Research Article
The Characterizations of WG Matrix and Its Generalized Cayley–Hamilton Theorem

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Based on the core-EP decomposition, we use the WG inverse, Drazin inverse, and other inverses to give some new characterizations of the WG matrix. Furthermore, we generalize the Cayley–Hamilton theorem for special matrices including the WG matrix. Finally, we give examples to verify these results.

1. Introduction

First, we use the following notations. Let \( C_{m,n} \) stand for the set of \( m \times n \) complex matrices. The symbols \( A^* \), \( \mathcal{R}(A) \), \( \text{rk}(A) \), and \( \det(A) \) represent the conjugate transpose, range, rank, and determinant of \( A \), respectively. The smallest positive integer \( k \) such that \( \text{rk}(A^{k+1}) = \text{rk}(A^k) \) is called the index of \( A \in C_{m,n} \) and it is denoted by \( \text{Ind}(A) \). The Moore–Penrose inverse of \( A \in C_{m,n} \) is the unique matrix \( X \in C_{n,m} \) satisfying the following equations:

\[
AXA = A, \quad XAX = X, \quad (AX)^* = AX, \quad (XA)^* = XA,
\]

and the unique matrix \( X \) is denoted by \( X = A^\dagger [1, 2] \). Furthermore, we denote

\[
E_A = AA^\dagger, \quad F_A = I_n - A^\dagger A.
\]

The Drazin inverse of \( A \in C_{n,n} \) is the unique matrix \( X \in C_{n,n} \) such that

\[
A^kXA = A^k, \quad XAX = X, \quad AX = XA,
\]

and the unique matrix \( X \) is usually denoted by \( X = A^\# \), where \( k = \text{Ind}(A) [1, 2] \). In particular, when \( k = 1 \), \( X \) is called the group inverse of \( A \) and is denoted by \( X = A^\# \). Therefore, we call it a group invertible matrix with index 1. The symbol \( C_{n,n}^{CM} \) stands for the set of group invertible matrices in \( C_{n,n} \):

\[
C_{n,n}^{CM} = \text{Ark}(A^2) = \text{rk}(A), A \in C_{n,n}.
\]

Baksalary and Trenkler [3] defined the core inverse of a complex matrix with index 1. Let \( A \in C_{n,n}^{CM} \); the core inverse of \( A \) is the unique matrix which satisfies the following equations:

\[
AX = AA^0, \quad \mathcal{R}(X) \subseteq \mathcal{R}(A),
\]

and it is denoted by \( X = A^\circ \). Subsequently, a variety of new generalized inverses have been established successively. Let \( A \in C_{n,n} \) with \( \text{Ind}(A) = k \). The core-EP inverse of \( A \) is the unique matrix \( X \in C_{n,n} \) satisfying \( XA^{k+1} = A^k \), \( XAX = X \), \( AXA = A^k \), \( XAX = X \), and the unique matrix \( X \) is usually denoted by \( X = A^\circ \), where \( k = \text{Ind}(A) [1, 2] \). In particular, when \( k = 1 \), \( X \) is called the group inverse of \( A \) and is denoted by \( X = A^\# \). Therefore, we call it a group invertible matrix with index 1. The symbol \( C_{n,n}^{CM} \) stands for the set of group invertible matrices in \( C_{n,n} \):

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\[
C_{n,n}^{CM} = \text{Ark}(A^2) = \text{rk}(A), A \in C_{n,n}.
\]
and \((AX)^* = AX\), and the core-EP inverse of \(A\) is denoted by \(A^\oplus\) [4]; the B-T inverse of \(A\) is the unique matrix \(X \in C_{n,n}\) satisfying \(X = (AE_A)^1\), and the B-T inverse of \(A\) is denoted by \(A^{\ominus}\) [5]; the DMP inverse of \(A\) is the unique matrix \(X \in C_{n,n}\) satisfying \(XAX = X, \ AX = AD, \) and \(AX = A^\delta A^\gamma, \) and the DMP inverse of \(A\) is denoted by \(X = A^{D,\gamma} [6]\); the CMP inverse of \(A \in C_{n,n}\) is the unique matrix \(X \in C_{n,n}\) satisfying \(XAX = X, \ AX = AD, \) and \(X = A^\delta A^\gamma, \) and the CMP inverse of \(A \in C_{n,n}\) is denoted by \(A^{C,\tau} [7]\). It is easy to see that core-EP inverse and DMP inverse are both generalized core inverses, which are extensions of core inverse on square matrices without index constraint, and when \(A \in C_{n,n}^{CM}, \ A^\oplus = A^{D,\tau} = A^{\oplus}\).

Furthermore, Wang and Chen [8] proposed a generalized group inverse. Let \(A \in C_{n,n}^{CM}, \) if \(X\) satisfies the following equations:

\[
AX^2 = X, \\
AX = A^\oplus A,
\]

where \(X\) is called the WG inverse of \(A, \) and \(X\) is unique. It is usually denoted by \(X = A^{\oplus}. \) By applying the definition, we can obtain \(A^\oplus AA^\oplus = A^\oplus \) and \(R(A^\oplus) \subseteq R(A^\oplus). \) It is noteworthy that \(A^\oplus = A^\# \) and \(A^\# \neq A^\oplus, \) when \(A \in C_{n,n}^{CM}. \) Then, Ferrerya et al. [9] extended the definition of WG inverse to the general matrix, defined the weighted WG inverse, and gave its expression, properties, and characterizations; Mosić and Zhang [10] established the weighted WG inverse of Hilbert space operator; Zhou et al. [11] generalized WG inverse to a proper \( \star \)-ring and gave a new characterization of WG inverse; Zhou et al. [12] generalized \(-\)WG inverse to a unitary ring with involution and gave some properties of \(-\)WG inverse; Mosić and Stanimirović [13] gave new characterizations, limit representations, integral representations, and perturbation formulae of the WG inverse.

