Planetesimal fragmentation and giant planet formation

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ABSTRACT

Context. In the standard scenario of planet formation, terrestrial planets and the cores of the giant planets are formed by accretion of planetesimals. As planetary embryos grow, the planetesimal velocity dispersion increases because of gravitational excitations produced by embryos. The increasing relative velocities of the planetesimal cause them to fragment through mutual collisions.

Aims. We study the role of planetesimal fragmentation on giant planet formation. We analyze how planetesimal fragmentation modifies the growth of giant planet cores for a wide range of planetesimal sizes and disk masses.

Methods. We incorporated a model of planetesimal fragmentation into our model of in situ giant planet formation. We calculated the evolution of the solid surface density (planetesimals plus fragments) taking into account the accretion by the planet, migration, and fragmentation.

Results. Incorporating planetesimal fragmentation significantly modifies the process of planetary formation. If most of the mass loss in planetesimal collisions is distributed in the smaller fragments, planetesimal fragmentation inhibits the growth of the embryo for initial planetesimals of radii smaller than 10 km. Only for initial planetesimals with a radius of 100 km, and disks larger than 0.06 $M_\odot$, embryos achieve masses larger than the mass of Earth. However, even for these large planetesimals and massive disks, planetesimal fragmentation induces the quick formation of massive cores only if most of the mass loss in planetesimal collisions is distributed in the larger fragments.

Conclusions. Planetesimal fragmentation seems to play an important role in giant planet formation. The way in which the mass loss in planetesimal collisions is distributed leads to different results, inhibiting or favoring the formation of massive cores.

Key words. planets and satellites: formation – methods: numerical

1. Introduction

According to the core-accretion model (Lissauer & Stevenson 2007), the formation of a giant planet occurs through a sequence of events: initially, the dust (particles of ~μm sizes) collapses onto the protoplanetary disk mid-plane. Then these particles agglomerate by different mechanisms, which are still debated, which leads to the formation of planetesimals (objects of between hundreds of meters and hundreds of kilometers). These planetesimals grow by mutual accretions until some bodies begin to separate themselves from the population of planetesimals (terrestrial embryos, objects with sizes of a few thousand kilometers). The embryo gravitational excitation, which is higher than that of the planetesimals, limits their growth, and embryos are the only bodies that grow by accretion of planetesimals. As the embryos grow, they bound a gaseous envelope. Initially, the planetesimal accretion rate is much higher than the gas accretion rate. However, when the mass of the envelope reaches a critical value on the order of the mass of the solid core, a gaseous runaway growth process starts. Finally – by mechanisms that are also still debated – the planet stops to accrete gas and evolves, contracting and cooling at constant mass.

Therefore, it is important to study the evolution of the population of planetesimals together with the process of accretion and planet formation. The evolution of the population of planetesimals is a complex phenomenon. Probably the most relevant phenomena are planetesimal accretion by the embryos, migration due to gas drag produced by the gaseous component of the protoplanetary disk, collisional evolution through gravitational excitations produced by embryos, and planetesimal dispersion and gap openings.

As embryos grow, they increase the relative velocities of the planetesimals causing planetesimal fragmentation. After successive disrupting collisions also called collisional cascade planetesimals become smaller. Inaba et al. (2003), Kobayashi et al. (2011), and Ormel & Kobayashi (2012) found that a significant amount of mass, which remains in small fragments as a product of the collisions between planetesimals, may be lost by migration due to gas drag. This means that the planetesimal fragmentation seems to play an important role in forming the cores of giant planets. Moreover, as embryos grow, they begin to bind the surrounding gas. Initially, embryo gaseous envelopes are less massive, but wide spread. These envelopes cause a loss of the planetesimal kinetic energy, significantly increasing the capture cross-section of the planets. The smaller planetesimals of the distribution suffer more from these effects. Accordingly, while smaller fragments have higher migration rates due to gas drag, they are more efficiently accreted by the planet. There is a strong competition between the time scales of migration and accretion of small fragments generated by planetesimal fragmentation. Therefore, it is important to study in detail whether the generation of small fragments, the products of planetesimal fragmentation, favors or inhibits giant planet formation.

In previous works (Guilera et al. 2010, 2011) we developed a model for giant planet formation that calculates their formation.
immersed in a protoplanetary disk that evolves in time. In these previous works the population of planetesimals evolved by the accretion of the embryos and by planetesimal migration. In this new work, we incorporated the fragmentation of planetesimals to study whether this phenomena produces significant changes, which would make it a primary key to consider in the process of planetary formation.

This work is organized as follows: in Sect. 2 we introduce some improvements to our previous model; in Sect. 3, we explain in detail our planetesimal fragmentation model; Sect. 4 shows the results of the role of planetesimal fragmentation on the growth of an embryo located at 5 au; finally, in Sect. 5 we present the conclusions from our results.

2. Improvements to our previous model

Our model that describes the evolution of the protoplanetary disk is based on the works of Guilera et al. (2010, 2011) with some minor improvements incorporated. We used an axisymmetric protoplanetary disk characterized by a gaseous and a solid component. The gaseous component is represented by a 1D grid for the radial coordinate, while the solid component is represented by a 2D grid, where one dimension is for the radial coordinate and the other one is for the different planetesimal sizes. Some quantities are only functions of the radial coordinate (R), such as the gas surface density \( \Sigma_g(R) \), while some others are also functions of the planetesimal sizes, such as the planetesimal surface density \( \Sigma_p(R, r_p) \).

2.1. Planetesimal size distribution

We changed the treatment of the planetesimal size distribution from our previous work. We now considered that the different radii are logarithmically equally spaced, so the \( j \) species is given by

\[
r_{p,j} = \left( \frac{r_{p,j-1/2}}{r_{p,j}} \right) r_{p,j}, \quad j = 1, ..., N, \tag{1}
\]

where \( r_{p,j} \) and \( r_{p,j-1/2} \) are the largest and smallest radii of the size distribution, and \( N \) is the number of size bins considered. If \( m_{p,j} \) is the mass between \( m_{p,j-1/2} \) and \( m_{p,j+1/2} \), and adopting that the planetesimal mass distribution is represented by a power law \( (dn/da \propto m_p)^{-\alpha} \), \( m_{p,j} \) is given by

\[
m_{p,j} = \int_{m_{p,j-1/2}}^{m_{p,j+1/2}} mn(m) \, dm = \frac{C m_{p,j-1/2}^{2-\alpha}}{2-\alpha} \left( \Delta_{3/2-\alpha} - \Delta_{5/2-\alpha} \right), \tag{2}
\]

where we use that \( m_{p,j} = \Delta^{(j-1)/(N-1)} m_{p,1} \) with \( \Delta = r_{p,j}/r_{p,j-1} \). In the same way, the total mass is given by

\[
m_T = \int_{m_{p,1/2}}^{m_{p,N+1/2}} mn(m) \, dm = \frac{C m_{p,1/2}^{2-\alpha}}{2-\alpha} \left( \Delta_{3/2-\alpha} - \Delta_{5/2-\alpha} \right). \tag{3}
\]

The amount of mass (with respect to the total mass) corresponding to the \( j \) species is given by

\[
p_j = \frac{m_{p,j}}{m_T} = \frac{\Delta_{3/2-\alpha} - \Delta_{5/2-\alpha}}{\Delta_{3/2-\alpha} - \Delta_{5/2-\alpha}}. \tag{4}
\]

Finally, the planetesimal surface density corresponding to the planetesimals of radius \( r_p \) is obtained by multiplying \( p_j \) and the total surface density of solids. Then, we treated each planetesimal size independently. In this approach we can use only one planetesimal size (for this case \( p = 1 \)) or a discrete number \( (N) \) of bins to approximate the continuous planetesimal size distribution.

2.2. Evolution of planetesimal eccentricities, inclinations, and velocity migrations

As in our previous works, we considered that the evolution of the eccentricities and inclinations of the planetesimals are governed by two main processes: the embryo gravitational excitations and the damping due to the gas drag.

