AN FIO CALCULUS FOR MARINE SEISMIC IMAGING,
II: SOBOLEV ESTIMATES

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ABSTRACT. We establish sharp $L^2$-Sobolev estimates for classes of pseudodifferential operators with singular symbols [29, 22] whose non-pseudodifferential (Fourier integral operator) parts exhibit two-sided fold singularities. The operators considered include both singular integral operators along curves in $\mathbb{R}^2$ with simple inflection points and normal operators arising in linearized seismic imaging in the presence of fold caustics [32, 10, 11].

1. Introduction

This paper is concerned with $L^2$-Sobolev estimates for some classes of operators sharing a common microlocal geometry that displays two different kinds of singularities. One of our results is that in certain cases these singularities interact, producing worse estimates than one might otherwise expect. We begin by describing the main features of this geometry and the motivations for studying these operators.

1.1. The cubic model. In $\mathbb{R}^2$, consider the Hilbert transform along a model curve $\gamma(t) := (t, t^3)$ with a simple inflection point,

\begin{equation}
\mathcal{H}f(x) = p.v. \int_{\mathbb{R}} f(x_1 - t, x_2 - t^3) \frac{dt}{t}.
\end{equation}

It is well known that $\mathcal{H}$ (and similar but much more general operators) are bounded on $L^2(\mathbb{R}^2)$ (see, e.g., [45, 46, 5].) The Schwartz kernel of $\mathcal{H}$ is given by

\begin{equation}
K_{\mathcal{H}}(x, y) = \delta(x_2 - y_2 - (x_1 - y_1)^3) \times p.v. \left( \frac{1}{x_1 - y_1} \right),
\end{equation}

which incorporates both pseudodifferential and Radon transform type singularities. In fact, the wave front set of $K_{\mathcal{H}}$ satisfies the inclusion $WF(K_{\mathcal{H}}) \subset \Delta' \cup C'_0$, where

- $\Delta = \{(x, \xi; x, \xi) : x \in \mathbb{R}^2, \xi \in \mathbb{R}^2 \setminus \{0\}\}$ is the diagonal of $T^*\mathbb{R}^2 \times T^*\mathbb{R}^2$,
- $C'_0$ is the conormal bundle of $\{x_2 - y_2 - (x_1 - y_1)^3 = 0\}$, and
- $'$ denotes the usual twist map in microlocal analysis, sending $(x, \xi; y, \eta) \mapsto (x, \xi; y, -\eta)$.

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The same geometry is present for fractional integral operators along $\gamma$,

$$J_\alpha f(x) = \int f(x_1 - t, x_2 - t^3) \frac{dt}{|t|^{1+\alpha}}, \quad 0 < \alpha < 1.$$  

Similar operators, combining fractional integral singularities along the curve with fractional derivatives transverse to it, have been studied for various curves in $\mathbb{R}^2$ or in nilpotent groups [41, 14, 4]. Operators with kernels that display two different types of singularities arise in a variety of settings and go under various names: In the terminology of [36], $\mathcal{H}$ is a singular Radon transform, while in the language of [29, 22], $\mathcal{H}$ and $J_\alpha$ are pseudodifferential operators with singular symbols. The latter concept was originally introduced to describe parametrices for variable coefficient wave and other real principal type operators, but has since found numerous applications in integral geometry [18, 19] and inverse scattering [20, 26].

In the present paper we obtain sharp $L^2$-Sobolev estimates for a class of operators containing $\mathcal{H}$ and $J_\alpha$, and with similar microlocal geometry. One feature is that in some cases the estimates are worse than one would expect by considering the orders of the pseudodifferential and Fourier integral operator parts of the operators separately. For example,

$$J_\alpha : H^{s}_{\text{comp}} \rightarrow H^{s-r}_{\text{loc}}$$

for $r = \frac{\alpha - 1}{3}$, rather than for $r = \max(\alpha - 1, -\frac{1}{3})$. Such behavior can already be seen, for general families of curves (for $\alpha$ close to 1) in Greenblatt [15].

However, the Schwartz kernels of the operators we are most interested in are not associated with a nested pair of submanifolds [13] in the same way that those of fractional integrals along submanifolds are. We thus need to formulate this class of operators using a microlocal approach: from this point of view, $\mathcal{H} \in I^{-\frac{1}{12}, \frac{1}{12}}(\Delta, C_0)$ and $J_\alpha \in I^{-\frac{1}{12}, \frac{1}{12}}(\Delta, C_0)$, where, for $p, l \in \mathbb{R}$, the space $I^{p,l}(\Delta, C_0)$ denotes the class of operators on $\mathcal{E}'(\mathbb{R}^2)$ whose Schwartz kernels belong to the class of paired Lagrangian distributions associated with the cleanly intersecting Lagrangian manifolds $\Delta'$ and $C_0'$ in $T^*(\mathbb{R}^2 \times \mathbb{R}^2)$. We refer the reader to [29, 22, 30, 18] for the theory of the $I^{p,l}$ classes and to §2 for the basic definitions that we need here. The key facts relevant for this paper are that

(i) The canonical relations $\Delta, C_0$ intersect cleanly in codimension one [18].
(ii) $C_0$ is a folding canonical relation in the sense of Melrose and Taylor [28] or a two-sided fold in the sense of [16] (see §2.1 for details).
(iii) The fold surface of $C_0$ equals its intersection with the diagonal, $\Delta \cap C_0$.

We consider the pair $(\Delta, C_0)$ mainly as a stepping-stone to the seismic geometries described below, and do not study non-translation invariant versions of $\mathcal{H}$ and $J_\alpha$ along the lines of [41, 14, 42, 4].

1.2. Single-source Seismic Imaging. A very similar geometry occurs in a completely unrelated problem, involving forward scattering maps in linearized seismic imaging [32, 10, 11]. Let $Y = \mathbb{R}^3_+ := \{y_3 > 0\}$ model the subsurface of the earth, and $\partial Y = \{y_3 = 0\}$ its surface or the surface of the ocean. Let $\Sigma \subset \partial Y \times \partial Y$ denote a source-receiver manifold of pairs $(s, r)$, and $T > 0$ the total time-length of the seismic experiment. The data space for a typical such imaging experiment is given by the collection $X = \Sigma \times (0, T)$, which corresponds to surface measurements being made at locations $r$ and times $t$, $0 < t < T$, resulting from seismic events with
idealized) delta-function impulses at sources $s$ and time $t_0 = 0$. The dimension of the data space is of course one more than that of the source-receiver manifold. It is known that under fairly general conditions, the corresponding (formally) linearized scattering operator $F$, mapping perturbations in the sound speed $c(y)$ in $Y$ (about a known smooth background $c_0(y)$) to perturbations in the pressure field measured on $X$, is a Fourier integral operator (hereafter referred to as FIO) associated with a canonical relation $C \subset (T^*X \setminus 0) \times (T^*Y \setminus 0)$ \cite{40, 25, 34}. More specifically, for some order $m \in \mathbb{R}$ dictated by the dimensionality of the problem at hand, $F$ belongs to the class of FIOs, $I^m(X,Y;C)$, consisting of operators mapping $\mathcal{E}'(Y) \rightarrow \mathcal{D}'(X)$ whose Schwartz kernels are Fourier integral distributions associated with $C' \subset T^*(X \times Y) \setminus 0$. The $L^2$-Sobolev regularity of the operator $F$, which in turn is tied to the question of microlocal invertibility, turns out to be heavily dependent on the data collection geometry and certain non-degeneracy hypotheses regarding the background sound speed $c_0(y)$, assumed smooth and known. Historically, the first situation to be mathematically analyzed was the single source geometry without caustics, for which (a) the seismic data is obtained from a single source, $s_0 \in \partial Y$ and the receivers range over an open subset of $\partial Y$ (i.e., $\dim X = \dim Y = 3$); and (b) the rays flowing out from the source $s_0$ have no caustics. The latter assumption means the following. Let us consider the smooth conic Lagrangian $\Lambda_{s_0} \subset T^*\mathbb{R}^3 \setminus 0$ obtained from the flowout of the points $(\xi_0, \tau_0)$ in the characteristic variety of the wave equation above the point $(x,t) = (s_0,0)$ using the Hamiltonian vector field of the principal symbol of the background wave operator, $\Box c_0$. There will be no caustics if the spatial projection from this Lagrangian manifold, $\pi_Y : \Lambda_{s_0} \rightarrow Y$, has full rank everywhere (except of course $(s_0,0)$). Beylkin \cite{3} showed that under these assumptions $C$ is a local canonical graph, so that $F^*F$ is an elliptic pseudodifferential operator (hereafter referred to as $\Psi$DO) on $Y$. Application of a left parametrix of $F^*F$ then results in high-frequency linearized seismic inversion. This conclusion also holds for other data geometries, under the traveltime injectivity condition \cite{25, 34, 47}, which ensures that the canonical relation $C$ satisfies the Bolker condition \cite{21}, i.e., $\pi_L : C \rightarrow T^*X \setminus 0$ is an injective immersion; this was further weakened in some situations \cite{47}.

However, caustics are unavoidable in physically realistic velocity models \cite{33} and, since they typically lead to artifacts in images, understanding the structure of $F$ and $F^*F$ when the background sound speed exhibits caustics is a fundamental problem in exploration seismology. Nolan \cite{32} showed that, for the single source geometry with caustics of at most fold type, $C$ is a folding canonical relation. It was then shown that, for any folding relation $C_{fold}$ and any $F \in I^m(C_{fold})$,

$$ F^*F \in I^{2m,0}(\Delta, C_1), $$

with $C_1$ having the properties (i,ii,iii) as in §1.1 above \cite{32, Felea 10}. In particular, for the seismic problem, $F^*F \in I^{2,0}(\Delta, C_1)$.  

1.3. Marine seismic imaging. Another seismic data set of interest comes from marine (or offshore) imaging. A mathematical idealization of the experimental setup is as follows. A survey vessel trails behind it a cable containing both an acoustic source and a line of recording instruments. The point source consists of
an airgun which sends acoustic waves through the ocean to the subsurface. Reflections occur when the sound waves encounter singularities in the soundspeed in the subsurface, such as discontinuities at interfaces of sedimentary layers, and the reflected rays are then received by a linear array of hydrophones towed behind the vessel. The vessel then makes repeated passes along parallel paths (say, parallel to the $x_1$ axis) contained in an open $U \subset \partial Y$. In other words, the source-receiver pairs form an open subset of

$$\Sigma = \{ (r,s) \in U \times U : r = (r_1, r_2, 0), s = (s_1, s_2, 0), r_2 = s_2 \},$$

which is a codimension one in $\partial Y \times \partial Y$. Thus the data set is overdetermined, with $\dim X = 4 > \dim Y = 3$. The forward operator $F \in I^{1-\frac{1}{\alpha}}(X;Y;C)$, and in [11] the first two authors identified the structure of $C$, under a natural extension of the fold caustic assumption to this context. General canonical relations having this structure, along with some additional nondegeneracy conditions, were called folded cross caps, and a composition result was proven: if $C$ is a folded cross cap and $A \in I^{m-\frac{1}{\alpha}}(X;Y;C)$, then

$$A^* A \in I^{2m-\frac{1}{\alpha}}(\Delta, C_2),$$

with $C_2 \subset (T^* Y \setminus 0) \times (T^* Y \setminus 0)$ again satisfying (i,ii,iii) from §1.1. In particular, for the marine seismic imaging problem, $F^* F \in I^{\frac{7}{4}}(\Delta, C_2)$.

Now we can compare the normal operators for the single source and the marine geometries (both in the presence of fold caustics). It follows from [29] [22] that microlocally away from $\Delta \cap C_2$ and for any $p,l \in \mathbb{R}$,

$$I^{p,l}(\Delta, C_2) \hookrightarrow I^{p+l}(\Delta \setminus C_2) + I^p(C_2 \setminus \Delta).$$

From §1.5 and §1.6, one observes that since $l = \frac{1}{2}$ for the marine geometry, the order of the non-$\Psi$DO part, i.e., the FIO part, of the normal operator $F^* F$ is $\frac{1}{2}$ lower than the $\Psi$DO part. On the other hand, from [1.4] and the analogue of (1.6), one sees that for the single source geometry the two orders are the same. In other words, the artifact resulting from the FIO part of the normal operator for the single source data set is at least as strong as the $\Psi$DO part and hence is nonremovable, but the fact that the artifact for the marine data set is $\frac{1}{2}$ lower order (away from $\Delta \cap C_2$) leads one to hope that in this situation the artifact might be removable.

1.4. Objectives and scope. However, the explanation in the previous paragraph is informal in the sense that it ignores the singular behavior of the operators at the intersection $\Delta \cap C_j$, $j = 0, 1, 2$, and the intuition above needs to be justified. As an initial step, one should understand the mapping properties of operators in $I^{p,l}(\Delta, C_j)$. The primary goal of this paper is to obtain sharp $L^2$ Sobolev estimates for operators in $I^{p,l}(\Delta, C_j)$, $j = 0, 1, 2$.

Although there exists a microlocal normal form for a folding canonical relation, $C$, obtained by applying suitable canonical transformations on the left and right [28], when applied to $\Delta$ these same transformations will turn $\Delta$ into some unknown canonical graph. Thus, there is no such normal form for pairs such as $(\Delta, C)$ satisfying (i,ii,iii) in §1.1. For this reason, our results will be limited to the pairs $(\Delta, C_j)$, $j = 0, 1, 2$, described above. In other words, our results apply to general operators with the same cubic geometry underlying $\mathcal{H}, \mathcal{F}_0$; the geometry arising from $F^* F$ for any FIO with a folding canonical relation, including the single source
forward operator; and the geometry for the normal operator in the marine seismic imaging problem. In these cases, one has good control over the phase functions in the oscillatory representations of the operators.

1.5. **Main result.** We show that, for the canonical relations that we consider, the following Sobolev estimates hold:

**Theorem 1.1.** Let $A \in I^{p,l}(\Delta, C_0)$ or $A \in I^{p,l}(\Delta, C_1)$ or $A \in I^{p,l}(\Delta, C_2)$, where the canonical relations $C_j$ are as above. Then $A : H^s_{\text{comp}} \rightarrow H^{s-r}_{\text{loc}}$ for

\[
 r = \begin{cases} 
 p + \frac{1}{6}, & l < -\frac{1}{2}, \\
 p + \frac{1}{6} + \epsilon, & l = -\frac{1}{2}, \forall \epsilon > 0, \\
 p + \frac{l+1}{3}, & -\frac{1}{2} < l < -\frac{1}{2}, \\
 p + l, & l \geq \frac{1}{2}.
\end{cases}
\]  

**Remarks:**

1. Here $H^s$, $H^s_{\text{comp}}$ and $H^s_{\text{loc}}$ denote the standard $L^2$-based Sobolev space and its compactly supported and local variants. Thus our analysis of the Schwartz kernels can be restricted to compact sets in the spatial variables.

2. Away from $\Delta \cap C_i$, which is also the fold surface of $C_i$, the inclusion (1.6) holds, and $I^{p+1}(\Delta \setminus C_i)$ and $I^p(C_i \setminus \Delta)$ satisfy standard Sobolev space estimates associated with local canonical graphs. These estimates are always more regular than the ones mentioned in the statement of Thm. 1.1. Thus it suffices to only consider operators $A$ supported microlocally close to $\Delta \cap C_i$. Keeping in mind both the $\Psi$DO and FIO natures of $I^{p,l}(\Delta, C_i)$ and the loss of $\frac{1}{6}$ derivative for FIOs associated with folding canonical relations [28], in general one certainly needs to take $r \geq \max(p + l, p + \frac{1}{6})$. Thm. 1.1 can therefore be interpreted as saying that, when the strengths of the $\Psi$DO and FIO parts of $A$ are sufficiently close, specifically $-\frac{1}{2} \leq l < \frac{1}{2}$, there is a further loss due to their interaction. We will see in [40] that this loss can in fact occur and Thm. 1.1 is in general sharp. For $l < \frac{1}{2}$ close to $\frac{1}{2}$, this type of behavior is already present in the estimates of Greenblatt [15] for fractional integrals along families of curves.

3. For comparison, it is natural to investigate the analogue of Thm. 1.1 when $C$ is a local canonical graph intersecting $\Delta$ cleanly in codimension one. We address this in Thm. 4.1. Singular Radon transforms over hypersurfaces satisfying the rotational curvature condition are of this general type but with higher codimension intersections. A particular case was first considered by Geller and Stein [12] and the general class is due to Phong and Stein [36]; see also Cuccagna [7], which allows for degenerate canonical relations. Different proofs of $L^2$-boundedness were given in [18, 37]. Our proof of Thm. 4.1 is essentially an adaptation of arguments in [18] using the methodology of parabolic cutoffs, cf. [27], whereas the more degenerate geometry of Thm. 1.1 requires a combination of a parabolic-type decomposition with a two-index dyadic decomposition inspired by the almost orthogonal decompositions of degenerate oscillatory integral operators due to Phong and Stein [38, 39].
1.6. Layout of the paper. In §2 we recall the basic theory of Fourier integral operators associated with a single smooth canonical relation, as well as the paired-Lagrangian operators associated with two cleanly intersecting canonical relations. The oscillatory representation of the two classes of operators under consideration, in particular the normal operators for the linearized marine seismic imaging problem in the presence of fold caustics [11] is also reviewed. In §3 we prove that the regularity exponents in Thm. [11] are sharp, in particular showing that the loss of derivatives for $I_{p,l}^{±}((\Delta, C_0))$ in the range $-\frac{1}{2} \leq l \leq \frac{1}{2}$ in Thm [11] is unavoidable. As a warm-up to the proof of Thm. [11] in §4 we give an analogous result in the case when the canonical relation is a canonical graph; here, a standard parabolic decomposition suffices to establish the Sobolev boundedness. In §5 and §6 we introduce, for the classes $I_{p,l}^{±}((\Delta, C_0))$ and $I_{p,l}^{±}((\Delta, C_2))$ respectively, the phase space decomposition of mixed type which is the main technical feature of the paper. The proof of Thm. [11] is given in §7. Finally, in §8 we examine the Hilbert transform $\mathcal{H}$ along the cubic in more detail. We show that, although elliptic in a naive sense, $\mathcal{H}$ is not microlocally invertible using operators bounded on $L^2$, indicating the difficulty of constructing parametrices for these kinds of operators.

