Non-autonomous Hamiltonian quantum systems, operator equations and representations of Bender-Dunne Weyl ordered basis under time-dependent canonical transformations.

Mariagiovanna Gianfreda and Giulio Landolfi

a Institute of Industrial Science, University of Tokyo, Komaba, Meguro, Tokyo 153-8505, Japan
b Department of Mathematics and Physics 'Ennio De Giorgi', Università del Salento, via Arnesano, I-73100 Lecce, Italy
c I.N.F.N. Sezione di Lecce, via Arnesano I-73100 Lecce, Italy

(Dated: October 26, 2015)

We address the problem of integrating operator equations concomitant with the dynamics of non-autonomous quantum systems by taking advantage of the use of time-dependent canonical transformations. In particular, we proceed to a discussion in regard to basic examples of one-dimensional non-autonomous dynamical systems enjoying the property that their Hamiltonian can be mapped through a time-dependent linear canonical transformation into an autonomous form, up to a time-dependent multiplicative factor. The operator equations we process essentially reproduce at the quantum level the classical integrability condition for these systems. Operator series form solutions in the Bender-Dunne basis of pseudo-differential operators for one dimensional quantum system are sought for such equations. The derivation of generating functions for the coefficients involved in the minimal representation of the series solutions to the operator equations under consideration is particularized. We also provide explicit form of operators that implement arbitrary linear transformations on the Bender-Dunne basis by expressing them in terms of the initial Weyl ordered basis elements. We then remark that the matching of the minimal solutions obtained independently in the two basis, i.e. the basis prior and subsequent the action of canonical linear transformation, is perfectly achieved by retaining only the lowest order contribution in the expression of the transformed Bender-Dunne basis elements.

PACS numbers: 03.65 -w

I. INTRODUCTION

In classical mechanics integrability is a fundamental concept that has witnessed a broad range of developments in different directions (see, e.g., [1]-[5] and Refs. therein). Owing to the different nature of dynamical objects to be considered, and of diverse characteristics of the spaces thence implied, the attempt to transfer the same fabrics at the quantum level clearly suffers of some inconsistencies. Nonetheless, efforts to overcome difficulties are expected, to improve the understanding of semiclassical regimes, and of classical to quantum transitions (e.g., in respect to chaotic dynamics) or vice versa. To this, it makes particularly sense to consider the peculiar issues that may plague a satisfactory correspondence within formalism that better allow the realization of common views shared by classical and quantum mechanics. For instance, approaches based on phase-space distributions appear well-suited to some purposes (among the others, see [6]-[9]). For a deeper insight it looks very reasonable to pay attention on independent conserved quantities and algebras underlying an assigned problem, for instance as discussed within the framework developed after the seminal papers [10, 11] or as currently pursued in consideration of the notion of superintegrability (see e.g. [12, 13]). Needless to say, to exploiting the results obtained in symmetry-based frameworks also supposes a profound comprehension of properties of the operators representing pairs of canonically conjugated quantum observables and of quantum implications of classical canonical transformations.

In discussing integrable systems in classical mechanics, the key role of canonical transformations cannot be ignored. Having proved to enable the gaining of general conceptual insights as well as the advantageous solving of a number of significant dynamical problems, their relevance is undoubted. Quantum canonical transformations, say the change of operator variables preserving the canonical commutation relations, may prove, in principle, similarly useful in connecting the wave equation solution for a system of interest to the solution of a simpler equation. Nevertheless, the topic enters in the discussion of quantum problems only limited, or with certain determined intents. In general, there

*Electronic address: mariagiovanna.gianfreda@gmail.com
†Electronic address: giulio.landolfi@unisalento.it; giulio.landolfi@le.infn.it
are some reasons why this happens. In some cases, one may just prefer to derive approximate solutions because they are sufficient for arguing on a definite problem. In other cases, one may feel uncomfortable in dealing with transformations that only preserve the dynamical equations and not necessarily other ingredients one may like to retain *tout court*, such as the norm of states and the Hilbert space structure of the model. But there are other primary obstacles. For instance, some caution is required in that the canonical transformation from position-momentum to action-angle coordinates are generally nonbijective (see *e.g.* discussions in [14, 15]). At the quantum level this unpleasant event is perceived as aggravated by the question raised about the uniqueness of the realization of operators obeying given commutation relations and operator equations. Moreover, the applicability of the standard correspondence principle, and of the outstanding uncertainty principles to arbitrary conjugate pairs generates controversial interpretations (see *e.g.* [16, 17]). So, before trying to learn from the introduction of new observables, one may find desirable being in the position of adhering to a more satisfactory mathematical formulation of Quantum Mechanics that excludes the appearance of non-unitary features and ambiguities.

Some of the above mentioned aspects are effectively grasped at once through a meaningful paradigmatic example. In a perspective slightly different from the standard Hamiltonian formulation, the problem of the integrability of a Hamiltonian system can be debated by putting some different emphasis on the time variable, in fact [51]. For instance, for a one dimensional autonomous system whose Hamiltonian is

\[ H = \frac{p^2}{2m} + V(q), \]

the problem of the integration of Hamilton equation of motion can be implemented by making use of the fact that the evolution of canonical coordinate \( q \) can be given implicitly via

\[ t = t_0 + \int_{q_0}^{q} \frac{dq}{\sqrt{E - V(q)}}, \]

being \( E \) the constant value taken by the Hamiltonian, i.e. the system’s energy. Equation (2) clearly effects the possibility to describe the system dynamics, since a parameter (time or angle-like variable) that parametrizes continuous curves (or pieces of) in phase space can identify representative trajectories implicitly preserving the existence of a dynamical group for time [52]. In a sense, integration of the energy conservation law replaces the integration of one of the Hamilton equations. One has, at variance, a focus on the relationship between the variable \( F(q(t)) = t + \text{const} \), that is to say the variable whose Poisson brackets with the Hamiltonian \( H \) equals to unity (i.e., the variable whose translations are the result of canonical transformations generated by the Hamiltonian). Armed with the map between position and \( F \), trajectories in phase space are likewise derived from the Hamilton equations. In passing at the quantum level, one may perform a transposition of the argument for Heisenberg equations of motion for position and momentum operators and Heisenberg equation \([F, H] = i\hbar \) [53]. While it seems kind of an innocuous change of variables, dealing with the aspects connected with the new problem is actually an outstanding issue in standard formulation of Quantum Mechanics. It poses unavoidably the question of the meaning of the classical-quantum correspondence and of the preservation of hermiticity and unitarity for operators entering in the framework [16, 17]. The doubts being supported by the famous Pauli’s embargo that there is no self-adjoint operator canonically conjugate to a Hamiltonian if the Hamiltonian spectrum is bounded from below. Remedies to ambiguities and inconsistencies have been valued, most significantly by means of positive operator measures (see *e.g.* [9]) or confinement [18, 19, 54]. Besides, within the phase-space distributions approach, a commonsensical way to act can be approved upon the suggestion that operators obtained by direct quantization (and introduction of an ordering rule) of classical phases attribute a correct sharp phase to large amplitude localized states (see [9] and Refs. therein). Hence, the formal solving of operator equations like the Heisenberg one above, \([F, H] = i\hbar \), always represents an obliged road for comprehending to what extend corrective terms for observables may be extracted and how a picture should be modified in order to probe more general dynamical regimes and states when deviation from classicality is considered.

For non-autonomous systems the integrability issue may be argued similarly, but some adaptations of the framework are needed. The question can be better elucidated from the point of view of the understanding of the time transformations required to fully preserve the structure of the equations (classical and quantum). Indeed, for general non-autonomous classical hamiltonian systems, symmetries are associated with vector fields whose components along the time-derivative directions are not constant and depend on \((q, p, t)\). Mapping a non-autonomous system into an autonomous one implies the accomplishment of a canonical transformation \((q, p, t) \rightarrow (Q(q, p, t), P(q, p, t), \tau(q, p, t))\) into the time-extended phase-space \((q, p, t)\), in such a way that the symmetry vector field introduces a derivative with respect to the new time-like variable \( \tau \). In practice, if this operation is actuated, a map is realized implying the time-dependent Hamiltonian going into a dynamical invariant. At the classical level, one may expound this by saying that, being not fixed, energy is not anymore the preferred observable for measuring features of orbits in phase-space, and transport of dynamics of system states over them. (This is due to the correspondence Hamiltonian-energy for
autonomous systems.) At the quantum level, this means that a basic stationary spectral quantum problem may be considered as opposite to the time-dependent Schrödinger equation involving the original Hamiltonian. Evolution equation through Poisson brackets or commutators are subject to adjustments accordingly. After doing so, the topic of their integrability may be assessed similarly to the autonomous case.

Whichever the approach to the topic of quantum integrability and the peculiarities of Hamiltonians, operator equations entailing commutators needs definitely to be analyzed. The task can be carried out by implementation of techniques accomplishing ordering of non-commuting operators (see e.g. [23] and Refs therein). Solving operator equation then essentially becomes into a matter of combinatorics, and interesting findings in this respect may be revealed in fact, see e.g. [24, 25]. A way to proceed is to resort to the technique proposed and discussed by Bender and Dunne in their enlightening paper [20], based on the introduction of Weyl ordering (an ordering which holds interesting properties). It basically consists in looking for solution to an equation for an operator $\hat{F}(\hat{q}, \hat{p})$ by finding its components in a basis $\{T_{m,n}\}_{m,n \in \mathbb{Z}}$ whose elements $T_{m,n}$ are constructed by superimposing Weyl ordering to products $\hat{p}^m \hat{q}^n$ of integer powers of position and momentum canonical operators. Hence the operator is sought in the series form $\hat{F} = \sum_{m,n} f_{m,n} \hat{T}_{m,n}$, the elements $\{T_{m,n}\}$’s being defined by applying the operator ordering prescription scheme

$$\hat{T}_{m,n} = : \hat{p}^m \hat{q}^n :_{\text{Weyl}} = \frac{1}{2^n} \sum_{k=0}^{n} \binom{n}{k} \hat{q}^k \hat{p}^{m-n+k} = \frac{1}{2^m} \sum_{k=0}^{m} \binom{m}{k} \hat{p}^j \hat{q}^m \hat{p}^{n-j} \quad (3)$$

where the first (second) ordered form has to be used for negative momenta $p$ (position $q$) powers [20]. Note that the binomials have to be expressed in terms of Gamma functions whenever the power indexes $m$ or $n$ are negative. (For an analysis of properties of the Bender-Dunne basis $\{T_{m,n}\}$, see [26].) In order to lighten the notation, and since no ambiguities can occur, the hat operator symbol $\hat{}$ shall be omitted hereinafter.

