Large Mixing Induced by the Strong Coupling with a Single Bulk Neutrino

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Abstract

Neutrino is a good probe of extra dimensions. Large mixing and the apparent lack of very complicated oscillation patterns may be an indication of large couplings between the brane and a single bulk neutrino. A simple and realistic five-dimensional model of this kind is discussed. It requires a sterile in addition to three active neutrinos on the brane, all coupled strongly to one common bulk neutrino, but not directly among themselves. Mindful that sterile neutrinos are disfavored in the atmospheric and solar data, we demand induced mixing to occur among the active neutrinos, but not between the active and the sterile. The size $R$ of the extra dimension is arbitrary in this model, otherwise it contains six parameters which can be used to fit the three neutrino masses and the three mixing angles. However, in the model those six parameters must be suitably ordered, so a successful fit is not guaranteed. It turns out that not only the data can be fitted, but as a result of the ordering, a natural connection between the smallness of the reactor angle $\theta_{13}$ and the smallness of the mass-gap ratio $\Delta M^2_{\text{solar}}/\Delta M^2_{\text{atmospheric}}$ can be derived.
I. INTRODUCTION

Neutrinos are different from the other fermions. They have small masses and large mixing. Small masses can be explained by the seesaw mechanism, or by the presence of large extra dimensions \([1]\). Large mixing is usually obtained with a right texture, which in the presence of extra dimensions can be arranged through appropriate couplings between the three or four brane neutrinos and the three or four bulk neutrinos. In this paper, we discuss a new and economical mechanism to generate large mixing \([2]\), through the strong coupling of a single bulk neutrino to the brane neutrinos.

We take the point of view that the main difference between neutrinos and other Standard Model (SM) fermions is due to the presence of extra dimensions. Being SM singlets, sterile neutrinos can roam in the bulk whereas other fermions cannot. If SM quantum numbers are trapped on the brane, perhaps flavor and generation numbers are trapped there as well, in which case there is no reason to require more than one neutrino in the bulk. With only one bulk neutrino to couple to, textures can no longer be arranged in the usual way, so the question is whether large and correct mixing between the brane neutrinos can be automatically induced by their couplings with this one common bulk neutrino. The answer is clearly no if the brane-bulk couplings are weak, but there is a chance when they are strong.

To be definite we consider a simple model with one extra flat dimension of radius \(R\), which we use as the inverse-energy unit in the problem. This model contains \(f\) brane neutrinos, each with its own Majorana mass \(m_i/R\), and a single sterile bulk neutrino, coupled via Dirac masses \(d_i/R\) to the brane neutrinos. The brane neutrinos do not directly couple among themselves, and the bulk neutrino does not have a 5D mass. All phases are ignored in this simple model, and for technical simplicity we shall take all \(m_i\) to be positive, and not equal to an integer nor a half integer. The \(f = 3\) case of this model with equal couplings \(d_i\) was first proposed in Ref. \([3]\).

We will not ask in this paper the dynamical origin of the Majorana mass nor the coupling; we will simply take the \(2f\) dimensionless parameters \(m_i\) and \(d_i\) to be real and adjustable.
Unless that works phenomenologically, there is no point to speculate on the dynamical origin of the model.

Models of this kind have been studied by many authors \[4–6\], but often without the Majorana masses, with \( f = 1 \), and/or in the weak coupling limit. When a single brane neutrino couples weakly to the bulk, oscillations occur between the brane neutrino and only a few low-lying Kaluza-Klein (KK) modes of the sterile bulk. Nevertheless, the participation of the few excited KK modes is important as they improve the poor energy dependence for a solar \( \nu_e \) to oscillate into a sterile neutrino \[1\]. To explain also atmospheric oscillation, it is necessary to introduce additional bulk neutrinos and arrange the texture of the couplings appropriately.

When couplings are increased, more KK modes are involved, which causes a wild and complicated oscillation pattern to emerge \[3\]. This could have been a smoking gun for the presence of an extra dimension, but unfortunately there is no hint in the experimental data to support it. The probability to convert an active neutrino into a sterile KK mode is also enhanced, a fact which might cause some discomfort because oscillation into sterile neutrinos is disfavored by experiments\[1\]. In the strong coupling limit when \( f = 1 \), the worrisome wild oscillations disappear, because the widths of the states are now larger than their separations, making the spectrum effectively a continuum. Leakage into the KK modes is now total, with a leakage rate increasing with the coupling \[6\], so very quickly the single brane neutrino simply disappear in sight. If \( f > 1 \), leakage is still present but is now divided among the \( f \) brane neutrinos. In addition to the continuum in the spectrum, there are now \( f - 1 \) isolated eigenstates through which brane neutrinos with induced mixing can oscillate. For \( f = 3 \), there are 2 isolated eigenvalues and hence only one mass difference, making it impossible to explain solar and atmospheric oscillations simultaneously \[2\].

In this paper we show that the strong coupling limit of \( f = 4 \) works. Besides the three

\[1\]The LSND experiment will be ignored throughout this paper.
active neutrinos $\nu_e, \nu_\mu, \nu_\tau$ on the brane, we must introduce a fourth one, $\nu_s$, which is sterile. Bearing in mind that oscillation into sterile neutrinos is disfavored, we concentrate on a scenario where no induced mixing exists between the sterile and the active brane neutrinos. In that case it turns out that the leakage into the bulk comes solely from $\nu_s$, which is nice for two reasons. First, since $\nu_s$ is sterile, there seems to be no reason for it to be confined to the brane, so one might expect it to mix more easily with the bulk. Second and more importantly, without leakage into the bulk or mixing with $\nu_s$, the active neutrinos behave as if the fifth dimension were absent. That increases the chance for the model to work because we know that 4D analyses are phenomenologically successful. Nevertheless, we must realize that the presence of the fifth dimension is indispensable for generating the induced mixing between the active neutrinos.

We will show that this decoupling scenario can be obtained by choosing $m_4$, the largest of the Majorana masses, to be much larger than the other $2f - 2 = 6$ dimensionless parameters. Six is just the right number of parameters to fit the three mixing angles and the three dimensionless neutrino masses $M_\alpha R$, whatever the radius $R$ is. Nevertheless, there is no guarantee that we can get a fit, because the resulting parameters must be ordered in a special way to be discussed later. It is therefore encouraging that a fit to experimental data is actually possible, with the requisite ordering of the parameters maintained.

As a consequence of this ordering, we will show that a very interesting connection can be established between the smallness of the reactor angle $\theta_{13}$ and the smallness of the mass-gap ratio $\Delta M_{\text{solar}}^2 / \Delta M_{\text{atmospheric}}^2$.

