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General scaling limitations of ground-plane and isolated-object cloaks

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We prove that, for arbitrary three-dimensional transformation-based invisibility cloaking of an object above a ground plane or of isolated objects, there are practical constraints that increase with the object size. In particular, we show that the cloak thickness must scale proportionally to the thickness of the object being cloaked, assuming bounded refractive indices, and that absorption discrepancies and other imperfections must scale inversely with the object thickness. For isolated objects, we also show that bounded refractive indices imply a lower bound on the effective cross section.

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1. INTRODUCTION

Invisibility cloaking refers to the idea of making an object appear invisible, or at least greatly reducing its scattering cross section, by surrounding it with appropriate materials, and has attracted extensive popular and research interest following a theoretical proposal by Pendry [1]. Unfortunately, cloaking of isolated objects turns out to be severely restricted, in that speed-of-light or causality constraints intrinsically limit perfect cloaking to an infinitesimal bandwidth [1,2]. An alternative with no intrinsic bandwidth limitations is ground-plane cloaking [3], in which the goal is to make an object sitting on a reflective surface indistinguishable from the bare surface. In this paper, however, we show that both forms of cloaking are subject to practical difficulties that increase as the size of the cloaked object grows, generalizing a simple one-dimensional argument that we previously applied to ground-plane cloaking [4]. We focus most of our attention on the case of ground-plane cloaking, which seems to be the most practical possibility, but we then show that a very similar analysis applies to cloaking of isolated objects. In both cases, our key starting point is the assumption that the attainable refractive indices are bounded, in which case we show that the cloak thickness must scale with the object size and hence any losses per unit volume (including both absorption and scattering from imperfections) must scale inversely with the object size. It has been suggested that gain could be used to compensate for absorption loss (but not other imperfections) in the cloak [5], but a corollary of our results is that such compensation must become increasingly exact as the object diameter increases.

Although there have been several experimental demonstrations of ground-plane cloaking [6–15], as well as theoretical investigation of several variations on the underlying idea [16–19], we previously argued using a simple one-dimensional model system that the difficulty of ground-plane cloaking must increase proportionally to the thickness of the object being cloaked [4]. In this paper, we generalize that simple argument to a rigorous proof for arbitrary cloaking transformations in three dimensions. We demonstrate that the thickness of the cloak must scale proportionally to the size of the object, given bounded material properties. (Previously, we arrived at a similar conclusion in one dimension from the delay–bandwidth product [4], but here our result is derived independent of the bandwidth, although the bounds on the indices ultimately depend on the bandwidth.) From this, if one requires a bounded reduction in the scattering cross section, it follows that the loss (due to absorption or other imperfections) per unit volume must scale inversely with the object thickness, and we quantify this scaling more precisely in the case of absorption loss and scattering from disorder. For a lossy ambient medium such as a fluid (with an observer close enough to see the object), the losses of the cloak must asymptotically approach those of the ambient medium, and defects or roughness that scatter light must still vanish, so there is still a sensitivity to imperfections. (On the other hand, ambient fluids have the advantage that it is easier to index match them with a solid cloak without resorting to complicated metamaterial microstructures susceptible to manufacturing imperfections. This helped recent authors, using natural birefringent materials, to demonstrate cloaking effects at visible wavelengths for cm-scale structures [13,14].) In addition to scattering and loss, systematic imperfections (such as an overall shift in the indices or an overall neglect of anisotropy in favor of approximate isotropic materials [3]) must also vanish inversely with object thickness, since such systematic errors produce a worst-case phase shift in the reflected field proportional to the imperfection and the thickness of the cloak (the path length, which scales with the object). (For oblique angles of incidence, such phase shifts can cause a lateral shift in the reflected beam [18], analogous to a Goos–Hänchen shift.)

