Statistical Beamforming Techniques for Power Domain NOMA System

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Abstract: Power-domain non-orthogonal multiple access (NOMA) assigns different power levels for near and far users in order to discriminate their signals by employing successive interference cancellation (SIC) at the near user. In this context, multiple-input-single-output NOMA (MISO-NOMA), where the base station (BS) is equipped with multiple antennas while each mobile user has a single antenna receiver, is shown to have a better overall performance by using the knowledge of instantaneous channel state information (CSI). However, this requires prior estimation of CSI using pilot transmission, which increases the transmission overhead. Moreover, its performance is severely degraded in the presence of CSI estimation errors. In this work, we provide statistical beamforming solutions for downlink power-domain NOMA that utilize only knowledge of statistical CSI, thus reducing the transmission overhead significantly. First, we derive the outage probabilities for both near and far users in the multi-user NOMA system without imposing strong assumptions, such as Gaussian or Chi-square distribution. This is done by employing the exact characterization of the ratio of indefinite quadratic form (IQF). Second, this work proposes two techniques to obtain the optimal solution for beam vectors which rely on the derived outage probabilities. Specifically, these two methods are based on (1) minimization of total beam power while constraining the outage probabilities to the QoS threshold, and (2) minimization of outage probabilities while constraining the total beam power. These proposed methods are non-convex function of beam vectors and, hence, are solved using numerical optimization via sequential quadratic programming (SQP). Since the proposed methods do not require pilot transmission for channel estimation, they inherit better spectral efficiency. Our results validate the theoretical findings and prove the supremacy of the proposed method.

Keywords: non-orthogonal multiple access; power domain NOMA; beamforming; outage probability

1. Introduction

Non-orthogonal multiple access (NOMA) constitutes a spectrum-efficient solution that can accommodate the huge data traffic of 5G networks [1,2]. NOMA techniques are typically integrated with other schemes, such as millimeter wave, beamforming and massive MIMO [3]. In contrast to the classical orthogonal multiple access (OMA) techniques, such as frequency division multiple access, NOMA has the capability of serving multiple users using the same (time, frequency, and code) resource blocks. This can be attained, in power-domain NOMA, by superimposing users’ streams into one signal while employing the successive interference cancellation (SIC) at the receivers [1,4,5]. The strong user, also known as the near user, decodes the weak user signal first and then decodes its own. Only a small amount of power has to be allocated to the strong user to give it a high rate while delivering near-optimal performance to the weak user [4,5].

Motivated by the spectral efficiency enhancement provided by NOMA schemes, several combined NOMA-aided beamforming multiple-input multiple-output (MIMO)
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schemes have been proposed recently [1,4,6–9]. However, designing efficient combined schemes includes several challenges, such as power allocations, user coordination, physical layer security and user clustering/selection [2,4]. For example, in [1], a joint user selection with optimized beamforming scheme was proposed for mmWave communication. Additionally, a combined game-based user clustering strategy and optimized beamforming techniques were suggested in [4]. Similarly, NOMA power allocation using the Glicksberg game was proposed in [6]. In [8], the beamforming optimization was carried out using the instantaneous channel state information (CSI). In [9], a scheme for joint beamforming and artificial noise optimization for MISO-NOMA cognitive radio was proposed that promises improved physical layer security. Meanwhile, the works in [10–12] addressed various issues in SIC for power domain NOMA.

The work in [13] discussed why and when NOMA is inefficient in multi-antenna settings by comparing its performance with multi-user linear precoding (MU–LP) and rate-splitting multiple access (RSMA). Although this work provides theoretical and numerical proofs for the inefficiency of NOMA in a multi-antenna scenario, these proofs are valid for specific scenarios. For example, MISO NOMA (here, \(G\) stands for the number of users in NOMA user groups, while \(M\) and \(K\) denote the number of antenna elements and total number of users, respectively) with \(G = 1\) and \(G = K/2\) can outperform or achieve the same performance as MU–LP when \(M < K\) in terms of max-min fair (MMF) multiplexing gain and has inferior performance for \(M > K\). Thus, MISO NOMA is still efficient for \(M < K\). Similarly, their numerical results provided in Figures 10 and 11 of [13] for sum rate and MMF, respectively, show that the performance of MISO NOMA has inferior performance than that of the RS only in the case of larger SNR values. On the other hand, their performance is almost identical for low SNR values. Thus, the utilization of MISO NOMA is still applicable for practical scenarios where SNR values are small. Finally, all the comparisons made in [13] are based on sum rate and MMF only. Moreover, their work is based on CSI estimation (whether perfect or imperfect), which requires pilot transmission. In contrast, we propose a blind technique without requiring any pilot transmission.