By applying the WG inverse, Wang and Liu [14] introduced the definition of WG matrix based on the properties and characterizations of WG inverse. Let \(A \in C_{n,n}^{CM}; \) if \(A\) commutes with its WG inverse, \(A\) is called WG matrix. The symbol \(C_{n,n}^{WG}\) stands for the set of WG matrices in \(C_{n,n} [14]:\)

\[
C_{n,n}^{WG} = AAA^\oplus = A^\oplus A, \quad A \in C_{n,n}^{CM}. \quad (7)
\]

Subsequently, Yan et al. [15] investigated some new characterizations of weak group inverse by projection, the Bott–Duffin inverse, etc.

Matrix decomposition is very important, which not only functions as a significant role in every branch of mathematics but also has a wide range of applications in engineering. With the development of new generalized inverses, new research tools such as matrix decomposition and algorithm are also given. Wang established the core-EP decomposition of square matrix over complex fields [16]. Core-EP decomposition is one of the commonly used tools to study core-EP inverse and several new generalized inverses.

Lemma 1 (see [16], core-EP decomposition). Let \(A \in C_{n,n}\) with \(Ind(A) = k. \) Then, there exist \(A_1, \ A_2, \) such that \(A = A_1 + A_2, \) where \(A_1 \in C_{n,n}^{CM}, \ A_2 = A_2 \ A_1 = 0. \) Furthermore,

\[
A_1 = U \begin{bmatrix} T & S \\ 0 & 0 \end{bmatrix} U^*, \quad (8)
\]

\[
A_2 = U \begin{bmatrix} 0 & 0 \\ 0 & N \end{bmatrix} U^*,
\]

where \(U\) is a unitary matrix, \(T \in C_{rk(A^\ominus)rk(A^\ominus)}\) is nonsingular, and \(N\) is nilpotent.

By applying the above decomposition, it is easy to verify

\[
A^k(A^k)^\ominus = U \begin{bmatrix} I_{rk(A^\ominus)} & 0 \\ 0 & 0 \end{bmatrix} U^*. \quad (9)
\]

Lemma 2 (see [14]). Let \(A \in C_{n,n}\) with \(Ind(A) = k, \) then \(rk(A^\oplus) = rk(A^D) = rk(A^k)\) and

\[
A^\oplus = A^D = A^k = (A^{k+1})^\oplus (A^t)^{k+1} A^t. \quad (10)
\]

Lemma 3 (see [8, 14]). Let \(A \in C_{n,n}\) be as in the form (8). Among \(A \in C_{n,n}^{WG}, \ (A^2)^\ominus = (A^\ominus)^2, \ S\ N = 0, \) and \(A\ A^\ominus = A^\ominus A, \) any two of them are equivalent. If \(A \in C_{n,n}^{WG}, \) then

\[
A^\ominus = A^D = A^k = (A^{k+1})^\oplus (A^t)^{k+1} A^t, \quad (11)
\]

where \(t\) is a positive integer and \(k\) is the index of \(A.\)

Lemma 4 (see [16–20]). Let \(A \in C_{n,n}\) be as in the form [21], then

\[
(1) A^\oplus = U \begin{bmatrix} T^* \Delta & -T^* \Delta SN^\oplus \\ F_N S^\Delta & A^\ominus - F_N S^\Delta SN^\oplus \end{bmatrix} U^*;
\]

\[
(2) A^D = U \begin{bmatrix} T^{-1} & T^{-(k+1)} \Delta T^{-1} \\ 0 & 0 \end{bmatrix} U^*;
\]

\[
(3) A^\ominus = U \begin{bmatrix} T^{-(k+1)} \Delta & 0 \\ 0 & 0 \end{bmatrix} U^*;
\]

\[
(4) A^* = U \begin{bmatrix} T^* \Delta_1 & -T^* \Delta_1 SN^\oplus \\ (E_N - E_{N^\ominus}) S^\Delta N^\ominus - (E_N - E_{N^\ominus}) S^\Delta_1 N^\ominus \end{bmatrix} U^*;
\]

\[
(5) A^{D,\tau} = U \begin{bmatrix} T^{-1} & (T^{-(k+1)} \Delta)^* T^{-(k+1)} \Delta \\ 0 & 0 \end{bmatrix} U^*;
\]

\[
(6) A^{t,D} = U \begin{bmatrix} T^* \Delta & T^* \Delta T^{-(k+1)} \Delta T^{-1} \\ F_N S^\Delta & F_N S^\Delta T^{-(k+1)} \Delta T^{-1} \end{bmatrix} U^*;
\]

\[
(7) A^{C,\tau} = U \begin{bmatrix} T^* \Delta & T^* \Delta T^{-(k+1)} \Delta T^{-1} \\ F_N S^\Delta & F_N S^\Delta T^{-(k+1)} \Delta T^{-1} \end{bmatrix} U^*;
\]
subset of $WG$ matrices. Special matrices such as $WG$ matrix, theorem for special matrices including $WG$ matrix.