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2. Background

In this section we develop the notation and terminology needed in the sequel, and in particular provide an explicit representation for the operators of interest. We refer the reader to [23, 9, 24] for the theory of classical FIOs, [23, 22, 30, 18] for material on the $I_{p,l}$ classes and parabolic cutoffs, and [11] §§3 and the references there for further details on the relevance of these techniques for linearized seismic imaging. However, for convenience we briefly recall the salient facts in the form needed here.

2.1. Preliminaries. Let $X$ and $Y$ be smooth manifolds and $T^*X \setminus 0, T^*Y \setminus 0$ their cotangent bundles (with the zero-sections deleted), equipped with the canonical symplectic forms $\omega_{T^*X}, \omega_{T^*Y}$. If $\Lambda \subset (T^*X \setminus 0) \times (T^*Y \setminus 0)$ is a conic Lagrangian submanifold with respect to $\omega_{T^*(X \times Y)} = \pi_L^*\omega_{T^*X} + \pi_P^*\omega_{T^*Y}$, then $\Lambda' := \{(x, \xi; y, \eta) : (x, \xi; y, -\eta) \in \Lambda\}$ is called a canonical relation. For example, the conormal bundle of any smooth submanifold $Z \subset Y \times Y$ is a canonical relation. In particular, if $X = Y$, then $\Delta = N^*\Delta_Y \subset (T^*Y \setminus 0) \times (T^*Y \setminus 0)$ is the diagonal relation.

If $\Lambda$ is a Lagrangian, $m \in \mathbb{R}$ and $0 \leq \delta \leq 1 - \rho \leq \rho \leq 1$, then $I_{\rho, \delta}^m(X \times Y, \Lambda)$ denotes the space of Fourier integral distributions of order $m$ and type $(\rho, \delta)$ whose wavefront set is contained in $\Lambda$ (see [9], p. 97), while if $C$ is a canonical relation, the associated class $I_{\rho, \delta}^m(X, Y; C)$ of FIOs of order $m$ and type $(\rho, \delta)$ mapping $\mathcal{E}'(Y) \to \mathcal{D}'(X)$ consists of those operators $A$ whose Schwartz kernels are Fourier integral distributions $K_A \in I_{\rho, \delta}^m(X \times Y; C^0)$ [23, 9]. This is abbreviated to $I_{\rho, \delta}^m(C)$ if $X$ and $Y$ are understood, and if $\rho = 1$ and $\delta = 0$, the subscripts $\rho$ and $\delta$ are omitted. If $\pi_L, \pi_P : C \to T^*Y \setminus 0$ are the natural projections on the left and right, then a canonical relation $C$ is a local canonical graph if and only if one of the projections (and hence the other) is a local diffeomorphism; of course, this can only happen if
\[ \text{dim } X = \text{dim } Y. \text{ In this case, } A \in I^m(C) \implies A : H^s_{\text{comp}}(Y) \to H^{s-m}(Y). \]  

In particular, if \( C = \Delta \), then \( I^m_{\rho,\delta}(\Delta) \) is the class of pseudodifferential operators of order \( m \) and type \((\rho, \delta)\). For our purposes, the definition of this class can be given in terms of multiphase functions [30] and symbol-valued symbols [22, 29], which we now describe.  

For an exposition on clean intersection theory and Fourier integrals, we refer the reader to [13, 9]. Classes of distributions associated with two cleanly intersecting Lagrangian manifolds were introduced by Melrose and Uhlmann [29] and Guillemin and Uhlmann [22] (see also [18] for further relevant discussion). For our purposes, the definition of this class can be given in terms of multiphase functions [30] and symbol-valued symbols [22, 29], which we now describe.

**Definition 2.1.** Given a manifold \( X \) and a positive integer \( M \geq 1 \), let \( \Gamma \) be a cone in \( X \times \mathbb{R}^M \setminus \{0\} \).

(i) A function \( \varphi = \varphi(x; \theta) \in C^\infty(\Gamma) \) is a phase function if it is homogeneous of degree 1 in \( \theta \) and has no critical points as a function of \( (x, \theta) \).

(ii) A phase function \( \varphi \) is said to be non-degenerate in \( \Gamma \) if  
\[
\begin{align*}
  d\varphi(x; \theta) = 0, (x, \theta) &\in \Gamma \implies \text{ the collection of vectors } \\
  \left\{ d_{x,j} \frac{\partial \varphi(x; \theta)}{\partial \theta_j} : j = 1, \ldots, M \right\} &\text{ is linearly independent.}
\end{align*}
\]

(iii) Let \( \Lambda \) be a conic \( C^\infty \) submanifold of \( T^*X \setminus 0 \). A nondegenerate phase function \( \varphi \) is said to parametrize \( \Lambda \) if  
\[ \Lambda = \{(x, d_x \varphi(x; \theta)) : d\varphi(x, \theta) = 0, (x, \theta) \in \Gamma \}. \]

**Definition 2.2.** Let \((\Lambda_0, \Lambda_1)\) be a pair of Lagrangians in \( T^*X \setminus 0 \) that intersect cleanly in codimension \( k \). Let \( \Lambda_0 \in \Lambda_0 \cap \Lambda_1 \) and \( \Gamma \subseteq X \times (\mathbb{R}^N \setminus 0) \times \mathbb{R}^k \) an open conic set. A multiphase function \( \phi \) parametrizing the pair \((\Lambda_0, \Lambda_1)\) is a function \( \phi(x; \theta; \sigma) \in C^\infty(\Gamma) \) such that

(i) \( \phi_0(x; \theta) := \phi(x; \theta; 0) \) is a nondegenerate phase function parametrizing \( \Lambda_0 \) in a conic neighborhood of \( \lambda_0 \), and
Example. It is known [29, 22] that any two pairs of cleanly intersecting Lagrangians are microlocally equivalent. One can thus consider the model pair \((\Lambda_0, \Lambda_1)\) in \(T^*\mathbb{R}^n\) where \(\Lambda_0\) and \(\Lambda_1\) are the conormal bundles of \(\{x = (x_1, \ldots, x_n) = 0\}\) and \(\{x_{k+1} = \cdots = x_n = 0\}\), resp., so that
\[
\Lambda_0 = T^*_0\mathbb{R}^n = \{(x, \xi) : x = 0\}, \\
\Lambda_1 = \{(x, \xi) : x_{k+1} = \cdots = x_n = 0, \xi_1 = \cdots, \xi_k = 0\}.
\]
Then \(\varphi(x; \theta', \sigma) = x \cdot (\sigma, \theta')\), with \(\theta' \in \mathbb{R}^{n-k} \setminus 0\), \(\sigma \in \mathbb{R}^k\), is an example of a multiphase function parametrizing \((\Lambda_0, \Lambda_1)\). In this paper, we will only be concerned with the case \(k = 1\), i.e., codimension one intersections.

Definition 2.3. The space \(S^{\tilde{p}, \tilde{l}}(X \times (\mathbb{R}^N \setminus 0) \times \mathbb{R})\) of symbol-valued symbols of orders \(\tilde{p}, \tilde{l}\), is the set of functions \(a(x; \theta; \sigma) \in C^\infty(X \times (\mathbb{R}^N \setminus 0) \times \mathbb{R})\) such that, for every relatively compact \(K \subset X\), non-negative multi-indices \(\alpha \in \mathbb{Z}^N\), \(\beta \in \mathbb{Z}\) and \(\gamma \in \mathbb{Z}^{\dim X}\), the following differential estimates hold:
\[
|\partial_0^\alpha \partial_\beta \partial_x^\gamma a(x; \theta; \sigma)| \leq C_{\alpha, \beta, \gamma, K} \langle \theta, \sigma \rangle^{\tilde{p}-|\alpha|} \langle \sigma \rangle^{|\gamma|} \langle \xi \rangle^{|\beta|},
\]
for all \((x, y) \in K\), where \(\langle \xi \rangle = (1 + |\xi|^2)^{1/2}\), etc., throughout the paper.

The quantities \(\sup_{x, \theta, \sigma} \langle \theta, \sigma \rangle^{\alpha-\tilde{p}} \langle \sigma \rangle^{\beta-\tilde{l}} |\partial_0^\alpha \partial_\beta \partial_x^\gamma a(x; \theta; \sigma)|\) are referred to as the seminorms for the class \(S^{\tilde{p}, \tilde{l}}\). If \(|\theta| \geq |\sigma|\) on the support of \(a\), then we say that the phase variable \(\theta\) is dominant.

We next define the classes of generalized Fourier integral distributions associated with an intersecting pair of Lagrangians.

Definition 2.4. If \(\Lambda_0, \Lambda_1 \subset T^*(X \times Y) \setminus 0\) are smooth, conic Lagrangians intersecting cleanly in codimension one, then the space of generalized (or paired Lagrangian) Fourier integral distributions of order \(p, l \in \mathbb{R}\) associated to \((\Lambda_0, \Lambda_1)\), denoted \(F^{p, l}(X \times Y; \Lambda_0, \Lambda_1)\), is the set of all locally finite sums of elements of \(F^{p+\tilde{l}}(\Lambda_0) + F^{p}(\Lambda_1)\) and distributions of the form
\[
u(x, y) = \int e^{i\phi(x, y; \theta; \sigma)} a(x, y; \theta; \sigma) d\sigma d\theta,
\]
where \(a \in S^{\tilde{p}, \tilde{l}}(X \times Y \times (\mathbb{R}^N \setminus 0) \times \mathbb{R})\), with
\[
p = \tilde{p} + \tilde{l} + \frac{N + 1}{2} - \frac{\dim X + \dim Y}{4}, \quad l = -\tilde{l} - \frac{1}{2},
\]
and \(\phi(x, y; \theta; \sigma)\) is a multiphase function parametrizing \((\Lambda_0, \Lambda_1)\) on a conic neighborhood of a point \(\lambda_0 \in \Lambda_0 \cap \Lambda_1\).

Remark. Aside from an adjustment in the orders, the paired Lagrangian spaces are symmetric [29, 22] in \(\Lambda_0, \Lambda_1\):
\[
F^{p-l}(\Lambda_0, \Lambda_1) = F^{p-l, -l}(\Lambda_1, \Lambda_0) \supseteq F^{p+l}(\Lambda_0) + F^{l}(\Lambda_1).
\]
Finally, we define the classes of generalized (or paired Lagrangian) Fourier integral operators which are the subject of this paper.
Definition 2.5. (i) If $C_0, C_1 \subset (T^*X \setminus 0) \times (T^*Y \setminus 0)$ are smooth, conic canonical relations intersecting cleanly, then $I^{p,l}(X,Y; C_0, C_1)$ denotes the set of operators $A : \mathcal{E}'(Y) \rightarrow \mathcal{D}'(X)$ with Schwartz kernels $K_A(x,y) \in I^{p,l}(X \times Y; C_0, C_1')$.

(ii) In particular, if $C \subset (T^*Y \setminus 0) \times (T^*Y \setminus 0)$ is a canonical relation intersecting the diagonal relation $\Delta$ cleanly, then the members of the associated class $I^{p,l}(Y; \Delta, C) := I^{p,l}(Y,Y; \Delta, C)$ are referred to as pseudodifferential operators with singular symbols.

The spaces $X$ and $Y$ are suppressed if clear from the context. Equipped with the definitions above, we are now ready to describe the operators of interest.

2.3. Oscillatory integral representation of operators in $I^{p,l}(\Delta, C_i)$. The operators we consider will be of the following two forms.

2.3.1. The cubic model. For the cubic model, the operator $A$ lies in the class $I^{p,l}(Y,Y; \Delta, C_0)$, where $Y$ is an open bounded subset of $\mathbb{R}^2$, and $C_0'$ is the conormal bundle of the cubic $\{x_2 - y_2 = (x_1 - y_1)^3\}$. The kernel of $A \in I^{p,l}(\Delta, C_0)$ can be written as

$$K_A(x,y) = \int_{\mathbb{R}^2} e^{i\phi_0(x,y;\theta)} a(x,y;\theta; \theta_1) d\theta,$$

where the symbol-valued symbol $a \in \mathcal{S}^{p+\frac{3}{2},j-\frac{3}{2}}(Y \times Y \times (\mathbb{R}_{\theta_2} \setminus 0) \times \mathbb{R}_{\theta_1})$, and the multi-phase function $\phi_0$ is given by

$$\phi_0(x,y,\theta) = (x_1 - y_1)\theta_1 + (x_2 - y_2 - (x_1 - y_1)^3)\theta_2.$$

The reader may verify that $\phi_0(x,y;\theta_2; \theta_1)$ is a multi-phase function parametrizing, as in Def. 2.2, the cleanly intersecting pair of canonical relations $(C_0, \Delta)$, in that order. The dominant phase variable is $\theta_2$.

2.3.2. Normal operators for seismic imaging. We now turn to the operator classes $I^{p,l}(Y,Y; \Delta, C_j)$ $j = 1, 2$, where $(\Delta, C_j)$ are the geometries that arise in the analysis of the normal operators $F^*F$ in seismic imaging, as described in the introduction. Here $Y$ is a bounded open subset of $\mathbb{R}^n$, $n \geq 3$ ($n = 3$ for the physical problem).

For the single source problem, the Melrose-Taylor normal form [28] for folding canonical relations, such as the one to which $F$ is associated, gives rise to a particularly simple normal form for the pair $(\Delta, C_1)$, namely $(\Delta, C_0 \times \Delta_{T \mathbb{R}^{n-2}})$. This allows for the estimates for $I^{p,l}(\Delta, C_1)$ to be proven as for $I^{p,l}(\Delta, C_0)$; see §§7.1.

In contrast, the marine data geometry is complicated by the fact that there is only an approximate normal form for folded cross caps. It was shown in [11] that, microlocally near any point in $\Delta \cap C_2$ the pair $(\Delta, C_2)$ can be parametrized, in that order, by a multi-phase function of the form

$$\phi(x,y;\xi; \rho) = (x - y) \cdot \xi + \frac{\rho}{\xi_1} \left( \xi_n - \frac{(x_n + y_n)^2}{4} \xi_1 - P \right),$$

on

$$\{ |\xi_1| \geq \frac{1}{2}(|\xi| + |\rho|) \}.$$
Here, $P = P(x_n, y, \xi')$ is an unknown smooth function on $\mathbb{R} \times \mathbb{R}^n \times (\mathbb{R}^{n-1} \setminus 0)$, homogeneous of degree one in $\xi' = (\xi_1, \cdots, \xi_{n-1})$ and satisfying
\begin{equation}
P|_{\{x_n = y_n\}} = 0, \quad \nabla P|_{\{x_n = y_n\}} = 0
\end{equation}
and
\begin{equation}
||\nabla^2 P|_{x_n, y_n}|| \ll |\xi_1|
\end{equation}
microlocai, i.e., one can arrange for the left hand side of (2.11) to vanish at any chosen base point, and thus be small nearby. Here, $\xi_1$ is a dominant phase variable. Note that we have translated the formulas in (11), which were written in $n-1$ dimensions, to an $n$-dimensional setting.

However, in order to handle this geometry in a way similar to the cubic model $(\Delta, C_0)$, we want a multiphase function that parametrizes the pair $(\Delta, C_2)$ in the reverse order. A prescription from [30], which we now describe, allows us to compute such a phase function explicitly. We observe that $\Delta'$ is the flowout from $C_2 \cap \Delta'$ by the Hamiltonian vector field $H_q$ on $T^* (\mathbb{R}^n \times \mathbb{R}^n)$, where $q(x, \xi, y, \eta) = (x - y, \eta - y, \eta)$.

