AN SDSS SURVEY FOR RESOLVED MILKY WAY SATELLITE GALAXIES. I. DETECTION LIMITS

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ABSTRACT

We present the detection limits of a new survey for resolved low surface brightness satellite galaxies to the Milky Way, based on the Sloan Digital Sky Survey (SDSS). Our survey exploits SDSS’s major strengths (multicolor photometry, depth, large-scale, and uniformity) by combining filter smoothing with limits in both magnitude and color space to search for low surface brightness galaxies and stellar counterparts to the compact high-velocity clouds out to the Milky Way’s virial radius (~350 kpc). Our calculated detection limits for a purely old stellar population vary with galaxy size and distance between $\mu_{\text{V,0}} = 26.7$ and 30.1 mag arcsec$^{-2}$. These limits will allow us to detect systems whose surface brightnesses are 0.5–3.9 mag arcsec$^{-2}$ fainter than Sextans, the lowest surface brightness Local Group member known. Our survey not only is sensitive to lower surface brightness stellar populations than possible with previous Local Group surveys, but will also allow us to make an unbiased and well-defined assessment of the completeness of the observed Local Group galaxy luminosity function, so that we may compare the results with the predictions of various structure formation scenarios.

Key words: Local Group — surveys

1. INTRODUCTION

Detailed investigation of the faint end of the Local Group (LG) luminosity function yields several constraints on the process of galaxy formation. First, the faint end of the LG luminosity function hosts the highest mass-to-light ratio ($M/L$), lowest-mass, and lowest-luminosity systems accessible for study, allowing us to probe the extreme limits of galaxy formation pathways. Second, these galaxies are sufficiently close that they can be resolved into individual stars, permitting direct study of their detailed star formation history and their chemical and dynamical evolution. Third, the number of the lowest-mass LG halos and their observed mass profiles can be used to help distinguish between various dark-matter, structure formation, and reionization scenarios.

In particular, results of recent N-body simulations have reignited a need for a well-defined and unbiased measurement of the galaxy mass function down to the lowest possible scales. These simulations suggest that both “standard” and $\Lambda +$ cold dark matter (CDM) cosmologies overpredict the number of low-mass dark matter halos around the Milky Way and M31 by over an order of magnitude (Klypin et al. 1999; Moore et al. 1999), compared with existing catalogs of the Local Group (see §2). Many solutions to this discrepancy between theory and observations have been suggested, including modification of the traditional CDM paradigm with warm (Hogan & Dalcanton 2000) or self-interacting dark matter (Spergel & Steinhardt 2000) and inclusion of dynamical friction, tidal stripping, and reionization on the results of cosmological simulation studies (Bullock, Kravtsov, & Weinberg 2000, 2001). However, the possibility remains that the discrepancy at least partially results from undercounting the population of dwarfs in the Local Group (e.g., the predictions of Benson et al. 2001).

Roughly 40 dwarf galaxy members of the Local Group have been identified to date, nine of which are dwarf spheroidal companions to the Milky Way (Mateo 1998). Several of these LG dwarfs have only been discovered within the last few years. Empirically, these recent discoveries of new Local Group members (for example, Whiting, Hau, & Irwin 1999; Armandroff, Davies, & Jacoby 1998; Karachentsev & Karachentseva 1999) suggest that we have not necessarily identified all of the faint Local Group galaxies accessible with existing large-sky survey data. These recent discoveries resulted from large-area searches that attempted to rectify incompleteness in Local Group membership. The surveys have generally fallen into one of two categories: (1) visual searches of unprocessed POSS-II (Karachentsev & Karachentseva 1999) or ESO/SERC survey plates (Whiting, Irwin, & Hau, 1997; Whiting et al. 1999; Karachentsev et al. 2000; Karachentseva & Karachentsev 2000) or (2) visual searches of digitally scanned and filtered POSS-II images (Armandroff et al. 1998; Armandroff, Jacoby, & Davies 1999). Even these most recent identifications of new Local Group members have, on some level, required visual evaluation of images and thus are prone to selection effects that are difficult to quantify. They are also fundamentally limited in surface brightness, due to the limited contrast of sparse dwarf spheroidals against the noise of the sky background.

