General-Relativistic Dynamics of an Extreme Mass-Ratio Binary with an External Body

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We study the dynamics of a hierarchical three-body system in the general-relativistic regime: an extreme mass-ratio inner binary under the tidal influence of an external body. The inner binary consists of a central Schwarzschild black hole and a test body moving around it. We discuss three types of tidal effects on the orbit of the test body. First, the angular momentum of the inner binary precesses around the angular momentum of the outer binary. Second, the tidal field drives a “transient resonance” when the radial and azimuthal frequencies are commensurable. In contrast with resonances driven by the gravitational self-force, this tidal-driven resonance may boost the orbital angular momentum and eccentricity (a relativistic version of the Kozai-Lidov effect). Finally, as an orbit-dynamical effect during the non-resonant phase, we calculate the correction to the Innermost Stable Circular (mean) Orbit due to the tidal interaction. Hierarchical three-body systems are potential sources for future space-based gravitational wave missions and the tidal effects that we find could contribute significantly to their waveform.

I. INTRODUCTION

The first direct detection of gravitational waves (GWs) [1] by ground-based detectors opens up a window to probe our universe, search for new physics and test the theory of General Relativity with unprecedented means. At the $mHz$ to $Hz$ frequency band, future space-based detectors such as the Laser Interferometer Space Antenna (LISA, see [2, 3]) will be able to observe signals from extreme mass-ratio inspirals (EMRIs) of massive black holes and stars/stellar-mass black holes, white dwarf binary mergers, etc. In particular, monitoring the orbital evolution of EMRIs offers a unique opportunity to probe the time-scale of a rotating black hole (Kerr), as well as to improve our understanding of the dynamics of stars in galactic centres [4].

Because of the separation in mass-scales in EMRI systems, their dynamics can be modelled by black hole perturbation theory. Within this framework, the small expansion parameter is the ratio $\mu$ of the smaller mass to the larger mass, and the least massive object is approximated by a point mass. The two-body dynamics can thus be simplified to an effective one-body scenario, where a point mass moves on a geodesic of an “EMRI space-time” whose metric is the sum of the background metric due to the larger black hole and the (appropriately regularized) linear [48] gravitational perturbation generated by the smaller object. That is, the smaller object undergoes geodesic motion on this “background+perturbation” [5, 6]. In general, such trajectory is no longer geodesic on the background space-time, and the deviation is due to the metric perturbation induced by the smaller object itself, which give rise to a gravitational self-force [7]. Motivated by future space-based GW missions, understanding EMRI dynamics via the gravitational self-force has been one of the major efforts in gravitational physics in the past couple of decades.

If an EMRI system is not isolated, but is instead influenced by another massive astrophysical object, e.g., a supermassive black hole, the orbital dynamics and GW radiation are likely modified by the gravitational interaction between the inner binary and the third object. For instance, Yunes et al. [8] studied the acceleration of the EMRI system due to the gravitational attraction of the third body and they estimated the resulting phase variations in the gravitational waveform. On the other hand, even in the rest frame of the inner binary, the tidal field induced by the third body changes further the EMRI space-time. Such modification was first computed by Poisson [9], for the case of a non-rotating (Schwarzschild) central black hole and later on by Yunes and González [10] for the case of a Kerr black hole.

Understanding the dynamical influence of a tidal field on an EMRI orbit and waveform is the central goal of our work. As a first step along this path, we consider an extreme mass-ratio (inner) binary within an external tidal field under the following assumptions. We assume that the tidal field is created by a source which is slowly-moving around the inner binary (thus constituting an outer binary) and includes only the leading quadrupole moment (since the source is far from the inner binary). As for the inner binary, we assume that the central black hole is a Schwarzschild black hole and we ignore self-force effects (despite that we shall still refer to it as an EMRI).

Even with a Schwarzschild central black hole and ignoring self-force effects, we discover interesting and new effects due to the tidal field. Specifically, we investigate
the following tidal-field effects on the orbit of the smaller particle. First, we show that the tidal field causes the angular momentum of the inner binary to precess around the angular momentum of the outer binary. This precession is caused by the interaction between quadrupole moment of the inner orbit and the tidal field. Second, we show that the tidal field leads to transient resonances: when the ratio of the (evolving) radial and angular orbital frequencies is a rational number, corrections larger than unity in the orbital phase may occur and the magnitude of the angular momentum may be boosted. Equivalent resonances have been observed within EMRI systems in the absence of a tidal field when including the dissipative piece of the self-force [11]. However, in contrast with our case, these self-force-driven resonances cannot increase the magnitude of the angular momentum (and can only occur when the central black hole is a Kerr black hole). Third and last, we calculate the shift, due to the tidal field, in the frequency, radius, energy and angular momentum of the Innermost Stable Circular Orbit (ISCO), which, for our system, we define in some orbital-average sense. Equivalent shifts have been found to be caused by the conservative piece of the self-force on particles moving around a Schwarzschild [12] or a Kerr [13] black hole. In our case, the frequency shift can be either positive or negative, as opposed to the self-force case which has been found to be positive.

The precession of angular momentum precession may lead to detectable GW phase variations within the precession timescales. The resonance effect could have significant observational imprints on the gravitational waves as we shall demonstrate later, which we expect to be true for generic Kerr-EMRI. The ISCO shift affects the peak frequency of the gravitational waveform, but we expect it to be small for the hierarchical triple systems considered here.

It is worth mentioning that in planetary systems, similar three-body dynamics have been extensively studied and many interesting behaviours have been discovered in the Newtonian and Post-Newtonian regimes For example, the well-known Kozai-Lidov (KL) mechanism [14,15] suggests that the inner binary could trade eccentricity for inclination angle under the influence of the quadrupole tidal field of the third body. In recent years, the KL mechanism has been further extended to include eccentric orbits [16], the octupole tidal field [14,18] and Post-Newtonian corrections [19,20]. As the inner binary transfers from the Newtonian regime to the relativistic regime, the degeneracy between radial and angular orbital frequencies breaks down, which in principle allows for a much richer phenomenology, as indicated by previous Post-Newtonian studies [20]. To the best of our knowledge, the present work is the first study of the dynamics of such three-body systems in the fully relativistic regime.

A. An order-of-magnitude analysis

Before moving into a detailed analysis in later sections, we first present an order-of-magnitude estimate of the relative strength between the tidal field and the smaller object’s self-force. Such analysis may serve as an indication of the orbital modification generated by the tidal field during the gravitational radiation-reaction timescale. Throughout the paper we use units with $c = G = 1$.

Let us denote the inner binary orbit separation by $r_0$ and its two masses by $M$ and $\mu M$, with $\mu \ll 1$. The third body is at a distance $d$ and it has a mass $M_\ast$. The system is illustrated in Fig.1.