The embryo stirring rates of the eccentricities and inclinations are given by (Ohtsuki et al. 2002)

\[
\frac{de^2}{dt}_{\text{stirr}} = \frac{M_p}{3bM^\star P_{\text{orb}}} P_{\text{stirr}}, \tag{5}
\]

\[
\frac{d\theta^2}{dt}_{\text{stirr}} = \frac{M_p}{3bM^\star P_{\text{orb}}} Q_{\text{stirr}}, \tag{6}
\]

where \( M_p \) is the mass of the planetary embryo, \( M^\star \) is the mass of the central star, \( b \) is the full width of the feeding zone of the planetary embryo in terms of its Hill radius, and \( P_{\text{orb}} \) is the orbital period of the embryo. Finally, \( P_{\text{stirr}} \) and \( Q_{\text{stirr}} \) are functions of the planetesimal eccentricities and inclinations (for more details see Chambers 2006). However, this is a local approach. The gravitational excitation decreases with increasing distance between the planetary embryo and the planetesimals. Hasegawa & Nakasawa (1990) showed that when the distance from the planetary embryo is larger than about four times its Hill radius, the excitation over the planetesimals decays significantly. Therefore, we need to restrict this effect to the neighborhood of the planetary embryo. Using the EVORB code (Fernandez et al. 2002), we fit a modulation function to reproduce the excitation over the quadratic mean value of the eccentricity of a planetesimal.

We found that this excitation is well reproduced by

\[
f(\Delta) = \frac{1}{1 + \left( \frac{\Delta}{2 \Delta_{5/2-\alpha}} \right)^2}, \tag{7}
\]

where \( \Delta = R - R_p \) represents the distance from the planet (\( R_p \) is the planet radius orbit), \( R_H \) is the planetary embryo Hill radius, and \( f(\Delta) \) guarantees that the eccentricity and inclination profiles of the planetesimals are smooth enough for a numerical treatment and that the planetary excitation on planetesimals is restricted to the embryo neighborhood.

On the other hand, the eccentricities and inclinations of the planetesimals are damped by the gaseous component of the protoplanetary disk. This damping depends on the planetesimal relative velocity with respect the gas, \( v_{\text{plan}} \), and on the ratio between planetesimal radius and the molecular mean free path, \( \lambda \). Adopting a gaseous disk mainly composed of molecular hydrogen (H\(_2\)), the last is given by (Adachi 1976)

\[
\lambda_{H_2} = \frac{\mu_{H_2}}{\sqrt{2\pi} p_g d_H}, \tag{8}
\]

where \( \mu_{H_2} \) and \( d_H \) are the molecular weight and molecular diameter of the molecular hydrogen, and \( p_g \) is the volumetric gas density.
As in the recent work of Fortier et al. (2013), we considered three different regimes (Rafikov 2004; Chambers 2008).

- the Epstein regime: \( r_p < \lambda_{\text{H}} \);
- the Stokes regime: \( r_p > \lambda_{\text{H}} \) and \( Re < Re_{\text{trans}} \); and
- the quadratic regime: \( r_p > \lambda_{\text{H}} \) and \( Re > Re_{\text{trans}} \).

where \( Re = \frac{v_{\text{rel}}^2 r_p}{v} \) is the Reynolds number and \( Re_{\text{trans}} = 20 \) is the transition between the Stokes and quadratic regimes (Rafikov 2004). The viscosity \( \nu \) corresponds to the molecular viscosity, given by

\[
nu = \frac{\lambda_{\text{H}} c_s}{3}.
\]

where \( c_s \) is the local speed of sound.

Incorporating the different regimes is important because smaller products (fragments of planetesimal fragmentation) might be present in the Stokes or Epstein regimes. The three drag regimes can be characterized in terms of the stopping time given by (Chambers 2008)

\[
\begin{align*}
\tau_{\text{stop}}^{\text{eps}} &= \frac{\rho_{\text{p}} v_{\text{rel}}}{\rho_{\text{g}} c_s}, \\
\tau_{\text{stop}}^{\text{sto}} &= \frac{2 \rho_{\text{p}} v_{\text{rel}}}{3 \rho_{\text{p}} c_s \lambda_{\text{H}}}, \\
\tau_{\text{stop}}^{\text{qua}} &= \frac{6 \rho_{\text{p}} v_{\text{rel}}}{\rho_{\text{g}} \lambda_{\text{H}}^2},
\end{align*}
\]

where \( \rho_{\text{p}} \) is the planetesimal density. The relative velocity between planetesimals and the gas is given by

\[
v_{\text{rel}}^{\text{rel}} = \sqrt{\frac{5}{8} \frac{v_k^2 c_s^2 + \frac{1}{2} v_k^2}{v_k}},
\]

where \( v_k \) is the Keplerian velocity and \( \eta = (v_k - v_g)/v_k \) is the ratio of the gas velocity to the Keplerian velocity.

The damping rates of the eccentricities and inclinations for each regime are given by (Rafikov 2004; Chambers 2008)

\[
\begin{align*}
\frac{d e^2}{dt}^{\text{eps}} &= -2 \tau_{\text{stop}}^{\text{eps}} \left( \frac{s_{\text{eps}}^2}{1 + s_{\text{eps}}^2} \right) e^2, \\
\frac{d i^2}{dt}^{\text{eps}} &= -2 \tau_{\text{stop}}^{\text{eps}} \left( \frac{s_{\text{eps}}^2}{1 + s_{\text{eps}}^2} \right) i^2,
\end{align*}
\]

where \( s_{\text{eps}} = 2 \pi \tau_{\text{stop}}^{\text{eps}} / P_{\text{orb}} \).

\[
\begin{align*}
\frac{d e^2}{dt}^{\text{sto}} &= -2 \tau_{\text{stop}}^{\text{sto}} \left( \frac{s_{\text{sto}}^2}{1 + c_s^2} \right) e^2, \\
\frac{d i^2}{dt}^{\text{sto}} &= -2 \tau_{\text{stop}}^{\text{sto}} \left( \frac{s_{\text{sto}}^2}{1 + c_s^2} \right) i^2,
\end{align*}
\]

where \( s_{\text{sto}} = 2 \pi \tau_{\text{stop}}^{\text{sto}} / P_{\text{orb}} \), and

\[
\begin{align*}
\frac{d e^2}{dt}^{\text{qua}} &= -2 \tau_{\text{stop}}^{\text{qua}} \left( \frac{s_{\text{qua}}^2}{1 + c_s^2} \right) e^2, \\
\frac{d i^2}{dt}^{\text{qua}} &= -2 \tau_{\text{stop}}^{\text{qua}} \left( \frac{s_{\text{qua}}^2}{1 + c_s^2} \right) i^2,
\end{align*}
\]

Finally, the evolution of the eccentricities and inclinations are given by solving the coupled equations by

\[
\begin{align*}
\frac{de^2}{dt} = f(\Delta) \frac{de^2}{dt}^{\text{gas}} + \frac{de^2}{dt}^{\text{stir}}, \\
\frac{di^2}{dt} = f(\Delta) \frac{di^2}{dt}^{\text{gas}} + \frac{di^2}{dt}^{\text{stir}}.
\end{align*}
\]

The gas drag also causes an inward planetary orbit migration. Then, the change rate of the major semi-axis is given by

\[
\frac{da}{dt} = \nu_{\text{mig}} = \begin{cases} 
\frac{2 \rho_{\text{p}} v_{\text{rel}}^2}{\rho_{\text{g}} \lambda_{\text{H}}^2} - \frac{\rho_{\text{p}} v_{\text{rel}}^2}{\rho_{\text{g}} c_s}, & \text{Epstein regime} \\
\frac{2 \rho_{\text{p}} v_{\text{rel}}^2}{\rho_{\text{g}} \lambda_{\text{H}}^2} - \frac{\rho_{\text{p}} v_{\text{rel}}^2}{\rho_{\text{g}} c_s}, & \text{quadratic regime.}
\end{cases}
\]

