RANDOM NETWORKS WITH PREFERENTIAL GROWTH AND VERTEX DEATH

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Abstract
A dynamic model for a random network evolving in continuous time is defined, where new vertices are born and existing vertices may die. The fitness of a vertex is defined as the accumulated in-degree of the vertex and a new vertex is connected to an existing vertex with probability proportional to a function \( b \) of the fitness of the existing vertex. Furthermore, a vertex dies at a rate given by a function \( d \) of its fitness. Using results from the theory of general branching processes, an expression for the asymptotic empirical fitness distribution \( \{ p_k \} \) is derived and analyzed for a number of specific choices of \( b \) and \( d \). When \( b(i) = i + \alpha \) and \( d(i) = \beta \), that is, linear preferential attachment for the newborn and random deaths, then \( p_k \sim k^{-(2+\alpha)} \). When \( b(i) = i + 1 \) and \( d(i) = \beta(i + 1) \), with \( \beta < 1 \), then \( p_k \sim (1 + \beta)^{-k} \), that is, if the death rate is also proportional to the fitness, then the power-law distribution is lost. Furthermore, when \( b(i) = i + 1 \) and \( d(i) = \beta(i + 1) \gamma \), with \( \beta, \gamma < 1 \), then \( \log p_k \sim -k\gamma \), a stretched exponential distribution. The momentaneous in-degrees are also studied and simulations suggest that their behaviour is qualitatively similar to that of the fitneses.

Keywords: Branching process; random network; preferential attachment; power-law distribution; degree distribution

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1. Introduction

Empirical studies on real networks have revealed that many of them exhibit features that are not captured by the classical Erdős–Rényi graph. In particular, many networks tend to have a quite heavy-tailed degree distribution, often described by a power law, that is, the fraction of vertices with degree \( k \) decays as \( k^{-\tau} \) for some exponent \( \tau \). To capture this, a number of new graph models have been developed that allow for this type of degree distribution; see, for instance, the seminal paper by Bollobás [5] (the setup described there includes many previously studied models as special cases) and the references therein.

A model type that has received a lot of attention is based on preferential attachment: new vertices are successively added to the network and are connected to existing vertices proportionally to a function \( f(k) = k^\gamma \) of the degree. The mechanism was introduced in the context of network modelling by Barabási and Albert [3], who observed that, for \( \gamma = 1 \), it seemed to lead to power-law distributions with exponent \( \tau = 3 \) for the degrees. This was proved rigorously in [6]. Krapivsky and Redner [14] later derived heuristic results indicating that the regimes \( \gamma \leq 1 \) and \( \gamma > 1 \) are qualitatively different: for \( \gamma > 1 \), the degree distribution is degenerate in the sense that there is a single dominant vertex that is connected to almost
every other vertex. This was confirmed in [18]. Recently, Dereich and Mörters [10] studied the degree evolution in the sublinear regime $\gamma < 1$.

Most preferential attachment models in the literature are defined in discrete time. Rudas et al. [19] however studied the model from a new perspective, embedding it in continuous time and interpreting it as a continuous-time branching process. This opens up for the use of well-established results from the theory of branching processes. Compared to the traditional techniques for analyzing models with linear preferential attachment, the approach has the advantage that it applies for any $\gamma \leq 1$. We mention also the paper by Athreya et al. [2], where the linear case $\gamma = 1$ is studied by aid of a different type of branching process embedding.

The purpose of the current paper is to define and analyze a preferential attachment model embedded in continuous time where vertices are not just added but may also die, and where the death rate of a vertex is taken to be a function of its previous success, quantified by its accumulated degree. Using results from the theory of general branching processes, a characterization of the asymptotic distribution of the accumulated degrees is derived and analyzed in various special cases. The momentaneous degrees are also discussed and analyzed by means of simulations. This generalizes results from [19]. More specifically, the generalization compared to [19] lies in that we work with a birth-and-death process instead of a pure-birth process. We also mention the paper by Britton and Lindholm [4], where a model is treated that is similar in spirit but not based on preferential attachment.

Preferential attachment models incorporating deaths of vertices are much less studied than pure-growth models, while real networks may well be affected by vertex emigration. Existing rigorous results are restricted to the case when vertices die randomly, that is, the death mechanism does not depend on features of the vertices (age, degree, etc.); see [7] and [8]. See also [9] and [15] for heuristic results, the latter concerning a situation where vertices die with a probability inversely proportional to their degree. Concentration results are so far comparably weak, see, e.g. [8, Lemma 4.1], and are lacking for models with more complicated death mechanisms.

