PREDICTION OF SATISFIED USER RATIO FOR COMPRESSED VIDEO

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ABSTRACT

A large-scale video quality dataset called the VideoSet has been constructed recently to measure human subjective experience of H.264 coded video in terms of the just-noticeable-difference (JND). It measures the first three JND points of 5-second video of resolution 1080p, 720p, 540p and 360p. Based on the VideoSet, we propose a method to predict the satisfied-user-ratio (SUR) curves using a machine learning framework. First, we partition a video clip into local spatial-temporal segments and evaluate the quality of each segment using the VMAF quality index. Then, we aggregate these local VMAF measures to derive a global one. Finally, the masking effect is incorporated and the support vector regression (SVR) is used to predict the SUR curves, from which the JND points can be derived. Experimental results are given to demonstrate the performance of the proposed SUR prediction method.

Index Terms— Video Quality Assessment, Satisfied User Ratio, Just Noticeable Difference

1. INTRODUCTION

A large amount of bandwidth of fixed and mobile networks is consumed by real-time video streaming. It is desired to lower the bandwidth requirement by taking human visual perception into account. Although the peak signal-to-noise ratio (PSNR) has been used as an objective measure in video coding standards for years, it is generally agreed that it is a poor visual quality metric that does not correlate with human visual experience well [1].

There has been a large amount of efforts in developing new visual quality indices to address this problem, including SSIM [2], FSIM [3], DLM [4], etc. Humans are asked to evaluate the quality of visual contents by a set of discrete or continuous values called opinion score; typical opinion scores in the range 1-5, with 5 being the best and 1 the worst quality. These indices offer, by definition, users’ subjective test results and thus correlate better than PSNR with their mean (called mean opinion score, or MOS). However, there is one shortcoming with these indices. That is, the difference of selected contents for ranking is sufficiently large for a great majority of subjects. Since the difference is higher than the just-noticeable-difference (JND) threshold for most people, disparities between visual content pairs are easier to tell.

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used in the H.264/AVC. Typically, clip $d_i$ has a higher PSNR value than clip $d_j$, if $i < j$, and $d_0$ is the losslessly coded copy of $r$. The first JND location is the transitional index $i$ that lies on the boundary of perceptually lossless and lossy visual experience for a subject. The first JND is a random variable rather than a fixed quantity since it varies with several factors, including the visual content under evaluation, the test subject and the test environment. Based on the study in [10], the JND position can be approximated by a Gaussian distribution in form of

$$X \sim N(\bar{x}, s^2),$$

where $\bar{x}$ and $s$ are the sample mean and sample standard deviation, respectively.

We say that a viewer is satisfied if the compressed video appears to be perceptually the same as the reference. Mathematically, the satisfied user ratio (SUR) of vide clip $d_i$ can be expressed as

$$S_i = 1 - \frac{1}{M} \sum_{m=1}^{M} I_m(d_i),$$

where $M$ is the total number of subjects and $I_m(d_i) = 1$ or 0 if the $m$th subject can or cannot see the difference between compressed clip $d_i$ and its reference, respectively. The summation term in right-hand-side of Eq. (2) is the empirical cumulative distribution function (CDF) of random variable $X$ as given in Eq. (1). Then, by plugging Eq. (1) into Eq. (2), we can obtain a compact formula for the SUR curve as

$$S_i = Q(d_i|\bar{x}, s^2),$$

where $Q(\cdot)$ is the Q-function of the normal distribution.

3. PROPOSED SUR PREDICTION SYSTEM

The SUR curve is primarily determined by two factors: 1) quality degradation due to compression and 2) the masking effect. To shed light on the impact of the masking effect, we use sequences #37 (DinnerTable) and #89 (ToddlerFountain) as examples. Their representative frames are shown in Figs. (a) and (b) and their JND data distributions are given in Figs. (2)(a) and (b), respectively. Sequence #37 is a scene captured around a dining table. It focuses on a male speaker with still dark background. His face is the visual salient region that attracts people’s attention. The masking effect is weak and, as a result, the JND point arrives earlier (i.e. a smaller $i$ value in $d_i$).

On the other hand, sequence #89 is a scene about a toddler playing in a fountain. The masking effect is strong due to water drops in background and fast object movement. As a result, compression artifacts are difficult to perceive and the JND point arrives later.