The operator equation considered in [20, 21] was just the one finalizing an operator $F$ formally conjugated to the Hamiltonian, and solutions were given there for basic autonomous one-dimensional hamiltonian systems such as the particle undergoing the quadratic or the quartic potential. Evidently, and regardless the particular strategy possibly employed, whenever one attempts to solve the above equation in practice, one is generally faced with the question of the non-uniqueness of operators that can be formally identified as solutions of an operator equation (for recent examples in this respect, see [24, 23]). For this reason, the concept of minimal solution has been introduced in [20] as a viable criterion: it is the simplest among the solutions that are compatible with the recursion relations implied for the expansion coefficients, i.e. the solution that minimize the number of nonzero coefficients. Remarkably, in [20] Bender and Dunne found that the minimal solution associated with the operator conjugated to the Hamiltonian in the harmonic oscillator case coincides with just the Weyl quantized form of the classical angle variable on the trajectory in the phase space. However, such a connection with the Weyl quantized form of the classical counterpart sounds incidental as the minimal solution strategy does not appear to carry this meaning in general. Indications to reconciling the minimal solution strategy introduced on pragmatic grounds with more authentic physical patterns have been elaborated in by resorting to the so-called inverse Liouville method.

When canonical transformations $C$ enter in the treatment of a dynamical systems, other Bender-Dunne operator bases $T_{m,n}$ are naturally defined in terms of the new pair of canonically conjugate operators. Of course, the expansion of an observable is affected by a canonical transformation accordingly and expansion’ coefficients have to be properly modified in moving from one basis to the other. Furthermore, if $C$ explicitly depends on time, the property is inherited by components of basis elements $T_{m,n}$ in basis $\{T_{m,n}\}$. One is faced with this situation whereby observables (e.g. solutions to some dynamical equations) may be possibly sought in a new basis $\{T_{m,n}\}$, rather than in the initial basis $\{T_{m,n}\}$, when there are hints that a canonical transformation is advantageous in some respects to the system’s investigation. One of such cases is the study of non-autonomous hamiltonian systems where extended generating functions can be identified that define canonical mappings $C$ into time-independent hamiltonian problems. Remark that, working out the transformation, a fictitious time $\tau$ can be put forward that turns out to be correlated with the original time parameter $t$ (sometimes referred as Poincaré -time transformation or as symplectic time rescaling method). In a sense, it acts as the proper time parameter whose invariance under translations is implied for the system described by the invariant emerging from the original Hamiltonian thanks to the transformation, in the same manner as it happens for the initial ‘physical’ time $t$ and an autonomous Hamiltonian in its initial phase-space coordinates. Some attention may be so needed in moving consistently between the two hamiltonian formulations (prior ans subsequent the action of $C$) while handling this time-diffeomorphism.

In the light of all the above, in this communication we are aimed at exploring issues raised and benefits possibly implied when time-dependent canonical transformations are resorted in the investigation of time-dependent operator equations for non-autonomous quantum hamiltonian systems, such as the equation for their angle-action type operators. We shall pay attention to linear time-dependent canonical transformations for position and momentum variables, say $(q, p) \rightarrow (Q, P) \equiv (A(t)q + D(t)p, B(t)p + C(t)q)$ where $A, B, C$ and $D$ are real-valued functions of
time $t$ obeying $AB - CD = 1$ (only one-dimensional systems shall be considered), performed simultaneously to a time diffeomorphism. In the applications, we shall be particularly interested in the point-type limit $D = 0$. This is the structure that emerges for the canonical transformation that maps time-dependent quadratic systems into time-independent ones. However, linear canonical transformations are of more general interest (see e.g. \cite{29,31} and \cite{15}) and resorting to them can be helpful in other cases as well.

The outline of the paper is as follows. In Section \textbf{II} the time-dependent linear phase-space transformations in which we are interested are introduced along with the accompanying unitary operator in order to point out that, if a proper ansatz does hold, they enable to transform a non-autonomous system into an equivalent one which is autonomous. Once the main reason why we are interested into time-dependent linear transformations is clarified, in Section \textbf{III} we consider their action on the Bender-Dunne basis of operators defined by equation \textbf{(3)}. We widen partial results already found in this regard \cite{32} to the case of negative power of position (respectively, momentum) operators, i.e. negative index $m$ (respectively, $n$) of the basis elements $T_{m,n}$ in eq. \textbf{(3)}, by explicitly expressing the result in manifestly ordered normal and Weyl forms. Section \textbf{IV} is aimed at providing an immediate intuition on the structural difference between the formal position-momentum expansions of Weyl-quantized classical solutions to the integrability condition for one-dimensional Hamiltonian systems and those of quantum solutions (including minimal ones). The succeeding sections are devoted to the processing of the integrability condition in some concrete examples, such as non-autonomous one-dimensional Hamiltonian systems undergoing the linear, the quadratic and the quartic potentials. All the cases are treated dwelling on details for enabling the reader to get more acquainted with the framework. This should serve particularly while applying it further for applications and developments in respect to to equations and operators that appear to be defined, or of interest, only at the quantum level. Finally, Appendix A summarizes the inverse Liouville method.

\section{Linear Phase-Space Transformations}

Although not very customary (even in the classical setting), the treatment of a non-autonomous system with Hamiltonian $H_{\text{na}}(p, q, t)$ may be concerned ultimately with contact transformation in the extended phase-space in such a way that the new Hamiltonian is actually autonomous. In practice, this means to deal with extended canonical transformations $(q, p, t) \rightarrow (Q, P, \tau)$ that mix position and momentum (coordinates or operators, reliant on the dynamical regime) through a time dependent phase-space map implemented by a redefinition of the time variable see e.g. \cite{33,34} (for a discussion treating with time-dependent quadratic systems, see also \cite{35}). As we already said, the basic $Q, P$ structure that enters in the analysis of the non-autonomous Hamiltonians in which we are interested is linear in the original canonical pair $(q, p)$. Below, we shall clarify the purposes of use.

Let us consider the one degree of freedom quantum time-dependent Hamiltonian

$$H = \frac{p^2}{2m(t)} + V(q, t).$$ \hfill (4)

In general, a unitary transformation $U(q, p, t)$ maps the original Hamiltonian (4) into a new operator $H'$, according to

$$H' = U^{-1}HU - iU^{-1}\partial_\tau U.$$ \hfill (5)

Attempts can be made to map the original Hamiltonian (4) into a new Hamiltonian taking a convenient form. Let us focus, in particular, on extended canonical transformations that are linear in position-momentum variables, and are defined according to

$$Q = A(t)q, \quad P = B(t)p + C(t)q, \quad \text{with} \quad A(t)B(t) = 1.$$ \hfill (6)

It is worth to remark that this transformation is unitary and consists of a two-step action in phase-space: a time-dependent dilatation of the configuration space, and a momentum translation that depends on the canonical position linearly. The composition of such kind of two actions can be identified through unitary operators of the form $U_2 = \exp[i\Delta_2(t)] \exp[\Delta_1(t)]$, respectively. Importantly the composition of two time-dependent actions of this type can marginalize the role of time in non-autonomous Hamiltonian quadratic systems, in the sense that solving the Schrödinger equation basically coincides with time-independent spectral problems in the new canonical coordinates (see, e.g., discussions in \cite{35,37}). To be precise, if the Hamiltonian is given in the form

$$H = \frac{p^2}{2m(t)} + \frac{m(t)}{2}\omega(t)^2q^2,$$ \hfill (7)
this happens provided that \[37\]

\[
U_1 = \text{Exp}\left\{-i\frac{\dot{\rho}(t)\rho(t)m(t)}{2}q^2\right\},
\]

\[
U_2 = \text{Exp}\left\{i\frac{\log[\rho(t)]}{2}(pq + qp)\right\},
\]

where \(\rho(t)\) depends on the potential frequency-type function \(\omega\) and mass-type function \(m\) through the differential equation

\[
m(t)\dot{\rho}(t) + \dot{m}(t)\rho(t) + m(t)\omega(t)^2\rho(t) = \frac{1}{m(t)\rho(t)^3},
\]

(which is more often presented as an Ermakov equation \[38, 39\] for the function \(\sigma = \kappa\sqrt{m}\rho\) with \(\kappa = \text{const}\), see e.g. \[40, 41\] and refs. therein). So, the transformation \[6\] is applied with time-dependent coefficients

\[
A(t) = \rho(r)^{-1}, \quad B(t) = \rho(r), \quad C(t) = -m(t)\rho(t),
\]

to give \(H' = (2m\rho^2)^{-1}(P^2 + Q^2)\). The question arises to this point about to what extend the transformation can also be tried out on other systems with the scope to endeavor to a new handy Hamiltonian. The simplest case would be if it will take the form of a time independent Hamiltonian multiplied by a time dependent factor. This convenient chance is not to be excluded \textit{a priori}, in fact. Precisely, we remark here that whenever the condition

\[
m(t)\rho^2(t)V(\rho(t)q, t) = W(q)
\]

holds true for a non-quadratic time-dependent potential \(V\) entering an Hamiltonian operator \(H\) defined as in \[4\], the net action on the Hamiltonian of the unitary transformation \(U = U_1U_2\), with \(U_{1,2}\) given by \[8\]–\[13\], results into the new Hamiltonian operator

\[
H' = \frac{1}{m(t)\rho^2(t)}H_0', \quad \text{where} \quad H_0' = \frac{P^2 + Q^2}{2} + W(Q)
\]

provided that the scaling function \(\rho\) and the mass-type function \(m(t)\) satisfy the differential equation

\[
m(t)\dot{\rho}(t) + \dot{m}(t)\rho(t) = \frac{1}{m(t)\rho(t)^3}.
\]

