On the Static and Dynamical Transition in the Mean-Field Potts glass

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Abstract

We study the static as well as the glassy or dynamical transition in the mean-field $p$-state Potts glass. By numerical solution of the saddle point equations we investigate the static and the dynamical transition for all values of $p$ in the non-perturbative regime $p > 4$. The static and dynamical Edwards-Anderson parameter increase with $p$ logarithmically. This makes the glassy transition temperature lie very close to the static one. We compare the main predictions of the theory with the numerical simulations.
1 Introduction

This work is devoted to the study of the glassy properties of the mean-field Potts glass. Very recently there have been new developments in the spin-glass theory concerning frustrated mean-field models without explicit disorder [1, 2, 3, 4, 5, 6, 7]. It has been shown that these systems do have a glassy transition temperature below which thermal fluctuations are very small and dynamical relaxations are very slow. Even though these results are not new in the context of disordered systems it is much interesting to know that non disordered models also share these properties.

The purpose of this work is to study the glassy behavior of a disordered spin glass. In general, these systems have a static transition $T_{RSB}$ where replica symmetry is broken. The breaking of the replica symmetry can occur in two ways. There can be a continuous breaking pattern (as happens in the case of the Sherrington-Kirkpatrick (SK) model [8]) or there can be a one step breaking of the replica symmetry (as happens in $p$-spin models with $p > 2$ [9]). Also one can find intermediate phases where there is a pattern with one step of breaking superimposed to a region with continuous breaking (as happens in $p$-spin models or Potts models at low enough temperatures). The breaking pattern is fully described by the order parameter $q(x)$ which is a function defined in the interval $(0, 1)$ [10].

All these transitions are continuous from the thermodynamical point of view, i.e. there is no latent heat. But in some cases they can be first-order in the order parameter. This can occur because the thermodynamic potentials are continuous (they are usually expressed as integrals of the order parameter function $q(x)$).

The purpose of this work is the study of a disordered model with a discontinuous transition in the order parameter. These systems generally have a temperature $T_G$ where a dynamic instability appears. This temperature is called the glass temperature and is higher than the transition $T_{RSB}$ where the replica symmetry breaks. The first observation of this type was due to Kirkpatrick and Thirumalai who solved the off-equilibrium dynamics for the $p$-spin model above the glass temperature [11]. Subsequently, Kirkpatrick, Thirumalai and Wolynes studied the Potts mean-field glass reaching similar conclusions [12, 13]. Similar results were obtained in case of the $p$-spin spherical spin glass by Crisanti, Horner and Sommers [14]. Below the glass transition it has been shown by Cugliandolo and Kurchan [15] that the energy of the $p$-spin spherical spin glass model in the low temperature phase is higher than that predicted by the statics. For times larger than a time scale (which diverges exponentially with the size of the system) it is expected that the energy of the system will relax to its equilibrium value. How fast this time scale grows with the size of the system depends on particular features of the glass transition like the discontinuity in
the Edwards-Anderson parameter \( q_G \).

In order to investigate the glassy behavior of a disordered model we have decided to study the infinite-ranged Potts glass model. The reason is threefold. On the one hand, in the Potts model \( p \) is a tuning parameter for the magnitude of the static and the dynamical transition. On the other hand, the Potts model is amenable of numerical tests while other models like the \( p \)-spin model (Ising or spherical) are time consuming which makes numerical simulations practically impossible for \( p > 3 \). The situation is different in case of the random orthogonal model \cite{2} where the replica theory predicts the existence of a glassy phase in good agreement with the numerical simulations. Finally, the Potts glass model lacks the reflection symmetry \( \sigma_i \rightarrow -\sigma_i \) of some other models. This makes it more similar to real structural glasses.

As we will see later the Potts glass model present one (not serious) drawback. This is that for \( p > 2 \) the systems order ferromagnetically at low enough temperatures. In order to investigate the spin-glass behavior it is necessary to introduce an additional antiferromagnetic coupling constant. It is in these conditions that we have investigated the glassy features of the discontinuous transition. The research of a glass transition in presence of ferromagnetic order remains an interesting open problem.

This work completely solves the replica equations for the Potts model for arbitrary number of states \( p \). We will be able to exactly compute the static and the dynamical transition and we will compare the predictions with the numerical simulations.

We will see that a complete dynamical freezing never takes place, even for very large values of \( p \). For generic \( p \) there is always a residual entropy at the static transition \( T_{RSB} \). As shown by Gross, Kanter and Sompolinsky \cite{16} in the limit \( p \rightarrow \infty \) the statics of the Potts model converges to the Random Energy Model (REM) \cite{17, 27}. We will see that the convergence of the statics of the Potts glass model to the REM when \( p \rightarrow \infty \) is very slow (logarithmic in \( p \)). Surprisingly, we will see that also the dynamics converges logarithmically with \( p \) to a fully frozen dynamics but even more slowly than does the statics. For all practical purposes, i.e. for reasonable values of \( p \), the system is never fully frozen. In addition we will see that, for \( p > 4 \), the dynamical transition (also called the glass transition) is always very close to the static transition. This makes the glassy behavior of the Potts model very different from other models with a discontinuous transition in the order parameter like, for instance, the \( p \)-spin interaction Ising spin-glass model where the static and the dynamic Edwards-Anderson order parameter increase relatively fast with \( p \).