After reviewing the known result of the strong coupling limit \[2\] in Sec. 2 for any $f$, a new parameterization is introduced in Sec. 3, which is needed for the phenomenology application in Sec 4.
II. THE MODEL AND ITS STRONG COUPLING LIMIT

The model to be considered here consist of $f$ brane neutrinos, with Majorana masses $m_i/R$, and a single massless bulk neutrino which is coupled to the brane neutrinos through Dirac masses $d_i/R$, with $R$ being the radius of the extra dimension. In units of $1/R$, its mass matrix is given by

$$M = \begin{pmatrix}
m_1 & 0 & \cdots & 0 & d_1 & d_1 & d_1 & d_1 & \cdots \\
n_2 & 0 & \cdots & 0 & d_2 & d_2 & d_2 & d_2 & \cdots \\
\vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \vdots & \vdots & \ddots \\
0 & 0 & \cdots & m_f & d_f & d_f & d_f & d_f & \cdots \\
d_1 & d_2 & \cdots & d_f & 0 & 0 & 0 & 0 & \cdots \\
d_1 & d_2 & \cdots & d_f & 0 & 1 & 0 & 0 & \cdots \\
d_1 & d_2 & \cdots & d_f & 0 & 0 & -1 & 0 & \cdots \\
d_1 & d_2 & \cdots & d_f & 0 & 0 & 0 & 2 & \cdots \\
\cdots & \cdots & \ddots & \cdots & \cdots & \cdots & \cdots & \cdots & \ddots 
\end{pmatrix},$$

(1)

in which the rows and columns are labelled respectively by the left-handed and right-handed neutrinos. The first $f$ rows and columns are the brane neutrinos, and the rest are the $n$th mode of the bulk neutrino. The $2f$ parameters $d_i$ and $m_i$ are real and arbitrary, but for technical simplicity we will assume the $m_i$’s to be non-negative, and not equal to an integer or a half-integer.

The eigenvalues $\lambda$ of this matrix satisfies the characteristic equation

$$\frac{1}{\pi} \tan(\pi \lambda) = d^2 r(\lambda),$$

(2)

where $d^2 = \sum_{i=1}^f d_i^2$, so $e_i = d_i/d$ obeys the constraint

$$\sum_{i=1}^f e_i^2 = 1.$$  

(3)
The function \( r(\lambda) \) is given by
\[
r(\lambda) = \sum_{i=1}^{f} \frac{e_i^2}{\lambda - m_i}. \tag{4}
\]

In the absence of coupling, the bulk eigenvalues are integers and the brane eigenvalues are located at \( \lambda = m_i \). Accordingly we label the flavor states by an index \( i \) or \( n \), where \( i = 1, \ldots, f \) label the brane states and \( n \in \mathbb{Z} \) label the KK tower of bulk states.

In the strong-coupling limit\(^2\), when \( d \gg m_i \) and 1, the characteristic equation (4) is satisfied when either \( \tan(\pi\lambda) = \infty \), or \( r(\lambda) = 0 \). The former produces half-integer eigenvalues \( \lambda_n = n + \frac{1}{2}, \ n \in \mathbb{Z} \). The latter produces \( f - 1 \) ‘isolated’ eigenvalues \( \lambda_\alpha (1 \leq \alpha \leq f - 1) \), which are the roots of that equation\(^3\). Since \( r(\lambda) \) approaches \( +\infty \) for \( \lambda = m_i^+ \) and \( -\infty \) for \( \lambda = m_i^- \), it is not difficult to see that the isolated eigenvalues must always occur between pairs of \( m_i \)'s. In other words,
\[
0 < m_1 < \lambda_1 < m_2 < \lambda_2 < \cdots < \lambda_{f-1} < m_f. \tag{5}
\]

It is important to realize that in the strong coupling limit, flavor states are so thoroughly mixed up that it is impossible to tell whether a mass eigenstate is more brane like or bulk like, much less which flavor brane neutrino it should be identified with. In particular, it is

\(^2\) Strong coupling is expected if \( R^{-1} \) is the only additional energy scale that is relevant in the problem. This may be the case if there is only one large extra dimension, because then the gravitational energy scale is still very high and presumably irrelevant. Neutrino mass is given by the formula \( M = \kappa v / \sqrt{R} \)\(^1\), where \( v \) is the Higgs expectation value and \( \kappa \) is the brane-bulk coupling constant in the Lagrangian. \( \kappa \) has a dimension of \( \sqrt{R} \), and therefore can be expected to be of that order if there is no other relevant dimensional quantity around in the bulk. Our coupling constant \( d_i = MR = \kappa v \sqrt{R} \sim vR \) is then much larger than 1, if \( R \) is of a sub-milliliter size.

\(^3\)There is a slight change of notation from Ref. [3]: \( \lambda_2, \cdots, \lambda_f \) in Ref. [3] have been renamed \( \lambda_1, \cdots, \lambda_{f-1} \). Accordingly the first column of \( V \) in eq. (29) of Ref. [3] now appears at the last column.
not true that the states with half-integer eigenvalues are bulk like and the isolated ones are brane like. After all, there are only \( f - 1 \) isolated eigenvalues and not \( f \).

The transition amplitude \( A_{ij}(\tau) \) from a brane flavor neutrino \( j \) of energy \( E \) to a brane flavor neutrino \( i \), after it has traversed a distance \( L = 2E\tau R^2 \), is given by

\[
A_{ij}(\tau) = \sum_\lambda u_{i\lambda} u_{j}\lambda^* e^{-i\lambda^2 \tau},
\]

(6)

where the infinite-dimensional mixing matrix \( u_{i\lambda} \) is given by the flavor-\( i \) component of the normalized mass eigenstate with eigenvalue \( \lambda \). The sum over \( \lambda = n + \frac{1}{2} \) can be computed in the strong-coupling limit, resulting in a term proportional to a function \( g(x) \), with \( g(0) = 1 \) and \( g(x) \rightarrow (1 - i)/\sqrt{2\pi x} \) for large \(|x|\). The final result is \( 2 \)

\[
A_{ij}(\tau) = \sum_{\alpha=1}^{f-1} V_{i\alpha} V_{j\alpha} e^{-i\lambda_{\alpha}^2 \tau} + V_{if} V_{jf} g(K^2 \tau),
\]