In fact, for potentials other than the quadratic one as in Hamiltonian \[7\], it turns out that, demanding the final Hamiltonian to be time-diffeomorphic to an autonomous operator, the single condition \[9\] is actually replaced by two distinct conditions: the algebraic condition \[11\] selecting the class of potentials for which the request can be successfully fulfilled, and the differential equation \[13\] for the identification of the proper scaling function \(\rho\) giving rise to the desired canonical transformation (as a matter of fact, the two conditions merge in the case of quadratic potentials \[7\] because both appear in connection with coefficients of quadratic position terms \(Q^2\) generated via the transformation). In a slightly different perspective, it can be said that a dynamical invariant \(I = UH_0'U^{-1}\) can be obtained for the system described by the Hamiltonian \[4\]. In fact, suitable conditions are so identified for the coefficients in Eq. \[4\] such that the change of variables \((q, p, t) \leftrightarrow (Q, P, T)\) enables to express the dynamical variable \(I\) as a stationary one with respect to \((Q, P)\) phase-space coordinate (i.e., \(I(p, q, t) \rightarrow I(P, Q)\)). In particular, this is achieved by setting coefficients as in \[11\] and by performing the change of time variable via

\[
\tau = \frac{1}{2} \int_{t_0}^t \frac{1}{m(t')\rho(t')^2}dt'.
\]

III. WEYL ORDERED SERIES EXPANSION OF THE OPERATOR \(q^\alpha\) UNDER LINEAR PHASE-SPACE TRANSFORMATIONS

A canonical transformation \(C\) on phase-space naturally induces a transformation on dynamical variables on the same space. If the transformation is time-dependent, the immediate quantum analogous of a classical dynamical variable is realized through time-dependent maps acting on the individual operators entering its definition. In particular, if the canonical transformation \(C\) is applied to Bender-Dunne basis elements \(T_{m,n}\), then Weyl ordered bases with elements
\( \mathcal{T}_{m,n} =: C(T_{m,n}) :_{\text{Weyl}} \) may be defined at different times. In this section, we will determine the explicit representation of operators \( \mathcal{T}_{m,n} \) in the basis \( \{ T_{m,n} \} \) once a linear transformation mapping is applied to position and momentum. We consider first the most general case where

\[
Q = A q + D p, \quad P = B p + C q ,
\]

(canonical if \( AB - CD = 1 \)) and we will then consider the canonical transformation stemming from \( \mathcal{T}_{m,n} \) with time dependent coefficients given in \( (10) \), viz.

\[
Q = \frac{q}{\rho (t)} , \quad P = \rho (t) p - m(t) \dot{\rho} (t) q .
\]

To achieve our goal, we adopt a strategy based on step-by-step calculations as follows. Introduce the Bender-Dunne basis associated with the new canonical operator pair \( Q \) and \( P \), that is the operator basis made of the Weyl ordered elements \( \{ 15 \} \):

\[
\mathcal{T}_{-m,n} =: P^{-m} Q^n :_{\text{Weyl}} = \frac{1}{2^n} \sum_{k=0}^{n} \binom{n}{k} Q^k P^{-m} Q^{n-k}
\]

We are interested here in finding a closed form for the operators \( (17) \) in terms of initial variables \( q, p \) and \( t \). Once the canonical transformation \( (15) \) is given, the \( \mathcal{T}_{-m,n} \)'s can be seen as depending on the initial variables \( (q, p, t) \), indeed. In particular, the \( \mathcal{T}_{-m,n} \)'s can be given in terms of the Weyl ordered expansions of products between powers of \( q \) and \( p \). This is straightforward if \( C = 0 \), in that the canonical transformation merely implies a time-dependent scaling of position and momentum, and accordingly \( \mathcal{T}_{-m,n} \rightarrow b^{m+n} \mathcal{T}_{-m,n} \). But if \( C \neq 0 \), the relationship between the two basis \( \{ \mathcal{T}_{-m,n} \} \) and \( \{ T_{-j,k} \} \) is obviously not that trivial. Indeed, while the positive powers of the operator \( Q \) can be easily expressed in terms of \( (q, p, t) \) as

\[
Q^\alpha = (D p + A q)^\alpha = \sum_{s=0}^{\alpha} \binom{\alpha}{s} \frac{D^{\alpha-s} A^s}{2^{\alpha-s}} \sum_{u=0}^{\alpha-s} \binom{\alpha-s}{u} p^u q^{s} p^{\alpha-s-u}
\]

where in \( (17) \) \( \alpha = k \) and \( \alpha = n - k \), the situation is more delicate for the negative power of the operator \( P \), that we can write as

\[
P^{-m} = C^{-m} p^{-m} \frac{1}{1 + \left( \frac{C}{B} \right)^m \sum_{j=0}^{m-1} D_{m,j} T_{j,m-j} p^{-m}}.
\]

We can then render operators \( (17) \) in the form

\[
\mathcal{T}^c_{-m,n} = \frac{D^n}{4^n C^n} \sum_{k=0}^{n} \frac{n}{k} \frac{k}{s} \frac{(k-s)}{u} \frac{2^s A^s}{D^s} \sum_{u=0}^{\alpha-s} \binom{\alpha-s}{u} \sum_{t=0}^{n-k-t} \sum_{v=0}^{n-k-t} \binom{n-k-t}{v} \times p^{u} q^{s} p^{k-s-u-m} \left( 1 + \frac{C_{m}^{m}}{B_{m}^{m}} \sum_{j=0}^{m-1} D_{m,j} T_{j,m-j} p^{-m} \right)^{-1} p^{u} q^{s} p^{n-k-t-v}.
\]

(We shall use the superscript \( ^c \) to point out that the canonical relationship \( (15) \) has been applied to express operators in the \( (q,p) \)-representation). By resorting to the series expansion \( (1 + \Delta_{m})^{-1} = \sum_{r=0}^{\infty} (-\Delta_m)^r \) for the operator

\[
\Delta_m = \frac{C_{m}}{B_{m}} \sum_{j=0}^{m-1} D_{m,j} T_{j,m-j} p^{-m},
\]

we can then express \( (20) \) as

\[
\mathcal{T}^c_{-m,n} = \frac{D^n}{4^n C^n} \sum_{r=0}^{\infty} (-1)^r \sum_{k=0}^{n} \frac{n}{k} \frac{k}{s} \frac{(k-s)}{u} \frac{2^s A^s}{D^s} \sum_{u=0}^{\alpha-s} \binom{\alpha-s}{u} \sum_{t=0}^{n-k-t} \sum_{v=0}^{n-k-t} \binom{n-k-t}{v} \mathcal{O}^r_{k,m,n,s,t,u,v},
\]

where

\[
\mathcal{O}^r_{k,m,n,s,t,u,v} = p^u q^s p^{k-s-u-m} \Delta_m p^v q^t p^{n-k-t-v}.
\]
At this stage, the operators $T_{m,n}^r$ are given by successive actions of different products of powers of the initial noncommuting canonical operators $q$ and $p$. Formal simplification of the above operator series can be realized for making as clear as possible the action of the operators $q$ and $p$. The most effective way for proceeding is to introduce normal ordering in each the operators \[\text{,} \] by making use of the formula

\[q^k p^\ell = \sum_{\alpha=0}^k B_{\alpha,k,\ell} p^{\ell-\alpha} q^{k-\alpha}, \tag{24}\]

with

\[B_{\alpha,k,\ell} = \frac{(-i\hbar)^\alpha \Gamma(k+1) \Gamma(\ell+1)}{\alpha! \Gamma(k-\alpha+1) \Gamma(\ell-\alpha+1)}, \quad (k \geq 0, \ell > 0) \tag{25}\]

for $\ell > 0$, otherwise

\[B_{\alpha,k,\ell} = \frac{(-i\hbar)^\alpha \Gamma(k+1) \Gamma(\alpha-\ell)}{\alpha! \Gamma(k-\alpha+1) \Gamma(-\ell)}, \quad (k \geq 0, \ell < 0). \tag{26}\]

By virtue of this, Equation (23) can be afterward expressed as

\[\mathcal{O}_{k,m,n,s,t,u,v}^r = C^{\text{nor}}_{B^{\text{nor}}} \sum_{j_i=0}^{m-1} D_{m,j_i} \sum_{\alpha_i=0}^{\delta_i} B_{\alpha_i,\delta_i,\gamma_i} p^{\ell-(r+1)m+J_r-A_r-s-t} q^{rm-J_r-A_r+s+t} \tag{27}\]

where

\[J_r = \sum_{\ell=1}^{r} j_{\ell}, \quad A_r = \sum_{\ell=0}^{r+1} \alpha_{\ell}, \tag{28}\]

and

\[
\delta_i = \begin{cases} 
  t & \text{if } i = 0 \\
  m - j_i & \text{if } 1 \leq i \leq r \\
  s & \text{if } i = r + 1 
\end{cases}, \\
\gamma_i = \begin{cases} 
  n - k - t - v & \text{if } i = 0 \\
  n - im - k - t + J_i - A_{i-2} - \beta_i & \text{if } 1 \leq i \leq r \\
  n - im - s - t - u + J_{i-1} - A_{i-1} & \text{if } i = r + 1 
\end{cases} \tag{29}\]

To invoke back the $T_{m,n}$ basis defined through equation (3), we will use the relation

\[p^a q^b = T_{a,0} T_{0,b} = \sum_{c=0}^{\infty} \sum_{d=0}^{\infty} F_{a,b,c,d} T_{a-c,b-c} \tag{30}\]

with

\[F_{a,b,c,d} = \frac{1}{c!} \left(\frac{i}{2}\right)^c \left[\frac{e^c}{(c-d)!}d!\right] \frac{\Gamma(a+1) \Gamma(b+1)}{\Gamma(a+1-d) \Gamma(b+1-d) \Gamma^2(d-2c)}, \tag{31}\]

that can be simplified according to

\[p^a q^b = T_{a,0} T_{0,b} = \sum_{c=0}^{b} \left(\frac{-i\hbar}{2}\right)^c \frac{\Gamma(1-a) \Gamma(1+b)}{\Gamma(1-a-j) \Gamma(1+b-j)} T_{a-c,b-c} \tag{32}\]

whenever the powers of $p$ are always non-positive and the powers of $q$ are always non-negative. We obtain therefore the final result for formula (24):

\[\mathcal{O}_{k,m,n,s,t,u,v}^r \sum_{c=0}^{\infty} \sum_{d=0}^{\infty} \sum_{\alpha_i=0}^{\delta_i} B_{\alpha_i,\delta_i,\gamma_i} F_{a,b,c,d} T_{a-c,b-c}, \tag{33}\]

where $a = n - (r+1)m + J_r - A_r - s - t$ and $b = rm - J_r - A_r + s + t$. This completes the derivation of how Weyl-ordered Bender-Dunne basis elements transform under linear transformations (15).
A. The subclass of canonical transformations \(^{(16)}\).

