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Sensory Perception in Cetaceans: Part I—Current Knowledge about Dolphin Senses As a Representative Species

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A large part of the literature on sensory perception and behavior in dolphins is devoted to its well-developed vocal and echolocation abilities. In this review, we aim to augment current knowledge by examining the literature on dolphins’ entire “Merkwelt” (which refers to everything a subject perceives, creating a crucial part of the subject’s Umwelt). We will show that despite extensive knowledge on audition, aspects such as context relatedness, the social function of vocalizations or socio-sexual recognition, remain poorly understood. Therefore, we propose areas for further lines of investigation. Recent studies have shown that the sensory world of dolphins might well be much more diverse than initially thought. Indeed, although underwater and aerial visual systems differ in dolphins, they have both been shown to be important. Much debated electro- and magnetoreception appear to be functional senses according to recent studies. Finally, another neglected area is chemoreception. We will summarize neuroanatomical and physiological data on olfaction and taste, as well as corresponding behavioral evidence. Taken together, we will identify a number of technical and conceptual reasons for why chemosensory data appear contradictory, which is much debated in the literature. In summary, this article aims to provide both an overview of the current knowledge on dolphin perception, but also offer a basis for further discussion and potential new lines of research.

Keywords: cetaceans, Delphinidae, Tursiops truncatus, audition, vision, electroreception, magnetoreception, chemoreception

DOLPHIN’S UMWELT

Sensory perception is essential for the survival of organisms, be it for the detection of (un)favorable physical conditions, the presence/absence of food or predators, the detection of communication signals or the recognition of social partners. It is crucial for any species to perceive regularities and changes in the properties of their abiotic and biotic environment.
The perception of an organism’s local environment is one part of a living being’s Umwelt (von Uexküll, 1909). The literal translation of Umwelt from German to English is “environment,” but the typical biological meaning is better described as an organism’s “subjective universe” (Chien, 2006). Initially, appropriate sensory receptors have to be able to detect the characteristics of surrounding objects, contexts and conspecifics (von Uexküll, 1909). After being perceived, information concerning the object is further processed through corresponding neural structures and a specific meaning is attributed to each stimulus depending on the context or the subject’s internal state. Everything an organism perceives creates its Merkwelt (English translation: perceptual world). For the sake of completeness: the other part of its Umwelt is the action a living being is taking on its environment according to the meaning that was previously attributed to the perceived stimuli. Everything an organism does creates its Wirkwelt (English translation: active world).

Sensory receptors and perceptual processing structures are critical in the perception of the environment, thus a species’ body plan determines the Umwelt (von Uexküll, 1934). Although several species can share the same environment, each has its own Umwelt as sensory abilities may differ from one species to another. Even within the same species, individuals do not necessarily share identical Umwelten because of morphoanatomical differences caused by genetic defects or events during ontogeny (e.g., a blind and a seeing person may share the same environment, but not the same Umwelt).

It is difficult to determine a species’ Umwelt from an external point of view because we, as humans, also possess our own Umwelt. By simply transferring our perception of reality to another species, we do not respect the subjectivity of a specific organism. Indeed, an object that might be meaningful from the human point of view may be meaningless to another species (Delfour, 2010) either because it does not possess the according receptors to perceive the object’s feature or because the object, although it can be perceived, does not have an importance for this species. Therefore, an unbiased study of a species’ sensory perception and behavior is necessary.

When it comes to sensory perception, cetaceans are particularly informative because they underwent a drastic change in lifestyle in the course of evolution. This mammalian order is currently considered as having evolved about 47 million years ago (MYA) from a small deer-like ancestor (Thewissen et al., 2009), moving from a terrestrial lifestyle back to an aquatic environment. This evolutionary reversal in habitat caused extensive, yet slow rate changes in anatomy, neuroanatomy, physiology, and behavior (Gatesy et al., 2013). The results of this transformation are overtly seen in the baleen whales (Mysticeti) and the toothed whales (Odontoceti). These two suborders are very different in terms of morphology, feeding ecology and behavior, wherefore knowledge gained about mysticete species can be generalized to odontocete species (and vice versa) only with caution, if at all. Therefore, a general “cetacean Umwelt” does not exist. A species-specific perspective is required to understand the Umwelt. The odontocete family Delphinidae includes the best-studied cetacean species; therefore, they present a suitable model to outline their Umwelt. The analysis of the dolphin’s perceived environment will begin with a review of some of the sensory abilities of dolphins, namely audition, equilibrioception, vision, somatosensory perception, electroreception, magnetoreception and chemoreception. Each sense is described in a section that comprises anatomical, physiological and behavioral data, followed by propositions for further lines of investigation. Whenever possible, precise data refer to the bottlenose dolphin (Tursiops truncatus), but for a broader view other members of the family of Delphinidae are included, as well as information that are true for Delphinidae or Odontoceti in general. For those sensory modalities where little literature is available for dolphins, this review includes other cetacean species.

**AUDITION**

**Current Knowledge on Audition**

Most research efforts on dolphin sensory systems over the past 50 years has been devoted to the study of audition (reviewed in Au et al., 2000), namely the ability to detect oscillations of pressure transmitted through air, water or another medium. Hearing in cetaceans has been evaluated mostly by auditory evoked potentials (e.g., Mooney et al., 2015) or behavioral audiograms (e.g., Kastelein et al., 2003).

The sounds that are perceived can originate from prey, predators or conspecifics. Beside echiolocation, some delphinids are known to detect their prey by passive listening (Barros, 1993; Gannon et al., 2005), meaning that they use the sounds produced by their prey to locate it. Noise-producing fish make up a large part of the bottlenose dolphin’s diet (Barros and Wells, 1998). Indeed, it was suggested that the cetacean ancestor developed high-frequency hearing to locate sound-producing fish already in Eocene and based on this ability echolocation evolved in Oligocene odontocetes enabling the location of silent prey (Fahikle et al., 2011).

Sharks (Heithaus, 2001) and orcas (Orcinus orca; Constantine et al., 1998) occasionally attack dolphins. However, not all orcas are hunting mammals (there are also fish-eating orcas) and other cetacean species seem to be able to discriminate between mammal- and fish-eating orcas. The playback of vocalizations of fish-eating orcas elicited an increase in group size in pilot whales (Globicephala melas) and a strong attraction toward the sound (Curé et al., 2012), whereas the playback of vocalizations of mammal-eating orcas prompted a clear avoidance response in beaked whales (Mesoplodon densirostris; Tyack et al., 2011).