(7)

where \( K^2 = d^2(1 + d^2\pi^2) \gg 1 \), \( V_{i\alpha} = u_{i\lambda} \), and \( V_{if} = e_1^2 \). Explicitly, the \( f \times f \) induced mixing matrix is given by

\[
V = \begin{pmatrix}
e_{1x1}/\sqrt{s_1} & e_{1x2}/\sqrt{s_2} & \cdots & e_{1x,f-1}/\sqrt{s_{f-1}} & e_1 \\
e_{2x1}/\sqrt{s_1} & e_{2x2}/\sqrt{s_2} & \cdots & e_{2x,f-1}/\sqrt{s_{f-1}} & e_2 \\
\cdots & \cdots & \cdots & \cdots & \cdots \\
e_{fx1}/\sqrt{s_1} & e_{fx2}/\sqrt{s_2} & \cdots & e_{fx,f-1}/\sqrt{s_{f-1}} & e_f
\end{pmatrix},
\]

(8)

where \( x_{i\alpha} = 1/(\lambda_{\alpha} - m_i) \) and

\[
s_{\alpha} = \sum_{i=1}^{f} \frac{e_i^2}{(\lambda_{\alpha} - m_i)^2}.
\]

(9)

The matrix \( V \) can be shown to be unitary; actually real orthogonal because \( e_i \) and \( m_i \) are assumed to be real. If we replace the function \( g(K^2 \tau) \) in (8) by \( \exp(-i\lambda_f^2 \tau) \), for some real number \( \lambda_f \), then (7) is the usual 4D transition-amplitude formula from flavor neutrino \( n_j \) to \( n_i \), through the mass eigenstates \( \tilde{n}_k \), with a mixing matrix\( 4 \) \( V: n_j = \sum_k V_{jk} \tilde{n}_k \). Moreover,

\[\text{4This relation is usually written as } \nu_i = \sum_{j=1}^{3} U_{ij} \tilde{\nu}_j (i = e, \mu, \tau) \text{ for three flavors. We use this unconventional notation to avoid later confusion, because } n_i \text{ turns out to be a permutation of } \nu_i, \text{ and } \tilde{\nu}_j \text{ a permutation of } \tilde{\nu}_j, \text{ so } U \text{ is obtained from } V \text{ by permutating rows and columns.}\]
if we choose $\lambda_f \gg \lambda_\alpha$, for $1 \leq \alpha \leq f - 1$, then for any detector with finite resolution, the last term $\exp(-i\lambda_f^2 \tau)$ averages to zero except for tiny $\tau$'s, just like $g(K^2 \tau)$. In other words, this 5D model in the strong coupling limit resembles a 4D theory with a mixing matrix $V$ and a mass pattern $(f - 1) + 1$, with a huge mass gap between the first $f - 1$ neutrinos $\tilde{n}_\alpha$ and the last one, $\tilde{n}_f$. Since $\tilde{n}_f$ represents the total effect of the tower of half-integral eigenvalues, rather than oscillating through it, it will be shown immediately below that a brane neutrino disappears into it. In other words, we should probably think of $\lambda_f^2$ as having a negative imaginary part.

Unlike the 4D case, the total probability for an initial flux of flavor $j$ to remain on the brane is not 1. There is a leakage into the bulk, equal to

$$1 - \sum_{i=1}^{f} |A_{ij}(\tau)|^2 = e_j^2 \{ 1 - |g(K^2 \tau)|^2 \} \simeq e_j^2.$$  

The leakage starts out to be 0 at $\tau = 0$, but in the strong-coupling limit it reaches its asymptotic value $e_j^2$ almost instantaneously. This leakage is given by the square of the matrix elements in the last column of $V$. Since $\sum_j e_j^2 = 1$, the total leakage into the bulk from all brane neutrinos is 1, independent of $f$.

III. A SIMPLE PARAMETERIZATION

It is fairly complicated to compute the elements of $V$ in (8). Given the parameters $e_i$ and $m_i$, we must first find the eigenvalues $\lambda_\alpha$ by solving $r(\lambda_\alpha) = 0$. Then we have to compute $x_{i\alpha}$ and $s_\alpha$, and finally the matrix elements of $V$. In this section, we discuss a much simpler parameterization of $V$ which enables its elements to be computed without having to solve any equation. This new parameterization is needed for the phenomenological discussion in the next section.

Instead of the $2f - 1$ parameters $e_i$ and $m_i$, we use as independent parameters $m_i$ and $\lambda_\alpha$. Since $\lambda_\alpha$ are the zeros of the function $r(\lambda)$ in (2), they must obey the ordering in (5), but otherwise these parameters are free to vary. To show that we must be able to compute
$e_i^2$ from these new parameters. To that end note that the function $r(\lambda)$ is a meromorphic function with zeros at $\lambda_\alpha$ and simple poles at $m_i$, and it goes like $1/\lambda$ for large $|\lambda|$. Hence it is equal to

$$r(\lambda) = \frac{\prod_\beta (\lambda - \lambda_\beta)}{\prod_j (\lambda - m_j)}.$$  \hfill (11)

Unless otherwise specified, all products over $j$ are taken from 1 to $f$, and all products over $\beta$ are taken from 1 to $f - 1$. The quantity $e_i^2$, being the residue at the simple pole $m_i$, is then equal to

$$e_i^2 = \frac{\prod_\beta (m_i - \lambda_\beta)}{\prod_{j \neq i} (m_i - m_j)}.$$  \hfill (12)

With the ordering (5), $e_i^2$ obtained from (12) are automatically non-negative.

We can now calculate from (9) to get

$$s_\alpha = (-1)^\alpha \frac{\prod_{\beta \neq \alpha} (\lambda_\alpha - \lambda_\beta)}{\prod_j (\lambda_\alpha - m_j)},$$  \hfill (13)

which is always positive if (3) is obeyed. Since $x_{i\alpha} = 1/(\lambda_\alpha - m_i)$, the matrix elements of $V$ become

$$V_{i\alpha} = \frac{1}{\lambda_\alpha - m_i} \frac{\prod_\beta (m_i - \lambda_\beta) \prod_j (\lambda_\alpha - m_j)}{\prod_{j \neq i} (m_i - m_j) \prod_{\beta \neq \alpha} (\lambda_\alpha - \lambda_\beta)},$$

$$V_{if} = e_i^2 = \frac{\prod_\beta (m_i - \lambda_\beta)}{\prod_{j \neq i} (m_i - m_j)}. \hfill (14)$$

