 \) for \( \delta \to 0 \), and the limit \((E_0, H_0) \in [H_{\text{loc}}(\text{curl}, \mathbb{R}^3)]^2 \) is unique.

The meaning of the radiating solution of \((E_0, H_0)\) in Theorem 2.2 is understood as follows. A pair \((E_0, H_0) \in [H_{\text{loc}}(\text{curl}, \mathbb{R}^3 \setminus \Gamma)]^2 \) satisfies (2.3) with \( \delta = 0 \) and is called a radiating solution of (1.3) with \( \delta = 0 \) if \((E_0, H_0)\) is a radiating solution of

\[
\begin{align*}
\nabla \times E_0 &= i \omega \mu_0 H_0 & \text{in } \mathbb{R}^3 \setminus \Gamma, \\
\nabla \times H_0 &= -i \omega \varepsilon_0 E + J & \text{in } \mathbb{R}^3 \setminus \Gamma,
\end{align*}
\]

and it satisfies

\[
(E_0 - \hat{E}_0) \times v = 0 = (H_0 - \hat{H}_0) \times v \text{ on } \Gamma.
\]

Note that (2.4) makes sense since, if \( \alpha_1 + \alpha_2 > 0 \) in \( O \),

\[
\nabla (E_0 - \hat{E}_0) = i \omega \mu H_0 - i \omega \hat{\mu} \hat{H}_0 = i \omega \mu (H_0 - \hat{H}_0) + i \omega (\mu - \hat{\mu}) \hat{H}_0 \text{ in } O
\]

and

\[
\nabla (H_0 - \hat{H}_0) = i \omega \varepsilon E_0 - i \omega \hat{\varepsilon} \hat{E}_0 = i \omega \varepsilon (E_0 - \hat{E}_0) + i \omega (\varepsilon - \hat{\varepsilon}) \hat{E}_0 \text{ in } O.
\]

One can then check, in both cases \( \alpha_1 + \alpha_2 > 0 \) in \( O \) or \( \alpha_1 + \alpha_2 = 0 \) in \( O \), that

\[
E_0 - \hat{E}_0 \in H(\text{curl, } D_{-\tau}) \text{ and } H_0 - \hat{H}_0 \in H(\text{curl, } D_{-\tau})
\]

using (2.3) with \( \delta = 0 \).

The proof of Theorem 2.2 is given in Sect. 4. The variational structure is explored in Lemma 4.5. Important ingredients in the proof are two forms of Poincaré’s lemmas: one with a gain in the integrability (Lemmas 4.1 and 4.2) and one with a gain of regularity (Lemma 4.4). We also suitably use local charts to avoid imposing topological conditions. Nevertheless, a more global approach in comparison with the proof of Theorem 2.1 is required in order to remove undesirable terms in the process of using local charts (see Remark 4.2). Some applications of Theorem 2.2 are given in Sect. 4.3.

Let \( B_r(x) \) denote the open ball in \( \mathbb{R}^3 \) centered at \( x \) and of radius \( r \) for \( x \in \mathbb{R}^3 \) and for \( r > 0 \). It is shown in [27, Proposition 2.2] that if \( \hat{\varepsilon} = \varepsilon \) and \( \hat{\mu} = \mu \) in \( B_r(x_0) \cap D_{-\tau} \) for some \( x_0 \in \Gamma \) and \( r > 0 \), then resonance may occur. These requirements on \( \varepsilon, \mu, \hat{\varepsilon}, \) and \( \hat{\mu} \) are related to the complementary property of media [24, Definition 1]. This property plays a role in the construction of lensing and cloaking devices using negative-index materials [24,25] for which a localized resonance can take place, an interesting
phenomenon of negative-index metamaterials in which the solutions blow up in some regions and remain bounded in others as the loss goes to 0.

The rest of the paper is organized as follows. The proof of Theorems 2.1 and 2.2 are given in Sects. 3 and 4, respectively. In the appendix, we present the proof of Proposition 3.1 on the optimality of complementing conditions for the Cauchy problem associated with two Maxwell systems.

3. Fourier Approach for the Cauchy Problems

This section is devoted to the proof of Theorem 2.1. We first establish several lemmas in Sect. 3.1 which are used in the proof of Theorem 2.1. The proof of Theorem 2.1 is given in Sect. 3.2. The optimality of the complementing conditions used in Theorem 2.1 is discussed in Proposition 3.1 whose proof is given in the appendix.

3.1. Preliminaries. We begin this section by recalling the following known form of Poincaré’s lemma, see e.g. [12, Theorem 3.4].

**Lemma 3.1.** Let \( \Omega \) be a simply connected, bounded, open subset of \( \mathbb{R}^3 \) of class \( C^1 \). There exists a linear, continuous transformation \( T : H(\text{curl}, \Omega) \to [H^1(\Omega)]^3 \) such that

\[
\nabla \times T(u) = \nabla \times u \text{ in } \Omega.
\]

We next establish the key ingredient of the proof of Theorem 2.1.

**Lemma 3.2.** Let \( \Omega \) be a simply connected, bounded, open subset of \( \mathbb{R}^3 \) of class \( C^1 \). Let \( \epsilon, \hat{\epsilon}, \mu, \hat{\mu} \) be real, symmetric, uniformly elliptic matrix-valued functions defined in \( \Omega \) and of class \( C^1 \). Let \( J_e, J_m, \hat{J}_e, \hat{J}_m \in [L^2(\Omega)]^3 \) and let \( (E, H), (\hat{E}, \hat{H}) \in [H(\text{curl}, \Omega)]^2 \) be such that

\[
\begin{align*}
\nabla \times E &= i\omega \mu H + J_e \text{ in } \Omega, \\
\nabla \times H &= -i\omega \epsilon E + J_m \text{ in } \Omega,
\end{align*}
\]

and

\[
E \times \nu = \hat{E} \times \nu \quad \text{and} \quad H \times \nu = \hat{H} \times \nu \text{ on } \partial \Omega.
\]

Set

\[
E = T(E), \quad \hat{E} = T(\hat{E}), \quad H = T(H), \quad \hat{H} = T(\hat{H}) \quad \text{in } \Omega,
\]

where \( T \) is the operator given in Lemma 3.1. We have

1. If \( (\epsilon, \hat{\epsilon}) \) satisfies the complementing condition with respect to \( \nu(x) \) for all \( x \in \partial \Omega \), then

\[
\|(E - E, \hat{E} - \hat{E})\|_{L^2(\Omega)} \leq C \left( \|(E, \hat{E}, J_m, \hat{J}_m)\|_{L^2(\Omega)} + \|(E - \hat{E})\|_{H^{-1/2}(\partial \Omega)} + \|(E - E, \hat{E} - \hat{E})\|_{[H^1(\Omega)]^*} \right).
\]

(3.1)
(2) If \((\mu, \hat{\mu})\) satisfies the complementing condition with respect to \(v(x)\) for all \(x \in \partial \Omega\), then
\[
\|(H - \mathbf{H}, \dot{H} - \dot{\mathbf{H}})\|_{L^2(\Omega)}
\leq C \left( \|(\mathbf{H}, \dot{\mathbf{H}}, J_e, \dot{J}_e)\|_{L^2(\Omega)} + \|H - \dot{\mathbf{H}}\|_{H^{-1/2}(\partial \Omega)} + \|(H - \mathbf{H}, \dot{H} - \dot{\mathbf{H}})\|_{[H^1(\Omega)]^*} \right).
\]

Here \(C\) denotes a positive constant depending only on \(\varepsilon, \mu, \) and \(\Omega\).

**Proof.** We only prove assertion 1. Assertion 2 can be obtained similarly and its proof is omitted. From the properties of \(T\), we have
\[
\nabla \times (\mathbf{E} - \mathbf{E}) = \nabla \times (\dot{\mathbf{E}} - \dot{\mathbf{E}}) = 0 \quad \text{in} \ \Omega.
\]
Since \(\Omega\) is simply connected, there exists \(\varphi, \hat{\varphi} \in H^1(\Omega)\) such that
\[
E - \mathbf{E} = \nabla \varphi, \quad \dot{E} - \dot{\mathbf{E}} = \nabla \hat{\varphi} \quad \text{in} \ \Omega, \quad \text{and} \ \int_{\Omega} \varphi = \int_{\Omega} \hat{\varphi} = 0.
\]

We have, by the second equation of the system of \((E, H)\),
\[
\text{div}(\varepsilon \nabla \varphi) = \text{div}(\varepsilon E) - \text{div}(\varepsilon \mathbf{E}) = - \text{div}(\varepsilon \mathbf{E}) - \frac{i}{\omega} \text{div}(J_m) \quad \text{in} \ \Omega,
\]
by the second equation of the system of \((\hat{E}, \dot{H})\),
\[
\text{div}(\hat{\varepsilon} \nabla \hat{\varphi}) = \text{div}(\hat{\varepsilon} \hat{E}) - \text{div}(\hat{\varepsilon} \dot{\mathbf{E}}) = - \text{div}(\hat{\varepsilon} \dot{\mathbf{E}}) - \frac{i}{\omega} \text{div}(\hat{J}_m) \quad \text{in} \ \Omega,
\]
\[
(\nabla \varphi - \nabla \hat{\varphi}) \times \nu = (E - \mathbf{E}) \times \nu - (\dot{E} - \dot{\mathbf{E}}) \times \nu = (\dot{E} - \dot{\mathbf{E}}) \times \nu \quad \text{on} \ \partial \Omega,
\]
and, on \(\partial \Omega\),
\[
\left( \varepsilon \nabla \varphi + \frac{i}{\omega} J_m \right) \cdot \nu - \left( \hat{\varepsilon} \nabla \hat{\varphi} + \frac{i}{\omega} \dot{J}_m \right) \cdot \nu
= \left( \varepsilon E + \frac{i}{\omega} J_m \right) \cdot \nu - \left( \hat{\varepsilon} \hat{E} + \frac{i}{\omega} \dot{J}_m \right) \cdot \nu
= - \frac{1}{\omega} \nabla \times (H - \dot{H}) \cdot \nu = \frac{1}{\omega} \text{div}_\Gamma[(H - \dot{H}) \times \nu] = 0.
\]

Since \((\varepsilon, \hat{\varepsilon})\) satisfies the complementing condition, applying [29, Lemma 18] (with \(\lambda = 1, \Sigma_1 = 1, \Sigma_2 \geq 0\) sufficiently large) and using the standard arguments of freezing coefficients, we derive from (3.4), (3.5), (3.6), and (3.7) that
\[
\|(\nabla \varphi, \nabla \hat{\varphi})\|_{L^2(\Omega)} \leq C \left( \|(E, \hat{E}, J_m, \dot{J}_m)\|_{L^2(\Omega)} + \|E - \hat{E}\|_{H^{-1/2}(\partial \Omega)} + \|(\varphi, \hat{\varphi})\|_{L^2(\Omega)} \right).
\]

We claim that, for \(u \in H^1(\Omega)\) with \(\int_{\Omega} u = 0\),
\[
\|u\|_{L^2(\Omega)} \leq C \|\nabla u\|_{[H^1(\Omega)]^*}.
\]
In fact, fix $\xi \in L^2(\Omega)$ arbitrary and set $\xi_\Omega := \frac{1}{|\Omega|} \int_\Omega \xi$. Let $\varphi \in H^1(\Omega)$ be the unique solution of $-\Delta \varphi = \xi - \xi_\Omega$ in $\Omega$ and $\partial_\nu \varphi = 0$ on $\partial \Omega$ with $\int_\Omega \varphi = 0$. We have

$$\|\nabla \varphi\|_{L^2(\Omega)} \leq C \|\xi\|_{L^2(\Omega)}$$

and

$$\left| \int_\Omega u\xi \right| = \left| \int_\Omega u(\xi - \xi_\Omega) \right| = \left| \int_\Omega \nabla u \nabla \varphi \right| \leq \|\nabla u\|_{L^2(\Omega)} \|\nabla \varphi\|_{L^2(\Omega)},$$

and the claim follows.

Applying the claim, we have

$$\|(\varphi, \hat{\varphi})\|_{L^2(\Omega)} \leq C \|(\nabla \varphi, \nabla \hat{\varphi})\|_{[H^1(\Omega)]^*},$$

and assertion 1) follows from (3.8) and the choice of $\varphi$ and $\hat{\varphi}$ in (3.3). □

**Remark 3.1.** In the proof of Lemma 3.2, we used [29, Lemma 18]. This lemma is in the spirit of the results given in [2] due to Agmon, Douglis, and Nirenberg where more regular data are used.

We next establish a compactness result used in Lemma 3.4, which is a key ingredient of the proof of Theorem 2.1.

