ON THE ASYMPTOTIC BEHAVIOR OF LARGE RADIAL DATA
FOR A FOCUSING NON-LINEAR SCHRÖDINGER EQUATION

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Abstract. We study the asymptotic behavior of large data radial solutions to the focusing Schrödinger equation \( iu_t + \Delta u = -|u|^2 u \) in \( \mathbb{R}^3 \), assuming globally bounded \( H^1(\mathbb{R}^3) \) norm (i.e. no blowup in the energy space). We show that as \( t \to \pm \infty \), these solutions split into the sum of three terms: a radiation term that evolves according to the linear Schrödinger equation, a smooth function localized near the origin, and an error that goes to zero in the \( \dot{H}^1(\mathbb{R}^3) \) norm. Furthermore, the smooth function near the origin is either zero (in which case one has scattering to a free solution), or has mass and energy bounded strictly away from zero, and obeys an asymptotic Pohozaev identity. These results are consistent with the conjecture of soliton resolution.

1. Introduction

In this paper we consider the (forward-in-time) asymptotic behavior of global energy-class solutions \( u : [0, +\infty) \times \mathbb{R}^3 \to \mathbb{C} \) to the focusing cubic non-linear Schrödinger equation

\[
iu_t + \Delta u = F(u)
\]

in three dimensions, where \( F(u) := -|u|^2 u \) is the focusing cubic non-linearity.

Non-linear Schrödinger equations such as (1) have been intensively studied and we review\(^2\) some of the results here. The equation (1) is locally well-posed in the energy class \( H^1(\mathbb{R}^3) \) (see e.g. [10], [45], [41]; in fact it is locally well-posed in \( H^s(\mathbb{R}^3) \) for

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\(^1\)It is likely that at least some of the results here also extend to other dimensions and exponents. However, we need to be in three and higher dimensions in order for the fundamental solution \( e^{it\Delta} \) to be “short range” (decaying faster than \( t^{-1} \)), and the algebraic nature of the cubic non-linearity is also somewhat convenient. Also much of the asymptotic analysis is restricted to the \( L^2 \)-supercritical regime \( p > 1 + \frac{4}{d} \) in order for global Strichartz estimates to be useful.

\(^2\)As this is a vast field, we cannot hope to come close to an exhaustive description of results here, and the references given are not intended to be complete. We refer the reader to the books [10], [45], [6], [41] for a more detailed survey.
all \( s \geq 1/2 \) [12]). It also enjoys the conservation of mass

\[
\text{MASS}(u(t)) := \int_{\mathbb{R}^3} |u(t,x)|^2 \, dx
\]

and conservation of the Hamiltonian

\[
\text{ENERGY}(u(t)) := \int_{\mathbb{R}^3} \frac{1}{2} |\nabla u(t,x)|^2 - \frac{1}{4} |u(t,x)|^4 \, dx,
\]

however these two conservation laws are unfortunately not enough to control the \( H^1(\mathbb{R}^3) \) norm; the Gagliardo-Nirenberg inequality

\[
\int |u|^4 \leq C (\int |\nabla u|^2)^{3/2}(\int |u|^2)^{1/2}
\]

is not sufficient unless the mass\(^3\) is sufficiently small. Indeed, if the Hamiltonian is negative then one has blowup in finite time from the virial identity [21], [31] (see [10], [45] for further discussion; see also Corollary 1.5 below).

In this paper we will consider the asymptotic behavior (as\(^4\) \( t \to +\infty \)) of solutions which do not blow up in the energy class; more precisely we consider solutions where we assume \textit{a priori} the uniform \( H^1 \) bound

\[
\sup_{t \in [0, +\infty)} \|u(t)\|_{H^1(\mathbb{R}^3)} \leq E
\]

for some \( 0 < E < +\infty \) (note we do not assume any smallness assumption on \( E \); we also allow the possibility that solution could blow up at some finite \textit{negative} time).

In particular (by (2)) we assume that the mass and energy of \( u \) is finite.

Bounded energy solutions will occur for instance when the product of the mass and energy of \( u \) (which is a scale-invariant quantity) is sufficiently small, thanks to the Gagliardo-Nirenberg inequality (2); another option is to modify the non-linearity \( F(u) \) for large \( u \) by replacing it smoothly with a non-linearity which behaves like \( O(|u|^p) \) for some \( p < 1 + \frac{4}{3} \), as this allows the Gagliardi-Nirenberg inequality argument to derive (3) even when the energy and mass are large (as we shall see, it is the low values of \( u \) which will dominate our discussion, the high values being irrelevant except in order to establish a local existence theory).

With the \textit{a priori} assumption (3) we know that \( u \) is globally well-posed in \( H^1(\mathbb{R}^3) \) by iterating the local well-posedness argument. But this standard global existence result does not reveal very much about the asymptotic behavior of \( u \). For data whose energy \( E \) is small it is possible to show that the solution \( u(t) \) eventually scatters to approach a free solution \( e^{it\Delta} u_+ \) in the energy norm \( H^1(\mathbb{R}^3) \) as \( t \to +\infty \),

\(^3\)More precisely, one needs a scale invariant quantity such as \( (\int |u|^2)(\int |\nabla u|^2) \) to be small at time zero, and then it will be small for all time by combining the above argument with the continuity method.

\(^4\)The behavior as \( t \to -\infty \) is completely identical, thanks to the time reversal symmetry \( u(t,x) \mapsto u(-t,x) \) of (1), and will not be discussed here. It is however an interesting question as to whether the solutions which scatter to a free solution as \( t \to +\infty \) match at all with the solutions which scatter to a free solution as \( t \to -\infty \); this is true in the completely integrable one-dimensional situation, as well as for small data, but may well be false for the three-dimensional large data case.
see e.g. [10], [41] (see also Theorem 1.1 below); note that the potential \( |u|^2 \) in \( F(u) \) is a “short-range” potential (it decays integrably in time if \( \|u(t)\|_\infty \) has the expected decay of \( t^{-3/2} \)) and thus does not cause any non-linear corrections (see [31] for more discussion). Furthermore, the map \( u(0) \mapsto u_+ \) is a local homeomorphism in the energy space near the origin (see e.g. [41]).

For large data we do not expect this scattering behavior\(^5\) to the focusing equation (1), even assuming the energy bound (3), because of the existence of soliton solutions (both ground states and excited states). These soliton solutions are generated by finite-energy solutions \( u(x) \) to the non-linear eigenfunction equation

\[
-\omega u + \Delta u = F(u)
\]

for some \( \omega > 0 \) (which is related to, but not quite the same, quantity as the energy \( E \) in (3)). Such solutions are known to be smooth and exponentially rapidly decreasing (see e.g. [10]), and if one makes the further assumption that \( u \) is non-negative and spherically symmetric then there is a unique solution to (4) for each \( \omega > 0 \) [14], [41], [3]; we refer to this \( u \) as the ground state. There also exist radial solutions which change sign, see [2]; we refer to these as excited states. Note that if \( u \) is either a ground state or excited state then \( u(t, x) := e^{i\omega t}u(x) \) is a solution to (1); we refer to these solutions as the ground soliton and excited soliton solutions respectively.

These special solutions can be of course modified by the various symmetries of the Schrödinger equation such as scaling, translations, Galilean transformations, and phase rotation to produce solitons of various velocities, energies, widths, etc.

The analysis of solutions close to a soliton state is by now well understood; the ground state soliton for the cubic NLS (1) is unstable due to the existence of nearby blowup solutions [1], [37], although if one mollifies the growth of the nonlinearity \( F(u) = |u|^2u \) near infinity enough then one can regain orbital stability [50], [51], [11], [22], [23] and asymptotic stability [7], [8], [9], [18], [19] for the ground state given appropriate conditions on the nonlinearity; see [10] or [34] for further discussion. For perturbations of excited solitons there seems to be far less known; one possible conjecture is that generic perturbations of the excited soliton should lead either to blowup, or to collapse to a less energetic soliton (or to the vacuum state), plus radiation. More recently there has been some results on the analysis of perturbations of multisoliton solutions, i.e. superpositions of widely separated and receding solitons (see [34], [32]; a similar result for the generalized KdV equation is in [26]); while these results do not apply directly to the \( L^2 \)-supercritical cubic equation (1), they do apply to certain mollified versions of the equation (see [34] for further discussion). We should also mention the work in [46], [47] on non-linear

\(^5\)One can show however that given any large scattering data \( u_+ \in H^1(\mathbb{R}^3) \), one can find a time interval \( (T_*, +\infty) \) and an energy class solution \( u : (T_*, +\infty) \times \mathbb{R}^3 \) such that \( \lim_{t \to +\infty} \|u(t) - e^{it\Delta}u_+\|_{H^1(\mathbb{R}^3)} = 0 \), basically by solving the Cauchy problem backwards in time from infinity; see [10]. But these scattering solutions do not capture all the large data solutions, for instance the soliton solutions are clearly not in this class. On the other hand, in the defocusing case every large energy (and even certain infinite energy) data scatters to a free solution, while conversely every free solution is the asymptotic limit of a nonlinear solution; see [20], [4], [15]. The arguments in the defocusing case rely on Morawetz inequalities, which have an unfavorable sign in the focusing case; it seems that Morawetz inequalities should still have some value for the focusing case but we were unable to obtain any natural application of them in this setting.
perturbations of ground and excited states of a Schrödinger equation with time-independent potential. These results however rely either on the variational characterization of the soliton one is perturbing, or on the fact that the time-dependent Hamiltonian $-\Delta - |u|^2$ is well approximated by an explicit linear Hamiltonian (e.g., the charge transfer model, or the linearization of (1) around a soliton) for which the spectral structure is well understood. In the general case we do not have good spectral control on this time-dependent Hamiltonian and so these techniques do not seem to extend to general large data.

However, in the special\(^6\) case of the cubic focusing NLS equation $iu_t + u_{xx} = -2|u|^2u$ in one dimension, which is completely integrable, one can use the methods of inverse scattering theory to analyze large data. For instance, if the initial data is smooth and rapidly decreasing, then it is known (see e.g. [52], [36]) that the solution eventually resolves into a finite number of solitons’ receding from each other, plus some dispersive radiation which goes to zero (although this radiation does not quite converge to a linear solution because in one dimension the cubic power is on the borderline between long-range and short-range; see [31]).

Thus one might conjecture that one has similar behavior (resolution into a multisoliton, plus dispersive radiation, for generic large data (with perhaps some exceptional channels such as breathers or slowly divergent solitons for a small unstable set of data), or else blowup in $H^1(\mathbb{R}^3)$ for other non-linear Schrödinger equations such as the ones studied in this paper; we shall refer to this rather informal statement as the soliton resolution conjecture. Apart from the results mentioned above when the data is close to a soliton or multi-soliton, there are only a few results known to support this conjecture. For instance, some progress has been made on controlling the growth of higher Sobolev norms for such equations, see [5], [4], [39]. In particular for $H^s$ solutions to (1) with the bounded energy assumption (3), it is known that the $H^s$ norms grow at most polynomially in time and that the local $H^s$ norm stays bounded; these results are consistent with the phenomenon of resolution into solitons. The growth of norms between $L^2$ and $H^1$ in the infinite defocusing energy case have also been studied, see [16], [17], again with polynomial type upper bounds on the growth. But to obtain control on asymptotic behavior uniformly in time (as opposed to polynomial growth bounds) seems quite difficult. In particular, the

\(^6\)We should caution however that the one-dimensional cubic NLS is $L^2$-subcritical, as opposed to the three-dimensional NLS which is $L^2$-supercritical; this seems to play a decisive role in the analysis. For $L^2$-subcritical equations one has excellent short-time control (in particular, there is no blowup), but very poor long-time control even in the defocusing case, whereas for $L^2$-supercritical focusing equations the situation is reversed. The $L^2$ critical equation (such as the 2D cubic NLS) is of course delicate at both short times and long times; see [50], [27], [28], [44] for some typical results regarding this equation.

\(^7\)This is an oversimplification. In the case when two or more solitons have equal speeds, it is possible for “breather” solutions which are periodic or even quasiperiodic, and localized for all time to appear. It is even possible to have two solitons of equal speeds and equal heights to recede from each other at a logarithmic rate $\log t$ in one dimension, although this latter phenomenon may be also due to the slow decay of the fundamental solution in one dimension and we do not know if it occurs in three dimensions. Nevertheless the generic behavior is that of resolution into receding solitons of different speeds, plus radiation, and even in the exceptional cases the non-radiation part of the solution is still very well localized and smooth, and has asymptotically constant velocity. We thank Jim Colliander for pointing out this subtlety.
soliton resolution conjecture for non-integrable equations and generic large data seems well out of reach of current techniques.

The case of general large data seems too difficult to analyze at present, so we now restrict our attention to the much simpler spherically symmetric case, where \( u(0, x) = u(0, |x|) \) (and hence \( u(t, x) = u(t, |x|) \)), by the rotational symmetry of (1) and the uniqueness theory. In this case the radial Sobolev inequality\(^8\)

\[
\| |x| u \|_{L^{\infty}(\mathbb{R}^3)} \lesssim \| u \|_{H^1(\mathbb{R}^3)}
\]  

combined with (3) tells us that \( u(t) \) decays away from the origin\(^9\) for all times \( t \), and thus we only expect at most a single stationary spherically symmetric soliton at the origin, and no other soliton behavior anywhere else.

Unfortunately even in the spherically symmetric case we were still unable to settle the soliton resolution conjecture. However, we have a number of partial results which may be of interest. We begin with two rather standard results (perhaps already known, though we could not find them explicitly in the literature). First, we show that if the solution ever has sufficiently small mass near the origin at a sufficiently late time, then one in fact has scattering and no soliton will ever form:

**Theorem 1.1.** There exist constants \( \varepsilon, R > 0 \) depending only on the energy \( E \) such that the following statement is true: if \( u \) is any spherically symmetric solution to (1) obeying (3), and

\[
\lim_{t \to +\infty} \inf \int_{B(0, R)} |u(t, x)|^2 \, dx \leq \varepsilon,
\]

then there exists a function \( u_+ \in H^1(\mathbb{R}^3) \) such that

\[
\lim_{t \to +\infty} \| u(t) - e^{it\Delta} u_+(t) \|_{H^1(\mathbb{R}^3)} = 0.
\]

Here \( B(0, R) \) is the ball \( B(0, R) := \{ x \in \mathbb{R}^3 : |x| < R \} \).

We prove this easy result (a variant of the small data scattering theory, combined with (5)) in Section 4.

From Theorem 1.1, we see that in order to have non-trivial asymptotic behavior (such as the presence of solitons), we must permanently station some mass near the spatial origin as \( t \to +\infty \). It is then natural to ask what the asymptotic behavior of this mass is. One can show without too much difficulty, even without any assumption of spherical symmetry, that the solution decouples into a free solution (which thus decays near the origin, thanks to local smoothing estimates) and a remainder

\(^8\)This inequality can be easily deduced by applying the one-dimensional Sobolev inequality \( \| v \|_{L^{\infty}(\mathbb{R})} \lesssim \| v \|_{H^1(\mathbb{R})} \) to the function \( v(|x|) := |x| u(|x|) \) and using Hardy’s inequality \( \| u/|x| \|_{L^2(\mathbb{R}^3)} \lesssim \| \nabla u \|_{L^2(\mathbb{R}^3)} \).

\(^9\)This explains our previous remark that the large values of \( u \) are not particularly relevant for our purposes; indeed, we see from (5) that they only make a difference near the spatial origin.
which is “weakly bound” in the sense that it is asymptotically orthogonal to all free solutions:

**Theorem 1.2.** Let $u$ be any solution to (1) obeying (3) (not necessarily spherically symmetric). Then there exists a unique decomposition

$$u(t) = u_{wb}(t) + e^{it\Delta}u_+$$

into the weakly bound component $u_{wb}$ and the linear radiation component $e^{it\Delta}u_+$, obeying the energy bounds

$$\|u_+\|_{H^1(R^3)} + \sup_{t \in [0, +\infty)} \|u_{wb}(t)\|_{H^1(R^3)} \lesssim 1$$

and the asymptotic orthogonality conditions

$$\lim_{t \to +\infty} \langle u_{wb}, e^{it\Delta}f \rangle_{L^2} = 0$$

for all $f \in H^{-1}(R^3)$, or equivalently that

$$\lim_{t \to +\infty} \langle u_{wb}, e^{it\Delta}f \rangle_{H^1} = 0$$

for all $f \in H^1(R^3)$, where

$$\langle f, g \rangle_{H^1} := \langle f, g \rangle_{L^2} + \langle \nabla f, \nabla g \rangle_{L^2} = \int_{R^3} f\overline{g} + \nabla f \cdot \nabla\overline{g} \ dx$$

is the inner product for the Hilbert space $H^1(R^3)$. Furthermore, $u_{wb}$ is a (local-in-time) approximate solution to (1) in the sense that

$$\lim_{T \to +\infty} ||(i\partial_t + \Delta)u_{wb} - F(u_{wb})||_{L^1_tH^{-1}_x([T,T+\tau] \times R^3)} = 0$$

for all $\tau > 0$. Finally, we have the mass decoupling identity

$$\text{MASS}(u_+) + \lim_{T \to +\infty} \text{MASS}(u_{wb}(T)) = \text{MASS}(u(0))$$

and the energy decoupling identity

$$\frac{1}{2} \int_{R^3} |\nabla u_+|^2 + \lim_{T \to +\infty} \text{ENERGY}(u_{wb}(T)) = \text{ENERGY}(u(0));$$

in particular the above two limits exist. Finally, if $u$ is spherically symmetric then $u_{wb}$ and $u_+$ are also spherically symmetric.

We prove this theorem (which is another variant of the small data scattering theory) in Section 5. We remark that (11), when combined with Theorem 1.1, shows that in the spherically symmetric case the asymptotically bound mass $\lim_{T \to +\infty} \text{MASS}(u_{wb}(T))$
is either equal to zero, or is bounded from below\textsuperscript{12} by some $\varepsilon = \varepsilon(E) > 0$. As for
the asymptotically bound energy, see Corollary 1.5 below.

Theorem 1.2 is consistent with the idea of global solutions to (1) decoupling into a
bound state plus radiation, but the control on the weakly bound state $u_{wb}$ given
by the above Theorem is very unsatisfactory; for instance, we do not know whether
$u_{wb}$ approaches a global solution to (1) in any reasonable sense (the above result
only shows that for any fixed length of time $\tau > 0$, the solution $u_{wb}$ approaches a
solution to (1) on intervals $[T, T + \tau]$ for $T$ sufficiently large depending on $\tau$). In
particular we do not know whether $u_{wb}(t)$ converges asymptotically to a soliton,
even if we restrict the time $t$ to a subsequence of times. However, in the spherically
symmetric case we can prove that $u_{wb}$ becomes asymptotically smooth and has
some decay:

**Theorem 1.3.** Let $u$ be any spherically symmetric global solution to (1) obeying
the energy bound (3). Then for any $J > 1$ and $\delta > 0$, we can decompose the weakly
bound component $u_{wb}$ of (6) further as

$$u_{wb}(t) = u_b(t) + o_{H^1(\mathbb{R}^3)}(1)$$

for all $t \geq 0$, where $o_{H^1(\mathbb{R}^3)}(1)$ is a time-dependent error whose $\dot{H}^1(\mathbb{R}^3)$ norm goes
to zero as $t \to \infty$, and $u_b(t)$ is a spherically symmetric function (depending on $J,
\delta$) obeying the symbol-type estimates

$$|\nabla^j_x u_b(t, x)| \lesssim \langle x \rangle^{-3/2 - j + \delta}$$

for all $x \in \mathbb{R}^3$, $t \geq T$, and $0 \leq j \leq J$, where $\langle x \rangle := (1 + |x|^2)^{1/2}$ and the implicit
constants can depend on the exponents $\delta, J$. Also, we have

$$\sup_{t \to +\infty} \|u_b(t)\|_{L^6(\mathbb{R}^3)} \lesssim 1.$$  

This theorem is considerably more technical than the previous two, and is the main
result of this paper. It is proven in Sections 6, 7, 8. As mentioned earlier, the
assumption (3) can be dropped if we mollify the non-linearity smoothly at infinity
to decay like $O(|u|^p)$ for $p < 1 + \frac{4}{3}$, although this requires a number of technical
changes to the argument (e.g. the introduction of the fractional chain rule) which
we omit.

Note that the error term in (13) is only controlled in the homogeneous space\textsuperscript{13}
$\dot{H}^1(\mathbb{R}^3)$ instead of the more natural energy space $H^1(\mathbb{R}^3)$; our arguments have the
defect of not being able to control the very low frequency portion of the solution $u$
in a satisfactory manner (in particular, we could not prevent the very low frequencies
of $u_b$ from absorbing a non-trivial amount of mass in the asymptotic limit). This is
also related to why the bounds in (14) only give decay of $O(\langle x \rangle^{-3/2})$ instead of the

\textsuperscript{12}Strictly speaking, this argument also requires Lemma 3.3 to dispose of the possible effect of
the radiation term $e^{it\Delta}u_i$. The above remark can also be derived in the non-spherically symmetric
case by a standard perturbation analysis of the free solution $e^{it\Delta}u_i$ at large times, similar to the
construction of wave operators for this equation; we omit the details.

