Phase sensitivity bounds for two-mode interferometers

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We provide general bounds of phase estimation sensitivity in linear two-mode interferometers. We consider probe states with a fluctuating total number of particles. With incoherent mixtures of state with different total number of particles, particle entanglement is necessary but not sufficient to overcome the shot noise limit. The highest possible phase estimation sensitivity, the Heisenberg limit, is established under general unbiased properties of the estimator. When coherences can be created, manipulated and detected, a phase sensitivity bound can only be set in the central limit, with a sufficiently large repetition of the interferometric measurement.

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I. INTRODUCTION

The problem of determining the ultimate phase sensitivity (often tagged as the “Heisenberg limit”) of linear interferometers has long puzzled the field [1–14] and still arises controversies [15–36]. The recent revival of interest is triggered by the current impressive experimental efforts in the direction of quantum phase estimation with ions [37], cold atoms [38], Bose-Einstein condensates [39] and photons [40], including possible applications to large-scale gravitational wave detectors [41]. Beside the technological applications, the problem is closely related to fundamental questions of quantum information, most prominently, regarding the role played by quantum correlations. In particular, the phase sensitivity of a linear two-mode interferometer depends on the entanglement between particles (qubits) in the input (or “probe”) state [15–17]. It is widely accepted [15, 16] that, when the number of qubits in the input state of is fixed, and equal to \( N \) so that the mean square particle-number fluctuations \( \langle \hat{N} \rangle^2 = 0 \), there are two important bounds in the uncertainty of unbiased phase estimation. The shot noise limit,

\[
\Delta \theta_{\text{SN}} = \frac{1}{\sqrt{mN}}, \quad \text{for } \langle \hat{N} \rangle^2 = 0, \quad (1)
\]

is the maximum sensitivity achievable with probe states containing only classical correlations among particles. The factor \( m \) accounts for the number of independent repetitions of the measurement. This bound is not fundamental. It can be surpassed by preparing the \( N \) particles of the probe in a proper entangled state. The fundamental (Heisenberg) limit is given by

\[
\Delta \theta_{\text{HL}} = \frac{1}{\sqrt{mN}}, \quad \text{for } \langle \hat{N} \rangle^2 = 0, \quad (2)
\]

and it is saturated by maximally entangled (NOON) states.

It should be noticed that most of the theoretical investigations have been developed in the context of systems having a fixed, known, total number of particles \( N \).

However, many experiments are performed in presence of finite fluctuations \( \langle \hat{N} \rangle^2 > 0 \). The consequences in the phase sensitivity of classical and quantum fluctuations of the number of particles entering the interferometer have not been yet investigated in great depth. In this case, the existence and discovery of the phase uncertainty bounds can be critically complicated by the presence of coherences between different total number of particles in the probe state and/or the output measurement [17, 18]. However such quantum coherences do not play any role in two experimentally relevant cases: \( i) \) in the presence of superselection rules, which are especially relevant for massive particles and forbid the existence of number coherences in the probe state; \( ii) \) when the phase shift is estimated by measuring an arbitrary function of the number of particles in the output state of the interferometer, e.g. when the total number of particles is post-selected by the measurement apparatus. The point \( (ii) \) is actually an ubiquitous condition in current atomic and optical experiments. Indeed, all known phase estimation protocols implemented experimentally are realised by measuring particle numbers.

In the absence of number coherences, or when coherences are present but irrelevant because of \( (ii) \), we can define a state as separable if it is separable in each subspace of a fixed number of particles [17]. A state is entangled if it is entangled in at least one subspace of fixed number of particles. With separable states, the maximum sensitivity of unbiased phase estimators is bounded by the shot-noise

\[
\Delta \theta_{\text{SN}} = \frac{1}{\sqrt{m\langle \hat{N} \rangle}}, \quad \text{for } \langle \hat{N} \rangle^2 > 0, \quad (3)
\]

while with entangled states the relevant bound, the Heisenberg limit, is given by [17]

\[
\Delta \theta_{\text{HL}} = \max \left[ \frac{1}{\sqrt{m\langle \hat{N} \rangle^2}}, \frac{1}{m\langle \hat{N} \rangle} \right], \quad \text{for } \langle \hat{N} \rangle^2 > 0. \quad (4)
\]

We point out that Eq. (4) cannot be obtained from Eq. (2) by simply replacing \( N \) with \( \langle \hat{N} \rangle \). On the other
hand, Eq. (4) reduces to Eq. (2) when number fluctuations vanish, \((\hat{N}^2) = (\bar{N})^2\). An example of phase estimation saturating the scaling \(1/m(\bar{N})\) is obtained with the coherent/squeezed-vacuum state [42]. When the probe state and the output measurement contain number coherences, the situation becomes more involved. It is still possible to show that Eq. (4) holds in the central limit \((m \gg 1)\), at least. Outside the central limit, it is possible to prove that the highest phase sensitivity is bounded by

\[
\Delta \theta_{\text{QCR}} = \frac{1}{\sqrt{m(\bar{N}^2)}}.
\]

(5)

The crucial point is that the fluctuations \((\hat{N}^2)\) can be made arbitrarily large even with a finite \((\bar{N})\). In general, no lower bound can be settled in this case: \(\Delta \theta \geq 0\), and it can be saturated with finite resources \((m < \infty, \langle \hat{N} \rangle < \infty)\) if an unbiased estimator exists. Outside the central limit, \(i.e.\) for a small number of measurements) we cannot rule out the existence of opportune unbiased estimators which can saturate Eq. (5).

This manuscript extends and investigates in detail the results and concepts introduced in Ref. [17]. In Sec. II we review the theory of multiparameter estimation with special emphasis on two-mode linear transformations. This allows us to introduce the useful concept of (quantum) Fisher information and the Cramér-Rao bound. We show that two mode phase estimation involves, in general, operations which belong to the \(U(2)\) transformation group. When number coherences in the probe state and/or in output measurement observables are not present, the only allowed operations are described by SU(2) group. In Secs. III and IV we give bounds on the quantum Fisher information depending whether or not the probe state contains number coherences. In the latter case, we set an ultimate bound that can be reached by separable states of a fluctuating number of particles. Finally, in Sec. VI we discuss the Heisenberg limit, Eq. (4), and under which conditions it holds.

This manuscript focuses on the ideal noiseless case. It is worth pointing out that decoherence can strongly affect the achievable phase uncertainty bounds. For several relevant noise models in quantum metrology as, for instance, particles losses, correlated or uncorrelated phase noise, phase uncertainty bounds have been derived [43–48].

II. BASIC CONCEPTS

In the (multi-) phase estimation problem, a probe state \(\hat{\rho}\) undergoes a transformation which depends on the unknown vector parameter \(\theta\). The phase shift is estimated from measurements of the transformed state \(\hat{\rho}_{\text{out}}(\theta)\). The protocol is repeated \(m\) times by preparing identical copies of \(\hat{\rho}\) and performing identical transformations and measurement. The most general measurement scenario is a positive-operator valued measure (POVM), \(i.e.\) a set of non-negative Hermitian operators \(\{\hat{E}(\epsilon)\}_\epsilon\) parametrized by \(\epsilon\) and satisfying the completeness relation \(\int d\epsilon \hat{E}(\epsilon) = \mathbb{1}\) [69]. The label \(\epsilon\) indicates the possible outcome of a measurement which can be continuous (as here), discrete or multivariate. Each outcome \(\epsilon\) is characterized by a probability \(P(\epsilon|\theta) = \text{Tr}(\hat{E}(\epsilon)\hat{\rho}_{\text{out}}(\theta))\), conditioned by the true value of the parameters. The positivity and Hermiticity of \(\{\hat{E}(\epsilon)\}_\epsilon\) guarantee that \(P(\epsilon|\theta)\) are real and nonnegative, the completeness guarantees that \(\int d\epsilon P(\epsilon|\theta) = 1\). The aim of this section is to settle the general theory of phase estimation for two-mode interferometers.

A. Probe state

A generic probe state with fluctuating total number of particles can be written as

\[
\hat{\rho}_{\text{coh}} = \sum_k p_k |\psi_k\rangle \langle \psi_k|.
\]

(6)

with \(p_k > 0\) and \(\sum_k p_k = 1\), where

\[
|\psi_k\rangle = \sqrt{Q_{N,k}} |\psi_{N,k}\rangle.
\]

(7)

is a coherent superposition of states \(|\psi_{N,k}\rangle\) with different number of particles. The coefficients \(Q_{N,k}\) are complex numbers and the normalization condition \(\langle \psi_k | \psi_\ell \rangle = 1\) implies \(\sum_N |Q_{N,k}|^2 = 1\). It is generally believed that quantum coherences between states of different numbers of particles do not play any observable role because of the existence of superselection rules (SSRs) for the total number of particles [49, 50]. In the presence of SSRs the only physically meaningful states are those which commute with the number of particles operator,

\[
[\hat{N}, \hat{\rho}_{\text{coh}}] = 0.
\]

(8)

A state satisfies this condition if and only if [51] it can be written as the incoherent mixture

\[
\hat{\rho}_{\text{inc}} = \sum_N Q_N \hat{\rho}^{(N)},
\]

(9)

where \(\hat{\rho}^{(N)}\) is a normalized \((\text{Tr}[\hat{\rho}^{(N)}] = 1)\) state, \(Q_N = \text{Tr}[\pi_N \hat{\rho}_{\text{coh}}]\) are positive numbers satisfying \(\sum_N Q_N = 1\) and \(\pi_N\) are projectors on the fixed-\(N\) subspace. The existence of SSRs is the consequence of the lack of a phase reference frame (RF) [50]. However, the possibility that a suitable RF can be established in principle cannot be excluded [50]. If SSRs are lifted, then coherent superpositions of states with different numbers of particles become physically relevant.
B. separability and multiparticle entanglement

A crucial property of the probe state is particle entanglement. A state of \( N \) particles is called separable if it can be written as a convex sum of product states [52, 53],

\[
\rho^{(N)}_{\text{sep}} = \sum_k P_k |\phi^{(1)}_k\rangle\langle\phi^{(1)}_k| \otimes \cdots \otimes |\phi^{(N)}_k\rangle\langle\phi^{(N)}_k|,
\]

where \( |\phi^{(i)}_k\rangle \) is the state of the \( i \)-th particle. A state is (multiparticle) entangled if it is not separable. One can further consider the case where only a fraction of the \( N \) particles are in an entangled state and classify multiparticle entangled states following Refs. [53–57]. A pure state of \( N \) particles is \( k \)-producible if it can be written as \( |\psi_{k\text{-prod}}\rangle = \otimes_{l=1}^{M} |\psi_l\rangle \), where \( |\psi_l\rangle \) is a state of \( N_l \leq k \) particles, with \( \sum_{l=1}^{M} N_l = N \). A state is \( k \)-particle entangled if it is \( k \)-producible but not \((k-1)\)-producible. Therefore, a \( k \)-particle entangled state can be written as \( |\psi_{k\text{-ent}}\rangle = \otimes_{l=1}^{M} |\psi_l\rangle \) where the product contains at least one state \( |\psi_l\rangle \) with \( N_l = k \) which does not factorize. A mixed state is \( k \)-producible if it can be written as a mixture of \((k \leq l)\)-producible pure states, i.e.,

\[
\rho_{k\text{-prod}} = \sum_l P_l |\psi_{k\text{-prod}}\rangle\langle\psi_{k\text{-prod}}|, \quad \text{where} \quad k \leq l \quad \text{for all} \quad l.
\]

Again, it is \( k \)-particle entangled if it is \( k \)-producible but not \((k-1)\)-producible. Notice that, formally, a separable state \( k \)-producible but not \((k-1)\)-producible. Similarly, an incoherent state \( \hat{\rho} \) is \( 1 \)-producible, and that a decomposition of this definition are entangled. Analogously, a state will be called \( k \)-producible if the projection on each fixed-\( N \) subspace has the form of Eq. (12).