### 2.3. Oligarchic accretion regime

As in previous works, we considered that the embryos grow in the oligarchic regime. Assuming the particle-in-a-box approximation, the planetesimal accretion rate of the \( j \) species is given by (Inaba et al. 2001)

\[
\frac{dM_j}{dt} = \frac{2 \pi \Sigma_j (R_p, r_p, j) R_i^2}{P_{\text{orb}}} P_{\text{coll}} \left( R_C, R_H, t_{\text{rel}}^{\mu^p, -p} \right),
\]

where \( M_C \) is the embryo core mass and \( P_{\text{coll}} \) is the collision probability between the planetesimal \( j \) species and the embryo (see Guidera et al. 2010, for the explicit expression of \( P_{\text{coll}} \)). The collision probability is a function of the embryo core radius \( (R_C) \), the embryo Hill radius, and the relative velocity between the planetesimal \( j \) species and the embryo, which is given by

\[
v_{\text{rel}}^{\mu^p, -p} = \sqrt{\frac{5}{8} e^2 + \frac{1}{2} \eta^2 v_k}.
\]

When the embryo has a substantial envelope we have to incorporate the enhancement of capture cross-section of the embryo. As in previous works, we used the prescription given by Inaba & Ikoma (2003) to calculate the embryo enhanced radius \( \tilde{R}_C \), where they proposed replace \( R_C \) for \( R_C \) in the expressions of the collision probability.

The feeding zone of the embryo is often defined as the ring around it where planetesimals can be accreted. We defined the width of the feeding zone as about four times the embryo Hill radius (at both sides of the embryo). To do this, we integrate Eq. (23) over the radial grid

\[
\frac{dM_j}{dt} = \frac{2 \pi R_i^2 P_{\text{coll}}}{P_{\text{orb}}} \int_F \frac{2 \pi R \psi(R, R_p, R_H) \Sigma_j (R, r_p) \ dR},
\]

where \( \psi(R, R_p, R_H) \) is a normalization function that satisfies \( \int_{\infty}^{\infty} 2 \pi R \psi(R, R_p, R_H) \ dR = 1 \). In contrast with our previous work, we chose that

\[
\psi = \frac{3 e^{-\frac{(R_p-R_H)^2}{8 \pi R_p R_H \Gamma(1/6)}}}{8 \pi R_p R_H \Gamma(1/6)},
\]

where \( \Gamma \) is the gamma function. With this new choice of \( \psi \), \( \frac{dM_j}{dt} \) becomes smooth for a numerical treatment. We employed a Simpson rule to integrate Eq. (25) where at least ten radial bins between \( R_p - 4 R_H \) and
$R_D + 4R_H$ are considered. Finally, the total planetesimal accretion rate is given by

$$\frac{dM_C}{dt} = \sum_j \frac{dM^j_C}{dt}. \quad (27)$$

The rest of the model is the same as described in detail in Guilera et al. (2010).

### 3. Planetesimal fragmentation

We incorporated a model of planetesimal fragmentation in our model of giant planet formation that is based on the BOULDER code (Morbidelli et al. 2009, and supplementary material). This code models the accretion and fragmentation of a population of planetesimals (because our model of giant planet formation starts with an embryo already formed, surrounded by a swarm of planetesimals, i.e., in the oligarchic growth regime, we first took into account only the corresponding fragmentation prescriptions, see next sections).

According to this model, if $Q_{D}^{i}$ is the specific impact energy per unit target mass (energy required to disperse 50% of the target mass) and $Q$ is the collisional energy per unit target mass, the collision between a target of mass $M_T$ and a projectile of mass $M_P$ (with $M_P \leq M_T$) gives a remnant of mass $M_R$ that is given by

$$M_R = \begin{cases} -0.35 \left( Q_{D}^{i} - 1 \right) + \frac{1}{2} \left( M_T + M_P \right), & \text{if } Q < Q_{D}^{i}, \\ -\frac{1}{2} \left( Q_{D}^{i} - 1 \right) + \frac{1}{4} \left( M_T + M_P \right), & \text{if } Q > Q_{D}^{i}. \end{cases} \quad (28)$$

If $M_R > M_T$, the collision results in accretion. On the other hand, if $M_R < 0$, the target is fully pulverized and its mass is lost. In general, $Q_{D}^{i}$ is function of the radius of the target. However, because the model considers that the mass of the remnant is a function of $(M_T + M_P)$, for consistency, $Q_{D}^{i}$ must be calculated using an effective radius which is given by

$$r_{\text{eff}} = \left[ \frac{3(M_T + M_P)}{4\rho} \right]^{1/3}, \quad (29)$$

where $\rho$ is the density of the planetesimals. The mass ejected from the collision, defined as $(M_T + M_P - M_R)$, is distributed following a power-law mass distribution $dn/dm \propto m^{-3}$ between the minimum bin mass considered and the bin mass corresponding to the larger fragment $M_F$ given by

$$M_F = 8 \times 10^{-3} \left( \frac{Q}{Q_{D}^{i}} \right)^{-3/4} e^{-\left( Q/4Q_{D}^{i} \right)^{4/3}} \left( M_T + M_P \right). \quad (30)$$

We found that for some hugely catastrophic collisions (when $M_R < M_T + M_P$) the mass of the larger fragment is greater than the mass of the remnant. Therefore, we set $M_F = 0.5M_T$ for these collisions.

The exponent $p$ of the mass distribution is given by

$$p = \frac{1}{3} (3-q), \quad (31)$$

where $q$ is the exponent of the cumulative power-law distribution, and is given by

$$q = -10 + 7 \left( \frac{Q}{Q_{D}^{i}} \right)^{0.4} e^{-\left( Q/7Q_{D}^{i} \right)}. \quad (32)$$

For the specific impact energy, we adopted the prescription given by Benz & Asphaug (1999). We used the prescription for basaltic at impact velocities of 5 km s$^{-1}$ given by

$$Q_{D}^{i} = 3.5 \times 10^{7} \rho_p^{-0.38} + 0.3 \rho_p r_p^{1.36}, \quad (33)$$

using a planetesimal density of $\rho_p = 1.5$ g cm$^{-3}$. In this prescription we used the effective radius (given by Eq. (29)) instead of the planetesimal radius.

In our global model we consider the evolution by migration, accretion and fragmentation of a population of planetesimals of radii between 1 cm and $r_p^{\text{max}}$ (a free parameter). However, in a collisional regime the evolution of the population is ultimately governed by the size distribution of the smallest objects. This means that the truncation in $r_p = 1$ cm can generate the accumulation of spurious mass in the smaller fragments. To avoid this problem, we extrapolated the size distribution to a minimum fragment size of $r_p = 0.01$ cm, when we calculated the fragmentation process. In this way, the mass ejected from the collision is distributed between the mass bin corresponding to $r_p = 0.01$ cm and the bin mass corresponding to $M_F$, as mentioned above. This means that we are considering that the mass distributed below the mass bin corresponding to $r_p = 1$ cm is lost. Moreover, if the mass bin corresponding to $M_F$ is below the mass bin corresponding to $r_p = 1$ cm, we considered that the target is fully pulverized.

The total number of collisions between targets $j$ and projectiles $i$ in a time $\Delta t$ is given by (Morbidelli et al. 2009, and supplementary material)

$$N_{C_{tn}}^{i} = p_{C}^{i} n_p f_{g}^{i} (r_p + r_p)^2 \Delta t, \quad (34)$$

where $p_{C}^{i}$ is the intrinsic collision probability, $n_p (r_p)$ and $n_p (r_p)$ are the numbers (radii) of targets and projectiles, respectively, and $f_{g}^{i}$ is the gravitational focusing factor. The time step $\Delta t$ is limited by a physical condition. Using that $N_{C_{tn}}^{i}$ is the total number of collisions of the targets $j$ given by

$$N_{C_{tn}}^{i} = \sum_{j} N_{C}^{i,j} = n_p \sum_{j} P_{C}^{i,j} n_p f_{g}^{i} (r_p + r_p)^2 \Delta t, \quad (35)$$

and defining $\tau_i$ as

$$\tau_i = \sum_{j} P_{C}^{i,j} n_p f_{g}^{i} (r_p + r_p)^2, \quad (36)$$

we can write,

$$N_{C_{tn}}^{i} = n_p \tau_i \Delta t. \quad (37)$$

Then, $N_{C_{tn}}^{i}$ cannot be greater than $n_p$, so for our model we adopted that $\Delta t < 0.1/\tau_i$. This condition implies that for our global model the time step cannot be greater than $10^{-4}$ Myr for $r_p^{\text{max}} = 10, \, 100 \, \text{km}$, and $10^{-3}$ Myr for $r_p^{\text{max}} = 0.1, \, 1 \, \text{km}$.

