Eruptions of coronal mass ejections (CMEs) from the Sun are usually associated with a number of signatures that can be identified in solar disc imagery. However, there are cases in which a CME that is well observed in coronagraph data is missing a clear low-coronal counterpart. These events have received attention during recent years, mainly as a result of the increased availability of multi-point observations, and are now known as “stealth CMEs.” In this work, we analyze examples of stealth CMEs featuring various levels of ambiguity. All the selected case studies produced a large-scale CME detected by coronagraphs and were observed from at least one secondary viewpoint, enabling a priori knowledge of their approximate source region. To each event, we apply several image processing and geometric techniques with the aim to evaluate whether such methods can provide additional information compared to the study of “normal” intensity images. We are able to identify at least weak eruptive signatures for all events upon careful investigation of remote-sensing data, noting that differently processed images may be needed to properly interpret and analyze elusive observations. We also find that the effectiveness of geometric techniques strongly depends on the CME propagation direction with respect to the observers and the relative spacecraft separation. Being able to observe and therefore forecast stealth CMEs is of great importance in the context of space weather, since such events are occasionally the solar counterparts of so-called “problem geomagnetic storms.”

Keywords: sun, coronal mass ejection, stealth coronal mass ejection, solar corona, space weather, remote-sensing analysis
1 INTRODUCTION

Coronal mass ejections (CMEs) are powerful solar eruptions containing large amounts of plasma and magnetic field that are regularly expelled from the Sun into the heliosphere. They were first identified in white light in the early 1970s (Tousey, 1973; Gosling et al., 1974) in images from the 7th Orbiting Solar Observatory (OSO-7) coronagraph (Koomen et al., 1975) and the coronagraph onboard the Skylab space station that formed part of the Apollo Telescope Mount (ATM; Tousey, 1977) suite of solar instruments. Around the same time, the low-corporal counterparts of white-light CMEs were being observed through multi-wavelength solar disc imagery, e.g., in extreme ultra-violet (EUV), soft X-rays, and Ha, using data from OSO-7, Skylab, and ground-based observatories (e.g., Demastus et al., 1973; Munro et al., 1979). The typical low-corporal signatures of CMEs were reviewed by Hudson and Cliver. (2001). These include the appearance of coronal dimmings (e.g., Thompson et al., 2000; Kahler and Hudson, 2001), flare ribbons (e.g., Rust and Bar, 1973; Martin, 1979), post-eruption arcades (e.g., Rust and Webb, 1977; Tripathi et al., 2004), and EUV waves (e.g., Thompson et al., 1998; Zhukov and Auchère, 2004), as well as the disappearance of filament material (e.g., Rust et al., 1975; Seeley et al., 1975) and X-ray sigmoid (e.g., Rust and Kumar, 1996; Green et al., 2007). A major step forward in CME research was achieved in the early 1980s, when Howard et al. (1982) reported observations of the first Earth-directed CME (in that case, a halo CME) in white-light images from the Solwind coronagraph (Michels et al., 1980) and linked this “coronal transient” with a disappearing filament on the solar disc and with a shock wave detected near Earth about 3 days later. The following decade saw the launch of two missions that have made a major impact on the field of solar physics, namely Yohkoh (also known as Solar-A; Ogawara et al., 1991) and the Solar and Heliospheric Observatory (SOHO; Domingo et al., 1995). Yohkoh carried several solar imagers, including the Soft X-ray Telescope (SXT; Tsuneta et al., 1991), while the SOHO payload includes remote-sensing and in-situ instruments, several of which are still operational, including the venerable Large Angle Spectroscopic Coronagraph (LASCO; Brueckner et al., 1995). By then, the whole Sun-to-Earth picture of CMEs was seemingly quite clear: The presence of low-corporal signatures preceding a halo CME observed by LASCO would signify that the CME is Earth-directed, whereas the lack of visible activity on the solar disc would indicate that the CME was associated with a far-sided eruption.

However, it was not long before this picture was shown to not always hold true. Studies of CMEs detected in situ near Earth noted that a large number of such events lacked clear solar associations (e.g., Cane and Richardson, 2003; Richardson and Cane, 2010). Specifically, Schwenn et al. (2005), reported that 20% of interplanetary CMEs could not be linked to a front-sided (partial or full) halo CME source, and Zhang et al. (2007) reported that 11% of CME-driven storms with minimum Dst ≤ −100 nT could not be linked to eruptive signatures in the low corona. A turning point came with the launch of the Solar Terrestrial Relations Observatory (STEREO; Kaiser et al., 2008) mission in 2006. The STEREO mission consisted of twin spacecraft, one advancing ahead of Earth in its orbit (STEREO-A) and one trailing behind (STEREO-B), thus enabling observations of the Sun from multiple viewpoints. Using data from the Sun Earth Connection Coronagraph and Heliospheric Investigation (SECCHI; Howard et al., 2008) suite onboard both STEREO spacecraft when they were separated by 53°, Robbrecht et al. (2009) reported that a CME erupted “leaving no trace behind on the solar disc.” Although the authors were able to identify a slow, streamer-blowout CME erupting off the limb in STEREO-A imagery, there were no corresponding on-disc signatures in STEREO-B data. The Robbrecht et al. (2009) event represents the first direct observation of what is now known in the solar physics community as a “stealth CME.” In the following years, numerous additional stealth events have been reported (Ma et al., 2010; D’Huys et al., 2014; Kilpua et al., 2014).