Starting with $\psi_0(x, y; \xi, \rho) = \phi$ as in (2.8), which parametrizes $C_2$, we solve for $\psi(x, y; \xi, \rho; s)$ satisfying
\begin{equation}
\frac{\partial \tilde{\psi}}{\partial s} = (x_n - y_n) \frac{\partial \tilde{\psi}}{\partial x_1}, \quad \tilde{\psi}|_{s=0} = \psi_0,
\end{equation}
and find that
\begin{equation}
\tilde{\psi} = (x - y) \cdot \xi + \frac{\xi_n \rho}{\xi_1} - \frac{1}{4} (x_n + y_n)^2 \rho - \frac{\rho}{\xi_1} P + s(x_n - y_n) \xi_1.
\end{equation}

Finally, letting $s = \frac{s}{\xi_1}$, this yields the multi-phase function
\begin{equation}
\psi(x, y; (\xi, \rho); \sigma) = (x - y) \cdot \xi + \frac{\xi_n \rho}{\xi_1} - \frac{1}{4} (x_n + y_n)^2 \rho - \frac{\rho}{\xi_1} P + (x_n - y_n) \sigma,
\end{equation}
which parametrizes $(C_2, \Delta)$ in that order according to Def. 2.2. By Def. 2.4 and the relations (2.5) and (2.4), the kernel of an operator $A \in \text{P}^{+l}(\Delta, C_2) = \text{P}^{+l}(\Delta, C_2)$ has a representation, modulo $\text{P}^{+l}(\Delta) + \text{P}^{+l}(C_2)$ of the form
\begin{equation}
K_A(x, y) = \int e^{i\psi(x, y; \xi, \rho; \sigma)} a(x, y; \xi, \rho; \sigma) d\xi d\rho d\sigma,
\end{equation}
with $a \in \text{P}^{+l-\frac{1}{2}} (Y \times (\mathbb{R}^{n+1} \setminus 0) \times \mathcal{R})$, and supp$(a) \subseteq \{ |\sigma| \leq |(\xi, \rho)| \}$.

2.4. A technical tool: the method of stationary phase. In the subsequent sections, especially [5] and [6] we will need to estimate repeatedly the oscillatory integrals that arise from (2.6) and (2.13) as the Schwartz kernels of the compositions $B^* A$ and $B A^*$, where $A, B \in \text{P}^+(\Delta, C_j)$. We will use the method of stationary phase to describe the asymptotic behavior of integrals of the form
\begin{equation}
I(a, \lambda) = \int_{\mathbb{R}^n} e^{i\lambda \varphi(w, a)} g(w, a, \lambda) dw, \quad a \in \mathbb{R}^p
\end{equation}
as $\lambda \to \infty$; for the sake of completeness, we state it in the form needed. The phase function $\varphi$ is assumed to be real-valued and smooth, while the amplitude function
$g$ is assumed to be smooth of compact support in the variables $(w,a) \in \mathbb{R}^n \times \mathbb{R}^p$ with the following growth restriction: there exists some $\eta < \frac{1}{2}$ such that
\begin{equation}
(2.14) \quad \left( \frac{\partial}{\partial w} \right)^\alpha g = O(\lambda^m + \eta |\alpha|) \quad \text{as} \quad \lambda \to \infty, \quad \text{uniformly in} \quad (w,a).
\end{equation}

We state here the principle of stationary phase in a form that we need.

**Lemma 2.6** ([9], p.14). Let $\varphi(w,a) = \frac{1}{2}(Q(a)w,w)$, where $Q$ is a real $n \times n$ nonsingular, symmetric matrix depending continuously on $a$, and let $g$ be an amplitude satisfying (2.14) above. Then $I(a,\lambda)$ has an asymptotic expansion
\[ I(a,\lambda) \sim \left( \frac{2\pi i}{\lambda} \right)^{\frac{n}{2}} \left| \det(Q(a)) \right|^{-\frac{1}{2}} e^{\frac{2\pi i}{\lambda} \text{sgn}(Q(a))} \sum_{r=0}^{\infty} \frac{(R^r g)(0,a,\lambda)}{r!} \lambda^{-r} \]
as $\lambda \to \infty$, uniformly in $a$. Here
\[ R = \frac{i}{2} \left\langle Q(a)^{-1} \frac{\partial}{\partial w}, \frac{\partial}{\partial w} \right\rangle \]
which is a second-order partial differential operator in $w$.

In the sequel, justifying an application of stationary phase will involve identifying an oscillatory integral with (quadratic) phase $\lambda \varphi$ and amplitude $g$, and verifying that (a) the Hessian of $\lambda \varphi$ evaluated at its critical point is nonsingular, and (b) the quantity $(\lambda^{-1} R)^r g$ evaluated at this critical point decays exponentially in $r$.

Also, while the notation $\sim$ was used in the above lemma to denote an asymptotic expansion of $I(a,\lambda)$, in subsequent applications we will use $\sim$ to represent just the leading order term of the asymptotic expansion, with the understanding that the latter also provides the sharp size estimate for $I(a,\lambda)$ for $\lambda \gg 1$.

### 3. Sharpness of Theorem 1.1

We start by showing that, at least for $I^{p,l}(\Delta, C_0)$, the estimates in Thm. 1.1 cannot be improved in general. For $l < -\frac{1}{2}$, the inclusion $I^l(C_0) \subset I^{p,l}(\Delta, C_0)$, cf. (2.5), implies that the Sobolev mapping index $r$ of $I^{p,l}(\Delta, C_0)$ must be at least as large as that of (2.1) for $I^l(C_0)$, i.e., $r \geq p + \frac{1}{2}$. On the other hand, the fact that $I^{p,l}(\mathbb{R}^2) = I^{p,l}(\Delta) \subset I^{p,l}(\Delta, C_0)$ implies that we must have $r \geq p + l$.

In the critical interval $-\frac{1}{2} \leq l < \frac{1}{2}$, we demonstrate the optimality of the estimates of Thm. 1.1 for the fractional integral operators along $(t, t^3)$. For $-\frac{1}{2} < l < \frac{1}{2}$, define, as in (1.3),
\begin{equation}
(3.1) \quad \mathcal{J}_{l+\frac{1}{2}} f(x) = f \ast \left( \delta(x_2 - x_1^3) \frac{\chi(x_1) dx_1}{x_1^{l+\frac{1}{2}}} \right),
\end{equation}
where $\chi \in C_0^\infty(\mathbb{R})$, $\chi(t) \equiv 1$ for $|t| \leq \frac{1}{2}$. Writing the kernel of the operator as an oscillatory integral, it follows from the discussion in §2.3.1 that $\mathcal{J}_{l+\frac{1}{2}} \in I^{-\frac{1}{2},l}(\Delta, C_0)$. Thm. 1.1 therefore implies that $\mathcal{J}_{l+\frac{1}{2}} : H^p_{\text{comp}}(\mathbb{R}^2) \to H^r_{\text{loc}}(\mathbb{R}^2)$ for $r = \frac{2l-1}{6}$. That this cannot be improved is seen as follows. Since the Fourier multiplier of $\mathcal{J}_{l+\frac{1}{2}}$ is
\begin{equation}
(3.2) \quad m_l(\xi) = \int_{\mathbb{R}} e^{-i(\xi_1 t + \xi_2 t^3)} \frac{\chi(t) dt}{|t|^{l+\frac{1}{2}}},
\end{equation}
it suffices to show that
\[
\sup_{\xi \in \mathbb{R}^2} |m(\xi)||\xi|^{\frac{2l}{2l+1}} \geq c > 0.
\]

Using the substitution \( u = \xi_2 t^3 \), \( du = (3\xi_2^{1/3} u^{2/3})^{-1} dt \), one has
\[
m_l(0, \xi_2) = \int e^{-i\xi_2 t^3} \chi(t) dt \frac{|t|}{|t|^{1+\frac{3}{2}}}
\]
(3.3)
\[
= c|\xi_2|^{\frac{2l-1}{6}} \int e^{-iu} \chi(\xi_2^{1/3} u^{4/3}) du \frac{1}{|u|^{1+\frac{2l}{3}}}.\]

Since the improper integral \( \int e^{-iu}|u|^{-\frac{2l+5}{6}} du \) converges to a nonzero value, the same is true for the integral in (3.3).

For \( l = -\frac{1}{2} \), we replace \( |x_1|^{-1} \) by \( \log |x_1| \) in (3.1), which still defines an operator \( \mathcal{J}_0 \in L^{-\frac{1}{2}-\frac{1}{2}}(\Delta, C_0) \) since \( \log |x_1| \) is conormal of order \(-1\) for \( \{x_1 = 0\} \) on \( \mathbb{R} \). The corresponding logarithmic divergence of \( |m_{-\frac{1}{2}}(0, \xi_2)| \cdot |\xi_2|^{\frac{3}{2}} \) then implies that one cannot in general eliminate the loss of \( \epsilon \) derivatives when \( l = -\frac{1}{2} \) in Thm. 1.1.

4. The canonical graph case

As a warmup for the proof of Thm. 1.1 and to provide a background for the decompositions that are needed, we first prove an analogous result under the optimal, nondegenerate microlocal geometry, namely when \( C \) is a canonical graph. While the intersection \( C \cap \Delta \) can be quite singular, we restrict ourselves to the configuration closest to that of Thm. 1.1, namely when \( C \) intersects \( \Delta \) clean, say in codimension \( k \). For example, if \( \gamma \) in (1.1) is replaced with the parabola \((t, t^2)\), then that \( \mathcal{H} \in L^{-\frac{1}{2}-\frac{1}{2}}(\Delta, C) \) for a local canonical graph \( C \), although for families of curves in higher dimensions, the canonical graph condition must always be violated somewhere. We mention in passing that singular Radon transforms associated with a family of \( k \)-dimensional surfaces in \( \mathbb{R}^n \) belong to the class \( L^{-\frac{1}{2}-\frac{1}{2}}(\Delta, C) \), where \( C \) is a local canonical graph under the rotational curvature condition [36], and with \( \Delta \) intersecting \( C \) cleanly in codimension \( k \) [18]. Estimates for such operators are in [31, 12, 36, 18, 37, 43]; see also [7] for worst-case estimates in degenerate cases.

The following result is similar to Thm. 1.1 but much easier to prove due to the nondegeneracy of \( C \). For \( C \) a conormal bundle, related estimates were found by Seeger and Wainger [43].

**Theorem 4.1.** Let \( Y \) be a manifold of dimension \( n \). Let \( C \subset (T^*Y \setminus 0) \times (T^*Y \setminus 0) \) be a local canonical graph intersecting \( \Delta \) clean, in codimension \( k \), \( 1 \leq k \leq n-1 \). If \( A \in L^{n,l}(\Delta, C) \), then \( A : H^s_{\operatorname{comp}}(\Delta, C, \mathbb{R}) \to H^r_{\operatorname{loc}}(\Delta, C, \mathbb{R}) \) for

\[
r = \begin{cases} 
    p, & l < -\frac{k}{2}, \\
    p + \epsilon, & l = -\frac{k}{2}, \ \forall \epsilon > 0, \\
    p + \frac{2l+k}{4}, & -\frac{k}{2} < l < \frac{k}{2}, \\
    p + l, & l \geq \frac{k}{2}.
\end{cases}
\]

**Proof.** We prove the theorem using a standard parabolic cutoff. Parabolic cutoffs in various guises have been used often in microlocal analysis; the argument given
here is a direct adaptation of that in [18], but related ideas are also in [31, 37, 27]. Since \( A \in \mathcal{P}^l(\Delta, C) = \mathcal{P}^{l-\frac{1}{2}}(\Delta, C) \) by (2.5), we can assume that \( A \) has kernel

\[
K_A(x, y) = \int_{\mathbb{R}^{N+1}} e^{i\phi(x, y; \theta, \sigma)} a(x, y; \theta; \sigma) d\theta d\sigma,
\]

where \( \phi \) is a multiphase function parametrizing the cleanly intersecting pair \((C, \Delta)\) and \( a \in S^{p-\frac{n}{2}-l-\frac{1}{2}}(Y \times Y \times (\mathbb{R}^N \setminus 0) \times \mathbb{R}) \). Decompose

\[
a = \chi\left( \frac{\langle \sigma \rangle}{\langle \theta \rangle} \right) \cdot a + \left( 1 - \chi\left( \frac{\langle \sigma \rangle}{\langle \theta \rangle} \right) \right) \cdot a := a_0 + a_1,
\]

with \( A = A_0 + A_1 \) the corresponding decomposition of \( A \). Since \( \langle \sigma \rangle \geq c\langle \theta \rangle \frac{1}{2} \) on \( \text{supp}(a_1) \), the differential estimates on \( a_1 = a_1(x, y; (\theta, \sigma)) \) ensure that it is a standard (non product-type) symbol,

\[
a_1 \in \begin{cases} S^{p-\frac{n}{2}+\frac{1}{2}(l-\frac{1}{2})}\left( Y \times Y \times (\mathbb{R}^{N+k} \setminus 0) \right), & l < \frac{1}{2}, \\ S^{p+\frac{1}{2}+\frac{n+k+1}{2}}\left( Y \times Y \times (\mathbb{R}^{N+k} \setminus 0) \right), & l \geq \frac{1}{2}. \end{cases}
\]

Since \( \phi(x, y; (\theta, \sigma)) \) parametrizes \( \Delta \), this implies that

\[
A_1 \in \Psi_{\frac{1}{2}, \frac{1}{2}}^{\max(p+\frac{k}{2}, p+l)}(Y).
\]

We now turn to \( A_0 \), whose Schwartz kernel is of the form (4.2), but with the amplitude \( a \) replaced by \( a_0 \). Recalling that \( \phi(x, y; \theta, 0) \) parametrizes \( C \) and reasoning as in [18, Prop. 2.1], let us integrate out \( \sigma \) and write

\[
K_{A_0}(x, y) = \int_{\mathbb{R}^N} e^{i\phi(x, y; \theta, 0)} b_0(x, y; \theta) d\theta,
\]

where

\[
b_0(x, y; \theta) = e^{i\phi(x, y; \theta, \sigma)-\phi(x, y; \theta, 0)} a_0(x, y; \theta, \sigma) d\sigma.
\]

Keeping in mind the symbol estimates for \( a_0 \) and the homogeneity of \( \phi \) in \((\theta, \sigma)\), the argument in [18] carries over with minor modifications to yield

\[
b_0 \in S^{p-\frac{n}{2}+\frac{1}{2}(l+\frac{1}{2})}_0, \quad \text{and hence} \quad A_0 \in \mathcal{P}^{p+\frac{1}{2}(l+\frac{1}{2})}_0(C).
\]

Here, and throughout, for \( t \in \mathbb{R} \), we set

\[
t_+ = \begin{cases} t & \text{if } t \geq 0, \\ 0 & \text{if } t < 0, \text{ and} \\ \text{any } \epsilon > 0 & \text{for } t = 0. \end{cases}
\]

Combining (4.5), (4.4) it follows from the Calderón-Vaillancourt theorem and its extension to FIOs of type \((\frac{1}{2}, \frac{1}{2})\) associated with local canonical graphs [2] [18] that \( A : H^s_{comp} \to H^{s-r}_{loc} \) for

\[
r \geq \max\left( p + \frac{1}{2}(l+\frac{k}{2}), p + \frac{2l+k}{4}, p+l \right),
\]
which yields (4.1). The calculations of \[ \text{§3} \] are easily modified for the curve \((t, t^2)\) to show that Theorem 4.1 is sharp, at least for \(k = 1\). \(\square\)

When \(C\) is a folding canonical relation, more involved decompositions of \(A\), requiring additional knowledge of the multiphase functions, are needed to prove the analogous estimates. \[ \text{§5, §6, §7} \] are devoted to dealing with the cases when \(C\) has one of the forms described in \[ \text{§2.3} \].

5. Mixed Parabolic-Phong-Stein Decompositions for \(I^{p,l}(\Delta, C_0)\)

In the previous section, we described and applied the method of parabolic cut-offs in the context of FIOs associated with canonical graphs. There is also a method introduced by Phong and Stein [38, 39] for proving \(L^2\) estimates using dyadic decompositions in phase space; this, along with variations, has proven to be a powerful technique for controlling oscillatory integral operators and FIOs with degenerate canonical relations [42, 8, 6, 17]. In the present context, our analysis of operators in \(I^{p,l}(\Delta, C_j)\), \(j = 0, 2\), will combine these two decomposition strategies. In this section, we describe this for the class \(I^{p,l}(\Delta, C_0)\), where we recall that 

\[
C_0 = N^- \{(x_2 - y_2 = (x_1 - y_1)^3)'\}.
\]

Appropriate modifications of these decompositions for \(I^{p,l}(\Delta, C_2)\) will be dealt with in \[ \text{§6} \].