In contrast to the pilot-based approaches, we propose statistical beamforming solutions for the downlink power-domain NOMA which do not require CSI estimation, thereby reducing the transmission overhead, which eventually enhances the spectral efficiency. For this purpose, closed form expression for the outage probabilities for both near and far users in the NOMA system is derived using the characterization of IQF [14]. The optimum beam vectors are then obtained by two approaches: (1) by minimizing the total beam power while constraining the outage probabilities to the QoS threshold, and (2) by minimizing the outage probabilities while constraining the total beam power. Thus, our proposed system can be used for low-latency communication in MTC (thanks to the no-CSI feedback as well as a low outage probability).

**Paper Contributions**

Main contributions of our work can be summarized as follows:

(a) Unlike the existing works which employ approximate characterization to derive outage probabilities, such as Gaussian or Chi-square distribution assumption, this work derives closed form expression for the outage probabilities for both near and far users in the multi-user NOMA system without imposing such assumptions. To elaborate further, we use the exact characterization of the ratio of IQF of the form (the notation \(||x||^2_A\) represents the weighted norm defined as \(||x||^2_A = x^H A x\) \(\frac{||x||^2_B}{||x||^2_A + \sigma^2}\))

(b) This work proposes two techniques to obtain an optimal solution for beam vectors which rely on the derived outage probabilities. More precisely, these techniques are as follows:
(i) To obtain the optimal beam vectors by minimizing the total beam power while constraining the outage probabilities to the QoS threshold.

(ii) To obtain the optimal beam vectors by minimizing the outage probabilities while constraining the total beam power.

The proposed methods (i) and (ii) are non-convex functions of beam vectors. Thus, we implement numerical optimization methods of SQP [15–17] by evaluating the gradients of the proposed objective function.

(c) It is important to highlight that the proposed methods require only statistical CSI in contrast to the existing works in [5,18], which employ the knowledge of instantaneous CSI. Thus, the proposed methods do not require pilot transmission for channel estimation and hence, can provide better spectral efficiency in contrast to the existing methods, which need pilot transmission.

2. Materials and Methods

2.1. System Model

Without loss of generality, we consider a cellular-based downlink multiuser transmission of Figure 1 in which the M-element antenna array-aided base station (BS) will transmit its signal to two users, each equipped with a single antenna [1,18]. Moreover, we have considered that there are total K users that are grouped into \( \frac{K}{2} \) number of pairs, where each pair consists of a near user and a far user.

![Figure 1. The downlink beamforming plus superposition code (BF + SC) system model transmission.](image)

The near user from the BS is denoted as NU, while the far user, also known as a cell-edge user, is denoted as FU. Both user signals are superposed using the superposition coding (SC) technique, then transmitted using an optimized beamforming (BF) scheme. Hence, the BS in our NOMA system is capable of serving multiple users simultaneously. Now, consider the \( l^{th} \) pair whose BS (BF + SC) transmitted signal can be written as follows:

\[
 z_l = w_l S_{NU}^l + v_l S_{FU}^l, \tag{1}
\]

where \( S_{NU}^l \) and \( S_{FU}^l \) are near and far user signals in the \( l^{th} \) pair, respectively, and \( w_l \) and \( v_l \) represent, respectively, the beamforming vectors for near and far users in the \( l^{th} \) pair. Thus, the total broadcast signal for the \( L \) pairs will be

\[
 z = \sum_{l=1}^{L} z_l = \sum_{l=1}^{L} w_l S_{NU}^l + \sum_{l=1}^{L} v_l S_{FU}^l, \tag{2}
\]
With the aid of Figure 1, the received signals at both NU and FIU for the \( l \)th pair are given, respectively, by the following:

\[
\begin{align*}
    r_{l}^{NU} &= \mathbf{h}_{l}^{H} \mathbf{z} + n_{l}^{NU} = \sum_{i=1}^{L} \mathbf{h}_{l}^{H} \mathbf{w}_{i} \mathbf{S}_{i}^{NU} + \sum_{i=1}^{L} \mathbf{h}_{l}^{H} \mathbf{v}_{l} \mathbf{S}_{l}^{FIU} + n_{l}^{NU} \\
    r_{l}^{FIU} &= \mathbf{g}_{l}^{H} \mathbf{z} + n_{l}^{FIU} = \sum_{i=1}^{L} \mathbf{g}_{l}^{H} \mathbf{w}_{i} \mathbf{S}_{i}^{NU} + \sum_{i=1}^{L} \mathbf{g}_{l}^{H} \mathbf{v}_{l} \mathbf{S}_{l}^{FIU} + n_{l}^{FIU}
\end{align*}
\]  

(3) 

(4)

where \( \mathbf{h}_{l} \) and \( \mathbf{g}_{l} \) are \( M \times 1 \) channel vectors for the near and far users, respectively, in the \( l \)th pair. These vectors are assumed to be frequency-flat block fading channels. Moreover, \( n_{l}^{NU} \) and \( n_{l}^{FIU} \) are the zero mean additive white Gaussian noises (AWGNs) for the near and the far users, respectively, i.e., \( n_{l}^{NU} \sim \mathcal{C} \mathcal{N}(0, \sigma_{l}^{2,NU}) \) and \( n_{l}^{FIU} \sim \mathcal{C} \mathcal{N}(0, \sigma_{l}^{2,FIU}) \).