Beside natural sound sources such as prey, predators or conspecifics, cetaceans are also exposed to and disturbed by anthropogenic noises originating from military and seismic survey sonars (e.g., Jepson et al., 2003; Piantadosi and Thalmann, 2004), boat noise (e.g., Buckstaff, 2004), or drilling (e.g., Bailey et al., 2010). After loud noise exposure, several cetacean species show a hearing threshold shift, which can be temporary or permanent, meaning a noise-induced hearing loss (e.g., Mooney et al., 2009a; Finneran and Schlundt, 2010; Mann et al., 2010).
Anatomical Data on Audition

The anatomy of the odontocete ear is exclusively adapted for underwater hearing and differs from that of terrestrial mammals: the outer ear pinna as sound collector is replaced with the lower jaw, and the tympanic membrane as sound transmitter is replaced with a thin and large tympanic bone plate (Hemilä et al., 2010). The primary sound perception pathway is considered to be that the lower jaw receives the sound energy and transmits it through fatty tissue located in the mandibular canal (mandibular fat pad) up to the tympanic plate, with best auditory sensitivity at the middle of the lower jaw (Mohl et al., 1999). The mandibular fat pad is composed of triacylglycerol being similar in density, and thus acoustic impedance, to water (Varanasi and Malins, 1971). Middle and inner ear are located together in the tympano-periostic complex that is surrounded by air cushions, which acoustically isolate the ear from the skull (Cranford et al., 2010). Bone density of the tympano-periostic complex increases rapidly during the first months of life, which possibly reflects the importance of hearing for dolphins (Cozzi et al., 2015).

Physiological Data on Audition

Acoustic impulses are transmitted from the ear to the brain via the cochlear nerve, part of the vestibulocochlear nerve (cranial nerve CN VIII; Figure 1). Dolphins seem to process auditory impulses in at least two brain areas. The primary auditory cortex is believed to be located in the suprasylvian gyrus along the vertex of the hemispheres, lateral and adjacent to the primary visual cortex (Popov et al., 1986). In addition, a recent study found that the auditory cortex also exists in the temporal lobe (Berns et al., 2015). Odontocetes tend to have a 10-octave functional hearing range with peak sensitivity between 40 and 80 kHz (Wartzok and Ketten, 1999). In the bottlenose dolphin, hearing ranges up to 150 kHz, with optimal sensitivity within 10–80 kHz (Houser and Finneran, 2006). Dolphins, like cetaceans in general, have good directional hearing. Generally, the direction from which a sound originates may be determined by the difference in arrival time of a sound to each of two ears. As this interaural time difference is calculated by interaural distance, the increased sound velocity in water (compared to air) leads to a reduction in the interaural time difference (compared to air). Cetaceans can compensate for this effect as they have relatively large heads and therefore a naturally large interaural distance, thus increasing the interaural time difference (Nunnmela and Thewissen, 2008).

Behavioral Data on Audition

Traditionally, research on audition in dolphins has focused on echolocation and communication. Dolphins produce three different categories of vocalizations: clicks, burst-pulsed sounds and whistles (reviewed in Janik, 2009). Clicks are short broadband signals that can exceed 100 kHz and are mostly used for echolocation. Burst-pulsed sounds consist of highly directional, rapid click trains: for example, the bray calls generated by the bottlenose dolphin (Janik, 2000a), the so-called “squawks,” “yelps,” and “barks” (Schultz et al., 1995), as well as “moans” or “rasps” (Caldwell and Caldwell, 1967). The distinction between echolocation clicks and burst-pulsed sounds is not always easy. Whistles are tonal, frequency-modulated signals with fundamental frequencies lying between 800 Hz (Schultz and Corkeron, 1994) and 28.5 kHz (May-Collado and Wartzok, 2008), and often several harmonics. Whistles and burst-pulsed sounds can be produced simultaneously (Janik, 2009). This corresponds with the generally accepted concept that there are two sites of sound production that can be controlled independently (Dormer, 1979). They are composed of two identical sound producing structures consisting of fatty dorsal bursae within a pair of phonic lips, one in the left and one in the right nasal passage (Cranford et al., 1996). A recent study suggested that the two dolphin brain hemispheres, which sleep independently (Lyamin et al., 2008), may also act independently when it comes to coordinating prey capture and communication with simultaneously emitted echolocation clicks and social sounds (Ridgway et al., 2015).

Echolocation

An important function of sound for odontocetes is echolocation (or biosonar), where they emit short sound pulses (clicks) and listen for returning echoes to generate an auditory representation of their surroundings for navigation and foraging (Madsen and Sürlykke, 2013). As shorter wavelengths have a better spatial resolution, and wavelength is inversely proportional to frequency, high frequencies are better suitable for detecting small objects compared to low frequencies. Consistently, species inhabiting acoustically complex inshore and river waters use higher frequencies for echolocation (>100 kHz) than near- and offshore species (<100 kHz) that inhabit low object-density environments (Wartzok and Ketten, 1999). Rapid auditory temporal processing facilitates echolocation and sound location (Mooney et al., 2009b). While echolocating, dolphins are able...
to hear (Li et al., 2011), to adjust their hearing (Nachtigall and Supin, 2008), as well as being able to process the heard echoes and vocalize while still echolocating (Ridgway et al., 2012). Furthermore, dolphins possess several mechanisms for gain control (reviewed in Supin and Nachtigall, 2013). Echolocation is so effective in bottlenose dolphins that they can still detect a small object of less than 8 cm at distances of over 110 m (Au and Snyder, 1980) and discriminate objects by using spectrum shape of the echo, as well as its peak and center frequency (DeLong et al., 2006). Bottlenose dolphins start to echolocate at the early age of around 2 months (Carder, 1983), supporting the hypothesis that the structures involved in hearing develop early in life due to the importance of these inputs for survival and development (Cozzi et al., 2015).

Communication

In a habitat where vision is not always possible, acoustic signals provide a good communication channel, even for over long distances. Most delphinids use whistles for communication, but some species use pulsed sounds (e.g., Commerson’s dolphin, Cephalorhynchus commersonii; Yoshida et al., 2014). Why some delphinid and other odontocete species [e.g., the family of Phocoenidae (porpoises), the pygmy sperm whale, Kogia breviceps, and the genus of Pontoporia] do not produce whistles, but only pulse sounds was connected to the orca predation risk. It was hypothesized that species with high orca predation risk were subject to a selective pressure favoring vocalizations restricted to sounds that orcas hear poorly or not at all (i.e., below 2 and above 100 kHz; Morisaka and Connor, 2007). On the other side, orcas adapt their vocal behavior to the prey they are hunting: transient orcas that feed on marine mammals (a prey with sensitive underwater hearing) vocalize less and reduce their vocal activity before and during hunting compared to resident orcas that feed on fish (a prey with poor hearing abilities; Deecke et al., 2005).

Most studies on delphinid communication are concerned with whistles because they are thought to play an important role in social interactions (Díaz López, 2011). Whistles have varying numbers of harmonics and delphinids can distinguish between whistles with and without harmonics (Yuen et al., 2007). Whereas the fundamental frequency is relatively omnidirectional, higher order harmonics are directional (Lammers and Au, 2003). Bottlenose dolphins can discriminate tonal sounds that differ in frequency by only 0.2–0.8% (Thompson and Herman, 1975), but they seem to pay more attention to frequency modulation than to the absolute frequency (Ralsdon and Herman, 1995). The active space (i.e., the transmission range over which a call can be detected by conspecifics) for bottlenose dolphins’ whistles is determined as 10–20 km for frequencies below 12 kHz (Janik, 2000b). However, the active space of a sound depends (among other factors such as its frequency) on bottom substrate and water depth. For example, the same call is perceived at less than 200 m in a shallow sea grass area of 1.6 m depth, but up to more than 6 km in a sandy bottom area of 3.5 m depth (Quintana-Rizzo et al., 2006).