5.1. Components of the operator. Let \(\{\chi_j : j \geq 0\}\) be a non-homogeneous dyadic partition of unity on \(\mathbb{R}\) such that

\[
\text{supp} (\chi_0) \subset \{ |t| \leq 2 \},
\]

\[
\text{supp} (\chi_j) \subset \{ 2^{j-1} \leq |t| \leq 2^{j+1} \}, \quad j \geq 1,
\]

\[
|\chi_j(m)| \leq Cm 2^{-mj}, \quad \text{for all } m \geq 1.
\]

Setting \(\chi_{jk}(\theta) = \chi_k(\theta) \chi_j(\theta)\), we note that \(\{\chi_{jk} : 0 \leq k \leq j < \infty\}\) is a bounded family in \(S^{0,0}\) with respect to the seminorms of (2.2). Furthermore, we set

\[
\chi_\infty := 1 - \sum_{j \geq 0} \sum_{k=0}^j \chi_{jk},
\]

so that \(\chi_\infty \in S^{0,0}_{1,0}\) and is supported in \(\{ |\theta_1| \geq \frac{1}{2} |\theta_2| \}\). Given any \(A \in I^{p,l}(\Delta, C_0)\) whose Schwartz kernel is of the form (2.6), its amplitude \(a(x, y; \theta_2; \theta_1)\) decomposes as

\[
a(x, y; \theta_2; \theta_1) = \left( \sum_{j \geq 0} \sum_{k=0}^j \chi_{jk}(\theta) + \chi_\infty(\theta) \right) \cdot a(x, y; \theta_2; \theta_1)
\]

\[
= \sum_{j=0}^\infty \sum_{k=0}^j a_{jk}(x, y; \theta_2; \theta_1) + a_\infty(x, y; \theta_2; \theta_1).
\]

Thus \(\{a_{jk}\}\) is a bounded family in \(S^{p+\frac{1}{2},l-\frac{1}{2}}\), with

\[
\text{supp} (a_{jk}) \subseteq \{ (x, y ; \theta) : 2^{j-1} \leq |\theta_2| \leq 2^{j+1}, \quad 2^{k-1} \leq |\theta_1| \leq 2^{k+1} \},
\]
and \( a_{\infty} \in S_{1,0}^{p+l} \). The decomposition of the amplitude \( a \) induces a decomposition of the operator \( A \),

\[
A = \sum_{j=0}^{\infty} \sum_{0 \leq k \leq j} A_{jk} + A_{\infty},
\]

where the \( A_{jk} \) and \( A_{\infty} \) are operators whose Schwartz kernels and multi-phase functions are of the form described in \( \S \S 2.3.1 \) (see (2.6) and (2.7)), but with the amplitudes replaced by \( a_{jk} \) and \( a_{\infty} \), resp. Thus, \( A_{\infty} \in I^{p+l}(\Delta_{T^*\mathbb{R}^2}) = \Psi^{p+l}(\mathbb{R}^2) \), and \( \{ A_{jk} : 0 \leq k \leq j < \infty \} \subseteq I^{p+l}(\Delta, C_0) \). It follows from standard \( \Psi DO \) estimates that \( A_{\infty} : H^{s}_{comp} \rightarrow H^{r-\gamma}_{loc}(\mathbb{R}^2) \), which is at least as smoothing as what is being claimed for the entire operator \( A \) in Theorem 1.1. We therefore disregard \( A_{\infty} \) in the sequel.

For a fixed constant \( \delta \in (0,1) \) to be set later (we will eventually take \( \delta \in [\frac{1}{3}, \frac{1}{2}] \)), we group the summands in \( A - A_{\infty} \) as follows,

\[
A - A_{\infty} = A_0 + \sum_{j=1}^{\infty} A_j, \quad \text{where}
\]

\[
A_0 = \sum_{j=0}^{\infty} \sum_{k=0}^{[\delta j]} A_{jk}, \quad A_j = \sum_{k=[\delta j]+1}^{j} A_{jk}, \quad j \geq 1.
\]

In this section we identify \( A_0 \) as a standard FIO associated with the folding canonical relation \( C_0 \) and record several almost orthogonality properties involving the \( A_j \), \( A_{j,\infty} \) and \( A_{jk} \). These facts will be used heavily in the proof of \( L^2 \)-Sobolev estimates.

5.2. Bounds for \( A_0 \).

**Lemma 5.1.** For any \( 0 < \delta < \frac{1}{2} \), the operator \( A_0 \) lies in the class \( I_{1-\delta,\delta}^{m}(C_0) \), where \( m = p + \delta(l + \frac{1}{2})^+ \), and hence maps \( H^{s}_{comp}(\mathbb{R}^2) \) boundedly into \( H^{r-\gamma}_{loc}(\mathbb{R}^2) \), where

\[
r_0 \geq p + \frac{1}{6} + \delta(l + \frac{1}{2})^+.
\]

Here \( t^+_\gamma \) is as in (4.6).

**Proof.** The kernel of \( A_0 \) is of the form (2.6), but with the amplitude replaced by

\[
a_0 = \sum_{j=0}^{\infty} \sum_{k=0}^{[\delta j]} \tilde{a}_{jk}.
\]

We observe that \( \text{supp}(\tilde{a}_0) \subseteq \{ (\theta_1) \leq C(\theta_2)^{\delta} \} \), and that \( \tilde{a}_0 \) satisfies the same differential inequalities as \( \tilde{\chi} (\langle \theta_1 \rangle \langle \theta_2 \rangle^{-\delta}) \cdot a(x,y;\theta_2;\theta_1) \), for some \( \tilde{\chi} \in C_{\infty}^\infty(\mathbb{R}) \). Integrating out \( \theta_1 \) in the oscillatory representation of \( K_{\tilde{A}_0} \), as in the proof of Theorem 1.1, we see that

\[
K_{\tilde{A}_0}(x,y) = \int e^{i\theta_2(x_2-y_2-(x_1-y_1))} \tilde{a}_0(x,y;\theta_2) d\theta_2,
\]

\[
\tilde{a}_0(x,y;\theta_2) = \int e^{i(x_3-y_3)\theta_1} a_0(x,y;\theta_2,\theta_1) d\theta_1.
\]
It is easily verified from the support and differentiability properties of $a_0$, using arguments similar to those used in Theorem 4.1 that $\tilde{a}_0 \in S^{m+\frac{1}{2}}_{1,\delta}$, where $m$ is as in the statement of the lemma. In other words $A_0$ is an FIO associated with the two-sided folding canonical relation $C_0$, of order $m + \frac{1}{2} + \frac{1}{2} - \frac{4}{4} = m$ and with an amplitude of type $(1, \delta)$. Since useful FIO classes need to be invariant under changes of variables and phase functions, we may as well consider (cf. [18]) the type as being $(1 - \delta, \delta)$. Now, $1 - \delta > \frac{1}{2}$ since $\delta < \frac{1}{2}$, so (5.4) follows from [28]. □

5.3. Almost orthogonality. The next two lemmas deal with the almost orthogonality among the components $\{A_{jk}\}$. Both for clarity and for possible future use, we will treat the $A^*$ in $A^*A$ as the adjoint of a general operator $B \in I^{p',l'}(\Delta, C_0)$.

Lemma 5.2 (Almost orthogonality in $j$). Fix $0 < \delta < 1$, and orders $p, p', l, l' \in \mathbb{R}$. Given $A \in I^{p,l}(\Delta, C_0)$ and $B \in I^{p',l'}(\Delta, C_0)$, we decompose $A$ and $B$ as described in §5.1 using the same value of $\delta$ for both. Let $\{A_{jk} : 0 \leq k \leq j\}$ and $\{B_{jk} : 0 \leq k \leq j\}$ denote the components of $A$ and $B$ respectively (see equations (5.2) and
Then for every $N \geq 1$, there exists a constant $C_N > 0$ such that for all $j, j' \geq 1$, $|j - j'| \geq 3$, $\delta j \leq k \leq j$, $\delta j' \leq k' \leq j'$, the following estimate holds:

$$
|B_{j,k}^* A_{j,k}|_{L^2 \rightarrow L^2} \leq C_N 2^{-N \max(j,j')}.
$$

In particular, if $|j - j'| \geq 3$, $j, j' \geq 1$, then

$$
|B_{j}^* A_{j}|_{L^2 \rightarrow L^2} \leq C_N 2^{-N \max(j,j')}.
$$

The same estimates also hold for $B_{j,k}^* A_{j,k}^*$ and $B_j^* A_j^*$.

Proof. We only give the proof for $B^*A$, that for $BA^*$ being similar. The Schwartz kernel of the composition $B_{j,k}^* A_{j,k}$ has the form

$$
K_{B_{j,k}^* A_{j,k}}(x,y) = \int e^{i\Phi(x,y,z;\theta,\theta')} \overline{B_{j,k}^*}(z,x;\theta') a_{j,k}(z,y;\theta) d\theta d\theta' dz,
$$

where the phase function $\Phi$ is given by

$$
\Phi(x,y,z;\theta,\theta') = (z_1 - y_1)\theta_1 - (z_1 - x_1)\theta'_1 + (z_2 - y_2 - (z_1 - y_1)^3)\theta_2 - (z_2 - x_2 - (z_1 - x_1)^3)\theta'_2.
$$

We note that $d_{z_2} \Phi = \theta_2 - \theta'_2$, so that for $|j - j'| \geq 3$ and on supp $(\overline{B_{j,k}^*}, a_{j,k})$,

$$
|d_{z_2} \Phi| \geq (2^{\max(j,j')-1} - 2^{\min(j,j')+1}) \geq \frac{1}{4} 2^{\max(j,j')}.
$$

Integrating by parts $N$ times in $z_2$, integrating in all variables, and applying the support and differentiability properties of $a_{j,k}$ and $\overline{B_{j,k}^*}$ throughout we obtain

$$
|K_{B_{j,k}^* A_{j,k}}(x,y)| \leq C_N 2^{(j+k)+(j'+k')} \times 2^{(p+\frac{1}{2})j+(p'+\frac{1}{2})j'+(l_1-\frac{1}{2})k+(l'-\frac{1}{2})k'-N \max(j,j')}.
$$

Integrating this over the compact support in either $x$ or $y$ yields the estimate

$$
sup_x \int |K_{B_{j,k}^* A_{j,k}}(x,y)| dy + sup_y \int |K_{B_{j,k}^* A_{j,k}}(x,y)| dx \leq C_N 2^{(M-N) \max(j,j')},
$$

where $M = 4 + |p+\frac{1}{2}| + |p'+\frac{1}{2}| + |l-\frac{1}{2}| + |l'-\frac{1}{2}|$ is a fixed constant. Schur’s lemma then implies the same bound for $|B_{j,k}^* A_{j,k}|_{L^2 \rightarrow L^2}$. Since $N$ is arbitrary, the proof of (5.5) is complete. The inequality (5.6) follows from (5.5) simply by summing in $k$ and $k'$. \(\square\)

Lemma 5.3 (Almost orthogonality in $k$). Under the same hypotheses as Lemma 5.2, the following conclusions hold.

(a) There exists a constant $C > 0$ such that for all $j \geq 1$ and $|\delta j| + 1 \leq k \leq j$,

$$
||A_{j,k}||_{L^2 \rightarrow L^2} \leq C 2^{(p+\frac{1}{2})j+(l-\frac{1}{2})k}.
$$

A similar statement holds for $B_{j,k}$.

(b) Now suppose $\delta \geq \frac{1}{3}$. Then, for any $N \geq 1$, there exists a constant $C_N > 0$ such that for all $j, j', k, k' \geq 1$, with $|j - j'| \leq 2$, $|k - k'| \geq 3$, $|\delta j| + 1 \leq k \leq j$ and $|\delta j'| + 1 \leq k' \leq j'$, the following estimate holds:

$$
||B_{j,k}^* A_{j,k}||_{L^2 \rightarrow L^2} \leq C_N 2^{(p+p'+1)j+(l-\frac{1}{2})k+(l'-\frac{1}{2})k'-2^{|k-k'|}N}.
$$

The same estimate holds for $B_{j,k}^* A_{j,k}$. 

We now turn to part (b), where we deal with the “off-diagonal terms” $K_{\lambda'k'}B_{j^*k'}A_{j}$. Proof. For any choice of indices $j, j', k, k'$ with $|\delta j| + 1 \leq k \leq j$ and $|\delta j'| + 1 \leq k' \leq j'$, we make a preliminary simplification of the integral kernel $K_{\lambda'k'}B_{j^*k'}A_{j}$ that will be useful in the proof of both (a) and (b). Going back to the oscillatory representation (5.7) with $\Phi$ as in (5.8), we perform stationary phase in this oscillatory integral. This step is justified by Lemma 2.6 with $w = (\theta_2', z_2)$, $a = (z_1, x, y, \theta, \theta_1')$ and $\lambda \varphi = \Phi$ in the notation of that lemma, so that $(\lambda^{-1} R)(\tilde{b}_{j'k'}a_{j'}) = (d_{\theta_2'}z_2)(\tilde{b}_{j'k'}a_{j'}) = O(2^{-3'}) \ll 1$. We are thus led to the estimate

$$
(5.12) \quad |K_{\lambda'k'}B_{j^*k'}A_{j}(x, y)| \sim \left| \int e^{i\tilde{\Phi}(x, y; z_1; \theta, \theta_1')} T_{j'k'}(\tilde{z}, x; \theta_2; \theta_1') a_{j}(\tilde{z}, \theta; \theta_2; \theta_1') d\theta_2 d\theta_1',ight|
$$

where $\tilde{z} = (x_1, x_2 + (z_1 - x_1)^3)$ and

$$
(5.13) \quad \tilde{\Phi} = (z_1 - y_1) \theta_1 - (z_1 - x_1)\theta_1' + (x_2 - y_2 + (z_1 - x_1)^3 - (z_1 - y_1)^3) \theta_2.
$$

Several integration by parts will now be performed on the integral in (5.12). In the subsequent computation, $N \geq 1$ will denote an arbitrarily large integer and $u_{j,j'k'}(x, y, z_1; \theta_2, \theta_1, \theta_1')$ any function satisfying similar size and differentiability estimates as $\tilde{b}_{j'k'}(\tilde{z}, x; \theta_2, \theta_1') \cdot a_{j}(\tilde{z}, \theta; \theta_2, \theta_1')$, possibly with different implicit constants. The value of $N$ or the exact functional form of $u_{j,j'k'}$ may vary from one occurrence to the next.

For part (a), we set $j = j'$, $k = k'$, integrate by parts $2N$ times in (5.12) with respect to each of the variables $\theta_2, \theta_1, \theta_1'$, finally obtaining

$$
|K_{\lambda'k'}B_{j^*k'}A_{j}(x, y)| \leq C_N \int \left[ 1 + (2^k(z_1 - y_1))^2 \right]^{-N} \left[ 1 + (2^k(z_1 - x_1))^2 \right]^{-N} \times \left[ 1 + (2^l(x_2 - y_2 + (z_1 - x_1)^3 - (z_1 - y_1)^3))^2 \right]^{-N} u_{j,jk} d\theta_1 d\theta_2.
$$

Fixing $x$ in the above expression, and integrating out the variables $y_2, y_1, z_1, \theta_1', \theta_2$ in that order yields the estimate

$$
(5.14) \quad \sup_x \int |K_{\lambda'k'}B_{j^*k'}A_{j}(x, y)| dy \leq C 2^{(p + p' + 1)j + (l + l' - 1)k}.
$$

The same estimate is obtained if the roles of $x$ and $y$ are interchanged in (5.14).

Schur’s lemma then gives the following estimate for the operator norm:

$$
\|B_{j^*k'}A_{j}\|_{L^2 \to L^2} \leq \sup_x \int |K_{\lambda'k'}B_{j^*k'}A_{j}(x, y)| dy \left[ \sup_y \int |K_{\lambda'k'}B_{j^*k'}A_{j}(x, y)| dx \right]^{\frac{1}{2}} \leq C 2^{(l + l' - 1)k + (p + p' + 1)j}.
$$

Substituting $B = A$, $p = p'$, $l = l'$ yields the conclusion of part (a) of the lemma.

We now turn to part (b), where we deal with the “off-diagonal terms” $B_{j^*k'}A_{j}$ with $|j - j| \leq 3$ and $|k - k'| \geq 3$. Without loss of generality, we may assume that $k \geq k' + 3$. Observing that

$$
(x_1 - y_1) e^{i\tilde{\Phi}} = [(z_1 - y_1) + (x_1 - y_1)] e^{i\tilde{\Phi}} = (d_{\theta_1} + d_{\theta_1'}) e^{i\tilde{\Phi}},
$$

an integration by parts in (5.12) in the $\theta_1, \theta_1'$ variables gives

$$
(1 + (2^k(x_1 - y_1))^2)^N |K_{\lambda'k'}B_{j^*k'}A_{j}(x, y)| \leq C_N \times
$$

The remaining computations follow exactly as in the proof of part (a), after some cancellation and a minor adjustment of the constants to accommodate the change of variables.
| \int e^{i\tilde{\Phi}(x,y,z;\theta,\theta')} u_{ij'k'k'}(x,y,z;\theta,\theta') \, dz_1 \, d\theta_1 \, d\theta |. |

On the other hand,
\[
d_{z_1} \tilde{\Phi} = \theta_1 - \theta_1' + 3\theta_2((z_1 - x_1)^2 - (z_1 - y_1)^2)
\]
\[
= \theta_1 - \theta_1' + 3\theta_2(d_{\theta_1}^2 - d_{\theta_1'}^2) \tilde{\Phi},
\]
from which we obtain

\[
L(e^{i\tilde{\Phi}}) = (\theta_1 - \theta_1')e^{i\tilde{\Phi}}, \text{ where } L := \frac{1}{2}d_{z_1} - 3\theta_2 d_{\theta_1}^2 + 3\theta_2 d_{\theta_1'}^2.
\]
We observe that \(|\theta_1 - \theta_1'| \geq \frac{1}{4}2^k|\), and that the loss from applying \(L^t\) to the amplitude \((\theta_1 - \theta_1')^{-1}u_{ij'k'k'}\) is \(\leq C(1 + 2j - 2k + 2^j - 2k') \leq C \max(1, 2j - 2k')\). More precisely, for any \(m \geq 1\),

\[
\min \left(1, 2^{2k-j}\right) L^t \left[ \frac{u_{ij'k'k}}{(\theta_1 - \theta_1')^m} \right] = \frac{u_{ij'k'k}}{(\theta_1 - \theta_1')^m}.
\]

Thus an integration by parts argument using the differential operator \((1 + L^2)\) yields

\[
(5.16) \quad \left[ 1 + \left(2^{k}(x_1 - y_1)\right)^2 \right]^{N} |K_{B^*_r \wedge A_{jk}}(x,y)| \leq C_N \times \\
\left| \int e^{i\tilde{\Phi}} \left[ 1 + \left(\min(1, 2^{k'-j})(\theta_1 - \theta_1')\right)^2 \right]^{-N} u_{ij'k'k}(x,y,z_1;\theta_2,\theta_1,\theta_1') \, dz_1 \, d\theta_1 \, d\theta \right|.
\]

We observe that the argument so far does not require any special choice of \(\delta\).