The index $i$ runs from 1 to $f$, and the index $\alpha$ runs from 1 to $f - 1$. It is easy to see that the sign of $V_{ij}$ is positive unless $j < i$, when it is negative. With the sign taken care of, the magnitude of the matrix elements can be written in the more symmetric form

$$|V_{i\alpha}| = \frac{\prod_{\beta \neq \alpha} (m_i - \lambda_\beta) \prod_{j \neq i} (\lambda_\alpha - m_j)}{\prod_{j \neq i} (m_i - m_j) \prod_{\beta \neq \alpha} (\lambda_\alpha - \lambda_\beta)},$$

$$V_{if} = e_i^2 = \frac{\prod_\beta (m_i - \lambda_\beta)}{\prod_{j \neq i} (m_i - m_j)}. \hfill (15)$$

Note that $V$ is scale invariant, in that $V$ is unchanged if we multiply every parameter $m_i, \lambda_\alpha$ by the same scale factor.
The matrix elements of $V$ in (15) appear deceptively symmetrical, but they are actually not because of (3). For example, there is no way to let $m_3 - m_2 \rightarrow 0$ without also letting $\lambda_2 - m_2$ and $m_3 - \lambda_2 \rightarrow 0$. Similarly, there is no way to make $m_3$ large without also making $\lambda_3$ and $m_4$ large, but we can make $m_4$ large without affecting other parameters.

In view of (4), all quantities can be expressed in terms of the $2(f - 1)$ consecutive distances

$$p_\alpha = \lambda_\alpha - m_\alpha , \quad (1 \leq \alpha \leq f - 1)$$
$$q_\alpha = m_{\alpha + 1} - \lambda_\alpha . \quad (16)$$

Since $V_{ij}$ is scale invariant, there are actually only $2f - 3$ independent parameters needed to specify $V$.

From (15) one sees that every matrix element of $V$ has an equal number of $m_\alpha$’s in the numerator as the denominator, except $V_{\alpha f}$ and $V_{f \alpha}$, which have one more $m_\alpha$ in the denominator than the numerator. Hence if $m_\alpha \gg m_\alpha, \lambda_\alpha$, the induced mixing matrix $V$ will take on the form

$$\begin{pmatrix}
* & * & \cdots & * & 0 \\
* & * & \cdots & * & 0 \\
\cdots & \cdots & \cdots & \cdots & \cdots \\
* & \cdots & \cdots & * & 0 \\
0 & 0 & \cdots & 0 & 1
\end{pmatrix}, \quad (17)$$

where the asterisks indicate elements that are generally not zero. In that case, there is no induced mixing between the first $f - 1$ flavor neutrinos and the last. There is also no leakage of $n_\alpha$ into the bulk, for $1 \leq \alpha \leq f - 1$.

IV. PHENOMENOLOGY

The neutrino mass corresponding to eigenvalue $\lambda_\alpha$ is $M_\alpha = \lambda_\alpha / R$. In order to have two different $\Delta M^2$’s to explain both atmospheric and solar neutrino oscillations, we need three
distinct $\lambda$’s, hence $f = 4$. Thus in addition to the three brane neutrinos $\nu_e, \nu_\mu, \nu_\tau$ which are active, we are forced to have one more brane neutrino $\nu_s$ that is sterile.

In the usual 4D analysis, a sterile neutrino $\nu_s$ is introduced to get us three independent $\Delta M^2$’s, needed to explain solar, atmospheric, as well as LSND oscillations. In the present context in five dimensions, leakage into the bulk is simulated by an infinite $\Delta M^2$, so we need four brane neutrinos just to have two finite $\Delta M^2$’s.

Experimentally, oscillation from solar and atmospheric neutrinos into the sterile ones are disfavored. Since $\nu_s$ must be present in the theory, this requirement can be fulfilled if $\nu_s$ decouples from the active neutrinos, as in (17). All we have to do is to let $n_4 = \nu_s$, and choose $m_4$ to be far greater than $\lambda_\alpha$ and $m_\alpha$.

Since $V$ is scale invariant, it is more useful to express it in scale-invariant parameters

$$\xi = p_1/(q_1 + p_2 + q_2 + p_3)$$
$$\alpha = q_1/(q_1 + p_2 + q_2 + p_3)$$
$$\beta = p_2/(q_1 + p_2 + q_2 + p_3)$$
$$\gamma = q_2/(q_1 + p_2 + q_2 + p_3)$$
$$\delta = p_3/(q_1 + p_2 + q_2 + p_3).$$

(18)

Only four of these are independent because

$$\alpha + \beta + \gamma + \delta = 1.$$ (19)

See Fig. 1 for a summary of the parameters used.

The exact expressions for the asterisks in (17) are:

$$V_{11} = \sqrt{\frac{(\alpha + \xi + \beta)(1 + \xi)(\gamma + \alpha + \beta)\alpha}{(\alpha + \xi)(\gamma + \alpha + \xi + \beta)(\beta + \alpha)}}$$
$$V_{12} = \sqrt{\frac{\xi(1 + \xi)\gamma\beta}{(\alpha + \xi)(\gamma + \alpha + \xi + \beta)(\delta + \gamma)(\beta + \alpha)}}$$
$$V_{13} = \sqrt{\frac{\xi(\alpha + \xi + \beta)\delta(\gamma + \beta + \delta)}{(\alpha + \xi)(\gamma + \alpha + \xi + \beta)(\delta + \gamma)}}$$
We shall henceforth denote this $3 \times 3$ sub-matrix of $V$ as $V$.

With phases neglected, there are six measurable quantities, the three neutrino masses and the three mixing angles. There are seven parameters in the model, so one of these parameters can never be determined. We shall take it to be the radius $R$ of the fifth dimension. The other six parameters $m_\alpha, \lambda_\alpha$ can in principle be determined from the six experimental quantities, but there is no guarantee that the fitted parameters will obey the ordering relation (5). It is therefore very encouraging that the resulting fit from the known experimental data does obey (5).

As seen in (20), four parameters are needed to specify the induced mixing matrix $V$, not three. Hence the values of the neutrino masses $M_\alpha$ may affect the values of the mixing angles. This turns out to be the case in a particularly relevant situation which we shall discuss later.

