Charging Strategy for Electric Vehicles Considering Consumer Psychology and Trip Chain

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As a kind of movable storage device, the electrical vehicles (EVs) are able to support load shaving through orderly charging. The existing researches mostly focus on the design of EVs charging control technology with little consideration of trip-chain-based consumer psychology of EV owners. To fill this gap, this article proposes a price-based orderly charging strategy for EVs considering both consumer psychology and trip chain. Then, the load shaving problem is transformed into a multiobjective optimization problem, to minimize peak-to-valley difference and network loss. A time-of-use price optimization model based on consumer psychology is established to describe the charging behavior of EV owners influenced by electricity price. Finally, the examples verify the feasibility of the proposed strategy by comparing the impact of EVs connected to grid under different ratios, different load transfer rates, and different scenarios.

Keywords: electrical vehicles, consumer psychology, trip chain, time-of-use price, peak shaving and valley filling

INTRODUCTION

Electric vehicle (EV) is a zero-emission and low-emission green transportation tool, whose large-scale promotion can effectively alleviate the increasingly severe social problems such as energy crisis and environmental pollution today. Therefore, it has received extensive attention from all walks of life. Monte Carlo (MC) simulation is a stochastic simulation method based on probability and statistical theory. It is a method that uses random numbers to solve many calculation problems, which connects the problem to be solved with a certain probability model, and realizes statistical simulation or sampling with an electronic computer to obtain an approximate solution.

The development of vehicle-to-grid (V2G) technology has made EVs a mobile energy storage device with functions including "peak shaving and valley filling," frequency modulation, and increasing reserve capacity (Cheng et al., 2014; Shafie-khah et al., 2016; Tang and Wang, 2015). Meanwhile, through proper scheduling of EVs charging and discharging, the ability of power system to absorb wind power, photovoltaic power, and other intermittent renewable energy can be enhanced (Ashtari et al., 2012; Li and Zhang, 2012; Xing et al., 2021).

As for the EVs charging and discharging control strategy in distribution network, there have been discussions in various directions at home and abroad. The trip data of household vehicles in the United States are analyzed by Rautiainen et al. (2012), where it is assumed that EVs and fuel vehicles have the same trip rules. Probabilistic models of trip start and end time, daily mileage, and charging characteristics are established through distribution fitting, and MC sampling is adopted to estimate EVs charging load distribution. Under the premise of considering constraints of EVs charging demand, a charging and discharging control strategy for EVs participating in power system...
frequency modulation services is proposed by Liu et al. (2013). For a three-phase unbalanced power distribution system, a mixed-integer linear programming model for orderly charging of EVs with the goal of minimizing power generation costs is established by Franco et al. (2015). A mixed integer programming model for EVs charging and discharging based on distributed control is established by Xing et al. (2016), where an efficient solution method for the characteristics of typical load curves is proposed. An optimal charging model with the minimum network loss within a given period as the objective function is established by Clement-Nyns et al. (2010), where impact of a large number of EVs on distribution system is analyzed from the perspective of network loss and voltage offset. The theory of traffic trip chain is introduced into the study of EVs load forecasting by Guo et al. (2014), Tang and Wang (2016), where a dynamic trip chain is assigned to each EV in the area. It characterizes the all-weather trip trajectory and driving law of EVs, and simulates the trip and charging behavior of EVs.

In the above-mentioned references, the main focus is on the design of EVs charging control technology with little consideration of trip-chain-based consumer psychology of EV owners. This article creatively considers both consumer psychology and trip chain, and proposes a price-based orderly charging strategy for EVs. First, based on the trip characteristics and charging behavior of EVs, the two characteristic variables of EV’s daily mileage and daily return time are modeled. Second, the load shaving problem is transformed into a multiobjective optimization problem, to minimize peak-to-valley difference and network loss. Then, a time-of-use price optimization model based on consumer psychology is established to describe the charging behavior of EV owners influenced by electricity price. Finally, the examples are provided to compare the impact of EVs connected to grid under different ratios, different load transfer rates, and different scenarios, whose results verify the feasibility of the proposed strategy.