Bottlenose dolphins are known for their production of signature whistles, which are individually distinctive whistles that do not depend on the individual’s voice features, but the whistles’ frequency contour (reviewed in Janik and Sayigh, 2013). These are used for individual recognition, for example between mother and offspring (Sayigh et al., 1998). A proof of the dolphins’ capacity to discriminate even complex frequency modulations is their call matching which has been experimentally tested in wild dolphins and it seems possible that dolphins use these copies (i.e., mimicking sounds) as referential vocal labels in order to address each other (King and Janik, 2013). Furthermore, dolphins seem to be capable of remembering the signature whistles of other individuals for at least 20 years (Bruck, 2013).

Perspectives on Audition

Although there is a multitude of studies concerning the vocal communication of delphinids, many questions remain unresolved that often due to technical and methodological constraints, such as individually assigned recordings and unlimited access to the animals. The latter concern greatly influences those studies with direct observation of free-ranging cetaceans, which are not always easy to detect and to follow. Technical assistance is necessary to identify the vocalizing individual as it is not possible to visually assign a vocalization to its emitter (i.e., dolphins do not open their mouths to vocalize and or systematically produce any other visible correlate of vocalizing). Although such approaches do exist, they are often expensive and/or possibly disturbing to the animals, as the device is generally secured to the body (e.g., Johnson and Tyack, 2003; Blomqvist and Amundin, 2004). For instance, most studies only tag one or a few individuals, which may result in limited data that does not appropriately address a particular research question. This technique might not be suitable for studies that want to test the social function of vocalizations or communication rules during vocal exchanges as this is difficult, if not impossible, when only one group member is tagged.

Alternatively, individuals can be temporarily restrained to record individually assigned vocalizations (e.g., Watwood et al., 2005), but this particular context does not allow for a broad range of vocalizations to be recorded and further studied as stress strongly influences the pattern and content of vocalizations. For example, bottlenose dolphins are thought to encode their level of stress via the whistle rate (Caldwell et al., 1990) and an alteration of acoustic parameters, while keeping the overall frequency modulation pattern constant (Esch et al., 2009). Another, less invasive technique is triangulation, where the location of the sound source is determined by recording with two or more hydrophones and then calculating the origin of the sound. Therefore, simultaneous visual information is necessary to identify the individual that is present at the location calculated as the sound source, making this technique sometimes difficult to apply to free-ranging dolphins.

With regards to echolocation, there is an approach that might yield some insightful results: the “echolocation visualization and interface system,” which can visualize echolocation signals and be used as an “acoustically operated ‘touch screen’” (Amundin et al., 2008). The echolocation signals of dolphins are recorded with hydrophones when those clicks are aimed at
a semitransparent screen. Subsequently, the recorded acoustic signals are translated into a corresponding visual image that is projected on the location where the echolocation signals contact the screen: this leads to immediate visual feedback (Amundin et al., 2008). Another approach is eavesdropping on echolocation signals of conspecifics (reviewed in Gregg et al., 2007). In a behavioral experiment, a bottlenose dolphin was able to correctly choose an object in a matching-to-sample task by eavesdropping on the echoes produced by the echolocation signals of a conspecific (Xitco and Roitblat, 1996). However, the ecological implications of this passive echolocation remain unknown.

EQUILIBRIOCEPTION

Current Knowledge on Equilibrioception

Equilibrioception is the sense of balance, which provides information about the body’s movement. Due to physical differences, more three-dimensional movements are possible in water compared to land, which lead to an increased importance of equilibrioception for aquatic species.

Anatomical Data on Equilibrioception

In vertebrates in general, the sensory organ of balance is the vestibular system in the inner ears. Linear movement and gravity are detected by the two otolith organs, one in the utricle and the other in the saccule, which are located in the vestibule (Rabbitt et al., 2004). Rotational movements are detected by the three membranous semicircular ducts, which are enclosed by the three bony semicircular canals (anterior, posterior, and lateral; Graf, 1988). The otolith organ seems to be well developed and fully functional in cetaceans, with a thicker membrane compared to other mammals (Solntseva, 2001). The semicircular canal system of cetaceans is smaller relative to body size when compared to other mammals. In bottlenose dolphins, the mean radius of curvature of the three canals is 1.1 mm (Spoor and Thewissen, 2008). For comparison: in greater kudus (Tragelaphus strepsiceros), an Artiodactyla species with a similar body mass, the mean radius of curvature of the three canals is 3.5 mm (Spoor and Thewissen, 2008). Furthermore, the cetacean lateral canal is the largest and the posterior canal the smallest of the three semicircular canals (reviewed in Spoer and Thewissen, 2008). In bottlenose dolphins, the relative size of the anterior, posterior and lateral canal is 34, 28, and 38%, respectively. This is in contrast to other mammals where the lateral canal is the smallest if the three canals.

The size reduction concerns only the semicircular canals, and not the entire inner ear of cetaceans, as their cochlea is similar in size relative to body mass when compared to other mammals (Spoor et al., 2002). Is was proposed that this size reduction is due to the dominant auditory function of the inner ear and thus a limited space for the vestibular system (Boenninghaus, 1903). Another explanation for the comparatively small semicircular canal system in cetaceans concerns its sensitivity: the smaller the semicircular canal system, the less sensitive it is. What seems disadvantageous at first sight might be favorable for species with increased head movements, as is the case for cetaceans due to their swimming movement and fused cervical vertebrae (leading to a mostly immobile neck that no longer compensates for body movement to stabilize the head). Here, reduced sensitivity of the sense of balance might help to avoid an overstimulation of the semicircular canal system, which would otherwise lead to disorienting effects (Spoor et al., 2002). Consistent with this hypothesis is the fact that size reduction is more pronounced in Odontoceti, which are more agile compared to Mysticeti (Spoor and Thewissen, 2008).

Physiological Data on Equilibrioception

It is presumed that equilibrioception in dolphins works physiologically similar to other species: impulses from the vestibular system are transmitted to the brain via the vestibular nerve, part of the vestibulocochlear nerve (CN VIII). The information is then processed in the vestibular brain stem nuclei, which transmit neural signals to motor nuclei in order to generate reflexive movements of the eyes and/or other body parts in order to stabilize the body (Sipla and Spoor, 2008).

VISION

Current Knowledge on Vision

Another important sense to perceive the environment is vision, which constitutes the ability to detect variations in the intensity and wavelength of light. When light passes through water it is differently absorbed, refracted and scattered depending on the wavelength of the light, as well as the concentration and type of dissolved material in the water. In shallow waters, longer wavelengths of the light spectrum are common, whereas only shorter wavelengths can penetrate well into deeper layers of water (Wartzok and Ketten, 1999). In general, light decreases with depth.