![FIG. 1: Illustration of our three-body system: an inner binary composed of the larger black hole of mass $M$ and the smaller compact object of mass $\mu M$, and a third body of mass $M_\ast$. This third body is distant from the inner binary and is, generally, orbiting around it. The angular momentum of the orbit of the smaller object is $\vec{L}$, which is perpendicular to the orbital plane of the inner binary and, in general, is neither parallel nor perpendicular to the direction between $M$ and $M_\ast$, indicated by the unit vector $\hat{n}$. We show in Sec. III A that $\vec{L}$ precesses around $\hat{n}$ assuming the tidal field is static within the period of inner binary: left plot. In realistic situations, however, we also need to apply the orbital average over the third body. After that averaging we find that $\vec{L}$ precesses around a vector $\vec{z}'$, which is parallel to the angular momentum of the outer binary: right plot.](image)

The dynamics of the inner binary is influenced by: (i) the background spacetime of its MBH of mass $M$; (ii) the gravitational field of its smaller body of mass $\mu M$ ($\mu \ll 1$; typically for EMRIs: $\mu \sim 10^{-4} - 10^{-8}$), causing a gravitational self-force [5,7,21,22]; (iii) the tidal force generated by the third body, another MBH of mass $M_\ast$.

The dissipative part of the self-force is the driver of the secular change of the conserved quantities of the orbit of the EMRI system to $O(\mu)$. The self-acceleration is $a_s \sim \mu v^9 / M \sim (M/r_0)^{9/2} \mu / M$, where $r_0$ and $v$ are,
respectively, the characteristic EMRI orbital separation and speed. The tidal acceleration is $a_{\text{side}} \sim M_* r_0 / d^3$, where $d$ is the distance between $M$ and $M_*$. As we show later, the orbital phase-shift generated by the tidal field during a transient resonance is $\sim 1/\sqrt{\text{SNR}}$, whereas LISA’s phase resolution of a given event is $\sim 1/\sqrt{\text{SNR}}$ (SNR: signal-to-noise ratio). Therefore, a tidal event is detectable if

$$d \leq 0.1 \text{ pc} \times \left( \frac{\mu}{10^{-6}} \right)^{-1/2} \left( \frac{M_*}{M} \right)^{1/3} \left( \frac{\text{SNR}}{40} \right)^{1/3} \left( \frac{r_0}{15 M} \right)^{11/6} \frac{M}{M_{\text{Schw}}},$$

with $M_{\text{Schw}} \sim 4 \times 10^6 M_\odot$. We expect the tidal effect is easier to detect around the less massive MBH ($M < M_*$), because its EMRI frequency is closer to the LISA band. Such orbits are also possibly eccentric due to the KL effect, in which case $r_0$ should be viewed as average radius and the peak frequency should be given by the periastron distance. According to [23], the detection rate of EMRIs by LISA ranges from a few tens to a few thousands per year, if the detection threshold of SNR is considered to be $\sim 10$ [24]. The time taken by the MBH binary to migrate to a distance of $\sim 10^{8}$ pc is about several hundreds of million years (a few percent of the Gyr). While in the first viewpoint, the smaller object is moving on an orbit of the background-space-time $g_{\mu\nu}$ and is undergoing an acceleration due to $h_{\mu\nu}$. The 4-acceleration $a^\mu \equiv \partial u^\mu / \partial \tau \equiv u^\nu \nabla_\nu u^\mu$ is given by [2]

$$a^\mu = \frac{1}{2} (g^\mu{}_{\nu} + u^\mu u^\nu)(2h_{\nu\lambda\rho} - h_{\nu\mu\rho})u^\lambda u^\rho, \tag{2}$$

where $u^\mu = dx^\mu / d\tau$ is the 4-velocity of the particle, $x^\mu(\tau)$ is the particle’s location (in a given system of coordinates $x^\mu$) and $\tau$ is the particle’s proper time. In principle, the 4-velocity in Eq.(2) should correspond to the accelerated orbit in $g_{\mu\nu}$. In practise, however, the 4-velocity in this accelerated orbit may be replaced with the 4-velocity of the geodesic (called the osculating geodesic) in $g_{\mu\nu}$ which is instantaneously tangential to the accelerated orbit [25]. The reason is that the radiation-reaction timescale is much larger than the orbital timescale and the osculating geodesic agrees with the true accelerated orbit to zeroth order for small $h$ (corresponding to small $M_*$ in the case of the tidal force and to small $\mu$ in the case of the self-force). Therefore, using one velocity or the other in Eq.(2) only changes the force at higher-than-linear order in $h$. When implementing Eq.(2) in this paper we shall use this osculating geodesic approximation. We shall use the symbol $C$ to denote any quantity which is conserved along geodesic motion in the space-time $g_{\mu\nu}$. Note that any such quantity is not necessarily conserved anymore when including the acceleration due to $h_{\mu\nu}$.

In the second viewpoint, the particle is considered to be following a geodesic of the full perturbed black hole space-time with metric $g_{\mu\nu} \equiv g_{\mu\nu} + h_{\mu\nu}$. Within the Hamiltonian formalism (see, e.g., [23][24] in the context of the conservative self-force), a particle’s geodesic motion in this space-time can be determined by invoking the Hamiltonian equations of motion. These equations are

$$\frac{d\tilde{p}^\mu}{d\tilde{\tau}} = \frac{\partial H}{\partial \tilde{p}_\nu}, \quad \frac{d\tilde{p}_\nu}{d\tilde{\tau}} = -\frac{\partial H}{\partial \tilde{q}^\nu}, \tag{3}$$

where $\tilde{p}_\nu$ is the 4-momentum associated to the canonical position $x^\mu(\tilde{\tau})$ and $\tilde{\tau}$ is the particle’s proper time.

II. FORMALISM

Our physical setting is that of an EMRI system, composed of a small compact object and a massive black hole, within the influence of an external tidal field. The small compact object is modelled as a point test (i.e., the self-force is neglected) particle and it is moving around a massive black hole, which we shall take to be a Schwarzschild black hole. The tidal field is created by a third, remote and slowly-moving (in this paper we take the static limit over the period of inner binary) body; the tidal field is considered to be a perturbation $h_{\mu\nu}$ of the metric $g_{\mu\nu}$ of the massive black hole. Specifically, in our setting, $g_{\mu\nu}$ is given by the Schwarzschild metric Eq.(5) below and the tidal perturbation $h_{\mu\nu}$ will be given later in Eq.(11) combined with Eq.(13).

We may adopt two different but equivalent viewpoints to approach this problem. We note that these viewpoints apply similarly to the different setting of an EMRI system including the self-force but no external tidal field, in which case $h_{\mu\nu}$ would correspond to the regularized gravitational self-field ($g_{\mu\nu}$ would continue to be the metric of the massive black hole).

