Cell-Free Symbiotic Radio: Channel Estimation Method and Achievable Rate Analysis

Zhuoyin Dai*, Ruoguang Li*, Jingran Xu*, Yong Zeng*,†, and Shi Jin*
*National Mobile Communications Research Laboratory, Southeast University, Nanjing 210096, China
†Purple Mountain Laboratories, Nanjing 211111, China
Email: {zhuoyin_dai, ruoguangli, jingran_xu, yong_zeng, jinshi}@seu.edu.cn

Abstract—Cell-free massive MIMO and symbiotic radio are promising beyond 5G (B5G) networking architecture and transmission technology, respectively. This paper studies cell-free symbiotic radio systems, where a number of distributed access points (APs) cooperatively send primary information to a receiver, and simultaneously support the backscattering communication of the secondary backscatter device (BD). An efficient two-phase uplink-training based channel estimation method is proposed to estimate the direct-link channel and cascaded backscatter channel, and the achievable primary and secondary communication rates taking into account the channel estimation errors are derived. Furthermore, to achieve a flexible trade-off between the primary and secondary communication rates, we propose a low-complexity weighted-maximal-ratio transmission (weighted-MRT) beamforming scheme, which only requires local processing at each AP without having to exchange the estimated channel state information. Simulation results are provided to show the impact of the channel training lengths on the performance of the cell-free symbiotic radio systems.

I. INTRODUCTION

Along with the rapid deployment of the fifth-generation (5G) mobile communication networks, researchers have started the investigation of 6G targeting for network 2030 [1], [2]. In order to support orders-of-magnitude performance improvement in terms of coverage, connectivity density, data rate, reliability, latency, etc., many promising technologies have been extensively studied, such as extremely large-scale MIMO/surface [3], [4], TeraHertz communication [5], non-terrestrial networks (NTN) [6], [7], and AI-aided wireless communications [8]. In particular, cell-free massive MIMO [9] and symbiotic radio [10] were recently proposed as promising networking architecture and transmission technology for beyond 5G (B5G), respectively.

Cell-free massive MIMO is different from the classical cellular networking architecture in the sense that it blurs the conventional concepts of cells or cell boundary [9]. Instead, distributed access points (APs), which are connected to the central processing unit (CPU), exploit their local channel state information (CSI) to simultaneously serve the users. As such, cell-free massive MIMO system is expected to mitigate the inter-cell interference issues in small cell systems and provides users with appealing uniform good service everywhere [11]. Meanwhile, no exchange of CSI is required among different APs, which enables low complexity and light backhaul load between APs and CPU. Therefore, significant research efforts have been recently devoted to the theoretical analysis and practical design of cell-free massive MIMO, e.g., precoding design [12], power optimization [9], and energy efficiency analysis [13], [14].

On the other hand, in terms of transmission technology for B5G, symbiotic radio, which combines the benefits of the conventional cognitive radio (CR) and ambient backscattering communications (AmBC), has been proposed for spectral- and energy-efficient communications [10]. In typical symbiotic radio systems, the secondary device not only utilizes the spectral but also the power of the primary system via the passive backscattering technology [15]. Based on the relationship of symbol durations of the primary and the secondary signals, symbiotic radio system can be classified as commensal symbiotic radio (CSR) and parasite symbiotic radio (PSR) [16]. In CSR, the secondary signals have much longer symbol duration than the primary signals, making the secondary backscattering transmission contribute additional multipath components to enhance the primary communication. As a result, the primary and secondary communications form a mutualism relationship [16]. By contrast, in PSR, the primary and secondary signals have equal symbol duration, and the secondary signals are often treated as interference to the primary signals. Significant research efforts have been recently devoted to the study of symbiotic radio systems, e.g., in terms of performance analysis [17] and resource allocations [18], [19].

