ALMOST SHARP NONLINEAR SCATTERING IN ONE-DIMENSIONAL BORN-INFELD EQUATIONS ARISING IN NONLINEAR ELECTRODYNAMICS

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Abstract. We study decay of small solutions of the Born-Infeld equation in 1+1 dimensions, a quasilinear scalar field equation modeling nonlinear electromagnetism, as well as branes in String theory and minimal surfaces in Minkowski space-times. From the work of Whitham, it is well-known that there is no decay because of arbitrary solutions traveling to the speed of light just as linear wave equation. However, even if there is no global decay in 1+1 dimensions, we are able to show that all globally small $H^{s+1} \times H^s$, $s > 1/2$ solutions do decay to the zero background state in space, inside a strictly proper subset of the light cone. We prove this result by constructing a Virial identity related to a momentum law, in the spirit of works [12, 13], as well as a Lyapunov functional that controls the $H^1 \times L^2$ energy.

1. INTRODUCTION AND MAIN RESULTS

1.1. The model. This note is concerned with the Born-Infeld equation (BI) in $\mathbb{R}^{1+1}$:

\begin{equation}
(1 - (\partial_t u)^2) \partial^2_{t} u + 2 \partial_x u \partial_t u \partial^2_{x} u - (1 + (\partial_x u)^2) \partial^2_{t} u = 0,
\end{equation}

\((t, x) \in \mathbb{R}^{1+1}\).

Here and along this paper \(u = u(t, x) \in \mathbb{R}\) is a scalar field. BI equation was originally derived by Born and Infeld in 1934 to describe nonlinear electrodynamics, a generalization of the standard (linear) Maxwell equations, see [8] for a detailed introduction to the field. A particular form of an electromagnetic plane wave solution to the original, three dimensional BI equations, leads to the quasilinear equation (1.1).

Although strictly nonlinear, equation (1.1) shares many similitudes with the classical linear wave equation. Given any $C^2$ real-valued profile $\phi = \phi(s)$, both

\(u_\pm(t, x) := \phi(x \pm t)\)

are solutions to (1.1) [25], just as the D’Alembert solution is to linear wave. This simple fact reveals that no standard decay estimates are expected in 1 + 1 dimensions. Additionally, a form of “two-soliton” solution was found by E. Schrödinger...
A Lax-pair representation for (1.1), just as in the case of Euler equations, was found in [6].

From a physical point of view, the Born-Infeld equation (1.1) can be derived as the Euler-Lagrange equation associated to the Lagrangian density [6]

\[ L[\partial^\mu u] := (1 + (\partial^\mu u \partial_\mu u)^2)^{1/2} = (1 + (\partial^x u)^2 - (\partial^t u)^2)^{1/2}, \] (1.3)

whose critical points also represent standard “minimal surfaces” in Minkowski geometry. More precisely, a simple computation reveals that (1.1) can be written as the minimal surface equation

\[ \frac{\partial_t u}{(1 + (\partial_x u)^2 - (\partial_t u)^2)^{1/2}} - \frac{\partial_x u}{(1 + (\partial_x u)^2 - (\partial_t u)^2)^{1/2}} = 0. \] (1.4)

This equation can be also recast as a mass conservation dynamics, which formally implies that the quantity

\[ \int \frac{\partial_t u}{(1 + (\partial_x u)^2 - (\partial_t u)^2)^{1/2}}. \]

is conserved along the dynamics. From this particular point of view, Lindblad [15] showed global existence for small data and decay estimates of order \( t^{-(n-1)/2} \) for the equivalent version of (1.4) in \( \mathbb{R}^{1+n} \) Minkowski space-time, provided \( n \geq 1 \). Similar results were also proved by Chae and Huh [7] in more generality. Both results are strongly influenced by vector field techniques [10], as well as the treatment of key null forms (such as \( Q(u, v) := \partial^\mu u \partial_\mu v \)), present in (1.4). In the case \( n = 1 \), Lindblad [15] constructs global small solutions by assuming sufficiently smooth, compactly supported data. However, as far as we understand, no decay estimate is given in this particular setting \( (n = 1) \), which remains the only case where no result of this type was available.

Additionally, the study of (1.1) has gained a large impulse in String theory in the last years because gauge fields on a D-brane (that arise from attached open strings) are described by the same type of Lagrangian as (1.3); see [11] and references therein for more details. The literature on the above subjects is huge; a fairly incomplete set of references on the “critical” submanifold problem from different points of view is given by [4, 5, 22, 14, 9].

1.2. Main result. In this paper we consider the remaining case \( n = 1 \), where no decay is present because the existence of arbitrary solutions moving to the speed of light. However, we will show that all sufficiently smooth and small solutions to (1.1) must decay to zero inside a slightly proper subset of the light cone.