We now consider two cases. First suppose that \(k' > \frac{j}{4}\), so that \(\min(1, 2^{k'-j}) = 1\). Since \(|\theta_1 - \theta_1'| \geq \frac{1}{4}2^k \geq \frac{1}{4}2^{j}\) on the support of \(u_{ij'k'k'}\), the estimate in (5.16) implies

\[
\int |K_{B^*_r \wedge A_{jk}}(x,y)| \, dy + \int |K_{B^*_r \wedge A_{jk}}(x,y)| \, dx \leq C_N 2^{3j - \delta_j N} \leq C_N 2^{-j N}
\]

for arbitrarily large \(N\). Recalling that \(|k - k'| \leq j\), the inequality above combined with Schur’s lemma yields a stronger estimate than the one claimed in (5.11).

Next we assume that \(2k' \leq j\). Here we will integrate by parts twice more in the integral in (5.16), using the differential operators \(L_r = 1 + \left(\frac{1}{2}d_{\theta_r}\right)^2\), \(r = 1, 2\), and keeping in mind that

\[
d_{\theta_1}(e^{i\tilde{\Phi}}) = i(z_1 - y_1)e^{i\tilde{\Phi}}, \quad d_{\theta_2}(e^{i\tilde{\Phi}}) = i(x_2 - y_2 + (z_1 - x_1)^3 - (z_1 - y_1)^3)e^{i\tilde{\Phi}}.
\]

We observe that

\[
d_{\theta_2}(u_{ij'k'k}) = 2^{-j} u_{ij'k'k}, \quad \text{while}
\]

\[
d_{\theta_1} \left[ \frac{u_{ij'k'k}}{\left(1 + \left(2^{k'-j}(\theta_1 - \theta_1')\right)^2\right)^N} \right] = \frac{2^{k'-j} - 2^{-k}}{\left(1 + \left(2^{k'-j}(\theta_1 - \theta_1')\right)^2\right)^N} u_{ij'k'k'}
\]

\[
\leq 2^{k'-j} \left(1 + \left(2^{k'-j}(\theta_1 - \theta_1')\right)^2\right)^N
\]

where the last inequality follows from the assumptions \(k \geq k' \geq \frac{1}{3}\) (since \(\delta \geq \frac{1}{3}\)) and \(|j - j'| \leq 3\). Combining all the arguments above we finally arrive at the estimate

\[
[1 + \left(2^{k'}(x_1 - y_1)\right)^2]^{N} |K_{B^*_r \wedge A_{jk}}(x,y)| \leq C_N 2^{(l - \frac{1}{2})k + (l' - \frac{1}{2})k' + (p + p' + 1)j} \times \\
\int \left[ 1 + \left(2^{k'-j}(\theta_1 - \theta_1')\right)^2 \right]^{-N} \left[ 1 + \left(2^{j-2k'}|z_1 - y_1|\right)^2 \right]^{-N}
\]
Choosing $N$ large enough and observing that $|\theta_1 - \theta'_1| \geq \frac{1}{2} 2^k$, we obtain
\[
\int |K_{\mathcal{B}'_{jk}, A_{jk}}(x, y)|\, dx 
\leq C 2^{(l-\frac{1}{2})k+(l'-\frac{1}{2})k'_1+(p+p'+1)} 2^{-N(2k'+k-j)} \\
\times \int_{\theta_2} \int_{\theta'_2} \int_{\theta_1} \left[ 1 + (2^{2k'-j}(\theta_1 - \theta'_1))^2 \right]^{-\frac{N}{2}} \\
\int_{x_2} \left[ 1 + (2^{j-2k'}|x_2 - y_2 + (z_1 - x_1)^3 - (z_1 - y_1)^3|^2)^{-N} \right] \\
\int_{x_1} \left[ 1 + (2^{k'(x_1 - y_1))^2)^{-N} \right] \\
\int \chi(x_1, y_1) \chi_2(x_2, y_2) \chi_3(x_3, y_3) \chi_4(x_4, y_4) \chi_5(x_5, y_5) \chi_6(x_6, y_6) \chi_7(x_7, y_7) \chi_8(x_8, y_8) \\
\leq C 2^{(l-\frac{1}{2})k+(l'-\frac{1}{2})k'_1+(p+p'+1)} 2^{-N(2k'+k-j)},
\]
where the last step follows from the fact that the $(x_2, x_1, z_1, \theta_1, \theta'_1, \theta_2)$ integrals when computed in that order yield $2^{-j}, 2^{-k'}, 2^{2k'-j}, 2^{j-2k'}, 2^{k'}$ and $2^j$ respectively. By symmetry, the same estimate also holds for the integral with respect to $dy$ of $|K_{\mathcal{B}'_{jk}, A_{jk}}(x, y)|$, with $x$ fixed. In view of the last line in (5.17) and the assumption that $\delta \geq \frac{1}{2}, \quad (5.11)$ then follows from Schur’s lemma and the inequality
\[
2k' + k - j = 3k' - j + (k - k') \geq (3k' - j') + (j - j') + (k - k') \\
\geq 0 - 2 + (k - k')
\]
since $k > k' \geq \delta j' \geq j'/3$ and $|j - j'| \leq 2$, completing the proof of part (b). \hfill \square

Corollary 5.4. Let $A \in \mathcal{B}^{p,l}(\Delta, C_0)$. Then for $j \geq 1$ and $\delta \geq \frac{1}{2}$, the operator $A_j$ satisfies the property
\[
\|A_j\|_{L^2 \to L^2} \leq \begin{cases} 
2^{(p+l)j} & \text{if } l \geq \frac{1}{2}, \\
2^{p+\delta(l-\frac{1}{2})} & \text{if } l < \frac{1}{2}.
\end{cases}
\]
Further, if $p + l \leq 0$ for $l \geq \frac{1}{2}$, or if $p + \frac{1}{2} + \delta(l - \frac{1}{2}) \leq 0$ for $l < \frac{1}{2}$, then $\sum_j A_j = A - A_0 - A_\infty$ is a bounded linear map on $L^2$.

Proof. The proof of (5.18) is a direct consequence of (5.11) in Lemma 5.3 with $p = p'$ and Cotlar-Knapp-Stein almost orthogonality lemma [11]. The second statement uses (5.18), Lemma 5.2, and almost orthogonality again. The details are left to the reader. \hfill \square

6. Normal Operators for Seismic Imaging

We now describe the decomposition of an operator $A \in \mathcal{B}^{p,l}(\Delta, C_2)$, where $(\Delta, C_2)$ is as in §1.3 and §2.3.2. As in §5, let us fix $\delta \in [\frac{1}{2}, \frac{1}{2})$, and a dyadic partition of unity $\{\chi_j : j \geq 0\}$ on $\mathbb{R}$ satisfying (5.1). Setting
\[
\chi_{jk}(\xi, \rho; \sigma) = \chi_k(\sigma) \chi_j(\langle \xi, \rho \rangle), \quad \chi_{\infty} = 1 - \sum_{j \geq 0} \sum_{k=0}^j \chi_{jk}, \quad \text{where } \langle \xi, \rho \rangle = (1 + |\xi|^2 + |\rho|^2)^{\frac{1}{2}},
\]
we arrive at a partition of unity on \( \left( \mathbb{R}_{\xi,\rho}^{n+1} \setminus \{0\} \right) \times \mathbb{R}_s \), namely

\[
1 \equiv \sum_{j=0}^{\infty} \sum_{k=0}^{j} \chi_{jk} + \chi_{\infty} = \sum_{j=0}^{\infty} \left[ \sum_{k=0}^{j} + \sum_{k=[j]+1}^{\infty} \right] \chi_{jk} + \chi_{\infty}.
\]

Here \( \chi_{\infty} \in \mathcal{S}_{0,0}^0 \) is supported on \( \{ \langle \xi, \rho \rangle \leq 2|\sigma| \} \), while \( \{ \chi_{jk} : j \geq 0, 0 \leq k \leq j \} \) is a bounded family (with respect to the seminorms) in \( \mathcal{S}_{0,0}^{0,0} \), with \n
\[
\supp(\chi_{jk}) \subseteq \{ 2^{j-1} \leq (\xi, \rho) \leq 2^{j+1}, 2^{k-1} \leq |\sigma| \leq 2^{k+1} \},
\]

so that

\[
\supp\left( \sum_{j=0}^{\infty} \sum_{k=0}^{[j]+1} \chi_{jk} \right) \subseteq \{ |\sigma| \leq C\langle \xi, \rho \rangle^\delta \}, \quad \text{and}
\]

\[
\supp\left( \sum_{j=0}^{\infty} \sum_{k=[j]+1}^{\infty} \chi_{jk} \right) \subseteq \{ C\langle \xi, \rho \rangle^\delta \leq |\sigma| \leq C\langle \xi, \rho \rangle \}.
\]

Letting \( a_{jk}(x, y; \xi, \rho; \sigma) = \chi_{jk}(\xi, \rho; \sigma) a(x, y; \xi, \rho; \sigma) \) and \( a_\infty = \chi_{\infty} a \) gives rise to a decomposition of the amplitude \( a \), which in turn induces a decomposition of the operator \( A \). More precisely,

\[
A = A_0 + \sum_{j=0}^{\infty} \sum_{k=[j]+1}^{\infty} A_{jk} + A_\infty,
\]

where \( A_{jk}, A_0 \) and \( A_\infty \) are operators whose Schwartz kernels and multphase functions are of the form given in §2.3.2 (see (2.12) and (2.13)), but whose amplitudes are given by \( a_{jk}, \sum_{j=0}^{\infty} \sum_{k=0}^{j} a_{jk} \) and \( a_\infty \) respectively. Then \( A_\infty \in \Psi^{p+l} \) and so maps \( H^r \) boundedly into \( H^{r+t} \) for \( t \geq p + l \). It turns out that the components \( A_0 \) and \( A_{jk} \) in this situation satisfy \( L^2 \) estimates and almost orthogonality properties analogous to their \( I^{p+l}(\Delta, C_0) \) counterparts with similar but more involved proofs. We record these facts below with the appropriate modifications.

**Lemma 6.1 (Bounds for \( A_0 \)).** For any \( 0 < \delta < \frac{1}{2} \), the operator \( A_0 \in \mathcal{I}^{m-\delta, \delta}_{\text{comp}}(\mathbb{R}^n) \), and hence maps \( H^r_{\text{comp}}(\mathbb{R}^n) \) boundedly into \( H^{r+t}_{\text{loc}}(\mathbb{R}^n) \), where \( m \) and \( r_0 \) are in Lemma 5.1.

**Proof.** The argument is identical to the one presented in Lemma 5.1 and involves integrating out \( \sigma \) in the oscillatory representation of \( K_{A_0} \). The details are left to the reader. \( \square \)

**Lemma 6.2.** Let \( A \in \mathcal{I}^{p,l}(\Delta, C_2) \), \( B \in \mathcal{I}^{p',l'}(\Delta, C_2) \), with decompositions \( \{ A_{jk} \} \) and \( \{ B_{jk} \} \) as above. Then the conclusions [5.5] and [5.6] of Lemma 5.2 hold for the same set of indices \( j, j', k, k' \) therein.

**Proof.** The kernel of \( B_{jk}^{j',k'} A_{jk} \) is

\[
K_{B_{j',k'} A_{jk}}(x, y) = e^{i\Phi(x, y; z; \xi, \rho, \sigma, \xi', \rho', \sigma')} \times b_{j',k'}(z, x; \tilde{\xi}, \tilde{\rho}; \sigma) a_{jk}(z, y; \xi, \rho; \sigma) dz d\xi d\rho d\sigma d\tilde{\xi} d\tilde{\rho} d\sigma',
\]

where, from (2.12),

\[
\Phi = (z - y) \cdot \xi - (z - x) \cdot \tilde{\xi} + \frac{\partial \Phi}{\partial \xi_1} - \frac{\partial \Phi}{\partial \xi_1} + (z_n - y_n) \sigma - (z_n - x_n) \tilde{\sigma}.
\]
and \( \xi = (\xi_1, \ldots, \xi_{n-1}) \). In view of (2.9) and (6.1), the amplitude satisfies the support condition
\[
\text{supp}(\tilde{b}_{j'k'}a_{jk}) \subseteq \left\{ \begin{array}{l}
|\xi, \rho| \leq 2|\xi_1|, \quad 2^j - 1 \leq |\xi, \tilde{\rho}| \leq 2^j + 1, \quad 2^{k'} - 1 \leq |\tilde{\sigma}| \leq 2^{k'+1} \\
|\xi, \rho| \leq 2|\xi_1|, \quad 2^j - 1 \leq |\xi, \rho| \leq 2^j + 1, \quad 2^{k'} - 1 \leq |\sigma| \leq 2^{k'+1}
\end{array} \right\},
\]
and the differentiability estimates
\[
|\partial_{\xi,\rho}^a \partial_{\tilde{\rho}}^b \partial_{\sigma}^c \partial_{x,y,z}^d (\tilde{b}_{j'k'}a_{jk})| \leq C_{\alpha,\tilde{\alpha},\beta,\tilde{\beta},\gamma} 2^{(p - \frac{1}{2})j + (p' - \frac{1}{2})j' + (l - \frac{1}{2})k + (l' - \frac{1}{2})k'} \\
\times 2^{-|a|j - |b|j' - |\beta - \tilde{\beta}|k'}
\]
with \( C_{\alpha,\tilde{\alpha},\beta,\tilde{\beta},\gamma} \) independent of \( j \) and \( k \).

Simply integrating the zeroth order bounds in (6.3) yields the basic estimate
\[
|K_{B_{j'k'}^*A_{jk}}(x,y)| \leq C_2 2^{(p - \frac{1}{2})j + (p' - \frac{1}{2})j' + (l - \frac{1}{2})k + (l' - \frac{1}{2})k'} 2^{(n+1)(j+j')+2(k+k')}
\leq C_2 2^{(p+n+\frac{1}{2})(j+j')+(l+\frac{1}{2})(k+k')}.
\]

Now, if \( j' \leq j - 3 \), then \( |\xi_1 - \tilde{\xi}_1| \geq c|\xi_1| \geq c2^j \) on \( \text{supp}(\tilde{b}_{j'k'}a_{jk}) \). Noting that \( d_z \Phi = \tilde{\xi}_1 - \xi_1 \), we can integrate by parts \( N \) times in \( z_1 \) and then estimate as in (6.4) to obtain
\[
|K_{B_{j'k'}^*A_{jk}}(x,y)| \leq C_2 2^{-Nj} 2^{(p+n+\frac{1}{2})(j+j')+(l+\frac{1}{2})(k+k')} \\
\leq C_2 2^{-(N-M)j}
\]
for some fixed \( M = M(p,l,n) \geq 0 \), since \( k' \leq j' < j \) and \( k \leq j \). By choosing \( N \) sufficiently large compared to \( M \), integrating the kernel in \( x \) and taking the supremum in \( y \), or vice versa, we get the same upper bound, which establishes the desired \( L^2 \) norm by Schur’s lemma. The case of \( j' \geq j + 3 \) is identical. \( \square \)

**Lemma 6.3 (Almost orthogonality in \( k \)).** Let \( A, B, \{ A_{jk} \} \) and \( \{ B_{jk} \} \) be as in Lemma 6.2. If the indices \( j, j', k, k' \) satisfy the same hypotheses as in Lemma 5.3, then the conclusions 5.10 and 5.11 hold.

**Proof.** The proof of (5.10) and (5.11) in this setting requires an initial preparation of the Schwartz kernel of \( B_{j'k'}^*A_{jk} \); we simplify (6.2) using four applications of stationary phase. The first three applications are with respect to the pairs \( (\rho, \xi_1), (\tilde{\rho}, \xi_0) \) and \( (z', \xi') \). Of these the first method of stationary phase may be justified using Lemma 2.6 by setting \( w = (\rho, \xi_0) \), so that in the notation of that lemma
\[
Q = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, \quad \lambda^{-1} R = -2\xi_1 \frac{\partial^2}{\partial \xi_1 \partial \tilde{\rho}}, \quad \text{and} \quad (\lambda^{-1} R)^* (\tilde{b}_{j'k'}a_{jk}) = O(2^{-j'})
\]
giving rise to a valid asymptotic expansion whose first term involves a factor \( \det(Q)^{-\frac{1}{2}} = |\xi_1| \sim 2^j \). The other stationary phases are handled similarly, their justification being left to the reader. By the same argument as before, the second stationary phase contributes a factor of \( 2^{j'} \) (from the determinant of the Hessian)
to the leading order term of the asymptotic expansion, while the corresponding contribution from the third is only a constant. The end result is

\begin{equation}
K_{B'_{j'k'}}A_{jk}(x, y) \sim \int e^{i\Phi_3}c_3 d\zeta d\sigma d\tilde{\sigma},
\end{equation}

where \(\Phi_3\) and \(c_3\) are both functions of \((x, y; z, \xi, \sigma, \tilde{\sigma})\), with

\[\Phi_3 = (x' - y') \cdot \xi' + (z_n - y_n)\sigma - (z_n - x_n)\tilde{\sigma}\]

\[-\frac{1}{4}((z_n - x_n)(z_n + x_n)^2 - (z_n - y_n)(z_n + y_n)^2)\xi_1\]

\[+ (z_n - y_n)P(z_n, y, \xi') - (z_n - x_n)P(z_n, x, \xi'),\]

and

\[c_3 = \xi_1^2 \cdot \tilde{\Phi}_{j'k'}(x', z_n, x; \xi', \frac{1}{4}(z_n + x_n)^2 \xi_1 + P(z_n, x, \xi'); (x_n - z_n)\xi_1, \tilde{\sigma})\]

\[\times a_{jk}(x', z_n, y; \xi', \frac{1}{4}(z_n + y_n)^2 \xi_1 + P(z_n, y, \xi'); (y_n - z_n)\xi_1, \sigma)\]

The amplitude \(c_3\) satisfies the same size and differentiability estimates as \(2^{l+j'}\tilde{\Phi}_{j'k'}a_{jk}\) with the eliminated variables absent (see (6.3)).

