ForensicTransfer: Weakly-supervised Domain Adaptation for Forgery Detection

Davide Cozzolino¹ Justus Thies² Andreas Rössler² Christian Riess³
Matthias Nießner² Luisa Verdoliva¹

¹University Federico II of Naples ²Technical University of Munich ³University of Erlangen-Nuremberg

Abstract

Distinguishing manipulated from real images is becoming increasingly difficult as new sophisticated image forgery approaches come out by the day. Naïve classification approaches based on Convolutional Neural Networks (CNNs) show excellent performance in detecting image manipulations when they are trained on a specific forgery method. However, on examples from unseen manipulation approaches, their performance drops significantly. To address this limitation in transferability, we introduce ForensicTransfer (FT). We devise a learning-based forensic detector which adapts well to new domains, i.e., novel manipulation methods and can handle scenarios where only a handful of fake examples are available during training. To this end, we learn a forensic embedding based on a novel autoencoder-based architecture that can be used to distinguish between real and fake imagery. The learned embedding acts as a form of anomaly detector; namely, an image manipulated from an unseen method will be detected as fake provided it maps sufficiently far away from the cluster of real images. Comparing to prior works, FT shows significant improvements in transferability, which we demonstrate in a series of experiments on cutting-edge benchmarks. For instance, on unseen examples, we achieve up to 85% in terms of accuracy, and with only a handful of seen examples, our performance already reaches around 95%.

1. Introduction

Image manipulation is as old as photography itself [16]; however, with recent advances in machine learning and synthetic image rendering, it has reached unprecedented levels of diffusion and sophistication. Manipulations that were once possible only for high-budget movie productions are now within the reach of anyone who can access large amounts of data — a democratization of high quality image and video synthesis. This development is the outcome of intense research in computer vision, driven by market demands in the movie industry, photography, virtual reality, game playing, and autonomous driving. A major focus of research has been face synthesis and manipulation. Nowadays, we can generate entirely synthetic faces [10, 28], even at very high-resolutions [25, 26], animate a subject’s face to make it express the desired emotions [5, 37], or modify facial expressions [47, 45, 27]. Beyond faces, a number of generic image manipulation methods have been proposed. It is now possible to transfer semantic content from a source domain to a target domain characterized by a different style [56, 26], create automatically image compositions [57], and reconstruct missing image parts by semantic inpainting [30, 24].

It is worth noting that most of these operations can be carried out using several editing tools (e.g., Photoshop, GIMP), and with some manual effort achieve highly convincing results. Although these processing tools were originally designed for benign applications, they can also be used to perform high-quality image forgeries. Realistic fake content can have a high impact on people’s lives, as demonstrated by
the Deepfake app [1]. They can be used to support fake news, and cause their viral spread over ubiquitous social networks. Therefore, it is critical to develop methods that allow the reliable detection of such manipulations, and there has been growing attention towards this goal in the research community.

Deep neural networks have proven to be very effective for this task and several works can be found in the current literature [7, 12, 38, 40, 3]. These methods heavily rely on a sufficient number of training examples and the performance impairs dramatically when new types of manipulations are presented, even though they are semantically close. The underlying neural networks quickly overfit to manipulation-specific artifacts, thus learning features that are highly discriminatory for the given task but severely lack transferability. This weakness can be partially addressed by fine-tuning a pre-trained network with new task-specific data, but this means that large amounts of new data are necessary.

Due to the high dynamics in the field of digital content synthesis this is not feasible and introduces a huge time delay for every new method that has to be debunked. Ideally, one would like to detect a forgery even if the network has not been trained for it, or if only a few labeled examples are available. The goal of this work is to develop a CNN-based method that ensures such generalization; i.e., being able to transfer knowledge between different but related manipulations. Specifically, we suppose to have a network trained to detect a specific manipulation and want to extend its capability to similar ones. To the best of our knowledge, this is the first work addressing this problem in the context of multimedia forensics. To this end, we make the following contributions:

- a novel autoencoder-based neural network architecture, that learns a model for a derived forensic embedding, capable of transferring between different manipulation domains,
- a thorough ablation study of our proposed method, including a survey on existing baseline methods,
- and state-of-the-art detection accuracies that enable robust forgery detection even when no or only a handful of training samples of a new manipulation are available.