The fitting of experimental data is not as straight-forward as it might be, because we do not know how $V$ is linked to the experimental mixing matrix $U$, defined by $\nu_i = \sum_{j=1}^{3} U_{ij} \tilde{\nu}_j \ (i = e, \mu, \tau)$, and parameterized as

\[
V_{21} = -\sqrt{\frac{\beta(\gamma + \beta + \delta)(\gamma + \alpha + \beta)\xi}{(\alpha + \xi)(\gamma + \beta)(\beta + \alpha)}}
\]
\[
V_{22} = \sqrt{\frac{\alpha(\gamma + \beta + \delta)\gamma(\alpha + \xi + \beta)}{(\alpha + \xi)(\gamma + \beta)(\delta + \gamma)(\beta + \alpha)}}
\]
\[
V_{23} = \sqrt{\frac{\alpha \beta \delta(1 + \xi)}{(\alpha + \xi)(\gamma + \beta)(\delta + \gamma)}}
\]
\[
V_{31} = -\sqrt{\frac{\gamma \delta \alpha \xi}{(\gamma + \alpha + \xi + \beta)(\gamma + \beta)(\beta + \alpha)}}
\]
\[
V_{32} = -\sqrt{\frac{(\gamma + \alpha + \beta)\delta \beta(\alpha + \xi + \beta)}{(\gamma + \alpha + \xi + \beta)(\gamma + \beta)(\delta + \gamma)(\beta + \alpha)}}
\]
\[
V_{33} = \sqrt{\frac{(\gamma + \alpha + \beta)\gamma(\gamma + \beta + \delta)(1 + \xi)}{(\gamma + \alpha + \xi + \beta)(\gamma + \beta)(\delta + \gamma)}}
\]
\[
U = \begin{pmatrix}
    c_{12}c_{13} & s_{12}c_{13} & s_{13} \\
    -s_{12}c_{23} - c_{12}s_{23}s_{13} & c_{12}c_{23} - s_{12}s_{23}s_{13} & s_{23}c_{13} \\
    s_{12}s_{23} - c_{12}c_{23}s_{13} & -c_{12}s_{23} - s_{12}c_{23}s_{13} & c_{23}c_{13}
\end{pmatrix}. \tag{21}
\]

As usual, \( s_{ij} = \sin \theta_{ij} \) and \( c_{ij} = \cos \theta_{ij} \), and phases are ignored. We shall follow the usual convention to take all mixing angles to be between 0 and \( \pi/2 \), so that both \( s_{ij} \) and \( c_{ij} \) are non-negative.

We do know that the three \( n \)'s are flavor neutrinos so they must be the same as the three \( \nu \)'s, and that the three \( \tilde{n} \)'s are mass eigenstates so they must be identical to the three \( \tilde{\nu} \)'s. But, we do not know which is which. \( n_i \) is arranged according to increasing Majorana masses \( m_i \) of the uncoupled flavor neutrinos, and \( \tilde{n}_j \) is arranged according to increasing eigenvalues. On the other hand, \( \nu_i \) is fixed by their weak interactions, and \( \tilde{\nu}_j \) is tied to \( \nu_i \) through \( U_{ij} \) and the experimental mixing angles. To find the correct assignments of \( n_i \) to \( \nu_i \) and \( \tilde{n}_j \) to \( \tilde{\nu}_j \), we need to determine what permutations of rows and columns of \( V \) are needed to bring it into the form of \( U \). As noted earlier, although there are six parameters in \( V \), the ordering requirement \((\ref{eq:ordering})\) does make the columns and rows of \( V \) inequivalent.

The present experimental situation is as follows.

Atmospheric mixing is maximal. It gives \( \tan^2 \theta_{23} = 1 \), with a square mass difference \( \Delta M_{\text{atm}}^2 = 2.5 \times 10^{-3} \text{(eV)}^2 \) \cite{atm_mass}.\footnote{Recent studies indicate that atmospheric mixing may be slightly smaller than previously thought, with some hints suggesting \( \tan^2 \theta_{23} = 1.0 \) \cite{atm_mass}}

There are several possible solar-neutrino solutions \cite{sol_mass,sol_mass2,sol_mass3}. Of these we consider the three most likely ones: LMA, LOW, and VAC. The exact parameters and the goodness of the fit of each depend on the specific analysis, but generally speaking, the LMA solution is the most favorable. In global analyses where both rate and spectrum are taken into account, the SMA solution is poor so we will not consider it. The parameters do not vary that much from analysis to analysis, so for the following discussions, we will adopt the parameters taken from Table 2 of Ref. \cite{sol_mass}. The \( (\tan^2 \theta_{12}, \Delta M_{\text{sol}}^2) \) values for these solutions are: LMA=(0.36, 5 \times 10^{-5}), VAC=(0.363, 1.4 \times 10^{-10}), LOW=(0.69, 1.1 \times 10^{-7}). The unit for \( \Delta M^2 \) is \( \text{(eV)}^2 \).\footnote{The solar mass-squared difference \( \Delta M_{\text{sol}}^2 \) is measured with high precision and is a key input in understanding the solar neutrino problem.}
As for the reactor angle, only an upper bound of \( \tan^2 \theta_{13} < 0.04 \) is known\(^5\) from the CHOOZ experiment [11].

We do not know the values of \( M_\alpha \), except for an upper bound of about 2 eV [12] from end point measurements of tritium \( \beta \)-decay. We will therefore treat \( M_1 \) as a parameter, to be varied from 0 to 2 eV. Using (5), the values of \( M_2 \) and \( M_3 \) are then determined from the magnitude of the solar and atmospheric gaps. If the solar gap is on top, then

\[
M_2 = \sqrt{M_1^2 + (\Delta M^2)_{atm}} \quad \text{and} \quad M_3 = \sqrt{M_2^2 + (\Delta M^2)_{sol}}.
\]

We will designate this case as \( G = 1 \).

If the solar gap is at the bottom, then

\[
M_2 = \sqrt{M_1^2 + (\Delta M^2)_{sol}} \quad \text{and} \quad M_3 = \sqrt{M_2^2 + (\Delta M^2)_{atm}}.
\]

We will designate this case as \( G = 2 \).

Let

\[
\rho = (M_2 - M_1)/(M_3 - M_1) = \alpha + \beta = 1 - \gamma - \delta
\]

be the ratio of mass differences. Its value depends on \( M_1 \), on \( G \), and on the solar-neutrino solution. Listed below are some values of \( \rho \) for the solar solutions [LMA, LOW, VAC] at various \( M_1 \) and \( G \):

\[
\begin{align*}
[.98995, .99998, 1.00000] & \quad (M_1 = 0 \text{ eV}, \ G = 1) \\
[.98001, .99996, 1.00000] & \quad (M_1 = 1 \text{ eV}, \ G = 1) \\
[.98000, .99996, 1.00000] & \quad (M_1 = 2 \text{ eV}, \ G = 1) \\
[.14142, .00663, 0.00024] & \quad (M_1 = 0 \text{ eV}, \ G = 2) \\
[.02001, .00004, 0.00000] & \quad (M_1 = 1 \text{ eV}, \ G = 2) \\
[.02000, .00005, 0.00000] & \quad (M_1 = 2 \text{ eV}, \ G = 2).
\end{align*}
\]

We see that \( \rho \) is close to 1 for \( G = 1 \), and close to 0 for \( G = 2 \).