The classical Cayley–Hamilton theorem is one of the most important theorems in matrix theory. On the basis of the classical Cayley–Hamilton theorem, mathematicians established the rectangular matrix, block matrix, pair of block matrix, and other matrices as well as more generalized Cayley–Hamilton theorem for generalized inverse matrices. They also gave application of generalized Cayley–Hamilton theorem in several control systems [22–25]. In [26], Wang, Chen, and Yan gave the generalized Cayley–Hamilton theorem of core-EP inverse matrix and $DMP$ inverse matrix by core-EP decomposition, and the characteristic polynomial equations of core-EP inverse matrix and $DMP$ inverse matrix were also discussed. In [2, 27], the researchers studied the applications of generalized Cayley–Hamilton theorems in generalized inverses such as Drazin inverse and Moore–Penrose inverse. Based on the above researches, this paper will focus on the $WG$ matrix, the equivalent characterizations of $WG$ matrix, and the generalized Cayley–Hamilton theorem for special matrices including $WG$ matrix.

2. Some Characterizations of $WG$ Matrix

In [14], the definition and characterizations of $WG$ matrix are given through the commutativity of matrix and $WG$ inverse. In [15], Yan et al. investigated some new characterizations of $WG$ matrix.

**Theorem 1** (see [15]). Let $A \in C_{n,n}$ with $\text{Ind}(A) = k$, then the following conditions are equivalent:

1. $A \in C_{n,n}^{WG}$;
2. $A^k A^0 = A^k A^0$;
3. $A^k A^0 = A^k A^D A^0$;
4. $A^D A^k = A^D A^k$;
5. $A^D A^D = A^D A^D$;
6. $A^D A^D = A^D A^D$;
7. $A^D A^D = A^D A^D$.

It is pointed out that the set of group invertible matrices is a subset of $WG$ matrices set. Special matrices such as $WG$ matrix, group matrix, $EP$, $I$-$EP$, and $k$-$EP$ matrix have rich intersection [14]. In this section, we will mainly apply core-EP decomposition to study the characterization of $WG$ matrix.

**Theorem 2.** Let $A \in C_{n,n}$ with $\text{Ind}(A) = k$, then the following conditions are equivalent:

1. $SN = 0$, where $S$ and $N$ are as in the form [21];
2. $AA^0 = A^0 A$;
3. $(A^0)^2 = (A^0)^2$;
4. $A^0 = A^0$;
5. $A^0 A$ commutes with $A^0 A^2$;
6. $UAU^*$ is a $WG$ matrix for any unitary matrix $U$;
7. $A$ commutes with $AA^0$;
8. $A$ commutes with $A^0 A$;
9. $AA^0 = AA^0 A$;
10. $A^0$ commutes with $A^0 A$;
11. $A^k (A^k)^0 A^2 = (A^k (A^k)^0 A^2)$;
12. $AA^0 A^2 = (AA^0 A^2)$;
13. $A^D A^0 = A^D A^0$;
14. $A^0 A = A^0 A A^0 A$;
15. $A (A^0)^2 A = AA^0$;
16. $A^D A^0 A = A^D A A^0$;
17. $(A^0)^2 = A^0$;
18. $(A^0)^2 = AA^0 A^0$;
19. $A (A^0)^2 = AA^0 D^0 A^0$;
20. $(AA^0)^2 = (AA^0)^2 AA^0 A^3$;
21. $(A^0 A)^2 = A^2 (A^0 A)^2$;
22. $AA^0$ commutes with $A^0 A$;
23. $AA^0 A = A^k (A^k)^0 A^2$;
24. $(A^0)^2 A = A^0 A$;
25. $(A^0)^2 A = A^D^0 A A^0 A^0$;
26. $(A^0)^2 A = AA^T D^0 A^0 A^0$;
27. $(A^0)^2 A = AA^0 C^0 A^0 A^0$;
28. $A^D A^0 A = A^D A^0 A^0$;
29. $A^0$ commutes with $AA^0$;
30. $AA^0 (I - AA^0 A = 0)$;
31. $A^k (I - AA^0 A = 0)$;
32. $AA^D (I - AA^0 A = 0)$;
33. $AA^D (I - AA^0 A = 0)$;
34. $A^D (I - AA^0 A = 0)$;
35. $AA^0 A^2 = AA^0 A^2$;
36. $A^2 A^D = AA^0 A^D$.

**Proof.** From [14], we know that Conditions (1)–(5) are equivalent.

Let $U$ be a unitary matrix, then $(UAU^*)^0 = UAA^0 U^*$ and $UAA^0 U^* = UAA^0 UF U^* UAA^0 U^* = (UAU^*)^0 (UAU^*)^0$.