**Theorem 1.1.** Let \( C > 0 \) be an arbitrary constant. Assume that for \( \varepsilon > 0 \) sufficiently small the solution \( (u, \partial_t u)(t) \) of (1.1) satisfies

\[ \sup_{t \in \mathbb{R}} \|(u, \partial_t u)(t)\|_{(H^{s+1+1/2})^2} < \varepsilon, \quad s > 1/2. \] (1.5)

Then, given the time-depending interval \( I(t) := \left( \frac{C|t|}{\log |t|}, \frac{C|t|}{\log^2 |t|} \right) \), \( |t| \geq 2 \), one has

\[ \lim_{t \to \pm \infty} \|(u, \partial_t u)(t)\|_{(H^1 \times L^2)(I(t))} = 0. \] (1.6)
Decay estimate (1.6) in Theorem 1.1 is almost sharp, in the sense that solution $u_\pm(t, x)$ given in (1.2) are natural counterexamples to time-decay, with both solutions moving along extremal light cones. The interval $I(t)$ can be slightly improved, see [21] for more details, but it seems hard to obtain decay inside the whole light cone $|x| \leq t - a$, for some $a > 0$. Complementing these results, strictly outside of the light cone, it is clear that no interesting dynamics occurs (because of finite speed of propagation).

Stability condition (1.5) is ensured for instance by applying Lindblad’s second theorem in [15]; note that it is highly unlikely to obtain (1.6) for data in the “energy space” $H^1 \times L^2$ only because of the scaling critical regularity in dimension $n$ given by $H^{n/2+1} \times H^{n/2}$. Actually, from the proof, and because of the Sobolev embedding, we will only need (1.5) to be satisfied in $\dot{H}^{s+1} \times \dot{H}^s$, $s > 1/2$. See also Stefanov [24] for a detailed account of equation (1.1) posed on Sobolev spaces only; in that case only results for dimensions $n \geq 3$ are available.

As a by-product of Theorem 1.6, one can also get a mild rate of decay for the solution. It can be proved (see (2.18)) that for any $c_0 > 0$,

$$\int_2^\infty \int e^{-c_0|x|}((\partial_x u)^2 + (\partial_t u)^2)(t, x) dx dt \lesssim c_0 \varepsilon^2,$$

which describes an averaged rate of local $L^2$ decay for the dynamics.

We prove this result by following very recent developments concerning the decay of solutions in $1 + 1$ dimensional scalar field models. Kowalczyk, Martel and the second author showed in [12, 13] that well chosen Virial functionals can describe in great generality the decay mechanism for models where standard scattering is not available (i.e. there is modified scattering), either because the dimension is too small, or the nonlinearity is long range. Moreover, this decay mechanism also describes “nonlinear scattering”, in the sense that solutions like (1.2) are also discarded by Theorem 1.1 inside $I(t)$, $t \to +\infty$. Previous Virial-type decay estimates were obtained by Martel-Merle and Merle-Raphaël [16, 20] in the case of generalized KdV and nonlinear Schrödinger equations. Moreover, the results proved in this note and in [12, 13, 16, 20] apply to equations which have long range nonlinearities, as well as very low or null decay rates. In this sense, Theorem 1.1 shows (local) decay even when there is no general decay, and as far as we know, it is a first application of these new methods to quasilinear equations. See also [21] for another application of this technique to the case of Boussinesq equations, a fourth order wave-fluid model. Additionally, unlike other wave-like models [1], no small solitary wave nor breather-like solution persists in time inside the proper light cone $I(t)$.

1.3. Organization of this paper. This note is planned as follows. In Section 2 we present some preliminary lemmas, proving a Virial identity (Lemma 2.1), which we will need in the proof of the Main Theorem. In Section 2.3 we show that the $\dot{H}^1 \times L^2$ local norm of the solution must be integrable in time; finally Section 3 deals with the end of the proof of Theorem 1.1.
2. INTEGRATION OF THE DYNAMICS

2.1. Virial identity. The purpose of this section is to present a new Virial identity which we will need in the proof of Theorem 1.1.

In what follows, we consider \( t \geq 2 \) only, and

\[
\lambda(t) := \frac{Ct}{\log^2 t}, \quad \frac{\lambda'(t)}{\lambda(t)} = \frac{1}{t} \left(1 - \frac{2}{\log t}\right). \tag{2.1}
\]

We introduce a new Virial identity for the Born-Infeld equation (1.1). Indeed, let \( \varphi := \tanh \) and let \( \mathcal{I} \) be defined as

\[
\mathcal{I}(t) := -\int \varphi \left(\frac{x}{\lambda(t)}\right) \frac{\partial_t u \partial_x u}{(1 + (\partial_x u)^2/(\partial_t u)^2)^{1/2}}. \tag{2.2}
\]

Clearly \( \mathcal{I}(t) \) is well defined as long as (1.5) is satisfied. Here we use the fact that both \( \partial_x u \) and \( \partial_t u \) are small in \( L^\infty \) thanks to the Sobolev embedding. Moreover,

\[
\sup_{t \in \mathbb{R}} |\mathcal{I}(t)| \lesssim \varepsilon^2.
\]

Note additionally that the denominator in (2.2) contains the gradient of \( u \) contracted with the standard Minkowski metric. A time-dependent weight was also considered in [19], but with different goals.

