OGLE-2016-BLG-0693LB: Probing the Brown Dwarf Desert with Microlensing

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Abstract

We present an analysis of a microlensing event OGLE-2016-BLG-0693, based on the survey-only microlensing observations by the OGLE and KMTNet groups. In order to analyze the light curve, we consider the effects of parallax, orbital motion, and baseline slope, and also refine the result using a Galactic model prior. From the microlensing analysis, we find that the event is a binary composed of a low-mass brown dwarf \((49.0^{+20.0}_{-11.0} M_J)\) companion and a K- or G-dwarf host, which lies at a distance of \(5.0 \pm 0.6 \text{kpc}\) toward the Galactic bulge. The projected separation between the brown dwarf and its host star is less than \(\sim 5\) au, thus it is likely that the brown dwarf companion is located in the brown dwarf desert.

Key words: binaries: general – brown dwarfs – gravitational lensing: micro

1. Introduction

Brown dwarfs are generally known as failed stars that lack sufficient mass to ignite hydrogen burning. The upper mass limit of brown dwarfs so defined therefore varies from 0.07 \(M_\odot\) to 0.09 \(M_\odot\), according to the metallicity. On the other hand, the lower mass limit is defined by the onset of deuterium burning, i.e., about 13 \(M_J\) (Burrows et al. 2001). Due to their low luminosity, brown dwarfs can be hard to detect, particularly when they are distant from Earth. By contrast, the microlensing technique has the advantage of detecting brown dwarfs at great distances, up to the Galactic bulge, because microlensing events can be detected regardless of the brightness of the lens system.

The discoveries of brown dwarfs can provide essential information on formation theory between giant planets and stars. Presently, 19 brown dwarfs have been detected by the microlensing method. Although the sample of microlensing brown dwarfs is still small, it includes various types of brown dwarf systems, such as isolated brown dwarfs (Poindexter et al. 2005; Gould et al. 2009; Zhu et al. 2016; Chung et al. 2017), brown dwarf companions to dwarf stars (Bachelet et al. 2012; Bozza et al. 2012; Shin et al. 2012a, 2012b; Park et al. 2013, 2015; Street et al. 2013; Jung et al. 2015; Ranc et al. 2015; Shvartzvald et al. 2016a), a brown dwarf binary (Choi et al. 2013), and a brown dwarf hosting a planet (Han et al. 2013; Shvartzvald et al. 2017).

Microlensing is particularly sensitive to detecting brown dwarfs around low-mass stars. Recently, Shvartzvald et al. (2016b) presented statistical results from “second-generation” microlensing surveys by the Optical Gravitational Lensing Experiment (OGLE; Udalski et al. 2015), Microlensing Observations in Astrophysics (MOA; Bond et al. 2001), and Wise microlensing groups. They analyzed 224 microlensing events observed by all three teams during four observation seasons, and suggested that the frequency of brown dwarf companions is relatively high in microlensing events. In addition, microlensing experiments are entering a new era, with surveys, such as the Korea Microlensing Telescope Network (KMTNet), having wider fields of view and higher cadence (Kim et al. 2016). The KMTNet project was designed for the purpose of round-the-clock observing using three 1.6 m wide-field optical telescopes located in Chile, South Africa, and Australia. Hence, all microlensing events are monitored at high cadence, making it possible to densely monitor perturbations generated by brown dwarfs.

Due to the lack of discovery of brown dwarfs with respect to discoveries of planets, there is a gap in the distribution between two populations of planets and stellar binaries that is referred to as the “brown dwarf desert.” The brown dwarf desert exists over the mass–ratio range of 0.01 < q < 0.1 (Halbwachs et al. 2000; Chabrier 2003). Marcy & Butler (2000) defined the brown dwarf desert as the paucity of brown dwarf companions.
to solar-type stars at separations of <3 au. Grether & Lineweaver (2006) quantified this desert as the intersection between two diverging power-law mass functions, one for planets and one for stellar companions, both declining toward brown dwarf masses. They therefore argued that the brown dwarf desert represents incontrovertible evidence for different formation mechanisms for stars and planets. However, the limits of the brown dwarf desert in separation and as a function of host mass are currently set by observational biases. Uncovering the true nature of this desert and its boundaries provides crucial information for understanding different formation mechanisms for stars and planets.

