Unsupervised Word Segmentation from Discrete Speech Units in Low-Resource Settings

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Abstract

Documenting languages helps to prevent the extinction of endangered dialects – many of which are otherwise expected to disappear by the end of the century. When documenting oral languages, unsupervised word segmentation (UWS) from speech is a useful, yet challenging, task. It consists in producing time-stamps for slicing utterances into smaller segments corresponding to words, being performed from phonetic transcriptions, or in the absence of these, from the output of unsupervised speech discretization models. These discretization models are trained using raw speech only, producing discrete speech units that can be applied for downstream (text-based) tasks. In this paper we compare five of these models: three Bayesian and two neural approaches, with regards to the exploitability of the produced units for UWS. For the UWS task, we experiment with two models, using as our target language the Mboshi (Bantu C25), an unwritten language from Congo-Brazzaville. Additionally, we report results for Finnish, Hungarian, Romanian and Russian in equally low-resource settings, using only 4 hours of speech.

Our results suggest that neural models for speech discretization are difficult to exploit in our setting, and that it might be necessary to adapt them to limit sequence length. We obtain our best UWS results by using Bayesian models that produce high quality, yet compressed, discrete representations of the input speech signal.

Keywords: unsupervised word segmentation, speech discretization, acoustic unit discovery, low-resource settings

1. Introduction

Popular models for speech processing still rely on the availability of considerable amounts of speech data and their transcriptions, which reduces model applicability to a limited subset of languages considered high-resource. This excludes a considerable number of low-resource languages, including many from oral tradition.

Besides, learning supervised representations from speech differs from the unsupervised way infants learn language, hinting that it should be possible to develop more data-efficient speech processing models.

Recent efforts for zero-resource processing (Glass, 2012; Jansen et al., 2013; Versteegh et al., 2016; Dunbar et al., 2017; Dunbar et al., 2019; Dunbar et al., 2020) focus on building speech systems using limited amounts of data (hence zero resource), and without textual or linguistic resources, for increasingly challenging tasks such as acoustic or lexical unit discovery. Such zero resource approaches also stimulated interest for computational language documentation (Besacier et al., 2006; Duong et al., 2016; Godard et al., 2018; Bird, 2021) and computational language acquisition (Dupoux, 2018).

In this paper we address the challenging task of unsupervised word segmentation (UWS) from speech. This task consists of outputting time-stamps delimiting stretches of speech, associated with class labels corresponding to word hypotheses, without access to any supervision. We build on the work presented in Godard et al. (2018): they proposed a cascaded model for UWS that first generates a discrete sequence from the speech signal using the model from Ondel et al. (2016), and then segments the discrete sequence into words using a Bayesian (Goldwater, 2007) or a neural (Boito et al., 2017) approach. Since then, much progress has been made in automatic speech discretization: efficient Bayesian models for acoustic unit discovery (AUD) emerged (Ondel et al., 2019; Yusuf et al., 2021), and self-supervised models based on neural networks – typically made of an auto-encoder structure with a discretization layer – were also introduced (van den Oord et al., 2017; Baevski et al., 2020a; Chorowski et al., 2019).

Therefore, in this work we revise and extend (Godard et al., 2018) by empirically investigating the exploitability of five recent approaches for speech discretization for the UWS task in a rather low-resource scenario, using approximately 4 hours of speech (roughly 5k sentences). More precisely, we train three Bayesian speech discretization models (HMM (Ondel et al., 2016), SHMM (Ondel et al., 2019) and H-SHMM (Yusuf et al., 2021)), and two neural models (VQ-VAE (van den Oord et al., 2017) and vq-wav2vec (Baevski et al., 2020a)). We extract discrete speech units from them using only 4 hours of speech, and we perform UWS from the sequences produced. Our pipeline targets the Mboshi language (Bantu C25), an unwritten language
from Congo-Brazzaville. Additionally, we perform experiments in equal data settings for Finnish, Hungarian, Romanian and Russian. This allows us to assess the language-related impact in our UWS pipeline.

Our experiments show that neural models for speech discretization are difficult to exploit for UWS, as they output very long sequences. In contrast to that, the Bayesian speech discretization approaches from [Ondel et al., 2019] and [Yusuf et al., 2021] are robust and generalizable, producing high quality, yet compressed, discrete speech sequences from the input utterances in all languages. We obtain our best results by using these sequences for training the neural UWS model from [Boito et al., 2017].