Anatomical and Physiological Data on Vision

As in all cetaceans, dolphin eyes are located laterally (directed ventronasally), allowing a panoramic vision with a 120–130° visual field, and can be moved independently from each other (Mass and Supin, 2009). Several anatomical structures inside the eye protect them from mechanical damage (e.g., a thickened cornea to resist water pressure) or cooling (Mass and Supin, 2009). Furthermore, a secretion produced by the Harderian gland protects the eyes from the high concentration of salt in marine water (Dawson et al., 1972, 1987). Bottlenose dolphins have good underwater and in-air vision with a visual acuity of 12.6 min of visual angle from a distance of 2.5 m (Herman et al., 1975), probably due to their asymmetric double-slit pupils (Rivamonte, 2009) and excellent distance estimation (Mobley and Helweg, 1990). Under low-light conditions this pupil is round and roughly U-shaped in bright light conditions (Mass and Supin, 2009). In general, the lens of the cetacean eye is very strong and more similar to those of fish compared to the lens of terrestrial mammals (Wartzok and Ketten, 1999).

In cetaceans, visual sensitivity is maximized by a high density of photoreceptors (400,000 cells/mm² in bottlenose dolphins; Dral, 1977), as well as a tapetum lucidum (i.e., a reflective layer behind the retina that increases the amount of light absorbed
by the photoreceptors; Dawson, 1980). Both rod and cone photoreceptors have been described in the retina of bottlenose dolphins (Perez et al., 1972), with absorption maxima of 488 and 524 nm for the rod and cone pigments, respectively, which are both short-wavelength shifted compared to many terrestrial mammals (Fasick et al., 1998). However, bottlenose dolphins only possess long/middle-wavelength-sensitive L-cones but no short-wavelength-sensitive S-cones, thus they are thought to lack the common dichromatic vision typical of many terrestrial mammals and may, therefore, be colorblind (Simons, 1977; Fasick et al., 1998; Peichl et al., 2001). However, under mesopic conditions, where both rods and cones are active, bottlenose dolphins (as well as other so-called monochromatic cetaceans) might exhibit “conditional dichromacy” and a rudimentary form of color vision (Davies et al., 2012), as hypothesized for wobbegong sharks (Theiss et al., 2012).

The dolphin retina possesses (partly giant) ganglion cells (Perez et al., 1972) with a density of up to 670 cells/mm² (Mass and Supin, 1995). The retinal ganglion cells receive visual information from the photoreceptors via inter-retinal neurons and transmit them through the optic nerve (CN II). The optic nerve has a low fiber density (50,000 fibers/mm² compared to >220,000 fibers/mm² in monkeys), which in bottlenose dolphin comprise of 150,000–180,000 optic fibers in total (Mass and Supin, 2009).

Visual impulses are transmitted by the optic nerve to the midbrain, the thalamus and the cerebral cortex (superior colliculus, lateral geniculate nucleus and primary visual cortex) where they are processed further (Glezer et al., 1995).

**Behavioral Data on Vision**

Tested in a visual-matching task, the patterns of perceptual similarities for two-dimensional forms of dolphins was found to be similar to those of chimpanzees and humans (Tomonaga et al., 2014). Contrarily to the previously mentioned hypothesis of color blindness in dolphins (Peichl et al., 2001), a behavioral experiment showed that a bottlenose dolphin had two peaks in spectral sensitivity and that it could discriminate between two wavelengths with equal brightness (Griebel and Schmid, 2002). These findings are consistent with the “conditional dichromacy” hypothesis (Davies et al., 2012) mentioned above. The debate on the evolution and underlying mechanisms of cetacean color vision is still ongoing (Griebel and Peichl, 2003; Meredith et al., 2013).

Delphinids use their good sense of sight in a variety of contexts, from social interactions to prey capture. In short-range communication, visual displays are known to play an important role for delphinids. Postures are thought to signal intent and demeanor of the signal emitter (Dudzinski, 1996). The S-posture, in which the dolphin’s body is bent into an S-shape (head pointing down, pectoral fins stretched out), is often associated with aggressive behaviors that include sexual interactions and disciplinary behavior toward juveniles (Dudzinski, 1996; Bojanowski, 2002). The S-posture is consistent with aggressive behaviors in other cetaceans too (e.g., humpback whales, *Megaptera novaeangliae*), which might be comparable with the arched head and neck position known in many terrestrial mammals during displays of aggression (Dudzinski, 1996). The dolphin’s head-to-head posture is often accompanied by jaw claps, hits, tail hits and “squawks” (burst-pulsed sounds) that are thought to express irritation or anger (Dudzinski, 1996). Jaw claps and head jerks are also described by Connor et al. (2000) as aggressive behaviors. Furthermore, these authors describe a distinct posture, in which the dolphin arches the head and flukes down, which may be used to threaten another dolphin.

Vision also mediates non-aggressive interactions. Affiliation between individuals is, among others, expressed by proximity and synchronous movements (Connor et al., 2000). Another visual display occurs in reproductive contexts; for example, when dolphins present their genital region to sexually attract a mating partner (Tyack, 2000).

There is some evidence that dolphins use pointing gestures (Xitco et al., 2001) and that complex behaviors such as foraging techniques are taught by action imitation that in turn require observation and good vision (Bender et al., 2009; Abramson et al., 2013).

Beside conspecifics, cetaceans use vision for the inspection of their surroundings, both in water and air. A common behavior of several cetacean species is sphyropping, i.e., surfacing vertically and lifting the head out of the water (e.g., Ford, 1984; Whitehead and Weilgart, 1991; Jensen et al., 2013), that seems to serve the inspection of objects above water (Madsen and Herman, 1980). When inspecting objects or humans, familiarity of the object/human to dolphins influences their behavior: dolphins show a visual laterality, using the left eye when looking at familiar objects and the right eye when looking at unfamiliar objects (Blois-Heulin et al., 2012). Furthermore, their gaze lasts longer when viewing unfamiliar humans compared to those that are familiar (Thielges et al., 2011). Dolphins use their accurate vision, for example, when catching fish in air after they have hit them firmly with their fluke (Wells et al., 1987). Some foraging behaviors of the bottlenose dolphin were also found to be lateralized, meaning a localization of function or activity on one side of the body in preference to the other (e.g., Silber and Fertl, 1995; Lewis and Schroeder, 2003). It was suggested that the observed right-sided lateralization in dolphins (but also whales) when foraging may be associated with the visual perception of prey (Karenina et al., 2016).

**Perspectives on Vision**

Color vision is another topic that appears worth of further analyses. Knowing which opsin-based photopigments are expressed in the cetacean retina and their corresponding spectral sensitivities only suggest the potential for color vision. However, behavioral experiments are critical to understanding the functional consequences of the suggested colorblindness or hypothesized “conditional dichromacy” that might exist in many so-called marine mammal monochromats. For example, the normally white ventral side of bottlenose dolphins can be remarkable pink in periods of high sexual activity (personal observation of the authors), which might be used as a reproductive visual cue. How males react to a female whose abdomen is colored pink (either in the field or altered experimentally) is unknown and worthy of further study.
**SOMATOSENSORY PERCEPTION**

**Current Knowledge on Somatosensory Perception**

Somatosensory systems comprise the perception of touch (via pressure and strokes), pain (nociception), temperature (thermoreception), and body position (kinesthesia and proprioception). Several different receptor types are involved (including mechanoreceptors, nociceptors, and thermoreceptors) that are located in the dermis, muscles, and joints. Aquatic species can perceive water movement through their mechanoreceptors (e.g., Dehnhardt et al., 1998). The ability to know the relative body position of an organism is crucial for an air-breathing animal that lives in a three-dimensional underwater habitat in order to orient itself toward the surface even when no visual cues are available and to feel whether the blowhole is above the water (to ensure respiration).

