On the Reproducibility of Neural Network Predictions

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Abstract

Standard training techniques for neural networks involve multiple sources of randomness, e.g., initialization, mini-batch ordering and in some cases data augmentation. Given that neural networks are heavily over-parameterized in practice, such randomness can cause churn – for the same input, disagreements between predictions of the two models independently trained by the same algorithm, contributing to the ‘reproducibility challenges’ in modern machine learning. In this paper, we study this problem of churn, identify factors that cause it, and propose two simple means of mitigating it. We first demonstrate that churn is indeed an issue, even for standard image classification tasks (CIFAR and ImageNet), and study the role of the different sources of training randomness that cause churn. By analyzing the relationship between churn and prediction confidences, we pursue an approach with two components for churn reduction. First, we propose using minimum entropy regularizers to increase prediction confidences. Second, we present a novel variant of co-distillation approach [Anil et al., 2018] to increase model agreement and reduce churn. We present empirical results showing the effectiveness of both techniques in reducing churn while improving the accuracy of the underlying model.

1 Introduction

Deep neural networks (DNNs) have seen remarkable success in a range of complex tasks, and significant effort has been spent on further improving their predictive accuracy. However, an equally important desideratum of any machine learning system is stability or reproducibility in its predictions. In practice, machine learning models are continuously (re)-trained as new data arrives, or to incorporate architectural and algorithmic changes. A model that changes its predictions on a significant fraction of examples after each update is undesirable, even if each model instantiation attains high accuracy.

As machine learning models make inroads into various aspects of society, ranging from healthcare, education, cyber-security, credit scoring to recidivism prediction, addressing such reproducibility issues is becoming increasingly important. For example, in health care applications, it is undesirable if models trained to detect a disease change their predictions over different training re-runs just due to randomness in the training algorithm. In cyber-security applications, [Krisiloff, 2019] highlighted the challenges prediction churn poses in updating machine learning models.

Reproducibility of predictions is a challenge even if the architecture and training data are fixed across different training runs, which is the focus of this paper. Unfortunately, two key ingredients that help deep networks attain high accuracy — over-parameterization, and the randomization of their training algorithms — pose significant challenges to their reproducibility. The former refers to the fact that NNs typically have many solutions that minimize the training objective [Neyshabur et al., 2015, Zhang et al., 2017]. The latter refers to...
the fact that standard training of NNs involves several sources of randomness, e.g., initialization, mini-batch ordering, non-determinism in training platforms and in some cases data augmentation. Put together, these imply that NN training can find vastly different solutions in each run even when training data is the same, leading to a reproducibility challenge. In Figure 1, we present few test set predictions from five ResNet-v2-50 models trained on ImageNet in independent training runs. While the different training runs result in similar accuracy, the predictions on individual examples vary significantly.

The prediction disagreement between two models is referred to as churn \cite{Cormier2016}. Concretely, given two models, churn is the fraction of test examples where the predictions of the two models disagree. Clearly, churn is zero if both models have perfect accuracy – an unattainable goal for most of the practical settings of interest. Similarly, one can mitigate churn by eliminating all sources of randomness in the underlying training setup. However, even if one controls the seed used for random initialization and the order of data — which by itself is a challenging task in distributed training — inherent non-determinism in the current computation platforms is hard to avoid (see §2.3). Moreover, it is desirable to have stable models with predictions unaffected by such factors in training. Thus, it is critical to quantify churn, and develop methods that reduce it.

In this paper, we study the problem of churn in NNs for the classification setting. We demonstrate the presence of churn, and investigate the role of different training factors causing it. Interestingly, our experiments show that churn is not avoidable on the computing platforms commonly used in machine learning, further highlighting the necessity of developing techniques to mitigate churn. We then analyze the relation between churn and predicted class probabilities. Based on this, we develop a novel regularized co-distillation approach for reducing churn.

Our key contributions are summarized below:

(i) Besides the disagreement in the final predictions of models, we propose alternative soft metrics to measure churn. We demonstrate the existence of churn on standard image classification tasks (CIFAR-10, CIFAR-100, ImageNet, SVHN and iNaturalist), and identify the components of learning algorithms that contribute to the churn. Furthermore, we analyze the relationship between churn and model prediction confidences (cf. §2).

(ii) Motivated from our analysis, we propose a regularized co-distillation approach to reduce churn that both improves prediction confidences and reduces prediction variance (cf. §3). Our approach consists of two components: a) minimum entropy regularizers that improve prediction confidences (cf. §3.1), and b) a new variant of co-distillation \cite{Anil2018} to reduce prediction variance across runs. Specifically, we use a symmetric KL divergence based loss to reduce model disagreement, with a linear warmup and joint updates across multiple models (cf. §3.2).

(iii) We empirically demonstrate the effectiveness of the proposed approach in reducing churn and (sometimes) increasing accuracy. We present ablation studies over its two components to show their complementary nature in reducing churn (cf. §4).

\footnote{Madani \textit{et al.} \textit{2004} referred to this as disagreement and used it as an estimate for generalization error and model selection}
1.1 Related work

Reproducibility in machine learning. There is a broad field studying the problem of reproducible research [Buckheit and Donoho, 1995, Gentleman and Lang, 2007, Sonnenburg et al., 2007, Kovacevic, 2007, Mesirov, 2010, Peng, 2011, McNutt, 2014, Braun and Ong, 2014, Rule et al., 2018], which identifies best practices to facilitate the reproducibility of scientific results. Henderson et al. [2018] analysed reproducibility of methods in reinforcement learning, showing that performance of certain methods is sensitive to the random seed used in the training. While the performance of NNs on image classification tasks is fairly stable (Table 2), we focus on analyzing and improving the reproducibility of individual predictions. Thus, churn can be seen as a specific technical component of this reproducibility challenge.

Cormier et al. [2016] defined the disagreement between predictions of two models as churn. They proposed an MCMC approach to train an initial stable model A so that it has a small churn with its future version, say model B. Here, future versions are based on slightly modified training data with possibly additional features. In Goh et al. [2016], Cotter et al. [2019], constrained optimization is utilized to reduce churn across different model versions. In contrast, we are interested in capturing the contribution of factors other than training data modification that cause churn.

More recently, Madhyastha and Jain [2019] study instability in the interpretation mechanisms and average performance for deep NNs due to change in random seed, and propose a stochastic weight averaging [Izmailov et al., 2018] approach to promote robust interpretations. In contrast, we are interested in robustness of individual predictions.

Ensembling and online distillation. Ensemble methods [Dietterich, 2000, Lakshminarayanan et al., 2017] that combine the predictions from multiple (diverse) models naturally reduce the churn by averaging out the randomness in the training procedure of the individual models. However, such methods incur large memory footprint and high computational cost during the inference time. Distillation [Hinton et al., 2015, Bucilua et al., 2006] aims to train a single model from the ensemble to alleviate these costs. Even though distilled model aims to recover the accuracy of the underlying ensemble, it is unclear if the distilled model also leads to churn reduction. Furthermore, distillation is a two-stage process, involving first training an ensemble and then distilling it into a single model.

