KINEMATIC SIGNATURES OF SUBVIRIAL INITIAL CONDITIONS IN YOUNG CLUSTERS

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ABSTRACT

Motivated by kinematic observations of young embedded clusters, this paper explores possible kinematic signatures produced by asphericity and departures from initial virial equilibrium in these systems. Specifically, the kinematic quantity that is measured and calculated in this study is the distribution of the line-of-sight velocities as a function of position along the cluster. Although clusters are found within a wide range of sizes, we focus on the regime with stellar membership \( N \sim 10^3 \). The gravitational potential of these young clusters is dominated by the gas, and the geometry of the gas distribution is generalized to include axisymmetric (and triaxial) forms. With this loss of symmetry, the kinematic results thus depend on viewing angle. This work also considers the stars to begin their trajectories with subvirial speeds, as indicated by observations of core motions in such clusters. Our results determine the conditions necessary for the kinematic signature to display interesting structure, i.e., a non-spherical potential, a viewing angle that is not along one of the principal axes, and subvirial starting conditions. We characterize the effects on this signature due to projection angle, initial stellar velocities, cluster elongation, and star formation efficiency. Finally, we compare our theoretical results to recent kinematic observations of the Orion Nebula Cluster; we find that the observations can be explained provided that the cluster is non-spherical, starts with subvirial initial velocities, and is not viewed along a principal axis.

Key words: methods: \( N \)-body simulations – open clusters and associations: general – stars: formation – stellar dynamics

1. INTRODUCTION

Most stars are thought to form within clusters of some type (e.g., Lada & Lada 2003; Porras et al. 2003), although a great deal of controversy remains concerning the distribution of cluster properties. Nonetheless, given that stars form in clusters, two overarching questions immediately arise. The first considers the clusters as astrophysical objects: (1) how can molecular clouds produce aggregates of \( N > 100 \) stars with centrally concentrated surface density, with the massive stars near the center, and with a stellar mass distribution that follows the IMF, all within a few pc and within a few Myr? A second vital question then becomes: (2) if stars form in clusters, how does the cluster environment affect star formation and the accompanying process of planet formation? A complete understanding of star and planet formation requires detailed answers to both questions. However, this paper will focus on one specific issue within this larger context. Observed young embedded stellar clusters display departures from both spherical symmetry and initial virial equilibrium, and this paper will explore the effects of these complications on the kinematics of cluster members through \( N \)-body simulations. These results, in turn, will help provide a contribution to the overarching questions posed above.

Departures from spherical symmetry in star-forming regions have long been known, but have been little studied. On the scale of cluster themselves (with radii of a few pc, and masses of 100–3000 \( M_\odot \)), for example, some systems are categorized as irregular (Lada & Lada 2003), or filamentary (Walsh et al. 2004), or otherwise described as non-spherical (Allen et al. 2007). Furthermore, the star formation efficiencies are low, so that the gravitational potential in these systems is dominated by the mass of the gas (at least in the early phases of evolution, before gas expulsion). As a result, the gas potential must be generalized to include the observed departures from spherical symmetry (see Adams et al. 2007 and Section 2). For completeness, we also note that on the smaller scale of cores (or clumps or kernels) that represent individual star formation events, the precollapse gas is observed to be non-spherical, with typical aspect ratios of 2:1 (e.g., Myers et al. 1991; Ryden 1996).

Observations are starting to show that clusters begin their evolution with subvirial initial conditions, and hence this complication must be included in our simulated clusters. In many regions, prestellar clumps are observed to move subsonically before the clumps form stars (Peretto et al. 2006; Walsh et al. 2004; André 2002; Kirk et al. 2007), implying that newly formed stars begin their dynamical evolution with subvirial speeds. Motivated by such observations, our work considers clusters that are seeded with subvirial stellar velocities. As such, our \( N \)-body simulations (see Section 2) differ from those of many preceding studies (though not all, see Bonnell & Davies 1998; Adams et al. 2006) that assume the initial phase space variables of the stars are close to virial equilibrium. Subvirial initial conditions can have a significant impact on the early cluster evolution (Adams et al. 2006), and are thus considered herein.

The theoretical work presented here provides a determination of the kinematic signature of young embedded clusters with both subvirial starting conditions and non-spherical gas potentials. Fortunately, astronomical observations are now becoming available to compare with these theoretical calculations. In this paper, we focus on clusters of moderately large size, with stellar membership \( N \sim 10^3 \), appropriate for the Orion Nebula Cluster (ONC). Clusters of this size are large enough for interesting kinematic signatures to arise in observations, and small enough that many such clusters are expected within the galactic cluster population. In addition, the ONC is an example of a non-spherical cluster as the stellar population is elongated north to south along the filament of dense molecular gas in the region (Hillenbrand & Hartmann 1998). Recent observations in the ONC (Fűrész et al. 2008; Tobin et al. 2009, TO9 hereafter) display a gradient in the radial velocity structure along the length of...
the cluster, much like that expected for the elongated subvirial clusters considered herein.

This paper is organized as follows. In Section 2, we outline the theoretical approach used in this paper. Specifically, we describe the $N$-body codes, the required number of realizations of the numerical experiments, the implementation of subvirial starting speeds, the inclusion axisymmetric and triaxial gas distributions, as well as the specification of simulation parameters. We then present the theoretical results of our simulations in Section 3, with a focus on the velocity signatures produced by the departures from equilibrium and spherical symmetry. In Section 4, we compare our results to observations, primarily the kinematic velocity measurements recently carried out in the ONC. We find good qualitative agreement, and reasonable quantitative agreement, and suggest that the observed kinematic signature requires subvirial starting conditions, nonspherical potentials, and viewing angles that do not coincide with the principal axes of the systems. These conclusions and other results are summarized in Section 5, along with a discussion of their implications.

2. METHODS

$N$-body simulation techniques are used to calculate the dynamics of young stellar clusters during the embedded star-forming epoch. We consider clusters with nonspherical geometries and subvirial initial velocities and study the observed kinematics of these clusters. In this section, we discuss the $N$-body code used, the simulation parameters chosen, and the experiments performed to identify and characterize kinematic signature in nonspherical clusters with subvirial initial conditions.

2.1. N-Body Simulation Techniques

The dynamical evolution of a young embedded cluster depends on its initial spatial distribution, the distribution and removal mechanism of the embedding gas, the star formation history, and is especially sensitive to the initial velocity distribution (e.g., Adams et al. 2006). In this paper, we complete a suite of $N$-body simulations of young embedded clusters to understand how the cluster’s initial spatial and velocity distribution imprints itself on the evolved cluster’s kinematic structure. The NBODY2 direct integration code developed by Aarseth (2001) is used as a starting point to calculate the cluster’s dynamics from the star-forming epoch out to ages of 10 Myr. As outlined below, we modify the code to include specific stellar and gas distributions and star formation epochs that are similar to those observed in young embedded clusters.

