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Self-Weighted LSE and Residual-Based QMLE of ARMA-GARCH Models †

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† This article is devoted to memorize Professor Michael McAleer for his friendship and long-term support of us.

Abstract: This paper studies the self-weighted least squares estimator (SWLSE) of the ARMA model with GARCH noises. It is shown that the SWLSE is consistent and asymptotically normal when the GARCH noise does not have a finite fourth moment. Using the residuals from the estimated ARMA model, it is shown that the residual-based quasi-maximum likelihood estimator (QMLE) for the GARCH model is consistent and asymptotically normal, but if the innovations are asymmetric, it is not as efficient as that when the GARCH process is observed. Using the SWLSE and residual-based QMLE as the initial estimators, the local QMLE for ARMA-GARCH model is asymptotically normal via an one-step iteration. The importance of the proposed estimators is illustrated by simulated data and five real examples in financial markets.

Keywords: ARMA models; GARCH models; QMLE; Self-weighted LSE

1. Introduction

Time series models have been extensively applied in various areas and many methodologies were proposed in the literature; for example, Zhang (2003) proposed a hybrid methodology that combines both ARIMA and ANN models to improve forecasting accuracy. Since Engle (1982), the ARCH-type models have been widely used in economics and finance. In particular, the GARCH model proposed by Bollerslev (1986) has been a benchmark in the risk management. Zhang and Zhang (2020) showed that the GARCH-based option-pricing models are able to price the SPX one-month variance swap rate, that is, the CBOE Volatility Index (VIX) accurately. Setiawan et al. (2021) used the GARCH(1, 1) model to analyze stock market turmoil during COVID-19 outbreak in an emerging and developed Economy.

However, recent research showed that the usual statistical inference procedure does not work if the fourth moment of the GARCH process does not exist. To make it clear, let us consider the AR(1)-GARCH(1, 1) model

\[ y_t = \phi_1 y_{t-1} + \varepsilon_t, \quad \varepsilon_t = \eta_t \sqrt{h_t} \text{ and } h_t = \alpha_0 + \alpha_1 \varepsilon_{t-1}^2 + \beta_1 h_{t-1}, \]

where \( \alpha_0 > 0, \alpha_1 \geq 0, \beta_1 \geq 0 \), and \( \eta_t \) is a sequence of independent and identically distributed (i.i.d.) innovations with zero mean and unit variance. For model (1), the least squares estimator (LSE) of \( \phi_1 \) is

\[ \hat{\phi}_{LSn} = \left( \frac{1}{n} \sum_{t=1}^{n} y_{t-1} \right)^{-1} \left( \frac{1}{n} \sum_{t=1}^{n} y_{t-1} y_t \right). \]
where \( n \) is the sample size. Weiss (1986) and Pantula (1989) showed that \( \hat{\phi}_{LSE} \) is \( \sqrt{n} \)-consistent and asymptotically normal if \( E\varepsilon_t^4 < \infty \). However, \( E\varepsilon_t^4 = \infty \) when the tail index \( \alpha \) of \( \varepsilon_t \) is in \((0, 4)\). In this case, Davis and Mikosch (1998) and Basrak et al. (2002) showed that \( \varepsilon_t \) has a heavy-tailed feature and its sample autocorrelation function is neither \( \sqrt{n} \)-consistent nor asymptotically normal. Lange (2011) showed that \( \hat{\phi}_{LSE} \) is \( n^{1-2/\alpha} \)-consistent and converges to a stable random variable when \( \alpha \in (2, 4) \). Furthermore, for the AR model with \( \varepsilon_t \) being G-GARCH(1, 1) noise in He and Teräsvirta (1999), Zhang and Ling (2015) showed that \( \hat{\phi}_{LSE} \) is consistent and asymptotically normal when the innovations are asymmetric, it is not as efficient as that when the GARCH noise does not have a finite fourth moment (i.e., \( \varepsilon_t \) is very small for \( \varepsilon_t^4 < \infty \) (i.e., \( \alpha > 4 \)). In practice, the estimated value of \( \alpha \) is very small for \( \varepsilon_t^4 < \infty \) (i.e., \( \alpha > 4 \)). Thus, it is very important to study the statistical inference when \( \alpha \in (0, 4) \). Zhu and Ling (2015) studied the self-weighted least absolute deviation estimator (SLADE) of the ARMA-GARCH model and showed that it is consistent and asymptotically normal when \( \alpha \in (0, 4) \).

This paper studies the self-weighted LSE (SWLSE) of the ARMA model with GARCH noises. It is shown that the SWLSE is consistent and asymptotically normal when the GARCH noise does not have a finite fourth moment (i.e., \( \alpha \in (2, 4) \)). Using the residuals from the estimated ARMA model, it is shown that the residual-based quasi-maximum likelihood estimator (QMLE) for the GARCH model is consistent and asymptotically normal, but if the innovations are asymmetric, it is not as efficient as that when the GARCH process is observed. Using the SWLSE and residual-based QMLE as the initial estimators, the local QMLE for ARMA-GARCH model is asymptotically normal via an one-step iteration.

\[
\frac{\sqrt{n}}{\log n} (\hat{\phi}_{LSE} - \phi_1) \rightarrow_{L} \text{Normal, if } \alpha = 4 \ (i.e., E\varepsilon_t^4 = \infty),
\]

\[
n^{1-\frac{2}{\alpha}} (\hat{\phi}_{LSE} - \phi_1) \rightarrow_{L} \text{Stable, if } \alpha \in (2, 4) \ (i.e., E\varepsilon_t^2 < \infty \text{ and } E\varepsilon_t^4 = \infty),
\]

\[
\log n (\hat{\phi}_{LSE} - \phi_1) \rightarrow_{L} \text{Stable, if } \alpha = 2 \ (i.e., E\varepsilon_t^2 = \infty),
\]

\[
\hat{\phi}_{LSE} - \phi_1 \rightarrow_{L} \text{Stable, if } \alpha \in (0, 2) \ (i.e., E\varepsilon_t^2 = \infty),
\]

when \( n \rightarrow \infty \), where \( \rightarrow_{L} \) denotes the convergence in distribution. From (3)–(6), we find that the LSE not only has a slower rate of convergence but also is not asymptotically normal when \( \alpha \in (0, 4) \). Thus, based on the LSE, the classical theory and methodology (e.g., \( t \)-test, Wald test, and Ljung-Box test, among others) do not work in this case. Using a simulation method, we give the regime of parameter vector \((\alpha_1, \beta_1)\) with \( E\varepsilon_t^2 < \infty \) in Figure 1 when \( \eta_1 \sim N(0, 1) \). It can be seen that the regime of \((\alpha_1, \beta_1)\) is very small for \( E\varepsilon_t^4 < \infty \) (i.e., \( \alpha > 4 \)). Figure 1 when \( \alpha_1 + \beta_1 = 1 \) (i.e., \( \alpha = 1 \)). This paper studies the self-weighted LSE (SWLSE) of the ARMA model with GARCH noises.
This paper is arranged as follows. Section 2 presents the model and assumptions. Section 3 presents our main results. Section 4 presents simulation results and Section 5 gives real examples. All the proofs are deferred into the Appendix A.

