Magnetic Field Evolution in Superconducting Neutron Stars

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ABSTRACT

The presence of superconducting and superfluid components in the core of mature neutron stars calls for the rethinking of a number of key magnetohydrodynamical notions like resistivity, the induction equation, magnetic energy and flux-freezing. Using a multi-fluid magnetohydrodynamics formalism, we investigate how the magnetic field evolution is modified when neutron star matter is composed of superfluid neutrons, type-II superconducting protons and relativistic electrons. As an application of this framework, we derive an induction equation where the resistive coupling originates from the mutual friction between the electrons and the vortex/fluxtube arrays of the neutron and proton condensates. The resulting induction equation allows the identification of two timescales that are significantly different from those of standard magnetohydrodynamics. The astrophysical implications of these results are briefly discussed.

Key words: Magnetohydrodynamics (MHD) – stars: magnetic fields – stars: neutron.

1 INTRODUCTION

Existing at the extremes of physics, neutron stars serve as excellent cosmic laboratories. Some of the most striking features are related to their magnetic properties. Measured magnetic field strengths, generally inferred from the star’s dipole spin-down, by far exceed the strengths of terrestrial magnets. Observations also suggest a link between the various classes of neutron stars. Old millisecond pulsars thought to be formed in low-mass X-ray binaries have fields between $10^8 - 10^{10}$ G, while the fields of ‘classical’ rotation-powered pulsars range between $10^9 - 10^{13}$ G. A third class of slowly rotating, highly magnetised neutron stars, so-called magnetars, reaches field strengths up to $10^{15}$ G. This class is believed to include both, soft gamma repeaters and anomalous X-ray pulsars. Understanding the long-term evolution of the stars’ magnetic fields might be key to establishing connections between the different classes and forming a unified picture of the neutron star ‘zoo’ [Kaspi 2013; Viganò et al. 2012; Harding 2013].

Unsurprisingly, such enormous strengths suggest that magnetic fields are crucial for the neutron stars’ dynamics. As first pointed out by Thompson & Duncan (1995; 1996), magnetic field decay on a timescale of $\sim 10^4$ yr could power the high activity of magnetars. The rotational energy is not sufficient to explain the observed emission of these objects. There are also observations indicating that the magnetic dipole fields of standard pulsars evolve on a timescale of the order $10^7$ yr [Lyne, Manchester & Taylor 1993; Narayan & Ostriker 1990].

The actual mechanisms, causing the magnetic field to change on these rather short timescales, are only poorly understood and there is no definitive answer to the question of which part of the neutron star dominates the magnetic field evolution. Most theoretical studies and numerical simulations focus on the crust as the source of the field decay and neglect the core contribution [Pons & Geppert 2007; Viganò et al. 2012; Gourgouliatos & Cumming 2014]. However, one could argue that the core, which carries the majority of the star’s inertia and magnetic energy, should also play a role in the magnetic field evolution.

The problem of magnetic field evolution in isolated neutron stars has been discussed by a number of authors. Goldreich & Reisenegger (1992) determined several mechanisms that are present in an ionised plasma consisting of neutrons, protons and electrons. Ohmic diffusion due to the interaction of relativistic electrons and lattice nuclei causes magnetic field dissipation in the crust. This mechanism is most effective on small scales and, thus, not expected to affect the large scale evolution of the crustal field.

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However, Ohmic decay could be enhanced by Hall drift, which is in itself conservative but may redistribute magnetic energy from large to gradually smaller lengthscales. The combined effect, sometimes referred to as the Hall cascade, could cause field evolution on a timescale of order 10³ years (Goldreich & Reisenegger 1992). However, recent neutron star crust simulations show no strong cascading behaviour but suggest the existence of a quasi-equilibrium established on timescales shorter than the Ohmic timescale (Pons & Geppert 2014; Gourgouloutos & Cumming 2014; Wood & Hollerbach 2015). In the core, standard Ohmic decay is negligible because the interior is expected to form a type-II superconductor (Baym, Pethick & Pines 1969a, see also below). Electron-proton scattering, already acting on very long timescales in the star’s interior (Baym, Pethick & Pines 1969a), is then restricted to the normal conducting cores of fluxtubes. These only contribute a tiny fraction to the star’s total cross section. Hence, the coupling timescale is increased further, making this dissipation mechanism irrelevant. Additionally, ambipolar diffusion, describing the motion of charged particles and magnetic field lines relative to the neutrons, could cause magnetic field decay and drive the flux from the core to the crust (Goldreich & Reisenegger 1992). This mechanism was originally considered by Thompson & Duncan (1995) to explain the magnetar activity. However, more recent results seem to indicate that the timescale for ambipolar diffusion considerably increases when the superfluid nature of the neutrons or proton superconductivity is taken into account (Glampedakis, Jones & Samuelsson 2011).

Lacking a clear answer, the question of magnetic field evolution in a neutron star is revisited in this paper. We focus on the outer core and use the formalism developed by Glampedakis, Andersson & Samuelsson (2011) (see also Mendell & Lindblom 1991, Mendell 1991), which presents a general set of macroscopic hydrodynamic equations for a multi-fluid mixture. We address, in particular, the effect of the superconducting component has on the evolution of the magnetic field.

The presence of superfluid and superconducting components in neutron stars is firmly supported by observations and microphysical calculations. Traditionally, glitches and post-glitch relaxation timescales on the order of months to years are seen as observational evidence of superfluidity. Anderson & Holz (1973) first proposed that the neutron star’s dynamical evolution during and after a glitch could be explained by the weak viscous properties of a superfluid component that is coupled to the crust. Moreover, recent spectral analyses of the neutron star in the supernova remnant Cassiopeia A indicate that the surface temperature of this young object decreases faster than one would expect from standard cooling models (Page et al 2011, Shaterin et al 2011). The rapid cooling could be explained by enhanced neutrino emission, resulting from the onset of neutron superfluidity and proton superconductivity in the core. In addition to observations, theoretical calculations provide strong reasons for macroscopic quantum condensates in neutron star cores. The idea of superfluid interiors was first put forward by Migdal (1950), several years before the first detection of a pulsar (Hewish et al 1968). A few hundred years after birth, neutron stars are in thermal equilibrium and have temperatures of $10^6 - 10^8$ K (Tsuruta 1998; Page, Geppert & Weber 2000; Ho, Glampedakis & Andersson 2012). While this is certainly hot in terms of terrestrial physics, the temperatures lie well below the Fermi temperature of nuclear matter, which is of the order $10^{12}$ K (Sauls 1988). Applying the microscopic theory of laboratory superconductors (Bardeen, Cooper & Schrieffer 1957) to the neutron star interior suggests that the neutrons and protons form Cooper pairs and, thus, condense into a superfluid and a superconductor, respectively.