The choice of \( \mathcal{I}(t) \) is partly motivated by the energy identity that one obtains in (2.8).

**Lemma 2.1** (Virial identity). We have

\[
\frac{d}{dt} \mathcal{I}(t) = \frac{1}{\lambda(t)} \int \varphi' \left(\frac{x}{\lambda(t)}\right) \left(1 - \frac{1 - (\partial_t u)^2}{(1 + (\partial_x u)^2/(\partial_t u)^2)^{1/2}}\right) \frac{\partial_t u \partial_x u}{(1 + (\partial_x u)^2/(\partial_t u)^2)^{1/2}} \tag{2.3}
\]

\[
+ \lambda'(t) \int \frac{x}{\lambda(t)} \varphi' \left(\frac{x}{\lambda(t)}\right) \frac{\partial_t u \partial_x u}{(1 + (\partial_x u)^2/(\partial_t u)^2)^{1/2}}.
\]

**Proof.** We readily have

\[
\frac{d}{dt} \mathcal{I}(t) = -\int \varphi \left(\frac{x}{\lambda(t)}\right) Q(\partial_t u, \partial_x u, \partial^2_t u, \partial^2_x u)
\]

\[
+ \lambda'(t) \int \frac{x}{\lambda(t)} \varphi' \left(\frac{x}{\lambda(t)}\right) \frac{\partial_t u \partial_x u}{(1 + (\partial_x u)^2/(\partial_t u)^2)^{1/2}}, \tag{2.4}
\]

where

\[
Q(\partial_t u, \partial_x u, \partial^2_t u, \partial^2_x u) := \frac{(\partial^2_{xx} u \partial_t u + \partial_x u \partial^2_t u)(1 + (\partial_x u)^2/(\partial_t u)^2) - (\partial_x u \partial^2_t u)\partial_x u \partial_t u}{(1 + (\partial_x u)^2/(\partial_t u)^2)^{3/2}}. \tag{2.5}
\]

The second term in (2.4) is already present in (2.3), so we focus only on the first term leading to the numerator \( Q(\partial_t u, \partial_x u, \partial^2_t u, \partial^2_x u) \). We rewrite it in the following compact form:

\[
(\partial^2_{xx} u \partial_t u + \partial_x u \partial^2_t u)(1 + (\partial_x u)^2/(\partial_t u)^2) - (\partial_x u \partial^2_t u)\partial_x u \partial_t u =
\]

\[
= -(1 + (\partial_x u)^2/(\partial_t u)^2)\partial_x (1 - (\partial_t u)^2)
\]

\[
+ 1 - (\partial_t u)^2 \partial_x \left(\frac{1}{2} (1 + (\partial_x u)^2/(\partial_t u)^2)\right). \tag{2.6}
\]
We assume this identity, see below for the proof. Hence, using \([2.6]\) we simplify \(\frac{d}{dt} I(t)\) as follows:

\[
\frac{d}{dt} I(t) = \varphi \left( \frac{x}{\lambda(t)} \right) \frac{(1 + (\partial_x u)^2 - (\partial_t u)^2)\partial_x (1 - (\partial_t u)^2)}{(1 + (\partial_x u)^2 - (\partial_t u)^2)^{3/2}}
- \int \varphi \left( \frac{x}{\lambda(t)} \right) \frac{(1 - (\partial_t u)^2)\partial_x \left( \frac{1}{2}(1 + (\partial_x u)^2 - (\partial_t u)^2) \right)}{(1 + (\partial_x u)^2 - (\partial_t u)^2)^{3/2}} \\
+ \frac{\lambda'(t)}{\lambda(t)} \int_x \varphi \left( \frac{x}{\lambda(t)} \right) \frac{\partial_x u \partial_x \varphi}{(1 + (\partial_x u)^2 - (\partial_t u)^2)^{1/2}} \\
= A_1 + A_2 + B.
\]

The important term above is \(A_1 + A_2\). We have

\[
A_1 + A_2 = - \int \varphi \left( \frac{x}{\lambda(t)} \right) \frac{\partial_x ((\partial_t u)^2)}{(1 + (\partial_x u)^2 - (\partial_t u)^2)^{1/2}} \\
- \frac{1}{2} \int \varphi \left( \frac{x}{\lambda(t)} \right) (1 - (\partial_t u)^2) \frac{\partial_x (1 + (\partial_x u)^2 - (\partial_t u)^2)}{(1 + (\partial_x u)^2 - (\partial_t u)^2)^{3/2}} \\
= - \int \varphi \left( \frac{x}{\lambda(t)} \right) \frac{\partial_x ((\partial_t u)^2)}{(1 + (\partial_x u)^2 - (\partial_t u)^2)^{1/2}} \\
+ \int \varphi \left( \frac{x}{\lambda(t)} \right) (1 - (\partial_t u)^2) \partial_x \left( \frac{1}{(1 + (\partial_x u)^2 - (\partial_t u)^2)^{1/2}} - 1 \right).
\]