The microlensing method is optimal for probing the nature of the brown dwarf desert at intermediate separations (1–10 au) and exploring its outer edge, if one exists. Shvartzvald et al. (2016b) suggested that the brown dwarf desert might actually reach a minimum at super-Jupiter masses for their microlensing sample, which probes companions to M dwarfs at wider separations than RV studies. However, they state that more data are needed to confirm and characterize this minimum. The stellar companion mass function in this region is well-understood (Duquennoy & Mayor 1991; Raghavan et al. 2010), but the lower-mass bound of the desert has not been determined. Microlensing can complete our understanding of the brown dwarf desert by measuring the mass function of companions in this region into the planetary regime (Gould et al. 2010; Cassan et al. 2012; Suzuki et al. 2016). As with other techniques, microlensing is even more sensitive to brown dwarfs than to planets, and Gaudi (2002) suggested that ∼25% of brown dwarf companions from 1 to 10 au should be detectable in microlensing events if they exist. To date, planets have been the focus of microlensing, but a full analysis of all two-body lens events will reveal the true extent of the brown dwarf desert and its implications for star and planet formation.

In this paper, we report the discovery of a brown dwarf located in the brown dwarf desert from data taken by the OGLE and KMTNet survey experiments. The structure of this paper is as follows. In Section 2, we describe the discovery and survey observations, and present the light curve modeling in Section 3. In Section 4, we derive the physical properties of the lens system. In Section 5, we finish with a discussion of our findings.

2. Observation

OGLE-2016-BLG-0693 was announced as a new microlensing event by the OGLE Early Warning System (EWS) on 2016 April 15 UT 20:12 (Udalski et al. 1994, 2015; Udalski 2003), and occurred on a star located toward the Galactic bulge with equatorial coordinates (α, δ)J2000 = (17h49m55.5s, 23°22′23.8″) corresponding to Galactic coordinates (l, b) = (5°548, 2°220). OGLE observed using its 1.3 m Warsaw Telescope with a 1.4 deg² camera at the Las Campanas Observatory in Chile. This event was also observed by KMTNet and MINDSTEp. In this paper, we use data based on the survey-only microlensing observations of the OGLE and KMTNet groups. KMTNet independently observed the event using three 1.6 m telescopes with 4 deg² cameras in Chile (KMT), South Africa (KMTS), and Australia (KMTA) (Kim et al. 2016).

In this study, we use the 491 OGLE data points taken over 7 years, and the data of KMTC, KMTS, and KMTA (98, 124, and 59 points, respectively). Note that we removed several outlier data points for each data set. We rescaled the photometry errors of the individual data sets in order to make χ² per degree of freedom unity for the best-fit model. In the case of the KMTNet data, the event is located in a newly added field (BLG20) with an observation cadence of ≲0.4 hr⁻¹ during 2016, and thus there are relatively few data points up to our adopted cutoff of HJD’(HJD—2450000) ~ 7568. Despite the low observation cadence, the caustic entrance was detected by KMTS. We present the light curve of the event in Figure 1. The event has a caustic crossing feature with a U-shape that is typical of binary lensing. Unfortunately, the caustic exit was not observed due to the weather conditions.

3. Binary-lens Modeling

The slope in the baseline data is clearly apparent in Figure 1. This cannot be intrinsic to the source because it would imply a period of several decades, which would be completely inconsistent with the properties of such dim stars. On the other hand, such long-term trends are a well-known artifact induced by proper motions of neighboring bright stars. Therefore, we include a linear trend in the blended flux to account for this effect.

In order to find all possible lensing models that can explain the light curve of the event, we first conduct a grid search for (s, q, α) parameters, where s is the projected separation between the companion and its host star, q is the mass ratio of the two components of the lens system, and α is the angle of the source trajectory. In addition, the four lensing parameters t₀, u₀, tₑ, and ρ are needed to fit a binary-lens light curve: t₀ and u₀ are respectively the time and separation of the source star’s approach to a reference position (for which we adopt the center of mass), tₑ is the Einstein ring crossing time corresponding to the total mass of the lens system, and ρ is the source radius normalized to the angular Einstein radius (θₑ). For a grid values of the (s, q, α) parameters, we find the best-fitting lensing model by optimizing the other parameters using the Markov Chain Monte Carlo (MCMC) approach. For the case of α, we seed it on a grid of six equally spaced starting values but then allow it to vary as a chain parameter to reduce calculation time. Since the major purpose of the grid search is to find crude solutions to use as a starting point, we use a fixed value for the baseline slope of 0.03 yr⁻¹.