1.1. Definition of the model

We now proceed to define the model. As already described, a vertex population evolving in continuous time is considered where existing vertices give birth to new vertices but may also die. More specifically, a vertex that is alive at time $t$ and that has given birth to $i$ new vertices during its lifetime, gives birth to an $(i + 1)$th vertex at rate $b(i)$, that is, the probability that the vertex gives birth in the time interval $(t, t + \varepsilon)$ is $b(i)\varepsilon + o(\varepsilon)$. Furthermore, the vertex dies at rate $d(i)$, that is, its probability of dying during $(t, t + \varepsilon)$ is $d(i)\varepsilon + o(\varepsilon)$. Let $\xi$ be a random point process on $[0, \infty)$ with points (representing the births) generated according to the above rules. Starting from a single root vertex at time 0, each vertex $x$ reproduces according to an independent copy $\xi_x$ of $\xi$. This means that the vertex population evolves as a birth-and-death process in continuous time and, hence, fits into the framework of general branching processes; see, e.g. [12, Chapter 6]. Below we shall formulate conditions which guarantee that the process is supercritical, so that the vertex population indeed grows to infinity with positive probability.

Write $Z_t$ for the set of vertices that are alive at time $t$, and, for $x \in Z_t$, let $A^x_t$ denote the total number of children that vertex $x$ has produced up to time $t$ (including children that are no longer alive), also referred to as the fitness of the vertex. The time until the next birth in the population is exponentially distributed with parameter $\sum_{x \in Z_t} b(A^x_t)$ and the time until the next death is exponentially distributed with parameter $\sum_{x \in Z_t} d(A^x_t)$. Hence, the probability
that the next event that occurs in the population is a birth is given by

\[ \sum_{x \in \mathbb{Z}} b(A^x_t) \left( \frac{-\lambda}{\lambda + b(i) + d(i)} \right) \cdot \sum_{x \in \mathbb{Z}} (b(A^x_t) + d(A^x_t)) \cdot \lambda \]

and the probability that the birth occurs at vertex \( x \) is proportional to \( b(A^x_t) \). We shall see later that, under certain assumptions on \( b \) and \( d \), the ratio (1.1) converges almost surely to a number in \((0, 1)\).

The vertex population described above naturally gives rise to a network structure: directed edges are created between a vertex and its children, pointing from the child to the mother. When a vertex dies it turns into a \textit{ghost} and all edges associated with it are turned into \textit{ghost links}. According to the dynamics, the rate at which a vertex produces/attracts new vertices depends on its previous success, measured by its in-degree, including ghost links. Whether or not it is realistic to include the ghost links depends on the setting. In many situations it is indeed natural to assume that the ability of a vertex to acquire new edges is affected by the total historical success of the vertex rather than just the contributions generated by vertices that are still present in the network (think e.g. of coauthorship networks, sexual networks, recruitment networks, etc.). A model where ghost links are excluded in the definition of the fitness can be analyzed by the same means as the present model. The calculations however become cumbersome and do not lead to explicit expressions. We elaborate on this and present simulation results in Section 5.

1.2. Results

Let \( \rho(t) \) be the density of \( \xi \), that is,

\[ \rho(t) = \lim_{\epsilon \to 0} \epsilon^{-1} P((t, t + \epsilon) \text{ contains a point from } \xi), \]

and define the Laplace transform

\[ \hat{\rho}(\lambda) = \int_0^\infty e^{-\lambda t} \rho(t) \, dt. \] (1.2)

Clearly, \( \hat{\rho}(\lambda) \) increases as \( \lambda \to 0 \), and we write

\[ \lambda^* = \inf\{\lambda > 0 : \hat{\rho}(\lambda) < \infty\}. \] (1.3)

Our first result is an expression for \( \hat{\rho}(\lambda) \).

Proposition 1.1. We have

\[ \hat{\rho}(\lambda) = \sum_{k=0}^\infty \prod_{i=0}^k \frac{b(i)}{\lambda + b(i) + d(i)}. \]

Throughout, we shall assume that the functions \( b \) and \( d \) are such that

(C1) \( \hat{\rho}(\lambda^*) = 1 \) has a solution \( \lambda^* \in (0, \infty) \).

In fact, we shall assume that

(C2) \( \lambda^* > \lambda \).
It is well known from the theory of branching processes that, when $\lambda < \infty$, condition (C1) is equivalent to the process being supercritical. To be more precise, write $\xi(t)$ for the $\xi$-measure of $[0, t]$ and let $Z_t = |Z_t|$ be the number of vertices alive at time $t$. Then $P(Z_t \to \infty) > 0$ if and only if $E[\xi(\infty)] > 1$ if and only if $\lambda^* > 0$; see [12, Chapter 6]. Writing

$$\hat{\rho}(\lambda) = \sum_{k=0}^{\infty} \exp \left( \sum_{i=0}^{k} \log \left( 1 - \frac{\lambda + d(i)}{\lambda + b(i) + d(i)} \right) \right)$$

and using the Taylor expansion $\log(1 - x) = -x + O(x^2)$ reveals that a necessary condition for $\hat{\rho}(\lambda) < \infty$ is that

$$\sum_{i=0}^{\infty} \frac{\lambda + d(i)}{\lambda + b(i) + d(i)} = \infty,$$

and, hence, a necessary condition for $\lambda < \infty$ (which is indeed necessary for (C1)) is that