However, all the aforementioned existing works studied cell-free massive MIMO and symbiotic radio separately, i.e., cell-free system with the conventional active transmission or symbiotic radio transmission in conventional cellular network or the basic point-to-point communications. As the promising B5G networking architecture and transmission technology, respectively, it is natural that cell-free networking and symbiotic radio communication would merge each other to reap the benefits of both. This thus motivates our current work to study cell-free symbiotic radio systems, which, to our best knowledge, have not been studied in the existing literature. In cell-free symbiotic radio systems, a number of distributed APs cooperatively send primary information to a receiver, and concurrently support the passive backscattering communication of the secondary backscatter device (BD). As such, the distributed cooperation gain by APs can be exploited to enhance both the primary and secondary communication rate. An efficient two-phase uplink-training based channel estimation method is proposed to estimate the direct-link channel and cascaded...
backscatter channel, respectively. Furthermore, the interrelationship between the primary and secondary transmission is revealed by deriving their achievable rates taking into account the channel estimation errors. Besides, to achieve a flexible trade-off between the primary and secondary communication rate, a low-complexity weighted-maximal-ratio transmission (weighted-MRT) beamforming scheme is proposed, which only requires local processing at each AP without having to exchange the estimated CSI among APs. Numerical results are provided to show the performance of the cell-free symbiotic radio system with different training lengths.

II. SYSTEM MODEL

As shown in Fig. 1, we consider a cell-free symbiotic radio system, which consists of M distributed APs, one information receiver, and one BD. The M APs cooperatively send primary information to the receiver, and simultaneously support the BD for secondary communication via backscattering to the same receiver. The considered setup may model a wide range of applications, e.g., with the receiver corresponding to smartphones and the BD being the smart home sensor nodes. We assume that each AP is equipped with N antennas, and the receiver and BD each has one antenna. Denote by \( g_m \in \mathbb{C}^{N \times 1} \) and \( f_m \in \mathbb{C}^{N \times 1} \) the multiple-input single-output (MISO) channels from the \( m \)th AP to the receiver and BD, respectively, where \( m = 1, \ldots, M \). Further denote by \( q \in \mathbb{C} \) the channel coefficient from the BD to the receiver. Then, the cascaded backscatter channel from the \( m \)th AP to the receiver via the BD is \( qf_m \).

In this paper, we focus on the PSR setup [16], where the symbol duration of the primary and secondary signals are equal. Let \( s(n) \sim \mathcal{CN}(0,1) \) and \( c(n) \sim \mathcal{CN}(0,1) \) denote the circularly symmetric complex Gaussian (CSCG) information-bearing symbols of the primary and secondary signals respectively. Further denote by \( p \) the transmit power of each AP, and \( w_m \in \mathbb{C}^{N \times 1} \) with \( \| w_m \|^2 = 1 \) denotes the transmit beamforming vector of the \( m \)th AP. Then the received signal at the receiver is

\[
r(n) = \sum_{m=1}^{M} \left[ \sqrt{p} g_m^H w_m s(n) + \sqrt{p} q f_m^H w_m (s(n)c(n)) \right] + z(n),
\]

where \( \alpha \) denotes the power reflection coefficient, \( z(n) \sim \mathcal{CN}(0, \sigma^2) \) is the additive white Gaussian noise. Based on the received signal \( r(n) \) in (1), the receiver wishes to decode both the primary and secondary signals. To that end, since the backscatter link is typically much weaker than the direct link, the receiver may first decode the primary symbols \( s(n) \), by treating the backscattered signals as noise, whose power is \( \mathbb{E}[p|q|^2] \sum_{m=1}^{M} \| f_m^H w_m \|^2 = p \mathbb{E}[q|q|^2] \sum_{m=1}^{M} \| f_m^H w_m \|^2 \). Therefore the signal-to-interference-plus-noise ratio (SINR) for decoding the primary information is

\[
\gamma_s = \frac{p \sum_{m=1}^{M} \| f_m^H w_m \|^2}{p \mathbb{E}[q|q|^2] \sum_{m=1}^{M} \| f_m^H w_m \|^2 + \sigma^2}.
\]

Note that due to the product of \( c(n) \) and \( s(n) \) in the second term of (1), the resulting noise for decoding \( s(n) \) is no longer Gaussian. However, by using the fact that for any given noise power, Gaussian noise results in the maximum entropy and hence constitutes the worst-case noise [20], [21], the achievable rate of the primary signal in (1) is

\[
R_s = \log_2 \left( 1 + \gamma_s \right).
\]

After decoding the primary information, the first term in (1) can be subtracted from the received signal before decoding the secondary symbols \( c(n) \). The resulting signal is

\[
\hat{r}_c(n) = \sqrt{p} \sqrt{\alpha} \sum_{m=1}^{M} f_m^H w_m s(n) c(n) + z(n).
\]