The properties of the proton superconductor were further discussed in the seminal paper by Baym, Pethick & Pines (1969a). As the conductivity of normal conducting matter is very large (Baym, Pethick & Pines 1969a), the authors argued that flux could not be expelled from the star’s interior. The phase transition into a superconducting state has to occur at constant magnetic flux. Two characteristic lengthscales determine the state of the superconducting protons. The London penetration depth describes the magnetic field’s exponential fall-off from the surface of a superconductor or the fluxtube cores due to the Meißner effect. The coherence length, which characterises the typical dimensions of a Cooper pair, is equivalent to the core radius of a fluxtube. The ratio of these two quantities, the Ginzburg-Landau parameter, $\kappa$, dictates the type of superconductivity. For $\kappa > 1/\sqrt{2}$, it is energetically favourable for the material to increase the surface area between normal and superconducting regions, implying that magnetic flux can penetrate the medium in the form of quantised fluxlines (Abrikosov 1957). Baym, Pethick & Pines (1969a) estimated $\kappa$ for the neutron star’s outer core and found that the protons would enter a metastable type-II state by forming a regular array of fluxtubes (see also Figure 1 of Glampedakis, Andersson & Samuelsson 2011).

The presence of fluxtubes significantly influences the magnetic properties of the star because the flux is no longer locked to the charged plasma but is mainly confined inside the fluxtubes. As standard coupling mechanisms, like Ohmic dissipation, are suppressed as a result of pairing, interactions of fluxlines with their surroundings determine the magnetic field evolution on macroscopic lengthscales. The most prominent of these effective coupling processes, known as mutual friction, is the scattering of electrons off the fluxtube magnetic field (Alpar, Langer & Sauls 1984; Mendell 1997; Andersson, Sidery & Comer 2006). In the following, we derive an equation for the magnetic field evolution of a superfluid/superconducting mixture using a smooth-averaged formalism. We translate the mesoscopic phenomena, influencing individual fluxtubes, to the large scale picture by applying the framework known from standard resistive magnetohydrodynamics (MHD).

The structure of this paper is as follows. In Section 2 we introduce the hydrodynamical equations for a multi-fluid system and the corresponding Maxwell equations. In Section 3 the standard resistive MHD formalism is reviewed. We then discuss the case of superconducting matter in Section 4 focussing on the standard resistive coupling introduced by Alpar, Langer & Sauls (1984). After giving the most general form of the superconducting induction equation, we use a few assumptions to simplify and interpret our results. We finally conclude with a discussion in Section 5.

Note that we will work in an inertial frame and carry
out the analysis in a coordinate basis. Vectors are, thus, denoted by their individual components. We also use Gaussian units in the remainder of this paper.

2 THEORETICAL BACKGROUND

2.1 Multi-fluid hydrodynamics

The model presented in this section largely builds upon the recent work by [Glampedakis, Andersson & Samuelsson (2011)]. Making use of the Lagrangian formalism developed by Carter, Prix and collaborators [Carter & Langlois (1993); Prix (2004); Andersson & Comer (2006)], a full set of MHD equations for the superfluid/superconducting bulk in the outer neutron star core is derived. The simplest representation of this Fermi liquid is a mixture of three components, namely relativistic electrons, superconducting protons and superfluid neutrons. In the following, the constituents are denoted by roman indices, $x = \{e, p, n\}$. Note that in order to keep the discussion clear, we neglect the presence of muons. However, generalising to the four-constituent case would be straightforward as electrons and muons are strongly coupled and move as one component on macroscopic length scales [Andersson & Samuelsson (2011)].

The dynamics of the three-fluid system is governed by two Euler equations, one representing the superfluid neutrons and the other representing the electron-proton conglomerate. The charged fluids can be characterised as a strongly coupled and move as one component on macroscopic scales that we have a method to deal with the presence of the quantum condensates in a consistent way. Taking advantage of the large numbers of vortices/fluxtubes, we average over the respective arrays and obtain a smooth-averaged description of the magnetic and mutual friction forces. Using this formalism, it is possible to determine how the presence of vortices and fluxtubes influences the macroscopic dynamics of a neutron star, i.e. its rotational and magnetic evolution. If individual vortices/fluxtubes do not overlap and are distant enough so that interactions within one array can be neglected, the averaging procedure is obtained from the macroscopic quantisation conditions originally developed by Onsager (1949) and Feynman (1953) for the dynamics of rotating superfluid helium. Assuming that neutron vortices and proton fluxtubes are locally straight and directed along the unit vectors, $\hat{\kappa}_e$ and $\hat{\kappa}_p$, the arrays can be assigned vortex and fluxtube surface densities, $N_e$ and $N_p$, respectively.

The variational approach used to derive the Euler and continuity equations explicitly distinguishes between the fluid momenta and velocities. This formalism provides the possibility to include any changes, caused by the superfluid and superconducting condensates, into the hydrodynamical model. In contrast to the momentum equations of standard plasma physics [Jackson (1999)], Equations (1) and (2) incorporate new inertial terms due to entrainment, which arise from the strong coupling of Fermi liquids, and terms that go beyond the standard electromagnetic interaction given by the Lorentz force. For the fluid mixture in the outer neutron star core, the right-hand sides of the momentum equations contain the total magnetic and mutual friction forces per unit volume, $f_{\text{mag}, x}^i$ and $f_{\text{int}}^i$, respectively. The former one is caused by interactions of the vortex/fluxtube magnetic field with the charged fluid. We point out that the neutron fluid experiences this magnetic force because protons are entrained around each neutron vortex and create an effective magnetic field. In the absence of entrainment, the magnetic force on the neutron component would vanish. Finally, the mutual friction forces arise from the dissipative coupling of the vortex and fluxtube array with the fluid components.

We keep in mind that our hydrodynamic model is solely based on averaged quantities and reflects the macroscopic behaviour of the fluid components. It is on these large scales that we have a method to deal with the presence of the quantum condensates in a consistent way. Taking advantage of the large numbers of vortices/fluxtubes, we average over the respective arrays and obtain a smooth-averaged description of the magnetic and mutual friction forces. Using this formalism, it is possible to determine how the presence of vortices and fluxtubes influences the macroscopic dynamics of a neutron star, i.e., its rotational and magnetic evolution. If individual vortices/fluxtubes do not overlap and are distant enough so that interactions within one array can be neglected, the averaging procedure is obtained from the macroscopic quantisation conditions originally developed by Onsager (1949) and Feynman (1953) for the dynamics of rotating superfluid helium. Assuming that neutron vortices and proton fluxtubes are locally straight and directed along the unit vectors, $\hat{\kappa}_e$ and $\hat{\kappa}_p$, the arrays can be assigned vortex and fluxtube surface densities, $N_e$ and $N_p$, respectively.

The averaged fluid velocities are denoted by $v_x^j$ and the mass densities by $\rho_x = m n_x$, where $m = m_e = m_p$ is the baryon mass. $w_{x y} \equiv v_x^j - v_y^j$ is the relative velocity, $\Phi$ the gravitational potential and $\varepsilon_x$ the entrainment parameters. By definition, the latter satisfy the condition $n_p \varepsilon_p = n_e \varepsilon_e$. The specific chemical potentials are defined as

$$\bar{\mu}_x \equiv \frac{\mu_x}{m}, \quad \bar{\mu} \equiv \frac{\bar{\mu}_e + \bar{\mu}_p}{2}$$

The two Euler equations are supplemented by three continuity equations for the number densities,

$$\partial_t n_x + \nabla_i (n_x v_x^i) = 0,$$

which reflect the conservation of mass for each individual species, and the Poisson equation

$$\nabla^2 \Phi = 4\pi G \rho.$$
The proton charge, the speed of light and the Planck constant are denoted by $e$, $c$ and $\hbar$, respectively.

