STRONG CONVERGENCE OF THE EULER–MARUYAMA APPROXIMATION FOR A CLASS OF LÉVY-DRIVEN SDES

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Abstract. Consider the following stochastic differential equation (SDE)
\[ dX_t = b(t, X_{t-}) \, dt + dL_t, \quad X_0 = x, \]
driven by a d-dimensional Lévy process \((L_t)_{t \geq 0}\). We establish conditions on the Lévy process and the drift coefficient \(b\) such that the Euler–Maruyama approximation converges strongly to a solution of the SDE with an explicitly given rate. The convergence rate depends on the regularity of \(b\) and the behaviour of the Lévy measure at the origin. As a by-product of the proof, we obtain that the SDE has a pathwise unique solution. Our result covers many important examples of Lévy processes, e.g. isotropic stable, relativistic stable, tempered stable and layered stable.

1. Introduction

For a given Lévy process \((L_t)_{t \geq 0}\) with values in \(\mathbb{R}^d\) and Lévy triplet \((\ell, Q, \nu)\) we consider the stochastic differential equation (SDE)
\[ dX_t = b(t, X_{t-}) \, dt + dL_t, \quad X_0 = x \in \mathbb{R}^d. \]
If the drift coefficient \(b\) is Hölder continuous in time and space, there is a quite general result on the existence of a pathwise unique solution, cf. Chen, Song & Zhang [1]. It is, however, in general not possible to calculate the solution explicitly, and therefore it is important to have numerical schemes which allow us to approximate the solution. In this paper we derive conditions on the Lévy process \((L_t)_{t \geq 0}\) and the drift coefficient \(b\) such that the Euler–Maruyama approximation
\[ X_t^{(n)} - x = \int_0^t b(s, X_{s-}^{(n)}) \, ds + L_t, \quad t \in [0,T], \quad n \in \mathbb{N}, \]
converges strongly to a solution of the given SDE with a certain rate; here \(\eta_n(s) := T_n^+ \) for \(s \in [T_n^-, T_n^+ + 1]\). It turns out that the convergence (rate) depends on two factors: the regularity of \(b\) and the behaviour of the Lévy measure at the origin.

If \(b = b(x)\) satisfies a one-sided Lipschitz condition, then a result by Higham & Kloeden [6] shows that the Euler–Maruyama approximation converges strongly with convergence rate \(1/2\). It is natural to ask whether the regularity assumption can be weakened to Hölder regularity. Pamen & Taguchi [21] study the convergence rate for SDEs with Hölder continuous coefficients driven by Brownian motion and by truncated \(\alpha\)-stable Lévy processes with index \(\alpha > 1\). For isotropic \(\alpha\)-stable Lévy processes, \(\alpha > 1\), first results were obtained by Qiao [23] (\(b\) is Lipschitz up to a log-term) and by Hashimoto [5] who proves the strong convergence under a Komatsu condition, but does not determine the convergence rate. More recently, Mikulevicius & Xu [19] have shown that
\[ \mathbb{E} \left( \sup_{0 \leq s \leq T} |X_s - X_t^{(n)}|^p \right) \leq C_n^{-p\beta/\alpha}, \quad p \in (0, \alpha), \]
if \(\alpha \in (1, 2)\) and \(b\) is \(\beta\)- Hölder continuous for some \(\beta > 1 - \alpha/2\). This estimate shows, in particular, that there are two factors which result in a slow convergence of the Euler–Maruyama approximation: weak regularity of \(b\) and a strong singularity of the Lévy measure \(\nu(dy) = |y|^{-(d+\alpha)} \, dy\) at \(y = 0\). The fact that the behaviour of the Lévy measure influences the convergence rate was

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already observed by Jacod [8] who investigated the weak convergence of the Euler–Maruyama approximation for a class of Lévy-driven SDEs.

Our main result, Theorem 2.1, shows the strong convergence of the Euler–Maruyama approximation for a large class of driving Lévy processes covering many important and interesting examples, e.g. isotropic α-stable, relativistic stable, tempered stable and layered stable Lévy processes. The proof relies on the so-called Itô-Tanaka trick which relates the time average \( \int_0^t b(s,X_s) \, ds \) of the solution \((X_t)_{t \geq 0}\) to the Kolmogorov equation

\[
\frac{\partial_t u(t, x)}{\partial_t} + A_x u(t, x) + b(t, x) \cdot \nabla_x u(t, x) = -b(t, x);
\]

here \( A_x \) denotes the infinitesimal generator of the driving Lévy process \((L_t)_{t \geq 0}\) acting with respect to the space variable \( x \). The key step is to prove the existence of a solution to (2) which is sufficiently regular and satisfies certain Hölder estimates. The required regularity of \( u \) depends on the regularity of \( b \) and the behaviour of the Lévy measure at 0.

The Itô-Tanaka trick has been used by Pamen & Taguchi [21] to prove the strong convergence of the Euler–Maruyama approximation for a class of Lévy-driven SDEs. Throughout \((L_t)_{t \geq 0}\) is a \( d \)-dimensional Lévy process with characteristic function \( E e^{it^T L_t} \). It is well-known that \( E e^{it^T L_t} = e^{-t \psi(t)} \) with a characteristic exponent \( \psi \) which is uniquely characterized via the Lévy–Khintchine formula by the Lévy triplet \((\ell,Q,\nu)\) consisting of \( \ell \in \mathbb{R}^d \), \( Q \in \mathbb{R}^{d \times d} \) positive semidefinite and a measure \( \nu \) on \( \mathbb{R}^d \setminus \{0\} \) such that \( \int \min\{1,|y|^2\} \nu(dy) < \infty \), see (7) and (8) p. 5.

2.1. Theorem. Let \((L_t)_{t \geq 0}\) be a \( d \)-dimensional Lévy process with Lévy triplet \((\ell,Q,\nu)\) and characteristic exponent \( \psi : \mathbb{R}^d \to \mathbb{C} \), and let \( \gamma_0 \in [1,2], \gamma_\infty > 0 \) be such that \( \int_{|z| \leq 1} |z|^\gamma_0 \nu(dz) < \infty \) and \( \int_{|z| \geq 1} |z|^\gamma_\infty \nu(dz) < \infty \). Assume that \( L_t \) admits a transition density \( p_t \in C^2(\mathbb{R}^d) \), i.e. \( x \mapsto p_t(x) \) is twice continuously differentiable, for all \( t > 0 \), such that there exist constants \( \alpha \in (1,2] \) and \( c = c(T) > 0 \) such that

\[
\int_{\mathbb{R}^d} |\partial_x p_t(x)| \, dx \leq c t^{-1/\alpha} \quad \text{for all} \quad i \in \{1,\ldots,d\}, \quad t \in (0,T].
\]

Let \( b : [0,\infty) \times \mathbb{R}^d \to \mathbb{R}^d \) be a bounded function which is \( \beta \)-Hölder continuous with respect to \( x \) and \( \eta \)-Hölder continuous with respect to \( t \) for some \( \beta, \eta \in (0,1] \), i.e.

\[
|b(t,x) - b(t,y)| \leq C|x-y|^\beta \quad \text{and} \quad |b(s,x) - b(t,x)| \leq C|s-t|^\eta
\]

holds for all \( s,t \geq 0, x,y \in \mathbb{R}^d \) and with an absolute constant \( C > 0 \). If the balance condition

\[
2\alpha - \gamma_0 (1-\beta) > 2,
\]

is satisfied, then the SDE

\[
dX_t = b(t,X_{t-}) \, dt + dL_t, \quad X_0 = x
\]

has a pathwise unique strong solution \((X_t)_{t \geq 0}\), and for any \( p \leq \gamma_\infty \) and \( T > 0 \) there exists a constant \( C > 0 \) such that

\[
E \left( \sup_{0 \leq t \leq T} |X_t - X_t^{(n)}|^p \right) \leq C n^{-\min\{1,p\beta/\gamma_0,\eta\}} \quad \text{for all} \quad n \in \mathbb{N}.
\]
2.2. Remark. (i) For the existence of a pathwise unique solution to (5) it is crucial that the mapping \( x \mapsto b(t, x) \) is sufficiently regular. For instance, if \((L_t)_{t \geq 0}\) is an isotropic \(\alpha\)-stable Lévy process, then the SDE

\[ dX_t = b(X_{t-}) \, dt + dL_t \]

fails, in general, to have a pathwise unique solution if \( b \) is \( \beta\)-Hölder continuous with \( \beta + \alpha < 1 \), cf. [28]; recently, Kulik [16] has shown that the SDE admits a pathwise unique solution if \( \beta + \alpha > 1 \). This shows that there is a trade-off and compensation between the (lack of) regularity of the driving Lévy noise and the (lack of) regularity of the coefficient \( x \mapsto b(x) \).

(ii) Condition (3) is equivalent to saying that the semigroup \( P_t \phi(x) := E\phi(x + L_t) \), \( \phi \in B_b(\mathbb{R}^d) \), associated with the Lévy process \((L_t)_{t \geq 0}\) satisfies the gradient estimate

\[ \| \nabla P_t \phi \|_\infty \leq ct^{-1/\alpha} \| \phi \|_\infty, \quad \phi \in B_b(\mathbb{R}^d), \]

cf. Lemma 4.1. If \((L_t)_{t \geq 0}\) is subordinate to a Brownian motion, then (3) can also be understood as a moment estimate, cf. Lemma 4.5.

(iii) The existence of the moments \( \int_{|z| \leq 1} |z|^\nu \nu(dz) \) and \( \int_{|z| \geq 1} |z|^\nu \nu(dz) \) is related to the growth of the characteristic exponent \( \psi \), cf. Lemma 5.1; Lemma 5.1 is very useful since it allows us to verify the assumptions of Theorem 2.1 if the Lévy measure \( \nu \) cannot be calculated explicitly.

(iv) A sufficient condition for the existence of a transition probability density \( p_t \in C^2(\mathbb{R}^d) \) for all \( t > 0 \) is the Hartman–Wintner condition:

\[ \lim_{|\xi| \to \infty} \frac{\Re \psi(\xi)}{\log(1 + |\xi|)} = \infty, \]

cf. [9] for a thorough discussion.

(v) Let \((X_t)_{t \geq 0}\) be a solution to (5). Since \( b \) is bounded, we have for any \( t > 0 \)

\[ X_t \in L^p(\mathbb{P}) \iff L_t \in L^p(\mathbb{P}) \iff \int_{|z| \geq 1} |z|^p \nu(dz) < \infty \]

– for the second equivalence see Sato [24] –, i.e. the solution inherits the integrability of the driving Lévy process and vice versa. This means that, in general, we cannot expect (6) to hold for \( p > \gamma_\infty \).

(vi) A slight variation of our arguments, see the uniqueness part of the proof of Theorem 2.1 on page 16, allows us to derive the estimate

\[ \mathbb{E} \left( \sup_{t \in [0, T]} |X_t(x) - X_t(y)|^p \right) \leq C' |x - y|^p, \quad p \leq \gamma_\infty \]

for some constant \( C' > 0 \) where \( X_t(z) \) denotes the solution to the SDE with initial condition \( X_0(z) = z \). If \( \gamma_\infty > d \) it follows from a standard Kolmogorov–Chentsov–Totoki argument that \( x \mapsto X_t(x) \) is Hölder continuous of order \( \kappa < 1 - d/\gamma_\infty \).

Let us give some further remarks on possible extensions of Theorem 2.1.

2.3. Remark. (i) If \((L_t)_{t \geq 0}\) has a non-vanishing (possibly degenerate) diffusion part, then the statement of Theorem 2.1 remains valid for \( \gamma_0 := 2 \). In particular, if \((W_t)_{t \geq 0}\) is a Brownian motion and \( b : [0, \infty) \times \mathbb{R}^d \to \mathbb{R}^d \) is a bounded function which is \( \beta\)-Hölder continuous with respect to \( x \) and \( \eta\)-Hölder-continuous with respect to \( t \) for some \( \beta, \eta \in (0, 1] \), then the SDE

\[ dX_t = b(t, X_t) \, dt + dW_t, \quad X_0 = x \]

has a pathwise unique solution, and for any \( p > 0, T > 0 \) there exists a constant \( C > 0 \) such that

\[ \mathbb{E} \left( \sup_{0 \leq t \leq T} |X_t - X_t^{(n)}|^p \right) \leq C n^{-\min\{1, p\beta/2, p\eta\}} \]

for all \( n \in \mathbb{N} \); this result extends [21, Theorem 2.11].
(ii) A close inspection of our arguments reveals that the Hölder condition on \( t \mapsto b(t, x) \) can be replaced by uniform continuity; if we denote by
\[
w(\delta) := \sup_{x \in \mathbb{R}^d} \sup_{|s-t| \leq \delta} |b(t, x) - b(s, x)|
\]
the modulus of continuity of \( t \mapsto b(t, x) \) (uniformly in \( x \)), then (6) becomes
\[
\mathbb{E} \left( \sup_{0 \leq t \leq T} |X_t - X_t^{(n)}|^p \right) \leq Cn^{-\min\{1, p\beta/\gamma_0\}} + Cw(1/n)^p, \quad n \in \mathbb{N},
\]
for a suitable constant \( C > 0 \).