Note that since \( s(n) \) varies across different secondary symbols \( c(n) \), (4) can be interpreted as a fast-fading channel, whose instantaneous channel gain depends on \( |s(n)|^2 \) [22]. With \( s(n) \sim \mathcal{CN}(0,1) \), its squared envelope follows an exponential distribution. Therefore, the ergodic rate of the backscatter communication (4) can be expressed as [16], [23]

\[
R_c = \mathbb{E}_s \left[ \log_2 \left( 1 + \frac{p \mathbb{E}[|q|^2]}{\sigma^2} \sum_{m=1}^{M} \| f_m^H w_m \|^2 |s(n)|^2 \right) \right]
= \int_0^{\infty} \log_2 \left( 1 + \frac{\beta x e^{-x}}{\sigma^2} \right) dx
= -e^{-\beta} \text{Ei} \left( -\frac{1}{\beta} \right) \log_2 e,
\]
where \( \text{Ei}(x) \equiv \int_0^x \frac{1}{t} e^t du \) is the exponential integral, and \( \beta = \frac{p \mathbb{E}[|q|^2]}{\sum_{m=1}^{M} \| f_m^H w_m \|^2} \) is the average received SNR of the backscatter link.

Note that the above analysis is based on the assumption of perfect CSI on \( f_m, g_m, \) and \( q \). In practical wireless communication systems, these channels need to be acquired via e.g., pilot-based channel estimation. In the following, we propose the channel estimation methods for cell-free symbiotic radio systems and analyze the achievable rates taking into account the channel estimation errors.

III. CHANNEL ESTIMATION AND ACHIEVABLE RATE ANALYSIS

Similar to the extensively studied massive MIMO systems, efficient channel estimation for cell-free massive MIMO can be achieved by exploiting the uplink-downlink channel reciprocity [24], [25], i.e., the downlink channels can be efficiently estimated via uplink training. However, different from the
existing cell-free massive MIMO systems [9], the channel estimation for cell-free symbiotic radio requires estimating not only the direct-link channels \( \mathbf{g}_m \), but also the backscatter channels \( q \) and \( f_m \), \( m = 1, \ldots, M \). To this end, in the following, we propose a two-phase based channel estimation method for cell-free symbiotic radio systems. In the first phase, pilot symbols are sent by the receiver while muting the BD, so as to estimate the direct-link channels \( \mathbf{g}_m \), \( m = 1, \ldots, M \). In the second phase, pilots are sent by both the receiver and the BD so that, together with the estimation of the direct-link channels, the cascaded backscatter channels \( qf_m \), are estimated.

### A. Direct-Link Channel Estimation

First, we discuss the uplink training-based estimation of the direct-link channels between the receiver and the \( M \) APs. Denote by \( \tau_1 \) the length of the uplink training sequence, and let \( p_t \) be the training power. Further denote by \( \varphi \in \mathbb{C}^{\tau_1 \times 1} \) the pilot sequence, where \( \| \varphi \|^2 = \tau_1 \). The received training signals by the \( N \) antennas of the \( m \)th AP over the \( \tau_1 \) symbol durations, which is denoted as \( Y_m' \in \mathbb{C}^{N \times \tau_1} \), can be written as

\[
Y_m' = \sqrt{p_t} \mathbf{g}_m \varphi + \mathbf{Z}_m', \quad m = 1, \ldots, M,
\]

where \( \mathbf{Z}_m' \) denotes the i.i.d. CSCG noise with zero-mean and power \( \sigma^2 \). With the pilot sequence \( \varphi \) known at the APs, \( Y_m' \) can be projected to \( \varphi \), which gives

\[
\hat{y}_m' = \frac{1}{\sqrt{p_t}} Y_m' \varphi = \tau_1 \mathbf{g}_m + \frac{1}{\sqrt{p_t}} \hat{z}_m',
\]

where \( \hat{z}_m' = \mathbf{Z}_m' \varphi \) is the resulting noise vector. It can be shown that \( \hat{y}_m' \) is i.i.d. CSCG noise with power \( \tau_1 \sigma^2 \), i.e., \( \hat{y}_m' \sim \mathcal{CN}(0, \tau_1 \sigma^2 I_N) \).

