An Analysis of the Convergence of Graph Laplacians

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Abstract

Existing approaches to analyzing the asymptotics of graph Laplacians typically assume a well-behaved kernel function with smoothness assumptions. We remove the smoothness assumption and generalize the analysis of graph Laplacians to include previously unstudied graphs including kNN graphs. We also introduce a kernel-free framework to analyze graph constructions with shrinking neighborhoods in general and apply it to analyze locally linear embedding (LLE). We also describe how for a given limiting Laplacian operator desirable properties such as a convergent spectrum and sparseness can be achieved choosing the appropriate graph construction.

1 Introduction

Graph Laplacians have become a core technology throughout machine learning. In particular, they have appeared in clustering [Kannan et al. (2004); von Luxburg et al. (2008)], dimensionality reduction [Belkin & Niyogi (2003); Nadler et al. (2006)], and semi-supervised learning [Belkin & Niyogi (2004); Zhu et al. (2003)].

While graph Laplacians are but one member of a broad class of methods that use local neighborhood graphs to model data lying on a low-dimensional manifold embedded in a high-dimensional space, they are distinguished by their appealing mathematical properties, notably: (1) the graph Laplacian is the infinitesimal generator for a random walk on the graph, and (2) it is a discrete approximation to a weighted Laplace-Beltrami operator on a manifold, an operator which has numerous geometric properties and induces a smoothness functional. These mathematical properties have served as a foundation for the development of a growing theoretical literature that has analyzed learning procedures based
on the graph Laplacian. To review briefly, Bousquet et al. (2003) proved an early result for the convergence of the unnormalized graph Laplacian to a regularization functional that depends on the squared density $p^2$. Belkin & Niyogi (2003) demonstrated the pointwise convergence of the empirical unnormalized Laplacian to the Laplace-Beltrami operator on a compact manifold with uniform density. Lafon (2004) and Nadler et al. (2006) established a connection between graph Laplacians and the infinitesimal generator of a diffusion process. They further showed that one may use the degree operator to control the effect of the density. Hein et al. (2005) combined and generalized these results for weak and pointwise (strong) convergence under weaker assumptions as well as providing rates for the unnormalized, normalized, and random walk Laplacians. They also make explicit the connections to the weighted Laplace-Beltrami operator. Singer (2006) obtained improved convergence rates for a uniform density. Giné & Koltchinskii (2005) established a uniform convergence result and functional central limit theorem to extend the pointwise convergence results. von Luxburg et al. (2008) and Belkin & Niyogi (2006) presented spectral convergence results for the eigenvectors of graph Laplacians in the fixed and shrinking bandwidth cases respectively.

Although this burgeoning literature has provided many useful insights, several gaps remain between theory and practice. Most notably, in constructing the neighborhood graphs underlying the graph Laplacian, several choices must be made, including the choice of algorithm for constructing the graph, with $k$-nearest-neighbor (kNN) and kernel functions providing the main alternatives, as well as the choice of parameters ($k$, kernel bandwidth, normalization weights). These choices can lead to the graph Laplacian generating fundamentally different random walks and approximating different weighted Laplace-Beltrami operators. The existing theory has focused on one specific choice in which graphs are generated with smooth kernels with shrinking bandwidths. But a variety of other choices are often made in practice, including kNN graphs, $r$-neighborhood graphs, and the “self-tuning” graphs of Zelnik-Manor & Perona (2004). Surprisingly, few of the existing convergence results apply to these choices (see Maier et al. (2008) for an exception).

This paper provides a general theoretical framework for analyzing graph Laplacians and operators that behave like Laplacians. Our point of view differs from that found in the existing literature; specifically, our point of departure is a stochastic process framework that utilizes the characterization of diffusion processes via drift and diffusion terms. This yields a general kernel-free framework for analyzing graph Laplacians with shrinking neighborhoods. We use it to extend the pointwise results of Hein et al. (2007) to cover non-smooth kernels and introduce location-dependent bandwidths. Applying these tools we are able to identify the asymptotic limit for a variety of graphs constructions including kNN, $r$-neighborhood, and “self-tuning” graphs. We are also able to provide an analysis for Locally Linear Embedding (Roweis & Saul, 2000).

A practical motivation for our interest in graph Laplacians based on kNN graphs is that these can be significantly sparser than those constructed using kernels, even if they have the same limit. Our framework allows us to establish
this limiting equivalence. On the other hand, we can also exhibit cases in which kNN graphs converge to a different limit than graphs constructed from kernels, and that this explains some cases where kNN graphs perform poorly. Moreover, our framework allows us to generate new algorithms: in particular, by using location-dependent bandwidths we obtain a class of operators that have nice spectral convergence properties that parallel those of the normalized Laplacian in von Luxburg et al. (2008), but which converge to a different class of limits.

2 The Framework

Our work exploits the connections among diffusion processes, elliptic operators (in particular the weighted Laplace-Beltrami operator), and stochastic differential equations (SDEs). This builds upon the diffusion process viewpoint in Nadler et al. (2006). Critically, we make the connection to the drift and diffusion terms of a diffusion process. This allows us to present a kernel-free framework for analysis of graph Laplacians as well as giving a better intuitive understanding of the limit diffusion process.

We first give a brief overview of these connections and present our general framework for the asymptotic analysis of graph Laplacians as well as providing some relevant background material. We then introduce our assumptions and derive our main results for the limit operator for a wide range of graph construction methods. We use these to calculate asymptotic limits for specific graph constructions.

2.1 Relevant Differential Geometry

Assume $M$ is an $m$-dimensional manifold embedded in $\mathbb{R}^b$. To identify the asymptotic infinitesimal generator of a diffusion on this manifold, we will derive the drift and diffusion terms in normal coordinates at each point. We refer the reader to Boothby (1986) for an exact definition of normal coordinates. For our purposes it suffices to note that normal coordinates are coordinates in $\mathbb{R}^m$ that behave roughly as if the neighborhood was projected onto the tangent plane at $x$. The extrinsic coordinates are the coordinates $\mathbb{R}^b$ in which the manifold is embedded. Since the density, and hence integration, is defined with respect to the manifold, we must relate to link normal coordinates $s$ around a point $x$ with the extrinsic coordinates $y$. This relation may be given as follows:

$$y - x = H_x s + L_x (ss^T) + O(\|s^3\|),$$

where $H_x$ is a linear isomorphism between the normal coordinates in $\mathbb{R}^m$ and the $m$-dimensional tangent plane $T_x$ at $x$. $L_x$ is a linear operator describing the curvature of the manifold and takes $m \times m$ positive semidefinite matrices into the space orthogonal to the tangent plane, $T_x^\perp$. More advanced readers will note that this statement is Gauss’ lemma and $H_x$ and $L_x$ are related to the first and second fundamental forms.
We are most interested in limits involving the weighted Laplace-Beltrami operator, a particular second-order differential operator.

### 2.2 Weighted Laplace-Beltrami operator

**Definition 1** (Weighted Laplace-Beltrami operator). The weighted Laplace-Beltrami operator with respect to the density \( q \) is the second-order differential operator defined by \( \Delta_q := \Delta_M - \frac{\nabla q}{q} \nabla \) where \( \Delta_M := \text{div} \nabla \) is the unweighted Laplace-Beltrami operator.

It is of particular interest since it induces a smoothing functional for \( f \in C^2(M) \) with support contained in the interior of the manifold:

\[
\langle f, \Delta_q f \rangle_{L_q} = \|\nabla f\|^2_{L_2(q)}.
\]

Note that existing literature on asymptotics of graph Laplacians often refers to the \( s \)th weighted Laplace-Beltrami operator as \( \Delta_s \) where \( s \in \mathbb{R} \). This is \( \Delta_{p^s} \) in our notation. For more information on the weighted Laplace-Beltrami operator see Grigor’yan (2006).

### 2.3 Equivalence of Limiting Characterizations

We now establish the promised connections among elliptic operators, diffusions, SDEs, and graph Laplacians. We first show that elliptic operators define diffusion processes and SDEs and vice versa. An elliptic operator \( G \) is a second order differential operator of the form

\[
Gf(x) = \sum_{ij} a_{ij}(x) \frac{\partial^2 f(x)}{\partial x_i \partial x_j} + \sum_i b_i(x) \frac{\partial f(x)}{\partial x_i} + c(x)f(x),
\]

where the \( m \times m \) coefficient matrix \((a_{ij}(x))\) is positive semidefinite for all \( x \). If we use normal coordinates for a manifold, we see that the weighted Laplace-Beltrami operator \( \Delta_q \) is a special case of an elliptic operator with \((a_{ij}(x)) = I\), the identity matrix, \( b(x) = \frac{\nabla q(x)}{q(x)} \), and \( c(x) = 0 \). Diffusion processes are related via a result by Dynkin which states that given a diffusion process, the generator of the process is an elliptic operator.

The (infinitesimal) generator \( G \) of a diffusion process \( X_t \) is defined as

\[
Gf(x) := \lim_{t \to 0} \frac{\mathbb{E}_x f(X_t) - f(x)}{t}
\]

when the limit exists and convergence is uniform over \( x \). Here \( \mathbb{E}_x f(X_t) = \mathbb{E}(f(X_t)|X_0 = x) \). A converse relation holds as well. The Hille-Yosida theorem characterizes when a linear operator, such as an elliptic operator, is the generator of a stochastic process. We refer the reader to Kallenberg (2002) for proofs.

