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To cite this version:
Norbert Mahouton, Pascal Dkengne Sielenou. Extremum conditions for functionals involving higher derivatives of several variable vector valued functions. 2022. hal-03557517

HAL Id: hal-03557517
https://inria.hal.science/hal-03557517
Preprint submitted on 4 Feb 2022

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Extremum conditions for functionals involving higher derivatives of several variable vector valued functions

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Abstract
This paper addresses both necessary and relevant sufficient extremum conditions for a variational problem defined by a smooth Lagrangian, involving higher derivatives of several variable vector valued functions. A general formulation of first order necessary extremum conditions for variational problems with (or without) constraints is given. Global Legendre second order necessary extremum conditions are provided as well as new general explicit formula for second order sufficient extremum condition which does not require the notion of conjugate points as in the Jacobi sufficient condition.

AMS Subject Classification: 49-01, 49J10, 49J40, 35A40, 35A15.
Keywords: Variational problems, critical points, extremum conditions.

1 Introduction
The calculus of variations encompasses a very broad range of mathematical applications. The methods of variational analysis can be applied to an enormous variety of physical systems, whose equilibrium configurations inevitably minimize or maximize a suitable functional which typically represents the potential energy of the system. The critical functions

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are characterized as solutions to a system of partial differential equations, known as the Euler-Lagrange equations associated with the variational principle. Each solution to the problem specified by the Euler-Lagrange equations subject to appropriate boundary conditions is thus a candidate for extrema of the functional defining the variational problem. In many applications, the Euler-Lagrange boundary value problem suffices to single out the physically relevant solutions, and one does not need to press onto the considerably more difficult second variation.

In general, the solutions to the Euler-Lagrange boundary value problem are critical functions for the functional defining the variational problem, and hence include all (smooth) local and global extrema. The determination of which solutions are genuine minima or maxima requires further analysis of the positivity properties of the second variation. Indeed, as stated in [8], a complete analysis of the positive definiteness of the second variation of multi-dimensional variational problems is quite complicated, and still awaits a completely satisfactory resolution! This is thus a reason for which second order conditions of extrema are customary established only for functional whose Lagrangian involves dependent variables together with at most their first order derivatives [8,3,4,1,9]. The aim of this paper is to give some satisfactory expressions of the second order extremum conditions for a functional whose Lagrangian also depends on the higher order derivatives of the dependent variables.

2 Brief review of known results

2.1 Holonomic constraints

We consider functional of the form

$$F(u) = \int_a^b F(x,u(x),u'(x))\,dx,$$  \hfill (2.1)

where $u \in C^2(\mathbb{R}^N)$, and $I = [a,b]$. We demand that $u$ satisfies a holonomic constraint

$$g(x,u(x)) = 0, \quad a \leq x \leq b.$$  \hfill (2.2)

**Theorem 2.1** ([9]). Suppose that $F \in C^2(\mathbb{T} \times \mathbb{R}^N)$, where $\mathbb{R}^N$ is an open set in $\mathbb{R}^{2N}$. Suppose that $g \in C^2(\mathbb{T} \times W)$, where $W \subset \mathbb{R}^N$ and that $\nabla_u g(x,u) \neq 0$ on the set where $g(x,u(x)) = 0$. Suppose that $u \in C^2(\mathbb{T} \times W)$ is a local extremum for $F$, subject to the holonomic constraint in (2.2). Then there is a function $\lambda \in C(\mathbb{T})$ such that $u$ is an extremum of the functional

$$G(u) = \int_a^b [F(x,u(x),u'(x)) + \lambda(x)g(x,u(x))]\,dx.$$  \hfill (2.3)

**Remark.** The Lagrangian of the functional $G$ in (2.3) is

$$G(x,u,u') = F(x,u,u') + \lambda(x)g(x,u)$$

and the Euler-Lagrange equations are

$$F_{u'} + \lambda g_{u'} - \frac{d}{dx}F_{u''} = 0, \quad j = 1,2,\cdots,N.$$
2.2 Nonholonomic constraints

**Theorem 2.2** ([9]). Suppose that $F$, and $g^j$ for $j = 1, 2, \cdots, m$ belong to $C^3(\mathbb{T} \times \Omega, \mathbb{R})$, where $\Omega \in \mathbb{R}^{2N}$ and that $u \in C^2([a,b], \mathbb{R}^N)$ is a local extremum of the functional

$$F(u) = \int_a^b F(x, u(x), u'(x)) \, dx,$$

subject to the nonholonomic constraints

$$g^j(x, u(x), u'(x)) = 0, \quad j = 1, 2, \cdots, m.$$

Suppose that the constraints together with $u$ satisfy the following properties.

1. The matrix
   $$D_u g(x, u, u') = \left( \frac{\partial g^j(x, u, u')}{\partial u^k} \right)$$
   has rank $m$ for $a \leq x \leq b$;

2. The only solutions to the system of differential equations
   $$\sum_{j=1}^m \left( g^j_{u^k} \frac{d}{dx} g^j_{u^k} \right) \mu_j - g^j_{u^k} \frac{d\mu_j}{dx} = 0, \quad k = 1, 2, \cdots, N$$
   are $\mu_1(x) = \mu_2(x) = \cdots = \mu_m(x) = 0$.

Then there exist functions $\lambda_1, \lambda_2, \cdots, \lambda_m$ defined on $[a,b]$ such that $u$ is an extremum for the functional with Lagrangian

$$G(x, u, u') = F(x, u, u') + \sum_{j=1}^m \lambda_j(x) g^j(x, u, u').$$

2.3 The Legendre condition

**Theorem 2.3** ([9]). Suppose that $u$ is a local, weak minimum for the functional

$$F(u) = \int_a^b F(x, u(x), u'(x)) \, dx.$$

Then

$$\sum_{j,k=1}^N F_{u^j u^k}(x, u(x), u'(x)) \xi^j \xi^k \geq 0, \quad \forall a \leq x \leq b, \forall \xi \in \mathbb{R}^N.$$  \hspace{1cm} (2.5)

The inequality in (2.5) is called the Legendre condition. As the theorem says, it is a necessary condition for $u$ to be a weak minimum. The Legendre condition says that the matrix

$$F_{u^j u^k} = (F_{u^j u^k})$$

must be positive semi-definite at every point along a minimum.
2.4 The Jacobi conditions

Consider the functional

\[ F(u) = \int_a^b F(x, u(x), u'(x)) \, dx, \]  

(2.6)

where \( u = (u^1, u^2, \ldots, u^n) \). Introduce the matrices

\[ F_{uu} = (F_{u'u'}), \quad F_{uu'} = (F_{u'u''}), \quad F_{u' u'} = (F_{u'u''}), \]

\[ P = \frac{1}{2} F_{u' u'}, \quad Q = \frac{1}{2} \left( F_{uu} - \frac{d}{dx} F_{u'u'} \right). \]

Definition 2.4. Let

\[ h^1 = (h_{11}, h_{12}, \ldots, h_{1n}) \]
\[ h^2 = (h_{21}, h_{22}, \ldots, h_{2n}) \]
\[ \vdots \]
\[ h^n = (h_{n1}, h_{n2}, \ldots, h_{nn}) \]  

(2.7)

be set of \( n \) solutions of the linear equations called the Jacobi system

\[ -\frac{d}{dx} (P h') + Q h = 0 \quad \text{(2.8)} \]

associated with the functional (2.6), where the \( i \)-th solution satisfies the initial conditions

\[ h_{ik}(a) = 0, \quad h'_{ik}(a) = 1, \quad h''_{ik}(a) = 0, \quad k \neq i, \quad i, k = 1, 2, \ldots, n. \]

Then the point \( \tilde{a}, (\tilde{a} \neq a) \), is said to be conjugate to the point \( a \) if the determinant

\[ \begin{vmatrix} 
  h_{11}(x) & h_{12}(x) & \cdots & h_{1n}(x) \\
  h_{21}(x) & h_{22}(x) & \cdots & h_{2n}(x) \\
  \vdots & \vdots & \ddots & \vdots \\
  h_{n1}(x) & h_{n2}(x) & \cdots & h_{nn}(x) 
\end{vmatrix} \]

vanishes for \( x = \tilde{a} \).

Theorem 2.5 (Jacobi necessary condition \[ \text{[3]} \]). If the extremum \( u \) corresponds to a minimum of the functional (2.6), and if the matrix \( P(x, u(x), u'(x)) \) is positive definite along this extremum, then the open interval \( [a, b] \) contains no points conjugate to \( a \).

Theorem 2.6 (Jacobi sufficient condition \[ \text{[3]} \]). Suppose that for some curve \( \gamma \) with equation \( u = u(x) \), the functional (2.6) satisfies the following conditions:

1. The curve \( \gamma \) is an extremum, i.e., satisfies the system of Euler equations

\[ F_{u^i} - \frac{d}{dx} F_{u'^i} = 0, \quad i = 1, 2, \ldots, n; \]
(2) Along $\gamma$ the matrix

$$P(x) = \frac{1}{2} F_{uu'}(x, u(x), u'(x))$$

is positive definite;

(3) The interval $[a, b]$ contains no points conjugate to the point $a$.

Then the functional (2.6) has a weak minimum for the curve $\gamma$.

In this work, we give an answer to the following question: What do the results of the four above theorems become when the vector-valued function $u = (u^1, \cdots, u^m)$ depends on several variables $x = (x^1, \cdots, x^n)$ and/or the Lagrangian of the used functional includes higher order derivatives of $u$? To our best knowledge of the literature, in this general situation, there is not explicit method available to determine if a known extremum is a minimum, a maximum, or a saddle point. To fill this gap and provide a suitable answer to our main question, we establish a regular connection between the second variation of a functional and an operational square matrix. Therefore, by the well known result of the matrix theory, explicit formula for the necessary and sufficient extremum conditions can be derived without making use of the notion of conjugate points as in the Jacobi theorems. Furthermore, the matrices $F_{uu}$, $F_{uu'}$ and $F_{u'u'}$ used in the above Legendre and Jacobi conditions are deduced as submatrices of a general matrix associated with the second variation.

3 Notations for partial derivatives of functions

Consider $X$, an $n$-dimensional independent variable space, and $U$, an $m$-dimensional dependent variable space. Let $x = (x^1, \cdots, x^n) \in X$ and $u = (u^1, \cdots, u^m) \in U$. We define the space $U^{(s)}$, $s \in \mathbb{N}$ as:

$$U^{(s)} := \left\{ u^{(s)} : u^{(s)} = \bigotimes_{j=1}^{m} \bigotimes_{k=0}^{s} u_j^{(k)} \right\},$$

(3.1)

where $u_j^{(k)}$ is the

$$p_k = \binom{n+k-1}{k}$$

(3.2)

tuple of all distinct $k$-order partial derivatives of $u^j$. The $u_j^{(k)}$ vector components are recursively obtained as follows:

i) $u_j^{(0)} = u^j$ and $u_j^{(1)} = (u_{x_1}^j, u_{x_2}^j, \cdots, u_{x_n}^j)$.

ii) Assume that $u_j^{(k)}$ is known.

- Form the tuples $\hat{u}_j^{(k+1)}(l)$:

$$\hat{u}_j^{(k+1)}(l) = \left( \frac{\partial}{\partial x^1} u_j^{(k)}[l], \frac{\partial}{\partial x^2} u_j^{(k)}[l], \cdots, \frac{\partial}{\partial x^n} u_j^{(k)}[l] \right), \quad l = 1, 2, \cdots, p_k;$$
As a matter of clarity, let us immediately illustrate this construction by the following.

Example 3.1. For \( n = 2 \), \( x = (x^1, x^2) \) and we have:

\[
\begin{align*}
\bar{u}^{(1)}_1 &= (u^j_{x^1}, u^j_{x^2}), \\
\bar{u}^{(2)}_1 &= \left( \frac{\partial}{\partial x^1} u^{(1)}_1[1], \frac{\partial}{\partial x^2} u^{(1)}_1[1] \right) = (u^j_{x^1}, u^j_{x^1 x^2}), \\
\bar{u}^{(2)}_2 &= \left( \frac{\partial}{\partial x^1} u^{(1)}_1[2], \frac{\partial}{\partial x^2} u^{(1)}_1[2] \right) = (u^j_{x^1}, u^j_{x^2}), \\
\bar{u}^{(2)}_2 &= \bar{u}^{(1)}_1(1), \quad \bar{u}^{(2)}_2 = (u^j_{x^1}, u^j_{x^1 x^2}) = (u^j_{x^2}); \\
\bar{u}^{(2)}_1 &= (u^j_{x^1}, u^j_{x^1 x^2}, u^j_{x^2}).
\end{align*}
\]

For \( n = 3 \), \( x = (x^1, x^2, x^3) \) and the same scheme leads to

\[
\begin{align*}
\bar{u}^{(2)}_1 &= (u^j_{x^1}, u^j_{x^1 x^2}, \ldots, u^j_{x^1 x^3}, u^j_{x^2}, \ldots, u^j_{x^2 x^3}, u^j_{x^3}), \\
\bar{u}^{(3)}_1 &= (u^j_{x^1}, u^j_{x^2}, \ldots, u^j_{x^3})
\end{align*}
\]

for \( k = 2 \) and \( k = 3 \), respectively.

An element \( u^{(s)} \), in the space \( U^{(s)} \), is the

\[ q_s = m(1 + p_1 + p_2 + \cdots + p_s) = m \left( \begin{array}{c} n + s \\ s \end{array} \right) \text{-tuple} \]  

(3.3)

defined by

\[ u^{(s)} = \left( u^{(0)}_0, u^{(1)}_1, \cdots, u^{(s)}_p, u^{(2)}_0, u^{(2)}_1, \cdots, u^{(s)}_{p^2}, \cdots, u^{(m)}_0, u^{(m)}_1, \cdots, u^{(s)}_{p^m} \right). \]  

(3.4)

We denote by \( X \times U^{(s)} \), the total space whose coordinates are denoted by \( (x, u^{(s)}) \), encompassing the independent variables \( x \) and the dependent variables with their derivatives up to order \( s \), globally denoted by \( u^{(s)} \).