With \( \mathbf{g}_m \) being a zero-mean random vector, its linear minimum mean square error estimation (LMMSE), denoted by \( \hat{\mathbf{g}}_m \in \mathbb{C}^{N \times 1} \), is [%26\]

\[
\hat{\mathbf{g}}_m = \mathbb{E}[\mathbf{g}_m \hat{y}_m'H | \{\mathbb{E}[\hat{y}_m'H \hat{y}_m']\}]^{-1} \hat{y}_m',
\]

where \( \mathbb{E}[\mathbf{g}_m \mathbf{g}_m'H] \) denotes the covariance matrix of \( \mathbf{g}_m \). By further decomposing the direct-link channel as \( \mathbf{g}_m = \sqrt{b_m} \mathbf{d}_m \), with \( b_m \) denoting the large-scale channel coefficient, and \( \mathbf{d}_m \in \mathbb{C}^{N \times 1} \) denoting the zero-mean CSCG small-scale fading component, i.e., \( \mathbf{d}_m \sim \mathcal{CN}(0, I_N) \). Then \( \mathbf{g}_m \) is CSCG distributed with covariance matrix \( \mathbb{E}[\mathbf{g}_m \mathbf{g}_m'H] = b_m I_N \), and thus LMMSE estimation is also the optimal MMSE estimation. In this case, (8) can be simplified as

\[
\hat{\mathbf{g}}_m = \frac{p_t b_m}{p_t \tau_1 b_m + \sigma^2} \hat{y}_m'.
\]

It can be shown that \( \hat{\mathbf{g}}_m \) follows the distribution

\[
\hat{\mathbf{g}}_m \sim \mathcal{CN}(0, \frac{\sigma^2}{1 + \frac{\bar{e}_1 b_m}{\tau_1} I_N}),
\]

where we have defined the transmit training energy-to-noise ratio (ENR) as \( \bar{e}_1 \triangleq \frac{p_t \tau_1}{\sigma^2} \).

Let \( \bar{\mathbf{g}}_m \) denote the channel estimation error of the \( m \)th AP, i.e., \( \bar{\mathbf{g}}_m = \mathbf{g}_m - \hat{\mathbf{g}}_m \). With MMSE estimation, it is known that \( \bar{\mathbf{g}}_m \) is uncorrelated with \( \hat{\mathbf{g}}_m \). Thus, (11) can be simplified as

\[
\hat{\mathbf{g}}_m \sim \mathcal{CN}(0, \frac{\sigma^2}{1 + \frac{\bar{e}_1 b_m}{\tau_1} I_N}).
\]

### B. Backscatter Channel Estimation

With the estimation \( \hat{\mathbf{g}}_m \) for the direct-link channels, in the second phase, pilot symbols are sent from both the receiver and the BD to estimate the cascaded backscatter channels \( qf_m \), \( m = 1, \ldots, M \). Let \( \tau_2 \) denote the length of the training sequence in the second phase and \( \varphi_2 \in \mathbb{C}^{\tau_2 \times 1} \) be the pilot sequence sent by the receiver, with \( \| \varphi_2 \|^2 = \tau_2 \). The received training signal by the \( m \)th AP can be written as

\[
Y_m'' = \sqrt{p_t} qf_m \varphi_2 + \sqrt{p_t}(\hat{\mathbf{g}}_m + \bar{\mathbf{g}}_m) \varphi_2 + \mathbf{Z}_m'',
\]

where \( \mathbf{Z}_m'' \) denotes the i.i.d. CSCG noise with power \( \sigma^2 \). Note that without loss of generality, we assume that the pilot symbols backscattered by the BD are all 1. After subtracting the terms related to the estimation \( \hat{\mathbf{g}}_m \) of the direct-link channels from (12), we have

\[
Y_m''' = \sqrt{p_t} qf_m \varphi_2 + \sqrt{p_t}(\hat{\mathbf{g}}_m + \bar{\mathbf{g}}_m) \varphi_2 + \mathbf{Z}_m''.
\]

With \( \varphi_2 \) known at the APs, the projection of \( Y_m''' \) after scaling by \( \sqrt{p_t} \), is

\[
\hat{y}_m'' = \frac{1}{\sqrt{p_t}} Y_m''' \varphi_2 = \tau_2 \mathbf{h}_m + \frac{\tau_2}{\sqrt{p_t} \alpha} \bar{\mathbf{g}}_m + \frac{1}{\sqrt{p_t} \alpha} \mathbf{Z}_m'',
\]

where we have defined the cascaded backscatter channel as \( \mathbf{h}_m \triangleq qf_m \), and \( \hat{z}_m'' \triangleq Z_m'' \varphi_2 \). It can be shown that \( \hat{z}_m'' \sim \mathcal{CN}(0, \tau_2 \sigma^2 I_N) \).