C. Two-mode transformations

In the following we will focus on linear transformations involving two modes. These includes a large class of optical and atomic passive devices, including the beam-splitter, Mach-Zehnder and Ramsey interferometers. Most of the current prototype phase estimation experiments [37–40] are well described by a two-mode approximation.

Denoting by \( \hat{a}_1 \) and \( \hat{a}_2 \) \((\hat{b}_1 \) and \( \hat{b}_2) \) are input (output) mode annihilation operators, we can write

\[
\begin{bmatrix}
\hat{b}_1 \\
\hat{b}_2
\end{bmatrix} = \mathbf{U} \begin{bmatrix}
\hat{a}_1 \\
\hat{a}_2
\end{bmatrix},
\]

where \( \mathbf{U} \) is a 2 × 2 matrix [3, 59, 60]. By imposing the conservation of the total number of particles, \( \hat{a}_1^\dagger \hat{a}_1 + \hat{a}_2^\dagger \hat{a}_2 = \hat{b}_1^\dagger \hat{b}_1 + \hat{b}_2^\dagger \hat{b}_2 \), we obtain that \( \mathbf{U} \) can be explicitly written as

\[
\mathbf{U} = e^{-i\phi_0} \begin{bmatrix}
e^{-i\phi_1} \cos \frac{\vartheta}{2} & -e^{-i\phi_2} \sin \frac{\vartheta}{2} \\
e^{-i\phi_1} \sin \frac{\vartheta}{2} & e^{-i\phi_2} \cos \frac{\vartheta}{2}\end{bmatrix}.
\]

The matrix Eq. (14) is unitary, preserves bosonic and fermionic commutation relations between the input/output mode operators and its determinant is equal to \( e^{-2i\phi_0} \). The most general two mode transformation thus belongs to the \( U(2) = U(1) \times SU(2) \) group (unitary matrices with determinant \( |\det \mathbf{U}| = 1 \)). The coefficients \( \vartheta \) is physically related to transmittance \( t = \cos^2 \vartheta/2 \) and reflectance \( r = \sin^2 \vartheta/2 \) of the transformation (14), \( \phi_0 \) and \( \phi_1 \) being the corresponding phases. The lossless nature of Eq. (14) is guaranteed by \( t + r = 1 \).

Using the Jordan-Schwinger representation of angular momentum systems in terms of mode operators [61], it is possible to find the operator \( \hat{\mathbf{U}} \) corresponding to the matrix (14). In other words, \( \hat{b}_i = \hat{\mathbf{U}} \hat{a}_i \hat{\mathbf{U}}^\dagger \) for \( i = 1, 2 \) is a transformation of mode operators (Heisenberg picture) and \( \rho_{\text{out}} = \hat{\mathbf{U}} \rho_{\text{in}} \hat{\mathbf{U}}^\dagger \) is the equivalent transformation of statistical mixtures and quantum states, respectively (Schrödinger picture). One finds [3, 59]

\[
\hat{\mathbf{U}}(\phi_0, \vartheta) = e^{-i\phi_0} \hat{\mathbf{N}} e^{-i\vartheta \hat{\mathbf{J}}_n},
\]

where

\[
\hat{\mathbf{N}} = \hat{a}_1^\dagger \hat{a}_1 + \hat{a}_2^\dagger \hat{a}_2
\]

is the number of particle operator, \( \hat{\mathbf{J}}_n = \hat{\mathbf{a}}_x \hat{\mathbf{J}}_x + \hat{\mathbf{a}}_y \hat{\mathbf{J}}_y + \hat{\mathbf{a}}_z \hat{\mathbf{J}}_z \) (where \( \alpha, \beta \) and \( \gamma \) are the coordinates of the vector \( \mathbf{n} \) in the Bloch sphere and satisfy \( \alpha^2 + \beta^2 + \gamma^2 = 1 \)), and

\[
\hat{\mathbf{J}}_x = \frac{\hat{a}_1^\dagger \hat{a}_2 + \hat{a}_2^\dagger \hat{a}_1}{2}, \quad \hat{\mathbf{J}}_y = \frac{\hat{a}_1^\dagger \hat{a}_2 - \hat{a}_2^\dagger \hat{a}_1}{2i}, \quad \hat{\mathbf{J}}_z = \frac{\hat{a}_1^\dagger \hat{a}_1 - \hat{a}_2^\dagger \hat{a}_2}{2}
\]

are spin operators. The exact relation between the parameters of the matrix \( \mathbf{U} \) \([\phi_r, \phi_s] \) and \( \vartheta \) in Eq. (14)]
and the parameters of the operator $\hat{U} [\theta, \alpha, \beta$ and $\gamma$ in Eq. (15)] is given in Appendix A. The operators $\hat{J}_x$, $\hat{J}_y$ and $\hat{J}_z$ satisfy the angular momentum commutation relations. Notice that the pseudo-spin operators commute with the total number of particles, $[\hat{J}_k, \hat{N}] = 0$ for $k = x, y, z$. We can thus rewrite $\hat{J}_n = \otimes_N \hat{j}_n^{(N)}$, where $\hat{j}_n^{(N)} = \hat{\pi}_N \hat{J}_n \hat{\pi}_N = \sum_l (-1)^l \hat{\sigma}_n^{(l)}/2$ and $\hat{\sigma}_n^{(l)}$ is the Pauli matrix (along the direction $n$ in the Bloch sphere, $\hat{\sigma}_n^{(l)} = \alpha \hat{\sigma}_n^{(l)} + \beta \hat{\sigma}_n^{(l)} + \gamma \hat{\sigma}_n^{(l)}$) acting on the $l$-th particle.

The most general U(2) transformation, Eq. (15), can be rewritten as

$$\hat{U}(\theta_1, \theta_2) = e^{i\chi \hat{J}_s} \begin{bmatrix} e^{-i\alpha_1 \hat{a}_1} & e^{-i\alpha_2 \hat{a}_2} \end{bmatrix} e^{-i\chi \hat{J}_s},$$

(16)

where $\theta_1 = \phi_0 + \theta/2$, $\theta_2 = \phi_0 - \theta/2$, $s$ is a direction perpendicular to $z$ and $n$, and $\cos \chi = n \cdot z$. Equation (16) highlights the presence of two phases, $\theta_1$ and $\theta_2$, which can be identified as the phases acquired in each mode $a_1$ and $a_2$ inside a Mach-Zehnder-like interferometer with standard balanced beam splitters replaced by the transformation $e^{\pm i\chi \hat{J}_s}$, see Fig. 1(a)]. Both phases may be unknown. When setting one of the two phases to zero (or to any fixed known value), Eq. (16) reduces to different single-phase transformations:

- SU(2) transformations $e^{-i\theta_\gamma \hat{J}_\gamma}$ ($\phi_0 = 0$) or, equivalently

$$\hat{U}(\theta) = e^{i\chi \hat{J}_s} e^{-i\theta_\gamma \hat{J}_\gamma} e^{-i\chi \hat{J}_s},$$

(17)

with notation analogous to Eq. (16) [see also Fig. 1(b)]. This depends only on the relative phase shift $\theta = \theta_1 - \theta_2$ among the two interferometer modes. This encompasses the beamsplitter $e^{-i\theta_\gamma \hat{J}_\gamma}$, the relative phase-shift $e^{-i\theta_\gamma \hat{J}_\gamma}$ and the Mach-Zehnder $e^{-i\theta_\gamma \hat{J}_\nu}$ transformations.

- U(1) transformations $e^{-i\theta_\alpha \hat{N}}$ ($\theta = 0$), which can be understood as a phase shift equally imprinted on each of the two modes: $e^{-i\theta_\alpha \hat{N}} = e^{-i\theta_\alpha \hat{a}_1^\dagger \hat{a}_1} \otimes e^{-i\theta_\alpha \hat{a}_2^\dagger \hat{a}_2}$. 

D. Output measurement

Generally speaking, a POVM $\{\hat{E}(\varepsilon)\}$ may or may not contain coherences among different number of particles. A POVM does not contain number coherences if and only if all its elements $\hat{E}(\varepsilon)$ commute with the number of particles operator,

$$[\hat{E}(\varepsilon), \hat{N}] = 0.$$ (18)

Equation (18) is equivalent to [62]

$$\hat{E}(\varepsilon) = \sum_N \hat{E}_N(\varepsilon),$$ (19)

where $\hat{E}_N(\varepsilon) \equiv \hat{\pi}_N \hat{E}(\varepsilon) \hat{\pi}_N$ acts on the fixed-$N$ subspace and $\hat{\pi}_N$ are projectors.

In current phase estimation experiments, the phase shift is estimated by measuring a function $f(N_1, N_2)$ of the number of particles at the output modes of the interferometer. The experimentally relevant POVMs can thus be written as

$$\hat{E}(\varepsilon) = \sum_{N_1, N_2} \delta \left[ f(N_1, N_2) - \varepsilon \right] |N_1, N_2 \rangle \langle N_1, N_2|. \hspace{1cm} (20)$$

By making a change of variable $N = N_1 + N_2$ and $M = (N_1 - N_2)/2$ ($-N/2 \leq M \leq N/2$), we can rewrite this equation as

$$\hat{E}(\varepsilon) = \sum_{N} \sum_{M} \delta \left[ f(N, M) - \varepsilon \right] |N, M \rangle \langle N, M|,$$ (21)

which has the form of Eq. (19). Notice that the information about the total number of particles is not necessarily included in the POVM. For instance, the POVM corresponding to the measurement of only the relative number of particles can be written as

$$\hat{E}_M = \sum_N |N, M \rangle \langle N, M|,$$

which, again, has the form of Eq. (19). This example can be straightforwardly generalized to the measurement of
any function of the relative number of particles. For the measurement of the number of particles in a single output port of the interferometer (for instance at the output port “1”), we have

\[ \hat{E}_{N_1} = \sum_{N,M} \delta [N/2 + M - N_1] \langle N,M|N,M \rangle. \]

We recover Eq. (19) also in this case. Analogous results hold for any function of \( N_1 \) (or \( N_2 \)), for instance the measurement of the parity [63] at one output port, \( f(N_1, N_2) = (-1)^{N_1}. \)

### E. Conditional probabilities

For U(2) transformations, Eq. (16), the conditional probability can be written as

\[ P(\varepsilon|\theta_1, \theta_2) = \text{Tr} [\hat{E}(\varepsilon) \tilde{U}(\theta_1, \theta_2) \hat{\rho} \tilde{U}^\dagger(\theta_1, \theta_2)]. \] (22)

If the probe state and/or the POVM do not contain number coherences, i.e., \( \hat{\rho} \) is given by Eq. (9) and/or \( \hat{E}(\varepsilon) \) is given by Eq. (19), then (22) reduces to

\[ P(\varepsilon|N, \theta) = \sum_{N} Q_N P(\varepsilon|N, \theta), \] (23)

where \( P(\varepsilon|N, \theta) = \text{Tr}[\hat{E}(\varepsilon) e^{-i\theta J_N} \hat{\rho} e^{i\theta J_N}] \). The derivation of Eq. (23) depends only on \( \theta \), the relative phase shift among the two modes of the interferometer. We conclude that U(2) transformations are relevant only if the input state contains coherences among different number of particles and the output measurement is a POVM with coherences. In all other cases the phase shift \( e^{-i\theta J_N} \) is irrelevant as the conditional probabilities are insensitive to \( \phi_0 \). In this case, the mode transformation Eq. (16) restricts to the unimodular (i.e., unit determinant) subgroup SU(2). The SU(2) representation, while being not general, is widely used because, in current experiments, the phase shift is estimated by measuring a function of the number of particles at the output ports of the interferometer. Table I summarizes the general two-mode transformation group for the phase estimation problem, depending on the presence of number coherences in the probe state and POVM.

| \( \hat{\rho} \) with coh. | POVM with coh. | POVM without coh. |
|---------------------------|----------------|------------------|
| with coh. | U(2) | SU(2) |
| without coh. | SU(2) | SU(2) |

Table I: The table summarizes the general two-mode transformation group for the phase estimation problem. The U(2) group is only relevant when number coherences are present in both the probe state and in the POVM.