\textsuperscript{13}Of course, since $H^1$ controls $L^6$ by Sobolev embedding, we do get convergence in $H^1(\mathbb{R}^3)$
on any fixed compact set in space, though again this would be more useful if we could improve
the bounds on $u_b$ in (14) from $O(\langle x \rangle^{-3/2 + \varepsilon})$ to the square-integrable $O(\langle x \rangle^{-3/2 - \varepsilon})$. 
exponential decay which is to be expected by comparison with the soliton solutions.

If one could improve the error control to $H^1$, and also improve the bounds in (14) from $O(x^{-3/2})$ to $O(x^{-3/2})$ or better, then the above theorem would say that the evolution of (1) in the bounded energy case (3) has a compact attractor in $H^1$ (once one projects out the linear radiation $e^{it\Delta u_0}$), namely the set generated by (14). In principle this makes the evolution of $u_{tb}$ almost periodic, and reduces the asymptotic study of (1) to the dynamical systems problem of understanding the flow on or near this compact attractor. It also raises the possibility that one could analyze the asymptotic behavior of the bound portion of the solution by passing to a weak limit at infinity. We caution however that the above theorem does not establish that $u_{tb}$ is in any way a global solution to (1); the best we could do was choose $u_{tb}$ so that it obeyed bounds of the form (10) (see also Lemma 10.1 below).

Thus Theorem 1.3 is still far from satisfactory in a number of ways, though it does represent some progress towards the soliton resolution conjecture. We speculate that the use of such identities as the virial identity, pseudoconformal conservation law, or the Morawetz inequalities (none of which are used in the proof of Theorem 1.3, which relies almost entirely on an analysis of the high frequencies only) may be useful tools to analyze this problem further; we give one example of this in Theorem 1.4 below, when we use virial-type identities to prove an asymptotic Pohozaev identity.

To put Theorem 1.3 in some context, we may compare it with the elliptic analogue, which is as follows. Consider a solution $u(x)$ to the nonlinear eigenfunction equation (4) for some $\omega > 0$, where $u$ is assumed to be spherically symmetric and finite energy, but not assumed to be non-negative (since that would force $u$ to be the unique ground state [14]). To put it another way, we assume that $u$ is a critical point of the Lagrangian associated to (4) but is not necessarily the minimizer. The analogue of Theorem 1.3 would be then that $u$ is smooth and rapidly decreasing. In the elliptic case, both facts follow easily from rewriting the equation (4) as $u = (\omega - \Delta)^{-1}(|u|^2 u)$ and then iterating this equation to bootstrap the finite energy and spherical symmetry assumptions to obtain arbitrary smoothness and decay; see e.g. [10].

In the dispersive case, where we have (1) instead of (4), we do not have the luxury of a smoothing operator such as $(\omega - \Delta)^{-1}$. However, we do have dispersion, which in principle achieves a similar effect (locally in space, at least) given sufficient amounts of time. The heuristic justification for the asymptotic regularity of $u$ is that any high frequency component of $u$ near the origin should quickly radiate to spatial infinity as $t \to \pm \infty$, but because $u(t)$ has bounded energy as $t \to +\infty$ this radiation should eventually decay in time on each fixed compact region of space (cf. the local smoothing effect [38], [48] for the Schrödinger equation). Thus if we restrict to $t > T$ for $T$ sufficiently large, the total energy of high frequencies that pass near the origin for times $t > T$ should be small. The main difficulty here is to ensure that the high frequency radiation does not interact significantly with the “bound states” of the time-dependent Hamiltonian $-\Delta - |u|^2$. This gets easier to accomplish if one already has some preliminary regularity result on $u$, which suggests that we can prove the regularity part of Theorem 1.3 by an iteration argument starting from
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similar to how one proceeds in the elliptic case. It also transpires that the further one gets away from the origin, the larger the range of frequencies one can classify as “high frequency” (roughly speaking, any frequency higher than \( (x)^{-1+\delta} \) can escape to spatial infinity either as \( t \to +\infty \) or \( t \to -\infty \), depending on whether it is outgoing or incoming with respect to the origin). This explains the decay factors in (14). Unfortunately we do not get infinite decay, because we could not find a dispersive analogue\(^{14}\) of the elliptic fact that the smoothing operator \((\omega - \Delta)^{-1}\) is highly local.

As indicated above, the methods used to prove Theorem 1.3 are fairly elementary, relying principally on the Duhamel formula, the Strichartz estimates and the dispersive inequality. There is one somewhat exotic ingredient however, which is a microlocal decomposition of free spherically symmetric solutions into incoming waves (waves moving towards the origin) and outgoing waves (waves moving away from the origin). This decomposition is useful because we have a freedom when applying the Duhamel formula to evolve either forwards in time (controlling the present from the past) or backwards in time (controlling the present from the future, taking advantage of the bounded energy hypothesis (3) on the future). To analyze outgoing waves it is easier if one evolves forwards in time (as the wave becomes increasingly dispersed), but for incoming waves it is easier to go backwards in time (in order to avoid the wave concentrating at origin, where the non-linear effects are strongest). To exploit this decomposition we will rely heavily on duality (and in particular of the unitarity of the free evolution operators \( e^{it\Delta} \)). This decomposition may be of independent interest (for instance, a similar decomposition is utilized in [35] to establish global-in-time local smoothing and Strichartz estimates on compact non-trapping perturbations of Euclidean space).

One of the main drawbacks of Theorem 1.3 is the poor control of the decay of \( u_b \), which is only shown to be \( O((x)^{-3/2+}) \). In particular, we were not able to place \( xu_b \) in \( L^2 \), which seems a natural objective as one may then apply the virial identity or pseudoconformal conservation law directly to obtain further information on \( u_b \).

We were however able to exploit the weaker decay in Theorem 1.3, combined with a modified virial identity, to prove the following statement:

**Theorem 1.4 (Asymptotic Pohozaev identity).** Let \( u \) is any spherically symmetric solution to (1) obeying (3), and let \( u_b \) be as in Theorem 1.3. Then we have

\[
\lim_{\tau \to \infty} \left( \lim_{T \to +\infty} \sup_{T} \left( \frac{1}{\tau} \int_{T}^{T+\tau} \int_{\mathbb{R}^3} 4|\nabla u_b|^2 - 3|u_b|^4 \, dx \, dt \right) \right) = 0.
\]

\(^{14}\)The difficulty is that, unlike the elliptic case, the portion of \( u \) near the origin can eventually influence even the very low frequencies \( u \) far away from the origin by Duhamel’s formula (27). To control this influence it seems that we need to control the spacetime integral of the non-linearity \(|u|^2u\) on large regions of spacetime. Using the equation (1) one can get some reasonable control on such spacetime integrals, but not infinite decay. Interestingly, in the case of a soliton \( u = Qe^{-i\omega t} \) one can get infinite decay on the spacetime integral of \(|u|^2u\) thanks to the time oscillation; if such a phenomenon held for general solutions then we would also get infinite decay of \( u_b \).
As the name of the Theorem suggests, this theorem is the dispersive analogue of the Pohozaev identity
\[
\int_{\mathbb{R}^3} 4|\nabla u|^2 - 3|u|^4 \, dx = 0
\]
for solutions to the non-linear eigenfunction equation (4), which is proven by multiplying (4) against \( x \cdot \nabla u \) and then integrating by parts. The above theorem is a (rather weak) generalization to the dispersive case, saying that the Pohozaev identity is asymptotically verified in an average sense for the bound portion of the solution (a similar estimate holds for \( u_{wb} \), by (13), Sobolev embedding, and the fact that both \( u_b \) and \( u_{wb} \) are bounded in \( H^1 \)). The standard dispersive generalization of the Pohozaev identity is Glassey’s virial identity
\[
\partial_t \int 2x \cdot \text{Im}(\nabla u \overline{u}) \, dx = \int 4|\nabla u|^2 - 3|u|^4 \, dx,
\] (16)
which, unsurprisingly, is also obtained by multiplying (1) by \( x \cdot \nabla u \) and then integrating by parts. Unfortunately the finite energy assumption on \( u \) is not enough to ensure that the integral on the left-hand side of (16) is finite (even with the spherical symmetry assumption), however if we replace \( u \) by \( u_b \) and we add a slight damping weight of \( \langle x \rangle \) then (14) will suffice to make the integral finite. We carry out this (standard) procedure and prove Theorem 1.4 rigorously in Section 10, after a review of virial identities in Section 9.

Combining Theorem 1.4 with Theorem 1.1 yields the following lower bound on the asymptotically bound energy:

**Corollary 1.5.** Let \( u \) is any spherically symmetric solution to (1) obeying (3), such that the asymptotically bound mass \( \lim_{t \to +\infty} \text{MASS}(u_{wb}) \) is non-zero. Then there exists \( \sigma = \sigma(E) > 0 \) such that the asymptotically bound energy is also bounded from zero:

\[
\lim_{t \to +\infty} \text{ENERGY}(u_b) = \lim_{t \to +\infty} \text{ENERGY}(u_{wb}) \geq \sigma > 0.
\]

**Proof** Let \( u \) be as above. By Theorem 1.1, there exists \( \varepsilon_0 > 0 \) and \( R > 0 \) (depending only on the energy \( E \)) such that

\[
\lim \inf_{t \to +\infty} \int_{B(0,R)} |u(t,x)|^2 \, dx \geq \varepsilon_0.
\]

By (6), (13), and Lemma 3.3 below, we thus have

\[
\lim \inf_{t \to +\infty} \int_{B(0,R)} |u_b(t,x)|^2 \, dx \geq \varepsilon_0.
\]

In particular, from Hölder we have

\[
\lim \inf_{t \to +\infty} \int |u_b(t,x)|^4 \, dx \geq c.
\]

\[\text{\textsuperscript{15}}\text{The left hand side is also equal to } \partial_t \int |x|^2|u|^2 \, dx, \text{ however in our applications we have nowhere near enough decay to make sense of this quantity and so we will rely instead on the left-hand side as stated in (16).}\]
for some $c = c(\varepsilon_0, R) > 0$. As a consequence, we have

$$\liminf_{t \to +\infty} \int_{\mathbb{R}^3} 4|\nabla u_b(t)|^2 - 3|u_b(t)|^4 \, dx \leq \liminf_{t \to +\infty} 8\text{ENERGY}(u_b) - c.$$ 

By Theorem 1.4 we thus obtain

$$\liminf_{t \to \infty} 8\text{ENERGY}(u_b) - c \geq 0.$$ 

Observe from (7), (15) that the error $o_{H^1(\mathbb{R}^3)}(1)$ in (13) is bounded in $H^1(\mathbb{R}^3)$ norm, and in particular by (2) will be decaying in $L^4(\mathbb{R}^3)$ norm. From this it is easy to see that

$$\lim_{t \to +\infty} \text{ENERGY}(u_b) - \text{ENERGY}(u_{wb}) = 0,$$ 

and the claim then follows from the above estimates (and (12), to establish existence of the limits).

Corollary 1.5 is a variant of the results in [21], [30], which state that initial data (which is either localized or spherically symmetric) with negative energy will lead to blowup in finite time. It is also consistent with soliton resolution, since solitons have strictly positive energy in the $L^2$ supercritical case (see e.g. [10]).

**Remark.** Except for Theorem 1.2, our results are restricted to the spherically symmetric case (although it seems Theorem 1.1 generalizes fairly easily, see the remarks at the end of Section 4), mainly because (5) gives us excellent control on where the solution is large (at the origin) and small (everywhere else). The general case is of course far more difficult, but one could speculate that similar results obtain for general bounded energy solutions to (1). At any given time there should be a bounded number of “points of concentration”, and the weakly bound component $u_{wb}$ should be asymptotically smooth and concentrated near these points, and decay away from these points. Furthermore these points should move at bounded speeds, though it is not clear to the author whether these speeds will eventually stabilize to be asymptotically constant. If these points of concentration end up receding from each other, then the behavior of the bound state near each concentration point should behave much like the analysis given here for the spherically symmetric case (after a Galilean transform), in analogy with the analysis in [34]. Thus ideally one should be able to reduce the problem of soliton resolution to the case where the only concentration point is the origin, though as with the results here, to proceed further seems to require some analysis of the dynamical system of the compact attractor associated to this concentration point, which the author does not know how to pursue.

2. Notation

We use the notation $X \lesssim Y$ or $X = O(Y)$ to denote the estimate $X \leq CY$, where $C > 0$ is a constant that can depend on exponents (such as regularity exponents $j$ or $\alpha$), as well as the energy $E$ in (3), but not on other parameters such as time parameters $t$ or functions $u$. 
We shall abuse notation and write \( f(|x|) = f(x) \) for spherically symmetric functions \( f \), i.e. we think of such functions as living on \([0, +\infty)\) as well as living on \( \mathbb{R}^3 \).

We fix \( \eta \) to denote a smooth spherically symmetric function on \( \mathbb{R}^3 \) adapted to the ball \( B(0, 1) \) which equals 1 on \( B(0, 1/2) \). For any \( R > 0 \) use \( \eta_R \) to denote the rescaling \( \eta_R(x) := \eta(x/R) \) of \( \eta \), thus \( \eta_R \) is adapted to \( B(0, R) \) and equals 1 on \( B(0, R/2) \). We shall frequently use differences such as \( \eta_R - \eta_r \) or \( 1 - \eta_R \) to localize space smoothly to various annular regions.

We define the Fourier transform \( \hat{f}(\xi) \) on \( \mathbb{R}^3 \) by
\[
\hat{f}(\xi) := \int_{\mathbb{R}^3} f(x) e^{-2\pi i x \cdot \xi} \, dx.
\]

We then define the Littlewood-Paley operators \( P_j \) for all integers \( j \) by
\[
\hat{P}_j f(\xi) := (\eta_{2^{j+1}}(\xi) - \eta_{2^j}(\xi)) \hat{f}(\xi).
\]

We record Bernstein’s inequality
\[
\|f\|_{L^p(\mathbb{R}^3)} \lesssim 2^{j\frac{\alpha}{2} - \frac{3}{2}\frac{1}{p}} \|f\|_{L^p(\mathbb{R}^3)}
\]
whenever \( j \in \mathbb{Z} \), \( 1 \leq p \leq q \leq \infty \), and the Fourier transform of \( f \) is supported on the ball \( B(0, C2^j) \) (e.g. \( f \) could equal \( P_j g \) for some \( g \)). This can be proven by applying Littlewood-Paley type operators and using Young’s inequality, as well as the standard bounds for the convolution kernel of the Littlewood-Paley operators.

We also define the ordinary Sobolev spaces \( H^s(\mathbb{R}^3) \) via the norm
\[
\|f\|_{H^s(\mathbb{R}^3)} := \|\xi^s \hat{f}\|_{L^2(\mathbb{R}^3)}
\]
and the homogeneous spaces \( \dot{H}^s(\mathbb{R}^3) \) by the norm
\[
\|f\|_{\dot{H}^s(\mathbb{R}^3)} := \|\xi^s \hat{f}\|_{L^2(\mathbb{R}^3)}.
\]

We shall unify these two spaces by defining the scaled Sobolev space \( \dot{H}_R^s(\mathbb{R}^3) \) for any spatial scale \( R > 0 \) by
\[
\|f\|_{\dot{H}_R^s(\mathbb{R}^3)} := \left( \int_{\mathbb{R}^3} (\xi^2 + \frac{1}{R^2})^s |\hat{f}(\xi)|^2 \right)^{1/2}.
\]

Thus \( \dot{H}_R^s(\mathbb{R}^3) \) is the inhomogeneous space \( H^s(\mathbb{R}^3) \), while \( \dot{H}^s(\mathbb{R}^3) \) is in some sense the limit of \( \dot{H}_R^s(\mathbb{R}^3) \) as \( R \to \infty \). There is also the easily verified scaling relationship
\[
\|f_R\|_{\dot{H}_R^s(\mathbb{R}^3)} = R^{3/2 - s} \|f\|_{H^s(\mathbb{R}^3)}
\]
for all \( R \), where \( f_R(x) := f(x/R) \). We remark that \( \dot{H}_R^s \) is the dual of \( H_{R}^{-s} \), and that we have the estimates
\[
\|f\|_{H^s(\mathbb{R}^3)} \lesssim \|f\|_{\dot{H}_R^s(\mathbb{R}^3)} \lesssim \|f\|_{H^s(\mathbb{R}^3)} \lesssim R^s \|f\|_{\dot{H}_R^s(\mathbb{R}^3)}
\]
when \( R \gtrsim 1 \) and \( s \geq 0 \), and dually that
\[
\|f\|_{H^s(\mathbb{R}^3)} \gtrsim \|f\|_{\dot{H}_R^s(\mathbb{R}^3)} \gtrsim \|f\|_{H^s(\mathbb{R}^3)} \gtrsim R^s \|f\|_{\dot{H}_R^s(\mathbb{R}^3)}
\]
when \( R \gtrsim 1 \) and \( s \leq 0 \).

We also have the following handy stability lemma with respect to cutoffs.
Lemma 2.1. Suppose that $a(x)$ is a function on $\mathbb{R}^3$ obeying the estimates
\[
\sup_{x \in \mathbb{R}^3} |\nabla^j a(x)| \leq A R^{-j}
\]
for some $A \geq 0$ and $R > 0$, and all $0 \leq j \leq J$. Then we have the estimate
\[
\|a f\|_{H^\alpha_{R} (\mathbb{R}^3)} \lesssim A \|f\|_{H^\alpha_{R} (\mathbb{R}^3)}
\]
for all $-J \leq \alpha \leq J$, where the implicit constants may depend on the exponents $\alpha$ and $J$.

Proof We may rescale $A = 1$ and $R = 1$. By duality we may take $\alpha \geq 0$; by interpolation we may assume that $0 \leq \alpha \leq J$ is an integer. But then the claim is clear from the Leibnitz rule and Hölder’s inequality.

We shall also need the standard Sobolev spaces
\[
\|f\|_{W^{k,p} (\mathbb{R}^3)} := \sum_{j=0}^{k} \|\nabla^j f\|_{L^p (\mathbb{R}^3)}
\]
and
\[
\|f\|_{\dot{W}^{k,p} (\mathbb{R}^3)} := \|\nabla^k f\|_{L^p (\mathbb{R}^3)}
\]
for $1 < p < \infty$ and non-negative integers $k$.

3. Preliminary estimates

Fix $u$ solving (1) and obeying (3); to begin with we do not assume spherical symmetry.

Let $e^{it\Delta}$ be the propagator for the free Schrödinger equation $iu_t + \Delta u = 0$; this is of course a unitary operator on $L^2$ (and indeed on every Sobolev space $H^s(\mathbb{R}^3)$). From the explicit formula\(^\text{16}\)
\[
e^{it\Delta} f(x) = \frac{C}{t^{3/2}} \int_{\mathbb{R}^3} e^{i|x-y|^2/4t} f(y) \, dy
\]
we obtain the standard dispersive inequality
\[
\|e^{it\Delta} f\|_{L^\infty (\mathbb{R}^3)} \lesssim t^{-3/2} \|f\|_{L^1 (\mathbb{R}^3)}
\]
\(^{16}\)We ignore the issue as to which branch of the square root of $t$ to take when $t$ is negative by hiding this issue under the undisclosed constant $C$. \]
and as a consequence the global Strichartz inequality (see [24] and the references therein)\textsuperscript{17}
\[
\|e^{it\Delta}f\|_{L^6_tL^6_x(\mathbb{R}^3)} + \|e^{it\Delta}f\|_{L^4_tL^2_x(\mathbb{R}^3)} \lesssim \|f\|_{L^2(\mathbb{R}^3)},
\]
and hence (since $e^{it\Delta}$ commutes with derivatives)
\[
\|e^{it\Delta}f\|_{L^2_tW^{1,6}_x(\mathbb{R}^3)} + \|e^{it\Delta}f\|_{L^4_tH^{1,6}_x(\mathbb{R}^3)} \lesssim \|f\|_{H^1(\mathbb{R}^3)}.
\]
In particular we observe from Sobolev embedding that
\[
\|e^{it\Delta}f\|_{L^6_tL^6_x(\mathbb{R}^3)} + \|e^{it\Delta}f\|_{L^4_tL^4_x(\mathbb{R}^3)} + \|e^{it\Delta}f\|_{L^4_tL^2_x(\mathbb{R}^3)} \lesssim \|f\|_{H^1(\mathbb{R}^3)}.
\]
As observed in [24], there are inhomogeneous versions of these estimates in which one introduces a forcing term in a dual Strichartz space. For instance, we have
\[
\|u\|_{L^6_tH^1_x([t_0,\infty) \times \mathbb{R}^3)} + \|u\|_{L^4_tL^4_x([t_0,\infty) \times \mathbb{R}^3)} \lesssim \|u(t_0)\|_{H^1(\mathbb{R}^3)} + \|\partial_x u + \Delta u\|_{L^2_tW^{-1,6}_x([t_0,\infty) \times \mathbb{R}^3)}
\]
for any (Schwartz) function $u$ and any time $t_0$. Of course, many other inhomogeneous Strichartz estimates are available, but we isolate this particular one as it shall arise specifically in our arguments\textsuperscript{18}.

