Detailed Network Measurements Using Sparse Graph Counters: The Theory

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Abstract—Measuring network flow sizes is important for tasks like accounting/billing, network forensics and security. Per-flow accounting is considered hard because it requires that many counters be updated at a very high speed; however, the large fast memories needed for storing the counters are prohibitively expensive. Therefore, current approaches aim to obtain approximate flow counts; that is, to detect large elephant flows and then measure their sizes.

Recently the authors and their collaborators have developed [1] a novel method for per-flow traffic measurement that is fast, highly memory efficient and accurate. At the core of this method is a novel counter architecture called “counter braids.” In this paper, we analyze the performance of the counter braid architecture under a Maximum Likelihood (ML) flow size estimation algorithm and show that it is optimal; that is, the number of bits needed to store the size of a flow matches the entropy lower bound. While the ML algorithm is optimal, it is too complex to implement. In [1] we have developed an easy-to-implement and efficient message passing algorithm for estimating flow sizes.

I. INTRODUCTION

This paper addresses a theoretical problem arising in a novel approach to network traffic measurement the authors and their collaborators have recently developed. We refer the reader to [1] for technological background, motivation, related literature and other details. In order to keep this paper self-contained, we summarize the background and restrict the literature survey to what is relevant for the results of this paper.

Background. Measuring the sizes of network flows on high speed links is known to be a technologically challenging problem [2]. The nature of the data to be measured is as follows: At any given time several 10s or 100s of thousands of flows can be active on core Internet links. Packets arrive at the rate of one in every 40-50 nanoseconds on these links which currently run at 10 Gbps. Finally, flow size distributions are heavy-tailed, giving rise to the well-known decomposition of flows into a large number of short “mice” and a few large “elephants.” As a rule of thumb, network traffic follows an “80-20 rule”; 80% of the flows are small, and the remaining 20% of the large flows bring about 80% of the packets or bytes.

This implies that measuring flow sizes accurately requires a large array of counters which can be updated at very high speeds, and a good counter management algorithm for updating counts, installing new counters when flows initiate and uninstalling them when flows terminate.

Since high-speed large memories are either too expensive or simply infeasible with the current technology, the bulk of research on traffic measurement has focused on approximate counting methods. These approaches aim at detecting elephant flows and measuring their sizes.

Counter braids. In [1] we develop a novel counter architecture, called “counter braids”, which is fast, very efficient with memory usage and gives an accurate measurement of all flow sizes, not just the elephants. We will briefly review this architecture using the following simple example.

Suppose we are given 5 numbers and are told that four of them are no more than 2 bits long while the fifth can be 8 bits long. We are not told which is which.

Figures 1 and 2 present two approaches for storing the values of the 5 numbers. The first one corresponds to a traditional array of counters, whereby the same number of memory registers is allocated to each measured variable (flow). The structure in Fig. 2 is more efficient in memory, but retrieving the count values is less straightforward, requiring a flow size estimation algorithm.

![Fig. 1. A simple counter structure: to each flow size we associate its binary representation (filled circle = 1, empty circle = 0).](image1)

![Fig. 2. Counters braid.](image2)
code [3]. However, the applications we consider impose a stringent constraint on such a code: each time the size of a flow changes (because a new packet arrives) a small number of operations must be sufficient to update the stored information. This is not the case with standard source codes, where changing a single letter in the source stream may alter completely the compressed version.

In this paper we prove that, under a probabilistic model for the flow sizes (namely that they form a vector of iid random variables), counter braids achieve a compression rate equal to the entropy of the flow sizes distribution, in the large system limit. Namely, for any rate larger than the flow entropy, the flow sizes can be recovered from the counter values, with error probability vanishing in the large system limit. Further, we prove optimal compression can be achieved by using braids that are sparse. The result is non-obvious, since counter braids form a pretty restrictive family of architectures.

Our treatment makes use of techniques from the theory of low-density-parity check codes, and the whole construction is inspired by that of LDPC [4], [5]. The construction of LDPC codes has an analogy in the source coding problem thanks to standard equivalence between coding over discrete memoryless symmetric channels, and compressing iid discrete random variables [6]. However, the key ideas in the present paper have been developed to deal with the problem that the flow sizes are a priori unbounded. In the channel coding language, this would be equivalent to use a countable but infinite input alphabet.

Finally, we insist on using sparse braids for two reasons. First, this allows the stored values to be updated with a small (typically bounded) number of operations. Second, it is easy to realize that ML decoding of counter braids is NP-hard, since it has ML decoding of linear codes as a special case [7]. However, thanks to the sparseness of the underlying graph, one may use iterative message passing techniques [8]. Indeed, a simple message passing algorithm for estimating flow sizes is described and analyzed using real and synthetic network traces in [1].

II. COUNTER BRAIDS: BASIC DEFINITIONS

Definition 1. A counter braid is a couple $G = (I, q)$ where $q \geq 2$ is an integer (register capacity) and $G$ is a directed acyclic graph on vertex sets $I$ (input nodes) and $R$ (registers), with the input nodes having in-degree zero. We write $G = (I, R, E)$, with $E$ the set of directed edges in $G$.

For any node $i \in I \cup R$, we will denote by $\partial_i (\cdot) \equiv \{ j : (i, j) \in E \}$ the set of descendants of $i$, and by $\partial_- (\cdot) \equiv \{ j : (j, i) \in E \}$ the set of parents of $i$. Finally $\partial_i \equiv \partial_i \cup \partial_- i$.

In the following we shall often omit the explicit reference to the register capacity and write $G$ for $(G, q)$. The input size of the braid is $|I| \equiv n$, and its storage size $|R| \equiv m$. An important parameter is its rate, which we measure in bits

$$r = \frac{|R| \log_2 q}{|I|}.$$  

We will say that a sequence of counters braids $G_n = (I_n, R_n, E_n)$ is sparse if the number of edges per input node $|E_n| / |I_n|$ is bounded.