### F. Multiphase estimation

Since U(2) transformations involve two phases, \( \theta_1 \) and \( \theta_2 \), we review here the theory of two-parameter estimation [64]. The vector parameter \( \Theta \equiv \{\theta_1, \theta_2\} \) is inferred from the values \( \varepsilon \equiv \{\varepsilon_1, \varepsilon_2, \ldots, \varepsilon_m\} \) obtained in \( m \) repeated independent measurements. The mapping from the measurement results into the two-dimensional parameter space is provided by the estimator function \( \hat{\Theta}(\varepsilon) \equiv [\Theta_1(\varepsilon), \Theta_2(\varepsilon)] \). Its mean value is \( \bar{\Theta} \equiv [\bar{\Theta}_1, \bar{\Theta}_2] \), with \( \bar{\Theta}_i = \int d\varepsilon \mathcal{L}(\varepsilon|\theta_i) (i = 1, 2) \) and the likelihood function \( \mathcal{L}(\varepsilon|\theta) \equiv \prod_{i=1}^{m} P(\varepsilon_i|\theta) \). We further introduce the covariance matrix \( \mathbf{B} \) of elements

\[ B_{i,j} = \int d\varepsilon \mathcal{L}(\varepsilon|\theta_i) (\Theta_i(\varepsilon) - \bar{\Theta}_i) (\Theta_j(\varepsilon) - \bar{\Theta}_j). \] (24)

Notice that \( \mathbf{B} \) is symmetric and its \( i \)th diagonal element is the variance \( \Delta \Theta_i^2 \) of \( \Theta_i(\varepsilon) \).

#### 1. Cramér-Rao bound

Following a Cauchy-Schwarz inequality [65], we have [66]:

\[ (v^\dagger \mathbf{b} u)^2 \leq m (v^\dagger \mathbf{B} v)(u^\dagger \mathbf{F} u), \quad \forall u, v \in \mathbb{R}, \] (25)

where \( b_{i,j} = \partial \Theta_i / \partial \Theta_j \) is the Jacobian matrix and

\[ F_{i,j} = \int d\varepsilon \frac{1}{P(\varepsilon|\theta)} \left( \frac{\partial P(\varepsilon|\theta)}{\partial \Theta_i} \right) \left( \frac{\partial P(\varepsilon|\theta)}{\partial \Theta_j} \right) \] (26)

the Fisher information matrix [67], which is symmetric and nonnegative definite. Note that \( \mathbf{B} \), \( \mathbf{F} \) and \( \mathbf{b} \) generally depend on \( \Theta \) but we do not explicitly indicate this dependence, in order to simplify the notation. Note also that \( \mathbf{b} \) may depend on \( \Theta \). In the inequality (25) \( \mathbf{b} \) and \( \mathbf{v} \) are arbitrary real vectors. Depending on \( \mathbf{v} \) and \( \mathbf{u} \) we thus have an infinite number of scalar inequalities. If the Fisher matrix is positive definite, and thus invertible, the specific choice \( \mathbf{u} = \mathbf{F}^{-1} \mathbf{b}^\dagger \mathbf{v} \) in Eq. (25) leads to the vector parameter Cramér-Rao lower bound \( \mathbf{B} \geq \mathbf{B}_{\text{CR}} \) [68], in the sense that the matrix \( \mathbf{B} - \mathbf{B}_{\text{CR}} \) is nonnegative definite [i.e. \( \mathbf{v}^\dagger \mathbf{B} \mathbf{v} \geq \mathbf{v}^\dagger \mathbf{B}_{\text{CR}} \mathbf{v} \) holds for all real vectors \( \mathbf{v} \)], where

\[ \mathbf{B}_{\text{CR}} = \frac{\mathbf{b} \mathbf{F}^{-1} \mathbf{b}^\dagger \mathbf{v}}{m}. \] (27)

This specific choice of \( \mathbf{u} \) leads to a bound which is saturable by the maximum likelihood estimator (see Sec. II F 2) asymptotically in the number of measurements.

In the two-parameter case, the Fisher information matrix

\[ \mathbf{F} = \begin{bmatrix} F_{1,1} & F_{1,2} \\ F_{1,2} & F_{2,2} \end{bmatrix} \] (28)
is invertible if and only if $F_{1,2} F_{2,1} - F^2_{1,2} \neq 0$, its inverse given by

$$F^{-1} = \frac{1}{F_{1,1} F_{2,2} - F^2_{1,2}} \begin{bmatrix} F_{2,2} & -F_{1,2} \\ -F_{1,2} & F_{1,1} \end{bmatrix}.$$  

(29)

Furthermore, if $\Theta_i$ does not depend on $\theta_j$ for $j \neq i$ (i.e. $b$ is diagonal), the diagonal elements of $B_{\text{CR}}$ satisfy the inequalities:

$$(\Delta \theta_i)^2_{\text{CR}} = \frac{F_{i,i} b^2_{i,i}}{m(F_{i,i} F_{j,j} - F^2_{i,j})} \geq \frac{b^2_{i,i}}{m F_{i,i}},$$  

(30)

with $i \neq j$, $i,j = 1,2$. For the two-parameter case, the inequality (30) can be immediately demonstrated by using $F_{1,1} F_{2,2} - F^2_{1,2} > 0$ which holds since $F$ nonnegative definite and assumed here to be invertible.

In the estimation of a single parameter, the matrix $B_{\text{CR}}$ reduces to the variance $(\Delta \theta_{\text{CR}})^2$. Equation (27) becomes

$$(\Delta \theta_{\text{CR}})^2 = \frac{b^2}{m F},$$  

(31)

where $b \equiv d\tilde{\Theta}(\theta)/d\theta$ [for unbiased estimators $b = 1$, i.e. $\tilde{\Theta}(\theta) = \theta$ and $F = \int d\epsilon \frac{1}{P(\epsilon)} (\frac{dP(\epsilon|\theta)}{d\theta})^2$ is the (scalar) Fisher information (FI)]. By comparing Eq. (30) and Eq. (31), we see, as reasonably expected, that the estimation uncertainty of a multi-parameter problem is always larger or at most equal than the uncertainty obtained for a single parameter (namely, when all other parameters are exactly known).

2. **Maximum likelihood estimation**

A main goal of parameter estimation is to find the estimators saturating the Cramér-Rao bound. These are called efficient estimators. While such estimators are rare, it is not possible to exclude, in general, that an efficient unbiased estimator may exist for any value of $m$. One of the most important estimators is the maximum likelihood (ML) $\Theta_{\text{ML}}(\epsilon)$. It is defined as the value $\Theta_{\text{ML}}(\epsilon)$ which maximizes the log-likelihood function:

$$\Theta_{\text{ML}}(\epsilon) = \arg \left[ \max_{\phi} \log L(\epsilon|\phi) \right].$$  

(32)

It is possible to demonstrate, by using the law of large numbers and the central limit theorem, that, asymptotically in the number of measurements, the maximum likelihood is unbiased and normally distributed with variance given by the inverse Fisher information matrix $[64, 65]$. Therefore, the specific choice of vector $u$ which leads to the Cramér-Rao bound (27) is justified by the fact that the ML saturates this bound for a sufficiently large number of measurements.

3. **Quantum Cramér-Rao bound**

The Fisher information matrix, satisfies

$$F \leq F_Q,$$  

(33)

in the sense that the matrix $F_Q - F$ is positive definite. The symmetric matrix $F_Q$ is called the quantum Fisher information matrix and its elements are

$$[F_Q]_{ij} = \frac{1}{2} \text{Tr} \left[ \hat{\rho}(\theta)(\hat{L}_i \hat{L}_j + \hat{L}_j \hat{L}_i) \right],$$  

(34)

with $i = 1,2$, where the self-adjoint operator $\hat{L}_i$ (and also $F_Q$) generally depends on $\theta$. Equation (33) holds for any Fisher information matrix (invertible or not) and there is no guarantee that, in general, the equality sign can be saturated. Assuming that $F$ and $F_Q$ are positive definite (and thus invertible) and combining Eq. (27) – in the unbiased case – with Eq. (33), we obtain the matrix inequality $B_{\text{CR}} \geq B_{Q\text{CR}}$ [70], where

$$B_{Q\text{CR}} = F_Q^{-1}.$$  

(36)

This sets a fundamental bound, the quantum Cramér-Rao (QCR) bound [69], for the sensitivity of unbiased estimators. The bound cannot be saturated, in general, in the multiparameter case.

In the single parameter case, we have $\Delta \theta_{\text{CR}} \geq \Delta \theta_{Q\text{CR}}$, where

$$\Delta \theta_{Q\text{CR}} = \frac{1}{\sqrt{m F_Q[\hat{\rho}(\theta)]}}$$  

(37)

The (scalar) quantum Fisher information (QFI) can be written as

$$F_Q[\hat{\rho}(\theta)] = (\Delta \hat{L})^2,$$  

(38)

where $\hat{L}$ is the $\theta$-dependent SLD and we used $\text{Tr}[\hat{\rho}(\theta) \hat{L}] = 0$. The equality $\Delta \theta_{\text{CR}} = \Delta \theta_{Q\text{CR}}$ (or, equivalently $F = F_Q$) holds if the POVM $\{ \hat{E}(\epsilon) \}$ is made by the set of projector operators over the eigenvectors of the operator $\hat{L}$, as first discussed in Ref. [71]. The quantum Cramér-Rao is a very convenient way to calculate the phase uncertainty since it only depends on the properties of the probe state and not on the quantum measurement.