To avoid this two-stage training process, multiple recent works [Anil et al., 2018, Zhang et al., 2018, Lan et al., 2018, Song and Chai, 2018, Guo et al., 2020] have focused on online distillation, where multiple identical or similar models (with different initialization) are trained while regularizing the distance between their prediction probabilities. At the end of the training, any of the participating models can be used for inference. Notably, Anil et al. [2018], while referring to this approach as co-distillation, also empirically pointed out its utility for churn reduction on the Criteo Ad dataset. In contrast, we develop a deeper understanding of co-distillation framework as a churn reduction mechanism by providing a theoretical justification behind its ability to reduce churn. We experimentally show that using a symmetric KL divergence objective instead of the cross entropy loss for co-distillation [Anil et al., 2018] leads to lower churn and better accuracy, even improving over the expensive ensembling-distillation approach.

Entropy regularizer. Minimum entropy regularization was earlier explored in the context of semi-supervised learning [Grandvalet and Bengio, 2005]. Such techniques have also been used to combat label noise [Reed et al., 2015]. In contrast, we utilize minimum entropy regularization in fully supervised settings for a distinct purpose of reducing churn and experimentally show its effectiveness.

1.2 Notation

Multi-class classification. We consider a multi-class classification setting, where given an instance $x \in \mathcal{X}$, the goal is to classify it as one of the $K$ classes in the set $\mathcal{Y} \triangleq [K]$. Let $\mathcal{W}$ be the set of parameters that define the underlying classification models. For $w \in \mathcal{W}$, the associated classification model $f(\cdot; w) : \mathcal{X} \rightarrow \Delta_K$ maps the instance $x \in \mathcal{X}$ into the $K$-dimensional simplex $\Delta_K \subset \mathbb{R}^K$. Given $f(x; w)$, $x$ is classified as element of

http://www.kaggle.com/c/criteo-display-ad-challenge
We begin by defining churn as the expected disagreement between the predictions of two models \( \hat{Y}_{x,w} \), where \( y \) is the true label for \( x \). Let \( P_{X,Y} \) be the joint distribution over the instance and label pairs. We learn a classification model by minimizing the risk for some valid surrogate loss \( \ell \) of the misclassification error \( \ell_{01} : L(w) \triangleq E_{X,Y}[\ell(Y, f(X; w))] \). In practice, since we have only finite samples \( S \in (X \times Y)^n \), we minimize the corresponding empirical risk

\[
L(w; S) \triangleq \sum_{(x,y) \in S} \ell(y, f(x; w)) / |S|.
\]

### 2 Churn: measurement and analysis

In this section we define churn, and demonstrate its existence on CIFAR and ImageNet datasets. We also propose and measure alternative soft metrics to quantify churn, that mitigate the discontinuity of churn. Finally, we present a relation between churn and prediction confidences of the model.

We begin by defining churn as the expected disagreement between the predictions of two models [Cormier et al., 2016].

**Definition 1** (Churn between two models). Let \( w_1, w_2 \in W \) define classification models \( f(\cdot; w_1), f(\cdot; w_2) : X \to \Delta^K \), respectively. Then, the churn between the two models is

\[
\text{Churn}(w_1, w_2) = E_X[1_{\{\hat{Y}_{x,w_1} \neq \hat{Y}_{x,w_2}\}}] = P_X[\hat{Y}_{X,w_1} \neq \hat{Y}_{X,w_2}],
\]

where \( \hat{Y}_{x,w_1} \triangleq \arg\max_{j \in Y} f(x; w_1)_j \) and \( \hat{Y}_{x,w_2} \triangleq \arg\max_{j \in Y} f(x; w_2)_j \).

Note that if the models have perfect test accuracy, then their predictions always agree with the true label, which corresponds to zero churn. In practice, however, this is rarely the case. The following rather straightforward result shows that churn is upper bounded by the sum of the test error of the models. See Appendix B for the proof. We note that a similar result was shown in Theorem 1 of [Madani et al., 2004].

**Lemma 1.** Let \( P_{\text{Err},w_1} \triangleq P_{X,Y}[Y \neq \hat{Y}_{X,w_1}] \) and \( P_{\text{Err},w_2} \triangleq P_{X,Y}[Y \neq \hat{Y}_{X,w_2}] \) be the misclassification error for the models \( w_1 \) and \( w_2 \), respectively. Then, \( \text{Churn}(w_1, w_2) \leq P_{\text{Err},w_1} + P_{\text{Err},w_2} \).

Despite the worst-case bound in Lemma 1 imperfect accuracy does not preclude the absence of churn. As the best-case scenario, two imperfect models can agree on the predictions for each example (whether correct or incorrect), causing the churn to be zero. For example, multiple runs of a deterministic learning algorithm produce models with zero churn, independent of their accuracy.

This shows that, in general, one cannot infer churn from test accuracy, and understanding churn of an algorithm requires independent exploration.
2.1 Demonstration of churn

In principle, there are multiple sources of randomness in standard training procedures that make NNs susceptible to churn. We now verify this hypothesis by showing that, in practice, these sources indeed result in a non-trivial churn for NNs on standard image classification datasets.

Table 2 reports churn over CIFAR-10, CIFAR-100 and ImageNet, with ResNets [He et al., 2016a,b] as the underlying model architecture. As per the standard practice in the literature, we employ SGD with momentum and step-wise learning rate decay to train ResNets. Note that the models obtained in different runs indeed disagree in their predictions substantially. To measure if the disagreement comes mainly from misclassified examples, we measure churn on two slices of examples, correctly classified (Churn correct) and misclassified (Churn incorrect). We notice churn even among the examples that are correctly classified, though we see a relatively higher churn among the misclassified ones.

This raises two natural questions: (i) do the prediction probabilities differ significantly, or is the churn observed in Table 2 mainly an artifact of the \( \arg\max \) operation in (1), when faced with small variation in prediction probabilities across models?, and (ii) what causes such a high churn across runs? We address these questions in the following sections.

2.2 Surrogate churn

Churn in Table 2 could potentially be a manifestation of applying the \( \arg\max \) operation in (1), despite the prediction probabilities being close. To study this, we consider the following soft metric to measure churn, which takes the models’ entire prediction probability mass into account.

