Bold Diagrammatic Monte Carlo Technique: When the Sign Problem Is Welcome

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| Authors         | Prokof’ev, N;Svistunov, B |
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In this Letter, we explore the possibility of employing the bold-line trick in the DiagMC approach. We propose a scheme which we call bold(-line) diagrammatic Monte Carlo (BMC). In essence, BMC is a generalized iterative scheme in which the iteration protocol depends on the number of iteration steps, or, equivalently, in which the next iteration is a function of not only its immediate ancestor, but of the (properly weighted) whole list of earlier iterations. The crucial difference between BMC and a naive iteration protocol—when one simply uses DiagMC to perform an integration for a given iteration step—is that the convergence of BMC has essentially broader parameter range. We present general arguments why this is the case and perform an illustrative simulation for one-particle s-scattering problem. Despite its formal simplicity, the problem contains all the ingredients one can meet in a general case: the perturbative series diverges if the scattering potential is strong enough, and—in the case of a repulsive potential—the series is not positive definite. The simplifications which we have here are mainly quantitative rather than qualitative. The bold-line trick reduces the infinite perturbative series to just two terms. In the case of a strong attractive potential, two more terms appear in the right-hand side to secure the convergence. Incidentally, with these extra terms a sign problem arises for strong attractive potential as well.

Before turning to the realistic simulation, we start with discussing a generalized iterative procedure which is most close to the actual BMC scheme. To analyze the convergence issues, we can confine ourselves with a linearized problem and write

\[ |f\rangle = |b\rangle + A |f\rangle , \]

where \(|f\rangle\) is some unknown vector, \(|b\rangle\) is a known vector, and \(A\) is a linear operator. Expanding all the vectors in terms of the operator \(A\) eigenvector basis \(\{|\phi_\xi\rangle\}\), we get

\[ f_\xi = b_\xi + a_\xi f_\xi , \]

where \(A |\phi_\xi\rangle = a_\xi |\phi_\xi\rangle\), \(|b\rangle = \sum_\xi b_\xi |\phi_\xi\rangle\), \(|f\rangle = \sum_\xi f_\xi |\phi_\xi\rangle\). The vector equation thus decouples into a set of independent equations for each \(\xi\). From now on the label \(\xi\) can be omitted. From the convergence point of view, it is advantageous to work with iterative schemes that involve—at least at the theoretical level—an averaging of the iterations. Let \(f_n\) be the \(n\)-th generator for the \((n+1)\)-st iteration

\[ \tilde{f}_{(n+1)} = b + a f_n . \]

The quantity \(f_n\) is supposed to be a function of all \(\tilde{f}_j\)'s with \(j \leq n\). As a characteristic example we choose

\[ f_n = \frac{\sum_{j=1}^n j^\alpha \tilde{f}_j}{\sum_{j=1}^n j^\alpha} \]

where \(\alpha > -1\) is a fixed parameter of the scheme. We can exclude \(\tilde{f}_j\)'s and explicitly relate \(f_{(n+1)}\) to \(f_n\) to see that for the deviation \(\delta_n = f - f_{n}\) of the \(n\)-th generator from the exact solution \(f = b/(1 - a)\) the following recursive relation takes place

\[ \delta_{(n+1)} = \delta_n + \frac{(1 + \alpha)(a - 1)}{n + 1} \delta_n . \]

It implies the asymptotic behavior

\[ \delta_n \propto e^{(1+\alpha)(a-1)\ln n} \quad (n \to \infty) . \]
Hence, the condition of convergence is

\[ \text{Re} a_\xi < 1. \]  

(7)

Here we restore the subscript \( \xi \) to emphasize that condition (7) has to be satisfied for all the eigenvalues of the matrix \( \mathbf{A} \). We see that the value of \( \alpha \) does not determine the fact of convergence, but does effect the asymptotic rate of convergence—the larger is \( \alpha \), the higher the rate. It is important that the convergence does not depend on the imaginary parts of \( a_\xi \)'s. Finally, negative real parts of \( a_\xi \) are desirable for convergence: the larger is the absolute value of the negative real part, the better. [Note that the plain iterative method \( (f_n \equiv \bar{f}_n) \) converges only when \( |a_\xi| < 1 \).]