Let \( \mathbf{R}_{h,m} = \mathbb{E}[\mathbf{h}_m \mathbf{h}_m'H] \) denote the covariance matrix of the cascaded backscatter channel \( \mathbf{h}_m \). Then the LMMSE estimation of \( \mathbf{h}_m \) based on (14) is

\[
\hat{\mathbf{h}}_m = \mathbb{E}[\mathbf{h}_m \hat{y}_m''H] (\mathbb{E}[\mathbf{y}_m''\mathbf{y}_m'''H])^{-1} \hat{y}_m''
\]

\[
= \mathbf{R}_{h,m}(\tau_2 \mathbf{R}_{h,m} + \frac{\tau_2}{\alpha} \mathbf{R}_{g,m} + \frac{\sigma^2}{\alpha^2} I_N)^{-1} \hat{y}_m'',
\]

where \( \mathbb{E}[\mathbf{g}_m \mathbf{g}_m'H] \) is the covariance matrix of \( \mathbf{g}_m \).

If the channel coefficients in \( \mathbf{f}_m \) are i.i.d. distributed with variance \( \zeta_m \), then we have \( \mathbf{R}_{h,m} = \mathbb{E}[\mathbf{f}_m \mathbf{f}_m'H] = \zeta_m \mathbf{I}_N \), where \( \zeta_m = \mathbb{E}[\| \mathbf{f}_m \|^2] \) and \( \mathbf{I}_N \) is the identity matrix.

As a result, (15) can be simplified as

\[
\hat{\mathbf{h}}_m = \frac{\tau_2 \mathbf{R}_{h,m}}{\alpha^2 \zeta_m} \hat{y}_m''
\]

Define the transmit training ENR in the second phase as \( \bar{e}_2 \triangleq \frac{\tau_2 \mathbf{R}_{h,m}}{\alpha^2 \zeta_m} \). It then follows from (11) and (16) that

\[
\mathbf{R}_{h,m} = \mathbb{E}[\mathbf{h}_m \mathbf{h}_m'H] = \frac{\alpha^2 \zeta_m^2}{\alpha^2 \bar{e}_2 \zeta_m + \frac{\bar{e}_1 b_m}{\tau_1} + \frac{\bar{e}_2 b_m}{\tau_2} + 1} \mathbf{I}_N.
\]

Let \( \mathbf{h}_m = \mathbf{h}_m - \hat{\mathbf{h}}_m \) denote the estimation error. We have

\[
\mathbf{R}_{h,m} = \mathbb{E}[(\mathbf{h}_m - \hat{\mathbf{h}}_m)(\mathbf{h}_m - \hat{\mathbf{h}}_m)H]
\]

\[
= \mathbf{R}_{h,m} - \frac{\bar{e}_1 b_m}{\tau_1 + \bar{e}_2 b_m + 1} \mathbf{I}_N.
\]
It follows from (11) that if $e_1 \to \infty$, in which case the direct-link channel $g_m$ is perfectly estimated without any error, the variance of the estimation error in (18) reduces to the same form as that in (11).

### C. Achievable Rate Analysis

In this subsection, we derive the achievable primary and secondary rates based on the channel estimation $\hat{g}_m$, and $\hat{h}_m$, $m = 1, \ldots, M$, by taking into account the channel estimation errors. By substituting $g_m = \hat{g}_m + \tilde{g}_m$ and $h_m = \hat{h}_m + \tilde{h}_m$ into (1), the received signal for information transmission can be written as

\[
r(n) = \sqrt{p} \sum_{m=1}^{M} [(\hat{g}_m + \tilde{g}_m)^H w_m s(n) + \sqrt{\alpha}(\hat{h}_m + \tilde{h}_m)^H w_m s(n)c(n)] + z(n).
\]