A time-homogeneous stochastic differential equation (SDE) defines a diffusion process as a solution (when one exists) to the equation

\[
dX_t = \mu(X_t) dt + \sigma(X_t) dW_t,
\]
where $X_t$ is a diffusion process taking values in $\mathbb{R}^d$. The terms $\mu(x)$ and $\sigma(x)\sigma(x)^T$ are the drift and diffusion terms of the process.

By Dynkin’s result, the generator $G$ of this process defines an elliptic operator and a simple calculation shows the operator is

$$Gf(x) = \frac{1}{2} \sum_{ij} (\sigma(x)\sigma(x)^T)_{ij} \frac{\partial^2 f(x)}{\partial x_i \partial x_j} + \sum_i \mu_i(x) \frac{\partial f(x)}{\partial x_i}.$$ 

In such diffusion processes there is no absorbing state and the term in the elliptic operator $c(x) = 0$. We note that one may also consider more general diffusion processes where $c(x) \leq 0$. When $c(x) < 0$ then we have the generator of a diffusion process with killing where $c(x)$ determines the killing rate of the diffusion at $x$.

To summarize, we see that a SDE or diffusion process define an elliptic operator, and importantly, the coefficients are the drift and diffusion terms, and the reverse relationship holds: An elliptic operator defines a diffusion under some regularity conditions on the coefficients.

All that remains then is to connect diffusion processes in continuous space to graph Laplacians on a finite set of points. Diffusion approximation theorems provide this connection. We state one version of such a theorem.

**Theorem 2** (Diffusion Approximation). Let $\mu(x)$ and $\sigma(x)\sigma(x)^T$ be drift and diffusion terms for a diffusion process defined on a compact set $S \subset \mathbb{R}^b$, and let and $G$ be the corresponding infinitesimal generator. Let $\{Y_t^{(n)}\}$ be Markov chains with transition matrices $P_n$ on state spaces $\{x_i\}_{i=1}^n$ for all $n$, and let $c_n > 0$ define a sequence of scalings. Put

$$\hat{\mu}_n(x_i) = c_n E(Y_1^{(n)} - x_i | Y_0^{(n)} = x_i),$$

$$\hat{\sigma}_n(x_i) = c_n \text{Var}(Y_1^{(n)} | Y_0^{(n)} = x_i).$$

Let $f \in C^2(S)$. If for all $\epsilon > 0$

$$\hat{\mu}_n(x_i) \to \mu(x_i),$$

$$\hat{\sigma}_n(x_i) \sigma(x_i)^T \to \sigma(x) \sigma(x)^T,$$

$$c_n \sup_{i \leq n} P \left( \left\| Y_1^{(n)} - x_i \right\| > \epsilon \mid Y_0^{(n)} = x_i \right) \to 0,$$

then the generators $A_n f = c_n (P_n - I) f \to G f$. Furthermore, for any bounded $f$ and $t_0 > 0$ and the continuous-time transition kernels $T_n(t) = \exp(t A_n)$ and $T$ the transition kernel for $G$, we have $T_n(t) f \to T(t) f$ uniformly in $t$ for $t < t_0$.

**Proof.** We first examine the case when $f(x) = x$. By assumption,

$$A_n \pi_n x = c_n (P_n - I) x = c_n E(Y_1^{(n)} - x_i | Y_0^{(n)} = x_i)$$

$$= \mu_n(x) \to \mu(x) = Ax.$$
Similarly if $f(x) = xx^T$, $\|A_n\pi_n f - Af\|_\infty \to 0$. If $f(x) = 1$, then $A_n\pi_n f = \pi_n Af = 0$. Thus, by linearity of $A_n$, $A_n\pi_n f \to Af$ for any quadratic polynomial $f$.

Taylor expand $f$ to obtain $f(x+h) = q_x(h) + \delta_x(h)$ where $q_x(h)$ is a quadratic polynomial in $h$. Since the second derivative is continuous and the support of $f$ is compact, $\sup_{x \in \mathcal{M}} \delta_x(h) = o(\|h\|^2)$ and $\sup_{x,h} \delta_x(h) < M$ for some constant $M$.

Let $\Delta_n = Y_1^{(n)} - x_1$. We may bound $A_n$ acting on the remainder term $\delta_x(h)$ by

$$\sup_x A_n\delta_x = c_n E(\delta_x(\Delta_n))|Y_0^{(n)} = x)$$

$$\leq \sup_x c_n E(\delta_x(\Delta_n) 1(\|\Delta_n\| \leq \epsilon)|Y_0^{(n)} = x) + M \sup_x c_n P(\|\Delta_n\| > \epsilon|Y_0^{(n)} = x)$$

$$= o(c_n E(\|\Delta_n\|^2|Y_0^{(n)} = x)) + M \sup_x c_n P(\|\Delta_n\| > \epsilon|Y_0^{(n)} = x)$$

$$= o(1)$$

where the last equality holds by the assumptions on the uniform convergence of the diffusion term $\delta_n \tilde{\sigma}_n^T$ and on the shrinking jumpsizes.

Thus, $A_n\pi_n f \to Af$ for any $f \in C^2(M)$.

The class of functions $C^2(M)$ is dense in $L_\infty(M)$ and form a core for the generator $A$. Standard theorems give equivalence between strong convergence of infinitesimal generators on a core and uniform strong convergence of transition kernels on a Banach space (e.g. Theorem 1.6.1 in Ethier & Kurtz (1986)).

We remark that though the results we have discussed thus far are stated in the context of the extrinsic coordinates $\mathbb{R}^b$, we describe appropriate extensions in terms of normal coordinates in the appendix.

2.4 Assumptions

We describe here the assumptions and notation for the rest of the paper. The following assumptions we will refer to as the standard assumptions.

Unless stated explicitly otherwise, let $f$ be an arbitrary function in $C^2(M)$.

**Manifold assumptions.** Assume $\mathcal{M}$ as a smooth $m$-dimensional manifold isometrically embedded in $\mathbb{R}^b$ via the map $i : \mathcal{M} \to \mathbb{R}^b$. The essential conditions that we require on the manifold are

1. Smoothness, the map $i$ is a smooth embedding.

2. A single radius $h_0$ such that for all $x \in \text{supp}(f)$, $\mathcal{M} \cap B(x, h_0)$ is a neighborhood of $x$ with normal coordinates, and

3. Bounded curvature of the manifold over $\text{supp}(f)$, i.e. that the second fundamental form is bounded.
When the manifold is smooth and compact, then these conditions are satisfied.

Assume points \( \{x_i\}_{i=1}^\infty \) are sampled i.i.d. from a density \( p \in C^2(M) \) with respect to the natural volume element of the manifold, and that \( p \) is bounded away from 0.

**Notation.** For brevity, we will always use \( x, y \in \mathbb{R}^d \) to be points on \( M \) expressed in extrinsic coordinates and \( s \in \mathbb{R}^m \) to be normal coordinates for \( y \) in a neighborhood centered at \( x \). Since they represent the same point, we will also use \( y \) and \( s \) interchangeably as function arguments, i.e. \( f(y) = f(s) \). Whenever we take a gradient, it is with respect to normal coordinates.

**Generalized kernel.** Though we use a kernel free framework, our main theorem utilizes a kernel, but one that is generalizes previously studied kernels by 1) considering non-smooth base kernels \( K_0 \), 2) introducing location dependent bandwidth functions \( r_x(y), \) and 3) considering general weight functions \( w_x(y) \).

Our main result also handles 4) random weight and bandwidth functions.

Given a bandwidth scaling parameter \( \epsilon > 0 \), define a new kernel by

\[
K(x, y) = w_x(y)K_0 \left( \frac{\|y - x\|}{hr_x(y)} \right). \tag{3}
\]

Previously analyzed constructions for smooth kernels with compact support are described by this more general kernel with \( r_x = 1 \) and \( w_x(y) = d(x)^{-\lambda}d(y)^{-\lambda} \) where \( d(x) \) is the degree function and \( \lambda \in \mathbb{R} \) is some constant.

The directed kNN graph is obtained if \( K_0(x, y) = \mathbb{I}(\|x - y\| \leq 1) \), \( r_x(y) = d(x) \) is the degree function and \( \lambda \in \mathbb{R} \) is some constant.

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We note that the kernel \( K \) is not necessarily symmetric; however, if \( r_x(y) = r_y(x) \) and \( w_x(y) = w_y(x) \) for all \( x, y \in M \) then the kernel is symmetric and the corresponding unnormalized Laplacian is positive semi-definite.

**Kernel assumptions.** We now introduce our assumptions on the choices \( K_0, \epsilon, r_x, w_x \) that govern the graph construction. Assume that the base kernel \( K_0 : \mathbb{R}_+ \rightarrow \mathbb{R}_+ \) has bounded variation and compact support and \( h_n > 0 \) form a sequence of bandwidth scalings. For (possible random) location dependent bandwidth and weight functions \( r^{(n)}_x(\cdot) > 0, w^{(n)}_x(\cdot) \geq 0 \), assume that they converge to \( r_x(\cdot), w_x(\cdot) \) respectively and the convergence is uniform over \( x \in M \). Further assume they have Taylor-like expansions for all \( x, y \in M \) with \( \|x - y\| < h_n \)

\[
\begin{align*}
\epsilon^{(n)}_r(x, s) &= r^{(n)}_x(x) + (\dot{r}_x(x) + \alpha_x \text{sign}(u_x^Ts)u_x^Ts + \epsilon^{(n)}_r(x, s))
\end{align*}
\]

\[
\begin{align*}
\epsilon^{(n)}_w(x, s) &= w^{(n)}_x(x) + \nabla w_x(x)^Ts + \epsilon^{(n)}_w(x, s)
\end{align*}
\]

where the approximation error is uniformly bounded by

\[
\sup_{x \in M, \|s\| < h_n} |\epsilon^{(n)}_r(x, s)| = O(h_n^2)
\]

\[
\sup_{x \in M, \|s\| < h_n} |\epsilon^{(n)}_w(x, s)| = O(h_n^2)
\]
We briefly motivate the choice of assumptions. The bounded variation condition allows for non-smooth base kernels but enough regularity to obtain limits. The Taylor-like expansions allow give conditions where the limit is tractable to analytically compute as well as allowing for randomness in the remainder term as long as it is of the correct order. The particular expansion for the location dependent bandwidth allows one to analyze undirected kNN graphs, which exhibit a non-differentiable location dependent bandwidth (see section 3.3). Note that we do not constrain the general weight functions $w^{(n)}(y)$ to be a power of the degree function, $d_n(x)^\alpha d_n(y)^\alpha$ nor impose a particular functional form for location dependent bandwidths $r_x$. This gives us two degrees of freedom, which allows the same asymptotic limit be obtained for an entire class of parameters governing the graph construction. In section 5.5, we discuss one may choose a graph construction that has more attractive finite sample properties than other constructions that have the same limit.