If condition (7) is not met, one can use an equation equivalent to (1), but with convergent iterative procedure. For the \( s \)-scattering problem, the matrix \( \mathbf{A} \) is Hermitian and thus all its eigenvalues are real. In this case, rewriting Eq. (1) as

\[ |f\rangle = |b\rangle + \mathbf{A} \langle f | + \lambda \mathbf{A} (|f\rangle - |b\rangle - \mathbf{A} |f\rangle) \]  

(8)

and fine-tuning the value of the constant \( \lambda \), one can render the iterative process converging. Indeed, the new equation has the same form as the original one, up to replacements \( |b\rangle \rightarrow |b\rangle - \lambda \mathbf{A} |b\rangle \) and \( \mathbf{A} \rightarrow (1 + \lambda) \mathbf{A} - \lambda \mathbf{A}^2 \). Correspondingly, condition (7) for the new matrix will be met if the original eigenvalues satisfy the inequality

\[ (1 + \lambda)a_\xi - \lambda a_\xi^2 < 1. \]  

(9)

As is easily checked, condition (7) is met provided \( \lambda \in (\lambda_1, \lambda_2) \), where

\[ \lambda_1 = \min_{a_\xi > 1} \{a_\xi\}, \quad \lambda_2 = \max_{a_\xi \in (0,1)} \{a_\xi\}. \]  

(10)

Hence, if the eigenvalues are real and separated from unity by a finite gap, there exists a value of \( \lambda \) at which convergence is guaranteed. Incidentally, the problem can always be re-formulated in such a way that the new matrix is Hermitian:

\[ |f\rangle = (1 - \mathbf{A}^\dagger)|b\rangle + (\mathbf{A} + \mathbf{A}^\dagger - \mathbf{A}^\dagger \mathbf{A}) |f\rangle. \]  

(11)

The \( s \)-scattering problem can be formulated (see, e.g., Ref. [3]; for simplicity, we work with a spherically symmetric potential) as Eq. (1) with \( |f\rangle \equiv |f(q)\rangle \) being the zero-energy scattering wave function in the momentum representation. In this case \( |b\rangle \equiv -|u(q)\rangle \), where \( u(q) = U(q)/2\pi \), and \( U(q) \) is the Fourier transform of the scattering potential; the Plank’s constant and particle mass are set equal to unity. The operator \( \mathbf{A} \) here is the integral operator

\[ \mathbf{A} f = -\frac{1}{\pi} \int_{-1}^{1} d\chi \int_{0}^{\infty} u(|q - q_1|) f(q_1) dqq_1, \]  

(12)

where \( |q - q_1| \equiv \sqrt{q^2 + q_1^2 - 2qq_1\chi} \); Eq. (8) then reads

\[ f = -u + \lambda \mathbf{A} u + (1 + \lambda) \mathbf{A} f - \lambda \mathbf{A}^2 f. \]  

(13)

The potential we use in simulations is a flat spherical well/bump defined as \( U(r) = U_0 \) at \( r < 1 \) and zero otherwise. For this potential,

\[ u(q) = \frac{2U_0}{q^3} (\sin q - q \cos q). \]  

(14)

Monte Carlo procedure. Here we discuss how generic DiagMC rules are used to calculate \( f(q) \) self-consistently. For brevity, let us index the four terms in the right-hand-side of Eq. (13) as terms \( \mathcal{A}, \mathcal{B}, \mathcal{C}, \) and \( \mathcal{D} \). Correspondingly, the “configuration space” of the problem is defined by the term index and all continuous variables associated with it. The goal of the Monte Carlo procedure is to perform stochastic summation over this configuration space. The contribution of each state to the answer is characterized by the weight with the sign which in our case is given by the product of \( u \)- and \( f \)-functions; for example, the weight and sign of the \( (\mathcal{B}, q, q', \chi) \) state is determined by the modulus and sign of \( u(|q - q'|)f(q') \).