\(^5\) CHOOZ quotes an upper bound of \( \sin^2(2\theta) = 0.1 \) for large \( \Delta M^2 \), corresponding to a \( \tan^2 \theta = 0.026 \). In the vicinity of \( \Delta M^2 = 2.5 \times 10^{-3} \text{ eV}^2 \), the best-fitted atmospheric mass difference, the bound is \( \tan^2 \theta \simeq 0.038 \). We will be cautious and take \( \tan^2 \theta_{13} < 0.04 \).
An analytical solution exists if we approximate \( \rho \) to be 0 for \( G = 2 \), and 1 for \( G = 1 \). This is discussed below, separately for \( G = 2 \) and \( G = 1 \), together with the numerical solutions when this approximation is not made.

**A. \( G = 2 \)**

The mass of \( \tilde{n}_i \) increases with \( i \). When the solar gap is at the bottom, either \((\tilde{n}_1, \tilde{n}_2, \tilde{n}_3) = (\tilde{\nu}_1, \tilde{\nu}_2, \tilde{\nu}_3)\), or \((\tilde{n}_1, \tilde{n}_2, \tilde{n}_3) = (\tilde{\nu}_2, \tilde{\nu}_1, \tilde{\nu}_3)\).

When \( \rho = 0 \), it follows from (22) that \( \alpha = \beta = 0 \), because both \( \alpha \) and \( \beta \) must be non-negative. Using (19), we also get \( \delta = 1 - \gamma \). Defining \( \alpha/\beta = a \), the matrix \( V \) in this limit simplifies to

\[
V = \begin{pmatrix}
\sqrt{(1 + \xi)\gamma a/(\gamma + \xi)(1 + a)} & \sqrt{(1 + \xi)\gamma/(\gamma + \xi)(1 + a)} & \sqrt{\xi(1 - \gamma)/(\gamma + \xi)} \\
-\sqrt{1/(1 + a)} & \sqrt{a/(1 + a)} & 0 \\
-\sqrt{(1 - \gamma)a\xi/(\gamma + \xi)(1 + a)} & -\sqrt{(1 - \gamma)\xi/(\gamma + \xi)(1 + a)} & \sqrt{(1 + \xi)/(\gamma + \xi)}
\end{pmatrix}
\]

(24)

The outstanding feature of this matrix is \( V_{23} = 0 \). Since \( \tilde{n}_3 = \tilde{\nu}_3 \) and the atmospheric mixing is maximal, the only way that this could happen is for \( n_2 = \nu_e \), and \( V_{23} = U_{e3} = s_{13} = 0 \).

Thus the smallness of \( s_{13} \) is naturally related to the smallness of \( \Delta M^2_{sol}/\Delta M^2_{atm} \), at least in the sense that we are forced to have \( s_{13} = 0 \) if the mass ratio is zero. This remarkable feature of the model is a consequence of the ordering (5), which demands both \( \alpha \) and \( \beta \) to be non-negative. It is not the result of an arranged texture.

To implement the atmospheric mixing condition \( \tan^2 \theta_{23} = 1 \), we need \( \xi = \gamma/(1 - 2\gamma) \), then

\[
V = \begin{pmatrix}
\sqrt{a/2(1 + a)} & \sqrt{1/2(1 + a)} & \sqrt{1/2} \\
-\sqrt{1/(1 + a)} & \sqrt{a/(1 + a)} & 0 \\
-\sqrt{a/2(1 + a)} & -\sqrt{1/2(1 + a)} & \sqrt{1/2}
\end{pmatrix}.
\]

(25)

To bring \( V \) into the form of \( U \), we can multiply the first column of \( V \) by \(-1\) (this is just a change of sign convention), and change its rows (1,2,3) to (2,1,3). The resulting matrix
\[
\mathbf{U} = \begin{pmatrix}
\sqrt{1/(1+a)} & \sqrt{a/(1+a)} & 0 \\
-\sqrt{a/2(1+a)} & \sqrt{1/2(1+a)} & \sqrt{1/2} \\
\sqrt{a/2(1+a)} & -\sqrt{1/2(1+a)} & \sqrt{1/2}
\end{pmatrix}
\] (26)

should be compared with \( U \) in the approximation \( s_{13} = 0 \), which is

\[
U = \begin{pmatrix}
c_{12} & s_{12} & 0 \\
-s_{12}c_{23} & c_{12}c_{23} & s_{23} \\
s_{12}s_{23} & -c_{12}s_{23} & c_{23}
\end{pmatrix}
\] (27)

It shows \( s_{12} = \sqrt{a/(1+a)} \) and \( c_{12} = \sqrt{1/(1+a)} \). Since \( a \) is arbitrary, all solar solutions can be accommodated.

If we interchange the first two columns and also the last two rows of \( \mathbf{U} \), we simply interchange \( a \) with \( a^{-1} \). Since \( a \) is arbitrary, this form is equally allowed. Hence there is no way to distinguish the case \((n_2, n_3) = (\nu_\mu, \nu_\tau)\) and \((\tilde{n}_1, \tilde{n}_2) = (\tilde{\nu}_1, \tilde{\nu}_2)\) from the case \((n_2, n_3) = (\nu_\tau, \nu_\mu)\) and \((\tilde{n}_1, \tilde{n}_2) = (\tilde{\nu}_2, \tilde{\nu}_1)\).

The actual value of \( \rho \) is given in (23). It is zero for the VAC solution when \( M_1 \) is between 1 and 2 eV, to within the number of digits shown, so the analytical solution discussed above is perfectly adequate. No more will be said about it.

For the other cases, \( \rho > 0 \), numerical solutions are provided in Table I. This Table is constructed in the following way. For a given \( M_1 \) and \( \xi \), and a given solar solution, the three parameters \( \beta, \gamma, \delta \) \((\alpha = 1 - \beta - \gamma - \delta)\) are determined from fitting the three inputs, \( \rho \), \( \tan^2 \theta_{23} = 1 \), and \( \tan^2 \theta_{12} \). Then \( \tan^2 \theta_{13} \) is calculated. To test the goodness of the approximation \( \rho = 0 \), we also list in the last two columns \( a = \alpha/\beta \) and \( \gamma/(1-2\gamma) \) calculated from the fitted parameters. When \( \rho = 0 \), the former is equal to \( \tan^2 \theta_{12} \), and the latter is equal to \( \xi \). Other than the LMA solution at \( M_1 = 0 \) eV, where \( \rho = .14 \) is fairly large, the agreement is quite good. This shows that the approximation \( \rho = 0 \) is a very reasonable one.