Definition 2. A state (or configuration of the counter braid $G_q$, with is an assignment $(x, y)$ of non-negative integers to the nodes in $G$, with $x = \{ x_i : i \in I \} \in \mathbb{N}^I$, and $y = \{ y_j : j \in R \} \in \mathbb{N}^R$. The state $(x, y)$ is valid if $y_j \in \{ 0, \ldots , q-1 \}$ for any register $j \in R$.

Notice that a valid register configuration can be regarded as an element of $(\mathbb{Z}_q)^R$ (where $\mathbb{Z}_q$ is the group of integers modulo $q$). We denote by $0$ the zero vector in $\mathbb{N}^R$.

We want now to describe the braid behavior when one of the input nodes is incremented by one unit (i.e., when a packet arrives at input node $i \in I$.) Assume the braid $(G, q)$ to be in a valid state $(x, y)$. Given $i \in I$, we define the new state $(x', y') = T_i(x, y)$ by letting $x'_i = x_i + 1, x'_j = x_j$ for any $j \neq i$, and $y'$ be defined by the following procedure.

Notice that this definition is ambiguous in that we did not specify which register to pick among the ones with $y_j(t) \geq q$ at step 4 in the registers update routine. However this is not necessary, as stated in the following lemma (the proof is omitted from this extended abstract).

Lemma 1. The update procedure above halts after a finite number of steps. Further its output $T_i(x, y)$ does not depend on the order of update of the registers.

With an abuse of notation we shall write $x^t = T_i(x)$, $y' = T_i(y)$, when $(x', y') = T_i(x, y)$.

When input values $x$ are incremented sequentially, the stored information $y$ is updated according to the above procedure. From now on we shall take a static view and assume a certain input $x$. The corresponding stored information $y$ is obtained through the mapping defined below.

Definition 3. Given a counter braid $(G, q)$, the associated storage function $F_G : \mathbb{N}^I \rightarrow \mathbb{Z}_q^R$ returns, for any input configuration $x \in \mathbb{N}^I$ a register configuration $y = F_G(x) \in \mathbb{Z}_q^R$ defined as follows. Let $x^{(0)} = 0, x^{(1)}, \ldots , x^{(N)} = x$ be a sequence of input configurations such that $x^{(s+1)}$ is obtained from $x^{(s)}$ by incrementing its entry $i(s)$. Then

$$F_G(x) \equiv T_{i(N)} \circ T_{i(N-1)} \circ \cdots \circ T_{i(1)}(0).$$

The registers update (input: flow index $i$)

1: $y_j(0) = y_j$ for $j \notin \partial_+ i$.
2: Set $t = 0$.
3: while $y_j(t)$ is not valid
4: Let $j \in R$ be such that $y_j(t) \geq q$.
5: Set $y_j(t+1) = y_j(t) - q$.
6: For any $l \in \partial_+ j$, set $y_l(t+1) = y_l(t) + 1$.
7: For any $l \in R \setminus \{ j, \partial_- j \}$, set $y_l(t+1) = y_l(t)$.
8: Increment $t := t + 1$.
9: end
10: return $y(t)$.
We shall drop the subscript $G$ from $F_G$ whenever clear from the context. A priori it is not obvious that the mapping $F_G$ is well defined. In particular, it is not obvious that it does not depend on the order in which input values are incremented, i.e. on the sequence $\{i(1), \ldots, i(N)\}$. This is nevertheless the case (the proof is omitted).

**Definition 5.** A sequence of counters braids $\sum_{i}^{-}$ as iid integer random variables $\mathcal{A}$. Main results

However, the achievability of such rates is far from obvious, since counter braids are a fairly specific compression scheme. Theorem 1. Shannon's source coding theorem implies that there cannot be the case (the proof is omitted.)

**Definition 4.** Theorem 1. For any admissible input distribution $p$, any rate $r > H_2(p)$ there exist a sequence of reliable sparse counter braids with asymptotic rate $r$.

As stressed above, we insist on the braid being sparse for two reasons: (i) It allows to update the registers content $y$ with a small number of operations, whenever one entry of $x$ is incremented (i.e. the storage function can be efficiently recomputed); (ii) It opens the way to using low-complexity message passing algorithms for estimating the input vector $x$, given the stored information (i.e. for evaluating the recovery function $F_G$).

A. Main results

Throughout this paper, we shall model the input values as iid integer random variables $(X_1, \ldots, X_n) \equiv X$ (identifying $V = [n]$) with common distribution $p$. The (binary) entropy of this distribution will be denoted by $H_2(p) \equiv -\sum_x p(x) \log_2 p(x)$.

**Definition 5.** A sequence of counters braids $\{G_n = (I_n, R_n, E_n)\}$, where $|I_n| = n$ has design rate $r$ if

$$r = \lim_{n \to \infty} \frac{|R_n|}{|I_n|} \log_2 q.$$ (3)

It is reliable for the distribution $p$ if there exists a sequence of reconstruction functions $\hat{F}_n \equiv \hat{F}_{G_n}$ such that, for $X$ a random input and $Y \equiv F_{G_n}(X)$

$$P_{\text{err}}(G_n, \hat{F}_n) \equiv P(\hat{F}(Y) \neq X) \to 0.$$ (4)

Shannon’s source coding theorem implies that there cannot exist reliable counter braids with asymptotic rate $r < h_2(p)$. However, the achievability of such rates is far from obvious, since counter braids are a fairly specific compression scheme. The main theorem of this paper establishes achievability, even under the restriction that the braid is sparse.