Now integrating by parts the second integral we get

\[
A_1 + A_2 = - \int \varphi \left( \frac{x}{\lambda(t)} \right) \frac{\partial_x ((\partial_t u)^2)}{(1 + (\partial_x u)^2 - (\partial_t u)^2)^{1/2}} \\
- \frac{1}{\lambda(t)} \int \varphi' \left( \frac{x}{\lambda(t)} \right) (1 - (\partial_t u)^2) \left( \frac{1}{(1 + (\partial_x u)^2 - (\partial_t u)^2)^{1/2}} - 1 \right) \\
+ \int \varphi \left( \frac{x}{\lambda(t)} \right) \partial_x ((\partial_t u)^2) \left( \frac{1}{(1 + (\partial_x u)^2 - (\partial_t u)^2)^{1/2}} - 1 \right).
\]

We continue simplifying,

\[
A_1 + A_2 = - \frac{1}{\lambda(t)} \int \varphi' \left( \frac{x}{\lambda(t)} \right) (1 - (\partial_t u)^2) \left( \frac{1}{(1 + (\partial_x u)^2 - (\partial_t u)^2)^{1/2}} - 1 \right) \\
- \int \varphi \left( \frac{x}{\lambda(t)} \right) \partial_x ((\partial_t u)^2).
\]

Finally, integrating again by parts the second integral, we obtain

\[
A_1 + A_2 = - \frac{1}{\lambda(t)} \int \varphi' \left( \frac{x}{\lambda(t)} \right) \left( (1 - (\partial_t u)^2) \left( \frac{1}{(1 + (\partial_x u)^2 - (\partial_t u)^2)^{1/2}} - 1 \right) - (\partial_t u)^2 \right) \\
= \frac{1}{\lambda(t)} \int \varphi' \left( \frac{x}{\lambda(t)} \right) \left( 1 - \frac{1 - (\partial_t u)^2}{(1 + (\partial_x u)^2 - (\partial_t u)^2)^{1/2}} \right).
\]

Collecting \(A_1 + A_2 + B\) we get the desired result. \(\square\)
Proof of (2.6). We have
\[
(\partial^2_{tt}u \partial_t + \partial_x u \partial^2_x u)(1 + (\partial_t u)^2 - (\partial_t u)^2) - (\partial_x u \partial^2_x u - \partial_t u \partial^2_t u) \partial_x u \partial_t u = \\
- \partial_x u \partial_t u (1 + (\partial_t u)^2 - (\partial_t u)^2) + \partial_x u \partial^2_t u (1 + (\partial_x u)^2 - (\partial_x u)^2) \\
+ \partial_x u \partial^2_x u (1 + (\partial_x u)^2 - (\partial_x u)^2) + \partial_x u \partial^2_t u (1 + (\partial_x u)^2 - (\partial_x u)^2) \\
- \partial_x u ^2 \partial_t u \partial^2_t u + \partial_x u \partial^2_t u \partial_t u \\
= \partial_x u ^2 \partial_t u \partial^2_t u + \partial_x u \partial^2_t u \partial_t u \\
= (\partial_x u )^2 (2 \partial_t u \partial^2_t u + \partial_x u \partial^2_x u (1 - (\partial_t u)^2) + (1 - (\partial_x u)^2) \partial_x u \partial^2_x u \\
+ (1 - (\partial_x u)^2) (\partial_x u \partial^2_x u - \partial_t u \partial^2_t u) \\
= (1 + (\partial_x u)^2 - (\partial_t u)^2) (2 \partial_t u \partial^2_t u + \partial_x u \partial^2_x u (1 - (\partial_t u)^2) + (1 - (\partial_x u)^2) \partial_x u \partial^2_x u - \partial_t u \partial^2_t u) \\
= - (1 + (\partial_x u)^2 - (\partial_t u)^2) \partial_x u \left( \frac{1}{2} (1 + (\partial_x u)^2 - (\partial_t u)^2) \right).
\]

\[\square\]

2.2. Energy identity. Let consider \( \phi := \varphi^2 = \text{sech}^4 \). The following Lemma will be useful to prove the integral estimate (2.3) in Section 2.3.