We also need the following variant of above estimates:

**Lemma 3.1.** We have
\[
\|e^{it\Delta}f\|_{L^4_tL^\infty_x(\mathbb{R} \times \mathbb{R}^3)} \lesssim \|f\|_{H^1(\mathbb{R}^3)}.
\]

**Proof.** This almost follows by interpolating (21) with itself, but the presence of the $L^\infty_x$ means that endpoint Sobolev embedding cannot be applied directly, and we must proceed with a bit more care, using interpolation theory instead. We shall use the Littlewood-Paley operators $P_j$ defined earlier. Observe from (20) and Bernstein’s inequality that
\[
\|e^{it\Delta}P_j f\|_{L^8_tL^\infty_x(\mathbb{R} \times \mathbb{R}^3)} \lesssim 2^{j/2}\|P_j f\|_{L^2_tL^2_x(\mathbb{R}^3)} \sim 2^{-j/2}\|P_j f\|_{H^1(\mathbb{R}^3)},
\]
for any $j$, and similarly that
\[
\|e^{it\Delta}P_j f\|_{L^6_tL^\infty_x(\mathbb{R} \times \mathbb{R}^3)} \lesssim 2^{j/2}\|P_j f\|_{L^2_tL^2_x(\mathbb{R}^3)} \sim 2^{j/2}\|P_j f\|_{H^1(\mathbb{R}^3)}.
\]
By Marcinkiewicz interpolation we thus obtain the Lorentz space estimate
\[
\|e^{it\Delta}P_j f\|_{L^4_tL^\infty_x(\mathbb{R} \times \mathbb{R}^3)} \lesssim \|P_j f\|_{H^1(\mathbb{R}^3)}.
\]
\textsuperscript{17}In this radial setting there are in fact some extra smoothing estimates available, see [49], although for our argument we will not need any such refinements of Strichartz inequalities (nor will we need more complicated versions involving for instance $X^{s,b}$ spaces. The main difficulty in this work is not so much the recovery of local regularity, which is fairly easy since we are in a sub-critical setting with no derivatives in the nonlinearity, but rather in obtaining sufficient long-term control (e.g. decay) of various components of the solution in time, and the relatively basic Strichartz and dispersive estimates already seem adequate for this task, at least in the three-dimensional case.

\textsuperscript{18}Note that these Strichartz estimates are not particularly sharp; we concede a number of derivatives and do not always use the endpoint exponents. This is a reflection of the fact that the non-linearity is not at a critical power such as the $L^2$-critical power $p = 1 + \frac{4}{3}$ or the $H^1$-critical power $p = 5$.
and thus by the triangle inequality we have the Besov space estimate
\[
\|e^{it\Delta}f\|_{L_t^{4,1}L_x^{\infty}(\mathbb{R}^3)} \lesssim \sum_{j \in \mathbb{Z}} \|P_j f\|_{\dot{H}^1(\mathbb{R}^3)}.
\]
On the other hand, from (25) and (26) we have the estimate
\[
\int_E \|e^{it\Delta}P_j f\|_{L_t^\infty L_x^{\infty}(\mathbb{R}^3)} \, dt \lesssim \min(2^{-j/2}|E|^{1/2}, 2^{j/2}|E|) \|P_j f\|_{\dot{H}^1(\mathbb{R}^3)}
\]
for any measurable set \(E\). Summing this in \(j\), we obtain
\[
\int_E \|e^{it\Delta}f\|_{L_t^\infty L_x^{\infty}(\mathbb{R}^3)} \, dt \lesssim |E|^{3/4} \sup_j \|P_j f\|_{\dot{H}^1(\mathbb{R}^3)}
\]
and hence (since \(E\) was arbitrary) the weak-type estimate
\[
\|e^{it\Delta}f\|_{L_t^{4,\infty}L_x^{\infty}(\mathbb{R}^3)} \lesssim \sup_j \|P_j f\|_{\dot{H}^1(\mathbb{R}^3)}.
\]
Interpolating this with the previous Besov space estimate we obtain the result. 

We can extend these estimates from the linear evolution to the non-linear evolution (1), provided we localize in time. The key tool here is the well-known Duhamel formula
\[
u(t_1) = e^{i(t_1-t_0)\Delta}u(t_0) - i \int_{t_0}^{t_1} e^{i(t_1-t)\Delta}F(u(t)) \, dt \tag{27}
\]
for solutions to (1) and all times \(t_0, t_1 \in [0, +\infty)\), where we adopt the convention that \(\int_{t_0}^{t_1} = -\int_{t_1}^{t_0}\) if \(t_1 < t_0\). Of course, it is the time integral in (27) which poses the most problems, especially as \(|t_1-t_0|\) gets large. Generally speaking, our strategy in this paper will be to apply Strichartz estimates or local smoothing estimates in the short term (when \(|t_1-t|\) is small) and to use the dispersive inequality (19) in the long term (when \(|t_1-t|\) is large).

We now give the (standard) non-linear local-in-time analogue of the Strichartz estimates.

**Lemma 3.2.** Let \(u\) be a solution to (1) obeying (3). Then we have
\[
\sup_{t \in [0, +\infty)} \|u(t)\|_{L_t^p(\mathbb{R}^3)} \lesssim 1 \tag{28}
\]
for all \(2 \leq p \leq 6\), and
\[
\|u\|_{L_t^2 W_x^{2,6}([T,T+\tau] \times \mathbb{R}^3)} \lesssim \langle \tau \rangle^{1/2} \tag{29}
\]
for all \(T \geq 0\) and \(\tau > 0\). In particular we have
\[
\|u\|_{L_t^2 L_x^\infty([T,T+\tau] \times \mathbb{R}^3)} \lesssim \langle \tau \rangle^{1/2} \tag{30}
\]
for all \(T \geq 0\) and \(\tau > 0\). Similarly, we have
\[
\|u\|_{L_t^4 L_x^\infty([T,T+\tau] \times \mathbb{R}^3)} \lesssim \langle \tau \rangle^{1/4}. \tag{31}
\]
Proof The bound (28) follows immediately from (3) and Sobolev. To prove (29), (30), (31), it suffices to do so for \( \tau > 0 \) sufficiently small depending on \( E \), since the claim for larger time spans \( \tau \) then follows by decomposition of the time interval into smaller pieces. We now fix \( T, \tau \), and let \( X \) denote the quantity

\[
X := \| u \|_{L^2_t W^{1,6}_x([T,T+\tau] \times \mathbb{R}^3)} + \| u \|_{L^2_t L^{\infty}_x([T,T+\tau] \times \mathbb{R}^3)} + \| u \|_{L^4_t L^\infty_x([T,T+\tau] \times \mathbb{R}^3)}.
\]

By (21), (22), (24), (27) and Minkowski’s inequality we have

\[
X \lesssim \| u(T) \|_{H^1(\mathbb{R}^3)} + \int_T^{T+\tau} \| F(u(t)) \|_{H^1(\mathbb{R}^3)} \, dt.
\]

By (3) the first term on the right-hand side is \( O(1) \). For the second term we use Leibnitz and Hölder to bound

\[
\int_T^{T+\tau} \| F(u(t)) \|_{H^1(\mathbb{R}^3)} \, dt \lesssim \tau^{1/2} \| u \|_{L^4_t L^\infty_x([T,T+\tau] \times \mathbb{R}^3)} \| u \|_{L^2_t H^1([T,T+\tau] \times \mathbb{R}^3)}
\]

and so by (3) and definition of \( X \) we have

\[
X \lesssim 1 + \tau^{1/2} X^3
\]

and the claim follows by standard continuity arguments (e.g. letting \( \tau \) increase continuously from 0) if \( \tau \) is sufficiently small.

Finally, we record a Riemann-Lebesgue type lemma for the free Schrödinger propagator \( e^{it\Delta} \), which while preserving the \( H^s(\mathbb{R}^3) \) norms, sends many other norms to zero:

**Lemma 3.3.** For any \( u_0 \in H^1(\mathbb{R}^3) \) we have

\[
\lim_{t \to +\infty} \int_{\mathbb{R}^3} \langle x \rangle^{-\varepsilon} (|e^{it\Delta} u_0(x)|^2 + |\nabla e^{it\Delta} u_0(x)|^2) \, dx = 0
\]

for all \( \varepsilon > 0 \), and similarly

\[
\lim_{t \to +\infty} \int_{\mathbb{R}^3} |e^{it\Delta} u_0(x)|^p \, dx = 0
\]

for all \( 2 < p \leq 6 \).

**Proof** Observe that the expressions in the limits are certainly bounded by some quantity depending only on the \( H^1(\mathbb{R}^3) \) norm of \( u_0 \), thanks to Sobolev embedding and the fact that \( e^{it\Delta} \) preserves the \( H^1 \) norm. Thus by the usual limiting argument (and the linearity of \( e^{it\Delta} \)) it suffices to verify this lemma for test functions \( u_0 \), which are dense in \( H^1(\mathbb{R}^3) \). But in that case we see from (19) that \( |e^{it\Delta} u_0(x)| \) decays like \( O(t^{-3/2}) \) (with the implicit constants here depending on \( u_0 \)). Since \( |e^{it\Delta} u_0(x)| \) is also bounded in \( L^2 \), the claim follows.

4. Proof of Theorem 1.1

We now prove Theorem 1.1, which will be an easy consequence of Strichartz estimates and the dispersive inequality. Let \( \varepsilon > 0 \) be a small constant to be chosen
later, and let \( R \gg 1 \) be a large number depending on \( \varepsilon \) to be chosen later. From (22) we have
\[
\|e^{it\Delta}u(0)\|_{L_t^4L_x^6(\mathbb{R}^3)} \lesssim 1.
\]
Thus (by monotone convergence) we may find a time \( T_0 > \varepsilon^{-2} > 0 \) (depending on \( u \)) such that
\[
\|e^{it\Delta}u(0)\|_{L_t^4L_x^6((0, T_0] \times \mathbb{R}^3)} \lesssim \varepsilon. \tag{32}
\]
By hypothesis, we may then find a time \( T_1 \geq T_0 \) such that
\[
\int_{B(0, R)} |u(T_1, x)|^2 \, dx \lesssim \varepsilon.
\]
Then of course we have
\[
\int \eta_R |u(t, x)|^2 \, dx \lesssim \varepsilon, \tag{33}
\]
where \( \eta_R \) was defined in the notation section. We now bootstrap this control of the local mass at a fixed time \( T_1 \) to control of the local mass at nearby times. From (1) we observe the mass flux identity
\[
\partial_t |u|^2 = -2 \nabla \cdot \text{Im}(\nabla u \overline{u})
\]
and hence by integration by parts\(^{19}\)
\[
\partial_t \int \eta_R |u|^2 \, dx = 2 \int \nabla \eta_R \cdot \text{Im}(\nabla u \overline{u}).
\]
Since \( \|\nabla \eta_R\|_{L^\infty} = O(1/R) \), we thus obtain from (3) the crude estimate
\[
|\partial_t \int \eta_R |u(t)|^2 \, dx| \lesssim 1/R
\]
for all times \( t \) (far better estimates are available, but this is already sufficient for our purposes). Thus by (33) we see that
\[
\sup_{t \in [T_1 - \varepsilon^{-1/4}, T_1]} \int \eta_R |u(t, x)|^2 \, dx \lesssim \varepsilon
\]
if \( R \) is large enough depending on \( \varepsilon \). In particular we see that for any \( t \in [T_1 - \varepsilon^{-1/4}, T_1] \) we have
\[
\|u(t)\|_{L^3(B(0, R/2))} \lesssim \|u(t)\|_{L^6(\mathbb{R}^3)}^{1/2} \|u(t)\|_{L^2(B(0, R/2))}^{1/2} \lesssim \varepsilon^{1/2}
\]
(using (28)), while
\[
\|u(t)\|_{L^3(\mathbb{R}^3 \setminus B(0, R/2))} \lesssim \|u(t)\|_{L^\infty(\mathbb{R}^3 \setminus B(0, R/2))}^{2/3} \|u(t)\|_{L^2(\mathbb{R}^3)}^{1/3} \lesssim R^{-2/3}
\]
using (3), (5). Thus if \( R \) is large enough depending on \( \varepsilon \) we have
\[
\sup_{t \in [T_1 - \varepsilon^{-1/4}, T_1]} \|u\|_{L^3(\mathbb{R}^3)} \lesssim \varepsilon^{1/2}. \tag{34}
\]
We now claim the following smallness bound on the linear evolution (starting from \( T_1 \)).
\(^{19}\)One can justify this step by starting with smooth solutions \( u \) and then taking limits using the \( H^1 \) local well posedness theory. We will justify similar formal manipulations later in this paper without further comment.
Lemma 4.1. We have the estimate
\[ \| e^{i(t-T_1)\Delta} u(T_1) \|_{L_t^1 L_x^6([T_1, +\infty) \times \mathbb{R}^3)} \lesssim \varepsilon^{1/32}. \] (35)

Proof We first apply Duhamel’s formula (27) to obtain
\[ u(T_1) = e^{iT_1\Delta} u(0) - i \int_0^{T_1} e^{i(T_1-t')\Delta} F(u(t')) \, dt' \]
and hence
\[ e^{i(t-T_1)\Delta} u(T_1) = e^{it\Delta} u(0) - i \int_{T_1-\varepsilon^{-1/4}}^{T_1} e^{i(t-t')\Delta} F(u(t')) \, dt' \]
(36)
\[ - i \int_0^{T_1-\varepsilon^{-1/4}} e^{i(t-t')\Delta} F(u(t')) \, dt'. \]

From (32) we see that the contribution of the first term (the linear component) of (36) is acceptable. Now consider the second term (the “recent past” contribution). By Strichartz (22) and Minkowski’s inequality we see that the contribution of this term to (35) is bounded by
\[ \lesssim \int_{T_1-\varepsilon^{-1/4}}^{T_1} \| F(u(t')) \|_{H^1_t(\mathbb{R}^3)} \, dt'. \]
But by the Leibnitz rule and Hölder we can bound this by
\[ \lesssim \| u \|_{L_t^\infty L_x^2} \| u \|_{L_t^2 L_x^\infty} \| u \|_{L_t^2 W_x^{1,6}} \]
where all norms are over \([T_1 - \varepsilon^{-1/4}, T_1] \times \mathbb{R}^3\). But by Lemma 3.2 we see that
\[ \| u \|_{L_t^2 L_x^\infty}, \| \nabla u \|_{L_t^2 L_x^2} \lesssim \varepsilon^{-1/8} \]
and so by combining this with (34) we see that this contribution is acceptable.

It remains to prove that
\[ \| \int_0^{T_1-\varepsilon^{-1/4}} e^{i(t-t')\Delta} F(u(t')) \, dt' \|_{L_t^1 L_x^6([T_1, +\infty) \times \mathbb{R}^3)} \lesssim \varepsilon^{1/32}. \]
On one hand, observe from Duhamel’s formula that
\[ \int_0^{T_1-\varepsilon^{-1/4}} e^{i(t-t')\Delta} F(u(t')) \, dt' = e^{i(t-T_1+\varepsilon^{-1/4})\Delta} (u(T_1 - \varepsilon^{-1/4}) - u(0)) \]
and so from Strichartz (20), Hölder, and (3) we have
\[ \| \int_0^{T_1-\varepsilon^{-1/4}} e^{i(t-t')\Delta} F(u(t')) \, dt' \|_{L_t^1 L_x^6([T_1, +\infty) \times \mathbb{R}^3)} \lesssim \| u(T_1 - \varepsilon^{-1/4}) - u(0) \|_{L_t^2(\mathbb{R}^3)} \lesssim 1. \]
Thus by Hölder’s inequality again, it will suffice to show that
\[ \| \int_0^{T_1-\varepsilon^{-1/4}} e^{i(t-t')\Delta} F(u(t')) \, dt' \|_{L_t^1 L_x^\infty([T_1, +\infty) \times \mathbb{R}^3)} \lesssim \varepsilon^{1/16}. \]
But from the dispersive inequality (19) we have
\[
\| \int_0^{T_1-\varepsilon^{-1/4}} e^{i(t-t')\Delta} F(u(t')) \, dt' \|_{L^\infty(R^3)} \lesssim \int_0^{T_1-\varepsilon^{-1/4}} (t-t')^{-3/2}\|F(u(t'))\|_{L^1(R^3)} \, dt'.
\]
But by (28) we see that \(\|F(u(t'))\|_{L^1(R^3)} = O(1)\), and thus
\[
\| \int_0^{T_1-\varepsilon^{-1/4}} e^{i(t-t')\Delta} F(u(t')) \, dt' \|_{L^\infty(R^3)} \lesssim (\varepsilon^{-1/4} + (t - T_1))^{-1/2}.
\]
The claim follows.

We can pass from the bounds (35) on the linear solution to a corresponding bound for the non-linear solution by standard arguments. Indeed, from the Duhamel formula (27) we have
\[
u(t) = e^{i(t-T_1)\Delta} u(T_1) - i \int_{T_1}^t e^{i(t-t')\Delta} F(u(t')) \, dt',
\]
and upon taking \(L^4_t L^6_x([T_1, +\infty) \times R^3)\) norms, we see from (35) and Strichartz (23) that
\[
\|\nu\|_{L^4_t L^6_x([T_1, +\infty) \times R^3)} \lesssim \varepsilon^{1/32} + \|F(u)\|_{L^2_t W^{6/5}_x([T_1, +\infty) \times R^3)}.
\]
But by Leibnitz and Hölder we have
\[
\|F(u)\|_{L^2_t W^{6/5}_x([T_1, +\infty) \times R^3)} \lesssim \|\nu\|_{L^4_t L^6_x([T_1, +\infty) \times R^3)} \|u\|_{L^\infty_t H^{6/5}_x([T_1, +\infty) \times R^3)}.
\]
Thus from (3) and a standard continuity argument (e.g. replacing \([T_1, +\infty)\) by \([T_1, T]\) and then letting \(T \to +\infty\)) we thus see that
\[
\|\nu\|_{L^4_t L^6_x([T_1, +\infty) \times R^3)} \lesssim \varepsilon^{1/32}
\]
if \(\varepsilon\) was chosen sufficiently small. Finally, we set \(u_+\) as
\[
uu = e^{-it_1\Delta} u(t_1) - i \int_{t_1}^{+\infty} e^{-i t'\Delta} F(u(t')) \, dt';
\]
the Strichartz inequality (23) shows that the latter integral converges in \(H^1\) since we have just shown \(F(u)\) to lie in \(L^4_t W^{6/5}_x([T_1, +\infty) \times R^3)\). Then from the Duhamel formula again we see that
\[
uu = e^{-it\Delta} u_+ = i \int_{t}^{+\infty} e^{-i t'\Delta} F(u(t')) \, dt'
\]
for all \(t \geq T_1\), and thus (by the convergence of the integral) we have
\[
\lim_{t \to +\infty} \|\nuu = e^{-it\Delta} u_+\|_{H^1(R^3)} = 0
\]
as desired.

**Remark.** This argument can mostly be extended to the non-radial case, and shows in fact that one has scattering to a free solution whenever
\[
\lim_{t \to +\infty} \inf_{x_0 \in R^3} \sup_{B(x_0, R)} \int_{B(x_0, R)} |u(t, x)|^2 \, dx \leq \varepsilon
\]
for some specific \(\varepsilon, R > 0\) depending on the energy \(E\); in other words, one must always have some concentration of the \(L^2\) mass in time in order to prevent the
solution from scattering to a free solution, although in the non-radial case one does not have much control on the location $x_0 = x_0(t)$ of this concentration (though the sub-critical nature of this equation, combined with finite speed of propagation heuristics, suggest that we can make $x_0(t)$ depend in a Lipschitz manner in time).

We leave the details of this generalization to the reader (similar results also occur in e.g. [29], [6]).

5. Proof of Theorem 1.2

We now prove Theorem 1.2, which is another application of Strichartz and dispersive inequalities. We begin with a standard preliminary estimate, which in some sense asserts the existence of an adjoint wave operator.

Lemma 5.1. Let $u$ be any solution to (1) obeying (3) \( \text{not necessarily spherically symmetric} \), and let $f \in H^{-1}(\mathbb{R}^3)$. Then the limit

$$\lim_{t \to +\infty} \langle u(t), e^{it\Delta} f \rangle_{L^2}$$

exists and is bounded in magnitude by $O(\|f\|_{H^{-1}(\mathbb{R}^3)})$.

Proof It is clear that

$$\sup_{t \in [0, +\infty)} |\langle u(t), e^{it\Delta} f \rangle_{L^2}| \lesssim \|f\|_{H^{-1}(\mathbb{R}^3)}$$

just from (3) and duality of $H^1(\mathbb{R}^3)$ and $H^{-1}(\mathbb{R}^3)$. Thus by the linearity of $\langle u(t), e^{it\Delta} f \rangle_{L^2}$ in $f$ and a standard limiting argument, it will suffice to prove the convergence of the limit (37) when $f$ is a test function, i.e. a smooth, compactly supported function. In particular $f$ now lies in $L^1$ and so from (19) we have the bound

$$\|e^{it\Delta} f\|_{L^\infty} \leq C_f t^{-3/2}$$

for all $t \geq 0$, where $C_f$ is a constant depending on $f$.

It will suffice to show that (37) is a Cauchy sequence. Accordingly, we pick an $\varepsilon > 0$ and seek to find a large time $T > 0$ such that

$$|\langle u(t), e^{it\Delta} f \rangle_{L^2} - \langle u(T), e^{iT\Delta} f \rangle_{L^2}| \lesssim \varepsilon$$

for all $t \geq T$. To show this we use Duhamel’s formula (27) to write

$$u(t) = e^{i(t-T)\Delta} u(T) - i \int_T^t e^{i(t-t')\Delta} F(u(t')) \ dt'$$

and hence the left-hand side of (39) can be rewritten as

$$|\langle \int_T^t e^{i(t-t')\Delta} F(u(t')), e^{it\Delta} f \rangle_{L^2} dt'|.$$

Thus it will suffice to show that

$$\int_T^{+\infty} |\langle F(u(t')), e^{it\Delta} f \rangle_{L^2} | \ dt' \lesssim \varepsilon.$$
But from (28) we see that \( \|F(u)\|_{L^1_t L^3_x} \lesssim 1 \), while from (19) we have \( \|e^{it\Delta} f\|_{L^\infty_x(\mathbb{R}^3)} \lesssim (t')^{-3/2} \|f\|_{L^1_t L^3_x} \). The claim thus follows from the decay of \((t')^{-3/2}\) if \( T \) is taken sufficiently large.