2. Related work

While the main focus of our work lies in the field of media forensics, ForensicTransfer also intersects with the field of transfer learning. There is a wide range of image forgery detection methods. These methods can be divided into traditional model-based and learning-based approaches.

Traditional Media Forensics Traditional model-based approaches exploit a specific clue, like inconsistencies at pixel-level related for example to JPEG compression artifacts [4], demosaicking clues [17], lens aberration [51], or camera noise [34]. They are very effective, but also very sensitive to the assumed hypotheses. Robustness is much more ensured by physics-based approaches that rely on inconsistencies in illumination or perspective mappings [15]; however, they are still not able to provide a performance comparable to pixel-based methods in realistic situations.

Learned Media Forensics Recently, the research community has shown that supervised deep learning approaches can achieve impressive detection results. Similar to the traditional media forensics, the first approaches concentrated on the high-frequency pixel-level signals. This can be accomplished by adding a first layer of fixed high-pass filters [39, 32], learned filters [7], or even by recasting hand-crafted features working on residuals as a convolutional neural network (CNN) [12]. Two-stream networks are used to exploit both low-level and high-level features [55]. Other architectures try to exploit sharp discontinuities created by the editing process, such as the boundary artifacts occurring when an object is spliced into the image [42, 6].

A significant performance gap can be observed by very deep networks, especially, on compressed data [40], which is critical to detect fake content on social networks. All proposed learning-based methods need some form of finetuning on a dataset that comprises manipulations aligned with the ones present in the test set. But often the underlying datasets are limited and prone to polarization, e.g., when a limited number of cameras is used. To avoid any form of polarization on the training-set, recent approaches have adopted Siamese networks to train couples of patches [23, 13]. This way, they do not need to rely on a specific training set, since they are acting as anomaly detectors on a pixel-level basis. Hence, their performance is much more effective on localization than on detection.

Recently, there are has been some effort in the detection of more recent manipulations that have been created using deep learning (i.e. deepfakes). Some papers have focused their effort in the detection of manipulations on faces [3, 20] or GAN generated images [35, 53]. In contrast to these methods, we are not restricted to a specific type of manipulation and only need a few samples to adapt to new manipulations.

Transfer learning Transfer learning is an important problem in the vision community, especially, in deep learning which relies on a large amount of training data compared to traditional machine learning approaches. When the distributions of training and test data do not match (domain shift), the network has to be re-trained on a large labeled dataset, and this is not easily feasible. In the literature several solutions have been proposed to adapt the source domain to the target domain in different scenarios [14, 21, 49]. A possible
direction is to use an autoencoder to learn a latent embedding in the source domain from which the feature space in the target domain is derived \([19, 8]\). This is as also carried out in \([29]\) to learn a better semantic representation in the \textit{Zero Shot Learning} scenario.

The \textit{Few Shot Learning} scenario is particularly interesting in our context, since it helps learning generalization using a limited amount of labeled examples. \textit{ForensicTransfer} is designed for the forensic analysis of imagery, i.e., we are interested in two classes – pristine vs forged images. This restriction is different to the traditional setting in the computer vision community which focuses on a large number of classes, resulting in approaches that aim at learning good model initialization, learning image similarity or learning to augment data through a proper generator \([9]\).

3. Proposed Method

We propose a new CNN-based image manipulation detector which provides state-of-the-art performance on known manipulations \textit{and} generalizes well to new forms of manipulations. \textit{ForensicTransfer}: \textit{i)} provides the same excellent performance as other deep nets over known manipulations, when plenty of labeled examples are available, \textit{ii)} generalizes better than these competitors to unseen manipulations \textit{(zero-shot performance)}, and \textit{iii)} improves effectively its performance for new manipulations based on a very small number of training examples \textit{(few-shot performance)}.