**Lemma 2.2.** Let \((u, \partial_t u)\) be a global small solution of (1.1). Then,
\[
\frac{d}{dt} \int \phi \left( \frac{x}{\lambda(t)} \right) \left( \frac{1 + (\partial_x u)^2}{(1 + (\partial_x u)^2 - (\partial_t u)^2)^{1/2}} - 1 \right) = \\
- \frac{1}{\lambda(t)} \int \phi' \left( \frac{x}{\lambda(t)} \right) \frac{\partial_x u \partial_t u}{(1 + (\partial_x u)^2 - (\partial_t u)^2)^{1/2}} \\
- \frac{\lambda'(t)}{\lambda(t)} \int \frac{x}{\lambda(t)} \phi' \left( \frac{x}{\lambda(t)} \right) \left( \frac{1 + (\partial_x u)^2}{(1 + (\partial_x u)^2 - (\partial_t u)^2)^{1/2}} - 1 \right).
\]

**Proof.** We have
\[
\frac{d}{dt} \int \phi \left( \frac{x}{\lambda(t)} \right) \left( \frac{1 + (\partial_x u)^2}{(1 + (\partial_x u)^2 - (\partial_t u)^2)^{1/2}} - 1 \right) = \\
\int \partial_t \left( \phi \left( \frac{x}{\lambda(t)} \right) \right) \left( \frac{1 + (\partial_x u)^2}{(1 + (\partial_x u)^2 - (\partial_t u)^2)^{1/2}} - 1 \right) \\
+ \int \phi \left( \frac{x}{\lambda(t)} \right) \partial_t \left( \frac{1 + (\partial_x u)^2}{(1 + (\partial_x u)^2 - (\partial_t u)^2)^{1/2}} - 1 \right) =: E_1 + E_2.
\]
As for $E_1$, we easily have
\[
\int \partial_t \left( \phi \left( \frac{x}{\lambda(t)} \right) \right) \left( \frac{1 + (\partial_x u)^2}{(1 + (\partial_x u)^2 - (\partial_t u)^2)^{1/2}} - 1 \right) = - \frac{\lambda(t)}{\lambda(t)} \int x \phi' \left( \frac{x}{\lambda(t)} \right) \left( \frac{1 + (\partial_x u)^2}{(1 + (\partial_x u)^2 - (\partial_t u)^2)^{1/2}} - 1 \right),
\]
which is the second term in the right hand side of (2.8).

Now, for $E_2$ we have
\[
E_2 = \int \phi \left( \frac{x}{\lambda(t)} \right) \partial_t \left( \frac{1 + (\partial_x u)^2}{(1 + (\partial_x u)^2 - (\partial_t u)^2)^{1/2}} - 1 \right)
\]
(2.9)
where
\[
Q(\partial_x u, \partial_t u, \partial_x^2 u, \partial_t^2 u) := \frac{2\partial_x^2 u \partial_x u (1 + (\partial_x u)^2) - (1 + (\partial_x u)^2) (\partial_x u \partial_x^2 u - \partial_t u \partial_t^2 u)}{(1 + (\partial_x u)^2 - (\partial_t u)^2)^{3/2}}.
\]
(2.10)
Similarly to (2.5), using (1.1) we have
\[
2\partial_x^2 u \partial_x u (1 + (\partial_x u)^2 - (\partial_t u)^2) - (1 + (\partial_x u)^2) (\partial_x u \partial_x^2 u - \partial_t u \partial_t^2 u)
= 2\partial_x^2 u \partial_x u (1 + (\partial_x u)^2) - 2\partial_x^2 u \partial_x u (\partial_t u)^2
+ \partial_t u (1 + (\partial_x u)^2)^2 \partial_t^2 u - (1 + (\partial_x u)^2)^2 \partial_x u \partial_t^2 u
= 2\partial_x^2 u \partial_x u (1 + (\partial_x u)^2) - 2\partial_x^2 u \partial_x u (\partial_t u)^2
+ \partial_t u (1 - (\partial_t u)^2)^2 \partial_x^2 u + 2\partial_x u \partial_t u \partial_x^2 u - (1 + (\partial_x u)^2) \partial_x u \partial_x^2 u
= \partial_x^2 u \partial_x u (1 + (\partial_x u)^2)^2 + \partial_t u (1 - (\partial_t u)^2)^2 \partial_x^2 u
= \partial_x^2 u \partial_x u (1 + (\partial_x u)^2 - (\partial_t u)^2) + \partial_x u \partial_x^2 u (\partial_t u)^2
+ \partial_t u (1 + (\partial_x u)^2 - (\partial_t u)^2)^2 \partial_x^2 u - \partial_x u \partial_x u (\partial_x^2 u)
= (\partial_x^2 u \partial_x u + \partial_t u \partial_x^2 u)(1 + (\partial_x u)^2 - (\partial_t u)^2) + \partial_x u \partial_t u (\partial_x^2 u \partial_x u - \partial_x u \partial_t^2 u)
= \partial_x^2 \partial_t u \partial_x u (1 + (\partial_x u)^2) - (\partial_t u)^2) - \frac{1}{2} \partial_x u \partial_t u \partial_x u (1 + (\partial_x u)^2 - (\partial_t u)^2).
\]
Replacing this last identity in $E_2$ in (2.4),
\[
E_2 = \int \phi \left( \frac{x}{\lambda(t)} \right) \left( \frac{\partial_x (\partial_t u \partial_x u)}{(1 + (\partial_x u)^2 - (\partial_t u)^2)^{1/2}} + \partial_x u \partial_t u \partial_x \left( \frac{1}{(1 + (\partial_x u)^2 - (\partial_t u)^2)^{1/2}} \right) \right).
\]
Integrating by parts,
\[
E_2 = - \frac{1}{\lambda(t)} \int \phi' \left( \frac{x}{\lambda(t)} \right) \frac{\partial_x u \partial_t u}{(1 + (\partial_x u)^2 - (\partial_t u)^2)^{1/2}},
\]
as desired. □
2.3. Integration of the dynamics. The purpose of this subsection is to show the following integral estimate, which gives us a proper control of the dynamics in time of the norm of the solution of (1.1):