**Anatomical Data on Somatosensory Perception**

The skin of bottlenose dolphins is furrowed by small ridges that are circumferentially oriented in the anterior part of the body (head to dorsal fin) and more obliquely positioned in the posterior part of the body (dorsal fin to caudal fin). The function of these ridges has been implicated in tactile sensing (Shoemaker and Ridgway, 1991), hydrodynamics (Ridgway and Carder, 1993) or both. In the region of the blowhole, large numbers of mechanoreceptors are present that are thought to serve in the perception of pressure changes that occur when the whale/dolphin breaks through the water surface in order to ensure that the blowhole is opened for respiration only after surfacing (Bryden and Molyneux, 1986). Most odontocetes possess vibrissae (i.e., sensory hair), especially on the rostrum of newborns, losing them shortly after birth (Ling, 1977). Thus, adult dolphins possess hairless vibrissal/follicle crypts on the rostrum, except for the Amazon River dolphin (*Inia geoffrensis*) where the presence of rostral sensory hairs continues into adulthood (Dehnhardt and Mauck, 2008). In general, vibrissae are more common in mysticetes (e.g., Drake et al., 2015).

**Physiological Data on Somatosensory Perception**

Cetacean skin is well innervated and very sensitive to touch (Tyack, 2000). Skin sensitivity was examined by studies using either somatosensory evoked potentials (e.g., Lende and Welke, 1972) or the galvanic skin response (e.g., Kolchin and Bel’kovich, 1973). Dolphins are most sensitive on their heads (corners of the mouth, eyes, snout, melon, and the area around the blowhole), reaching a sensitivity comparable to human fingertips or lips (Ridgway and Carder, 1990). Somatosensory information is processed in the postcruciate gyrus of the cerebral cortex (Supin et al., 2001).

**Behavioral Data on Somatosensory Perception**

Dolphins are able to perceive pressures as small as 10 mg/mm² around the blowhole and the eyes (Kolchin and Bel’kovich, 1973). Besides the surrounding water, somatic stimuli can originate from objects in the environment. Rubbing occurs in both captive and free-ranging cetaceans. Delphinids were found rubbing their bodies on particular substrates (e.g., pebbles, sand, or along rocky edges; Smith et al., 1992; Whitehead et al., 2004; Rossi-Santos and Wedekin, 2006), which may possibly have a role in pleasure, hygiene (Dudzinski et al., 2012), or might even be a result of play behavior (Kuczaj et al., 2006).

Touch is also an important short-range communication signal utilized during play, sexual, maternal and social contexts, and involves the entire body (Dudzinski et al., 2009a). Tactile contacts between dolphin conspecifics can be observed during aggressive interactions (including biting etc.), but are also common in affiliative contexts (Paulos et al., 2008; Dudzinski et al., 2009b, 2010, 2012). Affiliation between individuals is expressed by proximity and physical contact (Connor et al., 1999), which includes contact swimming, gentle stroking with the pectoral fin or rubbing against another individual. Sakai et al. (2006) reported that flipper rubbing in wild Indo-Pacific bottlenose dolphins (*Tursiops aduncus*) is an affiliative behavior, which could be a quantitative measure of social relationships among individuals. Tamaki et al. (2006) reported that flipper rubbing might contribute to restore friendly relationships between former opponents or reduce conflicts. Thus, flipper rubbing may be the cetacean equivalent of primate grooming (Tamaki et al., 2006; Connor, 2007). People working with delphinids in captivity suggest that petting is appreciated by the animals and, therefore, could be used as a reinforcer in training (Dudzinski et al., 2009a).

**Perspectives on Somatosensory Perception**

Most odontocetes possess vibrissae, especially on the rostrum, right from birth (Ling, 1977). It would be informative to test whether these perioral hairs serve a tactile function in the context of suckling, when acoustic (echolocation) and visual abilities of young dolphins are not fully developed.

**ELECTRORECEPTION**

**Current Knowledge on Electroreception**

Electroreception is the ability to detect an electric field. Electric stimuli can originate from both abiotic and biotic sources. Bioelectric fields are generated for instance by all muscle movement and the water medium provides ideal conditions for conducting electrical currents, although the spread of these stimuli is far less in the marine environment compared to freshwater (Czech-Damal et al., 2013). In active electroreception, the animal itself generates an electric field and senses distortion of this field from objects of varying conductivity present in its habitat; for example, in electric eels (*Electrophorus electricus*; Souza et al., 2007). In passive electroreception, the animal perceives electric fields generated by an object that is located in close vicinity (Czech-Damal et al., 2012); for example, prey detection by elasmobranchs (Kalmijn, 1971) that possess electroreceptors called ampullae of Lorenzini (Murray, 1960).

**Behavioral Data on Electroreception**

So far, there is only one study on electroreception in cetaceans, which analyzes the behavioral response of a trained Guiana dolphin (*Sotalia guianensis*) toward electrical stimuli. The
dolphin has been found to be sensitive to weak electric currents, such as those emitted by the muscles of prey fish buried in the sediment (Czech-Damal et al., 2012). The electroreceptors are probably situated within the hairless vibrissal crypts on the rostrum (Czech-Damal et al., 2013). As a control, these vibrissal crypts were covered with a plastic shell to prevent contact with seawater. After such treatment, the dolphin could not detect the electric stimuli, whereas a plastic shell that did not impede seawater from contacting the vibrissal crypts did not affect the dolphin’s ability to detect electric stimuli (Czech-Damal et al., 2012).

**Perspectives on Electoreception**

Electoreceptors as found in the Guiana dolphin (Czech-Damal et al., 2012), however, further investigation is essential in other dolphin species to determine their broad functional role in electoreception. Bottlenose dolphins, for example, possess vibrissal crypts on their rostrum, but their involvement in electoreception has not been assessed. Passive electoreception could function as a supplementary sense to echolocation during benthic feeding (Roitblat et al., 1995), which is not uncommon in bottlenose dolphins (Rossbach and Herzing, 1997).

**Magnetoreception**

**Current Knowledge on Magnetoreception**

Magnetoreception is the ability to perceive a magnetic field. The Earth’s magnetic field is a dipole field that is generated by the Earth's fluid outer iron core (Wiltschko and Wiltschko, 1995), providing a consistent source of directional information (Winklhofer, 2010). Its intensity ranges from over 60,000 nT near the magnetic poles to 30,000 nT at the magnetic equator, but shows minimum values below 26,000 nT at the east coast of South America. In the ocean, the magnetic topography (i.e., variation in the magnetic field) is regular and stable long-term, with “magnetic hills” (i.e., local higher total intensities) and “magnetic valleys” (i.e., local lower intensities) quasi-symmetrically arranged on both sides of the mid-oceanic ridge. There are some anomalies that run parallel on opposite sides of the ridge and some that are found in a perpendicular orientation (reviewed in Walker and Dennis, 2005). Differently magnetized rocks can cause such local anomalies (Wiltschko and Wiltschko, 1995). Besides spatial variation, the geomagnetic field also shows temporal variation caused by solar electromagnetic radiation (leading to regular daily variations) or sun spot activity (leading to irregular fluctuations called magnetic storms; Wiltschko and Wiltschko, 1995).