Cloaking of isolated objects, on the other hand, is already subject to severe bandwidth restrictions: Perfect cloaking in vacuum over a nonzero bandwidth would imply rays traveling at greater than the speed of light around the object [1], which can be interpreted as a causality violation [2]. Nevertheless, the isolated cloaking problem is of considerable fundamental theoretical interest [5,20–42], and several groups have demonstrated single-frequency cloaking of small objects in experiments [43–46]. Although several theoretical simulations included absorption loss [5,20,23,24,37,42,47,48], a tradeoff between absorption tolerance and object size was suggested in Ref. [31]. Based on these numerical experiments [31] and on comparison with ground-plane cloaking, we suggested [4] that even single-frequency isolated-object cloaking must become...
increasingly difficult as the cloaked object becomes bigger, and in this paper we are able to prove that result analytically. In particular, assuming that the attainable refractive indices are bounded above, we show that the cloak thickness must scale proportionally to the object diameter and any cloak losses (absorption or imperfections) must scale inversely with diameter. (Experimentally, the group to claim isolated cloaking of an object more than wavelength scale in diameter [49] did not do so in vacuum, but rather within a parallel-plate wave guide system free of complex microstructures and hence with very low intrinsic losses.) Another limitation on isolated-object cloaking is that the singularity of the cloaking transformation (which maps an object to a single point) corresponds to very extreme material responses (e.g., vanishing effective indices) at the inner surface of a perfect cloak [50]. Here, independent of our results on losses, we show that if the attainable refractive indices are bounded below, then the cloak is necessarily imperfect: It reduces the object cross section by a bounded fraction, even for otherwise lossless and perfect materials. (Previous authors showed that the bounded reduction in the cross section obtained from a nonsingular cloaking transformation could be partially defeated by resonant inclusions in the object [51], but this problem seems avoidable by a cloak with a reflective inner surface that masks the nature of the cloaked object.) Both of these diameter-scaling limitations are apparent if one looks at explicit examples of cloaking transformations, such as Pendry’s original linear scaling [1], but our results differ from such observations in that they hold in general for any arbitrary transformation, including transformations that are not spherically symmetrical.

II. GROUND-PLANE CLOAKING

Consider an object in a volume $V_0$ on a reflective ground plane, surrounded by a homogeneous isotropic ambient medium with permittivity $\varepsilon_a$ and permeability $\mu_a$. This object is cloaked by choosing the materials $\varepsilon$ and $\mu$ in a surrounding volume $V_c$ to mimic a coordinate transformation, with Jacobian $\mathcal{J}$, mapping the physical space $X$ to a virtual space $X'$ in which the object is absent ($\mathcal{J}_{ij} = \partial x'_i / \partial x_j$), as shown in Fig. 1. This is achieved by $\varepsilon = \varepsilon_a \mathcal{J} \mathcal{J}^T / \det \mathcal{J}$ and $\mu = \mu_a \mathcal{J} \mathcal{J}^T / \det \mathcal{J}$ (for isotropic $\varepsilon_a, \mu_a$) [1]. (The surface of the object in $X$ is mapped to the ground plane in $X'$, and so the inner surface of the cloak must be reflective like the ground plane.) We derive the limitations of cloaking under the following two practical requirements:

(i) The attainable refractive index contrast $\sqrt{\varepsilon \mu \varepsilon_a \mu_a}$ (the eigenvalues of $\mathcal{J} \mathcal{J}^T / \det \mathcal{J}$) is bounded above by $B$ and below by $b$.

(ii) The scattering cross section (nonzero due to imperfections in the cloak) for any incident wave is bounded above by some fraction $f$ of the geometric cross section $S_g$.

Given these two constraints, we derive the following relations between the difficulty of cloaking and the size of the object to be cloaked:

(i) The thickness of the cloak must scale with the object thickness (divided by $B$).

(ii) The allowed imperfections (e.g., disorder or absorption) must scale at most inversely with the object thickness.