**Lemma 2.3.** For \( \lambda(t) \) given as in (2.1), and \((u, \partial_t u)(t)\) satisfying (1.5), we have the averaged estimate

\[
\int_2^\infty \frac{1}{\lambda(t)} \int \text{sech}^2 \left( \frac{x}{\lambda(t)} \right) \left( (\partial_t u)^2 + (\partial_x u)^2 \right)(t, x) dx dt \lesssim \varepsilon^2. \tag{2.11}
\]

Moreover, there exists an increasing sequence of times \( t_n \to +\infty \) such that

\[
\lim_{n \to +\infty} \int \text{sech}^2 \left( \frac{x}{\lambda(t_n)} \right) \left( (\partial_t u)^2 + (\partial_x u)^2 \right)(t_n, x) dx = 0. \tag{2.12}
\]

This result roughly states that, all global small solutions must decay locally in space. The exact region of decay is determined by the scaling parameter \( \lambda(t) \), chosen in (2.1).

In order to show Lemma 2.3, we use the new Virial identity for (2.2) presented for the Born-Infeld equation (1.1).

**Proof.** From (2.3), we have the identity

\[
\frac{d}{dt} I(t) = \frac{1}{\lambda(t)} \int \varphi' \left( \frac{x}{\lambda(t)} \right) \left( 1 - \frac{1 - (\partial_t u)^2}{(1 + (\partial_x u)^2 - (\partial_t u)^2)^{1/2}} \right) dx \\
+ \frac{\lambda'(t)}{\lambda(t)} \int \frac{x}{\lambda(t)} \varphi' \left( \frac{x}{\lambda(t)} \right) \frac{\partial_t u \partial_x u}{(1 + (\partial_x u)^2 - (\partial_t u)^2)^{1/2}} dx
\]

\[=: \mathcal{I}_1 + \mathcal{I}_2.\]

We will estimate each term above separately. First, we claim

\[
\left| 1 - \frac{1 - (\partial_t u)^2}{(1 + (\partial_x u)^2 - (\partial_t u)^2)^{1/2}} \right| = \frac{1}{2} ((\partial_x u)^2 + (\partial_t u)^2) \leq (\partial_x u)^4 + (\partial_t u)^4. \tag{2.13}
\]

This is a simple consequence of the inequality

\[
\left| \frac{1 - a}{1 + b - a} \right| - 1 + \frac{1}{2} (a + b) \leq a^2 + b^2,
\]

valid for all \( a, b \geq 0 \) sufficiently small. Consequently,

\[
\mathcal{I}_1 \geq \frac{1}{2\lambda(t)} \int \varphi' \left( \frac{x}{\lambda(t)} \right) \left( (\partial_x u)^2 + (\partial_t u)^2 \right) dx \\
- \frac{1}{\lambda(t)} \int \varphi' \left( \frac{x}{\lambda(t)} \right) ((\partial_x u)^4 + (\partial_t u)^4) dx \\
\geq \frac{1}{4\lambda(t)} \int \varphi' \left( \frac{x}{\lambda(t)} \right) ((\partial_x u)^2 + (\partial_t u)^2), \quad (\text{see \ (1.5)}).
\]

On the other hand, from the estimate

\[
(1 + (\partial_x u)^2 - (\partial_t u)^2)^{1/2} \geq \frac{1}{2}, \tag{2.14}
\]
Proof. Proceeding as in the proof of estimate (2.13), we have
\[ |I_2| \leq \frac{2}{t} \int \frac{|x|}{\lambda(t)} \varphi' \left( \frac{x}{\lambda(t)} \right) |\partial_t u| |\partial_x u| \]
\[ \leq \frac{C \lambda(t)}{t^2} \sup_{x \in \mathbb{R}} \frac{|x|^2}{\lambda^2(t)} \varphi' \left( \frac{x}{\lambda(t)} \right) \int (\partial_t u)^2 + \frac{1}{8\lambda(t)} \int \varphi' \left( \frac{x}{\lambda(t)} \right) (\partial_x u)^2 \]
\[ \leq \frac{C \varepsilon^2}{t \log^2 t} + \frac{1}{8\lambda(t)} \int \varphi' \left( \frac{x}{\lambda(t)} \right) (\partial_x u)^2. \]

