GARSIDE GROUPS AND GEOMETRY

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Abstract. This article in memory of Patrick Dehornoy (1952 – 2019) is an invitation to Garside theory for mainstream geometric group theorists interested in mapping class groups, curve complexes, and the geometry of Artin–Tits groups.

1. Meeting Patrick

When I remember Patrick Dehornoy, the first thing that comes to my mind is his humour – he was one of the people who knew how to do serious work and have serious discussions with a smile and even a laugh, always in a way that advanced the work. And his work! His energy and his efficiency at everything he touched were downright scary to me. He was clearly the driving force behind the two book projects [23, 24] he had with me (together with Ivan Dynnikov and Dale Rolfsen). Each time, his plans for these books grew more and more ambitious even during the writing process, and it must have been terribly frustrating to him that his co-authors had trouble following his rhythm. His unbelievable productiveness and efficiency concerned not only his mathematical work, but also his administrative work (as head of his department, but also in French national scientific administration), and his private projects (constructing his house and his garden, and creating humorous little movies, for instance).

I remember Patrick’s sometimes startling openness when discussing his private life. I remember his kindness and generosity, in particular with younger mathematicians, taking time and sharing his ideas. I remember his patience with less efficient people. When I told him quite frankly that the book on the foundations of Garside theory was too long and abstract for me, he listened patiently and promised to write something short and enjoyable that would at least give a glimpse of the book. The result was the survey paper [19], which I highly recommend as readable introduction to the subject.

He must have known that some of his work was only readable for a very few experts. But I believe he had a clear vision of the kind of larger theory his work will one day be part of, and he had the confidence, and self-confidence, that it will be recognised as important. There is a scene in one of Patrick’s little movies [18] where a mathematician in the far future (played by Cédric Villani) bases his revolutionary work on Patrick’s LD-systems. This was of course a joke, but who believes that it was only a joke? Here is another telling example of his humour: I once wrote to Patrick that a research project which we wanted to start had to wait, because I was still too busy with other projects. His answer: “Quel dommage pour toi... dans ce
2. GARSIDE THEORY

Some of Patrick Dehornoy’s major contributions in the last few years of his life were, of course, to the foundations of Garside theory [22]. The beautiful subject of Garside theory is now an important tool for geometric group theorists working on Artin–Tits groups – see e.g. [5, 16, 14, 29, 30, 4, 8, 11, 20, 21, 26, 25]. (And by the way, Patrick advocated the name “Artin–Tits groups” for this family of groups, in place of “Artin groups”.) On the other hand, Garside theory is not so much used by geometric group theorists working on mapping class groups, curve complexes, Teichmüller spaces etc. The rest of the present paper is meant as an invitation to them, and many others, to have a closer look at Garside theory.

This paper is mostly a list of open questions concerning Garside theory, questions whose answers should be of great interest to geometers. Even the most basic examples of Garside groups, namely the braid groups equipped with the classical Garside structure, are fascinating! All these questions are related to the following

**Meta-question.** Is Garside theory on braid groups a geometric theory?

We give substance to this vague question with three

**Detailed questions.**

1. Do Garside normal forms of braids represent quasi-geodesics in the curve graph?
2. Is the additional length graph of braid groups, equipped with their classical Garside structure, quasi-isometric to the curve graph?
3. Can Garside theory furnish a polynomial time solution to the conjugacy problem in braid groups?

In order to make Question (A) more precise, we start with the following special case of an observation of Masur and Minsky [27]: the curve graph of the $n$-times punctured disk $C(D_n)$ is quasi-isometric to an “electrified” Cayley graph of the braid group. Specifically, starting with $Cay(B_n, S_{Gar})$, the Cayley graph of $B_n$, equipped with the Garside generators, we can “squash down”, or “cone off” the normaliser of every parabolic subgroup of the form $\langle \sigma_i, \ldots, \sigma_j \rangle$ with $1 \leq i \leq j < n$, and also the subgroup $(\Delta^2)$ generated by the Dehn twist along the boundary of the disk. We do this simply by adding every element of every such subgroup to the generating set, thus adding plenty of edges to the Cayley graph; we denote $Cay(B_n, S_{NP})$ the Cayley graph with respect to this enlarged, infinite generating set. The observation now is that $Cay(B_n, S_{NP})$ is quasi-isometric to the curve graph $C(D_n)$! Thus the composition $Cay(B_n, S_{Gar}) \rightarrow Cay(B_n, S_{NP}) \xrightarrow{q_{isom}} C(D_n)$ is a Lipschitz map from the standard Cayley graph to the curve graph. We are now ready to give a more precise version of Question (A): the images (or “shadows”) of Garside normal form paths in $Cay(B_n, S_{Gar})$ under the above Lipschitz map are paths in $C(D_n)$ – do these paths form a uniform family of re-parametrised quasi-geodesics?