This paper is organized as follows. Section 2 presents related work, and Section 3 details the speech discretization models we experiment with. Section 4 presents our experimental setup, and Section 5 our experiments. Section 6 concludes our work.

2. Related Work

The work presented here revises the UWS model from speech in low-resource settings presented in [Godard et al., 2018]. [Boito et al., 2019] complemented that work by tackling different neural models for bilingual UWS, but they did not address the discretization portion of the pipeline, working directly from manual phonetic transcriptions. In [Kamper and van Niekerk, 2021], the authors propose constraining the VQ-VAE model in order to generate a more exploitable output representation for direct application to the UWS task in English. Different from that, in this work we focus on providing an empirical comparison of recent discretization approaches, extending [Godard et al., 2018] and providing results in low-resource settings, and in five different languages. This work falls into the category of computational language documentation approaches. Recent works in this field include the use of aligned translation for improving transcription quality [Anastasopoulos and Chiang, 2018], and for obtaining bilingually grounded UWS [Duong et al., 2016] Boito et al., 2017]. We find pipelines for obtaining manual [Foley et al., 2018] and automatic [Michaud et al., 2018] transcriptions, and for aligning transcription and audio [Strunk et al., 2014]. Other examples are methods for low-resource segmentation [Lignos and Yang, 2010] Goldwater et al., 2009], and for lexical unit discovery without textual resources [Bartels et al., 2016]. Finally, direct speech-to-speech [Tjandra et al., 2019] and speech-to-text [Bescacier et al., 2006] Bérand et al., 2016] architectures could be an option for the lack of transcription, but it remains to be seen how exploitable these architectures could be in low-resource settings.

Lastly, we highlight that recent models based on self-supervised learning [Schneider et al., 2019] Baevski et al., 2019] Wang et al., 2020] Liu et al., 2020] Baevski et al., 2020b] [Hsu et al., 2021] provide an interesting novel option for reducing the amount of labeled data needed in downstream tasks such as automatic speech recognition and speech translation. In this work we experiment with the vq-wav2vec 2.0 (Baevski et al., 2020b). We however, do not extend our investigation to the latter, or to models such as HuBERT [Hsu et al., 2021]. This is because, while these models do produce a certain discretization of the speech (for wav2vec 2.0 via quantization module, for HuBERT via clustering of MFCC features), we judge this discretization to be insufficiently exploitable for downstream text-based approaches due to their excessive length. We do, however, find promising the integration of self-supervised speech features into Bayesian AUD models as in [Ondel et al., 2022].

3. Unsupervised Speech Discretization Models

Speech discretization consists in labeling the speech signal into discrete speech units, which can correspond or not to the language phonetic inventory. This problem can be formulated as the learning of a set of discrete units with embeddings \( \mathbb{H} = \{ \eta^1, \ldots, \eta^\ell \} \) from a sequence of untranscribed acoustic features \( X = [x_1, \ldots, x_N] \), as well as the assignment of frame to unit \( z = [z_1, \ldots, z_N] \). Depending on the approach, neural (Section 3.1) or Bayesian (Section 3.2), the assumptions and the inference regarding these three quantities will differ.

3.1. Neural (VQ-based) models

VQ-VAE. It comprises an encoder, a decoder, and a set of unit-specific embeddings \( \mathbb{H} \). The encoder is a neural network that transforms the data into a continuous latent representation \( V = (v_1, \ldots, v_N) \). Each frame is then assigned to the closest embedding in the Euclidean sense (Equation 1). The decoder transforms the sequence of quantized vectors into parameters of the conditional log-likelihood of the data \( p(x_n | z) \), and the network is trained to maximize this likelihood. Since the quantization step is not differentiable, the encoder is trained with a straight through estimator [Bengio et al., 2013]. In addition, a pair of \( \ell_2 \) losses are used to minimize the quantization error, and the overall objective function that is maximized is presented in Equation 2 where \( s_q[.] \) is the stop-gradient operator. We define the likelihood \( p(x_n | z_n) = \mathcal{N}(x_n; \mu(\eta^z_n), \mathbf{I}) \). Under this assumption, the log-likelihood reduces to the mean-squared error \( \sum_u \|v_n - \eta^u\|^2 \).

\[
|| x_n - \mu(\eta^z_n) ||^2. \tag{1}
\]