In the first viewpoint, the smaller object is moving on an orbit of the background-space-time $g_{\mu\nu}$ and is undergoing an acceleration due to $h_{\mu\nu}$. The 4-acceleration $a^\mu \equiv \partial u^\mu / \partial \tau \equiv u^\nu \nabla_\nu u^\mu$ is given by [2]

$$a^\mu = \frac{1}{2} (g^\mu{}_{\nu} + u^\mu u^\nu)(2h_{\nu\lambda\rho} - h_{\nu\mu\rho})u^\lambda u^\rho, \tag{2}$$

where $u^\mu = dx^\mu / d\tau$ is the 4-velocity of the particle, $x^\mu(\tau)$ is the particle’s location (in a given system of coordinates $x^\mu$) and $\tau$ is the particle’s proper time. In principle, the 4-velocity in Eq.(2) should correspond to the accelerated orbit in $g_{\mu\nu}$. In practise, however, the 4-velocity in this accelerated orbit may be replaced with the 4-velocity of the geodesic (called the osculating geodesic) in $g_{\mu\nu}$ which is instantaneously tangential to the accelerated orbit [25]. The reason is that the radiation-reaction timescale is much larger than the orbital timescale and the osculating geodesic agrees with the true accelerated orbit to zeroth order for small $h$ (corresponding to small $M_*$ in the case of the tidal force and to small $\mu$ in the case of the self-force). Therefore, using one velocity or the other in Eq.(2) only changes the force at higher-than-linear order in $h$. When implementing Eq.(2) in this paper we shall use this osculating geodesic approximation. We shall use the symbol $C$ to denote any quantity which is conserved along geodesic motion in the space-time $g_{\mu\nu}$. Note that any such quantity is not necessarily conserved anymore when including the acceleration due to $h_{\mu\nu}$.

In the second viewpoint, the particle is considered to be following a geodesic of the full perturbed black hole space-time with metric $g_{\mu\nu} \equiv g_{\mu\nu} + h_{\mu\nu}$. Within the Hamiltonian formalism (see, e.g., [23][24] in the context of the conservative self-force), a particle’s geodesic motion in this space-time can be determined by invoking the Hamiltonian equations of motion. These equations are

$$\frac{d\tilde{p}^\mu}{d\tilde{\tau}} = \frac{\partial H}{\partial \tilde{p}_\nu}, \quad \frac{d\tilde{p}_\nu}{d\tilde{\tau}} = -\frac{\partial H}{\partial \tilde{q}^\nu}, \tag{3}$$

where $\tilde{p}_\nu$ is the 4-momentum associated to the canonical position $x^\mu(\tilde{\tau})$ and $\tilde{\tau}$ is the particle’s proper time.
along the geodesic in $\tilde{g}$. The Hamiltonian is given by
\[ H = \frac{1}{2} \dot{\nu}^\mu \dot{\nu}^\nu g_{\mu \nu} = \frac{1}{2} \dot{\nu}^\mu (g_{\mu \nu} + h_{\mu \nu}). \] (4)

We shall use the symbol $\tilde{C}$ to denote any quantity which is conserved along geodesic motion in the perturbed space-time $\tilde{g}$.

We shall essentially adopt the first viewpoint in the calculations from Sec. II C until Sec. IV where, for convenience, we shall adopt the second viewpoint. The rest of this section is organized as follows. In Sec. IIA we describe geodesic motion on a Schwarzschild black hole background $g_{\mu \nu}$. In Sec. IIB we give expressions for a tidal perturbation $h_{\mu \nu}$. Finally, in Sec. IIC, we give expressions for rates of change of quantities $C$ which are conserved along geodesics in $g_{\mu \nu}$.

A. Geodesic motion on the black hole space-time

Here we consider geodesic motion on the black hole background space-time, i.e., with $h_{\mu \nu} = 0$ in Eq. (4).

In the case that the massive black hole is a Kerr black hole, particles following geodesic motion have three conserved quantities: the energy, $E = -u_t$, the component of the angular momentum along the spin ($z$)-axis, $L_z = u_\phi$, and the Carter constant $Q$ [31]. Thanks to the three conserved quantities, the radial and angular geodesic motions are separable.

From now on, however, we restrict ourselves to the case that the massive black hole is a Schwarzschild black hole. The Schwarzschild line-element in Schwarzschild coordinates $x^\mu = \{t, r, \theta, \phi\}$ is
\[ ds^2 = g_{\mu \nu} dx^\mu dx^\nu = -f dt^2 + \frac{dr^2}{f} + r^2 d\Omega^2, \] (5)
where $f \equiv 1 - 2M/r$ and $d\Omega^2 = d\theta^2 + \sin^2 \theta d\phi^2$ is the line-element of the 2-sphere. The same metric may be written in Ingoing-Eddington-Finkelstein coordinates as
\[ ds^2 = -f dv^2 + 2dvdr + r^2 d\Omega^2, \] (6)
where $v \equiv t + r_*$ and $r_* \equiv r + 2M \log (1 - r/(2M))$ is the tortoise radial coordinate.

Unlike in Kerr, in the Schwarzschild case the vector angular momentum $L$ is conserved, and the particle’s motion is planar. Because of the additional constraint of planar motion, there are only two effective degrees of freedom left. One of them is radial:
\[ \frac{dr}{d\lambda}^2 = V(r) \]
\[ \equiv r^4 \left( E^2 - \left( 1 - \frac{2M}{r} \right) \left( 1 + \frac{L_z^2 + Q}{r^2} \right) \right), \] (7)
where we use “Mino time” $\lambda$, defined via $d\lambda \equiv dr/r^2$, to parameterize the trajectory, following the discussion in

We note that, in Schwarzschild, the Carter constant is given by $Q = u_\theta^2 + \cot^2 \theta L_{\phi}^2$ and the square modulus of the total angular momentum $L = (L_x, L_y, L_z)$ is given by $L^2 = ||L||^2 = L_z^2 + Q$, for a given choice of Cartesian coordinates $x$, $y$ and $z$.

The motion along the $\phi$-direction is given by
\[ \frac{d\phi}{d\lambda} = \frac{L_z}{\sin^2 \theta}. \] (8)

The motion along the $\theta$-direction (for inclined orbits) can be obtained using a direct mapping from $\phi$ or, alternatively, from
\[ \left( \frac{d\theta}{d\lambda} \right)^2 = \frac{L_z^2}{\sin^4 \theta} \left( \frac{d\phi}{d\lambda} \right)^2 = Q - L_z^2 \cot^2 \theta \equiv V_\theta(\theta). \] (9)

The particle moves in the region $\theta \in [\theta_m, \pi - \theta_m]$, with $\theta_m \equiv \arctan(L_z/\sqrt{Q})$ being the angle between $L$ and the projection of $L$ onto the plane perpendicular to the $z$-axis.