**Physiological Data on Magnetoreception**

There are two main mechanisms that underpin the perception of a magnetic field, namely those that are based on induction or are reliant on magnetite (reviewed in Wiltschko and Wiltschko, 1995). Induction-based perception assumes that the electric field, which is generated by the magnetic field, is detected by electroreceptors; it is dependent on the conductivity of the surrounding medium, thus salt water provides a suitable conductive medium. By contrast, magnetite-based perception is mediated by ferromagnetic particles such as magnetite (iron oxide). These miniature magnets align themselves in the magnetic field and are connected to the central nervous system; however, the exact pathways of signal transmission are still unclear (Lohmann and Johnsen, 2000). Magnetite has been found in the dura mater of both bottlenose (Bauer et al., 1985) and short-beaked common dolphins (Delphinus delphis), where nerve fibers have been identified adjacent to the surface of the iron oxide particles (Zoeger et al., 1981).

**Behavioral Data on Magnetoreception**

Magnetoreception is commonly used for navigation, i.e., animal orientation based on the geomagnetic field (reviewed in Wiltschko and Wiltschko, 1995). Observations of free-ranging cetaceans show some evidence of magnetoreception-based navigation. For example, fin whale (Balaenoptera physalus) migration routes are correlated with low geomagnetic intensity (Walker et al., 1992) and offshore cetacean live strandings seem to occur where valleys in the geomagnetic field cross the coast (Klinowska, 1985; Kirschvink et al., 1986). However, foraging routes of wild short-beaked common dolphins do not seem to be influenced by the geomagnetic field (Hui, 1994). Generally, there are few studies that test magnetoreception in dolphins. Kuznetsov (1999) reported that neurovegetative responses in dolphins, such as the electrocardiogram, galvanic skin responses and respiration, are altered by changes in the magnetic field. The author interpreted this as “a high sensitivity of the dolphin to changes in the permanent magnetic field (a ‘magnetic sense’).” However, as this study is only presented as an abstract, it is difficult to evaluate both the data and conclusions of the work. When captive bottlenose dolphins were exposed to a magnetic field created in their pool by an induction coil (magnetic field strength unknown), they did not show any differential response (Bauer et al., 1985). Even during a series of conditioning experiments using two-choice discrimination and go/no-go designs (magnetic field strength: 37 µT), the dolphins did not show any indication of magnetic discrimination (Bauer et al., 1985). However, Bauer et al. (1985) admitted “experiments that constrain the subject in time and place may be putting significant limits on appropriate orientation.” In a recent study, we conducted an experiment that neither confined dolphins spatially to a given position (as, for example, during a go/no-go experiment), nor demanded a direct response (as it is the case in conditioning experiments), but rather observed their spontaneous reaction toward magnetized and demagnetized devices. Dolphins approached the device with shorter latency when it contained a strongly magnetized neodymium block (magnetic field strength of 1.2 T) compared to a control demagnetized block that was identical in form and density and, therefore, undistinguishable through echolocation (Kremers et al., 2014). This finding suggests that dolphins may be able to discriminate the two stimuli used in our study based on their magnetic properties.
been identified unequivocally (Lohmann and Johnsen, 2000; Winklhofer, 2010). To date, only a magnetite-based system has been proposed in cetaceans (Walker et al., 1992). Since the geomagnetic field is on average 4.5 \( \mu \)T strong (Wiltshcko and Wiltshko, 1995), it is not clear whether or not dolphins are sensitivity enough to perceive and use geomagnetic cues for navigation. As such, further studies concerning the magnetic perception threshold, as well as the possible influence of the orientation of the magnetic field, on dolphin behavior awaits to be tested. Finally, it is still unclear whether magnetic fields are attractive or repulsive to dolphins. Such information could be important for the development of repellent devices that could, for example, protect fishing nets from foraging dolphins and simultaneously decrease the dolphins’ risk of entanglement in those nets.

**CHEMORECEPTION**

Compared to the other senses, chemoreception has drawn little empirical attention in marine mammals and its functional status in cetaceans remains unknown. The different modalities of chemoreception (i.e., olfaction, vomerolfaction, gustation, and trigeminal sensation) are sometimes difficult to tell apart in aquatic animals due to less clear physicochemical selectivity of stimuli conveyed by water (Hemilä and Reuter, 2008). Moreover, it is possible that chemoreceptors of aquatic mammals are found on unexpected body parts compared to terrestrial mammals. Cetaceans might possess chemoreceptors allowing them to sense all types of substances carried in either water or air (Hemilä and Reuter, 2008). However, chemoreceptive structures known from terrestrial mammals may be modified, displaced, reduced or absent in extant cetaceans due to evolutionary adaptation to an aquatic environment. The latter appears to be the case for the vomeronasal organ and related accessory olfactory tracts (Thewissen, 2009), although a recent study found some evidence for the potential presence of a vomeronasal organ in a neonate gray whale (Eschrichtius robustus; Kienle et al., 2015). Accordingly, the following sections will only focus on olfaction and gustation.

**Current Knowledge on Olfaction**

Olfaction is traditionally defined as the ability to detect airborne volatile compounds, viz. compounds having a molecular weight below 400 Dalton (Hemilä and Reuter, 2008; Mollo et al., 2014). In terrestrial mammals, odorants have to dissolve in the mucus covering the olfactory epithelium inside the nasal cavity, where they adhere to binding proteins that in turn activate olfactory receptors (ORs) located on the cilia of sensory neurons that transmit impulses to the brain via the olfactory nerve (CN I). However, olfactorily active stimuli can be conveyed by water, as shown, for example, in the fetuses of mammalian terrestrial species that react to acute chemical stimulations and detect the chemosensory qualities of their amniotic environment (Schaal and Orgeur, 1992). Thus, even when the detected chemicals are waterborne, the modality has to be considered as olfaction if the neural transmission pathway involves CN I (e.g., Hara, 1994). The important point here is that olfaction can be fully functional under aquatic conditions. For instance, several marine (Davis et al., 2006; DeBose et al., 2008) and freshwater (Hara, 2006) fish species are known to use odorants as social or foraging cues and display a specific behavior called “sniffing” or “coughing” to drive water into the olfactory sacs, thus increasing the supply to the olfactory epithelium (Nevitt, 1991). In addition, the olfactory modality might not necessarily require receptor cells that are exclusively located within the nasal cavity.

**Anatomical Data on Olfaction**

The nasal cavity is not considered to be involved in olfaction in odontocetes as it accommodates parts of their echolocation system and because the cribiform plate of the ethmoid bone, as well as the ethmoturbinals, are absent (Breathnach, 1960). The main and accessory olfactory tracts are absent in toothed whales and considerably reduced or absent in baleen whales (Breathnach, 1960; Oelschläger, 2008). Furthermore, CN I appears to vanish during early ontogeny in both of these species (Oelschläger and Buhl, 1985).