This partial freezing which occurs for the mean-field Potts glass has to be compared with deterministic models without quenched disorder and disordered spin-glasses. On the one hand, models like the low autocorrelation binary sequences \cite{1}, fully frustrated lattices
in the mean-field limit [6] or discrete matrix models [5] display a stronger glass transition because \( q_G \sim 1 \). In those cases there is no quenched disorder and frustration alone is the responsible to the existence of the glassy phase. The origin of the frustration is purely dynamical and self-induced by the dynamical process [3]. On the other hand, disordered models like the \( p \)-spin glass model [9] or the random orthogonal model (ROM) [2] do have a stronger freezing at the dynamical transition temperature. The presence of uncorrelated quenched disorder (i.e. \( \overline{J_{ij}J_{kl}} = J_{ij}J_{kl} \)) in the Potts glass, and also in the SK model, has the effect of softening the discontinuous transition. In some sense frustration corresponds to the existence of some constraints on the different values of the quenched couplings \( J_{ij} \). This is what happens in the random orthogonal model where the \( J_{ij} \) form an orthogonal random matrix. Also in the case of the \( p \)-spin glass model the quenched disorder variables \( J_{i1i2...ip} \) tend to frustrate the system much more than in the Potts case. In the Potts glass case, for a fixed value of the number of states \( p \), the number of quenched variables goes like \( N^2 \) (\( N \) is the number of sites) while in the \( p \)-spin glass model this number increases much faster with \( N \) for \( p > 2 \) (like \( N!/(N-p)! \sim N^p \) for finite \( p \)).

The work is divided as follows. In section 2 we introduce the model and we write closed expressions for the free energy at first order of replica symmetry breaking. In section 3 we solve numerically the static equations at one step of replica symmetry breaking and we determine the static and the dynamical transition. Section 4 compares the predictions to the numerical simulations. Finally we present the conclusions.

## 2 Static replica equations for the Potts glass

The Potts glass model is defined by the random Hamiltonian

\[
\mathcal{H} = -p \sum_{i<j} J_{ij} \delta_{\sigma_i \sigma_j},
\]

where \( p \) is the number of states and the variables \( \sigma \) can take the values 0, 1, ..., \( p - 1 \). The sum is extended over all \( \frac{N(N-1)}{2} \) pairs in the lattice and \( N \) is the number of sites. The couplings \( J_{ij} \) are randomly distributed with mean \( \frac{J_0}{N} \) and variance \( \frac{1}{N} \). In order to solve this random model we apply the replica method in order to compute the free energy \( f \)

\[
\beta f = \lim_{n \to 0} \frac{\log \overline{Z_n^p}}{Nn}
\]

where \( n \) is the number of replicas and the overline means average over the disorder. Performing the usual transformations (averaging over the disorder, decoupling the sites and introducing auxiliary fields) and using the identity (\( a, b = 1, \ldots, n \) are replica indices)
\[ \delta_{\sigma^+_a \sigma^+_b} = \sum_{r=0}^{p-1} \delta_{\sigma^+_a r} \delta_{\sigma^+_b r} \]  

(3)

one gets the following result \(^1\)

\[ Z_T^p = \int dm^r_a dQ^{rs}_{ab} e^{-N A[m,Q]} \]  

(4)

where \(r, s = 0, ..., p - 1\) denote the Potts states. The function \(A[m, Q]\) is given by

\[ A[m, Q] = \frac{n\beta^2(1-p)}{4} + \frac{\beta^2}{2p} (J_0 + \frac{p - 2}{2}) \sum_a (m^r_a)^2 + \frac{\beta^2}{2p^2} \sum_a \sum_{r, s} (Q^{rs}_{ab})^2 - \log Tr e^{H[m, Q]} \]  

(5)

with

\[ H[m, Q] = \frac{\beta}{p} (J_0 + \frac{\beta(p - 2)}{2}) \sum_a \sum_r m^r_a (p\delta_{\sigma^+_a r} - 1) + \frac{\beta^2}{2p^2} \sum_a \sum_{r, s} Q^{rs}_{ab} (p\delta_{\sigma^+_a r} - 1)(p\delta_{\sigma^+_b s} - 1) \]  

(6)

The stationary saddle point equations read

\[ m^r_a = \langle p\delta_{\sigma^+_a r} - 1 \rangle \]

\[ Q^{rs}_{ab} = \langle (p\delta_{\sigma^+_a r} - 1)(p\delta_{\sigma^+_b s} - 1) \rangle \]  

(7)

where the mean \(\langle \ldots \rangle\) is evaluated over the effective Hamiltonian in eq.(6). The order parameters \(m\) and \(Q\) satisfy the constraints

\[ \sum_r m^r_a = 0 \]

\[ \sum_r Q^{rs}_{ab} = 0 \]  

(8)

In the particular case \(p = 2\) with \(Q^{rs}_{ab} = -Q_{ab}\), \(Q^{rr}_{ab} = Q_{ab}\) one recovers the solution for the SK model [8]. It can be shown that ferromagnetic order is always preferred for \(p > 2\) for low enough temperatures. An estimate \(T_E\) for the temperature \(T_F\) below which ferromagnetic order appears is given by the following condition [19]

\[ J_0 + \frac{p - 2}{2T_E} = 1 \]  

(9)

In the special case \(J_0 = 0\) the ferromagnetic transition appears below \(T = 1\) for \(p < 4\) and above that temperature for \(p > 4\). Our main interest in this work is the study of

\(^1\)Alternatively one can use the simplex representation [18]
the spin-glass transition. In order not to observe the ferromagnetic transition it will be necessary to add an antiferromagnetic coupling in case \( p > 4 \). This will be discussed further at the end of this section. The spin-glass solution is given by \( m^r_a = 0 \). This means that all different \( p \) states are equally populated. The saddle point equations are independent of \( J_0 \) and the replica symmetric solution in this case is given by

\[
\begin{align*}
Q^r_{ab} &= q - q, \\
Q^r_{ab} &= q(p - 1).
\end{align*}
\] (10)

Substituting this result in eq.(7) we obtain

\[
\beta f = \frac{\beta^2}{4} (1 - p)(1 - q)^2 - \int_{-\infty}^{\infty} \prod_{r=1}^{p} \left( \frac{dy_r}{\sqrt{2\pi}} e^{-\frac{y_r^2}{2}} \right) \log \left( \sum_{r=1}^{p} \exp \left( \beta(qp)^{\frac{1}{2}} y_r \right) \right). \] (11)

The high-temperature result \( q = 0 \) gives the free energy \( f \), the internal energy \( u \) and the entropy \( s \),

\[
\begin{align*}
\beta f &= \frac{\beta^2 (1 - p)}{4} - \log(p) \\
u &= \frac{\beta(p - 1)}{2} \\
s &= \frac{\beta^2 (1 - p)}{4} + \log(p).
\end{align*}
\] (12)

Because the entropy has to be positive one finds that the replica symmetric solution breaks down, at least above or equalt to

\[
T_0 = \left( \frac{(p - 1)}{4 \log(p)} \right)^{\frac{1}{2}}.
\] (14)

It has been shown [20] that there is a continuous phase transition at \( T_c = 1 \) for \( p < 6 \) which is unstable for \( p \geq 2 \). This transition ceases to exist above \( p = 6 \) and cannot be found within the replica symmetric hypothesis.