In Figure 2, we present the Δχ² map for the (s, q) parameters and identify two local solutions at close (s < 1) and wide (s > 1) separations, which is the well-known close/wide binary degeneracy (Dominik 1999). In the MCMC fitting process, we calculate the finite-source lensing magnification using the inverse ray-shooting method when the source passes the caustic (Kayser et al. 1986; Schneider & Weiss 1988; Wambsganss 1997), while outside of the caustic, the magnification is calculated using the semi-analytic hexadecapole approximation (Pejcha & Heyrovský 2009; Gould 2008). We also consider the limb-darkening effect by the source star. On the surface of the source star, the brightness profile is modeled by

$$I_s(\phi) = \frac{F_0}{\rho s} \left[ 1 - \Gamma_s \left( 1 - \frac{3}{2} \cos \phi \right) \right],$$

where $F_0$ is the total flux of the source star, $\phi$ is the angle of the line of sight relative to the normal to the star’s surface, and $\Gamma$ is...
the linear limb-darkening coefficient (Albrow et al. 1999). The limb-darkening coefficient ($\Gamma_l$) is related to the linear limb-darkening coefficient $u$ of Claret (2000) as

$$\Gamma_l = \frac{2u}{3 - u}. \quad (2)$$

We adopt $\Gamma_l = 0.54$ according to the source type (see Section 4 for more details).

For each local minimum of the grid search, we perform an optimization using the MCMC fitting process by allowing the eight parameters, including the slope, to vary. In cases with long-timescale events, since the position of the observer is changed due to Earth’s orbital motion during the lensing phenomenon, the light curve is changed due to this parallax effect. Therefore, we include the parallax effect in our model, and perform the fitting of the light curve by adding two parallax parameters, $\pi_{E,N}$ and $\pi_{E,E}$, to the standard models with the slope (Gould 1992, 2004).

In Figure 3 we present the light curves and caustic structures for the best-fit parallax models at close ($s < 1$) and wide ($s > 1$) separations. The best-fitting parameters and their 1$\sigma$ uncertainties are shown in Table 1, where the error of each individual parameter is the standard deviation determined from the distribution of MCMC chains. As shown in Table 1, the lens system has a small mass ratio ($\approx 0.02$), and has an unusually long timescale $t_E$ and uncertainty compared to typical microlensing events.

Figure 4 shows that both parallax parameters are consistent with zero at the 2$\sigma$ level. It had been common practice in the past to suppress the parallax parameters in such cases on the grounds that the parallax was “not measured” to be different from zero. However, this viewpoint was not correct, as discussed in the appendix of Han et al. (2016). The key point is that $\pi_E$ is known a priori to be different from zero, so the fact that it is shown to be consistent with zero to within small errors is important information. In the present case, this parallax constraint will constrain the lens system not to be very close (and low mass). This will be combined with a flux constraint to provide reasonably strong constraints on all parameters. Hence, this “non-measurement” actually plays an important role.

The question of whether to introduce orbital motion parameters is governed by the same fundamental issues of physics as known for parallax parameters, but falls into a very different regime and therefore leads to a substantially different treatment. Just as we know a priori that all microlenses have finite (non-zero) microlens parallax, we also know that all binaries have (non-zero) orbital motion. Hence, we should in principle include such motion in the fit. We therefore begin by adding two linearized orbital motion parameters $ds/dt$ and $d\theta/dt$, i.e., the instantaneous time derivatives of the separation and orientation of the binary axis. However, we find that these parameters are quite poorly constrained, with both the best fit and the majority of the chain being in the unphysical $\beta > 1$ regime, with very modest improvement in $\chi^2$. Here, $\beta$ is the
ratio of the projected kinetic to projected potential energy (Dong et al. 2009) given by

\[ \beta = \left( \frac{KE}{PE} \right)_\perp = \frac{sM_\odot \gamma^2}{8\pi^2} \frac{\pi_E^3 \gamma^2}{\theta_E (\pi_E + \pi_S/\theta_E)^3}, \]

where \( \pi_S = \text{au}/D_S \) is the parallax of the source star at the distance \( D_S \), \( \gamma^2 = (ds/dt/s)^2 + (d\alpha/dt)^2 \), \( \kappa = (4G/c^2 \text{au}) \approx 8.14 \text{ mas yr}^{-1} \), and \( \pi_E = \sqrt{\pi_{E,N}^2 + \pi_{E,E}^2} \). We discuss the evaluation of \( \theta_E \) in Section 4.2.

Since we know a priori that \( \beta < 1 \), there is no information at all in the very mild preference of the models for large \( \beta \). Under these circumstances, one might well consider suppressing orbital motion by imposing \( ds/dt = d\alpha/dt = 0 \), i.e., simply not including these parameters in the fit.