The expression (37) is thus a bounded linear functional of \( f \) on \( H^{-1}(\mathbb{R}^3) \), and hence by duality there exists a unique \( u_+ \in H^1(\mathbb{R}^3) \) such that

\[
\lim_{t \to +\infty} \langle u(t), e^{it\Delta} f \rangle_{L^2} = \langle u_+, f \rangle_{L^2}
\]

for all \( f \in H^{-1} \), and we have the bound \( \|u_+\|_{H^1(\mathbb{R}^3)} \lesssim 1 \). If we then define \( u_{\text{wb}} \) by

\[
u_{\text{wb}}(t) := u(t) - e^{it\Delta} u_+
\]

then we clearly have (6) and (8) (and hence (9)), thanks to the unitarity of \( e^{it\Delta} \). Also we obtain (7) from (3). Note that this argument also shows that \( u_+ \) (and hence \( u_{\text{wb}} \)) are unique. Also it is clear from construction that if \( u \) is spherically symmetric then \( u_+ \) and \( u_{\text{wb}} \) are also.

Now we prove (10). Fix \( \tau \). Since

\[
(i\partial_t + \Delta)u = F(u)
\]

and

\[
(i\partial_t + \Delta)e^{it\Delta} u_+ = 0
\]

we have

\[
(i\partial_t + \Delta)u_{\text{wb}} - F(u_{\text{wb}}) = F(u) - F(u_{\text{wb}}).
\]

Thus it will suffice to show that

\[
\lim_{T \to \infty} \|F(u) - F(u_{\text{wb}})\|_{L^1_t H^1_x([T,T+\tau] \times \mathbb{R}^3)} = 0.
\]

Let us just show this for the homogeneous norm \( H^1_x \), the contribution of the \( L^2_x \) norm being similar. We observe the pointwise estimate

\[
|\nabla(F(u) - F(u_{\text{wb}}))| \lesssim (|\nabla u_{\text{wb}}| + |\nabla u|)(|u| + |u_{\text{wb}}|)|u - u_{\text{wb}}| + (|u| + |u_{\text{wb}}|)^2 |
abla(u - u_{\text{wb}})|
\]

and hence by Hölder

\[
\|F(u) - F(u_{\text{wb}})\|_{L^1_t H^1_x} \lesssim \|\nabla u_{\text{wb}}\| + |\nabla u|\|L^\infty_t L^3_x\| \|u\| + |u_{\text{wb}}|\|L^\infty_t L^3_x\| \|u - u_{\text{wb}}\|L^2_t L^6_x
\]

\[
+ \|u\| + |u_{\text{wb}}|\|L^2_t L^6_x\| \|u\| + |u_{\text{wb}}|\|L^\infty_t L^6_x\| \|\nabla(u - u_{\text{wb}})\|L^2_t L^6_x
\]

where all norms are in \([T,T+\tau] \times \mathbb{R}^3 \). From (21) we have

\[
|\nabla(u - u_{\text{wb}})| \lesssim 1
\]

and hence

\[
\lim_{T \to \infty} \|\nabla(u - u_{\text{wb}})\|_{L^2_t L^6_x([T,T+\tau] \times \mathbb{R}^3)} = 0.
\]

A similar argument using (22) gives

\[
\lim_{T \to \infty} \|u - u_{\text{wb}}\|_{L^2_t L^\infty_x([T,T+\tau] \times \mathbb{R}^3)} = 0.
\]

Meanwhile from (21), (22) and Lemma 3.2 we have

\[
\|u\| + |u_{\text{wb}}|\|L^2_t L^6_x([T,T+\tau] \times \mathbb{R}^3) \lesssim (\tau)^{1/2}
\]
for \( p = 6, \infty \). Combining all these bounds together with (7) and Sobolev embedding we thus obtain
\[
\lim_{T \to \infty} \| F(u) - F(u_{wb}) \|_{L^1([T,T+\tau] \times \mathbb{R}^3)} = 0
\]
as desired. The analogous argument for the \( L^2_x \) norm is similar (because every bound that we have on derivatives of \( u \) and \( u_{wb} \) themselves) and is omitted. This proves (10).

We now prove (11). Observe that
\[
\| u(t) \|_{L^2_x(\mathbb{R}^3)}^2 = \| u_{wb}(t) \|_{L^2_x(\mathbb{R}^3)}^2 + \| e^{it\Delta} u_+ \|_{L^2_x(\mathbb{R}^3)}^2 + 2 \text{Re} \langle u_{wb}(t), e^{it\Delta} u_+ \rangle_{L^2_x(\mathbb{R}^3)}.
\]
The left-hand side is \( \text{MASS}(u(0)) \) by conservation of mass. The second term on the right-hand side is \( \text{MASS}(u_+) \) since \( e^{it\Delta} \) is unitary. The third term on the right goes to zero as \( t \to +\infty \) by (8), and the claim follows.

Now we prove (12), which is in the same spirit but a little trickier. We begin with the \( H^1 \) version of the above identity,
\[
\| \nabla u(t) \|_{L^2_x(\mathbb{R}^3)}^2 = \| \nabla u_{wb}(t) \|_{L^2_x(\mathbb{R}^3)}^2 + \| \nabla e^{it\Delta} u_+ \|_{L^2_x(\mathbb{R}^3)}^2 + 2 \text{Re} \langle \nabla u_{wb}(t), \nabla e^{it\Delta} u_+ \rangle_{L^2_x(\mathbb{R}^3)}.
\]
Observe that the third term on the right still goes to zero by (8) (moving both derivatives over to \( e^{it\Delta} u_+ \)). The left-hand side is equal to \( 2\text{ENERGY}(u(t)) + \frac{1}{2} \int |u(t,x)|^4 \, dx \), while the first term on the right is equal to \( 2\text{ENERGY}(u_{wb}(t)) + \frac{1}{2} \int |u_{wb}(t,x)|^4 \, dx \). Finally, the second term on the right-hand side is just \( \int |\nabla u_+(x)|^2 \, dx \).

Putting all this together we see that (12) will follow if we can show
\[
\lim_{t \to +\infty} \int_{\mathbb{R}^3} |u(t,x)|^4 - |u_{wb}(t,x)|^4 \, dx = 0.
\]
From (3), (7) we see that \( \| u(t) \|_{L^4_x(\mathbb{R}^3)}, \| u_{wb} \|_{L^4_x(\mathbb{R}^3)} \lesssim 1 \). Thus the claim follows from the pointwise bound
\[
|u(t,x)|^4 - |u_{wb}(t,x)|^4 \lesssim (|u(t,x)| + |u_{wb}(t,x)|)^3 (|u - u_{wb}|(t,x))
\]
\[
= (|u(t,x)| + |u_{wb}(t,x)|)^3 |e^{it\Delta} u_+(x)|
\]
(40) and (41) and Lemma 3.3 (applied with \( p = 4 \)).

**Remark.** One can obtain more explicit Duhamel-style formulae for \( u_{wb} \) and \( u_+ \), namely
\[
u_{wb}(t) = i \int_t^{+\infty} e^{i(t-t')\Delta} F(u(t')) \, dt'
\]
and
\[
u_+ = u(0) - i \int_0^{+\infty} e^{-it\Delta} F(u(t)) \, dt
\]
although these integrals do not converge in the energy class, but only in weaker senses such as in the distributional sense (which is what is essentially done above). Note that the Duhamel-type formula for \( u_{wb} \) consists entirely of a forcing term (from the future) and no linear term; we thus expect \( u_{wb} \) to be smoother and more localized than \( u \) itself, although the infinite time integral \( \int_0^{+\infty} \) and the lack of time decay of \( F(u) \) does cause some difficulty in making this heuristic precise. As
indicated in Theorem 1.3, we will throw away a small energy error from $u_{wb}$ (which is basically caused by the coupling of the bound state with either the initial data $e^{it\Delta}u(0)$ or the data at infinity $e^{it\Delta}u_+,$ as well as the non-linear self-interactions of the radiation term $e^{it\Delta}u_+$) before establishing our final smoothness and decay estimates.

**Remark.** The above result establishes $L^2$ and $\dot{H}^1$ type estimates on the radiation term $u_+.$ It is an interesting problem as to whether there are similar estimates for higher regularities; in particular, if the map $u(0) \mapsto u_+$ is bounded from $H^s(\mathbb{R}^3)$ to $H^s(\mathbb{R}^3)$ for some $s > 1.$ This type of result is true in the defocusing case (see e.g. [15]), but our methods do not seem strong enough to establish this result for the focusing equation. The obstruction is a scenario in which the bound state ($u_{wb}$ or $u_b$) from continually emits minute amounts of high frequency radiation (which could conceivably cause the $H^s$ norm to become unbounded) without contradicting conservation of mass and energy, and without causing the bound state to collapse into the vacuum state. We do not know how to show that such a scenario does not occur.

### 6. Decomposition into incoming and outgoing waves

We now introduce a fundamental concept in our analysis of the free Schrödinger propagator $e^{it\Delta},$ namely the decomposition of a spherically symmetric function into *incoming* and *outgoing* components (plus a smooth error); these basically correspond to superpositions of radial waves $e^{i\omega |x|}$ with $\omega < 0$ and $\omega > 0$ respectively. A similar decomposition (constructed using pseudo-differential operators) is also available for non-spherically-symmetric functions, see for instance [35].

**Proposition 6.1.** Let $\delta > 0,$ and let $R \geq 0$ be such that either $R = 0$ or $R \gtrsim 1.$ Let $f$ be a spherically symmetric test function supported on the exterior region \{ $x : |x| \geq R$ \} (so if $R = 0$ then $f$ is just any spherically symmetric test function). Then there exists a decomposition

$$ f = f_+ + f_- + f_{\text{smooth}} \quad (42) $$

with the following properties:

- **($L^2$-boundedness)** We have

$$ \|f_+\|_{L^2(\mathbb{R}^3)}, \|f_-\|_{L^2(\mathbb{R}^3)}, \|f_{\text{smooth}}\|_{L^2(\mathbb{R}^3)} \lesssim \|f\|_{L^2(\mathbb{R}^3)}. \quad (43) $$

- **(Smooth error)** The function $f_{\text{smooth}}$ obeys the estimates

$$ \|\nabla f_{\text{smooth}}\|_{L^2(\mathbb{R}^3)} \lesssim (R^{(\delta-1)(1+\alpha)}) \|f\|_{H^\alpha(R^3)} \quad (44) $$

for all $\alpha \geq 0.$

- **(Asymptotic decay of incoming waves)** For any $u_0 \in L^2(\mathbb{R}^3)$ and any $\varepsilon > 0,$ there exists a time $T = T(u_0, \varepsilon, \delta, R) > 0$ such that

$$ |\langle e^{it\Delta}u_0, f_- \rangle| \lesssim \varepsilon \|f\|_{L^2(\mathbb{R}^3)} \quad (45) $$
for all \( t \geq T \) and all test functions \( f \) on \( \{ x : |x| \geq R \} \). (Informally, this means that as \( t \to +\infty \), the free wave \( e^{it\Delta} u_0 \) consists asymptotically of purely outgoing radiation).

- (Exponential decay near origin in the favorable time direction) We have
  \[
  \int_{t_0}^{+\infty} \| e^{i(t-t_0)\Delta} f_+ \|_{L^2(B(0,R/\delta))} \, dt \lesssim \langle R \rangle^{-\beta} \| f \|_{H^{-\alpha}(\mathbb{R}^3)}
  \] (46)
and
  \[
  \int_{-\infty}^{t_0} \| e^{i(t-t_0)\Delta} f_- \|_{L^2(B(0,R/\delta))} \, dt \lesssim \langle R \rangle^{-\beta} \| f \|_{H^{-\alpha}(\mathbb{R}^3)}
  \] (47)
for any \( \alpha, \beta \geq 0 \). (Thus, outgoing waves radiate away from the origin as \( t \to +\infty \), while incoming waves radiate away from the origin as \( t \to -\infty \).)

- (Local smoothing in the favorable time direction) We have
  \[
  \int_{t_0}^{+\infty} \| \langle x \rangle^{-2} e^{i(t-t_0)\Delta} f_+ \|_{H^{-\alpha}(\mathbb{R}^3)} \, dt \lesssim \langle R \rangle^{-1+\delta} \| f \|_{H^{-\alpha+1+\delta}(\mathbb{R}^3)}
  \] (48)
and similarly
  \[
  \int_{-\infty}^{t_0} \| \langle x \rangle^{-2} e^{i(t-t_0)\Delta} f_- \|_{H^{-\alpha}(\mathbb{R}^3)} \, dt \lesssim \langle R \rangle^{-1+\delta} \| f \|_{H^{-\alpha+1+\delta}(\mathbb{R}^3)}
  \] (49)
for any \( \alpha \geq 0 \). Here \( H^{\delta}_{\mathbb{R}}(\mathbb{R}^3) \) is the scaled Sobolev space defined in the notation section.

In the above estimates we allow implicit constants to depend on the exponents \( \delta, \alpha, \beta \) but not on \( R \).

**Proof** In what follows the reader may find it helpful to keep in mind the following heuristics: firstly, that the Littlewood-Paley projection operators \( P_j \) only introduce a spatial uncertainty of \( O(2^{-j}) \), by the uncertainty principle; and secondly, the dispersion relation indicates that the Schrödinger propagator \( e^{i(t-t_0)\Delta} \), when acting on functions of frequency \( \sim 2^j \) (such as \( P_j f \)), will move this function by speeds comparable to \( 2^j \). Because all functions here will be spherically symmetric, there are only two directions for propagation: inwards toward the origin, and outwards away from the origin. To separate these two modes\(^{20}\) we will use (truncated) radial Riesz projections.

In the argument that follows we assume some familiarity with the heuristics of stationary phase, and in particular the ability to get arbitrary decay\(^{21}\) of oscillatory

\(^{20}\) It is possible instead to proceed using the full machinery of Fourier integral operators and semi-classical analysis; for instance, \( f_\pm \) is basically the projection of \( f \) to the phase space region \( \xi \gtrsim \langle x \rangle^{-1+\delta}, \pm \xi \cdot x \geq 0 \), while \( f_{\text{smooth}} \) is basically the projection to the region \( \xi \lesssim \langle x \rangle^{-1+\delta} \). However, to keep the paper reasonably self-contained, we have proceeded more explicitly (though perhaps at the cost of brevity), relying mostly on integration by parts, stationary phase heuristics, and the Fourier inversion formula. The reader who is content to accept this Proposition may in fact skip the technicalities and move on to the proof of Theorem 1.3 in the next section.

\(^{21}\) We shall refer to this as the **principle of non-stationary phase**. We also need a Van der Corput lemma, which asserts that \( \int_{\mathbb{R}^3} e^{i\phi(x)} \psi(x) = O(\lambda^{-3/2}) \) if \( \psi \) has exactly one stationary point with \( \nabla^2 \psi \geq \lambda \) at that stationary point, \( \psi \) is a rescaled bump function, and \( \phi \) obeys the usual smoothness bounds on the domain of \( \psi \). See [42].
integrals $\int e^{i\phi(x)} \psi(x) \, dx$ via repeated integration by parts when the oscillation $\nabla \phi$ of the phase exceeds the amount one loses when differentiating $\psi$; we refer to [42] for more precise formulations of this heuristic.

Let us first consider the case when $R = 0$, and $f$ is supported on $B(0, 2)$. In this case we set $f_- := f_{\text{smooth}} := 0$ and $f_+ := f$. The bounds (43), (45), (44), (49) are then trivial, while (46), (47) are vacuously true (since $B(0, R/2)$ is empty). It thus remains only to verify the outgoing local smoothing estimate (48). We have to show that

$$\int_{t_0}^{\infty} \| \langle x \rangle^{-2} e^{i(t-t_0)\Delta} f \|_{H^{-\alpha}(R^3)} \, dt \lesssim \| f \|_{H^{-\alpha-\delta}(R^3)}.$$  

We use Littlewood-Paley operators to split $f = P_{\leq 0} f + \sum_{j > 0} P_j f$, where $P_{\leq 0} f := \sum_{j \leq 0} P_j f$. Consider first the contribution of the low frequencies $P_{\leq 0} f$. Observe from (19) that

$$\| e^{i(t-t_0)\Delta} P_{\leq 0} f \|_{L^1(B(0, 1))} \lesssim |t - t_0|^{-3/2} \| P_{\leq 0} f \|_{L^2} \lesssim |t - t_0|^{-3/2} \| f \|_{H^{-\alpha-1/\delta}},$$

and hence

$$\| e^{i(t-t_0)\Delta} P_{\leq 0} f \|_{L^2} \lesssim (t - t_0)^{-3/2} \| f \|_{H^{-\alpha-1/\delta}}.$$

By Hölder we thus see that

$$\| \langle x \rangle^{-2} e^{i(t-t_0)\Delta} P_{\leq 0} f \|_{L^2} \lesssim (t - t_0)^{-3/2} \| f \|_{H^{-\alpha-1/\delta}}$$

and the claim follows by integrating in $t$ (noting that $L^2$ controls $H^{-\alpha}$). To control the high frequencies, it will suffice to show that

$$\int_{t_0}^{\infty} \| \langle x \rangle^{-2} e^{i(t-t_0)\Delta} P_j f \|_{H^{-\alpha}(R^3)} \, dt \lesssim 2^{-\alpha+1/2} \| P_j f \|_{L^2(R^3)} \lesssim 2^{-\delta j/2} \| f \|_{H^{-\alpha+1/\delta}(R^3)},$$

for all $j \geq 0$, since the claim then follows by summing in $j$. Fix $j$; we define $\tau = \tau_j := 2^{(-1+\delta/2)j}$ and divide the above integral into the immediate future $\int_{t_0}^{t_0+\tau}$ and the later future $\int_{t_0+\tau}^{\infty}$. For the immediate future, we use Lemma 2.1 to discard $\langle x \rangle^{-2}$, and thus bound this contribution by

$$\lesssim \int_{t_0}^{t_0+\tau} \| e^{i(t-t_0)\Delta} P_j f \|_{H^{-\alpha}(R^3)} \, dt,$$

which is then acceptable by definition of $\tau$ since $e^{i(t-t_0)\Delta}$ preserves the $H^{-\alpha}$ norm. Now consider the later future $\int_{t_0+\tau}^{\infty}$. For this contribution we write $P_j = \tilde{P}_j P_j$ where $\tilde{P}_j$ is a slight enlargement of the Fourier projection operator $P_j$. Now observe that using stationary phase that the convolution kernel $K(x)$ of $e^{i(t-t_0)\Delta}$ $\tilde{P}_j$ is mostly concentrated in the region $|x| \gtrsim 2^{j} |t - t_0| \gtrsim 2^{\delta j/2}$ (the latter bound following definition of $\tau$); indeed from the principle of non-stationary phase we can obtain bounds of the form $|K(x)| \lesssim (2^{j} |t - t_0|)^{-M}$ in the region $|x| \ll 2^{j} |t - t_0|$. Thus the contribution of the region of space $|x| \ll 2^{j} |t - t_0|$ is easily seen to be manageable. Thus by applying a smooth cutoff we may restrict to the region $|x| \gtrsim 2^{j} |t - t_0|$. 


But then we may invoke Lemma 2.1 again to replace \( \langle x \rangle^{-2} \) by \( (2^j |t - t_0|)^{-2} \). Thus we can bound this contribution by

\[
\lesssim \int_{t_0 + \tau}^{t_0 + \tau} (2^j |t - t_0|)^{-2} \| e^{i(t - t_0)\Delta} P_j f \|_{H^{-\alpha}(\mathbb{R}^3)} \, dt,
\]

which by the boundedness of \( e^{i(t - t_0)\Delta} \) is bounded by

\[
2^{-2j} \tau^{-1} \| P_j f \|_{H^{-\alpha}(\mathbb{R}^3)}
\]

which is acceptable by definition of \( \tau \). This concludes the treatment when \( f \) is supported on \( B(0, 2) \).

It thus remains to consider the case \( R \gtrsim 1 \), since the case \( R = 0 \) then follows from the \( R \gtrsim 1 \) case and the localized case just considered. We can then replace \( \langle R \rangle \) by the comparable quantity \( R \) throughout. We then define \( f_{\text{smooth}} \) as

\[
f_{\text{smooth}} := \sum_{2^j \leq R^{d-1}} P_j f + \eta_R \sum_{2^j > R^{d-1}} P_j f,
\]

where \( \eta_R \) is defined in the notation section, and now proceed to verify the bounds (44) on \( f_{\text{smooth}} \). The contribution of \( \sum_{2^j \leq R^{d-1}} P_j f \) is clear just from taking Fourier transforms, so it will suffice to verify that

\[
\sum_{2^j < R^{d-1}} \| \nabla \eta_R P_j f \|_{L^2(\mathbb{R}^3)} \lesssim R^{(d-1)(1+\alpha)} \| f \|_{H^{-\alpha}(\mathbb{R}^3)}.
\]

But \( f \) is supported on \( \mathbb{R}^3 \setminus B(0, R) \), which is a distance \( R/2 \) from the support of \( \eta_R \), while the convolution kernel of \( P_j \) decays rapidly outside of \( B(0, 2^{-j}) \), as does all of its derivatives, so it is easy to verify the pointwise estimate

\[
\| \nabla \eta_R P_j f \|_{\infty} \lesssim (2^j R)^{-M} \| f \|_{H^{-\alpha}(\mathbb{R}^3)}
\]

for any \( M > 0 \). Summing over all \( j \) with \( 2^j > R^{d-1} \), we obtain the result (if \( M \) is sufficiently large depending on \( \delta, \alpha \) we may absorb all powers of \( R \) that arise on the right-hand side). This proves (44).

