TWO QUADRATURE RULES FOR STOCHASTIC ITÔ-INTEGRALS WITH FRACTIONAL SOBOLEV REGULARITY

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Abstract. In this paper we study the numerical quadrature of a stochastic integral, where the temporal regularity of the integrand is measured in the fractional Sobolev–Slobodeckij norm in $W^{\sigma,p}(0,T)$, $\sigma \in (0,2)$, $p \in [2,\infty)$. We introduce two quadrature rules: The first is best suited for the parameter range $\sigma \in (0,1)$ and consists of a Riemann–Maruyama approximation on a randomly shifted grid. The second quadrature rule considered in this paper applies to the case of a deterministic integrand of fractional Sobolev regularity with $\sigma \in (1,2)$. In both cases the order of convergence is equal to $\sigma$ with respect to the $L^p$-norm. As an application, we consider the stochastic integration of a Poisson process, which has discontinuous sample paths. The theoretical results are accompanied by numerical experiments.

1. Introduction

In this paper we investigate the quadrature of stochastic Itô-integrals. Such quadrature rules are, for instance, important building blocks in numerical algorithms for the approximation of stochastic differential equations (SDEs). For example, let $T \in (0,\infty)$ and $(\Omega,\mathcal{F},(\mathcal{F}_t)_{t \in [0,T]},\mathbb{P})$ be a filtered probability space satisfying the usual conditions. By $W: [0,T] \times \Omega \to \mathbb{R}$ we denote a standard $(\mathcal{F}_t)_{t \in [0,T]}$-Wiener process. Then, for a given continuous coefficient function $\lambda: [0,T] \to \mathbb{R}$ and a stochastically integrable process $G: [0,T] \times \Omega \to \mathbb{R}$ the numerical solution of the initial value problem

\[
\begin{cases}
    dX(t) = \lambda(t)X(t) \, dt + G(t) \, dW(t), & t \in [0,T], \\
    X(0) = 0,
\end{cases}
\]

can be reduced to the quadrature of the Itô-integral

\[
X(t) = \int_0^t \exp \left( \int_s^t \lambda(u) \, du \right) G(s) \, dW(s), \quad t \in [0,T],
\]

by the variation of constants formula. We refer to [10, Section 4.4] for further examples of SDEs which can be reduced to quadrature problems.

In the standard literature, as for example in [2, 7, 13, 14, 15, 17], the regularity of the integrand is often measured in terms of Hölder norms. However, in many cases the order of convergence observed in numerical experiments is larger than the theoretical order derived from the Hölder regularity. The starting point of this paper is the observation that the gap between the theoretical and the experimental order of convergence can often be closed if the regularity of the integrand is measured in terms of fractional Sobolev spaces.

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We then introduce two quadrature formulas: The first is a Riemann–Maruyama quadrature rule but with a randomly shifted mesh. The second is a stochastic version of the trapezoidal rule and is applicable to Itô-integrals with deterministic integrands possessing a higher order Sobolev regularity. As our main result we obtain error estimates with positive convergence rates even in the case of possibly discontinuous integrands.

To give a more precise outline of this paper, let \( G : [0, T] \times \Omega \to \mathbb{R} \) be a stochastically integrable process as above. We want to find a numerical approximation of the definite stochastic Itô-integral

\[
I[G] = \int_0^T G(s) \, dW(s).
\]

If \( G \in C^\gamma([0, T]; L^p(\Omega)), \gamma \in (0, 1), p \in [2, \infty), \) then one often applies the classical Riemann–Maruyama-type quadrature formula

\[
Q_{RM}^N[G] = \sum_{j=1}^N G(t_{j-1}) (W(t_j) - W(t_{j-1}))
\]

for the approximation of the stochastic integral \( I[G] \), where \( N \in \mathbb{N} \) determines the equidistant step size \( h = \frac{T}{N} \) and an equidistant partition of \([0, T] \) of the form

\[
\pi_h = \{ t_j := jh : j = 0, 1, \ldots, N \} \subset [0, T].
\]

Then, standard results in the literature, see for instance [2, 15, 17], show that

\[
\left\| I[G] - Q_{RM}^N[G] \right\|_{L^p(\Omega)} \leq C \| G \|_{C^\gamma([0, T]; L^p(\Omega))} h^\gamma
\]

for all \( N \in \mathbb{N} \), where the constant \( C \) is independent of \( N \) and \( h \).

In this paper, we first focus on the case that the integrand \( G : [0, T] \times \Omega \to \mathbb{R} \) is of lower temporal regularity. To be more precise, we assume that \( G \in L^p(\Omega; W^{\sigma,p}(0, T)) \) with \( \sigma \in (0, 1) \) and \( p \in [2, \infty) \). See Equation (9) below for the definition of the Sobolev–Slobodeckij norm. We emphasize that the space \( W^{\sigma,p}(0, T) \) contains possibly discontinuous trajectories if \( \sigma p < 1 \). In particular, several of the singular functions studied in [14] are included in the fractional Sobolev spaces in a natural way.

In this situation we introduce a randomly shifted version of the Riemann–Maruyama quadrature rule (2) for the approximation of (1). To this end, let \( N \in \mathbb{N} \) and set \( h = \frac{T}{N} \) as above. We will, however, not make use of the equidistant partition (3). Instead we introduce an additional uniformly distributed random variable \( \xi : \Omega \to [0, 1] \), that is assumed to be independent of the stochastic processes \( G \) and \( W \) in (1). The value of \( \xi \) then determines a randomly shifted equidistant partition \( \pi_h(\xi) \) of \([0, T] \) defined by

\[
\pi_h(\xi) = \{ 0 \} \cup \{ \xi_j := (j - 1 + \xi)h : j = 1, \ldots, N \} \cup \{ T \} \subset [0, T],
\]

where we also write \( \xi_0 := 0 \) and \( \xi_{N+1} := T \). Note that \( \pi_h(\xi) \) is strictly speaking not equidistant due to the addition of the initial and final time point. However, it holds true that

\[
|\xi_j - \xi_{j-1}| \leq h
\]
for all \( j \in \{1, \ldots, N + 1\} \), where we have equality in (6) for all \( j \in \{2, \ldots, N\} \). The randomly shifted Riemann–Maruyama quadrature rule is then given by

\[
Q_{N}^{\text{SRM}}[G, \xi] = \sum_{j=1}^{N} G(\xi_j)(W(\xi_{j+1}) - W(\xi_j)).
\]

In Section 3 we will show that \( Q_{N}^{\text{SRM}} \) is well-defined for all progressively measurable \( G \in L^p(\Omega; W^{\sigma,p}(0, T)) \). If \( G \) satisfies an additional integrability condition at \( t = 0 \) we have

\[
\|I[G] - Q_{N}^{\text{SRM}}[G, \xi]\|_{L^p(\Omega)} \leq C(1 + \|G\|_{L^p(\Omega; W^{\sigma,p}(0, T))})h^\sigma,
\]

where \( C \in (0, \infty) \) is a suitable constant independent of \( N \) and \( h \). For a precise statement of our conditions on \( G \) we refer to Assumption 3.1 below.

We remark that quadrature formulas for stochastic integrals on random time grids are already studied in the literature. In contrast to our observation, however, it usually turns out that the additional randomization does not yield any advantage over algorithms with deterministic grid points if the regularity of the integrand is measured in terms of the Hölder norm. See, for instance, [2]. We also refer to [5] for a related observation in mathematical finance.

In Section 4 we then discuss the case of deterministic integrands \( g: [0, T] \to \mathbb{R} \) with regularity \( g \in W^{1+\sigma,p}(0, T) \), \( \sigma \in (0, 1) \), \( p \in [2, \infty) \). Under this additional regularity assumption we obtain a higher order error estimate for a stochastic version of the well-known trapezoidal quadrature rule given by

\[
Q_{N}^{\text{Trap}}[g] = \sum_{j=1}^{N} \frac{1}{2} (g(t_{j-1}) + g(t_j))(W(t_j) - W(t_{j-1}))
\]

\[
+ \sum_{j=1}^{N} \frac{1}{h} (g(t_j) - g(t_{j-1})) \int_{t_{j-1}}^{t_j} (t - t_j)^{-\frac{1}{2}} dW(t),
\]

where \( t_j = t_{j-1} + \frac{1}{2} (t_{j-1} + t_j) \). Observe that in the deterministic case \( dW(t) = dt \) the second sum would disappear and we indeed recover the trapezoidal rule. In Section 4 we also show that the implementation of (8) is straight-forward.

The remainder of this paper is organized as follows: In Section 2 we recall the definition of the fractional Sobolev spaces \( W^{\sigma,p}(0, T) \) and the associated Sobolev–Slobodeckij norm. In addition, we fix some notation and collect a few martingale inequalities. Section 3 and Section 4 then contain the error analysis of the quadrature rules (7) and (8), respectively. In Section 5 we then present several numerical experiments for the case of deterministic integrands with various degrees of smoothness. In Section 6 we finally show that a Poisson process satisfies the conditions imposed on the randomly shifted Riemann–Maruyama rule.