To estimate the norm of each \(A_{jk}\), we set \(B = A, j = j', k = k', p = p', l = l'\) and apply one final method of stationary phase in \((z_n, \tilde{\sigma})\) (once again justified by the existence of the large parameter \(|\tilde{\sigma}| \geq 2^{k-1} \gg 1\), obtaining

\begin{equation}
K_{A^*_{j'k'}A_{jk}}(x, y) \sim \int e^{i\Phi_4}c_4 d\xi d\sigma.
\end{equation}

Here \(\Phi_4\) and \(c_4\) are functions of \((x, y; \xi, \sigma)\), with

\[\Phi_4 = (x' - y') \cdot \xi' + (x_n - y_n)\sigma + \frac{1}{4}(x_n - y_n)(x_n + y_n)^2 \xi_1\]

\[+ (x_n - y_n)P(x_n, y, \xi'),\]

and \(c_4\) satisfying the same estimates as \(c_3\), i.e.,

\begin{equation}
|\partial_\zeta^\alpha \partial_\zeta'^\beta \partial_\sigma^\gamma c_4| \leq C_{\alpha\beta\gamma}2^{(2p+1)j+(2l-1)k-|\alpha|j-|\beta|k}.
\end{equation}

Simple integration in \(\xi', \sigma\) in the range \(|\xi'| \leq 2^{l+1}, |\sigma| \leq 2^{k+1}\) yields the basic estimate

\[K_{A^*_{j'k'}A_{jk}}(x, y) \leq C2^{(2p+n)j+2l},\]

but one may substantially improve upon this by integrating by parts, using the differential operators

\[d_{\xi'} \Phi_4 = x_1 + y_1 + \frac{1}{4}(x_n - y_n)(x_n + y_n)^2 + (x_n - y_n)\xi_1(x_n, y, \xi'),\]

\[d_{\xi'} \Phi_4 = x_1 - y_1 + (x_n - y_n)\xi_1(x_n, y, \xi'),\]

\[d_\sigma \Phi_4 = x_n - y_n,\]

where \(x'' = (x_2, \ldots, x_{n-1})\). Since \(\partial_\zeta^\beta P(x_n, y, \xi')\) is homogeneous of degree \(1 - |\beta|\) in \(\xi'\), and \(|\xi'| \geq 2^{i-1}\), we find that

\begin{equation}
\frac{\partial}{\partial \xi_i} \left[ \frac{\partial_\zeta^i \Phi_4}{(d_{\xi'} \Phi_4)^m} \right] = 2^{-j} \frac{\partial_\zeta^i \Phi_4}{(d_{\xi'} \Phi_4)^m}, \quad 1 \leq i \leq n - 1, m \geq 1,
\end{equation}

while

\[\frac{\partial}{\partial \sigma} (\partial_\zeta^k \Phi_4) = 2^{-k} \partial_\zeta^k \Phi_4,\]
where \( \tilde{c}_3 \) denotes a function satisfying the same estimates (6.8) as \( c_4 \), possibly with different implicit constants, and whose exact functional form may vary from one occurrence to the next. Integrating by parts \( N \) times with respect to each of the variables \( (\xi_1, \ldots, \xi_{n-1}, \sigma) \) in (6.6), and combining (6.9) and (6.10) yields

\[
\left| K_{A_j^* A_{jk}} (x, y) \right| \leq C_N \int \frac{2^{(2p+1)j+(2l-1)k}}{(1 + 2 |d_{c \cdot \Phi_4}|)^N (1 + 2^k |d_{\sigma \Phi_4}|)^N} d\xi' d\sigma,
\]

from which one obtains

\[
\int |K_{A_j^* A_{jk}} (x, y)| dx \leq C_N 2^{(2p+1)j+(2l-1)k} \int \int \frac{d\xi' d\sigma dx}{(1 + 2 |d_{c \cdot \Phi_4}|)^N (1 + 2^k |d_{\sigma \Phi_4}|)^N} \leq \frac{C_N 2^{(2p+1)j+(2l-1)k + (2l-1)h - (n-1)j - k}}{\int |\xi'|^2N \int |\sigma|^2N} \leq \frac{C_N 2^{(2p+1)j+(2l-1)k}}{C_N 2^{(2p+1)j+(2l-1)k}}.
\]

In the second step above and in view of (6.9), one has to integrate first in \( x' \) and then in \( x_n \), while the last step uses the size of the \( (\xi', \sigma) \)-support of \( A_{jk} \). The same estimate holds for \( \int |K_{A_j^* A_{jk}} (x, y)| dy \), completing the proof of (5.10) for \( I^{p,1}(\Delta, C_2) \).

In order to prove the analogue of (5.11), it suffices to show that for any \( N \geq 1 \), \( |j - j'| \leq 2 \), \( |k - k'| \geq 3 \),

\[
(6.11) \quad \sup_{x} \int \left| K_{B_{j'}^{\sigma}, A_{jk}} (x, y) \right| dy + \sup_{y} \int \left| K_{B_{j'}^{\sigma}, A_{jk}} (x, y) \right| dx \leq C_N 2^{(p+p'+1)j+(l-\frac{1}{2}k+(l' - \frac{1}{2}k')2^k - k - k')N}.
\]

For this we return to the representation (6.5). As in the proof of Lemma 5.3, we will subject the integral in (6.5) to a large of number of integration by parts using several differential operators. However due to the complicated structure of the multiphase function (6.6) (compared to (5.13)), the differential operators and hence the resulting integrations by parts are more involved. We now proceed to describe each of these steps systematically. Throughout this discussion, as in the proof of Lemma 5.3, we will assume that \( k \geq k' + 3 \), and denote by \( u_{j'kk'} \) any function (with possibly different functional forms) satisfying the same size and differentiability estimates as \( c_3 \). The value of the large constant \( N \) may also vary from one occurrence to the next.

**Step 1.** Since

\[
d_{\sigma} \Phi_3 = z_n - y_n, \quad d_{\bar{\sigma}} \Phi_3 = x_n - z_n, \quad (d_{\sigma} + d_{\bar{\sigma}}) \Phi_3 = x_n - y_n,
\]

with

\[
d_{\sigma}(u_{j'kk'}) = 2^{-k} u_{j'kk'}, \quad \text{and} \quad d_{\bar{\sigma}}(u_{j'kk'}) = 2^{-k'} u_{j'kk'},
\]

integrating by parts in (6.5) a large number of times using \( 1 + \frac{1}{4}(d_{\sigma} + d_{\bar{\sigma}}) \) and \( 1 + \frac{1}{4}(d_{\sigma} + d_{\bar{\sigma}}) \) gives

\[
\left[ 1 + (2^{k'}(x_n - y_n))^2 \right]^N \int K_{B_{j'}^{\sigma}, A_{jk}} (x, y) \sim \int e^{i\Phi_3} \frac{u_{j'kk'}(x, y, z_n; \sigma, \bar{\sigma})}{1 + (2^{k'}(x_n - y_n))^2} d\xi' d\sigma d\bar{\sigma}.
\]
The above expression permits a localization in the spatial variables $x_n, y_n, z_n$, which will be useful in the sequel. Fixing $\chi \in C_0^\infty([-2,2])$, with $\chi \equiv 1$ on $[-1,1]$, and introducing the partition of unity

$$1 \equiv \chi(2^{k'-k'}(x_n - y_n)) + (1 - \chi)(2^{k'-k'}(x_n - y_n))$$

$$\equiv \chi(2^{k'-k'}(x_n - y_n)) \left[ \chi(2^{k'-k'}(x_n - z_n)) + (1 - \chi)(2^{k'-k'}(x_n - z_n)) \right]$$

$$+ (1 - \chi)(2^{k'-k'}(x_n - y_n)),$$

we obtain the decomposition

$$K_{B_{y'k'}} A_{jk} = K_1 + K_2 + K_3,$$

where each $K_i$ is an oscillatory integral with multi-phase $\Phi_i$, and amplitude of the form $(1 + (2^k(x_n - z_n))^2)^{-N}(1 + (2^k(x_n - y_n))^2)^{-N}\Theta_i$, where

$$\Theta_1 = \chi(2^{k'-k'}(x_n - y_n))\chi(2^{k'-k'}(x_n - z_n))u_{jj'kk'},$$

$$\Theta_2 = \chi(2^{k'-k'}(x_n - y_n))(1 - \chi)(2^{k'-k'}(x_n - z_n))u_{jj'kk'},$$

$$\Theta_3 = (1 - \chi)(2^{k'-k'}(x_n - y_n))u_{jj'kk'}.$$

It follows from (6.13) that for any $\epsilon > 0$

$$|K_i(x, y)| \leq C_N 2^{-jN} \quad \text{for } i = 2, 3 \text{ and all } N \geq 1,$$

which is a stronger statement than the one required in (6.11). We therefore restrict attention only to $K_1$ in the sequel, in which $x_n, y_n$ and $z_n$ are further restricted to satisfy

$$(6.14) \quad |x_n - z_n| \leq 2^{1-k'+k'}, \quad |x_n - y_n| \leq 2^{1-k'+k'}, \quad \text{hence } |z_n - y_n| \leq C2^{1-k'+k'}.$$

**Step 2.** Our next integration by parts (in $K_1$) will involve $z_n, \sigma, \tilde{\sigma}$ and will exploit the disparity in the sizes of $\sigma$ and $\tilde{\sigma}$. For this, we note that

$$d_{z_n} \Phi_3 = \sigma - \tilde{\sigma} + \frac{\xi_1}{4} \left[ 2(x_n - z_n)(x_n - y_n) - (x_n - y_n)^2 \right] + P(z_n, y, \xi') - P(z_n, x, \xi')$$

$$+ (z_n - y_n) P_{z_n, n, y, \xi'} - (z_n - x_n) P_{z_n, x, \xi'}$$

$$= \sigma - \tilde{\sigma} + \frac{\xi_1}{4} \left[ 2(x_n - z_n)(x_n - y_n) - (x_n - y_n)^2 \right]$$

$$+ \frac{3}{2}(z_n - y_n)^2 P_{z_n, n, y, \xi'} - \frac{3}{2}(z_n - x_n)^2 P_{z_n, x, \xi'}$$

$$+ (z_n - y_n)^3 Q(z_n, y, \xi') - (z_n - x_n)^3 Q(z_n, x, \xi'),$$

where the last step follows by expanding $P(z_n, y, \xi')$ and $P_{z_n, n, y, \xi'}$ (resp. $P(z_n, x, \xi')$ and $P_{z_n, x, \xi'}$) in a Taylor series in the $z_n$ variable about $z_n = y_n$ (resp. $z_n = x_n$) using (2.10). Here $Q$ is a smooth function that is homogeneous of degree one in $\xi'$. In view of (6.12), we find that

$$L(\Phi_3) = \sigma - \tilde{\sigma} + (z_n - y_n)^3 Q(z_n, y, \xi') - (z_n - x_n)^3 Q(z_n, x, \xi'),$$

where

$$L = d_{z_n} - \frac{\xi_1}{4} \left[ 2d_\sigma (d_\sigma + d_{\tilde{\sigma}}) - (d_\sigma + d_{\tilde{\sigma}})^2 \right]$$

$$- \frac{3}{2} P_{z_n, n, y, \xi'} d_\sigma^2 + \frac{3}{2} P_{z_n, x, \xi'} d_{\tilde{\sigma}}^2$$

$$= L_1 + L_2, \quad \text{with } L_1 := d_{z_n}, \text{ and}$$
\[ L_2 = \mathcal{P}(y_n, y', \xi')d_x^2 - \mathcal{P}(x_n, x, \xi')d_x^2. \]

Here \( \mathcal{P}(x_n, x, \xi') \) is a smooth function in all its arguments and homogeneous of degree one in \( \xi' \). The support properties in (6.14) and the homogeneity of \( \mathcal{Q} \) imply that

\[
|L(\Phi_3)| \geq |\sigma| - |\tilde{\sigma}| - C2^j|z_n - y_n|^3 - C2^j|z_n - x_n|^3 \\
\geq 2^{k-1} - 2^{k'+1} - C2^{j-3k+3k'} - C2^{j-3k+3k'} \geq \epsilon 2^k,
\]

where the last inequality follows from \( k \geq k'+3 \) and \( k+3k'(1-\epsilon) - j \geq j'(1-\epsilon) - \frac{2k}{3} \geq j\left(\frac{1}{3} - \epsilon\right) - 2 \gg 1 \), choosing \( \epsilon < \frac{1}{3} \).

We will integrate by parts a large number of times in \( \mathcal{K}_1 \) using \( L \), which is justified in light of (6.15). In order to describe the action of the differential operator on the amplitude, let us denote by \( \tilde{\Theta}_1 \) any (generic) function satisfying the same size and differentiability estimates as \( \Theta_1 \), and observe that \( L_2 \) is independent of \( z_n \), so that for any \( m \geq 1 \),

\[
L_2^t \left[ \frac{\tilde{\Theta}_1}{L(\Phi_3)^m} \right] = 2 \sum_{r=0}^{2} \frac{1}{L(\Phi_3)^{m+r}} \left[ \mathcal{P}(y_n, y, \xi')d_x^{2-r} - \mathcal{P}(x_n, x, \xi')d_x^{2-r} \right] (\tilde{\Theta}_1) \\
= 2^j \sum_{r=0}^{2} \frac{2^{-k'(2-r)}\tilde{\Theta}_1}{(L(\Phi_3))^{m+r}}, \text{ since } k \geq k'+3 \text{ and } \mathcal{P}\tilde{\Theta}_1 = 2^j\tilde{\Theta}_1.
\]

On the other hand,

\[
L_1^t \left[ \frac{\tilde{\Theta}_1}{(L(\Phi_3)^m(1 + (2^k(x_n - z_n))^2)^N) \right] = \frac{d_{z_n}\tilde{\Theta}_1}{(L(\Phi_3)^m(1 + (2^k(x_n - z_n))^2)^N} \\
+ \frac{\tilde{\Theta}_1}{(L(\Phi_3)^m(1 + (2^k(x_n - z_n))^2)^N} \left[ \frac{(z_n - y_n)^2\tilde{Q}(z_n, y, \xi') - (z_n - x_n)^2\tilde{Q}(z_n, x, \xi')}{[1 + (2^k(x_n - z_n))^2]^N} \right] \\
+ \frac{\tilde{\Theta}_1}{(L(\Phi_3)^m(1 + (2^k(x_n - z_n))^2)^N+1} \left[ \frac{2^k(x_n - z_n)}{2^{k'-k'}\tilde{\Theta}_1} \right] \\
+ \frac{1}{(L(\Phi_3)^m(1 + (2^k(x_n - z_n))^2)^N} \left[ \frac{2^j(z_n - y_n)^2\tilde{\Theta}_1 - 2^j(z_n - x_n)^2\tilde{\Theta}_1}{[1 + (2^k(x_n - z_n))^2]^N} \right] \\
+ \frac{\tilde{\Theta}_1}{(L(\Phi_3)^m(1 + (2^k(x_n - z_n))^2)^N} \left[ \frac{2^k(x_n - z_n)}{2^{k'-k'}\tilde{\Theta}_1} \right]
\]

where \( \tilde{Q} \) shares the same smoothness and homogeneity properties as \( Q \), and hence \( \tilde{\Theta}_1 Q = 2^j\tilde{\Theta}_1 \). In view of (6.12) and the factors involving \( (z_n - y_n), (x_n - z_n) \) in the expression above, one can follow up an application of \( L_1^t \) by another integration by
parts using \( d_\sigma \) and \( d_\delta \), obtaining

\[
\int e^{i\Phi_3} L^1_1 \left[ \frac{\tilde{\Theta}_1}{(L(\Phi_3))^m (1 + (2k'(x_n - z_n))^2)^N} \right] dz_n \, d\xi \, d\sigma \, d\tilde{\sigma} \\
= \int \frac{e^{i\Phi_3}}{[1 + (2k'(x_n - z_n))^2]^N} \left[ \frac{2k' \tilde{\Theta}_1}{(L(\Phi_3))^m} + 2^j (d_\sigma^2 - d_\tilde{\sigma}^2) \left( \frac{\tilde{\Theta}_1}{(L(\Phi_3))^{m+1}} \right) \right] d\xi' d\sigma d\tilde{\sigma} \\
+ 2^{k'} d_\delta \left( \frac{\tilde{\Theta}_1}{(L(\Phi_3)^m)} \right) d\xi' d\sigma d\tilde{\sigma}
\]

(6.17)

Combining (6.16) and (6.17), we observe that a \( J \)-fold application of integration by parts in \( K_1 \) using \( L \) results in a finite sum of oscillatory integrals with multiphase \( \Phi_3 \), whose amplitudes are all of a similar form, namely

\[
\Xi_1 = \frac{2^{\beta_j(j,k',\mu)} \tilde{\Theta}_1}{(L(\Phi_3))^{\mu} [1 + (2k'(x_n - z_n))^2]^N [1 + (2k'(x_n - y_n))^2]^N},
\]

with \( \mu \geq J \). It is easy to check using the restrictions \( 3k' \leq j \) and \( k' \leq k \) that the exponents \( \beta_j(j,k',\mu) \) satisfy the inequality \( \beta_j(j,k',\mu) \leq (\mu - 1)k + k' \). An induction in \( J \), which we ask the reader to verify, then shows that in general

\[
\beta_j(j,k',\mu) \leq (\mu - J)k + k'J, \quad J \geq 1.
\]

We work with a general term in this sum, which by a slight abuse of notation we continue to denote by \( K_1 \):

\[
K_1(x, y) \sim \int e^{i\Phi_3} \Xi_1(x, y, z_n, \xi', \sigma, \tilde{\sigma}) \, dz_n \, d\xi' \, d\sigma \, d\tilde{\sigma},
\]

where \( \Xi_1 \) is as in (6.18).