III. FISHER INFORMATION FOR STATES WITHOUT NUMBER COHERENCES

As discussed above, for states without number coherences we can restrict to SU(2) transformations and thus
the estimation of a single parameter: the relative phase shift among the arms of a Mach-Zehnder-like interferometer. In this case, an important property of the QFI holds:

\[ F_Q[\hat{\rho}_{\text{inc}}, \hat{J}_n] = \sum_{N} Q_N F_Q[\hat{\rho}^{(N)}, \hat{J}_n^{(N)}], \]  

(39)

where \( F_Q[\hat{\rho}^{(N)}, \hat{J}_n^{(N)}] \) is the QFI calculated on the fixed-\( N \) subspace. To demonstrate this equation let us consider the general expression of QFI given in Ref. [71],

\[ F_Q[\hat{\rho}, \hat{J}_n] = \sum_{i,j} \left( \frac{p_i'}{\hat{J}_n} |j\rangle \langle i| + \frac{p_j'}{\hat{J}_n} |i\rangle \langle j| \right)^2, \]  

(40)

where \( p_j \geq 0 \) and \( \{|j\rangle\} \) is a basis of the Hilbert space, \( \sum_i |j\rangle \langle j| = 1 \), chosen such that \( \hat{\rho} = \sum_j p_j |j\rangle \langle j| \).

For states without number coherence, we have \( \hat{\rho}_{\text{inc}} = \sum_{N} Q_N \sum_{j} p_j^{(N)} |j^{(N)}\rangle \langle j^{(N)}| \) where \( \{|j^{(N)}\rangle\} \) is a basis on the fixed-\( N \) subspace. Since \( \langle j^{(N)}| \hat{J}_n |j^{(N)}\rangle = \langle j^{(N)}| \hat{J}_n^{(N)} |j^{(N)}\rangle \delta_{N,N}, \) i.e. \( \hat{J}_n \) does not couple states of different number of particles. In an analogous way it is possible to demonstrate that the SLD \( \hat{L} = \sum_{N} \hat{L}^{(N)} \). We thus conclude that, when the input state does not have number coherences, the Von Neumann measurement on the eigenstates of \( \hat{L}^{(N)} \) for each value of \( N \) – which in particular does not have number coherences – is such that the corresponding FI saturates the QFI.

\section{IV. FISHER INFORMATION FOR STATES WITH NUMBER COHERENCES}

In this section we discuss the quantum Fisher information for states with number coherences. First we consider the estimation a single phase, either \( \theta_0 \) or \( \theta_1 \), separately, assuming that the other parameter is known. We then apply the multiparameter estimation theory outlined above to calculate the sensitivity when \( \theta_1 \) and \( \theta_2 \) are both estimated at the same time. We will mainly focus on the calculation of an upper bound to the quantum Fisher information.

\subsection{A. Single parameter estimation}

Let us consider the different transformations outlined in Sec. II C:

- SU(2) transformation \( \hat{U} = e^{-i\theta\hat{J}_n} \). It is interesting to point out that, for SU(2) transformations, number coherences may increase the value of the QFI. We have

\[ F_Q[|\psi\rangle, \hat{J}_n] \geq F_Q[\hat{\rho}_{\text{inc}}, \hat{J}_n], \]

where \( |\psi\rangle = \sum_N \sqrt{Q_N} |\psi^{(N)}\rangle \) is a normalized pure state with coherences and \( \hat{\rho}_{\text{inc}} = \sum_N \pi_N |\psi^{(N)}\rangle \langle \psi^{(N)}| = \sum_N |Q_N| |\psi^{(N)}\rangle \langle \psi^{(N)}| \) is obtained from \( |\psi\rangle \langle \psi| \) by tracing out the number-coherences. Notice that, if \( F_Q[|\psi\rangle, \hat{J}_n] > F_Q[\hat{\rho}_{\text{inc}}, \hat{J}_n] \) holds, then that saturation of \( F_Q[|\psi\rangle, \hat{J}_n] \) necessarily requires a POVM with number coherences.

This is a consequence of the fact that the Fisher information obtained with POVMs without coherences is independent on the presence of number coherences in the probe state and it is therefore upper bounded by \( F_Q[\hat{\rho}_{\text{inc}}, \hat{J}_n] \). Equation (41) can be demonstrated using \( i ) F_Q[|\psi\rangle, \hat{J}_n] = 4(\Delta J_n^2) \) [16, 71] and \( F_Q[\hat{\rho}_{\text{inc}}, \hat{J}_n] = \sum_N Q_N (\Delta J_n^{(N)})^2 |\psi^{(N)}\rangle \langle \psi^{(N)}| \) [see Eq. (39)], where we have explicitly indicated the state on which the variance is calculated on (we will keep this notation where necessary and drop it elsewhere) and ii) the Cauchy-Schwartz inequality

\[ \left( \sum_{N} |Q_N| |\psi^{(N)}\rangle \langle \psi^{(N)}| \right)^2 \leq \sum_{N} |Q_N| |\psi^{(N)}\rangle \langle \psi^{(N)}| \sum_{N} |Q_N| |\psi^{(N)}\rangle \langle \psi^{(N)}|. \]  

(41)

The equality holds if and only if \( \langle \psi^{(N)}| \hat{J}_n^{(N)} |\psi^{(N)}\rangle \) is a constant independent of \( N \).

In the following we discuss the bounds to the QFI. For this, a useful property of the QFI is its convexity [64]. In our case it implies

\[ F_Q[\hat{\rho}_{\text{coh}}, \hat{J}_n] \leq \sum_k p_k F_Q[|\psi_k\rangle, \hat{J}_n] = 4 \sum_k p_k (\Delta J_{n,k}^2), \]  

(42)

where the equality holds only for pure states. Furthermore,

\[ 4(\Delta J_{n,k}^2) \leq 4 \sum_{N} |Q_N,k| (\Delta J_{n,k}^2 |\psi_{N,k}\rangle \langle \psi_{N,k}| \]

\[ \leq \sum_{N} |Q_N,k| N^2 = \langle \hat{N}^2 |\psi_{k}\rangle. \]  

(43)

The first inequality is saturated for \( \langle \hat{J}_n| |\psi_k\rangle = 0 \). In the second inequality we used \( 4(\Delta J_{n,k}^2 |\psi_{N,k}\rangle \langle \psi_{N,k}| \) both saturated for the NOON state \( |\text{NOON}_n\rangle \equiv (|N,0\rangle_n + |0,N\rangle_n)/\sqrt{2} \) with \( |\hat{J}_n| |\text{NOON}_n\rangle = (N/2)|N,0\rangle_n \) and \( |\hat{J}_n| |\text{NOON}_n\rangle = -(N/2)|0,N\rangle_n \). In this case, by using Eq. (42), we have that

\[ F_Q[\hat{\rho}_{\text{coh}}, \hat{J}_n] \leq \text{Tr}[\hat{\rho}_{\text{coh}} \hat{N}^2] \]  

(44)

where the equality can be saturated by a coherent superposition of NOON states (note indeed that \( \langle \text{NOON}_n| \hat{J}_n|\text{NOON}_n\rangle = 0 \)). We thus have

\[ (\Delta \theta)^2_{\text{QCR}} \geq \frac{1}{m \text{Tr}[\hat{\rho}_{\text{coh}} \hat{N}^2]}. \]  

(45)

- U(2) transformations \( \hat{U} = e^{-i\phi \hat{N}} \). Using the convexity of the QFI, we have

\[ F_Q[\hat{\rho}_{\text{coh}}, \hat{N}] \leq 4 \sum_k p_k (\Delta N_{k}^2) \leq 4(\Delta N)^2 \]  

(46)
where the second inequality follows from a Cauchy-Schwarz inequality. We thus have
\[(\Delta \phi_0)_{\text{CR}}^2 \geq \frac{1}{4m(\Delta N)^2}.\] (47)

B. Two-parameter estimation

In the U(2) framework, there are, in general, two phases to estimate: \(\phi_0\) and \(\theta\). When estimating both at the same time, the phase sensitivity is calculated using the multiphase estimation formalism discussed above. The inequality (30), leads to
\[(\Delta \phi_0)^2 \geq \frac{1}{mF_Q[\rho_{\text{coh}}, \hat{J}_n]},\] (48)
which can be further bounded by using the above inequalities for the QFI. For pure states we have
\[F_Q^{-1} = \frac{2}{\det[F_Q]} \left(2(\Delta \hat{J}_n)^2 - \langle \hat{N} \rangle \langle \hat{J}_n \rangle - \langle \hat{N} \hat{J}_n \rangle \right)\] (49)
where \(\det[F_Q] = 4(\Delta \hat{N})^2(\Delta \hat{J}_n)^2 - 4[\langle \hat{N} \hat{J}_n \rangle - \langle \hat{N} \rangle \langle \hat{J}_n \rangle]^2\).
We thus have
\[(\Delta \phi_0)^2 \geq (\Delta \hat{N})^2 - (\langle \hat{N} \hat{J}_n \rangle - \langle \hat{N} \rangle \langle \hat{J}_n \rangle)^2/(\Delta \hat{J}_n)^2.\] (50)
which is always larger than \(1/m(\Delta N)^2\), and
\[(\Delta \theta)^2 \geq \frac{m^{-1}}{4(\Delta \hat{J}_n)^2 - 4[\langle \hat{N} \hat{J}_n \rangle - \langle \hat{N} \rangle \langle \hat{J}_n \rangle]^2/(\Delta \hat{J}_n)^2},\] (51)
which is always larger than \(1/4m(\Delta \hat{J}_n)^2\).

V. SEPARABILITY AND ENTANGLEMENT

When the number of particles is fixed, there exists a precise relation between the entanglement properties of a probe state and the QFI: if the state is separable [i.e. can be written as in Eq. (10)] then the inequality
\[F_Q[\rho_\text{sep}, \hat{J}_n^{(N)}] \leq N\] (52)
holds [16]. A QFI larger than \(N\) is a sufficient condition for entanglement and singles out the states which are useful for quantum interferometry, i.e. states that can be used to achieve a sub shot sound phase uncertainty. The above inequality can be extended to the case of multiparticle entanglement. In Refs [72, 73], it has been shown that for \(k\)-producible states the bound
\[F_Q[\rho_\text{k-prod}, \hat{J}_n^{(N)}] \leq sk^2 + r^2\] (53)
holds, where \(s = \lfloor \frac{N}{k} \rfloor\). Hence a violation of the bound (51) proves \((k + 1)\)-particle entanglement. For general states of a fixed number of particles, we have \(F_Q[\rho^{(N)}, \hat{J}_n^{(N)}] \leq N^2 [15, 16]\), whose saturation requires \(N\)-particle entanglement.

In the case of states with number fluctuations, the situation is more involved. For states without number coherences, by using Eq. (39), we straightforwardly obtain
\[F_Q[\rho_{\text{sep}}, \hat{J}_n] = \sum_N Q_N F_Q[\rho_\text{sep}, \hat{J}_n^{(N)}] \leq \sum_N Q_N N = \langle N \rangle.\] (54)
The phase sensitivity achievable with separable states without number coherences thus satisfies the chain of inequalities \(\Delta \theta \leq \Delta \theta_{\text{CR}} \leq \Delta \theta_{\text{QFI}} \leq \Delta \theta_{\text{SN}}\), where
\[\Delta \theta_{\text{SN}} = \frac{1}{\sqrt{m(\langle N \rangle)}}.\] (55)
which agrees with the common definition of the shot-noise or standard quantum limit. This brings us to the following results. An arbitrary state with non-fixed number of particles but without number-coherences is entangled if it fulfills the inequality
\[\chi^2 \equiv \frac{\langle \hat{N} \rangle}{F_Q[\rho, \hat{J}_n]} < 1,\] (56)
for some direction \(n\). Entanglement is a necessary resource for sub shot-noise sensitivity in linear SU(2) interferometers, i.e. when number coherences are not available or not measured. States \(\hat{\rho}\) satisfying Eq. (54) are useful in a linear interferometer implemented by the transformation \(\hat{J}_n\), since, according to Eq. (37), they can provide a sub shot-noise (SSN) phase sensitivity.