In the NOMA system, where generally \( \| \mathbf{h}_{l} \|^{2} \gg \| \mathbf{g}_{l} \|^{2} \), it can be thus assumed that the near user can decode both the near and far users’ data streams of their own pair. However, the far user needs only to decode their pair transmitted sequence. The power allocated to the near user can decode both the near and far users’ data streams of their own pair. However, the far user does not need to decode the far user’s data. Thus, at the near user, SIC is employed to completely remove all the far user’s data from the superimposed received signal. As a result, the near user’s signal is decoded using SINR (denoted by \( \zeta_{l}^{NU} \)). Now, using Equations (3) and (4), the SINR for the near user can be expressed as follows:

\[
\zeta_{l}^{NU} = \frac{\| \mathbf{h}_{l}^{H} \mathbf{v}_{l} \|^{2}}{\sum_{k=1}^{L} \| \mathbf{h}_{l}^{H} \mathbf{w}_{k} \|^{2} + \sum_{k=1,k\neq l}^{L} \| \mathbf{h}_{l}^{H} \mathbf{v}_{k} \|^{2} + \sigma_{l,NU}^{2}}
\]  

(5)

At the far user, the \( S_{l}^{NU} \) (from all pairs) and the \( S_{l}^{FIU} \) (from all pairs excluding the \( l \)th pair) are considered interference terms but these may not be decoded, as their signal powers are severely faded [5,18]. Therefore, the SINR (denoted by \( \gamma_{l}^{FIU} \)) for \( S_{l}^{FIU} \) is given by the following:

\[
\gamma_{l}^{FIU} = \frac{\| \mathbf{g}_{l}^{H} \mathbf{v}_{l} \|^{2}}{\sum_{k=1}^{L} \| \mathbf{g}_{l}^{H} \mathbf{w}_{k} \|^{2} + \sum_{k=1,k\neq l}^{L} \| \mathbf{g}_{l}^{H} \mathbf{v}_{k} \|^{2} + \sigma_{l,FIU}^{2}}
\]  

(6)

2.2. Derivation of Outage Probabilities

In this section, we derive the outage probabilities for \( \zeta_{l}^{NU} \), \( \zeta_{l}^{FIU} \), and \( \gamma_{l}^{FIU} \). To do so, we employ a generic framework that can incorporate all the aforementioned SINRs. First, we reformulate the \( \zeta_{l}^{NU} \), \( \zeta_{l}^{FIU} \), and \( \gamma_{l}^{FIU} \) defined in (5) and (6) as follows:

\[
\zeta_{l}^{NU} = \frac{\| \mathbf{h}_{l} \|^{2}_{\mathbf{w}_{l}^{H} \mathbf{w}_{l}} + \sum_{k=1,k\neq l}^{L} \| \mathbf{h}_{l} \|^{2}_{\mathbf{w}_{l}^{H} \mathbf{v}_{k}} + \sigma_{l,NU}^{2}}{\sum_{k=1}^{L} \| \mathbf{h}_{l} \|^{2}_{\mathbf{w}_{l}^{H} \mathbf{w}_{k}} + \sum_{k=1,k\neq l}^{L} \| \mathbf{h}_{l} \|^{2}_{\mathbf{w}_{l}^{H} \mathbf{v}_{k}} + \sigma_{l,FIU}^{2}}
\]  

(7)

\[
\zeta_{l}^{FIU} = \frac{\| \mathbf{h}_{l} \|^{2}_{\mathbf{w}_{l}^{H} \mathbf{v}_{l}} + \sigma_{l,FIU}^{2}}{\sum_{k=1,k\neq l}^{L} \| \mathbf{h}_{l} \|^{2}_{\mathbf{w}_{l}^{H} \mathbf{v}_{k}} + \sigma_{l,FIU}^{2}}
\]  

(8)

and

\[
\gamma_{l}^{FIU} = \frac{\| \mathbf{g}_{l} \|^{2}_{\mathbf{w}_{l}^{H} \mathbf{v}_{l}} + \sigma_{l,FIU}^{2}}{\sum_{k=1,k\neq l}^{L} \| \mathbf{g}_{l} \|^{2}_{\mathbf{w}_{l}^{H} \mathbf{v}_{k}} + \sigma_{l,FIU}^{2}}
\]  