Let us now consider the canonical transformation \(^{(6)}\) with time dependent coefficients given in \(^{(10)}\), i.e. Eq. \(^{(16)}\). In this case the general structure for the operators \(T^{c}_{m,n}\) simplifies to

\[
T^{c}_{m,n} = \frac{1}{2^n \rho^m (m+n)} \sum_{r=0}^{\infty} (-1)^r \sum_{k=0}^{n} \binom{n}{k} \mathcal{O}^{r}_{k,m,n},
\]

where

\[
\mathcal{O}^{r}_{k,m,n} = \left( -\frac{m\dot{\rho}}{\rho} \right)^{mr} q^k \left\{ \sum_{j=0}^{m-1} D_{m,j} T_{j,m-j} p^{-m} \sum_{\beta=1}^{j} D_{j,\beta} \sum_{\alpha=0}^{\delta_i} B_{\alpha,\delta_i,\gamma_i} \right\}^{r} q^{n-k}.
\]

By virtue of this, after some manipulations, we can write a closed form expression for each operator \(\mathcal{O}^{r}_{k,m,n}\):

\[
\mathcal{O}^{r}_{k,m,n} = \frac{1}{2^n} \left( -\frac{m\dot{\rho}}{\rho} \right)^{mr} \sum_{k=0}^{n} \binom{n}{k} \sum_{j=0}^{m-1} \frac{D_{m,j}}{2^n j^{i_1}} \sum_{\beta=1}^{j} \frac{B_{\alpha,\delta_i,\gamma_i}}{\delta_i} \sum_{\alpha=0}^{\delta_i} \left( -\frac{i\hbar}{2} \right)^{i_2} \frac{\Gamma(1-a)}{\Gamma(1-a-j)} \frac{\Gamma(1+b)}{\Gamma(1-b-j)} T_{a-c,b-c}.
\]

where

\[
d_r = \sum_{\ell=1}^{r+1} (j_{\ell} - \alpha_{\ell}), \quad s_r = \sum_{\ell=1}^{r+1} (j_{\ell} + \alpha_{\ell}),
\]

\[
\delta_i = m - j_i, \quad (i = 1, 2 \ldots r), \quad \delta_{r+1} = k
\]

and

\[
\gamma_i = \sum_{\ell=1}^{i} j_{\ell} - \sum_{\ell=1}^{i-1} \alpha_{\ell} - \beta_i - im = d_{i-2} + j_i - \beta_i - im
\]

(we have assumed that \(\sum_{\alpha=n_0}^{n} = 0\) if \(n < n_0\) and \(\beta_{r+1} = j_{r+1} = 0\). Hence, taking into account \(^{(32)}\), from equation \(^{(36)}\) we obtain

\[
\mathcal{O}^{r}_{k,m,n} = \frac{1}{2^n} \left( -\frac{m\dot{\rho}}{\rho} \right)^{mr} \sum_{k=0}^{n} \binom{n}{k} \sum_{j=0}^{m-1} \frac{D_{m,j}}{2^n j^{i_1}} \sum_{\beta=1}^{j} \frac{B_{\alpha,\delta_i,\gamma_i}}{\delta_i} \sum_{\alpha=0}^{\delta_i} \left( -\frac{i\hbar}{2} \right)^{i_2} \frac{\Gamma(1-a)}{\Gamma(1-a-j)} \frac{\Gamma(1+b)}{\Gamma(1-b-j)} T_{a-c,b-c}.
\]

with \(a = -(r+1)m + d_r, b = n + rm - s_r\). Since \(a\) is always negative, we can use the identity

\[
\frac{\Gamma(1-a)}{\Gamma(1-a-j)} = (-1)^j \frac{(-a-1+j)!}{(-a-1)!}, \quad a < 0
\]

and perform the change of variable \(a \rightarrow -a\) in \(^{(40)}\), that becomes

\[
\mathcal{O}^{r}_{k,m,n} = \frac{1}{2^n} \left( -\frac{m\dot{\rho}}{\rho} \right)^{mr} \sum_{k=0}^{n} \binom{n}{k} \sum_{j=0}^{m-1} \frac{D_{m,j}}{2^n j^{i_1}} \sum_{\beta=1}^{j} \frac{B_{\alpha,\delta_i,\gamma_i}}{\delta_i} \sum_{\alpha=0}^{\delta_i} \left( -\frac{i\hbar}{2} \right)^{i_2} \frac{\Gamma(1+a-1+j)!}{(b-j)!(a-1)!} T_{a-c,b-c}.
\]

where now \(a = (r+1)m - d_r, b = -n - rm + s_r\). In turn, it follows that the operators \(T^{c}_{m,n}\) in \(^{(34)}\) are expressed in terms of the Bender-Dunne basis operators \(^{(3)}\) by means of the formula

\[
T^{c}_{m,n} = \frac{1}{2^n} \left( -\frac{m\dot{\rho}}{\rho(t)^{n+m}(r+1)} \right) \sum_{r=0}^{\infty} (-1)^r \sum_{k=0}^{n} \binom{n}{k} \sum_{j=0}^{m-1} \frac{D_{m,j}}{2^n j^{i_1}} \sum_{\beta=1}^{j} \frac{B_{\alpha,\delta_i,\gamma_i}}{\delta_i} \sum_{\alpha=0}^{\delta_i} \left( -\frac{i\hbar}{2} \right)^{i_2} \frac{\Gamma(1+a-1+j)!}{(b-j)!(a-1)!} T_{a-c,b-c}.
\]
The criterion significantly simplifies the formula for the operator for this particular case. Formulation (42) has a rather different structure as compared to the one attributed to the polynomials associated with the product of positive powers of position and momentum operators subjected to linear transformations. In particular, it is represented by an infinite sum of operator terms. Precisely, the latter form can be obtained by making essential use of the worthwhile identities

\[ T_{r,r} = \frac{1}{2} \left( -\frac{1}{q} \right)^r + \frac{1}{2} \left( \frac{1}{q} \right)^r = \frac{1}{2} X^r + \frac{1}{2} Y^r , \]

and

\[ \sum_{r=n+1}^{\infty} (-1)^r \frac{r-1}{n-1} z^r = z^n \left( 1 + (1 - z)^{n-r} \right) . \]

Equation (45) may in fact effectively work as an operating expedient in some investigations.

**IV. CLASSICAL VS. QUANTUM POSITION AND MOMENTUM EXPANSIONS OF OBSERVABLES**

In next Sections, some examples will be given as of the application of Weyl-ordered basis à la Bender-Dunne to basic problems pertinent the integrability of quantum non-autonomous systems. Before doing so, however, we would like to make some remarks on the reliability of quantization and dequantization procedures in connection to a given hamiltonian problem. In fact, direct quantization of classical solutions in phase space generally fails (with exceptions whose existence will be intelligible later) in representing the solution to the quantum version of the same equations obtained on algebraic grounds via the substitution of Poisson brackets with commutators. A quantum operator equations has to be investigated *per se*, even if we already have a solution for its classical relative. In...
translating a classical dynamical equation into a quantum one, there is an issue in respect to the proper transfer of algebraic features into the solutions. The root cause is that at the classical level there are no ordering rules, as opposite to the quantum level: the difference equation one would obtain for expansion coefficients in a classical basis of a classical dynamical object obeying an algebraic condition (in the Poisson brackets algebra sense) commonly differs from the difference equation one would obtain for expansion coefficients in a quantum analogous of the same basis for the observable required to obey the condition after replacing Poisson brackets through commutators. If we have a classical observable represented in one basis (like the set of products of position and momentum powers \( t_{m,n} = p^m q^n \), associated with Laurent-type expansions), relations between coefficients are structurally simpler because the Poisson-brackets formalism introduces algebraic aspects that only concern scalar functions and their derivatives, i.e. commutative objects. In different words, while the direct dequantization of operator equations and theirs solutions ends up into the forms arising for the solution to the classical problem, the converse is not true: direct dequantization of operator equations and theirs solutions does not capture all the features implied by the solution of the quantum version of the dynamical equation. For arbitrary dynamical variable the aspect is an acute, in the meaning which can be desumed for the simple discussion below. For illustrating effectively the point, it is enough to focus on the observable canonically conjugated to the Hamiltonian in the simple case of an autonomous system whose quantum (classical) dynamics is conducted by a power-law potential, namely by the quantum (classical) Hamiltonian

\[
H_L = \frac{p^2}{2} + \frac{q^L}{L}
\]  

where \( L \) is a positive integer. The discussion can be immediately adapted to other observables and to the class of non-autonomous analytical potentials, though. Let us consider therefore the formal expansion in the Bender-Dunne basis

\[
\Theta_L = \sum_{m,n} \alpha_{m,n} T_{m,n}
\]  

for the operator \( \Theta_L \) canonically conjugate to \( H_L \) through the operator equation \([\Theta_L, H_L] = i\hbar \). From the algebra of the \( T_{m,n} \) operators

\[
[T_{m,n}, T_{r,s}] = 2 \sum_{j=0}^{\infty} \frac{1}{(2j+1)!} \left( \frac{i\hbar}{2} \right)^{2j+1} (-1)^j \begin{pmatrix} 2j+1 \\ l \end{pmatrix} \times \\
\times \frac{\Gamma(m+1)\Gamma(n+1)\Gamma(r+1)\Gamma(s+1)}{\Gamma(m-l+1)\Gamma(n+l-2j)\Gamma(r+l-2j)\Gamma(s-l+1)} T_{m+r-2j-n,s-2j-1} = i\hbar(n-r) T_{m+r-1,n+s-1} + \sum_{j=1}^{\infty} \left( \frac{i\hbar}{2} \right)^{2j+1} \frac{\Gamma(n+1)\Gamma(r+1)}{(2j+1)!\Gamma(n-2j)\Gamma(r-2j)} \times \\
\times \begin{pmatrix} 3F2 \end{pmatrix} [-1-2j,-m,-s; -2j+n,-2j+r;1] T_{m+r-2j-1,n+s-2j-1}
\]  

we know that

\[
[T_{m,n}, p^2] = 2i\hbar n T_{m+1,n-1}
\]

\[
[T_{m,n}, q^L] = -i\hbar L m T_{m-1,n+L-1} - i\hbar \sum_{j=1}^{(L-1)/2} \hbar^{2j} A_{m,j,L} T_{m-2j-1,n+L-2j-1}
\]

where the nonvanishing coefficients \( A_{m,j,L} \) can be inferred from Eq. with \( r = 0 \) and \( s = L \),

\[
A_{m,j,L} = \frac{(-1)^j \Gamma(m+1)\Gamma(L+1)}{4^j (2j+1)!\Gamma(m-2j)\Gamma(L-2j)}
\]