We anticipate that substantial progress toward completeness and uniformity in the known luminosity function can be made with the Sloan Digital Sky Survey (SDSS) (York et al. 2000), an on going five-color large area CCD survey that will encompass a quarter of the celestial sphere. Instead of searching for smooth overdensities of diffuse stellar light, we will isolate overdensities of resolved stars, taking advantage of SDSS’s faint photometric limits, multiple filters, and robust star-galaxy separation (Ivezić et al. 2000).
A survey based on resolved stars has a number of benefits. Use of resolved stars allows us to substantially suppress galactic foreground stars relative to a galaxy’s resolved stellar population (see §§ 3 and 5) by analyzing data in small bins of color and/or magnitude. As we show below, these cuts can greatly increase the contrast of the dwarf galaxy against the background and should allow us to reach unprecedentedly low surface brightnesses. Also, unlike surveys for Local Group galaxies based on diffuse light, a survey using a red color cut and resolved stellar counts will not be biased toward detecting galaxies with recent star formation. By identifying galaxies by their resolved stars, we remove a bias toward detecting galaxies with young main-sequence stars, which contribute a disproportionate fraction of the total light of a galaxy relative to the number of stars they represent.

In this paper we describe the particular survey we have undertaken with the SDSS imaging data set. We begin by describing the likely prospects for the existence of undetected dwarf galaxies in § 2. We then describe the actual survey in § 3, calculate the detection limits in § 4, present the results in § 5, and demonstrate our approach using the Draco dSph in § 6. The prospects for future work on the survey and the application to the regions near compact high-velocity clouds (Braun & Burton 1999; Putnam et al. 2001; see also Willman et al. 2002) are then considered in § 7.

2. Predictions of existing N-body simulations

The first issue we wish to investigate is whether there is any compelling expectation that new Local Group dwarfs might remain undetected within the virial radius of the Milky Way. If CDM is the correct description of dark matter, then the current generation of N-body simulations suggest that there is indeed fertile ground for discovering new dwarfs in our local neighborhood. For example, Moore et al.’s (1999) CDM simulations predict over 400 substructures within the Milky Way’s virial radius, roughly 10 of which have a circular velocity, \(v_c \gtrsim 30\) km s\(^{-1}\) (where \(v_c \equiv \left[\frac{G M_{\text{bound}}}{r_{\text{bound}}}\right]^{1/2}\)). Assuming a homogeneous spatial distribution, these numbers translate to approximately 100 subhalos within the volume that we can probe with SDSS. For halos with \(v_c \lesssim 30\) km s\(^{-1}\) these numbers are significantly reduced by reionization, dynamical friction, tidal stripping, and gas dynamics (Thoul & Weinberg 1996; Quinn, Katz, & Efstathiou 1996; Bullock et al. 2000, 2001; Benson et al. 2001), although the degree to which these processes play a role is uncertain. For example, the results of recent simulations of the tidal stirring of dwarf galaxies (Mayer et al. 2001) suggest that previous estimates of tidal disruption as a means to destroy low-mass halos may have been overestimated.

The above modifications of CDM simulations may well produce observable consequences. For example, if the central densities of dark matter halos increase with decreasing mass, as CDM predicts, then there may be observable dense stellar cores left as remnants of any disruption process. Likewise, if CDM is not the correct form of dark matter, then the number of halos is also likely to be lower.

Independent of the number of halos which may be expected in a particular cosmological scenario, our survey will be sensitive to a range of galaxy structural parameters which have been previously inaccessible to existing surveys. We anticipate that we could detect new galaxies (1) with comparable masses and distances of known MW companions but higher \(M/L_s\), and thus lower surface brightnesses and/or (2) those galaxies with similar \(M/L_s\) as known MW companions but lower masses and thus lower surface brightnesses. It is unclear whether such lower mass systems would host a detectable stellar population, as any gas initially accreted in such halos may be unable to cool and could “boil out” after reionization (see Barkana & Loeb 1999). However, the detection or nondetection of lower mass dwarfs will place constraints on any such line of reasoning.