2. Model and Assumptions

Assume that \( \{y_t : t = 0, \pm 1, \pm 2, \cdots \} \) are generated by the ARMA-GARCH model

\[
y_t = \mu + \sum_{i=1}^{p} \phi_i y_{t-i} + \sum_{i=1}^{q} \psi_i \varepsilon_{t-i} + \varepsilon_t, \quad (7)
\]

\[
\varepsilon_t = \eta_t \sqrt{h_t} \text{ and } h_t = a_0 + \sum_{i=1}^{r} \alpha_i \varepsilon_{t-i}^2 + \sum_{i=1}^{s} \beta_i h_{t-i}, \quad (8)
\]

where \( \alpha_i \geq 0 \) and \( \beta_j \geq 0 \), \( i = 0, \cdots, r \), \( j = 1, \cdots, s \), and \( \eta_t \) is defined as in (2). Denote \( \gamma = (\mu, \phi_1, \cdots, \phi_p, \psi_1, \cdots, \psi_q)' \), \( \delta = (\phi_0, \alpha_1, \cdots, \alpha_r, \beta_1, \cdots, \beta_s)' \), and \( \lambda = (\gamma', \delta')' \). Let \( \gamma_0, \delta_0, \text{ and } \theta_0 \) be the true values of \( \gamma, \delta, \text{ and } \theta \), respectively. The parameter subspaces \( \Theta_\gamma \subset R^{p+q+1} \) and \( \Theta_\delta \subset R^{p+q+1} \) are compact, where \( R = (-\infty, \infty) \) and \( R_0 = [0, \infty) \). Denote \( \Theta = \Theta_\gamma \times \Theta_\delta \), \( m = p + q + r + s + 2 \), \( \alpha(z) = \sum_{i=1}^{r} \alpha_i z^i \), \( \beta(z) = 1 - \sum_{i=1}^{s} \beta_i z^i \), \( \phi(z) = 1 - \sum_{i=1}^{p} \phi_i z^i \), and \( \psi(z) = 1 + \sum_{i=1}^{q} \psi_i z^i \). We introduce the following conditions:

**Assumption 1.** \( \theta_0 \) is an interior point in \( \Theta \) and for each \( \theta \in \Theta \), \( \phi(z) \neq 0 \) and \( \psi(z) \neq 0 \) when \( |z| \leq 1 \), and \( \phi(z) \) and \( \psi(z) \) have no common root with \( \phi_p \neq 0 \) or \( \psi_q \neq 0 \).

**Assumption 2.** \( \alpha(z) \) and \( \beta(z) \) have no common root, \( \alpha_r + \beta_s \neq 0 \), and \( \sum_{i=1}^{r} \alpha_i + \sum_{j=1}^{s} \beta_j < 1 \) for each \( \theta \in \Theta \).

Assumption 1 is the stationarity and invertibility condition of ARMA models, under which it follows that

\[
\psi^{-1}(z) = \sum_{i=0}^{\infty} a_\psi(i) z^i \text{ and } \phi(z) \psi^{-1}(z) = \sum_{i=0}^{\infty} a_\gamma(i) z^i, \quad (9)
\]

where \( \sup_{\Theta_\gamma} |a_\gamma(i)| = O(p^i) \) and \( \sup_{\Theta_\delta} |a_\delta(i)| = O(p^i) \) with \( p \in (0, 1) \). Assumption 2 ensures that \( \{\varepsilon_t\} \) is strictly stationary and ergodic with \( E\varepsilon_t^2 < \infty \), see Ling and Li (1997) and Ling and McAleer (2002). It is also the identifiability condition for model (2) and, by Lemma 2.1 in Ling (1999), the condition \( \sum_{i=1}^{s} \beta_i < 1 \) is equivalent to

\[
0 \leq \rho(G) < 1, \text{ where } G = \begin{pmatrix} \beta_1 & \cdots & \beta_s \\ 1_{s-1} & & \end{pmatrix}, \quad (10)
\]

where \( I_k \) is the \( k \times k \) identity matrix, and \( \rho(B) \) is the spectral radius of matrix \( B \). Under this condition, we have

\[
\beta^{-1}(z) = \sum_{i=0}^{\infty} a_\beta(i) z^i \text{ and } \alpha(z) \beta^{-1}(z) = \sum_{i=1}^{\infty} a_\delta(i) z^i, \quad (11)
\]

where \( \sup_{\Theta_\beta} |a_\beta(i)| = O(p^i) \) and \( \sup_{\Theta_\delta} |a_\delta(i)| = O(p^i) \) with \( p = \rho(G) \).

Given the observations \( \{y_{t_n}, \cdots, y_{t}\} \) and initial value \( Y_0 = \{y_0, y_{-1}, \cdots\} \), we can write the parametric model as

\[
\varepsilon_t(\gamma) = y_t - \mu - \sum_{i=1}^{p} \phi_i y_{t-i} - \sum_{i=1}^{q} \psi_i \varepsilon_{t-i}(\gamma), \quad (12)
\]

\[
\eta_t(\lambda) = \varepsilon_t(\gamma) \sqrt{h_t(\lambda)} \text{ and } h_t(\lambda) = a_0 + \sum_{i=1}^{r} \alpha_i \varepsilon_{t-i}^2(\gamma) + \sum_{i=1}^{s} \beta_i h_{t-i}(\lambda). \quad (13)
\]
It is easy to see that \( \eta_t(\lambda_0) = \eta_t, \varepsilon_t(\gamma_0) = \varepsilon_t, \) and \( h_t(\lambda_0) = h_t. \) In practice, we do not observe those \( y_t \) in \( Y_0 \) and hence they have to be replaced by some constants. This does not affect our asymptotic results, see Ling and McAleer (2003a). For simplicity, we do not study this case in details.

3. Main Results

The self-weighted estimation approach was proposed by Ling (2005) and it has been used to solve the problem on statistical inference of the heavy-tailed ARMA-GARCH model in Ling (2007) and Zhu and Ling (2011). Using a similar idea, we define the SWLSE as

\[
\hat{\gamma}_n = \arg \min_{\gamma \in \Theta} \frac{1}{n} \sum_{t=1}^{n} \frac{e_t^2(\gamma)}{w_t},
\]

where \( w_t = 1 + \sum_{k=1}^{\infty} k^{-1/2} |y_{t-k}|. \) We can state the following result:

**Theorem 1.** Suppose that Assumptions 1–2 hold. Then, as \( n \to \infty, \)

\[
\begin{align*}
(i) \quad & \hat{\gamma}_n \xrightarrow{p} \gamma_0, \\
(ii) \quad & \sqrt{n}(\hat{\gamma}_n - \gamma_0) \xrightarrow{d} N(0, \Lambda^{-1} B A^{-1}),
\end{align*}
\]

where \( \xrightarrow{d} \) denotes the convergence in probability, \( A = E(w_t^{-1} M_t), B = E(w_t^{-2} h_t M_t), \) and \( M_t = [\partial e_t (\gamma_0) / \partial \gamma] [\partial e_t (\gamma_0) / \partial \gamma]' \).

The preceding result holds for any kind of ARCH-type errors only if \( Eh_t < \infty, \) see the proof in the Appendix A. To easily understand it, we refer to model (1)–(2) again. In this case, the information function is \( E(y_{t-1}^2 / w_t) \leq E|y_{t-1}| < \infty. \) The score function is \( n^{-1/2} \sum_{t=1}^{n} y_{t-1} \varepsilon_t / w_t \) and \( E(y_{t-1} \varepsilon_t / w_t)^2 \leq O(1) Eh_t < \infty, \) which is the condition we need for the GARCH errors. This result holds when \( E\hat{\varepsilon}_t^4 < \infty, \) but it is not as efficient as the LSE in this case. When \( E\hat{\varepsilon}_t^4 = \infty \) and \( E\hat{\varepsilon}_t^2 < \infty, \) the process \( y_t \) has a heavy tailed feature and the SWLSE has a faster rate of convergence than that of LSE. The weight function \( w_t \) can be replaced by others, see Ling (2007).

Next, we use the residual \( \hat{\varepsilon}_t \equiv \varepsilon_t(\hat{\gamma}_n) \) from ARMA parts as the artificial observation of \( \varepsilon_t. \) The log-quasi-likelihood function based on \( \hat{\varepsilon}_t \) can be written as

\[
L_{\hat{\delta}_n}(\delta) = \frac{1}{n} \sum_{t=1}^{n} \tilde{L}_t(\delta) and \tilde{L}_t(\delta) = -\frac{1}{2} \log \tilde{h}_t(\delta) - \frac{\hat{\varepsilon}_t^2}{2 \tilde{h}_t(\delta)},
\]

where \( \tilde{h}_t(\delta) = h_t(\lambda)|_{\gamma = \hat{\gamma}_n}. \) We define the residual-based QMLE of \( \delta_0 \) as

\[
\hat{\delta}_n = \arg \max_{\delta \in \Theta} L_{\hat{\delta}_n}(\delta).
\]

Denote \( H_{\hat{\delta}}(\lambda) = h_t^{-2}(\lambda) |\partial h_t(\lambda)/\partial \delta| |\partial h_t(\lambda)/\partial \delta'| \) and \( H_{\hat{\delta}}(\lambda_0) \) by \( H_{\hat{\delta}}. \) We now give the asymptotic properties of \( \hat{\delta}_n \) as follows.