**Step 3.** Our last integration by parts will be in the variables \( \xi', \sigma, \tilde{\sigma} \). Specifically, we note that

\[
d_\xi \Phi_3 = \left[ x' - y' + \frac{1}{4} \left( (z_n - y_n)(z_n + y_n)^2 - (z_n - x_n)(z_n + x_n)^2 \right) \right] \bar{c}_1
\]

\[
= (z_n - y_n)P_{\xi'}(z_n, y, \xi') - (z_n - x_n)P_{\xi'}(z_n, x, \xi')
\]

\[
= R(z_n, y, \xi') - (z_n - x_n)^3 R(z_n, x, \xi'),
\]

where the last step follows from Taylor expansion of \( P_{\xi'}(z_n, y, \xi') \) (resp. \( P_{\xi'}(z_n, x, \xi') \)) in the \( z_n \) variable about the point \( z_n = y_n \) (resp. \( z_n = x_n \)) using (2.10). Here \( R = (R_1, \ldots, R_{n-1}) \) is a smooth vector-valued function that is homogeneous of degree zero in \( \xi' \). In view of (6.12), this implies that the vector differential operator

\[
P = (P_1, \ldots, P_{n-1}) = d_{\xi'} - R(z_n, y, \xi') d_\sigma - R(z_n, x, \xi') d_{\tilde{\sigma}}
\]

satisfies

\[
P(\Phi_3) = x' - y' + \frac{1}{4} \left( (z_n - y_n)(z_n + y_n)^2 - (z_n - x_n)(z_n + x_n)^2 \right) \bar{c}_1.
\]
In order to describe the result of a large number of integration by parts in \( K_1 \) using \( P_i \), we observe that \( P_i(\Phi_3) \) is independent of \((\xi', \sigma, \tilde{\sigma})\), so (in view of (6.20) and (6.18)) one only needs to understand the effect of \( P_i \) on \( \tilde{\Theta}_i(L(\Phi_3))^{-\mu} \). For every \( 1 \leq i \leq n - 1 \),

\[
P_i \left[ \frac{\tilde{\Theta}_i}{(L(\Phi_3))^\mu} \right] = \frac{d\tilde{\Theta}_i}{(L(\Phi_3))^\mu}
\]

\[
+ \frac{\tilde{\Theta}_i}{(L(\Phi_3))^\mu+1} \left[ (z_n - y_n)^3 Q_{\xi}(z_n, y, \xi') - (z_n - x_n)^3 Q_{\xi}(z_n, x, \xi') \right]
\]

\[
- \left[ R(z_n, x, \xi')d_\sigma^3 + R(z_n, x, \xi')d_\tilde{\sigma}^3 \right] \left( \frac{\tilde{\Theta}_i}{(L(\Phi_3))^\mu} \right)
\]

As in step 2, we exploit (6.12) and use another integration by parts with respect to \( \sigma, \tilde{\sigma} \) to replace the factors involving \((z_n - y_n)\) and \((x_n - z_n)\) in the expression above, thus obtaining

\[
\int e^{i\phi_3} P_i \left[ \frac{\tilde{\Theta}_i}{(L(\Phi_3))^\mu} \right] d\xi' d\sigma d\tilde{\sigma} = \int d\xi' d\sigma d\tilde{\sigma} e^{i\phi_3} \left[ \frac{2^{-j} \tilde{\Theta}_i}{(L(\Phi_3))^\mu} \right]
\]

\[
+ \left[ Q_{\xi}(z_n, y, \xi')d_\sigma^3 + Q_{\xi}(z_n, x, \xi')d_\tilde{\sigma}^3 \right] \left( \frac{\tilde{\Theta}_i}{(L(\Phi_3))^\mu+1} \right)
\]

\[
- \left[ R(z_n, x, \xi')d_\sigma^3 + R(z_n, x, \xi')d_\tilde{\sigma}^3 \right] \left( \frac{\tilde{\Theta}_i}{(L(\Phi_3))^\mu} \right)
\]

\[
= \int e^{i\phi_3} \left[ \frac{2^{-j} \tilde{\Theta}_i}{(L(\Phi_3))^\mu} + \sum_{r=0}^{3} \frac{2^{-k(3-r)} \tilde{\Theta}_i}{(L(\Phi_3))^{\mu+1+r}} + \sum_{r=0}^{3} \frac{2^{-k(3-r)} \tilde{\Theta}_i}{(L(\Phi_3))^{\mu+r}} \right] d\xi' d\sigma d\tilde{\sigma},
\]

since \( Q_{\xi}, \tilde{\Theta}_i = \tilde{\Theta}_i \) and \( R_i, \tilde{\Theta}_i = \tilde{\Theta}_i \). Recalling (6.15) and observing that

\[
k'(3-r) + k(1+r) \geq k'(3-r) + kr \geq 3k' \geq j
\]

we conclude from (6.22) after an easy induction that an \( m \)-fold integration by parts using \( P_i \) yields

\[
\int e^{i\phi_3} \frac{\tilde{\Theta}_i}{L(\Phi_3)^m} d\xi' d\sigma d\tilde{\sigma} = \frac{1}{(P_i \Phi_3)^m} \sum_{r=0}^{2} 2^{\gamma_m(j,k', r)} \int e^{i\phi_3} \frac{\tilde{\Theta}_i}{L(\Phi_3)^{m+r}} d\xi' d\sigma d\tilde{\sigma},
\]

where

\[
(6.24) \quad \gamma_m(j, k', r) \leq -jm.
\]

This concludes the steps that involve various integration by parts.

**Step 4.** It remains to combine the results of the previous steps to prove (6.11). Combining (6.20) with (6.23), choosing \( m = M \gg 1 \) and continuing to call a generic term in the resulting sum by \( K_1 \), we find that

\[
K_1(x, y) \leq C_N \frac{2^{\delta_j(j,k', \mu)}}{\left[1 + (2^{k'}(x_n - y_n))^2\right]^{N}} \times \int \frac{e^{i\phi_3} \tilde{\Theta}_i d\xi' d\sigma d\tilde{\sigma}}{(L(\Phi_3))^{m+r} \left[1 + (2^{k'}(z_n - x_n))^2\right]^{N} \prod_{i=1}^{n-1} \left[1 + 2^{-\gamma_m(j,k',r)}(P_i \Phi_3)^M]}.
\]
To prove (6.11), we compute
\[
\sup_x \frac{1}{\|K\|_{\mathcal{L}^s}} \int |K(x, y)| \, dy \leq C 2^{p + p' + 1} \frac{1}{\|K\|_{\mathcal{L}^s}} \int |K(x, y)| \, dy
\]
where we have used the size estimate for $\tilde{\Theta}$, $r \geq 0$ and (6.15) at the first step; the expressions (6.21) and the support sizes of $\varphi_{j,k}, \psi_{j,k'}$ at the second step to integrate in the order specified; (6.24) at the third step; and (6.19) at the final step. Since the roles of $x$ and $y$ may be interchanged to get the same bound, the desired conclusion is established.

**Corollary 6.4.** For $\delta \geq \frac{1}{4}$, the statement of Cor. 5.4 holds for $A \in I^{p,l}(\Delta, C_2)$.

**Proof.** The proof is identical to that of Cor. 5.4.

### 7. Proof of Theorem 1.1

Now in a position to prove Thm. 1.1, we first treat the classes of operators $I^{p,l}(\Delta, C_j)$ for $j = 0, 2$. Since there are standard elliptic $\Psi$DOs that map any $L^2$-Sobolev space isomorphically onto any other, and

\[
\Psi^m \circ I^{p,l}(\Delta, C_j) \circ \Psi^{m'} \subseteq I^{p+m+m',l}(\Delta, C_j) \quad \text{for any } m, m' \in \mathbb{R},
\]

it suffices to assume that $s = r = 0$ in Thm. 1.1 and show that $A \in I^{p,l}(\Delta, C_j)$ is bounded from $L^2 \to L^2$. These assumptions will be used without further reference throughout this section as will the decompositions of the operator $A$ introduced in §5. The proof consists of combining the estimates for $A_0, A_\infty$ and $A - A_0 - A_\infty$. Of these $A_\infty \in \Psi^{\Psi^{p,l}}$, and hence is a bounded map from $H^s \to H^{s-r'}$, for all $s \in \mathbb{R}$ and $r' \geq r_\infty = p + l$. For $I^{p,l}(\Delta, C_0)$, the bounds for $A_0$ and $A - A_0 - A_\infty$ are given in Lemma 5.1 and Cor. 5.4 respectively; for $I^{p,l}(\Delta, C_2)$ they are in Lemma 6.1 and Cor. 6.4. It therefore suffices to show that

\[
r = \min_{\delta \in [\frac{1}{2}, \frac{3}{2}]} \max(r_0, r_1, r_\infty),
\]

where $r_0 = p + \frac{1}{6} + \delta(l + \frac{1}{2})\frac{1}{2}$, $r_\infty = p + l$ and

\[
r_1 = \begin{cases} p + \frac{1}{2} + (l - \frac{1}{2})\frac{1}{2} & \text{if } l \geq \frac{1}{2}, \\
p + \frac{1}{2} + \delta(l - \frac{1}{2})\frac{1}{2} & \text{if } l < \frac{1}{2}.
\end{cases}
\]

For $l > \frac{1}{2}$, one has $r_1 = r_\infty$, so $\max(r_0, r_1, r_\infty) = \max(p + \frac{1}{6} + \delta(l + \frac{1}{2}), p + l) \geq p + l$, with equality being attained if and only if $\delta = (l - \frac{1}{2})/(l + \frac{1}{2})$. Since the right hand side is always strictly larger than $\frac{1}{3}$ in the range of $l$ being considered, choosing $\delta = \frac{1}{3}$ gives $r = p + l$ in this case. Similarly, if $l < -\frac{1}{2}$, then $r = \max(r_0, r_1, r_\infty) = p + \frac{1}{6}$.
if and only if $\delta \geq \frac{1}{2}/(\frac{1}{2} - l)$. The right hand side being always smaller than $1/3$ in the given range of $l$, choosing any $\frac{1}{3} < \delta < \frac{1}{2}$ suffices. For $-\frac{1}{2} < l \leq \frac{1}{2}$, we get
\[
 r = \min_{\delta \geq \frac{1}{2}} \max \left( p + \delta l + \frac{1 - \delta}{2}, p + \frac{1}{6} + \delta(l + \frac{1}{2}), p + l \right) \\
= \min_{\delta \geq \frac{1}{2}} \left[ p + \delta l + \max \left( \frac{1 - \delta}{2}, \frac{1 + 3\delta}{6} \right) \right] \\
= \min_{\delta \geq \frac{1}{2}} \left[ p + \delta l + \frac{1 + 3\delta}{6} \right] \\
= p + \frac{l + 1}{3}.
\]
The case $l = -\frac{1}{2}$ is handled similarly. The details are left to the reader.  

7.1. **Remark.** Finally, we point out how, for the geometry $(\Delta, C_1)$ arising for the normal operator in single source seismic imaging in the presence of fold caustics, and more generally for FIOs with folding canonical relations, Thm. 1.1 follows from the proof for $(\Delta, C_0)$. From [32], one knows that the linearized forward scattering operator $F$ belongs to $I^1(C_{\text{sing}})$, where, as described in §§1.2, $C_{\text{sing}} \subset T^*X \times T^*Y$ is a folding canonical relation, and $F^*F \in I^{2,0}(\Delta, C_1)$. However, any folding canonical relation $C_{\text{fold}}$ may, by application of canonical transformations $\chi_L, \chi_R$ on the left and right, resp., be microlocally put in Melrose-Taylor normal form [28], so that we may assume that $C_{\text{fold}} \subset C_0 \times \Delta_{T \cdot \mathbb{R}^n - 2}$. In composing $C_{\text{fold}} \circ C_{\text{fold}}$, the $\chi_L, \chi_R^{-1}$ cancel, and a calculation shows that
\[
\chi_R^{-1}(C_{\text{fold}}^t \circ C_{\text{fold}})\chi_R \subset \chi_R^{-1}(\Delta \cup C_1)\chi_R \subset \Delta_{T \cdot \mathbb{R}^n} \cup \left[ C_0^{\frac{1}{4}} \times \Delta_{T \cdot \mathbb{R}^n - 2} \right],
\]
with $C_0^{\frac{1}{4}} = N^*\{x_2 - y_2 = \frac{1}{2}(x_1 - y_1)^3 \}^\prime$; on the operator level, for $A \in I^m(C_{\text{fold}})$, $B \in I^m(C_{\text{fold}})$, one has $B^*A \in I^{m+3,0}(\Delta, C_1)$ [32] [10]. Since $\chi_R$ and its inverse correspond to unitary FIOs, $L^2$-Sobolev estimates for $I^{p,j}(\Delta, C_1)$ follow from those for $I^{p,j}(\Delta, C_0^{\frac{1}{4}} \times \Delta_{T \cdot \mathbb{R}^n - 2})$. The coefficient $\frac{1}{4}$ being irrelevant to the analysis, the argument above for the $(\Delta, C_0)$ geometry can be repeated.

8. **Microlocal invertibilty : a counterexample**

In this section we describe an example related to the question of microlocal invertibility. Given an operator $A$ of the type considered in this paper, e.g., $A \in I^{p,l}(\Delta, C_0)$ as in [2,6], that is also elliptic in the sense that
\[
(8.1) \quad \inf_{x,y,\theta} \frac{|a(x,y,\theta)|}{\langle \theta_2, \theta_1 \rangle^{p+l} \langle \theta_1 \rangle^{l-\frac{1}{2}}} \geq c > 0,
\]
we would like to determine whether it is possible to left-invert $A$ microlocally in some appropriate $I^{p',l'}(\Delta, C_0)$ class. More precisely, and in view of Thm. 1.1 we pose the following:

**Question:** Let $r = r(p,l)$ denote the regularity exponent obtained in Thm 1.1. Given $p,l$, does there exist $p',l' \in \mathbb{R}$ satisfying
\[
r(p,l) + r(p',l') = 0
\]
and \( \epsilon > 0 \) depending only on \( p, p', l, l' \) such that for every \( A \in I^{p,l}(\Delta, C_0) \) that is elliptic in the sense of (8.1), one can find \( B \in I^{p',l'}(\Delta, C_0) \) such that

\[
E = BA - I \text{ maps } H^s_{\text{comp}} \text{ boundedly to } H^{s+\epsilon}_\text{loc} \text{ for every } s \in \mathbb{R}.
\]

We will call an operator \( E \) satisfying the Sobolev mapping property in (8.2) smoothing of order at least \( \epsilon \). The following result shows that the answer to this question is no in general.

**Proposition 8.1.** Let \( \mathcal{H} \) be the Hilbert transform along the cubic in \( \mathbb{R}^2 \) defined in (1.1), and let \( \psi \in C^\infty_0(\mathbb{R}^2) \). Then the operator \( \mathcal{H}_0 = \psi \mathcal{H} \psi \) lies in \( I^{-\frac{1}{2}, \frac{1}{2}}(\Delta, C_0) \) but there does not exist any \( B \) that maps \( H^s_{\text{comp}} \) boundedly into \( H^{s+\epsilon}_\text{loc} \) for every \( s \in \mathbb{R} \) and for which \( B \mathcal{H}_0 - I \) is smoothing of any positive order.

### 8.1. Facts about \( \mathcal{H} \)

Since the operator \( \mathcal{H} \) is translation-invariant, its Fourier transform is a multiplier operator, i.e., there exists a function \( m \) on \( \mathbb{R}^2 \) such that

\[
\mathcal{H} \hat{f}(\xi_1, \xi_2) = m(\xi_1, \xi_2) \hat{f}(\xi_1, \xi_2), \quad \text{with} \quad m(\xi_1, \xi_2) = \int e^{i(\xi_1 t + \xi_2 t^3)} \frac{dt}{t}.
\]

Properties of multipliers such as \( m \) have been extensively studied in the literature; see [13, 35] and references there. We note below without proof a few well-known facts about \( m \) that are crucial to the proof of the proposition.