$$\sum_{i=0}^{\infty} \frac{1 + d(i)}{b(i) + d(i)} = \infty.$$

Furthermore, a sufficient condition for having $\hat{\rho}(\lambda) < \infty$ for all $\lambda > 0$ (so that $\lambda^* = 0$) is that

$$\frac{1 + d(i)}{d(i) + b(i)} \geq ci^{-\gamma} \text{ for some } \gamma < 1.$$  

Indeed, a bound of the same order then applies for $(\lambda + d(i))/(\lambda + b(i) + d(i))$ and, hence, by the Taylor expansion and integral approximation, the exponent in (1.4) decays at least like $-k^{1-\gamma}$, making the sum convergent. Also, note that (C1)—or, more specifically, the fact that $\lambda^* < \infty$—guarantees that the process does not explode in finite time: a sufficient condition for nonexplosion is that $E[\xi(t)] < \infty$ for some $t > 0$ (see [12, Theorem 6.2.2]), and, since $\rho(t) \, dt = E[\xi(dt)]$, it is clear that $\lambda^*$ cannot be finite if this does not hold.

We are now ready to formulate the main theorem, which is a characterization of the asymptotic fitness distribution in the vertex population. To this end, recall that $Z_t$ is the number of alive vertices at time $t$ and write $Z_t^k$ for the number of alive vertices at time $t$ with fitness $k$.

**Theorem 1.1.** Assume that $b$ and $d$ satisfy conditions (C1) and (C2). Then, for all $k$, on the event $\{Z_t \to \infty\}$, almost surely,

$$\lim_{t \to \infty} \frac{Z_t^k}{Z_t} = \frac{C}{\lambda^* + b(k) + d(k)} \prod_{i=0}^{k-1} \frac{b(i)}{\lambda^* + b(i) + d(i)},$$

where

$$C^{-1} = \int_0^\infty e^{-\lambda^* t} \, P(L > t) \, dt$$

and the empty product arising for $k = 0$ is defined as 1.

The rest of the paper is organized as follows. In Section 2 we state the results we shall need from the theory of branching processes and, in Section 3, Proposition 1.1 and Theorem 1.1 are proved. Then, in Section 4, the limiting distribution in Theorem 1.1 is analyzed in more
detail for a number of specific choices of \( b(i) \) and \( d(i) \). In Section 5, a formula is given for the asymptotic degree distribution in a network where the birth and death rates are based on the momentaneous in-degrees rather than the fitnesses (that is, the accumulated in-degrees). Unfortunately, this expression is hard to analyze, but simulation results are presented that indicate that the qualitative behaviour of the distribution is the same as for the fitnesses. Finally, some possibilities for further work are mentioned in Section 6.

2. Preliminaries on branching processes

The corpus of literature on branching processes is vast and we do not intend to give a survey; for this, see [12] or the more expository book by Haccou et al. [11]. We shall however briefly explain the concepts that are needed to establish Theorem 1.1. These revolve around general branching processes counted with random characteristics. In a general branching process, the individuals reproduce independently of each other according to a random point process \( \xi \) on \([0, \infty)\) during a lifetime \( L \), where there are no restrictions on the dependence structure between \( \xi \) and \( L \). An individual \( x \) can be represented as \( x = (j_1, \ldots, j_n) \), indicating that \( x \) is the \( j_n \)th child of the \( j_{n-1} \)th child … of the \( j_1 \)th child of the ancestor. Hence, the space of possible individuals is

\[
\Omega = \bigcup_{i=0}^{\infty} \mathbb{N}^n.
\]

Write \( \sigma_x \) for the time when the individual \( x \) is born, that is, \( \sigma_0 = 0 \) and, if \( x \) is the \( i \)th child of \( x' \), then

\[
\sigma_x = \sigma_{x'} + \inf\{t : \xi_{x'}(t) \geq i\}.
\]

Roughly, when counting a branching process with a random characteristic, a random score is assigned to each individual and the quantity of interest is then the total score in the population. More specifically, let \( \phi(t) \) be a real-valued stochastic process with \( \phi(t) = 0 \) for \( t \leq 0 \) giving the score of an individual of age \( t \). The score of the individual \( x \) at time \( t \) is then given by \( \phi_x(t) = \phi(t - \sigma_x) \) and the total score in the population at time \( t \) becomes

\[
Z^\phi_t = \sum_{x \in \Omega} \phi_x(t).
\]

Examples of common characteristics are \( \phi(t) = 1 \{t \geq 0\} \), in which case \( Z^\phi_t \) is the number of individuals born up to time \( t \), and \( \phi(t) = 1\{0 \leq t < L\} \), in which case \( Z^\phi_t \) is the number of individuals that are alive at time \( t \)—for this quantity, we shall use the notation \( Z_t \). These characteristics are both individual, meaning that \( \xi_x \) depends only on the process of descendants of \( x \). Characteristics that also involve information about preceding generations are called relational. An example of such a characteristic that we shall be interested in below is when an individual is assigned the value 1 if its mother is still alive and 0 otherwise.