In the sequel, a \( q_s \)-uple \( u^{(s)} \) is referred to \((3.4)\), whereas the integers \( p_k \) and \( q_s \) are defined by \((3.2)\) and \((3.3)\), respectively.
4 First variation and necessary conditions for local extrema

This section contains two parts. First, we briefly recall useful definitions and properties used in the sequel. Then, we analyze the variational problem with constraints, and give a general formulation of the first order necessary extremum condition which is rigorously proved.

4.1 Variational problem without constraints: definitions and main results

Consider a functional of the form
\[ F(u) = \int_{\Lambda} L\left(x, u^{(s)}(x)\right) dx \]  

(4.1)

where \( \Lambda \) is a connected subset of \( X \). Let \( \Omega \) be an open subset of \( U^{(s)} \). We assume that the function \( L \), usually called the Lagrangian of the functional \( F \), is defined on the open subset \( \Lambda \times \Omega \) of \( X \times U^{(s)} \) and is continuous in all its \( n+q_s \) variables so that the variational integral (4.1) exists. The problem consists in finding conditions that the function \( u \) must satisfy in order to be a minimum or maximum of the functional \( F \), requiring that \( L \in C^{s+1}(\Lambda \times \Omega, \mathbb{R}) \).

For the integral in (4.1) be defined, it is necessary that the function \( u \in C^{s+b}_{b}(\Lambda, U) \), where
\[ C^{s}_{b}(\Lambda, U) = \left\{ \psi \in C^{s}(\Lambda, U) : \sum_{j=1}^{m} \sum_{k=0}^{s} \sum_{l=1}^{p_k} \sup_{x \in \Lambda} \left| \psi^{(l)}_{(j,k)}(x) \right| < +\infty \right\}. \]

In addition, \( L(x, u^{(s)}(x)) \) must be defined for all \( x \in \Lambda \). This means that \( u^{(s)}(x) \in \Omega \) for all \( x \in \Lambda \). Such a function \( u \) is said to be admissible for the functional \( F \).

**Definition 4.1.** A function \( u \) which is admissible for the functional \( F \) is a global minimum for \( F \), if \( F(u) \leq F(v) \) for every admissible function \( v \).

**Definition 4.2.** A function \( u \) which is admissible for the functional \( F \) is a global maximum for \( F \), if \( F(v) \leq F(u) \) for every admissible function \( v \).

A function which is either a global minimum or a global maximum is called a global extremum. To come up with the definition of local extrema for a functional, we need to have a measure of distance between two functions.

**Definition 4.3.** Let \( \phi \in C^{s}_{b}(\Lambda, U) \). We define the 0-norm of \( \phi \) by
\[ \|\phi\|_0 = \sum_{j=1}^{m} \sup_{x \in \Lambda} \left| \phi^{(s)}(x) \right| \]

and the \( s \)-norm of \( \phi \) by
\[ \|\phi\|_s = \sum_{j=1}^{m} \sum_{k=0}^{s} \sum_{l=1}^{p_k} \sup_{x \in \Lambda} \left| \phi^{(l)}_{(j,k)}(x) \right|. \]

Clearly, for \( s > 0 \) the numbers \( \|\phi - \psi\|_0 \) and \( \|\phi - \psi\|_s \) provide quite different measures of the distance between \( \phi \) and \( \psi \). These measures lead to two different definitions of local minima.
Definition 4.4. A function $u$ which is admissible for the functional $F$ is a weak local minimum for $F$ if there is an $\varepsilon > 0$ such that $F(u) \leq F(v)$ for all admissible functions $v$ satisfying $\|v - u\| < \varepsilon$. $u$ is a strict weak local minimum if $F(u) < F(v)$ for all such $v$ with $v \neq u$.

Definition 4.5. A function $u$ which is admissible for the functional $F$ is a strong local minimum for $F$ if there is an $\varepsilon > 0$ such that $F(u) \leq F(v)$ for all admissible functions $v$ satisfying $\|v - u\| < \varepsilon$. $u$ is a strict strong local minimum if $F(u) < F(v)$ for all such $v$ with $v \neq u$.

Definition 4.6. A function $u$ which is admissible for the functional $F$ is a weak local maximum for $F$ if there is an $\varepsilon > 0$ such that $F(u) \geq F(v)$ for all admissible functions $v$ satisfying $\|v - u\| < \varepsilon$. $u$ is a strict weak local maximum if $F(u) > F(v)$ for all such $v$ with $v \neq u$.

Definition 4.7. A function $u$ which is admissible for the functional $F$ is a strong local maximum for $F$ if there is an $\varepsilon > 0$ such that $F(u) \geq F(v)$ for all admissible functions $v$ satisfying $\|v - u\| < \varepsilon$. $u$ is a strict strong local maximum if $F(u) > F(v)$ for all such $v$ with $v \neq u$.

A function which is either a weak local minimum or a weak local maximum is called a weak local extremum. A function which is either a strong local minimum or a strong local maximum is called a strong local extremum.

Without loss of generality, we can assume that $\Lambda = \prod_{i=1}^{n} [a^i, b^i]$ with $a^i \leq b^i$.

Definition 4.8. A function $\psi \in C(\Lambda, U)$ is said to have compact support in $\Lambda$ if there is $\varepsilon > 0$ such that $\psi(x) = 0$ for all $x = (x^1, \ldots, x^n)$ with $x^i \in [a^i, a^i + \varepsilon]$ or $x^i \in [b^i - \varepsilon, b^i]$ for some $i \in \{1, 2, \ldots, n\}$. The set of all functions which are infinitely differentiable and have compact support in $\Lambda$ is denoted by $C_0^\infty(\Lambda, U)$.

Lemma 4.9. Let $f \in C(\Lambda, \mathbb{R})$. If $\int_\Lambda f(x)\psi(x)dx = 0$ for all $\psi \in C_0^\infty(\Lambda, \mathbb{R})$, then $f(x) = 0$ for all $x \in \Lambda$.

Given an admissible function $u \in C^1(\Lambda, U)$ and any $\phi \in C_0^\infty(\Lambda, U)$, there is an $\varepsilon_0 > 0$ such that the function $v = u + t\phi$ is admissible for all $|t| < \varepsilon_0$. Therefore, the function

$$
\Phi(t) = F(u + t\phi) = \int_\Lambda L\left(x, u(x) + t\phi(x)\right)dx
$$

(4.2)

is a well defined function of $t$ for $|t| < \varepsilon_0$. Throughout this paper, $\varepsilon_0$ stands for such a number.

Assume now that $u \in C^1(\Lambda, U)$ is a local extremum of $F$. We may as well assume that $u$ is a local minimum. We have $\Phi(t) = F(u + t\phi) \geq F(u) = \Phi(0)$ for $|t| < \varepsilon_0$, i.e. 0 is a local minimum for $\Phi$. Suppose that $L \in C^1(\Lambda \times \Omega, \mathbb{R})$ implying that $\Phi$ is also continuously differentiable and we must have

$$
\Phi'(0) = 0.
$$

(4.3)
We can calculate $\Phi'$ by differentiating $\Phi$ with respect to $t$ under the integral sign. Doing so and using the chain rule we get

\[
\Phi'(t) = \frac{d}{dt} F(u + t \phi) = \frac{d}{dt} \int_{\Lambda} L(x, u^{(s)}(x) + t \phi^{(s)}(x)) \ dx = \int_{\Lambda} \frac{d}{dt} L(x, u^{(s)}(x) + t \phi^{(s)}(x)) \ dx = \int_{\Lambda} \sum_{j=1}^{m} \sum_{k=0}^{s} \sum_{h=1}^{p_k} \frac{\partial L}{\partial u^{(s)}[h]} \frac{\partial L}{\partial \phi^{(s)}[h]} dx. \tag{4.4}
\]

In particular at $t = 0$ we get

\[
\Phi'(0) = \int_{\Lambda} \sum_{j=1}^{m} \sum_{k=0}^{s} \sum_{h=1}^{p_k} \frac{\partial L}{\partial u^{(s)}[h]} \frac{\partial L}{\partial \phi^{(s)}[h]} dx. \tag{4.5}
\]

**Definition 4.10.** The first variation of $F$ in a neighborhood of $u$ in the direction $\phi$ is defined by

\[
\delta F(u + t \phi, \phi) = \Phi'(t). \tag{4.6}
\]

In particular, the first variation of $F$ at $u$ in the direction $\phi$ is expressed by

\[
\delta F(u, \phi) = \Phi'(0). \tag{4.7}
\]

Notice that the first variation at $u$ is defined in Definition 4.10 whether $u$ is a local extremum or not. However, if $u$ is a local extremum of $F$, then by (4.3) and (4.7), $\delta F(u, \phi) = 0$. We have proved the following first order necessary condition on a local extremum of $F$.

**Proposition 4.11.** Suppose that $L \in C^1(\Lambda \times \Omega, \mathbb{R})$, and that $u \in C^0_b(\Lambda, U)$ is a local extremum for the functional $F(u) = \int_{\Lambda} L(x, u^{(s)}(x)) \ dx$. Then

\[
\delta F(u, \phi) = 0 \tag{4.8}
\]

for all $\phi \in C^0_b(\Lambda, U)$.

The condition in (4.8) is called the weak form of the Euler-Lagrange equations. A function $u$ which satisfies (4.8) is called the weak extremum of $F$.

Now assume that the Lagrangian $L \in C^{s+1}(\Lambda \times \Omega, \mathbb{R})$, and $u \in C^s_b(\Lambda, U)$. Using the divergence theorem to successively integrate by parts (4.5) until all derivative actions on $\phi^j$ are now moved into $\frac{\partial L}{\partial u^{(s)}[h]}$, and taking into account that $\phi^j \in C^s_0(\Lambda, \mathbb{R})$, we get

\[
\delta F(u, \phi) = \int_{\Lambda} \sum_{j=1}^{m} \left( \sum_{k=0}^{s} (-1)^k \sum_{h=1}^{p_k} \frac{\partial L}{\partial u^{(s)}[h]} \phi^j(x) dx. \tag{4.9}
\]
If $u$ is a weak local extremum, then (4.9) is equal to 0 for all $\phi \in C^\infty_0(\Lambda, U)$. In particular if we take $\phi = \psi e^l$, where $\psi \in C^\infty_0(\Lambda, \mathbb{R})$ and $e^l$ is the $l$-th vector of the canonical basis of $\mathbb{R}^m$, then we get

$$0 = \delta F(u, \psi e^l) = \int_\Lambda \left( \sum_{k=0}^s (-1)^k \sum_{h=1}^{p_k} \left( \frac{\partial L(x, u^{(s)}(x))}{\partial u^{(k)}_l[h]} \right) [h] \right) \psi(x) dx$$

for all $\psi \in C^\infty_0(\Lambda, \mathbb{R})$. By Lemma 4.9, we see that

$$\sum_{k=0}^s (-1)^k \sum_{h=1}^{p_k} \left( \frac{\partial L(x, u^{(s)}(x))}{\partial u^{(k)}_l[h]} \right) [h] = 0$$

for all $x \in \Lambda$ and $l = 1, 2, \cdots, m$. Thus, we have proved the following theorem.

**Theorem 4.12.** Suppose that $L \in C^{s+1}_b(\Lambda \times \Omega, \mathbb{R})$, and $u \in C^s_b(\Lambda, U)$ is a local extremum for the functional $F(u) = \int_\Lambda L(x, u^{(s)}(x)) dx$. Then

$$\sum_{k=0}^s (-1)^k \sum_{h=1}^{p_k} \left( \frac{\partial L(x, u^{(s)}(x))}{\partial u^{(k)}_l[h]} \right) [h] = 0 \quad (4.10)$$

for all $x \in \Lambda$ and $j = 1, 2, \cdots, m$.

The equations (4.10) are called the Euler-Lagrange equations. A solution to the Euler-Lagrange equations is called an extremum for the functional $F$.

**4.2 Variational problem with constraints: main results**

We want to find extrema for the functional

$$F(u) = \int_\Lambda L(x, u^{(s)}(x)) dx \quad (4.11)$$

subject to constraints of the form

$$F_j\left(x, u^{(s_2)}(x)\right) = 0 \quad j = 1, 2, \cdots, m' \quad (4.12)$$

for all $x \in \Lambda$. Let $\Omega_i$ be open subsets of $U^{(s_i)}$, $i = 1, 2$ such that $L$ is defined on $\Lambda \times \Omega_1$ and $F_j$ is defined on $\Lambda \times \Omega_2$. Constraints of type (4.12) are called holonomic constraints if $s_2 = 0$, and nonholonomic constraints if $s_2 \geq 1$. In this subsection, we examine these types of constrained variational problems.