**Theorem 2.** Suppose that Assumptions 1–2 hold. Then, as \( n \to \infty, \)

\[
\begin{align*}
(i) \quad & \hat{\delta}_n \xrightarrow{p} \delta_0, \text{ if } E|\eta_t|^{2+l} < \infty \text{ for some } l > 0, \\
(ii) \quad & \sqrt{n}(\hat{\delta}_n - \delta_0) \xrightarrow{d} N(0, (EH_{\hat{\delta}}^{-1})^{-1} \Omega_{\delta} (EH_{\hat{\delta}}^{-1})^{-1}), \text{ if } \eta_t^4 < \infty,
\end{align*}
\]

where \( \Omega_{\delta} = \kappa EH_{\hat{\delta}} + ED_{\hat{\delta}}(A^{-1} BA^{-1}) ED_{\hat{\delta}} + \kappa_3 \hat{\Omega}_{\delta}, \) \( \hat{\Omega}_{\delta} = ED_{\hat{\delta}} A^{-1} E(w_t^{-1} \hat{D}_t) + E(w_t^{-1} \hat{D}_t) A^{-1} ED_{\hat{\delta}}, \) \( \kappa = E\hat{\eta}_t^4 - 1, \) \( \kappa_3 = E\hat{\eta}_t^3, \) \( D_t = E[h_{t-2}^{-1} \partial h_t(\lambda_0)/\partial \delta |\partial h_t(\lambda_0)/\partial \gamma'|], \) \( \) and \( \hat{D}_t = E[h_{t-1}^{-2} \partial h_t(\lambda_0)/\partial \delta |\partial \varepsilon_t(\gamma_0)/\partial \gamma'|]. \)
When \( \eta \) is symmetric and \( \mu = 0 \), we have \( E\eta^3 = 0 \), \( ED_t = E\bar{D}_t = 0 \), and hence \( \Omega_0 = \kappa EH_0 \). When the conditional mean is zero (i.e., \( y_t = \varepsilon_t \)), model (7)–(8) reduces to the GARCH model. In this case, the log-quasi-likelihood function based on \( \varepsilon_t \) can be written as
\[
L_\delta(\delta) = \frac{1}{n} \sum_{t=1}^{n} l_t(\delta) \quad \text{and} \quad l_t(\delta) = -\frac{1}{2} \log h_t(\delta) - \frac{\varepsilon_t^2}{2h_t(\delta)}.
\] (15)

Then, the global QMLE of \( \delta_0 \) is defined as \( \delta_n = \arg \max_{\delta \in \Theta} L_\delta(\delta) \). Berkes et al. (2003) and Hall and Yao (2003) showed that \( \delta_n \) is consistent and as \( n \to \infty \),
\[
\sqrt{n}(\delta_n - \delta_0) \xrightarrow{d} N(0, \kappa(EH_0)^{-1}). \tag{16}
\]

From Theorem 2, we see that the efficiency of the estimated \( \delta_0 \) is affected by the estimated parameters in ARMA parts unless \( \eta \) has a symmetric density and \( \mu \) is known to be zero without estimation. This gives a reminder to practitioners that we need to be careful when ones use the residuals to estimate the GARCH model.

Given \( \{y_n, \cdots, y_1\} \) and the initial value \( \lambda_0 \), we can write down the log-quasi-likelihood function of model (7)–(8) as follows:
\[
L_n(\lambda) = \frac{1}{n} \sum_{t=1}^{n} l_t(\lambda) \quad \text{and} \quad l_t(\lambda) = -\frac{1}{2} \log h_t(\lambda) - \frac{\varepsilon_t^2}{2h_t(\lambda)}.
\] (17)

Then, the global QMLE of \( \lambda_0 \) is defined as the maximizer of \( L_n(\lambda) \) in \( \Theta \). Ling and McAleer (2003a) proved the consistency of this QMLE. But the asymptotic normality of this QMLE requires \( E\varepsilon_t^4 < \infty \), see also Francq and Zakoïan (2004).

Based on \( \hat{\lambda}_n = (\hat{\gamma}_n, \hat{\delta}_n)' \), we obtain the local QMLE through an one-step iteration
\[
\hat{\lambda}_n = \hat{\lambda}_0 - \frac{1}{n} \sum_{t=1}^{n} \frac{\partial^2 l_t(\hat{\lambda}_n)}{\partial \lambda \partial \lambda'} \left[ \sum_{t=1}^{n} \frac{\partial l_t(\hat{\lambda}_n)}{\partial \lambda} \right]^{-1} \sum_{t=1}^{n} \frac{\partial l_t(\hat{\lambda}_n)}{\partial \lambda}.
\] (18)

As in Ling (2007), we can show that as \( n \to \infty \),
\[
\sqrt{n}(\hat{\lambda}_n - \lambda_0) \xrightarrow{d} N(0, \Sigma^{-1} \Omega \Sigma^{-1}),
\]
where \( \Sigma = E[U_t(\lambda_0)U_t'(\lambda_0)] \), \( \Omega = E[U_t(\lambda_0)U_t(\lambda_0)] \), \( J = \begin{pmatrix} 1 & \kappa_3 & \kappa_5 \\ \kappa_3 & \kappa \\ \kappa_5 & \kappa \end{pmatrix} \), and \( U_t(\lambda) = [h_t^{1/2}\partial \varepsilon_t(\gamma)/\partial \lambda, h_t^{-1}\partial h_t(\lambda)/\partial \lambda] \). When \( \eta \sim N(0, 1) \), the local QMLE is efficient. So, Theorems 1–2 provide an approach to obtain an efficient estimator for the full ARMA-GARCH models under the finite second moment condition of \( \varepsilon_t \). When \( \eta \) is not normal, the efficient and adaptive estimators can be obtained by using the results in this section and following the similar lines as in Drost et al. (1997), Drost and Klaassen (1997), Ling (2003), and Ling and McAleer (2003b).

4. Simulation Study

In this section, we assess the finite sample performance of \( \hat{\lambda}_n = (\hat{\gamma}_n, \hat{\delta}_n)' \) and \( \hat{\lambda}_n = (\hat{\gamma}_n, \hat{\delta}_n)' \), where \( \hat{\gamma}_n \) is the SWLSE, \( \hat{\delta}_n \) is the residual-based QMLE, and \( \hat{\lambda}_n \) is the local QMLE. We generate 1000 replications of sample size \( n = 1000 \) and 2000 from the following model
\[
y_t = \phi_{10} y_{t-1} + \psi_{10} \varepsilon_{t-1} + \varepsilon_t, \tag{19}
\]
\[
\varepsilon_t = \eta_t \sqrt{h_t} \quad \text{and} \quad h_t = \alpha_{00} + \alpha_{10} \varepsilon_{t-1}^2 + \beta_{10} h_{t-1}, \tag{20}
\]
where \( \gamma_0 = (\phi_{10}, \psi_{10}) = (0.4, 0.5) \), \( \delta_0 = (\alpha_{00}, \alpha_{10}, \beta_{10}) = (0.1, 0.1, 0.8) \), and \( \eta_t \) is chosen to be the standard normal N(0, 1) distribution, re-scaled Laplace \( L(0, 1) \) distribution, or re-scaled student’s t(5) distribution with \( E\eta^2 = 1 \). Table 1 reports the sample bias (Bias), the
sample standard deviations (SD), and the average estimated asymptotic standard deviation (AD) of $\hat{\lambda}_n$ and $\tilde{\lambda}_n$. From this table, we find that (i) each considered estimator has a small bias, and its value of SD is close to that of AD, demonstrating the validity of its asymptotic normality; (ii) $\hat{\gamma}_n$ could be slightly more efficient than $\tilde{\gamma}_n$, whereas $\tilde{\delta}_n$ is as efficient as $\hat{\delta}_n$; (iii) all estimators for $\eta_1 \sim N(0, 1)$ are more efficient than the corresponding ones for $\eta_1 \sim L(0, 1)$ or $t(5)$. All these findings are consistent with our theory in Section 3. We should mention that the QMLE of $\delta_0$ is not reliable when the sample size $n$ is less than 800 according to our simulation experiments and hence the results are not reported here.