B. External tidal field

Poisson and collaborators [9, 33, 34] have obtained the metrics of black holes deformed by tidal forces which are created by a remote distribution of matter. They obtain these metrics by solving the perturbative Einstein equation and matching the solution to an external (asymptotic) tidal metric. In our case, we shall only take into account the leading – quadrupole – tidal moment of the field generated by the remote – third – body. This quadrupole moment can be characterized by electric-type tensors $E_{AB}, E_A$ and $E$, and magnetic-type tensors $B_{AB}, B_A$, where $A$ and $B$ are indices over the angular degrees of freedom $\theta$ and $\phi$. These tensors can be obtained by decomposing the tidal field using tensor, vector and scalar spherical harmonics – their explicit definitions are given in [9, 33, 34]. As the outer object is only moving slowly, in this paper we shall neglect its motion over the orbital timescale of the inner binary. Hence, we shall take the magnetic-type tensor, as well as any derivatives of the electric-type tensor, to be zero in our analysis. Under these approximations of quadrupole moment and static source, the metric perturbation of a Schwarzschild black hole immersed in an external tidal field is:
\[ h_{\nu \nu} = -r^2 f^2 E, \quad h_{\nu \lambda} = 0, \]
\[ h_{\nu A} = -\frac{2}{3} r^3 f E_A, \]
\[ h_{AB} = -\frac{1}{3} r^4 \left( 1 - \frac{2M^2}{r^2} \right) E_{AB}. \] (10)

For our purposes, it is more convenient to work with the metric perturbation in Schwarzschild coordinates, which
\[ h_{tt} = -r^2 f^2 \mathcal{E}, \quad h_{rr} = -r^2 \mathcal{E}, \quad h_{t r} = -r^2 f \mathcal{E}, \]
\[ h_{tA} = -\frac{2}{3} r^3 f \mathcal{E}_A, \quad h_{rA} = -\frac{2}{3} r^3 \mathcal{E}_A, \]
\[ h_{AB} = -\frac{1}{3} r^4 \left(1 - \frac{2M^2}{r^2}\right) \mathcal{E}_{AB}. \]  

(11)

The expressions in \[9, 33, 34\] for the electric-type (and magnetic-type) tensors are, in the static limit (within the dynamical timescale of the inner binary), in terms of an external gravitational potential \(U_{\text{ext}}\), which can be expanded in multipoles. The dipole piece contributes to the acceleration of the center-of-mass of the inner binary, as studied in \[8\]. Keeping only the quadrupole order terms, it is, trivially,

\[ U_{\text{ext}} = \frac{M_s (x^2 + y^2 - 2z^2)}{2d^3} = \frac{M_s r^2 (1 - 3 \cos^2 \theta)}{2d^3}. \]  

(12)

Here, \(z\) is along the direction between the black hole of mass \(M\) and the third body of mass \(M_s\), and its origin is at the location of \(M\); \(\theta\) is the polar angle with respect to the \(z\)-axis. From the expressions in \[9, 33, 34\] for the electric-type tensors, it then follows that

\[ \mathcal{E}_{\theta \theta} = \frac{3M_s \sin^2 \theta}{d^3}, \quad \mathcal{E}_{\phi \phi} = \frac{3M_s \sin^2 \theta}{d^3}, \]
\[ \mathcal{E}_{\theta} = \frac{3M_s \sin \theta \cos \theta}{d^3}, \quad \mathcal{E} = \frac{M_s (1 - 3 \cos^2 \theta)}{d^3}, \]
\[ \mathcal{E}_{\theta \phi} = \mathcal{E}_{\phi \theta} = \mathcal{E}_{\phi} = 0. \]  

(13)

C. Changes in “conserved quantities”

Let us now combine a background \(g_{\mu \nu}\) and a perturbation \(h_{\mu \nu}\), within the first viewpoint described at the start of this section. That is, we consider a particle in accelerated motion due to \(h_{\mu \nu}\) on a background \(g_{\mu \nu}\). Then, the rate of change of a quantity \(\mathcal{C}\), which is conserved along a geodesic in \(g_{\mu \nu}\), may be obtained via

\[ \frac{d\mathcal{C}}{d\tau} = \frac{\partial \mathcal{C}}{\partial \rho^\nu} \frac{d\rho^\nu}{d\tau} + \frac{\partial \mathcal{C}}{\partial x^\nu} u^\nu = \frac{\partial \mathcal{C}}{\partial \rho^\nu} \omega^\nu. \]  

(14)

For example, let us find expressions for the rates of change of the energy, the angular momentum along the \(z\)-direction and the Carter constant in the Schwarzschild background. These quantities in the case now of an accelerated orbit are still defined as in the case of a geodesic orbit in Sec. 14 A, i.e., \(E \equiv -\dot{p}_t\), \(L_z \equiv \dot{u}_\phi\) and \(Q = u^2_\phi + \cot^2 \theta L^2_z\), respectively. Here, the \(u_\mu\) correspond to the accelerated orbit but they are approximated by the values on the osculating geodesic. Eq. (14) then yields

\[ \frac{dE}{d\tau} = \left(1 - \frac{2M}{r}\right) \dot{a}, \]
\[ \frac{dL_z}{d\tau} = r^2 \sin^2 \theta \dot{a}, \]
\[ \frac{dQ}{d\tau} = 2 \cot \theta L_z \frac{dL_z}{d\tau} + 2p_\theta r^2 \dot{a}. \]  

(15)

The presence of a tidal field breaks the spherical symmetry of the background. Therefore, the tidal force is generically \(\phi\)- or \(\theta\)-dependent as well as \(\tau\)-dependent. As a consequence, its secular effect implies averaging over one of these angular degrees of freedom as well as over the radial degree of freedom \(r\). That is, the Mino-time-averaged Mino-time-derivative of a quantity \(\mathcal{C}\), which is conserved along the osculating geodesic in \(g_{\mu \nu}\), is given by

\[ \left\langle \frac{d\mathcal{C}}{d\lambda} \right\rangle = \frac{1}{\Lambda_r \Lambda_\theta} \int_0^{\Lambda_r} d\lambda_r \int_0^{\Lambda_\theta} d\lambda_\theta \frac{d\mathcal{C}}{d\tau} r^2, \]

(16)

or, equivalently, by

\[ \left\langle \frac{d\mathcal{C}}{d\lambda} \right\rangle = \frac{L}{2\pi \Lambda_r \Lambda_\theta} \int_0^{\Lambda_r} d\lambda_r \int_0^{2\pi} d\phi \sin \theta \frac{d\mathcal{C}}{d\tau} r^2. \]  

(17)

Here it is understood that in the integrands we write \(r \equiv r(\lambda_r)\) and, in Eq. (16), \(\theta = \theta(\lambda_\theta)\) as functions of Mino time, as well as \(\theta = \theta(\phi)\) in Eq. (17). The “Mino time” periods in the \(\theta\)- and \(r\)-directions are, respectively, \(\Lambda_\theta = 2\pi/L\) and

\[ \Lambda_r = 2 \int_{r_{\min}}^{r_{\max}} \frac{dr}{\sqrt{v_r(r)}}, \]  

(18)

where \(r_{\min/\max}\) is the minimum/maximum radius of the orbit. We note that \(\lambda_\theta : 0 \rightarrow \Lambda_\theta\) corresponds to \(\phi : 0 \rightarrow 2\pi\).