According to these studies, CMEs that lack distinct low-corporal signatures tend to occur close to solar minimum, are generally slow and narrow, and often form at higher altitudes in the solar atmosphere. One major question that started to be raised is whether the eruption mechanism for stealth CMEs is fundamentally different from that of “ordinary” CMEs, or if stealth CMEs simply represent the lowest end of the full energy spectrum of solar eruptions (Howard and Harrison, 2013; Lynch et al., 2016). Additionally, it was soon clear that stealth CMEs can be detected in situ, starting with the Robbrecht et al. (2009) event that was observed at STEREO-B featuring a classic flux-rope structure (Möstl et al., 2009; Lynch et al., 2010; Nieves-Chinchilla et al., 2011). It also became evident that the interplanetary counterparts of stealth CMEs are able to cause significant space weather disturbances if they encounter Earth (Nitta and Mulligan, 2017). CME-driven storms that cannot be linked to a clear source on the Sun or to appreciable solar activity are particularly challenging to forecast and are known as “problem geomagnetic storms” (e.g., McAllister et al., 1996).

During the last decade, routine observations of the solar disc have advanced considerably due to the high temporal and spatial resolution of data from the Solar Dynamics Observatory (SDO; Pesnell et al., 2012), launched in 2010. Nevertheless, despite the improvement of EUV observations with respect to previous instrumentation, stealth CMEs continue to be reported (e.g., Nitta and Mulligan, 2017). It has been suggested that apparently stealth CMEs result from observational limitations such as instrument sensitivity and bandwidth issues, even in the SDO era (Howard and Harrison, 2013), and that advanced image processing techniques may reveal hard-to-observe signatures in both solar disc and coronagraph imagery (Alzate and Morgan, 2017; O’Kane et al., 2019). Additionally, some studies have applied geometric triangulation and reconstruction techniques.

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1Note that a halo CME is not necessarily Earth-directed, and a CME does not need to be a halo in order to impact Earth.

2CMEs have been called by various names since their discovery, ranging from “coronal transient phenomena” (MacQueen et al., 1974) to “mass ejections from the Sun” (Gosling et al., 1974). The term “coronal mass ejection” was first introduced by Gosling (1975), but came into common usage only in the early 1980s.
to data from complementary viewpoints in order to trace stealth CMEs back to an approximate source region on the disc (Pevtsov et al., 2012; O’Kane et al., 2019; Talpeanu et al., 2020). These methods, however, have not been tested on a large number of events and hence it is not known whether they are suitable to all circumstances or whether they can be applied only to a limited number of cases. To complicate things further, there is currently no formal definition describing what a stealth CME is or defining the “observational limit” below which a CME can be considered to be stealthy.

In this paper, we contemplate the following question: Since stealth CMEs can present diverse characteristics, is it possible that there exists a class of “extremely stealth” CMEs that cannot be revealed even with the aid of state-of-the-art techniques? In order to address this issue, this work aims to investigate the efficacy of various techniques applied to remote-sensing data in revealing the signatures of CMEs that are elusive on the solar disc. We test such techniques on four well-studied stealth CMEs for which the “true” source is more or less known because of the availability of remote-sensing imagery from additional viewpoints. This will ensure that any solar activity that is observed away from the expected source region will not be mistakenly interpreted as a signature of the stealth CME under analysis. This manuscript is organized as follows. In Section 2, we present and describe the imaging and geometric techniques that we employ in this study to analyze stealth CMEs. In Section 3, we apply these techniques to four case studies and compare them with information that can be retrieved from plain inspection of intensity images only. Finally, in Section 4 we discuss our results and present our conclusions.

2 TECHNIQUES EMPLOYED

This section summarizes the remote-sensing techniques that are used throughout this work to analyze the four elusive CMEs under study. Imaging techniques are described in Section 2.1, while geometric techniques are presented in Section 2.2.

2.1 Imaging Techniques

2.1.1 Image Differencing

The image differencing technique simply consists of subtracting from an image a preceding one, so that changes in total intensity over time appear as patches that are either dark (denoting an intensity decrease) or bright (denoting an intensity increase). This method has been long used in solar physics applications for both on-disc and coronagraph observations (e.g., Burlaga et al., 1982; Hudson et al., 1992). The commonly used nomenclature for the technique is that subtracting a pre-event image yields a “base difference” image, while subtracting successive images yields a “running difference” image. Base-difference images are often used to highlight transient phenomena that develop over larger time scales, such as coronal dimmings (e.g., Attrill and Wills-Davey, 2010), while running-difference images are often used to highlight short-term transient features such as EUV waves (e.g., Attrill et al., 2007). Since stealth CMEs tend to be slow, i.e. they erupt and accelerate over the course of several hours, their evolution is not expected to be captured in running-difference images, hence we focus in this work on using image differencing over longer time scales. In particular, Nitta and Mulligan (2017) noted that in the case of stealth CMEs, difference images with “long enough” temporal separations (of the order of ∼10 h) should often be used in order to reveal weak low-coronal signatures, including dimmings and post-eruption arcades. In this work, in order to minimize the appearance of artifacts at the solar limb due to rotation (which are still present even after accounting for differential rotation), we calculate the percentage variation between each couple of images and use a fixed temporal separation of Δt = 12 h.

2.1.2 Wavelet Packets Equalization

The Wavelet Packets Equalization (WPE; Stenborg and Cobelli, 2003; Stenborg et al., 2008) technique is a multi-resolution image processing method that can be applied to enhance features based on their multi-scale nature. In the WPE technique, an image is first decomposed over both dimensions using spatially localized functions known as wavelets. We have implemented the Stenborg and Cobelli (2003) procedure using a 2D à trous wavelet transform (e.g., Shensa, 1992), where the scaling function is a B3-spline corresponding to a 5×5 smoothing kernel. This produces a set of wavelet planes at different spatial scales (called wavelet scales) derived from the initial image, together with the remaining “continuum” background image representing the lowest frequencies and largest scales. A wavelet-processed image is constructed by summing over all the wavelet planes and the continuum background with user-defined weights to emphasize the desired scale sizes. In general, the weighting strategy must be fine-tuned to both the particular image (e.g., different EUV wavelengths or different coronagraphs) and to the spatial scales of interest. In the case of stealth CMEs, the WPE technique has been used to enhance off-limb structures from secondary viewpoints (e.g., Vourlidas et al., 2011; Nieves-Chinchilla et al., 2013; Liewer et al., 2021), and had been explored to search for elusive on-disc signatures by Robbrecht et al. (2009).

