Protein complex detection based on flower pollination mechanism in multi-relation reconstructed dynamic protein networks

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Abstract

Background: Detecting protein complex in protein-protein interaction (PPI) networks plays a significant part in bioinformatics field. It enables us to obtain the better understanding for the structures and characteristics of biological systems.

Methods: In this study, we present a novel algorithm, named Improved Flower Pollination Algorithm (IFPA), to identify protein complexes in multi-relation reconstructed dynamic PPI networks. Specifically, we first introduce a concept called co-essentiality, which considers the protein essentiality to search essential interactions, Then, we devise the multi-relation reconstructed dynamic PPI networks (MRDPNs) and discover the potential cores of protein complexes in MRDPNs. Finally, an IFPA algorithm is put forward based on the flower pollination mechanism to generate protein complexes by simulating the process of pollen find the optimal pollination plants, namely, attach the peripheries to the corresponding cores.

Results: The experimental results on three different datasets (DIP, MIPS and Krogan) show that our IFPA algorithm is more superior to some representative methods in the prediction of protein complexes.

Conclusions: Our proposed IFPA algorithm is powerful in protein complex detection by building multi-relation reconstructed dynamic protein networks and using improved flower pollination algorithm. The experimental results indicate that our IFPA algorithm can obtain better performance than other methods.

Keywords: Protein complex, Dynamic protein-protein interaction (PPI) network, Essential protein, Flower pollination algorithm

Background

Understanding biological processes is an important task in the living organisms. Proteins are vital components in many biological processes, such as metabolism, signalling, transportation and so on. Biological functions are performed by protein complexes composed of proteins interacted with each other, rather than by individual proteins [1, 2]. Detection of protein complexes made great contribution to our knowledge of the molecular mechanisms in cellular life activities. To the best of our knowledge, a large number of works have been done to identify protein complexes from the PPI networks up to now.

As one of the earliest computational methods to predict protein complexes, the Molecular Complex Detection (MCODE) [3] weighted all vertices by using their local neighborhood density and identified the densely connected areas in PPI networks. ClusterONE [4] was utilized to find overlapping protein complexes in the PPI networks. The Clustering-based on Maximal Cliques (CMC) [5] method weighted the interacting protein pairs to identify protein complex. Recent studies TP-WDPIN [6] and NEOComplex [7] were based on the
seed-extension idea to mine protein complexes. WG-Cluster [8] considered the edge weights to detect network modules. Markov Clustering (MCL) [9] discovered relatively dense regions based on the random walks. After that, F-MCL [10] used the firefly algorithm into Markov clustering to optimize the parameters and then recognized protein complexes.

It is well known that Gavin et al. [11] introduced the proteins in complexes consist of two types: core and attachment (periphery), namely, core-attachment structure. As clustering problem [20] and the identification of essential proteins [21] and the interactions are considered as edges. Here, the static PPI networks are converted into the multi-relation reconstructed dynamic PPI networks. And then we apply IFPA to add attachments to the appropriate cores based on the core-attachment structure.

In general, the judgment of interactions between two proteins is implemented by using experimental methods. Unfortunately, these methods are not always dependable [1] and it means that this may contain false positive interactions. There are many previous literatures have revealed the fact that the incorporation of additional biological information can improve the accuracy of protein complex prediction to some extent. For example, Zhang et al. [15] proposed CSO method to predict complexes by combining gene ontology (GO) information with PPI networks. InteHC method [16] integrated different types of data sources to predict protein complexes, including PPI data, GO data, gene expression profiles and AP-MS data. Zhao et al. [17] constructed the weighted protein interaction network by using gene expression information for protein complex identification. Zhou et al. [18] utilized GO to measure semantic similarities as the weights.