**Definition 2** (Surrogate churn between two models). Let \( f(\cdot; w_1), f(\cdot; w_2) : \mathcal{X} \rightarrow \Delta^K \) be two models defined by \( w_1, w_2 \in W \), respectively. Then, for \( \alpha \in \mathbb{R}^+ \), the surrogate churn between the models is

\[
S_{\text{Churn}}(\alpha) = \frac{1}{2} \mathbb{E}_X \left[ \left\| \left( \frac{f(X; w_1)}{\max f(X; w_1)} \right)^\alpha - \left( \frac{f(X; w_2)}{\max f(X; w_2)} \right)^\alpha \right\|_1 \right].
\]

As \( \alpha \rightarrow \infty \), this reduces to the standard Churn definition in (3). In Table 2 we measure \( S_{\text{Churn}} \) for \( \alpha = 1 \), which shows that even the distance between prediction probabilities is significant across runs. Thus, the churn observed in Table 2 is not merely caused by the discontinuity of the \( \arg\max \), but it indeed highlights the instability of model predictions caused by randomness in training.

2.3 What causes churn?

We now investigate the role played by randomness in initialization, mini-batch ordering, data augmentation, and non-determinism in the computation platform in causing churn. Even though these aspects are sources of randomness in training, they are not necessarily sources of churn. We experiment by holding some of these factors constant and measure the churn across 5 different runs. We report results in Table 1, where the first column gives the baseline churn with no factor held constant across runs.

Model initialization is a source of churn. Simply initializing weights from identical seeds (odd columns in Table 1) can decrease churn under most settings. Other sources of randomness include mini-batch ordering and dataset augmentation. We hold them constant by generating data with different mini-batch order and augmentation and storing it for all epochs. This ensures that the same datapoint is visited in order in different training runs. While fixing the data order alone does not seem to decrease churn for this model, combining it fixed initialization results in churn reduction. Note that these methods are considered only to understand the role of different components in churn, and in general are not always feasible for churn reduction in real applications.

Finally, there is churn resulting from an unavoidable source during training, the non-determinism in computing platforms used for training machine learning models, e.g., GPU/TPU [Morin and Willetts, 2020, PyTorch]...
The experiments in Table 1 were run on both CPU and GPU. On CPU we are able to achieve 0 churn by eliminating randomness from training algorithm. However on GPU, even when all other aspects of training are held constant (rightmost column), model weights diverge within 100 steps (across runs) and the final churn is significant. We verified that this is the sole source of non-determinism: models trained to 10,000 steps on CPUs under these settings had identical weights.

These experiments underscore the importance of developing and incorporating churn reduction strategies in training. Even with extreme measures to eliminate all sources of randomness, we continue to observe churn due to unavoidable hardware non-determinism.

2.4 Reducing churn: Relation to prediction probabilities

We now focus on the main objective of this paper – churn reduction in NNs. Many factors that have been shown to cause churn in § 2.3 are crucial for the good performance of NNs and thus cannot be controlled or eliminated without causing performance degradation. Moreover, controlling certain factors such as hardware non-determinism is extremely challenging, especially in the large scale distributed computing setup.

Towards reducing churn, we first develop an understanding of the relationship between the distribution of prediction probabilities of a model and churn. Intuitively, encouraging either larger prediction confidence or smaller variance across multiple training runs should result in reduced churn.

To formalize this intuition, let us consider the prediction confidence realized by the classification model $f(\cdot; w)$ on the instance $x \in X$:

$$
\gamma_{x;w} = f(x; w)\hat{y}_{x,w} - \arg\max_{p \neq \hat{y}_{x,w}} f(x; w)j,
$$

where $\hat{y}_{x,w}$ is the model prediction in [1]. Note that $\gamma_{x;w}$ denotes the difference between the probabilities of the most likely and the second most likely classes under the distribution $f(x; w)$, and is not the same as the standard multi-class margin [Koltchinskii et al., 2001]. It captures how confident the model $f(\cdot; w)$ is about its prediction $\hat{y}_{x,w}$, without taking the true label into account.

The following result relates the prediction confidence to churn. See Appendix B for the proof.

**Lemma 2.** Let $\gamma_{x;w_1}$ and $\gamma_{x;w_2}$ be the prediction confidences realized on $x \in X$ by the classification models $f(\cdot; w_1)$ and $f(\cdot; w_2)$, respectively. Then,

$$
\text{Churn}(w_1, w_2) = \mathbb{P}_X\{Y_{X;w_1} \neq Y_{X;w_2}\} \leq \mathbb{P}_X[D_{L1}(f(X; w_1), f(X; w_2)) > \min\{\gamma_{X;w_1}, \gamma_{X;w_2}\}],
$$

Here, $D_{L1}(f(x; w_1), f(x; w_2)) = \sum_{j \in Y} |f(x; w_1)j - f(x; w_2)j|$ measures the L1 distance. Lemma 2 establishes that, for a given instance $x$, the churn between two models $f(\cdot; w_1)$ and $f(\cdot; w_2)$ becomes less likely as their confidences $\gamma_{x;w_1}$ and $\gamma_{x;w_2}$ increase. Similarly, the churn becomes smaller when the difference between their prediction probabilities, $D_{L1}(f(x; w_1), f(x; w_2))$, decreases.

3 Regularized co-distillation for churn reduction

In this section we present our approach for churn reduction. Motivated by Lemma 2, we consider an approach with two complementary techniques for churn reduction: 1) We first propose entropy based regularizers that encourage solutions $w \in \mathcal{W}$ with large prediction confidence $\gamma_{x;w}$ for each instance $x$. 2) We next employ co-distillation approach with novel design choices that simultaneously trains two models while minimizing the distance between their prediction probabilities.

Note that the entropy regularizers themselves cannot actively enforce alignment between the prediction probabilities across multiple runs as the resulting objective does not couple multiple models together. On the other hand, the co-distillation in itself does not affect the prediction confidence of the underlying models (as verified in Figure 3). Thus, our combined approach promotes both large model prediction confidence and small variance in prediction probabilities across multiple runs.

6
3.1 Minimum entropy regularizers

Aiming to increase the prediction confidences of the trained model \( \{ \gamma_{x;w} \}_{x \in \mathcal{X}} \), we propose novel training objectives that employ one of two possible regularizers based on: (1) entropy of the model prediction probabilities; and (2) negative symmetric KL divergence between the model prediction probabilities and the uniform distribution. Both regularizers encourage the prediction probabilities to be concentrated on a small number of classes, and increase the associated prediction confidence.

**Entropy regularizer.** Recall that the standard training minimizes the risk \( L(w) \). Instead, for \( \alpha \in [0, 1] \) and \( \mathcal{S} = \{(x_i, y_i)\}_{i \in [n]} \), we propose to minimize the following regularized objective to increase the prediction confidence of the model \[ L_{\text{entropy}}(w; \mathcal{S}) = (1 - \alpha) \cdot L(w; \mathcal{S}) + \alpha \cdot \frac{1}{n} \sum_{i \in [n]} H(f(x_i, w)), \] (6)

where \( H(f(x; w)) = -\sum_{j \in [K]} f(x; w)_j \log f(x; w)_j \) denotes the entropy of predictions \( f(x; w) \).