2.1.3 Multi-Scale Gaussian Normalization

The Multi-scale Gaussian Normalization (MGN; Morgan and Druckmuller, 2014) technique, similarly to the WPE method described in Section 2.1.2, is based on a multi-scale normalization algorithm. In the MGN technique, a set of 2D Gaussian kernels of different scale lengths are used to locally normalize an image using a set of local mean and standard deviation values. A weighted combination of the normalized components is then used to obtain a weighted mean locally normalized image, which is finally superposed to the corresponding global gamma-transformed image. This results in an enhancement of the local intensity fluctuations within the images. The MGN image processing tool has been applied to EUV images to identify the low-coronal signatures associated with stealth events in both on-disc and off-limb observations (Alzate and Morgan, 2017; O’Kane et al., 2019, 2021b).
2.2 Geometric Techniques

2.2.1 Latitude Projection

Since all CMEs investigated in this study have been observed off-limb from at least one additional perspective, a simple approach to adopt when triangulation is not possible (i.e., when only one “non-stealthy” viewpoint is available) is to project the approximate latitude from which the CME originated onto the “stealthy” field of view. Considering a “classic” three-part CME structure in coronagraph imagery (Illing and Hundhausen, 1985), we trace back to the solar disk the approximate latitude of the central, bright core that is observed off-limb. We note that not all CMEs feature a three-part structure (e.g., Vourlidas et al., 2013), but stealth CMEs often belong to the streamer blowout category, in which flux rope signatures tend to occur at a higher rate than in the general CME population (Vourlidas and Webb, 2018). The projected latitude of the source region from the off-limb viewpoint naturally focuses the search for any possible faint or ambiguous on-disc signature to a more localized area. This enhances the potential to find any low-coronal signatures or dynamics that, by themselves, would not have necessarily been interpreted as being eruption-related.

2.2.2 Tie-Point Technique

The Tie-point (TP) triangulation technique was formulated by Inhester. (2006) and first employed by Thompson. (2009) to study a Sun-grazing comet. The principle on which the TP technique is based is that two separate observers and the point of interest in space (to be triangulated) form a plane called “epipolar plane,” which is reduced to a line (“epipolar line”) in image projections. A point identified in an image from the first observer must lie on the same epipolar line in the corresponding image from the second observer. Larger-scale features can be tracked by finding correspondences between different pixels along epipolar line pairs in images from both spacecraft. The 3D reconstruction or triangulation is then achieved by finding the intersection of the two lines of sight (for each pixel of interest) along the corresponding epipolar plane, which is unambiguously defined. In solar physics applications, the TP method has been used to evaluate the 3D morphology of erupting filaments (e.g., Bemporad et al., 2011; Thompson et al., 2012; Panasenco et al., 2013; Palmerio et al., 2021) and the evolution of CME fronts or cores in coronagraph data (e.g., Mierla et al., 2008, 2009; Srivastava et al., 2009; Liewer et al., 2011).

2.2.3 Graduated Cylindrical Shell

The Graduated Cylindrical Shell (GCS; Thernisien et al., 2006, Thernisien et al., 2009; Thernisien, 2011) model is a reconstruction technique usually applied to white-light coronagraph images. In the GCS model, a wireframe describing the geometry of flux ropes is used to fit CMEs from one or more simultaneous viewpoints. Within a single reconstruction, six free parameters (latitude, longitude, axis tilt, apex height, half-angle, and aspect ratio) can be adjusted until they best match the CME morphology observed in one or more images. The geometry of the model itself is often referred to as a “hollow croissant” and consists of a half-torus frontal part with two conical legs connected to the Sun. The resulting shape, reminiscent of a croissant, is “hollow” in the sense that the electron density is placed uniquely on the shell of the model. Thus, fits performed with the GCS model can provide information on the morphology of CMEs, but not on their magnetic field structure. The GCS technique is widely used in solar physics and space weather applications to determine geometric and kinematic parameters of CMEs and their shocks through the corona (e.g., Mierla et al., 2010; Shi et al., 2015; Schmidt et al., 2016), also in the case of stealth CMEs (e.g., Lynch et al., 2010; He et al., 2018). More recently, O’Kane et al. (2019), and Freiherr von Forstner et al. (2021) used the inferred propagation latitude and longitude from GCS reconstructions to obtain an approximate location for the source region of the stealth CMEs they analyzed. The full list of GCS-reconstructed parameters for all CMEs studied in this work can be found in Supplementary Table S1.

3 ANALYSIS OF SAMPLE STEALTH EVENTS

We present in this section the remote-sensing analysis of four CMEs with elusive on-disc signatures: 2008 June 1, 2011 March 3, 2012 February 4, and 2016 October 8. These events were selected based on two main factors. First of all, they were all observed as classic three-part CMEs including a flux rope by at least one spacecraft, i.e., they do not belong to the so-called “jet” and/or “blob” categories. Furthermore, each event was observed from at least one additional viewpoint, enabling estimation of its approximate source region on the solar disc. Such observations are provided for each case study as supplementary videos in which EUV data have been enhanced with a radial filter, in order to bring out off-limb emission. The reader is invited to initially rapidly move the video player slider back and forth, so that the motion catches the eye. As stealth CMEs are usually slower than average, it may be difficult to identify erupting structures that evolve over extremely long time scales when played at the speeds shown in the videos (i.e., 2–4 h per second). Additionally, kinematic (height–time) plots for each event based on observations from these additional viewpoints are provided in Supplementary Figure S1.