The relation between the properties of a probe state without number coherences and the QFI can be further extended to the case of multiparticle entanglement. Using Eqs. (39) and (12), we have
\[F_Q[\rho_\text{k-prod}, \hat{J}_n] = \sum_N Q_N F_Q[\rho_\text{k-prod}, \hat{J}_n^{(N)}]\] and thus, by using Eq. (51),
\[F_Q[\rho_\text{k-prod}, \hat{J}_n] \leq \sum_N Q_N \left(\frac{N}{k} k^2 + (N - \frac{N}{k} k)^2\right) = \langle \hat{N} k^2 \rangle + \langle \hat{r}^2 \rangle.\] (57)
Here, \(\hat{s} = \lfloor \frac{N}{k} \rfloor\), \(\hat{r} = \hat{N} - \hat{k}\), commute with the number operator \(\hat{N}\). The maximum value of the Fisher information is thus obtained for maximally entangled states \((k = N)\) and is
\[\max_{\rho_\text{inc}} F_Q[\rho_{\text{inc}}, \hat{J}_n] = \langle N^2 \rangle.\] (58)

Equation (55) is reached for incoherent superpositions of NOON states \(\sum Q_N |\text{NOON}\rangle_n |\text{NOON}\rangle_n\). By using Eq. (55), we can define an upper limit for the quantum
Cramér-Rao bound Eq. (37), maximized over all possible quantum states:
\[ \min_{\hat{\rho}_{\text{unc}}} \Delta \theta_{\text{QCR}} = \frac{1}{\sqrt{m(N^2)}}. \] (56)

In particular it is always true that \( \langle N^2 \rangle \geq \langle N \rangle^2 \), where the equality holds if and only if the number of particles does not fluctuate. By a proper choice of the \( Q_N \) distribution, \( \langle N^2 \rangle \) can be an arbitrary function of \( \langle N \rangle \). Therefore, when fixing \( \langle N \rangle \), the bound Eq. (56) can be arbitrarily small, even zero for distribution having \( \langle N^2 \rangle = +\infty \). This was first noticed in Ref. [18]. The significance of the bound Eq. (56) is the subject of a vivid debate in the recent literature [21, 22].

Let us now turn to the case of states with number coherences. In this case there is no clear relation between separability/multiparticle-entanglement (as defined in Sec. 2B) and the QFI. The two examples below illustrate this fact: we show states with number coherences which are separable in each subspace of finite number of particles and have a QFI that can be arbitrarily larger than \( \langle N \rangle \). In other words, the inequality \( \Delta \theta_{\text{QCR}} \leq \Delta \theta_{\text{SN}} \) does not hold for separable states with number coherences. However, it is still possible to find a bound of phase sensitivity for SU(2) transformations if we restrict to POVMs without number coherences. In this case we should consider the state (which we call “MOON” state)
\[ |\psi\rangle = \sqrt{\frac{N}{N+M}} e^{i\phi} |M,0\rangle + \sqrt{\frac{M}{N+M}} |0,N\rangle, \] (57)
with \( N, M > 0 \). For \( N \neq M \) this state is separable in each subspace of a fixed number of particles and thus separable according to our definition (11). If \( N = M \) Eq. (57) reduces to the well known NOON state, which is maximally entangled. The QFI is maximum along the \( z \) direction and given by
\[ F_Q[|\psi\rangle, \hat{J}_z] = N M. \] (58)

The average number of particles in (57) is \( \langle \hat{N} \rangle = 2NM/(N+M) \). Therefore, since \( N + M > 0 \), we have \( F_Q[|\psi\rangle, \hat{J}_z] > \langle \hat{N} \rangle \). We thus have an example of a separable state (with number coherences) which has a QFI larger than the average number of particles. The incoherent mixture is obtained from the pure state Eq. (57) by projecting over fixed-\( N \) subspaces is
\[ \hat{\rho} = \frac{N}{N+M} |M,0\rangle \langle M,0| + \frac{M}{N+M} |0,N\rangle \langle 0,N|. \] (59)

Its QFI which is maximum on the plane orthogonal to \( z \) and fulfills \( F_Q[\hat{\rho}, \hat{J}_n] \leq \langle \hat{N} \rangle \), as expected. Notice that \( F_Q[|\psi\rangle, \hat{J}_z] \geq F_Q[\hat{\rho}, \hat{J}_z] \), as expected.

2. Example: coherence with the vacuum

An example similar to the one above has been discussed by Benatti and Braun in Ref. [27] and highlights how the coherence with the vacuum state can increase the QFI (see also [25, 26], in the single-mode case). Let us take
\[ |\psi\rangle = \sqrt{1 - \frac{\langle N \rangle}{N}} |0,0\rangle + \sqrt{\frac{\langle N \rangle}{N}} e^{i\phi_N} |N,0\rangle, \] (60)
where \( \langle N \rangle \leq N \) is the average number of particles. The QFI for rotations around the \( \hat{J}_z \) axis is \( F_Q[|\psi\rangle, \hat{J}_z] = \langle \hat{N} \rangle \). Properly choosing \( N \) it is possible to reach arbitrary large values of the QFI. For instance \( F_Q[|\psi\rangle, \hat{J}_z] > \langle \hat{N} \rangle \) for \( N > \langle \hat{N} \rangle^k \) and any \( k > 0 \). In particular, Eq. (60) is, as above, an example of separable state [according to Eq. (11)] which has a QFI larger than \( \langle \hat{N} \rangle \) for \( N > \langle \hat{N} \rangle + 1 \). We also have \( F_Q[|\psi\rangle, \hat{J}_z] > \langle \hat{N} \rangle^2 \) for \( N > 2\langle \hat{N} \rangle \). Finally note that, as expected, the condition \( F_Q[|\psi\rangle, \hat{J}_z] < \langle N^2 \rangle = N \langle \hat{N} \rangle \) is always fulfilled (for \( \langle \hat{N} \rangle > 0 \)).

VI. THE HEISENBERG LIMIT

In this section we discuss the ultimate phase sensitivity allowed when fixing the average number of particles \( \langle \hat{N} \rangle \) in the probe state. This is generally indicated as the Heisenberg limit. We focus on SU(2) transformations \( e^{-i\phi \hat{J}_z} \). We show that the Heisenberg limit for states and/or POVMs without number coherences is given by Eq. (5). The first bound in Eq. (5) will be demonstrated in the following. It is generally not tight and is valid for estimators which are unbiased in each fixed-\( N \) subspace [see Sec. VI.A]. The second bound in Eq. (5) is the optimal quantum Cramér-Rao bound, Eq. (56), for estimators which are globally unbiased (\( \Theta = \theta \)). It can be saturated by the maximum likelihood estimator in the central limit (i.e. for \( m \gtrsim m_{cl} \) and a sufficiently large \( m_{cl} \)) by using an incoherent mixture of NOON states. Since \( \langle N^2 \rangle \geq \langle \hat{N} \rangle \), the first bound in Eq. (5) is significant for small values of \( m \). Comparing
Taking \( P/\epsilon \) is is larger than 1 where \( \epsilon \)
ishes, \( \Delta \) \( \rightarrow \) tral limit requires an infinite number of measurement
and saturate Eq. (56). If \( m \)
but, at the same time, the larger is the number of re-
\( \langle \rangle \)
Therefore, the larger is \( m \) the two bounds in Eq. (5) one obtains a lower bound for
\( m_{\text{cl}} \),
\[
m_{\text{cl}} \geq \frac{\langle N^2 \rangle}{\langle N \rangle^2}.
\]
Therefore, the larger is \( \langle N^2 \rangle \), the smaller is the Eq. (56)
but, at the same time, the larger is the number of repeated measurements needed to reach the central limit and saturate Eq. (56). If \( \langle N^2 \rangle \rightarrow \infty \), reaching the central limit requires an infinite number of measurement \( m \rightarrow +\infty \), and, accordingly, the phase uncertainty vanishes, \( \Delta \theta \rightarrow 0 \). Equation (5) is schematically represented in Fig. 2. For states and POVM with number coherences we give some argument on the validity of Eq. (5), even though a conclusive demonstration is missing. For this case, we give an overview of the results obtained in the literature.