2.2 Macroscopic magnetic induction

In the averaged framework, the total magnetic induction, $B'$, is the sum of three individual components, namely the averaged fluxtube and vortex field and the London field,

$$ B' = B'_V + B'_K + B'_L. \quad (10) $$

The former two contributions are obtained by multiplying the surface densities, $N_x$, with the flux carried by a single line of the lattice, $\phi_x$. The fluxes can be derived by considering the dynamics of a single vortex/fluxtube on mesoscopic length scales, denoted by bars on the respective quantities. Using the corresponding quantisation condition and the mesoscopic Ampère law (e.g. see Appendix A of Glampedakis, Andersson & Samuelsson (2011) for details), it is possible to derive generalised London equations for the mesoscopic magnetic fields, $b'_x$,

$$ \lambda^2 \nabla^2 b'_\alpha - B'_\alpha = -\phi_x \kappa_x^i \delta(\vec{r}), \quad (11) $$

where $\delta(\vec{r})$ is the two-dimensional delta function located at the centre of each vortex/fluxtube, $\phi_x$ is defined below and the effective London penetration depth is given by

$$ \lambda_x = \left( \frac{1}{4\pi \rho_p \alpha_p^2} \frac{1 - \epsilon_n - \epsilon_p}{1 - \epsilon_n} \right)^{1/2}. \quad (12) $$

In the absence of entrainment, $\epsilon_n = \epsilon_p = 0$, this expression reduces to the standard result of superconductivity (Tinkham 2004). Taking advantage of the symmetry and using cylindrical coordinates, the inhomogeneous Helmholtz equation (11) can be solved using a Green’s function approach in two dimensions (Fetter & Hohenberg 1969). Integrating the resulting magnetic induction over a disc of radius $r \gg \lambda_x$ perpendicular to $\hat{k}_x^i$ gives for the magnetic flux

$$ \int B'_x dS = \phi_x \hat{k}_x^i. \quad (13) $$

For a proton fluxtube, we obtain the expected unit of flux,

$$ \phi_p = \phi_0 = \frac{\kappa}{\alpha_p} = \frac{\hbar c}{2e} \approx 2.1 \times 10^{-7} \text{G cm}^2, \quad (14) $$

whereas the flux of a superfluid vortex is

$$ \phi_n = -\frac{\epsilon_p}{1 - \epsilon_n} \phi_0. \quad (15) $$

We note that the minus sign originates from $\hat{k}_n^i$ and $B'_n$ pointing in opposite directions. In the absence of entrainment, the neutron flux would be zero. The averaged contributions from the two arrays to the macroscopic magnetic induction, $B'$, are then obtained by

$$ B'_x = N_x \phi_x \hat{k}_x^i. \quad (16) $$

The third contribution to the induction is the London field. It is a fundamental property of a superconductor and associated with its rotation (Tilley & Tilley 1990). While superfluids need to form vortices in order to support any circulation, the superconducting fluxtube array is not related to the macroscopic rotation. However, these dynamics induce an additional magnetic field inside the superconductor, whose axis is parallel to the rotation axis. In contrast to $B'_x$, the London field is not of microscopic origin but related to the macroscopic electromagnetic current (see Subsection 2.3). Combining the quantisation conditions (11) and (12) with Equation (16), the London field can be related to the macroscopic fluid properties. Assuming that the hydrodynamical lengthscales are sufficiently small to ensure constant entrainment parameters, we have

$$ b'_L = \frac{1}{\alpha_p} \frac{1 - \epsilon_n - \epsilon_p}{1 - \epsilon_n} \epsilon_p \nabla_v \vec{v}^p. \quad (17) $$

The proton entrainment parameter is related to the effective proton mass via

$$ \epsilon_p = 1 - \frac{m^*_p}{m} \approx 0.3, \quad (18) $$

where we have used the estimate $m^*_p \approx (0.6 - 0.9)m$ given by Chamel & Haensel (2006) for the outer neutron star core. For small proton fractions, $x_p \equiv \rho_p/\rho \ll 1$, an approximation which is valid in the interior of a neutron star, the neutron entrainment coefficients is negligible because $\epsilon_n \approx x_p \epsilon_p \ll 1$. Taking the proton fluid to be tightly coupled to the neutron star’s crust through the magnetic field and, thus, rotating rigidly at the observable pulsar frequency, we can substitute a canonical rotation period to calculate an estimate for the magnitude of the London field. Using the normalisation $P_{10} \equiv P/(10 \text{ms})$, we find

$$ b'_L \approx 9.2 \times 10^{-2} P_{10}^{-1} \text{G}, \quad (19) $$

which is many orders of magnitude smaller than the magnetic field strengths usually invoked for neutron star physics. Hence, it is generally justified to neglect the London field in Equation (11), an approach we will take in Subsection 2.3.

We can simplify the magnetic induction, $B'$, one step further by taking the properties of the vortex and fluxtube arrays into account. Although the individual fluxes, $\phi_x$, are comparable, the contribution from the superconducting protons dominates: Consider smooth-averaged fluid velocities of the form $\epsilon_p \nabla_v \vec{v}^p \approx 2 \kappa \phi_0 \hat{z}$. In this case, the vortices/fluxtubes are aligned with the $z$-axis, i.e. $\hat{z} = \hat{k}_x^i$, and Equation (16) gives

$$ N_x \epsilon_p = \frac{2}{\kappa} [\Omega_n + \epsilon_n \Omega_p]. \quad (20) $$

As we expect the lag, $\Omega_p = \Omega_n$, to be small on macroscopic scales and the neutrons to be coupled to the crust, the vortex surface density is

$$ N_x \approx \frac{4\pi}{\kappa P_{10}} \approx 6.3 \times 10^5 P_{10}^{-1} \text{cm}^{-2}, \quad (21) $$

The neutron vortex density is, thus, fixed by the rotation of the neutron star. Using previous estimates for the entrainment parameters, the magnetic field strength of the neutron vortex array is

$$ B_n \approx N_x \epsilon_p \phi_0 \approx 4.0 \times 10^{-2} P_{10}^{-1} \text{G}. \quad (22) $$

This is again many orders of magnitude smaller than typical neutron star field strengths, which implies that the magnetic field of the outer neutron star core is mainly confined to the proton fluxtube cores. It is, therefore, important to investigate which mechanisms affect the motion of individual fluxtubes in order to understand small scale behaviour to the large scale evolution of the star’s magnetic field. The
Euler equation, to obtain an expression for \( E^i \). Neglecting again the electron inertial terms, we have

\[
E^i = -\frac{1}{c} \epsilon^{ijk} v^j \dot{B}_k - \frac{m_e}{c} \nabla^i (\mu_e + \Phi) - \frac{F^i_e}{c n_e \rho_p},
\]

where \( F^i_e \) represents the total force exerted on the electrons due to interactions with the surrounding fluid components.