It then remains to decompose

\[
(1 - \eta_R) \sum_{2^j > R^{d-1}} P_j f = f_- + f_+
\]

with the desired properties. We shall do this by decomposing each \( (1 - \eta_R)P_j f \) separately for each \( 2^j > R^{d-1} \),

\[
(1 - \eta_R)P_j f = f_{-j} + f_{+j}
\]

and then defining \( f_{\pm} := \sum_{2^j > R^{d-1}} f_{\pm j} \).

We begin by taking the radial Fourier transform \( g_j \) of the odd extension of \( (1 - \eta_R)P_j f \),

\[
g_j(\rho) := \int_{-\infty}^{+\infty} e^{-2\pi i r \rho \text{sgn}(r)} (1 - \eta_R(|r|)) P_j f(|r|) \, dr,
\]

(51)
so that \( g_j \) is an odd function on \( \mathbb{R} \), and observing the Fourier inversion formula
\[
(1 - \eta_R) P_j f = \int_{-\infty}^{\infty} g_j(\rho) e_{\rho} \, d\rho
\]
on \( \mathbb{R}^3 \), where \( e_{\rho} \) is the radial function
\[
e_{\rho}(x) := e^{2\pi i \rho |x|}.
\]
We can thus define
\[
f_{\pm,j} := \int_{\pm[0, +\infty)} g_j(\rho) (1 - \eta_R/2) e_{\rho} \, d\rho
\]
and we thus obtain the decomposition (50) (and hence (42)); note that the factor \((1 - \eta_R/2)\) does not affect (50) since it equals 1 on the support of \((1 - \eta_R)\).

Now we verify the \( L^2 \) bounds (43). It suffices to show the claim for \( f_{\pm} \). By (52), it suffices to show that
\[
\| \int_{\pm[0, +\infty)} g(\rho)(1 - \eta_R/2) e_{\rho} \|_{L^2(\mathbb{R}^3)} \lesssim \| f \|_{L^2(\mathbb{R}^3)}
\]
where \( g := \sum_{2^j \geq R^{-1}} g_j \). We discard the \((1 - \eta_R/2)\) and use polar co-ordinates to write the left-hand side as
\[
\| r \int_{\pm[0, \infty)} g(\rho)e^{2\pi i r \rho} \|_{L^2}.
\]
Since \( g \) is odd, we can integrate by parts to estimate this as
\[
\lesssim \| \int_{\pm[0, \infty)} g'(\rho)e^{2\pi i r \rho} \|_{L^2}
\]
which by Plancherel is bounded by
\[
\lesssim (\int_{\mathbb{R}} |g'(\rho)|^2 \, d\rho)^{1/2}.
\]
Expanding out \( g' \) using (51), this is
\[
\lesssim (\int_{\mathbb{R}} \int_{-\infty}^{+\infty} e^{-2\pi i r \rho} \text{sgn}(r)(1 - \eta_R(|r|)) \sum_{2^j > R^{-1}} P_j f(|r|) \, r \, dr \|_{L^2}^{1/2},
\]
which by Plancherel again is bounded by
\[
\lesssim (\int_{-\infty}^{+\infty} \| (1 - \eta_R(|r|)) \sum_{2^j > R^{-1}} P_j f(|r|)^2 \, r^2 \, dr \|_{L^2}^{1/2}.
\]
But if we discard the cutoff \((1 - \eta_R)\) and undo the polar co-ordinates, this can be estimated as
\[
\| \sum_{2^j > R^{-1}} P_j f \|_{L^2(\mathbb{R}^3)} \lesssim \| f \|_{L^2(\mathbb{R}^3)} \| u_0 \|_{L^2(\mathbb{R}^3)},
\]
as desired.

Now we prove the asymptotic decay estimate (45) for the incoming wave. From (43) we already have
\[
\sup_{t \geq 0} \| (e^{it\Delta} u_0, f_-)_{L^2(\mathbb{R}^3)} \|_{L^2(\mathbb{R}^3)} \lesssim \| f \|_{L^2(\mathbb{R}^3)} \| u_0 \|_{L^2(\mathbb{R}^3)}.
\]
so by the usual Riemann-Lebesgue type limiting argument (as in Lemma 3.3) it will suffice to prove (45) assuming that \( u_0 \) is a (spherically symmetric) test function. But in that case \( e^{it\Delta}u_0 \) has the asymptotics

\[
e^{it\Delta}u_0(x) = t^{-3/2}e^{i|x|^2/4t}a(x/t) + o_{L^2}(R^3)(1)
\]

where \( a \) is a spherically symmetric Schwartz function (it is essentially the Fourier transform of \( u_0 \)) and \( o_{L^2}(R^3)(1) \) is an error whose \( L^2(R^3) \) norm goes to 1 as \( t \to +\infty \); see e.g. [43] (or one can work directly from (18)). Using (43) again, it thus suffices to show that

\[
t^{-3/2}\|e^{i|x|^2/4t}a(x/t), f_-\|_{L^2}(R^3^3) \lesssim \varepsilon \|f\|_{L^2}(R^3)
\]

for all \( f \in L^2(R^3) \) supported on \( R^3 \setminus B(0,R) \), and all \( t > T = T(a,\varepsilon,R) \). We expand out \( f_- \) using (52) and estimate the left-hand side by

\[
\lesssim t^{-3/2} \int_{-\infty}^{0} |g(\rho)|\|e^{i|x|^2/4t}a(x/t), (1 - \eta_{R/2})e^{\rho}\|_{L^2}(R^3) \, d\rho.
\]

We can write this in polar co-ordinates as

\[
\lesssim t^{-3/2} \int_{-\infty}^{0} |g(\rho)| \int e^{ir^2/4t - i\rho r^2}a(r/t)(1 - \eta_{R/2}) \, dr \, d\rho,
\]

and then break this up dyadically as

\[
\lesssim \sum_{k=0}^{\infty} t^{-3/2} \int_{-\infty}^{0} |g(\rho)| \int e^{ir^2/4t - i\rho r^2}a(r/t)(\eta_{2^k R} - \eta_{2^{k-1} R}) \, dr \, d\rho,
\]

(54)

But the phase \( e^{ir^2/4t - i\rho r^2} \) oscillates in \( r \) with frequency at least \( |\rho| + 2^k R/t \) on the support of \( \eta_{2^k R} - \eta_{2^{k-1} R} \) (because \( \rho \) is negative), and so by the principle of non-stationary phase we have the bounds

\[
| \int e^{ir^2/4t - i\rho r^2}a(r/t)(\eta_{2^k R} - \eta_{2^{k-1} R}) \, dr | \lesssim (2^k |\rho| R + 2^{2k} R^2/t)^{-M} (2^k R)^3
\]

for any \( M > 0 \) by repeated integration by parts (the function \( a(r/t) \) obeys symbol estimates in \( r \) regardless of what \( t \) is, because \( a \) is Schwartz). This decays rapidly for \( |\rho| \gg R^{-1/2} \). Hence we can estimate (54) as

\[
\lesssim \sum_{k=0}^{\infty} t^{-3/2} (2^{2k} R^2/t)^{-M} (2^k R)^3 (R^{-1/2} - k)^{1/2} ||g||_{L^2}.
\]

This decays rapidly for \( 2^k \gtrsim t^{1/2} R^{-1} \), so we may sum in \( k \) to obtain the bound

\[
\lesssim t^{-3/2}(t^{1/2} R^{-1} R)^3 (R^{-1} t^{-1/2} R)^{1/2} ||g||_{L^2} = t^{-1/4} ||g||_{L^2}.
\]

But by (51) and (one-dimensional) Plancherel we have the somewhat crude estimate

\[
||g_j||_{L^2} \lesssim ||(1 - \eta_R)P_j f||_{L^2} \lesssim ||P_j f||_{L^2(R^3)}
\]

and more generally

\[
||g||_{L^2} \lesssim ||(1 - \eta_R) \sum_{2^j > R^{k-1}} P_j f||_{L^2} \lesssim || \sum_{2^j > R^{k-1}} P_j f||_{L^2(R^3)} \lesssim ||f||_{L^2(R^3)}
\]

and the claim follows for \( t \) sufficiently large.
Now we prove (46), which is basically an application of the principle of non-stationary phase. It suffices to show that

\[
\int_{t_0}^{+\infty} \|\nabla e^{i(t-t_0)\Delta} f_{+,j}\|_{L^2(B(0,R/8))} \, dt \lesssim (2^j R)^{-M} \|P_j f\|_{L^2(\mathbb{R}^3)}
\]

for every \(2^j \geq R^{d-1}\) and every \(M > 0\), since the claim then follows by taking \(M\) large enough depending on \(\alpha, \beta, \delta\) and summing in \(j\).

Fix \(j\). By time translation invariance we may take \(t_0 = 0\). We expand the left-hand side using (52) and use Minkowski’s inequality to estimate by

\[
\lesssim \int_0^{+\infty} \int_0^{+\infty} \|g_j(\rho)\| \|\nabla e^{i\frac{t_0}{2}}(1 - \eta_{R/2})e_p\|_{L^2(B(0,R/8))} \, d\rho dt.
\]

It will suffice to prove the estimate when \((1 - \eta_{R/2})\) is replaced by \((\eta_R - \eta_{R/2})\), since the claim will then follow by replacing \(R\) by \((2^k R)\) for \(k = 0, 1, \ldots\) and summing the telescoping series. By (18), we have

\[
e^{i\Delta} (\eta_R - \eta_{R/2})e_p(x) = \frac{C}{t^{d/2}} \int_{\mathbb{R}^3} e^{i|x-y|^2/4t} (\eta_R - \eta_{R/2}(y))e^{2\pi i |y|} \, dy;
\]

using polar co-ordinates in \(y\) this becomes

\[
\frac{C}{t^{d/2}} e^{i|x|^2/4t} \int_0^\infty \int_0^\pi e^{-i|x| r \cos \theta / 2t} (\eta_R - \eta_{R/2}(r)) e^{i r^2 / 4t} e^{2\pi i r} \sin \theta \, d\theta r^2 \, dr.
\]

Substituting \(s = \cos \theta\), this becomes

\[
\frac{C}{t^{d/2}} e^{i|x|^2/4t} \int_0^1 \int_0^\infty e^{i r^2 / 4t} e^{-i|x| r / 2t} e^{2\pi i r} (\eta_R - \eta_{R/2}(r)) r^2 \, dr \, ds.
\]

If \(x \in B(0,R/8)\), then the phase \(e^{i r^2 / 4t} e^{-i|x| r / 2t} e^{2\pi i r}\) oscillates in \(r\) at a rate of at least \(\geq \rho + R/t\) on the support of \(\eta_R - \eta_{R/2}\) (note that this uses the positivity of \(\rho\), i.e. the fact that we are only considering outgoing waves). Meanwhile, every derivative applied to \((\eta_R - \eta_{R/2}(r)) r^2\) lowers this quantity by a factor of about \(R\). Thus one can integrate by parts repeatedly to obtain a bound of \(O(t^{-3/2} R^3 (\rho R + R^2/t)^{-M'})\) for any \(M'\). Applying \(\nabla_x\) introduces factors of the order of at worst \(R/t\) and thus we obtain a bound of the form

\[
|\nabla e^{i\Delta} (\eta_R - \eta_{R/2})e_p(x)| \lesssim t^{-5/2} R^4 (\rho R + R^2/t)^{-M}.
\]

Thus it remains to show that

\[
\int_0^{+\infty} \int_0^{+\infty} t^{-5/2} R^4 (\rho R + R^2/t)^{-M} |g_j(\rho)| \, d\rho dt \lesssim (2^j R)^{-M} \|P_j f\|_{L^2(\mathbb{R}^3)}.
\]

We can evaluate the \(t\) integral to estimate the left-hand side as

\[
\int_0^{+\infty} \left(\frac{R^2}{(R\rho)}\right)^{-3/2} R^4 (\rho R)^{-M} |g_j(\rho)| \, d\rho.
\]

If \(\rho\) was much larger than \(1/R\), e.g. \(\rho \geq (2^j R)^{1/2}\), then the claim is now easily proven from (55), since \(2^j \geq R^{d-1}\). So we may restrict our attention to the region \(\rho \leq (2^j R)^{1/2}\). But then we may use (51) to write

\[
g_j(\rho) = \int_{-\infty}^{+\infty} e^{-2\pi i r \rho} \text{sgn}(r) (1 - \eta_R(|r|)) P_j f(|r|) \, dr,
\]
which by collapsing the integral to \( \int_0^\infty \) and then undoing the polar co-ordinates becomes
\[
g_j(\rho) = C \int_{\mathbb{R}^3} \sin(2\pi |x|/\rho) \frac{1-\eta_R(x)}{|x|^2} P_j f(x) \, dx.
\]
We now integrate by parts repeatedly, integrating \( P_j f \) to effectively gain a factor of \( 2^{-j} \) (by the frequency localization) while differentiating \( \sin(2\pi |x|/\rho) \) or \( 1-\eta_R(x) \), at worst losing a factor of \( (2^j/R)^{1/2} \). This will eventually gain us an arbitrary power of \( (2^j R)^{-M} \), and then if we estimate everything else crudely (e.g. using Cauchy-Schwarz and Plancherel to handle the \( \rho \) integral) we will eventually show this contribution is acceptable (recall that \( 2^j R > R^\delta \) and so we can eventually overcome any polynomial losses in \( R \)). This proves (46). The proof of (47) is very similar and is left to the reader (it is essentially the conjugate of (46)), so we now turn to (48) and (49). Actually it will suffice to prove (48) since (49) is essentially the conjugate of (48) (recall that conjugation turns the forward Schrödinger evolution into the backward Schrödinger evolution).

We now prove (48). Again we may use time translation invariance to set \( t_0 = 0 \). First observe that the portion in the ball \( B(0,R/8) \) can be easily treated by the estimate (46) just proven, so we may freely insert a cutoff \( (1-\eta_{R/8}) \). By dyadic decomposition in \( j \) it will suffice to show that
\[
\int_0^{+\infty} \|(1-\eta_{R/8}) \langle x \rangle^2 e^{it\Delta} f_{+,j} \|_{H^{-\alpha}_R(\mathbb{R}^3)} \, dt \lesssim R^{-1+\delta} \|P_j f\|_{H^{-\alpha+1}_R(\mathbb{R}^3)}
\]
for all \( 2^j \geq R^{\delta^{-1}} \).

Fix \( j \). The intuition here is that at time \( t \), the wave \( f_{+,j} \) will have propagated away from the origin by a distance of \( \sim 2^j t \), and will hence the weight \( \langle x \rangle^{-2} \) will have size \( O((2^j t + R)^{-2}) \). Integrating this in time gives us \( R^{-1} 2^{-j} \), which explains both the gain of the power of \( R \) and the smoothing of one derivative. This should be contrasted with the standard Kato local smoothing result [38], [48], which works both forward and backwards in time (for both incoming and outgoing waves) and gives square-integrable bounds in time, but gains only half a derivative and no gain in \( R \).

We turn to the details. We first split the time integral \( \int_0^{+\infty} \) into the near future \( \int_0^{\tau} \) and the distant future \( \int_{\tau}^{\infty} \), where
\[
\tau := 2^{-j} R^{1+\delta/2}
\]
(this can be interpreted as the time it takes for the wave to leave the region \( |x| \sim R \), times a safety margin of \( R^{\delta/2} \)). We first consider the near future. For this region we estimate \( (1-\eta_{R/8}) \langle x \rangle^2 \) by \( R^{-2} \) (using Lemma 2.1) and estimate this contribution by
\[
\int_0^{\tau} R^{-2} \|(e^{it\Delta} f_{+,j}) \|_{H^{-\alpha}_R(\mathbb{R}^3)} \, dt.
\]
Since \( e^{it\Delta} \) preserves the \( H^{-\alpha}_R \) norm, it will thus suffice by (56) to show that
\[
\|f_{+,j}\|_{H^{-\alpha}_R(\mathbb{R}^3)} \lesssim \|P_j f\|_{H^{-\alpha}_R(\mathbb{R}^3)}
\]
(57).
(this estimate will also be useful for the treatment of the distant future, below).

We expand this using (52) as

$$\| \int_{[0, +\infty)} g_j(\rho)(1 - \eta_{R/2})e_\rho \, d\rho \|_{L^2_\xi(\mathbb{R}^3)} \lesssim 2^{-\alpha_j} \|P_j f\|_{L^2_\xi(\mathbb{R}^3)}.$$  

By an easy modification of the proof of (43) we already have that

$$\| \int_{[0, +\infty)} g_j(\rho)(1 - \eta_{R/2})e_\rho \, d\rho \|_{L^2_\xi(\mathbb{R}^3)} \lesssim \| P_j f \|_{L^2_\xi(\mathbb{R}^3)}.$$  

so by Littlewood-Paley decomposition (and the hypothesis $2^j \gtrsim R^{1 - \delta}$) it will suffice to prove the estimates

$$\| \sum_{j' \leq j - 10} P_{j'} \int_{[0, +\infty)} g_j(\rho)(1 - \eta_{R/2})e_\rho \, d\rho \|_{L^2_\xi(\mathbb{R}^3)} \lesssim (2^j R)^{-M} \| P_j f \|_{L^2_\xi(\mathbb{R}^3)} (58)$$

for all $M$; here of course the implicit constant is allowed to depend on $M$.

This estimate is based on two observations; firstly, that the Fourier transform $(1 - \eta_{R/2})e_\rho$ is concentrated near the sphere $|\xi| \sim \rho$ (and in particular $P_j((1 - \eta_{R/2})e_\rho)$ is very small if $\rho \gg 2^j$), and secondly that $g_j(\rho)$ decays very quickly if $\rho/2^j$ is small.

We begin by quantifying the first observation. We write the Fourier transform $(1 - \eta_{R/2})e_\rho$ as a telescoping sum

$$\sum_{k=0}^{\infty} \int_{\mathbb{R}^3} (\eta_{2^k R}(y) - \eta_{2^{k-1} R}(y)) e^{2\pi i (\rho - |\xi|) y} \, dy.$$  

If $\rho > |\xi| + \frac{1}{R}$, then the phase oscillates by at least $\rho - |\xi|$, and so by the principle of non-stationary phase we can bound this expression by

$$\lesssim \sum_{k=0}^{\infty} O((2^k R)^3 (\rho - |\xi| - M)) = O(R^3 (\frac{\rho - |\xi|}{R})^{-M})$$

for any large $M$. In particular we see from Plancherel that

$$\| \sum_{j' \leq j - 10} P_{j'}((1 - \eta_{R/2})e_\rho) \|_{L^2_\xi(\mathbb{R}^3)} \lesssim ((2^j + \rho) R)^{-M}$$

when $\rho \geq 2^{j-5}$ for any $M$ (note that this decay can absorb any bounded powers of $2^j$ or $R$). This easily allows us to control the portion of (58) arising from the region $\rho \geq 2^{j-5}$, using (55).

Now we consider the contribution where $\rho \leq 2^{j-5}$. For this contribution we discard the projector $\sum_{j' \leq j - 10} P_{j'}$ and instead establish decay of $g_j(\rho)$. By (51), (17) and the Fourier inversion formula we have

$$g_j(\rho) = \int_{\mathbb{R}^3} (\eta_{2^{j+1}}(\xi) - \eta_{2^j}(\xi)) \hat{f}(\xi) \int_{-\infty}^{+\infty} e^{-2\pi i \rho \mathrm{sgn}(r)(1 - \eta_{R}(|r|)))} e^{2\pi i |\xi| r} \, dr \, d\xi$$

where $e_1 = (1, 0, 0)$ (say). We can divide the $r$ integral into positive and negative axes, and then decompose further dyadically (note there is no singularity at the origin because of the cutoff $1 - \eta_{R}(|r|)$). If $\rho \leq 2^{j-5}$, then the phase oscillates at a rate of at least $\gtrsim 2^j$, because of the support of the Littlewood-Paley multiplier.
Thus by integrating by parts as before, we may bound this expression by

$$|g_j(\rho)| \lesssim \int_{\mathbb{R}^3} |\eta_{2^j+1}(\xi) - \eta_{2^j}(\xi)||f(\xi)|R(2^j R)^{-M} d\xi$$

for any $M > 0$. Using Hölder and Plancherel, and using the $(2^j R)^{-M}$ factor to absorb any powers of $R$ and $2^j$ which appear, we thus obtain the bound

$$|g_j(\rho)| \lesssim (2^j R)^{-M} \|P_j f\|_{L^2(\mathbb{R}^3)}$$

(59)

for all $\rho \lesssim 2^{j-5}$. In fact a similar argument also gives similar bounds for arbitrarily many derivatives of $g_j(\rho)$ in this region. By another application of Plancherel (in the radial direction) we thus have

$$\| \int_{0}^{2^{j-5}} g_j(\rho)(1 - \eta_{R/2}) e_\rho \ d\rho \|_{L^2(\mathbb{R}^3)} \lesssim (2^j R)^{-M} \|P_j f\|_{L^2(\mathbb{R}^3)}$$

(again absorbing any powers of $2^j$ or $R$ which appear into the $(2^j R)^{-M}$ factor, and so this portion of the $\rho$ integral is also acceptable. This proves (58), and concludes the treatment of the near future.