**Functions and convergence.** We define here what we mean by convergence when the domains of the functions are changing. When take $g_n \to g$ where $\text{domain}(g_n) = \mathcal{X}_n \subset \mathcal{M}$, to mean $\|g_n - \pi_n g\|_\infty \to 0$ where $\pi_n g = g|_{\mathcal{X}_n}$ is the restriction of $g$ to $\mathcal{X}_n$. Likewise, for operators $T_n$ on functions with domain $\mathcal{X}_n$, we take $T_n g = T_n \pi_n g$. Convergence of operators $T_n \to T$ means $T_n f \to Tf$ for all $f \in C^2(\mathcal{M})$. When $\mathcal{X}_n = \mathcal{M}$ for all $n$, this is convergence in the strong operator topology under the $L_\infty$ norm.

We consider the limit of the random walk Laplacian defined by $L_{rw} = I - D^{-1}W$ where $I$ is the identity, $W$ is the matrix of edge weights, and $D$ is the diagonal degree matrix.

### 2.5 Main Theorem

Our main result is stated in the following theorem.

**Theorem 3.** Assume the standard assumptions hold eventually with probability 1. If the bandwidth scalings $h_n$ satisfy $h_n \downarrow 0$ and $nh_n^{m+2}/\log n \to \infty$, then for graphs constructed using the kernels

$$K_n(x, y) = w^{(n)}_x(y)K_0 \left( \frac{\|y - x\|}{h_n r^{(n)}_x(y)} \right) \quad (5)$$

there exists a constant $Z_{K_0,m} > 0$ depending only on the base kernel $K_0$ and the dimension $m$ such that for $c_n = Z_{K_0,m}/h^2$,

$$-c_n L_{rw}^{(n)} f \to Af$$

where $A$ is the infinitesimal generator of a diffusion process with the following drift and diffusion terms given in normal coordinates:

$$\mu_s(x) = r_x(x)^2 \left( \frac{\nabla p(x)}{p(x)} + \frac{\nabla w(x)}{w(x)} + (m + 2) \frac{\dot{r}_x(x)}{r_x(x)} \right),$$

$$\sigma_s(x)\sigma_s(x)^T = r_x(x)^2 I$$
where I is the $m \times m$ identity matrix.

Proof. We apply the diffusion approximation theorem (Theorem 2) to obtain convergence of the random walk Laplacians. Since $h_n \downarrow 0$, the probability of a jump of size $> \epsilon$ equals 0 eventually. Thus, we simply need to show uniform convergence of the drift and diffusion terms and identify their limits. We leave the detailed calculations in the appendix and present the main ideas in the proof here.

We first assume that $K_0$ is an indicator kernel. To generalize, we note that for kernels of bounded variation, we may write $K_0(x) = \int_{|x| < z} d\eta_-(z) - \int_{|x| > z} d\eta_+(z)$ for some finite positive measures $\eta_-, \eta_+$ with compact support. The result for general kernels then follows from Fubini’s theorem.

We also initially assume that we are given the true density $p$. After identifying the desired limits given the true density, we show that the empirical version converges uniformly to the correct quantities.

The key calculation is lemma 7 in the appendix which establishes that integrating against an indicator kernel is like integrating over a sphere re-centered on $h^{-1} r_x(x)$.

Given this calculation and by Taylor expanding the non-kernel terms, one obtains the infinitesimal first and second moments and the degree operator.

\[ M_1^{(n)}(x) = \frac{1}{h_n^{m}} \int s K_n(x, y)p(y)ds \]
\[ = \frac{1}{h_n^{m}} \int s w_x^{(n)}(s) K_0 \left( \frac{|y - x|}{h_n r_x^{(n)}(s)} \right) p(s)ds \]
\[ = \frac{1}{h_n^{m}} \int s \left( w_x(x) + \nabla w_x(x)^T s + O(h_n^2) \right) \left( p(x) + \nabla p(x)^T s + O(h_n^2) \right) \times \]
\[ \times K_0 \left( \frac{|y - x|}{h_n r_x^{(n)}(s)} \right) ds \]
\[ = C_{K_0, m} h_n^2 r_x(x)^{m+2} \left( w_x(x) \frac{\nabla p(x)}{m+2} + p(x) \frac{\nabla w_x(x)}{m+2} + w_x(x)p(x) \hat{r}_x(x) + o(1) \right) \]

\[ M_2^{(n)}(x) = \frac{1}{h_n^{m}} \int s s^T K_n(x, y)p(y)ds \]
\[ = \frac{1}{h_n^{m}} \int s s^T w_x^{(n)}(s) K_0 \left( \frac{|y - x|}{h_n r_x^{(n)}(s)} \right) p(s)ds \]
\[ = \frac{1}{h_n^{m}} \int s s^T \left( w_x(x) + O(h_n) \right) \left( p(x) + O(h_n) \right) K_0 \left( \frac{|y - x|}{h_n r_x^{(n)}(s)} \right) ds \]
\[ = \frac{C_{K_0, m}}{m} h_n^2 r_x(x)^{m+2} \left( w_x(x)p(x)I + O(h_n) \right), \]
\[ d_n(x) = \frac{1}{h_n^m} \int K_n(x,y)p(y)dy \]  \hspace{1cm} (6)

\[ = \frac{1}{h_n^m} \int w_x^{(n)}(s)K_0 \left( \frac{\|y-x\|}{h_n r_x^{(n)}(s)} \right) p(s)ds \]  \hspace{1cm} (7)

\[ = \frac{1}{h_n^m} \int (w_x(x) + O(h_n)) \left( p(x) + O(h_n) \right) K_0 \left( \frac{\|y-x\|}{h_n r_x^{(n)}(s)} \right) ds \]  \hspace{1cm} (8)

\[ = C'_{K_0,m} r_x(x)^m (w_x(x)p(x) + O(h_n)) \]  \hspace{1cm} (9)

where \( C'_{K_0,m} = \int u_m + 2 \, d\eta \), \( C_{K_0,m} = \int u \, d\eta \) and \( \eta \) is the signed measure \( \eta = \eta_+ - \eta_- \).

Let \( Z_{K_0,m} = (m + 2)C'_{K_0,m}/C_{K_0,m} \) and \( c_n = Z_{K_0,m}/h_n^2 \). Since \( K_n/d_n \) define Markov transition kernels, taking the limits \( \mu_s(x) = \lim_{n \to \infty} c_n M_1^{(n)}(x)/d_n(x) \) and \( \sigma_s(x)\sigma_s(x)^T = \lim_{n \to \infty} c_n M_2^{(n)}(x)/d_n(x) \) and applying the diffusion approximation theorem gives the stated result.

To more formally apply the diffusion approximation theorem we may calculate the drift and diffusion in extrinsic coordinates. In extrinsic coordinates, we have

\[ \mu(x) = r_x(x)^2 H_x \left( \frac{\nabla p(x)}{p(x)} + \frac{\nabla w_x(x)}{w_x(x)} + (m + 2) \frac{\dot{r}_x(x)}{r_x(x)} \right) + r_x(x)^2 L_x(I), \]

\[ \sigma(x)\sigma(x)^T = r(x)^2 \Pi_T, \]

where \( \Pi_T \) is the projection onto the tangent plane at \( x \), and \( H_x \) and \( L_x \) are the linear mappings between normal coordinates and extrinsic coordinates defined in Eqn (1).

We now consider the convergence of the empirical quantities. For non-random \( r_x^{(n)} = r_x, w_x^{(n)} = w_x \), the uniform and almost sure convergence of the empirical quantities to the true expectation follows from an application of Bernstein’s inequality. In particular, the value of \( F_n(x,S) = S K \left( \frac{\|Y-x\|}{h_n r_x^{(n)}(x)} \right) \) is bounded by \( K_{\text{max}} h_n \), where \( S \) is \( Y \) in normal coordinates and \( K_{\text{max}} \) depends on the kernel and the maximum curvature of the manifold. Furthermore, the second moment calculation for \( M_2^{(n)} \) gives that the variance \( \text{Var}(F_n(x,S)) \) is bounded by \( c h_n^{m+2} \) for some constant \( c \) that depends on \( K \) and the max of \( p \), and does not depend on \( x \). By Bernstein’s inequality and a union bound, we
have

\[
\Pr \left( \sup_{i \leq n} \left| \mathbb{E}_n \frac{1}{h_n^{m+2}} F_n(x_i, Y) - \frac{1}{h_n^2} M_1^{(n)} \right| > \epsilon \right)
= \Pr \left( \sup_{i \leq n} \left| \mathbb{E}_n F_n(x_i, Y) - \mathbb{E}F_n(x_i, Y) \right| > \epsilon h_n^{m+2} \right)
< 2n \exp \left( -\frac{\epsilon^2}{2c/(nh_n^{m+2}) + 2K_{\max} \epsilon/(3nh_n^{m+1})} \right),
\]

(10)

The uniform convergence a.s. of the first moment follows from Borel-Cantelli. Similar inequalities are attained for the empirical second moment and degree terms.