A. Cloak thickness

The volume $V_c$ is given by $\int_{V_c} |\det \mathcal{J}| dx' dy' dz'$, and therefore constraints on $V_c / V_0$ immediately follow from two facts. First, $|\det \mathcal{J}|$ can be bounded due to the bound $B$ on the index change above. Second, an even tighter bound follows from the fact that the outer surface $S_c$ of the cloak is invariant under the coordinate transformation. In particular, defining $\mathcal{J}_x$ and $\mathcal{J}_y$, as the first two columns of $\mathcal{J}$ and denoting singular values of $\mathcal{J}$ by $\sigma_i (\sigma_i^2$ are eigenvalues of $\mathcal{J} \mathcal{J}^T$ [52]), referring to the cross sections $A(z')$ defined in Fig. 2, we show the following sequence of bounds:

\[
V_c = \iiint_{V_c} |\det \mathcal{J}| dx' dy' dz' \geq (\min \sigma_i) \int_{z_0}^{z_0} \int \mathcal{J}_x \times \mathcal{J}_y |dx' dy'| \geq (\min \sigma_i) \int_{z_0}^{z_0} A(z') dz' \geq (\min \sigma_i) \int_{z_0}^{z_0} A'(z') dz' = (\min \sigma_i) V_c' \geq V_c' / B.
\] (1)

Step (2) follows from $|\det \mathcal{J}|| = \|\mathcal{J}^T (\mathcal{J}_x \times \mathcal{J}_y)\|$, and $\|\mathcal{J}^T u\| \geq (\min \sigma_i) \|u\|$ for any vector $u$ [52]. The $x'y'$ integral in line in Eq. (1b) is simply the area $A(z')$ that $A'(z')$ maps to, and $A(z') \geq A'(z')$ because the outer boundary (solid dots in

FIG. 1. (Color online) Schematic of a general cloaking problem: An object in a volume $V_0$, sitting on a reflective ground is cloaked by choosing the materials $\varepsilon$ and $\mu$ in a surrounding volume $V_c$ to mimic a coordinate transformation, with Jacobian $\mathcal{J}$, mapping the physical space $X$ to a virtual space $X'$ in which the object is absent ($\mathcal{J}_{ij} = \partial x'_i / \partial x_j$), as shown in Fig. 1. This is achieved by $\varepsilon = \varepsilon_a \mathcal{J} \mathcal{J}^T / \det \mathcal{J}$ and $\mu = \mu_a \mathcal{J} \mathcal{J}^T / \det \mathcal{J}$ (for isotropic $\varepsilon_a, \mu_a$) [1]. (The surface of the object in $X$ is mapped to the ground plane in $X'$, and so the inner surface of the cloak must be reflective like the ground plane.) We derive the limitations of cloaking under the following two practical requirements:

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A. Cloak thickness

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FIG. 2. (Color online) The cloaked volume $V_c'$ in virtual space can be divided into flat cross sections $A'(z')$ for each $z' \in [0, z_0]$. These are mapped to curved surfaces $A(z')$ in $X$. The invariance of the outer surface $S_c$ means that the boundaries (solid dots) of $A(z')$ and $A'(z')$ coincide, and hence $A(z') \geq A'(z')$. 

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Fig. 2) is identical in and for the flat surface to the minimal area for this boundary. Finally, step Eq. (1e) stems from elementary properties of singular values; the eigenvalues of $\mathcal{J}^T / \det \mathcal{J}$ are simply $b \leq \sigma_1^2 / \sigma_1 \sigma_2 \sigma_3 \leq B$ [52], and algebraic manipulation of this inequality yields $B^{-1} \leq \sigma_i \leq b^{-1}$. Thus, we have shown that $V_i \geq V_c / B$, but since the outer surface $\mathcal{S}$ is invariant it follows that the thickness of the cloak must scale proportionally to the object thickness divided by $B$.