We collect the estimates on \( I_1 \) and \( I_2 \) to obtain
\[ \frac{d}{dt} I(t) \geq \frac{1}{8\lambda(t)} \int \varphi' \left( \frac{x}{\lambda(t)} \right) (\partial_x u)^2 \left( (\partial_x u)^2 + (\partial_t u)^2 \right) - \frac{C \varepsilon^2}{t \log^2 t}. \]

After integration in time we get (2.11). Finally, (2.12) is obtained from (2.11) and the fact that \( \lambda^{-1}(t) \) is not integrable in \([2, \infty)\). □

2.4. A final estimate. We finish this Section with a small result.

**Lemma 2.4.** Under the conclusions of Lemma 2.3, we have
\[ \lim_{n \to +\infty} \int \text{sech}^4 \left( \frac{x}{\lambda(t_n)} \right) \left( \frac{1 + (\partial_x u)^2}{1 + (\partial_x u)^2 - (\partial_t u)^2} - 1 \right)(t_n) = 0. \quad (2.15) \]

**Proof.** Proceeding as in the proof of estimate (2.13), we have
\[ \left| \frac{1 + (\partial_x u)^2}{1 + (\partial_x u)^2 - (\partial_t u)^2} - 1 \right| \leq \frac{1}{2} \left( (\partial_x u)^2 + (\partial_t u)^2 \right) \leq (\partial_x u)^4 + (\partial_t u)^4. \quad (2.16) \]

Using (1.5), we are lead to the estimate
\[ \int \text{sech}^4 \left( \frac{x}{\lambda(t_n)} \right) \left( \frac{1 + (\partial_x u)^2}{1 + (\partial_x u)^2 - (\partial_t u)^2} - 1 \right)(t_n) \]
\[ \leq \int \text{sech}^2 \left( \frac{x}{\lambda(t_n)} \right) (\partial_x u)^2 (\partial_t u)^2 (t_n), \]
which shows (2.15). □

**Remark 2.1.** Lemma 2.3 can also be obtained using a new and different functional. Consider now the slightly modified Virial term
\[ J(t) := - \int \varphi' \left( \frac{x}{\lambda(t)} \right) \frac{\partial_t u \partial_x u}{1 + (\partial_x u)^2}. \quad (2.17) \]

The main difference with respect to (2.2) is that \( J(t) \) is defined in the larger space \( (u, \partial_t u) \in H^1 \times L^2 \), because the denominator is never zero. It is not difficult to show, using the ideas in (2.3), that the following cleaner identity holds
\[ \frac{d}{dt} J(t) = \frac{1}{2\lambda(t)} \int \varphi' \left( \frac{x}{\lambda(t)} \right) \left( \frac{(\partial_x u)^2 + (\partial_t u)^2}{1 + (\partial_x u)^2} \right) \]
\[ + \frac{\lambda'(t)}{\lambda(t)} \int \frac{x}{\lambda(t)} \varphi' \left( \frac{x}{\lambda(t)} \right) \frac{\partial_t u \partial_x u}{1 + (\partial_x u)^2}, \]
which reveals a slightly better control of the local \( L^2 \) norm of the pair \( (\partial_x u, \partial_t u) \). However, unless we ensure that \( \partial_x u \) is small in certain uniform sense, this last
identity cannot be used to prove Lemma 2.3 for data in $\dot{H}^1 \times L^2$ only. This is certainly another key signature of quasilinear models, as the BI equation (1.1).

Remark 2.2. Finally, note that by choosing $\lambda(t) = \lambda_0 > 0$ fixed in (2.17), we have the better integral estimate
\[
\int_2^\infty \int \sech^2 \left( \frac{x}{\lambda_0} \right) ((\partial_x u)^2 + (\partial_t u)^2) dx dt \lesssim \lambda_0 \varepsilon^2.
\] (2.18)

We can recast this integral as an averaged decay estimate for the local $L^2$-norm of $(\partial_x u, \partial_t u)$, meaning that formally, and locally in space, both decay better than $1/\sqrt{t}$. However, note also that (2.18) describes nonlinear scattering, in the sense that even nonlinear objects, solutions to (1.1), depart far away from every compact subset of space.

3. PROOF OF THEOREM 1.1

We start with the following energy estimate.

Lemma 3.1. Let $(u, \partial_t u)$ be an $H^2 \times H^1$ solution to (1.1) satisfying (1.5). Then we have
\[
\left| \frac{d}{dt} \int \phi \left( \frac{x}{\lambda(t)} \right) \left( \frac{1 + (\partial_x u)^2}{(1 + (\partial_x u)^2 - (\partial_t u)^2)^{1/2}} - 1 \right) \right| \lesssim \frac{1}{\lambda(t)} \int \sech^2 \left( \frac{x}{\lambda(t)} \right) ((\partial_x u)^2 + (\partial_t u)^2).
\] (3.1)

Remark 3.1. The choice of functional in (3.1) is motivated by the “energy”
\[
\int \left( \frac{1 + (\partial_x u)^2}{(1 + (\partial_x u)^2 - (\partial_t u)^2)^{1/2}} - 1 \right),
\]
which is formally conserved by the dynamics. This energy controls the $\dot{H}^1 \times L^2$ norm if $(\partial_x u)^2 - (\partial_t u)^2$ is small, in the sense that
\[
\int \left( \frac{1 + (\partial_x u)^2}{(1 + (\partial_x u)^2 - (\partial_t u)^2)^{1/2}} - 1 \right) \sim \int ((\partial_x u)^2 + (\partial_t u)^2);
\]
see more details in (3.2) below.