Combining Equations (28) and (29) leads to an evolution equation for the magnetic induction that only depends on macroscopic fluid variables. However, the procedure relies on the forces, \( F^i_e \), and we address this in the following sections.

### 3 Magnetic Field Evolution in Standard MHD

Before discussing the more complicated problem of magnetic field evolution in a superfluid/superconducting mixture, we briefly review the approach taken in normal resistive matter, which allows us to compare our new results with a well studied model.

#### 3.1 The MHD Induction Equation

In a charged plasma containing electrons and protons, the only relative flow present is the motion between the two species. Assuming that a frictional mechanism would damp these dynamics and try to bring the two species into co-motion is straightforward. Hence, resistive coupling acting on a timescale \( \tau_e \) leads to a dissipative force on the electron fluid,

\[
F^i_e = \frac{n_e m_e}{\tau_e} \omega_{pe}^i - \frac{m_e}{\tau_e} J^i.
\]

Substituting this force into Equation (20) gives a generalised Ohm’s law

\[
E^i = -\frac{1}{c} \epsilon^{ijk} \left( \frac{v^j}{\epsilon n_e} - \frac{J^j}{\epsilon n_e} \right) \dot{B}_k - \frac{m_e}{c} \nabla^i (\mu_e + \Phi) + \frac{J^i}{\sigma_e}.
\]

with the standard electrical conductivity defined by

\[
\sigma_e \equiv \frac{\epsilon n_e \Lambda_e}{m_e} = \frac{n_e e^2 \tau_e}{m_e}.
\]

Equation (31) combined with Faraday’s law (25) leads to an evolution equation for the magnetic induction,

\[
\partial_t B^i = \epsilon^{ijk} \nabla_j \epsilon_{klm} \left( \frac{v^l B^m}{c^2} - \epsilon^{ijk} \nabla_j \epsilon_{klm} \left( \frac{m_e}{4 \pi \sigma_e} \nabla^l B^m \right) - \epsilon^{ijk} \nabla_j \epsilon_{klm} \left( \frac{m_e}{4 \pi \sigma_e \rho_p} \epsilon_{spq} \nabla_p B_k \right) B^m \right).
\]

We have used Ampère’s law for normal matter (25) to eliminate the macroscopic current in the last expression. The second and the third term on the right-hand side represent the Ohmic decay and the Hall evolution. We can extract the following well-known timescales,

\[
\tau_{\text{Ohm}} = \frac{4 \pi \sigma_e L^2}{c^2},
\]

and

\[
\tau_{\text{Hall}} = \frac{4 \pi \epsilon_p B}{mc}.
\]
where $L$ is the characteristic lengthscale over which the magnetic field changes.

### 3.2 Flux-freezing in MHD

We can estimate the two characteristic timescales for a neutron star core. According to Baym, Pethick & Pines (1969a), the electrical conductivity associated with the interaction of highly relativistic electrons and normal, degenerate protons is given by

$$ \sigma \approx 5.5 \times 10^{28} T_8^{-2/3} \rho_{14}^{3/2} \left( \frac{x_p}{0.05} \right)^{3/2} \text{s}^{-1}, $$

(36)

where $T_8 \equiv T/(10^8 \text{K})$ is the star’s normalised temperature, $\rho_{14} \equiv \rho/(10^{14} \text{g cm}^{-3})$ the normalised total density and $x_p$ the proton fraction. Approximating the characteristic lengthscale by the radius of the neutron star, the Ohmic diffusion timescale is

$$ \tau_{\text{Ohm}} \approx 2.4 \times 10^{13} T_8^{-2/3} L_6^2 \rho_{14}^{3/2} \left( \frac{x_p}{0.05} \right)^{3/2} \text{yr}, $$

(37)

with the normalised lengthscale $L_6 \equiv L/(10^6 \text{cm})$. For the Hall timescale, we obtain

$$ \tau_{\text{Hall}} \approx 1.9 \times 10^{10} B_{12}^{-1} L_6^2 \rho_{14} \left( \frac{x_p}{0.05} \right) \text{yr}. $$

(38)

Both estimates are many orders of magnitude larger than the typical spin-down ages of radio pulsars. We would, therefore, expect Ohmic decay and Hall term to be negligible for the evolution of the plasma’s magnetic field. In this idealised case, which is commonly used to approximate astrophysical or laboratory plasmas, the induction equation reduces to

$$ \partial_t B^i = \epsilon^{ijk} \nabla_j \epsilon_{klm} \left( \epsilon^{lm}_{\nu} B^\nu \right). $$

(39)

Using Equation (27), we can rewrite the last expression and simplify the result using the standard Lie derivative,

$$ \partial_t B^i + L_{v}\nu B^i = -B^i \nabla \epsilon_{\nu}. $$

(40)

The left-hand-side describes how the magnetic field vector, $B^i$, is transported with the fluid flow, $v_{\nu}$. Taking into account that the mass of the proton plasma is conserved, we use Equation (14) to further simplify,

$$ \frac{\partial}{\partial t} \left( \frac{B^i}{\rho_p} \right) + L_{v}\nu \left( \frac{B^i}{\rho_p} \right) = 0. $$

(41)

This implies that the magnetic field is moving with the fluid, i.e. the fluxlines are frozen into the proton plasma.

As soon as Ohmic and Hall terms play a role for the dynamics, this frozen-in condition is destroyed and field lines are no longer forced to follow the protons. In particular, if Ohmic decay characterised by the conductivity, $\sigma_c$, is included, the induction equation resembles a diffusion equation. It encodes how the magnetic field lines diffuse through the fluid and reconnect, leading to the decay of magnetic energy as discussed in Section 3.3. If the Hall term is present but Ohmic decay is negligible, the induction equation reduces to

$$ \partial_t B^i = \epsilon^{ijk} \nabla_j \epsilon_{klm} \left( \epsilon^{lm}_{\nu} B^\nu \right). $$

(42)

In contrast to Equation (39), the electron velocity enters the magnetic evolution law. This implies that the relative motion between electrons and protons becomes important and the magnetic field is frozen into the electron fluid. The Hall term in Equation (33) itself is not dissipative but may act to redistribute magnetic energy from large scales to smaller ones, where it can decay ohmically. Many studies of the induction equation’s non-linear behaviour are based on results from hydrodynamic turbulence (Kolmogorov 1941), as it has several similarities with the vorticity equation of a viscous fluid (Goldreich & Reisenegger 1992). However, recent numerical simulations in the context of neutron stars have shown no evidence of strong cascading behaviour. Instead the Hall cascade appears to be saturated at long length-scales (Pons & Geppert 2010; Gourgouliatos & Cumming 2014; Wood & Hollerbach 2013).

