Applied Awareness: Test-Driven GUI Development using Computer Vision and Cryptography

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Abstract

Graphical user interface testing is significantly challenging, and automating it even more so. Test-driven development is impractical: it generally requires an initial implementation of the GUI to generate golden images or to construct interactive test scenarios, and subsequent maintenance is costly. While computer vision has been applied to several aspects of GUI testing, we demonstrate a novel and immediately applicable approach of interpreting GUI presentation in terms of backend communications, modeling "awareness" in the fashion employed by cryptographic proofs of security. This focus on backend communication circumvents deficiencies in typical testing methodologies that rely on platform-dependent UI affordances or accessibility features. Our interdisciplinary work is ready for off-the-shelf practice: we report self-contained, practical implementation with both online and offline validation, using simple designer specifications at the outset and specifically avoiding any requirements for a bootstrap implementation or golden images. In addition to practical implementation, ties to formal verification methods in cryptography are explored and explained, providing fertile perspectives on assurance in UI and interpretability in AI.

1 Introduction

User interfaces are often the hardest part of a system to test and maintain, particularly in the face of rapid architectural changes, design updates, and disparate, evolving, distributed backend services. This work describes techniques for validating graphical user interfaces by applying image classification to automate the interpretation of UI snapshots in terms of underlying data model transmissions. Specifically: to be validated, a user interface rendering must be aware of the underlying communications in a particular, technical sense.

This work explores and exhibits several aspects of validating GUIs using ML and crypto:

- Automated testing
- Test-driven development without requiring baseline implementation
- Simple, practical, performant implementation
- Online and offline validation
- Platform independence
- Formal notions arising in cryptographic protocol validation

We describe an end-to-end implementation of a client-server based GUI validated by training CV object detection to identify essential affordances and then create a convincingly fake version of the

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JSON tree served by the backend. When the fake JSON diverges from the actual JSON, a validator reports GUI failures. The trained ML system is small and fast enough for a GUI to be "self-aware" of its performance: the GUI (optionally) shows its shame immediately, when it realizes the JSON from its images doesn’t match the JSON from the backend.

Remarkably, training on designer mockup slides in Keynote/PowerPoint suffices, prior to writing any code. The validation paradigm is not only sufficient for automated testing, it makes properly-disciplined test-driven development possible from scratch - where the UI tests are written in advance of the first line of code. No “golden images” are needed; no fine-grained anticipation of the deployment platform (iOS/Android iconography, map tile sources, etc.) are needed.

1.1 Paradigm summary

There are many automated approaches to UI testing, including applying computer vision techniques to determine quality of a result or to identify affordances in order to create interaction sequences that better cover the application state space [11, 4, 6-8, 2]. These generally seek to compare the final rendering to an expected rendering - after code has been changed, or after states have been traversed. Namely, they focus on the presented images and affordances.

In contrast, this work focuses on the communications model behind the scenes. Taking a page from cryptographic protocol verification, we advance the following paradigm:

A user interface enjoys awareness-based assurance if it is technically aware of its backend communications: an independent, automated interpreter should map the rendering to the backend communication stream faithfully enough to convince an automated validator.

We give a concrete demonstration here, but this work is not so much about “the most optimized or robust object detector” or “the best test set” as it is about the importance, relevance and ease of using computer vision to give automated test assurance by way of “awareness.”

Roadmap: §2 Background; §3 Awareness; §4 Case Study; §5 Crypto.

2 Background

2.1 Automated testing

Quality assurance performed by humans can be tedious, error-prone and expensive. While obtaining a baseline validation of an initial software deployment may be straightforward, the effort in repeating QA after minor or major changes can be costly and tedious. Automated test suites are widely relied on for non-UI production software, but automated UI testing remains brittle for many reasons.

First, even where automated UI testing is practiced, a very common approach is the "golden image" approach: compare images after a change to already-validated images stored prior to a change. Acceptance criteria may demand the comparison be pixel perfect, or it may allow for deviations measured by image distance or similar treatments. Often, a human needs to be bothered to eyeball differences. When discrepancies occur, new snapshots are often trusted if they “look good.” While images are small in modern storage terms, they are unwieldy in source control repositories tailored to track text changes.

Second, some UI testing approaches are particularly platform-dependent, requiring extensive platform expertise. Apple’s iOS/MacOS platform is exceptional in its robust accessibility features - and these features have a dual use to support UI testing. The UI components are already instrumented and tailorable for alternate interactions: for example, using voice to trigger a button action rather than requiring a screen tap; or having explicit metadata associated for vocalizing an otherwise-visual presentation. Apple’s goodwill provides a significant development benefit: one can write UI tests that take advantage of accessibility features to track and assert expected affordances. This approach has such immediate benefit that Apple’s XCode now offers up templates and guides [10]. But it requires a specific platform and a reasonably experienced developer.