For instance, wav2vec 2.0 trains on a joint diversity loss for inciting the use of its discrete units. Their large codebook of \( G = 8 \); \( V = 8 \) results in an upper-bound of \( 8^8 \) units.
\[
\mathcal{L} = \frac{1}{N} \sum_{n=1}^{N} \left( \ln p(x_n|z_n) - k_1||s_g(\eta_x^n) - v_n||_2^2 - k_2||\eta_x^n - s_g(v_n)||_2^2 \right)
\]  

(2)

**vq-wav2vec.** This model is composed of an encoder \((j : \mathbf{X} \rightarrow \mathbf{Z})\), a quantizer \((q : \mathbf{Z} \rightarrow \hat{\mathbf{Z}})\) and an aggregator \((g : \hat{\mathbf{Z}} \rightarrow \mathbf{C})\). The encoder is a CNN which maps the raw speech input \(\mathbf{X}\) into the dense feature representation \(\mathbf{Z}\). From this representation, the quantizer produces discrete labels \(\hat{\mathbf{Z}}\) from a fixed-size codebook vector \(\mathbf{e} \in \mathbb{R}^{V \times d}\) with \(V\) representations of size \(d\). Since replacing an encoder feature vector \(\mathbf{z}_i\) by a single entry in the codebook makes the method prone to model collapse, the authors independently quantize partitions of each feature vector by creating multiple quantized feature vector time-steps into \(k\)-means clustering. Finally, the aggregator corresponding to a fixed codebook vector \((k \text{ is the sequence length, } T\text{ variables for a given group, and each element } \sigma_i \text{indices})\) partitions of each feature vector by creating multiple centroids) is set to 50. This setting is unusually low to model collapse, the authors independently quantize. This model is composed of an encoder \((j : \mathbf{X} \rightarrow \mathbf{Z})\), but it helps to reduce the length of the output sequence.

**3.2. Bayesian Generative Models**

For generative models, each acoustic unit embedding \(\eta_u\) represents the parameters of a probability distribution \(p(x_n|\eta_u, z_n)\) with latent variables \(z\). Discovering the units amounts to estimating the posterior distribution over the embeddings \(\mathbf{H}\) and the assignment variables \(\mathbf{z}\) given by:

\[
p(\mathbf{z}, \mathbf{H}|\mathbf{X}) \propto p(\mathbf{X}|\mathbf{z}, \mathbf{H})p(\mathbf{z}|\mathbf{H}) \prod_{x=1}^{U} p(\eta^x).
\]

(4)

From this, we describe three different approaches.

**HMM.** In this model each unit is a 3-state left-to-right HMM with parameters \(\eta^u\). Altogether, the set of units forms a large HMM analog to a “phone-loop” recognition model. This model, described in Ondel et al. (2016), serves as the backbone for the two subsequent models.

**SHMM.** The prior \(p(\eta)\) in Equation [4] is the probability that a sound, represented by an HMM with parameters \(\eta\), is an acoustic unit. For the former model, it is defined as a combination of exponential family distributions forming a prior conjugate to the likelihood. While mathematically convenient, this prior does not incorporate any knowledge about phones, i.e. it considers all possible sounds as potential acoustic units. In Ondel et al. (2019), they propose to remedy this shortcoming by defining the parameters of each unit \(u\) as in Equation [5] where \(e^u\) is a low-dimensional unit embedding, \(\mathbf{W}\) and \(\mathbf{b}\) are the parameters of the phonetic subspace, and the function \(f(\cdot)\) ensures that the resulting vector \(\eta^u\) dwells in the HMM parameter space. The subspace, defined by \(\mathbf{W}\) and \(\mathbf{b}\), is estimated from several labeled source languages. The prior \(p(\eta)\) is defined over the low-dimensional embeddings \(p(e)\) rather than \(\eta\) directly, therefore constraining the search of units in the relevant region of the parameter space. This model is denoted as the Subspace HMM (SHMM).

\[
\eta^u = f(W \cdot e^u + b)
\]