For $m = m'$, i.e. the number of equations in the system formed by the constraints is equal to the number of unknowns, we exploit the fact that such a system appears for the Euler-Lagrange equations of some variational problems to prove our next result.
Theorem 4.13. Suppose that \( L \in C^{s_1+1}(\Lambda \times \Omega_1, \mathbb{R}) \), \( F_j \in C^{s_2+1}(\Lambda \times \Omega_2, \mathbb{R}) \) and that the function \( u \in C^{s_1+1}(\Lambda, U) \), \( s = \max(s_1, s_2) \), verifies the constraints (4.12) and is a local extremum for the functional \( J \) defined by (4.11). If a function \( \lambda(x) = (\lambda^1(x), \cdots, \lambda^m(x)) \) defined on \( \Lambda \) is solution of the system

\[
\sum_{k=0}^{s_2} (-1)^k \sum_{h=1}^{p_k} \left( \frac{\partial \left[ \sum_{l=1}^{m} \lambda_l^j(x) F_l \left( x, u^{(s_2)}(x) \right) \right]}{\partial u^j_{(k)}[h]} \right) [h] = 0, \quad j = 1, 2, \cdots, m \quad (4.13)
\]

then \( u \) is a local extremum for the functional whose Lagrangian is

\[
G \left( x, u^{(s)}(x) \right) = L \left( x, u^{(s_1)}(x) \right) + \sum_{l=1}^{m} \lambda^l(x) F_l \left( x, u^{(s_2)}(x) \right) \quad (4.14)
\]

Proof. Consider the variational problem whose Lagrangian is defined by

\[
G' \left( x, u^{(s)}(x), v(x) \right) = L \left( x, u^{(s_1)}(x) \right) + \sum_{l=1}^{m} v^l(x) F_l \left( x, u^{(s_2)}(x) \right), \quad (4.15)
\]

where \( v(x) = (v^1(x), \cdots, v^m(x)) \) is viewed as dependent variable. The Euler-Lagrange equations of this variational problem are

\[
P_j \equiv \sum_{k=0}^{s_1} (-1)^k \sum_{h=1}^{p_k} \left( \frac{\partial G' \left( x, u^{(s)}(x), v(x) \right)}{\partial u^j_{(k)}[h]} \right) [h] = 0; \quad (4.16)
\]

\[
Q_j \equiv \sum_{k=0}^{s_2} (-1)^k \sum_{h=1}^{p_k} \left( \frac{\partial G' \left( x, u^{(s)}(x), v(x) \right)}{\partial v^j_{(k)}[h]} \right) [h] = 0, \quad (4.17)
\]

\( j = 1, 2, \cdots, m \). Taking into account (4.15), the expressions of \( P_j \) and \( Q_j \) give

\[
P_j = P_{j,1} + P_{j,2}; \quad Q_j = Q_{j,1} + Q_{j,2}
\]

where

\[
P_{j,1} = \sum_{k=0}^{s_1} (-1)^k \sum_{h=1}^{p_k} \left( \frac{\partial L \left( x, u^{(s_1)}(x) \right)}{\partial u^j_{(k)}[h]} \right) [h];
\]

\[
P_{j,2} = \sum_{k=0}^{s_2} (-1)^k \sum_{h=1}^{p_k} \left( \frac{\partial \left[ \sum_{l=1}^{m} v^l(x) F_l \left( x, u^{(s_2)}(x) \right) \right]}{\partial u^j_{(k)}[h]} \right) [h];
\]

\[
Q_{j,1} = \sum_{k=0}^{s_1} (-1)^k \sum_{h=1}^{p_k} \left( \frac{\partial L \left( x, u^{(s_1)}(x) \right)}{\partial v^j_{(k)}[h]} \right) [h];
\]

\[
Q_{j,2} = \sum_{k=0}^{s_2} (-1)^k \sum_{h=1}^{p_k} \left( \frac{\partial \left[ \sum_{l=1}^{m} v^l(x) F_l \left( x, u^{(s_2)}(x) \right) \right]}{\partial v^j_{(k)}[h]} \right) [h].
\]

The \( P_{j,1} \) are expressions defining the Euler-Lagrange equations of the variational problem (4.11). Thus, \( P_{j,1} = 0 \) since \( u \) is a local extremum for the functional \( J \). According
to the relations \( (4.13) \), the expressions \( P_{j,2} \) vanish when \( v(x) = \lambda(x) \). The expressions \( Q_{j,1} \) vanish since the Lagrangian \( L \) does depend neither on \( v \) nor on its derivatives.

For \( j = 1, 2, \cdots, m \), \( Q_{j,2} = F_j(x, u^{(s_2)}(x)) \) and therefore vanish since the function \( u \) satisfies the constraints \( (4.12) \).

Finally, the Euler-Lagrange equations \( (4.16)-(4.17) \) are automatically verified if and only if \( v(x) = \lambda(x) \). This proves that \( u \) is also a local extremum for the functional whose Lagrangian is \( G'(x, u^{(s)}(x), \lambda(x)) = G(x, u^{(s)}(x)) \). \( \square \)

For \( m' < m \), we redefine the problem in the following manner: Find the extrema for the functional

\[
F(u, \tilde{u}) = \int_{\Lambda} L\left(x, u^{(s_1)}(x), \tilde{u}^{(s_1)}(x)\right) \, dx
\]

subject to the constraints

\[
F_j\left(x, u^{(s_2)}(x), \tilde{u}^{(s_2)}(x)\right) = 0 \quad j = 1, 2, \cdots, m
\]

for all \( x \in \Lambda \), where \( \tilde{u}(x) = \left( \tilde{u}^1(x), \cdots, \tilde{u}^{m'}(x) \right) \in \tilde{U} \), \( \tilde{U} \) being an \( m' \)-dimensional space. Let \( \Omega_i \) be open subsets of \( U^{(s_i)} \) and \( \tilde{\Omega}_i \) be open subsets of \( \tilde{U}^{(s_i)} \), \( i = 1, 2 \) such that \( L \) is defined on \( \Lambda \times \Omega_1 \times \tilde{\Omega}_1 \) and \( F_j \) is defined on \( \Lambda \times \Omega_2 \times \tilde{\Omega}_2 \). Here, the number of equations in the system formed by the constraints is lower than the number of unknowns, i.e. the constraints form an under-determined system. Such a system appears for the Euler-Lagrange equations of some variational problems \([2]\). We then prove the following result.

**Theorem 4.14.** Suppose that \( L \in C^{s_1+1}(\Lambda \times \Omega_1 \times \tilde{\Omega}_1, \mathbb{R}) \), \( F_j \in C^{s_2+1}(\Lambda \times \Omega_2 \times \tilde{\Omega}_2, \mathbb{R}) \) and that the function \( (u, \tilde{u}) \in C^2(\Lambda, U) \times C^2(\Lambda, \tilde{U}) \), \( s = \max(s_1, s_2) \), verifies the constraints \( (4.19) \) and is a local extremum for the functional \( F \) defined by \( (4.18) \). If a function \( \left( \lambda(x), \tilde{\lambda}(x) \right) \) defined on \( \Lambda \) with \( \lambda(x) = \left( \lambda^1(x), \cdots, \lambda^m(x) \right) \) and \( \tilde{\lambda}(x) = \left( \tilde{\lambda}^1(x), \cdots, \tilde{\lambda}^{m'}(x) \right) \), is solution to the system

\[
\sum_{k=0}^s (-1)^k \sum_{h=1}^{p_k} \left( \frac{\partial}{\partial u^{(k)}_{(h)}} \left[ \sum_{l=1}^{m} \left( \lambda^l_{(h)} + \sum_{j=1}^{m'} \tilde{\lambda}^{j}_{(h)} \right) F_j\left(x, u^{(s_2)}(x), \tilde{u}^{(s_2)}(x)\right) \right] \right) [h] = 0; \quad (4.20)
\]

\[
\sum_{k=0}^s (-1)^k \sum_{h=1}^{p_k} \left( \frac{\partial}{\partial \tilde{u}^{(k)}_{(h)}} \left[ \sum_{l=1}^{m} \left( \lambda^l_{(h)} + \sum_{j=1}^{m'} \tilde{\lambda}^{j}_{(h)} \right) F_j\left(x, u^{(s_2)}(x), \tilde{u}^{(s_2)}(x)\right) \right] \right) [h] = 0, \quad (4.21)
\]

\( j = 1, 2, \cdots, m, \tilde{j} = 1, 2, \cdots, m' \), then \( (u, \tilde{u}) \) is a local extremum for the functional whose Lagrangian is

\[
G\left(x, u^{(s)}(x), \tilde{u}^{(s)}(x)\right) = \sum_{l=1}^{m} \left( \lambda^l(x) + \sum_{j=1}^{m'} \tilde{\lambda}^j(x) \right) F_l\left(x, u^{(s_2)}(x), \tilde{u}^{(s_2)}(x)\right) + L\left(x, u^{(s_1)}(x), \tilde{u}^{(s_1)}(x)\right). \quad (4.22)
\]
Proof. Consider the variational problem whose Lagrangian is defined by

\[
G' (x, u^{(s)}(x), \bar{u}^{(s)}(x), v, \bar{v}) = \sum_{l=1}^{m} \left( v'(x) + \sum_{l=1}^{\bar{m}} \bar{v}'(x) \right) F_l (x, u^{(s_2)}(x), \bar{u}^{(s_2)}(x)) \\
+ L (x, u^{(s_1)}(x), \bar{u}^{(s_1)}(x)),
\]

where \( v(x) = (v^1(x), \ldots, v^m(x)) \), and \( \bar{v}(x) = (\bar{v}^1(x), \ldots, \bar{v}^{\bar{m}}(x)) \) are viewed as dependent variables. The Euler-Lagrange equations of this variational problem are

\[
P_j = \sum_{k=0}^{s_j} (-1)^k \sum_{h=1}^{p_k} \left( \frac{\partial G' (x, u^{(s)}(x), \bar{u}^{(s)}(x), v(x), \bar{v}(x))}{\partial u_l^j [h]} \right) [h] = 0; \quad (4.24)
\]

\[
Q_j = \sum_{k=0}^{s_j} (-1)^k \sum_{h=1}^{p_k} \left( \frac{\partial G' (x, u^{(s)}(x), \bar{u}^{(s)}(x), v(x), \bar{v}(x))}{\partial \bar{u}_l^j [h]} \right) [h] = 0, \quad (4.25)
\]

\[
R_j = \sum_{k=0}^{s_j} (-1)^k \sum_{h=1}^{p_k} \left( \frac{\partial G' (x, u^{(s)}(x), \bar{u}^{(s)}(x), v(x), \bar{v}(x))}{\partial v_l^j [h]} \right) [h] = 0; \quad (4.26)
\]

\[
S_j = \sum_{k=0}^{s_j} (-1)^k \sum_{h=1}^{p_k} \left( \frac{\partial G' (x, u^{(s)}(x), \bar{u}^{(s)}(x), v(x), \bar{v}(x))}{\partial \bar{v}_l^j [h]} \right) [h] = 0, \quad (4.27)
\]

\( j = 1, 2, \ldots, m \), \( \bar{j} = 1, 2, \ldots, \bar{m} \). Taking into account (4.23), the expressions of \( P_j, Q_j, R_j \) and \( S_j \) are given by

\[
P_j = P_{j,1} + P_{j,2}; \quad Q_j = Q_{j,1} + Q_{j,2};
\]

\[
R_j = R_{j,1} + R_{j,2}; \quad S_j = S_{j,1} + S_{j,2}
\]

where

\[
P_{j,1} = \sum_{k=0}^{s_j} (-1)^k \sum_{h=1}^{p_k} \left( \frac{\partial L (x, u^{(s)}(x), \bar{u}^{(s)}(x))}{\partial u_l^j [h]} \right) [h];
\]

\[
P_{j,2} = \sum_{k=0}^{s_j} (-1)^k \sum_{h=1}^{p_k} \left( \frac{\partial \sum_{l=1}^{m} \left( v^l + \sum_{l=1}^{\bar{m}} \bar{v}^l \right) F_l (x, u^{(s_2)}(x), \bar{u}^{(s_2)}(x))}{\partial u_l^j [h]} \right) [h];
\]

\[
Q_{j,1} = \sum_{k=0}^{s_j} (-1)^k \sum_{h=1}^{p_k} \left( \frac{\partial L (x, u^{(s)}(x), \bar{u}^{(s)}(x))}{\partial \bar{u}_l^j [h]} \right) [h];
\]

\[
Q_{j,2} = \sum_{k=0}^{s_j} (-1)^k \sum_{h=1}^{p_k} \left( \frac{\partial \sum_{l=1}^{m} \left( v^l + \sum_{l=1}^{\bar{m}} \bar{v}^l \right) F_l (x, u^{(s_2)}(x), \bar{u}^{(s_2)}(x))}{\partial \bar{u}_l^j [h]} \right) [h];
\]

\[13\]
\[ R_{j,1} = \sum_{k=0}^{s_1} (-1)^k \sum_{h=1}^{p_k} \left( \frac{\partial L(x, u^{(s_1)}, \tilde{u}^{(s_1)})}{\partial v^j(h)} \right) [h] ; \]

\[ R_{j,2} = \sum_{k=0}^{s_2} (-1)^k \sum_{h=1}^{p_k} \left( \frac{\partial \left[ \sum_{l=1}^{m} \left( v^l + \sum_{i=1}^{m} \tilde{v}^i \right) F_l(x, u^{(s_2)}, \tilde{u}^{(s_2)}) \right]}{\partial v^j(h)} \right) [h] ; \]

\[ S_{j,1} = \sum_{k=0}^{s_1} (-1)^k \sum_{h=1}^{p_k} \left( \frac{\partial L(x, u^{(s_1)}(x), \tilde{u}^{(s_1)}(x))}{\partial v^j(h)} \right) [h] ; \]

\[ S_{j,2} = \sum_{k=0}^{s_2} (-1)^k \sum_{h=1}^{p_k} \left( \frac{\partial \left[ \sum_{l=1}^{m} \left( v^l + \sum_{i=1}^{m} \tilde{v}^i \right) F_l(x, u^{(s_2)}(x), \tilde{u}^{(s_2)}(x)) \right]}{\partial v^j(h)} \right) [h] . \]

The \( P_{j,1} \) and \( Q_{j,1} \) are nothing but the Euler-Lagrange equations of the variational problem (4.18). Hence, \( P_{j,1} = 0 \) and \( Q_{j,1} = 0 \) since \((u, \tilde{u})\) is a local extremum for the functional \( \mathcal{F} \).