2. Preliminaries

First let us recall the definition of fractional Sobolev spaces which are used in order to determine the temporal regularity of the integrand. For \( T \in (0, \infty) \), \( p \in [1, \infty) \) and \( \sigma \in (0, 1) \) the Sobolev–Slobodeckij norm of an integrable mapping \( v: [0, T] \to \mathbb{R} \) is given by

\[
\|v\|_{W^{\sigma,p}(0,T)} = \left( \int_0^T |v(t)|^p \ dt + \int_0^T \int_0^T \frac{|v(t) - v(s)|^p}{|t-s|^{1+\sigma p}} \ dt \ ds \right)^{\frac{1}{p}}.
\]
We denote by $W^\sigma_p(0, T) \subset L^p(0, T)$ the subspace of all $L^p$-integrable mappings $v : [0, T] \to \mathbb{R}$ such that $\|v\|_{W^\sigma_p(0, T)} < \infty$. The space $W^\sigma_p(0, T)$ is called fractional Sobolev space. It holds true that $W^1_p(0, T) \subset W^\sigma_p(0, T) \subset L^p(0, T)$ for all $\sigma \in (0, 1)$. For further details on fractional Sobolev spaces we refer the reader, for example, to [3, Chapter 4] or to the survey papers [4] and [16].

For the error analysis it is convenient to assume that the probability space $(\Omega, \mathcal{F}, \mathbb{P})$ is of product form, that is

\begin{equation}
(\Omega, \mathcal{F}, \mathbb{P}) := (\Omega_\xi \times \Omega, \mathcal{F}^\xi \otimes \mathcal{F}, \mathbb{P}_W \otimes \mathbb{P}_\xi),
\end{equation}

such that $(\Omega_\xi, \mathcal{F}^\xi, (\mathcal{F}^\xi_t)_{t \in [0, T]}, \mathbb{P}_\xi)$ is the stochastic basis of the Wiener process $W$ and the integrand $G$ in (1), while the family of random temporal grid points $\pi_n^{\xi}$ determined by the random variable $\xi$ is defined on $(\Omega_\xi, \mathcal{F}^\xi, \mathbb{P}_\xi)$. In the following we denote by $\mathbb{E}_W[\cdot]$ and $\mathbb{E}_\xi[\cdot]$ the expectation with respect to the measures $\mathbb{P}_W$ and $\mathbb{P}_\xi$, respectively.

For the error analysis with respect to the $L^p(\Omega)$-norm, $p \in [2, \infty)$, we also require the following higher moment estimate of stochastic integrals. For a proof we refer to [11, Chapter 1, Theorem 7.1].

**Theorem 2.1.** Let $p \in [2, \infty)$ and $G \in L^p(\Omega_W; L^p(0, T))$ be stochastically integrable. Then, it holds true that

\[
\mathbb{E}_W \left[ \left| \int_0^T G(t) \, dW(t) \right|^p \right] \leq \left( \frac{p(p-1)}{2} \right)^{\frac{p}{2}} T^{\frac{p-2}{2}} \mathbb{E}_W \left[ \int_0^T |G(t)|^p \, dt \right].
\]

The error analysis also relies on a discrete time version of the Burkholder–Davis–Gundy inequality. A proof is found in [1].

**Theorem 2.2.** For each $p \in (1, \infty)$ there exist positive constants $c_p$ and $C_p$ such that for every discrete time martingale $(X_n)_{n \in \mathbb{N}}$ and for every $n \in \mathbb{N}$ we have

\[
c_p \left\| [X]^*_n \right\|_{L^p(\Omega, \mathbb{R}^d)} \leq \left\| \max_{i \in \{1, \ldots, n\}} |X_i| \right\|_{L^p(\Omega, \mathbb{R}^d)} \leq C_p \left\| [X]^*_n \right\|_{L^p(\Omega, \mathbb{R}^d)}
\]

where $[X]^*_n = |X_1|^2 + \sum_{i=1}^{n-1} |X_{i+1} - X_i|^2$ denotes the quadratic variation of $(X_n)_{n \in \mathbb{N}}$ up to $n$.

3. ERROR ANALYSIS OF THE LOWER ORDER QUADRATURE RULE

In this section we present the error analysis of the randomly shifted Riemann–Maruyama quadrature rule defined in (7). First, we state the assumptions on the integrand in the stochastic integral (1).

**Assumption 3.1.** The mapping $G : [0, T] \times \Omega_W \to \mathbb{R}$ is a progressively measurable, $(\mathcal{F}^W_t)_{t \in [0, T]}$-adapted stochastic process such that there exist $p \in [2, \infty)$ and $\sigma \in (0, 1)$ with

\[
G \in L^p(\Omega_W; W^\sigma_p(0, T)).
\]

In addition, there exist $C_0 \in (0, \infty)$ and $h_0 \in (0, T]$ with

\begin{equation}
\left( \int_0^{h_0} t^{-\max(0, \sigma - \frac{p-2}{2})} \mathbb{E}_W \left[ |G(t)|^p \right] \, dt \right)^{\frac{1}{p}} \leq C_0.
\end{equation}

Under Assumption 3.1 the stochastic process $G$ is stochastically integrable and the Itô-integral (1) is well-defined. For more details on stochastic integration we refer the reader, for instance, to [8, Chapter 17] or [9, Chapter 25]. Moreover,
we show that a Poisson process satisfies all conditions of Assumption 3.1 for all \( p \in [2, \infty) \) and \( \sigma \in (0, 1) \) with \( \sigma p < 1 \).

**Remark 3.2.** The condition (11) ensures that the \( L^p(\Omega_W) \)-norm of the process \( G \) is not too explosive at \( t = 0 \). In Section 5 we will show that Assumption 3.1 includes weak singularities of the form \([0, T] \ni t \mapsto t^{-\gamma} \) for \( \gamma \in (0, \frac{1}{2}) \). On the other hand, if the integrand enjoys more regularity at \( t = 0 \) but is nonzero, then one might apply the quadrature rule (7) to the integrand \( \tilde{G}(t) := G(t) - G(0) \).

**Remark 3.3.** The randomly shifted quadrature rule \( Q_{SRM}^N[G, \xi] \) only evaluates \( G \) on the randomized time points in \( \pi_\delta(\xi) \) determined by \( \xi \sim U(0, 1) \). Because of this, the quadrature rule is independent of the choice of the representation of the equivalence class \( G \in L^p(\Omega; W^{\sigma, p}(0, T)) \) in the following sense: For all \( \omega \in \Omega_W \) with \( G(\cdot, \omega) \in W^{\sigma, p}(0, T) \) let \( G_1(\cdot, \omega) \), \( i \in \{1, 2\} \), be two representations of the same equivalence class in \( W^{\sigma, p}(0, T) \). Then it follows from

\[
G_1(t, \omega) = G_2(t, \omega)
\]

for almost all \( t \in [0, T] \) that

\[
G_1(\xi_j, \omega) = G_2(\xi_j, \omega) \quad \mathbb{P}_\xi\text{-almost surely in } \Omega\xi
\]

for every \( j \in \{1, \ldots, N\} \), and hence \( G_1(\xi_j) = G_2(\xi_j) \mathbb{P}\text{-almost surely on } \Omega = \Omega_W \otimes \Omega_\xi \).

We now state and prove the error estimate of the randomly shifted Riemann–Maruyama quadrature rule defined in (7).

**Theorem 3.4.** Let Assumption 3.1 be satisfied with \( p \in [2, \infty) \), \( \sigma \in (0, 1) \), \( C_0 \in (0, \infty) \), and \( h_0 \in (0, T) \). Then, there exists \( C(p) \in (0, \infty) \) depending only on \( p \in [2, \infty) \) with

\[
\|I[G] - Q_{SRM}^N[G, \xi]\|_{L^p(\Omega)} \leq C(p)\left(C_0 h_0^{\max(0, \frac{\sigma}{2} - \sigma)} + T^{\frac{p-2}{p}} \|G\|_{L^p(\Omega; W^{\sigma, p}(0, T))}\right)h^\sigma
\]

for all \( N \in \mathbb{N} \) with \( \frac{T}{N} = h \leq h_0 \).

**Proof.** For the proof we first recall from (6) that for all \( j \in \{0, 1, \ldots, N\} \) we have

\[
|\xi_{j+1} - \xi_j| \leq h
\]

by definition of \( (\xi_j)_{j \in \{0, \ldots, N+1\}} \). Moreover, each random grid point \( \xi_j = (j - 1 + \xi)h \) is uniformly distributed in \([t_{j-1}, t_j]\) for all \( j \in \{1, \ldots, N\} \).