The block diagram of the proposed SUR prediction system is given in Fig. 3. When a subject evaluates a pair of video clips, different spatial-temporal segments of the two video clips are successively assessed. The segment dimensions are spatially and temporally bounded. The spatial dimension is determined by the area where the sequence is projected on the fovea. The temporal dimension is limited by the fixation duration or the smooth pursuit duration, where the noticeable difference is more likely to happen than the process of saccades [13, 14]. Thus, the proposed SUR prediction system first evaluates the quality of local Spatial-Temporal Segments. Then, similarity indices in these local segments are aggregated to give a compact global index. Then, significant segments are selected based on the slope of quality scores between neighboring coded clips. After that, we incorporate the masking effect that reflects the unique characteristics of each video clip. Finally, we use the support vector regression (SVR) to minimize the $L_2$ distance of the SUR curves, and derive the JND point accordingly. Several major modules of the system will be detailed below.

**Step 1. Spatial-Temporal Segment Creation**

The purpose of this module is to divide a video clip into multiple spatial-temporal segments and evaluate their quality at the eye fixation level. The dimension of a spatial-temporal segment is $W \times H \times T$. In case of eye pursuit, the spatial dimension should be large enough while the temporal dimension should be short enough to ensure that the moving object is still covered in one segment. In case of eye fixation, the spatial dimension should not be too large and the temporal dimension should not be too long to represent quality well at the fixation level. Based on the study in [15], we set $W = 320$, $H = 180$ and $T = 0.5s$ here. The neighboring segments overlap 50% in the spatial dimension. For example, the original dimension of 720p video is $1280 \times 720 \times 5s$, and there are $7 \times 7 \times 10 = 490$ segments created from each clip.

**Step 2. Local Quality Assessment**

We choose the Video Multimethod Assessment Fusion (VMAF) [12] as the primary quality index to assess quality degradation of compressed segments. VMAF is an open-source full-reference perceptual video quality index that aims to capture the perceptual quality of compressed video. It first estimates the quality score of a video clip with multiple high-performance image quality indices on a frame-by-frame basis. Then, these image quality scores are fused together using the support vector machine (SVM) at each
Step 3. Significant Segments Selection

VMAF is typically applied to all spatial-temporal segments. However, not all segments contribute equally to the final quality of the entire clip. To select significant segments that are more relevant to our objective, we examine the local quality degradation slope, which is defined as

$\delta V(S_{dwh}^{i}) = \frac{V(S_{r}^{i}) - V(S_{dwh}^{i})}{k}$, \hspace{1cm} (4)

where $V(S_{dwh}^{i})$ is the VMAF score of segment $S_{dwh}^{i}$ that is cropped from compressed clip $d_i$ with spatial indices $(w, h)$ and temporal index $t$, respectively. The slope in Eq. (4) evaluates how much the VMAF score of the current segment $S_{dwh}^{i}$ differs from that in its neighboring compressed clip $S_{dwh}^{i-k}$, where $k = 2$ is the QP difference between them. If the slope is small, the local quality does not change too much and the probability of the associated coding index to be a JND point is lower. We order all spatial-temporal segments based on their slopes and select $p$ percents of them with larger slope values. We set $p = 80\%$ in our experiment. The goal is to filter out less important segments before we extract a representative feature vector.

Step 4. Quality Degradation Features

A cumulative quality degradation curve is computed for every coded clip based on the change of VMAF scores in significant segments. Its computation consists of two steps. First, we compute the difference of VMAF scores between a significant segment from compressed clip $d_i$ and its reference $r$ as

$\Delta V(S_{dwh}^{i}) = V(S_{r}^{i}) - V(S_{dwh}^{i})$. \hspace{1cm} (5)

The values $\Delta V(S_{dwh}^{i})$ collected from all significant segments can be viewed as samples of a random variable denoted by $\Delta V(S_{dwh})$. Then, based on the distribution of $\Delta V(S_{dwh})$, we can compute the cumulative quality degradation curve as

$F_{dwh}(n) = Prob[\Delta V(S_{dwh}^{i}) \leq 2n]$, for $n = 1, \cdots, 20$. \hspace{1cm} (6)

which captures the cumulative histogram of VMAF score differences for coded video $d_i$. As shown in Eq. (6), the cumulative quality degradation curve is represented in form of a 20-D feature vector.