**Symmetric KL divergence regularizer.** Instead of encouraging the low entropy for the prediction probabilities, we can alternatively maximize the distance of the prediction probability mass function from the uniform distribution as a regularizer to enhance the prediction confidence. In particular, we utilize the symmetric KL divergence as the distance measure. Let \( \text{Unif} \in \Delta_K \) be the uniform distribution. Thus, given \( n \) samples \( \mathcal{S} = \{(x_i, y_i)\}_{i \in [n]} \), we propose to minimize

\[ L_{\text{SKL}}(w; \mathcal{S}) = (1 - \alpha) \cdot L(w; \mathcal{S}) - \alpha \cdot \frac{1}{n} \sum_{i \in [n]} \text{SKL}(f(x_i; w), \text{Unif}), \] (7)

where \( \text{SKL}(f(x; w), \text{Unif}) = \text{KL}(f(x; w)||\text{Unif}) + \text{KL}(\text{Unif}||f(x; w)) \).

As discussed in the beginning of the section, the intuition behind utilizing these regularizers is to encourage spiky prediction probability mass functions, which lead to higher prediction confidence. The following result supports this intuition in the binary classification setting. See Appendix E for the proof. As for multi-class classification, we empirically verify that the proposed regularizers indeed lead to increased prediction confidences (cf. Figure 3).

**Theorem 3.** Let \( f(\cdot; w) \) and \( f(\cdot; w') \) be two binary classification models. For a given \( x \in \mathcal{X} \), if we have \( H(f(x; w)) \leq H(f(x; w')) \) or \( \text{SKL}(f(x; w)) \geq \text{SKL}(f(x; w')) \), then \( \gamma_{x;w} \geq \gamma_{x;w'} \).

Note that the effect of these regularizers is different from increasing the temperature in softmax while computing \( f(x; w) \). Similar to max entropy regularizers [Pereyra et al. 2017], they are independent of the label, a crucial difference that allows them to reduce churn even among misclassified examples.

3.2 Co-distillation

As the second measure for churn reduction, we now focus on designing training objectives that minimize the variance among the prediction probabilities for the same instance across multiple runs of the learning algorithm. Towards this, we consider novel variants of co-distillation approach [Anil et al., 2018]. In particular, we employ co-distillation by using symmetric KL divergence (Co-distill_{SKL}), with a linear warm-up, to penalize the prediction distance between the models instead of the popular step-wise cross entropy loss (Co-distill_{CE}) used in [Anil et al., 2018] (see § C). We motivate the proposed objective for reducing churn using Lemma 2.

Recall from Lemma 2 that, for a given instance \( x \), churn across two models \( f(\cdot; w_1) \) and \( f(\cdot; w_2) \) decreases as the distance between their prediction probabilities \( D_{\text{L}_1}(f(x; w_1), f(x; w_2)) \) becomes smaller. Motivated by...
We conduct experiments on 5 different datasets, CIFAR-10, CIFAR-100, ImageNet, SVHN, and iNaturalist. In Table 2, we present the accuracy and churn of models trained with the minimum SKL where $\alpha$ varies, potentially due to the discontinuous nature of the churn. Also note that the proposed methods reduce ensembling. We also compare with the ensembling-distillation approach [Hinton et al., 2015] in Table 2, the accuracy, showing their utility beyond churn reduction.

For problems with a large number of outputs, e.g. ImageNet, it is not required to penalize all the predictions to reduce churn. Recall that prediction confidence is only a function of the top two prediction probabilities. Hence, on ImageNet, we consider the top $k$ predictions, with $k = 10$.

### 4 Experiments

We conduct experiments on 5 different datasets, CIFAR-10, CIFAR-100, ImageNet, SVHN, and iNaturalist. We use LeNet5 for experiments on SVHN, ResNet-56 for experiments on CIFAR-10 and CIFAR-100, and ResNet-v2-50 for experiments on ImageNet and iNaturalist. We use the cross entropy loss and the Momentum optimizer. We use the same hyperparameters for all the experiments on a dataset. We emphasize that the hyper-parameters are chosen to achieve the best performance for the baseline models on each of the datasets. We do not change them for our experiments with different methods. We only vary the relevant hyper-parameter for the method, e.g. $\alpha$ of the entropy regularizer, and report the results. For complete details, including the range of hyper-parameters considered, we refer to the Appendix A.

### Top$_k$ regularizer

For problems with a large number of outputs, e.g. ImageNet, it is not required to penalize all the predictions to reduce churn. Recall that prediction confidence is only a function of the top two prediction probabilities. Hence, on ImageNet, we consider the top $k$ variants of the proposed regularizers, and penalize the entropy/SKL only on the top $k$ predictions, with $k = 10$.

### Accuracy and churn

In Table 2 we present the accuracy and churn of models trained with the minimum entropy regularizers, co-distillation and their combination. For each dataset we report the values for the best $\alpha$ and $\beta$. We notice that our proposed methods indeed reduce the churn and Schurn. While both minimum entropy regularization and co-distillation are consistently effective in reducing Schurn, their effect on churn varies, potentially due to the discontinuous nature of the churn. Also note that the proposed methods reduce churn both among the correctly and incorrectly classified examples. Our co-distillation proposal, Co-distill$_{\text{SKL}}$, consistently showed a significant reduction in churn, and has better performance than Co-distill$_{\text{CE}}$ [Anil et al., 2018] that is based on the cross-entropy loss, showing the importance of choosing the right objective for reducing churn. We present additional comparison in Figure 3 showing churn and Top-1 error on ImageNet, computed for different values of $\beta$ (cf. 9). Finally, we achieve an even further reduction in churn by the combined approach of entropy regularized co-distillation. Interestingly, the considered methods also improve the accuracy, showing their utility beyond churn reduction.

### Ensembling

We also compare with the ensembling-distillation approach [Hinton et al., 2015] in Table 2,
We next report results of our ablation study on the entropy (Ablation). where we use a 2 teacher ensemble for distillation. We show that proposed methods consistently outperform complementary approaches. Note that for co-distillation we measure churn of a single model (e.g. Co-distill) offers the best way to reduce churn, improving over the ensembling-distillation and Co-distillCE approaches. Additional, these methods also improve the accuracy. Finally combining the entropy regularizer with Co-distillSKL offers the best way to reduce churn, improving over the ensembling-distillation and Co-distillCE approaches. Note that for co-distillation we measure churn of a single model (e.g. f: w1) in eq (9) across independent training runs.

Table 2: Estimate of Churn (cf. (3)) and SChurn (cf. (4)) on the test sets. For each setting, we report the mean and standard deviation over 10 independent runs, with random initialization, mini-batches and data-augmentation. We report the values corresponding to the smallest churn for each method (see Table 3 in §A for the exact parameters). We boldface the best results in each column. First we notice that both the proposed methods are effective at reducing churn and Schurn, with Co-distillSKL showing significant reduction in churn. Additionally, these methods also improve the accuracy. Finally combining the entropy regularizer with Co-distillSKL offers the best way to reduce churn, improving over the ensembling-distillation and Co-distillCE approaches. Note that for co-distillation we measure churn of a single model (e.g. f: w1) in eq (9) across independent training runs.