**Lemma 3.3.** Let $d \geq 2$, and let $O \subset \mathbb{R}^d$ be open, bounded, and of class $C^1$. Let $(u_n)$ be a bounded sequence in $L^2(O)$. Then, up to a subsequence, $(u_n)$ converges in $[H^1(O)]^*$.

**Proof.** Without loss of generality, one may assume that $(u_n)$ converges weakly to $u$ in $L^2(O)$. It suffices to prove that, up to a subsequence, $(u_n - u)$ converges to 0 in $[H^1(O)]^*$. By definition of the norm on $[H^1(O)]^*$, for every $n \in \mathbb{N}$, there exists $v_n \in H^1(O)$ with $\|v_n\|_{H^1(O)} \leq 1$ such that

$$\|u_n - u\|_{[H^1(O)]^*} \leq \langle u_n - u, v_n \rangle + \frac{1}{n}. \quad (3.9)$$

Since $\|v_n\|_{H^1(O)} \leq 1$ for every $n \in \mathbb{N}$, passing to a subsequence, we can assume $v_n \rightharpoonup v$ weakly in $H^1(O)$ and $v_n \rightarrow v$ strongly in $L^2(O)$ for some $v \in H^1(O)$. Thus, $\langle u_n, v_n \rangle \rightarrow \langle u, v \rangle$ and $\langle u, v_n \rangle \rightarrow \langle u, v \rangle$. Passing to the limit in (3.9), one obtains

$$\|u_n - u\|_{[H^1(O)]^*} \rightarrow 0,$$

which yields the conclusion. □

As a consequence of Lemma 3.2, one can derive the following compactness result for Maxwell’s equations, which is the key ingredient in the proof of Theorem 2.1.

**Lemma 3.4.** Let $\Omega \subset \mathbb{R}^3$ be open, bounded, and of class $C^1$ and let $\varepsilon, \hat{\varepsilon}, \mu, \hat{\mu}$ be real, symmetric, uniformly elliptic matrix-valued functions defined in $\Omega$ and of class $C^1$. Let $(J_{e,n}), (J_{m,n}), (\hat{J}_{e,n}),$ and $(\hat{J}_{m,n}) \subset [L^2(\Omega)]^3$, and let $(E_n, H_n), (\hat{E}_n, \hat{H}_n) \in [H(\text{curl}, \Omega)]^2$ be such that

\[
\begin{align*}
\nabla \times E_n &= i \omega \mu H_n + J_{e,n} \quad \text{in } \Omega, \\
\nabla \times H_n &= -i \omega \varepsilon E_n + J_{m,n} \quad \text{in } \Omega.
\end{align*}
\]

\[
\begin{align*}
\nabla \times \hat{E}_n &= i \omega \hat{\mu} \hat{H}_n + \hat{J}_{e,n} \quad \text{in } \Omega, \\
\nabla \times \hat{H}_n &= -i \omega \hat{\varepsilon} \hat{E}_n + \hat{J}_{m,n} \quad \text{in } \Omega.
\end{align*}
\]
and
\[ E_n \times v = \hat{E}_n \times v \quad \text{and} \quad H_n \times v = \hat{H}_n \times v \quad \text{on} \ \partial \Omega. \]

Let \( S \) be a connected component of \( \partial \Omega \) and assume that
\((\varepsilon, \hat{\varepsilon})(x), (\mu, \hat{\mu})(x)\) satisfy the complementing condition with respect to \( v(x) \) for all \( x \in S \), \((E_n, H_n, \hat{E}_n, \hat{H}_n)\) are bounded in \([L^2(\Omega)]^2\), and
\[
(J_{e,n}, J_{m,n}, \hat{J}_{e,n}, \hat{J}_{m,n}) \text{ converges in } [L^2(\Omega)]^2 \text{ as } n \to +\infty.
\]

There exists a neighborhood \( U \) of \( S \) such that, up to a subsequence, \((E_n, H_n, \hat{E}_n, \hat{H}_n)\) converges in \([L^2(U) \cap \Omega)]^2\).

**Proof.** Let \( \ell \geq 1 \), \( x_k \in S \), \( r_k > 0 \), and \( \varphi_k \in C^1(\mathbb{R}^3) \) for \( 1 \leq k \leq \ell \) be such that \( B_{r_k}(x_k) \cap \Omega \) is simply connected with connected boundary, \( \text{supp} \ \varphi_k \subseteq B_{r_k/2}(x_k) \), and \( \sum_{k=1}^{\ell} \varphi_k = 1 \) in a neighborhood \( U \) of \( S \). For \( 1 \leq k \leq \ell \), set \( O_k = B_{r_k}(x_k) \cap \Omega \), and, in \( O_k \), define
\[
E_{k,n} = T(\varphi_k E_n), \quad \hat{E}_{k,n} = T(\varphi_k \hat{E}_n), \quad H_{k,n} = T(\varphi_k H_n), \quad \hat{H}_{k,n} = T(\varphi_k \hat{H}_n),
\]

where \( T = T_{k} \) is the operator given in Lemma 3.1 for the set \( O_k \). By Lemma 3.1, we have
\[
\|(E_{k,n}, \hat{E}_{k,n}, H_{k,n}, \hat{H}_{k,n})\|_{H^1(O_k)} \leq C \|(E_n, \hat{E}_n, H_n, \hat{H}_n, J_{e,n}, \hat{J}_{e,n}, J_{m,n}, \hat{J}_{m,n})\|_{L^2(O_k)}.
\]

Without loss of generality, one may assume that, as \( n \to +\infty \),
\[
(E_{k,n}, \hat{E}_{k,n}, H_{k,n}, \hat{H}_{k,n}) \text{ converges in } [L^2(O_k)]^2,
\]
and
\[
(\varphi_k E_n - E_{k,n}, \varphi_k \hat{E}_n - \hat{E}_{k,n}, \varphi_k H_n - H_{k,n}, \varphi_k \hat{H}_n - \hat{H}_{k,n}) \text{ converges in } [H^1(O_k)]^2.
\]

Applying Lemma 3.2, we have
\[
\|(\varphi_k E_n - E_{k,n}) - (\varphi_k E_l - E_{k,l})\|_{L^2(O_k)} \leq C \|(\varphi_k E_n - E_{k,n}) - (\varphi_k \hat{E}_n - \hat{E}_{k,n})\|_{H^1(O_k)}
\]
\[
+ C \|(E_{k,n} - E_{k,l}, \hat{E}_{k,n} - \hat{E}_{k,l}, J_{m,n} - J_{m,l}, \hat{J}_{m,n} - \hat{J}_{m,l})\|_{L^2(O_k)}
\]
\[
+ C \|(E_{l,n} - \hat{E}_{l,n})\|_{H^{-1/2}(\partial O_k)} \to 0 \quad \text{as} \quad l, n \to +\infty,
\]
and
\[
\|(\varphi_k H_n - H_{k,n}) - (\varphi_k H_l - H_{k,l})\|_{L^2(O_k)} \leq C \|(\varphi_k H_n - H_{k,n}) - (\varphi_k \hat{H}_n - \hat{H}_{k,n})\|_{L^2(O_k)}
\]

1 The complementing conditions holds on \( \partial O_k \cap S \) a priori. However, since \( \varphi_k = 0 \) in \( B_{r_k}(x_k) \setminus B_{r_k/2}(x_k) \), one can modify \( \varepsilon \), \( \mu \), \( \hat{\varepsilon} \), \( \hat{\mu} \) in \( B_{r_k}(x_k) \setminus B_{2r_k/3}(x_k) \) so that the complementing conditions hold on the whole boundary and the systems are unchanged, e.g. \( \varepsilon > \hat{\varepsilon} \) and \( \mu > \hat{\mu} \) in \( B_{r_k}(x_k) \setminus B_{2r_k/3}(x_k) \) (see Proposition 2.1).
The proof is quite standard as in the usual case. We present it here for the completeness. Multiplying the equation of $E$ by $\varphi_k \hat{H}_n - \hat{H}_{k,n}$, we have
\begin{align*}
\langle \varphi_k H_n - \mathbf{H}_{k,n}, \varphi_k H_l - \hat{H}_{k,l} \rangle \leq C \| (\varphi_k H_n - \mathbf{H}_{k,n}) - (\varphi_k H_l - \hat{H}_{k,l}) \|_{H^1(\Omega_k)^n}^*
+C \| (\mathbf{H}_{k,n} - \hat{H}_{k,l}, \hat{H}_{k,n} - \hat{H}_{k,l}, J_{e,n} - J_{e,l}, \hat{J}_{e,n} - \hat{J}_{e,l}) \|_{L^2(\Omega_k)}
+C \| (\mathbf{H}_{k,n} - \hat{H}_{k,n}) - (\hat{H}_{l,n} - \hat{H}_{l,n}) \|_{H^{-1/2}(\partial \Omega_k)} \rightarrow 0 \text{ as } l, n \rightarrow +\infty.
\end{align*}
Hence \((\varphi_k E_{k,n}, \varphi_k \hat{E}_{k,n}, \varphi_k H_{k,n}, \varphi_k \hat{H}_{k,n})\) is a Cauchy sequence in \([L^2(\Omega_k)]^4\) and therefore convergence in \([L^2(\Omega_k)]^4\). The conclusion then follows since \(\sum_{k=1}^l \varphi_k = 1\) in \(U\).

We next recall the following well-posedness result on (1.3) (see [24, Lemma 6]).

**Lemma 3.5.** Let \(0 < \delta < 1\), \(f, g \in [L^2(\mathbb{R}^3)]^3\), and \((\varepsilon_\delta, \mu_\delta)\) be defined in (1.1). Assume that \(\text{supp } f, \text{supp } g \subset B_{R_0}\). There exists a unique radiating solution \((\mathcal{E}_\delta, \mathcal{H}_\delta) \in [H^1_{\text{loc}}(\text{curl}, \mathbb{R}^3)]^2\) to
\begin{align*}
\nabla \times \mathcal{E}_\delta &= i \omega \mu_\delta \mathcal{H}_\delta + f \quad \text{in } \mathbb{R}^3, \\
\nabla \times \mathcal{H}_\delta &= -i \omega \varepsilon_\delta \mathcal{E}_\delta + g \quad \text{in } \mathbb{R}^3.
\end{align*}
Moreover, we have
\[
\| (\mathcal{E}_\delta, \mathcal{H}_\delta) \|_{H(\text{curl}, B_R)} \leq \frac{C_R}{\delta} \| (f, g) \|_{L^2},
\]
where \(C_R\) denotes a positive constant depending on \(R, R_0, \varepsilon, \mu, \text{ and } \mu\), but independent of \(f, g, \text{ and } \delta\).

We now deal with the uniqueness of (1.3) for \(\delta = 0\).

**Lemma 3.6.** Let \(J = 0\) and \((E_0, H_0) \in [H^1_{\text{loc}}(\text{curl}, \mathbb{R}^3)]^2\) is a radiating solution of (1.3) with \(\delta = 0\). Then
\[
E_0 = H_0 = 0 \text{ in } \mathbb{R}^3.
\]

**Proof.** The proof is quite standard as in the usual case. We present it here for the completeness. Multiplying the equation of \(E_0\) by \(\nabla \times \bar{E}_0\) (\(\bar{E}_0\) denotes the conjugate of \(E_0\)), we have
\[
\int_{B_{R_0}} \langle \mu^{-1} \nabla \times E_0, \nabla \times E_0 \rangle = \int_{B_{R_0}} \langle i \omega H_0, \nabla \times E_0 \rangle.
\]
Integrating by parts the RHS and using the equation of \(H_0\), we obtain
\[
\int_{B_{R_0}} \langle \mu^{-1} \nabla \times E_0, \nabla \times E_0 \rangle = \int_{B_{R_0}} \omega^2 |E_0|^2 + \int_{\partial B_{R_0}} i \omega (H_0 \times \nu) \cdot \bar{E}_0.
\]
This implies
\[
\Re \int_{\partial B_{R_0}} (H_0 \times \nu) \cdot \bar{E}_0 = 0.
\]
It follows, see, e.g., [8, Theorem 6.10], that \(E_0 = H_0 = 0\) in \(\mathbb{R}^3 \setminus B_{R_0}\). Therefore, \(E_0 = H_0 = 0\) in \(\mathbb{R}^3\) by the unique continuation principle, see [4,30] (and also [15,34]).
3.2. Proof of Theorem 2.1. We first prove (2.1) with \( r_0 := R_0 + 1 \) by contradiction. Assume that there exist a sequence \((\delta_n) \subset (0, 1)\) and a sequence \((J_n) \subset [L^2(\mathbb{R}^3)]^3\) with \( \text{supp} \, J_n \subset B_{R_0} \) such that
\[
\|(E_n, H_n)\|_{L^2(B_{R_0})} = 1 \quad \text{and} \quad \lim_{n \to +\infty} \|J_n\|_{L^2(\mathbb{R}^3)} = 0. \quad (3.10)
\]
Here \((E_n, H_n)\) is the corresponding solution of (1.3) with \( \delta = \delta_n \) and \( J = J_n \). By Lemma 3.5, without loss of generality, one may assume that \( \delta_n \to 0 \). Since
\[
\begin{align*}
\nabla \times E_n &= i \omega H_n \quad \text{in} \, \mathbb{R}^3 \setminus B_{R_0}, \\
\nabla \times H_n &= -i \omega E_n \quad \text{in} \, \mathbb{R}^3 \setminus B_{R_0},
\end{align*}
\]
we have, for \( R > R_0 + 1/2 \), by [19, Lemma 5],
\[
\|(E_n, H_n)\|_{L^2(B_R \setminus B_{R_0 + 1/2})} \leq CR \|\nabla \times (\nu \times E_n, \nu \times H_n)\|_{H^{-1/2}(\text{div}, \partial B_{R_0 + 1/2})} \leq CR \|(E_n, H_n)\|_{H(\text{curl}, B_{R_0 + 1/2} \setminus B_{R_0})} \quad \text{(see e.g. [12])} \quad (3.11)
\]
Combining (3.10) and (3.11) yields
\[
\|(E_n, H_n)\|_{L^2(B_R)} \leq CR \quad \text{for all} \, \ R > 0. \quad (3.12)
\]