### B. Cloak losses

We will analyze losses due to imperfections via perturbation theory: We first obtain the fields in a perfect cloak ($\varepsilon$ and $\mu$ given exactly by the transformation law), and then consider the lowest-order absorption or scattering in the presence of small imperfections. Suppose the object is illuminated by an incident plane wave with electric-field amplitude $E_0$, which means that the total field (incident plus reflected) in the ambient medium and in $V_c$ has amplitude $\leq 2E_0$. For a perfect cloak, the fields in the cloak $V_c$ are simply given by $(\mathcal{J}^T)^{-1}$ multiplied by the reflected plane wave in virtual space $X'$ [1], and hence the field amplitude $E$ in the cloak is $\leq 2E_0 / \min \sigma_i \leq 2E_0 B$ (using the bounds on the singular values $\sigma_i$ from above). We must consider the worst-case losses for arbitrary incident waves; since this is bounded below by the loss from any particular incident wave, it is convenient to consider glancing-angle $p$-polarized plane waves where the field is a constant $E_0$ everywhere in $V_c$ and $E \geq E_0 b$ in the cloak (from the bound on max $\sigma_i$).

#### 1. Absorption

An absorption is a small deviation $\Delta \varepsilon$ in the imaginary part of $\varepsilon$ compared with $\varepsilon_0 \mathcal{J}^T / \det \mathcal{J}$. (Similarly for $\mu$, but it suffices to consider electric absorption here.) This gives a change $\frac{\varepsilon}{\omega} \varepsilon \mathcal{E} \Delta \varepsilon \varepsilon \mathcal{E}$ in the time-average absorbed power at a frequency $\omega$ [53]. To lowest order in $\Delta \varepsilon$, we can take $\mathcal{E}$ to be the field in the perfect cloak, and suppose for simplicity that the absorption is isotropic ($\Delta \varepsilon \varepsilon$ is a scalar), and therefore the worst-case change in the absorbed power is $\geq \frac{\varepsilon}{\omega} \varepsilon B^2 \frac{1}{V_c} \Delta \varepsilon \varepsilon$. Combined with our initial requirement on the scattering cross section, the change in the absorbed power must be $\leq f s_c b_0$ where $b_0 = \varepsilon_0 B^2 \sqrt{\varepsilon_0 / \mu_0}$ is the incident intensity, and we obtain the following bound:

$$\text{mean } \Delta \varepsilon \varepsilon \leq \frac{f \varepsilon_0 B^2 s_c}{4 \alpha B^2} \frac{\varepsilon_0}{V_c} \leq \frac{f \varepsilon_0 B^2 s_c}{4 \alpha B^2} \frac{\varepsilon_0}{V_c} \leq \frac{f \varepsilon_0 B^2 s_c}{4 \alpha B^2} \frac{\varepsilon_0}{V_c}$$

(2)

(using the $V_c$ inequality above). The ratio $s_c / V_c$ scales as $1 / \text{thickness}$, so this means that the mean $\Delta \varepsilon \varepsilon$ scales inversely with the thickness of the object to be cloaked. (The $1 / \omega$ dependence means that this can be interpreted as a bound on the conductivity.)

Equation (2) is a necessary condition on the loss, but is too optimistic to be a sufficient condition. For example, suppose that the ambient medium is lossy, so that $\Delta \varepsilon \varepsilon$ can have either sign depending on whether the cloak is more or less lossy than the ambient medium (or alternatively, $\Delta \varepsilon \varepsilon < 0$ could come from gain). Equation (2) is satisfied if the more lossy and less lossy regions of the cloak average to zero, but in fact this will not result in a zero scattering cross section for arbitrary incident waves. For example, a narrow incident beam (rather than a plane wave) will interrogate the loss in some regions of the cloak more than others, and even a plane wave at a different angle will create a standing-wave pattern that has higher field intensity in some regions—these cases, any delicate cancellation in the absorption will be destroyed. Instead, we can derive a sufficient condition on the loss by bounding the change in absorption above rather than below. In particular, $\frac{\varepsilon}{\omega} \varepsilon \mathcal{E} \Delta \varepsilon \varepsilon \mathcal{E} \leq \frac{f \varepsilon_0 B^2 s_c}{4 \alpha B^2} \frac{\varepsilon_0}{V_c} \leq \frac{f \varepsilon_0 B^2 s_c}{4 \alpha B^2} \frac{\varepsilon_0}{V_c}$

This is, perhaps, stronger than strictly necessary; we conjecture that a weaker sufficient condition exists that replaces max $\Delta \varepsilon \varepsilon$ by an average of $\Delta \varepsilon \varepsilon$. (5) is satisfied if the more lossy and less lossy regions of the cloak average to zero, but in fact this