Since the flower pollination algorithm (FPA) [19] has shown excellent performance in many applications, such as clustering problem [20] and the identification of essential proteins [21], we explore the application of FPA in detecting protein complexes. In this study, we elicit a concept named co-essentiality, whose basic idea is to use the protein essentiality to find essential edges. Then the multi-relation reconstructed dynamic protein networks are built by combining heterogeneous topology and biology information. Next, those closely linked proteins are grouped together as the cores. Finally, based on the core-periphery structure, the modified FPA algorithm is developed to find the optimal pollination plants for pollen, which means that the peripheries attach to the best core to form the predicted protein complex. The experiments between IFPA and several typical algorithms including MCODE, MCL, ClusterONE, CSO, COACH and CORE are performed on three different PPI networks, and the results demonstrate that IFPA algorithm is more robust and powerful than those existing methods in protein complex recognition.

The remaining part of this paper is organized as follows. Section 2 (Methods) elucidates our proposed new algorithm called IFPA. Section 3 (Results and Discussion) provides the exhaustive analysis and descriptions for the experiments. Finally, Section 4 (Conclusions) is the summary of this study.

Methods

The PPI network can be represented generally as an undirected graph, and the proteins are treated as nodes and the interactions are considered as edges. Here, the static PPI networks are converted into the multi-relation reconstructed dynamic PPI networks. And then we apply IFPA to add attachments to the appropriate cores based on the core-attachment structure.

Building multi-relation reconstructed dynamic PPI networks

The availability of gene expression data enables researchers to reveal the dynamics of molecular networks and improve the identification of protein complexes [22–24]. Hence, based on the study [25], the time course gene expression data is integrated into original static PPI networks to generate dynamic PPI subnetworks so that we can capture the dynamics of protein complexes, that is to say, we split the original static PPI network (OSPN) into twelve dynamic PPI subnetworks (DPSNs), in which all interactions in a DPSN can occur simultaneously, and then perform complex discovery on each DPSN.

First, we use three-sigma method [25] in order to construct dynamic PPI subnetworks with time series gene expression data. The gene expression data involves three metabolic cycles and each cycle contains twelve timestamps. A protein $v$ is considered to be active in DPSN if its gene expression value is not less than the active threshold $Active_{Th}(v)$:

$$Active_{Th}(v) = \mu(v) + 3\sigma(v)(1-F(v))$$

$$F(v) = \frac{1}{1 + \frac{\sigma^2(v)}{\mu(v)}}$$

where $\mu(v)$ is the algorithmic mean of gene expression values of $v$ over times 1 to $n$ and $\sigma(v)$ is the standard deviation of its gene expression values. For each protein, three-sigma method is used to calculate the active threshold $Active_{Th}(v)$. A original PPI network can be described as an undirected graph $G(V, E)$, where $V$ denotes node set that are proteins and $E$ presents edge set that are their connections. And the dynamic PPI network can be represented as $G_t(V, E)$ at timestamp $t$ ($t = 1, 2, ..., n$). At a certain time point, if two proteins $v_i$ and $v_j$ are active and
interact with each other in the original static PPI network, then there is a connection between protein \( v_i \) and \( v_j \) in a DPSN. After that, twelve dynamic PPI subnetworks are constructed from the original static PPI network. Moreover, integrating heterogeneous data source into a single network can enhance the reliability of networks, which inspires us that assigning the suitable weights to edges can strengthen the confidence of interactions, and the implementation will be discussed in the following. Figure 1 illustrates an example of multi-relation reconstructed dynamic PPI networks construction.

Before giving the concept of co-essentiality, we first elaborate the definition of an essential edge. Given two proteins \( v_i \) and \( v_j \), the edge between them is considered as an essential edge if both of \( v_i \) and \( v_j \) are the essential proteins, similarly, the edge between them is considered as an uncertain edge if \( v_i \) or \( v_j \) is the essential protein, and the edge between them is considered as a nonessential edge if neither of \( v_i \) and \( v_j \) is the essential protein. Only the essential edges are taken into account to reconstruct the networks here. And \( ee_{ij} \) is the essential edge between \( v_i \) and \( v_j \), the co-essentiality between these two proteins can be represented as follows.

\[
\text{co-essentiality} (i, j) = \frac{ESS_{ij}}{\text{sum}(ESS_j)}
\]

where \( ESS_{ij} \) denotes the weight value of essential edge which equals to one and \( \text{sum}(ESS_j) \) denotes the sum of the weight values of a column.