Our approach disentangles the information necessary to make the real/fake decision in the source domain from a faithful latent-space representation of the image, which may be exploited in new target domains. To prevent the net from discarding precious information during training, we rely on autoencoder-based representation learning \([48]\) by which the latent space is constrained to preserve all the data necessary to reconstruct the image in compact form.

Therefore, the latent space holds both the image representation and the data used for the real/fake decision, but these pieces of information live in orthogonal spaces, and do not interfere with one another. This is obtained by dividing the latent space in two parts, one activated exclusively by real samples, and the other by fake samples. Since the network has to reproduce the image anyway, all relevant information on the input image is stored in both parts. Thus, the features of the learned forensic embedding keep all desired information, useful for diverse forensic tasks, and easily adapted to new domains based on a small number of new training samples.

\textbf{Forensic Embedding:} Initially, we assume to have only training data for the source domain, formed by the set \(S_1 = \{x_i^1\}_{i=1}^N\), comprising images tampered by the known manipulation, and the set \(S_0 = \{x_i^0\}_{i=1}^N\) of the correspond-

![Figure 2: ForensicTransfer scheme. (1) We train our autoencoder-based approach on a source domain, disentangling the fake and real images in the latent space. (2) Using few target training samples one can adapt to the target domain. (3) The latent space is used to predict the class.](image-url)

\textbf{Loss:} During the training phase, we enforce a reconstruction loss \(L_{REC}\) on the output image of the autoencoder and an activation loss \(L_{ACT}\) on the latent space:

\[
L = \gamma \cdot L_{REC} + L_{ACT},
\]
where $\gamma$ weights the influence of the reconstruction error, and is set to 0.1 for all our experiments. The reconstruction loss $L_{REC}$ measures the difference of the input image $x$ and the reconstructed image $\hat{x}$ which is given by $D(E(x))$ using an $\ell_1$-norm:

$$L_{REC} = \frac{1}{K} \sum_{x \in S_0 \cup S_1} \|x - \hat{x}\|_1,$$

where $K$ is the number of components of the input sample. The reconstruction constraint forces the net to store all relevant data of the input in the latent vector. Hence, we avoid to encode only the information directly useful for discriminating the source manipulation, allowing adaptation to novel manipulations. The activation loss $L_{ACT}$ is defined as:

$$L_{ACT} = \sum_{x \in S_0} |a_0(x) - 1| + |a_1(x)| + \sum_{x \in S_1} |a_1(x) - 1| + |a_0(x)|$$

At test time, the decision on the presence of a forgery relies on the strength of the activations. A sample $x$ is considered to be forged ($c = 1$) if $a_1(x) > a_0(x)$, and real otherwise. Unlike the widespread classification loss based on cross-entropy, the proposed loss does not only force the separation of the two classes, but also the reduction of the intra-class variances, which improves transferability in our forensic application. As a consequence, an unseen novel manipulation can be more easily distinguished from the class of real images. In the literature, the importance of reducing intra-class variances has been demonstrated in [22] for transfer learning and in [9] for few-shot problems.

**Transferability:** Based on strength of the activations, we are able to decide whether the input image is closer to the real or to the forged images of the source domain. Having to deal with a novel manipulation, where only a few examples are available, we exploit a detector already trained on a “close” manipulation, which can be assumed to share some artifacts with the new one. Therefore, we fine-tune this detector to the target domain using the available examples in $T_1$ and $T_0$ and the loss $L$.

**Network architecture** In this work we consider the encoder-decoder architecture shown in Fig. 3. Input images have size $256 \times 256 \times 3$ or $128 \times 128 \times 3$ pixels, depending on the dataset (see Sec. 5). The encoder and decoder have mirrored structures, with 5 convolutional layers with a $3 \times 3$ kernel each, and without skip connections. In the encoder, all convolutions, except the first one, have stride 2, thus reducing spatial resolution by a factor 16 overall. To recover the original size, the decoder employs a $2 \times 2$ nearest-neighbor up-sampling before each convolution except the last one. All activation functions are ReLUs (Rectified Linear Units) except for the hyperbolic tangent activation used in the last layer to ensure the output to be in a pre-defined limited range. The latent space at the encoder output, comprises 128 feature maps, 64 associated with the class “real” and 64 with the class “fake”. The selection block sets the off-class part of latent space to zero, depending on the class label, forcing the decoder to learn how to reconstruct the input sample only from the same-class part of the latent space.

