VELOCITIES MEASURED IN SMALL-SCALE SOLAR MAGNETIC ELEMENTS

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ABSTRACT

We have obtained high-resolution spectrograms of small-scale magnetic structures with the Swedish 1-m Solar Telescope. We present Doppler measurements at 0.2° spatial resolution of bright points, ribbons, and flowers, and their immediate surroundings, in the C i 25380.3 line (formed in the deep photosphere) and the two Fe i lines at 5379.6 and 5386.3 Å. The velocity inside the flowers and ribbons are measured to be almost zero, while we observe downflows at the edges. These downflows are increasing with decreasing height. We also analyze realistic magnetoconvective simulations to obtain a better understanding of the interpretation of the observed signal. We calculate how the Doppler signal depends on the velocity field in various structures. Both the smearing effect of the nonnegligible width of this velocity response function along the line of sight and of the smearing from the telescope and atmospheric point-spread function are discussed. These studies lead us to the conclusion that the velocity inside the magnetic elements is really upflow of order 1–2 km s\(^{-1}\), while the downflows at the edges really are much stronger than observed, of order 1.5–3.3 km s\(^{-1}\).

Subject headings: Sun: atmospheric motions — Sun: photosphere — techniques: spectroscopic

1. INTRODUCTION

In the Sun’s photosphere one can observe magnetic structures in a range of different scales: from sunspots tens of megameters in size to small-scale magnetic elements of about 200 km or less. Observationally these small-scale magnetic elements become visible as features brighter than the surroundings (leading to the often used term “bright points”) when the photosphere is imaged at sufficiently high angular resolutions (Dunn & Zirker 1973). Title & Berger (1996) showed that bright points cannot be detected with spatial resolutions worse than about 0.4° due to a smearing out of the contrast, because bright points are surrounded by darker areas. As observational methods have become more sophisticated, such as adaptive optics (AO) (e.g., Rimmle 2000; Scharmer et al. 2003b) and postprocessing methods (e.g., von der Luehe 1993; van Noort et al. 2005), the observations of such structures have become almost routine. Recently, Berger et al. (2004) concluded that at 100 km resolution the magnetic elements do not always resolve into discrete bright elements. Instead, in plage regions of stronger average magnetic field, the small-scale magnetic elements are found to be concentrated into elongated “ribbons” and round “flowers” with a darker core and bright edges. These elements are constantly evolving; the merging and splitting of “flux sheets” and the transitions between the ribbons, flowers, and micropores are described by Rouppe van der Voort et al. (2005). The understanding of these small-scale elements is of great importance, and these structures have therefore been subjected to intense research in recent years (e.g., Kiselman et al. 2001; Rutten et al. 2001; Sánchez Almeida et al. 2001; Steiner et al. 2001; Keller et al. 2004; Carlsson et al. 2004). This has resulted in good theoretical models and a good understanding of why the magnetic elements look the way they do in observations. One main conclusion of the above papers is that the dominant reason for the brightness of bright points is the lower density inside the bright point due to magnetic pressure, hence allowing the observer to look into deeper layers. These layers are hotter than the higher layers seen outside the magnetic elements because of the temperature increasing with depth. At equal geometric height, the temperature inside the magnetic element is lower than in the surroundings due to the suppression of convective energy transport by the magnetic field. This temperature contrast may be large enough in larger magnetic concentrations that it offsets the effect of the difference in formation height, and the magnetic element no longer looks bright. Smaller magnetic elements (bright points) and the edges of the larger magnetic elements (ribbons, flowers, and pores) are heated radiatively by the surrounding hotter, nonmagnetic atmosphere, and we get a bright point or a bright edge. Bright points have often been observed in the G band (spectral domain dominated by CH molecular lines at 4300 Å). This is because bright points have higher contrast in this domain due to an increased height difference of the optical depth unity height because of the destruction of CH molecules in low-density magnetic elements.