It is necessary to break the replica symmetry. By expanding the free energy eq.(5) close to \( T_c = 1 \), Gross, Kanter and Sompolinsky [16] have found two different regimes according to the value of \( p \). In both cases the correct solution is given by one step of breaking. In the region \( 2.8 < p < 4 \) the transition is continuous. The breaking parameter \( m \) is \( \frac{\nu}{\sqrt{2}} \) at the transition temperature \( T_c = 1 \). At low enough temperatures the entropy of the one-step solution becomes negative and a continuous breaking is then necessary. In the regime \( p > 4 \)
the transition is discontinuous in $Q$ and the breakpoint parameter $m$ is equal to 1 at the transition temperature $T_c > 1$. Cwilich and Kirkpatrick [21] have shown that this one step solution is always stable for $p > p^* = 2.82$ below but close to $T_c$.

At first order of replica symmetry breaking we subdivide the $n$ replicas into $\frac{n}{m}$ blocks. Each block contains $m$ replicas [22]. The order parameter $Q_{ab}^r$ takes a certain value when both replicas $a, b$ belong to the same subblock and it is zero when both indices belong to two different subblocks. More explicitly, if $K$ denotes a subblock, we impose

$$Q_{ab}^{rs} = -q \quad (a, b \in K), \quad Q_{ab}^{rs} = 0 \quad (otherwise)$$

$$Q_{ab}^{rr} = -q(p - 1) \quad (a, b \in K), \quad Q_{ab}^{rr} = 0 \quad (otherwise)$$

(15)

We obtain the result,

$$\beta f = \frac{\beta^2}{4} (1 - p) + \frac{\beta^2}{4} (m - 1)(p - 1)q^2 + \frac{\beta^2}{2} q(p - 1) + \frac{\beta^2}{2} qm - \frac{1}{m} \log \int_{-\infty}^{\infty} \prod_{r=1}^{p} \left( \frac{dy_r}{\sqrt{2\pi}} e^{-\frac{y_r^2}{2}} \right) \left( \sum_{r=1}^{p} \exp(\beta (qp y_r)) \right)^m$$

(16)

The corresponding saddle point equations are

$$\frac{\partial f}{\partial q} = \frac{\partial f}{\partial m} = 0$$

(17)

which determine the correct solution. It is possible to solve perturbatively these equations in three different cases:

- Expanding around $p = 4$ since in this limit case the transition is quasi-continuous [12, 13]. This technique has be applied also in case of the $p$-spin model [11].

- Expanding around $T = 1$ using the so-called effective approximation for the free energy eq.(5) up to order $Q^4$ [21].

- Solving the limit $p \to \infty$. In this limiting the model converges to the random energy model [23]. For recent work see [24]

We are interested in the glassy behavior of the Potts model. Our approach will be to numerically solve the equation (17). This is the purpose of the next section.

Some comments are in order regarding the existence of the ferromagnetic transition. We said previously that the system orders ferromagnetically at low enough temperatures.
The temperature $T_F$ below which the system orders ferromagnetically is smaller than $T_E$ with $T_E < 1$ for $p < 4$. Also for $p < 4$ the spin-glass transition appears at $T_{RSB} = 1$. This means that in the regime $p < 4$ the spin-glass transition occurs at a temperature $T_{RSB}$ larger than the temperature $T_F$ at which ferromagnetic order sets in. On the other hand, for $p > 4$ the spin-glass transition $T_{RSB}$ occurs at a temperature greater than 1 but smaller than $T_F$. In order that $T_F < T_{RSB}$ it is necessary to introduce a negative value for $J_0$. In our numerical simulations we have chosen $J_0 = \frac{4-p}{2}$ in case $p > 4$ and $J_0 = 0$ for $p < 4$. In this way the spin-glass transition occurs at a larger temperature than the ferromagnetic ordering. Now, let us suppose that we perform a dynamical process of the system in which the temperature is slowly decreased starting from the high-temperature phase. We think that, once the system has entered the metastable glassy phase, then it remains trapped in this phase for a time which diverges exponentially with the size of the system. Consequently, the system is unable to see the ferromagnetic transition which occurs at a lower temperature. Two reasons reinforce this observation:

- Numerical studies of the case $J_0 = 0$ for $p > 4$ (see section 4) show that the ferromagnetic transition occurs at a temperature $T_F$ smaller than $T_E$ (eq.(9)). Then, for a generic negative value of $J_0$ we can expect the ferromagnetic transition to appear at a temperature much lower than $T_{RSB}$.

- We can expect there exists a glass transition associated to the static spin-glass one which probably occurs at a temperature $T_G$ larger than $T_{RSB}$.

In summary, by choosing $J_0$ as indicated above, the ferromagnetic transition temperature will always be smaller than the freezing temperature at which the spin-glass ordering appears. Only the case $p = 4$ could be a little tricky because the estimate for the ferromagnetic transition $T_E$ and the spin-glass transition coincide, but even in this case we have not observed in the numerical simulations a strong magnetic ordering.

We should note that there are very few works devoted to the study of the ferromagnetic behavior in the mean-field Potts glass and we think it would be interesting to investigate it.

