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Micromesh-selection for the ATLAS New Small Wheel Micromegas detectors

F. Kuger on behalf of the ATLAS Muon collaboration

CERN
Geneva 23, Switzerland
University of Würzburg
97074 Würzburg, Germany

E-mail: Fabian.Kuger@cern.ch

ABSTRACT: The ATLAS New Small Wheels will be the first major upgrade to an LHC experiment utilizing the Micromegas technology. With an active detection area of 1280 m² and comprising more than two million channels it is the largest and probably most ambitious system of Micro Pattern Gaseous Detectors (MPGDs) currently under construction.

The eponymous component of the Micromegas technology, the micromesh, is the detector’s most precise component. Although a wide range of meshes, mesh geometries and parameters can be used to build an operational Micromegas, its properties can affect a range of detector qualities, such as reconstruction efficiency, timing and energy resolution. Conversely, the correct choice of this component will permit a wider range in operation parameters and optimize the detector performance.

KEYWORDS: Materials for gaseous detectors; Micropattern gaseous detectors (MSGC, GEM, THGEM, RETHGEM, MHSP, MICROPIC, MICROMEGAS, InGrid, etc); Detector design and construction technologies and materials
1 Introduction

To fully exploit the discovery potential of the Large Hadron Collider [1], an upgrade towards high luminosity (HL-LHC) is scheduled for 2024-25 [2]. In parallel to the accelerator, the experiments have to be adapted to the higher luminosity, causing higher particle rates and detector occupancy [3]. Within the next long shutdown the innermost end-cap stations of the ATLAS Muon spectrometer [4] will be replaced by the New Small Wheels [5]. Each of them comprises resistive Micromegas and sTGC detectors in an overlapping structure of eight large and eight small sectors, with each sector hosting two (Micromegas) respectively three (sTGC) Quadruplet modules (4 active detection layers) (figure 1).

Figure 1. The ATLAS Detector at the LHC (left) [4] showing the position of the (New) Small Wheels with their sector structure (center) [5] and the composition of each sector out of sTGC and Micromegas Quadruplet modules (right).
A key component of the Micromegas (Micromesh gaseous structure) [6] detectors is the fine conductive mesh, dividing the gas volume into a drift and an amplification region. The selection of the proper mesh is an important design objective, affecting various detector aspects, several of these being discussed in this publication.

2 An ideal Micromesh for a Micromegas detector

The construction of m²-size Micromegas detectors with a mechanically floating mesh requires sufficient robustness of the meshes. Additionally they must be durable enough to sustain a sequence of assembly, transport and cleaning processes.

In an ideal Micromegas the cathode, the anode and the mesh create independent and homogeneous electrical fields in the drift and the amplification volume. Therefore the mesh should resemble to first approximation a metallic plane with an internal structure finer than all other detector components. It should be as thin and flat as possible.

On the other hand an ideal mesh would be completely permeable to electrons traversing from the low drift field into the amplification field region while absorbing all ions drifting in the other direction. Furthermore it should allow an unhindered gas exchange between the volumes. Both requirements support a highly perforated structure.

Since no material can fully satisfy all these partially contradicting requirements, a trade-off between the different aspects is required.

3 Mechanical and production-related considerations

Meshes or grids can be produced by a variety of techniques. Although photo-lithographical etching or electroforming can yield finer-pitched and flatter meshes, these grid structures typically lack the mechanical robustness to be stretched over several meters, as required for a large size floating mesh Micromegas. Weaving of stainless steel wires has proven to be the most reliable method to manufacture accurate and mechanically durable meshes of several m² size.

![Figure 2](image_url)

**Figure 2.** Left: schematic of the three most common weaving patterns: plain weave, twilled weave and (plain) dutch weave (left to right). Right: defining geometry of a plain weave unit cell. [7].

Different weaving patterns can increase the robustness of the mesh cloth but cause smaller open areas and/or asymmetries in warp and weft directions, like e.g. the dutch weave. Plain weave

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1The mesh is stretched and positioned on a layer of support pillars. Once the anode is polarized the resulting electrostatic force draws the electrically grounded mesh on the pillars and creates a precise amplification gap.
results in the symmetric pattern with shortest periodicity and represents the best approximation to a flat perforated plane (figure 2). For the symmetrical plain weave, the mesh is completely specified by the wire diameter $d$ and the aperture between neighboring wires $a$ (figure 2). The open area of the mesh is defined as $O = [a/(a + d)]^2$ and its pitch or periodicity is $p = a + d$.

The weaving process of meshes with more than two meter width requires sufficiently stable wires. Additionally a reduction of the wire diameter requires more wire-length to weave a mesh of comparable open area and thus increases costs per square meter significantly. To avoid production flaws and to keep costs reasonable, a wire diameter of $\geq 30 \mu m$ is recommended. Choosing the mesh aperture for optimized mechanical properties is a trade-off: while smaller apertures increase the bending angle of the wire during the weaving process and therefore the risk of wire rapture, a mesh cloth with larger apertures is less rigid and more prone to damage during handling.

Although the flatness of the mesh can be increased by calendering, a process where the mesh cloth is pressed between two precisely parallel rolls, this process is not industrially available for meshes of $> 2 \text{ m}$ width.