(iii) Case \( \alpha = 1 \): If we replace (3) by
\[
\int_{\mathbb{R}^d} |\partial_s p_t(x)| \, dx \leq ct^{-1} \log^{-1-\epsilon} t, \quad i \in \{1, \ldots, d\}, \ t \in (0, T]
\]
for some \( \epsilon > 0 \), then the statement of Theorem 2.1 holds for \( \alpha = 1 \).

2.4. Remark. It is a natural question whether it is possible to consider (1) with multiplicative noise, i.e. with \( \sigma(t, X_t) \cdot dL_t \) instead of \( dL_t \). This, however, requires different methods than the ones used here, see the recent paper [2] by Chen et al.; in particular, it is not clear how to find a solution to the PDE (24) appearing in Theorem 4.4.

Combining Theorem 2.1 with the gradient estimates in [27] we can easily prove the following statement which covers many interesting and important examples of Lévy processes, cf. Section 5.

2.5. Corollary. Let \((L_t)_{t \geq 0}\) be a d-dimensional Lévy process with characteristic exponent \( \psi \) and Lévy triplet \((\ell, 0, \nu)\). Let \( \gamma_0 \in [1, 2], \gamma_\infty > 0 \) be exponents such that \( \int_{|z| \leq 1} |z|^\gamma_0 \nu(dz) < \infty \) and \( \int_{|z| \geq 1} |z|^\gamma_\infty \nu(dz) < \infty \). Assume that there exists a strictly increasing function \( f : (0, \infty) \to [0, \infty) \) which is differentiable near infinity and satisfies the following conditions.

(i) \( c^{-1} f(|\xi|) \leq \text{Re} \psi(\xi) \leq cf(|\xi|) \) for some constant \( c \in (0, \infty) \);
(ii) \( \limsup_{r \to \infty} r^{-1} f^{-1}(2r)/f^{-1}(r) < \infty \);
(iii) there exist constants \( \alpha \in (1, 2) \) and \( c > 0 \) such that \( f(r) \geq cr^\alpha \) for large \( r > 0 \).

Let \( b : [0, \infty) \times \mathbb{R}^d \to \mathbb{R}^d \) be a bounded function which is \( \beta \)-Hölder continuous with respect to \( x \) and \( \eta \)-Hölder continuous with respect to \( t \) for some \( \beta, \eta \in (0, 1] \). If the balance condition holds
\[
2\alpha - \gamma_0(1 - \beta) > 2,
\]
then the SDE
\[
dX_t = b(t, X_t) \, dt + dL_t, \quad X_0 = x
\]
has a pathwise unique strong solution \((X_t)_{t \geq 0}\), and for any \( p \leq \gamma_\infty \) and \( T > 0 \) there exists a constant \( C > 0 \) such that
\[
\mathbb{E} \left( \sup_{0 \leq t \leq T} |X_t - X_t^{(n)}|^p \right) \leq Cn^{-\min\{1, p\beta/\gamma_0, p\eta\}} \quad \text{for all} \ n \in \mathbb{N}.
\]

Typical examples for \( f \) are \( f(r) = r^\alpha \) and \( f(r) = r^\alpha \log^\beta(1 + r) \), see Section 5.

For the particular case that the driving Lévy process is subordinate to a Brownian motion, Theorem 2.1 has the following corollary.

2.6. Corollary. Let \( L_t = B_{S_t} \) be a d-dimensional Brownian motion subordinated by a subordinator \((S_t)_{t \geq 0}\) with Laplace exponent (Bernstein function) \( f \),
\[
f(\lambda) = \int_{(0, \infty)} (1 - e^{-\lambda r}) \, \mu(dr), \quad \lambda \geq 0.
\]
Assume that there exist constants \( \delta_0 \in [1/2, 1], \delta_\infty > 0 \) and \( \rho \in (1/2, 1] \) such that
\[
\int_{(0, 1)} r^{\delta_0} \, \mu(dr) + \int_{(1, \infty)} r^{\delta_\infty} \, \mu(dr) < \infty
\]
and
\[
\liminf_{\lambda \to \infty} \frac{f(\lambda)}{\lambda^\beta} > 0.
\]

Let \( b : [0, \infty) \times \mathbb{R}^d \to \mathbb{R}^d \) be a bounded function which is \( \beta \)-Hölder continuous with respect to \( x \) and \( \eta \)-Hölder continuous with respect to \( t \) for some \( \eta \in (0, 1] \). If
\[
2\beta - \delta_0(1 - \beta) > 1
\]
then the SDE
\[
dX_t = b(t, X_{t-}) dt + dL_t, \quad X_0 = x
\]
has a unique strong solution \((X_t)_{t \geq 0}\) and for any \( p \leq 2\delta_\infty \) and \( T > 0 \) there exists a constant \( C > 0 \) such that
\[
E \left( \sup_{0 \leq t \leq T} |X_t - X_t^{(n)}|^p \right) \leq C n^{-\min\{1, p\beta/(2\delta_\infty), \eta\}} \quad \text{for all } n \in \mathbb{N}.
\]

3. Preliminaries

We consider Euclidean space \( \mathbb{R}^d \) endowed with the Borel \( \sigma \)-algebra \( \mathcal{B}(\mathbb{R}^d) \). The open ball centered at \( x \in \mathbb{R}^d \) of radius \( r > 0 \) is denoted by \( B(x, r) \). For a differentiable function \( f : \mathbb{R}^d \to \mathbb{R} \) the partial derivative with respect to \( x_i \) is denoted by \( \partial_{x_i} f \), and \( \nabla f \) is the gradient of \( f \). As usual, \( C^k(\mathbb{R}^d) \) is the space of \( k \)-times continuously differentiable functions, \( \mathcal{B}(\mathbb{R}^d) \) the space of bounded Borel measurable functions, and \( C_\infty(\mathbb{R}^d) \) is the space of continuous functions vanishing at infinity. For \( \beta \in [0, 1] \) we define Hölder spaces by
\[
C^\beta_b(\mathbb{R}^d) := \left\{ f : \mathbb{R}^d \to \mathbb{R}^k; \|f\|_{C^\beta_b(\mathbb{R}^d)} := \sup_{x \in \mathbb{R}^d} |f(x)| + \sup_{x \neq y} \frac{|f(x) - f(y)|}{|x - y|^{\beta}} < \infty \right\}
\]
\[
C^{1,\beta}(\mathbb{R}^d) := \left\{ f \in C^1(\mathbb{R}^d, \mathbb{R}^k); \|f\|_{C^{1,\beta}(\mathbb{R}^d)} := \sup_{x \in \mathbb{R}^d} |f(x)| + \sup_{x \neq y} \frac{|\nabla f(x)|}{|x - y|^{\beta}} < \infty \right\}.
\]

For a function space \( M \) and a function \( g : [a, b] \times \mathbb{R}^d \to \mathbb{R}^k \), we write \( g \in C([a, b], M) \) if \( g(t, \cdot) \in M \) for all \( t \in [a, b] \) and \( t \mapsto g(t, \cdot) \) is continuous. Similarly, \( g \in C^1([a, b], M) \) means that \( \partial_t g(t, \cdot) \in M \) and \( t \mapsto \partial_t g(t, \cdot) \) is continuous. If \( M \) is a normed function space, then
\[
\|g\|_{C([a, b], M)} := \sup_{t \in [a, b]} \|g(t, \cdot)\|_M
\]
defines a norm on \( C([a, b], M) \). For brevity we will often denote this norm by \( \|g\|_M \); in particular we will write
\[
\|g\|_{C^\beta_b(\mathbb{R}^d)} := \sup_{t \in [a, b]} \sup_{x \in \mathbb{R}^d} |g(t, x)| + \sup_{t \in [a, b]} \sup_{x, y \neq y} \frac{|g(t, x) - g(t, y)|}{|x - y|^{\beta}}.
\]

We say that a bounded function \( g : [a, b] \times \mathbb{R}^d \to \mathbb{R}^k \) is \( \beta \)-Hölder continuous with respect to \( x \) if \( \|g\|_{C^\beta_b(\mathbb{R}^d)} < \infty \).

Throughout, \( (\Omega, \mathcal{A}, P) \) is a probability space. A family of random variables \( L_t : \Omega \to \mathbb{R}^d \), \( t \geq 0 \), is a \( d \)-dimensional Lévy process if \( (L_t)_{t \geq 0} \) has stationary and independent increments, \( t \mapsto L_t \) is, with probability 1, right-continuous with finite left limits (càdlàg), and \( L_0 = 0 \). A Lévy process can be uniquely (in the sense of finite-dimensional distributions) characterized by its characteristic exponent \( \psi : \mathbb{R}^d \to \mathbb{C} \),
\[
E e^{i\xi L_t} = e^{-t\psi(\xi)}, \quad t \geq 0, \ \xi \in \mathbb{R}^d,
\]
the exponent is given by the Lévy–Khintchine formula
\[
\psi(\xi) = -i\ell \cdot \xi + \frac{1}{2} \xi \cdot Q \xi + \int_{\mathbb{R}^d \setminus \{0\}} \left( 1 - e^{iy \cdot \xi} + iy \cdot \xi I_{(0,1)}(|y|) \right) \nu(dy), \quad \xi \in \mathbb{R}^d.
\]

There is a one-to-one correspondence between the exponent \( \psi \) and the Lévy triplet \((\ell, Q, \nu)\) consisting of a vector \( \ell \in \mathbb{R}^d \) (drift parameter), a symmetric positive semi-definite matrix \( Q \in \mathbb{R}^{d \times d} \) (diffusion parameter) and a measure \( \nu \) on \((\mathbb{R}^d \setminus \{0\}, \mathcal{B}(\mathbb{R}^d \setminus \{0\}))\) satisfying \( \int_{y \neq 0} \min\{|y|^2, 1\} \nu(dy) < \infty \) (Lévy measure).
It is not difficult to see that any Lévy process \((L_t)_{t \geq 0}\) is a Markov process, and therefore there is a transition semigroup \((P_t)_{t \geq 0}\) and an infinitesimal generator \((A, \mathcal{D}(A))\) associated with \((L_t)_{t \geq 0}\). It is well known that

\[
P_tf(x) = E f(x + L_t), \quad x \in \mathbb{R}^d, \quad t \geq 0, f \in \mathcal{B}_b(\mathbb{R}^d),
\]

and, for any \(f \in \mathcal{C}_b^2(\mathbb{R}^d), \)

\[
(9) \quad A \xi(x) = \ell \cdot \nabla \xi(x) + \frac{1}{2} \text{div} \left( Q \nabla \xi(x) \right) + \int_{y \neq 0} \left( f(x + y) - f(x) - \nabla f(x) \cdot y \mathbb{1}_{(0,1]}(|y|) \right) \nu(dy).
\]

If \((L_t)_{t \geq 0}\) is a Lévy process with Lévy triplet \((\ell, \gamma, \nu)\) and \(\int_{|y| \leq 1} |y| \gamma \nu(dy) < \infty\) for some \(\gamma \in [1,2]\), then \(\mathcal{E}_b^{1,\gamma-1}(\mathbb{R}^d) \subseteq \mathcal{D}(A)\), and \((9)\) holds for any \(f \in \mathcal{E}_b^{1,\gamma-1}(\mathbb{R}^d)\), cf. [14, Theorem 4.1]; moreover,

\[
(10) \quad \|A f\|_\infty \leq 2 \left( \|\ell\| + \int_{y \neq 0} \min\{|y|^{\gamma},1\} \nu(dy) \right) \|f\|_\mathcal{E}_b^{1,\gamma-1}(\mathbb{R}^d) \quad \text{for all } f \in \mathcal{E}_b^{1,\gamma-1}(\mathbb{R}^d).
\]

For a function \(f = f(t,x)\) we indicate by \(A_s f(t,x)\) that the operator \(A\) acts on the variable \(x\) for any fixed \(t\). Our standard reference for Lévy processes is the monograph [24] by Sato.

A Lévy process \((S_t)_{t \geq 0}\) with non-decreasing sample paths is called a subordinator. It can be uniquely characterized by its Laplace exponent (Bernstein function) \(f(r) := \log E e^{-rS_1}\),

\[
f(r) = br + \int_{(0,\infty)} (1 - e^{dr}) \mu(dr), \quad r > 0,
\]

where \(b \geq 0\) and \(\mu\) is a measure on \((0,\infty)\) such that \(\int_{(0,\infty)} \min\{r,1\} \mu(dr) < \infty\). If \((L_t)_{t \geq 0}\) is a Lévy process with characteristic exponent \(\psi\) and \((S_t)_{t \geq 0}\) a subordinator with Laplace exponent \(f\) such that \((L_t)_{t \geq 0}\) and \((S_t)_{t \geq 0}\) are independent, then the subordinator process

\[
X_t(\omega) := L_{S_t(\omega)}(\omega), \quad \omega \in \Omega, \quad t \geq 0,
\]

is a Lévy process and its characteristic exponent is given by \(f(\psi(1))\), see [26] for further details.