So the quantum canonical conjugation relation \([\Theta_L, H_L] = i\hbar\) can be complied with if coefficients characterizing the realization of the observable \( \Theta_L \) fulfill the recursion equation

\[
(n+1)\alpha_{m-1,n+1} - (m+1)\alpha_{m+1,n-L+1} - \frac{1}{L} \sum_{j=1}^{(L-1)/2} \hbar^{2j} \alpha_{m+2j+1,n-L+2j+1} A_{m+2j+1,n-L+2j+1,L,j} = \delta_{m,n}\delta_{n,0}
\]
(we have used that \( 1 = \sum_{m,n} \delta_{m,0} \delta_{n,0} T_{m,n} \)). If we consider instead the problem classically, and resort to the use of the classical counterpart of the Bender-Dunne basis in phase space, the expansion in the \((p, q)\) coordinates pair

\[
\Theta_{L}^c = \sum_{m,n} \alpha_{m,n}^c t_{m,n} = \sum_{m,n} \alpha_{m,n}^c p^n q^n ,
\]

(55)

would be introduced for the variable \(\Theta_{L}^c\) conjugated to the classical form of Hamiltonian \(H_L\). This successively means that the classical condition of canonical pairing involving the Poisson brackets \(\{\Theta_{L}^c, H_L^c\} = p \partial_q \Theta_{L}^c - q L^{-1} \partial_p \Theta_{L}^c = 1\) generates the difference equation

\[
(n + 1) \alpha_{m-1,n+1}^c - (m + 1) \alpha_{m+1,n-s+1}^c = \delta_{m,0} \delta_{n,0}^c \]

(56)

for the coefficients \(\alpha_{m,n}^c\). Hence, direct quantization of the dynamical variable \(\Theta_{L}^c\) through the mere substitution of the basis elements \(t_{m,n}\) with their quantum analogous \(T_{m,n}\) is not enough to comprise additional features of quantum analogue of the same dynamical problem due to the quantum ordering. In fact, while dequantization of an observable solving an assigned quantum equation naturally ends up in its classical counterpart obtained by solving the same formal equation after the replacement of commutators through Poisson brackets, something may be lost when the converse procedure of straight quantization of a classical observable is performed.

V. EXAMPLES. I. TIME-DEPENDENT QUADRATIC HAMILTONIAN SYSTEMS

As we anticipated, in the present and the next Sections we make some examples concerning the application of Weyl-ordered basis a là Bender-Dunne to basic problems pertinent the integrability of quantum non-autonomous systems whenever the condition (11) on the potential is fulfilled, such as in the cases where the dependence of potential on position is through a power-law term or a series whose time-dependent coefficients scale by a factor at the same power of the coordinate one. Our investigation will be confined to the former case. In particular, the general formulation of the problems that we will analyze is as follows: Let a non-autonomous hamiltonian system (4) be given and let \(I \equiv I(q,p,t)\) be an invariant operator for the system. Which is the operator \(\Theta \equiv \theta(q,p,t)\) formally conjugated to \(I\) via the commutator equation

\[
[I, \Theta] = i\hbar ,
\]

(57)

and how can we express \(\Theta\) in a Weyl-ordered basis of position- and momentum-type operators?

To answer this query, we will be actuated by the discussions and remarks given in the previous Sections. In particular, solutions to (57) will be derived in the time-dependent basis.

We start the discussion of examples by considering the time dependent Hamiltonian

\[
H = \frac{p^2}{2m(t)} + \frac{1}{2} m(t) \omega(t)^2 q^2 ,
\]

(58)

which can be mapped into the new non-autonomous Hamiltonian

\[
H' = \frac{1}{2m\rho^2} H_0 , \quad H_0 = P^2 + Q^2 ,
\]

(59)

by means of a linear canonical transformation of the type \(L\). An invariant operator \(I(q,p,t) = U H_0 U^{-1}\) can be devised contextually which reads

\[
I(q,p,t) = \rho^2 \rho^2 - m \rho \dot{\rho} (pq + qp) + (m^2 \rho^2 + \rho^{-2}) q^2 .
\]

(60)

The operator function \(\Theta(q,p,t)\) canonically conjugated to \(I(q,p,t)\) can be found as a series expansion in the \(T_{r,s}\) basis,

\[
\Theta(q,p,t) = \sum_{r,s} \alpha_{r,s} \ T_{r,s} ,
\]

(61)

The resulting recursion relation for the coefficients \(\alpha_{r,s}\) in (11) is

\[
\rho^2 (s + 1) \alpha_{r-1,s+1} - (m^2 \rho^2 + \rho^{-2})(r + 1) \alpha_{r+1,s-1} - (s - r) m \rho \dot{\rho} \alpha_{r,s} = \frac{1}{2} \delta_{r,0} \delta_{s,0} .
\]

(62)
We look for the minimal solution to (62), where by minimal solution we mean the solution with starting point \( \alpha_{-1,1} = 1/(2\rho^2) \) and \( \alpha_{r,s} = 0 \) for \( r \leq 2 \) and \( s \). In doing so, we first reduce the recursion relation (62) to a one-index recursion relation with the substitution \( s = k = -r \). Redefining the coefficients as

\[ A_k = \alpha_{r-1,s+1} = \alpha_{-k-1,k+1}, \]

equation (62) for the \( A_k \)'s thus becomes

\[ \rho^2(k+1)A_k + (m^2\rho^2 + \rho^{-2})(k-1)A_{k-2} - 2k m \rho \dot{\rho} A_{k-1} = 0, \]

with initial condition \( A_0 = 1/(2\rho^2) \). Equation (64) turns into a recursion relation with constant coefficients after the substitution \( A_k = \frac{B_k}{(k+1)!} \), i.e.

\[ \rho^2 B_k + (m^2\rho^2 + \rho^{-2}) B_{k-2} - 2k m \rho \dot{\rho} B_{k-1} = 0, \quad B_0 = \frac{1}{2\rho^2}. \]

The idea for solving (65) is to guess a solution of the form \( B_k = x^k \) for some number \( x \). To fix the values of \( x \) we substitute this expression into (65) and identify the two roots

\[ x_{\pm} = \frac{m(t) \rho \dot{\rho} \pm i}{\rho^2}. \]

The general solution of (65) is then \( B_k = c_+ x^k_+ + c_- x^k_- \) with \( c_+ \) and \( c_- \) to be determined by imposing the initial conditions \( B_0 = \frac{1}{2\rho^2} \) and \( B_1 = \frac{m(t) \dot{\rho}}{\rho^3} \), i.e.

\[ c_{\pm} = \frac{(1 \pm m(t) \rho \dot{\rho})}{4 \rho^2}. \]

The final expression for the operator \( \Theta(q,p,t) \) is then

\[ \Theta(q,p,t) = \frac{1}{4 \rho^2} \sum_{k=0}^{\infty} A_k T_{-k,k} \]

with coefficients

\[ A_k = \frac{(1 + m \rho \dot{\rho})^{k+1} + (-1)^{k}(1 - m \rho \dot{\rho})^{k+1}}{(k + 1) \rho^{2k}} \]

Instead of solving eq. (62), we may rely on the results of Sec III which suggest i) to solve the easier recursion relation for the operator \( \Theta_0(Q,P) = \sum_{m,n} \alpha_{m,n} T_{m,n} \) canonically conjugate to the Hamiltonian \( H_0 \) in (69) in the \( T_{m,n} \) basis

\[ (n+1)\alpha_{m-1,n+1} - (m+1)\alpha_{m+1,n-1} = \delta_{m,0}\delta_{n,0}, \]

whose solution gives (21, 25)

\[ \Theta_0 = \sum_{k=0}^{\infty} \frac{(-1)^k}{2k+1} T_{-2k-1,2k+1}, \]

and then ii) to express the basis elements \( T_{-2k-1,2k+1} \) of (70) in terms of the basis elements \( T_{m,n} \) in the \( (q,p) \)-representation obtained from (14) with \( n = 2k+1 \). The series expression for the operator \( \Theta \) will then be

\[ \Theta = \sum_{k=0}^{\infty} \frac{(-1)^k}{2k+1} \left[ \rho^{-4k-2} T_{-2k-1,2k+1} + \frac{1}{(m \rho \dot{\rho})^{2k+1}} \sum_{r=2k+2}^{\infty} (-1)^r \left( \frac{r-1}{2k} \right) \left( -\frac{m \dot{\rho}}{\rho} \right)^r T_{-r,r} \right], \]

or, by using (14),

\[ \Theta = \frac{1}{2} \arctan \left[ \frac{X}{\rho^2} \left( 1 - \frac{m \dot{\rho}}{\rho} \right) X^{-1} \right] + \frac{1}{2} \arctan \left[ \frac{Y}{\rho^2} \left( 1 - \frac{m \dot{\rho}}{\rho} \right) Y^{-1} \right]. \]