(5)

\[\text{[a]}\text{Implementation available at: } \text{https://github.com/BUTSpeechFIT/vq-aud}\]

\[\text{[b]}\text{Implementation available at: } \text{https://github.com/pytorch/fairseq/tree/master/examples/wav2vec}\]
H-SHMM. While the SHMM significantly improves results over the HMM, it also suffers from an unrealistic assumption: it assumes that the phonetic subspace is the same for all languages. Yusuf et al. (2021) relax this assumption by proposing to adapt the subspace for each target language while learning the acoustic units. Formally, for a given language \( \lambda \), the subspace and the acoustic units’ parameters are constructed as in Equation 6 where the matrices \( M_i \) and vectors \( m_i \) represent some “template” phonetic subspace linearly combined by a language embedding \( \alpha^\lambda = [\alpha_1^\lambda, \alpha_2^\lambda, \ldots, \alpha_K^\lambda]^T \). The matrices \( M_i \) and the vectors \( m_i \) are estimated from labeled languages – from multilingual transcribed speech dataset for instance. The acoustic units’ low-dimensional embeddings \( \{e_i\} \) and the language embedding \( \alpha \) are learned on the target (unlabeled) speech data. We refer to this model as the Hierarchical SHMM (H-SHMM).

\[
W^\lambda = M_0 + \sum_{k=1}^K \alpha_k^\lambda m_k \\
\eta^\lambda,n = f(W^\lambda \cdot e_i^\lambda,n + b^n) \\
\]

Inference. For the three generative models, the posterior distribution is intractable and cannot be estimated. Instead, one seeks an approximate posterior \( q(\eta_i | z) = q(\{\eta_n\})q(z) \) that maximizes the variational lower-bound \( \mathcal{L}[q] \). Concerning the estimation of \( q(z) \), the expectation step is identical for all models and is achieved with a modified forward-backward algorithm described in Ondel et al. (2016). Estimation of \( q(\eta) \), the maximization step, is model-specific and is described in Ondel et al. (2016) for the HMM, in Ondel et al. (2019) for SHMM models, and in Yusuf et al. (2021) for the H-SHMM model. Finally, the output of each system is obtained from a modified Viterbi algorithm that uses the expectation of the log-likelihoods with respect to \( q(\{\eta_n\}) \), instead of point estimates.

Training. The models are trained with 4 Gaussians per HMM state and using 100 for the Dirichlet process’ truncation parameter. SHMM and H-SHMM use an embedding size of 100, and H-SHMM models have a 6-dimensional language embedding. For the methods that use subspaces estimation (SHMM and H-SHMM), this estimation uses the following languages: French, German, Spanish, Polish from the Globalphone corpus (Schultz et al., 2013), as well as Amharic (Abate et al., 2005), Swahili (Gelas et al., 2012) and Wolof (Gauthier et al., 2016) from the ALPFA project (Besacier et al., 2015). We use 2-3 hours subsets of each, for a total of roughly 19 hours.

4. Experimental Setup

From the discrete speech units produced by the presented speech discretization models, we produce segmentation in the symbolic domain by using two UWS models. A final speech segmentation is then inferred using the units’ time-stamps and evaluated by using the Zero-Resource Challenge 2017 evaluation suite, track 2 (Dunbar et al., 2017). We now detail the UWS models used in this work, which are trained with the same parameters from Godard et al. (2018). We also detail the datasets and the post-processing for the discrete speech discrete units.

Bayesian UWS approach (monolingual). Non-parametric Bayesian models (Goldwater, 2007) Johnson and Goldwater, 2009) are statistical approaches for UWS and morphological analysis, known to be robust in low-resource settings (Godard et al., 2016). In these models, words are generated by a unigram or bigram model over an infinite inventory, through the use of a Dirichlet process. In this work, we use the unigram model from dpseg (Goldwater et al., 2009), which was shown to be superior to the bigram model in low-resource settings (Godard, 2019).

Neural UWS approach (bilingual). We follow the bilingual pipeline from Godard et al. (2018). The discrete speech units and their sentence-level translations are fed to an attention-based neural machine transla-

Table 1: Statistics for the datasets, computed over the text (FR), or over the phonetic representation (*).
Figure 1: Heatmaps for the soft-alignment probability matrices generated by the neural UWS models (bilingual) trained on different discrete speech units, for the same French-Mboshi sentence. The darker the square, the higher the pair probability. The rows present the automatically generated units from the different discretization models, informed in the bottom.