A stochastic differential equation (SDE) driven by a Lévy process is of the form

\[
dX_t = b(t, X_{t-}) dt + g(t, X_{t-}) dL_t
\]

for suitable coefficients \(b, g\) and an initial condition fixing \(X_0\). The Euler–Maruyama approximation of the SDE is given by

\[
X_t^{(n)} := X_0 + \int_0^t b(s, X_{\eta(n)s-}) ds + \int_0^t g(s, X_{\eta(n)s-}) dL_s, \quad t \in [0, T]
\]

where \(\eta_n(s) := T \frac{i}{n}\) for any \(s \in [T \frac{i}{n}, T \frac{i+1}{n}], i = 0, 1, \ldots, n\), for fixed \(T > 0\). We say that the SDE has a pathwise unique solution if for any two solutions \((X_t)_{t \geq 0}\) and \((Y_t)_{t \geq 0}\) such that \(X_0 = Y_0\), we have

\[
P(\forall t \geq 0 : X_t = Y_t) = 1.
\]

We refer to Ikeda–Watanabe [7] and Protter [22] for a thorough discussion of stochastic integration and SDEs. A key tool for the proof of Theorem 2.1 is Novikov’s [20] version of the Burkholder–Davis–Gundy inequality for jump processes which holds for any \(p > 0\). Let us state this result from [20] in our notation.

3.1. Theorem (Novikov 1975). Let \(\tilde{N}\) be a Poisson random measure with compensator \(\tilde{N}\) of the form \(\tilde{N}(dy, ds) = \nu(dy) ds\), and let \(H\) be a predictable stochastic process.

(i) If \(\mathbb{E} \left( \int_0^T \int_{y \neq 0} |H(s,y)| \nu(dy) ds \right) < \infty\) then

\[
\mathbb{E} \left( \sup_{t \leq T} \left| \int_0^t H(s,y) \tilde{N}(dy, ds) \right|^p \right) \leq C_{p,\alpha} \mathbb{E} \left[ \left( \int_0^T \int |H(s,y)|^\alpha \nu(dy) ds \right)^{p/\alpha} \right]
\]

for any \(\alpha \in [1,2]\) and \(p \in [0,\alpha]\); here \(C_{p,\alpha}\) is an absolute constant depending only on \(\alpha\) and \(p\).
4. PROOFS

Before we start to prove Theorem 2.1 let us briefly explain the idea of the proof in dimension $d = 1$; the general case $d > 1$ follows from this by considering the coordinates. Suppose that $(X_t)_{t \geq 0}$ solves the SDE

$$dX_t = b(t, X_{t-}) dt + dL_t, \quad X_0 = x.$$ 

From the definition of the Euler–Maruyama approximation (11) we see that

$$X_t - X_t^{(n)} = \int_0^t \left( b(s, X_{s-}) - b(s, X_{s-}^{(n)}) \right) ds,$$

and so we have to show that the right-hand side converges in $L^p(\mathbb{P})$ to 0 as $n \to \infty$. To this end, we use the so-called Itô–Tanaka trick: We will show that there exists a sufficiently well-behaved solution $u : [0, T] \times \mathbb{R}^d \to \mathbb{R}$ to the integro-differential equation

$$\frac{\partial}{\partial t} u(t, x) + A_x u(t, x) + b(t, x) \cdot \nabla_x u(t, x) = -b(t, x), \quad u(T, x) = 0$$

for small $T > 0$; by $A$ we denote the generator of the driving Lévy process $(L_t)_{t \geq 0}$. Applying Itô’s formula, we get

$$\int_0^t (b(s, X_{s-}) - b(s, X_{s-}^{(n)}) \right) ds \approx u(t, X_t) - u(t, X_t^{(n)}) + M_t$$

for some martingale $M$. If $u$ is sufficiently smooth, this will allow us to estimate the $L^p$-norm of the right-hand side of (12) using the Burkholder–Davis–Gundy inequality, see pp. 12.

In the first part of this section we establish the existence of a solution to (13), cf. Theorem 4.4. In order to make sense of (13) we have, in particular, to show that $u(\cdot, x)$ and $u(t, \cdot)$ are differentiable and that $A_x u(t, x)$ is well-defined. We start with an auxiliary result showing that (3) gives automatically an estimate for the integrated second derivatives $\int_{\mathbb{R}^d} |\partial_x \partial_{x_k} p_t(x)| \, dx.$

4.1. Lemma. Let $(L_t)_{t \geq 0}$ be a $d$-dimensional Lévy process with transition semigroup $(P_t)_{t \geq 0}$ and density $p_t \in C^2(\mathbb{R}^d)$. Let $c : (0, T) \to [0, \infty)$ be a non-negative function.

(i) $\int_{\mathbb{R}^d} |\partial_x p_t(x)| \, dx \leq c(t) \iff \forall \phi \in \mathcal{B}_b(\mathbb{R}^d) : |\partial_x P_t \phi| \leq c(t) \|\phi\|_{\infty}$. If one (hence both) of the conditions is satisfied, then $\nabla P_t \phi = P_t (\nabla \phi)$ for any $\phi \in C^1_0(\mathbb{R}^d)$.

(ii) If $|\partial_x P_t \phi| \leq c(t) \|\phi\|_{\infty}$ for all $t \in (0, T)$, $\phi \in \mathcal{B}_b(\mathbb{R}^d)$ and $i \in \{1, \ldots, d\}$, then $|\partial_x \partial_{x_i} P_t \phi| \leq c(t) \|\phi\|_{\infty}$ for all $t \in (0, T)$, $\phi \in \mathcal{B}_b(\mathbb{R}^d)$ and $i, k \in \{1, \ldots, d\}$.

(iii) If $\int_{\mathbb{R}^d} |\partial_{x_i} p_t(x)| \, dx \leq c(t)$ for all $t \in (0, T)$ and $i \in \{1, \ldots, d\}$, then $\int_{\mathbb{R}^d} |\partial_{x_i} \partial_{x_k} p_t(x)| \, dx \leq c(t)^2$ for all $t \in (0, T)$ and $i, k \in \{1, \ldots, d\}$.

Proof. (i) Suppose that $\int_{\mathbb{R}^d} |\partial_x p_t(x)| \, dx \leq c(t)$ for some $t \in (0, T)$. Since

$$x \mapsto \int_{\mathbb{R}^d} \phi(z) \partial_x p_t(z - x) \, dz$$

is continuous – this is readily seen with a change of variables $z \mapsto z + x$, dominated convergence, and the fact that $\phi$ is bounded and continuous – it follows from the differentiation lemma, cf. Lemma A.1, that

$$x \mapsto P_t \phi(x) = E \phi(x + L_t) = \int_{\mathbb{R}^d} \phi(z) p_t(z - x) \, dz$$
is differentiable and
\[ \partial_z P_t \phi(x) = \int_{\mathbb{R}^d} \phi(z) \partial_z p_t(z - x) \, dz; \]
thus
\[ \| \partial_z P_t \phi \|_\infty \leq c(t) \| \phi \|_\infty, \quad \phi \in \mathcal{B}_b(\mathbb{R}^d). \]

Suppose that (\star) holds. Let $\chi_n \in C_c(\mathbb{R}^d)$ be a cut-off function such that $\mathbf{1}_{B(0,n)} \leq \chi_n \leq \mathbf{1}_{B(0,n+1)}$. Applying the differentiation lemma, we find that
\[ \partial_z P_t(\phi \chi_n)(x) = \int_{\mathbb{R}^d} \phi(z) \chi_n(z) \partial_z p_t(z - x) \, dz = -\int_{\mathbb{R}^d} \phi(x + y) \chi_n(x + y) \partial_y p_t(y) \, dy \]
for any $x \in \mathbb{R}^d$ and $\phi \in \mathcal{B}_b(\mathbb{R}^d)$. Thus,
\[ \int_{|y| \leq n} |\partial_y p_t(y)| \, dy = \sup \left\{ \int_{|y| \leq n} \phi(y) \partial_y p_t(y) \, dy : \phi \in \mathcal{B}_b(\mathbb{R}^d), \| \phi \|_\infty \leq 1 \right\} \]
\[ = \sup \left\{ \int_{|y| \leq n} \phi(y) \chi_n(y) \partial_y p_t(y) \, dy : \phi \in \mathcal{B}_b(\mathbb{R}^d), \| \phi \|_\infty \leq 1 \right\} \]
\[ \leq \sup \| \partial_z P_t(\phi \chi_n) \| \infty; \quad \phi \in \mathcal{B}_b(\mathbb{R}^d), \| \phi \|_\infty \leq 1 \leq c(t). \]

As $n \in \mathbb{N}$ is arbitrary, the monotone convergence theorem gives $\int_{\mathbb{R}^d} |\partial_y p_t(y)| \, dy \leq c(t)$. Then (14) and the integration by parts formula show that $\nabla P_t \phi = P_t(\nabla \phi)$ for any $\phi \in C^1(\mathbb{R}^d)$.

(ii) Fix $\phi \in \mathcal{B}_b(\mathbb{R}^d)$ and $t \in (0, T]$. Since $P_t \phi \in C^1(\mathbb{R}^d)$ it follows from (i) and the semigroup \[ \| \partial_z \partial_z x P_{2t} \phi \|_\infty = \| \partial_z \partial_z x P_t \partial_z P_t \phi \|_\infty = \| \partial_z P_t(\partial_z x P_t \phi) \|_\infty \leq c(t) \| \partial_z P_t \phi \|_\infty \]
\[ \leq c(t) \| \phi \|_\infty. \]

(iii) By (i) and (ii), we have $\| \partial_z \partial_z x P_{2t} \phi \|_\infty \leq c(t)^2 \| \phi \|_\infty$. Using a very similar reasoning as in the proof of (i), we find that
\[ \int_{|y| \leq n} |\partial_y \partial_y x P_{2t}(y)| \, dy \leq c(t)^2; \]
applying the monotone convergence theorem completes the proof. \[ \square \]

Recall that we use for a function $g : [0, T] \times \mathbb{R}^d \to \mathbb{R}$ and $\beta \in (0, 1]$ the notation
\[ \| g \|_{C^0_\beta(\mathbb{R}^d)} := \sup_{t \in [0,T]} \sup_{x \in \mathbb{R}^d} |g(t, x)| + \sup_{t \in [0,T]} \sup_{x \neq y} \frac{|g(t, x) - g(t, y)|}{|x - y|^\beta}. \]

**4.2. Lemma.** Let $(L_t)_{t \geq 0}$ be a Lévy process as in Theorem 2.1 with generator $(A, \mathcal{D}(A))$. Let $g \in C([0, T], C^\infty(\mathbb{R}^d))$ for $\beta \in (0, 1]$ satisfying (4). For every $T > 0$ there exists a mapping $u \in C([0, T], C^1_{\beta, \gamma}(\mathbb{R}^d)) \cap C^1([0, T], C_0(\mathbb{R}^d))$ solving
\[ \frac{\partial}{\partial t} u(t, x) = A_x u(t, x) + g(t, x) \quad \text{on } [0, T] \times \mathbb{R}^d \]
such that $u(0, \cdot) = 0$ and
\[ \| u \|_\infty + \| \nabla u \|_{C^0_\beta(\mathbb{R}^d)} + \| \nabla u \|_{C^0_{\beta, \gamma}(\mathbb{R}^d)} \leq C_T \| g \|_{C^0_\beta(\mathbb{R}^d)} \]
for some constant $C_T > 0$ which does not depend on $g$ and satisfies $\lim_{T \to 0} C_T = 0$.

**4.3. Remark.** (i) If we define $v(t, x) := u(T - t, x)$ for fixed $T > 0$, then $v$ is a solution to the equation with reversed time
\[ -\frac{\partial}{\partial t} v(t, x) = A_x v(t, x) + g(t, x), \quad v(T, \cdot) = 0. \]
In Theorem 2.1 (and hence in Lemma 4.2) we assume that the constant $\alpha$ appearing in (3) is strictly larger than 1 and we require that the balance condition (4) is satisfied. Both assumptions are crucial for the proof of Lemma 4.2. The assumption $\alpha > 1$ is needed to prove that $\nabla u(t, \cdot)$ exists and $\nabla^2 u(t, \cdot) \in C^0_b(\mathbb{R}^d)$ whereas (4) is used to show that $\nabla u(t, \cdot) \in C^{\gamma_0/2}_b(\mathbb{R}^d)$. The fact that $\nabla u(t, \cdot) \in C^0_b(\mathbb{R}^d)$ will be needed to construct a solution to (13) using Picard iterations, see Theorem 4.4, and $\nabla u(t, \cdot) \in C^{\gamma_0/2}_b(\mathbb{R}^d)$ will be used when we apply Itô’s formula, see Proposition A.2 and the proof of Theorem 2.1. Note that $\nabla u(t, \cdot) \in C^{\gamma_0/2}_b(\mathbb{R}^d)$ implies, in particular, that $u(t, \cdot) \in D(A)$ for all $t \in [0, T]$, see the remark following (9).