III. SECULAR EFFECTS

The tidal-induced metric perturbation is stationary in time, which implies conservation of energy (of the orbit on \(g_{\mu \nu}\) when including tidal acceleration or, equivalently, of the geodesic on \(\tilde{g}\)), i.e., the rate of change of the total energy \(E \equiv -\dot{p}_t\) is zero – instantaneously and so also secularly. The rotational-symmetry along the line connecting the central black hole and the third body also implies conservation of angular momentum along that direction, \(z\), i.e., \(L_z \equiv \dot{u}_\phi\) is conserved. We note that the relative difference between \(\mathcal{C}\) and \(\tilde{\mathcal{C}}\) of order \(O(h)\), which is expected to be small at all times. Therefore, we do not try to highlight their difference when studying secular evolution of the orbit unless it is necessary.

Now, consider a geodesic orbit in \(\tilde{g}_{\mu \nu}\). By using the time-reversal symmetry of \(g_{\mu \nu}\), one can argue that the
secular rate of change of the magnitude of the total angular momentum $\mathbf{L}$ of this orbit must be zero. The argument goes as follows. First, we notice that $\mathbf{L}^2$ is a scalar that is invariant under the time-reversal operation. Secondly, because $g_{\mu\nu}$ and $h_{\mu\nu}$ are independent of time, a time-reversed trajectory still satisfies the correct equation of motion. Based on the above reasoning, if $\mathbf{L}^2$ evolves from $\mathbf{L}^2_{\text{init}}$ to $\mathbf{L}^2_{\text{final}}$ after some period of time that is longer than the orbital timescale, a time-reversed orbit would evolve $\mathbf{L}^2$ from $\mathbf{L}^2_{\text{final}}$ to $\mathbf{L}^2_{\text{init}}$. Lastly, it is straightforward to see that an orbit is mapped to its time-reversed orbit under the reflection operation through a certain symmetry plane. The symmetry plane is that formed by the location of $M$, the location of $M_*$ and the point on the orbit where

\[
\frac{dr}{d\tau} = 0 \quad \text{and} \quad \frac{d\theta}{d\tau} = 0. \tag{19}
\]

We argue that an orbit and its reflected one are identical in the sense that the points mapped to each other under reflection should carry the same $\mathbf{L}^2$, and consequently, $\mathbf{L}^2_{\text{init}}$ must be the same as $\mathbf{L}^2_{\text{final}}$. The joint secular conservation of $\mathbf{L}^2 = ||\mathbf{L}||^2$ and $\mathbf{L}_z$ then means that the opening angle, $\arccos(\mathbf{L}_z/\mathbf{L})$, between the orbital angular momentum and the symmetry axis of the tidal field must be invariant as well. As a result, the orbital angular momentum $\mathbf{L}$ can only precess along the tidal symmetry axis (this is after orbit-averaging, not instantaneously), with a rate that we compute in Sec. IIIA.

Let us now consider another secular effect due to the tidal field. For that purpose, we turn to the viewpoint where the orbit is accelerated in $g_{\mu\nu}$. We denote by $\Omega_r \equiv 2\pi/\Lambda_r$, $\Omega_\theta \equiv 2\pi/\Lambda_\theta$ and $\Omega_\phi$ the orbital frequencies (with respect to Mino time) associated to, respectively, the $r$-, $\theta$- and $\phi$-motions of a geodesic in $g_{\mu\nu}$. A “transient resonance” is a point on the accelerated orbit such that the radial and angular frequencies of the oscillating geodesic at that point are commensurate with each other: $\Omega_r \cdot \Omega_\phi = p \cdot q$ (there are only two independent frequencies in Schwarzschild, since the $\theta$- and the $\phi$-dynamics are degenerate and the motion is planar, so we could have equivalently used $\Omega_\theta$ instead of $\Omega_\phi$ in the condition), where $p$ and $q$ are prime numbers. In this case, the orbit becomes closed and the double integration in Eq. (16) or Eq. (17) reduces to an integral over the closed trajectory. The orbital-averaged rate of change of the magnitude of the angular momentum no longer vanish. We evaluate them and discuss their impact on the orbital plane in Sec. IIIB.

A. Orbital Precession

Intuitively speaking, after averaging over the radial and angular (either azimuthal or polar) degrees of freedom, the particle trajectory occupies a finite-width ring ($r$ between $r_{\text{min}}$ and $r_{\text{max}}$) in the orbital plane of the inner binary. We note that when we refer to any quantity (such as $U_{\text{ext}}$, $\mathbf{L}$, $\Omega_{\text{prec}}$, etc) within this subsection, we shall in fact be refering to such orbital-average version of the quantity, even if we do not say so explicitly. The mentioned ring has minimum tidal potential energy $U_{\text{ext}}$, given in Eq.(12), if the orbital angular momentum $\mathbf{L}$ is orthogonal to the tidal symmetry axis, and maximum energy if they are parallel. Therefore, a torque is exerted on the particle orbit, trying to tilt it to the minimum energy state. Such a torque generates precession of the orbital plane, in a similar way to the case of a top precessing under Earth’s gravitational field.

In this subsection we adopt the viewpoint of an accelerated orbit in $g_{\mu\nu}$. In order to evaluate the precession of the orbital plane due to the tidal interaction, we need to compute the secular rate of change of different components of the angular momentum. With of the choice of the $z$-axis lying along the direction of the central black hole and the third body, $L_z$ must be conserved due to the symmetry argument above. The precession frequency (with respect to $t$) can be computed from the rate of
change of $L_x$ and $L_y$ as:

$$\Omega_{\text{prec}} = \frac{1}{\Gamma \Lambda \Lambda^\prime} \int_0^{\Lambda_0} \int_0^{\Lambda_0} \left( \frac{L_x dL_y - L_y dL_x}{d\tau} \right) r^2 \frac{d\tau}{Q},$$

(20)

where $\Gamma$ is the average lapse rate of $t$ with respect to $\phi$.

We evaluate the quantities in Eqs. (20) and (21) for the osculating geodesic and so, in particular, $E$, $L_z$ and $Q$ are constant. In order to evaluate the rate of change of $L_x$ and $L_y$, we notice that

$$L_x = -(\sin \phi p_\theta + \cot \theta \cos \phi L_z).$$

(22)

As a result, its rate of change is related to the acceleration by (as $L_z$ is conserved)

$$\frac{1}{\mu M} \frac{dL_x}{d\tau} = -a^3 r^2 \sin \phi.$$

(23)

The rate of change of $L_y$ can be obtained similarly. Separately, one can compute the orbit-averaged interaction energy (based on the 2-D average of $u_i$) between the "mass ring" and the tidal field, which contains a term $E_{\text{int}} \propto 1 - 3(\hat{n} \cdot \tilde{L})^2 = 1 - 3 \sin^2 \theta_m (\text{with a proportionality factor independent of } \theta_m)$, where $\theta_m$ is defined via the last equality as the angle between the tidal symmetry axis $\hat{n}$ (here, parallel to $z$) and the orbital plane. Consequently, the modulus of the torque is equal to $dE_{\text{int}}/d\theta_m \propto \sin \theta_m \cos \theta_m$. Because the component of the angular momentum orthogonal to $z$ is proportional to $\cos \theta_m$, it must be

$$\Omega_{\text{prec}} = w(r_{\text{min}}, r_{\text{max}}) \frac{M_{\ast} M_{\ast}}{d^3} \sin \theta_m,$$

(24)

for a dimensionless function $w = w(r_{\text{min}}, r_{\text{max}}); the proportionality factor $M_{\ast} M_{\ast}/d^3$ measures the strength of the tidal-induced acceleration (see Eqs. (22) and (23)).