For decoding the primary signals $s(n)$, besides the interference from the backscatter symbols $c(n)$, the term caused by the channel estimation error $\tilde{g}_m$ is also treated as noise [21]. Therefore, (19) can be decomposed as

\[
r_p(n) = DS' \cdot s(n) + ER + ST + z(n),
\]

where $DS'$, $ER$, and $ST$ denote the desired signal, estimation errors, and the secondary transmission signal respectively, which are given by

\[
DS' = \sqrt{p} \sum_{m=1}^{M} \tilde{g}_m^H w_m,
\]

\[
ER = \sqrt{p} \sum_{m=1}^{M} (\tilde{g}_m + \sqrt{\alpha} \tilde{h}_m(c(n)))^H w_m s(n),
\]

\[
ST = \sqrt{p} \sum_{m=1}^{M} \sqrt{\alpha} \tilde{h}_m^H w_m s(n)c(n).
\]

Therefore, the resulting SINR can be expressed as (24) shown at the top of the next page, and the achievable rate is $R_p = \log_2(1 + \gamma_s)$. Note that for any given channel estimations $\hat{g}_m$ and $\hat{h}_m$, since the channel estimation errors $\tilde{g}_m$ and $\tilde{h}_m$ are random, the SINR in (24) and hence its rate $R_p$ is random. By taking the expected achievable rate with respect to the random estimation errors $\tilde{g}_m$ and $\tilde{h}_m$, we have the result (25) shown at the top of the next page, where $E = \sum_{m=1}^{M} \frac{b_m}{1 + \epsilon_i b_m} + \frac{\alpha \epsilon_i}{\alpha \epsilon_i + 1} + \frac{\alpha \epsilon_i}{\alpha \epsilon_i + 1} + \frac{\alpha \epsilon_i}{\alpha \epsilon_i + 1} + \frac{\alpha \epsilon_i}{\alpha \epsilon_i + 1}$ accounts for the average channel estimation error and noise. Note that the inequality in (25) follows from Jensen’s inequality, and the fact that $\log_2(1 + C/x)$ is a convex function for $x > 0$.

Next, we derive the achievable rate of the secondary signals $c(n)$. After decoding $s(n)$, the primary signals $s(n)$ can be subtracted from (19) based on the estimated channel $\tilde{g}_m$. The resulting signal is

\[
r_c(n) = \sqrt{p} \sum_{m=1}^{M} [\sqrt{\alpha}(\hat{h}_m + \tilde{h}_m)^H w_m s(n)c(n)] + \tilde{g}_m^H w_m s(n) + z(n).
\]

By treating the terms caused by the channel estimation error $\tilde{g}_m$ and $\tilde{h}_m$ as noise, (26) can be decomposed as

\[
r_c(n) = DS'' \cdot c(n) + ER + z(n),
\]

where ER denotes the estimation errors given in (22), and $DS''$ denotes the desired signal, which is given by

\[
DS'' = \sqrt{p} \sum_{m=1}^{M} \sqrt{\alpha} \tilde{h}_m^H w_m s(n),
\]

The resulting SINR is

\[
\gamma_c = \frac{|DS''|^2}{E s_r[|ER|^2] + \sigma^2}
\]

\[
= \frac{\alpha \sum_{m=1}^{M} \tilde{h}_m^H w_m |s(n)|^2}{E \sum_{m=1}^{M} \sum_{l=1}^{M} (\tilde{g}_m \tilde{g}_l^H + \alpha \tilde{h}_m \tilde{h}_l^H) w_l + \sigma^2},
\]

and the achievable rate is $R_c = \log_2(1 + \gamma_c)$.

Note that different from (24), as the desired channel $DS''$ also depends on the primary symbols $s(n)$, the SINR in (29) is a random variable that depends on both $|s(n)|^2$ and the channel estimation errors. Consider the expectation of $R_c$, with the expectation taken with respect to both $|s(n)|^2$ and the channel estimation errors, we have

\[
E[R_c] = \mathbb{E}_{g_m, h_m, s(n)} \log_2(1 + \gamma_c).
\]

where the inequality is obtained by applying Jensen’s inequality to the convex function $\log_2(1 + C/x)$, and $\beta_c = \frac{1}{E s_r[|ER|^2]}$ represents the average SNR for the secondary signals taking into account the channel estimation errors.