Thus, Conditions (2) and (6) are equivalent. Let the core-EP decomposition of $A$ be as in the form [21]. By using Lemma 3, we obtain

$$AA^0 = U \begin{bmatrix} T & S \\ 0 & N \end{bmatrix} \begin{bmatrix} T^{-1} & T^{-2} S \\ 0 & 0 \end{bmatrix} U^* = U \begin{bmatrix} I_{rk(A^0)} & T^{-1} S \\ 0 & 0 \end{bmatrix} U^*,$$

$$A^D A^0 = U \begin{bmatrix} T^{-1} & T^{-2} S \\ 0 & 0 \end{bmatrix} \begin{bmatrix} T & S \\ 0 & N \end{bmatrix} U^* = U \begin{bmatrix} I_{rk(A^0)} & T^{-1} S + T^{-3} SN \\ 0 & 0 \end{bmatrix} U^*.$$
Applying [21, 27], we have

\[
AA\circ A = U \begin{bmatrix}
I_{rk(A)} & T^-1S + T^-2SN \\
0 & 0
\end{bmatrix} U^* = U \begin{bmatrix}
T & S \\
0 & 0
\end{bmatrix} U^*,
\]

By comparing [4, 7], we can get

\[
SN = 0 \iff AAA\circ = AA\circ A.
\]

Thus, Conditions (1) and (7) are equivalent.

By Lemma 4, we obtain

\[
AA\circ A = U \begin{bmatrix}
I_{rk(A)} & 0 \\
0 & 0
\end{bmatrix} U^* = U \begin{bmatrix}
T & S \\
0 & 0
\end{bmatrix} U^*,
\]

By applying [10, 13], we have

\[
AA\circ A = U \begin{bmatrix}
I_{rk(A)} & 0 \\
0 & 0
\end{bmatrix} U^* = U \begin{bmatrix}
T & S \\
0 & 0
\end{bmatrix} U^*.
\]

From what has been discussed above, we can surely come to the conclusion that

\[
SN = 0 \iff AA\circ A = AA\circ A.
\]

Thus, Conditions (1) and (8) are equivalent.

Because of [7, 16], we can get

\[
SN = 0 \iff AA\circ A = AA\circ A.
\]

Thus, Conditions (1) and (9) are equivalent.

From [6, 23], we obtain

\[
A\circ A\circ A = U \begin{bmatrix}
T^-1 & T^-2S \\
0 & 0
\end{bmatrix} \begin{bmatrix}
I_{rk(A)} & T^-1S + T^-2SN \\
0 & 0
\end{bmatrix} U^*
= U \begin{bmatrix}
T^-1 & T^-2S + T^-3SN \\
0 & 0
\end{bmatrix} U^*,
\]

\[
A\circ AA\circ = U \begin{bmatrix}
I_{rk(A)} & T^-1S + T^-2SN \\
0 & 0
\end{bmatrix} U^* = U \begin{bmatrix}
T^-1 & T^-2S \\
0 & 0
\end{bmatrix} U^*.
\]

By comparing the above equations, we have

\[
SN = 0 \iff A\circ A\circ A = A\circ AA\circ.
\]

Thus, Conditions (1) and (11) are equivalent.
By comparing the above equations, we can get
\[ SN = 0 \iff AA^0 A^2 = (AA^0 A)^2. \]  
(30)

Thus, Conditions (1) and (12) are equivalent. By applying Lemma 4, we have
\[ A^0 A^2 A^0 = U \begin{bmatrix} I_{rk(A^\ell)} & T^{-1}S + T^{-2}SN \\ 0 & 0 \end{bmatrix} U^*, \]  
(37)

\[ = U \begin{bmatrix} I_{rk(A^\ell)} & T^{-1}S \\ 0 & 0 \end{bmatrix} U^*. \]

By comparing the above equation and [6], we obtain
\[ SN = 0 \iff A^0 A^2 A^0 = A^0. \]  
(38)

Hence, Conditions (1) and (16) are equivalent. By applying Lemma 2, we have
\[ A(A^\ell)^W = U \begin{bmatrix} T & T^{-2} \quad (TS + SN) \\ 0 & 0 \end{bmatrix} U^* \]  
(39)

\[ = U \begin{bmatrix} T^{-1} & T^{-2}S + T^{-3}SN \\ 0 & 0 \end{bmatrix} U^*. \]

By using Lemma 2, we have
\[ AA^\ell = U \begin{bmatrix} T & T^{-1}S \\ 0 & 0 \end{bmatrix} - T^\ell SN^{\ell} \]  
(41)

By (41), we obtain
\[ SN = 0 \iff A(A^\ell)^W = A^W. \]  
(40)

Thus, Conditions (1) and (17) are equivalent. By applying Lemma 4, we can get
\[ AA^\ell = U \begin{bmatrix} I_{rk(A^\ell)} & T^{-1}S \\ 0 & 0 \end{bmatrix} U^* \]  
(42)

By the above equation and [27], we have
\[ SN = 0 \iff AA^\ell = AA^\ell. \]  
(43)

\[ = U \begin{bmatrix} I_{rk(A^\ell)} & T^{-k}TNN^\ell \\ 0 & 0 \end{bmatrix} U^*. \]
Because of (43), we obtain

\[
AA^{D,t} A^\oplus = U \begin{bmatrix} T^{-k} & T^{-2}N \end{bmatrix} \begin{bmatrix} T^{-1} & T^{-2}S \\ 0 & 0 \end{bmatrix} U^* = U \begin{bmatrix} T^{-1} & T^{-2}S \\ 0 & 0 \end{bmatrix} U^*. 
\]

(44)

By comparing the above formula and (39), we obtain

\[
SN = 0 \text{ if and only if } A(A^\oplus)^2 = AA^{D,t} A^\oplus. \text{ Thus, Conditions (1) and (19) are equivalent.}
\]