**Definition 1** (Co-essentiality) Essential proteins are indispensable for the survival of an organism. Then we can believe that the interaction between two essential proteins is also necessary. Hence, a concept based on essential protein is extended to measure the essentiality between two proteins, and the essentiality values are considered as their weights.

**Fig. 1** An example of multi-relation reconstructed dynamic PPI networks construction.
**Definition 2** (Co-localization) Given two interacting proteins \( v_i \) and \( v_j \), the interaction between them will be more reliable if \( v_i \) and \( v_j \) exist in the same subcellular location, its co-localization is defined by the following equation.

\[
\text{co-localization}(i, j) = \frac{|SCL_i \cap SCL_j|^2}{|SCL_i| \cdot |SCL_j|} \tag{4}
\]

where \(|SCL_i|\) and \(|SCL_j|\) are the number of subcellular location of proteins \( v_i \) and \( v_j \) respectively.

**Definition 3** (Co-annotation) Given two interacting proteins \( v_i \) and \( v_j \), they have the similar function if there are some common GO annotations between \( v_i \) and \( v_j \), its co-annotation is calculated as follows.

\[
\text{co-annotation}(i, j) = \frac{|GO_i \cap GO_j|^2}{|GO_i| \cdot |GO_j|} \tag{5}
\]

where \(|GO_i|\) and \(|GO_j|\) are the number of GO annotations of proteins \( v_i \) and \( v_j \) respectively.

**Definition 4** (Co-cluster) Given two interacting proteins \( v_i \) and \( v_j \), its co-cluster is measured by using the edge clustering coefficient (ECC) [26] as follows.

\[
\text{co-cluster}(i, j) = \frac{Z_{ij}}{\min\{|N_i|-1, |N_j|-1\}} \tag{6}
\]

where \( Z_{ij} \) represents the number of triangles built on edge \((v_i, v_j)\), \(|N_i|\) and \(|N_j|\) are the degrees of protein \( v_i \) and \( v_j \) respectively.

Multiple relation defined above are used to weight the networks. The multi-relation value between \( v_i \) and \( v_j \) is stands for as follows.

\[
\text{multi-relation}(i, j) = \text{co-essentaility}(i, j) + \text{co-localization}(i, j) + \text{co-annotation}(i, j) + \text{co-cluster}(i, j) \tag{7}
\]

These multi-relation values are regarded as the weights of edges \( W(i,j) \) to upgrade the credibility of interactions. For an edge, its normalized \( W(i,j) \) value \( NW(i,j) \) is expressed by the following formula.

\[
NW(i, j) = \frac{\text{multi-relation}(i, j)}{\text{num(multi-relation)}} \tag{8}
\]

where \( \text{num(multi-relation)} \) is the total number of the interactions. For an edge, its normalized weights of edges \( v_i \) and \( v_j \) exist in the same subcellular location, its co-localization is defined by the following equation.
the process of pollen falling on suitable flowers, which is completely different from other general methods. In this subsection, we first give a brief introduction to the flower pollination algorithm (FPA) [19], and then we find the optimal cores for peripheries by ameliorating it.

