Models of Co-occurrence

I. Dan Melamed
University of Pennsylvania, melamed@unagi.cis.upenn.edu

Follow this and additional works at: https://repository.upenn.edu/ircs_reports

University of Pennsylvania Institute for Research in Cognitive Science Technical Report No. IRCS-98-05.

For more information, please contact repository@pobox.upenn.edu.
Abstract
A model of co-occurrence in bitext is a boolean predicate that indicates whether a given pair of word tokens co-occur in corresponding regions of the bitext space. Co-occurrence is a precondition for the possibility that two tokens might be mutual translations. Models of co-occurrence are the glue that binds methods for mapping bitext correspondence with methods for estimating translation models into an integrated system for exploiting parallel texts. Different models of co-occurrence are possible, depending on the kind of bitext map that is available, the language-specific information that is available, and the assumptions made about the nature of translational equivalence. Although most statistical translation models are based on models of co-occurrence, modeling co-occurrence correctly is more difficult than it may at first appear.

Comments
University of Pennsylvania Institute for Research in Cognitive Science Technical Report No. IRCS-98-05.
Models of Co-occurrence

I. Dan Melamed
Dept. of Computer and Information Science
University of Pennsylvania
Philadelphia, PA, 19104, U.S.A.
melamed@unagi.cis.upenn.edu
http://www.cis.upenn.edu/~melamed

Abstract

A model of co-occurrence in bitext is a boolean predicate that indicates whether a given pair of word tokens co-occur in corresponding regions of the bitext space. Co-occurrence is a precondition for the possibility that two tokens might be mutual translations. Models of co-occurrence are the glue that binds methods for mapping bitext correspondence with methods for estimating translation models into an integrated system for exploiting parallel texts. Different models of co-occurrence are possible, depending on the kind of bitext map that is available, the language-specific information that is available, and the assumptions made about the nature of translational equivalence. Although most statistical translation models are based on models of co-occurrence, modeling co-occurrence correctly is more difficult than it may at first appear.

1 Introduction

Most methods for estimating translation models from parallel texts (bitexts) start with the following intuition: Words that are translations of each other are more likely to appear in corresponding bitext regions than other pairs of words. The intuition is simple, but its correct exploitation turns out to be rather subtle. Most of the literature on translation model estimation presumes that corresponding regions of the input bitexts are represented by neatly aligned segments. As discovered by Church (1993), most of the bitexts available today are not easy to align. Moreover, imposing an alignment relation on such bitexts is inefficient, because alignments cannot capture crossing correspondences among text segments.

Melamed (1996) proposed methods for producing general bitext maps for arbitrary bitexts. The present report shows how to use bitext maps and other information to construct a model of co-occurrence. A model of co-occurrence is a boolean predicate, which indicates whether a given pair of word tokens co-occur in corresponding regions of the bitext space. Co-occurrence is a precondition for the possibility that two tokens might be mutual translations. Models of co-occurrence are the glue that binds methods for mapping bitext correspondence with methods for estimating translation models into an integrated system for exploiting parallel texts. When the model of co-occurrence is modularized away from the translation model, it also becomes easier to study translation model estimation methods per se.

Different models of co-occurrence are possible, depending on the kind of bitext map that is available, the language-specific information that is available, and the assumptions made about the nature of translational equivalence. The following three sections explore these three variables.
2 Relevant Regions of the Bitext Space

By definition of “mutual translations,” corresponding regions of a text and its translation will contain word token pairs that are mutual translations. Therefore, a general representation of bitext correspondence is the natural concept on which to build a model of where mutual translations co-occur. The most general representation of bitext correspondence is a bitext map (Melamed, 1996). Token pairs whose co-ordinates are part of the true bitext map (TBM) are mutual translations, by definition of the TBM. The likelihood that two tokens are mutual translations is inversely correlated with the distance between the tokens’ co-ordinate in the bitext space and the interpolated TBM.

It may be possible to develop translation model estimation methods that take into account a probabilistic model of co-occurrence. However, all the models in the literature are based on a boolean co-occurrence model — they want to know either that two tokens co-occur or that they do not. A boolean co-occurrence predicate can be defined by setting a threshold $\delta$ on the distance from the interpolated bitext map. Any token pair whose co-ordinate is closer than $\delta$ to the bitext map would be considered to co-occur by this predicate. The optimal value of $\delta$ varies with the language pair, the bitext genre and the application. Figure 1 illustrates what I will call the distance-based model of co-occurrence. Dagan et al. (1993) were the first to use a distance-based model of co-occurrence, although they measured the distance in words rather than in characters.

General bitext mapping algorithms are a recent invention. So far, most researchers interested in co-occurrence of mutual translations have relied on bitexts where sentence boundaries (or other text unit boundaries) were easy to find (e.g. Gale & Church, 1991; Kumano & Hirakawa, 1994; Fung, 1995; Melamed, 1995). Aligned text segments suggest a boundary-based model of co-occurrence, illustrated in Figure 2.