Rimmle (2004) presented measurements of the line of sight (LOS) velocity field in and around magnetic flux concentrations based on narrowband filtergrams. He found downflows at the edge of flux concentrations of “a few hundred meters per second.” The size of these downflow areas is approximately 0.2°, which indicates that they are smaller, since this is the approximate spatial resolution of the observations. Furthermore, he concluded that the downdraft gets narrower and stronger in deeper layers, and the plasma within the flux concentration is more or less at rest. Rouppe van der Voort et al. (2005) found that magnetic structures such as flowers, ribbons, and flux sheets have a weak upflow inside and a sharp downdraft at the edge, in accordance with Rimmle (2004). The LOS flow inside flowers and ribbons was measured to be about 0–150 m s\(^{-1}\) upflow, and the downdrafts at the edge to about 360 m s\(^{-1}\).

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Both Rimmel (2004) and Rouppe van der Voort et al. (2005) used filtergrams at only two spectral positions to derive the velocities—adding more spectral sampling points would increase the accuracy of the measurements and would also make it possible to derive the velocity as a function of height. Spectroscopic measurements of bright points were reported by Langhans et al. (2002), and they derived velocity maps showing downflows close to bright points. Furthermore, Langhans et al. (2004) used spectroscopic diagnostics to measure velocities inside bright points; at resolutions of about 0.3″ they found both upflows and downflows inside bright points.

In this paper, we present spectroscopic data of magnetic elements such as ribbons, flowers, and bright points with excellent spatial resolution. Intensity cuts of the smallest features and analysis of the spatial power spectrum show that the spatial resolution is better than 0.2″ for the spectra used in this work. These spectra are used to obtain the LOS velocities in and close to small-scale magnetic elements. Furthermore, we analyze a three-dimensional simulation of magnetoconvection by solving the radiative transfer through the simulation cube in the same spectral domain as in the observations. These simulations are used to understand the effects of the smearing along the LOS (the velocity response function) and spatial smearing (the instrument and atmospheric point-spread function [PSF]) have on the determinations of velocities.

In § 2 we present and discuss the observational program and the instrumentation. The data reduction methods are discussed in § 3. In § 4 we present the results of the Doppler shift measurements in the three spectral lines. The analysis of the magnetoconvective simulation, the determination of the velocity response functions in the diagnostics used, and the discussion of the smearing effects that this kind of velocity measurements is hampered with are presented in § 5. Finally, we summarize our results in § 6.

2. OBSERVING PROGRAM AND INSTRUMENTATION

The main aim of these observations was to obtain good spectra in and close to small-scale magnetic structures. On 2005 May 13 we observed the NOAA active region 10759 (N8.4° E10.5°, \( \mu = 0.97 \)) using a small pore as AO lock point; see Figure 1 for an example of a slit-jaw image.

The spectra were obtained using the Swedish 1-m Solar Telescope (SST) (Scharmer et al. 2003a) together with the AO system (Scharmer et al. 2003b) and the TRI-Port Polarimetric Echelle-Littrow (TRIPPEL) spectrograph. As indicated by the name, the TRIPPEL spectrograph is a Littrow spectrograph with an Echelle grating using 79 grooves mm⁻¹. The blaze angle is 63.43°, the focal length is 1500 mm, and the slit width is 25 μm. Simultaneous spectra of two wavelength intervals, 4566–5366 Å (hereafter the 4571 interval) and 5376.5–5388 Å (hereafter the 5380 interval), were obtained. In the present paper we focus on the 5380 interval, since these spectra were obtained with the shortest exposure time, and thus, the Doppler shifts in the spectral lines will be less affected by seeing. The spectrograph should always be operated with angles close to the blaze angle. We observe at 62.73° and in order 47 and 42 for the 4571 and 5380 intervals, respectively. The theoretical slit-limited bandpass for the 5380 interval is \( W_f = 23 \text{ mÅ} \), or in terms of effective theoretical spectral resolution, \( R \approx 234,000 \). In all our comparisons with FTS spectra and simulations we convolve these spectra to this resolution.