In order to avoid technical complication, we make two assumptions on the input distribution $p$:

1) It has at most power-law tails. By this we mean that $P\{X_i \geq x\} \leq Ax^{-\epsilon}$ for some $\epsilon > 0$.
2) It has decreasing digit entropy. Let $X_i = \sum_{a \geq 0} X_i(a)q^a$ be the $q$-ary expansion of $X_i$, and $h_i$ be the $q$-ary entropy of $X_i(l)$. Then $h_i$ is monotonically decreasing in $l$ for any $q$ large enough.

We call a distribution $p$ with this two properties admissible. While this class does not cover all possible distributions, it is likely to include any case of practical interest.

**Theorem 1.** For any admissible input distribution $p$, and any rate $r > H_2(p)$ there exist a sequence of reliable sparse counter braids with asymptotic rate $r$.

As stressed above, we insist on the braid being sparse for two reasons: (i) It allows to update the registers content $y$ with a small number of operations, whenever one entry of $x$ is incremented (i.e. the storage function can be efficiently recomputed); (ii) It opens the way to using low-complexity message passing algorithms for estimating the input vector $x$, given the stored information (i.e. for evaluating the recovery function $F_G$).

B. Recovery function

We now describe the recovery function $\hat{F}$. Since in this paper we are only interested in achievable, we will neglect complexity considerations.

1) One layer: Let us start from a one-layer braid and assume the inputs to be iid with common distribution $p_i$ supported on $\{0, \ldots, q-1\} \equiv x_i$. Then the register values are $y = Hx \mod q$, where $H$ is the adjacency matrix of the braid. Fix $\gamma \in (0, 1)$. We say that the input $x \in \{0, \ldots, q-1\}^n$ is typical, and write $x \in T_n(p_i)$ if its type $x$ satisfies $D(\theta_x || p_i) \leq n^{-\gamma}$ (here the Kullback-Leibler divergence is computed in natural base). Denote by $T_n(p_i; y)$ the set of input vectors that are typical and such that $Hx = y \mod q$.

The typical set decoder returns a vector $\hat{x}$ if this is the unique element in $T_n(p_i; y)$ and a standard error message otherwise. In formulae

$$\hat{F}(y) = \begin{cases} \hat{x} & \text{if } T_n(p; y) = \{\hat{x}\}, \\ \ast & \text{if } |T_n(p; y)| \neq 1. \end{cases}$$ (6)

2) Multi-layer: Consider now a multi-layer braid and $x \in \mathbb{N}^L$ (inputs not restricted to be smaller than $q$) with $x_i$'s distributed independently according to $p$. It is convenient to write the input vector in base $q$

$$x = \sum_{a \geq 0} x(a) q^a.$$ (7)

where $x(a) = \{x_i(a) : i \in V\}$ with $x_i(a) \in \{0, \ldots, q-1\}$. Notice that, for each $a \geq 0$, the vector $x(a)$ has iid entries. Let $p_a$ be the distribution on $x_i(a)$ when $x_i$ has distribution $p$.

We’ll apply typical set decoding recursively, determining the $q$-ary vectors $x(0), x(1), x(2), \ldots$ in this order. Consider

III. The architecture

A. Layering

We will consider layered architectures. By this we mean that the set of register is the disjoint union of $L$ layers $R = R_1 \cup R_2 \cup \cdots \cup R_L$ and that directed edges are either from $I$ to $R_1$ or from $R_i$ to $R_{i+1}$ for some $l \in \{1, \ldots, L-1\}$ (we shall sometimes adopt the convention $R_L \equiv I$). We denote by $y(0) = \{y_i : i \in R_1\}$ the vector of register values in layer $0$. We further let $m_l \equiv |R_l|$ denote the size of the $l$-th layer (with $m_0 \equiv n$).

The graph structure is conveniently encoded in $L$ matrices $\mathbb{H}_1, \ldots, \mathbb{H}_L$, whereby $\mathbb{H}_l$ is the $m_l \times m_{l-1}$ adjacency matrix of the subgraph induced by $R_l \cup R_{l-1}$. We further let $\mathbb{H}_0 = \mathbb{H}_L \cup \mathbb{H}_{L-1} \cup \cdots \cup \mathbb{H}_1$. The storage function $F$ can be characterized as follows.

**Lemma 2.** Consider an $L$-layers counters braid, let $x$ be its input, and define the sequence of vectors $z(l) \in \mathbb{N}^{R_l}$, by $z(0) = x$ and

$$z(l) = (\mathbb{H}_l z(l-1)) \mod q.$$ (5)

(the division and floor operation being component-wise on the vector $\mathbb{H}_l z(l-1)$.) Then, the register values are $y(l) = \mathbb{H}_l z(l-1) \mod q$.

B. Recovery function

We now describe the recovery function $F$. Since in this paper we are only interested in achievable, we will neglect complexity considerations.

1) One layer: Let us start from a one-layer braid and assume the inputs to be iid with common distribution $p_i$ supported on $\{0, \ldots, q-1\}$. Then the register values are $y = Hx \mod q$, where $H$ is the adjacency matrix of the braid. Fix $\gamma \in (0, 1)$. We say that the input $x \in \{0, \ldots, q-1\}^n$ is typical, and write $x \in T_n(p_i)$ if its type $\theta_x$ satisfies $D(\theta_x || p_i) \leq n^{-\gamma}$ (here the Kullback-Leibler divergence is computed in natural base). Denote by $T_n(p; y)$ the set of input vectors that are typical and such that $Hx = y \mod q$.