### D. Weighted-MRT Beamforming

It can be observed from (25) and (30) that for cell-free symbiotic systems, the achievable primary and secondary communication rates depend on the transmit beamforming vectors $w_m$. In particular, in order to maximize the primary communication link, all the $M$ APs set their beamforming vector $\{w_m\}_{m=1}^{M}$ as the MRT beamforming vector matched to the estimated direct-link channel $\tilde{g}_m$, which is

\[
w_m = \frac{\tilde{g}_m}{\|\tilde{g}_m\|}, \quad m = 1, \ldots, M.
\]

On the other hand, to maximize the secondary communication rate in (30), $w_m$ is set as the MRT beamformer matched to the estimated backscatter link $\tilde{h}_m$, which is

\[
w_c = \frac{\tilde{h}_m}{\|\tilde{h}_m\|}, \quad m = 1, \ldots, M.
\]

In order to achieve a flexible trade-off between the primary and secondary communication rate, in this paper, we propose a low-complexity weighted-MRT beamforming scheme, where the transmit beamforming vector for each AP is set as

\[
w_m = \kappa [\rho w_m + (1 - \rho) w_c], \quad m = 1, \ldots, M,
\]

where $0 \leq \rho \leq 1$ is a weighting coefficient that controls the trade-off between the primary and secondary communication rate, and $\kappa$ is a power normalization factor to ensure $\|w_m\|^2 = 1$ for any given $\rho$. By varying $\rho$ between 0 and 1, the achievable rate regions of the primary and secondary
\[ \gamma_s = \frac{|\text{DS}|^2}{E_{s,c} |\text{ER}|^2 + E_{s,c} |\text{ST}|^2 + \sigma^2} \]
\[ = \frac{|\sum_{m=1}^{M} \hat{g}_m^H w_m|^2}{E_{s,c} |s(n)|^2 \sum_{m=1}^{M} (\hat{g}_m + \sqrt{\alpha} h_m c(n))^H w_m|^2 + \alpha E_{s,c} |\sum_{m=1}^{M} h_m^H w_m|^2 |s(n)|^2 |c(n)|^2 + \frac{\sigma^2}{p}} \]
\[ = \frac{|\sum_{m=1}^{M} \hat{g}_m^H w_m|^2}{\sum_{m=1}^{M} \sum_{l=1}^{M} w_m^* (\hat{g}_m \hat{g}_l^H + \alpha h_m h_l^H) w_l + \alpha |\sum_{m=1}^{M} h_m^H w_m|^2 + \frac{\sigma^2}{p}}. \]

Equation (24)

\[ \mathbb{E}[R_s] = \mathbb{E}_{\hat{g}_m, h_m} \left[ \log_2 (1 + \gamma_s) \right] \geq \log_2 \left( 1 + \frac{|\sum_{m=1}^{M} \hat{g}_m^H w_m|^2}{\sum_{m=1}^{M} \sum_{l=1}^{M} w_m^* (\hat{g}_m \hat{g}_l^H + \alpha h_m h_l^H) w_l + \alpha |\sum_{m=1}^{M} h_m^H w_m|^2 + \frac{\sigma^2}{p}} \right) \]
\[ = \log_2 \left( 1 + \frac{|\sum_{m=1}^{M} \hat{g}_m^H w_m|^2}{E + \alpha |\sum_{m=1}^{M} h_m^H w_m|^2} \right) \]
\[ = \log_2 \left( 1 + \frac{\sum_{m=1}^{M} \hat{g}_m^H w_m|^2}{E + \alpha |\sum_{m=1}^{M} h_m^H w_m|^2} \right) \]

Equation (25)

transmission can be obtained. Note that weighted-MRT beamforming is especially appealing for cell-free symbiotic radio systems, due to its low-complexity and scalability, since each AP can perform the beamforming locally with its own channel estimations \( \hat{g}_m \) and \( h_m \), without having to exchange the estimated CSIs among APs.