According to the relations (4.20) and (4.21), the expressions \( P_{j,2} \) and \( Q_{j,2} \) vanish when \((v(x), \tilde{v}(x)) = (\lambda(x), \tilde{\lambda}(x))\).

The expressions \( R_{j,1} \) and \( S_{j,1} \) vanish since the Lagrangian \( L \) does depend neither on \( v \) and \( \tilde{v} \) nor on their derivatives.

For \( j = 1, 2, \cdots, m \), and \( \tilde{j} = 1, 2, \cdots, \tilde{m}, \) we have \( R_{j,2} = F_j(x, u^{(s_2)}(x), \tilde{u}^{(s_2)}(x)) \) and \( S_{j,2} = \sum_{l=1}^{m} F_l(x, u^{(s_2)}(x), \tilde{u}^{(s_2)}(x)) \) which therefore vanish since the function \( u \) satisfies the constraints (4.19).

Finally, the Euler-Lagrange equations (4.24)-(4.27) are automatically verified if and only if \((v(x), \tilde{v}(x)) = (\lambda(x), \tilde{\lambda}(x))\). This proves that \( u \) is also a local extremum for the functional whose Lagrangian is \( G'(x, u^{(s)}(x), \tilde{u}^{(s)}(x), \lambda(x), \tilde{\lambda}(x)) = G(x, u^{(s)}(x), \tilde{u}^{(s)}(x)) \) .

\[ \square \]

5 Second variation and conditions for local extrema: main results

This section contains relevant results which are new to our best knowledge of the literature. We investigate the second variation of a functional as well as the necessary and sufficient conditions that a function should satisfy to be either a minimum or a maximum.

Consider a variational problem of the form (4.1) with the Lagrangian \( L \in C^2(\Lambda \times \Omega, \mathbb{R}) \). Define an \( m \times m \) block matrix \( A \) of second order partial derivatives of \( L \) by:

\[ A = \left[ A^{j'}_{j'} \right]_{1 \leq j, j' \leq m} \]

(5.1)

with \( A^{j'}_{j'} \) being again an \( s \times s \) block matrix defined by

\[ A^{j'}_{j'} = \left[ A^{j' \ell}_{\ell k} \right]_{0 \leq k, k' \leq s} , \]

14
where $A_{kk'}^{ij}$ is a $p_k \times p_{k'}$ matrix defined by

$$A_{kk'}^{ij} = \begin{bmatrix} \frac{\partial^2 L}{\partial u_i^{(k)} \partial u_j^{(k')}} \\ \vdots \\ \frac{\partial^2 L}{\partial u_i^{(k)} \partial u_j^{(k')}} \end{bmatrix}_{1 \leq i \leq p_k, 1 \leq j \leq p_{k'}}. \quad (5.2)$$

Note that the matrix $A$ is obviously symmetric by construction.

**Example 5.1.** Let us construct the matrix $A^{ij}$ for particular values of the integers $n$ and $s$.

If $s = 1$, then

$$A^{ij} = \begin{bmatrix} A^{ij}_{00} & A^{ij}_{01} \\ A^{ij}_{10} & A^{ij}_{11} \end{bmatrix}.$$ 

In this case, we have for $n = 1, x = x^1$:

$$A^{ij}_{00} = \frac{\partial^2 L}{\partial u_1^{(1)} \partial u_1^{(1)}}, \quad A^{ij}_{01} = \frac{\partial^2 L}{\partial u_1^{(1)} \partial u_2^{(1)}},$$

$$A^{ij}_{10} = \frac{\partial^2 L}{\partial u_2^{(1)} \partial u_1^{(1)}}, \quad A^{ij}_{11} = \frac{\partial^2 L}{\partial u_2^{(1)} \partial u_2^{(1)}},$$

thus

$$A^{ij} = \begin{bmatrix} \frac{\partial^2 L}{\partial u_1^{(1)} \partial u_1^{(1)}} & \frac{\partial^2 L}{\partial u_1^{(1)} \partial u_2^{(1)}} \\ \frac{\partial^2 L}{\partial u_2^{(1)} \partial u_1^{(1)}} & \frac{\partial^2 L}{\partial u_2^{(1)} \partial u_2^{(1)}} \end{bmatrix};$$

For $n = 2, x = (x^1, x^2)$:

$$A^{ij}_{00} = \frac{\partial^2 L}{\partial u_1^{(1)} \partial u_1^{(1)}}, \quad A^{ij}_{01} = \left( \frac{\partial^2 L}{\partial u_1^{(1)} \partial u_2^{(1)}} \frac{\partial^2 L}{\partial u_2^{(1)} \partial u_2^{(1)}} \right),$$

$$A^{ij}_{10} = \left( \frac{\partial^2 L}{\partial u_2^{(1)} \partial u_1^{(1)}} \frac{\partial^2 L}{\partial u_2^{(1)} \partial u_2^{(1)}} \right), \quad A^{ij}_{11} = \left( \frac{\partial^2 L}{\partial u_2^{(1)} \partial u_2^{(1)}} \frac{\partial^2 L}{\partial u_2^{(1)} \partial u_2^{(1)}} \right),$$

thus

$$A^{ij} = \begin{bmatrix} \frac{\partial^2 L}{\partial u_1^{(1)} \partial u_1^{(1)}} & \frac{\partial^2 L}{\partial u_1^{(1)} \partial u_2^{(1)}} & \frac{\partial^2 L}{\partial u_2^{(1)} \partial u_1^{(1)}} & \frac{\partial^2 L}{\partial u_2^{(1)} \partial u_2^{(1)}} \\ \frac{\partial^2 L}{\partial u_2^{(1)} \partial u_1^{(1)}} & \frac{\partial^2 L}{\partial u_2^{(1)} \partial u_2^{(1)}} & \frac{\partial^2 L}{\partial u_2^{(1)} \partial u_2^{(1)}} & \frac{\partial^2 L}{\partial u_2^{(1)} \partial u_2^{(1)}} \\ \frac{\partial^2 L}{\partial u_2^{(1)} \partial u_1^{(1)}} & \frac{\partial^2 L}{\partial u_2^{(1)} \partial u_2^{(1)}} & \frac{\partial^2 L}{\partial u_2^{(1)} \partial u_2^{(1)}} & \frac{\partial^2 L}{\partial u_2^{(1)} \partial u_2^{(1)}} \\ \frac{\partial^2 L}{\partial u_2^{(1)} \partial u_2^{(1)}} & \frac{\partial^2 L}{\partial u_2^{(1)} \partial u_2^{(1)}} & \frac{\partial^2 L}{\partial u_2^{(1)} \partial u_2^{(1)}} & \frac{\partial^2 L}{\partial u_2^{(1)} \partial u_2^{(1)}} \end{bmatrix};$$

If $s = 2$, then

$$A^{ij} = \begin{bmatrix} A^{ij}_{00} & A^{ij}_{01} & A^{ij}_{02} \\ A^{ij}_{10} & A^{ij}_{11} & A^{ij}_{12} \\ A^{ij}_{20} & A^{ij}_{21} & A^{ij}_{22} \end{bmatrix}.$$ 

In this case, we have for $n = 1, x = x^1$:

$$A^{ij}_{00} = \frac{\partial^2 L}{\partial u_1^{(1)} \partial u_1^{(1)}}, \quad A^{ij}_{01} = \frac{\partial^2 L}{\partial u_1^{(1)} \partial u_2^{(1)}}, \quad A^{ij}_{02} = \frac{\partial^2 L}{\partial u_1^{(1)} \partial u_3^{(1)}},$$

$$A^{ij}_{10} = \frac{\partial^2 L}{\partial u_2^{(1)} \partial u_1^{(1)}}, \quad A^{ij}_{11} = \frac{\partial^2 L}{\partial u_2^{(1)} \partial u_2^{(1)}}, \quad A^{ij}_{12} = \frac{\partial^2 L}{\partial u_2^{(1)} \partial u_3^{(1)}},$$

$$A^{ij}_{20} = \frac{\partial^2 L}{\partial u_3^{(1)} \partial u_1^{(1)}}, \quad A^{ij}_{21} = \frac{\partial^2 L}{\partial u_3^{(1)} \partial u_2^{(1)}}, \quad A^{ij}_{22} = \frac{\partial^2 L}{\partial u_3^{(1)} \partial u_3^{(1)}};$$
thus

\[
A^{ij} = \begin{bmatrix}
\frac{\partial^2 L}{\partial u \partial u'} & \frac{\partial^2 L}{\partial u' \partial u} \\
\frac{\partial^2 L}{\partial u \partial u''} & \frac{\partial^2 L}{\partial u' \partial u''} \\
\frac{\partial^2 L}{\partial u \partial u_1'} & \frac{\partial^2 L}{\partial u' \partial u_1'} \\
\frac{\partial^2 L}{\partial u \partial u_2'} & \frac{\partial^2 L}{\partial u' \partial u_2'}
\end{bmatrix};
\]

For \( n = 2, x = (x^1, x^2) \):

\[
A_{00}^{ij} = \frac{\partial^2 L}{\partial u \partial u}, \quad A_{01}^{ij} = \begin{pmatrix}
\frac{\partial^2 L}{\partial u \partial u_1'} & \frac{\partial^2 L}{\partial u' \partial u_1'} \\
\frac{\partial^2 L}{\partial u \partial u_2'} & \frac{\partial^2 L}{\partial u' \partial u_2'}
\end{pmatrix},
\]

\[
A_{02}^{ij} = \begin{pmatrix}
\frac{\partial^2 L}{\partial u \partial u_{1,2}'} & \frac{\partial^2 L}{\partial u' \partial u_{1,2}'} \\
\frac{\partial^2 L}{\partial u \partial u_{2,1}'} & \frac{\partial^2 L}{\partial u' \partial u_{2,1}'}
\end{pmatrix},
\]

\[
A_{10}^{ij} = \begin{pmatrix}
\frac{\partial^2 L}{u'u' \partial u} & \frac{\partial^2 L}{u' \partial u' \partial u} \\
\frac{\partial^2 L}{u' \partial u' \partial u} & \frac{\partial^2 L}{u' \partial u' \partial u}
\end{pmatrix}, \quad A_{11}^{ij} = \begin{pmatrix}
\frac{\partial^2 L}{u' \partial u' \partial u} & \frac{\partial^2 L}{u' \partial u' \partial u} \\
\frac{\partial^2 L}{u' \partial u' \partial u} & \frac{\partial^2 L}{u' \partial u' \partial u}
\end{pmatrix},
\]

\[
A_{12}^{ij} = \begin{pmatrix}
\frac{\partial^2 L}{u' \partial u' \partial u} & \frac{\partial^2 L}{u' \partial u' \partial u} \\
\frac{\partial^2 L}{u' \partial u' \partial u} & \frac{\partial^2 L}{u' \partial u' \partial u}
\end{pmatrix},
\]

\[
A_{20}^{ij} = \begin{pmatrix}
\frac{\partial^2 L}{u_1 \partial u_1} & \frac{\partial^2 L}{u_1' \partial u_1'} \\
\frac{\partial^2 L}{u_2 \partial u_2} & \frac{\partial^2 L}{u_2' \partial u_2'}
\end{pmatrix}, \quad A_{21}^{ij} = \begin{pmatrix}
\frac{\partial^2 L}{u_1 \partial u_1} & \frac{\partial^2 L}{u_1' \partial u_1'} \\
\frac{\partial^2 L}{u_2 \partial u_2} & \frac{\partial^2 L}{u_2' \partial u_2'}
\end{pmatrix},
\]

\[
A_{22}^{ij} = \begin{pmatrix}
\frac{\partial^2 L}{u_1 \partial u_1} & \frac{\partial^2 L}{u_1' \partial u_1'} \\
\frac{\partial^2 L}{u_2 \partial u_2} & \frac{\partial^2 L}{u_2' \partial u_2'}
\end{pmatrix},
\]

thus

\[
A^{ij} = \begin{bmatrix}
\frac{\partial^2 L}{\partial u \partial u'} & \frac{\partial^2 L}{\partial u' \partial u} \\
\frac{\partial^2 L}{\partial u \partial u''} & \frac{\partial^2 L}{\partial u' \partial u''} \\
\frac{\partial^2 L}{\partial u \partial u_1'} & \frac{\partial^2 L}{\partial u' \partial u_1'} \\
\frac{\partial^2 L}{\partial u \partial u_2'} & \frac{\partial^2 L}{\partial u' \partial u_2'}
\end{bmatrix};
\]

Let us recall the following formulation of the Taylor’s theorem with the remainder, useful in the sequel.
Theorem 5.2. Suppose that \( f \in C^2(I, \mathbb{R}) \), \( a \in I \), where \( I \) is an open interval. Then

\[
f(a + t) = f(a) + f'(a)t + f''(a)\frac{t^2}{2} + e(a, t)t^2,
\]

where

\[
e(a, t) = \int_0^1 \left[ f''(a + \sigma t) - f''(a) \right](1 - \sigma)d\sigma.
\]

We can apply this theorem to rewrite (4.2) as

\[
\mathcal{F}(u + t\phi) = \Phi(t) = \Phi(0) + \Phi'(0)t + \frac{1}{2}t^2 \Phi''(0) + e(0, t)t^2,
\]

where

\[
e(0, t) = \int_0^1 \left[ \Phi''(\sigma t) - \Phi''(0) \right](1 - \sigma)d\sigma.
\]

As already shown \( \Phi(0) = \mathcal{F}(u) \) and by definition \( \Phi'(0) = \delta \mathcal{F}(u, \phi) \). The quantity \( \Phi''(t) \) can be found by differentiating (4.4) under the integral sign and using the chain rule:

\[
\Phi''(t) = \frac{d}{dt} \int_L \sum_j \sum_{k=1}^m \sum_{h=1}^n \phi_{(k)}^j[h](x) \frac{\partial L(x, u^s(x) + t\phi^j(x))}{\partial u_{(k)}^j[h]} \, dx
\]
\[
- \int_L \sum_j \sum_{k=1}^m \sum_{h=1}^n \phi_{(k)}^j[h](x) \frac{d}{dt} \left( \frac{\partial L(x, u^s(x) + t\phi^j(x))}{\partial u_{(k)}^j[h]} \right) \, dx
\]
\[
+ \int_L \sum_j \sum_{k=1}^m \sum_{h=1}^n \sum_{h'=1}^n \phi_{(k)}^j[h]\phi_{(k')}^{j'}[h'] \frac{\partial^2 L(x, u^s(x) + t\phi^j(x))}{\partial u_{(k)}^j[h] \partial u_{(k')}^{j'}[h']} \, dx
\]
\[
= \int_L \phi^s(x) A \left(x, u^s(x) + t\phi^j(x)\right) T \phi^j(x) \, dx,
\]

where the notation \( T(\cdot) \) denotes the transpose of \( (\cdot) \). In particular at \( t = 0 \), we get

\[
\Phi''(0) = \int_L \sum_j \sum_{k=1}^m \sum_{h=1}^n \sum_{h'=1}^n \phi_{(k)}^j[h](x) \phi_{(k')}^{j'}[h'][x] \frac{\partial^2 L(x, u^s(x))}{\partial u_{(k)}^j[h] \partial u_{(k')}^{j'}[h']} \, dx
\]
\[
= \int_L \phi^s(x) A \left(x, u^s(x)\right) T \phi^s(x) \, dx.
\]

We then arrive at the following formulation.