ESTABLISHMENT OF EVS LOAD MODEL

Classification of EVs

The EVs load model is closely related to the type, charging characteristics, and trip demand of EVs; meanwhile, the type of EVs directly determines the required charging characteristics and trip demand. According to different uses, EVs can be divided into different types such as electric buses, electric cars, and electric taxis. Electric taxis need to change shifts frequently, whose daily mileage, charging time, and location are relatively random, so their charging controllability is relatively weak. Therefore, this article mainly investigates two types of EVs, electric buses and electric cars.

Trip Chain and its Characteristic Variables

The trip chain refers to the connection form of different trip purposes in a certain time sequence to complete one or several activities. It is generally described as the process of a user starting from home and returning home during a scheduling period. During the process, the user will trip several times, and each time includes driving process and destination stopping process, which is the ith drive and the ith stop \((i = 1, 2, \ldots, n)\) in Figure 1.

The trip chain includes time chain and space chain. Similarly, its characteristic variables can also be divided into two categories.

1) Space chain characteristic variables, which describe the transfer of user trip in the space during scheduling period, including daily mileage, daily parking times, etc. This article mainly considers the daily mileage \(D_{dr}\) of EVs, as shown in Figure 1, \(D_{dr} = \sum d_i\).

According to reference (Sun et al., 2020; Heinisch et al., 2021), the daily mileage of buses conforms to log-normal distribution, and its probability density function is

\[
f_D(D_{dr}) = \frac{1}{\sqrt{2\pi\sigma_b}} \exp \left( -\frac{(\ln D_{dr} - \mu_b)^2}{2\sigma_b^2} \right)
\]

where \(D_{dr}\) is the daily mileage of buses, \(\mu_b\) is the expected value of the daily mileage of buses, and \(\sigma_b\) is their standard deviation.

According to reference (Sun et al., 2020; Heinisch et al., 2021), the daily mileage of cars conforms to log-normal distribution, and its probability density function is

\[
f_D(D_{dc}) = \frac{1}{\sqrt{2\pi\sigma_cD_c}} \exp \left( -\frac{(\ln D_{dc} - \mu_c)^2}{2\sigma_c^2} \right)
\]

where \(D_{dc}\) is the daily mileage of cars, \(\mu_c\) is the expected natural logarithm value of the daily mileage of cars, and \(\sigma_c\) is their standard deviation.

2) Time chain characteristic variables, which describe the patterns of user trip in the time during scheduling period, including daily return time, daily trip time, etc. This article
mainly considers the daily return time $T_{re}$ of EVs, as shown in Figure 1, $T_{re} = T_{mc,n}$.

According to reference (Muratori et al., 2018; Dagdougui et al., 2020), the daily return time of buses and cars both conform to normal distribution, and their probability density functions are

$$f_T(T_{re}) = \begin{cases} 
\frac{1}{\sqrt{2\pi} \sigma_T} \exp \left[ -\frac{(T_{re} + 24 - \mu_T)^2}{2\sigma_T^2} \right] & 0 < T_{re} \leq \mu_T - 12 \\
\frac{1}{\sqrt{2\pi} \sigma_T} \exp \left[ -\frac{(T_{re} - \mu_T)^2}{2\sigma_T^2} \right] & \mu_T - 12 < T_{re} \leq 24 
\end{cases}$$

(3)

where $T_{re}$ is the daily return time of EVs, $\mu_T$ is the expected value of the daily return time of EVs, and $\sigma_T$ is their standard deviation.

The probability density functions of characteristic variables of EVs’ daily mileage and daily return time are taken to carry out MC simulation. Then the distribution of the above random variables is taken as input. Starting from the time of first trip, data are extracted sequentially based on the normal distribution of each variable, to generate a complete trip chain.

In the trip chain, under the condition that some variables are known, the remaining variables can be calculated. It is assumed that EV is fully charged before first trip during the scheduling period, that is, the state of charge (SOC) is 1, so its SOC at the beginning of charging is

$$S_{start} = 1 - \frac{D_{eb} \cdot E_{100}}{100 \cdot C_{battery}}$$

(4)

where $D_{eb}$ is the daily mileage of EV, $E_{100}$ is its energy consumption per 100 km, and $C_{battery}$ is its battery capacity.

It is assumed that EV has enough time to fully charge at night, and its charging speed can also meet the above requirements, so its charging duration is

$$T_{ch} = \frac{D_{eb} \cdot E_{100}}{100 \cdot P_{ch} \cdot \eta_{ch}}$$

(5)

where $P_{ch}$ is the charging power of EV and $\eta_{ch}$ is its charging efficiency.