In the following proof, we abbreviate the time discrete error term by

\[
E_n = \int_0^{\xi_n} G(t) \, dW(t) - \sum_{j=1}^{n-1} G(\xi_j) (W(\xi_{j+1}) - W(\xi_j))
\]

\[
= \int_0^{\xi_1} G(t) \, dW(t) + \sum_{j=1}^{n-1} \int_{\xi_j}^{\xi_{j+1}} (G(t) - G(\xi_j)) \, dW(t)
\]

for \( n \in \{1, \ldots, N + 1\} \). Then, we can write the error of the quadrature rule (7) as

\[
\|I[G] - Q_{SRM}^N[G, \xi]\|_{L^p(\Omega)} = \mathbb{E}_\xi[\mathbb{E}_W[|E_n|^{p}]].
\]

Furthermore, it follows from Assumption 3.1 and Theorem 2.1 that \( E_n : \Omega \to \mathbb{R} \) is an element of \( L^p(\Omega) \) for every \( n \in \{1, \ldots, N + 1\} \). Consequently, there exists a null set \( \mathcal{N} \subset \Omega_\xi \) such that for every fixed \( \omega_\xi \in \Omega_\xi \setminus \mathcal{N} \) the random variables \( E_n(\omega_\xi) \),
n ∈ {1, . . . , N + 1}, are elements of \( L^p(\Omega_W) \). In addition, \( E^n(\omega_\xi) \) is measurable with respect to the \( \sigma \)-algebra \( \mathcal{F}_{\xi_n(\omega_\xi)}^W \). Since we obtain for all \( 1 \leq m \leq n \leq N + 1 \) that

\[
\mathbb{E}_W \left[ E^n(\omega_\xi) \bigg| \mathcal{F}_{\xi_m(\omega_\xi)}^W \right]
= \mathbb{E}_W \left[ \int_0^{\xi_1(\omega_\xi)} G(t) \, dW(t) + \sum_{j=1}^{n-1} \int_{\xi_j(\omega_\xi)}^{\xi_{j+1}(\omega_\xi)} (G(t) - G(\xi_j(\omega_\xi))) \, dW(t) \bigg| \mathcal{F}_{\xi_m(\omega_\xi)}^W \right]
= \int_0^{\xi_1(\omega_\xi)} G(t) \, dW(t) + \sum_{j=1}^{m-1} \int_{\xi_j(\omega_\xi)}^{\xi_{j+1}(\omega_\xi)} (G(t) - G(\xi_j(\omega_\xi))) \, dW(t)
+ \mathbb{E}_W \left[ \sum_{j=m}^{n-1} \int_{\xi_j(\omega_\xi)}^{\xi_{j+1}(\omega_\xi)} (G(t) - G(\xi_j(\omega_\xi))) \, dW(t) \bigg| \mathcal{F}_{\xi_m(\omega_\xi)}^W \right]
= E^n(\omega_\xi),
\]

the process \( (E^n(\omega_\xi))_{n \in \{1, \ldots, N + 1\}} \) is a discrete time martingale with respect to the filtration \( (\mathcal{F}_{\xi_n(\omega_\xi)}^W)_{n \in \{1, \ldots, N + 1\}} \). From an application of the Burkholder–Davis–Gundy inequality from Theorem 2.2 and the triangle inequality we obtain for \( \omega_\xi \in \Omega_\xi \setminus \mathcal{N} \)

\[
\left( \mathbb{E}_W \left[ \left| E^{N+1}(\omega_\xi) \right|^p \right] \right)^{\frac{1}{p}}
\leq C_p \left( \mathbb{E}_W \left[ \left( \left| E^1(\omega_\xi) \right|^2 + \sum_{i=1}^N \left| E^{i+1}(\omega_\xi) - E^i(\omega_\xi) \right|^2 \right)^{\frac{p}{2}} \right] \right)^{\frac{1}{p}}
\leq C_p \left( \left\| E^1(\omega_\xi) \right\|_{L^p(\Omega_W)}^2 + \sum_{i=1}^N \left\| E^{i+1}(\omega_\xi) - E^i(\omega_\xi) \right\|_{L^p(\Omega_W)}^2 \right)^{\frac{1}{2}}
\leq C_p \left( \left\| E^1(\omega_\xi) \right\|_{L^p(\Omega_W)} + \sum_{i=1}^N \left\| E^{i+1}(\omega_\xi) - E^i(\omega_\xi) \right\|_{L^p(\Omega_W)} \right)^{\frac{1}{2}}
\leq C_p (X_1 + X_2),
\]

where we will consider \( X_1 \) and \( X_2 \) separately in the following. By making use of Theorem 2.1 we obtain the estimate for \( X_1 \)

\[
X_1^p = \left\| \int_0^{\xi_1(\omega_\xi)} G(t) \, dW(t) \right\|_{L^p(\Omega_W)}^p \leq \left( \frac{p(p-1)}{2} \right)^{\frac{p}{2}} h^{\frac{p-2}{2}} \int_0^{\xi_1(\omega_\xi)} \mathbb{E}_W \left[ |G(t)|^p \right] \, dt,
\]

since \( \xi_1(\omega_\xi) \leq h \). To estimate \( X_2 \) we again apply Theorem 2.1 and obtain that

\[
X_2^2 = \sum_{i=1}^N \left\| E^{i+1}(\omega_\xi) - E^i(\omega_\xi) \right\|_{L^p(\Omega_W)}^2
\leq \left( \frac{p(p-1)}{2} \right)^{\frac{p}{2}} \sum_{i=1}^N \int_{\xi_i(\omega_\xi)}^{\xi_{i+1}(\omega_\xi)} \mathbb{E}_W \left[ |G(t) - G(\xi_i(\omega_\xi))|^p \right] \, dt \right)^{\frac{2}{p}}.
\]
Altogether, this yields
\[
\left( E_W \left[ \left| E^{N+1} (\omega_\xi) \right|^p \right] \right)^{\frac{1}{p}} \\
\leq C(p) h^{\frac{p-2}{2p}} \left( \int_0^{\xi} E_W \left[ |G(t)|^p \right] dt \right)^{\frac{1}{p}} \\
+ C(p) h^{\frac{p-2}{2p}} \left( \sum_{i=1}^N \left( \int_{\xi_i}^{\xi_{i+1}} E_W \left[ |G(t) - G(\xi_i)|^p \right] dt \right)^{\frac{1}{p}} \right)^{\frac{1}{p}}
\]
for all \( \omega_\xi \in \Omega \setminus \mathcal{N} \), where \( C(p) = C_\mu \left( \frac{h}{2} \right)^{\frac{1}{p}} \). Hence, after applying the norm \((E_\xi([\cdot]^p])^\frac{1}{p}\) we arrive at
\[
\| E^{N+1} \|_{L^p(\Omega)} = \left( E_\xi \left[ \left( E_W \left[ |E^{N+1}|^p \right] \right)^{\frac{1}{p}} \right] \right)^{\frac{1}{p}} \\
\leq C(p) h^{\frac{p-2}{2p}} \left( E_\xi \left[ \left( \int_0^{\xi} E_W \left[ |G(t)|^p \right] dt \right)^{\frac{1}{p}} \right] \right)^{\frac{1}{p}} \\
+ \left( E_\xi \left[ \left( \sum_{i=1}^N \left( \int_{\xi_i}^{\xi_{i+1}} E_W \left[ |G(t) - G(\xi_i)|^p \right] dt \right)^{\frac{1}{p}} \right)^{\frac{1}{p}} \right] \right)^{\frac{1}{p}}.
\]
Due to \( h \leq h_0 \) we have by condition (11) for the first term that
\[
E_\xi \left[ \int_0^{\xi} E_W \left[ |G(t)|^p \right] dt \right] = \frac{1}{h} \int_0^{h} \int_0^{\tau} E_W \left[ |G(t)|^p \right] dt \, d\tau \\
\leq \int_0^{h} E_W \left[ |G(t)|^p \right] dt \\
\leq \int_0^{h} t^{p(0, p) - \frac{2}{2p}} E \left[ |G(t)|^p \right] dt h^{p(0, p) - \frac{2}{2p}} \\
\leq C(p) h^{p(0, p) - \frac{2}{2p}}.
\]
Since \( |t - \xi| \leq |\xi_{i+1} - \xi_i| \leq h \) is fulfilled in the second summand on the right hand side of (12) we further estimate the second sum by
\[
E_\xi \left[ \left( \sum_{i=1}^N \left( \int_{\xi_i}^{\xi_{i+1}} E_W \left[ |G(t) - G(\xi_i)|^p \right] dt \right)^{\frac{1}{p}} \right)^{\frac{1}{p}} \right] \\
\leq N h^{\frac{p-2}{2p}} \sum_{i=1}^N E_\xi \left[ \left( \int_{\xi_i}^{\xi_{i+1}} E_W \left[ |G(t) - G(\xi_i)|^p \right] dt \right)^{\frac{1}{p}} \right] \\
\leq N h^{\frac{p-2}{2p}} h^{1+\sigma p} \sum_{i=1}^N E_\xi \left[ \left( \int_{\xi_i}^{\xi_{i+1}} E_W \left[ \frac{|G(t) - G(\xi_i)|}{|t - \xi_i|^{1+\sigma p}} \right]^p dt \right)^{\frac{1}{p}} \right] \\
\leq N h^{\frac{p-2}{2p}} h^{1+\sigma p} \sum_{i=1}^N E_\xi \left[ E_W \left[ \frac{|G(t) - G(\xi_i)|}{|t - \xi_i|^{1+\sigma p}} \right]^p \right] dt \\
= N h^{\frac{p-2}{2p}} h^{1+\sigma p} \sum_{i=1}^N E_\xi \left[ \int_0^{T} \int_{\xi_i}^{\xi_{i+1}} E_W \left[ \frac{|G(t) - G(s)|}{|t - s|^{1+\sigma p}} \right] ds \, dt \right] \\
= N h^{\frac{p-2}{2p}} h^{1+\sigma p} \| G \|_{L^p(\Omega; \mathcal{W}^{0,p}(0, T))}^p,
\]
where we made use of the fact that \( \xi_i \sim \mathcal{U}(t_{i-1}, t_i) \) in the second last step. The assertion then follows at once after inserting the last two estimates into (12) and by noting that \( N h^{\frac{p-2}{2p}} = T^{\frac{p-2}{2p}} \) and \( \max(0, \sigma - \frac{p-2}{2p}) + \frac{p-2}{2p} = \max(\frac{p^2}{4p}, \sigma) \geq \sigma \). \( \square \)
Remark 3.5. Let us briefly compare the error estimate of Theorem 3.4 to the standard case with Hölder regularity, where it is assumed that \( G \in C^\gamma([0,T]; L^p(\Omega_W)) \), \( \gamma \in (0,1) \). In this case the random shift of the mesh \( \pi_h \) is not required and it is well-known that the standard Riemann–Maruyama quadrature rule (2) converges with order \( \gamma \).