Third, somewhat more principled and abstract (and debated), there is the pitfall of testing the implementation rather than the contract. In ordinary testing, one should not be examining whether a
square root algorithm is faithfully following Newton’s algorithm. One should just verify if the result, squared, is expected. For us, the presence of a specific DOM element in a renderer model is not necessarily the goal: the ability to resurrect the conveyed backend messages from such elements is the "contract" to be vetted. Certainly, one can be interested in both - but we are not focusing on DOM elements. DOM elements or UIKit views are characteristics of the current "internal" implementation of a rendering, not of the "affordance contract."

Finally, navigating the state transitions of a UI is a distinct challenge, particularly for generating broad case coverage. There is an established line of research into automatically identifying affordances and generating user interactions to trigger comprehensive state changes \[8, 11, 4, 7, 5, 6\]. In fact, a state-change bug was the original motivation for the current work, although our focus is not specifically on finding or triggering state changes.

State transitions are important but also somewhat complementary in our setting. We require validations be satisfactory after sequences of state transitions, but we are focused on how the validation occurs once those state transitions have been triggered. We seek to expand the menu of complementary options available to applying CV to testing. With our ability to enable online validation, we can also leverage live feedback in A/B testing, relying on empirical behaviors to validate the important regions of state space.

In sum, there are many concerns or gaps in preceding work, which we propose to circumvent or fill:

- Brittleness
- Difficult maintenance
- Platform-dependent tricks
- Delayed, offline image/log aggregation and pipelining
- Subjective aspects of automated difference-checking
- Narrow focus on the renderings

### 2.1.1 Test-driven GUI development

Automated TDD for GUIs – as distinguished from "testing GUIs after the fact" – is extremely challenging. Tests for DOM elements could be written up front, but this flavor is "testing the implementation" rather than "testing the API." Tests for images invariably require a bootstrap implementation. Even with a bootstrapped set of images, moving forward in a TDD manner is quite hard, if ever actually performed in a principled TDD way. After moving a button, for example, generating the next round of valid images (or image validators) is vastly easier using approved logs from already-modified code than editing previous golden snapshots.

Turning our attention away from image fidelity or DOM fidelity, and focusing it on the communications being represented by the GUI, we can both theoretically and practically produce tests and validation methods up front, before any code is written or changed. We don’t need to run square-root algorithm to build our square-root test cases; we don’t need to count the expected Newton iterations to have confidence.

ML-based image analysis is the key to obtaining sufficiently general flexibility. It is, arguably, what the human does, when choosing to accept a new golden snapshot. The human verifies that the new snapshot is sensible, in that it expresses states conveyed by backend messaging.

Naturally, object detection and the human can also verify specific design aspects, such as "the button is 44x44 pixels" - but this is already relatively covered ground. We are focused on the "semantics" of the image as explained by the backend communications. The JSON offers a testable interpretation of what the GUI is "aware" of representing.

### 2.2 Cryptography and Simulated Environments

Relationships to validation of cryptographic protocols are described in detail in \[5\]. Briefly, prominent formal methods require of course that an attacker finds a cryptosystem hard to decipher, but they demand more strictly that an adversary can only send encryptions using a cryptosystem if the adversary is aware of the cleartext content. This subtle demand for awareness is decades old, but it also took decades to emerge, and it is critical in formal security analysis.
The rendering of UI is analogous to encryption of a cleartext. The UI is intended for "easy deciphering" by humans, of course. Here, as in cryptosystems, we demand that the UI is mechanically decipherable to reveal the messages employed in its formulation. When this demand for awareness is satisfiable – and we show it is, in §4 – the "deciphering" proves useful as a tool for validating the UI renderings (not in terms of other renderings but in terms of cleartexts).

Furthermore, drawing on cryptographic principles also provides critical notions and pitfalls when analyzing aspects individually. Concretely, consider showing that a GUI’s renderings are aware of the left branch of JSON messages, and then showing that the renderings are aware of the right branch of JSON messages. One would like to conclude that the composition is therefore validated. In cryptography, however, the combination of properties like integrity and confidentiality are sufficiently subtle that naive composition can lead to failures in validation if not outright breakage. Any approach for composing GUI validation efforts does well to be informed by the potential for subtle gaps.