Why should we care about Question (A)? One of the major open problems in the theory of mapping class groups is whether all mapping class groups are bi-automatic. And one of the most successful techniques used in the study of mapping class groups and related objects has been Masur–Minsky’s hierarchy machinery on
the curve graph – see e.g. [28, 3]. One should expect this technique to be helpful at attacking the bi-automaticity question.

A good place to start any such attack would surely be to understand what the known bi-automatic normal forms on mapping class groups look like from the point of view of the curve graph. But there is currently only one known bi-automatic normal form on any mapping class group, namely the Garside normal form (including the dual structure of [7]), on the braid groups. The fact that Question (A) is open is therefore a major embarrassment, and it illustrates the difficulty of the bi-automaticity question. It is certainly reasonable to believe in a positive answer to Question (A), but [33] is a cautionary tale.

Concerning Question (B): in [10, 11] it was shown how to associate to every Garside group $G$ a $\delta$-hyperbolic graph $\mathcal{C}_{\text{AL}}(G)$ with an isometric $G$-action. It was shown that for all spherical-type Artin-Tits groups, the graph is of infinite diameter, and the action has the weak proper discontinuity (“WPD”) property [6]. The construction of $\mathcal{C}_{\text{AL}}(G)$ starts again with the Cayley graph of $G$ with respect to the Garside generators, and proceeds again by a “coning off”, or “adding to the generating set” procedure: the idea is to add all the obvious elements – obvious from the point of view of Garside theory – which should be squashed so as to force hyperbolicity. Firstly, all powers of the Garside element $\Delta$ must be added to the generating set (in order to squash the center of $G$). Moreover, if two elements $x$ and $y$ can “telescope into each other”, i.e. if $x, y$ and $x \cdot y$ have infimum zero (meaning that they can be written as products Garside generators, not their inverses, but that no such writing can use the letter $\Delta$), and if all three elements $x, y$, and $x \cdot y$ have the same length, then these three must belong to to generating set. (The element $y$ in the preceding discussion is “absorbable”, in the notation of [10, 11, 12].) The obvious example of this kind telescoping takes place in the braid groups, when $x$ and $y$ are positive braids of the same length with support in disjoint subsurfaces.

The proof that $\mathcal{C}_{\text{AL}}(G)$ is hyperbolic is quite easy from the construction. In order to give some idea of the proof that it has infinite diameter, we can state a corollary of this proof (which is unfortunately not stated in [11]): there are elements in the group whose axes in the Cayley graph have the strong contraction property, or equivalently, the bounded geodesic image property – see [2, Section 2] for a good introduction to this property. (One fact which is helpful in proving the bounded geodesic image property is that Garside normal form paths are geodesics in the Cayley graphs of Garside groups, with respect to their Garside generators [15].)

Question (B) amounts to the following: if two braids $x$ and $y$ can “telescope into each other” as above, is there necessarily something in the geometry, in the subsurface structure of these braids, which explains this behaviour, like there is in the “obvious example”?

Why should we care about Question (B)? A positive answer would deepen our understanding both of Garside theory and of the curve complex. For a start, it would imply a positive answer to question (A). Also, if $x$ and $y$ are two positive braids (with infimum zero), there would be a wonderfully elegant answer to the question: where is the quasi-center of a geodesic triangle in the curve graph (the electrified braid group) with vertices 1, $x$ and $y$? The answer would be: at the greatest common divisor $x \wedge y$. Another attractive aspect of this question is its relation to a very puzzling gap in our understanding of the curve graph, namely: if
you have a Euclidean disk of sufficiently large radius quasi-isometrically embedded in the Cayley graph of a mapping class group, does electrifying the Cayley graph (projecting to the curve complex) shrink it to universally bounded diameter? As shown in [12], a positive answer would imply a positive answer to Question (B)!