**ESTABLISHMENT OF CONSUMER PSYCHOLOGY MODEL**

**Price Response Model Based on Consumer Psychology**

The user’s response to electricity prices is embodied in adjusting own electricity usage periods according to price signals, changing electricity usage patterns by time periods, and so on. The price elasticity of electricity demand is the relative change in electricity consumption caused by the relative change in electricity price, which is

$$e = \frac{\Delta q}{q} \left( \frac{\Delta p}{p} \right)^{-1}$$

(6)

where $\Delta q$ and $\Delta p$ are the increment of electricity consumption and price respectively; $q$ and $p$ are the electricity consumption and price respectively before the electricity price change.

However, the user response model based on the electricity demand price elasticity matrix cannot reflect consumer psychology. There is a minimum noticeable difference in the stimulus of selling electricity price to users. When electricity price is less than the minimum noticeable difference, users basically have no response, and when selling electricity price is greater than an upper limit, users will no longer provide more transferable loads, whose response capacity is approaching saturation (Zhou et al., 2016). Therefore, this section builds a demand response (DR) model for electricity prices based on consumer psychology, and the load transfer rate from the peak to valley period is shown in Figure 2.

For a certain user, the EV load transfer rate from the peak to valley period is

$$\lambda_{EV} = \begin{cases} 0 & 0 \leq \Delta p_{pv} \leq a_{EV} \\
\frac{K_{EV}^2 (\Delta p_{pv} - a_{EV})}{\lambda_{EV, max}} & a_{EV} < \Delta p_{pv} \leq \frac{\lambda_{EV, max}}{K_{EV}} + a_{EV} \\
\lambda_{EV, max} & \Delta p_{pv} \geq \frac{\lambda_{EV, max}}{K_{EV}} + a_{EV} \end{cases}$$

(7)

where $\Delta p_{pv} = p_{EV}^p - p_{EV}$ is the peak-to-valley price difference; $\lambda_{EV, max}$ is the upper limit of EV load transfer rate; $a_{EV}$ is the upper limit of dead zone of EV load transfer rate to peak-to-valley price difference; $K_{EV}$ is the slope of its linear zone. Since buses are more sensitive to load changes than cars, $K_{EV}$ of buses is greater than that of cars.

Under the influence of time-of-use price, EV load will shift from peak to valley period. Given the value of $\lambda_{EV}$, the EV load in each period is

$$P_{t}^{EV} = (1 - \lambda_{EV})P_{t}^{EV, base} + \lambda_{EV}P_{t}^{EV, optimal} \quad t \in T$$

(8)

where $P_{t}^{EV, base}$ is the baseline load at time $t$ when EVs do not adopt any orderly charging control strategy; $P_{t}^{EV, optimal}$ is the optimal load at time $t$ after load is completely transferred when the orderly charging control strategy is adopted; $T$ is the scheduling period.

Except for EVs, other loads will also respond to changes in electricity prices. Similarly, the other load transfer rate from peak to valley period is

$$\lambda_{else} = \begin{cases} 0 & 0 \leq \Delta p_{pv} \leq a_{else} \\
\frac{K_{else}^2 (\Delta p_{pv} - a_{else})}{\lambda_{else, max}} & a_{else} < \Delta p_{pv} \leq \frac{\lambda_{else, max}}{K_{else}} + a_{else} \\
\lambda_{else, max} & \Delta p_{pv} \geq \frac{\lambda_{else, max}}{K_{else}} + a_{else} \end{cases}$$

(9)

where $\lambda_{else, max}$ is the upper limit of other load transfer rate; $a_{else}$ is the upper limit of dead zone of other load transfer rates to peak-to-valley price difference; $K_{else}$ is the slope of its linear zone. Then the other load in each period is

$$P_{t}^{else} = \begin{cases} P_{t}^{else, base} + \lambda_{else, max}P_{t}^{else, ave} & t \in T_p \\
\lambda_{else, max}P_{t}^{else, ave} & t \in T_v \end{cases}$$

(10)
where $P_{t}^{\text{else,base}}$ is the baseline of other load at time $t$; $P_{t}^{\text{else,ave}}$ is the average of other load in the period of time $t$; $T_{p}$ is the peak period; $T_{v}$ is the valley period, $T = T_{p} + T_{v}$.