Two Megaplus 1.6 cameras (KAF-0401E Blue Plus and KAF-0401 Image sensor) were used at exposure times of 200 and 80 ms for the 4571 and 5380 intervals, respectively. The two cameras have a quantum efficiency of about 35% and 25% at the operating wavelengths. In addition to the spectral cameras we used two cameras to obtain slit-jaw images. One of the slit-jaw cameras using a 10.3 Å bandpass interference filter centered at 4572.6 Å was slaved to the spectral camera at the same wavelength. The other slit-jaw camera, using a 9.2 Å bandpass interference filter centered at 5321 Å, had exposure times of 8 ms and was not slaved. In the spatial domain the sampling is 0.0411″ pixel⁻¹. With this setup we observed several series of good to excellent seeing with a fixed slit position. One of these series, with a duration of about 17 minutes (10:59:40–11:17:06 UT),
is excellent both with respect to seeing conditions and structures crossed by the slit (see Fig. 1). In the following all the data presented come from this series, and we consider data of excellent quality spread over the full 17 minutes.

3. DATA REDUCTION

3.1. Flat Fields and Dark Currents

The spectrograms are corrected for dark currents and flat fields. Flat fields are constructed from five series of 50 images of random scans of the quiet solar disk center. We then construct a mean spectrum. To obtain a mean spectrum we need to correct for the spectrograph’s main distortions, namely, smile (the curvature of the spectral lines) and keystone (different spectral dispersions at different slit positions). The distortions are determined by fitting a fourth-order polynomial to the central part of the spectral line, and in this way we measure the line core position over the slit. This is done for five lines distributed over the spectrogram. The smile is of order 4 pixels, while the keystone is of order 0.15 pixels; thus, the smile is the most profound aberration. The final flat fields are obtained by dividing the total of the 250 images by a distortion-corrected mean spectrogram. In this way we remove both spatial and spectral information without losing the fixed CCD-dependent signal and without any interpolation of pixels in the flat field.

3.2. Wavelength Calibration

We make a mean solar spectrogram by adding together all 250 flat-field spectra. The mean aberration corrected spectrum is then compared to the Fourier transform spectroscope (FTS) atlas of Brault & Neckel (1987). This atlas has proved to be well calibrated in wavelength, and it shows no systematic offset in line shifts with wavelength (Allende Prieto & Garcia Lopez 1998). Since the solar atlas is corrected for the Earth’s rotation, the Earth’s orbital motion, and the Sun’s rotation, we automatically get a corrected spectrogram when we calibrate using the FTS atlas. The top panel of Figure 2 gives a good impression of the accuracy of this calibration. Note that in this way our wavelength scale is the same as that of the FTS atlas; there is thus no correction for gravitational redshift. The slit covers a region of almost 38” or approximately 28 Mm on the Sun. During the observations there is a temporal change of the spectral position on the cameras. This wavelength shift is the same in both spectral regions. Part of the shift is periodic, with an amplitude of 50–150 m s$^{-1}$ and a period of 5 minutes. This variation is caused by global oscillations averaged over the slit length. In addition there are slow trends, probably caused by temperature variations in the spectrograph. The frame-to-frame standard deviation is 8 m s$^{-1}$. We correct for this temporal change by applying a shift to the wavelength calibration determined from the flat-field spectra. Since the slit is covering an active region, the mean spectrum of each slit is not directly comparable to the solar atlas (Brandt & Solanki 1990 and references therein). Brandt & Solanki (1990) measured the mean convective blueshift in 19 Fe $\mathit{i}$ lines, including the Fe $\mathit{i}$ 5379.6 line, in quiet-Sun and magnetically active regions. They found that the convective blueshifts are decreased from 350 m s$^{-1}$ in quiet-Sun areas to 120 m s$^{-1}$ in active areas. We determine the temporal shifts by comparing the line center of the mean Fe $\mathit{i}$ 5379.6 line in each spectrogram (averaged over an active region) with the line-center position of the quiet-Sun atlas. We thus need to compensate for the difference in line-center convective blueshift between active regions and the quiet Sun. The difference of 230 m s$^{-1}$ found by Brandt & Solanki (1990) refers to an intensity level of 60% and not line center. From our observations we find that the difference is 30 m s$^{-1}$ smaller at line center. We thus apply a redshift of 200 m s$^{-1}$ to the atlas before comparing with our mean Fe $\mathit{i}$ 5379.6 line when determining the temporal shift.