Since \( \tan^2 \theta_{13} = 0 \) when \( \rho = 0 \), one might expect \( \tan^2 \theta_{13} \) (and therefore also \( \sin^2 \theta_{13} \)) to be small when \( \rho \) is small. A glance at Table I shows that this is not necessarily the case, as we can adjust the parameter \( \xi \) to yield a \( \tan^2 \theta_{13} \) as large as the CHOOZ bound 0.04, or
even bigger. To understand what this means let us examine the formula

\[ \sin^2 \theta_{13} = \frac{\alpha \beta \delta (1 + \xi)}{(\alpha + \xi)(\gamma + \beta)(\delta + \gamma)} \]  

(28)

obtained from (20). For small \( \rho \), both \( \alpha \) and \( \beta \) are small. As pointed out above, the approximations \( \xi \simeq \gamma/(1 - 2\gamma) \) and \( \tan^2 \theta_{12} \simeq a = \alpha/\beta \) are good. The parameter \( a \) is fixed by the solar solution, so \( \sin^2 \theta_{13} \) is of order \( \beta^2 \), unless the denominator in (28) is also small. Now \( \delta + \gamma = 1 - \alpha - \beta \simeq 1 \) for small \( \beta \) and \( \alpha \), and \( \xi \) is proportional to \( \gamma \) for small \( \gamma \), hence the denominator is small and of order \( \beta^2 \) if and only if \( \gamma \) is itself of order \( \beta \). In that case \( \xi \simeq \gamma \), and

\[ \sin^2 \theta_{13} \simeq \frac{a}{(a + c)(1 + c)} \quad (\gamma = c\beta \ll 1) \]  

(29)

may indeed be large. An examination of Table I shows this is indeed what happens: \( \tan^2 \theta_{13} \) is relatively large only when \( \gamma \) is relatively small.

\( \gamma \) can vary from 0 to 1 \(-\alpha - \beta \simeq 1 \) for small \( \rho \). Except for very small \( \gamma \), in most of this range it yields a small \( \tan^2 \theta_{13} \). So in a statistical sense it is indeed true that a small \( \rho \) tends to yield a small \( \tan^2 \theta_{13} \), meaning that the smallness of the reactor angle is naturally related to the smallness of the solar to atmospheric mass gap ratio.

**B. \( G = 1 \)**

The main conclusions of the last subsection are essentially unchanged. Here are the details.

When the solar gap is on top, either \((\bar{n}_1, \bar{n}_2, \bar{n}_3) = (\bar{\nu}_3, \bar{\nu}_2, \bar{\nu}_1)\) or \((\bar{n}_1, \bar{n}_2, \bar{n}_3) = (\bar{\nu}_3, \bar{\nu}_1, \bar{\nu}_2)\) must be true.

When \( \rho = 1 \), it follows from (22) that \( \gamma = \delta = 0 \) because they must both be positive. In that case it follows from (19) that \( \alpha = 1 - \beta \). Defining \( \delta/\gamma = d \), the matrix \( \mathbf{V} \) in this limit simplifies to be
\[
\mathbf{V} = \begin{pmatrix}
\sqrt{\frac{(1+\xi)(1-\beta)}{1-\beta+\xi}} & \sqrt{\frac{-\xi\beta}{(1-\beta+\xi)(1+d)}} & \sqrt{\frac{-\xi d\beta}{(1-\beta+\xi)(1+d)}} \\
-\sqrt{\frac{d\beta}{1-\beta+\xi}} & \sqrt{\frac{(1-\beta+\xi)(1+d)}{(1-\beta+\xi)(1+d)}} & \sqrt{\frac{(1-\beta)(1+\xi)}{(1-\beta+\xi)(1+d)}} \\
0 & -\sqrt{\frac{d}{1+d}} & \sqrt{\frac{1}{1+d}}
\end{pmatrix}.
\]  
(30)

Similar to the case \( G = 2 \), since \( \tilde{n}_1 = \tilde{v}_3 \), we should identify \( V_{31} = U e^3 = s_{13} = 0 \), and hence \( n_3 = \nu_e \). The atmospheric condition \( \tan^2 \theta_{13} = 1 \) then requires \( \xi = (1 + d - \beta - d\beta)/(\xi - d + 2\beta + d\beta) \), and turns \( \mathbf{V} \) into

\[
\mathbf{V} = \begin{pmatrix}
\sqrt{\frac{1}{(2+d)}} & \sqrt{\frac{1}{(2+d)}} & \sqrt{\frac{d}{(2+d)}} \\
-\sqrt{\frac{1}{(2+d)}} & \sqrt{\frac{1}{(2+d)}} & \sqrt{\frac{d}{(2+d)}} \\
0 & -\sqrt{\frac{d}{1+d}} & \sqrt{\frac{1}{1+d}}
\end{pmatrix}.
\]  
(31)

Multiplying the second row and the second column each by \(-1\), and interchanging the first and third rows and well as the first and third columns, bring \( \mathbf{V} \) to the form

\[
\mathbf{U} = \begin{pmatrix}
\sqrt{\frac{1}{(1+d)}} & \sqrt{\frac{d}{(1+d)}} & 0 \\
-\sqrt{\frac{d}{(1+d)(2+d)}} & \sqrt{\frac{1}{(1+d)(2+d)}} & \sqrt{\frac{(1+d)/(2+d)}{1/(2+d)}} \\
\sqrt{\frac{d}{(2+d)}} & -\sqrt{\frac{1}{(2+d)}} & \sqrt{\frac{1}{(2+d)}}
\end{pmatrix},
\]  
(32)

which we can identify with \( U \) of \( (27) \) to fix the parameter \( d \) from the solar angle.

we can carry out a numerical fit like Table I and obtain similar results. Since in this case \( \rho \sim 1 \) is a fairly good approximation even for the \( M_1 = 2 \) situation of LMA, we will not show these fits here.