Distributions of stellar positions and velocities are required to characterize kinematic signatures in these young clusters. We find that ~50 equivalent realizations of each set of cluster initial conditions are required to provide statistically robust distributions of stellar positions and radial velocities. This study focuses on the kinematic signatures produced by two different contributions to the initial conditions commonly present in young embedded clusters: asphericity (combined with effects due to projection of a three-dimensional cluster onto the two-dimensional sky), and subvirial initial velocities. In addition, we consider the effect of extinction on the observed kinematic structure of young clusters.

Cluster evolution is numerically integrated from the star formation epoch (0–1 Myr) through the gas removal phase (at $t = 5$ Myr) out to ages of 10 Myr (see Section 2.2 for further detail). After 50 realizations of each set of initial conditions are completed, the results are combined to produce distributions of stellar positions and velocities. The simulations provide three-dimensional position and velocity information for each stellar member at intervals of 0.1 Myr. These six phase space coordinates are reduced to two position coordinates in the plane of the sky and two velocity components, one along the line of sight (radial velocity) and one in the plane of the sky (transverse velocity). For the sake of definiteness, the $\hat{z}'$-projected axis is defined by the projection of the three-dimensional $\hat{z}$-axis (the major axis in elongated clusters) onto the plane perpendicular to the line of sight. The terms ‘north’ and ‘south’ with reference to projections of simulated clusters correspond to positive and negative $\hat{z}'$ values, respectively. This nomenclature is arbitrary and has been chosen to coincide with that of the ONC, which is elongated north to south and displays north–south asymmetry in the radial velocity structure (see Section 4).

2.2. Simulation Parameters

Cluster membership $N$. We consider moderately large young clusters comparable in size to the Orion star-forming region. Specifically, our simulated clusters contain $N = 2000$ or 2700 stars. Estimates of the stellar population of the ONC vary depending on the cluster radius adopted, and our choices of $N$ roughly reflect the range of this variation (e.g., Hillenbrand & Hartmann (1998) advocate $N = 2300$, near the center of this range). We found that there were no significant differences in the kinematic signature observed in clusters of 2000 and 2700 stars. Another motivation for our choice of cluster size is that clusters of this size have large enough memberships that kinematic signatures may be identified in the data from observed clusters and compared to the results presented in this study.

The stellar masses are sampled from the log-normal analytic fit presented by Adams & Fatuzzo (1996) to the standard IMF of Miller & Scalo (1979). The masses range from 0.07 to 10 $M_\odot$. A limited number of simulations with equal stellar masses were completed, and we found that the kinematic signature discussed herein was present in both the single stellar mass clusters and those with a more realistic stellar mass distribution.

Stellar distribution. One goal of this study is to compare kinematic signatures of clusters with spherical geometries to those of elongated clusters. Spherical clusters have centrally concentrated stellar distributions described by an $r^{-1}$ density profile. Two elongated stellar distributions are considered: uniform density prolate spheroids and centrally concentrated clusters with $\rho \sim m^{-1}$, where $m^2 = x^2/a^2 + y^2/b^2 + z^2/c^2$ is the triaxial coordinate. We compare elongated clusters with different aspect ratios to characterize the effect of cluster elongation on the observed kinematic signature. Table 1 summarizes the initial stellar density distributions used in the cluster simulations.

Initial speeds. Initial stellar velocities are sampled from a uniform distribution within a unit sphere, producing an isotropic and position-independent velocity distribution. The velocities are then scaled to produce a cluster in a particular virial state, defined by the virial ratio $Q \equiv |K/W|$, where $K$ is the total kinetic energy of the cluster and $W$ is the total virial potential energy of the cluster. A cluster in virial equilibrium is defined to have $Q = 0.5$. Simulations of clusters with virialized initial velocities are compared to clusters with subvirial initial velocities. The subvirial clusters are chosen to have $Q = 0.04$ or 0.15, which corresponds to initial velocities that are approximately one-third or one-half of the virial velocity, respectively.
Star formation history. The simulated clusters have a star formation epoch that lasts for the first 1 Myr of the cluster’s evolution. During simulation initialization each star, regardless of mass or initial position within the cluster, is assigned a random formation time between 0 and 1 Myr (with a uniform distribution, independent of stellar mass, over this interval). A star is then tied to its formation site (chosen as described above) until its collapse phase of star formation is complete. That is, the stars are initially included in the simulation as point masses, but are held at a fixed position until their formation time. After that time, the star becomes free to move through the total gravitational potential of the cluster with an initial velocity sampled from the distribution described above. As a result, the stars do not execute ballistic orbits until after they have formed. For completeness, we note that stellar evolution is not included in these simulations.

We vary the star formation efficiency (SFE) from 17% to 50%, which spans the range of mass estimates of the gas in the region of the ONC. It is important to note that although the evolution of a cluster subsequent to gas removal depends strongly on the SFE, its evolution prior to gas removal is more sensitive to the virial ratio than it is to the SFE alone. In other words, provided that the stars are moving with sufficient velocities to account for the additional potential due to excess gas (i.e., their virial ratios are comparable), the evolution of a cluster with an SFE of 33% or 50% will be qualitatively similar during the embedded stage. Increasing the SFE will, however, decrease the average virial velocity. After gas is removed from the cluster, the subsequent dynamical evolution does depend on the SFE. Of course, increasing the SFE will increase the rate of close encounters, but this effect is modest on the (short) timescales of interest here (Adams et al. 2006).

Embedding gas distributions. We assume that the distributions of stars in a cluster roughly traces the geometry and density of the embedding gas. Thus, a spherical centrally concentrated Hernquist profile (Hernquist 1990) is chosen to represent the embedding gas in a spherical cluster (see Adams et al. 2006).

Likewise, the elongated stellar distributions are embedded in elongated gas potentials. Specifically, the uniform density stellar distributions are embedded in a uniform density gas distribution that is twice the extent of the stellar distribution. The homoeoid theorem states that the net force on a particle within a uniform density homoeoid shell is zero. Thus, the larger gas distribution allows for a simpler computation of the force and potential terms due to the embedding gas without changing the dynamics of the system (Binney & Tremaine 1987).

The centrally concentrated prolate clusters are embedded in a static gas potential of the form \( \rho \sim m^{-1} \), where \( m \) is the generalized coordinate. Calculation of the force terms, analytic expressions for the potential, and a discussion of orbits and orbit instabilities within this triaxial potential were presented in Adams et al. (2007). The gas distributions and associated parameters are summarized in Table 2.