By contrast, other studies imply that cetaceans may possess neural structures involved in olfaction. Chemoreceptor cells were found in the nasal cavity (frontal and vestibular sacs) of harbor porpoises (Phocoena phocoena; Behrmann, 1989), perhaps enabling some kind of odor sensation. Odontoceti were found to possess a well-developed olfactory tubercle (Oelschläger and Oelschläger, 2009). In bowhead whales (Balaena mysticetus), a complex olfactory bulb and olfactory tracts are present and more than half of the OR genes are intact, suggesting a potentially functional sense of smell (Thewissen et al., 2011; Kishida et al., 2015a). However, OR genes are reported to be functionally reduced by pseudogenization in Odontoceti (Kishida et al., 2007). Bottlenose dolphins possess only two class I and ten class II OR genes that are intact, as well as a single vomeronasal receptor type 1 gene (Kishida et al., 2015b).

**Current Knowledge on Gustation**

Gustation is the ability to detect waterborne compounds such as hydrophilic substances (i.e., organic acids, amino acids, or nucleotides), but also traces of all sorts of miscible or hydrophobic compounds (Hemilä and Reuter, 2008), that are ingested with prey or during social interactions. Gustation provides information about water or food materials already in the mouth, through taste bud receptor cells that are located on the tongue, palate, epiglottis, esophagus and duodenum (Purves et al., 2001).

**Anatomical Data on Gustation**

No taste buds were found on the tongue or other areas in the oral cavity of various odontocete species (Kuznetsov, 1990). However, the number and age of individuals investigated are often unknown or very limited; therefore, these findings remain unconvincing. Nevertheless, several authors have suggested that cetaceans in general and odontocetes in particular should exhibit taste sensation (e.g., Pfeiffer et al., 2001). Taste buds were indeed found in younger individuals of the same species that were previously described as absent in adults (Yamasaki et al., 1978; Behrmann, 1988; Kuznetsov, 1990). Other studies did not
describe taste buds, but found marginal vallate papillae on the tongue of dolphins, known to be potential locations of taste buds (Kastelein and Dubbeldam, 1990; Werth, 2007), as well as cells that resemble von Ebner's glands (also called gustatory glands) that might be important for chemoreception (Ferrando et al., 2010).

**Physiological Data on Gustation**

It was proposed that in dolphins the well-developed trigeminal nerve (CN V; Oelschläger, 2008) might provide a pathway to transmit impulses from the oral cavity to the brain, called trigeminal chemoreception (Kuznetsov, 1990). In mammals, CN V innervates the oral and nasal cavities, as well as the eyes, and responds especially to chemical irritants (Silver and Finger, 2009). Unlike other mammals, where CN VII innervates the lingual taste buds (Purves et al., 2001), this nerve does not seem to be involved in dolphin chemoreception, but rather in acoustic signal production (Oelschläger, 2008). However, CN V, just like CN VII, is able to excite gustatory neurons in the nucleus of the solitary tract in the brainstem of other mammals (Purves et al., 2001; Boucher et al., 2003), so it might be involved in taste perception in cetaceans.

Taste receptor genes are reported to be mostly pseudogenized in Odontoceti: in bottlenose dolphins, sweet, umami, bitter and sour taste receptor genes are non-functional, whereas salty taste receptor genes are intact and potentially have functional roles in gustation (Jiang et al., 2013; Feng et al., 2014; Kishida et al., 2015b). Recent molecular findings suggest that this reduction of gustatory abilities in cetaceans occurred between the Artiodactyla-Cetacea and the Odontoceti-Mysticeti evolutionary divisions (Kishida et al., 2015b).

**Behavioral Data on Gustation**

Behavioral studies have shown that bottlenose dolphins can perceive the sour and bitter tastes of citric acid and quinine sulfate/hydrochloride dehydrate solutions, respectively, nearly as well as humans (Nachtgall and Hall, 1984; Friedl et al., 1990; Kuznetsov, 1990). Moreover, they were able to detect the salty taste of sodium chloride solution (Friedl et al., 1990; Kuznetsov, 1990). Studies that test the perception of sweet stimuli are contradictory, stating that dolphins are able to perceive the sweet taste of sucrose solution (Friedl et al., 1990) or not (Kuznetsov, 1990). In addition to these simple tastants, dolphins were able to detect complex tastants, such as those conveyed in conspecific urine and feces (Kuznetsov, 1990). Kuznetsov (1990) proposed the term “quasi-olfaction” to describe the chemical sense in dolphins that combines characteristics of both gustation and olfaction. Recent behavioral studies suggest that dolphins are able to detect airborne odors and discriminate between different flavors (Kremers et al., 2016).

**Perspectives on Chemoreception**

Generally, the air above the ocean is chemically less rich compared to air above land, wherefore the chemical environment for air-breathing aquatic species is less diverse compared to terrestrial species: indeed, this lack of chemical variation might have been one of the main drivers that led to the evolution of more specialized sensory abilities in aquatic species. Water birds, for example, show adaption to their aquatic environment in their olfactory receptor complement compared to land birds, with OR families 2/13, 51, and 52 (that were correlated with aquatic adaptations) being expanded (Khan et al., 2015). Just as other marine species are able to detect chemical compounds and exploit them as source of information (e.g., from conspecifics, prey, and predators), it is not unreasonable to hypothesize that dolphins might use a similar sensory system, either by detecting airborne molecules when they surface or waterborne cues. Indeed, fish emit chemical cues that are perceived by other fish and used for the detection of conspecifics, prey and predators, as well as analyzing the chemical profile of water to direct locomotion (Hara, 1994; Hirvonen et al., 2000). Although it is widely accepted that dolphins use echolocation to locate prey, it may be possible that dolphins also use chemical cues to identify and assess the quality of prey. These questions have not been investigated so far, which is probably due to technical issues and the availability of animals for testing.

Extrapolations from anatomical data in determining actual sensory capacities may have been over-interpreted and should be revised accordingly. For example, the reduced size of chemoreceptive organs in some cetaceans do not exclude that a given species may exhibit specialized sensitivity to particular chemical cues (Pihlström et al., 2005; Nummela et al., 2013). As the chemical senses in dolphins are not yet sufficiently delineated, all chemosensory modalities (i.e., olfaction, gustation, and trigeminal sensation) are potentially involved. Behavioral studies might be a good approach to investigate the functional status of chemoreception in dolphins as anatomical and genetic studies have yielded conflicted and controversial results. Similarly, it was proposed that sweet taste perception in hummingbirds (who lack the specific corresponding taste receptor genes) is enabled through unrelated taste receptors that have undergone a change in function (Baldwin et al., 2014). Thus, the simple absence or pseudogenization of taste or olfactory receptor genes should not be the sole basis for proposing firm conclusions that relate to the chemosensory abilities of a particular species: appropriately conducted and controlled behavioral studies should be included.