Figure 2: ImageNet ablation study: We plot the effect of the entropy regularizer (top10), for varying α, and Co-distillSKL for varying β, on the prediction entropy, accuracy and churn. These plots show the complementary nature of these methods in reducing churn. While entropy_regularizer reduces churn by reducing the prediction entropy, Co-distillSKL reduces churn by improving the agreement between two models, hence increasing the entropy.

where we use a 2 teacher ensemble for distillation. We show that proposed methods consistently outperform ensembling-distillation approach, despite having a lower training cost.

Ablation. We next report results of our ablation study on the entropy (top10) regularizer coefficient α, and the Co-distillSKL coefficient β in Figure 2. While both methods improve accuracy and churn, the prediction entropy shows different behavior between these methods. While entropy regularizers improve churn by
Figure 3: ImageNet: Left - effect of the entropy regularizer and our proposed variant of co-distillation, Co-distill\textsubscript{SKL}, on the prediction confidence. Right - comparison with Co-distill\textsubscript{CE} \cite{Aniletal2018}. We plot the trade-off between accuracy and churn for Co-distill\textsubscript{CE} and Co-distill\textsubscript{SKL} by varying $\beta$. The plot clearly shows that the proposed variant achieves a better tradeoff, compared to Co-distill\textsubscript{CE}.

| Dataset | Method            | Weight decay $= 0$ | Weight decay $= 0.0001$ | Weight decay $= 0$ | Weight decay $= 0.0001$ |
|---------|-------------------|--------------------|-------------------------|-------------------|-------------------------|
| CIFAR-10| Baseline          | 91.62 ± 0.2        | 91.97 ± 0.11            | 8.4 ± 0.21        | 5.72 ± 0.18             |
|         | Entropy (this paper) | 91.56 ± 0.26     | 94.05 ± 0.18            | 8.45 ± 0.25       | 5.59 ± 0.21             |
|         | SKL (this paper)  | 91.91 ± 0.22       | 93.75 ± 0.13            | 7.84 ± 0.24       | 5.79 ± 0.18             |
|         | Co-distill\textsubscript{SKL} (this paper) | 92.1 ± 0.31    | 94.63 ± 0.15            | 6.74 ± 0.32       | 4.29 ± 0.14             |
| CIFAR-100| Baseline        | 68.6 ± 0.21        | 73.26 ± 0.22            | 32.23 ± 0.45      | 26.77 ± 0.26            |
|          | Entropy (this paper) | 68.41 ± 0.33     | 73.24 ± 0.29            | 32.02 ± 0.42      | 26.55 ± 0.26            |
|          | SKL (this paper) | 69.02 ± 0.33       | 73.35 ± 0.3             | 31.22 ± 0.38      | 25.62 ± 0.38            |
|          | Co-distill\textsubscript{SKL} (this paper) | 72.29 ± 0.42    | 76.58 ± 0.16            | 23.14 ± 0.83      | 17.70 ± 0.33            |

Table 3: Weight decay ablation studies. Similar to Table 2, we provide results on accuracy and churn for baseline and the proposed approaches, with and without weight decay. We notice that the proposed approaches improve churn both with and without weight decay.

| Method | Training cost | CIFAR-10 - ECE (×1e-2) | CIFAR-100 - ECE (×1e-2) | ImageNet - ECE (×1e-2) |
|--------|---------------|-------------------------|-------------------------|------------------------|
| Baseline | 1x            | 4.04 ± 0.13             | 15.23 ± 0.32            | 3.71 ± 0.12             |
| Entropy (this paper) | 1x            | 4.19 ± 0.18             | 17.43 ± 0.26            | 6.17 ± 0.09             |
| SKL (this paper) | 1x            | 5.41 ± 0.12             | 21.82 ± 0.16            | 6.49 ± 0.12             |
| 2-Ensemble distill \cite{Hintonetal2015} | 3x            | 3.83 ± 0.05             | 13.85 ± 0.23            | 2.14 ± 0.1             |
| Co-distill\textsubscript{CE} \cite{Aniletal2018} | 2x            | 4.13 ± 0.12             | 15.86 ± 0.13            | 11.97 ± 0.07            |
| Co-distill\textsubscript{SKL} (this paper) | 2x            | 3.88 ± 0.15             | 11.39 ± 0.15            | 2.44 ± 0.09             |
| +Entropy (this paper) | 2x            | 3.94 ± 0.09             | 11.55 ± 0.23            | 3.89 ± 0.39             |

Table 4: Expected Calibration Error. We compute the Expected Calibration Error (ECE) \cite{Guoetal2017} to evaluate the effect on calibration of logits by the churn reduction methods considered in this paper, for different datasets. We report ECE for the predictions of the models used to report accuracy and churn in Table 2. We note that while the minimum entropy regularizers, predictably, increase the calibration error, our combined approach with co-distillation results in calibration error competitive with 2-ensemble distillation method.

reducing the entropy, co-distillation reduces churn by reducing the prediction distance between two models, resulting in an increase in entropy. This complementary nature explains the advantage in combining these two methods (cf. Table 2).

We next present ablation studies on weight decay regularization in Table 3 showing that the proposed approaches improve churn on models trained both with and without weight decay.

5 Discussion

Connection to label smoothing and calibration. Max entropy regularizers, such as label smoothing, are often used to reduce prediction confidence \cite{Pereyraetal2017, Mulleretal2019} and provide better prediction calibration. The minimum entropy regularizers studied in this paper have the opposite effect and
increase the prediction confidence, whereas co-distillation reduces the prediction confidences. To study this more concretely we measure the effect of churn reduction methods on the calibration.

We compute Expected Calibration Error (ECE) \cite{Guo2017} for methods considered in this paper and report the results in Table \ref{table:results}. We notice that the minimum entropy regularizers, predictably, increase the calibration error, whereas the propose co-distillation approach (Co-distill\textsubscript{SKL}) significantly reduces the calibration error. We notice that our joint approach is competitive with the ensemble distillation approach on CIFAR datasets but incurs higher error on ImageNet. Developing approaches that jointly optimize for churn and calibration is an interesting direction of future work.