Fix \( \psi \in C^1_c(\mathbb{R}^3) \) (arbitrary) be such that \( \psi = 0 \) in a neighborhood of \( \Gamma \). We have, in \( \mathbb{R}^3 \),
\[
\nabla \times (\psi E_n) = \psi \nabla \times E_n + \nabla \psi \times E_n \quad \text{and} \quad \text{div}(\varepsilon_0 \psi E_n) = \psi \text{div}(\varepsilon_0 E_n) + \nabla \psi \cdot \varepsilon_0 E_n.
\]
Using (3.12) and the system of equations of \((E_n, H_n)\) and applying e.g. [24, Lemma 1], one may assume that
\[
(\psi E_n) \text{ converges in } L^2(\mathbb{R}^3),
\]
which yields, since \( \psi \) is arbitrary,
\[
(E_n) \text{ converges in } L^2_{\text{loc}}(\mathbb{R}^3 \setminus \Gamma). \quad (3.13)
\]
Similarly, one may also assume that
\[
(H_n) \text{ converges in } L^2_{\text{loc}}(\mathbb{R}^3 \setminus \Gamma). \quad (3.14)
\]

For \( \tau > 0 \) sufficiently small (the smallness depends only on \( D \)), define \( \mathcal{F} : D_\tau \to D_{-\tau} \) by
\[
\mathcal{F}(x_\Gamma + t \nu(x_\Gamma)) = x_\Gamma - t \nu(x_\Gamma) \quad \forall \, x_\Gamma \in \Gamma, \ t \in (-\tau, 0)
\]
and set, in \( D_{-\tau} \),
\[
(\hat{\varepsilon}, \hat{\mu}) = (\mathcal{F} \ast \varepsilon^-, \mathcal{F} \ast \mu^-) \quad \text{and} \quad (\hat{E}_n, \hat{H}_n) = (\mathcal{F} \ast E_n, \mathcal{F} \ast H_n).
\]
Note that the pairs \((\varepsilon, \hat{\varepsilon})(x)\) and \((\mu, \hat{\mu})(x)\) satisfy the complementing conditions with respect to \( \nu(x) \) for all \( x \in \Gamma \) if and only if the pairs \((\varepsilon^+, -\varepsilon^-)(x)\) and \((\mu^+, -\mu^-)(x)\)
do, by Proposition 2.1. By a change of variables for the Maxwell equations, see e.g. [24, Lemma 7], we have
\[
\begin{align*}
\nabla \times E_n &= i \omega \mu H_n \quad \text{in } D_{-\tau}, \\
\nabla \times H_n &= -i \omega \varepsilon E_n + J_n \quad \text{in } D_{-\tau},
\end{align*}
\]
and
\[
\begin{align*}
\nabla \times \hat{E}_{e,n} &= i \omega \hat{\mu} \hat{H}_{e,n} + \hat{J}_{e,n} \quad \text{in } D_{-\tau}, \\
\nabla \times \hat{H}_{e,n} &= -i \omega \hat{\varepsilon} \hat{E}_{e,n} + \hat{J}_{m,n} \quad \text{in } D_{-\tau},
\end{align*}
\]
and
\[
E_n \times v = \hat{E}_{e,n} \times v \quad \text{and} \quad H_n \times v = \hat{H}_{e,n} \times v \quad \text{on } \Gamma.
\]
Here
\[
\hat{J}_{e,n} = -\delta \omega \mathcal{F}_s \hat{I} \hat{H}_n \quad \text{and} \quad \hat{J}_{m,n} = \delta \omega \mathcal{F}_s \hat{I} \hat{E}_{e,n} + \mathcal{F}_s J_n \quad \text{in } D_{-\tau}.
\]
By Lemma 3.4, there exists a neighborhood \( U \) of \( \Gamma \) such that, up to a subsequence,
\[
(E_n, H_n, \hat{E}_n, \hat{H}_n) \text{ converges in } [L^2(U \cap D_{-\tau/2})]^{12}. \tag{3.15}
\]
It follows from (3.13), (3.14), and (3.15) that, up to a subsequence,
\[
(E_n, H_n) \text{ converges in } [L^2_{\text{loc}}(\mathbb{R}^3)]^{12}. \tag{3.16}
\]
Moreover, the limit (\( E_0, H_0 \)) is in \([H_{\text{loc}}(\text{curl}, \mathbb{R}^3)]^2\) and is a radiating solution of the equations
\[
\begin{align*}
\nabla \times E_0 &= i \omega \mu_0 H_0 \quad \text{in } \mathbb{R}^3, \\
\nabla \times H_0 &= -i \omega \varepsilon_0 E_0 \quad \text{in } \mathbb{R}^3.
\end{align*}
\]
By Lemma 3.6, we have
\[
E_0 = H_0 = 0 \text{ in } \mathbb{R}^3.
\]
This contradicts the fact that \( \| (E_n, H_n) \|_{L^2(B_{R_0})} = 1 \) and, up to a subsequence, \((E_n, H_n)\) converges to \((E_0, H_0)\) in \([L^2_{\text{loc}}(\mathbb{R}^3)]^6\).

Hence (2.1) holds for \( R = R_0 + 1 \). This implies, exactly as in the proof of (3.12),
\[
\| (E_\delta, H_\delta) \|_{L^2(B_R)} \leq C_R \| J \|_{L^2(\mathbb{R}^3)} \quad \text{for all } R > R_0 + 1,
\]
which is (2.1).

We next establish the remaining part of Theorem 2.1. By (2.1), for every sequence \( (\delta_n) \to 0 \), there exists a subsequence \( (\delta_{n_k}) \) such that \((E_{\delta_{n_k}}, H_{\delta_{n_k}})\) converges weakly in \([L^2_{\text{loc}}(\mathbb{R}^3)]^6\). Moreover, the limit \((E_0, H_0) \in [H_{\text{loc}}(\text{curl}, \mathbb{R}^3)]^2\) is a radiating solution of (1.3) with \( \delta = 0 \). By Lemma 3.6, the limit is unique. Therefore, \((E_\delta, H_\delta)\) converges to \((E_0, H_0)\) weakly in \([L^2_{\text{loc}}(\mathbb{R}^3)]^6\) as \( \delta \to 0 \). It is then clear that (2.2) follows from (2.1).

The strong convergence follows from (2.1) by the same way (3.16) followed from (3.12) and once again using the uniqueness of the limit. The proof is complete. \( \Box \)

A key part in the proof of Theorem 2.1 is the compactness result in Lemma 3.4 which is derived from Lemma 3.2 where the complementing conditions plays a crucial role. Assume that \((\varepsilon, \hat{\varepsilon})\) and \((\mu, \hat{\mu})\) both satisfy the complementing conditions and of class \( C^2 \). Then, instead of (3.1) and (3.2), one has (see [2])
\[
\| (E, \hat{E}, H, \hat{H}) \|_{H^1(\Omega)} \leq C \left( \| (E, \hat{E}, H, \hat{H}) \|_{L^2(\Omega)} + \| (J_e, \hat{J}_e, J_m, \hat{J}_m) \|_{H(\text{div}, \Omega)} \right) \tag{3.17}
\]
for some positive constant \( C \) independent of \((E, \hat{E}, H, \hat{H}), (J_e, \hat{J}_e, J_m, \hat{J}_m)\). The following proposition shows that the complementing conditions on each pair \((\varepsilon, \hat{\varepsilon})\) and \((\mu, \hat{\mu})\) are necessary to have (3.17).
**Proposition 3.1.** Let $\Omega$ be a bounded, connected open subset of $\mathbb{R}^3$ and of class $C^2$ and let $\varepsilon$, $\hat{\varepsilon}$, $\mu$, $\hat{\mu}$ be real, symmetric, uniformly elliptic matrix-valued functions defined in $\Omega$ and of class $C^1$. Assume that either $(\varepsilon, \hat{\varepsilon})$ or $(\mu, \hat{\mu})$ does not satisfy the complementing condition at some point $x_0 \in \partial \Omega$. Then there exist sequences $(J_{e,n})$, $(J_{m,n})$, $(\hat{J}_{e,n})$, $(\hat{J}_{m,n}) \subset H(\text{div}, \Omega)$ and $((E_n, H_n), (\hat{E}_n, \hat{H}_n)) \subset [H^1(\Omega)]^6$ such that

\[
\begin{align*}
\nabla \times E_n &= i \omega \mu H_n + J_{e,n} \text{ in } \Omega, \\
\nabla \times H_n &= -i \omega \varepsilon E_n + J_{m,n} \text{ in } \Omega, \\
\nabla \times \hat{E}_n &= i \omega \hat{\mu} \hat{H}_n + \hat{J}_{e,n} \text{ in } \Omega, \\
\nabla \times \hat{H}_n &= -i \omega \hat{\varepsilon} \hat{E}_n + \hat{J}_{m,n} \text{ in } \Omega,
\end{align*}
\]

\[E_n \times v = \hat{E}_n \times v, \quad H_n \times v = \hat{H}_n \times v \text{ on } \partial \Omega,\]

\[\sup_n \|(J_{e,n}), (J_{m,n}), (\hat{J}_{e,n}), (\hat{J}_{m,n})\|_{H(\text{div}(\Omega))} < +\infty,\]

\[\sup_n \| (E_n, \hat{E}_n, H_n, \hat{H}_n) \|_{L^2(\Omega)} < +\infty,\]

and

\[\sup_n \| (E_n, \hat{E}_n, H_n, \hat{H}_n) \|_{H^1(\Omega)} = +\infty.\]

The proof of Proposition 3.1 is given in the appendix.

4. Variational Approach for the Cauchy Problems

This section containing three subsections is devoted to Theorem 2.2. In the first section, we present lemmas used in the proof of Theorem 2.2. The proof of Theorem 2.2 is given in the second subsection. In the last section, we give some applications of Theorem 2.2.

4.1. Some useful lemmas. We begin with the following version of Poincaré’s lemma which plays an important role in the proof of Theorem 2.2.

**Lemma 4.1.** Let $0 \leq \alpha < 2$ and $\Omega$ be a domain diffeomorphic to $B_1$. There exists a linear operator

\[T_1 : \left\{ f \in H(\text{div}, \Omega); \ \text{div} f = 0 \text{ in } \Omega \right\} \rightarrow H(\text{curl}, \Omega)\]

such that

\[\nabla \times T_1(f) = f \text{ in } \Omega\]

and

\[\int_{\Omega} |T_1(f)|^2 \, dx \leq C \int_{\Omega} d_{\partial \Omega}^\alpha |f|^2 \, dx, \quad (4.1)\]

for some positive constant $C = C(\alpha, \Omega)$ independent of $f$. 