Observations indicate that embedding gas does not remain in young clusters for a long time. After a few million years, winds from hot young stars begin to carve out the embedding gas and very few embedded clusters are found with ages greater than ~5 Myr. Our simulations account for gas removal as a temporal step function in the evolution of the static gas potential: at \( t = 5 \) Myr, the gas potential is completely removed from the cluster which then continues to evolve due to interactions between the stars. After gas removal, the cluster expands and a significant fraction of the members become gravitationally unbound.

2.3. Numerical Experiments

In this section, we discuss the specific parameters that were varied to study the effects of particular initial conditions on the kinematic structure observed in the clusters. A more detailed discussion of each experiment’s initial setup and result is reserved until Section 3.

Cluster geometry and virial ratio. We compare the evolution of clusters under various assumptions of initial geometry and virial balance. Specifically, we compare centrally concentrated (\( \rho \sim r^{-1} \)) spherical clusters with subvirial (\( Q = 0.04 \)) and virial (\( Q = 0.5 \)) initial velocities to uniform density elongated clusters with similarly subvirial and virial velocities. The spherical clusters are 2 pc in radius, and the elongated clusters have axis parameters \( a = b = 2 \) pc and \( c = 4 \) pc. Each of these clusters had stellar membership \( N = 2000 \) and an SFE of 50%. We find that only clusters with subvirial initial velocities and elongated geometries produce significant gradients in the radial velocity along the length of the cluster. The observed radial velocity gradients are thus a combined effect of global collapse and the projection of a nonspherical cluster. Hereafter, the term “kinematic signature” refers to this radial velocity gradient. This kinematic signature is discussed in detail in Section 3.1.

Table 1

| Description      | Density Profile | Parameters |
|------------------|-----------------|------------|
| Spherical        | \( \rho(\xi) = \frac{\rho_0}{\xi(1 + \xi^2)} \),  \( \xi = r/r_0 \) | \( \rho_0 < \xi < 1 \) |
| Uniform spheroid | \( \rho(m) = \left\{ \begin{array}{ll} \rho_0, & 0 < m \leq 1 \\ 0, & m > 1 \end{array} \right\} \) | \( m^2 = (x/a)^2 + (y/b)^2 + (z/c)^2 \) |
| 1/m spheroid     | \( \rho(m) = \left\{ \begin{array}{ll} \rho_0/m, & 0 < m \leq 1 \\ 0, & m > 1 \end{array} \right\} \) | \( m^2 = (x/a)^2 + (y/b)^2 + (z/c)^2 \) |

Table 2

| Description      | Density Profile | Parameters |
|------------------|-----------------|------------|
| Spherical        | \( \rho(\xi) = \rho_0/\xi(1 + \xi^2) \),  \( \xi = r/r_0 \) | \( \rho_0 < \xi < 2 \) |
| Uniform spheroid | \( \rho(m) = \left\{ \begin{array}{ll} \rho_0, & 0 < m \leq 2 \\ 0, & m > 2 \end{array} \right\} \) | \( m^2 = (x/a)^2 + (y/b)^2 + (z/c)^2 \) |
| 1/m spheroid     | \( \rho(m) = \rho_0/m, \) | \( m^2 = (x/a)^2 + (y/b)^2 + (z/c)^2 \) |
With the requirements of subvirial velocities and elongated stellar/gas distributions identified as prerequisites for the kinematic signature, we proceed to complete a series of numerical experiments to determine how changing cluster parameters in subvirial elongated clusters changes the observed structure of the signature.

Initial virial ratio. To characterize the effect of subvirial velocities on the kinematic signature, the evolution of centrally concentrated elongated clusters with virial ratio $Q$ ranging from 0.04 to 0.15 is compared. These virial ratios correspond to average initial velocities that are roughly one-third to one-half of the virial velocity and are comparable to prestellar clump velocities observed many star-forming regions including NGC 2264 (Peretto et al. 2006) and Perseus (Kirk et al. 2007).

Cluster elongation. The effect of cluster elongation on the evolved velocity structure of the cluster is studied by comparing subvirial clusters that range from spherical to elongated with aspect ratios ranging from 1 to 4. Recent results from the Spitzer Young Cluster Survey indicate this range of aspect ratios is appropriate, as the clusters in the survey had aspect ratios between 0.53 and 3.88 (R. Gutermuth et al. 2009, in preparation).

Initial density distribution. Another experiment compares subvirial elongated clusters with uniform density distributions to those with $\rho \sim m^{-1}$ to study the effect of the density distribution on the strength of and evolution of the kinematic signature.

Star formation efficiency. To determine the effect of SFE on the kinematic signatures observed in the cluster, we compare subvirial elongated clusters with efficiencies ranging from 17% to 50%.

3. SIMULATION RESULTS

3.1. Radial Velocity Structure Due to Global Collapse and Elongation

We find that radial velocity gradients along the length of the clusters are produced by a combination of two effects: (1) projection of an elongated or nonspherical cluster and (2) subvirial initial velocities. The separation of these two effects is nontrivial, as discussed below.

A cluster that is initially subvirial will collapse as stars in the outer parts of the cluster fall toward the cluster’s center of mass. This collapse takes place because cluster members that are seeded with subvirial velocities are not moving fast enough to remain in orbit (at their starting radial positions) around the cluster’s center. Instead, they fall through the gravitational potential, gain kinetic and potential energy, and eventually reach an equilibrium state in which the virial theorem is satisfied. Thus, during the first crossing time, a subvirial cluster will collapse significantly as the stellar velocities increase. Figure 1 compares the mean cluster radius and velocity dispersion as a function of time for spherical clusters with both virial and subvirial initial conditions. The overall cluster collapse and velocity enhancement in subvirial clusters are clearly demonstrated by these plots.

During the initial collapse phase, the velocity vectors of the cluster members are preferentially directed toward the center of mass until the stars pass close to the cluster’s center and continue on (mostly) radial trajectories outward. During this first crossing time, some close encounters may cause the individual stellar motions to deviate from this general pattern. As shown in Adams et al. (2006), however, close encounters are relatively rare on these short timescales (a few Myr or less) and the aggregate dynamics are thus dominated by this initial collapse and re-expansion.

Elongated subvirial clusters display a gradient in the radial velocity along the direction of elongation due to this initial collapse. For example, consider a cluster with its major axis in the $\hat{z}$-axis direction and let the system be observed along a line of sight that is less than $90^\circ$ from the major axis. For clarity, we define north and south to be the projected positive and negative $\hat{z}$-axes, respectively. During the first half of a crossing time, the northern portion of the cluster appears to be redshifted while the lower portion of the cluster appears more blueshifted. This asymmetry results in a radial velocity gradient along the extent of the cluster.