Definition 5.3. The second variation of the functional \( \mathcal{F} \) in the neighborhood of \( u \) in the direction \( \phi \) is defined by

\[
\delta^2 \mathcal{F}(u + t\phi, \phi) = \Phi''(t).
\]

In particular, the second variation of \( \mathcal{F} \) at \( u \) in the direction \( \phi \) is given by

\[
\delta^2 \mathcal{F}(u, \phi) = \Phi''(0).
\]
The Taylor expansion \((5.3)\) can be now re-expressed as

\[
\Phi(t) = F(u + t \phi) = F(u) + t \delta F(u, \phi) + \frac{1}{2} t^2 \delta^2 F(u, \phi) \\
+ t^2 \int_{0}^{1} \left[ \delta^2 F(u + \sigma t \phi, \phi) - \delta^2 F(u, \phi) \right] (1 - \sigma) d\sigma. \tag{5.9}
\]

Let us also recall the following two results which are important to prove the main results of this work.

**Lemma 5.4** \((9)\). Suppose that \(A = (a_{ij})\) is an \(N \times N\) matrix, and set \(|||A||| = \sqrt{\sum_{i,j=1}^{N} a_{ij}^2}\). Then \((|| \cdot ||\) denotes the Euclidean norm \(\mathbb{R}^N)\)

1. \(v \cdot w \leq ||v|| ||w||\) for all \(v \) and \(w\) in \(\mathbb{R}^N\).
2. \(||Av|| \leq |||A||| ||v||\) for all \(v\) in \(\mathbb{R}^N\).
3. \(||v \cdot Av|| \leq |||A||| ||v|| ||w||\) for all \(v\) and \(w\) in \(\mathbb{R}^N\).

**Definition 5.5** (Positive semi-definite). A symmetric matrix \(A \in \mathbb{R}^{N^2}\) is called positive semi-definite if \(v \cdot Av \geq 0\) for all \(v \in \mathbb{R}^N\).

**Definition 5.6** (Positive definite). A symmetric matrix \(A \in \mathbb{R}^{N^2}\) is called positive definite if \(v \cdot Av > 0\) for all \(v \in \mathbb{R}^N \setminus \{0\}\).

**Lemma 5.7** \((9)\). Suppose that \(A\) is a positive definite \(N \times N\) matrix. Then there is a constant \(k > 0\) such that \(v \cdot Av \geq k||v||^2\) for all \(v\) in \(\mathbb{R}^N\).

There results the following.

**Lemma 5.8.** Suppose that \(L \in C^2(\Lambda \times \Omega, \mathbb{R})\), and \(u \in C^1_0(\Lambda, U)\) is admissible for \(F\). Then for any \(\varepsilon > 0\), there is \(\delta > 0\) such that

\[
|e(0,t)| \leq \frac{\varepsilon}{2} \int_{\Lambda} \sum_{i=1}^{m} \sum_{k=0}^{s} \sum_{h=1}^{R_h} \left| \phi_i^{(k)}(x) |h|^2 \right| dx = \frac{\varepsilon}{2} \int_{\Lambda} \left\| \phi^{(s)}(x) \right\|^2 dx
\]

for all \(\phi \in C_0^\infty(\Lambda, U)\) and \(|t| \leq \varepsilon_0\) such that

(i) \(u + t \phi\) is admissible for \(F\),

(ii) \(|t||\sigma||\phi^{(s)}(x)|| < \delta\) for all \(x \in \Lambda\) and \(0 \leq \sigma \leq 1\).

Here, \(|| \cdot ||\) denotes the Euclidean norm in \(\mathbb{R}^q\).

**Proof.** Using \((5.5)\) and \((5.6)\), we see that

\[
e(0,t) = \int_{0}^{1} (1 - \sigma) \left[ \delta^2 F(u + \sigma \phi, \phi) - \delta^2 F(u, \phi) \right] d\sigma \\
= \int_{0}^{1} (1 - \sigma) \int_{\Lambda} \phi^{(s)}(x) \left[ A \left( x, u^{(s)}(x) + \sigma \phi^{(s)}(x) \right) \right] T \phi^{(s)}(x) dx d\sigma.
\]
Each entry of the matrix $A$ is a second derivative of the function $L$ with respect to the coordinates in $\Omega$.

Let $\varepsilon > 0$. Since all the second derivatives of $L$ with respect to the variables in $\Omega$ are continuous, then the matrix $A$ is continuous and there exists $\delta > 0$ such that, for all $\phi \in C^2_0(\Lambda, U)$,

$$
\left\| \left( u^{(s)}(x) + t \sigma \phi^{(s)}(x) \right) - u^{(s)}(x) \right\| = |t| \| \sigma \| \left\| \phi^{(s)}(x) \right\| < \delta \implies \|B(x, \sigma, t)\| < \varepsilon
$$

for all $x \in \Lambda$, $|t| \leq \varepsilon_0$ and $0 \leq \sigma \leq 1$, where

$$
B(x, \sigma, t) = A \left( x, u^{(s)}(x) + \sigma t \phi^{(s)}(x) \right) - A \left( x, u^{(s)}(x) \right).
$$

Therefore, using the continuity of the bilinear form induced by the matrix $A$ (see the third property of Lemma 5.4), we obtain the required result:

$$
e(0, t) \leq \varepsilon \int_0^1 (1 - \sigma) d\sigma \int_\Lambda \sum_{j=1}^m \sum_{k=0}^s \sum_{h=1}^p \left| \phi_j(x) [h](x) \right|^2 dx \leq \varepsilon \int_\Lambda \sum_{j=1}^m \sum_{k=0}^s \sum_{h=1}^p \left| \phi_j^h[x](x) \right|^2 dx = \varepsilon \int_\Lambda \left\| \phi^{(s)}(x) \right\|^2 dx.
$$

Here, $\| \cdot \|$ denotes the Euclidean norm in $\mathbb{R}^q$, since $\phi^{(s)}(x) \in \mathbb{R}^q$ for all $x \in \Lambda$.

**Theorem 5.9.** Suppose that $L \in C^2(\Lambda \times \Omega, \mathbb{R})$, and $u \in C^0_0(\Lambda, U)$ is admissible for $\mathcal{F}$.

1. If $u$ is a weak local minimum for $\mathcal{F}$, then for all $\phi \in C^0_0(\Lambda, U)$, we have

$$
\delta \mathcal{F}(u, \phi) = 0 \quad \text{and} \quad \delta^2 \mathcal{F}(u, \phi) \geq 0.
$$

2. If $u$ is a weak local extremum for $\mathcal{F}$ and there is a constant $k > 0$ such that

$$
\delta^2 \mathcal{F}(u, \phi) \geq k \int_\Lambda \left\| \phi^{(s)}(x) \right\|^2 dx
$$

for all $\phi \in C^0_0(\Lambda, U)$, then $u$ is a strict weak local minimum.

**Proof.** For the first part of Theorem 5.9, the assumption that $u$ is a weak local minimum for $\mathcal{F}$ implies that $t = 0$ is a local minimum for the function $\Phi(t) = \mathcal{F}(u + t \phi)$. Consequently, $0 = \Phi'(0) = \delta \mathcal{F}(u, \phi)$. The Taylor expansion (5.3) of $\Phi$ gives

$$
\Phi''(0) = 2 \frac{\Phi(t) - \Phi(0)}{t^2} + 2 e(0, t)
$$

which leads to

$$
0 \leq \lim_{t \to 0} \frac{\Phi(t) - \Phi(0)}{t^2} = \Phi''(0) = \delta^2 \mathcal{F}(u, \phi)
$$

since $\lim_{t \to 0} e(0, t) = 0$ and $\Phi(t) \geq \Phi(0)$ for all $t \neq 0$. 

19
For the second part, we suppose that \( v \in C^1_0(\Lambda, U) \) is admissible for \( F \). Let \( \phi \in C^\infty_0(\Lambda, U) \) so that \( v = u + t \phi \) for some \( t \in \mathbb{R} \) such that \( |t| \leq \varepsilon_0 \). Then

\[
F(v) = F(u + t \phi) = F(u) + t \delta F(u, \phi) + \frac{1}{2} t^2 \delta^2 F(u, \phi) + t^2 e(0, t),
\]

where

\[
e(0, t) = \int_0^1 \left[ \delta^2 F(u + \sigma t \phi, \phi) - \delta^2 F(u, \phi) \right] (1 - \sigma) d\sigma.
\]

By assumption, \( u \) is a weak extremum, so \( \delta F(u, \phi) = 0 \). By Lemma 5.8, there is \( \varepsilon > 0 \) such that

\[
|e(0, t)| \leq \frac{k}{4} \int_{\Lambda} \|\phi^{(s)}(x)\|^2 dx
\]

provided \( |t| \leq \varepsilon \) for all \( x \in \Lambda \) and \( 0 \leq \sigma \leq 1 \). Therefore, using (5.11), if \( \|v - u\|_x = |t| \|\phi\|_x < \varepsilon \) we have

\[
F(v) \geq F(u) + \frac{t^2}{2} \delta^2 F(u, \phi) - t^2 |e(0, t)|
\]

\[\geq F(u) + \frac{kt^2}{2} \int_{\Lambda} \|\phi^{(s)}(x)\|^2 dx - \frac{kt^2}{4} \int_{\Lambda} \|\phi^{(s)}(x)\|^2 dx
\]

\[= F(u) + \frac{kt^2}{4} \int_{\Lambda} \|\phi^{(s)}(x)\|^2 dx.
\]

If \( v \neq u \), i.e. \( \phi \neq 0 \), then the integral on the right hand side is strictly positive, and we have \( F(v) > F(u) \). Therefore \( u \) is a strict weak local minimum. \( \square \)

**Theorem 5.10.** Let \( \Lambda \) be a bounded connected subset of \( X \). Suppose that \( L \in C^2(\Lambda \times \Omega, \mathbb{R}) \), and \( u \in C^1_0(\Lambda, U) \) is admissible for \( F \). If \( u \) is a weak local extremum for \( F \) and

\[
\delta^2 F(u, \phi) \geq 0
\]

(5.12)

for all \( \phi \in C^\infty_0(\Lambda, U) \), then \( u \) is a weak local minimum.

**Proof.** Let \( \varepsilon > 0 \). Suppose that \( v \in C^1_0(\Lambda, U) \) is admissible for \( F \). Let \( \phi \in C^\infty_0(\Lambda, U) \) so that \( v = u + t \phi \) for some \( t \in \mathbb{R} \) such that \( |t| \leq \varepsilon_0 \). Then

\[
F(v) = F(u + t \phi) = F(u) + t \delta F(u, \phi) + \frac{1}{2} t^2 \delta^2 F(u, \phi) + t^2 e(0, t),
\]

where

\[
e(0, t) = \int_0^1 \left[ \delta^2 F(u + \sigma t \phi, \phi) - \delta^2 F(u, \phi) \right] (1 - \sigma) d\sigma.
\]

By assumption, \( u \) is a weak extremum, so \( \delta F(u, \phi) = 0 \). By Lemma 5.8, there is \( \varepsilon > 0 \) such that

\[
|e(0, t)| \leq \frac{\varepsilon}{2} \int_{\Lambda} \|\phi^{(s)}(x)\|^2 dx \leq \frac{\varepsilon}{2} \text{mes}(\Lambda) \|\phi\|^2_x
\]

20
provided \(|t| ||σ|| |ϕ^{(s)}(x)|| < ε\) for all \(x \in Λ\) and \(0 ≤ σ ≤ 1\). Therefore, using \((5.12)\), if \(\|v - u\|_x = |t| ||ϕ||_x < ε\) with \(ϕ ≠ 0\), we have
\[
F(v) ≥ F(u) + \frac{t^2}{2} δ^2 F(u, ϕ) - t^2 |e(0, t)|
\]
\[
≥ F(u) - \frac{ε}{2} t^2 \text{mes}(Λ) \|ϕ\|^2_x
\]
\[
≥ F(u) - \frac{ε}{2} t^2 \text{mes}(Λ).
\]
Thus,
\[
F(v) ≥ F(u) - \lim_{ε→0} \left[ \frac{ε}{2} t^2 \text{mes}(Λ) \right] = F(u).
\]
We have \(F(v) ≥ F(u)\). Therefore \(u\) is a weak local minimum. □

In part (1) of Theorem \[5.9\] the fact that the second variations must be nonnegative is a necessary condition for \(u\) to be a local minimum.