### 3 The static and the dynamical transition

In this section we are going to solve numerically eq.(16). As is usual in spin-glass theory we have to maximize the free energy as a function of $q$ and $m$. We face the problem of computing the $p$-dimensional integral
\[ I = \int_{-\infty}^{\infty} \prod_{r=1}^{p} \left( \frac{dy_r}{\sqrt{2\pi}} e^{-\frac{y_r^2}{2}} \right) \left( \sum_{r=1}^{p} \exp(\beta(qp)^{1/2}y_r) \right)^m \]  

(18)

Because the solution of the replica equations involve a maximization in the \((q, m)\) plane it is mandatory to compute \(I\) with relatively high precision. Because \(I\) is a \(p\)-dimensional integral it can be computed with the usual techniques only for \(p\) not too large. The most easy thing one can do is to divide the \(p\)-dimensional space into small squares and use the Simpson algorithm or a similar one. The computation time grows as a power of \(p\). This makes the calculation practically impossible for \(p > 3\). However, if one exploits the fact that the integration argument is invariant under the permutation of the \(p\) indices \(r = 0, \ldots, p - 1\) then the integration region can be reduced to the hyperplane \(y_1 < y_2 < \ldots < y_p\) where the \(y_r\) denote the coordinates of one point. In this way one can gain a factor \(p!\) in the computation time and we have been able to solve with good enough precision up to \(p = 7\). These preliminary methods should be considered as checks for the main computation.

We have been able to reduce the \(p\)-dimensional integral to a two dimensional integral. In this way the problem is completely resoluble, at least numerically. We use the identity,

\[ A^{m-1} = \frac{1}{\Gamma(1-m)} \int_{0}^{\infty} dx \, x^{-m} e^{-Ax} \]  

(19)

where \(\Gamma(x)\) is the Gamma function that is well defined for \(x > 0\), i.e. \(m < 1\) as is the case once the analytic continuation \(n \rightarrow 0\) (\(n\) is the number of replicas) has been done.

We decompose the integrand in eq.(18) as a product of two terms \(A \ast A^{m-1}\) with \(A\) given by,

\[ A = \sum_{r=1}^{p} \exp(\beta(qp)^{1/2}y_r) \]  

(20)

Applying eq.(19) and using the fact that the integrand in eq.(18) is invariant under permutation of the indices we get the final result,

\[ I = \frac{pe^{\langle \frac{\beta^2}{2} \rangle}}{\Gamma(1-m)} \int_{0}^{\infty} dx \, x^{-m} (w(x))^{p-1} w(xe^{\beta^2/2}) \]  

(21)

where \(w(x)\) is given by

\[ w(x) = \int_{-\infty}^{\infty} \frac{dy}{\sqrt{2\pi}} \exp(-\frac{y^2}{2} - x \exp(\beta(qp)^{1/2}y)) \]  

(22)

The integral over \(x\) is well defined and free of divergences. However one has to be careful evaluating the integrand close to \(x = 0\). We have been able to maximize the free energy and completely solve the static replica equations up to \(p = 40\).
The results are shown in figures 1 and 2 where we plot the variational parameters $q$ and $m$ as a function of $T$. We plot the solutions for the cases, $p = 3, 5, 7, 10, 20, 40$. The transition temperature also grows with $p$. The solution of the integral eq.(21) presents some problems of precision at very low temperatures and also close to the transition temperature where it is difficult to precisely determine the value of the discontinuity. A more precise way to compute the critical temperature and the discontinuous jump of $q$ will be presented below. It is interesting to note how much slow is the convergence to the random energy model as $p$ increases. When $p$ increases the value of $q$ at the transition point grows very slowly. In fact, in the limit $p \to \infty$, the value of $q$ converges to 1 and the entropy is zero at the transition temperature. Using eq.(14) we obtain that the critical temperature grows like $T_0$ of eq.(14). This result was already noted in [16].

We have already observed that at very low temperatures the entropy of the one-step solution becomes negative (of order $10^{-2}$). Continuous breaking is necessary (as noted in [16]) but we have not studied this type of solution. It is not clear to us if any effect of this new transition could be observable in a numerical simulation.

We want to show now a more precise computation of the critical temperature $T_{RSB}$ and the glass transition $T_G$. From the dynamical point of view an instability in the dynamical equations appears at a temperature $T_G$ above the static transition $T_{RSB}$. Using the static approach, this dynamical temperature $T_G$ can be determined computing the smallest eigenvalue in the stability matrix. The vanishing at $T_G$ of this eigenvalue, sometimes called the replicon, corresponds to the marginality condition [25]. In principle, this condition correctly determines the dynamical or glass transition. Anyway it is not clear if it is the correct description of the dynamical behavior in the low temperature phase. This condition has been numerically solved in the random orthogonal model and it has been shown that it correctly describes the dynamical energy below the glass transition and not too low temperatures [2]. It also describes correctly the glass transition in case of deterministic models. The interested reader is referred to [2] for more details. In order to determine the glass transition for the Potts case we should compute the stability matrix of the problem. This is an involved task (which has been done by Cwilich and Kirkpatrick close to $T_c$ [21]) and we will follow a different strategy (already noted by Cwilich and Kirkpatrick but not fully explained). It can be shown that in the limit $m \to 1$ the replicon eigenvalue coincides with the longitudinal eigenvalue. This result can be shown using the exact expressions for the spectrum of the stability matrix which have been reported in the literature at first order of replica symmetry breaking [26]. From the stability analysis results of Cwilich and Kirkpatrick this can also be directly tested in the Potts glass case. Consequently, in order to determine the dynamical transition, suffices to impose the marginality condition for the
longitudinal fluctuations.