Figure 1. Top panel displays the evolution of the mean radius of a spherical cluster with virial (dashed curve) and subvirial (solid curve) initial velocities. The bottom panel displays the evolution of the velocity dispersion of a spherical cluster with virial (dashed curve) and subvirial (solid curve) initial velocities.

Figure 2. Diagram represents an elongated collapsing cluster which is viewed along a line of sight not coincident with a primary axis. During the initial (collapse-like) phase of a cluster with subvirial initial conditions, the upper portion of the cluster will appear redshifted while the lower portion of the cluster appears more blueshifted. This asymmetry results in a radial velocity gradient along the extent of the cluster.
Figure 3. Radial velocity as a function of $z'$ position for a differing geometries, initial velocity distributions, and projections for simulated embedded clusters. The mean radial velocity (averaged over 0.2 pc bins) is indicated by the data points. The error bars correspond to the standard deviation of the radial velocity distribution within the bins. The panels correspond to differing initial geometries, initial velocity distribution, and projections of simulated embedded clusters: (a) spherical cluster, with subvirial initial conditions; (b) elongated cluster, with subvirial initial conditions, and viewing angle of $0^\circ$ from major axis; (c) elongated cluster, with virial initial conditions, and viewing angle of $30^\circ$ from major axis, and (d) elongated cluster, with subvirial initial conditions, and viewing angle of $30^\circ$ from major axis. The first distribution is shown at time $t = 1.5$ Myr after the start, whereas the other three cases are shown at $t = 2.1$ Myr.

that is not coincident with a principal axis and if the cluster has subvirial velocities. When viewed along a minor axis, a subvirial elongated cluster displays no north–south gradient in the radial velocities, as the stars are preferentially moving perpendicular to the line of sight. Viewed along the major axis, the portion of the cluster moving away from the observer is projected directly onto the region of the cluster moving toward the observer, and hence a gradient is not observed.

Likewise, a virial cluster does not display a strong radial velocity gradient, as it is not globally collapsing and the stellar velocities have no spatial correlation. A very slight gradient is observed in the virial clusters at early times; however, it is approximately 10 times weaker than that observed in the subvirial clusters and is associated with the slight contraction of the simulated virial clusters as the stellar velocities are redistributed from the random isotropic distribution to a true virial distribution (see Figure 1).

A cluster that is undergoing global expansion can also produce a gradient in the radial velocities similar to that observed in the collapsing elongated cluster (Figure 3, panel(d)). However, the signature will differ in shape because the stars that populate outermost spatial bins will not have bound orbits. The stars will not be at the furthest point in their orbits and therefore will not have reduced velocities as they change direction and return to the cluster’s center. Therefore, instead of having an S-shaped kinematic signature, an expanding cluster will have a relatively flat gradient, with no turnover at the endpoints. We also note that rotation of a virial cluster may produce a kinematic signature that is similar to the one observed in subvirial clusters, but only if the rotation takes place around an axis perpendicular to the line of sight.

Figure 3 illustrates the radial velocity signature for various projections of spherical and elongated subvirial and virial clusters. In each panel, the data points correspond to the mean radial velocity of the stars in 0.2 pc bins and the lengths of the error bars correspond to the standard deviation of the velocities within each bin. For completeness, we note that this radial velocity gradient calculated from the simulated clusters is not sensitive to the choice of bin size for bin sizes ranging from 0.05 to 1.0 pc. In individual clusters (such as the ONC), the lower limit of the bin size is determined by small number statistics.

It is clear from this figure that the radial velocity signature is created by a combination of two effects: projection of an elongated cluster and subvirial initial velocities (the latter implies global collapse). The bottom right panel shows the only cluster that demonstrates this kinematic signature. This cluster is elongated, is not viewed along a primary axis, and is seeded with subvirial initial velocities.

One way to characterize the strength of a radial velocity gradient is by using the amplitude of the cumulative velocity distribution, $A_{RV}$. The cumulative radial velocity distribution is created by sorting the individual radial velocity measurements by the $z'$-coordinate and then producing the cumulative distribution from this sorted data set. We normalize this measure by both the number of stars in the cluster, $N$, and the velocity dispersion of the cluster, $\sigma_{RV}$. This procedure results in a (dimensionless) normalized cumulative radial velocity distribution that can be more meaningfully compared across clusters of different sizes and velocity dispersions. An additional advantage of the cumulative velocity distribution is that it is created from individual stellar radial velocities and thus is insensitive to the choice of bin size.

A cluster with no radial velocity gradient will have (on average) the same number of stars with positive and negative radial velocities with respect to the cluster’s center of mass or mean radial velocity. Therefore, the cumulative velocity distribution in such a cluster will fluctuate around zero and be relatively flat as a function of $z'$.

On the other hand, a cluster with a strong gradient along $z'$ will have preferentially more blueshifted stars at the negative
The virial cluster peaks at the subvirial elongated cluster. The cumulative distribution for this signature is more than seven times weaker than in velocity, the cumulative distribution indicates that the strength of Figure 3 appears to have a slight gradient in the radial conditions. Although the virial elongated cluster in panel (c) how this distribution varies for subvirial and virial initial conditions; (b) elongated cluster, with subvirial initial conditions, and viewing angle of 0° from major axis; (c) elongated cluster, with virial initial conditions, and viewing angle of 30° from major axis; and (d) elongated cluster, with subvirial initial conditions, and viewing angle of 30° from major axis. The first distribution is shown at time $t = 1.5$ Myr after the start, whereas the other three cases are shown at $t = 2.1$ Myr.

The $z'$ end of the cluster center and more redshifted stars at the positive $z'$ end of the cluster. Therefore, the cumulative radial velocity distribution will be a decreasing function for $z' < 0$ and an increasing function for $z' > 0$, resulting in a dip in the cumulative radial velocity distribution.

The normalized cumulative radial velocity distributions for the clusters depicted in Figure 3 are displayed in Figure 4. The ranges on the $y$-axes are held constant to emphasize how this distribution varies for subvirial and virial initial conditions. Although the virial elongated cluster in panel (c) of Figure 3 appears to have a slight gradient in the radial velocity, the cumulative distribution indicates that the strength of this signature is more than seven times weaker than in the subvirial elongated cluster. The cumulative distribution for the virial cluster peaks at $A_{CRV} \sim 0.04$, whereas that of the subvirial cluster peaks at $A_{CRV} \sim 0.29$. Note that the minimum is not observed in the subvirial spherical cluster, panel (a), which indicates that subvirial velocities alone are insufficient to produce this kinematic signature. As a result, in general, both subvirial and nonspherical initial conditions are required to observe the kinematic signature.