Instead of correcting each spectrum for smile and keystone we use the determined aberrations to determine a separate wavelength scale for each slit position. This procedure avoids interpolation of the spectrogram data.

3.3. Scattered Light

When the mean quiet-Sun spectrum is plotted against the FTS atlas (see Fig. 2, top), it is clear that the mean spectrum has shallower lines than the FTS atlas. This discrepancy is due to scattered light, mainly from the diffuse scattering in the spectrograph. In the bottom panel in Figure 2 we have plotted the intensity level of the mean spectrum against the FTS intensity level. We use a least-squares linear fit to these data points. Assuming a constant level of diffuse scattered light, the offset and the new continuum calibration of the mean spectrum is given by this fit. The amount of constant scattered light is 6%. This level is subtracted from the spectra, and the resulting spectra are then divided by a scaling factor found from the slope of the curve in the bottom panel of Figure 2. Again we refer to Figure 2 (top) to see the effect of this correction of the scattered light.
According to Sobotka et al. (1994), “the mean intensity in abnormal granulation is equal to that of quiet granulation,” so we expect the mean spectrum from the flat fields to have the same mean count as we have in each of the mean spectrometers when we do not include the pores. This turns out not to be the case. There are many reasons for this discrepancy: different atmospheric conditions, the changing path length of the light ray in the atmosphere due to the time of the day, and changing intensity on the Sun due to solar oscillations (p-modes). All these effects are corrected for by introducing a scaling factor that gives the same mean solar continuum intensity in the mean spectrum of each spectrometer as in the mean solar atlas. We multiply with this scaling factor before we correct for scattered light.

### 3.4. Slit-Jaw Images

The slit-jaw images are corrected for dark currents and flat fields and postprocessed using the multiframe blind deconvolution (MFBD) method (van Noort et al. 2005). The intensity on the slit in the slit-jaw image is correlated to the mean intensity in the corresponding spectrometer to obtain the relative scaling and offset between the spectrometer and the slit-jaw image. The aligned slit-jaw images are used to identify the structures crossed by the slit (see Fig. 1). Note that the slit-jaw image has shorter exposure time than the spectrum and has been postprocessed—it is thus sharper and has a more narrow PSF than the spectrometer.

### 4. OBSERVED DOPPLER SHIFTS

The 5380 interval contains the deep-forming (Livingston et al. 1977) C i λ5380.3 line (see Fig. 1). Furthermore, it contains a well-suited, quite strong Fe i line at 5379.6 Å and a weaker Fe i line at 5386.3 Å. These two iron lines have been singled out by other authors as good both in the sense that they are blend free and thus are well suited to measure the line asymmetry (Dravins et al. 1981) and that their central wavelengths are well known (Allende Prieto & Garcia Lopez 1998). Nave et al. (1994) gave the central wavelength of these Fe i lines (see Table 1), and they claimed the error in the central wavelength of these two lines to be less than 1.25 and 2.5 mÅ, respectively, which corresponds to uncertainties in velocities of 70 and 140 m s\(^{-1}\). The central wavelength of the C i line was given by Johansson (1966), and he quoted the uncertainty to be less than 0.02 Å, which corresponds to 1115 m s\(^{-1}\). This high uncertainty makes it difficult to use this line to determine velocities on an absolute scale. The Fe i line at 5383.3 Å was also picked out by Dravins et al. (1981), but we do not use this line due to a blend in the blue wing. We use the laboratory wavelengths as reference wavelengths for the two Fe i lines, while we use a reference wavelength that gives us a more realistic convective blueshift for the C i line. Using the wavelength given by Johansson (1966), 5380.337 Å, we get a convective blueshift of 1465 m s\(^{-1}\). Instead we use a reference wavelength that is in agreement with a three-dimensional magneto-convective simulation (see § 5). The simulation gives a convective blueshift of 664 m s\(^{-1}\), which indicates a convective blueshift in nonmagnetic regions of 864 m s\(^{-1}\), which corresponds to a reference wavelength of 5380.3262 Å. This wavelength is well within the given uncertainty of 0.02 Å. The line core wavelengths in the FTS atlas, the reference wavelengths, used to calculate the LOS velocities, and the corresponding blueshifts are shown in Table 1. Note that we have corrected for a gravitational redshift of 633 m s\(^{-1}\). The Landé g-factors of the Fe i lines are 1.10 and 1.17; for the C i line it is unknown but greater than zero.