A. Heisenberg limit for states and/or POVMs without number coherences

The mean value (for \( m \) independent measurements) of an arbitrary estimator \( \Theta(\epsilon) \) is
\[
\bar{\Theta} = \int d\epsilon P(\epsilon|\theta) \Theta(\epsilon),
\]
where \( \epsilon \equiv \{\epsilon_1, \epsilon_2, \ldots, \epsilon_m\} \) and \( P(\epsilon|\theta) = \prod_{i=1}^{m} P(\epsilon_i|\theta) \).
Taking \( P(\epsilon|\theta) \) as in Eq. (23), we can rewrite Eq. (62) as
\[
\bar{\Theta} = \sum_{N} Q_{N} \bar{\Theta}_{N},
\]
where the sum extends over all possible sequences \( N \equiv \{N_1, N_2, \ldots, N_m\} \), \( Q_{N} = \prod_{i=1}^{m} Q_{N_i} \) is the probability of the given sequence \( \sum_{N} Q_{N} = 1 \),
\[
\bar{\Theta}_{N} \equiv \int d\epsilon P(\epsilon|N, \theta) \Theta(\epsilon),
\]
and \( P(\epsilon|N, \theta) = \prod_{i=1}^{m} P(\epsilon_i|N_i, \theta) \).
Following an analogous method, we can rewrite the standard deviation of the estimator as
\[
(\Delta \theta)^2 = \sum_{N} Q_{N} [\Theta(N) - \bar{\Theta}]^2 + \sum_{N} Q_{N} (\Delta \Theta_{N})^2,
\]
where
\[
(\Delta \Theta_{N})^2 \equiv \int d\epsilon P(\epsilon|N, \theta) [\Theta(\epsilon) - \bar{\Theta}_{N}]^2
\]
is the variance of the estimator \( \Theta(\epsilon) \) for a given sequence \( N \). Since \( \int d\epsilon P(\epsilon|N, \theta) = 1 \), we can apply the Cramér-Rao theorem to set a bound to the variance \( (\Delta \Theta_{N})^2 \):
\[
(\Delta \Theta_{N})^2 \geq \frac{b^2_{N}}{F_N(\theta)},
\]
where \( b_{N} \equiv \partial_{\theta} \bar{\Theta}_{N} \) and
\[
F_N(\theta) \equiv \int d\epsilon P(\epsilon|N, \theta) \left( \frac{d}{d\theta} P(\epsilon|N, \theta) \right)^2
\]
is the Fisher information for the specific sequence \( N \).
Note that \( F_N(\theta) = \sum_{i=1}^{m} F_{N_i}(\theta) \), where \( F_{N_i}(\theta) \) is the Fisher information calculated on the subspace of \( N_i \) particles,
\[
F_{N_i}(\theta) = \int d\epsilon_i \frac{1}{P_1(\epsilon_i|N_i, \theta)} \left( \frac{d}{d\theta} P(\epsilon_i|N_i, \theta) \right)^2.
\]
If all the numbers \( N_i \) are equal to \( N \), we would recover \( F_{N_i}(\theta) = m F_{N}(\theta) \) and thus the usual multiplication factor \( m \). Note also that the Fisher information \( F_{N_i}(\theta) \) is bounded as \( F_{N_i}(\theta) \leq N_i^2 \) \([15, 16]\), and thus \( F_{N}(\theta) \leq \sum_{i=1}^{m} N_i^2 = N \cdot N = N^2 \). By using this result and Eqs. (67) we obtain
\[
\sum_{N} Q_{N} (\Delta \Theta_{N})^2 \geq \sum_{N} Q_{N} b^2_{N} / N^2 \geq \sum_{N} Q_{N} b^2_{N} / S(N)^2
\]
where \( S(N) \equiv \sum_{i=1}^{m} N_i \) is the sum of all values of \( N \) in the sequence, and we have used the inequality \( N^2 \leq S(N)^2 \) which follows since the \( N_i \) are all positive numbers. We now use the Cauchy-Schwarz inequality
\[
\sum_{N} Q_{N} b^2_{N} / S(N)^2 \sum_{N} Q_{N} \geq \left( \sum_{N} Q_{N} b_{N} / S(N) \right)^2.
\]
Using the normalization of \( Q_N \) and Eq. (70), we have
\[
\sum_N Q_N (\Delta \theta_N)^2 \geq \left( \sum_N \frac{Q_N b_N}{S(N)} \right)^2. 
\tag{72}
\]
A second Cauchy-Schwarz inequality,
\[
\sum_N Q_N b_N \sum_{N'} Q_{N'} S(N') \geq \left( \sum_N Q_N \sqrt{b_N} \right)^2, 
\tag{73}
\]
where we note that \( \sum_N Q_N S(N) = m\langle \bar{N} \rangle \) and \( b_N \) are positive numbers, gives
\[
\sum_N Q_N (\Delta \theta_N)^2 \geq \frac{\left( \sum_N Q_N \sqrt{b_N} \right)^4}{(m\langle \bar{N} \rangle)^2}. 
\tag{74}
\]
Finally, by using Eqs. (65) and (74), the sensitivity of the estimator can be bounded by
\[
(\Delta \theta)^2 \geq \sum_N Q_N (\theta_N - \bar{\theta})^2 + \frac{\left( \sum_N Q_N \sqrt{b_N} \right)^4}{(m\langle \bar{N} \rangle)^2}. 
\tag{75}
\]
This is the main result of this section. The first term in Eq. (75) is always positive and is characteristic of phase estimation with probe states of a non-fixed number of particles. It is equal to zero if and only if \( \Theta_N = \Theta \) for all possible sequences \( N \). Since sequences with \( m \) values of the same total number of particles \( N \) are possible, the above condition implies that the mean value of the estimator is the same (and equal to \( \Theta \)) in each fixed-\( N \) subspace. Furthermore, a convenient situation is to have an unbiased estimator \( \bar{\Theta} = \theta \) for all values of \( m \). In this case (assuming that the first term in Eq. (75) is equal to zero, \( \bar{\Theta}_N = \theta \) for all possible sequences \( N \)), we have [17]
\[
\Delta \theta \geq \frac{1}{m\langle \bar{N} \rangle}. 
\tag{76}
\]
We recall that this holds when the estimator is unbiased in each fixed-\( N \) subspace and for all the values of \( m \). If this does not hold, the more general, but less conclusive, inequality (75) can be used.

### B. Some considerations about the Heisenberg limit for states and POVMs with number coherences

In this subsection we show that the bound \( 1/m\langle \bar{N} \rangle \) applies in the fully coherent situation at least in the central limit.

As discussed in Sec. IV, the optimal quantum Cramér-Rao bound is \( \Delta \theta_{QCR} = 1/\sqrt{m\text{Tr}[\rho_{coh}\bar{N}^2]} \), which is uniquely saturated by a probe given by superpositions of pure NOON states of the form \( |\psi\rangle = \sum_N \sqrt{Q_N} |\text{NOON}_n\rangle \) [see discussion after Eq. (43)]. Since \( \langle\text{NOON}_m|\hat{J}_n|\text{NOON}_n\rangle = 0 \) for any \( N \), the QFI can be written, in this case, as \( F_Q = 4\langle\hat{J}_n^2\rangle \). In addition, since the operator \( \hat{J}_n \) commutes with \( \bar{N} \), off-diagonal terms \( N \neq N' \) in the density matrix \( [\text{NOON}_m]|\text{NOON}_n\rangle \) do not play any role in the calculation of the Cramér-Rao bound. Hence a mixture \( \sum_N Q_N|\text{NOON}_n\rangle\langle\text{NOON}_n| \) does not influence the calculation of the Cramér-Rao bound. This is the main result of this section. The first term in Eq. (75) is always positive and is characteristic of phase estimation with probe states of a non-fixed number of particles. It is equal to zero if and only if \( \Theta_N = \Theta \) for all possible sequences \( N \). Since sequences with \( m \) values of the same total number of particles \( N \) are possible, the above condition implies that the mean value of the estimator is the same (and equal to \( \Theta \)) in each fixed-\( N \) subspace. Furthermore, a convenient situation is to have an unbiased estimator \( \bar{\Theta} = \theta \) for all values of \( m \). In this case (assuming that the first term in Eq. (75) is equal to zero, \( \bar{\Theta}_N = \theta \) for all possible sequences \( N \)), we have [17]
\[
\Delta \theta \geq \frac{1}{m\langle \bar{N} \rangle}. 
\tag{76}
\]
We recall that this holds when the estimator is unbiased in each fixed-\( N \) subspace and for all the values of \( m \). If this does not hold, the more general, but less conclusive, inequality (75) can be used.

### C. Overview of the recent literature on the Heisenberg limit

The comparison between our results and the recent literature deserves some discussion. We recall that our definition of Heisenberg limit, Eq. (5), holds for two-mode transformations and unbiased estimators. It does not apply to states and POVM with number coherences outside the central limit, for which no conclusive results has been obtained so far. A summary of our findings is reported in Table II. In the literature, the problem of defining the Heisenberg limit for states and POVMs with number coherences has been tackled with different techniques which we briefly discuss below. Overall, there is a general strong indication that Eq. (5) is the general form of Heisenberg limit. While the literature leaves open the possibility to overcome the bound \( 1/m\langle \bar{N} \rangle \) at specific phase values (called “sweet spots”, see below), there is no proposal showing convincing evidences of sub-Heisenberg uncertainties.

Before presenting an overview of the literature, it is
important to recall here that there are two models of phase estimation: i) The first model assumes that the phase to be estimate is a nonrandom unknown quantity. This is the framework discussed in this manuscript. It assumes that we can collect an arbitrary number of sequences \( \varepsilon = \{\varepsilon_1, \varepsilon_2, \ldots, \varepsilon_m \} \) of measurements while keeping fixed the (unknown) phase shift in the apparatus. The phase sensitivity is given by the variance of the estimator \( \Theta(\varepsilon) \) (see Sec. II F):

\[
(\Delta \Theta)^2 = \int d\varepsilon P(\varepsilon|\theta)[\Theta(\varepsilon) - \hat{\Theta}(\theta)]^2,
\]

where \( \Theta(\theta) \) is the \( \theta \)-dependent mean value of the estimator. ii) The second model assumes that the phase is a random variable with a probability distribution \( P(\theta) \) called “the prior”. Parameter estimation based on this model is referred to as Bayesian estimation [74]. In this case, each sequence \( \varepsilon \) of \( m \) measurements is obtained with a phase shifts randomly varying with a probability \( P(\theta) \). The phase sensitivity is defined as the weighted mean square error

\[
(\Delta \Theta)^2_{\text{bay}} = \int d\theta \int d\varepsilon P(\varepsilon, \theta)[\Theta(\varepsilon) - \hat{\Theta}(\theta)]^2,
\]

where \( P(\varepsilon, \theta) = P(\varepsilon|\theta)P(\theta) \) is the joint probability distribution of phase \( \theta \) and experimental measurements \( \varepsilon \).

1. Sweet spot phase estimation

Let us consider here the estimation of a fixed phase shift with a state and POVM with number coherences. In this case the Cramér-Rao is the sole sensitivity bound. At certain phase values (indicated as “sweet spots” in Ref. [34]) it can be arbitrary small when fixing the average number of particles \( \langle N \rangle \) in the state. Nevertheless, in Ref. [34] it is shown that the sum of sensitivities calculated at two nearby phase shifts, \( \theta_1 \) and \( \theta_2 \), is bounded when the phases are sufficiently far apart. For unbiased estimators, the inequality [34]

\[
\frac{(\Delta \Theta)_{\theta_1} + (\Delta \Theta)_{\theta_2}}{2} \geq \frac{\kappa}{m(\langle \hat{H} \rangle - H_0)}
\]

holds, where \( \hat{H} \) is the generator of phase shift (the phase encoding transformation \( e^{-i\hat{H} \theta} \) is assumed), \( H_0 \) is the minimum eigenvalue of \( \hat{H} \) populated in the probe state. The maximum value of \( \kappa \) is 0.074 reached when \( |\theta_1 - \theta_2| \geq 0.83/m(\langle \hat{H} \rangle - H_0) \). In the special (which yet might be nonoptimal) case when the phase sensitivity \( (\Delta \Theta)_{\theta} \) does not depend on \( \theta \), Eq. (79) implies \( (\Delta \Theta)_{\theta} \geq \kappa/m(\langle \hat{H} \rangle - H_0) \) [34]. These results imply that the generator of phase shift to have a discrete spectrum and a finite lowest eigenvalue [34]. The bound (79) thus holds, for instance, for single-mode phase estimation, when the generator of phase shift is the number of particles operator, \( \hat{N} \). Equation (79) does not hold for the two mode case unless one imposes a bound on the total number of particles distribution. It should also be noticed that the bound found in Ref. [34] refers to the mean square fluctuation of the estimator with respect to the true phase values. It coincides to Eq. (77) only if the estimator is unbiased. For biased estimators, the bound (79) does not hold.

2. Bayesian bounds

Several works [29–33] have discussed the Heisenberg limit within the framework Bayesian phase estimation, i.e. when the phase sensitivity is averaged over the prior, Eq. (78). This approach might be considered as a generalisation of the averaging over two phases discussed above [34]. In this case, the Heisenberg limit is found by making use of suitable Bayesian bounds. Using the Ziv-Zakai (Bayesian) bound [74] in the “low prior information regime” (e.g. when \( P(\phi) \) is uniform a phase interval sufficiently wider than \( 1/m(\langle \hat{H} \rangle) \)) it was possible to demonstrate that [29, 30]

\[
(\Delta \Theta)_{\text{bay}} \geq \frac{\alpha}{m(\langle \hat{H} \rangle)},
\]

where \( \alpha \) is a constant [29, 30] (\( \alpha = 0.1548 \) for an uniform prior distribution [35]). In the opposite regime, when the width of \( P(\phi) \) is smaller than \( 1/m(\langle \hat{H} \rangle) \), the phase uncertainty is essentially determined by the prior distribution [29, 35]. In this case, sub-Heisenberg uncertainties are possible but ineffective (i.e. the estimation process does not bring more information than a random guess of the phase within the prior \( P(\theta) \) itself [29]). In Refs. [29, 30] the bound (80) was demonstrated by assuming \( \hat{H} \) to have a finite lower bound in the spectrum, as in the single-mode case with \( \hat{H} = \hat{N} \). The extension of Eq. (80) to unbounded Hamiltonians (and thus when \( \hat{H} = \hat{J}_n \)) is discussed in [35].