FPA is a nature-inspired optimization algorithm that comprises two main patterns, that is global pollination and local pollination. The global pollination can be represented as:

\[
x_{t+1}^i = x_t^i + L(x_t^i - G)
\]

where \( x_t^i \) is the pollen \( i \) at iteration \( t \), and \( G \) is the current best solution. The parameter \( L \) is the strength of the pollination, namely a step size, we use a Lévy flight to represent that insects move over a long distance with various distance steps. That is, \( L \) is greater than 0 and obeys the Lévy distribution:

\[
L \sim \frac{\lambda \Gamma(\lambda) \sin(\pi \lambda/2)}{\pi^{1+\lambda}} \left( \frac{s}{s_0} > 0 \right)
\]

where \( \lambda \) is the standard gamma function. The local pollination can be defined as:

\[
x_{t+1}^i = x_t^i + \Psi(x_{t}^j - x_k^j)
\]

where \( x_t^j \) and \( x_k^j \) are pollen from the different flowers of the same plant species. This substantially simulates the flower constancy in a limited neighborhood. Mathematically, if \( x_t^j \) and \( x_k^j \) come from the same plant species or select from the same population, this can be seen as a local random walk if \( \Psi \) obeys the uniform distribution of 0 to 1.

Then, we use IFPA which is an advanced version of FPA algorithm to find the closest cores for peripheries, which is equivalent to finding the most satisfactory flowering plants for pollen. The workflow of IFPA algorithm is shown in Fig. 2. Those proteins not included in the core set are considered as the candidate pollen. In IFPA algorithm, the pollen corresponds to attachments and the pollination plants correspond to cores. The pollen position equals the core sequence numbers. The update of pollen position is expressed as follows.

\[
S_{i,j}^{t+1} = \begin{cases} 
S_{i,j}^t, & \text{if Pollination Priority}_{i,j} > \text{Thr \ randperm}(\text{Num}, d) \\
\end{cases}
\]

where \( \text{Thr} \) denotes a threshold and it is set as 0.2 here. The function of \( \text{randperm} \) is to return an integer from one to \( \text{Num} \) which means to find new core sequence number; and \( \text{Num} \) is the number of cores and the value of \( d \) is one.

**Definition 7 (Pollination Priority)** As a part of an entire protein complex, the attachments maintain relatively close relationship with the core, we call this relationship as pollination priority. The "pollination priority" of a pollen to its core set \( CS \) is represented as follows.

\[
\text{Pollination Priority}(\text{pollen}, CS) = \sum_{u \in CS} \text{co-cluster}(\text{pollen}, u)
\]

where \( u \) is the protein in core set \( CS \). The pollination priority depends on the affinity between the pollen and the flowers. The closer the relationship between pollen and a flower, the higher priority it pollinates on this flower. In the update procedure, if the pollen can find a flower that makes the value of pollination priority better, then the pollen falls on this flower, otherwise, the pollen finds a new flower to pollinate.

Algorithm 1: The pseudoocode of IFPA algorithm

**Input:** The multiset of reconstructed dynamic PPI subnetworks \( G_1, G_2, \ldots, G_t \); Density threshold \( DT \); The maximal iterations of external loop \( maxiter \); Population size \( n \).

**Output:** The set of detected protein complexes \( PSet \).

**Begin:**

for each \( G \) do

- Find core set \( CC \) —the proteins with weighted degree greater than average weighted degree are sorted in descending order.

- \( PSet = \emptyset \)

- // Finding cores

  for each protein \( v \in CC \)

  if protein \( v \) has not been visited do

    \( CS = \{v\} \)

    Find the neighbor \( u \) of \( v \) named \( Nu \)

    for each protein \( u \in Nu \) do

      Calculate Density by using Formula (3)

      if Density > \( DT \) do

        \( CS = CS \cup \{u\} \)

      end

    end

  end

  Merge all the \( CS \)-called \( CSv \)

  Output \( CSv \)

end for

// Finding peripheries

Initialize population

Calculate the values of pollination priority and find optimal solution in initial population

for \( m = 1 : \text{maxiter} \) do

  for \( i = 1 : n \) do

    Update the position of pollen by using formula (14)

    Measure new solutions by using formula (15)

    if new solutions are better, update them in the population

  end for

end for

End for

Find the optimal pollen position, viz., detected candidate protein complexes \( PC \)

End for

Return the final detected protein complexes \( PSet = \{PC, \ldots, PCo\} \)

Filtration operation

**End:**

Finally, we further merge all the candidate protein complexes mined in twelve subnetworks and filter highly overlapping complexes, as our final predicted protein complexes. Algorithm 1 outlines the implementation process of our IFPA method.