Since the C i line is very shallow we only determine the total line shift for this line, while the Fe i lines are well suited for determining the Doppler shift at different intensity levels by determining the bisector of the line. To facilitate a comparison of velocities in different features we use the same absolute intensity levels in the various features (we thus do not use the local continuum of that feature). The intensity levels used are relative to the average continuum level of the average Sun at disk center. This continuum value, as given by Neckel & Labs (1984), and the values at other intensity levels are given in Table 2, both as absolute intensities and as radiation temperatures. The latter is indicative of the gas temperature at the level of formation of the radiation at this intensity level.

The total line shift in the C i line is calculated using a Gaussian fit to the line. When we calculate the velocities we correct for gravitational redshift.

Our slit crosses from two to three ribbons, depending on the temporal evolution of the photosphere as well as the changes in slit position due to differential seeing. It must be emphasized that we do not have magnetic information, so all classification has to be done purely by visual inspection. The kind of ribbon structures we see has been shown to be magnetic (Berger et al. 2004). A flower/ribbon and a typical granule can be seen in Figure 3. This figure also shows velocities and the continuum intensity at the slit position. It is clear that we have downflows at the edge of the flower/ribbon (arrows), which are increasing with increasing intensity level in the line (formation deeper in the atmosphere). Furthermore, the velocity in the granule is somewhat high (the mean measured value in our observations is about 1.2–1.7 km s\(^{-1}\)), with about 1.4–2.0 km s\(^{-1}\) upflow. Finally, we see that in the center of the flower/ribbon we measure the velocities to be more or less zero. Intensity minima between magnetic structures and granules are found by visual inspection; these are hereafter intergranular lanes close to magnetic structures (IGM). The peak velocity close to the intensity minimum in the IGM is measured; this peak can vary slightly from the intensity minimum, but not more than 0.15" (see Fig. 3). This peak velocity is measured for...
up to 51 different IGMs; the velocities and the standard deviations are shown in Table 3. The pixel-to-pixel standard deviation in the velocity determination is 40 m s$^{-1}$.

A statistical analysis of the minimum LOS velocity within flowers and ribbons (ribbon centers [RCs]) gives us velocities around 0 m s$^{-1}$ in the Fe i 5379 line, while the C i line shows an upflow of about 300 m s$^{-1}$. The Fe i 5386 line shows a small upflow inside RCs with a mean of about 200 m s$^{-1}$. The standard deviations are of order 100–200 m s$^{-1}$ in the Fe i lines, while the C i line has a standard deviation of about 350 m s$^{-1}$. These results are hampered with relatively high uncertainties of a few hundred meters per second. We therefore want to investigate the effects of smearing along the LOS and spatially on these velocity measurements.

We have also measured velocities inside bright points, but since the spatial extent of each bright point is small, they are difficult to identify. Nevertheless, we visually classify 15 bright points and measure the velocities at intensity maximum. We measure a mean downflow of a few hundred meters per second, but the velocities inside bright points vary a lot, and we also measure upflows inside some of the bright points. The standard deviation is quite high, about 0.5 km s$^{-1}$. Due to the small spatial extent of each bright point, the measured velocities are strongly affected by the surrounding intergranular velocity.