In Refs. [31–33], using an entropic uncertainty relation, it was possible to show that

\[
(\Delta \Theta)_{\text{bay}} \geq \frac{\beta}{m(\langle |\hat{H} - h| \rangle)},
\]

where \( h \) is an arbitrary eigenvalue of \( \hat{H} \), which can have a discrete or continuous spectrum [33], and \( \beta \), depending

| POVM with coh. | POVM without coh. |
|----------------|-------------------|
| \( \rho_{m} \) with coh. | \( \Delta \theta \geq \Delta \theta_{\text{CR}} \) | \( \Delta \theta \geq \Delta \theta_{\text{IL}} \) |
| \( \rho_{m} \) without coh. | \( \Delta \theta \geq \Delta \theta_{\text{IL}} \) | \( \Delta \theta \geq \Delta \theta_{\text{IL}} \) |

Table II: Table summarizing the fundamental bounds of phase sensitivity discussed in this manuscript. For states and/or POVM without number coherence, the Heisenberg limit is given by the competition of two bounds [see Eq. (5)], as explained in Sec. VI. For general POVMs and states with number-coherences (i.e. for U(2) transformations) only the Cramér-Rao bound applies. In this case and for SU(2) transformations, the Heisenberg limit Eq. (5) holds at least in the central limit, as discussed in Sec. VI.B.
on the prior distribution \(P(\theta)\), can be arbitrarily small for a sufficiently narrow prior (\(\beta = 0.559\) for a completely random phase shift in a 2\(\pi\) interval [31]). The derivation of Eq. (81) does not require \(\hat{H}\) to be discrete, have integer eigenvalues or have a lowest eigenvalue [33]. In particular, the bound applies for two-mode operators [32], i.e. when \(\hat{H} = \hat{J}_n\). In this case, we have \(\langle \psi \big| \hat{J}_n \big| \psi \rangle = \sum_N \sum_{\mu=-N/2}^{N/2} |\mu| Q_{N,\mu}^2\), where \(-N/2 \leq \mu \leq N/2\) are eigenvalues of \(\hat{J}_n\) with eigenstate \(|N,\mu\rangle\) and \(|\psi\rangle = \sum_N \sum_{\mu=-N/2}^{N/2} Q_{N,\mu}|N,\mu\rangle\) is a state with number coherences. Using \(|\mu| \leq N/2\) we obtain \(|\langle \hat{J}_n \rangle| \leq \langle \hat{N} \rangle/2\) and thus, from Eq. (81), \(\delta\phi \geq \beta/m\langle \hat{N} \rangle\).

3. Proposal by Rivas and Luis

Reference [25] discusses a single-mode phase estimation reaching, at specific phase values, a phase uncertainty arbitrarily smaller than \(1/m\langle \hat{N} \rangle\). This claim is the result of a calculation of the Fisher information for states with strong coherences with the vacuum (see also the example in Sec. V A 2). Rivas and Luis argue that the maximum likelihood estimator might reach an arbitrary small phase uncertainty [25]. Results and claims similar to the one of Ref. [25] can be found in the early literature [5–7]. The bounds (80) and (81) do not apply to this case and therefore there are no analytical results in the literature that forbid the conclusions of Ref. [25] (and also of [5–7]). A detailed numerical analysis of the estimation protocol proposed in Ref. [25] can be found in [26], showing no violation of the Heisenberg limit. It is shown [26] that the number of measurements needed to saturate an arbitrary small Cramér-Rao bound is so large that the Heisenberg limit \(\Delta \theta = 1/m\langle \hat{N} \rangle\) is not overcome. Analogous conclusions were reported in Ref. [8], showing no violation of the Heisenberg limit for the proposals [5–7].

D. Examples

1. Example: biased estimator

We recall once again that the demonstration of Eq. (5) reported in Sec. VI A requires the estimator to be unbiased in each fixed-\(N\) subspace. If this is not the case, the bound \(1/m\langle \hat{N} \rangle\) can be violated. This is explicitly shown in the following example. Consider the state

\[
\hat{\rho} = (1 - p) |0,0\rangle\langle 0,0 | + p |\psi_M\rangle\langle \psi_M |,
\]

where \(|\psi_M\rangle\) is, for instance, a NOON state of \(M\) particles, \(|\psi_M\rangle = (|M,0\rangle + |0,M\rangle)/\sqrt{2}\). The average number of particles is \(\langle \hat{N} \rangle = pM\). The QFI is

\[
F_Q[\hat{\rho}, \hat{J}_n] = pF_Q[|\psi_M\rangle, \hat{J}_n] = pM^2 = \frac{\langle \hat{N} \rangle^2}{p},
\]

leading to the quantum Cramér-Rao bound

\[
(\Delta\theta_{QCR})^2 = \frac{1}{mF_Q[\hat{\rho}, \hat{J}_n]} = \frac{p}{m\langle \hat{N} \rangle^2}. \tag{84}
\]

We assume to have an estimator such that [75]

\[
\Theta(\varepsilon) = \begin{cases} 0 & \text{if } N = 0, \\ \bar{\Theta}(\varepsilon)/p & \text{if } N = M.
\end{cases}
\]

where \(\varepsilon\) is the result of a possible measurement in the fixed-\(N\) subspace and \(\bar{\Theta}(\varepsilon)\) is an arbitrary unbiased estimator. The estimator is biased on each \(N\) subspace but it is globally unbiased, \(\Theta = \bar{\theta}\). Let us consider a single measurements \((m = 1)\), the standard deviation of the estimator is given by Eq. (65)

\[
(\Delta\theta)^2 = \sum_N Q_N (\bar{\theta}_N - \bar{\theta})^2 + \sum_N Q_N (\Delta\theta_N)^2 = \frac{1 - p}{p} \theta^2 + \frac{(\Delta\bar{\theta})^2}{p} \geq \frac{1 - p}{p} \theta^2 + \frac{1}{pF_Q[|\psi_M\rangle, \hat{J}_n]} \geq \frac{1 - p}{p} \theta^2 + \frac{p}{\langle \hat{N} \rangle^2}. \tag{85}
\]

The first term highlights the role of \(\theta = 0\) as a sweet spot for the phase estimation. If \(\theta = 0\) we may have a violation of Eq. (5) – by an arbitrary small factor \(p\) – due to the fact that the estimator is biased in each fixed-\(N\) subspace.

2. Example: Two-mode SSW state

In 1989 Shapiro, Shephard and Wong [5–7] proposed a state (hereafter indicated as SSW state) that can be used to overcome the limit \(\Delta \theta = 1/\langle \hat{N} \rangle\) in a single-mode phase estimation. It was then showed by Braunstein et al. [8], with a maximum likelihood analysis, that the SSW state does not allow to overcome \(\Delta \theta = 1/m\langle \hat{N} \rangle = 1/\langle \hat{N}_{tot} \rangle\) in the central limit. The analysis of [8] emphasizes the non-trivial role of the number of repeated measurements, \(m\). We here extend the SSW state to two modes and study how our bounds apply to this case.

The SSW state can be straightforwardly extended to two-mode as, for instance, a superposition of Twin-Fock states:

\[
|\psi_{SSW} \rangle = \sum_{n=0}^M \frac{A}{n + 1} |n,n \rangle, \tag{86}
\]

where \(A\) is a normalization constant, \(M\) is a cut-off and \(|n,n \rangle\) is a Twin-Fock state [10] of \(2n\) particles. Using the
results of Refs. [7, 8], we have
\[ A^2 = \frac{6}{\pi^2} + \frac{36}{\pi^4(M+1)} + O\left(\frac{1}{M^2}\right), \]
\[ \langle \hat{N}^2 + 1 \rangle = \frac{6}{\pi^2} [\gamma + \ln(M+1)] + O\left(\ln M / M\right), \]
\[ \langle \left(\hat{N}^2 + 1\right)^2 \rangle = A^2(M+1), \]
where \( \gamma \approx 0.57721 \) is the Euler’s constant. To the leading order in \( M \), the QFI is given by
\[ F_Q \left[ |\psi_{SSW}\rangle, \hat{J}_y \right] \approx \frac{12}{\pi^2} (M+1) \approx \frac{12}{\pi^2} \epsilon^{-\gamma} e^{-\frac{1}{2}(\frac{\hat{N}^2}{2}+1)} \]
The state Eq. (86), similarly to its one-mode counterpart [8], has a QFI that scales exponentially with \( \langle \hat{N} \rangle \), diverging for \( M \rightarrow \infty \). The Quantum Cramér-Rao bound can thus be arbitrarily small. What is the optimal sensitivity achievable with the SSW state, Eq. (86)? According to our results, if the phase is estimated with a POVM without coherences, the Heisenberg limit is given by Eq. (5), which becomes,
\[ \Delta \theta_{HL} = \max \left[ \frac{\pi e^{\frac{1}{2}} e^{-\frac{1}{2}(\frac{\hat{N}^2}{2}+1)}}{2\sqrt{3m}} , \frac{1}{m \langle \hat{N} \rangle} \right] \] (87)
and thus
\[ m_{cl} \geq \frac{\pi^2 \epsilon^{-\gamma} e^{-\frac{1}{2}(\frac{\hat{N}^2}{2}+1)}}{12 \langle \hat{N} \rangle^2}. \] (88)
We can obtain an arbitrary high sensitivity but i) it is always larger than \( 1/m \langle \hat{N} \rangle \) (second term in Eq. (87)) and, according to Eq. (88), ii) the central limit is reached for a number of measurements \( m_{cl} \) which diverges for \( \langle \hat{N} \rangle \rightarrow \infty \). This conclusion holds for any arbitrary unbiased estimator, even though the maximum likelihood remains the most relevant example. If the phase is estimated by a POVM with coherences, Eq. (87) holds in the central limit, at least.