The key feature in the cumulative radial velocity distribution signature is neither the growth nor the decay of the function, but rather the peak produced by both a region of growth and then a region of decay. While either the growth, or the decay, of the distribution can be mimicked by constructing the distribution in a velocity frame that is significantly different from the average velocity of the cluster, both cannot be created in the same frame. For instance, if the cumulative radial velocity distribution for a virial cluster is constructed by shifting into a velocity frame that is significantly higher than the cluster’s average velocity, then almost all stars contribute negative values to the distribution, and thus the distribution decreases as a function of $z'$. For the purpose of this study, we construct all cumulative radial velocity distributions by shifting each stellar velocity by the median radial velocity.

We also note that a flat radial velocity gradient, such as that produced by a rotating virial cluster, or an expanding elongated cluster, can produce a peak in the cumulative radial velocity distribution similar to the one observed in the collapsing elongated cluster. Therefore, both the kinematic signatures presented in Figure 3 and the integrated distributions presented in Figure 4 should be considered when looking for signs of collapse in an observed cluster’s radial velocity structure.

### 3.2. Velocity Dispersions

Observations of kinematic signatures in young clusters can be compared to these simulated signatures only if the observed clusters are large enough that the binned radial velocity data do not suffer significantly from small number statistics. We investigate trends in the total, radial, and tangential velocity dispersions in order to allow for comparison to smaller and less studied clusters for which only estimates for the total velocity dispersions are available.

In both spherical and elongated subvirial clusters, the velocity dispersions increase as a function of time during the initial collapse phase and then decrease as the cluster evolves toward virial equilibrium. Clusters that experience multiple collapse and re-expansion cycles before gas removal also display corresponding cycles in their velocity dispersions. The dispersions peak before the re-expansion phase and bottom out before the collapse phase, with the peak values becoming smaller with each successive cycle. Virial clusters have velocity dispersions that increase only slightly during the first 1 Myr, the star formation epoch, and then remain relatively flat through the rest of the embedded stage. These trends are similar to the ones depicted in Figure 1. While an elongated cluster’s total velocity dispersion does not depend on the projection, its radial and tangential velocity dispersions do. This dependence on projection angle, $\theta$, is discussed in Section 3.3.2.

### 3.3. Kinematic Signatures

As discussed in Section 3.1, only clusters with subvirial initial velocities and elongated geometries produce radial velocity gradients. The kinematic signature evolves over time. During

![Figure 4. Cumulative radial velocity distribution (normalized by cluster size and velocity dispersion) summed along the $z'$-axis of the projected cluster. The panels correspond to differing initial geometries, initial velocity distribution, and projections of simulated embedded clusters: (a) spherical cluster, with subvirial initial conditions; (b) elongated cluster, with subvirial initial conditions, and viewing angle of 0° from major axis; (c) elongated cluster, with virial initial conditions, and viewing angle of 30° from major axis; and (d) elongated cluster, with subvirial initial conditions, and viewing angle of 30° from major axis. The first distribution is shown at time $t = 1.5$ Myr after the start, whereas the other three cases are shown at $t = 2.1$ Myr.](image-url)
the first 1 Myr, the radial velocity gradient arises as stars become free to move through the gravitational potential of the cluster. The gradient becomes larger during the first “free-fall time” while the stars fall toward the cluster center. As a majority of the stars pass through the cluster center, the radial velocity gradient decreases and eventually changes sign as the cluster re-expands. Clusters with sufficiently small crossing times will undergo several gradient sign changes before gas removal at \( t = 5 \text{ Myr} \) as the cluster size oscillates around its equilibrium size. In addition, as the cluster evolves toward equilibrium, the strength of the kinematic signature decays.

At \( t = 5 \text{ Myr} \), the embedding gas potential is removed from the cluster which then continues to evolve due to gravitational interactions between the stars. Depending on the specific kinematic status of the cluster at the time of gas removal, the signature considered here may or may not remain in the cluster. If the gas is removed while a significant portion of the stars are in the re-expanding phase, the kinematic signature is amplified and remains in the cluster even after 5 Myr of evolution. It is important to note that the details of the gas removal process may significantly affect the characteristics of the signature, and hence we refrain from making any strong conclusions about the kinematic signature’s presence after gas removal.

### 3.3.1. Effect of Initial Virial Ratio

We compare centrally concentrated elongated clusters (\( \rho \sim m^{-1} \)) with virial parameters \( Q = 0.04 \) and 0.15 to determine how the departure from virial equilibrium affects the strength of the kinematic signature. The clusters have \( N = 2000 \) members, an SFE of 50\%, and axis parameters \( a = b = 2 \text{ pc} \) and \( c = 4 \text{ pc} \). We find that as the initial virial ratio (and the average starting stellar velocity) decreases, the strength of the kinematic signature increases. Therefore, the larger the departure from virial equilibrium corresponds to a larger kinematic signature.

We measure the strength of the signature by the amplitude of the normalized cumulative radial velocity distribution \( A_{\text{CRV}} \), and find that the \( Q = 0.04 \) cluster had a maximum at \( A_{\text{CRV}} \sim 0.33 \) whereas the \( Q = 0.15 \) cluster had a maximum at \( A_{\text{CRV}} \sim 0.20 \).

In addition, even though the \( Q = 0.15 \) cluster had larger initial velocities, the \( Q = 0.04 \) cluster has a larger average velocity dispersion over the embedded stage. Specifically, the average velocity dispersions were 0.51 km s\(^{-1}\) and 0.47 km s\(^{-1}\) for the \( Q = 0.04 \) and 0.15 clusters, respectively.

### 3.3.2. Effect of Projection Angle

For a subvirial elongated cluster, the strength of the radial velocity signature varies most strongly with projection angle. This trend is due to two competing effects. First, the most significant collapse occurs along the major axis of the cluster, the \( \hat{z} \)-axis. The component of the velocity that is observed along the line of sight varies as the cosine of the projection angle \( \theta \) between the \( \hat{z} \)-axis and the line of sight. Therefore, the smaller the projection angle, the stronger the signature. Second, the radial velocity signature is only observed when there are significantly more redshifted stars in a declination bin than blueshifted stars (or vice versa). Therefore, a larger projection angle \( \theta \) will cause the red- and blueshifted populations to be more spatially separated, whereas a small projection angle will result in a projected cluster whose redshifted and blueshifted populations appear to overlap.