Now assume \( r_x^{(n)}, w_x^{(n)} \) are random and define \( F_n \) as before. To handle the random weight and bandwidth function case, we first choose deterministic weight and bandwidth functions to maximize the first moment under a constraint that is satisfied eventually a.s.. Define

\[
\begin{align*}
\overline{w}_x^{(n)}(y) &= w_x(y) + \kappa h_n^2 \text{sign}(s_i) \\
\overline{r}_x^{(n)}(y) &= r_x(x) + (\dot{r}_x(x) + \alpha_x \text{sign}(u_x^T s) u_x)^T s - \kappa h_n^2 \text{sign}(s_i) \\
\overline{F}_n(y) &= s_i \overline{w}_x^{(n)}(y) K_0 \left( \frac{\|y - x\|}{h_n \overline{r}_x^{(n)}(y)} \right)
\end{align*}
\]

for some constant \( \kappa \) such that \( \overline{r}_x^{(n)} < r_x^{(n)} \) and \( \overline{w}_x^{(n)} > w_x^{(n)} \) eventually. This is possible since the perturbation terms \( \epsilon_r^{(n)}(x, s), \epsilon_w^{(n)}(x, s) = O(h_n^2) \). Thus, we have \( \overline{F}_{\kappa, n}(x, y) > F_n(x, y) \) for all \( x, y \in M \) eventually with probability 1. Since \( \overline{F}_{\kappa, n}(x, Y) \) uses deterministic weight and bandwidth functions, we obtain i.i.d. random variables and may apply the Bernstein bound on \( \overline{F}_{\kappa, n}(x, y) \) to obtain an upper bound on the empirical quantities, namely \( \mathbb{E}_n \overline{F}_{\kappa, n}(x, Y) > \mathbb{E}F_n(x, Y) \) for all \( x \in M \) eventually with probability 1. We may similarly obtain a lower bound. By lemma 10 the difference between the expectation of the upper bound and the is \( \mathbb{E}\overline{F}_{\kappa, n}(x, Y) - \mathbb{E}F_{0, n}(x, Y) = o(h_n^{m+2}) \). Applying the squeeze theorem gives a.s. uniform convergence of the empirical first moment \( M_1^{(n)}/h_n^2 \). The degree and second moment terms are handled similarly.

Since \( p, w_x, r_x \) are all assumed to be bounded away from 0, the scaled degree operators \( d_n \) are eventually bounded away from 0 with probability 1, and the continuous mapping theorem applied to \( \frac{M^{(n)}/h_n^2}{d_n} \) gives a.s. uniform convergence of the drift and diffusion.

\[ \square \]

2.6 Unnormalized and Normalized Laplacians

While our results are for the infinitesimal generator of a diffusion process, that is, for the limit of the random walk Laplacian \( L_{rw} = I - D^{-1}W \), it is easy to generalize them to the unnormalized Laplacian \( L_u = D - W = DL_{rw} \) and symmetrically normalized Laplacian \( L_{norm} = I - D^{-1/2}WD^{-1/2} = D^{1/2}L_{rw}D^{-1/2} \).
Corollary 4. Take the assumptions in Theorem 3 and let $A$ be the limiting operator of the random walk Laplacian. The degree terms $d_n(\cdot)$ converge uniformly a.s. to a function $d(\cdot)$, and

$$-c'_n L^{(n)}_{u} f \rightarrow d \cdot Af \quad \text{a.s.}$$

where $c'_n = c_n/h^n$. Furthermore, under the additional assumptions $nh_n^{m+4}/ \log n \rightarrow \infty$, sup$_{x,y} |w_x^{(n)} - w_x| = o(h_n^2)$, sup$_{x,y} |r_x^{(n)} - r_x| = o(h_n^2)$, and $d, w, r \in C^2(\mathcal{M})$, we have

$$-c_n L^{(n)}_{\text{norm}} f \rightarrow d^{1/2} \cdot A(d^{-1/2}f) \quad \text{a.s.}$$

Proof. For any two functions $\phi_1, \phi_2 : \mathcal{M} \rightarrow \mathbb{R}$, define $g_u(\phi_1, \phi_2) = (\phi_1(\cdot), f_1(\cdot)\phi_2(\cdot))$. We note that $g_u$ is a continuous mapping in the $L_\infty$ topology and

$$(d_n, c'_n L^{(n)}_{u} f) = g_u(d_n, c_n L_{rw} f).$$

By the continuous mapping theorem, if $d_n \rightarrow d$ a.s. and $c_n L^{(n)}_{rw} f \rightarrow L f$ a.s. in the then

$$c'_n L^{(n)}_{u} \rightarrow d \cdot L f.$$

Thus, convergence of the random walk Laplacians implies convergence of the unnormalized Laplacian under the very weak condition of convergence of the degree operator to a bounded function.

Convergence of the normalized Laplacian is slightly trickier. We may write the normalized Laplacian as

$$L^{(n)}_{\text{norm}} f = d_n^{1/2} L^{(n)}_{rw}(d_n^{-1/2}f)$$

$$= d_n^{1/2} L^{(n)}_{rw}(d^{-1/2}f) + d_n^{1/2} L^{(n)}_{rw}(d_n^{-1/2} - d^{-1/2})f).$$

Using the continuous mapping theorem, we see that convergence of the normalized Laplacian, $c_n L^{(n)}_{\text{norm}} f \rightarrow d^{-1/2} L_{rw}(d^{-1/2}f)$, is equivalent to showing $c_n L^{(n)}_{rw}(d_n^{-1/2} - d^{-1/2}) \rightarrow 0$. A Taylor expansion of the inverse square root gives that showing $c_n L^{(n)}_{rw}(d_n - d) \rightarrow 0$ is sufficient to prove convergence.

We now verify conditions which will ensure that the degree operators will converge at the appropriate rate. We further decompose the empirical degree operator into the bias $Ed_n - d$ and empirical error $d_n - Ed_n$.

Simply carrying out the Taylor expansions to higher order terms in the calculation of the degree function $d_n$ in Eq. 1 and using the refined calculation of the zeroth moment in Lemma 8 in the appendix, the bias of the degree operator is $d_n - d = h_n^2 b + o(h_n^2)$ for some uniformly bounded, continuous function $b$.

Thus we have,

$$c_n L^{(n)}_{rw}(d_n - d) = c_n h_n^2 ((I - P_n)b) \rightarrow 0$$

since $c_n h_n^2$ is constant and $((I - P_n)b) \rightarrow 0$ for any continuous function $\phi$.

We also need to check that the empirical error $d_n - Ed_n \rightarrow 0$ a.s.

If $nh_n^{m+4}/ \log n \rightarrow \infty$ then using the Bernstein bound in equation 10 with $\epsilon$ replaced by $h_n^2$ and applying Borel-Cantelli gives the desired result.
2.7 Limit as weighted Laplace-Beltrami operator

Under some regularity conditions, the limit given in the main theorem (Theorem 3) yields a weighted Laplace-Beltrami operator.

For convenience, define \( \gamma(x) = r_x(x) \), \( \omega(x) = w_x(x) \).

**Corollary 5.** Assume the conditions of Theorem 3 and let \( q = p^2 \omega^m \gamma^m + 2 \). If \( r_x(y) = r_y(x), w_z(y) = w_y(x) \) for all \( x, y \in \mathcal{M} \) and \( r^{(1)}(\cdot), w^{(1)}(\cdot) \) are twice differentiable in a neighborhood of \((x, x)\) for all \( x \), then for \( c_n = Z_{K_0, m}/h^{m+2} \)

\[
-c_n^L(u) \rightarrow \frac{q}{p} \Delta_q. \tag{14}
\]

**Proof.** Note that \( \nabla|_{y=x} \gamma(y) = 2 \nabla|_{y=x} r_x(y) \). The result follows from application of Theorem 3, Corollary 4, and the definition of the weighted Laplace-Beltrami operator.

3 Application to Specific Graph Constructions

To illustrate Theorem 3, we apply it to calculate the asymptotic limits of graph Laplacians for several widely used graph construction methods. We also apply the general diffusion theory framework to analyze LLE.

3.1 \( r \)-Neighborhood and Kernel Graphs

In the case of the \( r \)-neighborhood graph, the Laplacian is constructed using a kernel with fixed bandwidth and normalization. The base kernel is simply the indicator function \( K_0(x) = I(|x| < r) \). The radius \( r_x(y) \) is constant so \( \dot{r}(x) = 0. \) The drift is given by \( \mu_s(x) = \nabla p(x)/p(x) \) and the diffusion term is \( \sigma_s(x) \sigma_s(x)^T = I \). The limit operator is thus

\[
\frac{1}{2} \Delta_\mathcal{M} + \frac{\nabla p(x)^T}{p(x)} \nabla = \frac{1}{2} \Delta_2
\]

as expected. This analysis also holds for arbitrary kernels of bounded variation. One may also introduce the usual weight function \( \omega_x^{(1)}(y) = d_x(x)^{-\alpha} d_y(y)^{-\alpha} \) to obtain limits of the form \( \frac{1}{2} \Delta_{2-2\alpha} \). These limits match those obtained by Hein et al. (2007) and Lafon (2004) for smooth kernels.