Proof. We first consider the case $\Omega = B_1$. Without loss of generality, one can assume that $1 < \alpha < 2$. We first assume that $f$ is smooth (and $\text{div} \ f = 0$). Set

$$F(x) = -\int_0^1 tx \times f(tx) \, dt \text{ in } B_1. \tag{4.2}$$

Using the fact that, for two vector fields $A$ and $B$ defined in $B_1$,

$$\nabla \times (A \times B) = A \text{div} \ B - B \text{div} \ A + (B \cdot \nabla) A - (A \cdot \nabla) B,$$

we have, in $B_1$,

$$\nabla \times F(x) = 2 \int_0^1 tf(tx) \, dt + \int_0^1 t(x \cdot \nabla) f(tx) \, dt = 2 \int_0^1 tf(tx) \, dt + \int_0^1 t^2 \frac{d}{dt} [f(tx)] \, dt = f(x).$$

We next prove (4.1). We have

$$\int_{B_1} |F|^2 \, dx \leq \int_{B_1} \left( \int_0^1 |tx||f(tx)| \, dt \right)^2 \, dx \leq \int_{B_1} \left( \int_0^1 |tx|^2 |f(tx)|^2 (1 - |tx|)^\alpha \, dt \int_0^1 (1 - t|x|)^{-\alpha} \, dt \right) \, dx. \tag{4.3}$$

In what follows in this proof, $C$ denotes a positive constant depending only on $\alpha$ and $\Omega$. Since

$$\int_0^1 (1 - t|x|)^{-\alpha} \, dt = (\alpha - 1)|x|^{-1} \left[ (1 - |x|)^{-\alpha+1} - 1 \right] \leq C (1 - |x|)^{-\alpha+1},$$

it follows that

$$\int_{B_1} |F|^2 \, dx \leq C \int_{B_1} \int_0^1 |tx|^2 |f(tx)|^2 (1 - |tx|)^\alpha \, dt (1 - |x|)^{-\alpha+1} \, dx \leq C \int_{B_1} \int_0^1 |y|^2 |f(y)|^2 (1 - |y|)^\alpha (t - |y|)^{-\alpha+1} t^{\alpha-4} \, dy \, dt \leq C \int_{B_1} |y|^2 |f(y)|^2 (1 - |y|)^\alpha \int_{|y|}^1 (t - |y|)^{-\alpha+1} t^{\alpha-4} \, dt \, dy. \tag{4.3}$$

Since $\alpha < 2$, we have

$$\int_{|y|}^1 (t - |y|)^{-\alpha+1} t^{\alpha-4} \, dt = \frac{1}{2 - \alpha} (t - |y|)^{-\alpha+2} t^{\alpha-4} \bigg|_{|y|}^1 + \frac{1}{(2 - \alpha)(4 - \alpha)} \int_{|y|}^1 (t - |y|)^{-\alpha+2} t^{\alpha-5} \, dt \leq C + C \int_{|y|}^1 t^{-3} \leq C |y|^{-2}. \tag{4.4}$$
Combining (4.3) and (4.4) yields

$$\int_{B_1} |F|^2 \, dx \leq C \int_{B_1} |f(y)|^2 (1 - |y|)^\alpha \, dy,$$

which is (4.6). The conclusion for a general \( f \) now follows by a standard approximation process.

We now consider a general \( \Omega \). Let \( T : \Omega \to B_1 \) be a diffeomorphism. Set, for \( x' \in B_1 \),

$$f'(x') = \frac{\nabla T(x)}{J(x)} f(x) \quad \text{with} \quad x' = T(x) \quad \text{and} \quad J(x) = \det T(x)$$

and

$$F'(x') = -\int_0^1 t x' \times f'(tx') \, dt.$$ 

Since (see, e.g., [17, Lemma 3.59]),

$$\nabla' \cdot f'(x') = \frac{\nabla \cdot f(x)}{J(x)} = 0 \text{ in } B_1,$$

it follows from the case \( \Omega = B_1 \) that

$$\nabla' \times F'(x') = f'(x') \text{ in } B_1.$$ 

Set, for \( x \in \Omega \),

$$T_1(f)(x) = \nabla T^T(x) F'(x') \quad \text{with} \quad x' = T(x).$$

Then (see, e.g., [17, Corollary 3.58])

$$\nabla \times T_1(f)(x) = f(x) \quad \text{for } x \in \Omega.$$ 

Assertion (4.6) now follows from (4.5). □

**Remark 4.1.** The definition of \( F \) in (4.2) is an explicit formula for solving the Poincaré lemma in a star-shaped domain taken from a note of Dacorogna [11].

In what follows, we denote \( \mathbb{R}_+^3 = \{(x_1, x_2, x_3) \in \mathbb{R}^3; x_3 > 0\}, \mathbb{R}_0^3 = \{(x_1, x_2, x_3) \in \mathbb{R}^3; x_3 = 0\}, Q = (-1, 1)^3, Q_+ = Q \cap \mathbb{R}_+^3, \text{ and } Q_0 = Q \cap \mathbb{R}_0^3. \) The proof of Lemma 4.1 can be used to obtain

**Lemma 4.2.** Let \( 0 \leq \alpha < 2 \) and let \( \Omega \) be an open bounded subset of \( \mathbb{R}^3 \) and let \( \mathcal{H} : \Omega \to Q_+ \) be a diffeomorphism. Denote \( S = \partial Q_+ \setminus Q_0 \) and let \( U \subset \mathbb{R}^3 \) be a neighborhood of \( \bar{S} \). There exist an open set \( V \subset \mathbb{R}^3 \) containing \( \mathcal{H}^{-1}(\bar{S}) \) and a linear operator

$$T_1 : \left\{ f \in H(\text{div}, \Omega); \ \text{div} \, f = 0 \text{ in } \Omega \right\} \to H(\text{curl}, \Omega)$$

such that

$$\nabla \times T_1(f) = f \text{ in } \Omega,$$
\[
\int_{\Omega} |T_1(f)|^2 \, dx \leq C \int_{\Omega} d_{\partial \Omega}^g |f|^2 \, dx,
\]  
for some positive constant \( C = C(\alpha, \Omega) \) independent of \( f \), and

\[ T_1(f) = 0 \text{ in } V \cap \Omega \text{ if } f = 0 \in \mathcal{H}^{-1}(U \cap Q_+). \]

**Proof.** Without loss of generality, one can assume that \( 1 < \alpha < 2 \). Let \( T_1 : Q_+ \to B_1 \) be a bi-Lipschitz homeomorphism such that \( T_1(\bar{S}) = \Sigma \) and \( \bar{C} \subset T_1(U \cap Q_+) \), where \( \Sigma := \partial B_1 \cap \mathbb{R}_+^3 \) and \( C := \{ r \sigma ; r \in (0, 1) \text{ and } \sigma \in \Sigma \} \). Let \( \Sigma_1 \subset \partial B_1 \) be an open set of \( \partial B_1 \) such that \( \bar{C} \subset \Sigma_1 \) and \( \bar{C}_1 \subset T_1(U \cap Q_+) \), where \( C_1 = \{ r \sigma ; r \in (0, 1) \text{ and } \sigma \in \Sigma_1 \} \).

Let \( T : \Omega \to B_1 \) be defined by

\[ T = T_1 \circ \mathcal{H}. \]

As in the proof of Lemma 4.1, set, for \( x' \in B_1 \),

\[ f'(x') = \frac{\nabla T(x)}{J(x)} f(x) \text{ with } x' = T(x) \text{ and } J(x) = \det T(x), \]

and

\[ F'(x') = -\int_0^1 tx' \times f'(tx') \, dt. \]  \hspace{1cm} (4.7)

Define, in \( \Omega \),

\[ T_1(f)(x) = \nabla T^T(x) F'(x') \text{ with } x' = T(x). \]

As in the proof of Lemma 4.1, we have

\[ \nabla \times T_1(f) = f \text{ in } \Omega \]

and

\[ \int_{\Omega} |T_1(f)|^2 \, dx \leq C \int_{\Omega} d_{\partial \Omega}^g |f|^2 \, dx. \]

Let \( V \) be an open subset of \( \mathbb{R}^3 \) such that \( \mathcal{H}^{-1}(\bar{S}) \subset V \) and \( V \cap \Omega = \mathcal{H}^{-1}(T^{-1}(\bar{C}_1)) \).

Such a \( V \) exists by the choice of \( C_1 \). Assume that \( f = 0 \) in \( \mathcal{H}^{-1}(U \cap Q_+) \). Then \( f'(x') = 0 \) for \( x' \in \bar{C}_1 \). It follows from (4.7) that \( F'(x') = 0 \) for \( x' \in \bar{C}_1 \). This implies that \( T_1(f) = 0 \) in \( \mathcal{H}^{-1}(T^{-1}(\bar{C}_1)) = V \cap \Omega \). The proof is complete. \( \square \)

In what follows, we use several times the following simple compactness result whose proof is omitted.

**Lemma 4.3.** Let \( \Omega \) be a bounded open subset of \( \mathbb{R}^d \) of class \( C^1 \) and let \( \gamma_1 < \gamma_2 \). Assume that \( (u_n) \subset L^2_{\text{loc}}(\Omega) \) is such that \( u_n \to u \) in \( L^2_{\text{loc}}(\Omega) \) as \( n \to +\infty \) and

\[ \sup_n \| u_n \|_{L^2(d_{\partial \Omega}^{\gamma_1}, \Omega)} < +\infty. \]

Then \( u_n \to u \) in \( L^2(d_{\partial \Omega}^{\gamma_2}, \Omega) \) as \( n \to +\infty \).
Here and in what follows, for a non-negative, measurable function $g$ defined in $\Omega$, one denotes, for $u \in L^2_{\text{loc}}(\Omega)$,

$$\|u\|_{L^2(g, \Omega)} = \left(\int_\Omega g|u|^2\right)^{1/2}.$$ 

For $(u_n) \subset L^2_{\text{loc}}(\Omega)$ and $u \in L^2_{\text{loc}}(\Omega)$, one says that $u_n \rightarrow u$ in $L^2(g, \Omega)$ as $n \rightarrow +\infty$ if

$$\lim_{n \rightarrow +\infty} \|u_n - u\|_{L^2(g, \Omega)} = 0.$$

Let $\Omega$ be a bounded open subset of $\mathbb{R}^3$ with Lipschitz boundary. We denote

$$H_0(\text{curl}, \Omega) = \left\{ u \in H(\text{curl}, \Omega); u \times v = 0 \text{ on } \partial \Omega \right\}.$$ 

In the proof of Lemma 4.5, we also use the following form of Poincaré’s lemma:

**Lemma 4.4.** Let $\Omega$ be a simply connected, bounded, open subset of $\mathbb{R}^3$ of class $C^2$. There exists a linear continuous transformation $T_0 : H_0(\text{curl}, \Omega) \rightarrow [H^1_0(\Omega)]^3$ such that

$$\nabla \times T_0(u) = \nabla \times u \text{ in } \Omega.$$ 

Consequently, for every $s > 0$, for every $0 \leq \alpha < 2$, and for every $\beta \geq 0$, there exists a constant $C_s = C(s, \alpha, \beta, \Omega) > 0$ such that

$$\|T_0(u)\|_{L^2(d^{-\alpha}_{\Omega}, \Omega)} \leq s\|u\|_{H(\text{curl}, \Omega)} + C_s\|u\|_{L^2(d^\beta_{\Omega}, \Omega)}.$$  \hspace{1cm} (4.8)

**Proof.** We only prove (4.8) and we prove it by contradiction. Assertion (4.4) is known, see e.g. [12, Theorem 3.6], [10, Theorem 8.16]. Assume that (4.8) does not hold. There exists a sequence of $(u_n) \subset H_0(\text{curl}, \Omega)$ such that

$$1 = \|T_0(u_n)\|_{L^2(d^{-\alpha}_{\Omega}, \Omega)} \geq s\|u_n\|_{H(\text{curl}, \Omega)}^2 + n\|u_n\|_{L^2(d^\beta_{\Omega}, \Omega)}^2.$$ \hspace{1cm} (4.9)

Since $T_0$ is continuous, it follows that the sequence $\left(\|T_0(u_n)\|_{H^1(\Omega)}\right)$ is bounded. Without loss of generality, one may assume that $T_0(u_n)$ converges to $v$ strongly in $[L^2(\Omega)]^3$ and weakly in $[H^1(\Omega)]^3$. By Hardy’s inequality

$$\int_\Omega d^2_{\Omega} |v|^2 \leq C\int_\Omega |\nabla v|^2,$$

we derive that

$$\int_\Omega d^{-2}_{\Omega}|T_0(u_n)|^2 \leq C.$$ 

Since $0 \leq \alpha < 2$, by Lemma 4.3, without loss of generality, one may assume that $T_0(u_n) \rightarrow v$ in $[L^2(d^{-\alpha}_{\Omega}, \Omega)]^3$.