The effect of a nonzero $g$-factor is increased broadening in magnetic areas. For a nonsymmetric profile this broadening may also introduce a change in the determined bisector. We have quantified this effect by applying a Zeeman splitting corresponding to a magnetic field strength of 1000 G to the observed profiles and redetermined the bisector. The change in measured velocity is less than 40 m s$^{-1}$.

5. SIMULATIONS

Since the intensity level can be considered as a height parameter, it is in principle possible to obtain the velocity as a function of absolute physical height. In order to explore this possibility we need a good model with which we can calibrate the velocities with height. One very suitable model is the magnetococonvective simulation used by Carlsson et al. (2004). In this realistic simulation we can see bright points as well as more elongated magnetic structures. To tailor this simulation to our observational setup we use 12 atmospheric snapshots, including the same snapshot as the one used by Carlsson et al. (2004) with 1 minute time difference between the snapshots. We solve the equations of radiative transfer in LTE for these three-dimensional atmospheres, using the MULTI code (Carlsson 1986). From 1364 frequency points spanning from 5377.6 to 5389.4 Å. A line list of 249 lines is used. The line data were retrieved from the Vienna Atomic Line Database (VALD) (Kupka et al. 1999; Piskunov et al. 1995; Ryabchikova et al. 1999), with a few exceptions: the C i oscillator strength is taken from Hibbert et al. (1993), and an Fe line at 5382.5 Å was removed due to obvious errors in its central wavelength and oscillator strength.

A temporally and spatially averaged mean spectrum over 12 minutes and 8.27" × 8.27", in total over 750,000 spectra, is constructed. Since the simulation is covering an active region we expect the mean spectrum to have less blueshift, have shallower lines, and to have more vertical lower bisectors (intensity level less than 0.7) than similar mean spectra obtained in nonmagnetic regions (Brandt & Solanki 1990 and references therein). For reference we therefore solve the equations of radiative transfer in LTE in three nonmagnetic snapshots with 1 minute cadence, in total over 190,000 spectra. Even though the temporal sampling is quite low, we believe that the difference from the nonmagnetic simulation will be within 1 mÅ, or approximately 50 m s$^{-1}$. In the nonmagnetic simulation we have deeper strong Fe lines than the atlas; this is due to non-LTE (NLTE) effects (Shchukina & Trujillo Bueno 2001). The Fe lines in the mean magnetic spectrum do not show any reduced line depth. This might be because the magnetic field in the simulation is too weak, but also because of NLTE effects. The convective blueshifts are in general well reproduced in the nonmagnetic simulation (Asplund et al. 2000). One difference is that the upper part of the bisector shows larger blueshift than the atlas (see Fig. 4). We therefore use the blueshift in the magnetic simulation as the reference wavelength for the C i line, since this simulation seems to give a more realistic convective blueshift in this line (see § 4). The magnetic simulation shows a blueshift that is about 200 m s$^{-1}$ smaller than the nonmagnetic simulation, very similar to what was found observationally by Brandt & Solanki (1990). Furthermore, the lower part of the bisector in the magnetic simulation is more vertical than in the nonmagnetic simulation, also similar to observations. These are indications that the simulations are reproducing the velocities in a realistic manner.
When we measure the velocity in a spectral line at a given intensity level there are two smearing effects that will influence the measurement. The first effect is an intrinsic property of the line formation mechanism, namely, the finite width of the response function. The response to a given velocity at a given height in a spectral line at a given intensity level is given by the response function to velocity at this intensity level (Magain 1986). We calculate the response functions numerically using a step function in the velocity, very similar to the way Fossum & Carlsson (2005) calculated their response functions to perturbations in temperature. Typical response functions will have a pronounced peak but with a significant width of a few hundred kilometers (see Figs. 5–6 for some examples). In Table 4 we give average response heights (given as the first-order moment) in six different solar features (see Figs. 5 and 7 for definition). These response heights are calculated in the line core (LC) and in the close to continuum line wing (CLW) for the Fe\textsubscript{i} lines, while the moment of the total line (TL) was used for the C\textsubscript{i} line.