(9)

By observing the required SINRs in (7)–(9), it can be concluded that all the required SINRs can be dealt by defining the following generic variables:

\[
Y = \frac{\| \mathbf{x} \|^{2}_{A}}{\| \mathbf{x} \|^{2}_{B} + \sigma_{l}^{2}}
\]  

(10)
where \( x \) is a complex circular Gaussian vector such that \( x \sim \mathcal{CN}(0, R_x) \), \( A \) and \( B \) are the matrices formed by product of beam vectors, and \( \sigma_i^2 \) is the noise variance with subscript \( i \) in the set \( \{(l, NUI), (l, FLU)\} \). It can be easily seen that the variable \( Y \) can incorporate all SINRs defined in Equations (7)–(9) with the proper choice of variables \( x, A, \) and \( B \) (e.g., \( x \) can be either \( h_i \) or \( g_l ), \( A \) and \( B \) can be any of the weighting matrices formed by the beam vectors \( \psi_i \) and/or \( \psi_l \)).

Next, following the approach of [19], the variable \( Y \) can be expressed as a ratio of indefinite quadratic forms as follows:

\[
Y = \frac{\|x\|^2_A}{\|x\|^2_B + \sigma_i^2},
\]

where \( x = R_x^{-\frac{1}{2}}x \) is the whitened version of \( x \), while the matrices \( A \) and \( B \) are defined as

\[
\bar{A} = R_x^{-\frac{1}{2}}AR_x^{-\frac{1}{2}} \quad \text{and} \quad \bar{B} = R_x^{-\frac{1}{2}}BR_x^{-\frac{1}{2}}.
\]

Now, using the definition of outage probability, the outage probability of \( Y \) (denoted by \( P_{\text{out}, Y} \)) for any given threshold value \( \gamma_{th} \) can be formulated as follows:

\[
P_{\text{out}, Y}(\gamma_{th}) = \Pr(Y < \gamma_{th}) = \Pr(\sigma_i^2 - \gamma_{th} + \|x\|^2_{\bar{B}^{-1}A} > 0)
\]

The solution of the above probability can be found using the approach outlined in [19] which results in the following:

\[
P_{\text{out}, Y}(\gamma_{th}) = 1 - \sum_{m=1}^{M} \lambda_m e^{-\frac{\gamma_{th}}{\lambda_m}} \frac{1}{|\lambda_m|} \left( 1 - \frac{1}{\lambda_m} \right)
\]

where \( u(\cdot) \) represents the unit step function and \( \lambda_m \) is the \( m \)th eigenvalue of the matrix \( \bar{A} - \bar{B} \gamma_{th} \).

### 2.3. Design of Optimized Beamvectors for the NOMA System

In this section, we provide two schemes to design optimal multicast beamforming with SC for the NOMA system. These methods are based on statistical performance measures, that is, the outage probability of near and far users which relies only on the channel statistics in terms of eigenvalues of the channel correlation matrix.

#### 2.3.1. Task 1: Beam Power Minimization While Constraining the Outage Probabilities

The task of optimal multicast beamforming with SC is to minimize the total power for beam vectors while achieving reliable signal reception. It should be noted that the eigenvalues \( \lambda_m \) appearing in Equation (14) are the function of beam vectors \( \psi \) and \( \psi_l \). Thus, we can design optimal beam vectors by minimizing the total beam powers while constraining the outage probability at the near user and the worst outage probability at the far user [5,18]. To do so, we formulate the optimization problem as the minimum power multicast beamforming as follows:

\[
J_i(\psi_l, \psi_l, \gamma_{th}) = \min_{\{\psi_l, \psi_l\}} \sum_{i=1}^{L} \left( \|\psi_l\|^2 + \|\psi_l\|^2 \right),
\]

subject to

\[
\|\psi_l\|^2 \geq \|\psi_l\|^2, \quad \forall \psi_l
\]

\[
P_{\text{out}, \psi_l}(\gamma_{th}) \leq P_{\psi_l}^{\text{FLU}}, \quad \forall \psi_l \text{ and } \gamma_{th}
\]

\[
\max \left\{ P_{\text{out}, \psi_l}(\gamma_{th}), P_{\text{out}, \psi_l}(\gamma_{th}) \right\} \leq P_{\psi_l}^{\text{FLU}}, \quad \forall \psi_l \text{ and } \gamma_{th}
\]