**Training** To evaluate its generalization capability, the network is first trained on a dataset built w.r.t. a specific manipulation method (source domain). Then, it is fine-tuned on a few images subject to a different, but similar, form of manipulation (target domain). The fine-tuning procedure allows the detection network to quickly adapt to the new manipulation scenario, without the need to be re-trained.

For training, we use the ADAM gradient-based optimization scheme with a learning rate of 0.001, a batch-size of 64 and default values for the moments ($\beta_1 = 0.9, \beta_2 = 0.999$ and epsilon $= 10^{-7}$). We train the network until the loss, evaluated on the validation, does not improve for 30 consecutive epochs.
4. Datasets

In our experiments we focus on manipulations performed by computer graphics (CG) or deep learning methods, which may involve parts of real images (for example, changes only in the mouth) or the generation of whole synthetic images (see Fig. 4). In all cases, we used large datasets for the source domain and split each dataset in training, validation and test. The few examples of the target dataset, used for fine-tuning, are randomly extracted from the training and validation sets. Note that we took care to pair two different but related manipulations in all our experiments for the source and target dataset. In the following we describe each dataset. For easy reproducibility of our results, we will publish our new datasets of synthetic and inpainted images.

Synthetic images: Because of the lack of publicly available dataset for forensic research purposes, we built 5 datasets of 30000 images each comprising images generated using progressive GAN [25], Cycle-GAN [56], Style-GAN [26], Glow [28], and StarGAN [10]. Progressive GAN and Style-GAN generate high resolution faces, Cycle-GAN performs image-to-image translation, and the last two methods change attributes of a face. Except for the high resolution images of dimension $1024 \times 1024$, all the other output images are $256 \times 256$ pixels. The total number of 30000 images per manipulation method is split into 21000, 6000 and 3000 image set for training, validation and test, respectively. For our test we used the progressive GAN, Cycle-GAN and StarGAN images as the source datasets while Cycle-GAN, Style-GAN and Glow are chosen to be the target datasets, respectively. Real faces come from CelebA-HQ dataset [25] for ProGAN and StyleGAN, CelebA dataset [33] for StarGAN and Glow, and from [56] for Cycle-GAN.

Inpainted images: We built another two datasets of 20000 images each using inpainting-based manipulation methods. To this end, we created a source database using the method of Iizuka et al. [24] and a target database using Yu et al. [52]. The inpainting is applied to the central $128 \times 128$-pixel region of the image. Since only the central region is manipulated, we considered only this part as the input for the networks. The set of 20000 images are split into 14000, 3000, 3000 images for training, validation and test, respectively. Original images come from ImageNet [41].

CG-based manipulated faces: We are using the public dataset FaceForensics, proposed in [40], with 1004 real videos and 1004 fake ones manipulated by Face2Face [47]. We used the same original videos to create another dataset of manipulated videos using FaceSwap [2]. The Face2Face generated images are used as the source dataset and the FaceSwap manipulation as the target dataset. The 1004 videos are divided into 704 for training, 150 for validation and 150 for testing. All videos have been compressed using H.264 with quantization parameter set to 23. During the training we used 200 frames from each video, while the testing is performed on ten frames per video. For each frame, we cropped all images to be centered around the face.

5. Results

In this section we give a thorough analysis of our approach. We show the impact of the design choices (see Sec. 5.1), and show state-of-the-art detection results in comparison to forensic approaches and few-shot learning methods (see Sec. 5.2 and supplemental document). We also analyze the influence of having multiple source domains on the detectability of fakes in a target domain (see Sec. 5.3).