### 3.3 Magnetic energy in standard MHD

The conservative and dissipative nature of the different pieces in Equation (33) is illustrated by considering the evolution of the magnetic energy. In order to compare the standard MHD plasma with the superconducting mixture later on, we calculate the magnetic energy associated with the work done by the Lorentz force. In its standard form, the Lorentz force density, given by

$$ F_L^i = \frac{1}{4\pi} \left( B_j \nabla^j B^i - \frac{1}{2} \nabla^i \left( B_k B^k \right) \right). $$

(43)

is composed of a tension and a pressure term. The work is obtained by calculating the product with the position vector, $r^i$, and integrating over the volume, $V$. Using the product rule and Equation (27), we arrive at

$$ W_L = \int r_i F_L^i \, dV = \frac{1}{4\pi} \int \nabla^i \left( r_j B^j B_i - \frac{1}{2} B^2 r_i \right) \, dV $$

$$ - \frac{1}{4\pi} \int \left( B^i B_j \nabla^j r_i - \frac{1}{2} B^2 \nabla^i r_i \right) \, dV. $$

(44)

The total gradient term can be rewritten as a surface integral using Gauss’ theorem. As no discontinuities are present at the boundary of the plasma region, we can push the integration radius to infinity. Provided that the magnetic induction vanishes at infinity, the surface contribution is zero. The integrand of the second term in Equation (44) simplifies to the well-known magnetic energy density

$$ W_L = \int \frac{B^2}{8\pi} \, dV = \int E_{\text{mag}} \, dV. $$

(45)

Changes in the magnetic energy are, thus, determined by

$$ \frac{\partial E_{\text{mag}}}{\partial t} = \frac{\partial}{\partial t} \left( \frac{B^2}{8\pi} \right) = B_i \frac{\partial B^i}{4\pi \partial t}. $$

(46)

Calculating the product of the induction equation with $B_i$ and using the product rule to rewrite the result, we find

$$ \frac{\partial E_{\text{mag}}}{\partial t} = \frac{1}{4\pi} \epsilon_{\nu} (\nabla_j B_{\nu}) \epsilon_{ijk} \nabla^k - \frac{e^2}{4\pi \sigma_e} \epsilon_{ijk} (\nabla^j B^k) $$

$$ - \frac{me}{4\pi \epsilon_{\nu}} \epsilon_{ijk} \epsilon_{lm} \nabla^l B_{\nu} B^k \nabla \epsilon_i. $$

(47)

The last term contains all contributions that can be written as a divergence. After integrating over the volume, it is possible to convert this part into a surface integral using Gauss’ theorem. Additionally, the third term has to be zero due to the properties of the Levi-Civita tensor. As expected,
the Hall term is conservative and does not contribute to the change in the magnetic energy density. Using Ampère’s law \(\mathcal{F}_M\) and the generalised Ohm’s law \(\mathcal{F}_e\), the remaining terms are simplified to
\[
\frac{\partial \mathcal{E}_{\text{mag}}}{\partial t} = \frac{1}{c} \epsilon_{ijk} v_j B_k - \frac{f^2}{\sigma_e} - \nabla_l \left[ \frac{c}{4\pi} \mathcal{S}_l - \frac{m_e}{e} \left( \mathcal{J}_l + \Phi \right) J_l \right],
\]
where \(\mathcal{S}^i = \epsilon_{ijk} E_j B_k\) is the Poynting vector. Equation (48) clearly shows that any resistive plasma is subject to the decay of magnetic energy due to Ohmic diffusion and the energy loss is proportional to \(j^2\). The inertial term vanishes if the protons are not able to move, which is, for example, the case in a standard metal, or the macroscopic current and the proton velocity are aligned.

4 MAGNETIC FIELD EVOLUTION IN SUPERCONDUCTING NEUTRON STARS

4.1 The coupling force: ‘standard’ resistivity

We now return to the question of magnetic field evolution in the superconducting outer neutron star core. In order to apply a formalism similar to the resistive MHD discussion, we need to determine the forces, \(F^i_e\), exerted on the electron component by the various fluid constituents and the vortices/fluxtubes. However, this is where things get complicated. Due to the multi-fluid nature of the superfluid/superconducting mixture, there are not simply two components coupled by a single resistive force. We could imagine a variety of ways for the components to interact with each other ranging from electron scattering (Sauls, Stein & Serend 1984; Alpar, Langer & Sauls 1984; Anderson, Sidery & Comer 2006) and vortex/fluxtube interactions (Ruderman, Zhu & Chen 1998; Jahan-Miri 2000; Link 2003) to shear or bulk viscosity (Anderson, Comer & Glampedakis 2005; Shternin & Yakovlev 2006; Manuel, Tauris & Telos 2013). Choosing a more pedagogical approach to our problem, we pick one specific mechanism, determine how it affects the electrons on mesoscopic scales and translate this into a macroscopic picture. While we won’t provide a complete picture of the magnetic field evolution in the core, this method provides more insight to how different mechanisms could play a role.

We keep in mind that the magnetic field is locked to the superconducting fluxtubes and their motion determines the evolution of the magnetic field. We, therefore, consider the scattering of electrons off the vortex/fluxtube magnetic fields as a source of mutual friction. This ‘standard’ resistive coupling in a superfluid/superconducting mixture, first discussed by Alpar, Langer & Sauls (1984), results in two forces acting on the electrons,
\[
F^i_e = F^i_{pe} + F^i_{in} \approx F^i_{pe}.
\]

We neglect the contribution from electrons scattering off the neutron vortices because \(N_p \gg N_e\). This implies that electron-fluxtube interactions are markedly more common and, thus, dominate the electron coupling. The macroscopic force, \(F^i_{pe}\), is obtained by multiplying the electron drag force, \(f^i_{pe}\), exerted on a single fluxtube, with the fluxtube density, \(N_p\),
\[
F^i_{pe} = N_p f^i_{pe} = N_p \rho_p \kappa R \left( u^i_p - u^i_0 \right).
\]
The dimensionless drag coefficient, \(\kappa\), contains all the information about the coupling on mesoscopic scales and \(u^i_p\) is the velocity of a single fluxtube.

In order to determine an evolution equation for the macroscopic magnetic field in superconducting matter, we have to eliminate any quantities from Equation (50) that are defined on mesoscopic length scales. Hence, the next step is to rewrite the fluxtube velocity, \(u^i_p\), in terms of the macroscopic fluid variables. This can be achieved by using the force balance for an individual fluxtube, an approach introduced by Hall & Vinen (1956) for the description of superfluid helium. We have
\[
\sum f^i = f^i_M + f^i_t + f^i_{\text{em}} = 0,
\]
where the fluxline inertia is neglected. Our force balance equation includes the electron drag force given above, the Magnus force, \(f^i_M\), the tension force, \(f^i_t\), and the electromagnetic Lorentz force, \(f^i_{\text{em}}\). The different forces have been calculated by Glampedakis, Andersson & Sannenológica (2011) and are given by
\[
f^i_M = -\rho_p \kappa \mathcal{E} \mathcal{J}_p \left( v^i_p - u^i_p \right),
\]
\[
f^i_t = \frac{H_{\text{Crit}}}{4\pi \rho_p} \mathcal{K} \mathcal{J}_p \nabla_j \mathcal{J}_p,
\]
where \(H_{\text{Crit}}\) is the lower critical field for superconductivity (Tilley & Tilley 1990), and
\[
f^i_{\text{em}} = \rho_p \kappa \mathcal{E} \mathcal{J}_p \mathcal{J}_p.
\]
Note at this point that we are interested in the linear analysis of one specific resistive mechanism. For this reason, our force balance (51) does not include a ‘pinning’ force, resulting from the magnetic short-range interaction between the two arrays (Ruderman, Zhu & Chen 1998; Jahan-Miri 2003; Glampedakis & Andersson 2011).