3 Synthesizing Backend Communications from GUI Renderings

The formalism here is more to pin down what we mean and to tie it in with cryptographic validation paradigms later. For the most part, we are soon going to focus on achieving it in practice.

Let’s restrict our attention to a standard architecture containing a frontend with a client receiving a data model comprised of a text-based dictionary tree, received from a backend service on a regular basis. The frontend GUI G renders images G(x) based on the supplied tree x. The following formalization captures the notion of awareness of the input by demanding the ability to recover the input from the rendering:

Definition 3.1. A GUI G is \(\epsilon\)-aware of the model, with respect to an input distribution \(D\) on model data, if there exists an efficient interpreter \(I\) such that \(I(G(x)) = x\) with probability exceeding \(1 - \epsilon\).

Typically, there will be information unrepresented in the GUI, so let’s allow for a filter \(F\) to confine our demands to a subset of the model data:

Definition 3.2. A GUI G is \(\epsilon\)-aware of the model relative to filter \(F\) if \(F(I(G(x))) = F(x)\) under conditions from [3.1]

The preferred distribution is what is seen in the deployment in the wild, of course, but this is hard to track. We break the domain into discovering desirable distributions versus measuring awareness for a given distribution, and focus on the latter. The job of discovering good test coverage (for implementation logic and for domain examples) is critical, of course, but our focus will be on what "awareness" means and why it is helpful when we have a distribution already in mind.

Definition 3.3. Let a test suite \(S\) generate backend text models with distribution \(D\). A GUI G satisfies awareness-based assurance with respect to test suite \(S\) and filter \(F\) if it is \(\epsilon\)-aware of the model with respect to \(D\) and relative to \(F\).

In more concrete and computational terms, let’s phrase this in terms of distinguishing power. We would like to have a validator \(V\) who, given filtered views \(F(I(G(x)))\) and \(F(x)\), cannot determine which is the actual input and which is the interpretation of its rendering.

Definition 3.4. Let \(V\) take an input pair of strings, \((a, b)\), and report a 1-bit output. A test validator \(V\) demonstrates awareness-based assurance of GUI G if \(\left| Pr[V(f_0, f_1) = i] - 1/2 \right| < \epsilon\), where \(i\) is a uniformly random bit, \(f_i\) is \(F(x)\) with \(x\) sampled from \(D\), and \(f_{1-i} = F(I(G((x))))\).

The validators are largely very simple, generally just being an equality test of a filtered branch of a tree.

3.1 Timeseries

A few brief remarks on an important generalization, without diving too much farther into formalization for its sake. In practice, we encounter a log of GUI snapshot images and a log of backend text messages. Ideally these have near identical timestamps and can be easily correlated, so that the pair of model and rendering-interpretation can be supplied to the Validator. A GUI rendering might lag the backend message badly, such that another backend message arrives before the rendering finishes.
Logs can be recorded by distinct processes and at distinct rates, particularly when log image storage is costly. For a given logged image, we will simply pair it with the most recent logged backend message preceding it. Robustness and error-tolerance of the overall validation could be improved by allowing leeway in this pairing. For example, we can lower the bar so that the rendering-interpretation matches any one of a window of backend messages. Our empirical explorations don’t need this, but some may.

4 Case Study

We demonstrate the paradigm by implementing a GUI from scratch, starting with "designer spec," and coding the GUI and backend independently of the bootstrap object detector and validator. Even very recently these efforts suffered from cross-platform variation: training models and doing validation on Linux, while running the GUI and aggregating screenshots in iOS, for example. Python, TensorFlow or PyTorch, ObjectiveC or Swift: many parts to master. A single platform is not required but it enables substantially easier implementation – and even online validation: the GUI can test itself live. In our setting, we used Swift on a MacBook Pro, end-to-end, to implement GUI, backend model messages, logging, testing (offline, and live online self-testing), and object detection training and evaluation. For initial design spec: Keynote; and Preview for snapshots and labels.

4.1 Test-Driven Design Phase

Our sample application is a GUI for a drone flying over a mapped area. We wish to be assured that warning conditions are exhibited correctly, e.g. when flying in risky or dangerous circumstances. This is a simplified example motivated by an actual production setting (and on expensive debugging of a flaw), but the production code wasn’t itself TDD-developed nor can it be released. The spec and code here will be available on github.

Disciplined TDD requires test cases prior to writing code. We approach this via straightforward steps:

1. Designer provides a slide deck spec (e.g. Keynote; any image-generating tool is fine)
2. Backend model representation is defined (JSON schema)
3. An object detector is trained on labeled spec (design deck) to identify affordances
4. Test code maps presence (or absence) of affordances to synthesized JSON

The idea of identifying affordances via CV is not remotely novel: many predecessors such as Sikuli \cite{11} and others have used it for years. Those prior applications focused on the challenging task of automatically generating test sequences and comparing images. Here, instead, we focus on awareness of the backend messages.