Applying [6, 27], we have

\[
(A^\oplus)^2 = U \begin{bmatrix} T^{-k} & T^{-2}N \end{bmatrix} \begin{bmatrix} T^{-1} & T^{-2}S \\ 0 & 0 \end{bmatrix} U^* = U \begin{bmatrix} T^{-1} & T^{-2}S \\ 0 & 0 \end{bmatrix} U^* 
\]

(45)

If \( SN = 0 \), then \( AA^\oplus)^2 = (A^\oplus)^2 AA^\oplus A^2 \). Conversely, let \( (AA^\oplus)^2 = (A^\oplus)^2 AA^\oplus A^2 \); we get \( T^{-1}S + T^{-2}SN + T^{-3}SN^2 = T^{-1}S \), that is, \( TS + SN^2 = 0 \).

By applying (35) and (37), we have

\[
AA^\oplus A = U \begin{bmatrix} T^{-1} & T^{-2}S \\ 0 & 0 \end{bmatrix} U^* = U \begin{bmatrix} T^{-1} & T^{-2}S \\ 0 & 0 \end{bmatrix} U^* 
\]

(46)

By comparing the above equation and [7], we obtain \( AA^\oplus A = A^k(A^\oplus)^0 A \). \( SN = 0 \) is equivalent to \( AA^\oplus A = A^k(A^\oplus)^0 A \). Hence, Conditions (1) and (23) are equivalent.

From [2, 23], we have \( SN = 0 \) if and only if \( A^k = (A^\oplus)^2 AA^\oplus A^2 \). Thus, Conditions (1) and (20) are equivalent.

By [6, 21, 23], we obtain

\[
A^2(A^\oplus)^2 = U \begin{bmatrix} T & S \\ 0 & 0 \end{bmatrix} \begin{bmatrix} T^{-1} & T^{-2}S \\ 0 & 0 \end{bmatrix} U^* = U \begin{bmatrix} T & S \\ 0 & 0 \end{bmatrix} U^* 
\]

(47)

By applying Lemma 4, we obtain

\[
A^{D,t} A = U \begin{bmatrix} T^{-1} & T^{-2}S \\ 0 & 0 \end{bmatrix} U^* = U \begin{bmatrix} T^{-1} & T^{-2}S \\ 0 & 0 \end{bmatrix} U^* 
\]

(48)

By comparing the above equations, we can get

\[
SN = 0 \iff (A^\oplus)^2 = A^2(A^\oplus)^2. 
\]

Thus, Conditions (1) and (21) are equivalent.
\[ AA^{1:D} = U \begin{bmatrix} T & S \\ 0 & N \end{bmatrix} \begin{bmatrix} T^* \triangle & T^* \Delta T^{-kT} \\ F_N S^* \triangle & F_N S^* \Delta T^{-kT} \end{bmatrix} U^* = U \begin{bmatrix} I_{rk(A')} & T^{-kT} \\ 0 & 0 \end{bmatrix} U^*. \] (51)

By applying (51), we have
\[ AA^{1:D} A^@ = U \begin{bmatrix} I_{rk(A')} & T^{-kT} \\ 0 & 0 \end{bmatrix} \begin{bmatrix} T^{-1} T^{-2S} \\ 0 & 0 \end{bmatrix} U^* = U \begin{bmatrix} T^{-1} T^{-2S} \\ 0 & 0 \end{bmatrix} U^* = A^@. \] (52)

Applying the above formula and [2], we can get \( SN = 0 \) if and only if \( A^@ A A^{1:D} A^@ \). Hence, Conditions (1) and (26) are equivalent.

Because of Lemma 4, we obtain
\[ AA^{C1} = U \begin{bmatrix} T & S \\ 0 & N \end{bmatrix} \begin{bmatrix} T^* \triangle & T^* \Delta T^{-kT} N \end{bmatrix} U^* = U \begin{bmatrix} I_{rk(A')} & T^{-kT} N \\ 0 & 0 \end{bmatrix} U^*. \] (53)

From (53), we have
\[ AA^{C1} A^@ = U \begin{bmatrix} I_{rk(A')} & T^{-kT} N \\ 0 & 0 \end{bmatrix} \begin{bmatrix} T^{-1} T^{-2S} \\ 0 & 0 \end{bmatrix} U^* = U \begin{bmatrix} T^{-1} T^{-2S} \\ 0 & 0 \end{bmatrix} U^* = A^@. \] (54)

By comparing the above formula and [2], we can get \( SN = 0 \) if and only if \( (A^@)^2 A = AA^{C1} A^@ \). Hence, Conditions (1) and (27) are equivalent.