It is easy to check that the coefficients of each \( T_{-n,n} \) in (67, 68) and (71) coincide.
VI. EXAMPLES. II. TIME DEPENDENT LINEAR HAMILTONIAN SYSTEMS

In this Section we shall consider a system ruled by the non-autonomous Hamiltonian

\[ H = \frac{1}{2} \left[ z(t) p^2 + \frac{z(t)}{2\rho(t)^2} q \right], \quad (73) \]

for which the adoption of canonical linear transformation \( \Theta \) with coefficients \( \Theta_{0} \) results into the new Hamiltonian

\[ H' = \frac{z(t)}{2\rho(t)^2} H_0, \quad \text{with} \quad H_0 = P^2 + Q^2 + q. \quad (74) \]

So, the Hamiltonian formulation of the dynamical problem governed by Equation (73) is time-diffeomorphic to an autonomous system whose Hamiltonian is of the form \( H_0 = P^2 + Q^2 + Q \). In other words, a genuine harmonic oscillator underlies the case up to a constant shift of position \( Q \) (and of the energy), \( Q \to Q = Q + 1/2 \) and \( H_0 = P^2 + Q^2 + Q \to P^2 + Q^2 - 1/4 \), accordingly. Solutions to operator dynamical equations having a physical meaning for a system described via (73) can be thus tailored throughout their corresponding in the harmonic oscillator model. The option of minimal and non-minimal solutions can be argued on similar basis. For the sake of completeness and homogeneity with the rest of the paper, and also because instructive, in the sequel explicit computation of solution to the integrability condition in stationary form for the system (73) will be performed by keeping the operator form (73), without reference to the solution for the same problem in the case of purely quadratic Hamiltonian. Let us start therefore by working out an invariant according to the arguments already expounded. By operating with the inverse transformation on the Hamiltonian \( H_0 \) in (74), the dynamical invariant

\[ I = \rho^2(t) p^2 + \beta(t) q^2 - \gamma(t)(pq + qp) + \rho^{-1}(t) q, \quad (75) \]

is then obtained for (74), where

\[ \beta(t) = \rho(t)^{-2} + \frac{\dot{\rho}(t)^2}{z(t)^2}, \quad \gamma(t) = \frac{\dot{\rho}(t)\rho(t)}{z(t)}. \quad (76) \]

Seeking a Weyl expansion solution in Bender-Dunne basis \( \{T_{m,n}\} \) for the operator \( \Theta \) formally conjugated to the operator \( \Theta_0 \) via Equation (77), therefore leads to the difference equation

\[ \rho(t)^2(n + 1)\alpha_{m-1,n+1} - \beta(t)\alpha_{m+1,n-1} - \gamma(t)(n - m)\alpha_{m,n} - \frac{1}{2\rho(t)}(m + 1)\alpha_{m+1,n} = \frac{1}{2} \delta_{m,0}\delta_{n,0} \quad (77) \]

for the time-dependent coefficients \( \alpha_{m,n} \) connoted in the expansion \( \Theta = \sum_{m,n} \alpha_{m,n} T_{m,n} \). To the same solution one would arrive by considering \( H_0 = P^2 + Q^2 + Q \) and solving the quantum integrability condition \( \{\Theta_0, H_0\} = \text{ih} \) in a Weyl series expansion in the \( \{T_{m,n}\} \) basis. In particular, assuming \( \Theta_0 = \sum_{m,n} \alpha_{m,n} T_{m,n} \) the equation \( [\Theta_0, H_0] = \text{ih} \) is conveyed onto the difference equation

\[ 2(n + 1)\tilde{\alpha}_{m-1,n+1} - 2(m + 1)\tilde{\alpha}_{m+1,n-1} - (m + 1)\tilde{\alpha}_{m+1,n} = \delta_{m,0}\delta_{n,0} \quad (78) \]

for the time-independent expansion coefficients \( \tilde{\alpha}_{m,n} \). The minimal solution corresponds to the choice \( \tilde{\alpha}_{1,1} = 1/2 \) and \( \tilde{\alpha}_{1,-1} = \tilde{\alpha}_{1,0} = 0 \). By using the inverse Liouville method expounded in [28] and summarized in Appendix A, we guess the general formula of the operator \( \Theta \) that is

\[ \Theta_0 = \sum_{k=0}^{\infty} \sum_{j=0}^{k} A_{k,j} T_{-2k-1,2k-j+1} \quad (79) \]

where the coefficients \( A_{k,j} \) must be determined. Equation (79) suggests the following transformation

\[ A_{k,j} = \tilde{\alpha}_{-2k-1,2k-j+1} = \tilde{\alpha}_{m-1,n+1} \quad (80) \]

along with the constraint \( A_{k,j} = 0 \) for \( k < 0 \) and \( j > k \). That means \( k = \frac{-m}{2} \) and \( j = -m - n \), \( (0 \leq j \leq k) \). The new recursion relation then reads

\[ (2k - j + 1)A_{k,j} + (2k - 1)A_{k-1,j} + (2k - 1)A_{k-1,j-1} = \delta_{k,0}\delta_{j,0}, \quad (81) \]
whose solution is

\[ A_{k,j} = \frac{(-1)^k}{2k+1} \binom{2k+1}{j}, \]  

so that

\[ \Theta_0 = \sum_{k=0}^{\infty} \sum_{j=0}^{k} \frac{(-1)^k}{2k+1} \binom{2k+1}{j} T_{-2k-1,2k-j+1}. \]  

For solving the time-dependent problem, we need to transform the basis elements in \( T \) according to (42). Remark that in this case we can also apply the relation

\[ T_{-2k-1,2k+1-j} = \frac{i^j (2k+1-j)!}{(2k+1)!} [P, [P, \ldots [P, T_{-2k-1,2k+1}] \ldots]]_{j-times}, \]

and recognize that formally

\[ T_{-2k-1,2k+1-j} \equiv \frac{i^j (2k+1-j)!}{(2k+1)!} \left[ \rho \left( \frac{\mu}{\rho} \right)^m \right] \left( \frac{\mu}{\rho} \right)^r \Gamma(r+2k+1) T_{-r,r}. \]

VII. EXAMPLES. III. TIME-DEPENDENT QUARTIC HAMILTONIAN SYSTEMS

In this Section we shall detail the analysis of the quantum integrability of a non-autonomous hamiltonian system associated with the quartic Hamiltonian

\[ H = \frac{z(t)}{2} \left[ p^2 + \frac{q^4}{2\rho(t)^6} \right], \]

by exploiting the same arguments exposed in previous sections. By application of the canonical coordinate transformation under consideration in this communication, the Hamiltonian \( \Theta \) can be mapped into

\[ H' = \frac{z(t)}{2\rho(t)^2} H_0, \quad H_0 = \frac{P^2 + Q^2}{2} + \frac{Q^4}{4}. \]

Furthermore, a dynamical invariant for \( \Theta \) is obtained which reads:

\[ I = \eta(t) p^2 + \beta(t) q^2 - \gamma(t)(pq + qp) + \delta(t) q^4, \]

where \( \eta(t) = \rho(t)^2, \delta(t) = \rho(t)^{-4}, \) and \( \beta(t) \) and \( \gamma(t) \) take the same form as in the linear case (i.e., \( \beta(t) = \rho(t)^{-2} + \frac{(\rho(t)^2)}{2} \) and \( \gamma(t) = \frac{(\rho(t)^2)}{z(t)}; \) Eq. (76)). We are interested in solutions to the integrability condition \( [\Theta, I] = i\hbar, \) with \( I \) given by equation (84) above. Once a solution is sought in the basis \( T_{m,n} \) by means of \( \Theta = \sum_{m,n} \alpha_{m,n} T_{m,n}, \) the recursion relation

\[ 2\eta(t)(n+1)\alpha_{m-1,n+1} - 2\beta(t)(m+1)\alpha_{m+1,n-1} - 2\gamma(t)(n-m)\alpha_{m,n} - 4\delta(t)(m+1)\alpha_{m+1,n-3} + \delta(t)(m+3)(m+2)(m+1)\alpha_{m+3,n-1} = \delta(t)(m+3)(m+2)(m+1)\alpha_{m+3,n-1} \]

is obtained for coefficients \( \alpha_{m,n}. \) With the aim of selecting minimal solution, for \( m = n = 0 \) we choose \( \alpha_{1,-1} = \alpha_{1,3} = 0 \) and \( \alpha_{-1,1} = \frac{1}{2\eta(t)} \). With the transformation \( M = \frac{1}{6}(2n + m + 4K - A), N = \frac{1}{6}(n - m + 2K - 2A), 0 \leq A \leq \frac{1}{3}(n + 2), 0 \leq K \leq \frac{1}{3}(5n + 3m - 2) \) we define the new dependent variable

\[ C_{N,M,K,A} = \alpha_{-4N+2M-A-1,2N+2M-2K+A+1} = \alpha_{m,n+1} \]
along with the constraint that $C_{N,M,K,A} = 0$ for $N,M,K,A \leq 0$, $N \leq M \leq K$ and $A \leq M + N - K + 1$. The difference equation for time-dependent coefficients $C_{N,M,K,A}(t)$ arises in the form

$$
\eta(t)(2M + 2N - 2K + A + 1)C_{N,M,K,A} + \beta(t)(4N - 2M + A - 1)C_{M-1,N-1,K-1,A} - 2\gamma(t)(3N + A - K)C_{N-1,M-1,K-1,A+1} + 2\delta(t)(4N - 2M + A - 1)C_{N-1,M-1,K,A} - \delta(t)(4N - 2M + A - 1)(4N - 2M + A - 2)(4N - 2M + A - 3)C_{N-1,M,K,A} = \frac{1}{2}\delta_{N,0}\delta_{M,0}\delta_{K,0}\delta_{A,0}
$$

Then

$$
\Theta = \sum_{N=0}^{\infty} \sum_{M=0}^{\infty} \sum_{K=0}^{\infty} \sum_{A=0}^{M-N+K+1} C_{N,M,K,A}(t) T_{-4N+2M-A-1, 2N+2M-2K+A+1} \quad (90)
$$