Figure 5 displays the amplitude of the normalized cumulative radial velocity distribution \( A_{\text{CRV}} \), as a function of projection angle \( \theta \), for the uniform density elongated cluster with \( a = b = 2 \text{ pc} \) and \( c = 4 \text{ pc} \) at \( t = 2.1 \text{ Myr} \). A projection angle between 25° and 35° from the \( \hat{z} \)-axis produces the strongest radial velocity signature. The peak of the distribution is relatively broad, however, with a full width at half-maximum of approximately 50°.

During collapse, the dispersion in the radial velocities \( \sigma_{\text{RV}} \) is a decreasing function of the projection angle \( \theta \) from the \( \hat{z} \)-axis, whereas the velocity dispersion along the \( \hat{z} \)-axis \( \sigma_{z} \) is an increasing function of \( \theta \). This result occurs because the dispersions are geometrically related to each other by \( \sigma_{\text{RV}}(\theta) = \sigma_{z}(90 - \theta) \). These trends are representative of the fact that during the collapse phase, the velocity dispersions are largest along the principal axis.

In contrast, the plane-of-sky velocity dispersion perpendicular to the \( \hat{z} \)-axis does not depend on the projection angle. This result is due to the \( x, y \) symmetry of the prolate spheroid. Figure 6 displays \( \sigma_{\text{RV}} \) (top panel), \( \sigma_{z} \) (middle panel), and \( \sigma_{x, y} \) (bottom panel) for the same cluster shown in Figure 5. Each curve corresponds to a different choice of projection angle, \( \theta = 0°, 15°, 30°, 45°, 60°, 75°, \) and 90°. The relationship between \( \sigma_{\text{RV}} \) and \( \sigma_{x, y} \) described above is apparent in Figure 6.

### 3.3.3. Effect of Cluster Elongation

To observe differences caused by the amount of elongation, we compare two subvirial clusters with differing axis ratios. Specifically, we compare a cluster with an aspect ratio of 0.5 (\( a = b = 2 \text{ pc} \), \( c = 4 \text{ pc} \)) to one with an aspect ratio of 0.25 (\( a = b = 1 \text{ pc} \), \( c = 4 \text{ pc} \)). Each of the clusters has 2700 members, a density profile \( \rho \sim m^{-1} \), a SFE of 33\%, and a virial parameter \( Q = 0.04 \).

We find that the more elongated cluster evolves on a slightly shorter timescale and that the mean radial velocities in a given declination bin are larger. As a result, the kinematic signature discussed in Section 3.1 is stronger. For comparison, the maximum mean radial velocity in a declination bin is approximately 1 km s\(^{-1}\) for the less elongated cluster and 2 km s\(^{-1}\) for the more strongly elongated cluster. Therefore, the overall change in radial velocity is approximately 4 km s\(^{-1}\) over the length of the cluster in the strongly elongated geometry. The average velocity dispersion is also larger in the more elongated cluster, \( \sigma = 1.60 \text{ km s}^{-1} \), compared to the less elongated cluster where \( \sigma = 1.18 \text{ km s}^{-1} \).
In addition, the inside-out collapse causes the average velocity dispersion during the embedded stage to be higher in centrally concentrated clusters than in uniform density clusters. This effect occurs because the peak in the velocity dispersion, which occurs during the cluster’s collapse and re-expansion, is broader (in time) in the $\rho \sim m^{-1}$ clusters than in the $\rho \sim \rho_0$ clusters. In a centrally concentrated spheroid, the stellar members reach their highest speeds at a time that depends on their initial position within the cluster. In contrast, in a uniform spheroid, the stellar members reach their highest speeds at roughly the same time. Therefore, the velocity dispersion in a centrally concentrated cluster remains higher for a longer period of time. This finding has observational consequences: initially centrally concentrated clusters are more likely to be seen with high-velocity dispersions.

### 3.3.5. Effect of Star Formation Efficiency

To investigate the effect of SFE on the kinematic signatures observed, we compare elongated clusters with SFE of 17%, 33%, and 50%. Each cluster has a $\rho \sim m^{-1}$ stellar density profile, axis parameters $a = b = 2$ pc and $c = 4$ pc, and subvirial $Q = 0.04$ initial velocities. The clusters with SFEs of 17% and 13% have $N = 2700$ stars, whereas the cluster with a 50% SFE has $N = 2000$ stars.

Clusters with lower star formation efficiencies evolve on shorter timescales due to the higher velocities associated with the deeper potential wells of the gas component. In addition, both the amplitude $A_{\text{CRV}}$ and the total velocity dispersion increase as SFE decreases.

### 3.3.6. Effect of Extinction due to High Column Density

Most very young clusters are still embedded in the molecular cloud from which they formed. In cases where optical spectra are used to determine stellar kinematics, extinction from the embedding clouds can potentially change the observed kinematic signatures in these clusters. For example, consider a cluster that is roughly shaped like a prolate spheroid with its north end tipped toward the observer. The southern region is farther away, and is collapsing toward the center of mass, and thus appears blueshifted with respect to the stars in the northern region. If even a modest fraction of the cluster members that are farthest from the observer are not included in the observed data set due to extinction by the embedding cloud, this blueshifted population would appear less blueshifted than if it were not obscured. These observed selection effects may be mitigated by using $H$- or $K$-band spectra to select targets.

As an example, consider an embedding cloud that has a dust opacity of $\kappa_V = 200$ cm$^2$ g$^{-1}$ at optical wavelengths and a mean molecular mass $\mu = 2.4 m_H$. In order to have an optical depth with the value of unity, the minimum column density is required to be $N_{\text{col}} \approx 1.28 \times 10^{21}$ cm$^{-2}$. A typical molecular cloud has number densities ranging from $n = 10^2$ to $10^3$ cm$^{-3}$. Therefore, if the sources are being observed through more than 0.4–4 pc of molecular cloud, they would be undetected and hence removed from the sample.

To test this hypothesis, we re-analyzed the simulated cluster data by omitting stars that are behind an “obscuring plane” (see Figure 7) which includes a column density threshold. In this model, the obscuring plane is introduced with an orientation normal to the line of sight and at a distance $0 \leq d_{\text{obs}} \leq 5$ pc beyond the center of the cluster from the observer. We found that if only a modest number of stars in the southern region of the cluster are removed from the sample (due to the fact that they...
are beyond the obscuration plane) and their velocities are not included in the velocity versus position plot, the southern portion of the cluster will have a significantly less steep velocity gradient compared to the northern region. Specifically, if 10%–15% of the stellar population is unobservable, the kinematic signature in the southern half of the simulated cluster is completely washed out. Figure 8 displays the radial velocity signatures for a cluster with various amounts of the stars extincted. In the top panel, \(d_{\text{obs}} = 0.6\) pc and 32% of the cluster members are removed from the sample. The radial velocity signature in the middle panel is observed when \(d_{\text{obs}} = 1.4\) pc and 12% of the cluster members are thus obscured. For comparison, the bottom panel is the radial velocity signature produced when all stars are included in the sample.