#### 2. Random imperfections

Small random imperfections can be thought of as scatterers distributed randomly throughout $V_c$ with some polarizability $\alpha$ (dipole moment $p = \alpha \mathcal{E}$) [54]. For example, a small change $\Delta \varepsilon \varepsilon$ in a small region $\delta V$ corresponds to $\alpha = \Delta \varepsilon \varepsilon \delta V$. Computing $\alpha$ for surface roughness is more involved, but is conceptually similar [54]. If these imperfections are uncorrelated, then on average the scattered power is simply the mean dipole radiation of each scatterer multiplied by the density $d_\alpha$ of scatterers (the radiation from different scatterers is incoherent, so interference terms average to zero) [53]. This radiation is most easily computed by transforming each scatterer back to virtual space $X'$, where the polarizability is $\alpha' = (\mathcal{J}^T)^{-1} \alpha \mathcal{J}^T \alpha^{-1}$ det $\mathcal{J}$, so that $|\alpha'| \geq |\alpha| / B$ from above. The radiated power of a point source in virtual space (homogeneous above a ground plane) varies with distance and orientation above the ground plane due to the image dipole source below the ground plane, but the worst-case (over all incident waves) average (over all scatterer positions) scattered power is proportional (with a constant factor of order unity) to the radiated power of a point source in the homogeneous medium, $(\alpha' E_0)^2 \alpha' B^2 \sqrt{\varepsilon_0 / \mu_0} / 12 \pi$ [53]. Multiplying this by the number $d_\alpha V_c$ of scatterers and comparing to the requirement on the worst-case loss, one finds that $\alpha'^2 d_\alpha$ is bounded above by a quantity proportional to $B^3 f s_c / V_c'$, which again scales inversely with the thickness of the cloaked object. Note that, while gain could conceivably be used to compensate for absorption loss, it does not seem applicable to scattering from imperfections.

### III. Cloaking of isolated objects

Consider the problem of cloaking an isolated object of volume $V_o$ in a homogeneous isotropic ambient medium using a transformation-based cloak of volume $V_c$ surrounding the object. As above, the cloak material is determined from...
which demonstrates these scalings: an adaptation of Pendry’s transformation [1]. However, we will begin with a specific illustrative example for ground-plane cloaking, above: Cloak thickness scales with object thickness divided by $R$. Below, we will generalize this thickness scaling to arbitrary nonspherical cloaks.

B. General limits on cloaking cross section

In this section, we show in general that the $S_o$, the effective surface area of the cloaked object, must be $\propto S_o b^2$. That is, if $b > 0$, then the area $S_o$ as seen by an observer must scale proportionally to the object area, so that the cross section is reduced by a bounded factor. (For objects much larger than the wavelength, the scattering cross section is proportional to the geometric cross section $S_o$.) From the spherical example above, it might be possible to derive an even tighter bound on $S_o$, but the $S_o b^2$ bound here is sufficient to demonstrate the scaling with $S_o$. Our basic approach is to write down $S_o$ in terms of an integral over $S_o$, and then to bound the integral

$$S_o = \iint_{S_o} |J_u \times J_v| dA'(u', v'),$$

where $(u, v) \leftrightarrow (u', v')$ is some coordinate system of the surfaces, $dA'(u', v')$ is the area element on $S_o$, and $J_u$ and $J_v$ are columns of the Jacobian matrix as in Sec. II A. We must then bound $|J_u \times J_v|$ similar to our previous analysis, but this is conceptually complicated somewhat by the fact that the coordinate system here is non-Cartesian, meaning that $J$ no longer has the same bounds. To circumvent this difficulty, we apply a standard trick from differential geometry [55]: We cover the surface $S_o$ with small overlapping neighborhoods $N_i$ (a locally finite open covering [55]) where the surface is locally approximately flat, in which case we can define a local Cartesian coordinate system and use the Cartesian bounds on $|J|$ (ultimately taking the limit of infinitesimal neighborhoods so that the local flatness becomes exact). To combine these local results, one uses a partition of unity [55]: a set of bump functions $p_k(u', v')$ (nonzero only on $N_i$) such that $\sum_k p_k = 1$ on $S_o$. Thus, we obtain