3.2 Directed k-Nearest Neighbor Graph

For kNN-graphs, the base kernel is still the indicator kernel, and the weight function is constant 1. However, the bandwidth function \( r_x^{(n)}(y) \) is random and depends on \( x \). Since the graph is directed, it does not depend on \( y \) so \( \dot{r}_x = 0 \).

By the analysis in section 3.3, \( r_x(x) = cp^{-1/m}(x) \) for some constant \( c \). Consequently the limit operator is proportional to

\[
\frac{1}{p^{2/m}}(\Delta_\mathcal{M} + 2 \frac{\nabla p^T}{p} \nabla) = \frac{1}{p^{2/m}} \Delta_{p^2}.
\]

13
Note that this is generally not a self-adjoint operator in $L(p)$. The symmetrization of the graph has a non-trivial affect to make the graph Laplacian self-adjoint.

### 3.3 Undirected $k$-Nearest Neighbor Graph

We consider the OR-construction where the nodes $v_i$ and $v_j$ are linked if $v_i$ is a $k$-nearest neighbor of $v_j$ or vice-versa. In this case $h_n^m r_x^{(n)}(y) = \max\{\rho_n(x), \rho_n(y)\}$ where $\rho_n(x)$ is the distance to the $k^{th}$ nearest neighbor of $x$. The limit bandwidth function is non-differentiable, $r_x(y) = \max\{p^{-1/m}(x), p^{-1/m}(y)\}$, but a Taylor-like expansion exists with $\dot{r}_x(x) = \frac{1}{2m} \frac{\nabla p(x)^T}{p(x)}$. The limit operator is

$$\frac{1}{p^{2/m}} \Delta_{p^{1-2/m}}.$$

which is self-adjoint in $L_2(p)$. Surprisingly, if $m = 1$ then the kNN graph construction induces a drift away from high density regions.

### 3.4 Conditions for kNN convergence

To complete the analysis, we must check the conditions for kNN graph constructions to satisfy the assumptions of the main theorem. This is a straightforward application of existing uniform consistency results for kNN density estimation. Let $h_n = (\frac{kn}{n})^{1/m}$. The condition we must verify is

$$\sup_{y \in M} \left\| r_x^{(n)} - r_x \right\|_\infty = O(h_n^2) \text{ a.s.}$$

We check this for the directed kNN graph, but analyses for other kNN graphs are similar. The kNN density estimate of [Loftsgaarden & Quesenberry (1965)] is

$$\hat{p}_n(x) = \frac{V_m}{n(h_n r_x^{(n)}(x))^{m+2}}$$

where $h_n r_x^{(n)}(x)$ is the distance to the $k^{th}$ nearest neighbor of $x$ given $n$ data points. Taylor expanding equation [15] shows that if $\left\| \hat{p}_n - p \right\|_\infty = O(h_n^2) \text{ a.s.}$ then the requirement on the location dependent bandwidth for the main theorem is satisfied.

[Devroye & Wagner (1977)]’s proof for the uniform consistency of kNN density estimation may be easily modified to show this. Take $\epsilon = (\frac{kn}{n})^2$ in their proof. One then sees that $h_n = \frac{kn}{n} \to 0$ and $\frac{nh_m^{m+2}}{\log n} = \frac{k^{2+2/m}}{n^{1+2/m} \log n} \to \infty$ are sufficient to achieve the desired bound on the error.
3.5 “Self-Tuning” Graphs

The form of the kernel used in self-tuning graphs is

\[ K_n(x, y) = \exp \left( - \frac{\|x - y\|^2}{\sigma_n(x)\sigma_n(y)} \right). \]

where \( \sigma_n(x) = \rho_n(x) \), the distance between \( x \) and the \( k \)th nearest neighbor. The limit bandwidth function is \( r_x(y) = \sqrt{\frac{p^{-1/m}(x)p^{-1/m}(y)}{p^{-2/m}}} \). Since this is twice differentiable, corollary 5 gives the asymptotic limit, which is the same as for undirected kNN graphs,

\[ p^{-2/m} \Delta_{p,2/m}. \]

3.6 Locally Linear Embedding

Locally linear embedding (LLE), introduced by [Roweis & Saul, 2000], has been noted to behave like (the square of) the Laplace-Beltrami operator [Belkin & Niyogi, 2003].

Using our kernel-free framework we will show how LLE differs from weighted Laplace-Beltrami operators and graph Laplacians in several ways. 1) LLE has, in general, no well-defined asymptotic limit without additional conditions on the weights. 2) It can only behave like an unweighted Laplace-Beltrami operator. 3) It is affected by the curvature of the manifold, and the curvature can cause LLE to not behave like any elliptic operator (including the Laplace-Beltrami operator).

The key observation is that LLE only controls for the drift term in the extrinsic coordinates. Thus, the diffusion term has freedom to vary. However, if the manifold has curvature, the drift in extrinsic coordinates constrains the diffusion term in normal coordinates.

The LLE matrix is defined as \((I - W)^T(I - W)\) where \( W \) is a weight matrix which minimizes reconstruction error \( W = \arg\min W \| (I - W)y \|^2 \) under the constraints \( W1 = 1 \) and \( W^T \neq 0 \) only if \( j \) is one of the \( k \)th nearest neighbors of \( i \). Typically \( k > m \) and reconstruction error = 0. We will analyze the matrix \( M = I - W \).

Suppose LLE produces a sequence of matrices \( M_n = I - W_n \). The row sums of \( M_n \) are 0. Thus, we may decompose \( M_n = A_n^+ - A_n^- \) where \( A_n^+, A_n^- \) are generators for finite state Markov processes obtained from the positive and negative weights respectively. Assume that there is some scaling \( c_n \) such that \( c_n A_n^+, c_n A_n^- \) converge to generators of diffusion processes with drifts \( \mu_+, \mu_- \) and diffusion terms \( \sigma_+\sigma_+^T, \sigma_-\sigma_-^T \). Set \( \mu = \mu_+ - \mu_- \) and \( \sigma\sigma^T = \sigma_+\sigma_+^T - \sigma_-\sigma_-^T \).

No well-defined limit. We first show there is generally no well-defined asymptotic limit when one simply minimizes reconstruction error. Suppose \( \text{rank}(L_x) < m(m + 1)/2 \) at \( x \). This will necessarily be true if the extrinsic dimension \( b < m(m + 1)/2 + m \). For simplicity assume \( \text{rank}(L_x) = 0 \). Minimizing the LLE reconstruction error does not constrain the diffusion term, and \( \sigma(x)\sigma(x)^T \) may be chosen arbitrarily. Choose asymptotic diffusion \( \sigma\sigma^T \) and drift
μ terms that are Lipschitz so that a corresponding diffusion process necessarily exists. A diffusion with terms $2\sigma\sigma^T$ and $\mu$ will also exist in that case.

One may easily construct graphs for the positive and negative weights with these asymptotic diffusion and drift terms by solving highly underdetermined quadratic programs. Furthermore, in the interior of the manifold, these graphs may be constructed so that the finite sample drift terms are exactly equal by adding an additional constraint. Thus, $A_n^+ \to 2G_0 + \mu^T \nabla$ and $A_n^- \to G_0 + \mu^T \nabla$ where $G_0$ is the generator for a diffusion process with zero drift and diffusion term $\sigma_- (x) \sigma_- (x)^T$. We have $c_n M_n = A_n^+ - A_n^- \to G_0$. Thus, we can construct a sequence of LLE matrices that have 0 reconstruction error but have an arbitrary limit. It is trivial to see how to modify the construction when $0 < \text{rank}(L_x) < m(m+1)/2$.

No drift. Since $\mu_s (x) = 0$, if the LLE matrix does behave like a Laplace-Beltrami operator, it must behave like an unweighted one, and the density has no affect on the drift.

Curvature and limit. We now show that the curvature of the manifold affects LLE and that the LLE matrix may not behave like any elliptic operator. If the manifold has sufficient curvature, namely if the extrinsic coordinates have dimension $b \geq m + m(m+1)/2$ and $\text{rank}(L_x) = m(m+1)/2$, then the diffusion term in the normal coordinates is fully constrained by the drift term in the extrinsic coordinates.

Recall from equation 1 that the extrinsic coordinates as a function of the normal coordinates are $y = x + H_x s + L_x (ss^T) + O(||s||^3)$. By linearity of $H_x$ and $L_x$, the asymptotic drift in the extrinsic coordinates is $\mu(x) = H_x \mu_s (x) + L_x (\sigma_s (x) \sigma_s (x)^T)$.

Since reconstruction error in the extrinsic coordinates is 0, we have in normal coordinates

$$\mu_s (x) = 0 \quad \text{ and } \quad L_x (\sigma_s (x) \sigma_s (x)^T) = 0.$$  

In other words, the asymptotic drift and diffusion terms of $A_n^+$ and $A_n^-$ must be the same, and $c_n M_n \to G_0 - G_0 = 0$.

This implies that the scaling $c_n$ where LLE can be expected to behave like an elliptic operator gives the trivial limit 0. If another scaling yields a non-trivial limit, it may include higher-order differential terms. It is easy to see when $L_x$ is not full rank, the curvature affects LLE by partially constraining the diffusion term.

Regularization and LLE. We note that while the LLE framework of minimizing reconstruction error can yield ill-behaved solutions, practical implementations add a regularization term when constructing the weights. This causes the reconstruction error to be non-zero in general and gives unique solutions for the weights which favor equal weights (and asymptotic behavior like kNN graphs).
4 Experiments

To illustrate the theory, we show how to correct the bad behavior of the kNN Laplacian for a synthetic data set. We also show how our analysis can predict the surprising behavior of LLE.