### 4. COMPARISON TO OBSERVATIONS

Recent kinematic studies of the Orion star-forming region have determined radial velocities for a large sample (\(\sim 1200\)) of visible sources within the region. In this section, we discuss the kinematic results of these studies in light of the numerical simulations presented above.

The ONC region is a good environment in which to look for kinematic signatures such as the ones observed in our simulated clusters for many reasons. First, the ONC has a large population and is close enough to be well studied so that many of the cluster members have measured radial velocities. The large sample size of the cluster allows the data to be binned in declination while maintaining a reasonable number of data points in each bin, so that the results suffer only mildly from small number statistics. Furthermore, the ONC is visibly elongated in projection (Hillenbrand & Hartmann 1998), which is one of the requirements for the kinematic signature to be observed.

Finally, although opinions vary, there are significant arguments supporting the assertion that the ONC region as a whole is young and is estimated to be less than one crossing time old. Observations of the ONC by Fűrész et al. (2008) and more recently by T09 identify spatially coherent kinematic structure in the stellar distribution that closely matches the observed kinematic structure of the gas in the region as measured in \(^{13}\)CO by Bally et al. (1987). The authors argue that this correlation indicates that the cluster is not dynamically relaxed and that in fact the region is less than a crossing time old. The results of the previous section indicate that the strength of the kinematic signature peaks before the cluster is a crossing time old. Therefore, the strongest observed signature will occur in clusters that are less than a crossing time old, such as the ONC.

#### 4.1. Observations

The radial velocities cited in this study were determined from multiple observations using Hectochelle on MMT and MIKE fibers at Magellan. The Hectochelle observations from Fűrész et al. (2008) have been combined with additional Hectochelle and MIKE observations (T09) to produce a list of \(\sim 1200\) sources with radial velocity measurements in the region surrounding the ONC. A detailed discussion of the observations, data reduction, spectral fitting, and radial velocity measurements is provided in the observational papers. In addition, much care has been taken to identify binaries and noncluster members from the ONC data, and this procedure is detailed in T09.

#### 4.2. Kinematic Signatures

As discussed in these observational papers (Fűrész et al. 2008 and T09), the stars and gas in the region surrounding the ONC show similar north–south velocity gradients. We consider the ONC members that are near the molecular cloud filament
Figure 9. Left panel displays the positions of stars in the ONC with radial velocities measured by Fűrész et al. (2008) and T09 that are spatially associated with the filament of dense gas. In the right panel, the median radial velocity of the stellar population is plotted for each declination bin. Bin width is indicated by the vertical extent of the bars. The horizontal error bars indicate the velocity dispersion in each bin, where the dispersion is defined by the distribution's full width at half-maximum divided by 2. There is a noticeable radial velocity gradient in the northern ONC, which is qualitatively similar to the one observed in the simulated subvirial clusters.

Figure 10 presents the cumulative radial velocity distribution summed along declination in the Orion star-forming region. This cumulative distribution is created from the ONC members with radial velocities within 3σ of the median radial velocity of the distribution. From Fűrész et al. (2008), the radial velocity dispersion in this region of the ONC is σ = 3.1 km s⁻¹. The cumulative radial velocity distributions for the stars north of declination −6 and −5.5 are indicated by the dashed lines.

4.3. Comparison to Simulation Results

The kinematic structure observed in the ONC may be understood in light of the simulated cluster kinematics. The correlation between the motion of the stars and the gas in the ONC indicates that the region is fairly young and that the stars and gas are still collapsing. The observed radial velocity gradient also supports the theory that the ONC is dynamically young and that the region is less than a crossing time old. Also, the signature suggests the stars in the region are formed with subvirial velocities, an initial condition required by the simulations to produce the structure observed. The ONC region is elongated and the combination of elongation, subvirial initial velocities, and extremely young dynamical age can account for the kinematic structure observed as demonstrated by the simulations presented in this study. This interpretation requires that the northern region of the ONC be closer to the observer than the southern region. However, at this time, the distance to the ONC as a whole is still poorly constrained (Jeffries 2007, and references therein) and determining distance differences on the order of 10 pc between the northern and southern regions of the ONC is not yet possible.

The kinematic signatures observed in the ONC are qualitatively similar to those observed in the elongated subvirial clusters. The simulated cluster that is physically most similar to the ONC region is the centrally concentrated elongated cluster with axis ratio: 2:2:8 pc and a low SFE of ~17%. This cluster displays a kinematic signature similar in magnitude to the observed signature in the ONC. Specifically, at t = 0.7 Myr, the simulated cluster has a radial velocity gradient of ~2 km s⁻¹ pc⁻¹ and A_CRV ~0.15. In addition, the simulated cluster has a radial velocity dispersion of ~3 km s⁻¹. In comparison, the Orion data have a radial velocity gradient of ~5 km s⁻¹ over 0.6 in declination; at a distance of 420 pc, the parameters are approximately a gradient of 1.1 km s⁻¹ pc⁻¹, A_CRV ~ 0.2, and a radial velocity dispersion of 3.1 km s⁻¹.
Proper-motion studies in Orion (such as the one conducted by Jones & Walker 1988) found plane-of-sky velocity dispersions along the cluster’s major axis that are somewhat larger than the dispersions perpendicular to the major axis. In the notation adopted in this paper, \( \sigma_{\parallel, z} = 2.63 \pm 0.9 \text{ km s}^{-1} \) and \( \sigma_{\perp, z} = 2.03 \pm 0.11 \text{ km s}^{-1} \). Fűrész et al. (2008) determined a radial velocity dispersion of \( \sigma_{RV} = 3.1 \text{ km s}^{-1} \). This relatively large difference between \( \sigma_{RV} \) and \( \sigma_{\perp, z} \) is indicative of some type of global collapse because virial elongated clusters have at most modest differences between \( \sigma_{RV} \) and \( \sigma_{\parallel, z} \). In our simulated virial clusters \( 1 < \sigma_{RV}/\sigma_{\parallel, z} < 1.3 \), whereas in the subvirial clusters \( 1 < \sigma_{RV}/\sigma_{\parallel, z} < 2.3 \).