$$S_o = \sum_k \iint_{N_i} |J_u \times J_v| p_k dA'.$$

Now, in the limit of infinitesimal neighborhoods $N_i$, we can freely treat each integral as being over a local Cartesian coordinate system, in which case $J$ is the ordinary Cartesian Jacobian matrix. Now, we use two facts. First, we know $|\det J| = |\sigma_1 \sigma_2 \sigma_3| \leq (\max \sigma_i)^2 (\min \sigma_i)^2$. Second, similar to Sec. II A, $|\det J| = \|J^T(J_u \times J_v)\| \geq (\min \sigma_i)|J_u \times J_v|$ from general properties of singular values [52]. Combining these two inequalities, we find $|J_u \times J_v| \leq (\max \sigma_i)^2 = 1/b^2$. Substituting this bound into the integral above, we finally obtain

$$S_o \leq \sum_k \iint_{N_i} p_k dA' / b^2$$

$$= \iint_{S_o} (\sum_k p_k) dA' / b^2 = \iint_{S_o} (1) dA' / b^2$$

$$= S_o / b^2.$$
the desired inequality. (Note that if the object contains corners where $S'_0$ is not locally flat, that does not affect this analysis since those corner regions have zero measure in the integral. The bounds on $J$ mean that corners in $S_0$ must be mapped to corners in $S'_0$ and vice versa, and the integrand is finite.)

We suspect that a tighter bound, proportional to $b$ instead of $b^2$, can be proven by taking into account the fact that the coordinate transformation must leave $S_0$ invariant. In the spherically symmetrical example above, the purely radial nature of the coordinate transformation caused it to have at most one factor of $1/b$ in $|\det J|$ (only one eigenvalue of $\varepsilon$ and $\mu$ vanishes for $R'_1 = 0$) and not two, leading to an $S_0 \sim S'_0/b$ dependence. A similar single factor of $b$ in the general case would give a 1/b scaling in the inequalities above by replacing $(\max \sigma_i)^2$ with $\max \sigma_i$.

C. General scaling of cloak thickness and loss

A simple linear scaling of the cloak volume, as mentioned at the beginning of Sec. II A, follows immediately from the bounds on $|\det J|$:

$$V_c = \iiint_{V_c'} |\det J| \, dx' \, dy' \, dz' \geq (\min \sigma_i)^3 V'_c \geq V'_c / B^3$$

As for ground-plane cloaking, we can define a mean thickness $V_c/S_c$ of the cloak. For a useful cloak, $V'_o \ll V_o$ and hence $V'_c \approx V_c + V'_o$. Thus, $V'_c/S_c = V'_c/S_c$ is a mean total (cloak plus object) diameter. Therefore, we have just demonstrated the inequality $V'_c/S_c \geq (V'_o/S'_o)^3 / B^3$ (to lowest order in $V'_o / V'_c$), which means that the mean cloak thickness $V'_c/S_c$ must scale proportionally to the object diameter.

The spherical Pendry example above leads us to suspect that a tighter bound $\sim 1/B$ can be derived. Similar to the ground-plane example in Sec. II A, we expect that the key point is that we have not yet taken into account the constraint $S'_c = S_o$ on the cloaking transformation. However, our main goal here is to demonstrate the scaling of cloak thickness with object thickness, not to fine-tune the constant factor.

Now that we know that cloak thickness must scale with object thickness, an analysis of losses similar to that in the ground-plane case above must apply. As the object becomes thicker, incident rays travel for a longer distance through the cloak, and hence for a fixed tolerance on the cross section the losses per unit distance must shrink proportionally to the object diameter. Hence absorption losses (or rather, the difference between the cloak absorption in $X'$ and the absorption of the ambient medium) and imperfections must scale inversely with the diameter. As we pointed out in our previous paper [4], precisely such an inverse scaling of absorption tolerance with diameter has been demonstrated numerically [50] for spherical cloaks, and our work now shows that this relationship is general. As suggested by some authors [5], gain could be used to compensate for absorption (but not disorder), but as discussed above our results imply that this compensation must become more and more exact as the object diameter increases.