By using Lemma 1 and Lemma 4, we obtain
\[ A^D A = U \begin{bmatrix} T^{-1} & T^{-2(k+1)T} \\ 0 & 0 \end{bmatrix} \begin{bmatrix} T & S \\ 0 & N \end{bmatrix} U^* = U \begin{bmatrix} I_{rk(A')} & T^{-1} T^{-2(k+1)T} N \\ 0 & 0 \end{bmatrix} U^*. \] (55)

By using the above formula, we have
\[ A^@ A^D A = U \begin{bmatrix} T^{-1} T^{-2S} & I_{rk(A')} T^{-1} S + T^{-2(k+1)T} N \\ 0 & 0 \end{bmatrix} U^* = U \begin{bmatrix} T^{-1} T^{-2S} + T^{-2(k+2)T} N \\ 0 & 0 \end{bmatrix} U^*. \] (56)

If \( SN = 0 \), we can easily prove that \( A^@ A^D A = A^@ \). Conversely, if the index of \( A \) is equal to 1 or 2, then obviously \( SN = 0 \). Let the index of \( A \) be more than or equal to 3; we get \( T^{-2S} + T^{- (k+2)} (\sum_{i=0}^{k-1} T^i SN^{k-i}) N = T^{-2S} \), that is, \( TSN^{k-1} + + T^{k-1} SN = 0 \). Postmultiplying the above equation by \( N^{k-2} \), then \( TSN^{k-3} + + T^{k-1} SN^{k-1} = 0 \), that is, \( SN = 0 \). Through \( TSN^{k-1} + + T^{k-1} SN = 0 \), we have \( T^2 SN^{k-2} + + T^{k-1} SN = 0 \). In the same way, we obtain \( T^{k-1} SN = 0 \), that is, \( SN = 0 \). From what has been discussed above, we have \( SN = 0 \) if and only if \( A^@ A^D A = A^@ \). Hence, Conditions (1) and (28) are equivalent.

By Lemma 1 and Lemma 4, we can get
\[ AA^D = U \begin{bmatrix} T & S \\ 0 & N \end{bmatrix} \begin{bmatrix} T^{-1} T^{-(k+1)T} \\ 0 & 0 \end{bmatrix} U^* = U \begin{bmatrix} I_{rk(A')} & T^{-kT} \\ 0 & 0 \end{bmatrix} U^*. \] (57)

By applying [23] and (57), we have
\[ AA^D A^@ = U \begin{bmatrix} I_{rk(A')} & T^{-kT} \\ 0 & 0 \end{bmatrix} \begin{bmatrix} T^{-1} T^{-2S} \\ 0 & 0 \end{bmatrix} U^* = U \begin{bmatrix} T^{-1} T^{-2S} \\ 0 & 0 \end{bmatrix} U^* = A^@. \] (58)

Since the above formula, \( A^@ A A^D = A^@ A^D A \) and \( A^D A^@ = A^@ A^D \) are equivalent to \( A^@ A A^D = AA^D A^@ \). Thus, Conditions (1) and (29) are equivalent.

Because of [13] and (57), we can get
\[ I - AA^@ = U \begin{bmatrix} I_{rk(A')} & 0 \\ 0 & I_{n-rk(A')} \end{bmatrix} \begin{bmatrix} I_{rk(A')} & 0 \\ 0 & 0 \end{bmatrix} U^* = U \begin{bmatrix} 0 & 0 \\ 0 & I_{n-rk(A')} \end{bmatrix} U^*. \] (59)

\[ AA^D (I - AA^@) A = U \begin{bmatrix} T^k & T^{-kT} \\ 0 & 0 \end{bmatrix} \begin{bmatrix} T & S \\ 0 & N \end{bmatrix} U^* = U \begin{bmatrix} 0 & 0 \\ 0 & T^{-kT} N \end{bmatrix} U^*. \] (60)

If \( SN = 0 \), then \( AA^D (I - AA^@) A = 0 \). Conversely, let \( AA^D (I - AA^@) A = 0 \), then \( T^{-k} (\sum_{i=0}^{k-1} T^i SN^{k-i}) N = 0 \), that is, \( TSN^{k-1} + + T^{k-1} SN = 0 \). By applying the method which is used to verify the equivalence of Conditions (1) and (28), we obtain \( SN = 0 \). From what has been discussed above, \( SN = 0 \) is equivalent to \( AA^D (I - AA^@) A = 0 \). Hence, Conditions (1) and (30) are equivalent.

From (59), we have
\[ A^R (I - AA^@) A = U \begin{bmatrix} T^k & T^{-kT} \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 0 & I_{n-rk(A')} \\ 0 & 0 \end{bmatrix} \begin{bmatrix} T & S \\ 0 & N \end{bmatrix} U^* = U \begin{bmatrix} 0 & T^{-kT} N \\ 0 & 0 \end{bmatrix} U^*. \] (61)
If $SN = 0$, then $A^k(I - AA^0)A = 0$. Conversely, let $A^k(I - AA^0)A = 0$, then $(\sum_{i=0}^{k-1}TSN^{k-1-i})N = 0$, that is, $TSN^{k-1} + \ldots + T^{k-1}SN = 0$. By applying the method which is used to verify the equivalence of Conditions (1) and (28), we obtain $SN = 0$. From what has been discussed above, $SN = 0$ is equivalent to $A^k(I - AA^0)A = 0$. Hence, Conditions (1) and (31) are equivalent.

By using [13], (43), and (59), we get

$$AA^{D,1}(I - AA^0)A = U \left[ \begin{array}{c} I_{rk}(A^0) \\ 0 \\ 0 \end{array} \right] T^{-k} TNN^0 = 0$$

\[ U = U \left[ \begin{array}{c} 0 \\ T^{-k} TNN^0 \\ 0 \\ 0 \end{array} \right]. \tag{62} \]

If $SN = 0$, then $AA^{D,1}(I - AA^0)A = 0$. Conversely, let $AA^{D,1}(I - AA^0)A = 0$, then $T^{-k}((\sum_{i=0}^{k-1}T^i)(SN^{k-1-i}))N = 0$, that is, $TSN^{k-1} + \ldots + T^{k-1}SN = 0$. By applying the method which is used to verify the equivalence of Conditions (1) and (28), we obtain $SN = 0$. From what has been discussed above, $SN = 0$ is equivalent to $AA^{D,1}(I - AA^0)A = 0$. Thus, Conditions (1) and (32) are equivalent.