| $\eta_1$ | $n$ | Bias | $\phi_{LS}$ | $\psi_{LS}$ | $\hat{\alpha}_n$ | $\delta_1$ | $\hat{\beta}_{1n}$ |
|----------|-----|------|-------------|-------------|---------------|----------|-----------------|
| $N(0, 1)$ | 1000 | Bias $-0.0012$ | $0.0032$ | $0.0189$ | $0.0012$ | $-0.0235$ | |
|          |     | SD 0.0443 | 0.0423 | 0.0650 | 0.0278 | 0.0839 | |
|          |     | AD 0.0424 | 0.0402 | 0.0524 | 0.0290 | 0.0726 | |
|          | 2000 | Bias $-0.0017$ | $0.0015$ | $0.0083$ | $-0.0000$ | $-0.0103$ | |
|          |     | SD 0.0300 | 0.0293 | 0.0342 | 0.0204 | 0.0471 | |
|          |     | AD 0.0300 | 0.0285 | 0.0332 | 0.0201 | 0.0469 | |

| $\eta_1$ | $n$ | Bias | $\phi_{LS}$ | $\psi_{LS}$ | $\hat{\alpha}_n$ | $\delta_1$ | $\hat{\beta}_{1n}$ |
|----------|-----|------|-------------|-------------|---------------|----------|-----------------|
| $L(0, 1)$ | 1000 | Bias $-0.0032$ | $0.0035$ | $0.0241$ | $0.0020$ | $-0.0304$ | |
|          |     | SD 0.0454 | 0.0414 | 0.0806 | 0.0381 | 0.1079 | |
|          |     | AD 0.0453 | 0.0433 | 0.0639 | 0.0385 | 0.0909 | |
|          | 2000 | Bias $-0.0001$ | $0.0014$ | $0.0116$ | $0.0016$ | $-0.0148$ | |
|          |     | SD 0.0328 | 0.0307 | 0.0426 | 0.0268 | 0.0599 | |
|          |     | AD 0.0223 | 0.0207 | 0.0397 | 0.0269 | 0.0577 | |

| $\eta_1$ | $n$ | Bias | $\phi_{LS}$ | $\psi_{LS}$ | $\hat{\alpha}_n$ | $\delta_1$ | $\hat{\beta}_{1n}$ |
|----------|-----|------|-------------|-------------|---------------|----------|-----------------|
| $t(5)$   | 1000 | Bias $-0.0012$ | $0.0016$ | $0.0300$ | $0.0046$ | $-0.0395$ | |
|          |     | SD 0.0460 | 0.0445 | 0.0867 | 0.0432 | 0.1137 | |
|          |     | AD 0.0454 | 0.0431 | 0.0734 | 0.0443 | 0.1038 | |
|          | 2000 | Bias $-0.0000$ | $0.0005$ | $0.0126$ | $0.0025$ | $-0.0164$ | |
|          |     | SD 0.0312 | 0.0305 | 0.0463 | 0.0325 | 0.0657 | |
|          |     | AD 0.0323 | 0.0308 | 0.0459 | 0.0316 | 0.0666 | |

As a comparison, we compute the classical LSE $\hat{\gamma}_{LSn} = (\phi_{LSn}, \psi_{LSn})'$ for $\gamma_0$ in model (19)–(20), where $\gamma_{LSn}$ is computed in a similar way as $\tilde{\gamma}_n$ with $w_1 \equiv 1$. Table 2 reports the corresponding results of $\gamma_{LSn}$. Compared with $\gamma_n$ in Table 1, we find that $\gamma_{LSn}$ is less efficient than $\gamma_n$ for all examined cases. This finding suggests that it seems better to fit
the ARMA model by the SWLSE rather than the LSE method when the data exhibit the conditionally heteroscedastic effect.

Table 2. The results of $\hat{\gamma}_{LSn}$.

| n  | $\hat{\gamma}_{LSn}$ | $\hat{\psi}_{LSn}$ | $\hat{\gamma}_{LSn}$ | $\hat{\psi}_{LSn}$ | $\hat{\gamma}_{LSn}$ | $\hat{\psi}_{LSn}$ |
|----|----------------------|---------------------|----------------------|---------------------|----------------------|---------------------|
| 1000 | Bias 0.0001 0.0012 | $-0.0034$ 0.0024 | $-0.0033$ 0.0015 | SD 0.0441 0.0412 | $0.0482$ 0.0473 | $0.0518$ 0.0487 |
| 2000 | Bias $-0.0018$ 0.0015 | $-0.0009$ 0.0011 | $-0.0008$ 0.0010 | SD 0.0307 0.0299 | $0.0350$ 0.0325 | $0.0382$ 0.0349 |

5. Real Examples

This section first studies the log returns ($\times 100$) of DJIA, NASDAQ, NASDAQ 100, and S&P 500 from 11 March 2015 to 10 March 2021, with a total of 1764 observations (see Figure 2). Denote each log return series by $\{y_t\}_{t=1}^{1764}$. Before fitting an AR(1)-GARCH(1, 1) to $\{y_t\}_{t=1}^{1764}$, we first estimate $\hat{\alpha}_y$, the tail index of $|y_t|$, and get the following results:

- (DJIA) $\hat{\alpha}_y = 2.3029$, (NASDAQ) $\hat{\alpha}_y = 3.2592$,
- (NASDAQ 100) $\hat{\alpha}_y = 3.6956$, (S&P 500) $\hat{\alpha}_y = 2.5329$,

where $\hat{\alpha}_y$ is the proposed estimator of $\alpha_y$ in Hill (2010), and the value in parentheses is the AD of $\hat{\alpha}_y$. From the above results, we can conclude that each $|y_t|$ has a finite second moment, but does not have a finite fourth moment. Hence, it is reasonable to fit four return series by using the procedure in Section 3, that is, we first obtain the SWLSE $\tilde{\gamma}_{n}$ and the residual-based QMLE $\tilde{\delta}_{n}$, and then obtain the local QMLE $\hat{\lambda}_{n}$. The resulting fitted models are as follows:

- (DJIA) $\begin{align*}
y_t &= 0.0859 - 0.0461y_{t-1} + \varepsilon_t, \\
h_t &= 0.0416 + 0.2108\varepsilon_{t-1}^2 + 0.7532h_{t-1},
\end{align*}$
- (NASDAQ) $\begin{align*}
y_t &= 0.1009 - 0.0663y_{t-1} + \varepsilon_t, \\
h_t &= 0.0643 + 0.1747\varepsilon_{t-1}^2 + 0.7826h_{t-1},
\end{align*}$
- (NASDAQ 100) $\begin{align*}
y_t &= 0.1125 - 0.0654y_{t-1} + \varepsilon_t, \\
h_t &= 0.0668 + 0.1751\varepsilon_{t-1}^2 + 0.7855h_{t-1},
\end{align*}$
- (S&P 500) $\begin{align*}
y_t &= 0.0910 - 0.0838y_{t-1} + \varepsilon_t, \\
h_t &= 0.0432 + 0.2206\varepsilon_{t-1}^2 + 0.7453h_{t-1},
\end{align*}$

where all estimated parameters are the local QMLE $\hat{\lambda}_{n}$, and the values in parentheses are the ADs of $\hat{\lambda}_{n}$. From these fitted models, we can find that all estimated parameters are...
significantly different from zero at the level of 5%. In particular, the significant parameters in the fitted AR models imply that the U.S. stock market is not efficient during the examined period.