The design spec is a Keynote deck starting with 3 slides as visual spec but expanded to 90 slides as synthetic test cases; 30 for each warning condition: nominal, caution, danger.

The Keynote design spec used a Keynote-provided standard iPhone wireframe and Open Street Maps images for background; see fig. 1.

Synthetic images were generated and labeled manually in Keynote (fig. 2), by dragging background maps and updating affordances. Although tedious, snapshotting took 10 seconds per image, 45
minutes for the full training/test set to support awareness-based TDD. The background variations were sufficiently diverse for robust training. Fully synthetic generation is completely compatible with this approach, of course, whether in “test-driven” or “post-testing” scenarios.

A CoreML (Apple) object detection model was trained on 250 iterations using transfer learning taking 78 minutes on a 2016 MacBook Pro. 60 images were used for training and 30 held for test. The resulting model was 61MB in size.

Results of later evaluation can be seen in fig. 3 where we see that the model trained on the designer spec is capable of locating the affordance and classifying it correctly.

4.2 Backend and Frontend Coding

The backend and frontend code are written and subjected to the testing above. In strict TDD, the tests are constructed first: here, rough designer images sufficed. Of course, for post-test scenarios, images from an existing production implementation or MVP are straightforward to label automatically using the backend JSON, to train for forward awareness after revisions.

The GUI was presented as a 9.7-inch iPad whose aspect ratio and dimensions differ from the design spec (iPhone). The GUI rendered Apple Map tiles, easily distinguishable from designer spec OSM images.

A smoke test was immediately successful: the first renderings of the GUI were evaluated using the object detection model to verify detections. Identification was comprehensive – using OD made variations in size, map tiles, and other affordances irrelevant for testing.

The Validator logic consisted of filtering the warning mode from the JSON tree and making sure that the rendering-interpretation matches the provided JSON. Specifically and trivially: evaluate the object detector, build JSON, all within XCode [10].

The code for logging GUI images, for logging JSON messages, for pairing up logged GUI images with most recent (independently-logged) JSON backend messages, is straightforward and occupied as much of the validation effort from scratch as the JSON-interpretation itself. Naturally, more complex settings would require greater effort – for example, supporting different platforms, or reverse-estimating GPS from maps. This app instrumentation is a fixed overhead, however; many different facets of a GUI and JSON tree can be explored using the same infrastructure.

**Observation 4.1.** The backend, GUI, awareness-interpreter and validator (all to be released on github) demonstrate a feasible implementation of test-driven GUI development using automated awareness-based validation, relative to a filter of JSON on the warning mode and with respect to a test suite comprised of pseudorandomly generated GPS waypoints over an urban area.

4.3 Debugging and Fault Injection

We validated the validation by injecting faults. We injected different kinds of failures but will present a particular one here. Common UI implementations first check for changes in latest JSON and trigger re-rendering only when change in the whole tree or a subscribed branch is detected. Motivated by a real-life example, we injected a failure to note transitions between *caution* and *danger*. One can imagine that changing a JSON model from one version to the next leads readily to these failures. A
“nominal” state might be represented implicitly but later explicitly in a tree. Subscriptions can be outdated after a branch is moved. Failures in thorough change detection itself can occur.

Although ordinary state testing (checklist, one at a time: works for nominal, caution, danger) would validate the implementation, these transition problems can hide latent bugs.

In run-throughs of pseudorandom sequences with pseudorandom fault injections, failures were detected universally and immediately. A short and simple script (comparing the JSON of which the GUI was “aware” to the most-recent JSON) quickly identified bugs, with timestamps.

Whether run in advance, or applied to a logged history which has not yet been debugged, the awareness-based, timestamped failures made it very easy to focus on finding root causes without needing hours of manual, side-by-side inspection. Figs. 6,7 show the reconstructed JSON during correct vs. faulty rendering. Mismatched JSON immediately points to GUI failures.

4.4 Live Self-Validation using Awareness

Although not specifically a required goal, the OD evaluation is compact and fast enough to deploy with the application. A version of our implementation included 1 Hz live-snapshots to validate against incoming JSON. An “shame” indicator was added to the GUI, to be shown when validation failed.

Under fault injections (§4.3), we observed that the self-aware GUI would show shame within a second of fault injection. (Demo also included in github.)