The Laplace transform \( \hat{\rho}(\lambda) \) of the density \( \rho(t) \) of \( \xi \) and the related quantity \( \lambda^* \) are defined as in (1.2) and (1.3). The solution \( \lambda^* \) to the equation \( \hat{\rho}(\lambda) = 1 \) is called the Malthusian parameter and the process is subcritical, critical, or supercritical depending on whether \( \lambda^* \) is less than 0, equal to 0, or greater than 0, respectively. A more frequent formulation of the definition of \( \lambda^* \) in the literature is as the solution to the equation

\[
\int_0^\infty e^{-\lambda t} \mathbb{E}[\xi(dt)] = 1,
\]

where, as in Section 1.1, \( \xi(t) = \xi([0, t]) \). Since \( \mathbb{E}[\xi(dt)] = \rho(t) dt \), the formulations are clearly equivalent.
Now, Theorem 1.1 will turn out to be a direct consequence of the following result concerning almost-sure convergence of ratios of random characteristics.

**Theorem 2.1.** ([17.]) Consider a supercritical branching process with Malthusian parameter \( \lambda^* > \lambda \) and let \( \phi \) and \( \psi \) be two individual characteristics satisfying

\[
E\left[ \sup_t \left( e^{-\lambda t} \phi(t) \right) \right] < \infty \text{ for some } \lambda < \lambda^*,
\]

(2.1)

and likewise for \( \psi \). Then, on the event \( \{Z_t \to \infty\} \), almost surely,

\[
\frac{Z_t^\phi}{Z_t^\psi} \to \frac{\hat{\phi}(\lambda^*)}{\hat{\psi}(\lambda^*)},
\]

where \( \hat{\phi}(\lambda) = \int_0^\infty e^{-\lambda t} E[\phi(t)] \, dt \).

**Remark 2.1.** The characteristics we shall work with will in general be bounded and, for such characteristics, (2.1) is trivially satisfied.

**Remark 2.2.** As pointed out in [11, p. 163], the conclusion of the theorem also holds for relational characteristics provided that these depend only on a finite number of preceding generations; see [13] for details.

3. Proofs

We now return to the specific setting defined in Section 1.1, where \( \xi \) is the point process generated by the described birth and death rules.

**Proof of Proposition 1.1.** The expression for \( \hat{\rho}(\lambda) \) follows from straightforward calculations. First note that

\[
\hat{\rho}(\lambda) = \sum_{k=0}^\infty b(k) \int_0^\infty e^{-\lambda t} P(\xi(t) = k \cap L > t) \, dt,
\]

where, trivially,

\[
P(\xi(t) = k \cap L > t) = P(\xi(t) = k) - P(\xi(t) = k \cap L \leq t).
\]

Consider a generic vertex (the root vertex for instance) and write \( T_i \) for the time, counting from the birth of the vertex, when its \( i \)th child is born, with \( T_i := \infty \) if \( \xi(\infty) < i \). Also, when \( T_i < \infty \), define \( \Delta_i^b = T_{i+1} - T_i \) and let \( \Delta_i^d \) be the time, counting from \( T_i \), until the vertex dies. For \( k = 0 \), we obtain

\[
\int_0^\infty e^{-\lambda t} P(\xi(t) = 0 \cap L > t) \, dt = \int_0^\infty e^{-\lambda t} P(0 \cap L > t) \, dt
\]

\[= \frac{1}{\lambda + b(0) + d(0)},\]

where \( e^{-\lambda t} P(0 \cap L > t) \) is the probability that nothing happens in the process up to time \( t \). To deal with \( k \geq 1 \), note that

\[
P(\xi(t) = k) = P(\xi(t) = k \mid T_k < \infty) P(T_k < \infty),
\]
with

\[ P(\xi(t) = k \mid T_k < \infty) = P(\xi(t) \geq k \mid T_k < \infty) - P(\xi(t) \geq k + 1 \mid T_{k+1} < \infty) P(T_{k+1} < \infty \mid T_k < \infty). \]

Here

\[ P(\xi(t) \geq k \mid T_k < \infty) = \mathbb{P}\left( \sum_{i=0}^{k-1} \Delta^b_i \leq t \mid T_k < \infty \right), \]

where, conditionally on \( T_k < \infty \), the variables \( \Delta^b_0, \ldots, \Delta^b_{k-1} \) are independent and \( \Delta^b_i \) is exponentially distributed with parameter \( b(i) + d(i) \). Similarly,

\[ P(\xi(t) = k \cap L \leq t) = P(\xi(t) = k \cap L \leq t \mid T_k < \infty \cap T_{k+1} = \infty) \times P(T_k < \infty \cap T_{k+1} = \infty) \]

with

\[ P(\xi(t) = k \cap L \leq t \mid T_k < \infty \cap T_{k+1} = \infty) = \mathbb{P}\left( \sum_{i=0}^{k-1} \Delta^b_i + \Delta^d_i \leq t \mid T_k < \infty \cap T_{k+1} = \infty \right), \]