![Graphs of DJIA, NASDAQ, NASDAQ 100, and S&P 500](image)

**Figure 2.** Log returns (×100) of DJIA, NASDAQ, NASDAQ 100, and S&P 500 from 11 March 2015 to 10 March 2021.

Next, this section considers the log returns (×100) of PHLX Oil Service Index OSX from 11 March 2015 to 10 March 2021, with a total of 1510 observations (see Figure 3). As before, we denote this log return series by \( \{y_t\}_{t=1}^{1510} \), and obtain its estimate \( \hat{\alpha}_y = 2.7960 \) with AD = 0.7078. This implies that \( |y_t| \) has a finite second moment, but does not have a finite fourth moment. Hence, we apply the local QMLE method to get the following fitted model for \( y_t \):

\[
(\text{OSX}) \quad \begin{cases} 
  y_t = -0.0377 + 0.0239y_{t-1} + \epsilon_t, \\
  h_t = 0.1329 + 0.1076\epsilon_{t-1}^2 + 0.8792h_{t-1}.
\end{cases}
\]

Unlike the fitted results for the four U.S. stock indexes above, the fitted AR coefficient for the OSX index is not significantly different from zero at the level of 5%, indicating that the oil market is efficient during the examined period.
6. Concluding Remarks

This paper studied the SWLSE of the ARMA model with GARCH noises and the residual-based QMLE for the GARCH model. The consistency and asymptotic normality of SWLSE were established under a little moment condition. The importance of the proposed estimators was illustrated by simulated data and four major stock indexes and one major oil index in U.S. The ARMA-GARCH model is very important in the risk management, see He et al. (2019). In practice, ones need to build the ARMA-GARCH model from the historical data. The major contribution of our paper is to present a way to build an efficient and reliable model for this purpose. Several potential future research topics are listed as follows: first, we may extend our procedure for the hybrid methodology that combines both ARIMA and ANN models with GARCH errors as in Zhang (2003); second, we could use our procedure to analyze the energy data and build an ARMA-GARCH model for the green energy, renewable energy, and bio-energy data as discussing in An and Mikhaylov (2020); third, we may explore a linear programming or a genetic algorithm to find the QMLE of ARMA-GARCH model as presented in An et al. (2021).

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Appendix A. Proofs

The following lemma gives two basic properties for model (7)–(8).

Lemma A1. Suppose \{\epsilon_i\} is generated by model (8) satisfying Assumption 2. Then (i) \{\epsilon_i\} is strictly stationary and ergodic with \(E\epsilon_i^2 < \infty\), and has the following causal representation:

\[
\epsilon_t = \eta_t \sqrt{h_t} \text{ and } h_t = \alpha_0 \left[ 1 + \sum_{j=1}^{\infty} u' \prod_{i=0}^{j-1} P_{t-i} \right] \text{ a.s.};
\]
and (ii) there exists some $i \in (0, 1)$ such that $E|\varepsilon_i|^{2+i} < \infty$ if $E|\eta_j|^{2+i} < \infty$ for some $i > 0$, where $\xi_i = (\eta_i^2, 0, \cdots, 0, 1, \cdots, 0)$ and the $r+1$th component $\eta_i^2$ and the $r+1$th component $1$, and $u = (0, \cdots, 0, 1, \cdots, 0)$.  

Proof. The result in (i) is from Theorem 2.1 of Ling and Li (1997). For (ii), we first show that there exists an integer $i_0$ such that, for some $i \in (0, 1)$, 

$$ E\| \prod_{k=1}^{i_0} P_{i-k} \|^{1+i_1} < 1, $$  

(A1)  

where $\|B\| = \sqrt{\text{Tr}(BB^T)}$ for a vector or matrix $B$. Let $P = [\Pi, O]_{(r+s) \times (r+s)}$ with $\Pi = (\alpha_1, \cdots, \alpha_r, \beta_1, \cdots, \beta_s)$, $C$ be defined as $P_t$ with all the elements of its first row replaced by $0$, and 

$$ P(x) = (E|\eta_j|^{2(1+x)})^{1/(1+x)} P + C. $$  

Since $E|\eta_j|^{2+x} < \infty$, the spectral radius $\rho(P(x))$ is continuous in terms of $x$ in $[0, 1]$. By Lemma 3.2 in Ling (1999) and Assumption 2, we know that $\rho(P(0)) = \rho(E P_t) < 1$, and there exists a constant $i_1 \in (0, 1)$ such that 

$$ \rho(P(i_1)) < \rho(E P_t) + [1 - \rho(E P_t)] < 1. $$  

(A2)  

By Corollary A.2 in Johansen (1995, pp. 220) and (A2), 

$$ \|P(i_1)\| \leq \sum_{h=1}^{r+s} \|c_h\| \prod_{i=1}^{i_1} P_i c_{j_2}, $$  

(A4)  

as $i \to \infty$, where $c$ is a constant. Let $c_j = (0, \cdots, 0, 1, 0, \cdots, 0)$ with the $j$th element being $1$. Since all the elements of $P_t$ are nonnegative, it follows that 

$$ \| \prod_{k=1}^{i_1} P_i \| \leq \sum_{h=1}^{r+s} \|c_h\| \prod_{i=1}^{i_1} P_i c_{j_2}. $$  

Using (A1) and the representation in (i), we can show that (ii) holds. This completes the proof.  

□
Lemma A2. [Lemma A.1 in Ling (2007)] If Assumptions 1–2 hold, then there exist constants $C$ and $\rho \in (0,1)$ such that the following holds uniformly in $\Theta$:

(i) $\epsilon_{t-1}(\gamma), \left\| \frac{\partial \epsilon_t(\gamma)}{\partial \gamma} \right\|$, and $\left\| \frac{\partial^2 \epsilon_t(\gamma)}{\partial \gamma \partial \gamma'} \right\|$ are bounded a.s. by $\xi_{\gamma_{t-1}}$,

(ii) $h_t(\lambda)$ is bounded a.s. by $\xi_{\gamma_{t-1}}^2$,

where $\xi_{\gamma_{t-1}} = C(1 + \sum_{i=1}^{\infty} \rho^i|y_{t-i}|)$ with constants $\rho \in (0,1)$ and $C$.

Proof of Theorem 1. (i) Let $L_{sn}(\gamma) = \sum_{i=1}^{n}[\epsilon_t^2(\gamma)/w_i]/n$. First, the space $\Theta_{\gamma}$ is compact and $\gamma_0$ is an interior point in $\Theta_{\gamma}$. Second, $L_{sn}(\gamma)$ is continuous in $\gamma \in \Theta_{\gamma}$ and is a measurable function of $\{y_s, s = t, t-1, \cdots\}$ for all $\gamma \in \Theta_{\gamma}$. Third, by Lemma A2(i),

$$E \sup_{\gamma \in \Theta_{\gamma}} [\epsilon_t^2(\gamma)/w_i] \leq CE(1 + \sum_{i=1}^{\infty} \rho^i|y_{t-i}|)^2 < \infty,$$

where $C$ is a constant. Moreover, by the ergodic theorem, $L_{sn}(\gamma) \rightarrow_p E[\epsilon_t^2(\gamma)/w_i]$ for each $\gamma$. Furthermore, by Theorem 3.1 in Ling and McAleer (2003a), $L_{sn}(\gamma) \rightarrow_p E[\epsilon_t^2(\gamma)/w_i]$ uniformly in $\Theta_{\gamma}$. Fourth,

$$\epsilon_t(\gamma) = \epsilon_t - [M_t(\gamma) - M_t(\gamma_0)],$$

where $M_t(\gamma) = \sum_{i=1}^{n} \phi_i y_{t-i} + \sum_{i=1}^{n} \phi_i \epsilon_{t-i}(\gamma)$. Thus,

$$E[\epsilon_t^2(\gamma)/w_i] = E[\epsilon_t^2(\gamma_0)/w_i] + E\left\{\frac{[M_t(\gamma) - M_t(\gamma_0)]^2}{w_i}\right\} \geq E[\epsilon_t^2(\gamma_0)/w_i],$$

where the equality holds if and only if $M_t(\gamma) = M_t(\gamma_0)$, that is, $\epsilon_t(\gamma) = \epsilon_t(\gamma_0)$, which holds if and only if $\gamma = \gamma_0$ under Assumption 1, that is, $E[\epsilon_t^2(\gamma)/w_i]$ reaches its unique minimum at $\gamma = \gamma_0$. Thus, we have established all the conditions for consistency in Theorem 4.1.1 in Amemiya (1985) and hence (i) holds.