3. Methodology of survey

3.1. Sloan Digital Sky Survey Data

The Sloan Digital Sky Survey will cover \(\pi\) steradians in the north Galactic cap. The sky will be observed nearly simultaneously through five broad photometric filters \((u', g', r', i', z')\) and will be complete (signal-to-noise ratio \([S/N] \sim 5:1\)) to limiting magnitudes of roughly 22.3, 23.3, 23.1, 22.3, and 20.8, respectively (see Fukugita et al. 1996 for details of Sloan’s photometric system). The photometric calibration system for SDSS filters has not yet been finalized, so the preliminary magnitudes as presented in this paper will be denoted as \(u^*, g^*, r^*, i^*,\) and \(z^*\). The system used in this paper will differ absolutely from the final photometric system by only a few percent in every band except for \(u'\), where it will differ by no more than 10% (Yanny et al. 2000). The imaging data are taken in drift-scan mode by a camera consisting of 30 2048 \(\times\) 2048 CCDs (see Gunn et al. 1998 for details on the camera used for SDSS). SDSS’s accurate astrometry combined with color and morphological information derived from the digital images provides robust star-galaxy separation to a limiting magnitude of 21.5 (Ivezić et al. 2000). See York et al. (2000) and references therein for an overview of the project and further details about the photometric survey.

For this paper, we used data from runs 94 and 125 taken in the spring of 1999 and fall of 1998. Each run is composed of six parallel strips that are separated by 0.2′. The full 25′-wide equatorial stripe is then composed of 12 interleaved strips from two slightly offset runs observed a few days apart (Yanny et al. 2000). All magnitudes presented in this paper have been corrected for reddening due to Galactic extinction with the maps of Schlegel, Finkbeiner, & Davis (1998).

3.2. Survey Technique

We identify candidate dwarf galaxies as spatial overdensities of resolved stars in subfields of SDSS data. Assuming foreground stars are approximately spatially uncorrelated, Poissonian fluctuations govern the random noise in the stellar foreground. Therefore, to increase the contrast of extragalactic systems against the foreground of Milky Way stars, we apply \(r^*\) magnitude binning and color selection criteria to the stellar sources in a field. Stars that pass the criteria are binned into a spatial array, which is then smoothed with an exponential filter. Candidates are automatically identified as overdensities in the smoothed sky map. Each field of sky is analyzed multiple times, once for each \(r^*\) magnitude bin combined with either a red color cut or no color cut.

These techniques have been utilized in different forms in other Local Group surveys. For example, Armandroff et al.
3.2.1. Color Cut for Red Stellar Sources

In galaxies more distant than 125 kpc, only red giant branch and (for the nearest systems) horizontal branch stars are bright enough to be resolved by SDSS. Therefore, to optimize analyses for extragalactic systems, we have chosen a color-color cut to select stars with colors consistent with those of a metal-poor red giant branch population (although Sloan’s photometric system may not be able to distinguish a red giant from a red dwarf). A cut in the colors $g^*-r^*$ and $r^*-i^*$ (Fig. 1) was selected, based upon Krisciunas, Margon, & Szkody (1998) observation of the globular cluster M15 ([Fe/H] = -2.22) through Sloan filters, Lenz et al.’s (1998) theoretical colors of stars in Sloan filters for a range of metallicities and surface gravities, and a linear fit to the observed SDSS stellar locus (Z. Ivezic 2001, private communication) coupled with a color-magnitude diagram (CMD) of the globular cluster Palomar 5 ([Fe/H] = -1.38) created with SDSS commissioning data (Fig. 2). Because the average photometric errors in the faintest magnitude bins are greater than or equal to the half width of the color cut in $r^*-i^*$ (0.05 mag), stars are only required to have a 25% chance of fulfilling the color criteria, given photometric errors, to satisfy the cut. We chose this lower probability limit to be less than 50% so that, when photometric errors are considered, stars whose quoted colors lie outside the color cut may scatter back in. In particular, we chose the limit to be no less than 25% so that only stars whose colors are less than 1σ outside of the color cut may scatter back in.

This loose restriction on the color cut also allows for the fact that the point-spread function magnitude errors quoted in the survey are systematically underestimated by 10%-20% (Stoughton et al. 2001).

When the red color cut is applied to field stellar sources with $17.0 < r^* < 21.5$, as shown in Figure 1, approximately three-fourths of field stars are eliminated. Figure 3 shows the color cut applied to the Galactic globular cluster Palomar 5, where the cluster stars that satisfy the cut are denoted with diamonds. In Figure 3 the red giant branch colors would shift down and to the left with decreasing metallicity.