By Lemma 4, [10], and (59), we obtain

$$A^{1,D}(I - AA^0)A = U \left[ \begin{array}{c} T^\Delta \\ T^\Delta T^{-k} T \end{array} \right] F_{N^* S^*} \Delta F_{N^* S^*} T^{-k} T \cdot \left[ \begin{array}{c} 0 \\ I_{-rk}(A^0) \end{array} \right] T S \cdot \left[ \begin{array}{c} 0 \\ 0 \\ 0 \\ 0 \end{array} \right] U^* \tag{63} \]

$$= U \left[ \begin{array}{c} 0 \\ T^\Delta T^{-k} TNN^0 \\ 0 \\ F_{N^* S^*} T^{-k} TNN^0 \end{array} \right] U^*. \tag{64} \]

If $SN = 0$, then $A^{1,D}(I - AA^0)A = 0$. Conversely, let $A^{1,D}(I - AA^0)A = 0$, then $T^\Delta [T^{\Delta^*} + SF_{N^* S^*}]^1 T^{-k}((\sum_{i=1}^{k-1}T^i)(SN^{k-1-i}))N = 0$ and $T^\Delta [T^{\Delta^*} + SF_{N^* S^*}]^1 T^{-k}((\sum_{i=0}^{k-1}T^i)(SN^{k-1-i}))N = 0$. By applying the method which is used to verify the equivalence of Conditions (1) and (28), we obtain $SN = 0$. From what has been discussed above, $SN = 0$ is equivalent to $A^{1,D}(I - AA^0)A = 0$. Hence, Conditions (1) and (33) are equivalent.

By Lemma 4, [13], and (59), we have

$$A^{c,1}(I - AA^0)A = U \left[ \begin{array}{c} T^\Delta \\ T^\Delta T^{-k} TNN^0 \end{array} \right] F_{N^* S^*} \Delta F_{N^* S^*} T^{-k} TNN^0 = 0$$

\[ = U \left[ \begin{array}{c} 0 \\ T^\Delta T^{-k} TNN^0 \\ 0 \\ F_{N^* S^*} T^{-k} TNN^0 \end{array} \right] U^*. \tag{64} \]

If $SN = 0$, then $A^{c,1}(I - AA^0)A = 0$. Conversely, let $A^{c,1}(I - AA^0)A = 0$, then $T^\Delta [T^{\Delta^*} + SF_{N^* S^*}]^1 T^{-k}((\sum_{i=1}^{k-1}T^i)(SN^{k-1-i}))N = 0$ and $T^\Delta [T^{\Delta^*} + SF_{N^* S^*}]^1 T^{-k}((\sum_{i=0}^{k-1}T^i)(SN^{k-1-i}))N = 0$. By applying the method which is used to verify the equivalence of Conditions (1) and (28), we obtain $SN = 0$. From what has been discussed above, $SN = 0$ is equivalent to $A^{c,1}(I - AA^0)A = 0$. Hence, Conditions (1) and (34) are equivalent.

By applying [4, 8], we obtain $SN = 0$ if and only if $A^0 A^2 = A^2 A^W$. Hence, Conditions (1) and (35) are equivalent.

Because of [16], (57) and

$$AAA^D = U \left[ \begin{array}{c} T \ S \\ 0 \ N \end{array} \right] I_{rk}(A^0) T^{-k} U^* = U \left[ \begin{array}{c} T T^{-k} U^* \end{array} \right]. \tag{65} \]

If $SN = 0$, then $A^2 A^D = AA^0 A$. Conversely, let $A^2 A^D = AA^0 A$, then $T^{-k-1}((\sum_{i=0}^{k-1}T^i)(SN^{k-1-i})) = S$, that is, $T^{-k-1}S N^{k-1} + \ldots + T^{k-1}SN = 0$. By applying the method which is used to verify the equivalence of Conditions (1) and (28), we obtain $SN = 0$. From what has been discussed above, $SN = 0$ is equivalent to $A^2 A^D = AA^0 A$. Hence, Conditions (1) and (36) are equivalent.

3. Generalized Cayley–Hamilton Theorem

In this section, we extend the classical Cayley–Hamilton theorem to some special matrix such as the WG matrix.

**Theorem 3** (see [21]). Let $A \in C_{nn}$: the characteristic polynomial of $A$ is

$$p_A(s) = det(sI_n - A) = s^n + a_{n-1}s^{n-1} + \ldots + a_1s + a_0,$$  \tag{66} \]

then

$$p_A(A) = A^n + a_{n-1}A^{n-1} + \ldots + a_1A + a_0I_n = 0.$$  \tag{67} \]

In [21], if $A$ is singular, then $a_0 = 0$.

**Theorem 4.** Let $A \in C_{nn}$ be singular with $Ind(A) = k$. If

$$det(sI_n - A) = s^n + a_{n-1}s^{n-1} + \ldots + a_1s,$$  \tag{68} \]

then

$$A^\circ + a_{n-1}(A^\circ)^{n-1} + \ldots + a_1A = 0.$$  \tag{69} \]

where $A^\circ \in C_{nn}$ is the weak group inverse of the matrix $A$.