(ii) First, $\tilde{\gamma}_n$ is a consistent estimator of $\gamma_0$. Second,

$$\frac{\partial^2 L_{sn}(\gamma)}{\partial \gamma \partial \gamma'} = \frac{2}{n} \sum_{i=1}^{n} \frac{1}{w_i} \frac{\partial \epsilon_t(\gamma)}{\partial \gamma} \frac{\partial \epsilon_t(\gamma)}{\partial \gamma'} + \frac{2}{n} \sum_{i=1}^{n} \frac{\epsilon_t(\gamma)}{w_i} \frac{\partial^2 \epsilon_t(\gamma)}{\partial \gamma \partial \gamma'},$$

exists and is continuous in $\Theta_{\gamma}$. Third, let

$$A_t(\gamma) = \frac{1}{w_i} \frac{\partial \epsilon_t(\gamma)}{\partial \gamma} \frac{\partial \epsilon_t(\gamma)}{\partial \gamma'} + \frac{\epsilon_t(\gamma)}{w_i} \frac{\partial^2 \epsilon_t(\gamma)}{\partial \gamma \partial \gamma'}.$$ 

By Lemma A2, we can show that $E \sup_{\gamma \in \Theta_{\gamma}} \|A_t(\gamma)\| < \infty$. By the ergodic theorem and Theorem 3.1 in Ling and McAleer (2003a), we can show that $\frac{\partial^2 L_{sn}(\gamma)}{\partial \gamma \partial \gamma'}$ converges to $2E A_t(\gamma)$ uniformly in $\Theta_{\gamma}$ in probability. Since $E A_t(\gamma)$ is continuous in terms of $\gamma$, we can show that $\frac{\partial^2 L_{sn}(\gamma_n)}{\partial \gamma \partial \gamma'}$ converges to $2A$ in probability for any sequence $\gamma_n$ such that $\gamma_n \rightarrow \gamma_0$ in probability. Fourth,

$$\frac{\partial L_{sn}(\gamma_0)}{\partial \gamma} = \frac{2}{n} \sum_{i=1}^{n} \frac{\epsilon_t(\gamma_0)}{w_i} \frac{\partial \epsilon_t(\gamma_0)}{\partial \gamma}.$$ 

By Lemma A2, it follows that

$$B = E \left[ \frac{\epsilon_t^2(\gamma_0)}{w_i^2} \frac{\partial \epsilon_t(\gamma_0)}{\partial \gamma} \frac{\partial \epsilon_t(\gamma_0)}{\partial \gamma'} \right] = E \left[ \frac{h_t(\lambda_0)}{w_i^2} \frac{\partial \epsilon_t(\gamma_0)}{\partial \gamma} \frac{\partial \epsilon_t(\gamma_0)}{\partial \gamma'} \right] \leq C^2 Eh_t < \infty.$$
Similar to the proof of Lemma 4.2 in Ling and McAleer (2003a), we can show that $A$ and $B$ are positive definite. By the central limit theorem, we have that $\frac{dL_{\alpha}(\gamma_0)}{d\gamma} \rightarrow_{\mathcal{L}} N(0, 4B)$. Thus, we have established all the conditions in Theorem 4.1.3 in Amemiya (1985), and hence $\sqrt{n}(\hat{\gamma}_n - \gamma_0) \rightarrow_{\mathcal{L}} N(0, A^{-1}BA^{-1})$. This completes the proof. □

The following Lemma A3(i)–(ii) is Lemma A.2 in Ling (2007) and Lemma A3(iii) is Lemma A.3(i) in Ling (2007).

**Lemma A3.** If Assumptions 1–2 hold, then it follows that

$$
\begin{align*}
(i) \quad & \sup_{\Theta} \left\| \frac{1}{h_t(\lambda)} \frac{\partial h_t(\lambda)}{\partial \delta} \right\| \leq \xi_{\delta t-1}, \\
(ii) \quad & \sup_{\Theta} \left\| \frac{1}{h_t(\lambda)} \frac{\partial^2 h_t(\lambda)}{\partial \delta \partial \delta} \right\| \leq \xi_{\delta t-1}, \\
(iii) \quad & \sup_{\Theta} \left\| \frac{1}{\sqrt{h_t(\lambda)}} \frac{\partial h_t(\lambda)}{\partial \gamma} \right\| \leq \xi_{\gamma t-1},
\end{align*}
$$

where $\xi_{\delta t-1} = C(1 + \sum_{i=1}^{\infty} \rho^{|i|} |y_{t-i}|^{|i|})$ with constants $\rho \in (0, 1)$ and $C$ for any $t_1 > 0$.

To prove Theorem 2, we need to introduce another three lemmas. For their proofs, we need the condition that $E|\eta_t|^{2+i} < \infty$ for some $i_1 > 0$. Here and in the sequel, $l_t(\delta) = l_t(\lambda)|_{\gamma=\gamma_0}$ and $h_t(\delta) = h_t(\lambda)|_{\gamma=\gamma_0}$.

**Lemma A4.** If Assumptions 1–2 hold with $E|\eta_t|^{2+i} < \infty$ for some $i > 0$, then it follows that

$$
\sup_{\delta \in \Theta_t} \left| \frac{1}{n} \sum_{t=1}^{n} [\tilde{h}_t(\delta) - l_t(\delta)] \right| = o_P(1).
$$

**Proof.** Since $\tilde{\xi}_{\gamma t}$ in Lemma A2 is strictly stationary with $E\tilde{\xi}_{\gamma t}^2 < \infty$, we have that $\max_{1 \leq t \leq n} \tilde{\xi}_{\gamma t} / \sqrt{n} = o_P(1)$. By Taylor’s expansion, Lemma A2(i), and Theorem 1(ii), it follows that

$$
\tilde{\epsilon}_t = \epsilon_t + (\gamma_n - \gamma_0) \frac{\partial E(\gamma_0)}{\partial \gamma} = \epsilon_t + o_P(1),
$$

(A5)

where $o_P(1)$ holds uniformly in $t$, and $\gamma_0$ lies between $\gamma_0$ and $\gamma_n$. By (A5), we can readily show that

$$
\sup_{\delta \in \Theta_t} \left| \frac{1}{n} \sum_{t=1}^{n} \tilde{\epsilon}_t^2 - \epsilon_t^2 \right| = o_P(1),
$$

(A6)

since $\tilde{h}_t(\delta) \geq g_0$ uniformly in $\delta \in \Theta_t$. Note that

$$
\tilde{h}_t(\delta) = h_t(\delta) + (\gamma_n - \gamma_0) \frac{\partial h_t(\lambda^*)}{\partial \gamma},
$$

(A7)

where $\lambda^* = (\gamma_0, \delta^*)$ and $\gamma_0$ lies between $\gamma_0$ and $\gamma_n$. By Lemma A1(ii), we can show that $E(\tilde{\epsilon}_t^2 \tilde{\xi}_{\gamma t}) < \infty$ as $\tilde{h}_t$ is small enough. By Lemma A3(iii) and the ergodic theorem, it follows that

$$
\sup_{\lambda \in \Theta_t} \left| \frac{1}{n} \sum_{t=1}^{n} \tilde{\epsilon}_t^2 \frac{\partial h_t(\lambda)}{\partial \gamma} \right| \leq \frac{1}{n} \sum_{t=1}^{n} \tilde{\epsilon}_t^2 \tilde{\xi}_{\gamma t}^2 = O_P(1),
$$
as \( \delta_1 \) is small enough. Thus,

\[
\frac{1}{n} \sum_{i=1}^{n} \frac{\varepsilon_i^2}{h_i(\delta)} \leq \frac{2}{\delta_0^{-1+i_1}} \sum_{i=1}^{n} \left| \frac{1}{h_i(\delta)} - \frac{1}{h_i(\delta)} \right|^{i_1} \\
\leq \frac{2}{\delta_0^{1+i_1}} \sum_{i=1}^{n} \left| h_i(\delta) - h_i(\delta) \right|^{i_1} \\
\leq \frac{2}{\delta_0^{1+i_1}} \sum_{i=1}^{n} \left| \frac{\partial h_i(\lambda^*)}{\partial \gamma} \right|^{i_1} = o_p(1),
\]

(A8)

where \( o_p(1) \) holds uniformly in \( \delta \in \Theta_\delta \). By (A6) and (A8), it follows that

\[
\sup_{\delta \in \Theta_\delta} \left| \frac{1}{n} \sum_{i=1}^{n} \frac{\varepsilon_i^2}{h_i(\delta)} - \frac{\varepsilon_i^2}{h_i(\delta)} \right| = o_p(1).
\]

(A9)