In §5 we demonstrate that we expect this color cut to enhance detection sensitivity for galaxies more distant than ~50 kpc. Closer than this, however, main-sequence stars that do not satisfy the color cut make a substantial contribution to the resolved stellar luminosity function (LF), and including the cut reduces our sensitivity. Thus we chose to analyze the data both with and without the red cut, to optimize our sensitivity to both distant and nearby galaxies, respectively.

3.2.2. Binning in Magnitude Space

We can also increase our sensitivity by limiting our analysis to small bins in magnitude space. Limiting our

![Fig. 1.—Color-color diagram of stellar sources, 15.0 < r* < 21.5, in SDSS commissioning data. Polygon outlines the region included in the red color cut.](image1)

![Fig. 2.—Color-magnitude diagram of Palomar 5’s core ([Fe/H] = -1.35) as observed by SDSS. No field subtraction has been performed. Diamonds denote the stars that satisfy the red color cut.](image2)

![Fig. 3.—Red color cut applied to color-color diagram of stellar sources in the Galactic globular cluster Palomar 5 ([Fe/H] = -1.35) without background subtracted. Diamonds denote the cluster stars that satisfy the color cut.](image3)
analysis by magnitude serves to isolate the subset of the resolved stellar population that produces the strongest signal over the foreground noise. For example, the only stars resolved in the most distant old-population systems within our virial radius would be red giant branch stars with \( r^* > 20.0 \). Including stellar sources brighter than \( r^* = 20.0 \) in the analysis adds greatly to the noise and nothing to the signal. Likewise, for a somewhat closer system, the magnitude bin containing a more densely populated portion of the lower red giant branch would provide the strongest signal over the foreground noise.

We apply the magnitude cuts in overlapping bins of 1.5 mag width spanning \( 17.0 < r^* < 21.5 \). The upper limit of this range represents the magnitude to which the star-galaxy separation is reliable (e.g., at \( r^* = 21.5 \) the star-galaxy classification is repeatable at a level better than 90\%). (Lupton et al. 2002 and Yasuda et al. 2001).

3.2.3. Smoothing with Exponential Filter

Many groups have found that spatial smoothing increases their sensitivity to LSB galaxies (for example, Davies et al. 1994 and Armandroff, Davies, & Jacoby 1998). A smoothing filter serves to suppress random fluctuations in foreground field stars, increasing the signal-to-noise of fluctuations on scales comparable to the size of the smoothing kernel. Davies et al. (1994) show that convolution filters that match the scale length of a low surface brightness (LSB) galaxy within a factor of 2 still serve to nearly maximally enhance the galaxy signal for detection. For our general survey we will smooth the spatial array of stellar sources that satisfy color and magnitude cuts with a 3′ exponential filter to optimally enhance the signal from galaxies with physical scale lengths matching those of the known LG dwarfs and with distances between 30 and 350 kpc. We will also use a 7′ smoothing filter in a more targeted analysis of regions containing known compact high-velocity cloud to better match their observed sizes (see Braun & Burton 1999).

3.3. Detection Criteria

Once the stellar sources have been restricted in magnitude and color and their surface density spatially smoothed, we use a minimum signal threshold and a minimum size as the two primary criteria for candidate selection.

The minimum signal threshold is defined as a surface density fluctuation which is 5 \( \sigma \) above the stellar foreground density. We choose the signal threshold such that, for a given smoothing length, there is no more than one expected false detection per 100 deg\(^2\) of sky in the absence of any other discriminant besides minimum size. Contiguous regions whose signal exceeds the threshold and are larger than \( \pi \times (\text{smoothing length}/2)^2 \) satisfy the minimum size requirement. This requirement eliminates many spurious detections of only 1 or 2 arcmin\(^2\).

We create a color-magnitude diagram each galaxy candidate’s resolved stars, which we can use to identify the source of the detection and discriminate against possible contaminants. Possible contaminants will include both completely false detections, due to rare random positive fluctuations, and clusters of galaxies, which may be a problem in the faintest magnitude bins where star-galaxy separation is difficult.

4. DETERMINING DETECTION LIMITS

The detection limits of this survey are primarily a function of (1) the stellar surface densities produced by different types of potential new Local Group galaxies and (2) the fluctuation level of the foreground stellar surface density above which galaxies must be detected. We simulated the stellar surface density of old population Local Group galaxies at a range of sizes and distances by creating template stellar luminosity functions from SDSS observations of the globular cluster Palomar 5. We used a foreground stellar field from the SDSS data to determine the effect of color and magnitude criteria on the foreground fluctuation level.

