Energy decay for systems of semilinear wave equations with dissipative structure in two space dimensions

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Dedicated to Professor Shuichi Kawashima on the occasion of his sixtieth birthday

Abstract: We consider the Cauchy problem for systems of semilinear wave equations in two space dimensions. We present a structural condition on the nonlinearity under which the energy decreases to zero as time tends to infinity if the Cauchy data are sufficiently small, smooth and compactly-supported.

Key Words: Nonlinear wave equations; Energy decay

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1 Introduction and the main result

We consider the Cauchy problem for a system of semilinear wave equations in two space dimensions:

\[ \Box u = F(\partial u), \quad (t, x) \in (0, \infty) \times \mathbb{R}^2, \tag{1.1} \]

with

\[ u(0, x) = \varepsilon f(x), \quad (\partial_t u)(0, x) = \varepsilon g(x), \quad x \in \mathbb{R}^2, \tag{1.2} \]

where \( u = (u_j)_{1 \leq j \leq N} \) is an \( \mathbb{R}^N \)-valued unknown function of \((t, x) \in [0, \infty) \times \mathbb{R}^2\), \( \Box = \partial_t^2 - \Delta_x = \partial_t^2 - \partial_1^2 - \partial_2^2 \), and \( \partial u = (\partial_a u_j)_{0 \leq a \leq 2, 1 \leq j \leq N} \) with the notation

\[ \partial_0 = \partial_t, \quad \partial_1 = \frac{\partial}{\partial x_1}, \quad \partial_2 = \frac{\partial}{\partial x_2}. \]

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For simplicity, we always suppose that $f = (f_j)_{1 \leq j \leq N}$ and $g = (g_j)_{1 \leq j \leq N}$ belong to $C^\infty_0(\mathbb{R}^2; \mathbb{R}^N)$, and that $\varepsilon$ is positive and sufficiently small. The nonlinear term $F(\partial u) = (F_j(\partial u))_{1 \leq j \leq N}$ is assumed to be a quadratic smooth function around $\partial u = 0$. To be more precise, we assume that $F \in C^\infty(\mathbb{R}^3N; \mathbb{R}^N)$ and

$$F(\partial u) = F^q(\partial u) + F^c(\partial u) + O(|\partial u|^4)$$

in a neighborhood of $\partial u = 0$, where the quadratic nonlinear term $F^q(\partial u) = (F^q_j(\partial u))_{1 \leq j \leq N}$ and the cubic nonlinear term $F^c(\partial u) = (F^c_j(\partial u))_{1 \leq j \leq N}$ are given by

$$F^q_j(\partial u) = \sum_{k,l=1}^N \sum_{a,b=0}^2 B^{ab}_{jkl}(\partial \omega_k u_k) (\partial \omega_l u_l),$$

$$F^c_j(\partial u) = \sum_{k,l,m=1}^N \sum_{a,b,c=0}^2 C^{abc}_{jklm}(\partial \omega_a u_k) (\partial \omega_b u_l) (\partial \omega_c u_m)$$

with some real constants $B^{ab}_{jkl}$ and $C^{abc}_{jklm}$. In order to state our conditions, we define the reduced nonlinearity

$$F^q_{\text{red}}(\omega, Y) = (F^q_{\text{red}}(\omega, Y))_{1 \leq j \leq N}$$

and

$$F^c_{\text{red}}(\omega, Y) = (F^c_{\text{red}}(\omega, Y))_{1 \leq j \leq N}$$

by

$$F^q_{\text{red}}(\omega, Y) = \sum_{k,l=1}^N \sum_{a,b=0}^2 B^{ab}_{jkl}(\partial \omega\omega_k Y_k Y_l),$$

$$F^c_{\text{red}}(\omega, Y) = \sum_{k,l,m=1}^N \sum_{a,b,c=0}^2 C^{abc}_{jklm}(\partial \omega\omega\omega Y_k Y_l Y_m)$$

(1.3)

for $Y = (Y_j)_{1 \leq j \leq N} \in \mathbb{R}^N$ and $\omega = (\omega_1, \omega_2) \in \mathbb{S}^1$, with the convention $\omega_0 = -1$.

It is known that the Cauchy problem (1.1)–(1.2) admits a unique global solution for small initial data if $F(\partial u) = O(|\partial u|^4)$ near $\partial u = 0$; however this is not true when we consider general cubic or quadratic nonlinearity. Thus the cubic nonlinearity is critical for small data global existence in two space dimensions, and we need some structural restriction on quadratic and cubic parts of $F$ to obtain global solutions for small initial data. Alinhac [2] proved that if the null condition (or the quadratic null condition)

$$F^q_{\text{red}}(\omega, Y) = 0, \quad (\omega, Y) \in \mathbb{S}^1 \times \mathbb{R}^N$$

(1.4)

and the cubic null condition

$$F^c_{\text{red}}(\omega, Y) = 0, \quad (\omega, Y) \in \mathbb{S}^1 \times \mathbb{R}^N$$

(1.5)

are satisfied, then the Cauchy problem (1.1)–(1.2) admits a unique global solution for small $\varepsilon$. More precisely, only the case of single quasi-linear equations is treated in [2], but we can
easily adopt the method in [2] to the system (1.1) (see [9]). It is also known that the null condition (1.4) without (1.5) implies the so-called almost global existence for (1.1)–(1.2). For the related results concerning the quadratic and cubic null conditions in two space dimensions, we refer the readers to [3], [6], [8], [11], [12], [13] and [14]. The (quadratic) null condition was originally introduced by Klainerman [20] as a sufficient condition for small data global existence in three space dimensions (see also Christodoulou [5]); the cubic null condition is not needed then, because the critical nonlinearity is quadratic in three space dimensions.

Concerning single wave equations with cubic nonlinearity in two space dimensions, Agemi [1] introduced another structural condition being weaker than the cubic null condition, and conjectured that the small data global existence would follow from his condition. Let \( N = 1 \) and \( F^q(\partial u) \equiv 0 \) for a while. Then \( F^{c,\text{red}} \) has the form \( F^{c,\text{red}}(\omega, Y) = P(\omega)Y^3 \) with a polynomial \( P \) of cubic order. Agemi’s condition is:

\[
P(\omega) \geq 0, \quad \omega \in S^1.
\]  

(1.6)

Observe that (1.6) is equivalent to

\[
Y F^{c,\text{red}}(\omega, Y) \geq 0, \quad (\omega, Y) \in S^1 \times \mathbb{R},
\]

and that the cubic null condition (1.5) implies (1.7). The Agemi conjecture was solved independently by Hoshiga [10] and Kubo [21]: Namely, for (1.1)–(1.2) with \( N = 1 \) and \( F^q(\partial u) \equiv 0 \), it was proved that (1.6) implies global existence of solutions for small \( \varepsilon \). For example, the Agemi condition (1.6) is satisfied for the nonlinearity \( F(\partial u) = -(\partial_t u)^3 \), but the cubic null condition is violated for this nonlinearity. Asymptotic behavior of global solutions under the Agemi condition (1.6) was studied in [21] and improved in [18]. In particular, it was proved in [18] that the energy of the global solution \( u \) decreases to zero as \( t \to \infty \) if the inequality in (1.6) is strict, i.e.,

\[
P(\omega) > 0, \quad \omega \in S^1.
\]

(1.8)

In other words, \( F \) satisfying (1.8) serves as a nonlinear dissipation (at least for small data). A typical example satisfying (1.8) is \( F(\partial u) = -(\partial_t u)^3 \), for which \( P(\omega) = 1 \). It should be emphasized that the general theory of nonlinear dissipation in Mochizuki–Motai [24] does not cover the case of \( \Box u = -(\partial_t u)^3 \) in two space dimensions (see also [26] and the references cited therein for the theory of nonlinear dissipation).

In this paper, we will unify two global existence results mentioned above: One is the global existence result under the quadratic and cubic null conditions (1.4)–(1.5) in [2]; another is the result under the Agemi condition (1.6) and \( F^q(\partial u) \equiv 0 \) in [10] and [21]. We will also investigate a condition, corresponding to (1.8), to ensure that the nonlinearity works as nonlinear dissipation for systems.

Now we would like to introduce our condition:

\[ \text{(Ag)} \]

There is an \( N \times N \)-matrix valued continuous function \( A = A(\omega) \) on \( S^1 \) such that \( A(\omega) \) is a positive-definite symmetric matrix for each \( \omega \in S^1 \), and that

\[
Y \cdot A(\omega) F^{c,\text{red}}(\omega, Y) \geq 0, \quad (\omega, Y) \in S^1 \times \mathbb{R}^N.
\]
where the symbol \( \cdot \) denotes the standard inner product in \( \mathbb{R}^N \).

Here and in what follows, \( \mathbb{R}^N \)-vectors are always regarded as column vectors. Observe that the cubic null condition (1.5) implies (Ag) with \( \mathcal{A}(\omega) = I_N \), where \( I_N \) is the \( N \times N \) identity matrix. Observe also that (Ag) with \( N = 1 \) coincides with the Agemi condition (1.6), because we have (1.7), and \( \mathcal{A}(\omega) \) in (Ag) plays no essential role when \( N = 1 \). Thus we may say that the condition (Ag) is the Agemi condition for systems.

**Theorem 1.1.** Suppose that the quadratic null condition (1.4) and the condition (Ag) are satisfied. Then, for any \( f, g \in C^\infty_0(\mathbb{R}^2; \mathbb{R}^N) \), there exists a positive constant \( \varepsilon_0 \) such that the Cauchy problem (1.1)–(1.2) admits a unique global \( C^\infty \)-solution \( u \) for \( (t,x) \in [0,\infty) \times \mathbb{R}^2 \) if \( \varepsilon \in (0,\varepsilon_0] \).

**Remark 1.1.** For systems (1.1) with cubic nonlinearity, another kind of extension of the cubic null condition is studied in [15]. There is no inclusion between the condition in [15] and the condition (Ag) here.

In [17], systems of semilinear wave equations with quadratic nonlinearity in three space dimensions are studied, and a sufficient condition, which is weaker than the null condition, for small data global existence is obtained. Our condition (Ag) above can be viewed as a two space dimensional version of the condition in [17]. Theorem 1.1 can be proved by a method similar to [17] (and also to [18]). However, we need some modification to treat the quadratic nonlinearity by using a generalized energy estimate due to Alinhac [2] and [4] (see Lemma 2.5 below). Theorem 1.1 will be proved in Section 3.