Moreover, we can show that

\[
\frac{1}{n} \sum_{i=1}^{n} \left[ \log h_i(\delta) - \log h_i(\delta) \right] I\{h_i(\delta) \geq h_i(\delta)\} \\
= \frac{1}{n} \sum_{i=1}^{n} \left[ \log \left( 1 + (\gamma_n - \gamma_0) \frac{1}{h_i(\delta)} \right) \right] I\{h_i(\delta) \geq h_i(\delta)\} \\
\leq \frac{1}{n} \sum_{i=1}^{n} \log \left( 1 + \eta \frac{\partial h_i(\lambda^*)}{\partial \gamma} \right)^{i_1},
\]

where \( \lambda^* = (\gamma', \delta')' \) and \( \gamma^* \) lies between \( \gamma_0 \) and \( \gamma_n \). Note that there exists an \( \delta_1 \) such that \( E \sup_{\lambda \in \Theta} \| \frac{\partial h_i(\lambda)}{\partial \gamma} \|^{i_1} \leq \infty \). For any \( \varepsilon > 0 \), first taking \( \eta \) small enough such that \( \log [1 + \eta \frac{\partial h_i(\lambda)}{\partial \gamma} \|^{i_1}] < \varepsilon^2 \delta_1 \) and then taking \( n \) large enough such that \( P(|\gamma_n - \gamma_0| \geq \eta) \leq \varepsilon \), it follows that

\[
P \left( \frac{1}{n} \sum_{i=1}^{n} \log \left[ 1 + \frac{1}{\delta_0} \| \gamma_n - \gamma_0 \| \sup_{\lambda \in \Theta} \left\| \frac{\partial h_i(\lambda)}{\partial \gamma} \right\| \right]^{i_1} \geq \varepsilon \right) \\
\leq P \left( \frac{1}{n} \sum_{i=1}^{n} \log \left[ 1 + \frac{1}{\delta_0} \| \gamma_n - \gamma_0 \| \sup_{\lambda \in \Theta} \left\| \frac{\partial h_i(\lambda)}{\partial \gamma} \right\| \right]^{i_1} \geq \varepsilon, \| \gamma_n - \gamma_0 \| \leq \eta \right) + \varepsilon \\
\leq \frac{1}{n} \sum_{i=1}^{n} E \log \left[ 1 + \frac{1}{\delta_0} \eta \sup_{\lambda \in \Theta} \left\| \frac{\partial h_i(\lambda)}{\partial \gamma} \right\| \right]^{i_1} + \varepsilon \\
= \frac{1}{n} \sum_{i=1}^{n} E \log \left[ 1 + \frac{1}{\delta_0} \eta \sup_{\lambda \in \Theta} \left\| \frac{\partial h_i(\lambda)}{\partial \gamma} \right\| \right]^{i_1} + \varepsilon \\
\leq \frac{1}{n} \log \left[ 1 + \frac{1}{\delta_0} \eta \sup_{\lambda \in \Theta} \left\| \frac{\partial h_i(\lambda)}{\partial \gamma} \right\| \right]^{i_1} + \varepsilon \leq 2 \varepsilon,
\]

where the last second inequality holds by Jensen’s inequality. Thus, as \( n \) is large enough,

\[
P \left( \sup_{\delta \in \Theta_\delta} \left| \frac{1}{n} \sum_{i=1}^{n} \left[ \log h_i(\delta) - \log h_i(\delta) \right] I\{h_i(\delta) \geq h_i(\delta)\} \right| \geq \varepsilon \right) \leq 2 \varepsilon.
\]

Similarly, we can show that

\[
P \left( \sup_{\delta \in \Theta_\delta} \left| \frac{1}{n} \sum_{i=1}^{n} \left[ \log h_i(\delta) - \log h_i(\delta) \right] I\{h_i(\delta) \leq h_i(\delta)\} \right| \geq \varepsilon \right) \leq 2 \varepsilon.
\]

Furthermore, by (A9), the conclusion holds. This completes the proof. \( \square \)
Lemma A5. If the assumptions of Lemma A3 hold, then it follows that

\[
(i) \quad \sup_{\delta \in \Theta_3} \left\| \frac{1}{n} \sum_{i=1}^{n} \left[ \frac{\partial^2 I_i(\delta)}{\partial \delta \partial \delta'} - \frac{\partial^2 I_i(\delta)}{\delta^2} \right] \right\| = o_p(1),
\]

\[
(ii) \quad E \sup_{\delta \in \Theta_3} \left\| \frac{\partial^2 I_i(\delta)}{\delta^2} \right\| < \infty.
\]

Proof. Denote \( \hat{V}_i(\delta) = \hat{h}_i^{-1}(\delta) [\partial \hat{h}_i(\lambda) / \partial \delta] \) and similarly for \( V_i(\delta) \). Then

\[
\frac{\partial^2 I_i(\delta)}{\delta \delta'} = -\frac{1}{2} \hat{V}_i(\delta) \frac{\hat{h}_i'(\delta)}{\hat{h}_i(\delta)} + \left[ \frac{\hat{h}^2_i}{\hat{h}_i(\delta)} - 1 \right] \frac{\partial \hat{V}_i(\delta)}{\delta}. \tag{A10}
\]

Similarly, we can have the formula of \( \frac{\partial^2 I_i(\delta)}{\delta \delta} \). By (A5), we have

\[
\frac{1}{n} \sum_{i=1}^{n} V_i(\delta) \hat{V}_i'(\delta) \frac{\hat{h}^2_i}{\hat{h}_i(\delta)} = \frac{1}{n} \sum_{i=1}^{n} V_i(\delta) \hat{V}_i'(\delta) \frac{\hat{h}^2_i}{\hat{h}_i(\delta)} + \frac{\rho_p(1)}{n} \sum_{i=1}^{n} V_i(\delta) \hat{V}_i'(\delta) \frac{\hat{h}^2_i}{\hat{h}_i(\delta)}
\]

\[
+ o_p(1) \sum_{i=1}^{n} V_i(\delta) \hat{V}_i'(\delta) \frac{1}{\hat{h}_i(\delta)}. \tag{A11}
\]

By Lemma A3(i), \( \sup_{\delta \in \Theta_3} \| \hat{V}_i(\delta) \| \leq \sup_{\Theta} \| h_i^{-1}(\lambda) [\partial h_i(\lambda) / \partial \delta] \| \leq \xi_{\delta t - 1} \). Furthermore, by Lemma A1, we can take \( t_1 \) in \( \xi_{\delta t - 1} \) small enough such that the leading factors in the last terms are bounded uniformly in \( \delta \in \Theta_3 \). Thus, the last two terms are \( o_p(1) \), and hence it follows that

\[
\frac{1}{n} \sum_{i=1}^{n} V_i(\delta) \hat{V}_i'(\delta) \frac{\hat{h}^2_i}{\hat{h}_i(\delta)} = \frac{1}{n} \sum_{i=1}^{n} V_i(\delta) \hat{V}_i'(\delta) \frac{\hat{h}^2_i}{\hat{h}_i(\delta)} + o_p(1), \tag{A12}
\]

where \( o_p(1) \) holds uniformly in \( \delta \in \Theta_3 \). Moreover, by Lemma A3(i), we have

\[
\frac{1}{n} \sum_{i=1}^{n} \hat{V}_i(\delta) \left\| \hat{V}_i(\delta) - V_i(\delta) \right\| \frac{\hat{h}^2_i}{\hat{h}_i(\delta)}
\]

\[
\leq \frac{1}{n} \sum_{i=1}^{n} V_i(\delta) \left\| \hat{V}_i(\delta) - V_i(\delta) \right\| \left[ \left\| V_i(\delta) \right\| + \left\| V_i(\delta) \right\| \right] \frac{1}{\hat{h}_i(\delta)}
\]

\[
\leq \frac{2}{n} \sum_{i=1}^{n} \xi_{\delta t - 1} \left\| \hat{V}_i(\delta) - V_i(\delta) \right\| \frac{\hat{h}^2_i}{\hat{h}_i(\delta)}. \tag{A13}
\]

By Lemma A1 and taking \( t \) and \( t_1 \) in \( \xi_{\delta t - 1} \) small enough, we have

\[
E \max_{1 \leq n < \infty} \sup_{\delta \in \Theta_3} \left[ \xi_{\delta t - 1} \left\| \hat{V}_i(\delta) - V_i(\delta) \right\| \frac{\hat{h}^2_i}{\hat{h}_i(\delta)} \right] \leq C E \xi_{\delta t - 1}^2 < \infty,
\]

where \( C \) is a constant. By the dominated convergence theorem, we can show that

\[
\lim_{n \to \infty} E \sup_{\delta \in \Theta_3} \left[ \xi_{\delta t - 1} \left\| \hat{V}_i(\delta) - V_i(\delta) \right\| \frac{\hat{h}^2_i}{\hat{h}_i(\delta)} \right] = 0.
\]