The standard Metropolis-type protocol consists of updates which change the current configuration state followed by measurements which evaluate contributions of the current state to the answer. The updating scheme described below generates states with probabilities proportional to their weight. In this case, the Monte Carlo estimator for \( f(q) \) is given by the state sign. The statistics of \( \pm 1 \) contributions is accumulated into the \( f(q) \)-histogram with bins covering the positive-\( q \) axis. Apart from representing the final result of the simulation, the histogram is used self-consistently to generate random variables from the probability density \( |f(q)| \) and to determine the sign of \( \mathcal{B} \) and \( \mathcal{D} \) states.

A straightforward accumulation of data into the histogram corresponds to \( \alpha = 1 \) in Eq. (4). However, large values of \( \alpha \) result in faster convergence, see Eq. (10). Numerically, the limit of \( \alpha \rightarrow \infty \) is implemented by simply erasing “old” histogram data.

The simplest updating scheme contains three pairs of complementary updates \( |A \rightarrow B, B \rightarrow A|, |A \rightarrow C, C \rightarrow A|, |C \rightarrow D, D \rightarrow C| \) which change the term index, and one self-complementary update \( A \leftrightarrow A \) changing the variable \( q \).

\( A \leftrightarrow A \) update. A new value for the variable \( q \) in state \( \mathcal{A} \) is generated from the normalized probability density

\[ p(q) = |u(q)|/I_u, \quad I_u = \int_{0}^{\infty} |u(q)| dq, \]  

(15)

The acceptance ratio for the \( A \leftrightarrow A \) update is unity.

\( A \rightarrow B \) update. First, we select the value of \( \chi \) from the uniform probability density on the \([-1,1]\) interval. Next, we select the value \( q' \) from the histogram based probability distribution \( |f(q')| \). The acceptance ratio for this update is

\[ R_{A \rightarrow B} = \frac{2(1 + \lambda) I_f}{\pi p_{\text{ABS}}} \left| \frac{u(q - q')}{u(q)} \right|, \]  

(16)

where \( p_{\text{ABS}} \) is the probability to apply the \( \mathcal{A} \rightarrow \mathcal{B} \) update while in state \( \mathcal{A} \) (we do not mention the probability of
applying an update to the current configuration if it is unity; in this scheme \( p_{BA} = 1 \).

\[
I_f = \int_0^\infty |f(q)| \, dq
\]  

(17)

is the normalization integral proportional to the sum of absolute values of all histogram contributions (its proper normalization is discussed below).

If we now write the normalization integral as a sum over states. In the statistical limit, \( I \approx 0 \) limit, \( a = -f(q = 0) \), and as a histogram sum (the last procedure gives better accuracy since it is based on all Monte Carlo data and thus is not susceptible to the noise in a particular bin)

\[
a = u(0) + \frac{2}{\pi} \int_0^\infty u(q) f(q) \, dq \to u(0) + \frac{2I_u}{\pi Z_A} \sum_s u(q_s) H_s .
\]  

(26)

We have tested our BMC scheme against the analytical answer for the scattering length in different regimes which included strong repulsive and attractive potentials outside of the convergence limits for the standard iterative scheme. For example, one can easily get results for \( a \) with four-digit (or higher) accuracy for the repulsive potential \( U_0 = 10 \); a straightforward summation of the series expansion for large positive values of \( U_0 \) would be impossible because of the divergence and/or the sign problem. Series divergence will also prevent one from going across the resonance and getting results for potentials with bound states. In Fig. 1 we present data for the scattering wave function obtained for \( U_0 = -3 \), i.e. for the potential well with the bound state. In this simulation \( a \) was obtained with the 4-digit accuracy. For negative values of \( U_0 < -10 \) we found that good initial conditions, e.g. results of the previous run for smaller \( |U_0| \), are important for convergence which was very slow and required that \( \lambda \approx 1 \). In view of Eq. (11), we conclude that in this parameter range we face the problem of having matrix \( \lambda \) eigenvalues being too close to unity.