Now we turn our attention to the decay of the energy. We define the energy norm \( \| u(t) \|_E \) by

\[
\| u(t) \|_E = \left( \frac{1}{2} \int_{\mathbb{R}^2} \sum_{a=0}^{2} |\partial_a u(t,x)|^2 \, dx \right)^{1/2}.
\]

**Theorem 1.2.** In addition to (1.4) and (Ag), we assume that

\[
Y \cdot \mathcal{A}(\omega) F^{c,\text{red}}(\omega,Y) \neq 0, \quad (\omega,Y) \in \mathbb{S}^1 \times (\mathbb{R}^N \setminus \{0\}).
\]

Let \( u \) be the global solution to (1.1)–(1.2) whose existence is guaranteed by Theorem 1.1. For any \( \delta > 0 \), there exists a positive constant \( C \) such that

\[
\| u(t) \|_E \leq \frac{C\varepsilon}{(1 + \varepsilon^2 \log(t + 2))^{\frac{1}{2} - \delta}}, \quad t \geq 0,
\]

provided that \( \varepsilon \) is sufficiently small.

If \( N = 1 \) and \( F^q(\partial u) \equiv 0 \), the assumption in Theorem 1.2 is nothing but (1.8). Although the expression is slightly different, we can easily check that the energy decay rate in [18] coincides with the above rate. In [18], the decay of the energy was obtained as a corollary to a general theorem on the pointwise asymptotics of the global solutions under the condition (1.6). Explicit solvability of some related ordinary differential equations plays an essential
role in the derivation of the asymptotics in [18]. It seems quite difficult to apply this method to our system, because we need to solve a related system of ODEs explicitly. Therefore we take another approach to analyze solutions to the related system of ODEs without solving it explicitly. Theorem 1.2 will be proved in Section 4.

Remark 1.2. Under the assumption of Theorem 1.2, we also have an enhanced pointwise decay estimate for \( \partial u \). See (4.3) below.

Remark 1.3. In [18], single but complex-valued wave equations with cubic gauge-invariant semilinear terms are treated in fact, and the complex version of (1.6) was considered. However, the results on global existence and the energy decay in [18] are easily recovered by our results here, by rewriting a single equation of a complex-valued unknown as a two-component system of real unknowns through the standard identification of \( \mathbb{C} \) with \( \mathbb{R}^2 \).

Remark 1.4. For closely related results on nonlinear Schrödinger equations and nonlinear Klein-Gordon equations, see [16] and [19], respectively.

We conclude this section by giving some examples satisfying our conditions (1.4), (Ag) and (1.9). Throughout this paper, we will use the following convention on implicit constants: The expression \( f = \sum'_{\lambda \in \Lambda} g_\lambda \) means that there exists a family \( \{ C_\lambda \}_{\lambda \in \Lambda} \) of constants such that \( f = \sum_{\lambda \in \Lambda} C_\lambda g_\lambda \).

Example 1.1 (Quadratic terms satisfying the null condition (1.4)). It is well known that the null condition (1.4) is satisfied if and only if

\[
F_j^0(\partial u) = \sum'_{1 \leq k, l \leq N} Q_0(u_k, u_l) + \sum'_{1 \leq k, l \leq N} Q_{ab}(u_k, u_l),
\]

(1.10)

where the null forms \( Q_0 \) and \( Q_{ab} \) are given by

\[
Q_0(\phi, \psi) = (\partial_t \phi)(\partial_t \psi) - (\nabla_x \phi) \cdot (\nabla_x \psi),
\]

(1.11)

\[
Q_{ab}(\phi, \psi) = (\partial_a \phi)(\partial_b \psi) - (\partial_b \phi)(\partial_a \psi), \quad 0 \leq a, b \leq 2
\]

(1.12)

(see [20] for instance). Similarly to (1.10), it is also known that the cubic null condition (1.5) is satisfied if and only if

\[
F_j^c(\partial u) = \sum'_{1 \leq k, l, m \leq N} (\partial_c u_m) Q_0(u_k, u_l) + \sum'_{1 \leq k, l, m \leq N} (\partial_c u_m) Q_{ab}(u_k, u_l)
\]

(see [13] for example). These nonlinear terms can be added freely without affecting the conditions (Ag) or (1.9).

Example 1.2 (Cubic terms satisfying the condition (Ag)). We begin with simple examples satisfying (Ag). When \( N = 1 \), \( F^c(\partial u) = - (\partial u)^3 \) is an example of the cubic terms satisfying (Ag) and (1.9), as we have mentioned above. Next we focus on the case of two-component systems (i.e., \( N = 2 \)). Consider

\[
F^c(\partial u) = \begin{pmatrix} F_1^c(\partial u) \\ F_2^c(\partial u) \end{pmatrix} = \begin{pmatrix} -a(\partial_t u_1)^3 + b(\partial_t u_1)(\partial_t u_2)^2 \\ -(\partial_t u_2)^3 \end{pmatrix}
\]
with $a \geq 0$ and $b \in \mathbb{R}$, whose reduced nonlinearity is
\[
F^{\text{c, red}}(\omega, Y) = \left( aY_1^3 - bY_1Y_2^2 \right). 
\]

- If $a = 0$ and $b \leq 0$, we have
\[
Y \cdot F^{\text{c, red}}(\omega, Y) = -bY_1^2Y_2^2 + Y_2^4 \geq 0, \quad (\omega, Y) \in S^1 \times \mathbb{R}^2,
\]
whence the condition (Ag) is satisfied with $A(\omega) = I_2$.

- If $a > 0$, then the conditions (Ag) and (1.9) are satisfied for all $b \in \mathbb{R}$. Indeed, by choosing $A(\omega) = \begin{pmatrix} 1 & 0 \\ 0 & 1 + (2a)^{-1}|b|^2 \end{pmatrix}$, we have
\[
Y \cdot A(\omega)F^{\text{c, red}}(\omega, Y) = \frac{a}{2}Y_1^4 + Y_2^4 + \left( \sqrt{\frac{a}{2}Y_1^2} - \sqrt{\frac{1}{2a}}|b|Y_2^2 \right)^2 + (|b| - b)Y_1^2Y_2^2.
\]

**Example 1.3** (A cubic term satisfying (Ag) and (1.9) with a non-diagonal weight). We give a bit less trivial example. Let $N = 2$ and consider
\[
F^c(\partial u) = \begin{pmatrix} F_1^c(\partial u) \\ F_2^c(\partial u) \end{pmatrix}
\]
with
\[
F_1^c(\partial u) = -((\partial_t u_1)^3 - (\partial_t u_2)^3 - \frac{1}{2}((\partial_t u_1)^2 - (\partial_t u_2)^2)(\partial_2 u_1 - \partial_2 u_2),
\]
\[
F_2^c(\partial u) = (\partial_t u_1)^3 - 3(\partial_t u_1)^2(\partial_t u_2)
\]
\[
+ \frac{1}{2}((\partial_1 u_1)(\partial_2 u_1) - (\partial_1 u_2)(\partial_2 u_2))(\partial_1 u_1 - \partial_1 u_2),
\]
whose reduced nonlinearity is
\[
F^{\text{c, red}}(\omega, Y) = \begin{pmatrix} Y_1^3 + Y_2^3 - \omega_1^2\omega_2(Y_1^2 - Y_2^2)/2 \\ -Y_1^3 + 3Y_1^2Y_2 + \omega_1^2\omega_2(Y_1^2 - Y_2^2)/(Y_1 - Y_2)/2 \end{pmatrix}.
\]
By choosing
\[
A(\omega) = 4\begin{pmatrix} 2 - \omega_1^2\omega_2 & 1 - \omega_1^2\omega_2 \\ 1 - \omega_1^2\omega_2 & 2 - \omega_1^2\omega_2 \end{pmatrix} = 2\begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} 3 - 2\omega_1^2\omega_2 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix},
\]
we get
\[
Y \cdot A(\omega)F^{\text{c, red}}(\omega, Y)
\]
\[
= (Y_1 + Y_2) \begin{pmatrix} 3 - 2\omega_1^2\omega_2 & 0 \\ 0 & 1 \end{pmatrix}
\]
\[
\times \begin{pmatrix} (Y_1 + Y_2)^3 - (Y_1 - Y_2)^3 \\ (Y_1 - Y_2)^3 + (3 - 2\omega_1^2\omega_2)(Y_1 + Y_2)(Y_1 - Y_2)^2 \end{pmatrix}
\]
\[
= (3 - 2\omega_1^2\omega_2)(Y_1 + Y_2)^4 + (Y_1 - Y_2)^4.
\]
Observing that $3 - 2\omega_1^2 \omega_2 \geq 1$ for $\omega \in S^1$, we see that (Ag) and (1.9) are satisfied for this cubic nonlinearity.

2 Preliminaries

2.1 Commuting vector fields

In this subsection, we recall basic properties of the vector fields associated with the wave equation. In what follows, we denote several positive constants by $C$ which may vary from one line to another. For $y \in \mathbb{R}^d$ with a positive integer $d$, the notation $(y) = (1 + |y|^2)^{1/2}$ will be often used.

We introduce

\[
S := t\partial_t + \sum_{j=1}^2 x_j \partial_j, \quad L_1 := t\partial_t + x_1 \partial_t, \quad L_2 := t\partial_t + x_2 \partial_t, \quad \Omega := x_1 \partial_2 - x_2 \partial_1,
\]

and we set

\[
\Gamma = (\Gamma_0, \Gamma_1, \ldots, \Gamma_6) := (S, L_1, L_2, \Omega, \partial_0, \partial_1, \partial_2).
\]

With a multi-index $\alpha = (\alpha_0, \alpha_1, \ldots, \alpha_6) \in \mathbb{Z}_7^+$, we write $\Gamma^\alpha = \Gamma_0^{\alpha_0} \Gamma_1^{\alpha_1} \cdots \Gamma_6^{\alpha_6}$, where $\mathbb{Z}_7^+$ denotes the set of non-negative integers. For a smooth function $\psi = \psi(t, x)$ and a non-negative integer $s$, we define

\[
|\psi(t, x)|_s = \sum_{|\alpha| \leq s} |\Gamma^\alpha \psi(t, x)|, \quad \|\psi(t, x)\|_s = \sum_{|\alpha| \leq s} \|\Gamma^\alpha \psi(t, x)\|_{L^2(\mathbb{R}^2)}.
\]

It is easy to see that $[\square, L_j] = [\square, \Omega] = [\square, \partial_a] = 0$ for $j = 1, 2$ and $a = 0, 1, 2$, where $[A, B] = AB - BA$ for operators $A$ and $B$. We also have $[\square, S] = 2\square$. Therefore for any $\alpha = (\alpha_0, \alpha_1, \ldots, \alpha_6) \in \mathbb{Z}_7^+$ and a smooth function $\psi$, we have

\[
\square \Gamma^\alpha \psi = \tilde{\Gamma}^\alpha \square \psi,
\]

where $\tilde{\Gamma}^\alpha = (\Gamma_0 + 2)^{\alpha_0} \Gamma_1^{\alpha_1} \cdots \Gamma_6^{\alpha_6}$. We can check that

\[
[\Gamma_a, \Gamma_b] = \sum'_{0 \leq c \leq 6} \Gamma_c, \quad [\Gamma_a, \partial_b] = \sum'_{0 \leq c \leq 2} \partial_c.
\]

Hence for any $\alpha, \beta \in \mathbb{Z}_7^+$, and any non-negative integer $s$, there exist positive constants $C_{\alpha, \beta}$ and $C_s$ such that

\[
|\Gamma^\alpha \Gamma^\beta \psi(t, x)| \leq C_{\alpha, \beta} |\psi(t, x)|_{|\alpha|+|\beta|},
\]

\[
C_s^{-1} |\partial \psi(t, x)|_s \leq \sum_{0 \leq a \leq 2} \sum_{|\gamma| \leq s} |\partial_a \Gamma^\gamma \psi(t, x)| \leq C_s |\partial \psi(t, x)|_s
\]

for any smooth function $\psi$. 