Proof of Lemma 4.2. We claim that
\[
    u(t, x) := \int_{(0,t]} E g(s, x + L_{t-s}) \, ds, \quad t \in [0, T], \ x \in \mathbb{R}^d,
\]
has all the desired properties.

Step 1: $u$ satisfies (16). For fixed $i \in \{1, \ldots, d\}$ and $t \in (0, T]$ define
\[
    F_t \phi(x) := \int_{\mathbb{R}^d} \phi(x + y) \partial_y p_t(y) \, dy = \int_{\mathbb{R}^d} \phi(y) \partial_y p_t(y - x) \, dy, \quad \phi \in C_b(\mathbb{R}^d), \ x \in \mathbb{R}^d.
\]
By Lemma 4.1,
\[
    \frac{\partial}{\partial x_i} E \phi(x + L_t) = \frac{\partial}{\partial x_i} \int \phi(y) p_t(y - x) \, dy = -F_t \phi(x)
\]
and because of (3) we know that
\[
    \|F_t \phi\|_\infty \leq \|\phi\|_\infty \int_{\mathbb{R}^d} |\partial_y p_t(y)| \, dy \leq c \|\phi\|_\infty t^{-1/\alpha}
\]
as well as
\[
    |F_t \phi(x) - F_t \phi(z)| = \int_{\mathbb{R}^d} (\phi(x + y) - \phi(z + y)) \partial_y p_t(y) \, dy \leq c \|\phi\|_{C^\gamma_0(\mathbb{R}^d)} |x - z|^{\gamma_0/\alpha} t^{-1/\alpha}
\]
for some absolute constant $c > 0$; therefore,
\[
    \|\partial_x, E \phi(\cdot + L_t)\|_{C^\gamma_0(\mathbb{R}^d)} = \|F_t \phi\|_{C^\gamma_0(\mathbb{R}^d)} \leq 2ct^{-1/\alpha}\|\phi\|_{C^\gamma_0(\mathbb{R}^d)} \quad \text{for all } \phi \in C^\gamma_0(\mathbb{R}^d).
\]
Applying this to $\phi(y) := g(s, y)$ (with $s \in (0, t)$ fixed) it follows from the differentiation lemma and (3) that $\partial_x u(t, x)$ exists for all $t \in (0, T]$ and
\[
    \partial_x u(t, x) = \int_{(0,t]} \partial_x E g(s, x + L_{t-s}) \, ds
\]
satisfies
\[
    \|\partial_x u\|_{C^\gamma_0(\mathbb{R}^d)} \leq 2c \|g\|_{C^\gamma_0(\mathbb{R}^d)} \int_0^T (T - s)^{-1/\alpha} \, ds =: C_1 T^{1-1/\alpha} \|g\|_{C^\gamma_0(\mathbb{R}^d)};
\]
(recall that, by assumption, $\alpha > 1$). In order to prove $\|\partial_x u\|_{C^{\gamma_0/2}(\mathbb{R}^d)} \leq C_2 T^{1-1/\alpha} \|g\|_{C^\gamma_0(\mathbb{R}^d)}$ we show that
\[
    \|F_t \phi\|_{C^{\gamma_0/2}(\mathbb{R}^d)} \leq c' \|\phi\|_{C^\gamma_0(\mathbb{R}^d)} t^{-(2+\gamma_0(1-\beta))/\alpha}, \quad \phi \in C^\gamma_0(\mathbb{R}^d),
\]
for some absolute constant $c' > 0$. By the differentiation lemma, we have
\[
    \partial_x F_t \phi(x) = \int_{\mathbb{R}^d} \phi(y) \partial_y p_t(y - x) \, dy
\]
for all $\phi \in C_b(\mathbb{R}^d)$, and so, by (3) and Lemma 4.1(iii),
\[
    \|\partial_x F_t \phi\|_\infty \leq c t^{-2/\alpha} \|\phi\|_\infty \quad \text{for all } k = 1, \ldots, d, \ \phi \in C_b(\mathbb{R}^d).
\]
If $\gamma_0 \in [1, 2]$, then we can use real interpolation to get $C^{\gamma_0/2}_b(\mathbb{R}^d) = (C^\gamma_0(\mathbb{R}^d), C^\gamma_0(\mathbb{R}^d))_{\gamma_0/2,\infty}$; cf. Triebel [29, Section 2.7.2] or Lunardi [17, Example 1.8]. From (17), (19) and the interpolation theorem, see e.g. [29, Section 1.3.3] or [17, Theorem 1.6], it follows that
\[
    \|F_t \phi\|_{C^{\gamma_0/2}(\mathbb{R}^d)} \leq \|F_t \phi\|_{C^\gamma_0(\mathbb{R}^d)} \|F_t \phi\|_{C^\gamma_0(\mathbb{R}^d)} \leq c \|\phi\|_\infty t^{-(2+\gamma_0(1-\beta))/\alpha}, \quad \phi \in C^\gamma_0(\mathbb{R}^d).
\]
If $\gamma_0 = 2$, then (20) is a direct consequence of (19). On the other hand, another application of the differentiation lemma shows that for any $\phi \in C^1_b(\mathbb{R}^d)$

$$\partial_{x_k} F_t \phi(x) = \int_{\mathbb{R}^d} \partial_{x_k} \phi(x + y) \partial_y p_t(y) \, dy$$

implying

$$\|\partial_{x_k} F_t \phi\|_\infty \leq c\|\phi\|_{C_t^2(\mathbb{R}^d)} t^{-\alpha}, \quad \phi \in C^1_b(\mathbb{R}^d).$$

Thus,

$$\|F_t \phi\|_{C^{\infty/2}_{\beta}(\mathbb{R}^d)} \leq c\|\phi\|_{C^1(\mathbb{R}^d)} t^{-(1-\beta)(1+\gamma_0/2)/\alpha - \beta/\alpha} = c\|\phi\|_{C^0(\mathbb{R}^d)} t^{-\kappa}. $$

for $\kappa := (2 + \gamma_0(1 - \beta))/(2\alpha)$; note that $\kappa < 1$ because of the balance condition (4). Applying the interpolation theorem once more to find that $F_t$ maps $C^\infty_{\beta}(\mathbb{R}^d) = (C^\infty(\mathbb{R}^d), C^1_b(\mathbb{R}^d))_{\beta, \infty}$ into $C^{\infty/2}_{\beta}(\mathbb{R}^d)$ and

$$\|F_t \phi\|_{C^{\infty/2}_{\beta}(\mathbb{R}^d)} \leq c\|\phi\|_{C^1(\mathbb{R}^d)} t^{-(1-\beta)(1+\gamma_0/2)/\alpha - \beta/\alpha} = c\|\phi\|_{C^0(\mathbb{R}^d)} t^{-\kappa}. $$

Step 2: $u$ solves (15). By [14, Theorem 4.1(ii)], we have

$$C^\infty_{\infty}(\mathbb{R}^d) := \{ f \in C^\infty_\infty(\mathbb{R}^d); f \in C^\infty(\mathbb{R}^d), \forall j = 1, \ldots, d : \partial_{x_j} f \in C^\infty(\mathbb{R}^d) \} \subseteq \mathcal{D}(A);$$

recall that $C^\infty(\mathbb{R}^d)$ is the space of continuous functions vanishing as $|x| \to \infty$. It follows from the proof of Step 1 that

$$x \mapsto P_t \phi(x) := \mathbb{E}\phi(x + L_t) \in C^\infty_{\infty}(\mathbb{R}^d) \subseteq C^\infty(\mathbb{R}^d) \subseteq \mathcal{D}(A)$$

for all $\epsilon > 0$ and $\phi \in C^\infty_{\beta}(\mathbb{R}^d) \cap C^\infty(\mathbb{R}^d)$. Since

$$\frac{d}{dt} P_t f = AP_t f \quad \text{for all} \quad f \in \mathcal{D}(A)$$

we find

$$\frac{d}{dt} P_{t+\epsilon} \phi = AP_{t+\epsilon} \phi$$

for all $t \geq 0$, $\epsilon > 0$ and $\phi \in C^\infty_{\beta}(\mathbb{R}^d) \cap C^\infty(\mathbb{R}^d)$ which means that

$$\frac{d}{dt} P_t \phi = AP_t \phi, \quad \tau > 0, \quad \phi \in C^\infty_{\beta}(\mathbb{R}^d) \cap C^\infty(\mathbb{R}^d).$$

Applying this identity to $\phi(x) := g(s, x)$ with $g \in C([0, T], C^\infty_{\beta}(\mathbb{R}^d))$ such that $g(s, \cdot) \in C^\infty(\mathbb{R}^d)$ for all $s \in [0, T]$ shows that $u(t, x) = \int_{0(t, t)} \mathbb{E}g(s, x + L_{t-s}) \, ds$ is a function in $C^\infty([0, T], C^\infty_{\beta}(\mathbb{R}^d))$ which solves (15), see [4, Lemma 7] for details.

For an arbitrary $g \in C([0, T], C^\infty_{\beta}(\mathbb{R}^d))$ fix a cut-off function $\chi \in C^\infty_c(\mathbb{R}^d)$ such that $1_{B(0, 1)} \leq \chi \leq 1_{B(0, 2)}$ and set $g_n(t, x) := g(t, x) \chi(x/n)$ for $t \in [0, T]$, $x \in \mathbb{R}^d$ and $n \in \mathbb{N}$. Since $g_n(t, \cdot)$ vanishes at infinity, it follows from the first part that $u_n(t, x) := \int_{0(t, t)} \mathbb{E}g_n(s, x + L_{t-s}) \, ds$ satisfies

$$\frac{\partial}{\partial t} u_n(t, x) = A_x u_n(t, x) + g_n(t, x), \quad u_n(0, x) = 0$$

i.e.

$$u_n(t, x) = \int_{0(t, t)} (A_x u_n(s, x) + g_n(s, x)) \, ds.$$

We are going to show that we can let $n \to \infty$ using the dominated convergence theorem. For any $R > 0$ and $t \in [0, T]$ we have

$$|u_n(t, x) - u(t, x)| \leq \sup_{s \in [0, T]} \sup_{|y+x| \leq R} |g_n(s, y) - g(s, y)| + 2T\|g\|_\infty P\left(\sup_{0 \leq s \leq T} \|L_s + x\| > R\right)$$
and, by Step 1,
\[
|\partial_x u_n(t, x) - \partial_x u(t, x)| \leq \int_0^t \int_{|y| \leq R} |g_n(s, y) - g(s, y)| \cdot |\partial_y p_{t-s}(y - x)| \, dy \, ds \\
+ 2\|g\|_\infty \int_0^t \int_{|y| > R} |\partial_y p_{t-s}(y - x)| \, dy \, ds.
\]
Therefore, we can combine the dominated convergence theorem, (3) and the fact that \( g_n \to g \) converges uniformly on compact sets to see that
\[
(23) \quad \sup_{t \in [0, T]} |u(t, x) - u_n(t, x)| + \sup_{t \in [0, T]} |\nabla_x u(t, x) - \nabla_x u_n(t, x)| \xrightarrow{n \to \infty} 0
\]
for all \( x \in \mathbb{R}^d \). Moreover, by Step 1,
\[
\|u_n\|_{C^{1, \gamma_0-1}(\mathbb{R}^d)} + \|u\|_{C^{1, \gamma_0-1}(\mathbb{R}^d)} \leq \|u_n\|_{C^{1, \gamma_0/2}(\mathbb{R}^d)} + \|u\|_{C^{1, \gamma_0/2}(\mathbb{R}^d)} \\
\leq C\|g\|_{C^0(\mathbb{R}^d)} + C\|g_n\|_{C^0(\mathbb{R}^d)} \leq 2C\|g\|_{C^0(\mathbb{R}^d)}.
\]
Observe that we have \( \int_{|y| \leq 1} |y|^{\gamma_0} \nu(dy) < \infty \) and for any function \( f \in C^{1, \gamma_0-1}(\mathbb{R}^d) \)
\[ |f(x + y) - f(x)| \leq 2\|f\|_\infty \quad \text{and} \quad |f(x + y) - f(x) - \nabla f(x) \cdot y| \leq \|f\|_{C^{1, \gamma_0/2}(\mathbb{R}^d)} |y|^{\gamma_0}. \]
Therefore, we can use dominated convergence and (23) to infer that
\[
\sup_{t \in [0, T]} |A_x u_n(t, x) + A_x u(t, x)| \xrightarrow{n \to \infty} 0 \quad \text{for all} \quad x \in \mathbb{R}^d.
\]
Letting \( n \to \infty \) in (22), we finally get
\[
u(t, x) = \int_{[0, t]} (A_x u(s, x) + g(s, x)) \, ds, \quad t \in [0, T], x \in \mathbb{R}^d.
\]
This shows that \( u \in C^1([0, T], C_b(\mathbb{R}^d)) \) solves (15). \( \square \)

4.4. Theorem. Let \((L_t)_{t \geq 0}\) be a \( d \)-dimensional Lévy process as in Theorem 2.1 with infinitesimal generator \((A, D(A))\), and \( b, g \in C([0, T], C^0_b(\mathbb{R}^d)) \) for \( \beta \in (0, 1] \) satisfying (4). For sufficiently small \( T > 0 \) there exists a map \( u \in C([0, T], \mathbb{R}^d) \cap C^1([0, T], C_b(\mathbb{R}^d)) \) solving the equation
\[
\begin{align*}
\frac{\partial}{\partial t} u(t, x) + A_x u(t, x) + b(t, x) \cdot \nabla_x u(t, x) &= -g(t, x) &\text{on} & [0, T) \times \mathbb{R}^d \\
&u(T, \cdot) = 0.
\end{align*}
\]
Moreover, \( u \) satisfies
\[
\|u\|_\infty + \|\nabla_x u\|_{C^0_b(\mathbb{R}^d)} + \|\nabla_x u\|_{C^{\gamma_0/2}(\mathbb{R}^d)} \leq c(T)\|g\|_{C^0(\mathbb{R}^d)}
\]
for some constant \( c(T) > 0 \) which does not depend on \( b, g \) and \( c(T) \to 0 \) as \( T \to 0 \).