**Fermipolaron T-matrix.** The fermipolaron is a spin-down particle interacting with the sea of spin-up fermions. Of special interest is the case when the spin-up sea is an ideal Fermi gas while the interaction between spin-up and spin-down particles is short-ranged but resonantly strong. In this regime—relevant to the notorious problem of BCS-BEC crossover in the limit of extreme population imbalance between the two fermionic components—the fermipolaron problem allows an unbiased numeric solution by DiagMC. The relevant diagrams are constructed out of the three types of propagators (in the imaginary-time-momentum representation): (i) spin-up Green’s functions, (ii) spin-down vacuum propagators, and (iii) the \( T \)-matrix of the pair interaction between spin-up and spin-down particles. While simple analytic expressions for


FIG. 1: (Color online). Scattering wave function at zero energy (solid line) and scattering potential (dashed line) for the attractive potential well with one bound state ($U_0 = -3$).

FIG. 2: The diagrammatic equation for the $T$-matrix (heavy dashed line) in terms of the vacuum $T$-matrix (light dashed line), spin-down vacuum propagator (straight solid line), and truncated (to the momenta less than Fermi momentum) spin-up propagator (solid arc).

type (i) and (ii) propagators are available, the $T$-matrix has to be tabulated numerically; this tabulation represents the performance bottleneck for the whole scheme. Noting that the equation defining the $T$-matrix through itself (see Fig. 2) is analogous to that for the scattering amplitude, one can directly apply the above-described BMC procedure for obtaining the $T$-matrix. We have successfully done that, which ultimately allowed us to solve the fermipolaron problem.

**Conclusions and outlook**

We have found a numeric counterpart to the bold-line trick of diagrammatic technique. The resulting scheme simulates unknown functions specified by diagrammatic series in terms of themselves. We illustrated our approach by solving the $s$-scattering problem in strong repulsive and attractive potentials. We introduced tools to secure convergence of the process. With these tools we were able to solve the $s$-scattering problem even in an attractive potential with a bound state—essentially non-groundstate problem.

The standard many-body diagrammatic technique deals with three functions that are expressed through each other: Green’s function, self-energy, and the four-point vertex. The generalization of the scheme to this case is theoretically straightforward, since formally one can think of all these functions as different components of the vector $|f\rangle$. The three practical questions that are immediately seen—in the order of their importance—are: (i) regularization of bold-line series, (ii) convergence of the scheme, (iii) optimal data structure. Formally, the convergence of the bold-line series may depend on the summation order and in certain cases be achievable at the expense of controllable systematic error. One may keep the expansion-order, $m$, of irreducible diagrams finite and extrapolate results to the $m \to \infty$ limit, work with a finite-size system and extrapolate to the thermodynamic limit, introduce constraints on continuous variables not allowing them to be either very small or very large and apply renormalization techniques (ultra-violet divergences would be a typical example), etc. The convergence of the scheme may be achieved by the tools described in this paper. If the initial approximation to unknown functions is close enough to the exact answer—which will be the case if one starts with an almost ideal system and moves to a strongly interacting regime by small steps in the interaction constant, then one may rely on linearization for constructing the correcting part of the right-hand side operator, using prescriptions of Eq. (8). If unknown functions depend on many continuous variables, histograms may well be not the best method. Instead one may use a variable-step meshes and, correspondingly, re-weighing techniques for collecting statistics. Another option is to approximate unknown functions with analytic expressions and permanently optimize their parameters to best fit coarse-grained histogram sampling coming from the BMC process.

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[2] Heavy (“bold”) lines are used for denoting exact Green’s functions, light lines standing for non-perturbed Green’s functions. Initially, the diagrammatic expansion for the exact Green’s function is written in terms of non-perturbed Green’s functions (light lines). Then one performs a partial summation of diagrams amounting to replacing the light lines with the bold lines, while introducing appropriate constraints on the diagram structure (to prevent double counting). [See, e.g., A.L. Fetter and J.D. Walecka, Quantum Theory of Many-Particle Systems, Dover, 2003.]

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