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For $x \in \mathbb{R}^2$, we use the polar coordinates $r = |x|$ and $\omega = |x|^{-1}x$, so that $x = r\omega$ and $\partial_r = \sum_{j=1}^{2}(x_j/|x|)\partial_j$. We put $\partial_{\pm} := \partial_t \pm \partial_r$ and $D_{\pm} := 2^{-1}(\partial_r \pm \partial_t)$. We also introduce

$$\hat{\omega} := (-1, \omega_1, \omega_2).$$

Remark that

$$D_{+} = \frac{1}{2(t + r)}\left(S + \omega_1L_1 + \omega_2L_2\right),$$

which implies a gain of $(t+r)^{-1}$ in $D_{+}$ with the aid of $\Gamma$’s. Writing $\partial_j$ in the polar coordinates, we get

$$\left| (\partial_j - \omega_j\partial_r)\psi(t, x) \right| \leq \frac{1}{r}|\Omega\psi(t, x)| = \frac{1}{t + r}|(\Omega + \omega_1L_2 - \omega_2L_1)\psi(t, x)| \leq C\frac{|\Gamma\psi(t, x)|}{t + r}, \quad j = 1, 2$$

for a smooth function $\psi$. Since $\partial_t = -D_+ + D_-$ and $\partial_r = D_- + D_+$, it follows from (2.3) and (2.4) that

$$|\partial\psi(t, x) - \hat{\omega}D_-\psi(t, x)| \leq C(t + r)^{-1}|\Gamma\psi(t, x)|.$$  

Now we summarize a couple of useful lemmas which will be needed in the subsequent sections.

**Lemma 2.1.** Let $\Lambda_T := \{(t, x) \in [0, T) \times \mathbb{R}^2; |x| \geq t/2 \geq 1\}$. There is a positive constant $C$ such that

$$\left| |x|^{1/2}\partial_{\pm}(t, x) - \hat{\omega}D_-(|x|^{1/2}\psi(t, x)) \right| \leq C(t + |x|)^{-1/2}|\psi(t, x)|_1$$

for $(t, x) \in \Lambda_T$ and $\psi \in C^1([0, T) \times \mathbb{R}^2)$.

**Lemma 2.2.** (i) Let $\psi$ be a smooth solution to

$$\Box \psi(t, x) = G(t, x), \quad (t, x) \in (0, T) \times \mathbb{R}^2$$

with initial data $\psi = \partial_t \psi = 0$ at $t = 0$. Then there exists a universal positive constant $C$, which is independent of $T$, such that

$$\langle t + |x| \rangle^{1/2}|\psi(t, x)| \leq C \sum_{|\alpha| \leq 1} \int_0^t \frac{||\Gamma^\alpha G(\tau, \cdot)||_{L^1(\mathbb{R}^2)}}{\langle \tau \rangle^{1/2}} d\tau,$$

for $(t, x) \in (0, T) \times \mathbb{R}^2$.

(ii) Let $\psi^0$ be a smooth solution to $\Box \psi^0(t, x) = 0$ for $(t, x) \in (0, T) \times \mathbb{R}^2$ satisfying $\psi^0(0, x) = (\partial_t \psi^0)(0, x) = 0$ for $|x| \geq R$ with some $R > 0$. Then there is a positive constant $C_R$, depending only on $R$, such that

$$\langle t + |x| \rangle^{1/2}|\psi^0(t, x)| \leq C_R\|\psi^0(0)\|_2, \quad (t, x) \in [0, T) \times \mathbb{R}^2.$$  

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Lemma 2.3. For any non-negative integer $s$, there exists a positive constant $C_s$ such that

$$|\partial \psi(t,x)|_s \leq C_s(t - |x|)^{-1}|\psi(t,x)|_{s+1}, \quad (t,x) \in [0, T) \times \mathbb{R}^2$$

for any $\psi \in C^{s+1}([0, T) \times \mathbb{R}^2)$.

Lemma 2.1 is a consequence of (2.5). See [18] for its proof. The estimate (2.6) in Lemma 2.2 is often called Hörmander’s $L^1$–$L^\infty$ estimate, which is proved in [7]. The estimate (2.7) for $t > 1$ is an easy consequence of (2.6) and the energy identity via the cut-off argument, while (2.7) for $0 \leq t \leq 1$ follows from the energy identity and the Sobolev embedding theorem (see [23] for example). Lemma 2.3 is due to Lindblad [22]; only the case of three space dimensions is treated in [22], but the two-dimensional case can be similarly proved (see [18] for instance).

### 2.2 The null condition and the generalized energy estimate

First we recall the estimates for quadratic terms satisfying the null condition (1.4). Using (2.5), we have

$$|Q_0(\phi, \psi)| + \sum_{a,b=0}^2 |Q_{ab}(\phi, \psi)| \leq C(t + r)^{-1}(|\partial \phi| |\Gamma \psi| + |\Gamma \phi| |\partial \psi|), \quad (2.8)$$

where $Q_0$ and $Q_{ab}$ are the null forms defined by (1.11) and (1.12). Since $\Gamma^\alpha(Q_0(\phi, \psi))$ or $\Gamma^\alpha(Q_{ab}(\phi, \psi))$ for any $\alpha \in \mathbb{Z}_+^7$ can be written as a linear combination of $Q_0(\Gamma^\beta \phi, \Gamma^\gamma \psi)$ and $Q_{cd}(\Gamma^\beta \phi, \Gamma^\gamma \psi)$ with $|\beta| + |\gamma| \leq |\alpha|$ and $0 \leq c, d \leq 2$, (1.10) and (2.8) yield the following lemma (see [20] for the details):

**Lemma 2.4.** Suppose that (1.4) is satisfied. For $s \in \mathbb{Z}_+$, we have

$$|F^a(\partial u)|_s \leq C(t + |x|)^{-1} \left( |\partial u| |\Gamma u|_s + |\partial u|_{s/2} |\Gamma u|_{s-1} + |\Gamma u|_{s/2} |\partial u|_s \right)$$

with a positive constant $C$. Here, $|\cdot|_{-1}$ is regarded as 0.

We must make use of this enhanced decay to treat $F^a$ in the energy estimate. However, if we use Lemma 2.4 in the standard energy inequality, we need some estimate for $|\Gamma u|_s$ which does not follow form the standard energy inequality. To overcome this difficulty, we use a generalized energy inequality due to Alinhac [2] and [4]. We introduce

$$Z = (Z_1, Z_2) = \left( \frac{x_1}{|x|} \partial_1 + \partial_t, \frac{x_2}{|x|} \partial_1 + \partial_2 \right).$$

**Lemma 2.5.** Let $T \in (0, \infty]$. Suppose that $\psi = \psi(t,x)$ is a smooth function satisfying

$$\Box \psi(t,x) = G(t,x), \quad (t,x) \in (0, T) \times \mathbb{R}^2.$$
For any \( \rho > 1 \), there is a positive constant \( C \), depending only on \( \rho \), such that
\[
\| \partial \psi(t) \|_{L^2(\mathbb{R}^2)}^2 + \int_0^t \left( \int_{\mathbb{R}^2} |Z\psi(\tau, y)|^2 \left( \frac{\tau}{|y|} \right)^{\rho} \, dy \right) \, d\tau
\leq C \| \partial \psi(0) \|_{L^2(\mathbb{R}^2)}^2 + C \int_0^t \left( \int_{\mathbb{R}^2} |G(\tau, y)(\partial_t \psi)(\tau, y)| \, dy \right) \, d\tau
\]
for \( t \in [0, T) \).

For the convenience of the readers, we will give the proof of this lemma in the appendix.

Next we introduce an auxiliary notation related to the operator \( Z \). For a non-negative integer \( s \) and a smooth function \( \psi \), we put
\[
|\psi(t, x)|_{Z,s} = \sum_{k=1}^{2} \sum_{|\alpha| \leq s} |Z_k \Gamma^\alpha \psi(t, x)|.
\]
Observing that
\[
S = x_1 Z_1 + x_2 Z_2 + (t - |x|) \partial_t, \quad L_k = |x| Z_k + (t - |x|) \partial_k, \quad k = 1, 2, \quad \Omega = x_1 Z_2 - x_2 Z_1,
\]
we can easily obtain the following lemma:

**Lemma 2.6.** For \( s \in \mathbb{Z}_+ \), we have
\[
|\Gamma \psi(t, x)|_s \leq C |x| |\psi(t, x)|_{Z,s} + \langle t - |x| \rangle |\partial \psi(t, x)|_s
\]
with a positive constant \( C \).

As a consequence, we have the following:

**Corollary 2.1.** Suppose that (1.4) is satisfied. For \( s \in \mathbb{Z}_+ \), we have
\[
|F^\alpha(\partial u)|_s \leq C \left( |\partial u|_{Z,s} + |\partial u|_{s/2} |u|_{Z,s-1} \right) + C \langle t + |x| \rangle^{-1} |u|_{s/2+1} |\partial u|_s
\]
with a positive constant \( C \). Here, \( | \cdot |_{Z,-1} \) is regarded as 0.