Table 3: UWS Boundary F-scores for the MB-FR dataset.

|          | dpseg    | neural   |
|----------|----------|----------|
|          | RAW +SIL | RAW +SIL |
| 1 HMM    | 32.4     | 35.1     |
| 2 SHMM   | 43.7     | 41.4     |
| 3 H-SHMM | 45.3     | 44.8     |
| 4 VQ-VAE | 39.0     | 32.1     |
| 5 VQ-W2V-V16 | 37.4 | 32.0     |
| 6 VQ-W2V-V36 | -       | 40.6     |
| 7 True Phones | -   | 77.1     |

We first present our results for the MB-FR dataset, the language which corresponds to the true low-resource scenario that we are interested in. Table 3 presents UWS Boundary F-scores for UWS models (dpseg and neural) trained using different discrete speech units for the MB-FR dataset. We include results for both the direct output (RAW) and the post-processed version (+SIL). The RAW VQ-W2V-V36 is not included as its output sequences were excessively large for training our UWS models (Table 2). We observe that in all cases, post-processing the discrete speech units with the silence information (+SIL) creates easier representations for the UWS task. We believe this is due to the considerable reduction in average length of the sequences (Table 2). For Bayesian models, we also observe a reduction in the number of units, meaning that some units were modelling silence windows, even though these models already produce an independent token for silence, which we remove before UWS training.

Looking at the results for UWS models trained using the output of VQ-based models (rows 4-6), we see that the best segmentation result is achieved using the one with the smallest average sequence length (VQ-VAE). In general, we believe that all VQ-based models underperform due to the excessively long sequences produced, which are challenging for UWS. Figure 2 illustrates this difference in representation length, by presenting the discrete speech units produced by Bayesian and neural models for a given utterance: the latter produces considerably more units. Overall, we find that UWS models trained using the discrete speech units from Bayesian models produce better segmentation, with models trained with SHMM and H-SHMM presenting the best results. In [Yusuf et al. (2021)], both systems showed competitive results for the AUD task. A noticeable difference between these two models is the compression level: H-SHMM...
Figure 2: Speech discrete units produced by the five models for the same Mboshi sentence. Black lines denote the true boundaries, while dashed white lines denote the discovered units boundaries. For each example, discrete speech units (top) and reference (bottom).

Table 4: UWS Boundary F-scores for the MaSS dataset using Bayesian models (+SIL only). Best UWS results from speech discrete units (bold) and from true phones (underlined) are highlighted.

|       | FI  | HU  | RO  | RU  | FI  | HU  | RO  | RU  |
|-------|-----|-----|-----|-----|-----|-----|-----|-----|
| HMM   | 45.6| 49.9| 53.5| 47.1| 53.4| 51.2| 56.6| 54.9|
| SHMM  | 49.0| 52.3| 53.5| 50.5| 56.0| 53.8| 58.9| 57.7|
| H-SHMM| 50.5| 52.9| 58.0| 52.9| 56.1| 53.3| 59.6| 58.0|
| True Phones | 59.6| 59.6| 59.6| 59.6| 68.4| 63.4| 75.7| 68.4 |

6. Conclusion

In this paper we compared five methods for speech discretization, two neural models (VQ-VAE, VQ-W2VEC), and three Bayesian approaches (HMM, SHMM, H-SHMM), with respect to their performance serving as direct input to the task of unsupervised word segmentation (UWS) in low-resource settings. Our motivation for such a study lies in the need of processing oral and low-resource languages, for which obtaining transcriptions is a known bottleneck (Brinckmann, 2009).

In our UWS setting, and using five different languages (Finnish, Hungarian, Mboshi, Romanian and Russian), we find that VQ-based methods are not a good fit for our pipeline, as they output very long and inconsistent sequences, which are difficult to treat. This was also recently observed in Kamper and van Niekerk (2021). In contrast to that, the Bayesian SHMM and H-SHMM models perform the best, as they produced concise yet
highly exploitable representations from just few hours of speech. We believe this difference in performance is due to HMM-based models explicitly performing acoustic unit discovery. This means the discretization produced by them aims not only to summarize the speech signal, but to closely match the language’s phonology. Moreover, the subspace estimation performed by both SHMM and H-SHMM, might also play a significant role. This is because these models are able to learn from an additional 19 hours of data in different languages. The other models (HMM and VQ-based models) do not have access to any form of pretraining or prior.

Finally, comparing the neural and Bayesian UWS approaches, we notice that the neural model is competitive in the noisier setting, reaching better UWS boundary scores working with the output of speech discretization models. The Bayesian model is however better at segmenting true phones (topline scenario). Concluding, this work updates Godard et al. (2018) by using more recent speech discretization models, and presenting better UWS results for Mboshi.

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