The app was instrumented to include fault injection (§4.3). For example, an error was simulated whereby state-change detection failed for transitions between caution and danger. By being aware of the JSON using the interpreter-validator, live, the GUI promptly showed the shame indicator within a second of fault injection. (This demonstration is also included in github.)

Figs. 4 shows satisfactory GUI display (correct backend GUI is derivable from the snapshot), while fig. 5 shows in-flight detection of mismatched JSON, leading to a self-aware display of shame.

The CoreML object detector net was 61 MB in size, close to double the average 34 MB iOS app size (circa 2020). With a current 200 MB cap on deployed apps, self-awareness does not present an impossible drawback for sampling deployments, although it increases battery drain. Full online awareness of a larger backend JSON tree would become prohibitive for store-deployed apps but less so for dedicated devices such as vehicle dashboards.
5 Cryptography

Imagine voters sending RSA-encrypted votes to a ballot counting center. Although Bob doesn’t
know Alice’s vote, Bob can copy Alice’s vote by copying her ciphertext, in a naive setting. Strictly
speaking, this is a voting violation that doesn’t occur with ideal paper ballots. (Although this might
not seem extreme, there are worse breakdowns.)

Historically, Shannon’s foundational analysis of one-time pad encryption security focused on privacy
of the ciphertext [9]. Other properties later became important - such as integrity or authentication -
but the focus remained on analyzing lists of ciphertext properties, with surprisingly subtle pitfalls.

Decades later, a different paradigm emerged: a “real” vs “ideal” approach, focusing instead on
interactions between parties in two different settings [1, 3]. An attacker in a “real” setting (using
a deployed cryptosystem) must be mapped to an attack in an “ideal” setting (e.g. a trusted party
or axiomatically-secure channel). An implication of this approach is that successfully
encrypting a
message requires reconstructibility of the cleartext. Now Bob can’t bluff.

Formally, this boils down to exhibiting a “simulator” who provides a mockup of the real world to
an adversary, while itself playing in the “ideal” protocol, where axiomatically-secure channels are
postulated. As in a Turing test for intelligence, if it’s infeasible to tell the difference between real-
world and ideal-world attacks, then whatever an adversary can achieve using real life cryptosystems
must also therefore be achievable in an ideal setting. In this formalism of what it means to be secure,
the simulator must extract an actual message to convey on the ideal channel.

Our approach and our definitions 3.1,3.2 of awareness are motivated by this paradigm. Where a
crypto simulator demonstrates an adversary’s awareness of the ciphertext (by building the cleartext
sent in an ideal channel), our mapping from rendering to backend JSON is a demonstration that the
renderer is aware of the backend JSON.

The fidelity of the synthesized JSON, like the fidelity of a synthesized cleartext, is core to this
approach. The formal and practical benefits make reverse-engineering the JSON a challenge worth
pursuing.

While crypto validation admits a wide range of adversaries (poly-time attackers), our adversary
class is limited to collections of challenging test sequences. The generation of broad-coverage test
sequences remains important (and an independent task), but fortuitously, unlike arbitrary crypto
adversaries, we can increase the validation level by scaling up from simpler to broader scenarios.

6 Closing Remarks

We proposed a GUI validation approach focusing on constructive awareness of the backend commu-
nications rather than on various properties of the rendering itself and how they change over time.
We showed an efficient and concrete single-platform implementation, demonstrating that disciplined
TDD for GUI development can be accomplished without “cheating” (i.e. without needing an initial
implementation to generate golden test images). The methodology is cross-platform and indepen-
dent of the rendering technology – it does not need to capitalize on platform-specific aspects like
accessibility features or DOM/UIKit structures.

Generating comprehensive test sequencing remains a critical part of validation but is independent
of this direction. In fact, our approach supports much greater flexibility of testing based on live,
empirical, unseen sequences – it is not confined to comparisons to prepackaged images from fixed,
pre-established transition-coverage collections.

Post-testing can be supported by training with automatically-labeled images from a production
implementation or MVP – using labels from the backend JSON. Testing is bootstrapped from verified
renderings of well-covered states, decoupled from efforts to cover all state transitions. This style of
migration is arguably more robust and objective than golden-image replacement.

Several directions lead from here. Many IDEs provide templates for test generation; here, practical
toolkits to automate and streamline the full design-to-test route can help, including the post-testing
auto-training approach. As in crypto, the composition of awareness of separately-vetted subtrees
needs formal support, as there are some edge-case pitfalls. Some otherwise-idle challenges gain a
practical application – for example, reverse engineering GPS from diverse map renderings.
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