**Proof.** By Lemmas 2.6 and 2.3, we have
\[
|\partial u||\Gamma u|_s \leq C \langle t + |x| \rangle |\partial u|_{Z,s} + C \langle t - |x| \rangle |\partial u| |u|_s
\]
as well as
\[
|\partial u|_{s/2} |\Gamma u|_{s-1} \leq C \langle t + |x| \rangle |\partial u|_{s/2} |u|_{Z,s-1} + C \langle t - |x| \rangle |\partial u|_{s/2} |\partial u|_{s-1}
\]
\[
\leq C \langle t + |x| \rangle |\partial u|_{s/2} |u|_{Z,s-1} + C |u|_{s/2+1} |\partial u|_{s-1}.
\]
The desired inequality follows immediately from them and Lemma 2.4. \( \square \)
2.3 The profile equation

Let \( 0 < T \leq \infty \), and let \( u \) be the solution to (1.1)-(1.2) on \([0,T) \times \mathbb{R}^2\). We suppose that

\[
\text{supp } f \cup \text{supp } g \subset B_R
\]

for some \( R > 0 \), where \( B_M = \{ x \in \mathbb{R}^2; |x| \leq M \} \) for \( M > 0 \). Then, from the property of finite propagation, we have

\[
\text{supp } u(t, \cdot) \subset B_{t+R}, \quad 0 \leq t < T.
\]

Now we put \( r = |x|, \omega = (\omega_1, \omega_2) = x/|x| \) so that

\[
r^{1/2} \Box \phi = \partial_+ \partial_- (r^{1/2} \phi) - \frac{1}{4r^{3/2}} (4\Omega^2 + 1) \phi.
\]

We define \( U = (U_j)_{1 \leq j \leq N} \) by

\[
U(t, x) := D_-(r^{1/2} u(t, x)), \quad (t, x) \in [0, T) \times (\mathbb{R}^2 \setminus \{0\})
\]

for the solution \( u \) of (1.1). In view of Lemma 2.1, the asymptotic profile as \( t \to \infty \) of \( \partial u \) should be given by \( \hat{\omega} U/r^{1/2} \), because we can expect \( |u(t, x)| \to 0 \) as \( t \to \infty \). Also it follows from (2.11) that

\[
\partial_+ U(t, x) = -\frac{1}{2t} F^{c, \text{red}}(\omega, U(t, x)) + H(t, x),
\]

where \( F^{c, \text{red}}(\omega, Y) \) is defined by (1.3), and \( H = H(t, x) \) is given by

\[
H = -\frac{1}{2} \left( r^{1/2} F(\partial u) - \frac{1}{t} F^{c, \text{red}}(\omega, U) \right) - \frac{1}{8r^{3/2}} (4\Omega^2 + 1) u.
\]

As Lemma 2.7 below indicates, \( H \) can be regarded as a remainder when (1.4) is satisfied. For these reasons, we call (2.13) the profile equation associated with (1.1), which plays an important role in our analysis.

We also need an analogous equation for \( \Gamma^\alpha u \) with a multi-index \( \alpha \in \mathbb{Z}^7_+ \). For this purpose, we put

\[
U^{(\alpha)}(t, x) := D_-(r^{1/2} \Gamma^\alpha u(t, x)).
\]

Since \( \Box (\Gamma^\alpha u) = \tilde{\Gamma}^\alpha (F(\partial u)) \), we deduce from (2.11) that

\[
\partial_+ U^{(\alpha)} = -\frac{1}{2t} G_\alpha(\omega, U, U^{(\alpha)}) + H_\alpha
\]

for \( |\alpha| \geq 1 \), where \( G_\alpha = (G_{\alpha,j})_{1 \leq j \leq N} \) and \( H_\alpha \) are given by

\[
G_{\alpha,j}(\omega, U, U^{(\alpha)}) = \sum_{k=1}^N \frac{\partial F^{c, \text{red}}_j}{\partial Y_k}(\omega, U) U^{(\alpha)}_k
\]
and

\[ H_\alpha(t, x) = -\frac{1}{2} \left( r^{1/2} \Gamma^\alpha (F(\partial u)) - \frac{1}{t} G_\alpha (\omega, U, U^{(\alpha)}) \right) \]

\[ - \frac{1}{8r^{3/2}} (4\Omega^2 + 1) \Gamma^\alpha u, \]

(2.17)

respectively.

We close this section with preliminary estimates for \( H \) and \( H_\alpha \), in terms of the solution \( u \), near the light cone. We put

\[ \Lambda_{T,R} := \{(t, x) \in [0, T) \times \mathbb{R}^2; 1 \leq t/2 \leq |x| \leq t + R\}. \]

Note that we have

\[ \langle t + |x|^{-1}, 1 \rangle \leq 2t^{-1} \leq 3(1 + t)^{-1} \leq 3(\langle R \rangle + 2)(t + |x|)^{-1} \]

for \((t, x) \in \Lambda_{T,R}\). In other words, the weights \(\langle t + |x|^{-1}, (1+t)^{-1}, |x|^{-1}\) and \(t^{-1}\) are equivalent to each other in \(\Lambda_{T,R}\). For \(s \in \mathbb{Z}_+\), we also introduce an auxiliary notation \(|\cdot|_{s, s}\) by

\[ |\phi(t, x)|_{s, s} := |\partial\phi(t, x)|_s + \langle t + |x|^{-1} |\phi(t, x)|_{s+1}. \]

(2.18)

**Lemma 2.7.** Suppose that the null condition (1.4) is satisfied. There is a positive constant \(C\), which is independent of \(T\), such that

\[ |H(t, x)| \leq Ct^{-1/2}(1 + t)|\partial u|^2 + |u|_{[s, 0]}|u|_1 + Ct^{-3/2}|u|_2 \]

(2.19)

for \((t, x) \in \Lambda_{T,R}\), provided that \(\sup_{(t,x) \in \Lambda_{T,R}} |\partial u(t, x)|\) is small enough. Also, for \(s \geq 1\), there is a positive constant \(C_s\), not depending on \(T\), such that

\[ \sum_{|\alpha|=s} |H_\alpha(t, x)| \leq C_s t^{1/2} |\partial u|_{s-1}^3 + C_s t^{-1/2}(1 + t)|\partial u|_s^2 + |u|_{s,s} |u|_{s+1}^s \]

\[ + C_s t^{-3/2}|u|_{s+2} \]

(2.20)

for \((t, x) \in \Lambda_{T,R}\), provided that \(\sup_{(t,x) \in \Lambda_{T,R}} |\partial u(t, x)|_{[s/2]}\) is small enough.

**Proof.** Let \((t, x) = (t, r\omega) \in \Lambda_{T,R}\) in what follows. We put

\[ F^h(\partial u) = F(\partial u) - (F^h(\partial u) + F^c(\partial u)), \]

so that we have \(F^h(\partial u) = O(|\partial u|^4)\) for small \(\partial u\).

First we consider the estimate for \(H\). We decompose it as follows:

\[ H = -\frac{1}{2} \left( r^{1/2} F(\partial u) - r^{-1} F^{c, \text{red}}(\omega, U) \right) - \frac{t - r}{2rt} F^{c, \text{red}}(\omega, U) \]

\[ - \frac{1}{8r^{3/2}} (4\Omega^2 + 1) u. \]
It is easy to see that the third term can be dominated by \( Ct^{-3/2} |u|_2 \). To estimate the second term, we note that
\[
|U| \leq r^{1/2} |D_{-} u| + \frac{C}{(t+r)^{1/2}} |u| \leq C r^{1/2} |u|_{\infty,0}
\]
and that
\[
\langle t - r \rangle |U| \leq C t^{1/2} \left( \langle t - r \rangle |\partial u|_0 + \frac{\langle t - r \rangle}{(t+r)} |u|_0 \right) \leq C t^{1/2} |u|_1,
\]
where we have used Lemma 2.3 to get the last inequality. Then we obtain
\[
\frac{|t - r|}{r t} |F^{\text{red}}(\omega, U)| \leq C t^{-1} \langle t - r \rangle |U| \cdot (r^{-1/2} |U|)^2 \leq C t^{-1/2} |u|_1 |u|_{\infty,0}^2.
\]
As for the first term, we deduce from Lemmas 2.4 and 2.1 that
\[
\begin{align*}
&|r^{1/2} F(\partial u) - r^{-1} F^{\text{red}}(\omega, U)| \\
&\leq |r^{1/2} F^q(\partial u)| + |r^{1/2} F^h(\partial u)| + |r^{1/2} F^c(\partial u) - r^{-1} F^{\text{red}}(\omega, U)| \\
&\leq Ct^{-1/2} |u|_1 |\partial u| + C t^{1/2} |\partial u|^4 \\
&+ C \sum_{k,l,m} \sum_{a,b,c} \left| \langle r^{1/2} \partial_a u_k \rangle \langle r^{1/2} \partial_b u_l \rangle \langle r^{1/2} \partial_c u_m \rangle - (\omega_u U_k)(\omega_u U_l)(\omega_u U_m) \right| \\
&\leq C t^{-1/2} |u|_1 |u|_{\infty,0} + C t^{1/2} |\partial u|^2 |u|_{\infty,0} |u|_1 \\
&+ C (|\partial u| + r^{-1/2} |U|) r^{1/2} \partial u - \omega U | \\
&\leq C t^{-1/2} (1 + t |\partial u|^2 + |u|_{\infty,0} |u|_1 |u|_{\infty,0} |u|_1).
\end{align*}
\]
Summing up, we arrive at (2.19).

Next we turn to the estimate for \( H_\alpha \) with \(|\alpha| = s \geq 1\). We set \( \tilde{F}_c^\alpha = (\tilde{F}_c^\alpha)_{1,j \leq N} \) with
\[
\tilde{F}_{\alpha,j}^c = \sum_{k,l,m=1}^N \sum_{a,b,c=0}^2 C_{jkim}^{abc} \left\{ (\Gamma^\alpha \partial_a u_k)(\partial_b u_l)(\partial_c u_m) + (\partial_a u_k)(\Gamma^\alpha \partial_b u_l)(\partial_c u_m) \\
+ (\partial_a u_k)(\partial_b u_l)(\Gamma^\alpha \partial_c u_m) \right\}
\]
to split \( H_\alpha \) into the following form:
\[
H_\alpha = - \frac{r^{1/2}}{2} \tilde{G}_\alpha^c \left( F^q(\partial u) + F^h(\partial u) \right) - \frac{r^{1/2}}{2} \left( \tilde{G}_\alpha^c (F^c(\partial u)) - \tilde{F}_c^\alpha \right) \\
- \left( \frac{r^{1/2}}{2} \tilde{F}_c^\alpha - r^{-1} G_\alpha \right) - \frac{t - r}{2 r t} G_\alpha - \frac{1}{8 t^{3/2}} (4 \Omega^2 + 1) \Gamma^\alpha u.
\]
The second term can be estimated by \( C t^{1/2} |\partial u|^3_{s-1} \), since it consists of a linear combination of the terms having the form
\[
r^{1/2} (\Gamma^\beta \partial_a u_k)(\Gamma^\gamma \partial_b u_l)(\Gamma^\delta \partial_c u_m).
\]
with $k, l, m \in \{1, \ldots, N\}$, $a, b, c \in \{0, 1, 2\}$, and $|\beta|, |\gamma|, |\delta| \leq s - 1$. Other four terms can be treated in the same way as in the previous case; they are dominated by

$$Ct^{-1/2}(1 + t|\partial u|^2 + |u|^s)u_{t,s}|u|_{s+1} + Ct^{-3/2}|u|_{s+2}.$$ 

Therefore we obtain (2.20) as desired.

3 Proof of the small data global existence

The argument of this section is almost parallel to that of Section 5 in [17], where quadratic semilinear systems of wave equations in $\mathbb{R}^3$ are considered. However, the argument becomes slightly more complicated because we are considering lower dimensional case here.