V. CONCLUSION

In theories with extra dimensions where ordinary particles are confined to the three-brane, only gravity and sterile neutrino are allowed to roam in the bulk. Moreover, if there is only a single large extra dimension, the energy scale of gravity would still be too high to produce many gravitons, then it leaves neutrino to be the only probe of extra dimensions in high-energy experiments. It is therefore important to investigate whether there are signs pointing to a higher dimension in the neutrino data.
A large extra dimension may explain the small neutrino mass. Strong coupling between brane and bulk neutrinos may also explain large mixing not seen in the quark sector. Unfortunately, it is not easy to realize these ideas, because oscillation into sterile neutrinos are greatly disfavored in the solar and atmospheric neutrino data, and the presence of the Kaluza-Klein tower of sterile neutrinos from the bulk tends to produce a very complicated oscillation pattern not hitherto observed. In this paper we consider a simple and economic model where both of these problems are solved. The model consists of a sterile neutrino $\nu_s$ in addition to three active neutrinos $\nu_e, \nu_\mu, \nu_\tau$ on the brane, coupled strongly to a single common neutrino in the bulk, but not directly among themselves. In the strong coupling limit, the complicated oscillation patterns are washed out, the induced couplings between the brane neutrinos become large, and the sterile neutrinos on the brane and in the bulk can be made to decouple from the active neutrinos. This results in a realistic theory of neutrino oscillations, capable of accommodating all existing neutrino data. It also predicts a natural connection between the smallness of the reactor angle $\theta_{13}$, and the smallness of the solar to atmospheric mass gap ratio.

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TABLE I. Each of these tables shows the fitted parameters \((\alpha, \beta, \gamma, \delta)\) for a given \(M_1\) and \(\xi\), when \(G = 2\). The resulting value of \(\tan^2 \theta_{13}\) is given. The last two columns should be equal to \(\tan^2 \theta_{12}\) and \(\xi\) respectively in the \(\rho = 0\) limit. To save space, \(1.8 \times 10^{-5}\), for example, is written as 1.8(-5).

LMA. \(M_1 = 2\) eV. \(\rho = .02\). \(\tan^2 \theta_{12} = 0.36\).

| \(\xi\) | \(\tan^2 \theta_{13}\) | \(\alpha\) | \(\beta\) | \(\gamma\) | \(\delta\) | \(\alpha/\beta\) | \(\gamma/(1 - 2\gamma)\) |
|-------|----------------|-------|-------|-------|-------|--------|----------------|
| .500  | .0007          | .0054 | .0146 | .2465 | .7335 | .3668   | .4862         |
| .300  | .0013          | .0054 | .0146 | .1868 | .7932 | .3662   | .2983         |
| .050  | .0211          | .0052 | .0148 | .0520 | .9280 | .3488   | .0581         |
| .032  | .0398          | .0050 | .0150 | .0375 | .9425 | .3329   | .0406         |

LMA. \(M_1 = 0\) eV. \(\rho = .14\). \(\tan^2 \theta_{12} = 0.36\).

| \(\xi\) | \(\tan^2 \theta_{13}\) | \(\alpha\) | \(\beta\) | \(\gamma\) | \(\delta\) | \(\alpha/\beta\) | \(\gamma/(1 - 2\gamma)\) |
|-------|----------------|-------|-------|-------|-------|--------|----------------|
| 100   | .0043          | .0415 | .0999 | .4106 | .4480 | .4150   | 2.297         |
| 10    | .0050          | .0414 | .1000 | .3937 | .4648 | .4142   | 1.853         |
| 1     | .0139          | .0408 | .1006 | .2846 | .5740 | .4054   | 0.661         |
| .34   | .0391          | .0390 | .1024 | .1901 | .6685 | .3807   | 0.307         |

LOW. \(M_1 = 2\) eV. \(\rho = .00005\). \(\tan^2 \theta_{12} = 0.69\).

| \(\xi\) | \(\tan^2 \theta_{13}\) | \(\alpha\) | \(\beta\) | \(\gamma\) | \(\delta\) | \(\alpha/\beta\) | \(\gamma/(1 - 2\gamma)\) |
|-------|----------------|-------|-------|-------|-------|--------|----------------|
| .5000 | 4.4(-9)        | 1.8(-5)| 2.7(-5)| .2500 | .7500 | .6900   | .4999         |
| .0100 | 4.9(-6)        | 1.8(-5)| 2.7(-5)| .0098 | .9901 | .6900   | .0100         |
| .0010 | .0005          | 1.8(-5)| 2.7(-5)| .0010 | .9989 | .6898   | .0010         |
| .0001 | .0313          | 1.8(-5)| 2.7(-5)| .0001 | .9998 | .6738   | .0001         |
LOW. $M_1 = 0$ eV. $\rho = .00663. \tan^2 \theta_{12} = 0.69.$

| $\xi$ | $\tan^2 \theta_{13}$ | $\alpha$ | $\beta$ | $\gamma$ | $\delta$ | $\alpha/\beta$ | $\gamma/(1 - 2\gamma)$ |
|-------|----------------|----------|----------|------------|---------|--------------|----------------------|
| 1     | 4.2(-5)       | .0027    | .0039    | .3302      | .6632   | .6946        | .9723                |
| .100  | .0012         | .0027    | .0039    | .0833      | .9101   | .6940        | .0999                |
| .030  | .0099         | .0027    | .0039    | .0291      | .9643   | .6894        | .0309                |
| .013  | .0398         | .0027    | .0040    | .0137      | .9797   | .6739        | .0141                |

VAC. $M_1 = 0$ eV. $\rho = .00024. \tan^2 \theta_{12} = 0.363.$

| $\xi$ | $\tan^2 \theta_{13}$ | $\alpha$ | $\beta$ | $\gamma$ | $\delta$ | $\alpha/\beta$ | $\gamma/(1 - 2\gamma)$ |
|-------|----------------|----------|----------|------------|---------|--------------|----------------------|
| .1000 | 1.3(-6)       | 6.3(-5)  | .0002    | .0834      | .9164   | .3631        | .1001                |
| .0100 | .0001         | 6.3(-5)  | .0002    | .0099      | .9899   | .3630        | .0101                |
| .0010 | .0080         | 6.2(-5)  | .0002    | .0011      | .9987   | .3562        | .0011                |
| .0004 | .0400         | 5.9(-5)  | .0002    | .0005      | .9993   | .3292        | .0005                |
FIG. 1. A summary of the parameters in the strong-coupling limit for $f = 4$. $m_i$ are the Majorana masses and $\lambda_\alpha$ are the isolated eigenvalues. These parameters must be ordered as indicated. Shown in the figures are also the distances $p_\alpha, q_\alpha$ as well as the ratios $\xi, \alpha, \beta, \gamma,$ and $\delta$. The common distance with respect to which the ratios are taken is $\lambda_3 - \lambda_1$. 