We expand the free energy eq.(16) around \( m = 1, \beta_f = 1 \)

\[
\beta f = \frac{1}{4} \beta^2 (1 - p) - \log(p) + (m - 1) \left( \frac{1}{4} \beta^2 (p - 1) q^2 + \frac{1}{2} \beta^2 q (p + 1) + \log(p) - I_2 \right)
\]  

(23)

where the integral \( I_2 \) is given by,

\[
I_2 = \exp\left(-\frac{\beta^2 pq}{2}\right) \int_{-\infty}^{\infty} \prod_{r=1}^{p} \left( \frac{dy_r}{\sqrt{2\pi}} e^{-y_r^2/2} \right) e^{\beta \sqrt{pq} y_1} \log\left( \sum_{r=1}^{p} \exp(\beta (qp)^{1/2} y_r) \right)
\]

(24)

For \( m = 1 \) eq.(23) reduces to the high-temperature free energy which is independent of \( q \). More generally, we can write the free energy as

\[
f = f_0 + (m - 1) f_1 + O((m - 1)^2)
\]

(25)

where \( f_0 \) is independent of \( q \). This general expansion locates the static and the dynamic transition. For the static transition we look for a temperature at which there is a solution \( q_{RSB} \) which satisfies

\[
\left( \frac{\partial f}{\partial q} \right)_{q=q_{RSB}} = \left( \frac{\partial f_1}{\partial q} \right)_{q=q_{RSB}} = 0
\]

\[
(f_1)_{q=q_{RSB}} = 0
\]

(26)

For the dynamical transition the stability is marginal and the second derivative of \( f \) respect to \( q \) vanishes,

\[
\left( \frac{\partial f}{\partial q} \right)_{q=q_G} = \left( \frac{\partial f_1}{\partial q} \right)_{q=q_G} = 0
\]

\[
\left( \frac{\partial^2 f}{\partial q^2} \right)_{q=q_G} = \left( \frac{\partial^2 f_1}{\partial q^2} \right)_{q=q_G} = 0
\]

(27)

The last equations correspond to the case in which an extremal solution of eq.(23) with \( q_G \neq 0 \) dissappears. It is then clear that the dynamical transition temperature is always higher than the static one. We have solved these equations for different values of \( p \). Now we face the problem of computing the \( p \)-dimensional integral \( I_2 \). It can be reduced to a two dimensional integral using the representation,

\[
\log(1 + A) = \int_{0}^{\infty} \frac{dx}{x} e^{-x}(1 - e^{-Ax})
\]

(28)
and taking

\[ A = \left( \sum_{r=1}^{p} \exp(\beta(qp)^{1/2}y_r) \right) - 1 \]  

we obtain the result

\[ I_2 = \int_{0}^{\infty} \frac{dx}{x} e^{-x} \left\{ 1 - e^{x} w(x e^{\beta/2}) w^{p-1}(x) \right\}. \]

with the same function \( w \) as given in eq.(22). We have solved equations eq.(26) and eq.(27) for different values of \( p \). Our results are summarized in Table 1. We find for each value of \( p \) two temperatures. One is \( T_{RSB} \) and corresponds to the static transition with the discontinuous jump \( q_{RSB} \). The other one is \( T_G \) and corresponds to the dynamical transition with the discontinuous jump \( q_G \). Our results for the static transition are in agreement with those found with the previous analysis using the maximization procedure for the free energy. This is a check of our procedures. Moreover this analysis provides a much more precise determination of the values of \( q_{RSB} \), \( q_G \) and the transition temperatures.

The results we have found are also in agreement with those reported by Cwilich and Kirkpatrick, the only difference is that all their computations are perturbative whereas ours are exact. As was obtained in [12] and [21] one finds that \( q_G/q_{RSB} = 3/4 \) for \( p \) close to 4. Looking at table 1 the reader can observe that the ratio \( q_G/q_{RSB} \) stays so close to \( 3/4 \), even for large values of \( p \), that one is tempted to conclude that this is exact at all orders in perturbation theory. Our numerical precision to solve the equations (26),(27) is good enough to exclude this possibility. From the results shown in the Table 1 it is clear that the convergence to the \( p \to \infty \) limit is very slow. Fortunately, our numerical program which solves the equations (26) and (27) is enough accurate to explicitly show this slow convergence even for exponentially large values of \( p \). We have solved the full equations up to \( p = 10^6 \). The results for \( q_{RSB} \) and \( q_G \) as a function of \( \frac{1}{\log(p)} \) are shown in figure 3.

Furthermore in the Potts case the ratio \( T_G/T_{RSB} \) grows very slowly with \( p \) being always smaller than 1.13 up to \( p = 10^6 \). The proximity of the temperatures makes it difficult to discern one from the other in numerical simulations. This proximity of the static and the dynamic transition temperatures is very probably related to the small value of the dynamical order parameter \( q_G \) for large values of \( p \). From these results we expect the glassy behavior of the Potts glass to be very different from other disordered spin-glass models.

For instance, in case of the \( p \)-spin interaction spin-glass model we have also solved the equations corresponding to eq.(26) and eq.(27). We have found that both the static order parameter \( q_{RSB} \) and the dynamical \( q_G \) converge to 1 in the limit \( p \to \infty \) much faster than
the Potts case in agreement with theoretical expansions around the $p \to \infty$ limit [24]. For $p = 3$ (the smallest value of $p$ compatible with a discontinuous transition) one finds in the $p$-spin model,

$$q_{RSB} \simeq 0.81 \quad (T_{RSB} \simeq 0.65)$$

$$q_G \simeq 0.68 \quad (T_G \simeq 0.68)$$  \hspace{1cm} (31)

For this particular model, the ratio $q_G/q_{RSB}$ tends to 1 in the limit $p \to \infty$ and the ratio $T_G/T_{RSB}$ increases with $p$ much faster than the Potts model does (for $p = 10$ we find $q_G/q_{RSB} \simeq .97$ and $T_G/T_{RSB} \simeq 1.38$).