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A Experimental setup

Architecture: For our experiments we use the standard image classification datasets CIFAR and ImageNet. For our experiments with CIFAR, we use ResNet-32 and ResNet-56 architectures, and for ImageNet we use ResNet-v2-50. These architectures have the following configuration in terms of $(n_{layer}, n_{filter}, stride)$, for each ResNet block:

- ResNet-32- $[(5, 16, 1), (5, 32, 2), (5, 64, 2)]$
- ResNet-56- $[(9, 16, 1), (9, 32, 2), (9, 64, 2)]$
- ResNet-v2-50- $[(3, 64, 1), (4, 128, 2), (6, 256, 2), (3, 512, 2)]$,

where ‘stride’ refers to the stride of the first convolution filter within each block. For ResNet-v2-50, the final layer of each block has $4 * n_{filter}$ filters. We use L2 weight decay of strength $1e^{-4}$ for all experiments.

Learning rate and Batch size: For our experiments with CIFAR, we use SGD optimizer with a 0.9 Nesterov momentum. We use a linear learning rate warmup for first 15 epochs, with a peak learning rate of 1.0. We use a stepwise decay schedule, that decays learning rate by a factor of 10, at epoch numbers 200, 300 and 400. We train the models for a total of 450 epochs. We use a batch size of 1024.

For the ImageNet experiments, we use SGD optimizer with a 0.9 momentum. We use a linear learning rate warmup for first 5 epochs, with a peak learning rate of 0.8. We again use a stepwise decay schedule, that decays learning rate by a factor of 10, at epoch numbers 30, 60 and 80. We train the models for a total of 90 epochs. We use a batch size of 1024.

Data augmentation: We use data augmentation with random cropping and flipping.

Parameter ranges: For our experiments with the min entropy regularizers, we use $\alpha \in [0.05, 0.5]$, in 0.05 increments and report the $\alpha$ corresponding to best churn in Table 2. For our experiments with the co-distillation approach, we use $\beta \in [0.01, 0.08]$, in 0.01 increments and report the $\beta$ corresponding to best churn in Table 2.
Table 5: In this table we list the hyper-parameter values corresponding to the settings for the results in Table 2. For each method we experiment with a range of hyper-parameters, and 10 independent runs, as described in the Section A and report the results for the setting with the best performance.

For our experiments on entropy regularized co-distillation, we use a linear warmup of the regularizer coefficient. We use the same range for $\alpha$ as described above, and use only the best $\beta$ value from the earlier experiments.

Finally, we run our experiments using TPUv3. Experiments on CIFAR datasets finish in an hour, experiments on ImageNet take around 6-8 hours.

Hyper parameters for Table 2: Finally we list in Table 5 the best hyperparameters used to obtain the results in Table 2. For reference we also include the accuracy and the churn again for all methods.
B Proofs

Proof of Lemma 2. Recall from Definition 1 that
\[
\text{Churn}(w_1, w_2) = \mathbb{P}_X[\hat{Y}_{X, w_1} \neq \hat{Y}_{X, w_2}] = \mathbb{P}_{X,Y}[\hat{Y}_{X, w_1} \neq \hat{Y}_{X, w_2}]
\]
\[
= \mathbb{P}_{X,Y}[\{\hat{Y}_{X, w_1} = Y, \hat{Y}_{X, w_2} \neq Y\} \cup \{\hat{Y}_{X, w_1} \neq Y, \hat{Y}_{X, w_2} \neq Y\}]
\]
\[
\leq \mathbb{P}_X[\hat{Y}_{X, w_1} = Y, \hat{Y}_{X, w_2} \neq Y] + \mathbb{P}[\hat{Y}_{X, w_1} \neq Y, \hat{Y}_{X, w_2} \neq Y]
\]
\[
\leq \mathbb{P}[\hat{Y}_{X, w_2} \neq Y] + \mathbb{P}[\hat{Y}_{X, w_1} \neq Y]
\]
\[
= \mathbb{P}_{\text{Err}, w_2} + \mathbb{P}_{\text{Err}, w_1},
\]
where (i) and (ii) follow from the union bound and the fact that \(\mathbb{P}[A] \leq \mathbb{P}[B]\) whenever \(A \subseteq B\), respectively.

Proof of Lemma 2. Note that, for any \(j \neq \hat{y}_{x, w_1}\),
\[
f(x; w_2)\hat{y}_{x, w_1} - f(x; w_2)j
\]
\[
= f(x; w_2)\hat{y}_{x, w_1} - f(x; w_1)\hat{y}_{x, w_1} + f(x; w_1)\hat{y}_{x, w_1} - f(x; w_1)j
\]
\[
\geq \gamma_{x, w_1} - \sum_{j \neq y} |f(x; w_1)j - f(x; w_2)j|
\]
\[
= \gamma_{x, w_1} - D_{L_1}(f(x; w_1), f(x; w_2)).
\]
Similarly, for any \(j \neq \hat{y}_{x, w_2}\), we can establish that
\[
f(x; w_1)\hat{y}_{x, w_2} - f(x; w_1)j \geq \gamma_{x, w_2} - D_{L_1}(f(x; w_1), f(x; w_2)).
\]

Note that experiencing churn between the two models on \(x\) is equivalent to
\[
\{\hat{y}_{x, w_1} \neq \hat{y}_{x, w_2}\} \subseteq \left\{ \exists j \neq \hat{y}_{x, w_1} : f(x; w_2)\hat{y}_{x, w_1} < f(x; w_2)j \right\} \cup \left\{ \exists j \neq \hat{y}_{x, w_2} : f(x; w_1)\hat{y}_{x, w_2} < f(x; w_1)j \right\}
\]
\[
\subseteq \left\{ D_{L_1}(f(x; w_1), f(x; w_2)) > \gamma_{x, w_1} \right\} \cup \left\{ D_{L_1}(f(x; w_1), f(x; w_2)) > \gamma_{x, w_2} \right\},
\]
where (i) follows from (11) and (12). Now, (13) implies that
\[
\mathbb{P}_X[\hat{Y}_{X, w_1} \neq \hat{Y}_{X, w_2}] \leq \mathbb{P}_X[D_{L_1}(f(X; w_1), f(X; w_2)) \geq \min\{\gamma_{X, w_1}, \gamma_{X, w_2}\}].
\]

Proof of Theorem 3. Let the prediction for a given \(x\) be \(p = f(x; w)\). W.L.O.G. let \(p \geq 1 - p\). The prediction confidence is then
\[
\gamma_{x, w} = p - (1 - p) = 2p - 1.
\]