Step 5. Masking Features

As mentioned earlier, quality degradation in a spatial-temporal segment is more difficult to observe if there exists a masking effect frame. Results on various video quality databases show that VMAF outperforms other video quality indices such as PSNR, SSIM [2], Multiscale Fast-SSIM [16], and PSNR-HVS [17] in terms of the Spearman Rank Correlation Coefficient (SRCC), Pearson Correlation Coefficient (PCC), and the root-mean-square error (RMSE) criteria. VMAF achieves comparable or outperforms the state-of-the-art video index, the VQM-VFD index [15], on several publicly available databases. For more details about VMAF, we refer interested readers to [12].
in the segment. Here, we use the spatial randomness and temporal randomness proposed in [18, 19] to measure the masking effect. The process is sketched below. First, high frequency components of distortions are first removed by applying a low-pass filter, which is inspired by the Contrast Sensitivity Function (CSF), in the preprocessing step. Then, we use the spatial randomness (SR) model [18] and the temporal randomness (TR) [19] to compute the spatial and temporal regularity in a spatial-temporal segment that is generated in Step 1. The spatial randomness is small in smooth or highly structured regions. Similarly, the temporal randomness is small if there is little motion between adjacent frames. When the SR and TR values are higher, the spatial and temporal masking effects are stronger. The masking features, $M_s$, are extracted from the reference clip only. The histograms of the SR and the TR are concatenated to yield the final masking feature vector:

$$M_{sd} = [Hist_{10}(SR), Hist_{10}(TR)].$$

(7)

Step 6. Prediction of SUR Curves and JND Points

The final feature vector is the concatenation of two feature vectors. The first one is the quality degradation feature vector of dimension 20 as given in Eq. (6). The second one is the masking feature vector of dimension 20 as given in Eq. (7). Thus, the dimension of the final concatenated feature vector is 40. The SUR prediction problem is treated as a regression problem, and solved by the Support Vector Regressor (SVR) [20]. Specifically, we adopt the $\epsilon$-SVR with the radial basis function kernel.

4. EXPERIMENTAL RESULTS

In this section, we present the prediction results of the proposed SUR prediction framework. The VideoSet consists of 220 videos in 4 resolutions and three JND points per resolution per video clip. Here, we focus on the SUR prediction of the first JND and conduct this task for each video resolution independently. For each resolution, we trained and tested 220 video clips using the 5-fold validation. That is, we choose 80% (i.e. 176 video clips) as the training set and the remaining 20% (i.e., 44 video clips) as the testing set. We rotated the 20% testing set five times so that each video clip was tested once. Since the JND location is chosen to be the QP value when the SUR value is equal to 75% in the VideoSet, we adopt the same rule here so that the JND position can be easily computed from the predicted SUR curve.

The averaged prediction errors of the SUR curve and the JND position for video clips in four resolutions were summarized in Table 1. We see that prediction errors increase as the resolution becomes lower. This is probably due to the use of fixed $W$ and $H$ values in generating spatial-temporal segments as described in Sec. 3. We will finetune these parameters to obtain better prediction results in the future.

To see the prediction performance of each individual clip, we use 720p video as an example. The histogram of the SUR prediction error is given in Fig. 4(a), where the mean absolute error (MAE) is 0.038 for all test sequences. The predicted JND location versus the ground-truth JND location is plotted in Fig. 4(b), where each dot denotes one video clip. As shown in the figure, most dots are distributed along the 45-degree line, which indicates that the predicted JND is very close to the ground truth JND for most sequences.

Table 1: Summary of averaged prediction errors for video clips in four resolutions.

|          | 1080p | 720p | 540p | 360p |
|----------|-------|------|------|------|
| $\Delta\text{SUR}$ | 0.039 | 0.038 | 0.037 | 0.042 |
| $\Delta\text{QP}$  | 1.218 | 1.273 | 1.345 | 1.605 |

5. CONCLUSION AND FUTURE WORK

A Satisfied User Ratio (SUR) prediction framework for H.264/AVC coded video was proposed in this work. It took both the local quality degradation as well as the masking effect into consideration and extract a compact feature vector and fed it into the support vector regressor to obtain the predicted SUR curve. The first JND point can be derived accordingly. The system achieves good performance in all resolutions. We will adopt the same framework to predict locations of the second and the third JND points in the near future.

Fig. 4: JND prediction result: (a) the histogram of $\Delta$ SUR and (b) the predicted VS. the ground truth JND location.
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