In the next section we shall compare all these predictions with Monte Carlo numerical simulations. We will see that the Potts glass transition is always present but it is far from being a complete thermodynamic freezing as happens in models where frustration is stronger (see, for instance the random orthogonal model [2]). Before showing our Monte Carlo results for the spin-glass transition it will be interesting to present some results on the ferromagnetic ordering that takes place in the Potts glass. The problem of the existence also of a real glass transition above the ferromagnetic transition still remains open. Our main interest is to show that if one does not introduce an antiferromagnetic coupling then the ferromagnetic ordering takes place even though the transition temperature is well below that given by eq.(9).

4 Monte Carlo tests of the glass transition

In order to simulate the Potts glass we have considered the Hamiltonian,

$$\mathcal{H} = - \sum_{i<j} J_{ij} (p \delta_{\sigma_i \sigma_j} - 1)$$  \hspace{1cm} (32)

The $J_{ij}$ are distributed with mean $J_0/N$ and variance equal to $\frac{1}{N}$. For computational reasons we have chosen a binary distribution where the $J_{ij}$ can only take the values $\pm \frac{1}{\sqrt{N}}$. The only difference between the Hamiltonians of eq.(32) and eq.(1) is a constant which vanishes in the thermodynamic limit. We have chosen this second version because we have found that the addition of the constant strongly reduces the sample to sample fluctuations in the high-$T$ region. This should not make too much difference for small values of $p$ but is crucial for large values of $p$. All simulations implement the Metropolis algorithm with random updating.
The results we present in the next subsections correspond to annealings in which we compute the main thermodynamic observables. Starting from the high-temperature region the temperature is progressively decreased. Statistics is collected at each temperature and the time we stay at each temperature is the same for all temperatures during the cooling procedure. We have computed the internal energy, the magnetization of the different $p$-states and the associated dissipative quantities, i.e. the specific heat and the $p$ different magnetic susceptibilities corresponding to each one of the $p$-states. The specific heat and the magnetic susceptibility of one of the $p$ states is computed measuring the fluctuations of the internal energy and the magnetization (see eq.(7)) respectively. Typically we performed several thousands of Monte Carlo sweeps at each temperature. We have to call the attention of the reader that our results are dependent on the time schedule of the annealing only for very large values of $p$ (i.e. where the finite-size corrections are large). Otherwise, one cannot observe a sensible dependence of the different quantities on the time the system stays at each temperature during the cooling procedure. At least, this dependence is of the same order as that arising from the sample to sample fluctuation. Obviously we have performed annealing schedules as large as possible within our computing capabilities. We will eventually show the dependence on the annealing time in the large $p$ case.

4.1 Ferromagnetic ordering with $J_0 = 0$

When $J_0 = 0$ the system orders ferromagnetically. We have investigated the ferromagnetic ordering for $p = 10$. This value of $p$ is in the regime ($p > 4$) where the ferromagnetic transition is expected to appear at a temperature higher than the spin-glass transition. From eq.(9) we expect ferromagnetic order to be present below $T_E = 4$. Figure 4 shows the internal energy as a function of the temperature compared to the energy of the spin-glass phase and the high-temperature result eq.(13). The energy is lower than that corresponding to the spin-glass solution. Figure 5 shows the result for the magnetic susceptibility averaged over the different $p = 10$ states. The first well defined peak is at $T_F = 2.3$ which corresponds to the temperature at which the energy of the system departs from the high-temperature result (dashed line in figure 4). The specific heat also shows a peak at that temperature. The reader will immediately recognize that temperature as the ferromagnetic ordering temperature $T_F$ which is much lower than the estimate $T_E$. It is interesting to note in figure 5 the emergence of further peaks at lower temperatures. These are a sign of new transitions in the ferromagnetic phase. From the measurements of the magnetization we have observed that at the transition temperature there is one state which acquires a magnetization greater than zero which means that one state is macroscopically populated. We also have observed
that the other peaks at lower temperatures correspond to the emergence of new states which start to be macroscopically populated.

We have also studied the zero temperature ground state following a steepest descent procedure. We have searched for stable configurations against one-spin flip (for a generalization to stability against n-spin flips see [28]). Starting from a random initial configuration we sequentially move on the lattice selecting (among the \( p - 1 \) possibilities) the state of the variable \( \sigma(i) \) which releases the largest amount of energy. In this way the system reaches a metastable state that should be magnetized if the ground state is ferromagnetic. We have repeated this procedure several times saving the energy and the magnetization of the final configurations. Figures 6 and 7 show the distribution probability of the energies and the magnetization eq.(7) of the stable configurations against one-spin flip movements for the same model \( J_0 = 0, p = 10 \) with \( N = 100 \). Figure 6 shows that the energies of this class of metastable states are distributed very similarly to the form predicted for the SK model [29]. This is a consequence of the glassy nature of the ferromagnetic phase. We have verified that the minimum energy found by the algorithm is higher than the energy obtained doing a slow cooling starting from the high-temperature phase. This is a proof of the glassy nature of this phase. The ferromagnetic nature (but glassy) of the phase is explicitly shown in figure figure 7. The value of \( m \) ranges from \( m = -1 \) to \( m = p - 1 = 9 \). The peak at \( m = -1 \) is consequence of the fact that only some of the \( p = 10 \) states are populated.

### 4.2 The continuous transition \((p = 3)\)

The case \( p = 3 \) is indeed very similar to the SK model \((p = 2)\). Because the transition is continuous the system relaxes very close to the true energy. As mentioned in section 2, it now suffices to take \( J_0 = 0 \). In this way the ferromagnetic transition lies well below the spin-glass transition. In fact, we have not observed any tendency of the system to be magnetized at low temperatures. Figure 8 shows the internal energy as a function of the temperature along with the one-step solution and the high-temperature result eq.(13). Below the critical temperature \( T_{RSB} = 1 \) the data departs from the prediction. Precisely at \( T = 1 \) the specific heat and the magnetic susceptibility have a cusp. Similar results for the internal energy were obtained for \( p = 4 \).