Entropy case. Now we can write entropy in terms of the prediction confidence (cf. (15))
\[
H(f(x; w)) = -p \log(p) - (1 - p) \log(1 - p)
\]
\[
= -\frac{(1 + \gamma_{x, w})}{2} \log \frac{1 + \gamma_{x, w}}{2} - \frac{(1 - \gamma_{x, w})}{2} \log \frac{1 - \gamma_{x, w}}{2}
\]
\[
= g(\gamma_{x, w}).
\]
Now the gradient of \(g(\cdot)\) is \(\nabla_{\gamma_{x, w}} g(\gamma_{x, w}) = \frac{1}{2} \log \left( \frac{1 - \gamma_{x, w}}{1 + \gamma_{x, w}} \right)\), which is less than 0 for \(\gamma_{x, w} \in [0, 1]\). Hence, the function \(g(\gamma_{x, w})\) is a decreasing function for inputs in range \([0, 1]\). Hence, if \(g(\gamma_{x, w'}) \geq g(\gamma_{x, w})\) implies \(\gamma_{x, w'} \leq \gamma_{x, w}\).
Symmetric-KL divergence case. Recall that
\[
\text{SKL}(f(x; w), \text{Unif}) = \text{KL}(f(x; w)||\text{Unif}) + \text{KL}(\text{Unif}||f(x; w))
\]
\[
= \sum_{j \in [K]} (f(x; w)_j - 1/K) \cdot \log (K \cdot f(x; w)_j)
\]
\[
= \sum_{j} f(x; w)_j \cdot \log (f(x; w)_j) - \frac{1}{K} \log (f(x; w)_j).
\]
For binary classification this reduces to,
\[
\text{SKL}(f(x; w), \text{Unif}) = -\frac{1}{2} \log(p(1 - p)) - H(p).
\]
By using (15) and (16), we can rewrite this function in terms of \(\gamma_{x,w}\) as:
\[
\text{SKL}(f(x; w), \text{Unif}) = -\frac{1}{2} \log(p(1 - p)) - H(p)
\]
\[
= -\frac{1}{2} \log \left( \frac{1 + \gamma_{x,w}}{2} \cdot \frac{1 - \gamma_{x,w}}{2} \right) - g(\gamma_{x,w}) = -\frac{1}{2} \log \left( 1 - \frac{\gamma_{x,w}^2}{4} \right) - g(\gamma_{x,w}).
\]
Now notice that both the above terms are an increasing function of \(\gamma_{x,w}\), as log is an increasing function, and \(g(\gamma_{x,w})\) is a decreasing function. Hence \(\text{SKL}(f(x; w), \text{Unif}) \geq \text{SKL}(f(x; w'), \text{Unif})\) implies \(\gamma_{x,w} \geq \gamma_{x;w'}\).

C Design choices in the proposed variant of co-distillation

Here, we discuss two important design choices that are crucial for successful utilization of co-distillation framework for churn reduction while also improving model accuracy.

Joint vs. independent updates. [Anil et al. 2018] consider co-distillation with independent updates for the participating models. In particular, with two participating models, this corresponds to independently solving the following two sub-problems during the \(t\)-th step.

\[
w_1^t = \arg \min_{w_1 \in \mathcal{W}} \frac{L(w_1; \mathcal{S}) + \beta \cdot \frac{1}{n} \sum_{i \in [n]} \text{KL}(f(x_i; w_2^T)||f(x_i; w_1))}{f(x_i; w_1)}
\]
\[
w_2^t = \arg \min_{w_2 \in \mathcal{W}} \frac{L(w_2; \mathcal{S}) + \beta \cdot \frac{1}{n} \sum_{i \in [n]} \text{KL}(f(x_i; w_1^T)||f(x_i; w_2))}{f(x_i; w_2)},
\]
where \(w_1^{t-T}\) and \(w_2^{t-T}\) corresponds to earlier checkpoints of two models being used to compute the model disagreement loss component at the other model. Note that since \(w_2^{t-T}\) and \(w_1^{t-T}\) are not being optimized in \((17a)\) and \((17b)\), respectively. Thus, for each model, these objectives are equivalent to regularizing its empirical loss via a cross-entropy terms that aims to align its prediction probabilities with that of the other model. In particular, the optimization steps in \((17)\) are equivalent to

\[
w_1^t = \arg \min_{w_1 \in \mathcal{W}} \frac{L(w_1; \mathcal{S}) + \beta \cdot \frac{1}{n} \sum_{i \in [n]} H(f(x_i; w_2^T), f(x_i; w_1))}{f(x_i; w_1)}
\]
\[
w_2^t = \arg \min_{w_2 \in \mathcal{W}} \frac{L(w_2; \mathcal{S}) + \beta \cdot \frac{1}{n} \sum_{i \in [n]} H(f(x_i; w_1^T), f(x_i; w_2))}{f(x_i; w_2)},
\]
where \(H(f(x; w_1), f(x; w_2)) = -\sum_{j} f(x; w_1)_j \log f(x; w_2)_j\) denotes the cross-entropy between the probability mass functions \(f(x; w_1)\) and \(f(x; w_2)\).

In our experiments, we verify that this independent updates approach leads to worse results as compared to jointly training the two models using the objective in \((9)\).
Deferred model disagreement loss component in co-distillation. In general, implementing co-distillation approach by employing the model disagreement based loss component (e.g., $\text{SKL}(f(x; w_1), f(x; w_2))$ in our proposal) from the beginning leads to sub-optimal test accuracy as the models are very poor classifiers at the initialization. As a remedy, Anil et al. [2018] proposed a step-wise ramp up of such loss component, i.e., a time-dependent $\beta(t)$ such that $\beta(t) > 0$ iff $t > t_0$, with $t_0$ burn-in steps. Besides step-wise ramp up, we experimented with linear ramp-up, i.e., $\beta_t = \min\{c \cdot t, \beta\}$ and observed that linear ramp up leads to better churn reduction. We believe that, for churn reduction, it’s important to ensure that the prediction probabilities of the two models start aligning before the model diverges too far during the training process.

D Combined approach: co-distillation with entropy regularizer

In this paper, we have considered two different approaches to reduce churn, involving minimum entropy regularizers and co-distillation framework, respectively. This raises an important question if these two approaches are redundant. As shown in Figures 3, 4, and 5 this is not the case. In fact, these two approaches are complementary in nature and combining them together leads to better results in term of both churn and accuracy.

Note that the minimum entropy regularizers themselves cannot actively enforce alignment between the prediction probabilities across multiple runs as the resulting objective does not couple multiple models together. On the other hand, as verified in Figure 3 the co-distillation framework in itself does not affect the prediction confidence of the underlying models. Thus, both these approaches can be combined together to obtain the following training objective which promotes both large model prediction confidence and small variance in prediction probabilities across multiple runs.

$$L_{\text{Combined}}^{\text{Co-distill-SKL}}(w_1, w_2; S) = L_{\text{Co-distill-SKL}}(w_1, w_2; S)(w_1, w_2; S) + \alpha \cdot \text{EReg}(w_1, w_2; S),$$

where

$$\text{EReg}(w_1, w_2; S) = \frac{1}{n} \sum_{i \in [n]} H(f(x_i, w_1)) + H(f(x_i, w_2))$$

or

$$\text{EReg}(w_1, w_2; S) = -\frac{1}{n} \sum_{i \in [n]} \left( \text{SKL}(f(x_i; w_1), \text{Unif}) + \text{SKL}(f(x_i; w_2), \text{Unif}) \right).$$

E Additional experimental results

In this section we present additional experimental results.