On the other hand, by considering, in the $Q,P$ coordinates, the operator $\Theta_0(Q,P) = \sum_{m,n} \delta_{m,n} T_{m,n}$ and the integrability condition $[H_0, \Theta_0] = i\hbar$ for the stationary quartic-type potential hamiltonian $H_0$ in (88), we get the recurrence constraint

$$
(n + 1)\alpha_{m-1,n-1} - (m + 1)\alpha_{m+1,n-1} + \frac{\hbar^2}{4}(m + 1)(m + 2)(m + 3)\alpha_{m+3,n-1} - (m + 1)\alpha_{m+1,n-3} = \delta_{m,0}\delta_{n,0}. \quad (91)
$$

Equation (91) differs by the last term in the left hand side from the equation one would obtain for the quartic oscillator $H_{BD} = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2}$, the case studied by Bender and Dunne in [20] (and later also by Galapon in [28] by exploiting the Inverse Liouville method). The structure of the minimal operator $\Theta_0$ can be written as

$$
\Theta_0 = \sum_{N=0}^{\infty} \sum_{M=0}^{N} \sum_{K=0}^{N-M} A_{M,N,K} T_{-2N-2M-1, 4N-4M-2K+1}, \quad (92)
$$

as it is also suggested by the inverse Liouville method (see Appendix A). By performing the transformation $m = -2M - 2N$ and $n = 4N - 2M - 2K$, the coefficients $A_{M,N,K}$ result connected to the coefficients $\alpha_{m,n}$ through the relation

$$
A_{M,N,K} = \alpha_{m-1,n+1} = \tilde{\alpha}_{-2N-2M+1, 4N-4M-2K+1} \quad (93)
$$

with the constraint $A_{N,M,K} = 0$ for $N,M,K \leq 0$, $N \leq M$ and $M \leq K$. So, the recursion relation (91) becomes

$$
\delta_{M,0}\delta_{N,0}\delta_{K,0} = (4N - 2M - 2K + 1)A_{M,N,K} + (2N + 2M - 1)A_{M-1,N-1,K-1} - \frac{\hbar^2}{4}(2N + 2M - 3)(2N + 2M - 2)(2N + 2M - 1)A_{M-1,N-1,K} + (2N + 2M - 1)A_{M,N-1,k} \quad (94)
$$

A further transformation reduces the partial difference equation -now of the first order in the $N,M,K$’s variables- to one whose coefficients are linear functions of $N,M,K$. To do this, we define

$$
B_{NMK} = \frac{2^{-N} \Gamma(1/2)}{\Gamma(N + M + 1/2)} A_{M,N,K}, \quad (95)
$$

along with the constraint that $B_{NMK} = 0$ for $N,M,K \leq 0$, $N \leq M$ and $M \leq K$. This enables us to obtain

$$
\delta_{M,0}\delta_{N,0}\delta_{K,0} = (4N - 2M - 2K + 1)B_{NMK} + B_{M,N-1,K-1} + B_{M,N-1,K} - \hbar^2(N + M - 1)B_{M-1,N-1,k}. \quad (96)
$$

It is simple to derive closed-form expressions for some sets of coefficients, e.g.

$$
B_{NN0} = \frac{\hbar^{2N}}{1 + 2N}, \quad N \geq 0, \quad B_{0N0} = \frac{(-1)^N \Gamma(5/4)}{4^{N} \Gamma(N + 5/4)}, \quad N \geq 0.
$$

Finally, a transformation allows to factor the $K$-index dependence out of the coefficients $B_{M,N,K}$. In fact, with the substitution

$$
B_{M,N,K} = \left(\frac{2N - M + 1/2}{M}\right) C_{M,N}, \quad (97)
$$

the recursion relation (96) takes the final form

$$
\delta_{M,0}\delta_{N,0} = (4N - 2M + 1)C_{MN} + C_{M,N-1} - \hbar^2(N + M - 1)C_{M-1,N-1}, \quad (98)
$$
that is exactly the recursion relation found in [21] for the angle variable for the quartic oscillator.

In the light of the above discussion and of results in [21], the following statement can be formulated to summarize the traits of the solution to the considered problem: The minimal angle-type operator \( \Theta_0 \) conjugated via \([H_0, \Theta_0] = i\hbar\) to the Hamiltonian operator \( H_0 = p^2 + \frac{Q^4}{4} + Q^2 \) takes the form

\[
\Theta = \sum_{N=0}^{\infty} \sum_{M=0}^{N} \sum_{K=0}^{N-M} \left( \frac{2N - M + 1/2}{K} \right) C_{M,N} \left. T_{-2N-2M-1,4N-2M-2K+1} \right)
\]

where the coefficients \( C_{m,n} \) can be expressed as

\[
C_{M,N} = \frac{1}{M!N!} \left( \frac{\partial}{\partial x} \right)^M \left( \frac{\partial}{\partial y} \right)^N g(x, y)\big|_{x=y=0},
\]

being \( g(x, y) \) the generating function given in [21]

\[
g(x, y) = \int_0^1 \frac{d\xi}{2\sqrt{\xi(1-xy\xi)}} \exp \left\{ \frac{1}{2xy} \left( \frac{2}{3} - xy + \frac{(1-xy)^{3/2}(xy\xi - 2/3)}{(1-xy\xi)^{3/2}} \right) \right\};
\]

equivalently \((N + M \to R)\),

\[
\Theta = \sum_{N=0}^{\infty} \sum_{R=N}^{2N} \sum_{K=0}^{2N-R} \tilde{C}_{N,R,K} T_{-2R-1,6N-4R-2K+1} \tilde{C}_{R-N,N} = \left( \frac{3N - R + 1/2}{K} \right) C_{R-N,N}.
\]

Formula (12) can be eventually appealed to write down the formal solution \( \Theta(q, p, t) \) to the operator equation \([I, \Theta] = i\hbar \) with the invariant \( I \) given by [90].

VIII. CONCLUSIONS

This communication has been concerned with the problem of solving operator equations in phase space. In particular, we entertained angle-like operators underlying Hamiltonian systems. For autonomous Hamiltonian systems, their defining equation corresponds to the condition that the sought operator is formally conjugated with the Hamiltonian (a condition that, as mentioned in the Introduction, may be seen as an integrability condition for the system, in that at the classical level it ensures the consistency and completeness of the description of evolution and level curves on the time parameter). For systems for which a non-autonomous Hamiltonian is given, the condition changes in that the Hamiltonian is no longer the generating function (conserved charge) for time translations. However, while it gets more involved, the defining problem share analogous technical traits and introduces similar conceptual peculiarities. So far, operator equations in phase space have been approached mainly in regard to conservative systems and by considering a Schrödinger (i.e. fixed time) representation of the Weyl ordered operator of the Bender-Dunne basis. Our aim here has been twofold. From one side, we have been interested in providing and explicit representation of the basis elements in a time-dependent representation. In order to make very manifest the influence of the time-dependence on the realization of the new basis, as the class of transformations to superimpose to operators basis in phase space we adopted the linear time-dependent canonical ones. We put forward explicit formulas expressing the relationship between elements of the Bender-Dunne basis element resulting in the two canonical pairs representations. Dealing with negative powers of operators involved, these formulas are supplementary to those that can be found in [32].

Over because of their simplicity, we considered linear time-depending canonical mappings in phase space partially inspired by the line undertook by Mostafazadeh in [20], as well as by the manner in which symplectic time rescaling approaches are employed for the development of adaptive techniques in molecular dynamics simulations [13-15]. By focusing on the simplest of these problems, we next moved to our second scope of solving some concrete examples of operator equations in phase space that pertain non-autonomous systems. In doing so, we focused on the equations defining angle-like operators conjugated to invariants in some simple non-autonomous cases such as the linear, the quadratic and the quartic type potentials. We have performed therefore a comparative study of the treatment of these equations through the use of two different basis for the space of solutions, that is the Weyl-ordered basis [3] and the one that results by letting act on it the time-dependent canonical transformation yielding the identification of an invariant. Having already elements coming from the discussion of time-dependent quadratic Hamiltonians [33], the choice of canonical transformation we made has allowed a prompt comparison and confirmation of formulas derived in section [31]. Other than the quadratic ones, time-type operator for linear and quartic non-autonomous one-dimensional
Hamiltonian systems have been discussed. While selecting explicit solutions by demanding them to concur with minimal ones (the terminology is borrowed from [20]), a link with the the Inverse Liouville method (see Appendix VIII) has been also recalled. For time-dependent quartic Hamiltonian, the recurrence relations obtained for the coefficients of the sought minimal angle-like operator put into effect an explicit reappraisal of the operatorial chain Eq. (103) that formally expresses solutions obtained by the inverse Liouville solution. The minimal solution does not meet the formal structure of the solutions in the classical limit. This immediately stimulates the attention on a possible future development of the topic, because it will be interesting to explicitly resume to what extent the solutions structures suggested by the classical limit are really affected in the semiclassical limit. To this, one should perform analysis similar to those expounded in previous sections, but incorporating the first nontrivial terms in powers of Planck’s constant in the approximations of operators $T_{m,n}$. Succeeding in this investigation is expected to give new hints on the subject of classical/quantum transitions of dynamical systems.

Acknowledgments. M.G. acknowledges support from the Japan Society for the Promotion of Science (Fellowship grant PE14011). G.L has been partially supported by PRIN 2010 - MIUR "Teorie geometriche e analitiche dei sistemi Hamiltoniani in dimensioni finite e infinite". G.L is grateful to the Institute of Industrial Science of the University of Tokyo for the hospitality during his visit to perform part of the work.