In summary, the baseline load of distribution network at each period without considering consumer psychology is

$$P_{\text{base},t} = P_{t}^{\text{EV,base}} + P_{t}^{\text{else,base}} \quad t \in T$$

(11)

Considering consumer psychology, the total load of distribution network at each period is

$$P_{t} = P_{t}^{\text{EV}} + P_{t}^{\text{else}} \quad t \in T$$

(12)

**Time-of-Use Price Optimization Model**

**Objective Function**

Taking peak price $\rho_{p}$ and valley price $\rho_{v}$ as decision variables, the problem of EVs charging with consumer psychology is transformed into an optimization problem. As a control variable, time-of-use price will directly determine the performance of peak shaving and valley filling, and then affect peak-to-valley difference, network loss, voltage deviation, and other indicators. By minimizing such indicators, the optimal peak-valley price for distribution network can be determined. The weighted sum of peak-to-valley difference rate and network loss rate of total distribution network load is selected as the multiobjective function, which is

$$\min F_{\text{total}} = \omega_{1} F_{1} + \omega_{2} F_{2}$$

(13)

where $\omega_{i} (i = 1, 2)$ is weight coefficients, which can be set according to actual needs, $\omega_{1} + \omega_{2} = 1$; $F_{i}$ is indicators, as follows:

1) $F_{1}$: Peak-to-valley difference rate, used to measure the improvement of orderly charging and discharging of EVs on load curve, which is

$$F_{1} = \frac{P_{\text{max}} - P_{\text{min}}}{P_{\text{max}}}$$

(14)

where $P_{\text{max}}$ and $P_{\text{min}}$ are the maximum and minimum loads of the distribution network during scheduling period, respectively.

2) $F_{2}$: Network loss rate, used to measure the improvement of orderly charging and discharging of EVs on electricity utilization, which is

$$F_{2} = \frac{\sum_{t \in T} P_{t}^{\text{loss}} \cdot \Delta t}{\sum_{t \in T} P_{t} \cdot \Delta t}$$

(15)

where $P_{t}^{\text{loss}}$ is the network loss at time $t$; $\Delta t$ is the time interval.

**Constraints**

The model needs to meet five types of constraints. Constraints (1)–(2) ensure the operation requirements of distribution network, and constraints (3)–(5) maintain the benefits of EVs’ users to encourage users to follow the strategy to orderly charge.

1) Load change speed constraint

To prevent transferred load from exceeding the regulating capacity of generators, load change at adjacent moments needs to meet

$$-R_{D} \leq P_{t} - P_{t-1} \leq R_{U} \quad t \in T$$

(16)

where $R_{U}$ and $R_{D}$ are the upper and lower limits of load change at adjacent moments, respectively.

2) Load transfer rate constraint

The average price after implementation of time-of-use price is

$$\rho_{pv} = \frac{\sum_{t \in T_{p}} P_{t} \Delta t + \rho_{v} \sum_{t \in T_{v}} P_{t} \Delta t}{\sum_{t \in T} P_{t} \Delta t}$$

(18)

where $\rho_{pv}$ is the average price after implementation of time-of-use price.

The average price before and after implementation of time-of-use price is required to remain unchanged, which is

$\rho_{p} \times P_{\text{max}} + \rho_{v} \times P_{\text{min}} = \rho_{pv} \times P_{\text{max}}$
\[ \rho_0 = \overline{\rho_{pv}} \]  

(19)

where \( \rho_0 \) is the constant price before implementation of time-of-use price.

4) Users charging cost constraint

The charging cost of users before and after implementation of time-of-use price are respectively

\[
\begin{cases}
M_0 = \rho_0 \sum_{t \in T} P_{\text{base}} t \Delta t \\
M_{pv} = \rho_{pv} \sum_{t \in T} P_{t} \Delta t + \rho_v \sum_{t \in T} P_{t} \Delta t
\end{cases}
\]

(20)

Users respond to time-of-use price by changing original electricity consumption habits, whose purpose is to make charging cost not higher than the original one after implementation of time-of-use price, which is

\[ M_0 \geq M_{pv} \]  

(21)

5) Users satisfaction constraint

Generally, the less the load changes, the higher the user satisfaction, so users satisfaction is defined as

\[ S_{\text{user}} = \sum_{t \in T} \varepsilon(t) \left[ 1 - \frac{|P_t - P_{\text{base}}|}{P_t} \right] \]