Proof. We use Picard iteration to prove the existence of the solution. Choose \( T > 0 \) so small that \( 2C_T\|b\|_{C^0_b(\mathbb{R}^d)} \leq 1/2 \) where \( C_T \) is the constant appearing in (16), and set \( u^{(0)} := 0 \). By Lemma 4.2 and Remark 4.3(i) we can define iteratively \( u^{(n+1)} \in C([0, T], C^0_b(\mathbb{R}^d)) \cap C^1([0, T], C_b(\mathbb{R}^d)) \) such that (16) holds and
\[
\frac{\partial}{\partial t} u^{(n+1)}(t, x) + A_x u^{(n+1)}(t, x) = -b(t, x) \cdot \nabla_x u^{(n)}(t, x) - g(t, x), \quad u^{(n+1)}(T, \cdot) = 0.
\]
Using repeatedly (16) we find
\[
\|u^{(n+1)} - u^{(n)}\|_{C^0_b(\mathbb{R}^d)} \leq C_T\|b\cdot \nabla_x u^{(n)} - b \cdot \nabla_x u^{(n-1)}\|_{C^0_b(\mathbb{R}^d)} \\
\leq 2C_T\|b\|_{C^0_b(\mathbb{R}^d)} \|\nabla_x u^{(n)} - \nabla_x u^{(n-1)}\|_{C^0_b(\mathbb{R}^d)} \\
\leq \frac{1}{2}\|\nabla_x u^{(n)} - \nabla_x u^{(n-1)}\|_{C^0_b(\mathbb{R}^d)} \leq \ldots \leq \frac{1}{2^n}\|g\|_{C^0_b(\mathbb{R}^d)},
\]
and, therefore,
\[ \sum_{n \geq 1} \|u^{(n+1)} - u^{(n)}\|_{C_b^{1,\max(\beta, \gamma_0/2)}(\mathbb{R}^d)} < \infty. \]

Since \( C([0, T], C_b^{1,\max(\beta, \gamma_0/2)}(\mathbb{R}^d)) \) is a Banach space, completeness implies that there is some \( u \in C([0, T], C_b^{1,\max(\beta, \gamma_0/2)}(\mathbb{R}^d)) \) such that \( u^{(n)} \to u \) in \( C([0, T], C_b^{1,\max(\beta, \gamma_0/2)}(\mathbb{R}^d)) \). In particular, by (10),
\[ \|Au(t, \cdot) - Au^{(n)}(t, \cdot)\|_\infty \leq M\|u - u^{(n)}\|_{C_b^{1,\gamma_0-1}(\mathbb{R}^d)} \leq M\|u - u^{(n)}\|_{C_b^{1,\gamma_0/2}(\mathbb{R}^d)} \xrightarrow{n \to \infty} 0 \]
(note that \( \gamma_0 - 1 \leq \gamma_0/2 \) as \( \gamma_0 \in [1, 2] \)). Letting \( n \to \infty \) in
\[ u^{(n)}(t, x) = \int_t^T \left( A_x u^{(n)}(s, x) + b(s, x) \cdot \nabla_x u^{(n)}(s, x) + g(s, x) \right) \, ds \]
we get
\[ u(t, x) = \int_t^T (A_x u(s, x) + b(s, x) \cdot \nabla_x u(s, x) + g(s, x)) \, ds. \]

Using the above estimates, it is not difficult to see that \( u \) has all the desired properties. \( \square \)

We are now ready to prove Theorem 2.1.

Proof of Theorem 2.1. By considering each coordinate of \( X_t \in \mathbb{R}^d \) separately, we may assume, without loss of generality, that \( d = 1 \). Fix some sufficiently small \( \epsilon > 0 \) (we will specify \( \epsilon \) later in the proof), \( p \leq \gamma_\infty, T > 0 \) and set \( T_i := T \frac{i}{n}, i = 0, \ldots, L \).

If we choose \( L = L(\epsilon) \in \mathbb{N} \) sufficiently large, Theorem 4.4 shows that there exists a function \( u_i \in C([T_{i-1}, T_i], C_b^{1,\max(\beta, \gamma_0/2)}(\mathbb{R})) \cap C([T_{i-1}, T_i], C_b(\mathbb{R})) \) such that
\[ \frac{\partial}{\partial t} u_i(t, \cdot) + A_x u_i(t, \cdot) + b(t, \cdot) \frac{\partial}{\partial x} u_i(t, \cdot) = -b(t, \cdot) \quad \text{on } [T_{i-1}, T_i] \times \mathbb{R} \]
\( u_i(T_{i-1}, \cdot) = 0 \)

and
\[ \|u_i\|_\infty + \|\partial_x u_i\|_{C_b^p(\mathbb{R})} + \|\partial_x u_i\|_{C_b^{1,\gamma_0/2}(\mathbb{R})} \leq \epsilon. \]

Denote by \( (X^{(n)}_t)_{t \geq 0} \) the Euler–Maruyama approximation, i.e.
\[ X^{(n)}_t = x + \int_0^t b(\eta_n(s), X^{(n)}_{\eta_n(s)}) \, ds + L_t \]
where \( \eta_n(s) := T \frac{s}{n} \) for \( s \in [T \frac{n}{n}, T \frac{n+1}{n}] \). We are going to show that
\[ \mathbb{E} \left( \sup_{0 \leq t \leq T} |X^{(n)}_t - X^{(m)}_t|^p \right) \xrightarrow{n,m \to \infty} 0. \]

Applying Itô’s formula, cf. Proposition A.2, it follows from (26) that
\[ \int_{T_{i-1}}^t b(s, X^{(n)}_s) \, ds = u_i(T_{i-1}, X^{(n)}_{T_{i-1}}) - u_i(t, X^{(n)}_t) \]
\[ - \int_{T_{i-1}}^t \int_{|y| < 1} (u_i(s, X^{(n)}_s + y) - u_i(s, X^{(n)}_s)) \, N(dy, ds) \]
\[ - \int_{T_{i-1}}^t \int_{|y| \geq 1} (u_i(s, X^{(n)}_s + y) - u_i(s, X^{(n)}_s)) \, N(dy, ds) \]
\[ - \int_{T_{i-1}}^t (b(\eta_n(s), X^{(n)}_{\eta_n(s)}) - b(s, X^{(n)}_s)) \partial_x u_i(s, X^{(n)}_s) \, ds \]
for any $t \in [T_{i-1}, T_i], i = 0, \ldots, L$, where $\tilde{N}(dy, ds) = N(dy, ds) - \nu(dy) \, ds$ denotes the compensated jump measure of the Lévy process $(L_t)_{t \geq 0}$. Fix $i \in \{0, \ldots, L\}$, $t \in [T_{i-1}, T_i]$ and $m, n \in \mathbb{N}$. Observing that

$$|X_t^{(m)} - X_t^{(n)}| \leq |X_{T_{i-1}}^{(m)} - X_{T_{i-1}}^{(n)}| + \int_{T_{i-1}}^t b(\eta_m(s), X_{\eta_m(s)}^{(m)}) \, ds - \int_{T_{i-1}}^t b(\eta_n(s), X_{\eta_n(s)}^{(n)}) \, ds,$$

we get

$$|X_t^{(m)} - X_t^{(n)}|^p \leq C|X_{T_{i-1}}^{(m)} - X_{T_{i-1}}^{(n)}|^p + C(I_1 + I_2 + I_3 + I_{4.1} + I_{4.2} + I_5)$$

for some constant $C = C(p) > 0$ and the following (integral) expressions

$$I_1 := \left| u_i(T_{i-1}, X_{T_{i-1}}^{(m)}) - u_i(T_{i-1}, X_{T_{i-1}}^{(n)}) \right|^p$$

$$I_2 := \int_{T_{i-1}}^t \int_{|y| < 1} H_s(y) \tilde{N}(dy, ds) \left| u_i(t, X_t^{(m)}) - u_i(t, X_t^{(n)}) \right|^p$$

$$I_3 := \int_{T_{i-1}}^t \int_{|y| \geq 1} H_s(y) N(dy, ds) \left| u_i(t, X_t^{(m)}) - u_i(t, X_t^{(n)}) \right|^p$$

$$I_{4.1} := \int_{T_{i-1}}^t (b(\eta_m(s), X_{\eta_m(s)}^{(m)}) - b(s, X_s^{(n)})) \partial_x u_i(s, X_s^{(n)}) \, ds$$

$$I_{4.2} := \int_{T_{i-1}}^t (b(\eta_n(s), X_{\eta_n(s)}^{(n)}) - b(s, X_s^{(m)})) \partial_x u_i(s, X_s^{(m)}) \, ds$$

$$I_5 := \int_{T_{i-1}}^t (b(\eta_m(s), X_{\eta_m(s)}^{(m)}) - b(s, X_s^{(n)})) \, ds + \int_{T_{i-1}}^t (b(\eta_n(s), X_{\eta_n(s)}^{(n)}) - b(s, X_s^{(m)})) \, ds$$

and

$$H_s(y) := (u_i(s, X_s^{(m)} + y) - u_i(s, X_s^{(m)})) - (u_i(s, X_s^{(n)} + y) - u_i(s, X_s^{(n)})).$$

We estimate the terms separately. Because of (27), we have $\|\partial_x u_i\|_\infty \leq \epsilon$, and therefore an application of the mean value theorem shows

$$I_1 \leq \epsilon^p \left| X_{T_{i-1}}^{(m)} - X_{T_{i-1}}^{(n)} \right|^p + \epsilon^p \left| X_t^{(m)} - X_t^{(n)} \right|^p.$$

Moreover, it follows from (27) and the fact that $b(t, x)$ is $\beta$-Hölder-continuous with respect to $x$ and $\eta$-Hölder continuous with respect to $t$ that

$$I_{4.1} \leq C \left| \int_{T_{i-1}}^t (b(\eta_m(s), X_{\eta_m(s)}^{(m)}) - b(s, X_s^{(n)})) \partial_x u_i(s, X_s^{(n)}) \, ds \right|^p$$

$$+ C \left| \int_{T_{i-1}}^t (b(\eta_n(s), X_{\eta_n(s)}^{(n)}) - b(s, X_s^{(m)})) \partial_x u_i(s, X_s^{(m)}) \, ds \right|^p$$

$$\leq C_4 n^{-\beta p} + C_5 \epsilon^p \sup_{T_{i-1} \leq t \leq T_i} |X_{\eta_m(t)}^{(n)} - X_t^{(n)}|^\\beta.$$

The same estimate holds for $I_{4.2}$ with $n$ replaced by $m$. In exactly the same fashion we get

$$I_5 \leq C_5 n^{-\beta p} + C_6 \epsilon^p \sup_{T_{i-1} \leq t \leq T_i} |X_{\eta_m(t)}^{(n)} - X_t^{(n)}|^\\beta + C_7 \sup_{T_{i-1} \leq t \leq T_i} |X_{\eta_n(t)}^{(m)} - X_t^{(m)}|^\\beta.$$