where \( J_i(\psi_l, \psi_l) \) is the total beam power, \( P_{\text{out}, \psi_l}(\gamma_{th}) \) is the outage probability of the \( i \)th user, and \( P_{\psi_l}^{\text{FLU}} \) is the power constraint at the \( i \)th user.
The first constraint in the above is employed to meet the requirement of power-domain NOMA. The second constraint is forcing the outage of the near user at the near user receiver to be less than the selected maximum acceptable value (the value of the maximum acceptable outage is usually determined by the QoS requirements) (denoted by $P_{\Gamma N}^l$) which is required to successfully decode the signal $S_{NUL}^l$ after SIC at the near user receiver. Finally, the last constraint is utilized to limit the worst case outage of the far user to be less than a certain maximum acceptable value (denoted by $P_{\Gamma F}^l$) which makes sure that the signal $S_{FUL}$ can be successfully decoded at both the near and far users. The objective function of Equation (15) is a non-convex function of beam vectors whose unique solution cannot be obtained. Thus, we employ numerical optimization methods, such as active set (AS) optimization and SQP [15–17] to solve the above optimization task. An overview of the SQP optimization is provided in Appendix A while the evaluation of required gradients in our optimization tasks is provided in Appendix B.

Remark 1. In contrast to the optimization problem defined in [5,18], where the constraints were applied to instantaneous SINRs (which assumes that the knowledge of instantaneous channels for both near and far users are available), we applied constraints on the outage probabilities, which only requires the statistics of the channel [14,19]. Thus, the proposed optimization problem is trying to find the optimal beam vectors by utilizing only the knowledge of channel statistics with much lesser computational complexity and bandwidth requirements than the one required for instantaneous channel information-based beamforming.

2.3.2. Task 2: Outage Probabilities Minimization While Constraining the Transmit Beam Powers

In this task, we propose to design optimum beam vectors by minimizing the sum outage probabilities while constraining the total beam power to unity. The sum outage probability is defined as follows:

$$
P_{\text{out,Total}}(\gamma_{th}) \triangleq \frac{1}{3} \sum_{l=1}^{L} \left( P_{\text{out,FL}}(\gamma_{th}) + P_{\text{out,FUL}}(\gamma_{th}) + P_{\text{out,FUL}}(\gamma_{th}) \right)
$$

(16)

where the factor of $\frac{1}{3}$ is used to normalize the maximum total probability to unity. Next, we propose the beamforming design via the following optimization task:

$$
J_l(w, x, \gamma_{th}) = \min_{(w, v)} P_{\text{out,Total}}(\gamma_{th}),
$$

subject to

$$
\|w_i\|^2 \geq \|w_i\|^2,
\|w_i\|^2 + \|v_i\|^2 = 1,
\forall i \text{ and } \gamma_{th}
$$

(17)

The first constraint in the above is employed to meet the requirement of power-domain NOMA. The second constraint is used to limit the total power to unity. Again, the objective function of Equation (17) is a non-convex function, and the numerical optimization method of AS and SQP are employed to find its solution. The implementation of these methods can be done using the approach outlined in Appendices A and B.

The pseudo-code for the the beamforming optimization in NOMA using Task 1 and Task 2 can be summarized in Algorithm 1 as follows:
Algorithm 1 NOMA-BeamformingOptimization Algorithm.

Set optimization algorithm to AS or SQP
Set precision level \((\epsilon)\), and maximum iteration count \(T\)
Initialize \(\mathbf{w}\) and \(\mathbf{v}\) with random orthonormal vectors
Time Index \(t = 0\)
Compute \(J_t(\mathbf{w}, \mathbf{v}, \gamma_{th})\) using Equation (15) or Equation (17)
repeat
\(t = t + 1\)
Find \(J_t(\mathbf{w}, \mathbf{v}, \gamma_{th})\)
if \(|J_t(\mathbf{w}, \mathbf{v}, \gamma_{th}) - J_{t-1}(\mathbf{w}, \mathbf{v}, \gamma_{th})| \geq \epsilon\) then
Update \(\mathbf{w} = \mathbf{w}^{opt}, \mathbf{v} = \mathbf{v}^{opt}\)
else
condition = true
until condition = true, or \(t > T\)

3. Results and Discussion

In this section, we report the results for our proposed multicast beamforming NOMA systems. Note that our proposed solution is valid for any number of users in NOMA systems. However, we present the results for two users only to show the proof of concept. We use \(L = 1\) and \(K = 2\) in our simulations. We set the length of beam vectors to \(M = 5\), and the additive noise variance is such that the SNR is kept to 20 dB. The channel vectors are generated as complex zero-mean circular Gaussian random vectors with a correlation matrix with exponential correlation coefficients, i.e., \(R_{ij} = \rho^{|i-j|}\) (the correlation coefficient \(\rho\) lies in \([0, 1]\)). To implement the power domain NOMA, we set the beam vectors as follows:

\[
\mathbf{v} = \sqrt{P_v} \bar{\mathbf{v}} \quad \text{and} \quad \mathbf{w} = \sqrt{P_w} \bar{\mathbf{w}}
\]

where \(||\bar{\mathbf{v}}||^2 = ||\bar{\mathbf{w}}||^2 = 1\). The SC powers assigned to near and far users are 0.2 and 0.8, respectively (i.e., \(P_w = 0.2\) and \(P_v = 0.8\)), where the summation of the two powers is normalized for fair comparison.