**Proof.** Let $A \in C_{nn}$ be singular; we use the Cayley–Hamilton theorem, then

$$A^n + a_{n-1}A^{n-1} + \ldots + a_1A = 0.$$  \tag{70} \]

Postmultiplying the above equation by $(A^\circ)^{n+1}$, we get

$$A^n(A^\circ)^{n+1} + a_{n-1}A^{n-1}(A^\circ)^{n+1} + \ldots + a_1A(A^\circ)^{n+1} = 0.$$  \tag{71} \]
By using the properties of the WG matrix, that is, \( A(\mathbb{A})^2 = \mathbb{A} \), we have \( A(\mathbb{A})^{p_{n+1}} = A(\mathbb{A})^p_{n+1} = A^p (\mathbb{A})^{p_{n+1}} = (\mathbb{A})^{p_{n+1}} \). A similar method can be used to obtain \( A^2 (\mathbb{A})^{p_{n+1}} = (\mathbb{A})^{p_{n+1}} \), \( \ldots \), \( A^{n-1} (\mathbb{A})^{p_{n+1}} = (\mathbb{A})^{p_{n+1}} \), and \( A^n (\mathbb{A})^{p_{n+1}} = \mathbb{A}^W \). Substituting the above equations into (71), we have (69).

Example 1. Let

\[
A = \begin{bmatrix} 1 & 0 \\ -1 & 0 \end{bmatrix}.
\]  

(72)

It is easy to confirm that the weak group inverse \( A^W \in C_{n,n} \) is

\[
A^\circ = \begin{bmatrix} 1 & 0 \\ -1 & 0 \end{bmatrix}.
\]  

(73)

Then,

\[
\det(sI_2 - A) = \begin{vmatrix} s - 1 & 0 \\ 1 & s \end{vmatrix} = s^2 - s.
\]  

(74)

From the classical Cayley–Hamilton theorem, we have

\[
A^2 - A \begin{bmatrix} 1 & 0 \\ -1 & 0 \end{bmatrix} - \begin{bmatrix} 1 & 0 \\ -1 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}.
\]  

(75)

By applying Theorem 4, we obtain

\[
A^\circ - (A^\circ)^2 = \begin{bmatrix} 1 & 0 \\ -1 & 0 \end{bmatrix} - \begin{bmatrix} 1 & 0 \\ -1 & 0 \end{bmatrix}^2 = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}.
\]  

(76)

The characteristic polynomial of \( T^{-1} \) is

\[
p_{T^{-1}}(s) = \det(sI_{tk(A^\circ)} - T^{-1}) = s^{n-k(A^\circ)} - b_{n-1}r^k(A^\circ) - 1 + \cdots + b_{n-k(A^\circ) - 1}r^k(A^\circ).
\]  

(78)

It is given by the classical Cayley–Hamilton theorem

\[
p_{T^{-1}}(T^{-1}) = (T^{-1})^{r^k(A^\circ)} + b_{n-1}(T^{-1})^{r^k(A^\circ) - 1} + \cdots + b_{n-k(A^\circ) - 1}r^k(A^\circ) + b_{n-k(A^\circ)}I_{rk(A^\circ)} = 0.
\]  

(79)

Postmultiplying the above equation by \( T^{rk(A^\circ)} \),

\[
I_{rk(A^\circ)} + b_{n-1}T + \cdots + b_{n-k(A^\circ) - 1}T^{rk(A^\circ) - 1} + b_{n-k(A^\circ)}T^{rk(A^\circ)} = 0.
\]  

(80)

By using (77) and (78), we have Theorem 5.

Theorem 5. Let \( A \in C_{n,n} \) with \( \text{Ind}(A) = k \), then the characteristic polynomial of \( A^\circ \) is

\[
p(s) = \det(sI_n - A) = s^n + b_{n-1}s^{n-1} + \cdots + b_{n-k(A^\circ)}s^{n-r^k(A^\circ)},
\]  

(81)

where \( b_{n-1}, \ldots, b_{n-k(A^\circ)} \) is as in (78).

Example 2. Let

\[
A = \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}.
\]  

(82)

then \( \text{Ind}(A) = 2, \text{rk}(A^2) = 2 \), and

\[
T = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix},
\]  

(83)

\[
A^\circ = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}.
\]

Furthermore,

\[
p_{T^{-1}}(s) = s^2 - 2s + 1, \quad p_{A^\circ}(s) = s^2(s^2 - 2s + 1) = s^4 - 2s^3 + s^2,
\]

\[
\begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}^4 \cdot \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}^3 \cdot \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}^2 = 0.
\]  

(84)

4. Conclusion

In this paper, we give some new characterizations of the WG matrix. Some relations between various well-known generalized inverses and the WG matrix are proved, and
generalized Cayley–Hamilton theorem for special matrices such as WG matrix is given. We are convinced that researches about the WG matrix will also gain more attention in the near future. Some perspectives for further researches can be described as follows: (1) our further goal will be to investigate the definition, properties, and characterizations of tensor WG matrix; (2) further, we will study the iterative algorithm of the tensor WG matrix and its application [28].

Data Availability

No data were used to support this study.

Conflicts of Interest

The authors declare that they have no conflicts of interest.

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