Calculating repeated cross products of the force balance equation with \(\mathcal{K}\), pointing along the local orientation of a fluxtube, it is possible to express the mesoscopic fluxtube velocity in terms of the averaged fluid velocities,
\[
u^i_p = u^i_p + \frac{1}{1 + R^2} \left( \mathcal{R} f^i_{\text{f}} + \mathcal{E} \mathcal{J}_p \mathcal{J}_p f^i_{\text{f}} \right),
\]
where
\[
f^i_{\text{f}} = \mathcal{E} \mathcal{J}_p \mathcal{J}_p + \frac{1}{\rho_p \kappa} \left( f^i_t + f^i_{\text{em}} \right).
\]
Combining the previous relations, we observe that the first term in Equation (55) and the electromagnetic force, \(f^i_{\text{em}}\), cancel each other. Then, the effective force, \(f^i_{\text{f}}\), is equivalent to the fluxtube tension,
\[
f^i_{\text{f}} = \frac{1}{\rho_p \kappa} f^i_{\text{f}} = \frac{H_{\text{Crit}}}{4\pi \rho_p} \mathcal{K} \mathcal{J}_p \nabla_j \mathcal{J}_p.
\]
Substituting Equations (55) and (57) back into Equation (56) finally gives for the macroscopic drag force,
\[
f^i_{\text{f}} = \frac{H_{\text{Crit}} \phi_{p} R}{4\pi (1 + R^2)} \left( \mathcal{R} \mathcal{K} \mathcal{J}_p \nabla_j \mathcal{J}_p + \mathcal{E} \mathcal{J}_p \mathcal{J}_p \nabla_j \mathcal{J}_p \right).
\]
For a straight fluxtube array, the tension force and, thus, the electron coupling would vanish.
\textbf{4.2 The superconducting induction equation}

Having determined the force, $F_i$, exerted on the electron component due to scattering off the fluxtube magnetic fields, we use Equation (22) for the macroscopic electric field to derive a generalised Ohm's law that is valid in the superfluid/superconducting mixture,

\[ E^i = \frac{1}{c} \varepsilon^{ijk} v^j B_k - \frac{m_e}{e} \nabla (\mu_e + \Phi) + \frac{H_{c3} \phi_0 N_p}{4 \pi \alpha p \rho_p} \]

\[ \times \frac{R}{1 + R^2} \left( R \hat{k}_p \nabla \phi_p \hat{k}_p + \varepsilon^{ijk} \hat{k}_p \nabla \phi_p \hat{k}_p \right). \]  

(59)

With Faraday's law \([25]\), we obtain a superconducting induction equation describing the evolution of the macroscopic magnetic field in the outer neutron star core,

\[ \partial_t B^i = \varepsilon^{ijk} \nabla \left[ \varepsilon_{\text{kin}} (v^l B^m) - \frac{H_{c3} \phi_0 N_p}{4 \pi \alpha p \rho_p} \right] \]

\[ \times \frac{R}{1 + R^2} \left( R \hat{k}_p \nabla \phi_p \hat{k}_p + \varepsilon^{ijk} \hat{k}_p \nabla \phi_p \hat{k}_p \right). \]  

(60)

Let us specify the lower critical field, $H_{c1}$, to simplify this expression further \([36]\). The field is related to the energy per unit length of the fluxtube, $E_p$, via

\[ H_{c1} = \frac{4 \pi E_p}{\phi_0}. \]  

(61)

The fluxtube energy, on the other hand, is determined by the characteristic lengthscales of the superconducting phase and given by

\[ E_p = \left( \frac{\phi_0}{4 \pi \lambda_s} \right)^2 \ln \left( \frac{\lambda_s}{\xi_p} \right). \]  

(62)

Here, $\xi_p$ denotes the proton coherence length and the effective London penetration depth was defined in Equation \([12]\). According to Tinkham \([2004]\), one can estimate $\ln (\lambda_s/\xi_p) \approx 2$, which leads to

\[ E_p \approx \frac{\rho_p \kappa^2}{2 \pi} \left( 1 - \frac{1}{\varepsilon_n} - \varepsilon_p \right) \approx \frac{\rho_p \kappa^2}{2 \pi} \frac{m_0}{m_p}. \]  

(63)

Combining the previous equations, we find

\[ \partial_t B^i = \varepsilon^{ijk} \nabla \left[ \varepsilon_{\text{kin}} (v^l B^m) - \frac{\kappa \phi_0 N_p}{2 \pi} \frac{m_0}{m_p} \right] \]

\[ \times \frac{R}{1 + R^2} \left( R \hat{k}_p \nabla \phi_p \hat{k}_p + \varepsilon^{ijk} \hat{k}_p \nabla \phi_p \hat{k}_p \right), \]  

(64)

which is the main result of our paper.

\textbf{4.3 A simplified set of equations and the field evolution timescales}

At this point, it seems natural to make several assumptions about the actual physics of the multi-fluid mixture inside a neutron star in order to find a simplified version of Equation \([64]\). As discussed previously, the main contribution to the macroscopic magnetic induction is given by the fluxtubes. In this case, we can neglect the weak London field and the superconducting Ampère law \([25]\) dictates that the protons and electrons are co-moving on large scales, i.e. $v_p^l \approx v_e^l$, and the macroscopic current vanishes. This also implies that the local direction of the fluxtube array is aligned with the direction of the magnetic field because

\[ B^l = B \hat{B}^l \approx N_p \phi_0 \hat{k}_p^l \]  

\[ \Rightarrow \hat{B}^l \approx \hat{k}_p^l. \]  

(65)

Using these simplifications to rewrite the force on the electron fluid, we obtain

\[ F^i_e \approx -\frac{H_{c3} B R}{4 \pi (1 + R^2)} \left( \nabla B^l \hat{B}^l + \varepsilon^{ijk} \hat{B}^j \nabla \hat{B}_k \right). \]  

(66)

The induction equation, on the other hand, reduces to

\[ \partial_t B^i \approx \varepsilon^{ijk} \nabla \left[ \varepsilon_{\text{kin}} (v_e^l B^m) - \frac{\kappa B}{2 \pi} \frac{m_0}{m_p} \right] \]

\[ \times \frac{R}{1 + R^2} \left( R \hat{k}_p \nabla \phi_p \hat{k}_p + \varepsilon^{ijk} \hat{k}_p \nabla \phi_p \hat{k}_p \right). \]  

(67)

We will compare this form of the superconducting induction equation with the standard MHD result in Equation \([53]\). As in the resistive MHD case, we can extract two timescales,

\[ \tau_{\text{diss}} = \frac{2 \pi L^2 (1 + R^2)}{\kappa R^2} \frac{m_0}{m_p}, \]  

(68)

\[ \tau_{\text{cons}} = \frac{R}{\kappa R^2} \frac{m_0}{m_p}, \]  

(69)

where $L$ is again the characteristic lengthscale over which the magnetic field changes. The naming convention of the two timescales might seem arbitrary at this point, but our choice will become clear later on.