In Fig. 2, we present a calculation of $\Omega_{\text{prec}}$, with a normalization constant $d^3/(M_{\ast})$ to make it dimensionless and to remove the dependence on the strength of the tidal field. We have calculated $\Omega_{\text{prec}}$ in the following way. We have used Eq. (20), with $L_y$ and their derivatives calculated via Eqs. (22) and (23), $h_{\mu\nu}$ from Eq. (11), and calculated $u^\mu$ by numerically integrating the geodesic equations in Schwarzschild. The (osculating) geodesic in the top panel corresponds to $r_{\text{min}} = 12 M$, $r_{\text{max}} = 15 M$ and varying values of $Q$ (equivalently, $L_z$ or $\theta_n$). This top panel confirms the dependence on $\sin \theta_m$ given in Eq. (24), and the bottom panel gives the numerical value of $w(r_{\text{min}}, r_{\text{max}})$. Apart from trajectories very close to the MBH, an approximate fit to Fig. 2 is $\Omega_{\text{prec}} \sim 1.3 M_\ast M^{-1/2} r_0^{3/2} / d^3 \sin \theta_m$, with $r_0 = (r_{\text{max}} + r_{\text{min}})/2$.

The above calculation shows that, in principle, the angular momentum $\tilde{L}$ of the inner body would in principle precess around the direction $\hat{n}$ between the massive black hole $M$ and the third body $M_\ast$. Now, assuming $M \sim M_\ast$, an order-of-magnitude estimate for the period of the outer binary gives $T_\text{o} = 2\pi/\Omega_{\text{prec}} \sim (d^3/M_{\ast})^{1/2}$, which is generically much longer than the precession period: $2\pi/\Omega_{\text{prec}} \sim d^3/(M M_{\ast})$. Therefore, we also need to perform an average over the orbit of the third body. This can be done by writing down the equation for the precession of the angular momentum after averaging over the orbit of the inner binary, but allowing the direction of the third body ($\hat{n}$) to be time-dependent. From Eq. (24) (for simplicity, here we do not distinguish between $\tilde{L}$ and $\tilde{L}$),

$$\frac{dL_i}{dt} = w(r_{\text{min}}, r_{\text{max}}) \frac{M_{\ast} M_{\ast}}{d^3} \langle \hat{n} \cdot \tilde{L} \rangle \hat{n} \times \tilde{L}.$$

(25)

Let us assume that the motion of the third body is on some arbitrary $x' \cdot y'$ plane, so that we can write $\hat{n} = \sin(\Omega_{\text{t}} \tau) \hat{x}' + \cos(\Omega_{\text{t}} \tau) \hat{y}'$. The angular momentum of the outer binary is therefore perpendicular to the $x' \cdot y'$ plane and so parallel to the $z'$ axis. By plugging this expression for $\hat{n}$ into the above equation and averaging over an orbital period of the outer binary, $2\pi/\Omega_o$, we obtain

$$\frac{dL_i}{dt} = -w(r_{\text{min}}, r_{\text{max}}) \frac{M_{\ast} M_{\ast}}{2d^3} (\hat{z}' \cdot \tilde{L}) \tilde{L} \times \tilde{L}.$$

(26)

Thus, now $\tilde{L}$ precesses around $z'$: Fig. [1]. Physically, Eq. (25) and (26) describes the precession generated by the quadrupole moment-curvature coupling of the inner binary. For the MBH (outer) binary scenario considered here, the precession period is generically longer than the LISA observation timescale. However, we note that the precession effect also extends to the Newtonian regime as well as to comparable-mass binaries (instead of EMRIs). Thus, let us consider here—and only here—the case of stellar-mass BH binaries close to a MBH of mass $M$, which could be relevant sources for both LISA and LIGO detections [35–39]. In this case, the precession period can be estimated as

$$\frac{2\pi}{\Omega_{\text{prec}}} \sim \frac{2\pi d^3 M_{\ast}^{1/2}}{1.3 \sin \theta_{m_0}^{3/2} M_{\ast}} \sim 2.6 \left( \frac{d}{30 M_{\ast}} \right)^3 \left( \frac{M_{\ast}}{M_{\ast} \text{MSgA}^\ast} \right)^2 \left( \frac{f_{\text{GW}}}{1 \text{mHz}} \right)^{2/3}.$$

(27)

where $\theta_{m_0}$ is taken to be $\pi/4$ for illustration purposes, $f_{\text{GW}}$ is the GW frequency (twice the orbital frequency) of the stellar-mass binary and the component masses are assumed to be $10 M_\odot \sim 10 M_{\odot}$. Notice that such binaries (as well as EMRIs) are likely to be eccentric due to the KL mechanism. Therefore, the waveform also contains a frequency component $\sim f_{\text{GW}}(1 - e)^{-3/2}$ (where $e$ is the eccentricity) corresponding to the pericenter passage.
B. Resonance

In this subsection we consider a point in an accelerated orbit of the particle where the osculating geodesic (in $g_{\mu\nu}$) is a resonant point. At a resonance, the osculating orbit is closed and we no longer consider “phase-space-averaged”-orbits which span a two-dimensional ring on a plane. In this sense, this situation is more similar to the Newtonian limit, which may be viewed as a $\Omega_r: \Omega_\phi = 1: 1$ resonance. In the Newtonian limit, the orbital eccentricity can be boosted to very high values via the Kozai-Lidov mechanism [14] [15]. Following the above analogy, we also expect a non-trivial change of eccentricity and angular momentum of the relativistic orbit during a resonance phase. In particular, the total angular momentum might be boosted, as compared to the monotonic reduction generated by the dissipative self-force [52].

In the calculation of the precession, an order-of-magnitude analysis showed that we could not neglect the orbit of the outer binary when $M \sim M_\star$. Let us carry out a similar order-of-magnitude analysis here. Also, the timescale of a transient resonance driven by the dissipative self-force generally scales as $T_{\text{res}} \sim \mu^{-1/2} M$. By comparing it to the orbital timescale of the third body, we have $T_{\text{res}}/T_\star \sim (a_{\text{tid}}/a_\star)^{1/2} (r_0/M)^{-11/4} \ll 1$. Therefore, for the case we study here, the static approximation for the tidal field applies.