Due to the embedding \( C^\gamma([0,T]; L^p(\Omega_W)) \subset L^p(\Omega_W; W^{\sigma,p}(0,T)) \) for all \( \sigma \in (0, \gamma) \) the error estimate in Theorem 3.4 guarantees that \( \gamma \) is essentially also a lower bound for the order of convergence of the quadrature rule (7). However, as we will also see in Section 5, one readily finds integrands \( G \in C^\gamma([0,T]; L^p(\Omega_W)) \cap L^p(\Omega_W; W^{\sigma,p}(0,T)) \) with \( \sigma > \gamma \). For example, the process \( G(t) := t^\sigma + W(t), \ t \in [0,T], \) is an element of \( C^\gamma([0,T]; L^2(\Omega_W)) \) with \( \gamma = \frac{1}{2} \). However, it is simple to verify that we also have \( G \in L^2(\Omega_W; W^{\sigma,2}(0,T)) \) for every \( \sigma \in (0, \frac{1}{2}) \).

4. Higher order quadrature rule

In this section we present the details on the stochastic version (8) of the trapezoidal rule. First we state the conditions for our error analysis.

Assumption 4.1. There exist \( p \in [2, \infty) \) and \( \sigma \in (0,1) \) such that the mapping \( g: [0,T] \to \mathbb{R} \) is an element of \( W^{1+\sigma,p}(0,T) \).

Throughout this section we investigate a slightly more general version of the quadrature rule (8). To this end, we introduce a parameter value \( \xi \in [0,1] \). Note that in contrast to the Riemann–Maruyama quadrature rule it does not yield any advantage to randomize \( \xi \). For each value of \( \xi \) we then define the two points

\[
\xi_j = t_{j-1} + \xi h, \quad \hat{\xi}_j = t_{j-1} + (1-\xi)h, \quad j \in \{1, \ldots, N\},
\]

where as before \( h = \frac{T}{N}, \ N \in \mathbb{N}, \) and \( t_j = jh, \ j \in \{0, \ldots, N\}. \) Also we denote the midpoint between two grid points \( t_{j-1} \) and \( t_j \) by \( t_{j-\frac{1}{2}} \), that is,

\[
t_{j-\frac{1}{2}} = \frac{t_{j-1} + t_j}{2}, \quad j \in \{1, \ldots, N\}.
\]

Then, the quadrature rule studied in this section is given by

\[
Q_N^{\text{Trap}}[g] = \sum_{j=1}^{N} \frac{1}{2} (g(\xi_j) + g(\hat{\xi}_j))(W(t_j) - W(t_{j-1})) + \sum_{j=1}^{N} \frac{1}{h} (g(t_j) - g(t_{j-1})) \int_{t_{j-1}}^{t_j} (t - t_{j-\frac{1}{2}}) dW(t).
\]

(13)

First, we observe that the parameter value \( \xi = 0 \) yields the stochastic trapezoidal rule (8). This choice of \( \xi \) also admits the practical advantage that it only requires \( N + 1 \) function evaluations of the integrand \( g \), since then \( \xi_j = t_{j-1} \) and \( \hat{\xi}_j = t_j \). Moreover, Assumption 4.1 and the Sobolev embedding theorem ensure that there exists a continuous representative of the integrand, more precisely \( g \in C^{\frac{1}{2}}([0,T]) \).

Hence, the point evaluation of \( g \) on the deterministic grid points in (13) is well-defined.

Before we come to the error analysis, let us mention that the quadrature rule (13) can also be seen as a derivative-free version of the Wagner–Platen scheme, see [10]. This has been studied in [13] under classical smoothness assumptions, that is, \( g \in C^1([0,T]) \) with a globally Lipschitz continuous derivative.
Remark 4.2. Note that for the implementation of the quadrature rule (13) we have to simulate the stochastic integral
\[ \int_{t_{j-1}}^{t_j} (t - t_j^{-\frac{1}{2}}) \, dW(t) \]
in addition to the standard increments \( W(t_j) - W(t_{j-1}) \). This can easily be accomplished by taking note of
\[ \mathbb{E}_W \left[ (W(t_j) - W(t_{j-1})) \int_{t_{j-1}}^{t_j} (t - t_j^{-\frac{1}{2}}) \, dW(t) \right] = \int_{t_{j-1}}^{t_j} (t - t_j^{-\frac{1}{2}}) \, dt = 0, \]
that is, the two random variables are uncorrelated. Since they are jointly normally distributed, they are also mutually independent. Therefore, we can simulate the two increments in practice by generating \((Z_1, Z_2) \sim \mathcal{N}(0, I_2)\) and then setting
\[ \left( \frac{W(t_j) - W(t_{j-1})}{\int_{t_{j-1}}^{t_j} (t - t_j^{-\frac{1}{2}}) \, dW(t)} \right) \sim \left( \frac{h^{\frac{1}{2}}}{\sqrt{\frac{1}{2}h^{\frac{1}{2}}}}, 0 \right) \left( Z_1, Z_2 \right), \]
hereby we make use of the fact that
\[ \mathbb{E}_W \left[ \int_{t_{j-1}}^{t_j} (t - t_j^{-\frac{1}{2}}) \, dW(t) \right]^2 = \int_{t_{j-1}}^{t_j} (t - t_j^{-\frac{1}{2}})^2 \, dt = \frac{12}{12} h^3. \]

Theorem 4.3. Let Assumption 4.1 be satisfied with \( p \in [2, \infty) \) and \( \sigma \in (0, 1) \). Then, for all \( N \in \mathbb{N} \) with \( \frac{\pi}{N} = h \) it holds true that
\[ \|I[g] - Q^{\text{Trap}}_N[g]\|_{L^p(\Omega)} \leq C_p(2p(p - 1))^{\frac{1}{2}} T^{\frac{2}{p-2}} h^{1+\sigma} \|g\|_{W^{1+\sigma,p}(0,T)}. \]

The proof of Theorem 4.3 relies on the following lemma, which contains a useful representation of the error of the quadrature formula (13).

Lemma 4.4. Let Assumption 4.1 be satisfied with \( p \in [2, \infty) \), \( \sigma \in (0, 1) \). Then, for every \( N \in \mathbb{N} \) the discrete time error process \((E^n)_{n \in \{0, \ldots, N\}}\) of the quadrature rule (13) defined by \( E^0 := 0 \) and
\[ E^n = \frac{1}{h} \sum_{j=1}^{n} \int_{t_{j-1}}^{t_j} \left( \hat{g}(t) - \frac{1}{2} (g(\xi_j) + g(\xi_j)) - \frac{1}{h} (g(t_j) - g(t_{j-1})) (t - t_j^{-\frac{1}{2}}) \right) \, dW(t) \]
for \( n \in \{1, \ldots, N\} \), is a discrete time \((\mathcal{F}_t)_{t \in [0, T]}\)-adapted \( L^p(\Omega_W)\)-martingale. Moreover, it holds true that
\[ E^n = \frac{1}{h} \sum_{j=1}^{n} \int_{t_{j-1}}^{t_j} \int_{t_{j-1}}^{t_j} \left( \int_{t_j^{-\frac{1}{2}}}^{t} (\hat{g}(s) - \hat{g}(r)) \, ds \right. \]
\[ \left. - \frac{1}{2} \int_{t_j^{-\frac{1}{2}}}^{\xi_j} (\hat{g}(s) - \hat{g}(r)) \, ds - \frac{1}{2} \int_{t_j^{-\frac{1}{2}}}^{\xi_j} (\hat{g}(s) - \hat{g}(r)) \, ds \right) \, dr \, dW(t) \]
for all \( n \in \{1, \ldots, N\} \).