### 5.1 Legendre necessary conditions

According to Theorem \[5.9\] if \(u\) is a weak local minimum for the functional \(F\), then \(δ^2 F(u, ϕ) ≥ 0\) for all \(ϕ ∈ C_0^∞(Λ, U)\). Here we find some natural and nontrivial consequences of that condition.

Construct nonzero functions \(ψ_l\) by \(ψ_0 = 1\) and for \(l = 1, 2, \ldots, s\)
\[
ψ_l(y) = \begin{cases} 0 & -∞ < y ≤ -1 \\ 1 - y^l \text{sign}(y) & -1 ≤ y ≤ +1 \\ 0 & +1 ≤ y < +∞ 
\end{cases}
\]
if \(l\) is odd, and
\[
ψ_l(y) = \begin{cases} 0 & -∞ < y ≤ -1 \\ 1 - y^l & -1 ≤ y ≤ +1 \\ 0 & +1 ≤ y < +∞ 
\end{cases}
\]
if \(l\) is even.

It is clear that \(ψ_l ∈ C^∞(R \setminus \{-1, 1\}, R)\) and satisfy \(ψ_l(y) = 0\) for all \(y\) with \(|y| > 1\), i.e. \(ψ_l ∈ C_0^∞(R \setminus \{-1, 1\}, R)\). Furthermore, \(ψ_l ∈ C(R, R)\) with \(ψ_l(-1) = ψ_l(1) = 0\). We also have
\[
(ψ_l)_{(l)}[1](y) \in \{-l!, 0, +l!\} \quad ∀ y ∈ R\quad(5.13)
\]
that is \((ψ_l)_{(l)}[1]\) is constant on \(R\). Thus,
\[
(ψ_l)_{(l+ν)}[1](y) = 0 \quad ∀ y ∈ R, ν ≥ 1.
\]
Let \(x_0 = (x_0^1, \ldots, x_0^n) ∈ Λ\). Since \(Λ\) is an open subset of \(R^n\), there is \(r_0 > 0\) such that \(B(x_0, r_0) = \{x ∈ R^n : ||x - x_0|| < r_0\} ⊂ Λ\). Let \(ξ = (ξ^1, \ldots, ξ^m) ∈ R^m\) and \(0 < ε < \frac{r_0}{\sqrt{n}}\).
Set $\phi_l(x) = (\phi_1^l(x), \ldots, \phi_n^l(x)) \cdot X_{B(x_0,r_0)}(x)$ where $X_{B(x_0,r_0)}$ is the characteristic function of the set $B(x_0,r_0)$ and
\[ \phi_j^l(x) = \xi^j x^l \sum_{t=1}^n \psi_t \left( \frac{x_t - x_0^t}{\epsilon} \right). \] (5.15)

Clearly, the support of $\phi_l$ is a compact contained in $\Lambda$. We have for all $k \in \mathbb{N}$ and $h = 1, 2, \ldots, p_k$
\[ \left( \phi_j^l \right)_{(k)} [h](x) = \xi^j x^l \psi_t \left( \frac{x^l - x_0^l}{\epsilon} \right). \] (5.16)

for some $i(h) \in \{1, 2, \ldots, n\}$. Using (5.13) and (5.14), we see that
\[ \phi_j^l [h] \in \{-\xi^j I! 0, +\xi^j I! \} \quad \forall h = 1, 2, \ldots, p_l \] (5.17)

and for $\nu \geq 1$
\[ \phi_j^l [h] = 0 \quad \forall h = 1, 2, \ldots, p_l + \nu. \] (5.18)

Therefore, if $u$ is a weak local minimum for the functional $\mathcal{F}$, we have for all $l = 0, 1, 2, \ldots, s$
\[ 0 \leq \delta^2 \mathcal{F}(u, \phi_l) = I_1 + I_2 + I_3, \] (5.19)

where
\[ I_1 = \int_{|x-x_0| \leq r_0} \sum_{j,k=1}^{m} \sum_{h=1}^{p_0} \sum_{k'=1}^{p_1} \frac{\partial^2 L(x, u^{(s)})}{\partial u_{(k)}[h] \partial u_{(k')}[h']} \] \(\times \) \left( \phi_j^l \right)_{(k)} [h](x) \left( \phi_j^{l'} \right)_{(k')} [h'](x) dx; \] (5.20)

\[ I_2 = \int_{|x-x_0| \leq r_0} \sum_{j,k=1}^{m} \sum_{h=1}^{p_0} \sum_{k'=1}^{p_1} \left( \phi_j^l \right)_{(l)} [h](x) \left( \phi_j^{l'} \right)_{(l)} [h'](x) \frac{\partial^2 L(x, u^{(s)})}{\partial u_{(l)}[h] \partial u_{(l')}[h']} \] \(\times \) \left( \phi_j^l \right)_{(k)} [h](x) \left( \phi_j^{l'} \right)_{(k')} [h'](x) dx; \] (5.21)

\[ I_3 = 2 \int_{|x-x_0| \leq r_0} \sum_{j,k=1}^{m} \sum_{h=1}^{l-1} \sum_{k'=1}^{l} \sum_{h'=1}^{l} \sum_{k'=1}^{p_1} \frac{\partial^2 L(x, u^{(s)})}{\partial u_{(l)}[h] \partial u_{(l')}[h']} \] \(\times \) \left( \phi_j^l \right)_{(k)} [h](x) \left( \phi_j^{l'} \right)_{(k')} [h'](x) dx. \] (5.22)

Of course, if $l = 0$ there is not the integral $I_3$. If $s = 0 I_1$ and $I_3$ do not exist. By (5.18), we see that $I_1 = 0$. Using (5.15) and (5.16) in (5.21), we have
\[ I_2 = \int_{|x-x_0| \leq r_0} \sum_{j,k=1}^{m} \xi_j x^l \sum_{h=1}^{p_0} \frac{\partial^2 L(x, u^{(s)})}{\partial u_{(l)}[h] \partial u_{(l')}[h']} \] \(\times \) \left( \psi_t \right)_{(l)} [1] \left( \frac{x^l - x_0^l}{\epsilon} \right) dx. \] (5.23)
If we set \( x = x_0 + \varepsilon y \) then \( dx = \varepsilon^n dy \) and using (5.13), \( I_2 \) satisfies

\[
I_2 \leq \varepsilon^n (l!)^2 \int_{|y| \leq 1} \sum_{j,j' = 1}^{m} \xi_j^j \xi_j^{j'} \left( \sum_{h,h' = 1}^{p_l} \frac{\partial^2 L(x_0 + \varepsilon y, u^{(s)}(x_0 + \varepsilon y))}{\partial u^{(l)}_h [h] \partial u^{(l)}_{h'} [h']} \right) dy. \tag{5.24}
\]

In a similar way, \( I_3 \) becomes

\[
I_3 = 2\varepsilon^n \varepsilon^{2l-(k+k')} \int_{|y| \leq 1} \sum_{j,j' = 1}^{m} \xi_j^j \xi_j^{j'} \left( \sum_{k=0}^{l-1} \sum_{k'=k+1}^{l} \sum_{h=1}^{p_k} \sum_{h'=1}^{p_{k'}} (\psi_l)_k \left[\psi_{l'}(k') \right] \frac{\partial^2 L(x_0 + \varepsilon y, u^{(s)}(x_0 + \varepsilon y))}{\partial u^{(l)}_h [h] \partial u^{(l')}_{h'} [h']} \right) \right) dy. \tag{5.25}
\]

Substituting (5.24) and (5.25) into (5.19), we have

\[
0 \leq \sum_{j,j' = 1}^{m} \xi_j^j \xi_j^{j'} \left[ (l!)^2 \int_{|y| \leq 1} \sum_{h,h' = 1}^{p_l} \frac{\partial^2 L(x_0 + \varepsilon y, u^{(s)}(x_0 + \varepsilon y))}{\partial u^{(l)}_h [h] \partial u^{(l)}_{h'} [h']} dy \right]
\]

\[
+ \varepsilon^{2l-(k+k')} \int_{|y| \leq 1} \sum_{k=0}^{l-1} \sum_{k'=k+1}^{l} \sum_{h=1}^{p_k} \sum_{h'=1}^{p_{k'}} (\psi_l)_k \left[\psi_{l'}(k') \right] \frac{\partial^2 L(x_0 + \varepsilon y, u^{(s)}(x_0 + \varepsilon y))}{\partial u^{(l)}_h [h] \partial u^{(l')}_{h'} [h']} \right] dy \right). \tag{5.26}
\]

We have \( \varepsilon^{2l-(k+k')} \longrightarrow 0 \) as \( \varepsilon \to 0 \) since in \( I_3, 2l - (k + k') \geq 1 \).

Therefore, as \( \varepsilon \to 0 \), the second term in (5.26) vanishes and it remains

\[
0 \leq (l!)^2 \sum_{j,j' = 1}^{m} \xi_j^j \xi_j^{j'} \left( \sum_{h,h' = 1}^{p_l} \frac{\partial^2 L(x_0, u^{(s)}(x_0))}{\partial u^{(l)}_h [h] \partial u^{(l)}_{h'} [h']} \right) \int_{|y| \leq 1} dy \tag{5.27}
\]

from which we deduce

\[
\sum_{j,j' = 1}^{m} \left( \sum_{h,h' = 1}^{p_l} \frac{\partial^2 L(x_0, u^{(s)}(x_0))}{\partial u^{(l)}_h [h] \partial u^{(l)}_{h'} [h']} \right) \xi_j^j \xi_j^{j'} \geq 0. \tag{5.28}
\]

Since \( x_0 \in \Lambda \) and \( \xi \in \mathbb{R}^m \) are arbitrary, we have proved the following theorem

**Theorem 5.11.** Suppose that \( L \in C^2(\Lambda \times \Omega, \mathbb{R}) \), and \( \overline{\pi} \) is a weak local minimum for \( \mathcal{F} \).

Then for all \( x \in \Lambda \) and \( \xi = (\xi^1, \cdots, \xi^m) \in \mathbb{R}^m \),

\[
\sum_{j,j' = 1}^{m} \left( \sum_{h,h' = 1}^{p_l} \frac{\partial^2 L(x, \overline{\pi}^{(s)}(x))}{\partial u^{(l)}_h [h] \partial u^{(l)}_{h'} [h']} \right) \xi_j^j \xi_j^{j'} \geq 0 \quad l = 0, 1, 2, \cdots, s, \tag{5.29}
\]

i.e. for all \( x \in \Lambda \), the square matrices \( A_l^{jj'}(x, \overline{\pi}^{(s)}(x)) \), \( l = 0, 1, 2, \cdots, s \), are positive semi-definite.
The inequalities in (5.29) are called the general forms of Legendre conditions. They define by Theorem 5.11 new necessary conditions for \( \pi \) to be a weak local minimum of \( \mathcal{F} \). We say that the function \( \pi \) satisfies the strict Legendre conditions if the matrices \( A_{ij}^{(s)}(x, \pi(x)) \), \( i = 0, 1, 2, \ldots, s \), are positive definite, uniformly for all \( x \in \Lambda \).

### 5.2 Relevant sufficient conditions

Part (2) of Theorem 5.9 gives us a sufficient condition for a function to be a minimum. However, the conditions involving the second variations are not easy to satisfy. So, the results of this subsection are useful as they imply the condition (5.11).

**Theorem 5.12.** Suppose that \( L \in C^2(\Lambda \times \Omega, \mathbb{R}) \), and \( u \) is a weak local extremum for \( \mathcal{F} \). If the matrix \( A(x, u^{(s)}(x)) \) defined by (5.7) is positive definite for all \( x \in \Lambda \), then \( u \) is a strict weak local minimum.

**Proof.** By (5.6), (5.8) and Lemma 5.1 for all \( \phi \in C^0_0(\Lambda, U) \) we have

\[
\delta^2 \mathcal{F}(u, \phi) = \int_\Lambda \phi^{(s)}(x) A(x, u^{(s)}(x)) T \phi^{(s)}(x) dx \geq k \int_\Lambda \| \phi^{(s)}(x) \|^2 dx
\]

for some \( k > 0 \). By part (2) of Theorem 5.9 \( u \) is a strict weak minimum for \( \mathcal{F} \).

**Theorem 5.13.** Let \( \Lambda \) be a bounded connected subset of \( X \). Suppose that \( L \in C^2(\Lambda \times \Omega, \mathbb{R}) \), and \( u \) is a weak local extremum for \( \mathcal{F} \). If the matrix \( A(x, u^{(s)}(x)) \) defined by (5.7) is semi-positive definite for all \( x \in \Lambda \), then \( u \) is a weak local minimum.

**Proof.** By hypothesis, the function \( V(x, \phi) = \phi^{(s)}(x) A(x, u^{(s)}(x)) T \phi^{(s)}(x) \) is continuous and positive on \( \Lambda \) for all \( \phi \in C^0_0(\Lambda, U) \). Therefore, by (5.6) and (5.8), for all \( \phi \in C^0_0(\Lambda, U) \), we have

\[
\delta^2 \mathcal{F}(u, \phi) = \int_\Lambda \phi^{(s)}(x) A(x, u^{(s)}(x)) T \phi^{(s)}(x) dx \geq 0.
\]

Thus, by Theorem 5.10 \( u \) is a weak minimum for \( \mathcal{F} \).