For example, let us explicitly consider absorption imperfections for the idealized case of $b = 0$, that is, suppose we are able to map $V_o$ to a single point $V'_o = 0$, but have a finite $B$ and are still concerned with imperfect materials. In this case, an incident plane wave of amplitude $E_0$ corresponds to a plane wave of constant amplitude in the cloak for perfect materials, or to lowest order in the imperfections for imperfect materials. Then, similar to our analysis in Sec. II B 1, the change in absorbed power is bounded below by $\frac{\sigma_i}{\varepsilon} \int V_c |\Delta \varepsilon / (\max \sigma_i)^2|$. Since we require that this change also be bounded above by the incident intensity ($\sim E_0^2$) multiplied by some fraction $f$ of the geometric cross section $s_o$, we obtain a necessary condition on the absorption imperfection as in Sec. II B 1. In particular it follows that an averaged absorption imperfection $\int V_c \Delta \varepsilon / (\max \sigma_i)^2$ must scale proportionally to $s_o / V_c \approx s_o B^3 / V'_c$, where $V'_c/s_o$ is proportional to the diameter. In Sec. II B 1, we further used $\max \sigma_i \leq 1/b$ and pulled out a $b^2$ factor, but that is not appropriate when $b = 0$, so instead we must leave a $1/(\max \sigma_i)^2$ weight factor (which is only zero at the inner surface of the cloak) in the average of $\Delta \varepsilon$. As in Sec. II B 1, this is not a sufficient condition because the observer need not use plane waves—for interrogating the cloak with a focused beam, a stronger condition must apply, in which $\Delta \varepsilon \propto b$ increases. If $b > 0$, this analysis is only slightly modified in principle (although the precise expression becomes much more complicated): The small scattered field (assuming $V'_o \ll V_o$) from the nonzero $V'_o > 0$ modifies the field in $X'$ by a small amount over most of $V'_c$ (except immediately adjacent to $V'_o$), which should only change the proportionality of the $\Delta \varepsilon$ scaling by a small factor.

IV. CONCLUSIONS

Generalizing our previous work [4], these scaling laws point to an inherent practical difficulty (though not a mathematical impossibility) in scaling experimental cloaking of small objects to larger ones. Furthermore, we showed that very similar analysis can be applied to cloaking of isolated objects—bounded index contrasts will imply a bounded reduction in the scattering cross section, a cloak thickness proportional to the object diameter, and imperfection tolerances that shrink with the object diameter (a scaling we already observed numerically [4]). It might be possible to further generalize the results in this paper to cloaks that are not derived from coordinate transformations (similar to the generality of our one-dimensional analysis [4]). However, the most serious constraint on isolated-object cloaking seems to be the bandwidth, which must be zero for perfect cloaking [1,2]. Clearly, if perfect cloaking is possible (theoretically) at a single frequency, then imperfect cloaking (reduction of the cross section by a given factor) must persist over a nonzero bandwidth, and an interesting open problem is to prove how the bandwidth of such imperfect isolated-object cloaking must scale with the object diameter from causality constraints.

An alternative direction is to consider relaxations of the cloaking problem that might prove more practical. In particular, it would be valuable to make precise the intuition that the cloaking problem becomes easier if the incident waves are restricted (e.g., to plane waves from a certain range of angles) and/or the observer is limited (e.g., only scattered waves at certain angles are visible, or only amplitude...
but not phase can be detected), since this is arguably the situation in most experiments. (For example, current stealth aircraft are designed in the radar regime mainly to reduce back-scattering only [56].) Another interesting possibility is to consider cloaking that attempts to make one object look like a different object of a similar size rather than making it invisible (although this approach is similar in spirit to ground-plane cloaking and may have similar limitations).

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