IV. SIMULATION RESULTS

In this section, simulation results are provided to evaluate the performance of cell-free symbiotic radio systems. We set up a Cartesian coordinate system, where the BD is located at the origin \((0,0)\), and the receiver is located at \((5m,0)\). Furthermore, we assume that \( M = 16 \) APs, each with \( N = 4 \) antennas, are evenly spaced in a square area of size \( 750m \times 750m \), i.e., their locations correspond to the \( 4 \times 4 \) grid points, with the x- and y-coordinates chosen from the set \{-375m, -125m, 125m, 375m\}. The channels of all communication links are independent, where the small-scale fading coefficients follow the i.i.d. CSGC distribution with zero mean and unit variance. Furthermore, the large-scale channel gains of all links are modeled as \( b = \beta_0 d^{-\gamma} \), where \( \beta_0 = \left( \frac{\lambda}{4\pi} \right)^2 \) is the reference channel gain with \( \lambda = 0.0857m \) denoting the wavelength, \( d \) represents the corresponding link distance, and \( \gamma \) denotes the path loss exponent. We set \( \gamma = 2.7 \) for the AP-to-BD and AP-to-receiver channels, and \( \gamma = 2.1 \) for BD-to-receiver channels. The power reflection coefficient is \( \alpha = 1 \), and the transmitter-side SNR for both information and pilot transmission is set as \( \frac{\alpha}{\sigma^2} = \frac{\alpha}{2\sigma^2} = 130 \text{ dB} \), which may correspond to \( p = p_t = 20 \text{ dBm} \) and \( \sigma^2 = -110 \text{ dBm} \). The simulation results are obtained by taking the average values over 1000 channel realizations.

Fig. 2 shows the achievable rate regions of the primary and secondary rates with different uplink training lengths \( \tau_1 \), and hence different training ENR \( \epsilon_1 = \frac{\alpha}{p_t^*} \), while the pilot length in the second training phase is fixed to \( \tau_2 = 100 \). Note that each point of the curve corresponds to a primary-secondary rate pair with the weighted-MRT beamforming (33), by varying the weight \( \rho \) from 0 to 1 with step size 0.1. It is observed from Fig. 2 that with the training SNR \( \frac{\alpha}{\sigma^2} \) and training length \( \tau_2 \) fixed, the achievable rate regions critically depend on the training length \( \tau_1 \). For \( \tau_1 = 1 \), which corresponds to low training ENR \( \epsilon_1 \) in the first phase, the secondary communication rate is almost zero, regardless of the beamforming weight \( \rho \). This can be explained by the fact that when \( \epsilon_1 \) is low, there exists severe channel estimation error for the direct-link channel estimation, whose detrimental effect will be exacerbated for the estimation of the weaker cascaded backscatter channels in the second training phase. This thus severely limits the achievable rate of the secondary backscattering communication. As \( \tau_1 \) increases to 100 so that both the direct-link and backscatter channels are estimated more accurately, the rate region enlarges significantly.

By fixing \( \tau_1 = 100 \), Fig. 3 plots the achievable rate regions with different training lengths \( \tau_2 \) in the second phase. Similar to Fig. 2, it is observed from Fig. 3 that the rate region enlarges significantly as \( \tau_2 \) increases, as expected. It is also interesting to note that with larger \( \tau_2 \), the minimum primary communication rate (corresponding to \( \rho = 0 \)) actually reduces. This can be explained by the fact that as the cascaded backscatter channels are estimated more accurately with larger \( \tau_2 \), it results in stronger interference to the primary communication with MRT beamforming matched to the secondary link, which thus decreases the minimum primary rate. However, the maximum primary rate (\( \rho = 1 \)) is almost unaffected by \( \tau_2 \). By comparing Fig. 2 and Fig. 3, it is also observed that larger rate regions are achieved for \( \tau_2 = 10 \) and \( \tau_2 = 1 \) in Fig. 3 than its counterpart in Fig. 2. This implies that if the total training length \( \tau_1 + \tau_2 \) is fixed, higher priority should be given to the first training phase. This is expected since the estimation of the direct-link channels in the first phase impacts not only the primary communication rate, but also the quality of the channel estimation of the backscatter channels.
In this paper, a novel cell-free symbiotic radio system was studied, in which a number of distributed APs cooperatively send primary information, while concurrently supporting the secondary backscattering communication. A two-phase uplink-training based channel estimation method was proposed to estimate the direct-link channel and cascaded backscatter channel. Furthermore, a low-complexity weighted-MRT beamforming scheme was proposed to achieve a flexible trade-off between the primary and secondary communication rate. Simulation results were provided to demonstrate the performance of the cell-free symbiotic radio systems.

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