5.1. Ablation study

As an ablation study, we compare the performance of the proposed method with four variants obtained by modifying
only a specific key aspect. In the no-residual variant, we remove the preliminary high-pass filter, thus working on natural images rather than residuals. In the no-reconstruction variant we remove the constraint on image reconstruction by setting $\gamma = 0$, which amounts to canceling the term $L_{REC}$ from the overall loss. In the cross-entropy variant, the proposed $L_{ACT}$ loss is replaced by a softmax/cross-entropy loss. Finally, in the large-margin variant, the proposed $L_{ACT}$ loss is replaced by a Large-Margin softmax loss [31]. In Fig. 5 we report the accuracy as a function of the number of target samples used for adaptation (shots), considering only two datasets pairings for brevity, Inpainting (left) and Pro/Cycle-GAN (right). In both cases, results fully support our choices. During fine-tuning, we also use a small validation set equal to three-fifths of the small training set. The no-residual version exhibits a dramatic impairment, with the performance gap closing only after 100 or more examples, thus proving the importance of focusing right-away on precious high-pass details. A similar behavior is observed for the cross-entropy version and the large-margin variant, confirming the soundness of the proposed $L_{ACT}$ loss. Instead, the reconstruction constraint has only a minor impact on the second pairing, but grants a significant improvement on the first one, with a 15% initial gain which reduces only slowly with new examples. With both dataset pairings, the proposed methods reaches accuracies above 90% within five shots.

Fig. 6 shows the scatter plots of the two activations, $a_0(x)$ and $a_1(x)$, for a number of test images, both real (green) and fake (red), of the Inpainting pairing. The first plot on the left shows that the two activations allow a reliable classification of source-domain images. On target-domain images (second column) the very same classifier fails to detect a good part of the fakes, never seen before. However, a single-shot adaptation (third column) allows a reasonable separation of the two classes, which becomes already quite good when using 10 samples, and nearly perfect at 100. On the second row, we
|                          | Pro/Cycle | Cycle/Style | Star/Glow | Inpainting | Face2/Swap |
|--------------------------|-----------|-------------|-----------|------------|------------|
|                          | S         | T           | S         | T           | S         | T         | S         | T         |
| Bayar                    | 99.92     | 50.42       | 98.92     | 55.93      | 99.98     | 50.00     | 99.08     | 50.10     |
| Cozzolino                | 99.92     | 52.43       | 99.92     | 49.98      | 100.00    | 50.00     | 98.12     | 63.33     |
| Rahmouni                 | 100.00    | 49.87       | 98.85     | 62.52      | 100.00    | 50.00     | 95.35     | 52.02     |
| MesoInc.                 | 97.47     | 44.19       | 87.98     | 50.30      | 100.00    | 50.00     | 87.65     | 45.17     |
| Xception                 | 100.00    | 58.79       | 99.92     | 50.08      | 100.00    | 50.00     | 99.98     | 51.08     |
| FT (ours)                | 100.00    | 85.00       | 100.00    | 90.53      | 100.00    | 82.05     | 99.77     | 70.62     |

Table 1: Accuracy on the Source dataset and Target dataset. All the methods perform very well on the manipulations seen in the training set and much worse on new ones.

|                          | Accuracy on CycleGAN |
|--------------------------|----------------------|
| one-to-one (Pro.GAN)     | 85.00                |
| one-to-one (StarGAN)     | 77.26                |
| one-to-one (Glow)        | 83.67                |
| multi-to-one (StarGAN+Glow) | 92.32              |

Table 2: Our approach enables the transfer of detection abilities from multiple source domains to a target domain. We show zero-shot results using our approach based on a one-to-one transfer in comparison to a multi-to-one transfer.

Figure 7: Few-shot adaptation. Plots show accuracy versus number of images used for fine-tuning (shots). Values are averaged over 10 runs. Note the zero and few-shot transferability of ForensicTransfer (FT, red curves).
show the same scatter plots when the proposed activation is replaced by the softmax/cross-entropy loss. Source-domain performance is as good as before, but results on the target domain are much worse in comparison to our approach. While L1 forces the activations to a specific value, the cross-entropy loss tries to push samples far from the separating hyper-plane irrespectively of the intra-class variance. The low variance gives an advantage when considering the target domain. As a result, the distribution of the novel manipulation is more easily distinguishable from the concentrated distribution of real images.