In order to estimate $I_2$ and $I_3$, we use Taylor’s formula and (27)

$$|H_s(y)| \leq |X_s^{(m)} - X_s^{(n)}| \int_0^1 \left| \frac{\partial}{\partial x} u_i(s, X_s^{(m)} + y + \tau(X_s^{(m)} - X_s^{(n)})) \right| d\tau$$

$$\leq \epsilon \min \{ |X_s^{(m)} - X_s^{(n)}| |y|^{\gamma/2}, 2 |X_s^{(m)} - X_s^{(n)}| \}.$$
Applying the Burkholder–Davis–Gundy inequality, cf. Theorem 3.1, we find
\[
E \left( \sup_{T_{i-1} \leq t \leq T_i} |I_2| \right) \\
\leq C_2 E \left( \int_{T_{i-1}}^{T_i} \int_{|y| < 1} |H_i(s, y)|^2 \nu(dy) ds \right)^{p/2} + C_2 E \left( \int_{T_{i-1}}^{T_i} \int_{|y| < 1} |H_i(s, y)|^2 \nu(dy) ds \right) \mathbb{1}_{[2, \infty)}(p)
\]
\[
\leq C'_2 \epsilon^p \left( \int_{|y| < 1} |y| \nu(dy) \right)^{p/2} + \int_{|y| < 1} |y| \nu(dy) E \left( \sup_{T_{i-1} \leq t \leq T_i} |X^{(m)}_s - X^{(n)}_s|^p \right)
\]
for some absolute constants $C_2, C'_2 > 0$. In order to estimate $I_3$ we distinguish between two cases. If $p \in (0, 1)$, then $(x + y)^p \leq x^p + y^p$ for all $x, y \geq 0$, and therefore by (29)
\[
E \left( \sup_{T_{i-1} \leq t \leq T_i} |I_3| \right) = E \left( \sup_{T_{i-1} \leq t \leq T_i} \left| \sum_{s \in [T_{i-1}, t]} H_i(s, \Delta L_s) \right|^p \right)
\]
\[
\leq E \left( \sum_{s \in [T_{i-1}, T_i]} |H_i(s, \Delta L_s)|^p \right)
\]
\[
= E \left( \int_{T_{i-1}}^{T_i} \int_{|y| \geq 1} |H_i(s, y)|^p N(dy, ds) \right)
\]
\[
= E \left( \int_{T_{i-1}}^{T_i} \int_{|y| \geq 1} |H_i(s, y)|^p \nu(dy) ds \right)
\]
\[
\leq 2p \epsilon^p \nu(B(0, 1)^c) E \left( \sup_{T_{i-1} \leq t \leq T_i} |X^{(m)}_t - X^{(n)}_t|^p \right).
\]
If $p \geq 1$, then $\int_{|y| \geq 1} |y| \nu(dy) < \infty$, and so
\[
I_3 \leq C \int_{T_{i-1}}^{T_i} \int_{|y| \geq 1} H_i(s, y) \tilde{N}(dy, ds)^p + C \int_{T_{i-1}}^{T_i} \int_{|y| \geq 1} H_i(s, y) \nu(dy) ds \right|^p.
\]
By the Burkholder–Davis–Gundy inequality and (29), there exist absolute constants $C_3, C'_3 > 0$ such that
\[
E \left( \sup_{T_{i-1} \leq t \leq T_i} I_3 \right)
\]
\[
\leq C_3 E \left( \int_{T_{i-1}}^{T_i} \int_{|y| \geq 1} |H_i(s, y)|^2 \nu(dy) ds \right)^{p/2} + C_3 E \left( \int_{T_{i-1}}^{T_i} \int_{|y| \geq 1} |H_i(s, y)|^p \nu(dy) ds \right)
\]
\[
\leq C'_3 \epsilon^p \left( \nu(B(0, 1)^c)^{p/2} + \nu(B(0, 1)^c) \right) E \left( \sup_{T_{i-1} \leq t \leq T_i} |X^{(m)}_t - X^{(n)}_t|^p \right).
\]
Combining the above estimates we conclude that there exist constants $c_1, c_2 > 0$ (not depending on $\epsilon, m, n, L, i$) such that
\[
E \left( \sup_{T_{i-1} \leq t \leq T_i} |X^{(m)}_t - X^{(n)}_t|^p \right)
\]
\[
\leq \epsilon^p c_1 E \left( \sup_{T_{i-1} \leq t \leq T_i} |X^{(m)}_t - X^{(n)}_t|^p \right) + c_2 E \left( |X^{(m)}_{T_{i-1}} - X^{(n)}_{T_{i-1}}|^p \right) + \frac{c_2}{mp^q} + \frac{c_2}{m(p^q)}
\]
\[
+ c_2 E \left( \sup_{T_{i-1} \leq t \leq T_i} |X^{(n)}_{\eta_n(t)} - X^{(n)}_t|^p \right) + c_2 E \left( \sup_{T_{i-1} \leq t \leq T_i} |X^{(n)}_{\eta_n(t)} - X^{(m)}_{\eta_n(t)}|^p \right).
\]
Thus,

\[
(1 - \epsilon^p c_1) \mathbb{E} \left( \sup_{T_{i-1} \leq t \leq T_i} |X_t^{(m)} - X_t^{(n)}|^p \right)
\]

\[
\leq c_2 \mathbb{E} \left( |X_{T_{i-1}}^{(m)} - X_{T_{i-1}}^{(n)}|^p \right) + \frac{2c_2}{N^p} \sup_{n \geq N} \mathbb{E} \left( \sup_{T_{i-1} \leq t \leq T_i} |X_t^{(n)} - X_t^{(n,p^\beta)}|^p \right)
\]

for any \( m, n \geq N \). Choose \( \epsilon > 0 \) so small that \( 1 - \epsilon^p c_1 \geq 1/2 \). By the very definition of the Euler–Maruyama approximation, we have

\[
X_t^{(n)}(t) - X_t^{(n)} = \int_{\eta_n(t)}^t b(\eta_n(s), X_s^{(n)}) \, ds + \int_{\eta_n(t)}^t \eta_n(s) \, ds.
\]

Using \( L_t - L_{\eta_n(t)} \overset{d}{=} L_{t - \eta_n(t)} \) and fractional moment estimates for Lévy processes, see [11, Section 5], we can find a constant \( c_3 > 0 \) such that

\[
\mathbb{E} \left( \sup_{T_{i-1} \leq t \leq T_i} |X_t^{(n)} - X_t^{(n)}|^p \right) \leq (2\|b\|_\infty)^p n^{-p\beta} + 2n^p \mathbb{E} \left( \sup_{T_{i-1} \leq t \leq T_i} |L_{t - \eta_n(t)}|^p \right)
\]

\[
\leq (2\|b\|_\infty)^p n^{-p\beta} + 2n^p \mathbb{E} \left( \sup_{s \leq 1/n} |L_s|^p \right)
\]

\[
\leq c_3 n^{-\min\{1,p\beta/\gamma_0\}}.
\]

Hence,

\[
\mathbb{E} \left( \sup_{T_{i-1} \leq t \leq T_i} |X_t^{(m)} - X_t^{(n)}|^p \right) \leq 2c_2 \mathbb{E} \left( |X_{T_{i-1}}^{(m)} - X_{T_{i-1}}^{(n)}|^p \right) + 8c_2 c_3 n^{-\min\{1,p\beta/\gamma_0,p\eta\}}.
\]

Using this estimate iteratively for \( i = 1, \ldots, L \), we conclude that there exists a constant \( c_4 = c_4(L) > 0 \) such that

\[
\mathbb{E} \left( \sup_{T_{i-1} \leq t \leq T_i} |X_t^{(m)} - X_t^{(n)}|^p \right) \leq c_4 n^{-\min\{1,p\beta/\gamma_0,p\eta\}}
\]

for all \( m, n \geq N \). Thus,

\[
(30) \quad \mathbb{E} \left( \sup_{0 \leq t \leq T} |X_t^{(m)} - X_t^{(n)}|^p \right) \leq \sum_{i=1}^L \mathbb{E} \left( \sup_{T_{i-1} \leq t \leq T_i} |X_t^{(m)} - X_t^{(n)}|^p \right) \leq c_4 L N^{-\min\{1,p\beta/\gamma_0,p\eta\}}
\]

for all \( m, n \geq N \); this means, in particular, that

\[
\mathbb{E} \left( \sup_{0 \leq t \leq T} |X_t^{(m)} - X_t^{(n)}|^p \right) \overset{m,n \to \infty}{\longrightarrow} 0.
\]

This implies that there exists a stochastic process \( (X_t)_{t \in [0,T]} \) and a subsequence \( (n_k)_{k \in \mathbb{N}} \) such that \( \sup_{t \in [0,T]} |X_t^{(n_k)} - X_t| \to 0 \) almost surely as \( k \to \infty \), cf. Lemma A.3. Letting \( k \to \infty \) in

\[
X_t^{(n_k)} - x = \int_0^t b(\eta_{n_k}(s), X_s^{(n_k)}) \, ds + L_t
\]

we find

\[
X_t - x = \int_0^t b(s, X_s) \, ds + L_t.
\]

Moreover, it follows from Fatou’s lemma and (30) that

\[
\mathbb{E} \left( \sup_{0 \leq t \leq T} |X_t - X_t^{(n)}|^p \right) \leq c_4 n^{-\min\{1,p\beta/\gamma_0,p\eta\}}.
\]

This proves the existence of a solution to (5) satisfying (6).
In order to show uniqueness, we assume that \((Y_t)_{t \geq 0}\) is a further solution to (5). Applying Itô’s formula to \(u_i(t, Y_t)\) with \(u_i\) as in (26), we get a similar expression as in (28) for \(\int_0^t b(s, Y_s) \, ds\), and a very similar reasoning as in the first part of the proof to shows that

\[
\mathbb{E} \left( \sup_{0 \leq t \leq T} |Y_t - X_t^{(n)}|^p \right) \leq c_s n^{-\min\{1, p^{\beta/\gamma}, p\eta\}}
\]

for all \(n \in \mathbb{N}\). Thus, by Fatou’s lemma,

\[
\mathbb{E} \left( \sup_{0 \leq t \leq T} |Y_t - X_t|^p \right) = 0.
\]

\[\square\]

Proof of Corollary 2.5. From [27, Theorem 1.3] it follows that the semigroup \(P_t \phi(x) := \mathbb{E} \phi(x + L_t)\) satisfies

\[
\|\nabla P_t \phi\|_\infty \leq c t^{-\alpha} \|\phi\|_\infty \quad \text{for all } \phi \in \mathcal{B}_b(\mathbb{R}^d).
\]

By Lemma 4.1, this implies \(\int_{\mathbb{R}^d} |\partial_t p_t(x)| \, dx \leq c t^{-\alpha}\) for all \(i \in \{1, \ldots, d\}\). Applying Theorem 2.1 finishes the proof.

\[\square\]

The remaining part of this section is devoted to the proof of Corollary 2.6. From now on \((S_t)_{t \geq 0}\) denotes a subordinator with Laplace exponent (Bernstein function) \(f\), \((B_t^{(d)})_{t \geq 0}\) is a \(d\)-dimensional Brownian motion and \(L_t^{(d)} := B_{S_t}\) is the process subordinate to Brownian motion. Note that \((L_t^{(d)})_{t \geq 0}\) is a \(d\)-dimensional Lévy process with characteristic exponent \(\psi(\xi) = f(|\xi|^2), \xi \in \mathbb{R}^d\). If \(f\) satisfies the Hartman–Wintner condition

\[
\lim_{r \to \infty} \frac{f(r)}{r \log(1 + r)} = \infty,
\]

then \(L_t^{(d)}\) has for all \(t > 0\) a transition density \(p_t^{(d)}\) see e.g. [9], and \(p_t^{(d)}\) is isotropic, i.e. \(p_t^{(d)}(x)\) depends only on \(|x|\); in abuse of notation we write \(p_t^{(d)}(x) = p_t^{(d)}(|x|)\). Using polar coordinates one finds, cf. Matheron [18, pp. 33–4] and [15],

\[
\frac{d}{dr} p_t^{(d)}(r) = -2\pi r p_t^{(d-2)}(r), \quad r > 0, \quad d \geq 1.
\]

4.5. Lemma. Let \(f\) be a Bernstein function satisfying the Hartman–Wintner condition (32), and let \((L_t^{(d)})_{t \geq 0}\) be a \(d\)-dimensional Lévy process with characteristic exponent \(\psi(\xi) = f(|\xi|^2), \xi \in \mathbb{R}^d\), for \(d \geq 1\). If there exist constants \(c > 0, \alpha > 0\) such that

\[
\mathbb{E} \left( \left|L_t^{(d+2)}\right|^{-1}\right) \leq c t^{-\alpha} \quad \text{for all } t \in (0, T],
\]

then the transition density of \(L_t^{(d)}\), \(t > 0\), satisfies (3).