where, conditionally on \( T_k < \infty \cap T_{k+1} = \infty \), the variables \( \Delta^b_1, \ldots, \Delta^b_{k-1}, \Delta^d_k \) are independent, \( \Delta^b_i \) is exponentially distributed with parameter \( b(i) + d(i) \), and \( \Delta^d_k \) is exponentially distributed with parameter \( b(k) + d(k) \). Also, note that

\[ P(T_k < \infty) = \prod_{i=0}^{k-1} \frac{b(i)}{b(i) + d(i)} =: q_k, \]

\[ P(T_{k+1} < \infty \mid T_k < \infty) = -\frac{b(k)}{b(k) + d(k)} =: q'_k, \]

\[ P(T_k < \infty \cap T_{k+1} = \infty) = \frac{d(k)}{b(k) + d(k)} \prod_{i=0}^{k-1} \frac{b(i)}{b(i) + d(i)} =: q''_k. \]

For independent exponential variables \( \{X_i\} \), where \( X_i \) has parameter \( b(i) + d(i) \), write

\[ I_k = \int_0^\infty e^{-\lambda t} P(X_0 + \cdots + X_{k-1} \leq t) \, dt. \]

Combining all of the above, we obtain

\[ \hat{\rho}(\lambda) = \frac{b(0)}{\lambda + b(0) + d(0)} + \sum_{k=1}^{\infty} b(k)(q_k I_k - (q_k q'_k + q''_k) I_{k+1}), \tag{3.1} \]

and all that remains is to note that

\[ I_k = \frac{1}{\lambda} \int_0^\infty e^{-\lambda t} f_{X_0 + \cdots + X_{k-1}}(t) \, dt = \frac{1}{\lambda} \prod_{i=0}^{k-1} \frac{b(i) + d(i)}{\lambda + b(i) + d(i)}, \]

where the first equality follows from partial integration and the second from independence. Substituting this, and the expressions for \( q_k, q'_k, \) and \( q''_k \), into (3.1) gives the desired formula for \( \hat{\rho}(\lambda) \).
We proceed to prove the main result, Theorem 1.1, which, as already mentioned, follows from Theorem 2.1.

**Proof of Theorem 1.1.** Consider the characteristic

\[ \phi(t) = 1\{\xi(t) = k \cap 0 < t < L\}, \]

that is, \( Z^{\phi}_{t} = Z^{k}_{t} \) is the number of alive vertices with \( k \) children at time \( t \), and let \( \psi(t) = 1\{0 < t < L\} \) so that \( Z^{\psi}_{t} = Z_{t} \) is the number of alive vertices at time \( t \). These characteristics are both bounded, and, hence, since \( b \) and \( d \) are assumed to be such that (C1) and (C2) are satisfied, all assumptions of Theorem 2.1 are fulfilled. It follows that, on the event \( Z_{t} \to \infty \), the ratio \( Z^{k}_{t} / Z_{t} \) converges almost surely to the limit identified in Theorem 2.1. The expression in the denominator becomes

\[ \hat{\phi}(\lambda^*) = \int_{0}^{\infty} e^{-\lambda^*t} P(\xi(t) = k \cap L > t) \, dt, \]

and identical calculations as in the proof of Proposition 1.1 yield the formula in Theorem 1.1.

### 4. Examples

We now investigate the behaviour of the limiting fitness distribution in Theorem 1.1 for a few specific choices of birth and death rates \( b \) and \( d \). The limiting distribution is henceforth denoted by \( \{p_k\} \). Furthermore, for two sequences \( \{a_k\} \) and \( \{b_k\} \) of real numbers, we write \( a_k \sim b_k \) to denote that \( a_k/b_k \) converges to a strictly positive constant as \( k \to \infty \).

**Example 4.1.** First consider the case when \( b(i) = i + \alpha \) and \( d(i) = \beta \) with \( \alpha > 0 \), that is, the birth rate is a linear function of the fitness and the vertices die at a constant rate. This means that a new vertex is connected to an existing vertex with a probability that depends linearly on the fitness of the existing vertex, and the vertices die at random. Using the relation

\[ \prod_{i=0}^{k} (i + c) = \frac{\Gamma(k + 1 + c)}{\Gamma(c)}, \]

we obtain

\[ \hat{\rho}(\lambda) = \sum_{k=0}^{\infty} \frac{i + \alpha}{\lambda + i + \alpha + \beta} = \frac{\Gamma(\lambda + \alpha + \beta)}{\Gamma(\alpha)} \sum_{k=0}^{\infty} \frac{\Gamma(k + 1 + \alpha)}{\Gamma(k + 1 + \alpha + \beta + \lambda)}. \]