5.2. Comparison with state-of-the-art

In this section we are comparing our method to several state-of-the-art CNN-based detection methods. Baryar16 [7] and Cozzolino17 [12] have been proposed to detect generic manipulations based on a constrained network. Rahmouni17 [38] detects computer-generated images, while MesoInception-4 was proposed [3] for deepfake detection. We are also considering a general-purpose state-of-the-art deep network, XceptionNet [11], given the excellent performance shown in [40] for facial manipulation detection. To ensure fairness, all methods are trained exactly on the same dataset as specified in the previous Section. When necessary, images have been rescaled [11, 3] or clipped [7, 12, 38], to match the size of the network input layer as specified in the original papers.

Generalization analysis: First of all, we evaluate the ability of each network to detect a manipulation performed with the same method seen in the training set (source) and with a different method (target) without any form of fine-tuning. This experiment is important to understand the intrinsic transferability of a network. We paired the datasets described in Sec. 4 to consider similar types of manipulations. Results are reported in Tab. 1. On the source domain, all methods, including the proposed ones, perform very well, with accuracies close to 100%, which lower only on the video datasets, where frames are subject to much stronger compression than images of the other datasets. When evaluating the trained networks on the respective target domain, we observe a dramatic performance loss for all reference methods, most of which provide accuracies close to 50%. Partial exceptions are represented by Cozzolino17, on the inpainting and video datasets, and Rahmouni17, only on videos. ForensicTransfer also shows a performance impairment; however, the residual-based network maintains good performance; e.g., 90% accuracy from Cycle [56] to Style-GAN [26].

Adaptation analysis: In Fig. 7(a-e) we show accuracies as a function of the number of target-domain training samples. Curves start from zero-shot values as discussed in the generalization paragraph. For all reference methods, the accuracy grows quite slowly with fine-tuning and in many cases remains largely below 100% even at 100 training images. ForensicTransfer, instead, reaches a very high accuracy with just a few shots, and outperforms all competitors with a large margin. On Pro/Cycle-GAN (Fig. 7(a)), the accuracy exceeds 90% at 4 shots, and reaches 100% before 100 sample images. Also on Cycle-GAN/StyleGAN (Fig. 7(b)) results are very good, which shows ForensicTransfer is able to transfer knowledge also from medium-quality to high-quality generation domains. On StarGAN/Glow (Fig. 7(c)) results are impressive and one shot is already enough. On Inpainting (Fig. 7(d)), the 90% mark is reached with two shots, and almost 100% using 100 training images. Only for the more challenging Face2Face/Swap experiment (Fig. 7(e)), a slower growth and a smaller gain is observed, with XceptionNet almost closing the gap at 100 shots, both with accuracy exceeding 90%.

5.3. Multi-source experiments

In the previous experiments we are showing examples of a one-to-one transferability of forgery detection. Given multiple source domains, we can extend this idea to a many-to-one transfer of knowledge. To this end, we train the proposed network on a dataset of multiple sources. Specifically, we use the following methods for our experiment. As source domain we generate images using StarGAN [10] and Glow [28]. The target domain images are synthesized by a CycleGAN [56]. Based on the images of the two source domains, we train the encoder-decoder network, disentangling the knowledge about real and fake images. In Tab. 2 we show the zero-shot results in comparison to a one-to-one transfer. The multi-source training improves the detection accuracy of unknown forgeries in the target domain by at least 7%. In Fig. 7(f), we compare the few-shot adaptation w.r.t. the baseline methods. All methods are trained on both source domains. As can be seen our approach behaves similarly to the one-to-one experiments. Our approach outperforms all baselines by more than 25% when there are less than 5 target domain samples available.