Proof. The martingale property and the \( L^p(\Omega_W)\)-integrability follow directly from the definition of \( E^n \) and the fact that \( g \in W^{1+\sigma,p}(0, T) \) implies the boundedness of \( g \). In order to prove (14) let us rewrite \( g(\xi_j) + g(\xi_j) \) in a suitable way by
\[ g(\xi_j) + g(\xi_j) = 2g(t_j^{-\frac{1}{2}}) + \int_{t_j^{-\frac{1}{2}}}^{\xi_j} \hat{g}(s) \, ds + \int_{t_j^{-\frac{1}{2}}}^{\xi_j} \hat{g}(s) \, ds, \]
where \( \hat{g} \) denotes the weak derivative of \( g \in W^{1+\sigma,p}(0,T) \). Therefore, we have for all \( t \in [t_{j-1}, t_j] \) that
\[
g(t) - \frac{1}{2} \left( g(\xi_j) + g(\xi_j) \right) = g(t) - g(t) - \frac{1}{2} \int_{t_{j-1}}^{\xi_j} \hat{g}(s) \, ds - \frac{1}{2} \int_{t_{j-1}}^{\xi_j} \hat{g}(s) \, ds.
\]
Inserting this into the definition of \( E^n \) then yields the three terms
\[
E^n = \sum_{j=1}^{n} \left( X^j_a - \frac{1}{2} X^j_b - X^j_c \right),
\]
where
\[
X^j_a = \int_{t_{j-1}}^{t_j} (g(t) - g(t_{j-1})) \, dW(t),
\]
\[
X^j_b = \int_{t_{j-1}}^{t_j} \left( \int_{t_{j-1}}^{\xi_j} \hat{g}(s) \, ds + \int_{t_{j-1}}^{\xi_j} \hat{g}(s) \, ds \right) \, dW(t),
\]
\[
X^j_c = \frac{1}{h} (g(t_j) - g(t_{j-1})) \int_{t_{j-1}}^{t_j} (t - t_{j-1}) \, dW(t).
\]
In the following let \( j \in \{1, \ldots, n\} \) be arbitrary. For the term \( X^j_c \) we then obtain
\[
X^j_c = \frac{1}{h} (g(t_j) - g(t_{j-1})) \int_{t_{j-1}}^{t_j} (t - t_{j-1}) \, dW(t)
= \frac{1}{h} \int_{t_{j-1}}^{t_j} \hat{g}(r) \, dr \int_{t_{j-1}}^{t_j} \int_{t_{j-1}}^{t} \, ds \, dW(t)
= \frac{1}{h} \int_{t_{j-1}}^{t_j} \int_{t_{j-1}}^{t} \int_{t_{j-1}}^{t_j} \hat{g}(r) \, dr \, ds \, dW(t).
\]
This now enables us to write
\[
X^j_a - X^j_b = \int_{t_{j-1}}^{t_j} \int_{t_{j-1}}^{t} \hat{g}(s) \, ds \, dW(t) - \frac{1}{h} \int_{t_{j-1}}^{t_j} \int_{t_{j-1}}^{t} \hat{g}(r) \, dr \, ds \, dW(t)
= \frac{1}{h} \int_{t_{j-1}}^{t_j} \int_{t_{j-1}}^{t} \left( \hat{g}(s) - \hat{g}(r) \right) \, ds \, dr \, dW(t).
\]
Further, due to the identity \( \xi_j - t_{j-1} = - (\xi_j - t_{j-1}) \) we have for the term \( X^j_b \) that
\[
X^j_b = \int_{t_{j-1}}^{t_j} \int_{t_{j-1}}^{\xi_j} \hat{g}(s) \, ds \, dW(t) + \int_{t_{j-1}}^{t_j} \int_{t_{j-1}}^{\xi_j} \hat{g}(s) \, ds \, dW(t)
= \frac{1}{h} \int_{t_{j-1}}^{t_j} \int_{t_{j-1}}^{\xi_j} \hat{g}(s) \, ds \, dW(t) + \frac{1}{h} \int_{t_{j-1}}^{t_j} \int_{t_{j-1}}^{\xi_j} \hat{g}(s) \, ds \, dW(t)
= \frac{\xi_j - t_{j-1}}{h} \int_{t_{j-1}}^{t_j} \hat{g}(r) \, dr \, dW(t) - \frac{\xi_j - t_{j-1}}{h} \int_{t_{j-1}}^{t_j} \hat{g}(r) \, dr \, dW(t)
= \frac{1}{h} \int_{t_{j-1}}^{t_j} \int_{t_{j-1}}^{\xi_j} \left( \hat{g}(s) - \hat{g}(r) \right) \, ds \, dr \, dW(t).
\]
Altogether, this completes the proof of (14). \( \square \)

This lemma in mind, we now present our proof of the main result of this section.
**Proof of Theorem 4.3.** Let \( N \in \mathbb{N} \) be arbitrary. Due to Lemma 4.4 we know that the discrete time error process \((E^n)_{n \in \{0, \ldots, N\}}\) is a \( p \)-fold integrable martingale with respect to the filtration \((\mathcal{F}^n_{t^n})_{n \in \{0, \ldots, N\}}\). Thus, an application of Theorem 2.2 yields

\[
\left\| \max_{n \in \{1, \ldots, N\}} |E^n| \right\|_{L^p(\Omega \times \mathbb{W})} \leq C_p \left\| \left( |E|^2 + \sum_{j=0}^{N-1} |E^{j+1} - E^j|^2 \right)^{\frac{1}{2}} \right\|_{L^p(\Omega \times \mathbb{W})}.
\]

After inserting \( E^0 = 0 \) and the representation (14) we obtain by an application of the triangle inequality

\[
\left\| \max_{n \in \{1, \ldots, N\}} |E^n| \right\|_{L^p(\Omega \times \mathbb{W})} \leq C_p \frac{1}{h} \left\| \left( \sum_{j=1}^{N} \left| \int_{t_{j-1}}^{t_j} \int_{t_{j-1}}^{t_j} \int_{t_{j-1}}^{t} (\hat{g}(s) - \hat{g}(r)) \, ds \, dr \, dt \right|^2 \right)^{\frac{1}{2}} \right\|_{L^p(\Omega \times \mathbb{W})} + C_p \frac{1}{h} \left\| \left( \sum_{j=1}^{N} \left| \int_{t_{j-1}}^{t_j} \int_{t_{j-1}}^{t_j} \int_{t_{j-1}}^{t} (\hat{g}(s) - \hat{g}(r)) \, ds \, dr \, dt \right|^2 \right)^{\frac{1}{2}} \right\|_{L^p(\Omega \times \mathbb{W})} + C_p \frac{1}{h} \left\| \left( \sum_{j=1}^{N} \left| \int_{t_{j-1}}^{t_j} \int_{t_{j-1}}^{t_j} \int_{t_{j-1}}^{t} (\hat{g}(s) - \hat{g}(r)) \, ds \, dr \, dt \right|^2 \right)^{\frac{1}{2}} \right\|_{L^p(\Omega \times \mathbb{W})}.
\]

All three terms on the right hand side of (15) can be estimated by the same arguments. We only give details for the first term: First note that

\[
C_p \frac{1}{h} \left\| \left( \sum_{j=1}^{N} \left| \int_{t_{j-1}}^{t_j} \int_{t_{j-1}}^{t_j} \int_{t_{j-1}}^{t} (\hat{g}(s) - \hat{g}(r)) \, ds \, dr \, dt \right|^2 \right)^{\frac{1}{2}} \right\|_{L^p(\Omega \times \mathbb{W})} = C_p \frac{1}{h} \left( \left\| \sum_{j=1}^{N} \left| \int_{t_{j-1}}^{t_j} \int_{t_{j-1}}^{t_j} \int_{t_{j-1}}^{t} (\hat{g}(s) - \hat{g}(r)) \, ds \, dr \, dt \right|^{2h} \right)^{\frac{1}{2}} \right)^{\frac{1}{2}} \leq C_p \frac{1}{h} \left( \sum_{j=1}^{N} \left| \int_{t_{j-1}}^{t_j} \int_{t_{j-1}}^{t_j} \int_{t_{j-1}}^{t} (\hat{g}(s) - \hat{g}(r)) \, ds \, dr \, dt \right|^{2h} \right)^{\frac{1}{2}}.
\]