Van der Hofstad et al. [20, Lemma 5.4] derived the formula

\[ \sum_{k=0}^{n} \frac{\Gamma(k + a)}{\Gamma(k + c)} = \frac{1}{1 + a - c} \left( \frac{\Gamma(n + 1 + a)}{\Gamma(n + c)} - \frac{\Gamma(a)}{\Gamma(c - 1)} \right), \]  

and, by Stirling's formula, \( \Gamma(k + c)/\Gamma(k) \sim k^c \) as \( k \to \infty \). It follows that

\[ \hat{\rho}(\lambda) = \begin{cases} \alpha & \text{if } \lambda \leq 1 - \beta, \\ \frac{\lambda + \beta - 1}{\lambda + \beta} & \text{otherwise}. \end{cases} \]
Hence, $\lambda^* = 1 + \alpha - \beta$, implying that the process is supercritical if $\beta < \alpha + 1$. For the fitness distribution, we obtain

$$p_k = \frac{C}{k + 1 + 2\alpha} \prod_{i=0}^{k-1} \frac{i + \alpha}{i + 1 + 2\alpha} = C' \frac{\Gamma(k + \alpha)}{\Gamma(k + 2 + 2\alpha)} \sim k^{-(2+\alpha)}.$$

The limiting behaviour of the fitness distribution is hence unaffected by the vertex death. This is explained by the fact that the vertices die randomly, that is, given that the next thing to occur is a vertex death, the vertex to die is chosen uniformly at random, and such a mechanism does not affect the tail behaviour of the power-law distribution generated by the birth mechanism. With $\alpha = 1$, the expression for $p_k$ is in agreement with previous results for pure linear preferential attachment.

Recall that, given the development of the process up to time $t$, the probability that the next event occurring is a vertex birth is given by (1.1), where $A_x^t$ is the fitness of vertex $x$ at time $t$. If the characteristics given by $\phi_x(t) = b(A_x^t - \sigma_x)$ and $\psi_x(t) = d(A_x^t - \sigma_x)$ satisfy condition (2.1), then it follows from Theorem 2.1 that the probability converges almost surely to a number in $(0, 1)$. This number is in general difficult to determine, but in the current case, defining the total fitness by $A_{\text{tot}}^t = \sum_{x \in Z(t)} A_x^t$, we obtain

$$\frac{\sum_{x \in Z(t)} b(A_x^t)}{\sum_{x \in Z(t)} (b(A_x^t) + d(A_x^t))} = \frac{A_{\text{tot}}^t + \alpha Z_t}{A_{\text{tot}}^t + (\alpha + \beta) Z_t}.$$

The total fitness in the alive population can be obtained by counting the population by the characteristic $\psi(t) = \mathbb{1}\{t > 0 \text{ and the mother of the individual is alive}\}$. Hence, by Theorem 2.1 and Remark 2.2, the ratio $A_{\text{tot}}^t/Z_t$ converges to 1 almost surely and it follows that

$$\lim_{t \to \infty} P(\text{the next event is a vertex birth}) = \frac{1 + \alpha}{1 + \alpha + \beta}.$$

This probability is strictly larger than $\frac{1}{2}$ precisely when $\beta < \alpha + 1$, that is, when the process is supercritical.

**Example 4.2.** Next consider the case when $b(i) = i + 1$ and $d(i) = \beta(i + 1)$, that is, both the birth and death rates are linear functions of the fitness. In this case, by (1.5) we have $\hat{\rho}(\lambda) < \infty$ for all $\lambda > 0$, and it is given by

$$\hat{\rho}(\lambda) = \sum_{k=0}^{\infty} \prod_{i=0}^{k} \frac{i + 1}{\lambda + (1 + \beta)i + (1 + \beta)} = \Gamma\left(\frac{\lambda + 1 + \beta}{1 + \beta}\right) \sum_{k=0}^{\infty} \frac{\Gamma(k + 2)}{\Gamma(k + 1 + (\lambda + 1 + \beta)/(1 + \beta)) (1 + \beta)^k} = F\left(1, 1, \frac{\lambda + 1 + \beta}{1 + \beta}, \frac{1}{1 + \beta}\right) = 1,$$

where $F$ denotes the Gauss hypergeometric function; see Chapter 15 of [1]. The equation $\hat{\rho}(\lambda^*) = 1$ cannot be solved explicitly, but a numerical solution is easily obtained for a given value of $\beta$. The process is supercritical precisely when $\beta < 1$, since the expected number of
children produced by a vertex is given by

$$E[\xi(\infty)] = \sum_{k=1}^{\infty} P(\xi(\infty) \geq k) = \sum_{k=1}^{\infty} \prod_{i=0}^{k-1} b(i) + d(i) = \sum_{k=1}^{\infty} \frac{1}{(1 + \beta)^k} = \frac{1}{\beta}. \quad (4.2)$$

The asymptotic fitness distribution is

$$p_k = \frac{c}{\lambda^* + (1 + \beta)(k + 1)} \prod_{i=0}^{k-1} \frac{i + 1}{\lambda^* + (1 + \beta)(i + 1)}$$

$$= \frac{c'}{\Gamma(k + 1)} \frac{1}{(1 + \beta)^k}$$

$$\sim k^{-(2+\lambda^*/(1+\beta))} \frac{1}{(1 + \beta)^k}.$$

A mechanism where the vertices die at a rate proportional to their fitness therefore destroys the power-law distribution obtained without vertex deaths regardless of how small the proportionality constant is, and instead produces a (super)exponentially decaying fitness distribution.