From (4.9), one may assume as well that $u_n \rightarrow 0$ weakly in $H_0(\text{curl}, \Omega)$. Since $T_0$ is linear and continuous, this in turn implies that $v = T_0(\lim_{n \rightarrow +\infty} u_n) = T_0(0) = 0$. This contradicts the fact $\|v\|_{L^2(d^{-\alpha}_{\Omega}, \Omega)} = \lim_{n \rightarrow +\infty} \|T_0(u_n)\|_{L^2(d^\beta_{\Omega}, \Omega)} = 1$. Therefore, (4.8) holds. \hspace{1cm} $\square$

We now present the key ingredient of the proof of Theorem 2.2, which is a variant of Lemma 3.4.
Lemma 4.5. Let $\tau > 0$, $0 < \delta < 1$, $s > 0$, and let $\Omega$ be a connected component of $D_{-\tau}$. Let $\varepsilon$, $\hat{\varepsilon}$, $\mu$, $\hat{\mu}$ be real, symmetric, uniformly elliptic matrix-valued functions defined in $\Omega$. Let $J_e, J_m, \hat{J}_e, \hat{J}_m \in [L^2(\Omega)]^2$ and $(E, H), (\hat{E}, \hat{H}) \in [H(\text{curl}, \Omega)]^2$ be such that

\[
\nabla \times E = i \omega \mu H + J_e \quad \text{in} \: \Omega, \\
\nabla \times H = -i \omega \varepsilon E + J_m \quad \text{in} \: \Omega,
\]

and

\[
E \times v = \hat{E} \times v \quad \text{and} \quad H \times v = \hat{H} \times v \quad \text{on} \: \partial \Omega \cap \Gamma.
\]

We have

(1) if, for some $c > 0$ and $0 \leq \alpha_1 < 2$,

\[
\hat{\varepsilon} - \varepsilon \geq c d_{\Omega}^{\alpha_1} I \quad \text{in} \: \Omega \quad \text{or} \quad \varepsilon - \hat{\varepsilon} \geq c d_{\Omega}^{\alpha_1} I \quad \text{in} \: \Omega
\]

then, for every $s > 0$ and for every $0 \leq \beta < 2$, there exists a constant $C_s > 0$, depending only on $s, \beta, c, \alpha_1, \Omega$, and the ellipticity of $\varepsilon, \hat{\varepsilon}, \mu, \hat{\mu}$ such that

\[
\int_\Omega |(\varepsilon - \hat{\varepsilon}) E, E| + |E - \hat{E}|^2 \leq s \int_\Omega |\mu H - \hat{\mu} \hat{H}|^2 + C_s \int_\Omega |J_m - \hat{J}_m||\hat{E}|
\]

\[
+ C_s \int_\Omega d_\Gamma^\beta |(E, \hat{E}, H, \hat{H})|^2 + |(J_e, \hat{J}_e, J_m, \hat{J}_m)|^2;
\]

(2) if, for some $c > 0$ and $0 \leq \alpha_2 < 2$,

\[
\hat{\mu} - \mu \geq c d_{\Omega}^{\alpha_1} I \quad \text{in} \: \Omega \quad \text{or} \quad \mu - \hat{\mu} \geq c d_{\Omega}^{\alpha_1} I \quad \text{in} \: \Omega
\]

then, for every $s > 0$ and for every $0 \leq \beta < 2$, there exists a constant $C_s > 0$, depending only on $s, \beta, c, \alpha_2, \Omega$, and the ellipticity of $\varepsilon, \hat{\varepsilon}, \mu, \hat{\mu}$ such that

\[
\int_\Omega |(\mu - \hat{\mu}) H, H| + |H - \hat{H}|^2 \leq s \int_\Omega |\varepsilon E - \hat{\varepsilon} \hat{E}|^2 + C_s \int_\Omega |J_e - \hat{J}_e||\hat{H}|
\]

\[
+ C_s \int_\Omega d_\Gamma^\beta |(E, \hat{E}, H, \hat{H})|^2 + |(J_e, \hat{J}_e, J_m, \hat{J}_m)|^2.
\]

Proof. We only establish assertion 1) and assume that $\varepsilon - \hat{\varepsilon} \geq c d_{\Omega}^{\alpha_1} I$. The proof of assertion 2) in the case $\hat{\varepsilon} - \varepsilon \geq c d_{\Omega}^{\alpha_1} I$ and the proof of assertion 2) can be derived similarly. Without loss of generality, one may assume that $s$ is small.

We use local charts for $\partial \Omega \cap \Gamma$. Let $\ell \geq 1$ and let $\varphi_k \in C^1_c(\mathbb{R}^3), U_k \subset \mathbb{R}^3$ open ball, and $\mathcal{H}_k : U_k \to Q$ for $1 \leq k \leq \ell$ be such that $\mathcal{H}_k$ is a diffeomorphism, $\mathcal{H}_k(U_k \cap \Omega) = Q_+$, and $\mathcal{H}_k(U_k \cap \Gamma) = Q_0$, supp $\varphi_k \subset U_k$, and $\Phi = 1$ in a neighborhood of $\partial \Omega \cap \Gamma$, where

\[
\Phi := \sum_{k=1}^{\ell} \varphi_k \text{ in } \mathbb{R}^3.
\]

By Lemma 4.2, for $1 \leq k \leq \ell$, there exists $\hat{E}_k \in H(\text{curl}, U_k \cap \Omega)$ and an open $V_k \subset \mathbb{R}^3$ containing $\partial U_k \cap \Omega$ such that

\[
\nabla \times \hat{E}_k = \nabla \times (\varphi_k \hat{E}) \quad \text{in} \: U_k \cap \Omega.
\]
\[ \| \hat{E}_k \|_{L^2(U_k \cap \Omega)} \leq C \| \hat{E} \|_{L^2(d_{\beta}^+, U_k \cap \Omega)}, \]
\[ \hat{E}_k = 0 \text{ in } U_k \cap \Omega \cap V_k. \]

Here and in what follows, \( C \) denotes a positive constant depending only on \( c, \alpha_1, \beta, \Omega, \varepsilon, \hat{\varepsilon}, \mu, \) and \( \hat{\mu} \); thus \( C \) is independent of \( s \).

Set, for \( 1 \leq k \leq \ell \),
\[ \delta_{\psi_k} E = \psi_k (E - \hat{E}) \text{ in } U_k \cap \Omega. \]

Let \( s_1 \) be a small positive number defined later. Since \((E - \hat{E}) \times \nu = 0 \text{ on } \partial \Omega \cap \Gamma,\) by Lemma 4.4, for \( 1 \leq k \leq \ell \), there exists \( \delta_{E_k} \in H^1_0(U_k \cap \Omega) \) such that
\[ \nabla \times \delta_{E_k} = \nabla \times \delta_{\psi_k} E \text{ in } U_k \cap \Omega, \]
\[ \| \delta_{E_k} \|_{L^2(d_{\beta}^+, U_k \cap \Omega)} \leq C_{s_1} \| \delta_{\psi_k} E \|_{L^2(d_{\beta}^+, U_k \cap \Omega)} + s_1 \| \delta_{\psi_k} E \|_{H(\text{curl}, U_k \cap \Omega)}. \]

It is clear then
\[ \delta_{E_k} = 0 \text{ in } \partial(U_k \cap \Omega). \]

We have, in \( \Omega \),
\[ \nabla \times (\psi_k E - \psi_k \hat{E}) = \nabla \psi_k \times (E - \hat{E}) + \psi_k \nabla (E - \hat{E}) \]
\[ = (4.10) \nabla \psi_k \times (E - \hat{E}) + i \omega \psi_k (\mu H - \hat{\mu} \hat{H}) + \psi_k (J_e - \hat{J}_e). \]

We derive from (4.18) that
\[ \| \delta_{E_k} \|_{L^2(d_{\beta}^+, U_k \cap \Omega)} \leq C_{s_1} \| E - \hat{E} \|_{L^2(d_{\beta}^+, U_k \cap \Omega)} \]
\[ + C_{s_1} \| (E - \hat{E}, \mu H - \hat{\mu} \hat{H}, J_e - \hat{J}_e) \|_{L^2(U_k \cap \Omega)}. \]

For \( 1 \leq k \leq \ell \), let \( \xi_k, \eta_k \in H^1(U_k \cap \Omega) \) be such that
\[ \nabla \xi_k = \delta_{\psi_k} E - \delta_{E_k} \text{ and } \nabla \eta_k = \psi_k \hat{E} - \hat{\xi}_k \text{ in } U_k \cap \Omega. \]

Such \( \xi_k \) and \( \eta_k \) exist by Poincare’s lemma, (4.14), and (4.17); moreover, one can assume that
\[ \xi_k = 0 \text{ on } \partial(U_k \cap \Omega) \text{ and } \eta_k = 0 \text{ on } \partial U_k \cap \Omega \]
\[ \text{since } \nabla \xi_k \times \nu = 0 \text{ on } \partial(U_k \cap \Omega) \text{ by (4.19) and } \nabla \eta_k \times \nu = 0 \text{ on } \partial U_k \cap \Omega \text{ by (4.16).} \]

Extend \( \xi_k \) and \( \eta_k \) by 0 in \( \Omega \setminus U_k \) and still denote these extensions by \( \xi_k \) and \( \eta_k \). Set, in \( \Omega \),
\[ F_E = \Phi \left( \varepsilon E - \hat{\xi}_k \hat{E} + \frac{i}{\omega} J_m - \frac{i}{\omega} \hat{J}_m \right) + \frac{i}{\omega} \nabla \Phi \times (H - \hat{H}), \]
\[ \delta_f = \sum_{k=1}^\ell \delta_{E_k}, \quad f = \sum_{k=1}^\ell \hat{E}_k, \quad \text{and } \delta_{\Phi E} = \Phi (E - \hat{E}). \]

It follows from (4.21) and (4.24) that, in \( \Omega \),
\[ \sum_{k=1}^\ell \nabla \xi_k = \delta_{\Phi E} - \delta_f \text{ and } \sum_{k=1}^\ell \nabla \eta_k = \Phi \hat{E} - f, \]
and from (4.15) and (4.20) that
\[ \| \delta f \|_{L^2(d \mathcal{M}, \Omega)} + \| f \|_{L^2(\Omega)} \leq C s_1 \| (J_e, \hat{J}_e) \|_{L^2(\Omega)} \]
\[ + C s_1 \| (E, \hat{E}, H, \hat{H}) \|_{L^2(d \mathcal{M}, \Omega)} + C s_1 \| (E - \hat{E}, \mu H - \hat{\mu} \hat{H}) \|_{L^2(U_k \cap \Omega)}. \]  
(4.26)

Since, by (4.10) and (4.23),
\[ F_E = \frac{i}{\omega} \nabla \times (\Phi H) - \frac{i}{\omega} \nabla \times (\Phi \hat{H}) \text{ in } \Omega \]
and, by (4.11),
\[ (\nabla \times (\Phi H - \Phi \hat{H})) \cdot \nu = \text{div}_\Gamma ((\Phi H - \Phi \hat{H}) \times \nu) = 0 \text{ on } \partial \Omega \cap \Gamma, \]
we obtain
\[ \text{div } F_E = 0 \text{ in } \Omega \quad \text{and} \quad F_E \cdot \nu = 0 \text{ on } \partial \Omega \cap \Gamma. \]  
(4.27)

From (4.22) and (4.27), we have, for \( 1 \leq k \leq \ell \),
\[ \int_\Omega \langle F_E, \nabla \eta_k \rangle = 0. \]

Summing this identity with respect to \( k \) and using (4.25), we obtain
\[ \int_\Omega \langle F_E, \Phi \hat{E} \rangle = \int_\Omega \langle F_E, f \rangle. \]  
(4.28)

We have, for \( 1 \leq k \leq \ell \),
\[ \frac{i}{\omega} (\nabla \times (\varphi_k \hat{H}) - \nabla \varphi_k \times \hat{H}) = \frac{i}{\omega} \varphi_k \nabla \times \hat{H} \overset{(4.10)}{=} \hat{e}(\varphi_k \hat{E}) + \frac{i}{\omega} \varphi_k \hat{J}_m \text{ in } \Omega. \]

It follows that
\[ \text{div}[\hat{e}(\varphi_k \hat{E})] = -\frac{i}{\omega} \text{div} (\varphi_k \hat{J}_m + \nabla \varphi_k \times \hat{H}) \text{ in } \Omega. \]

We derive that, for \( 1 \leq k, l \leq \ell \),
\[ \int_\Omega \langle \hat{e} \nabla \xi_l, \varphi_k \hat{E} \rangle = \int_\Omega \langle \nabla \xi_l, \varphi_k \hat{J}_m + \nabla \varphi_k \times \hat{H} \rangle, \]  
(4.29)

since \( \xi_l = 0 \) on \( \partial \Omega \). Summing with respect to \( k \) and \( l \) and using (4.25), we get
\[ \int_\Omega \langle \hat{e}(\delta \Phi E - \delta f), \Phi \hat{E} \rangle = \int_\Omega \langle \delta \Phi E - \delta f, \Phi \hat{J}_m + \nabla \Phi \times \hat{H} \rangle. \]