3.1 Event 1: 2008 June 1

The first CME that we focus on in this study (Event 1) erupted on 2008 June 1 and was a stealth event as seen from STEREO-B. This CME was first reported by Robbrecht et al. (2009) and its eruption was later modeled by Lynch et al. (2016). As mentioned in the Introduction, this event marked the first direct observation of a CME that left “no trace behind” in EUV imagery from one viewpoint, hence we treat it here as a “stealth CME prototype.” At the time of this event, STEREO-A was located 28° west of Earth and STEREO-B was positioned 25° east of Earth. The pre-eruptive configuration and eruption process were well observed by STEREO-A, as shown in Extreme UltraViolet Imager (EUVI) and COR1 coronagraph data shown in Supplementary Video S1. From the STEREO-A perspective, a flux rope structure (observed as a characteristic cavity in off-limb imagery; Gibson et al., 2006) can be seen to lie at relatively high
altitudes below a coronal streamer above the southeastern limb. The eruption itself took place over large time scales (\sim 1.5 days), during which the flux rope slowly lifted off (starting around 15:00 UT on May 31), causing the streamer to swell and resulting in a classic streamer-blowout CME that reached the COR2-A coronagraph field of view around 22:00 UT on June 1. We remark that corresponding images from the Extreme-ultraviolet Imaging Telescope (EIT; Delaboudinière et al., 1995) onboard SOHO are not available because of a data gap.

EUVI images from STEREO-B for the eruption period processed with different techniques are shown in Figure 1 and Supplementary Video S2. It is clear that the succession of images in Figure 1 does not show any strong indication that an eruption has occurred. Nevertheless, it is possible to note two extremely faint dimmings (indicated with arrows) developing in the southern hemisphere starting around 15:00 UT on June 1 (see also Supplementary Video S2). These dimmings are not straightforward to identify even in

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**FIGURE 1** | Imaging techniques applied to the 2008 June 1 CME (Event 1). STEREO/SECCHI/EUVI-B 195Å images are shown at four different times and processed with four different methods. (A–D) Intensity images. (E–H) Difference images with fixed $\Delta t = 12$ h. (I–L) WPE-processed images. (M–P) MGN-processed images. Two faint dimmings are indicated with arrows (see text for details).
difference data, possibly because they are rather weak and hence appear “camouflaged” by other intensity fluctuations on the solar disc. We also note that these signatures appear equally visible in images produced using the other three methods (i.e., intensity, WPE, and MGN). The dimmings seem to be spatially consistent with the approximate CME source region deduced from STEREO-A imagery (see Supplementary Video S1), but because they are so faint it is not possible to draw strong conclusions as to their association with the 2008 June 1 CME.

Results from the application of geometric techniques to Event 1 are shown in Figure 2. In the top row, the approximate latitude of the footpoints of the flux rope structure seen in off-limb imagery from STEREO-A (marked with an arrow in Figure 2A, see also Supplementary Video S1) is projected onto the solar disc from all three available viewpoints. The flux rope lifted off from ≈S27°, roughly consistently with the location of the faint dimmings shown in Figure 1, which extend between ≈S20° and ≈S50°. We also perform a GCS reconstruction of the large-scale CME in the corona, shown in the middle row of

![Figure 2](https://example.com/figure2.png)

**Figure 2** Geometric techniques applied to the 2008 June 1 CME (Event 1). (A–C) Latitude (thick red line) of the CME core (indicated with an arrow) projected onto the solar disc as seen by STEREO-A, SOHO, and STEREO-B. (D–F) GCS reconstruction applied to the white-light structure seen in STEREO-A, SOHO, and STEREO-B imagery. (G–I) The GCS-reconstructed CME displayed together with the “source latitude” in a 3D representation and shown from the three viewpoints of STEREO-A, Earth, and STEREO-B.
Figure 2. We remark that, given that the eruption is a halo from STEREO-B and rather close to the central meridian as seen from Earth, the first available time for a meaningful fitting is ~3.5 h after the first appearance of the CME in the COR2-A field of view. According to GCS results, the CME apex is located at S04°E29° as seen from Earth, which converts into a longitude of E04° as seen from STEREO-B. While the value for latitude is significantly different, the longitude is quite consistent with that of the faint dimmings indicated in the last column of Figure 1, which cover a longitudinal span of E25°–W25° in the STEREO-B reference frame (note that the images in the middle row of Figure 2 and those in the last column of Figure 1 are taken at the same time). The “source latitude” and the reconstructed GCS wireframe are shown together in a 3D representation in the bottom row of Figure 2. It is clear that the CME deflected significantly toward the solar equatorial plane during its early evolution, which is also visible from Supplementary Video S1 and is consistent with the tendency of CMEs to align themselves with the heliospheric current sheet during solar minimum (e.g., Yurchyshyn et al., 2009; Isavnin et al., 2014). Hence, we conclude that searching for the source of the eruption based on coronagraph images and GCS reconstructions alone would have likely resulted in a somewhat misleading region.