**kNN Laplacian.** We consider a non-linear embedding example which almost all non-linear embedding techniques handle well but the kNN graph Laplacian performs poorly. Figure 1 shows a 2D manifold embedded in 3 dimensions and embeddings using different graph constructions. The theoretical limit of the normalized Laplacian $L_{knn}$ for a kNN graph is $L_{knn} = \frac{1}{p} \Delta_1$, while the limit for a graph with Gaussian weights is $L_{gauss} = \Delta_p$. The first 2 coordinates of each point are from a truncated standard normal distribution, so the density at the boundary is small and the effect of the $1/p$ term is substantial. This yields the bad behavior shown in Figure 1 (C). We may use the relationship between the $k^{th}$-nearest neighbor and the density in Eqn (15) to obtain a pilot estimate $\hat{p}$ of the density. Choosing $w_{x}(y) = \sqrt{\hat{p}_n(x)\hat{p}_n(y)}$, gives a weighted kNN graph with...
Figure 2: (A) shows a 1D manifold isometric to a circle. (B-D) show the embeddings using (B) Laplacian eigenmaps which correctly identifies the structure, (C) LLE with regularization $1e^{-3}$, and (D) LLE with regularization $1e^{-6}$.

the same limit as the graph with Gaussian weights. Figure 1 (D) shows that this change yields the roughly desired behavior but with fewer “holes” in low density regions and more in high density regions.

LLE. We consider another synthetic data set, the toroidal helix, in which the manifold structure is easy to recover. Figure 2 (A) shows the manifold which is clearly isometric to a circle, a fact picked up by the kNN Laplacian in Figure 2 (B).

Our theory predicts that the heuristic argument that LLE behaves like the Laplace-Beltrami operator will not hold. Since the total dimension for the drift and diffusion terms is 2 and the global coordinates also have dimension 2, that there is forced cancellation of the first and second order differential terms and the operator should behave like the 0 operator or include higher order differentials. In Figure 2 (C) and (D), we see this that LLE performs poorly and that the behavior comes closer to the 0 operator when the regularization term is smaller.
5 Remarks and Discussion

5.1 Non-shrinking neighborhoods

In this paper, we have presented convergence results using results for diffusion processes without jumps. Graphs constructed using a fixed, non-shrinking bandwidth do not fit within this framework, but approximation theorems for diffusion processes with jumps still apply (see Jacod & Širjaev (2003)). Instead of being characterized by the drift and diffusion pair \( \mu(x), \sigma(x) \sigma(x)^T \), the infinitesimal generators for a diffusion process with jumps is characterized by the “Lévy-Khintchine” triplet consisting of the drift, diffusion, and “Lévy measure.” Given a sequence of transition kernels \( K_n \), the additional requirement for convergence of the limiting process is the existence of a limiting transition kernel \( K \) such that \( \int K_n(\cdot, dy)g(y)dy \to \int K(\cdot, dy)g(y)dy \) locally uniformly for all \( C^1 \) functions \( g \). This establishes an impossibility result, that no method that only assigns positive mass on shrinking neighborhoods can have the same graph Laplacian limit as a kernel construction method where the bandwidth is fixed.

5.2 Convergence rates

We note that one missing element in our analysis is the derivation of convergence rates. For the main theorem, we note that it is, in fact, not necessary to apply a diffusion approximation theorem. Since our theorem still uses a kernel (albeit one with much weaker conditions), a virtually identical proof can be obtained by applying a function \( f \) and Taylor expanding it. Thus, we believe that similar convergence rates to Hein et al. (2007) can be obtained. Also, while our convergence result is stated for the strong operator topology, the same conditions as in Hein give weak convergence.

5.3 Relation to density estimation

The connection between kernel density estimation and graph Laplacians is obvious, namely, any kernel density estimation method using a non-negative kernel induces a random walk graph Laplacian and vice versa.

In this paper, we have shown that as a consequence of identifying the asymptotic degree term, we have shown consistency of a wide class of adaptive kernel density estimates on a manifold. We also have shown that on compact sets, the the bias term is uniformly bounded by a term of order \( h^2 \), and a small modification to the Bernstein bound (Eqn 10) gives that the variance is bounded by a term of order \( h^{-m} \). Both of which one would expect. This generalizes previous work on manifold density estimation by Pelletier (2005) and Ozakin (2009) to adaptive kernel density estimation.

The well-studied field of kernel density estimation may also lead to insights on how to choose a good location dependent bandwidth as well. We compare the form of our density estimates to other well-known adaptive kernel density estimation techniques. The balloon estimator and sample smoothing estimators
as described by Terrell & Scott (1992) are respectively given by

\[
\hat{f}_1(x) = \frac{1}{nh(x)^d} \sum_i K\left(\frac{\|x_i - x\|}{h(x_i)}\right)
\]

(16)

\[
\hat{f}_2(x) = \frac{1}{n} \sum_i \frac{1}{h(x_i)^d} K\left(\frac{\|x_i - x\|}{h(x_i)}\right).
\]

(17)

In the univariate case, Terrell & Scott (1992) show that the balloon estimators yield no improvement to the asymptotic rate of convergence over fixed bandwidth density estimates. The sample smoothing estimator gives a density estimate which does not necessarily integrate to 1. However, it can exhibit better asymptotic behavior in some cases. The Abramson square root law estimator (Abramson, 1982) is an example of a sample smoothing estimator and takes \(h(x_i) = hp(x_i)^{-1/2}\). On compact intervals, this estimator has bias of order \(h^4\) rather than the usual \(h^2\) (Silverman, 1998), and it achieves this bias reduction without resorting to higher order kernels, which necessarily negative in some region. However, the bias in the tail for univariate Gaussian data is of order \((h/\log h)^2\) (Terrell & Scott, 1992), which is only marginally better than \(h^2\).

While we do not make claims of being able to reduce bias in the case of density estimation a manifold, in fact, we do not believe bias reduction to the order of \(h^4\) is possible unless one makes some use of manifold curvature information, the existing density estimation literature suggests what potential benefits one may achieve over different regions of a density.

5.4 Eigenvalues/Eigenvectors

Fixed bandwidth case We find our location dependent bandwidth results to be of interest in the context of the negative result in von Luxburg et al. (2008) for unnormalized Laplacians with a fixed bandwidth. Their results state that for unnormalized graph Laplacians, the eigenvectors of the discrete approximations do not converge if the corresponding eigenvalues lie in the range of the asymptotic degree operator \(d(x)\), whereas for the normalized Laplacian, the “degree operator” is the identity and the eigenvectors converge if the corresponding eigenvalues stay away from 1. Our results suggest that even with unnormalized Laplacians, one can obtain convergence of the eigenvectors by manipulating the range of the degree operator through the use of a location dependent bandwidth function. For example, with kNN graphs we have that the degree operator is essentially 1. For self-tuning graphs, the degree operator also converges to 1, and since the kernels form an equicontinuous family of functions, the theory for compact integral operators may be rigorously applied when the bandwidth scaling is fixed.

Thus we can obtain unnormalized and normalized graph Laplacians that (1) have spectra that converges for fixed (non-decreasing) bandwidth scalings and (2) converge to a limit that is different from that of previously analyzed normalized Laplacians when the bandwidth decreases to 0.
**Corollary 6.** Assume the standard assumptions. Further assume that for some $h_0 > 0$, $\left\{ K_0 \left( \frac{\|y-x\|}{h} \right) : h > h_0 \right\}$ form an equicontinuous family of functions. Let $q, g \in C^2(M)$ be bounded away from 0 and $\infty$. Set

$$
\gamma = \sqrt{\frac{q}{pg}} \quad r_x(y) = \sqrt{\gamma(x)\gamma(y)}
$$

(18)

$$
\omega = \left( \frac{pq}{q} \right)^{m/2} \frac{g}{p} \quad w_x(y) = \sqrt{\omega(x)\omega(y)}.
$$

(19)

If $h_n = h_1$ for all $n$, then the eigenvectors of the normalized Laplacians converge in the sense given in von Luxburg et al. (2008). If $h_n \downarrow 0$ satisfy the assumptions of theorem 5, then the limit rescaled degree operator is $d = g$ and

$$
-c_n L_{\text{norm}} f \to g^{-1/2} \frac{g}{p} \Delta q (g^{-1/2} f)
$$

(20)

which induces the smoothness functional

$$
\left\langle f, g^{-1/2} \frac{g}{p} \Delta q (g^{-1/2} f) \right\rangle_{L_2(p)} = \left\langle \nabla (g^{-1/2} f), \nabla (g^{-1/2} f) \right\rangle_{L_2(q)}.
$$

(21)

**Proof.** Assume the $h_n \downarrow 0$ case. Use corollary 5 and solve for $\omega$ and $\gamma$ in the system of equations: $q = p^2 \omega \gamma + 2$, $g = p \omega \gamma$. In the $h_n = h_1$ case, the conditions satisfy those given in von Luxburg et al. (2008) with the modification that the kernel is not bounded away from 0 and the additional assumption that $p$ is bounded away from 0. Thus, the asymptotic degree operator $d$ is bounded away from 0, and the proofs in von Luxburg et al. (2008) remain unchanged. \qed

We note that the restriction to an equicontinuous family of kernel functions excludes kNN graph constructions. However, one may get around this by considering the two-step transition kernels $K_2(x, y) = K(x, \cdot) \ast K(\cdot, y)$, where $\ast$ denotes the convolution operator with respect to the underlying density. For indicator kernels like those used in kNN graph constructions, $K_2$ will be Lipschitz and hence form an equicontinuous family. Thus, if one handles the potential issues with the random bandwidth function, one may apply the theory of compact integral operators to obtain convergence of the spectrum and eigenvectors for kNN graph Laplacians when $k$ grows appropriately.