First of all, we validate the derived analytical expression of outage probability for \(\zeta_{NU}\) in Figure 2 by comparing the Monte Carlo simulation results with the one obtained via the analytical expression in Equation (14) with eigenvalues calculated from the matrix \(R_h \bar{\mathbf{w}} \mathbf{w}^H R_h\) and setting \(\sigma^2 = \sigma^2_{NU}\). It can be depicted from Figure 2 that there is a good match between the simulation and the derived analytical expression.

![Figure 2. Validation of analytical outage probability \(P_{out,\zeta_{NU}}(\gamma_{th})\) for \(K = 2\).](image-url)
3.1. Results for Task 1

In this part, we investigate the performance of the beamforming optimization via Equation (15). The results in Figure 3 illustrate the optimization performance for beam powers $|v|^2$, $|w|^2$, and $|v|^2 + |w|^2$ for two different lengths of antenna array, that is, $L = 5$ and $L = 8$. It can be seen that the total beam power is minimized in both scenarios while the constraint on individual powers, that is, $|v|^2 \geq |w|^2$ is also satisfied. Moreover, it can be observed that the power minimization is more for $L = 8$ in contrast to $L = 5$, showing the benefit of using a larger antenna array. Next, in Figure 4, the performance of the outage probability constraint for $\zeta_{NU}$ is investigated for $L = 8$, which clearly exhibits a reduction in outage probability, thereby satisfying the constraint successfully.

![Figure 3. Optimization performance for beam powers with $L = 5$ and $L = 8$.](image1)

![Figure 4. Performance of outage probability constraint for $\zeta_{NU}$ for $L = 8$.](image2)

Next, in Figure 5, the performance of the outage probability constraint for the far user is compared before and after optimization. It can be depicted from the figure that the worst outage probability of the far user never exceeds the limit and hence, successfully
meets the desired constraint. Moreover, it can be easily seen that the proposed method not only satisfies the constraints, but also minimizes the outage probability w.r.t. to the constraint reference. Hence, the overall performance of the proposed beamforming method can achieve both lower transmission power as well as lower outage probabilities for both near and far users, which guarantee reliable QoS service. It should not be forgotten that the proposed method is bandwidth efficient, as it does not require to send pilots for channel estimation.

Next, we demonstrate the performance of the beamforming optimization via Equation (17). In Figure 6, the total outage probability $P_{\text{out,Total}}(\gamma_{\text{th}})$ is plotted before and after optimization by minimizing the objective function in (17) via the AS method. It can be observed that the proposed method can achieve a remarkable reduction in the total outage probability. On the other hand, the result in Figure 7 shows that the constraints on the beam power employed in (17) are satisfied for the whole range of $\gamma_{\text{th}}$. Thus, the beam vectors obtained via (17) maintain the total beam power to unity (i.e., $\|\mathbf{w}\|^2 + \|\mathbf{v}\|^2 = 1$) while the beam power of the far user is greater than that of the near user (i.e., $\|\mathbf{v}\|^2 \geq \|\mathbf{w}\|^2$).

Figure 5. Performance of outage probability constraint for far user.

Figure 6. Performance of outage probability minimization via Task 2.
4. Conclusions

In this work, we proposed spectral efficient beamforming schemes for downlink power-domain NOMA, as it does not require pilots transmission for channel estimation. In the proposed methods, the beam vectors are optimized using two approaches:

1. By minimizing the total beam powers while constraining the outage probabilities for near and far users;
2. By minimizing the total outage probabilities in the system while constraining the beam powers.

To achieve this, outage probabilities derived in a closed form, which, in turn, were utilized to implement the desired optimization tasks via the AS and SQP methods. The performance of the proposed algorithms was tested for different scenarios, showing that the proposed beamforming method can provide both lower transmission power as well as lower outage probabilities for both near and far users. Most importantly, the proposed schemes rely only on the statistical CSI, which reduces the transmission overhead. Thus, our proposed system can be considered a strong candidate for spectral efficient 5G communications.