This yields
\[ \int_\Omega \langle \hat{e} \delta \Phi E, \Phi \hat{E} \rangle = \int_\Omega \langle \hat{e} \delta f, \Phi \hat{E} \rangle + \int_\Omega \langle \delta \Phi E - \delta f, \Phi \hat{J}_m + \nabla \Phi \times \hat{H} \rangle. \]  
(4.30)

Noting that \( \varepsilon E - \hat{e} \hat{E} = (\varepsilon - \hat{\varepsilon}) \hat{E} \) in \( \Omega \), we obtain from (4.23) that
\[ F_E = \varepsilon \delta \Phi E + (\varepsilon - \hat{\varepsilon}) \Phi \hat{E} + \frac{i}{\omega} \Phi \left( J_m - \hat{J}_m \right) + \frac{i}{\omega} \nabla \Phi \times (H - \hat{H}) \text{ in } \Omega. \]  
(4.31)
Subtracting (4.30) from (4.28) and using (4.31), we have
\[
\begin{align*}
\int_{\Omega} \langle (\varepsilon - \hat{\varepsilon}) \delta_{\Phi E}, \Phi \hat{E} \rangle &+ \int_{\Omega} \langle (\varepsilon - \hat{\varepsilon}) \Phi \hat{E}, \Phi \hat{E} \rangle \\
&= -\frac{i}{\omega} \int_{\Omega} \langle \Phi \left( J_m - \hat{J}_m \right) + \nabla \Phi \times (H - \hat{H}), \Phi \hat{E} \rangle \\
&+ \int_{\Omega} \langle F_E, f \rangle - \int_{\Omega} \langle \hat{\varepsilon} \delta_f, \Phi \hat{E} \rangle - \frac{i}{\omega} \int_{\Omega} \langle \delta_{\Phi E} - \delta_f, \Phi \hat{J}_m + \nabla \Phi \times H \rangle.
\end{align*}
\] (4.32)

From (4.22) and (4.27), we derive that, for \(1 \leq k \leq \ell\),
\[
\int_{\Omega} \langle F_E, \nabla \xi_k \rangle = 0.
\] (4.33)

Summing (4.33) with respect to \(k\) and using (4.25), we get
\[
\int_{\Omega} \langle F_E, \delta_{\Phi E} - \delta_f \rangle = 0.
\]

It follows from (4.31) that
\[
\begin{align*}
\int_{\Omega} \langle \varepsilon \delta_{\Phi E}, \delta_{\Phi E} \rangle &+ \int_{\Omega} \langle \varepsilon - \hat{\varepsilon} \rangle \Phi \hat{E}, \delta_{\Phi E} \rangle \\
&= -\frac{i}{\omega} \int_{\Omega} \langle \Phi (J_m - \hat{J}_m) + \nabla \Phi \times (H - \hat{H}), \delta_{\Phi E} \rangle + \int_{\Omega} \langle F_E, \delta_f \rangle.
\end{align*}
\] (4.34)

We have, by (4.31),
\[
\left| \int_{\Omega} \langle F_E, f \rangle \right| \leq C \left( \int_{\Omega} |f|^2 \right)^{1/2} \left( \int_{\Omega} |\langle (\varepsilon - \hat{\varepsilon}) \Phi \hat{E}, \Phi \hat{E} \rangle| + |\delta_{\Phi E}|^2 \right)^{1/2} \\
+ C \int_{\Omega} |(f, J_m, \hat{J}_m, \nabla \Phi \times H, \nabla \Phi \times \hat{H})|^2.
\] (4.35)

Since \(\varepsilon - \hat{\varepsilon} \geq 0\) and \(\varepsilon\) is uniformly elliptic, we deduce that
\[
\langle (\varepsilon - \hat{\varepsilon}) x, x \rangle + \langle \varepsilon y, y \rangle + \langle (\varepsilon - \hat{\varepsilon}) x, y \rangle + \langle (\varepsilon - \hat{\varepsilon}) y, x \rangle \geq C \left( \langle (\varepsilon - \hat{\varepsilon}) x, x \rangle + \langle \varepsilon y, y \rangle \right),
\]
for any \(x, y \in \mathbb{R}^3\). It follows from (4.32), (4.34), and (4.35) that
\[
\begin{align*}
\int_{\Omega} |\langle (\varepsilon - \hat{\varepsilon}) \Phi \hat{E}, \Phi \hat{E} \rangle| + |\delta_{\Phi E}|^2 &\leq C \int_{\Omega} |(J_m, \hat{J}_m, \nabla \Phi \times H, \nabla \Phi \times \hat{H}, f, \delta_f) + C \int_{\Omega} \langle \hat{\varepsilon} \delta_f, \Phi E \rangle \}
+ C \int_{\Omega} |J_m - \hat{J}_m| |\hat{E}| + C \int_{\Omega} |\nabla \Phi \times (H - \hat{H})| |\Phi \hat{E}|.
\end{align*}
\] (4.36)

We next estimate \( \int_{\Omega} \langle \hat{\varepsilon} \delta_f, \Phi E \rangle \). Since
\[
\left| \int_{\Omega} \langle \hat{\varepsilon} \delta_f, \Phi E \rangle \right| = \left| \int_{\Omega} \langle (\varepsilon - \hat{\varepsilon})^{-1/2} \hat{\varepsilon} \delta_f, (\varepsilon - \hat{\varepsilon})^{1/2} \Phi E \rangle \right|
\]
\[ \leq \frac{1}{4s} \int_\Omega \langle (\varepsilon - \hat{\varepsilon})^{-1/2} \hat{\varepsilon} \delta_f, (\varepsilon - \hat{\varepsilon})^{-1/2} \hat{\varepsilon} \delta_f \rangle + s \int_\Omega \langle (\varepsilon - \hat{\varepsilon})^{1/2} \Phi E, (\varepsilon - \hat{\varepsilon})^{1/2} \Phi E \rangle \]

and \( \varepsilon - \hat{\varepsilon} \geq c dI^{\alpha_1} \) in \( \Omega \), we obtain

\[ \left| \int_\Omega \langle \hat{\varepsilon} \delta_f, \Phi E \rangle \right| \leq \frac{C}{s} \int_\Omega d\Gamma^{2\alpha_1}|\delta_f|^2 + s \int_\Omega \langle (\varepsilon - \hat{\varepsilon}) \Phi E, \Phi E \rangle. \quad (4.37) \]

Combining (4.26) and (4.37) yields

\[ \left| \int_\Omega \langle \hat{\varepsilon} \delta_f, \Phi E \rangle \right| \leq C_{s,s1} \int_\Omega |(J_e, \hat{J}_e)|^2 + C_{s,s1} \int_\Omega d\Gamma^\beta |(E, \hat{E}, H, \hat{H})|^2 \]

\[ + \frac{Cs}{s} \int_\Omega |(\mu H - \hat{\mu} \hat{H}, E - \hat{E})|^2 + s \int_\Omega \langle (\varepsilon - \hat{\varepsilon}) \Phi E, \Phi E \rangle. \quad (4.38) \]

Using (4.26) and the fact \( \Phi = 1 \) in a neighborhood of \( \Gamma \cap \partial \Omega \), we derive from (4.36) and (4.38) that

\[ \int_\Omega |\langle (\varepsilon - \hat{\varepsilon}) \Phi \hat{E}, \Phi \hat{E} \rangle| + |\delta_{\varepsilon E}|^2 \]

\[ \leq C_{s,s1} \int_\Omega |(J_e, \hat{J}_e, J_m, \hat{J}_m)|^2 + C_{s,s1} \int_\Omega d\Gamma^\beta |(E, \hat{E}, H, \hat{H})|^2 \]

\[ + \frac{Cs}{s} \int_\Omega |(\mu H - \hat{\mu} \hat{H}, E - \hat{E})|^2 \]

\[ + Cs \int_\Omega \langle (\varepsilon - \hat{\varepsilon}) \Phi E, \Phi E \rangle + C \int_\Omega |J_m - \hat{J}_m||\hat{E}|. \quad (4.39) \]

Take \( s_1 = Cs^2 \). One derives from (4.39) that, for \( s \) small,

\[ \int_\Omega |\langle (\varepsilon - \hat{\varepsilon}) \Phi \hat{E}, \Phi \hat{E} \rangle| + |\delta_{\varepsilon E}|^2 \leq C_s \int_\Omega |(J_e, \hat{J}_e, J_m, \hat{J}_m)|^2 + C_s \int_\Omega d\Gamma^\beta |(E, \hat{E}, H, \hat{H})|^2 \]

\[ + s \int_\Omega |(\mu H - \hat{\mu} \hat{H})|^2 + C \int_\Omega |J_e - \hat{J}_e||\hat{H}|, \]

which implies (4.12). \( \square \)

Remark 4.2. The proof of Lemma 4.5 involves local charts. The involvement is of a global character in the sense that one has to combine local charts before deriving desired estimates in some parts of the proof, see (4.36) and (4.39). In fact, one cannot derive variants of (4.12) and (4.13) for \( (\varphi_k E, \varphi_k \hat{E}, \varphi_k H, \varphi_k \hat{H}) \). To this end, note that, in \( U \cap \Omega \),

\[
\begin{align*}
\nabla \times (\varphi_k E) = i \omega \mu (\varphi_k H) + J_{e,k}, \\
\nabla \times (\varphi_k H) = -i \omega \varepsilon (\varphi_k E) + J_{m,k}
\end{align*}
\]

where

\[ J_{e,k} = \varphi_k J_e + \nabla \varphi_k \times E, \quad \hat{J}_{e,k} = \varphi_k \hat{J}_e + \nabla \varphi_k \times \hat{E}, \]

\[ J_{m,k} = \varphi_k J_m + \nabla \varphi_k \times H, \quad \hat{J}_{m,k} = \varphi_k \hat{J}_m + \nabla \varphi_k \times \hat{H}. \]

Due to the terms \( \nabla \varphi_k \times E, \nabla \varphi_k \times \hat{E}, \nabla \varphi_k \times H, \) and \( \nabla \varphi_k \times \hat{H} \) in \( J_{e,k}, \hat{J}_{e,k}, J_{m,k}, \) and \( \hat{J}_{m,k}, \) respectively, we are not able to derive the variants of (4.12) and (4.13) for
\( (\varphi_k E, \varphi_k \hat{E}, \varphi_k H, \varphi_k \hat{H}) \). This combination is the key difference between the proof strategies of Lemmas 4.5 and 3.4 and makes the proof of Lemma 4.5 more involved. Another difference between the proofs is that one considers the extensions of \( \varphi E_k \) and \( \varphi_k (E - \hat{E}) \) in the proof Lemma 4.5 instead of the extensions of \( \varphi E_k \) and \( \varphi_k \hat{E} \) as in the proof Lemma 3.4 to ensure integration by parts arguments, see (4.29) where \( \xi_k = 0 \) on \( \partial(\Omega \cap U_k) \) is required.