Next, we apply Theorem 2.1 to each summand and obtain

\[
\left( \sum_{j=1}^{N} \left| \int_{t_{j-1}}^{t_j} \int_{t_{j-1}}^{t_j} \int_{t_{j-1}}^{t} (\hat{g}(s) - \hat{g}(r)) \, ds \, dr \, dt \right|^{2h} \right)^{\frac{1}{2}} \leq \left( \frac{p(p-1)}{2} \right)^{\frac{1}{2}} h^{p \sigma - \frac{1}{2}} \left( \sum_{j=1}^{N} \left( \int_{t_{j-1}}^{t_j} \int_{t_{j-1}}^{t} (\hat{g}(s) - \hat{g}(r)) \, ds \, dr \right)^p \right)^{\frac{1}{p}} \leq \left( \frac{p(p-1)}{2} \right)^{\frac{1}{2}} h^{p \sigma - \frac{1}{2}} N \left( \sum_{j=1}^{N} \left( \int_{t_{j-1}}^{t_j} \int_{t_{j-1}}^{t} (\hat{g}(s) - \hat{g}(r)) \, ds \, dr \right)^p \right)^{\frac{1}{p}} \leq \left( \frac{p(p-1)}{2} \right)^{\frac{1}{2}} T^{p \sigma - \frac{1}{2}} \left( \sum_{j=1}^{N} h^{2(p-1)} \left( \int_{t_{j-1}}^{t_j} \left| \int_{t_{j-1}}^{t} |\hat{g}(s) - \hat{g}(r)| \, ds \, dr \right|^p \right)^{\frac{1}{p}} \right)^{\frac{1}{p}} \leq \left( \frac{p(p-1)}{2} \right)^{\frac{1}{2}} T^{p \sigma - \frac{1}{2}} \left( \sum_{j=1}^{N} h^{2(p-1)} \left( \int_{t_{j-1}}^{t_j} \left( \int_{t_{j-1}}^{t} |\hat{g}(s) - \hat{g}(r)| \, ds \right)^p \right)^{\frac{1}{p}} \right)^{\frac{1}{p}} \leq \left( \frac{p(p-1)}{2} \right)^{\frac{1}{2}} T^{p \sigma - \frac{1}{2}} h^{2+\sigma} \left( \int_{0}^{T} \left| g \right|^p \right)^{\frac{1}{p}}.
\]
where we also applied Hölder’s inequality several times. Thus, together with the factor \( C_p \frac{1}{h} \) we arrive at

\[
C_p \frac{1}{h} \left( \sum_{j=1}^{N} \left( \int_{t_{j-1}}^{t_{j}} \int_{t_{j-1}}^{t} (\dot{g}(s) - \dot{g}(r)) \, ds \, dW(t) \right)^2 \right)^{\frac{1}{2}} \leq C_p \left( \frac{p(p-1)}{2} \right) \frac{1}{T} \frac{1}{\hbar^2} \left( h \right)^{1+\sigma} \left\| g \right\|_{W^{1+\sigma}(0,T)}.
\]

Up to an additional factor \( \frac{1}{2} \) the same estimate is valid for the other two terms in (15). This completes the proof. \( \square \)

5. Numerical examples with some deterministic integrands

In this section we perform numerically the quadrature of the Itô-integral (1) with three deterministic integrands \( g_i : [0,T] \to \mathbb{R}, i \in \{1, 2, 3\} \). Hereby, the first integrand \( g_1 \) is smooth but oscillating, while the second is discontinuous with a jump. The third integrand is not smooth in the sense that either itself or its derivative contains a weak singularity at \( t = 0 \). We perform a series of numerical experiments which verify the theoretical results of both quadrature formulas (7) and (13).

For the implementation of the numerical examples, we follow a similar approach as already mentioned in Remark 4.2. In order to approximate the error we simultaneously generate the exact value of the Itô-integral and the Wiener increments required for the quadrature rules. For this we generate a random vector \((Z_1, Z_2, Z_3) \sim \mathcal{N}(0, I_3)\) and define

\[
\begin{pmatrix}
X_1 \\
X_2 \\
X_3
\end{pmatrix} := \begin{pmatrix}
\int_{t_{j-1}}^{t_j} dW(t) \\
\int_{t_{j-1}}^{t_j} (t - t_{j-1}) \, dW(t) \\
\int_{t_{j-1}}^{t_j} g(t) \, dW(t)
\end{pmatrix} \sim G \begin{pmatrix}
Z_1 \\
Z_2 \\
Z_3
\end{pmatrix},
\]

where \( t_{j-1} = \frac{1}{h} (t_{j-1} + t_j) \) and the matrix \( G \) is the Cholesky decomposition of the covariance matrix \( Q \in \mathbb{R}^{3,3} \) given by

\[
Q = \mathbb{E}_W \left[ X_n X_m \right]_{n,m \in \{1,2,3\}}.
\]

Similar to Remark 4.2 the upper left part of \( Q \) takes on the values

\[
\mathbb{E}_W [X_1^2] = h, \quad \mathbb{E}_W [X_2^2] = \frac{h^3}{12} \quad \text{and} \quad \mathbb{E}_W [X_1 X_2] = 0.
\]

The newly appearing terms in the third column and row of \( Q \) are given by

\[
\begin{align*}
\mathbb{E}_W [X_3^2] &= \int_{t_{j-1}}^{t_j} g^2(t) \, dt, \\
\mathbb{E}_W [X_1 X_3] &= \int_{t_{j-1}}^{t_j} g(t) \, dt, \quad \text{and} \\
\mathbb{E}_W [X_2 X_3] &= \int_{t_{j-1}}^{t_j} t g(t) \, dt - t_{j-\frac{1}{2}} \int_{t_{j-1}}^{t_j} g(t) \, dt.
\end{align*}
\]

The random variables are then used to compute the exact value of the Itô-integral as well as the stochastic integral in the higher order quadrature formula (13). In the same way, we simulate the increments and the exact solution for the randomly shifted Riemann-Maruyama rule (7), where we do not need to simulate \( X_2 \) and we have to replace the grid points \( \pi_h = (t_j)_{j \in \{0, \ldots, N\}} \) by those in \( \pi_h(\xi) \) for each realization of the random shift \( \xi \sim \mathcal{U}(0,1) \) as defined in (5). For a more detailed introduction and explanation of this procedure, see, for example, [6, Section 2.3.3].
In our example we first choose the function \( g_1 : [0, T] \to \mathbb{R} \) with \( g_1(t) = \sin(\lambda t) \) for a constant value \( \lambda \in \mathbb{R} \). For this choice of integrand the appearing integrals in the covariance matrix \( Q \) can be stated explicitly and are given by

\[
\int_{t_{j-1}}^{t_j} g_1(t) \, dt = \frac{1}{\lambda} \left( -\cos(\lambda t_j) + \cos(\lambda t_{j-1}) \right),
\]

\[
\int_{t_{j-1}}^{t_j} t g_1(t) \, dt = \frac{1}{\lambda^2} \left( \sin(\lambda t_j) - \sin(\lambda t_{j-1}) \right) - \frac{1}{\lambda} \left( t_j \cos(\lambda t_j) - t_{j-1} \cos(\lambda t_{j-1}) \right),
\]

as well as

\[
\int_{t_{j-1}}^{t_j} g_1^2(t) \, dt = \frac{h}{2} - \frac{1}{4\lambda} \left( \sin(2\lambda t_j) - \sin(2\lambda t_{j-1}) \right).
\]

Using the fact that \( |\sin(t)| \leq t \) holds true for all \( t \in [0, \infty) \), we obtain for every \( h_0 \in (0, T] \) and \( \sigma \in (0, 1) \) that

\[
\int_0^{h_0} t^{-2\sigma} \sin^2(\lambda t) \, dt \leq \int_0^{h_0} \lambda^2 t^{-2\sigma + 2} \, dt < \infty.
\]

Thus, it is easy to see that our choice of the integrand \( g_1 \) fulfills Assumption 3.1 and Assumption 4.1 for \( p = 2 \) and every value \( \sigma \in (0, 1) \). Therefore, our results from Theorem 3.4 and Theorem 4.3 suggest that the quadrature rule (7) converges with a rate of 1 whereas the quadrature rule (13) converges with a rate 2.

Next, for \( c \in (0, T) \) we consider the jump function

\[ g_2 : [0, T] \to \mathbb{R}, \quad g_2(t) = \begin{cases} 0, & t \in [0, c) \\ 1, & t \in [c, T]. \end{cases} \]

This type of function is considered in more detail in Section 6 coming. There, we prove in Lemma 6.3 that this function is an element of \( W^{\sigma, p}(0, T) \) for \( \sigma p < 1 \). Therefore, Assumption 3.1 is fulfilled for \( p \in [2, \infty) \) and every value \( \sigma \in (0, 1+) \) and Theorem 3.4 yields the convergence of (7) with a rate \( \sigma \). Note that this function is not even continuous, therefore one can not expect to prove any rate of convergence when measuring the regularity in an Hölder setting. The integrals appearing in the covariance matrix \( Q \) can again be stated explicitly as

\[
\int_{t_{j-1}}^{t_j} g_2(t) \, dt = \int_{t_{j-1}}^{t_j} g_2^2(t) \, dt = \begin{cases} 0, & t_j < c \\ t_j - c, & c \in [t_{j-1}, t_j] \\ t_j - t_{j-1}, & t_{j-1} > c \end{cases}
\]

and

\[
\int_{t_{j-1}}^{t_j} t g_2(t) \, dt = \begin{cases} 0, & t_j < c \\ \frac{1}{2} (t_j^2 - c^2), & c \in [t_{j-1}, t_j] \\ \frac{1}{2} (t_j^2 - t_{j-1}^2), & t_{j-1} > c. \end{cases}
\]