The typical set decoder returns a vector $\hat{x}$ if this is the unique element in $T_n(p; y)$ and a standard error message otherwise. In formulae

$$\hat{F}(y) = \begin{cases} \hat{x} & \text{if } T_n(p; y) = \{\hat{x}\}, \\ \ast & \text{if } |T_n(p; y)| \neq 1. \end{cases}$$ (6)

2) Multi-layer: Consider now a multi-layer braid and $x \in \mathbb{N}^L$ (inputs not restricted to be smaller than $q$) with $x_i$'s distributed independently according to $p$. It is convenient to write the input vector in base $q$

$$x = \sum_{a \geq 0} x(a) q^a.$$ (7)

where $x(a) = \{x_i(a) : i \in V\}$ with $x_i(a) \in \{0, \ldots, q-1\}$. Notice that, for each $a \geq 0$, the vector $x(a)$ has iid entries. Let $p_a$ be the distribution on $x_i(a)$ when $x_i$ has distribution $p$.

We’ll apply typical set decoding recursively, determining the $q$-ary vectors $x(0), x(1), x(2), \ldots$ in this order. Consider
first $x(0)$. It is clear from Lemma 2 that $y^{(1)} = H_1 x(0) = \mod q$. We then apply typical set decoding to the determination of $x(0)$. More precisely, we look for a solution of $H_1 x = y^{(1)} \mod q$ that is typical under distribution $p_0$. If there is a unique such solution, we declare it our estimate of $x(0)$ and denote by $\hat{x}(0)$. Otherwise we declare an error.

Consider now the determination of $x(l)$ and assume the lower order terms in the expansion (7) have already been estimated to be $\hat{x}(0), \hat{x}(1), \ldots, \hat{x}(l-1)$. Let $\hat{z}(0) = \sum_{a=0}^{q-1} \hat{x}(a) q^a$, and $\hat{z}(a), a \geq 1$ be determined through the same recursion as in Eq. (5). Further let $\hat{y}^{(a)} = H_{a+1} \hat{z}(a) \mod q$ (this are nothing but the register values on input $\hat{z}(0)$).

Assume the estimates $\hat{x}(0), \hat{x}(1), \ldots, \hat{x}(l-1)$ to be correct. It is then easy to realize that $\hat{y}^{(a)} = y^{(a)}$ for $a = 1, \ldots, l$. Further $z^{(l)} = \hat{z}^{(l)} + H_{l+1} x(l) \mod q$, hence

$$y^{(l+1)} = \hat{y}^{(l+1)} + H_{l+1} x(l) \mod q.$$  

We therefore proceed to compute $y^{(l+1)} - \hat{y}^{(l+1)} \mod q$. If the linear system $H_{l+1} x(l) = y^{(l+1)} - \hat{y}^{(l+1)} \mod q$ admits more than one or no solution that is typical with respect to the distribution $p_l$, an error is returned. Otherwise, the next term in the expansion (7) is estimated through the unique typical solution of such linear system.

The recovery algorithm is summarized below, with one improvement with respect to the description above. Instead of recomputing $\hat{z}(0), \ldots, \hat{z}(l)$, at stage $l$ we only compute the vector $\hat{z}(l)$ that is needed at the present stage.

**RECOVERY (INPUT: register values $y$)**

1: Initialize $\hat{z}^{(a)} = 0$ for $a \geq 0$;
2: for $l \in \{0, \ldots, L\}$
3: Set $\hat{y}^{(l+1)} = H_{l+1} \hat{z}^{(l)} \mod q$;
4: Let $T_l$ be the set of $p_l$-typical solutions of $H_{l+1} x = y^{(l+1)} - \hat{y}^{(l+1)} \mod q$;
5: if $T_l = \{\hat{x}\}$ let $\hat{x}(l) = \hat{x}$
otherwise if $|T_l| \neq 1$ return error;
6: Set $\hat{z}^{(l+1)} = \{\hat{y}^{(l+1)} + H_{l+1} \hat{x}(l)\}$ / $q$;
7: end
8: return $\hat{x} = \sum_i \hat{x}(i) q^i$.

**C. Sparse graph ensemble and choice of the parameters**

The optimal compression rate in Theorem 1 is achieved with the following random sparse graph construction. Fix the registers capacity $q$ and an integer $k \geq 2$. Then for $l = 1, \ldots, L_0$, the graph induced by vertices $R_{l-1} \cup R_l$ has a random edge set that is sampled by connecting each $i \in R_{l-1}$ to $k$ iid uniformly random vertices in $R_l$ (all edges being directed from $R_{l-1}$ to $R_l$). In other words, the $m_l \times m_{l-1}$, $0 \rightarrow 1$ matrix $H_l$ has independent columns, each sampled by increasing $k$ iid positions.

The choice of this ensemble is motivated by implementation concerns. In the flow counting problem, we do not know a priori the exact number of flows that needs to be stored. The above structure, this number can be changed without modifying existing links. Further, for each new flow, the subset of $k$ registers it is connected to can be chosen through a simple hash function.

To these $L_0$ stages, we add further $L_1$ stages, all of the same size $m_{L_0+1} = \cdots = m_{L_0+L_1} = m$, with edges connecting each node in $R_{l-1}$ to a different node in $R_l$. Equivalently, we take $H_l$ to be the identity matrix in these stages.

It remains to specify the number of stages $L_0$, $L_1$ and their sizes $m_1, \ldots, m_{L_0}$. Let $p_l$ be the distribution of the $l$-th least significant digit in the $q$-ary expansion of $X$. Recall that we defined $h_l$ to be the $q$-ary entropy of the distribution $p_l$, i.e.

$$h_l = -\sum_{x=0}^{q-1} p_l(x) \log q p_l(x).$$  

Finally, in the achievability proof, we shall assume that $q$ is a prime number, large enough for $h_l$ to be monotonically decreasing.