3.2 Event 2: 2011 March 3

The second CME that we analyze in this work (Event 2) erupted on 2011 March 3 and was a stealth event as seen from Earth. This case study was previously analyzed by Pevtsov et al. (2012), Nitta and Mulligan (2017), O’Kane et al. (2019), and O’Kane et al. (2021b), who all placed the CME source region in the vicinity of active region AR 11165, located close to the central meridian from Earth’s perspective. Hence, we investigate this event as a possible case of a more localized, active region stealth CME. At the time of this eruption, STEREO-A was located 87° west of Earth and STEREO-B was positioned 95° east of Earth, meaning that the two spacecraft had a nearly quadrature view of the event from opposite sides. Such observations are shown in Supplementary Video S3, which presents simultaneous EUVI and COR1 data from the twin STEREOs. In the video, a large bubble-shaped set of loops can be initially seen to lie off the limb above AR 11165, before slowly inflating (starting around 18:00 UT on March 2) and erupting as a flux rope CME that reached the COR2 field of view around 04:00 UT on March 3. From the STEREO-A perspective, high-altitude post-eruption arcades could be observed after the CME lifted off as AR 11165 rotated into view, forming just above the longer-lived active region loops. It is clear from these observations alone that this CME indeed originated from AR 11165, albeit from higher altitudes than usual and thus away from stronger active region fields. This may be a contributing factor to the stealthiness of the event in on-disc imagery, as suggested by O’Kane et al. (2019).

Images from the Atmospheric Imaging Assembly (AIA; Lemen et al., 2012) instrument onboard SDO corresponding to the eruption period are shown in Figure 3 and Supplementary Video S4. While the intensity, MGN, and WPE images do not show strong eruptive signatures, the difference images in the second row display clearer signs of activity on the solar disc. First of all, an extended pair of dimmings and flare loops at the southern periphery of a large coronal hole in the western hemisphere can be observed in Figure 3E (indicated with arrows). These are found to be associated with a filament eruption that occurred on March 1, which possibly destabilized the nearby active region fields and thus triggered the later stealth CME. The successive panels are characterized by a series of dimmings (starting around 22:00 UT on March 2 and marked in panels (F) and (G)) and a strong brightening (starting around 01:00 UT on March 3 and marked in panel (H)) around AR 11165 (indicated with a circle in the first column of Figure 3). It can be seen that initially, a pair of dimmings develops north–south of the active region and later a third, more diffuse dimming appears to the east of the fading southern one. Corresponding images obtained with other techniques, on the other hand, show more elusive signatures. A faint pair of dimmings north and south of AR 11165 can be seen in Supplementary Video S4 (the northern dimming is marked in panels (C), (K), and (O) of Figure 3), together with the appearance of a set of loops that seem to correspond to the post-eruption arcade seen by STEREO-A (marked in panels (D), (L), and (P) of Figure 3). We emphasize that these signatures are rather weak, and thus without prior knowledge of an eruption having occurred they would have been easily overlooked. Furthermore, we note that although the arcade is well observed in all non-differenced data (i.e., intensity, WPE, and MGN), its fine structure is more easily revealed in images processed with advanced techniques.

Results from the application of geometric techniques to Event 2 are shown in Figure 4. Since the pre-eruptive structure was well observed by both STEREO spacecraft, we analyze it using the TP technique. The triangulated balloon-shaped feature is overlaid onto EUVI images in panels (A) and (C). However, despite the favourable viewing perspective of nearly quadrature with Earth from both observers, it is not possible to obtain a meaningful triangulation of the loop onto the solar disc imaged by SDO. This is because the uncertainty associated with the TP technique depends on the angle between the observing spacecraft, and specifically is proportional to the inverse of the sine of the separation angle (Inhester, 2006). In the case of this event, the separation of ~180° between the two STEREOs results in a large uncertainty in the east–west direction. Hence, the only information that can be retrieved from the TP technique applied to Event 2 is the latitudinal position of each point part of the triangulated loop, resulting in a vertical bar in Figure 4B that is arbitrarily placed at central meridian relative to Earth since its exact longitude is not known. The extent of the loop in the north–south direction is consistent with the location of AR 11165, as expected. Results of the GCS reconstruction are shown in the middle panels of Figure 4. Since the CME was well observed as a limb event from both STEREO spacecraft, we perform our reconstruction while the transient is still visible in SECCHI/COR1 and before it reaches the LASCO/C2 field of view, in order to capture the eruption as close as possible to its initial state. In this results in a propagation direction of S27°W07° as seen from Earth, rather close to location of AR 11165 at the reconstruction time (S17°W12°), but still suggesting a slight
southward deflection. Results from the two geometric techniques are shown together in a 3D representation in the bottom panels of Figure 4. Despite the issues with the application of the TP technique for this particular event discussed above, the two structures obtained match fairly well. Even if an exact longitude of the source region cannot be retrieved from TP, it may be argued that the viewing geometry of the two STEREO spacecraft implies that the triangulated structure was located close to central meridian. An alternative would be to perform a GCS reconstruction based on the EUV images, as made e.g., by O’Kane et al. (2021a).

3.3 Event 3: 2012 February 4
The third CME that we analyze in this work (Event 3) erupted on 2012 February 4 and was a stealth event as seen from Earth. This CME was first reported by D’Huys et al. (2014) and was further analyzed by Alzate and Morgan. (2017). This event was also well observed off limb by both STEREO spacecraft, with STEREO-A
being located 108° west of Earth and STEREO-B being placed 115° east of Earth. Observations from both EUVI and COR1 telescopes are provided in Supplementary Video S5 and show the CME of interest being ejected off the northeastern limb from STEREO-A’s viewpoint and off the northwestern limb from STEREO-B’s perspective, indicating that the eruption originated from the Earth-facing Sun. The pre-eruptive structure could be observed for several hours above the limb from both spacecraft before its slow lift-off (starting around 04:00 UT on February 4), indicating that the CME flux rope erupted from unusually high altitudes. The CME reached the COR2 field of view around 10:00 UT on February 4.