(22)

\[ S_{\text{user}} \geq S_{\text{user}}^{\text{min}} \]

(23)

where \( S_{\text{user}}^{\text{min}} \) is the minimum value of users satisfaction; \( \varepsilon(t) \) is the satisfaction coefficient of users responding to time-of-use price at time \( t \), which depends on the impact degree of load transfer on users, and satisfies

\[ \sum_{t \in T} \varepsilon(t) = 1 \]

(24)

MODEL SOLVING METHOD

The price response model based on consumer psychology is solved by matlab with MC simulation. The time-of-use price optimization model is solved by matlab with yalmip/gurobi toolboxes, which transforms the original load distribution problem into a large-scale mixed integer programming (MIP) problem. Specifically, on the basis of branch and bound method, outer approximation method and tangent secant method are introduced, which reduces invalid branches in the optimization of binary tree, and finally the optimal solution within tolerance range is obtained.

The power flow and node voltage of distribution network containing EVs are solved by matlab with matpower toolbox, specifically using the standard Newton-Raphson method. The testing process in this article is carried out on Gurobi 9.1.1 and Matpower 7.1.

CASE STUDY

Basic Data and Parameter Settings

In this article, the IEEE-33 node distribution network with buses and cars is used for simulation verification, whose topology is shown in Figure 3.

According to the structure of trip chain and function of plot, the IEEE-33 node distribution network is divided into two functional districts, a residential district and a commercial district. Nodes 1–3, 19–25 are divided into
TABLE 1 | Parameters of EVs.

| Parameters | Buses (commercial district) | Cars (residential district) | Parameters | Buses (commercial district) | Cars (residential district) |
|------------|-----------------------------|-----------------------------|------------|-----------------------------|-----------------------------|
| \( u_b, u_c \) | 10                          | 500                         | \( \mu_f/h \) | 21                          | 19                          |
| \( C_{\text{Battery}}/\text{KWh} \) | 324                         | 60                          | \( \sigma_f/h \) | 1                           | 1                           |
| \( E_\text{EV}/\text{KWh} \) | 140                         | 20                          | \( \lambda_{tv} \) | 23:00~9:00 + 1               | 21:00~7:00 + 1               |
| \( P_{\text{EV}}/\text{KW} \) | 45                          | 14                          | \( \alpha_{v} \) | 0.05                        | 0.05                        |
| \( \rho_{\text{EV}} \) | 0.9                         | 0.9                         | \( K_{\text{EV}}/\text{Y}^{-1} \) | 2.5                         | 1.5                         |
| \( u_b, u_c/\text{km} \) | 170                         | 2.98                        | \( \lambda_{\text{EV}}/\text{V}_{\text{max}} \) | 1.0                         | 0.8                         |
| \( \sigma_{\text{u}}/\text{km} \) | 20                          | 1.14                        | \( \rho_{\text{EV}}/(\text{V}-\text{KWh}^{-1}) \) | 0.6715                      | 0.5483                      |

For other load transfer rates, the \( \sigma \) parameters of buses are set as \( \sigma_{b} = 0.6715 \) and \( \sigma_{c} = 0.5483 \), respectively.

The probability density function of EVs' daily return time and daily mileage is shown in Figure 6. It is assumed that the final arrival of buses during scheduling period are all in commercial district, similarly, that of cars are all in residential district. EVs are only charged after daily returning, which has no effect on distribution network load. It is assumed that each plot contains sufficient charging piles. The influence of location distribution of charging piles on charging behavior and route selection of EVs is not considered.

Based on actual situation, the day-ahead scheduling period with a time interval of 1 h is adopted. The baseline load curves of residential and commercial districts on a typical day in Shenzhen city are selected, as shown in Figure 5. The total load of two functional districts is distributed to each node in proportion.

The parameters of EVs are set as listed in Table 1. Users' parameters are set as \( \frac{R_{\text{EV}}}{R_{\text{p}}_{\text{max}}} = 0.05 \), \( S_{\text{max}} = 0.6 \), \( \epsilon(t) = \frac{1}{20} \), \( \sigma(T) = \frac{1}{25} \), \( \sigma_{\text{EV}} = 1.2 \text{Y}^{-1} \), \( \alpha_{\text{EV}} = 0.15 \), and \( \lambda_{\text{EV}} = 0.39 \), respectively.