Let $u(t, x)$ be a smooth solution to (1.1)–(1.2) on $[0, T_0) \times \mathbb{R}^2$ with some $T_0 \in (0, \infty]$. For $0 < T \leq T_0$, we put

$$e[u](T) = \sup_{(t, x) \in [0, T) \times \mathbb{R}^2} \left( (t + |x|)^{(1/2) - \mu}|u(t, x)|_{k+1} + \langle t - |x| \rangle^{1/2} \langle t - |x| \rangle^{1-\mu} |\partial u(t, x)| \right)$$

with some $\mu, \nu > 0$ and a positive integer $k$. We also put

$$e[u](0) = \lim_{T \to +0} e[u](T).$$

Observe that there is a positive constant $\varepsilon_1$ such that $0 < \varepsilon \leq \varepsilon_1$ implies $e[u](0) \leq \sqrt{\varepsilon}/2$, because we have $e[u](0) = O(\varepsilon)$.

The main step in the proof of Theorem 1.1 is to show the following:

**Proposition 3.1.** Let $k \geq 4$, $0 < \mu < 1/10$ and $0 < (8k + 7)\nu \leq \mu$. There exist positive constants $\varepsilon_2$ and $M$, which depend only on $k, \mu$ and $\nu$, such that

$$e[u](T) \leq \sqrt{\varepsilon}$$

implies

$$e[u](T) \leq M\varepsilon,$$

provided that $0 < \varepsilon \leq \varepsilon_2$ and $0 < T \leq T_0$.

Once the above proposition is obtained, the small data global existence for (1.1)–(1.2) can be derived by the standard continuity argument: Let $T^*$ be the supremum of such $T \in (0, \infty)$ that the Cauchy problem (1.1)–(1.2) admits a unique classical solution $u \in C^\infty([0, T) \times \mathbb{R}^2; \mathbb{R}^N)$, and assume that $T^* < \infty$. Then, it follows from the standard blow-up criterion (see, e.g., [25]) that

$$\lim_{t \to T^*-0} \left( \|u(t, \cdot)\|_{L^\infty(\mathbb{R}^2)} + \|\partial u(t, \cdot)\|_{L^\infty(\mathbb{R}^2)} \right) = \infty.$$
On the other hand, by setting

\[ T^* = \sup \{ T \in [0, T^*) : e[u](T) \leq \sqrt{\varepsilon} \}, \]

we can see that Proposition 3.1 yields \( T^* = T^* \), provided that \( \varepsilon \) is small enough. Indeed, if \( T_* < T^* \), then we have \( e[u](T_*) \leq \sqrt{\varepsilon} \), and Proposition 3.1 implies that

\[ e[u](T_*) \leq M\varepsilon \leq \frac{\sqrt{\varepsilon}}{2} \]

for \( 0 < \varepsilon \leq \min \{ \varepsilon_1, \varepsilon_2, 1/(4M^2) \} \) (note that we have \( T_* > 0 \) for \( \varepsilon \leq \varepsilon_1 \)). Then, by the continuity of the mapping \([0, T^*) \ni T \mapsto e[u](T)\), we can take \( \delta > 0 \) such that \( e[u](T_* + \delta) \leq \sqrt{\varepsilon} \), which contradicts the definition of \( T_* \), and we conclude that \( T_* = T^* \).

In particular, we have \( e[u](T^*) \leq \sqrt{\varepsilon} \). This implies that (3.3) never occurs for small \( \varepsilon \). In other words, we must have \( T^* = \infty \), that is, the solution \( u \) exists globally for small data.

This completes the proof of Theorem 1.1.

From this proof, we see that

\[ e[u](\infty) \leq \sqrt{\varepsilon} \]  

holds for the global solution \( u \) with small \( \varepsilon \), and Proposition 3.1 again yields

\[ e[u](\infty) \leq M\varepsilon. \]  

Proof of Proposition 3.1. In what follows, we always suppose that \( 0 \leq t < T \), and that \( 0 < \varepsilon \leq 1 \). Let \( R \) be the constant satisfying (2.9). Recall that we also have (2.10) for the solution \( u \). The proof of Proposition 3.1 will be divided into several steps.

**Step 1: Basic energy estimates.**

We set

\[ E_l(t) = \frac{1}{2} \| \partial u(t) \|_l^2 + \frac{1}{2} \int_0^t \left( \int_{\mathbb{R}^2} \frac{|u(\tau, y)|^2 z_{l,1} dy}{|\tau - y|^{1+\mu}} \right) d\tau. \]

The goal of this step is to establish the following estimates:

\[ E_l(t)^{1/2} \leq C\varepsilon(t)^{C_*+2\nu} \]  

for \( l \in \{ 0, 1, \ldots, 2k + 1 \} \), where the constant \( C_* \) is to be fixed.

Let \( 0 \leq l \leq 2k + 1 \). In the sequel, we will use the following conventions:

\[ |\partial u|_{-1} = 0, \quad |u|_{Z,-1} = 0, \quad \|\partial u\|_{-1} = 0, \quad E_{-1}(t) = 0. \]

From (2.1), (2.2) and Lemma 2.5, we get

\[ E_l(t) \leq C_{1,l} \|\partial u(0)\|_l^2 + C_{1,l} \int_0^t \left( \int_{\mathbb{R}^2} |F(\partial u(\tau, y))|_l |\partial u(\tau, y)| dy \right) d\tau, \]  

where \( C_{1,l} \) is a positive constant depending only on \( l \). It follows from (3.1) that

\[ |F(\partial u) - F^\varepsilon(\partial u)|_l \leq C_l \left( |\partial u|^2 |\partial u|_l + |\partial u|_{l/2}^2 |\partial u|_{l-1} \right) \leq C_l \varepsilon(t)^{-1} |\partial u|_l + C_l \varepsilon(t)^{2\nu-1} |\partial u|_{l-1} \]  

(3.8)
with a positive constant $C_l$ depending only on $l$. By Corollary 2.1, we also have
\[
|F^q(\partial u)|_l \leq C_l \sqrt{\varepsilon} (t-r)^{-1/2} \langle t-r \rangle^{\mu-1} \langle |u|_{Z,l} + \langle t \rangle^\nu |u|_{Z,l-1} \rangle + C_l \sqrt{\varepsilon} (t)^{-3/2} |\partial u|_l.
\]
(3.9)

Since $\mu - 1 \leq -(1 + \mu)/2$, we deduce from (3.8) and (3.9) that
\[
|F(\partial u)|_l \leq |F^q(\partial u)|_l |\partial u|_l + |F(\partial u) - F^q(\partial u)|_l |\partial u|_l
\leq C_l \sqrt{\varepsilon} (t-r)^{-1+\mu/2} \langle |u|_{Z,l} + \langle t \rangle^\nu |u|_{Z,l-1} \rangle \cdot \langle t \rangle^{-1/2} |\partial u|_l
+ C_l \varepsilon^{3/4} (t)^{1/2} |\partial u|_{l-1} \cdot \langle t \rangle^{-1/2} |\partial u|_l
\leq C_l \sqrt{\varepsilon} \langle t-r \rangle^{1+\mu} + C_l \sqrt{\varepsilon} (t)^{-1} |\partial u|_{l}^2
+ C_l \varepsilon^{3/2} (t)^{4\nu-1} |\partial u|_{l-1}^2.
\]

By integrating with respect to $(t, x)$, and choosing $\varepsilon$ suitably small, we get
\[
C_{1,l} \int_0^t \left( \int_{\mathbb{R}^2} |F(\partial u(\tau, y))|_l |\partial u(\tau, y)| dy \right) d\tau
\leq \frac{1}{2} E_0(t) + C_{2,l} \sqrt{\varepsilon} \int_0^t (1 + \tau)^{-1} |\partial u(\tau)|_{l-1}^2 d\tau + C_{2,l} \sqrt{\varepsilon} (1 + t)^{2\nu} E_{l-1}(t)
+ C_{2,l} \varepsilon^{3/2} \int_0^t (1 + \tau)^{4\nu-1} |\partial u(\tau)|_{l-1}^2 d\tau
\]
(3.10)

with a positive constant $C_{2,l}$ depending only on $l$.

Now we put $C_* = 2 \max_{1 \leq l \leq 2k+1} C_{2,l}$. We are going to prove (3.6) by induction on $l$. In the case of $l = 0$, it follows from (3.7) and (3.10) that
\[
E_0(t) \leq C \varepsilon^2 + C_* \varepsilon \int_0^t (1 + \tau)^{-1} |\partial u(\tau)|_{l-1}^2 d\tau
\leq C \varepsilon^2 + 2C_* \varepsilon \int_0^t (1 + \tau)^{-1} E_0(\tau) d\tau,
\]
whence the Gronwall lemma implies
\[
E_0(t) \leq C \varepsilon^2 (1 + t)^{2C_* \varepsilon}.
\]

This shows (3.6) for $l = 0$. Next we assume that (3.6) holds for some $l \in \{0, 1, \ldots, 2k\}$.
Then it follows from (3.7) and (3.10) that

\[
E_{l+1}(t) \leq C\varepsilon^2 + C_\varepsilon \sqrt{\varepsilon} \int_0^t (1 + \tau)^{-1} \| \partial u(\tau) \|^2_{l+1} d\tau \\
+ C_\varepsilon \sqrt{\varepsilon} (1 + t)^{2\nu} E_l(t) + C_\varepsilon \varepsilon^{3/2} \int_0^t (1 + \tau)^{4\nu-1} \| \partial u(\tau) \|^2 d\tau \\
\leq C\varepsilon^2 + 2C_\varepsilon \sqrt{\varepsilon} \int_0^t (1 + \tau)^{-1} E_{l+1}(\tau) d\tau + C_\varepsilon \varepsilon^{5/2} (1 + t)^{2C_\varepsilon \sqrt{\varepsilon} + 4(1+\nu)} \\
+ C_\varepsilon^{7/2} \int_0^t (1 + \tau)^{2C_\varepsilon \sqrt{\varepsilon} + 4(1+\nu)} d\tau \\
\leq C\varepsilon^2 + 2C_\varepsilon \sqrt{\varepsilon} \int_0^t (1 + \tau)^{-1} E_{l+1}(\tau) d\tau + C_\varepsilon \varepsilon^{5/2} (1 + t)^{2C_\varepsilon \sqrt{\varepsilon} + 4(1+\nu)},
\]

which yields

\[
E_{l+1}(t) \leq C\varepsilon^2 (1 + t)^{2C_\varepsilon \sqrt{\varepsilon} + 5\varepsilon / (1+C_\varepsilon \sqrt{\varepsilon})} \\
\leq C\varepsilon^2 (1 + t)^{2C_\varepsilon \sqrt{\varepsilon} + 4(\nu + 1)}.
\]

This means that (3.6) remains true when \( l \) is replaced by \( l + 1 \), and (3.6) has been proved for all \( l \in \{0, 1, \ldots, 2k + 1\} \).