However, in reality, all we are rigorously permitted to do by our prior knowledge is to impose the physical constraint \( \beta < 1 \). In some circumstances, this would be effectively the same as ignoring orbital motion altogether (i.e., \( ds/dt = d\alpha/dt = 0 \)).

However, as pointed out by Batista et al. (2011) and Han et al. (2016), orbital-motion parameters can be correlated with parallax parameters. Hence, they must be included with the \( \beta < 1 \) constraint.

In fact, we impose a constraint \( \beta < 0.8 \) because larger values of \( \beta \) require very unlikely physical situations observed at very special angles. We find that the parallax parameters are in this case essentially uncorrelated with the orbital motion parameters thus restricted, so the basic result derived by suppressing orbital motion remains. However, the introduction of orbital motion parameters does slightly increase the uncertainty in the parallax. Hence, in our tables, we report results derived by including orbital motion parameters but restricted to \( \beta < 0.8 \). We report the orbital motion parameters themselves in brackets because these values are not measurements, but rather simply reflect the prior constraints.

4. Physical Quantities

4.1. Overview

The total mass of lens system and its distance can be determined by

\[ M_{\text{tot}} = \frac{\theta_E}{\kappa \pi_E}; \quad D_L = \text{au} \frac{\pi_E \theta_E + \pi_S}{\pi_E \theta_E}. \]

Figure 2. \( \Delta \chi^2 \) map for \((s, q)\) parameters. The \( \Delta \chi^2 \) with \(<100, <400, <900, <1600, <2500, \) and \(<3600 \) levels are presented in red, yellow, green, light blue, blue, and purple, respectively.
solutions scale almost perfectly in \((f_s, \rho, q, u_0, 1/r_\theta)\). (Here, \(f_s\) is the OGLE source flux normalized at \(I = 18\).) Hence, almost all the information on breaking this degeneracy comes from portions of the light curve \(u \sim 1\). However, because the source is extremely faint, the fractional errors in the magnified source flux are high. In addition, because this is a relatively low-cadence field for both OGLE and KMTNet, there are relatively few data points in this part of the light curve. If the source color is well-determined, then the source size \(\theta_s = K \sqrt{f_s}\), where \(K\) is a constant that we evaluate below. Then, \(\theta_E = \theta_s/\rho = K (f_s/r_E)/\theta_s \sqrt{f_s}\). Since (from Table 1) the parameter combinations \((f_s/r_E)\) and \(t_s \equiv \rho t_E\) are relatively well constrained, this means that \(\theta_E \propto f_s^{-1/2}\). See also Yee et al. (2012).

Nevertheless, there are two major pieces of auxiliary information that can constrain the physical nature of the system in conjunction with the microlens fit. First, there is a hard limit on the flux from the lens, which (together with assumption that the host is neither a neutron star nor a black hole), leads to a limit on the lens mass. Second, the lens and source are both drawn from Galactic populations whose statistical properties are known. In order to assess the individual impact of these two pieces of “external” information, we introduce them sequentially. However, first we evaluate \(\theta_s\), or rather the constant \(K\) that relates \(\theta_s\) to the source flux \(f_s\) of an individual solution.

Figure 3. Caustic and light curve of the parallax models, with the effect of the slope. The two upper panels represent the caustic structure for the close- (left panel) and wide-separation (right panel) models. The black solid line with an arrow is the source trajectory, and the circles with various colors show the source positions corresponding to the times of observation of each observatory. The lower panel shows the light curves of the caustic crossing parts for close- and wide-separation models.
4.2. Evaluation of $\theta_0$

Because (from Table 1) $I_s$ is very poorly determined, we begin by evaluating $\theta_0$ for an arbitrarily chosen fiducial value $I_{s,\text{fid}} = 22.50$, on the scale of the OGLE-IV observations. (As we discuss below, this fiducial value is much brighter than the best-fit models in Table 1). We measure the centroid of the OGLE-IV clump to be at $I_{\text{clump}} = 16.86$. We adopt $I_{0,\text{clump}} = 14.35$ from Nataf et al. (2013) and thus derive

$$I_s = I_t + I_{0,\text{clump}} - I_{\text{clump}} = I_t - 2.51,$$

and hence $I_{s,\text{fid}} = 19.99$.