For bitexts involving languages with similar word order, a more accurate combined model of co-occurrence can be built using both segment boundary information and the map-distance threshold. As shown in Figure 3, each of these constraints eliminates the noise from a characteristic region of the bitext space.
Figure 1: *Distance-based model of co-occurrence.* Word token pairs whose co-ordinates lie in the shaded region count as co-occurrences. Thus, \((s,t_2)\) co-occur, but \((s,t_1)\) do not.
Figure 2: Boundary-based model of co-occurrence. Word token pairs whose co-ordinates lie in shaded regions count as co-occurrences. In contrast with Figure 1, (s, t1) co-occur, but (s, t2) do not.
Figure 3: Combined model of co-occurrence. Word token pairs whose co-ordinates lie in shaded regions count as co-occurrences. In contrast with Figures 1 and 2, neither \((s,t1)\) nor \((s,t2)\) co-occur. Striped regions indicate eliminated sources of noise.
3 Co-occurrence Counting Methods

Both the boundary-based and distance-based constraints restrict the region of the bitext space where tokens may be considered to co-occur. Yet, these constraints do not answer the question of how to count co-occurrences within the restricted regions. It is somewhat surprising that this is a question at all, and most authors ignore it. However, when authors specify their algorithms in sufficient detail to answer this question, the most common answer (given, e.g., by Brown et al., 1993; Dagan et al., 1993; Kupiec, 1993; Melamed, 1995) turns out to be unsound. The problem is easiest to illustrate under the boundary-based model of co-occurrence. Given two aligned text segments, the naive way to count co-occurrences is

\[
\text{cooc}(u, v) = e(u) \cdot f(v) \tag{1}
\]

where \(e(u)\) and \(f(v)\) are the frequencies of occurrence of \(u\) and \(v\) in their respective segments. For many \(u\) and \(v\), \(e(u)\) and \(f(v)\) are either 0 or 1, and Equation 1 returns 1 just in case both words occur. The problem arises when \(e(u) > 1\) and \(f(v) > 1\). For example, if \(e(u) = f(v) = 3\), then according to Equation 1, \(\text{cooc}(u, v) = 9\)! If the two aligned segments are really translations of each other, then it is most likely that each of the occurrences of \(u\) is a translation of just one of the occurrences of \(v\). Although it may not be known which of the 3 \(v\)'s each \(u\) corresponds to, the number of times that \(u\) and \(v\) co-occur as possible translations of each other in that segment pair must be 3.

There are various ways to arrive at \(\text{cooc}(u, v) = 3\). Two of the simplest ways are

\[
\text{cooc}(u, v) = \min[e(u), f(v)] \tag{2}
\]

and

\[
\text{cooc}(u, v) = \max[e(u), f(v)]. \tag{3}
\]

Equation 2 is based on the simplifying assumption that each word is translated to at most one other word. Equation 3 is based on the simplifying assumption that each word is translated to at least one other word. Either simplifying assumption results in more plausible co-occurrence counts than the naive method in Equation 1.

Counting co-occurrences is more difficult under a distance-based co-occurrence model, because there are no aligned segments and consequently no useful definition for \(e()\) and \(f()\). Furthermore, under a distance-based co-occurrence model, the co-occurrence relation is not transitive. E.g., it is possible that \(s_1\) co-occurs with \(t_1\), \(t_1\) co-occurs with \(s_2\), \(s_2\) co-occurs with \(t_2\), but \(s_1\) does not co-occur with \(t_2\). The correct counting method becomes clearer if the problem is recast in graph-theoretic terms. Let the words in each half of the bitext represent the vertices on one side of a bipartite graph. Let there be edges between each pair of words whose co-ordinates are closer than \(\delta\) to the bitext map. Now, under the “at most one” assumption of Equation 2, each co-occurrence is represented by an edge in the graph’s maximum matching \(^1\). Under the “at least one” assumption of Equation 3, each co-occurrence is represented by an edge in the graph’s smallest vertex cover. Maximum matching can be computed in polynomial time for any graph (Ahuja et al., 1993). Vertex cover can be solved in polynomial time for bipartite graphs\(^2\). It is of no importance that maximum matchings and minimum vertex covers may be non-unique — by definition, all solutions have the same number of edges, and this number is the correct co-occurrence count.

\(^1\)A maximum matching is a subgraph that solves the cardinality matching problem (Ahuja et al., 1993, pp. 469-470).