Now we consider the distant future $f_\tau^\infty$; we have to show that

$$\int_{\tau}^{\infty} \| \frac{1}{(1 - \eta_{R/8})} |x|^{-2} e^{it\Delta} f_{+,j} \|_{H^{a}_R(\mathbb{R}^3)}^2 \ dt \lesssim R^{-1+\delta} \|P_j f\|_{H^{a-1}_R(\mathbb{R}^3)}$$

We divide the time integral further into dyadic blocks; it will suffice to show that

$$\int_{2^k \tau}^{2^{k+1} \tau} \| \frac{1}{(1 - \eta_{R/8})} |x|^{-2} e^{it\Delta} f_{+,j} \|_{H^{a}_R(\mathbb{R}^3)}^2 \ dt \lesssim 2^{-\delta k} R^{-1+\delta} \|P_j f\|_{H^{a-1}_R(\mathbb{R}^3)}$$

for each $k \geq 0$.

Fix $k$. Recalling the heuristic that the wave $f_{+,j}$ propagates outward at speed $2^j$, we expect the function $f_{+,j}$ to be concentrated in the region $|\xi| \gtrsim 2^{j+k} \tau \gg 2^k R$. Accordingly, we split the cutoff $(1 - \eta_{R/8})$ into the near component $\eta_{2^k R} - \eta_{R/8}$ and the far component $1 - \eta_{2^k R}$.

Let us deal with the far component first. We can estimate $(1 - \eta_{2^k R}) |x|^{-2}$ by $(2^k R)^{-2}$ (using Lemma 2.1), and so we can control this contribution by

$$\lesssim \int_{2^k \tau}^{2^{k+1} \tau} (2^k R)^{-2} \|e^{it\Delta} f_{+,j} \|_{H^{a}_R(\mathbb{R}^3)}^2 \ dt.$$  

Using the boundedness of $e^{it\Delta}$ on $H^{a}_R$ and (57) (and then (56)) we can bound this by

$$\lesssim 2^{k \tau} (2^k R)^{-2} \|P_j f\|_{L^2(\mathbb{R}^3)} \sim 2^{-k} R^{-1+\delta/2} \|P_j f\|_{H^{a-1}_R(\mathbb{R}^3)}$$

which is acceptable.

Now consider the near component, which will turn out to be very small. We expand out $f_{+,j}$ using (52) to estimate this contribution (using Minkowski’s inequality) by

$$\lesssim \int_{2^k \tau}^{2^{k+1} \tau} \int_{[0, \infty)} \ |g_j(\rho)||\eta_{2^k R} - \eta_{R/8})| |x|^{-2} e^{it\Delta}((1 - \eta_{R/2}) e_\rho) \|_{H^{a}_R(\mathbb{R}^3)} \ dt.$$
We crudely estimate the $H^{α}_R$ norm by the $L^2(\mathbb{R}^3)$ norm, and use Cauchy Schwarz, combined with the observation that $(η_{2^kR} - η_{R/8})^{-2}$ has bounded $L^2$ norm on $B(0, 2^kR)$, to estimate the previous by

$$\lesssim \int_{2^kτ}^{2^{k+1}τ} \int_{[0, +∞)} |g_j(ρ)| ||e^{ıtΔ}((1 - η_{R/2})e_ρ)||_{L^∞(B(0, 2^kR))} dt;$$

we shall be able to get away with these very inefficient estimates because we will shortly gain a large power of $(2^jR)^{-M}$ which can absorb these losses. Let us first deal with those $ρ$ for which $ρ ≥ 2^j^{-5}$; as we saw in the treatment of the immediate future, this is the dominant case. We now compute $e^{ıtΔ}((1 - η_{R/2})e_ρ)(x)$ for $x ∈ L^2(B(0, 2^kR))$, using (18), as

$$e^{ıtΔ}((1 - η_{R/2})e_ρ)(x) = Ct^{-3/2} \int_{\mathbb{R}^3}(1 - η_{R/2}(x))e^{2πiρ|y| + i|x-y|^2/4t} dy;$$

we may decompose this dyadically as

$$Ct^{-3/2} \sum_{m=0}^{∞} \int_{\mathbb{R}^3}(η_{2^mR} - η_{2^{m-1}R}(x))e^{2πiρ|y| + i|x-y|^2/4t} dy.$$ (61)

Observe that the gradient of the phase $2πρ|y| + |x-y|^2/4t$ in $y$ is

$$\nabla_y(2πρ|y| + |x-y|^2/4t) = (ρ + \frac{|y|}{2t}) \frac{y}{|y|} - \frac{x}{2t}.$$ (62)

Since $ρ ≥ 2^j^{-5}$, $x ∈ B(0, 2^kR)$, $|y| ∼ 2^mR$, and $t ∼ 2^kτ ∼ 2^kR/2^j$, we thus see that (62) has magnitude $≥ ρ + 2^mR$; the point is that $x/2t$ has magnitude at most $O(R/τ) ≪ O(ρ)$ and thus does not significantly affect the magnitude of the (62). Thus by repeated integration by parts we may estimate

$$|e^{ıtΔ}((1 - η_{R/2})e_ρ)(x)| ≤ t^{-3/2} \sum_{m=0}^{∞} (2^mR)^3(2^mRρ)^{-M}$$

for any $M$; in particular we have

$$|e^{ıtΔ}((1 - η_{R/2})e_ρ)(x)| ≤ (ρR)^{-M}2^{-3k/2}$$

(using the the fact that $ρ ≥ 2^j^{-5}$ and $2^j_1 ≥ R_1^{d-1}$ to absorb all other factors using the $(ρR)^{-M}$ term). Combining this with (55) we see that this contribution to (60) is

$$\lesssim 2^{-k/2}R^{-M}||P_jf||_{H^{α-1}_R(\mathbb{R}^3)}$$

for any $M ≥ 0$, as desired (note that the factor of $(ρR)^{-M}$ can absorb any losses of $2^j$ or $R$ which appear).

Finally we consider the portion of the low frequencies where $ρ < 2^j^{-5}$. Here we will enjoy unlimited decay in the $2^j$ and $R$ parameters (because of (59)) so the only issue is to obtain the required decay in the $2^k$ parameter, which basically amounts to ensuring that one obtains the expected $t^{-3/2}$ decay in the $L^∞$ norm. Again we expand $e^{ıtΔ}((1 - η_{R/2})e_ρ)(x)$ as (61), but divide now into two cases, depending on whether $m ≤ k+10$ or $m > k+10$. First suppose $m > k+10$; then the gradient (62) has magnitude at least $≥ |y|/t ∼ 2^{m-k}2^jR^{-d/2}$ (using (56)), because the $x/2t$ term
is much smaller than the other terms. Thus we may integrate by parts repeatedly and estimate this portion of (61) in magnitude by

$$\lesssim t^{-3/2} \sum_{m > k+10} (2^m R) (2^m R^2 2^{m-k} R^{-3/2})^{-M}$$

for arbitrary $M$. Discarding the $2^{m-k}$ factor we thus see this expression is $O(t^{-3/2} 2^{-Mk} (2^j R^{-M})$ for any $M$; inserting this bound back into (60) and using (59) we see that this contribution is acceptable.

Now suppose that $m \leq k+10$. Here the gradient (62) might vanish, but it can only do so at one point (when $y$ is parallel to $x$ and $\rho + |y|/2t = |x|/2t$). Furthermore we have the double derivative estimate

$$\nabla_x^2 (2\pi \rho |y| + |x-y|^2/4t) \geq 1/2t$$

where we use $A \geq B$ to denote the statement that $A - B$ is positive definite; this is basically due to the fact that the function $2\pi \rho |y|$ is (non-strictly) convex, because $\rho$ is positive. Hence by Van der Corput’s lemma (see e.g. [42]) we obtain a bound of

$$\left| \int_{\mathbb{R}^3} (\eta_{2^m R} - \eta_{2^{m-1} R}(x)) e^{2\pi i \rho |y|} e^{i|x-y|^2/4t} \, dy \right| \lesssim t^{-3/2};$$

summing this over $m \leq k+10$ we thus see that this contribution to (61) is at most $O(k^{-3/2})$. (Actually we may easily get rid of the $(k)$, but it will not be important in our argument in any event). If we combine this with (59) we obtain the desired result.

This proves (48). As mentioned earlier, the proof of (49) is similar, so the proof of Proposition 6.1 is now complete.

### 7. Exterior energy decay of $u_{WB}$

We now begin the proof of Theorem 1.3, which will be done in a number of stages. In this section we will establish the following preliminary decay property of $u_{WB}$ away from the origin:

**Proposition 7.1.** Let the notation and assumptions be as in Theorem 1.3, and let $0 < \delta < 1$ be arbitrary. Then for every $R \geq 0$ we have

$$\limsup_{t \to +\infty} \int_{\mathbb{R}^3 \setminus B(0,R)} |\nabla u_{WB}(t,x)|^2 \, dx \lesssim R^{-2+2\delta}.$$ 

Note that this Proposition only gives decay of the energy of $u_{WB}$ away from the origin; we suspect that the mass of $u_{WB}$ also decays away from the origin (which would allow us to upgrade the $o_{H^1}(1)$ error in (13) to the more natural $o_{H^1}(1)$), but we do not know how to do this. This Proposition is significantly weaker than Theorem 1.3 but is also somewhat easier to prove, and the basic strategy used in this argument will be used again when we prove the rest of Theorem 1.3.
Finally, we consider the incoming wave on the ball thanks to (6), (8). Thus it will suffice to show that

$$\int_{\mathbb{R}^3 \setminus B(0,R)} |\nabla u_{\text{wb}}(t_0, x)|^2 \, dx \lesssim R^{-2+2\delta}$$

for all \( t_0 \geq T_0 \). By duality, it suffices to show that

$$|\langle \nabla u_{\text{wb}}(t_0), f \rangle_{L^2(\mathbb{R}^3)}| \lesssim R^{-1+\delta}$$

(63)

for all \( t_0 \geq T_0 \), and all test functions \( f \) supported outside of \( B(0, R) \) with bounded norm in \( L^2(\mathbb{R}^3) \). Since \( u_{\text{wb}} \) is spherically symmetric we may take \( f \) to be also.

Fix \( f, t_0 \). We use Proposition 6.1 to decompose \( f = f_- + f_+ + f_{\text{smooth}} \), and deal with the contribution of each term separately. The term \( f_{\text{smooth}} \) is easy, in fact we just use integration by parts and (7) to bound

$$|\langle \nabla u_{\text{wb}}(t_0), f_{\text{smooth}} \rangle_{L^2(\mathbb{R}^3)}| \lesssim \| \nabla f_{\text{smooth}} \|_{L^2(\mathbb{R}^3)}$$

which is acceptable by (44).

Now we consider the contribution of the outgoing wave \( f_+ \); here the strategy will be to compare \( u \) with the asymptotic solution \( e^{it\Delta}u_\pm \). By (6) it suffices to show that

$$|\langle \nabla u(t_0), f_+ \rangle_{L^2(\mathbb{R}^3)} - \langle \nabla e^{it_0\Delta}u_+, f_+ \rangle_{L^2(\mathbb{R}^3)}| \lesssim R^{-1+\delta}.$$

To prove this we first apply (27) to obtain

$$u(t_0) = e^{i(t_0-T)\Delta}u(T) + i \int_{t_0}^T e^{i(t_0-t)\Delta}F(u(t)) \, dt$$

for any \( T \geq 0 \). Taking inner products with \( f_+ \), we thus obtain

$$\langle \nabla u(t_0), f_+ \rangle_{L^2(\mathbb{R}^3)} = \langle \nabla u(T), e^{i(T-t_0)\Delta}f_+ \rangle_{L^2(\mathbb{R}^3)} + i \int_{t_0}^T \langle F(u(t)), e^{i(t-t_0)\Delta}f_+ \rangle_{L^2(\mathbb{R}^3)} dt.$$ 

As \( T \to +\infty \), we have

$$\lim_{T \to +\infty} \langle \nabla u(T), e^{i(T-t_0)\Delta}f_+ \rangle_{L^2(\mathbb{R}^3)} = \langle \nabla u_+, e^{-it_0\Delta}f_+ \rangle_{L^2(\mathbb{R}^3)} = \langle \nabla e^{it_0\Delta}u_+, f_+ \rangle_{L^2(\mathbb{R}^3)}$$

thanks to (6), (8). Thus it will suffice to show that

$$\int_{t_0}^\infty | \int \langle \nabla F(u(t)), e^{i(t-t_0)\Delta}f_+ \rangle_{L^2(\mathbb{R}^3)} dt | \lesssim R^{-1+\delta}.$$ 

We now observe that

$$\| \langle x \rangle^2 \nabla F(u(t)) \|_{L^1(\mathbb{R}^3)} \lesssim 1;$$

on the ball \( B(0, 1) \) this just comes from (3), (28) and Leibnitz, while outside of this ball this comes from (5) and (3). The claim then follows from Cauchy-Schwarz and (48) (with \( \alpha = 0 \)).

Finally, we consider the incoming wave \( f_- \); which is similar except that we compare \( u \) to the initial data \( e^{it_0\Delta}u_0 \) instead of the asymptotic data. From (45) we have

$$|\langle \nabla e^{it_0\Delta}u_+, f_- \rangle_{L^2(\mathbb{R}^3)}| \lesssim R^{-1+\delta}$$

and

$$|\langle \nabla e^{it_0\Delta}u(0), f_- \rangle_{L^2(\mathbb{R}^3)}| \lesssim R^{-1+\delta}.$$
for all $t_0 \geq T_0$, if $T_0$ is chosen sufficiently large. Thus by (6) it will suffice to show that

$$\left| \langle \nabla u(t_0), f_- \rangle_{L^2(\mathbb{R}^3)} - \langle \nabla e^{it_0 \Delta} u(0), f_- \rangle_{L^2(\mathbb{R}^3)} \right| \lesssim R^{-1+\delta}.$$

Applying (27) we thus reduce to showing that

$$\int_0^t \left| \int \langle \nabla F(u(t)), e^{i(t-t_0)\Delta} f_- \rangle_{L^2} \right| dt \lesssim R^{-1+\delta}.$$

But this follows from (49) (with $\alpha = 0$) by arguing as in the $f_+$ case. This concludes the proof of (63) and hence of the Proposition.

8. IMPROVING THE SMOOTHNESS OF $u_{WB}$

We now use an iteration argument to bootstrap the asymptotic regularity of $u_{WB}$ from $H^1$ to $H^{1+\alpha}$ for arbitrary values of $\alpha$, and also to gain some symbol-type decay estimates on $u_{WB}$ away from the origin. For inductive purposes it is convenient to phrase this regularity in a dual formulation.

Theorem 8.1. Let the notation and assumptions be as in Theorem 1.3, and let $\delta > 0$ and $\alpha \geq 0$ be arbitrary. Then for every $\varepsilon > 0$ there exists a time $T = T(u, \delta, \alpha, \varepsilon) > 0$ such that one has

$$\left| \langle \nabla u_{WB}(t), f \rangle_{L^2} \right| \lesssim \langle R \rangle^{-(1+\alpha)(1-\delta)} \| f \|_{H^{-\alpha}} + \varepsilon \| f \|_{L^2}$$

(64)

for all $t \geq T$, all $R \geq 0$ and all test functions $f$ supported on $\mathbb{R}^3 \setminus B(0, R)$. Here $H^{-\alpha}_{(R)}$ is the scaled Sobolev space defined in the notation section.

At the end of this section we will use this Theorem to construct $u_b$ and thus prove Theorem 1.3.

Proof We fix $\delta > 0$ and induct on $\alpha$ (keeping $\varepsilon, R$ free to vary). It suffices by interpolation to prove the claim when $\alpha$ is a non-negative multiple of $\delta$. When $\alpha = 0$ the claim follows immediately from (7) (just using the first term on the right-hand side of (64). Now suppose inductively that $\alpha \geq \delta$, and the claim (64) has already been proven for $\alpha$ replaced by $\alpha - \delta$, and all $\varepsilon, R$ (assuming $T$ sufficiently large of course). The idea is to use local smoothing and dispersive type estimates and Duhamel’s identity (27) to boost the regularity of $u_{WB}$ by at least $\delta$ of a derivative (the point being that $u_{WB}$ does not contain the linear part of the solution $e^{it\Delta} u_+$ as $t \to +\infty$, which of course has no gain in regularity except in the local sense of Lemma 3.3).

Now fix $\varepsilon$, and let $T > 0$ be a large time (depending on all the above parameters) to be chosen later. We first obtain some bounds on the non-linearity $F(u)$ away from the origin.

Lemma 8.2. Let $R \geq 1$. Then there exists a $T_0 > 0$ such that

$$\left| \langle \nabla ((1 - \eta_{R/8}) F(u(t))), f \rangle_{L^2} \right| \lesssim R^{-1+\alpha}(1-\delta)^2 \| \langle x \rangle^{-2} f \|_{H^{-\alpha+\delta}} + \varepsilon^{100} \| f \|_{L^2}$$

(65)
for all $\varepsilon > 0$, $t \geq T_0$, and all test functions $f$ on $\mathbb{R}^3$.

Proof We first verify this in the case where $f$ vanishes on the ball $B(0, \varepsilon^{-200})$. Then on the support of $f$ we have $u = O(\varepsilon^{100})$ by (5), and hence by (3) we have

$$\| \nabla((1 - \eta_{R/8})F(u(t))) \|_{L^2(\mathbb{R}^3)} \lesssim \varepsilon^{100}$$

and the claim follows. Hence we may assume without loss of generality that $f$ is supported in $B(0, \varepsilon^{-200})$. Indeed by dyadic decomposition it then suffices to show that

$$| \langle \nabla((\eta_{R/4} - \eta_{R/8})F(u(t))), f \rangle_{L^2} \rangle \lesssim R^{-2} R^{-(1+\alpha-\delta)(1-\delta)}\|f\|_{H^{\alpha+\delta}_R} + \varepsilon^{200}\|f\|_{L^2}$$

for all $1 \leq R \lesssim \varepsilon^{-200}$ equal to a power of 2, and all test functions $f$, as the claim then follows by summing using the triangle inequality (and taking $T_0$ to be the supremum of all the individual values of $T_0$ obtained from each of the finite values of $R$).

Fix $R$. By the inductive hypothesis, we can ensure that

$$| \langle \nabla u_{\text{wb}}(t), f \rangle_{L^2} \rangle \lesssim R^{-(1+\alpha-\delta)(1-\delta)}\|f\|_{H^{\alpha+\delta}_R} + \varepsilon^{500}\|f\|_{L^2}$$

for all $t \geq T_0$ and all test functions $f$ on the annulus $B(0, R) \setminus B(0, R/64)$, if $T_0$ is chosen large enough. By duality this implies that

$$(\eta R - \eta R/32) \nabla u_{\text{wb}} = O_{H^R_R}(R^{-(1+\alpha-\delta)(1-\delta)}) + O_{L^2}(\varepsilon^{500})$$

By Lemma 3.3 and (6) we thus have

$$(\eta R - \eta R/32) \nabla u = O_{H^R_R}(R^{-(1+\alpha-\delta)(1-\delta)}) + O_{L^2}(\varepsilon^{500}),$$

if $T_0$ is chosen sufficiently large. By a Poincare inequality argument (adapted to the scale $R$), this implies that

$$(\eta R/2 - \eta R/16)(u - \overline{u}) = O_{H^R_R}(R^{-(1+\alpha-\delta)(1-\delta)}) + O_{H^R_R}(\varepsilon^{500}),$$

where

$$\overline{u} := \frac{\int_{B(0, R/2) \setminus B(0, R/32)} u}{|B(0, R/2) \setminus B(0, R/32)|}$$

is the mean of $u$ on the annulus $B(0, R/2) \setminus B(0, R/32)$. Since $R = O(\varepsilon^{-200})$, we may replace the $O_{H^R_R}(\varepsilon^{500})$ error by $O_{H^1_R}(\varepsilon^{200})$. Since $u$ has bounded mass we see that $\overline{u} = O(R^{-3/2})$, and it is then easy to check that $(\eta R/2 - \eta R/16)\overline{u}$ can be absorbed into the $O_{H^R_R}(R^{-(1+\alpha-\delta)(1-\delta)})$ term. Thus we have

$$(\eta R/2 - \eta R/16)u = O_{H^R_R}(R^{-(1+\alpha-\delta)(1-\delta)}) + O_{H^1_R}(\varepsilon^{200}).$$

The contribution of the $O_{H^1_R}(\varepsilon^{200})$ term to $\nabla((\eta_{R/4} - \eta_{R/8})|u|^2 u)$ can easily be seen to be $O_{L^2}(\varepsilon^{200})$, since $u$ is bounded in this region thanks to (5). Thus by Cauchy-Schwarz the net contribution of this error term is $O(\varepsilon^{200}\|f\|_2)$, which is acceptable, and so we may ignore this error and pretend in fact that

$$\| (\eta R/2 - \eta R/16) u \|_{H^R_R} \lesssim R^{-(1+\alpha-\delta)(1-\delta)}.$$ 

On the other hand, from (5) we also have

$$\| (\eta R/2 - \eta R/16) u \|_{L^\infty} \lesssim R^{-1}.$$
From an application of the fractional Leibnitz rule (see e.g. [13], [25]) we thus have
\[ \| (\eta R/4 - \eta R/8) u^2 \|_{H^{1+\alpha-\delta}_R} \lesssim R^{-2} R^{-(1+\alpha-\delta)(1-\delta)}, \]
and the claim (66) follows by duality. 