The ONC region displays significant mass segregation among the most massive stars (\( m \gtrsim 2 \text{ M}_\odot \)) which reside in the Trapezium at the center of the ONC. Previous numerical studies of the ONC cluster indicate that the mass segregation must be primordial as the cluster is not old enough for dynamical mass segregation to account for the presence of the Trapezium (Bonnell & Davies 1998). Our simulated clusters begin with somewhat different initial conditions, by focusing on subvirial initial velocities and cluster elongation, but arrive at the same conclusion; the region is not old enough for dynamical mass segregation to have taken place. In the simulated clusters, we compared the radii that enclosed 25%, 50%, and 75% of the stellar mass in different mass bins. The results of these simulations showed no difference in the radii of different mass bins during the first 1–3 Myr of evolution, indicating that dynamical mass segregation had not yet occurred. Subvirial initial velocities will result in a higher central density at earlier times on account of global collapse, but even with an increased density and thus higher interaction rate, the ONC is still too young for significant mass segregation to have occurred.

In addition to the lack of mass segregation in the spatial distribution of stars within the cluster, no significant differences in the kinematic distributions are observed as a function of stellar mass in the simulations. The masses of stars in the Orion region are not well enough constrained to compare this result of the simulations to the observations at this time. However, future studies of young stars in this region may yield mass information that, combined with kinematic data, will be able to test this prediction.

As seen in Figure 9, the radial velocity gradient apparent in the northern region is not as evident in the region south of the ONC. The asymmetry may indicate that the center of the gravitational collapse is not the Trapezium, but rather is located slightly north of the Trapezium. The collection of cumulative radial velocity distributions displayed in Figure 10, however, indicates that the signature is present even if the center of the gravitational collapse is assumed to be somewhat north of the Trapezium. The asymmetry could also be due to a north–south asymmetry in the initial conditions that is not well represented by the idealized simulations of Section 3. The star-forming region north of the ONC is located at the edge of the integral-shaped molecular cloud, whereas the region south of the ONC extends into a larger complex of molecular clouds. Therefore, the dynamics in the northern region is better suited to our approximate of an isolated elongated centrally concentrated cluster than those of the south.

5. CONCLUSION

This study presents N-body simulations that explore the kinematic signatures produced by asphericity and subvirial initial velocities in young embedded clusters. We have identified a robust kinematic signature, in particular a gradient in the radial velocities, which is naturally produced by elongated subvirial clusters. We characterize the properties of this kinematic signature as a function of initial conditions. Specifically, we compare the kinematics of evolving spherical and aspherical clusters and with both virial and subvirial initial conditions. We consider changes in the kinematic signature due to differing amounts of cluster elongation, SFE and departure from virial equilibrium, and discuss possible sample bias due to extinction in observed clusters. Finally, we compare the signature displayed in our simulated clusters to kinematic data from the ONC. The main results of our work are summarized as follows.

1. Elongated clusters with subvirial initial velocities display a gradient in the radial velocities as a function of projected position along the cluster. Both aspherical initial geometries and subvirial initial velocities are required to produce this kinematic signature (see Figure 3).

2. The strength of the kinematic signature increases during the first free-fall time as the cluster collapses, and then decreases as the stars pass through the center of the cluster. The gradient changes sign as the cluster re-expands, and the amplitude of the cumulative radial velocity distribution decreases (see Figure 4) as the cluster evolves (see also Figure 1).

3. The strength of the kinematic signature varies most sensitively as a function of the projection angle, as measured from the major axis of the cluster. The signature is weakest at projection angles of 0° or 90° and strongest at projection angles of \( \sim 25°–35° \) (see Figure 5).

4. Making the cluster more elongated increases the gradient of the radial velocity across the cluster while leaving the velocity dispersions roughly similar.

5. The initial stellar (and gas) density distribution affects the rate at which the cluster evolves and thus the timescale on which the kinematic signature evolves. In addition, centrally concentrated clusters have higher velocity dispersions than uniform density clusters.

6. The kinematic signature is sensitive observational selection effects. Extinction in an embedded cluster can preferentially deselect stars further from the observer and will thus affect the kinematic signature. A modest amount of extinction that removes 10% of the cluster members will wash out the kinematic signature in the region of extinction (see Figure 7).

7. The asymmetric kinematic signature is qualitatively similar to the observed kinematics of the Orion star-forming region, suggesting that in addition to being elongated (as observed) a significant fraction of the cluster members started with subvirial initial velocities (see Section 4). The large gradient observed (\( \sim 1 \text{ km s}^{-1} \text{ pc}^{-1} \)) indicates that the cluster is dynamically young. This result is consistent with previous independent claims (e.g., Bonnell & Davies 1998).

Previous studies have shown that the SFE of clusters and the initial velocity distribution have significant effects on the long-term evolution of a cluster (Adams 2000; Boily & Kroupa 2003; Adams et al. 2006), i.e., the cluster bound fraction and stellar interaction rates. This work emphasizes the fact that these conditions affect the short-term evolution of the cluster as well. In addition, this work is significantly different from previous studies in that it considers nonspherical initial conditions in both the stellar and gaseous components in young embedded clusters. Although many examples of clusters with nonspherical geometries exist and a considerable amount of work has considered orbits of individual stars within axisymmetric and triaxial
potentials, little work has been done theoretically to understand how these clusters, taken as a whole, differ from spherical clusters. We have shown that elongated clusters naturally produce observable kinematic signatures that depend on the initial starting velocities of the cluster members and the projection of the cluster onto the plane of the sky. These signatures may allow us to identify, or at least constrain, the initial conditions in star-forming clusters that still retain most of their embedding gas.

The kinematic signatures found in the elongated subvirial cluster simulations may shed some light on kinematics within nearby young clusters. As one example, this work shows that the gradient produced in simulated clusters is qualitatively similar to that observed in the radial velocities of the ONC members. Although the ONC kinematic data display some additional asymmetry not observed in the simulated clusters, this asymmetry is likely to be due to the more complicated environment and feedback processes which are not well represented by the simulation. Nevertheless, the general structure and magnitude of the observed kinematic signature in the ONC may be explained theoretically, provided that the stars are formed with subvirial initial velocities.

Current instruments such as the Hectochelle and MIKE have helped make large spectroscopic studies of many objects more efficient and have produced many radial velocity studies of stellar clusters as well as larger globular clusters and dwarf galaxies. These instruments have provided insight into the kinematics of astronomical objects ranging from the rotation of individual stars to the large-scale dynamics of galaxies. In the next decade, the GAIA mission will provide the opportunity to study the three-dimensional kinematics of clusters with exquisite detail. For example, proper motions and radial velocities will be measured for stars in ONC brighter than 20th magnitude. This study will result in accurate transverse velocities to combine with the radial velocities supplemented by ground-based observations. As more detailed kinematic data become available for the ONC and other young clusters, they should be used in conjunction with cluster simulations such as those presented here to understand the initial conditions necessary to produce the observed kinematics. A more detailed understanding of the initial conditions can then inform cluster formation and evolution models, with the overarching goal of better understanding star and planet formation within young stellar clusters.

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