**Results and discussion**

**Datasets**

Three popular datasets, i.e., DIP [27], MIPS [28] and Krogan [29], are used to verify our proposed IFPA algorithm. The DIP dataset contains 5028 proteins and 22,302 interactions, the MIPS dataset composes of 4546 proteins and 12,319 interactions, and the Krogan dataset
includes 2674 proteins and 7075 interactions. The gene expression data is obtained from GEO [30] and the dataset contains 9336 genes in three cell life cycles, each cycle having twelve time points. The dynamic PPI networks are built by combining original static PPI networks with gene expression data and the details of dynamic PPI networks on three datasets are presented in Table 1.

The protein subcellular localization dataset is downloaded from the COMPARTMENTS database [31]. There are eleven subcellular localizations as follows: Cytoskeleton, Golgi apparatus, Peroxisome, Nucleus, Extracellular space, Vacuole, Cytosol, Endosome, Mitochondrion, Plasma membrane, Endoplasmic reticulum. After preprocessing, it still includes 6892 subcellular localization records. The GO information was gained from the SGD database [32]. There are 1285 essential proteins are collected from the following databases: MIPS [33], SGD [32], DEG [34], and SGDP (http://sequence.stanford.edu/group/yeast_deletion_project). CYC2008 [35] is used as the benchmark dataset which contains 408 protein complexes.

**Evaluation metrics**

The most commonly used evaluation metrics are used in our experiments and their specific definitions are described below.

**Definition 8 (Overlapping Score)** Given a predicted protein complex $P$ and a known protein complex $K$, the Overlapping Score ($OS$) between $P$ and $K$ is defined as follows.
OverlappingScore$(P, K) = \frac{|V_P \cap V_K|^2}{|V_P| \cdot |V_K|}$ \hfill (16)

where $|V_P \cap V_K|$ is the number of common proteins in the predicted protein complex $P$ and the known protein complex $K$, $|V_P|$ is the size of the predicted complex and $|V_K|$ is the size of the known complex. If $OS \geq 0.2$, we consider that the predicted complex matches with the real one.

**Definition 9 (Sensitivity, Specificity and F-measure)**

Sensitivity ($Sn$), Specificity ($Sp$) and F-measure are represented as follows.

\begin{equation}
Sn = \frac{TP}{TP + FN} \hfill (17)
\end{equation}

\begin{equation}
Sp = \frac{TP}{TP + FP} \hfill (18)
\end{equation}

\begin{equation}
F\text{-measure} = \frac{2 \cdot Sn \cdot Sp}{Sn + Sp} \hfill (19)
\end{equation}

where $TP$ is the number of the predicted complexes which are matched with the known complexes, $FN$ is the number of known complexes which are not matched with any predicted complexes, and $FP$ is the number of the predicted complexes which are not matched with any known complexes. F-measure is a comprehensive metric combined sensitivity and specificity.

**Definition 10 (p-value)** In order to estimate the statistical significance of detected protein complexes, the researchers annotate their biological functions by using p-value. Given a predicted protein complex, the p-value [36] is the probability that a protein complex is enriched by a given functional group by chance. Let $k$ is the number of proteins of the functional group in the complex, $N$ is the size of the whole PPI network, $C$ is the size of a protein complex and $F$ is the size of a functional group in the network. And the p-value is defined as follows.

\begin{equation}
p\text{-value} = 1 - \sum_{i=0}^{k-1} \left( \frac{F}{i} \right) \left( \frac{N-F}{C-i} \right) \hfill (20)
\end{equation}
The $p$-value is used to evaluate the biological relevance of the predicted protein complexes. Generally, the protein complex is considered to be meaningless if its $p$-value is greater than 0.01. And for a complex, the smaller its $p$-value is, the more biological significance it has.