**Step 2: Rough pointwise estimates.**

From now on, we assume that \( \varepsilon \leq (\nu / C_\varepsilon)^2 \). Then, since we have \( k \geq 4 \), it follows from (3.6) with \( l = 2k + 1 \) that

\[
E_{k+5}(t)^{1/2} \leq E_{2k+1}(t)^{1/2} \leq C_\varepsilon \langle t \rangle^{(4k+3)\nu}.
\]

Observing that \( 2(4k + 3)\nu \leq \mu - \nu \) and \( \lfloor (k+5)/2 \rfloor \leq k \), we get

\[
\left\| \left| F(\partial u(t)) - F^q(\partial u(t)) \right|_{k+5} \right\|_{L^1} \leq C \left\| \left| \partial u(t) \right|_{\lfloor (k+5)/2 \rfloor} \right\|_{L^{\infty}} \left\| \partial u(t) \right\|_{k+5}^2 \\
\leq \left( C_\varepsilon^{1/2} \langle t \rangle^{-\nu / (1+\nu)} \right) \left( C_\varepsilon \nu \langle t \rangle^{2(4k+3)\nu} \right) \\
\leq C_\varepsilon^{5/2} \langle t \rangle^{\mu - (1+\nu)}
\]

which yields

\[
\int_0^t \left\| \left| F(\partial u(\tau)) - F^q(\partial u(\tau)) \right|_{k+5} \right\|_{L^1} \langle \tau \rangle^{1/2} d\tau \leq C_\varepsilon^{5/2} \int_0^t \langle \tau \rangle^{\mu - 1} d\tau \\
\leq C_\varepsilon^{5/2} \langle t \rangle^{\mu}.
\] (3.11)

On the other hand, it follows from Corollary 2.1 that

\[
|F^q(\partial u)|_{k+5} \leq C_\varepsilon \sqrt{\varepsilon} \left( \langle t \rangle^{\nu / (1+\nu)} \langle t - \tau \rangle^{(3\nu - 1)/2} \right) \left( t - \tau \right)^{-(\mu+1)/2} \left| u \right|_{k+5} \\
+ C_\varepsilon \sqrt{\varepsilon} \langle t \rangle^{\mu / (3+2)} \left| \partial u \right|_{k+5}.
\]

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Recalling (2.10), we deduce from the Schwarz inequality that
\[
\int_0^t \left\| F^q(\partial u(\tau)) \right\|_{L^1} d\tau
\leq C\sqrt{\varepsilon} \left( \int_0^t \langle \tau \rangle^{\nu - 2} \langle \tau - |\cdot| \rangle^{(4k+3)\nu} \right)^{1/2} E_{k+5}(t)^{1/2}
\]
\[
+ C\sqrt{\varepsilon} \int_0^t \langle \tau \rangle^{\mu - 2} \| \partial u(\tau) \|_{L^2(B_{r+R})} \| | \tau | - | \cdot | \|_{L^2(B_{r+R})}^2 d\tau
\leq C\varepsilon^{1/2} \left( \langle t \rangle^{(3\mu+2)+3(4k+3)\nu} + \langle t \rangle^{(3\mu+2)+3(4k+3)\nu} \right)
\leq C\varepsilon^{1/2} \langle t \rangle^{3\mu}.
\]  
(3.12)

By (3.11), (3.12) and Lemma 2.2, we have
\[
\langle t + |x| \rangle^{1/2} u(t, x)|_{k+4} \leq C_R \| u(0) \|_{k+6} + C \int_0^t \left\| F(\partial u(\tau)) \right\|_{L^1} d\tau
\leq C\varepsilon + C\varepsilon^{3/2} \langle t \rangle^{3\mu}
\leq C\varepsilon \langle t + |x| \rangle^{3\mu},
\]
that is,
\[
|u(t, x)|_{k+4} \leq C\varepsilon \langle t + |x| \rangle^{3\mu - (1/2)}
\]  
(3.13)

for \((t, x) \in [0, T) \times \mathbb{R}^2\). Since \(\langle (k + 3)/2 \rangle \leq k\), we see from Lemmas 2.4 and 2.3 that
\[
|F^q(\partial u)|_{k+3} \leq C \langle t + r \rangle^{-1} \langle |\partial u|_{k+1} |\Gamma u|_{k+3} + |\Gamma u|_{k+1} |\partial u|_{k+3} \rangle
\leq C \langle t + r \rangle^{-1} \langle t - r \rangle^{-1} |u|_{k+1} |u|_{k+3}
\leq C\varepsilon^{3/2} \langle t + r \rangle^{4\mu - 2} \langle t - r \rangle^{-1}
\leq C\varepsilon^{3/2} \langle t \rangle^{5\mu - 2} \langle t - r \rangle^{-1}\mu.
\]

Hence we get
\[
\int_0^t \left\| F^q(\partial u(\tau)) \right\|_{k+3} d\tau \leq C\varepsilon^{3/2} \int_0^t \langle \tau \rangle^{5\mu - (5/2)(1-\mu)} \| | \tau | - | \cdot | \|_{L^1(B_{r+R})}^{-1-\mu} d\tau
\leq C\varepsilon^{3/2} \int_0^t \langle \tau \rangle^{5\mu - (3/2)} d\tau
\leq C\varepsilon^{3/2},
\]  
(3.14)

because \(5\mu - (3/2) < -1\). Now it follows from (3.11), (3.14) and Lemma 2.2 that
\[
\langle t + |x| \rangle^{1/2} u(t, x)|_{k+2} \leq C_R \| u(0) \|_{k+4} + C \int_0^t \left\| F(\partial u(\tau)) \right\|_{L^1} d\tau
\leq C\varepsilon + C\varepsilon^{3/2} \langle t \rangle^{\mu}
\leq C\varepsilon \langle t + |x| \rangle^{\mu}.
\]
In other words, we obtain
\[ |u(t, x)|_{k+2} \leq C \varepsilon (t + |x|)^{\mu - (1/2)} \]
for \((t, x) \in [0, T) \times \mathbb{R}^2\). By Lemma 2.3, we also have
\[ |\partial u(t, x)|_{k+1} \leq C \varepsilon (t + |x|)^{\mu - (1/2)} (t - |x|)^{-1} \]
for \((t, x) \in [0, T) \times \mathbb{R}^2\).

**Step 3: Estimates for \(|\partial u(t, x)|_k\) away from the light cone.**

Now we put \(\Lambda_{T,R} := ([0, T) \times \mathbb{R}^2) \setminus \Lambda_{T,R}\). In the case of \(t/2 < 1\) or \(|x| < t/2\), we see that
\[ \langle t - |x| \rangle \leq \langle t + |x| \rangle \leq C \langle t - |x| \rangle. \]
On the other hand, it follows from (2.10) that \(u(t, x) = 0\) if \(|x| > t + R\). Hence (3.16) implies
\[
\sup_{(t,x)\in \Lambda_{T,R}} \langle t + |x| \rangle^{(3/2)\mu} |\partial u(t, x)|_k \leq C \varepsilon. \quad (3.17)
\]

**Step 4: Estimates for \(|\partial u(t, x)|_k\) near the light cone.**

Let \((t, x) \in \Lambda_{T,R}\). We may assume \(T \geq 2\), because \(\Lambda_{T,R}\) is empty for \(T < 2\). Remember that \(t^{-1}, r^{-1}, (t)^{-1}\) and \((t + r)^{-1}\) are equivalent to each other in \(\Lambda_{T,R}\). We define \(U, U^{(\alpha)}\), \(H, H_{\alpha}\) and \(| \cdot |_{l,s}\) as in the previous section (see (2.12), (2.14), (2.15), (2.17) and (2.18)). We see from (3.15) and (3.16) that
\[
|u(t, x)|_{l,k} \leq C \varepsilon t^{\mu - 1/2} \langle t - |x| \rangle^{-1}. \quad (3.18)
\]

By (2.2), (3.15) and Lemma 2.1, we have
\[
t^{1/2} |\partial u(t, x)|_l \leq C \sum_{|\alpha| \leq l} |x|^{1/2} |\partial \Gamma^{\alpha} u(t, x)|
\leq C \sum_{|\alpha| \leq l} |U^{(\alpha)}(t, x)| + C \varepsilon t^{\mu - 1} \quad (3.19)
\]
for \(l \leq k\). Also, it follows from (3.1), (3.15), (3.18) and Lemma 2.7 that
\[
|H(t, x)| \leq C \varepsilon t^{2\mu - (3/2)} \langle t - |x| \rangle^{-1} + C \varepsilon t^{2\mu - 2} \leq C \varepsilon t^{2\mu - (3/2)} \langle t - |x| \rangle^{-\mu - (1/2)}. \quad (3.20)
\]

Next we put
\[
\Sigma = \left\{ (t, x) \in [0, \infty) \times \mathbb{R}^2; |x| \geq \frac{t}{2} = 1 \text{ or } |x| = \frac{t}{2} \geq 1 \right\}
\]

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and we define $t_{0,\sigma} = \max\{2, -2\sigma\}$. What is important here is that the half line $\{(t, (t + \sigma)\omega); t \geq 0\}$ meets $\Sigma$ at the point $(t_{0,\sigma}, (t_{0,\sigma} + \sigma)\omega)$ for each fixed $(\sigma, \omega) \in \mathbb{R} \times S^1$, so that

$$\Lambda_{T,R} = \bigcup_{(\sigma,\omega) \in (-T/2,R) \times S^1} \{(t, (t + \sigma)\omega); t_{0,\sigma} \leq t < T\}.$$  

We also remark that

$$C^{-1} \langle \sigma \rangle \leq t_{0,\sigma} \leq C\langle \sigma \rangle, \quad \sigma \leq R$$  

with a positive constant $C$ depending only on $R$. When $(t, x) \in \Sigma$, we have $t^\mu \leq C \langle t - |x| \rangle^\mu$. So it follows from (2.2), (3.18) and Lemma 2.1 that

$$\sum_{|\alpha| \leq k} |U^{\alpha}(t, x)| \leq C t^{1/2} |u(t, x)|_{2,k} \leq C \varepsilon (t - |x|)^{\mu - 1}, \quad (t, x) \in \Sigma \cap \Lambda_{T,R}.$$  

Let $A$ be the matrix in the condition (Ag). Since $A$ is positive-definite and continuous on $S^1$, we can find a positive constant $M_0$ such that

$$M_0^{-1} |Y|^2 \leq Y \cdot A(\omega) Y \leq M_0 |Y|^2, \quad (\omega, Y) \in S^1 \times \mathbb{R}^N.$$  