4.1. Stellar Luminosity Function of Palomar 5

Located 22.6 kpc from the Sun, Palomar 5 (Pal 5) has a large core radius (\( r_{\text{core}} = 2.9 \) pc), a low central surface brightness (\( \mu_{V,0} = 24.67 \)) and a moderately high metallicity (\( [\text{Fe/H}] = -1.38 \)) for a globular cluster (Harris 1996). Smith et al. (1986) use isochrone fitting to infer an age of 14–15 Gyr for the cluster, which is comparable to the ages of the oldest populations in most known LG dwarf galaxies (Mateo 1998). The metallicities of the known Local Group dwarfs range from \( [\text{Fe/H}] = -0.8 \) to \( -2.2 \), which are also comparable to the metallicity of Palomar 5.

We note that the stellar population of Palomar 5 may contain departures from that of a ”typical” globular cluster (GC). Low-mass stars and stars in the base of the subgiant branch appear to be underpopulated in the central regions when creating the stellar templates from the data. In our final analysis of the survey results when the SDSS is complete, we will be able to use a superposition of a number of observed dwarf galaxy populations to create a more precise template. However, we have already repeated the entire analysis presented in this paper with the SDSS observations of the Draco dSph (see § 6), and the resultant detection limits differed from the ones determined using only Pal 5 as the template, from insignificantly up to a couple tenths of a magnitude (depending on the galaxy size and distance).

We constructed Pal 5’s stellar LF from the SDSS data by magnitude binning its stars, with and without a color cut, and subtracting the mean stellar luminosity function of the surrounding field. Figure 4 shows the resulting luminosity functions. We then projected the LF to systems with distances ranging from \( d_{\text{proj}} \) to roughly 350 kpc. The new LF was constructed by shifting the color-magnitude diagram fainter and recalculating the luminosity function. The surface density of stellar counts was then scaled by distance squared.

4.2. Calculating Limiting \( \mu_{V,0} \)

We calculate the survey’s limiting \( \mu_{V,0} \) for galaxies with a range of exponential scale lengths and distances. To determine the limits, we created numerous galaxies with a range of surface brightnesses, sizes, and distances, placed them in
constructed spatial arrays of foreground stars and applied our survey algorithm to the resultant artificial data sets.

Our simulated galaxies were given exponential scale lengths and distances that ranged between 1' and 13' and 23 to 350 kpc. For each set of parameters we created 500 trial galaxies in a range of surface brightness centered around an initial “best-guess” detection limit. Each trial galaxy was populated with an integral number of stars drawn from a Poisson distribution of the Palomar 5 stellar surface density template appropriate to the distance and scaled to the appropriate surface brightness for the specific trial.

We created the stellar foreground spatial array by calculating the surface density of stellar sources observed by SDSS around $\ell \sim 96^\circ$, $b \sim -60^\circ$ and assuming a random stellar distribution. This assumption will tend to underestimate $\sigma$, since foreground stars may be somewhat correlated.

Once we analyzed the artificial data sets with our survey algorithm, we did a linear fit to determine the surface brightness at which there is a 50% detection efficiency for galaxies at each combination of size and distance.

4.3. Caveats

There are a few important caveats, which can affect the universality of the detection limits calculated above. First, all of the limits presented are dependent on the details of a stellar system’s star formation history. The fact that Palomar 5 is a purely old population stellar system results in detection limits for only the old stellar population in a galaxy. Recent star formation adds more to a galaxy’s surface brightness than to the overall stellar counts, so our calculated $\mu_V$’s are only upper limits (lower limits in brightness) for galaxies with star formation within the last 10 Gyr.

Second, the limits are dependent on the particular $\ell$ and $b$ of the foreground field. We calculated detection limits for a direction representative of the region $b > 30^\circ$, but the actual limits will be brighter as one looks closer to the Galactic plane and, likewise, fainter as one looks toward the Galactic pole.

Also, as mentioned above, we may be underestimating $\sigma$ of the stellar foreground due to our assumption of a random foreground stellar distribution.