**Parameter analysis**

The density threshold $DT$ decides whether a protein could be merged into the current core. How to choose a relatively suitable $DT$ should be carefully considered to achieve better performance of our IFPA algorithm. Thus, varying $DT$ from 0.1 to 0.9 with the interval 0.05, we calculate $F$-measure to observe the effect of the variation of $DT$ on the performance of our IFPA algorithm, so as to choose the relatively appropriate $DT$, as shown in Fig. 3. Obviously, all three datasets show similar trends in most cases from Fig. 3. Especially, the major evaluation metrics $F$-measure obtains the better value when $DT$ is set as 0.25 based on the both DIP and MIPS datasets and when $DT$ is set as 0.15 based on the Krogan dataset, which means that IFPA is more effective. For this reason, the density threshold $DT$ is set as 0.25 in DIP and MIPS datasets and 0.15 in Krogan dataset.

**Performance comparison**

To prove the validity of our proposed algorithm, we compare IFPA algorithm with MCODE, MCL, ClusterONE, CSO, COACH and CORE on three different PPI networks. Figures 4, 5, 6 show the overall comparison in terms of $Sn$, $Sp$ and $F$-measure based on DIP, MIPS and Krogan datasets, respectively. Apparently, IFPA algorithm yields the best $F$-measure in comparison with other...
existing methods in all datasets, which means that our IFPA method remarkably outperforms other methods. Besides, in Table 2, PC denotes the total number of detected protein complexes, MPC is the number of detected protein complexes which were matched, MKC represents the number of matched known protein complexes, Perfect denotes OS = 1 which means that the predicted protein complexes are perfectly matched with the known protein complexes. As shown in Table 2, the protein complexes detected by our IFPA method dominates other methods in the aspects of Perfect both in DIP and MIPS datasets.

Many of our detected protein complexes have a good match with the known protein complexes. We consider a detected complex to be biologically significant if its p-value is less than 0.01. In order to confirm the biological significance of detected protein complexes, the p-value is calculated by using the tool GO::TermFinder (https://www.yeastgenome.org/cgi-bin/GO/goTermFinder.pl). We randomly select some predicted protein complexes to calculate their p-value concerning Biological Process ontologies based on Krogan dataset, as shown in Table 3. From Table 3, all of these detected protein complexes obtain smaller p-value and it demonstrates that the protein complexes predicted by our IFPA method have strong biological significance. The predicted complexes with strong biological significance can provide help for biology researches to some extent.

Figure 7 visualizes an example of predicted protein complex named golgi transport complex in Krogan dataset so as to display the detection result more obviously. Figure 7 (A) displays a benchmark protein complex, Fig. 7 (B), (C), (D), (E) and (F) illustrate the identified protein complexes by MCODE, MCL, CORE, ClusterONE and IFPA, respectively. The purple nodes are the correctly identified proteins, the blue nodes are proteins that are not recognized, and the pink nodes are the wrongly identified proteins. From Fig. 7, we can see that MCODE and CORE correctly identifies four and two proteins, respectively. And MCL identifies a total of four proteins including