Now we define

$$V(t; \sigma, \omega) = U(t, (t + \sigma)\omega)$$  

for $0 \leq t < T$ and $(\sigma, \omega) \in \mathbb{R} \times S^1$. In what follows, we fix $(\sigma, \omega) \in (-T/2, R) \times S^1$ and write $V(t)$ for $V(t; \sigma, \omega)$. Then, since the profile equation (2.13) is rewritten as

$$\frac{\partial V}{\partial t}(t) = (\partial_t U)(t, (t + \sigma)\omega) = -\frac{1}{2t} F_{c,\text{red}}(\omega, V(t)) + H(t, (t + \sigma)\omega)$$  

for $t_{0,\sigma} < t < T$, it follows from the condition (Ag) that

$$\frac{\partial}{\partial t} (V(t) \cdot A(\omega)V(t)) = 2V(t) \cdot A(\omega) \frac{\partial V}{\partial t}(t)$$

$$= 2V(t) \cdot A(\omega) \left(-\frac{1}{2t} F_{c,\text{red}}(\omega, V(t)) + H(t, (t + \sigma)\omega)\right)$$

$$\leq 2V(t) \cdot A(\omega) H(t, (t + \sigma)\omega)$$

$$\leq C \sqrt{V(t) \cdot A(\omega)V(t)} |H(t, (t + \sigma)\omega)|$$  

for $t_{0,\sigma} < t < T$. We also note that (3.22) for $k = 0$ can be interpreted as

$$|V(t_{0,\sigma})| = |U(t_{0,\sigma}, (t_{0,\sigma} + \sigma)\omega)| \leq C \varepsilon \langle \sigma \rangle^{\mu - 1}.$$  

(3.27)
We deduce from (3.20), (3.21), (3.23), (3.26) and (3.27) that
\[
|V(t)| \leq \sqrt{M_0} \sqrt{V(t) \cdot A(\omega)V(t)}
\]
\[
\leq C \left( \sqrt{V(t_{0,\sigma}) \cdot A(\omega)V(t_{0,\sigma})} + \int_{t_{0,\sigma}}^{t} \left| H(\tau, (\tau + \sigma)\omega) \right| d\tau \right)
\]
\[
\leq C\varepsilon(\sigma)^{\mu-1} + C\varepsilon(\sigma)^{-\mu-(1/2)} \int_{t_{0,\sigma}}^{t} \tau^{2\mu-(3/2)} d\tau
\]
\[
\leq C\varepsilon(\sigma)^{\mu-1} \left\{ 1 + (\langle \sigma \rangle / t_0, \sigma)^{(1/2) - 2\mu} \right\}
\]
\[
\leq C\varepsilon(\sigma)^{\mu-1}
\]
(3.28)
for \(t \geq t_{0,\sigma}\), where \(C\) is independent of \(\varepsilon, \sigma\) and \(\omega\). (3.28) implies
\[
|U(t, x)| = |V(t; |t - x|/|x|)| \leq C\varepsilon(|t - |x||)^{\mu-1}, \quad (t, x) \in \Lambda_{T,R}.
\]
Finally, in view of (3.19) with \(l = 0\), we obtain
\[
\sup_{(t, x) \in \Lambda_{T,R}} (t + |x|)^{1/2} (t - |x|)^{1-\mu} |\partial u(t, x)| \leq C\varepsilon.
\]
(3.29)

**Step 5: Estimates for \(|\partial u(t, x)|_k\) near the light cone.**

For a nonnegative integer \(s\), we set
\[
U^{(s)}(t, x) := \sum_{|\beta| \leq s} U^{(\beta)}(t, x).
\]
Let \(1 \leq |\alpha| \leq k\) and \((t, x) \in \Lambda_{T,R}\). By (3.19) we get
\[
|\partial u(t, x)|_{|\alpha|-1} \leq Ct^{-1/2} U^{(|\alpha|-1)}(t, x) + C\varepsilon t^{\mu-3/2}.
\]
(3.30)
It follows from (3.15), (3.16), (3.18), (3.30) and Lemma 2.7 that
\[
|H_\alpha(t, x)| \leq C(1 + \varepsilon^2 2\mu + \varepsilon t^{\mu-(1/2)})\varepsilon^2 t^{2\mu-(3/2)} (t - |x|)^{-1}
\]
\[
+ C\varepsilon t^{\mu-2} + C\varepsilon^3 t^{\mu-4} + Ct^{-1} U^{(|\alpha|-1)}(t, x)^3
\]
\[
\leq C\varepsilon t^{\mu-(3/2)} (t - |x|)^{-\frac{3\mu-(1/2)}{2}} + Ct^{-1} U^{(|\alpha|-1)}(t, x)^3.
\]
(3.31)
We put
\[
V^{(\alpha)}(t; \sigma, \omega) = U^{(\alpha)}(t, (t + \sigma)\omega)
\]
for \(0 \leq t < T\) and \((\sigma, \omega) \in (-\infty, R] \times S^1\). We fix \((\sigma, \omega) \in (-T/2, R] \times S^1\) and write \(V^{(\alpha)}(t)\) for \(V^{(\alpha)}(t; \sigma, \omega)\). Then (2.16) is rewritten as
\[
\frac{\partial V^{(\alpha)}}{\partial t}(t) = -\frac{1}{2t} G_\alpha(\omega, V(t), V^{(\alpha)}(t)) + H_\alpha(t, (t + \sigma)\omega)
\]
for $t_{0,\sigma} < t < T$. Hence by (3.28) and (3.31) we obtain

$$\frac{\partial}{\partial t} |V^{(\alpha)}(t)|^2 \leq \frac{C}{t} |V(t)|^2 |V^{(\alpha)}(t)|^2 + 2 |H_\alpha(t, (t + \sigma)\omega)| |V^{(\alpha)}(t)| \leq \frac{2C^*\varepsilon^2}{t} |V^{(\alpha)}(t)|^2 + C \left( \varepsilon t^{\mu-(3/2)} \sigma^{-3\mu-(1/2)} + t^{-1}(V^{(\alpha-1)}(t)\right) ^3) |V^{(\alpha)}(t)|,$$

where

$$V^{(s)}(t) = V^{(s)}(t; \sigma, \omega) := \sum_{|\beta| \leq s} |V^{(\beta)}(t; \sigma, \omega)|,$$

and $C^*$ is a positive constant independent of $\alpha$. Therefore it follows from (3.21) and (3.22) that

$$t^{-C^*\varepsilon^2} |V^{(\alpha)}(t)| \leq t_{0,\sigma}^{C^*\varepsilon^2} |V^{(\alpha)}(t_{0,\sigma})| + C\varepsilon\langle \sigma \rangle^{-3\mu-(1/2)} \int_{t_{0,\sigma}}^t \tau^{-C^*\varepsilon^2+4\mu-(3/2)} d\tau + C \int_{t_{0,\sigma}}^t \tau^{-C^*\varepsilon^2-1}(V^{(\alpha-1)}(\tau)) ^3 d\tau \leq C\varepsilon\langle \sigma \rangle^{\mu-1} + C \int_{t_{0,\sigma}}^t \tau^{-C^*\varepsilon^2-1}(V^{(\alpha-1)}(\tau)) ^3 d\tau.$$

By this inequality for $1 \leq |\alpha| \leq l$ and (3.28), we have

$$t^{-C^*\varepsilon^2} V^{(l)}(t) \leq C\varepsilon\langle \sigma \rangle^{\mu-1} + C \int_{t_{0,\sigma}}^t \tau^{-C^*\varepsilon^2-1}(V^{(l-1)}(\tau)) ^3 d\tau$$

for $l \in \{1, \ldots, k\}$. Using this inequality, we can show inductively that

$$V^{(l)}(t) \leq C\varepsilon\langle \sigma \rangle^{\mu-1} t^{3\mu-1} C^*\varepsilon^2$$

for $t_{0,\sigma} \leq t < T$ and $l \in \{1, \ldots, k\}$. Indeed, we already know that

$$V^{(0)}(t) = |V(t)| \leq C\varepsilon\langle \sigma \rangle^{\mu-1}$$

by (3.28). Hence we have

$$t^{-C^*\varepsilon^2} V^{(1)}(t) \leq C\varepsilon\langle \sigma \rangle^{\mu-1} + C\varepsilon^3\langle \sigma \rangle^{3\mu-3} \int_{t_{0,\sigma}}^\infty \tau^{-C^*\varepsilon^2-1} d\tau \leq C\varepsilon\langle \sigma \rangle^{\mu-1},$$

which implies (3.32) for $l = 1$. Next we suppose that (3.32) is true for some $l \in \{1, \ldots, k-1\}$. Then we have

$$t^{-C^*\varepsilon^2} V^{(l+1)}(t) \leq C\varepsilon\langle \sigma \rangle^{\mu-1} + C\varepsilon^3\langle \sigma \rangle^{3\mu-3} \int_{t_{0,\sigma}}^l \tau^{(3\mu-1)C^*\varepsilon^2-1} d\tau \leq C\varepsilon\langle \sigma \rangle^{\mu-1} l^{(3\mu-1)C^*\varepsilon^2},$$

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which yields (3.32) with \( l \) replaced by \( l + 1 \). Hence (3.32) for \( l \in \{1, \ldots, k\} \) has been proved.

By (3.19) and (3.32) with \( l = k \), we have
\[
|\partial u(t, x)|_k \leq C\varepsilon (t + |x|)^{-1/2+3^{k-1}C^*\varepsilon^2} (t - |x|)^{-1+\mu}, \quad (t, x) \in \Lambda_{T,R}.
\]
Finally we take \( \varepsilon \) so small that \( 3^{k-1}C^*\varepsilon^2 \leq \nu \). Then we obtain
\[
\sup_{(t,x)\in\Lambda_{T,R}} \langle t + |x| \rangle^{1/2-\nu} \langle t - |x| \rangle^{1-\mu} |\partial u(t, x)|_k \leq C\varepsilon.
\] (3.33)

The final step.

By (3.15), (3.17), (3.29) and (3.33), we can find two positive constants \( \varepsilon_2 \) and \( M \) such that (3.2) holds for \( 0 < \varepsilon \leq \varepsilon_2 \). This completes the proof of Proposition 3.1. \( \square \)

4 Proof of the energy decay

Before we proceed to the proof of Theorem 1.2, we introduce a useful lemma.

Lemma 4.1. Let \( C_0 > 0, C_1 \geq 0, p > 1, q > 1 \) and \( t_0 \geq 2 \). Suppose that \( \Phi(t) \) satisfies
\[
\frac{d\Phi}{dt}(t) \leq -\frac{C_0}{t} |\Phi(t)|^p + \frac{C_1}{t^q}
\]
for \( t \geq t_0 \). Then we have
\[
\Phi(t) \leq \frac{C_2}{(\log t)^{p^*-1}}
\]
for \( t \geq t_0 \), where \( p^* \) is the Hölder conjugate of \( p \) (i.e., \( 1/p + 1/p^* = 1 \)), and
\[
C_2 = \frac{1}{\log 2} \left( (\log t_0)^p \Phi(t_0) + C_1 \int_{2}^{\infty} \frac{(\log \tau)^p}{\tau^q} d\tau \right) + \left( \frac{p^*}{C_0 p} \right)^{p^*-1}.
\]

Remark 4.1. Special cases of this lemma have been used in Section 4 of [16] and Section 5 of [19] less explicitly.