### 3.1. Implementation of the fragmentation model

The evolution of the surface densities of planetesimals obeys a continuity equation,

$$\frac{\partial}{\partial t} \left[ \Sigma_p (R, r_p) \right] - \frac{1}{R} \frac{\partial}{\partial R} \left( R \frac{dR}{dt} \Sigma_p (R, r_p) \right) = {\mathcal F}(R, r_p), \quad (38)$$

where $R$ and $r_p$ reference radial and planetesimal size dependencies, and $\mathcal F$ are the sink terms. In our previous works, we only considered the planetesimal accretion by forming embryos as a
Fig. 1. Schematic illustration of the fragmentation zone for an isolated planet in the radial grid. IEFZ (OEFZ) represents the inner (outer) edge of the fragmentation zone, while \( R_p \) is the radial bin corresponding to the planet. The fragmentation zone extends to eight Hill radii on either side of the planet. sink term. With the incorporation of the planetesimal fragmentation, we introduce a new sink term in Eq. (38), which is solved with a full implicit method in finite differences.

To incorporate the fragmentation process in the global model, we defined a fragmentation zone for each embryo where we calculated the collisional process (Fig. 1). This zone extends to eight Hill radii on either side of the embryo (twice the feeding zone)\(^1\). In this way we reduced the computational cost and safely guaranteed that collisions that produce fragmentation (craterization or catastrophic collisions) are within this zone, since they do not extend far away from the feeding zone. In fact, the excitations of the eccentricities and inclinations of the planetesimals (and hence the relative velocities) abruptly decay far away from the feeding zone (Eq. (21)).

In each radial bin of the fragmentation zone, the eccentricities, inclinations, and surface densities for each planetesimal size are defined. As we mentioned above, to calculate the evolution of the system mass, we considered a size distribution between 1 cm and a \( r_{p}^{\text{max}} \), where initially the total mass of the system is distributed in planetesimals of radii \( r_{p}^{\text{max}} \). However, to model the fragmentation we extrapolated the planetesimal sizes (also the eccentricities, inclinations, and numbers of bodies) to planetesimals of radius \( r_{p} = 0.01 \) cm. In this way, we avoided spurious mass accumulation in the smaller planetesimals of the distribution.

The implementation methodology is as follows. The eccentricities, inclinations, and surface densities are defined for each size bin (between \( r_{p} = 1 \) cm and \( r_{p} = r_{p}^{\text{max}} \)) and for each radial bin in the fragmentation zone. From the surface densities, the number of bodies for each size bin and for each radial bin are calculated. With these data, we extrapolate the inclinations, eccentricities, and number of bodies for the corresponding size bins between \( r_{p} = 0.01 \) cm and \( r_{p} = 1 \) cm. Then, we take a target \( j \) belonging to the radial bin IEFZ (inner edge of the fragmentation zone, Fig. 1). We take a projectile \( i \) (with \( r_{p,i} \leq r_{p,j} \), i.e. from \( r_{p,j} = 0.01 \) cm to \( r_{p,j} = r_{p,j} \)) of the radial bin IEFZ, and calculate if the orbits of the target and the projectile overlap (taking into account only the eccentricities of the target and projectile). If the orbits overlap, the number of collisions between targets \( j \) and projectiles \( i \) are calculated. With this information we can calculate how much mass the projectiles \( i \) disperse from targets \( j \) and how this mass (remnant plus fragments) is distributed in smaller planetesimals than target \( j \).\(^2\) This is repeated for all projectiles belonging to the radial bin IEFZ. Then we move to the radial bin IEFZ+1 and repeat the process for all the projectiles that correspond to target \( j \) of the radial bin IEFZ. This process is repeated until the radial bin OEFZ (outer edge of the fragmentation zone) is achieved. This process is repeated for all targets \( j \) from radial bin IEFZ, that is, from \( r_{p,j} = 1 \) cm to \( r_{p,j} = r_{p}^{\text{max}} \). Then we move to the radial bin IEFZ+1 and repeat the process for all the targets. The process is repeated until it reaches the radial bin OEFZ for the targets.

When the process is completed, we have the change in mass (loss and gain) for each planetesimal size and for each radial bin, the product of the planetesimal fragmentation. With this we can calculate the change in the surface densities for each planetesimal size inside the fragmentation zone.

4. Results

The protoplanetary disk is defined between 0.4 au and 20 au, using 2500 radial bins logarithmically equally spaced. We applied our model to study the role of planetesimal fragmentation on giant planet formation. We calculated the in situ formation of an embryo located at 5 au for different values of the minimum mass solar nebula (MMSN; Hayashi 1981), which is given by

\[
\Sigma_p = \begin{cases} 
7.1 \left( \frac{R}{1 \text{ au}} \right)^{-3/2} & \text{g cm}^{-2} \quad R < 2.7 \text{ au} \\
30 \left( \frac{R}{1 \text{ au}} \right)^{-3/2} & \text{g cm}^{-2} \quad R > 2.7 \text{ au},
\end{cases}
\] (39)

\[
\Sigma_g = 1700 \left( \frac{R}{1 \text{ au}} \right)^{-3/2} \text{g cm}^{-2},
\] (40)

\[
T = 280 \left( \frac{R}{1 \text{ au}} \right)^{-1/2} \text{K},
\] (41)

\[
\rho_g = 1.4 \times 10^{-9} \left( \frac{R}{1 \text{ au}} \right)^{-11/4} \text{g cm}^{-3}.
\] (42)

where \( \Sigma_p \) and \( \Sigma_g \) represent the planetesimal and gaseous surface densities, \( T \) is the temperature profile, and \( \rho_g \) is the volumetric density of gas at the mid-plane of the disk. The discontinuity at 2.7 au in the surface density of planetesimals is caused by the condensation of volatiles, often called snow line. For numerical reasons, and following Thommes et al. (2003), we spread the snow line with a smooth function, so the surface density of planetesimals is described by

\[
\Sigma_p = \begin{cases} 
7.1 + (30 - 7.1) \left[ \frac{1}{2} \tanh \left( \frac{R - 2.7}{0.5} \right) + \frac{1}{2} \right] & \text{g cm}^{-2}.
\end{cases}
\] (43)

We carried out two different sets of simulations. In the first one, we took into account that the planetesimal surface density evolved only by accretion of planetesimals by the embryo and for the orbital migration of planetesimals. In the other set of simulations the planetesimal surface density evolved by accretion, orbital migration, and planetesimal fragmentation.

For the gaseous component of the disk, Alexander et al. (2006) found that after a few Myr of viscous evolution the disk could be completely dissipated by photo-evaporation in a timescale of 10\(^5\) yr. For simplicity, we considered that the gaseous component of the disk exponentially dissipated in 6 Myr, when photo-evaporation acts and completely dissipates it. So, we ran our models until the embryo achieved the critical mass (when the mass of the envelope equals the mass of the core) or for 6 Myr.

\(^1\) If the fragmentation zones of two embryo overlap, we only define one fragmentation zone that contains both embryos.