Similarly, we find the dereddened source color in $(V - I)$ from its measured offset from the clump and the Bensby et al. (2013) evaluation $(V - I)_{0,\text{clump}} = 1.06$. Unfortunately there

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**Table 1**

| Parameters | Parallax Models | Parallax+Orbital Motion Models |
|------------|----------------|--------------------------------|
| $\chi^2$/dof | $s < 1$ | $s > 1$ | $s < 1$ | $s > 1$ |
| $\chi^2$/dof | 767.217/756 | 767.304/756 | 766.769/754 | 767.126/754 |
| $\varpi_0$ (HJD) | 7497.484 ± 0.087 | 7497.559 ± 0.158 | 7497.465 ± 0.125 | 7497.561 ± 0.168 |
| $\varpi_0$ (days) | 0.011 ± 0.006 | 0.014 ± 0.010 | 0.010 ± 0.010 | 0.014 ± 0.011 |
| $\varpi_0$ (days) | 451.190 ± 136.631 | 488.108 ± 287.923 | 507.369 ± 127.955 | 556.115 ± 128.564 |
| $q$ | 0.592 ± 0.030 | 1.760 ± 0.044 | 0.582 ± 0.039 | 1.788 ± 0.044 |
| $q$ (10$^{-1}$) | 2.127 ± 0.805 | 2.077 ± 1.532 | 1.931 ± 2.61 | 1.902 ± 1.584 |
| $\rho$ (rad) | 1.562 ± 0.019 | 4.718 ± 0.022 | 1.581 ± 0.041 | 4.719 ± 0.022 |
| $\rho$ (10$^{-4}$) | 3.296 ± 1.462 | 2.987 ± 2.287 | 2.872 ± 2.726 | 2.689 ± 2.426 |
| $\varpi_{\text{N}}$ | −0.017 ± 0.125 | 0.014 ± 0.099 | 0.010 ± 0.162 | 0.003 ± 0.141 |
| $\varpi_{\text{E}}$ | 0.011 ± 0.020 | 0.012 ± 0.019 | 0.011 ± 0.027 | 0.011 ± 0.025 |
| Slope (yr$^{-1}$) | 0.038 ± 0.007 | 0.038 ± 0.008 | 0.037 ± 0.009 | 0.036 ± 0.008 |
| $ds/dt$ (yr$^{-1}$) | ... | ... | [0.259 ± 0.628] | [−0.107 ± 0.471] |
| $ds/dt$ (yr$^{-1}$) | ... | ... | [0.039 ± 0.316] | [0.091 ± 0.277] |
| $I_s$ | 23.649 ± 0.378 | 23.731 ± 0.584 | 23.812 ± 0.476 | 23.882 ± 0.433 |
| $I_s$ | 20.587 ± 0.039 | 20.584 ± 0.057 | 20.577 ± 0.068 | 20.573 ± 0.057 |
| $t_0$ (days) | 0.148 ± 0.021 | 0.146 ± 0.023 | 0.146 ± 0.025 | 0.149 ± 0.021 |
| $t_0$ (days) | 5.122 ± 0.788 | 6.812 ± 1.608 | 4.817 ± 0.809 | 7.802 ± 1.639 |
| $q_{rE}$ (days) | 9.597 ± 1.187 | 10.140 ± 0.936 | 9.799 ± 1.338 | 10.579 ± 0.935 |
| $f_0$ | 2.483 ± 0.213 | 2.491 ± 0.189 | 2.402 ± 0.218 | 2.469 ± 0.184 |

Note. HJD$^\prime$ = HJD—2450000. $ds/dt$ and $ds/dt$ cannot be regarded as “measured.” They basically reflect the physically motivated condition $\beta < 0.8$. 

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Figure 4. Contours for parallax parameters derived from MCMC fits. The red, yellow, green, and light blue colorings correspond to $\Delta \chi^2 < 1, <4, <9$, and $<16$, respectively.
are no magnified $V$ data from OGLE and only one significantly magnified $V$ point from KMT Chile (KMTC). To measure the source color we apply PyDIA (Albrow et al. 1999) to the KMTC data, which yields DIA light curves and photometry of neighboring stars on the same system. In Figure 5 we show a calibrated version of the PyDIA color–magnitude diagram (CMD), which we obtain by aligning to OGLE-III (Szymański et al. 2011). Using PyDIA reductions of these data, we find an offset $(V - I)_h = (V - I)_{0,\text{clump}} - (V - I)_{\text{clump}} = 0.29 \pm 0.10$, and hence

$$(V - I)_{0,0} = (V - I)_h = (V - I)_{0,\text{clump}} = 1.35 \pm 0.10.$$  

Finally, we apply the $VIK$ color–color relations of Bessell & Brett (1988) and the color/surface-brightness relations of Kervella et al. (2004) to obtain

$$
\theta_\mu = (0.605 \pm 0.024) \mu\text{as} \times 10^{-0.2((V - I)_h - (V - I)_{0,\text{clump}})}
= (0.605 \pm 0.024) \mu\text{as} \times 10^{-0.2(0.29 - 22.50)}.
$$  

We note that a typical main-sequence star with $(V - I)_{0,0} = 1.35$, lying at the distance of the bar toward this direction (7.4 kpc), would have a dereddened magnitude of $I_0 \sim 20.4$, a point to which we will return.