**Lemma 3.** Assume $P\{X_1 \geq x\} \leq A x^{-\epsilon}$. Then there exists constants $B, C$ that only depend on $A, \epsilon$, such that for all $l \geq 1$, and all $q$ large enough

$$h_l \leq B l q^{-\epsilon},$$  
\begin{equation}
|h_2(p) - \sum_{l=0}^{q-1} h_l \log_2 q| \leq C (q^4 (\log_2 q)^2.  
\end{equation}

The proof of this simple Lemma is deferred to Section [VI]

**Lemma 4.** Let $p_r$ be a distribution over $\{0, \ldots, q\}$, with $q$-ary entropy $H(p_r)$. and $T_n(p_r)$ be the set of $p_r$-typical vectors defined as in Sec [III-B]. Let $|T_n(p_r)|$ be the size of this set. Recall that $x \in T_n(p_r)$ if its type $\theta_x$ satisfies $D(\theta_x||p_r) \leq n^{-\gamma}$. Then, for any $\beta \in (1 - \gamma/2, 1)$, there exists $A = A(\beta, \gamma, q)$ such that

$$|T_n(p_r)| \leq q^{nH(p_r) + An^\beta},$$  

Further, if $X = (X_1, \ldots, X_n)$ is a vector with iid entries with common distribution $p_r$

$$P\{X \notin T_n(p_r)\} \leq (n + 1)^q e^{-n^1 - \gamma}.$$  

In the following we will consider $\gamma$ and $\beta$ fixed once and for all, for instance by $\gamma = 1/2$ and $\beta = 7/8$.

Fix some $\delta > 0$, and let $A(q)$ be a suitably large constant, we let, for $l = 1, \ldots, L_0$,

$$m_l = \max\{m_{l-1}, [\delta m_{l-1}]\},$$  
$$\mu_l = (1 + \beta) [nh_{l-1}(1 + \delta) + A(q)n^\beta].$$  

The number of stages is such that

$$\mu_l \leq n((\log n)^{-2} for any $l \geq L_0.$

This implies, by Lemma 3, $L_0 = O((\log \log n)$. To this we add $L_1 = (\log n)^3/2$ stages within the second group, of size $m_1 = m_{L_0} \leq n((\log n)^{-2}$. The total number of registers is therefore upper bounded as $|R| \leq n(1 + \delta) \sum_{l=0}^{L_0} (h_l + \delta)$.
Lemma 5. The expression

\[ r \leq \frac{1 + \delta}{1 - \delta} \sum_{l \geq 0} b_l \log_2 q. \]  

(16)

Since the right hand side can be made arbitrarily close to \( h(p) \) by Lemma 3, Theorem 1 follows from the following.

Theorem 2. For any input distribution \( p \) with at most polynomial tails and any choice of \( \delta \geq 2 \) and \( \delta > 0 \), there exists \( k \geq 2 \) such that the multi-layer braid described above is reliable.

IV. ANALYSIS OF ONE-LAYER ARCHITECTURES

In order to prove our main Theorem or, equivalently, Theorem 2 we need first to prove a few preliminary results concerning a one-layer architecture. The proof here follows the technique of [9], the main tool being an estimate of the distance enumerator as in [4], [10], [11]. Distance enumerators for non-binary LDPC codes have been estimated in [12]. Unhappily we cannot here limit ourselves to citing these works, because the graph ensemble is different from the regular ones treated there.

Throughout this Section the source is a vector \( X = (X_1, \ldots, X_n) \) with iid taking values in \( \{0, \ldots, q - 1\} \) and distribution \( p_\lambda \) (in the application to multi-layer schemes \( p_\lambda \) will coincide with \( p_l \) for some \( l \geq 0 \)). We let \( \mathbb{H} \) be a \( n \times n \) matrix whose columns are independent vectors with integer entries. Each column is obtained by choosing \( k \) positions independently and uniformly at random (eventually with repetition) and incrementing the corresponding entry by one. In other words, \( \mathbb{H} \) is distributed as the adjacency matrix of a given layer in the multi-layer architecture.

Our first result is a simple combinatorial calculation. Let \( \lambda = \{\lambda_z : z = 1, \ldots, q - 1\} \) be a vector in \( \mathbb{P}_{+}^{q-1} \). It is convenient to introduce the random variable \( \mathcal{W} = \{W_z : z = 1, \ldots, q - 1\} \) taking values in \( \mathbb{N} \). The joint distribution of \( \mathcal{W} = (W_1, \ldots, W_{q-1}) \) is the one of \( q - 1 \) Poisson random variables with \( \lambda_z \), conditioned on \( \sum_{z=1}^{q-1} z W_z = 0 \), mod \( q \).

Lemma 5. Let \( x \in \{0, \ldots, q - 1\}^n \) be an input vector with \( n_z \) entries equal to \( z \), for \( z = 0, \ldots, q - 1 \), and \( \mathbb{H} \) be a random matrix as above. Define \( \overline{\mathbb{H}} = \{n_z : z = 1, \ldots, q - 1\} \). For any \( \lambda \in \mathbb{P}_{+}^{q-1} \), let \( \overline{W}, \ldots, \overline{W}_m \) be \( m \) iid vectors with distribution \( \mathcal{P}_\lambda \). Then the probability that \( \mathbb{H} x = 0 \) mod \( q \) is

\[ \mathbb{P}\{\mathbb{H} x = 0\} = \prod_{z=1}^{q-1} \frac{(kn_z)!}{(m \lambda_z)^{kn_z}} Q(\lambda)^{m \lambda_z} \mathcal{P}_\lambda^{m} \left( \sum_{i=1}^{m} \overline{W}_i = k n_z \right), \]  

(17)

where \( Q(\lambda) \) is the probability that \( \sum_{z=1}^{q-1} z U_z = 0 \), mod \( q \) for independent Poisson random variables with means \( \lambda_z \).