The width of the response functions means that we do not measure the real plasma velocity but rather a height smeared velocity. The difference between the response function weighted velocity and the velocity at monochromatic optical depth unity can be several hundred meters per second (see Fig. 7). It is thus important to be aware of this effect when one talks about Doppler shifts measured in spectral lines. The response function to velocity in the IGM is quite narrow at all intensity levels, while the response function in the RC is much wider (see Fig. 6). The effect of the

| Feature | Fe\textsubscript{i} 5379 | Fe\textsubscript{i} 5386 | C\textsubscript{i} |
|---------|----------------|----------------|----------------|
|         | LC (km) | CLW (km) | LC (km) | CLW (km) | TL (km) |
| RC      | 232     | 32      | 46     | –28       | 2       |
| IGM     | 129     | 29      | 78     | 34        | 50      |
| BP      | –36     | –112    | –44    | –116      | –134    |
| G       | 305     | 156     | 205    | 141       | 135     |
| LMC     | 79      | –123    | –76    | –170      | –183    |
| IG      | 248     | 127     | 211    | 143       | 141     |
response function smearing is, however, much higher in the IGM, since the actual atmospheric velocity is changing much more quickly with height in IGMs than in RCs. This explains why we measure almost the exact plasma velocity in the RC in Figure 7, while we measure lower velocities in the IGM.

The second effect is the spatial smearing that originates from atmospheric seeing, the diffraction pattern of the telescope, and scattering in the atmosphere, the telescope, and the spectrograph. Even if we could determine the total PSF of the atmosphere-telescope-spectrograph system, we cannot correct for these effects in the measured spectra, since we have spectral information only along the one dimension of the slit. Another approach is to model the PSF and convolve the simulations with such a model to quantify the effects of the PSF on the measurements. The PSF of a partially AO-corrected image for short exposures is usually assumed to consist of a diffraction core and a seeing halo from uncorrected or partially corrected modes. We assume that we can use this model for our spectra, even though 80 ms is longer than what is normally accepted as short exposure. Furthermore, we assume that the seeing halo has the form of a Lorentzian (Nordlund 1984). Our model PSF thus has two free parameters: the width of the Lorentzian and the fraction of the Lorentzian component compared with the Airy core. A more detailed model of the PSF could not be obtained, since we lack the statistics necessary for the determination of more than two parameters. The observable is the continuum intensity distribution as measured in the spectra, excluding the pore. We assume that the intensity distribution in the simulations is realistic and compare the normalized distribution function (NDF) of the intensities in the smeared simulation with the observed distribution function to determine the parameters. We find a good fit with a Lorentzian with FWHM of 0.7″ having a fraction of 0.1 at the center of the PSF (see Fig. 8). The Strehl ratio of this PSF is 0.15, which is low compared with what one would expect from the AO system of the SST. One should remember here that we have no separate component to describe the scattering of the Earth’s atmosphere, which is known to be very wide, and the Strehl ratio obtained includes this effect.

It is also important to point out that a range of parameters give acceptable fits to the observed intensity distribution function—wider Lorentzians with smaller fraction give almost the same effect on the NDFs as a narrower Lorentzian with larger fraction. To check the sensitivity of the results to the PSF, we have performed tests both with a wider central core than the Airy disk and with different combinations of the width and fraction of the Lorentzian. As long as the NDF is close to the observed one, we do not see significant changes in the resulting velocities (in comparison with the standard deviations shown in Fig. 9). At the same time, the velocities determined from the convolved simulations are very different from the velocities in the unconvolved simulation. This may seem contradictory but is due to the fact that intensities and velocities are correlated—high-intensity granules have large upflows, and low-intensity intergranular lanes downflow. When the PSF gives the observed intensity distribution function, this also implies similar effects on the velocity distribution function. Before comparing with observations, the spectral domain is convolved with the theoretical resolution of the TRIPPEL spectrograph.
We use the laboratory wavelengths as reference wavelengths for the Fe I lines, while we use the same wavelength as in the observations for the C I line. Furthermore, we calculate the central wavelength in the simulated atlas and the corresponding blueshift. The results are shown in Table 5 (with negative velocity meaning blueshift).