In this subsection, we continue to choose the $z$-axis to be parallel to the symmetry axis of the tidal field. Such setup is slightly different from the celestial coordinate setting in previous studies of hierarchical triple system in Newtonian and post-Newtonian regimes [16] [17] [20], as we do not perform the average over the third body’s orbit. On the other hand, our coordinate choice ensures rotational symmetry of the space-time around the $z$-axis, so that $L_z$ must be conserved.

Suppose that $\Omega_r: \Omega_\phi = p: q$, where $p$ and $q$ are co-prime numbers. Then the integration of the rate of change of a quantity $\mathcal{C}$ over a resonant closed orbit is

$$\left\langle \frac{d\mathcal{C}}{d\lambda} \right\rangle_r \equiv \frac{1}{\Lambda} \int_{0}^{\Lambda} d\lambda \frac{d\mathcal{C}}{d\tau} r^2,$$

where $\Lambda \equiv p \Lambda_r = q \Lambda_\phi$. Such an integration is independent of the longitude of the ascending node for generic inclined orbits [40], but it does depend on the integration constant $\lambda_{0\theta}$ in the $\theta$-motion,

$$\lambda_\theta = \lambda_{0\theta} + \int_{\theta_m}^{\theta} \frac{d\theta}{\sqrt{\Omega_\theta(\theta)}},$$

which is related to the argument of the periastron [40].

In order to illustrate this point, we pick a resonance point with $\Omega_r/\Omega_\phi = 1/2$. This can be achieved with a one-parameter family of radius (e.g., either $r_{\text{min}}$ or $r_{\text{max}}$). For convenience, we choose $r_{\text{min}} = 7 M$ and $r_{\text{max}} = 9.39117 M$, although this choice is not unique.

Also, we choose the inclination angle to be $\theta_m = \pi/4$ (sin $\theta_m = \hat{z} \cdot \hat{L}$). From Eqs. (28) and (15), with the tidal acceleration from Eqs. (2) and (11), we calculated the orbital-averaged rate of change of the Carter constant $Q = L_z^2 - L_z$ as a function of $\lambda_{0\theta}/\lambda_\theta$. The equivalent rates of change of $E$ and $L_z$ are both zero.

![FIG. 3: The resonant-orbit-averaged rate of change of the Carter constant $Q = L_z^2 - L_z$ as a function of the argument of the periastron, $\lambda_{0\theta}/\lambda_\theta$. The equivalent rates of change of $E$ and $L_z$ are both zero.](image-url)
is much larger than unity. We have shown that tidal interaction also drives the evolution of conserved quantities during resonance. Its contribution to the phase error in the radiation-reaction timescale is $\sim \mu^{-1/2} a_{\text{side}}/a_s$. We emphasize that the secular amplification of order $\mu^{-1/2}$ accumulates over the transient resonance scale. Therefore, this is an effect which cannot be captured by directly evaluating $a_{\text{side}}/a_s$ in the dynamical regime as in [5].

IV. ISCO SHIFT

As is well-known, the conservative piece of the gravitational self-force on the smaller mass in an EMRI system causes a shift in the ISCO frequency and radius, with respect to the test particle case [12, 13]. Similarly, in a hierarchical three-body system, the tidal field by the third body also modifies the ISCO frequency and radius. In a hierarchical three-body system, the tidal field by the third body also modifies the ISCO frequency and radius. This is maintained under gauge transformations that preserve Eq. (30) but also the reflection symmetry through the ISCO shift are all gauge-dependent quantities (e.g., $\tilde{\xi}$, $\xi$).

In this section, for the convenience of analysis and to allow easier implementation of previous results in the gravitational self-force problem, we choose a new coordinate system such that the $z$-axis is orthogonal to the orbital plane of the inner binary (while it still goes through $M$). We shall also adopt the viewpoint that the particle in the geodesic of the perturbed Schwarzschild space-time, similar to the treatment in [13, 41]. Correspondingly, the angles $\theta$ and $\phi$ are now the polar and azimuthal angle, respectively, with respect to this new $z$-axis. Thus, in particular, the instantaneous angular velocity of the particle is given by $\Omega = \partial \phi / \partial t$.

Notice that the quantities for which we compute the ISCO shift are all gauge-dependent quantities (e.g., $E$ is conserved but gauge-dependent). Therefore, any result obtained here has to be associated with the gauge that we have chosen. This observation and the associated ambiguity has been emphasized in [42] in the context of the gravitational self-force problem. In that context, this issue is partly resolved by Detweiler in [41] by considering quantities (such as $\Omega$) which, on “quasi-circular” orbits are pseudo-invariants with respect to helical-symmetric gauge transformations:

$$\mathcal{L}_k g_{\alpha\beta} = 0, \quad \mathcal{L}_k h_{\alpha\beta} = \mathcal{O}(\mu^2),$$

where $L_k$ is the Lie-derivative with respect to the helical symmetry vector $k = k^\mu \partial_{\xi^\mu} = \partial_t + \Omega \partial_\phi$. In our case, however, the external field itself breaks such symmetry, and it is not clear whether there is a similar construction of pseudo-invariant quantities. On the other hand, it is possible to assert an angular-averaged version of helical symmetry:

$$\int_0^{2\pi} d\phi \mathcal{L}_k h_{\alpha\beta} = \mathcal{O}(\mu^2).$$

If the above requirement is satisfied, it is straightforward to modify Detweiler’s derivation of gauge invariance of $\Omega$ to prove the invariance of $\int_0^{2\pi} d\phi \Omega$ on “quasi-circular” orbits with respect to any gauge choices satisfying Eq. (31). Note that, based on Eqs. (8) and (9), the average over $\phi$ can be replaced by an average over a period of $\Delta \phi$.

There is one more restriction on the gauge choice, though a rather natural one. Detweiler requires the gravitational perturbation not only to respect the helical symmetry Eq. (30) but also the reflection symmetry through the equatorial plane. The tidal field in our system, however, leads to the violation of this symmetry. If one does not require reflection symmetry, the changes in the metric perturbation under a gauge transformation are then given by those in Eqs. B2-B7 [41] with the only following modification:

$$\Delta h_{\phi\phi} \rightarrow \Delta h_{\phi\phi} - \xi^\mu \xi^\nu \sin^2 \theta \cos \theta, \quad (32)$$

where $\xi^\mu$ is the gauge vector. Because here we are considering orbits on the equatorial plane (where $\cos \theta = 0$), the modification term in Eq. (32) vanishes as long as $\xi^\mu$ is finite. As a result, the gauge-invariance of $\int_0^{2\pi} d\phi \Omega$ is maintained under gauge transformations that preserve Eq. (31) and with $\xi^\mu$ finite.