### 4.3 The discontinuous transition

To investigate the discontinuous spin-glass transition we have chosen \( J_0 = \frac{4-p}{2} \) for \( p > 4 \). In this way the system first enters the metastable glassy phase in which there is no
ferromagnetic ordering. In all our simulations we have observed that this is what happens and that there is no tendency for the ferromagnetic domains to grow as the temperature is decreased. At high temperatures the size of the domains (i.e. the fraction of sites of the lattice which are in the same state) is $1/p$. This is true down to very low temperatures where in the worst case the size of the domains increase approximately ten percent. To make any tendency to the ferromagnetic ordering completely disappear we can increase the intensity of the antiferromagnetic coupling. This is only possible if $p$ is not too large because otherwise finite-size corrections (an consequently finite-time effects) considerably increase. In the regime of large values of $p$ one can neglect finite-size effects only if $p \ll N$. This is a problem of the simulations in the large $p$ regime (the region where the glass transition can be clearly appreciated). We will explicitly show the time dependence of the results of annealing for $p = 20$. We divide our results for the discontinuous transition in two parts, the small and the large $p > 4$ regime (corresponding to the magnitude of the finite-size corrections).

4.3.1 The small $p > 4$ regime

We have measured the internal energy as a function of the temperature for cases $p = 5, 10$. In this regime we have observed that the results do not vary too much depending with the time schedule of the cooling procedure. Comparison with theory is shown in figures 9 and 10. For these small values of $p$ the dynamical transition practically coincides with the static one. Comparing to the previous continuous case $p = 3$ we see that the energy in the low $T$ region is very close to the predicted one for $p = 5$ and remains slightly above the expected one in case $p = 10$. This is the glassy phase where the system remains trapped making excursions between several metastable states of similar energy but without reaching the static phase of slightly lower free energy. The difference in free energy (and energy) between the static phase and the metastable glassy phase is small for $p = 5$ and increases with $p$. It is important to note that the energy we are computing is purely dynamical. For $p \leq 4$ this difference of free energy does not exist. This does not mean that the system relaxes to the true ground state energy in an annealing process (see figure 8). In fact, for a continuous transition we expect the system should relax to the static free energy at a finite temperature very slowly (as a power law) very similarly to the relaxation of the remanent energy or the remanent magnetisation in the $SK$ model [30, 31]. For a discontinuous transition the relaxation of the free energy takes place also very slowly but to a dynamical value higher than that predicted by the static approach. We have also computed the specific heat and the magnetic susceptibility. They display a cusp located
approximately at the static transition (and, because of its proximity, also the dynamical transition). The reader may be a little puzzled by the data shown in figure 10 because the dynamical energy departs from the high-$T$ behavior at a temperature higher than the glass transition temperature. We think this occurs because the static and the glass transition temperatures are very close to each other. We will return to this point in the conclusion.

4.3.2 The large $p > 4$ regime

Finite-size corrections are important and one has to simulate large sizes in order to reduce these effects. We present the results of annealings for $p = 20, 40$ in figures 11 and 12. We decided to simulate the Gaussian $J_{ij}$ model instead of the binary $\pm J$ one in order to reduce finite-size corrections. As $p$ increases the finite-time effects also increase and we have found a clear dependence of our results on the cooling procedure. Figure 11 shows simulation results for $p = 20$ for $N = 2000$ and two different cooling procedures. The simulation results show a drift with the annealing time. For $p = 40$ (figure 12) we show simulations of two different sample realizations. Since sample to sample fluctuations increase with $p$, the relative magnitude of the fluctuations of figure 12 should be considered as an upper bound for the previous figures with smaller values of $p$. Also finite-time effects are large for $p = 40$. From figures 11 and 12 it can be appreciated that also in this case the energy departs from the high-$T$ result at a temperature higher than predicted for the glass transition.

Glassy effects are much more pronounced in the large $p$-regime, the dynamical energy being larger than the static one. All dissipative quantities show a cusp very close to the dynamical transition. Even though the static and the glass transition are very close one to the other the fact that the energy of the system is much higher than the static one (when approaching the glass transition) is a proof that the system has entered the glassy phase.

5 Conclusions

We have studied the glassy behavior of the mean-field Potts glass. We have been able to numerically solve the static equations at first order of replica symmetry breaking. Also we have introduced a simple method, already observed by Cwilich and Kirkpatrick [21], which allows a full computation of the static and the dynamical or glass transition and the associated Edwards-Anderson parameter.

We have numerically computed the parameters of the transition for different values of $p$. We observe that the Edwards-Anderson parameter at the glass transition $q_G$ increases logarithmically with $p$. The ratio of the static and glass temperature is smaller than $1.13$.
up to $p = 10^6$. The situation is very different from other disordered models such as the $p$-spin Ising model. For that model the dynamic transition temperature is much higher than the static one.

All our numerical results seem to indicate that the dynamical transition takes place at a temperature higher than that predicted by the theory. But this is due to the proximity of the dynamical transition to the static one. If the dynamical transition temperature were much larger than the static one then we would expect that the energy departs from the high-$T$ result precisely at the dynamical temperature. This is indeed the situation one observes in low autocorrelation models [1, 3, 7], in the random orthogonal model [2, 6] and discrete matrix models [5]. We would also expect this situation for the $p$-spin Ising model in the regime of not too small $p$, but unfortunately we are only able to perform simulations for $p = 3$.

For large values of $p$ (like $p = 20, 40$) we have observed a clear dependence on the time spent during the cooling procedure. The origin of the finite-time effects is related to the finite-size effects we also observe in this regime. We expect that simulations for larger sizes should give results nearly independent of the annealing time leaving only a small thermalization time effect close to the glass transition where critical effects begin to be important. We interpret this effect in the following scenario.