SDO/AIA images corresponding to the eruption period are shown in Figure 5 and Supplementary Video S6. As is often the case for stealth CMEs, these data do not show “explosive” eruption signatures that are more typical of active-region CMEs. Nevertheless, it is possible to distinguish rather clear indications that an eruption occurred, as marked with arrows in the difference image in Figure 5H. Specifically, we observe an elongated pair of brightenings attributable to flare ribbons, the
first being rather prominent and close to the northwestern limb and the second being more diffuse and culminating in the vicinity of the solar north pole, with faint loops reminiscent of a post-eruption arcade in between. These features start to develop around 12:00 UT on February 4. In non-differenced images, the westernmost ribbon appears significantly less prominent and the more diffuse one is not visible at all. The structure that we recognized as a post-eruption arcade based on difference images is somewhat visible, but less clearly attributable to a post-eruption arcade. Although all these coronal features can be observed in intensity images as well, their structure appears sharper in WPE- and MGN-processed data. Furthermore, all images reveal an especially faint dimming region close to the solar north pole (with onset around 06:00 UT on February 4 and indicated with arrows in Figure 5D,L,P. This darkening feature appears equally visible in intensity, MGN, and WPE images. Supplementary Video S6 demonstrates that while it is not possible to establish with certainty whether a large-scale eruption occurred from
intensity images alone, the development of the various brightening features in difference images unambiguously links the CME seen off limb from the twin STEREOs to a rather de
defined source region on the Earth-facing disc.

Figure 6 shows the results of the geometric techniques applied to Event 3. Being well-observed off limb from two different perspectives, the 2012 February 4 CME is well suited to be analyzed using the TP technique. Furthermore, the ~135° separation between the two STEREO spacecraft does not lead to the uncertainty issues that were encountered for Event 2. In the top row of Figure 6, a pre-eruptive loop (on 2012 February 3 at 18:00 UT) is traced with the TP technique in 195Å images from both STEREO spacecraft and then projected onto Earth’s view, resulting in a structure rooted around N55°W30°. Note that the triangulated loop has been projected into a 174Å image from the Sun Watcher using Active Pixel System Detector and Image Processing (SWAP; Halain et al., 2013; Seaton et al., 2013) telescope onboard the Project for On Board Autonomy 2
(PROBA2; Santandrea et al., 2013) satellite, which has a larger field of view than SDO/AIA. The highest point in the reconstructed loop lies at 1.81 \( R_\odot \) from the solar center, confirming that a high-altitude flux rope was involved in the eruption. The middle row of Figure 6 shows the GCS technique applied to simultaneous images of the white-light CME from the SECCHI/COR2 coronagraphs onboard STEREO and the LASCO/C2 coronagraph onboard SOHO. The CME apex has direction N50°W03°, consistent with a high-latitude eruption. Results from the two reconstructions are combined in the bottom row of Figure 6. While the latitudes retrieved from the two methods are in agreement, larger differences are found in the longitudes, which is not surprising considering, for example, that the GCS precision is typically around ±4° for latitude and ±17° for longitude (Thernisien et al., 2009). Nevertheless, both techniques yield a source region that is (at least to some extent) consistent with the bright features indicated in Figure 5H.

### 3.4 Event 4: 2016 October 9

The fourth CME that we analyze in this work (Event 4) erupted on 2016 October 8 and was a stealth event as seen from Earth. This CME was first reported by Nitta and Mulligan. (2017) and was further analyzed by He et al. (2018). Having taken place in 2016, only the viewpoint from STEREO-A located 148° east of Earth is available since contact with STEREO-B was lost in October 2014. Observations from the EUVI and COR1 telescopes onboard STEREO-A are presented in Supplementary Video S7, where the eruption can be seen to originate close to the solar equator off the western limb, corresponding to an ejection off the Earth-facing disc. In addition, the CME cavity extended significantly beyond the central core early in the eruption, suggestive of a much larger-scale event. Loops corresponding to the outer CME rim can be observed to lift off ~25° south of the equator around 16:00 UT on October 8, while structures to the north of the central core cannot be discerned with clarity in the EUVI field of view, most likely because of the presence of a bright helmet streamer. The resulting CME reached the COR2 field of view around 22:00 UT on October 8.

Images from SDO/AIA corresponding to the eruption period are shown in Figure 7 and Supplementary Video S8. It is possible to discern signatures of two different eruptions in the presented data. The first can be noted clearly in the figure in difference images (indicated with an arrow in panel (E)) and in all panels in Supplementary Video S8, and corresponds to a small filament eruption from the northeastern quadrant. Despite the rather evident low-coronal signatures, this eruption does not correspond to the CME seen off limb in STEREO-A imagery (see Supplementary Video S7) because of its timing (~14:00 UT on October 8, several hours too early compared to its first appearance in COR1), its source region (~40° north of the equator), and its localized nature (in contrast to the large-scale CME observed by STEREO-A). Nevertheless, it is possible that this minor eruption destabilized the overlying field(s) and thus facilitated the onset of the subsequent, larger CME. Over the following hours, starting around 18:00 UT on October 8, a pair of coronal dimmings developed, marked by arrows in Figure 7D and evident in Supplementary Video S8. In the difference images in panels (F) and (G), it is evident that the eastern dimming appears deeper than the western one. In data processed with WPE or MGN in panels (A) to (L) and (M) to (P), respectively, the progressive darkening of these two areas over the presented interval shows that the dimmings developed over a remarkably long time span (i.e., even longer than the \( \Delta t = 12 \) h used here for difference images). We do not note differences in the appearance of the dimmings in the intensity, WPE, and MGN images. Their extent in latitude (from ~N02° to ~S22°) is in agreement with the location of the off-limb signatures observed from the STEREO-A viewpoint and shown in Supplementary Video S8.