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Appendix A. Overview of Sequential Quadratic Programming

In this Appendix, we provide an overview of the SQP optimization that can be used to solve any nonlinear optimization problem of the following form:

\[
\begin{align*}
\text{minimize} & \quad f(x) \\
\text{subject to} & \quad h(x) = 0 \\
& \quad g(x) \leq 0
\end{align*}
\]  

(A1)

where \( f(x) \in \mathbb{R}^n, h(x) \in \mathbb{R}^m, \) and \( g(x) \in \mathbb{R}^p \) are objective function, equality constraints, and inequality constraints, respectively. The SQP is an iterative optimization technique which models the non-linear optimization problem in (A1) at iteration \( k \) (i.e., \( x_k \)) by a quadratic programming (QP) sub-problem. Next, it solves that QP sub-problem to obtain the solution for iteration \( k + 1 \) (i.e., \( x_{k+1} \)), which results in a local minimum of the actual objective function. The Lagrangian functional \( \mathcal{L} \) for the problem in (A1) can be formulated as follows:

\[
\mathcal{L}(x, \lambda, \mu) = f(x) + \mu_{eq}^T h(x) + \mu_{iq}^T g(x) = f(x) + \sum_{i=1}^m \mu_{eq,i} h_i(x) + \sum_{i=1}^p \mu_{iq,i} g_i(x)
\]

(A2)

where \( \{\mu_{eq,i}\} \) and \( \{\mu_{iq,i}\} \) are the Lagrangian multipliers for equality and inequality constraints, respectively. In order to solve the above problem, the SQP utilizes the following QP sub-problem formation:

\[
\begin{align*}
\text{minimize}_{\{d(x)\}} & \quad \frac{1}{2} d^T(x) H_k d(x) + \nabla f(x_k)^T d(x) \\
\text{subject to} & \quad \nabla h_i(x_k)^T d(x) + h_i(x_k) = 0, \quad i = 1, 2, \cdots, m \\
& \quad \nabla g_i(x_k)^T d(x) + g_i(x_k) = 0, \quad i = 1, 2, \cdots, p
\end{align*}
\]

(A3)

where \( d(x) = x - x_k \) and \( \nabla \) represents the gradient operation. The Hessian matrix \( H_k \) appeared in the above can be calculated using the Broyden–Fletcher–Goldfarb–Shanno (BFGS) method [20–23]. Finally, the solution of the QP sub-problem in (A3) can be found using any of the standard QP solving procedures, such as the one mentioned in [24].

Appendix B. Evaluation of required Gradient Vectors for the Proposed Method

In this Appendix, we evaluate the required gradient vectors for the proposed method, namely \( \nabla f(x) \), \( \nabla h_i(x) (i = 1, 2, \cdots, m) \), and \( \nabla g_i(x) (i = 1, 2, \cdots, p) \).

If we consider our proposed optimization task in (15), we can formulate the \( x \) by stacking real and imaginary parts of both beam vectors \( w_l \) and \( v_l \) for all the pairs (\( l = 1, 2, \cdots, L \)) in a column vector, that is,

\[
x = [w_R, v_R, w_I, v_I]^T
\]

(A4)

where the notations \( (\cdot)_R \) and \( (\cdot)_I \) are used to represent real and imaginary vectors, respectively. Each of these vectors is of length \( L \). Next, by observing (15), we have

\[
\begin{align*}
f(x) &= \sum_{l=1}^L \left( ||w_l||^2 + ||v_l||^2 \right) \\
g_{1,l}(x) &= ||w_l||^2 - ||v_l||^2, \quad \forall l \\
g_{2,l}(x) &= P_{out}^{\ell_{out}}(\gamma_l) - P_{I_{1l}}^N, \quad \forall l \\
g_{3,l}(x) &= P_{out}^{\ell_{out}}(\gamma_l) - P_{I_{1l}}^R, \quad \forall l \\
g_{4,l}(x) &= P_{out}^{\ell_{out}}(\gamma_l) - P_{I_{2l}}^R, \quad \forall l
\end{align*}
\]

(A5) - (A9)
Thus, we require to evaluate $\nabla f(x)$, $\nabla g_{1,j}(x)$, $\nabla g_{2,j}(x)$, $\nabla g_{3,j}(x)$, and $\nabla g_{4,j}(x)$ which are provided in the ensuing.

First, we can easily show that the $\nabla f(x)$ will result in

$$\nabla f(x) = [2w_{1R}(1), \cdots, 2w_{LR}(M), 2v_{IR}(1), \cdots, 2v_{LR}(M), \cdots, 2v_{1J}(1), \cdots, 2v_{LJ}(M)]^T$$  \hspace{1cm} (A10)

Next, the gradient $\nabla g_{1,j}(x)$ can be found to be

$$\nabla g_{1,j}(x) = [0, \cdots, 2w_{1R}(1), \cdots, 2w_{1J}(M), -2v_{1R}(1), \cdots, -2v_{1J}(M), \cdots, 0]^T$$  \hspace{1cm} (A11)