3. Example: two-mode squeezed vacuum state

In Ref. [21] it was argued that the two-mode squeezed vacuum state can be used to overcome the Heisenberg limit in a Mach-Zehnder interferometer with parity detection in a single-output. This example is similar to the one discussed above (In Sec. VI D 2) nevertheless it is worth analysing it in details. The two-mode squeezed vacuum state is:
\[ |\psi\rangle = \sum_{N=0}^{+\infty} \frac{e^{i\psi N} (\tanh r)^N}{\cosh r} |N, N\rangle , \] (89)
where \( r \) is a squeezing parameter. In optics, it can be experimentally produced by a nondegenerate down-conversion process with a nonlinear crystal. With atoms, a state similar to Eq. (89) can be obtained with spin-dependent collisions in spinor Bose-Einstein condensates. For the state Eq. (89), we have \( \langle \hat{N} \rangle = 2 \sinh^2 r \), \( \langle \hat{N}^2 \rangle = 2 \langle \hat{N} \rangle + 1 \) and \( \langle \Delta \hat{N} \rangle = 2 \sinh^2 2r = \langle \hat{N} \rangle (\langle \hat{N} \rangle + 2) \). For a POVM without number coherences, as the one considered in [21], the Heisenberg limit (5) is
\[ (\Delta \theta)_{HL} = \max \left[ \frac{1}{\sqrt{2m \langle \hat{N} \rangle (\langle \hat{N} \rangle + 1)}}, \frac{1}{m \langle \hat{N} \rangle} \right]. \] (90)
This can be compared to the quantum Cramér-Rao bound for rotations around the \( y \) axis, [corresponding to the Mach-Zehnder interferometer transformation, with quantum Fisher information \( F_Q = 4(\Delta \hat{J}_y)^2 \):
\[ (\Delta \theta)_{QCR} = \frac{1}{\sqrt{m \langle \hat{N} \rangle (\langle \hat{N} \rangle + 2)}}. \] (91)
In Ref. [21] the sensitivity was calculated with an error propagation formula and, at \( \theta = 0 \), it matches Eq. (91). Equation (91) overcomes \( (\Delta \theta) = 1/\sqrt{m \langle \hat{N} \rangle} \) that is often indicated as the Heisenberg limit [21]. While this appears as the natural extension of Eq. (2) to the case of fluctuating number of particles (by replacing \( N \) with \( \langle \hat{N} \rangle \)), it is not a fundamental bound.

In the large-\( m \) limit Equation (91) is always (for the interesting case \( \langle \hat{N} \rangle > 1 \)) smaller than the Heisenberg limit Eq. (90). The two-mode squeezed vacuum state is very useful to overcome the shot noise limit but it does not really surpass the Heisenberg limit (even if POVMs with number coherences are used). The saturation of the Heisenberg limit in the large \( m \) limit Eq. (90) can be obtained with the superposition of NOON states
\[ \sum_{N=0}^{+\infty} \frac{e^{i\psi N} (\tanh r)^N}{\cosh r} |N,0\rangle_{+} |0,N\rangle_{-}. \]
In the small-\( m \) limit (for \( m = 1 \) in particular), we find \( (\Delta \theta)_{QCR} \leq 1/\langle \hat{N} \rangle \), violating Eq. (90) [35]. The apparent contradiction between our results and Ref. [21] is solved by noticing that Eq. (91) is known to be saturable (by the maximum likelihood estimator) only in the large-\( m \) limit. There is no guarantee (and not shown in [21]) that an unbiased estimator saturating Eq. (91) for small-\( m \) values can be found. The results of our manuscript show that such an unbiased estimator cannot exist.

VII. CONCLUSIONS

Phase estimation will likely become the first large scale technology where classical bounds are overcome by quantum means. It is therefore an interesting problem to set the fundamental quantum bound (generally indicated as the Heisenberg limit) which will limit the sensitivity of future phase estimation experiments. In this manuscript we have set the Heisenberg limit, Eq. (5), under relevant experimental conditions: fluctuating number of particles, absence of number coherence in the probe state and/or
in the measurement strategy and unbiased estimations. In this case we have also demonstrated that particle entanglement (we have extended the concept of particle entanglement to the case of state with fluctuating number of particles) is necessary to overcome the classical – shot noise – phase uncertainty. If the probe state and the output measurement contain coherences between different number of particles, it is not possible to establish a relation between entanglement and phase sensitivity and the phase sensitivity bound Eq. (5) can only be set in the central limit.

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APPENDIX

Appendix A: general two-mode transformations

It is possible to write the general transformation (14) as the product of four matrices [59]:

\[
U = \begin{bmatrix}
  e^{-i\phi_0} & 0 & 0 & 0 \\
  0 & e^{-i\phi_0} & 0 & 0 \\
  e^{-i\psi/2} & 0 & e^{i\psi/2} & 0 \\
  0 & e^{-i\psi/2} & 0 & e^{i\psi/2}
\end{bmatrix} \times \begin{bmatrix}
  \cos \frac{\theta}{2} & -\sin \frac{\theta}{2} & 0 & 0 \\
  -\sin \frac{\theta}{2} & \cos \frac{\theta}{2} & 0 & 0 \\
  0 & 0 & e^{-i\phi/2} & 0 \\
  0 & 0 & 0 & e^{i\phi/2}
\end{bmatrix},
\]

(92)

where \( \phi_\psi = (\psi + \phi)/2 \) and \( \phi_\phi = (\psi - \phi)/2 \). Using the Jordan-Schwinger representation of angular momentum, we have [3],

\[
\begin{align*}
U_x &= \begin{bmatrix}
  \cos \frac{\theta}{2} & -i \sin \frac{\theta}{2} & 0 & 0 \\
  -i \sin \frac{\theta}{2} & \cos \frac{\theta}{2} & 0 & 0 \\
  0 & 0 & e^{-i\phi/2} & 0 \\
  0 & 0 & 0 & e^{i\phi/2}
\end{bmatrix} \leftrightarrow \hat{U}_x = e^{-i\hbar \hat{J}_z}, \\
U_y &= \begin{bmatrix}
  \cos \frac{\theta}{2} & -\sin \frac{\theta}{2} & 0 & 0 \\
  \sin \frac{\theta}{2} & \cos \frac{\theta}{2} & 0 & 0 \\
  0 & 0 & e^{-i\phi/2} & 0 \\
  0 & 0 & 0 & e^{i\phi/2}
\end{bmatrix} \leftrightarrow \hat{U}_y = e^{-i\hbar \hat{J}_y}, \\
U_z &= \begin{bmatrix}
  e^{-i\phi/2} & 0 & 0 & 0 \\
  0 & e^{i\phi/2} & 0 & 0 \\
  0 & 0 & e^{-i\phi} & 0 \\
  0 & 0 & 0 & e^{i\phi}
\end{bmatrix} \leftrightarrow \hat{U}_z = e^{-i\hbar \hat{J}_z},
\end{align*}
\]

(93-95)

and using \( e^{i\phi_0 \hat{N}} \hat{a} e^{-i\phi_0 \hat{N}} = e^{-i\phi_0 \hat{\alpha}} \), Eq. (14) can be associated to

\[
\hat{U}(\phi_0, \theta) = e^{-i\phi_0 \hat{N}} e^{-i\phi \hat{J}_x} e^{-i\phi \hat{J}_y} e^{-i\phi \hat{J}_z},
\]

(96)

By using the Euler-Rodrigues formula, Eq. (96) can be rewritten as

\[
\hat{U}(\phi_0, \theta) = e^{-i\phi_0 \hat{N}} e^{-i\theta \hat{J}_n},
\]

(97)

where

\[
\cos \frac{\theta}{2} = \cos \frac{\phi + \psi}{2} \cos \frac{\phi - \psi}{2},
\]

(98)

and \( \hat{J}_n = \alpha \hat{J}_x + \beta \hat{J}_y + \gamma \hat{J}_z \), with

\[
\begin{align*}
\alpha &= \frac{\sin \frac{\theta}{2} \sin \frac{\phi - \psi}{2}}{\sqrt{1 - \cos^2 \frac{\theta}{2} \cos^2 \frac{\phi + \psi}{2}}}, \\
\beta &= \frac{\sin \frac{\theta}{2} \cos \frac{\phi + \psi}{2}}{\sqrt{1 - \cos^2 \frac{\theta}{2} \cos^2 \frac{\phi + \psi}{2}}}, \\
\gamma &= \frac{\cos \frac{\theta}{2} \sin \frac{\phi + \psi}{2}}{\sqrt{1 - \cos^2 \frac{\theta}{2} \cos^2 \frac{\phi + \psi}{2}}}
\end{align*}
\]

(99-101)

This encompasses, for instance, the beam splitter [Eq. (93), for \( \phi = \pi/2, \psi = -\pi/2 \) and \( \theta = \theta \), Mach-Zehnder [Eq. (94), for \( \phi = 0, \psi = 0 \) and \( \theta = \theta \) and phase shift [Eq. (95), for \( \psi = \theta = 0 \) and \( \phi = \theta \) transformations.

Appendix B: derivation of Eq. (23)

States without number coherences. The incoherent probe Eq. (9) transforms according to Eq. (15) as

\[
\hat{\rho}_{\text{out}}(\phi_0, \theta) = \sum_{N=0}^{+\infty} Q_N \hat{U}(\phi_0, \theta) \hat{\rho}^{(N)} \hat{U}(\phi_0, \theta)^\dagger \\
= \sum_{N=0}^{+\infty} Q_N e^{-i\theta \hat{J}_n} \hat{\rho}^{(N)} e^{i\theta \hat{J}_n},
\]

(102)

as a consequence of \( [\hat{\rho}^{(N)}, \hat{N}] = 0 \). Equation (102) is a function of \( \theta \) and shows that only SU(2) transformations, \( e^{-i\theta \hat{J}_n} \), are relevant for states without number coherence. Equation (23) follows from Eq. (102), independently from the presence of number coherences in the POVM.

POVMs without number coherence. For the case of states with coherences, Eq. (6), and POVM without num-
ber coherences, Eq. (19), we have

\[
P(\varepsilon |N, \theta) = \sum_N \text{Tr} \left[ \tilde{\pi}_N \hat{E}_N(\varepsilon) \tilde{\pi}_N \hat{U}(\phi_0, \theta) \hat{\rho}_\text{coh} \hat{U}(\phi_0, \theta)^\dagger \right]
\]

\[
= \sum_N \text{Tr} \left[ \hat{E}_N(\varepsilon) \hat{U}(\phi_0, \theta) \tilde{\pi}_N \hat{\rho}_\text{coh} \tilde{\pi}_N \hat{U}(\phi_0, \theta)^\dagger \right]
\]

\[
= \sum_N Q_N \text{Tr} \left[ \hat{E}_N(\varepsilon) \hat{U}(\phi_0, \theta) \hat{\rho}(N) \hat{U}(\phi_0, \theta)^\dagger \right]
\]

\[
= \sum_N Q_N P(\varepsilon |N, \theta),
\]

(103)

where \( P(\varepsilon |N, \theta) = \text{Tr}[\hat{E}_N(\varepsilon) e^{-i\theta \hat{J}_N} \hat{\rho}(N) e^{+i\theta \hat{J}_N}] \). To derive this result we have used the commutation relation \([\hat{U}, \tilde{\pi}_N] = 0\) and the \( \tilde{\pi}_N \hat{\rho}_\text{coh} \tilde{\pi}_N = Q_N \hat{\rho}(N) \) where \( \hat{\rho}(N) \) is a density matrix defined on the fixed-N subspace. We have also used \( \tilde{\pi}_N \hat{U}(\phi_0, \theta) \tilde{\pi}_N = e^{-i\theta \hat{J}_N} e^{\theta \hat{J}_N} \) due to the fact that \( \hat{J}_N = \hat{g}_N \hat{J}_N \) where \( \hat{g}_N \) acts on the fixed-N subspace. When POVM as in Eq. (19) are used, we can therefore conclude, from Eq. (103), that only SU(2) transformations are relevant and number coherences in the probe state do not play any role.

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