We can now verify (64) near the origin. This region has to be treated separately because the radial Sobolev bound (5) is too singular to be useful here, but the basic structure of the argument here will also be used later to prove (64) away from the origin.

**Proposition 8.3.** If \( T \) is sufficiently large, then we have
\[ |\langle \nabla u_{wb}(t), f \rangle_{L^2} | \lesssim \| f \|_{H^{-\alpha}} + \varepsilon \| f \|_{L^2} \]
for all test functions \( f \) supported on \( B(0, 1) \).

**Proof** From the splitting (6) and Duhamel’s formula (27) we have
\[ \langle \nabla u_{wb}(t), f \rangle_{L^2} = \langle \nabla u_{wb}(T'), e^{i(T'-t)\Delta} f \rangle_{L^2} + i \int_t^{T'} \langle \nabla F(u(t')), e^{i(t'-t)\Delta} f \rangle_{L^2} dt'. \]
Letting \( T' \to +\infty \) and using (8), it thus suffices to show that
\[ \int_t^{+\infty} |\langle \nabla F(u(t')), e^{i(t'-t)\Delta} f \rangle_{L^2} | \, dt' \lesssim \| f \|_{H^{-\alpha}} + \varepsilon \| f \|_{L^2}. \]  

Let \( \tau := \varepsilon^{-10} \). We split this integral into the near future \( \int_t^{t+\tau} \) and the distant future \( \int_{t+\tau}^{+\infty} \). To treat the distant future, we observe from (3), Leibnitz, Sobolev and Hölder that
\[ \| \nabla F(u(t')) \|_{L^1(\mathbb{R}^3)} \lesssim 1 \]
and hence by (19) we have
\[ \langle \nabla F(u(t')), e^{i(t'-t)\Delta} f \rangle_{L^2} \lesssim |t' - t|^{-3/2} \| f \|_{L^1} \lesssim |t' - t|^{-3/2} \| f \|_{L^2} \]
by the compact support of \( f \). Thus this contribution is bounded by \( \tau^{-1/2} \| f \|_{L^2} \), which is acceptable by the choice of \( \tau \).

It then remains to control the near future \( \int_t^{t+\tau} \). We split \( F(u) \) into the portion \( \eta_1 F(u) \) near the origin, and the portion \( (1 - \eta_1) F(u) \) away from the origin. Let us first consider the portion away from the origin. By (65) with \( R = 1 \) we can bound this contribution to (67) by
\[ \lesssim \int_t^{t+\tau} \| (\hat{x})^{-2} e^{i(t'-t)\Delta} f \|_{L^2} \| f \|_{H^{-\alpha} + \delta} + \varepsilon^{100} \| e^{i(t'-t)\Delta} f \|_{L^2} \, dt'. \]
The second term here is just \( \varepsilon^{100} \| f \|_{L^2} \) which is acceptable by choice of \( \tau \). The first term can be controlled using (48) as \( O(\| f \|_{H^{-\alpha}}) \) (recall from the proof of Proposition 6.1 that when \( f \) is supported on \( B(0, 1) \) then we can take \( f_+ = f \) which is also acceptable. This concludes the treatment of the portion away from the origin.
It remains to show that
\[ \int_t^{t+\tau} (\|\nabla (\eta_1 F(u(t')))\|_{L^2} + e^{i(t'-t)\Delta} f)\, dt' \lesssim \|f\|_{H^{-\alpha}} + \varepsilon\|f\|_{L^2}. \]
From the inductive hypothesis (64), with \( \alpha \) replaced by \( \alpha - \delta, \varepsilon \) replaced by \( \varepsilon^{100} \), and \( R \) replaced by 1, we have by duality that
\[ \nabla u_{wb}(t) = O_{H^{\alpha-\delta}}(1) + O_{L^2}(\varepsilon^{100}) \]
if \( T \) is large enough. From this and (7) we obtain in particular the local estimate
\[ \eta_2 u_{wb}(t) = O_{H^{1+\alpha-\delta}}(1) + O_{H^1}(\varepsilon^{100}) \]
where \( \eta_2 \) is a spherically symmetric cutoff to \( B(0,1) \) which equals 1 on \( B(0,1/2) \). From (6) and Lemma 3.3 we thus see that
\[ \eta_2 u_{wb}(t) = O_{H^{1+\alpha-\delta}}(1) + O_{H^1}(\varepsilon^{100}) \]
if \( T \) is chosen large enough.

Let us use \( u_{\text{error}} \) to denote the second term \( O_{H^1}(\varepsilon^{100}) \). This error term contributes a number of terms to \( \nabla (\eta_1 F(u)) \), which roughly look like either \( u^2 \nabla u_{\text{error}} \) or \( u \nabla uu_{\text{error}} \) (there is also a term \( |u|^2 u_{\text{error}} \) arising from when the derivative hits the cutoff). In all cases we see from (3) and Sobolev that these expressions are all \( O_{L^{5/2}}(\varepsilon^{100}) \). On the other hand, by (20)
\[ e^{i(t'-t)\Delta} f = O_{L^2} L^6(\|f\|_2). \]
Thus by Hölder the total contribution of the error is at most \( O(\varepsilon^{100} \tau^{1/2}) \), which is acceptable by choice of \( \tau \). Thus we shall ignore the error term and pretend that
\[ \|\eta_2 u(t)\|_{H^{1+\alpha-\delta}} \lesssim 1. \quad (68) \]
Let us now split up the integral \( \int_t^{t+\tau} \) again, into the immediate future \( \int_t^{t+1} \) and the medium-term future \( \int_{t+1}^{t+\tau} \). For the medium-term future we use duality to rewrite this contribution as
\[ \int_{t+1}^{t+\tau} (\|e^{i(t'-t)\Delta} \eta_1 F(u(t'))\|_{L^2} + \|\nabla f\|_{L^2})\, dt'. \]
Because the kernel of \( e^{i(t'-t)\Delta} \) is smooth and decays like \( (t-t')^{-3/2} \), it is easy to verify that
\[ \|\eta_2 e^{i(t'-t)\Delta} \eta_1 g\|_{C^K} \lesssim (t-t')^{-3/2}\|g\|_1 \]
for any \( K > 0 \). In particular we may control this expression in \( H^\alpha \). Since \( ||u||^2 u(t')||_1 \lesssim 1 \) by (28), we thus see that this portion of the integral is bounded by \( ||f||_{H^{-\alpha}} \) as desired.

Finally, we consider the immediate future. For this term we use the well-known Kato local smoothing estimate [38], [48]
\[ \|\eta_2 e^{i(t'-t)\Delta} f\|_{L^2_t H^{\alpha+1/2}([t,t+1] \times \mathbb{R}^3)} \lesssim ||f||_{H^{-\alpha}}(\mathbb{R}^3); \]
this allows us to estimate the contribution of the immediate future by
\[ \lesssim ||\nabla (\eta_1 F(u(t')))||_{L^2_t H^{\alpha-1/2}([t,t+1] \times \mathbb{R}^3)}. \quad (69) \]
We may freely replace \( F(u) \) by \( F(\eta_2 u) \). Heuristically, the fractional Leibnitz rule allows us to write
\[ \nabla^{\alpha-1/2} \nabla (\eta_1 |\eta_2 u|^2 \eta_2 u) \approx \eta_1 (\eta_2 u)^2 \nabla^{\alpha+1/2} (\eta_2 u), \]
which heuristically allows us to estimate (69) by
\[ \|\eta_2 u\|_{L^1_t L^\infty_x([t,t+1]\times\mathbb{R}^3)}^2 \|\eta_2 u\|_{L^2_t H^{\alpha+1/2}_x([t,t+1]\times\mathbb{R}^3)} \]
which is then acceptable by (31) and (68), if \( \delta \) is sufficiently small. This heuristic can then be justified by a rigorous application of the fractional Leibniz rule, for instance by decomposing everything into Littlewood-Paley pieces, or by using the Coifman-Meyer theory of paraproducts; we omit the details. (Note that the presence of the \( L^\infty_x \) norm here is not dangerous, and in any event we have some surplus regularity to waste in the \( H^{\alpha+1/2} \) component if one is concerned about endpoints).

In light of the above proposition, it will suffice to verify (64) for \( R \geq 1 \). Accordingly, let us set \( R \geq 1 \), \( t \geq T \), and let \( f \) be supported on \( \mathbb{R}^3 \setminus B(0, R) \). Observe from Proposition 7.1 that
\[ |\langle \nabla u_{wb}(t), f \rangle_{L^2}| \lesssim R^{-1+\delta} \|f\|_{L^2} \]
and so we may assume
\[ 1 \leq R \lesssim \varepsilon^{1-1/\alpha} \]
(70)
since the claim (64) follows automatically otherwise from the above discussion. Indeed the above argument (combined with a smooth partition of unity) also shows that we may now assume that \( f \) is supported on the annular region \( \{ R \leq |x| \lesssim \varepsilon^{-1/(1-\delta)} \} \), and we will now do so. We also observe that it suffices to verify (64) when \( R \) is either equal to zero or an integer power of two, since the intermediate cases then follow automatically. In particular, by (70) there are only a finite number of values of \( R \) to consider. Thus in order to prove (64) it suffices to do so for a fixed value of \( R \), since one can then let \( T \) be the supremum of all such times \( T \) obtained for individual values of \( R \).

We thus fix \( R, t, f \) and now apply Proposition 6.1 to decompose \( f = f_- + f_+ + f_{\text{smooth}} \). The contribution of \( f_{\text{smooth}} \) can be estimated by (7), (44) as
\[ |\langle \nabla u_{wb}(t), f_{\text{smooth}} \rangle_{L^2}| \lesssim \|\nabla f_{\text{smooth}}\|_{L^2(\mathbb{R}^3)} \lesssim R^{-(1+\alpha)(1-\delta)} \|f\|_{H^{-\alpha}} \]
which is acceptable.

We now consider the contribution of \( f_- \), arguing as in the proof of Proposition 7.1. From (45) we may assume that
\[ |\langle \nabla e^{i u(t) \Delta} u(0), f_- \rangle| \lesssim \varepsilon \|f\|_{L^2(\mathbb{R}^3)} \]
and
\[ |\langle \nabla e^{i u(t) \Delta} u_+, f_- \rangle| \lesssim \varepsilon \|f\|_{L^2(\mathbb{R}^3)} \]
if \( T \) is chosen sufficiently large. Thus by (6) it suffices to show that
\[ |\langle \nabla u(t), f_- \rangle_{L^2} - \langle \nabla e^{i u(t) \Delta} u(0), f_- \rangle_{L^2}| \lesssim R^{-(1+\alpha)(1-\delta)} \|f\|_{H^{-\alpha}} + \varepsilon \|f\|_{L^2}. \]
But by Duhamel’s formula (27) (as in the proof of Proposition 7.1) we may estimate the left-hand side here by
\[ \lesssim \int_0^t |\langle \nabla F(u(t')), e^{i(t'-t) \Delta} f_- \rangle_{L^2}| \ dt'. \]
Let \( \tau := \varepsilon^{-10} \). We shall split this time integral \( \int_0^t \) into the distant past \( \int_0^{t-\tau} \) and the recent past \( \int_{t-\tau}^t \). Note that \( t-\tau \) is positive if \( T \) is chosen sufficiently large depending on \( \varepsilon \). The contribution of the distant past is treated similarly to the corresponding contribution of the distant future in (67); we pick up an additional factor of \( O(\varepsilon^{-3/2(1-\delta)}) \) because \( f \) is now supported on the ball of radius \( O(\varepsilon^{-1/(1-\delta)}) \) instead of \( O(1) \), but this still does not affect the argument significantly because \( \tau \) is so large.

It remains to consider the recent past. We have to show that

\[
\int_{t-\tau}^t |\langle \nabla F(u(t')), e^{i(t'-t)\Delta} f_- \rangle| \ dt' \lesssim R^{-(1+\alpha)(1-\delta)} \| f \|_{H^{-\alpha}} + \varepsilon \| f \|_{L^2}
\]  

(71)

Let \( \eta_{R/8} \) be a smooth cutoff to \( B(0, R/8) \) which equals 1 on \( B(0, R/16) \). We split \( F(u(t')) \) into the part \( \eta_{R/8} F(u(t')) \) near the origin and the part \( (1-\eta_{R/8})F(u(t')) \) away from the origin. Let us first deal with the part near the origin. For this part we use Cauchy-Schwarz, observing from (3) and Sobolev that \( F(u(t')) \) is in \( L^2(\mathbb{R}^3) \), to bound this portion by

\[
\int_{t-\tau}^t \| \nabla e^{i(t'-t)\Delta} f_- \|_{L^2(B(0,R/8))} \ dt'.
\]

But this component is acceptable by the exponential decay bound (47) near the origin (choosing \( \alpha, \beta \) in (47) sufficiently large).

It remains to deal with contribution of \( (1-\eta_{R/8})F(u(t')) \) to (71). By Lemma 8.2 we see that this contribution

\[
\lesssim R^{-(1+\alpha-\delta)(1-\delta)} \int_{t-\tau}^t \| \langle x \rangle^{-2} e^{i(t'-t)\Delta} f_- \|_{H^{-\alpha+\delta}} + \varepsilon^{100} \| e^{i(t'-t)\Delta} f_- \|_{L^2} \ dt'.
\]

The contribution of the \( \varepsilon^{100} \) term is at most

\[
\lesssim \varepsilon^{100} \| f_- \|_{H^{-1}},
\]

which is acceptable by (43) and the definition of \( \tau \). Now consider the main term. Applying (49) we may bound this by

\[
\lesssim R^{-(1+\alpha-\delta)(1-\delta)} R^{-1+\delta} \| f_- \|_{H^{-\alpha}}
\]

which is acceptable. This proves (71) and concludes the treatment of \( f_- \). The treatment of \( f_+ \) is very similar, and involves evolving forward in time instead of backward in time (cf. the proof of Proposition 8.3), and so uses \( u_+ \) instead of \( u(0) \) but is otherwise almost identical. (Note also that the integration parameter \( t' \) is now greater than \( t \) and hence also greater than \( T \), so there is no difficulty ensuring that \( t' \) is large). This proves (64), which closes the induction and completes the proof of the Theorem.

We now wrap up by using (64) to prove Theorem 1.3. We first undo the duality in (64). Let \( \alpha > 0, \delta > 0 \) and \( \varepsilon > 0 \) be chosen later, and suppose that \( t \) is sufficiently large depending on \( \alpha, \delta, \varepsilon \); our implicit constants can depend on \( \alpha, \delta, \varepsilon \).
For the portion of $u_{wb}$ near the origin, we observe from (64) (replacing $\varepsilon$ by $\varepsilon^{100}$) that
\[
|\langle \eta_2 \nabla u_{wb}(t), f \rangle_{L^2} | \lesssim \| f \|_{H^{-\alpha}} + \varepsilon^{100} \| f \|_{L^2}
\]
for all test functions $f$ and for any $\alpha > 0$, $\varepsilon > 0$. By duality, this means that we may decompose
\[
\eta_2 \nabla u_{wb}(t) = O_{H^{\alpha}(\mathbb{R}^3)}(1) + O_{L^2}(\mathbb{R}^3)(\varepsilon^{100}).
\]
On the other hand, from (7) we have that $\eta_2 u_{wb}(t) = O_{H^{1}(\mathbb{R}^3)}(1)$. A Poincare inequality argument (writing $\eta_{1/2} u_{wb}(t)$ as a localized fractional integration operator of $\eta_2 \nabla u_{wb}(t)$ of order -1, plus an infinitely smoothing operator of $\eta_2 u_{wb}(t)$) then easily yields that
\[
\eta_{1/2} u_{wb}(t) = O_{H^{1+1}(\mathbb{R}^3)}(1) + O_{H^{1}(\mathbb{R}^3)}(\varepsilon^{100}).
\]
In particular, we can find a function $u_{b,0}(t)$ for all sufficiently large times $t$ such that
\[
\| \eta_1 u_{wb}(t) - u_{b,0} \|_{H^{1}(\mathbb{R}^3)} \lesssim \varepsilon^{100}
\]
and
\[
\| u_{b,0} \|_{H^{\alpha+1}(\mathbb{R}^3)} \lesssim 1.
\]
By applying $\eta_2$ if necessary we may ensure that $u_{b,0}$ is supported on $B(0, 2)$. From Sobolev embedding we see that
\[
|\nabla^j u_{b,0}(x) | \lesssim 1
\]
for all $0 \leq j < \alpha + 1/2$.

This is enough to construct $u_b$ near the origin. We now start working in dyadic shells outside of the origin. We first observe from Proposition 7.1 that it will suffice to construct $u_b$ on, say, the ball $B(0, \varepsilon^{-10})$, since the energy of $u_{wb}$ outside this ball is asymptotically zero. Accordingly, we let $1/4 \leq R \leq \varepsilon^{-10}$ be a power of 2. From (64) we have that
\[
|\langle (\eta_{32R} - \eta_{2R}) \nabla u_{wb}(t), f \rangle_{L^2} | \lesssim R^{-(1+\alpha)(1-\delta)} \| f \|_{H^{-\alpha}} + \varepsilon^{100} \| f \|_{L^2}
\]
for all test functions $f$, if $t$ is large enough (note that there are only a finite number of $R$ involved, so we can use a single time threshold $t \geq T = T(\varepsilon, u, \alpha, \delta)$ for all of them). By duality again, this implies
\[
(\eta_{32R} - \eta_{2R}) \nabla u_{wb} = O_{H_{R}^{\alpha}}(R^{-(1+\alpha)(1-\delta)}) + O_{L^2}(\varepsilon^{100}).
\]
We now claim that a Poincare inequality argument gives
\[
(\eta_{8R} - \eta_{4R}) u_{wb} = O_{H_{R}^{\alpha+1}}(R^{-(1+\alpha)(1-\delta)}) + O_{H_{b}^{\alpha}}(\varepsilon^{100}).
\]
This time we shall perform this argument in detail, taking note of the scaling factor of $R$. We begin by observing from integration by parts that for any function $f$ on $\mathbb{R}^3$ and any unit vector $\omega$, we have
\[
f(x) = -\int_0^\infty \eta_R(r) \omega \cdot \nabla f(x + r \omega) + \eta_R'(r) f(x + r \omega) \, dr.
\]
Averaging this over all \( \omega \in S^2 \) and then removing the polar co-ordinates, we obtain
\[
f(x) = C \int_{\mathbb{R}^3} \eta(y) \frac{y}{|y|^3} \cdot \nabla f(x+y) + \frac{\eta_R(y)}{|y|^2} f(x+y) \, dy.
\]
Applying this to \( f = u_{\omega b} \) when \( x \) lies in the support of \( \eta_{8R} - \eta_{1R} \), we see in particular that
\[
(\eta_{8R} - \eta_{1R}) u_{\omega b}(x) = C(\eta_{8R}(x) - \eta_{1R}(x)) \int_{\mathbb{R}^3} \eta(y) \frac{y}{|y|^3} \cdot \nabla ((\eta_{32R} - \eta_{2R}) u_{\omega b})(x+y) \, dy
\] + \( C(\eta_{8R}(x) - \eta_{1R}(x)) \int_{\mathbb{R}^3} \eta_R(y)|y|^{-2}((\eta_{32R} - \eta_{2R}) u_{\omega b})(x+y) \, dy. \]

We now substitute (74) into the first term, and (7) into the second term. Observe that convolution with \( \eta_{1R}(y) \) is a smoothing operator which maps \( H^s_R \) to \( H^{s+1}_R \) with constant \( O(1) \) (the factor of \( R \) can be easily scaled out) and \( L^2 \) to \( H^s_R \), again with a bound of \( O(1) \). Meanwhile, convolution with \( \eta_{1R}(y)|y|^{-2} \) is a smoothing operator which maps \( L^2 \) to \( H^{s+1}_R \) with constant \( O(1) \). The claim (75) follows.