We note that \(b(i) = (i + 1)^\gamma\) and \(d(i) = \beta(i + 1)^\eta\) give rise to the same exponential decay for any \(\gamma > 0\). Indeed,

$$p_k = \frac{1}{\lambda^* + (1 + \beta)(k + 1)^\gamma} \prod_{i=0}^{k-1} \frac{(i + 1)^\gamma}{\lambda^* + (1 + \beta)(i + 1)^\gamma}$$

$$\sim \frac{1}{(1 + \beta)^k} \exp\left(-\sum_{i=0}^{k-1} \log\left(1 + \frac{\lambda^*}{(1 + \beta)(i + 1)^\gamma}\right)\right),$$

where the sum in the exponent grows like \(k^{1-\gamma}\) for \(\gamma < 1\) and is convergent for \(\gamma > 1\).

**Example 4.3.** Next take \(b(i) = i + 1\) and \(d(i) = \beta(i + 1)^\eta\) for \(\beta < 1\) and \(\eta \in (0, 1)\). Also, in this case \(\hat{\rho}(\lambda) < \infty\) for all \(\lambda\) and, by comparison with the previous example, \(\beta < 1\) guarantees that the process is supercritical. For the fitness distribution, we obtain

$$\log p_k \sim -\sum_{i=0}^{k} \log\left(1 + \frac{\lambda^* + \beta(i + 1)^\eta}{i + 1}\right) \sim -k^\eta.$$ 

Vertex deaths determined by a sublinear function of the fitness therefore also destroy the power-law distribution obtained without vertex death, bringing it down to a stretched exponential distribution. In contrast to the case when the vertices die at random however, the tail behaviour of the distribution is changed by the vertex deaths.

Again, we note that \(b(i) = (i + 1)^\gamma\) and \(d(i) = \beta(i + 1)^\eta\) for arbitrary \(\gamma > \eta > 0\) with \(\gamma - \eta \in (0, 1)\) give rise to the same type of fitness distribution: a similar derivation as above implies that \(\log p_k \sim -k^{1-(\gamma-\eta)}\).

**Example 4.4.** Finally, consider a situation with \(b(i) = \alpha\) and \(d(i) = (i + 1)^{-1}\), that is, new vertices attach randomly to existing vertices and vertex deaths occur inversely proportional to
the fitness. Analogously to (4.2) we obtain
\[
E[\xi(\infty)] = \Gamma \left( 1 + \frac{1}{\alpha} \right) \sum_{k=1}^{\infty} \frac{\Gamma(k+1)}{\Gamma(k+1/\alpha)},
\]
and, using (4.1), it follows that
\[
E[\xi(\infty)] = \begin{cases} 
\infty & \text{if } \alpha \geq 1, \\
\frac{\alpha}{1-\alpha} & \text{otherwise}.
\end{cases}
\]
Hence, the process is supercritical if and only if \( \alpha > \frac{1}{2} \). The Laplace transform is
\[
\hat{\rho}(\lambda) = \sum_{i=0}^{\infty} \left( \frac{\alpha}{\lambda + \alpha} \right)^{k+1} \frac{\Gamma(k+2)}{\Gamma(k+2+1/\alpha)} = F\left(1, 1, 1 + \frac{1}{\lambda + \alpha}, \frac{\alpha}{\lambda + \alpha}\right) - 1,
\]
where again \( F \) is the hypergeometric function, and the equation \( \hat{\rho}(\lambda^*) = 1 \) is easily solved numerically for a given value of \( \alpha \). As for the fitness distribution, we have
\[
p_k = \frac{1}{\lambda^* + \alpha + 1/(k+1)} \prod_{i=0}^{k-1} \frac{\alpha}{\lambda^* + \alpha + 1/(k+1)} = \frac{1}{\alpha} \left( \frac{\alpha}{\lambda^* + \alpha} \right)^{k+1} \frac{\Gamma(k+2)}{\Gamma(k+2+1/\alpha)} \sim \left( \frac{\alpha}{\lambda^* + \alpha} \right)^{k-1/\alpha^*},
\]
that is, the fitness distribution decays (super)exponentially at rate \( \alpha/(\lambda^* + \alpha) \). The fact that vertices that are not successful in acquiring edges die at a higher rate is hence not sufficient in itself to explain the power-law distributions for the fitnesses.

5. The in-degrees

As mentioned in Section 1.1, the fitnesses (that is, the accumulated in-degrees) are often the primary object of interest when studying a network incorporating vertex death. However, there are also situations when the momentaneous in-degrees, henceforth referred to as just the in-degrees, are the relevant quantities. This is presumably the case for instance when modelling the World Wide Web. In this section we demonstrate how a formula for the asymptotic in-degree distribution follows from the same method as for the fitnesses and we present simulation results that show that the in-degree distribution behaves in a similar way to the fitness distribution.