4.2. Proof of Theorem 2.2. For a simpler presentation, we will assume that \( D_{-\tau} \) is connected. We first consider the case where \( \alpha_1 + \alpha_2 > 0 \). Set

\[
\beta = (\max\{\alpha_1, \alpha_2\} + 2)/2
\]

and

\[
\delta E_\delta = E_\delta - \hat{E}_\delta \text{ in } D_{-\tau} \quad \text{and} \quad \delta H_\delta = H_\delta - \hat{H}_\delta \text{ in } D_{-\tau}.
\]

Then

\[
\max\{\alpha_1, \alpha_2\} < \beta < 2. \tag{4.40}
\]

We first prove by contradiction that

\[
\| (E_\delta, H_\delta) \|_{L^2(d\beta/\Gamma_1, B_{R_0})} \leq C \| J \|_{L^2(\mathbb{R}^3)}. \tag{4.41}
\]

Assume, for some \( \delta_n \to 0 \) and \( J_n \in [L^2(\mathbb{R}^3)]^3 \) with \( \text{supp } J_n \subset B_{R_0} \setminus ((D_{-\tau} \cup \mathcal{F}^{-1}(D_{-\tau})) = \emptyset \) that

\[
\lim_{n \to +\infty} \| J_n \|_{L^2(\mathbb{R}^3)} = 0 \quad \text{and} \quad \| (E_n, H_n) \|_{L^2(d\beta/\Gamma_1, B_{R_0})} = 1, \tag{4.42}
\]

where \((E_n, H_n)\) is the solution corresponding to \( \delta_n \) and \( J_n \). Integrating by parts and using the radiating condition, as usual, we obtain

\[
3 \int_{B_{R_0}} \langle \mu^{-1}_{\delta_0} \nabla \times E_n, \nabla \times E_n \rangle - \omega^2 \langle \varepsilon_{\delta_0} E_n, E_n \rangle - \omega^2 \langle \varepsilon_{\delta_0} E_n, E_n \rangle \leq \left| \int_{B_{R_0}} \langle \omega J_n, E_n \rangle \right| \to 0 \text{ as } n \to +\infty.
\]

This implies

\[
\int_D \delta_n (|E_n|^2 + |H_n|^2) \to 0 \text{ as } n \to +\infty. \tag{4.43}
\]

By a change of variables for the Maxwell equations, see e.g. [24, Lemma 7], we have

\[
\left\{ \begin{array}{ll}
\nabla \times E_n = i\omega \mu H_n & \text{in } D_{-\tau}, \\
\nabla \times H_n = -i\omega \varepsilon E_n & \text{in } D_{-\tau}, \\
\end{array} \right.
\]

and

\[
\left\{ \begin{array}{ll}
\nabla \times \hat{E}_n = i\omega \hat{\mu} \hat{H}_n + \hat{J}_{e,n} & \text{in } D_{-\tau}, \\
\nabla \times \hat{H}_n = -i\omega \hat{\varepsilon} \hat{E}_n + \hat{J}_{m,n} & \text{in } D_{-\tau}, \\
\end{array} \right.
\]

and

\[
E_n \times \nu = \hat{E}_n \times \nu \quad \text{and} \quad H_n \times \nu = \hat{H}_n \times \nu \quad \text{on } \Gamma.
\]

Here

\[
\hat{J}_{e,n} = -\delta \omega \mathcal{F} I \hat{H}_n \quad \text{and} \quad \hat{J}_{m,n} = \delta \omega \mathcal{F} I \hat{E}_n \text{ in } D_{-\tau}.
\]
Note that, in $D_{-\tau}$,
\[
\varepsilon E - \hat{\varepsilon} \hat{E} = (\varepsilon - \hat{\varepsilon})E + \hat{\varepsilon}(E - \hat{E})
\]
and
\[
\mu H - \hat{\mu} \hat{H} = (\mu - \hat{\mu})H + \hat{\mu}(H - \hat{H}).
\]
Applying (4.12) and (4.13) for a sufficiently small $s$ and using (4.43), we have
\[
\int_{D_{-\tau}} |\langle (\varepsilon - \hat{\varepsilon}) E_n, E_n \rangle| + \int_{D_{-\tau}} |\langle (\mu - \hat{\mu}) H_n, H_n \rangle| + \int_{D_{-\tau}} |(\delta E_n, \delta H_n)|^2 \leq C.
\]  
(4.44)
This implies
\[
\|E_n\|_{L^2(d_{\Gamma}^1, B_{R_0})} + \|H_n\|_{L^2(d_{\Gamma}^2, B_{R_0})} \leq C.
\]  
(4.45)
Fix $\psi \in C^1_c(\mathbb{R}^3)$ (arbitrary) such that $\psi = 0$ in a neighborhood of $\Gamma$. We have, in $\mathbb{R}^3$,
\[
\nabla \times (\psi E_n) = \psi \nabla \times E_n + \nabla \psi \times E_n \quad \text{and} \quad \text{div}[\varepsilon_0(\psi E_n)] = \psi \text{div}(\varepsilon_0 E_n) + \nabla \psi \cdot \varepsilon_0 E_n.
\]
Using (4.40) and (4.41), and applying [24, Lemma 1], one may assume that
\[
(\psi E_n) \text{ converges in } [L^2(\mathbb{R}^3)]^3,
\]
which yields, since $\psi$ is arbitrary,
\[
(E_n) \text{ converges in } [L^2_{\text{loc}}(\mathbb{R}^3 \setminus \Gamma)]^3.
\]  
(4.46)
Similarly, one may also assume that
\[
(H_n) \text{ converges in } [L^2_{\text{loc}}(\mathbb{R}^3 \setminus \Gamma)]^3.
\]  
(4.47)
Moreover, from (4.45), (4.46), (4.47) and the fact $\beta > \max\{\alpha_1, \alpha_2\}$, by Lemma 4.3, one may assume that
\[
((E_n, H_n)) \text{ converges in } [L^2(d_{\Gamma}^\beta, B_{R_0})]^6
\]  
(4.48)
and, by (4.44),
\[
((\delta E_n, \delta H_n)) \text{ converges weakly in } [L^2(D_{-\tau})]^6.
\]  
(4.49)
Let $(E, H)$ be the limit of $((E_n, H_n))$ in $[L^2_{\text{loc}}(\mathbb{R}^3 \setminus \Gamma)]^6$. From (4.44), we derive that $(\delta E, \delta H) \in [L^2(D_{-\tau})]^2$. From the equations of $(E, H)$, it follows that $(\delta E, \delta H) \in [H(\text{curl}, D_{-\tau})]^2$. One also has
\[
\delta E \times v = \delta H \times v = 0 \text{ on } \Gamma.
\]  
(4.50)
We have, for $R > R_0$,
\[
\lim_{n \to +\infty} \left| \Re \int_{\partial B_R} H \times v \cdot \hat{E}_n \right| \leq \lim_{n \to +\infty} \left| \Re \int_{\partial B_R} H_n \times v \cdot \hat{E}_n \right| \overset{(4.43)}{=} \lim_{n \to +\infty} \left| \Re \int_{B_R} J_n \hat{E}_n \right| \overset{(4.42)}{=} 0.
\]
Since \((E, H)\) satisfies the radiating condition, it follows that
\[
E = H = 0 \text{ in the unbounded connected component of } \mathbb{R}^3 \setminus \bar{D},
\]
which in turn implies, by (4.50) and the unique continuation principle, that
\[
E = H = 0 \text{ in } \mathbb{R}^3.
\]
(4.51)
Combining (4.42), (4.48), (4.49), and (4.51) yields a contradiction. Hence (4.41) is proved. Applying Lemma 4.5 again, we derive (2.3) from (4.41).

By the same method, one also obtains the following fact: for any \((\delta_n, H_{\delta_n})\) converges in \([L^2_{\text{loc}}(\mathbb{R}^3)]\), and the limit is a radiating solution of the corresponding system.

We next consider the case \(\alpha_1 = \alpha_2 = 0\). We first prove by contradiction that
\[
\|(E_{\delta}, H_{\delta})\|_{L^2(B_{R_0})} \leq C \|J\|_{L^2(\mathbb{R}^3)}.
\]
Assume, for some \(\delta_n \to 0\) and \(J_n \in L^2(\mathbb{R}^3)\) with \(\text{supp} \ J_n \subset B_{R_0}\) that
\[
\lim_{n \to +\infty} \|J_n\|_{L^2(\mathbb{R}^3)} = 0 \quad \text{and} \quad \|(E_n, H_n)\|_{L^2(B_{R_0})} = 1,
\]
(4.52)
where \((E_n, H_n)\) is the solution corresponding to \(\delta_n\) and \(J_n\). By a change of variables for the Maxwell equations, see e.g. [24, Lemma 7], we have
\[
\begin{align*}
\nabla \times E_n &= i \omega \mu H_n \quad \text{in } D_{-\tau}, \\
\nabla \times H_n &= -i \omega \varepsilon E_n + J_n \quad \text{in } D_{-\tau},
\end{align*}
\]
and
\[
E_n \times \nu = \hat{E}_n \times \nu \quad \text{and} \quad H_n \times \nu = \hat{H}_n \times \nu \quad \text{on } \Gamma.
\]

Here
\[
\hat{J}_{e,n} = -\delta \omega \varepsilon \mathcal{F}_* \hat{H}_n \quad \text{and} \quad \hat{J}_{m,n} = \delta \omega \mu \mathcal{F}_* \hat{E}_n + \mathcal{F}_* J_n \quad \text{in } D_{-\tau}.
\]
Note that
\[
\int_{\Omega} |J_n - \hat{J}_{m,n}| |\hat{E}_n| + |\hat{J}_{e,n}| |\hat{H}_n| \leq \left( \int_{\Omega} |(J_n, \hat{J}_{m,n}, \hat{J}_{e,n})|^2 \right)^{1/2} \left( \int_{\Omega} |(\hat{E}_n, \hat{H}_n)|^2 \right)^{1/2}.
\]
As in (4.45), we then have
\[
\|E_n\|_{L^2(B_{R_0})} + \|H_n\|_{L^2(B_{R_0})} \leq C.
\]
As in the proof of Theorem 2.1, one can prove that, up to a subsequence,
\[
(E_n, H_n) \text{ converges in } [L^2_{\text{loc}}(\mathbb{R}^3)]^{12}.
\]
Moreover, the limit \((E_0, H_0)\) is in \([H_{\text{loc}}(\text{curl}, \mathbb{R}^3)]^2\) and is a radiating solution of the equations
\[
\begin{align*}
\nabla \times E_0 &= i \omega \mu_0 H \quad \text{in } \mathbb{R}^3, \\
\nabla \times H_0 &= -i \omega \varepsilon_0 E \quad \text{in } \mathbb{R}^3.
\end{align*}
\]
By Lemma 3.6, we get
\[
E_0 = H_0 = 0 \text{ in } \mathbb{R}^3.
\]
This contradicts (4.52) and (4.53). The uniqueness of \((E_0, H_0)\) is a consequence of Lemma 3.6 and the strong convergence of \((E_{\delta}, H_{\delta})\) to \((E_0, H_0)\) in \([L^2_{\text{loc}}(\mathbb{R}^3)]^{12}\) can be derived as in the proof of Theorem 2.1 and are omitted. \(\square\)
4.3. Some applications of Theorem 2.2. In this section, we present two applications of Theorem 2.2. The first is a consequence of Theorem 2.2 with \( \alpha_1 = \alpha_2 = 0 \). We have

**Corollary 4.1.** Let \( 0 < \delta < 1 \), \( J \in [L^2(\mathbb{R}^3)]^3 \) with supp \( J \subset B_{R_0} \), and let \((E_\delta, H_\delta) \in [H_{\text{loc}}(\text{curl}, \mathbb{R}^3)]^2\) be the unique radiating solution of (1.3). Assume that \( D \) is of class \( C^2 \) and, for each connected component \( O \) of \( D \), \( \tau > 0 \) small, the following four conditions hold:

- either \( \varepsilon^+|_{D_{-\tau}\cap O} \) or \( \varepsilon^-|_{D_{\tau}\cap O} \) is isotropic,
- either \( \mu^+|_{D_{-\tau}\cap O} \) or \( \mu^-|_{D_{\tau}\cap O} \) is isotropic,
- \( \varepsilon^+(x_\Gamma - tv(x_\Gamma)) \geq -\varepsilon^-(x_\Gamma + tv(x_\Gamma)) + cI \) or \( -\varepsilon^-(x_\Gamma - tv(x_\Gamma)) \geq \varepsilon^+(x_\Gamma + tv(x_\Gamma)) + cI \)

and

- \( \mu^+(x_\Gamma - tv(x_\Gamma)) \geq -\mu^-(x_\Gamma + tv(x_\Gamma)) + cI \) or \( -\mu^-(x_\Gamma - tv(x_\Gamma)) \geq \mu^+(x_\Gamma + tv(x_\Gamma)) + cI \),

for every \( x_\Gamma \in \Gamma \cap O \) and for every \( t \in (0, \tau) \), for some \( c > 0 \). Then, for all \( R > 0 \),

\[
\int_{B_R} |(E_\delta, H_\delta)|^2 \leq C_R \| J \|^2_{L^2(\mathbb{R}^3)}
\]

for some positive constant \( C_R \) independent of \( \delta \) and \( J \). Moreover, \((E_\delta, H_\delta)\) converges to \((E_0, H_0)\) strongly in \([L^2_{\text{loc}}(\mathbb{R}^3)]^6\), as \( \delta \to 0 \), where \((E_0, H_0) \in [H_{\text{loc}}(\text{curl}, \mathbb{R}^3)]^2\) is the unique radiating solution of (1.3) with \( \delta = 0 \). As a consequence,

\[
\int_{B_R} |(E_0, H_0)|^2 \leq C_R \| J \|^2_{L^2(\mathbb{R}^3)}
\]

**Remark 4.3.** It is worth comparing Corollary 4.1 with Corollary 2.1. First, in Corollary 4.1, one does not require \( \varepsilon^+, \varepsilon^-, \mu^+, \mu^- \) to be \( C^1 \) near \( \Gamma \). Second, in Corollary 2.1, one does not require any isotropy conditions on \( \varepsilon^+, \varepsilon^-, \mu^+, \mu^- \).