In general, go/no-go tasks are an elegant way to investigate perceptual abilities as the behaviors displayed by dolphins in response to internal (e.g., pleasure/liking, aversion, interest, fright etc.) or external stimuli can be subtle. However, these experiments require that dolphins are trained, thus preventing the investigation of spontaneous responses or preferences. Similar to experiments conducted to test gustatory stimuli, detection thresholds for airborne stimuli could be determined using go/no-go tasks. Furthermore, dolphins could be trained to react to the presence of an odor with a certain response (e.g., choosing one of two proposed symbols or buttons) and to the absence of another, using positive reinforcement.

Although dolphinariums provide a good opportunity to train dolphins involving several research tasks, there are a number of constraints: for example, training sessions and actual presentations for public viewing limit the time available for experimentation. Furthermore, some methods that work well in captivity are not applicable in the field. For instance, in...
contrast to captive dolphins, wild dolphins cannot be trained; therefore, other methods may have to be developed for the same research tasks. While chemoreception may be tested in captive dolphins by using odor sources close to the pool or ice cubes (see Kremers et al., 2016), floating dispensers (such as the ones used for chlorine tablets in swimming pools) may be adopted for wild dolphins. For olfactory studies, the substance to be tested is simply placed inside the device. For gustatory studies, the substance is contained within large ice cubes, which themselves are placed within the device. When submerged into water, this allows for a slow release of the tastant through holes located at the bottom of the device. The behavior of the dolphins toward the device, such as their distance to it or their approach latency, can then be analyzed and compared with other tested substances or controls. Given the fact that such observations are made at the surface of the water body, they are often inaccurate due to the shallow angle of the observer; therefore, it might be helpful to use drones (i.e., small unmanned aerial vehicle that are remotely controlled) equipped with cameras to record animal movements from above. An aerial view with an approximately perpendicular angle has the advantage that even animals under the water surface are visible (as long as they are not too deep). Furthermore, the use of drones would permit an increased distance between the boat and the device, thereby reducing the potential disturbance to the test subjects.

It would be informative to test different chemical cues within diverse experimental contexts. As dolphins prefer fish species with a high energy density (Spitz et al., 2010), it would be insightful to investigate if food choices are dependent on chemical cues. Therefore, a test with high vs. low energy density fish would be revealing. Another substance to test is dimethyl sulfide (DMS), which is released by phytoplankton when being grazed on by zooplankton (Dacey and Wakeham, 1986), and used by predators (including at least one other marine mammal, the harbor seal Phoca vitulina vitulina) to find their prey (Nevitt et al., 1995; Kowalewsky et al., 2006; Wright et al., 2011). As phytoplankton attracts zooplankton and zooplankton in turn attracts fish, the ability to detect DMS might allow dolphins to find fish. Indeed, prey detection by using chemical cues has already been suggested for bowhead whales (Thewissen et al., 2011).

Another approach would be to test for chemical cues in social and reproductive contexts, as individual recognition or mate detection (e.g., female receptiveness) could be chemically mediated as is common in many other species. Therefore, the use of urine (given the fact that dolphins seem to be able to detect urine and feces; Kuznetzov, 1990) and/or excretions from the urogenital glands could be used as stimuli (e.g., those obtained from known and unknown individuals or receptive and non-receptive females). The idea of odor-mediated sexual behavior was previously suggested for spinner dolphins (Stenella longirostris; Norris, 1991) and exploratory behaviors such as “genital inspections” have also been reported (Norris and Dohl, 1980; Herzing, 1996). In a behavioral and endocrinological study of three female bottlenose dolphins, that were observed during three conception estrous cycles, Muraco and Kuczaj (2015) found that reproductive behaviors increased with estradiol and luteinizing hormone levels. During estrus, females received more behavioral attention than they initiated, including an investigatory behavior (“genital tracking”), as defined by the authors of the corresponding study) and having their genital slit being touched by the rostrum of another dolphin (“goose,” as defined by the authors of the corresponding study). Thus, the authors suggested that dolphins might be able to gain information about the physiological state of another dolphin (e.g., during reproduction) by using chemosensory abilities.

Finally, it seems worth investigating whether some repulsive stimuli are inherent or acquired. Chemical stimuli that are potentially involved in eliciting negative responses might be compounds associated with natural predators (e.g., orcas, a natural predator of dolphins), or intensively irritating, tasting or smelling substances such as capsaicin or putrescine. A possible application could be the development of a device to repel dolphins from fishing nets or areas with high boat traffic by using an effectively repulsive substance, thus minimizing adverse human-dolphin interactions.

**FURTHER QUESTIONS AND POTENTIALLY PROMISING APPROACHES ON PERCEPTION IN DOLPHINS**

As the previous sections have illustrated, there is a huge amount of knowledge on sensory perception in dolphins. Nevertheless, as always in research, each finding raises new questions that require further experimentation. One promising line of research is cross-modal perception, which describes the interaction between two or more different sensory modalities (i.e., the ability to relate information received from one sense with information obtained from another). Probably the best-studied example of cross-modal perception in dolphins concerns their ability to link auditory and visual cues. Dolphins are able to recognize objects visually that were previously inspected by echolocation and vice versa (e.g., Herman et al., 1998; DeLong et al., 2000; Hoffmann-Kuhnt et al., 2008). Furthermore, dynamic information about movement, in addition to stationary objects, can be perceived across those two senses (Kuczaj et al., 2008).

So far, cross-modal perception in dolphins was only investigated with regards to the interaction between audition and vision within the context of object and movement recognition. However, other senses and contexts should also be investigated. Possible valid questions may concern if dolphins are able to link information in the context of: (1) individual recognition of conspecifics between audition (signature whistles), vision (individually distinctive physical features) and/or chemoreception (chemical profile); (2) communication between audition (e.g., jaw claps, tail hits or “squawks”) and vision (body postures); (3) prey location between audition (returning echo) and electroreception (electric field generated by prey); and (4) food evaluation between audition (returning echo), somatosensory perception (haptic characteristics of prey) and/or chemoreception (flavor characteristics of prey).
CONCLUSION

Although intensively studied for decades, many facets of dolphin biology remain unknown. Without doubt, this is partly due to the difficulties researchers encounter when studying marine mammals, especially in the field. Generally, hearing is considered to be the most important sensory modality, not only in dolphins but also in odontocetes in general (e.g., Thewissen, 2009), as it is involved in navigation, prey location, and communication. This has led to the majority of studies addressing questions related to hearing, sound production, echolocation and related communicative activities. By contrast, other sensory modalities are considered to be less important (e.g., Marriott et al., 2013) and, therefore, have become physically reduced or may even be absent due to complex trade-offs between different sensory modalities (Nummela et al., 2013). This approach appears biased and runs the risk of distorting knowledge or oversimplifying the degree by which dolphins, and other cetacean, might possess and utilize a potentially diverse array of senses. Therefore, the sensory perception of cetaceans, and in particular the dolphin, should be revisited, especially regarding the study of those modalities that have been largely neglected, namely electroreception, magnetoreception and chemoreception.

AUTHOR CONTRIBUTIONS

DK, AL, and MH prepared the main text of the manuscript. All authors contributed to the preparation of the article, in the form of discussion and critical comments, and reviewed the manuscript.

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