Thus, we can show that (A13) is \( o_p(1) \) uniformly in \( \delta \in \Theta_3 \). Furthermore, by (A12),

\[
\frac{1}{n} \sum_{i=1}^{n} \hat{V}_i(\delta) \hat{V}_i'(\delta) \frac{\hat{h}^2_i}{\hat{h}_i(\delta)} = \frac{1}{n} \sum_{i=1}^{n} V_i(\delta) V_i'(\delta) \frac{\hat{h}^2_i}{\hat{h}_i(\delta)} + o_p(1). \tag{A14}
\]
Similarly, we can show that

\[ \frac{1}{n} \sum_{i=1}^{n} \nabla_i \nabla_i^\top = \frac{1}{n} \sum_{i=1}^{n} \nabla_i \nabla_i^\top + o_p(1). \] (A15)

Similar to (A8), we can show that

\[ \frac{1}{n} \sum_{i=1}^{n} \nabla_i \nabla_i^\top = \frac{1}{n} \sum_{i=1}^{n} \nabla_i \nabla_i^\top + o_p(1). \] (A16)

The \( o_p(1) \) in (A14)–(A16) hold uniformly in \( \delta \in \Theta_3 \). By (A12) and (A14)–(A16), we have that

\[ \frac{1}{n} \sum_{i=1}^{n} \nabla_i \nabla_i^\top = \frac{1}{n} \sum_{i=1}^{n} \nabla_i \nabla_i^\top + o_p(1). \]

We can show that a similar equation holds for other terms in (A10). Thus, (i) holds. By Lemmas A2–A3, it is straightforward to show that (ii) holds. This completes the proof. \( \square \)

**Lemma A6.** [Lemma A.7 in Ling (2007)] If the conditions in Theorem 1 holds and \( \sqrt{n} \| \lambda - \lambda_0 \| \leq M \), then it follows that

\[ \frac{1}{n} \sum_{i=1}^{n} \frac{\partial^2 l_i(\lambda)}{\partial \lambda \partial \lambda^\top} = \frac{1}{n} \sum_{i=1}^{n} \frac{\partial^2 l_i(\lambda_0)}{\partial \lambda \partial \lambda^\top} + o_p(1), \]

for any fixed constant \( M \).

**Proof of Theorem 2.** Let \( L_n(\delta) = \sum_{i=1}^{n} l_i(\delta) / n \). First, the space \( \Theta_3 \) is compact and \( \delta_0 \) is an interior point in \( \Theta_3 \). Second, \( L_n(\delta) \) is continuous in \( \delta \in \Theta_3 \) and is a measurable function of \( \{y_s, s = t, t-1, \cdots \} \) for all \( \delta \in \Theta_3 \). Third, by Lemma A2(ii), there exist constants \( C \) and \( \rho \in (0, 1) \) such that

\[ 1 \leq \frac{h_l(\delta)}{\delta_0} \leq C(1 + \sum_{i=1}^{\infty} \rho^i | e_{t-i} |)^2, \]

uniformly in \( \delta \in \Theta_3 \). By Jensen’s inequality, \( E \sup_{\delta \in \Theta_3} | \log h(\delta) | \leq E \sup_{\delta \in \Theta_3} \log | h(\delta) / \delta_0 | + | \log \delta_0 | < \infty \). Thus, we can show that \( E \sup_{\delta \in \Theta_3} | l_i(\delta) | < \infty \). By the ergodic theorem, \( \sum_{t=1}^{\infty} l_i(\delta) / n \to_p E l_i(\delta) \) for each \( \delta \). Furthermore, by Theorem 3.1 in Ling and McAleer (2003a), \( \sum_{t=1}^{\infty} l_i(\delta) / n \to_p E l_i(\delta) \) uniformly in \( \Theta_3 \). By Lemma A4, \( L_n(\delta) \to_p E l_i(\delta) \) uniformly in \( \Theta_3 \). Fourth, similar to the proof of Lemma A.10 of Ling (2007), we can show that \( E l_i(\delta) \) reaches its unique maximum at \( \delta = \delta_0 \). Thus, we have established all the conditions for consistency in Theorem 4.1.1 in Amemiya (1985) and hence (i) holds.

For (ii), we first have a consistent estimator \( \hat{\delta}_n \) of \( \delta_0 \). Second, \( \partial^2 L_n(\delta) / \partial \delta \partial \delta^\top \) exists and is continuous in \( \Theta_3 \). Third, by Lemma A5(ii), \( E \sup_{\delta \in \Theta_3} \| \partial^2 l_i(\delta) / \partial \delta \partial \delta^\top \| < \infty \). By the ergodic theorem and Theorem 3.1 in Ling and McAleer (2003a), we can show that \( \sum_{t=1}^{\infty} | \partial^2 l_i(\delta) / \partial \delta \partial \delta^\top | / n \to_p E | \partial^2 l_i(\delta) / \partial \delta \partial \delta^\top | \) uniformly in \( \Theta_3 \). Since \( E | \partial^2 l_i(\delta) / \partial \delta \partial \delta^\top | \) is continuous in terms of \( \delta \), we can show that \( \sum_{t=1}^{\infty} | \partial^2 l_i(\delta_n) / \partial \delta \partial \delta^\top | / n \to_p -EH_{\delta n} / 4 \) for any sequence \( \delta_n \), such that \( \delta_n \to_p \delta_0 \). Furthermore, by Lemma A5(ii), \( \partial^2 L_n(\delta_n) / \partial \delta \partial \delta^\top \to_p -EH_{\delta n} / 4 \) for any sequence \( \delta_n \), such that \( \delta_n \to_p \delta_0 \). Fourth, by Taylor’s expansion, it follows that

\[ \frac{1}{\sqrt{n}} \sum_{t=1}^{n} \frac{\partial l_i(\delta_n)}{\partial \delta} = \frac{1}{\sqrt{n}} \sum_{t=1}^{n} \frac{\partial l_i(\delta_0)}{\partial \delta} + \frac{1}{\sqrt{n}} \sum_{t=1}^{n} \left[ \frac{\partial^2 l_i(\lambda^* \gamma)}{\partial \delta \partial \gamma^\top} \right] (\gamma_n - \gamma_0), \]
where $\lambda^* = (\gamma^*, \delta_0^*)'$ and $\gamma^*$ lies between $\gamma_0$ and $\gamma$. By Lemma A6, we have

$$\frac{1}{n} \sum_{t=1}^{n} \left[ \frac{\partial^2 l_n(\lambda^*)}{\partial \gamma^2} \right] = \mathbb{E} \left[ \frac{\partial^2 l_n(\lambda_0)}{\partial \gamma^2} \right] + o_p(1) = -\frac{1}{2} ED_t + o_p(1).$$

Furthermore, by Theorem 1, we can show that

$$\frac{1}{\sqrt{n}} \sum_{t=1}^{n} \frac{\partial l_n(\delta_0)}{\partial \delta} = \frac{1}{\sqrt{n}} \sum_{t=1}^{n} \frac{\partial l_n(\delta_0)}{\partial \delta} + \frac{ED_t A^{-1}}{2\sqrt{n}} \sum_{t=1}^{n} \frac{\partial \varepsilon_t(\gamma_0)}{\partial \gamma} + o_p(1).$$

By Lemma A4, we can see that $E \| H_{\delta} \| < \infty$ and $E \| \partial l_n(\delta_0) / \partial \delta \|^2 < \infty$. Thus, $\Omega_{\delta}$ is finite. Similar to the proof of Lemma 4.2 in Ling and McAleer (2003a), we can show that $EH_{\delta} \Omega_{\delta}$ and $\Omega_{\delta}$ are positive definite. By the central limit theorem, we have that $n^{1/2} \partial L_n(\delta_0) / \partial \delta \rightarrow L \mathcal{N}(0, \Omega_{\delta}^{-1} H_{\delta})$. Thus, we have established all the conditions in Theorem 4.1.3 in Amemiya (1985), and hence $\sqrt{n}(\hat{\delta} - \delta_0) \rightarrow L \mathcal{N}(0, E^{-1} H_{\delta} \Omega_{\delta} E^{-1} H_{\delta})$. This completes the proof. $\square$

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