**Proof.** For \( \tau > 0 \) sufficiently small (the smallness depends only on \( D \)), define \( \mathcal{F} : D_{\tau} \cup \Gamma \cup D_{-\tau} \to D_{\tau} \cup \Gamma \cup D_{-\tau} \) by

\[
\mathcal{F}(x_\Gamma + tv(x_\Gamma)) = x_\Gamma - tv(x_\Gamma) \quad \forall x_\Gamma \in \Gamma, \, t \in (-\tau, \tau)
\]

and set, in \( D_{-\tau} \),

\[
(\hat{\varepsilon}, \hat{\mu}) = (\mathcal{F}_\# \varepsilon^-, \mathcal{F}_\# \mu^-).
\]

For the simplicity of the presentation, we assume that \( D_{-\tau} \) is connected. We will only consider the case

- \( \varepsilon^+|_{D_{-\tau}} \) is isotropic,
- \( \mu^+|_{D_{-\tau}} \) is isotropic,
- \( \varepsilon^+(x_\Gamma - tv(x_\Gamma)) \geq -\varepsilon^-(x_\Gamma + tv(x_\Gamma)) + cI \),

and

- \( \mu^+(x_\Gamma - tv(x_\Gamma)) \geq -\mu^-(x_\Gamma + tv(x_\Gamma)) + cI \),
for every \( x_\Gamma \in \Gamma \cap O \) and for every \( 0 < t < \tau \), for some \( c > 0 \). The other cases can be dealt similarly.

For \( x' \in D_\tau \), set \( x = \mathcal{F}^{-1}(x') \) and \( J(x) = \det \nabla \mathcal{F}(x) \). We have, for \( x \in \Gamma \),

\[
\nabla \mathcal{F}^{-1}(x) \nabla \mathcal{F}^{-T}(x) = I \quad \text{and} \quad J(x) = -1.
\]

Since \( \varepsilon^+ \) is isotropic and \( \varepsilon^+(x_\Gamma - tv(x_\Gamma)) \geq -\varepsilon^-(x_\Gamma + tv(x_\Gamma)) + cI \) in \( D_{-\tau} \), it follows from the definition of \( \hat{\varepsilon} \) that, for sufficiently small \( \tau \),

\[
\varepsilon(x') \geq \hat{\varepsilon}(x') + cI/2 \quad \text{for} \quad x' \in D_{-\tau}.
\]

Similarly, we have, for sufficiently small \( \tau \),

\[
\mu(x') \geq \hat{\mu}(x') + cI/2 \quad \text{for} \quad x' \in D_{-\tau}.
\]

Take \( \tau \) sufficiently small such that (4.54) and (4.55) hold. Applying Theorem 2.2, we obtain the conclusion. \( \square \)

Here is a direct consequence of Corollary 4.1. Let \( \Omega_1 \) and \( \Omega_2 \) be open subsets of \( D \) such that \( \Omega_1 \cap \Omega_2 = \emptyset \), \( D = \Omega_1 \cup \Omega_2 \), \( \partial \Omega_1 \cap \partial D \neq \emptyset \), and \( \partial \Omega_2 \cap \partial D \neq \emptyset \). Assume that \( \varepsilon^- = -\gamma_1 I \) in \( \Omega_1 \) and \( = -\gamma_2 I \) in \( \Omega_2 \), and \( \varepsilon^+ = I \) in \( \mathbb{R}^3 \setminus D \) for some constants \( \gamma_1, \gamma_2 > 0 \) with \( \min\{\gamma_1, \gamma_2\} > 1 \) or \( \max\{\gamma_1, \gamma_2\} < 1 \). For \( J \in L^2(\mathbb{R}^3) \) with \( \text{supp} \ J \subset B_{R_0}^c \), let \( (E_\delta, H_\delta) \in [H_{\text{loc}}(\text{curl}, \mathbb{R}^3)]^2 \) be the unique radiating solution of (1.3) for \( 0 < \delta < 1 \). We have \( (E_\delta, H_\delta) \) is bounded in \( [L^2_{\text{loc}}(\mathbb{R}^3)]^6 \). Moreover, \( (E_\delta, H_\delta) \) converges to \( (E_0, H_0) \) strongly in \( [L^2_{\text{loc}}(\mathbb{R}^3)]^6 \), the unique radiating solution of (1.3) with \( \delta = 0 \). Note that this setting is out of the scope of Corollary 2.1 for \( \gamma_1 \neq \gamma_2 \).

Here is another consequence of Theorem 2.2 for which \( \alpha_1 = \alpha_2 = 1 \). We first introduce

**Definition 4.1.** A connected component of \( \Gamma \) is called strictly convex if it is the boundary of a strictly convex set.

We have

**Corollary 4.2.** Let \( 0 < \delta < 1 \), \( \tau > 0 \), \( J \in [L^2(\mathbb{R}^3)]^3 \) with \( \text{supp} \ J \subset B_{R_0}^c \setminus (D_{\tau} \cup D_{-\tau}) \), and let \( (E_\delta, H_\delta) \in [H_{\text{loc}}(\text{curl}, \mathbb{R}^3)]^2 \) be the unique radiating solution of (1.3). Let \( e, m \) be positive symmetric matrix-valued functions defined in \( D_{-\tau} \cup \Gamma \cup D_{\tau} \) such that they are constant and isotropic on each connected component of their domain of definition. Assume that

\[
D \text{ is of class } C^3, \text{ each connected component of } \Gamma \text{ is strictly convex},
\]

\[
(\varepsilon^+, \mu^+) = (e, m) \text{ in } D_{-\tau}, \quad \text{and} \quad (\varepsilon^-, \mu^-) = -(e, m) \text{ in } D_{\tau}.
\]

Then, for \( R > 0 \) and open \( V \supset \Gamma \),

\[
\|(E_\delta, H_\delta)\|_{L^2(B_R \setminus V)} \leq C_{R,V} \|J\|_{L^2(\mathbb{R}^3)} \quad \forall R > 0,
\]

(4.56)

for some positive constant \( C_{R,V} \) independent of \( \delta \) and \( J \). Moreover, for a sequence \( (\delta_n) \to 0 \), up to a subsequence, \( (E_{\delta_n}, H_{\delta_n}) \) converges to \( (E_0, H_0) \) strongly in \( L^2_{\text{loc}}(\mathbb{R}^3 \setminus \Gamma) \) as \( n \to +\infty \), where \( (E_0, H_0) \in [H_{\text{loc}}(\text{curl}, \mathbb{R}^3 \setminus \Gamma)]^2 \) is a radiating solution of (1.3) with \( \delta = 0 \) and (4.56) holds with \( \delta = 0 \).
Proof. For simple presentation, we assume that $D$ is convex. Let $\mathcal{F}$ be defined as follows:

$$ x_\Gamma - t\nu(x_\Gamma) \mapsto x_\Gamma + t\left[1 + t c(x_\Gamma)\right]\nu(x_\Gamma), $$

for $x_\Gamma \in \Gamma$ and $0 < t < \tau$ (small). Here $c(x_\Gamma) = \beta \text{trace}(\Pi(x_\Gamma))$ where $\Pi(x_\Gamma)$ is the second fundamental form of $\Gamma$ at $x_\Gamma$ and $-1 < \beta < 0$. By taking $\beta$ sufficiently close to $-1$, one can prove that, see [22, Proof of Corollary 3],

$$ \mathcal{F}_*( -I ) - I \geq \gamma d_\Gamma I \text{ in } D_{-\tau} $$

for some positive constant $\gamma$ (note that the definition of $\mathcal{F}_*$ in this paper is different from the one in [22] in which $|\det(\nabla \mathcal{F})|$ is used instead of $\det(\nabla \mathcal{F})$). We are now in the range of the application of Theorem 2.2 and the conclusion follows. □

Here is an immediate application of Corollary 4.2. Let $D$ be a smooth strictly convex set of class $C^3$ and assume that, for $\delta \geq 0$,

$$ (\varepsilon_\delta, \mu_\delta) = \begin{cases} I, I & \text{in } \mathbb{R}^3 \setminus D, \\ -I + i\delta I, -I + i\delta I & \text{in } D. \end{cases} $$

Let $J \in [L^2(\mathbb{R}^3)]^3$ with supp $J \subset B_{R_0} \setminus (D_\tau \cup D_{-\tau})$ and let $(E_\delta, H_\delta)$ be the unique radiating solution of (1.3). As a consequence of Theorem 2.2 and [22, Corollary 3], one has

$$ \| (E_\delta, H_\delta) \|_{L^2(B_R \setminus \Omega)} \leq C_R \| J \|_{L^2(\mathbb{R}^3)} \forall R > 0, $$

for some positive constant $C_R$ independent of $\delta$ and $J$. Corollary 4.2 is a variant of [22, Corollary 3] for the Maxwell equations.

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A. Proof of Proposition 3.1

We only consider the case $(\mu, \hat{\mu})$ does not satisfy the complementing conditions at some point $x_0 \in \partial\Omega$. The other case can be dealt similarly. Then, from [2], there exist sequences

$$(u_n, \hat{u}_n) \subset H^2(\Omega), \quad (f_n, \hat{f}_n) \subset L^2(\Omega), \quad (p_n) \subset H^\frac{3}{2}(\partial\Omega) \quad \text{and} \quad (q_n) \subset H^\frac{1}{2}(\partial\Omega)$$

such that

$$ \begin{align*}
\text{div}(\mu \nabla u_n) &= f_n, & \text{div}(\hat{\mu} \nabla \hat{u}_n) &= \hat{f}_n & \text{in } \Omega, \\
\mu \nabla u_n - \mu \nabla \hat{u}_n \cdot v &= q_n & \text{on } \partial\Omega, \\
\text{and } (\|f_n\|_{L^2(\Omega)}), (\|\hat{f}_n\|_{L^2(\Omega)}), (\|p_n\|_{H^\frac{3}{2}(\partial\Omega)}), (\|q_n\|_{H^\frac{1}{2}(\partial\Omega)}) \text{ are bounded and } \lim_{n \to +\infty} \| (u_n, \hat{u}_n) \|_{H^2(\Omega)} &= +\infty.
\end{align*} $$

Let $\phi_n \in H^2$ and $\hat{\phi}_n \in H^2$ be the unique solution of

$$ \begin{align*}
\begin{cases} 
\text{div}(\mu \nabla \phi_n) = f_n & \text{in } \Omega, \\
\phi_n = p_n & \text{on } \partial\Omega.
\end{cases} \quad \text{and} \quad \begin{cases} 
\text{div}(\hat{\mu} \nabla \hat{\phi}_n) = \hat{f}_n & \text{in } \Omega, \\
\hat{\phi}_n = 0 & \text{on } \partial\Omega.
\end{cases}
\end{align*} $$
By the standard theory of elliptic equations, one has
\[ \| \phi_n \|_{H^2} \leq C \left( \| f_n \|_{L^2} + \| p_n \|_{H^2(\partial \Omega)} \right) \quad \text{and} \quad \| \hat{\phi}_n \|_{H^2} \leq C \left( \| \hat{f}_n \|_{L^2} \right), \]
for some positive constant \( C \) independent of \( n \). Set
\[ H_n = \nabla u_n - \nabla \phi_n \quad \text{and} \quad \hat{H}_n = \nabla \hat{u}_n - \nabla \hat{\phi}_n, \]
in \( \Omega \).
We have, in \( \Omega \),
\[ \text{curl} \, H_n = 0 = \text{curl} \, \hat{H}_n \quad \text{and} \quad \text{div} \, (\mu \, H_n) = 0 = \text{div} \, (\hat{\mu} \, \hat{H}_n). \]
Since \( u_n - \hat{u}_n = p_n - \phi_n \) on \( \partial \Omega \), and \( \hat{\phi}_n = 0 \) on \( \partial \Omega \), we deduce that
\[ \nu \times (H_n - \hat{H}_n) = 0 \quad \text{on} \ \partial \Omega. \]
Set
\[ E_n = \hat{E}_n = 0 \ \text{in} \ \Omega \]
and, in \( \Omega \),
\[ J_{e,n} = -i \omega \mu H_n, \quad \hat{J}_{e,n} = -i \omega \hat{\mu} \hat{H}_n, \quad J_{m,n} = 0, \quad \text{and} \quad \hat{J}_{m,n} = 0. \]
One can easily check that \((E_n, \hat{E}_n, H_n, \hat{H}_n)\) and \((J_{e,n}, \hat{J}_{e,n}, J_{m,n}, \hat{J}_{m,n})\) satisfies all the required properties. \( \square \)

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