4 Homogeneity of the amplification field and gas gain

Although primarily determined by the potential difference between the mesh and the anode the electrical field in the amplification gap, and thus the Micromegas gain, is highly sensitive to small changes in the electrodes’ geometry and position. Figure 3 visualizes the electrical field in the amplification gap and the drift volume close to the mesh wires. The streamlines indicate the idealized electron path, neglecting diffusion in the gas. Electrons created in the drift volume are strongly focused on a path in-between the mesh wires and accordingly the electrical field strength along these paths is the main determinant for the Micromegas’ gain.

![Figure 3](image-url). Electrical field strength in the vicinity of the mesh wires. The mesh has a periodicity of 100 $\mu \text{m}$ (diameter $= 30 \mu \text{m}$, aperture $= 70 \mu \text{m}$), the strip pitch is 450 $\mu \text{m}$ (strip width $= 300 \mu \text{m}$). The position and orientation of two probe lines are indicated (dashed). (COMSOL Multiphysics\textsuperscript{®} [8] Simulation — the streamline (grey) density is not proportional to the field strength.)

With an increased distance between the wires, the electrical field strength along the electrons’ most probable path through the amplification gap (vertical probe line) decreases as shown in
figure 4. Consequentially a larger aperture results in a smaller gas gain requiring higher voltages for comparable gain, increasing the risk of discharges in the detector.

The influence of the wire positions on the field homogeneity along the amplification gap (horizontal probe line) is clearly visible in figure 5 and most pronounced close to the wires. Along the wire periodicity, the non-homogeneity is dominated by the anode strip structure, especially in the lower part of the amplification gap.

5 Electrostatic shielding between drift- and amplification-field

Since a mesh is not a continuous metal plate, the electrical fields on both sides are not perfectly shielded, but interfere with each other. The shielding capabilities of different meshes can already be assessed in figure 4, depicting the significant deviation of the electrical field strength from the nominal drift field $E_{D,\text{nom}}$ in the vicinity of the mesh wires. Besides this effect, which is locally constrained to the region of non-homogeneous drift fields close to the wires, a mesh specific deviation from nominal is visible closer to the drift cathode as well (figure 6). While a continuous offset between the effective drift field strength $E_{D,\text{eff}}$ and its nominal value $E_{D,\text{nom}}$ can easily be taken into account in a TPC-like reconstruction algorithm, the increase of the non-homogeneous region within the drift volume is more difficult to cope with. Hence, an aperture not wider than 80 $\mu$m between neighboring 30 $\mu$m wires is recommended, to limit the $E_{D,\text{eff}}$ uncertainty in the top 80% of the drift gap to $\leq 1\%$.

The non-homogeneity along a horizontal direction in the drift volume, parallel to the mesh is shown in figure 7. It is dominated by the anode strip periodicity for distances $\geq 300 \mu$m from the anode, $\approx 130 \mu$m from the mesh top surface. The wires systematic effect on the electrical field strength is only visible closer to the mesh. For distances $\geq 500 \mu$m from the anode, the field strength fluctuation is $< 1\% E_{D,\text{eff}}$ for a mesh aperture of $\leq 70 \mu$m.

A similar effect of the drift field on the field-strength in the amplification region can be observed, but is negligibly small due to the ratio of the two fields.
6 Electron Transparency

Electrons approaching the mesh are either conducted through the mesh or end up on its surface due to scattering [9]. If absorbed by the mesh the electrons are lost for signal production. Consequently, an electron transparency close to 100% is important for optimal track reconstruction.

Figure 8 and figure 9 summarize extensive simulation studies on electron transparencies, verified by measurements with an exchangeable mesh Micromegas prototype [10]. With a 30 µm-wire an aperture of ≥ 70 µm (open area > 49 %) is required to reach an electron transparency of ≥ 90% (dashed line) with the voltage settings foreseen for the NSW Micromegas (shaded blue region).
7 Gas flow through the mesh

An effective gas exchange through the mesh is important to keep the gas mixture in the amplification gap pure, since contamination is created there during the avalanche formation e.g. by dissociative attachment: $e^- + \text{CO}_2 \rightarrow \text{O}^- + \text{CO}$. Gas-flow-simulations with a simplified (flat) mesh model ($d = 30 \mu m$, $a = 70 \mu m$) show a gas exchange time between drift and amplification volumes in the order of a few seconds (figure 10). Given the exchange-rate of the full detector (4 Volumes/day), the gas flow hindrance caused by the mesh is negligible.

![Figure 10](image)

Figure 10. Propagation of the gas during the exchange process (blue: old gas; red: new gas) in the drift- and the amplification-region at three sequential instances.

8 Conclusion and Mesh-selection

Woven wire meshes have proven to be an affordable and technologically viable choice for large area Micromegas. Although a finer and flatter mesh is desirable, mechanical stability and cost-considerations exclude wires of $< 30 \mu m$ diameter. The meshes’ transparency to electrons (and to a certain extend also to the gas flow) requirements set a lower limit to the mesh aperture. Very large apertures are excluded because of the decrease in amplification field homogeneity and the increase in interference effects between the electrical fields.

A plain weave mesh with $71 \mu m$ aperture, $30 \mu m$ wire diameter and 250 lines per inch (lpi) is the optimum trade-off between all the above aspects. The large-scale production of $2800 m^2$ woven wire mesh (71/30, 250 lpi) for the ATLAS NSW Micromegas has been finished in June 2016.

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