Results from applying geometric techniques to Event 4 are shown in Figure 8. In the top row, the red line indicates the approximate latitude of the CME core as derived from STEREO-A observations (marked with an arrow in Figure 8A, see also Supplementary Video S7) projected onto the solar disc from both available viewpoints. The latitude of ~S02° is rather consistent with the dimming locations, but less compatible with the GCS reconstruction shown in the middle row of Figure 8, which gives a CME apex propagation direction of N12°E05°, indicating a significant deflection and/or non-radial propagation of the structure toward the north after eruption (this aspect can also be noted in Supplementary Video S8). The dimmings covered a longitudinal span of E44°–W22° at the time of the GCS reconstruction, highlighting the large-scale nature of the event, and were centered around E12°, i.e., well within the GCS uncertainties mentioned in Section 3.3. As was the case for Event 2 and Event 3, this eruption can be convincingly linked to low-coronal signatures (albeit weak), and as was the case for Event 1, relying uniquely on coronagraph imagery and GCS reconstructions would have resulted in a somewhat misleading estimated source region. The fact that this CME was a full halo as seen by SOHO and that only two viewpoints were available certainly contributed to the late reconstruction time, when the apex was already at ~10 \( R_\odot \). Hence, the geometric parameters were only determined after the CME had already experienced significant alterations to its trajectory.

### 4 DISCUSSION AND CONCLUSION

In this work, we have presented and analyzed four stealth CMEs that presented diverse characteristics: a classic streamer blowout (Event 1), a CME originating from an active region (Event 2), a flux rope lying at unusually high altitudes prior to eruption (Event 3), and a significantly large-scale event (Event 4). These case studies were also characterized by different viewing geometries between the “stealthy perspective” (on the solar disc) and the off-limb observ(ers): Event 1 had STEREO-A ~50° away from STEREO-B, Event 2 had the STEREOs nearly in quadrature with Earth, Event 3 had the STEREOs ~110° away from Earth, and Event 4 had STEREO-A separated by ~150° from Earth. We have investigated these CMEs using remote-sensing imaging and geometric techniques in order to determine their corresponding source region on the Sun. Our analysis was based
on EUV images of the solar disc in the 195 Å (STEREO) and 211 Å (SDO) channels, especially suited to detect dimming and brightening regions associated with low-coronal signatures of CMEs (e.g., Nitta and Mulligan, 2017), together with white-light images of the solar corona. Since for all events an approximate region of origin was known due to off-limb views from additional viewpoints, the motivation for our analysis was to test and demonstrate the effectiveness of the different techniques over a range of events with different properties and observation geometries. Our main findings are summarized in Table 1.

Analysis of solar disc imagery with various image processing techniques revealed the presence of signatures for all events, as shown in Table 1, albeit with different confidence levels. The most convincing evidence was found for Event 2 and Event 3, while Event 4 was associated with weak but reasonable signatures and Event 1 was characterized by the largest uncertainties. At least
FIGURE 8 | Geometric techniques applied to the 2016 October 8 CME (Event 4). (A–B) Latitude (thick red line) of the CME core (indicated with an arrow) projected onto the solar disc as seen by STEREO-A and SDO. (C–D) GCS reconstruction applied to the white-light structure seen in STEREO-A and SOHO. (E–F) The GCS-reconstructed CME displayed together with the “source latitude” from (A) and (B) in a 3D representation and shown from the two viewpoints of STEREO-A and Earth.
According to the small sample investigated here, it seems that the main factor contributing to the level of "stealthiness" is the spatial extent of the eruption rather than the altitude from which a CME lifts off (in particular, compare the size of the on-disc signatures for Event 1 and Event 4 with those for Event 2 and Event 3, which are significantly more localised). Another aspect to note is that the eruption associated with the weakest signatures (Event 1) was also the only event that did not feature a nearby active region or area of strong magnetic fields. Regarding the image processing techniques used, it is evident that difference images with large temporal separations revealed the clearest eruptive signatures, as was also reported by Nitta and Mulligan (2017). Moreover, we note that even if dimmings are often evident enough in intensity data, brightenings tend to appear overwhelmingly clearer in difference images (see Event 2 and Event 3). In this work, we have used a fixed $\Delta t = 12$ h for all events, but even longer separations may be explored in the case of eruptions that develop extremely slowly (as for Event 1 and Event 4), although artifacts at the solar limb would also become more prominent and problematic. In this regard, it should be noted that difference images are particularly prone to spurious effects due to spatio-temporal interference; i.e., dimming and brightening features may correspond to “true” dimmings and brightenings as well as moving structures over long time scales. Thus, difference images may be complemented with non-differenced data, which should be used to properly interpret the identified large-scale changes and connect them to well-defined activity on the Sun. Furthermore, we did not find substantial differences in the features revealed in "normal" intensity images and those produced by more advanced processing techniques for the cases that were only associated with (more or less defined) dimmings, i.e. Event 1 and Event 4. Since the main purpose of these methods is to sharpen coronal features and accentuate small-scale variations, it is not surprising that they are as powerful as non-processed images when such structures and alterations are missing in the first place, i.e. in the case of the most problematic events. This overall conclusion is in agreement with O’Kane et al. (2021a), who studied a stealth CME off limb (from a secondary viewpoint) using MGN, but found that this technique did not also reveal the corresponding signatures on disc, which were however completely elusive to other data sets as well. On the other hand, the events that were associated with more prominent structural changes in the corona, i.e. Event 2 and Event 3, showed significantly enhanced features in WPE and MGN imagery in comparison to intensity data. This allows for deeper analysis of the onset and signatures of these eruptions, which may in turn advance understanding of at least a subset of elusive events. Hence, this work demonstrates that advanced image processing techniques are also applicable to a portion of large-scale stealth CMEs observed against the solar disc, in addition to their usefulness for investigating small, short-lived activity and off-limb events that has been shown in previous studies (e.g., Alzate and Morgan, 2017; O’Kane et al., 2019; Liewer et al., 2021). In conclusion, our recommendation for identifying and analyzing the origins of stealth CMEs on the solar disc is a multi-step approach: 1) use difference images to easily single out large-scale changes, 2) use intensity data to properly interpret difference images and rule out artifacts, and 3) if coronal features such as brightenings, loops, and ribbons can be identified, use advanced image processing techniques such as WPE and MGN to analyze their fine structure in deeper detail.