There are two characteristic relaxation times in the system. The first time $\tau_G$ diverges as the dynamical transition is approached, the other one $\tau_s$ diverges as the static transition is approached. Because $T_G$ is so close to $T_{RSB}$ the system feels the static low temperature phase very close to the dynamical transition temperature. Above the glass temperature we have $\tau_G \sim \tau_s$ which is certainly large if the system is entering the low temperature phase. Because the characteristic time scale $\tau_G$ increases very fast only very close to the dynamical transition temperature then we expect that close to $T_G$ the correlation time $\tau_s$ will set the characteristic time scale above which our simulation results should be time independent. Only for times larger than $\tau_s$ (which we are not able to reach in our simulations) the system would behave as dynamics predicts. It is then clear that all our simulation results are smeared by the static relaxation time $\tau_s$. In the other models mentioned in the previous paragraph the dynamical transition temperature is much larger than the static one. Approaching the dynamical transition the system is in the high temperature phase where the relaxation time is very small. Consequently, $\tau_G$ grows very much only very close to $T_G$ (very probably diverges like $\tau_G \sim (T - T_G)^{-\gamma}$ where $\gamma = 2$ the typical value for mean-field models [7]) and the system departs from the high-$T$ result very close to that temperature.

Because the Potts model is only partially frozen at the glass transition this is a model
appropriate for study of the dynamics in the metastable glassy phase. We expect that jumps among states could be seen numerically without special effort. For models without disorder, the system freezes quickly at the glass temperature and more involved numerical techniques are needed in order to allow the system to change state [32].

We would also like to draw attention to the interest of studying the ferromagnetic ordering for zero mean coupling. It would be interesting to understand the static as well as the dynamical behavior in that case.

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Figure caption

Fig. 1 The one-step breaking parameter $q$ as a function of the temperature. From left to right: $p = 3, 5, 7, 10, 20, 40$

Fig. 2 The one-step breaking parameter $m$ as a function of the temperature. The different lines that intersect the upper horizontal axis $m = 1$ correspond from left to right to: $p = 3, 5, 7, 10, 20, 40$

Fig. 3 The static and the dynamic Edwards-Anderson parameter as a function of $\frac{1}{\log(p)}$. They increase logarithmically with $p$. The dots are for the static value, the crosses for the dynamical one.

Fig. 4 Energy versus temperature for the case $p = 10$ with $J_0 = 0$. The continuous line corresponds to the one step spin-glass solution and the dashed line is the high-$T$ result. The ferromagnetic transition is close to 2.3. Simulation results are for one sample and $N = 1000$.

Fig. 5 Magnetic susceptibility versus temperature for the case $p = 10$ with $J_0 = 0$. The first peak appears at $T_F \sim 2.3$.

Fig. 6 Probability distribution of the energy of the ground states for case $p = 10$ and $J_0 = 0$ and $N = 100$.

Fig. 7 Probability distribution of the magnetization associated to the zero-temperature metastable states. The singularity at $m = -1$ means that only some states are populated. The same parameters as in figure 6.

Fig. 8 Energy versus temperature in case $p = 3$, $J_0 = 0$. The continuous line is the one-step solution. The dashed line is the high-$T$ result. The transition temperature is $T_{RSB} = T_G = 1$. The full dots are for one sample and $N = 2000$.

Fig. 9 Energy versus temperature in case $p = 5$, $J_0 = -1$. The continuous line is the one-step solution. The dashed line is the high-$T$ result. The transition temperatures are $T_{RSB} \simeq 1.0091, T_G \simeq 1.01$. The full dots are simulation results for $N = 1000$.

Fig. 10 Energy versus temperature in case $p = 10$, $J_0 = -3$. The continuous line is the one-step solution. The dashed line is the high-$T$ result. The transition temperatures are $T_{RSB} \simeq 1.13, T_G \simeq 1.14$. The full dots are simulation results for $N = 1000$. 
Fig. 11 Energy versus temperature in case $p = 20$, $J_0 = -8$. The continuous line is the one-step solution. The dashed line is the high-$T$ result. The transition temperatures are $T_{RSB} \simeq 1.36, T_G \simeq 1.39$. The crosses and the full dots correspond to the Gaussian model with $N = 2000$ and two cooling procedures (the simulations with crosses are 10 times larger in simulation time than the dots).

Fig. 12 Energy versus temperature in case $p = 40$, $J_0 = -18$. The continuous line is the one-step solution. The dashed line is the high-$T$ result. The transition temperatures are $T_{RSB} \simeq 1.71, T_G \simeq 1.76$. The crosses and the full squares correspond to the Gaussian model with $N = 1000$ and two different samples.
| $p$ | $T_{RSB}$ | $q_{RSB}$ | $T_G$ | $q_G$ | $T_G/T_{RSB}$ | $q_G/q_{RSB}$ |
|-----|----------|----------|------|------|---------------|----------------|
| 3   | 1        | 0        | 1    | 0    | —             | —              |
| 4   | 1        | 0        | 1    | 0    | —             | —              |
| 5   | 1.0091   | 0.130    | 1.0100 | 0.0985 | 1.001         | 0.757          |
| 7   | 1.053    | 0.308    | 1.058 | 0.231 | 1.004         | 0.75           |
| 10  | 1.1312   | 0.452    | 1.142 | 0.328 | 1.009         | 0.725          |
| 20  | 1.364    | 0.641    | 1.393 | 0.468 | 1.02          | 0.73           |
| 40  | 1.711    | 0.752    | 1.765 | 0.551 | 1.03          | 0.732          |
| 100 | 2.388    | 0.838    | 2.496 | 0.633 | 1.045         | 0.755          |
| $10^3$ | 6.075  | 0.931    | 6.51  | 0.721 | 1.07          | 0.774          |
| $10^4$ | 16.54  | 0.966    | 18.05 | 0.769 | 1.091         | 0.796          |
| $10^5$ | 46.69  | 0.981    | 51.64 | 0.802 | 1.1           | 0.817          |
| $10^6$ | 134.65 | 0.989    | 150.5 | 0.835 | 1.12          | 0.844          |

Table 1.