According to formula Equations 1–3 and the parameters in Table 1, the probability distributions of daily return time and daily mileage of buses and cars are shown in Figure 6.

Performance of EVs Charging Under Different Proportions

According to the probability density function of EVs’ daily return time and daily mileage, the situation of EVs connected to grid is simulated by MC simulation. It is assumed that EV starts charging immediately when it returns, until its battery is fully charged, which is a kind of disorderly charging strategy. The characteristic variables data of \( n_b \) buses and \( n_c \) cars are obtained by simulation, then the situations when EVs account for 25, 50, and 100% of total number of vehicles are considered respectively. The results are shown in Figure 7.

Enlarging the nonoverlapping part of curves corresponding to different proportions of EVs, it can be seen that: 1) Compared with buses, cars have a greater impact on the load of their district due to their larger number. 2) Since daily return times of buses are already in valley period of commercial district load, if buses start charging immediately when they return, their charging period will coincide with valley period, which has certain “valley filling” effect. 3) Since daily return times of cars are just close to starting time of evening peak period of residential district load, if cars do that, their charging period will coincide with evening peak period, resulting in “peak plus peak” situation.

Performance of EVs Charging Under Different Load Transfer Rates

Taking the load transfer rate as a control variable, simulations are performed on \( n_b \) buses and \( n_c \) cars. Since \( K_{\text{EV}} \) of buses is greater than that of cars, it is assumed that \( K_{\text{EV}} \) of commercial district is increased from 0 to 1 with a step of 0.25, and that of residential district is increased from 0 to 0.8 with a step of 0.2.

The results are shown in Figure 8. It can be seen that: 1) The greater the load transfer rate, the smaller the peak-to-valley difference, and the more obvious the effect of peak shaving and valley filling. 2) Since buses’ charging period coincides with valley period, and cars’ charging period coincides with evening peak period, impact of changes in load transfer rate on the load in commercial district is mainly reflected in "valley filling," while that in residential district is mainly reflected in "peak shaving."
Comparison of Different Charging Strategies of EVs

The following 3 scenarios are considered:

Scenario 1: The disorderly charging strategy for EVs is adopted. EVs start charging immediately when they return.

Scenario 2: The traditional orderly charging strategy for EVs is adopted. It is assumed that EV users are completely rational. Under the influence of time-of-use price (the whole day only includes peak and valley periods), EVs start charging at the beginning of valley period.

Scenario 3: The orderly charging strategy considering consumer psychology and trip chain is adopted. It is assumed that charging time of EVs is evenly distributed in valley period through the intelligent charging control technology. The probability density function of EVs charging starting time is

$$f_{T_{\text{start}}}(T_{\text{start}}) = \begin{cases} 1 & t_{\text{vs}} - t_{\text{ve}} - T_{\text{ch}} \leq T_{\text{start}} < t_{\text{ve}} - T_{\text{ch}} \\ 0 & \text{else} \end{cases}$$

(25)

where $T_{\text{start}}$ is the charging starting time of EVs; $t_{\text{vs}}$ and $t_{\text{ve}}$ are the start and end time of valley period respectively.

In each scenario, simulations are performed on $n_b$ buses and $n_c$ cars. The results are shown in Figure 9. It can be seen that: 1) Due to the unreasonable control of charging load in scenario 1, charging of EVs at night is mostly concentrated before 24:00, which makes load distribution at night more uneven and increases local peak-to-valley difference. 2) Compared with...
FIGURE 9 | Charging load of different scenarios of EVs. (A) Electric buses. (B) Electric cars.

FIGURE 10 | Nodal voltage surface diagram. (A) Baseline load. (B) Scenario 1. (C) Scenario 2. (D) Scenario 3.
Scenario 1, Scenarios 2 and 3 can transfer charging load under the influence of time-of-use price. However, Scenario 2 still lacks sufficient control of charging load, so a large number of EVs are integrated into grid for charging at the same time, causing a sudden load change at the beginning of valley period. 3) Since cars have a more obvious impact on load than buses, the sudden load change is also more obvious in Scenario 2, which has reached the level of impacting grid. 4) Scenario 3 evenly distributes charging time of EVs in valley period, which makes full use of power generation potential of valley period. It has the least impact on grid without generating new load peaks, and truly realizes “valley filling.”