Analysis of the events in this study with the aid of various geometric techniques has revealed that triangulation and reconstruction methods can help trace an eruption back to its source as long as they are used when the CME is as close as possible to the Sun. Given that most CME deflections and other non-radial propagation effects take place below a few solar radii (e.g., Kay et al., 2015; Kay and Opher, 2015; Liewer et al., 2015), it is crucial to determine the geometric parameters before the most dramatic evolution has occurred. In this sense, the CME propagation direction with respect to the observers plays a central role, as can be seen from the reconstructed CME apex heights shown in Table 1: among the cases investigated here, the best scenario was achieved for Event 2 and Event 3, in which the CMEs were propagating in directions well away from at least two viewpoints, enabling a meaningful GCS reconstruction to be made early on. The least favourable configuration happened for Event 4, where the CME was a full halo from one viewpoint and only a second observer was available, thus the apex was already at $\sim 10 R_\odot$ at the time of the performed GCS fitting. In this case, the resulting CME reconstruction strongly hints at an eruption that originated from the northern hemisphere. Hence, without complementary observations from STEREO-A, the source of the white-light structure might have been erroneously attributed to the previous small filament eruption preceding the “main” event. Hence, our recommendation for tracing a CME observed in white light back to its elusive source is to take into consideration the viewing configuration of the event and to be more cautious the farther the reconstructed CME is from the Sun. The TP technique, on the other hand, is quite efficient in triangulating a pre-eruptive structure and/or tracing an eruption back to a source, but is more strongly dependent on the viewing geometry (see Table 1). Excluding cases in which a spacecraft separation of $\sim 180^\circ$ does not allow for a unique solution (see e.g. Event 2), the method requires two well-separated spacecraft to
observe a particular feature simultaneously, so it is not applicable to cases in which an eruption is behind the limb relative to at least one observer. Of course, being able to analyze a stealth CME with triangulation and reconstruction methods implies the availability of additional viewpoints to start with. Apart from helping to discern whether a CME is stealthy or simply far-sided, remote-sensing measurements away from the Sun–observer line may help identify the source of an elusive event in a more or less straightforward way, as was the case for the sample events analyzed in this study. Unfortunately after the loss of STEREO-B and with STEREO-A slowly approaching Earth, the capability to observe stealth CMEs from a viewpoint well-separated from the Sun–Earth line will be lost at least for a while. In the longer term, observations away from the Sun–Earth line, made for example by a STEREO-like, polar, or L4/L5 mission, would help to provide this capability (e.g., Vourlidas, 2015; Lavraud et al., 2016; Gibson et al., 2018; Bemporad, 2021).

The four events analyzed here took place during different stages of the solar cycle, with Event 1 happening at solar minimum, Event 2 and Event 3 close to solar maximum, and Event 4 in the midst of the descending phase of the cycle. Together with the different characteristics of each eruption summarized in Table 1, this indicates that stealth CMEs are not restricted to a particular set of source regions or solar activity period. Hence, although the long-standing question on the fundamental nature of stealth CMEs has not been officially answered yet, this study emphasizes that the characteristics of these events can be as diverse as those of “ordinary” eruptions. Other methods that may help advance current understanding of stealth CMEs include the study of the coronal environment from which these eruptions originate, as was done by O’Kane et al. (2021b) for Event 2 in this work. The authors concluded that flux emergence and magnetic reconnection episodes were observed in the CME source region prior to eruption, which led to the formation of the structure that later left the Sun as a stealth event, and that a high-altitude null point was revealed by photospheric magnetic field extrapolations of the pre-eruptive configuration. Moreover, images of the solar disc taken closer than 1 AU may more easily reveal the eruptive signatures of stealth CMEs. The Solar Orbiter (Müller et al., 2020) spacecraft, launched in February 2020 to orbit the Sun as close as ~0.3 AU and equipped with an EUV instrument as well as a coronagraph, will possibly be able to provide answers in this regard. Finally, it is worth remarking on the impact of stealth CMEs in the wider context of space weather. These events are occasionally capable of driving large geomagnetic disturbances (e.g., Nitta and Mulligan, 2017), so it is important to develop a framework in which they can be fully observed and forecast. One major issue in this sense is that the lack of well-defined low-coronal signatures does not allow for unambiguous analysis of the remote-sensing proxies that are necessary to determine the CME pre-eruptive structure and configuration (e.g., Palmerio et al., 2017). Nevertheless, successfully identifying the source region of a stealth CME represents a first step toward providing more reliable predictions.

DATA AVAILABILITY STATEMENT

All the solar data available in this study can be accessed at the Virtual Solar Observatory (http://sdac.virtualsolar.org/cgi/search). These data were visualised, processed, and analysed using Python’s SunPy package (SunPy Community et al., 2020), IDL SolarSoft (Freeland and Handy, 1998), and the ESA JHelioviewer software (Müller et al., 2017). The original contributions presented in the study are included in the article/Supplementary Material, further inquiries can be directed to the corresponding author.

AUTHOR CONTRIBUTIONS

EP and NN selected the events examined in this study and organized the various aspects of the analysis. EP led the investigation and wrote the draft manuscript. All authors participated in the discussions, read and critically reviewed the manuscript, approved the final version, and agreed to be accountable for all aspects of the work.

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SUPPLEMENTARY MATERIAL

The Supplementary Material for this article can be found online at: https://www.frontiersin.org/articles/10.3389/fspas.2021.695966/full#supplementary-material
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Remote-Sensing Techniques for Stealth CMEs

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Conflict of Interest: The authors declare that the research was conducted in the absence of any commercial or financial relationships that could be construed as a potential conflict of interest.

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