Proof. Denote by \(p_t^{(d)}(x) = p_t^{(d)}(|x|), x \in \mathbb{R}^d\), the transition density of \((L_t^{(d)})_{t \geq 0}\). Using polar coordinates and (33), we find for each \(i = 1, \ldots, d\),

\[
\int_{\mathbb{R}^d} |\partial_i p_t^{(d)}(x)| \, dx \leq 2\pi \int_{\mathbb{R}^d} |x| p_t^{(d-2)}(|x|) \, dx = 2\pi \sigma_d \int_{(0, \infty)} r p_t^{(d+2)}(r) r^{d-1} \, dr
\]

\[
= 2\pi \sigma_d \int_{(0, \infty)} \frac{1}{r} p_t^{(d-2)}(r) r^{d-1} \, dr
\]

\[
= \frac{\sigma_d}{\sigma_{d+2}} \int_{\mathbb{R}^{d+2}} \frac{1}{|x|} p_t^{(d+2)}(|x|) \, dx
\]

\[
= \frac{\sigma_d}{\sigma_{d+2}} \mathbb{E} \left( \left|L_t^{(d+2)}\right|^{-1}\right)
\]

where \(\sigma_d\) is the surface volume of the unit sphere \(S^{d-1} \subseteq \mathbb{R}^d\). Hence, by (34),

\[
\int_{\mathbb{R}^d} |\partial_i p_t(x)| \, dx \leq c t^{-\alpha} \quad \text{for all } t \in (0, T], \quad i = 1, \ldots, d.
\]

\[\square\]
Proof of Corollary 2.6. By assumption, there exists some Brownian motion \( cf. [3, Theorem 3.17] \). As (35) \( \gamma > \alpha \) is the density of \( |L| \), that the density of \( \gamma \), and therefore \( \alpha \) guarantees that the assumptions of Theorem 2.1 are satisfied for \( \alpha \) such that

\[
\int_{\mathbb{R}^d} |\partial^2_x p_t(x)| \, dx \leq c't^{-\gamma/\alpha} \quad \text{for all } \gamma \in \mathbb{N}_0, \, |\gamma| \leq k, \, t \in (0, T].
\]

Proof of Corollary 2.6. By assumption, there exists some \( c > 0 \) such that \( \psi(\xi) \geq c|\xi|^{2\rho} \) for large \( |\xi| \), and therefore

\[
p_t(x) = (2\pi)^{-d} \int_{\mathbb{R}^d} e^{-ix \cdot \xi} e^{-t \psi(\xi)} \, d\xi, \quad x \in \mathbb{R}^d
\]

is the density of \( L_t \); by the differentiation lemma, \( p_t \) is twice continuously differentiable. To prove that the density of \( L_t = L_t^{(d)} = B_{S_t}^{(d)}, \, t > 0, \) satisfies (3) for \( \alpha := 2\rho \), it suffices by Lemma 4.5 to show that (34) holds for \( \alpha = 2\rho \). To this end, we recall that for any \( \kappa > 0 \) there exists a constant \( C > 0 \) such that

\[
(35) \quad E(S_t^{-\kappa}) \leq C \min\{t, \, 1\}^{-\kappa/\rho}, \quad t \geq 0,
\]

cf. [3, Theorem 3.17]. As \( (B_t^{(d)})_{t \geq 0} \) and \( (S_t)_{t \geq 0} \) are independent, we get by the scaling property of Brownian motion

\[
E \left( |L_t^{(d+2)}|^{-1} \right) = E \left( |B_{S_t}^{(d+2)}|^{-1} \right) = E \left( |\sqrt{S_t} B_1^{(d+2)}|^{-1} \right) = E \left( S_t^{-1/2} \right) E \left( |B_1^{(d+2)}|^{-1} \right).
\]

Note that

\[
E \left( |B_1^{(d+2)}|^{-1} \right) = \int_{\mathbb{R}^d} \frac{1}{|z|^{(d+2)/2}} \, dz < \infty
\]

as \( 1 < d + 2 \). Because of (35) we get (34), hence (3), for \( \alpha = 2\rho \).

Finally, since

\[
\int_{(0,1)} r^{\delta_0} \mu(dr) + \int_{(1,\infty)} r^{\delta_\infty} \mu(dr) < \infty
\]

implies

\[
\int_{B(0,1)} |y|^{2\delta_0} \nu(dy) + \int_{B(0,1)^c} |y|^{2\delta_\infty} \nu(dy) < \infty,
\]

the assumptions of Theorem 2.1 are satisfied for \( \alpha := 2\rho, \, \gamma_0 := 2\delta_0, \, \gamma_\infty := 2\delta_\infty \), and this completes the proof.

\[ \square \]

5. Examples

The following lemma is useful if one wants to verify the assumptions of Theorem 2.1 and Corollary 2.6. It shows how the growth of the characteristic exponent at 0 (resp., at infinity) is related to the existence of moments of the Lévy measure at infinity (resp., at 0).

5.1. Lemma. Let \( \psi: \mathbb{R}^d \to \mathbb{C} \) be a continuous negative definite function with Lévy triplet \( (\ell, 0, \nu) \), and let \( f \) be a Bernstein function with characteristics \( (0, \mu) \).

(i) If \( \mu(dy) \geq c|y|^{-1-\rho} \, dy \) on \( B(0,1) \) for some \( c > 0 \) and \( \rho \in (0,1) \), then

\[
\liminf_{\lambda \to \infty} \frac{f(\lambda)}{\lambda^\rho} > 0.
\]

(ii) (a) \( f(r) \leq cr^\delta \) for all \( r \geq 1 \) implies \( \int_{(0,1)} r^{1+\epsilon} \mu(dr) < \infty \) for any \( \epsilon > 0 \).

(b) \( f(r) \leq cr^\delta \) for all \( r \in [0,1] \) implies \( \int_{(1,\infty)} r^{\delta-\epsilon} \mu(dr) < \infty \) for any \( \epsilon > 0 \).

(iii) (a) \( \Re \psi(\xi) \leq c|\xi|^\alpha \) for all \( |\xi| \geq 1 \) implies \( \int_{B(0,1)} |y|^{\alpha+\epsilon} \nu(dy) < \infty \) for any \( \epsilon > 0 \).

(b) \( \Re \psi(\xi) \leq c|\xi|^\alpha \) for all \( |\xi| \leq 1 \) implies \( \int_{B(0,1)^c} |y|^{\alpha-\epsilon} \nu(dy) < \infty \) for any \( \epsilon > 0 \).
Proof. (i) Fix $\lambda > 1$. As $1 - e^{-\lambda r} \geq 0$ for $r \geq 0$, we have

$$f(\lambda) = \int_{(0, \infty)} (1 - e^{-\lambda r}) \mu(dr) \geq \int_{(0, \lambda^{-1})} (1 - e^{-\lambda r}) \mu(dr) \geq c \int_{(0, \lambda^{-1})} (1 - e^{-\lambda r}) \frac{dr}{r^{1+\rho}}.$$

Changing variables according to $s := \lambda r$, we find that the right-hand side equals $c'\lambda^\rho$ for some strictly positive constant $c'$.

(ii)(a) If $\delta + \epsilon \geq 1$ there is nothing to show since $\int_{(0,1)} r \mu(dr) < \infty$. For $\delta + \epsilon \in (0, 1)$ we use the formula

$$(36) \quad r^{\delta + \epsilon} = \frac{\delta + \epsilon}{\Gamma(1 - \delta - \epsilon)} \int_{(0, \infty)} (1 - e^{-rs}) \frac{ds}{s^{1+\delta+\epsilon}}.$$

It is not difficult to see that this implies

$$r^{\delta + \epsilon} \leq C \int_{(1, \infty)} (1 - e^{-rs}) \frac{ds}{s^{1+\delta+\epsilon}} \quad \text{for all} \quad r \in (0, 1)$$

for some constant $C > (\delta + \epsilon)/\Gamma(1 - \delta - \epsilon)$. Applying Tonelli's theorem we find

$$\int_{(0,1)} r^{\delta + \epsilon} \mu(dr) \leq C \int_{(1, \infty)} \int_{(0,1)} (1 - e^{-rs}) \mu(dr) \frac{ds}{s^{1+\delta+\epsilon}} \leq C \int_{(1, \infty)} f(s) \frac{ds}{s^{1+\delta+\epsilon}} ds < \infty.$$

(ii)(b) Since $f$ grows at most linearly and $\int_{|y| \geq 1} \mu(dy) < \infty$, we can assume without loss of generality that $\delta \in (0, 1]$ and $\delta - \epsilon > 0$. It follows from (36) (with $\epsilon$ replaced by $-\epsilon$) that there exists a constant $c' > 0$ such that

$$r^{\delta - \epsilon} \leq c' \int_{(0,1)} (1 - e^{-rs}) \frac{ds}{s^{1+\delta-\epsilon}} \quad \text{for all} \quad r \geq 1.$$

Applying Tonelli’s theorem once again shows

$$\int_{(1, \infty)} r^{\delta - \epsilon} \mu(dr) \leq c' \int_{(0,1)} \frac{f(s)}{s^{1+\delta-\epsilon}} ds < \infty.$$

(iii) The reasoning is very similar to the proof of (ii); use that for $\alpha \in (0, 2)$

$$|\xi|^\alpha = \frac{\alpha^{2\alpha-1}}{\pi^{d/2}} \frac{\Gamma\left(\frac{\alpha+d}{2}\right)}{\Gamma\left(1-\frac{d}{2}\right)} \int_{\mathbb{R}^d \setminus \{0\}} (1 - \cos(\xi y)) \frac{dy}{|y|^{d+\alpha}}, \quad \xi \in \mathbb{R}^d;$$

see also [14, Lemma A.1].

Combining Lemma 5.1 with Corollary 2.6 we get the following statement.

5.2. Example. Let $(L_t)_{t \geq 0}$ be a $d$-dimensional Lévy process with one of the following characteristic exponents $\psi : \mathbb{R}^d \to \mathbb{R}$:

(i) $\psi(\xi) = |\xi|^\alpha$ for $\alpha \in (1, 2);$ (isotropic stable)

(ii) $\psi(\xi) = (|\xi|^2 + m^2)^{\alpha/2} - m^\alpha$ for $\alpha \in (1, 2), m > 0;$ (relativistic stable)

(iii) $\psi(\xi) = -(|\xi|^2 + m^2)^{\alpha/2} \cos \left( \alpha \arctan \frac{\langle \xi \rangle}{m} \right) + m^\alpha$ for $\alpha \in (1, 2), m > 0;$ (tempered stable)

(iv) $\psi(\xi) = (|\xi|^2 + m^2)\alpha - (m^2)\alpha$ for some $\alpha \in (1, 2), m > 0;$ (Lamperti stable)

here $(t)_\alpha := \Gamma(t + \alpha)/\Gamma(t)$ denotes the Pochhammer symbol.

If $b : (0, \infty) \times \mathbb{R}^d \to \mathbb{R}^d$ is a bounded function which is $\beta$-Hölder continuous with respect to $t$ for some $\eta \in (0, 1]$ and $\beta > \frac{d}{\alpha} - 1$, then the SDE

$$dX_t = b(t, X_{t-}) dt + dL_t, \quad X_0 = x \in \mathbb{R}^d,$$

has a pathwise unique strong solution. For any $p < \gamma_\infty$ and $T > 0$ there exists a constant $C > 0$ such that

$$E \left( \sup_{t \leq T} |X_t - X_t^{(n)}|^p \right) \leq C n^{-\min\{1, p\beta/\alpha, pq\}} \quad \text{for all} \quad n \geq 1.$$
where we set $\gamma_\infty := \alpha$ for the exponent (i) and $\gamma_\infty := \infty$ for all other exponents (ii)–(iv).

5.3. **Remark.** (i) The Lévy measure of a tempered stable Lévy process is given by

$$\nu(dy) = \frac{1}{2} \frac{\alpha(\alpha - 1)}{\Gamma(2 - \alpha)} e^{-|y| \gamma} |y|^{-\alpha - \gamma} dy \quad \text{for } \alpha \in (1, 2]$$

cf. [10] or [13, Example 5.7]. Note that different authors use different names for this process, e.g. KoBoL process, CGMY process and truncated Lévy process.

(ii) Example 5.2 can be also shown by combining Theorem 2.1 with the heat kernel estimates established in [13], see also [12]; in fact, any continuous negative definite function listed in [13, Table 2] satisfies the assumptions of Theorem 2.1.

We close this section with a further example; it covers many interesting and important Lévy processes.