We can estimate these two timescales provided the strength of the mutual friction is known. A method to calculate the dimensionless drag parameter, $R$, for the coupling of relativistic electrons and a single fluxtube is discussed in Alpar, Langer & Sauls \([1984]\) (see also Sauls, Stein & Serend \([1982]\), Andersson, Sidery & Comet \([2004]\)). The authors give the relaxation timescale, $\tau_{\text{rel}}$, for the 'resistive' interaction and include effects caused by the finite fluxtube size and the increase in moment of inertia due to the coupling of electrons and protons on much shorter timescales. The relaxation timescale is related to the drag coefficient via

\[ R = (\kappa N_p \tau_{\text{rel}})^{-1}, \]  

(70)

which leads to the following numerical estimate

\[ R \approx 1.9 \times 10^{-4} \left( \frac{m_0}{m_p} \right)^{1/2} \rho_{14}^{1/6} \left( \frac{x_{p}}{0.05} \right)^{1/6} \]  

(71)

This gives $R \ll 1$ and implies that the standard friction mechanism is rather weak. Adopting this limit, we can approximate for the neutron star core,

\[ \tau_{\text{diss}} \approx 3.1 \times 10^{11} L_6^2 \rho_{14}^{-1/6} \left( \frac{x_{p}}{0.05} \right)^{-1/6} \text{ yr} \]  

(72)

and

\[ \tau_{\text{cons}} \approx 1.3 \times 10^{15} L_6^2 \rho_{14}^{-2/6} \left( \frac{x_{p}}{0.05} \right)^{-2/6} \text{ yr}. \]  

(73)

We have used Equation \([13]\) to estimate the effective proton mass, i.e. the entrainment parameter.

\[ ^1 \text{Note that according to Jones \([2004]\), magnetic scattering off individual fluxtubes is suppressed for very large fluxtube densities. Instead electron scattering by a cluster of fluxtubes dominates the coupling, leading to a much smaller drag coefficient, $R$.} \]
4.4 Flux-freezing and magnetic energy

For conventional electron-fluidtube coupling, the timescales for the magnetic field evolution are rather long and the dynamics of the macroscopic induction are dominated by the inertial term in the induction equation. In the weak mutual friction limit, we are, thus, left with an equation that is equivalent to the ones discussed in Subsection 4.2. The magnetic field in the superconducting sample is frozen to proton fluid, which implies that the superconducting fluxtubes are locked to the proton plasma, i.e. $v^p_\parallel \approx u^p_\parallel$. Hence, electrons, protons and fluxtubes are comoving on large scales, which is different to the weakly resistive case of standard MHD, where the relative motion between the charged particles was important.

In order to determine whether the additional terms in Equation (78) are conservative or dissipative and which timescale dominates, we discuss the evolution of the superconducting magnetic energy. As before, we evaluate the energy associated with the work done by the magnetic field. However, in a superfluid/superconducting mixture the standard Lorentz force (43) has to be changed accordingly. For a non-rotating star in the absence of entrainment the total magnetic force is given by [Easson & Pethick 1977; Akgün & Wasserman 2008; Glampedakis, Andersson & Samuelsson 2011; Lander 2014]

$$F_{\text{mag}} = \frac{1}{4\pi} \left[ B_i \nabla^j H_{i1} - \nabla^j \left( \rho_p B \frac{\partial H_{i1}}{\partial p} \right) \right], \quad (74)$$

where $H_{i1} = H_i \hat{B}^i$. This expression also contains a tension and a pressure term but both scale with $B^2$ instead of $B^4$. The work associated with this force is given by

$$W_{\text{mag}} = \frac{1}{4\pi} \int \nabla^j \left( \tau_j H_{i1} B_i - \rho_p B \frac{\partial H_{i1}}{\partial p} \tau_i \right) \, dV - \frac{1}{4\pi} \int \left( H_{i1} B_j \nabla^i \tau_i - \rho_p B \frac{\partial H_{i1}}{\partial p} \nabla^i \tau_i \right) \, dV, \quad (75)$$

where we have used the product rule and Equation (24).

Similar to the standard MHD case, the first term can be rewritten using Gauss’ theorem. However, in the superconducting outer core, this contribution does not simply vanish because discontinuities are likely to be present at the fluids’ boundaries. The dynamics that might arise due the presence of a current sheet at the crust-core interface or the type-II to type-I transition region in the neutrons star’s inner core are only poorly understood and significantly complicate the problem. Incorporating these interfaces would require a much more detailed understanding of the microphysics involved. In the following, we, therefore, omit a discussion of the surface terms and focus on the much simpler problem of magnetic field evolution in the bulk fluid.

Taking into account that $H_{i1}$ is a function linear in $\rho_p$, the second integral in Equation (75) reduces to

$$W_{\text{mag, bulk}} = \int \frac{H_{i1} B_i}{2\pi} \, dV = \int \mathcal{E}_{\text{mag, SC}} \, dV. \quad (76)$$

Taking the time derivative of the magnetic energy density gives two contributions

$$\frac{\partial \mathcal{E}_{\text{mag, SC}}}{\partial t} = \frac{B}{2\pi} \frac{\partial H_{i1}}{\partial t} + \frac{H_{i1}}{2\pi} \frac{\partial B^i}{\partial t}. \quad (77)$$

Comparison with the corresponding expression of standard MHD given in Equation (10) shows that the superconducting nature of the mixture gives rise to a new contribution for the change in energy density. In contrast to resistive MHD, the evolution of matter and the magnetic induction are no longer decoupled in the condensate. Equation (77) demonstrates that modifying the properties of the superconductor, such as the lower critical field, $H_{c1}$, alters the magnetic energy. This implies that an evolving matter configuration can be closely linked to a changing magnetic field.