The second variation of \( \mathcal{F} \) is given by

\[
\delta^2 \mathcal{F}(u, \phi) = \int_\Lambda \sum_{j,k=1}^m \sum_{k'=0}^s \phi_j^{(k)}(x) A_{kk'}^{ij} T \phi_{j}^{(k')}(x) dx
\]

\[
= \int_\Lambda \sum_{j,k=1}^m \sum_{k'=0}^s \left[ \phi_j^{(k)} A_{kk'}^{ij} T \phi_j^{(k')} + 2 \sum_{k''=0}^s \phi_j^{(k)} A_{kk'}^{ij} \phi_j^{(k'')} \right] dx
\]

\[
= I_1 + 2I_2,
\]

where the matrices \( A_{kk'}^{ij}(x, u^{(s)}(x)) \) are defined by (5.2) and

\[
I_1 = \int_\Lambda \sum_{j,k=1}^m \sum_{k'=0}^s \phi_j^{(k)} A_{kk'}^{ij} T \phi_j^{(k')} dx; \quad (5.30)
\]

\[
I_1 = \int_\Lambda \sum_{j,k=1}^m \sum_{k'=0}^s \phi_j^{(k)} A_{kk'}^{ij} T \phi_j^{(k')} dx; \quad (5.31)
\]
Thus, the second variation can be written as

\[ I_2 = \int_\Lambda \sum_{j,j'=1}^m \sum_{k=0}^s \sum_{\nu \neq \kappa}^s \phi_{(k)}^{jj'} A_{kk}^{jj'} \Phi_{(k)}^{jj'} dx. \]  

(5.32)

Integral \( I_1 \) can be rewritten as

\[
I_1 = \int_\Lambda \sum_{j=1}^m \left[ \sum_{k=0}^s \phi_{(k)}^{jj} A_{kk}^{jj} \Phi_{(k)}^{jj} + 2 \sum_{j'=1}^m \sum_{k=0}^s \phi_{(k)}^{jj'} A_{kk}^{jj'} \Phi_{(k)}^{jj'} \right] dx
= J_1 + 2J_2,
\]

(5.33)

\[
J_1 = \int_\Lambda \sum_{j=1}^m \sum_{k=0}^s \phi_{(k)}^{jj} A_{kk}^{jj} \Phi_{(k)}^{jj} dx;
\]

(5.34)

\[
J_2 = \int_\Lambda \sum_{j=1}^m \sum_{j'=1}^m \sum_{k=0}^s \phi_{(k)}^{jj'} A_{kk}^{jj'} \Phi_{(k)}^{jj'} dx.
\]

(5.35)

Thus, the second variation can be written as

\[
\delta^2 F(u, \phi) = I_1 + 2I_2 = J_1 + 2J_2 + 2I_2 = J_1 + 2(J_2 + I_2).
\]

(5.36)

We can now prove the following new sufficient condition.

**Theorem 5.14.** Suppose that \( L \in C^2(\Lambda \times \Omega, \mathbb{R}) \), and \( u \) is a weak local extrema for \( F \). If

(i) \( J_2 + I_2 \geq 0 \), and

(ii) the square matrices \( A_{kk}^{jj'}(x, u^{(s)}(x)) \) are positive definite for all \( x \in \Lambda \), i.e., satisfy the strict Legendre conditions,

then \( u \) is a strict weak local minimum for \( F \).

**Proof.** We have shown that

\[
\delta^2 F(u, \phi) = J_1 + 2(J_2 + I_2),
\]

(5.37)

where \( J_1, J_2 \) and \( I_2 \) are defined by (5.34), (5.35) and (5.32), respectively. By condition (ii), using the Lemma 5.7, there exist constants \( \alpha_j^k > 0 \) such that

\[
J_1 \geq \int_\Lambda \sum_{j=1}^m \sum_{k=0}^s \alpha_j^k \phi_{(k)}^{jj} \Phi_{(k)}^{jj} \phi_{(k)}^{jj} dx
\]

\[
\geq \alpha \int_\Lambda \sum_{j=1}^m \sum_{k=0}^s \sum_{h=1}^s \phi_{(k)}^{jj} \phi_{(k)}^{jj} \left( \phi_{(k)}^{jj} \phi_{(k)}^{jj} \right) dx
\]

\[
= \alpha \int_\Lambda \left\| \phi_{(s)}(x) \right\|^2 dx,
\]

(5.38)

where \( 0 < \alpha = \min \left\{ \alpha_j^k, 1 \leq j \leq m, 0 \leq k \leq s \right\} \). By condition (i) and the inequality (5.38), the second variation (5.37) satisfies for all \( \phi \in C_0^\infty(\Lambda, U) \) the inequality

\[
\delta^2 F(u, \phi) \geq \alpha \int_\Lambda \left\| \phi_{(s)}(x) \right\|^2 dx.
\]

(5.39)

Consequently, by the second part of Theorem 5.9, \( u \) is a weak minimum for \( F \).
Corollary 5.15. Suppose that $L \in C^2(\Lambda \times \Omega, \mathbb{R})$, $u$ is a weak extremum for $\mathcal{F}$. If

(a) for all $k \neq k'$, the bilinear forms defined on $\mathbb{R}^{p_k} \times \mathbb{R}^{p_{k'}}$ by the matrices $A_{kk'}^{ij}(x, u^{(s)}(x))$ are positive for all $x \in \Lambda$, and

(b) the square matrices $A_{kk'}^{ij}(x, u^{(s)}(x))$ are positive definite for all $x \in \Lambda$,

then $u$ is a strict weak local minimum for $\mathcal{F}$.

Proof. It suffices to show that condition (i) in Theorem 5.14 is satisfied. We have

$$J_2 = \int_{\Lambda} \sum_{j=1}^{m} \sum_{j'=1}^{m} \sum_{k=0}^{s} \sum_{k'=0}^{s} p_j \phi_j^{(i)} [h] A_{kk'}^{ij} [h, h']^T \phi_j^{(i')} [h'] dx \geq 0 \quad (5.40)$$

since by condition (b) the integrand is always positive;

$$I_2 = \int_{\Lambda} \sum_{j,j'=1}^{m} \sum_{j'=1}^{m} \sum_{k=0}^{s} \sum_{k'=0}^{s} p_j \phi_j^{(i)} [h] A_{kk'}^{ij} [h, h']^T \phi_j^{(i')} [h'] dx, \quad (5.41)$$

since by condition (a) the integrand is always positive. Therefore $J_2 + I_2 \geq 0$.

6 Applications

To conclude this work, let us analyze some applications.

Example 6.1. Consider the problem of finding extremum point $u = u(x)$ with $x \in [a, b]$, of the functional $\mathcal{F}$ defined by

$$\mathcal{F}(u) = \int_{a}^{b} \sqrt{1 + u_x(x)^2} dx.$$

The Lagrangian of this functional is

$$L(x, u^{(1)}) = \sqrt{1 + u_x^2}.$$

The extremum must satisfy the Euler-Lagrange equation

$$\frac{\partial L}{\partial u} - \frac{d}{dx} \left( \frac{\partial L}{\partial u_x} \right) = 0$$

which gives

$$\frac{u_{xx}}{(1 + u_x^2)^{3/2}} = 0.$$

The general solution of this equation is $u(x) = c_1 x + c_2$, where $c_1$ and $c_2$ are constants determined by the given end point constraints.

Determine the matrix $A$ associated to the second variation of this problem.

$$A = \begin{bmatrix} A_{00} & A_{01} \\ A_{10} & A_{11} \end{bmatrix},$$
where
\[ A_{00} = \frac{\partial^2 L}{\partial u \partial u} = 0, \quad A_{01} = \frac{\partial^2 L}{\partial u \partial u_x} = 0, \quad A_{10} = \frac{\partial^2 L}{\partial u_x \partial u} = 0, \quad A_{11} = \frac{\partial^2 L}{\partial u_x \partial u_x} = \frac{1}{(1 + u_x^2)^{\frac{3}{2}}}. \]

Thus,
\[ A = \begin{bmatrix} 0 & 0 \\ 0 & \frac{1}{(1 + u_x^2)^{\frac{3}{2}}} \end{bmatrix}. \]

It is clear that the matrix \( A \) is positive semi-definite. Therefore, the found function \( u \), solution to the Euler-Lagrange equation, is a minimum point to the functional \( F \).

Note here that the Legendre necessary conditions are well satisfied. Indeed, \( A_{00} \geq 0 \) and \( A_{11} \geq 0 \).

**Example 6.2.** Consider the problem of finding extremum point \( u = u(x) \) with \( x \in [a, b] \), of the functional \( F \) defined by
\[ F(u) = \int_a^b u(x) \sqrt{1 + u_x(x)^2} \, dx. \]

The Lagrangian of this functional is
\[ L(x, u^{(1)}) = u \sqrt{1 + u_x^2}. \]

The extremum must satisfy the Euler-Lagrange equation
\[ \frac{\partial L}{\partial u} - \frac{d}{dx} \left( \frac{\partial L}{\partial u_x} \right) = 0 \]
which gives
\[ \frac{1 + u_x^2 - uu_{x,x}}{(1 + u_x^2)^{\frac{3}{2}}} = 0. \]

The general solution of this equation is \( u(x) = c_1 \cosh \left( \frac{x + c_2}{c_1} \right) \), where \( c_1 \) and \( c_2 \) are constants determined by the given end conditions.

Determine the matrix \( A \) associated with the second variation of this problem.
\[ A = \begin{bmatrix} A_{00} & A_{01} \\ A_{10} & A_{11} \end{bmatrix}, \]
where
\[ A_{00} = \frac{\partial^2 L}{\partial u \partial u} = 0, \quad A_{01} = \frac{\partial^2 L}{\partial u \partial u_x} = \frac{u_x}{\sqrt{1 + u_x^2}}, \quad A_{10} = \frac{\partial^2 L}{\partial u_x \partial u} = \frac{u_x}{\sqrt{1 + u_x^2}}, \quad A_{11} = \frac{\partial^2 L}{\partial u_x \partial u_x} = \frac{u_x}{(1 + u_x^2)^{\frac{3}{2}}}. \]
Thus, \[
A = \begin{bmatrix}
0 & \frac{\mu_0}{\sqrt{1+\mu_0^2}} \\
\frac{\mu_0}{\sqrt{1+\mu_0^2}} & \frac{\mu_1}{(1+\mu_0^2)^2}
\end{bmatrix}.
\]

It is clear that the matrix \(A\) is neither positive semi-definite nor negative semi-definite (i.e., \(-A\) is not positive semi-definite). Hence, the found function \(u\), solution to the Euler-Lagrange equation, is neither a minimum point nor a maximum point to the functional \(\mathcal{F}\). Therefore, we can conclude that this function \(u\) is an unstable equilibrium point.

**Example 6.3.** Let \(\Lambda\) be a connected subset of \(\mathbb{R}^2\). Consider the problem of finding the function \((u^1, u^2)\), where \(u^1 = u^1(x^1, x^2)\), \(u^2 = u^2(x^1, x^2)\) with \((x^1, x^2) \in \Lambda\), which is an extremum of the functional \(\mathcal{F}\) defined by

\[
\mathcal{F}(u^1, u^2) = \int_\Lambda L\left(x^1, x^2, u^{1(1)}(x^1, x^2), u^{2(1)}(x^1, x^2)\right) \, dx^1 \, dx^2,
\]

where the Lagrangian \(L\) is

\[
L = (u^1)^2 + (u^2)^2 + (u^1_x)^2 + (u^2_x)^2 + (u^1_{xx})^2 + \frac{1}{2} (u^1 u^2 - u^1_x u^2_x - u^1_x u^2_x).
\]

Extremum of the functional \(\mathcal{F}\) must satisfy the Euler-Lagrange equations

\[
\frac{\partial L}{\partial u^1} - \frac{\partial}{\partial x^1}\left(\frac{\partial L}{\partial u^1_x}\right) - \frac{\partial}{\partial x^2}\left(\frac{\partial L}{\partial u^1_{xx}}\right) = 0
\]

\[
\frac{\partial L}{\partial u^2} - \frac{\partial}{\partial x^1}\left(\frac{\partial L}{\partial u^2_x}\right) - \frac{\partial}{\partial x^2}\left(\frac{\partial L}{\partial u^2_{xx}}\right) = 0
\]

which give the system

\[
2u^1 + \frac{1}{2} u^2 - 2u^1_{x^1} + u^1_{x^1 x^2} - 2u^1_{x^2} = 0
\]

\[
2u^2 + \frac{1}{2} u^1 - 2u^2_{x^1} + u^2_{x^1 x^2} - 2u^2_{x^2} = 0.
\]

The general solution to this system is

\[
u^1(x^1, x^2) = c_5 e^{-\frac{c_3}{2} x^1} + c_6 e^{-\frac{c_3}{2} x^2} + c_7 e^{-\frac{c_3}{2} (x^1 + x^2)} + c_8 e^{-\frac{c_3}{2} (x^1 - x^2)}
\]

\[
- \left( c_1 e^{-\frac{c_3}{2} x^1} + c_2 e^{-\frac{c_3}{2} x^2} + c_3 e^{-\frac{c_3}{2} (x^1 + x^2)} + c_4 e^{-\frac{c_3}{2} (x^1 - x^2)} \right)
\]

\[
u^2(x^1, x^2) = c_1 e^{-\frac{c_3}{2} x^1} + c_2 e^{-\frac{c_3}{2} x^2} + c_3 e^{-\frac{c_3}{2} (x^1 + x^2)} + c_4 e^{-\frac{c_3}{2} (x^1 - x^2)}
\]

\[
+ c_5 e^{-\frac{c_3}{2} x^1} + c_6 e^{-\frac{c_3}{2} x^2} + c_7 e^{-\frac{c_3}{2} (x^1 + x^2)} + c_8 e^{-\frac{c_3}{2} (x^1 - x^2)},
\]

where the constants \(c_i\) are determined by the given boundary conditions.