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**4.3. Constraint on Lens Light**

The “baseline object” observed by OGLE has $I_{\text{base}} = 20.53$, which $I_{\text{base}} - I_{\text{clump}} = 3.98$ mag below the clump. This is the brightness of a bulge turnoff star. Since this baseline object must contain all the light from the source and lens (as well as other possible ambient stars), we conservatively conclude that the lens mass is $M < 1.2 M_\odot$.

We then impose this constraint on the same chain that was summarized in Table 1. For each line in the chain, we take note of the values of $(I, \rho, \pi_{E,N}, \pi_{E,E})$. We evaluate $\theta_\mu$ by inserting $I_s$ into Equation (8) and then evaluate $\theta_\mu = \theta_\mu / \rho$ and $\pi_E = (\pi_{E,N}^2 + \pi_{E,E}^2)^{1/2}$. We insert $\theta_E$ and $\pi_E$ into Equation (4) and reject the link if the resulting value violates the mass constraint. Figure 6 presents the distribution of parallax parameters after the mass constraint, and Table 2 shows the resulting microlensing parameters.

Comparison of these results with Table 1 reveals several significant differences. Before commenting on these, however, it is important to note that the “conserved quantities” below the line actually change very little. As derived in Section 4.1, the fact that $(f_s f_L)$ and $t_s = (\rho f_s^2)$ are nearly invariant implies that $\theta_\mu = K (f_s f_L) / (t_s \sqrt{f_s})$ basically scales $\propto f_s^{-1/2}$. Hence, it can be well approximated by

$$M_{\text{det}} \propto f_s^{-1/2} \pi_E^{-1}. $$  

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10 We note that while DoPhot (Schechter et al. 1993) has been demonstrated by Bensby et al. (2013) to work well for sources that become bright ($I < 16$) during the event, it may work less well for faint sources.
From the first term, it follows that imposing a mass limit will tend to suppress solutions with small $f_s$ and therefore, from the approximate invariance of $(f_s t_E)$, $(q t_E)$, $t_s$, and $t_{\text{eff}}$, also suppress solutions with large $t_E$, small $q$, small $\rho$ and small $u_0$.

The differences in these parameters between Tables 1 and 2 is uniformly a factor 2.2 for $s < 1$ and 2.6 for $s > 1$. We note that although the proper motion $\mu$ is not explicitly shown in these tables, it is directly affected, $\mu = \theta_s / t_s \propto f_s^{1/2}$, i.e., pushed upward.

The second term in Equation (9) directly suppresses solutions with small $\pi_E$. Because (as is often the case) $\pi_{E,E}$ is much better constrained by the light curve than $\pi_{E,N}$, the main impact of the mass constraint is on $\pi_{E,N}$ which then becomes approximately bimodal, especially for the $s < 1$ solution. To better capture this behavior, we show in Table 2 the absolute value of $\pi_{E,N}$, rather than the parameter itself.

4.4. Galactic Model Prior

The Galactic model prior is evaluated using the method of Batista et al. (2011), and the prior distribution of the Galactic model is given by

$$P_{\text{Gal}} \propto 2R_{E,\text{rel}} \nu(x, y, z)f(\mu)g(M),$$

where $R_E$ is the physical Einstein ring radius, $v_{\text{rel}} = \mu D_L$ is the lens velocity relative to the observer-source line of sight, $\mu$ is the lens-source relative proper motion, and $\nu(x, y, z)$ is the density distribution of the lenses. We adopt the Han & Gould (2003) model, which includes the bulge model of Dwek et al. (1995) and disk model of Zheng et al. (2001). Here, $g(M)$ is the mass function, for which we adopt $g(M) \propto M^{-1}$ in common with Batista et al. (2011), and $f(\mu)$ is the probability function for the lens-source relative proper motion. Equation (10) can be

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Figure 6. Contours and histograms for parallax parameters after the mass constraint.
expressed for microlensing parameters as

\[ P_{\text{Gal}} \propto \frac{4D_L^4 \mu^4}{au_{\text{rel}}^4} \nu(x, y, z)f(\mu). \]  

We apply the Galactic model priors to each of the chain links. We show microlensing parameters after imposing these priors in Table 3.

By comparing Table 3 with 2, we can understand the impact of these priors. The main impact comes from the Jacobian in Table 3. We apply the Galactic model priors to each of the chain links.