\(^2\) Numerically, when a collision occurs, we consider that the target \( j \) disappears from its corresponding radial bin \( a_j \), while the projectile \( i \) disappears from its corresponding radial bin \( a_i \). On the other hand, the remnant and the fragments are distributed in the radial bin \( a_j \) corresponding to the target.
We started our simulations with an embryo of 0.005 $M_\oplus$, which has an initial envelope of $\sim 10^{-13} M_\oplus$, immersed in an initial homogeneous population of planetesimals of radius $r_{\text{max}}$ (we considered different values for $r_{\text{max}}$: 0.1, 1, 10, 100 km). It is important to remark that our initial conditions correspond to the beginning of the oligarchic growth. Employing statistical simulations, Ormel et al. (2010) found that starting with an homogeneous population of planetesimals of radius $r_0$, the transition from the runaway growth to the oligarchic growth is characterized by a power-law mass distribution given by $dn/dm \propto m^{-p}$ (with $p \sim 2.5$), between $r_0$ and a transition radius $r_{\text{trans}}$ for the population of planetesimals, and isolated bodies (planetary embryos). This implies that most of the solid mass lies in small planetesimals. For simplicity, and considering the fact that most of the mass lies in the smaller planetesimals of the population, we used a single-size distribution instead of a planetesimal-size distribution to represent the initial planetesimal population. Consequently, our initial conditions are consistent with the oligarchic growth regime using $r_{\text{max}}$ as $r_0$.

In this work we aim to analyze how planetesimal fragmentation impacts on the process of planetary formation. Accretion collisions between planetesimals are important for studying the transition from planetesimal runaway growth to the oligarchic growth. In the oligarchic growth, embryos gravitationally dominate the dynamical evolution of the surrounding planetesimals. As embryos grow, they increase the planetesimal relative velocities and collisions between planetesimals result in fragmentation (erosive or disruptive collisions). For these reasons, we focused our analysis on fragmentation collisions. However, as we show in next sections, for some special cases the total planetesimal accretion rates are dominated by the accretion of very small fragments ($r_p \sim 1$ m). For these small fragments, collisions between them (and obviously with smaller fragments) result in accretion. Therefore, we also calculated coagulation between planetesimals for these special cases (see next sections for a detailed discussion of this topic).

As we mentioned in the previous section, when planetesimal fragmentation is considered (when it is not considered, we used a single-size distribution to represent the planetesimal population) we used a discrete size grid between 1 cm and $r_{\text{max}}$ to represent the continuous planetesimal size distribution where the fragments, products of planetesimal fragmentation, are distributed. The size step is given by Eq. (1). Because we used the same size step independently of the value of $r_{\text{max}}$, this implies that we used 21 size bins for $r_{\text{max}} = 0.1$ km, 26 size bins for $r_{\text{max}} = 1$ km, 31 size bins for $r_{\text{max}} = 10$ km, and 36 size bins for $r_{\text{max}} = 100$ km. In all cases, the initial total mass of solids along the disk remains in the size bins corresponding to $r_{\text{max}}$. The collisional evolution of planetesimals is the mechanism that regulates the exchange of mass between the different size bins.

In previous works (Guilera et al. 2010, 2011) we showed that the in situ simultaneous formation of solar system giant planets occurred on a time-scale compatible with observed estimates only if most of the solid mass accreted by the planets remains in small planetesimals ($r_p < 1$ km). Recently, Fortier et al. (2013) studied the role of planetesimal sizes in planetary population synthesis in detail. They found that including oligarchic growth makes the formation of giant planets using big planetesimals ($r_p \sim 100$ km) unlikely, and only if most of the mass of the system remains in small objects ($r_p \sim 0.1$ km) cores grow enough to form giant planets. However, small planetesimals have lower specific impact energies per unit target mass. This means that small planetesimals suffer catastrophic collisions at lower collisional energies.

The results of the two sets of simulations are summarized in Table 1. For smaller planetesimals ($r_p = 0.1$ km), the collisional evolution completely inhibited planetary formation. When planetesimal fragmentation was not taken into account, the embryo was able to achieve the critical mass for $2-10$ values of the MMSN before the dissipation of the nebula. Moreover, for disks more massive than four times the MMSN the times at which embryo achieves the critical mass are very short ($\lesssim 0.5$ Myr), while the critical masses are high ($\gtrsim 30 M_\oplus$). When we included planetesimal fragmentation, the picture drastically changed. For none of the analyzed cases the critical mass was reached. Moreover, even for the case of the more massive disk (10 MMSN), the planetary embryo was unable to achieve one Earth mass. In Fig. 2, we show the total accretion rate of planetesimals as a function of the core mass for $r_{\text{max}} = 0.1$ km. When planetesimal fragmentation is incorporated, the total planetesimal accretion rate is completely inhibited despite the low values of the core masses. The small differences between the disks at which the values of the core mass planetesimal fragmentation start to decrease the accretion rates are caused by the amount of gas of the different disks. The more massive the disk, the higher the damping in the planetesimal eccentricities and inclinations, hence the planetesimal relative velocities are lower for the same value of the core mass.

These drops in the planetesimal accretion rates are due to a drastic diminution in the mean value of the surface density of planetesimals of radius 0.1 km in the feeding zone compared

### Table 1. Results of the two sets of simulations, with and without planetesimal fragmentation (PF).

| #   | $r_{\text{max}} = 0.1$ km | $r_{\text{max}} = 1$ km | $r_{\text{max}} = 10$ km | $r_{\text{max}} = 100$ km |
|-----|--------------------------|-------------------------|--------------------------|---------------------------|
|     | Without PF | With PF | Without PF | With PF | Without PF | With PF | Without PF | With PF | Without PF | With PF |
|     | $M_C$ (t) | (Myr) | $M_C$ (t) | (Myr) | $M_C$ (t) | (Myr) | $M_C$ (t) | (Myr) | $M_C$ (t) | (Myr) |
| 2   | 23.10      | 4.41  | 23.10      | 4.41  | 23.10      | 4.41  | 23.10      | 4.41  | 23.10      | 4.41  |
| 4   | 32.23      | 0.39  | 32.23      | 0.39  | 32.23      | 0.39  | 32.23      | 0.39  | 32.23      | 0.39  |
| 8   | 35.25      | 0.17  | 35.25      | 0.17  | 35.25      | 0.17  | 35.25      | 0.17  | 35.25      | 0.17  |
| 10  | 36.24      | 0.77  | 36.24      | 0.77  | 36.24      | 0.77  | 36.24      | 0.77  | 36.24      | 0.77  |

Notes. The first column corresponds to the disk mass. A value of # means that we consider a disk # times more massive than the minimum mass solar nebula (MMSN) of Hayashi (1981). $M_C$ represents the core mass when the planet achieves the critical mass and t represents the time at which this occurs. Simulations stopped at $t = 6$ Myr, so that in this case $M_C$ represents the core mass at this time. For $r_{\text{max}} = 0.1$ km and for disks 8 and 10 times more massive than the MMSN, planetesimal accretion rates become so high that models do not converge when planetesimal fragmentation is not considered.

3 For 8 and 10 values of the MMSN the planetesimal accretion rates become so high that models do not converge.
the three di
is shown as dotted lines. For this case, the critical mass is achieved for
function of the core mass. The case without planetesimal fragmentation
Fig. 2. Total planetesimal accretion rates for three different disks as a
function of the core mass. The case without planetesimal fragmentation
is shown as dotted lines. For this case, the critical mass is achieved for
three different disks in less than 6 Myr. When planetesimal fragmentation
is incorporated the total planetesimal accretion rates significantly
drop. Despite the lower values of the core masses, the fragmentation
process truncated the embryo growth.

with the case without planetesimal fragmentation. In Fig. 3, we
plot the time evolution of the mean value of the surface density of planetesimals in the feeding zone for a disk 6 times more massive than the MMSN. For the case without planetesimal fragmentation (red solid curve), the total surface density corresponds to planetesimals of radius 0.1 km. This is not the case when planetesimal fragmentation is considered (solid black curve). However, the total surface density is dominated by the surface density of planetesimals of 0.1 km (dashed red curve). (Color version online.)