5. RESULTING DETECTION LIMITS

Figure 5 displays the detection limits of our survey, performed both with and without the red color cut, as a function of galaxy physical scale length and distance. Each line follows the detection limit for a galaxy of a given exponential scale length (in parsecs) as it moves further away. Open points represent the known Milky Way galaxy companions fainter than $\mu_V = 25.0$, including Sextans, the lowest surface brightness Local Group member with a $\mu_V$ of 26.2 (Mateo 1998). These points are given as lower limits, since the limiting $\mu_V$ is calculated for a purely old stellar population (see § 4.3), and some dwarf spheroidals show signs of more recent star formation. Comparison of the two panels shows that for all but the closest distances, the red color cut makes a notable improvement in galaxy detectability.

The most obvious and general result of our analysis is that our survey will be sensitive to dwarf galaxies, within the Galaxy’s virial radius, with unprecedentedly low surface brightnesses. In addition to this our limits display two general trends: (1) larger scale length systems are easier to detect at a given distance, and (2) the red color cut causes systems with $h_{R} \gtrsim 250$ pc to have an S/N that does not decrease with distance. The first trend simply results from the fact that the signal from a galaxy with a larger angular scale length falls off less quickly than that with a smaller length. The second trend, although perhaps initially counterintuitive, is due to two combined effects: a system’s surface brightness remains constant with distance, but its stellar density increases with distance squared, and outer halo stellar populations can only be detected in the magnitude bins containing their RGB stars, which are specifically selected by the color cut.

6. APPLICATION OF SURVEY TECHNIQUE TO DRACO dSph

To demonstrate our methodology and to test the feasibility of the detection limits presented above, we analyzed a field centered on the Draco dSph galaxy, which was observed by SDSS in data runs 1356 and 1359. Draco has a distance of 82 kpc, $r_{exp}$ of 4.5, and a central surface brightness $\mu_V = 25.3$ mag arcsec$^{-2}$. Draco is one of the two least-luminous galaxies in the Local Group, with $M_V = -8.8$ and $M_B = -7.8$ (Mateo 1998). Figure 6 shows a smoothed stellar density map of Draco with overlaid contours, where each contour represents a 10 $\sigma$ fluctuation above the mean smoothed stellar distribution. This map was constructed from stars with $19.5 \leq r^* \leq 21.0$ that pass the red color cut. One can see that our survey identifies the central regions of Draco at a level of 50 $\sigma$ above the field.

This result confirms that, on the angular scale of Draco, we should be able to detect systems at least $2.5 \log (50 \sigma/5) \sigma$ mag arcsec$^{-2}$ fainter than Draco, or 27.8 mag arcsec$^{-2}$. This is in good agreement with our expectations from Figure 5 (roughly 28.6 mag arcsec$^{-2}$ for a 4.5 scale length galaxy at 80 kpc). The 0.8 mag offset between the Draco observation and our calculated limit is easily accounted for by the facts that (1) Draco lies 30' closer to the galactic plane than the region we used to calculate our detection limits, so the density of the stellar foreground is about 1.75 times greater than our artificial foreground field, and (2) we have assumed a spatially uncorrelated foreground distribution in our calculations.
7. CONCLUSION

We have presented approximate detection limits of a new Local Group survey for resolved low surface brightness galaxies. Our detection limits for a purely old stellar population vary with galaxy size and distance between about $\mu_{\text{V,0}} = 26.7$ and 30.1, and are 0.5–3.9 mag arcsec$^{-2}$ fainter than the lowest surface brightness Local Group members known.

Our survey will provide a much needed systematic analysis of the content of the Local Group for comparison with theoretical cosmological models of structure formation. Independent of whether or not we do detect additional faint end Local Group galaxies or stellar counterparts with the

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Fig. 5.—Comparison of central surface brightness limits for our survey conducted with a 3′ smoothing filter without and with the red color cut, respectively. Each line represents systems of different physical scale lengths and the filled points represent the angular scale lengths that correspond to the plotted combinations of distance and physical scale lengths, as summarized in the legend. Open points represent the known Milky Way galaxy companions fainter than $\mu_{\text{V,0}} = 25.0$.

Fig. 6.—Smoothed stellar image of Draco dSph. Each contour represents a 10 $\sigma$ fluctuation above the mean smoothed stellar density. The center of Draco is detected at 50 $\sigma$. 
compact high-velocity clouds, our calculated detection limits will quantitatively describe the region of unsampled Local Group parameter space for the first time and therefore still yield valuable constraints on various structure formation scenarios.

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