Proof of Lemma 3.1. Using Lemma 2.2, we show estimate (3.1) above. First of all, using (2.14) we have
\[
\left| \frac{1}{\lambda(t)} \int \phi' \left( \frac{x}{\lambda(t)} \right) \frac{\partial_x u \partial_t u}{(1 + (\partial_x u)^2 - (\partial_t u)^2)^{1/2}} \right| \lesssim \frac{1}{\lambda(t)} \int \sech^2 \left( \frac{x}{\lambda(t)} \right) ((\partial_x u)^2 + (\partial_t u)^2).
Finally, using (2.16) and (2.1), and the fact that \( \phi = \text{sech}^4 \) satisfies the estimate
\[
\left| \frac{x}{\lambda(t)} \phi' \left( \frac{x}{\lambda(t)} \right) \right| \lesssim \text{sech}^2 \left( \frac{x}{\lambda(t)} \right),
\]
we have
\[
\left| \frac{\lambda'(t)}{\lambda(t)} \int \frac{x}{\lambda(t)} \phi' \left( \frac{x}{\lambda(t)} \right) \left( \frac{1 + (\partial_x u)^2}{(1 + (\partial_x u)^2) - (\partial_t u)^2 + (\partial_t u)^2} \right) - 1 \right|
\]
\[
\lesssim \frac{1}{t} \int \text{sech}^2 \left( \frac{x}{\lambda(t)} \right) ((\partial_x u)^2 + (\partial_t u)^2)
\]
\[
\lesssim \frac{1}{\lambda(t)} \int \text{sech}^2 \left( \frac{x}{\lambda(t)} \right) ((\partial_x u)^2 + (\partial_t u)^2).
\]
Collecting these two estimates we get (3.1).

We finish the proof of Theorem 1.1.

Proof of Theorem 1.1 We have from (3.1), and for \( t < t_n \),
\[
\left| \int \phi \left( \frac{x}{\lambda(t_n)} \right) \left( \frac{1 + (\partial_x u)^2}{(1 + (\partial_x u)^2) - (\partial_t u)^2} - 1 \right) (t_n) 
\right|
\]
\[
- \int \phi \left( \frac{x}{\lambda(t)} \right) \left( \frac{1 + (\partial_x u)^2}{(1 + (\partial_x u)^2) - (\partial_t u)^2} - 1 \right) (t)
\]
\[
\lesssim \int_i^{t_n} \frac{1}{\lambda(s)} \int \text{sech}^2 \left( \frac{x}{\lambda(s)} \right) ((\partial_x u)^2 + (\partial_t u)^2) dx ds.
\]
Sending \( n \) to infinity, and using (2.15), we get
\[
\left| \int \phi \left( \frac{x}{\lambda(t)} \right) \left( \frac{1 + (\partial_x u)^2}{(1 + (\partial_x u)^2) - (\partial_t u)^2} - 1 \right) (t) \right|
\]
\[
\lesssim \int_i^\infty \frac{1}{\lambda(s)} \int \text{sech}^2 \left( \frac{x}{\lambda(s)} \right) ((\partial_x u)^2 + (\partial_t u)^2) dx ds,
\]
which implies, thanks to Lemma 2.3
\[
\lim_{t \to +\infty} \left| \int \phi \left( \frac{x}{\lambda(t)} \right) \left( \frac{1 + (\partial_x u)^2}{(1 + (\partial_x u)^2) - (\partial_t u)^2} - 1 \right) (t) \right| = 0.
\]
Finally, from the inequality (2.16) we get the lower bound
\[
\int \phi \left( \frac{x}{\lambda(t)} \right) ((\partial_x u)^2 + (\partial_t u)^2) (t)
\]
\[
\lesssim \int \phi \left( \frac{x}{\lambda(t)} \right) \left( \frac{1 + (\partial_x u)^2}{(1 + (\partial_x u)^2) - (\partial_t u)^2} - 1 \right) (t), \tag{3.2}
\]
which finally shows the validity of Theorem 1.1.

Remark 3.2 (Final remarks). It is expected that some of these results hold for larger dimensions, with probably difficult proofs. However, in view of the already well-known results [15] for dimensions \( n \geq 2 \), we believe that the main new contribution in this note is given in the treatment of the scattering problem in the one dimensional case.
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