Further, for some universal constant \( C \) and \( D_q = 1 - \cos 2\pi/q \), and \( n_* = \sum_n n_z \),

\[ \mathbb{P}\{\mathbb{H} x = 0\} \leq (Ckn_\lambda)^{\frac{q-1}{2}} Q(kn/m)^{m R(m, \frac{k}{q} \sum_{z=1}^{q-1} zn_z)} \leq \frac{1}{q} \left( 1 + (q - 1) e^{-D_q \frac{k n_z}{m}} \right) \]  

(18)

\[ Q(kn/m) \leq \frac{1}{q} \left( 1 + (q - 1) e^{-D_q \frac{k n_z}{m}} \right) \]  

(19)

\[ R(m, N) = \min \{1, (Cq^2N/m)^N\} \]  

(20)

Proof. Due to the symmetry of the distribution of \( \mathbb{H} \) with respect to permutation of its columns, \( \mathbb{P}\{\mathbb{H} x = 0\} \) does depend on \( x \) only through the number of ones, twos, etc. Without loss of generality we can assume the first \( n_1 \) coordinates to be ones, the next \( n_2 \) to be twos, and so on, and neglect the last \( n - \sum_n n_z \) columns, corresponding to zeros. Think now of filling the matrix, by choosing its non-zero entries (edges in the associated graph). If we associate to each such entry the value of the corresponding coordinate in \( x \), we want the probability for the sum of labels on each row to be \( 0 \mod q \). Since entries are independent and uniformly random, this is equal to the probability that each of \( m \) urns is filled with balls whose labels add to \( 0 \), when we throw \( k n_1 \) balls labeled with \( 1 \), \( k n_2 \) labeled with \( 2 \), and so on. It is an exercise in combinatorics to show that this is

\[ \prod_{z=1}^{q-1} \frac{(kn_z)!}{m n_z} \mathcal{P}_\lambda \]  

(17)

is the probability that \( \mathcal{H} \mathcal{X} = 0 \) mod \( q \). Equation (17) is then obtained by evaluating \( \mathcal{P}_\lambda \) and showing that it yields the above combinatorial expression.

In order to get Eq. (18), we denote \( \mathcal{P}_\lambda \{\cdots\} \) by \( R \), and use \( \lambda_z = k n_z / m \), thus leading to

\[ \mathbb{P}\{\mathbb{H} x = 0\} = \prod_{z=1}^{q-1} \frac{(kn_z)!}{(kn/m) n_z} Q(kn/m)^{m R}. \]  

Equation (18) follows from the observation that \( N! \leq \sqrt{2\pi N} (N/e)^N \) for some universal constant \( C \).

In order to prove Eq. (19), notice that, by discrete Fourier transform

\[ Q(\lambda) = \frac{1}{q} \sum_{\ell=0}^{q-1} e^{2\pi i \ell} \sum_{z=1}^{q-1} z U_z \]  

(18)

\[ = \frac{1}{q} \sum_{\ell=0}^{q-1} \exp \left\{ - \sum_{z=1}^{q-1} \lambda_z (1 - e^{2\pi i \ell}) \right\}. \]  

(19)

The claim is proved by singling out the \( \ell = 0 \) term and bounding the others using \( \Re(1 - e^{2\pi i \ell}) \geq D_q \).

Let us finally prove Eq. (20). Obviously \( R \leq 1 \) since it is an upper bound on the probability \( \mathcal{P}_\lambda \{\cdots\} \). If we let \( N = \sum_{z=1}^{q-1} zn_z \), we can therefore assume, without loss of generality, that \( N \) is an integer with \( N/m \leq 1/q \). Let \( V_i \)
be distributed as $\sum_{i=1}^{q-1} W_{i,z}/q$ conditioned on $V_i$ being an integer. Then the probability $\mathbb{P}_X\{\cdots\}$ is upper bounded by
\[
\mathbb{P}\left\{ \sum_{i=1}^{m} V_i \geq N \right\} \leq \left( \frac{m}{N} \right) \mathbb{P}\{V_i \geq 1\}^N \leq \left( \frac{CN}{N} \mathbb{P}\{V_i \geq 1\} \right)^N.
\]
Recalling the definition of $V_i$, we have
\[
\mathbb{P}\{V_i \geq 1\} = \mathbb{P}\left\{ \sum_{z=1}^{q-1} zU_z \geq \left( \sum_{z=1}^{q-1} zU_z = 0 \mod q \right) \right\} \leq e^{\sum_{z=1}^{q-1} \lambda_z \mathbb{P}\{zU_z \geq q\}}.
\]
But $\sum_{z=1}^{q-1} \lambda_z = kn_*/m \leq Nq/m \leq 1$. Further, $\sum_{z=1}^{q-1} zU_z \geq q$ only if $\sum_{z=1}^{q-1} U_z \geq 2$. Therefore we get
\[
\mathbb{P}\{V_i \geq 1\} \leq e^{\mathbb{P}\left\{ \sum_{z=1}^{q-1} U_z \geq 2 \right\}} \leq C \left( \sum_{z=1}^{q-1} \lambda_z \right)^2 \leq C(kn_*/m)^2.
\]
The proof is completed by noticing that $(kn_*/m) \leq (Nq/m)$.

In the following, given a vector $x = (x_1, \ldots, x_n)$, we shall denote by $||x||_0$ number of non-zero entries.

**Lemma 6.** Let $H$ be a random $m \times n$ matrix distributed as above, with column weight $k$. Assume $k$ not to be a multiple of $q$, $m \leq n$, $(m/n)^{1/k} \geq \Delta > 0$ and $3 \leq k \leq m/\log m$. Then, there exists a constant $B = B(q, \Delta)$, $C = C(q, \Delta)$, such that, if
\[
E \leq \frac{Cm}{\log(nk/m)},
\]
then
\[
\mathbb{P}\left\{ ||z||_0 \leq E : \mathbb{H}z = 0 \mod q \right\} \leq n^2 \left( \frac{Bk}{m} \right)^{\frac{k}{q}}
\]
(where it is understood that $z \in \{0, \ldots, q-1\}^n$.)