As we mentioned above, we considered that the mass loss in collisions is distributed following a power-law mass distribution between fragments of $r_p = 0.01$ cm and the largest fragment of mass $M_F$. Accordingly, if the exponent $p$ of the mass distribution ($dn/dm \propto m^p$) is higher than 2, most of the mass is distributed in the smaller fragments, and if $p < 2$, most of the mass is distributed in bigger fragments. When $p > 2$, most of the mass is distributed in fragments smaller than 1 cm, so this mass is lost in our model. In Fig. 4, we show the values of $q$, the exponent of the cumulative power-law distribution (Eq. (32)), as a function of $Q/Q_*$. We can see that except for values between $2 \leq Q/Q_* \leq 3.5$, $q$ is always lower than $-3$. This means that in general $q < -3$, so $p > 2$ (see Eq. (31)) and most of the mass distributed in fragments is lost. It is important to remark that for these step distributions, the integration over the mass, between $m = 0$ and $m = M_F$, diverges. In the Boulder code, this problem is solved by using that these mass distributions are valid between $m = m_0$ and $m = M_F$ and using an ad hoc mass distribution with an exponent $p = 11/6$ between $m = 0$ and $m = m_0$. In this approach, most of the mass loss in collisions is distributed in the radial bin corresponding to $r_1$ (the transition radius corresponding to $m_0$). However, we did not follow this approach. We truncated the mass distribution in a minimum mass, the one corresponding to $r_p = 0.01$ cm (we tested lower values than $r_p = 0.01$ cm and found analogous results). This is an alternative approach, adopting a fixed value of $r_1 = 0.01$ cm and calculating the exponent $p$, such that the integration over the mass between $m = 0$ and $m = M_F$, converges. In this way, we always guarantee for each collision that the mass distributed between $r_p = 0.01$ cm and the radial bin corresponding to planetesimals of mass $M_F$ does not exceed the mass ejected from the collision ($M_T + M_P - M_k$).

The second effect is that the remnants, products of the collisions between planetesimals of radius 0.1 km, are quickly pulverized. Because these planetesimals initially contain all the mass of the system, the pulverization of the remnants implies a high loss of mass. For example, in Fig. 5 we can see the radial

Fig. 3. Time evolution of the mean value of the surface density of planetesimals in the feeding zone for a disk 6 times more massive than the MMSN. For the case without planetesimal fragmentation (red solid curve), the total surface density corresponds to planetesimals of radius 0.1 km. This is not the case when planetesimal fragmentation is considered (solid black curve). However, the total surface density is dominated by the surface density of planetesimals of 0.1 km (dashed red curve). (Color version online.)

Fig. 4. Exponent of the cumulative power-law distribution as a function of $Q/Q_*$ given by the fragmentation model. The value $q = -3$ implies that $p = 2$ (Eq. (31)). This means that the mass lost in a collision is distributed homogeneously among the fragments.

4 For some simulations, we tested the approach given by the Boulder code and found that $r_1$ is always smaller than 1 cm. However, we had to accept the assumption that there is only one body of mass $M_F$ to be able to calculate all the free parameters in the resulting integral mass equation.
profiles of the eccentricities and inclinations at different times at the embryo’s neighborhood. The gravitational perturbations of the planet increase the eccentricities and inclinations of the planetesimals near the planet’s location. From this profile we can analyze the relative velocities, and the ratio $Q/Q^*$, when targets and projectiles belong to the same radial bin. Figure 6 shows the time evolution of the radial profiles for the relative velocities (top panel) and for the ratio $Q/Q^*$ (bottom panel) when targets and projectiles belong to the same radial bin. It follows from Eq. (28) that if the ratio $Q/Q^*$ corresponding to a collision is higher than $\sim 2.5$, the remnant of such a collision is pulverized. As we can see from Fig. 6, the collisions between planetesimals with radius of 0.1 km quickly become supercatastrophic and the mass of the remnants, their products, is lost.

Finally, in Fig. 7 we show the time evolution of the number of planetesimals and the planetesimal surface densities at the embryo’s radial bin. The number of planetesimals with a radius of 0.1 km is quickly reduced by the collisional evolution. Moreover, the generation of fragments does not compensate the loss of planetesimals with a radius of 0.1 km. In fact, the values of the planetesimal surface densities for planetesimals smaller than 0.1 km are always $\ll$ 1 gr cm$^{-2}$.

We found similar results for the others values of $r_p^{\max}$. Collisions between planetesimals of radius $r_p^{\max}$ become supercatastrophic and significantly reduce the total planetesimal accretion rates. This effect, combined with the fact that most of fragment mass is deposited in size bins smaller than the one corresponding to $r_p = 1$ cm, prevented the formation of a core from reaching the critical mass.

Only for $r_p^{\max} = 100$ km and massive disks, we were able to form cores with masses greater than one Earth mass. This is because despite of higher relative velocities for bigger planetesimals, the ratio $Q/Q^*$ is lower compared to small planetesimals (Fig. 8). In Fig. 9, we plot the planetesimal accretion rates for $r_p^{\max} = 100$ km and a disk ten times more massive than the MMSN. With the red solid line, we plot the total planetesimal accretion rate. This accretion rate abruptly drops compared with the case without planetesimal fragmentation because of the lower accretion of planetesimals with a radius of 100 km. The accretion of fragments also does not compensate for the lower accretion of planetesimals with a radius of 100 km.

Finally, in Fig. 10 we show the time evolution of the radial surface density profiles of planetesimals with a radius of 100 km, for the case with and without planetesimal fragmentation. The profiles are the same at 0.5 Myr. At 1 Myr the planetesimal surface density around the planet’s location (5 au) is clearly lower for the case with planetesimal fragmentation, but not by planetesimal accretion by the embryo. We can see from Fig. 9 that at this time the accretion rate of planetesimals with a radius of 100 km is practically the same as that without planetesimal fragmentation. Eventually, the lower planetesimal surface density around the planet’s location increases even more, for the case with planetesimal fragmentation. Finally, at 4 Myr, the planetesimal surface density is almost zero around the planet’s location. We also can see that the mass-loss through planetesimal fragmentation is higher near the planet’s location and lower far away from the planet.

We found that our results are insensitive to the numbers of radial and size bins. We tested our results with twice radial and size bins and obtained analogous results.
cretion of the embryo, migration, and planetesimal fragmentation. The number of planetesimals evolves by accretion adopting a value of $10^3 m_{⊕}$. The formation of cores with masses greater than $100 km$ is only possible for massive disks, and only if large planetesimals are considered ($r_p \geq 100 km$).

As we mentioned in previous sections, most of the fragment mass produced by the collisions between planetesimals is deposited in size bins smaller than $1 cm$, because the exponent $p$ of the power-law of the fragment mass distribution is generally larger than 2. However, other works suggested that the exponent $p$ should be in a range between 1 and 2. This implies that most of the fragment mass is deposited in larger fragments and the mass loss is much smaller than in our model. Kobayashi & Tanaka (2010) developed a similar fragmentation model (in a qualitative way about the outcome of a collision) where the fragment mass is also distributed following a power-law distribution ($dn/dm \propto m^{-p}$). In Kobayashi et al. (2010, 2011) and Ormel & Kobayashi (2012), this model was applied to study planetary formation adopting a value of $p = 5/3$. These authors found that in general planetesimal fragmentation inhibits the formation of massive cores. The formation of cores with masses greater than $10 M_{⊕}$ is only possible for massive disks, and only if large planetesimals are considered ($r_p \geq 100 km$).

We applied our model using a fixed exponent $p = 5/3$ for the power-law mass distribution of the fragments. We again ran the simulation for a disk ten times more massive than the MMSN using an initial population of planetesimals with a radius of $100 km$ (our best case). Using a fixed exponent $p = 5/3$, we found that planetesimal fragmentation favors the formation of a massive core. For this simulation, we found that the embryo achieved the critical mass at $3.61 Myr$ ($\sim 0.5 Myr$ early than without planetesimal fragmentation) with a core of $18 M_{⊕}$ ($\sim 6.5 M_{⊕}$ smaller than without planetesimal fragmentation).