Consider a vertex population that evolves in the same way as described above, with the difference that the birth and death rates are based on the in-degrees rather than the accumulated in-degrees. More specifically, a vertex that is alive at time \( t \) and has \( i \) alive children at time \( t \) gives birth to a new vertex at rate \( b(i) \) and dies at rate \( d(i) \). Let \( \xi \) be a random point process on \([0, \infty)\) with points (representing the births) generated according to these rules. We use the same
notation as before, equipped with a wave-hat for quantities related to $\tilde{\xi}$, omitting the original hat for the Laplace transform of the reproduction function. The Laplace transform is given by

$$\tilde{\rho}(\lambda) = \sum_{k=0}^{\infty} b(k) \int_{0}^{\infty} P(\tilde{\xi}(t) = k \cap \tilde{L} > t) \, dt,$$

(5.1)

and $\tilde{\lambda}^*$ is defined by $\tilde{\rho}(\tilde{\lambda}^*) = 1$. Furthermore, if $b(i)$ and $d(i)$ satisfy the analogues of (C1) and (C2), it follows from Theorem 2.1 that

$$\lim_{t \to \infty} \frac{Z_k^t}{Z_t} = \frac{\int_{0}^{\infty} e^{\tilde{\lambda}^*t} P(\tilde{\xi}(t) = k \cap \tilde{L} > t) \, dt}{\int_{0}^{\infty} P(\tilde{L} > t) \, dt},$$

(5.2)

that is, the fraction of vertices with in-degree $k$ converges almost surely and the limit is given by the right-hand side of (5.2). Unfortunately, it does not seem possible to derive a more explicit expression for the limit in this case. The event that a vertex of age $t$ has $k$ alive children occurs if the vertex has given birth to $n$ children for some $n \geq k$ and $n - k$ of these children have died before the vertex has reached the age $t$. To find an expression for the probability of this event that leads to a tractable formula for the integral in (5.1) and the numerator of (5.2) does not seem possible.

To get a grip of the asymptotic in-degree distribution, we turn to simulations. These indicate that the qualitative behaviour of the in-degrees is the same as for the fitnesses. Figure 1 shows simulated in-degrees and fitnesses plotted on a log–log scale for $b(i) = i + 1$ and $d(i) = 0.5$. In Example 4.1 it was shown that the asymptotic fitnesses in this case follow a power-law distribution with exponent 3, and Figure 1 reveals that the in-degrees seem to follow the same type of distribution, although the exponent appears to be slightly larger. Figure 2 shows simulated in-degrees and fitnesses for $b(i) = i + 1$ and $d(i) = 0.5(i + 1)$, with a log scale on the $y$-axis. The asymptotic fitness distribution was shown in Example 4.2 to have an exponentially decaying tail in this case, and the same seems to be true for the in-degrees. Finally, Figure 3 shows simulated in-degrees and fitnesses on a log–log scale for $b(i) = i + 1$.

Figure 1: Simulation with $b(i) = i + 1$ and $d(i) = 0.5$. The figure shows the tail probabilities of the fitness distribution (stars) and the in-degree distribution (circles).
Figure 2: Simulation with $b(i) = i + 1$ and $d(i) = 0.5(i + 1)$. The figure shows the tail probabilities of the fitness distribution (stars) and the in-degree distribution (circles).

Figure 3: Simulation with $b(i) = i + 1$ and $d(i) = 0.5(i + 1)$. The figure shows the tail probabilities of the fitness distribution (stars) and the in-degree distribution (circles).

and $d(i) = 0.5(i + 1)^{0.5}$. The plot reveals a slightly curved behaviour for both the in-degrees and the fitnesses which is significant for a stretched exponential distribution and in agreement with the analytical result for the fitness distribution. Note that, in all three cases, the tail of the in-degree distribution seems to decay faster than the tail of the fitness distribution. All simulations have been run until the number of alive vertices equals 100,000.

6. Further work

There are a number of questions about the studied model that deserve further investigation. What about the global properties of the obtained structure for instance? If the ghost links are included we get a random tree, analyzed in [19], and excluding the ghost links gives rise to a forest. Will there be an infinite component in this forest? How does the answer depend on $b(i)$
and $d(i)$? Another issue to look into is the time evolution of the process. For models without vertex death, it is known that the maximal degree grows polynomially with the same order as the first vertex; see [16]. Is this the case also in the current setting for the maximal fitness? Recently, Dereich and Mörters [10] have shown for a model with attachment function $k^\gamma$ and no vertex death that there is a phase transition at $\gamma = \frac{1}{2}$: if $\gamma > \frac{1}{2}$, there is a persistent hub that will be of maximal degree at all but at most finitely many times, while, if $\gamma < \frac{1}{2}$, there is no persistent hub. Is there a similar phenomenon in a model with vertex death?

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