### 5.5 Reasons for choosing a graph construction method

We highlight how our more general kernel can yield advantageous properties. In particular, it yields graphs constructions where one can (1) control the sparsity of the Laplacian matrix, (2) control connectivity properties in low density regions, (3) give asymptotic limits that cannot be attained using previous graph construction methods, and (4) give Laplacians with good spectral properties in the non-shrinking bandwidth case.
One way to control (1) and (2) is to make the binary choice of using kNN or a kernel with uniform bandwidth to construct the graph. Our results show that, by using a pilot estimate of the density, one can obtain sparsity and connectivity properties in the continuum between these two choices.

For (3) and (4), we note that the limits for previously analyzed unnormalized Laplacians were of the form \( p^{\alpha-1} \Delta p^\alpha f \). Using corollary 5 one see that limits of the form \( \frac{q}{p} \Delta q \) for any smooth, bounded density \( q \) on the manifold can be obtained. Equivalently, one can approximate the smoothness functional \( \|\nabla f\|_{L_2(q)}^2 \) for any almost any \( q \), not just \( p^\alpha \).

For normalized Laplacians, which have good spectral properties, the previously known limits induced smoothness functionals of the form \( \|\nabla (p^{(1-\alpha)/2} f)\|_{L_2(p^\alpha)}^2 \).

With our more general kernel and any \( g, q \in C^2(M) \), we may induce a smoothness functional of the form \( \|\nabla (gf)\|_{L_2(q)}^2 \). In particular, in the interesting case where \( g = 1 \) and the smoothness functional is just a norm on the gradient of \( f \), i.e. \( \|\nabla f\|_{L_2(q)}^2 \), \( q \) may be chosen to be almost any density, not just \( q = p^1 \).

6 Conclusions

We have introduced a general framework that enables us to analyze a wide class of graph Laplacian constructions. Our framework reduces the problem of graph Laplacian analysis to the calculation of a mean and variance (or drift and diffusion) for any graph construction method with positive weights and shrinking neighborhoods. Our main theorem extends existing strong operator convergence results to non-smooth kernels, and introduces a general location-dependent bandwidth function. The analysis of a location-dependent bandwidth function, in particular, significantly extends the family of graph constructions for which an asymptotic limit is known. This family includes the previously unstudied (but commonly used) kNN graph constructions, unweighted \( r \)-neighborhood graphs, and “self-tuning” graphs.

Our results also have practical significance in graph constructions as they suggest graph constructions that (1) can produce sparser graphs than those constructed with the usual kernel methods, despite having the same asymptotic limit, and (2) in the fixed bandwidth regime, produce normalized Laplacians that have well-behaved spectra but converge to a different class of limit operators than previously studied normalized Laplacians. In particular, this class of limits include those that induce the smoothness functional \( \|\nabla f\|_{L_2(q)}^2 \) for almost any density \( q \). The graph constructions may also (3) have better connectivity properties in low-density regions.

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8 Appendix

8.1 Main lemma

**Lemma 7** (Integration with location dependent bandwidth). Let 1 be the indicator function and h > 0 be a constant. Let r, be a location dependent bandwidth
function that satisfies the standard assumptions, i.e. it has a Taylor-like expansion
\[ \ddot{r}_x(y) = r_x(x) + (\dot{r}_x(x) + \alpha_x \text{sign}(u_x^T s) u_x) s + \epsilon_r(x, s). \]

Let \( V_m = \frac{m^{m/2}}{\Gamma(m+1)} \) be the volume of the unit \( m \)-sphere.

\[ M_0 = \frac{1}{V_m h^m} \int \mathbb{1} \left( \frac{\|y - x\|}{\dot{r}_x(s)} < h \right) ds = r_x(x)^m + h^2 \epsilon_0(x, h) \]
\[ M_1 = \frac{1}{V_m h^m} \int s \mathbb{1} \left( \frac{\|y - x\|}{\dot{r}_x(s)} < h \right) ds = h^2 r_x(x)^{m+2} \dot{r}(x) + h^3 \epsilon_1(x, h) \]
\[ M_2 = \frac{1}{V_m h^m} \int s^2 \mathbb{1} \left( \frac{\|y - x\|}{\dot{r}_x(s)} < h \right) ds = \frac{2h^2}{m+2} r_x(x)^{m+2} I + h^3 \epsilon_2(x, h) \]

where \( \sup_{x \in M, h < h_0} \| \epsilon_1(x, h) \| < C_\epsilon \) for some constant \( C_\epsilon > 0 \).

**Proof.** Let \( v(s) = \ddot{r}(x) + \text{sign}(s^T u_x) \alpha_x u_x \). We will show that the set on which the indicator function is approximately a sphere shifted by \( v/r_x(x) \) with radius \( h r_x(x) \).

\[ \mathbb{1} \left( \frac{\|y - x\|}{\dot{r}_x(s)} < h \right) = \mathbb{1} \left( \|s\|^2 + \|L(s^T s)^T s + O(\|s\|^2) \right) < h^2 (r_x(x) + v(s)^T s + O(\|s\|^2))^2 \]
\[ = \mathbb{1} \left( \|s\|^2 < h^2 r_x(x)^2 (1 + 2v(s)^T s + O(h^2)) \right) \]
\[ = \mathbb{1} \left( \|s\|^2 - 2h^2 v(s)^T s + h^4 v(s)^T v(s) r_x(x)^2 < h^2 r_x(x)^2 + O(h^4) \right) \]
\[ = \mathbb{1} \left( \left\| s - \frac{v(s)}{r_x(x)} \right\| < h r_x(x) + h^3 \delta_x(s) \right) \]

for some function \( \delta_x(s) \). Furthermore, the assumptions on the bounded curvature of the manifold and uniform bounds on the bandwidth function remainder term \( \epsilon_r(x, s) \) give that the perturbation term \( \delta_x(s) \) may be uniformly bounded by \( \sup_{x \in M} \| \delta_x(s) \| \leq C_\delta(\|s\|^2) \) for some constant \( C_\delta \).

The result for the zeroth moment follows immediately from this. The results for the first and second moments we calculate in lemma [10]. \( \square \)

### 8.1.1 Refined analysis of the zeroth moment

For convergence of the normalized Laplacian, we need a more refined result for the zeroth moment.

**Lemma 8.** Assume
\[ \ddot{r}_x(y) = r_x(s) + \epsilon_r(x, s). \]
where \( r_x(s) \) is twice continuously differentiable as a function of \( x \) and \( s \) and and \( \epsilon_r \) is bounded. Then

\[
\int \frac{1}{V_m h^m} \left( \|y - x\| < h \right) ds = r_x(x)^m + h^2 b(x) + h^2 \epsilon_0(x, h)
\]

where \( b \) is continuous and \( \sup_x |\epsilon_0(x, h)| \to 0 \) as \( h \to 0 \).

**Proof.** We first sketch idea behind the proof and leave the details to interested readers. One may convert the integral in normal coordinates to an integral in polar coordinates \((R, \theta)\). One may then apply the implicit function theorem to obtain that the unperturbed radius function \( R \) is a twice continuously differentiable function of \( h \). This gives a Taylor expansion of the zeroth moment with respect to \( h \). \( \epsilon_r(x, s) \) gives the desired result.

We may express the integral for the zeroth moment in polar coordinates

\[
Z_x(h) = \int \frac{1}{V_m h^m} \left( \|y - x\| < h \right) ds = \int R_x(\theta, h) d\mu_\theta \text{ where } \mu_\theta \text{ is the uniform measure on the surface of the unit } m\text{-sphere and } \tilde{s} = s/h = R_x(\theta, h) \theta \text{ solves the equation}
\]

\[
\|\tilde{s}\|^2 + L(\tilde{s}^T \tilde{s}) = \left( r_x(x) + h \nabla r_x(x)^T \tilde{s} + h^2 \tilde{s}^T \mathcal{H}_{r_x}(0) \tilde{s} \right)^2.
\]

and \( \mathcal{H}_{r_x}(0) \) is the Hessian of \( r_x(\cdot) \) evaluated at 0.

By the implicit function theorem, the solutions \( \tilde{s} \) define a twice continuously differentiable function of \( x, h \). For sufficiently small \( h \geq 0 \), \( \tilde{s} \) is bounded away from 0 since \( r_x \) is bounded away from 0 and \( \|s/h\| \) is bounded away from \( \infty \) by the bound in lemma 7. Thus, \( R_x(\theta, h) \) and \( Z_x(h) \) are twice continuously differentiable with bounded second derivatives.

\( Z_x(h) \) then has a second-order Taylor expansion \( Z_x(h) = Z_x(0) + Z'_x(0) h + Z''_x(0) h^2 + o(h^2) \).

By the less refined analysis in lemma 7 we have that \( Z_x(0) = r_x(x)^m \) and \( Z'_x(0^+) = 0 \). One may apply a squeeze theorem to obtain that the contribution of the error term \( \epsilon_r(x, s) \) to the zeroth moment is bounded by \( C_{\epsilon_r} \sup_{x,s} |\epsilon_r(x, s)| \) for some constant \( C_{\epsilon_r} \), and the result follows.

### 8.2 Moments of the indicator kernel / Integrating over the centered sphere in normal coordinates

Here we calculate the first three moments of the normalized indicator kernel where \( V_m = \int 1(\|u\| < 1) du = \int_{S_m} du \) is the volume of the \( m \)-dimensional unit sphere in Euclidean space.