**Proof.** Throughout the proof, $A$ will denote a generic constant depending only on $q$ that can be chosen large enough to make the inequalities below hold.

Let $z \in \{0, \ldots, q-1\}^n$ be such that $||z||_0 = \ell$. We will upper bound the probability that $\mathbb{H}z = 0 \mod q$ in different ways depending whether $\ell \leq E_0$ or $\ell > E_0$, where
\[
E_0 = \rho(q) \frac{m}{k} \left( \frac{m}{nk} \right)^{2/(k-2)},
\]
with $\rho(q)$ a function to be determined. Notice that, under our hypotheses,
\[
kE_0 \geq \rho(q) \Delta^{2k/(k-2)}
\]
is bounded away from 0 (as $2 \leq 2k/(k-2) \leq 6$ for $k \geq 3$.) For $||z||_0 = \ell \leq E_0$ (and $z \neq 0$) we use Lemma 5 Eq. (19) where we set $Q(\cdots) \leq 1$, $n_0 = \ell$ and $k/\ell \leq \frac{1}{2} \sum_{z=1}^{q-1} zn_z \leq k\ell$. Further we assumed $\Delta\ell^k/m \leq 1$, which holds without loss of generality if we take $\rho(q) \leq 1/A\Delta^6 \leq 1/A\Delta^{2k/(k-2)}$ in Eq. (23), thus getting
\[
\mathbb{P}\{\mathbb{H}z = 0\} \leq (A\ell)^{2k/(k-2)} (Ak\ell/m)^{k/\ell}.
\]
Since $(k\ell)^{(q-1)/2} \leq A\ell^{q/2}$, we have (by properly adjusting $A$)
\[
\mathbb{P}\{\mathbb{H}z = 0\} \leq (Ak\ell/m)^{k/\ell}. \quad (25)
\]
For $||z|| > E_0$, we use Eq. (18) with $R(\cdots) \leq 1$. Since $k\ell/m > kE_0/m$ is bounded away from 0 by Eq. (24), we have $Q(\cdots) \leq e^{-C}$ for some $C = C(\Delta, q) > 0$ and therefore
\[
\mathbb{P}\{\mathbb{H}z = 0\} \leq (Ak\ell)^{(q-1)/2} e^{-Cm}. \quad (27)
\]

There are at most $(\binom{n}{\ell} (q-1)^{\ell})$ vectors $z$ with $||z||_0 = \ell$. If we denote by $\mathbb{P}_{E_1, E_2}$ the probability of the event $\{z : E_1 \leq ||z||_0 \leq E_2, \mathbb{H}z = 0 \mod q\}$, the probability in Eq. (22) is upper bounded by $\mathbb{P}_{E_2, E_0} + \mathbb{P}_{E_0, E}$ (notice that if $k$ is not a multiple of q, $\mathbb{H}z = 0$ is impossible for $||z||_0 = 1$). By union bound we have
\[
\mathbb{P}_{E_2, E_0} \leq \sum_{\ell=2}^{E_0} \binom{A}{\ell} \left( \frac{Ak\ell}{m} \right)^{k/\ell} \leq \left( \frac{A}{2} \right)^{2k/(q-2)} \left( \frac{2Ak}{m} \right) \sum_{\ell=2}^{E_0} \xi(\ell)^{\ell-2},
\]
where (using $(\ell/2)^{2k/(q-2)} \leq A^{k/(q-2)}$ and eventually adjusting the constant $A$)
\[
\xi(\ell) \equiv \frac{\ell}{\ell} \left( \frac{Ak\ell}{m} \right)^{k/\ell}.
\]
For $\ell \leq E_0$, and choosing $\rho(q)$ small enough in Eq. (23), we obtain $\xi(\ell) \leq 1/2$ thus leading to $\mathbb{P}_{E_2, E_0} \leq n^2(Ak/m)^{k/\ell}$. Finally consider the contribution of vectors $||z||_0 \geq E_0$. Proceeding as above, we have
\[
\mathbb{P}_{E_0, E} \leq \sum_{\ell=E_0}^{E} \binom{A}{\ell} \left( \frac{Ak\ell}{m} \right)^{k/\ell} \leq \frac{A}{E} \mathbb{P}_{E_0, E} \left( \frac{Ak\ell}{m} \right)^{(q-1)/2} e^{-Cm}.
\]
Here we bounded $(An/\ell)^{\ell} = \left( \frac{An}{\ell} \right)^{\ell} \leq (An/E)^{\ell}$, using the fact that $x^{-x}$ is an increasing function of $x$ for $x \leq e^{-1}$, and that $E/An \leq Cm/An \log(nk/m) \leq Cm/An$ is smaller than $e^{-1}$ for $C$ small enough.

Finally we bound $E^{(q+1)/2} \leq A^E$ and $k^{(q-1)/2} \leq k^E$ (which holds for $m$ large enough), thus getting
\[
\mathbb{P}_{E_0, E} \leq \left( \frac{nAk}{m} \right)^{E} e^{-Cm}.
\]
If we take $E_0 = Cm^2/2 \log(nk/Am)$, we get $\mathbb{P}_{E_0, E} \leq e^{-Cm/2}$, which is smaller than $\left( Bk/m \right)^{k/2}$ for a properly chosen constant $B$ and $k \leq m/\log m$ (indeed $k \leq m \varepsilon m$ would be enough for any $\varepsilon m \leq 1$).
V. ANALYSIS OF MULTI-LAYER ARCHITECTURES AND PROOF OF THEOREM 1

Proof: Let \( \mathbb{P}^{(l)}_{\text{err}} \) denote the probability that \( l \)-th term in the \( q \)-ary expansion of \( x \) is decoded incorrectly by the decoder in Section III-B (i.e. that \( \tilde{x}(l) \neq x(i) \)) given that \( x(0), \ldots, x(l-1) \) have been correctly recovered. We will prove that \( \mathbb{P}^{(l)}_{\text{err}} = O(n^{-A}) \) for some \( A > 0 \). Since the multi-layer architecture involves at most \( C \log(n)^2 \) layers, this implies the thesis. Further, we shall consider only the first \( l_0 \) layers, since it will be clear from the derivation below that the error probability is decreasing for the last \( L \) layers.