Now we can measure the velocities in the IGMs in the simulations. This is done in a similar manner as we used to measure the velocities in the IGMs in the observations: the results are plotted together with the observed results in Figure 9. The absolute velocities in the simulations and the observations differ with 200 m s\(^{-1}\) or less, which is amazingly close when one considers the uncertainty in the observations of 100–200 m s\(^{-1}\) and that the standard deviation is about 200 m s\(^{-1}\). Note that we believe that the Fe I 5386 line has an error of about 100 m s\(^{-1}\) in the laboratory wavelength. This will increase the measured velocities with the same amount. Furthermore, we see an increase in measured velocity with intensity level for both the observations and the simulations. This increase is somewhat lower in the simulation than in the observations. Note that the C I line gives substantially lower downflow values than the iron lines at comparable intensity level. This is true both in the observations and in the simulations. In the latter, the determined velocity is completely independent of the reference wavelength used, so an error in the reference wavelength is not the explanation for the low velocities in the observations. The explanation is rather the differences in the response functions and the spatial smearing due to the seeing. The difference between the response functions in the IGM is minimal, but the difference between the response functions in granules is substantial. In the granule the C I line is formed deeper in the atmosphere, and hence this line will show a larger upflow. When the spatial smearing is applied, this difference will lead to a smaller downflow in IGMs in the C I line, as observed. It is clear that the simulations and the observations are not in disagreement, even though there is room for improvements.

We also measure the lowest velocities within the magnetic elements in the simulation. The velocities measured range from about 200 m s\(^{-1}\) upflow to about 200 m s\(^{-1}\) downflow. The standard deviation is 250–300 m s\(^{-1}\). Due to the lack of good sampling of bright points in the simulations we do not include any statistics on bright points in the simulations.

### TABLE 5

| Atomic Species | Simulation (Å) | Reference (Å) | Velocity (m s\(^{-1}\)) |
|---------------|----------------|---------------|------------------------|
| Fe I          | 5386.3301      | 5386.3341     | –223                   |
| C I           | 5380.3143      | 5380.3262     | –664                   |

6. CONCLUSIONS

We have presented spectrograms of small-scale magnetic structures with excellent spatial resolution. These spectrograms have been used to measure the LOS velocities in several different magnetic structures. At the edges of the ribbons and flowers we measure downflow with an increasing magnitude with depth in the atmosphere. The magnitude of the downflow is about 200–700 m s\(^{-1}\), with increasing velocity deeper down in the atmosphere. Inside the ribbons and flowers we measure a small upflow. The upflows are usually in the range 100–300 m s\(^{-1}\). Our investigation of the velocities inside bright points shows both up- and downflow, but nevertheless with a mean downflow of a few hundred meters per second. In most cases the velocity is closely related to the intergranular velocity, which indicates a strong presence of scattered light in the measured velocity.

Furthermore, we have investigated the processes that are involved in the smearing of the measured velocities. The results from this work can be summarized as follows.

1. We have calculated response functions and response heights for several different solar features. The width of the response functions is usually a few hundred kilometers.
2. We have convolved the simulations with a simple model of the PSF of the observations. Due to the strong horizontal gradients in the velocity field and close to small-scale magnetic features, this spatial smearing has a strong effect on the measurements: the measured velocities in the intergranular lanes close to magnetic elements are decreased with about 1 km s\(^{-1}\).
3. Since the simulations are reproducing the observations reasonably well, we believe that the plasma velocities in the simulations are close to the real solar plasma velocities. In particular, the velocities in and close to larger magnetic structures such as ribbons are well reproduced. The velocity in the simulation in intergranular lanes close to magnetic structures increases from about 1.5 km s\(^{-1}\) at 150 km height to 3.3 km s\(^{-1}\) at 0 km height.

The velocity inside bigger magnetic structures such as ribbons in the simulations is about 1–2 km s\(^{-1}\) upflow, with the velocity changing only a few hundred meters per second throughout the formation height between about 100 and 250 km.

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