From (75) we may find a function \( u_{b,R}(t) \) for each \( 1/4 \leq R \leq \varepsilon^{-10} \) and all sufficiently large times \( t \) such that
\[
\left\| (\eta_{8R} - \eta_{1R}) u_{\omega b} - u_{b,R} \right\|_{H^s(R^3)} \lesssim \varepsilon^{100} \tag{76}
\]
and
\[
\left\| u_{b,R} \right\|_{H^{s+1}_R} \lesssim R^{-(1+\alpha)(1-\delta)}.
\]
By applying \( \eta_{16R} - \eta_{2R} \) to \( u_{b,R} \) if necessary we may assume that \( u_{b,R} \) is supported in the annulus \( B(0,16R) \setminus B(0,R) \). From Sobolev embedding (rescaled by \( R \)) we thus see that
\[
|\nabla^j u_{b,R}(t,x)| \lesssim R^{-\frac{j}{2} - jR^{(1+\alpha)}|\delta|} \tag{77}
\]
for all integers \( 0 \leq j < \alpha + 1/2 \). If we now define\(^{22}\)
\[
u_t := \underbrace{u_{b,0}}_{t=0} + \sum_{1/4 \leq R \leq \varepsilon^{-10}} u_{b,R}
\]
where \( R \) ranges over powers of 2, we thus see by adding up (73), (77) that \( u_t \) obeys the symbol bounds (14), if \( \alpha \) is chosen sufficiently large depending on \( J \), and \( \delta \) chosen sufficiently small depending on \( \alpha \). Furthermore, by telescoping (72) and (76) we see that
\[
\| (\eta_{8R_0} u_{\omega b}(t) - u_t(t) \|_{H^1(R^3)} \lesssim \varepsilon^{100} \log 1/\varepsilon,
\]
where \( R_0 \) is the largest power of two less than or equal to \( \varepsilon^{-10} \). But from Proposition 7.1 and Hardy’s inequality we see that
\[
\left\| (1 - \eta_{R_0}) u_{\omega b}(t) \right\|_{H^1(R^3)} \lesssim \varepsilon
\]
\(^{22}\)Strictly speaking, this only defines \( u_b \) for sufficiently large times. But for bounded times we can set \( u_b \) arbitrarily to (say) 0. In practice we will actually need to take a sequence of values of \( \varepsilon \) tending to zero, with corresponding time thresholds \( T_\varepsilon > 0 \) tending to infinity, and redefine \( u_b \) according to a new value of \( \varepsilon \) every time we cross one of the time thresholds, in order to make the error in (13) \( \sigma_{H^1}(1) \) rather than merely \( O_{H^1}(\varepsilon) \) for any given \( \varepsilon \). We omit the details.
if \( t \) is sufficiently large. Thus we obtain
\[
    u_{wb}(t) = u_b(t) + O_{H^1}(\varepsilon)
\]
which will imply (13) since \( \varepsilon \) can be arbitrarily small (though of course this forces \( t \) to be increasingly large; see previous footnote). Finally, from (76) we see that
\[
    \|(\eta_R - \eta)u_{wb} - u_{b,R}\|_{H^1(\mathbb{R}^3)} \lesssim R\varepsilon^{100}
\]
which telescopes (together with (72)) to obtain that
\[
    \|(\eta_R - \eta)u_{wb} - u_b\|_{H^1(\mathbb{R}^3)} \lesssim R\varepsilon^{100}.
\]
Since \( R_0 \lesssim \varepsilon^{-10} \), the claim (43) then follows from (7). Finally, we can easily ensure that \( u_b \) is spherically symmetric (either by making sure each step of the argument preserves spherical symmetry, or else averaging \( u_b \) over rotations at the end of the argument. This concludes the proof of Theorem 1.3.

\[\blacksquare\]

9. A digression on virial-type identities

Before we begin the proof of Theorem 1.4, we pause to review the derivation of virial identities such as (16). First observe that if \( u \) is any solution to (1), then we have the momentum flux identity
\[
    \partial_t \text{Im}(u_j\overline{u}) = -2\partial_k \text{Re}(\overline{u_j}u_k) + \frac{1}{2} \partial_j \Delta(|u|^2) + \frac{1}{2} \partial_j |u|^4
\]
where \( j, k \) range over 1, 2, 3 with \( u_j := \partial_j u = \partial_x u \) and the usual summation conventions; this can be verified by direct calculation (or see [45]). Integrating this against a suitable gradient \( a_j = \partial_j a \) for some explicit weight \( a(x) \) to be chosen later, we (formally) obtain after some integration by parts
\[
    \partial_t \int a_j \text{Im}(u_j\overline{u}) \, dx = \int -2a_j \partial_k \text{Re}(\overline{u_j}u_k) + \frac{1}{2} a_j \partial_j \Delta(|u|^2) + \frac{1}{2} a_j \partial_j |u|^4 \, dx
\]
\[
    = \int 2a_{jk} \text{Re}(\overline{u_j}u_k) - \frac{1}{2} (\Delta \Delta a) |u|^2 - \frac{1}{2} (\Delta a) |u|^4 \, dx.
\]
Thus for instance if \( a(x) := |x|^2 \), then we obtain Glassey’s virial identity (16). Unfortunately we do not have quite enough decay on \( u_b \) to make the left-hand side of (16) finite, and so we will instead use a slightly different weight \( a \), namely \( a(x) := |x|^2(x)^{-\delta}\eta_R \), where \( \delta > 0 \) is a small exponent and \( R \gg 1 \) is a large radius, and \( \eta_R \) is a cutoff to \( B(0,R) \) which equals 1 on \( B(0,R/2) \). Observe that
\[
    \Delta \Delta a = O(\delta)(x)^{-2-\delta} + O(R^{-2-\delta})
\]
and
\[
    \Delta a = (6 + O(\delta))(x)^{-\delta} + O(R^{-\delta})
\]
on the ball \( B(0,R) \), while
\[
    a_{jk} \text{Re}(\overline{u_j}u_k) = ((1 + O(\delta))(x)^{-\delta} + O(R^{-\delta}))|\nabla u|^2.
\]
We thus have
\[
    \partial_t \int 2a_j \text{Im}(u_j\overline{u}) \, dx = \int_{B(0,R)} 4(x)^{-\delta}|\nabla u|^2 - 3(x)^{-\delta}|u|^4 \, dx + O((\delta+R^{-\delta})\|u\|_{H^1}^2 + \|u\|_{L^4}^4).
\]
We of course can estimate $\|u\|_{L^4}$ by $\|u\|_{H^1}$ by Sobolev embedding. Integrating this in time, and using the fact that $|\nabla a| = O(\langle x \rangle^{1-\delta})$, we obtain

$$\frac{1}{\tau} \int_T^{T+\tau} \int_{B(0,R)} 4\langle x \rangle^{-\delta}|\nabla u|^2 - 3\langle x \rangle^{-\delta}|u|^4 \, dx \, dt \lesssim$$

$$\frac{1}{\tau} \sup_{t=T,T+\tau} \int_{B(0,R)} (\langle x \rangle)^{1-\delta}|u(t)||\nabla u(t)| \, dx + (\delta + R^{-\delta})(\|u\|_{L^\infty([T,T+\tau] \times \mathbb{R}^3)}^4).$$

(79)

This will be our main tool in proving Theorem 1.4, which we do next.

10. PROOF OF THEOREM 1.4

We now prove Theorem 1.4. Let $u$ be as in the theorem, and let $\varepsilon$ be arbitrary. We need to show that for $\tau > 0$ sufficiently large depending on $\varepsilon$, and $T > 0$ sufficiently large depending on $\varepsilon, \tau$, that

$$\frac{1}{\tau} \int_T^{T+\tau} \int_{\mathbb{R}^3} 4|\nabla u_b|^2 - 3|u_b|^4 \, dx \, dt \lesssim \varepsilon.$$  

(80)

Fix $\varepsilon$. We now choose a number of parameters; it will be important to pay attention to the order in which these parameters are selected. For reasons which will be apparent later we will need a large radius $R_0 > 0$ depending on $\varepsilon > 0$ to be chosen later. To apply (79) we shall need a small exponent $\delta > 0$ depending on $\varepsilon$, $R_0$ to be chosen later, as well as an even larger radius $R \gg R_0$ depending on $\delta, \varepsilon, R_0$ to be chosen later, and then we will choose $\tau$ sufficiently large depending on $\varepsilon, \delta, R_0, R$. Finally we let $T$ be a sufficiently large time (depending on $u$ and all previous parameters) again to be chosen later. Let $u_{wb,T}$ be the solution to (1) with initial data $u_{wb,T}(T) = u_{wb}(T)$. Similarly define $u_{b,T}$. We now show that these solutions will approximate the actual functions $u_{wb}, u_b$ on the time interval $[T, T+\tau]$ if $T$ is large enough.

**Lemma 10.1.** If $T$ is sufficiently large (depending on $\tau$), then we have

$$\|u_{wb}(t) - u_{wb,T}(t)\|_{H^1} \lesssim \varepsilon^{10} R^{-10}$$

and

$$\|u_b(t) - u_{b,T}(t)\|_{H^1} \lesssim \varepsilon^{10} R^{-10}$$

(81)

for all $t \in [T, T+\tau]$. In particular, from the $H^1$ local well-posedness theory we see that $u_{b,T}$ and $u_{wb,T}$ are well-defined for all $t \in [T, T+\tau]$ (note that the $L^2$ norm of $u_{b,T}$ stays bounded by mass conservation).

**Proof** Fix $T, \tau$; all spacetime norms will be on the slab $[T, T+\tau] \times \mathbb{R}^3$. We will assume a priori that $u_b$ and $u_{wb}$ exist and are in $H^1$ on the entire time interval $[T, T+\tau]$, this a priori assumption can then be removed by the usual continuity argument, e.g. letting $\tau$ increase continuously from zero.
We begin with $u_{wb}$. Write $v = u_{wb} - u_{wb,T}$; then $v(T) = 0$ and we have the equation
\[ iv_t + \Delta v = F(u_{wb}) - F(u_{wb} - v) + (i\partial_t + \Delta)u_{wb} - F(u_{wb}). \]
However, from (10) we have that
\[ \|(i\partial_t + \Delta)u_{wb} - F(u_{wb})\|_{L_t^1H_x^1} \lesssim \varepsilon', \]
for an $\varepsilon' > 0$ (much smaller than $\varepsilon$) which we will choose later, if $T$ is sufficiently large depending on $\varepsilon'$, $\tau$, $u$. We can thus write the above equation as
\[ iv_t + \Delta v = F(u_{wb}) - F(u_{wb} - v) + O_{L_t^1H_x^1}(\varepsilon'). \]
Let $X$ denote the norm
\[ \|v\|_X := \|v\|_{L_t^\infty H_x^1} + \|v\|_{L_t^4L_x^\infty}. \]
From the Strichartz inequality (24) (and energy estimates and Duhamel’s formula) we have
\[ \|v\|_X \lesssim \|v(T)\|_{H_x^1} + \|F(u_{wb}) - F(u_{wb} - v)\|_{L_t^1H_x^1} + \varepsilon', \]
we will refrain for the moment from using the fact that $v(T) = 0$. However, from Leibnitz and H"older one easily checks that
\[ \|F(u_{wb}) - F(u_{wb} - v)\|_{L_t^2H_x^1} \lesssim \|v\|_X(\|v\|_X + \|u_{wb}\|_X)^2, \]
(basically, one applies the derivative in the $H^1$ norm to the cubic expression $F(u_{wb}) - F(u_{wb} - v)$, and whatever the derivative hits is placed in $L_t^4L_x^2$, and the other two factors in $L_t^4L_x^\infty$). Thus by H"older we have
\[ \|v\|_X \lesssim \|v(T)\|_{H_x^1} + \tau^{1/2}\|v\|_X(\|v\|_X + \|u_{wb}\|_X)^2 + \varepsilon'. \]
Now observe that Lemma 3.2 gives bounds on the $X$ norm of $u$, which are also obeyed by the free solution $e^{it\Delta}u_\perp$. Hence by (6) we have $\|u_{wb}\|_X \lesssim \langle \tau \rangle^{1/4}$, thus
\[ \|v\|_X \lesssim \|v(T)\|_{H_x^1} + \tau^{1/2}\|v\|_X(\|v\|_X + \langle \tau \rangle^{1/4})^2 + \varepsilon'. \]
This estimate does not help us directly when $\tau$ is large. However, if we decompose the interval $[T,T+\tau]$ into $O(\tau)$ intervals $[t_1,t_1+\tau']$ of small length $\tau' \ll 1$, and apply this estimate on each interval, we may show (using continuity arguments in the usual manner) a bound of the form
\[ \|v\|_{X([t_1,t_1+\tau']\times R^d)} \lesssim \|v(t_1)\|_{H^1} + \varepsilon' \]
asuming that $\|v(t_1)\|_{H^1}$ was sufficiently small. In particular we can control the $H^1$ norm of $v(t_1+\tau')$ in terms of that of $v(t_1)$, plus an error of $\varepsilon'$. Iterating this we see that (if $\varepsilon'$ is sufficiently small depending on $\tau'$, $\varepsilon$, $R$) we have
\[ \sup_{t \in [T,T+\tau]} \|v(t)\|_{H^1} \lesssim \varepsilon^{10} R^{-10} \]
as desired.

Now we handle $u_b$. From (13) and the bounds just proven, it will suffice to show that
\[ \sup_{t \in [T,T+\tau]} \|u_{b,T}(t) - u_{wb,T}(t)\|_{H^1} \lesssim \varepsilon^{10} R^{-10} \]
Thus we have \( \| w(T) \|_{H^1} \leq \varepsilon' \)
for any \( \varepsilon' > 0 \) to be chosen later, if \( T \) is sufficiently large depending on \( \varepsilon' \), \( u \). Since \( u_{b,T} \) and \( u_{w,b,T} \) both obey (1), we see that \( w \) obeys the equation
\[
i w_t + \Delta w = F(u_{w,b,T} + w) - F(u_{w,b,T}).
\]
We now perform a homogeneous version of the previous analysis. Let \( \tilde{X} \) denote the norm
\[
\| w \|_{\tilde{X}} := \| w \|_{L^\infty_t H^1_x} + \| w \|_{L^1_t L^\infty_x},
\]
than by Strichartz again (in particular (24)) we have
\[
\| w \|_{\tilde{X}} \lesssim \| w(T) \|_{H^1} + \| F(u_{w,b,T} + w) - F(u_{w,b,T}) \|_{L^1_t H^1_x}.
\]
By Leibnitz and Hölder we have
\[
\| F(u_{w,b,T} + w) - F(u_{w,b,T}) \|_{L^1_t H^1_x} \lesssim \tau^{1/2} \| w \|_{\tilde{X}} \| w \|_{\tilde{X}} (\| u_{w,b,T} \|_{\tilde{X}} + \| w \|_{\tilde{X}})^2.
\]
But from the previous discussion we already have bounds of the form \( \| u_{w,b} \|_{\tilde{X}} \lesssim 1 \)
when \( \tau \) is small enough. Thus if we subdivide \([T, T + \tau] \) into small intervals and choose \( \varepsilon' \) sufficiently small as before, we may obtain
\[
\sup_{t \in [T, T + \tau]} \| w \|_{H^1} \lesssim \varepsilon^{10} R^{-10}
\]
as desired.

We now apply (79) to \( u_{b,T} \) to obtain
\[
\left| \frac{1}{\tau} \int_0^{T + \tau} \int_{B(0,R)} 4 \langle x \rangle^{-\delta} |\nabla u_{b,T}|^2 - 3 \langle x \rangle^{-\delta} |u_{b,T}|^4 \, dx \, dt \right|
\lesssim \frac{1}{\tau} \sup_{t \in [T, T + \tau]} \int_{B(0,R)} \langle x \rangle^{1-\delta} |u_{b,T}(t)| |\nabla u_{b,T}(t)| \, dx
\lesssim (\delta + R^{-\delta})(\| u_{b,T} \|_{L^\infty_t H^1_x([T, T + \tau] \times \mathbb{R}^3)}^4.)
\]
We now estimate the various terms in this expression.

First of all, from (15) we have
\[
\| u_{b,T}(T) \|_{H^1} = \| u_b(T) \|_{H^1} \lesssim 1
\]
and in particular by mass conservation
\[
\| u_{b,T} \|_{L^\infty_t L^2_x([T, T + \tau] \times \mathbb{R}^3)} \lesssim 1.
\]
Also from (81) we have
\[
\| u_{b,T} \|_{L^\infty_t H^1_x([T, T + \tau] \times \mathbb{R}^3)} \lesssim 1.
\]
Thus we have
\[
(\| u_{b,T} \|_{L^\infty_t H^1_x([T, T + \tau] \times \mathbb{R}^3)}^4 \lesssim 1
\]
and thus (if we choose \( \delta \) small enough depending on \( \varepsilon \), and \( R \) large enough depending on \( \delta \))
\[
(\delta + R^{-\delta})(\| u_{b,T} \|_{L^\infty_t H^1_x([T, T + \tau] \times \mathbb{R}^3)}^4 \lesssim \varepsilon.
\]
We now consider the first term in the right-hand side of (82). Crudely bounding \( \langle x \rangle^{1-\delta} \) by \( R \) and using the above \( H^1 \) bounds on \( u_{b,T} \) we see that this term is bounded by \( O(R/\tau) \). Thus if we choose \( \tau \) large enough depending on \( R \) then this term is also \( O(\varepsilon) \). We have thus obtained
\[
\frac{1}{\tau} \int_T^{T+\tau} \int_{B(0,R)} 4\langle x \rangle^{-\delta} |\nabla u_{b,T}|^2 - 3\langle x \rangle^{-\delta} |u_{b,T}|^4 \, dx \, dt \lesssim \varepsilon. \tag{83}
\]
We now divide the spatial region of integration \( B(0,R) \) on the left into the part \( B(0,R_0) \) near the origin, and the part \( B(0,R) \setminus B(0,R_0) \) away from the origin. First consider the part away from the origin. From the bounds in (14) (or from Proposition 7.1), applied for instance with \( \delta = 0.1 \), we have that
\[
\left| \int_{\mathbb{R}^3 \setminus B(0,R_0)} |\nabla u_b|^2 + |u_b|^4 \, dx \right| \lesssim R_0^{-2+0.2} \tag{84}
\]
if \( T \) is sufficiently large. Using (81) and Sobolev and Hölder, we thus have
\[
\left| \int_{B(0,R) \setminus B(0,R_0)} |\nabla u_{b,T}|^2 + |u_{b,T}|^4 \, dx \right| \lesssim R_0^{-2+0.2}
\]
if \( T \) is sufficiently large. In particular, if \( R_0 \) is chosen sufficiently large depending on \( \varepsilon \) we have
\[
\int_{B(0,R) \setminus B(0,R_0)} |\nabla u_{b,T}|^2 + |u_{b,T}|^4 \, dx \lesssim \varepsilon. \tag{85}
\]
On the other hand, inside the ball \( B(0,R_0) \) we have \( \langle x \rangle^{-\delta} = 1 + O(\delta R_0) \) (for instance), and so again by the \( H^1 \) bounds on \( u_{b,T} \) we have
\[
\int_{B(0,R_0)} 4\langle x \rangle^{-\delta} |\nabla u_{b,T}|^2 - 3\langle x \rangle^{-\delta} |u_{b,T}|^4 \, dx = \int_{B(0,R_0)} 4|\nabla u_{b,T}|^2 - 3|u_{b,T}|^4 \, dx + O(\delta R_0).
\]
Again, if we choose \( \delta \) sufficiently small depending on \( R_0 \) then \( O(\delta R_0) \) can be made less than \( \varepsilon \). Combining this with (84), (85) we thus have
\[
\int_{B(0,R)} 4\langle x \rangle^{-\delta} |\nabla u_{b,T}|^2 - 3\langle x \rangle^{-\delta} |u_{b,T}|^4 \, dx = \int_{\mathbb{R}^3} 4|\nabla u_b|^2 - 3|u_b|^4 \, dx + O(\varepsilon).
\]
Combining this with (83) we obtain (80) as desired. \( \blacksquare \)

**Remark.** The above argument can be refined slightly to show that
\[
\lim_{T \to +\infty} \sup_{T-\tau} \left| \int_T^{T+\tau} \int_{\mathbb{R}^3} 4|\nabla u_b|^2 - 3|u_b|^4 \, dx \, dt \right| \lesssim \langle \tau \rangle^{\sigma}
\]
for any \( \sigma > 0 \), with the implicit constant depending on \( \sigma \). This can be done by setting \( R_0, R \) to be large powers of \( \tau \), and \( \delta \) to be a small power of \( \tau \), and using (14) to improve the crude bound of \( O(R/\tau) \) obtained above for the first term of (82) to \( O(R^{0+} / \tau) \). We omit the details.

**Remark.** By choosing different multipliers \( a \) (not just perturbations of \( |x|^2 \)), it is likely one can prove other asymptotic identities of this type. For instance, it seems likely that one has the asymptotic Morawetz identity
\[
\lim_{\tau \to +\infty} \lim_{T \to +\infty} \sup_{T-\tau} \left| \frac{1}{\tau} \int_T^{T+\tau} (4\pi|u_b(t,0)|^2 - \int_{\mathbb{R}^3} \frac{|u_b|^4}{|x|} \, dx) \right| = 0,
\]
which (formally at least) is associated to the multiplier $a = |x|$, although the singularity at 0 has to be treated here with some care. More generally, it seems that the momentum flux (78), when applied to $u_1$, should converge asymptotically to zero in some weak sense when averaged over increasingly large intervals of time. If one could get stronger control on the decay of the momentum flux, e.g., if it converged in a suitably strong sense to zero without any averaging in time, this would be substantial progress towards the soliton resolution conjecture (solutions have zero momentum current, and are probably the only spherically symmetric solutions to (1) with this property). However, to do this it seems one would first have to discover a technique that would eliminate the possibility of breather solutions (smooth localized periodic solutions to (1) which are not of the form $u(t, x) = Q(x)e^{iwt}$).

We do not know of a way to rule out such solutions; the monotonicity formulae arising from virial-type identities do not appear appropriate for this task. Note that the completely integrable 1D equation supports some breather solutions (see [52]), but this may be a phenomenon caused by complete integrability and we do not know if there is a similar phenomenon in higher dimensions, say in the spherically symmetric case.

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