Let \( x \) be the input. Since we are focusing on the \( l \)-th term in the \( q \)-ary expansion of the input, we will drop the index \( l \), and take \( x \in \{0, \ldots, q-1\}^n \). This is just a vector whose entries are iid with distribution \( p \).

The error probability \( \mathbb{P}^{(l)}_{\text{err}} \) is upper bounded by the probability that \( x \notin \mathbb{T}_n(p) \) plus the probability that there exists \( x' \neq x \) with \( \mathbb{H}^l x' = \mathbb{H}^l x \mod q \). The first contribution is bounded by Lemma 4, and we can therefore neglect it. Denoting the second contribution as \( \mathbb{P}^{(l)}_{\text{err}} \), and writing \( E_x, \mathbb{P} \) for (respectively) expectation with respect to \( x \) and probability with respect to the matrices \( \mathbb{H}_1, \ldots, \mathbb{H}_l \), we have (matrix multiplications below are understood to be modulo \( q \))

\[
\begin{align*}
\mathbb{P}^{(l)}_{\text{err}} &= \mathbb{E}_x \mathbb{P} \left\{ \exists x' \in \mathbb{T}_n(p_i) \setminus \{x\} \text{ s.t. } \mathbb{H}^l x' = \mathbb{H}^l x \right\} \\
&= \sum_{i=1}^{l} Q^{(l)}_i,
\end{align*}
\]

Since, \( l \leq L = O(\log n) \), it is sufficient to show \( Q^{(l)}_i = O(n^{-A}) \). In \( Q^{(l)}_i \) we can separate error events due to input \( x' \) such that \( d_{it} \equiv d(\mathbb{H}^{l-1} x', \mathbb{H}^{l-1} x) \leq E \) and the others.

As a consequence \( Q^{(l)}_i \) is upper bounded by

\[
\begin{align*}
&\mathbb{E}_x \mathbb{P} \left\{ \exists x' \in \mathbb{T}_n(p_i) \setminus \{x\} \text{ s.t. } \mathbb{H}^l x' = \mathbb{H}^l x \right\} \\
&= \sum_{i=1}^{l} Q^{(l)}_i,
\end{align*}
\]

which implies Eq. (10) for \( \mathbb{P} \leq A q^{-l} \).

In order to prove Eq. (11), first notice that \( H(X_1) = H(\{X_1(l)\}) \leq \sum_{l=0}^{\infty} H(X_1(l)) \) whence \( h_2(p) \geq \sum_{l=0}^{\infty} h_1 \log_2 q \). By the same argument \( h_2(p) \geq \log_2 q \). The thesis follows by bounding \( \sum_{l=0}^{\infty} h_1 \) using Eq. (10).

Proof: Lemma 4. The number of vectors with type \( \theta \) is upper bounded by \( q^{nH(\theta)} \). Since there are at most \((n+1)^q \) distinct types, \( |\mathbb{T}_n(p)\| \leq q^{nH(p)} + nK_n \) where

\[
K_n \equiv \sup_{\theta} \{ H(\theta) - H(p_s) : D(\theta) = n^{-\gamma} \} \\
\]

The bound \( H(\theta) = H(p_s) \leq ||\theta - p_s||_1 \log(q/||\theta - p_s||) \) and \( ||\theta - p_s||_1 \leq \sqrt{2D(\theta)p_s} \).

Equation (12) is just Sanov Theorem.

VI. SOME AUXILIARY RESULTS

Proof: Lemma 3 First consider Eq. (10). Let \( X_1 \) be an integer random variable with distribution \( p \), \( X_1(l) \) its \( l \)-th least significant \( q \)-ary digit and \( Z \) the indicator function on \( X_1(l) \geq 0 \). From \( H(X_1(l)) = H(Z) + H(X_1(l)/Z) \) it follows that, for \( p \),

\[
h_i \leq p_i \log(q-1) - p_i \log(p_i) - (1 - p_i) \log_2(q - 1) \log_2(q - 1).
\]

Choosing \( q \) large enough so that \( p_i \leq A q^{-l} \leq 1/2 \) for all \( l \geq 1 \), we can upper bound \(- (1 - p_i) \log_2(q - 1) \) by \( 2p_i \), thus getting

\[
h_i \leq 3p_i - p_i \log_2(p_i),
\]

which implies Eq. (10) for \( p_i \leq A q^{-l} \).

Proof: Lemma 2. The number of vectors with type \( \theta \) is upper bounded by \( q^{nH(\theta)} \). Since there are at most \((n+1)^q \) distinct types, \( |\mathbb{T}_n(p)\| \leq q^{nH(p)} + nK_n \) where

\[
K_n \equiv \sup_{\theta} \{ H(\theta) - H(p_s) : D(\theta) = n^{-\gamma} \} \\
\]

The bound \( H(\theta) = H(p_s) \leq ||\theta - p_s||_1 \log(q/||\theta - p_s||) \) and \( ||\theta - p_s||_1 \leq \sqrt{2D(\theta)p_s} \).
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