As a third example we consider functions of the form \( g_3 : [0, T] \to \mathbb{R} \) with \( g_3(t) = t^\gamma \) for \( \gamma \in (-\frac{1}{2}, \frac{1}{2}] \setminus \{0\} \). For this choice of integrand the appearing integrals can again be stated explicitly and are given by

\[
\int_{t_{j-1}}^{t_j} g_3(t) \, dt = \frac{1}{\gamma + 1} (t_j^{\gamma+1} - t_{j-1}^{\gamma+1}), \quad \int_{t_{j-1}}^{t_j} t g_3(t) \, dt = \frac{1}{\gamma + 2} (t_j^{\gamma+2} - t_{j-1}^{\gamma+2}),
\]
as well as
\[ \int_{t_{j-1}}^{t_j} g_3^2(t) \, dt = \frac{1}{2\gamma + 1}(t_{j+1}^{2\gamma+1} - t_{j-1}^{2\gamma+1}). \]

The regularity of the second integrand \( g_3 \) requires a little more attention and depends on the choice of \( \gamma \). First, if \( \gamma \in (0, \frac{1}{2}] \) the weak derivative of \( g_3 \) satisfies \( g_3 \in L^p(0, T) \) for \( p < \frac{1}{1-\gamma} \). Hence, from Sobolev’s embedding theorem, see, for example, \([16, \text{Corollary 18}]\), we get
\[ W^{1,p}(0, T) \hookrightarrow W^{\sigma,2}(0, T) \]
for \( 1 - \frac{1}{p} = \sigma - \frac{1}{2} \). This implies \( g_3 \in W^{\sigma,2}(0, T) \) for every \( \sigma = \frac{3}{2} - \frac{1}{p} < \frac{3}{2} - (1 - \gamma) = \frac{1}{2} + \gamma \). Thus, in this case Assumption 3.1 is satisfied with \( p = 2 \) and for all \( \sigma \in (0, \frac{1}{2} + \gamma) \) including condition (11) for the initial value. Assumption 4.1 is, however, not satisfied for any value \( \gamma \in (0, \frac{1}{2}] \).

Next, we turn to the case \( \gamma \in (-\frac{1}{2}, 0) \), where we explicitly estimate the Sobolev–Slobodeckij norm. For this let \( s, t \in [0, T] \) with \( s < t \) be arbitrary. Then, since \( g_3 \) is a decreasing, nonnegative function for \( \gamma \in (-\frac{1}{2}, 0) \) we have
\[ |g_3(t) - g_3(s)| = g_3(s) - g_3(t) \leq g_3(s) = s^\gamma. \]

Moreover, by the fundamental theorem of calculus it holds true that
\[ |g_3(t) - g_3(s)| = \frac{1}{|\gamma|} \int_s^t (s + \rho(t-s))^{-1+\gamma} \, d\rho \leq \frac{1}{|\gamma|} s^{-1+\gamma}|t-s|. \]

Inserting this into the Sobolev–Slobodeckij semi-norm yields for every \( \mu \in (0, \frac{1}{2} + \gamma) \) that
\[
\begin{align*}
\int_0^T \int_0^T \frac{|g_3(t) - g_3(s)|^2}{|t-s|^{1+2\mu}} \, ds \, dt &= 2 \int_0^T \int_0^t \frac{|g_3(t) - g_3(s)|^{2(1-\mu)} |g_3(t) - g_3(s)|^{2\mu}}{|t-s|^{1+2\sigma}} \, ds \, dt \\
&\leq \frac{2}{|\gamma|^{2\mu}} \int_0^T \int_0^t s^{2(1-\mu)\gamma}s^{2\mu(-1+\gamma)}|t-s|^{2\mu-2\sigma} \, ds \, dt \\
&= \frac{2}{|\gamma|^{2\mu}} \int_0^T \int_0^t s^{2\gamma-2\mu}|t-s|^{2\mu-2\sigma} \, ds \, dt.
\end{align*}
\]

The latter integral is finite for every \( \sigma \in (0, \mu) \) due to \( 2\gamma - 2\mu > -1 \) by our choice of \( \mu \in (0, \frac{1}{2} + \gamma) \). In sum, this proves that \( g_3 \in W^{\sigma,2}(0, T) \) for all \( \sigma \in (0, \frac{1}{2} + \gamma) \). Since condition (11) is also easily verified, it again follows that \( g_3 \) satisfies Assumption 3.1 with \( p = 2 \) and for all \( \sigma \in (0, \frac{1}{2} + \gamma) \) if \( \gamma \in (-\frac{1}{2}, 0) \). Therefore, we can apply Theorem 3.4 and we obtain that the quadrature rule (7) converges with a rate of \( \gamma + \frac{1}{2} \) in both parameter ranges \( \gamma \in (0, \frac{1}{2}) \) and \( \gamma \in (-\frac{1}{2}, 0) \).

Since Assumption 4.1 is violated for all values of \( \gamma \), Theorem 4.3 does not apply to \( g_3 \). Nevertheless, we still used the quadrature rule (13) in our numerical experiments in this case. Hereby, it should be mentioned that for \( \gamma \in (-\frac{1}{2}, 0) \) the scheme (13) is actually not well defined, since there appears an evaluation of the function \( g_3 \) at the point \( t_0 = 0 \) at which \( g_3 \) possesses a singularity. In the numerical example we made use of the fact, that we knew in advance where the singularity is situated and left out this specific summand in the quadrature rule.

This problem illustrates well one advantage of a randomized point evaluation. A quadrature formula based on a deterministic time grid might not offer a useful approximation if a singularity of the integrand happens to be at a grid point. On
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For the numerical experiment displayed in Figure 1, we chose the final time $T = 1$ and the parameter values $\lambda = 42$ for $g_1$, $c = 0.5$ for $g_2$ as well as the parameters $\gamma = -0.3$ and $\gamma = 0.5$ for $g_3$. As step sizes we took $h_i = 2^{-i}$ with $i \in \{3, \ldots, 12\}$. For the computation of the error we used the sum of the random variables $X_3$ defined in (16) as the exact solution. For both quadrature formulas, the $L^2$-norm was approximated by taking the average over 1000 Monte Carlo iterations. The parameter $\xi$ in (13) was chosen to be 0, so we obtained the stochastic version of the trapezoidal quadrature rule (8).

It can be seen in Figure 1 that both quadrature rules (7) and (8) performed as expected in all our experiments. In particular, in the case of $g_1$ we observed an experimental order of convergence of rate 1 for (7) and of rate 2 for (8). For the function $g_2$ the randomly shifted Riemann-Maruyama rule (7) converges experimentally with a rate of 0.5. Even though the assumptions for Theorem 4.3 are not fulfilled, the approximation (8) is comparable to (7). For $g_3$ we expected a convergence rate of $\gamma + \frac{1}{2}$ for (7) which is well visible in our two numerical tests in the second row of Figure 1. Observe that (8) shows the same convergence rates in our last two experiments as (7) but with a better error constant. This indicates that the higher order method is advantageous even in some situations, where the regularity of the

![Figure 1. $L^2$-convergence of the lower order scheme (7) (green triangles) and the higher order scheme (13) (blue circles) with $g_1$ with $\lambda = 42$, $g_2$ with $c = 0.5$ as well as $g_3$ with both $\gamma = 0.5$ and $\gamma = -0.3$. For the function $g_1$ we inserted order lines with slopes 1 and 2 as well as an order line of slope 0.5 for $g_2$. In the second row we added two order lines with slope 1 into the left hand subfigure while both order lines have a slope of 0.2 on the right hand side.](image)
The integrand is not sufficient to ensure a more accurate approximation. However, as already mentioned above, we had to slightly modify the quadrature rule (8) for $g_3$ with $\gamma = -0.3$ in order to prevent an evaluation of $g_3$ at its singularity.

6. Application to Poisson processes

In this section we apply the randomly shifted Riemann–Maruyama rule (7) for the approximation of a stochastic integral whose integrand is a Poisson process. To this end, we first recall the definition of a Poisson process. Then we show that it fulfills the condition of Assumption 3.1. Finally, we perform a numerical experiment.

Definition 6.1. A Poisson process $\Pi: [0, T] \times \Omega_W \to \mathbb{N}_0$ with intensity $a \in (0, \infty)$ is a stochastic process on $(\Omega_W, \mathcal{F}_W, P_W)$ with the following properties:

(i) There holds $\Pi(0) = 0$ almost surely.

(ii) For any $0 \leq t_0 < t_1 < \ldots < t_n \leq T$, $n \in \mathbb{N}$, the random variables $(\Pi(t_i) - \Pi(t_{i-1}))_{i \in \{1, \ldots, n\}}$ are independent.

(iii) For all $0 \leq s \leq t \leq T$ the law of the increment $\Pi(t) - \Pi(s)$ is the Poisson distribution with mean $a(t - s)$, that is

$$P_W(\Pi(t) - \Pi(s) = n) = \frac{(a(t-s))^n}{n!} e^{-a(t-s)},$$

for all $n \in \mathbb{N}_0$.

(iv) The sample paths of $\Pi$ are càdlàg.