In Fig. 11 we plot the time evolution of the total planetesimal accretion rates for the case without planetesimal fragmentation and $p = 5/3$, and the planetesimal accretion rates for different planetesimal sizes for $p = 5/3$. Without planetesimal fragmentation, the planetesimal accretion rate of planetesimals with a radius of $100 km$ corresponds to the total planetesimal accretion rate. However, this is not the case when planetesimal fragmentation is considered. Between $\sim 0.5 Myr$ and $\sim 1 Myr$ the accretion rate of planetesimals with $r_p = 100 km$ is slightly lower than that without fragmentation. However, the total planetesimal accretion rate is higher. This is because of the accretion of fragments, especially for the accretion of fragments between $0.1 km$ and $25 km$. Then, the accretion rate of planetesimals of $r_p = 100 km$ increases at $\sim 1 Myr$. This is because at this time

4.1. Fragment distribution
the ratio $\tilde{R}_C/\tilde{R}_C$ becomes higher than unity, so the enhanced in the capture-cross section due to the embryo’s envelope for planetesimals with a radius of 100 km make the accretion of such planetesimals more efficient. The total planetesimal accretion rate remains higher than without fragmentation until $\sim$2.5 Myr. This excess in the total planetesimal accretion rate is the reason that at $\sim$2.5 Myr the planet has a core of $\sim$12.5 $M_\oplus$ (Fig. 13 top). At the same time, the planet without planetesimal fragmentation has a core of $\sim$4.5 $M_\oplus$. After 2.5 Myr, the total planetesimal accretion rate decreases because of planetesimal fragmentation until the planet reaches the gaseous runaway phase.

In Fig. 12, we compare the time evolution of the number of planetesimals at the planet’s radial bin for the cases where the exponent of the power-law that represents the planetesimal mass distribution has a constant value of 5/3 and where this exponent is calculated via Eq. (31). There are many more fragments between $\sim$0.1 km and $\sim$25 km in the first case for 0.75 Myr, 1 Myr, and 2 Myr. This is because for this case, the mass loss in collisions is deposited in smaller fragments, while open circles represent the case where the mass loss in collisions is deposited in larger fragments. For this last case, the planet achieved the critical mass at $\sim$3.61 Myr. (Color version online.)

A similar behavior occurs for less massive disks. However, for a disk eight times more massive than the MMSN the planet
did not reach the critical mass. After 6 Myr of evolution, the planet achieved a total mass of $\sim 20 \, M_\oplus$ ($\sim 14 \, M_\oplus$ for the core and $\sim 6 \, M_\oplus$ for the envelope, Fig. 13 bottom). Although this final core is smaller than the case without planetesimal fragmentation (Table 1), at 4 Myr the planet has a core slightly larger than $10 \, M_\oplus$ (in the case without planetesimal fragmentation the planet has a core of $\sim 4 \, M_\oplus$ at the same time).

We also found that for small planetesimals, if most of the fragment mass is deposited in larger fragments the total planetesimal accretion rate becomes higher than in the case in which most of the fragment mass is deposited in smaller fragments. However, for these cases the total planetesimal accretion is always lower than for the case in which planetesimal fragmentation is considered. We calculated again the simulations for a disk ten times more massive than the MMSN, in which $p = 5/3$ and $r_p^{\text{max}} = 0.1$ km, as a function of time. The dashed black line represents the total planetesimal accretion rate for the case without planetesimal fragmentation (WF). The dashed red line represents the total planetesimal accretion rate for the case with planetesimal fragmentation with $p = 5/3$. Bottom: time evolution of the total planetesimal accretion rates (solid lines) and the accretion rates of fragments with $1 \, \text{m}$ (dashed lines) for the case where only planetesimal fragmentation is considered (red lines) and for the case in which planetesimal coagulation and fragmentation are considered (black lines). The plot corresponds to a disk ten times more massive than the MMSN and for the case of $r_p^{\text{max}} = 0.1$ km. (Color version online.)

As an example, in Fig. 14 (top) we plot the planetesimal accretion rates for $r_p^{\text{max}} = 0.1$ km. The accretion rate of planetesimals with a radius of radius $0.1$ km drops significantly (green curve), and the total accretion rate is ultimately dominated by small planetesimals ($r_p \sim 1$ m, violet curve). The planetesimal accretion rates of fragments with $r_p \sim 1$ m become significant high values of the total planetesimal accretion rates, but this effect is fictitious because small planetesimals coagulate and form larger bodies. For this case, we stopped the simulation at 0.75 Myr because at this time the core had reached a mass of $\sim 12 \, M_\oplus$. But again, these results might be fictitious. A planetesimal coagulation model is necessary in these cases.

This effect does not occur for large planetesimals, where the accretion of such small fragments does not significantly contribute to the total accretion rate. In fact, for large planetesimals,
the total accretion rate is always dominated by the accretion of planetesimals of radius \( r_p^{\text{max}} \) and the fragments that significantly contribute to the total accretion rate have radii larger than 0.1 km (collisions are disruptive for such fragments).

However, to be more rigorous with these intuitive analyses, we recalculated the simulations for \( r_p^{\text{max}} = 100 \) km and \( r_p^{\text{max}} = 0.1 \) km, but also incorporating coagulation between planetesimals in the model. Following the Boulder code, we considered that the outcome of a collision results in accretion if the mass of the remnant is larger than the mass of the target. We considered that when a coagulation between planetesimals occurs, the target and projectile are removed from their corresponding radial bins, and a new object of mass \( M_T + M_P \) is put in the radial bin corresponding to the target, that is, we considered perfect accretion. We pursued a very simple intuition with this: we wish to analyze whether the coagulation between planetesimals modifies (or not) the results found in this section. Therefore, we considered for simplicity the size grid that represents the continuous planetesimal size distribution to be fixed. It is important to note that the computational costs are much higher.

For \( r_p^{\text{max}} = 100 \) km, we found identical results for both cases, considering only planetesimal fragmentation or considering planetesimal coagulation and fragmentation. As we argued before, this is because small fragments contribute negligibly to the total planetesimal accretion rate (Fig. 11).

However, for \( r_p^{\text{max}} = 0.1 \) km, we found that the incorporation of planetesimal coagulation significantly modified the results. In Fig. 14 (bottom), we plot the time evolution of the total planetesimal accretion rate and the accretion rate of fragments of 1 m for the case with only planetesimal fragmentation and for the case with planetesimal coagulation and fragmentation. For this last case, after 6 Myr of evolution the core achieved a mass of only \( \sim 3 \) \( M_\oplus \). In both cases, the accretion of fragments of \( \sim 1 \) m governed the total accretion rates, but the incorporation of planetesimal coagulation drastically lowers the accretion of such fragments. It is clear that when the accretion of very small fragments becomes important in the total planetesimal accretion rate, a full planetesimal collisional model (which includes coagulation and fragmentation) is needed. We will study this topic in detail by developing a full planetesimal collisional model in a future work, incorporating an adaptive size grid to study in more detail the collisional evolution of the planetesimal population and starting from the planetesimal runaway growth.

Finally, planetesimal coagulation did not quantitatively modify the results shown in Table 1 for low values of \( r_p^{\text{max}} \). For these cases, all the accretion rates for the different planetesimal sizes significantly decrease with time because the fact that most of the mass loss in collisions is distributed below the size bin corresponding to \( r_p = 1 \) cm.

4.2. Accretion of small fragments

We briefly discuss the accretion of small fragments (pebbles). Lambrechts & Johansen (2012) found that pebbles are accreted extremely efficiently by embryos. Pebbles with the appropriate Stoke number have a capture cross-section as large as the Hill radius of the embryo, even if the embryo does not have a gaseous envelope. When they pass within the Hill radius, they spiral down to the embryo’s physical radius because of gas drag. Lambrechts & Johansen (2012) found that the pebble accretion rates (in the Hill accretion regime) is given by

\[
M_{\text{H}} = 2 \pi \Sigma_p r_p \Omega_p r_{\text{H}},
\]

where \( \Omega_p = \Omega_K R_p \), and \( \Omega_K \) is the Keplerian frequency. As the authors note, in the classical scenario of planetesimal accretion, planets do not accrete planetesimals from the Hill radius. Instead, planets accrete planetesimals from a fraction \( \alpha^{1/2} \) of the Hill radius, with \( \alpha = R_C/R_H \).