Next, the gradient $\nabla g_{2,j}(x)$ is given by

$$\nabla g_{2,j}(x) = \frac{d}{dx}P_{\text{out},j}^\text{NU}(\gamma_{th}) = \frac{d}{dx} \left( 1 - \sum_{m=1}^{M} \frac{\lambda_m^M e^{-\frac{\sqrt{2}\nu_{NU}\gamma_{th}}{\lambda_m}}}{\prod_{l=1,i\neq m}^{M}(\lambda_l - \lambda_i)} \right)$$

where $\lambda_m$ is the $m^{th}$ eigenvalue of the matrix $\tilde{A} - \gamma_{th} \tilde{B}$ with $\tilde{A} = R_{h1}^\frac{1}{2} w_l^H R_{h1}^\frac{1}{2}$ and $\tilde{B} = R_{h1}^\frac{1}{2} \sum_{k=1 \neq j}^L w_k^H R_{h1}^\frac{1}{2}$.

Since the term $u(\lambda_m)$ is imposing the restriction of positive $\lambda_m$ only, we can reformulate the derivative in (A12) as

$$\nabla g_{2,j}(x) = -\sum_{m=1}^{M} \frac{d}{dx} \left( \lambda_m^M e^{-\frac{\sqrt{2}\nu_{NU}\gamma_{th}}{\lambda_m}} \right) \frac{\prod_{l=1,i\neq m}^{M}(\lambda_l - \lambda_i)}{\prod_{l=1,i\neq m}^{M}(\lambda_l - \lambda_i)^2}$$

In the above, we have to calculate the derivative terms $\frac{d}{dx} (\lambda_m^M e^{-\frac{\sqrt{2}\nu_{NU}\gamma_{th}}{\lambda_m}})$ and $\frac{d}{dx} \left( \prod_{l=1,i\neq m}^{M}(\lambda_l - \lambda_i) \right)$. Both these derivative terms can be easily calculated for any given $M$ using product formulas. However, this eventually requires the calculation of derivative terms of the form $\frac{d}{dx}\lambda_i$ for any $i$. In order to do so, we first express the eigenvalue $\lambda_i$ using its $i^{th}$ eigenvector (denoted by $q_i$) as follows

$$\lambda_i = ||q_i||_2^2 \frac{1}{\lambda_i} \frac{d}{dx} = ||q_i||_2^2 \frac{1}{\lambda_i} \frac{d}{dx} \left( R_{h1}^{-\frac{1}{2}} w_l w^H_l R_{h1}^{-\frac{1}{2}} - \gamma_{th} R_{h1}^{-\frac{1}{2}} \sum_{k=1 \neq m} w_k^H R_{h1}^\frac{1}{2} \right)$$

Thus, the $n^{th}$ element of the gradient $\frac{d}{dx} \lambda_i$ can be calculated as

$$\frac{d}{dx} (\lambda_i) = ||q_i||_2^2 \frac{1}{\lambda_i} \frac{d}{dx} \left( R_{h1}^{-\frac{1}{2}} w_l w^H_l R_{h1}^{-\frac{1}{2}} - \gamma_{th} R_{h1}^{-\frac{1}{2}} \sum_{k=1 \neq m} w_k^H R_{h1}^\frac{1}{2} \right)$$

Knowing the fact that

$$w_l w^H_l = \begin{bmatrix} w^2_l(1) + w^2_l(1) & w_l(1)w^*_l(2) & \cdots & w_l(1)w^*_l(M) \\ \vdots & \vdots & \ddots & \vdots \\ w_l(M)w^*_l(1) & w_l(M)w^*_l(2) & \cdots & w^2_l(M) + w^2_l(M) \end{bmatrix}$$
the derivative \( \frac{d}{dx(n)} (w_l w_l^H) \) appearing in (A15) can be easily evaluated. As an example, the derivative \( \frac{d}{dx(n)} (w_l w_l^H) \) for \( x(n) = w_{IR}(1) \) is given by

\[
\frac{d}{dw_{IR}(1)} (w_l w_l^H) = \begin{bmatrix}
2w_{IR}(1) & jw_{II}(1)w_1^T(2) & \cdots & jw_{II}(1)w_M^T(M) \\
\vdots & \vdots & \vdots & \vdots \\
-jw_{II}(1)w_1^T(M) & 0 & \cdots & 0
\end{bmatrix}, \tag{A17}
\]

Similarly, the remaining elements in \( \frac{d}{dx(n)} (w_l w_l^H) \) can be evaluated. Moreover, following the same approach, the derivative term \( \frac{d}{dx(n)} (w_k w_l^H) \) can also be calculated. Hence, this completes the evaluation of \( \nabla S_{2j}(x) \) and \( \nabla S_{4j}(x) \).

Finally, the same approach can be employed to evaluate the gradients \( \nabla S_{3j}(x) \) and \( \nabla S_{4j}(x) \).

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