The second term in Equation (77) is similar to the result for normal conducting matter. Calculating the product of the induction equation (67) with $\hat{B}_i$ and using the product rule to simplify, we find

$$\frac{\partial B^i}{\partial t} = \epsilon^{ijk} (\nabla_j B_k - \nabla_k B_j) \left( \frac{\epsilon_{ijk} \epsilon^{ilm} B^k}{2\pi(1 + R^2)} \right) \cdot \hat{B}_i \nabla_i \hat{B}_i - \frac{\kappa B R}{2\pi(1 + R^2)} \frac{m}{m_p} \epsilon_{ijk} \epsilon^{ilm} B^k \nabla_i \hat{B}_i. \quad (78)$$

As before, $\Sigma^i$ denotes the divergence terms. This equation bears some resemblance with the result (77) found in standard MHD and we would equivalently expect to obtain a conservative and a dissipative contribution. In order to determine which of the terms are nonzero or zero, we rewrite the tension using the following identity

$$\hat{B}_i \nabla_i \hat{B}_i = \epsilon_{ijk} \epsilon^{ilm} (\nabla_j \hat{B}_m) \hat{B}^k. \quad (79)$$

The second term in Equation (78) is, thus, proportional to

$$\epsilon^{ijk} (\nabla_j \hat{B}_k) \hat{B}_i \nabla_i \hat{B}_i = \epsilon^{ijk} (\nabla_j \hat{B}_k) \epsilon_{ilm} (\nabla_j \hat{B}_m) \hat{B}^k. \quad (80)$$

Analogous to the Hall term of standard resistive MHD, this vanishes due to the properties of the antisymmetric Levi-Civita tensor. Thus, the second term in the superconducting induction equation (78) is conservative and does not modify the total magnetic energy of the superconducting mixture. The last term in Equation (78), on the other hand, is proportional to

$$\epsilon^{ijk} (\nabla_j \hat{B}_k) \epsilon_{ilm} \hat{B}^l \nabla_i \hat{B}_m = C^{ijk} \epsilon_{ilm} \hat{J}_i \hat{B}_m, \quad (81)$$

where we defined the vector

$$C^{ijk} \equiv \epsilon^{ikl} \nabla_l \hat{B}_k. \quad (82)$$

Rewriting the remaining two Levi-Civita tensors in terms of Kroncker deltas, $\delta_{ij}$, gives the projection

$$C^{ijk} \epsilon_{ilm} \hat{J}_i \hat{B}_m = C^{ijk} \hat{J}_i \hat{B}_j. \quad (83)$$

Decomposing the vector $C^{ijk}$ into a component parallel to $\hat{B}_i$ and one perpendicular to the magnetic field direction, i.e. $C^{ijk} = C_{\parallel i} \hat{B}_i + C_{\perp i}$, we see that Equation (83) only depends on the component of $C^{ijk}$ that is perpendicular to $\hat{B}_i$,

$$C_{\parallel i} \hat{J}_i - \left( C^{ijk} \hat{J}_i \hat{B}_j \right) (\hat{J}_i \hat{B}_j) = C_{\parallel i}. \quad (84)$$

Similar to the Ohmic term in standard MHD, we also retain a dissipative contribution to the total magnetic energy in the case of superconducting MHD. It is given by

$$\frac{\partial \mathcal{E}_{\text{mag, SC}}}{\partial t} = \frac{B}{2\pi} \frac{\partial H_{i1}}{\partial t} + \frac{H_{i1}}{2\pi} \frac{\partial B^i}{\partial t} - \frac{H_{i1} \kappa B R}{4\pi^2(1 + R^2)} \frac{m}{m_p} (\nabla^2 - \frac{\kappa B R}{2\pi(1 + R^2)} \frac{m}{m_p}) \nabla^i \nabla_i \hat{B}_i \nabla_i \nabla_i. \quad (85)$$
Having calculated the change in the magnetic energy density, we can associate the timescale $\tau_{\text{diss}}$, given in Equation (72), with a dissipative mechanism. Comparing the numerical estimate to the Ohmic decay timescale $\tau_{\text{Ohm}}$ (67), we observe that the resistive coupling in a superfluid/superconducting mixture acts on a timescale, which is two orders of magnitude smaller than the standard MHD diffusion,

$$\frac{\tau_{\text{diss}}}{\tau_{\text{Ohm}}} \approx 1.3 \times 10^{-2} T_8^2 \rho_{14}^{-5/3} \left( \frac{x_p}{0.05} \right)^{-5/3}. \quad (86)$$

On the other hand, the timescale $\tau_{\text{Hall}}$ for the Hall evolution in a normal conducting plasma can be compared to $\tau_{\text{cons}}$ in Equation (73). In contrast to the standard MHD case, the conservative timescale emerging from the superconducting induction equation is several orders of magnitude larger than the Hall timescale,

$$\frac{\tau_{\text{cons}}}{\tau_{\text{Hall}}} \approx 6.8 \times 10^4 B_{12} \rho_{14}^{-4/3} \left( \frac{x_p}{0.05} \right)^{-4/3}. \quad (87)$$

We also note that due to the dependence on the dimensionless drag coefficient, $R$, the dissipative term in the superconducting induction equation governs the magnetic field evolution, whereas in standard MHD the conservative Hall term acts on shorter timescales. In the latter case, the order of the two timescales is necessary for any cascading behaviour to take place; the Hall term drives the magnetic field to shorter lengthscales, where it can decay ohmically. However, if diffusion is dominating the evolution, the redistribution of magnetic energy will happen on much longer timescale not causing a cascade. Hence, despite the close similarities between the conservative terms in Equation (67) and standard MHD, we conjecture that the analysis of the Hall cascade by Goldreich & Reisenegger (1992) is not transferable to the superconducting case.

## 5 DISCUSSION

Strong magnetic fields are a key ingredient for many phenomena observed in neutron stars. Understanding the fields’ long-term evolution might give insight into the ‘metamorphosis’ between the different neutron star classes, the changing fields of standard radio pulsars or the high activity of magnetars, which would require timescales of order $10^7$ yr and $10^9$ yr respectively, for the evolution to take place; the Hall term drives the magnetic field to shorter lengthscales, where it can decay ohmically. However, if diffusion is dominating the evolution, the redistribution of magnetic energy will happen on much longer timescale not causing a cascade. Hence, despite the close similarities between the conservative terms in Equation (67) and standard MHD, we conjecture that the analysis of the Hall cascade by Goldreich & Reisenegger (1992) is not transferable to the superconducting case.

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Our results additionally suggest that the highly conducting neutron star core might affect the crustal field and slow down its evolution. Making a precise statement at this point is, however, not possible due to the poorly known physics at the crust-core boundary. This transition is crucial in understanding how changes of the core magnetic field are translated to the crust. The analysis presented in this paper does, therefore, not reconcile the discrepancy between short crustal decay timescales (Pons, Miralles & Geppert 2003)
and the much longer core evolution. In order to significantly reduce the latter different dissipative mechanisms have to be invoked. The typical candidate for strong coupling is vortex-fluxtube ‘pinning’ due to the short-range magnetic interaction between the two arrays. While we did not address pinning specifically, discussing the vortex-fluxtube interaction would be the natural continuation of this paper as our prescription can deal with any coupling mechanism. Based on a mesoscopic description of the pinning process, one would have to determine how the coupling affects the electron fluid and substitute the respective force, $F_e$, into the generalised Ohm’s law. Determining the superconducting induction equation that would result from the pinning interaction will be left for future work.

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