In the low velocity regime, the probability collision or small planetesimals is given by

\[
P_{\text{coll}} = 11.3 \sqrt{R_C/R_H},
\]

because we also considered the enhanced radius due to the planet’s gaseous envelope \( P_{\text{coll}} = 11.3 \sqrt{R_C/R_H} \). In terms of the pebble accretion rate, our planetesimal accretion rate (for small fragments) is given by

\[
M = 5.65 \sqrt{R_C/R_H} M_\oplus.
\]

In Fig. 15 we plot the evolution of the term \( \sqrt{R_C/R_H} \) as a function of the core mass for different planetesimal sizes. The plot corresponds to the case of a disk ten times more massive than the MMSN and \( r_p^{\text{max}} = 100 \) km when planetesimal coagulation and fragmentation are considered. The black dashed line corresponds to the evolution of the term \( (R_p/R_H)^{1/2} \), where \( R_p \) is the radius of the planet. (Color version online.)

\[\text{Fig. 15. Factor } \sqrt{R_C/R_H} \text{ as a function of the core mass for different planetesimal sizes. The plot corresponds to the case of a disk ten times more massive than the MMSN and } r_p^{\text{max}} = 100 \text{ km when planetesimal coagulation and fragmentation are considered. The black dashed line corresponds to the evolution of the term } (R_p/R_H)^{1/2}; \text{ where } R_p \text{ is the radius of the planet. (Color version online.)}\]

In our models the planet’s radius is the radius of the envelope, which is the minimum between the accretion radius and the Hill radius, see Guilera et al. (2010).
4.3. Simultaneous formation of two embryos

Finally, we analyzed the in situ simultaneous formation of two embryos. We aimed to study if the fragments generated by an outer embryo (which have an inward migration) favor the formation of an inner embryo. We only analyzed the case of a disk ten times more massive than the MMSN, where initially all the solid mass of the system is deposited in planetesimals of \( r_p = 100 \) km and for the case \( p = 5/3 \). We located the embryos at 5 au and 6 au. Both embryos initially have cores of 0.005 \( M_\oplus \) and envelopes of \( \sim 10^{-12} M_\oplus \). The simulation stopped at \( \sim 2.5 \) Myr. At this time, the embryo located at 5 au achieved a total mass of 13.20 \( M_\oplus \) (12.10 \( M_\oplus \) for the core and 1.10 \( M_\oplus \) for the envelope), while the embryo located at 6 au achieved a total mass of 2.61 \( M_\oplus \) (2.60 \( M_\oplus \) for the core and 0.01 \( M_\oplus \) for the envelope). The simulation stopped because the distance between the embryos became smaller than 3.5 mutual Hill radii. When two embryos are too close, their mutual gravitational perturbation may lead to encounters or collisions between them.

The time evolution of the radial profiles for the surface density of planetesimals of \( r_p = 100 \) km and \( r_p = 25 \) km (which are the two sizes that most contribute to the total planetesimal accretion rate, see Fig. 11, where the 25 km is the size of the fragments that contribute most) for the embryo located at 5 au are very similar (Fig. 16). Therefore, we do not expect a significant difference in the formation of this embryo. In Fig. 17 we plot the time evolution of the core mass for both embryos compared with the isolated embryo located at 5 au. We do not find a difference in the formation of the embryo located at 5 au between isolated and the simultaneous formation with an outer embryo, at least for the profile of the disk we analyzed here.

5. Conclusions

Employing the Boulder code, Morbidelli et al. (2009) found that the present size frequency distribution of bodies in the asteroid belt can be reproduced starting with an initial population of large planetesimals with sizes of between 100–1000 km. An initial population of large planetesimals is suggested by the works of Johansen et al. (2007), Cuzzi et al. (2008, 2010), and Youdin (2011). However, Fortier et al. (2009) demonstrated that the formation of massive cores able to achieve the critical mass to start the gaseous runaway phase, starting from large planetesimals, requires several million years, even for massive disks.

We studied the role of planetesimal fragmentation on giant planet formation. We developed a model for planetesimal fragmentation based on the Boulder code and incorporated it in our model of giant planet formation (Guilera et al. 2010, 2011), so that the planetesimal population evolved by planet accretion, migration, and fragmentation. We numerically studied how planetesimal fragmentation modified the formation of an embryo located at 5 au for a wide range of disk masses and planetesimal sizes.

We considered that initially all the solid mass of the system is deposited in planetesimals of radius \( r_p^{\text{max}} \), and that the mass...
loss in collisions is distributed by a power-law mass distribution between the largest fragment and the smallest size bin. The exponent of this power-law mass distribution was calculated by the model. We found that this exponent is generally larger than 2, so most of the mass is distributed in fragments smaller than 1 cm, which is the smallest size we considered for accretion. For this reason, most of the mass produced by the collisions was lost and fragments did not significantly contribute to the embryo growth.

We found that planetesimal fragmentation inhibits planet formation. Only for large planetesimals ($r_{\text{p}} = 100$ km), the mass of the embryo was larger than $1 M_\oplus$ for high-mass disks, but for all cases the core did not achieve the critical mass. However, if most of the mass loss in collisions was distributed in larger fragments, that is, when the exponent of the power-law mass distribution was lower than 2, we found that planetesimal fragmentation favored the relatively rapid formation of a massive core (larger than $10 M_\oplus$), as previously reported (Kobayashi et al. 2011; Ormel & Kobayashi 2012). The accretion of fragments between $\sim 100$ m and $\sim 25$ km increments the total planetesimal accretion rate, but this total accretion rate is always governed by the accretion of planetesimals of $r_{\text{p}} = 100$ km. For this case, we also analyzed whether the presence of an outer embryo modified the formation of an inner one. For this, we calculated the in situ simultaneous formation of two embryos located at 5 au and 6 au. In particular, we analyzed whether the fragment migration produced by the outer embryo affected the formation of the inner one. We did not find a difference between isolated and simultaneous formation for the embryo located at 5 au. But in this case, at $\sim 2.5$ Myr, the separation between the embryos became smaller than 0.5 mutual Hill radii, therefore the simulation was stopped. Possible mergers between massive embryos may lead to a rapid formation of massive cores.

On the other hand, Weidenschilling (2011) showed that the present size distribution observed in the asteroid belt can be also reproduced starting from planetesimals with a radius of $\sim 0.1$ km. Kenyon & Bromley (2012) concluded that the size distribution of the transneptunian objects can be reproduced starting from a massive disk composed of relative small planetesimals ($r_{\text{p}} < 10$ km). However, for such small planetesimals, collisions quickly become highly catastrophic because of the low values for the specific impact energy. This means that targets are quickly pulverized and the total surface density of solids drops drastically. When the mass loss in collisions is distributed in smaller fragments, as the Boulder code predicts, planet formation is completely inhibited. When the mass loss in collisions is distributed in larger fragments, fragments of $\sim 1$ m ultimately govern the total planetesimal accretion rate. However, for these small fragments collisions result in accretion. Therefore, we repeated the simulations (for $r_{\text{p}}^{\text{max}} = 0.1$, 100 km) for the case where the mass loss in collisions is deposited in larger fragments, but incorporated planetesimal coagulation. As we expected, planetesimal coagulation did not modify the process of planetary formation for $r_{\text{p}}^{\text{max}} = 100$ km, because small fragments contribute only negligibly to the total planetesimal accretion rate. On the other hand, planetesimal coagulation significantly modified the results for $r_{\text{p}}^{\text{max}} = 0.1$ km, inhibiting the formation of a massive core. We will analyze this case in detail, developing a full planetesimal collisional model in a future work.

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