Appendix A. Inverse Liouville Method

We summarize here the formal framework presented in [28] in regard to the treatment of the operator equation $[H, F] = i \hbar$ and its solutions, $H$ denoting a system’s Hamiltonian operator. The idea upon which the discussion there develops is that, once it is assumed that the inverse of the operator \( \mathcal{L}_H^{-1} \) exists (an hypothesis that holds true for analytic potentials), the formal solution for $F$ can be written as $F = i \hbar \mathcal{L}_H^{-1}$, an expression that can be further diversified. Precisely, if the Hamiltonian is split into its kinetic $K$ and potential $V$ parts, so that $H = K + V$, the operator $F$ that formally solves the operator equation under consideration $[H, F] = i \hbar$ (or, in Liouville form, $\mathcal{L}_H \cdot F = i \hbar 1$) can be given via the geometric expansion

\[
F = \sum_{k=0}^{\infty} (-1)^k F_k
\]

where $F_0$ denotes the purely kinetical contribution and all the other terms are obtained recursively, i.e.

\[
F_0 = \mathcal{L}_K^{-1} (i \hbar), \quad F_k = \left( \mathcal{L}_K^{-1} \mathcal{L}_V \right) F_{k-1}
\]  

(\( k \geq 1 \)). Being an operator in the space of pseudo-differentials over $L^2(R)$, $\mathcal{L}_K$ itself can be defined in terms of its action on Bender-Dunne basis operators. Terms in the expansion are accomplished accordingly.

For instance, application of the framework to the quartic Hamiltonian $H = p^2 + q^2 + q^4$ provides us with the zero-th order term $F_0 = -\frac{1}{2} T_{-1,1}$ and the expansion

\[
F = -\frac{1}{2} \sum_{k=0}^{\infty} (-1)^k \left( \mathcal{L}_K^{-1} \mathcal{L}_V \right)^k T_{-1,1},
\]  

the action of the composite operator $\mathcal{L}_K^{-1} \mathcal{L}_V$ on the Bender-Dunne basis being identified by means of the condition

\[
\left( \mathcal{L}_K^{-1} \mathcal{L}_V \right) T_{-m,n} = -2 \left( \frac{m}{n+4} \right) T_{-m-2,n+4} + \frac{1}{2} \frac{m(m+1)(m+2)}{n+2} T_{-m-4,n+2} - \frac{m}{n+2} T_{-m-2,n+2}
\]  

Repeated applications of equation (105) for the specific case $m = n = 1$ give rise to

\[
\left( \mathcal{L}_K^{-1} \mathcal{L}_V \right)^n T_{-1,1} = \sum_{m=0}^{n} \sum_{k=0}^{m} A_{n,m,k} T_{-4n+2m-1,2n+2m-2k+1},
\]  

for $n \geq 0$ and for some constants $A_{n,m,k}$ to be determined. It is simple to prove by induction that equation (106) holds for all $n \geq 0$ and, in the process, the recurrence relation that determines uniquely the unknown coefficients.
with the boundary condition \( A_{0,0,0} = 1 \) can be rearranged as (12). This proves that the minimal solution coincides with the inverse Liouville solution.

[1] V.E. Zakharov (Ed.), *What Is Integrability?*, Springer Series in Nonlinear Dynamics, Springer-Verlag, Heidelberg 1991.
[2] O. Babelon, D. Bernard and M. Talon, *Introduction to Classical Integrable Systems*, Cambridge Univ. Press, Cambridge 2003.
[3] A. Perelomov, *Integrable Systems of Classical Mechanics and Lie Algebras*, Birkhäuser Basel 1990.
[4] A. Perelomov, *Generalized Coherent States and Their Applications*, Springer Series in Theoretical and Mathematical Physics, Springer-Verlag, Heidelberg 1986.
[5] B.E. Schwarzhabach and Y. Kosmann-Schwarzbach, *The Noether Theorems: Invariance and Conservation Laws in the Twentieth Century*, Springer, Berlin, 2010.
[6] H. J. Carmichael, *Statistical Methods in Quantum Optics. I.*, Springer, Heidelberg, 1998
[7] L. E. Ballentine, Y. Yang, and J.P. Ziben, Phys. Rev. A50, 2854 (1994)
[8] R.F. Fox and T.C. Elston, Phys. Rev. E50, 2553 (1994).
[9] A. Royer, Phys. Rev. A53, 70 (1996).
[10] A.O. Barut and A. Bohm, Phys. Rev. B139, 1107-1112 (1965)
[11] Y. Dothan, M. Gell-Mann, and Y. Ne‘eman, Phys. Lett. 17, 148 (1965); Y. Dothan, Phys. Rev. D2, 2944-2954 (1970)
[12] W. Miller Jr., S. Post and P. Winternitz, J. Phys. A: Math. Theor. 46 423001 (2013).
[13] P. Winternitz and I. Yurdusen, J. Math. Phys. 47, 103509 (2006).
[14] M. Moshinsky and T. Seligman, Ann. Phys. 114 243 (1978); J. Phys. A12, L135 (1979).
[15] T. Hakioglu, J. Math. Phys. A: Math. Gen. 32 4111 (1999).
[16] P. Carruthers and M.M. Nieto, Rev. Mod. Phys. 40, 411 (1968); P. Carruthers and M.M. Nieto, Phys. Rev. Lett. 14 387 (1965).
[17] R. Lynch, Phys. Rep. 256, 367 (1995).
[18] E. A. Galapon, R. Caballar, and R. Bahague, Phys. Rev. Lett. 93, 180406 (2004).
[19] E. A. Galapon, R. Caballar, and R. Bahague, Phys. Rev. A72, 062107 (2005).
[20] C. M. Bender and G. V. Dunne, Phys. Rev. D 40, 2739 (1989).
[21] C. M. Bender and G. V. Dunne, Phys. Rev. D 40, 3504 (1989).
[22] H-Y. Fan, Ann. Phys. 321, 480 (2006)
[23] H-Y. Fan, Ann. Phys. 323 500 (2008).
[24] C.M. Bender and G.V. Dunne, J. Math. Phys. 29 1727 (1988).
[25] C.M. Bender and M. Gianfreda, J. Math. Phys. 53 (2012) 062102.
[26] J. Bunao and E.A. Galapon, J. Math. Phys 55, 022102 (2014).
[27] C.M. Bender and M. Gianfreda, J. Physics A: Math. Theor. 46 (2013) 275306.
[28] E. A. Galapon, A. Villanueva, J. Phys. A: Math. Theor. 41, 455302 (2008).
[29] Y.S. Kim and E.P. Wigner, Am. J. Phys. 58 449 (1990).
[30] K-H Yeon et al, Phys. Rev. A58, 1765 (1998).
[31] A.J. Bordner, J. Math. Phys. 38, 3427 (1997).
[32] M.A. Lohe and A. Thilagam, J. Phys. A: Math. Gen. 38, 461 (2005).
[33] J. Struckmeier and C. Riedel, Ann. Phys. 11 (2002) 1, 15-38.
[34] O.D. Johns, *Analytical mechanics for relativity and quantum mechanics*, Oxford University Press, Oxford, 2005.
[35] G. Landolfi, J. Phys. A: Math. Gen. 41, 185302 (2008).
[36] A. Mostafazadeh, J. Phys. A: Math. Gen. 31 (1998) 6495-6503.
[37] M. Maanache, J. Math. Phys. 39 (1), 161 (1998).
[38] V.P. Ermanakov, Univ. Izv. Kiev 20, 1 (1880).
[39] N.H. Ihrigimov, *CRC Handbook of Lie Group Analysis of Differential Equations*, Vol. 3, CRC Press, NY 1995.
[40] A. Geralico, G. Landolfi, G. Ruggeri, and G. Soliani Phys. Rev. bf D69, 043504 (2004).
[41] B. M. Rodriguez-Lara, P. Aleahmad, H. M. Moya-Cessa, and D. N. Christodoulides, Opt. Lett. 39, 2083 (2014).
[42] V. Kolokoltsov and V. Maslov, *Idempotent Analysis and Applications*, Kluwer Acad. Publ., Dordrecht (1997).
[43] B.J. Leimkuhler and C.R. Sweet, J. Appl. Dyn. Syst. 4, 187-216 (2005)
[44] S. Bond, B. Laird, and B. Leimkuhler, J. Comp. Phys., 151, 114 (1999).
[45] S. Nosé, J. Phys. Soc. Jpn., 70, 75 (2001).
[46] N.M.J. Woodhouse, *Geometric Quantization*, Oxford Mathematical Monographs, Clarendon Press, 2 edition, 1997.
[47] M. Hron and M. Razavy, Phys. Rev. A54, (1996) 3801.
[48] R. Giannitrapani, Int. J. Theor. Phys. 36, 1575 (1997).
[49] E. A. Galapon, F. Delgado, J. Gonzalo Muga, and I. Egusquiza, Phys. Rev. A72, 42107 (2005).
[50] M. Gianfreda and G. Landolfi, J. Math. Phys. 52, 122104 (2011).

We are aware that in the theory of dynamical systems and in mathematical physics integrability has acquired a meaning other than merely the success in the integration of equations [1]-[5]. In quantum mechanics, instead, the characterization of exact or approximate solutions to Schrödinger equation has been the main issue so far, and only a minor focus has been
put on other aspects, such to produce a more natural development from classical to quantum on geometric grounds [46].
On the other hand, problems we are going to deal with in this communication have a meaning close to that of Liouville integrability, but they will be addressed having in mind the explicit construction of solutions as the definite object (while aspects concerning orbits/orbitals will not be not mentioned). For this, we relax the distinction between actual integration and integrable dynamics, and we use the term integrability somewhat roughly to encompass both meanings.

[52] The reader should be aware that the locution "dynamical group" here has a distinct meaning from its use in the context inspired by papers [10, 11]

[53] For systems with more degrees of freedom, the argument logically requires the solving of equation of motion for all but one the canonical variables. A simple example can be stated, for instance, by means of a central potential problem, in which case the coordinate $q$ in terms of which time is stated is nothing but the radial coordinate; see e.g. [47]

[54] It is worth to recall that for a free particle the Kijowski’s arrival distribution and the Aharonov-Bohm time operator have already been formally linked each to the other both by means of the concept of positive operator valued measure in the unconfined case [13], and as limit of the distribution one would obtain by restricting the position domain to a finite real interval [54].

[55] Formal questions can be obviously raised in respect to the definition and the action of position and momentum operators and of their inverse, which in turn address to the properties of canonically conjugated operators. Implications can be discussed similarly to the case of operators $T_{m,n}$; see, for instance, investigations [28, 51] for possible consequences of confinement.