Proof. It follows from the Young inequality that
\[
|\Phi(t)| = \left( \kappa (\log t) |\Phi(t)|^p \right)^{\frac{1}{p}} \cdot \left( \frac{1}{(\kappa \log t)^{p^*-1}} \right)^{\frac{1}{p^*}}
\]
\[
\leq \frac{\kappa}{p} (\log t) |\Phi(t)|^p + \frac{1}{p^* (\kappa \log t)^{p^*-1}}
\]
for \( \kappa > 0 \). By choosing \( \kappa = C_0 p/p^* \), we have
\[
p^* \frac{(\log t)^{p^*-1}}{t} \Phi(t) \leq (\log t)^p \frac{C_0}{t} |\Phi(t)|^p + \left( \frac{p^*}{C_0 p} \right)^{p^*-1} \frac{1}{t}.
\]

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whence
\[
\frac{d}{dt} (\log t)^p \Phi(t) = (\log t)^p \frac{d\Phi}{dt}(t) + p^*(\log t)^{p^*-1} \Phi(t)
\]
\[
\leq (\log t)^p \left\{ \frac{d\Phi}{dt}(t) + \frac{C_0}{t} |\Phi(t)|^p \right\} + \left( \frac{p^*}{C_0 p} \right)^{p^*-1} \frac{1}{t}
\]
\[
\leq C_1 (\log t)^p + \left( \frac{p^*}{C_0 p} \right)^{p^*-1} \frac{1}{t}.
\]
Integration with respect to \( t \) implies
\[
(\log t)^p \Phi(t) \leq (\log t_0)^p \Phi(t_0) + C_1 \int_{t_0}^t \frac{(\log \tau)^p}{\tau^q} d\tau + \left( \frac{p^*}{C_0 p} \right)^{p^*-1} \log \left( \frac{t}{t_0} \right)
\]
\[
\leq C_2 \log t,
\]
from which we deduce the desired inequality. \( \Box \)

Now we are ready to finish the proof of Theorem 1.2. Note that all the estimates in the proof of Proposition 3.1 are valid with \( T = \infty \), because of (3.4). Let the assumptions of Theorem 1.2 be fulfilled. The conditions (Ag) and (1.9) imply
\[
\min_{|Y|=1, \omega \in S^1} Y \cdot A(\omega) F^{c,\text{red}}(\omega, Y) > 0.
\]
Hence, in view of (3.23), we can choose \( C_0 > 0 \) such that
\[
Y \cdot A(\omega) F^{c,\text{red}}(\omega, Y) \geq C_0 (Y \cdot A(\omega) Y)^2, \quad (\omega, Y) \in S^1 \times \mathbb{R}^N.
\]
For \( (t, x) \in \Lambda_{T,R} \), we fix \( \sigma = |x| - t, \omega = x/|x| \) and set \( \Phi(t) = V(t) \cdot A(\omega) V(t) \) with \( V(t) = V(t; \sigma, \omega) \) defined by (3.24). By (3.20), (3.25) and (3.28), we get
\[
\frac{d\Phi}{dt}(t) = 2V(t) \cdot A(\omega) \frac{dV}{dt}(t) \leq -\frac{C_0}{t} (\Phi(t))^2 + \frac{C' \varepsilon^2 (\sigma)^{-3/2}}{t^{1/2} - 2\mu}
\]
for \( t \geq t_{0,\sigma} \) (cf. (3.26)), where \( C' \) is a positive constant independent of \( t, \sigma, \omega \) and \( \varepsilon \). Therefore we can apply Lemma 4.1 to obtain
\[
\Phi(t) \leq \frac{C_{\sigma,\omega}}{\log t}, \quad t \geq t_{0,\sigma}
\]
(4.1)
with
\[
C_{\sigma,\omega} = \frac{1}{\log 2} \left( (\log t_{0,\sigma})^2 \Phi(t_{0,\sigma}) + C' \varepsilon^2 (\sigma)^{-3/2} \int_{2}^{\infty} \frac{(\log \tau)^2}{\tau^{1/2} - 2\mu} d\tau \right) + \frac{1}{C_0}.
\]
By (3.21) and (3.27), we can find a positive constant \( C_3 \), not depending on \( \varepsilon, \sigma, \omega \) and \( T \), such that \( C_{\sigma,\omega} \leq C_3 \) for all \( (\sigma, \omega) \in (-T/2, R] \times S^1 \). Hence (3.23) and (4.1) lead to
\[
|V(t; \sigma, \omega)| \leq \sqrt{M_0 \Phi(t)} \leq \frac{C_3}{\log t}, \quad t \geq t_{0,\sigma},
\]
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which, together with (3.17) and (3.19), yields
\[ |\partial u(t, x)| \leq Ct^{-1/2}(\log t)^{-1/2}, \quad (t, x) \in [2, \infty) \times \mathbb{R}^2. \]  
(4.2)

By (3.5) and (4.2), we have
\[ |\partial u(t, x)| \leq Ct^{-1/2} \min\{(\log t)^{-1/2}, \varepsilon(R + |t - |x||)^{\mu-1}\} \]  
(4.3)
for \((t, x) \in [2, \infty) \times \mathbb{R}^2\).

On the other hand, we get as well as
\[ \varepsilon > 0 \]  
which, together with (3.17) and (3.19), yields
\[ \int \varepsilon > 0 \]  
\(0\). We choose
\[ \mu = 4\delta_0/(1 + 4\delta_0) \]  
in the definition of \(e[u](T)\). Let \(t \geq 2\). For small \(\varepsilon > 0\) we have \(0 < \rho(t; \varepsilon) < t\), and we get \(0 < t + R - \rho(t; \varepsilon) \leq t + R\). Then it follows from (2.10) that
\[ \|u(t)\|^2_E = \frac{1}{2} \int_{|x| \leq t+R} |\partial u(t, x)|^2 dx = I_1 + I_2, \]
where
\[ I_1 = \frac{1}{2} \int_{|x| \leq t+R - \rho(t; \varepsilon)} |\partial u(t, x)|^2 dx; \]
\[ I_2 = \frac{1}{2} \int_{t+R - \rho(t; \varepsilon) \leq |x| \leq t+R} |\partial u(t, x)|^2 dx. \]
Note that we have \(t^{-1}r \leq t^{-1}(t + R) \leq 1 + R/2\) for \(0 \leq r \leq t + R\), and \(0 < \rho(t; \varepsilon) \leq R + t - r \leq R + |t - r|\) for \(0 \leq r \leq t + R - \rho(t; \varepsilon)\). By using the polar coordinates, we deduce from (4.3) that
\[ I_1 \leq C\varepsilon^2 \int_0^{t+R - \rho(t; \varepsilon)} t^{-1}(R + |t - r|)^{2\mu - 2} r dr \]
\[ \leq C\varepsilon^2 \int_0^{t+R - \rho(t; \varepsilon)} (R + t - r)^{2\mu - 2} dr \]
\[ \leq C\varepsilon^2 \rho(t; \varepsilon)^{2\mu - 1} = \frac{C\varepsilon^2}{(\varepsilon^2 \log t)^{(1/2) - 2\delta_0}}, \]
as well as
\[ I_2 \leq C \int_{t+R - \rho(t; \varepsilon)}^{t+R} t^{-1}(\log t)^{-1} r dr \leq C(\log t)^{-\mu} = \frac{C\varepsilon^2}{(\varepsilon^2 \log t)^{(1/2) - 2\delta_0}}. \]
On the other hand, we get
\[ \|u(t)\|^2_E \leq C\varepsilon^2 \int_0^{t+R} t^{-1}(R + |t - r|)^{2\mu - 2} r dr \leq C\varepsilon^2 \int_{-\infty}^{\infty} (\sigma)^{2\mu - 2} d\sigma \leq C\varepsilon^2. \]
Summing up, we have
\[ \|u(t)\|^2_E \leq \frac{C\varepsilon^2}{(1 + \varepsilon^2 \log t)^{(1/2) - 2\delta_0}} \leq \frac{C\varepsilon^2}{(1 + \varepsilon^2 \log t)^{(1/2) - 2\delta}} \]
for \(t \geq 2\), which completes the proof of Theorem 1.2. \(\square\)
A Proof of Lemma 2.5

First we put

$$\eta(t, x) = \int_{-\infty}^{\mid x \mid - t} \frac{dz}{\langle z \rangle^\rho}, \quad (t, x) \in \mathbb{R} \times \mathbb{R}^2.$$  

Then we can easily check that

$$1 \leq e^{\eta(t,x)} \leq \exp \left( \int_{\mathbb{R}} \frac{dz}{\langle z \rangle^\rho} \right) < \infty \quad \text{(A.1)}$$

and that

$$(\partial_t \eta) |\partial \psi|^2 - 2(\nabla_x \eta) \cdot (\nabla_x \psi) \partial_t \psi = -|Z\psi|^2 \langle t - \mid x \mid \rangle^\rho.$$

Next, as in the usual energy integral method, we compute

$$\frac{d}{dt} \left( \int_{\mathbb{R}^2} e^{\eta} |\partial \psi|^2 dx \right)$$

$$= \int_{\mathbb{R}^2} \left( e^{\eta} (\partial_t \eta) |\partial \psi|^2 + 2e^{\eta} \left\{ (\partial_t \psi)(\partial_\xi \psi) + (\nabla_x \psi) \cdot (\nabla_x \partial_t \psi) \right\} \right) dx$$

$$= 2 \int_{\mathbb{R}^2} e^{\eta} (\square \psi)(\partial_t \psi) dx + \int_{\mathbb{R}^2} e^{\eta} \left\{ (\partial_t \eta) |\partial \psi|^2 - 2(\nabla_x \eta) \cdot (\nabla_x \psi) \partial_t \psi \right\} dx$$

$$= 2 \int_{\mathbb{R}^2} e^{\eta} G \partial_t \psi dx - \int_{\mathbb{R}^2} e^{\eta} \frac{|Z\psi|^2}{\langle t - \mid x \mid \rangle^\rho} dx.$$

By the integration with respect to $t$, we have

$$\int_{\mathbb{R}^2} e^{\eta(t,x)} |\partial \psi(t, x)|^2 dx + \int_{0}^{t} \int_{\mathbb{R}^2} e^{\eta(\tau,x)} \frac{|Z\psi(\tau, x)|^2}{\langle \tau - \mid x \mid \rangle^\rho} dxd\tau$$

$$= \int_{\mathbb{R}^2} e^{\eta(0,x)} |\partial \psi(0, x)|^2 dx + 2 \int_{0}^{t} \int_{\mathbb{R}^2} e^{\eta(\tau,x)} G(\tau, x)(\partial_t \psi)(\tau, x) dxd\tau.$$

With the aid of (A.1), we arrive at the desired estimate. \hfill \Box

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