Because the tidal field breaks the axi-symmetry when the orbital angular momentum is not aligned with the symmetry axis of the tidal field, there is no innermost orbit with strictly circular motion (in fact, there are no strictly-circular orbits at all). Instead, the true trajectory $\gamma'$ (on the full metric $\tilde{g}_{\mu\nu}$) has a slight oscillation in the radial coordinate of magnitude $\delta r \sim \epsilon 2 M$. In fact, if for a moment we take the point of view that the particle is moving in an accelerated orbit in Schwarzschild space-time, the tidal forces (proportional to $\epsilon$) in both radial and azimuthal angle directions contain pieces that are periodic in $\phi$ and pieces that are independent of $\phi$. By solving the equations of motion including the tidal acceleration, it is easy to see that the radial motion of the ISCO orbit (note that the orbit is not actually circular, but it is an innermost stable, circular mean orbit) can be written as $r = r_{\text{mean}} + \epsilon (c_1 \sin \phi + c_2 \cos \phi + c_3 \sin 2\phi + c_4 \cos 2\phi)$ for some $r_{\text{mean}}$, where $c_i$ $(i = 1, 2, 3, 4)$ are coefficients independent of $\phi$. Such description should also be valid in the perturbed space-time picture to which we now return, i.e., the orbit is closed to leading order in $\epsilon$. Given a Hamiltonian $H$ of the “EMRI+tidal interaction system”, we define $H = H/(\mu^2 M^2)$ as a dimensionless quantity. Let us denote by $\gamma$ the “mean” circular orbit (on $\tilde{y}$) with radius $r_{\text{mean}}$. We notice that $\gamma$ is not strictly geodesic and that it has a Hamiltonian order $\mathcal{O}(\epsilon^2)$ away from the true trajectory [44]. In other words, the effect of radial motion only contributes with $\mathcal{O}(\epsilon^2)$ terms to the Hamiltonian. As a result, we can replace $\gamma'$ with the mean
circles of ISCO (i.e., \( r_\text{ISCO} \)), given by, respectively, Eq. (41) and we apply it on the mean circular orbit \( r \) and \( \hat{\mathbf{l}} \). We have performed an analysis of the general-relativistic dynamics of a Schwarzschild EMRI (without gravitational self-force) residing in an external quadrupole tidal field. As discussed earlier, the detection rates of such systems are still subject to uncertainties in EMRI merger rate as well as the merger history of MBHs before GW radiation takes over. This also means that a possible detection of such event would also shed light on the myth of the MBH merger mechanism. It would also provide a unique opportunity to test a perturbed Schwarzschild/Kerr metric predicted by General Relativity, as it has distinctive dynamic and waveform features compared to isolated EMRI systems.

We have discussed three interesting relativistic effect due to the tidal interactions. First, in the non-resonant phase of the EMRI orbit, the main secular effect of this tidal interaction is the precession of the orbital plane around the orbital angular momentum of the outer binary. This precession may contribute at order \( O(2\pi) \) to the phase of the waveform during the precession timescale, given by \( T/\Omega_{\text{prec}} \sim M/c \). However, such precession timescale for EMRIs might be longer than observation timescale of LISA, whereas a similar mechanism applied to stellar mass binary systems near a SMBH gives \( O(\text{days}) \) precession timescale in the LISA band. Second, during the resonant phase, the magnitude of the angular momentum may increase or decrease, in stark comparison with the monotonic suppression driven by the dissipative part of the self-force. The fractional change in the magnitude of the angular momentum driven by the tidal-field during a resonance is, when including the dissipative self-force as well as the tidal force, proportional to \( \mu^{1/2}a_{\text{tidal}}/a_s \), and the resulting orbital phase modification is \( \sim \mu^{-1/2}a_{\text{tidal}}/a_s \). This value could be greater
than phase resolution of LISA depending on the strength of the tidal field and the parameters of the inner binary. Finally, in order to capture some of the dynamical effects due to the tidal field, we also included a calculation of the shift in frequency, radius, energy and angular momentum of the ISCO. In contrast with the conservative piece of the gravitational self-force, which always causes a positive frequency shift in Schwarzschild [12] and for all spins sampled in Kerr [13], the tidal field could lead to either a positive or a negative ISCO frequency shift, depending on the inclination angle of the orbit. In particular, orbits with $\hat{n} \cdot \mathbf{L} < 1/\sqrt{3}$ undergo a negative frequency shift, while orbits with $\hat{n} \cdot \mathbf{L} > 1/\sqrt{3}$ undergo a positive frequency shift. A negative frequency shift corresponds to an earlier merger, and a positive frequency shift to a later merger.

To the best of our knowledge, our analysis is the first fully-relativistic one of three-body systems. In the future, it will be interesting to extend our analysis to the cases of a central Kerr black hole and of inclusion of the gravitational self-force. In addition, for planetary systems it has been shown that octupole-order tidal field by the third body could generate much richer dynamics [17, 18]. For the system we consider here, tidal effect affects the GW waveform mostly through transient resonance phases. During such limited evolution within transient resonances, as the magnitude of octupole order tidal force is $\mathcal{O}(\frac{a}{M})^2$ smaller than the quadrupole order tidal force, it should be subdominant unless we are dealing with highly-eccentric orbits.

Finally, we note that we have analyzed the case where the inner binary is in the extreme mass-ratio regime. It is reasonable to expect that the analytical understanding that we have provided could shed some light on the dynamics of triple systems with a comparable-mass (stellar mass) inner binary, similarly to the spirit of using the Effective-One-Body formalism for describing the nonlinear two-body problem [13]. Such triple systems could form in nuclear field clusters and they are expected to be important sources for ground-based GW detectors [24, 25, 38, 41, 45].

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[53] Although here we only include the perturbation to first order in \( \mu \), that motion is geodesic on the “background+perturbation” space-time has been shown to second order in \([21, 22]\); it is expected that it holds to higher orders as well.
[54] The “average” SNR of detected events is higher than the detection threshold by definition, but it is not clear what are the exact values from \([23]\). Based on Monte-Carlo simulation of binary black holes for LIGO detections in a separate study \([16]\), the distribution probability density of SNR roughly follows SNR\(^{-2} \) – SNR\(^{-3} \) scaling, and hence the mean SNR of detected events is roughly 2 times of detection threshold.
[55] In order to not overburden the notation we use the same symbol \( x^\mu \) to denote the particle’s location in the two viewpoints, although strictly we should be differentiating between them since one is a location in \( g_{\mu
u} \) and the other one in \( \tilde{g}_{\mu
u} \) – it will be obvious from the context which one we mean.
[56] Similarly, Hamiltonian of the particle on a geodesic of \( \tilde{g}_{\mu
u} \) is obtained later in Eq.(34). Such Hamiltonian contains a term that corresponds to the tidal interaction of the “mass ring”.
[57] Note that the dissipative self-force may increase the eccentricity below a certain critical radius \([17]\).
[58] Note that the dissipative self-force may increase the eccentricity below a certain critical radius \([17]\).
[59] A similar treatment was employed in \([13]\) to compute the ISCO shift on the equator of Kerr due to the gravitational self-force.