Churn examples. We present additional examples illustrating churn in ResNet-v2-50 models trained on ImageNet in Figure 4.

Figure 4: ImageNet trained on ResNet-v2-50: Sample predictions from 5 independent training runs and the prediction probabilities. True label is highlighted in the predictions. Despite all the runs achieving a top-1 accuracy of around 76%, individual predictions of these models can vary dramatically, highlighting the necessity of having methods with more reproducible predictions and less churn. Note that even when the independent runs predict the true label, their prediction probabilities vary significantly.
We notice that proposed approaches are either competitive or improve churn over 2-ensemble method, while Ablation on CIFAR-100. Next we present our ablation studies, similar to results in Figure 2, for CIFAR-100. Table 6: Similar to Table 2, we provide results on accuracy and churn for 2-ensemble and proposed approaches. We notice that the proposed approach with entropy regularizer and co-distillation achieve similar churn. While the regularizer reduces churn, by reducing the prediction entropy, Co-distill_SKL reduces churn by improving the agreement between two models, hence increasing the entropy.

| Dataset       | Method          | Training cost | Inference cost | Accuracy | Churn (%) | SChurn (%) | Churn correct | Churn incorrect |
|---------------|-----------------|---------------|----------------|----------|-----------|------------|---------------|----------------|
| CIFAR-10      | Baseline        | 1x            | 1x             | 73.26±0.22 | 26.77±0.26 | 37.19±0.35 | 11.43±0.26   | 68.77±0.72    |
| ResNet-56     | 2-Ensemble      | 2x            | 2x             | 76.28±0.24 | 20.23±0.29 | 35.91±0.33 | 8.26±0.25    | 59.52±0.83    |
|               | Co-distill [Anil et al., 2018] | 3x | 1x | 76.27±0.25 | 18.86±0.26 | 25.43±0.23 | 7.79±0.23 | 54.3±0.86 |
|               | Co-distill [Anil et al., 2018] | 2x | 1x | 75.11±0.17 | 19.55±0.27 | 25.03±0.27 | 9.98±0.97 | 48.8±2.84 |
|               | Co-distill [Anil et al., 2018] | 2x | 1x | 76.59±0.16 | 17.70±0.33 | 24.99±0.31 | 9.08±0.38 | 45.98±2.98 |
|               | Entropy (this paper) | 2x | 1x | 76.35±0.20 | 17.09±0.3 | 24.06±0.28 | 7.2±0.26 | 40.4±2.11 |
| ResNet-56     | Baseline        | 1x            | 1x             | 76.0±0.11  | 15.22±0.16 | 35.01±0.24 | 5.87±0.11 | 44.77±0.46 |
|               | 2-Ensemble      | 2x            | 2x             | 77.24±0.09 | 11.13±0.13 | 27.71±0.18 | 4.2±0.11 | 34.8±0.43 |
|               | Co-distill [Anil et al., 2018] | 3x | 1x | 77.83±0.06 | 12.92±0.14 | 34.02±0.2 | 4.92±0.11 | 38.04±0.79 |
|               | Co-distill [Anil et al., 2018] | 2x | 1x | 76.12±0.08 | 11.62±0.21 | 18.38±0.34 | 4.97±0.36 | 32.67±1.45 |
|               | Co-distill [Anil et al., 2018] | 2x | 1x | 76.74±0.06 | 11.45±0.13 | 28.60±0.26 | 5.11±0.36 | 32.45±1.45 |
|               | Entropy (this paper) | 2x | 1x | 76.96±0.02 | 11.88±0.36 | 22.02±1.01 | 4.32±0.32 | 32.89±1.15 |

Table 6: Similar to Table 2 we provide results on accuracy and churn for 2-ensemble and proposed approaches. We notice that proposed approaches are either competitive or improve churn over 2-ensemble method, while keeping the inference costs low.

Ablation on CIFAR-100. Next we present our ablation studies, similar to results in Figure 2 for CIFAR-100. In Figure 5 we plot the mean prediction entropy, accuracy and churn, for the proposed SKL regularizer (7) and the co-distillation approach (9), for varying \( \alpha \) and \( \beta \), respectively. Similar to Figure 2 the plots show the effectiveness of the proposed approaches in reducing churn, while improving accuracy.

E.1 2-Ensemble

In Table 6 we provide the results for 2-ensemble models and compare with distillation and co-distillation approaches. We notice that the proposed approach with entropy regularizer and co-distillation achieve similar or better churn, with lower inference costs. However the the ensemble models achieve better accuracy on certain datasets, and could be an alternative in settings where higher inference costs are acceptable.

F Loss landscape: Entropy regularization vs. temperature scaling

Figure 6 visualises the entropy regularised loss (6) in binary case. We do so both in terms of the underlying loss operating on probabilities (i.e., log-loss), and the loss operating on logits with an implicit transformation via the sigmoid (i.e., the logistic loss). Here, the regularised log-loss is \( \ell: [0, 1] \rightarrow \mathbb{R}_+ \), where \( \ell(p) = (1 - \alpha) \cdot - \log p + \alpha \cdot H_{\text{bin}}(p) \), for binary entropy \( H_{\text{bin}} \). Similarly, the logistic loss is \( \ell: \mathbb{R} \rightarrow \mathbb{R}_+ \), where \( \ell(f) = (1 - \alpha) \cdot - \log \sigma(f) + \alpha \cdot H_{\text{bin}}(\sigma(f)) \), for sigmoid \( \sigma(\cdot) \). The effect of increasing \( \alpha \) is to dampen
the loss for high-confidence predictions – e.g., for the logistic loss, either very strongly positive or negative predictions incur a low loss. This encourages the model to make confident predictions.

Figure 7, by contrast, illustrates the effect of changing the temperature $\tau$ in the softmax. Temperature scaling is a common trick used to decrease classifier confidence. This also dampens the loss for high-confidence predictions. However, with strongly negative predictions, one still incurs a high loss compared to strongly positive predictions. This is in contrast to the more aggressive dampening of the loss as achieved by the entropy regularised loss.

Figure 6: Visualisation of entropy regularised loss (eq. (6)) in binary case. On the left panel is the regularised log-loss $(1 - \alpha) \cdot - \log p + \alpha \cdot H_{\text{bin}}(p)$, which accepts a probability in $[0, 1]$ as input. On the right panel is the logistic loss $(1 - \alpha) \cdot - \log \sigma(f) + \alpha \cdot H_{\text{bin}}(\sigma(f))$, which accepts a score in $\mathbb{R}$ as input and passes it through sigmoid $\sigma(\cdot)$ to get a probability estimate.

Figure 7: Visualisation of temperature scaling on binary logistic lau. We plot $- \log \sigma(f/\tau)$ for varying temperature parameter $\tau$. 