6. Conclusion

We introduce ForensicTransfer a new method to facilitate transferability between image manipulation domains. Specifically, we address the shortcomings of convolutional neural networks, that when trained for a given manipulation approach, are unable to achieve good detection results on different edits – even when they are related. In comparison to traditional learning techniques, we can achieve significantly higher detection rates in cases where no or only a few training samples are available in the target domain. Overall, we believe that our method is a stepping stone towards forgery detectors that only need a few training samples of the target domain.
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Supplemental Material

Given a database of manipulated images from a source domain, we are able to detect fakes generated with a different manipulation method (target domain). In this supplemental document, we show, through visualization of the class activation maps, the transferability of our proposal respect to the use of a classic classifier (Sec. D), then we report additional ablation studies (Sec. A) as well as a comparison to few-shot learning methods (see Sec. B). For reproducibility, we report the hyperparameter of the used baseline methods from the main paper (see Sec. C).

A. Ablation studies

In Fig. 8 we show an ablation study with respect to the dimension of the forensic embedding. The results reported in the main paper are based on a forensic embedding of size 128, where we are using 64 to encode pristine and another 64 to encode manipulated images. In this experiment, we reduce and increase the number of features in the latent space. Tab. 3 shows the zero-shot performance for a one-to-one transfer on the inpainting dataset (Iizuka et al. [24] as source and Yu et al. [32] as target domain). As can be seen the dimensionality has an influence on the performance and 128 is the sweet spot with the best performance. With a lower or higher dimensionality of the feature space, the transferability performance decreases, but it is still better or comparable with respect to the baseline methods.

The few-shot adaptation experiment in Fig. 8 shows that the performance of the 128 long feature space is consistently better than the other configurations while they converge with the number of samples from the target domain.

B. Comparison to few-shot learning methods

Few-shot learning is a relevant problem in many computer vision applications and several methods have been proposed especially with reference to image classification. In this section, we describe briefly some of such methods and discuss their performance when applied in our scenario.

Chen19 [9] proposes an approach where a feature extractor is followed by a classifier. The whole network is trained on the source dataset, then the feature extractor is frozen, and only the classifier is fine-tuned on new examples from the target domain. A ResNet-18 is used for feature extraction, while classification is carried out by a cosine similarity layer, which helps reducing intra-class variances [18].

FADA [36] resorts to adversarial learning to find a feature space where the distributions of source and target samples are aligned, ensuring reliable classification in both domains. As proposed in the reference paper, we use a VGG-16 net for feature extraction, a fully connected layer for classification, and a network of 2 fully connected layers for the discriminator used in adversarial learning.

MatchingNet [50], ProtoNet [43], and RelationNet [44] are similar few-shot learning methods, based on the use of suitable distance metrics. A network is first used to extract feature vectors, and then a suitable distance metric is computed to make predictions, by comparing the input with a small support set of labeled examples. MatchingNet uses the cosine similarity, ProtoNet the Euclidean distance with respect to class-mean representation, and RelationNet relies on an appropriately trained CNN. As feature extractor we use always a ResNet-18, which was proven in [9] to work well for all these methods. Then, we train the comparison model in the source domain, and test it using the few examples of the target domain as support set.

When used for few-shot learning on the Inpainting dataset pairing, all these methods exhibit a disappointing performance, with accuracy close to 50% and only slowly growing with the number of examples. In addition, they are generally much slower than ForensicTransfer, especially FADA due to the adversarial learning. However, it is worth underlining that all these methods were originally devised for problems like image classification that presents a large number of classes. Hence, using them in our two-class context may prove sub-optimal.

C. Baseline methods

For the forensic baseline methods used in the main paper, we use the Adam optimizer with the default values for the moments ($\beta_1 = 0.9$, $\beta_2 = 0.999$) and different parameters

| $d$  | 32   | 64   | 128  | 256  | 512  |
|------|------|------|------|------|------|
| Accuracy | 56.32 | 64.60 | **70.62** | 62.17 | 59.75 |

Table 3: Here, we show an ablation study regarding the dimension of the forensic embedding. The results are based on a zero-shot transfer scenario on the inpainting dataset.