1. \( m \in L^\infty(\mathbb{R}^2) \cap C^\infty(\mathbb{R}^2 \setminus \{0\}) \).
2. \( m(\rho \xi_1, \rho^3 \xi_2) = m(\xi_1, \xi_2) \) for all \( \rho > 0 \) and all \( \xi = (\xi_1, \xi_2) \in \mathbb{R}^2 \). In fact, \( m(\mu, 1) \) is an antiderivative of the classical Airy function composed with an affine transformation. See [1] Ch. 10.4 for details.
3. Figure 2 contains the graph of the function \( \mu \mapsto m(\mu, 1) \). We observe that the graph has a zero, i.e., there exists \( \alpha \neq 0 \) such that \( m(\xi_1, \alpha \xi_2^3) = 0 \). In other words, there is a unique cubic curve on which \( m \) vanishes.

Properties (i)-(iii) imply that there exists a constant \( C > 0 \)

\[
|m(\xi)| \leq C \min \left[ 1, \left| \alpha - \frac{\xi_2}{\xi_1^3} \right| \right].
\]

### 8.2. Construction of the function \( f_0 \)

The key element of the proof of Proposition 8.1 is the construction of a function \( f_0 \) of fixed compact support which lies in \( L^2 \) and not in \( H^s \) for any \( s > 0 \), but for which \( \mathcal{H} f \in H^s_{\text{loc}} \) for some \( \epsilon > 0 \). To this end, let us fix \( \chi \in C^\infty_0[-1, 1] \) such that \( \hat{\chi} \geq 0 \) on \( \mathbb{R} \), \( \hat{\chi}(0) > 0 \), set

\[
c_k = k^{-\frac{1}{2}}(1 + \log k)^{-1}, \quad k \geq 1,
\]

and define

\[
\hat{f}_0(\xi) = \sum_{k \geq 1} c_k \hat{\chi}(\xi_1 - n_k) \hat{\chi}(\xi_2 - \alpha n_k^3),
\]

where \( \{n_k\} \) is a fast growing sequence to be determined in the sequel. In particular, we will see that choosing \( n_k = 2^k \) works. We collect several facts about \( f_0 \) in the following sequence of lemmas.
Lemma 8.2. The function $f_0$ given by (8.5) has compact support in $[-1, 1] \times [-1, 1]$ and lies in $L^2(\mathbb{R}^2)$. A posteriori, this means that the infinite sum in (8.5) converges for almost every $\xi$.

Proof. Since 
\[ f_0(x) = \chi(x_1) \chi(x_2) \sum_{k \geq 1} c_k e^{i(n_k x_1 + \alpha n_k^3 x_2)}, \]
the support property of $f_0$ follows easily from that of $\chi$. We proceed to estimate the $L^2$ norm of $f_0$:

\[ \|f_0\|_2^2 = \|\hat{f}_0\|_2^2 = \sum_{k, k' \geq 1} c_k c_{k'} \int \hat{\chi}(\xi_1 - n_k) \hat{\chi}(\xi_2 - \alpha n_k^3) \hat{\chi}(\xi_1 - n_{k'}) \hat{\chi}(\xi_2 - \alpha n_{k'}^3) \, d\xi_1 \, d\xi_2 \]

\[ = \left[ \sum_{k = k'} + \sum_{k \neq k'} \right] =: S_1 + S_2, \quad \text{where} \]

\[ S_1 = \sum_{k \geq 1} c_k^2 \int \left[ \hat{\chi}(\xi_1 - n_k) \hat{\chi}(\xi_2 - \alpha n_k^3) \right]^2 \, d\xi \]

\[ \leq C \sum_{k \geq 1} k^{-1} (1 + \log k)^{-2} < \infty, \quad \text{and} \]

\[ S_2 = \sum_{k \neq k'} c_k c_{k'} \int \hat{\chi}(\xi_1 - n_k) \hat{\chi}(\xi_2 - \alpha n_k^3) \hat{\chi}(\xi_1 - n_{k'}) \hat{\chi}(\xi_2 - \alpha n_{k'}^3) \, d\xi \]

\[ \leq C \sum_{k \neq k'} c_k c_{k'} \int \hat{\chi}(\xi_1 - n_k) \hat{\chi}(\xi_1 - n_{k'}) \, d\xi \]

Figure 2. Plot of $\mu \mapsto m(\mu, 1)$
Let \( f \) be any smooth function of compact support. Without loss of generality, we may assume that \( \hat{\psi} \geq 0 \), with \( \hat{\psi}(0) > 0 \). We have to show that \( \psi f_0 \notin H^s \) for any \( s > 0 \).

Let us now choose small constants \( c_0, \epsilon_0 > 0 \) such that

\[
(8.6) \quad \inf \{ \hat{\psi}(|\xi|) : |\xi| \leq \epsilon_0 \} \geq c_0, \quad \inf \{ \hat{\chi}(|\xi_1|) : |\xi_1| \leq \epsilon_0 \} \geq c_0.
\]

We compute

\[
||\psi f_0||_{H^s}^2 = \int (1 + |\xi|^2)^s [\hat{\psi} * \hat{f}_0(\xi)]^2 d\xi
\]
\[
= \int (1 + |\xi|^2)^s \left[ \int \hat{\psi}(\xi - \eta) \hat{f}_0(\eta) d\eta \right] \left[ \int \hat{\psi}(\xi - \eta') \hat{f}_0(\eta') d\eta' \right] d\xi
\]
\[
\geq c_0^2 \int \int_D (1 + |\xi|^2)^s \hat{\psi}(\xi - \eta) \hat{f}_0(\eta) d\eta d\eta' d\xi,
\]

where at the last step we have replaced the domain of \((\xi, \eta, \eta')\) integration by the subset

\[
D := \{ (\xi, \eta, \eta') : |\xi - \eta| \leq \epsilon_0, |\xi - \eta'| \leq \epsilon_0 \},
\]

and then used the first inequality in (8.6). Substituting the expression for \( \hat{f}_0 \) from (8.5) in the last integrand and replacing the infinite sum (of non-negative summands) in \( k, k' \) by the smaller subsum over \( k = k' \) we obtain

\[
||\psi f_0||_{H^s}^2 \geq c_0 \sum_{k, k' \geq 1} c_k c_{k'} \int \int_D (1 + |\xi|^2)^s \hat{\chi}(\eta_1 - n_k) \hat{\chi}(\eta_2 - \alpha n_k^3)
\]

In the computation above, the second step in the estimation of \( S_2 \) follows from the bound

\[
\sup_{k, k'} \int \hat{\chi}(\xi_2 - \alpha n_k^3) \hat{\chi}(\xi_2 - \alpha n_{k'}^3) d\xi_2 \leq C < \infty,
\]

while the fourth step uses the inequality \( |\xi_1 - n_k| \geq |n_k - n_{k'}| - |\xi_1 - n_{k'}| \geq \frac{1}{2} |n_k - n_{k'}| \) if \( |\xi_1 - n_k| \leq \frac{1}{2} |n_k - n_{k'}| \). This completes the proof of Lemma 8.2. \( \square \)

Lemma 8.3. The function \( f_0 \) given by (8.5) does not lie in \( H^s_{loc} \) for any \( s > 0 \).

Proof. Let \( \psi \) be any smooth function of compact support. Without loss of generality, we may assume that \( \hat{\psi} \geq 0 \), with \( \hat{\psi}(0) > 0 \). We have to show that \( \psi f_0 \notin H^s \) for any \( s > 0 \).
The sum on the right hand side above diverges to $\infty$ for which there exists Lemma 8.4.

8.3.

sufficiently fast, for instance exponentially. This completes the proof of the Lemma

We now proceed to estimate the two sums separately. For the first, we write

\[
\|\mathcal{H} f_0\|_{H^s}^2 = \int \left| \mathcal{H} f_0(\xi) \right|^2 (1 + |\xi|^2)^s \, d\xi
\]

\[
= \int |m(\xi)|^2 |\mathcal{H} f_0(\xi)|^2 (1 + |\xi|^2)^s \, d\xi
\]

\[
= \sum_{k,k'} c_k c_{k'} \int |m(\xi)|^2 (1 + |\xi|^2)^s \hat{\chi}(\xi_1 - n_k) \hat{\chi}(\xi_2 - \alpha n_k^3) \hat{\chi}(\xi_1 - n_{k'}) \hat{\chi}(\xi_2 - \alpha n_{k'}^3) \, d\xi
\]

\[
= \left[ \sum_{k=k'} + \sum_{k \neq k'} \right] =: T_1 + T_2.
\]

We now proceed to estimate the two sums separately. For the first, we write

\[
T_1 = \sum_{k \geq 1} c_k^2 \int |m(\xi)|^2 \hat{\chi}(\xi_1 - n_k)^2 \hat{\chi}(\xi_2 - \alpha n_k^3)^2 (1 + |\xi|^2)^s \, d\xi
\]

\[
= \sum_{k \geq 1} c_k^2 \left[ \int_{\mathcal{E}_k} + \int_{\mathcal{E}_k^c} \right] =: T_{11} + T_{12},
\]

where \( \mathcal{E}_k = \{ \xi : |\xi_1 - n_k| \leq n_k^\epsilon, \ |\xi_2 - \alpha n_k^3| \leq n_k^\epsilon \} \).
Here $\kappa$ is a fixed small positive constant (in fact, any $\kappa < \frac{1}{3}$ will work). The multiplier estimate \((8.4)\) yields

\[
T_{11} \leq C \sum_{k \geq 1} c_k^2 \int_{E_k} \left| \alpha - \frac{\xi_2}{\xi_1} \right|^2 (1 + |\xi|)^{2s} d\xi
\]

\[
C \sum_{k \geq 1} c_k^2 \sup_{\xi \in E_k} \left[ (1 + |\xi|)^{2s} \left( \frac{|\xi_2 - \alpha \xi_1|^2}{|\xi_1|^2} \right) \right] |E_k|.
\]

But on $E_k$,

\[
|\xi_2 - \alpha \xi_1^3| = |\xi_2 - \alpha((\xi_1 - n_k) + n_k)^3| = |\xi_2 - \alpha n_k^3| + |\alpha||\xi_1 - n_k|^3 + 3|\alpha||\xi_1 - n_k|^2|n_k - n_k^c| + 3|\alpha||n_k^3| + 3|\alpha||n_k|^{1+2}\kappa
\]

\[
\leq n_k^c + |\alpha||n_k^3| + 3|\alpha||n_k^{1+2}\kappa| + 3|\alpha||n_k|^{2+\kappa}
\]

\[
\leq Cn_k^{2+\kappa},
\]

while

\[
|\xi_1| \geq n_k - |\xi_1 - n_k| \geq n_k - n_k^c \geq \frac{1}{2} n_k,
\]

and

\[
1 + |\xi| \leq 1 + |\xi_1| + |\xi_2|
\]

\[
\leq 1 + n_k + |\alpha n_k^3| + |\xi_1 - n_k| + |\xi_2 - \alpha n_k^3|
\]

\[
\leq 1 + n_k + |\alpha n_k^3| + 2n_k^c \leq Cn_k^3.
\]

Combining estimates \((8.9), (8.10)\) and \((8.11)\), and using the fact that $|E_k| = n_k^{2c}$, we arrive at the following bound for $T_{11}$:

\[
T_{11} \leq C \sum_{k \geq 1} c_k^2 \sum_{k \geq 1} c_k^2 n_k^{6s} \frac{n_k^{2+\kappa}n_k^{2}}{n_k^{6}} n_k^{2c} \leq C \sum_{k \geq 1} c_k^2 n_k^{4c+6s-2} < \infty
\]

if $s > 0$ is chosen small enough so that $4c + 6s < 2$.

We will now estimate $T_{12}$. For any $N \geq 1$,

\[
T_{12} = \sum_{k \geq 1} c_k^2 \int_{E_k} |m(\xi)|^2 \tilde{\chi}(\xi_1 - n_k)^2 \tilde{\chi}(\xi_2 - \alpha n_k^3)^2 (1 + |\xi|^2)^s d\xi
\]

\[
\leq C_N \sum_{k \geq 1} c_k^2 \int_{E_k} \frac{(1 + |\xi_1|)^{2s} (1 + |\xi_2|)^{2s} d\xi}{(1 + |\xi_1 - n_k|)^{2N} (1 + |\xi_2 - \alpha n_k^3|)^{2N}}
\]

\[
\leq C_N \sum_{k \geq 1} c_k^2 \int_{E_k} \frac{(1 + n_k + |\xi_1 - n_k|)^{2s} (1 + |\alpha n_k^3| + |\xi_2 - \alpha n_k^3|)^{2s} d\xi}{(1 + |\xi_1 - n_k|)^{2N} (1 + |\xi_2 - \alpha n_k^3|)^{2N}}
\]

\[
\leq C_N \sum_{k \geq 1} c_k^2 (1 + n_k)^{2s} (1 + |\alpha n_k^3|^{2s} \int_{E_k} \frac{d\xi}{[(1 + |\xi_1 - n_k|)(1 + |\xi_2 - \alpha n_k^3|)]^{2N-2s}}
\]

\[
\leq C_N \sum_{k \geq 1} c_k^2 n_k^{8s-\kappa N} \int (1 + |\xi_1 - n_k|)^{-2} (1 + |\xi_2 - \alpha n_k^3|)^{-2} d\xi < \infty.
\]

The last step follows from the fact that on $E_k$ at least one of the quantities $|\xi_1 - n_k|$ or $|\xi_2 - \alpha n_k^3|$ must be $\geq n_k^c$. For the sum in the last step to converge for a given
choice of $s$ and $\kappa$, we must choose $N$ large enough so that $2s - N < -2$ and $8s - \kappa N < 0$.

Finally, we turn to the estimation of $T_2$. This will be done almost exactly in the same way as $T_1$ but this time keeping in mind the almost orthogonality of the summands. More precisely,

$$T_2 = \sum_{k \neq k'} c_k c_{k'} \int |m(\xi)|^2 (1 + |\xi|^2)^s \hat{\chi}(\xi_1 - n_k) \hat{\chi}(\xi_2 - \alpha n_k^3)$$

$$\times \hat{\chi}(\xi_1 - n_{k'}) \hat{\chi}(\xi_2 - \alpha n_{k'}^3) \, d\xi$$

$$= \sum_{k \neq k'} c_k c_{k'} \left[ \int_{|\xi_1 - n_k| \leq \frac{1}{2}|n_k - n_{k'}|} + \int_{|\xi_1 - n_k| \geq \frac{1}{2}|n_k - n_{k'}|} \right]$$

$$\leq C \sum_{k \neq k'} c_k c_{k'} \int_{|\xi_1 - n_k| \geq \frac{1}{2}|n_k - n_{k'}|} |m(\xi)|^2 (1 + |\xi|^2)^s \hat{\chi}(\xi_1 - n_k) \hat{\chi}(\xi_2 - \alpha n_k^3)$$

$$\times \hat{\chi}(\xi_1 - n_{k'}) \hat{\chi}(\xi_2 - \alpha n_{k'}^3) \, d\xi$$

We observe that the integrand in the last step above is of the same form as the one occurring in the expression for $T_1$ (see the first line in (8.7)); the only distinction is that the function $\hat{\chi}^2$ in $T_1$ has been replaced by $\hat{\chi}$, which makes no difference to the estimation process. We leave the reader to verify that the same set of arguments that was used to estimate $T_1$ now yields a number $r = \min(2 - 4\kappa - 6s, \kappa N - 8s) > 0$ such that

$$\int |m(\xi)|^2 \hat{\chi}(\xi_1 - n_k) \hat{\chi}(\xi_2 - \alpha n_k^3)(1 + |\xi|)^{2s} \, d\xi \leq C n_k^{-r},$$

so that

$$T_2 \leq C \sum_{k \neq k'} \frac{c_k c_{k'} n_k^{-r}}{(1 + |n_k - n_{k'}|)^2}$$

$$\leq C \left[ \sum_{k \neq k'} \frac{c_k^2 n_k^{-2r}}{1 + |n_k - n_{k'}|} \right]^{\frac{1}{2}} \left[ \sum_{k \neq k'} \frac{c_{k'}^2}{1 + |n_k - n_{k'}|} \right]^{\frac{1}{2}} < \infty.$$

This completes the proof of Lemma 8.4.

8.3. Proof of Proposition 8.1. It is easy to check that $H_0 \in L^{-\frac{1}{2}, \frac{1}{2}}(\Delta, C_0)$, and we leave this to the reader. Without loss of generality, we may assume that the function $\psi$ in the statement of the proposition is identically 1 on $[-1, 1]^2$ and vanishes outside $[-2, 2]^2$. Let us suppose that there exists an operator $B$ that maps $H^s_{\text{comp}}$ boundedly to $H^s_{\text{loc}}$ for all $s \in \mathbb{R}$ and such that $B H_0 = I + E$, where $E$ is a smoothing operator of some order $\geq s_0 > 0$. Then $f_0 = B H_0 f_0 - E f_0$, where $f_0$ is the function in (8.5). Since supp($f_0$) $\subseteq [-1, 1]^2$ by Lemma 8.2, it follows from Lemma 8.4 that $H(\psi f_0) = H f_0 \in H^{s_1}$ for some small $s_1 > 0$, so $B H_0 f_0 \in H^{s_1}$. 

\[ \square \]
On the other hand, $Ef_0 \in H^{s_0}_{loc}$ since $f_0 \in L^2$ by Lemma \ref{s2}. This implies that $f_0 = Bf_0 - Ef_0 \in H^{s_2}_{loc}$ where $s_2 = \min(s_0, s_1) > 0$, thereby contradicting Lemma \ref{s3}. □

References

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