Determine the matrix \(A\) associated with the second variation of the functional \(\mathcal{F}\).

\[
A = \begin{bmatrix}
A^{11} & A^{12} \\
A^{21} & A^{22}
\end{bmatrix}
\]

28
with $A^{ij}$ defined by

$$A^{ij} = \begin{bmatrix} A_{00}^{ij} & A_{01}^{ij} \\ A_{10}^{ij} & A_{11}^{ij} \end{bmatrix}.$$ 

We have:

$$A_{00}^{11} = \frac{\partial^2 L}{\partial u^1 \partial u^1} = 2, \quad A_{00}^{12} = \frac{\partial^2 L}{\partial u^1 \partial u^2} = \frac{1}{2},$$

$$A_{01}^{21} = \frac{\partial^2 L}{\partial u^2 \partial u^1} = \frac{1}{2}, \quad A_{00}^{22} = \frac{\partial^2 L}{\partial u^2 \partial u^2} = 2,$$

$$A_{10}^{11} = \begin{bmatrix} \frac{\partial^2 L}{\partial u^1_{j} \partial u^1_{i}} \\ \frac{\partial^2 L}{\partial u^2_{i} \partial u^1_{j}} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}, \quad A_{10}^{12} = \begin{bmatrix} \frac{\partial^2 L}{\partial u^1_{j} \partial u^2_{i}} \\ \frac{\partial^2 L}{\partial u^2_{i} \partial u^2_{j}} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix},$$

$$A_{10}^{21} = \begin{bmatrix} \frac{\partial^2 L}{\partial u^1_{j} \partial u^1_{i}} \\ \frac{\partial^2 L}{\partial u^2_{i} \partial u^1_{j}} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}, \quad A_{10}^{22} = \begin{bmatrix} \frac{\partial^2 L}{\partial u^1_{j} \partial u^2_{i}} \\ \frac{\partial^2 L}{\partial u^2_{i} \partial u^2_{j}} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix},$$

$$A_{00}^{11} = \begin{bmatrix} \frac{\partial^2 L}{\partial u^1_{j} \partial u^1_{i}} \\ \frac{\partial^2 L}{\partial u^2_{i} \partial u^1_{j}} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}, \quad A_{00}^{12} = \begin{bmatrix} \frac{\partial^2 L}{\partial u^1_{j} \partial u^2_{i}} \\ \frac{\partial^2 L}{\partial u^2_{i} \partial u^2_{j}} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix},$$

$$A_{01}^{21} = \begin{bmatrix} \frac{\partial^2 L}{\partial u^1_{j} \partial u^1_{i}} \\ \frac{\partial^2 L}{\partial u^2_{i} \partial u^1_{j}} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}, \quad A_{01}^{22} = \begin{bmatrix} \frac{\partial^2 L}{\partial u^1_{j} \partial u^2_{i}} \\ \frac{\partial^2 L}{\partial u^2_{i} \partial u^2_{j}} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix},$$

$$A_{11}^{12} = \begin{bmatrix} \frac{\partial^2 L}{\partial u^1_{i} \partial u^1_{j}} & \frac{\partial^2 L}{\partial u^2_{i} \partial u^1_{j}} \\ \frac{\partial^2 L}{\partial u^1_{j} \partial u^1_{i}} & \frac{\partial^2 L}{\partial u^2_{j} \partial u^1_{i}} \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix},$$

$$A_{11}^{21} = \begin{bmatrix} \frac{\partial^2 L}{\partial u^1_{i} \partial u^1_{j}} & \frac{\partial^2 L}{\partial u^2_{i} \partial u^1_{j}} \\ \frac{\partial^2 L}{\partial u^1_{j} \partial u^1_{i}} & \frac{\partial^2 L}{\partial u^2_{j} \partial u^1_{i}} \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix},$$

$$A_{11}^{11} = \begin{bmatrix} \frac{\partial^2 L}{\partial u^1_{i} \partial u^1_{j}} & \frac{\partial^2 L}{\partial u^2_{i} \partial u^1_{j}} \\ \frac{\partial^2 L}{\partial u^1_{j} \partial u^1_{i}} & \frac{\partial^2 L}{\partial u^2_{j} \partial u^1_{i}} \end{bmatrix} = \begin{bmatrix} 2 & -\frac{1}{2} \\ -\frac{1}{2} & 2 \end{bmatrix},$$

$$A_{11}^{22} = \begin{bmatrix} \frac{\partial^2 L}{\partial u^1_{i} \partial u^1_{j}} & \frac{\partial^2 L}{\partial u^2_{i} \partial u^1_{j}} \\ \frac{\partial^2 L}{\partial u^1_{j} \partial u^1_{i}} & \frac{\partial^2 L}{\partial u^2_{j} \partial u^1_{i}} \end{bmatrix} = \begin{bmatrix} 2 & -\frac{1}{2} \\ -\frac{1}{2} & 2 \end{bmatrix},$$

which give

$$A^{12} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} = A^{21}, \quad A^{11} = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & -\frac{1}{2} \\ 0 & -\frac{1}{2} & 2 \end{bmatrix} = A^{22},$$

and hence

$$A = \begin{bmatrix} 2 & 0 & 0 & \frac{1}{2} & 0 & 0 \\ 0 & 2 & -\frac{1}{2} & 2 & 0 & 0 \\ 0 & -\frac{1}{2} & 2 & 0 & 0 & 0 \\ \frac{1}{2} & 0 & 0 & 2 & 0 & 0 \\ 0 & 0 & 0 & 2 & -\frac{1}{2} \\ 0 & 0 & 0 & -\frac{1}{2} & 2 \end{bmatrix}. $$
It is easy to see that the matrices $A_{kk}^{ij}$, $k = 0, 1$, are all semi-positive definite. This implies that the Legendre necessary conditions for minimum point are satisfied. Furthermore, the matrix $A$ is positive definite. Thus, we can well conclude that the found solution $(u^1, u^2)$ to the Euler-Lagrange equations is effectively a minimum point for the functional $\mathcal{F}$.

**Example 6.4.** Let $\Lambda$ be a connected subset of $\mathbb{R}^2$. Consider the problem of finding a function $u = u(x^1, x^2)$ with $(x^1, x^2) \in \Lambda$, which is an extremum of the functional $\mathcal{F}$ defined by

$$\mathcal{F}(u) = \int_{\Lambda} L\left(x^1, x^2, u^{(2)}(x^1, x^2)\right) dx^1 dx^2$$

whose Lagrangian $L$ is

$$L = u^2 + u_{x^1}^2 + u_{x^2}^2 + u_{x^1 x^2}^2 + u_{x^2 x^2}^2 - \frac{1}{2} (u_{x^1} u_{x^2} + u_{x^2} u_{x^1} + u_{x^1} u_{x^1} u_{x^2} + u_{x^2} u_{x^2} + u_{x^1} u_{x^2} u_{x^2}).$$

(6.1)

The extremum must satisfy the Euler-Lagrange equation

$$0 = \frac{\partial L}{\partial u} - \frac{\partial}{\partial x^1}\left(\frac{\partial L}{\partial u_{x^1}}\right) - \frac{\partial}{\partial x^2}\left(\frac{\partial L}{\partial u_{x^2}}\right) + \frac{\partial}{\partial x^1}\frac{\partial}{\partial x^2}\left(\frac{\partial L}{\partial u_{x^1 x^2}}\right)$$

$$+ \frac{\partial}{\partial x^1}\frac{\partial}{\partial x^2}\left(\frac{\partial L}{\partial u_{x^2 x^2}}\right)$$

(6.2)

which gives the equation

$$2u - 2u_{x^1} + u_{x^1 x^2} - 2u_{x^2} + 2u_{x^1} - u_{x^1 x^2} + u_{x^2 x^2} - u_{x^1} - u_{x^2} = 0.$$ 

The general solution to this equation is

$$u(x^1, x^2) = e^{-\frac{\sqrt{2}}{2}x^1}\left[c_1 \cos\left(\frac{1}{2}x^1\right) + c_2 \sin\left(\frac{1}{2}x^1\right)\right]$$

$$+ e^{\frac{\sqrt{2}}{2}x^1}\left[c_3 \cos\left(\frac{1}{2}x^1\right) + c_4 \sin\left(\frac{1}{2}x^1\right)\right]$$

$$+ e^{-\frac{\sqrt{2}}{2}x^2}\left[c_5 \cos\left(\frac{1}{2}x^2\right) + c_6 \sin\left(\frac{1}{2}x^2\right)\right]$$

$$+ e^{\frac{\sqrt{2}}{2}x^2}\left[c_7 \cos\left(\frac{1}{2}x^2\right) + c_8 \sin\left(\frac{1}{2}x^2\right)\right],$$

where the constants $c_i$ are determined by the boundary conditions.

Determine the matrix $A$ associated with the second variation of $\mathcal{F}$:

$$A = \begin{bmatrix} A_{00} & A_{01} & A_{02} \\ A_{10} & A_{11} & A_{12} \\ A_{20} & A_{21} & A_{22} \end{bmatrix},$$

where

$$A_{00} = \frac{\partial^2 L}{\partial u^2} = 2, \quad A_{02} = \begin{bmatrix} \frac{\partial^2 L}{\partial u_{x^1}^2} & \frac{\partial^2 L}{\partial u_{x^1} x^2} & \frac{\partial^2 L}{\partial u_{x^2} x^2} \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 \end{bmatrix}.$$
Thus, matrix the Legendre necessary conditions for minimum point are satisfied. Furthermore, the Euler-Lagrange equations is effectively a minimum point for the functional $\mathcal{F}$.

$$A_{10} = \begin{bmatrix} \frac{\partial^2 L}{\partial u_1 \partial u_1} \\ \frac{\partial^2 L}{\partial u_2 \partial u_2} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}, \quad A_{01} = \begin{bmatrix} \frac{\partial^2 L}{\partial u_2 \partial u_1} \\ \frac{\partial^2 L}{\partial u_1 \partial u_2} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix},$$

$$A_{11} = \begin{bmatrix} \frac{\partial^2 L}{\partial u_1 \partial u_1} & \frac{\partial^2 L}{\partial u_1 \partial u_2} \\ \frac{\partial^2 L}{\partial u_2 \partial u_1} & \frac{\partial^2 L}{\partial u_2 \partial u_2} \end{bmatrix} = \begin{bmatrix} 2 & -\frac{1}{2} \\ -\frac{1}{2} & 2 \end{bmatrix}, \quad A_{20} = \begin{bmatrix} \frac{\partial^2 L}{\partial u_2 \partial u_1} \\ \frac{\partial^2 L}{\partial u_1 \partial u_2} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix},$$

$$A_{12} = \begin{bmatrix} \frac{\partial^2 L}{\partial u_1 \partial u_1} & \frac{\partial^2 L}{\partial u_1 \partial u_2} & \frac{\partial^2 L}{\partial u_1 \partial u_3} \\ \frac{\partial^2 L}{\partial u_2 \partial u_1} & \frac{\partial^2 L}{\partial u_2 \partial u_2} & \frac{\partial^2 L}{\partial u_2 \partial u_3} \\ \frac{\partial^2 L}{\partial u_3 \partial u_1} & \frac{\partial^2 L}{\partial u_3 \partial u_2} & \frac{\partial^2 L}{\partial u_3 \partial u_3} \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix},$$

$$A_{21} = \begin{bmatrix} \frac{\partial^2 L}{\partial u_2 \partial u_1} & \frac{\partial^2 L}{\partial u_2 \partial u_2} \\ \frac{\partial^2 L}{\partial u_3 \partial u_1} & \frac{\partial^2 L}{\partial u_3 \partial u_2} \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix},$$

$$A_{22} = \begin{bmatrix} \frac{\partial^2 L}{\partial u_2 \partial u_1} & \frac{\partial^2 L}{\partial u_2 \partial u_2} & \frac{\partial^2 L}{\partial u_2 \partial u_3} \\ \frac{\partial^2 L}{\partial u_3 \partial u_1} & \frac{\partial^2 L}{\partial u_3 \partial u_2} & \frac{\partial^2 L}{\partial u_3 \partial u_3} \end{bmatrix} = \begin{bmatrix} 2 & -\frac{1}{2} & -\frac{1}{2} \\ -\frac{1}{2} & 2 & -\frac{1}{2} \\ -\frac{1}{2} & -\frac{1}{2} & 2 \end{bmatrix}.$$}

Thus,

$$A = \begin{bmatrix} 2 & 0 & 0 & 0 & 0 & 0 \\ 0 & 2 & -\frac{1}{2} & 0 & 0 & 0 \\ 0 & -\frac{1}{2} & 2 & 0 & 0 & 0 \\ 0 & 0 & 0 & 2 & -\frac{1}{2} & -\frac{1}{2} \\ 0 & 0 & 0 & -\frac{1}{2} & 2 & -\frac{1}{2} \\ 0 & 0 & 0 & -\frac{1}{2} & -\frac{1}{2} & 2 \end{bmatrix}.$$}

It is easy to see that the matrices $A_{kk}$, $k = 0, 1, 2$ are all semi-positive definite. This implies that the Legendre necessary conditions for minimum point are satisfied. Furthermore, the matrix $A$ is positive definite. Thus, we can well conclude that the found solution $u$ to the Euler-Lagrange equations is effectively a minimum point for the functional $\mathcal{F}$.

**Acknowledgments**

This work is partially supported by the ICTP through the OEA-ICMPA-Prj-15. The ICMPA is in partnership with the Daniel Iagolnitzer Foundation (DIF), France.

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