When we look at more general Artin-Tits groups, we also see quite momentous consequences of a generalised version of Question (B): there is currently a lot of activity trying to define an analogue of the curve graph for general Artin-Tits groups (a long-term goal being a proof that they are hierarchically hyperbolic [3]). There is actually an obvious candidate graph, which might conceivably work for every Artin-Tits group \( A \), namely the graph of irreducible parabolic subgroups \( C_{\text{parab}}(A) \) defined in [17]. Here is the definition: for any Artin-Tits group \( A \), vertices of the graph \( C_{\text{parab}}(A) \) correspond to irreducible parabolic subgroups of \( A \), and two vertices are connected by an edge if, either, one of the corresponding subgroups is contained in the other, or if the two corresponding subgroups have trivial intersection and commute. In the case of braid groups, this graph is isometric to the curve graph. However, in general, the hyperbolicity of these candidate graphs is an open problem, except in the cases \( A_n, B_n, \tilde{A}_n \) and \( \tilde{C}_n \), where it can be deduced (in a highly non-trivial way [9]) from the hyperbolicity of the curve graph. See [17] for details on the case of Artin-Tits groups of spherical type, [9] for the spherical and Euclidean type, and [31] for FC type.

Getting back to the motivation for question (B), the most elegant strategy for proving hyperbolicity of the graphs of irreducible parabolic subgroups, at least in the spherical-type case, and maybe also in the Euclidean-type case [29, 30], would be to prove that they are quasi-isometric to the additional length graphs of the corresponding groups, equipped with their Garside structures!

Turning to Question (C), we recall that solving the conjugacy problem in mapping class groups in polynomial time is one of the major open problems concerning these groups, so any progress on Question (C) would be remarkable. A more precise version of Question (C) is: “For any fixed number of strands \( n \), is there an algorithm which takes as its input two elements of the braid group \( B_n \), of lengths \( \ell_1 \) and \( \ell_2 \), and which outputs the information whether or not the braids are conjugate, and which runs in time \( P(\ell_1 + \ell_2) \), for some polynomial \( P \)”? (Even more optimistically, we could ask for a polynomial dependence on both \( \ell_1 + \ell_2 \) and the number of strands \( n \).)

The biggest roadblock to solving Question (C) using Garside theory is the following problem: consider a braid \( x \in B_n \) of length \( \ell \) which is rigid (i.e. whose Garside normal form is cyclically in normal form). We try to find an upper bound for the number of rigid conjugates of \( x \) — the desired answer would be a polynomial \( P_n(\ell) \), and ideally, the degree of \( P_n \) should not grow too fast with respect to the number of strands \( n \). This is a purely Garside-theoretical question! Also, we know from Garside-theoretical considerations [13] that generically, \( x \) has only \( 2\ell \) rigid conjugates, but we are interested in a worst-case bound. Now, computational experiments with large numbers of randomly generated braids, as well as explicit constructions of families of braids with many rigid conjugates were reported on in [34]. This work suggest that the desired upper bound may be of the form \(|\{\text{rigid conjugates}\}| \leq c_n \cdot \ell^{n-2} \). Not only that, but it appears that when the set of rigid conjugates gets so exceptionally large, there is a geometric reason for this: the braid is “almost reducible in multiple ways”. If a braid is reducible, then its closure
admits a torus containing an “interior braid” which can slide freely relative to the “exterior braid”. In our “almost reducible braids”, by contrast, we do not have a torus but only a long tube whose two ends do not quite close up (what is called an “ouroboros”). As a consequence, the interior of the tube can only slide by a limited amount relative to the exterior. If there are several such tubes in the same closed braid, which can all slide by some amount relative to each other, then the set of conjugates thus obtained can grow polynomially with the length $\ell$.

In particular, it appears that the braids for which solving the conjugacy problem using Garside theory is hard all have very short translation length in the curve complex. In terms of hierarchies, there are multiple disjoint or nested subsurfaces with large subsurface projections.

In summary, in each of the cases referenced by Questions (A), (B), and (C), there may be some hidden rigidity to Garside theoretical structures, and in each case, this rigidity may correspond to some geometric information. If true, these phenomena may prove mutually beneficial for both geometry and Garside theory. And if not, well, then Garside may reveal structures not visible in curve-complex like objects. I imagine that either answer would have been deeply satisfying for Patrick Dehornoy.

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