The following proposition is very useful in order to determine the temporal regularity of a typical sample path of a Poisson process. A proof is found, for instance, in [12, Proposition 4.9].

Proposition 6.2. Let $\Pi: [0, T] \times \Omega_W \to \mathbb{N}_0$ be a Poisson process with intensity $a \in (0, \infty)$. Then there exists an independent and with the same parameter $a \in (0, \infty)$ exponentially distributed family of random variables $(Z_n)_{n \in \mathbb{N}}$ on $(\Omega_W, \mathcal{F}_W, P_W)$ such that

$$\Pi(t) = \begin{cases} 0, & \text{if } t \in [0, Z_1), \\ k, & \text{if } t \in [Z_1 + \ldots + Z_k, Z_1 + \ldots + Z_{k+1}). \end{cases}$$

We recall that a random variable $Z: \Omega_W \to \mathbb{R}$ is exponentially distributed with parameter $a$ if

$$P_W(Z > x) = e^{-ax} \quad \text{for all } x \in [0, \infty).$$

Next, let us introduce an indicator function $I_c: [0, T] \to \mathbb{R}$, $c \in [0, \infty)$, of the form $I_c(t) = \mathbb{1}_{[c, \infty)}(t)$, $t \in [0, T]$. It then follows from Proposition 6.2 that we can formally write $\Pi$ as a series of the form

$$\Pi(t, \omega) = \sum_{k=1}^{\infty} I_{S_k(\omega)}(t), \quad t \in [0, T], \omega \in \Omega_W,$$

where the random jump points $S_k(\omega)$ are given by

$$S_k(\omega) := \sum_{j=1}^{k} Z_j(\omega), \quad \text{for all } \omega \in \Omega_W.$$
Lemma 6.3. For every \( c \in [0, T] \), \( \sigma \in (0, 1) \), and \( p \in [1, \infty) \) with \( \sigma p < 1 \) it holds true that \( L_c \in W^{\sigma, p}(0, T) \). In addition, we have

\[
\sup_{c \in [0, T]} \| L_c \|_{W^{\sigma, p}(0, T)} < \infty.
\]

Proof. Since the indicator function is bounded by 1 we directly get

\[
\| L_c \|_{L^p(0, T)} \leq T^\frac{1}{p}
\]

for all \( p \in [1, \infty) \). In addition, for every \( c \in [0, T] \), \( \sigma \in (0, 1) \), and \( p \in [1, \infty) \) with \( \sigma p < 1 \) we have

\[
\int_0^T \int_0^T \frac{|L_c(t) - L_c(s)|^p}{|t-s|^{1+\sigma p}} \, dt \, ds
= \int_0^c \int_0^T \frac{1}{|t-s|^{1+\sigma p}} \, dt \, ds + \int_c^T \int_0^T \frac{1}{|t-s|^{1+\sigma p}} \, dt \, ds
= \frac{2}{\sigma p} \int_c^T (t-c)^{-\sigma p} - t^{-\sigma p} \, dt
\leq \frac{2}{\sigma p (1-\sigma p)} T^{1-\sigma p}.
\]

Since \( c \in [0, T] \) was arbitrary, the assertion follows. \( \square \)

We are now well-prepared to verify that every Poisson process indeed satisfies the conditions of Assumption 3.1.

Theorem 6.4. Let \( \Pi : [0, T] \times \Omega_W \to \mathbb{N}_0 \) be a Poisson process with intensity \( a \in (0, \infty) \). Then, for any \( p \in [1, \infty) \), \( \sigma \in (0, 1) \) with \( \sigma p < 1 \) we have

\[\Pi \in L^p(\Omega_W; W^{\sigma, p}(0, T)).\]

In addition, for every \( h_0 \in (0, T) \), \( p \in [1, \infty) \), and \( \sigma \in (0, 1) \) with \( \sigma p < 1 \) there exists \( C_0 \in (0, \infty) \) such that

\[\left( \int_0^{h_0} t^{-\sigma p} \mathbb{E}_W \left[ \| \Pi(t) \|^p \right] \, dt \right)^{\frac{1}{p}} \leq C_0.\]

In particular, every Poisson process with intensity \( a \in (0, \infty) \) fulfills the conditions of Assumption 3.1 for every \( p \in [2, \infty) \) and \( \sigma \in (0, 1) \) with \( \sigma p < 1 \).

Proof. First, let \( p \in [1, \infty) \) be arbitrary. We observe that a typical sample path of \( \Pi \) is nonnegative and increasing. Hence, we have

\[\sup_{t \in [0, T]} \| \Pi(t) \|_{L^p(\Omega_W)} = \| \Pi(T) \|_{L^p(\Omega_W)} < \infty\]

by the Poisson distribution of \( \Pi(T) \) with mean \( aT \). From this we immediately obtain (20).

Furthermore, we obtain \( \mathbb{P}_W(A) = 1 \) where \( A \in \mathcal{F}_W \) denotes the event

\[A = \{ \omega \in \Omega_W : \sup_{t \in [0, T]} \Pi(t, \omega) = \Pi(T, \omega) < \infty \} \].

Then, for every \( \omega \in A \) the series in (18) consists of fact of only finitely many indicator functions. More precisely, there exists \( N(\omega) := \Pi(T, \omega) \in \mathbb{N}_0 \) such that

\[\Pi(t, \omega) = \sum_{k=1}^{N(\omega)} I_{S_k(\omega)}(t), \quad t \in [0, T],\]

where \( S_k(\omega) \) are defined in (19). Together with Lemma 6.3 this proves that for every \( p \in [1, \infty) \), \( \sigma \in (0, 1) \) with \( \sigma p < 1 \) we have

\[\mathbb{P}_W \left( \{ \omega \in \Omega_W : \Pi(\cdot, \omega) \in W^{\sigma, p}(0, T) \} \right) = 1.\]
Hence, it remains to show that

\[ \mathbb{E}_W \left[ \int_0^T \int_0^T \frac{|\Pi(t) - \Pi(s)|^p}{|t - s|^{1+\sigma p}} \ ds \ dt \right] < \infty. \]

To this end, we insert the representation (21) and obtain

\[ \mathbb{E}_W \left[ \int_0^T \int_0^T \frac{|\Pi(t) - \Pi(s)|^p}{|t - s|^{1+\sigma p}} \ ds \ dt \right] \]

\[ = \sum_{n=0}^{\infty} \int_{\Omega_W} I_{\{\Pi(T,\omega) = n\}}(\omega) \int_0^T \int_0^T \frac{|\Pi(t,\omega) - \Pi(s,\omega)|^p}{|t - s|^{1+\sigma p}} \ ds \ dt \ dP_W(\omega) \]

\[ \leq \sum_{n=0}^{\infty} \sum_{k=1}^{n} \int_{\Omega_W} I_{\{\Pi(T,\omega) = n\}}(\omega) n^{p-1} \int_0^T \int_0^T \frac{|I_{S_k}(\omega)(t) - I_{S_k}(\omega)(s)|^p}{|t - s|^{1+\sigma p}} \ ds \ dt \ dP_W(\omega) \]

\[ \leq \sum_{n=0}^{\infty} \sum_{k=1}^{n} \int_{\Omega_W} I_{\{\Pi(T,\omega) = n\}}(\omega) n^{p-1} \|I_{S_k}(\omega)\|^p_{W^{\sigma,p}(0,T)} \ dP_W(\omega) \]

\[ \leq \sup_{c \in [0,T]} \|I_c\|^p_{W^{\sigma,p}(0,T)} \sum_{n=0}^{\infty} n^{p} \int_{\Omega_W} I_{\{\Pi(T,\omega) = n\}}(\omega) \ dP_W(\omega) \]

\[ \leq \sup_{c \in [0,T]} \|I_c\|^p_{W^{\sigma,p}(0,T)} \|\Pi(T)\|^p_{L^p(\Omega_W)}, \]

where we also used that \(S_k(\omega) \in [0,T]\) for all \(\omega \in \{\Pi(T) = n\}\) and \(1 \leq k \leq n\). An application of Lemma 6.3 then completes the proof. \(\square\)

We close this section with a short numerical experiment. Hereby we applied the randomly shifted Riemann–Maruyama quadrature rule for the approximation of an Itô-integral whose integrand is a Poisson process. For the error plot displayed in Figure 2 we chose the final time \(T = 10\) and the intensity parameter \(a = \frac{3}{4}\). As step sizes we took \(h \in \{T2^{-i} : i = 3, \ldots, 12\}\). For the approximation of the error we compared the result of the quadrature rule with a given step size \(h\) to a numerical reference solution with the smaller step size \(\frac{h}{16}\) driven by the
same stochastic trajectories. In addition, the $L^2(\Omega)$-norm was approximated by a 
standard Monte Carlo simulation with 1000 independent samples.

As one can see in Figure 2, the randomly shifted Riemann–Maruyama rule per-
formed as expected with an experimental order of convergence close to $\frac{1}{2}$, in agree-
ment with the regularity of the Poisson process. Since we already knew from Section 5 
that the higher order quadrature rule (8) does not yield an advantage if the 
integrand has jumps, it was not implemented in this example.

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