5.4. **Example.** Let $(L_t)_{t \geq 0}$ be a $d$-dimensional Lévy process with characteristic exponent $\psi$ and Lévy triplet $(0, 0, \nu)$. Assume that $\nu$ is of the form

$$\nu(A) = \int_{S^{d-1}} \int_{(0, \infty)} 1_A(r \rho) Q(r) dr \mu(d \rho), \quad A \in \mathcal{B}(\mathbb{R}^d \setminus \{0\})$$

for a finite measure $\mu$ on the unit sphere $S^{d-1}$ in $\mathbb{R}^d$ such that the support of $\mu$ is not contained in $S^{d-1} \cap V$ where $V \subseteq \mathbb{R}^d$ is a lower-dimensional subspace, and a function $Q : (0, \infty) \to (0, \infty)$ satisfying

$$0 < \liminf_{r \to 0} \frac{Q(r)}{r^{1+\gamma_0}} \leq \limsup_{r \to 0} \frac{Q(r)}{r^{1+\gamma_0}} < \infty \quad \text{and} \quad \limsup_{r \to \infty} \frac{Q(r)}{r^{1+\gamma_\infty}} < \infty$$

for some $\gamma_0 \in (1, 2]$ and $\gamma_\infty > 0$. If $b : (0, \infty) \times \mathbb{R}^d \to \mathbb{R}^d$ is a bounded function which is $\beta$-Hölder continuous with respect to $x$ and $\eta$-Hölder continuous with respect to $t$ for some $\eta \in (0, 1]$ and $\gamma_0(1 + \beta) > 2$,

then the SDE

$$dX_t = b(t, X_{t-}) dt + dL_t, \quad X_0 = x \in \mathbb{R}^d,$$

has a pathwise unique strong solution. For any $p < \gamma_\infty$ and $T > 0$ there exists a constant $C > 0$ such that

$$\mathbb{E} \left( \sup_{t \leq T} |X_t - X_t^{(n)}|^p \right) \leq C n^{-\min\{1, p\beta/\gamma_0, p\eta\}} \quad \text{for all } n \geq 1.$$

Since each of the processes in Example 5.2 has a Lévy measure of the form (37), Example 5.4 is more general than Example 5.2. Let us point out that Example 5.4 includes truncated stable Lévy processes, i.e. $Q(r) = r^{-1-\alpha} 1_{(0,1)}(r)$, and layered stable Lévy processes, i.e. $Q(r) = r^{-1-\alpha} 1_{(0,1)}(r) + r^{-1-\beta} 1_{[1, \infty)}(r)$.

**Proof of Example 5.4.** Some elementary calculations show that $e^{-1} |\xi|^{\gamma_0} \leq \Re \psi(\xi) \leq c |\xi|^{\gamma_0}$ for some constant $c \in (0, \infty)$ as $|\xi| \to \infty$. Moreover, by the very definition of $\nu$, $\int_{|y| \leq 1} |y|^{\gamma_\infty - \epsilon} \nu(dy) + \int_{|y| > 1} |y|^{\gamma_\infty - \epsilon} \nu(dy) < \infty$ for any $\epsilon > 0$. Applying Corollary 2.5 with $f(r) := r^{\gamma_\infty}$ finishes the proof. \qed

**APPENDIX A.**

For the proof of our main results we use the following auxiliary statements.

A.1. **Proposition** (differentiation lemma for parameter-dependent integrals). Let $(X, A, \mu)$ be a $\sigma$-finite measure space and $\phi : (a, b) \times X \to \mathbb{R}$ a measurable function with the following properties.

(i) $\int_X |\phi(s, x)| \mu(dx) < \infty$ for all $s \in (a, b)$.

(ii) $s \mapsto \phi(s, x)$ is differentiable for all $x \in X$ and

$$\int_{(a,b)} \int_X |\partial_s \phi(s, x)| \mu(dx) ds < \infty.$$

(iii) $s \mapsto \int_X \partial_s \phi(s, x) \mu(dx)$ is continuous.
Then $F(s) := \int_X \phi(s, x) \mu(dx)$ is continuously differentiable for all $s \in (a, b)$ and

$$F'(s) = \int_X \partial_s \phi(s, x) \mu(dx), \quad s \in (a, b).$$

Note that (iii) is always satisfied if $t \mapsto \partial_t \phi(t, x)$ is continuous and there exists a function $w \in L^1(\mu)$ such that $|\partial_t \phi(t, x)| \leq w(x)$ for all $t \in (a, b)$ and $x \in X$; therefore, Proposition A.1 extends the standard version of the differentiation lemma which can be found, for instance, in [25, Theorem 12.5].

**Proof of Proposition A.1.** Fix $s \in (a, b)$. Applying the fundamental theorem of calculus and Fubini’s theorem, we find

$$F(s + h) - F(s) = \int_X (\phi(s + h, x) - \phi(s, x)) \mu(dx) = \int_X \int_s^{s+h} \partial_r \phi(r, x) \mu(dx) dr$$

for all $h \in \mathbb{R}$. By assumption, $f(r) := \int_X \partial_x \phi(r, x) \mu(dx)$ is continuous, and so

$$\lim_{h \to 0} \frac{1}{h} (F(s + h) - F(s)) = \lim_{h \to 0} \frac{h}{h} \int_s^{s+h} f(r) dr = f(s) \overset{\text{def}}{=} \int_X \partial_s \phi(s, x) \mu(dx).$$

**A.2. Proposition.** Let $(L_t)_{t \geq 0}$ be a $k$-dimensional Lévy process with Lévy triplet $(\ell, 0, \nu)$ and jump measure $\mu$ such that $|y|^{1+\gamma} \nu(dy) < \infty$ holds for some $\gamma \in [1, 2]$. Denote by $\mathcal{F} := (\mathcal{F}_t)_{t \geq 0}$, $\mathcal{F} := \sigma(L_s; s \leq t)$, the natural filtration and let $b : [0, \infty) \times \Omega \to \mathbb{R}^d$ and $\sigma : [0, \infty) \times \Omega \to \mathbb{R}^{d \times k}$ be $\mathcal{F}$-progressively measurable bounded functions. Then the process

$$X_t := x + \int_0^t b(s) ds + \int_0^t \sigma(s) dL_s, \quad x \in \mathbb{R}^d$$

satisfies Itô’s formula

$$F(t, X_t) - F(0, X_0) = \int_{(0,t)} \partial_{s} F(s, X_s) ds + \int_{(0,t)} \nabla_x F(s, X_s) \cdot (b(s) + \sigma(s) \cdot \ell) ds$$

$$+ \int_{(0,t) \times B(0,1)} (F(s, X_s) + \sigma(s) \cdot y - F(s, X_s)) \tilde{N}(dy, ds)$$

$$+ \int_{(0,t) \times B(0,1)^c} (F(s, X_s) + \sigma(s) \cdot y - F(s, X_s)) N(dy, ds)$$

$$+ \int_{(0,t) \times \mathbb{R}^d} (F(s, X_s) + \sigma(s) \cdot y - F(s, X_s) - \nabla_x F(s, X_s) \cdot \sigma(s) y 1_{(0,1)}(|y|)) \nu(dy) ds$$

for any function $F \in C^{1,1}_{b}((0, \infty) \times \mathbb{R}^d)$ such that for every $T > 0$

$$\|\nabla_x F\|_{C^{\gamma-1}([0,T])} := \sup_{t \in [0,T]} \sup_{x \in \mathbb{R}^d} |\nabla_x F(t, x) + \sup_{t \in [0,T]} x,y \in \mathbb{R}^d \sup_{x \neq y} |\nabla_x F(t, x) - \nabla_y F(t, y)| \frac{|x-y|^{\gamma-1}}{|x-y|} < \infty.$$ 

**Sketch of the proof.** Fix $T > 0$ and pick $\chi \in C^\infty_c(\mathbb{R}^d)$ such that $\chi \geq 0$, $\int \chi(y) dy = 1$ and $\chi(y) = 0$ for all $|y| \geq 1$. If we set

$$F_k(t, x) := k^d \int_{\mathbb{R}^d} F(t, x + ky) \chi(ky) dy, \quad x \in \mathbb{R}^d, \ t \geq 0, \ k \in \mathbb{N},$$

then $F_k \in C^{1,2}_{b}((0, \infty) \times \mathbb{R}^d)$,

$$\sup_{t \in [0,T]} \sup_{x \in \mathbb{R}^d} \left( |F_k(t, x)| + |\nabla_x F_k(t, x)| + |\partial_t F_k(t, x)| \right) \overset{k \to \infty}{\longrightarrow} 0$$

for any compact set $K \subseteq \mathbb{R}^d$; moreover, we have

$$\sup_{k \in \mathbb{N}} \|\nabla_x F_k\|_{C^{\gamma-1}([0,T])} \leq \|\nabla_x F\|_{C^{\gamma-1}([0,T])} < \infty.$$

Please see the correction on the final page.
Applying Taylor's formula we find that there exist a sequence \( c_k \to 0 \) and a constant \( C > 0 \) such that
\[
|(F - F_k)(s, x + z) - (F - F_k)(s, x)| \leq c_k \min \{1, |z|\}
\]
for all \( x \in K, z \in \mathbb{R}^d \) and \( s \in [0, T] \). Since we can apply Itô’s formula for each \( F_k \in C_b^2((0, \infty) \times \mathbb{R}^d) \), see e.g. [7, Chapter II.5], we get (38) for \( F = F_k \). Define
\[
\tau_R := \inf\{t \geq 0; |X_t| \geq R\}.
\]
Using (38) for \( F_k \) and replacing \( t \) by \( t \land \tau_R \), it is not difficult to see that each of the integrals converges as \( k \to \infty \): for the third integral (which is an \( L^2 \)-martingale), we use Itô’s isometry, (39) and the dominated convergence theorem to get \( L^2 \)-convergence and then we extract an almost surely convergent subsequence; all other integral expressions converge almost surely because of (39) and dominated convergence. This gives (38) for \( F \) and with \( t \) replaced by \( t \land \tau_R \). Almost the same argument allows us now to let \( R \to \infty \), and the claim follows.

A.3. Lemma. Let \((X^{(n)}_t)_{t \in [0,T]}\) be a sequence of stochastic processes with càdlàg sample paths such that
\[
\mathbb{E} \left( \sup_{0 \leq t \leq T} |X^{(n)}_t - X^{(m)}_t|^p \right) \xrightarrow{m,n \to \infty} 0
\]
for some \( p > 0 \). Then there exists a stochastic process \((X_t)_{t \in [0,T]}\) and a subsequence \((n_k)_{k \in \mathbb{N}}\) such that \(\sup_{t \in [0,T]} |X_t - X^{(n_k)}_t| \to 0\) almost surely as \( k \to \infty \).

Proof. For \( p \geq 1 \) this follows from the Riesz–Fischer theorem on the completeness of the spaces \( L^p \), see e.g. [25, Theorem 13.7]; therefore it suffices to consider the case \( p \in (0, 1) \). For \( k \geq 1 \) choose iteratively \( n_k > n_{k-1} \) such that
\[
\mathbb{E} \left( \sup_{0 \leq t \leq T} |X^{(n_k)}_t - X^{(n_{k-1})}_t|^p \right) \leq \frac{1}{2^k}.
\]
As \( p \in (0, 1) \), we have \((x + y)^p \leq x^p + y^p\) for \( x, y \geq 0 \), and this implies
\[
\mathbb{E} \left( \sum_{k \geq 1} \sup_{0 \leq t \leq T} |X^{(n_k)}_t - X^{(n_{k-1})}_t|^p \right) \leq \sum_{k \geq 1} \mathbb{E} \left( \sup_{0 \leq t \leq T} |X^{(n_k)}_t - X^{(n_{k-1})}_t|^p \right) \leq \sum_{k \geq 1} \frac{1}{2^k} < \infty.
\]
Since \( X^{(n_k)}_t = X^{(n_1)}_t + \sum_{i=1}^{k-1} (X^{(n_i)}_t - X^{(n_{i-1})}_t) \) this shows that the limit \( X_t := \lim_{i \to \infty} X^{(n_i)}_t \) exists uniformly in \( t \in [0, T] \) with probability 1.

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Correction to the present paper:

In the statement of Itô’s formula, formula (38) of Proposition A.2, the last integral appearing on the right-side ranges only over \((0, t) \times B(0, 1)\) rather than \((0, t) \times \mathbb{R}^d\), i.e.

\[
\cdots + \int_{(0, t) \times \mathbb{R}^d} \ldots \nu(dy) \, ds \quad \text{should read} \quad \cdots + \int_{(0, t) \times B(0, 1)} \ldots \nu(dy) \, ds
\]

We are using (38) on the proof of Theorem 2.1, p. 12, formula (28). The above mentioned change gives one further term on the right-hand side of (28)

\[
\cdots - \int_{T_{i-1}}^{t} \int_{|y| \geq 1} (u_i(s, X^{(n)}_s + y) - u_i(s, X^{(n)}_s)) \nu(dy) \, ds
\]

leading to an additional term \(I_6\) on p. 13 (line 6 from above), i.e.

\[
|X^{(m)}_t - X^{(n)}_t|^p \leq \ldots + C(I_1 + I_2 + I_3 + I_{4,1} + I_{4,2} + I_5 + I_6)
\]

which is of the form

\[
I_6 := \left| \int_{T_{i-1}}^{t} \int_{|y| \geq 1} H_i(s, y) \nu(dy) \, ds \right|^p
\]

with \(H_i\) defined on p. 13 (line 16 from below). Since \(\nu(B(0, 1)^c) < \infty\), we can estimate this term using (29):

\[
E \left( \sup_{T_{i-1} \leq s \leq T_i} |I_6| \right) \leq 2^p e^{pP} E \left( \sup_{T_{i-1} \leq s \leq T_i} |X^{(m)}_s - X^{(n)}_s|^p \right) \left( \int_{|y| \geq 1} \nu(dy) \right)^p,
\]

as is needed for the rest of the proof.

We are grateful to Changsong Deng (Wuhan University) for pointing out the error in formula (38).