Figure 8: In this graph, we show the few-shot adaptation abilities with different dimensions of the forensic embedding. Plots show accuracy versus number of images used for fine-tuning (shots). Values are averaged over 10 runs.
Figure 10: Two examples of images manipulated with Face2Face [47] and FaceSwap [2] (left) and their corresponding class activation maps, when the network (XceptionNet [11]) is trained on Face2Face forgeries (middle) and when it is trained on FaceSwap ones (right).

Bayar16 [7]: is a constrained network that uses a convolutional layer designed to suppress the high-level content of the image (total of 8 layers). The used learning-rate is $10^{-5}$ with batch-size 64.

Cozzolino17 [12]: is a CNN-based network that rebuilds hand-crafted features used in the forensic community. We adopt a learning-rate of $10^{-5}$ and a batch-size of 16.

Rahmouni17 [38]: integrates the computation of statistical feature extraction within a CNN framework. We adopt the best performing network (Stats-2L) with a learning-rate equal to $10^{-4}$ and a batch-size of 64.

MesoInception-4 [3]: is a CNN-based network proposed to detect DeepFakes. The network includes inception modules inspired by InceptionNet [46]. During training, the mean squared error between true and predicted labels is used as loss instead of the classic cross-entropy loss. As proposed by the authors, the learning-rate is initially $10^{-3}$ and is reduced by a factor of ten for each 1000 iterations. The used batch-size is 76.

XceptionNet [11]: is based on depth-wise separable convolution layers with residual connections. XceptionNet is pre-trained on ImageNet. We adopt a learning-rate of $10^{-3}$ and a batch-size of 64.

The training for all methods process is stopped when the validation accuracy does not improve for 10 consecutive epochs and we save the network weights relative to the best validation accuracy.

D. Activation maps

In this section we want to carry out a further experiment to gain better insights on the ability of our proposal to transfer to different but closely related manipulations with respect to existing CNN-based detectors. To showcase this problem, we trained XceptionNet [11] on images generated by Face2Face [47], which achieves an accuracy of 98.13%. A similar performance is achieved when the network is trained to detect images generated by FaceSwap [2], achieving an accuracy of 98.30%. In Fig. 10, we show two examples of class activation maps (CAMs), obtained using the approach proposed by [54], for the same subject manipulated with the two approaches. They clearly show that the network learns to focus on some specific features based on the type of forgery. As an undesired consequence, a forged image which lacks these artifacts may escape the detector scrutiny. This becomes problematic when we swap the test sets: now, we train on Face2Face and test on FaceSwap and vice-versa. Thus, train and test sets are generated from different (even though related) approaches. Therefore, the cross-domain accuracies drop to 50.20% and 52.73%, respectively – this is only marginally better than random chance.

Our proposal, ForensicTransfer, is a CNN-based forensic detector that tackles the problem of detecting novel unseen
manipulation methods, without the need of a large amount of training data. Given a new image from a target domain, one can use the encoder trained on source domain to determine the forensic embedding. Based on the classification rule mentioned in the main paper, we are able to decide whether the input is closer to the real or to the fake images of the source domain. If the two manipulation methods share specific artifacts, a fake image of the target domain is closer to the fake images of the source domain. Given a few samples of the target domain we are able to fine-tune the classifier.

To proof the transferability of our proposal, we compare the results using our novel approach by visualizing the class activation maps (see Fig. 11, cp. to Fig. 10). In contrast to a deep CNN like XceptionNet, our approach is able to adapt to the different artifacts of Face2Face and FaceSwap (the nose in the first case, the eyebrows and mouth in the second case). Fine-tuning on few images further helps to rely on these different artifacts.

**Figure 11:** Class activation maps for our method when it is trained on Face2Face [47] and tested on Face2Face forgeries (left) or FaceSwap [2] (middle), and finally trained on Face2Face but fine-tuned using only four images manipulated with FaceSwap and tested on FaceSwap (right).