In each scenario, voltage of each node when nb buses and nc cars trip in the distribution network is calculated. The results are shown in Figure 10. It can be seen that: 1) Since the access of EVs will increase total load of distribution network, voltage per unit values of three scenarios are all slightly lower than that of baseline load. 2) It is generally required that safety voltage per unit value is between 0.95 and 1.05. Owing to the sudden load change at the beginning of valley period in Scenario 2, the voltage drops below the lower limit. 3) The charging process in Scenario 3 has the least impact on grid, whose voltage deviation is smaller than Scenarios 1 and 2.

The calculation results of total load indicators in different scenarios are shown in Table 2. It can be seen that: 1) Scenarios 1 and 2 have no obvious improvement effect on peak-to-valley difference and network loss. Even due to the sudden load change in Scenario 2, the peak-to-valley difference rate slightly increases. 2) Scenario 3, where the orderly charging strategy considering consumer psychology and trip chain is adopted, can greatly reduce peak-to-valley rate and network loss rate, and play a role in fully improving load curve.

Optimization Results of Time-of-Use Price

The function surface diagrams of peak-to-valley difference rate and network loss rate with respect to load transfer rate in residential district and commercial district are drawn respectively, as shown in Figure 11. It can be seen that: the greater the two load transfer rates, the peak-to-valley difference rate generally tends to decrease, and the network loss rate shows a slower growth trend.

To solve the optimization problem established in Trip Chain and its Characteristic Variables, the relative MIP gap tolerance in gurobi is set to 0.01%. Considering that peak-to-valley difference rate and network loss rate are both dimensionless physical quantities, and the two have little difference in their status when measuring the qualities of load curve, so the weight coefficients of multiobjective function are selected as $\omega_1 = \omega_2 = 0.5$. Total load curve before and after optimization is shown in Figure 12, and optimization results of time-of-use price in commercial and residential district are listed in Table 3.

It can be seen that: 1) The optimal load curve considering consumer psychology is relatively stable on the whole, showing an obvious effect of “peak shaving and valley filling.” 2) The load during peak and valley periods both have a certain amount of transfer. Moreover, EVs load transfer rate in residential and commercial district and other load transfer rate are all in linear region. In summary, by establishing the time-of-use price optimization model, EVs can be guided to charge orderly, which can reduce peak-to-valley difference and network loss, and provide a theoretical basis for system operators to determine time-of-use price.

![Figure 11](A) Peak-to-valley difference rate. (B) Network loss rate.)
CONCLUSION

Aiming at the hot issue of impact of large-scale EVs connected to grid on distribution network load, this article proposes a price-based orderly charging strategy for EVs considering both consumer psychology and trip chain. A time-of-use price optimization model based on consumer psychology is established to describe the charging behavior of EV owners influenced by electricity price. The examples are provided to compare the impact of EVs connected to grid under different ratios, different load transfer rates, and different scenarios. The conclusions are as follows:

1) The impact of disorderly charging for EVs without considering consumer psychology on distribution network is related to their daily return time. Disorderly charging of buses can achieve a certain “valley filling” effect; that of cars can result in “peak plus peak” situation.

2) When considering consumer psychology, the greater the load transfer rate, the smaller the peak-to-valley difference, and the more obvious the effect of peak shaving and valley filling. Impact of changes in load transfer rate on the load in commercial district is mainly reflected in “valley filling,” while that in residential district is mainly reflected in “peak shaving.”

3) Among a variety of charging strategies, the orderly charging strategy considering consumer psychology and trip chain can greatly reduce peak-to-valley difference and network loss, and make voltage deviation smaller.

4) Time-of-use price optimization model, established based on consumer psychology and trip chain, can guide EVs to charge orderly, and provide a theoretical basis to determine time-of-use price.

In the future work, the uncertainty of renewable energy power will be considered, combined with the SOC transition probability of EVs based on Markov Chain, to further investigate impact of the SOC of EVs on distribution network load in different scenarios.

DATA AVAILABILITY STATEMENT

The original contributions presented in the study are included in the article/Supplementary Material, further inquiries can be directed to the corresponding author.

AUTHOR CONTRIBUTIONS

JG and CL proposed the methodology. JL, BG, and ZL conducted the theoretical analysis as well as the simulation verification. YC wrote the original draft which was reviewed and edited by YL and YB. All authors agree to be accountable for the content of the work.

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