As shown in Section 4.1, the microlensing chains have a uniform prior in \( \pi_E \), for which phase space is dominated by short \( D_L \), whereas for Euclidean geometry, phase space is dominated by large distances. This is the origin of the terms “\( D_L^4 \mu^4 \)” as discussed in Section 4.3, \( \mu \propto f_0^{1/2} \). Hence, the \( \mu^4 \) term strongly favors higher \( f_0 \), and therefore also the corresponding changes in \( \tau_E, q, \rho, u_0 \) implied by the invariant quantities at the bottoms of Tables 1–3.

The \( D_L^4 \) term works in the same direction, albeit more weakly. As shown in Section 4.1, \( \theta_E \propto f_0^{1/2} \). Hence, high \( f_0 \) leads to lower \( \theta_E \), lower \( \pi_{\text{rel}} \equiv \theta_E \pi_E \), and thus (via Equation 4) higher \( D_L \). However, this effect is somewhat “watered down” by the appearance of \( \pi_E \) in the denominator. The \( D_L \) term similarly favors solutions with smaller \( \pi_E \), as of course does the direct appearance of \( \pi_E \) in the denominator of Equation 11.

All of these effects are seen in the comparison of Table 3 with Table 2. A more detailed analysis would show that the “\( \nu(x, y, z) \)” and “\( f(\mu) \)” terms act in the same direction, but more weakly. Comparing Table 3 to Table 1, one sees that the lens-light constraint and the Galactic priors combine to greatly reduce the range of microlensing parameters.

### 4.5. Transformation from Microlensing to Physical Parameters

In Figure 7, we present the histograms for the host \( M_1 \) and companion \( M_2 \) mass, the projected separation between them \( a_\perp \), and the distance of the lens system \( D_L \). The histograms with black and red lines show the distributions of physical quantities from MCMC runs and the Galactic model prior including the host-mass cut, respectively. In Table 4, we present the physical quantities with 1 \( \sigma \) error for two parallax + orbital motion models after applying the Galactic model prior (including host-mass cut). In the case of the physical quantities obtained by applying the Galactic model prior, we mark them in brackets. The main effect of applying the priors is to shift the masses of the brown dwarf and host sharply higher and also to place the system at significantly larger distance. As discussed in Section 4.4, the primary reason for this is not the Galactic model parameters, but the Jacobian term, which in turn overwhelmingly reflects the ratio of phase space available to chain relative to the real physical phase space available to the lens.

In the present case, the mass cut (derived from the lens flux constraint) also plays a significant role. This is because the parallax measurement is consistent with zero, which means that the Jacobian itself tends to be unrestricted in its “preference” for high-mass solutions. However, just as the microlens parallax cannot actually be zero, it also cannot be so small as to imply a huge lens mass, even though this is not ruled out by the MCMC chain itself.

Based on the results summarized in Table 4 and Figure 7, OGLE-2016-BLG-0693LB is well constrained to be a brown dwarf in either the close \( (s < 1) \) or wide \( (s > 1) \) solutions, which are fully degenerate (see first row of Table 1). Its host is almost certainly an FGK star, i.e., the traditional targets of RV surveys on which the brown dwarf desert was originally defined by Marcy & Butler (2000), although there is a small probability that the host is an early M dwarf. The original definition of the “brown dwarf desert” \( (a < 3 \text{ au}) \) was set by observational limits of RV surveys at that time. In the close solution, OGLE-2016-BLG-0693LB is within the brown dwarf desert according to this restrictive definition. In the wide solution, it lies at or somewhat beyond its outer edge. This
The model proper motions ($\mu = 1.7 \pm 0.4$ and $\mu = 1.4 \pm 0.2$) at first sight appear more problematic given that the lens is in the disk and the source is (at least assumed to be) in the bulge. This is because, if we ignore the peculiar motions of the observer, lens, and source, and if we assume a flat rotation curve and also assume zero bulk motion for the bulge, then the expected proper motion is just $\mu = v_{\text{rot}}/D_5 = 6.3$ mas yr$^{-1}$, where we have adopted $v_{\text{rot}} = 220$ km s$^{-1}$ and $D_5 = 7.4$ kpc. Then, it would appear to require some fine-tuning to “arrange” for the peculiar motions to almost perfectly cancel out this mean motion in order to yield $\mu \sim 1.5$ mas yr$^{-1}$.