| Table 2 | Comparative performance of IFPA and other methods on three datasets |
|---------|-------------------------|
| Dataset | Algorithm  | PC   | MPC  | MKC  | Perfect |
| DIP     | MCODE      | 165  | 102  | 70   | 6       |
|         | MCL        | 1541 | 386  | 245  | 14      |
|         | ClusterONE | 972  | 329  | 197  | 15      |
|         | CORE       | 1517 | 420  | 259  | 39      |
|         | CSO        | 342  | 214  | 136  | 11      |
|         | COACH      | 474  | 265  | 144  | 13      |
|         | IFPA       | 935  | 425  | 219  | 47      |
| MIPS    | MCODE      | 135  | 72   | 60   | 4       |
|         | MCL        | 1259 | 254  | 196  | 17      |
|         | ClusterONE | 744  | 208  | 152  | 17      |
|         | CORE       | 1217 | 303  | 225  | 29      |
|         | CSO        | 246  | 127  | 87   | 6       |
|         | COACH      | 396  | 145  | 92   | 5       |
|         | IFPA       | 772  | 288  | 167  | 32      |
| Krogan  | MCODE      | 160  | 127  | 73   | 10      |
|         | MCL        | 658  | 300  | 178  | 40      |
|         | ClusterONE | 585  | 271  | 161  | 28      |
|         | CORE       | 677  | 279  | 172  | 39      |
|         | CSO        | 189  | 156  | 89   | 10      |
|         | COACH      | 221  | 179  | 85   | 11      |
|         | IFPA       | 447  | 288  | 131  | 21      |
one that is misidentified. Albeit ClusterONE recognizes more proteins, it also has misidentifications. IFPA successfully detects the most proteins and all of them are correct, indicating that our predicted complex match very well with benchmark complex and our IFPA method is more accurate than other comparative methods.

**Conclusions**

Identification of protein complexes from PPI networks is distinctly important in proteomics. In this study, a flower pollination mechanism-based method is proposed to detect protein complexes in multi-relation reconstructed dynamic protein networks. To begin with, we build multi-relation reconstructed dynamic protein networks. Then, according to the core–periphery structure, we group the closely connected proteins as the cores and apply IFPA algorithm to attach peripheries to the optimal cores to form the predicted protein complexes. IFPA algorithm has been carried out on three different multi-relation reconstructed dynamic PPI networks and the experimental results demonstrate that our IFPA algorithm can obtain better clustering performance compared with other methods in most cases. The protein complexes we detected are likely to help the biologists gain some useful biological insights.

**Table 3** Function enrichment analysis of predicted protein complexes detected on Krogan dataset

| No. | Gene Ontology term                                         | p-value   | Cluster frequency | Genes annotated to the term                                                                 |
|-----|-----------------------------------------------------------|-----------|------------------|-----------------------------------------------------------------------------------------------|
| 1   | intra-Golgi vesicle-mediated transport                    | 1.91e-16  | 100.0%           | YER157W, YGL005C, YGL223C, YGR120C, YMR091C, YNL041C, YPR105C                                |
| 2   | polyadenylation-dependent snoRNA 3’-end processing        | 3.32e-18  | 100.0%           | YER157W, YGL005C, YGR120C, YMR091C, YNL041C, YPR105C, YPR4/YMR001W                         |
| 3   | exonucleolytic trimming involved in rRNA processing       | 5.02e-20  | 100.0%           | YER157W, YGL005C, YGR120C, YMR091C, YNL041C, YPR105C, YPR4/YMR001W                         |
| 4   | negative regulation of gluconeogenesis                   | 3.00e-17  | 100.0%           | YER157W, YGL005C, YGR120C, YMR091C, YNL041C, YPR105C, YPR4/YMR001W                         |
| 5   | chromatin disassembly                                     | 3.83e-20  | 100.0%           | YER157W, YGL005C, YGR120C, YMR091C, YNL041C, YPR105C, YPR4/YMR001W                         |
| 6   | positive regulation of transcription from RNA polymerase I promoter | 5.96e-16  | 87.5%            | YER157W, YGL005C, YGR120C, YMR091C, YNL041C, YPR105C, YPR4/YMR001W                         |

Fig. 7 The golgi transport complex detected by different methods

(A) Benchmark

(B) MCODE

(C) MCL

(D) CORE

(E) ClusterONE

(F) IFPA
Abbreviations
ECC: Edge clustering coefficient; FPA: Flower pollination algorithm; GO: Gene ontology; OS: Overlapping Score; PPI: Protein-protein interaction

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Authors’ contributions
XL conceptualized the algorithm, designed the method and drafted the manuscript, MF designed the method and drafted the manuscript and polished the English expression. All of the authors have read and approved the final manuscript.

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