**Lemma 9** (Moments for the sphere). Let \( K(\|s\|/h) = \frac{1}{V_m} 1(\|s\| < h) \). Then
the first two moments are given by:

\[ M_0 = \int K(\|s\| / h) ds = \frac{1}{h^m V_m} \int_{S_m} ds = 1 + O(h^3) \]

\[ M_1 = \int sK(\|s\| / h) ds = \frac{1}{h^m V_m} \int_{S_m} sds = 0 + O(h^4) \]

\[ M_2 = \int ss^T K(\|s\| / h) ds = \frac{1}{h^m V_m} \int_{S_m} ss^T ds = \frac{1}{m+2} 1 + O(h^4). \]

**Proof.** The error terms \( O(h^i) \) arise trivially after converting normal coordinates to tangent space coordinates. Thus, we may simply treat the integrals as integrals in \( m \)-dimensional Euclidean space to obtain the leading term. The values for \( M_0 \) and \( M_1 \) follow immediately from the definition of the volume \( V_m \) and by symmetry of the sphere. We obtain the second moment result by calculating the values on the diagonal and off-diagonal. On the off-diagonal

\[ \frac{1}{V_m} \int_{S_m} s_i s_j ds = 0 \]

for \( i \neq j \) due to symmetry of the sphere.

On the diagonal

\[ \frac{1}{V_m} \int_{S_m} s_i^2 ds = \frac{V_{m-1}}{V_m} \int_{-1}^{1} s_i^2 \left(1 - s_i^2\right)^{(m-1)/2} ds_i \]

\[ = \frac{V_{m-1}}{V_m} \int_{-1}^{1} s_i \times s_i \left(1 - s_i^2\right)^{(m-1)/2} ds_i \]

\[ = 0 + \frac{V_{m-1}}{V_m} \int_{-1}^{1} \frac{1}{m+1} \left(1 - s_i^2\right)^{(m+1)/2} ds_i \]

\[ = \frac{1}{m+1} \frac{V_{m-1}}{V_{m+1}} \int_{-1}^{1} V_{m+1} \left(1 - s_i^2\right)^{(m+1)/2} ds_i \]

\[ = \frac{1}{m+1} \frac{V_{m-1}}{V_{m+2}} \]

\[ = \frac{1}{m+2} \]

where the last equality uses the recurrence relationship \( V_{m+2} = \frac{2\pi}{m+2} V_m. \)

### 8.3 Integrating the shifted and perturbed sphere

Here we calculate the moments used in Lemma 7.

The integrals in lemma 7 essentially involve integrating over sphere with (1) a shifted center \( h^2 \tilde{r}_x(x) \), (2) a symmetric shift by \( \text{sign}(s^T u) h^2 \alpha_x u \) on two half-spheres, and (3) a small perturbation \( h^3 \delta_x(s) \).

**Lemma 10** (Moments of the shifted and perturbed sphere). Let \( v_c \in \mathbb{R}^m \), \( u \) be a unit vector in \( \mathbb{R}^m \), \( \beta \in \mathbb{R} \), and \( h > 0 \). Define \( K(s) = I\left(\|s - v_c + \text{sign}(s^T u) \beta u\| < h \right. \)

\[ \begin{align*}
M_0 &= \int K(\|s\| / h) ds = \frac{1}{h^m V_m} \int_{S_m} ds = 1 + O(h^3) \\
M_1 &= \int sK(\|s\| / h) ds = \frac{1}{h^m V_m} \int_{S_m} sds = 0 + O(h^4) \\
M_2 &= \int ss^T K(\|s\| / h) ds = \frac{1}{h^m V_m} \int_{S_m} ss^T ds = \frac{1}{m+2} 1 + O(h^4).
\end{align*} \]
\(h + h^3\delta\), so that the support of \(\tilde{K}\) is a shifted and perturbed sphere with center \(v_c\), symmetric shift \(\text{sign}(s^T u)\beta u\), and radius perturbation \(h^3\delta\).

Assume \(\|v_c\|, |\beta| < Ch^2\) and \(\delta < \min\{C, 1\}\) for some constant \(C\), and put \(h_{\text{max}} = h + h^3\delta\)

Then

\[
M_0 = \frac{1}{V_m} \int_{R^m} \tilde{K}(s) ds = h^m + \epsilon_0
\]

\[
M_1 = \frac{1}{V_m} \int_{R^m} s\tilde{K}(s) ds = h^{m+2}v_c + \epsilon_1
\]

\[
M_2 = \frac{1}{V_m} \int_{R^m} ss^T\tilde{K}(s) ds = \frac{h^{m+2}}{m+2}I + \epsilon_2.
\]

where \(\epsilon_1 < \kappa Ch_{\text{max}}^{m+1}\) and \(\epsilon_i < \kappa Ch_{\text{max}}^{m+3}\) for \(i = 1, 2\) and \(\kappa\) is some universal constant that does not depend on \(\delta, v_c\), or \(\beta\).

**Proof.** Set \(H_+ = \{ s \in \mathbb{R}^m : u^Ts > 0 \}\) and \(H_- = H_+^C\) to be the half-spaces defined by \(u\). For a set \(H \subset \mathbb{R}^m\), let \(H + v_c := \{ w + v_c : w \in H \}\).

We first bound the error introduced by the perturbation \(h^3\delta\). Define

\[
\mathcal{A} := \text{supp}(\tilde{K}) = \{ s \in \mathbb{R}^m : \|s - v_c + \text{sign}(s^T u)\beta u\| < h + h^3\delta \}
\]

\[
\overline{\mathcal{A}} := \{ s \in \mathbb{R}^m : \|s - v_c + \text{sign}(s^T u)\beta u\| < h \}
\]

so that \(\overline{\mathcal{A}}\) gets rid of the dependence on the perturbation.

For any function \(Q\), we have a trivial bound

\[
\left| \int_{\mathcal{A}} Q(s) ds - \int_{\overline{\mathcal{A}}} Q(s) ds \right| < Q_{\text{max}} |\text{Vol}(\mathcal{A}) - \text{Vol}(\overline{\mathcal{A}})|
\]

\[
< Q_{\text{max}} V_m |h_{\text{max}}^m - h^m|
\]

\[
< Q_{\text{max}} V_m (m h_{\text{max}}^{m-1})(h^3\delta)
\]

\[
= O(h^{m+2}Q_{\text{max}})
\]

where \(Q_{\text{max}} = \sup_{\|s\| < h_{\text{max}}} Q(s)\) and \(mV_{m-1}\) is the surface area of the \(m\)-dimensional sphere. For \(Q(s) = 1/V_m\), \(s/V_m\), or \(ss^T/V_m\), the corresponding \(Q_{\text{max}}\) are \(1/V_m\), \(h_{\text{max}}/V_m\), and \(h_{\text{max}}^2/V_m\). The error induced by the perturbation is thus of the right order.

We now consider the integral over the unperturbed but shifted sphere. Denote by \(B_h(v)\) the ball of radius \(h\) centered on \(v\). Note that the function \(1(s \in \overline{\mathcal{A}}) = 1(\|s - v_c + \text{sign}(s^T u)\beta u\| < h)\) is symmetric around \(v_c\). Thus,
for a function $Q(s - v_c + \beta u)$ which is symmetric around $v_c$,

\[
\int_{\mathcal{A}} Q(s - v_c) ds = 2 \int_{\mathcal{X} \cap H^+} Q(s - v_c) ds
\]

\[
= 2 \int_{H^+} Q(s - v_c) [1(||s - v_c|| < h)] ds
- 2 \int_{H^+} Q(s - v_c) [1(||s - v_c| < h) - 1(||s - v_c + \beta u| < h)] ds
\]

\[
= \int Q(s) [1(||s|| < h)] ds
- 2 \int_{H^+} Q(s - v_c) [1(s \in B_h(v_c)) - 1(s \in B_h(v_c - \beta u))] ds.
\]

For $Q(s) = 1/V_m$ or $ss^T/V_m$, lemma [9] gives that the value of the main term $\int Q(s) [1(||s|| < h)] ds$ is $h^m$ or $\frac{h^{m+2}}{m+2} I$ respectively. The error term is bounded by

\[
2 \int_{H^+} Q(s - v_c) [1(s \in B_h(v_c)) - 1(s \in B_h(v_c - \beta u))] ds
\]

\[
\leq 2Q_{\text{max}} \int_{H^+} [1(s \in B_h(v_c)) - 1(s \in B_h(v_c - \beta u))] ds
\]

\[
< 2Q_{\text{max}} |\beta| \text{Area}(H^+ \cap B_h(v_c))
\]

\[
< 2Q_{\text{max}} |\beta| (mV_{m-1} h^{m-1})
\]

\[
< 2m V_{m-1} C Q_{\text{max}} h^{m+1}
\]

where \(\text{Area}(H^+ \cap B_h(v_c))\) is the surface area of a half-sphere of radius $h$. Plugging in $Q_{\text{max}} = 1/V_m$ and $h^2/V_m$ give that the error terms for the zeroth and second moment calculations are of the right order.

By another symmetry argument, we have for the first moment calculation

\[
\frac{1}{V_m} \int_{\mathcal{A}} s ds = \frac{v_c}{V_m} \int_{\mathcal{A}} ds
\]

\[
= h^m v_c + O(h^{m+3})
\]

where the last equality holds from the calculation of the zeroth moment above. More precisely, the error term is bounded by $2m V_{m-1} C Q_{\text{max}} h^{m+1} v_c$. 

\[
\square
\]