\(^2\)The algorithm is folklore, but Phillips & Warnow (1996) describe relevant methods.
4 Language-Specific Filters

Co-occurrence is a universal precondition for translational equivalence among word tokens in bitexts. Other preconditions may be imposed if certain language-specific resources are available (Melamed, 1995). For example, parts of speech tend to be preserved in translation (Papageorgiou et al., 1994). If part-of-speech taggers are available for both languages in a bitext, and if cases where one part of speech is translated to another are not important for the intended application, then we can rule out the possibility of translational equivalence for all token pairs involving different parts of speech. A more obvious source of language-specific information is a machine-readable bilingual dictionary (MRBD). If token \( a \) in one half of the bitext is found to co-occur with token \( b \) in the other half, and \( (a,b) \) is an entry in the MRBD, then it is highly likely that the tokens \( a \) and \( b \) are indeed mutual translations. In this case, there is no point considering the co-occurrence of \( a \) or \( b \) with any other token. Similarly exclusive candidacy can be granted to cognate token pairs (Simard et al., 1992).

Most published translation models treat co-occurrence counts as counts of potential link tokens (Melamed, 1998). More accurate models may result if the co-occurrence counts are biased with language-specific knowledge. Without loss of generality, whenever translation models refer to co-occurrence counts, they can refer to co-occurrence counts that have been filtered using whatever language-specific resources happen to be available. It does not matter if there are dependencies among the different knowledge sources, as long as each is used as a simple filter on the co-occurrence relation (Melamed, 1995).

5 Conclusion

In this short report, I have investigated methods for modeling word token co-occurrence in parallel texts (bitexts). Models of co-occurrence are a precursor to all the most accurate translation models in the literature. So far, most researchers have relied on only a restricted form of co-occurrence, based on a restricted kind of bitext map, applicable to only a limited class of bitexts. A more general co-occurrence model can be based on any bitext map, and thus on any bitext.

The correct method for counting the number of times that two words co-occur turns out to be rather subtle, especially for more general co-occurrence models. As noted in Section 3, many published translation models have been based on flawed models of co-occurrence. This report has exposed the flaw and has shown how to fix it.

References

R. K. Ahuja, T. L. Magnati & J. B. Orlin. (1993) Network Flows: Theory, Algorithms, and Applications. Prentice Hall, Englewood Cliffs, NJ.

P. F. Brown, S. A. Della Pietra, V. J. Della Pietra, & R. L. Mercer. (1993) "The Mathematics of Statistical Machine Translation: Parameter Estimation," Computational Linguistics 19(2).

K. W. Church. (1993) "Charalign: A Program for Aligning Parallel Texts at the Character Level," Proceedings of the 31st Annual Meeting of the Association for Computational Linguistics. Columbus, OH.
I. Dagan, K. Church, & W. Gale. (1993) “Robust Word Alignment for Machine Aided Translation,” Proceedings of the Workshop on Very Large Corpora: Academic and Industrial Perspectives. Columbus, OH.

P. Fung. (1995) “A Pattern Matching Method for Finding Noun and Proper Noun Translations from Noisy Parallel Corpora,” Proceedings of the 33rd Annual Meeting of the Association for Computational Linguistics. Boston, MA.

W. Gale & K. W. Church. (1991) “Identifying Word Correspondences in Parallel Texts,” Proceedings of the DARPA SNL Workshop. Asilomar, CA.

A. Kumano & H. Hirakawa. (1994) “Building an MT Dictionary from Parallel Texts Based on Linguistic and Statistical Information,” Proceedings of the 15th International Conference on Computational Linguistics. Kyoto, Japan.

J. Kupiec. (1993) “An Algorithm for Finding Noun Phrase Correspondences in Bilingual Corpora,” Proceedings of the 31st Annual Meeting of the Association for Computational Linguistics. Columbus, OH.

I. D. Melamed. (1995) “Automatic evaluation and uniform filter cascades for inducing N-best translation lexicons,” Proceedings of the Third Workshop on Very Large Corpora. Cambridge, Massachusetts.

I. D. Melamed. (1996) “A Geometric Approach to Mapping Bitext Correspondence,” Proceedings of the First Conference on Empirical Methods in Natural Language Processing. Philadelphia, PA.

I. D. Melamed. (1998) Empirical Methods for Exploiting Parallel Texts. Ph.D. dissertation, University of Pennsylvania, Philadelphia, PA.

H. Papageorgiou, L. Cranias & S. Piperidis. (1994) “Automatic Alignment in Parallel Corpora,” Proceedings of the 32nd Annual Meeting of the Association for Computational Linguistics (Student Session). Las Cruces, NM.

C. Phillips & T. J. Warnow. (1996) “The Asymmetric median tree — A New Model for Building Consensus Trees,” Discrete Applied Mathematics 71(1-3), pp. 331-335.

M. Simard, G. F. Foster & P. Isabelle. (1992) “Using Cognates to Align Sentences in Bilingual Corpora,” Proceedings of the Fourth International Conference on Theoretical and Methodological Issues in Machine Translation. Montreal, Canada.