However, the Galactic longitude of this event is unusually high, $l = 5^\circ.5$. The Galactic bar is certainly rotating. The exact Galactic prior does have a strong $\mu$ dependence, but this is overwhelmingly due to the Jacobian term $\mu^A$ and is only weakly responsive to the Galactic-model assumption $f(\mu)$. Therefore, we can ask whether the final values of these quantities are consistent with what is expected given our knowledge of the Galaxy, as external checks on the solution.

The best-fit source magnitudes in the $s < 1$ and $s > 1$ solutions are $I_1 = 22.3 \pm 0.4$ and $I_2 = 22.5 \pm 0.3$, respectively. Recall from Section 4.2 that the expected value for a typical star of the source’s color and lying in Galactic bar would be $I_1 = 22.9$. Since variations in depth within the bar and source-star metallicity could cause this to vary by $\pm 0.3$ mag, either of these models is consistent with expectations at the $1\sigma$ level.

Figure 7. Histograms for physical quantities of the lens. The histograms with the black line represent the uncertainties of physical quantities from the MCMC runs, and the histograms with the red line show that after applying the Galactic model prior (including the lens-mass cut $M < 1.2 M_\odot$; gray dashed line). The large offsets between the black and red histograms are overwhelmingly due to the Jacobian term, which is the ratio of phase space available to the lens relative to that available to the MCMC chain. See the text.

4.6. Two Consistency Checks

The solutions derived in Tables 3 and 4 did not depend in any way on the source magnitude being “reasonable” given its color and only very weak prior information on the lens-source relative proper motion $\mu$. That is, as we noted in Section 4.4, detection therefore illustrates the prospects for microlensing to probe the outer edges of the brown dwarf desert, where it is sensitive to both brown dwarfs and massive planets, and can thus determine whether the brown dwarfs remain a minimum in the companion mass function as they approach closer separations.
angular speed is not precisely known, but we can plausibly adopt 100 km s\(^{-1}\) kpc\(^{-1}\). Then, the mean motion projected on the plane of the sky at the source position is \(\sim 100 \text{ km s}^{-1}\). For the geometry of this event (and now taking account of the solar peculiar motion) the mean proper motion is \(\mathbf{\mu} = (3.0, 0.0) \text{ mas yr}^{-1}\) in Galactic \((l, b)\) coordinates. Note that in Equatorial coordinates, this direction is about 30° east of north, which is very similar to the direction of \(\mathbf{\mu}_G\) (i.e., the same as \(\mu\)). Given this mean motion, the observed proper motion is not at all unexpected.

Finally, we recall that \(t_{\text{s}} \approx 3.6 \text{ hr}\) is a near-invariant, i.e., it is a nearly model-independent property of the light curve. This long duration was actually essential to the publication of this paper. Recall that the event lies in a field with KMT cadence \(\Gamma = 0.4 \text{ hr}^{-1}\). It was only this long \(t_{\text{s}}\) that permitted accurate measurement of the caustic crossing time. Even with the long \(t_{\text{s}}\), there were only two data points over the caustic, which is the minimum for a reliable measurement. However, given that the majority of microlensing sources are main-sequence stars (include the source star in the present case), such a long \(t_{\text{s}} = \theta_0/\mu\) is only possible if the proper motion is small.

## 5. Conclusion

The event of OGLE-2016-BLG-0693 was discovered based on the survey-only microlensing observations of the OGLE and KMTNet groups. Although the event lies in a relatively low-cadence KMTNet field (0.4 hr\(^{-1}\)), the caustic crossing part was observed by KMTS. This became possible because the source crossing time was exceptionally long (given that the source is a dwarf), \(t_{\text{s}} = 3.6 \text{ hr}\), which permitted two flux measurements over the caustic crossing. The long crossing time was in turn due to a proper motion, \(\mu = 1.55 \pm 0.3 \text{ mas yr}^{-1}\), that is much lower than is typical for most microlensing events, but not unexpected for events seen at high positive Galactic longitude (5°.5) on the near side of the Galactic bar.

In the analysis of the event, we considered the effect of parallax according to Earth’s orbital motion during the lensing phenomenon because the event has an unusually long timescale (which is another consequence of its unusually low proper motion). In addition, we took the effects of the baseline slope into account. We conducted the analysis of the light curve for two microlensing models with close and wide separation, respectively.

After applying a Galactic model prior and a lens-mass upper limit (due to limits on lens light), we found that the lens system is composed of a low-mass brown dwarf (\(49_{-20}^{+28} M_J\)) orbiting a K or G dwarf. Finally, we note that the separation of the brown dwarf is less than \(\sim 5\text{ au}\), demonstrating that microlensing is poised to probe the brown dwarf desert at intermediate separations.

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